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Maximum and Minimum Return Losses From a Passive Two-Port Network Terminated With a Mismatched Load

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This article presents an analytical method for determining the exact distance a load is required to be offset from a passive two-port network to obtain maximum or minimum return losses from the terminated two-port network. Equations are derived in terms of two-port network S-parameters and load reflection coefficient. The equations are useful for predicting worst-case performances of some types of networks that are terminated with offset short-circuit loads.

I. Introduction

With the advent of automatic network analyzers, it has become common practice to characterize microwave twoport networks in terms of measured S-parameters [1]. As a result, many measurement techniques and network configurations are now being analyzed in terms of S-parameters rather than in terms of the impedance and admittance characterization parameters that have been used in the past. Microwave measurement techniques often employ the use of a sliding load, sliding short, or mismatched loads of known reflection-coefficient values. A frequently encountered problem of interest is determining the distance a particular load has to be offset from the two-port network output port to obtain a maximum or minimum return loss from the terminated two-port network. When the load is fixed (rather than sliding), line spacers can be inserted between the output of the two-port network and the load for producing the desired return losses. It is desirable to know what spacer-line length is required without having to resort to a trial-and-error process. A literature search indicates that analytical solutions, in terms of Sparameters, have not been published for these purposes.

This article will present these analytical expressions of interest.

Section II of this article sets forth the theory and analytical derivations of the conditions for maximum and minimum return losses. Also presented are design equations for dielectric spacers that can be used to obtain desired return losses. Section III presents examples showing how these equations can be used for predicting and avoiding the occurrence of a type of resonance phenomenon (leading to large dissipative losses) for some types of reflector antennas.

II. Theory

A. Derivations

The circuit under consideration is shown in Fig. 1 and the following conditions exist. It is assumed that the Sparameters of the two-port network and load reflectioncoefficient values are known. In practice, if the load is fixed, the phase of its reflection coefficient as defined at the network output port can be varied through the use of dielectric spacers. The following presents the derivation of equations required to calculate the specific conditions under which maximum or minimum return losses will be obtained from the terminated network.

Given the two-port network terminated in Γ_L as shown in Fig. 1, the input reflection coefficient as seen looking into port 1 is

$$\Gamma_1 = S_{11} + \frac{S_{12}S_{21}\Gamma_L}{1 - S_{22}\Gamma_L} \tag{1}$$

where S_{11} , S_{12} , S_{21} , and S_{22} are scattering parameters [1]. From Eq. (1),

$$\Gamma_{1} \models \sqrt{\frac{|S_{11}|^{2} + 2|S_{11}U\Gamma_{L}|\cos\theta_{1} + |U\Gamma_{L}|^{2}}{1 - 2|S_{22}\Gamma_{L}|\cos\theta_{2} + |S_{22}\Gamma_{L}|^{2}}} \quad (2)$$

where

$$U = S_{12}S_{21} - S_{11}S_{22} \tag{3}$$

$$\theta_1 = \psi_L + \psi_U - \psi_{11} \tag{4}$$

$$\theta_2 = \psi_L + \psi_{22} \tag{5}$$

and ψ_L , ψ_U , ψ_{11} , and ψ_{22} are the phase angles of Γ_L , U, S_{11} , and S_{22} , respectively.

In the following analysis, $|\Gamma_L|$ is assumed to be a constant and only ψ_L is allowed to vary. To find the maximum or minimum values of $|\Gamma_1|$ under these conditions, set

$$\frac{\partial |\Gamma_1|^2}{\partial \psi_L} = 0 \tag{6}$$

This leads to an equation of the form

$$A\sin\theta_1 + B\sin\theta_2 + C = 0 \tag{7}$$

where

$$A = |S_{11}U| (1+|S_{22}\Gamma_L|^2)$$
(8)

$$B = |S_{22}| (|S_{11}|^2 + |U\Gamma_L|^2)$$
(9)

$$C = 2 | S_{11}S_{22}U\Gamma_L | \sin(\psi_{22} + \psi_{11} - \psi_U)$$
(10)

