# NASTRAN STATIC AND BUCKLING ANALYSIS COMPARISON WITH OTHER LARGE-CAPACITY PROGRAMS 

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SUMMARY

A square plate with clamped edges under a concentrated load was modeled using NASTRAN (refeience 1) and ASKA (reference 2) finite element computer prograns. Deflections were computed for various width-to-thickness ratios (b/t) of the plate element, and were compared against the classical theory to determine the $\mathrm{b} / \mathrm{t}$ limitations.

A cylinder with simply supported ends was modeled using NASTRAN and STAGS (reference 3) computer programs for buckling analysis. The models :vere subjected to a uniform radial pressure loading. Several parameters were changed, and the effects of those variations are presented. Utilizing thes data, a model which will produce results comparable to pubiisheu empirical data can be constructed and processed for a minimized cost.

## STATIC ANALYSIS

The user of finite element computer programs has numerous limitations to be considered when constructing a mathematical model of the structure to be analyzed. Although considerable information is available concerning the plate element aspect ratio ( $\mathrm{a} / \mathrm{b}$ ) (i.e., length-to-width ratio), the effect of varying the width-to-thickness ratio ( $b / t$ ) has not previously been presented. The effect of varying the plate element $b / t$ ratio was investigated for the NASTRAN and ASKA finite element computcr prograns.

This investigation utilized a square plate with clamped edges. Two elements, CTRIA2 and CQUAD2, available in NASTRAN, were used in two separate models. One tritugle-plate element, TRIB3, available in ASKA, was used in the third model. These models, shown in Figure 1, were 152.4 cm ( 60 inches) square plates with varied thickness to achieve the b/t ratio desired. The
basic model mesh size was selected based upon previous experience. One model with mesh size reduced by a factor of 2 was processed, and the results were compared to verify that the basic model mesh size was valid.

One loading, which consisted of a concencrated load applied in the geometric center normal to the plate, was selected due to its ideal checks for the bending characteristics of any plate element. This loading was applied to each model processed.

The results of the two NASTRAN models and the ASKA model are surmarized in table I. The resulting computed deflections for the three models are tabulated for the various $\mathrm{b} / \mathrm{t}$ ratios investigated. Inciuded in this table are the theoretical deflections based upon classical equations (reference 4). These deflection data are presented graphically in figures 2 through 4 . The plot of the percentage difference between conputed deflection and theoretical deflection is shown in figure 5 for the three models investigated. The two NASTRN plate elements, CTRIA2 and CQUAD2, break down in regions of b/t less than five. The ASKA element, TRIB3, is quite consistent, even for extremely low values of b/t. It is apparent that a limitation on the value of $b / t$ exists for the NASTRAN plate elements. This limitation should be considered along with the aspect ratio (a/b) limitations when constructing a model for the NASTRAN computer program.

## BUCKIING ANALYSIS

Buckling analysis is an eigenvalue problem which may result in very high computer processing costs to achieve a valid solution. This report presents an investigation into the various modeling parameters that affect the solution and the computer cost. The results of this study reveal an approach to achieving a valid solution for minimized computer cost.

This investigation considered a cylinder under uniform radial pressure loading. According to Donnell's equation, under uniform radial pressure, the buckling stress of the cylinder is:

$$
\sigma_{c r}=\frac{K_{y^{2}}^{2} E}{12\left(1-\nu^{2}\right)}\left(\frac{t}{L}\right)^{2}
$$

For moderately long cylinders, this equation gives quite good correlation with test data (reference 5). For this investigation, a data point was selected where the test result and the preceding equation value practically coincide. This cylinder model is shown in figure 6. The cylinder was moleled for

NASTRAN, a finite element computer program, and for STAGS, a finite difforence computer program. Essentinlly, the same parameters were varied for both models in determining effects upon the solution validity and the computer costs.

The results of the NASTRAN and STAGS models are presented in tables 11 and III, respectively. These data are presented in figures 7 through 9. Appendix A contains the mode shapes for all the models studiod in this investigation.

