



Near Earth Asteroid Scout Mission

AIAA Space 2014

7 August 2014

Andrew Heaton (NASA/MSFC)

Julie Castillo-Rogez (JPL/Caltech/NASA)

Andreas Frick (JPL/Caltech/NASA)

Wayne Hartford (JPL/Caltech/NASA)

Les Johnson (NASA/MSFC)

Laura Jones (JPL/Caltech/NASA)

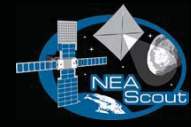
Leslie McNutt (NASA/MSFC)

And the NEA Scout Team

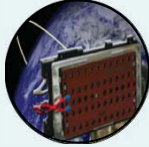
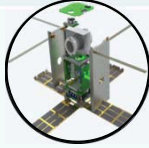





SLS EM-1 Secondary Payload Overview

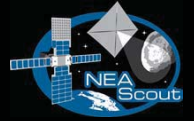


- HEOMD's Advanced Exploration Systems (AES) selected 3 concepts for further refinement toward a combined Mission Concept Review (MCR) and System Requirements Review (SRR) planned for August 2014
- Primary selection criteria:
 - Relevance to Space Exploration Strategic Knowledge Gaps (SKGs)
 - Life cycle cost
 - Synergistic use of previously demonstrated technologies
 - Optimal use of available civil servant workforce
- Project in Pre-formulation
- Completed a Non-Advocate Review of the Science Plan

Payload <i>NASA Centers</i>	Strategic Knowledge Gaps Addressed	Mission Concept
BioSentinel <i>ARC/JSC</i> 	Human health/performance in high-radiation space environments <ul style="list-style-type: none"> • Fundamental effects on biological systems of ionizing radiation in space environments 	Study radiation-induced DNA damage of live organisms in cis-lunar space; correlate with measurements on ISS and Earth
Lunar Flashlight <i>JPL/MSFC</i> 	Lunar resource potential <ul style="list-style-type: none"> • Quantity and distribution of water and other volatiles in lunar cold traps 	Locate ice deposits in the Moon's permanently shadowed craters
Near Earth Asteroid (NEA) Scout <i>MSFC/JPL</i> 	Human NEA mission target identification <ul style="list-style-type: none"> • NEA size, rotation state (rate/pole position) How to work on and interact with NEA surface <ul style="list-style-type: none"> • NEA surface mechanical properties 	Flyby/rendezvous and characterize one NEA that is candidate for a human mission



NEA Scout Overview



Why NEA Scout?

- Characterize a NEA with an imager to address key Strategic Knowledge Gaps (SKGs)
- Demonstrates low cost reconnaissance capability for HEOMD (6U CubeSat)

Leverages:

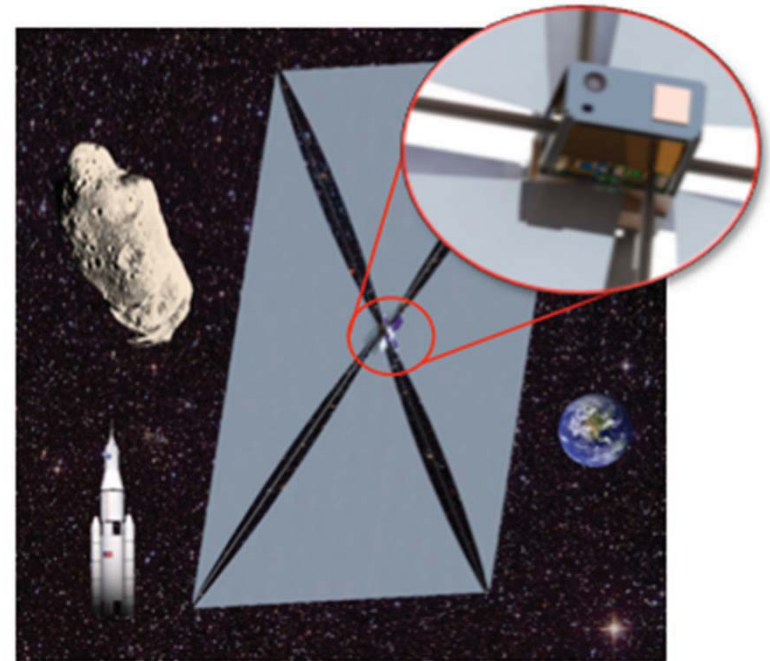
- Solar sail development expertise (NanoSail-D, Sunjammer, LightSail-1)
- CubeSat developments and standards (INSPIRE, University & Industry experience)
- Synergies with Lunar Flashlight are in review (Cubesat bus, solar sail, communication system, integration & test, operations)

Measurements: *NEA volume, spectral type, spin mode and orbital properties, address key physical and regolith mechanical SKG*

- $\geq 80\%$ surface coverage imaging at ≤ 50 cm/px
- Spectral range: 400-900 nm (incl. 4 color channels)
- $\geq 30\%$ surface coverage imaging at ≤ 10 cm/px

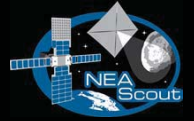
Key Technical Constraints:

- 6U Cubesat and ~ 80 m² sail to leverage commonalities with Lunar Flashlight, expected deployer compatibility and optimize cost
- Target must be within 1 AU distance from Earth due to telecom limitations
- Slow flyby with target-relative navigation on close approach

