MAGNETIC AND VELOCITY EFFECTS ON IONOSPHERIC

ELECTRON CURRENT TO CYLINDRICAL ELECTROSTATIC PROBES

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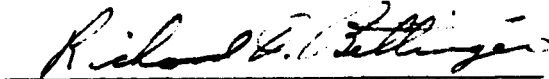COLLEGE PARK, MARYLAND

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                  Current to Cylindrical Electrostatic Probes

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ABSTRACT

Title of Thesis: Magnetic and Velocity Effects on Ionospheric Electron
                  Current to Cylindrical Electrostatic Probes.

Nathan J. Miller, Master of Science, 1967

Thesis directed by: R. T. Bettinger, Assistant Professor of Physics

Ionospheric measurements made with cylindrical electrostatic probes show fluctuations in the current collection due to both the satellite velocity and the earth's magnetic field. These fluctuations represent deviations from the Mott-Smith and Langmuir theory for current collection by electrostatic probes. The present analysis of electron current data from the Explorer 31 satellite probe experiment shows the satellite velocity effects and the magnetic field effects to be re-solvable into separate velocity and magnetic field modulations of current which are superimposed upon some constant electron current. After separation, the manner in which each effect arises is explored in a manner consistent with the data.

The results indicate that ionospheric electron current measure-ments in the accelerating region for cylindrical electrostatic probes may contain a velocity modulation which could increase the current by a factor of two or reduce it by one-half. If the velocity modulations are accounted for, the magnetic modulations can cause fluctuations of from 20 - 60% in the remaining current. Since such current measurements are used to deduce ionospheric electron densities, these velocity and magnetically related electron current modulations should be considered in evaluating ionospheric electrostatic probe data.

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CHAPTER I

THE IONIZED COMPONENT OF THE EARTH'S ATMOSPHERE

Introduction

In terms of significant ionization, the earth's ionized
atmosphere extends from near 50 km to the boundary of the earth's
magnetic field. However, charged particles are a minor constituent
of the earth's atmosphere until altitudes near 1500 km where neutral
and charged particle densities become comparable. The charged
particle density increases to an altitude near 400 km. Above that
height, the decreasing atmospheric density causes the ion density to
decrease with altitude, though the percentage of ionization continues
to increase.

The Ionosphere

The term "ionosphere" could be applied to the total altitude
range of atmospheric ionization, but the ionosphere proper is that
portion of the earth's atmosphere which significantly influences ground-
based radio wave propogation. This definition is used because it was
through radio wave interactions that the charged particle region between
60 and 400 km was discovered. Radio wave reflection occurs whenever
the free electron density of a medium changes. However, total reflection
occurs whenever the radio frequency is less than a critical frequency ω_p,
termed the plasma frequency which is specified by the electron density
n_e through the relation

$$\omega_p = \left(\frac{n_e e^2}{m\varepsilon}\right)^{\frac{1}{2}}$$

The properties of the medium containing the free electrons is accounted for by the term ϵ, the permitivity of the medium while m and e are the electronic mass and charge respectively. Since n_e is the free electron number denisty at a point in space, scanning a frequency range of radiowaves sent upward from the earth and noting the time interval between emission and reception leads to an altitude profile of electron density, so long as the density is increasing. Ground-based studies have implied a layered structure for the ionosphere, as shown in Figure 1. Each ionization layer is specified by a letter.

The lower D region is sometimes referred to as the C region and extends between 50 and 70 km. The C region has associated with it a maximum electron density near 10^2/cc. The ionization source is cosmic ray interactions with the neutral atmosphere. The electron density disappears at night and maintains its maximum value at a constant height during daytime. This behavior results from an attachment of electrons to neutrals. The resulting negative ion is readily dissociated by sunlight.

$$O_2 + e + M \rightarrow O_2^- + M$$

Electron Attachment

$$O_2^- + h_v \rightarrow O_2 + e$$
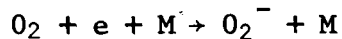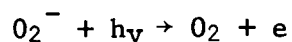
Photodetachment

Cosmic rays penetrate below the C region but attachment processes are

strong enough and solar radiation transmission is weak enough to make the free electron density negligible.

The most important process for producing D region ionization is the photoionization of NO by Lyman – α solar radiation (Nicolet and Aiken, 1960).

$$NO + h_v \rightarrow NO^+ + e$$
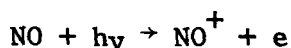
This region forms between 70 and 85 km and has associated with it a maximum of electron density near 10^3/cc. The altitude maximum electron density increases with decreasing solar zenith angle in a predictable manner during the daytime. The nighttime electron density effects on radio waves become negligible because of electron losses in dissociative recombination reactions and electron attachment to neutrals.

$$N_2^+, \; O_2^+ \} + e \rightarrow \begin{cases} N + N \\ O + O \end{cases}$$
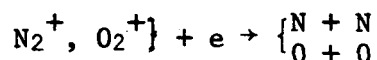
Dissociative Recombination

Atmospheric NO is only present in small quantities but it appears that the amount present is sufficient to account for NO as the principle ion in the D region. Some ions must be formed from x-ray photoionization of O_2 and N_2 because there is a solar cycle effect in the electron density variations which does not occur in the Lyman – α radiation.

