

PORTABLE FIBER OPTIC COUPLED DOPPLER INTERFEROMETER  
SYSTEM FOR DETONATION AND SHOCK WAVE DIAGNOSTICS

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ABSTRACT

Testing and analysis of shock wave characteristics such as detonators and ground shock propagation frequently require a method of measuring velocity and displacement of the surface of interest. One method of measurement is doppler interferometry. The VISAR (Velocity Interferometer System for Any Reflector) uses doppler interferometry and has gained wide acceptance as the preferred tool for shock measurement. An important asset of VISAR is that it measures velocity and displacement nonintrusively.

The conventional VISAR is not well suited for portability because of its sensitive components, large power and cooling requirements, and hazardous laser beam. A new VISAR using the latest technology in solid state lasers and detectors has been developed and tested. To further enhance this system's versatility, the unit is fiber optic coupled which allows remote testing, allowing the VISAR to be over a kilometer away from the target being measured. Since the laser light is contained in the fiber optic, operation of the system around personnel is far less hazardous. A software package for data reduction has been developed for use with a personal computer. These new advances have produced a very versatile system with full portability which can be totally powered by batteries or a small generator.

This paper describes the solid state VISAR and its peripheral components, fiber optic coupling methods and the fiber optic

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coupled sensors used for sending and receiving laser radiation.

### VISAR OPERATION AND DESCRIPTION

The conventional VISAR consists of a single mode, single frequency laser (typically argon ion), interferometer cavity, peripheral optics, modulator, photomultiplier tubes (pmt's), amplifiers, digitizer(s) and computer (figure 1). In a typical VISAR setup in the "push-pull" configuration using the "fixed cavity", the laser beam is routed through a focusing lens placed in front of the surface that is to be measured (the surface is diffusely reflective). The lens focuses the light on the surface and the scattered return light is routed back to the interferometer cavity (figure 2). The interferometer is a modified Michaelson cavity. The return beam is split and routed through the cavity in which one beam goes through air (reference leg) and the other beam travels through glass (delay leg) and an eighth wave retarder with a mirrored coating on the rear surface. The two combined beams are split and sent to polarizing beamsplitting cubes (PBC). The beams interfere with each other producing either a bright or dark spot (constructive or destructive interference) that are converted to electrical signals by photomultiplier tubes (pmt). The polarizing beamsplitting cubes separate and linearly polarize the light containing the doppler information into their "S" and "P" components (figure 3). The S and P light possess the same doppler information but since the light passes through the 1/8 wave retarder twice, the phase is retarded by 90 degrees. The light (P component) that passes through the PBC is called DATA 2 and DATA 2' and light that is reflected (S component) is DATA 1 and DATA 1'. The two pairs of interfered light have identical phase-time information except that they are out of phase with each other by 180 degrees. DATA 1 is electronically inverted and added to DATA 1' as is DATA 2 and DATA 2'. The advantage of this method of inverting and adding the signals is that it cancels out self light and the signal amplitude is doubled. The stored data is then manipulated and converted to displacement and velocity using custom software (figure 4).

When the target is at rest, the wavelength in both legs of the interferometer cavity is equal and no change in the interference fringes pattern is observed (figure 5). The instant the target starts moving, a doppler shift of the light occurs (the optical equivalent of the changing pitch of a car engine as it passes by). Since the light in the glass portion of the interferometer cavity is delayed before it is recombined with the reference light, the interference fringe pattern moves. The velocity of the target correlates to the amount of fringes recorded and the amount of delay the interferometer induces to the light. Velocity per fringe (VPF) is related by the equation:

$$VPF = \lambda / 2\tau (1 + \Delta \frac{v}{\Delta})^{1/1+\gamma}$$

where:  $\lambda$  = laser wavelength

$\tau$  = delay time of the interferometer

$\Delta v/v$  = correction for window materials

$\gamma$  = correction factor for refractive index vs wavelength

The fringe change (phase-time change) is captured by the optical detectors (pmt's) and the amount of fringe movement is correlated to the amount of delay in one leg of the interferometer cavity. The VISAR cavity can be configured with varying amounts of delay for the anticipated velocity range or multiple systems may be used to cover a wider range of velocities. The normal range of velocities VISAR normally covers is 100-8000 meters-per-second.

### SOLID STATE VISAR

VISAR has been limited to the laboratory because of its large size, sensitivity to transportation, large electrical & heating requirements and setup complexity. Recently, a new VISAR (Fixed Cavity VISAR) has been developed which uses an interferometer cavity that is permanently cemented together (figure 3). Although this improvement reduces the size and complexity of the system and simplifies operation, the large size, power and cooling requirements restricts portability of the system. Also, fiber optic coupling is limited to short runs because of the high attenuation and low bandwidth for short (514nm) wavelengths that the argon-ion laser produces.

Two types of solid state VISARs have been successfully designed, built and tested. The design differences revolve around the laser and detectors. These systems use low power consumption and the components are rugged enough to be used in the field. The attenuation and bandwidth are substantially lower than visible lasers allowing long fiber optic runs with minimal losses.

## DIODE LASER BASED VISAR

Single mode-single frequency diode lasers with a power output of 120 milliWatts operating at 830 nanometers wavelength are used for this system. The output beam is collimated using either GRIN lenses or aspherical lenses. The optical isolation of the laser to prevent mode hopping and damage to the laser is accomplished by installing an optical isolator. The Faraday effect is used to rotate the polarization of the laser light 45 degrees. Two polarizers are installed on either side of the Faraday rotator which cancels out any reflected light trying to re-enter the laser cavity. The transmitted light is then focused into a fiber optic and the light is routed to the experiment via an optical probe (figure 6). The light is focused on the target and the reflected light is picked up by a second fiber and transmitted to the interferometer cavity.