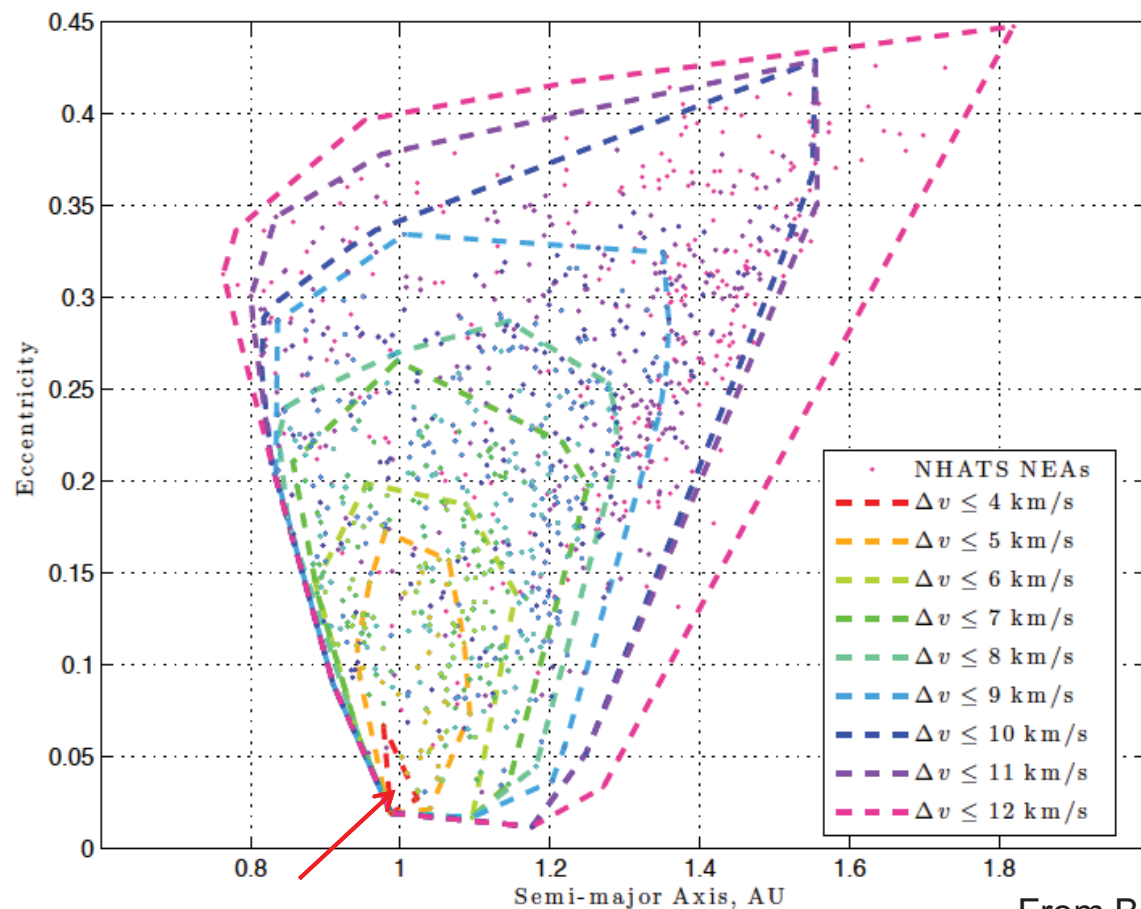




NEA Scout Targets an NHAT



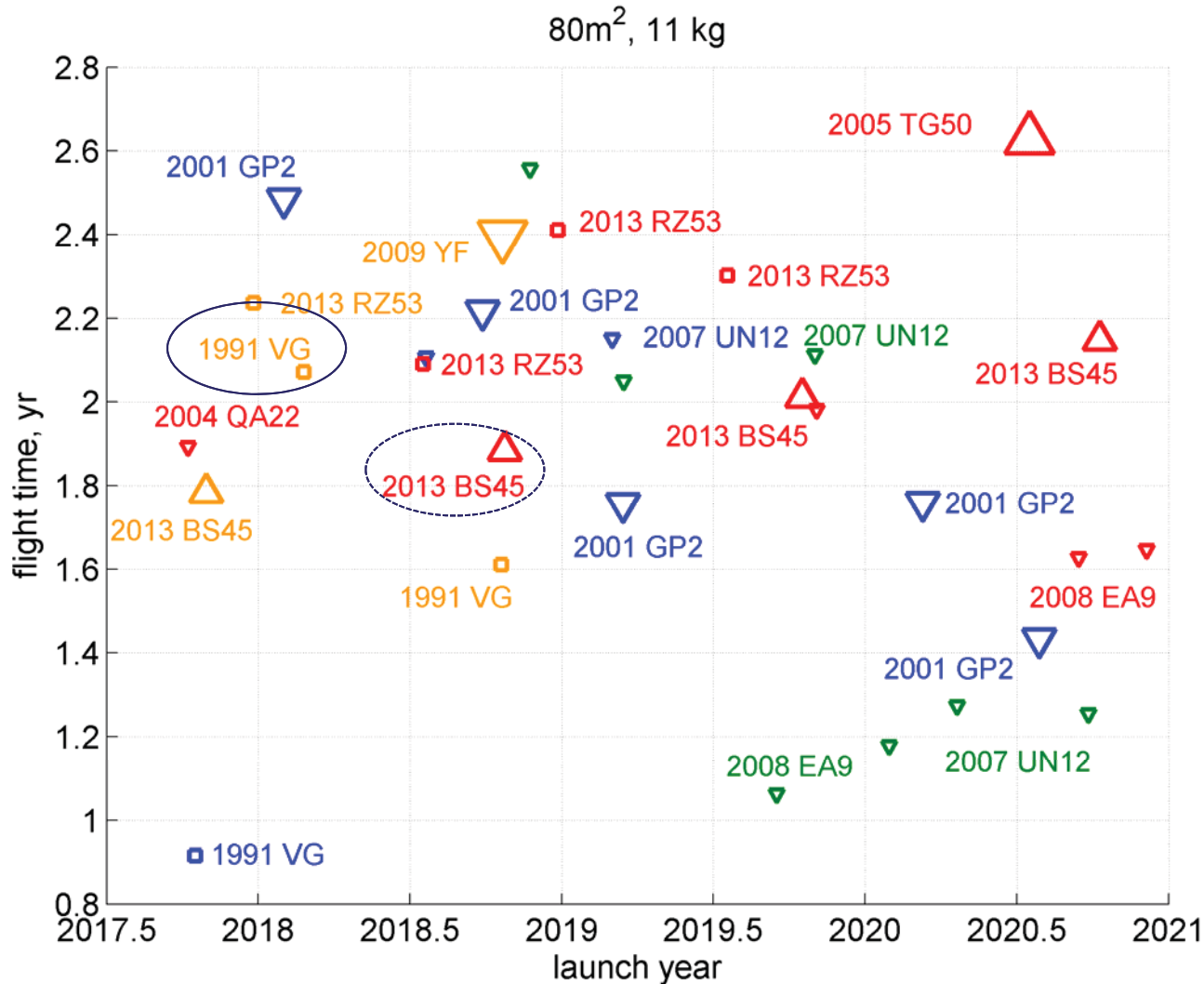
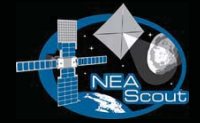
- NHATS database contains targets from 1 m to >1 km
 - Do not all carry same value: low orbit condition code, >10 m, synodic period < 10 yr are of high priority
- Targets accessible to NEA Scout are < 50m



From B. Barbee (2013)



Rendezvous Target Search



- **Telecom Distance (AU)**

- blue < .25
- green < .5
- orange < .75
- red < 1

- **OCC**

- △ under 2
- under 4
- ▽ under 7

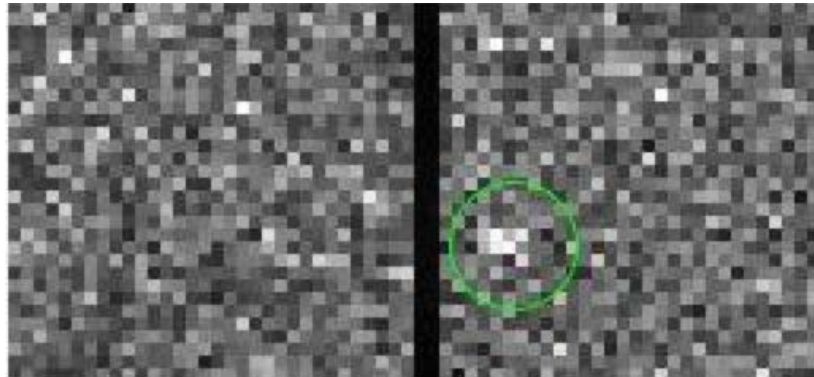
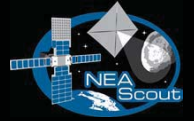
- **Size (appx dia.)**

- small < ~15 m
- med. < ~30 m
- large < ~50 m

*Local minima for flight time. Flight time increases linearly with pre-escape loiter time
Flight time increases non-linearly with delayed escapes*



What Do We Know About 1991 VG and Backups



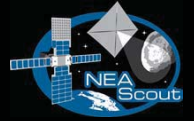
2013 BS45 (radar, courtesy of Lance Benner):

