

FACILITY FORM 802

N 65-21461	
(ACCESSION NUMBER)	(THRU)
85	1
(PAGES)	(CODE)
CR-62188	12
(NASA CR OR TMX OR AD NUMBER)	(CATEGORY)

ANALYSIS OF FLOW FROM PLUG NOZZLES WITH SECONDARY EJECTOR SYSTEMS

by C. C. LEE and S. J. INMAN

January, 1965

GPO PRICE \$ _____
OTS PRICE(S) \$ _____
Hard copy (HC) \$3.00
Microfiche (MF) .25

RESEARCH LABORATORIES

BROWN ENGINEERING COMPANY, INC.

HUNTSVILLE, ALABAMA

TECHNICAL NOTE R-128

ANALYSIS OF FLOW FROM PLUG
NOZZLES WITH SECONDARY EJECTOR SYSTEMS

January, 1965

Prepared For

PROPULSION DIVISION
P&VE LABORATORY
GEORGE C. MARSHALL SPACE FLIGHT CENTER

By

RESEARCH LABORATORIES
BROWN ENGINEERING COMPANY, INC.

Contract NAS8-5289

Prepared By

C. G. Lee
S. J. Inman

ABSTRACT

21461

The method of characteristics is presented for the calculation of the supersonic flow field, with the Rankine-Hugoniot equations used to compute the flow properties across a shock. The secondary flow properties are calculated by the one-dimensional isentropic relationships. The gas is assumed to be an inviscid nonreacting perfect gas with constant specific heat. Sample calculations, as well as the listing of the FORTRAN program, are presented.

Author

Approved

C. E. Kaylor
C. E. Kaylor, Ph.D.
Director, Mechanics and
Propulsion Laboratories

Approved

R. C. Watson, Jr.
R. C. Watson, Jr.
Director of Research

TABLE OF CONTENTS

	<u>Page</u>
INTRODUCTION	1
METHOD OF ANALYSIS	3
COMPUTING PROCEDURE	11
SAMPLE RESULTS AND DISCUSSION	13
REFERENCES	17
APPENDIX A - DESCRIPTION OF DATA INPUT AND OUTPUT	19
APPENDIX B - FORTRAN LISTING	27

LIST OF FIGURES

<u>Figure</u>		<u>Page</u>
1	Aerodynamic Plug Nozzle Flow Schematic	2
2	Nomenclature for Boundary Point Calculation	7
3	Characteristic Network for an Interior Shock	7
4	Characteristic Net for an Aerodynamic Plug Nozzle	14
5	Variations of Plume Shapes for Various Ambient Pressures	15
6	Variations of Plume Shapes for Various Secondary Total Pressures	16

LIST OF SYMBOLS

a	speed of sound, ft/sec
A	cross-sectional area of secondary flow, ft ²
A^*	cross-sectional area of secondary flow at which the Mach Number is unity, ft ²
h	enthalpy, ft ² /sec ²
M	Mach Number
m	mass flow rate, lbm/sec
p	pressure, lbf/ft ²
P_o	total pressure of the primary flow, lbf/ft ²
P_T	total pressure of the secondary flow, lbf/ft ²
s	entropy, ft ² /sec ² °R
T	temperature, °R
V	velocity, ft/sec
X, Y	Cartesian coordinates, ft
β	Mach angle, $\sin^{-1}\left(\frac{1}{M}\right)$
γ	ratio of specific heat
δ	shock angle with respect to stream direction behind a shock
ϵ	density ratio across shock
θ	flow angle with respect to x axis
μ	shock angle with respect to x axis
ρ	density, lbm/ft ³

INTRODUCTION

In recent years, considerable effort has been devoted to the problems associated with base pressures of plug nozzles. In the case of the plug nozzle with a secondary ejector system, the flow phenomenon is only partially understood. The purpose of this study is to demonstrate the essential features of the primary and secondary flow interaction. It is known that viscous effects play a major role in these flow cases, and also that the viscous effects can be superimposed on an inviscid flow field for the region of interest¹. Therefore, the study has been divided into two stages. The first stage is to obtain an inviscid solution for the primary and secondary flow, and the second stage is to determine the viscous effects. This report presents the results of the first stage study.

The primary supersonic flow properties are determined by using the method of characteristics, and the flow is assumed to be rotational and axisymmetric. The gas is assumed to be perfect and inviscid. The flow properties across a shock are calculated by using the Rankine-Hugoniot equations. The Prandtl-Meyer equations are used to compute the flow properties at the lip of the shroud and at the corner of the plug. The secondary flow properties are determined by using the one-dimensional isentropic relationships.

In order to obtain the nozzle exit conditions as initial conditions for the jet computation, the calculations in Reference 2 have been adopted. A flow model for demonstrating the basic construction of a jet is shown in Figure 1. The theoretical analysis is presented in the order of computation. The equations of the analysis have been coded in IBM 7040 FORTRAN IV computer language. Some sample results are also presented in this report.

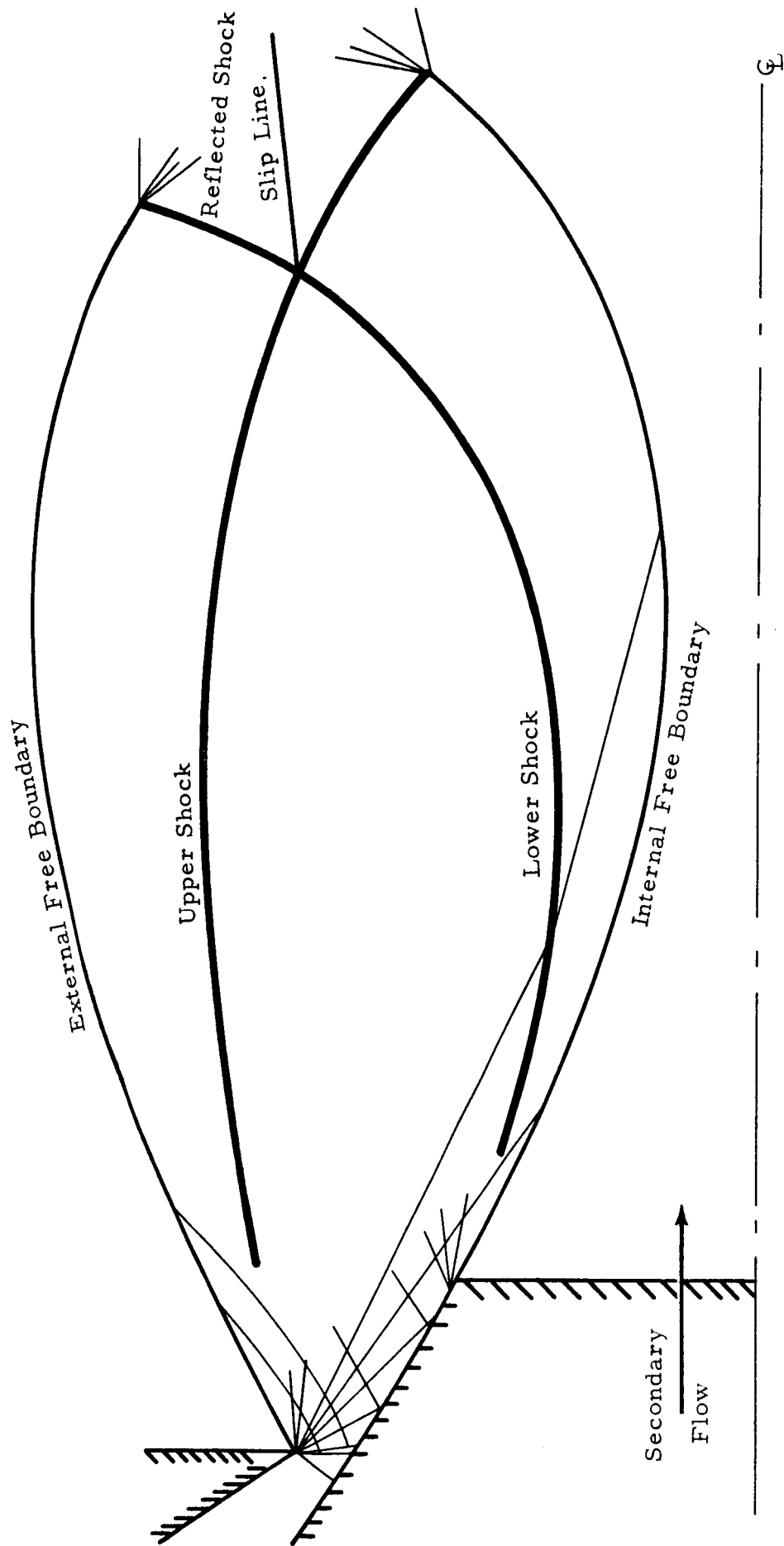


Figure 1. Aerodynamic Plug Nozzle Flow Schematic

METHOD OF ANALYSIS

The method of characteristics is used to calculate the downstream flow field of a plug nozzle. The Prandtl-Meyer equations are used to calculate the flow properties at the lip of the shroud and at the corner of the plug. The calculations of flow properties across shocks are based on the method presented in Reference 3. The secondary flow is determined by the one-dimensional isentropic relationships. The calculation procedures are summarized below.

In Reference 2 a computer program is presented which calculates the flow properties in the entire nozzle flow field. By knowing the conditions at the edge of the plug, the Prandtl-Meyer equations provide a means of computing the corner wave. Combining the Prandtl-Meyer equation

$$\frac{dV}{V} = - \frac{d\theta}{(M^2 - 1)^{\frac{1}{2}}} \quad (1)$$

and the energy equation

$$V dV = - \frac{dp}{\rho} \quad (2)$$

one obtains

$$dp = \frac{\rho V^2 d\theta}{(M^2 - 1)^{\frac{1}{2}}} \quad (3)$$

Once the corner waves are determined, the flow field calculations can be continued by using the method of characteristics. Since the nozzle flow field is computed along the right running characteristics, the same scheme can be applied to the downstream flow field.

At the internal boundary, an iteration is required to match the static pressure of the primary flow with that of the secondary flow. As shown in Figure 2, $\overline{bd}$ is a streamline, and

$$Y_d = Y_b + (X_d - X_b)(\tan \theta)_{bd} \quad . \quad (4)$$

$\overline{nd}$ is a right running characteristic

$$Y_d = Y_n + (X_d - X_n)[\tan (\theta - \beta)]_{nd} \quad . \quad (5)$$

Combining Equations 4 and 5, one obtains

$$X_d = \frac{Y_n - Y_b - X_n[\tan (\theta - \beta)]_{nd} + X_b(\tan \theta)_{bd}}{(\tan \theta)_{bd} - [\tan (\theta - \beta)]_{nd}} \quad . \quad (6)$$

Once the Y_d value is known, the cross sectional area is known. The Mach Number of the secondary flow can be computed by a method of successive approximations from the following equation

$$\frac{A}{A^*} = \frac{1}{M} \left[\left(\frac{2}{\gamma + 1} \right) \left(1 + \frac{\gamma - 1}{2} M^2 \right) \right]^{\frac{\gamma + 1}{2(\gamma - 1)}} \quad .$$

By rearranging the above equation, the following function can be obtained to calculate the Mach Number

$$f(M) = M \left(\frac{A}{A^*} \right) - \left[\frac{2 + (\gamma - 1)M^2}{\gamma + 1} \right]^{\frac{\gamma + 1}{2(\gamma - 1)}} \quad .$$

Expanding this function in a Taylor's series

$$f(M + \Delta M) = f(M) + f'(M)\Delta M + f''(M) \frac{\Delta M^2}{2!} + \dots + f^n(M) \frac{\Delta M^n}{n!} \quad (7)$$

where

$$f'(M) = \frac{A}{A^*} - M \left[\frac{2 + (\gamma - 1)M^2}{\gamma + 1} \right]^{\frac{3 - \gamma}{2(\gamma - 1)}} \quad .$$

By truncating Equation 7 at the first two terms and assuming a value for M , the following expression for ΔM may be obtained

$$\Delta M = - \frac{f(M)}{f'(M)} .$$

A new approximation for M is

$$M = M + \Delta M .$$

The Mach Number can be obtained by carrying on this process until the ΔM is within a desired limit.

The static pressure of the secondary flow can be determined by the following irrotational flow relation

$$p = P_T \left(1 + \frac{\gamma - 1}{2} M^2 \right)^{-\frac{\gamma}{\gamma - 1}} . \quad (8)$$

The static pressure of the primary flow is equal to that of secondary flow and Equation 8 can also be used to compute the primary flow Mach Number. Of course, the total pressure would be different between the two flow fields. The flow angle at point d can be computed by the right running characteristic equation

$$\begin{aligned} (V_d - V_n) \left(\frac{\cot \beta}{V} \right)_{dn} + (\theta_d - \theta_n) - \left[\frac{\sin \beta \sin \theta}{\gamma \cos(\theta - \beta)} \right]_{dn} (X_d - X_n) \\ + \left(\frac{T}{a^2} \sin \beta \cos \beta \right)_{dn} (s_d - s_n) = 0 . \end{aligned} \quad (9)$$

The θ_d value can be substituted into Equation 4, and the procedure repeated until the tolerance is met. This method has been proved to be convergent when iterated.

When characteristics of the same family intersect, it is an indication of shock. The flow properties across the shock can be computed

by using the Rankine-Hugoniot equations. Moe and Troesch³ have developed a method for the computations. A detailed form of this method presented by Eastman⁴ has been adapted in the present calculations, and the symbols used in the equations are essentially those of the originals.

As shown in Figure 3, point 3 can be computed by using regular field point calculation. Point 4 can be solved by the following equations:

$$B = \frac{(Y_1 - Y_2) - (X_1 - X_2)(\tan \mu)_{14}}{(Y_3 - Y_2) - (X_3 - X_2)(\tan \mu)_{14}} \quad (10)$$

$$X_4 = X_2 + B(X_3 - X_2)$$

$$Y_4 = Y_2 + B(Y_3 - Y_2)$$

$$\theta_4 = \theta_2 + B(\theta_3 - \theta_2)$$

$$V_4 = V_2 + B(V_3 - V_2) \quad .$$

(11)