The altitude range between 85 and 150 km is the E region, which has a daytime electron density maximum near 10^4/cc. This region

forms a transition from a realm in which charged particle motions are constrained by the geomagnetic field. In the E region, the electron motions are governed by the magnetic field lines and the ion motions are governed by the neutral particle motions. This behavior pattern emerges because the electron-neutral collision frequencies have decreased sufficiently for magnetic effects to be important while the ion motions are still collision dominated. The neutral particle motions also are changing in the E region, from a condition of convective equilibrium which existed below, to a condition of diffusive equilibrium. The result is that the altitudinal distribution of neutral particles is approximately described by the barometric formula

$$\frac{d \ln n_s}{dZ} = \frac{m_s g}{k T_s}$$

which applies for diffusive equilibrium conditions. Z represents the altitude, n_s is the number density of one neutral constituent, m_s and T_s are the mass and temperature of the same constituent, g is the gravitational acceleration at height Z, and k is the Boltzmann constant. The ionization is formed by photoionization of O, O_2, and N_2 by normal solar x-ray flux. As with the D region, the height of the daytime electron density maximum increases in a predictable manner with decreases in solar zenith angle. However, radio wave effects continue at night because of ionization from meteors, and decreased recombination and electron attachment reactions.

In the F region, which lies between 150 and 400 km, the neutral

particles have reached diffusive equilibrium. The principle

ionization reaction is solar ultraviolet photoionization of O.

The continuing decrease in atmospheric density with increasing

altitude has a great impact upon the charged particles in this

region. The collision frequencies have decreased enough that both

ion and electron motions are constained by the magnetic field lines;

transport into and out of the upper F region is great enough that

the ion composition can no longer be predicted by local chemical

processes alone; lastly, the electron loss mechanism charges from

one in which dissociative recombination determines the loss rate to

one in which the ion-atom interchange reactions are rate determining.

$$\left.\begin{array}{l} N_2^+ + O \\ N_2 + O^+ \end{array}\right\} \rightarrow NO^+ + N \qquad\qquad NO^+ + e \rightarrow N + O$$

<u>Ion-Atom Interchange Followed By Dissociative Recombination</u>

The last effect leads to two maxima of electron density, the F_1

maximum with electron densities near 10^5/cc around 200 km, and the

F_2 maximum between 300 and 400 km with electron densities near 10^6/cc.

The F_1 maximum occurs in the vicinity of the F region photoionization

maximum. Near this same position, the loss mechanism changes form.

The photoionization above the F_1 peak depends on the concentration of

O whereas the loss rate by ion-atom interchange depends on the concentra-

tion of N_2. Since the N_2 density decreases with altitude much more

rapidly than the O density, the loss rate for electrons decrases much

more rapidly than the production rate resulting in an increasing electron

density as the altitude increases to the position of the F_2 maximum. The

height of the F_1 maximum increases with decreasing solar zenith angle until it merges with the F_2 maximum. The F_2 maximum is present during both day and night. Its behavior is not well correlated with that of normal solar radiation, hence the current view is that there is an important secondary ionization source for the F_2 region, (Antonova and Ivanov-Kholodnyy, 1961).

The Topside Ionosphere

The topside ionosphere is the ionized atmosphere above the F_2 maximum. The bottomside ionosphere can be characterized as a region in which photo-chemical processes strongly influence the charged particle composition. The equation describing chemical equilibrium is of the form

$$\frac{dn(XY^+)}{dt} \; = \; q - L = 0 \; .$$

where

$$n(XY^+)$$

is the density of a molecular ion XY^+. q is the production rate for XY^+ and generally is of the form $k_\lambda F_\lambda n(XY)$ where k_λ is a production rate coefficient and F_λ is the solar flux for a given wavelength interval. L is the loss rate and generally is of the form $\alpha n_e n(XY^+)$ where α is a recombination coefficient for dissociative recombination and n_e is the ambient electron density. At the F_2 maximum, chemical processes and transport processes have become equal in importance, so the continuity equation for an ionic species must add a transport term and take the form

$$\frac{dn(XY^+)}{dt} = q - L - \frac{d\ n(XY^+)v}{ds}$$

where v is the ionic transport velocity and s is distance along a
magnetic field line. Within the topside ionosphere, transport
processes become the dominant factor in determining the charged particle
composition. Therefore, the topside ionosphere can be characterized
as the region of the ionosphere in which the charged particles approach
diffusive equilibrium.