- $H=28.4 \pm 0.7$
- Diameter ~ 5-12 meters
- Albedo is unknown
- Rotation period between a few minutes and less than 1 hr
- Unlikely to have a companion
- Likely did not retain an exosphere or dust cloud
 - Solar radiation pressure sweeps dust on timescales of hours or day

NEA	Absolute magnitude	30% albedo Diameter (m)	5% albedo Diameter (m)	Orbit Condition Code	Observation Opportunity prior to launch
1991 VG	28.5	5	12	2	2017-07 (Optical)
2001 GP ₂	26.9	10	25	6	Depends on launch date 2020-10 (Optical)
2013 BS45	25.9	11	51	0	2015-01 (Optical)
2008 EA ₉	27.7	7	17	5	none
2012 UV ₁₃₆	25.5	19	47	1	2014-08 (Optical) 2020-05 (RADAR)



Prioritized Strategic Knowledge Gaps

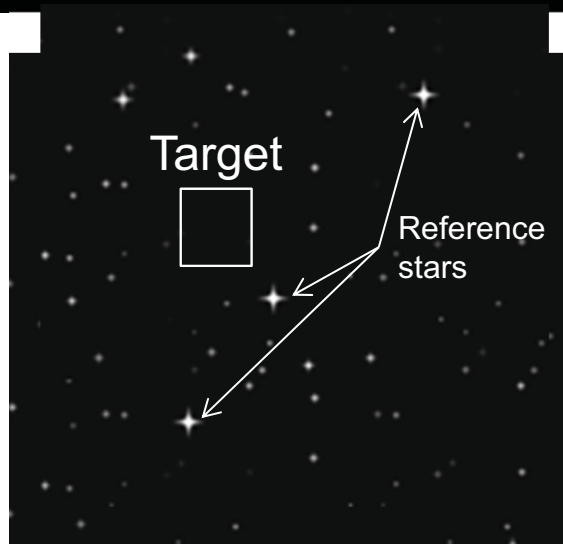
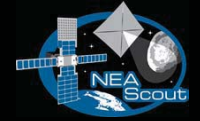


HEO-Defined Strategic Knowledge Gaps	Expected Performance	Risk Reduction or Benefit
Location (position prediction/orbit)	OCC decrease to 0	● ● ●
Size (existence of binary/ternary)	High accuracy on size, detection of satellites	● ● ● ●
Rotation rate & pole orientation	High accuracy on pole and velocity	● ● ● ●
Particulate environment/Debris field	Depends on flyby vs. rendezvous	● ● ● ● ●
Regolith mechanical & geotechnical properties	Indirect (imagery interpretation)	● ● ● ● ●
Mass/density estimates (Internal structure)	Indirect (based on taxonomic characterization)	● ● ● ●
Surface morphologies and properties	Depends on flyby vs. rendezvous	● ● ● ● ●
Mineralogical & chemical composition	Indirect from taxonomic characterization	● ● ● ● ●

● Crew/Mission ● Operations ● Cost ● Performance ● Science/Engineering

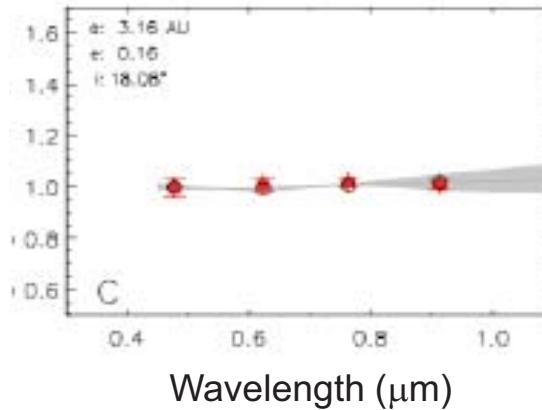


Summary: NEAScout Observation Plan



Target Detection and Approach

SNR >1.5 of target at 10K km, before frame co-adding, spectral class
SKGs: Ephemeris determination and composition assessment



Target Reconnaissance

50 cm/px resolution over 80% surface

SKGs: volume, global shape, spin rate and pole position determination



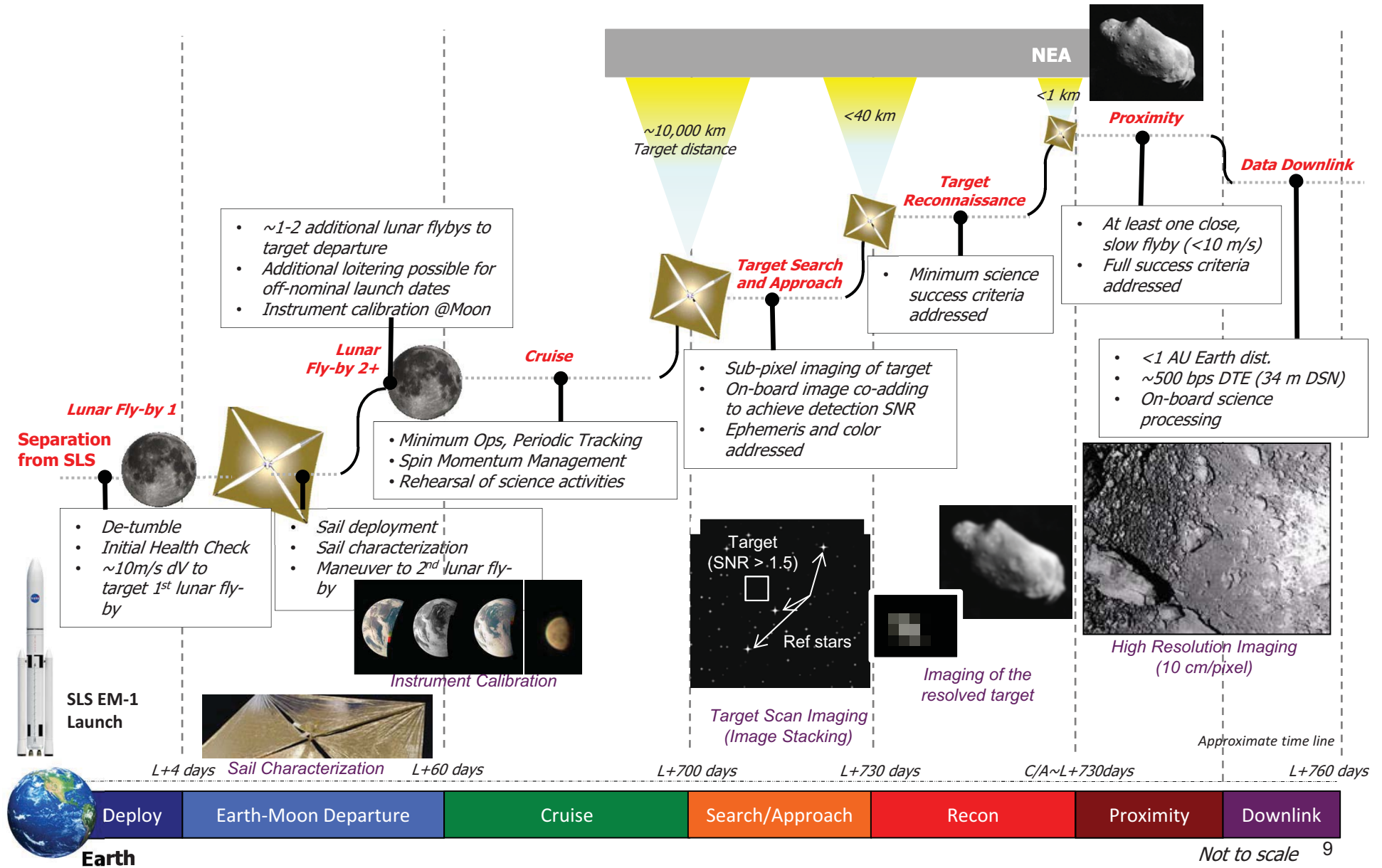
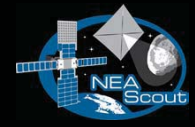
Close Proximity Imaging