The detectors used to convert optical power to electrical power are solid state Schottky silicon photodetectors. Silicon based detectors are preferred because their sensitivity is peaked for the wavelength of the laser. Various alignments and beam manipulation is difficult with an invisible beam. A simple solution is using a fiber optic splitter in reverse. A visible diode laser (680 nm wavelength) is injected into the fiber optic and routed through the optics at the target area. Since the visible laser is routed through the same fiber optic as the VISAR laser and the wavelength is not appreciably different and the insertion loss is only .5 decibels (db) per laser. This system enables the user to do the alignment without the use of infra-red imaging devices.

## DIODE PUMPED Nd:YLF LASER BASED VISAR

Although diode laser light has a fairly low loss in fiber optics, there are situations where minimal attenuation and maximum bandwidth are critical. Dispersion is a major concern in maximizing bandwidth. There is a point where dispersion approaches zero at a particular wavelength when light is propagating in a typical silica fiber optic (figure 7). A diode pumped Nd:YLF laser with an output wavelength of 1319 nanometers and output power of 160 milliWatts is used in conjunction with InGaAs based detectors. This VISAR is capable of operation with kilometer length fiber optics.

## DESIGN CONSIDERATIONS

Although these two types of lasers are quite different in their lasing mechanisms, they share many of the same traits that must be considered when designing a solid state VISAR.

## OPTICAL FEEDBACK

Optical isolation of the laser from any backreflected light is essential for proper mode structure and longevity of the laser. A diode laser operating in the single frequency-single longitudinal mode is especially sensitive to optical feedback and will hop modes or operate in a multimode structure with as little as .05% backreflected light returning to the cavity (Dakin & Culshaw(figure 8)). A greater than 38 db isolation using a TIGG crystal Faraday rotator is usually enough for most applications. Minimization of fiber optic connectors will also reduce the feedback due to Fresnel reflections at each connector surface. Wherever possible, connectors using index matching fluid should be used to virtually eliminate Fresnel backreflections.

Nd:YLF lasers are 30-100 times less sensitive to optical feedback than diode lasers. Also, the longer operating wavelength allows the use of BIG (bismuth iron garnet) deposited film isolators. Termed "aspirin tablet" isolators, they are well suited for compact design when size is important.

## LIGHT INJECTION INTO FIBER OPTICS

Injecting light from a laser diode into fiber optics is more difficult than most lasers emitting a collimated beam because of the large beam divergence that is not uniform. Care must be taken to keep planar surfaces that are normal to the laser out of the optical design so optical feedback is reduced. Since the beam's divergence is too large for direct transmission through the optical isolator, it must be collimated first, meaning that there is no isolator protecting the laser from the fresnel reflections off of the lens. Two types of collimating lenses have been used successfully with the diode laser. A GRIN (GRADIENT INDEX) lens with a convex front surface and an angle polished rear surface both with anti-reflective coatings is an economical, compact method of collimating the light through the isolator. Recently, Corning Glass has been able to manufacture diffraction limited aspheric lenses that are also suitable for optimum collimation while minimizing aberrations.

These methods of collimation are not necessary for the Nd:YLF laser since the light is collimated well enough for transmission through the isolator. Selecting optics for injection of light into fiber optics is dependant on the diameter of the fiber optic core and its Numerical Aperture (NA). The ideal optical design for light injection is a diffraction limited lens with a focal length as short as possible with the working NA of the lens less than the NA of the fiber. (NA is the sine of the half angle of the cone of light exiting a lens. NA of a fiber optic is the sine of the maximum half angle that light is coupled and guided in a fiber and also the half angle of the exiting light.)

## FIBER OPTIC SELECTION

Careful selection of fiber optics is essential for proper bandwidth and efficiency of the system. Multimode fiber optics are preferred because single mode fiber optics are difficult to inject light into, are sensitive to bending and exhibit nonlinearities such as Stimulated Brillouin Scattering and wavelength broadening. Normally light is sent to the target in a 50 um fiber optic and collected with the largest fiber that still has adequate bandwidth for the test. The small diameter of the sending fiber has a smaller exit aperture and is easier to image a small spot on the target. Conversely, the smaller spot is more efficiently imaged into the return fiber and thus signal strength is larger. Visible wavelength laser beams not only exhibit large attenuations in fibers but the bandwidth is also lower due to more coupled modes and higher dispersion. Although the diode laser has low attenuation and dispersion in fiber optics compared to the argon-ion laser, The Nd:YLF laser operating at 1319 nm wavelength has much lower attenuation than the diode laser and has the lowest dispersion of any laser operating outside the 1300 nm wavelength. This is due to several modes of dispersion cancelling out each other.

## DETECTORS

For most uses, PIN, Schottky and APD are the three most common types of high speed solid state photodetectors. APD (avalanche photodiode) has an internal gain when biased near its threshold. Its disadvantages are that it must have a very well regulated high voltage power supply and they also have fairly long transit times for the hole carriers. PIN diodes have fairly high parasitic resistance which reduces the operating bandwidth. Schottky diodes are the preferred choice because they have low parasitic resistance allowing a high bandwidth while retaining a larger active area than APD or PIN photodiodes. Large active areas are essential for ease of alignment since the light must be focused completely into the active area of the detector (some high speed detectors have active areas of only 100um in diameter).

## SUMMARY

The visible laser/photomultiplier tube VISAR with the open beam to the target is the simplest, most light efficient system and is preferred for laboratory conditions where only short, if any, distances of fiber optic transmission is required. If the user needs remote testing capabilities, low power requirements, portability, or foresees any condition where long lengths (>200

meters) of fiber optic cable is needed, the solid state fiber coupled VISAR may be the right system.