Once point 4 is determined, the flow properties of point 11 can be computed by the Rankine-Hugoniot equations

$$\epsilon = \frac{(\gamma - 1)M_4^2 \sin^2(\theta_4 - \mu_4) + 2}{(\gamma + 1)M_4^2 \sin^2(\theta_4 - \mu_4)} \quad (12)$$

$$p_{11} = p_4 + \rho_4 V_4^2 (1 - \epsilon) \sin^2(\theta_4 - \mu_4) \quad (13)$$

$$h_{11} = h_4 + \frac{V_4^2}{2} (1 - \epsilon^2) \sin^2(\theta_4 - \mu_4) \quad (14)$$

$$V_{n11} = V_4 \epsilon \sin(\theta_4 - \mu_4) \quad (15)$$

$$V_{T11} = V_4 \cos(\theta_4 - \mu_4) \quad (16)$$

$$V_{11} = \left(V_{n11}^2 + V_{T11}^2 \right)^{\frac{1}{2}} \quad (17)$$

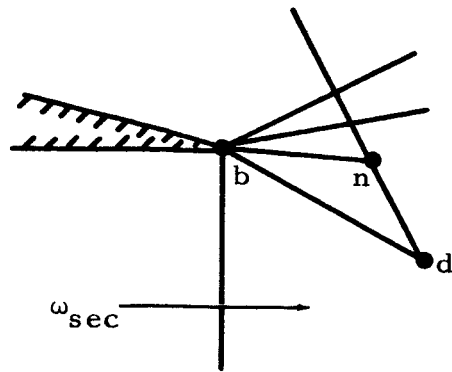


Figure 2. Nomenclature for Boundary Point Calculation

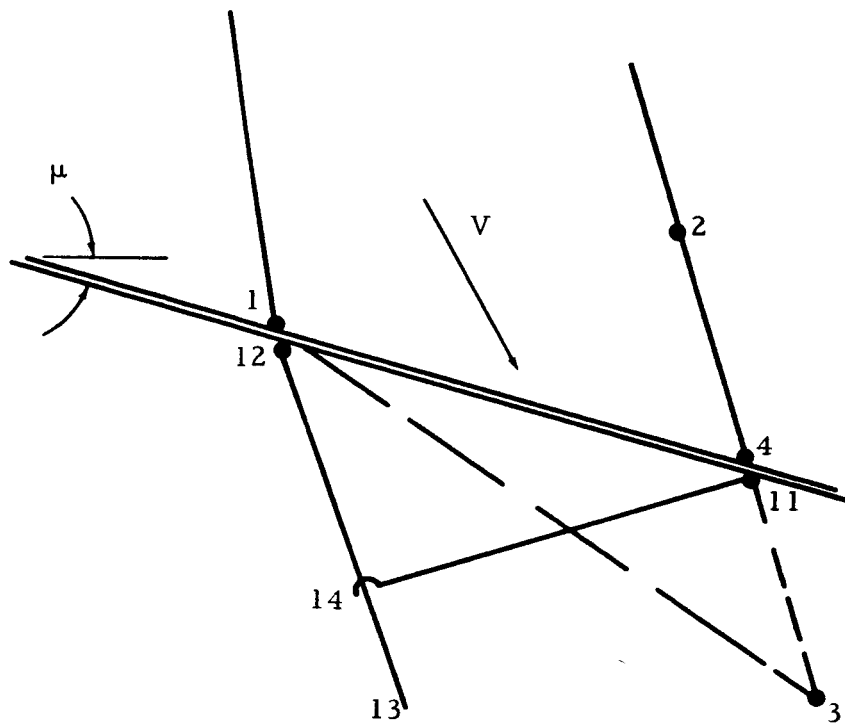


Figure 3. Characteristics Network for an Interior Shock

$$s_{11} = \tan^{-1}[\varepsilon \tan(\theta_4 - \mu_4)] \quad (18)$$

$$\theta_{11} = \mu_4 + \delta_{11} \quad (19)$$

Point 14 is an inserted left running characteristic point from point 11

$$G = \frac{(Y_{11} - Y_{12}) - (X_{11} - X_{12})[\tan(\theta + \beta)]_{11,14}}{(Y_{13} - Y_{12}) - (X_{13} - X_{12})[\tan(\theta + \beta)]_{11,14}} \quad (20)$$

$$X_{14} = X_{12} + G(X_{13} - X_{12})$$

$$Y_{14} = Y_{12} + G(Y_{13} - Y_{12})$$

$$V_{14} = V_{12} + G(V_{13} - V_{12})$$

$$\theta_{14} = \theta_{12} + G(\theta_{13} - \theta_{12}) \quad (21)$$

$$\beta_{14} = \beta_{12} + G(\beta_{13} - \beta_{12})$$

$$T_{14} = T_{12} + G(T_{13} - T_{12})$$

$$s_{14} = s_{12} + G(s_{13} - s_{12})$$

The flow angle at point 11 can be computed by using the left running characteristic equation

$$\begin{aligned} \theta_{11} = \theta_{14} + (V_{11} - V_{14}) \left(\frac{\cot \beta}{V} \right)_{11,14} - \left[\frac{\sin \beta \sin \theta}{Y \cos(\theta + \beta)} \right]_{11,14} (X_{11} - X_{14}) \\ + \left(\frac{T}{a^2} \sin \beta \cos \beta \right)_{11,14} (s_{11} - s_{14}) \end{aligned} \quad (22)$$

The iteration scheme is based on Reference 4. Assuming three values of μ_4 , three sets of θ_{11} values will be obtained from Equations 19 and 22. The value of θ_{11} is assumed to vary parabolically with μ_{11} .

$$\theta_{11} = a_1 + b_1 \mu_4 + c_1 \mu_4^2 \quad (23)$$

$$\theta_{11} = a_2 + b_2 \mu_4 + c_3 \mu_4^2 \quad (24)$$

The μ_4 value can then be solved from Equations 23 and 24. The same numerical technique can be applied to the shock near the upper boundary. The lower shock is computed first since it is difficult to compute the upper shock and the lower shock simultaneously. The lower field and shock points are computed along the right running characteristics which originated from the lip of the shroud until the last one is reached or the shock deflection angle becomes excessive ($M < 1$). Then the upper field and shock points are calculated along the left running characteristics.

The methods of computing the upper shock are the same as those of the lower shock except that the calculations follow along the left running characteristics instead of the right running characteristics. The same set of equations, which are described in previous pages, can be used by replacing the term $(\theta + \beta)$ by $(\theta - \beta)$ in Equations 20 and 22 by a right running characteristic equation

$$\begin{aligned} \theta_{11} = \theta_{14} - (V_{11} - V_{14}) \left(\frac{\cot \beta}{V} \right)_{11,14} + \left[\frac{\sin \beta \sin \theta}{Y \cos(\theta + \beta)} \right] (X_{11} - X_{14}) \\ - \left[\frac{T}{a^2} \cos \beta \sin \beta \right] (s_{11} - s_{14}) \quad (25) \end{aligned}$$

COMPUTING PROCEDURE

The computer program contains various phases of calculations: the determination of field points, solid boundary points, upper and lower shock points, upper and lower free boundary points, and the one-dimensional isentropic computations. The linkage of the system is shown in Figure 1.

The computation is initiated from a starting line which is assumed to be uniform and at a slightly supersonic condition. The nozzle field points and solid boundary points calculations are based on the program presented in Reference 2. The jet field points and shock points are computed along the right running characteristics until the last one originated from the lip is obtained or the flow behind the shock becomes subsonic. Then the upper field points and shock points are calculated along the left running characteristics. If the last point of the upper shock lies above the lower shock, the calculations of the lower shock have to be continued until it meets the upper shock. The flow properties at the intersection of the upper and lower shocks are interpolated between the nearest two shock points. Behind the shock intersection, two reflected shocks and a slip stream occur. A numerical scheme for solving this part of flow field can be found in Reference 5. This scheme is a combination of the shock routine, the field point calculations and the solid boundary point calculation, and the slip stream angle is iterated until the static pressure is equal on both sides.

When there is a secondary flow in the plug base, the solution for the boundary point between the primary and the secondary flow must be iterated to determine a common static pressure. The secondary flow is assumed to be governed by the one-dimensional isentropic relationships.

The calculation of the present type flow field can be carried very far downstream; however, due to the particular objectives of this study, the computer program has only been developed for the computation of flow field properties through the first shock intersection point.

SAMPLE RESULTS AND DISCUSSION

A sample case has been calculated by using the present computer program; the characteristic net has been plotted in Figure 4. When studying the mixing effect between the primary and the secondary flow, the lower boundary is the most important region. Since a fine net size is obtained at the lower boundary, no attempt has been made to refine the net size of the upper field points.

Three cases have been computed for studying the effects of the ambient pressure and the total pressure of the secondary flow on the plume shape. The effect of varying the ambient pressure in a fixed nozzle is shown in Figure 5. When the ambient pressure ratio (P_o/P_a) decreased from 594.1 to 101.3, the length (X/R_E) of the plume up to the shocks intersection decreased from 3.06 to 2.11. The effect of varying the secondary total pressure in a fixed nozzle is shown in Figure 6. When the secondary total pressure ratio (P_o/P_T) decreased from 64.12 to 27.79, the length (X/R_E) of the plume up to the shocks intersection decreased from 3.06 to 2.00.

