



Mars Science Laboratory Overview & MSL EDL Challenges

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PRE-DECISIONAL DRAFT: For Planning and Discussion Purposes Only

Mars Program This Decade

2001



MARS ODYSSEY

2003



MARS EXPRESS
(ESA)

2005



MARS RECONNAISSANCE
ORBITER

2007



PHOENIX

2009



MARS TELESAT ORBITER

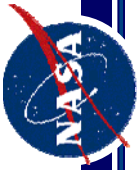
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MARS EXPLORATION
ROVERS

MARS SCIENCE LABORATORY





MSL PROJECT OVERVIEW

Salient Features

Mobile Science Laboratory

Hundreds of days of surface operational lifetime

Discovery Responsive over wide range of latitudes and altitudes

Controlled Propulsive Landing

Precision Landing via Guided Entry



Science

Mission science will focus on Mars habitability

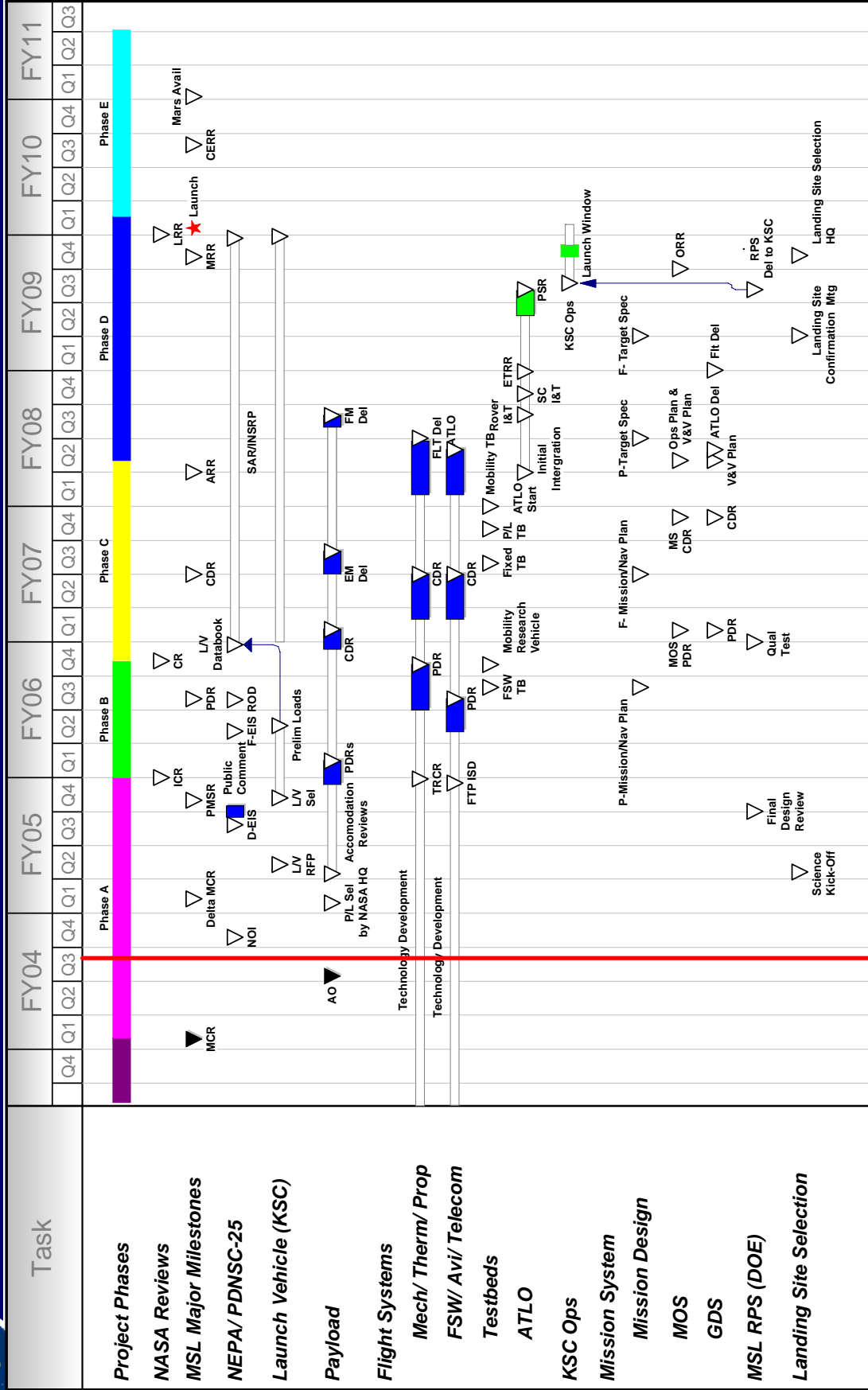
Next generation in-situ science investigations – To be acquired during FY'04 / FY'05

