



Kennedy Space Center, Space Shuttle Processing, and International Space Station Program Overview

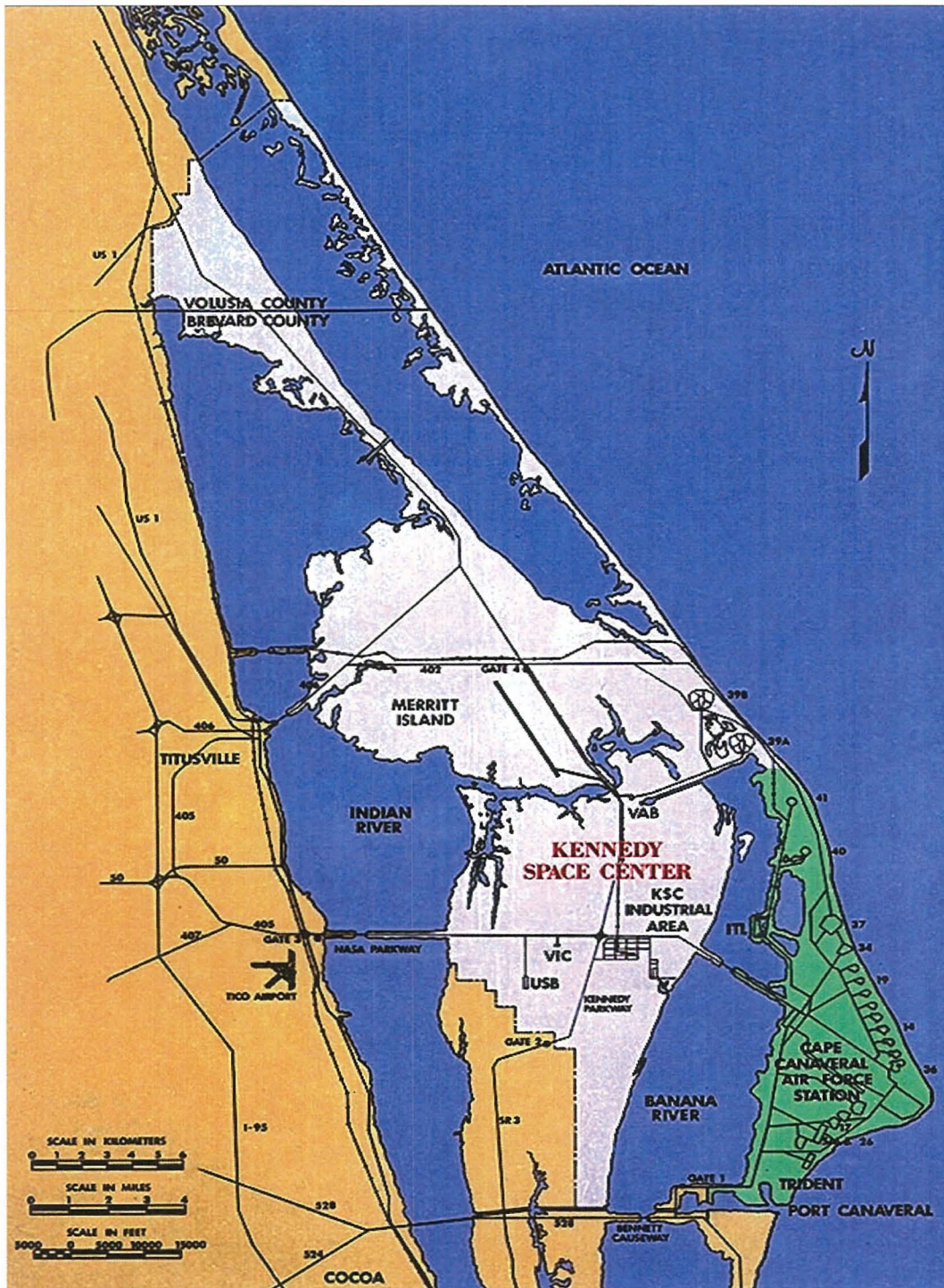
Scott Higginbotham

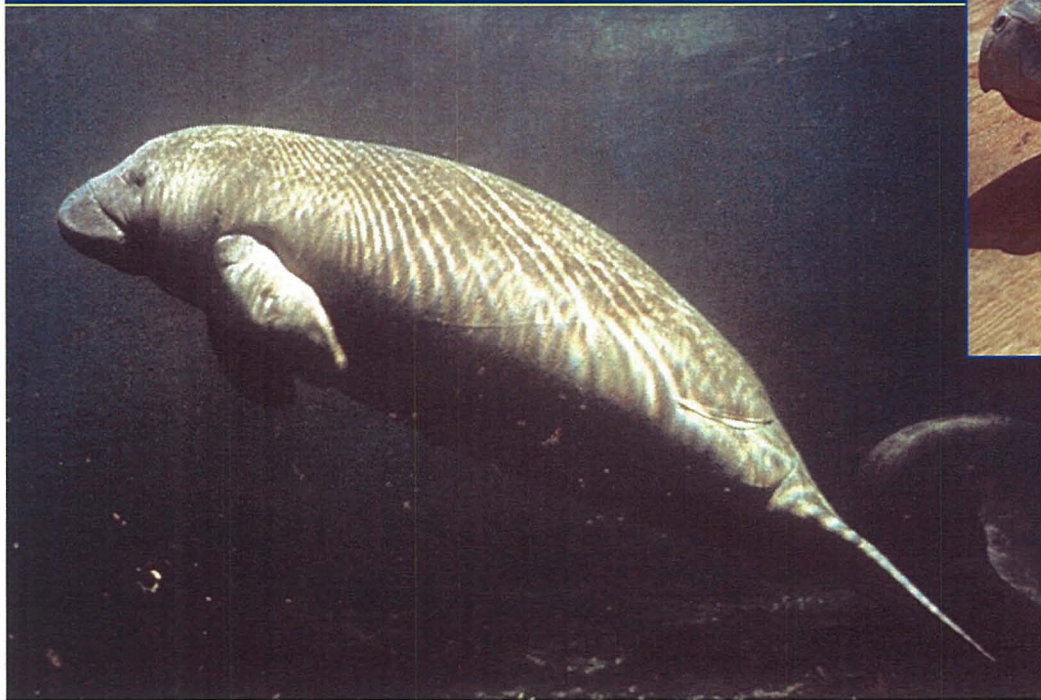
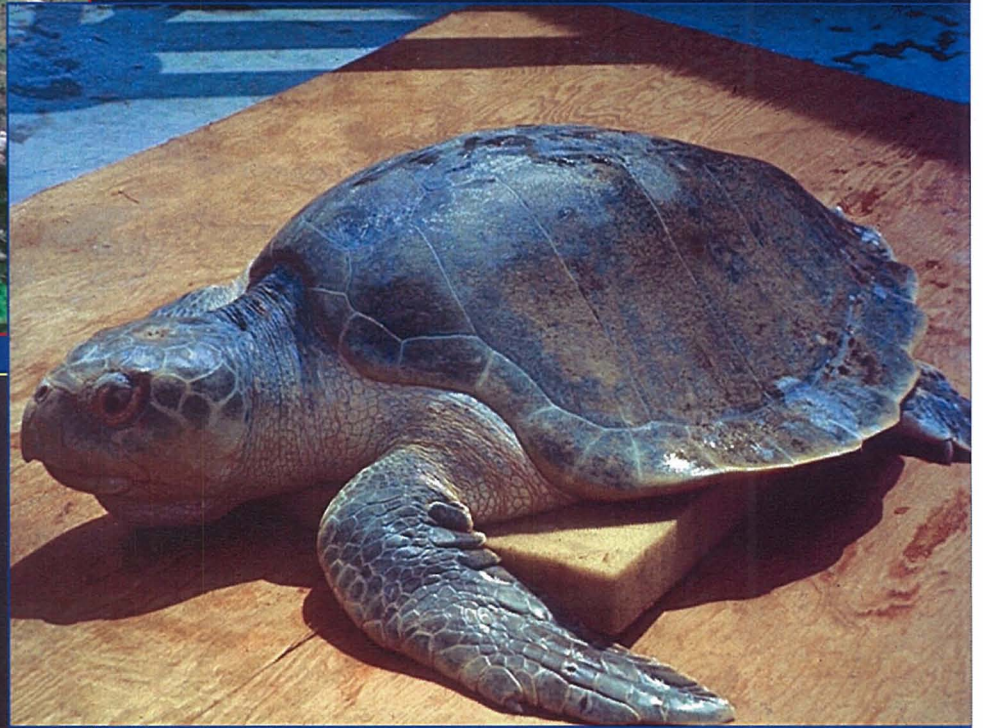
Mission Manager

International Space Station and Spacecraft Processing Directorate

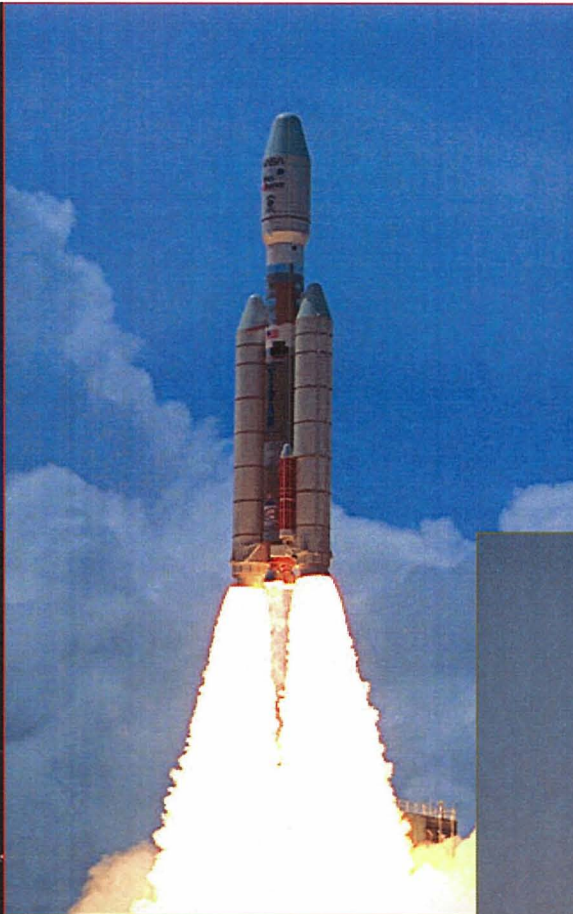
NASA – John F. Kennedy Space Center





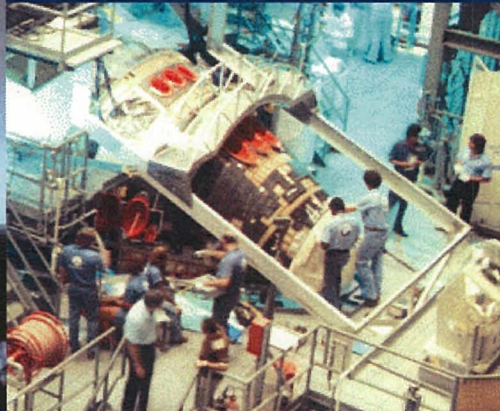






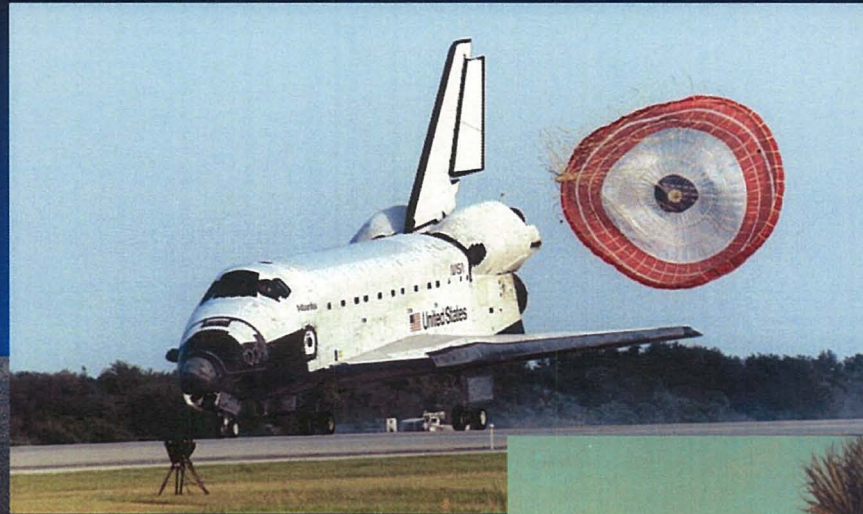
SPACE SHUTTLE GROUND OPERATIONS

Shuttle Processing



SPACE SHUTTLE GROUND OPERATIONS

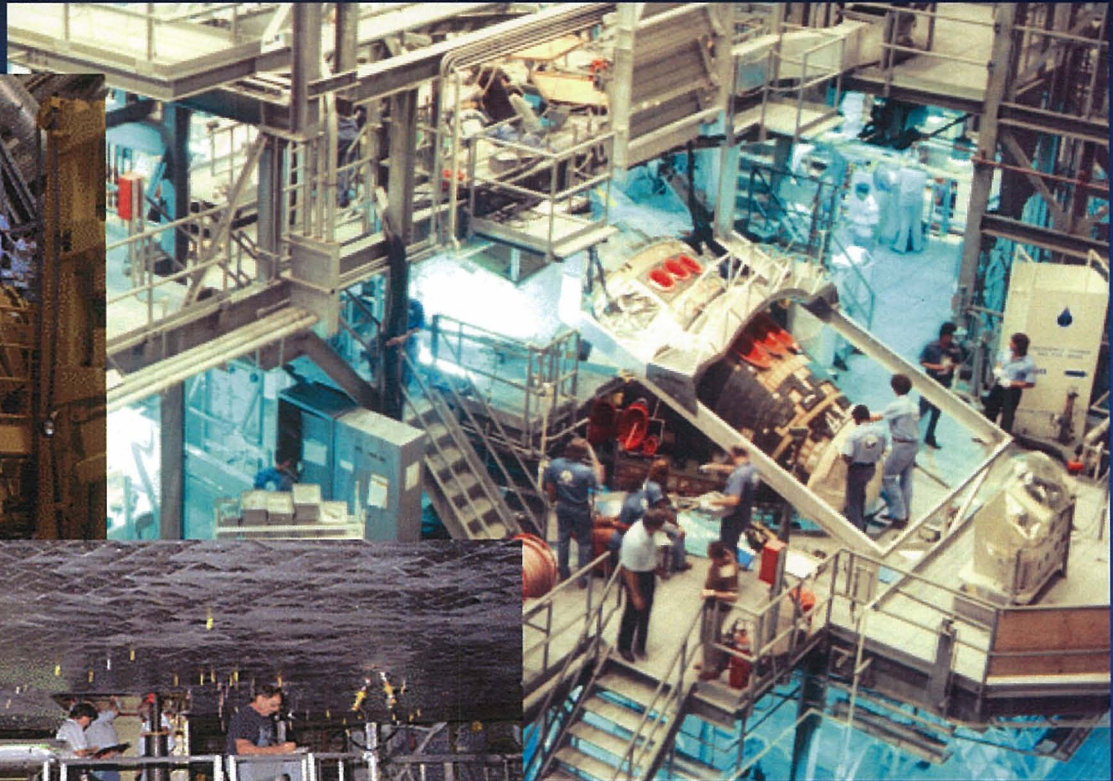
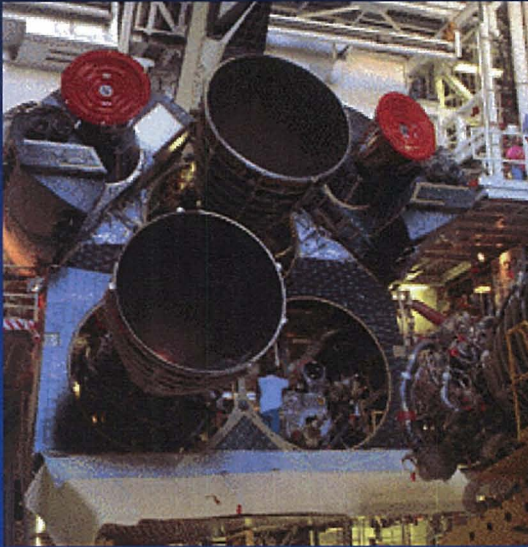
Shuttle Landing Facility (SLF)





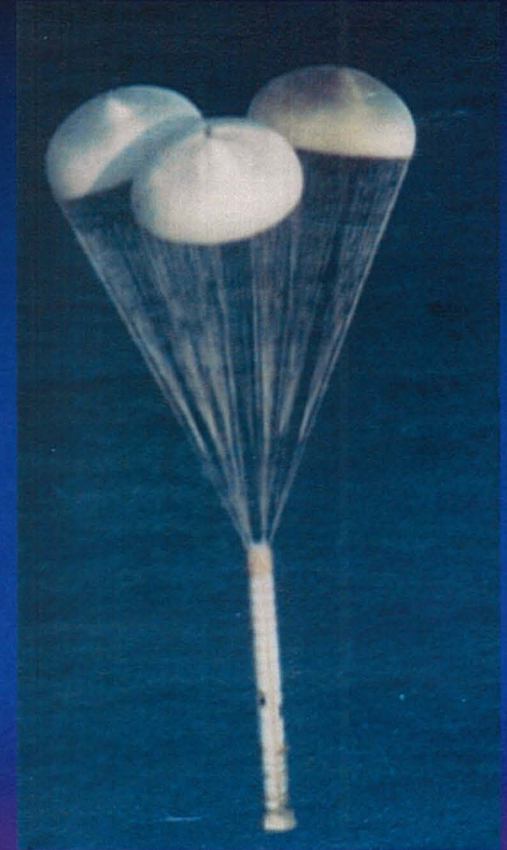
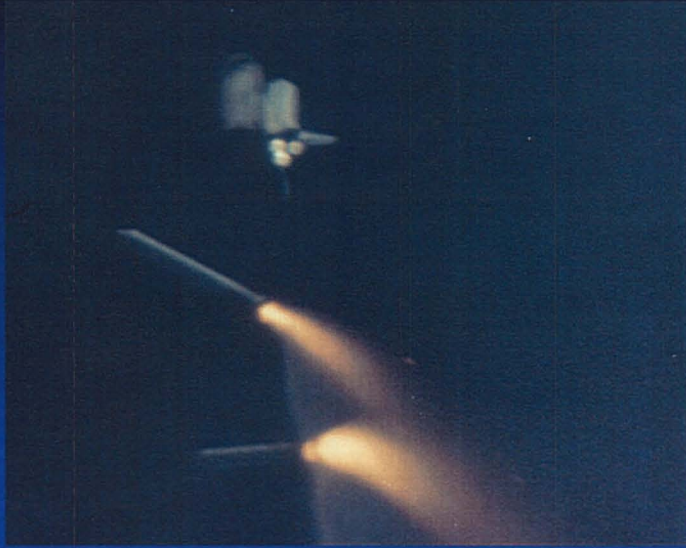
SPACE SHUTTLE GROUND OPERATIONS

