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(NASA-CR-146805) POSTFLIGHT ANALYSIS FOR	N76-21262 F
DELTA PROGRAM MISSION NO. 113: COS-B	
MISSION (McDonnell-Douglas Astronautics Co.)	
213 p HC \$7.75 CSCL 22C	Unclas
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POST FLIGHT ANALYSES FOR DELTA PROGRAM MISSION NO. 113 - COS-B MISSION CONTRACT NAS7-832 •





A3-262-AMOO-M75-509 Date: FEB 2 0 1976

MEMORANDUM

Subject: POSTFLIGHT ANALYSES FOR DELTA PROGRAM MISSION NO. 113 - COS-B MISSION - CONTRACT NAS7-832*

To: E. W. Bonnett, A3-900

Copies to: C. H. Baumann, F. M. Keller, D. W. Knebel, J. R. Reider, J. C. Simmons, D. W. Tutwiler, F. B. VanShoubrouek, A3-200; F. J. Maguire, A3-G83; T. B. Rehder, J. L. Schmidt, A31-822; M. D. Steffey, A41-770; D. R. Cummings, A41-792; D. A. Maclean, A41-822; File

From: C. A. Ordahl, A3-262

1. This memorandum has been prepared in accordance with COM 15 of the subject contract.

2. On 8 August 1975, the COS-B spacecraft was launched successfully from the Western Test Range (Delta Program Mission No. 113). The launch vehicle was a three-stage Extended Long Tank Delta DSV-3P-11B vehicle, Serial No. 20018.

3. Postflight analyses performed in connection with Delta Program Mission No. 113 (COS-B Mission) are presented in the attachments to this memorandum (Attachments 1 through 10). These attachments consist of the following:

Attachment <u>Number</u>		Title	Pages
l	Section 1.	System Performance - COS-B Mission	1-1 through 1-26
2	Section 2.	Propulsion Systems - COS-B Mission	2-1 through 2-28
3	Section 3.	Guidance System - COS-B Mission	3-1 through 3-15
4	Section 4.	Flight Control System - COS-B Mission	4-1 through 4-29
5	Section 5.	Electronics System - COS-B Mission	5-1 through 5-11
6	Section 6.	Mechanical Systems - COS-B Mission	6-1 through 6-10

0. 3360-1114; EWO 54173; COM 15

TRACTUAL DOCUMENT

E. W. Bonnett, A3-900

-2-

Attachment Number	Title	Pages
7	Section 7. Structural Systems - COS-B Mission	7-1 through 7-6
8	Section 8. Reliability	8-1 through 8-2
9	Definitions of Performance Parameters [Tables 2-3 and 2-4 of Attachment 2 (Section 2)]	9-1 through 9-2
10	Vehicle Performance Telemetry Plots - COS-B Mission	10-1 through 10-73

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C. A. Ordahl Chief Engineer Delta Programs Engineering Division

FMW:lsm

Attachments: As Noted

Attachment 1 to: A3-262-AM00-M75-509

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ATTACHMENT 1:

SECTION 1. SYSTEM PERFORMANCE - COS-B MISSION

INTRODUCTION AND SUMMARY

Delta Mission Number 113, COS-B, was launched from Pad SLC-2W of the Western Test Range (WTR) at a flight azimuth of 196 degrees from true north at 0147:59.595 Greenwhich Mean Time (GMT) on August 8, 1975.

This section provides a discussion of the mission analysis aspects of the COS-B spacecraft launch and a description of the trajectory flown by the Delta vehicle from liftoff to third-stage burnout; data pertaining to the experimental second stage restart are included. This section also presents a comparison between (1) the actual trajectory flown by the vehicle, (2) the guided nominal trajectory (Reference 1), and (3) the latest predicted or Best Estimate Trajectory with launch-day winds and atmosphere (BET-with-winds). The actual trajectory flown by the first and second stage is based on Federal Electric Corporation (FEC) radar tracking data and NASA-provided hardpoint position and velocity vectors (Reference (2). PCM telemetry data was utilized to support the determination of trajectory data at the time points specified in the subsections to follow. The following table compares the achieved orbit at spacecraft injection (TECO) to the nominal orbit given in the Orbit Accuracy Incentive TWX (Reference 3). Incentive flight requirements may be seen to have been met; that is, all fall within allowable tolerances.

Parameter	Nominal (Reference 3)	<u>Achieved</u>	Achieved Minus <u>Nominal</u>	Incentive Tolerance
Apogee Altitude (n.mi.)* (Integrated)	53,992	; 54 , 433	+442	+2115
Perigee Altitude (n.mi.)*	188.19	187.17	-1.02	-10.0
Inclination (deg)	90.000	90.155	+0.155	+0.82

Table 1 summarizes the orbit parameters of all Delta missions to date and, where applicable, includes the corresponding three-sigma deviations. Table 2 presents the guided nominal, BET-with-winds, and actual sequence of events for the COS-B mission.

VEHICLE DESCRIPTION

The launch vehicle used for the COS-B mission consists of a DSV-3P-LA Extended Long Tank Booster No. 602 (Serial No. 20020) powered by a Rocketdyne RS-27 liquid propellant engine and nine strap-on Thickol TX-354-5 (Castor II) solid propellant rockets with low-drag nose cones. The second stage is a DSV-3P-4B (Serial No. 20023) having a TRW engine (light quartz nozzle with Expansion Ratio = 43:1) with restart capability and a DSV-3P-7A fairing (Serial No. 20023). The third stage consists of a TE-364-3 engine (Serial No. 00025).

METEOROLOGICAL CONDITIONS

Figures 1, 2, and 3 present the launch day temperature, pressure, and wind speed and direction from ground level to 100,000 feet measured at WTR at the time of launch. Figure 1 shows the atmospheric temperature was hotter than the reference temperature until approximately 42,000 feet, colder between 42,000 feet and 70,000 feet and hotter above 70,000 feet. The atmospheric pressure (Figure 2) is generally higher than the reference atmosphere. Figure 3 indicates that the wind speed was significantly lower than the 90 percent IRIG wind reference until approximately 65,000 feet and increasingly higher above 65,000 feet. The maximum wind speed was 49 knots at 100,000 feet. The wind direction changed from a north-westerly direction to an easterly direction with increasing altitude.

PERFORMANCE ANALYSIS

First and second stage performance up to second stage cutoff (SECO) is based on the radar tracking data and NASA SECO hardpoint. PCM telemetry data was utilized to determine the vehicle velocity at second stage burnout. Reconstruction of the third stage is based on the SECO I PCM data and NASA hardpoint data at third stage burnout.

FIRST STACE PERFORMANCE

An analysis of pertinent data indicates that the first-stage flight was near nominal with respect to the vehicle's instantaneous impact point (IIP) and present position traces, which remained well within the three-sigma boundaries. Table 3 presents comparison of the guided nominal, BET-with-winds, and actual trajectory at significant times. The actual inertial velocity at MECO may be seen to be 2.1 ft/sec higher than the guided nominal and 59 ft/sec lower than the BET-with-winds.

SECOND STAGE PERFORMANCE

Table 4 presents trajectory comparisons of second stage performance parameters at significant event times during the first burn period of the second stage. Actual SECO I was determined from PCM telemetry data.

Figure 4 compares the tag second stage thrust history with the actual reconstructed thrust based on DIGS acceleration data, flowmeter weight-flow data (Reference 4), weights (Reference 5), and actual event times (Reference 6). The reconstructed thrust curve is higher than the tag an average of 48 pounds over the first burn. The higher than tag thrust level resulted in a 1.5 second shorter burn while the low (-71 ft/sec) velocity at ignition results in a 1.4 second longer burn, thus the first burn of the second stage was within 0.1 seconds of nominal.

THIRD STAGE PERFORMANCE

PCM position and velocity vectors at SECO were used in the following manner to reconstruct third stage performance. An MDAC-W predicted orbit was generated utilizing a PCM position and velocity vector at second stage burnout, vehicle attitude as defined in the BET-with-winds, actual third stage ignition time, and the latest predicted third stage performance and burn time. A reconstructed orbit was then generated using the same initial PCM position and velocity vectors and coast time as those for the predicted orbit in order to determine the third stage performance parameters required to match the NASA orbit parameters at a time after third stage burnout. The following table presents a summary of third stage predicted and reconstructed performance.

Parameter	Unit	Predicted Value	Reconstructed Value
Effective Specific Impulse	sec	287.93 <u>+</u> 1.10 3σ	288.39
Total Impulse	lb-sec	417678.9	418338.82
Impulsive Velocity	fț/sec	9497.10	<i>93</i> 12.09
Vehicle Attitude Error; Pitch Component, Nose-Up Positive	deg	0 <u>+</u> 3.90 30	0.699
Vehicle Attitude Error; Yaw Component, Nose Right Positive	deg	0 <u>+</u> 3.90 3σ	0.649

Table 5 presents comparison of the MDAC-W predicted, BET-with-winds, and reconstructed third-stage trajectory parameters at third stage ignition and burnout.

POSTFLIGHT STATISTICS

Statistical information for pertinent performance and trajectory parameters are presented in Tables 6 and 7. Table 6 provides data as compared to nominal predictions, while Table 7 compares to tag (BET) predictions.

REFERENCES

- Memorandum A3-200-AAC3-M-75-417, "Guided Nominal Trajectory for the COS-B Spacecraft Mission," dated 18 July 1975.
- NASA Memorandum, "Tracking Data for COS-B Mission (Delta 113)," dated 11 September 1975.

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- TWX A3-130-Delta/AAC3-750137, "Orbit Accuracy Incentive Criteria for the COS-B Spacecraft Mission - Contract NAS7-832," dated 11 July 1975.
- Memorandum A3-226-AD03-75293, "Propulsion Postflight Reconstruction for COS-B Delta Mission No. 113, Second Stage, DSV-3P-4B (Light Quartz), S/N 20020," dated 29 September 1975.
- 5. Memorandum A3-224-ABE2-75-169, "COS-B (Configuration 2913) -Final Postflight Weight Summary," dated 2 October 1975.

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6. AVI A3-230-AEF0-AVI-75-234, "COS-B Sequence of Events," dated 7 October 1975.

TABLE 1-1 COMPARISON OF ORBIT PARAMETERS

FAGE I	'
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MISSION *	LAUNCH NUMBER	LAUNCH DATE	CONF		NOMI		ECC	ACTURL APOGEE	DELTA APXGE	30	RCTURE	DELTA PERKEE	30	ACTURE	DELTA	30- 41	ACTURE ECC	DELTA ECC	30 10	CONTINIENTS
ECHO I	Noniben			APOGEE				ArtGee	APLOCE	<u>a.a</u>	FERRICE	-carisee	<u>Ahp</u>	INGUN	IACON	<u> </u>			26	COAST PHASE ATTICUDE FALLURE
نى جەم <u>مەم يىرى بىرى مەم مەم مەم مەم مەم مەم مەم مەم مەم مە</u>		5-13-60		900	_900	48.0	00					60	[47.2			0.0.02			THE STREE DID NOT LUNITE
ECHO IA	2	8-12-60		900	900	47/	0.0	907	7	110	818	82	110		0.1	0.5	00103	0.0103		SUCCESS
TIROS AZ	3	11-23-60	· · · · · · · · · · · · · · · · · · ·	.330	330	483	00	395	15	86	334	46	86	485	0.2	0.5	0.0080	0 0000	t	BUCCESS
P.14	4	3-25-61	DM.R	120000	94	330	0 9442	128611	8611	6500	90	4	2	329	0.1	0.3	09479	0.0037	0020	SUCCESS
	5	7-12-61	DM 19	390	380	48 3	00	-42	62	81	398	18	81	479	0.4	0.5	0.0067	0 0057	0 0153	SUCCESS
<u> </u>	6	8-15-61	1	47000	160	330	0 8666	41762	5238	9252	159	<u> </u>	2	330		06	0 8524	0 0142	0 0204	SUCCESS
	7	2.8.62	DM-19	- 330	380	48 5	00	462	82	82	389	9	81	483		05	0.0094	0 0094	00153	SUCCESS
5-16	8	3-7-62		300	_300	329	00	322	22	53	299	<u> </u>	53	389	0	05	0.0030	0 00 30	00112	SUCCESS
5-51	9	4-26 62	DM-19	550	200	550	0 0450	656	106	365	211		60_	53,9	1.1	1.5	0.0574	0.0116	00463	SUCCESS
TIROS E	10	6-19-62	DM-19	350	350	584	00	585	175	76	319	31	76	581	0.3	05	0 0266	0 0266	0 0146	PDS (BTL FAILURE)
<u></u>	"	1-10-62	DM-19	3000	600	450	0 2401	3042	42	321	512	12	23	44 B	0.2	1.1	0.2424	0 0017	0 0232	SUCCESS
TIRDS F	12	9-18-62	DM-19	350	350	594	00	384	- 34	76	370	20	76_	583	0.1	05	0.0019	0 0019	0,1460	SUCCESS
<u>5.3</u> A	13	10-8-68	C51-3A	47000	160	330	0 8667	53204	6204	8000	152	8	28	330	0	16	0 8306	00137	0.0201	SUCCESS
<u> </u>	14	10 27-62	05√. <u>3</u> A	9000	150	178	05519	9520	520		170	20	<u> </u>	180	0.2		0 5692	0 0123	i	SUCCESS' X. TAB ADT. 14
	15	12-13-62	051.38	4000	100	478	0 2343	4014	14	375	7/3	13	23	475	03	1.5	0 2048	0 0006	0 0259	SULCESS' SPIN AVENTS
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5.0	17	4-2-63	DSV 3B	485	135	578	0 0470	495	10	57	138	13	4	576	0.2	07	0.0479	0.0009	0 0070	SUCCESS
T5x-2	18	5-7-63	OSV 3B	5100	500	430	0 3938	5833	193	475	525	25	18	427	03		0.4007	0.0069	00202	5000655
TIRDS G	19	6-19-63	DSV 3₿	355	355	583	00	350	5	76	355	0	76	592	01	0.5	0.0020	0 0020	0 0130	500055
51.1.2011 7-20	20	1-26-63	DSV-38	2016	120	330	0 1363	19647	369	2925	118	2		33.1	01	0.8	0 7327	00036		SUCCESS
1.V. D A	21	11-26-63	DSV-3C	1,50000	105	330	09548	106718	43288	52570	103	2	9	33 3	03	1.9	0.9376	0 0172	0 0839	SUCCESS FIRST X- 155 41701
7 225 4	22	12-21-63	DSV-3B	;	370	586	0.0	407	37	84	378	8	84	58 5	01	0.5	0 0038	0 0038		
- E> -7-,0	23	1-21-64	D54-38	4200	1150	465	02366	4203	3	376	1120	22	77	463	0.2	1.5		0 0026		SVILESS
5-36	24	3-19-60	DSV-BE	617	642	707	0 0007				<u> </u>	†. <u> </u>		#					· · · · · · · · · · · · · · · · · · ·	DID NOT DE HIN AL J. T INJELTION LAST X-248 ASTOL
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1.10-3	26	10 3.64	·	<u> </u>	105	1330	09391	51114	58891	52590	102	3	9	1336	0.6	19	0.8780		00239	PARTIN. SPLESS. DID NOT ALLOW
5.30	27	12-21-64	DSV 3C	13782	174	200	0.6529	14148	366	6184	165	9	30	li 20 1	01	1:8	0 6595	0.0066	0.0954	SUCCESS
T.EOS I	20	1-22-65		400	400	984	00002	1392	992	103	379	21	103	964	20	0.8	0.1171	0 1169	00169	INATIAL SIGLASS BITL ANTEANA
050-B	29	2-3-65		300	300	32.9	00001	342	42	30	297	3	80	329	0	04	0.0059		<u> </u>	SUCCESS
CSN1547 *1	30	4-6-65		20155	175	185	0 6967	19705	450	4199	778	3	77	18.1	0.4	1.5	0.6915	0 0052	0.0443	<u> </u>
. VP.C	31		SIDSV-3C	3000	102	380		142681	22681	52590	105	3	9	339	09	19	09626	00029	0.0239	
	32	1.1.65	DSV 3C	432	130	986	0 0001	1	21	103	406	24	103	986	0	08	0'0061	1	·	SVEESS
	33	1			300	329		453	· / ·			- 	100	100	<u>⊢-≚</u>	<u>⊢</u> °-		0 0060	00182	SULCESS
GE05 A	+ • • •	8-25-6		801		1	00001	1237	131	123	601		<u> </u>	1000	0.4			1		SUCCESS POS (UT/MED NILLES)
PID SER A	34	11 6 6 2		5.984	0824	59.0	0 0203	0 900	436	143	0 814	0015	24	59 \$	1	05	00189	0 0456	00140	
	35	12-16-65		· #	a.u	0.147	0085	au		{	au	a.u.	1.00	0.176	0029		0.0940	0.0090	00182	SUCCESS
T.RJ5 07.3**	36	2.3-66	054.90	408	398		. <u>-</u>	457	.49	106	383	. 13	106	97.9	03	07	0 0093	0 0018	0 0143	5042635
T. 205 0T. 2***	37	2.28-44	05V-36	743	715	101.3	00034	768	25	142	735	20	142	101.0	0.3	2.7	0.0000	0 0006	00166	SUCCESS

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TABLE 1-1 (CONTINUED)

COMPARISON OF ORBIT PARAMETERS

TAUNCH LAUNCH ACTUAL DELTA 30 ACTUAL DELTA ACTUAL DELTA NOMINAL Sa 30 ACTUAL DELTA 3σ COMMENTS MISSION CONF APOGEE APOGEE Sha PERIGEE PERIGEE Anp INCUN INCLIN NUMBER OATE ECC. FCC. 1 e APOCHE PERIGEE INCLIN. ECC. 41 SULLESS FIRST FW. 4 MOTOR 1471 0 0873 0.0656 AE-8 146 640 00657 824 647 0.7 1.0 0 1550 38 5-25-14 051-30 650 302 156 n 16 SUCCESS ACTERNATE MISSION AIMP-D 28.8 0.9763 37 1-1-66 DSV-36 201.936 3600 468207 168371 0 9847 0 0084 3602 2 28.9 0.1 a u 1124 0,010 1.009 0002 PIONEER.B 40 8-17-66 OSV-3E 0 0099 0.05820 0.1037 0 0933 005379 00441 SUCCESS a u a u 105 WTP*/ 41 10-2-66 051.36 0.0076 0 0062 0 0145 767 156 101.2 00014 813 148 719 7 148 101.0 0.2 1.0 SUCCESS 46 INTELSAT I 0.3 12 10-26-66 DEV 35 86 7 07344 161 26.4 0.7 0.7377 0 0033 0 0083 2016 5 171 20436 211 714 10 53 SULLESS 8.25·A 43 1-14-66 DSV-30 170.8 169 4 33.5 00019 111.5 0.7 661 3.3 211 39.5 0.0 0 00074 0 0055 0 005 SULLESS INTELSAT # 1-11-67 05V-3E 20/65 171 SULLESS 44 267 07344 0 733/ 0 0013 0 0083 19958 201 714 160 11 53 26.2 05 07 45 .05 WIR' 2 1-26-67 DSV. BE 777.1 172.6 1016 785 12 148 718 59 149 102.0 0.4 0.0080 0 0075 SUCCESS 0.0005 10 C50-E1 3-8-67 05V.3C 46 3006 2993 3291 312 7 121 520 291 83 520 32.87 0.04 0 00 89 0 00 27 0.0081 SUCCESS 0002 0.39 TOS DATE 47 3-22-67 DSV-3E 20165 171 267 201887 10638 158 2 18.8 640 26.57 0.13 0 7344 237 0.94 0.7355 0.0011 0 0111 SULCESS 4-20-67 OSV-BE 777 4 773.8 113.5 101.9 0.4 48 101.5 1694 415 00000 .80 113.5 7323 10 0 00 44 0 00 40 SUCCESS 7050 IMP-F 49 5-84-47 OSV-3E 121908 141 66.49 29446 13854 8048 21827 130 17 181 6717 0.68 1.74 0.9:07 0 035 0 0100 SUCCESS 111 AINP.E 7-19-67 OSV 36 894076 355 325104 31030 2961 0.9772 SUCCESS 50 29.36 0.9748 348 7.3 025 0 0024 5:05-3 9-7-67 054.36 170 8 51 1694 33.50 0 002 175 6 4.8 SULCESS 25 1618 76 25 33 47 003 0 0017 0 005 10019 INFELSAT D 52 9-87-67 DSV.3E 20165 171 267 07344 20028 137 11637 162 90 63 1 26 44 0.26 1025 0 7336 00008 0 0168 50CCE 55 050-D 53 10-18-67 05V-3C 305.4 299 3 34 J 3291 0 0002 3/15 61 2959 34 343 33.00 0.09 SUCCESS 0.34 0.0021 0 0019 2 0080 105.C/NA5-54 190.9 188 6 187 11-10-67 OSV-3E 101 76 000259 7604 760.0 SUCCESS 8098 268 76 04 102 1325 0.37 1.03 1 .058 0.00550 0116 PINNEER - C 12-13-67 DSV.3E a 4 0 0 987 0010 0 913 0 001 1.090 55 0 0249 0.0541 00489 SUCCESS 10588 0.0337 00052 GEOS-B 1-11-68 DSV 35 849.9 594.2 105 98 0 0307 SUCCESS 56 795 274 858.3 84 5846 9.6 105.80 0.18 099 0 0329 0,0022 0 0099 RAE-A 57 7.4.68 DSV-35 3174 5 345.2 12101 0 2756 3176 6 21 104 94 9445 0.7 15 64 120 63 0.38 1.05 0 2720 0 0036 SUCCESS 0125 705-Ę 8 16-68 DSV-31 7898 788 8 7963 6.5 21.6 101.73 0.01 0 37 0.0020 10 0019 58 101.72 0.0001 21.4 179.1 9.7 SUCCESS INTELSAT IL-A 9-18 68 DSY-31 19823 143 3 59 E9.B 0 7288 FIRST STAGE FALLIRE PIONEER D 11-8.68 DSV. 36 2401 0755 0080 01352 0 491 0000 0.007 a 4 0 754 Q U 0001 a 4. 0 0903 0.010 60 SUCCESS 0 084 0.1357 0 0005 12-5-68 DSV-3E 114 750 239 8 28 29 0 9397 120552 5802 -205-A 61 2298 28 28 0 010 0.12 0 9425 0 0028 SULLESS 28218 100 20.14 0 0068 78855 785.29 01 729 0.0001 1795.75 7 20 TOS-F 62 12-15-68 DSV-3L SUCCESS 76492 21.4 20 37 -219 101 801 0 072 0 37 0 10 38 0 1037 NIELSAT III.C ý đ 18.868 05V-3L 19835 1431 29.80 0 7330 19642 -193 -978 1453 2.2 29.86 0.06 0 65 10 7309 0 0021 0124 SUCCESS 20.7 030-F 64 1.22.69 DSV-30 300 8 299.6 3291 00017 3072 6.4 494 2966 -29 59.18 32 99 0.08 0.58 0 0014 0.0012 SUCCESS .5:5 A 88 5 0,1750009 1918 8 132-69 DSV-36 1895.1 17.7 311.9 SUCCESS 65 304 7 68.7 7.2 88.42 1 32 0 1755 0 03067 2892 -0 08 0.0054 VIELSAT II -B 2.5.69 054.36 19835 143.1 19563 2986 006 66 29 80 0 7330 1431 065 0.7303 0 027 0.0124 SUCCESS -272 -972 00 -21.0 135.G 61 2 86 69 034.3E 793 71 786.43 101.73 000200 820 427 101 785 0 06 0 89 :00605310 00575 26 77 74.9 739.16 -17 27 - 790 SUCCESS 28 61 0.26 0 78 10 7330 0,0007 0 0126 NELSAT ZI-D 68 5-81 69 DSV-31 19956 150 28.87 0.7337 19911 -45 -1251 1583 23 199 SUCCESS INP-G 69 6.21-69 054-3E 113960 184.9 83 792 0 9401 96296 -17665 -20414 20.3 21.8 86 793 3001 1.684 09292 0.0107 5 SUCCESS 2052 0122 8105-D 6-29-69 OSV-36 207.9 199.1 SUCCESS 70 33 498, 0 0011 1 212.5 4.6 17.8 196.5 -32 143 33,560 0 062 0 063 0 0022 0.0011 0033 11 7-26-69 DSV. 31 19940 149.7 INSELSAT II.6 28 81 0 7336 2913 -17327 -1251 1470 -8.7 21.6 1.49 078 THIRD STAGE FAILURE 30,30 0 2181 0 45550 0126 050 · G 12 8.9.69 054.32 300.458 299 251 32 944 a 00323 299.447 - 1.017 -593 213 411 - 24,84 - 26,62 32 967 0 023 0.124 0.00349 0.003167 0.0385 SUCCESS 6.7. g 98 PIONEER-C 8-27-69 DOV-3L 13 0.025 0.03 FIRST STRGE FRILUEE IDC5P/A.A 11-28-69 DSV-36 1973.8 150 2 28.0 0.7325 ADE3 2 291.4 178.3 14146 - 8.7 -131 74 27 56 -0 44 -0 85 0.7360 0 035 0.0079 SUCCESS

*** THREE SIGMA VALUES ARE 90% CONFIDENCE LEVEL VALUES GENERATED FOR THE MISSION INCENTIVE CRITERIA

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			r		NOMIN		<u></u>	ACTURE	DECTA	30	ACTUAL	Deur	30	ASSUAL	Decm	30-	ACTUAL	Detro	30	I
MISSION	LAUNCH	GOTE	covr	APOGE	PERKSCE		ECC.	APOCKA	APOGEE	∆ha.	PERISSI		Ohp	INCON	INCLIN	4	Ecc.	ELC.	∆e_	COMMENTS
INTELSAT I	15	1-14.70	054.32	19541 3	1476	28.03	0 1308	193993	-145.0	- 728.4	143 4	-4.2	-25.0	20 05	0.08	0.99	0 <u>.7</u> 285	a.0023	20079	5000E55
TIROS .M	76	1-25-10	054.36	7982	784 5	101 746	0 00088	798.3	6.1	26 64	781.32	-2.18	- 22 671	101 9.98	0.236	0496	0.00/88	0.001	0.0002	51/20555
NATO . A	77	3.20.70	05 V 3L	20116	103 8	25.90	0 7360	19896	202	864 6	152.53	-0.10	-23.0	25.68	0.88	-085	0.7339	0.0021	20050	SUCCESS
INTELSAT ILG	78	4-22-10	DSV-3L	195443	147.6	28.03	<u>0.7308</u>	1 <u>7923.9</u>	2220.4	-113.7	153.7	6.1	25.0	2781	-0.88	-097	0.7017	0.0261	<u>5 0019</u>	GUCCESS VELOUITY END STOP
INTELSAT I H	79	7-23-70	DSV-3L	R537 6	147.8	<i>E8.0</i> 3	0.7897	19572.8	40.2	761.15	1499	2.7	25.0	2796	-0.07	-099	07299	00002	0.009;	SUCCESS
IDCSPLA.B	80	8-19-70	DSV-3L	20116.9	153.2	25.90	0.7360	20271 5	165.1	917.46	1441	-9.1	- 25.0	28 93	0.03	085	0.1382	0 0022	0.0090	SUCCESS
I TOS-A	81	12 11.70	034.36	791.8	7815	101.75	0 000501	785.0	3.2	27.5	7769		-29.1	101.944		0472	0.00214	0 00/64	0 00577	SUCCESS
NATO-B	88	2.3.71	054.36	20,116.4	153.2	25.90	0.7360	20389.5	272.1	917.45	146.3	- 6.9	-25.0	25.78	-0.12	-0.85	0.7382	0.0022	0.0090	SUCCESS
IMP-I	83	3-13-71	DSV-3L	114912	127.6	28.78	0.9415	111424	-3548	74760	132.9	5.3	25.0	29.69	-0.09	040	0.9395	0.0019	0.0069	SUCCESS
1915-D	84	4.1.71	OSV.3E	757.1	756.2	88.73	0 00011	<i>782</i> 7	25.60	62.7	737.7	7854	-68.3	88.15	-0.58	-1.00	0 00537	00526	0 012991	SUCCESS
050-H	85	9.29.11	051-31	300.5	897.5	32.96	0.0004	310.2	9.7	29.5	204.8	-92.7	-29.5	33 095	0.135	0.138	0.0142	00138	0.005z	SUCCESS: STALLE MORAULI
I 705-B	86	10 21-71	05V-3L	791.0	188.0	101 60	0 0003	(IM	PACT	ING	TRA	JECT	DRY	AT S	ECON	(11)				SECOND STAGE FAILURE
HEOS-AL	87	1.31.72	DSV-3L	132370	220.98	9001	094154	132210	-100	5767	214+	-6.98	7.3	8995+	-006	023	0.94751	<u>ō,2223</u>		SUCCESS + QUICK LOOK DA
TD-1	88	3.11.12	DSV-3L	295.84	295.25	97.62	0000018	294.7	-1.14	8.76	291.1+	- 4.15	88	97.55+	-007	010	2.32783	0 024		SUCCESS + DUICH LODY 27
ERTS-A	89	7.23 72	900	497.4	491.0	99.10	0.0009	499.1	1.7	3.4	489.6	-1.4	-5.6	9903	-0.02	0045		0 003	0.001	SUCCESS: FIRST DIGS
IMP-H	90	9.22.72	1604	130873	133.9	28 81	<u> 1948/2</u>	1291624	1710	13262	134.3	0.4	3.11	<u> 7.8 646</u>	-0.16	0.670	094746	0 00066	60067	SUCCESS: FIRST ELT
I 105-D	91	10-15-12	300	790.4	7890	101.77	<u>a axo z</u>	789.3	-1.1	-8.9	784.7	-4.9	-8.9	101 74	-0.03	Q.043	0.0005	<u>aav3</u>	0.00.12	SUCCESS
TELESAT-A	98	11-10-72	1914	19524	1050	27.00	0.7338	19699	175	498	104.Z	-0.8	-2.3	27.00	0	0.382	0.7356	0 00:8	00049	SUCCESS: SECOND STAGE
NIMBUS-E	95	12.10.72	900	597.5	596.0	99.96	0.0002	597.6	+0.1	+8.3	594.7	-1.3	-7.0	99.9.1	-0.02	0.041	aaxoos	200015	0.0011	SUCCESS
TELESAT-B	94	4.20.75	1914	19533	115.1	26. <u>80</u>	<u>0.7328</u>	19596.	+63	485	114.8	-0.3	-2.2	26.73	-007	<i>-0</i> .33	<u>0.733</u> 4	00006	000+3	SUCCESS
RHE - B	95	6-10-73	1913	211275	99.1	29 31	0.9684	209110	-8165	E6040	99.0	-0.1	-2.15	29.11	-0.20	-0.66	09673	Javi	ā.w55	504453
I 105-E	96	7-16-73	300	805.6	805.5	101.91	0 00001	<u> </u>											<u> </u>	SECOND STASE FAULEE
IMP-J	97	10-26-13	1604	121396	106.6	28.8	094647	123591	-3805	-19609	107 2	0.6	6.78	28.17	-0.03	-0.51	094706	0.00059	0.0081	3066555
I 105-F	98	11-6-73	300	820.8	820.2	102.05	0.00001	817.6	- 3.2	-8.2	816.3	-3.9	-8.2	102 07	0.02	0.05	0 00015	a.00014	00046	SUCCESS
AE-C	99	1216-73	1900	2330.3	84.6	68./	0.24140	2335.5	5.2	12.9	85.6	-1.0	-1.0	68.191	0.031	0.048	0 24196	0.00056	0.0013	SUCCESS
SKYNET IA	100	1-19-74	2513	20054	100.9	24.6	0.7379		<u> </u>									·		SECOND STAGE FAILURE
WESTAR - A	101	4-13-14	2914	19506	185.0	24.765	0.7319	19579	+79	593	124.3	-0.7	-3./	24.734	0.051	~0,35	0.7326	0.0007	0.0059	SUCCESS CHERIFO TO MECC
5M5-A	102	5-17-74	2914	19524	99.9	23,800	0 7337	/7757	-1167	-688	94.9	-5.0	-3.0	24.531	0.731	0.343	0.7/50	6,0813	3.0070	SUCCESS STASE VELOCAN
WESTAR-B	103	10-10-74	2914	19506	125.0	24,769	0.7919	19484	-22.	593	124.5	-0.5	- 3.1	24.764	0.001	0.35	0.7317	0.0002	0 0059	5000055
I 105-G	104	11 15.74	2310	7897	189.9	101.73	0.00004	189 b	-0.1	-3.6	785 5	-4.0	-83	101.79	0.000	0.05	00005	0.0005	0 0012	SUCCESS
SKYNET-IIB	105	11-22-74	2313	19949	100	24.6	0.7379	19948	-1.0	-621	99.96	-0.04	-2.3	24 594	0.006	0.33	0.7379	0.0	20053	SUCCESS ,
SYMPHONIE-A	106	12-18-74	2914	20519	216.0	13.156	0 7560	20.548	+29	+1686	217.0	+1.0	+ 2.7	19.205	\$0.049	0.34	07359		0 0159	SUCCESS
ERIS-B	107	1.22.75	8910	498.0	4922	99.094	0.00073	496.6	-1.4	-2.9	493.9	+1.7	+46	99.074	-0.020	0033	0 000 3	-	0 0000	SUCCESS
5M5-70	108	8-06-75	8914	19784	100.0	23.000	0 7363	19770	-14	-461	99.4	-06	-30	23.815	0.015	0.323	0.7362	0.0001	7.0067	5000695
GEOS-C	109	4.09.75	1410	458.2	457.8	114.996	0.00005	458.4	+0.2	+9.56	457.8	-1.5	-9.09	114.982	0.014	0.049	0.00025		0.001	SUCCESS
TELESAT-C	110	5.01.75	8914	19506	125.0	24.765	0,7319	19408	-98	-666	125.0	0.0	2.9	24.751	0.014	0.366			3.0069	SUCCESS
NIMBUS-F	111	6-12-75	2910	599.2	597.5	99.960	0.00022	598.3	-0.9	-5.3	596.6	-0.9	-6.0	99.960	0.0		0.00022		0.0010	SUCCESS

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050-I		6-21-75			299.9						299.3						0.00013			
C03-B	113	8-08-75	2913	59992	188.19	90 000	188113	54433	+441	+2/35.0	187.17	-1.02	-9.5	90.155	+0.155	10 822	0 88276	0 00/43	a 00 597	SUCCESS
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TABLE 1-1 (CONTINUED) COMPARISON OF ORBIT PARAMETERS

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Table 2

SEQUENCE OF EVENIS - COS-B MISSION

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		- Time	e From Liftoff (se	c)
	Event	Guided Nominal Value	BET-With-Winds Value	Actual Value
FIR	ST STAGE		·	-
1.	Solid-Motor Ignition Arm	-0.90	***	· -1.14
2.	Solid-Motor Ignition Command	0.20		-0.38
3.	Telemetry Liftoff			-0.18
4.	Solid-Motor Burnout (6)	38.62	38.61	38.47
5.	Solid-Motor Ignition (3)	39.00	39.08	38.58
6.	Solid Motor Burnout (3)	77.81	77.81	77.61
7.	Solid-Motor Separation (9)	87.00	87.00	87.34
8.	MECO Enable	230.942	223.653	222,32
9.	Sensed MECO (0.5g)	230.322	231.033	227.28
10.	Vernier-Engine Cutoff (VECO) .	236.322	237.033	233.80
11.	First-Stage/Second-Stage Separation Command	238 . 322	239.033 .	235.88
SECO	ND STAGE - FIRST BURN			
13.	Second-Stage Ignition Command No. 1	243.322	244.073	240.81
14.	Second-Stage Engine Start No. 1 (Steady State)	243.662	244.373	241.18
15.	Fairing Separation (Actual)	273.332	274.033	270.35
16.	Second-Stage Engine Cutoff Command (SECOM) No. 1 (DIGS Velocity Cutoff)	530.121	533.919	530.56
17.	Sensed Second-Stage Engine Cutoff (SECO) No. 1 (.5g)	530.832	534.662	530,87

Table 2 (Continued)

SEQUENCE OF EVENTS - COS-B MISSION

.

		Time	From Liftoff (Sec) -
	Event	Guided Nominal Value	BET-With-Winds Value	Actual Value
HIRI	STAGE			
	Fire Spin Rockets, Start Third- Stage Ignition Time Delay, and Start Third-Stage Timer	3026.621	3027.439	3025,30
9.	Second-Stage/Third-Stage Separation Second-Stage Retro Initiation	3028.621	3029.439	3027.32
0.	Third-Stage Ignition	3070.121	3070.939	3071.2
1.	Third-Stage Burnout	3114.921	3115.739	3115.7
2.	Spacecraft Separation	3187.00	3187.439	3185.32

Table 3

SUMMARY OF FIRST STACE PERFORMANCE PARAMETERS (COS-B MISSION)

Item	Unit	Guided Nominal Value	BET-With-Winds Value	Actual Value
FTOFF WEIGHT (LB)	······································	291,785.71	291,288.85	291,290.0
LID MOTOR BURNOUT (6)				
Time (Average)	sec	38.62	38.61	38.97
Inertial Velocity	ft/sec	1660.03	1677.0	1668.89
Velocity (Relative to Launch Point)	ft/sec	1,259.8	1,274.5	1,264.1
Inertial Flight Path Elevation Angle	deg .	42.67	42.99	43-05
Flight Path Elevation Angle*	deg	63.12	63.62	64.15
Inertial Flight Path Azimuth Angle	deg	116.37	116.17	115.51
Flight Path Azimuth Angle *	deg .	196.61	195.93	196.42
Range	ft	6530.9	6604.3	6680.2
Altitude	ft	19,624.4	19,759.2	20,533.4
DLID MOFOR BURNOUT (3)				
Time (Average)	sec	77.81	77.81	77.61
Inertial Velocity	ft/sec	2,657.7	2,643.5	2,679.0
Velocity (Relative to Launch Point)	ft/sec	2,640.4	2,628.5	2,664.3
Inertial Flight Path Elevation Angle	deg	37.34	37.47	38.27
Flight Path Elevation Angle*	deg	37.46	37.55	38.35
Inertial Flight Path Azimuth Angle	de g	161.60	161.60	161.66
Flight Path Azimuth Angle*	deg	196.48	196.71	196.67
Range	ft	52,668	52,499	51,723
Altitude	ft	71,030	71,649	72,573

* Angle is with respect to the relative velocity vector.

- Table 3 (Continued)

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SUMMARY OF FIRST STAGE PERFORMANCE PARAMETERS (COS-B MISSION)

Item	Unit	Guided Nominal Value	BET With Winds Value	Actual Value
DLID-MOTOR SEPARATION (8)				
Time (Average)	sec	87.00	87.00	87.34
Inertial Velocity	ft/sec	2853.1	2833.1	2891.0
Velocity (Relative to Launch Point)	ft/sec	2878.3	2864.8	2926.4
Inertial Flight Path Elevation Angle	deg	33.11	33.19	33.85
Flight Path Elevation Angle*	deg	32.61	32.60	33.22
Inertial Flight Path Azimuth Angle	deg	166.10	166.33	166.75
Flight Path Azimuth Angle*	deg	196.50	196.93	196.93
Range	n.mi.	12,06	12.00	12.12
Altitude	n.mi.	14.08	14.17	14.56
UIDANCE INITIATION	,		, · · ,	
Time	sec	125.0	125.0	125.0
Inertial Velocity	ft/sec	4486.2	4465.7	4528.9
Velocity (Relative to Launch Point)	ft/sec	4609.7	4594.5	4674.9
Inertial Flight Path Elevation Angle	deg	20.52	20.43	21.24
Flight Path Elevation Angle#	deg	19 .77	19.66	20.38
Inertial Flight Path Azimuth Angle	deg	177.35	177.58	178.53
Flight Path Azimuth Angle#	deg	194.38	194.65	195.40
Renge	n.mi.	23.66	23.68	24.43
Altitude	n.mi.	23.66	23.68	24.43

Table 3 (Concluded)

SUMMARY OF FIRST STAGE PERFORMANCE PARAMETERS (COS-B MISSION)

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Item .	Unit .	Guided Nominal Value	BET-With-Winds Value	Actual Value
N ENGINE CUPOFF SIGNAL				
Time	sec	229.942	230.653	226.835
Inertial Velocity	ft/sec	16443.9	16505.0	16446.0
Velocity (Relative to Launch Point)	ft/sec	. 16486.4	16547.5	16482.6
Inertial Flight Path Elevation Angle	deg .	11.31	11.30	11.18
Flight Path Elevation Angle *	deg	11.11	11.10	10.99
Inertial Flight Path Azimuth Angle	deg	179 . 53	179.54	179.28
Flight Path Azimuth Angle*	deg	184.22	184.21	183.96
Longitude	deg	121.19	121.19	121.18
Geodetic Latitude	deg	31.71	31.69	31.78
Range	n.mi.	184.64	185.67	180 .40
Altitude	n.mi.	58.58	58.78	57.81
IIP Time	sec	659.52	663.15	652.30
IIP Range	n.mi.	1297.21	1309.7	1283.0
Weight	1b ,	26924.4	26833.4	26833.4
Liquid Propellant Utilization	<i>7</i>	99.81	99.81	99.84

* Angle is with respect to the relative velocity vector.

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Table 4

Item	Unit	Guided Nominal Value	BET With Winds Value	Actual Value
COND STAGE START				
Time (Steady State)	sec	243.662	244.373	240.813
Inertial Velocity	ft/sec	16426.6	16487.9	16416.5
Velocity (Relative to Launch Point)	ft/sec	16470.0	16531.4	16460.1
Inertial Flight-Path Elevation Angle	deg .	10.47	10.47	10.60 [.]
Flight-Path Elevation Angle*	deg	10.27	10.27	10.40
Inertial Flight-Path Azimuth Angle	deg	179.54	179.55	, 179.55
Flight-Path Azimuth Angle*	deg	184.26	184.25	184.26
Range	n.mi.	220.5	221.66	216.9
Altitude	n.mi.	65.5	65.72	64.9
Weight	lb .	15744.6	15706.0	15708.7
SE FAIRING JETTISON	· · ·		-	•
Time	Sec	273.32	274.033	270.35
Weight of Fairing	Ъ	1320.0	1305.0	1305.0

SUMMARY OF SECOND STAGE PERFORMANCE PARAMETERS (COS-B MISSION)

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* Angle is with respect to the relative velocity vector.



Table 4 (Continued)

SUMMARY OF SECOND STAGE PERFORMANCE PARAMETERS

Item	Unit	Guided Nominal Value	BET With Winds Value	Actual Value
COND STAGE FIRST BURNOUT ECO) 1		. ·		
Time	sec	530.832	534.662	530.873
Inertial Velocity	ft/sec	25636.8	25639.3	25636.2
Velocity (Relative to Launch Point)	ft/sec	25678.2	25680 . 8	25677.7
Inertial Flight Path Elevation Angle	deg	-0.98	-0.97	-0.97
Flight Path Elevation Angle*	deg	-1.07	-1.07	-1.07
Inertial Flight Path Azimuth Angle	deg	179.86	179.86	179.86
Flight Path Azimuth Angle*	deg .	183.26	183.26	183.26
Range	n.mi.	1140.6	1154.5	1152.64
Altitude	n.mi.	121.4	. 121.2	121.54
Weight	16	5170.0	5194.4	5143.62
Longitude	deg	122.36	122.37	122.36
Geodetic Latitude	deg	15.75	15.52	15.55
Radius of Apogee	n.mi.	3678.4	3679.0	3677.5
Radius of Perigee	n.mi.	3531.4	3531.6	3531.2
Inclination	deg '	89.869	89.869	89.869
Eccentricity		0.02039	0.02044	0.02029

* Angle is with respect to the relative velocity vector.

Table 4 (Concluded)

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Item	Unit	Guided Nominal Value	BET-With-Winds Value	Actual Value
PROPULSIVE PERFORMANCE PARAMETERS (FIRST BURN)				
Burn Period (Steady State to SECQM 1)		286.459	289.546	289.42
Thrust (Average)	1b	9,707.09	9,548.36	9,596.9
Specific Impulse (Average)	sec	301.77	300.63	300,66
Total Second Stage Impulse	lb-sec	2,780,681.9	2,764,689.6	2,777,539.2
Total Propellant Consumed (Steady State to SECOM ₁)	1b	9,236.4	9,196.45	9,238.0
Propellant Consumption (Steady State to SECOM ₁)	×	92.01	91.81	92.37

SUMMARY OF SECOND STAGE PERFORMANCE PARAMETERS (COS-B MISSION)

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Table 5

SUMMARY OF THIRD STAGE PERFORMANCE PARAMETERS (COS-B MISSION)

Item	Unit	Pre- dicted Value	BET-With-Winds Value	Recon- structed . Value
THIRD STAGE IGNITION	• •			
Time .	sec*	3,068.82	3,070.94	3,068.82***
Inertial Velocity	fps	25,159.8	25,152.8	25,159.8
Velocity (Relative to Launch Point)	fps	25,199.8	25,192.7	- 25,199.8
Inertial Flight Path Elevation Angle*	deg	1.09	· 1.10	1.09
Flight Path Elevation Angle*	deg	0.97	0.97	0.96
Inertial Flight Path. Aziruth Angle	deg ·	0.14	0.14	0.14
Flight Path Azimuth Angle#	deg	356.77	356.77	356.77
Longitude	deg	-47.01	-47.01	-47.00
Geodetic Latitude	deg	-23.19	-23.19	-22.91
Euler Attitude Angles*				
Pitch (0 _{PB})	deg	169.56	169.56	170.37
$Y_{aw} (\psi_{PB})$	deg	15.57	15.57	15.01
Roll (ϕ_{PB})	deg	-79.09	-78.79	-79.00
Range	n.mi.	9,849.9	9,862.7	9,849.9
Altitude	n.mi.	189.2	190.7	189.2
Weight	lb	2,262	2,262	2,262

*Angle is with respect to the relative velocity vector.

