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TEMPERATURE AND HUMIDITY PROFILES IN THE ATMOSPHERE FROM SPACE BORNE LASERS

(a feasibility study)

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ABSTLACT

Computer simulations of the differential absorption lidar technique in a space craft for the purpose of temperature and humidity profiling indicate:

- Current technology applied to 02 and H2O lines in the .7 to .8µm wavelength band gives sufficiently high signal-to-noise ratios (up to 50 for a single pulse pair) if backscattering by aerosol particles is high, i.e. profiling accurate to 2 K for temperature and 10 % for humidity should be feasible within the turbid lower troposphere in 1 km layers and with an averaging over approximately 100 pulses.
- 2) The impact of short term fluctuations in aerosol particle concentration is too big for a one laser cystem. Only a two laser system firing at a time lag of about 1 millisecond can surmount these difficulties.
- 3) The finite width of the laser line and the quasi-random shift of this line introduce tolerable, partly systematic errors.

1. INTRODUCTION

The retrieval of temperature and humidity profiles from radiances measured with current space borne passive radiometers mainly suffers from a poor height resolution. Therefore any system increasing the number of independent informations - equivalent to enhanced height resolution - at the same or even slightly reduced accuracy level is highly desirable. The present study simulates the backscattering of laser light by the atmosphere to a space craft flying at 250 or 800 km above the earth surface. The main goals of this study, temperature and humidity profiles, need at least two wavelengths, while the aerosol backscattering profiles in clear atmospheres and above clouds as well as cloud top detection can be determined from a single wavelength lidar.

We report on temperature and humidity profiles from a two wavelength differential absorption lidar (DIAL). Quite a number of parameters, which all influence the backscattering of laser light and the accuracy of its detection have been set to realistic values or varied within realistic ranges in order to assess their impact on the signal-to-noise ratio (SNR):

- tropospheric and stratospheric aerosol particles
- absorber amount (for humidity profiles only)
- laser power (remaining within technologically feasible ranges)
- instability of the laser wavelength
- width of the laser line
- shift of the O2 or H2O line center with atmospheric pressure
- time integration (equivalent to layer thickness desired)
- line shape of the atmospheric absorption line
- space averaging (necessary to increase SNR)

2. BASIC EQUATIONS

1. L. A.

1 2 m 3 m W Construction

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We start with the lidar equation describing the power received at the detector P(r) after backscattering of laser power P_0 by a substance at distanc r.

$$P(r) = P_0 \eta_0 \eta_1 A^* \frac{\tau c}{2} \cdot \frac{1}{r^2} \beta(r) \exp\left(-2 \int_0^{r} e(r') dr'\right)$$
(1)

with P_0 = emitted laser power accounting for losses within the laser optics η_0 = correction for beam overlapping

 η_1 = optical efficiency of the receiving system

- A = effective receiver area
- τ = pulse length
- c = velocity of light

B(r) = backscattering coefficient at distance r

e(r) = extinction coefficient at distance r' = r

Discretization of the integral in (1) into m finite layers with thickness Δr and and formulation for two wavelengths λ_1 and λ_2 leads to the ratio of signals

$$\frac{P(r,\lambda_1)}{P(r,\lambda_2)} = \frac{\beta(r,\lambda_1)}{\beta(r,\lambda_2)}, \frac{\prod_{l=1}^{m=r/\Delta r} \exp(-2e(r,\lambda_1)\Delta r)}{\prod_{l=1}^{m} \exp(-2e(r,\lambda_2)\Delta r)}$$
(2)

where $r' = r - \Delta r/2$ has been introduced. Writing (2) in terms of the layer i-1 leads to a recursion formula, which - after the neglection of the wavelength dependence of β (certainly valid for $\Delta \lambda \leq .2nm$) - is reduced to

$$\frac{P(\tau,\lambda_1)}{P(\tau,\lambda_2)} = \frac{P(\tau-\Delta r,\lambda_1)}{P(\tau-\Delta r,\lambda_2)} \cdot \frac{\exp\left(-2k(\tau',\lambda_1)\Delta r\right)}{\exp\left(-2k(\tau',\lambda_2)\Delta r\right)}$$