## DEFINITION OF TERMS

- **VISAR - VELOCITY INTERFEROMETER SYSTEM FOR ANY REFLECTING SURFACE**
- **MONOCHROMATIC LIGHT - LIGHT COMPOSED OF A VERY NARROW BAND OF WAVELENGTHS**
- **DOPPLER SHIFT - THE CHANGE IN FREQUENCY OF LIGHT REFLECTED FROM A MOVING OBJECT**
- **INTERFERENCE PATTERN - THE RESULTING LIGHT LEVEL WHEN TWO OR MORE WAVELENGTHS ARE COMBINED**



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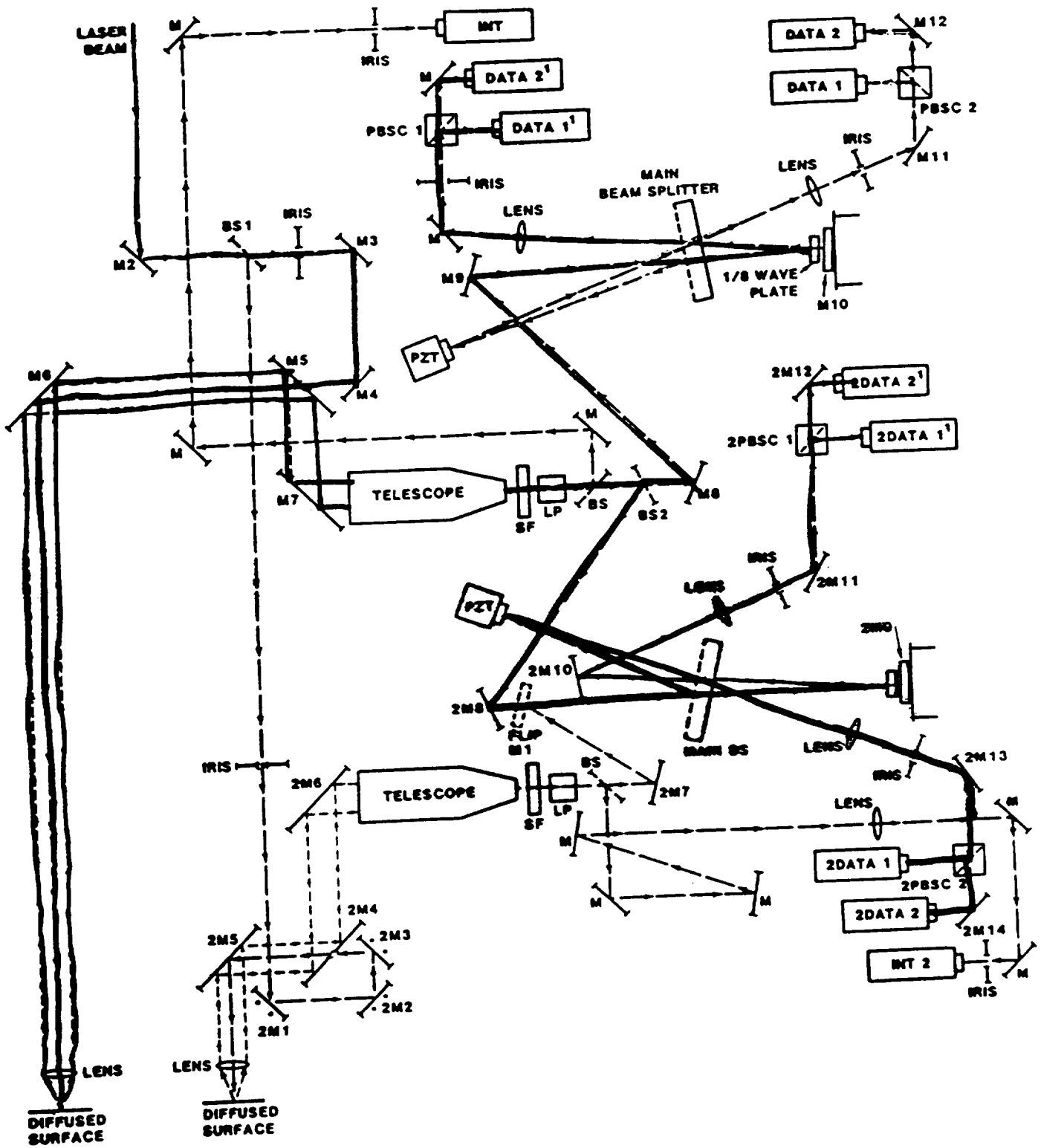