**Euler angles θ_{PB} , ψ_{PB} , and ϕ_{PB} are the angles specifying the orientation of the vehicle axes $(X_{PB}, Y_{PB}, \text{ and } Z_{PB})$ with respect to an inertial reference platform. The order of rotation is: Pitch, θ_{PB} about Y_{PB} (positive turning Z_{PB} into X_{PB}); yaw, ψ_{PB} about Z_{PB} (positive turning X_{PB} into Y_{PB}); and roll, ϕ_{PB} about X_{PB} (positive turning Y_{PB} into Z_{PB}), in degrees.

***41.5 seconds after stage II/III separation.

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Table 5 (Continued)

SUMMARY OF THIRD STAGE PERFORMANCE PARAMETERS

(COS-B MISSION)

Item .	Unit	Pre- dicted Value	BET-With-Winds Value	Recon- structed Value
HIRD STAGE BURNOUT			<u></u>	• • • • • • • • • • • • • • • • • • •
Time	sec	3,113,62	3,115.739	3,113.62
Inertial Velocity	ft/sec	34,615.3	34,609.8	34,622.8
Velocity (Relative to Launch Point	ft/sec	34,648.7	34,643.1	34,660.5
Inertial Flight Path Elevation Angle	deg	2.56	2.49	2.76
Flight Path Elevation Angle#	deg	2.44	2.37	2.64
Inertial Flight Path Azimuth Angle	đeg	360.00	360.00	359.84
Flight Path Azimuth Angle*	·đeg	357.48	357.49	357.32
Longitude	deg	-46.82	-46.83	-46.82
Geodetic Latitude	deg	-19.52	-19.79	-19.52
Euler Attitude Angles**	i			
Pitch (0 _{PB})	deg	169.56	169.56	170.37
Yaw (ψ_{PB})	deg	15.57	15.57	15.01
Roll (ϕ_{PB})	deg	-78.79	-78.79	-79.00

*Angle is with respect to the relative velocity vector.

**Euler angles Θ_{pB} , ψ_{pB} , and ϕ_{pB} are the angles specifying the orientation of the vehicle axes $(X_{PB}, Y_{PB}, \text{ and } Z_{PB})$ with respect to an inertial reference platform. The order of rotation is pitch, Θ_{PB} about Y_{PB} (positive turning Z_{PB} into X_{PB}); yaw, ψ_{PB} about Z_{PB} (positive turning X_{PB} into Y_{PB}); and roll, ϕ_{PB} and X_{PB} (positive turning Y_{PB} into Z_{PB}), in degrees.

Table 5 (Concluded)

SUMMARY OF THIRD STAGE PERFORMANCE PARAMETERS.

(COS-B MISSION)

Item	`Unit	Pre- dicted Value	BET-With-Winds Value	Recon- structed Value
Inertial Attitude Angles*				
Elevation Angle (Θ^*_{L})	deg	5.30	5.03	6.04
Azimuth Angle (ϕ'_{L})	deg	359.62	359.63	359.02
Roll Angle (¢',)	deg .	-82.11	-82,10	-82.16
Range	n.mi.	9,681.5	9,695.4	9,681.4
Altitude	n.mi.	194.79	196.2 ·	195.2
Weight	· lb	811.5	811.6	811.5
Total Third Stage Impulse	lb-sec	417,678.9	417,678.9	418338.8
Spacecraft Weight	1b	612.0	614.15	614.15
Radius of Apogee	n.mi.	57,670.8	57,732.8	58,204.6
Radius of Perigee	n.mi.	3,629.7	3,631.4	3,628.8
Inclination Angle	deg	90.000	90.000	90.155
Eccentricity		.8816	.8816	.8826
Argunent of Perigee	deg	335.13	335.009	334.7

*The vehicle centerline elevation angle $0'_{L}$ is the angle between the vehicle centerline and the plane perpendicular to the radius vector from the center of the earth to the vehicle (positive for the vehicle nose pointing away from the earth), in degrees. Vehicle centerline azimuth angle ψ'_{L} is the angle between the local meridian and the projection of the vehicle centerline onto a plane perpendicular to the radius vector from the center of the earth to the vehicle (positive clockwise from true north), in degrees. The vehicle instantaneous geocentric roll angle ϕ'_{L} is in degrees.

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Table 6

SUMMARY OF POSTFLIGHT STATISTICS

NOMINAL PREDICTIONS

(COS-B MISSION)

BOOSTER: DSV-3P-1A Extended Long Tank

SECOND STAGE: DSV-3P-4B (Quartz)

'arameter	COS-B Deviation from Guided Nominal	No. of Samples	Mean Deviation	Sigma About Mean
OLID MOTORS (6)	· · ·			
Drop Time	+0.34	<u>,15</u>	-0.235	0.686
WIDANCE INITIATION	· · ·			•
Altitude (n.mi.)	+0.77	10	0.623	0.527
Inertial Velocity (ft/sec)	+92.7	10	60.7	97.7
Inertial Flight-Path Elevati Angle (deg)	.on +0.72	10	0.948	0.360
Inertial Flight-Path Azimuth Angle (deg)	+1.18	10	-0.018	0.621
<u>ECO</u>				
Time (sec)	-3.107	10	-1.555	2.825
Altitude (n.mi.)	-0.77	10	0.037	0.523
Inertial Velocity (ft/sec)*	154	· 10	179.2	110.7
Inertial Flight-Path Elevati Angle (deg)	.on -0.12	10	. 0.040 _	0.130
Inertial Flight-Path Azimuth Angle (deg)	-0.15	10	0.016	0.079

" Based on DIGS telemetry data and predicted nominal MECO velocity.

TABLE 6 (Concluded)

SUMMARY OF POSTFLIGHT STATISTICS

NOMINAL PREDICTIONS

COS-B MISSION

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<u>.</u>

BOOSTER: DSV-3P-1A Extended Extended Long Tank

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SECOND STAGE: DSV-3P-48 (Quartz)

Parameter D	COS-B eviation from Guided Nominal	No, of Samples	Mean Deviation	Sigma About Mean
SECOND STAGE				
First Burn Time (sec) '	2.892	10	0.488	2.902
Propellant Consumption Through End of Primary Mission (%PU/oPU)	0.66	10	-0.771	1.320
SECO 1				
Altitude (n.mi.)	. +0.10	11	0.014	0.242
Inertial Velocity (ft/sec)	0.6	בנ	-0.493	3.644
Inertial Flight-Path Elevat Angle (deg)	ion 0.01	11	0.0004	-0,010
Inertial Flight-Path Azimut Angle (deg)	h . 0.00	11 .	0.063	0.090
	,			

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Table 7

SUMMARY OF POSTFLIGHT STATISTICS

TAG PREDICTIONS

COS-B MISSION

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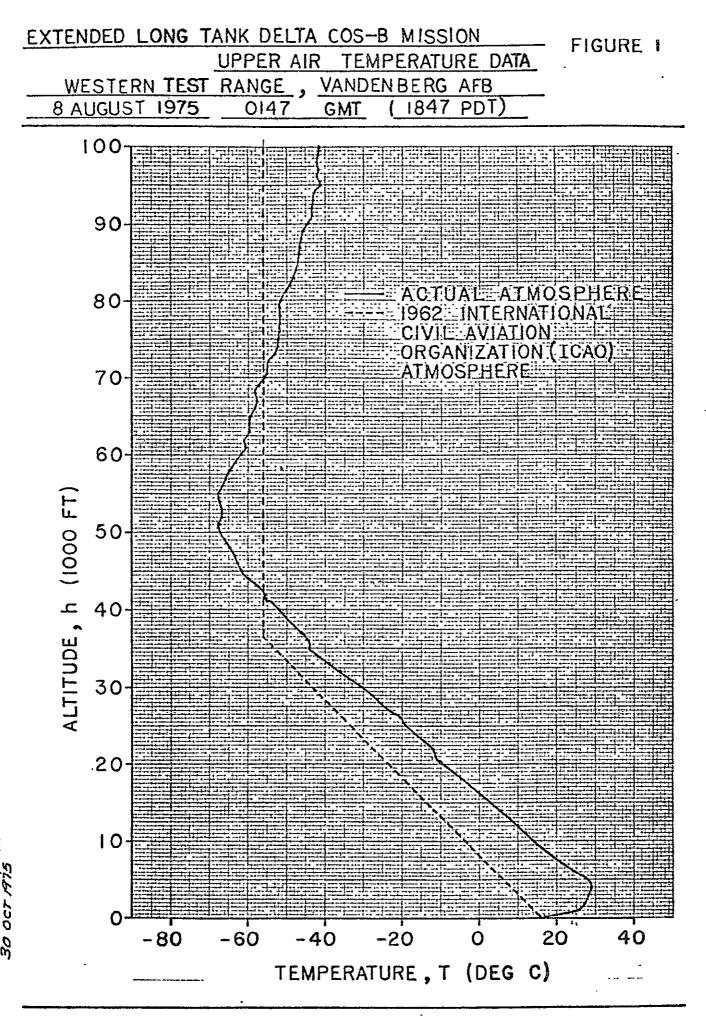
BOOSTER: DSV-3P-1A Extended Long Tank SECOND STAGE: DSV-3P-4B (Quartz)

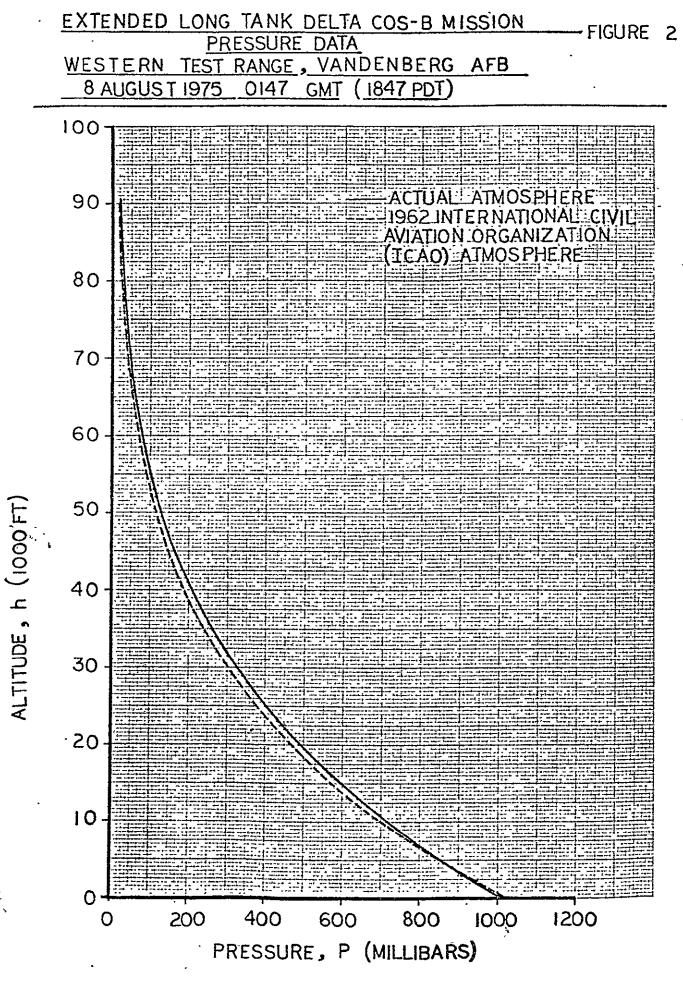
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Parameter	COS-B Deviation from Tag	No. of Samples	Mean Deviation	Sigma About Mean
BOOSTER	· · · · · · · · · · · · · · · · · · ·			· · · ·
Burn Time (sec)	-3.497	10	-1.736	1.820
MECO Inertial Velocity (ft/sec)* +92	10	. 176.9	121.2
MECO Altitude (n.mi.)	-0.98	10	0.021	0.533
SECOND STAGE		,		
First Burn Time (sec)	-0.227	10	-4.988	2.867
Propellant Consumption Through End of Primary Mission (%PU/oPU)	0.035	10	0.035	1.066
Tailoff Impulse (1b-sec)	147	10	44.778	102.404

* Based on DIGS telemetry data and predicted nominal MECO velocity.

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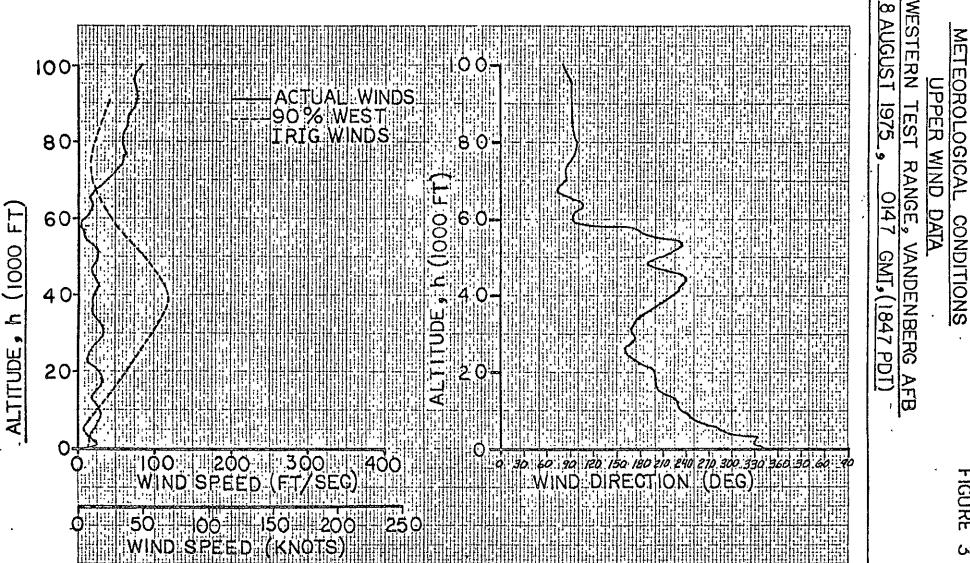
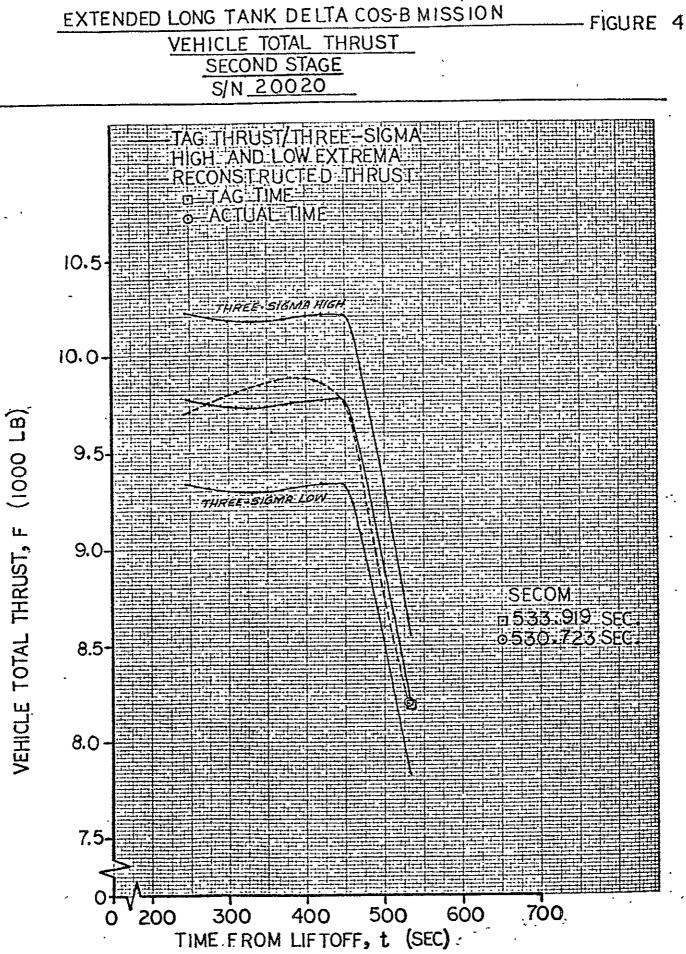


FIGURE сл



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Attachment 2 to: A3-262-AM00-M75-509

ATTACHMENT '2:

SECTION 2. PROPULSION SYSTEMS - COS-B MISSION

SECTION 2

PROPULSION SYSTEMS - COS-B MISSION

2.1 INTRODUCTION

Overall performance of the COS-B launch vehicle propulsion systems was satisfactory throughout first, second, and third stage flight. All data returned by telemetry channels used to monitor propulsion systems performance were satisfactory with two exceptions. The LOX pump inlet pressure transducer failed at approximately 74 seconds from liftoff, and the second stage chamber pressure exhibited the same anomalous characteristics observed on previous SSPU flights.

A summary of vehicle model and serial numbers is provided in Table 2-1. There were seven first flight items on this flight. These first flight items are listed in Table 2-2. All flight times in the text are given in seconds after DIGS indicated liftoff unless otherwise noted. The "DIGS Liftoff" time for this flight was defined as the time at which the vehicle achieved approximately 37.5 ft/sec² acceleration (about 5.3 ft/sec² off the pad) for four consecutive 20-millisecond time intervals. The propulsion system sequence of events is summarized in Table 2-3.

Reconstructed booster and second stage performance parameters are compared in Table 2-4 with corresponding values from the latest booster nominal simulation (Reference 2-1) and the Detailed Test Objectives Report (DTO, Reference 2-2). Values from both reports are referred to as nominal values since results of the nominal simulation are used to generate the DTO.

First and second stage reconstructed values are compared also with values from the Best Estimate Trajectory without winds (BET, Reference 2-3) and the Propulsion preflight tag predictions (References 2-4 and 2-5) in Table 2-4. Cumulative statistics for all comparisons in Table 2-4 are presented in Table 2-5.

In this section, the word "predicted" refers to preflight predictions of performance for the Propulsion systems utilized on this vehicle (References 2-4 and 2-5) and does not denote nominal or DTO values. The word "reconstructed" refers to postflight reconstructions of performance generated using telemetered system pressures, temperatures, event times, acceleration, and (for the second stage) flowrates. The term "internal" refers to reconstructions based on pressures, temperatures, and events. The term "external" refers to reconstructions using acceleration and the internally reconstructed vehicle mass history.

2.2 FIRST STAGE PERFORMANCE

Performance of the first stage propulsion systems is described in the following paragraphs.

2.2.1 Main Engine

All valid telemetry data indicated that the main engine flight performance was satisfactory, as summarized in Table 2-4.

Figure 2-1 shows the nominal and actual start sequence times. The agreement observed between the nominal and actual sequence times indicates a normal start sequence based on available engine statistics. The main engine start sequence was initiated 2.338 seconds prior to liftoff (DIGS).

Main engine cutoff (MECO) occurred 226.835 seconds after liftoff due to actuation of the fuel injector pressure switches (FIPS). The propellant residual at MECO was 281 pounds of fuel or 19 pounds less than the loaded bias of 300 pounds. The residual corresponds to a propellant consumption and a propellant utilization (PU) of 99.84 percent and mixture ratio variations of -0.0007 mixture ratio units (mru) from the preflight prediction and -0.0187 mru from the ground test tag prediction.

Figures 2-2 and 2-3 present the internal reconstructed liquid engine thrust and flowrate histories, respectively. The overall performance was good and generally verified the performance model.

The DIGS thrust acceleration measurements, together with preflight predicted drag and postflight internal reconstructed vehicle mass, were used to compute total external booster thrust and specific impulse. Figure 2-4 depicts the internal and external reconstructed thrust histories which agree very closely from liftoff to MECO.

Table 2-6 presents a comparison of averages for total vehicle altitude thrust and specific impulse between 120 seconds and MECO and the average mixture ratio over the entire flight. The internal reconstruction indicates first stage Isp was about 0.52 seconds higher than predicted; the external reconstruction shows a decrease of about 1.45 seconds from the predicted value. The preflight predicted and internal and external reconstructed values are compared with the ground test tag prediction in Table 2-6. Cumulative statistics for these parameters are also tabulated in Table 2-6.

2.2.2 POGO Suppression System (PSS)

The PSS was pressurized from a 464 psia regulated AGE source until liftoff. No inflight pressurization was provided, thus the inflight LOX volume was a function of the ullage gas mass and temperature and of the LOX pump inlet pressure. The two temperature probes in the PSS showed that the PSS performed satisfactorily and the LOX and ullage gas volume constraints were satisfied throughout the flight. The upper probe may have been covered momentarily by splashing at liftoff.

2.2.3 Vernier Engines

Vernier engine performance appeared satisfactory based on telemetered chamber pressure data from vernier engine No. 2. Reconstruction indicates that the engine was operating at a thrust level of 977 pounds during vernier engine solo, which is less than the nominal thrust of 1002 pounds.

2.2.4 30170 110 tors

Based on telemetered data and reconstructed performance values, the performance of the solid motors was satisfactory. Table 2-4 summarizes solid motor performance and Table 2-5 presents cumulative statistics for Castor II motors.

The reconstructed solid motor performance is based on event times and the chamber pressure histories. Total burn times for both the ground-ignited and altitude-ignited motor sets were generally slightly less than predicted. Web times were slightly greater than predicted. All burn and web times were well within the allowable dispersion band of the Castor II motors.

All of the solid motor start and thrust buildup transients were normal. Total thrust and flowrate histories for the solid motors plus the main engine are shown in Figures 2-4 and 2-5, respectively.

2.3 SECOND STAGE PERFORMANCE

The second stage engine operated normally for the first burn of 289.75 seconds, which was 0.75 seconds shorter than the BET prediction. The experimental restart had a duration of 25.06 seconds for a total burn time about 6.1 seconds less than the predicted depletion burn time of 320.6 seconds. A fuel depletion was observed. A summary of second stage first burn engine performance is presented in Table 2-4 while specific impulse, thrust, and flowrate histories are depicted in Figures 2-6, 2-7, and 2-8, respectively. Table 2-5 presents statistical data for values in Table 2-4.

2.3.1 First Burn

During first burn operation, the second stage temperatures and pressures were nominal. The propellant tanks pre-pressurization signal occurred at 229.83 seconds, 3.00 seconds after MECO (FIPS) command. During the pre-pressurization, the helium bottle, helium regulator, and propellant tank pressures were as expected.

2.3.1.1 First Burn Transient Performance

The total start transient impulse calculated using chamber pressure data was 346 pound-seconds compared to the previous average-flight value of 383 pound-seconds. The total propellant consumed during the start transient was 2.31 pounds compared to the average value experienced of 2.43 pounds. The shutdown propellant flow to propellant valves closure was 6.36 pounds compared to the average value experienced of 3.45 pounds.

DIGS accelerometer data indicate a shutdown impulse of 3187 pound-seconds, compared to the 3040 pound-seconds prediction derived from analysis of data from previous flights. The shutdown transient performance is summarized in Table 2-4.

2.3.1.2 Steady-State Performance

Second Stage Ignition Command No. 1 (SSIC No. 1) occurred 240.81 seconds after liftoff and Engine Start No. 1 occurred 0.37 second later at 241.18 seconds. SECOM No. 1 occurred 530.56 seconds after liftoff as the result of a planned DIGS-initiated cutoff command. Therefore, the propulsion system first burn steady-state powered flight duration (from Engine Start No. 1 to SECOM No. 1) was 289.42 seconds. This time was 1.08 seconds shorter than the BET predicted duration. The reconstructed average thrust was higher than predicted, as was the average flowrate yielding an average specific impulse that was 1.75 seconds lower than the BET prediction.

Although it did not adversely affect the primary mission, the COS-B vehicle experienced an anomalous vibration which occurred from 165 to 212 seconds into second stage burn. This anomaly is discussed in detail in Anomaly Report No. TOO166. The vibration had an acceleration level of approximately 2 g's zero to peak in the thrust axis at a frequency of approximately 130 Hz, as measured at the guidance section.

The fuel manifold used on COS-B was of a new buy, built especially for the Delta Program (previous fuel manifolds were designed for the Lunar Module Descent Engine or LMDE). The Delta fuel manifold incorporated minor production changes, including

a weld bead at the inlet. Corrective measures being considered at this time include the removal of the weld bead and stiffening of the thrust mount.

Analysis is continuing as additional test data become available. During the interim, silica chambers are being flown on stages utilizing the Delta manifold to improve stability margins.

Another anomaly with respect to mixture ratio and specific impulse was identified and is discussed in detail in Anomaly Report No. TOO168. Reconstruction of inflight performance indicated an approximate 0.010 mru shift in mixture ratio (M.R.) starting during the period of 130 Hz oscillations. The initial reconstruction also indicated an apparent 1% lower than expected specific impulse (Isp) throughout first burn engine operation.

The specific cause of the mixture ratio shift has not been determined, but is considered an effect of the 130 Hz oscillations due to the simultaneous onset times. Possible causes of the M.R. shift are: 1) cracks in the oxidizer pintle slots as a result of the oscillations, or 2) the effect of oscillations on flowmeter calibration (although the apparent increase in oxidizer flow rate is not consistent with postulated flowmeter failure modes).

The apparent low specific impulse has been attributed to flowmeter calibration error. A detailed evaluation of propellant depletion characteristics indicated a bias in the oxidizer flowmeter over the entire engine burn time. With the bias taken out of the flowmeter data, the calculated specific impulse is normal. Normal performance was also verified by stage velocity data; therefore, it is concluded that the engine specific impulse was normal. Information presented in this report reflects the corrected data.

Predicted and reconstructed values for propellant consumption were comparable. Approximately 808 pounds of usable propellant remained on board after SECOM No. 1 in reserve for the second and third burns. This represents a first burn propellant consumption (PC) of 92.37 percent. According to the integration of flowmeter data, the average first burn mixture ratio was 1.584 mru, less than the 1.598 predicted but within two sigma of the predicted value.

Reconstruction of thrust from acceleration data yields an average specific impulse of 300.66 seconds compared to a BET predicted specific impulse of 302.41 seconds. As depicted in Figure 2-6, from approximately ignition plus 200 seconds the reconstructed specific impulse decreases at a faster rate, moving farther away from the predicted level. The start of this decay in specific impulse (Isp) is coincident with the beginning of the tailoff portion of flight.

Based on chamber pressure data, the reconstructed throat erosion was -1.2 percent compared to a predicted value of 2.2 percent.

2.3.2 Coast

The second stage coasted for approximately 2688 seconds between the first and second burn. All monitored pressure and temperature values were acceptable during coast. The fuel tank pressure increased by about 15 psi and the oxidizer tank pressure rose about 27 psi during coast due to heating. Characteristics of the fuel tank pressure data indicate proper levels throughout the mission.

2.3.3 Second Burn (Experimental)

The second burn (as reconstructed) was initiated at 3218.3 seconds after liftoff. The burn was preceded by a settling period of approximately 15 seconds. No actual data were available for restart. Therefore, no conclusion can be made as to the adequacy of the settling period.

The restart steady-state burn duration was approximately 25.06 seconds which was 5.79 seconds shorter than the predicted value. Restart burn times usually are shorter than predicted because heating during coast increases the propellant tank pressures resulting in higher than predicted thrust and flowrate levels.

Approximately 55 pounds of propellant remained on board after SECOM No. 2. This corresponds to a propellant consumption value of 99.74 percent for the two burns.

2.3.6 Nitrogen Auxiliary Propulsion System (APS)

Predicted and actual impulse usages from the nitrogen APS for various events are tabulated below:

Event	Usage	Predicted	Actual-Predicted
First burn	18	16	2.3
First coast	297	430	-133
Separation and retro	54	44	10
Plume impingement	- 14	40	-26
Settling	125		10
Experimental burn	1	1	0
Total	509	646	-137

Overall APS performance was normal.

2.3.7 Second Stage Retro Initiation

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-Second stage retro initiation occurred at 3027.29 seconds after liftoff. During retro, bottle pressure decayed normally from 190 psia to approximately zero psia. Based on the DIGS system integrated velocity value, the separation distance at third stage ignition was approximately 42.3 feet, compared to the minimum required of 25 feet.

2.4 THIRD STAGE PERFORMANCE

2.4.1 Spin Motors

The spin table microswitch data indicate that the eight spin motors were fired at 3025.30 seconds after vehicle liftoff and produced a spin rate of approximately 39.3 rpm (versus predicted 39.8 rpm) at third stage/spin table separation. It is concluded that all eight spin motors performed satisfactorily.

2.4.2 Third Stage Motor

Performance of the third stage motor (TE-M-364-3, S/N 00025) was satisfactory based on the accuracy of the spacecraft orbit. The chamber pressure data exhibited a -10 psi shift at 23 seconds after ignition, and a complimentary

+10 psi shift at motor tailoff. The shape of the pressure-time curve appeared to be normal both prior to and after the pressure shifts. Accelerometer data did not exhibit corresponding shifts in the acceleration level, and it is therefore believed that the chamber pressure data shifts are not indicative of actual motor performance. Immediately after third stage motor tailoff, low level oscillations were noted on the spacecraft attach fitting accelerometers. The oscillations had a maximum amplitude of 2.3 G's 0-peak at a frequency of 800-1000 Hz, and lasted for 18 seconds. During this period of time, the motor chamber pressure did not register any activity. The cause of the oscillations is unknown at this time, but is under investigation. Predicted third stage solid motor performance parameters, obtained from Reference 2-6, are listed in Table 2-7.

REFERENCES

2-1	1emorandum A3-250-AD03-74090, dated 21 March 1974	
2-2	1emorandum A3-200-AAC3-11-75-357, dated June 23, 197	5
2-3	1emorandum A3-200-AAC3-M-75-454, dated 6 August 1975	5
2-4	1emorandum A3-226-AD03-75191, dated 10 July 1975	
2-5	1emorandum A3-226-AD03-75190, dated 2 July 1975	
2-6	demorandum A3-226-AD03-75178, dated 23 June 1975	

VEHICLE AND VEHICLE COMPONENT: IDENTIFICATION SUMMARY (COS-B)

Item	Manufacturer	Model	Sertal No.
Launch Vehicle	MDAC	DSV-3P-11B	20018
First Stage	MDAC	DSV-3P-1A	20020 (602)
Main Engine	Rocketdyne/A Division of Rockwell International Corporation (RD)	RS2701A	0017
Vernier Engines (two)	RD	LR-101-NA-11	No. 1: 338180 No. 2: 338181
Solid Motors (Set No. 1 - three)	Thickol Corporation (TC)	TX354-5 (Castor II)	No. 1: 473 No. 2: 474 No. 3: 475
Solid Motors (Set No. 2 - three)	TC	TX354-5 (Castor II)	No. 4: 480 No. 5: 535 No. 6: 489
Solid Motors (Set No. 3 - three)	TC	TX354-5 (Castor II)	No, 7: 494 No, 8: 498 No, 9: 548
Second Stage Propulsio	n System MDAC	DSV-3P-4B	20020
Engine	TRW	TR-201	1016
Third Stage	TC	TE-M-364-3	00025
Spin Motors	Atlantic Research Corporation (ARC)	1000399 - 529	

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FIRST FLIGHT ITEMS (COS-B)

- 1. Castor II motors with bimodal oxidizer propellant: Castor II Motors, S/N's 473, 474, 475, 480, and 489, were loaded with bimodal oxidizer propellant aft of the aft propellant slot. This is a departure from the standard trimodal oxidizer propellant.
- 2. Castor II direct-mount pressure transducer: Previously, the solid motor chamber pressure transducer was mounted in the motor forward dome with a short hardline connection to the motor pressure port. The change to the direct-mount configuration was accomplished to reduce potential hardline leak paths and facilitate launch site installation.
- 3. Castor II solid motor aluminum wiring tunnel: The previous fiberglass tunnel cover has been replaced with a similar design fabricated of aluminum including cork sheet interior insulation. The change to the aluminum tunnel was implemented to reduce cost.
- 4. Over-age TE-M-364-3 third stage motor: This was the oldest third stage motor to be flown (44 months old at launch). The oldest motor previously flown was S/N 00026 on SKYNET-IIB (35 months old).
- 5. Second stage fuel and oxidizer tank shutoff valves: The Fuel Tank Shutoff Valve (FTSV), P/N 1B96916-1, and Oxidizer Tank Shutoff Valve (OTSV), P/N 1B96916-501, replace the FTSV, P/N 1B95417-507, and OTSV, P/N 1B95417-509, effective DSV-3P-4B, S/N 20020, and subsequent.

The Pneudraulics, Inc., P/N 9386, restrictor check valve (PRCV) was replaced by the 1B97422-1 PRCV in order to obtain proper OTSV-FTSV differential opening time with the new TSV's. Physically, the two valves are identical except for the size of the restrictor flow orifice. The incorporation of the new TSV's also required minor modification of the interconnecting tubes between the PRCV and the TSV's, and a change in the pressurization sequence.

- 6. Second stage fuel pressurization fitting modification: The 1B94500-1 fuel tank pressurization fitting located on the forward dome of the SSPU fuel tank was modified by having its sense port increased from 0.098 inch diameter to 0.300 inch diameter. In addition, a 0.012 to 0.013 inch diameter hole was added between the fitting inlet pressure port and the fuel tank top pressure sense port.
- 7. POGO accumulator vendor change: The 1B89068-507 POGO accumulator (manufactured by Solar) was replaced by 1B96342 (manufactured by Coast Metal Craft). The vendor change was necessary because Solar no longer builds this part. The new accumulator is similar to the old part except for relocated transducer bosses and a slight decrease in internal volume as a result of different manufacturing techniques.

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PROPULSION SEQUENCE OF EVENTS (COS-B)

Events	. Timé from Liftoff (Seconds)
irst Stage	
Main Engine Start Command Solid Motor Sets Nos. 2 and 3 Ignition Command Solid Motor Sets Nos. 2 and 3 Burnout Solid Motor Set No. 1 Ignition Command Solid Motor Set No. 1 Burnout Solid Motors Separation Fuel Floatswitch Actuation LOX Floatswitch Actuation Main Engine Cutoff Command (MECO) Enable MECO (FIPS) Sensed MECO Vernier Engines Cutoff Command (VECO) Ist/2nd Stage Separation (Actual)	-2.518 -0.38 38.53 38.97 77.62 87.34 217.555 220.285 222.32 226.835 227.281 233.805 235.83
econd Stage	
First Burn	·
Pressurize Tanks Second Stage Ignition Command (SSIC) No. 1 First Chamber Pressure Rise Engine Start No. 1 (Full Thrust) Fairing Separation (Command) Second Stage Engine Cutoff Command (SECOM) No. 1 (Velocity or Depletion, etc.) Engine Stop (Valve Closure)	229.83 240.811 241.075 241.15 270.35 530.563 530.963
Second Burn	
Settling Jets On SSIC No. 2 First Chamber Pressure Rise Engine Start No. 2 (Full Thrust) Settling Jets Off SECOM No. 2 (Fuel Depletion) Engine Stop (Valve Closure) Spacecraft or Third Stage Separation	3203.32 LOS LOS LOS 3247.514 3247.914 3027.32

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PROPULSION SEQUENCE OF EVENTS (COS-B) CONTINUED

Events	Time from Liftoff (Seconds)			
Third Stage (From Third Stage Telemetry Data)				
Spin Motor Initiation; Third Stage Delay Squib Initiation	3025.30			
Second Stage Retro Initiation	3027.29			
Third Stage Separation	3027.32			
Third Stage Ignition	3071.2*			
Third Stage Burnout	3115.7*			
Spacecraft Separation	N/A			

*Estimated from third stage chamber pressure data.

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SUNMARY OF PERFORMANCE PARAMETERS (COS-B)

Parameter	Unit	Nominal Value	Tag Value	.Internal Reconstructed Value	Deviation From Nominal Value	Deviation From Tag Value
rst Stage					•	
Liquid Engine System						
Average vacuum thrust Average-vacuum effective specific impulse	lbf. sec	223,278 291.55	223,019 292.61	226,522 292,37	3,244 0.82	3,503 -0.24
Propellant utilization	%	99.81	99.81	99.84	0.03	0.03
Solid Motors (4, 5, 6)		•				
Average vacuum thrust Average vacuum effective specific impulse (Isp)	lbf sec	166,119 258.80	166,119 258.80	168,311 260,81	2,192 2.01	2,192 2.01
Vacuum axial total impulse	1bf-sec	6,414,503	6,414,503	6,473,312	58,809	58,809
Solid Motors (7, 8, 9)				•		
Average vacuum thrust Average vacuum effective Isp Vacuum axial total impulse	lbf sec lb-sec	166,119 258.80 6,414,503	166,119 258.80 6,414,503	167,117 260.3 6,447,931	998 . 1.5 33,428	998 1.50 33,428
Solid Motors (1, 2, 3)	ι	,	•			
Average vacuum thrust Average vacuum effective Isp Vacuum axial total impulse	lbf sec lbf-sec	166,296 259.75 6,454,599	166,296 259.75 6,454,599	168,072 261.01 6,494,323	1,776 1.26 39,724	1,776 1.26 39,724

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SUMMARY OF PERFORMANCE PARAMETERS (COS-B)

(CONTINUED)

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Unit	Nominal Value	Tag Value	Internal Reconstructed Value	Deviation From Nominal Value	Deviation From Tag Value
1bf sec mru % % 1bf-sec 1bf-sec	9,650 302,47 1.595 93.02 99.71 2,822,434 3,040	9,432 302.41 1.598 91.73 99.71 2,777,874 3,040	9,597* 300.66* 1.584 92.37 99.75 2,777,885 3,187***	-53 -1.81 -0.011 -0.65 0.04 -44,549 147.0	165 -1.75 -0.014 0.64 0.04 11 147.0
	lbf sec mru ຊູ ໃ bf-sec	Unit Value 1bf 9,650 sec 302,47 mru 1.595 % 93.02 % 99.71 1bf-sec 2,822,434	Unit Value Value 1bf 9,650 9,432 sec 302,47 302.41 mru 1.595 1.598 % 93.02 91.73 % 99.71 99.71 1bf-sec 2,822,434 2,777,874	Nominal Tag Reconstructed Unit Value Value Value 1bf 9,650 9,432 9,597* sec 302,47 302.41 300.66* mru 1.595 1.598 1.584 % 93.02 91.73 92.37 % 99.71 99.71 99.75 1bf-sec 2,822,434 2,777,874 2,777,885	Nominal UnitTag ValueReconstructed ValueFrom Nominal Value1bf $9,650$ $9,432$ $9,597*$ -53 sec $302,47$ 302.41 $300.66*$ -1.81 mru 1.595 1.598 1.584 -0.011 % 93.02 91.73 92.37 -0.65 % 99.71 99.71 99.75 0.04 1bf-sec $2.822,434$ $2.777,874$ $2.777,885$ $-44,549$

*Externally Reconstructed **Nominal and Tag values are based on DTO and BET burn times, respectively ***Based on DIGS velocity data ****Latest Propulsion Nominal and Tag Values

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		(COS-B)				
Parameter	Unit	Number of Samples	Mean Deviation From Nominal*	Mean Deviation From Tag	Standard Deviation Nominal	Standard Deviation Tag
Irst Stage		_				•
Liquid Engine System			•			
Average vacuum thrust Average vacuum effective specific impulse	Ìbf sec	1}	1,821 0,176	1,506 -0,004	2,238 0.526	T,749 0,309
Propellant utilization	*	11	-0.020	0.010	-	—
Solid Motors (Sea-Level Ignition)			•			
Average vacuum thrust Average vacuum specific impulse Total vacuum axial impulse	lbf sec lb f-sec	29 29 29	1,117 0,460 11,712	1,189 0,460 11,766	2,446 1.351 33,343	2,450 1.361 33,601
Solid Motors (Altitude Ignition)					•	
Average vacuum thrust Average vacuum specific impulse Total vacuum axial impulse	lbf sec lbf-sec	11 11 11	-1,139 -1.610 -38,425	-1,134 -1.600 -38,221	2,741 1.231 34,847	2,749 1.228 34,884
econd Stage					-	•
Average thrust** Average specific impulse** Average mixture ratio Propellant consumption	16f sec mru %	13 13 13 11	-169 -1.59 0.0020 -0.114	60.7 -1.776 -0.0040 -0.28	161 0.633 0.0093	82.9 0.4246 0.0094

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INTERNAL RECONSTRUCTED PERFORMANCE PARAMETER CUMULATIVE STATISTICS

(CONTINUED) (COS-B)

Parameter	•	Unit	Number of Samples	Mean Deviation From Nominal*	Mean Deviation From Tag	Standard Deviation Nominal	Standard Deviation Tag
Second Stage (Continued)							
Propellant utilization Total steady-state impulse** Total shutdown impulse***	¥ .	% 1bf-sec 1bf-sec		0.028 -28,312 19.3	0.027 -25,500 19.3	29,552 111.8	25,839 111.8

2-18

*Nominal values are based on DTO burn times

******Externally reconstructed

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***Updated based on the latest Propulsion nominal and tag values

TABLE 2-6									
SUMMARY	0F	PERFORMANCE	PARAMETERS	FOR	FIRST	STAGE	LIQUID	ENGINE	
		120 SECONI	DS TO MECO	(COS-	-B)				

Parameter Units Average total 'lbf vehicle altitude thrust*	Ground Test Tag 217,844	Preflight Predicted	Internal Reconstructed	External Reconstructed	Preflight Predicted	Internal Reconstructed	External Reconstructed
vehicle altitude	217,844	217,844	221 660				
	•		221,660	220,753	0	3,816	2,909
Averag <mark>e altitude sec</mark> specific impulse*	291,79	291,79	292.31	290.34	0	0.52	-1.45
Average mixture mru ratio		, •	-	-	-0.01798	-0.01870	• _

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		Marchan	Mean Deviation f	rom Ground Tag	Standard Deviation			
Parameter	Units	Number of Samples	Internal Reconstructed	External Reconstructed	Interna } Recons tructed	External Reconstructed		
Average total vehicle altitude thrust**	lpt	11	2,444	3,118	1,766	1,879		
Average altitude specific impulse**	sec	11	0.007	0.9136	0.365	1,313		
Average mixture ratio shift**	mru	11	-0.01780	-	0.0118	-		

*Averages for vehicle between 120 seconds and MECO **SMS-A not included .

