NASA Contractor Report 3053



Aerodynamic Characteristics of Forebody and Nose Strakes Based on F-16 Wind Tunnel Test Experience

Volume I: Summary and Analysis

C. W. Smith, J. N. Ralston, and H. W. Mann

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LIST OF SYMBOLS, (Continued)

Sw	Wing theoretical planform area	$m^2(ft^2)$
TEF	Trailing-edge-flap deflection angle	deg
WL	Water line of the full-scale airplane	cm (in.)
α	Angle of attack of the wing chord plane	deg
α break	Angle of attack separating linear and non-linear lift curve regions	deg
β	Angle of sid <u>esli</u> p or Prandtl-Glanert parameter, $\sqrt{1-M^2}$	deg,
η_{B}	Non-dimensional span station separating inboard and outboard panels (See Figure 34)	
$\Lambda_{c/4}$	Quarter-chord sweep angle	deg
Λ_{LE}	Wing leading-edge sweep angle	deg
Λ_{LE_1}	Strake leading-edge sweep angle	deg
Λ_{TE}	Wing trailing-edge sweep angle	
λ	Taper ratio of the theoretical wing planform	

1. SUMMARY

The YF-16 and F-16 developmental wind tunnel test program has been reviewed and all force data pertinent to the design of forebody and nose strakes extracted. Volume I of this study is reported herein and contains geometrical descriptions, general comments, representative data, and the initial efforts towards the development of design guides for the application of strakes to future aircraft. Volume II of this study contains a complete set of these data without analysis and is reported in NASA CR-158922.

Longitudinal and lateral/directional data are presented for low-speed and transonic Mach numbers for families of nose and forebody strakes on several configurations that reflect different stages in the F-16 development. Included are simple wing-body configurations and highly blended wing-bodystrake configurations. All have 40-degree-leading-edge-sweep wings with a nominal aspect ratio of 3.0.

It is concluded that the generation of incremental strake lift is primarily dependent upon the area affected by the strake vortex and that strake planform is of secondary importance below the angle of attack for which vortex breakdown effects become significant. Forebody strakes can have beneficial effects on lateral/directional stability if properly designed. Nose strakes provide significant gains when added to the forebody configurations of this study.

2. INTRODUCTION

Possibly the most distinguishing characteristic of the latest generation of fighter aircraft, the F-16 and F-18, is the utilization of forebody and nose strakes to provide significant increases in usable maneuver lift. These designs are the culmination of long and expensive design evolutions, which relied extensively on wind tunnel testing. This approach was required because no reliable aerodynamic prediction methods are available that address the highly complex flow field present at the moderate-to-high angles of attack under consideration. As a consequence, an extensive body of experimental aerodynamic data exists.

In particular, during the course of configuration development of the YF-16 Lightweight Fighter Prototype and the F-16 Air Combat fighter, General Dynamics wind-tunnel-tested many strake variations at subsonic and/or transonic speeds. Strake effects noted in these data can be generalized in the sense that both conventional and highly blended configurations were investigated early in the YF-16 development program. The effects of variations in strake size, strake planform, strake location relative to the nose, strake span relative to the span of the wing, and leading-edge-flap deflection received considerable interest. Additionally, several different types of strakes were investigated. These consisted of strakes that extended from the forebody to the wing leading edge (forebody strakes), strakes that started at the nose and extended only a short way back on the forebody (nose strakes), and relatively short strakes that were placed aft of the nose but did not extend to the wing leading edge (canard strakes).

The primary benefit attributed to the forebody strakes is a significant increase in usable lift at transonic speeds compared to a conventional wing configuration. During the development programs, General Dynamics found that significant interactions occur between the vortex flows generated by strakes, the wing and the empennage flow fields, and that the interactions can be favorable or unfavorable. While it is relatively simple to achieve a high maneuvering lift capability with forebody strakes, it is necessary to tailor the strake-wing-empennage combination to enhance the moderate-tohigh-angle-of-attack lateral/directional stability characteristics and thus make the additional lift usable. Another major fact encountered in the development programs is that some strake-wing configurations result in a deep-stall

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situation at angles of attack in the range from 35 to 60 degrees; therefore, it is also necessary to evaluate low-speed pitch-control effectiveness in this angle of attack range.

Forebody nose shape plays an important role in the highangle-of-attack lateral/directional stability characteristics. The effects of nose shape can be minimized by employing nose strakes but, again, it is necessary to limit the nose-strake size to prevent adverse effects in pitch at high angles of attack.

The objective of this investigation is to conduct a detailed review of all of the YF-16 and F-16 developmental wind tunnel data, select the data pertinent to strake design, and present them in a useful form complete with detailed geometric data. Initial efforts have been conducted herein to coalesce the experimental aerodynamic characteristics of strakes into a set of generalized design guidelines for the application of forebody and nose strakes to future aircraft. Of particular interest are the geometric parameters that have the most significant effects on (1) the prevention of lowspeed deep stall, (2) the development of lift capability at transonic speeds, and (3) the establishment of the limits on the usable angle of attack at transonic speeds that preserve satisfactory longitudinal and lateral/directional stability characteristics. The complete data base may be found in NASA CR-158922.

Northrop Corporation has been funded by the Air Force Flight Dynamics Lab to conduct a similar study dealing with the strake data obtained during the F-5 and YF-17 developments. The results of this work are published in AFFDL TR 78-94.

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3. THE WIND TUNNEL

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TEST PROGRAM

The YF-16 and F-16 aircraft are products of an extensive wind tunnel test developmental program. It was during the YF-16 test program that the many design features of the F-16 evolved. The resultant configuration is an integrated design incorporating:

- o Forebody strakes for controlled vortex flow
- o Automatically actuated leading-edge flaps
- o Relaxed static stability

and the second second

- o Blended wing-body cross-section shape
- o Single engine fed by a simple underslung inlet
- o Single vertical tail
- o High-visibility canopy

The design evolution is discussed here to lay the groundwork for understanding the strake development and the impact of comparing strake effects from the multitude of configurations studied. Detailed descriptions of the strake geometry and summaries of the available wind tunnel test conditions pertinent to the evaluation of strake performance are also presented.

3.1 THE EVOLUTION OF FOREBODY STRAKES ON THE F-16

A study of the YF-16 aerodynamic features began in 1968. After intensified analysis in 1970-71 and wind tunnel tests in 1971-72, detailed designs were finalized in 1972-73. Configuration refinement and growth modifications continued through wind-tunnel testing until the Full-Scale Development (FSD) aircraft, F-16A and F-16B, were finalized in 1975.

Early design studies set the basic features of two very different design approaches. One was a simple wing-bodyempennage design with a single vertical tail (Configuration 785, shown in Figure 1). Later in the program this design

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was also tested with a twin-tail arrangement (Configuration 786, Figure 2). The other approach was a highly blended wing-body with a wide lifting forebody and twin tails mounted on booms extending aft on either side of the engine exhaust nozzle. This design is known as Configuration 401F, an early version of which is shown in Figure 3 (Configuration 401F-2).

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The best features of the two separate initial models were combined into one model and the resulting configuration refined through several tunnel entries to produce the final YF-16 design. Significant intermediate steps included the combination of the Configuration 785 afterbody with the Configuration 401F-2 forebody to obtain Configuration 401F-5, Figure 4, and the addition of afterbody shelves to which the horizontal tails were mated, Configuration 401F-10A, Figure 5. Minor modifications continued through Configuration 401F-16F, which is similar to the YF-16 prototype lines.

The aerodynamic design concept of obtaining high-lift coefficients at transonic speeds by the use of wide forebody shapes has been an integral feature of most General Dynamics fighter designs since before the FX (F-15) competition. The concept was initially wind-tunnel-tested in 1966. Sharp, narrow forebody strakes were also investigated briefly at that time; however, it was then considered an advantage to produce the lift with a blunt leading edge in order to maintain attached flow and greater leading-edge suction for lower drag.

The 401F-0 configuration was developed under that concept, and to accommodate the underslung single inlet, the forebody cross section was made elliptical (flattened on the lower surface), which blended into an upright triangular shape having rounded corners and finally blended into the wing. Available NASA test data on effects of body cross section on lift indicated that significant lift could be expected from the forebody. The first transonic test of the configuration verified these expectations.

However, the directional stability characteristics of the wing-vertical-tailed 401F-0 configuration exhibited a severe loss of directional stability at moderate-to-high angles of attack. In addition, the subsonic drag polar "breaks" occurred at lower lift coefficients than expected. Analysis of oil-flow-visualization photographs and force and moment test results utilizing FX and other research models (Reference 1) showed that forebody flow separations and the

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interaction of the resulting vortices with the wing and vertical tail flow fields were major causes of the stability problem.

At this point, NASA/Langley Research Center aerodynamicists were consulted. They suggested that the lift of the wide forebody could be increased by sharpening the leading edge to strengthen the vortices rather than weaken them as our earlier attempts had done. The point was that forebody separation is inevitable at very high angle of attack; therefore, the lift advantages offered by sharp leading edges should be exploited. This also would allow the forebody vortices to dominate and stabilize the high-angle-of-attack flow field over the entire aircraft, even improving the flow over the outboard wing panels.

Two series of parametric forebody strake tests were initiated. A series of delta planform strakes were designed for testing on the conventional forebody aircraft Configurations 785 (single vertical tail) and 786 (twin vertical tail). The second series had curved planforms (gothic and ogee) and were designed for testing on the blended configuration, 401F-5. These two parametric transonic tests provided the basic data for all the other evolutionary forebody strake tests, which continued throughout the YF-16 and F-16 development as various design changes required re-evaluation of the strake effectiveness.

3.2 GEOMETRIC DESCRIPTIONS

All data presented herein were obtained with a 40-degreeleading-edge-sweep wing with a nominal aspect ratio of 3.0. The basic 26-square meter (280-square foot) wings, W3 and W3BB, were used on all of the YF-16 developmental configurations except Configurations 785 and 786, which used a 26square -meter wing of different planform, W6. Later, F-16 versions utilized wings of 27.6 sq. m (297 sq. ft), W24, and 27.9 sq. m (300 sq. ft), W25. Each of these planforms is sketched in Figure 6.

A listing of all of the strakes and the configurations upon which they were tested is provided in Table 1. Also included are pertinent geometrical parameters, which consist of strake length, maximum width, exposed area and position on the forebody. Figures that provide sketches of the strakes on the appropriate forebodies are referenced in the table. After the initial strake tests on Configurations 785, 786, and 401F-2 through 401F-5, it became apparent that a forebody

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strake would be part of the final configuration. As a consequence, forebody strake-off configurations were no longer tested. The subsequent configurations have variations in strake size, shape, and location but do not have definable strake geometry for the purpose of determining an explicit strake width and exposed area for Table 1.

Figures 7 to 20 present sketches of the strakes on the appropriate forebodies. Figure 7 shows the delta planform family, Z7-Z10, which was tested on the simple wing-body configurations, 785 and 786. Several canard-type strakes were tested early in the program on Configurations 401F-2 (Figure 8), 401F-4 (Figure 9), 401F-5 (Figure 10), and 401F-10A (Figure 11a). Also, a gothic planform, Z5, was tested on Configuration 401F-4 (Figure 9), and several ogee planforms in addition to a delta and gothic strake were tested on Configuration 401F-5 (Figure 10). Slotted strakes, Z22A and Z23, were also tested on Configuration 401F-5, as shown in Figure 10.

Later tests investigated small changes to blended strakes, generally ogee in shape (Figure 11b to 14). Low-speed tests were also conducted with a variety of small rotating (variable incidence) strakes that formed a piece of a basic ogee strake, Z33 (Figure 15). Larger sections of ogee planform strakes were also rotated, as shown in Figure 16. Nose strakes and additional canard strakes were also tested on the basic YF-16 configuration (Figure 17).

Initial designs for the trainer (two-place) version of the F-16 included fuselage stretches of 77.5 cm (30.5 in) and 113 cm (44.5 in). Numerous forebody strakes with ogee planforms of various width and length plus a few nose and canard strakes were tested on these configurations (Figure 18).

The FSD aircraft has two major modifications from the YF-16: a 25.4 cm (10 in) fuselage stretch and an increased wing area from 26 to 27.9 sq. m (280 to 300 sq. ft). Forebody-strake variations for this configuration are shown in Figure 19. Numerous nose strakes were also investigated as shown in Figure 20.

Several strake families have been selected for analysis purposes because they provide significant variations in strake geometry on the same basic configuration. Forebodystrake families that receive primary analysis are those of Figure 7 (Z7-Z10, Configuration 785), Figure 10 (Z4, Z5, Z14-Z18, Configuration 401F-5), Figure 11b (Z24-Z27, Configuration 401F-10A), and Figure 18a (Z63-Z72, stretched YF-16). Nose-strake families of primary interest were tested on the F-16 FSD configuration and are shown in Figure 20 (Z110-Z117, Z123-Z128, Z131).

Several nose shapes were tested at low speed in conjunction with the nose strakes. Sketches of these noses are provided in Figure 21.

3.3 SCOPE OF STRAKE TESTING

A list of all of the YF-16 and F-16 force tests is provided in Table 2. These tests encompass the entire developmental program from the early configuration testing in 1971 to the recent FSD testing in 1977. Each of these tests has been surveyed for data applicable to strake design, resulting in the selection of the tests shown in Table 3. A complete set of the resultant data for the tests of Table 3 are provided in plotted form in Volume II of this study (NASA CR-158922). Test parameters for each strake configuration are summarized in Table 4. Figure numbers in Volume II for data for each strake configuration are also provided in Table 4. Selected data are shown in this volume.

During the initial development program, emphasis was placed on the aerodynamic and stability characteristics at specific transonic Mach numbers (.80 and 1.20). Later testing included additional Mach numbers for selected configurations. Very little low-speed testing was accomplished until the configuration had evolved to basically that of the YF-16 (Configuration 401F-16). Much of the low-speed effort was associated with the evolution of the two-place aircraft during the Air Combat Fighter (ACF) competition and, therefore, includes effects of stretching and modifying the forebody shapes. The nose strake testing also occurred at the time of the ACF competition and later during the FSD program.

All of the low-speed testing was conducted at a Reynolds number of 1.4 million per foot. The transonic tests were conducted with a Reynolds number range of 2 to 3 million per foot. Reynolds number effects on high-angle-of-attack aerodynamics may be significant; however, investigation of the effect of Reynolds number on the strake characteristics is beyond the scope of this document. 4. ANALYSIS AND DESIGN GUIDELINE DEVELOPMENT

This study makes the strake wind tunnel test data obtained during the F-16 development available for general This is accomplished through the geometrical descripuse. tions of Section 3 and the complete set of plotted data provided in NASA CR-158922. Since a large amount of data was obtained during a development program containing numerous configuration changes, assimilation of the data is not a simple task. The intent of this section is to concisely extract and present the trends observed from the data, using representative data to illustrate and substantiate the conclusions. Where possible, initial steps have been taken to form general design guides. All deducements from the data must be tempered by the fact that high-angle-of-attack aerodynamics, and particularly lateral/directional stability characteristics, are strongly dependent upon the complete wing-body-empennage configuration. Assessments of the degree of general applicability of the conclusions reached, e.g., to configurations dissimilar to the F-16, have been attempted throughout the section.