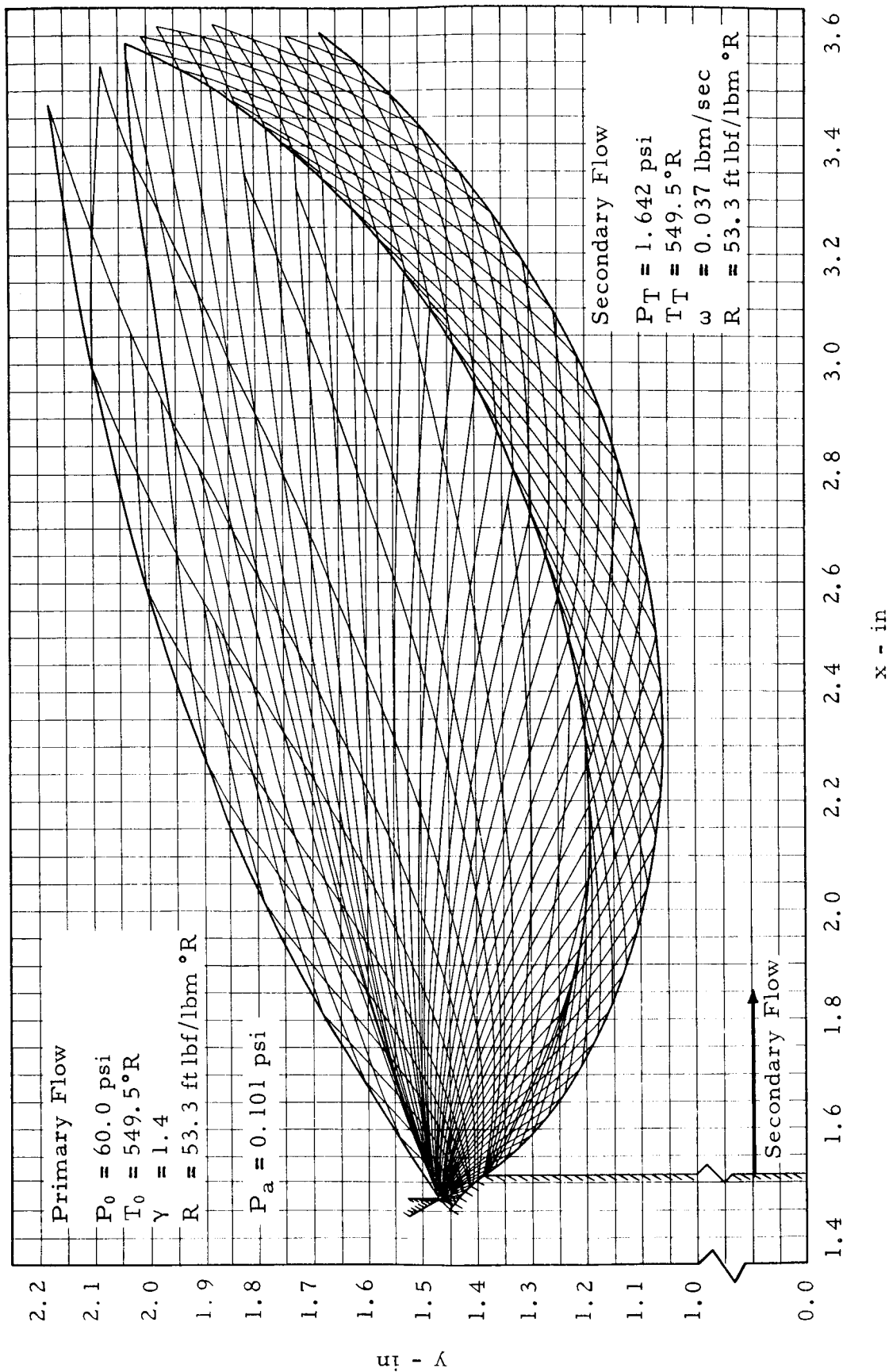


Figure 4. Characteristic Net for an Aerodynamic Plug Nozzle

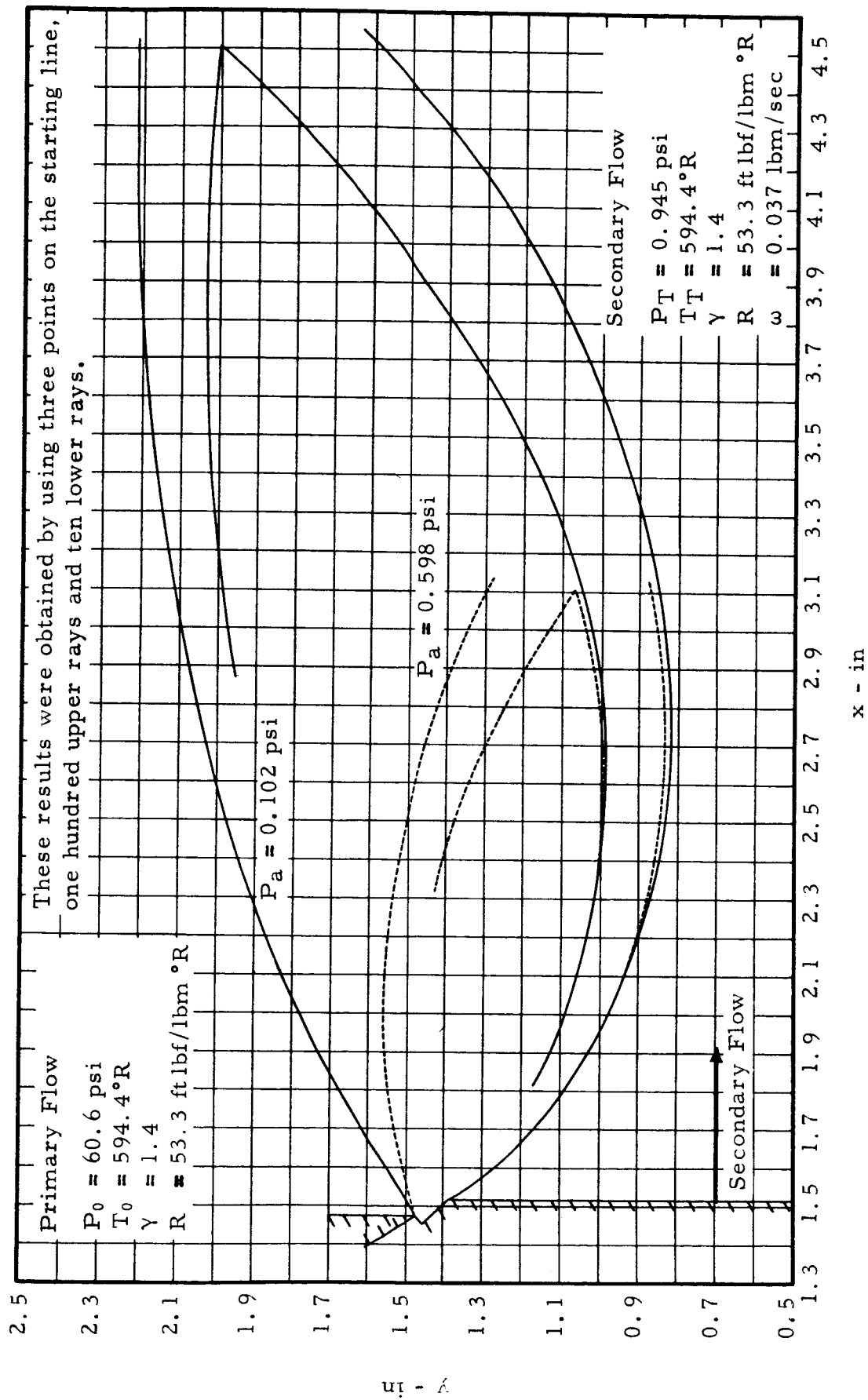


Figure 5. Variations of Plume Shapes for Various Ambient Pressures

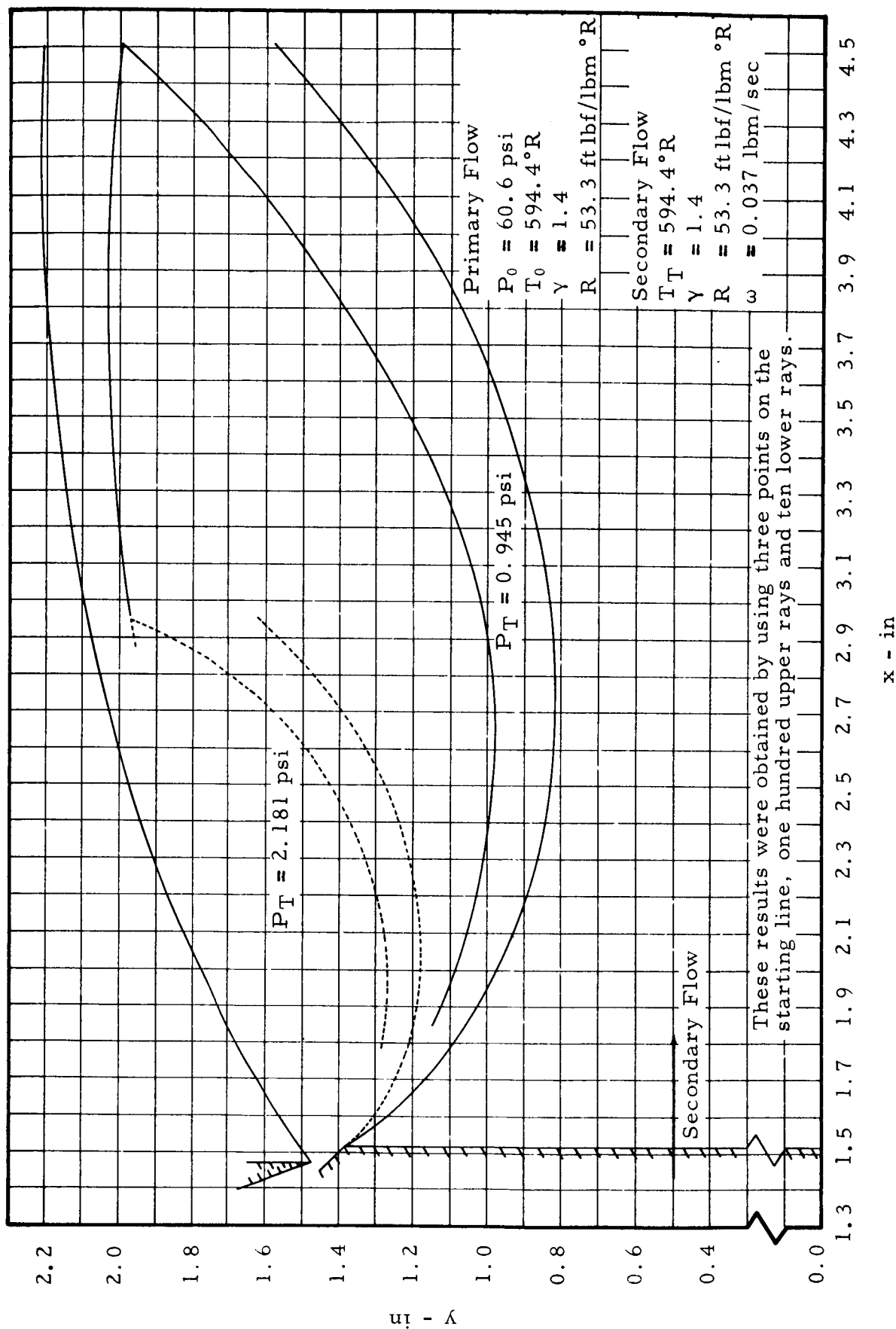


Figure 6. Variations of Plume Shapes for Various Secondary Total Pressure

REFERENCES

1. Chow, W. L., and A. L. Addy, "Interaction Between Primary and Secondary Streams of Supersonic Ejector Systems and Their Performance Characteristics", AIAA Journal, Volume 2, Number 4, pp. 686-695, April, 1964
2. Lee, C. C., and S. J. Inman, "Numerical Analysis of Plug Nozzles by the Method of Characteristics", Technical Note R-101, Brown Engineering Company, Inc., May, 1964
3. Moe, M. M., and B. A. Troesch, "Jet Flows with Shock", ARS Journal, Volume 30, Number 5, pp. 487-489, May, 1960
4. Eastman, D. W., "Two Dimensional or Axially Symmetric Real Gas Flows by the Method of Characteristics, Part I, Formulation of the Equations", Category Code No. 81205 Document No. D2-10597, Boeing Airplane Company, Seattle 24, Washington, December, 1961
5. Der. J., Jr., B. N. Mullings, G. H. Hoffman, B. N. Pridmore Brown, "Numerical Analysis of Supersonic Flow Through Curved Channels", ARL 63-117, Northrop Norair, Hawthorne, California, July, 1963

APPENDIX A

DESCRIPTION OF DATA INPUT AND OUTPUT

Input

This program requires the following input data:

1. Nozzle components (3 cards)

GAM(γ)	ratio of specific heats for primary flow
XM(Mest)	initial Mach Number
P(P_0)	total pressure for primary flow
T(T_0)	total temperature for primary flow
R	gas constant for primary flow
GW(γ_s)	ratio of specific heats for secondary flow
RW	gas constant for secondary flow
P _T	total pressure for secondary flow
TT	total temperature for secondary flow
PA(p_a)	ambient pressure
W(w)	secondary flow rate
N	number of points on starting line, must be < 100
Nl	number of lower wall contour points, must be ≤ 100
NU(η)	the number of upper corner rays to be computed, must be $< (600 - N - NL - 1)$
NL	the number of lower corner rays to be computed, must be < 100

2. A title or job-description card

3. Nl lower wall contour points given as Cartesian coordinates

4. Upper corner point given as Cartesian coordinates
5. KK If input is in feet, KK = 0
 If input is in inches, KK = 1

Input cases can be stacked and processed several at a time. If a bad data case is found which cannot run to completion, the remaining data cases will not be processed. This is due to the computer system, not the program.

Output

1. Units of variables
2. Job title
3. Input conditions
4. Upper corner point
5. Lower wall contour points
6. Starting line points

Point	X	Y	M	THETA	T	P
↓	↓	↓	↓	↓	↓	↓

where X, Y are Cartesian coordinates; M is Mach Number, THETA is flow angle, T is temperature (°R), and P is pressure

7. Right running characteristics from the upper corner point

Point	X	Y	M	THETA	T	P
↓	↓	↓	↓	↓	↓	↓

8. External expansion

(a) Field routine points

Point	X	Y	M	THETA	T	P	ITR
↓	↓	↓	↓	↓	↓	↓	↓

where ITR is the number of iterations before convergence in calculations

(b) Body point routine

Point	X	Y	M	THETA	T	P	ITR
↓	↓	↓	↓	↓	↓	↓	↓

Field and body points alternate until the last point on the lower wall contour is reached or until the network is completed.

(c) Insert point

Point	X	Y	M	THETA	T	P
-------	---	---	---	-------	---	---

(d) Corner point

Point	X	Y	M	THETA	T	P
-------	---	---	---	-------	---	---

9. Thrust distribution along the plug

(a) SUMM (thrust at the throat)

(b) CFI (thrust coefficient at the throat)

(c) Mass flow rate

(d)	X	Y	T (thrust)	CF (thrust coefficient)
	↓	↓	↓	↓

for each point on the lower wall.

(e) AT - throat area

(f) Secondary mass flow rate

(g) Thrust from plug nozzle wall

(h) Thrust from base

(i) Total vacuum thrust

(j) Actual thrust (considering the ambient pressure)

10. Jet flow field computations

(a) Left running characteristics

(b) Flow properties computed along right running characteristics

(1) Field routine

Point	X	Y	M	THETA	T	P	ITR
↓	↓	↓	↓	↓	↓	↓	↓

(2) Free boundary point

Point	X	Y	M	THETA	T	P	ITR
-------	---	---	---	-------	---	---	-----

(3) Secondary Mach Number

(4) Primary velocity

(5) Secondary flow temperature

(6) Secondary flow velocity

Repeat 10 until shock is encountered, then the insert point and shock points appear in the field points.

Point	X	Y	M	THETA	T	P	Shock Angle
-------	---	---	---	-------	---	---	-------------

Section 10 is repeated until the last right running characteristic is used or the deflection angle becomes too big.

11. Upper external flow field and boundary computed along left running characteristics.

(a) Upper free boundary point

Point	X	Y	M	THETA	T	P	ITR
-------	---	---	---	-------	---	---	-----

(b) Field routine

Point	X	Y	M	THETA	T	P	ITR
↓	↓	↓	↓	↓	↓	↓	↓

Repeat from 11 until shock is encountered, then the insert point and shock points appear in the field points.

Point	X	Y	M	THETA	T	P	Shock Angle
-------	---	---	---	-------	---	---	-------------

Repeat from 11 until the upper shock crosses the lower shock or it becomes necessary to extend the lower shock to cross the upper shock.

12. Shock intersection

Characteristics of the shock intersection are printed in the following order:

- B - upper shock
- C - upper reflected shock
- A - lower shock
- D - lower reflected shock

Point	X	Y	M	THETA	T	P	Shock Angle
-------	---	---	---	-------	---	---	-------------

13. Punched card output

- (a) First card - At first free boundary point: primary temperature, secondary temperature, primary velocity, secondary velocity (Format 4E12.5)
- (b) One card for each free boundary point. X, Y, Pressure (Format 3E16.7)

End of Calculation

Point Number Identification

- (a) Points numbered 1 are always free boundary points
- (b) Points from one set of field points to the next set of field points connect with points one greater than their number (i. e., point 5 in a set of field points connects with point 4 of the preceding set of field points and connects with point 6 of the next set of field points. Also, each set of field points itself is a characteristic.

INPUT DATA AND FORMAT

Format	Data	Description	No. of Cards
(4E15.8)	GAM, XM, P, T	Symbols are defined in 1 of Input Description	1
(5E15.8)	R, GW, RW, PT, TT	Symbols are defined in 1 of Input Description	1
(2E15.8, 2I2, I3, I2)	PA, W, N, N1, NU, NL	Symbols are defined in 1 of Input Description	1
(13A6)	Title or Job Description Card	Maximum of 78 alphanumeric characters (Col. 1-78)	1
(2E15.8)	X, Y	Contour Cartesian coordinates lower wall points followed by one upper corner point	One for each point (N1 + 1)
(I2)	KK	Defined in 5 of Input Description	1

INPUT CARD FORMAT

	15	30	45	60	75
GAM	XM	P	T		
R	GW	RW	PT	TT	
PA	W	N	N1	NU	NL
		32	34	37	39

TITLE CARD

X	Y	(N1 + 1 contour point cards)
KK		
2		

SAMPLE DATA

15	30	45	60	75
+0.14000000E+01+0.10500000E+01+0.60600000E+02+0.59440000E+03				
+0.53300000E+02+0.14000000E+01+0.53300000E+02+0.94500000E+00+0.59440000E+03				
3234 3739				
+0.10200000E+00+0.03700000E+00030210010				
45 Degree Cowl Plug Nozzle				
+0.14520000E+01+0.14520000E+01 lower wall contour points				
+0.15140000E+01+0.13900000E+01 ↓ ↓				
+0.14730000E+01+0.14730000E+01 upper corner point				
1				
2				
01				

APPENDIX B
FORTRAN LISTING

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```

C      AERODYNAMIC PLUG NOZZLE ANALYSIS
C      BY USING THE METHOD OF CHARACTERISTICS
      DIMENSION YP(600),XP(600),TH(600),XMP(600),TP(600),PP(600),
      1VLP(600)
      DIMENSION XB1(100),YB1(100)
      DIMENSION FRX(50),FRY(50),FRV(50),FRT(50),FRP(50),FRTH(50),
      1FLX(50 ),FLY(50 ),FLP(50 )
      COMMON YP,XP,TH,XMP,TP,PP,VLP,GAM,GM1,G,XM,N,P,T,R,L,M,J,NL,XXB2,
      1YYB2,NU,GPI,FE,PA
      COMMON FRX,FRY,FRV,FRT,FRP,FRTH,FLX,FLY,FLP,AT,NF
      COMMON YO,GW,RW,PT,TT ,W,XO
      DIMENSION SX(600),SY(600),SM(600),STH(600),ST(600),SP(600),SV(600)
      COMMON/BEN/SX,SY,SM,STH,ST,SP,SV
      COMMON/BUN/UX,UY,BX,BY,UI,UM,BM,UTH,BTH,UT,BT,UP,BP,UV,BV,UU,BU
      DIMENSION UX(2),UY(2),BX(2),BY(2),UM(2),BM(2),UTH(2),BTH(2),UT(2),
      1BT(2),UP(2),BP(2),UV(2),BV(2),UU(2),BU(2)
      DIMENSION EP(3),P7(3),P5(3)
      COMMON/MIKE/EPF,SH(2),CM,SI(2),CP,SL(2),CT,SZ(2),DM,SK(2),DP,
      1SJ(2),DT,SK1(2),I1,UB,UA,CU,DU
      COMMON/JUL/KXSH
      78 READ(5,1001)  GAM,XM,P,T,R,GW,RW,PT,TT,PA,W,N,N1,NU,NL
      KXSH=0
      UX(1)=0.
      1001 FORMAT(4E15.8/5E15.8/2E15.8,2I2,I3,I2)
      1003 FORMAT(2E15.8)
      1002 FORMAT(1H0,///,1H0,5HPOINT,10X,1HX,17X,1HY,17X,1HM,13X,5HTHETA,13X
      1,1HT,17X,1HP,10X,3HITR)
      300 FORMAT(1H1,48X,35HAERODYNAMIC PLUG NOZZLE ANALYSIS/1H0,44X,43HB
      1Y USING THE METHOD OF CHARACTERISTICS///1H0,5X,5HUNITS///1H0
      2,10X,16HCOORDINATES X,Y,14X,3HIN./1H0,10X,25HINCLINED THROAT ANGL
      3E(FE),5X,7HDEGREES/1H0,10X,8HPRESSURE,22X,9HLBF/IN*IN/1H0,10X,11HT
      4EMPERATURE,19
      1X,15HDEGREES RANKINE/1H0,10X,16HGAS CONSTANT (K),14X,26HFT LBF/LBM
      1 DEGREES RANKINE/1H0,10X,4HAREA,26X,5HIN*IN/1H0,10X,6HTHRUST,24X,3
      1HLBF)
      301 FORMAT(13A6)
      302 FORMAT(1H0,13A6)
      303 FORMAT(1H0,5X,17HINPUT CONDITIONS///1H0,10X,3H
      1PA=E15.8/1H0,7X,12HPRIMARY FLOW/1H0,10X,6HGAMMA=E15.8/1H0,10X,5HME
      2ST=E15.8/1H0,10X,2HR=E15.8/1H0,10X,3HPO=E15.8/1H0,10X,3HTO=E15.8/
      31H0,7X,15HSECONDARY FLOW/1H0,10X,6HGAMMA=E15.8/1H0,10X,2HR=E15.8/
      41H0,10X,2HW=E15.8/1H0,10X,3HPT=E15.8/1H0,10X,3HTT=E15.8)
      READ(5,301)A1,A2,A3,A4,A5,A6,A7,A8,A9,A10,A11,A12,A13
      WRITE(6,300)
      WRITE(6,302)A1,A2,A3,A4,A5,A6,A7,A8,A9,A10,A11,A12,A13

```

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```

READ(5,1003)(XB1(I),YB1(I),I=1,N1),XXB2,YYB2
WRITE(6,303) PA,GAM,XM,R,P,T,GW,RW,W,PT,TT
WRITE(6,1006)
WRITE(6,1007)XXB2,YYB2
WRITE(6,1008)
WRITE(6,1007)(XB1(I),YB1(I),I=1,N1)
READ(5,52)KK
IF(KK.EQ.0)GO TO 401
P=P*144.
PT=PT*144.
PA=PA*144.
XXB2=XXB2/12.
YYB2=YYB2/12.
DO 402 K=1,N1
XB1(K)=XB1(K)/12.
402 YB1(K)=YB1(K)/12.
401 YO=YB1(N1)
XO=XB1(N1)
1006 FORMAT(1H0,18HUPPER WALL CONTOUR/1H0,7X,1HX,16X,1HY)
1007 FORMAT(1H0,2(E15.8,2X))
1008 FORMAT(1H0,18HLOWER WALL CONTOUR/1H0,7X,1HX,16X,1HY)
KIT=0
NF=2
GM1=GAM-1.
GP1=GAM+1.
G=32.2
WRITE(6,1002)
52 FORMAT(I2)
84 F=ATAN((XXB2-XB1(1))/(YYB2-YB1(1)))
FE=-(F+1.5707963)
CALL STL2(XB1,YB1,N1)
AT=3.1415927*(YYB2+YB1(1))*SQRT((XXB2-XB1(1))**2+(YYB2-YB1(1))**2)
GO TO 2
1005 FORMAT(6E13.6)
79 FORMAT(1H0,6(3X,E15.8))
2 CP=GAM*R/GM1
K=N+NL
DO 61 J=1,N
H=CP*TP(K)*G
A=SQRT(GM1*H)
60 VLP(K)=XMP(K)*A
FRX(J)=XP(K)
FRY(J)=YP(K)
FRV(J)=VLP(K)
FRT(J)=TP(K)