THIRD STAGE SOLID MOTOR PREDICTED PERFORMANCE

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(COS-B)

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. Parameter	Unit	Value
Total Loaded Weight	1bm	1580,33
Propellant Weight	1bm	1438.29
Inert Weight Loss During Burning	lbm	12,35
Burnout Weight (Motor Only)	Ibm	129.69
Propellant Specific Impulse*	Sec .	290,4
Total Impulse*	lbf-sec	417,679
Action Time .	sec	44.8
Nozzle Misalignment	degrees	- 0,00

•	MASS PROPERTIES		
Moment of Inertia	Uni t	Loaded Motor	Expended Motor
Pitch	slug-ft ²	48.32	6.63
Roll	slug-ft ²	49.62	4.29
Center of Gravity**	inc hes aft of the forward attac h flange	16.05	21.80

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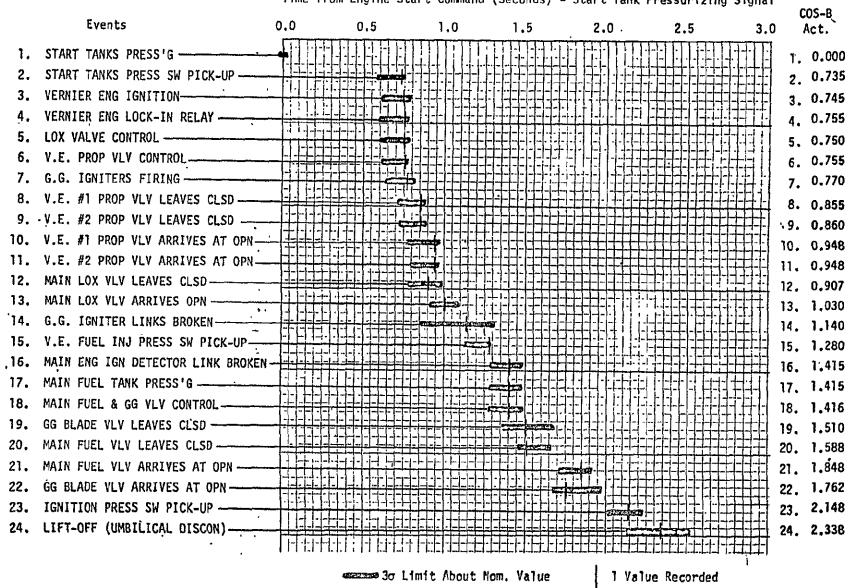
*Values are for vacuum condition and 75°F

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**Measured from the forward face of the 18-inch attach flange

NOMINAL RS-27 START SEQUENCE

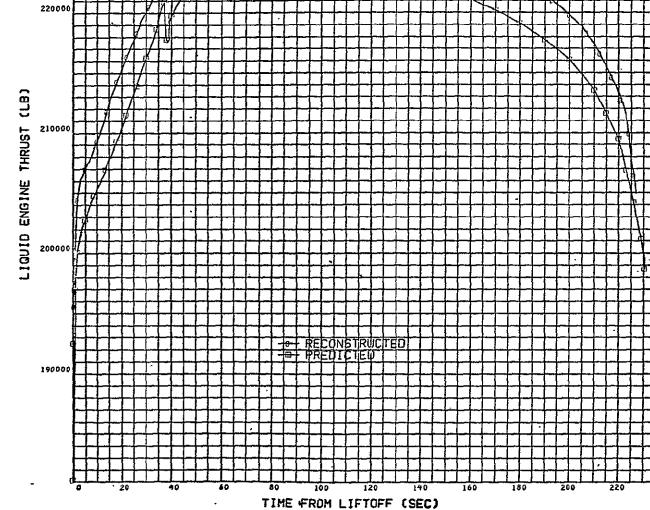


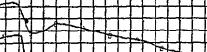
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2-21

Time from Engine Start Command (Seconds) - Start Tank Pressurizing Signal

FIGURE 2-1





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FIRST STAGE THRUST HISTORY (LIQUID ENGINE) DELTA NO. 113

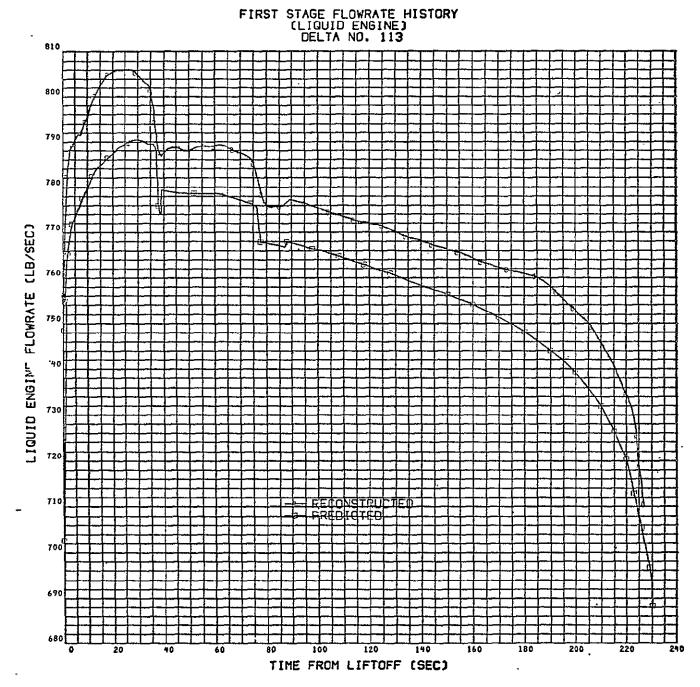
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FIGURE 2-2

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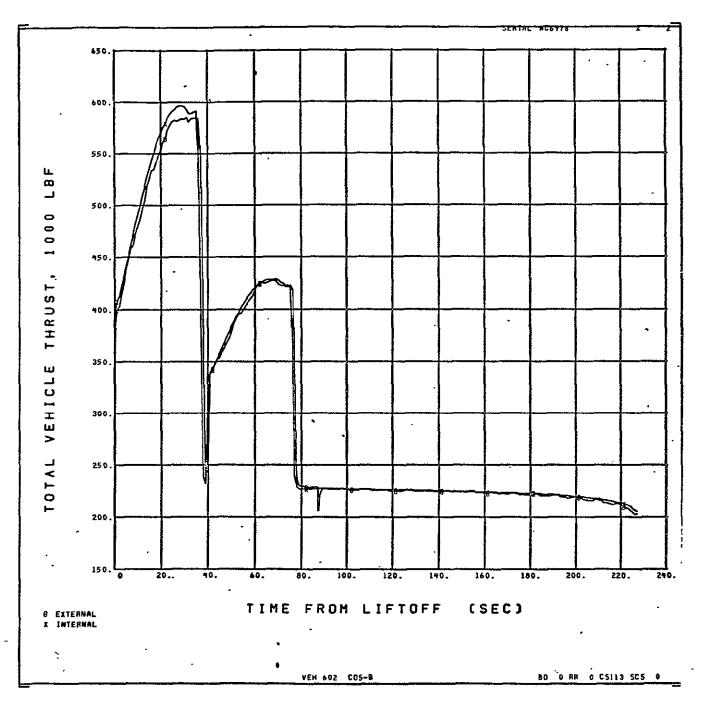


FIGURE 2-4

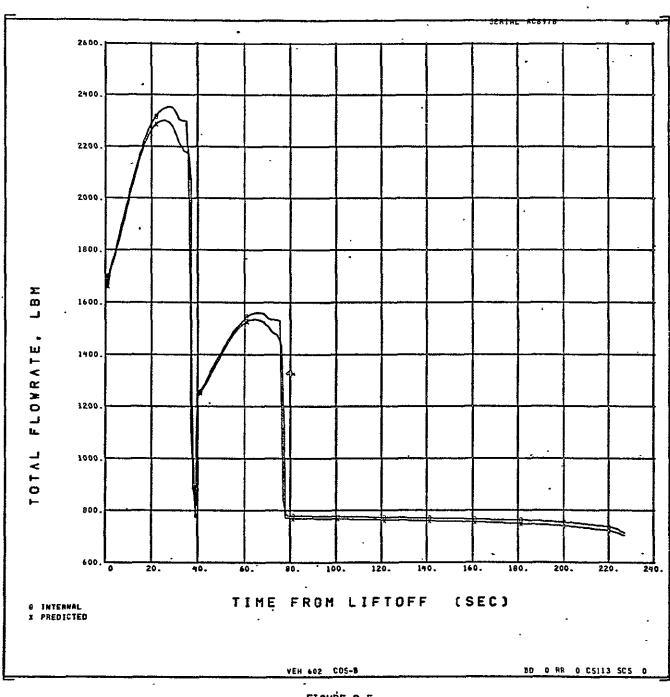


FIGURE 2-5

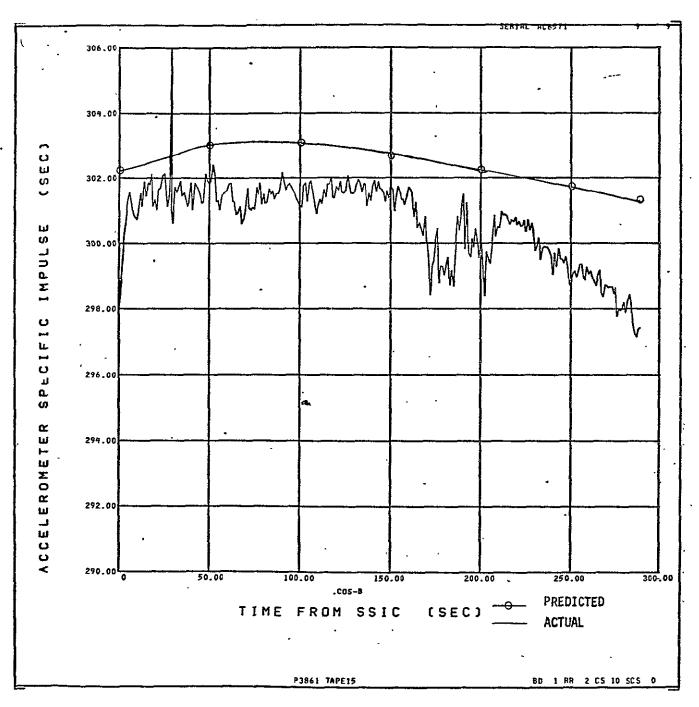


FIGURE 2-6

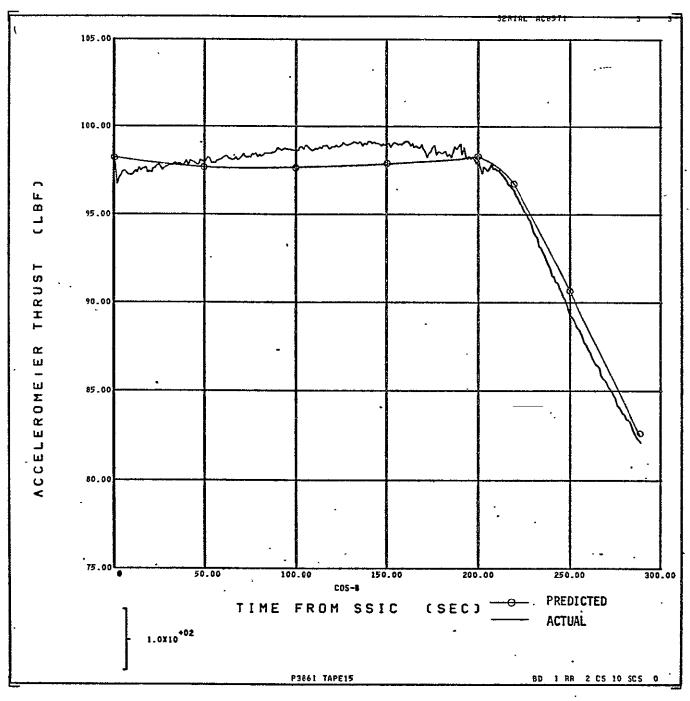
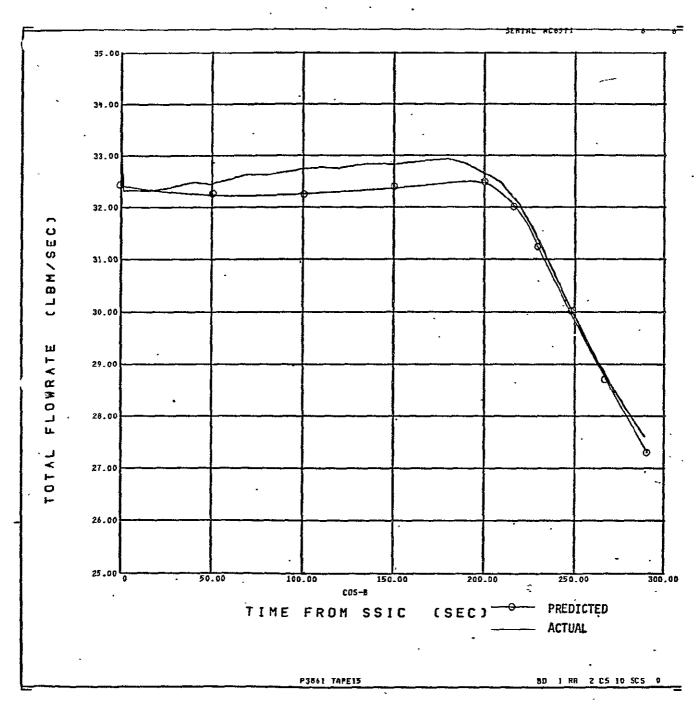


FIGURE 2-7

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Attachment 3 to: A3-262-AM00-M75-509

ATTACHMENT 3:

SECTION 3. GUIDANCE SYSTEM - COS-B MISSION

Section 3

GUIDANCE SYSTEM - COS-B MISSION

The Delta Inertial Guidance System (DIGS) performed its functions properly throughout the COS-B mission. From the observed small off-nominal SECO orbit parameter deviations, the system navigation errors appear to be nominal. Postflight statistics and interpretations of key guidance, navigation, and trajectory parameters are provided in this section.

3.1 ALIGNMENT

The gyro update parameters were observed small and a continuous steady state solution to these existed long before liftoff during the terminal count as shown in Figure 3-2. This means that a minimum of vehicle sway occurred in each body coordinate. The system tracked this motion well since alignment had reached a converged solution. The gyro bias update parameters resolved into the IMU (X, Y, Z) frame are respectively (0.058, 0.007, -0.081) deg/hr.

3.2 CLOSED LOOP GUIDANCE PERFORMANCE

The observed response of the guidance system for the COS-B mission was as expected. Table 3-1 presents the significant mission trajectory event times and attitude errors. Figure 3-1 shows a continuous time history of guidance adjustments in vehicle sequencing time while Figures 3-3 through 3-6 present guidance system time adjustment and steering. As shown in Table 3-1 and the figures, all guidance time adjustments, attitude errors, and guidance steering commands were within the normal ranges. Figure 3-7 show the velocity gained after SECO 1 as a function of time. These can be used to compute actual tailoff impulse. Figure 3-8 presents the second stage thrust axis velocity and shows the change in velocity at third stage separation and ignition. Note that this figure is valid only for changes in velocity (not total velocity) since the range is -1024 to +1024 ft/sec with overflow allowed.

3.3 NAVIGATION AND PERFORMANCE

A total guidance system error can essentially be categorized as residual system errors and system navigation errors. Table 3-2 normally lists the MECO and SECO 1 orbital parameters extrapolated from data reflecting NASA hardpoint (tracking, SECO 1 only), guidance computed (telemetry) and the targeted nominal conditions. However, due to lack of NASA tracking data from before SECO 1 through experimental restart, no valid hardpoint SECO 1 orbital data is available. Errors due to less than perfect mavigation normally can be computed as differences between NASA and telemetry data. The total guidance system performance as of SECO 1 normally can be observed in the difference between NASA hardpoint and the targeted (DTO) data. Even though no valid NASA hardpoint data is available, from the observed data presented in Table 3-2, it is evident that DIGS performed well throughout the second stage burn.

3.4 ANGLE OF ATTACK HISTORIES

A reference angle-of-attack profile was generated from PCM inertial velocity vector by subtracing the atmospheric rotational velocity due to the earth rate and transforming the resulting relative velocity vectory_into the body coordinates using the T^C matrix. Note that the angle-of-attack values include the wind velocity effects which were measured prior to launch. The wind velocity vector was resolved into body coordinates and accounted for prior to computing the angles of attack. The true pitch, yaw and total angle-of-attack are defined from the wind coorected velocity vector in body coordinates using the equations

$$\alpha = \tan^{-1} (V_{ZRB}/V_{XRB})$$

$$\beta = \tan^{-1} (-V_{YRB}/V_{XRB})$$

$$\alpha^* = \tan^{-1} (\sqrt{V_{YRB}^2 + V_{ZRB}^2}/V_{XRB})$$

Figures 3-9 and 3-10 provide the angle-of-attack histories up to 240 seconds of flight.

3.5 EXPERIMENTAL RESTART

From the guidance standpoint, no significant events occurred during the open-loop experimental restart (TM data was very poor during this period), except for the long burn time. This is discussed further in the Propulsion and System Performance sections of this report.

Table 3-1.

Cos-B

- MAJOR EVENT TIMES AND VEHICLE INERTIAL ATTITUDE ERROR

Event	Time (Sec)	Vehicle Attitude From Nominal (Deg)		Event	Time	(Sec)		le Attitu Iominal (1	
Liftoff	0	Δφ = 0.209 Δθ = 0.063 Δψ = 0.039	•	Start Coast Guidance #1	Nominal Actual	630 ,000	Δφ Δο Δψ	· No PCM	date
First-Stage Guidance Initiation	Nominal 125.000 Actual 125.232	Δφ = 0.343 Δθ = 2.206 Δψ = -1.559	۰.	Stop Coast Guidence #1	Nominal Actual	680.000	Δφ Δ0 Δψ	= No PCM	Date
MECO (DIGS Sensed)	Nominal 228.061 Actual 227.381	$\Delta \phi = -0.045$ $\Delta \Theta = 1.287$ $\Delta \psi = 0.264$	•	Start Coast Guidance #2		2975.000 2973.395	Δφ Δθ Δψ	= 0.038 = 0.066 = 2.143	,
Second-Stage Guidance Initiation	Nominal 280.000 Actual 279.524	$\Delta \phi = 4.957$ $\Delta \Theta = 0.409$ $\Delta \psi = 0.199$	•	Stop Coast Guidance #2		3025.000 3023.204	Δ¢ Δθ ΔΦ		!
SECO 1 (DIGS Sensed)	Nominal 531.075 Actual 530.981	Δφ = -6.614 Δθ = 2.135 Δψ = -0.085			OF POOR QUALITY				

3-4

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Table 3-2

ORIGINALI PAGE IG OF POOR QUALITY				COS-B ORB	ITAL DATA				
IAL PAG OR QUAL	Trajectory Point	Trajectory Type	Apogee Altitude [®] (n.mi.)	. [.]	Perigee Altitude [#] (n.mi.)	Δh _p (<u>n.ml.</u>)	Inclination (deg)	Δ1 (<u>deg</u>)	ΔV (<u>ft/sec</u>)
KLIT BI B	MECO	Targeted Nominal	103,687	• 0	-2608,49	0	89.5930	· 0	0
,		Telemetry (Guidance Computed)	106,104	2.417 P	-2585.08	23.41	89.6103	0.0173	192 .593
μ, .	8EC0 1	Targeted Nominal**	238.710 +1,660	0	91,849 +2,071	·0	89.8687 <u>+</u> 0.041	O ,	0
		Telemetry (Guidance Computed)	237.842	-0,868	91,615	⊷0 ₄23 []] ∔	89,8688	0.0001	-1.892
		NASA (Hardpoint Data)		CO 1 data a tal burn SE		o lack of (tracking prior	to SECO a	2

* Based on earth radius of 3439.62 n.ml.

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^{so} Indicated tolerances are root sum square of 30 contributions to orbit parameter dispersions. The value of Δt^{adj} calculated at the beginning of second stage guidance was -1.890 seconds.

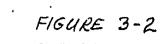
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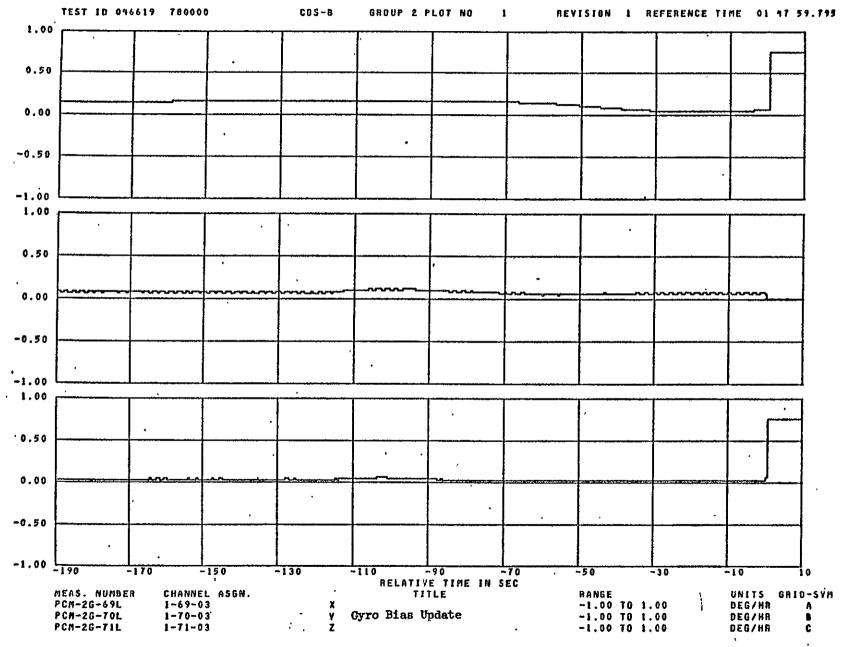
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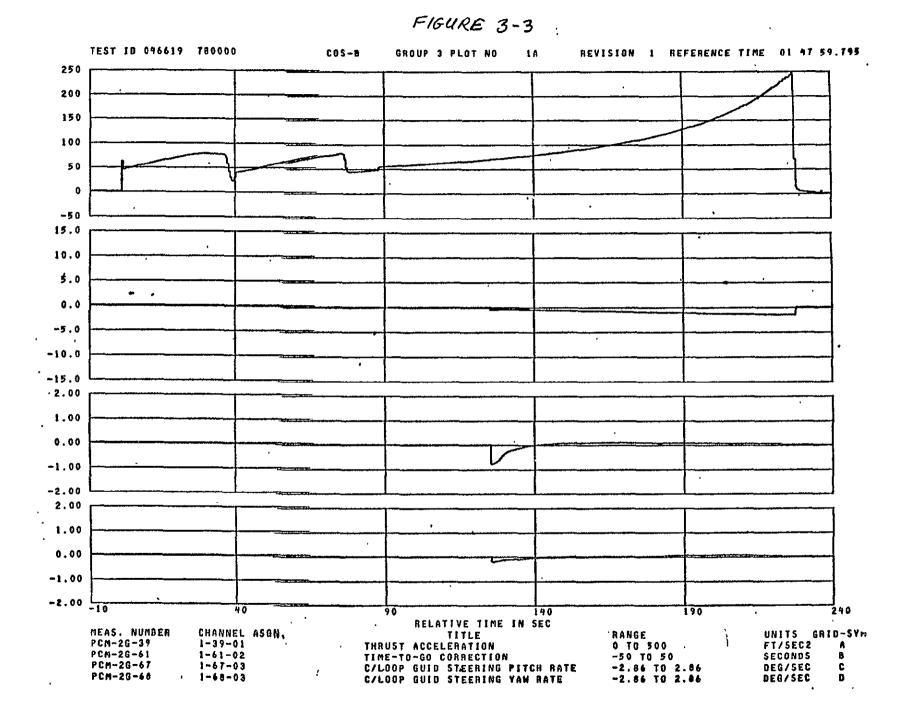
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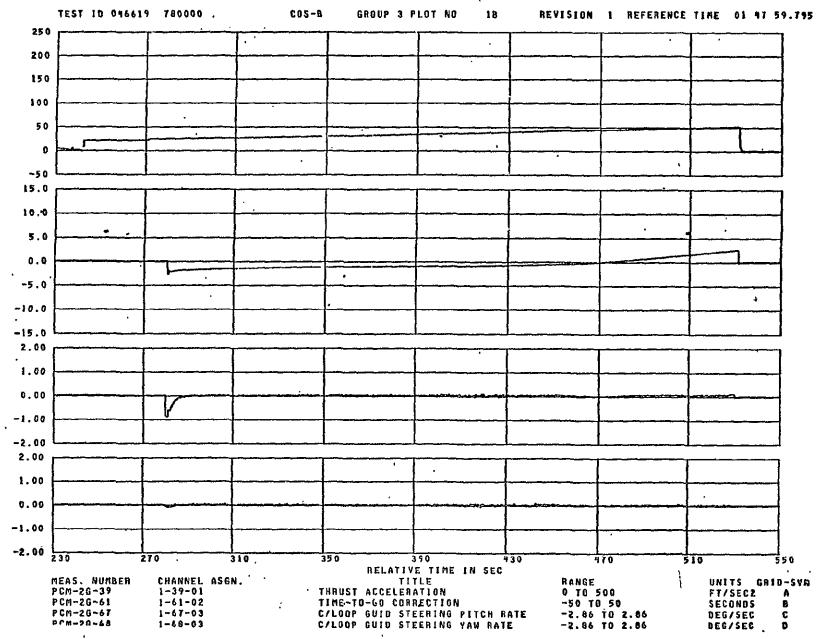
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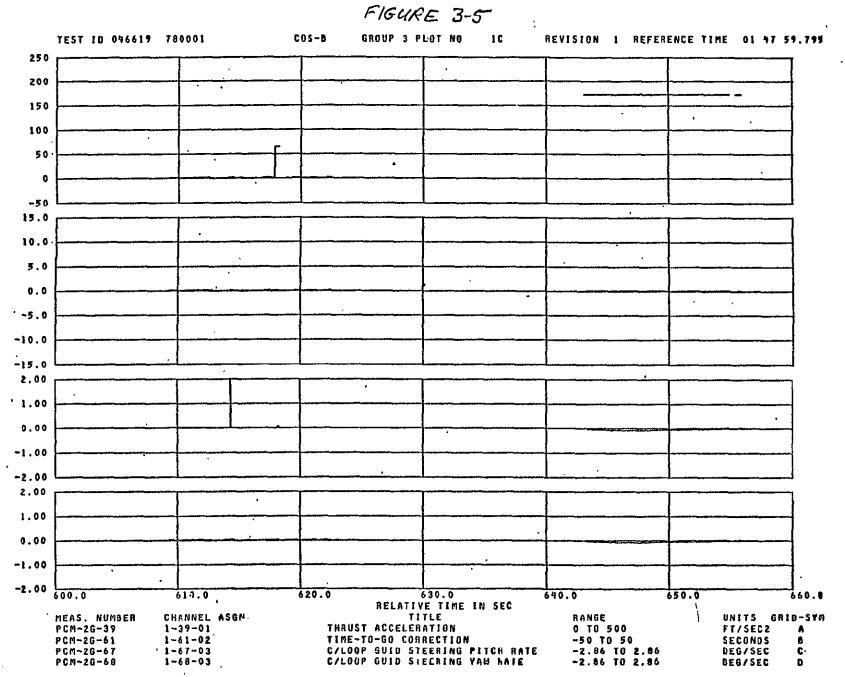


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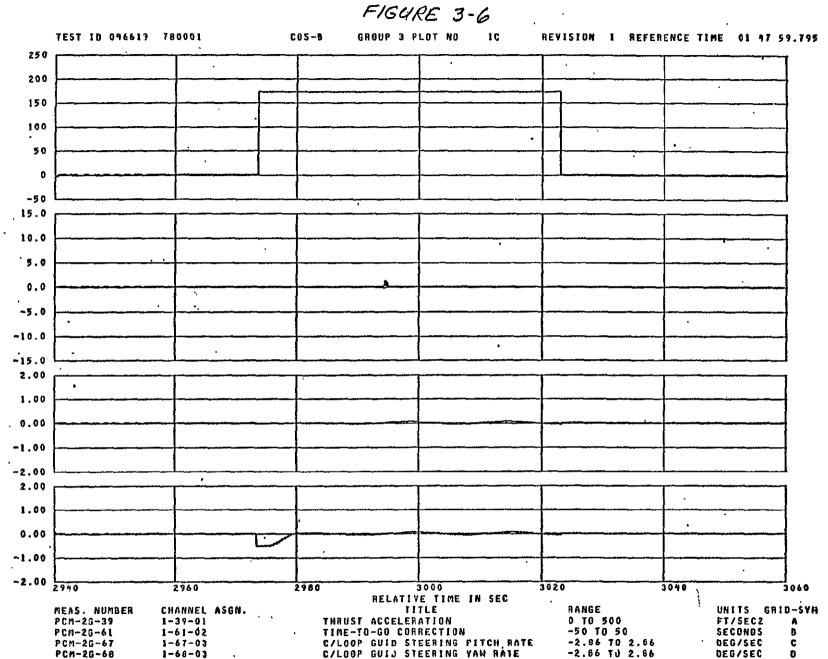
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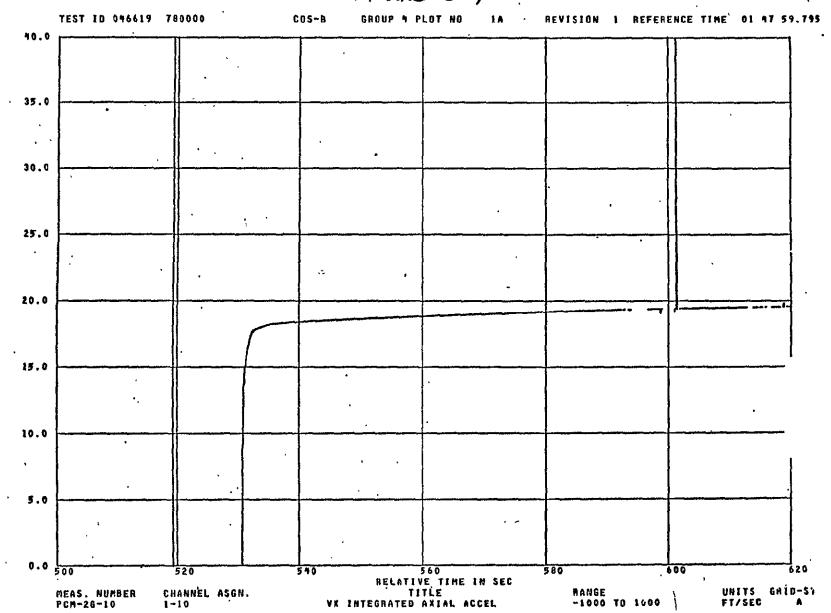
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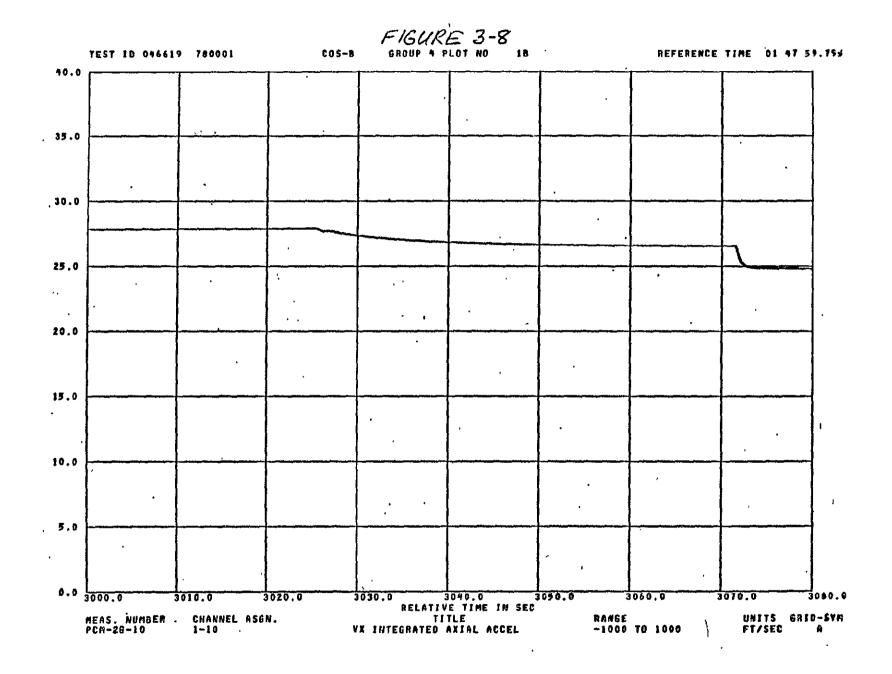
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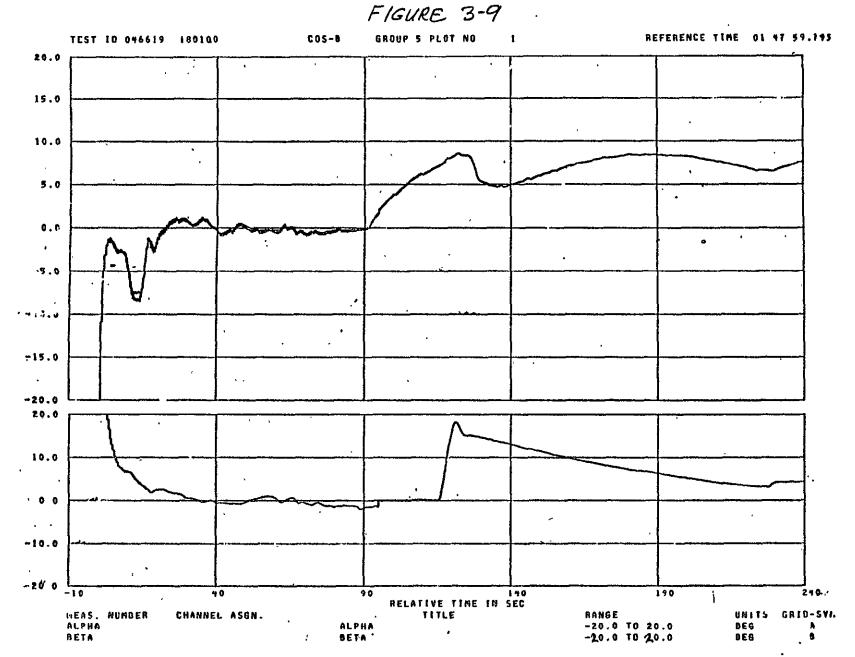


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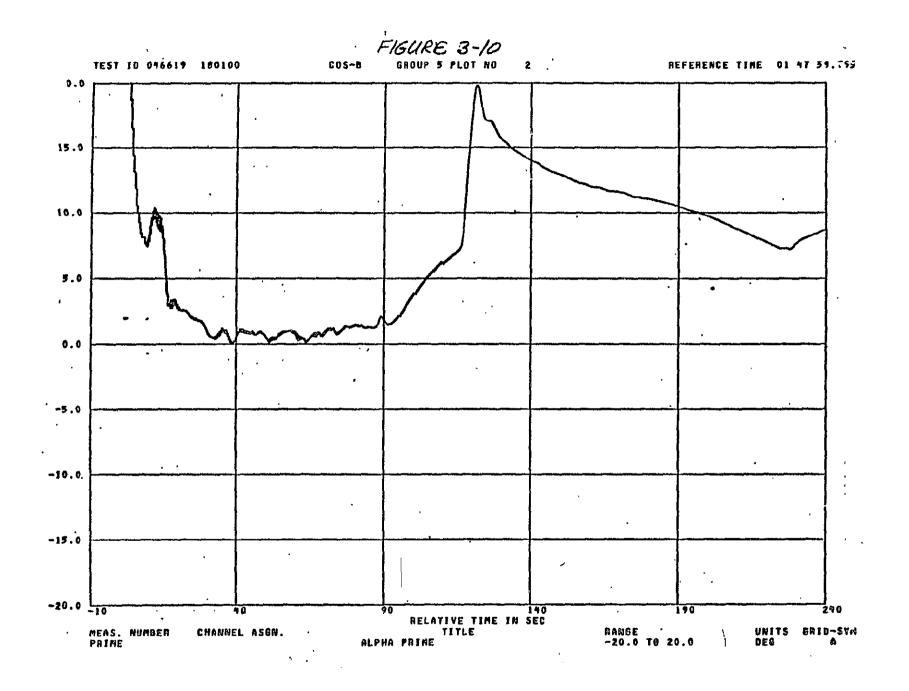
FIGURE 3-7

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Attachment 4 to: A3-262-AM00-M75-509

ATTACHMENT 4:

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SECTION 4. FLIGHT CONTROL SYSTEM - COS-B MISSION

FLIGHT CONTROL SYSTEM - COS-B

4.0 FLIGHT CONTROL SYSTEM

All flight control systems operated nominally throughout the first and second stage flight for the COS-B mission. First-second and second-third stage separations occurred satisfactorily. This was the first DIGS mission to use a modified second stage propulsion fuel manifold system. An unexpected pogo resonance of significant duration was observed during powered flight. This anomaly had no impact on the successful completion of primary and secondary mission objectives. Maneuvers to shield the payload from the sun and to reorient the vehicle prior to third stage separation were adequately performed. The nitrogen gas usage through third stage separation was well within the predicted three-sigma deviations.

4.1 FIRST STAGE

The first stage control system maintained vehicle stability and performed the required functions throughout first stage flight.

4.1.1 First Stage Statistical Record

Table 4-1 provides a compilation of some of the control system characteristics for this flight and the corresponding statistics generated from past flights.

4.1.1.1 Thrust Misalignment

The first stage main engine positions required to direct the thrust vector through the vehicle center of gravity are shown in Figures 4-1 and 4-2 for liftoff and MECO, respectively. Data points of previously flown 2914 vehicle configurations and the mean values applicable for each plot are also shown. Note that the engine positions for COS-B were within one-sigma deviations from their respective mean values.

4.1.1.2 Maximum Aero Moment Region

Peak roll rate and pitch attitude error with their respective peak engine deflections occurred at the maximum dynamic pressure time of about T+36 seconds. All other peak values of attitude errors, rates and engine deflections occurred between T+67 and T+79 seconds. Large engine deflections prior to 20 seconds were primarily due to programmed pitch maneuvers. Figure 4-3 shows that the peak pitch and yaw engine deflections after 20 seconds were -1.2 and 1.5 degrees, respectively. These deflections were primarily caused by the combined effects of wind shear and dynamic pressure.

4.1.1.3 Roll Moments

External roll moments were computed at liftoff, maximum dynamic pressure, MECO and vernier engine solo times of flight. The roll moments shown in Table 4-1 are the total external moments (includes thrust misalignments and aerodynamics) which are computed from the vernier engine deflections. A vernier engine thrust of 1000 pounds was used for all calculations.

4.1.1.4 Peak Vernier Solo Engine Deflection

Rates and attitude errors from just before MECO to just after stage II (second stage engine) ignition are shown in Figures 4-4 and 4-5. Note that attitude errors and body rates present at MECO are zeroed out by the vernier solo control system prior to first-second stage (I/II) separation. The peak vernier engine deflections occurred shortly after MECO. The largest deflection was in the yaw channel due to the large attitude error existing at MECO in that plane.

4.1.1.5 Maximum Guidance Rate Commands

The maximum guidance rate commands occurred at guidance initiation (T+125 seconds). The pitch command was very close to the mean value observed over 12 missions. The yaw command of -0.20 deg/sec was less than one standard deviation from its mean value.

4.1.1.6 Conditions Before and After First-Second Stage Separation

Rate and attitude errors in the pitch and yaw planes were essentially zero prior to stage I/II separation. The roll rate and attitude error before separation were close to mean walues. Figures 4-4 and 4-5 show the rate and attitude error changes during separation were very slight indicating a smooth separation event.

4.1.2 First Stage Control System Response

4.1.2.1 Vehicle Bemding

The shock of liftofff excited the first and possibly the second bending mode. Figure 4-6 shows the pitch and yaw angular rates while Figure 4-7 shows the DAC outputs following liftoff. Second mode bending oscillations can be observed in the angular rate data. Due to the heavy attenuation of these high frequencies by the rate and attitude feedback digital filters, the DAC output trace shows only the first mode oscillations. As opposed to most DIGS missions, the first mode oscillations were larger in yaw than pitch and were quite mild. The first bending frequency was ≈ 2.3 Hertz at liftoff while the predicted was 2.0 Hertz. The second mode frequency was $^{4.5}$ Hertz compared to $^{4.3}$ Hertz predicted. During wernier engine solo, starting immediately after MECO, bending transients were observed in pitch and yaw. The DAC output transients shown in Figure 4-8 include ffirst bending mode oscillations at 4.8 Hertz versus the predicted frequency of $^{4.4}$ Hertz. Similar bending mode oscillations have been seen on prior missions and cause no problems to the control system.

4.1.2.2 Pogo Resonance

Just prior to MECO, Pogo resonance effects sensed by the rate gyros were about 2 deg/sec peak-to-peak in roll and about 1.5 deg/sec peak-to-peak in pitch and yaw (Figure 4-4). The Pogo resonant frequency was approximately 19 Hertz. Pogo resonance also occurred earlier in flight (T+140 seconds) as shown in Figure 4-9. The resonant frequency at that region of time was about 21 Hertz. Note that as expected, attitude error history of that figure show no trace of these high frequency oscillations.

4.1.2.3 Roll Limit Cycle

Roll limit cycling was observed in the attitude error, rate and vernier engine position traces from solid drop until MECO. The rate and attitude error histories of Figure 4-9 show that the oscillations were at a frequency of 0.35 Hertz. Peak-to-peak amplitudes were approximately 1.0 degree per second in rate and 0.5 degree in attitude error. The limit cycle is due to the nonlinearities in the vernier engine linkage and actuator combined with DAC granularities. All past DIGS flights have exhibited this limit cycle.

4.2 SECOND STAGE

The second stage control systems maintained stability and satisfactorily controlled the vehicle throughout powered and coast phase flight.

4.2.1 Second Stage Statistical Record

Table 4-2 provides a compilation of some of the control system characteristics of this flight.

4.2.1.1 Second Stage Thrust Misalignment

At ignition, all attitude errors and body rates as well as pitch and yaw thrust misalignment for the SSPU were well within one-sigma of the mean values recorded for the TRW second stage. An increase in pitch thrust misalignment at SECO 1 over that observed at ignition was observed. However, these (as well as yaw) misalignments were less than one standard deviation from the mean values. Engine positions required to counter the disturbing moments generated by the thrust misalignment errors are shown in Figures 4-10 and 4-11 for the first ignition and cutoff times, respectively. As was done for the first stage engine, data from prior TRW missions and the mean values are also shown. Note that based on 14 samples, there exists a general tendency of increased misalignment effect at SECO compared to engine ignition.

4.2.1.2 Roll Impulse at Fairing Jettison

The roll impulse imparted to the second stage by the successful separation of the fairing was 0.99 foot-pound-seconds clockwise looking forward. The induced

roll rate transient was +0.15 degree per second. This roll impulse was within one-sigma deviation from the mean value. Figure 4-12 presents the relative sequencing of roll attitude error and rate transients with roll control jet activations and triaxial accelerator excitations. Despite an apparent second excitation of the triaxial accelerometer, the lack of the usual high frequency content in this data plus the analysis of the jet actuation and body roll rate data made vehicle recontact by a fairing section doubtful.

4.2.1.3 Powered Flight Roll Moment

From the control jet actuation data, the gas impulse used to counter the external roll moments induced during second stage engine burn was 28 lb-sec. This impulse was calculated using an assumed jet on-time of 13 milliseconds for a 20 millisecond "on" signal. Shortly after ignition, a clockwise external roll moment developed. This moment changed direction at T+340 seconds and remained counterclockwise until SECO. The average roll moment was about one signa higher than the mean for light quartz nozzle liners.

4.2.1.4 SECO Transients

Pitch and yaw switchlines with 0.5 degree deadzone were used at second engine first cutoff. In the roll axis, switchlines with a deadzone of 6.5 degrees were used. Impulse usage to reduce or maintain attitude errors within the switchlines were within one-sigma deviations from mean values for the pitch and yaw axes. The unusually large roll rate transient (1.6 deg/sec) is attributed to the absence of a rate deadzone of the spinup switchlines. The roll impulse was about two-sigma higher than the mean value for 20 data samples.

4.2.1.5 Ratio of Actual to Predicted Acceleration

The roll-pitch orientation meaneuvers for sun shielding (see Figures 4-13 and 4-14) were used to determine to actual control acceleration capability of the vehicle in the two planes. During the zeroing of the roll rate command, a twojet, full-on condition prevailed. During this period, the roll acceleration was 3.08 deg/sec² which was almost exactly the predicted nominal. For a similar 1 jet full-on period, the pitch acceleration was 0.48 deg/sec² (7 percent

4.5

higher than the predicted nominal). The actual value calculations were based on nominal thrust and mass property conditions. These accelerations are within one-sigma deviations of the mean achieved-to-predicted acceleration ratios.

4.2.2 Coast Control System

4.2.2.1 Coast Control System Impulse Usage

Figure 4-15 shows the COS-B coast control system impulse usage as a function of time. The predicted mean and three-sigma high usage from Reference 4-1 are also shown. Actual usage was much less than that of the predicted mean through third-stage separation. The actual impulse usage (solid curve) was computed by using the combination of observing the achieved body rates (PCM data), NTOT (software data of total jet firing counts) and nitrogen bottle pressure data. The primary source of the difference is the much lower gas actually used for the convergence to the fine switchlines at SECO 1 and for the coast guidance periods. Predictions assumed ultra conservative rate commands corresponding to the pitch and yaw rate ledges for these events.

4.2.2.2 Coast Control Limit Cycling

Periods of coast control limit cycling was observed at various times of flight. Closed loop limit cycles just prior to stage II-III separation were present in the pitch and yaw axes. The frequencies of the limit cycles were about 0.07 Hertz. Open loop (without guidance) limit cycles developed shortly after the second burn of the second stage engine. These frequencies appeared to be more than an order of magnitude lower (0.003 Hertz) than those with guidance.

4.2.2.3 Pogo Resonance

On COS-B, the propulsion fuel manifold system was of a modified configuration. About 150 seconds after second stage engine ignition, pogo resonance started to develop. By T+425 seconds, the resonance grew to 1 deg/sec peak-to-peak in yaw and roll whereas in the pitch axis, the magnitude was about 2 deg/sec. The frequency initially was about 100 Hertz and increased with time to 130 Hertz. From F/M data, peak magnitudes were observed when the resonance was at 125 Hertz.

Figure 4-16 shows the effects of foldback due to the difference between the increasing pogo resonant frequencies and the telemetry data sampling rate of 25 per second. Note that, as expected, none of the high frequency oscillations are observable in the filtered attitude error data of Figure 4-17. The resonance did not hamper satisfactory second stage operation and subsequent successful mission completion.

4.2.2.4 Third-Stage Separation Transients

Angular rate and attitude error transients were observed in all axes following third stage spinup and separation (Figures 4-18 and 4-19). The roll transients are due to: (1) the impulse required to break the spin table retention cord, (2) the roll-control-moment correction effect, and (3) the spin table bearing friction. This friction increases when the spin table petals fully open at the height of the spin and the crush blocks make contact with the spin rockets. The shock of the contact and of the detonation of the separation bolts cause the pitch and yaw transients shown on the figures. Also shown in the figures are rate and attitude error transients resulting from impingement effects due to third stage engine ignition.

The spin rate was 47.1 rpm versus the predicted 45.7 rpm. To counter the disturbing moments and suppress the separation transients, a total gas impulse of 73 pound-seconds was used. The above transients and gas usage were similar to those achieved on prior missions and caused no problem to the control system.

4.2.2.5 Experimental Restart

An experimental restart of the second stage engine was performed. Data dropout during most of this flight period made a thorough analysis impossible. This burn commenced after about 16 seconds of ullaging and continued on to fuel depletion about 29 seconds later. One cycle of an oxidizer tank sloshing oscillation occurring just prior to SECO 2 was observed. The oscillation frequency was about 1.5 Hertz (predicted was 1.4 Hertz). Oscillations like these for the ated second stage in the powered flight mode were observed on prior ons and are not detrimental to the satisfactory performance of restart

guidance. After SECO 2, the desired switchover to pitch and yaw bang-bang control was clearly evident from flight data. The SECO 2 transients of the depletion burn were relatively mild. A gas impulse usage of 2.3 lb-sec was spent during the burn for control moment purposes.

