

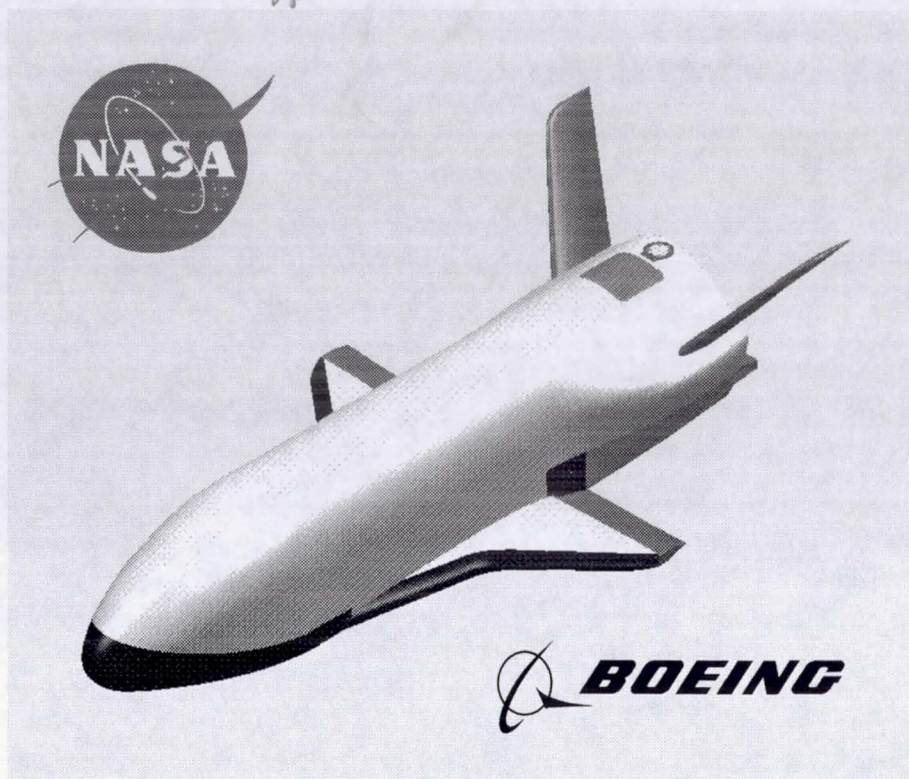
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The NASA IVHM Technology Experiment for X-37

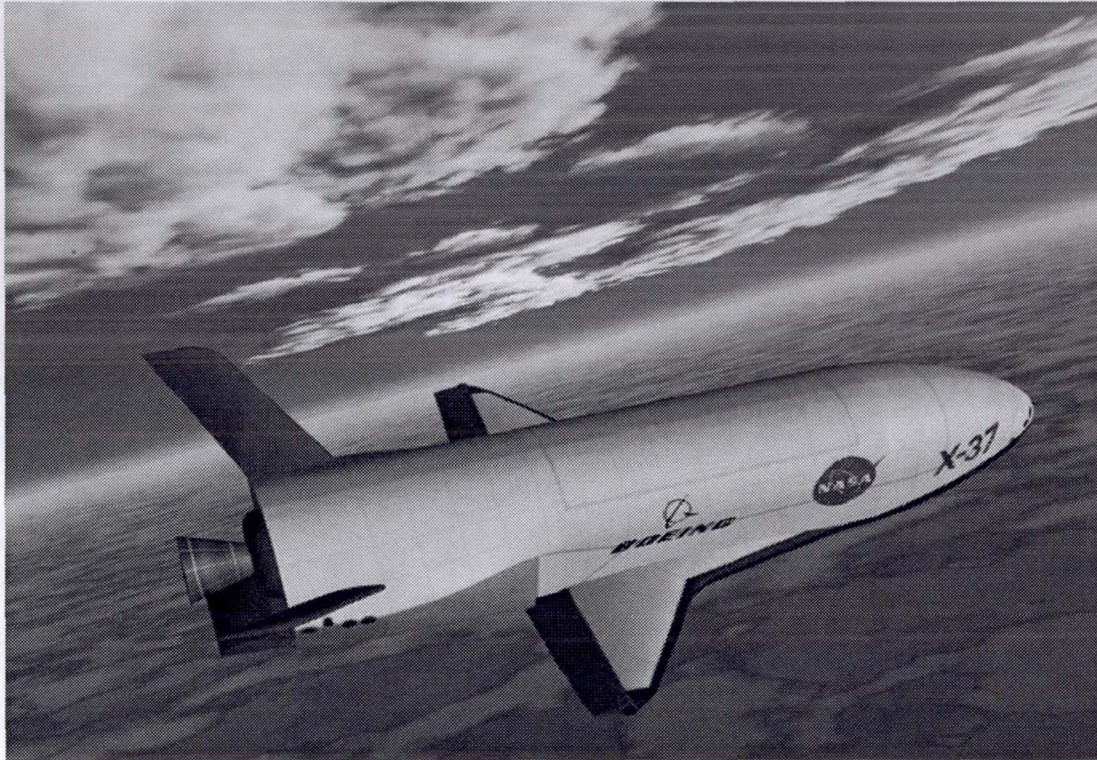
Mark Schwabacher
NASA Ames Research Center