4.1 LIFT AND DRAG

It is well-known that the addition of forebody strakes significantly increases the high-angle-of-attack lift and decreases the high-angle-of-attack drag of low- to mediumsweep wings. General observations as to the character and extent of these effects with respect to the strake geometry are presented in this subsection. The discussions are primarily concerned with strake effects on lift at moderate-tohigh angles of attack. However, drag effects exhibit the same trends and will be shown to be a function of CL tan α as would be expected. A brief evaluation of an empirical prediction method for high-angle-of-attack lift has been made and the method found to be inadequate for strake configurations. This leads to empirical correlations of the strake lift and drag increments with the intent of producing design guides relating the aerodynamic effects to strake geometry. Results of these correlations are also discussed in this subsection.

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4.1.1 General Discussion

Typical examples of the lift and drag benefits attributed to forebody strakes are shown in Figures 22 and 23. The family of delta planform strakes, Z7-Z10, on the simple wing-body configuration (785) yields lift and drag benefits beginning at approximately a 10-degree angle of attack (Figure 22). The most significant geometric parameter appears to be the area: the bigger the strake, the more the lift. The data shown in Figure 23 are representative of the later highly blended strake configurations (geometry of Figure 18a) and as such, there is no strake-off level for comparison. The strong effect of strake size is nonetheless again present at angles of attack above 17 degrees.

The effects of nose strakes on lift and drag are negligible for the size strakes tested in the F-16 program. A typical effect is that of nose strake Z124 tested in front of the F-16 forebody strake, Z120 (Figure 24). A sketch of Z124 was provided in Figure 20b. This negligible effect is undoubtably a result of the small size of the nose strakes. A contributing factor, however, is also that the vortex shed from the nose strake tends to flow over the forebody and does not interact with the wing flow field. Conversely, a vortex shed from a forebody strake passes over the strake and wing upper surface. Further evidence of this concept is present in Figure 25, which compares the lift effects of a nose strake and a small canard strake for the YF-16 forebody (Figure 17 shows geometry). The canard strake, although small, has a noticeable effect on the lift and drag, particularly at very high angles of attack. A vortex shed from this canard strake would pass over the forebody strake and wing, and tend to reinforce the existing forebody strake vortex.

The data of Figures 22 and 23 show significant beneficial effects of forebody strakes on the lift and drag of a wing with no leading-edge flap deflection. Wing leading-edge flap deflections can significantly reduce the incremental strake effects. For example, on configuration 401F-5 without a forebody strake, increasing the leading-edge flap deflection results in an orderly increase in lift with increasing angle of attack (Figure 26). However, the addition of a modified delta forebody strake, Z4, significantly reduces the effect of the leading edge flap (Figure 27). There is actually a reduction in lift with leading-edge flap deflection in the 15- to 23-degree angle-of-attack range for the configuration with strake Z4.

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The result is that the effects of forebody strakes on the envelope lift and drag curves, which are representative of aircraft, such as the F-16, that have scheduled leadingedge-flap deflections, are significantly reduced from the no-leading-edge-flap case. Envelope curves (Figure 28) that result from a minimum-drag leading-edge-flap schedule illustrate this point. This effect is logical when the effect on the wing upper surface flow is considered. Without a leadingedge flap or a strake the flow over the F-16 wing, which is rather thin (t/c = .04), begins to exhibit significant separation (stall onset) at approximately a 10-degree angle-ofattack (Figure 22). A leading-edge flap delays this separation considerably and thus improves the lift and drag characteristics. A forebody strake accomplishes much the same effect at high angles of attack by passing high-energy vortex flow over the region of the wing that otherwise would have separated (stalled) airflow. These effects are not entirely additive, thus the strake benefit in the presence of leadingedge flaps is reduced from the no-flap case, Figure 28. In summary, the design of a forebody strake/wing leading-edge flap combination must consider the strong coupling effects.

The comparisons of Figure 28 are with a zero horizontaltail deflection, i.e., untrimmed. Trim effects are generally favorable to the forebody strake configurations because of the linearization of the pitching moment curve, as will be discussed in Subsection 4.2.

Whenever additional exposed area, such as a strake, is added to a configuration to improve the high-angle-of-attack characteristics, the question of the effect on cruise and dash performance must be addressed. Figures 29 and 30 illustrate the typical low-lift drag penalty for forebody strakes at .80 and 1.20 Mach number, respectively. The predicted skin friction drag (Reference 2) for the largest strake shown, Z7, is .0007 at wind tunnel Reynolds number and .80 Mach number. It can be seen in Figure 29 that the data for all of the strakes fall within this band at the lift coefficient for minimum drag, indicating that the drag penalty is of the same order as the friction drag prediction at .80 Mach number. The penalty remains relatively constant up to typical optimum-altitude cruise lift coefficients for the F-16 (C] \approx .3). Figure 30 shows that at 1.20 Mach number some strakes produce a small drag reduction at low lift. It is probable (based on area distributions from similar configurations) that for this unblended configuration (785) the strake is filling the area curve immediately forward of the wing, thus improving the airplane's 1.2 Mach area distribution.

The majority of the transonic strake parametric data is at Mach numbers of .80 and 1.20. Limited configuration comparisons are available at .90 Mach. Although the strake effects on lift and drag are, in general, consistent between .80 and .90 Mach, the effects are greatly reduced at the higher Mach number. Figures 31 and 32 illustrate this effect for a series of blended forebody strakes on Configuration 401F-10A.

The effect on lift and drag of fairing the strake into the forebody is shown in Figure 33. The basic Z4 strake is a flat plate added to Configuration 401F-5. This strake was first tested with the upper surface faired, Z4A, and then the upper and lower surfaces faired, Z4B (geometry in Figure 10). There are only very small effects on the lift and drag.

Of primary importance in this subsection is the effect of forebody strake size and shape on lift and drag and the associated interaction of the strake and leading-edge flap. These items are therefore considered in more detail in the following subsections.

4.1.2 Evaluation of Existing Prediction Techniques

If an existing method would adequately predict lift and drag effects of forebody strakes, it would be a considerable aid to the definition of the important geometrical relationships and associated development of design guides. To this end, a typical existing method has been evaluated. The method selected for consideration is an empirical method developed at General Dynamics under a USAF contract (WINSTAN) and documented in Reference 3. The contract task was to develop methods to predict the aerodynamic characteristics of double delta, cranked, and curved leading-edge wings. The particular aspect of interest herein is the method developed to predict the nonlinear lift of double-delta planforms.

The method is based on a correlation at constant angle of attack of the parameters $(C_L/C_{L_{\alpha}})(AR_i/\eta_B)$ and $\beta \tan \Lambda_{LE_i}$ for available experimental data for double-delta planforms. These parameters are defined as follows:

 C_L - lift coefficient, lift/qS_{REF} $C_{L\alpha}$ - linear lift curve slope AR_i - aspect ratio of inboard panel, bi^2/S_i

 $\eta_{\rm B}$ - nondimensional span station of intersection of inboard and outboard panels

 β - Prandtl-Glauert parameter, $\sqrt{1 - M^2}$

 Λ_{LE_2} - leading-edge-sweep angle of inboard panel

The resultant correlation, taken from Reference 3, is shown in Figure 34.

To apply this method to predict the incremental effects due to strakes, it is necessary to predict both the strakeon and strake-off configurations. The strake-on case is predicted as if it were a conventional double-delta planform. The strake-off case is predicted by assuming that a double delta planform approaches the wing-fuselage combination as a limiting case. It is noted in Figure 34 that as the sweep of the inboard panel approaches 90°, the parameter $(C_L/C_{L\alpha})$ (AR_i/η_B) approaches an asymptotic value. The strake-off case is predicted by use of this asymptotic value as representative of a wing-body combination with the fuselage forward of the wing trailing edge defined as the inboard panel.

The family of delta planform strakes shown in Figure 7 has been selected for the test-prediction comparison because of its configuration simplicity. These strakes are not blended into the fuselage, thus the definition of each configuration component is straightforward. These strakes also form a consistent family, not involving several different planform shapes.

The predicted increment between strake on and off is shown in Figure 35. Obviously the increment predicted in this manner does not adequately model the increment obtained from the test data. It is noted that the strake does not produce a substantial lift increment within the range of angles of attack normally considered to be characterized by linear (or nearly linear in the case of the F-16 aspect ratio 3.0 wing) variations in lift. An attempt has been made to account for this region by predicting the $\alpha_{\rm break}$ between the linear and nonlinear lift regions and utilizing the increment above this point to predict the strake effects.

A correlation of α_{break} and leading-edge-sweep angle of the inboard panel is presented in Reference 3 for an

uncambered wing. The effect of wing camber on α_{break} is estimated by use of an empirical correlation found in Reference 4 and repeated below.

$$\alpha_{\text{break}} = (12.05 - 4.1 \text{ M cos } \Lambda_{c/4}) \left(\frac{C\ell_{d}}{\cos \Lambda_{c/4}}\right)$$

The strake-on and -off predictions are collapsed at the value of α_{break} predicted by the above method, and the increment above this point used to predict the strake effects, as shown in Figure 36. This is an adaptation of the double-delta method, which is similar in approach to the adaptation used in Reference 3 for cranked wings.

Prediction using this technique is shown in Figure 37. This adaptation of the double-delta correlations predicts the order of magnitude of the strake lift, although the effects of angle of attack and strake geometry are not always predicted correctly.

The apparent failure of the double-delta method of Reference 3 to adequately model the incremental strake effects does not discredit the method with respect to its original intended use. The method is based on correlations of conventional double-delta planforms of relatively high sweep and low aspect ratio. The outboard wing panel of the configurations within the present study have in all cases a moderate sweep angle (40°) and aspect ratio (3.0). In addition, the incremental values used for comparison are dependent upon the ability to predict the strake-off levels at high angles of attack - a purpose for which the methods of Reference 3 were not originally intended.

Some of the more recently developed computerized methods show promise for evaluating the longitudinal aerodynamic characteristics of wing-body-strake configurations. For example, an adaptation of the Polhamus suction analogy concept is shown to reasonably predict forebody strake effects on a basic wing-body research model in Reference 5.

4.1.3 Correlation of Incremental Lift and Drag

Due to the lack of a fully adequate method to predict the strake incremental effects, attempts have been made to

correlate the effects with appropriate geometrical param-This effort is difficult due to the lack of a eters. consistent baseline from which to increment. As discussed previously, most of the configurations with strakes are highly blended strake-wing-body combinations, and a true strake-off configuration does not always exist for incremental purposes. For these cases, the incremental values studied represent the effect of modifying an existing strake and not the total strake effect per se. Furthermore, not enough consistent families of strakes exist to systematically define the effect of a particular geometric variation. However, within the context of these limiting factors, correlations can be made that lead to several interesting conclusions concerning the general effects of forebody strake geometry.

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Initial observations noted in Subsection 4.1 indicated a strong effect of strake area on the incremental lift. If indeed area is the dominating factor, it would be helpful to remove this effect from the data so that effects that are perhaps secondary can be identified. A first attempt at this consisted of referencing the strake incremental lift to the exposed area of the strake, thereby obtaining a pure strake lift coefficient. Results showed that the exposed area was much too small to collapse the data. At this point it was hypothesized that the strake incremental lift would be a direct function of the total area affected, or energized, by the strake vortex. This is similar in concept to the augmented vortex method developed by Lamar (Reference 6). Due to the lack of diagnostic data to determine the area being influenced by the strakes, a geometrical definition of an area considered to be representative was necessary. The definition of such an area is illustrated in Figures 38 and 39. For conventional strakewing-body-combinations, the definition is simply the exposed strake area plus the wing planform area that falls within the projected strake exposed area, as shown in Figure 38. For the highly blended configurations, which do not have well-defined strake planforms, the definition was not as straightforward. For these configurations, the blended area between the strake and body was included with the strake exposed area as illustrated in Figure 39.

Four families of strakes were tested for which a definite strake-off baseline exists. The incremental lift data referenced to the theoretical wing area (26 square meters, 280 square feet) for these families are shown in Figures 40 through 43. Strake geometry was shown in Figures 7, 10 and

11b. The lift increments referenced to the strake-wing effective area, as defined in Figures 38 and 39, are shown in Figures 44 through 47. The lift increments tend to collapse to a single curve for a fixed value of wing leadingedge-flap deflection.

This is an important fact. It says that for a given configuration the overriding factor in determining the strake lift is the area affected by the strake generated vortex for the angle of attack range tested. Shape effects should become more pronounced in the 30 degree angle of attack range where vortex bursting will occur over the lifting surface.

An exception to the area correlation is the ogee family of data (Figure 46) at angles of attack greater than 18 degrees. Strakes Z16, Z18, and Z17 intersect the wing at increasing semi-spans. It can be speculated that for the larger span strakes (Z17 for example) the effective area needs to be redefined to include less of the inboard part of the wing, as shown in Figure 48. This would tend to further collapse the data of Z16, Z17, and Z18 in Figure 46 at high angles of attack. Strake Z14 is the least effective of those shown in Figure 46, which may indicate that it is too narrow to generate as strong a vortex as, say, Z18 (which has the same span).

Divergence of the effective area-based data at the higher angles of attack can also be caused by the sweeping of the strake vortex outboard over the wing. Typically, below about 20 degrees angle of attack the vortex passes across the wing in a streamwise direction for the F-16 configuration. However, at higher angles of attack (depending on leading edge flap deflection) the path of the vortex begins to curve spanwise over the wing. Obviously, the effective area definition would have to be modified to represent this effect.

Average fairings representing the collapsed data of Figures 44 through 47 are shown in Figure 49 for each family. Variations in strake shape are of only secondary importance to the generation of lift, as shown by the 10degree flap data on Configuration 401F-5 for delta (Z4), ogee (Z14, Z16-Z18), and gothic (Z5) planforms. Figure 49 also shows that the incremental lift decreases for the more highly blended configurations. Configuration 401F-10A is the most highly blended configuration shown in Figure 49 and has the lowest incremental strake lift. Configurations 785 (simple wing body) and 401F-5 (blended) show approximately the same level of strake lift to 18 degrees angle of attack. This is fortuitous, however, because the strakes of Configuration 785 have a nominal negative 2 degrees of incidence at the leading edge relative to those of Configuration 401F-5. The strakes on the simple wing body would be more effective at high angles of attack if they were at the same incidence as those of Configuration 401F-5.

A definite dependence on wing leading-edge-flap deflection can be noted in the lift increments of Figure 49. Deflecting the leading-edge flap delays the beneficial strake effects to a higher angle of attack as discussed previously in Subsection 4.1.1.