Figure 1

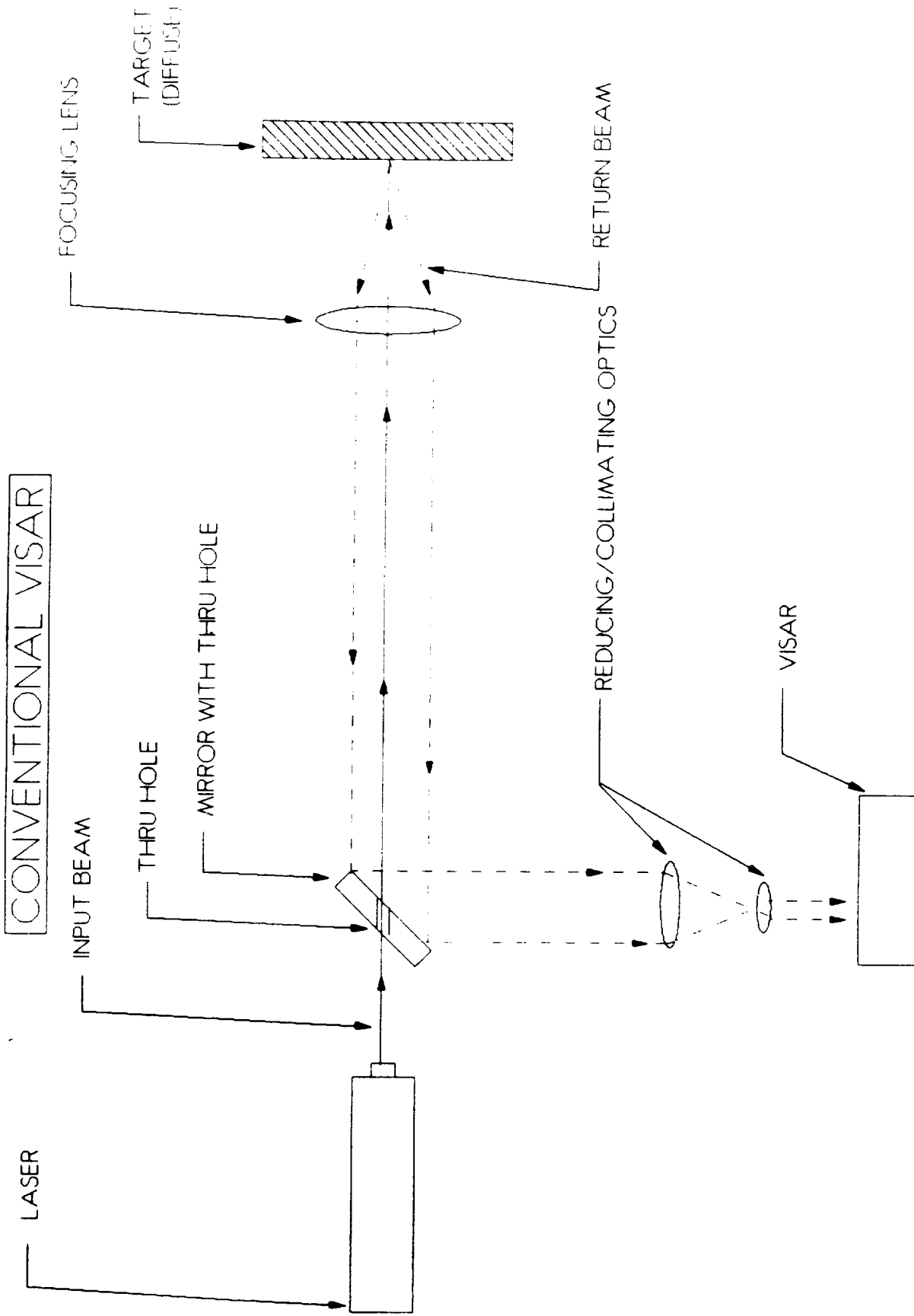