High-resolution imaging,
10 cm/px GSD

SKGs: Medium-scale morphology, regolith properties, and local environment characterization

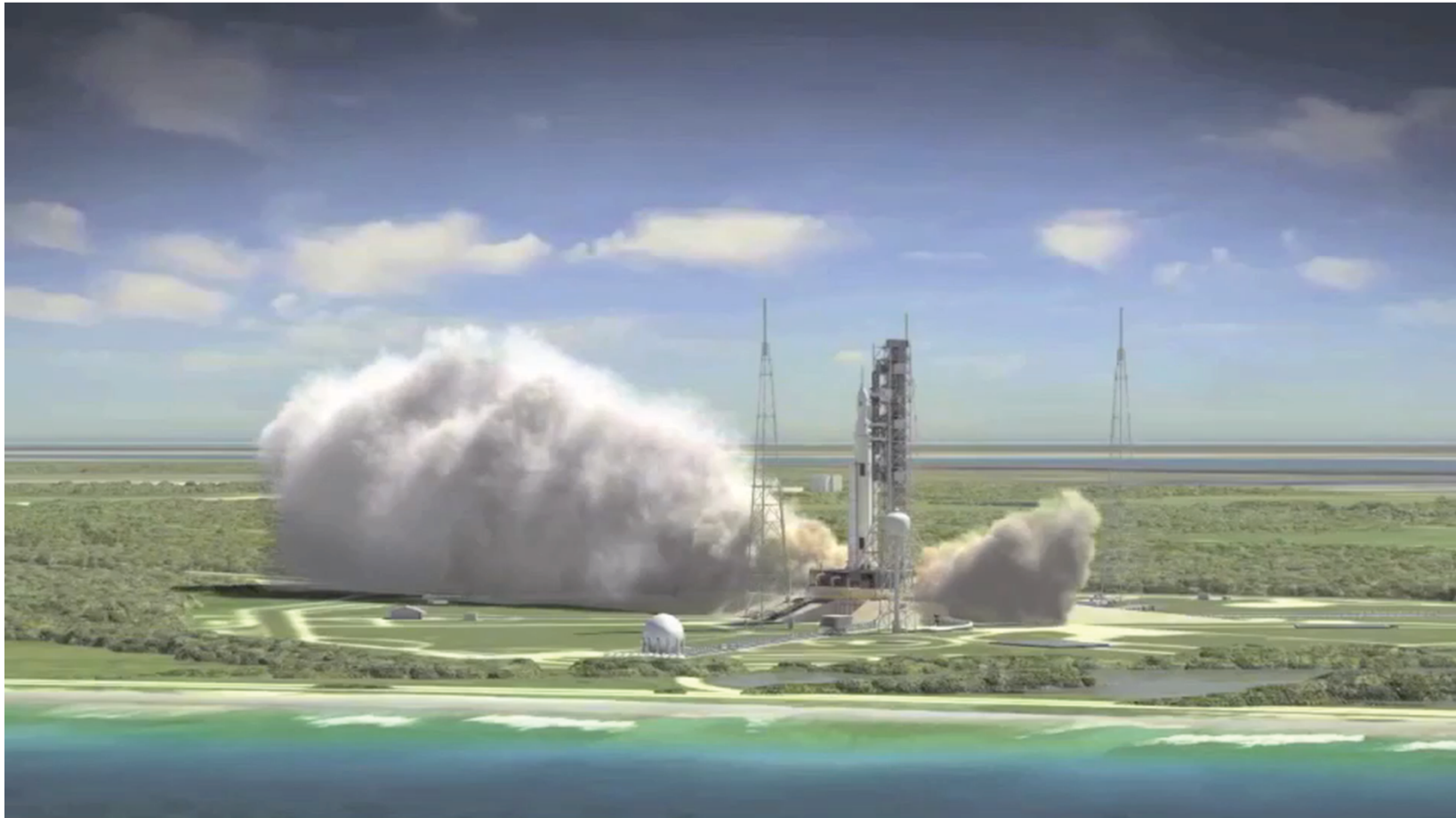
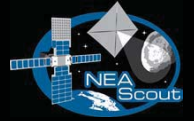


NEA Scout ConOps Summary



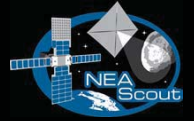


NEA Scout Animation

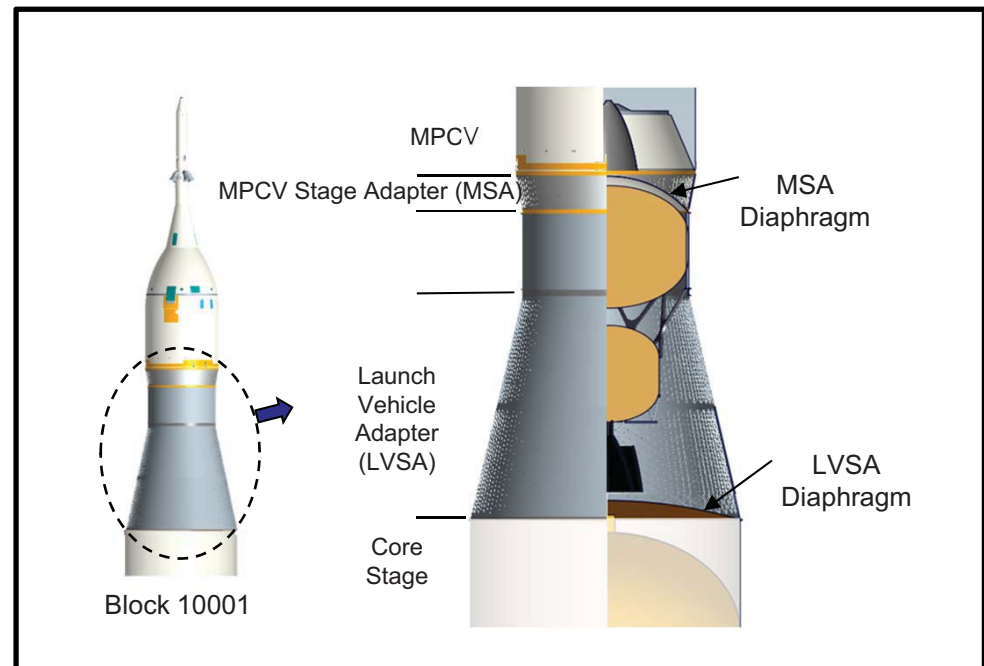
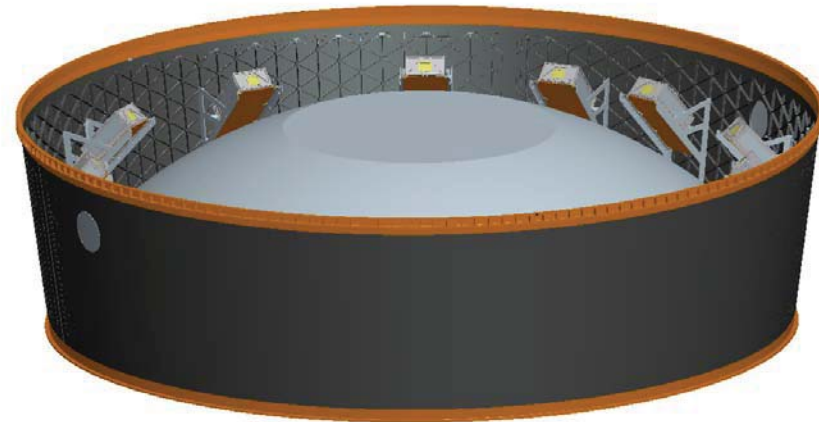