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TABLE 4-1

FIRST STAGE CONTROL SYSTEM PARAMETERS

COS-B

			CO2-B				
PARAMETER	TIME OF FLIGHT		VALUE		MEAN	STANDARD DEVIATION	SAMPLE NUMBER
				. 1			1 .
hrust		Pitch	<u> </u>	deg	13	•09 ·	10
lisalignment		Yaw	.70	, deg	.45	•29	10
Fhrust	MECO	Pitch	.18	deg	.16	:09	11
Misalignment		Yaw	•54	deg	•38	.20 -	11
Peak Attitude Error		Pitch	.85	deg	,12	.87	13
		Yaw	1.0	deg	.24	.86	13
	Maximun	Roll	.62	deg	.20	•58	10
Peak Rate	Aero	Pitch	-1.2	deg/sec	-1.1	.16	13
		Yaw		deg/sec	.10	.64	13
	Moment	Roll	.8	deg/sec	•36	•45	10
Peak Engine		Pitch	-1.15	deg	1.5	1,4	13
Deflection	-	Yaw	-1.47	deg	13	1.6	13
	••••••••	Roll	8.4	deg	-3.1	11.6	10
Equivalent Roll Moment (External)	Liftoff		575	ft-lb		252	17
	Max Q		-959	ft-lb	209	1315	9
	MECO		210	ft-1b	192	121	13
	Vern. Solo		55	ft-1b	14	174	13
Peak Vernier Engine	Vernier	Pitch	18	deg	1.7	2.1	12
	Solo '	Yaw		deg	-14.6	5.5	12
Deflection		Roll	-11 -3.8	deg	.61	2.1	13
Maximum		Pitch	75	deg/sec	78	.31	13
Guidance Rate Command	Initiatiom	Yaw	20	deg/sec	0022	•24	<u>13</u> 13
Attitude . Error		Pitch	0	deg	.0073	.043	15
	MECO	Yaw	0	de <i>r</i> ,	.021	.030	15
	Plus 8 Sec	Roll	•35	deg	.05 8	•30	15
Rate	- (Before	Pitch	0	deg/sec	-,0003	,0090	15
	Separation)	L	0	deg/sec	0007	.0026	15
		Roll	•15	deg/sec	043	.18	15
Rate Change	First-	Pitch	.02	deg/sec	.0085	.056	15
Due To	Second	Yaw		deg/sec	00053	070	15
Separation	Separation	Roll '	•05	deg/sec	.011	.070 .18	15

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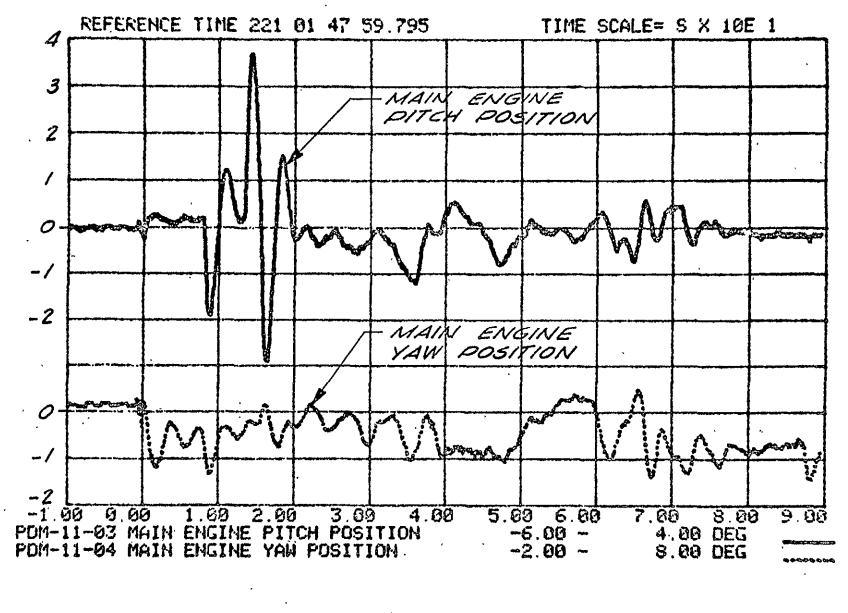
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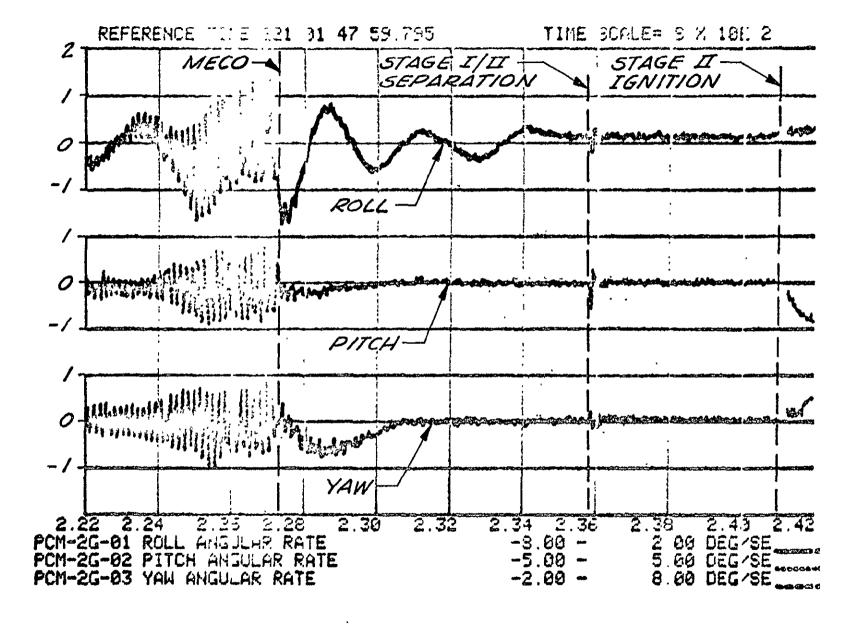
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MAIN ENGINE POSITIONS AT LIFTOFF

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FIGURE 4-3

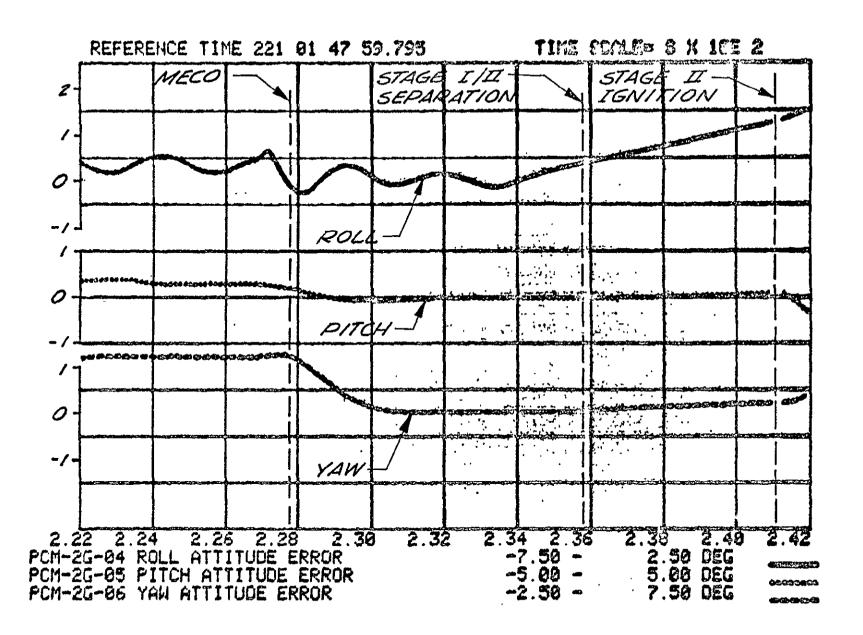


ANGULAR RATES FROM MECO TO STAGE I IGNITION

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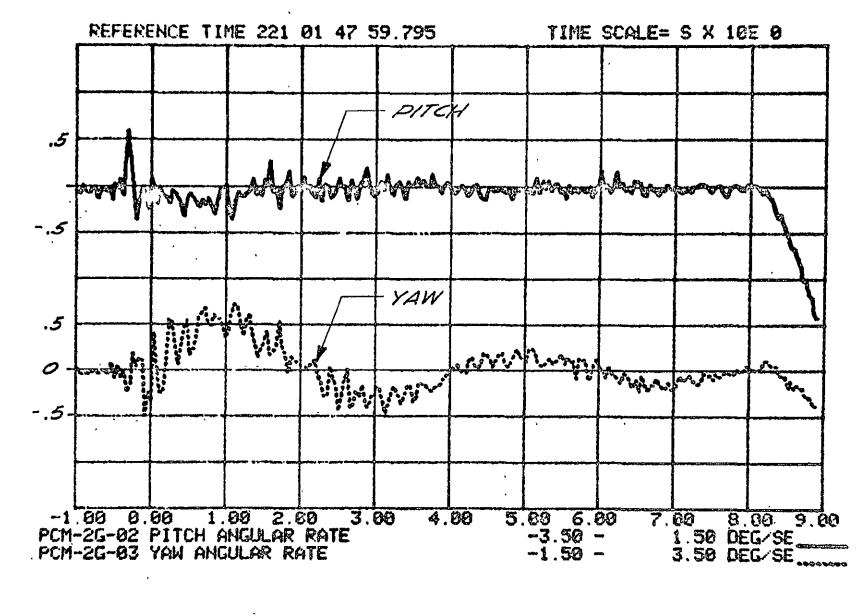
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EIGURE 4-4



ATTITUDE ERRORS FROM MECO TO STAGE I IGNITION

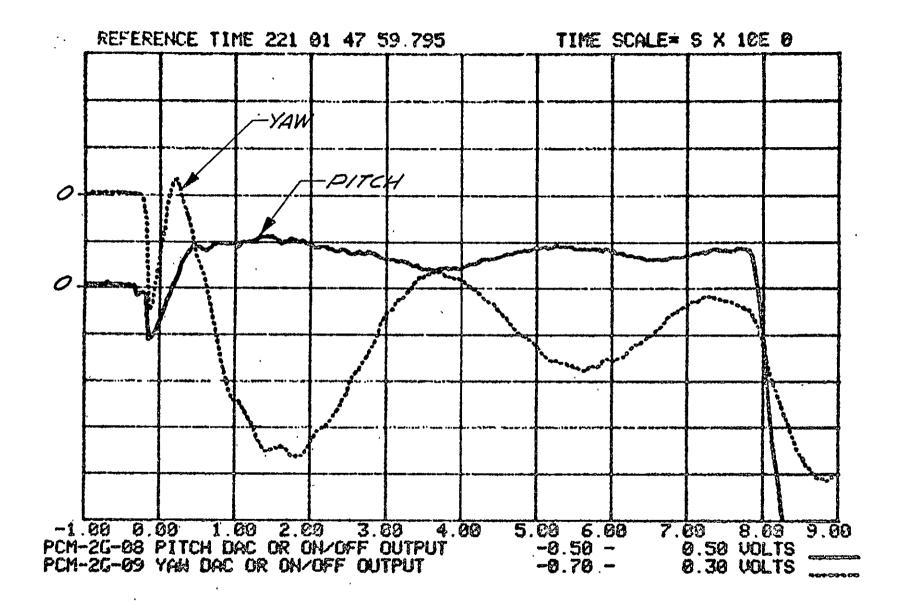
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ANGULAR RATES AT LIFTOFF

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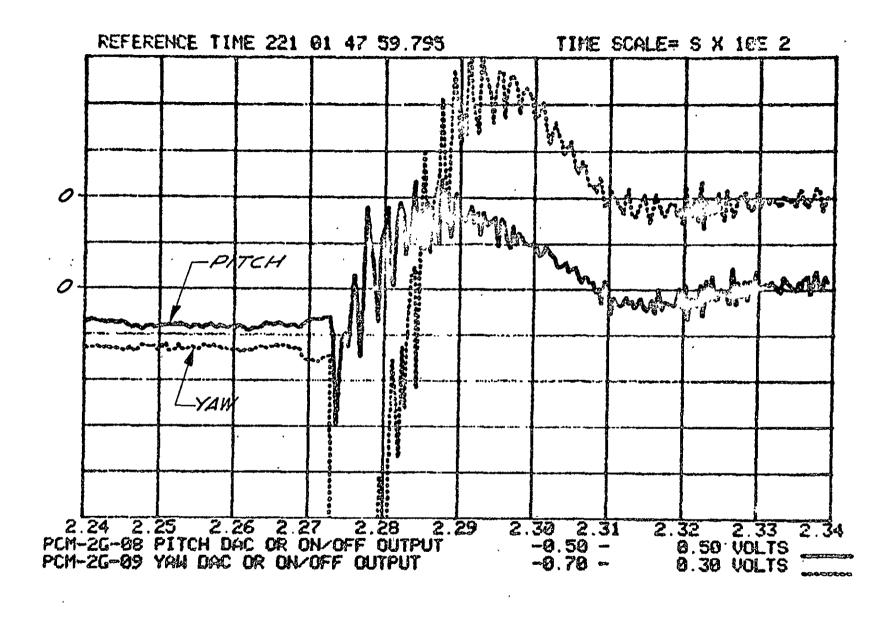
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DAC OUTPUTS AT LIFTOFF

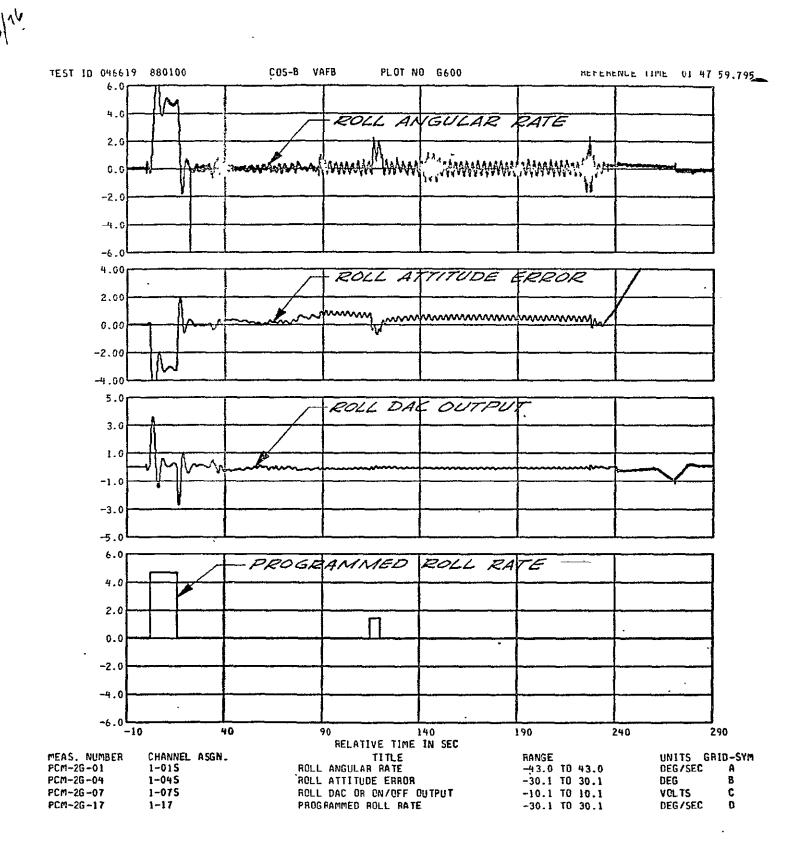
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DAC OUTPUTS AT MECO

CIGURE 4-8



ROLL AXIS PARAMETERS DÜRING FIRST STAGE FLIGHT

FIGURE 4-9

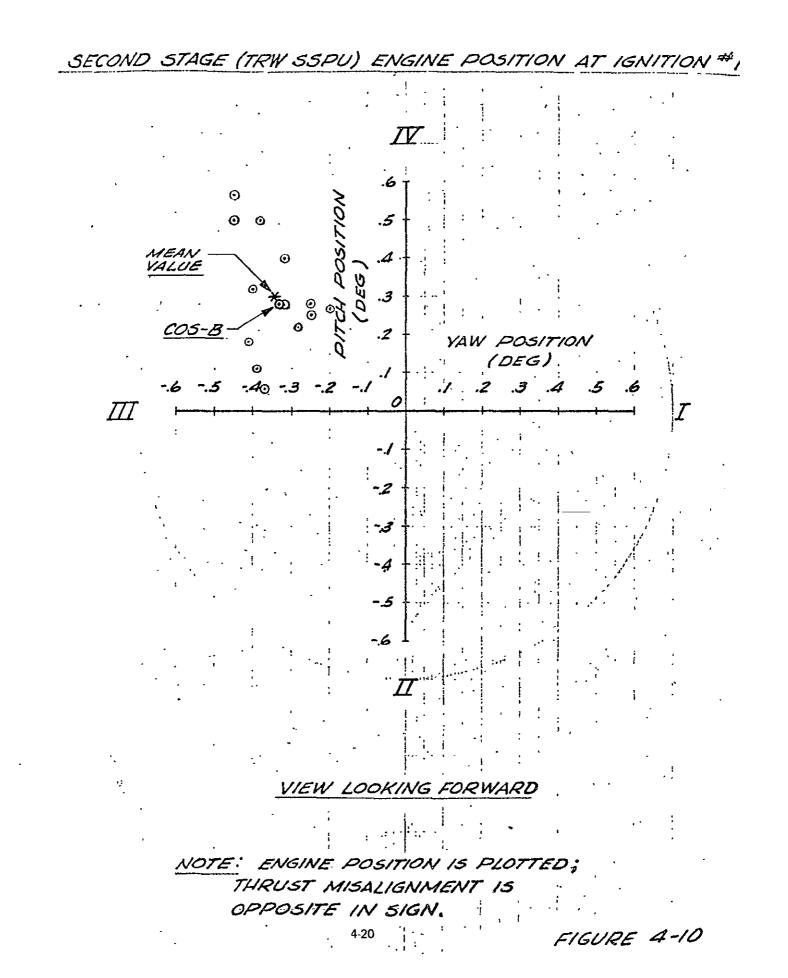
TABLE 4-2

SECOND STAGE CONTROL SYSTEM PARAMETERS COS-B

PARAMETER	TIME OF FLIGHT		VALUE		MEAN	STANDARD DEVIATION	SAMPLE NUMBER
Attitude Error	Second Stage	Pitch Yaw Roll	.10 .20 1.25	deg deg deg	.69 .06 .05	1.1 .21 .72	<u>14</u> <u>14</u> <u>14</u>
Rate	First Ignition	Pitch Yaw Roll	0 0 .15	deg/sec deg/sec deg/sec	.26 . .00 .00	.38 .12 .09	<u>14</u> <u>14</u> <u>14</u> <u>14</u>
Thrust Misalignment	Second Stage First Ignition	Pitch Yaw	28 .33	deg deg	30 .34	.15 .079	<u>14</u> 14
Thrust Misalignment	SECO 1	Pitch Yaw	- <u>40</u> -33	deg deg	42 .41	.18 .10	14 14
Roll Impulse	Fairing Jettison		• •99	ft-lb-sec	71	3.28	12
Average External Roll Moment	Powered Flight		32	ft-lb	15	.17	8
Average [External Roll Moment]	Powered Flight		•32	ft-lb	.21	.11	8
Roll Gas Usage	Powered Flight		13.1	lb-sec 100_sec	7.7	4.1	. 8
SECO Impulse	SECO	SECO # Pitch Yaw Roll	1 2 7.3 - 3.2 - 3.7 -	3 lb-sec	1 2 14.2 - 8.9 - 1.4 -	1 2 10.2 - 5.7 - 1.2 -	11 11 20
Ullage Moment Disturbance Impulse	Prior to Restart		N/A	<u>lb-sec</u> sec	.	-	-
Ratio of Actual to Predicted Angular Acceleration	Coast Phase	Pitch Yaw Roll	 <u>1.07</u> 	N.D.	1.1	.13 	15 - 8

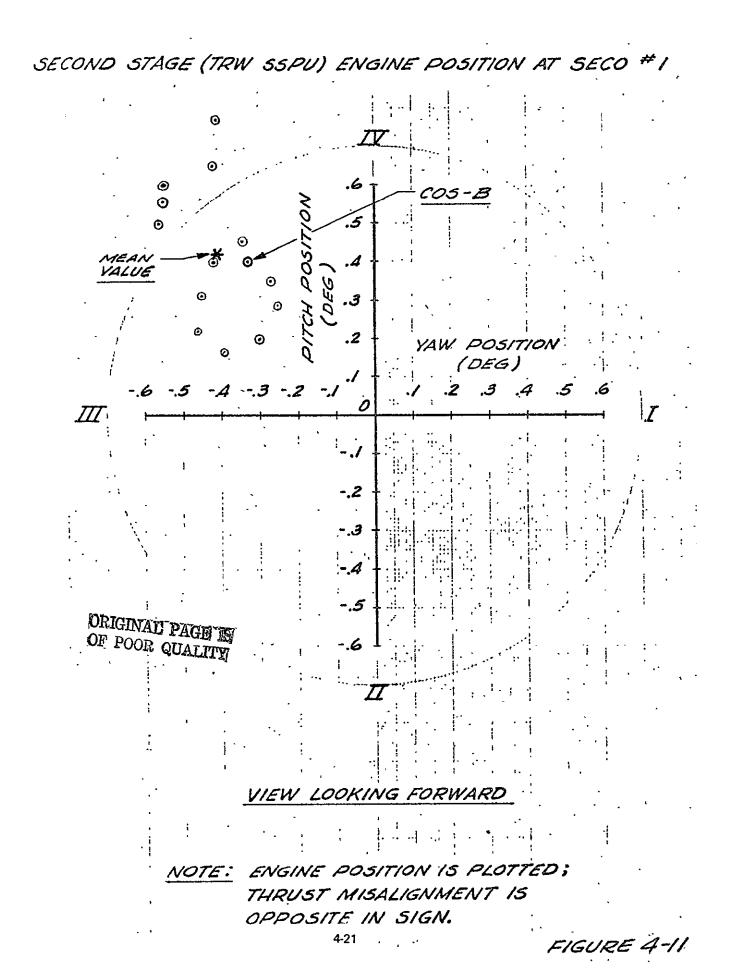
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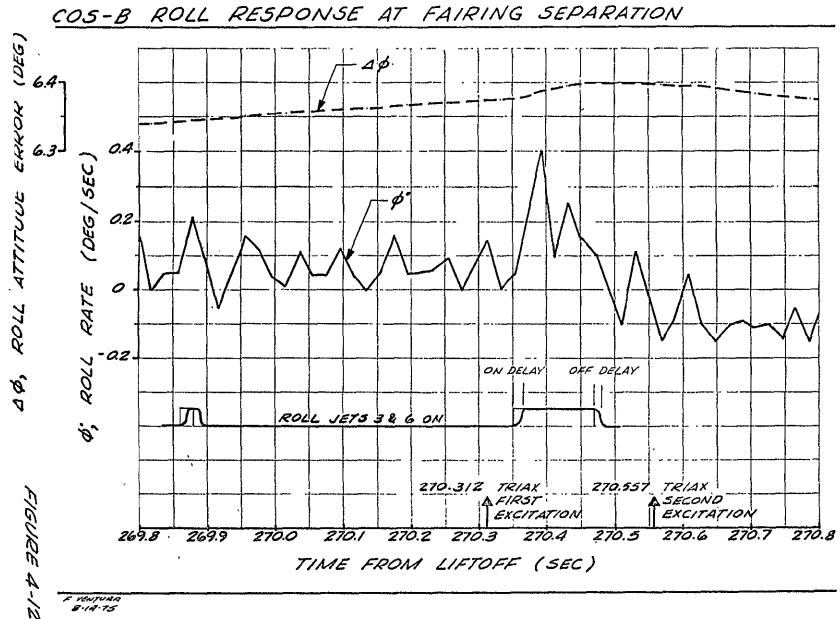
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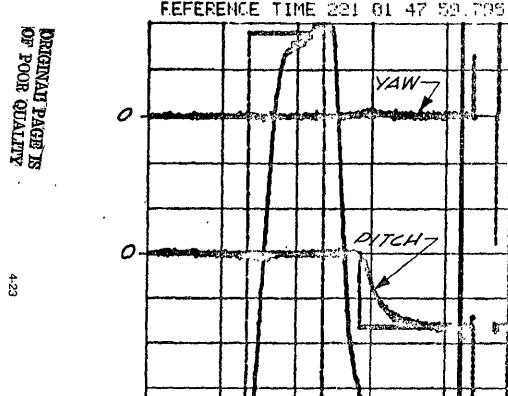
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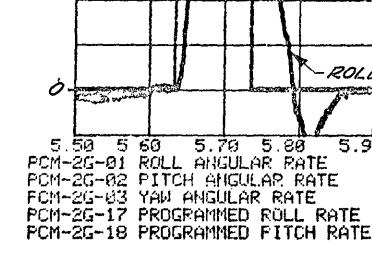
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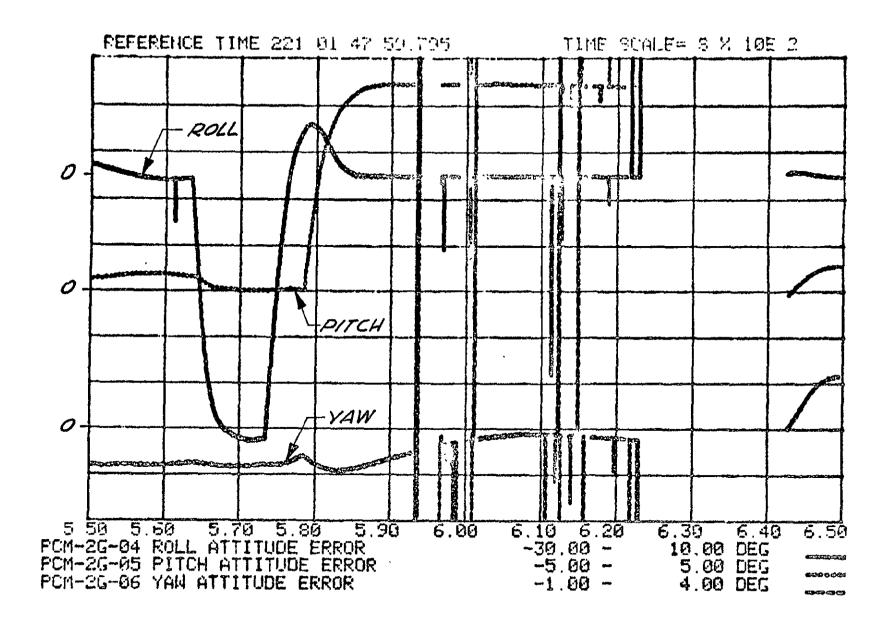
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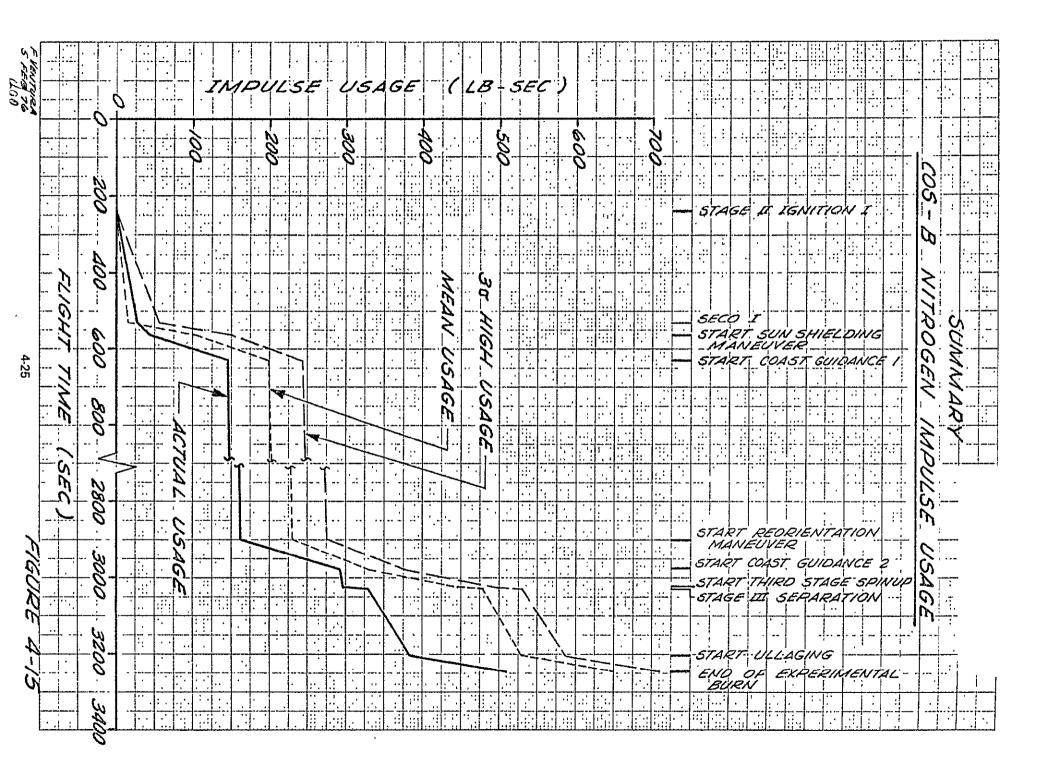
ANGULAR RATES DURING SUN SHIELDING MANEUVERS

FIGURE 4-13



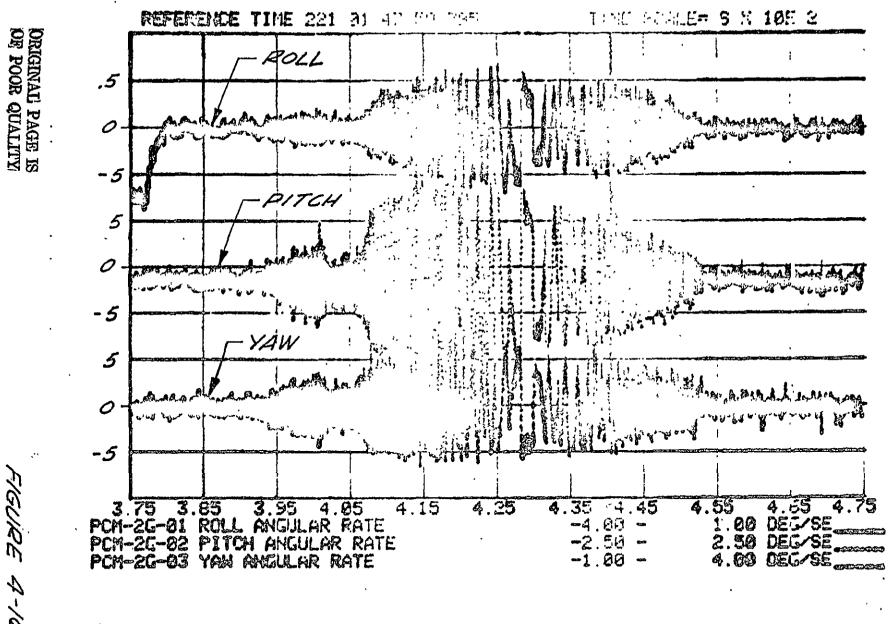
ATTITUDE ERRORS DURING SUN SHIELDING MANEUVERS

FIGURE 4-14



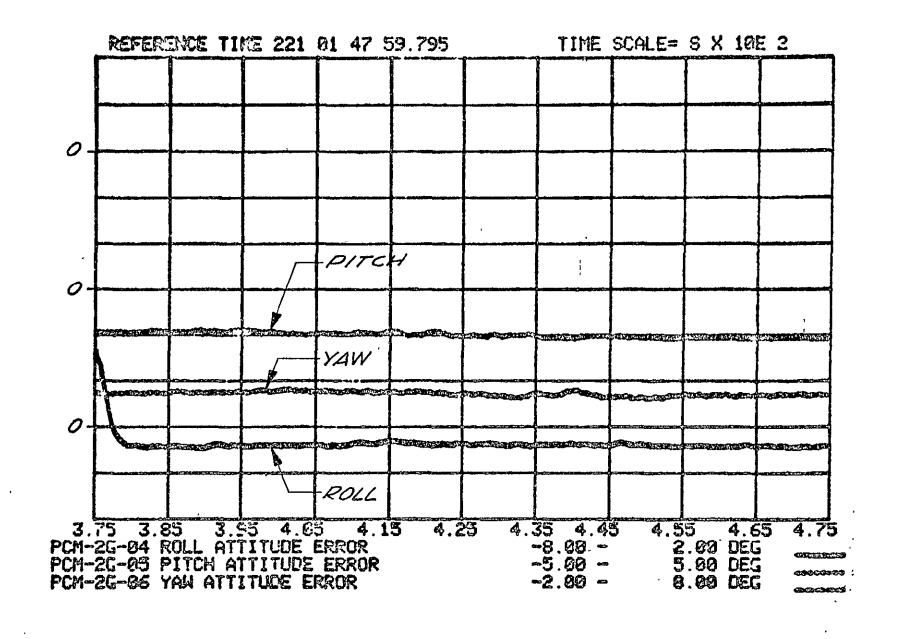
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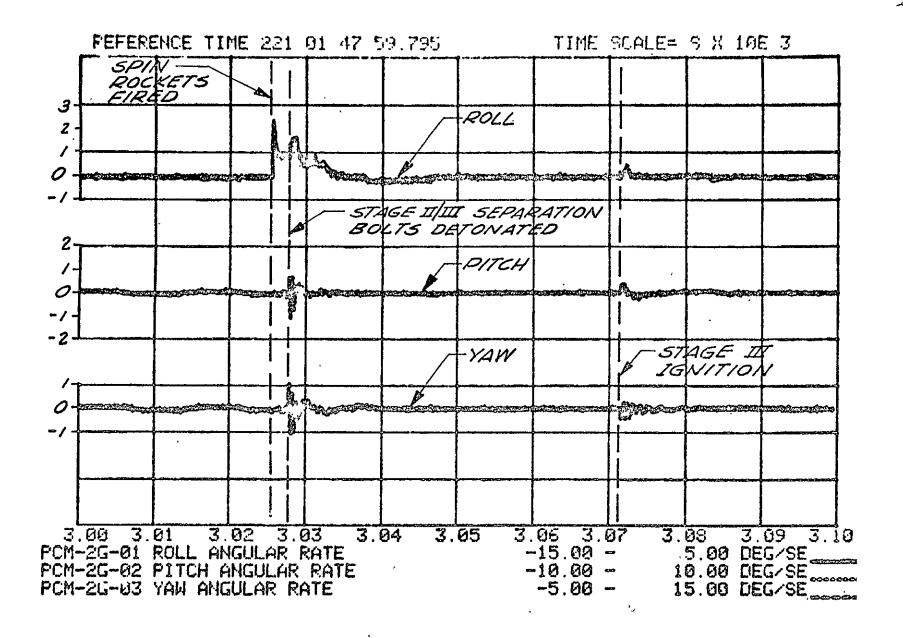
ANGULAR RATES DURING SECOND STAGE POWERED FLIGHT

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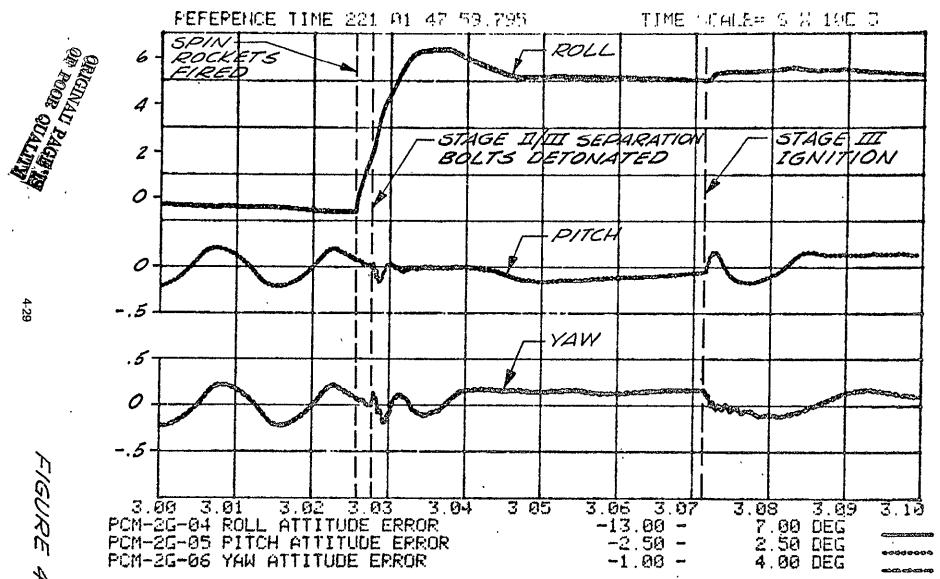
ATTITUDE ERRORS DURING SECOND STAGE POWERED FLIGHT

FIGURE 4-17



ANGULAR RATES AT STAGE IS TIL SEPARATION

FIGURE 4-18



41/3/6

ATTITUDE ERRORS AT STAGE II/II. SEPARATION

4-29

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CIGURE 4-19

SECTION 5: ELECTRONICS SYSTEM - COS-B MISSION

ATTACHMENT 5:

Attachment 5 to: A3-262-AM00-M75-509

Attachment 5 to: A3-262-AM00-M75-509

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SECTION 5

ELECTRONICS SYSTEM - COS-B

5.1 FIRST STAGE PERFORMANCE

The first stage event times for the COS-B flight are tabulated in Table 5-1 and are satisfactory. The first stage electronics system voltages are tabulated in Table 5-2 and are normal. The first stage electronics system performed normally throughout the period of first stage operation except for the instrumentation anomaly indicated in subsection 5.3

5.2 SECOND STAGE PERFORMANCE

The second stage event times for the COS-B flight are tabulated in Table 5-1 and are satisfactory. Second stage electronics system voltages and steadystate parameters are listed in Table 5-3 and are normal. Table 5-4 tabulates sequence times obtained from PCM data which indicates the guidance computer discrete output activity. The second stage electronics system performed normally throughout the flight except for the instrumentation anomaly indicated in subsection 5.3

5.3 ANOMALIES

5.3.1 First Stage LOX Pump Inlet Pressure - FM11-09

The LOX pump inlet pressure transducer returned data until approximately 75 seconds at which time the unit failed. The transducer is located in the LOX pump inlet elbow and has repeatedly failed in this position. Due to the repeated failures in this position, a change has been implemented to relocate the transducer to the LOX Accumulator for all vehicles. The relocation did not carry COS-B effectivity.

5.3.2 Second Stage Thrust Chamber Pressure - FM21-09

The Second Stage Chamber Pressure measurement indicated a 50 second duration pressure transient beginning approximately 25 seconds after second stage ignition. Analysis of other propulsion parameters revealed that the chamber pressure could not respond as the data indicates. Analysis indicates that the transducer is probably being affected by a thermal gradient.

TABLE 5-1

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SEQUENCE OF EVENTS - COS-B

	NOMINAL	SYSTEM RESPONSE				
EVENT	TIME	ACTUAL TIME //	TIME #	PARAMETER		
IGNITION ARM, SETS #2 & #3	-0.900	-1,14	N/A	N/A		
IGNITION CMD. SETJ #2 & #3	-0,200	-0.38	-0.35	CHAMBER PRESS.		
TM LIFTOFF IND.		-0.18	N/A	N/A		
ACCEL. SENSE	0.000	-0.199	N/A	N/A		
FEEDBACK GAIN CHANGE	38.000	37.84	N/A	N/A		
IGNITION, SET #1	.39.000	38.97	39.07	CHAMBER PRESS.		
SEP. CMD, SET #1	87.000	87.34	87.39	CHAMBER PRESS.		
SEP. CMD, SET #2	87.000	87.34	87.37	CHAMBER PRESS.		
SEP. CMD, SET #3	87.000	87.33	87.37	CHAMBER PRESS.		
FUEL FLOAT SWITCH	خصر میں بیت سے این	217.555	N/A	N/A		
. LOX FLOAT SWITCH -	Quel des litte sam dage aug	220.285	N/A	N/A		
MECO ENABLE	224.061	222.32	N/A	N/A		
FUEL LEVEL SENSOR ENABLE	224.061	222.305	~ N/A	N/A		

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TABLE 5-1 (Continued)

SEQUENCE OF EVENTS - COS-B

.

	NOMETIAT		SYSTEM RESPO	NSE
EVENT	NOMINAL TIME	ACTUAL TIME //	TIME_#	PARAMETER
MECO	228.061	226.835	*	ME CHAM. PRESS.
DECEL. SENSE	111	227.281	N/A	N/A
VE ENABLE/ME LOCKOUT	## <u></u>	227.31	227.35	ME POSITION
ARM STAGE II BUS	<i>!! #</i>	227.33	N/A	N/A
PRESS TANKS-ON	230.061	229.83	229.86	HEL. REG. PRESS.
VECO	234.061	233.805	233.94	CHAMBER PRESS.
STAGE I/II SEP.	236.061	235.83	235.88	RELAY DEACT.
REMOVE SEP. DISCRETES	240.061	239.85	N/A	N/A
START STAGE II	241.061	240.811	21,1.101	CHAMBER PRESS,
ACCEL SENSE	##	241.181	N/A	N/A
FAIRING UNLATCH	270.000	269.33	N/A	N/A
FAIRING SEPARATION	271.000	270.35	270.35	SEP. MONITOR CKT.
FAIRING UNLATCH OFF	271.000	270.32	N/A	N/A
FAIRING SEP. OFF	273.000	272.34	N/A	N/A

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TABLE 5-1 (Continued)

SEQUENCE OF EVENTS - COS-B

			SYSTEM RESPON	SE
EVENT	NOMINAL TIME	ACTUAL TIME #	TIME #	PARAMETER
SECO I	531.075	530.563	530.723	CHAMBER PRESS.
DECEL SENSE	##	530.873	N/A	N/A
HYD. PUMP OFF	##	530.92	531.14	HYD. SYS. PRESS.
CDR OFF	592.075	N/A	590.32	CDR AGC
SPIN ROCKETS/3RD STAGE IGNITION T.D.	3027.000	3025.30	3025.764	SPIN RATE SWITCH
3RD STAGE WIRE CUTTERS	3028.000	3026.29	N/A	N/A
SPIN ROCKET CMD OFF	3028.000	3026.29	3026.29	ENG. BATT. CUR.
WIRE CUTTER CMD OFF	3029.000	3027.33	N/A	N/A
STAGE II/III SEP.	3029.000	3027.32	3027.2940	TRIAXIAL ACCEL.
FIRE RETROS	3029.000	3027.29	3027.31	HEL. REG. PRESS.
REMOVE SEP. DISCRETE	3031.000	3029.30	N/A	N/A
RETRO CMD OFF	3031.000	3029.32	N/A	N/A
HYD PUMP ON	3199.000	LOS	LOS	HYD. SYS. PRESS.
INIT. ULLAGE JETS	3205.000	3203,32	3203.314	N2 REG. PRESS.
ENGINE RESTART I	3220.000	los	LOS	CHAMBER PRESS.

TABLE 5-1 (Continued)

SEQUENCE OF EVENTS - COS-B

.

	-	SYSTEM RESPON	SYSTEM RESPONSE	
EVENT	NOMINAL TIME	ACTUAL TIME #	TIME #	PARAMETER
ACCEL SENSE	##	LOS	N/A	N/A
ULLAGE JETS OFF	3221.000	LOS	LOS	N ₂ REG. PRESS.
DECEL SENSE ***	3250.000	3247.514	N/A	N/A
SECO II	##	3247.514	N/A	N/A



TABLE 5-1 (Concluded) SEQUENCE OF EVENTS - COS-B

In this report all times are referenced to DS23 which is issued by the guidance computer upon sensing acceleration at liftoff. The actual zero reference time is obtained manually from an oscillograph plot of channel FM 21-08 versus time. The zero reference time was misread by 200 milliseconds and thus to obtain the true time relative to liftoff 200 milliseconds must be added to the relative times of the data. The times in this table and Table 5-4 have been taken directly from the data without the 200 millisecond correction being added. The TM liftoff indication comes from PDM 11-30 when the liftoff switches in the vehicle are activated by the vehicle's motion away from the liftoff pins on the pad.

- # Times listed as XX.XX are from PDM data with a time resolution of 50 msec. Times listed as XX.XXX are from FM data and have a time resolution of 10 msec.
- ## These events occur due to the sensing of acceleration or deceleration.
- * N/A if MECO due to fuel injector pressure switches (FIPS).
- ** Event did not occur.
- *** SECO II was due to a planned propellant depletion. The SECO command was issued due to the sensing of deceleration.
- N/A Not applicable. An observable system response does not (or did not) occur.
- LOS Loss of signal, either due to noise or out of range of ground station.
- ∆ System response and event occur simultaneously and response time prior to event time is due to sampling time between channels during event occurrence.

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TABLE 5-2

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1ST STAGE SYSTEM VOLTAGES - COS-B

PARAMETER	NOMINAL (VDC)	ACTUAL (VDC)
+5 VDC REFERENCE	+5.0 <u>+</u> 0.1	5.00
INSTRUM. CROUND	0.00 + 0.1	0.00
SOLID MOTOR POT. EXCIT.	+4.5 + 0.25	4.50*
F/B POT. EXCIT. (+)	+25.0 + 1.3	25.4
F/B POT. EXCIT. (-)	-25.0 <u>+</u> 1.3	-25.2
ACTUATOR EXCIT. (+)	+50.0 <u>+</u> 3.0	49.5
ACTUATOR EXCIT. (-)	-25.0 <u>+</u> 1.5	-25.0
+12.35 V BIAS	+12.35 <u>+</u> 0.15	12.2
+10 VDC TRANSDUCER	+10.0 + 0.25	9.8
-10 VDC TRANSDUCER	-10.0 <u>+</u> 0.25	-10.2

* VOLTAGE ROSE TO 5.0 VDC AT SOLID MOTOR SEPARATION WHICH IS NORMAL

TABLE 5-3

2ND STAGE SYSTEM PARAMETERS - COS-B

PARAMETER	NOMINAL	ACTUAL
+5 VDC REFERENCE	+5.0 <u>+</u> 0.1 VDC	5.00 VDC
INSTRUM. GROUND	0.0 <u>+</u> 0.1 VDC	0.00 VDC
+5 VDC PCT. EXCIT.	+5.0 <u>+</u> 0.1 VDC	5.00 VDC
F/B POF. EXCIT. (+)	+20.0 <u>+</u> 1.0 VDC	19.7 VDC
F/B POT. EXCIT. (-)	-20.0 <u>+</u> 1.0 VDC	-20.0 VDC
VALVE EXCIT. (+)	+35.0 <u>+</u> 2.0 VDC	34.7 VDC
VALVE EXCIT. (-)	-35.0 + 2.0 VDC	-34.5 VDC
GC LOGIC VOLTS	+5.0 <u>+</u> 0.3 VDC	4.90 VDC
GC MEMORY VOLTS	-30 ± 2.1 VDC	-29.6 VDC
IMU LOGIC VOLTS	+5.0 <u>+</u> 0.5 VDC	5.2 VDC
IMU GYRO EXCIT.	22.0 ± 2.2 VRMS	20.5 VRMS
GYRO WHEEL FREQ.	388.0 <u>+</u> 3.9 HZ	389.0 HZ
IMU BLOCK TEMP.	+160 <u>+</u> 2.0°F	160.4°F

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The following tabulation includes all computer discrete activity to show compliance to the Sequence of Events 1896808. This data was taken from the PCM data. The mission times tabulated in Table 5-1 were obtained from the PDM/FM telemetry data with a time resolution of 10 ms (FM) and 50 ms (PDM). The PCM times are listed here separately since the PCM time resolution is 0.125 seconds and would not accurately correlate to the PDM/FM times. This tabulation includes some events not tabulated in the PDM/FM data due to the limited monitoring capability of the PDM/FM system.