Remote sensing/contact investigations - To be acquired during FY'04 / FY'05



Mars Science Laboratory Top Level Schedule (Single Launch)

Predecisional Draft



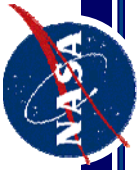
4/14/2007

Work Activity

Dependencies

Margin

Subsystem Reviews Milestones
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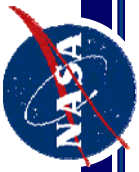
EDL Challenges

Desires

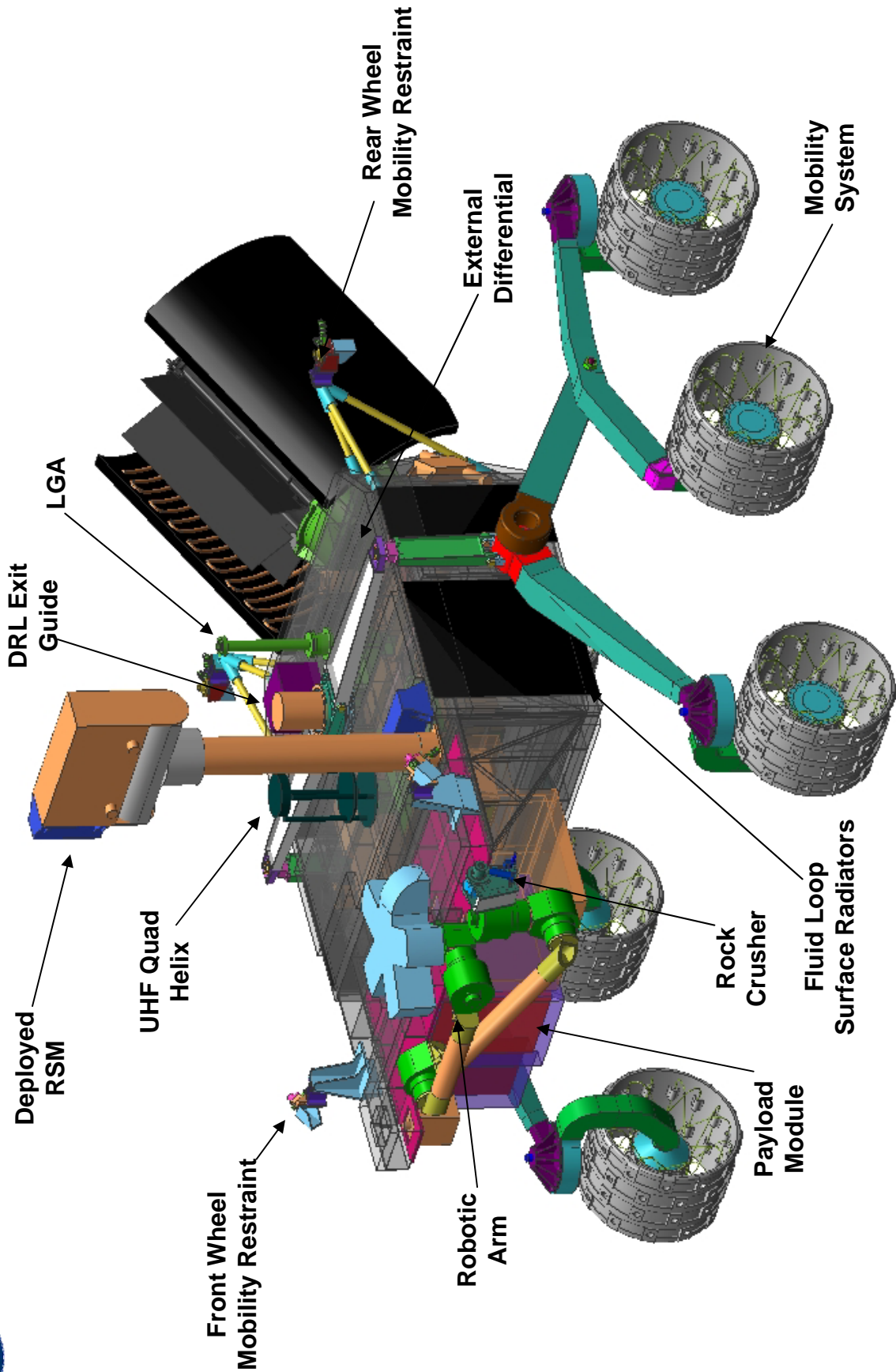
- Significantly larger landed payload
 - Mass: 550 kg max
- Global access to Mars
 - Up to +2.5 km (MOLA)
 - Broad latitude range
- Smaller landing ellipse
 - ~ 20 km major axis
- EDL communication coverage
- Generalize EDL for future missions