Resolved for the differential absorption coefficient $\Delta k(r) = k(r, \lambda_1) - k(r, \lambda_2)$ we get

$$\Delta k(r') = -\frac{1}{2\Delta r} \cdot \ln \left(\frac{P(r,\lambda_1) \cdot P(r-\Delta r,\lambda_2)}{P(r,\lambda_2) \cdot P(r-\Delta r,\lambda_1)} \right)$$
(3)

If one laser wavelength, λ_2 , is in a window between absorption lines, the differential absorption coefficient $\Delta k(r) = k(r, \lambda_1)$. Now adopting the Lorentz line shape the absorption coefficient at wavenumber ν reads

$$k_{y}(r') = \frac{5(r')}{\pi} \cdot \frac{\alpha(r')}{(v - (v_{0} - r(r'))) + \alpha(r')^{2}}$$
(4)

where S = line intensity depending on temperature T

 $v_{\rm O}$ = central wavenumber at standard conditions

- α = line halfwidth depending on T and pressure p
- Y = line shift depending on T and p

we introduce one of the desired parameters: temperature T. Accounting for the temperature and pressure dependence of S and

$$5(\tau') = 5_{o} n(\tau') \left(\frac{T_{o}}{T(\tau')}\right)^{d} exp\left(-\frac{E_{o}}{k_{o}}\left(\frac{1}{T(\tau')} - \frac{1}{T_{o}}\right)\right)$$

$$\alpha(\tau') = \alpha_{o} \cdot \frac{p(\tau')}{P_{o}} \cdot \left(\frac{T_{o}}{T(\tau')}\right)^{1/2}$$
(5)

we have to handle some more parameters,

 $S_{0} = \text{line strength at reference temperature } T_{0} \\ E_{0} = \text{energy of the lower state} \\ k_{0} = \text{Boltzmanns constant} \\ d = \text{molecular constant depending on degrees of freedom for rotation} \\ (\delta = 1 \text{ for linear molecules, } \delta = 1.5 \text{ for } H_{2}O) \\ \alpha_{0} = \text{halfwidth at } T_{0}, N_{0}$

 $p_0 = 1$ atm pressure

but we also find the second desired parameter: the number density n(r) of the molecule having a line at v_0 . Insertion of (4) for $v = v_0$ and of (5) into (3) gives the basic equation for temperature determination as long as n/p is known.

$$k_{v} = \frac{S_{o} \rho_{o}}{1.132 \pi \alpha_{o}} \cdot \frac{n}{P} \left(\frac{\overline{T_{o}}}{T}\right)^{d-\frac{\eta_{2}}{2}} \exp\left(-\frac{E_{o}}{k_{o}} \left(\frac{1}{T} - \frac{1}{T_{o}}\right)\right)$$
(6)

For given T and p this expression can be reformulated to allow for instance water vapor determination.

$$n_{H_2O} = \frac{k_v 1.132 \pi \alpha_o \rho}{S_o \rho_o} \cdot \left(\frac{T}{T_o}\right) \exp\left(-\frac{E_o}{k_o} \left(\frac{1}{T} - \frac{1}{T_o}\right)\right)$$
(7)

A more thorough treatment of the DIAL technique should account for the Doppler and Voigt line shape too. However, since the subsequent error equations are also valid for the Doppler line shape and deviations from the Lorentz line shape in the troposphere are well within the errors of laser line shape knowledge, we omit in accordance with a statement by Megie et al (1983) a thorough treatment of Voigt line profiles.

3. ERROR ASSESSMENT

We define the error of a function $f(x_i; i=1, ..., m)$ by

$$\Delta f(\mathbf{x}_{i}, i=1,...,m) = \sum_{i=1}^{m} \left| \frac{\partial f_i}{\partial \mathbf{x}_i} \right| \Delta \mathbf{x}_i$$
(8)

which resolved for Δx_i reads

$$\Delta x_{j} = \left(\Delta f - \sum_{i=1}^{m} \left| \frac{\partial f_{i}}{\partial x_{i}} | \Delta x_{i} \right) \right/ \left| \frac{\partial f_{i}}{\partial x_{j}} \right|$$
(9)