A substantial amount of strake data is available that cannot be analyzed in the preceding manner due to the lack of a true strake-off baseline. This is the case for many of the highly blended strake-wing-body configurations. For these configurations, the strake of smallest exposed area was selected as the baseline for all force increments. The incremental lift for two such families of strakes is shown in Figure 50 referenced to the wing area (26 sq. m, 280 sq. ft) and in Figure 51 referenced to the change in strake effective area from the baseline strake configuration. There is a tendency for these increments to collapse, although it is not as definite as noted in the previous comparisons. The strakes with the smallest changes in area from the baseline (Z64 and Z71), and thus the smallest lift increments (Figure 50), correspond to those curves in Figure 51 that fall the furthest away from the main body of data. Here small increments are being referenced to small areas, and a sensitivity factor may be involved. Or it may be that extension of the strake forward, Z63 to Z64, is a relatively efficient method (it takes less area) to increase the lift in the 20- to 30-degree angle of attack range because it provides a longer growth time for the vortex. More data is required to isolate this effect.

Since the forebody strakes tested on the F-16 are of high sweep and have sharp leading edges, it is expected that the drag, ΔC_D , due to the strake lift, ΔC_L , would be close to the no-suction value, $\Delta C_L \tan \alpha$. This has been evaluated in terms of incremental strake lift and drag in Figure 52 for several strakes with zero leading-edge flap deflection. Since strakes Z7-Z10 have leading-edge incidences of nominally 2 degrees, the angle of attack has been appropriately modified. The data are reasonably approximated by an adaptation of the Reference 3 methodology for double delta wings;

$$\Delta C_{\rm D} = .95 \ \Delta C_{\rm I} \ \tan(\alpha + i)$$

Some data scatter is apparent at the lower angles of attack, but the data generally fall within \pm 2 percent of the total strakeoff configuration drag.

4.2 LONGITUDINAL STABILITY

The addition of strakes, particularly forebody strakes, to a wing-body configuration produces changes in airplane longitudinal characteristics. The purpose of this portion of the investigation, therefore, is to examine the available wind tunnel data in order to define pertinent strake design factors, such as strake shape, area, location, etc., that have significant effects on longitudinal stability.

Proper strake design and location can result in a beneficial influence in maneuver lift, directional stability, and/or longitudinal stability at high angles of attack. In the longitudinal case, strakes can yield improved linearity of pitching moment characteristics, particularly in the transonic regime where wing stall usually results in a large stable break of the pitching moment curve. It was observed early in the analysis that available nose strakes had a small effect on the longitudinal characteristics (presumably because of their relatively small exposed area with respect to wing area) and were, therfore, not included in this longitudinal analysis. Forebody strakes, on the other hand, do affect longitudinal characteristics and in some cases introduce nonlinearities. These will be identified and reviewed.

The nature of the strake's effectiveness, its vortex generation, and effects on the wing and forebody, is highly dependent on the general configuration of the aircraft. Isolation of these effects (particularly in regard to stability characteristics) is difficult considering that nearly every family of strakes as tested was on a different forebody configuration, making overall correlation difficult. Additional limitations are imposed on the low-speed analysis, since relatively few forebody strakes were tested in this flight regime, and, of those that were, no corresponding strake-off condition was available. 18

4.2.1 Selected Low Speed Data and Discussion

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For both subsonic and transonic cases it is apparent from References 7 and 8 and the data of the present study that the major influences on the forward shift of aerodynamic center due to the strake are the strake's exposed area and its location ahead of the wing. The faired ogeeshaped strakes of Figure 18a are the only forebody strake family that was tested at low speed, but no strake-off case was tested. However, the variation of geometries within this family provided information as to trends due to certain design factors.

Within the linear C_L region at 0.2 Mach number, it is apparent that the primary strake characteristic influencing the change in the a.c. is its area directly ahead of the wing. For example, strakes Z63 and Z64, which have similar planforms, except that Z64 extends approximately 102 cm (40 in.)further forward on the nose, have essentially the same a.c. location (Figure 53). Configurations Z65 and Z66, both of which retain the extension forward and the basic shape of Z64 but increase the areas in the region in front of the wing, yield proportional decreases in pitch stability. These data indicate that either the more powerful vortex produced by the larger area in front of the wing or the effect of the basic wing upwash, or both, tend to make this portion of the strake highly effective in influencing the overall a.c. location in the linear region of lift. Insufficient lowspeed strake data precluded exact determination of shape effects.

The region above the linear CL is crucial from a strake design standpoint, primarily because of the effect of the strake on the airplane stall and post-stall characteristics. The addition of forebody strakes enable the wing-strake combination to continue lifting to angles of attack of 30 to 40 degrees, whereupon the combination stalls. The pitching moment curve, linear up to stall in most cases, tends to break erratically stable or unstable after stall, depending on the configuration (see Figure 53). The nature of the pitching moment break after stall is extremely important to the prevention of a deep (unrecoverable) stall. As in the lower-angle-of-attack region, strake area has a major influence, the larger strake (Z66) exhibiting the most unstable break (Figure 53). No guidelines as to area requirements could be formulated from the available data because of the geometrical limitations discussed above.

In this region, the stall characteristics are also sensitive to the forward extension of the strake. In Figure 54, strakes Z63, Z64, and Z72 all have basically the same shape and are approximately the same size, but the narrow area extension increases with strake number. Post-stall stability is degraded with forward extension. This destabilizing effect indicates that the highly swept leading-edge extension, with the area further forward, produces lift beyond stall, and the adverse effects after stall are a consequence of the resulting moment.

Finally, forebody configuration has significance in stall behavior. The group of strakes Z68 through Z70 are identical to strakes Z64 through Z66, with the exception of being mounted on an extended forebody (35.6 cm. full scale) and the strake leading edge extended accordingly. This modification results in a considerable degradation of the stall characteristics when compared to strakes Z64 through Z66 (Figure 55). Whether this is dependent on forebody extension, strake extension, or (most likely) both could not be accurately established.

The control effectiveness of the horizontal tail beyond stall seems to be affected by the same strake factors influencing stall behavior. In Figure 56, strake Z63 displays a marked change from a stable to unstable stall break with a horizontal-tail deflection of 25 degrees, resulting in diminished control effectiveness at the post-stall angles of In comparison to strake Z63, the larger strake Z66, attack. with a 25-degree tail deflection, shows a more adverse break after stall, to the extent that the pitching moment almost falls on the corresponding zero-degree tail deflection curve, indicating little nose-down pitch control authority at these angles of attack. Strake extension forward on the nose and lengthening the forebody also tend to reduce nose down control effectiveness at post stall angles of attack. Careful attention to the available post stall pitching moment is an important part of the strake design process and may well be a driving factor in selecting the strake size and shape.

4.2.2 Selected Transonic Data and Discussion

A large array of forebody strake configurations were tested transonically, thus allowing considerably more analysis and correlation work to be performed. Several approaches were followed. As mentioned earlier, the addition of strake area ahead of the wing would be expected to produce a destabilizing effect on longitudinal stability, essentially proportional to the strake size and its positioning ahead of the wing.

The a.c. shift has been correlated with pertinent strake parameters. On the basis of the results of the lift increment analysis of Subsection 4.1.3, the strake is assumed to be a low-aspect-ratio wing spanning from the body/strake juncture to the wing-leading-edge/strake intersection and inclusive of the portion of the wing directly aft of the strake (the shaded areas in Figures 38 and 39). Geometrical data for the resulting strake/wing inboard panel for several strake configurations are given in Table 5. Representative leading-edge sweeps were selected for the curved strakes as shown in Table 5. The strake lift curve slopes, $C_{L_{\alpha}}$, and the non-dimensional distance from the aerodynamic center of the constructed strake area to the aerodynamic center of the basic wing alone, $l_{\rm s}/\bar{\rm c}$, are predicted by the methods of Reference 9 and 10, respectively. The predicted values are presented in Table 6 with corresponding parameters

 $\frac{l_{s}^{A}{}_{EFF}}{cS_{REF}} \text{ and } \frac{l_{s}^{A}{}_{EFF}}{\overline{c}S_{REF}} \quad C_{L_{\alpha_{s}}}.$ The relation between the change

in the a.c. in the linear $C_{\rm L}$ region (less than 10 degrees angle of attack) due to the strake ($\Delta {\rm AC_1})$ and the parameter

 $\frac{\mathbf{L}_{s}^{A}_{EFF}}{\overline{c}S_{REF}} \quad C_{L_{\alpha_{s}}} \text{ is shown in Figure 57 for the various families}$

noted. For all of the strakes investigated, regardless of shape, flap deflection, or fuselage configuration (785 and 401F-5), a linear relationship of a.c. with

 $\frac{f_{s}^{A}_{EFF}}{\overline{c}S_{REF}} \quad C_{L\alpha_{s}} \quad \text{was essentially obtained. Only strake Z17}$

falls considerably off the correlating line. This is believed to be a result of the affected area definition for large span strakes, as described in Subsection 4.1.3. A similar linear relationship is shown in Figure 58 for the strakes tested at Mach 1.2. Such a relationship of a.c.

with $\frac{l_{s}A_{EFF}}{cS_{REF}} C_{L_{\alpha_{s}}}$ suggests the stability change in the linear

lift region due to the addition of the forebody strake is a function of the lift produced by the strake and its influenced

area on the wing, and it shows promise for the development of a semi-empirical prediction method for strakes similar to the Paniszczyn a.c. prediction method for cranked wings of Reference 3. At this time, estimation of the strake effect on aerodynamic center in the linear lift region can be roughly determined by use of the relationship established in Figures 57 and 58.

 $\Delta AC_{1} = 0.483 \frac{\boldsymbol{l}_{s}^{A}_{EFF}}{\overline{c}S_{REF}} C_{L\alpha_{s}} \text{ at } 0.80 \text{ Mach number}$ $\Delta AC_{1} = 0.296 \frac{\boldsymbol{l}_{s}^{A}_{EFF}}{\overline{c}S_{REF}} C_{L\alpha_{s}} \text{ at } 1.20 \text{ Mach number}$

Efforts to establish the change in a.c. due to strakes in the nonlinear lift region beyond the initiation of wing stall (nominally 10 degrees angle of attack) provided the results shown in Figure 59. For this nonlinear lift region the stability change (ΔAC_2) is correlated with the

parameter $\frac{l_s^{A}_{EFF}}{cS_{REF}}$. Note that the lift curve slope term is

omitted, primarily because of the characteristic nonlinear lift variation of low-aspect-ratio wings at high anglesof attack. All strake configurations exhibited essentially the same linear variation in a.c. with the parameter

 $\frac{\boldsymbol{\ell}_{s}^{A}_{EFF}}{cs_{REF}}$ for given leading-edge-flap deflections.

Deflecting the leading-edge flap in the nonlinear lift region reduces the shift due to the strake (as expected, based on the reduced lift, Figure 49). For strake configuration Z4 and a flap deflection of 25 degrees, there is a noticable change in stability over the strake-off configuration, although for this flap deflection the increment in lift due to the strake is small (Figures 26a and 27a). Thus strakes can provide beneficial linearization of the pitching moment even when the flap effects reduce the increment in lift due to the strakes.

An additional lateral shift between Configuration 785 and 401F-5 is shown in Figure 59. This is probably due to the fuselage blending of 401F-5, which results in further forward strake-off a.c. location and a smaller overall shift in a.c. due to the strake. Examination of the data contained in Tables 5 and 6 indicate that the strake shapes tested seem to evidence negligible effects longitudinally at transonic speeds. The strake shape is, however, of considerable importance in the lateral directional case, as will be discussed in the following subsection

4.3 LATERAL/DIRECTIONAL STABILITY

Maintaining directional stability to maximum usable lift is of major importance in the design of high-performance maneuvering aircraft. Generally progressive deterioration in static directional stability begins at moderate-to-high angles of attack for most conventional configurations and, consequently, limits the maximum usable lift. Strakes, both nose and forebody, have proven effective in extending the usable lift range. Herein, families of nose strakes and forebody strakes are systematically reviewed to establish their effectiveness on lateral/directional characteristics in order to formulate a strake design guide toward extending the usable lift range.

The adverse effects on lateral/directional stability due to vortex flow shed by the fuselage nose and wing-body juncture, and the associated destablizing flow field on the fuselage afterbody and at the vertical tail, have been investigated and reported in References 7 and 8. Addition of strakes, both nose and forebody, were found to produce improvements in lateral/directional characteristics, particularly at high angles of attack by altering the generated vortex flow patterns.

A survey of catalogued strake lateral/directional data revealed a lack of systematic strake geometry variation. Consequently, practical considerations result in different investigation techniques based upon the kind and amount of strake data available. In contrast to developing quantitative results, the strake lateral/directional analyses are qualitative in nature on the basis of the available data. Several reasons are addressed in support of a qualitative analysis. First, strakes are predominantly effective at high angles of attack within a region in which vortex and separated flow are extremely complex and directly dependent upon numerous aircraft variables (e.g., forebody configuration, wing sweep, vertical-tail geometry, etc.). Analysis is complicated further by the numerous fuselages on which the strakes were tested and the large nonparametric variation in the combinations of strakes, tails, and forebodies.

Additional complications arose in that most nose strakes were tested subsonically while the forebody strakes were primarily tested transonically (one family series was tested subsonically).

4.3.1 Selected Low-Speed Data and Discussion

Especially at low speed and moderate to high angles-ofattack nose strakes have a pronounced effect on lateral/ directional stability characteristics. Improvement in lateral/directional stability is influenced by the size (length and width) of the nose strake. Each baseline configuration used in the nose-strake evaluations had an integrated forebody strake. In all cases, the improvement in lateral/directional stability due to the nose strake over the baseline forebody strake case is significant. Typical results are displayed in Figure 60 for nose strake Z124 applied to forebody strake Configuration Z120 (faired ogee). The strake width and extension aft are the most significant design parameters. A typical example of the effect of nose strake extension for a family of truncated strakes is shown in Figure 61. The wider nose strakes also result in better lateral/directional characteristics (Z112 vs Z114 in Figure 62). Actual strake shape seems to be of little consequence; however, truncation of the strake (e.g., Z112, Z114) improves stability, especially laterally, compared to the same strakes faired back into the fuselage (Z110, Z113 in Figure 62).

Slight inclination of the strake with respect to the aircraft waterline is of minor consequence. This is shown in Figure 63 in which strake Z128 is rotated 5 degrees up with respect to strake Z124 (both have same planform).

As mentioned earlier, the forebody strakes were not found to be as effective lateral/directionally as the nose strakes for the wing-body-strake configurations tested in the F-16 program. Actual measurement of the forebody strake's effectiveness over the strake-off configuration was not possible since no strake-off configurations were tested at low speed. The variation of strake geometric parameters (leadingedge extensions and width) in the one family tested (Z63-Z70) displays few predictable trends since the data become quite erratic at higher angle of attack (Figure 64). The extended strake/forebody configurations (Z67-Z70 in Figure 65) are noticeably less stable than the corresponding shorter forebody combinations (Z63 - Z66 shown in Figure 64). All configurations incorporating this family of strakes became directionally unstable beyond an angle of attack of 32 degrees.