OPF Operations



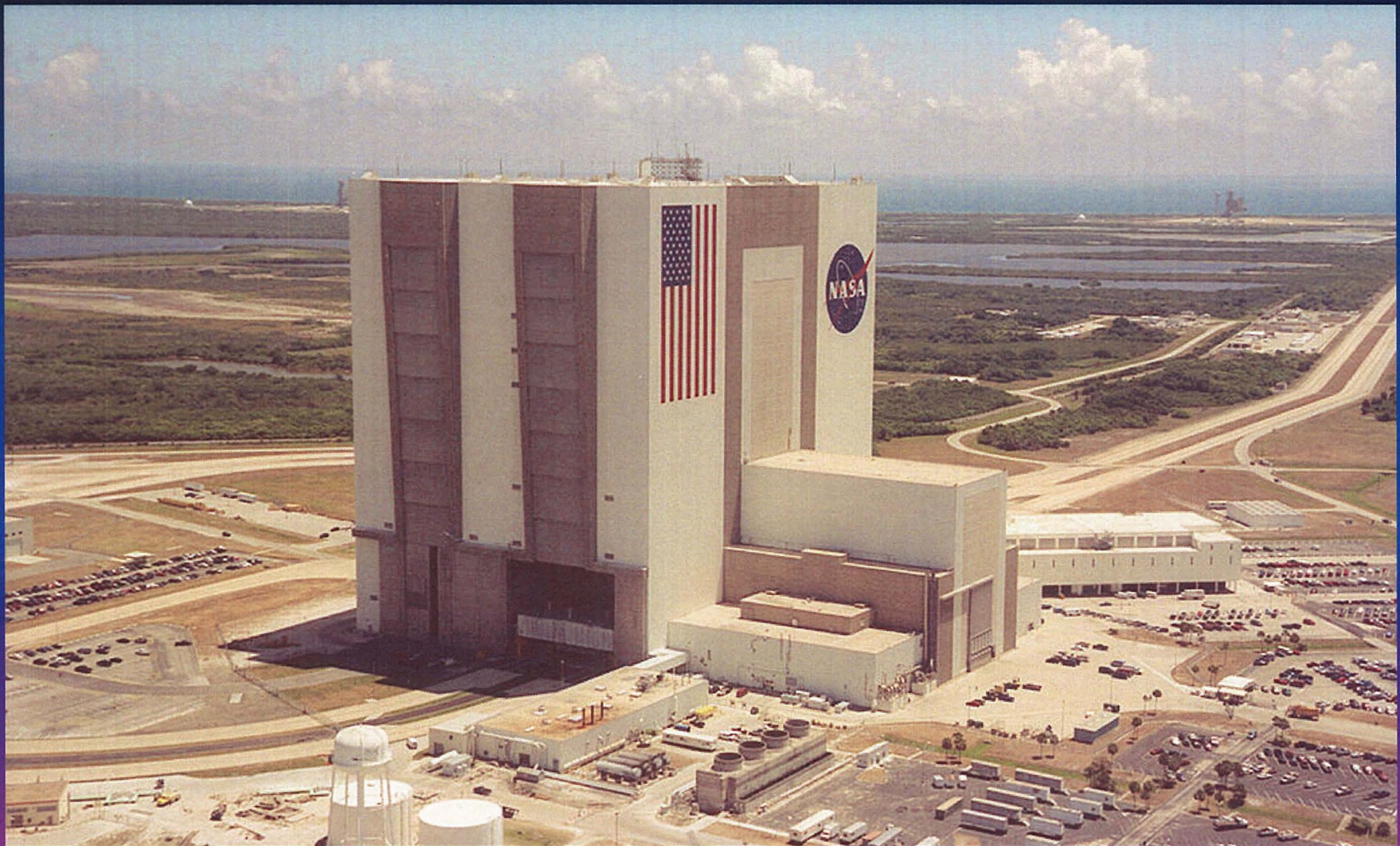
SPACE SHUTTLE GROUND OPERATIONS

SRB Recovery and Refurbishment



SPACE SHUTTLE GROUND OPERATIONS

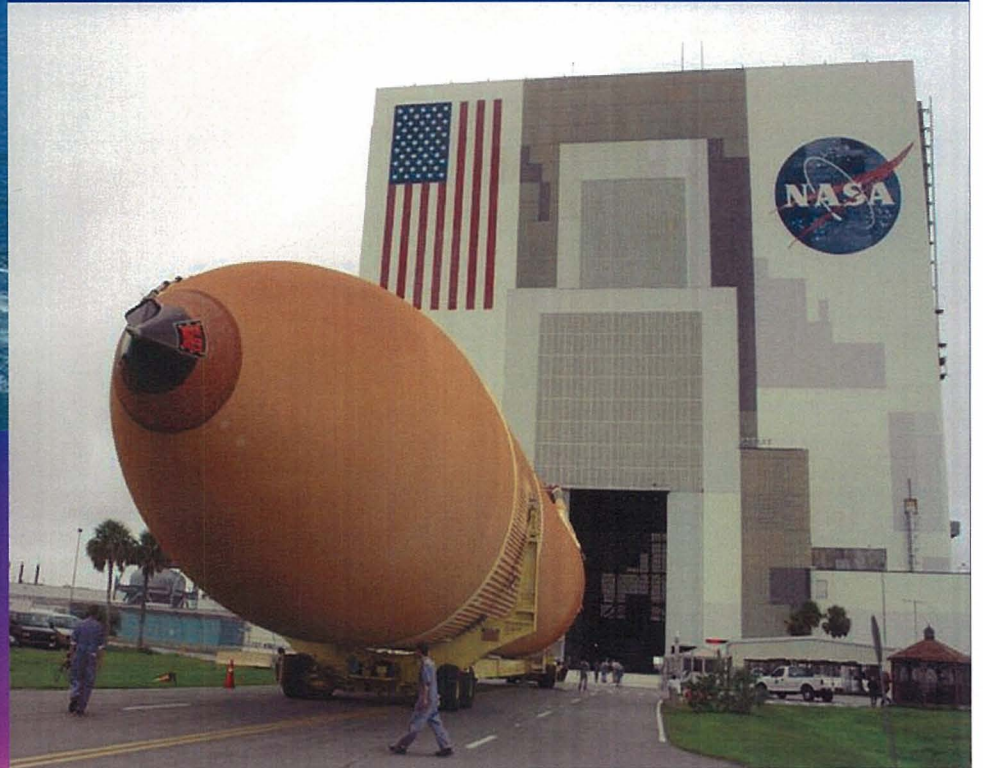
VAB Operations

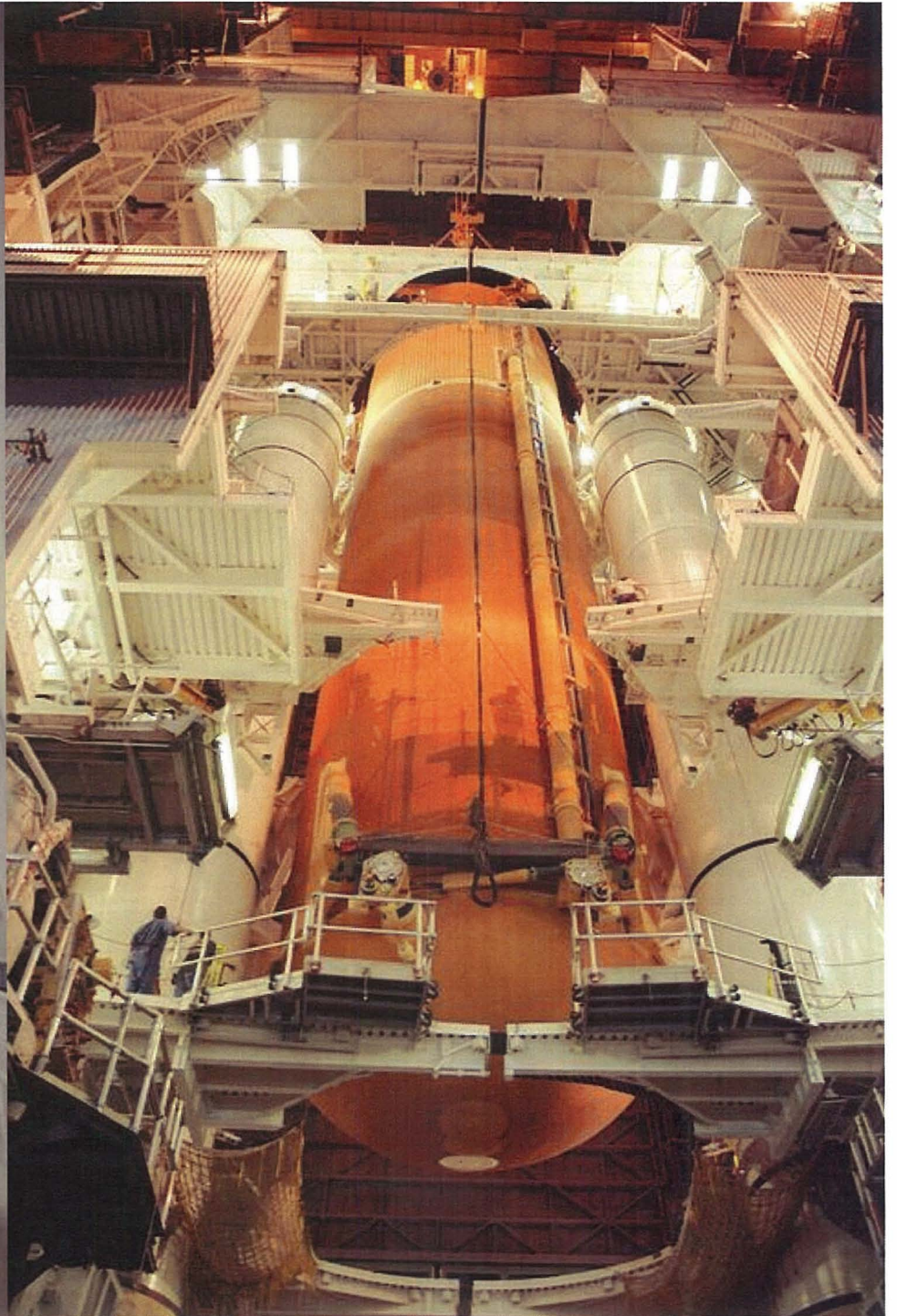
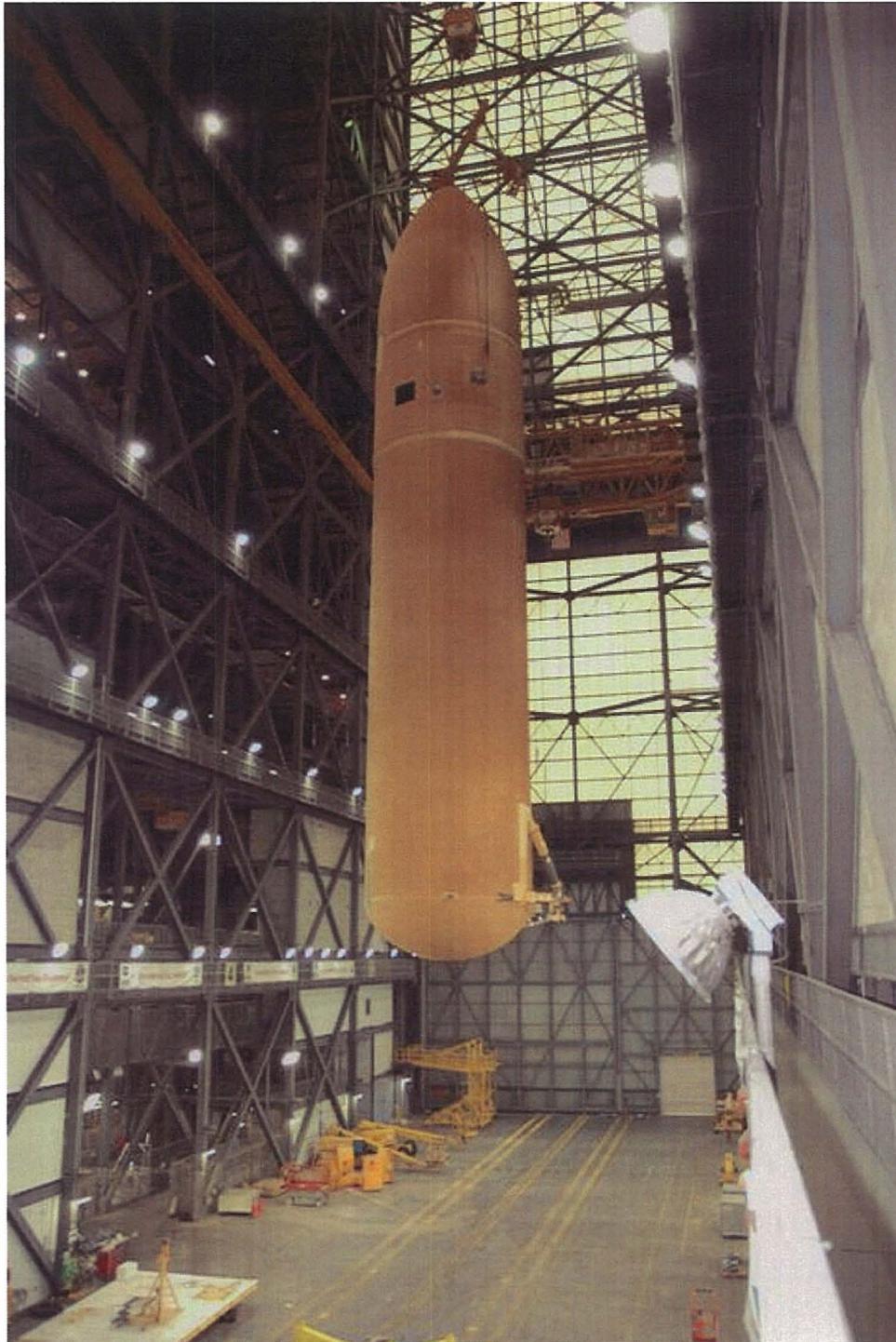




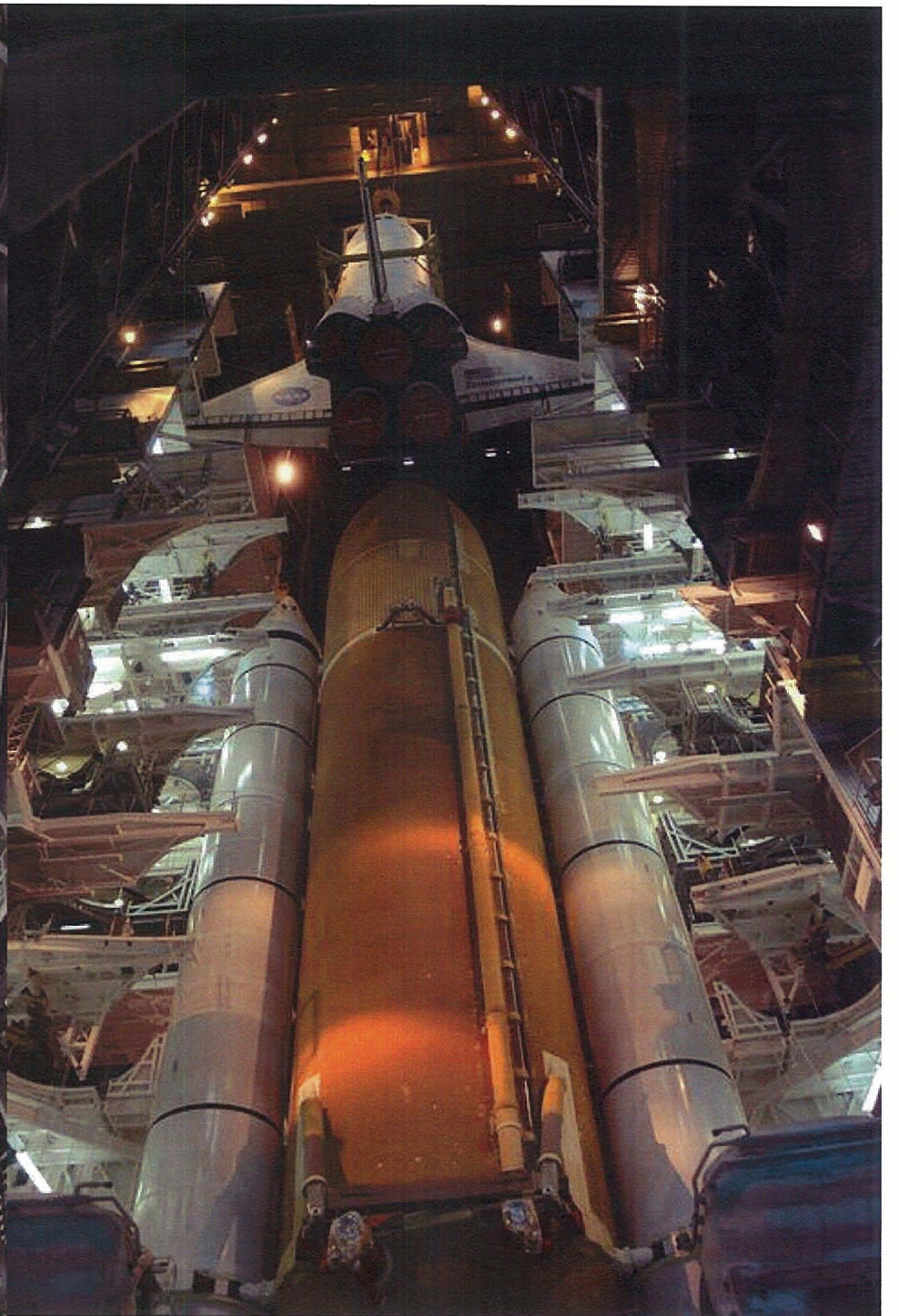
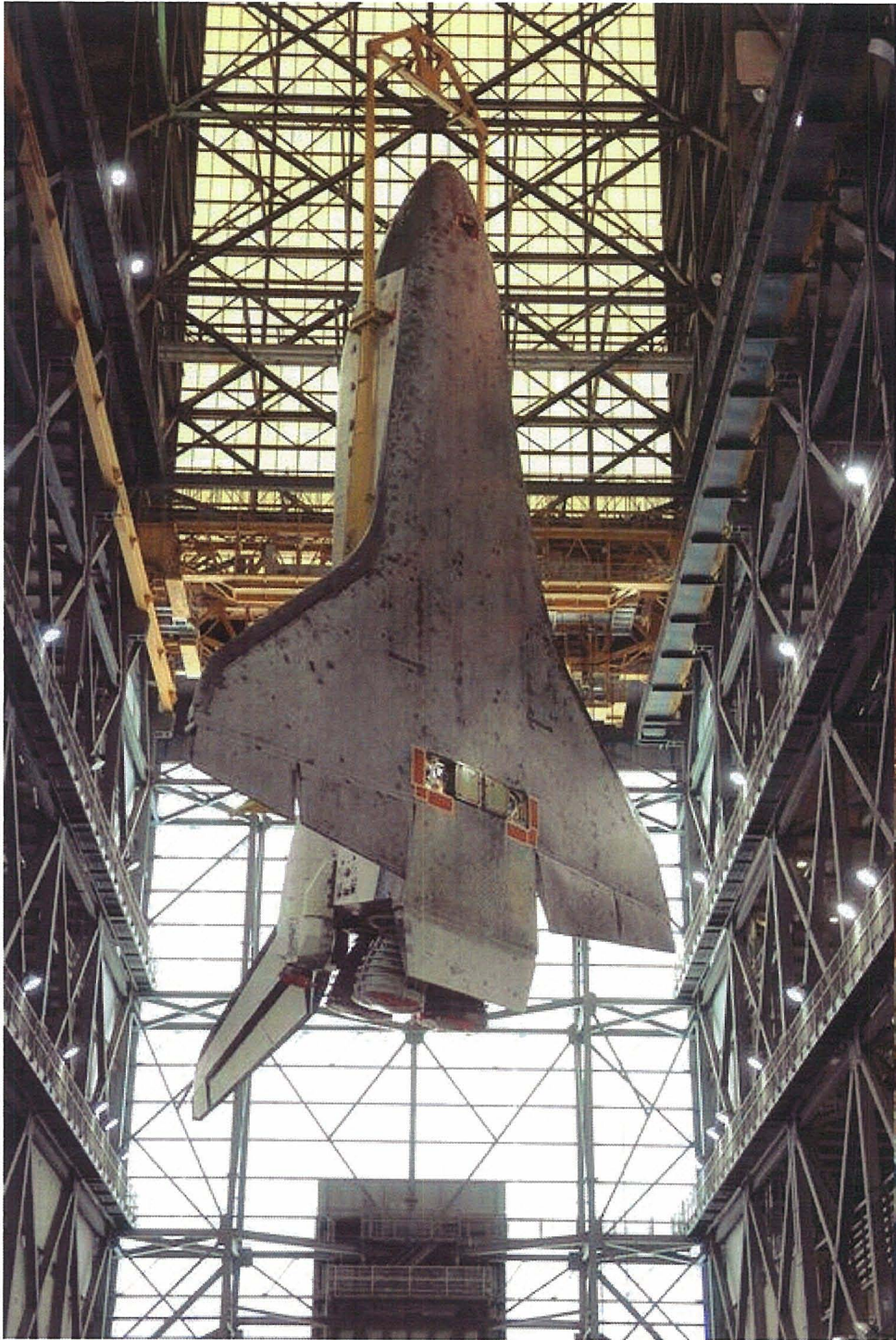
SPACE SHUTTLE GROUND OPERATIONS

External Tank



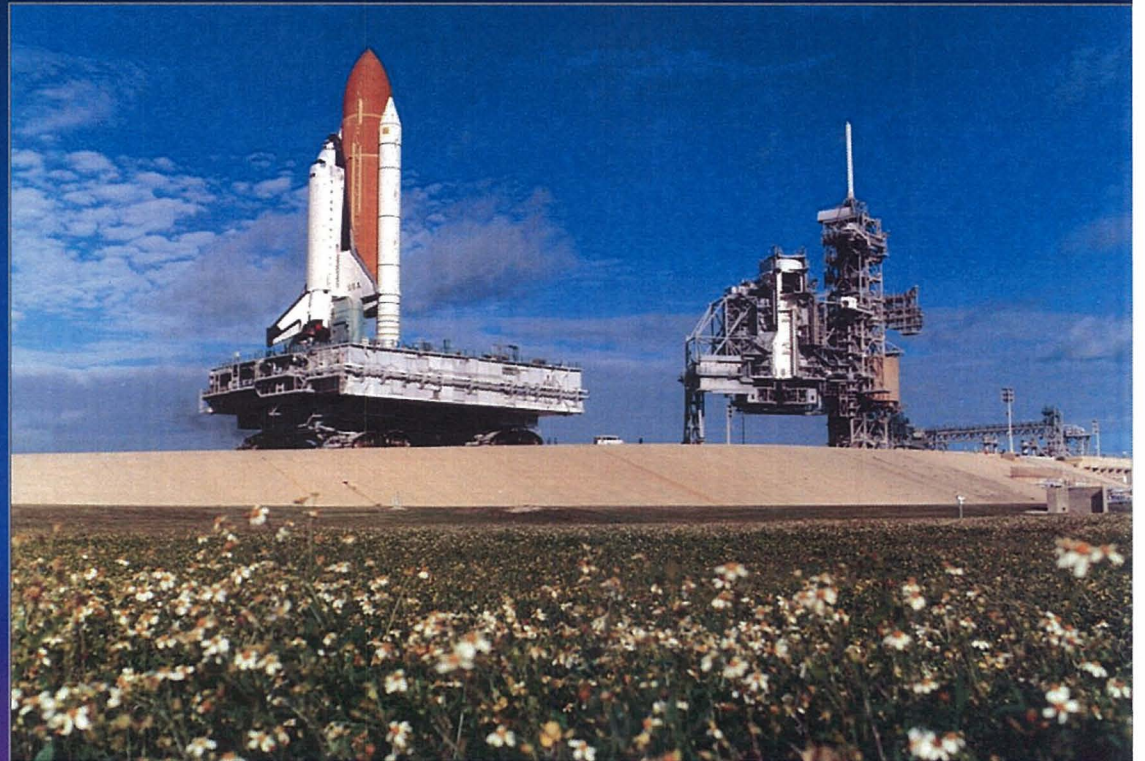
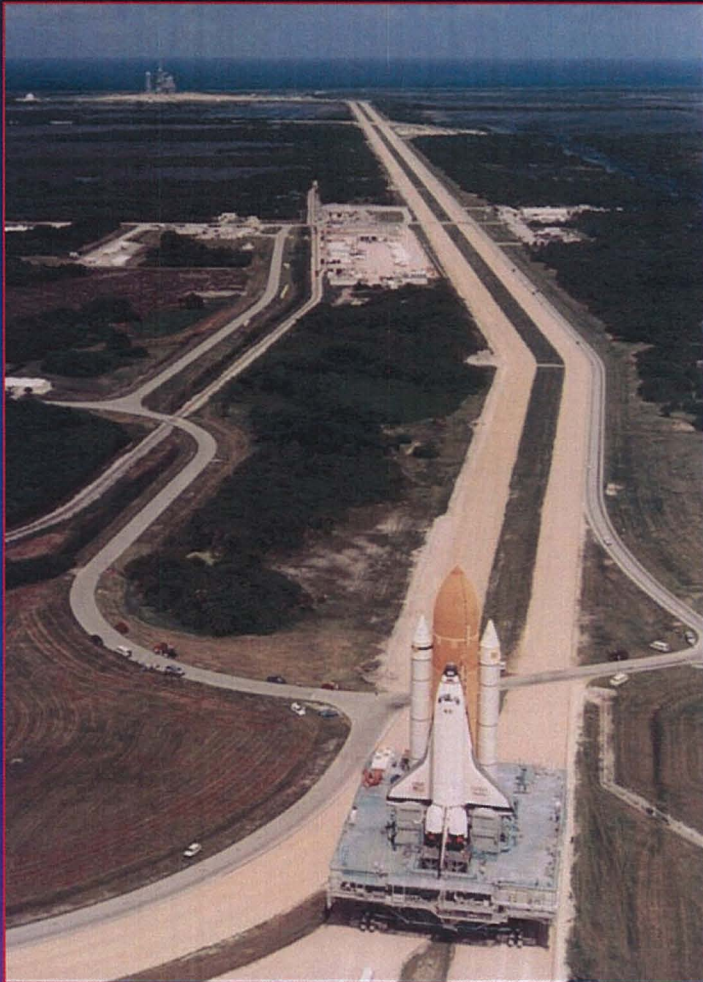






SPACE SHUTTLE GROUND OPERATIONS

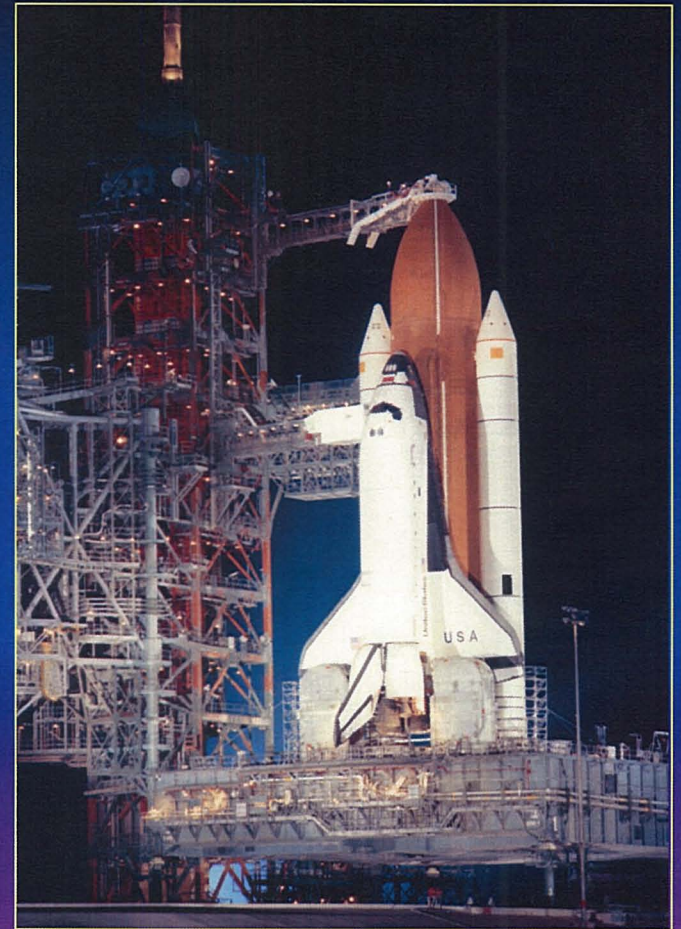
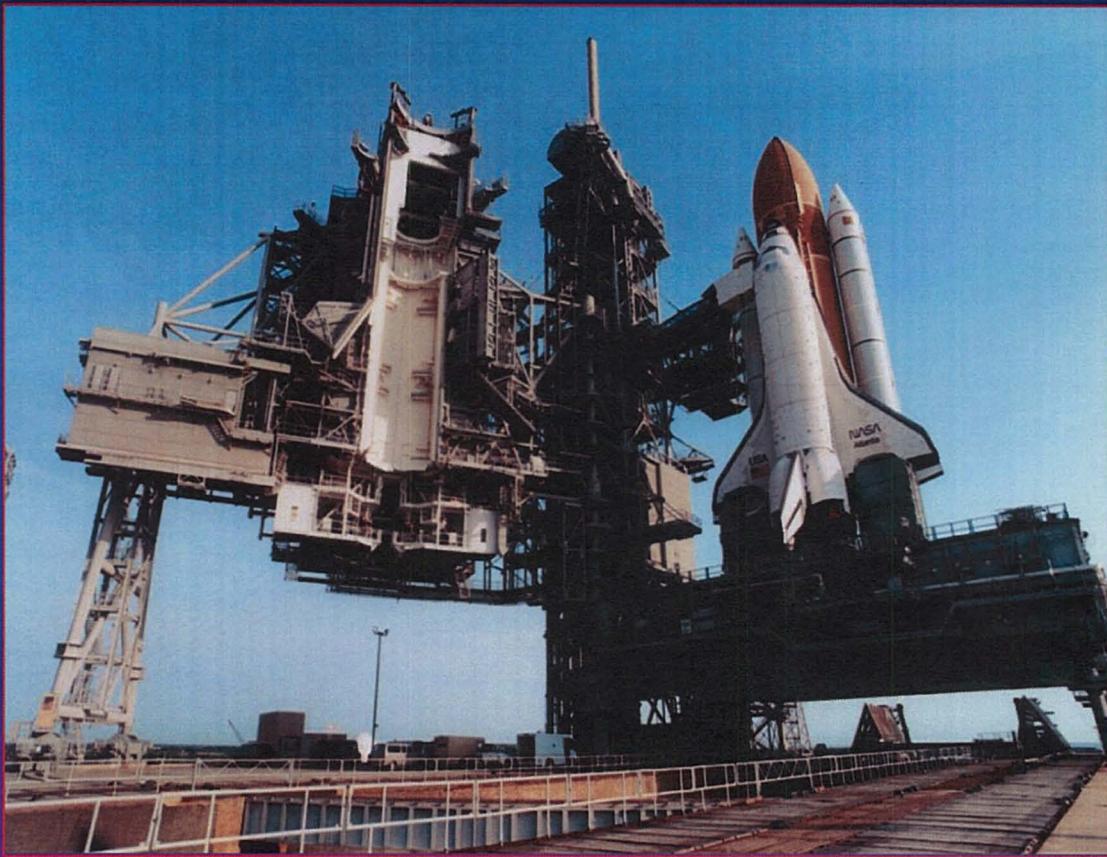
Rollout to Pad