Substituting Eqs. (4) and (5) into Eq. (7), using trigonometric sum angle identities, and collecting terms leads to the expression

$$D\cos\psi_L + E\sin\psi_L + C = 0 \tag{11}$$

where

$$D = A\sin(\psi_U - \psi_{11}) + B\sin\psi_{22}$$
(12)

$$E = A\cos(\psi_U - \psi_{11}) + B\cos\psi_{22}$$
(13)

Upon expressing Eq. (11) in the equivalent form

$$\sqrt{D^2 + E^2} \cos\left(\psi_L - \varphi\right) = -C \tag{14}$$

where

$$\varphi = \tan^{-1}\left(\frac{E}{D}\right) \tag{15}$$

then, from Eq. (14), the values of ψ_L that correspond to maximum or minimum values of $|\Gamma_1|$ are

$$\psi_{Lm} = \varphi \pm \cos^{-1} \left(\frac{-C}{\sqrt{D^2 + E^2}} \right) \tag{16}$$

Substitution of $\psi_L = \psi_{Lm}$ into Eqs. (4), (5), and (2) gives the desired values of $|\Gamma_1|_{max}$ and $|\Gamma_1|_{min}$. Return losses are computed from

$$RL_{dB} = -20\log_{10} |\Gamma_1| \tag{17}$$

B. Design of Spacers

As shown in Fig. 1, if the actual load reflection coefficient is Γ_T , but a particular Γ_L load reflection coefficient is desired to obtain a maximum or minimum return loss, a dielectric spacer can be utilized. The relationship for the dielectric spacer length of a nonferrous material is given as follows:

$$\ell = \frac{1}{2\beta} \arg R \tag{18}$$

where β is the phase constant whose expression will follow and arg R is the phase angle of a complex value R

$$R = \left(\frac{\Gamma_D + \Gamma_T}{1 + \Gamma_D \Gamma_T}\right) \left(\frac{1 + \Gamma_D \Gamma_L}{\Gamma_D + \Gamma_L}\right)$$
(19)

Eq. (19) was derived from input impedance and reflection coefficient relationships, starting at termination and transforming through the dielectric to the Z_{01} input interface.

Defining ϵ' to be the relative permittivity, $\tan \delta$ the loss tangent, λ_0 the free-space wavelength, and θ_i the incident angle, then the dielectric-air interface reflection coefficient for perpendicular polarization is

$$\Gamma_D = (\Gamma_D)_{\perp} = \frac{\sqrt{(\epsilon' - \sin^2 \theta_i) - j \epsilon'' - \cos \theta_i}}{\sqrt{(\epsilon' - \sin^2 \theta_i) - j \epsilon'' + \cos \theta_i}}$$
(20)

and for parallel polarization,

$$\Gamma_{D} = (\Gamma_{D})_{\parallel}$$

$$= \frac{(\epsilon' - j\epsilon'')\cos\theta_{i} - \sqrt{(\epsilon' - \sin^{2}\theta_{i}) - j\epsilon''}}{(\epsilon' - j\epsilon'')\cos\theta_{i} + \sqrt{(\epsilon' - \sin^{2}\theta_{i}) - j\epsilon''}}$$
(21)

For either polarization, the following relationships hold:

$$\epsilon'' = \epsilon' \tan \delta \tag{22}$$

$$\gamma = \alpha + j\beta \tag{23}$$

$$\alpha = \frac{2\pi}{\lambda_0} \sqrt{\epsilon' - \sin^2 \theta_i} \sqrt{\frac{\sqrt{1 + \tan^2 \delta'} - 1}{2}} \qquad (24)$$

$$\beta = \frac{2\pi}{\lambda_0} \sqrt{\epsilon' - \sin^2 \theta_i} \sqrt{\frac{\sqrt{1 + \tan^2 \delta'} + 1}{2}}$$
(25)

$$\tan \delta' = \frac{\epsilon''}{\epsilon' - \sin^2 \theta_i} \tag{26}$$

When measurements are made in a TE_{10} mode waveguide, in the above equations for perpendicular polarization, one may substitute