A significant parameter in modeling for either NASIRNN or STAGS is the circumferential spacing of grid points which determine the number of elements per half wave-length. As indicated in figure 7, an extremely narrow range of circumferential spacing may be considered in modeling in order for NASTPAN buckling analysis to achieve valid results. The NASTRAN model that is very fine is equally as erroneous as a model that is very coarse. These models that are outside this narrow band of acceptable circumferential spacing produced results that deviated from the theoretical value by up to 70 percent. The improper selection of the circumferential spacing for the STAGS program can result in extremely high errors, over 3,000 percent, as shown in figure 7. The results from the STAGS models indicate that the error percentage is directly related to the coarseness of the model, and as the circumferential spacing is reduced, the computed value approaches the theoretical solution. For this particular cylinder model to achieve a valid solution, the STAGS model required a 3 -degree circumferential spacing, whereas the NASTRAN model required a 10 -degree spacing.

The aspect ratio of the plate elements was considered as an important parameter in this irvestigation. Although most of the models utilized a constant number of uniformly spaced longitudinal cuts, a few were processed using nonuniformly spaced longitudinal cuts to determine the effects of varying the aspect ratio. It was a surprise to learn that the results did not change appreciably. Apparently the aspect ratio of the plate elements is not a critical parameter for NASTRAN buckling analysis. The data presented in figure 8 for extremely low and extremely high aspect ratios are related to the very coarse and the very fine circumferential spacing models, respectively. Therefore, the most probable reason for the results is due to the circumferential spacing.

The NASTRAN models were prccessed on IBM 370/165, and the STAGS models were processed on CDC 660 n computer system. The resulting machine time data are presented in tables iV and V. This information is converted to machine cost in dollars and presented in figure 9. Even the very fine model used in STAGS to achieve a valid solution resulted in less computer cost than any of the NASTRAN models processed. This may be partly attributed to the two computer systems used in the investigation. Aithough figure 9 presents the computer cost, a significant part of the total cost for buckling analysis is the man-hours required to construct the model and prepare the data. Also, the

NASTRAN program provides a lot more flexibility in modeling as compared to the STAGS program. The total cost data for this investigation are not available, but it is estimated that for a typical problem, the total cost would be nearly equal for these two prograns.

Cumallisions

In the static analysis investigation, it was determined that the NASTRAN plate element has a width-to-thickness ratio (b/t) limitation, as well as an aspect ratio limitacion. These are both important paraneters to be considered in modeling thick plate stmuctures. Extra care should be excrcised to avoid large aspect ratios and/or small (less than five) width-to-thickness ratios. The investigation did indicate that ASKA element TRIB3 is consistently valid for extremely luw :alues of $\mathrm{b} / \mathrm{t}$. For those structures whose configuration requires modeling to b/t values less than five, it is recommended that they get processed using the ASKA program or use solid elements available in NASTRAN.

The buckling analysis investigation revealed that modeling requirements are quite different from static analysis. The conventional rules for static analysis modeling are neither sufficient nor applicable for buckling analysis. Although the effect of varying aspect ratio is negligible, the effect of varying the number of clements per hain wavelength is very critical to both a valid solution and the computer cost. The cost of performing a valid buckling analysis is very high measured by static analysis standards. Although STAGS computer cost is quite $10 w$, the man-hour cost is quite high, compared to NASTRAV costs. The evaluation of the buckling analysis performed in this investigation has revealed that it is very difficult to separate a reasonable solution from an erroneous solution. The NASTRAN models indicate an extremely narrow band of circumferential spacing (number of elements per half wavelength) may be selected for a valid solution, whereas the STAGS models indicate the finer models produced an acceptable solution.

## ACNNOWLEDGEMENT

The author expresses his gratitude to Mr. W. D. Mock and Mr. Y. N. Tsou for the assistance in carrying out this work.

SYMBOLS
$\theta$
l Length of vlinder element
a Length of plate
b Width of plate
$t \quad$ Thıckness of plate or cylinder
$\mathrm{R} \quad$ Cylinder radius
$\mathrm{P}_{\mathrm{cr}} \quad$ Critical buckling load - program output
P Critical buckling load - theoretical value
$\sigma_{\mathrm{cr}} \quad$ Critical buckling stress - theoretical value