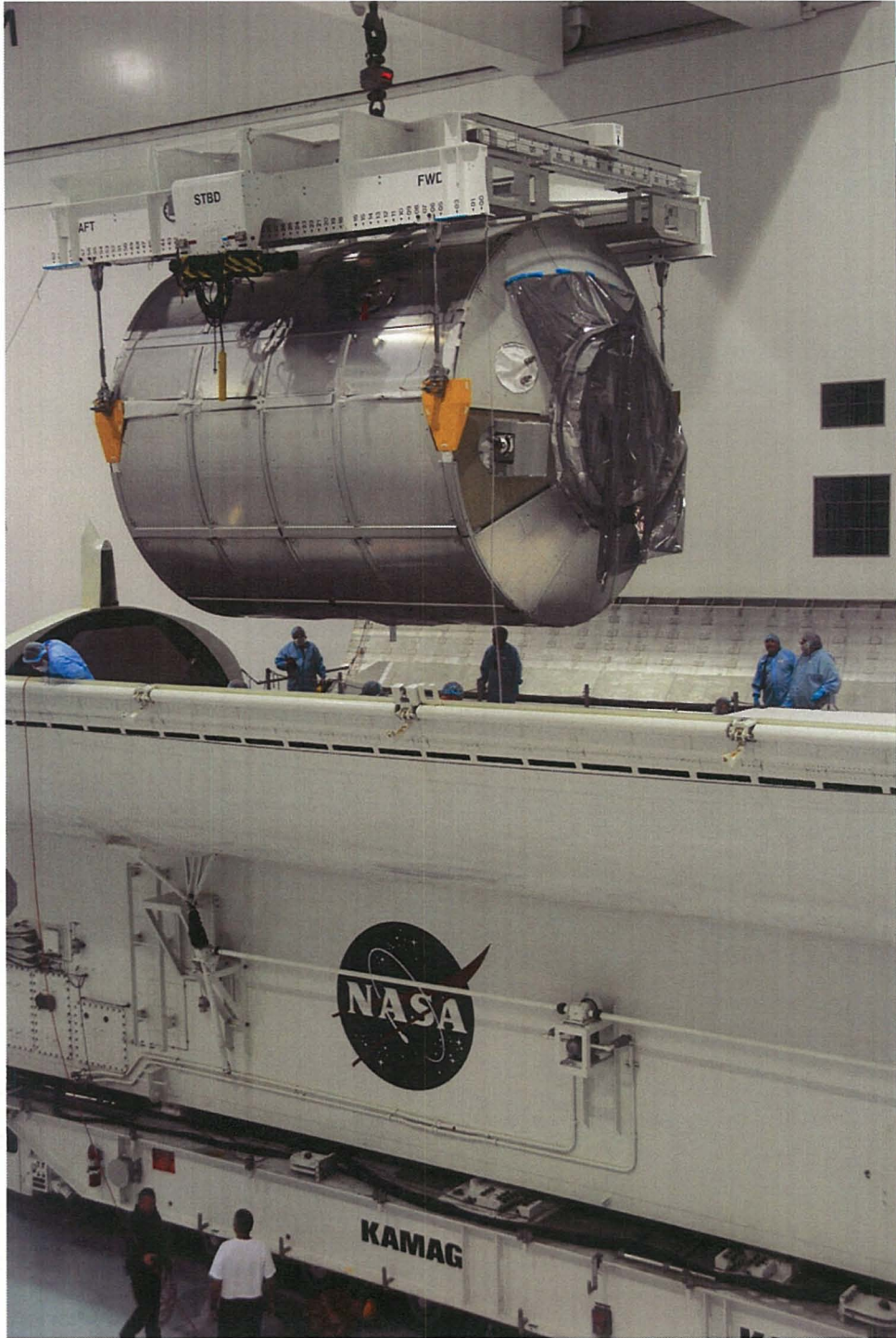


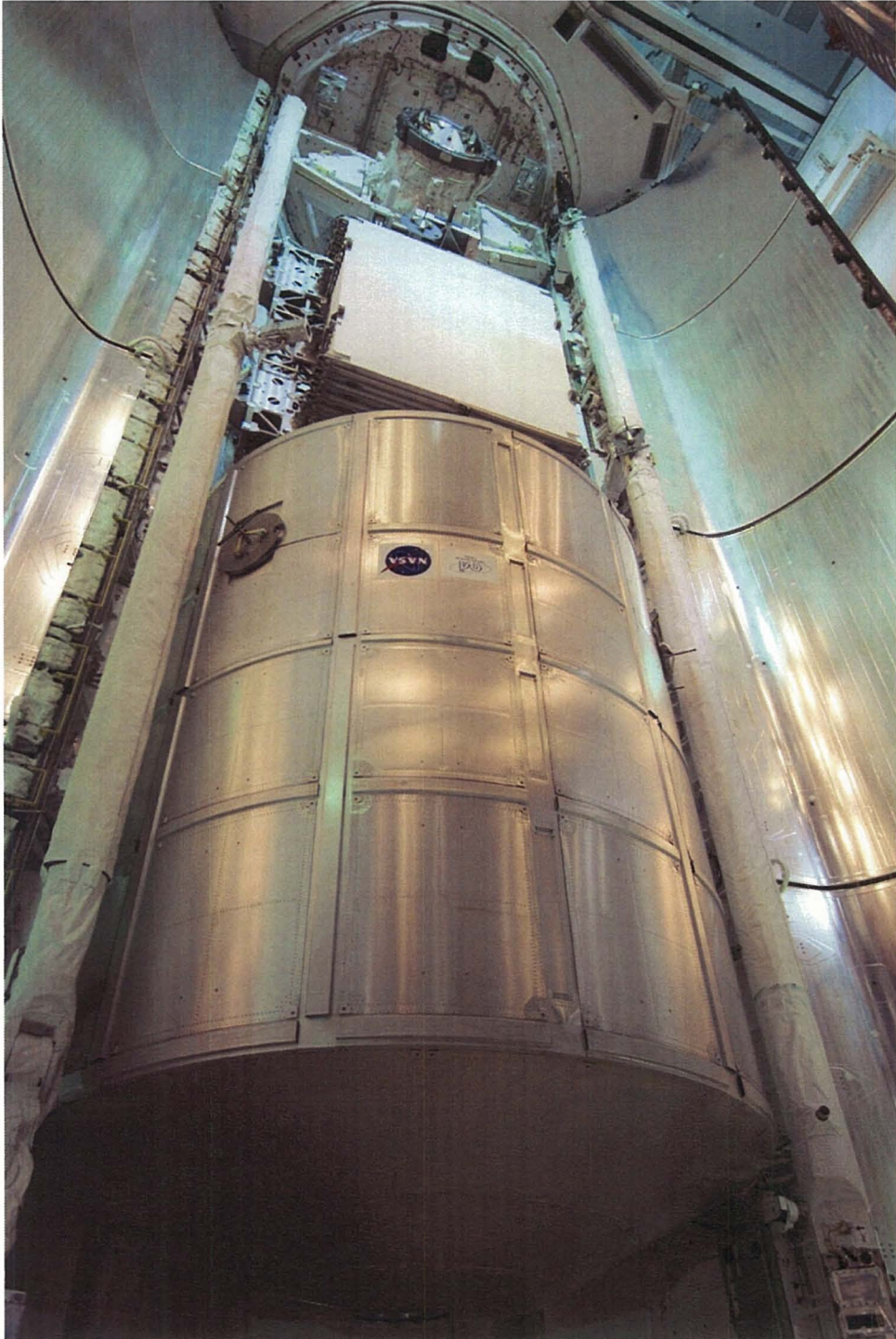


SPACE SHUTTLE GROUND OPERATIONS

Launch Pad

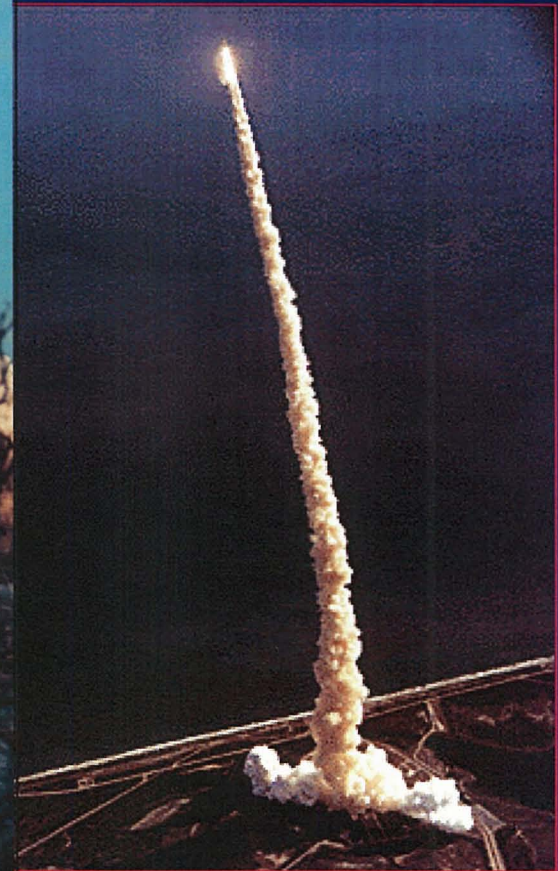
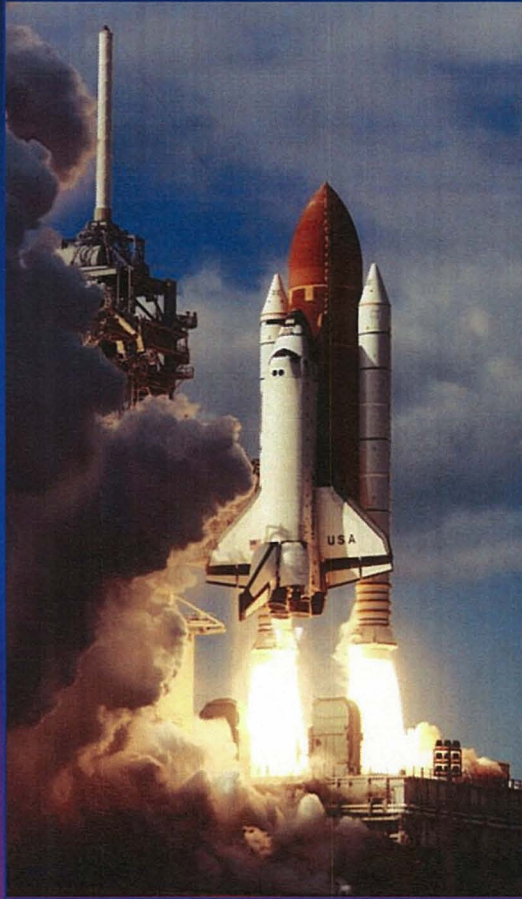


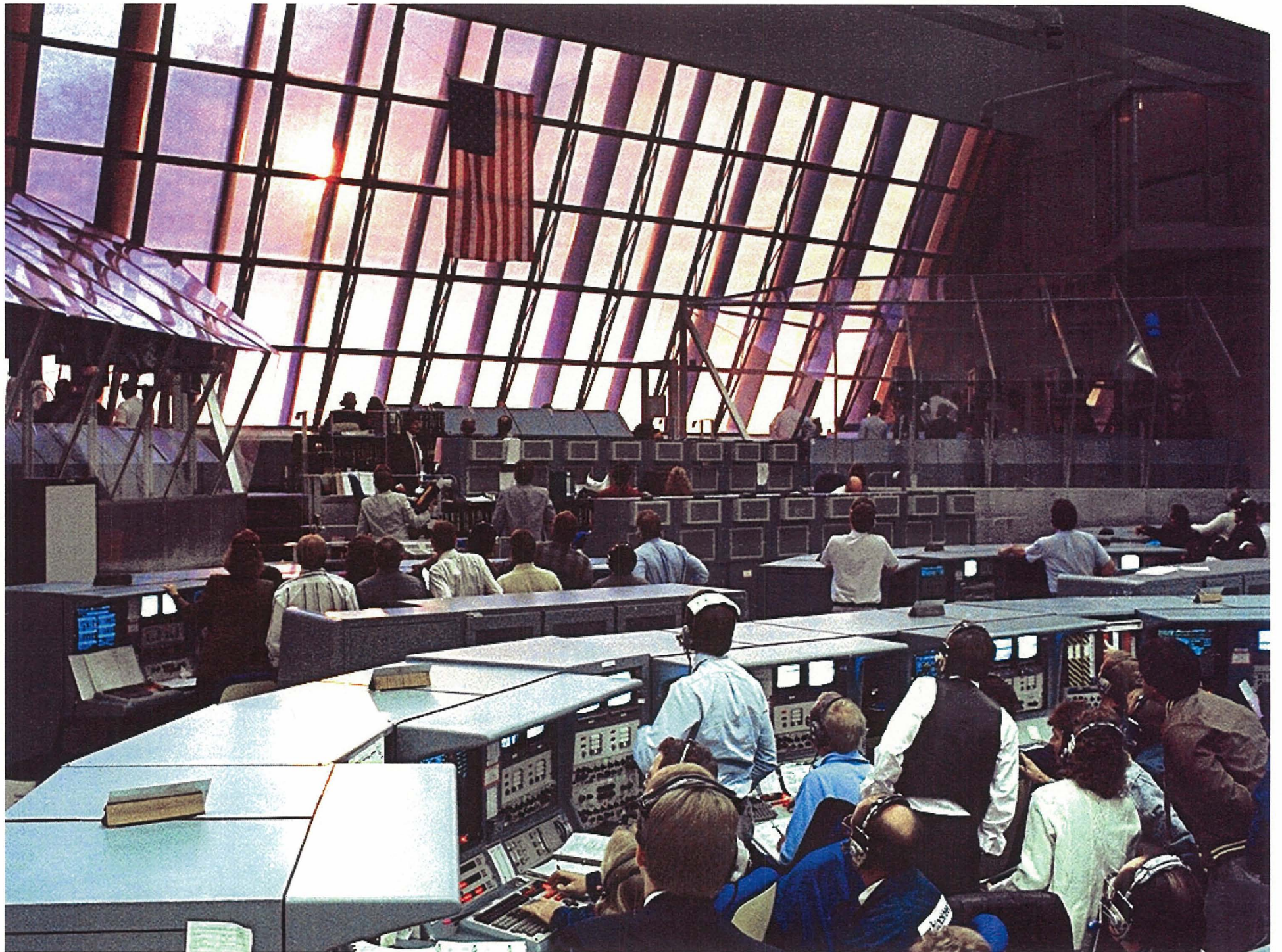


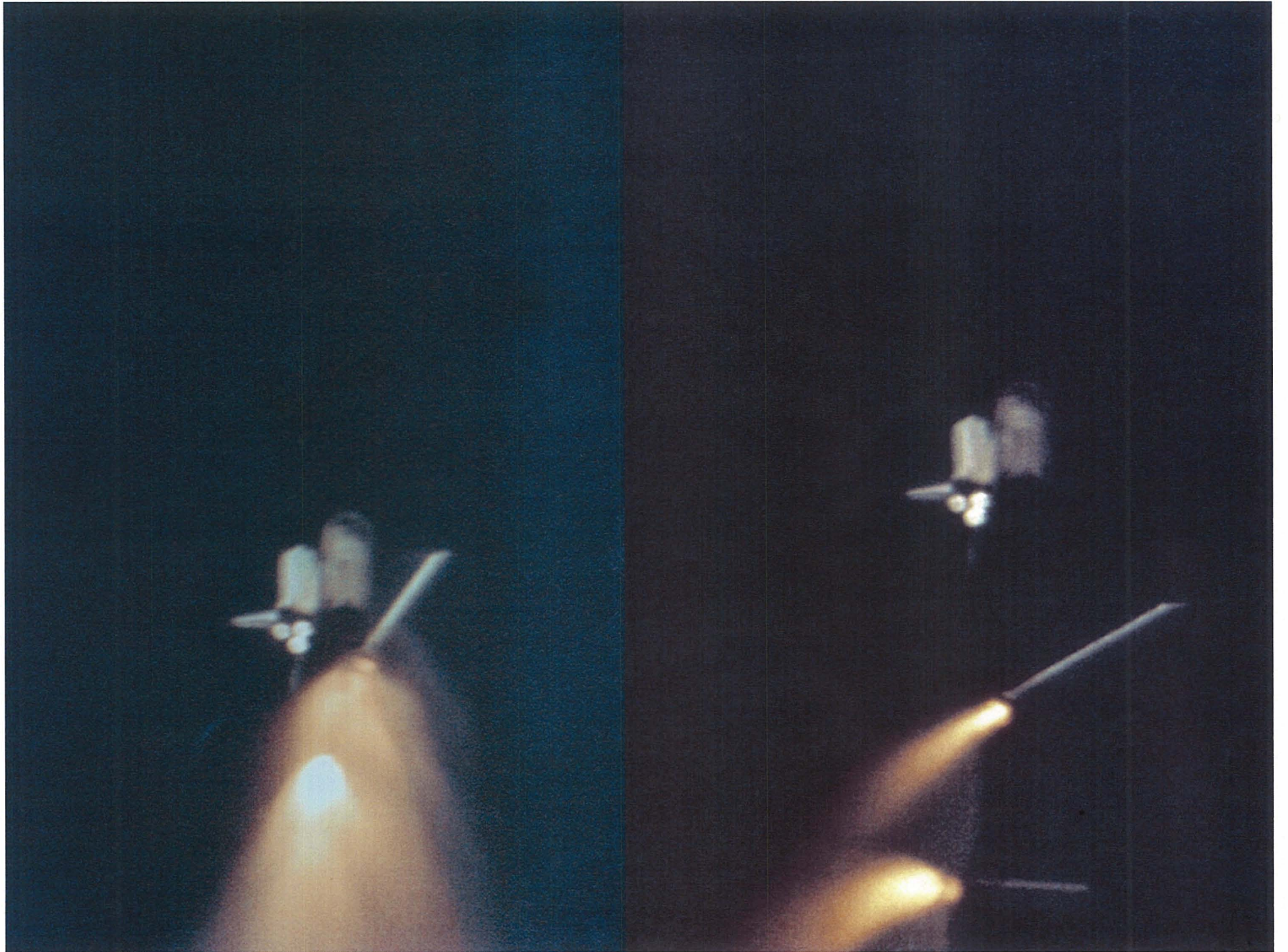


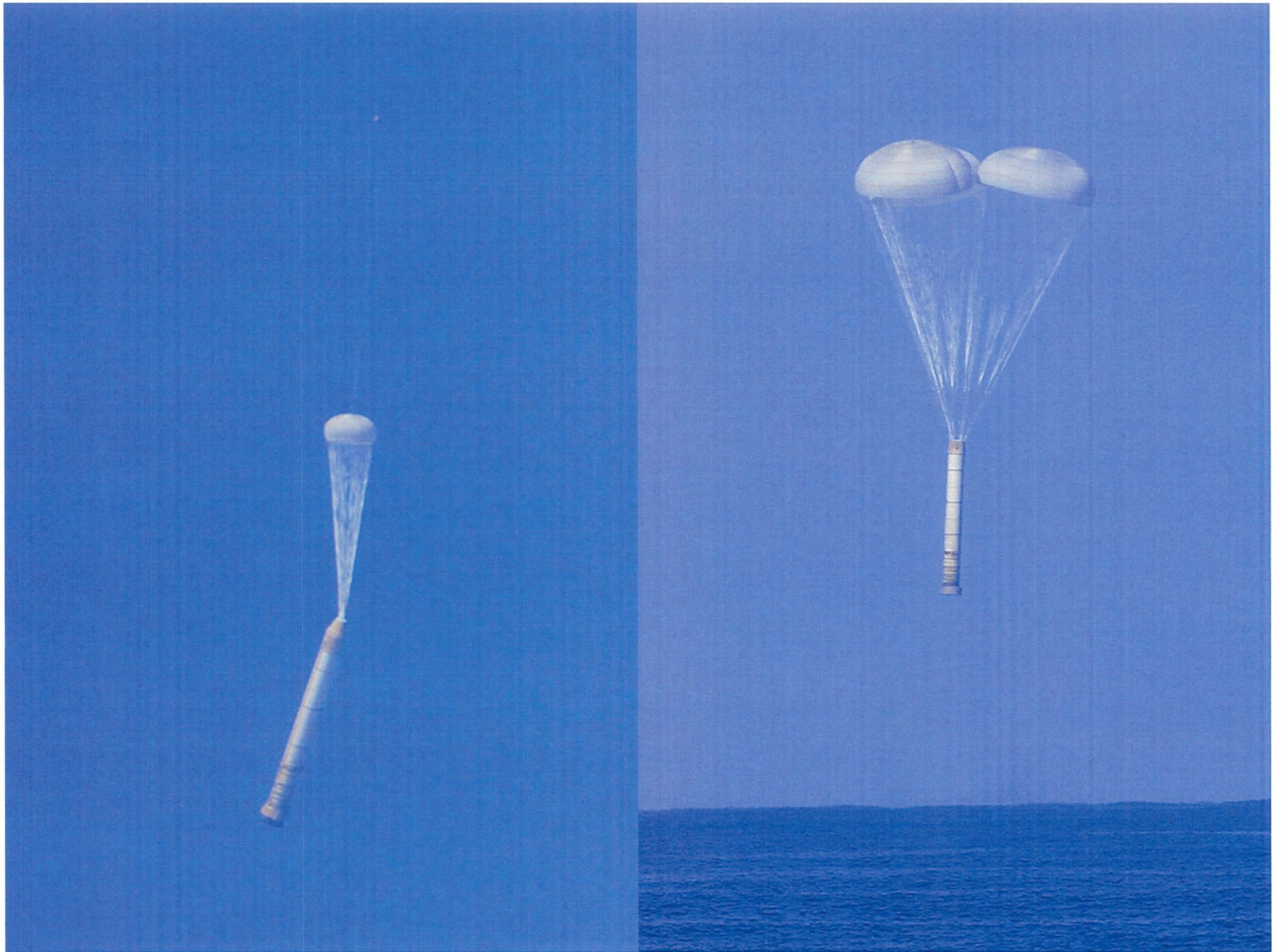
SPACE SHUTTLE GROUND OPERATIONS

Space Shuttle Launch

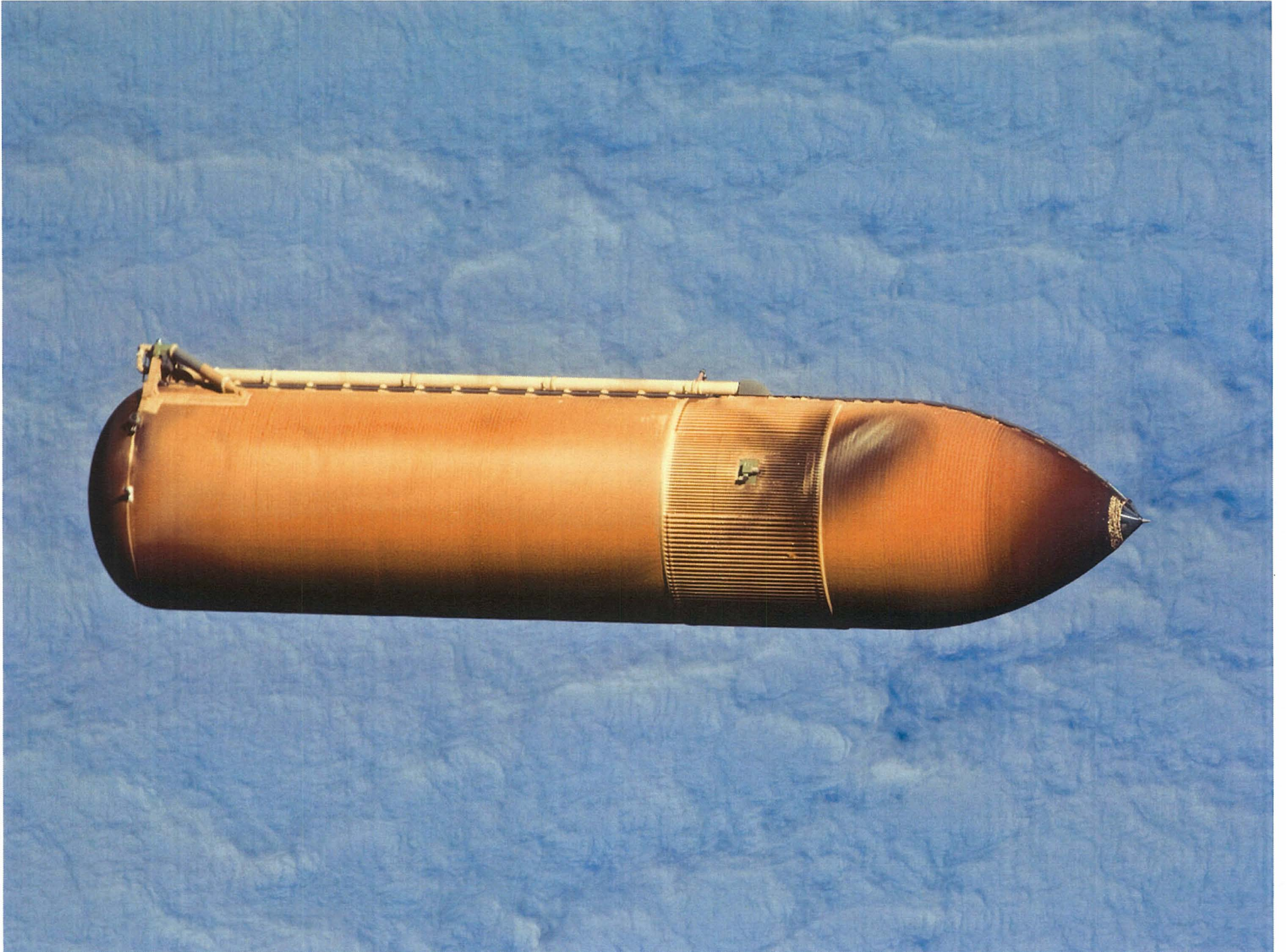




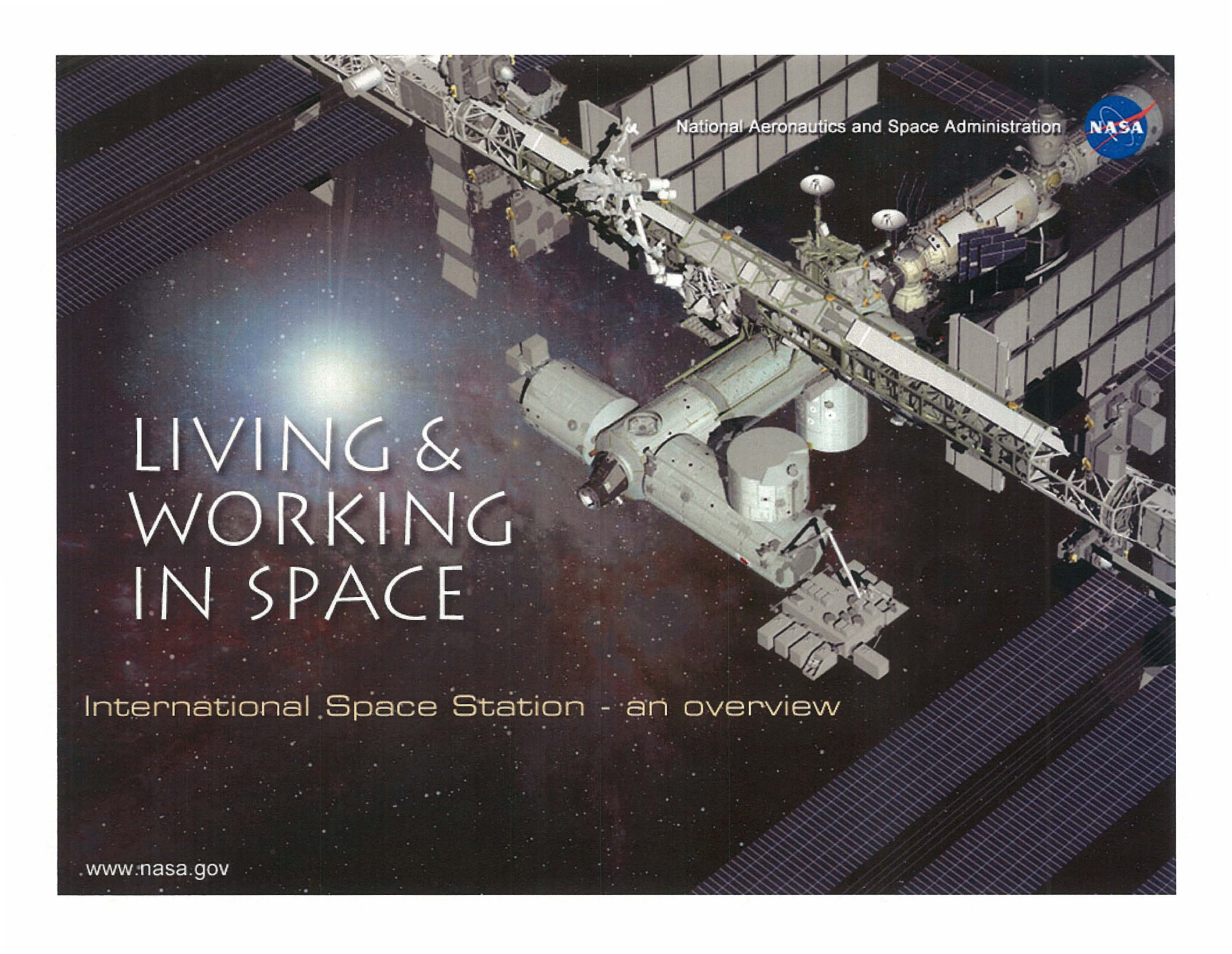










An aerial view of the International Space Station (ISS) in space. The station's complex structure, including the large truss system and various modules, is clearly visible against the dark background of space. The Earth's surface is partially visible at the bottom right. The NASA logo is in the top right corner.