SLS Integration

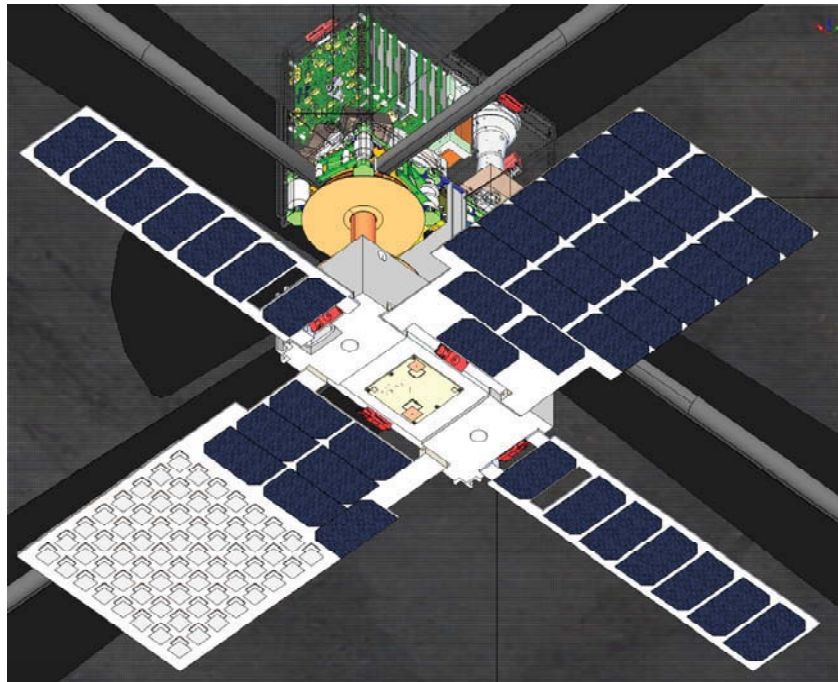
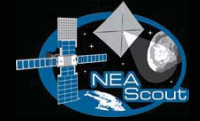


- Notional Launch on SLS EM-1 (Dec. 2017)
- Secondary payloads will be integrated on the MPCV stage adapter (MSA) on the SLS upper stage.
- Secondary payloads will be deployed on a trans-lunar trajectory after the upper stage disposal maneuver.





NEA Scout Flight System Overview



Mission: Retire Strategic Knowledge Gaps at a Near-Earth Asteroid

Launch Opportunity: SLS EM-1 (Dec. 2017 notional launch)

Bus: JPL Deep Space NanoSat Bus (based on INSPIRE)

Form Factor: "6U" CubeSat (<12kg)

Main Propulsion: MSFC ~80 m² Solar Sail (based on NanoSail-D)

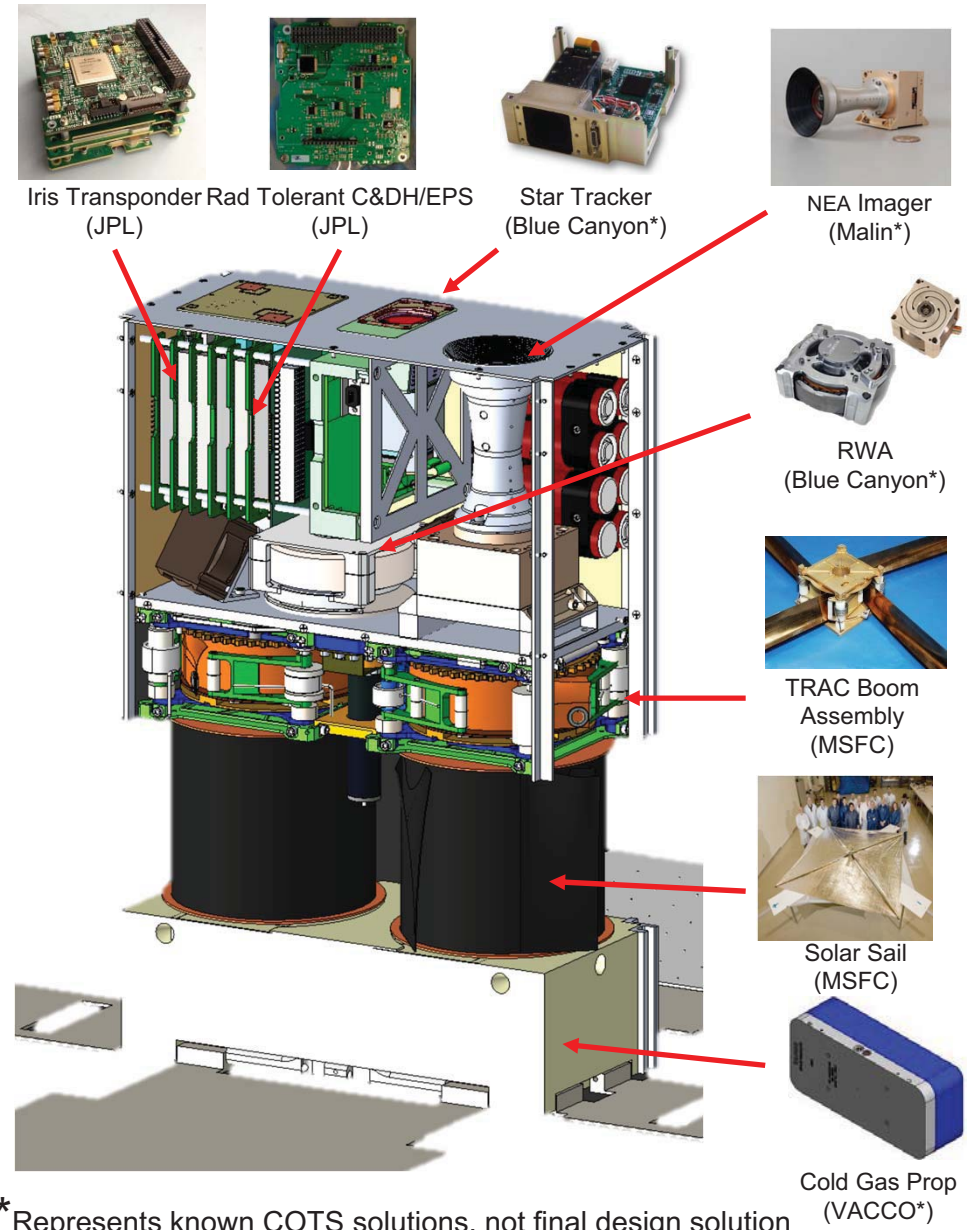
Payload: COTS NEA Imager, e.g. MSSS ECAM M-50