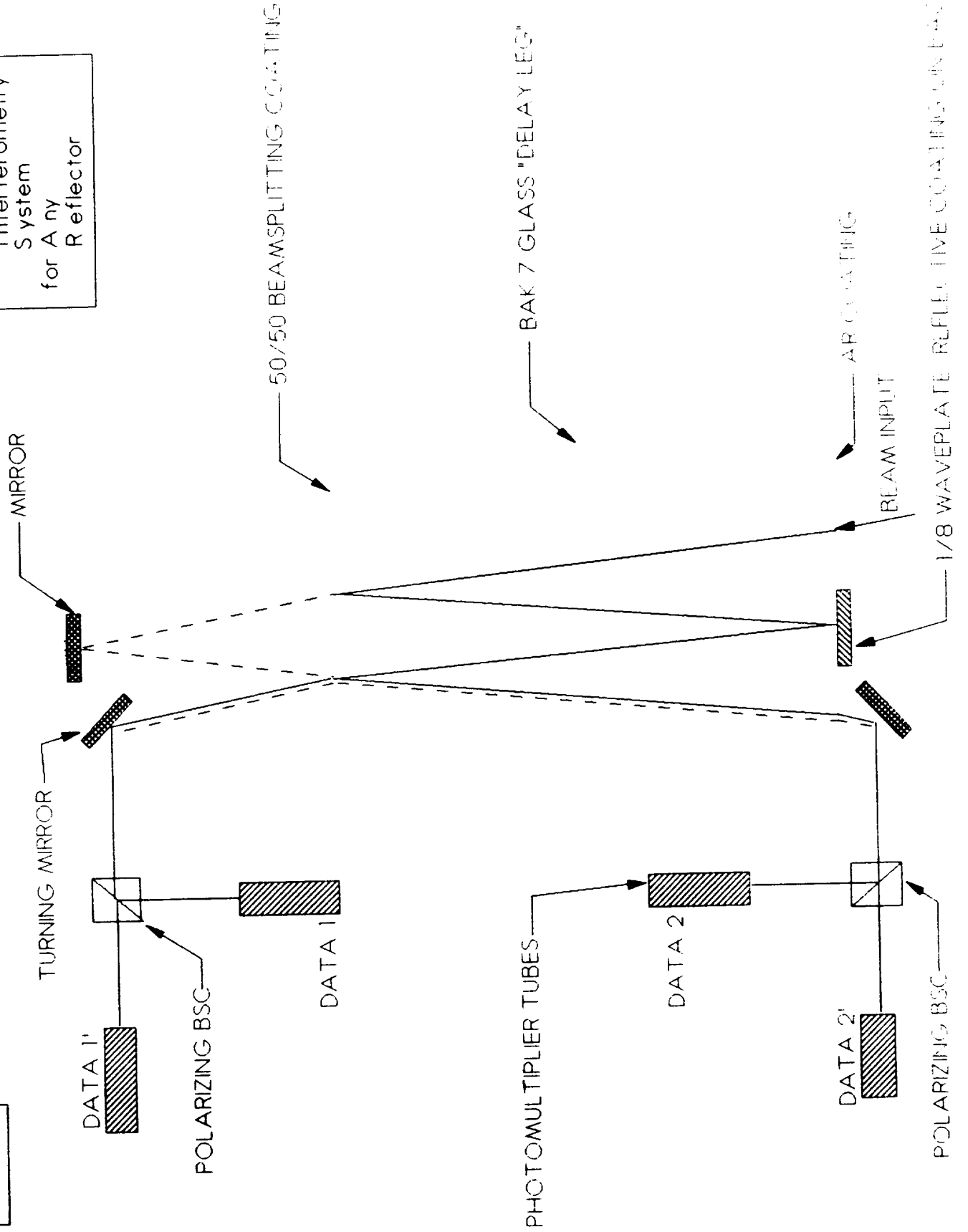
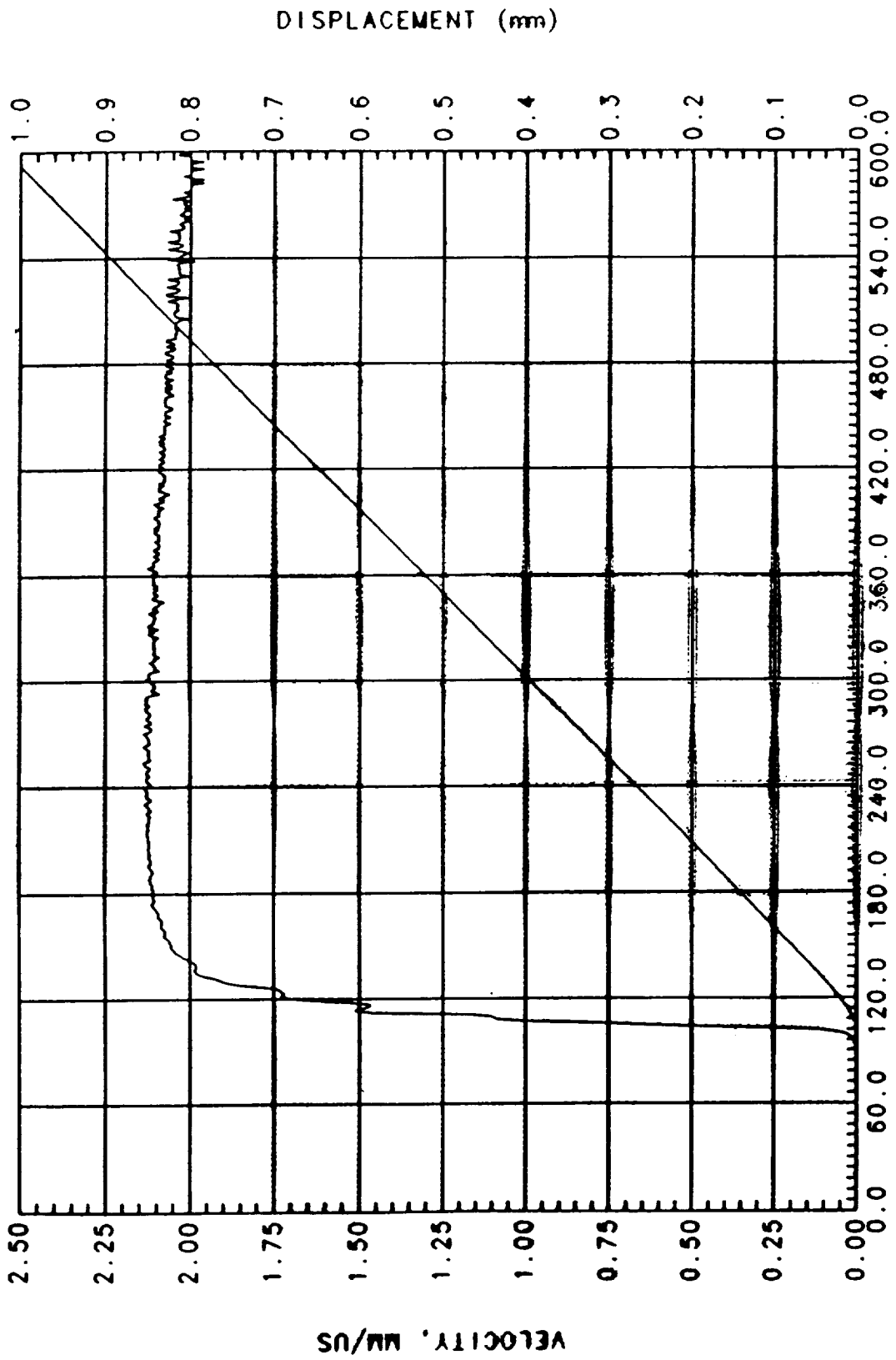