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Applying (9) to (3) we get for the absorption coefficient

$$\Delta k(r') = \frac{1}{2(\Delta r)^2} \ln \left(\frac{P(r,\lambda_1) P(r-\Delta r,\lambda_2)}{P(r,\lambda_2) P(r-\Delta r,\lambda_3)} \right) \Delta r + 2 \left| \frac{1}{2\Delta r} \frac{1}{P(r',\lambda_3)} \right| \Delta P(r',\lambda_3)$$

$$+ 2 \left| \frac{1}{2\Delta r} + \frac{1}{P(r',\lambda_2)} \right| \Delta P(r,\lambda_2)$$

$$\simeq \frac{1}{\Delta r + SNR_1} + \frac{1}{\Delta r + SNR_2}$$
(10)

The approximation uses $P/\Delta P = SNR$ and neglects the first term in (10), which is of the order of 10^{-6} to 10^{-8} for an error of 10 m in the determination of $\Delta r = 1$ km and for an optical depth $t^* = k(r) \Delta r$ between 10^{-3} and 10^{-1} , while the second and the third vary from 10^{-1} to 10^{-3} for SNR between 1 and 100. Calculating $\Delta T/T$ according to (9) using (6) yields

$$\frac{\Delta T}{T} = \frac{1}{\left|\frac{E_{o}}{k_{o}} - \frac{1}{T} - \frac{1}{2} + \delta\right|} \left(\frac{\Delta P}{P} + \frac{\Delta n}{n} + \frac{1}{k_{v}} \cdot \left(\frac{1}{\Delta r SNR_{T}} + \frac{1}{\Delta r SNR_{z}}\right)\right) \quad (11)$$

The application of (9) to (7) finally gives the relative error $n_{\rm H2O}/n_{\rm H2O}$ for water vapor profiling.

$$\frac{\Delta n}{n} = \frac{\Delta P}{P} + \left| \frac{E_o}{k_o} - \frac{1}{T} + \frac{1}{2} - \delta \right| \frac{\Delta T}{T} + \frac{2}{\Delta r k_v SNR}$$
(12)

4. THE SIGNAL-TO-NOISE RATIO

The error equations (10) - (12) mainly depend on SNR at the detector. The most important noise sources for this study (fixed to the .75 μ m wavelength region) are:

- 1) shot noise caused by statistical fluctuations of photons constituting the signal current
- 2) background noise due to backscattered or reflected sun light

All other noise sources have been shown to be negligible (Endemann, 1983). For the above noise sources Megie and Menzies (1980) propose

$$5NR = \frac{N_{k}}{(N_{k} + N_{B})^{\frac{1}{2}}}$$
(13)

with the number of backscattered photons received per unit time from layer k

$$N_{k} = \frac{P_{k}}{hf} \eta^{*} \frac{2\Delta r}{c}$$
(14)

and the number of background photons per unit time

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$$N_{\rm B} = \frac{I_{\rm B}}{hf} \frac{A^* \Omega^2 \pi B}{hf} \eta_1^* \eta_2^* \frac{2\Delta r}{c}$$
(15)

- P_k = signal power from layer k after passage through the front filter in front of the detector
- η_1^- = filter transmission
- η_1^* = quantum efficiency of the detector
- $f = frequency (f = c/\lambda)$
- I_B = background radiance
- \mathcal{A} = field of view of the receiver optics
- B = filter bandwidth
- h = Planck's constant

5. RESULTS

5.1 Impact of Variations in Aerosol Particle Concentration

Before we discuss the signal-to-noise ratio of the proposed system the errors due to random fluctuations of aerosol particle concentration in both the horizontal and vertical direction between two pulses of a multi-wavelength lidar are presented. Table 1 clearly demonstrates, that there is no way to get accurate profiles with only one laser shifting wavelength within 0.1 second. If particle concentration varies by only 0.1 percent - still unrealistically low - between two pulses, the relative error calculated from 100 trials with a random number generator reaches at the maximum 0.7, 0.4, and 2.1 percent for temperature T, pressure p and number density $n_{\rm H2O}$ in the troposphere

Table 1: Maximum error in percent caused by variations in aerosol particle concentration between two pulses.