Command & Data Sys.: Radiation tolerant LEON3 architecture

Attitude Control: 3-Axis Control (Zero-momentum spin cruise)

Electrical Power: ~35W (@1 AU)

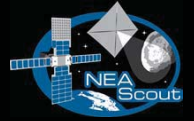
Telecom: JPL Iris, INSPIRE LGA (2 Pair) + Microstrip Array HGA
(~500 bps @ 0.75 AU to 34m DSN)



* Represents known COTS solutions, not final design solution

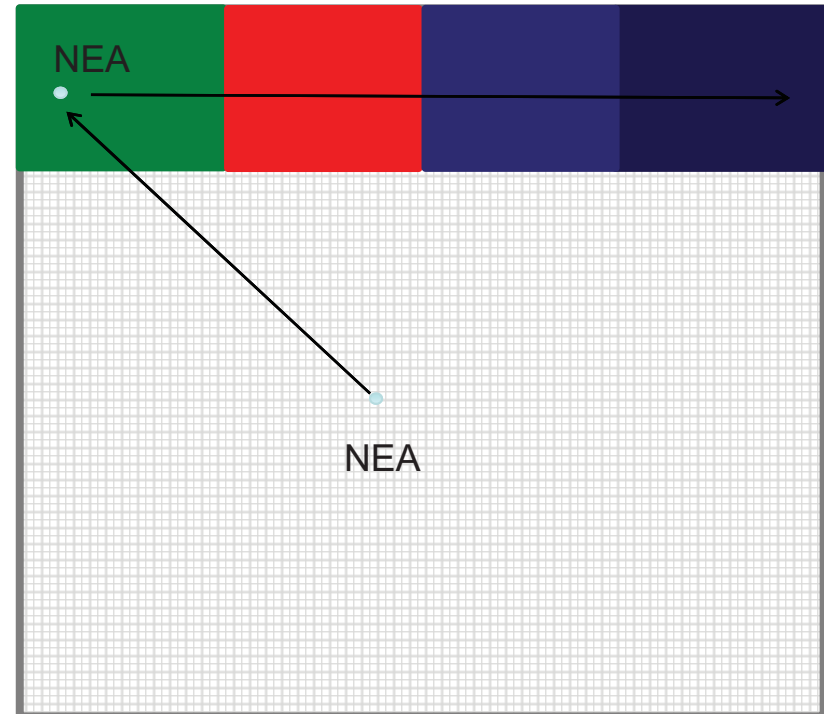
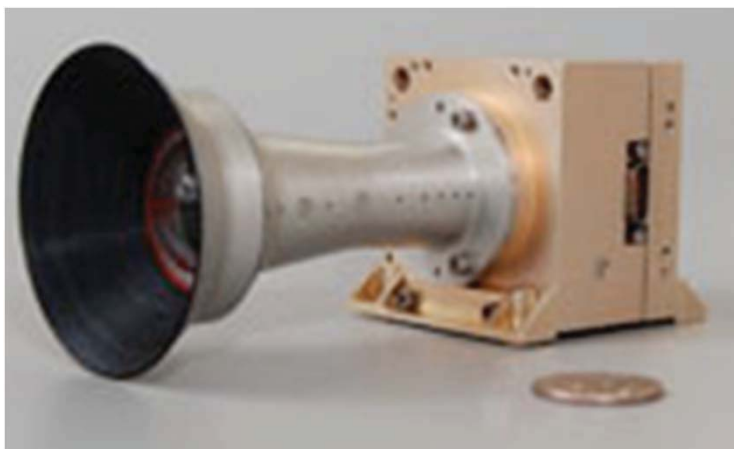


Instrument Concept

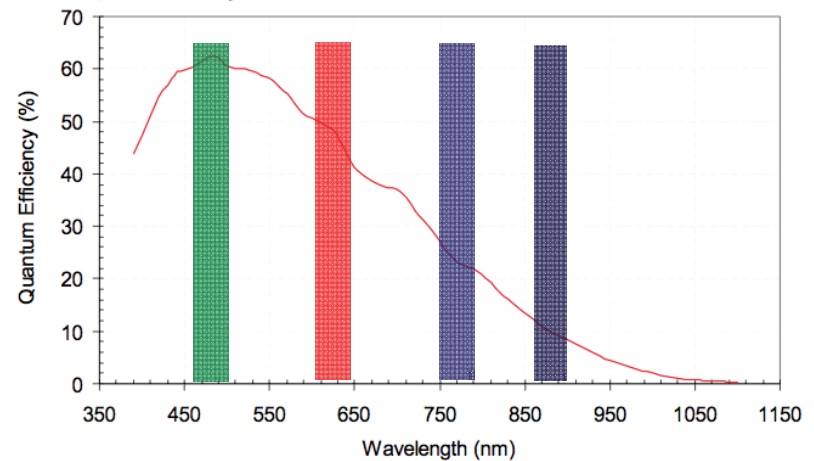


Baseline

- MSSS ECAM M-50 camera with NFOV lens
- COTS, TRL 8 via OSIRIS-Rex, excellent IFOV & FOV, volume, power
- Aptina MT9P031 FPA