At topside altitudes, the neutral particle collision frequencies
are so small that the neutrals perform ballistic motions. If neutral
particles velocities are high enough particles can escape from this
neutral exosphere. Standard gas laws based on fluid behavior no
longer describe the neutral density distribution (Chamberlain, 1963)
under these circumstances. In contrast, the long range coulomb forces
guarantee that charged particle collision frequencies will remain
important in the topside ionosphere.

Because of coulomb interactions, the diffusive equilibrium
which charged particles can attain is a modified form of the diffusive
equilibrium which neutrals reach. For a single ionic species,
diffusive equilibrium is described by the equation

$$\frac{d\ ln\ n_s}{dz} = -\frac{m_s\ g}{k(T_e + T_i)}$$

where T_i and T_e are the temperatures of the ions and electrons
respectively. The equation is similar to the barometric equation
for neutrals except that the ion and electron temperatures must be

considered separately. The difference in form occurs because there can be no appreciable charge separation between ions and electrons. The electrons, which from mass considerations should diffusive to much greater heights than any ion, must drag the ions along because charge separation produces polar electric fields which act on the ions. The result is that ions diffuse to much greater heights than would neutrals of the same mass and temperature. In the topside ionosphere, the charged particles must diffuse along magnetic field lines and also there is more than one ionic species present at a time. Both factors modify the manner in which diffusion takes place among charged particles and can produce situations in which diffusive equilibrium requires that the density of a minor ion should increase with altitude.

The principal ions in the topside ionosphere are O^+, H^+, and He^+. The process for ion production is photoionization of the atoms by normal solar x-rays and ultraviolet radiation. Coupling between the topside ionosphere above 1000 km and the F region of the ionosphere has been investigated in an attempt to explain the nighttime F_2 peak (Geisler and Bowhill, 1965). It was found that magnetically aligned charged particle fluxes between the topside ionosphere and the F region of the ionosphere would be insufficient to account for the nighttime F_2 maximum. However, it was found that fluxes of photoelectrons flowing from the F region to the daytime topside ionosphere could explain the topside electron temperature structure. At night then, there would be charged particle fluxes from the topside ionosphere to the F region. The character of the ion transport changes at various altitudes causing

the degree to which diffusive equilibrium is approached to vary similarly. For example, near the F_2 maximum the diffusion is 0^+ through a predominately atomic oxygen atmosphere; near 700 km the diffusion is H^+ through a mixture of 0 and He. The data presented in this thesis was taken in the region above 700 km where H^+ is the major diffusing ion.

CHAPTER II

THE EXPLORER·31 ELECTROSTATIC PROBE EXPERIMENT

Introduction

The Explorer 31 satellite was launched on November 29, 1965
into an elliptical orbit about the earth. The orbit apogee is
3000 km and the perigee is 500 km. The satellite's spin axis is
nearly perpendicular to the satellite translational velocity. The
satellite carries a number of experiments to measure atmospheric
parameters, among which is a Langmuir probe experiment. This consists
of two cylindrical electrostatic probes mounted near the bottom of the
satellite and at opposite ends of a satellite diameter.

The cylindrical electrostatic probes are conducting wires
which extend into the ionized medium and are connected to a voltage
generator on the satellite. The schematic diagram in Figure 2 shows
the relationship between the probes and the satellite's translational
velocity while the satellite rotates. The experimental procedure
is to monitor the current drawn as the probe voltage is swept in 1
second from −2 to +5 volts relative to the satellite potential. At the
endpoint of a voltage sweep, satellite spatial relationships are
measured, e. g. the angle between the probe axis and the sun direction.
While one probe is being used for measurements appropriate to electron
temperature determinations, the other is being used for measurements
appropriate to the determination of electron densities. The wake region
of the satellite path is not suitable for making these measurements and,

therefore, meaningful temperature and density determinations are
separated in time by at least the time necessary for the satellite
to rotate through 180°. This time is 10 seconds and represents a
spatial distance of 80 km.

Measurement Theory

The theory of electrostatic probe current collection was
summarized by Mott-Smith and Langmuir in 1926. When a conductor is
immersed into the ionospheric plasma, it will normally become
negatively charged because the electrons move faster than the ions
and, therefore, accumulate faster. The limit of the charge buildup
is reached when incoming electrons and ions are affected by the
negative charge to the extent that the flux of ions and electrons
to the conductor becomes equal, resulting in no net current. The
potential distribution about the negatively charged conductor is only
significant over a limited region of space surrounding the conductor
known as the plasma sheath. Essentially all of the potential difference
between the conductor and the plasma falls within this sheath. Therefore,
the theory assumes that all plasma particles beyond the sheath behave
as though the conductor were not present.