Space Transportation Technology IVHM Session

- ◆ **Long-term goal: Reduce cost and increase reliability of space transportation**
- ◆ **Demonstrate benefits of in-flight IVHM to the operation of a Reusable Launch Vehicle**
- ◆ **Advance this IVHM technology to Technology Readiness Level ~7 within a flight environment**
- ◆ **Operate IVHM software on the Vehicle Management Computer**

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Technology Goals and Objectives

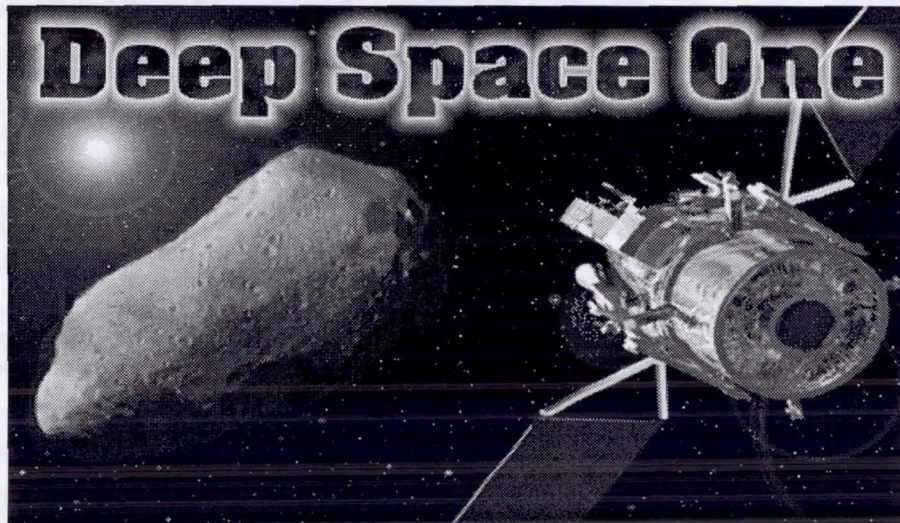


- ◆ Unpiloted
- ◆ Reusable
- ◆ 27.5 feet long
- ◆ Mission:
 - launch from Shuttle's cargo bay
 - orbit Earth 21 days
 - De-orbit and land on runway autonomously
- ◆ First flight in 2002
- ◆ Being built by Boeing for NASA MSFC

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Background: X-37

- ◆ Livingstone automates system-level fault diagnosis
- ◆ Qualitative, Model-based Reasoning
 - Searches system-wide interactions to detect and isolate failures
 - Eliminates 'hardwiring' pre-defined set of failures
 - Updating and verifying the model is straightforward
 - Streamlines development and maximizes code reusability
- ◆ Accomplishment: Successfully flown on Deep Space One
- ◆ Also scheduled to fly on X-34