EVENT .	NOMINAL TIME	ACTUAL TIME	FUNCTION
Accel Sense	0.000	-0.083	DS23
Feedback Shaping Network Gain Change	38.000	37.867	DŞ30
Enable MECO · · ·	224.061	222.400	DS31
Decel. Sense	228.061	227.381	DS23 Off
VE Enable/ME Lockout	228.061	227.381	DS29
Stage II Hydraulic Pump On (Backup)	228.061	227.381	DS7
Arm Stage II Ignition and Pyrotechnic Power	228.061	227.381	DS12 DS13
Pressurize Tanks	230.061	229.871	D522
VE Cutoff (VECO)	234.061	233.903	DS32
Blow Stage I/II Separation Bolts	236.061	235.919	DS2 DS18
Remove Stage I Discretes	237.061	236.868	DS18 DS29 Off DS30 Off DS31 Off DS32 Off DS2 Off DS2 Off DS18 Off
Remove Separation Discretes	240.061	239.952	DS2 Off DS18 Off S

SEQUENCE TIMES

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PCM DATA - COS-B

VENT	NOMINAL TIME	ACTUAL TIME	FUNCTION
tart Stage II Engine	241.061	240.900	DS3
ccel Sense	##	241.258	DS23
emove Tank Pressurization and agine Start Discretes	242.061	241.849	DS22 Off DS3 Off
airing Unlatch	270.000	269.363	DS4 ·
airing Unlatch Off	271.000	270.431	DS4 Off
Fairing Separation	271.000	270.431	DS19
Fairing Separation Off	273.000	272.447	DS19 Off
SECO I	531.075	530.625	DS5
Decel Sense	##	530.981	DS23 Off
Turn Off Hydraulic Pump	##	530.981	DS7 Off DS6
Enable CDR Turnoff	591.075	589.448	DS27 DS28
Turn Off CDR's	592,075	590.397	DS27 Off
RACS Enable	iyada kada alayo danin kalin kaling dalay	##	DS17
Remove RACS Enable	gene bank igen gant dan wak man I	ж ж.	DS17 Off
Fire Spin Rockets & 3rd Stage Ign Comm	3027.000	3025.377	DS10
Fire 3rd Stage Wire Cutters	3028.000	3026.326	DS11
Remove Spin Rocket Discrete	3028.000	3026.326	DS10 Off

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EVENT	NOMINAL TIME	ACTUAL TIME	FUNCTION
Remove Wire Cutter Discrete	3029.000	3027.393	DS11 Off
Stage II/III Separation Command	3029.000	3027.393	DS15
Fire Retros	3029.000	3027.393	DS14
Remove Separation Discrete	3031.000	3029.409	DS15 Off
Remove Retro Discrete	3031.000	3029.409	DS14 Off
Hydraulic Pump - On	3199.000	LOS	DS7 DS6 Off
Initiate Ullage Jets	3205.000	3203.387	ds8
Engine Restart #1	3220.000	LOS	DS3 DS5 Off
Acceleration Sense	##	lós	DS23
Ullage Jets Off	3221.000	LOS .	DS9 DS8 Off
Deceleration Sense****	3250.000	3247.743	DS23 Off
SECO II***	##	3247.624	DS5 DS3 Off
Turn Off Hydraulic Pump On Discrete (Pump Remains On)	##	3247.624	DS7 Off

SEQUENCE TIMES - PCM DATA - COS-B

*** SECO II.was commanded as a result of sensed deceleration due to a planned propellant depletion.

**** FM data indicated the acceleration sense discrete, DS 23, went off at 3247.514 long enough to command SECO II, however went on again before it could be sampled by the PCM telemetry. DS 23 went off and remained off at 3247.694 and was then sampled by the PCM telemetry at 3247.743 as being off.

Attachment 6 to: A3-262-AM00-M75-509

ATTACHMENT 6:

SECTION 6. MECHANICAL SYSTEMS - COS-B MISSION

Attachment 6 to: A3-262-AMO0-M75-509

6.1 First Stage Hydraulic System

Hydraulic power is supplied to the six first stage gimbal actuators by a pressure compensated variable displacement pump and an integrated accumulator/ reservoir. The hydraulic system functioned normally throughout main and vernier engine operation. Quantitative data is presented in Table 6-1 and Figures 6-1 and 6-2.

6.1.1 Supply Pressure

All supply pressure measurements were within the TRD limits for steady state and transient operation. The system was supplied by HTS power at a pressure of 2955 psia until one second before liftoff when the assessory drive accelerated the pump to 4036 RPM at T-O. The pump pressure peaked at 3268 psia, 0.45 seconds after liftoff, then stabilized at 3175 psia at T + 1.5 seconds.

Supply pressure oscillations occurred from T-0.6 seconds to T-0.3 seconds in a pump speed range of 3208 to 3587 RPM. A survey of these startup oscillations on missions back to Skynet IIB showed that "blossoming" occurred on all pumps including those used with MB-3 engines. Also, the RPM at first indication of amplitude increase varied from 1600 to 3108 while the RPM at the end of the "blossoming" varied from 3000 to 3621. Peak amplitudes measured between 175 and 240 psi peak-to-peak. Documented test results show that resonances occur at frequencies corresponding to speeds of 2184 RPM to 2726 RPM, however, resonance frequencies have been accurately recorded up to 3400 RPM (Westar A, simulated flight test). Large datum errors are possible when using T/M measurements because of the low datum sample rate, therefore, the above flight test results are approximations. The pump oscillations do not degrade hydraulic system performance and overtests have verified ample margin against a malfunction during this transient period.

The supply pressure decreased normally until MECO when it was measured at 3135 psia. The rate of decrease was 0.11 psi/second in a flight experience band of 0.06 to 0.18 psi/second. The pressure decrease is primarily due to decreasing oil viscosity and change in pump pressure compensator spring force with increasing temperature. The accumulator bleeddown required 73.5 seconds measured from first piston motion (at MECO) to the time the accumulator was empty (supply pressure corner). The corner pressure was 1610 psia which is the lowest corner measurement since Delta 92, and is indicative of low accumulator precharge and long bleeddown time. A leaking accumulator fill valve was found which had a pressure decay rate of 24 psi/day after the last of three accumulator fill procedures had been performed at VTC. At the pre-launch slew check 30 minutes before launch, the accumulator pressure measured 2070 psia at 92 degrees F or 1984 psi at 70 degrees F, which is below the TRD limit, but well above the 1715 psia precharge launch redline. This is calculated to yield the observed bleeddown corner, and an increase in bleeddown time of 5.1 seconds over the bleeddown time with nominal precharge. The hydraulic system responded normally at this precharge.

The reservoir began filling at T + 227 seconds (MECO) and was full at T + 234.7 seconds. The pump spun down and stopped at T + 234.2 seconds. Decompression of the supply side of the system required 1.6 seconds.

6.1.2 Accumulator GN2 Pressure

The average piston friction was measured at 26 psi using the differential supply - GH2 pressures. A volume of 66.5 cubic inches of oil was transferred to the accumulator due to the low precharge and represents an operating level of 65 percent full.

6.1.3 Return Pressure

Before liftoff, return pressure is the relief pressure of the low pressure relief values and measured 233 psia on COS-B which is nominal. At pump startup, the relief values closed and the return pressure went to a bootstrap level of 163 psia. The bootstrap return pressure permits T/M verification of the accuracy of supply and return pressures, since they differ by the bootstrap ratio which is nearly constant at 21.39 \pm .04. The transient dip in pressure went to 144 psia during startup while the low pressure relief values were closing. This verified the nominal response time of the values and reservoir piston

At MECO the return pressure was 147 psia. At the reservoir full point, the return pressure became independent of supply pressure and peaked at 220 psia, the cracking point of the relief valves. The steady state relief pressure during bleeddown was 213 psia. All return pressure measurements were within TRD limits.

6.1.4 Reservoir Piston Position and Temperature

The piston position measurement for the reservoir full condition was measured at 98.4 percent. At pump startup the reservoir gave up 10.5 cubic inches of fluid to the accumulator due to differential increase in supply pressure, and at this point the piston position measured 93.7 percent. The piston gradually settled to a 93 percent position at T + 90 seconds as the GN2 temperature gradually recovered from the compression heating at pump startup. The reservoir oil temperature had remained stable at 87 degrees since liftoff. After T + 90 seconds the temperature gradually climbed to 98 degrees at MECO as the oil picked up compression energy from the pump.

6.1.5 Hydraulic Servo

The six servo values and actuators functioned normally throughout flight. The summation of the actuator rates was a maximum at T + 16 seconds at which time the flow was calculated to be 1.6 gpm. Therefore, no fluid was required from the accumulator to meet servo demands during the mission. Drift and balance shift were well within TRD limits for all servo values.

6.2 Second Stage Hydraulic System

The second stage hydraulic system provides the hydraulic power for the second stage engine gimballing and bi-propellant flow control valve actuation. The hydraulic system comprises an electric motor dirven fixed displacement piston

6.2 Second Stage Hydraulic System - Continued

pump, and a separate precharged accumulator and precharged reservoir. Performance of the system was nominal during the first duty cycle from T - 45 seconds to SECO 1 at T + 531 seconds. Recorded T/M data from the subsequent experimental restart failed to include the pump startup transient and loss of battery power. However, all steady state data on the run were normal.

6.2.1 First Duty Cycle

Prior to pump turn on the return pressure measured 67 psia at a temperature of 60 degrees F, and reflects the reservoir precharge which was 3 psi above nominal in a tolerance band of 10 psi. At turn on the supply pressure transient peak prior to accumulator piston first motion was 915 psia interpolated between datum points with a TRD allowable of 1135 psia. Accumulator piston first motion occurred at a pressure of 650 psia. The steady state supply pressure of 1100 psia was attained in 1.30 seconds, then slowly decreased to 1080 psia at SECO 1 due to oil heating. At turn on the return pressure decreased to a steady state value of 49.5 psia at completion of accumulator filling.

The motor pump temperature increased from a turn on value of 60 degrees F to 194 degrees F at SECO-I and peaked at 202 degrees F at 610 seconds. Accumulator bleeddown required 11.0 seconds to a precharge corner of 565 psia. All measurements were within TRD limits during the run.

6.2.2 Experimental Restart

Datum coverage started at 3202 seconds, whereas pump restart was scheduled for 3199 seconds. Usefull data amounted to 1.5 seconds during which time the supply pressure was 1095, the return pressure 58, and the motor case temperature 125 degrees F. Data coverage began again at 3242 seconds while the hydraulic system was operating and was lost for the last time at 3465 seconds. The system responded normally during the restart.

6.2.3 Hydraulic Servo

Servo valves and actuators functioned satisfactorily during both hydraulic duty cycles. At initial pump start, the engine was snapped to zero deflection angle for a total oil useage of 0.9 cubic inches which was supplied by the pump during the transient rise in pressure as the accumulator was empty at this time. This increased the duration of the pressure transient to 1.60 seconds in a prior experience band of 1.0 to 1.6 seconds. Bi-propellant valve actuation caused a dip of 80 psi in system pressure and a dip to 47 psia in return pressure.



6.3 Ordnance and Mechanical Devices

All ordnance and mechanical devices functioned satisfactorily to complete a successful launch.

6.4 Environmental Control Aerospace Ground Equipment (AGE)

All environmental control AGE equipment performed satisfactorily during the countdown and launch.

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6.5 Hydraulic Control Aerospace Ground Equipment

All hydraulic control AGE performed satisfactorily during the countdown and launch.

TABLE 6-1

FIRST STAGE HYDRAULIC SYSTEM

PERFORMANCE SUMMARY

COS-B

Event	Time from Liftoff (sec)	Supply Pressure (psia)	Return Pressure (psia)
	(320)	<u>(p3/u)</u>	<u></u>
HTS power	-5.0	2955	233
Peak pressure	0.4	3268	-
Steady state	5.0	3175	163
Solid motor separation	87	31 50	150
Reference point	120	3145	148
MECO	227	3135	147
Pump stall	234,24	2990	141
Reservoir full	234.76	2964	141
LPRV crack	234.9	2953	220
Accumulator empty	300.6	1610	,213
Bleed down + 5 sec	·	200	212
Accumulator bleed down time	73.5 s	econds	
Decompression time	1.6 s	econds	

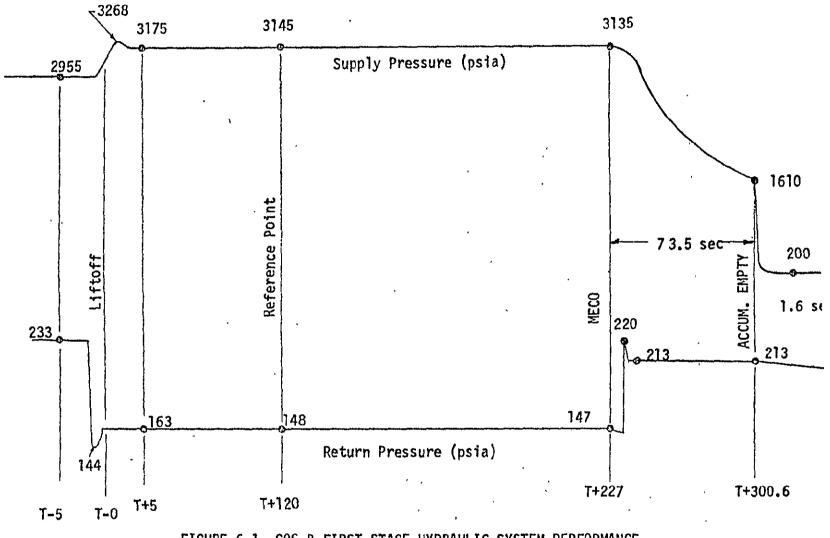


FIGURE 6-1 COS-B FIRST STAGE HYDRAULIC SYSTEM PERFORMANCE

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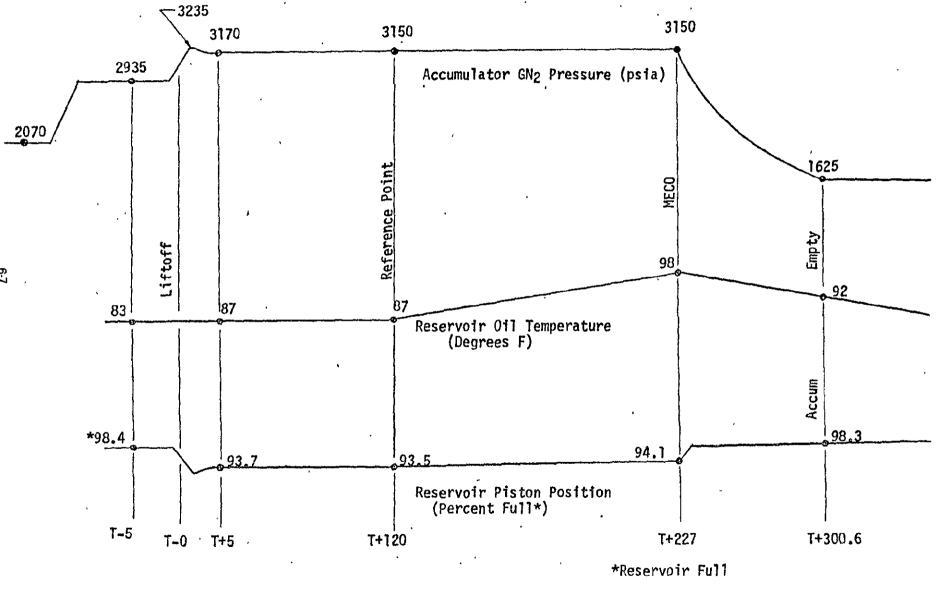


FIGURE 6-2 COS-B FIRST STAGE HYDRAULIC SYSTEM PERFORMANCE

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TABLE 6-2

SECOND STAGE HYDRAULIC

SYSTEM PERFORMANCE SUMMARY

COS-B

-

Event	Time from Liftoff (sec)	Supply Pressure (psia)	Return Pressure (psia)
Prior to pump on	-46	60	67
Pressure knee	-45.4	680	-
Steady state	-40	1100 (actual) 49.5
Liftoff	0	1100	53
At engine ignition	241	1090	59/47
SECO-1	531	1080	62
Accumulator empty	542	565	87
Prior to restart	Data	not available	•
Pressure knee	Data	not available	
Steady state	3203	1095	58
SECO-2	3247.5	1090	57
Accumulator bleed down time (lst cycle)	11.0 s	econds	
Accumulator bleed down time	N/A -	Pump remained o	on .

(restart)

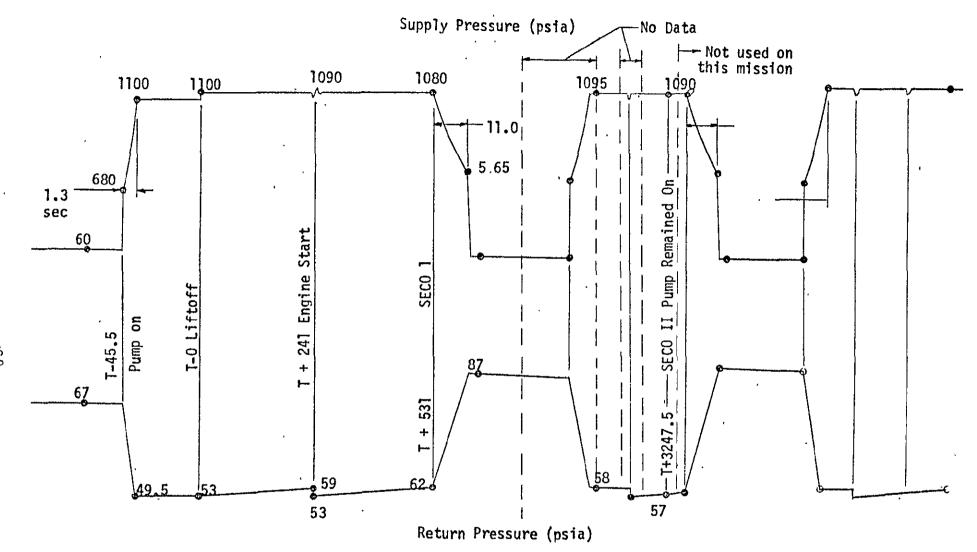
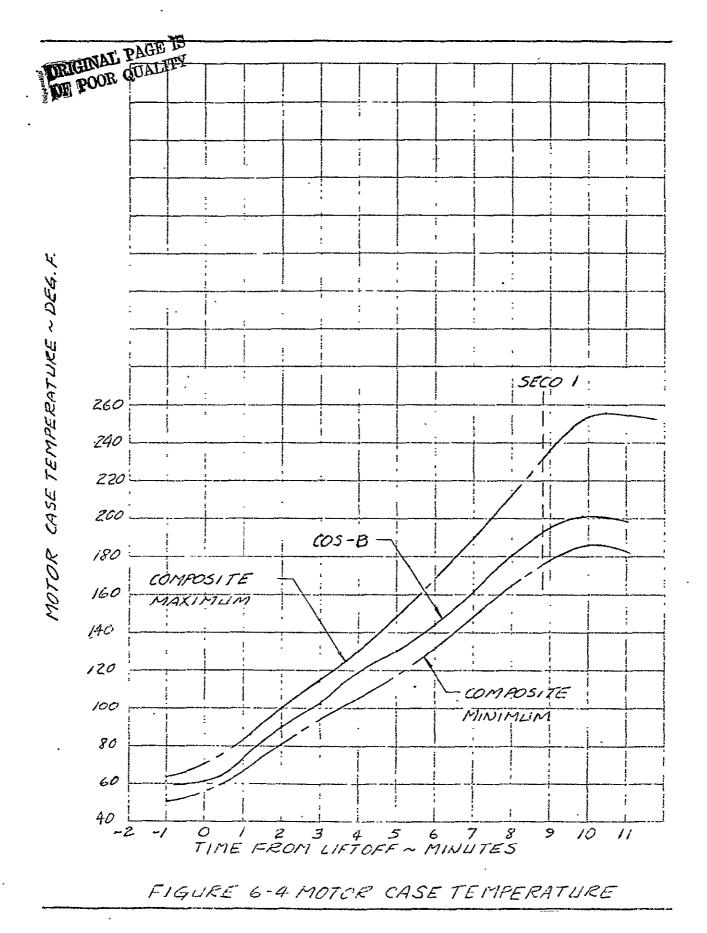


FIGURE 6-3 COS-B SECOND STAGE HYDRAULIC SYSTEM PERFORMANCE



Attachment 7 to: A3--262-AM00-M75-509

ATTACHMENT 7:

SECTION 7. STRUCTURAL SYSTEMS - COS-B MISSION

Section 7

STRUCTURAL SYSTEMS - COS-B MISSION

7.1 STRUCTURAL PERFORMANCE

The COS-B first and second stage and fairing structural subsystems and associated components satisfactorily provided the launch vehicle with the strength and rigidity required to withstand all design conditions during handling and throughout all phases of the flight. A secondary transient was noted during fairing jettison. Reference T00164, "Fairing Separation and Roll Moment", unreleased at this time. A second stage POGO was noted and will be covered by T00166, "COS-B Anomaly Investigation", unreleased at this time.

7.2 VIBRATION MEASUREMENT DATA

Vibration data analysis results for COS-B will be documented under separate cover at a later date.

7.3 WEIGHT DATA

Actual inflight weight data for the COS-B launch vehicle and its various components are provided in Table 7-1. Included in this table are actual dry weights, propellant liftoff weights and densities, and pressurization and control gas weights.

7.4 SUPPORT EQUIPMENT AND FACILITIES

All support equipment performed satisfactorily during countdown and launch. Damage to the facilities at Launch Complex SLC 2W at the Vandenberg Test Center was light. Recycle time to support the next launch was normal.

7-1

TABLE 7-1

FINAL POST FLIGHT WEIGHT SUMMARY

COS-B CONFIGURATION 2913

	ITEM	WEIGHT (LBS)	WEIGHT (LBS)
1.	THIRD STAGE USEFUL LOAD		681.81
	COS-B Spacecraft Payload Attach Fitting, MDAC	614.15 63.31	
	Mods and Telemetry Ballast	4.35	
2.	BURNED OUT THIRD STAGE (TE-364-3 S/N 00025)		129.69
3.	THIRD STAGE BURNOUT		811.50
4.	PROPELLANTS AND INERTS CONSUMED		1,450.64
5.	THIRD STAGE IGNITION	<u></u>	2,262.14
7.	SPINTABLE ASSEMBLY DSV-3E-17C (S/N 20236)		. 214.83
8.	SECOND STAGE USEFUL LOAD	· · · · · · · · · · · · · · · · · · ·	2,476.97
9.	DRY SECOND STAGE - DSV-3P-4B (S/N 20020) (LESS 8.0 LBS. ABLATIVE EXPENDABLES)	, ,	1,815.47
10.	TRAPPED PROPELLANTS		29.34
	Fuel Oxidizer (Liquid) Oxidizer (Vapor)	5.24 11.10 13.00	
11.	HELIUM (2 BOTTLE SYSTEM)		20.34
12.	NITROGEN RESERVE - 1 BOTTLE SYSTEM		18.25
13.	PROPELLANT RESERVE		778.40
	Fuel Oxidizer	288.04 490.36	

TABLE 7-1 (CONTINUED)

FINAL POST FLIGHT WEIGHT SUMMARY

.

COS-B CONFIGURATION 2913

	ITEM	WEIGHT (LBS)	WEIGHT (LBS)
22.	NITROGEN USED DURING COAST AND FIRST BURN		4.85
25.	SECOND STAGE ENGINE CUTOFF - FIRST BURN		5,143.62
. & 26.	STOP TRANSIENT & TCA BOILOFF	•	11.72
	Fuel Oxidizer	5.10 6.62	
23.	ABLATIVE EXPENDABLES		8.00
27.	PROPELLANT CONSUMED		9,238.02
	Fuel Oxidizer	3,575.54 5,662.48	
28.	FAIRING DSV-3P-7A (S/N 20023)		1,305.00
29.	START TRANSIENT		2.31
	Fuel Oxidizer	.62 1.69	
30.	SECOND STAGE IGNITION	<u>, , , , , , , , , , , , , , , , , , , </u>	15,708.67
31.	FIRST TO SECOND STAGE ADAPTER - DSV-3P-2A (S/N 20019)		986
32.	DRY BOOSTER DSV-3P-1A (20020) (602)		8,948
33 . [.]	TRAPPED PROPELLANTS AND GASES		670
	Fuel Liquid Oxygen Gaseous Oxygen Gaseous Nitrogen FABU Lube and/or Fuel	142 70 335 117 6	·

.

TABLE 7-1 (CONTINUED)

FINAL POST FLIGHT WEIGHT SUMMARY

COS-B CONFIGURATION 2913

	ITEM	WEIGHT (LBS)	WEIGHT (LBS)
34.	RESIDUAL PROPELLANTS		282
	Fuel Liquid Oxygen	282 0	
35.	RESIDUAL VERNIER PROPELLANTS		54
	Fuel (Includes 18 pounds vernier refill)	25	
	Liquid Oxygen (Includes 12 pounds vernier refill)	29 .	
36.	VERNIER ENGINE CUTOFF		26,649
37.	VERNIER PROPELLANT CONSUMED		44
•	Fuel Liquid Oxygen	16 28	
38.	MAIN ENGINE STOP LOSSES		140
	Fuel Liquid Oxygen	47 93	
39.	MAIN ENGINE CUTOFF	المريخ بين و دو دو دو دان خطر اور و مريخ مير مير مير مير مير مير مير مير مير مير	26,833
40.	LIQUID PROPELLANTS CONSUMED		175,388
	Fuel Liquid Oxygen	55,590 119,798	
41.	LIQUID PROPELLANTS & GASES VENTED		364
	Fuel Overflow Liquid Oxygen Overflow Gaseous Oxygen Vented	8 29 327	

TABLE 7-1 (CONTINUED)

FINAL POST FLIGHT WEIGHT SUMMARY

COS-B CONFIGURATION 2913

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	ITEM	WEIGHT (LBS)	WEIGHT (LBS)
42.	SOLID MOTOR CASES (6) (FIRST BURN)	-	9,530
	Solid Motor Cases (6) MDAC Modifications Cork Insulation	8,797 413 320	
43.	SOLID MOTOR CASES (3) (SECOND BURN)		4,725
	Solid Motor Cases (3) MDAC Modifications Cork Insulation	4,373 207 145	
44.	SOLID MOTOR PROPELLANT & INERTS CONSUMED (6) (FIRST BURN)		49,591
	Propellants Inert Loss During Burning	49,233 358	
¥5.	SOLID MOTOR PROPELLANTS & INERTS CONSUMED (SECOND BURN)		24,837
	Propellants Inert Loss During Burning Pyrogen	24,652 179 6	
47.	SOLID MOTOR NOZZLE PLUGS (3) (SEOND BURN)		22
48.	LIFTOFF		291,290

TABLE 7-1 (CONTINUED) FINAL POST FLIGHT WEIGHT SUMMARY COS-B CONFIGURATION 2913

PROPELLANT DATA			
ITEM	WEIGHT (LBS)	DENSITY (LBS/FT ³)	
FIRST STAGE			
Oxidizer in tank at liftoff Fuel in tank at liftoff	120,501 55,898	70.589 50.496	
SECOND STAGE			
Oxidizer loaded Fuel loaded	6,185.25 3,874.54	90.843 56.504	

Attachment 8 to: A3-262-AM00-M75-509

ATTACHMENT 8:

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SECTION 8. RELIABILITY

Section 8

RELIABILITY

The reliability point estimates and 90 percent lower confidence limits for the various Delta vehicle configurations flown to date, considering 113 flights, are furnished in Table 8-1. The indicated reliability point estimate values were obtained by dividing the number of flight successes by the total number of flights. Using these values, applicable standard probability tables were then utilized to obtain the 90 percent confidence limit values that are shown.

8-1

Item	Trials	Failures	Reliability Point Estimate	90% Lower Confidence Limit
Complete Vehicle Delta Improved Delta Long Tank Delta Extended Long Tank Delta Total Vehicles	38 26 29¤ 20Ъ 113	- 3 0 5 1 9	0.921 1.000 0.828 0.950 0.920	0.833 0.915 0.704 0.819 0.877
First Stage Booster Thor Long Tank Thor Extended Long Tank Thor RS-27 (E.L.T.) Total Boosters	64 29a 8d 12d 113	0 2 0 0 2	1.000 0.931 1.000 1.000 0.982	0.965 0.827 0.750 0.825 0.954
Second Stage Delta Improved Delta Transtage Delta SSPU (TRW) Total Second Stages	38 48c 12 13 111	1 1 2 0 4	0.974 0.979 0.833 1.000 0.964	0.901 0.921 0.614 0.838 0.929
Third Stage Motor X-248 Motor X-258 Motor FW-4D Motor TE-364-3 Motor TE-364-4 Motor Total Third Stages	22a 18 21a 17e 10 88f	1 0 1 0 3 .	0.955 0.944 1.000 0.941 1.000 0.966	0.834 0.801 0.896 0.790 0.794 0.926

Table 8-1 RELIABILITY SUMMARY (COS-B)

a. Long Tank Thor/Delta: Includes four six-solid-motor booster configurations (IMP-I, TIROS-M, ITOS-A, ITOS-B) and two nine-solid-motor booster configurations (ERTS-A, NIMBUS-E).

b. Extended Long Tank Thor/Delta: Includes three three-solid-motor booster configurations (SKYNET-IIA, SKYNET-IIB, ITOS-G), one four-solid motor booster configuration (GEOS-C), two six-solid-motor booster configurations (IMP-H, IMP-J), and fourteen nime-solid-motor booster configurations (TELESAT-A, AEC, TELESAT-B, RAE-B, WESTAR-A, WESTAR-B, SMS-A, SYMPHONIE-A, ERTS-B, SMS-B, TELESAT-C, NIMBUS-F, OSO-I, and COS-B).

- c. Two improved Delta vehicles were not considered trials.
- d. One motor of this model was not considered a trial.
- e. One motor of this model was not considered a trial, and the one flown on the INTELSAT-III-E mission (Delta Program Mission No. 71) was considered a failure.
- f. Twenty-two launch vehicles did not have a third stage.

ORIGINAL PAGE IS OF POOR QUALITY ATTACHMENT 9:

DEFINITIONS OF PERFORMANCE PARAMETERS [TABLES 2-4 THROUGH 2-6 OF ATTACHMENT 2 (SECTION 2)]

Attachment 9 to: A3-262-AMO0-M75-509

Attachment 9

DEFINITIONS OF PERFORMANCE PARAMETERS [TABLES 2-4 THROUGH 2-6 OF ATTACHMENT 2 (SECTION 2)]

This attachment provides the performance parameter definitions on which the values given in Tables 2-4 through 2-6 of Attachment 2 (Section 2) are based.

9.1 First Stage

First stage performance parameters for the liquid engine system and for the solid motors are defined in the following paragraphs.

9.1.1 Liquid Engine System

Parameter

Definition

The liquid engine thrust for altitude conditions averaged from liftoff to MECO.

The liquid engine thrust for vacuum

The liquid engine effective specific

The liquid engine effective specific

impulse for vacuum conditions averaged

from liftoff to MECO.

from liftoff to MECO.

conditions averaged from liftoff to MECO.

impulse for altitude conditions averaged

Average Altitude Thrust:

Average Vacuum Thrust:

Average Altitude Effective Specific Impulse:

Average Vacuum Effective Specific Impulse:

Propellant Utilization:

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The ratio of the weight of propellant consumed during steady-state burn (from liftoff to depletion at MECO) to the weight of total propellant available for the steady-state burn.

9.1.2 Solid Motors

Parameter

Definition

Average Altitude Thrust:

Average Vacuum Thrust:

The total thrust of the solid motors for altitude conditions averaged from liftoff to burnout.

The total thrust of the solid motors for vacuum conditions averaged from liftoff to burnout.

Average Altitude Specific Impulse:	The specific impulse for altitude con- ditions averaged for the solid motors from liftoff to burnout.
Average Vacuum Specific Impulse:	The specific impulse for vacuum con- ditions averaged for the solid motors from liftoff to burnout.

9.2 Second Stage

Second stage performance parameters are defined as follows:

Parameter	Definition
Average Thrust (ACC):	The thrust of the second stage engine averaged from start* to SECOM. The reconstructed value is based on a flight kinetic reconstruction using DIGS accel- eration, flow rates, and actual vehicle weight data.
Average Thrust (Pc):	The thrust of the second stage engine averaged from start* to SECOM. The reconstructed value is based on a pro- pulsion reconstruction using chamber pressure (Pc), flow rates, nozzle throat area, thrust coefficients, and acceptance test data.
Average Specific Impulse (ACC):	The specific impulse of the second stage engine averaged from start* to SECOM. The reconstructed value is based on the flight kinetic reconstruction.
Average Specific Impulse (Pc):	The specific impulse of the second stage engine averaged from start* to SECOM. The reconstructed value is based on the propulsion reconstruction.
Propellant Consumption:	The ratio of the weight of propellant consumed during steady-state burn (from start* to SECOM) to the weight of total propellant available for a steady-state burn.
Propellant Utilization:	The ratio of the weight of propellant that would have been consumed during steady-state burn if the engine had burned to depletion to the weight of the total propellant available for a steady-state burn.

*Start and restart are defined as the time at which chamber pressure reaches a steady-state level.

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Attachment 10 to: A3-262-AM00-M75-509

ATTACHMENT 10:

VEHICLE PERFORMANCE TELEMETRY PLOTS - COS-B MISSION

Attachment 10 to: A3-262-AM00-M75-509

Attachment 10

VEHICLE PERFORMANCE TELEMETRY PLOTS - COS-B MISSION

A series of telemetry plots relating to COS-B launch vehicle inflight performance is furnished in this attachment. Included are all of the PDM and FM data; the first-stage plots cover the period from -300 seconds to 500 seconds (pages 10-6 through 10-29); the second-stage plots cover the period from -300 seconds to 3,600 seconds (pages 10-30 through 10-59); and the third stage plots cover the period from -300 seconds to 3,600 seconds (pages 10-68 through 10-73). Also included in this attachment are data for fourteen selected PCM channels from the second-stage T/M; the PCM data plots cover the period from -300 seconds to 3,600 seconds (pages 10-60 through 10-67). An index to the PDM, FM, and PCM data plots is provided on pages 10-2 through 10-5 of this attachment.



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FUEL DEPLETION SECUENCE NO.1 LOX ACCUMULATOR PRESSURE CONTROL BATTERY CURRENT MAIN ENGINE CHAMBER PRESSURE TURBOPUMP SPEED FUEL PUMP INLET PRESSURE TRIAXIAL ACCEL THRUST AXIS (X) GYRD WHEEL SUPPLY FREQUENCY CONTROL BATTERY CURRENT YAW JET ACTUATION-PRIMARY PITCH/POLL JET ACTUATION-PRIMAR ROLL/PITCH JET ACTUATION-PRIMAR THRUST CONTROL SIGNAL 2ND STAGE YAW CONTROL SIGNAL	100 102 400 401 401 402 Y 402	
SECUENCE NO.1 LOX ACCUMULATOR PRESSURE CONTROL BATTERY CURRENT MAIN ENGINE CHAMBER PRESSURE TUBBOPUMP SPEED FUEL PUMP INLET PRESSURE TRIAXIAL ACCEL THRUST AXIS (X) GYRO WHEEL SUPPLY FREQUENCY CONTROL BATTERY CURRENT YAN JET ACTUATION-PRIMARY PITCH/POLL JET ACTUATION-PRIMAR ROLL/PITCH JET ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAN CONTROL SIGNAL	101 102 101 101 100 102 400 401 401 402 402 402	
FUEL PUMP INLET PRESSURE TRIAXIAL ACCEL THRUST AXIS (X) GYRD WHEEL SUPPLY FREQUENCY CONTROL BATTERY CURRENT YAN JET ACTUATION-PRIMARY PITCH/POLL JET ACTUATION-PRIMAR ROLL/PITCH JET ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAN CONTROL SIGNAL	102 101 101 100 102 400 401 401 402 402	
FUEL PUMP INLET PRESSURE TRIAXIAL ACCEL THRUST AXIS (X) GYRD WHEEL SUPPLY FREQUENCY CONTROL BATTERY CURRENT YAN JET ACTUATION-PRIMARY PITCH/POLL JET ACTUATION-PRIMAR ROLL/PITCH JET ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAN CONTROL SIGNAL	100 102 400 401 401 402 Y 402	
FUEL PUMP INLET PRESSURE TRIAXIAL ACCEL THRUST AXIS (X) GYRD WHEEL SUPPLY FREQUENCY CONTROL BATTERY CURRENT YAN JET ACTUATION-PRIMARY PITCH/POLL JET ACTUATION-PRIMAR ROLL/PITCH JET ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAN CONTROL SIGNAL	100 102 400 401 401 402 Y 402	
FUEL PUMP INLET PRESSURE TRIAXIAL ACCEL THRUST AXIS (X) GYRD WHEEL SUPPLY FREQUENCY CONTROL BATTERY CURRENT YAN JET ACTUATION-PRIMARY PITCH/POLL JET ACTUATION-PRIMAR ROLL/PITCH JET ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAN CONTROL SIGNAL	100 102 400 401 401 402 Y 402	
FUEL PUMP INLET PRESSURE TRIAXIAL ACCEL THRUST AXIS (X) GYRD WHEEL SUPPLY FREQUENCY CONTROL BATTERY CURRENT YAW JET ACTUATION-PRIMARY PITCH/POLL JET ACTUATION-PRIMAR ROLL/PITCH JET ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAW CONTROL SIGNAL	102 400 401 401 402 402 402	
TRIAXIAL ACCEL THRUST AXIS (X) GYRD WHEEL SUPPLY FREQUENCY CONTROL BATTERY CURRENT YAW JET ACTUATION-PRIMARY PITCH/POLL JET ACTUATION-PRIMAR ROLL/PITCH JET ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAW CONTROL SIGNAL	400 401 401 402 Y 402	
GYRD WHEEL SUPPLY FREQUENCY CONTROL BATTERY CURRENT YAN JET ACTUATION-PRIMARY PITCH/POLL JET ACTUATION-PRIMAR ROLL/PITCH JET ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAN CONTROL SIGNAL	401 401 402 Y 402	
PITCH/POLL JEY ACTUATION-PRIMAR ROLL/PIYCH JEY ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAW CONTROL SIGNAL	Y 402	
PITCH/POLL JEY ACTUATION-PRIMAR ROLL/PIYCH JEY ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAW CONTROL SIGNAL	Y 402	
PITCH/POLL JEY ACTUATION-PRIMAR ROLL/PIYCH JEY ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAW CONTROL SIGNAL	Y 402	
ROLL/PITCH JET ACTUATION-PRIMAR THRUST CHAMBER PRESSURE 2ND STAGE YAN CONTROL SIGNAL	Y 467	
THRUST CHAMBER PRESSURE 2ND STAGE YAN CONTROL SIGNAL		
2ND STAGE YAN CONTROL SIGNAL	401	
AND FILDE DISAN ADDRADI ATAN'S	402	
	401	
TRIAXIAL ACCEL YAW AXIS (2)	401	
TRIATING AVOLL THE RATE INF	400	
TRIAXIAL ACCEL YAW AXIS (Z) TRIAXIAL ACCEL YAW AXIS (Z) BATIERY MONITOR VOLTAGE PITCH ACCELEROMETER YAW ACCELEROMETER THRUST ACCELEROMETER THRUST ACCELEROMETER THIRD STAGE CHAMBER PRESSURE	701	
DITCH ACCELEDANETED	702	
VAL ACCELERUNCTED	702	
THRUST ACCELEROMETER	702	
THIND STACE CHANGED DECEMBE	702	
DOLL ANCINAD DATE	/00	
DITCH INCH AD DATE	000	0600 0601
VAU ANGULAR RATE	467	0602
DOLL ATTITUDE BOODD	- 46A	0000
. DITCH ATTITUDE CORAD	401	0601
VAN ATTITURE CODOR	402	0602
POLL DAC ON ANADES ANTENT	400	0600
PITCH DAC OR ON/OFF OUTPUT	A01	0601
PITCH DAC OR ON/OFF OUTPUT YAN DAC OR ON/OFF OUTPUT	417	Q602
DARS CIP	R100	R200
PROGRAMMED POLY PATE	408	0600
PROGRAMNED DITCH PATE	404	0601
PROGRAMMED YAN DATE	402	0602
V RODY COORD ACCEL	403	0603
THRUST ACCELERATION	600	0603
5 VOLT REFERENCE	200	
INSTRUMENTATION GROUND	200	
HAIN ENGINE PITCH POSITION	200	
HAIN ENGINE YAW POSITION	204	
10 M NO 4 DITANIONIN DODITION	205	
VAES NUST PETPHZHULI POSTITON	205	
APP NOT AT AUDITION APP NOT ALLOWADE ADDITION	206	
V.F. NO.1 YAW POSITION V.F. NO.1 YAW POSITION	206	
V.F. NO.2 YAW POSITION V.E. NO.2 PITCH/POLL POSITION V.E. NO.2 PITCH/POLL POSITION V.E. NO.2 YAW POSITION	204	
V.F. NO.1 YAW POSITION V.F. NO.2 PITCH/POLL POSITION V.F. NO.2 YAW POSITION V.F. NO.2 YAW POSITION PITCH SUMMING APP OUTPUT	204	
V.F. NO.1 FIGHTROLL POSITION V.F. NO.2 PITCHTROLL POSITION V.F. NO.2 YAU POSITION PITCH SUMMING AMP OUTPUT YAU SUPMING AMP OUTPUT	206	
	VIE, NUIZ TAN POSITION Pitch Summing App Output Yaw Supming App Output	V.F. NO.2 YAN POSITION 206 PITCH SUMMING APP DUTPUT 204

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FAGE NO. 7

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MEASUREHELT	CHANNEL NO.	MEASURENE NAME	CATS21 PLOT NUMBERS
PDH=11=12	Cũ::-12	POLL SUMMING AND JUTPUT VE NO.1	.
PDH-11-13	CG11-13	ADEL SOFFICE AND JUIPUL VE NO.1	205
		SECUENCE NO. 9	203
PDM-11-14	CG11-14	SOLID NOTOR 10.4 CHAMBER PRESS	210
PDM=11=15	CG11-15	SOLID MOTOR NO.5 CHAMBER PRESS	210
PDH-11-16	CG11-16	SOLID MOTOR NO. SHAMBER PRESS	210
PDH=11-17	CG11-17	FEEDBACK POT EXCITATION (POS)	201
PDM-11-18		FEEDBACK POT EXCITATION (NEG)	201
PDM-11-19		SOLID MOTOR NO.7 CHAMBER PRESS	211
PDM-11-20		SOLID MOTOR, NO.3 CHAMBER PRESS	211
PDN#11=21	C 411-21	ACTUATOR EXCITATION (NEG)	201
PDH=11=22	CG11-22	V.E. NO.2 CHANBER PRESSURE	206
PDM=11=23	CG11-23	CONTROL BATTERY VOLTAGE	200
PDM-11-24	CG11+24	INSTRUMENTATION BATTERY VOLTAGE	200
PDM-11-25	CG11-25	HYNRAULIC SUPPLY PRESSURE	207
PDM-11-26	CG11-26	HYDRAULIC RETURN PRESSURE	
PDH-11-27	CG11-27	HYDRAULIC ACCUM PISTON POSITION	207
PDM=11=28	CG11-28	SEQUENCE NO.2 S.M. SET NO.2 + 3	207
PDM=11=29	CG11-29	SOLID MOTOR POT EXCITATION	202
PDH-11-30	CG11-30	SEQUENCE NO.4	200
PDH=11=31	CG11-31		202
PDM-11-32		SEQUENCE NO.3 S.H. SET NO.3	20 <u>5</u>
	CG11-32	SEDUENCE NO.6 S.M. SET NO.2	203
PDM-11-33	CG11-33	ENGINE PNEUMATIC BOTTLE PRESS	208
PDM+11-34	CG11-34	ACTUATOR EXCITATION (POS)	201
PDM-11-35	CG11-35	SEQUENCE NO.7 S.M. SET NO.1	203
PDH=11-36	CG11-36	SEQUENCE NO.5	202
PDM-11-37	CG11-37	SOLID MOTOR NO.1 CHAMBER PRESS	209
	CG11-38	SOLID MOTOR NO.2 CHAMBER PRESS	209
PDM-11-39	CG11=39	SEQUENCE NO.8 S.H. SET NO.1	203
	C011-40	HAIN FUEL TANK TOP PRESSURE	208
	CG11-41	SOLID MOTOR NO.3 CHANBER PRESS	209
	CG11-42	LOX TANK TOP PRESSURE	208
PDH=11=43	CG11-43	SOLID MOTOR NO.9 CHAMBER PRESS	211
	CG12-01	5 VOLT REFERENCE	300
	CG12-02	INSTRUMENTATION GROUND	300
PDM-12-03	CG12-03	FUEL PUMP INLET TEMPERATURE	308
₽DM+12-07	CG12-07	MAIN ENGINE CHAMBER PRESSURE	308
	CG12-08	GG COMBUSTION TEMPERATURE	306
	CG12-10	GG LOX INJECTOR PRESSURE	306
	CG12-11	LOX PUMP INLET TEMPERATURE	305
	CG12-12	12.35 VOLT BIAS	
	CG12-13	V.E. NO.1 HOUSING TEMPERATURE	300
	CG12+14	V.C. NO 2 HOURING TEMPERATURE	301
	CG12-15	V.F. NO.2 HOUSING TEMPERATURE	301
	CG12-16	H.E. PITCH ACTUATOR TEMPERATURE	302
	CG12-17	AIR CONDITIONING INLET TEMP	301
		SKIRT SECTION TEMPERATURE	301
PDM-12-21		GENTER BODY SKIN TEMPERATURE	307
	CG12-23	M.E. PITCH SERVO DIFF. SIGNAL	302
	CG12-24	VE 1 PITCH/ROLL SERVO DIFF SGNL	303
PDH=12=25	C012-25	VE 2 PITCH/ROLL SERVO DIFF SGNL	303

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946: NO.

