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CALCULATION OF THE AILERON AND ELEVATOR STICK FORCES

AND RUDDER PEDAL FORCES FOR THE BELL XP-83 AIRPLANE

(PROJECT MX-511) IN SPINS

By Ralph W. Stone, Jr., and Leslie E. Schneiter

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NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

MEMORANDUM REPORT

for the Air Technical Service Command, Army Air Forces CALCULATION OF THE AILERON AND ELEVATOR STICK FORCES AND RUDDER PEDAL FORCES FOR THE BELL XP-83 AIRPLANE (PROJECT MX-511) IN SPINS

By Ralph W. Stone, Jr., and Leslie E. Schneiter

SUMMARY

Aileron and elevator stick forces and rudder pedal forces for the Bell XP-83 (project MX-511) airplane in spins have been calculated. The hinge-moment characteristics of 0.14-scale models of the control surfaces of the XP-83 airplane in attitudes simulating spins, as determined in the Langley 4- by 6-foot tunnel and steady-spin data obtained on a 1/24-scale model of the subject airplane in the 20-foot free-spinning tunnel, have been used in the cálculations.

The results indicate that the aileron and elevator stick forces may be excessive unless some suitable booster or more highly balanced control surfaces are used. The pilot will be able to move the surfaces only slightly from their normal floating locations. The ailerons will tend to float slightly with the spin (stick right in a right spin) and the elevator will float full up. The rudder pedal forces will be within the capabilities of the pilot.

INTRODUCTION ·

At the request of the Air Technical Service Command, Army Air Forces, an investigation has been made to determine the control forces that would be expected in spins of the Bell XP-83 airplane. Some indication of the elevator and rudder forces were obtained during the course of the spin tests of a 1/24-scale model in the Langley 20-foot free-spinning tunnel (unpublished data). These tests have been supplemented by a more extensive series of hinge-moment measurements (reference 1) in the Langley 4- by 6-foot tunnel on 0.14-scale models of all three control surfaces in attitudes simulating those obtained in spins. In the present report the results of these hinge-moment measurements (reference 1) have been converted to actual full-scale control forces expected in spins at an altitude of 20,000 feet by considering the rates of descent, attitudes, and rates of rotation determined in the spin tests of a 1/24-scale model in the Langley 20-foot free-spinning tunnel. The results are given for the complete range of attitudes and rates of descent expected in spins of the XP-83 airplane for different control settings and loading conditions.

SYMBOLS

angle of attack of wing at midspan of aileron (the angle between the chord line and the line of the relative wind projected into a plane containing the chord line and parallel to the plane of symmetry) on inner wing (right wing in

a right spin), degrees $\left(\alpha_{c.g.} - \frac{\Omega_y}{V}\right)$

aao

angle of attack of wing at midspan of aileron (the angle between the chord line and the line of the relative wind projected into a plane containing the chord line and parallel to the plane of symmetry) on outer wing (left wing in

plane of symmetry) on outer wing (left wing in a right spin), degrees $\left(\alpha_{c.g.} - \frac{\Omega y}{V}\right)$

V

angle of yaw at the tail (the acute angle between the direction of the relative wind at the tail and the plane of symmetry), positive when relative wind is striking left side of vertical tail surface, degrees $\tan^{-1}\left[\frac{-\Omega(l \sin \alpha_{C.E.} + R)}{V}\right] - \emptyset$

radius of spin (distance from center of gravity of airplane to spin axis), feet $\left(\frac{32.2 \text{ cot } \alpha_{\text{C.S.}}}{\Omega^2}\right)$

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 $\left(\frac{\left(C_{h_{ai}} - C_{h_{ao}}\right)qb_{a}c_{a}^{2}}{\frac{180}{\pi}\frac{X_{a}}{\delta_{a_{T}}}}\right)$

Fe

Fa

elevator stick force (positive when force is a pull force), pounds $\begin{pmatrix} C_{h_e}q_{b_e}c_e^2 \\ \hline \frac{180}{\pi} \frac{X_e}{\delta_{e_{TT}}} \end{pmatrix}$

aileron stick force, pounds

 F_r rudder pedal force (positive when push force is on right rudder pedal), pounds $\left(\frac{C_{h_r}q_{b_r}c_r^2}{\frac{180}{\pi}\frac{X_r}{\delta_r}}\right)$

ac.g.	angle of attack at plane of symmetry, degrees
Ω	full-scale angular velocity about spin axis, positive in a right spin, radians per second
У	projected distance from plane of symmetry of airplane to midspan of aileron (21 ft)
V	full-scale rate of vertical descent, feet per second
Z	full-scale distance from normal center-of-gravity location to rudder hinge line (24.98 ft)
ø	angle between span axis and horizontal, positive when right wing is down, degrees
a	subscript denoting the aileron
9 <u>1</u>	subscript denoting inner wing
0	subscript denoting outer wing
е	subscript denoting the elevator
r	subscript denoting the rudder
T	subscript denoting total angular movement
Ch	hinge-moment coefficient (H/qbc2)