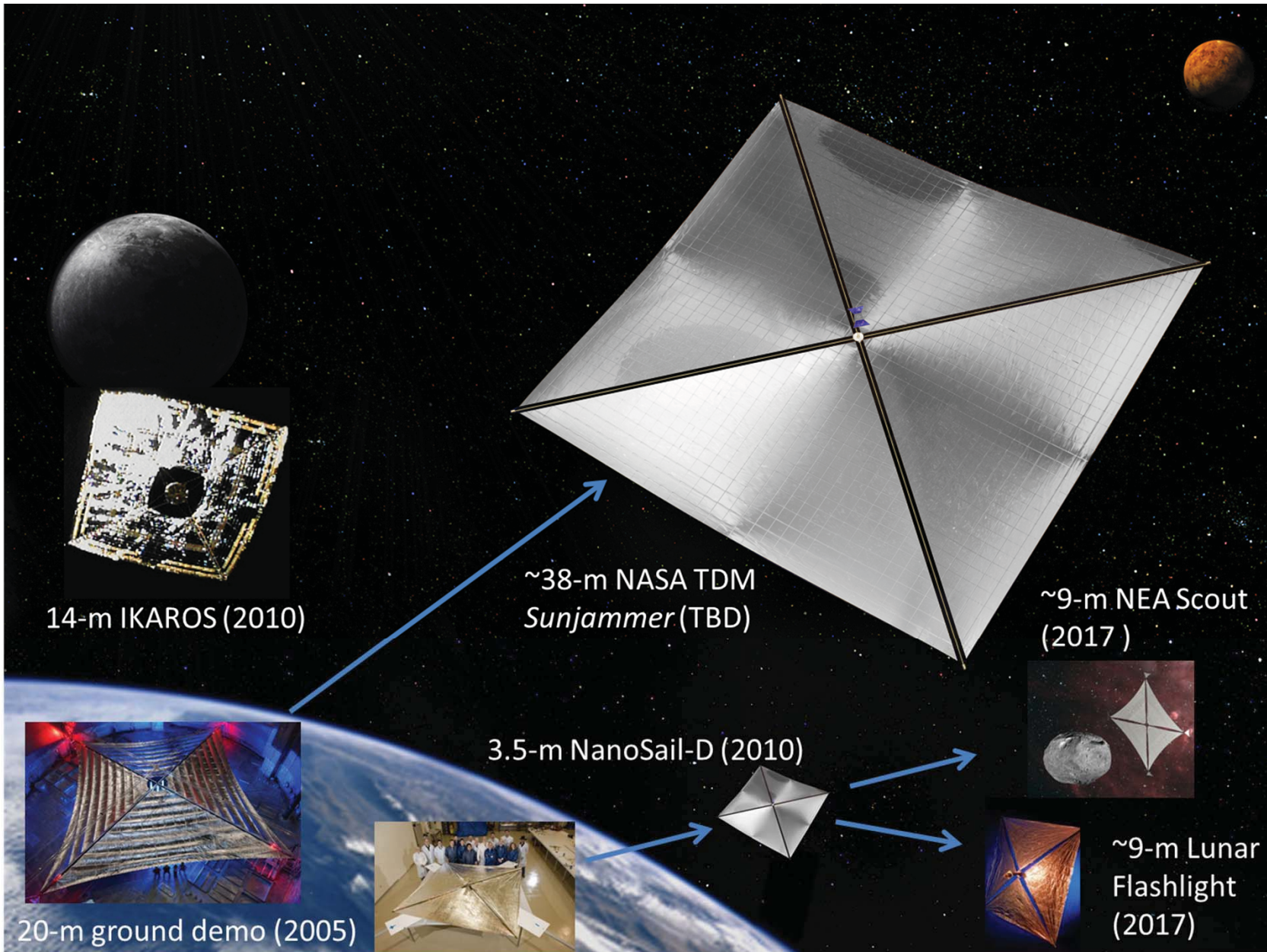
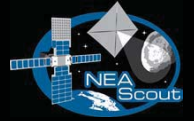


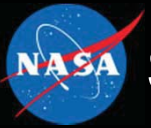
Monochrome Quantum Efficiency



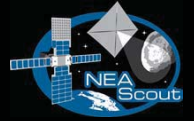


Solar Sail Propulsion Summary

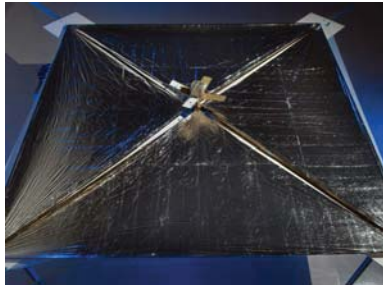




Solar Sail Design



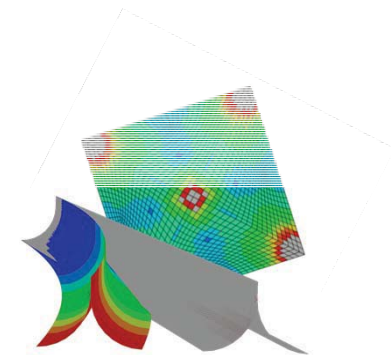
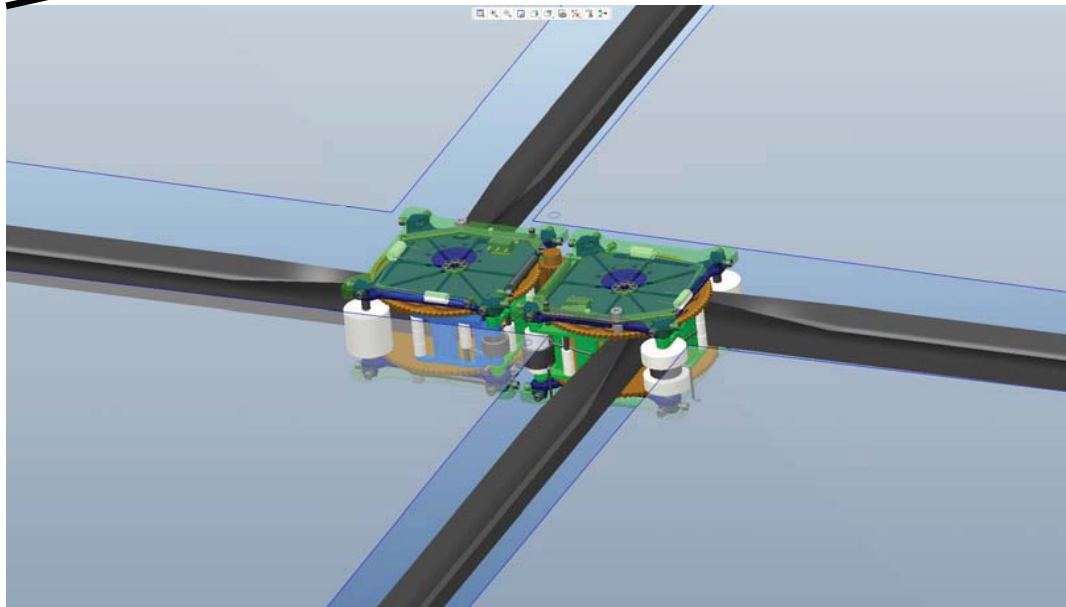
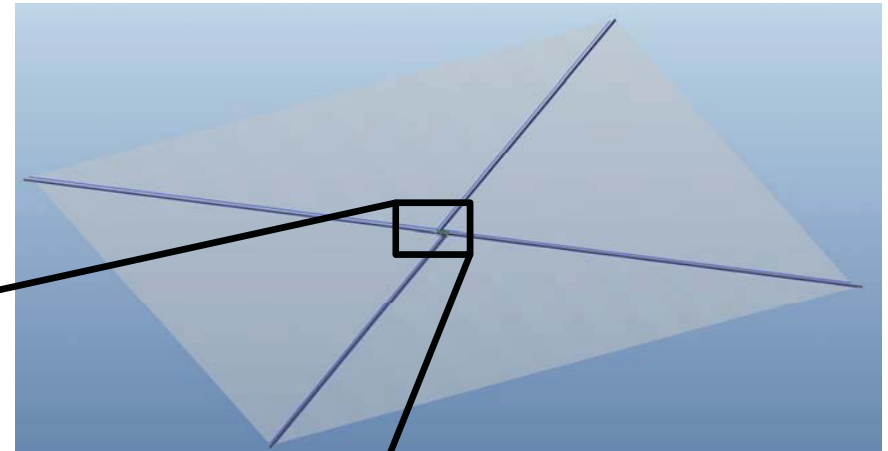
Sail Design by MSFC



NanoSail-D2 (flown in 2010)



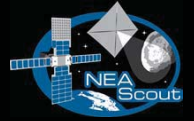
TRAC Boom Deployer



Structural Analysis by LaRC



ACS Architecture



Spinning Sail

- Induce a slow, 1 rev/hour spin about the norm of the sail
- Averages momentum accumulation over mission