figure 2

Velocity Interferometry System for Any Reflector

FIGURE 3





dot:DOIFP.V05

16-MAR-92

10:08:59

Figure 4

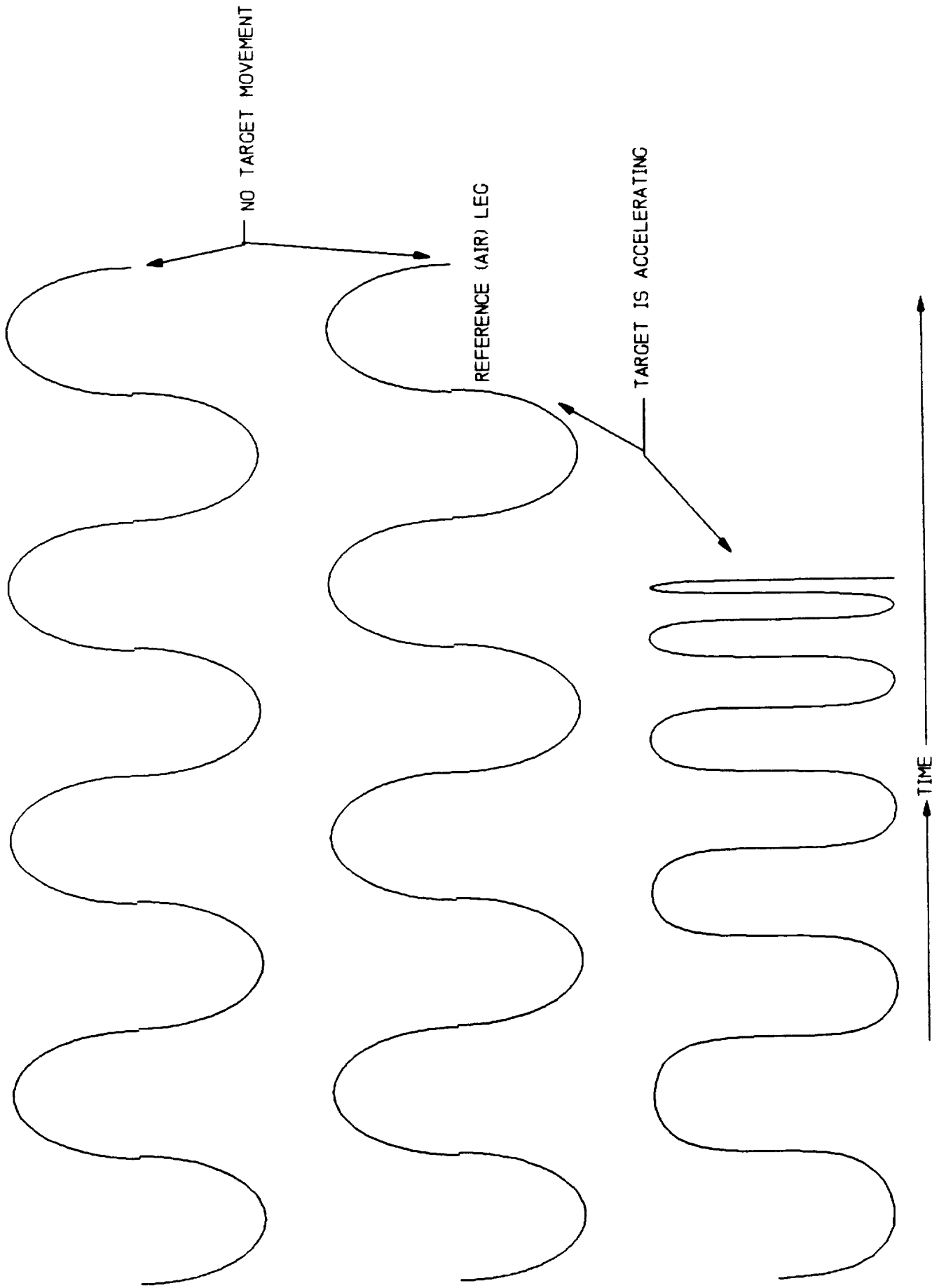


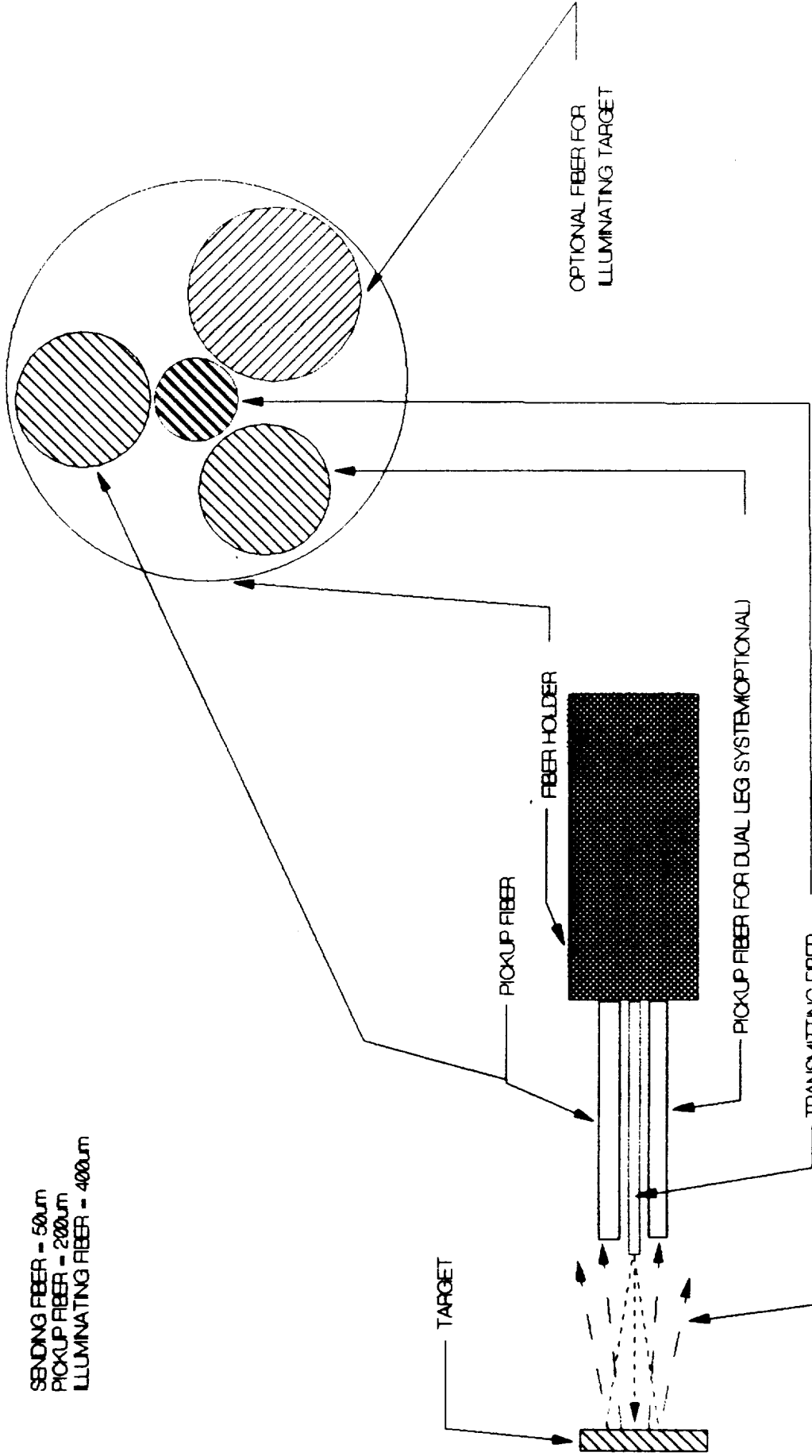
Figure 5