The significant difference in effectivenss between the two types of strakes leads to the following postulation for the F-16 type configuration. Without nose strakes the shed vortices from the forebody emanate from variable locations along the nose depending on the angle of attack, sideslip, configuration, etc. With nose strakes applied, especially the truncated nose strakes, the location of vortex initiation is fixed and the vortex is directed along the fuselage afterbody and vertical tail in a more symmetrical manner resulting in improved lateral/directional behavior. The effectiveness of forebody strakes on directional stability is not as significant as the effectiveness of nose strakes since the forebody strakes tend to be located behind the initiation point of forebody vortices, plus the probability that their vortices are affected by the flow field surrounding the wing. However, it must be stressed that the effects of both nose and forebody strakes and their interactions are extremely configuration oriented and the results from this set of data are not necessarily representative of other configurations.

4.3.2 Selected Transonic Data and Discussion

The nose strakes tested at transonic speeds were limited to a small number of configurations. The few that were tested again exhibited an improvement in the lateral-directional stability compared to the forebody-strake-alone case, for example nose strake Z100 (Figure 66). The first three families of forebody strakes tested offer the best comparative basis for the effects of changes to the strake geometry.

The delta-shaped family of strakes displayed rather small effects with respect to directional stability but large changes laterally with the leading-edge flap deflection set at zero (Figure 67). In this case, the largest strake of the family, Z7, exhibited an extremely destabilizing increment in dihedral effect. This family of strakes has significant anhedral, (see in Figure 7) which may contribute to this effect. Subsequent leading-edge-flap deflections decreased the over-all effects exhibited by strakes Z7 and Z10 (Figure 68). The second family, strakes Z4 (modified delta) and Z5 (gothic) exhibited improved directional stability behavior over the strake-off case (Figures 69 and 70). The change in lateral characteristics with leading-edge-flap deflection is not as great for this family (Figures 69 and 70) as for the delta-shaped strakes (Figures 67 and 68).

The third family, Z14 and Z16 - Z18 (ogee) show improvement in directional stability with adverse effects laterally with the leading-edge flap deflected 10 degrees (Figure 71). Because this was the only flap condition tested, flap effects could not be determined.

These results support some general conclusions. Adjustment of the forebody strake shape has definite effects on the lateral/directional stability, regardless of leading-edgeflap deflections. The most pertinent geometric parameters tend to be the extension of the strake forward on the nose and the width of the strake at this point. These trends are supported by the improved characteristics of the strakes Z4 and Z5 (Figures 69 and 70). Of the first three families, Z4 and Z5 extend furthest forward with the greatest width in the forward region. This conclusion is further supported by the relative stability within the fourth (Z24 - Z27) and fifth families (Z28 - Z33). For each family, the strake that extends furthest with the greatest width toward the nose (strakes Z25 and Z28, respectively) show the greatest improvement over the strake-off case (Figures 72 and 73). The reasoning behind this behavior agrees with the demonstrated subsonic stability improvements of the nose strakes compared to forebody strakes. For both cases, the obvious area of effectiveness lies forward on the nose. In that forebody strakes usually lie behind the shed point of the forebody nose vortices, their effect on lateral directional stability tends to be much less than properly positioned nose strakes. Only for cases in which the forebody strakes extend considerably forward on the nose do they show significant stability improvements. A contributing factor to the improved stability for some forebody strakes is the formation of a stronger, more stable vortex. This vortex, when sufficiently strong, provides a stabilizing influence on the wing flow field and in the afterbody region.

Obviously, the lateral/directional benefits attained through the use of strakes are of primary concern to any aircraft design. It is suggested that in configuration development well-structured testing be performed to thoroughly determine the influence of strakes on stability. In addition, care must be taken when combining nose and forebody strakes because the interactions can become significant and effects noted from separate testing are most likely not linearly additive.

4.4 DESIGN GUIDELINES

The analysis and resulting conclusions presented in the preceding sections have been qualified by the configurational dependence of high-angle-of-attack aerodynamics. However, some initial design guidelines have been developed that are believed to be valid for rather general application (at least to configurations with outboard wing panels and single vertical tails similar to the F-16). These are summarized in this subsection.

In addition to increased wing-body lift, one of the primary purposes for adding a forebody strake to a configuration is the linearization of the pitching moment curve at high angles of attack. Elimination of the typical strong stable break results in significant improvements in trim drag, which results in additional positive increments in maneuver lift.

Estimation of the aerodynamic-center shift in the linear lift region due to strakes can be made with the relations shown in Figures 57 and 58:

$$\Delta AC_1 = .483 \frac{\ell_s A_{EFF}}{\overline{cS}_{REF}} C_{L\alpha_s}$$
 at .80 Mach number

$$\Delta AC_1 = .296 \frac{l_s^A EFF}{\overline{cS}_{REF}} C_{L_{\alpha_s}}$$
 at 1.20 Mach number

and

The strake lift curve slope, $C_{L\alpha_S}$, and moment arm, l_s , are estimated by the methods of References 9 and 10, as described in Section 4.2. The effective strake area, $A_{\rm EFF}$, is defined as shown in Figures 38 and 39.

The aerodynamic-center shift above the linear region can be estimated from Figure 59. Since all configuration leading-edge-flap combinations have the same slope

 $\left(\frac{I_s^{A}_{EFF}}{cS_{REF}}\right)$ versus ΔAC_2 , the effects of variations in strake

size can easily be estimated for a particular configuration. Thus, Figure 59 can be used to size a forebody strake to provide a linear pitching moment curve.

The incremental lift effects of forebody strakes are primarily a function of the affected area, as defined in Figures 38 and 39. This means that given a particular strake, leading-edge flap, and body configuration, the lift increments that can be obtained by modifying the strake (e.g., to the strake area required for a linear pitching moment curve) are easily estimated up to the angle of attack for vortex breakdown (which may vary for different strake planforms).

$$\left(\Delta C_{L_{\text{STRAKE}}}\right)_{2} = \left(\Delta C_{L_{\text{STRAKE}}}\right)_{1} \times \frac{\left(\Delta E_{\text{EFF}}\right)_{2}}{\left(\Delta E_{\text{EFF}}\right)_{1}}$$

Furthermore, incremental lift and the stability shift due to adding a strake to a simple wing-body configuration or a blended configuration can be estimated to the first order with the curves of Figures 49 and 59 by simply selecting a similar configuration. The incremental drag resulting from the strake lift can also be obtained by use of the relation derived from the correlation shown in Figure 52:

 $\Delta C_{D} = .95 \ \Delta C_{I} \tan (\alpha + i)$

At this time general design guides have not been developed for lateral/directional stability or low-speed stall characteristics because of the large configuration-dependence of these items and the lack of parametric information. Additional, well structured, testing is required to properly isolate the effects of strake geometry on these phenomena. However, several general comments are appropriate. Care should be taken in the design of strakes to maintain adequate control capability in the post-stall region. This is a function of strake size and shape as well as tail size. Based on the data presented herein the effects of forebody strakes on lateral/directional stability become more pronounced when the strake is extended far forward on the nose.

Nose strakes strongly influence directional stability at high angle of attack. Results from the present study imply they should be truncated for best lateral characteristics. Additional important geometric parameters are the width and length. Caution is required when combining nose and forebody strake stability effects because the interactions can become significant and the effects noted from separate testing are most likely not linearly additive.

5. CONCLUSIONS AND RECOMMENDATIONS

Nose strakes offer significantly improved lateral/ directional performance with a minimum increase in wetted area and little effect on longitudinal characteristics. Forebody strakes provide beneficial linearlization of the pitching moment curve, improved maneuver lift, and in some cases, improved lateral/directional characteristics. Although the application of the strakes is highly configuration-dependent and optimization will undoubtedly require tunnel testing, initial design guidelines have been developed and several recommendations can be forwarded.

Design guidelines have been developed that allow forebody strakes to be sized to obtain a linear pitching moment curve and the resulting lift and drag increments to be estimated. The incremental lift effects have been shown to be primarily a function of the area affected by the strake induced vortex. Forebody-strake-planform shape is of secondary importance to lift generation below vortex breakdown but has a significant effect on lateral/directional characteristics.

The shape of nose strakes for lateral/directional stability seems to be of minor importance. The major positive influences are found to be the width of the strake and the truncation of the surface, that is, cutting it off rather than fairing it back into the fuselage. The nose strakes analyzed have little effect on longitudinal stability; however, increasing surface widths, and consequently area, may lead to possible adverse effects in the subsonic high-angleof-attack region.

Forebody strake effects on lateral-directional stability are most pronounced with no leading-edge flap deflection. The lateral-directional effects appear to increase as the strake is extended forward on the forebody. The extension forward on the nose, however, becomes undesirable from the standpoint of subsonic longitudinal stability at high anglesof-attack.

A need has been identified for further well-structured parametric testing designed to isolate the effects of strake geometry on, in particular, the lateral/directional-stability and low-speed-stall characteristics. It is recommended that systematic families of forebody and nose strakes be designed for a simple wing-body configuration with single and twin vertical tails and these definitive tests conducted. These data will also serve to verify and/or expand the initial design guidelines that have been developed for longitudinal effects.
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NO.	CONFIG.	Cm (in)	MAXIMUM*** WIDTH cm (in)	$\frac{A_{exp}}{cm^2(in)}$	F.S. cm(in)	W.L.* cm(in)	CANT	TYPE	FIGURE
21	401F-2	124.0 (48.8)	29.5 (11.6)	1806.4 (280)	292.1 (115)	236.2 (93)	0	canard (flat delta)	8
Z1A	401F-2,-5, -10A	124.0 (48.8)	29.5 (11.6)	1806.4 (280)	381.0 (150)	269.2 (106)	0	canard (flat delta)	8,10,11a
Z1B	401F-5,-4	124.0 (48.8)	29.5 (11.6)	1806.4 (280)	381.0 (150)	243.8 (96)	-1 ⁰ 55'	canard (flat delta)	9,10
Z1D	YF-16 +30.5 stretch	124.0 (48.8)	29.5 (11.6)	1806.4 (280)	129.5 (51)	228.6 (90)	0	canard (flat delta)	18ь
Z.2	401F-2	124.0 (48.8)	29.5 (11.6)	1806.4 (280)	472.4 (186)	256.8 (101.1)	-3°15'	canard (flat delta)	8
Z3	401F-4	215.9 (85.0)	18.0 (7.1)	2980.6 (462)	292,1 (115)	240.0 (94.5)	-1°55'	canard (flat rect.)	9
Z3	401F-5	215.9 (85.0)	18.0 (7.1)	2832.3 (439)	292,1 (115)	240.0 (94.5)	-1 ⁰ 55'	canard (flat rect.)	10
Z4+	401F-5	430.5 (169.5)	36.8 (14.5)	7851.6 (1217)	254.0 (100)	231.6 (91.2)	0	forebody (flat mod. delta)	10
Z4A +	401F-5	430.5 (169.5)	36.8 (14.5)	7851.6 (1217)	254.0 (100)	231.6 (91.2)	0	forebody (U.S. faired)	10 :
Z4B+	401F-5	430.5 (169.5)	36.8 (14.5)	7851.6 (1217)	254.0 (100)	231.6 (91.2)	0	forebody (U.& L.S. faired)	10
Z5	401F-4	494.0 (194.5)	50.3 (19.8)	14129.0 (2190)	190.5 (75)	237.5 (93.5)	-1 ⁰ 55'	forebody (flat gothic)	9
25 +	401F-5	494.0 (194.5)	50.3 (19.8)	13806.4 (2140)	190.5 (75.0)	231.6 (91.2)	-1 ⁰ 55'	forebody (flat gothic)	10
27 +	785,786	497.8 (196.0)	69.3 (27.3)	12645.1 (1960)	158.8 (62.5)	232.9 (91.7)	-4 ⁰ 01'	forebody (flat delta)	7
Z8 +	785	345.4 (136.0)	50.3 (19.8)	9812.9 (1521)	311 .2 (122.5)	247.9 (97.6)	-4 ⁰ 01'	forebody (flat delta)	7

Table 1 STRAKE GEOMETRY

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Table 1 (Continued)

	LENGTH MAXIMUM Aero (SIDE L.E. POSITION				ON TYPE		FICURE		
NO.	CONFIG.	cm (in)	WIDTH cm (in)	cm ² (in ²)	F.S. cm(in)	W.L.* cm(in)	CANT		FIGURE
Z9 +	785	332.7 (131.0)	40.9 (16.1)	7761.3 (1203)	311.2 (122.5)	247.9 (97.6)	-4 ⁰ 01'	forebody (flat delta)	7
Z10+	785	189.2 (74.5)	30.5 (12.0)	2567.7 (398)	433.1 (170.5)	256.5 (101.0)	-4 ⁰ 01'	forebody (flat delta)	7
214 +	401F-5	494.0 194.5	6.9 (2.7)	3625.8 (562)	190.5 (75)	231.6 (91.2)	0	forebody (flat ogee)	10
Z16 +	401F-5	452.1 (178.0)	21.6 (8.5)	5735.5 (889)	190.5 (75)	231.6 (91.2)	0	forebody (flat ogee)	10
217 +	401F-5	535.9 (211.0)	36.1 (14.2)	9870.9 (1530)	190.5 (75)	231.6 (91.2)	0	forebody (flat ogee)	10
218 +	401F-5	494.0 (194.5)	30.0 (11.8)	7754.8 (1202)	190.5 (75)	231.6 (91.2)	0	forebody (flat ogee)	10
220	401F-10A	642.6 (253)	**	**	55.9 (22)	231.6 (91.2)	0	forebody (faired)	11
221	401F-10A	508.0 (200)	**	**	190.5 (75)	218.2 (85.9)	0	forebody (faired)	lla
222	401F-5	632.5 (249.0)	22.9 (9.0)	8012.9 (1242)	52.1 (20.5)	231.6 (91.2)	0	forebody (flat ogee)	10
Z22A	401F-5	632.5 (249.0)	22.9 (9.0)	8012 .9 (1242)	52.1 (20.5)	231.6 (91.2)	0	slotted Z22 (flat ogee)	10
223	401F-5	430.5 (169.5)	36.8 (14.5)	7103.2 (1101)	254.0 (100)	231.6 (91.2)	0	forebody (flat mod.delta)	10
Z24 +	401F-10A	190.5 (75)	**	**	190.5 (75.0)	231.6 (91 .2)	0	forebody (faired)	11b
Z25+	401F-10A	325.1 (128)	**	**	55.9 (22)	231.6 (91.2)	· 0	forebody (faired)	11ь
Z26+	401F-10A	505.5 (199)	**	**	190.5 (75.0)	231.6 (91.2)	0	forebody (faired)	11b

Table 1 (Continued)