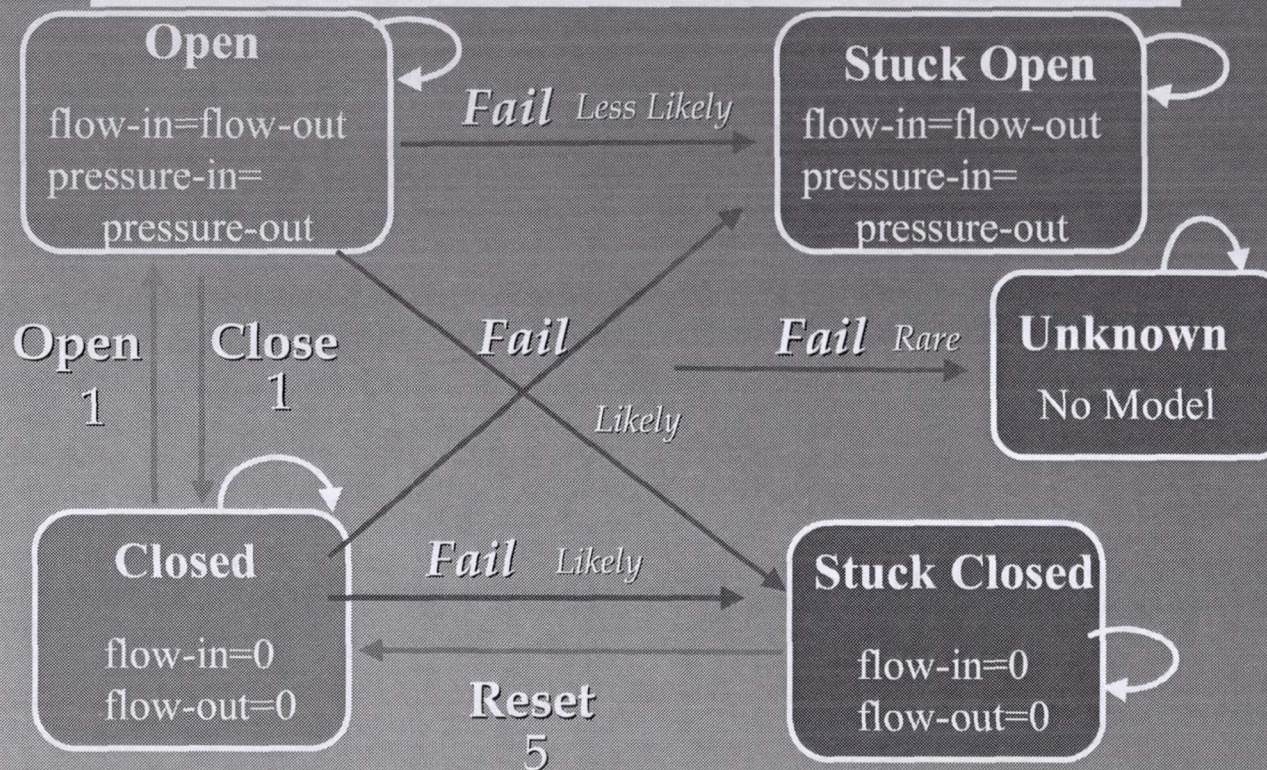


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Background: Livingstone



Livingstone Valve Model

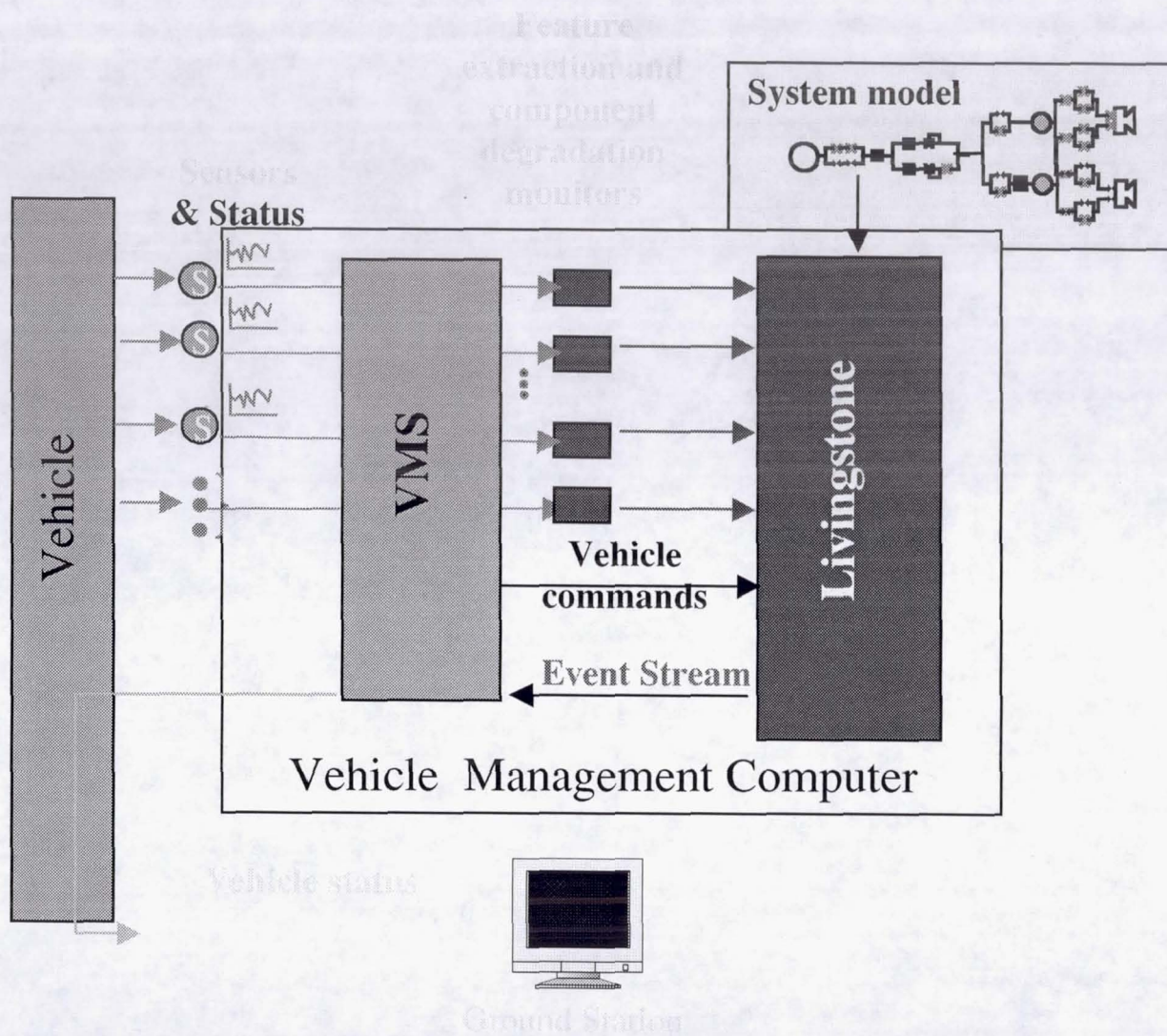


NASA Ames Research Center, Center of Excellence in Information Technologies, Autonomy Program