National Aeronautics and Space Administration



LIVING & WORKING IN SPACE

International Space Station - an overview

www.nasa.gov



Vision

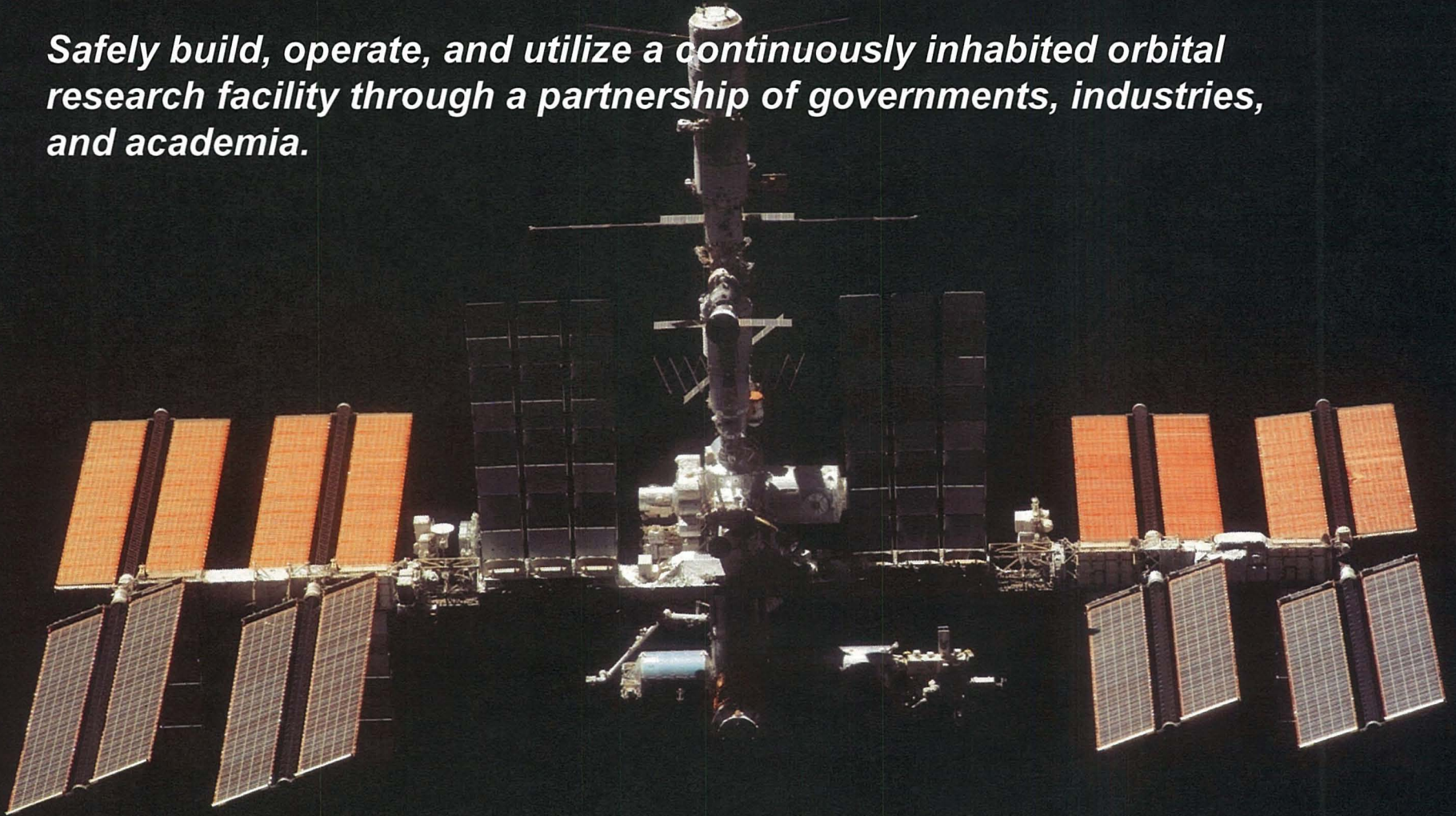
A human outpost in space bringing nations together for the benefit of life on Earth ... and beyond.

We will make revolutionary discoveries and establish a permanent international presence of humans in space, to advance the exploration of the solar system and enable commerce in space.

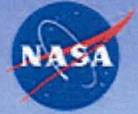
INTERNATIONAL SPACE STATION

Mission

Safely build, operate, and utilize a continuously inhabited orbital research facility through a partnership of governments, industries, and academia.



ISS Today



dimensions:

240 ft. long, 291 ft. wide, 45 ft. high,
29,560 cubic feet of living space.

weight:

815,520 lbs.

science capabilities:

laboratories from four inter-
national space agencies – U.S.,
Russia, Europe, and Japan.

orbital inclination/path:

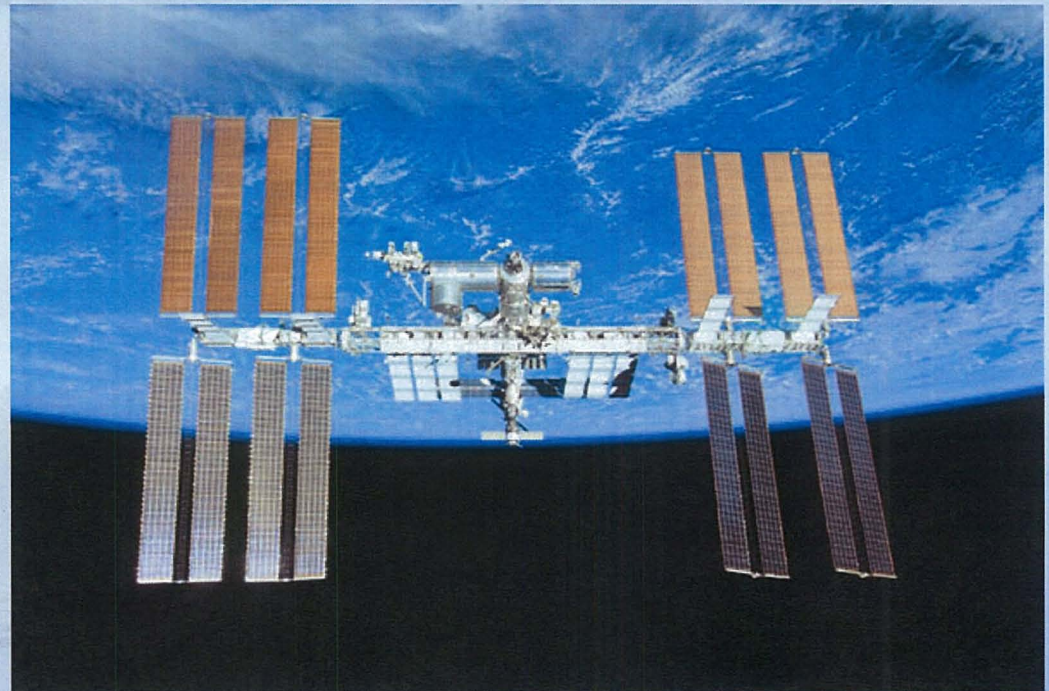
51.6 degrees, covering 90% of
the world's population.

altitude:

approximately 220 miles above
the Earth.

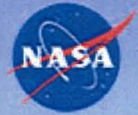
speed:

17,500 miles per hour, orbiting
the Earth 16 times a day.



The International Space Station is more powerful, and
4 times larger than any human space craft ever built.

ISS Today



Multi-dimensional challenges:

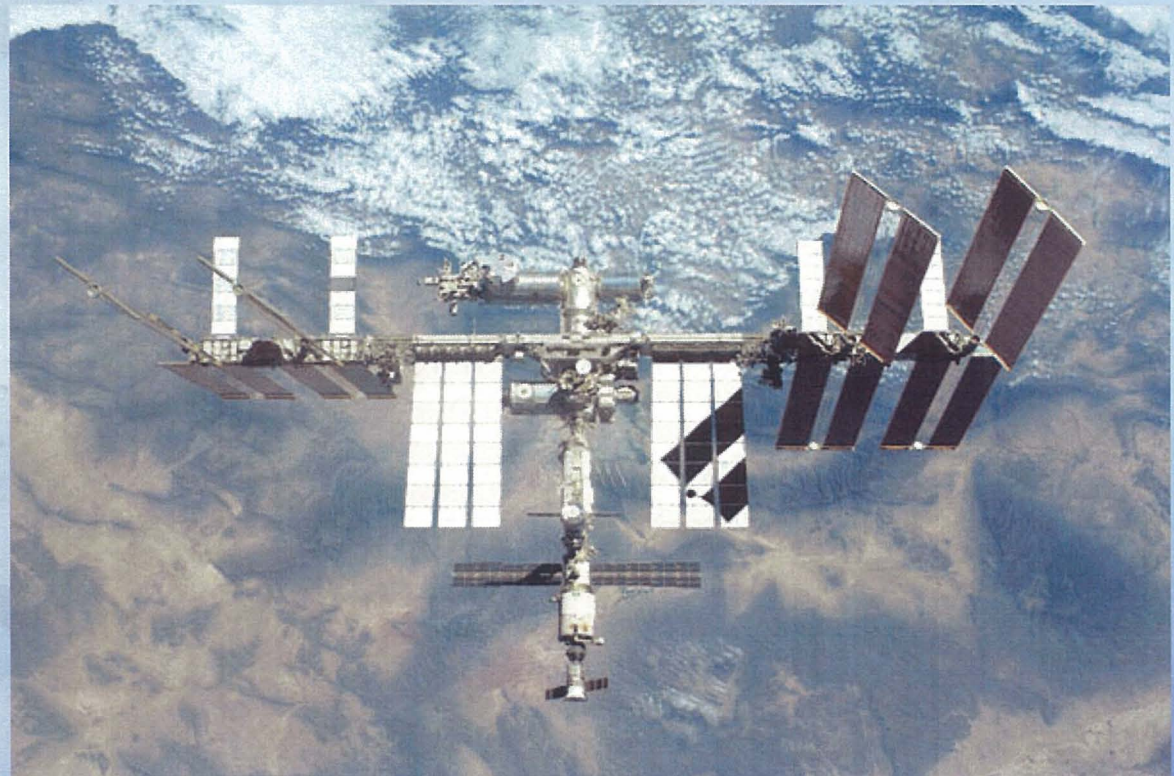
Integrating International Partners

Engineering Excellence

Prioritizing Science

24/7 Space Operations

Organization, Budget, and People



INTERNATIONAL SPACE STATION



Ten years

of continued human presence...



INTERNATIONAL SPACE STATION

Five international partners

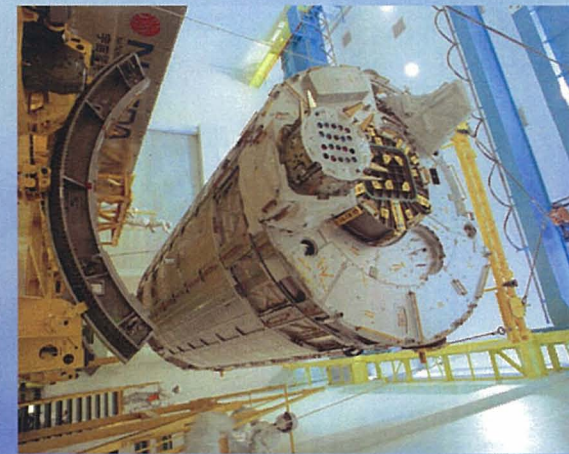
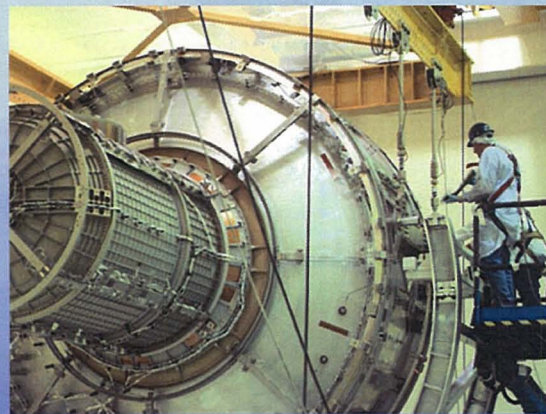
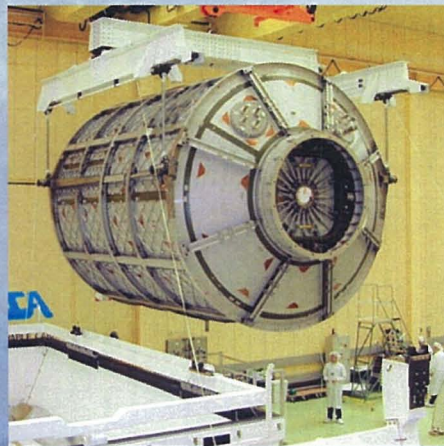


INTERNATIONAL SPACE STATION



Elements are constructed around the world

and come together in space with hairline tolerance.



INTERNATIONAL SPACE STATION



110 flights to the ISS so far (11/98 - 4/11)

35 shuttle flights

* crew member exchange

STS-88 - U.S. Node

STS-96 - Logistics

STS-101 - Logistics

STS-106 - Logistics

STS-92 - Z-1 Truss

STS-97 - Solar Array

STS-98 - Destiny Lab

STS-102 - MPLM

STS-100 - Canadarm2

STS-104 - U.S. Airlock

STS-105* - MPLM

STS-108* - Expedition 4

STS-110 - S0 Truss

STS-111* - Science, Expedition 5

STS-112 - S1 Starboard Truss

STS-113* - P1 Port Truss, Expedition 6

STS-114 - Logistics

STS-121 - Logistics

STS-115 - P3/P4 Truss

STS-116* - P5 Integrated Truss, Expedition 14

STS-117* - S3/S4 Truss, Expedition 15

STS-118 - S5 Truss

STS-120* - Harmony module

STS-122* - Columbus module

STS-123* - "Kibo" module, "Dextre" robotic arm

STS-124* - second "Kibo" module

STS-126 - Logistics

STS-119* - S6 Truss Solar Array

STS-127* - "Kibo" platforms

STS-128* - MPLM

STS-129* - spare hardware on 2 logistics pallets

STS-130 - Node 3/Cupola

STS-131 - MPLM

STS-132 - MRM1, spare antenna

STS-133 - PMM "Leonardo", 1 logistics pallet

71 Russian flights

2 Proton, (FGB, Service Module)

2 Unmanned Soyuz (Pirs and Poisk docking compartments)

26 Soyuz crew vehicles

41 Progress re-supply ships

2 European flights

2 ATV re-supply ship

2 Japanese flights

2 HTV re-supply ship

INTERNATIONAL SPACE STATION

Present ISS launch vehicles



Shuttle



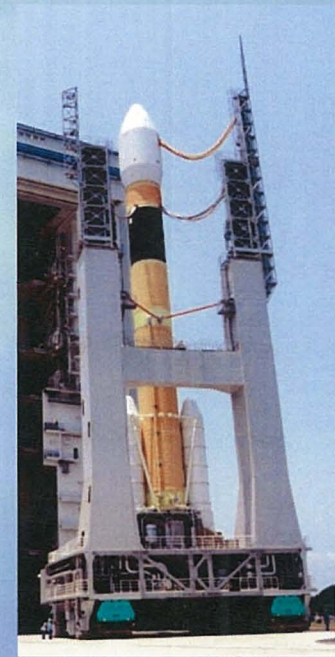
Proton



Soyuz



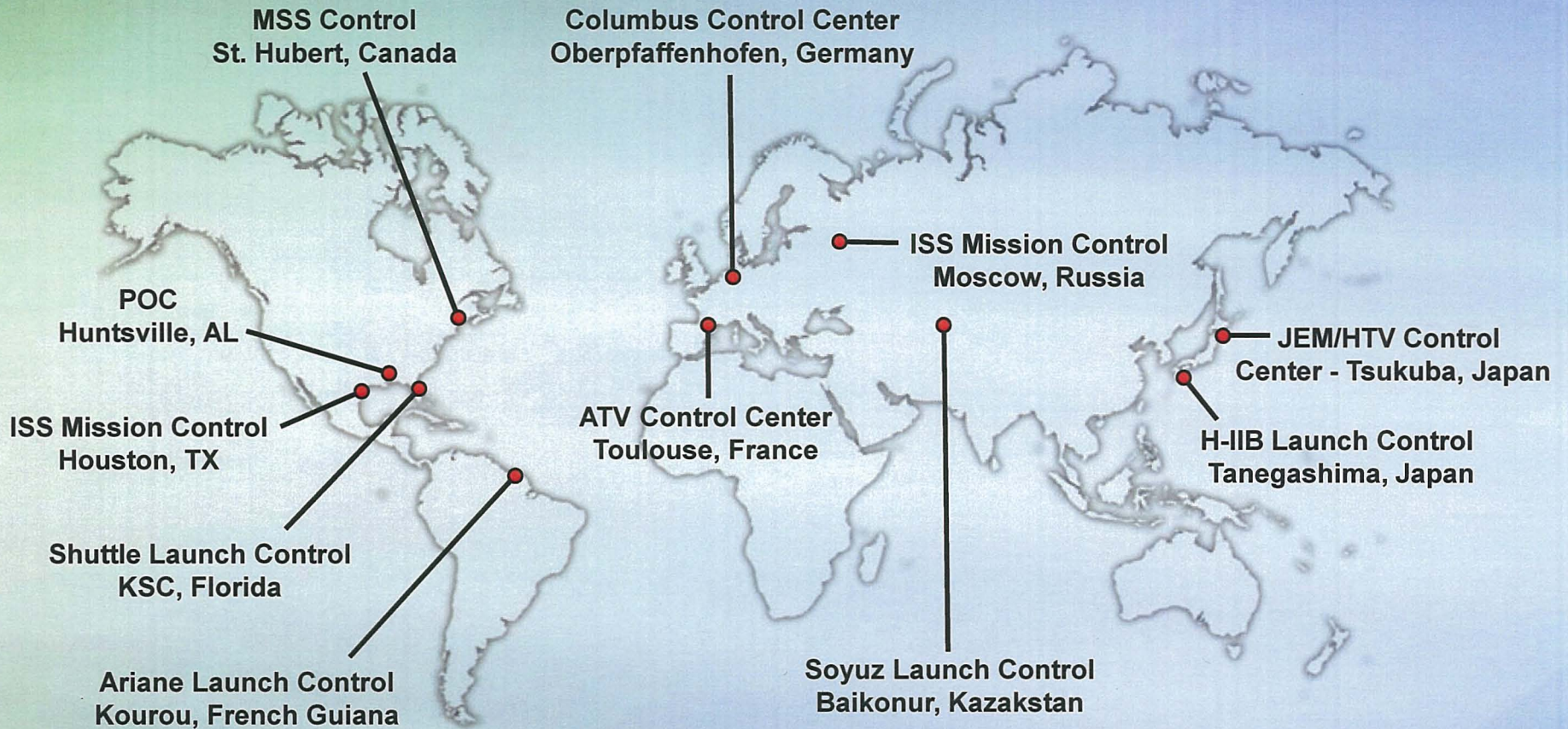
Ariane



HII B



NASA and international partner control centers



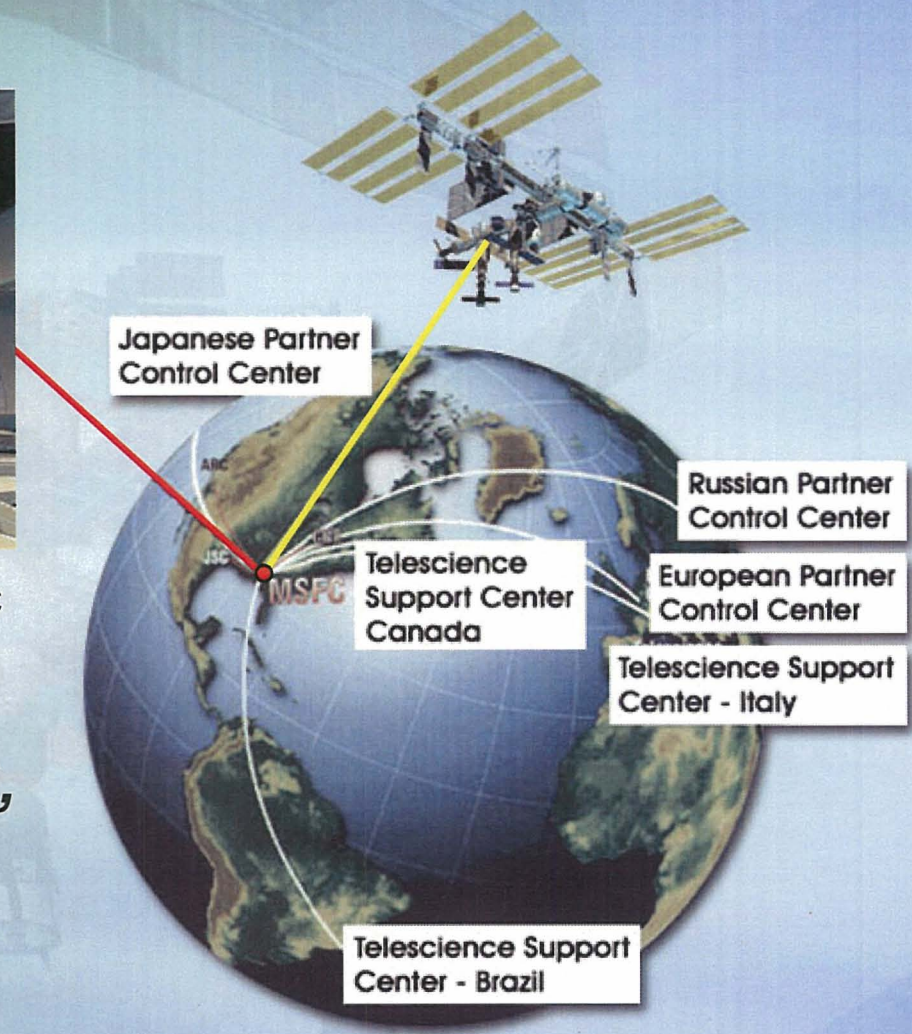


Payload Operations Centers



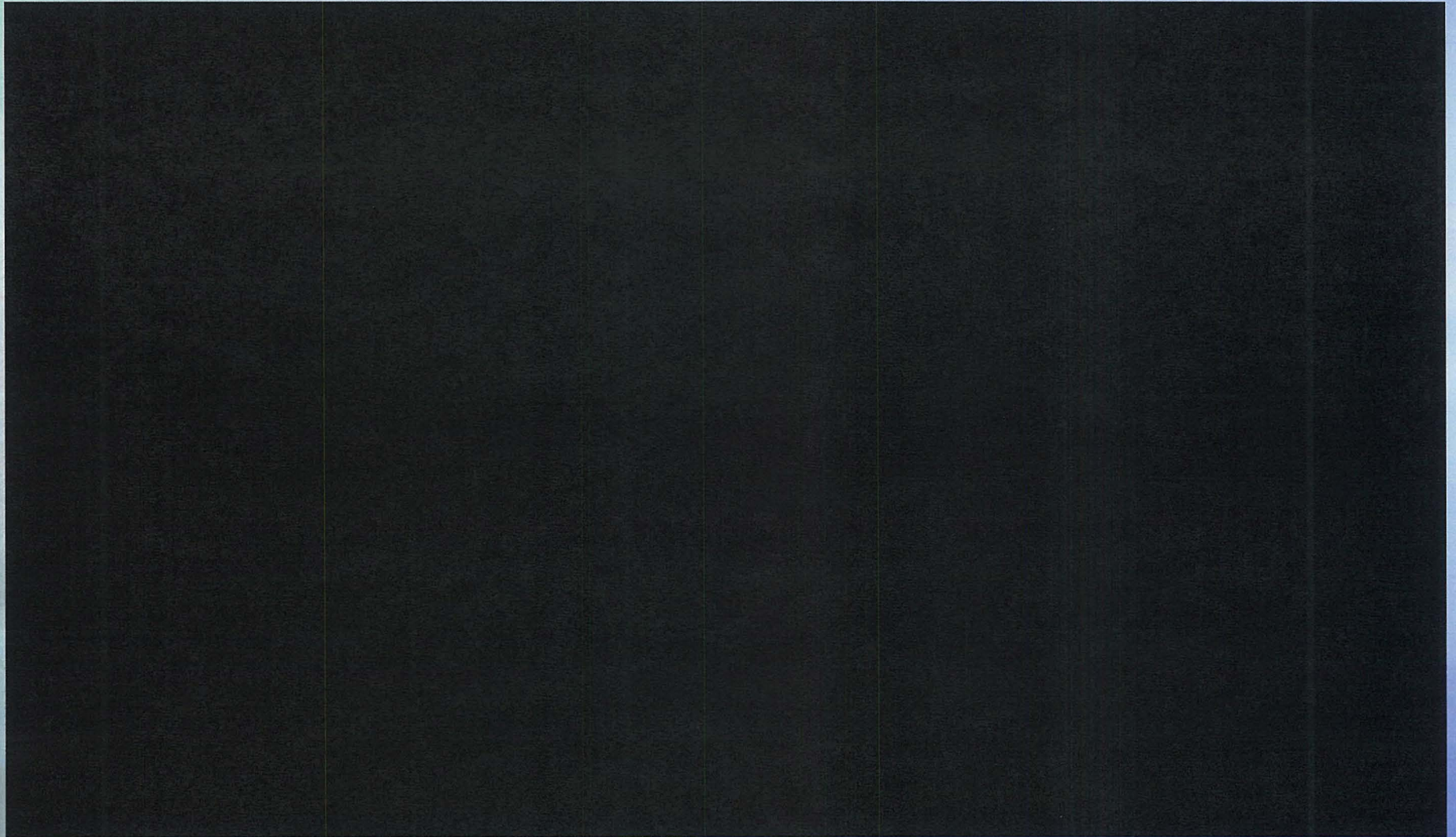
ISS Payload Operations Center - MSFC

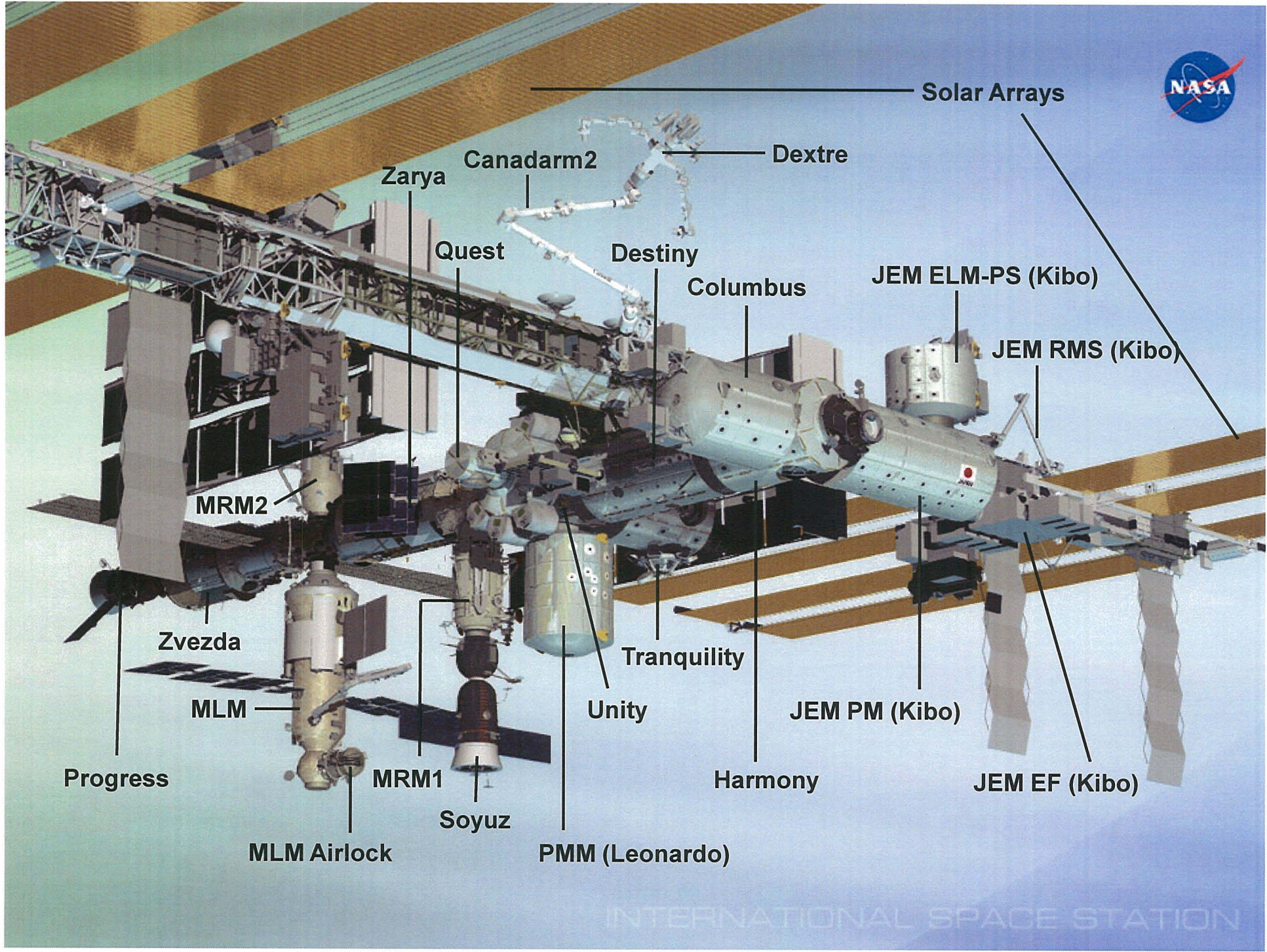
*From laptop, to ISS,
to the world*



INTERNATIONAL SPACE STATION

ISS Assembly Sequence





Solar Arrays

Dextre

Zarya

Canadarm2

Quest

Destiny

Columbus

JEM ELM-PS (Kibo)