```

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```

FRP(J)=PP(K)
FRTH(J)=TH(K)
61 K=K-1
FLX(1)=XP(NL+1)
FLY(1)=YP(NL+1)
FLP(1)=PP(NL+1)
74 CALL BPRTN(3,XXB2,YYB2,1)
NR=N+1+NL
86 M=NR-1
L=2+NL
J=NR-1
CALL FLDRTN(3)
M=1+NL
L=2+NL
CALL BPRTN(1,XB1,YB1,N1)
FLX(NF)=XP(NL+1)
FLY(NF)=YP(NL+1)
FLP(NF)=PP(NL+1)
NF=NF+1
NR=NR+1
IF(NR-(N+NL+NU))88,6,6
88 IF(J.NE.666)GO TO 86
M=1+NL
J=1+NL
L=2
CALL FLDRTN(3)
M=1
L=2
CALL BPRTN(4,XXB2,YYB2,1)
700 M=NR-1
L=2
J=NR-1
CALL FLDRTN(3)
IF(M.EQ.0)GO TO 6
M=1
L=2
CALL BPRTN(4,XXB2,YYB2,1)
I=1
K=NR
602 CALL SAVE (2,4,I,K,UI)
NR=NR+1
IF(NR-(N+NL+NU))700,6,6
6 CONTINUE
IF(N.EQ.0)GO TO 521
WRITE(6,6978)

```

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```

6978 FORMAT(////////32X,59HFLOW PROPERTIES COMPUTED ALONG LEFT RUNNING CH
    IARACTERISTICS)
    LSK=I
    CALL FLDRTN(4)
    BACKSPACE 2
    BACKSPACE 2
    KN=K
    KNR=KN
    IF(M.EQ.0) GO TO 620
    DO 6543 I=1,KNR
    CALL TRANS (I,I,1)
6543 CONTINUE
623 CONTINUE
    JM=1
    L=1
    N=LSK
    JN=LSK
    IF(M.NE.0) GO TO 797
    JN=JN+NB-NR+1
    N=JN
    JM=NB-NR+2
    L=2
    J=JM
    M=JM
    CALL FLDRTN(5)
797 CALL BPRTN(5,XXB2,YYB2,1)
    I=1
    M1=JM+1
605 CALL SAVE (3,1,I,M1,UI)
    L=2
    JM=JM+1
    IF(JM.GE. N)GO TO 788
    IF(N.EQ.JN) GO TO 962
788 Q1=BX(2)-BX(1)
    Q2=BY(2)-BY(1)
    Q3=UX(2)-BX(1)
    Q4=UY(2)-BY(1)
    ZY=0.
    IF(Q4.LT.0.)ZY=3.1415927
    KZ=1
    GO TO 6144
6143 CONTINUE
    IF(JM.GE.N) GO TO 606
962 CONTINUE
    J=JM

```

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```

      M=JM
      CALL FLDRTN(5)
      GO TO 797
6144  ZX=ATAN(Q1/Q2)
      ZY=ATAN(Q3/Q4)+ZY
      Q1=BX(1)-UX(2)
      Q2=BX(2)-UX(1)
      IF(UY(1).LT.UY(2)) GO TO 6245
      Q3=BY(1)-UY(1)
      Q4=BY(2)-UY(2)
6246  IF(ZY.GT.ZX.AND.Q1*Q2.LT.0..AND.Q3*Q4.LT.0.) GO TO 614
      GO TO (6143,6145),KZ
6245  Q3=BY(1)-UY(2)
      Q4=BY(2)-UY(1)
      GO TO 6246
      614  CONTINUE
      PAUSE 6666
2000  BACKSPACE 4
      BACKSPACE 4
      READ(4)I
      READ(4)(XP(K),YP(K),XMP(K),TH(K),TP(K),PP(K),VLP(K),K=1,I),BU(2)
      BACKSPACE 4
      BACKSPACE 4
      IF(BX(2).NE.XP(1))GO TO 2000
      BM(2)=XMP(1)
      BTH(2)=TH(1)
      BT(2)=TP(1)
      BP(2)=PP(1)
      BACKSPACE 4
      BACKSPACE 4
      READ(4)I
      IU=I+2
      READ(4)(XP(K),YP(K),XMP(K),TH(K),TP(K),PP(K),VLP(K),K=3,IU),BU(1)
      BACKSPACE4
      BACKSPACE 4
      BM(1)=XMP(3)
      BTH(1)=TH(3)
      BT(1)=TP(3)
      BP(1)=PP(3)
      I1=IU+1
2001  BACKSPACE 1
      BACKSPACE 1
      READ(1)I
      READ(1)(SX(K),SY(K),SM(K),STH(K),ST(K),SP(K),SV(K),K=1,I),UU(2)
      BACKSPACE 1

```

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```

BACKSPACE 1
IF(UX(2).NE.SX(1))GO TO 2001
UM(2)=SM(1)
UTH(2)=STH(1)
UT(2)=ST(1)
UP(2)=SP(1)
BACKSPACE 1
BACKSPACE 1
I2=IU+3
READ(1)I
IL=IU+2+I
READ(1)(XP(K),YP(K),XMP(K),TH(K),TP(K),PP(K),VLP(K),K=I2,IL),UU(1)
BACKSPACE 1
BACKSPACE 1
UM(1)=XMP(I2)
UTH(1)=TH(I2)
UT(1)=TP(I2)
UP(1)=PP(I2)
C=(UY(2)-UY(1))/(UX(2)-UX(1))
D=(BY(2)-BY(1))/(BX(2)-BX(1))
XP(1)=(BY(1)-UY(1)+C*UX(1)-D*BX(1))/(C-D)
XP(I1)=XP(1)
YP(1)=UY(1)+C*(XP(1)-UX(1))
YP(I1)=YP(1)
E=(XP(1)-UX(1))/(UX(2)-UX(1))
XMP(1)=UM(1)+E*(UM(2)-UM(1))
TH(1)=UTH(1)+E*(UTH(2)-UTH(1))
TP(1)=UT(1)+E*(UT(2)-UT(1))
PP(1)=UP(1)+E*(UP(2)-UP(1))
UB=UU(1)+E*(UU(2)-UU(1))
E=(XP(1)-BX(1))/(BX(2)-BX(1))
XMP(I1)=BM(1)+E*(BM(2)-BM(1))
TH(I1)=BTH(1)+E*(BTH(2)-BTH(1))
TP(I1)=BT(1)+E*(BT(2)-BT(1))
PP(I1)=BP(1)+E*(BP(2)-BP(1))
UA=BU(1)+E*(BU(2)-BU(1))
CALL RESK
QX=XP(1)*12.
QY=YP(1)*12.
I=1
QT=TH(1)*57.29578
QP=PP(1)/144.
WRITE(6,8990)
U=UB*57.29578
WRITE(6,99)I1,QX,QY,XMP(1),QT,TP(1),QP,U

```

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```

QT=EPF*57.29578
QP=CP/144.
U=CU*57.29578
WRITE(6,99) I1,QX,QY,CM,QT,CT,QP,U
QT=TH(I1)*57.29578
QP=PP(I1)/144.
U=UA*57.29578
WRITE(6,99) I,QX,QY,XMP(I1),QT,TP(I1),QP,U
QP=DP/144.
QT=EPF*57.29578
U=DU*57.29578
WRITE(6,99) I,QX,QY,DM,QT,DT,QP,U
99 FORMAT(1H0,I3,7(3X,E15.8))
8990 FORMAT(1H0,18HSHOCK INTERSECTION)
GO TO 521
CALL TRANS(1,1,2)
CALL TRANS(1,I1,3)
CALL TRANS(I1,1,1)
UI=CU
M=IU+3
J=I1+1
CALL TRANS(J,I1,3)
L=IL
CALL FLDRTN(7)
CU=UI
IL=M
JPL=L
UI=DU
M=3
J=2
CALL TRANS(2,1,3)
L=IU
CALL FLDRTN(8)
DU=UI
JPU=L
IU=M
PP(I1)=CP
TP(I1)=CT
XMP(I1)=CM
PP(1)=DP
TP(1)=DT
XMP(1)=DM
511 KNT=0
KEY=0
MK=0

```

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```

THX=.01745329
EP(1)=EPF
EP(2)=EPF+THX
EP(3)=EP(2)+THX
MQ=3
YD=YP(1)
YC=YP(I1)
TD=TP(1)
TC=TP(I1)
XMD=XMP(1)
XMC=XMP(I1)
XD=XP(1)
XC=XP(I1)
PC=PP(1)
PD=PP(1)
506 DO 500 I=1,MQ
    YP(1)=YD
    YP(I1)=YC
    TP(1)=TD
    TP(I1)=TC
    XMP(1)=XMD
    XMP(I1)=XMC
    XP(1)=XD
    XP(I1)=XC
    PP(I1)=PC
    PP(1)=PD
    M=I1
    L=M+1
    MB=-1
    CALL BPRTN(1,EP(I),XX,MB)
    M=1
    L=2
    CALL BPRTN(2,EP(I),XX,MB)
    IF(XP(I1).GT.XP(1)) GO TO 501
    P7(I)=PD+(XP(I1)-XD)/(XP(1)-XD)*(PP(1)-PD)
    P5(I)=PP(I1)
    GO TO 500
501 P7(I)=PC+(XP(1)-XC)/(XP(I1)-XC)*(PP(I1)-PC)
    P5(I)=PP(1)
500 CONTINUE
    IF(KEY.EQ.0)GO TO 502
    IF(MQ.NE.3)GO TO 503
504 CALL SOLUT(EP,P5,P7,THX,MQ,EPP,EPM)
    KNT=KNT+1
    IF(KNT.GT.20.AND.MQ.NE.1)STOP

```

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```

      GO TO 506
502  XDPP=P5(1)-P7(1)
      XDP=P5(2)-P7(2)
      DPP=ABS(XDPP)
      DP=ABS(XDP)
      KEY=1
      IF(XDPP*XDP.LT.0.) GO TO 504
      IF(DPP.GT.DP)GO TO 504
      THX=-THX
      EP(2)=EP(1)+THX
      EP(3)=EP(2)+THX
      GO TO 506
503  EPF=EP(1)
      XD=XP(1)
      XC=XP(11)
514  QX=XP(11)*12.
      QY=YP(11)*12.
      QT=TH(11)*57.29578
      QP=PP(11)/144.
      WRITE(6,510)
      WRITE(6, 99)I1,QX,QY,XMP(11),QT,TP(11),QP
517  QX=XP(1)*12.
      QY=YP(1)*12.
      QT=TH(1)*57.29578
      QP=PP(1)/144.
      WRITE(6,510)
      L=1
      WRITE(6, 99)L,QX,QY,XMP(1),QT,TP(1),QP
510  FORMAT(1H0,9 HSLIP LINE)
521  CALL FLDRTN(4)
      GO TO 78
606  BACKSPACE 3
      BACKSPACE 3
      CALL FLDRTN(9)
      J2=KNR
      J1=1
      Q1=SX(2)
      Q2=SY(2)
      Q3=SM(2)
      Q4=STH(2)
      Q5=ST(2)
      Q6=SP(2)
      Q7=SV(2)
      DO 609 JK=LSK,KNR
      CALL TRANS (J1,J2,2)

```

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```

      J1=J1+1
609 J2=J2-1
      J1=J1-1
      LSK=J1
      DO 615 JK=1,J1
      CALL TRANS (JK,JK,1)
615 CONTINUE
      BACKSPACE 3
      BACKSPACE 3
      READ(3) I
      K=I+J1
      J1=J1+1
      READ(3)(XP(K1),YP(K1),XMP(K1),TH(K1),TP(K1),PP(K1),VLP(K1),K1=J1,K
1)
      BACKSPACE 3
      BACKSPACE 3
      XP(J1)=Q1
      YP(J1)=Q2
      XMP(J1)=Q3
      TH(J1)=Q4
      TP(J1)=Q5
      PP(J1)=Q6
      VLP(J2)=Q7
      UX(1)=XP(K)
      UY(1)=YP(K)
      BX(2)=XP(LSK)
      BY(2)=YP(LSK)
      L=2
      M=LSK+1
      MM=M
      J=M
      CALL FLDRTN(6)
616 L=2
      M=1
      CALL BPRTN(4,XXB2,YYB2,1)
      K=MM
      DO 950 I=1,MM
      IF(XP(K).NE.XP(K-1)) GO TO 951
950 K=K-1
951 KK=K
      DO 952 I=1,KK
      CALL TRANS(I,K,2)
952 K=K-1
      WRITE(4)KK
      WRITE(4)(SX(I),SY(I),SM(I),STH(I),ST(I),SP(I),SV(I),I=1,KK),UI

```

LIST OF FORTRAN PROGRAM

MAIN PROGRAM

```
MM=MM+1
M=MM
K=LSK+N-1
Q1=UY(2)-UY(1)
Q2=UX(2)-UX(1)
Q3=BY(2)-UY(1)
Q4=BX(2)-UX(1)
ZY=0.
KZ=2
GO TO 6144
6145 CONTINUE
J=M
CALL FLDRTN(3)
GO TO 616
620 NB=N+NL+NU-1
I=NB
J8=1
DO 621 JI=NR,NB
CALL TRANS (J8,I,3)
I=I-1
621 J8=J8+1
DO 622 I=1,KNR
CALL TRANS(J8,I,1)
622 J8=J8+1
KNR=J8-1
GO TO 623
END
```

LIST OF FORTRAN PROGRAM

SUBROUTINE STL2

```

C      SUBROUTINE STL2(XB,YB,NL)
      STARTING LINE COMPUTATION
      DIMENSION YP(600),XP(600),TH(600),XMP(600),TP(600),PP(600),
1 VLP(600)
      COMMON YP,XP,TH,XMP,TP,PP,VLP,GAM,GM1,G,XM,N,P,T,R,L,M,J,NL,XXB2,
1 YYB2,NU,GP1,FE,PA
      DIMENSION XB(100),YB(100)
      PI=3.1415927
12 THST=FE+PI/2.
      FE=FE+(PI/2.-ARSIN(1./XM)+SQRT(GP1/GM1)*ATAN(SQRT(GM1/GP1*(XM*XM-1
1.))) - ATAN(SQRT(XM*XM-1.)))
16 JJ=1
      TSC=SIN(PI+FE)/COS(PI+FE)
1 YD=YB(JJ+1)-YB(JJ)
      XD=XB(JJ+1)-XB(JJ)
      XA=1./((YD/XD- TSC)*((YYB2-YB(JJ))+YD/XD*XB(JJ))-XXB2*TSC)
      IF(XA-XB(JJ))3,2,2
2 IF(XA-XB(JJ+1))4,4,5
5 JJ=JJ+1
      GO TO 1
3 WRITE(6,6)XA,XB(JJ),XB(JJ+1)
6 FORMAT(1H0,3E15.8)
      STOP
4 YP(NL+1)=YB(JJ)+(XA-XB(JJ))/XD*YD
      XP(NL+1)=XA
14 TH(NL+1)=ATAN((YB(JJ+1)-YB(JJ))/(XB(JJ+1)-XB(JJ)))
15 XMP(NL+1)=XM
      PP(NL+1)=P/((1.+GM1/2.*XM**2)**(GAM/GM1))
      TP(NL+1)=T/(1.+GM1/2.*XM**2)
      THP=TH(NL+1)*57.29578
      QX=XP(NL+1)*12.
      QY=YP(NL+1)*12.
      QP=PP(NL+1)/144.
      KN=NL+1
      WRITE(6,10)KN,QX,QY,XM,THP,TP(KN),QP
      XN=N
      XN=XN-1.
      DX=(XXB2-XA)/XN
      MQ=2+NL
      MR=N+NL
      DO 9 MM=MQ,MR
      XP(MM)=XP(MM-1)+DX
      YP(MM)=YP(MM-1)+(YYB2-YP(NL+1))/(XXB2-XP(NL+1))*DX
      XMP(MM)=XM
      TH(MM)=TH(NL+1)

```

LIST OF FORTRAN PROGRAM

SUBROUTINE STL2

```
TP(MM)=TP(NL+1)
PP(MM)=PP(NL+1)
QX=XP(MM)*12.
QY=YP(MM)*12.
KN=1+NL
9 WRITE(6,10)MM,QX,QY,XM,THP,TP(MM),QP
10 FORMAT(1H0,I3,2X,6(3X,E15.8),I5)
RETURN
END
```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

C      SUBROUTINE BPRTN(KODE,X,Y,NX)
      BODY POINT CALCULATIONS
      DIMENSION YP(600),XP(600),TH(600),XMP(600),TP(600),PP(600),
1VLP(600)
      DIMENSION X(100),Y(100)
      DIMENSION FRX(50),FRY(50),FRV(50),FRT(50),FRP(50),FRTH(50),
1FLX(50 ),FLY(50 ),FLP(50 )
      COMMON YP,XP,TH,XMP,TP,PP,VLP,GAM,GM1,G,XM,N,P,T,R,L,M,J,NL,XXB2,
1YYB2,NU,GP1,FE,PA
      COMMON FRX,FRY,FRV,FRT,FRP,FRTH,FLX,FLY,FLP,AT,NF
      COMMON YD,GW,RW,PT,TT ,W,XO
      COMMON/LEE/WX
      CALL SSWTCH(2,JSW)
      IJK=0
      IF(KODE .EQ. 3) GO TO 65
      ITR=1
1004  FORMAT(1H0,40X,18HBODY POINT ROUTINE)
      CP=GAM*R/GM1
      H1=CP*TP(L)*G
      A1=SQRT(GM1*H1)
      V1=XMP(L)*A1
      B1=ARSIN(A1/V1)
      H=WX
      PS=P*(2./GP1)**(GAM/GM1)
      TS=T*(2./GP1)
      S1=CP*ALOG((TP(L)/TS)/((PP(L)/PS )**(GM1/GAM)))+500.
      SB=CP*ALOG((TP(M)/TS)/((PP(M)/PS )**(GM1/GAM)))+500.
      IF(NX.LT.0) GO TO 3000
      IF(KODE.EQ.5)GO TO 5999
      IF(KODE.EQ.4)GO TO 3336
      IF(JSW.EQ.2)
1WRITE(6,1004)
      DO 1 I=1,NX
      K=I
      IF(X(I)-XP(M))1,1,2
1  CONTINUE
20  GO TO (60,61,52),KODE
60  KEY=1
      GO TO 23
61  CONTINUE
23  K=NX
      TH3=ATAN((Y(K)-Y(K-1))/(X(K)-X(K-1)))
      B3=ARSIN(1./XMP(M))
      B4=B3
      A3=SQRT(GM1*CP*TP(M)*G)