SEKE98 06/20/98

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Livingstone Model Example from DS-1



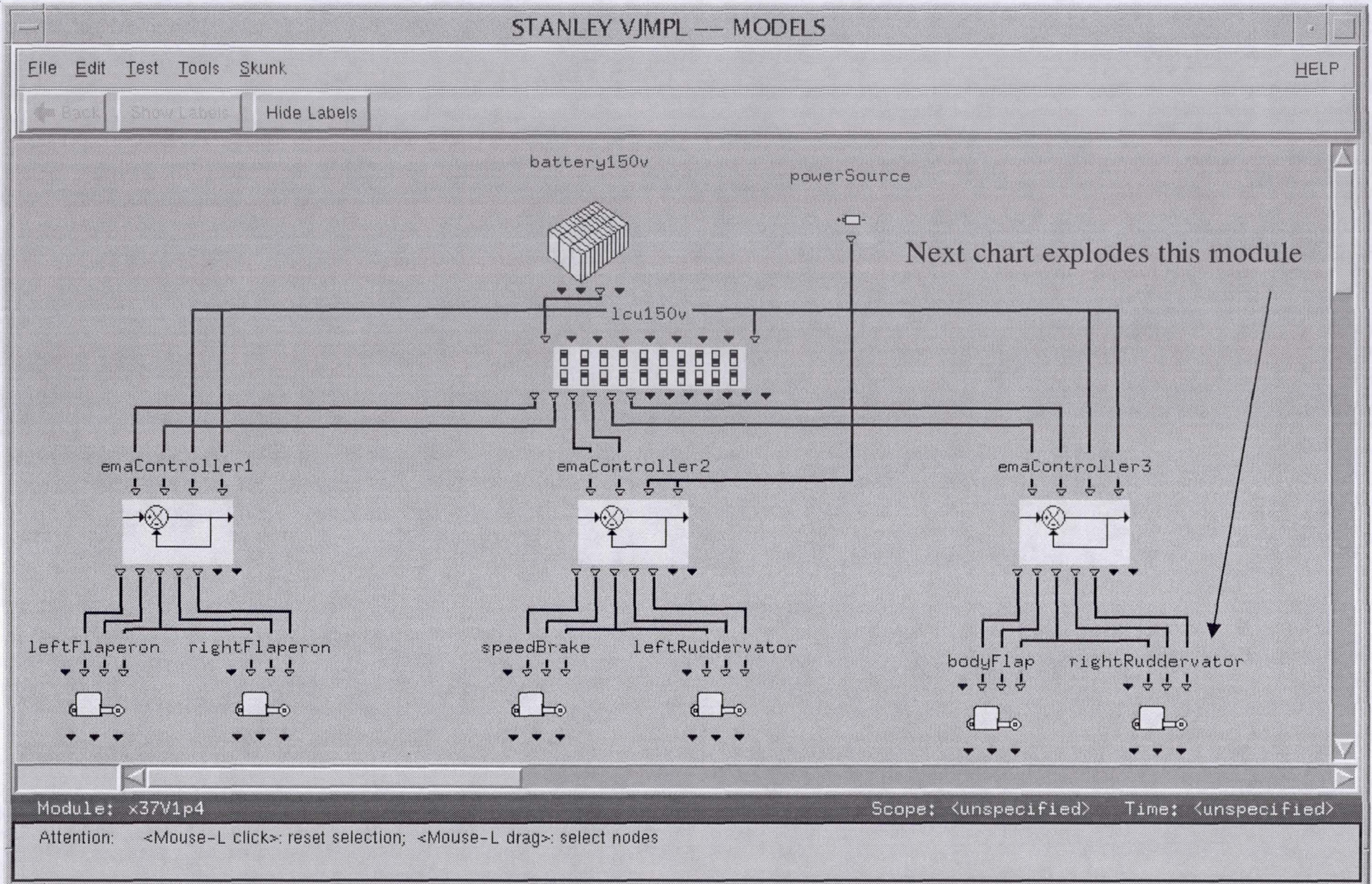
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Experiment Overview