JEM RMS (Kibo)

MRM2

Zvezda

MLM

Progress

MRM1

Soyuz

MLM Airlock

PMM (Leonardo)

Tranquility

Unity

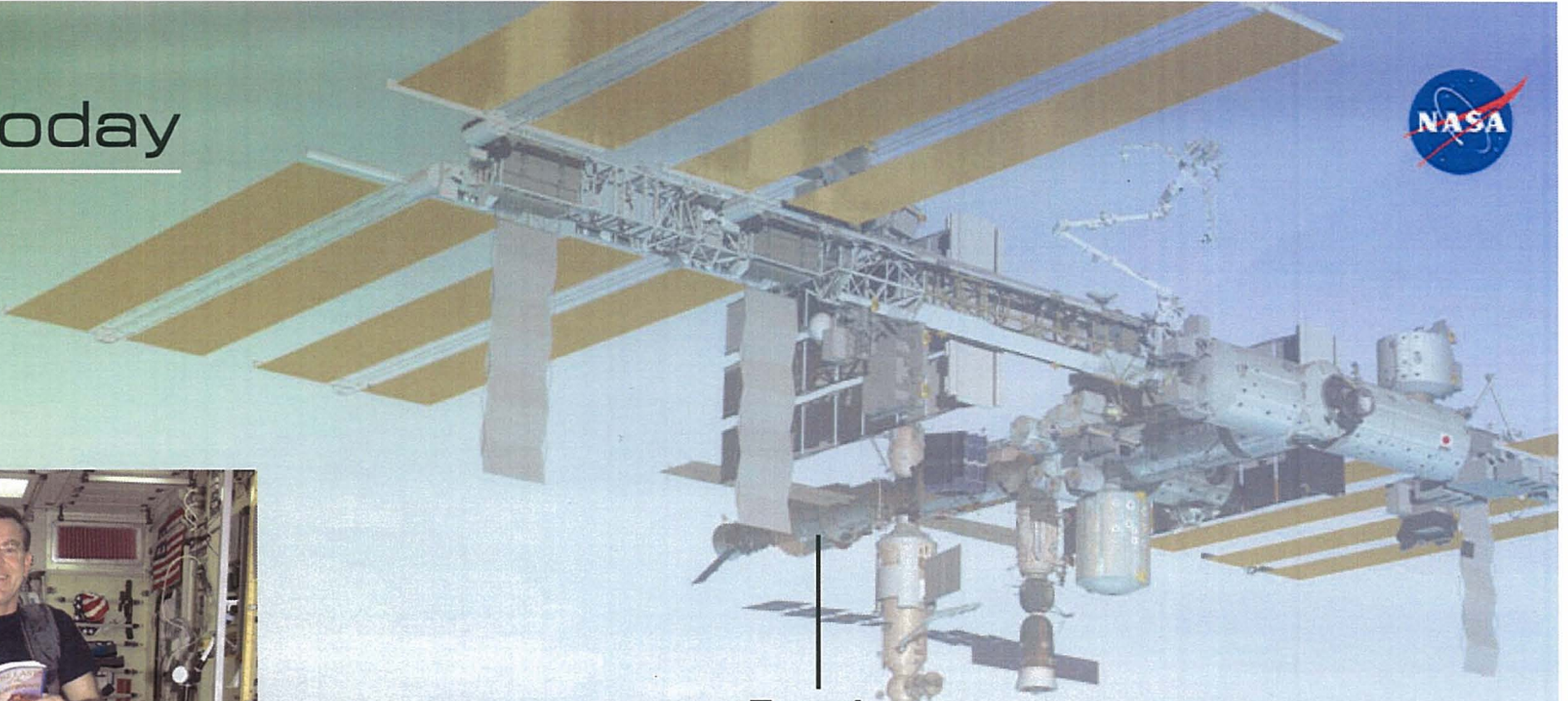
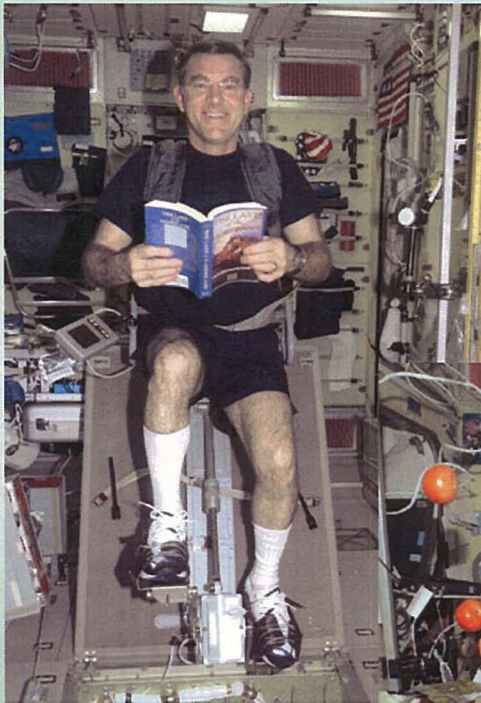
JEM PM (Kibo)

Harmony

JEM EF (Kibo)

INTERNATIONAL SPACE STATION

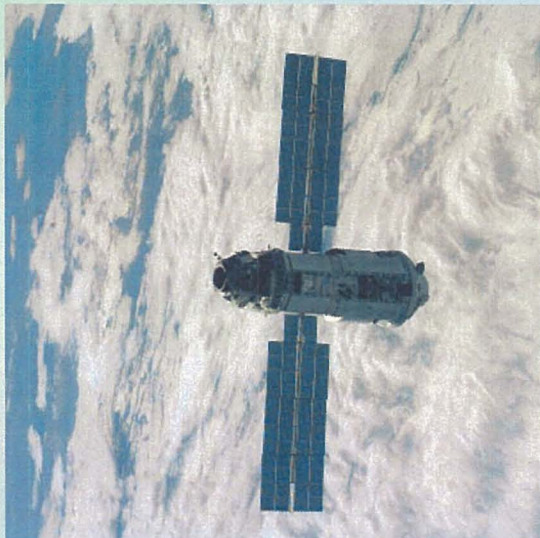
ISS today



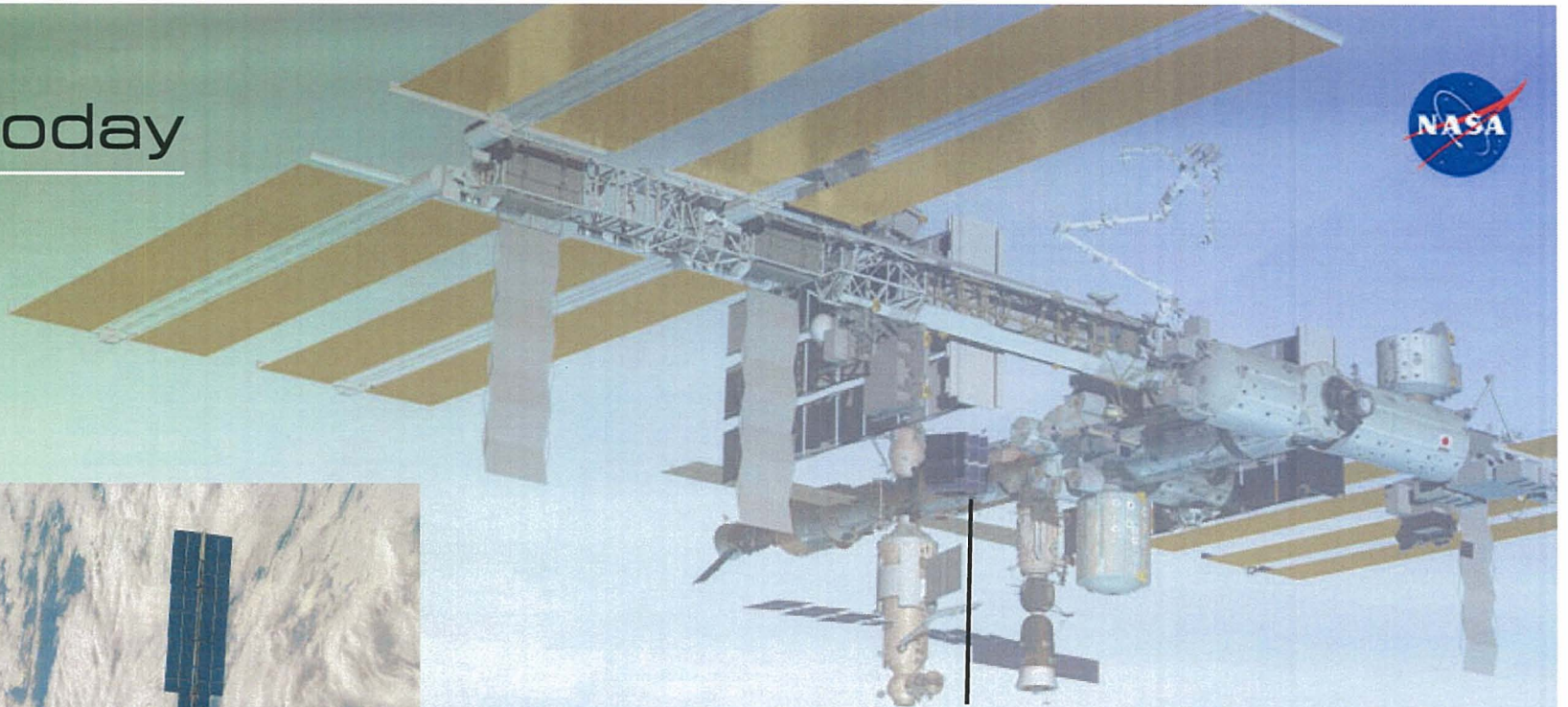
Zvezda

“Zvezda”, or the Service Module, serves as the Station’s crew quarters, providing a place for the astronauts to eat, live, rest, exercise, and conduct science experiments.

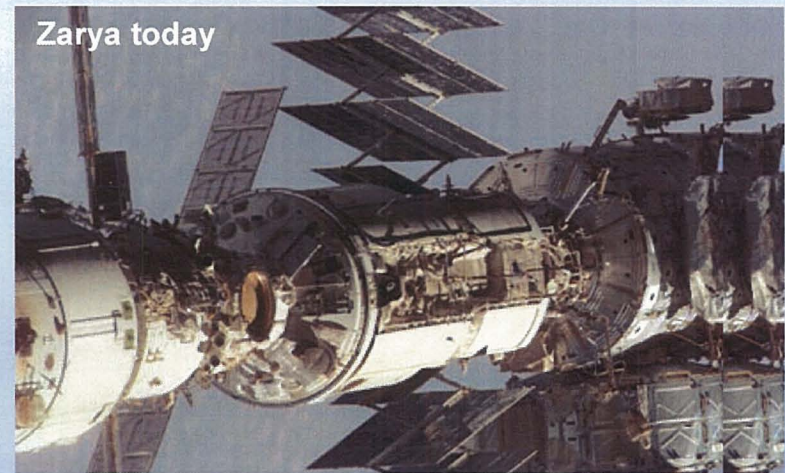
ISS today



The Russian built Zarya, or functional cargo block (FCB) was the initial building block, control center, and propulsive power of the Station.

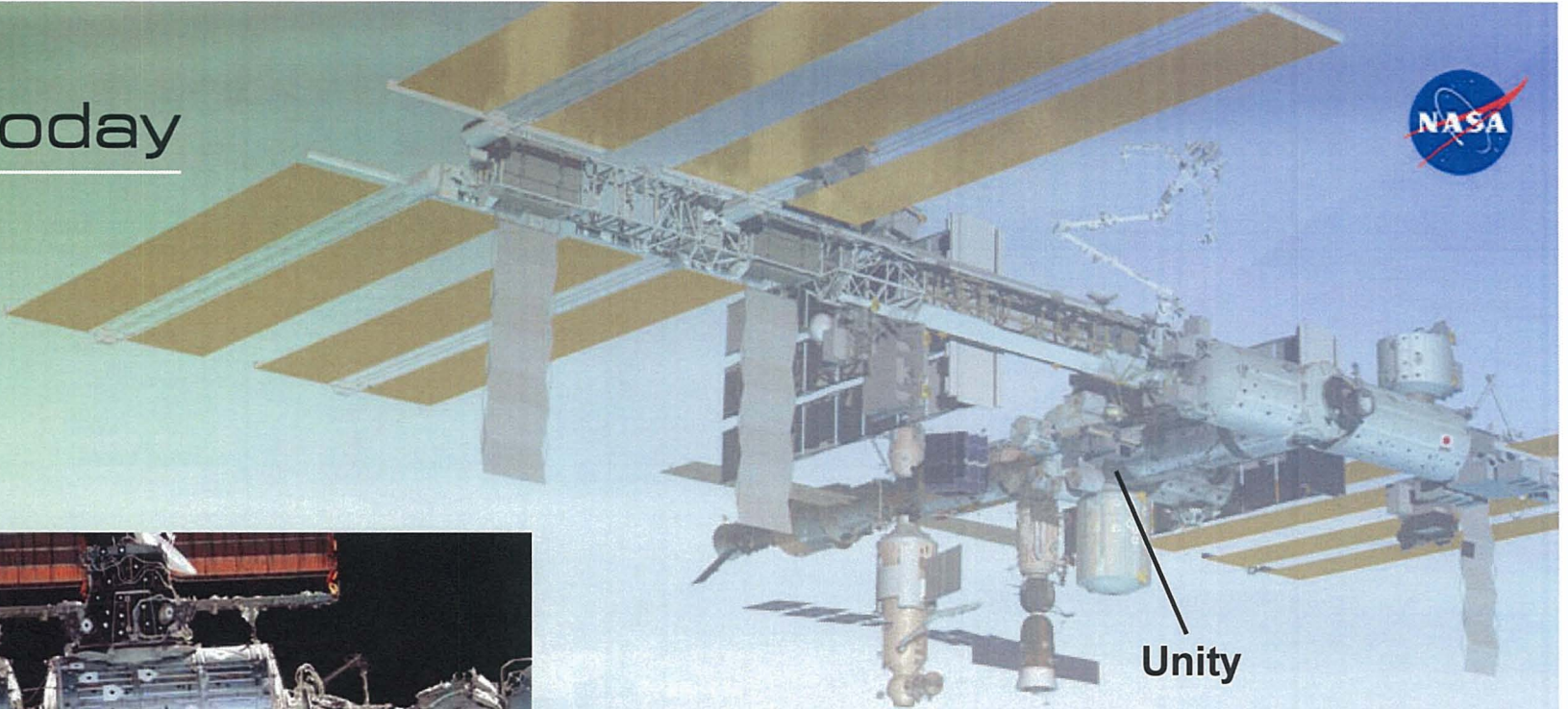


Zarya

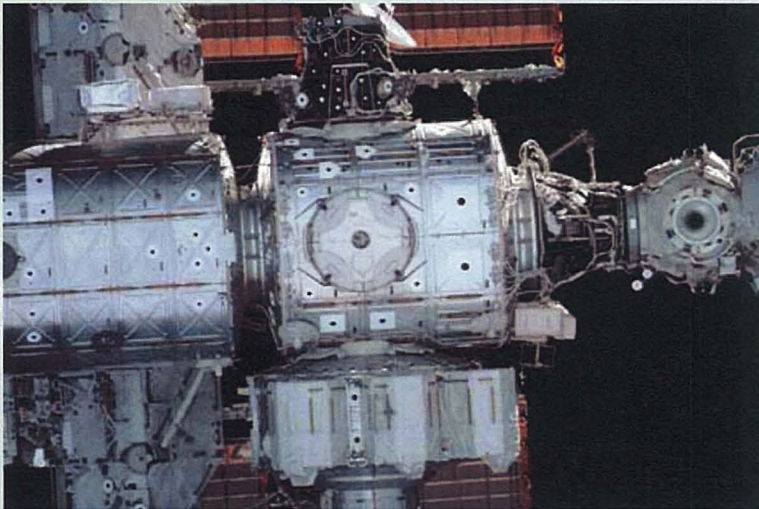


Zarya today

ISS today



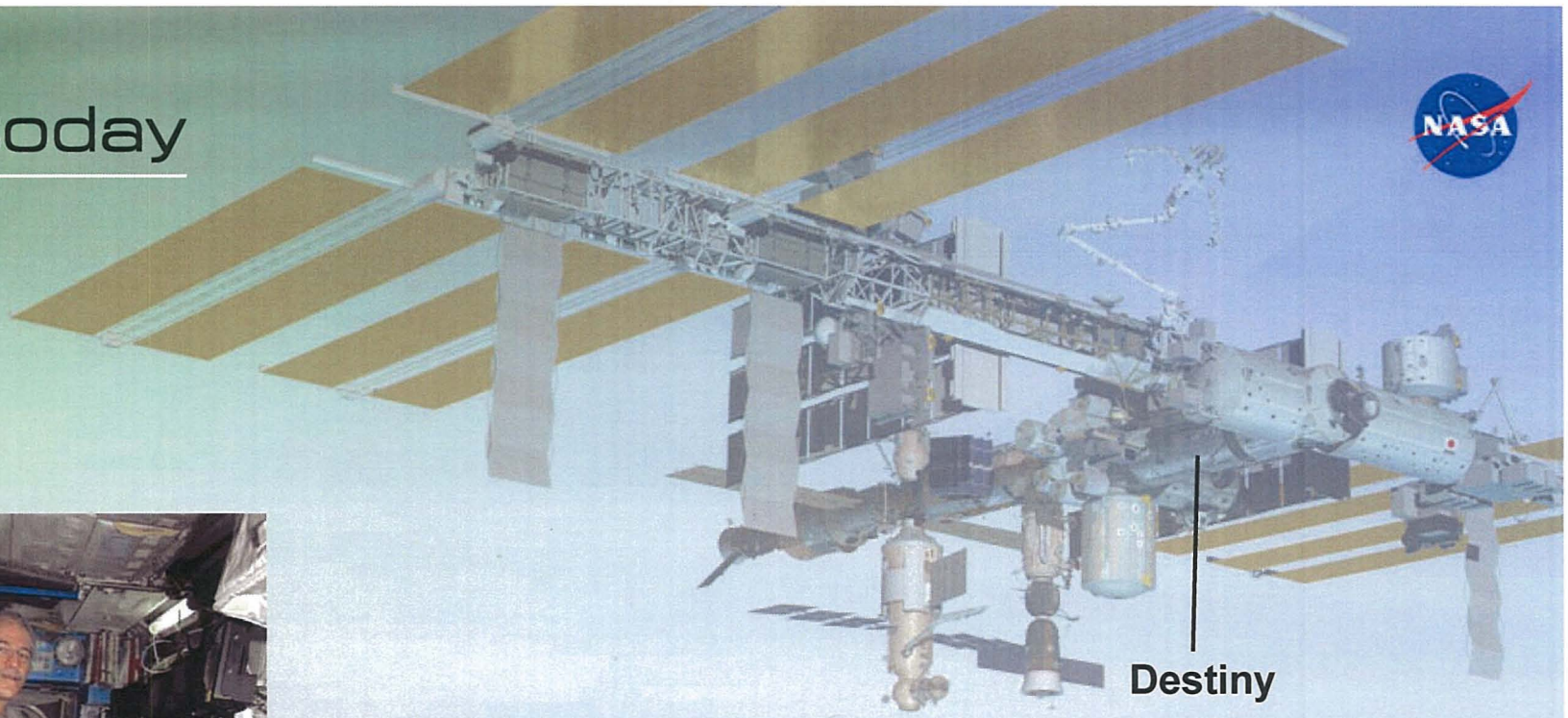
Unity



With six docking ports, "Unity" (Node1) is the nexus of the Station's U.S. segment connecting the lab, airlock, and solar array structures.



ISS today

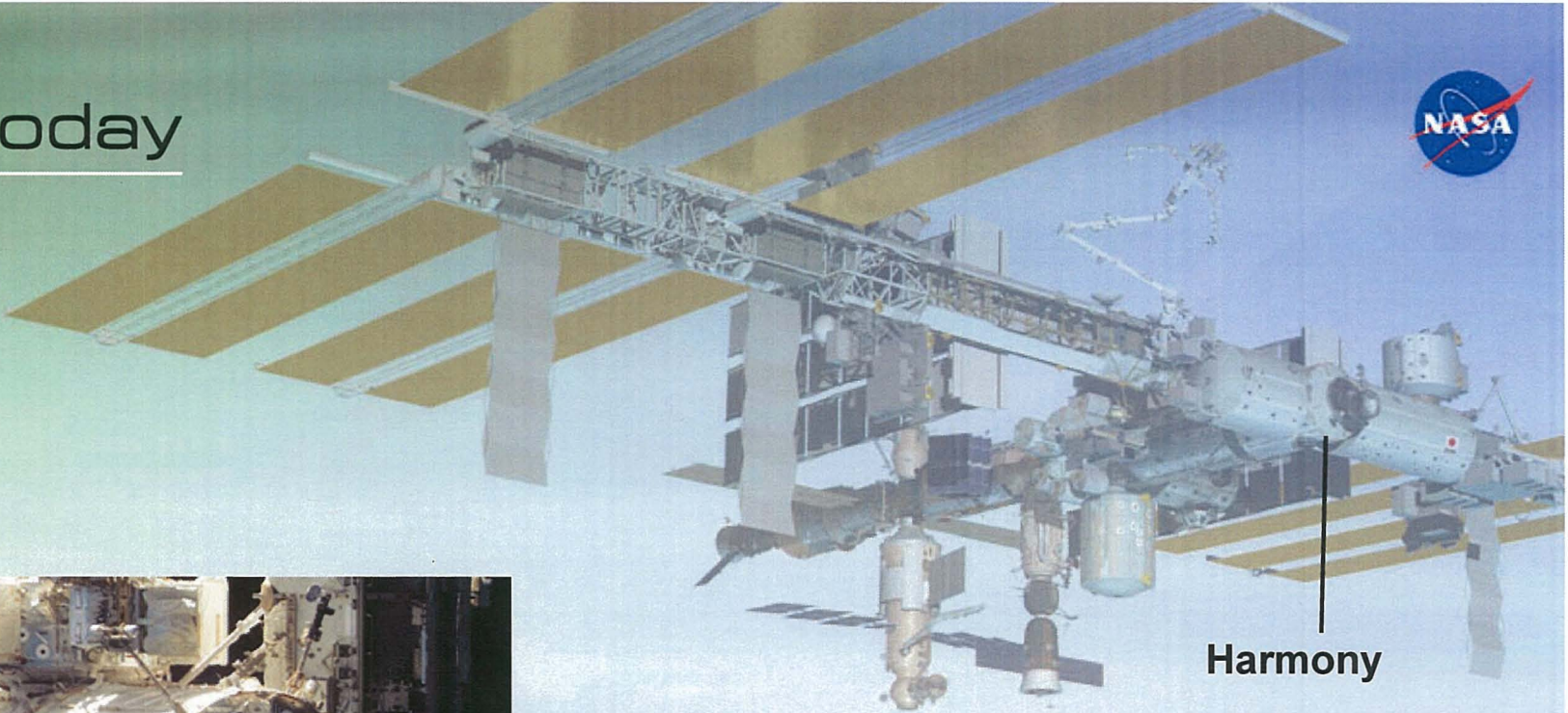


Destiny

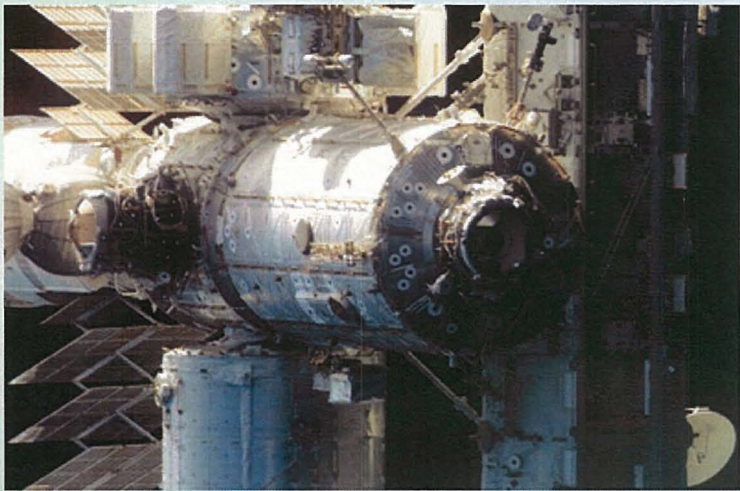


The Station's main U.S. science facility is the home of four different types of racks, where ongoing experiments are performed and monitored by the crew.