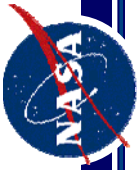
Realities

- Each EDL design is somehow different
 - Different mission design
 - Entry velocity
 - The Martian atmosphere is different at each opportunity
 - Due to atmospheric pressure cycle
 - Different landing site
- Many uncertainties associated with the atmosphere
- EDL design is highly coupled
- EDL communication requirements introduce many constraints and variables

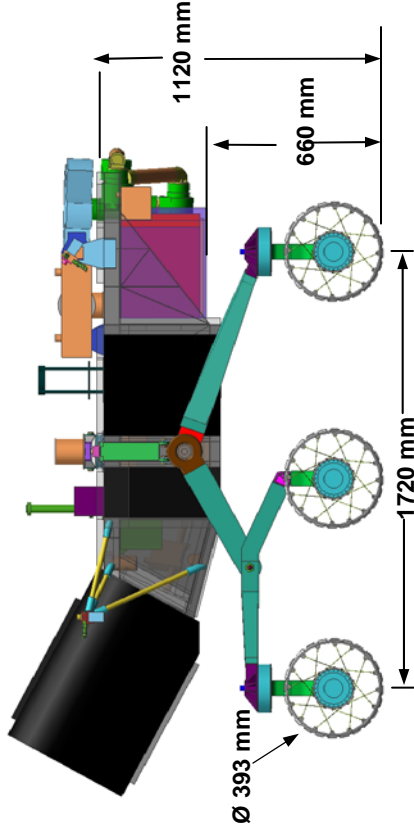


MSL Surface System

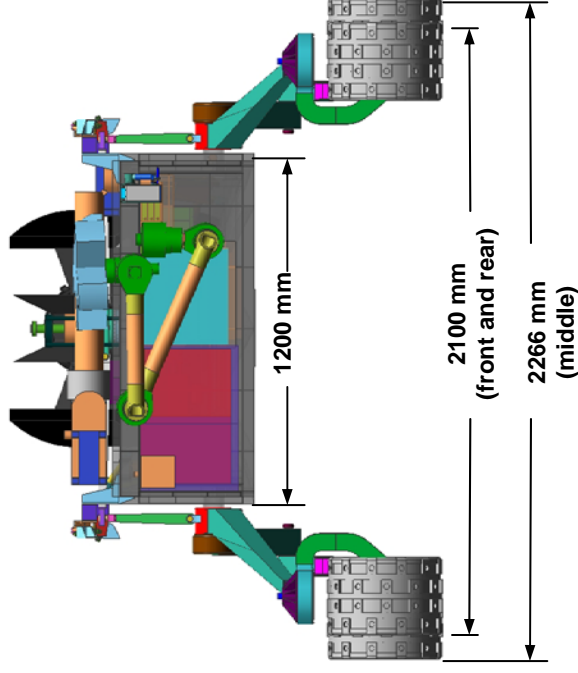


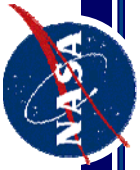


MSL Surface System



- Current Mobility Details:
 - Wheels – 393 mm dia
 - Ground clearance – 660 mm static
 - Wheel base – 1720 mm
 - Track – 2100 mm
 - Middle Wheel is located 83 mm outside of front and rear wheels