$$\sin \theta_i = \frac{\lambda_0}{\lambda_c} \tag{27}$$

$$\cos\theta_i = \sqrt{1 - \left(\frac{\lambda_0}{\lambda_c}\right)^2} \tag{28}$$

where λ_c is the cutoff wavelength for the TE_{10} mode. For a dielectric sheet of thickness ℓ , the general-case S-parameter relationships that apply to perpendicular or parallel polarization in free space or to the TE_{10} mode waveguide cases are

$$(S_{11})_D = (S_{22})_D = \frac{-\Gamma_D \left(1 - e^{-2\gamma \ell}\right)}{1 - \Gamma_D^2 e^{-2\gamma \ell}}$$
(29)

$$(S_{12})_D = (S_{21})_D = \frac{(1 - \Gamma_D^2) e^{-\gamma \ell}}{1 - \Gamma_D^2 e^{-2\gamma \ell}}$$
(30)

The above formulas were derived by considering the airto-dielectric interfaces as separate individual two-port networks, and the dielectric media of length ℓ as the third twoport network. Then, the overall S-parameters for three cascaded networks were derived using cascading formulas given in [1].

III. Applications

A. Salisbury Screen

An application of the previously derived equations is the determination of maximum return loss that will occur when a perforated plate or mesh is terminated with an offset short circuit. For this type of configuration, sometimes referred to as a Salisbury Screen [2], it is of interest to know the exact offset distance, between the short and mesh, that will lead to maximum return loss. Maximum return loss for this type of configuration will occur when there is maximum dissipation due to the resistive losses of the perforated screen or mesh.

To demonstrate the application of the derived equations, Table 1 presents measured S-parameters of a perforated plate that has been used for the antenna reflector surface material on some DSN antennas. These measured S-parameters also agree well with those calculated from theory [3]. Maximum and minimum return losses for an offset short-circuit load, as calculated through Eqs. (16) and (17), are shown in Table 2.

It is of interest to study the characteristics of this perforated plate material when terminated in an offset shortcircuit load and the offset distance is allowed to vary. Return losses calculated from Eq. (1) are plotted in Fig. 2. A sharp resonance is caused by the resistive losses of the perforated plate, and the maximum return loss is 33.2 dB. If the perforated plate were lossless, then the return loss would have been 0 dB. The exact short-circuit load position corresponding to the 33.2-dB maximum return loss was calculated from equations in this article and is shown in Table 2. The resonance phenomenon shown in Fig. 2 was observed experimentally when a sample of the perforated plate test sample was inserted in the waveguide and terminated with a sliding short-circuit load. Knowledge of maximum return loss can be used to obtain information on the resistive losses of the perforated plate. Similar techniques can be applied to the determination of resistive losses of other types of meshes such as a tricot-mesh material used for spacecraft unfurlable antennas [4,5].

The equations presented in this article are not limited to short-circuit loads, but are applicable for any load whose reflection-coefficient magnitude is greater than zero. For interest, Table 2 tabulates the conditions under which maximum and minimum return losses occur when the described perforated plate is terminated with loads having various load reflection-coefficient magnitudes.

B. Water Film on the Reflector Surface

The manufacturing process of some commercial Kuband reflectors involves pouring a fiberglass epoxy mix onto a thin metallic screen laid on a parabolic-shaped mold. After drying, the reflector consists of a fiberglass layer bonded to the metal screen. It will be shown that a fiberglass layer thickness of 1.59 mm (0.0625 in.), which sometimes results in the manufacturing process, leads to poor reflector performance at 12 GHz when the surface becomes wet due to condensation or rain.