Variation	∆T/T	∆p/p	$\Delta n/n (H_2O)$	level
1 %	20.0	8.0	37.0	troposphere
0.1%	1.6 0.7	2.3 0.4	11.0 2.1	stratosphere troposphere

5.2 Signal-to-Noise Ratio (SNR)

This section sticks to a two laser system, as shown to be necessary within the previous section. The separation of pulses has to be below a millisecond in order to neglect particle concentration changes. The SNR calculations include the major noise sources: shot noise and background noise of the sunlit atmosphere as expressed in (13) - (15). Other noise sources have been handled by Endemann (1983) and shown to be negligible for the proposed system whose performance will be tested under laboratory contitions.

SNR depends on such a variety of parameters that part of them has been fixed in order to assess the influence of some specifically. In accordance with the envisaged hardware development we have set: $\eta_{,}^{*}=0.45$, $\eta_{,}^{*}=0.18$ (Endemann, 1983a), $A^{*}=0.25 \text{ m}^{2}, \Omega=0.5 \text{ mrad}, B=1 \text{ nm}, \Delta r=1 \text{ km}$; IB varies from 0 (night) to 5 (standard illumination) and 200 W m⁻² sr⁻¹ m⁻¹ (strong sin glint or thick clouds). The central wavenumber $\nu = 12975 \text{ cm}^{-1}$, $P_{0} = 25 \text{ MW}$, and the height of the space craft varies from 250 to 800 km. The line parameters used are summarized in table 2. The first atmosphere adopted is a standard atmosphere for 60°N, July,

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with 23 km horizontal visibility at the ground and an aerosol scale height of 1.25 km. The SNR values displayed in figures 1 and 2 for 250 and 800 km clearly demonstrate:

SNR±10 for a single shot is only achievable within the troposphere. SNR for the on-line shot is drastically reduced for the stronger O₂ line. However, this does not mean enhanced temperature error, because the concomittant increase in optical depth $\tau^* = \Delta r \cdot k(r^*)$ more than compensates this reduction. An additional constraint is: measurements must be taken outside sun glint areas. Within these first figures we did not tune aerosol backscattering in order to reach higher SNR.

Table 2: Lines and windows chosen								
wavelength λ	wavenumber ⁺ y	absorber and use	line strength S _O	+ halfwidth ∝₀	lower state energy E _O			
мт	cm-1		cm	cm ⁻¹	cm-1			
0.7707129 0.7711989 0.7698983 0.7866600 0.7867201	12975.000 12966.823 12988.728 12711.972 12711.000	window; T O ₂ ; T O ₂ ; T H ₂ O; n window; n	0.734 10-26 0.431 10-25 0.362 10-24	0.042 0.042 0.0655	1803.18 1422.502 704.214			

⁺at 296 K and 1013.25 hPa

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Figure 1: Vertical profiles of backscattered power (----) and SNR for a standard atmosphere at 60°N, July, with 23 km horizontal visibility, aerosol scale height 1.25 km, space craft at 250 km. The thicker curves stand for the weak 0₂ line, thinner ones for the stronger line. Fulse energy for all the simulations is kept at 0.5 J.

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ORIGINAL PAGE IS OF POOR QUALITY 2 night 104 8 6 Height [m] 2 10³ 8 6 sun guni 4 10 12 16 8 14 18 20 6 SNR 10-15 10-14 10-13 10-12 10⁻¹¹ 10-10 Power [W]

Figure 2: As fig.1, however space craft at 800 km

Since figures 1 and 2 show SNR for one pulse pair, an averaging over 100 pulse pairs, which will be tolerable from the point of view of horizontal resolution, gives SNR > 100 in large parts of the troposphere for a space craft at 250 km. Using a standard aerosol model (Lenoble and Brogniez, 1983) for continental areas in the troposphere and a young (1 month) stratospheric aerosol layer of volcanic origin SNR is enhanced compared to the atmospheric model in figures 1 and 2, now surmounting the value 10 even for a space craft at 800 km under night conditions. All the other aerosol models proposed, which were input to our programme but are not shown, do not give strongly different results. They all point to the drastic dependence on aerosol particle concentration. Rayleigh scattering can not give high enough SNR.