DATA PED CTICH ENGINEERING OPERATION PLAN FOR RECHILE, NO. - DELTA

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"EAS, DEVEN	T CHANNEL "	NC.	MEASUREHENT NAME	CAT+21 PLO" NUMBERS
P3M-12-26	0610 04			
PDH=12-27			HIE, YAN SERVO DIFF. SIGNAL	302
PDH-12-28			VE 1 TAH SERVO DIFF. SIGNAL	303
PDM+12=20	0412-24		VE 2 TAN SERVO DIFF. SIGNAL	393
PDH+12+30			VE 1 YAH SERVO DIFF. SIGNAL VE 2 YAH SERVO DIFF. SIGNAL +10 VDC TRANSDUCER POHER -10 VDC TRANSDUCER POHER -10 VDC TRANSDUCER POHER	300
PDH=12=31	CGTS-30		-10 VUC TRANSDUCER POWER	300
PDH-12-31 PDH-12-37 PDM-12-33	CG12-31 CG12 TO		HYDRAULIC ACCUM TEMPERATURE HYDRAULIC ACCUM GN2 PRESSURE	304
PDN=12-33	C612-32		HTDRAULIC ACCUM GN2 PRESSURE	304
PDH=12-36	CG12-34		HELIUH BOTTLE PRESSURE	305
PDM#12-37			CENTER BODY AIR TENPERATURE	307
PDH=12=38	CG12-38		THRUST CHAMBER DONE OXID PRESS	
PDM=12=39	CG12-39		LUBE SYSTEM PRESSURE	308
PDH-12-40	CG12-40		GG FUEL INLET PRESSURE	306
PDH-12+42	CG12-43		THRUST CHMBR DOME FUEL INJ PRESS	308
PDH=12-43	CG12-43		POGO NO. 2 LOX ACCUHULATOR TEMP	307
PDH-21-01			POGO NO. 1 LOX ACCUMULATOR TEMP 5 VOLT ABSOLUTE	307
PDN-21-02			T YULI AUSULUTE	500
PDH-21-03			INSTRUMENTATION GROUND	500
PDM-21-04			VAN SUMMING AMP OUTPUT VALVE EXCITATION (POS)	502
PDH-21-05			PALYE CADITATION (POS)	503
PDM+21-06	CG21-06		EVENT GROUP NO.1	506
PDH=21-07	CG21+07		VALVE EXCITATION (NEG) G.C. LOGIC VOLTAGE	503
PDH-21-08				508
PDH=21-09			ROLL/PITCH JET ACT - SECONDARY	504
PDH+21-10			PITCH ACTUATOR POSITION CDR NGT 1 AGC INU BLOCK TEMPERATURE ENGINE BATTERY CURRENT YAN ACTUATOR POSITION EVENT GROUP NO A	505
PDN+21-11	6621-11		181	507
PDN=21+12	CG21-12		ENGINE BATTERY AUDIONS	508
PDH=21=13	CG21+13		VAN ACTUATOR DESITION	501
PDH+21-14	CG21-14		SVENT GROUP NO A	502
PDN+21-15	CG21-15		EVENT GROUP NO.8	506
PDM#21#16	CG21-16		EVENT GROUP NO.4 EVENT GROUP NO.4 EVENT GROUP NO.5 NITROGEN BOTTLE PRESSURE 5 YOLT POT EXCITATION	506
PDH#21-17	CG21+17		S VOLT FOT FIRITATION	510
PDN+21-18	CG21-18		S VOLT POT EXCITATION PITCH SUMMING AMP OUTPUT PITCH SERVO DIFFERENTIAL STOLL	500 505
PDH-21-19	CG21-19		PITCH SERVO DIFFERENTIAL SIGNAL	505
PDN-21-20			OUNTNUL BATTERY VOLTABE	501
PDN=21=21	CG21-21		INGTRUNGNTATION BATTERY VOLTAGE	500
PDN=21-22	CG21-22		OXIDIZER TANK PRESSURE	510
PDM-21-27	CG21-23		HYDRAULIC SYSTEM PRESSURE	509
PDM-21-24	CG21-24		FEEDBACK POT EXCITATION (Pos)	503
PDM-21-25			FEEDBACK POT EXCITATION (NEG)	503
PDH-21-26	CG21-26		HYD MOTOR PUMP YEMPERATURE	# ĂO
PDH#21-27			NITROGEN REGULATOR PRESSURE	510
PDH#21-28	CG21-28		NITROGEN REGULATOR PRESSURE OXIDIZER LINE TEMPERATURE	510
PDH=21-20	CG21-29		HTDRAVGIC STSTEM RETURN PRESSURE	509
PDN=21=30	CG21-30 CG21-31		CDR NO, 2 AGC	507
PDN=21=31	0621-31		GC HEHORY VOLTAGE	508
PDM-21-32			INU GYRO EXCITATION	508
PDM-21-33	C421-33		IST STAGE POLL CONTROL SIGNAL	904
PDM-21-34	CG21-34		EVENT GROUP NO.2	506
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PAGE NO. 9

DATA RED UTION EXCENSERING OPERATION RUAN FOR JECHILE NO. DELTA

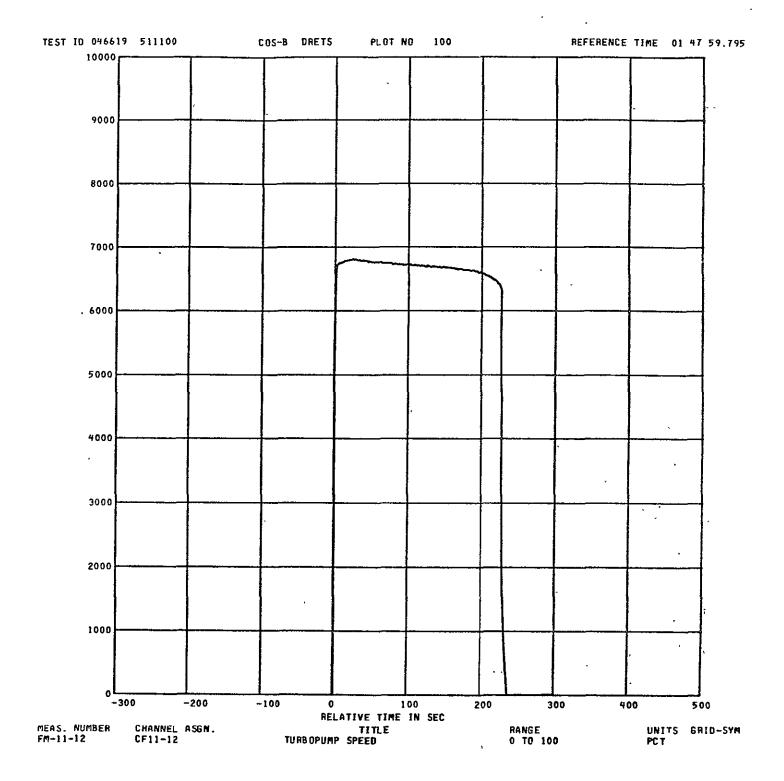
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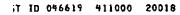
HETZ STHE .	CHARMEL HO.	. MEASUREHENT NAME	CAT#21 PLOT NUMBERS
PDM+21+35	C621-35	THE LOGIC VOLTAGE	508
PDM#21+36	CG21-36	YA. SERVO DIFFERENTIAL SIGNAL	502
PD%#21#37	CG21-37	HELIUM BOTTLE PRESSURE	511
PDM#21-38	CP51-38	HELIUM REGULATED PRESSURE	511
PDF#21=30	C621-39	FUEL LINE TEMPERATURE	511
PDF#21=4r	C621-40	PITCH/ROLL JET ACT - SECONDARY	504
PDH=21-44	CG21-41	YAN JET ACTUATION-SECONDARY	502
PDM=21-42	CG21+42	FUEL TANK PRESSURE	511
PDM=21+43	CG21-43	ENGINE BATTERY VOLTAGE	501



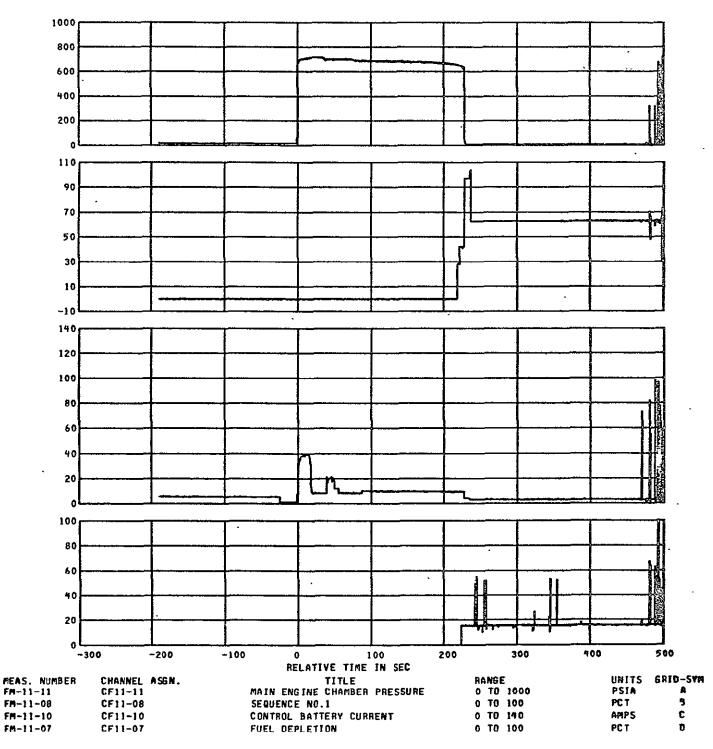
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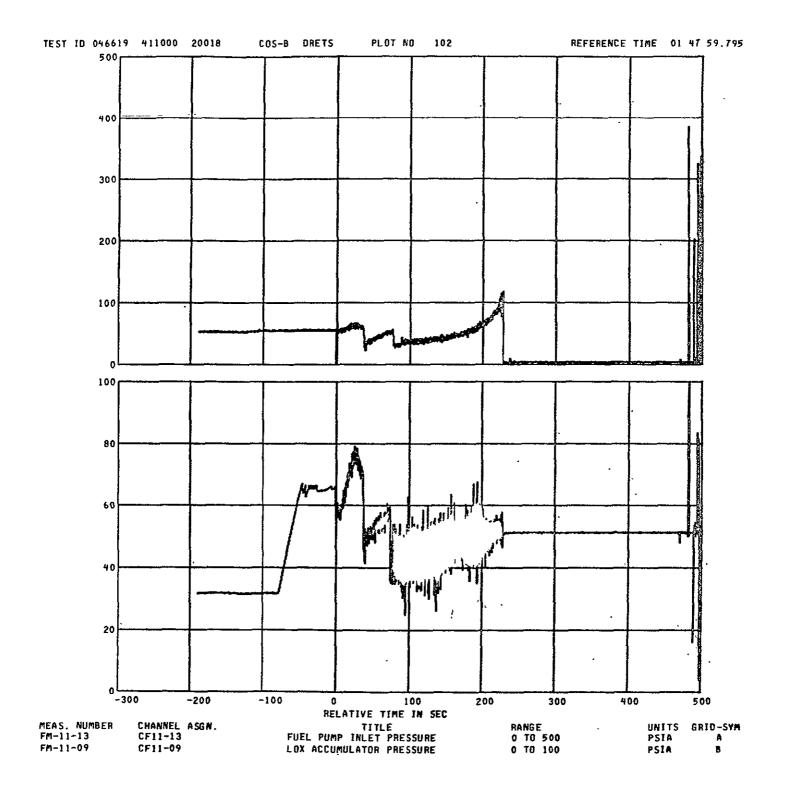
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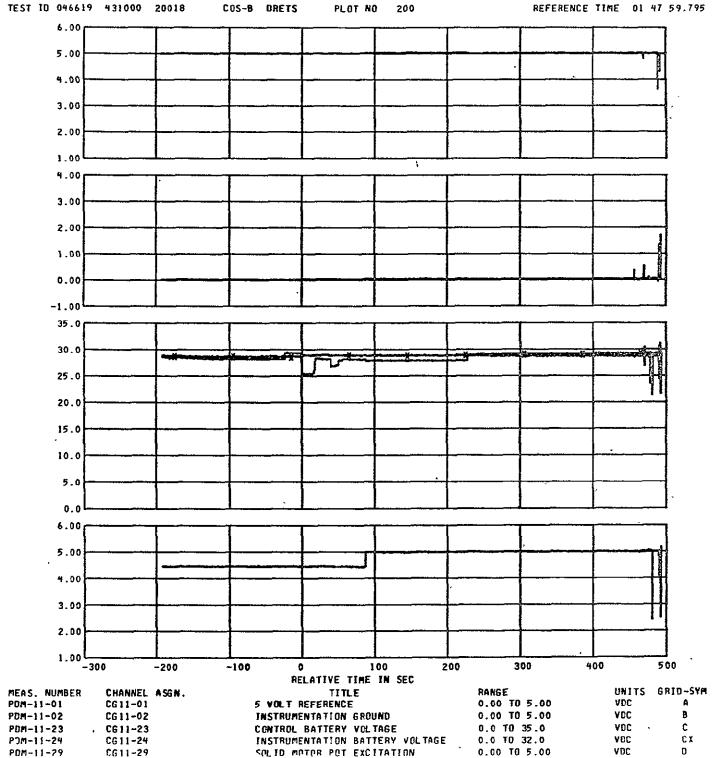




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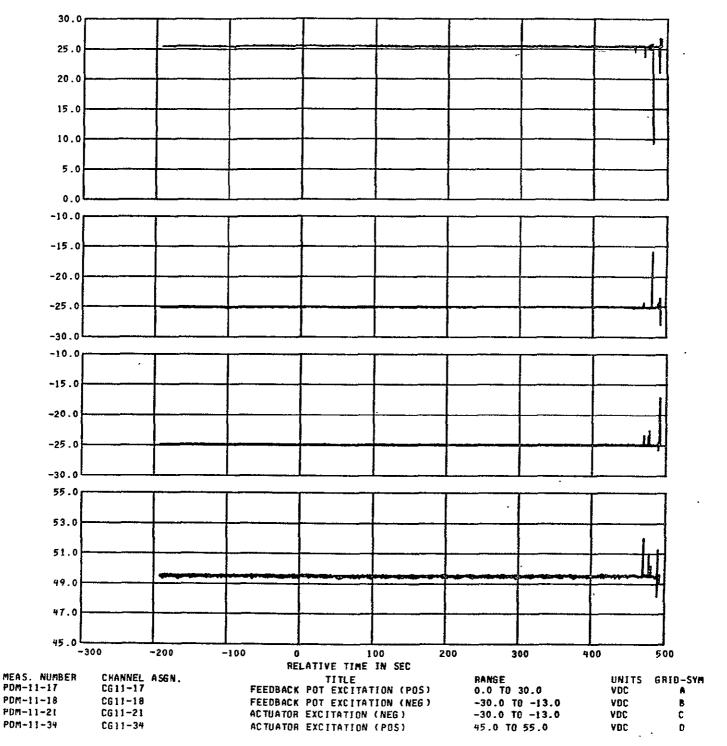




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TEST ID 046619 431000 20018

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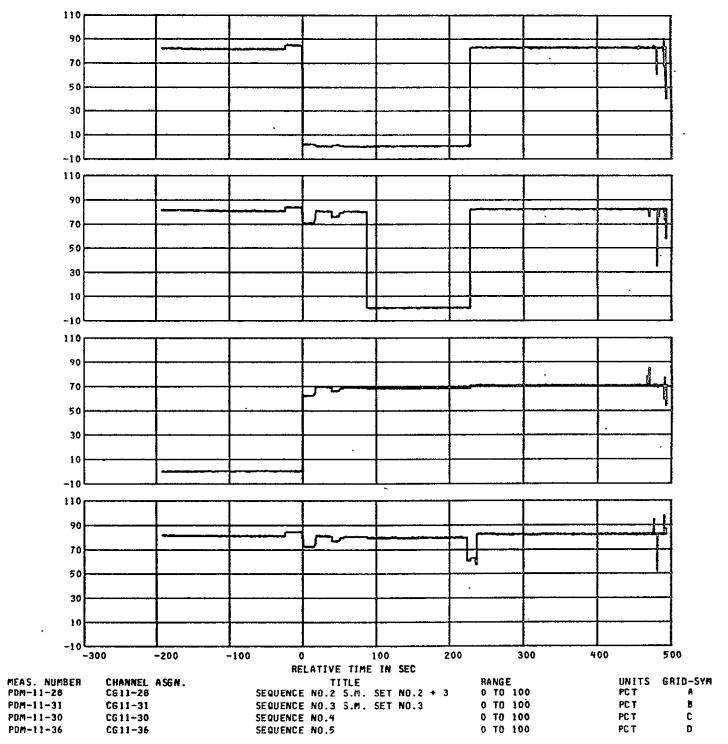
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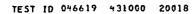
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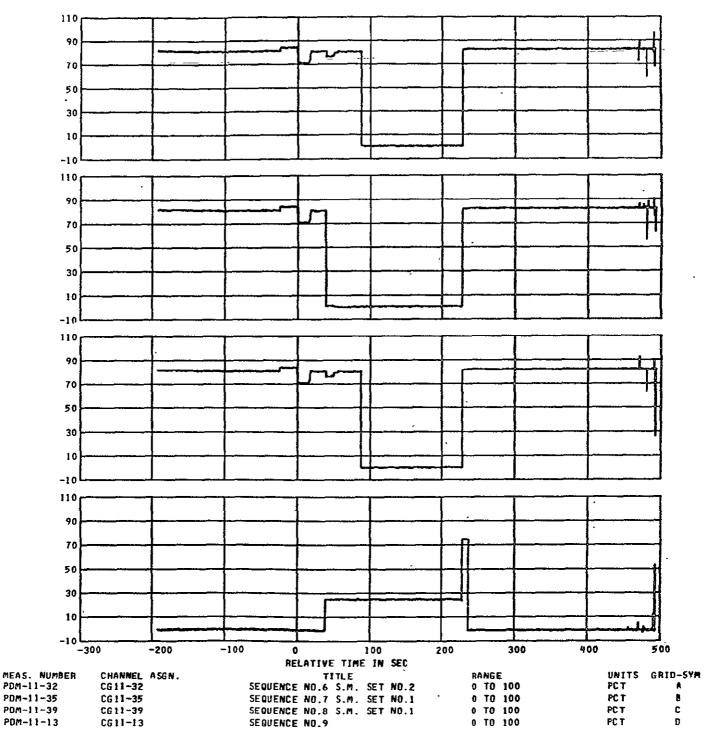
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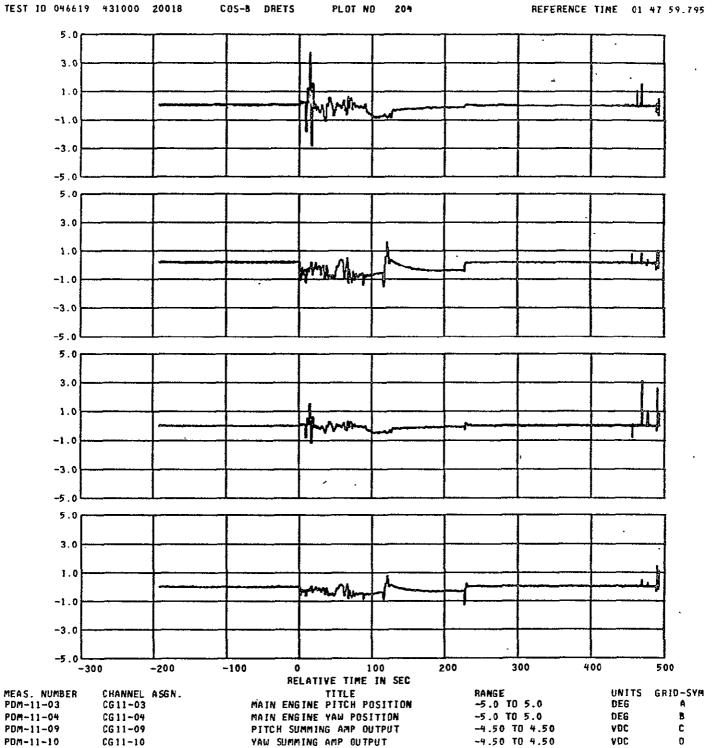
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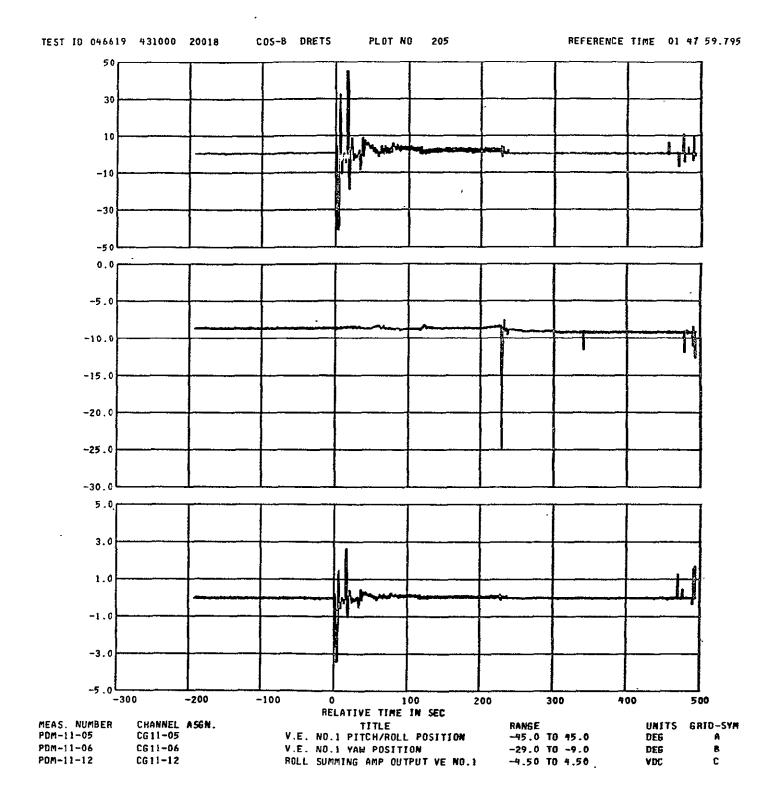
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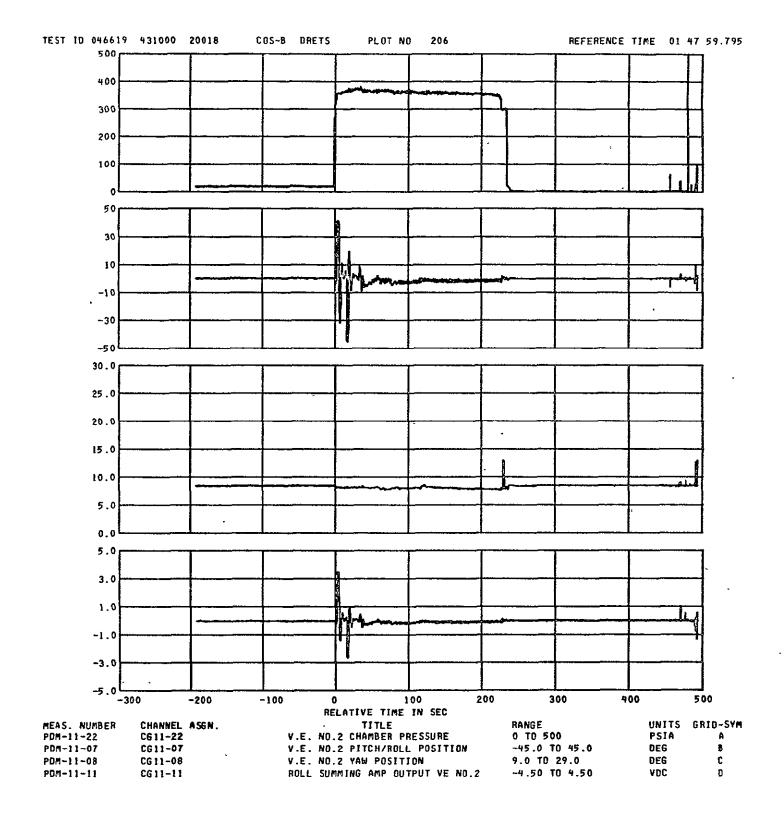
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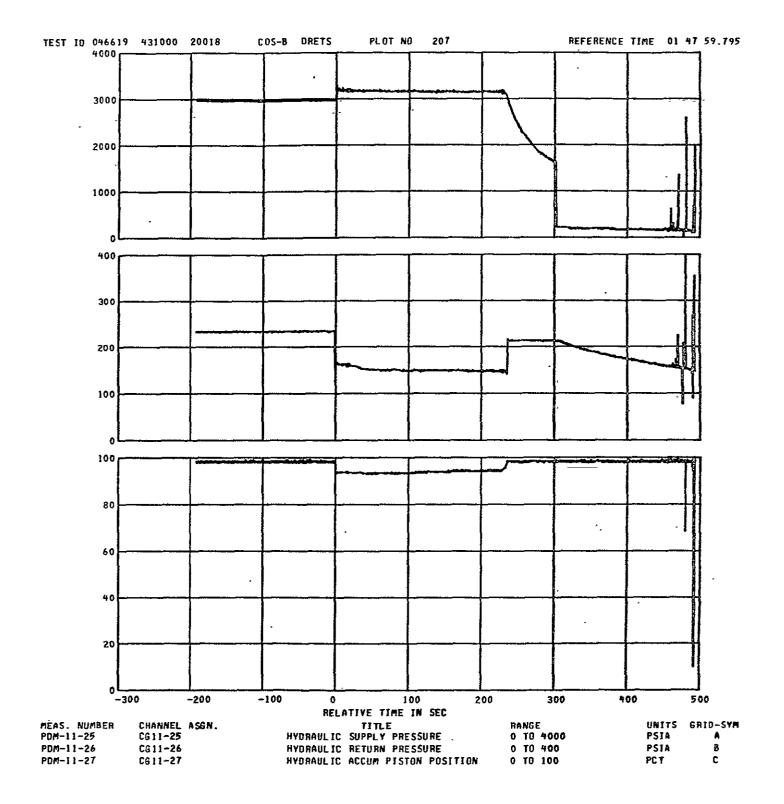


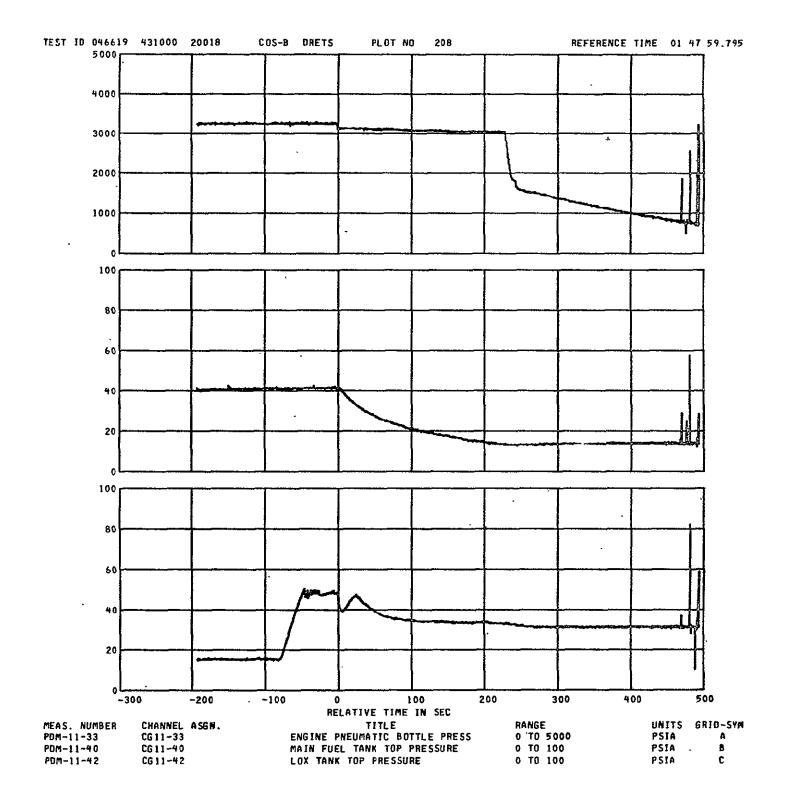
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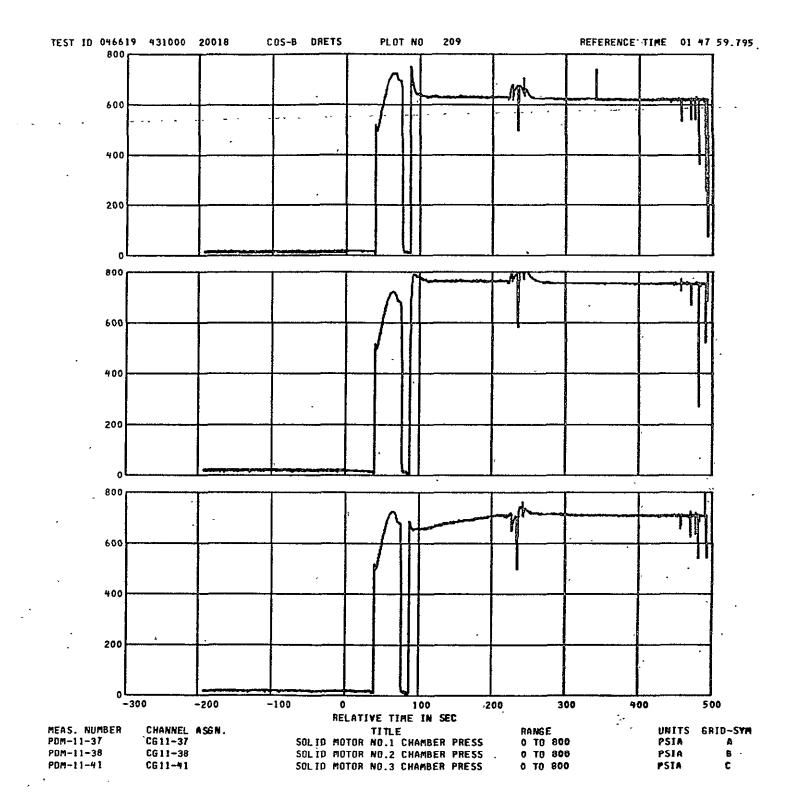


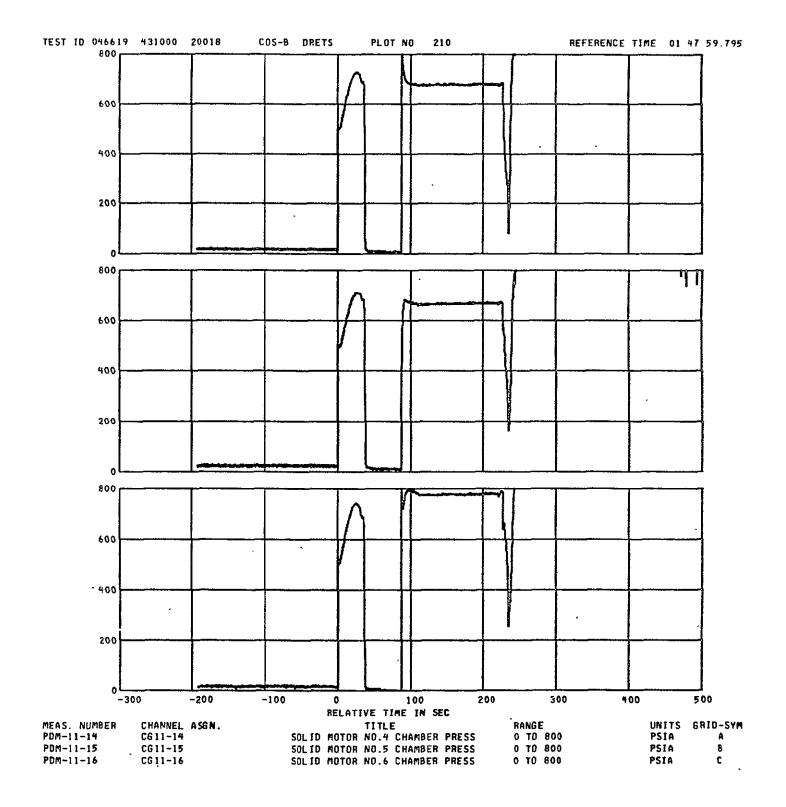


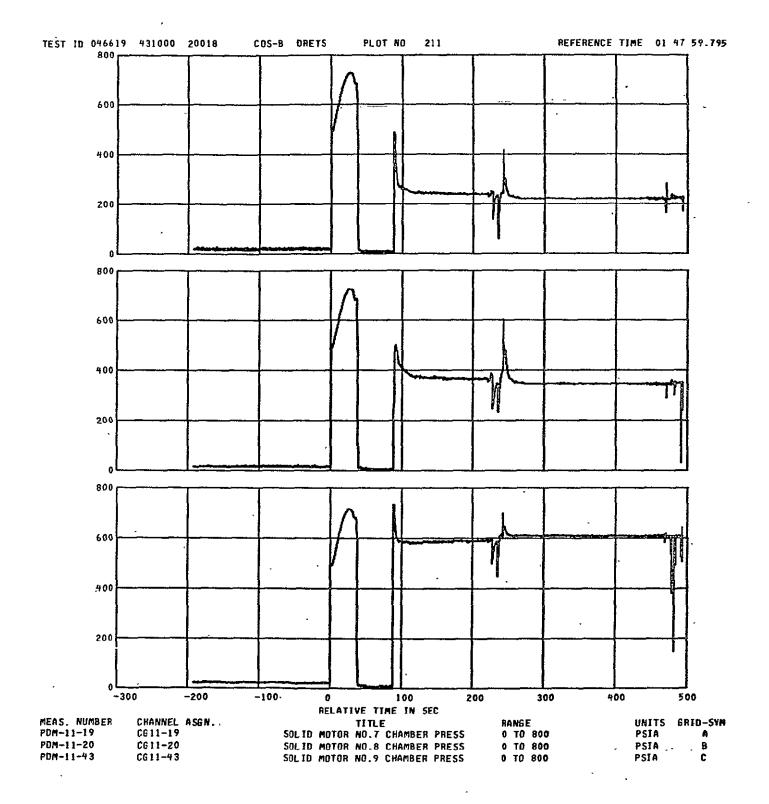
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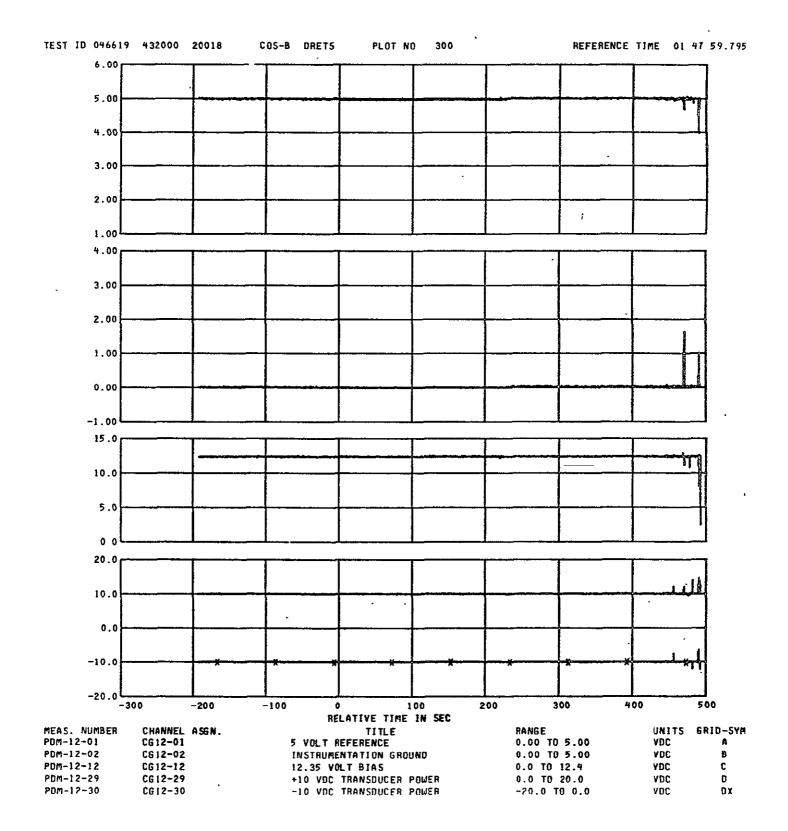


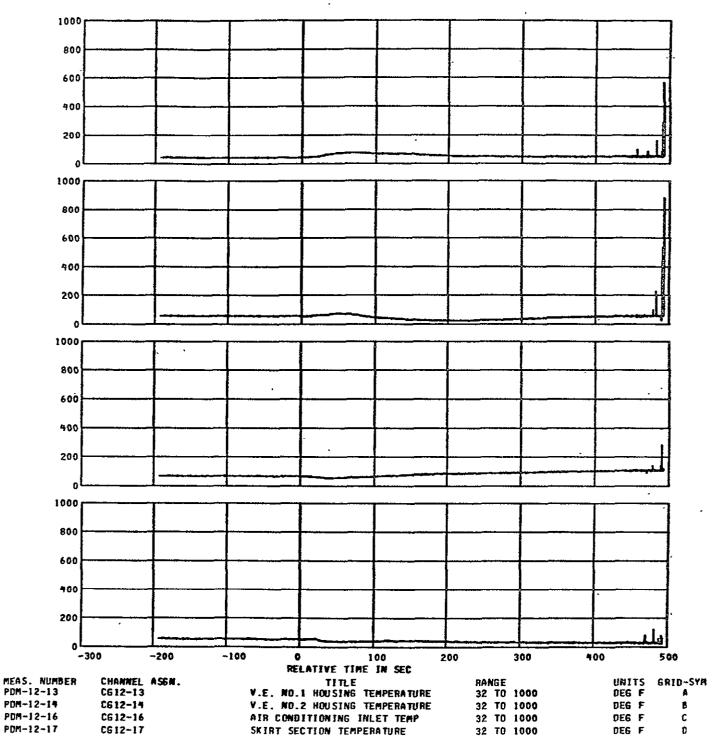






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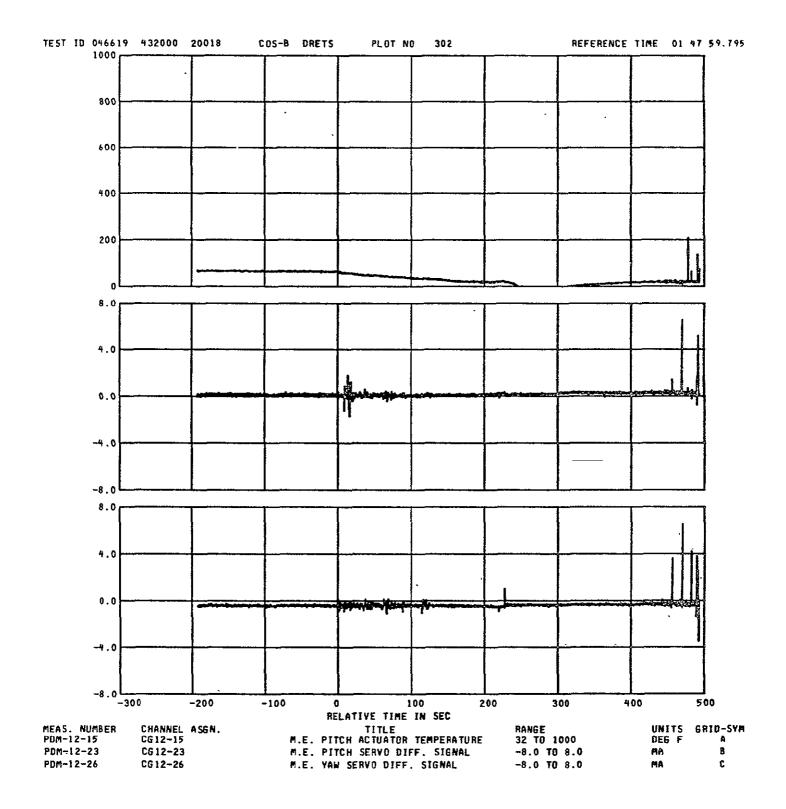


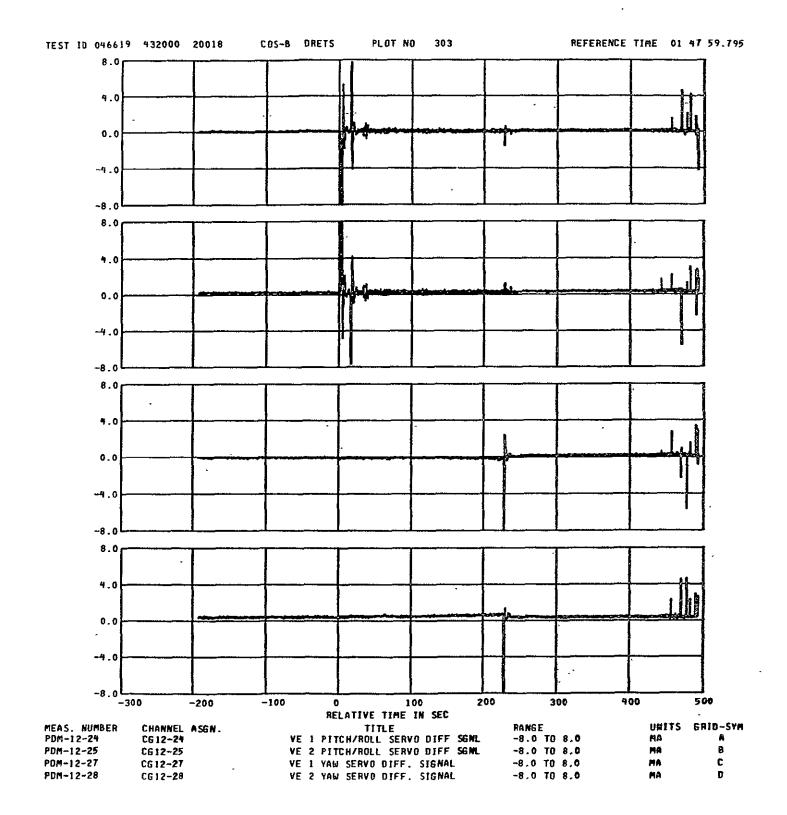
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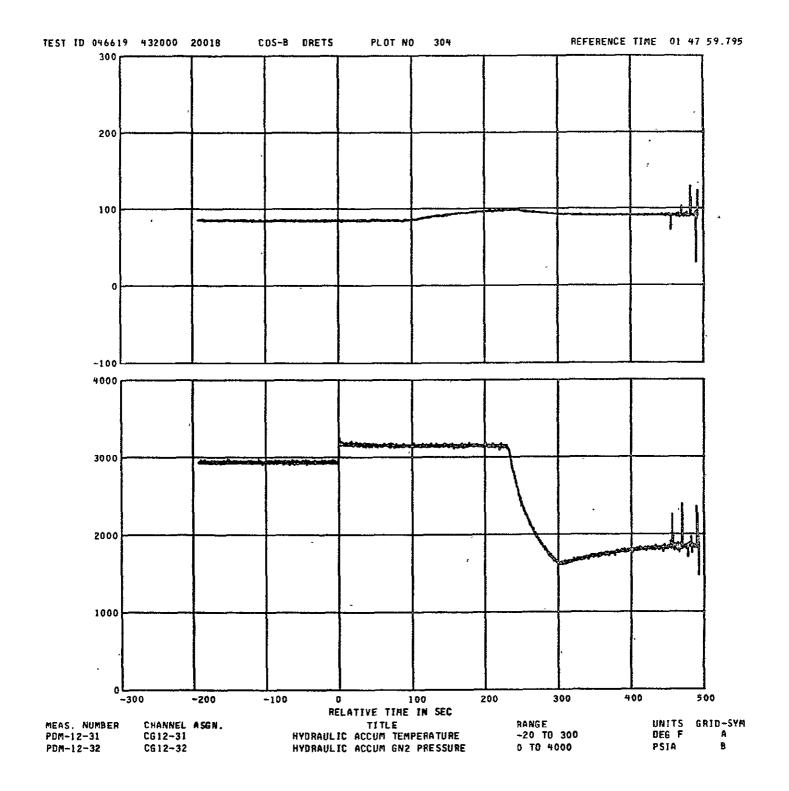
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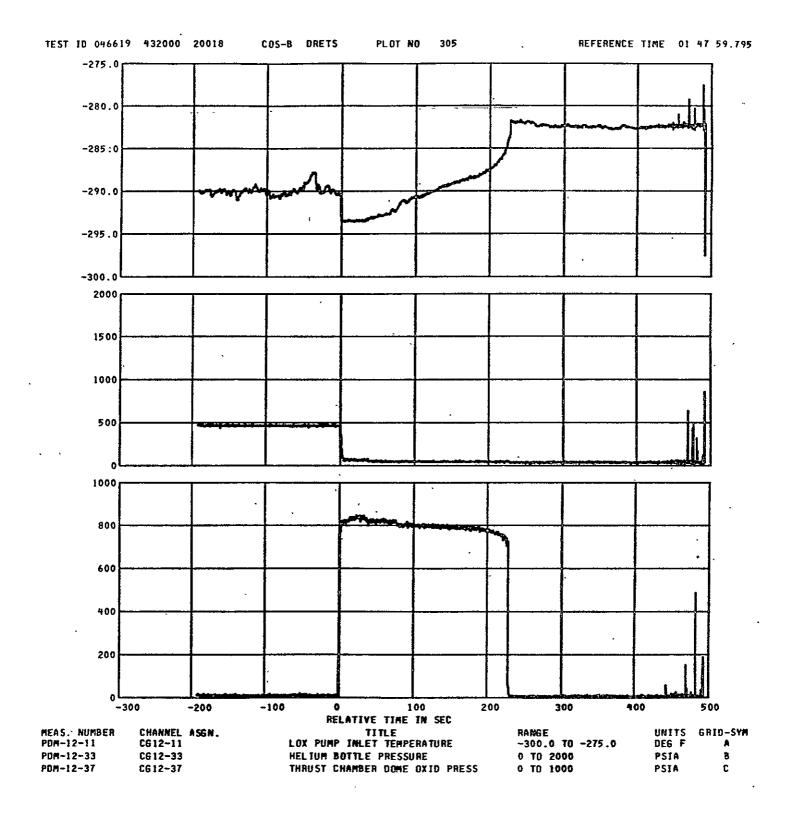
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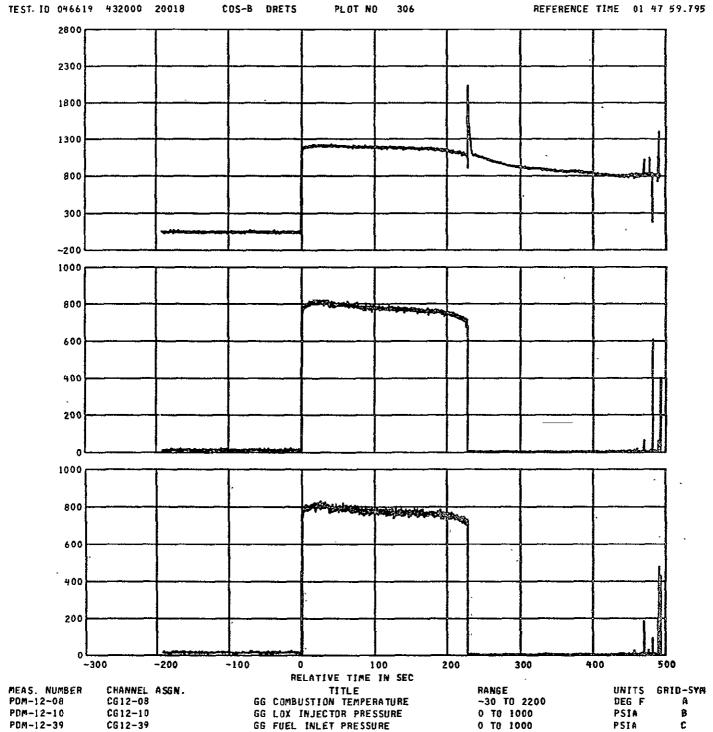