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

V3=XMP(M)*A3
T3=TP(M)
TH4=TH(M)
58 CONTINUE
34 C1=(TH3-B3+TH4-B4)/2.
43 C1=SIN(C1)/COS(C1)
B=((Y(K)-YP(L))-(X(K)-XP(L))*C1)/((YP(M)-YP(L))-(XP(M)-XP(L))*C1)
X4=XP(L)+B*(XP(M)-XP(L))
Y4=YP(L)+B*(YP(M)-YP(L))
XM4=XMP(L)+B*(XMP(M)-XMP(L))
TH4=TH(L)+B*(TH(M)-TH(L))
T4=TP(L)+B*(TP(M)-TP(L))
P4=PP(L)+B*(PP(M)-PP(L))
S4=S1+B*(S8-S1)
TH44=TH4*57.29578
A4=SQRT(GM1*CP*T4*G)
V4=XM4*A4
B4=ARSIN(1./XM4)
45 C3=COS((TH3-B3+TH4-B4)/2.)
47 C1=(B3+B4)/2.
C2=COS(C1)
C1=SIN(C1)
48 V3=V4+((V3+V4)/2.*C1/C2)*((TH4-TH3+C1*SIN((TH3+TH4)/2.))/((Y(K)
1+Y4)/2.*C3)*(X(K)-X4)-((T3+T4)/2.)/(((A3+A4)/2.)*2)*C1*C2 *
1(S8-S4)*G))
50 H3=H-.5*V3*V3
A3=SQRT(GM1*H3)
B3=ARSIN(A3/V3)
XMP3=V3/A3
T3=H3/(CP*G)
P3=PP(M)*(T3/TP(M))*[GAM/GM1)
THP=TH3*57.29578
IF(ABS(B-BP)-.000001)56,56,57
57 BP=B
GO TO 58
56 IF(JSW.EQ.2)
1WRITE(6,205)
205 FORMAT(1H0,12HINSERT POINT)
QX=X4*12.
QY=Y4*12.
QP=P4/144.
IF(JSW.EQ.2)
1WRITE(6,1006)M,QX,QY,XM4,TH44,T4,QP
IF(JSW.EQ.2)
1WRITE(6,206)

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

206 FORMAT(1H0,12HCURNER POINT)
    QX=X(K)*12.
    QY=Y(K)*12.
    QP=P3/144.
    IF(JSW.EQ.2)
1WRITE(6,1006)M,QX,QY,XMP3,THP,T3,QP
    VLP(M)=V3
    XP(M)=X(K)
    YP(M)=Y(K)
    XMP(M)=XMP3
    TH(M)=TH3
    TP(M)=T3
    PP(M)=P3
51 CONTINUE
    MP=1
    FLX(NF)=XP(NL+1)
    FLY(NF)=YP(NL+1)
    FLP(NF)=PP(NL+1)
500 FORMAT(6E13.6)
    GW2=GW-1.
    GW1=GW+1.
    HB=CP*G*TP(M)
    AB=SQRT(GM1*HB)
    VB=XMP(M)*AB
    EB=PP(M)/(R*TP(M))
    PBD=PP(M)*((1.+GM1/2.*XMP(M)**2)**(GAM/GM1))
    TBU=TP(M)*((1.+GM1/2.*XMP(M)**2))
    IF(W.EQ.0.)GO TO 4441
    AS=W/(PT*SQRT(GW*G/TT/RW*(2./GW1)**(GW1/GW2)))
    IF(JSW.EQ.2)
1WRITE(6,6666)AS
6666 FORMAT(1H0,6HASTAR=E15.8)
    CALL PRR(YO,PS,AS,PT,GW,XMS,MP,XO,XM1,XM2,PM1,PM2)
    IF(MP.EQ.3)GO TO 7777
    XM1=XO
    PM1=PS
    IF(JSW.EQ.2)
1WRITE(6,305)
305 FORMAT(1H0/1H0,34HTHRUST DISTRIBUTION ALONG THE PLUG)
    SUMM=0.
    SUMV=0.
    NZ=N-1
    DO 91 I=1,NZ
    P12=(FRP(I)+FRP(I+1))/2.
    T12=(FRT(I)+FRT(I+1))/2.

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

R012=P12/(R*T12)
A12=3.1415927*(FRY(I)+FRY(I+1))*SQRT((FRX(I)-FRX(I+1))*2+(FRY(I)
1-FRY(I+1))*2)
TH12=(FRTH(I)+FRTH(I+1))/2.
FE12=ATAN((FRX(I)-FRX(I+1))/(FRY(I+1)-FRY(I)))
V12=(FRV(I)+FRV(I+1))/2.
SQ=FE12-TH12
VM=R012*V12*A12*COS(SQ)
VMOM=VM/G*V12*COS(TH12)
VMOMP=P12*A12*COS(FE12)
VMO=VMOM+VMOMP
SUMM=SUMM+VMO
SUMV=SUMV+VM
91 CONTINUE
CFI=SUMM/(P*AT)
IF(JSW.EQ.2)
1WRITE(6,96)SUMM,CFI
IF(JSW.EQ.2)
1WRITE(6,400)SUMV
400 FORMAT(1H0,23HPRIMARY MASS FLOW RATE=E15.8)
96 FORMAT(1H0,5HSUMM=E15.8,3X,4HCFI=E15.8)
SUMP=0.
NB=NF-1
DO 92 I=1,NB
IF(SUMP)602,602,601
602 CONTINUE
IF(FLX(1)-FLX(I+1))600,92,92
600 IF(I.EQ.1)GO TO 601
P12=(FLP(1)+FLP(I+1))/2.
A12=3.1415927*(FLY(1)+FLY(I+1))*SQRT((FLX(1)-FLX(I+1))*2
1+(FLY(1)-FLY(I+1))*2)
FE12=ATAN((FLX(1)-FLX(I+1))/(FLY(I+1)-FLY(1)))
PI=P12*A12*COS(FE12)
IF(FLY(1)-FLY(I+1))72,73,73
601 P12=(FLP(I)+FLP(I+1))/2.
A12=3.1415927*(FLY(I)+FLY(I+1))*SQRT((FLX(1)-FLX(I+1))*2
1+(FLY(I)-FLY(I+1))*2)
FE12=ATAN((FLX(I)-FLX(I+1))/(FLY(I+1)-FLY(I)))
PI=P12*A12*COS(FE12)
IF(FLY(I)-FLY(I+1))72,73,73
72 PI=-PI
73 SUMP=SUMP+PI
TOT=SUMM+SUMP
CF=TOT/(P*AT)
QX=FLX(I+1)*12.

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

      QY=FLY(I+1)*12.
      IF(JSW.EQ.2)
        1WRITE(6,94)QX,QY,TOT,CF
92  CONTINUE
94  FORMAT(1H0,2HX=E15.8,3X,2HY=E15.8,3X,2HT=E15.8,3X,3HCF=E15.8)
      AX=AT*144.
      IF(JSW.EQ.2)
        1WRITE(6,93)AX
93  FORMAT(1H0,3HAT=E15.8)
      TS=TT/(1.+GW2/2.*XMS**2)
      HS=GW*RW/GW2*TS*G
      SS=SQRT(GW2*HS)
      VS=XMS*SS
      RS=PS/RW/TS
      AB=3.1415927*YO**2
      XXM=RS*VS*AB
      XMB=XXM/G*VS+PS*AB
      TVAC=TOT+XMB
      IF(JSW.EQ.2)
        1WRITE(6,5000)XXM
5000 FORMAT(1H0,25HSECONDARY MASS FLOW RATE=E15.8)
      CFVAC=TVAC/(P*AT)
      AE=3.1415927*YYB2      **2
      THRUST=TVAC-PA*AE
      CFREAL=THRUST/(P*AT)
      PB=PS/144.
      IF(JSW.EQ.2)
        1WRITE(6,6111)TOT,XMB,TVAC,THRUST
6111 FORMAT(1H0,29HTHRUST FROM PLUG NOZZLE WALL=E15.8/1H0,17HTHRUST FRO
      1M BASE=E15.8/1H0,20HTOTAL VACUUM THRUST=E15.8/1H0,49HACTUAL THRUST
      1 (CONSIDERING THE AMBIENT PRESSURE)=E15.8)
4442 PB=PP(M)
      IF(PP(M)-PS)503,503,504
503  IF(JSW.EQ.2)
        1WRITE(6,507)PB,PS
507  FORMAT(1H0,2(3X,E15.8))
      STOP
504  DTT=G*(PB-PS)*SQRT(XMP(M)**2-1.)/EB/VB/VB
      FL=NL
      DT=DTT/(FL-1.)
      IK=NL
      NLL=NL-1
      DO 505 I=1,NLL
        IK=IK-1
        PP(IK)=PB-EB*VB**2/(G*SQRT(XMP(M)**2-1.))*(FLOAT(I)*DT)

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

XP(IK)=XP(M)
TH(IK)=TH(M)-(FLOAT(I)*DT)
YP(IK)=YP(M)
XMP(IK)=SQRT(2./GM1*((PBO/PP(IK))**(GM1/GAM)-1.))
505 TP(IK)=TBU/(1.+GM1/2.*XMP(IK)**2)
CALL TRANS(NL,M,3)
IF(JSW.EQ.2) WRITE(6,6222)
6222 FORMAT(/////////1H0,50X,27HJET FLOW FIELD COMPUTATIONS/1H0,30X,70H(RE
1SULTS VALID EXCLUDING THOSE BEYOND THE POINT OF SHOCK INTERSECTION
1))
IF(JSW.EQ.2)
1WRITE(6,501)
501 FORMAT(1H0,28HLEFT RUNNING CHARACTERISTICS)
I=NL
DO 506 I=1,NL
THP=TH(I)*57.29578
QP=PP(I)/144.
IF(JSW.EQ.2)
1WRITE(6,1006)I,QX,QY,XMP(I),THP,TP(I),QP
506 I=I-1
AA=SQRT(GM1*CP*TP(1)*G)
VPD=XMP(1)*AA
IF(JSW.EQ.2)
1WRITE(6,7002)VPD
TSEC=TT*(PS/PT)**((GW-1.)/GW)
CPP=GW*RW/(GW-1.)
HSEC=CPP*TSEC*G
ASEC=SQRT((GW-1.)*HSEC)
VSEC=ASEC*XMS
IF(JSW.EQ.2)
1WRITE(6,7003)TSEC
IF(JSW.EQ.2)
1WRITE(6,7004)VSEC
IF(JSW.EQ.2)
1WRITE(7,7799)TP(1),TSEC,VPD,VSEC
7799 FORMAT(4E12.5)
J=666
IF(JSW.EQ.2) WRITE(6,6223)
6223 FORMAT(1H0,30X,60HFLOW PROPERTIES COMPUTED ALONG RIGHT RUNNING CHA
1RACTERISTICS)
RETURN
65 NZ=N+NL
TH3=TH(NZ)
XMP3=XMP(NZ)
P3=PP(NZ)

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

      T3=TP(NZ)
      K=1
52  CONTINUE
401 IF(JSW.EQ.2)
      IWRITE(6,207)
207 FORMAT(1H0,29HRIGHT RUNNING CHARACTERISTICS)
1007 FORMAT(I2,E15.8,I2)
      C3=(GAM+1.)/GM1
      C4=1./C3
      TERM=TH3-SQRT(C3)*ATAN(SQRT(C4*(XMP3**2-1.)))+ATAN(SQRT(XMP3**2-1.
1))
      XME=SQRT(2./GM1*((1.+GM1/2.*XMP3**2)/((PA/P3)**(GM1/GAM))-1.)
1)
      XNU=NU
      DM=(XME-XMP3)/(XNU-1.)
      XM=XMP3
53 DO 54 II=1,NU
      XMP(NZ)=XM
      TH(NZ)=TERM+SQRT(C3)*ATAN(SQRT(C4*(XM*XM-1.)))-ATAN(SQRT(XM*XM-1.
1))
      RTHP=TH(NZ)* 57.29578
      TP(NZ)= T3/(1.+GM1/2.*XM*XM)*(1.+GM1/2.*XMP3**2)
      PP(NZ)=P3*((1.+GM1/2.*XMP3**2)/(1.+GM1/2.*XM*XM))
1** (GAM/GM1)
      XM=XM+DM
995 XP(NZ)=X(K)
      YP(NZ)=Y(K)
544 QX=X(K)*12.
      QY=Y(K)*12.
      QP=PP(NZ)/144.
      IF(JSW.EQ.2)
1WRITE(6,1006)NZ,QX,QY,XMP(NZ),RTHP ,TP(NZ),QP
54  NZ=NZ+1
      RETURN
2  J=K-1
      XB1=X(J)
      XB2=X(K)
      YB1=Y(J)
      YB2=Y(K)
300 CONTINUE
      XTH3=TH(M)
      XY3=YP(M)
      XXMX3=XMP(M)
      XB=XB1
      BB=B1

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

VB=V1
TB=TP(L)
AB=A1
KCNT=0
IF(NX.LT.0) GO TO 22
KKNT=0
11 KKNT=KKNT+1
   IF(KKNT-50)111,111,133
133 IF(JSW.EQ.2)
   1WRITE(6,134)XBP,XB,XB1,XB2
134 FORMAT(1H0,4E15.8)
   GO TO 13
111 TH(M)=ATAN((YB2-YB1)/(XB2-XB1))
22 GO TO (33,44),KODE
33 Z1=(TH(L)-B1+TH(M)-BB)/2.
   Z9=TH(L)-TH(M)
   GO TO 55
44 Z1=(TH(L)+B1+TH(M)+BB)/2.
   Z9=TH(M)-TH(L)
55 Z2=COS(Z1)
   KCNT=KCNT+1
   Z10=SIN((B1+BB)/2.)
   Z3=SIN(Z1)/Z2
   Z4=SIN(TH(M))/COS(TH(M))
   Z5=SIN((TH(L)+TH(M))/2.)
   Z7=(B1+BB)/2.
   Z8=COS(Z7)
   Z6=SIN(Z7)
   XBP=(YP(L)-YB1-XP(L)*Z3+XB1*Z4)/(Z4-Z3)
   YP(M)=YB1+(XBP-XB1)*Z4
   VBP=V1+((V1+VB)/2.*Z6/Z8)*(Z9+(Z5*Z10/((YP(L)+YP(M))/2.*Z2)) *
1XBP-XP(L))-((TP(L)+TB)/2./(((A1+AB)/2.)*2)*Z6*Z8)*(SB-S1)*G)
12 HBP=H-VBP*VBP/2.
   AB =SQRT(GM1*HBP)
   XMP(M)=VBP/AB
   TB =GM1*HBP/(GAM*R*G)
   IF(XMP(M)-1.)997,998,998
997 IF(JSW.EQ.2)
   1WRITE(6,134)XMP(M)
   N=0
   NU=0
   NL=0
   RETURN
998 CONTINUE
   IF(ABS((XBP-XB)/XB)-.000001)3,3,4