# MULTI-FIBER PROBE

TYPICAL VALUES FOR FIBER CORE

- SENDING FIBER - 50µm
- PICKUP FIBER - 200µm
- ILLUMINATING FIBER - 400µm

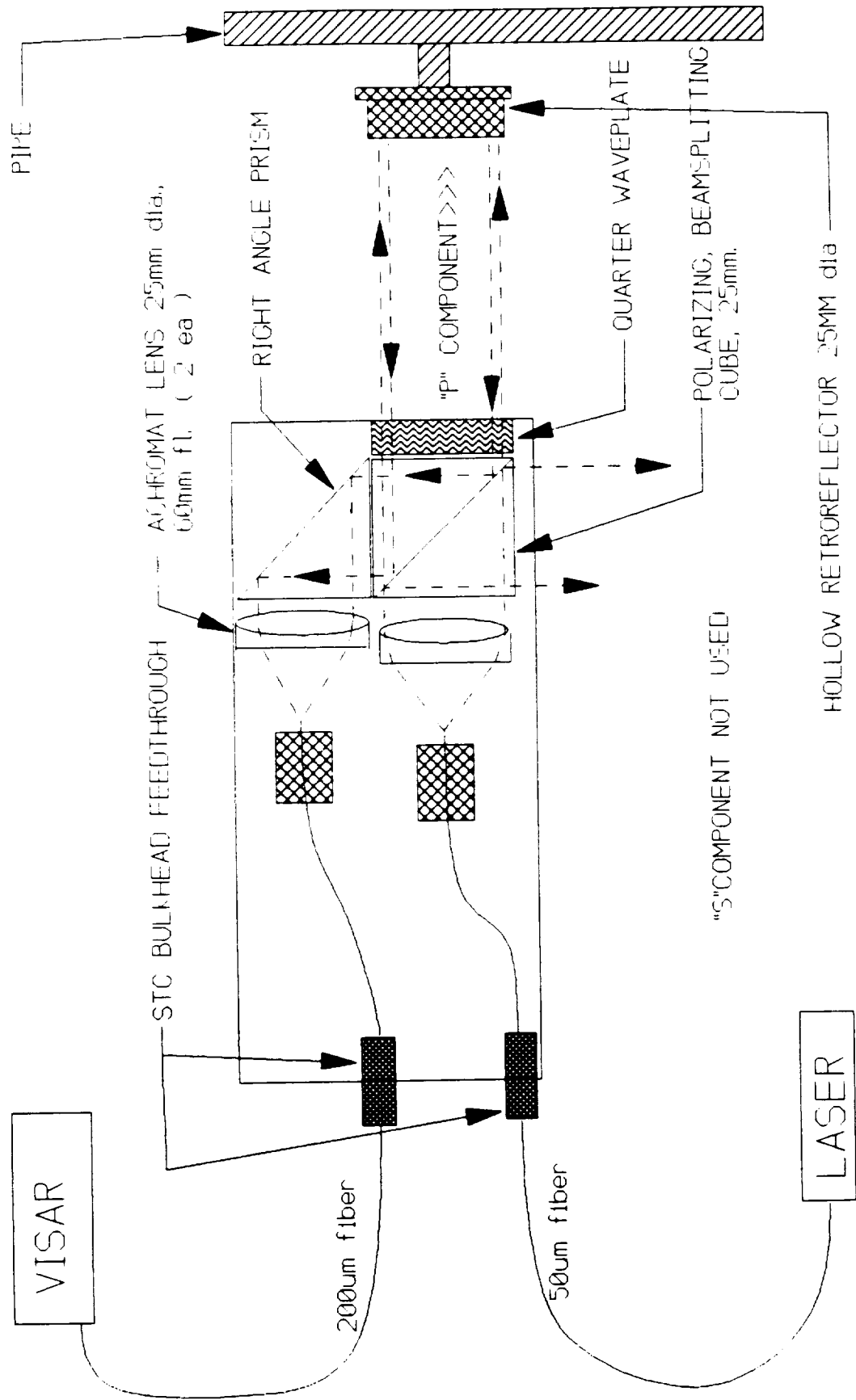
END-ON VIEW OF FIBER ASSEMBLY (ENLARGED)