- ◆ **Monitor and diagnose:**
 - **Electro-Mechanical Actuators (EMA) for control surfaces**
 - **Associated Electrical Power System components**
- ◆ **Real-time fault detection and isolation**
- ◆ **Diagnosis, not prognosis**
- ◆ **Shadow mode only (no reconfiguration commands)**
- ◆ **Generate advisory recommendations for ground ops**

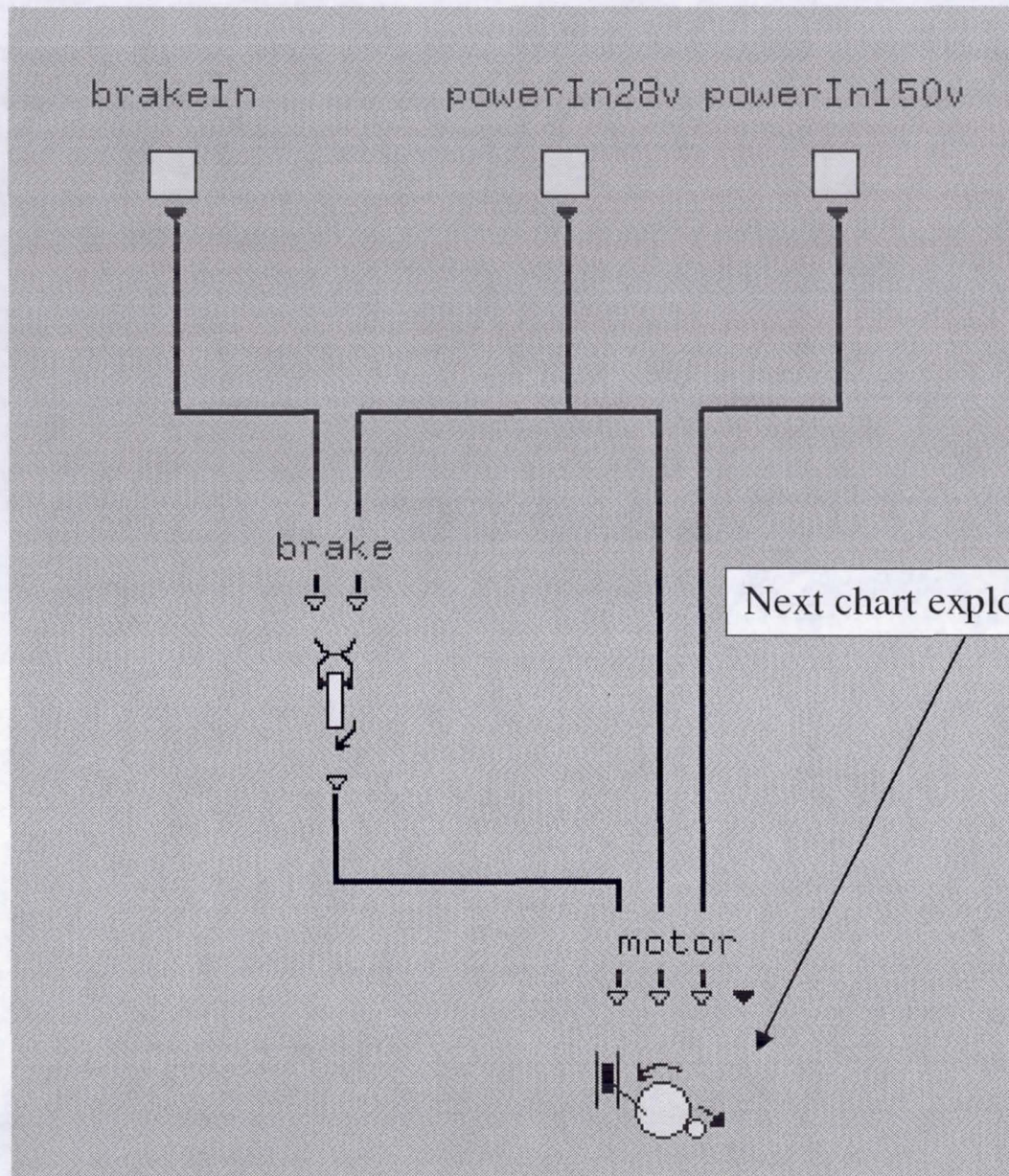
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X-37 IVHM Scope