For theoretical calculation purposes, it will be assumed that the fiberglass dielectric material has a relative permittivity of 4.5 and loss tangent of 0.002 at 12 GHz. First, the S-parameters of the fiberglass sheet of 1.59-mm thickness are calculated from Eqs. (29) and (30) for a normally incident, linearly polarized wave at 12 GHz. Then, the input reflection coefficient is calculated from Eq. (1) for the fiberglass sheet terminated in a short-circuit load. The result is an input reflection coefficient of 0.9994 with a phase angle of 123.9 deg when this fiberglass sheet is terminated with a short-circuit load. The corresponding return loss value of 0.005 dB calculated from Eq. (17) shows that this reflector with the described fiberglass layer is an excellent reflector under dry conditions. For purposes of analyzing the wet surface condition, a thin water film will be treated as a two-port network whose S-parameters are calculated from Eqs. (29) and (30) for water-film thicknesses varying between 0.05 mm (0.002 in.) and 0.10 mm (0.004 in.). These thicknesses are typical for a water film lying on a flat, smooth surface. A relative permittivity of 55.4 and loss tangent of 0.637 are used for water at 20 deg C and 12 GHz. These values for water¹ agree closely with those published in [6,7]. The resulting calculated S-parameters of water films are shown in Table 3 for normal incidence at 12 GHz.

Next, the water film terminated by the fiberglass-screen reflector is considered. Through the use of S-parameters shown in Table 3, and a load with a reflection-coefficient magnitude of 0.9994 and phase angle of 123.9 deg, the input reflection coefficient at the surface of the water film is calculated from Eq. (1). The results show that the return losses are unexpectedly high. For example, for the water-layer thickness of 0.10 mm (0.004 in.), the return loss is 12.8 dB. This result is consistent with experimental observation of about 10-dB signal losses when the fiberglass surfaces became wet from rain.²

To study the loss behavior in more detail, the return losses are shown plotted in Fig. 3 for water film terminated by a load with a reflection-coefficient magnitude of 0.9994 and a variable phase. Note that for the water-film thickness of 0.1 mm, the return loss is about 13 dB when the load phase angle is about 124 deg, but the actual peak of the resonance curve is at a lower phase angle and is about 25 dB. The exact values for the peaks of the curves for the various water-film thicknesses were calculated from Eq. (18) and are shown in Table 4. The high return losses result from the position of the maximum E-field having shifted to the inside of the film of water, which is very dissipative.

The values for minimum return losses are also tabulated in Table 4, as well as the fiberglass-layer thicknesses that correspond to maximum and minimum return losses. It is of interest to note that to obtain minimum return loss, the thickness of the fiberglass layer should be 5.84 mm (0.230 in.). The corresponding load phase angle (represented by the fiberglass-screen reflector) would then be close to 180 deg. Except for small losses due to the dielectric, this condition would be equivalent to the reflector

¹ S. J. Keihm, private communication, Microwave Observational Systems Section, Jet Propulsion Laboratory, Pasadena, California, September 1991.

² D. A. Bathker, private communication, Ground Antennas and Facilities Engineering Section, Jet Propulsion Laboratory, Pasadena, California, July 1989.

having no dielectric layer, where the rain film would lie directly on the metal surface. This result of a minimum return loss is consistent with experimental observations that very little degradation or signal loss occurs when rainwater wets a solid metallic reflector surface.

If the reflector were manufactured with a fiberglasslayer thickness of 5.84 mm (0.230 in.), rather than the current 1.59 mm (0.0625 in.), the return loss in dry conditions for the new thickness would be degraded only to 0.026 dB as compared to 0.005 dB for the original 1.59mm thickness. However, if the fiberglass surface were to become wet with water thicknesses varying from 0.05 to 0.10 mm, the return loss would still be the 0.026 dB worst case as compared to 12.8 dB for a fiberglass-layer thickness of 1.59 mm.

The equations used for this study of a fiberglass-layered reflector can also be applied for performance studies of graphite-epoxy-layered reflector surfaces being proposed for future ground-space communication antennas. It is important that the thicknesses of the dielectric layer be designed properly so as to obtain good performance in wet conditions due to rain or condensation.

IV. Conclusions

The analytical equations derived in this article are useful for determining worst-case return losses that can occur when a passive two-port network is terminated with a mismatched load. In one of the examples presented, the equations were useful for predicting worst-case return losses that could occur when water film was on a reflector surface that had a dielectric layer. The same type of analysis might be applied to a similar type of reflector painted with thermal diffusive paint suspected of being very lossy.