	[LENGTH	MAXIMUM	Aexn/SIDE		L.E.POSIT	ION		
NO.	CONFIG.	cm (in)	WIDTH cm (in)	cm ² (in ²)	F.S. cm(in)	W.L. cm(in)	CANŤ	TYPE	FIGURE
Z27 +	401F-10A	654.1 (257.5)	**	**	55.9 (22)	231.6 (91.2)	0	forebody (faired)	11b
Z28 +	401F-16	657.9 (259)	**	**	55.9 (22)	231.1 (91)	fwd of F.S. 381(150) down 1 ⁰ 27'	forebody (faired ogee)	12
Z29 +	401F-16	649.0 (255.5)	**	**	55.9 (22)	231.1 (91.0)	fwd of F.S. 381(150) down 1 ⁰ 27'	forebody (faired ogee)	12
Z29A'	401F-16	175.3 (69)	30.5 (12)	2621.0 (414)	523.2 (206)	231.1 (91)	var.	rotating (part of Z29)	15a
229A	401F-16	649.0 (255.5)	**	**	55.9 (22)	231.1 (91)	fwd of F.S. 381 (150) down 1 ⁰ 27'	slotted Z29	12
Z30+	401F-16	521.5 (205.3)	**	**	190.5 (75.0)	231.1 (91.0)	fwd of F.S. 381 (150) down 1 ⁰ 27'	forebody (fairedœlta)	12
z31 +	401F-16	440.7 (173.5)	**	**	254.0 (100.0)	231.1 (91.0)	fwd of F.S. 381 (150) dorm 1 ⁹ 27'	forebody (faired delta)	12
Z32	401F-16	638.8 (251.5)	**	**	55.9 (22)	231.1 (91.0)	fwd of F.S. 381 (150) down 1°27'	forebody (mod.faired ogee)	12
Z33	401F-16	450.9 (177.5)	sk sk	**	254.0 (100)	231.1 (91)	fwd of F.S. 381 (150) down 1 ⁰ 27'	forebody (faired ogee)	12
Z 33A	401F-16	175.3 (69)	30.5 (12)	2671.0 (414)	523.2 (206)	231.1 (91)	var.	rotating (contoured)	15a
Z33A'	401F-16	175.3 (69)	30,5 (12)	2671.0 (414)	523.2 (206)	231.1 (91)	var.	rotating (flat)	15a
Z33B	401F-16	122.9 (48.4)	21.8 (8.6)	1400.0 (217)	538.5 (212)	231.1 (91)	var.	rotating (contoured)	15a

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Table 1 (Continued)

		LENCTH	MAXIMIM	A /STDE		L.E. POS	ITION		
NO,	CONFIG.	cm(in)	WIDTH cm(in)	$cm^2(in^2)$	F.S. cm(in)	W.L. cm(in)	CANT	TYPE	FIGURE
Z33B'	401F-16	121.4 (47.8)	32.4 (8.8)	2252.9 (349.2)	542.5 (213.6)	231.1 (91)	variable	rotating (flat)	15a
Z33C	401F-16	130.3 (51.3)	23.9 (9.4)	1664.5 (258)	534.9 (210.6)	231.1 (91)	variable	rotating (contoured)	15a
233D	401F-16	76.2 (30)	16.8 (6.6)	580.6 (90)	523.2 (206)	231.1 (91)	variable	rotating (contoured)	15b
Z33E	401F-16	77.0 (30.3)	15.2 (6.0)	464.5 (72)	523.2 (206)	231.1 (91)	variable	rotating (contoured)	15Ъ
Z33F	401F-16	75.7 (29.8)	11.2 (4.4)	129.0 (20)	417.1 (164.2)	231.1 (91)	vari a b i e	rotating (contoured)	15Ъ
233G	401F-16	69.1 (27.2)	14.2 (5.6)	309.7 (48)	427.2 (168.2)	231.1 (91)	variable	rotating (contoured)	15Ъ
Z 3 3H	401F-16	76.2 (30)	16.8 (6.6)	929.0 (144)	521.0 (205.1)	231.1 (91)	variable	rotating (contoured)	15a
Z33I	401F-16							rotating Z33C removed	15a
Z48	401F-16E	449 , 6 (177)	**	**	221.0 (87.0)	231.1 (91)	fwd of F.S. 381 (150) Down 1º27'	forebody (faired ogee)	13
Z49	401F-16E	511.8 (201.5)	**	**	158.8 (62.5)	231.1 (91)	fwd of F.S. 381(150)	forebody (faired ogee)	13
Z 50	401F-16E	511.8 (201.5)	**	**	158.8 (62.5)	231.1 (91)	fwd of F.S. 381(150) Down 1 ⁰ 27'	forebody (modified faired delta)	13
255	YF-16	383.5 (151)	**	**	254.0 (100)	231.1 (91)	fwd of F.S. 444.5(175) Down 45'	forebody (faired)	14
Z56	YF-16	383.5 (151)	**	**	254.0 (100)	2 31,1 (91)	fwd of F.S. 444.5(175) Down 45'	forebody (faired ogee)	14
257	YF-16	302.3 (119)	48.3 (19)	11367.7 (1762)	368.3 (145)	231.1 (91)	variable	rotating (faired gothic)	16
258	YF-16	233.7 (92)	48.3 (19)	7387.1 (1145)	436.9 (172)	231.1 (91)	variable	rotating (faired ogee)	16

	0011070	LENGTH	MAXIMUM	Aexp/SIDE	L.E. POSITION			· · · · · · · · · · · · · · · · · · ·	
NU.	CONFIG.	cm(1n)	cm (in)	cm ² (1n ²)	F.S. cm(in)	W.L. cm(in)	CANT	ТҮРЕ	FIGURE
Z63+	YF-16 + 30.5 Stretch	416.6 (164)	**	**	254.0 (100.0)	231.1 (91.0)	fwd of F.S. 381 (150) Down 1 ⁰	forebody (faired ogee)	18
Z64+	YF-16 + 30.5 Stretch	495.3 (195)	**	**	176.5 (69.5)	231.1 (91.0)	fwd of F.S. 381 (150) Down 1 ⁰	forebody (faired ogee)	18a
Z65+	YF-16 + 30.5 Stretch	495.3 (195)	**	**	176.5 (69.5)	231.1 (91.0)	fwd of F.S. 381 (150) Down 1 ⁰	forebody (faired ogee)	18a
Z66+	YF-16 + 30.5 Stretch	495.3 (195)	**	**	176.5 (69.5)	231.1 (91.0)	fwd of F.S. 381 (150) Down 1 ⁰	forebody (faired ogee)	18a
Z67+	YF-16 + 44.5 Stretch	416.6 (164.0)	**	**	254.0 (100.0)	231.1 (91.0)	fwd of F.S. 381 (150) Down 10	forebody (faired ogee)	18a
268+	YF-16 + 44.5 Stretch	530.9 (209.0)	**	**	141.0 (55.5)	231.1 (91.0)	fwd of F.S. 381 (150) Down 10	forebody (faired ogee)	18a
Z69+	YF-16 + 44.5 Stretch	530.9 (209)	**	**	141.0 (55.5)	231.1 (91.0)	fwd of F.S. 381 (150) Down 10	forebody (faired ogee)	18a
Z70+	YF-16 + 44.5 Stretch	530.9 (209)	**	**	141.0 (55.5)	231.1 (91.0)	fwd of F S. 381 (150) Down 1 ⁰	forebody (faired ogee)	18a
271+	YF-16 + 30.5 Stretch	495.3 (195)	**	**	176.5 (69.5)	231.1 (91.0)	fwd of F.S. 381 (150) Down 10	forebody (faired ogee)	18a
Z72+	YF-16 + 30.5 Stretch	571.2 (224.9)	**	**	99.6 (39.2)	231.1 (91.0)	fwd of F.S. 381 (150) Down 10	forebody (faired ogee)	18a
273	YF-16 + 30.5 Stretch	54.6 (21.5)	4.1 (1.6)	193.5 (30)	(-30.5)	209.3 (82.4)	0	nose	185
274	YF-16 + 30.5 Stretch	54.6 (21.5)	7.9 (3.1)	387.1 (60)	+77.5	209.3 (82.4)	0	nose	185
275+	YF-16 + 30.5 Stretch	571.2 (224.9)	**	**	99.6 (39.2)	231.1 (91)	fwd of F.S. 381 (150) Down 10	forebody (faired ogee)	18
276+	YF-16	57.2 (22.5)	8.4 (3.3)	451.6 (70)	20.3 (8)	217.7 (85.7)	- 3° 30 '	nose	17
277	YF-16	123.7 (48.7)	9.4 (3.7)	1058.1 (164)	20.3	217.7 (85.7)	-3º30'	nose	17

Table 1 (Continued)

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Table 1 (Continued)

[]		LENGTH	MAXTMIM	A/STDE		L.E. POSI	TION		· · · · · · · · · · · · · · · · · · ·
NO.	CONFIG.	cm(In)	cm(in)	cm ² (in ²)	F.S. cm (in)	w.L. cm(in)	CANT	TYPE	FIGURE
279	YF-16	116.1 (45.7)	26.7 (10.5)	1567.7 (243)	144.0 (56.7)	225.3 (88.7)	-1 ⁰	canard (flat delta)	17
280+	YF-16 + 30.5 Stretch	571.2 (224.9)	**	** `	99.6 (39.2)	231.1 (91)	fwd of F.S. 381 (150) Down 10	forebody (faired ogee)	18
Z81	YF-16 + 30.5 Stretch	58.4 (23.0)	15.7 (6.2)	922.6 (143)	129.5 (51)	228.6 (90)	0	canard (flat d e lta)	18b
Z82	YF-16	104.9 (41.3)	15.2 (6.0)	735.5 (114)	144.0 (56.7)	225.3 (88.7)	-1 ⁰	canard (flat delta)	17
Z84	YF-16 + 30.5 Stretch	129.0 (50.8)	28.4 (11.2)	1806.4 (280)	131.6 (51.8)	228.6 (90)	0	canard (flat delta)	18Ъ
Z86+	YF-16	62.0 (24.4)	26.7 (10.5)	858.1 (133)	198.1 (78.0)	226.1 (89)	-1 ⁰	canard (flat delta)	17
287	YF-16 + 30.5 Stretch	416.6 (164.0)	**	**	254.0 (100.0)	231.1 (91)	fwd of F.S. 381 (150) Down 1 ⁰	forebody (faired ogee)	18Ь
288	YF-16 + 30.5 Stretch	416.6 (164.0)	**	**	254.0 (100)	231.1 (91)	fwd of F.S. 381 (150) Down 10	forebody (faired ogee)	18ъ
289	YF-16 + 30.5 Stretch	391.2 (154)	**	**	279.4 (110)	231.1 (91)	fwd of F.S. 381 (150) Down 10	forebody (faired ogee)	18Ъ
Z100+	F16	81.3 (32.0)	8.3 (3.25)	483.9 (75)	-49.8 (-19.6)	209.3 (82.4)	-2°30'	nose	20a
Z101	YF-16 + 30.5 Stretch	391.2 (154.0)	**	**	279.4 (110)	231.1 (91)	fwd of F.S. 381 (150) Down 10	forebody (faired og ee)	18Ъ
Z 102	¥F-16	416.0 (164.0)	**	**	254.0 (100)	231.1 (91)	fwd of FS. 444.5(175) Down 1 ⁰	forebody (faired ogee)	19 (same plan- form as 2104
Z103 +	F-16	416.6 (164.0)	**	**	254.0 (100)	231.1 (91)	fwd of F.S. 419.1(165) Down 1 ⁰	forebody (faired ogee)	19
[.] Z104	F-16	430.0 (169.3)	**	**	240.5 (94.7)	231 5 1 (91 5 1	fwd of F.S. 419.1(165) Down 1	forebody (faired ogee)	19

Table 1	(Continued)
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_		LENGTH	MAXIMUM	A _{exp} /SIDE		L.E. POSIT	ION		
NO.	CONFIG.	cm(in)	WIDTH	$cm^2(in^2)$	F.S.	W.L.	CANT	TYPE	FIGURE
		·· <u> </u>	cm(1n)		cm(in)	cm(in)			
Z105	F-16	442.0 (174.0)	**	**	228.6 (90)	231.1 (91)	fwd of F.S. 419.1(165) Down 1º	forebody (faired ogee)	19
Z106	YF-16 + 30.5 Stretch	533.4 (210)	**	**	137.2 (54)	231.1 (91)	fwd of F.S. 381(150) Down 10	forebody (faired ogee)	18Ъ
Z107	F-16	378.5 (149)	**	**	292.1 (115)	231.1 (91)	fwd of F.S. 419.1(165) Down 1 ⁰	forebody (faired ogee)	19
Z108	F-16	340.4 (134)	**	**	330.2 (130)	231.1 (91)	fwd of F.S. 419.1(165) Down 10	forebody (faired ogee)	19
2109	F-16	340.4 (134)	**	**	330.2 (130)	231.1 (91)	fwd of F.S. 419.1(165) Down 10	forebody (faired ogee)	19
2110 +	F-16	238.0 (93.7)	7.9 (3.1)	1200.0 (186.0)	-66.8 (-26.3)	209.3 (82.4)	-2°30'	nose	20a
2111 +	F-16	225.3 (88.7)	7.9 (3.1)	1083.9 (168.0)	-51.3 (*20.2)	209.3 (82.4)	- 2 ⁰ 30 '	nose	20a
Z112 +	F-16	99.1 (39.0)	8.4 (3.3)	66 7 .7 (103.5)	-66.9 (-26.35)	209.3 (82.4)	-2°30'	nose	20a
Z113 +	F-16	194.3 (76.5)	5.3 (2.1)	696.8 (108.0)	-51.8 (-20.4)	209.3 (82.4)	-2°30'	nose	20a
Z114 +	F-16	83.8 (33.0)	5.0 (1.95)	343.2 (53.2)	-49.0 (19.3)	209.3 (82.4)	-2°30'	nose	20a
Z115 +	F-16	96.5 (38.0)	6.1 (2.4)	327.7 (50.8)	-52.5 (-20.65)	209.3 (82.4)	-2 ⁰ 30'	nose	20a
2117	F-16	81.3 (32.0)	8.3 (3.25)	483,9 (75)	-49.8 (-19.6)	209.3 (82.4)	-2 ⁰ 30';aft 35.6(14) +2 ⁰ 30'	nose	20a
Z120 +	F-16 (F-16A Production Strake)	430.5 (169.5)	**	**	240.0 (94.5)	231.1 (91)	fwd of F.S. 419.1(165) down 1	forebody	19
Z121	F-16	378.5 (149)	**	**	292.1 (115)	231.1 (91)	fwd of F.S. 419.1(165) Down 1 ⁰	forebody	19
2123	F-16	55.4 (21.8)	7.9 (3.1)	417.4 (64.7)	-10.9 (-4.3)	209.3 (82.4)	-2°30'	nose	20Ъ

		LENGTH	MAXIMUM	Aexp/SIDE		L.E. POSI	TION		
NO.	CONFIG.	cm(in)	WIDTH cm (in)	$cm^2(in^2)$	F.S. cm(in)	W.L. cm(in)	CANT	TYPE	FIGURE
Z124 +	F-16	89.4 (35.2)	7.6 (3.0)	572.3 (88.7)	-45.2 (-17.8)	209.3 (82.4)	²⁰ 30'	nose	20Ъ
Z125	F-16	66.0	6.6	324.0	-21.6	209.3	-2 ⁰ 30'	nose	20b
Z126	F-16	(26.0) 55.3 (21.78)	(2.6) 7.4 (2.9)	(51) 283.9 (44)	(-8.5) -39.9 (-15.71)	(82.4) 209.3 (82.4)	-2 ⁰ 30'	nose	20Ъ
Z127	F-16	66.0 (26.0)	3.8 (1.5)	238.7 (37)	-21.6 (-8.5)	209.3 (82.4)	-2 ⁰ 30'	nose	20Ъ
Z128 +	F-16	89.4 (35.2)	7.6 (3.0)	572.3 (88.7)	-45.2 (-17.8)	209.3 (82.4)	+2 ⁰ 30'	nose	20Ъ
Z131 +	F-16	84.3	7.1	557.4	-39.9	209.3	-2 ⁰ 30'	nose	20c
Z131A +	F-16	71.6	7.1	461.9	-39.9	209.3	-2 ⁰ 30'	nose	20c
Z131B +	F-16	(28.2) 39.9 (15.7)	(2.8) 7,1 (2.8)	205.8	-39.9	209.3	-2 ⁰ 30'	nose	20c
Z132	F-16	33.5	6.1	128.4	-33.5	209.3	-2 ⁰ 30'	nose	20c
Z133	F-16	(13.2) 77.5 (30.5)	(2.4) 2.5 (1.0)	(19.9) 23.2 (3.6)	-33.0 (-13.0)	(82.4)	-2 ⁰ 30'	nose	20c
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Table 1 (Continued)

+ Data presented in this volume. * Leading edge when all of strake is canted, position of horizontal portion when nose is canted up or down. ** Blended configuration, A_{exp} and width are not defined. *** Maximum exposed width per side.