Mars Rover Wheel Family Tree

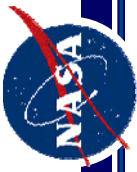
Mars Science Laboratory

MSL: ø400 mm

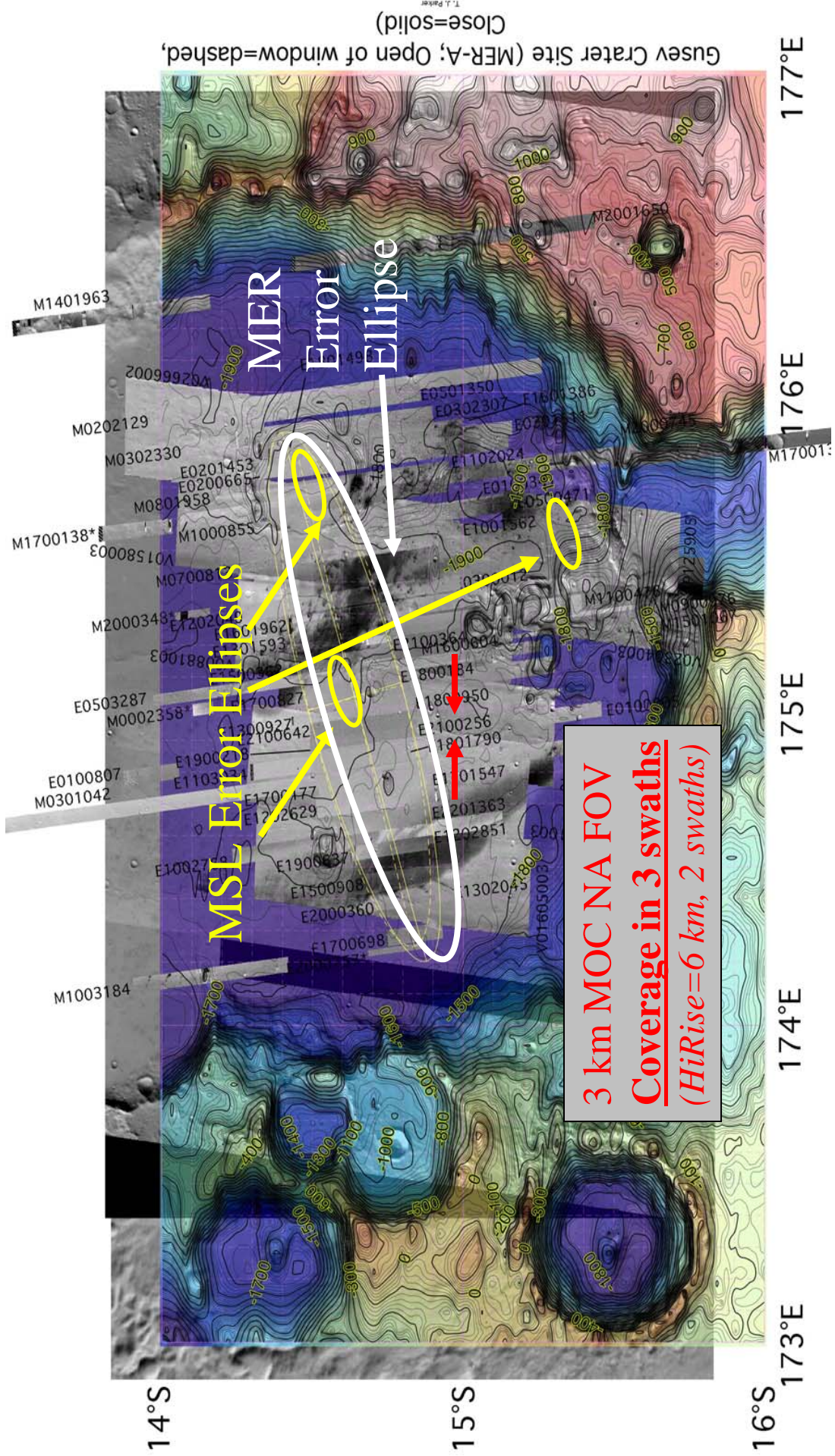
MER: ø250 mm

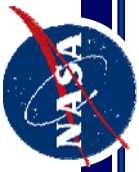
MPF: ø127 mm





Gusev Comparisons