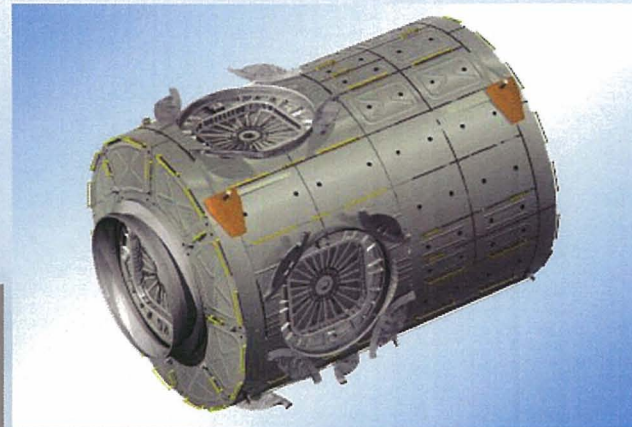
ISS today



Harmony



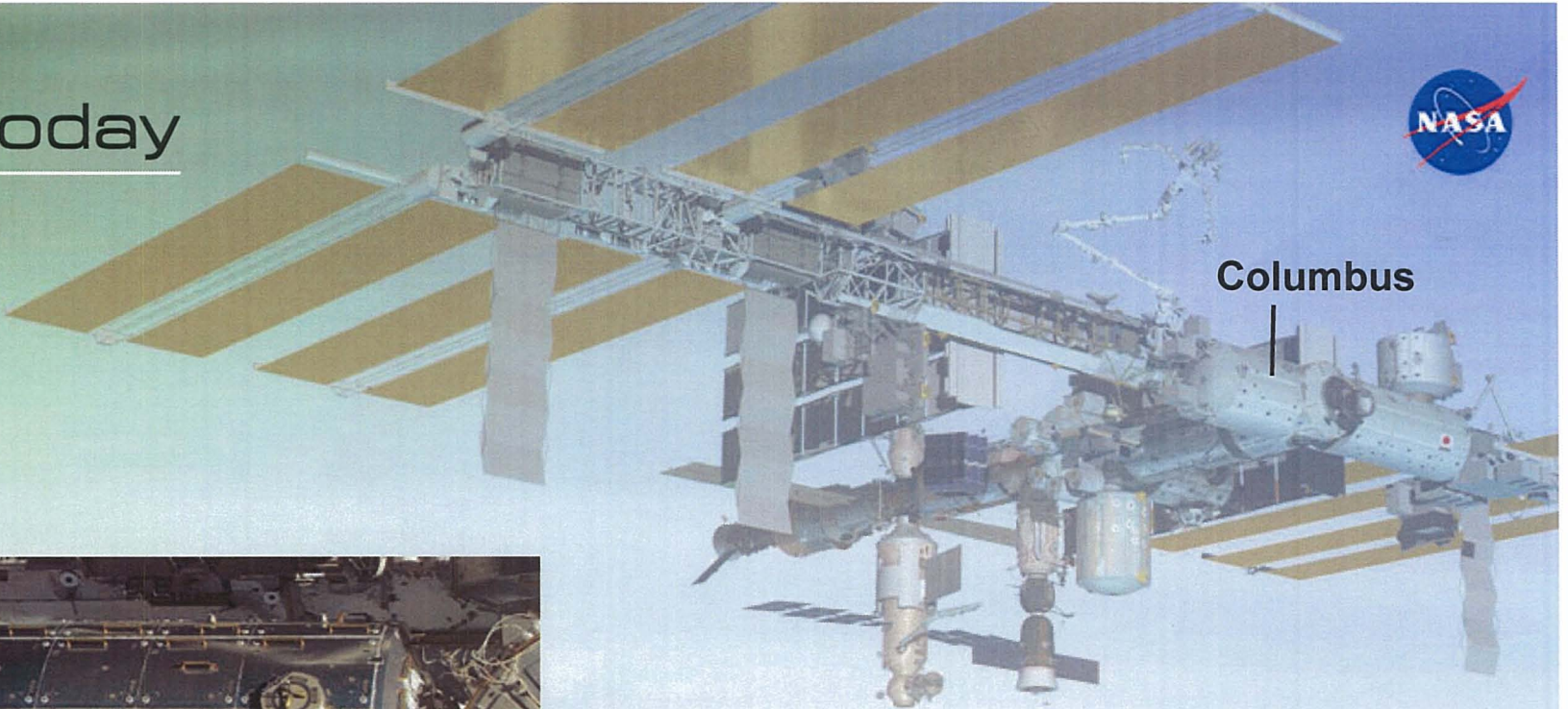
Node 2, or "Harmony", acts as a hub connecting the U.S. science lab "Destiny" to Europe's "Columbus" lab and Japan's "Kibo".



ISS today



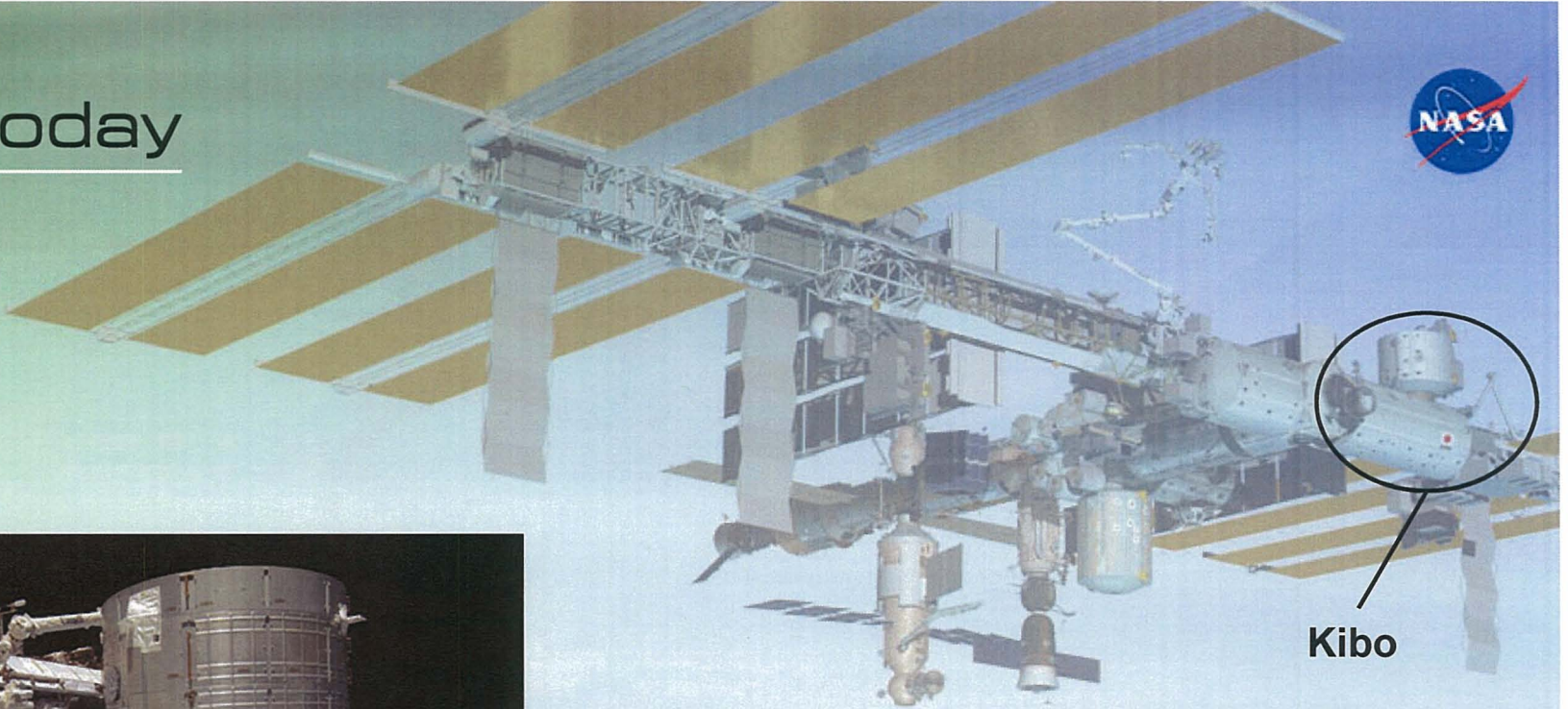
Columbus



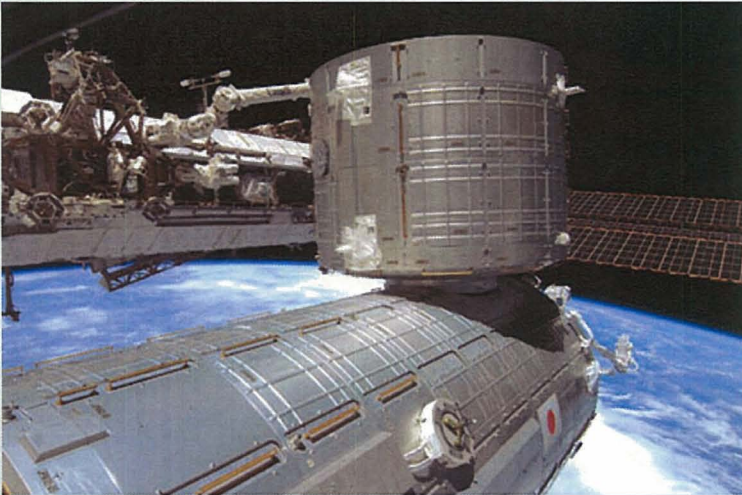
Europe's research laboratory was launched with five science experiment racks and has room for five more.



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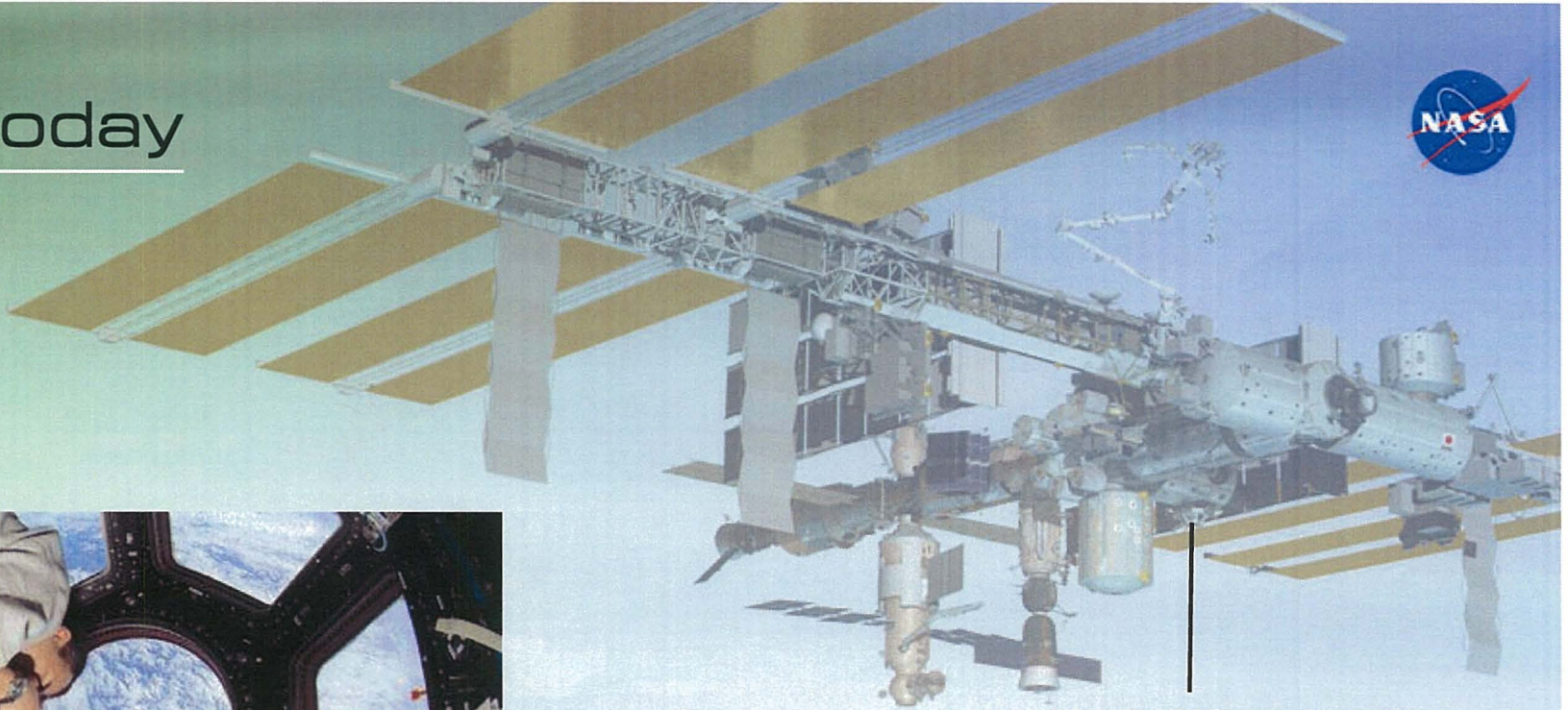
Kibo



“Kibo” (“Hope”), is Japan’s state of the art science lab consisting of two modules providing room to house ten racks - it also has it’s own robotic arm (JRMS) outside the station.

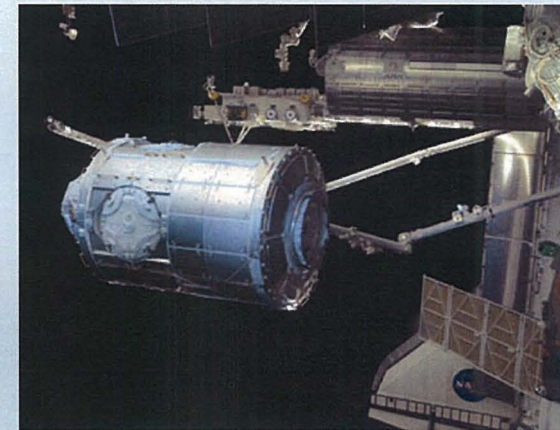


ISS today

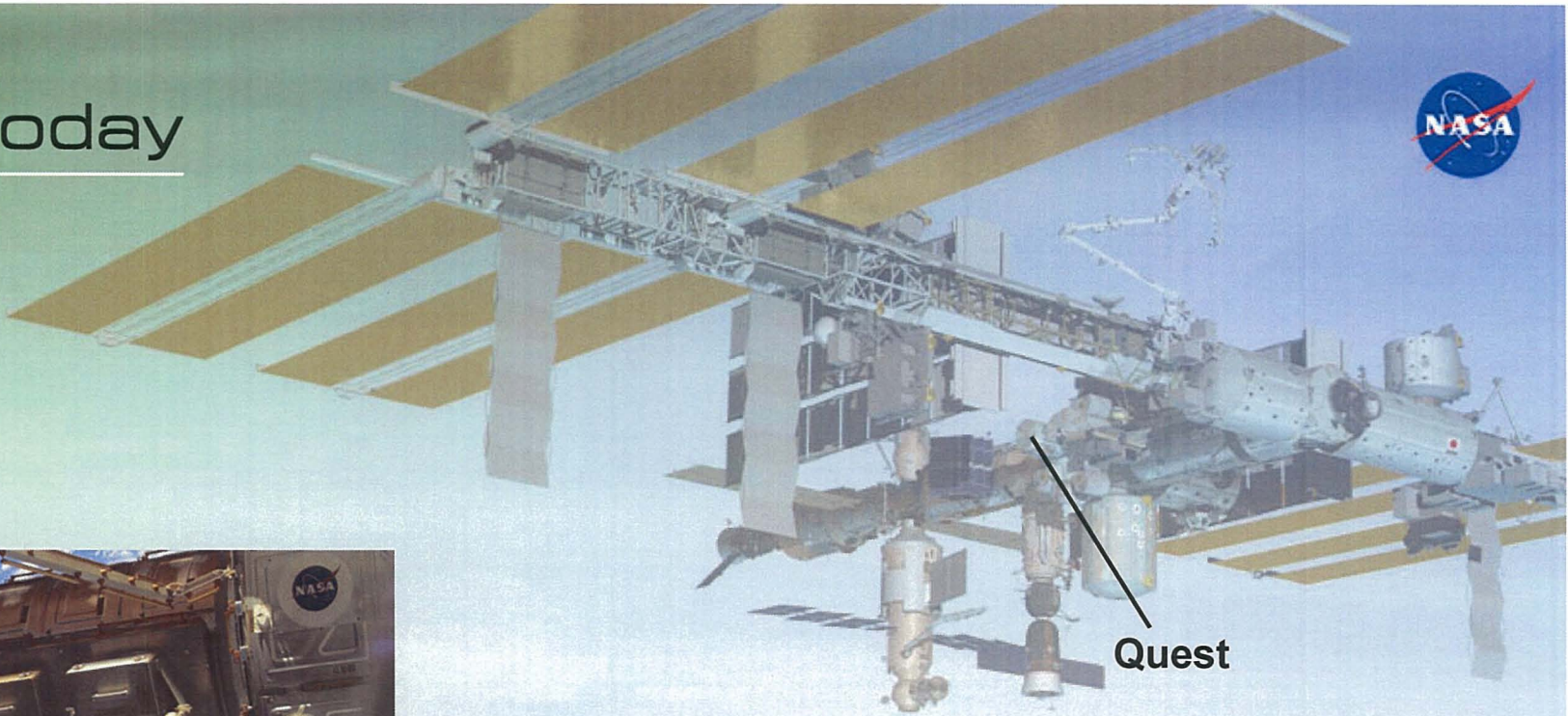


Node 3/Cupola

The European built Node 3, named "Tranquility", is the final connecting module to be added to the Station. Attached to the node is the Cupola, a robotic control station with seven windows providing a panoramic view of Earth, celestial objects, and visiting space craft.



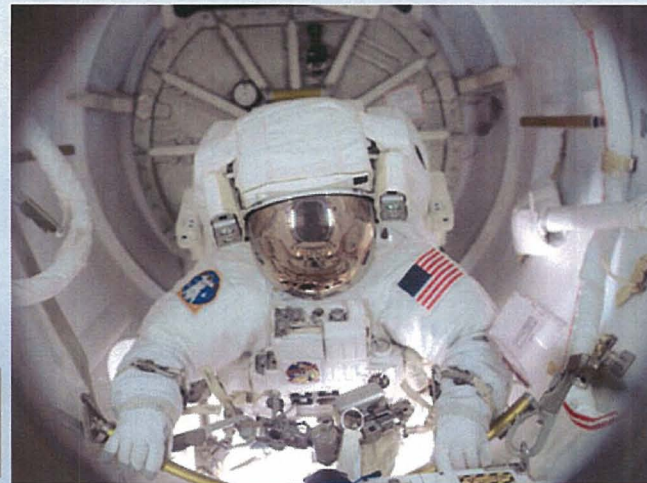
ISS today



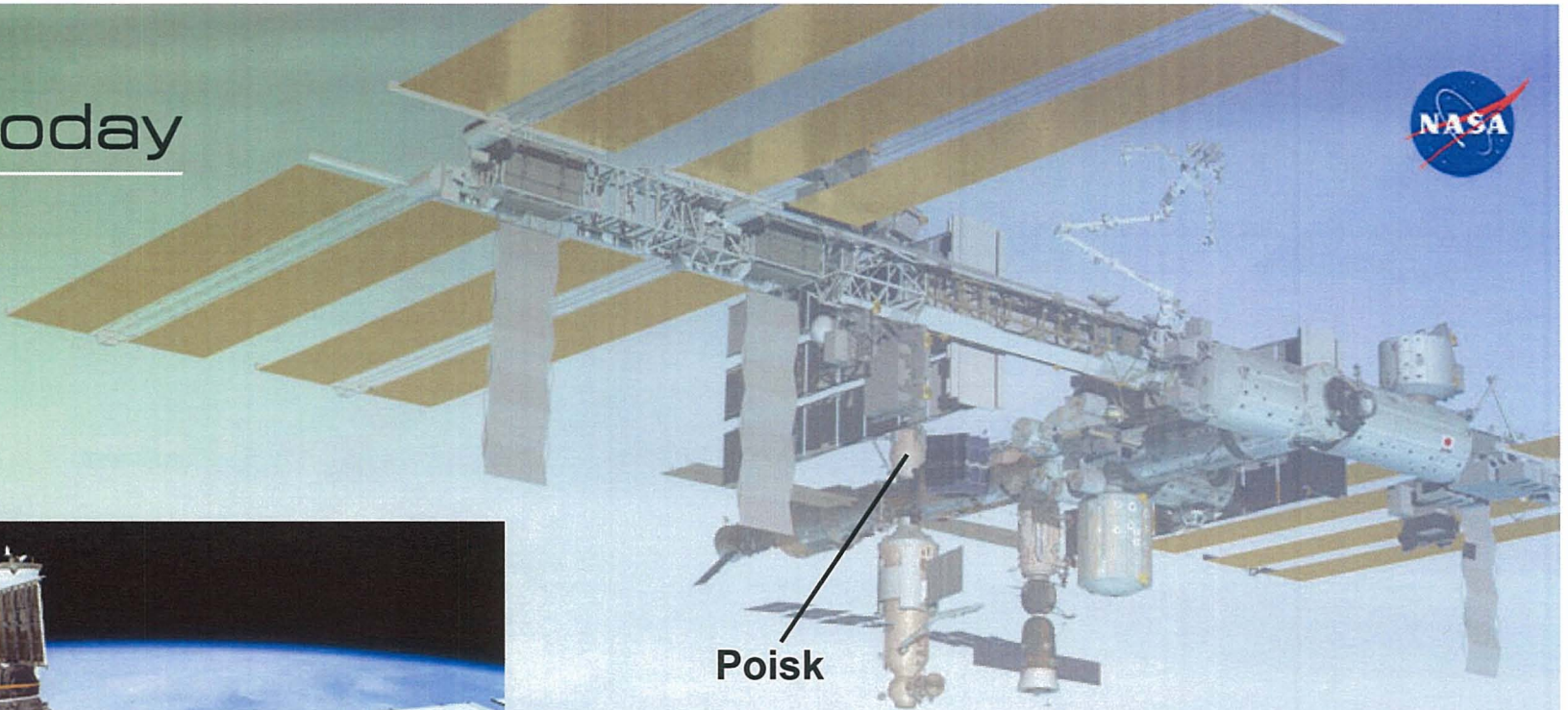
Quest



Astronauts exit the Station using the Joint Airlock "Quest" .



ISS today



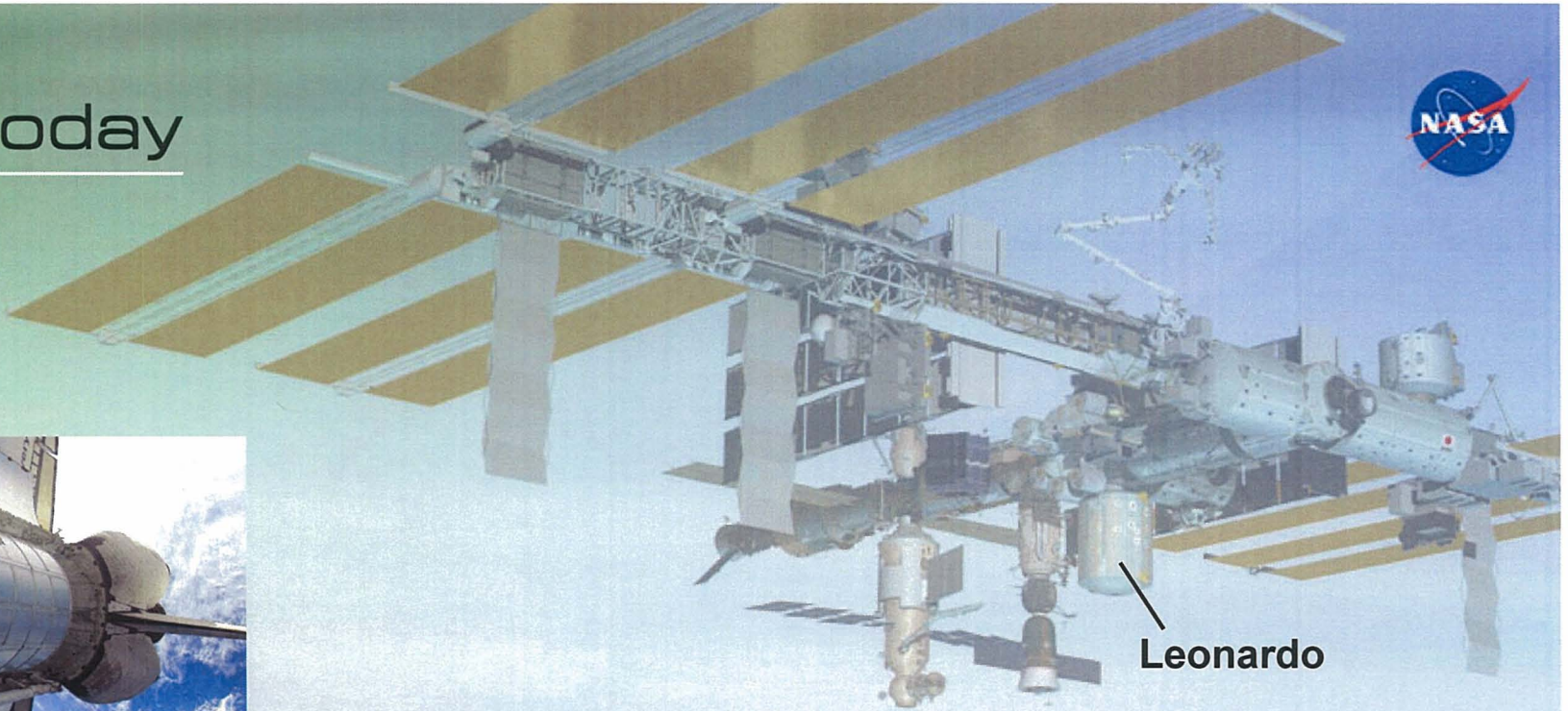
Poisk



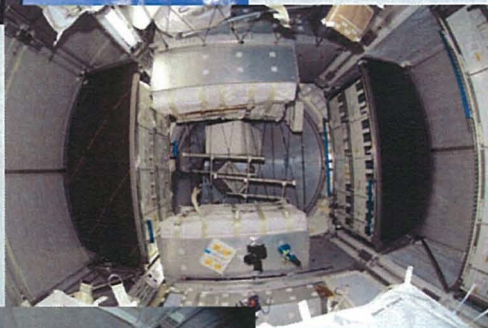
The Russian built "Poisk" (MRM2), along with functioning as a mini research module, also serves as an extra airlock for spacewalkers, and a docking port for re-supply ships.



ISS today

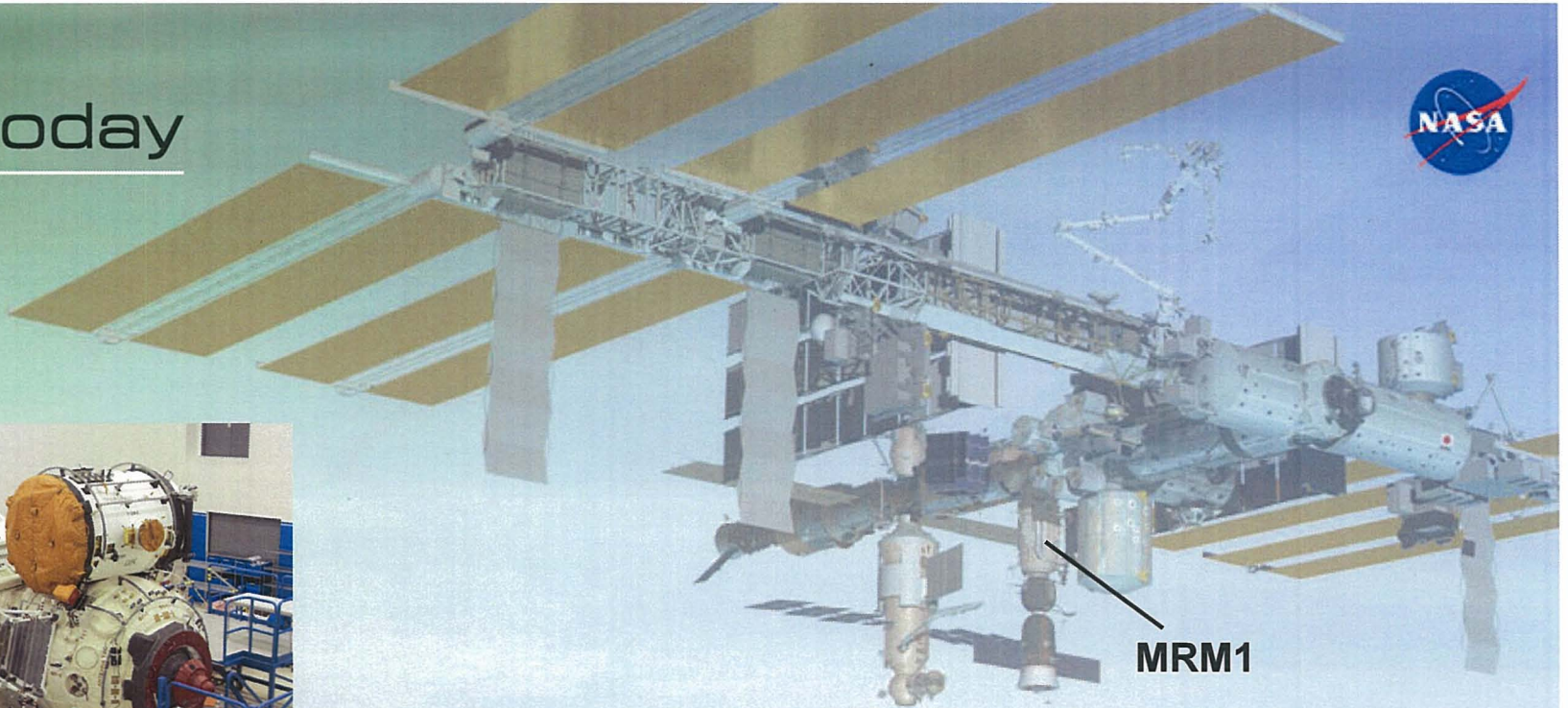
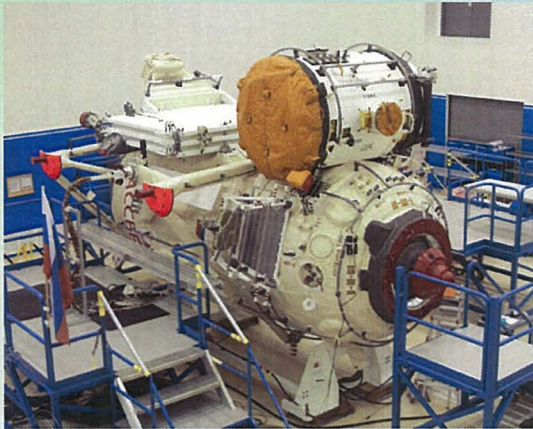


Leonardo



Leonardo is one of the three Multi-Purpose Logistics Modules (MPLM) built by the European Space Agency to ferry supplies, equipment and other cargo to and from the Station via the shuttle's payload bay. Later this year space shuttle Discovery will deliver the modified module one last time (STS-133), after which it will serve as a permanent pressurized storage facility for the crew.