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Н	hinge moment, foot-pounds
q	dynamic pressure $\left(\frac{1}{2}\rho V^2\right)$
Ъ	span of the aileron, elevator, or rudder along corresponding hinge axis, feet
c	root mean square chord of the control surface rearward of the hinge axis, feet
Х	total movement of the control stick or rudder pedal (values estimated from specifications listed in reference 2)
	Control stick { laterally 1.5 feet longitudinally 1.5 feet
	Rudder pedal 0.54 foot
δ	angular movement of the control surfaces relative to the chord line of the surface to which it is attached, degrees
	Total angular movement of:
	Aileron 50° (±25°) positive when trailing edge is down
	Elevator 40° (-25° to 15°) positive when trailing edge-is down
	Rudder 50° $(\pm 25^{\circ})$ or 40° $(\pm 20^{\circ})$ positive when trailing edge is to left. (The rudder pedal forces were calculated for both $\pm 25^{\circ}$ and $\pm 20^{\circ}$ total deflection inasmuch as it is not definite at present which deflections are to be used on the airplane).
ρ	air density, slug per cubic foot

 $I_{\rm X},\,I_{\rm Y},\,I_{\rm Z}$ moments of inertia about X-, Y-, and Z-body axes, respectively, slug-feet^2

APPARATUS AND METHODS

Models

Drawings showing the 0.14-scale models of the loft wing panel and the dummy fuselage and tail surfaces used for the hinge-moment tests in the h- by 6-foot tunnel (see reference 1) are presented on figures 1 and 2, respectively. A photograph of the tail surfaces mounted in the h- by 6-foot tunnel is given in figure 3. A three-view drawing of the 1/24-scale spin-tunnel model used for the spin tests in the Langley 20-foot free-spinning tunnel is shown on figure 4. The dimensional characteristics of the plane are given in table I.

Method of Calculation

The hinge-moment characteristics of the 0.14-scale models of the control surfaces of the XP-83 airplane used in the calculation of the stick and rudder pedal forces are presented in reference 1. The steady-spin data obtained from spins of the 1/24-scale model of the XP-83 airplane used in the calculation of the stick forces are presented on tables II and III.

Aileron stick forces. - In the calculation of the aileron stick forces, it is necessary to consider the variation of angle of attack at the aileron due to rolling. Reference & gives a method of obtaining, for the normal flight range, the location along the aileron span at which the angle of attack should be calculated for use in determining the hinge-moment coefficient for a given aileron deflection. This method is based on spanwise pressure distributions in unstalled flight. Because of the difference in pressure distribution between stalled and unstalled flight, it was felt that this method was not applicable to the present problem and therefore the angle of attack used was arbitrarily that of the midspan of the aileron.

Elevator stick forces. - In the calculation of the elevator stick forces the hinge-moment coefficient for a given elevator deflection was taken from the curve of elevator hinge-moment coefficient versus angle of attack for 0° yaw with the rudder neutral (fig. 6).

The use of these hinge-moment data is justifiable because the effects of yaw and rudder deflection on the elevator hinge-moment characteristics are generally small according to reference 2. The angle of attack at the plane of symmetry of the model was used in the computations. It is appreciated that as a result of rotation of the spinning airplane (or model) there is a variation in angle of attack along the tail span which may amount to a difference of approximately 50 between the angle of attack at the plane of symmetry and the angle of attack at the tip of the horizontal This variation in angle of attack is, for all tail. practical purposes, linear and, hence, the average angle of attack of the horizontal tail is approximately equal to the angle of attack at the plane of symmetry of the airplane. Inasmuch as the airplane will normally be spun with the elevator full up ($\delta_{\Theta} = -25^{\circ}$), the stick force necessary to move the elevator from the up stop to neutral or full down was calculated using the steadyspin data for elevator-up spins with different aileron deflections, model loadings, and model configurations in order to cover the complete range of rate of descent expected for the airplane. The highest rate of descent and the lowest angle of attack recorded for a steady spin during the model spin tests was for an elevatordown spin. Data from this spin were used for several elevator-up spins that had rates of descent greater than that readily obtainable in the spin tunnel but were otherwise similar to this elevator-down spin. The elevator hinge-moment data (presented in reference I) were obtained with the stabilizer at -2,66° incidence, whereas the steady-spin data (tables II and III) were obtained with the stabilizer neutral. No correction was made for this difference in angle of attack of the horizontal tail.