Model	Tunnel/Test No.	Dates	Hours	General Dynamics Report
1/15 ADF 401F -1	CAL T03-153	8/3-8/12/71	76.0	FZT-205
1/15 ADF 401F	GDLST 594-0	8/19-8/21/71	22.5	FZT-200
1/15 ADF 401F	GDHST 319-0	8/23-8/26/71	16.3	FZT-202
1/15 ADF 401F -2, -3	CAL T03-163	9/10-9/15/71	71.0	FZT-206
1/15 ADF 785/786	CAL T03-173	9/15-9/20/71	70.25	FZT-208
1/15 ADF 401F -2	CAL T03-183	9/23-9/25/71	40.0	FZT-206
1/15 ADF 401F-4	CAL T03-193	10/6-10/11/71	39.5	FZT-209
1/15 ADF 401F-5	CAL T03-193	10/13-10/19/71	37.5	FZT-210
1/15 ADF 785	CAL T03-193	10/19-10/21/71	33.5	FZT-208
1/15 ADF 401FS-3	CAL T03-203	10/21-10/25/71	29.25	FZT-207
1/15 ADF 786	CAL T03-203	10/29-10/29/71	13.0	FZT-208
1/15 ADF 401F-5	CAL T03-213	11/12-11/15/71	24.0	FZT-210
1/15 ADF 401F-10A,5A	CAL T03-213	11/17-11/23/71	92.5	FZT-211
1/15 ADF 401F-16	CAL T03-223	12/7-12/13/71	78.0	FZT-212
1/15 ADF 401F-16,5A	GDLST 594-1	12/14-12/30/71	122.0	FZT-228
	GDLST 594-2		8.0	FZT-228
	GDHST 319-2		53.0	FZT-227
1/15 ADF 401F-16	CAL T03-233	1/3-1/7/72	69.5	FZT-212
1/15 ADF 401F-16	GDLST 594-3	1/11-1/18/72	· 80.0	. FZT-228
	GDHST 319-3		14.0	FZT-227
1/15 ADF 401F-16E	CAL T03-253	1/27-2/3/72	127.0	FZT-224
· · · · · · · · · · · · · · · · · · ·		2/5-2/7/72		
1/15 ADF 401F-16	CAL T03-243	2/3-2/5/72	. 22.0	FZT-225
1/15 ADF 401F-16E	ARC 11-652-1	2/25-2/29/72	50.0	FZT-401-003
1/15 ADF 401F-16E	GDHST 319-4	5/2-5/9/72	34.0	FZT-401-012
1/15 ADF 401F-16E	GDLST 613-0	5/10-5/12/72	54.0	FZT-401-013
1/15 ADF 401F-16E	CAL T03-273	5/16-5/19/72	34.0	FZT-401-004
1/15 YF-16	CAL T03-283	7/12-7/17/72	35.0	FZT-401-010
1/15 YF-16	CAL T03-293	7/17-7/20/72	61.75	FZT-401-011

Table 2 YF-16 & F-16 DEVELOPMENTAL FORCE TESTS

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Table 2 (Continued)

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[· · · · · · · · · · · · · · · · · · ·	General Dynamics
_Model	Tunnel/Test No.	Dates	Hours	Report
1/15 YF-16 + 30.5	CAL T03-373	9/18-9/19/74	33.0	FZT-401-032
Stretch				
1/15 YF-16(Wing-	CAL T03-383	9/20/74	11.75	FZT-401-032
lets)				
1/15 YF-16(B1con-	CAL T03-393	9/21/74	13.25	FZT-401-032
1/15 VF-16 + 30 5	AFDC TE-357	10/12 - 10/20/76	100 7	ፑፖጥ / 01 020
Stretch	ABDC IF-JJ,	10/12-10/30//4	122.7	r21-401-038
1/15 YF-16 + 30.5	GDLST 677-0	2/10-2/13/75	58.0	16PR029
Stretch, F-16		-/ 20 -/ 20// 5	50.0	101 102 /
1/15 YF-16, F-16	CAL T03-403	2/18-2/22/75	44.75	16PR029
1/15 F-16	GDLST 677-1	2/24-2/25/75	25.5	16PR029
1/15 F-16	GDHST 385-0	2/25-2/28/75	23.5	16PR029
1/9 F-16	GDLST 681-0	4/25-4/27/75	22.5	16PR047
1/9 F-16	AEDC TF-380	5/1-5/14/75	153.7	16PR048
1/9 F-16	AEDC SF-175	5/15-5/18/75	43.7	16PR048
1/9 F-16	ARC 12-082-1	5/27-6/4/75	77.75	None
1/9 F-16	GDLST 681-1	6/6-6/26/75	135.5	16PR137
1/15 F-16	GDHST 385-1	7/7-7/11/75	19.6	16PR082
1/15 F-16	GDLST 677-2	7/18-7/21/75	20.0	16PR082
1/9 F-16	AEDC TF-390	8/21-9/9/75	224.0	16PR134
1/15 YF-16 (AIM 7)	LTV VSD 564	10/16-10/20/75	50.0	FZT-272
1/9 F-16	AEDC SF-177	10/27-11/4/75	67.5	16PR134
1/15 F-16(Stores)	CAL T03-443	11/4-11/15/75	131.5	FZT-271
	CAT TO2.452			1 -
1/15 F-16	IRC 4-1140	10/2-10/1//75	100 1	F777 076
1/9 F-16		1/20 - 1/20/76	120.1 51.0	FZT-2/0
1/9 F-16	CDIST 600_1	$1/20^{-1}/30/70$	J1.0	16PK222
1/7 1-10		2/13-2/20/70	40.0	FZT-280

Table 2 (Continued)

Table 2 ((Continued)
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Model	Tunnel/Test No.	Dates	Hours	General Dynamics Report
1/9 F-16(AIM 7)	GDLST 690-2	2/25-2/26/76	9.5	FZT-280
1/15 F-16(AIM 7)	LRC 4-1146	3/8-3/19/76	96.0	FZT-282
1/15 F-16(AIM 7)	CAL T03-483	3/15-4/5/76	66.0	FZT-285
1/9 F-16	GDLST 695-0	4/19-4/23/76	33.5	16PR299
1/9 F-16 (Stores)	AEDC TF-406	5/7-5/29/76	234.1	16PR331
1/15 F-16 (Stores)	LRC 4-1172	11/4-11/17/76	54.0	FZT-293
1/15 F-16	LRC 4-1174	11/12/76	9.0	FZT-293
1/15YF-16, F-16	LRC 4-1180	12/6-12/10/76	46.0	FZT-294
1/9 F-16 (Stores)	AEDC TF-451	4/29-5/11/77	108.6	16PR814
1/9 F-16(AIM 7)	GDLST 721-0	7/11-7/12/77	18.0	FZT-318
1/9 F-16(Pave Penny)	GDLST 709-0	7/13-7/15/77	24.0	16PR761
1/9 F-16(Drag Chute)	GDLST 708-0	7/18-7/19/77	20.0	16PR761
1/9 F-16(Spin Chute)	GDLST 724-0	7/19-7/20/77	9.0	16PR761
1/15 F-16	LRC 4-1216	8/22-8/26/77	32.0	FZT-309

TADLE 3 WIND TUNNEL TESTS USED FOR STRAKE ANALYSI

SPEED	TUNNEL	TEST	TEST CODE FOR PLOTS	STRAKES
Low	GDLST	594-1 594-3 613-0 625-0 662 664 677-0 677-1 677-2 * 681-1 * 690-1 *	5941 5943 6130 6250 6620 6640 6770 6771 6672 6811 6901	222,222A,229,229A,231,233,233A',233B' 229,233,233A-233I 233,250 255,256,257,258 233,263-266,267-270 263,264,272,274-277,279,280,282,284,286-289 263,287,2100-2106 2103,2107-2115,2117 2124 279,2120,2123-2128 2131,2131A,2131B,2132,2133
Transonic	CALSPAN AEDC 16T	T03-163 T03-173 T03-193 T03-193 T03-193 T03-203 T03-213 T03-213 T03-223 T03-233 T03-253 T03-273 T03-273 T03-363 T03-403 T03-443 * TF-390 *	1630 1730 1830 1930 1931 1932 2031 2130 2131 2230 2330 2530 2730 3630 4030 4430 3900	Z1 OFF Z1A,Z2 Z1B,Z3,Z5 Z7,Z8,Z9,Z10 Z1A,Z1B,Z3,Z4,Z4A,Z4B,Z5,Z14,Z16,Z17,Z18 Z7 Z1A,Z22,Z23 Z1A,Z20,Z21,Z22,Z24,Z25,Z26,Z27 Z28,Z29,Z30,Z31,Z32 Z31,Z33 Z33,Z48,Z49,Z50 Z33,Z50 Z1D,Z63-Z66,Z71-Z75,Z80,Z81 Z100,Z102,Z103,Z108,Z109 Z124 Z128
Supersonic	HST LRC	375-0 4-1140 *	3750 1140	Z63,Z64,Z87,Z88 Z124

* contains data for F-16 production strake/wing/fuselage configuration

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								LO	I SP	EED					1												TRA	NSON	TC											
ĺ	{					PI	тсн					S	IDES	SLIP	t			_				P	ITC	1					1				SIL)ES	LIP			NASA	CR-158922	ĺ
STRAKE	WING	CONFIGURATION		LEF					HT			LE	F	HT			LEF				HT	1	T			MA	СН				LE	F	1	łT		MA	СН	-	. FIGURE NUM	BERS
		(1) (2)	0 1	5 25	35	OFF	-25	-20) <u> -1</u>	0 0	25	0	25	0	0	5 1	0 1	5 2	5 -	-30	-20	-10	0.	6.	8	<u>9 1.</u>	2/1.	6 2.	0 0	5	101	15	25	0	. 8	9 1	.2 2.0			
<u>z1</u>	W3	401F-2 (TV)			L		L											×	:				x		<u>.</u>					Li	_		×	x	x	_		3-1,	+-1	
ZIA	W3	401F-5													×)'	•	×	•				x	1	•	×			x		×		×	×	x		x	3-2,3	-3,3-4,3-12,3-13 3-41,4-7,4-8,4-9 4-15,4-16	;
		401F-2 (TV@150)								1				х	Τ		×					x	2		×			x	Π			x	x	x		x	3-5,3	-7,4-4,4-5	
		401F-2						1	1		1		-		Π		1	к					x	,						T I			x	x	x	1		3-6,4	-6	
}		401F-2(TV@7.5)								T						Τ	Τ	1							Ţ			x	Π				x	x	Τ	x	4-2,4	-3	
		401F-10A				-					1				x	,	ĸ						x	,	(×					x			x	x			3-36,	3-37,3-38,4-34	
Z18	W3	401F-5						T			Τ				x	Τ							x	,	(x			x		x			x	\mathbf{x}^{l}_{i}		x	3-12,	3-13,4-15,4-16	
1		401F-4 (TV)				-					T		· [T											×					×	×		x	4-12,4	•14	
Z1D	₩ЗВВ	YF-16+30.5Scr	•												×			×					x	,	(x	×			×				x	x	1	×		3-74, 4-52	3-75,3-76,3-77,4	J-51
Z2	W3	401F-2(TV)													×		Τ	Τ					x	;	(1		x					x	x			3-8,4	-11	
23	W3	401F-4(TV)									T				×				T				x	1	(x	×			x		Τ			x	x	×	×	3-9,3 4-14	-10,3-11,4-12,4-	-13,
		401F-5					1								×				1				x	,		x			×	\square	x			x	x	-	x	3-12,	3-13,4-15,4-16	
Z4	W3 .	401F-5		1				T							×	,	(x	×	-	-			x	,	(×			x		x	x	x	×	x		x	3-14, 3-20,	3-16,3-17,3-18,3 3-21,3-22,3-23,4	3-19 4-17