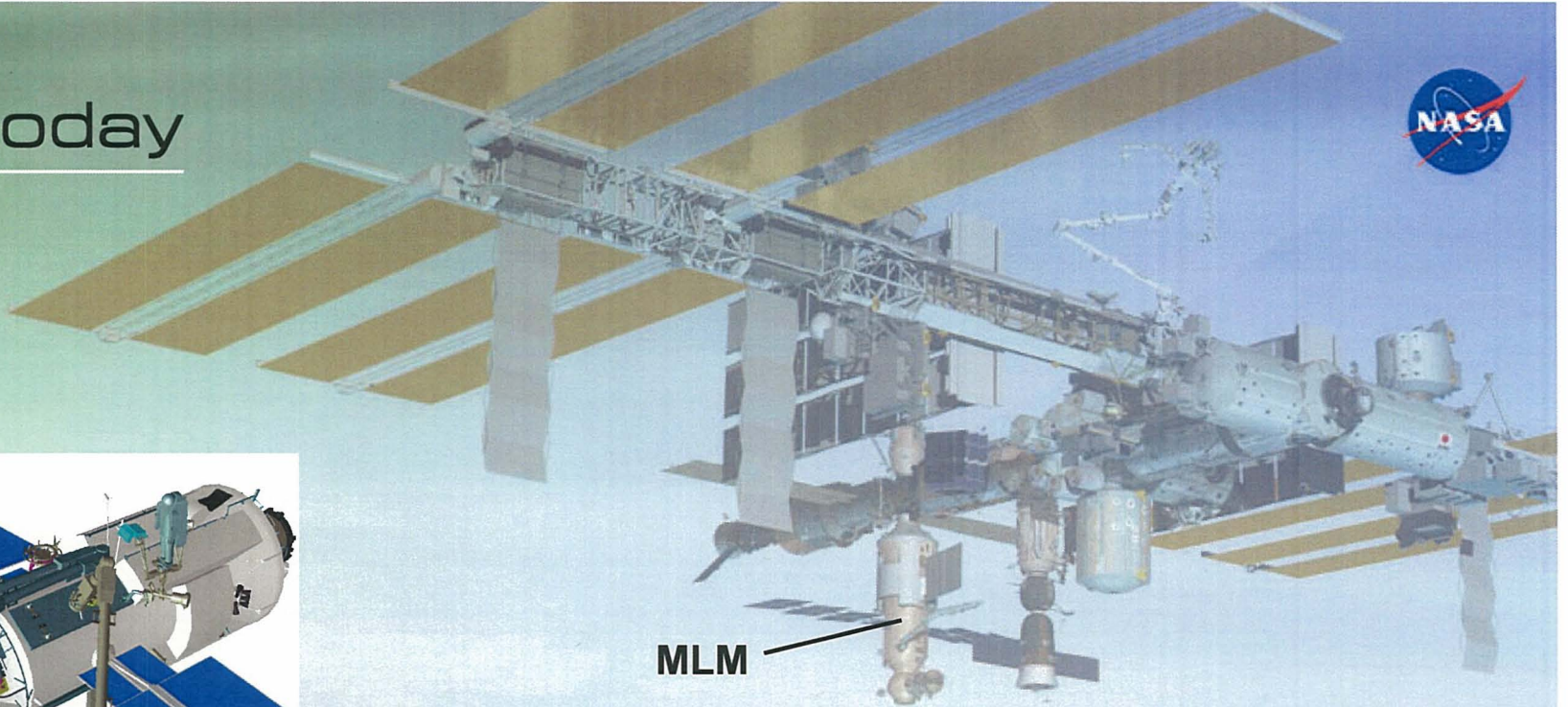
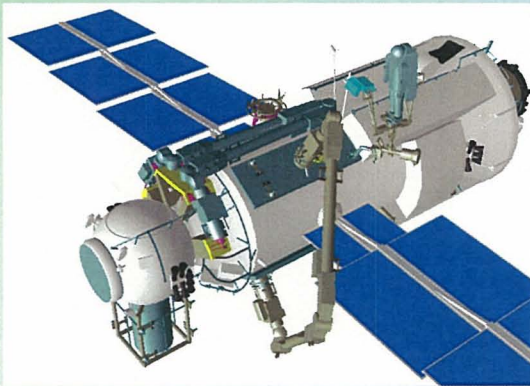
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MRM1

The Russian built MRM1 (Mini Research Module) is primarily used for cargo storage and payload operations. It also provides a fourth docking port on the Russian operation segment of the station, and on it's shell carries outfitting equipment for a future Russian lab module (MLM scheduled to launch in 2012).

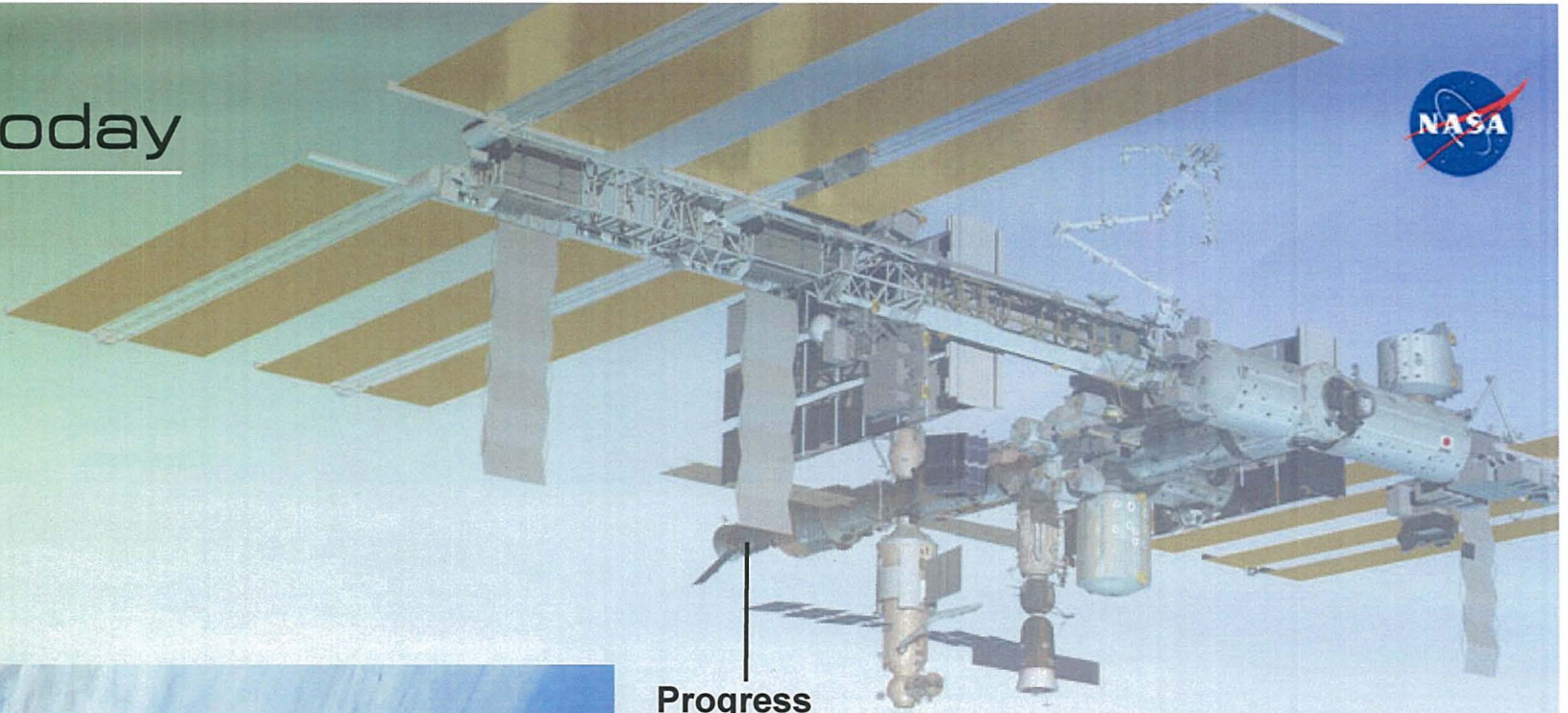
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MLM

Once docked to the Zvezda module the MLM (Multipurpose Laboratory Module) will become Russia's primary research module. It will also add to the Station an additional docking port/airlock and provide backup attitude control. It is scheduled for launch aboard a Russian Proton rocket in 2012.

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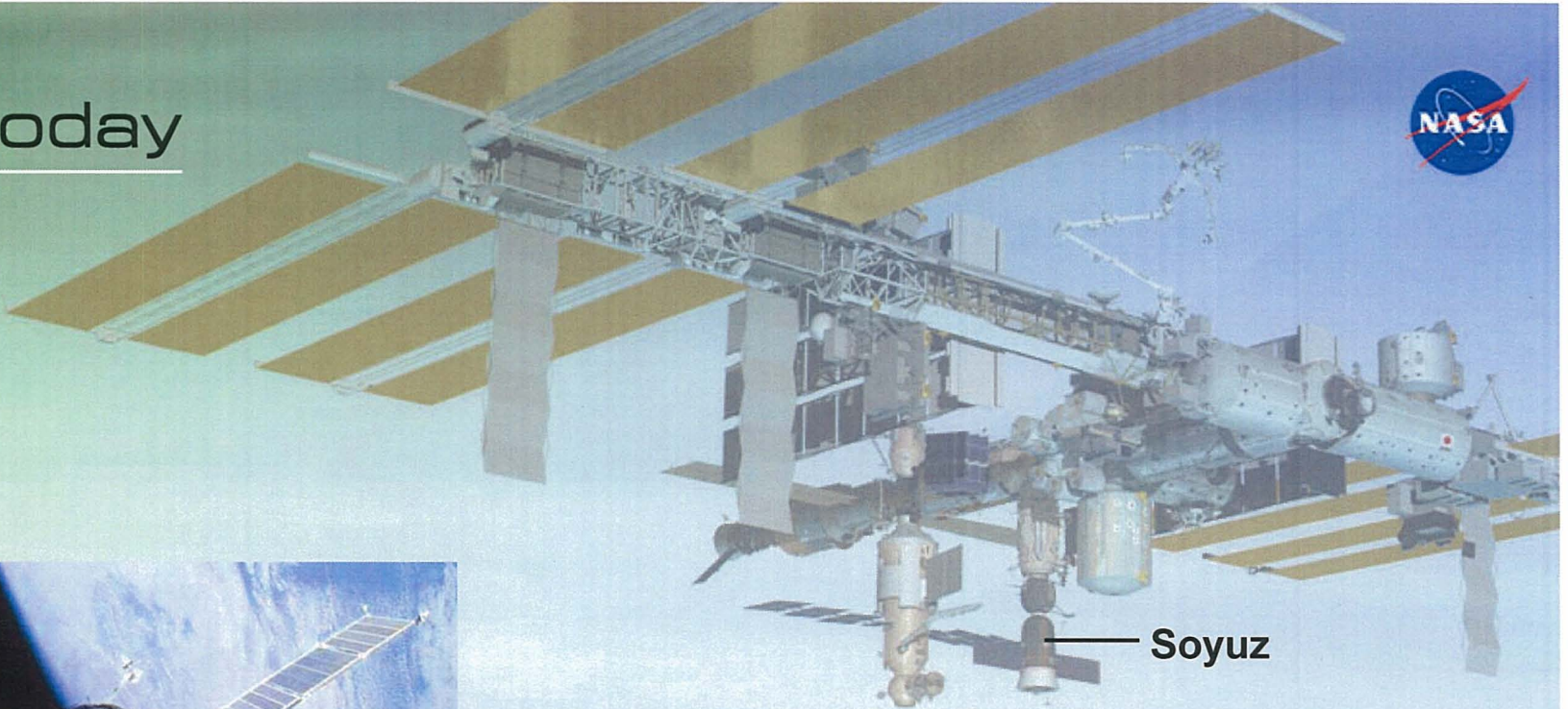
Progress



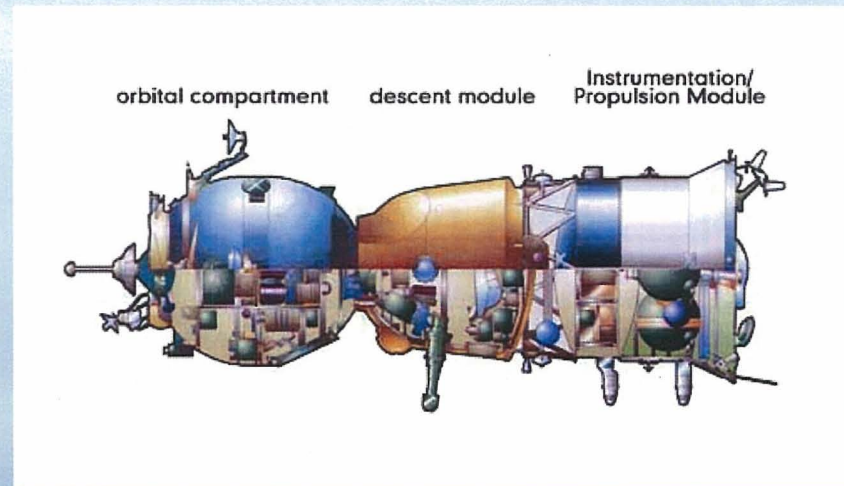
Progress approaching station

Supplies and fuel are brought to the Station by the Russian Progress vehicle, which also boosts the Station's orbit when needed.

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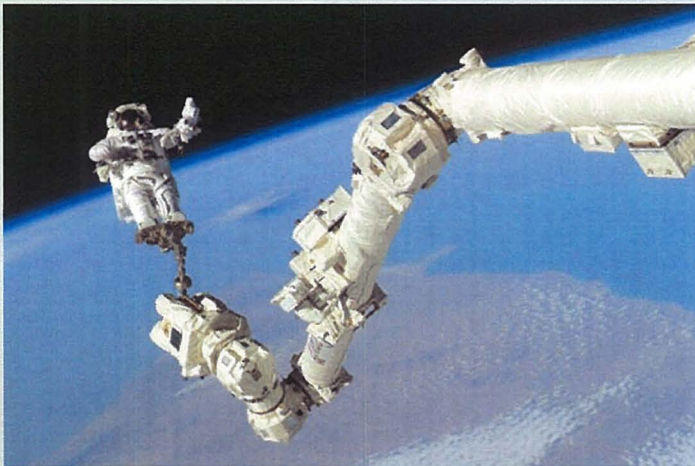
The Soyuz, replaced every six months, provides crew rotation and emergency evacuation.



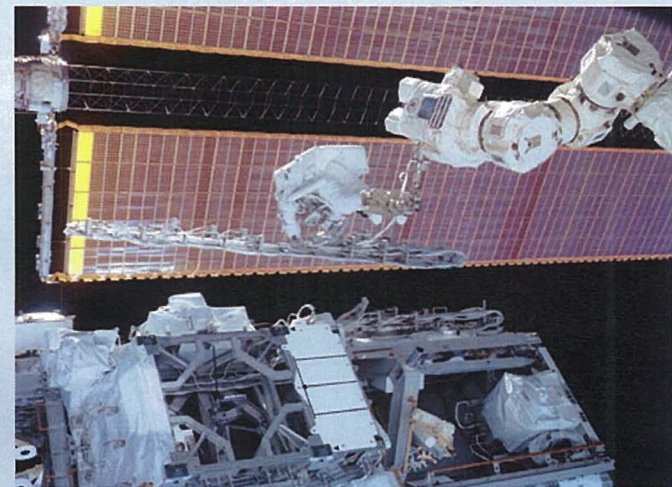
ISS today



— Canadarm2

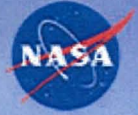


During space walks astronauts are able to maneuver and assemble the Station's massive elements with the help of the Canadian robotic arm system.

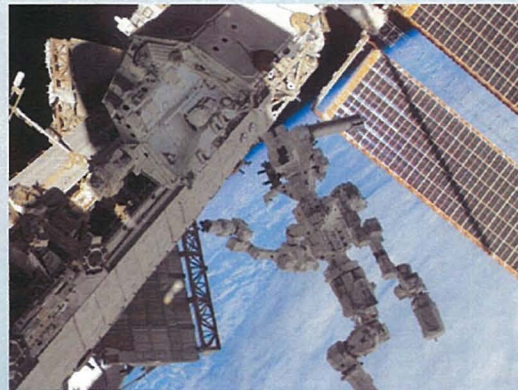
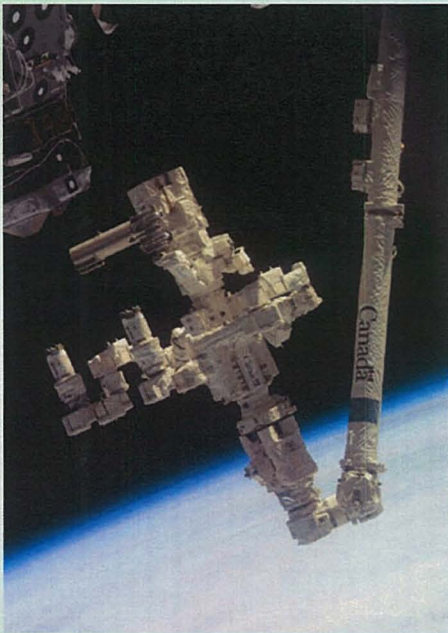


INTERNATIONAL SPACE STATION

ISS today

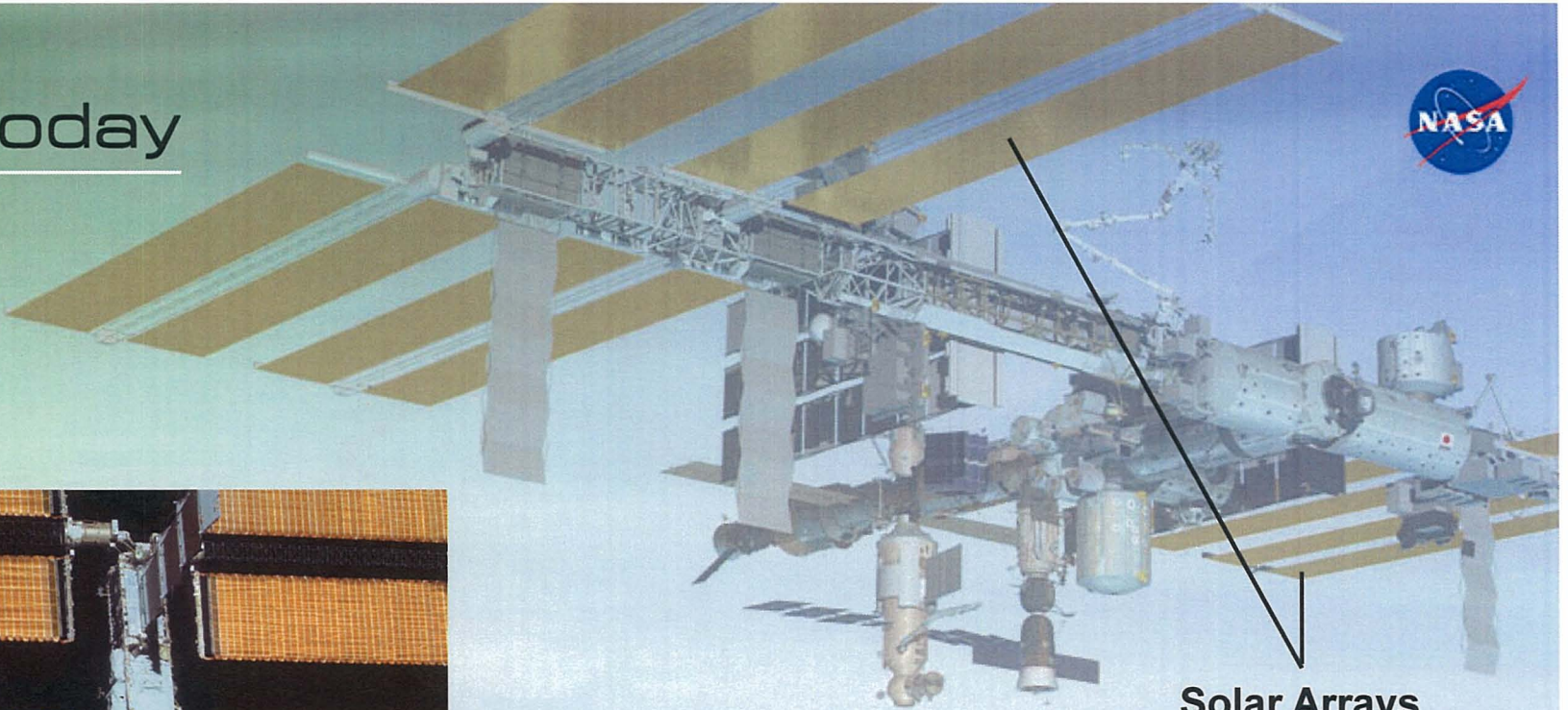


Dextre

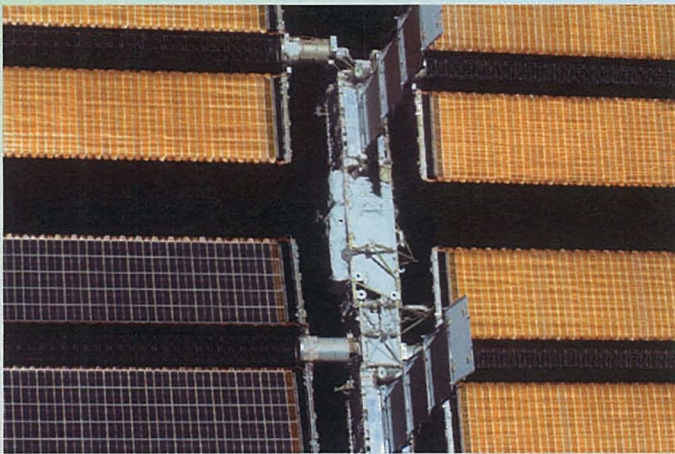


“Dextre”, or the Special Purpose Dexterous Manipulator, is the final element of the Station’s Mobile Servicing System. It works with the Station’s robotic arm (Canadarm2) for Station maintenance and service.

ISS today



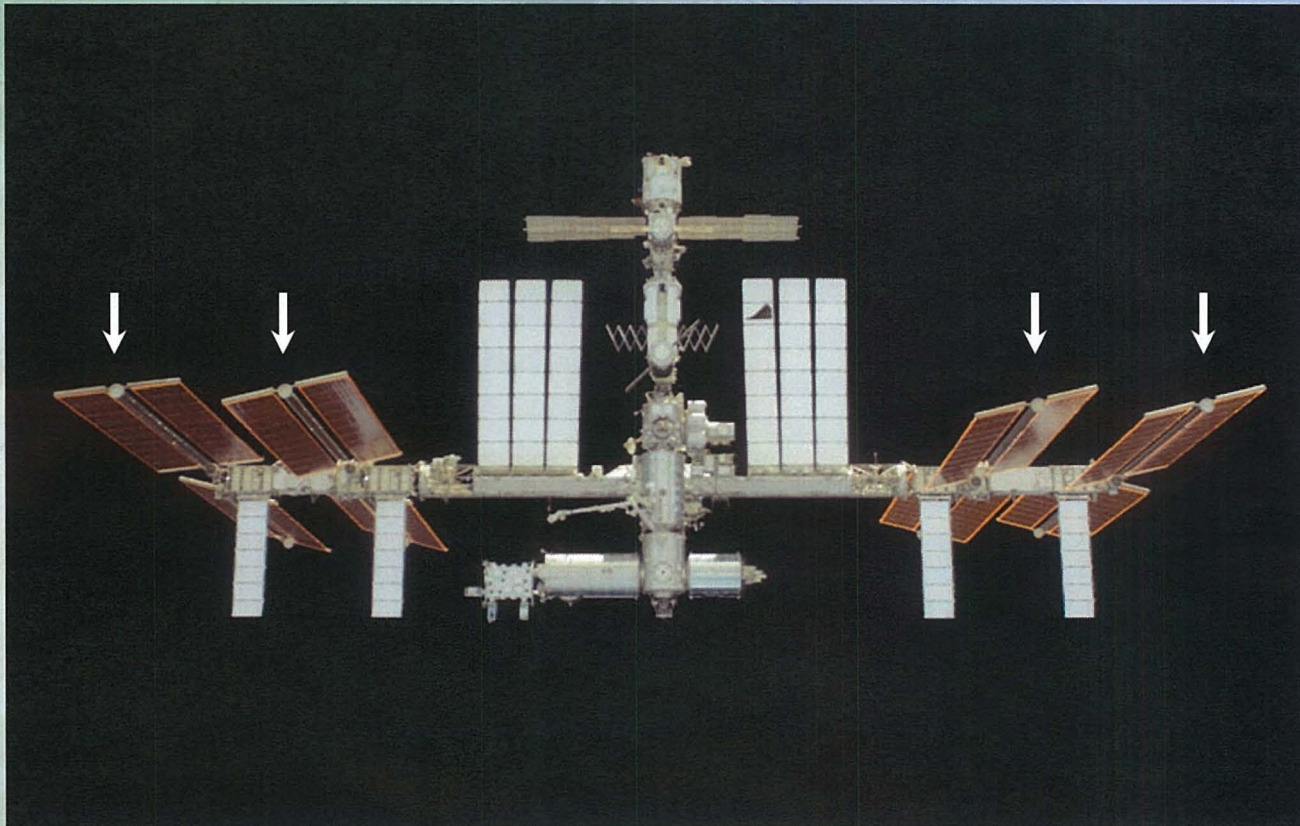
Solar Arrays



In Earth orbit, the most practical and main source of power for the Station is sunlight, converted by the Solar Array panels. During the shadow phase, the Space Station relies on banks of nickel-hydrogen rechargeable batteries to provide a continuous power source.