270  
C-4

Figure 6

# HUNTER'S TROPHY EXTENDED RANGE PROBE



IFHTP

Figure 6a

# ATTENUATION IN FIBER OPTICS

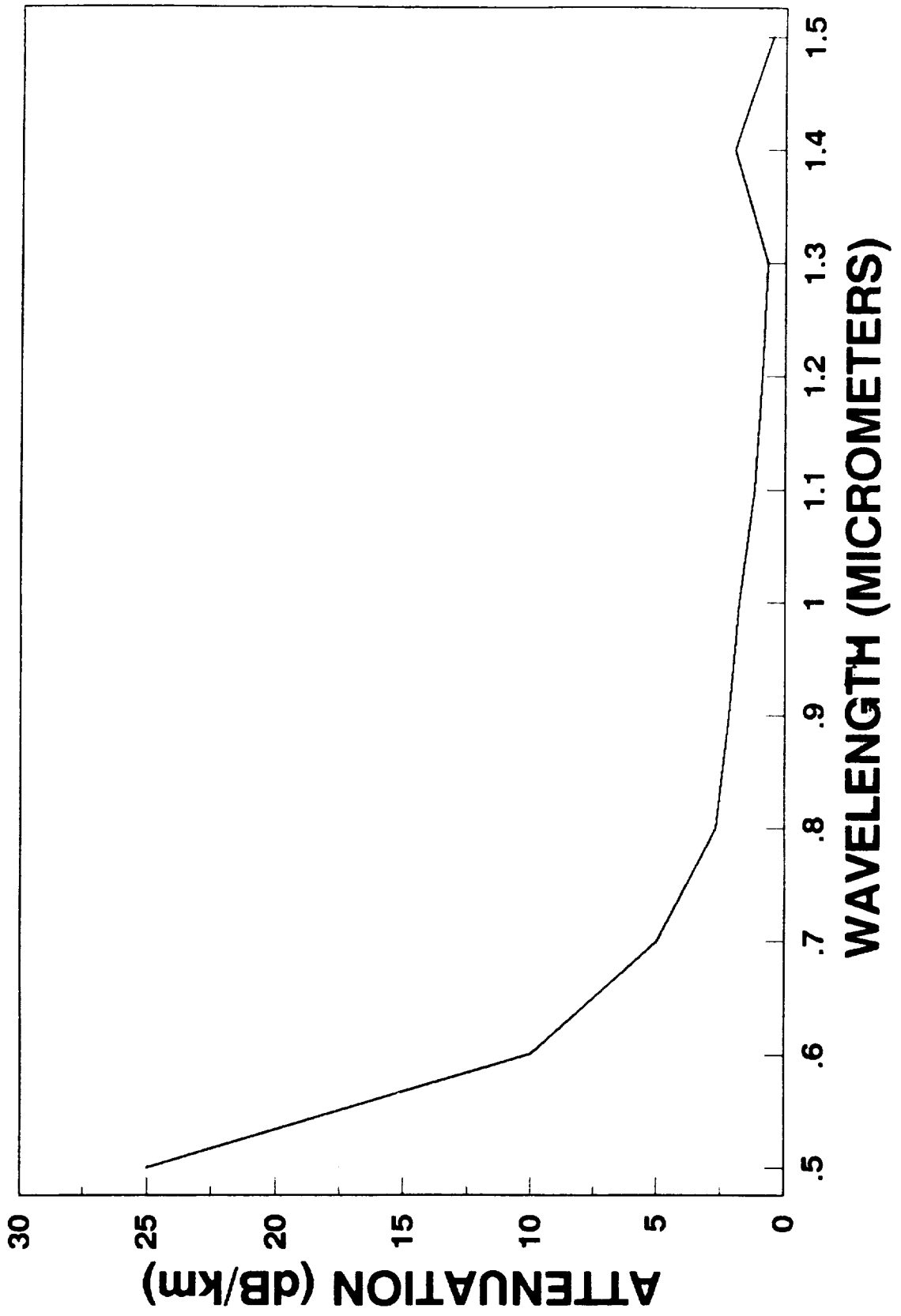


Figure 7



# SPATIAL MODE STRUCTURE WITH VARYING OPTICAL FEEDBACK

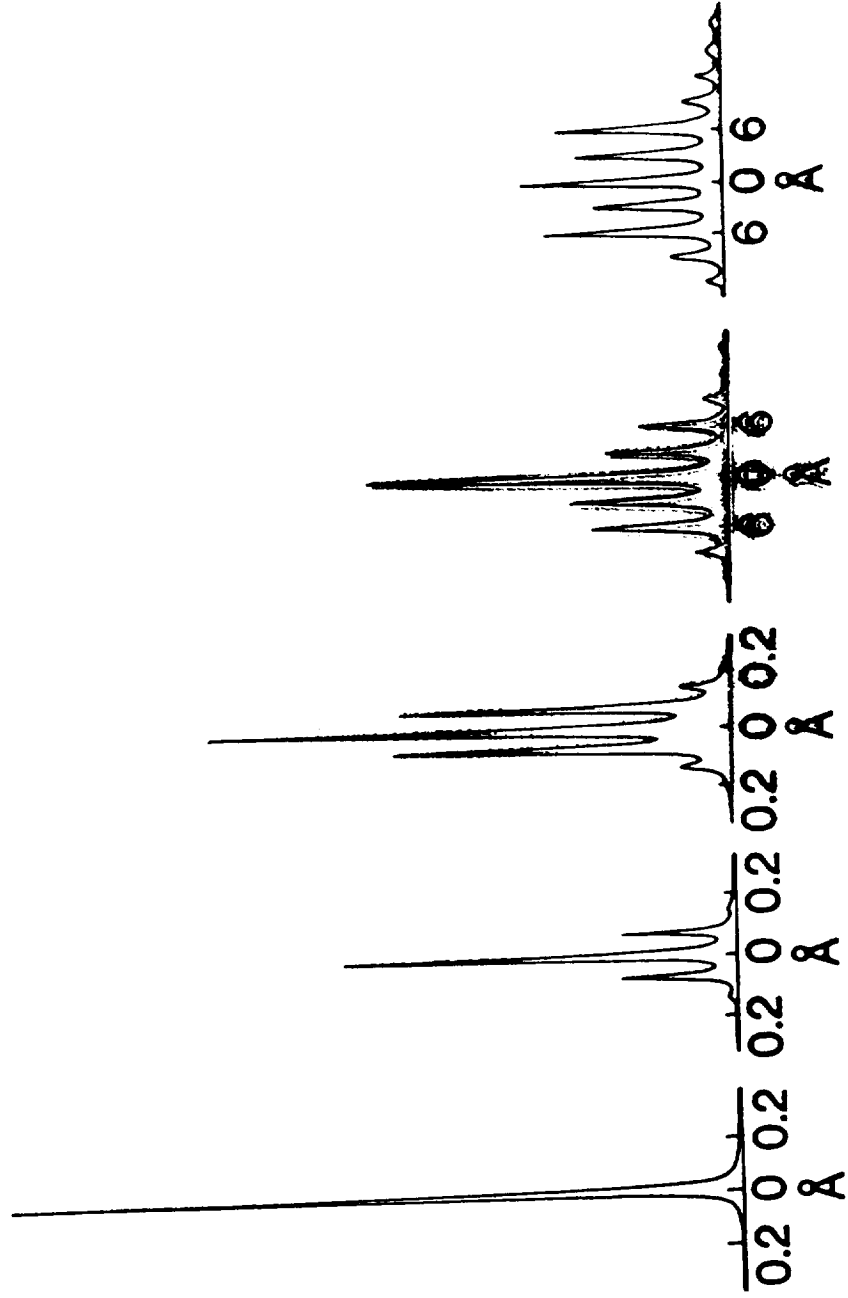


Figure 8

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