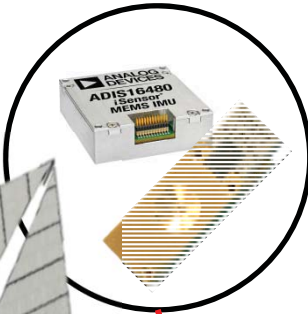
Pointing Algorithms

- Pointing accuracy for thrust vectoring, LF science
- Pointing stability for NEAS science



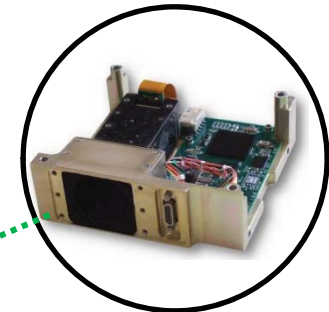
Zero-Momentum RWA

- One 100 mNms wheel
- Controls spin of the sail
- Maintain a zero-momentum system



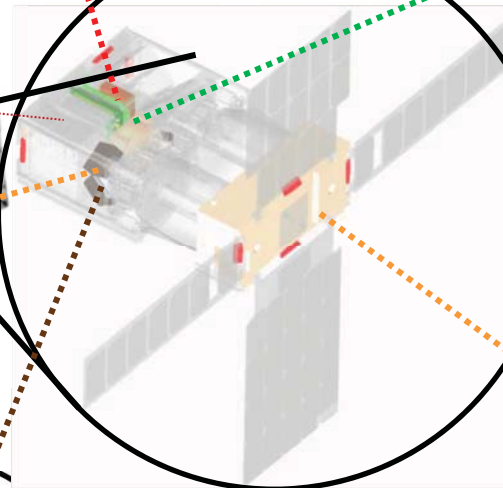
Sun Sensors/IMUs

- ~0.5 deg accuracy
- Detumbling
- Safe mode
- Rapid slews



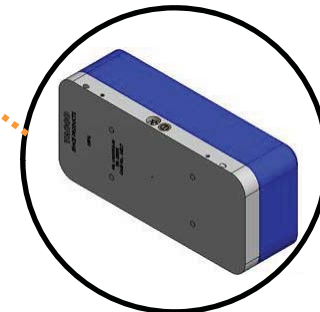
Star Tracker

- ~0.01 deg accuracy
- Fine pointing in interplanetary space



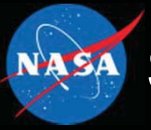
Steering RWA

- Three 15 mNms wheels
- Attitude control for science, telecom, and nav. pointing

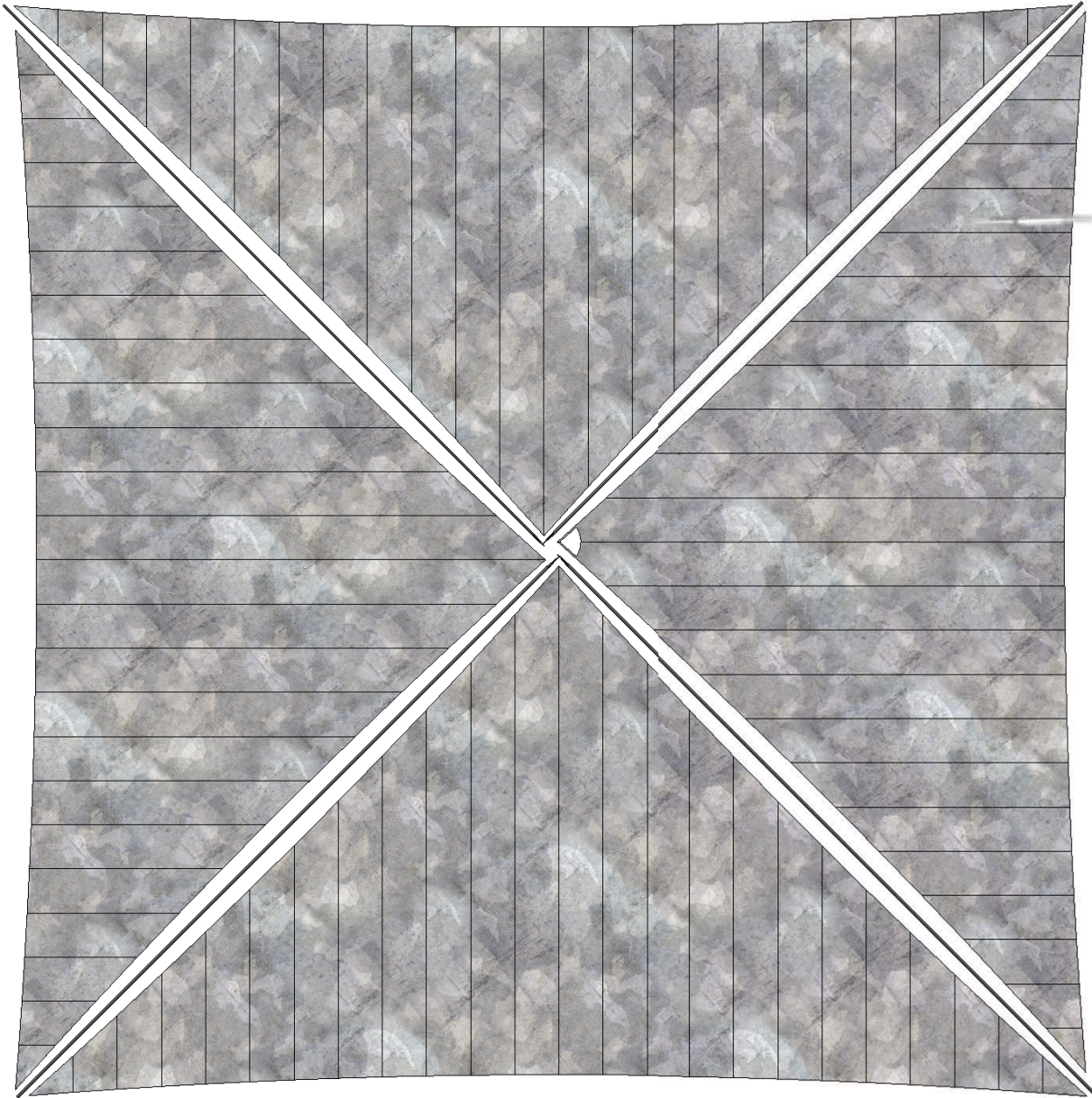
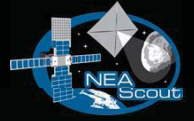


Cold Gas System

- $I_{sp} \geq 40s$
- ~ 1.5 kg of fuel
- Momentum mgmt
- Initial delta-V burn 16



Size comparison



Soyuz

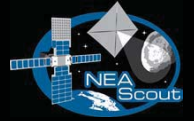


Human



6U CubeSat





- **Contribution to the CubeSat Community**
 - Long-lived CubeSat bus for deep space missions (C&DH, EPS, ADCS, Deep Space Transponder)
 - Further characterization of deep space environment effects on CubeSats (building on INSPIRE)
 - First science-grade observations of solar system objects
 - Mature CubeSat Solar Sail propulsion
- **Future Potential of Small Missions for Big Science**
 - Secondary spacecraft hosted on interplanetary missions
 - NEA Scout could be repeated to characterize additional NEAs or increase coverage of lunar ices (possibly with different, complementary payloads)
 - Other solar sail applications (e.g. Space Weather Monitoring constellation at Lagrange Points)