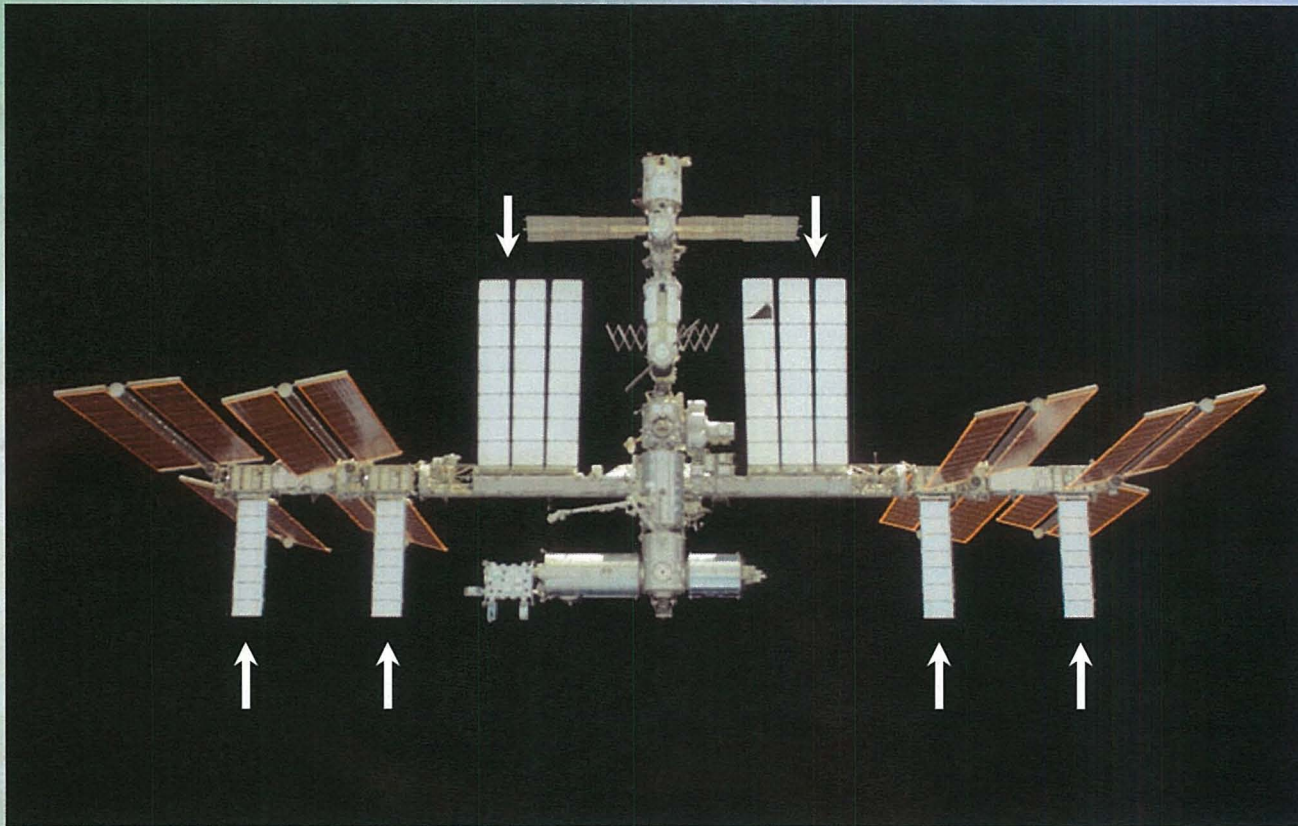
Electrical power subsystem



The four U.S. Solar Arrays provide up to 120 kW of power for life support, battery charging, and other power management use, enough to power 40 average homes.



Thermal control subsystem



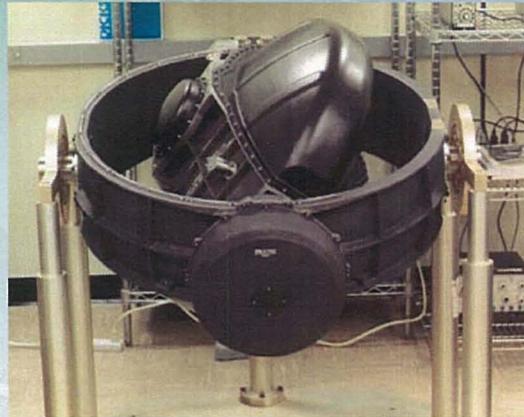
The Station's outstretched radiators are made of honey-comb aluminum panels, each providing 6 by 10 feet of ammonia tubing filled heat exchange area.



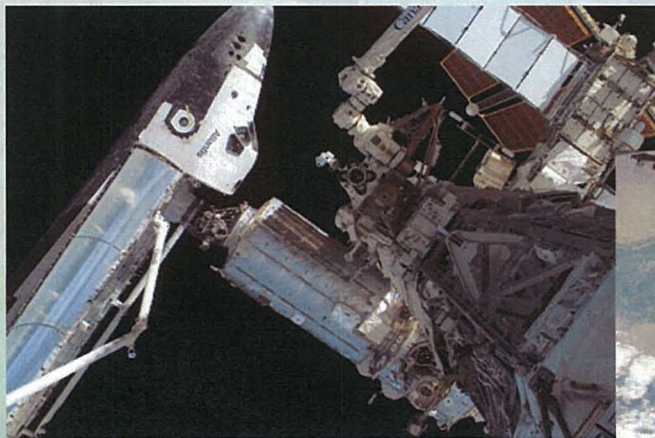
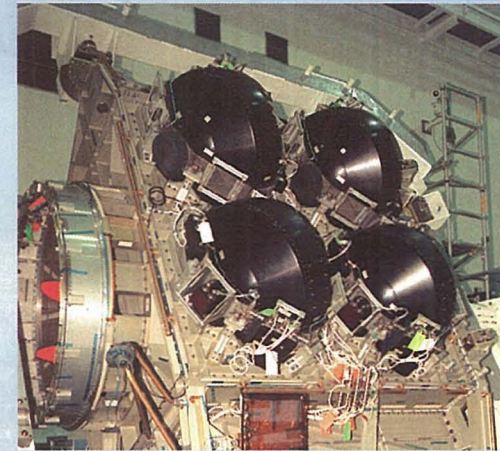
Guidance, navigation, and control

Electrical powered attitude control provided by four U.S. Control Moment Gyros.

Service Module (“Zvezda”) jets can also be used.



CMGs

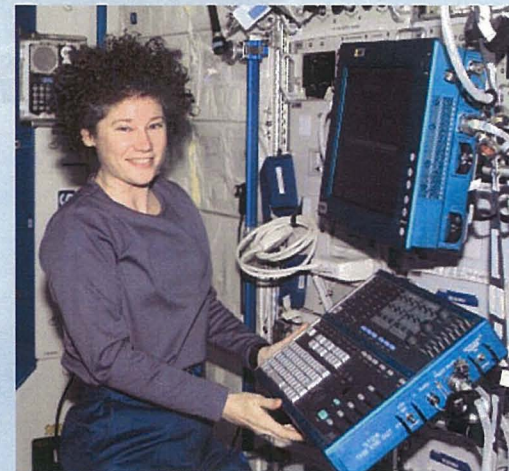


The Shuttle and the Progress are used to boost the Station when docked.



Command data and handling

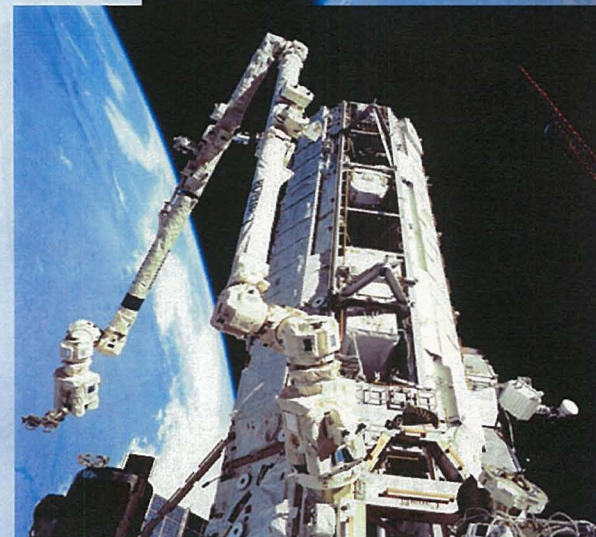
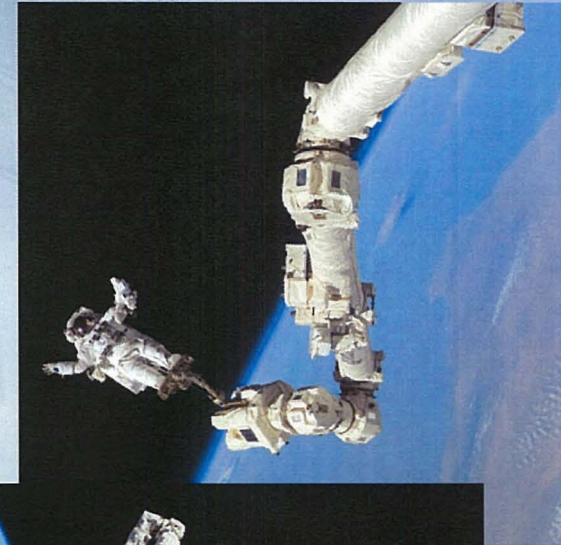
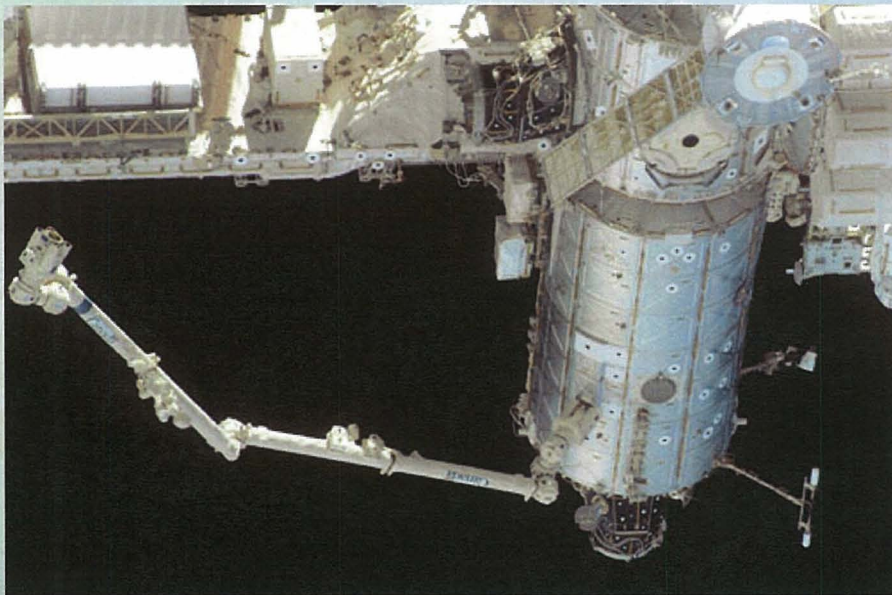
The Space Station systems are controlled by over 4 million lines of software code, about half provided by the U.S. in core computers (MDMS) and laptops, and the balance from the other international partners.



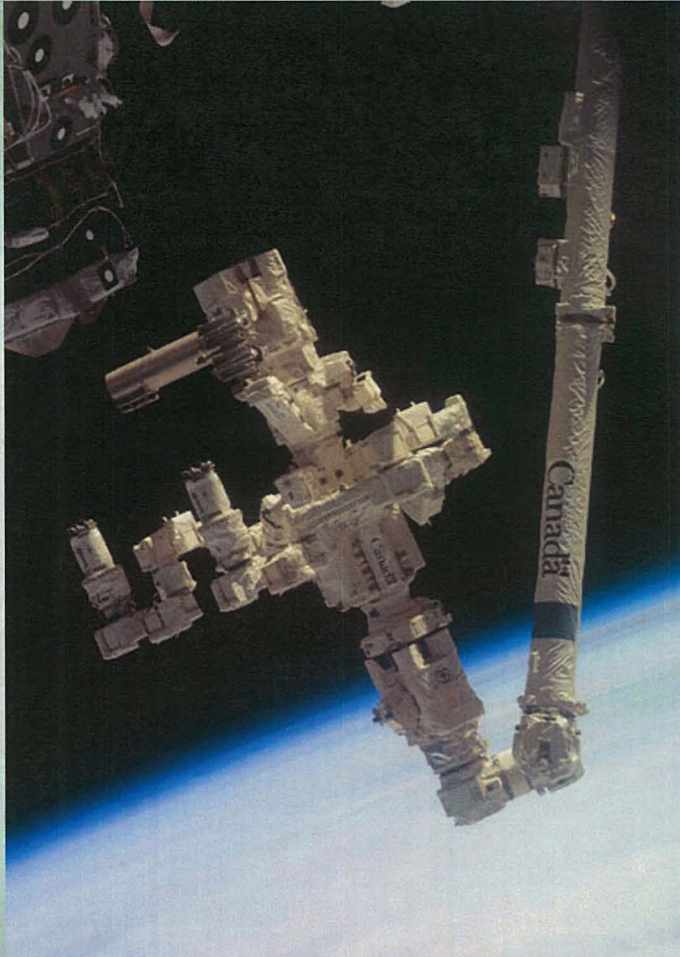


Robotics

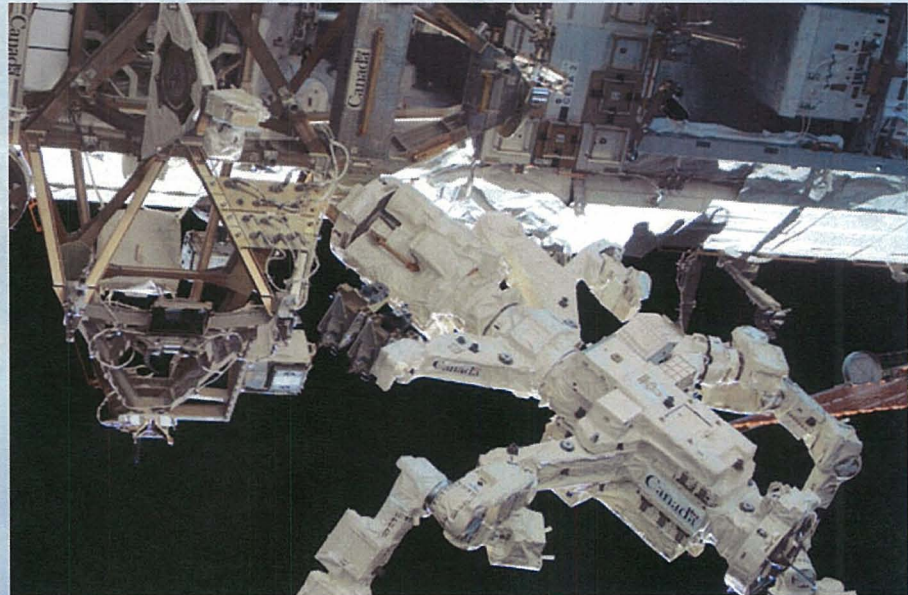
Canadarm2 represents next-generation robotics. By flipping end-over-end between anchor points it can move around the ISS like an inchworm. With its seven joints, Canadarm2 is more maneuverable than its predecessor on the shuttle and even more agile than a human arm.



Robotics



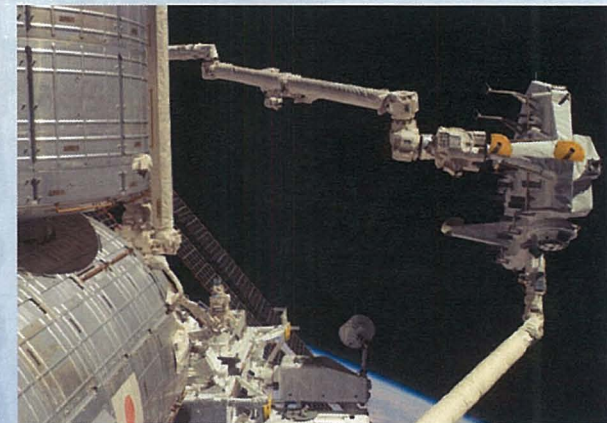
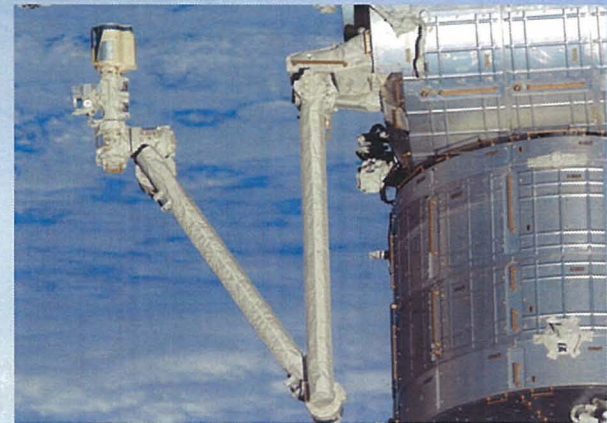
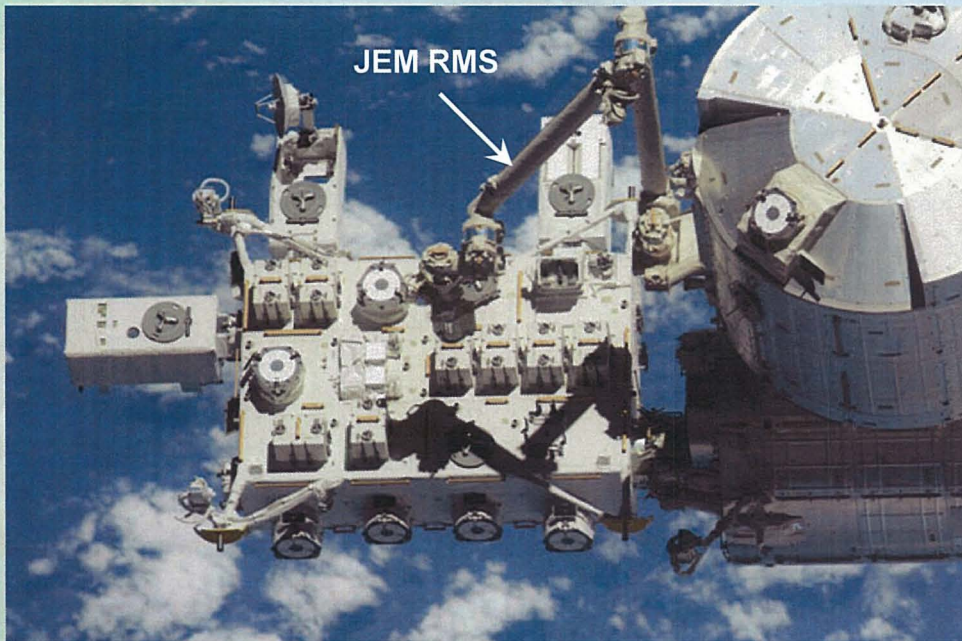
Dextre, or Special Purpose Dexterous Manipulator, is the final element of the station's Mobile Servicing System. Designed for station maintenance and service, it has two arms and four cameras and is able to work from the end of Canadarm2 or the station's Mobile Base System.



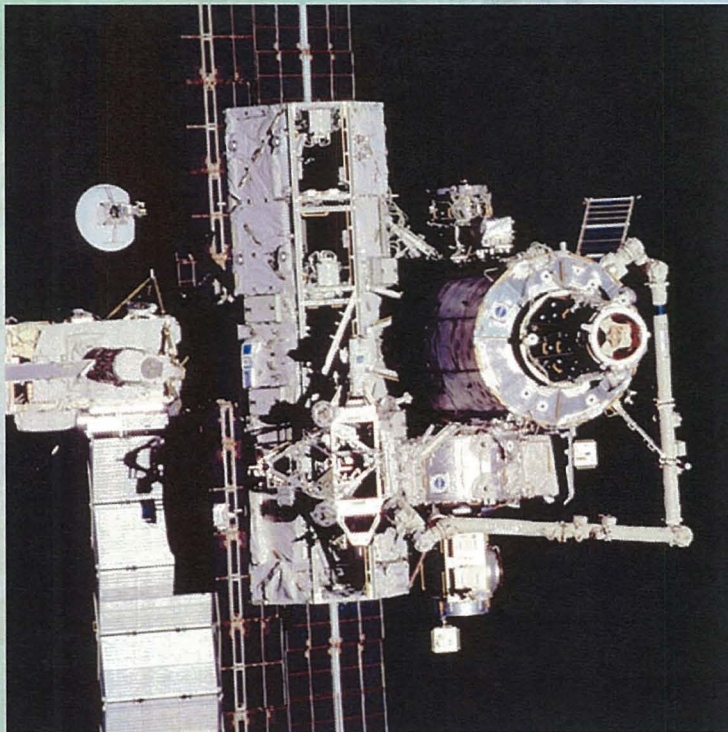


Robotics

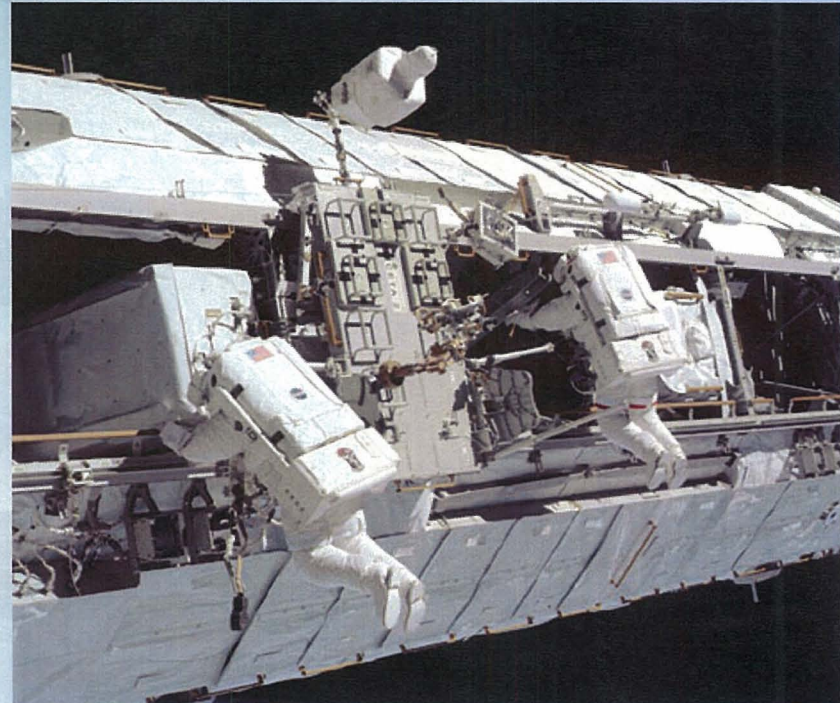
The JEM Remote Manipulator System (JEMRMS) is a robotic arm developed for supporting experiment and maintenance activities on the exposed areas of the "Kibo" science lab.



Robotics



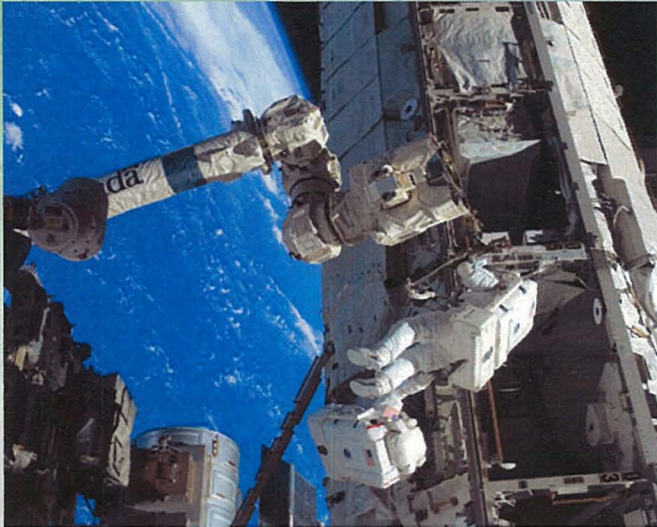
Mobile Base System



**Crew Equipment and Translation
Aid Cart (CETA)**



Human and robotic integration



The ISS is advancing human and robotic space operations to new heights experimenting with tools and equipment in the challenging environment of space.

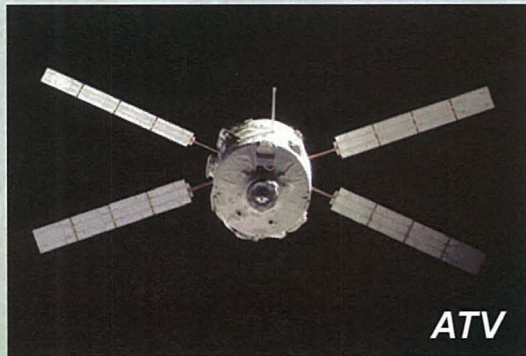




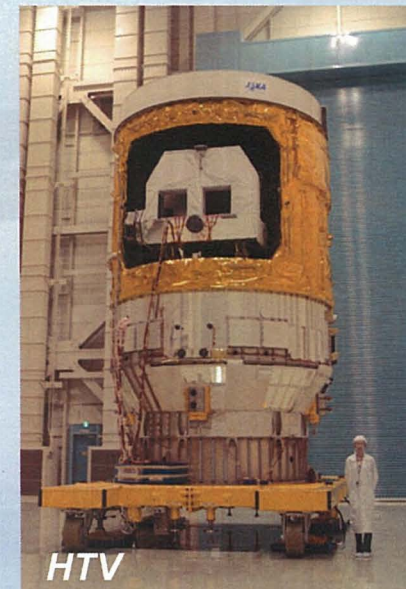
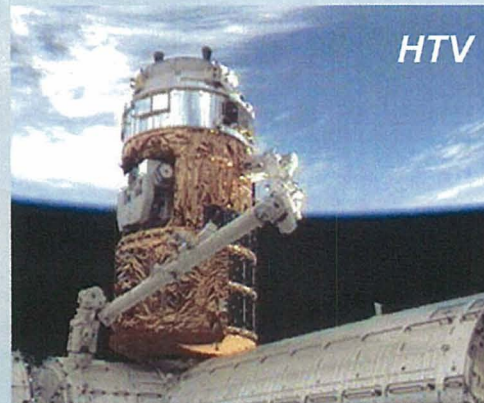
Additional modes of re-supply



The European Space Agency's three Italian built Multi-Purpose Logistics Modules (MPLM) - Leonardo, Raffaello, and Donatello - are brought to the Station in the shuttle's payload bay. ESA has also successfully docked and undocked their first unmanned Automated Transfer Vehicle (ATV).



Japan has also built, launched and docked the unmanned HII Transfer Vehicle (HTV), that will perform additional logistics and re-supply functions in the future.





A springboard for many futures

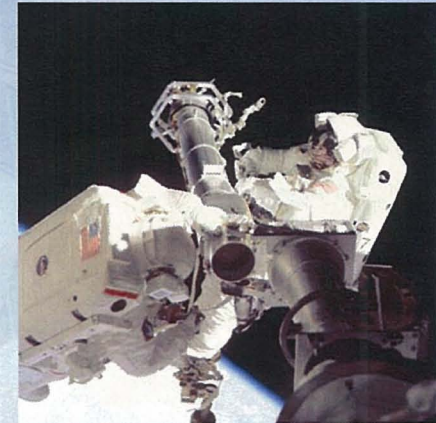
Science Leads the Way

Space Engineering

Exploration of the Universe

Space Commerce test bed

Inspiring the Next Generation



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