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

4  BB=ARSIN(1./XMP(M))
   XB=XPB
   ITR=ITR+1
   VB=VBP
   IF(KCNT-50)22,22,333
333 IF(JSW.EQ.2)
   1WRITE(6,134)XPB,XB,XB1,XB2
   3 IF(NX.LT.0)GO TO 13
   IF(XB1-XPB)6,13,5
   6 IF(XBP-XB2)13,13,9
   9 XB1=XB2
   YB1=YB2
   J=J+1
   K=K+1
   IF(K-NX)21,21,200
200 TH(M)=XTH3
   YP(M)=XY3
   XMP(M)=XXMX3
   GO TO 20
21  XB2=X(K)
   YB2=Y(K)
   GO TO 11
   5  XB2=XB1
   YB2=YB1
   J=J-1
   K=K-1
   XB1=X(J)
   YB1=Y(J)
   IF(J)20,20,11
13  THB2=TH(M)*57.29578
   PP(M)=PP(M)*(TB/TP(M))**(GAM/GM1)
   TP(M)=TB
   QX=XPB*12.
   QY=YP(M)*12.
   QP=PP(M)/144.
   VLP(M)=VBP
   XP(M)=XPB
   IF(NX.GT.0.AND.JSW.EQ.2)
   1WRITE(6,1006)M,QX,QY,XMP(M),THB2,TP(M),QP,ITR
   RETURN
1006 FORMAT (1H0,I3,2X,6(3X,E15.8),15)
3336 THD=TH(1)
   IF(JSW.EQ.2)
   1WRITE(6,7000)
7000 FORMAT(1H0,40X,19HFREE BOUNDARY POINT)

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

TD=TP(1)
SD=SB
AB=SQRT(GM1*CP*TP(1)*G)
AD=AB
VB=XMP(1)*AB
VD=VB
BB=ARSIN(AB/VB)
BD=BB
PBO=PP(1)*(1.+GM1/2.*XMP(1)**2)**(GAM/GM1)
3333 Z1=(TH(2)-B1+THD-BD)/2.
Z2=SIN(Z1)
Z3=COS(Z1)
Z4=Z2/Z3
Z5=(TH(1)+THD)/2.
Z6=SIN(Z5)/COS(Z5)
XPD=(YP(2)-YP(1)-XP(2)*Z4+XP(1)*Z6)/(Z6-Z4)
YPD=YP(1)+(XPD-XP(1))*Z6
IF(W.EQ.0.)GO TO 4443
CALL PRR(YPD,PS,AS,PT,GW,XMS,MP,XPD,XM1,XM2,PM1,PM2)
IF(MP.EQ.3)GO TO 7777
XMD=SQRT(2./GM1*((PBO/PS)**(GM1/GAM)-1.))
PD=PS
TD=TP(1)*(PD/PP(1))*(GM1/GAM)
HD=CP*TD*G
AD=SQRT(GM1*HD)
VPD=XMD*AD
BD=ARSIN(AD/VPD)
4446 Z3=COS((TH(2)-B1+THD-BD)/2.)
Z7=(B1+BD)/2.
Z8=SIN(Z7)
Z11=COS(Z7)
Z9=Z8/Z11
Z10=SIN((TH(2)+THD)/2.)
Z12=(TP(2)+TD)/2.
TPD=TH(2)-((VPD-V1)*COS(B1+BD)/SIN(B1+BD)/((VPD+V1)/2.))+Z8*Z10/((
1YP(2)+YPD)/2.*Z3)*(XPD-XP(2))-(((TD+TP(2))/2.)/(((AD+A1)/2.))**2)
1*Z8*Z11)*(SD-S1)*G
IF(ABS((TPD-THD)/THD)-.00001)3335,5552,5552
5552 THD=TPD
IJK=IJK+1
IF(IJK-50)3333,3335,3335
3335 XP(1)=XPD
XM2=XM1
XM1=XPD
PM2=PM1

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

MP=2
PM1=PS
YP(1)=YPD
VLP(1)=VPD
TH(1)=TPD
TPD=TPD*57.29578
TP(1)=TD
PP(1)=PD
XPD=XPD*12.
YPD=YPD*12.
PD=PD/144.
KA=1
IF(JSW.EQ.2)
1WRITE(6,1006)KA,XPD,YPD,XMD,TPD,TD,PD,IJK
IF(JSW.EQ.2)
1WRITE(6,7001)XMS
IF(JSW.EQ.2)
1WRITE(6,7002)VPD
TSEC=TT*(PS/PT)**((GW-1.)/GW)
CPP=GW*RW/(GW-1.)
HSEC=CPP*TSEC*G
ASEC=SQRT((GW-1.)*HSEC)
VSEC=ASEC*XMS
IF(JSW.EQ.2)
1WRITE(6,7003)TSEC
IF(JSW.EQ.2)
1WRITE(6,7004)VSEC
7003 FORMAT(1H0,27HSECONDARY FLOW TEMPERATURE=E15.8)
7004 FORMAT(1H0,24HSECONDARY FLOW VELOCITY=E15.8)
7002 FORMAT(1H0,17HPRIMARY VELOCITY=E15.8)
7001 FORMAT(1H0,22HSECONDARY MACH NUMBER=E15.8)
IF(JSW.EQ.2)
1WRITE(7,1666)XP(1),YP(1),PP(1)
1666 FORMAT(3E16.7)
RETURN
7777 IF(JSW.EQ.2)
1WRITE(6,7778)
N=0
NL=0
NU=0
7778 FORMAT(1H0,10X,20HSECONDARY FLOW CHUKE)
RETURN
4441 PS=PT
GO TO 4442
4443 VPD=VD

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```

      XMD=XMP(1)
      PD=PP(1)
      GO TO 4446
5999 IF(JSW.EQ.2)
      1WRITE(6,5001)
5001 FORMAT(1H0,40X,25HUPPER FREE BOUNDARY POINT)
      II=1
      JP=II
      J=2
      ITR=1
      B3=ARSIN(1./XMP(II))
      B2=ARSIN(1./XMP(J))
      H3=CP*G*TP(II)
      H2=CP*G*TP(J)
      A3=SQRT(GM1*H3)
      A2=SQRT(GM1*H2)
      V3=A3*XMP(II)
      S3=CP*ALOG((TP(II)/TS)/((PP(II)/PS)**(GM1/GAM)))+500.
      S2=CP*ALOG((TP(J)/TS)/((PP(J)/PS)**(GM1/GAM)))+500.
      T3=TH (II)
      C2=(B3+B2)/2.
      C11=SIN(C2)
      C12=COS(C2)
5003 C1=(T3+TH (J))/2.
      C3=(T3+TH (JP))/2.
      C4=C1+C2
      C5=SIN(C4)
      C6=COS(C4)
      C7=C5/C6
      C8=SIN(C3)
      C9=COS(C3)
      C10=C8/C9
      X3=(YP(J)-YP(JP)+XP(JP)*C10-XP(J)*C7)/(C10-C7)
      Y3=YP(J)+C7*(X3-XP(J))
      T3P=TH(J)+(V3-VLP(J))*C12/C11/((V3+VLP(J))/2.)-C11*C5/(YP(J)+Y3)/2
      1.*C6 *(X3-XP(J))+((TP(2)+T3)/2./(((A2+A3)/2.))**2)*C11*C12*(S3-S2)*G
      IF(ABS((T3P-T3)/T3)-.00001)5010,5010,5002
5002 T3=T3P
      IF(ITR.EQ.50)GO TO 5010
      ITR=ITR+1
      GO TO 5003
5010 XP(II)=X3
      YP(II)=Y3
      TH (II)=T3
      TX=T3*57.29578

```

LIST OF FORTRAN PROGRAM

SUBROUTINE BPRTN