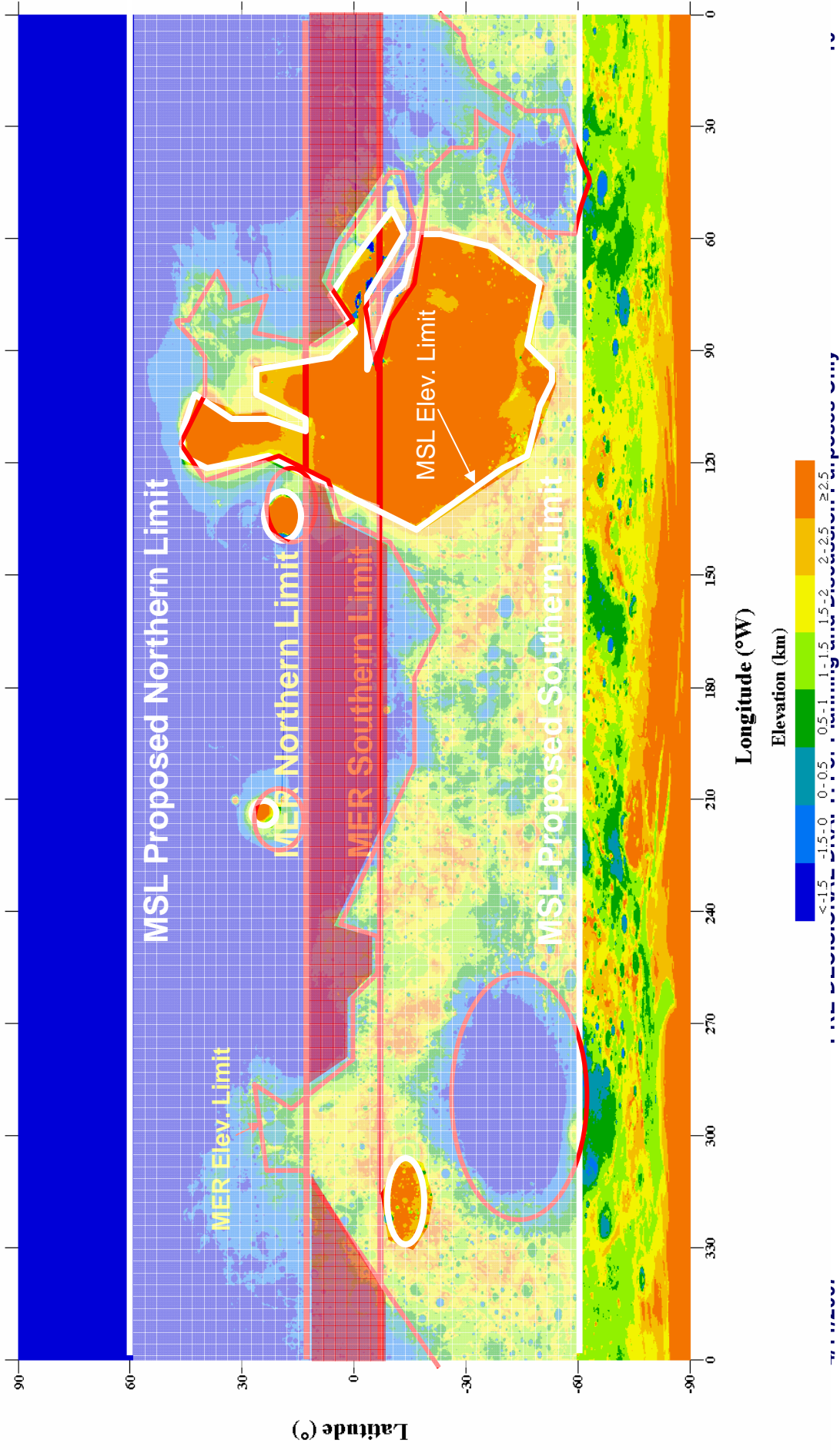




Mars Surface Accessibility

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MOLA 1/4° Gridded Topography



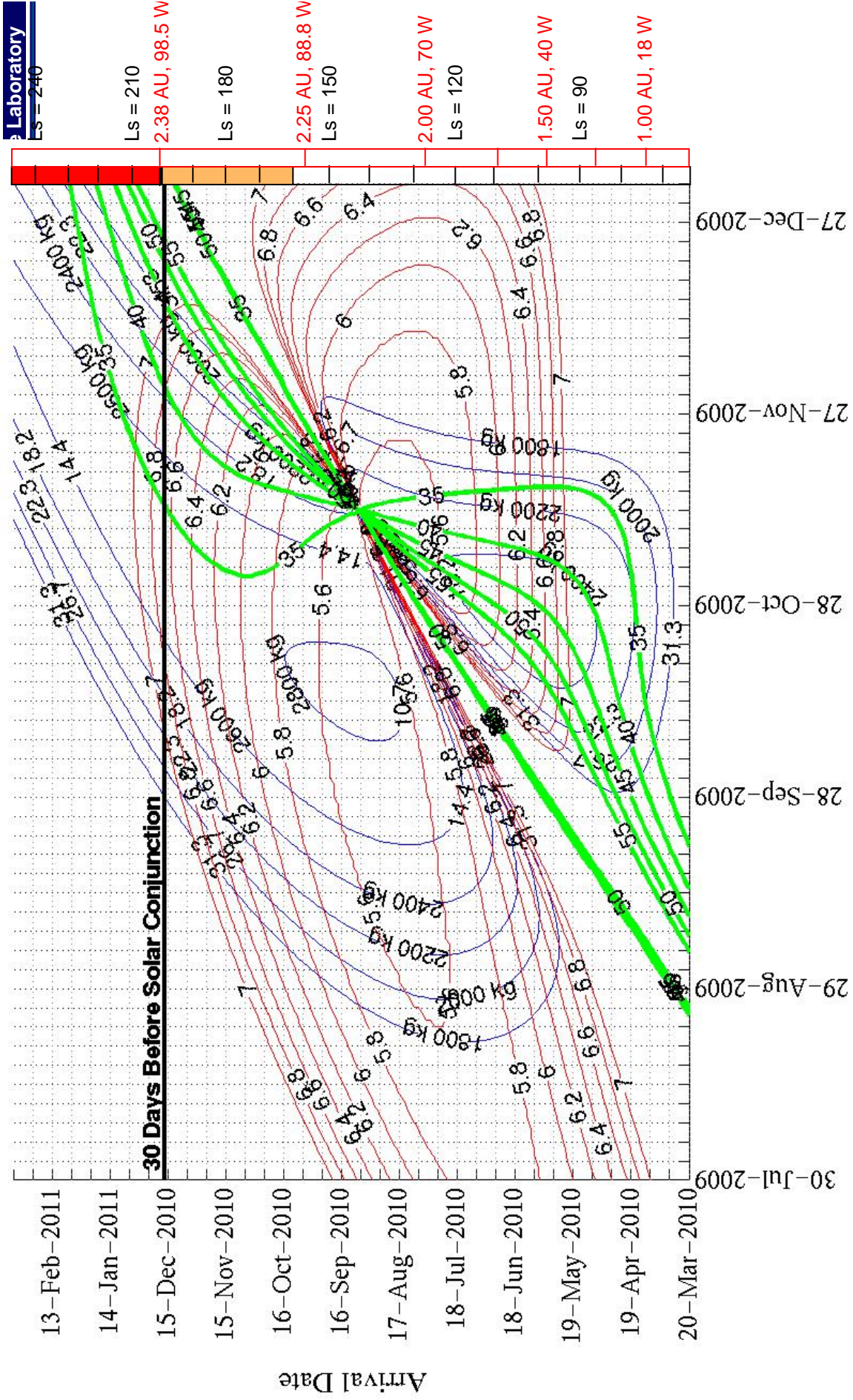
Atlas V 401 Launch Performance (C3:

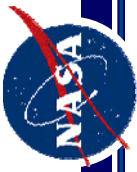


Planet-encircling dust storms

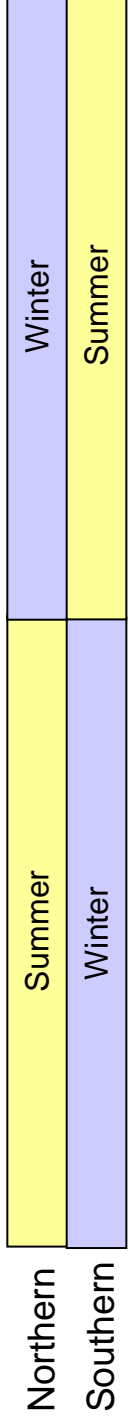
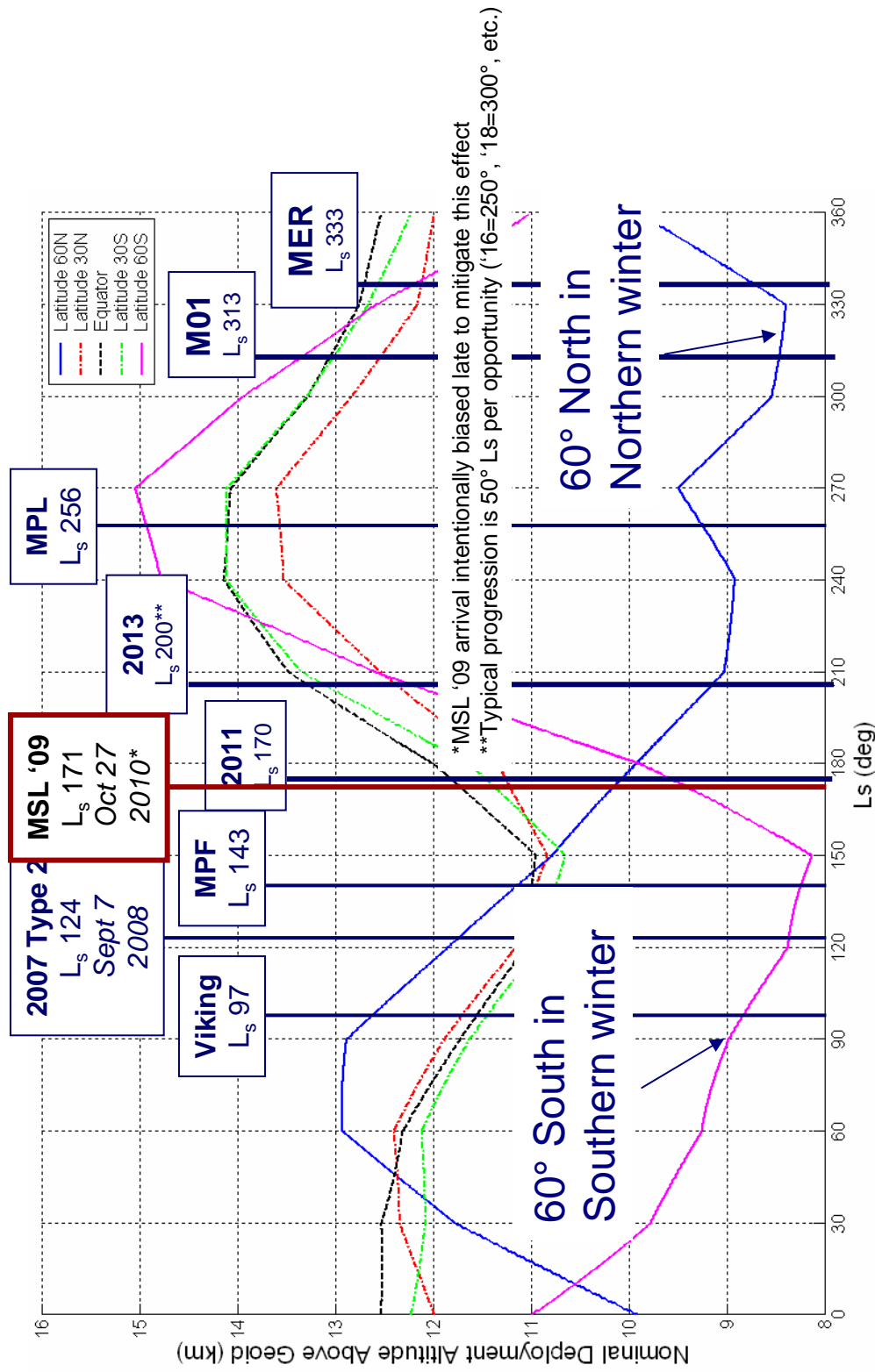
blue Regional dust storms
red Mars list, AU, & Xtr RF pwr, W, 60° ant angle constraint
DLA: green