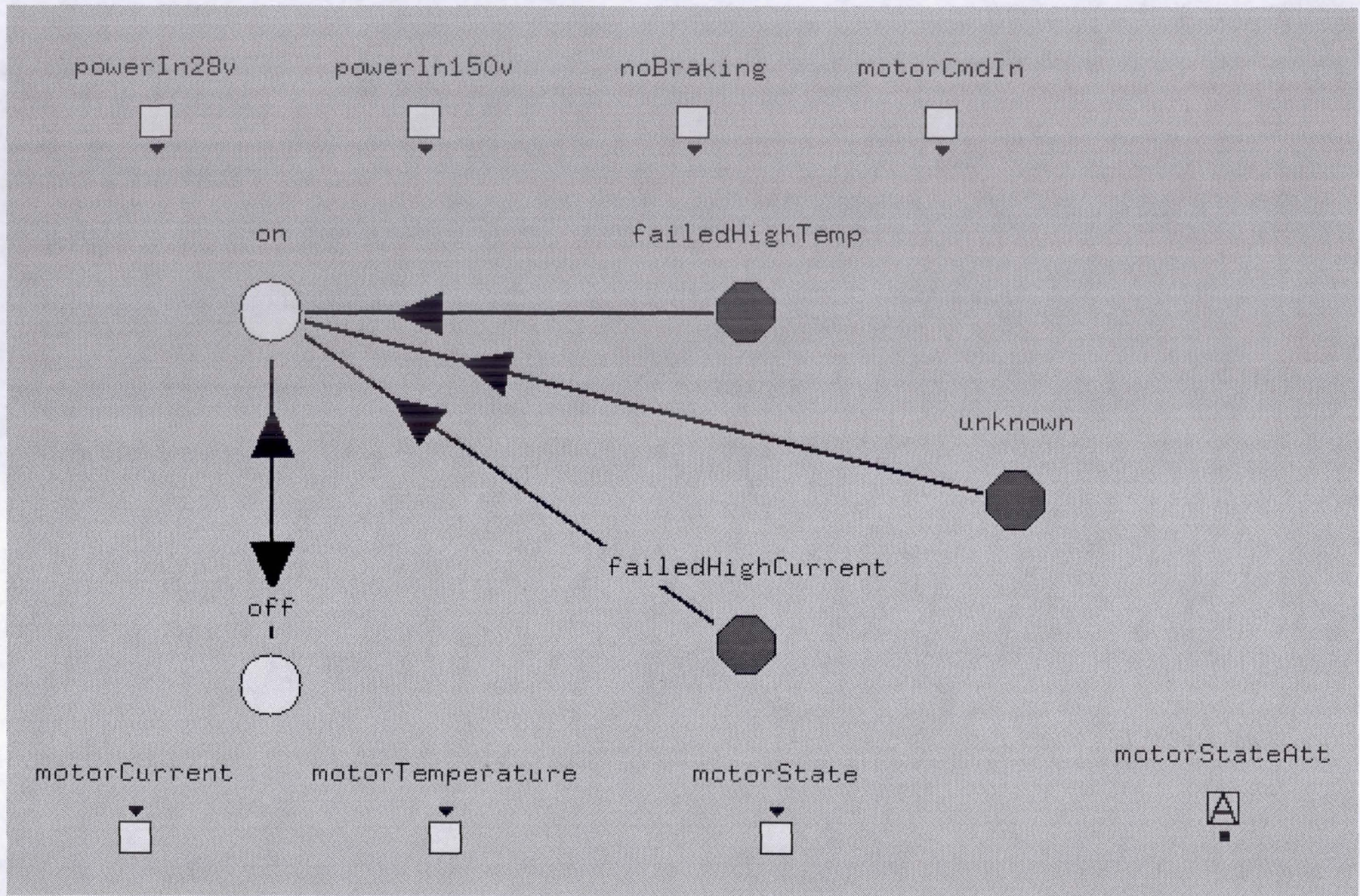
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Stanley Interface to Livingstone Model