```
      QX=X3*12.  
      QY=Y3*12.  
      QP=PP(II)/144.  
      IF(JSW.EQ.2)  
1WRITE(6,1006)II,QX,QY,XMP(II),TX,TP(II),QP,ITR  
      RETURN  
3000 TH(M)=X(1)  
      XB1=XP(M)  
      YB1=YP(M)  
      GO TO 300  
      END
```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

C      SUBROUTINE FLDRTN (IZ)
      FIELD POINT CALCULATIONS INCLUDING SHOCK POINT CALCULATIONS
      DIMENSION YP(600),XP(600),TH(600),XMP(600),TP(600),PP(600),
1VLVP(600)
      DIMENSION FRX(50),FRY(50),FRV(50),FRT(50),FRP(50),FRTH(50),
1FLX(50),FLY(50),FLP(50)
      DIMENSION U4(3),TH1(3),TH(3)
      DIMENSION H(3),A(3),V(3),B(3),S(3)
      COMMON YP,XP,TH,XMP,TP,PP,VLP,GAM,GM1,G,XM,N,P,T,R,L,M,J,NL,XXB2,
1YYB2,NU,GP1,FE,PA
      COMMON FRX,FRY,FRV,FRT,FRP,FRTH,FLX,FLY,FLP,AT,NF
      COMMON YD,GW,RW,PQ,TQ,WH,XD
      DIMENSION SX(600),SY(600),SM(600),STH(600),ST(600),SP(600),SV(600)
      COMMON/BEN/SX,SY,SM,STH,ST,SP,SV
      COMMON/LEE/W
      COMMON/BUN/UX,UY,BX,BY,UI,UM,BM,UTH,BTH,UT,BT,UP,BP,UV,BV,UU,BU
      DIMENSION UX(2),UY(2),BX(2),BY(2),UM(2),BM(2),UTH(2),BTH(2),UT(2),
1BT(2),UP(2),BP(2),UV(2),BV(2),UU(2),BU(2)
      COMMON/TERRY/CP,PT,TT,X14,Y14,XM14,TH14,T14,P14,S14,V14,B14,A14,
1H,A,V,B,S
      COMMON/JUL/KX
      CALL SSWTCH(2,JSW)
      IF(M.EQ.(N+NU+NL-2)) M9=1
      IF(IZ.EQ.9) GO TO 6661
      MS=1
      CP=GAM*R/GM1
      KY=0
      XTH=.0174532925
      IF(IZ.EQ.10.OR.IZ.EQ.11)GO TO 831
      IF(IZ.EQ.7.OR.IZ.EQ.8) GO TO 4
      IF(IZ.EQ.5)XTH=-XTH
      IF(IZ.EQ.4)GO TO 400
      IF(JSW.EQ.2)
1WRITE(6,2)
2  FORMAT(1H0,40X,13HFIELD ROUTINE)
      IF(IZ.EQ.6) GO TO 1555
24  II=M
25  DO 10 IJ=L,M
      ITR=1
18  J=J-1
11  JP=II+1
      IF(IZ.NE.5.AND.IZ.NE.8) GO TO 20
      J1=JP
      JP=J
      J=J1

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

20 DO 8 I=1,2
    J1=J
    IF(I.EQ.2) J1=JP
    H(I)=CP*TP(J1)*G
    A(I)=SQRT(GM1*H(I))
    V(I)=XMP(J1)*A(I)
    B(I)=ARSIN(A(I)/V(I))
    PT=P*(2./GP1)**(GAM/GM1)
    TT=T*(2./GP1)
    S(I)=CP*ALOG((TP(J1)/TT)/((PP(J1)/PI)**(GM1/GAM)))+500.
8 CONTINUE
    IF(KX.NE.5) W=H(1)+V(1)*V(1)/2.
    KX=5
    TP(11)=TP(J)
    B(3)=B(1)
    TH(11)=TH(J)
    S(3)=S(1)
    A(3)=A(1)
    V(3)=V(1)
227 CONTINUE
    Z1=(TH(J)+B(1)+TH(11)+B(3))/2.
    Z2=(TH(JP)-B(2)+TH(11)-B(3))/2.
    Z4=(B(1)+B(3))/2.
    Z5=(B(2)+B(3))/2.
    Z6=(V(1)+V(3))/2.
    Z7=(V(2)+V(3))/2.
    Z12=COS(Z1)
    Z13=COS(Z2)
    Z16=COS(Z4)
    Z17=COS(Z5)
5 FORMAT(1H0,I3,2X,6(3X,E15.8),I3,E13.6)
    Z8=SIN(Z1)/Z12
    Z9=SIN(Z2)/Z13
    Z10=SIN(Z4)
    Z11=SIN(Z5)
    Z14=Z16/Z10
    Z15=Z17/Z11
    Z18=(TP(J)+TP(11))/2.
    Z19=(TH(J)+TH(11))/2.
    Z20=(TH(JP)+TH(11))/2.
    Z21=2.*Z18
    Z32=((A(2)+A(3))/2.)*2
    Z38=(TP(JP)+TP(11))/2.
    Z22=((A(1)+A(3))/2.)*2
    Y8=ABS(Z8)

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

      IF(Y8.LE..000001)XP(II)=XP(JP)+(YP(J)-YP(JP))/Z9
      IF(Y8.GT..000001)
1XP(II)=(XP(J)+1./Z8*(YP(JP)-YP(J)-XP(JP)*Z9))/(1.-Z9/Z8)
      Z25=XP(II)-XP(JP)
      Z26=XP(II)-XP(J)
      YP(II)=YP(JP)+Z9*Z25
      Z23=(YP(J)+YP(II))/2.
      Z24=(YP(JP)+YP(II))/2.
      S(3)=S(1)+((S(2)-S(1))*Z26*(Z10/Z12))/(Z26*Z10/Z12+Z25*Z11/Z13)
      V(3)=1./((Z14/Z6+Z15/Z7)*(TH(JP)-TH(J)+Z14/Z6*V(1)+Z15/Z7*V(2)+
1Z10*SIN(Z19)/(Z23*Z12)*Z26+Z11*SIN(Z20)/(Z24*Z13)*Z25-Z18/(Z22)*Z
210*Z16*(S(3)-S(1))*G-(Z38/Z32)*Z11*Z17*(S(3)-S(2))*G)
      TH3P=TH(J)+(V(3)-V(1))*(Z14/Z6)-(Z10*SIN(Z19))/(Z23*Z12)*Z26+Z18/
1Z22*Z10*Z16*(S(3)-S(1))*G
      H(3)=W-V(3)*V(3)/2.
      A(3)=SQRT(GM1*H(3))
      TP(II)=GM1*H(3)/(GAM*R*G)
      IF(ITR-50)67,67,68
68 IF(JSW.EQ.2)
1WRITE(6,5)II,TH3P,TH(II)
      ITR=1
      GO TO 6
67 IF(ITR-1)7,7,66
66 IF(ABS(TH3P-TH(II))-000001)6,6,7
7 B(3)=ARSIN(A(3)/V(3))
      TH(II)=TH3P
      ITR=ITR+1
      GO TO 227
6 TH(II)=TH3P
      VLP(II)=V(3)
      THPP=TH(II)*57.29578
      PP(II)=PP(J)*((H(3)/H(1))**(GAM/GM1))/(EXP((S(3)-S(1))/R))
      XMP(II)=V(3)/A(3)
      QX=XP(II)*12.
      QY=YP(II)*12.
      QP=PP(II)/144.
500 FORMAT(1H0,6I5)
      IF(IZ.EQ.7.OR.IZ.EQ.8) GO TO 555
      IF(KEY.EQ.9.OR.KEY.EQ.8)GO TO 555
      IF(KEY.EQ.4)GO TO 9
      IF(IZ.EQ.5)GO TO 3122
      IF(L.NE.2)GO TO 3111
      N9=N9+1
      IF(KEY.EQ.3)GO TO 99
9999 TT2=YP(II)-YP(II+1)

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

      TT1=TT2/(XP(II)-XP(II+1))
      THETA=ATAN(TT1)
      IF(((THETA.GE.0.).AND.(TT2.GE.0.)).OR.((THETA.LT.0.).AND.(TT2.LT.0
1.)))GO TO 3111
      GO TO 3
99  IF(YP(II)-YP(LMN))3111,98,98
98  IF((II-1).LE.LMN)JX=JX+1
      IF(JSW.EQ.2)
1WRITE(6,6789)QX,QY,XMP(II),THPP,TP(II),QP
      IP=II+1
      CALL TRANS(II,IP,3)
      I9=I9-1
      YP(II)=YP(II+1)
      IF((II-1).NE.LMN)GO TO 31
      JX=JX-1+(II-LMN)
      J=LMN
      LMN=II
      JP=JP+1
      II=II+1
      GO TO 15
555 IF(KITE.NE.500)U4(1)=UI
      IF(IZ.NE.5.AND.IZ.NE.8)GO TO 988
      J1=J
      J=JP
      JP=J1
988 IF(IZ.EQ.7.OR.IZ.EQ.8) GO TO 155
      U4(2)=U4(1)+XTH
      U4(3)=U4(2)+XTH
      LN=3
      IF(JSW.EQ.2)
1WRITE(6,6789)QX,QY,XMP(II),THPP,TP(II),QP
      GO TO 155
501 CONTINUE
      IF(IZ.EQ.7.OR.IZ.EQ.8) GO TO 5033
      IF(JSW.EQ.2)
1WRITE(6,5)II,QX,QY,XMP(II),THPP,TP(II),QP,ITR
      IF(KEY.NE.9)IXI=II
      IF(KEY.EQ.9)I99=I99-1
      J=I99
      II=II-1
      KEY=9
      GO TO 11
3  IF((II.GT.(N9+NL)).AND.(IZ.NE.5))GO TO 3111
      IF(JSW.EQ.2)
1WRITE(6,6789)QX,QY,XMP(II),THPP,TP(II),QP

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

      KEY=3
      IP=II+1
      CALL TRANS(II,IP,3)
      IF(JSW.EQ.2)
1WRITE(6,42)
42  FORMAT(1H0,40X,17HSHOCK ENCOUNTERED)
      UI=TH(II+1)+B(2)
      IF(IZ.EQ.5)UI=TH(II+1)-B(2)
      U44=UI
      JX=1
      LN=3
      LMN=II+1
      X12=XP(LMN)
      Y12=YP(LMN)
      XM12=XMP(LMN)
      TH12=TH(LMN)
      T12=TP(LMN)
      P12=PP(LMN)
      V12=VLP(LMN)
      B12=B(2)
      I9=LMN-2
      S12=S(2)
      GO TO 31
9  GO TO 311
311 IF((II-1).EQ.LMN)GO TO 15
3111 IF(JSW.EQ.2)
1WRITE(6,5)II,QX,QY,XMP(II),THPP,TP(II),QP,ITR
      GO TO 31
21 IF(KEY.EQ.8)I99=I99-1
      IF(IZ.EQ.7.OR.IZ.EQ.8) GO TO 2121
      J=I99
1111 KEY=8
      GO TO 11
15  X22=X12
      IF(IZ.NE.5)GO TO 989
      J1=J
      J=JP
      JP=J1
989 CONTINUE
      Y22=Y12
      XM22=XM12
      T22=T12
      TH22=TH12
      P22=P12
      B22=B12

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

S22=S12
V22=V12
XJP=XP(J)
LN=3
U4(1)=UI
U4(2)=U4(1)+XTH
U4(3)=U4(2)+XTH
YJP=YP(J)
KKK=0
155 DO 22 I=1, LN
    IF(XP(II).LT.XP(JP))GO TO 21
2121 CONTINUE
    C=(UI+U4(I))/2.
    C1=SIN(C)
    C2=COS(C)
    C=C1/C2
    BB=((YJP -YP(JP))-(XJP -XP(JP))*C)/((YP(II)-YP(JP))-(XP(II)-XP(
1JP))*C)
    X4=XP(JP)+BB*(XP(II)-XP(JP))
    Y4=YP(JP)+BB*(YP(II)-YP(JP))
    TH4=TH(JP)+BB*(TH(II)-TH(JP))
    T4=TP(JP)+BB*(TP(II)-TP(JP))
    V4=VLP(JP)+BB*(VLP(II)-VLP(JP))
    P4=PP(JP)+BB*(PP(II)-PP(JP))
    R2=PP(JP)/R/TP(JP)
    A4=SQRT(GM1*CP*T4*G)
    XM4=V4/A4
    R3=PP(II)/R/TP(II)
    R4=R2+BB*(R3-R2)
    H4=W-V4**2/2.
    IF(LN.EQ.3.AND.KITE.NE.500) GO TO 503
    IF(X4.GT.XP(II))GO TO 501
5033 CONTINUE
    IF(X4.LT.XP(JP))GO TO 601
503 CONTINUE
    X11=X4
    C1=SIN(TH4-U4(I))
    EP=(GM1*XM4**2*C1**2+2.)/(GP1*XM4**2*C1**2)
    Y11=Y4
35 P11=P4+R4*V4*V4/G*(1.-EP)*C1**2
    H11=H4+V4*V4/2.*(1.-EP*EP)*C1**2
    T11=GM1*H11/GAM/R/G
    S11=500.+GAM*R/GM1*ALOG((T11/TT)/((P11/PT)**(GM1/GAM)))
    VN11=V4*EP*C1
    VT11=V4*COS(TH4-U4(I))

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

V11=SQRT(VN11**2+VT11**2)
A11=SQRT(GM1*H11)
B11=ARSIN(A11/V11)
R11=R4/EP
D11=ATAN( EP*C1/COS(TH4-U4(I)))
TH11(I)=U4(I)+D11
XM11=V11/A11
IF(I2.EQ.7.OR.I2.EQ.8) GO TO 41
91 FORMAT(1H0,10I5)
I9=I99
H13=W-VLP(I9)**2/2.
A13=SQRT(GM1*H13)
B13=ARSIN(A13/VLP(I9))
TH14=(TH22+TH(I9))/2.
B14=(B22+B13)/2.
TH1(I)=TH11(I)
IJX=0
X12=X22
Y12=Y22
XM12=XM22
TH12=TH22
T12=T22
P12=P22
V12=V22
B12=B22
S12=S22
36 C=(TH1(I)+TH14+B11+B14)/2.
IF(I2.EQ.5)C=(TH1(I)-B11+TH14-B14)/2.
C1=SIN(C)
C2=COS(C)
C=C1/C2
84 GP=((Y11-Y12)-(X11-X12)*C)/((YP(I9 )-Y12)-(XP(I9 )-X12)*C)
X14=X12+GP*(XP(I9 )-X12)
Y14=Y12+GP*(YP(I9 )-Y12)
IF(X14.GT.XP(I9))GO TO 83
IF(X14.LT.X12)GO TO 383
V14=V12+GP*(VLP(I9 )-V12)
TH14=TH12+GP*(TH(I9 )-TH12)
H13=W-VLP(I9 )**2/2.
A13=SQRT(GM1*H13)
B13=ARSIN(A13/VLP(I9 ))
S13=CP*ALUG((TP(I9 )/TT)/((PP(I9 )/PT)**(GM1/GAM)))+500.
B14=B12+GP*(B13-B12)
T14=T12+GP*(TP(I9 )-T12)
A14=SQRT(GM1*CP*T14*G)

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

S14=S12+GP*(S13-S12)
P14=P12+GP*(PP(I9)-P12)
XM14=V14/A14
IF(ABS(GP-GP0)-.000001)82,82,38
38 GP0=GP
IJX=IJX+1
IF(IJX.EQ.100)GO TO 82
GO TO 36
83 CONTINUE
X12=XP(I9)
Y12=YP(I9)
XM12=XMP(I9)
TH12=TH(I9)
T12=TP(I9)
P12=PP(I9)
V12=VLP(I9)
H12=W-V12**2/2.
A12=SQRT(GM1*H12)
B12=ARSIN(A12/V12)
S12=CP*ALOG((T12/TT)/((P12/PT)**(GM1/GAM)))+500.
I9=I9-1
IF(I9.LE.0.OR.(KITE.EQ.500.AND.I9.LE.L-2)) GO TO 401
H13=W-VLP(I9)**2/2.
A13=SQRT(GM1*H13)
B13=ARSIN(A13/VLP(I9))
TH14=(TH12+TH(I9))/2.
B14=(B12+B13)/2.
GO TO 36
401 IF(JSW.EQ.2)
1WRITE(6,402)
QX14=X14*12.
IF(JSW.EQ.2)
1WRITE(6,6789)QX14
402 FORMAT(1H0,10X,47HSHOCK ROUTINE RAN OUT OF POINTS BELOW THE SHOCK)
KKK=KKK+1
IF(KKK.EQ.20)GO TO 987
U4(1)=U4(1)+XTH
U4(2)=U4(2)+XTH
U4(3)=U4(3)+XTH
LN=3
GO TO 155
987 CONTINUE
N=0
NL=0
NU=0

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

      STOP
      RETURN
82  CONTINUE
      C1=(B14+B11)/2.
      C2=SIN(C1)
      C3=COS(C1)
      TH1(I)=TH14+(V11-V14)*C3/C2/((V11+V14)/2.)-C2*SIN((TH1(I)+TH14)/2.
1)/((Y11+Y14)/2.*COS((TH1(I)+B11+TH14+B14)/2.))*(X11-X14)+(T11+T14)
2/2./(((A11+A14)/2.))**2)*C2*C3*(S11-S14)*G
      IF(IZ.EQ.5)TH1(I)=
1          TH14-(V11-V14)*C3/C2/((V11+V14)/2.)+C2*SIN((TH1(I)+TH14)/2.
2)/((Y11+Y14)/2.*COS((TH1(I)-B11+TH14-B14)/2.))*(X11-X14)-(T11+T14)
3/2./(((A11+A14)/2.))**2)*C2*C3*(S11-S14)*G
      IF(LN.NE.1)GO TO 22
      QX=X14*12.
      QY=Y14*12.
      QP=P14/144.
      THP=TH14*57.29578
      IF(JSW.EQ.2)
1WRITE(6,5678)
5678  FORMAT(1H0,5X,12HINSERT POINT)
      IF(JSW.EQ.2)
1WRITE(6,6789)QX,QY,XM14,THP,T14,QP
6789  FORMAT(1H0,5X,6(3X,E15.8))
22  CONTINUE
      IF(LN.EQ.1)GO TO 41
      CALL SOLUT (U4,TH1,TH11,XTH,LN,U441,U442)
      IF(LN.EQ.1) U44=U4(1)
      IF(LN.EQ.1) GO TO 155
      IF(KY.EQ.3)GO TO 838
      GO TO 155
4004 CONTINUE
      M9=N+NL+NU-M
      M=0
      IF(JSW.EQ.2)
1WRITE(6,4010)
4010  FORMAT(1H0,24HDEFLECTION ANGLE TOO BIG)
      LMN=0
      KEY=1
      J=II
      RETURN
835  B123=B11
      S123=S11
      IU9=I99
      GO TO 912

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

834 B125=B11
    S125=S11
    IL9=I99
    GO TO 912
911 JK=J
    GO TO 9122
41  IF(KEY.EQ.9)II=IXI
    KEY=4
    XP(II)=X4
    YP(II)=Y4
    XMP(II)=V4/A4
    VLP(II)=V4
    TH(II)=TH4
    PP(II)=P4
    TP(II)=T4
    QX=X4*12.
    QY=Y4*12.
    QP=P4/144.
    THPP=TH(II)*57.29578
    NQ=4
    U444=U4(1)*57.29578
    IF(JSW.EQ.2)
1WRITE(6,5)II,QX,QY,XMP(II),THPP,T4,QP,NQ,U444
    IF(IZ.EQ.5)GO TO 4005
    IF(IZ.EQ.7.OR.IZ.EQ.8) GO TO 911
    XM2=XMP(II)**2
    XM4=XM2**2
    FUN=1./((4.*GAM*XM2)*(GP1*XM2-(3.-GAM)+SQRT(GP1*(GP1*XM4-2.*(3.-
1GAM)*XM2+(GAM+9.))))
    ANG=ARSIN(SQRT(FUN))
    AGL=ABS(TH(II)-U4(1))
    IF(AGL.GE.ANG)GO TO 4004
4005 CONTINUE
    X12=X11
    Y12=Y11
    V12=V11
    TH12=TH11(1)
    B12=B11
    T12=T11
    S12=S11
    IF(KITE.NE.500) L=2
    J=I9+1
    M=I9+1
    JK=I9+2
    I99=I9+1

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

9122 IF((IZ.EQ.3.AND.KITE.EQ.500).OR.IZ.EQ.7) GO TO 835
      IF((IZ.EQ.5.AND.KITE.EQ.500).OR.IZ.EQ.8) GO TO 834
912  JX=II-1
      DO 97 IX=JK,JX
      XP(IX)=X11
      YP(IX)=Y11
      XMP(IX)=V11/A11
      TP(IX)=T11
      PP(IX)=P11
      TH(IX)=TH11(1)
97   VLP(IX)=V11
      QP=P11/144.
      THPP=TH11(1)*57.29578
      NQ=11
      NQQ=II-1
      IF(JSW.EQ.2)
1    WRITE(6,5)NQQ,QX,QY,XMP(NQQ),THPP,T11,QP,NQ
      IF(IZ.EQ.7.OR.IZ.EQ.8) GO TO 913
      LMN=LMN+1
      IF(J-1)17,24,24
31   II=II-1
      IF(IZ.EQ.5)J=JP
10   CONTINUE
17   IF(KITE.EQ.500) GO TO9914
      IF(KEY.NE.3) GO TO 95
      I99=I9
      KEY=4
95   UI=U44
      IF(IZ.EQ.3)UXI=UI
      IF (NK.EQ.3) GO TO 914
      IF (NK.NE.2) RETURN
      UX(1)=UX(2)
      UY(1)=UY(2)
      UY(2)=YP(LMN)
      UX(2)=XP(LMN)
      RETURN
914  BX(1)=BX(2)
      BY(1)=BY(2)
      BX(2)=XP(LMN)
      BY(2)=YP(LMN)
      RETURN
913  M=LL
      L=JP
      RETURN
601  JP=JP+1

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

      IF(IZ.EQ.6) GO TO 602
      IF(JP.GT.M+1) GO TO 602
      II=II+1
      JX=JX+1
      LMN=LMN+1
      IF(JSW.EQ.2)
1WRITE(6,403)
604 CONTINUE
403 FORMAT(1H0,10X,18HIGNORE ABOVE POINT)
      KKK=0
      U4(1)=UI
      U4(2)=U4(1)+XTH
      U4(3)=U4(2)+XTH
      LN=3
      IF(IZ.EQ.7.OR.IZ.EQ.8) LN=1
      GO TO 155
602 JP=JP-1
      NK=3
      IF(IZ.EQ.5)NK=2
      IF(IZ.EQ.7.OR.(IZ.EQ.3.AND.KITE.EQ.500))NK=1
      IF(IZ.EQ.8.OR.(IZ.EQ.5.AND.KITE.EQ.500))NK=4
      IP=II+1
      CALL TRANS(II,IP,3)
      BACKSPACE NK
      BACKSPACE NK
      READ(NK)I
      I=M9+I-1
      LL=LL-1
      KQ=0
      IF(KITE.EQ.500)KQ=I-LL
      M8=M9-KQ
      I=I-KQ
      READ(NK)(SX(K),SY(K),SM(K),STH(K),ST(K),SP(K),SV(K),K=M8,1)
      BACKSPACE NK
      BACKSPACE NK
      IF(JP.GT.LL.AND.KITE.EQ.500) GO TO 917
      IF(NK.EQ.3) GO TO 915
      IF(NK.NE.2) GO TO 916
      IF(UX(1).NE.0.) GO TO 9166
      UX(2)=XP(J)
      UY(2)=YP(J)
      BX(1)=XP(N)
      BY(1)=YP(N)
9166 BX(2)=BX(1)
      BY(2)=BY(1)

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

      BX(1)=SX(I)
      BY(1)=SY(I)
      GO TO 916
915  UX(2)=UX(1)
      UY(2)=UY(1)
      UX(1)=SX(I)
      UY(1)=SY(I)
916  CONTINUE
      N=I
1212 DO 603 KI=JP,I
      CALL TRANS(KI,KI,1)
603  CONTINUE
      KX=I-II
      IF(JP.EQ.N) GO TO 1111
      GO TO 604
400  KEY=1
      N9=0
      JX=0
      LMN=0
      RETURN
383  KY=3
      U4(1)=U4(1)+XTH
      U4(2)=U4(2)+XTH
      U4(3)=U4(3)+XTH
      GO TO 155
3122 IF(KEY.EQ.3)GO TO 3999
      TT2=YP(II)-YP(II+1)
      TT1=TT2/(XP(II)-XP(II+1))
      THETA=ATAN(TT1)
      IF((((THETA.LE.0.).AND.(TT2.LE.0.)).OR.(((THETA.GT.0.).AND.(TT2.GT.
10.)))GO TO 3111
      GO TO 3
3999 IF(YP(II)-YP(LMN))98,98,3111
1555 LMN=M-1
      M9=M
      NK=3
      JP=M+1
      J=LMN
      II=M
      I99=LMN-2
      I9=LMN-2
      LN=3
      UI=UXI
      KEY=4
      LM=LMN-1

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

H(1)=CP*TP(LM)*G
A(1)=SQRT(GM1*H(1))
V12=VLP(LM)
B12=ARSIN(A(1)/V12)
X12=XP(LM)
Y12=YP(LM)
XM12=XMP(LM)
TH12=TH(LM)
T12=TP(LM)
P12=PP(LM)
S12=CP*ALOG((TP(LM)/TT)/((PP(LM)/PT)**(GM1/GAM)))+500.
GO TO 15
4 GPO=0.
U4(1)=UI
I99=J-1
M9=M
KITE=500
ITR=1
JP=M+1
LL=L
JX=J-1
IF(JP.GT.LL) GO TO 917
KE=2
IF(IZ.EQ.7)KE=1
62 CALL INSPT(J,JP,M,KE)
IF(X14.GT.XP(M).AND.X14.LT.XP(JP)) GO TO 138
GPO=0.
M=M+1
JP=JP+1
JX=JX+1
GO TO 62
138 LMN=J
YJP=YP(J)
XJP=XP(J)
LN=1
M=JP-1
L=M
J=J+1
GO TO 24
917 CALL EXIT
838 U44=U441
IF(U44.GE.UI.AND.U44.LE.U4(1).AND.IZ.NE.5)GO TO 417
IF(U44.LE.UI.AND.U44.GE.U4(1).AND.IZ.EQ.5)GO TO 417
U44=U442
IF(U44.GE.UI.AND.U44.LE.U4(1).AND.IZ.NE.5)GO TO 417