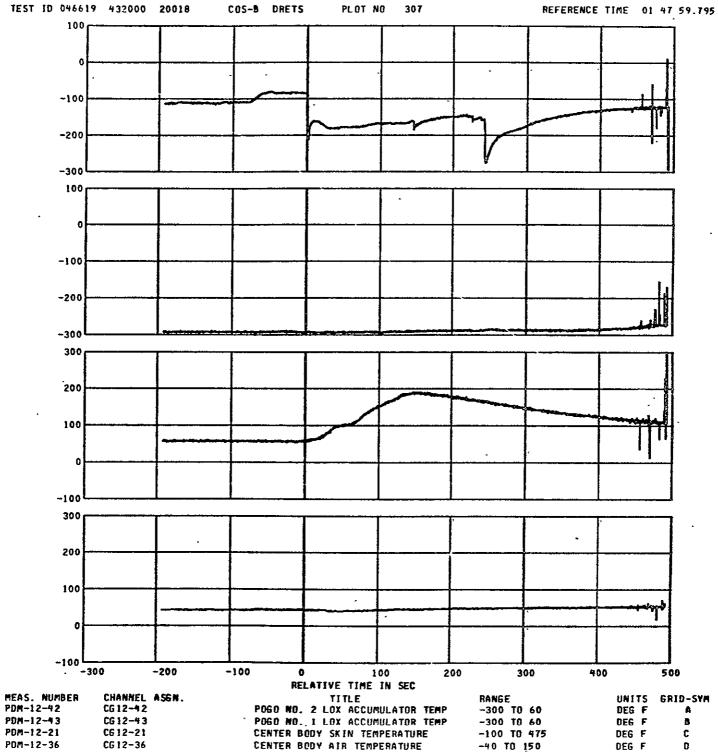
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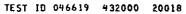




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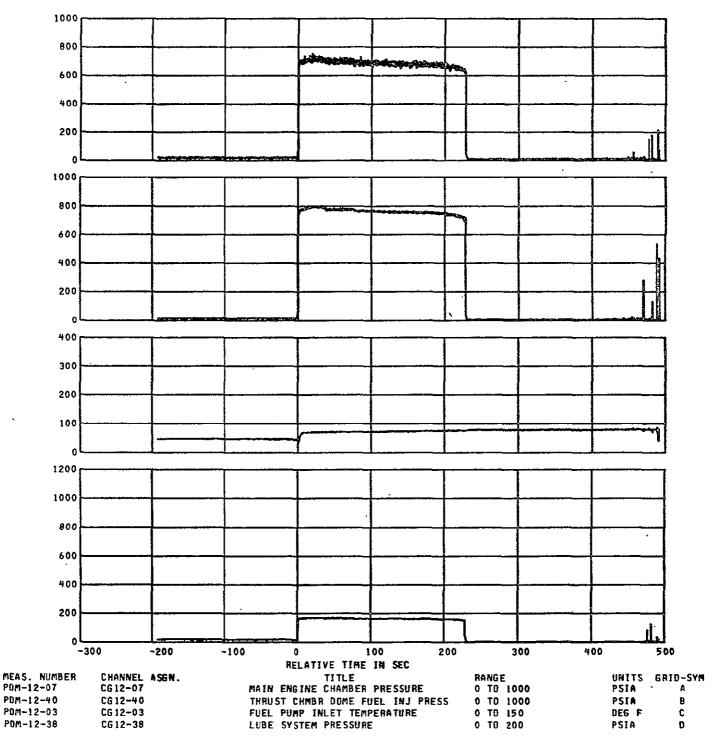
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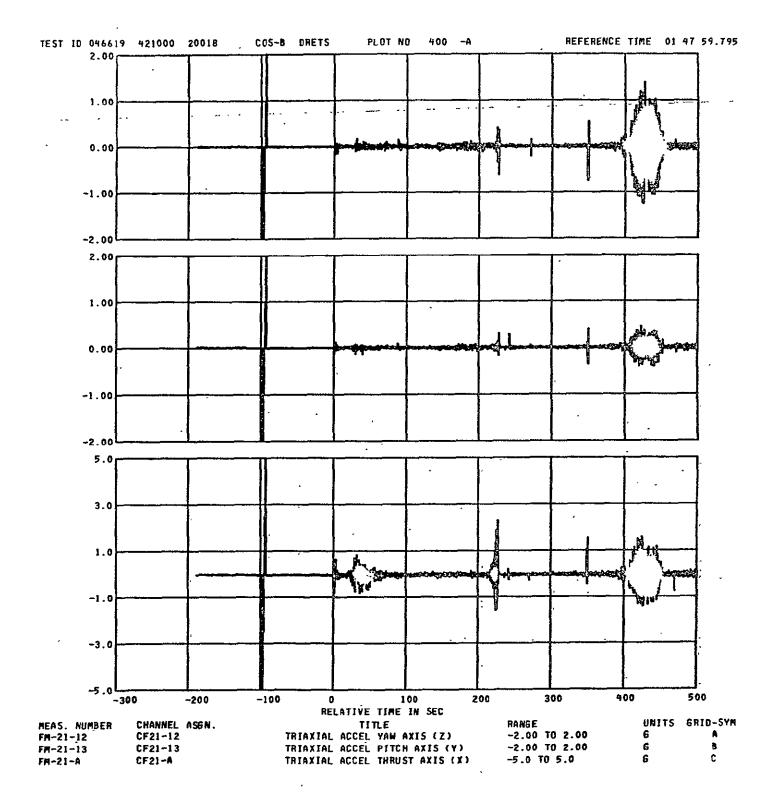


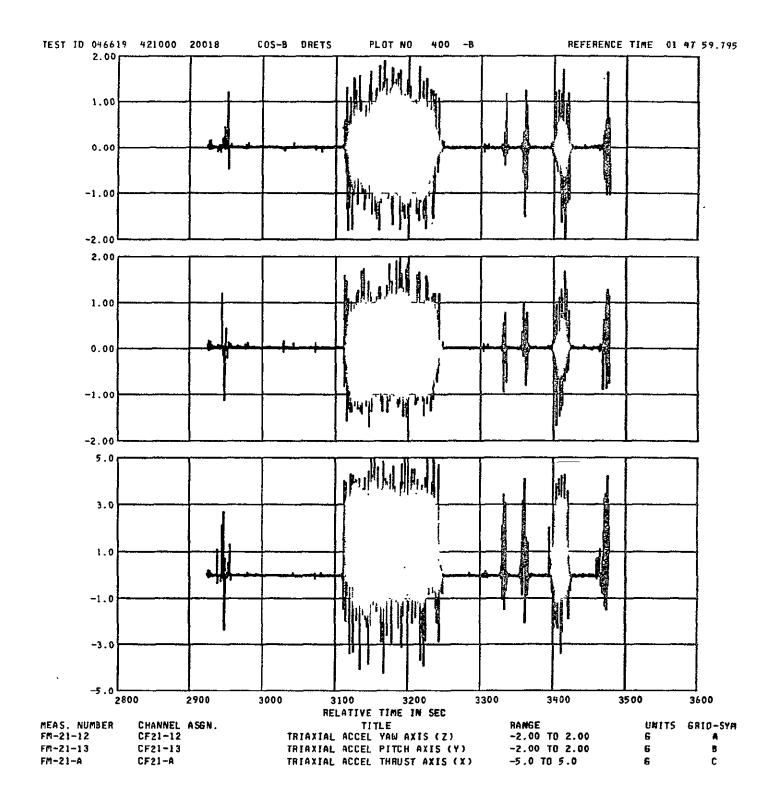
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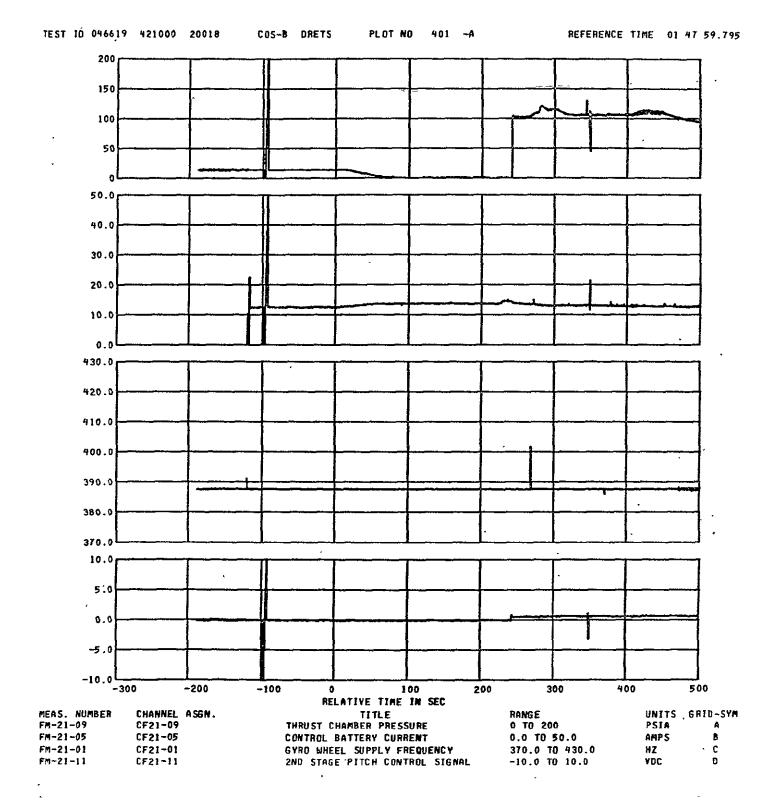
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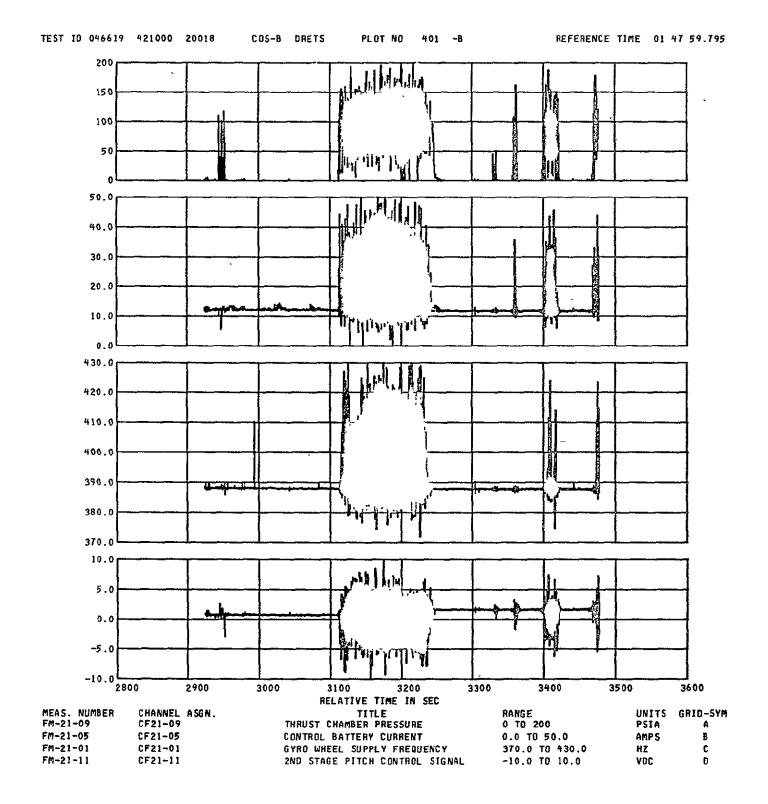
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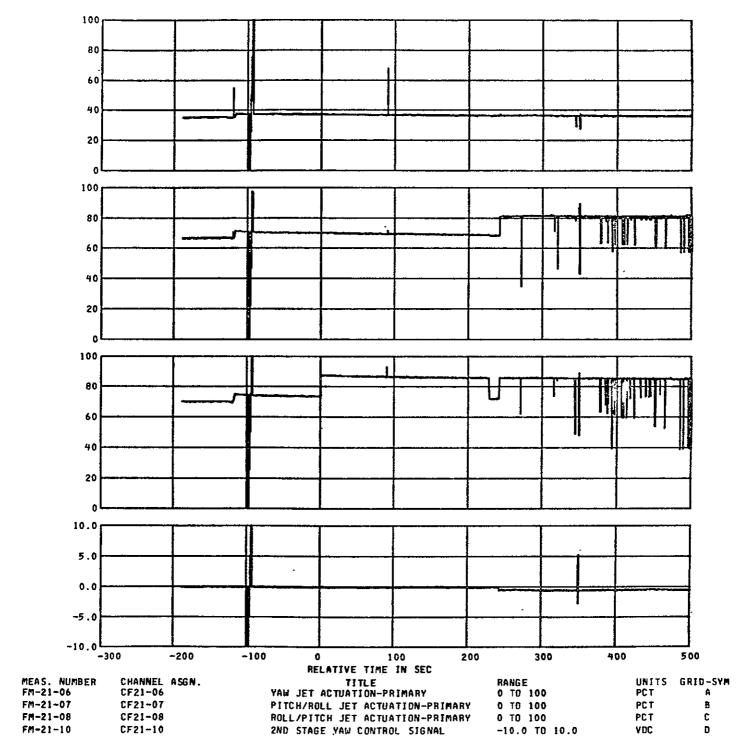










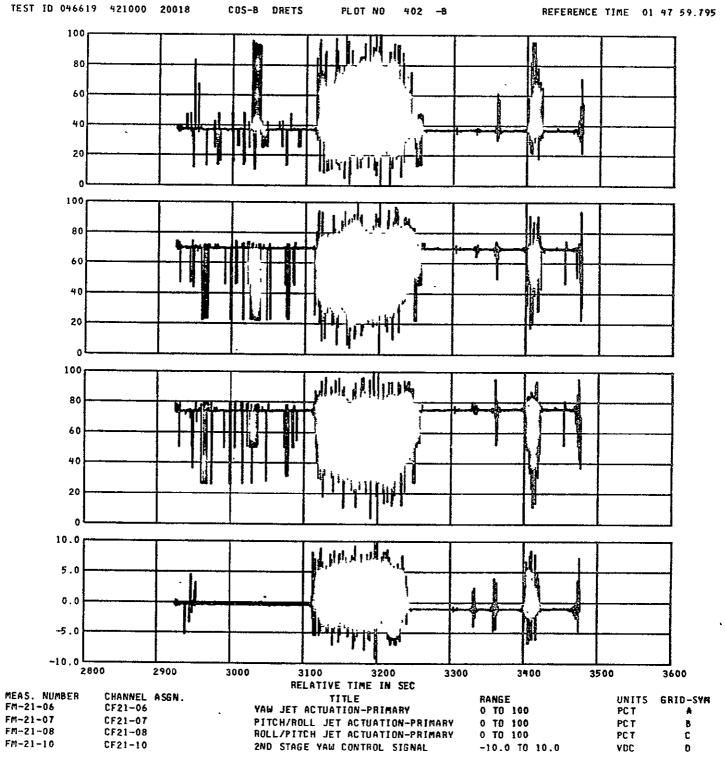


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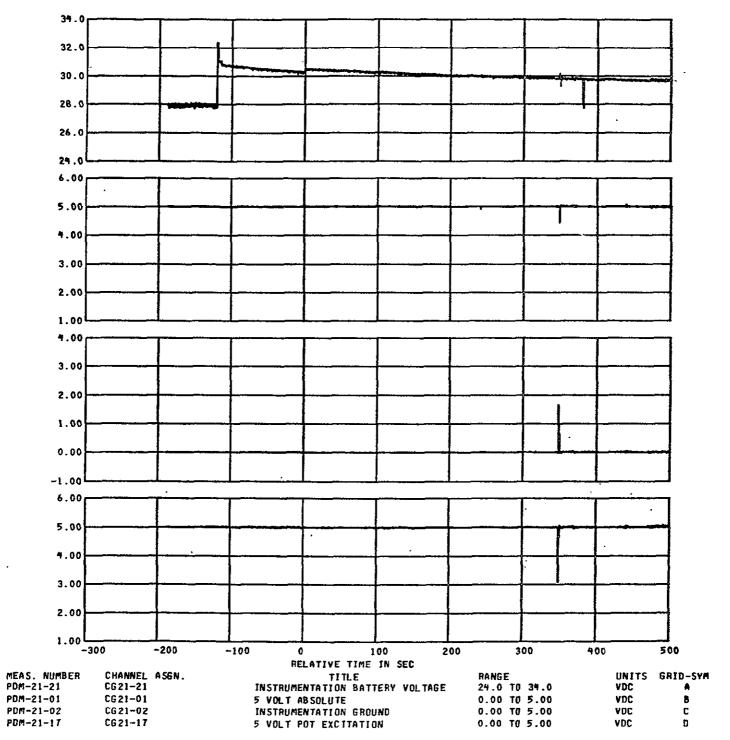


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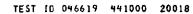
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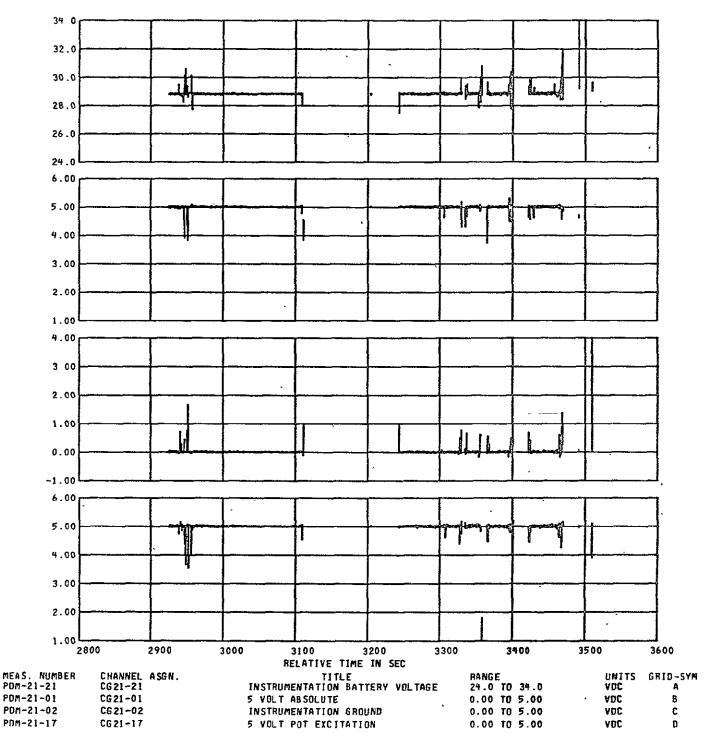
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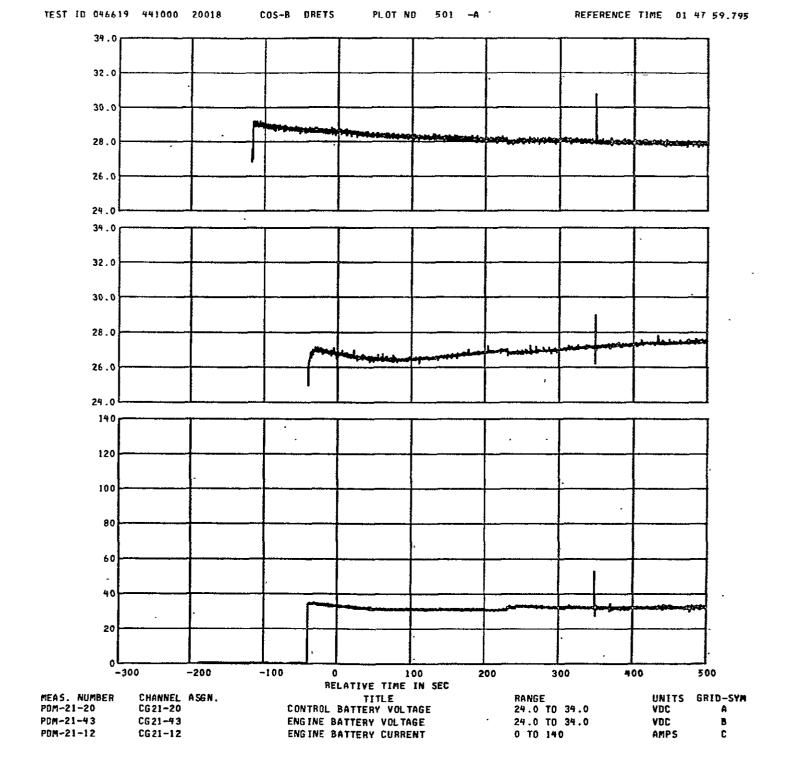


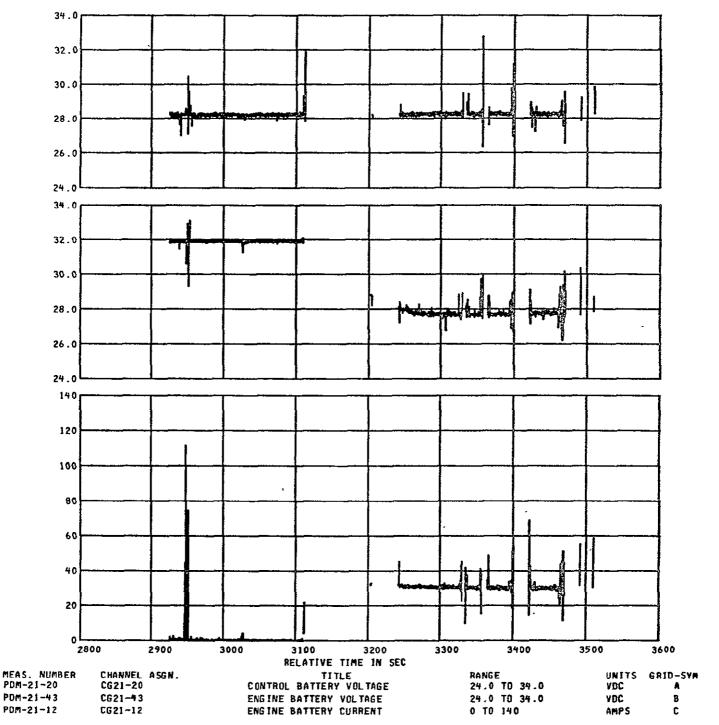
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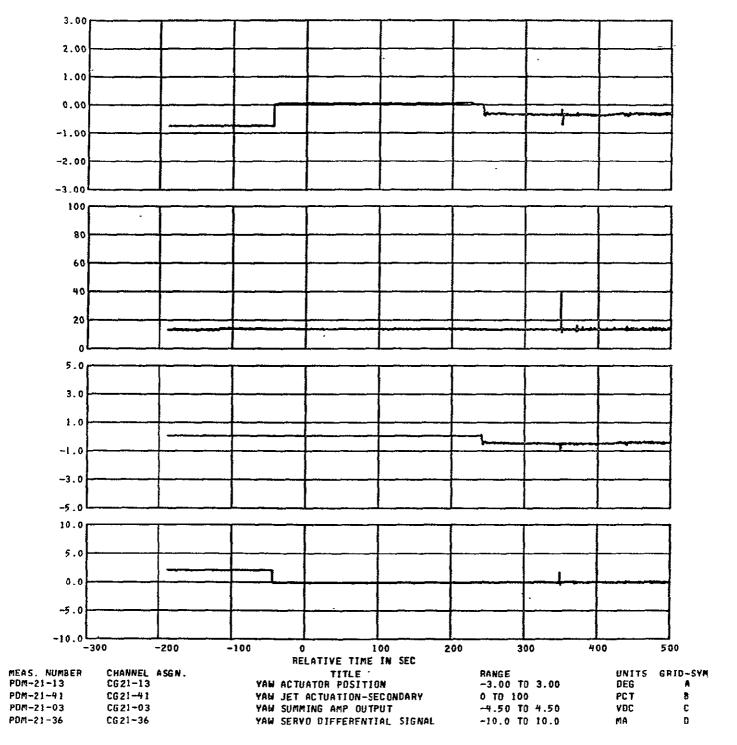
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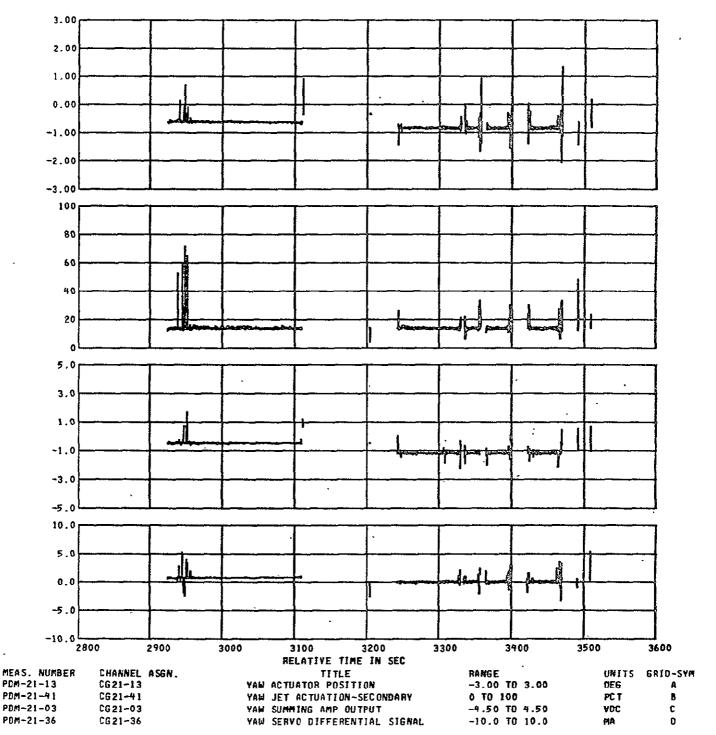
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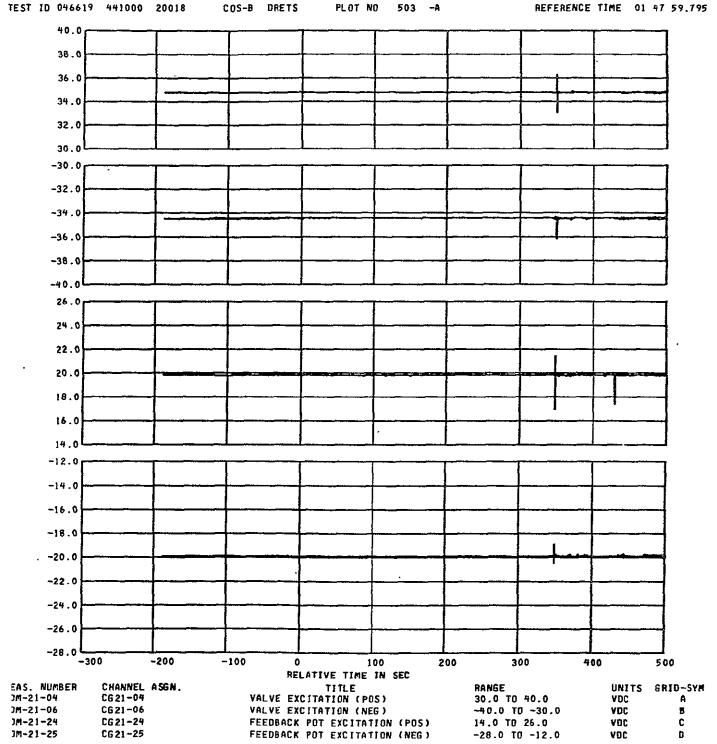
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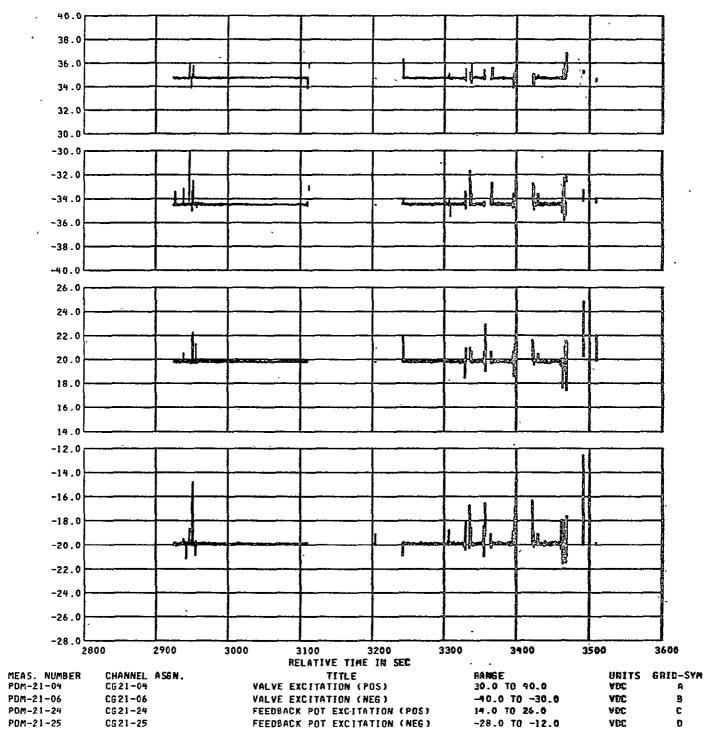
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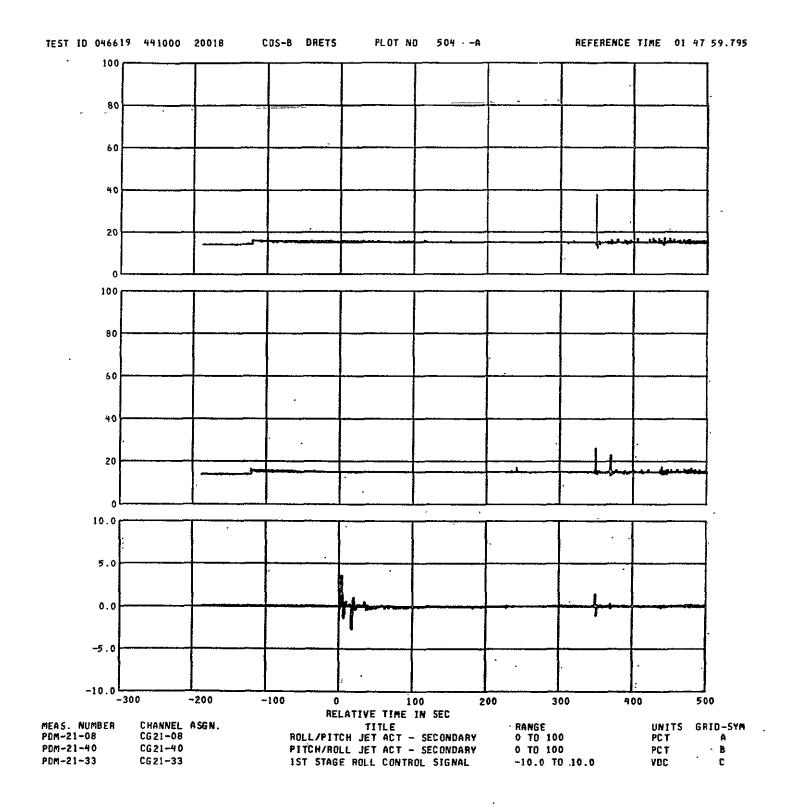


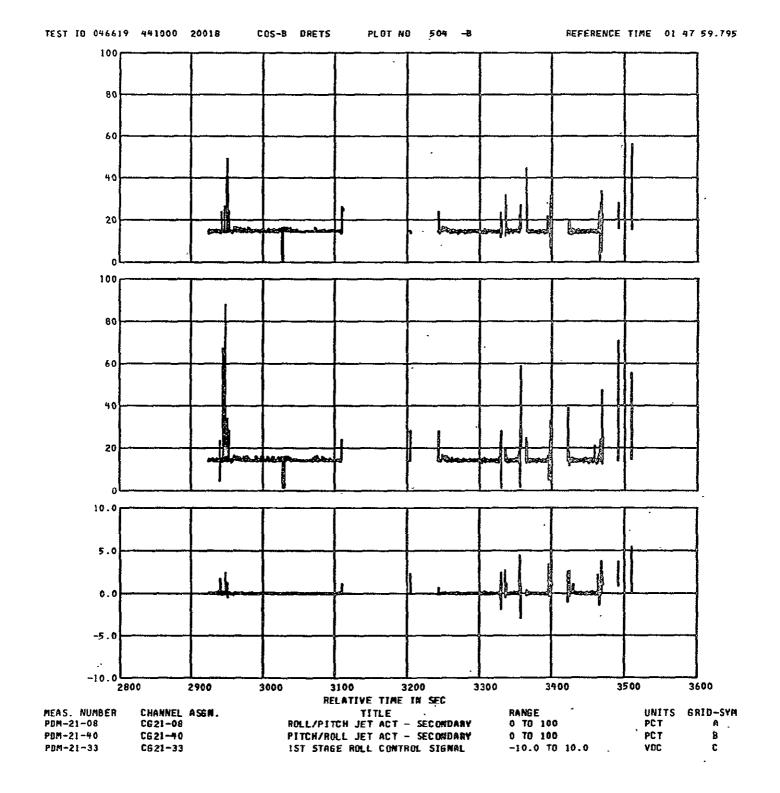


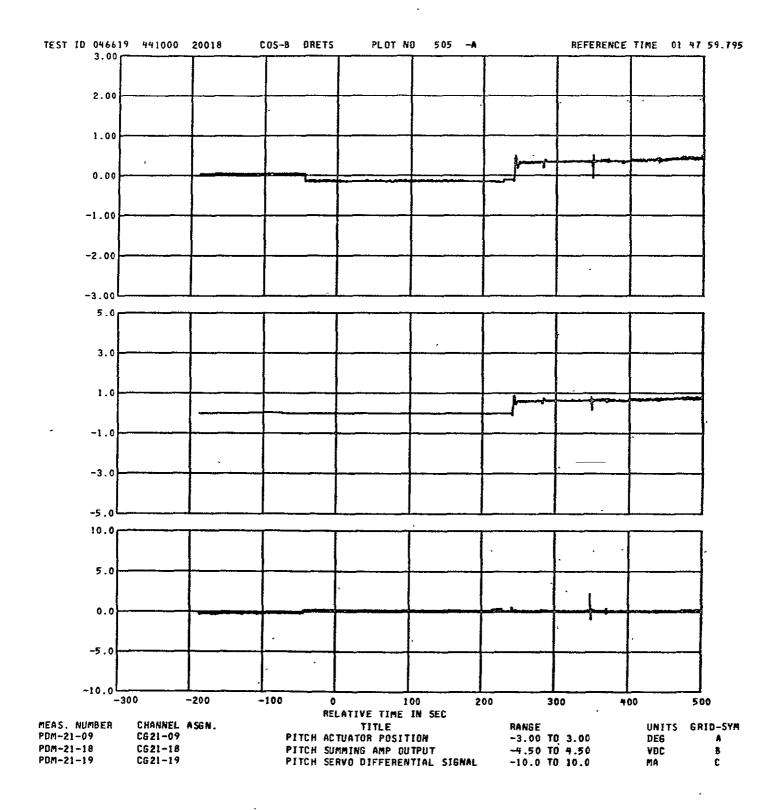
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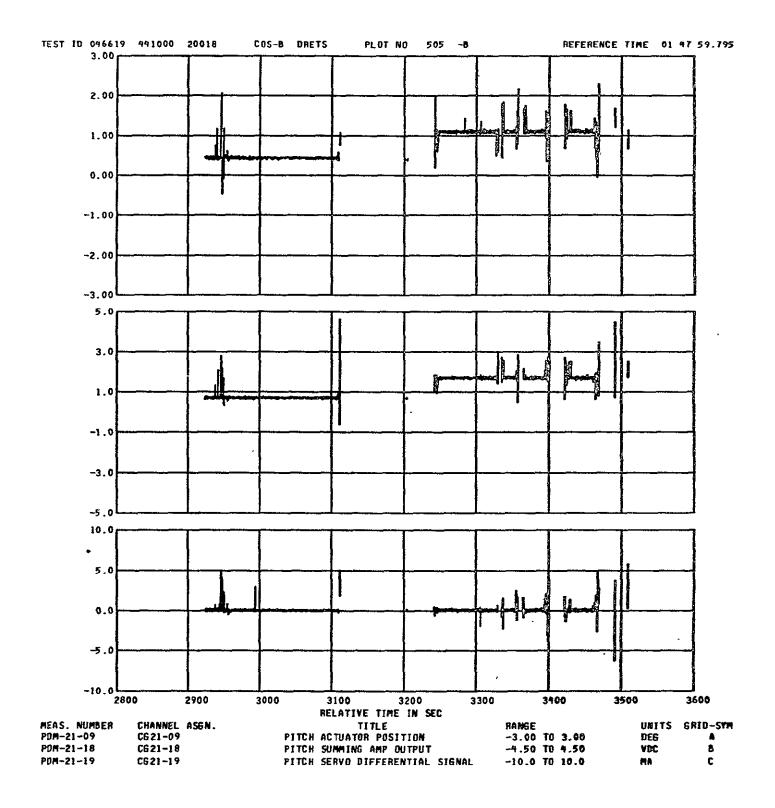
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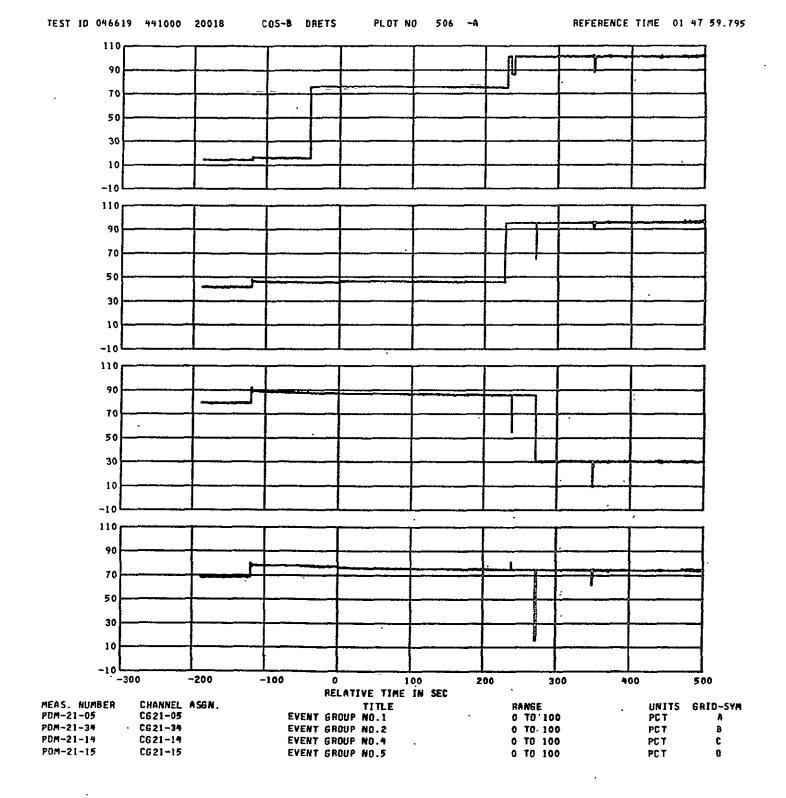


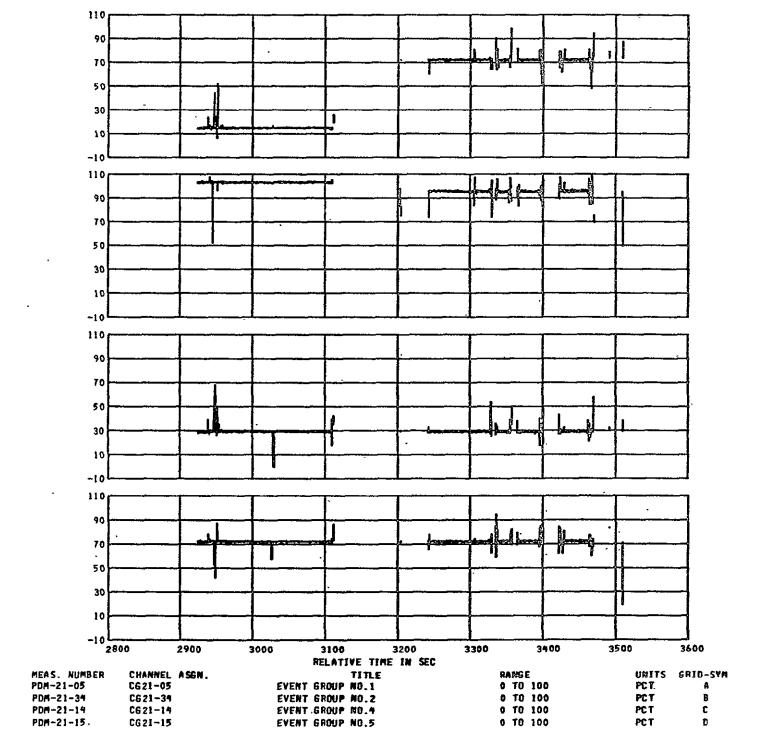




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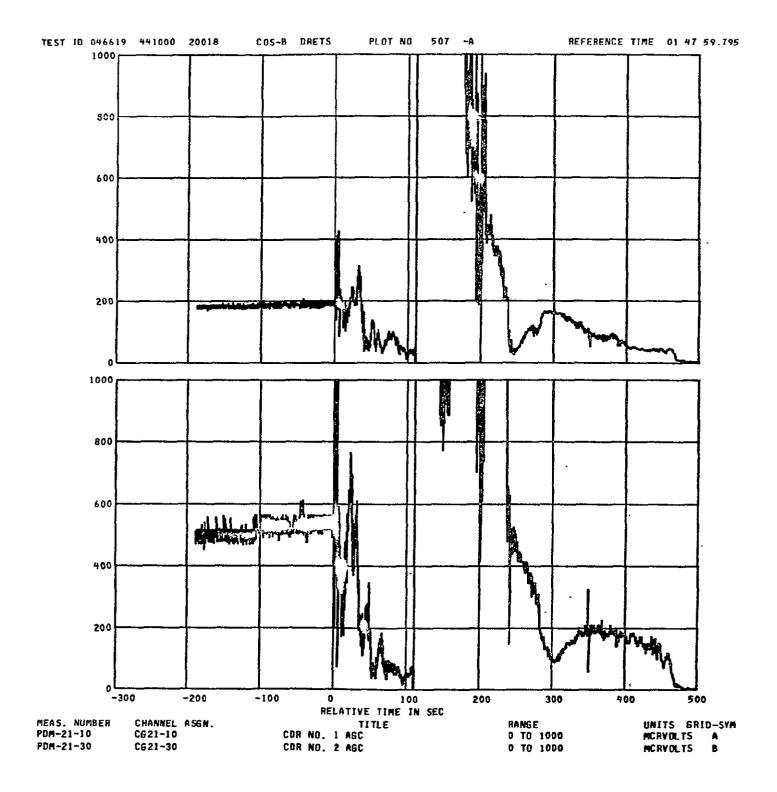