		401F-2					.1		_								1	^			1	^]		<u>.</u>	-	.1	1	_	-		1						
		401F-2 (TV@7.5				-			Τ	T																		x				x	x		x	1	4-2,4-3
		401F-10A						1				1	-	,	,	×		-		1		x	- ,		×				×			x	x	1			3-36,3-37,3-38,4-34
18	W3	401F-5	1				T	Τ		1		1		,		T	1		-		1	x	,	,	×			x	×	1	1	x	x		x		3-12,3-13,4-15,4-16
		401F-4 (TV)													T			1		1								x	1			×	×		x ;	1	4-12, 4-14
1D	W3BB	YF-16+30.5Str													(×				×	,	• •	(x			x			x	x	×	:			3-74,3-75,3-76,3-77,4-51, 4-52
2	W3	401F-2(TV)						1												Ţ	1	x	,	,				x	1			x	x				3-8,4-11
.3	W3	401F-4(TV)								1					•							x	1	. ,	ı x	1		x			1	x	xx	-	x		3-9,3-10,3-11,4-12,4-13, 4-14
		401F-5									1-				(x	2	(x			x	×			x	x		x		3-12,3-13,4-15,4-16
:4	W3 .	401F-5													•	x	x	×				x	,	ſ	×			x	×	×	x	x	×		×		3-14,3-16,3-17,3-18,3-19 3-20,3-21,3-22,3-23,4-17 4-18,4-19,4-20,4-21
4A	W3	401F-5								T	[(x	1				x	,	:	x		1		x			x	x	1		_	3-18,3-19,3-20,4-17
4B	W3	401F-5		1									1	•			x					x	,	•	x				x	1		x	x		- [3-18,3-19,3-20,4-17
5	W3	401F-5														x					Т	x	,		x			x	×			x	x		x		3-21,3-22,3-23,4-18,4-19
	w3	401F-4 (TV)																1						Τ			-	x				×	x		x		4-22,4-23
.7	W6	785					$\left \right $			1		1			• • •	-	x		x	×	x	×	,		×			x	x x	×	T	x	×		×		3-24,3-25,3-26,3-27,3-28 3-30,4-24,4-25,4-26,4-27
		786 (TV)														×	x					×	,	:	x	\top		×	x x	x		x	×		×		4-28 3-31,3-32,3-33,3-34,4-29 4-30,4-31,4-32,4-58
8	WÓ	785													:					Ĭ		x	,	;	x			x				x	x		x		3-24,3-25,4-24,4-25
9	W6	785																				×	,		x			x				x	×		×		3-24,3-25,4-24,4-25
10	W6	785													ц ж	:	x					×	,	:	x			x	××	×		x	x	Ţ	×		3-24,3-25,3-26,3-27,4-24 4-25,4-26,4-27,4-28
.14	W3	401F-5														x						x	,	;					×			x	x				3-35,4-33
16	W3	401F-5														×						×	١,	:					x			×	x				3-35,4-33
17	w3 -	401F-5														x				1		x	,	:					×			x	x				3-35,4-33
18	W3	401F-5										1				x		1		Ι		x	,						×			x	x				3-35,4-33
20	W3	401F-10A													x	x		x				x	,	:	x				×		x	x	x				3-36,3-37,3-38,3-39,4-34 4-35
21	W3	401F-10A			;										×	×		x				×	,	:	×				×	:	×	x	x				3-36,3-37,3-38,3-39,4-34 4-35

Table 4 (Continued)

						-				LOW	SPE	ED				[Т	RANS	ONIC	2										
1						_	P	ITCH		10.				IDE	SLIP	L_				-			PITC	CH I						1-				IDE	ESL	IP	- 62	011	_	NASA CR-158922
STRAKE	WING	CONFIGURATION	011	5	EF 251	35	OFF	-25	1-20	4T 11 - 14	าโกไ	25		F 25	HT 0	01	511	LEF	512	5	- 301 - 2	<u>HT</u>	1010	1,	. s	1 0	MAC	ห อ[า	612		151	LE 101	3F 151	25		8	۳۷ ۹۱۱	22	0	FIGURE NUMBERS
722	w3	401F-5		1		x	011			×	x		-			x	1,	x	1	1	<u></u>			×	x		1	1.	1	+	H		-		Ť	<u>.</u>	1		-	1-1,1-2,3-40,3-41
Z22A	W3	401F-5	\vdash	╋	-	x				×	x					11	╈	╈	╀	+				+	T			1	-	+			1	-†	1		1			1-1,1-2
Z23	W3	401F-5		1		-1										x	-	x	+-	\uparrow		+		x	x	1			1	+					1					3-40,3-41
z24	W3	401F-10A		-						1-						x	1	x	-			+		×	x	x		1	1	T	Ħ	x		×	×	x	x			3-42,3-43,3-44,3-45,3-46,
7.25	W3	401F-10A	┝╌┼	-+	-+				<u> </u>	+	╋		-			x	+	×	-	: † ·				×	x	x		┢	-+	+	\square	x	+	x	׆	x	×		+	4-36, 4-37, 4-38 3-42, 3-43, 3-44, 3-45, 3-46, 4-36, 4-37, 4-38
Z26	W3	401F-10A		+	+	- 1			-		+-					x	+	×	 ×	-	_	1		×	x	×	-	+	+	-†-	\square	x	-	x	×	x	×	+		3-42,3-43,3-44,3-45,3-46
z27	W3 -	401F-10A	\mathbb{H}	+		-			+	+	+	H					-+-	×	-	-		-+-	†:	x	×	x		-		-		x	\neg	×	×	x	-+-	+-	-+	3-42,3-44,3-45,3-46,4-36
228	W3	401F-16		-							+					×	-	x	8	-				×	×						\uparrow	x		x	x	x				<u>4-57</u> 3-47,3-48,3-49,4-39,4-40
229	W3	401F-16				x					×					×	1	×	×	:			:	x	x							×		x	×	x			ļ	1-3,3-47,3-48,3-49,3-50, 3-51,4-39,4-40,4-41,4-42
229A	W3	401F-16	$\left[\right]$			x			[×					Π	T			Τ						Γ				T	Π						Ţ			1-3
Z30	W3	401F-16		-												k	1	ĸ	ж	:			:	x	x	T						x		x	×	x				3-47, 3-48, 3-49, 4-39, 4+40
Z31	w3	401F-16														×	,	x	×	:				x	x							ĸ		x	x	×				3-47, 3-48, 3-49, 3-52, 3-53, 3-54, 4-39, 4-40, 4-43, 4-44
Z32	w3	401F-16	Π														,	ĸ	×				-	×	x	Γ	Τ		T	Τ		ĸ		×	×	x				3-50,3-51,4-41,4-42
z33	W3	401F-16	x		×	x			x	x	×			х	x	x	,	ĸ	ж	:				×	x				1			×		x	×	×				1-5,1-6,1-8,1-9,2-1,3-52 3-53,3-54,4-43,4-44
	W 3вв	401F-16E		1												ĸ	x	T	х					×	ĸx	×	×										T			3-55,3-56,3-57,3-58,3-59, 3-60
233A	W3	401F-16				x				x															1						1									1~5
Z33A'	W3	401F-16	Π			x				x	Τ														1												1			1-4
Z33B	W3	401F-16				х				x														Ι													-			1-5
Z33B'	W3	401F-16				x				x															ì								1							1-4
233C	wз	401F-16				x				x	×															Ī			,	T	;			-			1			1-5,1-7
233D	W3	401F-16				x				×										-					Ì									- 1			1			1-5
Z33E	W3	401F-16				x	_			x															1	1		Ì				1	i		1		i			1-6
Z33F	W3	401F-16				x				x	T																I			T		ļ	1		5					1-6
233G	wЗ	401F-16	Π		Ĩ	x				×						П	T										T		Τ	T			Ţ		ł		Τ			1-6
Z33H	W3	401F-16	Π	T		x				ĸ									T							:	1	1		T				1	:				ې—. ا	1-6
Z331	W3	401F-16		_		x					x						T					-	-	Ţ		1	1			T			i	- 1						1-7
Z48	W3BB	401F-16E									1						x						1	ĸİ	1	x	1	1		T									7	3-60
z49	W3BB	401F-16E	Π	I							Т					1	×	1					1	K (X	Τ	Τ			i	- 1		Ţ						3-60
250	W3	401F-16	×		x				x		×			x	x	11		Τ				-			-	1			T						2		1	-		1-8,1-9,2-1
	W3BB	401F-16E														x	x		×					ĸ i ı	(x	x	×								ľ					3-55,3-56,3-57,3-58,3-59 3-60
255	W3BB	YF-16		x							×									1	1	1				1	T	T	Ì											1-10

Table 4 (Continued)

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		i .					PI	ГСН	•					IDES	LIP								Ρľ	гсн			·					_			ID	SLI	IP				NASA CR-158922
STRAKE	WING	CONFIGURATION		L	EF				1.0	HT	-	- 10	1-1-	EF	HT		- 1.7	LE	F	_		H	ir T					MAC	H	-	_		1	EF	0.	HT	-		MAC	H	FIGURE NUMBERS
			0	15	25	35	OFF	-25	-20) - 1	0	9 2	50	25	0	10	5	10	15	25	- 30	-20	<u>) - 1</u>	0 0	.6	.8	.9	1.2	11.6	<u>2.</u>	0 0) 5	110	15	25	0	. 8	.9	1.	212.0	
256	W3BE	YF-16	\vdash	x	_	_			-			< <u> </u>	_			\downarrow		_						4				Ļ	┣	_			 	ļ		\square	_		L	_	1-10
257	W3BB	YF-16	\square	x	-+	-+			4	+	-	4-	1	 	<u> </u>	╉╌┨		-		-			+			\square				+	+	+	-		[\square					1-11
Z58	W3BB	YF-16	\downarrow	×		\downarrow			-	1		<u>ر</u>	1	_	L	┶┿	_	_	_	_				_						_			1	-	ļ				L		
263	W3BB	YF-16+30.5Str YF-16+30.5Str +N6	x		×		×	×		x		c :	×	×	x x	x				×				2	5	x	x	x	x	x	1	¢			x	x		×)		$\begin{array}{c} 1-12, 1-14, 1-15, 1-16, 1-23, \\ 1-24, 1-25, 1-26, 1-27, 1-30, \\ 1-32, 1-33, 2-2, 3-66, 3-62, \\ 3-64, 3-54, 3-56, 3-67, 3-68, \\ 3-64, 3-56, 3-76, 3-77, 3-63, 3-77, \\ 4-45, 4-46, 4-49, 4-50, 4-51, \\ 4-52, 2-3, 2-4, 2-10, 2-11, 2-13, \\ 2-16 \end{array}$
264	#38B	¥F-16+30.5Str	×		×						,	< ×	-	×	х	×				×				*	"	x	×	×	×	×	1	•			×	×					1-12,1-17,1-18,1-23,1-24, 2-2,2-9,3-61,3-62,3-63, 3-64,3-65,3-66, 4-45,4-46
		¥F-16+30.5Str +N6			×						,	×																													2-3
Z65	W3BB	¥F-16+30.5Str.			×							×		×	×	x				×				ж	•	×	x	x			,	•				x		x			1-12,2-2,3-61,3-62,3-63, 3-64,4-45
Z66	извв	¥F-16+30.5Str.	×		×		x	x		×	×		•	×	x	×				×				×	"	×	x	×			,	¢			x	x		×			1-12,1-14,1-15,1-16,2-2, 3-61,3-62,3-63,3-64,4-45, 4-46
		YF-16+30.5Str. +N6												×	×																									1	2-4,2-6
Z67	•Звв	YF-16+44.5Str.	k		x					1	×	(x	:	x	x							1	1											ļ	1		· .	ł	1		1-13,1-19,1-20,2-7
		YF-16+44.5Str. +N6		-						T				×	x																										2-8
Z68	V3BB	YF-16+44.5Str.	×		×	1					×	; ,	1	x	x								1		1		1					T			1	1. 1		1	1		1-13,1-17,1-18,2-7,2-9
760	1200	VE-16164 5000									_		Τ	1.			П	_																	1			1		1	1-13,2-7
z70	V3BB	YF-16+44.5Str.	×		x					1	;	x	×	×	x				1		_		1	1					1	1				$\left[\right]$				f			1-13,1-19,1-20,2-7
		YF-16+44.5Str +N6												×	×																	T						ι			2-8
z71	WЗВВ	YF+16+30.5Str												1		×				x				×		x	x	x				×			x	x		x			3-61,3-62,3-63,3-64,4-45, 4-46
z72	W3BB	YF-16+30.5Str			×						-	×	×	×	x	x				×				x		x	x	×	-	 		×			x	×		×			1-23,1-24, 2-3,3-70, 3-71,3-72,3-73,4-47,4-48
Z73	W3BB	YF-16+30.5Str	LI													x								x		×	x	x				x			x	x		x			3-67,3-68,3-69,4-49,4-50
z74	W3BB	YF-16+30.5Str	x		x							×	×	x	x	x								×		x	×	x				x			×	x		x			1-25,1-26,2-10,2-11,3-67, 3-68,3-69,4-49,4-50
z75	w3вв	YF-16+30.5Str			×							××		×	x	×				x				×		x	×	×				x			×	×		×			1-28,1-29,2-12,3-70,3-71, 3-72,3-73,4-47,4-48
<u>z</u> 76	W3BB	¥F-16			×							××		×	×				$ \downarrow$						_	-	.			1_			<u> </u> _						 		1-21,1-22,2-14
277	w3вв	YF-16			_	_			1					×	×		ĺ						_					-						 				ļ	-		2-15
z79	₩Звв	YF-16												×	×		i					1				ĺ			Ì			I		ŀ							2-15