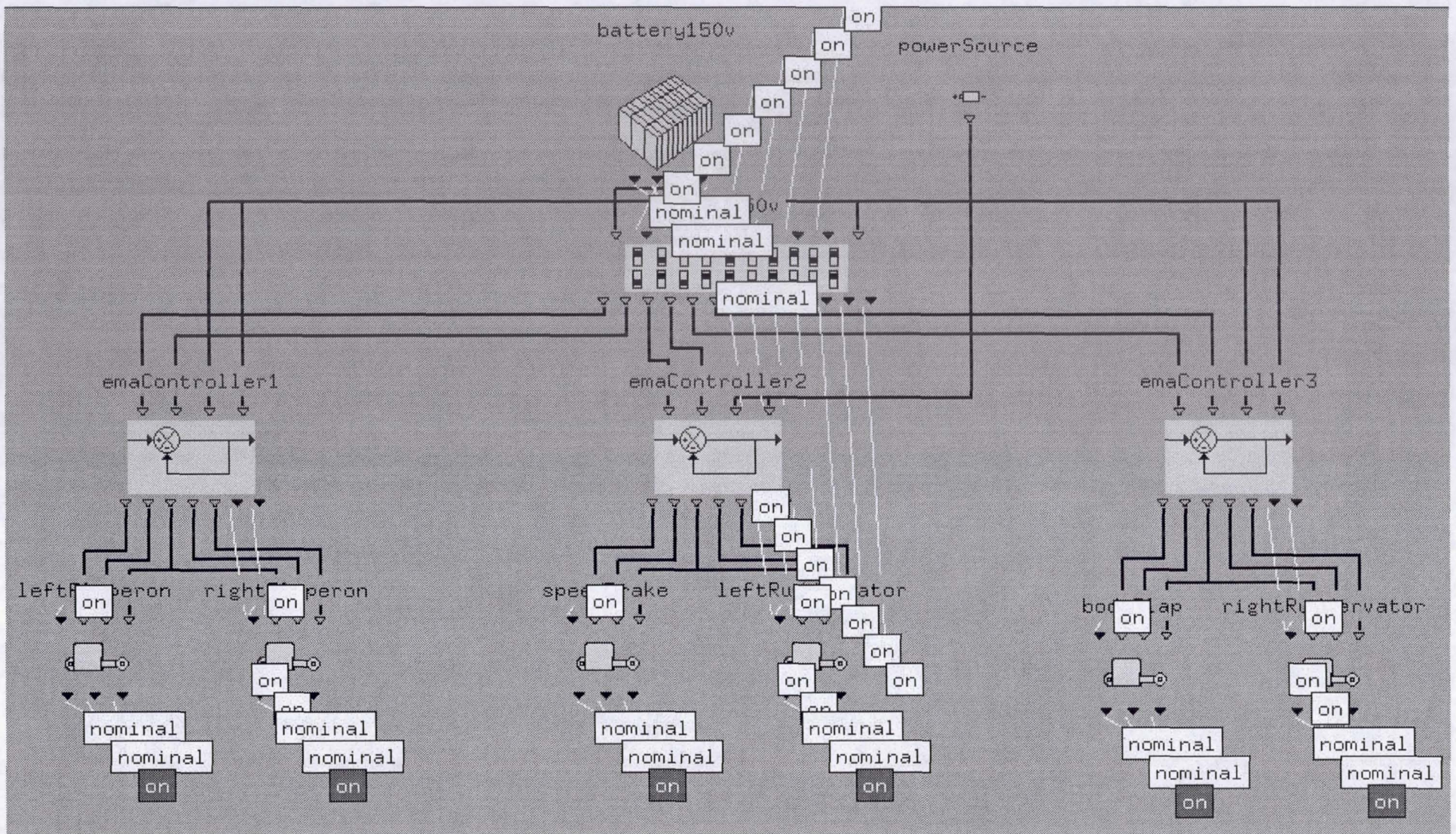


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Right Ruddervator Actuator Detail