## REFERENCES

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Table I
STATIC ANALYSIS - DEFLECTION DATA

| Plate Thickness $t$ (cm) | b/t | NASTRAN CQuAD2 | NAËRAN CTRIA2 | $\begin{aligned} & \text { ASKA } \\ & \text { TRIB3 } \end{aligned}$ | $\begin{aligned} & \text { Theoretical } \\ & \text { (Ref 4) } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1.27 | 20.0 | $15.06 \times 10^{-1}$ | $13.64 \times 10^{-1}$ | $13.39 \times 10^{-1}$ | $14.91 \times 10^{-1}$ |
| 5.08 | 5.0 | $24.0 \times 10^{-3}$ | $22.07 \times 10^{-3}$ | $20.9 \times 10^{-3}$ | $23.37 \times 10^{-3}$ |
| 10.16 | 2.5 | $3.2 \times 10^{-3}$ | $2.97 \times 10^{-3}$ | $2.62 \times 10^{-3}$ | $2.92 \times 10^{-3}$ |
| 15.24 | 1.67 | $10.39 \times 10^{-4}$ | $9.73 \times 10^{-4}$. | $7.82 \times 10^{-4}$ | $8.61 \times 10^{-4}$ |
| 20.32 | 1.25 | $4.93 \times 10^{-4}$ | $4.65 \times 10^{-4}$ | NA | $3.63 \times 10^{-4}$ |
| 25.4 | 1.00 | $2.87 \times 10^{-4}$ | $2.72 \times 10^{-4}$ | $16.74 \times 10^{-5}$ | $18.54 \times 10^{-5}$ |

Table II
BUCKLING ANALYSIS - EIGENVALUE DATA NASTRAN MODEL

| Shell | Mesh Size |  | $\mathrm{P}_{\mathrm{cr}} / \mathrm{P}$ | legree of Freedom* |
| :---: | :---: | :---: | :---: | :---: |
|  | $\theta$, deg | $f, \mathrm{~cm}$ |  |  |
| 90 | 2 | 25.4 | 1.6434 | $\mathrm{T}_{1}$ |
| 90 | 5 | 25.4 | 1.5409 | T 1 |
| 90 | 9 | 25.4 | 1.3614 | $\mathrm{R}_{2}$ |
| 90 | 10 | 2!.4 | 1.0390 | $\mathrm{R}_{2}$ |
| 90 | 11 | 25.4 | . 7844 | $\mathrm{R}_{2}$ |
| 180 | 20 | 25.4 | . 5568 | $\mathrm{R}_{3}$ |
| 180 | 30 | 25.4 | . 3079 | $\mathrm{R}_{3}$ |

*Eirenvectoi's are nomalized with respect to this degree of freedom.

Table III
BUCKLING ANALYSIS - EICLANNUL IATA SIACS MOMAL

| Shell | Mesh Size |  | $\mathrm{P}_{\mathrm{cr}} / \mathbf{P}$ | legrec of Ireedom* |
| :---: | :---: | :---: | :---: | :---: |
|  | $\theta$, deg | $\bar{l}, \mathrm{~cm}$ |  |  |
| 90 | 3.1 | 4.24 | 1.08 | $\mathrm{I}_{1}$ |
| 90 | 3.1 | 9.53 | 1.09 | '1 |
| 90 | 3.1 | 19.05 | 1.11 | '1 |
| 90 | 3.1 | 38.1 | . 37 | $\mathrm{i}_{1}$ |
| 90 | 5.3 | 4.24 | 1.27 | $\mathrm{r}_{1}$ |
| 90 | 11.25 | 12.7 | 2.78 | r 1 |
| 90 | 22.5 | 12.7 | 29.9 | $\mathrm{T}_{1}$ |

*Eigenvectors are normalized with respect to this degree of freedom.

Table IV
BUCKLING AVALYSIS - MACIINE TIME DATA NASIRAV MDIHEL IBM 370/165

| Number of <br> Grid Points | CPU Time <br> $(\mathrm{sec})$ | Channel Time <br> $(\mathrm{sec})$ | Billing Units |
| :---: | :---: | :---: | :---: |
| 184 | 222.432 | 114.732 | 28.9015 |
| 76 | 80.208 | 93.438 | 12.9700 |
| 44 | 57.732 | 91.212 | 10.4555 |
| 40 | 63.23 | 10272 | 12.1796 |
| 40 | 54.63 | 93.75 | 10.8100 |
| 36 | 58.398 | 104.118 | 11.5798 |
| 28 | 43.662 | 95.358 | 9.6276 |

Table V
BUCXLING ANALYSIS - MACHINE TINE DATA STAGS MODEL CIC 6600

| Number of <br> Grid Points | CPU Time <br> (sec) | T/O Time <br> (sec) | System Sec |
| :---: | :---: | :---: | :---: |
| 300 | 46.228 | 105.800 | 72.678 |
| 180 | 18.469 | 40.9 | 28.694 |
| 150 | 19.176 | 48.626 | 31.332 |
| 90 | 11.312 | 33.816 | 19.766 |
| 60 | 7.858 | 30.624 | 15.514 |
| 36 | 3.227 | 21.162 | 8.517 |
| 20 | 2.036 | 23.259 | 7.85 |



Figure 1. Static analysis - basic model geometry.