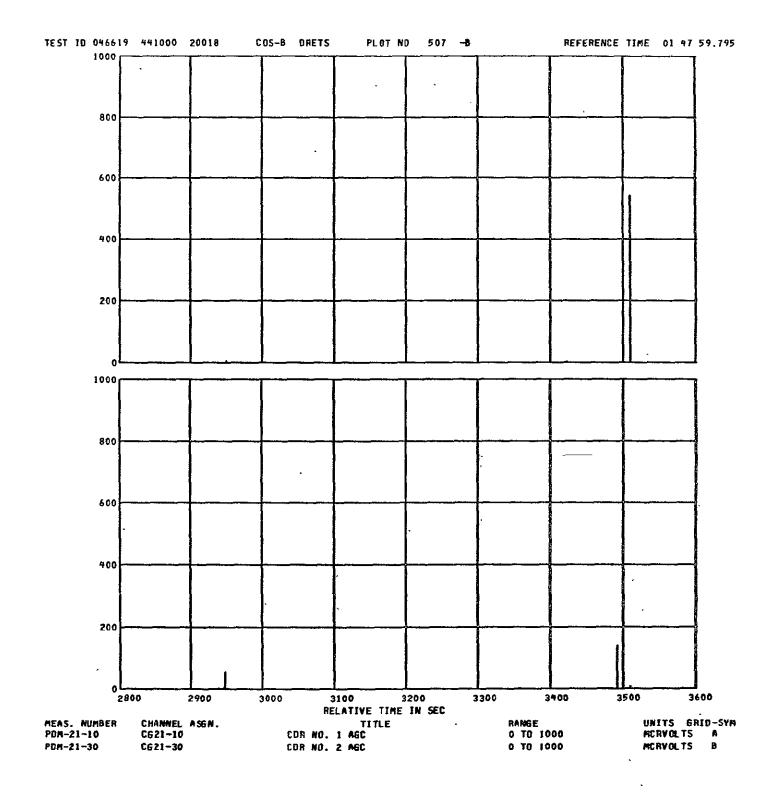
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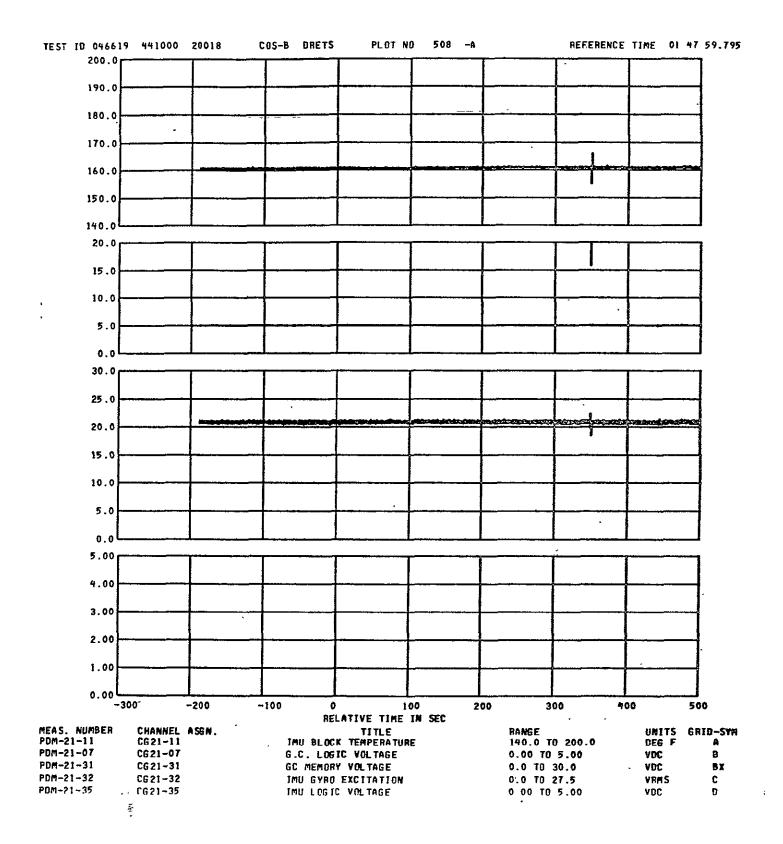
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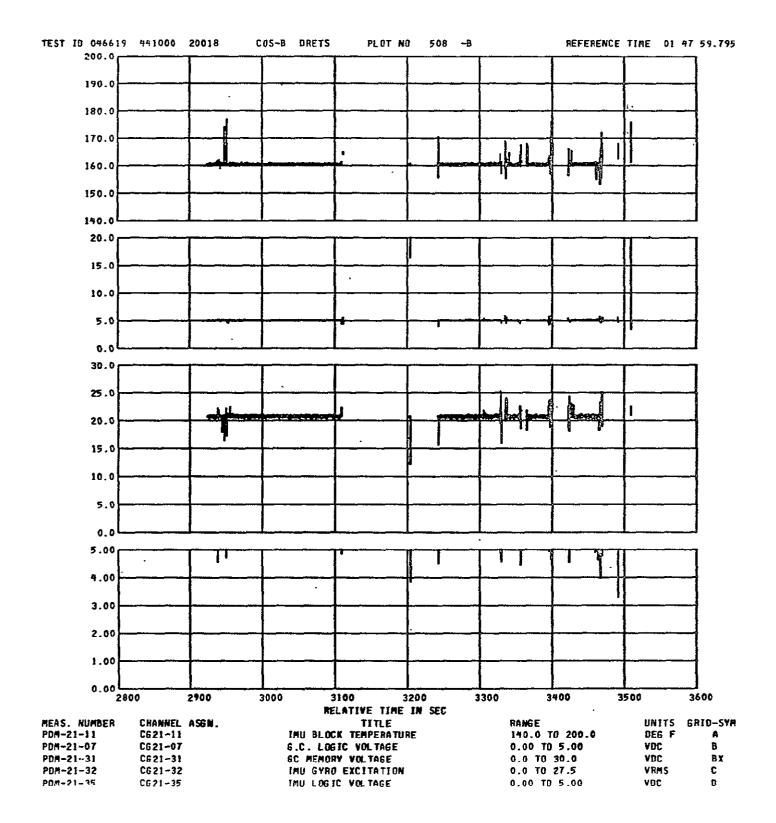
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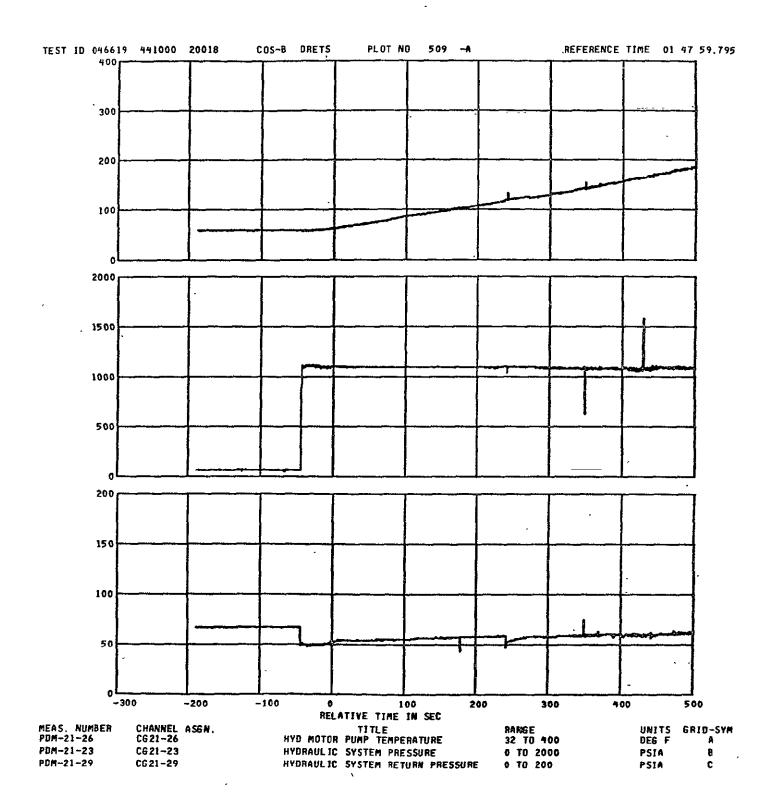


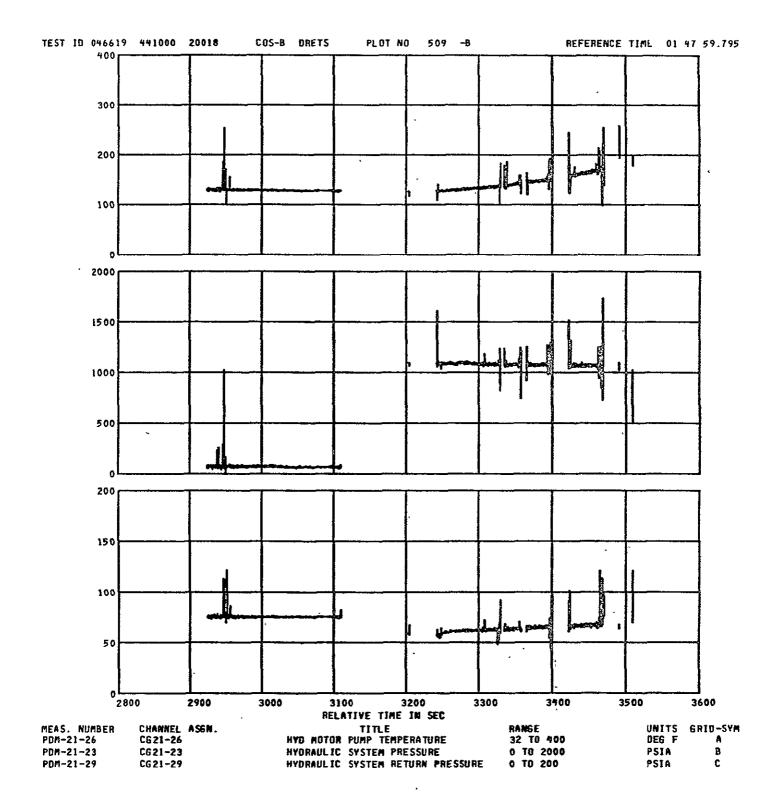




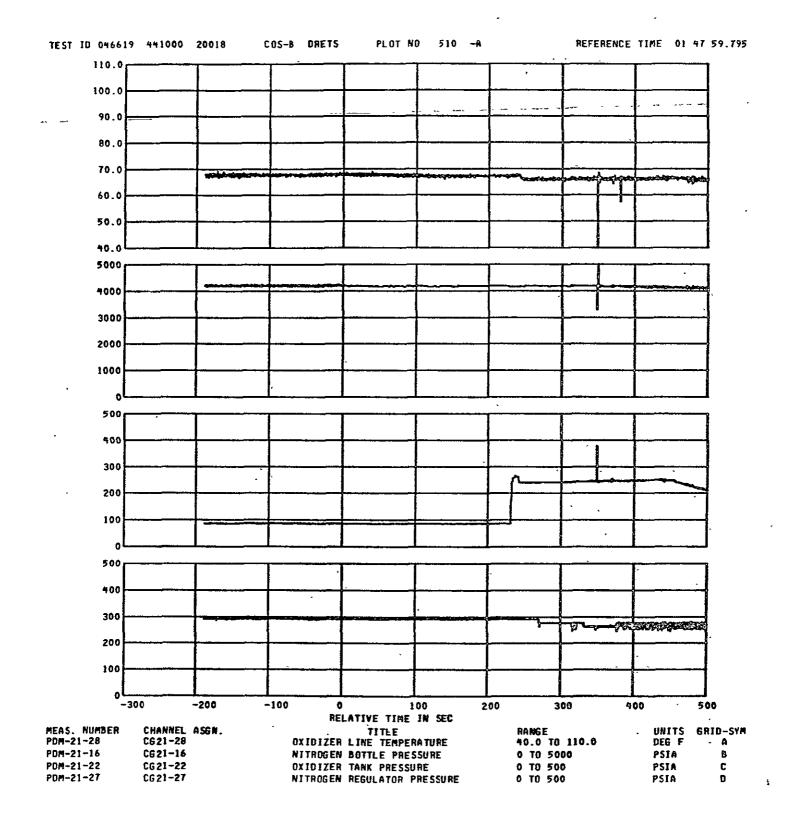


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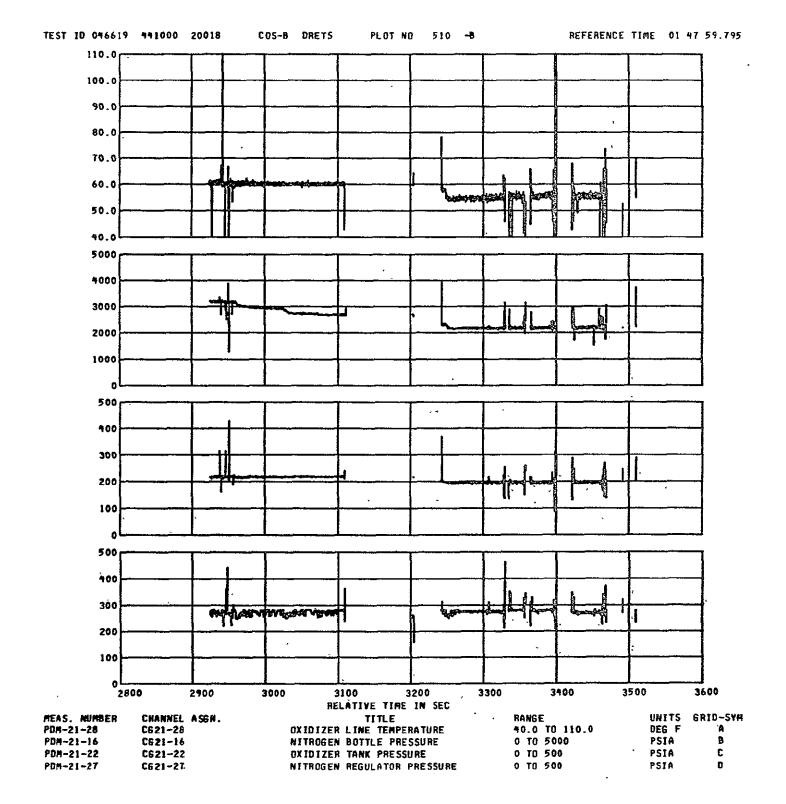


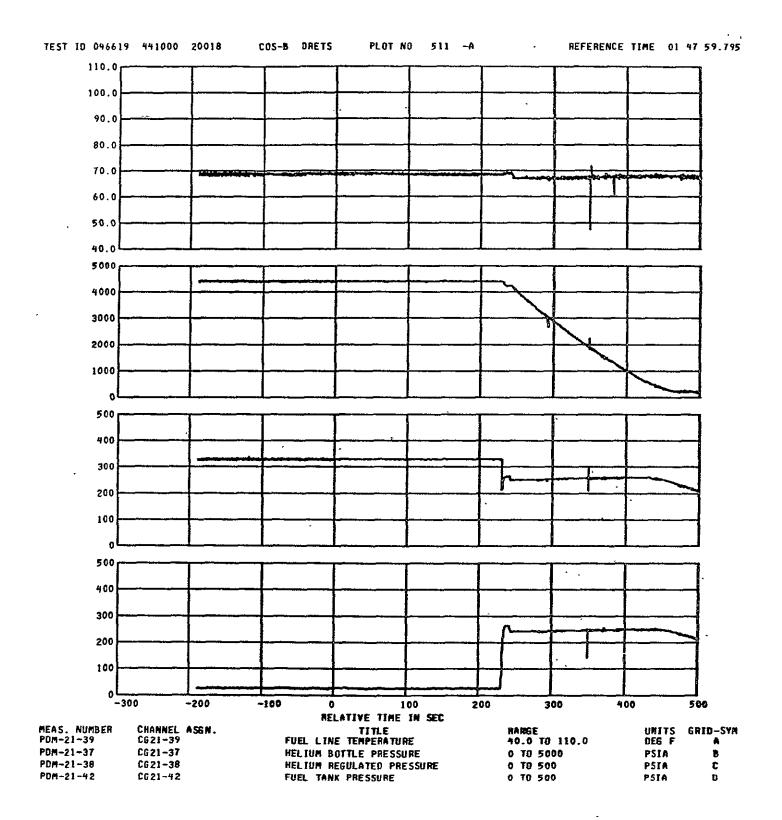


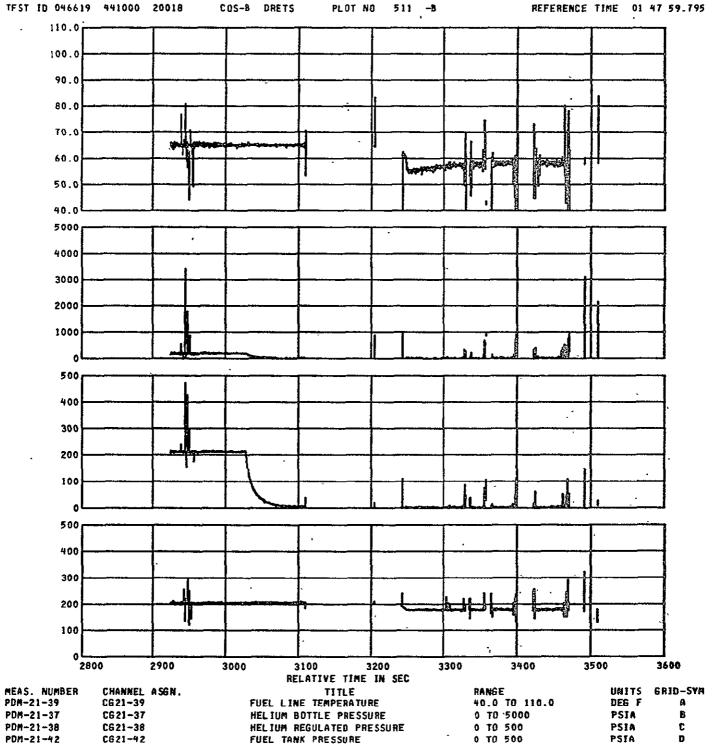
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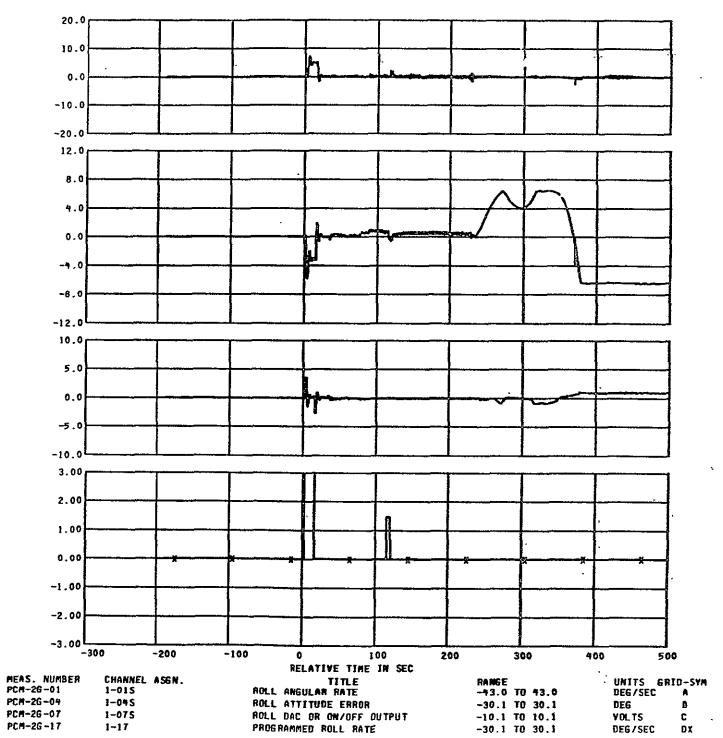




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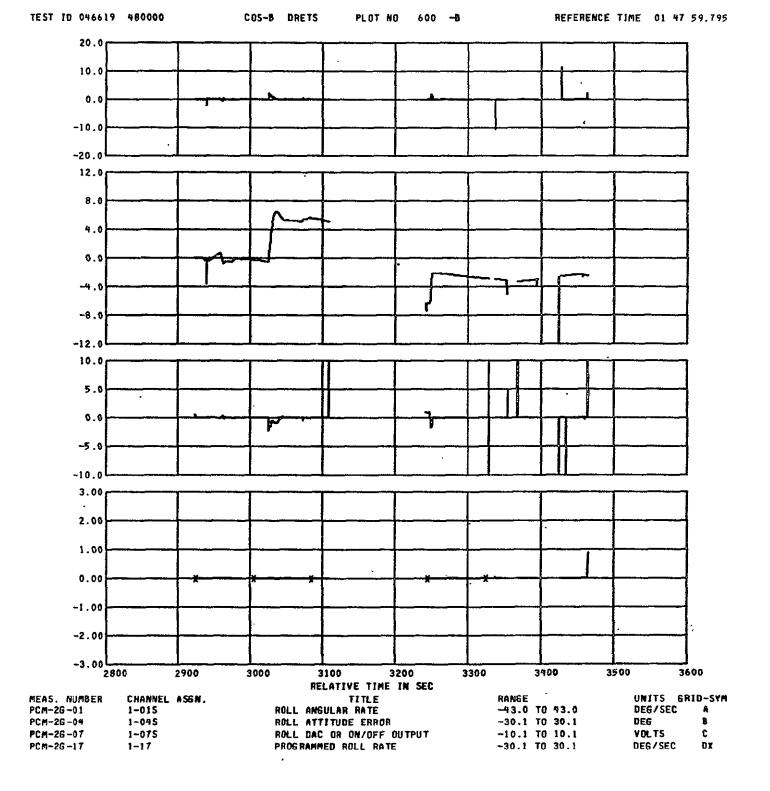
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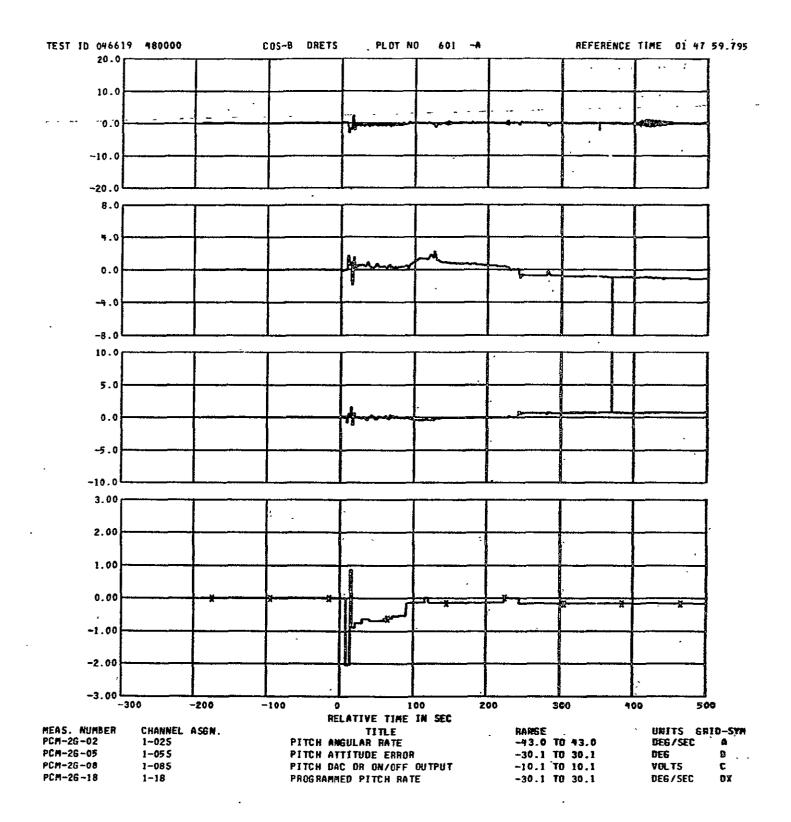


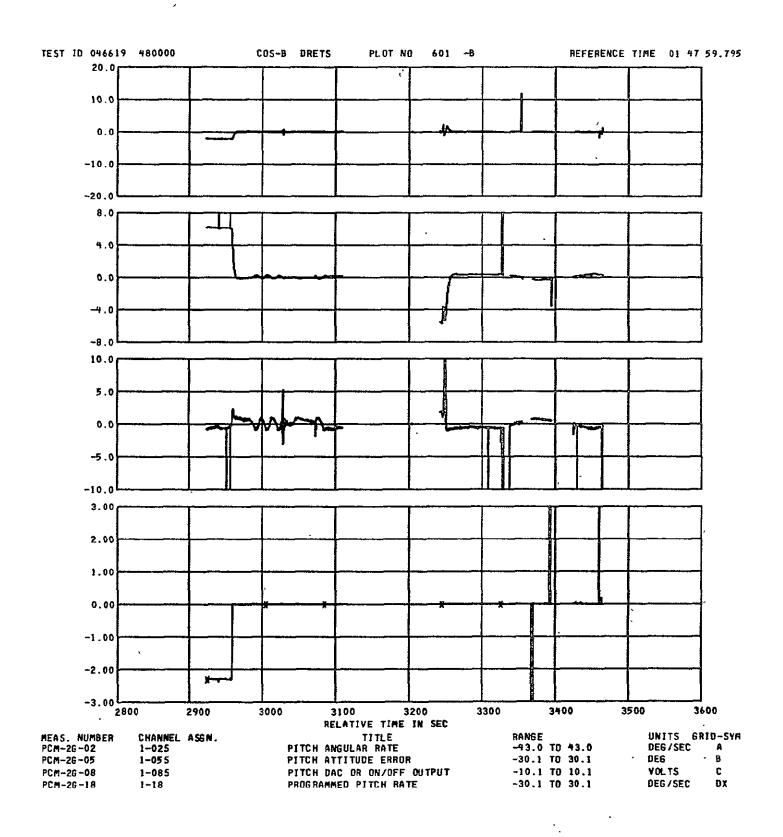
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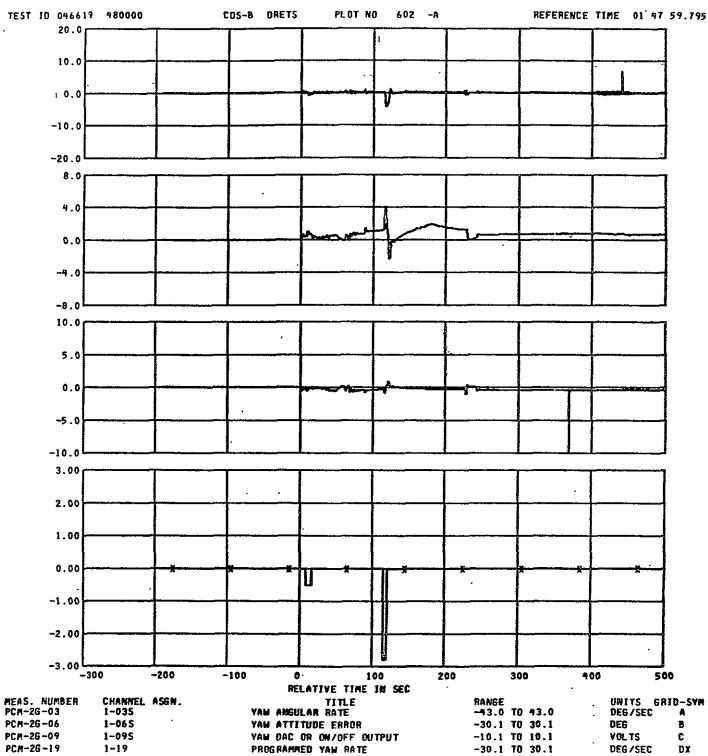
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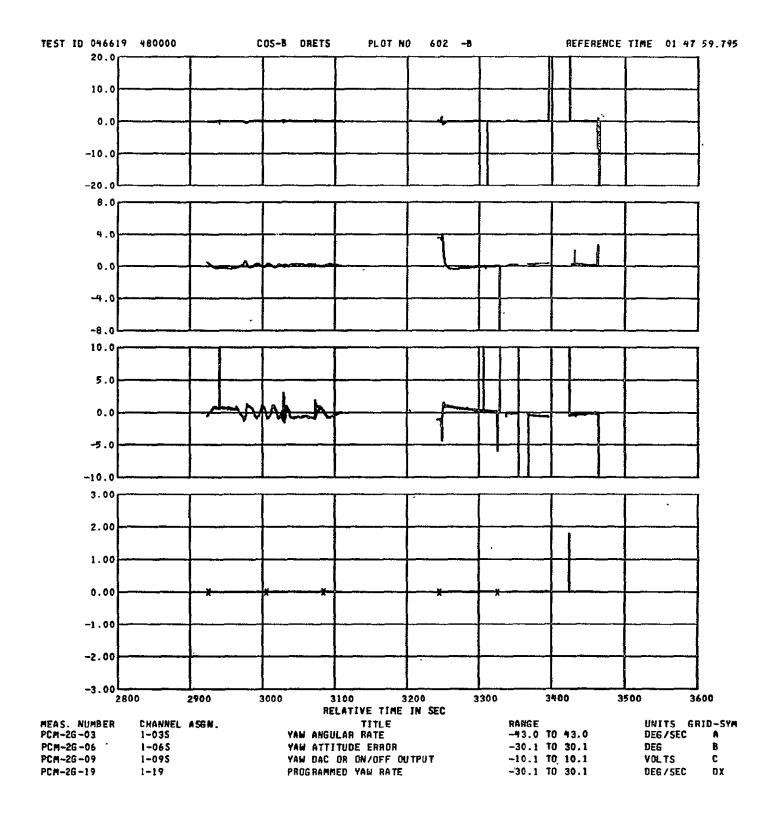
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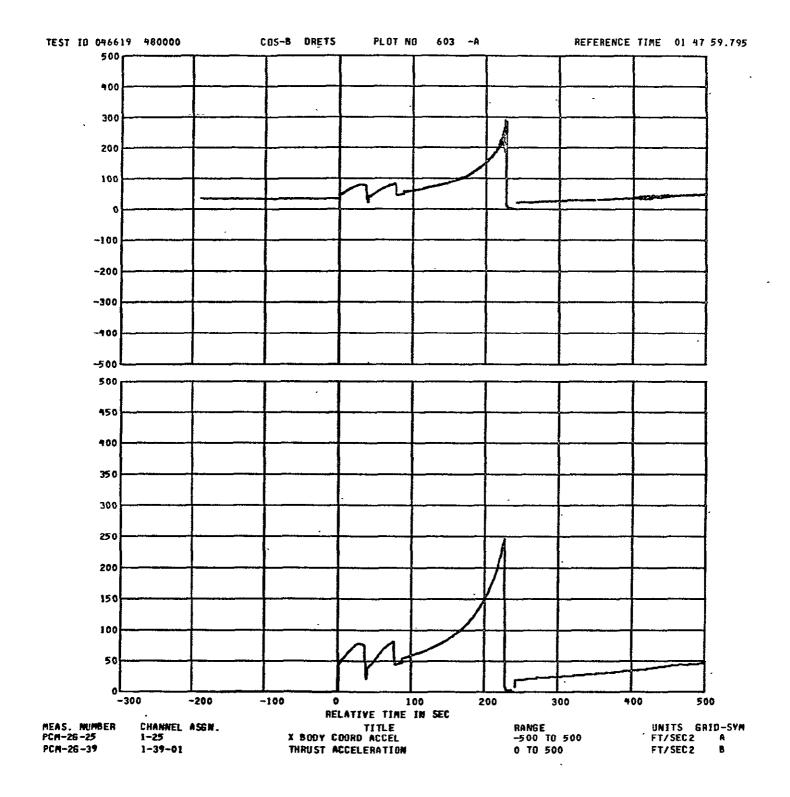
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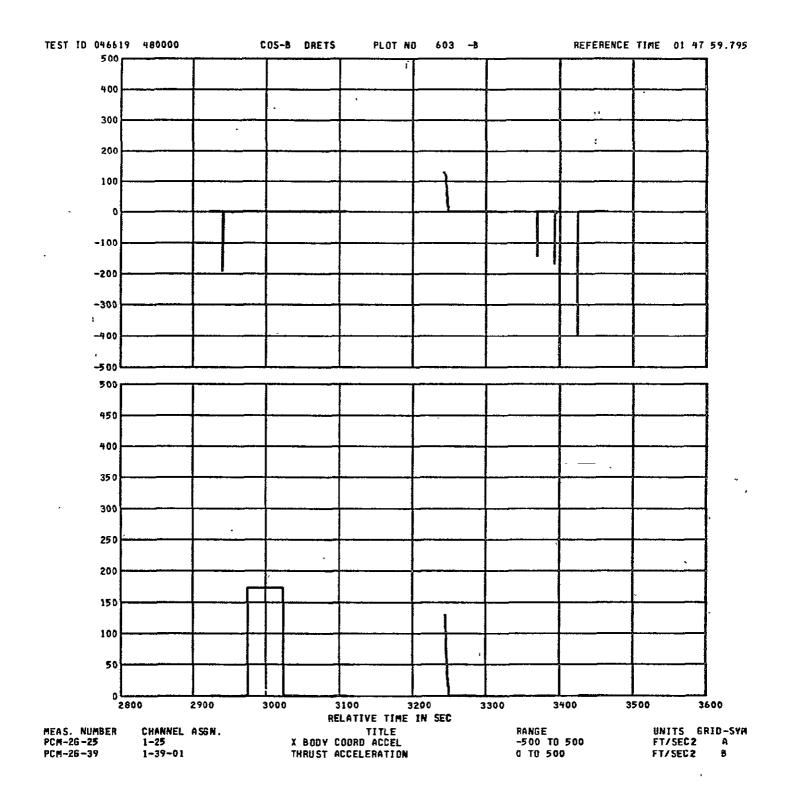
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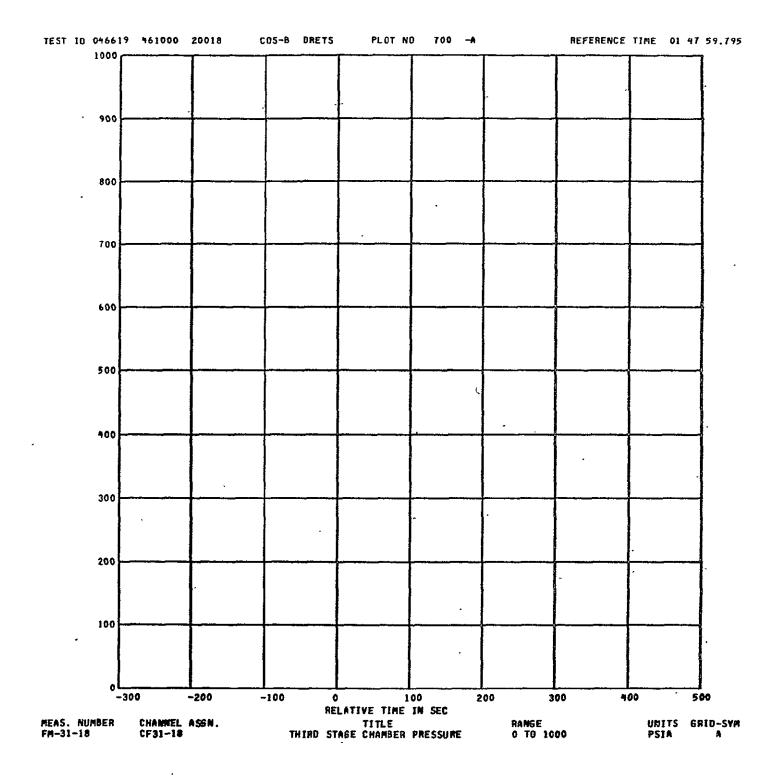
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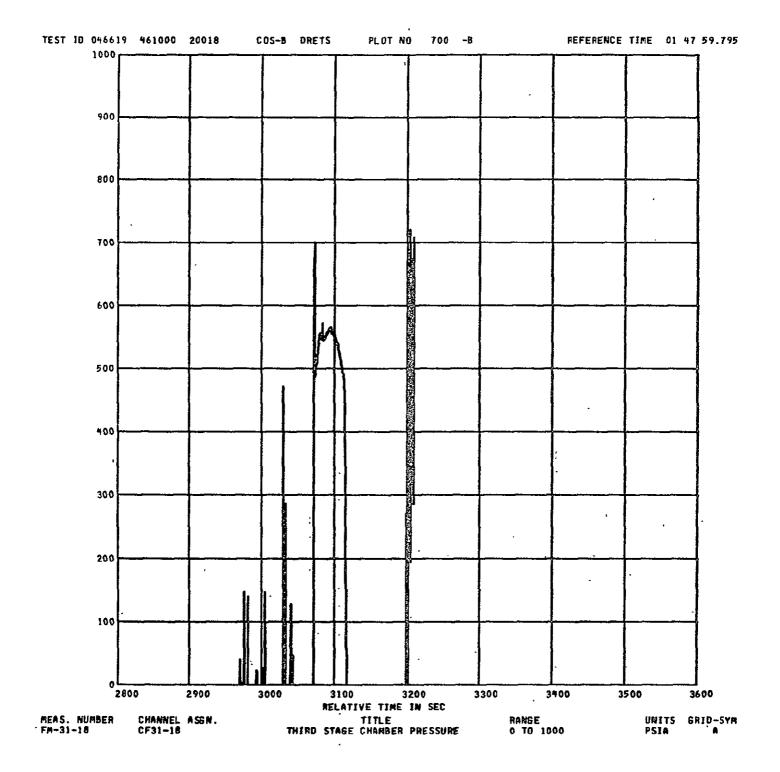


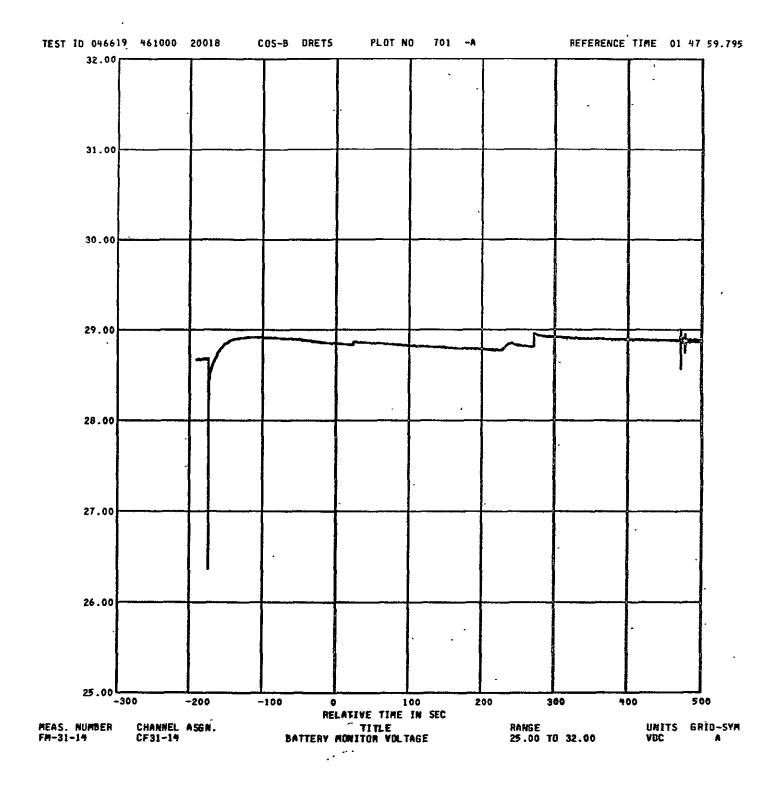


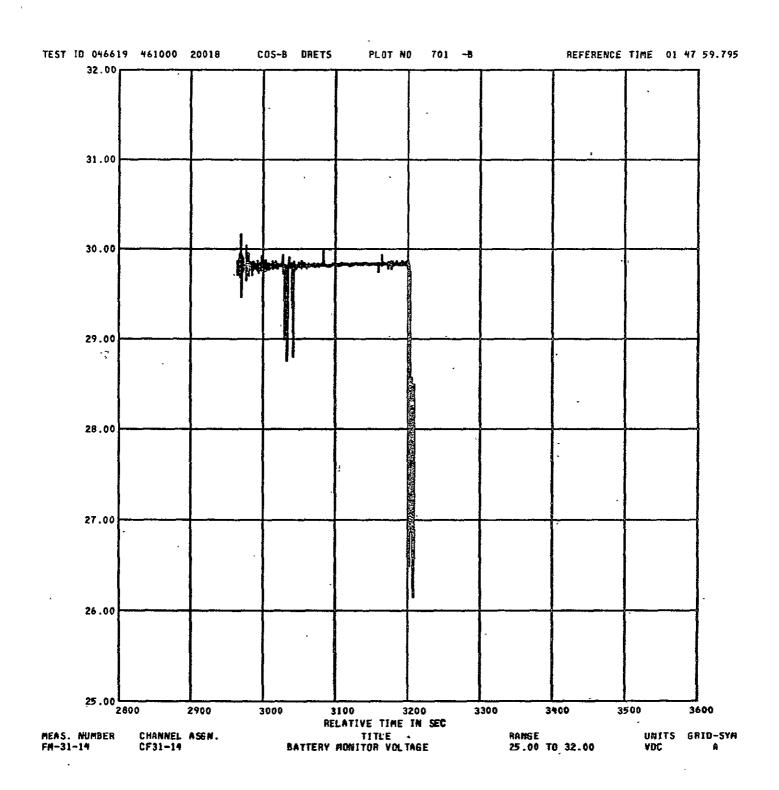
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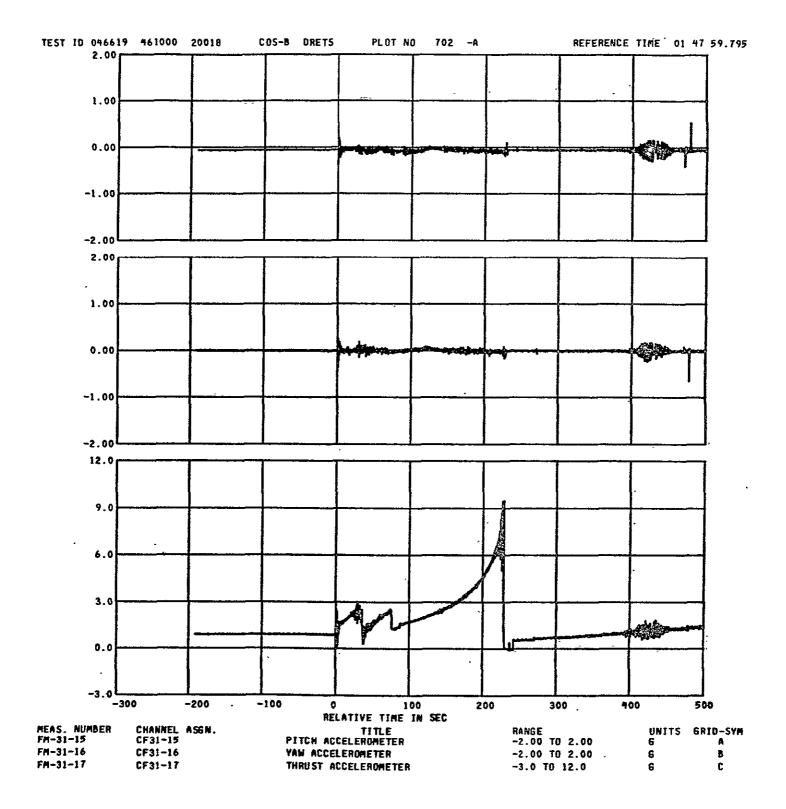




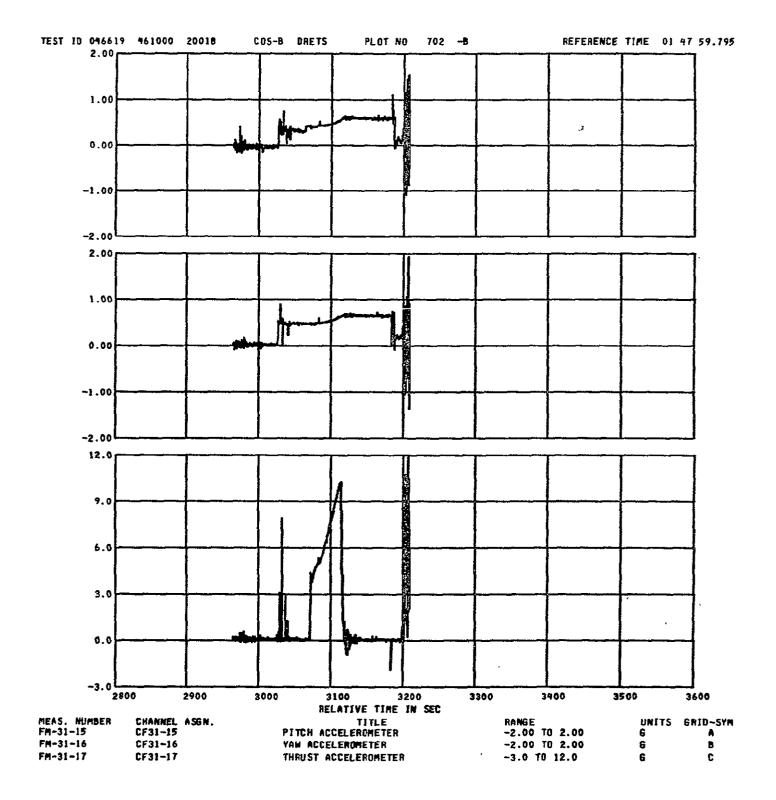








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MCDONNELL DOUGLAS ASTRONAUTICS COMPANY

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