Although it was not shown through a specific example, for $(|\Gamma_T| < 1)$, the equations presented in this article can also be used to design dielectric- or air-line spacers that can be inserted between a fixed load $(|\Gamma_T| < 1)$ and the network if the goal is to obtain maximum or minimum return loss from the terminated two-port network.

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Table 1. Measured S-parameters of the 64-m diameter antenna perforated panel test sample at 8.448 GHz, with perpendicular polarization, 38.5-deg incidence angle, and $\phi = 0$ deg.

S-parameter	Magnitude	Phase, deg		
S_{11}	0.9990	172.4		
S_{21}	0.0305	82.2		

Notes: 1. $S_{12} = S_{21}$ and $S_{22} = S_{11}$.

- 2. S-parameters are defined for free-space characteristic impedance Z_{01} at the input and output ports.
- 3. Perforated-plate hole diameter, hole-to-hole spacing, with thicknesses of 4.763 mm (0.1875 in.), 6.350 mm (0.250 in.), and 2.286 mm (0.090 in.).

Γ_L nagnitude	Γ_L phase, deg	Return loss, dB	Comments		
1.0	-172.40	33.21	This maximum return loss occurs when the distance from a short = 0.4894 $\lambda_g^{\ a}$		
1.0	-4.00	0.0040	This minimum return loss occurs when the distance from a short = 0.2556 λ_g		
0.5	-172.27	0.1641	Maximum return loss		
0.5	8.80	0.0056	Minimum return loss		
0.1	-172.07	0.0092	Maximum return loss		
0.1	8.09	0.0076	Minimum return loss		
0.0	All values	0.0087	20 log 10 S_{11}		

 Table 2. Load reflection coefficient phase angle for minimum and maximum return losses for the 64-m diameter antenna perforated plate (see Table 1).

S-parameter	0.05-mm thick		0.076-mm thick		0.10-mm thick	
	Magnitude	Phase, deg	Magnitude	Phase, deg	Magnitude	Phase, deg
S ₁₁	0.3249	-139.48	0.4319	-145.23	0.5137	- 149.82
S_{12}	0.7855	-16.56	0.6975	-22.38	0.6239	-27.07

Table 3. Calculated S-parameters of water film for relative permittivity = 55.4, l	085	tangent
= 0.637, at 12 GHz, and with normal incidence angle.		

Notes: 1. $S_{12} = S_{21}$ and $S_{22} = S_{11}$.

2. S-parameters are defined for free-space characteristic

impedance Z_{01} at the input and output ports (see Fig. 1).

Table 4. Fiberglass plus screen load reflection coefficients and corresponding return losses for various water-layer thicknesses whose S-parameters are shown in Table 3.

Fiberglass thickness, mm	Fiberglass thickness, in.	Γ_L magnitude	Γ_L phase, deg	Return loss (no water layer), dB	Water layer thickness, mm	Return loss (with water layer), dB
1.59	0.0625	0.99940	123.86	0.0052	0.050	3.24
1.59	0.0625	0.99940	123.86	0.0052	0.076	6.69
1.59	0.0625	0.99940	123.86	0.0052	0.100	12.77
2.344	0.0923	0.99700	70.22	0.0261	0.050	8.46
2.075	0.0817	0.99824	93.37	0.0153	0.076	14.20
1.836	0.0723	0.99895	109.83	0.0091	0.100	24.92
5.865	0.2309	0.99704	-179.32	0.0257	0.050	0.026
5.847	0.2302	0.99704	-178.81	0.0257	0.076	0.026
5.834	0.2297	0.99704	-178.44	0.0257	0.100	0.026

Note: Γ_L is defined for free-space characteristic impedance Z_{01} (see Fig. 1).



Fig. 1. Two-port network terminated in a Γ_L load.



Fig. 2. Return loss of a perforated plate as a function of loadreflection coefficient phase angle.



Fig. 3. Return loss versus load phase angle for various thicknesses of water films terminated in a load having a reflection coefficient magnitude of 0.9994 at 12 GHz.