Earth 7 Mars list, AU, & Xtr RF pwr, W, 60° ant angle constraint

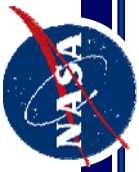




Parachute Deployment Altitude Variation with Time of Year and Latitude



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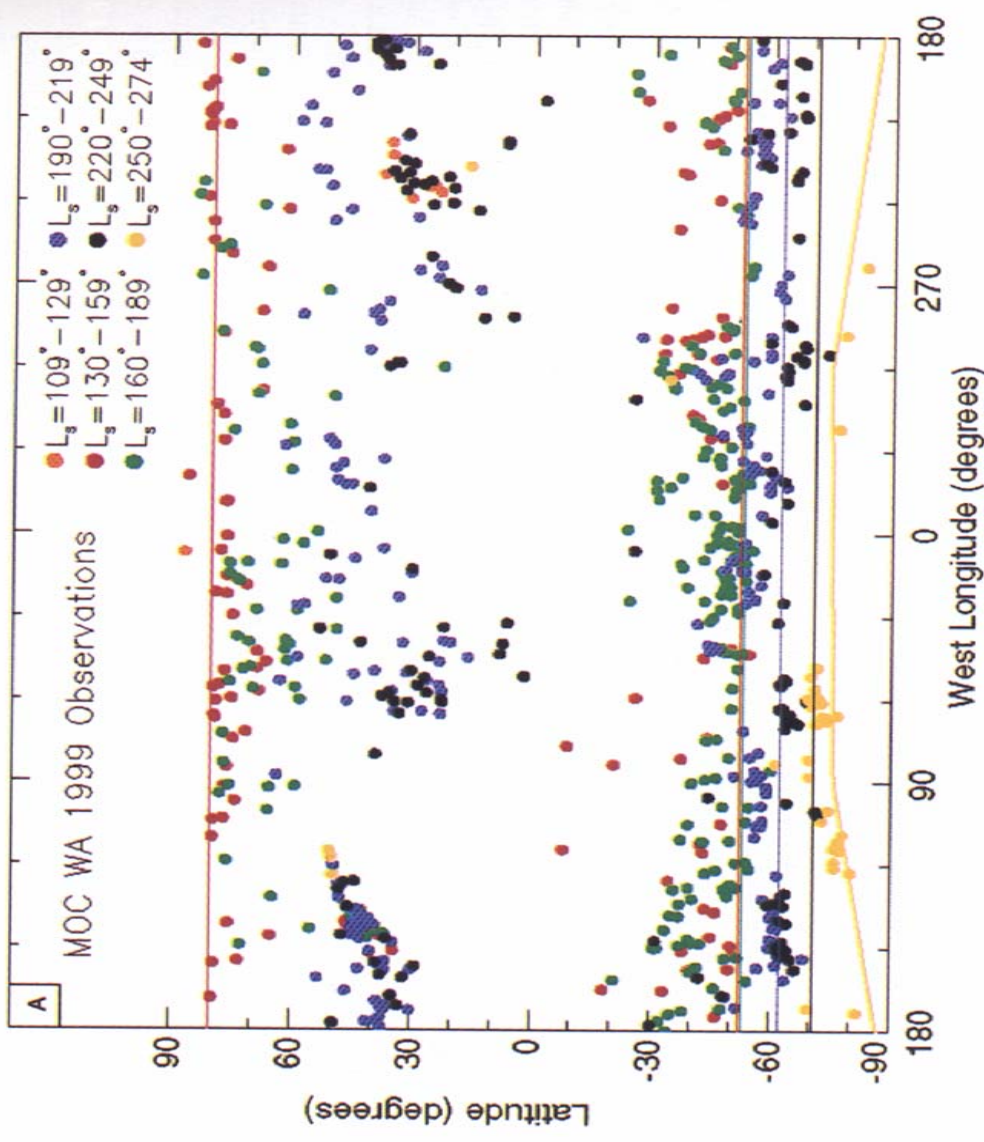