5.3 Relative Temperature and Humidity Error

The error equations (11) and (12) were explored under a variety of situations. However, the only figure displayed already contains the main result. The temperature error $\Delta T/T$ in the lowest troposphere (figure 4) for $\Delta r=2$ km is below 2 K only for SNR₂ (window wavelength) ≥ 200 and rather low total optical depth τ^* of the line. For water vapor profiling very similar results exist. However, the relative error $\Delta n/n$ at SNR₂ ≥ 200 is only below 0.1 at a E₀ = 900 cm⁻¹. The dependence on τ^* is unchanged.



Figure 3: Vertical profiles of backscattered power (----) and SNR for a standard atmosphere at 60°N, July, with continental aerosol in the troposphere and volcanic aerosol in the stratosphere, one month after eruption. Thick lines for a space craft at 250 km, thin lines for a space craft at 800 km.

6. ERRORS CAUSED BY THE FINITE WIDTH OF THE LASER LINE

Most simulations hitherto reported neglect the laser line width. According to Browell et al (1983) present lasers have a line width of 3 pm, corresponding to 0.05 cm^{-1} at $0.7 \,\mu$ m. Korb and Weng (1982) assume 0.02 cm^{-1} . Thus the laser line width is comparable to the halfwidth of the 0_2 and H₂O lines chosen. Since the above simulations assume the laser line to be monochromatic and to meet the absorption line center we have to assess the errors thus introduced. The optimal approach would be: revised analytic solutions. Here we adopt an inferior approach. We average transmissions due to gaseous absorption within one layer spectrally, symmetric to the line center. The differential absorption coefficients thus obtained are handled as before with the monochromatic approach. The result is a systematic error. Assuming a rectangular laser line of width 0.05 cm^{-1} the relative temperature error varies from +1.1 percent in the upper tmosphere to -.53 percent in the lower troposphere. Assuming a triangular distribution, where the laser line intensity has dropped to 1/8 at 0.025 cm^{-1} distance from the center, $\Delta T/T$ lies between -0.01 and +0.12 percent. The relative humidity error $\Delta n/n$ then varies between +2.c and -0.95 percent.

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Figure 4: Relative temperature error $\Delta T/T$ as a function of the signal-to-noise ratio for the window position, SNR₂, for different total optical depth τ^* as indicated.

7. FLUCTUATIONS OF LASER FREQUENCY

The instability of the laser frequency also causes errors, which in this case will not be systematic. After Browell et al (1983) contemporary lasers show fluctuations of \pm 0.3 pm, approximately a tenth of the halfwidth of the absorption lines. We simulated these fluctuations by shifting the laser line in two different ways: 1) random shift with equal probability for all deviations within \pm 0.3 pm; 2) random shift with a Gaussian distribution and a standard deviation 6= 0.3 pm

and accounting for a finite triangular laser line width of 3 pm (10% level). $\Delta T/T$ varies from nearly o percent to 0.1 percent for both cases depending on height level. The values $\Delta n/n$ reach 1.5 percent. This, however has to be compared to the $\Delta n/n$ from (12) and thus is not intolerably high. All numbers reported are valid for the troposphere only and after an averaging over 100 realisations.

8. INFLUENCE OF A POSSIBLE ABSORPTION LINE SHIFT WITH PRESSURE

The absorption lines of atmospheric gases are not fixed to a distinct wavelength. Their shift is negligibly small for many applications. The shift $f = \frac{1}{2} \frac{1}{$

9. CONCLUSIONS

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The major result of this study is:

Tropospheric temperature and humidity profiles in 1 to 2 km layers may be determined by a space borne DIAL using present technology to an accuracy of better than 2 K or 10 percent respectively under the following conditions:

1) Two laser system firing with a time lag below 1 millisecond.

- 2) Averaging over at least 100 pulses for a space craft at 250 km height.
- 3) Averaging over some hundred pulses for a space craft at 800 km.
- 4) Highest accuracy is found for both temperature and humidity with O₂ and H₂O lines respectively at total optical depth at the line center within the 0.1 to 0.5 range.
- 5) The optical depth of the pure Fayleigh scattering atmosphere in window areas has to be strongly enlarged by aerosol particles, i.e. only turbid atmospheres give reliable results.

Major gaps found:

- 1) The impact of laser line width and laser line position fluctuations or accuracy has to be investigated in more detail.
- 2) The poor knowledge of absorption line shift with atmospheric pressure hampers an assessment of its importance for DIAL from space.

10. ACKNOWLEDGEMENT

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