Table 4 (Continued)

	r	r	F						nu «	PEET				r .												TRAM	ISON	IC				· • · • · •				· · · · · · · · · · · · · · · · · · ·
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STRAKE	WING	CONFIGURATION		LEF	7			ł	т		1	ĒF	HT	1	1	LEF		<u> </u>	Н	IT				1	MACH	1		1		LEF		HT		MA	СН	FIGURE NUMBERS
			0 1	5 25	35	OFF	-25	-20	-10	0 2	5 0	25	0	0	5 10	0 15	5 25	- 30	-20	0-10	0	.6.	8	. 9	1.2	1.6	2.0	0	5 1	0 1	5 25	0	8.	91	.2 2.	ō
280	W3BB	YF-16+30.5Str		×						хх		×	×	×			×				×		×	x	x			×			×	×	×			1-28,1-29,2-12,3-70,3-71, 3-72,3-73,4-47,4-48
Z81	W3BB	YF-16+30.5str	T											x			×				×		×	×	×			x			×	×	×	:		3-74,3-75,3-76,3-77,4-51, 4-52
282	W3BB	YF-16										x	x			T																				2-15
Z8 4	W3BB	YF-16+30.5Str		х	T					xx		x	x				Τ	[1-26,1-27;2-11
286	W3BB	YF-16		x						x		x	x															Ĺ								1-21,2-14
Z87	₩ЗВВ	YF-16+30.5Str	×	×						××	×	x	×	x							x					x	×									1-28,1-29,1-30,1-32,1-33, 2-12,2-13,2-16,3-65,3-66
Z88	W3BB	YF-16+30.5Str		×						,				x							x					x	x								_	1-31,1-57,3-65,3-66
289	₩ЗВВ	YF-16+30.5Str		×						ж															_											1-31
Z100	₩ЗВВ	YF-16		×						xx		x	x																							1-34,2-17
	W24	F-16	Π		T				T	Π				x			1	1			x		T	x							x	x	x			3-78,4-53
Z101	₩Звв	YF-16+30.5Str	T	x			1			хх	1-	x	x									[]				ŀ										1-32,1-33,2-16
z102	w3вв	YF-16										x	x								T,															2-17
z103	WЗВВ	F-16	×	×						××	x	×	x	x				1		1	x			x	x											1-35,1-36,1-37,2-18,2-20, 2-21,3-78,3-79,3-80,3-81, 3-82,4-53
	W24	F-16	×	×						хх	x	x	×																							1-38,1-39,1-40,1-41,1-44, 2-19,2-20,2-22
		F-16+Z112		x						×		x	x							1	i														_[1-42,1-43,2-23
2104	W3BB	F-16	┝┥╴	x						x x	_	x	×	\downarrow				<u> </u>			4		_								_	\downarrow				1-36,1-37,2-18
	W24	F-16		x	_					xx		x	×															_								1-39,1-40,2-19
Z105	W3BB	F-16		x				<u> </u>		xx	_	x	x																				1			1-36,1-37,2-18
	W24	F-16	\downarrow	x		<u></u>	Ļ.	<u></u>	ļ	XX		<u> </u>	×			_			1									1.			_		i			1-39,1-40,2-19
Z106	<u>W38B</u>	F-16+30,5Str.	╟╟╴	x	+	ļ	ļ	ļ		xx		x	×	++		+	_	<u> </u>		, 	╞						<u> </u>	4			_	\vdash				1-32,1-33,2-10
Z107	w24	F-16		×			ļ			×	_	x	×						-	;			<u> </u>	\square						_	-				_i	1-41,2-22
ļ	 	F-16+2112		x	<u> </u>	<u> </u>	<u></u>	<u> </u>	L	1				-			_			i]			\square							1-43
Z108	W24	F-16		x			: 			1 7		×	×	x	1	į				I	x		j	x	x		i)	-					1-41,2-22,3-79,3-80
L	L	F-16+2112		x			ļ			×										? 							Υ			1	1-					1-43
Z109	w24	F-16		×						×				×	Ĺ			1			x		ĺ	x	x		۱ ۱				}					1-41,1-45,3-81,3-82
L		F-16+2112		x	_	<u> </u>	 			×						1	L	1	1								:	İ.								1-42,1-43
Z110	W24	F-16										x	x			i		1								E										2-24,2-25
Z111	W24	F-16	\square	_		1	L	L	1	\square	1	х	x						1				1				1	1			Í			Ĩ.		2-24
Z112	W24	F-16		x								x	<u> </u>									: •	r									11				1-44,1-45,2-24
<u>2113</u>	₩24	F-16					:					x	x					i.					1			}					1					2-24
Z114	w24	F-16					İ	L.,				x	x	i			i.																			2-24
2115	W24	F-16										x	x				ļ		1.			. 1											Ţ			2-24
Z117	W24	F-16					i					x	x	iJ	T		L													Τ			;	1		2-25
Z120	w24 w25	F-16		×						××	x	×	x	Í																			Ì			1-46,1-47,1-48,1-49,1-50, 1-51,1-52,2-26,2-27,2-28, 2-29,2-30,2-31

	<u> </u>							LO	₹ SPE	ED														-		Т	RAN	ISON	IC										
		1			I	ITCI	1		_			SI	DESL	IP							PIT	CH											DES	LIP					NASA CR-158922
STRAKE	WING	CONFIGURATION		LE	F			1	T			LE	F	ĤT		_	LEF				HT					MA	CH					LEF	·	HT			MACI	1	FIGURE NUMBERS
I	L		0 1	5 25	5 35	OFF	-25	-20	- 10	0	25	0	25	0	0	5/1	0 1	5 2	5 - 3	0 -	20	-10	0.	6 .	8.	911.	. 2	1.6	2.0	0	5 1	0 1	5 29	i 0	. 8	. 9	1.2	2.0	
z121	W25	F-16											x	х		1].	ļ.	[2-26
z123	W25	F-16		×	T					×	Τ		×	×	Π	T														Π				Γ			•		1-51,2-31
Z124	W24 W25	F-16		×						x	×	x	x	x	x								x						x	x				×			×	x	1-47,1-48,1-49,1-50,1-52, 2-27,2-28,2-29,2-30,4-54 4-55
Z125	W25	F-16 ·		×					1	×		-	x	×	17	1	1			T										1-11			-	Ť			Γ		1-51,2-31
Z126	₩25	F-16		×					1	×			×	×												_													1-51,2-31
2127	W25	F-16		x						x			x	x	\Box											Τ			• •		1		Τ						1-51,2-31
z128	W25	F-16		x						x	Ţ		x	x			T	Τ									T			×				×			x		1-52,2-30,4-56
2131	W25	F-16		x						x	T		×	x	Π			T		Τ					T	-				Π		Τ	1						1-53,1-54,2-32,2-33,2-36
Z131A	W25	F-16											x	×																									2-32
2131B	W25	F-16			Γ					T			х	x	П																		Τ	-				T.	2-32
z132	W25	F-16		×						x	Í		x	x			Τ											-											1-54,2-33
z133	W25	F-16		x				1		x			x	x																						ŀ			1-55,2-34

Table 4 (Continued)

NOTES :

(1) Configurations have single vertical tail unless noted as twin vertical (TV)

(2) The YF-16 fuselage was stretched 25.4 cm (10 in) for the F-16

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STRAKE	AR _{EFF}	b _{EFF} m (ft)	c _r m (ft)	c _t m (ft)	Λ _{LE} Degrees	A _{EFF} m ² (ft ²)
Z7	. 308	1.57 (5.17)	6.78 (22.25)	3.45 (11.33)	77.0	8.06 (86.75)
Z8	. 287	1.37 (4.5)	6.10 (20.0)	3.45 (11.33)	75.0	6.55 (70.49)
Z9	. 257	1.27 (4.17)	6.30 (20.67)	3.58 (11.76)	77.0	6.28 (67.56)
Z10	.157	.71 (2.33)	5.31 (17.42)	3.76 (12.33)	77.0	3.22 (34.66)
Z4	. 293	1.68 (5.5)	7.19 (23.58)	4.27 (14.0)	73.5	9.60 (103.35)
25	. 262	1.68 (5.5)	7.62 (25.0)	5.21 (17.08)	71.0	10.73 (115.50)
Z16	. 192	1.17 (3.83)	7.06 (23.17)	5.13 (16.83)	73.5	7.12 (76.65)
Z17	.436	2.79 (7.5)	6.48 (21.25)	4.01 (13.17)	65.5	11.99 (129.08)
Z18	. 297	1.68 (5.5)	6.65 (21.83)	4.65 (15.25)	67.5	9.47 (101.98)

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				M = 0.8	30				M =	1.20		
STRAKE	A _{EFF} m ² (ft ²)	<i>l</i> s/ē	C _{Lαs} per radian	L _S A _{EFF} c s _{REF}	$\frac{I_{S} A_{EFF}}{\bar{c} S_{REF}} C_{L\alpha_{S}}$ per radian	AC 1	AC 2	1 ₅ /c	C _L ρer radian	$\frac{l_{s}}{\bar{c}}$ a _{eff} \bar{c} s _{ref}	$\frac{l_{\rm S} \Lambda_{\rm EFF}}{\bar{c} S_{\rm REF}} C_{\rm L} \alpha_{\rm S}$ per radian	AC1
Z7	8.06 (86.75)	.69	.468	.214	. 100	.049	. 34	.81	.530	.25	.133	.045
Z8	6.55 (70.49)	.642	.443	. 162	.072	.041	.29	.772	.486	.194	.094	.03
Z9	6.28 (67.6)	.670	. 395	.161	.064	.029	. 28	. 80	.432	.193	.083	.02
Z10	3.22 (34.7)	.596	.244	.074	.018	.014	.24	.76	.248	.094	.023	.01
Z4	9.60 (103.3)	.815	.452	. 220	. 099	.048	.24	.945	.491	. 349	. 171	.04
Z5	10.73 (115.5)	.998	.407	.412	. 168	.088	.34	1.139	.422	.470	. 198	.06
Z16	7.12 (76.65)	.932	. 299	. 255	.076	.035	.11	1.086	. 302	. 297	.09	-
Z17	11.99 (129.08)	.65	.671	. 300	.201	.06	. 12	.760	.741	.35	.26	-
Z18	9.47 (101.98)	. 786	.461	.286	. 132	.05	.14	.923	.476	. 336	.16	-
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Figure 2



Figure 3 Sketch of Configuration 401F-2

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Figure 4 Sketch of Configuration 401F-5

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Figure 5 Sketch of Configuration 401F-10A

WING	$S_{w} \sim m^{2}(ft^{2})$	AR	λ	$\Lambda_{\rm LE}$ ~ Deg	$\Lambda_{\rm TE} \sim {\rm Deg}$
W3	26.01 (280.0)	3.00	.227	40	0
W3BB	26.10 (280.9)	3.05	.220	40	0
W6	26.01 (280.0)	3.00	.30	40	6.9
W24	27.58 (296.9)	3.03	.222	40	0
W25	27.87 (300)	3.00	.227	40	0



Figure 6 Wing Planforms



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Figure 8 Configuration 401F-2 Strakes











Figure 11a Configuration 401F-10A Strakes



Figure 11b Additional Configuration 401F-10A Strakes

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Configuration 401F-16 Strakes

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Figure 13

Configuration 401F-16E Strakes


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Figure 15a Configuration 401F-16 Small Rotating Strakes

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Figure 16 Large YF-16 Rotating Strakes

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Figure 17 YF-16 Nose and Canard Strakes

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YF-16 + 77.5(30.5) Stretch

*267-270 are with 113.0 (44.5) Stretch

Figure 18a Strakes for Stretched YF-16

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YF-16 + 77.5(30.5) Stretch





Figure 19 F-16 Forebody Strakes



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Figure 20a F-16 Nose Strakes



Figure 20b Additional F-16 Nose Strakes



Figure 20c Additional F-16 Nose Strakes

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Figure 22a Lift Effects of a Family of Delta Planform Forebody Strakes on Configuration 785



Figure 22b Drag Effects of a Family of Delta Planform Forebody Strakes on Configuration 785



Figure 23a Lift Effects of a Family of Ogee Planform Forebody Strakes on a Stretched YF-16



Figure 23b Drag Effects of a Family of Ogee Planform Forebody Strakes on a Stretched YF-16



Figure 24

Effects of a Nose Strake on the F-16 Lift

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Figure 25a

Lift Effects of a Nose and Canard Strake on the YF-16



Figure 25b

Drag Effects of a Nose and Canard Strake on the $\rm YF{-}16$

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Figure 26a Lift Effects of a Leading-Edge Flap on Configuration 401F-5 with No Strake



Figure 26b Drag Effects of a Leading-Edge Flap on Configuration 401F-5 with No Strake



Figure 27a Lift Effects of a Leading-Edge Flap on Configuration 401F-5 with a Forebody Strake



Figure 27b Drag Effect of a Leading-Edge Flap on Configuration 401F-5 with a Forebody Strake







Figure 28b Effect of a Forebody Strake on the Envelope Drag Polar



Figure 29 Effects of a Family of Delta Planform Forebody Strakes on the Low-Lift Drag at .80 Mach Number



Figure 30 Effects of a Family of Delta Planform Forebody Strakes on the Low-Lift Drag at 1.20 Mach Number



Figure 31 Lift Effects of a Family of Forebody Strakes on Configuration 401F-10A at .80 Mach Number



Figure 32 Lift Effects of a Family of Forebody Strakes on Configuration 401F-10A at .90 Mach Number



Figure 33a Effects of Forebody-Strake Blending on Lift



Figure 33b Effects of Forebody-Strake Blending on Drag



Figure 34 Calculation Chart for Prediction of Non-Linear Lift of Double-Delta Planforms at Subsonic Speeds.



Figure 35 Evaluation of WINSTAN Lift Prediction Technique







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Figure 37 Evaluation of Modified WINSTAN Lift Prediction Technique

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Figure 39 Definition of Effective Strake Area for a Blended Configuration





Incremental Strake Lift for a Family of Delta Planform Strakes on Configuration 785





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Incremental Strake Lift for a Delta and Gothic Planform Strake on Configuration 401F-5

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Figure 42 Incremental Strake Lift for a Family of Ogee Planform Strakes on Configuration 401F-5



Figure 43

Incremental Strake Lift for a Family of Ogee Planform Strakes on Configuration 401F-10A







Figure 45 Incremental Strake Lift for a Delta and Gothic Planform Strake on Configuration 401F-5 (Based on A_{EFF})



Figure 46

Incremental Strake Lift for a Family of Ogee Planform Strakes on Configuration 401F-5 (Based on A_{EFF})



Figure 47 Incremental Strake Lift for a Family of Ogee Planform Strakes on Configuration 401F-10A (Based on A_{EFF})



Figure 48 Definition of Effective Strake Area for Large Span Strakes



ure 49 Effects of Configuration and Strake Geometry on Incremental Lift





Incremental Strake Lift for a Family of Ogee Planform Strakes on the Stretched YF-16



Figure 51 Incremental Strake Lift for a Family of Ogee Planform Strakes on the Stretched YF-16 (Based on ΔA_{EFF})





Incremental Drag Correlation for Forebody Strakes



Figure 53 Pitch Effects of a Family of Ogee Planform Forebody Strakes on the YF-16 + 30.5 Stretch



Figure 54

Pitch Effects of Forebody Strake Forward Extent on the YF-16 + 30.5 Stretch



Figure 55

Pitch Effects of a Family of Ogee Planform Forebody Strakes on the YF-16 + 44.5 Stretch

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Figure 56

Effect of Horizontal Tail Deflection on the Pitch Effects of Ogee Planform Forebody Strakes, YF-16 + 30.5 Stretch



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Figure 57 Linear Region Stability Shift Due to Forebody Strakes, M = 0.80

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 $\Delta A C 1$

Figure 58 Linear Region Stability Shift Due to Forebody Strakes, M = 1.20



 $\Delta A C 2$

Figure 59 H

High Angle of Attack Stability Shift Due to Forebody Strakes, M = 0.80



Figure 60









Figure 62 Effect of Nose Strake Shape on the F-16 Sideslip Characteristics



Figure 63 Effect of Nose Strake Inclination on the F-16 Sideslip Characteristics



Figure 64 Sideslip Characteristics of a Family of Ogee Planform Forebody Strakes, YF-16 + 30.5 Stretch

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Figure 65 Sideslip Characteristics of a Family of Ogee Planform Forebody Strakes, YF-16 + 44.5 Stretch



Figure 66 Sideslip Characteristics of Nose Strake Z100 on the F-16 at 0.9 Mach Number



Figure 67 Sideslip Characteristics of a Family of Delta Planform Forebody Strakes on Configuration 785, LEF = 0

















Figure 71 Sideslip Characteristics of a Family of Ogee Planform Forebody Strakes on Configuration 401F-5



Figure 72 Sideslip Characteristics of a Family of Ogee Planform Forebody Strakes on Configuration 401F-10A



Figure 73 Sideslip Characteristics of a Family of Ogee Planform Forebody Strakes on Configuration 401F-16

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