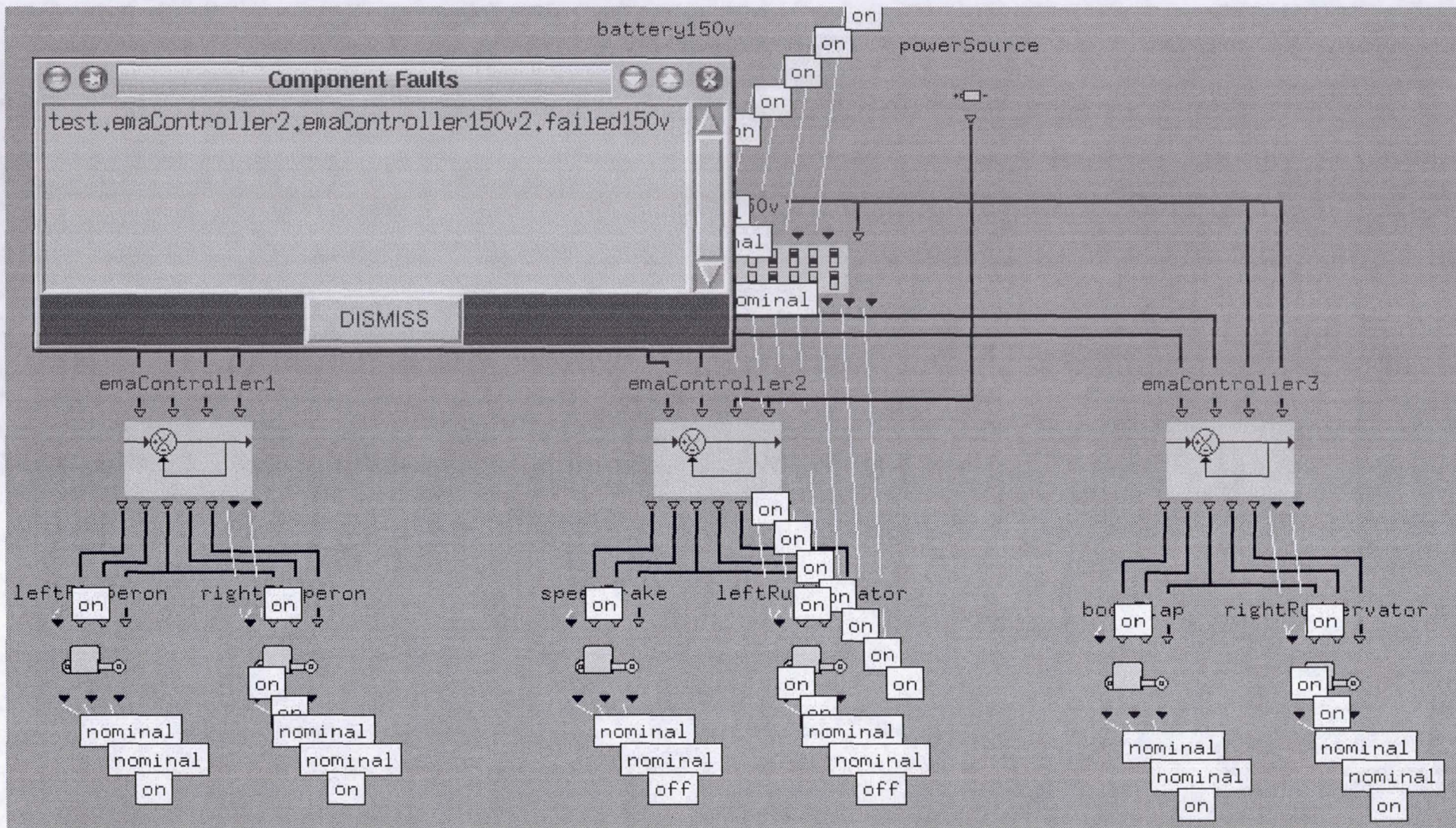


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Motor state diagram



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Inferred Nominal State



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Inferred Failure

- ◆ The IVHM Experiment's outputs will be provided as inputs to the X-37 Informed Maintenance (IM) Experiment
- ◆ The IM software will run in the X-37 ground station, processing IVHM Experiment flight data in real-time
- ◆ IM Experiment is being performed by NASA KSC and Boeing
- ◆ The IM Experiment's goal is to reduce the cost and time needed to maintain the vehicle

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X-37 Informed Maintenance Experiment

- ◆ **During the second orbital mission, we will use simulated faults to demonstrate the IVHM software's ability to diagnose them**

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Simulated Faults

- ◆ Livingstone ported from LISP to C++ under VxWorks
- ◆ Preliminary design of Interface with Boeing software completed
- ◆ Knowledge of X-37 subsystems gained from Boeing experts
- ◆ First subset of X-37 model completed

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Current Status

- ◆ **Limited vehicle resources available to IVHM**
 - CPU
 - Memory
 - Telemetry
 - May need to descope experiment to fit resource constraints
- ◆ **Rigorous software safety standards**

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Challenges

- ◆ **03/01/01: Deliver IVHM Ver1 Software to Boeing for B-52-based autonomous approach and landing tests**
- ◆ **03/01/02: Deliver IVHM Ver2 Software to Boeing for orbital flights**

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Upcoming Milestones

- ◆ **Mina Cappuccio:** X-37 L3 PM & Expt Programmatic Lead,
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- ◆ **Jeff Samuels:** Technical Lead,
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- ◆ **Mark Schwabacher:** Software Lead,
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- ◆ **Scott Poll, Kevin Carbajal:** X-37 Models & Monitors
- ◆ **Scott Christa, Benoit Hudson:** Software Integration & Test
- ◆ **Dan Clancy, Jim Kurien:** Consulting

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People and Contact Information