Rudder pedal forces. - The rudder hinge-moment data (reference 1) are for the extended vertical tail surfaces whereas the majority of the steady-spin data used in these calculations were obtained with the original vertical tail. It is felt that this is justifiable because steady-spin data of brief tests with the extended tail did not vary appreciably when compared with that with the original tail. In the calculation of the forces required to move the rudder to its full deflection against the spin for the ±20° maximum rudder deflection, the steady-spin data for ±25° maximum rudder deflection were assumed to apply, as sufficient steady-spin data with the reduced deflections were not

available. Brief spin tests (unpublished) with the revised rudder deflection indicate that the steady-spin data for spins with either of the rudder deflections are similar.

Rudder hinge-moment data (reference 1) were obtained only for angles of attack of 20° and 50° as these angles represented typical attitudes at the extremes of the range of angles of attack possible on the airplane. The rudder pedal forces were calculated for spins that had angles within a few degrees of these values. The forces necessary to fully reverse the rudder to 25° and 20° against the spin were calculated.

In the calculation of the stick and pedal forces it was assumed that the control movements were accomplished rapidly and that the attitude and rate of descent of the airplane did not change appreciably during the control movement. Because of the lack of data on control-system mass unbalanced and friction, control-system mass and friction forces were not considered in the calculations.

RESULTS AND DISCUSSION

The results of the aileron and elevator stick and rudder pedal force calculations are presented on figure 5, figure 6 and table II, and figure 7 and table III. The steady-spin and control-force data are presented in terms of full-scale values for the airplane at a test altitude of 20,000 feet.

Aileron Stick Forces

The results of the aileron stick-force calculations are presented on figure 5 as a plot of rate of descent versus aileron stick force for various aileron deflections. The results show that the ailerons will tend to float slightly with the spin (zero stick force). The results also show that the force required to move the stick laterally far from the floating location will be greater than the pilot can exert. From model spin tests it was indicated that aileron-with settings may seriously retard recovery for some loadings.

Elevator Stick Forces

The results of the elevator stick-force calculations are presented on figure 6 and table II. Figure 6 is a plot of the maximum elevator stick force for each of three elevator movements versus rate of descent. Table II is a list of the angles of attack, rates of descent, and the stick forces for the three elevator movements for each of the conditions calculated.

The curves represent the maximum elevator stick forces expected at the various rates of descent. For rates of descent below 330 feet per second, lower stick forces were also obtained for some conditions but for purposes of clarity on the figure these stick forces were not plotted. It is shown on the figure that the highest elevator stick force will be encountered while attempting to fully reverse the elevator in steep spins and will be of the order of 250 pounds push force. In reference 2 it is shown that the maximum push force that a pilot can exert with one hand is 120 pounds. It appears, therefore, that the stick force necessary to fully reverse the elevator may be greater than the pilot can exert.

Rudder Pedal Forces

The calculated rudder pedal forces, as well as the steady-spin data used in the calculation of the forces, are presented on figure 7 and table III. A study of this figure and table shows that the rudder pedal forces are within the capabilities of the pilot. Reference 2 states that the maximum push force that the pilot can exert on a rudder pedal is approximately 400 pounds. The maximum pedal force to move the rudder 25° against the spin was calculated as 265 pounds and the minimum force was 73 pounds. The maximum pedal force to move the rudder 20° against the spin was 119 pounds and the minimum force was 52 pounds.

Control Forces in Recovery

The recommended recovery technique for the XP-83 airplane is to hold the stick neutral laterally and full back; rapidly reverse the rudder and follow in 1/2 turn

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by movement of the stick forward of neutral. The control positions must be held until recovery is effected. Figures 5 and 6 indicate that the forces required to hold the stick neutral laterally and to move it forward of neutral will probably be in excess of the pilot's capabilities, the force required to hold the stick neutral laterally being of the order of 100 pounds and the force required to move the stick forward of neutral being in excess of 120 pounds.

Comparison of Spin-Model Control-Force Results

with Results of Hinge-Moment Tests

A comparison of the control-force results obtained from the 1/24-scale spin-model tests in unpublished data for spins at moderate attitudes and rates of descent indicates good agreement with the results obtained herein from hinge-moment data for a corresponding condition. The elevator stick force measured in free-spinning tests at a rate of descent of 310 feet per second (full-scale values) was approximately 140 pounds. This compares favorably with a force of 160 pounds for the same rate of descent as taken from figure 6. The rudder pedal force obtained in free-spinning tests at a rate of descent of 272 feet per second (full-scale values) was approximately 140 pounds (full-scale values). It is shown on table III that forces calculated for spins with rates of descent of 273 foot per second vary from 135 to 142 pounds.