```

LIST OF FORTRAN PROGRAM

SUBROUTINE FLDRTN

```

      IF(U44.LE.UI.AND.U44.GE.U4(1).AND.IZ.EQ.5)GO TO 417
      GO TO 155
417  U4(1)=U44
      LN=1
      GO TO 155
6661 UX(2)=XP(LMN)
      UY(2)=YP(LMN)
      RETURN
831  LMN=M-1
      II=M
      JP=II+1
      M9=L+1
      KEY=4
      LMX=LMN-1
      X22=XP(LMX)
      Y22=YP(LMX)
      T22=TP(LMX)
      TH22=TH(LMX)
      P22=PP(LMX)
      XM22=XMP(LMX)
      LL=J
      V22=VLP(LMX)
      J=M-1
      XJP=XP(J)
      YJP=YP(J)
      IF(IZ.EQ.10) GO TO 833
      I99=IU9
      IZ=3
      B22=B123
      S22=S123
      XTH=-XTH
      GO TO 601
833  I99=IL9
      IZ=5
      B22=B125
      S22=S125
      GO TO 601
9914 UI=U44
      M=LL
      L=LMN+1
      RETURN
      END

```

LIST OF FORTRAN PROGRAM

SUBROUTINE SAVE

```

SUBROUTINE SAVE(N1,N2,I,K,UI)
  DIMENSION YP(600),XP(600),TH(600),XMP(600),TP(600),PP(600),
1VLP(600)
  DIMENSION SX(600),SY(600),SM(600),STH(600),ST(600),SP(600),SV(600)
  COMMON YP,XP,TH,XMP,TP,PP,VLP
  COMMON/BEN/SX,SY,SM,STH,ST,SP,SV
602 CALL TRANS(I,K,2)
  IF(XP(K).EQ.XP(K-1))GO TO 601
  IF(K.EQ.1)GO TO 601
  I=I+1
  K=K-1
  GO TO 602
601 WRITE(N1)I
  WRITE(N1)(SX(L),SY(L),SM(L),STH(L),ST(L),SP(L),SV(L),L=1,I),UI
  IF(K.EQ.1)RETURN
  K1=K-1
  I1=I+1
  CALL TRANS(I1,K1,2)
  I1=I+2
  K1=K1-1
  KN=K1
  DO 964 J=1,KN
    IF(XP(K1).NE.XP(K1-1))GO TO 965
964 K1=K1-1
965 K1=K1-1
    IL=2
966 CALL TRANS(I1,K1,2)
    K1=K1-1
    IL=IL+1
    I1=I1+1
    IF(K1.GE.1)GO TO 966
    IL=IL-1
    I1=I1-1
    IP=I+1
    K=I1
  WRITE(N2)IL
  WRITE(N2)(SX(L),SY(L),SM(L),STH(L),ST(L),SP(L),SV(L),L=IP,I1),UI
  RETURN
END

```

LIST OF FORTRAN PROGRAM

SUBROUTINE TRANS

```
SUBROUTINE TRANS(I,J,KODE)
  DIMENSION YP(600),XP(600),TH(600),XMP(600),TP(600),PP(600),
1 VLP(600),SX(600),SY(600),SM(600),STH(600),ST(600),SP(600),SV(600)
  COMMON YP,XP,TH,XMP,TP,PP,VLP
  COMMON/BEN/SX,SY,SM,STH,ST,SP,SV
  GO TO(1,2,3),KODE
1 XP(I)=SX(J)
  YP(I)=SY(J)
  VLP(I)=SV(J)
  XMP(I)=SM(J)
  TH(I)=STH(J)
  TP(I)=ST(J)
  PP(I)=SP(J)
  RETURN
2 SX(I)=XP(J)
  SY(I)=YP(J)
  SV(I)=VLP(J)
  SM(I)=XMP(J)
  STH(I)=TH(J)
  SP(I)=PP(J)
  ST(I)=TP(J)
  RETURN
3 XP(I)=XP(J)
  YP(I)=YP(J)
  TH(I)=TH(J)
  XMP(I)=XMP(J)
  PP(I)=PP(J)
  TP(I)=TP(J)
  VLP(I)=VLP(J)
  RETURN
END
```

LIST OF FORTRAN PROGRAM

SUBROUTINE MIR

```

C  SUBROUTINE MIR (N1,N2,A)
    SOLVES A SET OF SIMULTANEOUS EQUATIONS
    DIMENSION A(4,6)
    N3 = N1 + 1
    N = N2 + 1
    DO 100 II = 1,N1
    N4 = N3 - II
    IF(N4.EQ.1) GO TO 8
    JJ1 = 0.
    TEST = ABS(A(1,1))
    DO 6 JJ = 2,N4
    IF(TEST.GE.ABS(A(JJ,1))) GO TO 6
    JJ1 = JJ
    TEST = ABS(A(JJ,1))
6  CONTINUE
    IF(JJ1.EQ.0) GO TO 8
    DO 7 JJ = 1,N2
    A(N3,JJ) = A(1,JJ)
    A(1,JJ) = A(JJ1,JJ)
7  A(JJ1,JJ) = A(N3,JJ)
8  A(N3,N2) = 1./A(1,1)
    DO 15 J1 = 1,N2
15  A(J1,N) = A(1,J1)
    DO 20 J = 2,N2
    J1 = J-1
20  A(N3,J1) = A(1,J)*A(N3,N2)
    DO 30 K = 2,N1
    K1 = K-1
    DO 25 J = 2,N2
    J1 = J-1
25  A(K1,J1) = -A(K,1)*A(J,N)*A(N3,N2) + A(K,J)
30  A(K1,N2) = -A(K,1)*A(N3,N2)
    DO 100 J = 1,N2
100 A(N1,J) = A(N3,J)
    RETURN
    END

```

LIST OF FORTRAN PROGRAM

SUBROUTINE PRK

```

C      SUBROUTINE PRR(Y,PS,AS,PT,GW,XM,MP,X,XM1,XM2,PM1,PM2)
      BASE PRESSURE ROUTINE
      K=0
      GW1=GW+1.
      GW2=GW-1.
      GW3=1.-GW
      GO TO (4,5),MP
5     PTS=PT*(GW1/2.)*(GW/GW3)
      PX=PM1+((PM1-PM2)/(XM1-XM2))*(X-XM1)
      IF(PX.GE.PTS) GO TO 4
      XM=4.
      GO TO 1
4     XM=.1
1     A=3.1415927*Y*Y
      IF(A-AS)6,7,8
7     XM=1.
      GO TO 2
6     WRITE(6,9)A
      MP=3
      RETURN
9     FORMAT(1H0,2HA=E15.8)
8     CONTINUE
      FM=XM*A/AS-((2.+GW2*XM**2)/GW1)*(GW1/(2.*GW2))
      FPM=A/AS-XM*((2.+GW2*XM**2)/GW1)*((3.-GW)/(2.*GW2))
      DM=-FM/FPM
      IF(ABS(DM)-.00001)2,2,3
3     XM=XM+DM
      K=K+1
      IF(K.EQ.50) GO TO 2
      GO TO 1
2     PS=PT*(1.+GW2/2.*XM**2)*(-GW/GW2)
      RETURN
      END

```

LIST OF FORTRAN PROGRAM

SUBROUTINE RESK

```

C      SUBROUTINE RESK
      REFLECTED SHOCK ROUTINE
      DIMENSION YP(600),XP(600),TH(600),XMP(600),TP(600),PP(600),
      1VLP(600)
      COMMON YP,XP,TH,XMP,TP,PP,VLP,GAM
      COMMON/MIKE/EP(3),XMC(3),PC(3),TC(3),XMD(3),PD(3),TD(3),I1,UB,UA,
      1UC,UD
      KT=1
      KNT=1
      THX=.01745329
      Q1=0.
      Q2=1.
      DQ=.1
99 EP(1)=Q1*TH(1)+Q2*TH(I1)
      EP(2)=EP(1)+THX
      EP(3)=EP(2)+THX
      KEY=0
      M=3
9 DO 3 I=1,M
      D=EP(I)-TH( 1)
      PC(I)=PP( 1)
      TC(I)=TP( 1)
      XMC(I)=XMP( 1)
      CALL SHCK (XMC(I),D,GAM,PC(I),TC(I))
      IF(PC(I).EQ.PP( 1)) GO TO 20
      UC=D+TH( 1)
      D=TH(I1)-EP(I)
      PD(I)=PP(I1)
      TD(I)=TP(I1)
      XMD(I)=XMP(I1)
      CALL SHCK(XMD(I),D,GAM,PD(I),TD(I))
      IF(PD(I).EQ.PP(I1))GO TO 20
3 UD=TH(I1)-D
      IF(KEY.EQ.0) GO TO 4
      IF(M.NE.3) RETURN
6 CALL SOLUT(EP,PC,PD,THX,M,EPP,EPM)
      KNT=KNT+1
      IF(KNT.GT.20.AND.M.NE.1) STOP
      GO TO 9
4 XDPP=PC(1)-PD(1)
      XDP=PC(2)-PD(2)
      DPP=ABS(XDPP)
      DP=ABS(XDP)
      KEY=1
      IF(XDPP*XDP.LT.0.)GO TO 6

```

LIST OF FORTRAN PROGRAM

SUBROUTINE RESK

```
IF(DPP.GT.DP)GO TO 6
THX=-THX
EP(2)=EP(1)+THX
EP(3)=EP(2)+THX
GO TO 9
20 Q1=Q1+DQ
Q2=Q2-DQ
IF(Q1.LE.1..AND.Q2.GE.0.) GO TO 99
WRITE(6,7)
7 FORMAT(1H0,18HDELTA.GT.DELTA-MAX)
CALL EXIT
END
```

LIST OF FORTRAN PROGRAM

SUBROUTINE INSPT

C

```

SUBROUTINE INSPT(I,J,K,KODE)
  INSERT POINT ROUTINE
  DIMENSION YP(600),XP(600),TH(600),XMP(600),TP(600),PP(600),
1VLP(600)
  DIMENSION H(3),A(3),V(3),B(3),S(3)
  COMMON YP,XP,TH,XMP,TP,PP,VLP,GAM,GM1,G
  COMMON/TERRY/CP,PT,TT,X14,Y14,XM14,TH14,T14,P14,S14,V14,B14,A14,
1H,A,V,B,S
  KNT=0
  GPU=0.
  DO 3 LI=1,3
    IX=K
    IF(LI.EQ.1)IX=I
    IF(LI.EQ.2)IX=J
    H(LI)=CP*TP(IX)*G
    A(LI)=SQRT(GM1*H(LI))
    V(LI)=XMP(IX)*A(LI)
    B(LI)=ARSIN(A(LI)/V(LI))
  3 S(LI)=CP*ALOG((TP(IX)/TT)/((PP(IX)/PT)**(GM1/GAM)))+500.
    TH14=(TH(J)+TH(K))/2.
    B14=(B(2)+B(3))/2.
  36 IF(KODE.EQ.1) C=(TH(I)-B(1)+TH14-B14)/2.
    IF(KODE.EQ.2) C=(TH(I)+TH14+B(1)+B14)/2.
    C1=SIN(C)
    C2=COS(C)
    C=C1/C2
    GP=((YP(I)-YP(J))-(XP(I)-XP(J))*C)/((YP(K)-YP(J))-(XP(K)-XP(J))*C)
    B14=B(2)+GP*(B(3)-B(2))
    TH14=TH(J)+GP*(TH(K)-TH(J))
    IF(ABS(GP-GPU)-.000001)82,82,38
  38 GPU=GP
    KNT=KNT+1
    IF(KNT.EQ.100)GO TO 82
    GO TO 36
  82 X14=XP(J)+GP*(XP(K)-XP(J))
    Y14=YP(J)+GP*(YP(K)-YP(J))
    V14=VLP(J)+GP*(VLP(K)-VLP(J))
    A14=A(2)+GP*(A(3)-A(2))
    S14=S(2)+GP*(S(3)-S(2))
    T14=TP(J)+GP*(TP(K)-TP(J))
    P14=PP(J)+GP*(PP(K)-PP(J))
    XM14=XMP(J)+GP*(XMP(K)-XMP(J))
  RETURN
  END

```

LIST OF FORTRAN PROGRAM

SUBROUTINE SHCK

```

C      SUBROUTINE SHCK(XM1,DLT,GAM,P1,T1)
      OBLIQUE SHUCK ROUTINE
10  FORMAT(5E15.8)
      IJK=0
      DLO=DLT
      GM1=GAM-1.
      GP1=GAM+1.
      W=ARSIN(1./XM1)
      DW=-.001
      XM2=XM1**2
      XM4=XM2**2
      F=1./((4.*GAM*XM2)*(GP1*XM2-3.+GAM+SQRT(GP1*(GP1*XM4-2.*(3.-GAM)*
1  XM2+(GAM+9.))))))
      WMAX=ARSIN(SQRT(F))
      DMAX=ATAN((XM2*SIN(2.*WMAX)-2.*COS(WMAX)/SIN(WMAX))/(XM2*(GAM+
1  COS(2.*WMAX))+2.))
      IF(DLT.GT.DMAX) GO TO 2
1  CONTINUE
      W=W+DW
      WW=W/.01745329
      X1=SIN(W)
      X2=COS(W)
      X3=XM2*SIN(2.*W)
      X4=XM2*COS(2.*W)
      X6=X2/X1
      X5=XM2*GAM+X4+2.
      DI=ATAN((X3-2.*X6)/X5)
      IF(ABS(DLT-DI).LE..00001)GO TO 3
      DDW=2.*COS(DI)**2/X5*(X4+1./((X1**2)+(X3-2.*X6)*X3/X5))
      D1=DI/.01745329
      DW=(DLO-DI)/DDW
      IJK=IJK+1
      IF(IJK.LT.50) GO TO 1
3  X7=XM2*X1**2
      X8=2.*GAM*X7-GM1
      X9=GM1* X7+2.
      X10=GP1**2*X7
      P2=P1*X8/GP1
      XMM=SQRT(((X10*XM2-4.*(X7-1.)*(GAM*X7+1.))/(X8*X9))
      T2=T1*X8*X9/X10
      P1=P2
      T1=T2
      XM1=XMM
      GO TO 5
5  DLT=W

```

LIST OF FORTRAN PROGRAM

SUBROUTINE SHCK

2 RETURN
END

LIST OF FORTRAN PROGRAM

SUBROUTINE SOLUT

```

C      SUBROUTINE SOLUT(EP,PC,PD,THX,KS,EPP,EPM)
      ITERATION SCHEME TO SOLVE FOR SHOCK ANGLE
      DIMENSION EP(3),PC(3),PD(3),Q(4,6)
      DO 39 I=1,3
        Q(I,1)=1.
        Q(I,2)=EP(I)
        Q(I,3)=EP(I)**2
        Q(I,4)=PC(I)
39     Q(I,5)=PD(I)
        CALL MIR(3,5,Q)
        X1=Q(2,1)-Q(2,2)
        X2=Q(3,1)-Q(3,2)
        X3=SQRT(X1**2-4.*X2*(Q(1,1)-Q(1,2)))
        X4=2.*X2
        EPP=(X3-X1)/X4
        EPM=(-X1-X3)/X4
        IF((EPP.GT.EP(1).AND.EPP.LT.EP(3)).OR.(EPP.LT.EP(1).AND.EPP.GT.
1     EP(3)))GO TO 7
        IF((EPM.GT.EP(1).AND.EPM.LT.EP(3)).OR.(EPM.LT.EP(1).AND.EPM.GT.EP(
13)))GO TO 8
        EP(1)=EP(1)+THX
        EP(2)=EP(2)+THX
        EP(3)=EP(3)+THX
        KS=3
        RETURN
7     EP(1)=EPP
9     KS=1
        RETURN
8     EP(1)=EPM
        GO TO 9
      END
  
```