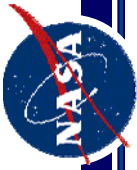
Dust Storms and Winds

- Increased dust (higher dust tau) reduces landing altitude capability
 - Higher atmospheric temperatures
 - Pushes column of air “up”
 - Results in higher chute deployment floor, reduced capability
 - Dust tau nominal range 0.1 – 0.9, 0.45 assumed to be typical
 - Designing to survive dust storm tau = 2.0

- Winds model based on MarsGRAM 2001 and Chia-Yen Peng dispersed wind model

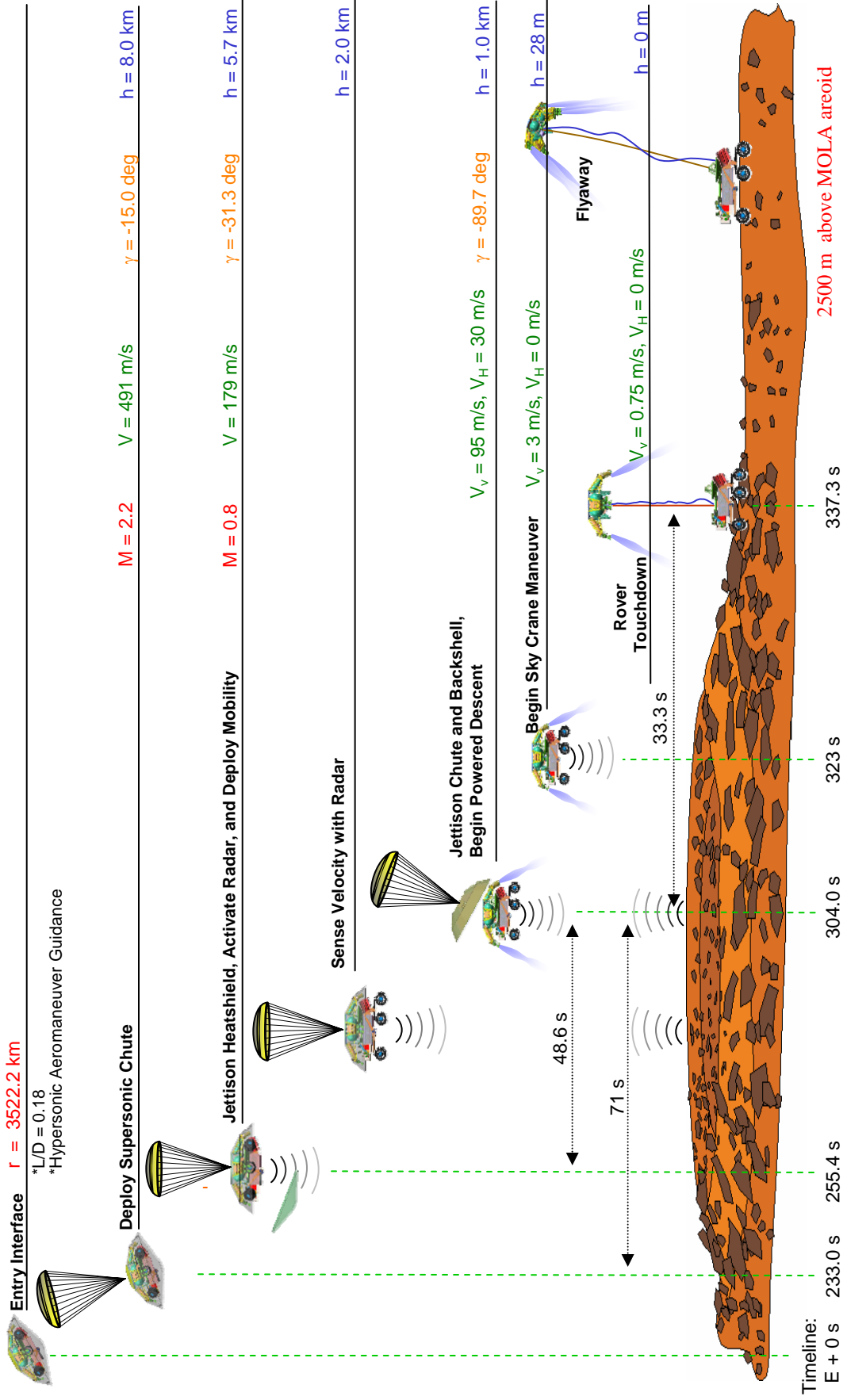
MSL Landing Season (green)

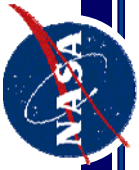




Nominal MSL EDL Timeline

Mach Velocity Flight Path Angle Altitude AGL





Specific EDL Challenges

- Entry
 - Aerothermal environment definition (i. e. TPS requirements)
 - TPS material selection and risk evaluation
 - Entry guidance reinvigoration, entry guidance last used on Viking
- Descent
 - Parachutes are never off the shelf
- Landing
 - Sky-crane lander is a new landing concept
 - Terminal Descent Sensor (landing radar)
 - Throttle-able propulsion system