CONCLUSIONS

Based on the results of calculations of the aileron and elevator stick and rudder pedal forces for the XP-83 airplane in spins at a test altitude of 20,000 feet, the following conclusions are made for the airplane with the extended vertical tail surfaces:

1. The aileron and elevator stick forces will probably exceed the pilot's capabilities and may, therefore, prevent use of the recommended technique for recovery.

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2. The rudder pedal force necessary to move the rudder to full against the spin will be within the capabilities of the pilot for both the $\pm 25^{\circ}$ and $\pm 20^{\circ}$ deflection.

Langley Memorial Aeronautical Laboratory National Advisory Committee for Aeronautics Langley Field, Va, September 7, 1945.

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- 2. Gough, M. N., and Beard, A. P.: Limitations of the Pilot in Applying Forces to Airplane Controls. NACA TN No. 550, 1936.
- 3. Swanson, Robert S., and Toll, Thomas A.: Estimation of Stick Forces from Wind-Tunnel Aileron Data. NACA ARR No. 3J29, 1943.

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TABLE I

DIMENSIONAL CHARACTERISTICS OF THE BELL XP-83 AIRPLANE

Wing span, ft Length over all, ft Normal weight, lb Normal center-of-gravity location, percent M.A.C.	53 44.8 18,300 23.5
Wing: Area, sq ft. Aspect ratio Sweepback of leading edge of wing, deg Dihedral at 45-percent chord line, deg Mean aerodynamic chord, in Leading edge of M.A.C. aft of leading edge of wing root	/430 6.51 8.1 105 11.32
Flaps: Type	Fowler 24.9 31.6
Ailerons: Chord, percent of wing chord	. 25 7.30 40.1
Horizontal tail surfaces: Total area, sq ft Span, ft Elevator area, including balance, sq ft Distance from normal center of gravity to elevator hinge line, ft Dihedral, deg	75.9 18.66 29.80 24.10 . 10
Original vertical tail surface: Total area, sq ft	42.86 8.84 18.33 24.98

TABLE I - Concluded

DIMENSIONAL CHARACTERISTICS - Concluded

Ext	ended	vertic	cal	tai	1 :	sur	fac	e:								
	Total	area,	sq	ft												47.6
	Span,	along	hir	ige	ax	is,	ft	;								10.34
	Rudder	area,	, in	iclu	di	ng	bal	and	ce	,	sq	f	t			20.06

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TABLE II

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ELEVATOR STICK FORCES AND STEADY-SPIN PARAMETERS FOR DIFFERENT CONFIGURATIONS

OF THE XP-83 AIRPLANE

[Configurations and steady-spin parameters taken from free-spinning test data (unpublished); stick forces calculated from data in reference 1 and from free-spinning test data]

Configuration	Control se	tting	Airspeed	Angle of attack a	Stick force	Stick force for $\delta_0 = 0^0$	Stick force for $\delta_0 = 15^\circ$
	Ailerons	Elevator	(ft/sec)	(deg)	(10)	(15)	(15)
Configuration Normal loading, clean condition Do	Ailerons Against do Against do do do do do do do With Against 1/3 with 1/5 with 1/3 gainst do With	Elevator Up Up Up Up Up Up Up Up Up Up Up Up Up	(ft/sec) 277 274 234 248 248 248 248 248 248 248 248 248 24	attack d (deg) 46.5 450.5 54.9 48.3 55.6 46.5 47.5 54.9 48.3 55.6 46.5 57.2 46.5 57.2 46.5 57.2 57.2 58.9 8.2 87.7 23.5 58.9 33.4 55.5 51.7 51.5 51.7 51.5 55.5 51.4 55.5 51.4 55.5 51.4 55.5 51.4 55.5 51.4 55.5 51.7 51.5 55.5 51.4 55.5 51.5 51	$\begin{array}{c} 101 & 6_{0} & -22 \\ (10) \\ \\ 50 \\ 47 \\ 542 \\ 40 \\ 399 \\ 399 \\ 399 \\ 399 \\ 399 \\ 399 \\ 47 \\ 54 \\ 99 \\ 442 \\ 567 \\ 599 \\ 661 \\ 99 \\ 651 \\ 499 \\ 440 \\ 440 \\ 4$	$\begin{array}{c} 101^{\circ} & 6_{0} & 2 & 0^{\circ} \\ (10) & & \\ 85 & 80 & \\ 73 & 81 & \\ 71 & 56 & \\ 76 & 65 & \\ 83 & 77 & \\ 94 & 68 & \\ 72 & 84 & \\ 90 & 86 & \\ 91 & 68 & \\ 94 & 82 & \\ 82 & 81 & \\ 93 & \\ \end{array}$	$\begin{array}{c} 101 & 0_{0} & -19^{-1} \\ (10) \\ \hline \\ 131 \\ 131 \\ 131 \\ 134 \\ 117 \\ 111 \\ 101 \\ 101 \\ 101 \\ 101 \\ 101 \\ 101 \\ 101 \\ 120 \\ 123 \\ 127 \\ 148 \\ 139 \\ 120 \\ 120 \\ 143 \\ 172 \\ 126 \\ 120 \\ 143 \\ 172 \\ 126 \\ 124 \\ 160 \\ 167 \\ 206 \\ 225 \\ 163 \\ 124 \\ 140 \end{array}$
Alternate loading III Alternate loading III Stabilizer leading edge 7° down Do	Neutral With 1/5 with Against do 2/3 against 1/3 against Neutral	Up Up Up Up Up Up Up Up Up Up Up Up	259 308 280 250 263 284 284 284 244 255 284 244 255 2245 443	2526226004328 82455371150298 541550298 105541150298	5089550065610	110 91 113 102 87 79 91 73 120 83 69 73 78	153 153 164 137 129 126 138 131 157 126 102 114 254