Figure 2. Deflection vs thickness ratio, NASTRAN - CQind 2.


Figure 3. Deflection vs thickness ratio, NASTRAN - CTRIA2.


Figure 4. Deflection vs thickness ratio, ASKA - TRIB3.


Figure 5. \% difference vs thickness ratio.


Figure 6. Buckling analysis - basic model geometry.


Figure 7. Effect of varying circumferential spacing.


Figure 8. Effect of varying aspect rativ.


Figure 9. Cost comparison between NASTRAN and STACS.


Figure A-1. Mode shape - NASTRAN mode1.

$$
\mathrm{P}_{\mathrm{cr}} / \mathrm{P}=1.5409 ; \ell=25.4 \mathrm{~cm} ; \theta=5^{\circ}
$$



Figure A-2. Mode shape - NASTRAN midel.

$$
\mathrm{P}_{\mathrm{cr}} / \mathrm{P}=1.3614 ; \ell=25.4 \mathrm{~cm} ; \theta=9^{\circ}
$$



Figure A-3. Mode shape - NASTRAN model.
$\mathrm{P}_{\mathrm{cr}} / \mathrm{P}=1.039 ; \ell=25.4 \mathrm{~cm} ; \theta=10^{\circ}$


Figure A-4. Mode shape - NASTRAN model.

$$
\mathrm{P}_{\mathrm{cr}} / \mathrm{P}=0.7844 ; \ell=25.4 \mathrm{~cm} ; \theta=11^{\circ}
$$



Figure A-5. Mode shape - NASTRAN model.

$$
\mathrm{P}_{\mathrm{cr}} / \mathrm{F}=0.5568 ; \ell=25.4 \mathrm{~cm} ; \theta=20^{\circ}
$$



Figure A-6. Mode shape - NASTRAN mode1.

$$
\mathrm{P}_{\mathrm{cr}} / \mathrm{P}=0.3079 ; \ell=25.4 \mathrm{~cm} ; \theta=30^{\circ}
$$


\& igure A-7. Mode shape - NASTRAN mode1.

$$
\mathrm{P}_{\mathrm{cr}} / \mathrm{P}=1.08 ; \ell=4.24 \mathrm{~cm} ; \theta=3.1^{\circ}
$$



Figure A-8. Mode shape - STAGS model.

$$
\mathrm{P}_{\mathrm{cr}} / \mathrm{P}=1.09 ; \ell=9.53 \mathrm{~cm} ; \theta=3.1^{\circ}
$$



Figure A-9. Mode shape - STAGS model.

$$
\mathrm{P}_{\mathrm{Cr}} / \mathrm{P}=1.11 ; \ell=19.05 \mathrm{~cm} ; \theta=3.1^{\circ}
$$



Figure A-10. Mode shape - STAGS model.

$$
\mathrm{P}_{\mathrm{cr}^{\prime}} / \mathrm{P}=0.37 ; \ell=38.1 \mathrm{~cm} ; \theta=3.1^{\circ}
$$



Figure A-11. Mode shape - STAGS model.

$$
\mathrm{P}_{\mathrm{cr}} / \mathrm{P}=1.27 ; \ell=4.24 \mathrm{~cm} ; \theta=5.3^{\circ}
$$



Figure A-12. Mode shape - STAGS model.

$$
\mathrm{P}_{\mathrm{cr}} / \mathrm{P}=2.78 ; \ell=12.7 \mathrm{~cm} ; \theta=11.25^{\circ}
$$



Figure A-13. Mode shape - STAGS model.

$$
\mathrm{P}_{\mathrm{cr}} / \mathrm{P}=29.9 ; \ell=12.7 \mathrm{~cm} ; \theta=22.5^{\circ}
$$



Figure A-i4. Mode shape - STACS model.