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TABLE III

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RUDDER PEDAL FORCES AND STEADY-SPIN PARAMETERS FOR DIFFERENT CONFIGURATIONS

OF THE XP-83 AIRPLANE

[Configurations and steady-spin parameters taken from free-spinning test data (unpublished); rudder pedal forces calculated from data in reference 1 and from free-spinning test data]

Configuration	Control se		Stead	Rudder pedal force .(1b)						
	Ailerons	Elevator	V (ft/sec)	a (deg)	A (rad/sec)	ø (deg)	R (ft)	(deg)	δ _r = 25°	$\delta_r = 20^{\circ}$
Normal loading, clean condition Do	Against do Neutral 1/2 against Against do With Against do With Against do do Neutral Against do Neutral Against do Neutral Against do Neutral Against do 1/3 against 	Down Up Down Up Down Up Down Up Down Up Down Up Down Down Down Down Up Down Up Down Up Up Up Up Up Up Up Up Up Up Up Up Up	25793444961931145057745600333335465	3 597097 3 9060605875970296 3 247826 66556498255 16 6662778 3 580914 3 38719820 208209145555145445544555551454455	$\begin{array}{c} 2.61\\ 2.01\\ 2.59\\ 2.28\\ 2.26\\ 2.532\\ $	8.9664678713002253202108008690693309995 1266666627976667991503022641071643	474754464605295600451139620077555 46659401569676070508837767488590440 474754463454750466526057657455366676556	$\begin{array}{c} 21.0\\ 23.53\\ 19.1\\ 9.92\\ 15.6\\ 20.1\\ 21.6\\ 19.7\\ 21.6\\ 19.7\\ 21.6\\ 19.7\\ 21.73\\ 19.7\\ 21.73\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 19.7\\ 20.7\\ 10.7\\ 10.5\\ 19$	$\begin{array}{c} 106\\ 150\\ 121\\ 135\\ 182\\ 108\\ 77\\ 108\\ 73\\ 94\\ 175\\ 84\\ 108\\ 121\\ 105\\ 113\\ 147\\ 195\\ 131\\ 147\\ 195\\ 134\\ 1461\\ 115\\ 87\\ 2653\\ 134\\ 142\\ 105\\ 129\\ 129\\ 129\\ \end{array}$	$\begin{array}{c} 76\\ 117\\ 86\\ 99\\ 79\\ 75\\ 80\\ 52\\ 71\\ 85\\ 57\\ 85\\ 101\\ 75\\ 81\\ 100\\ 75\\ 81\\ 100\\ 92\\ 970\\ 844\\ 994\\ 994\\ 994\\ 996\\ 832\\ 119\\ 85\\ 99\\ 114\\ 31\\ 111 \end{array}$

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Figure 3.- Three-quarter top view of the XP-83 tail surfaces as tested in the Langley 4- by 6-foot tunnel. Wind direction vertically downward in plane of picture.



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Figure 4. - Drawing of 1/24-scale model of the Bell XP-83 airplane as tested in the spin tunnel. Wing incidence 1° leading edge up. Stabilizer incidence 0.° Center-ofgravity position shown for normal loading.

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