The thermal motions of charged particles cause some to diffuse
into a sheath region where they are affected by the potential
distribution. If the potential on a conductor is varied, as is done
with an electrostatic probe, the sheath dimensions will vary similarly.
However, under the assumptions of no collisions within the sheath region
(Mott-Smith and Langmuir, 1926), it was found that the current to an

infinite cylindrical probe was independent of the sheath dimensions and potential distribution so long as the sheath radius was much larger than the probe radius and the potential distribution was monotonic. The probe equations correlate with observed cylindrical probe characteristics as typified by the one in Figure 3.

The equation

$$ j = \frac{ne\bar{v}}{4} \left(\frac{2}{\sqrt{\pi}} \right) \left(1 + \frac{eV}{kT} \right)^{\frac{1}{2}} $$

where j is current density, describes the ion or electron flux to a cylindrical probe at rest in the ion or electron accelerating region of a cylindrical probe characteristic curve for a Maxwellian velocity distribution whenever $eV \geq 5kT$.

n = the number density of the charged species

e = the electronic charge

T = the temperature of the charged species

k = the Boltzmann constant

$\bar{v} = \left(\frac{8kT}{\pi M} \right)^{\frac{1}{2}}$ = the mean velocity of a Maxwellian velocity distribution

V = the probe potential relative to the plasma potential

The electron accelerating region is the voltage range where the probe is positive enough to repulse all ions resulting in only electron current collection. The ion accelerating voltage range is a negative counterpart to the electron accelerating range. The accelerated charged particle current can be used to deduce charged particle densities from the current equation.

In the electron retarding voltage region the probe has a

negative potential but some of the electrons are energetic enough
to reach the probe anyhow. The electrons arriving at the probe
cancel some of the ion flux which the negative probe attracts. The
equation

$$j = \frac{ne\bar{v}}{4} \exp[eV/kT]$$

applies to the retarded electron component of the charged particle
flux to the probe in this region. The retarded electron current can
be used to determine electron temperatures from the current equation.

Measurement Results

Satellite measurements in the ionosphere introduce complications
into electrostatic probe theory since the satellite velocity and
the magnetic field both affect the charged particle flux to the
probe. We define the angle between the probe axis and the velocity
of the satellite to be the aspect angle, θ, and the angle between the
probe axis and the magnetic field direction to be the field angle, ϕ.
Determinations of both of these angles are made at the ends of the
probe voltage sweeps and their values appear on data sheets along with
the probe current values. Plots of the raw current values at the
positive maxima of the probe characteristics taken from the Explorer 31
satellite data yield results similar to the plots in Figures 4 and 5.
The data was taken while the satellite was traversing its orbit through
changing altitudes and electron densities. Since this data only includes
current taken as a satellite probe rotated into the forward direction
of the satellite's orbital motion, what would appear as a single curve,
increasing or decreasing monotonically in time, appears on the graphs

as unconnected curves because of the omission of wake region data.
Moreover, there is the presence of a periodic fluctuation within the
data producing minima and maxima at various aspect angles. The plots
of data show that the periodic fluctuations are related to both the
aspect and field angles, hence, it is desirable to separate the current
modulation into its components before attempting to explain the
variations which appear.

The first assumption in the separation procedure is that in
the electron accelerating region of the cylindrical probe characteristics,
the electron current divided by the square root of the probe potential
relative to the plasma potential is proportional to the electron density.
Taking note of the equation describing the probe electron current for this
voltage region shows that this is equivalent to assuming that eV/kT
is enough greater than 1 to ignore the 1 in $(1 + eV/kT)^{\frac{1}{2}}$. For the data
that was analyzed $eV/kT \geq 5$ which makes a maximum error of 9% resulting
from this assumption.

The time for a probe to rotate through the forward aspect angles
on the Explorer 31 satellite is 10 seconds during which there should be
only slight variations in the electron density. Therefore, a plot of
$I/V^{\frac{1}{2}}$ values taken at the maxima of the probe characteristics against
forward aspect angle should give a series of nearly straight horizontal
lines. The fact that this is not the case is due to the modulations
caused by satellite velocity and magnetic field effects in the ionosphere,
which leads to the next assumption in the separation procedure. The
reference level for velocity induced modulations is arbitrarily defined

as zero at 90° aspect angle. Under these conditions, the electron current to a rotating cylindrical probe with an orbital motion in the ionosphere would draw the same current at 90° aspect angle as the same probe without its orbital motion, i.e. there is only a magnetic field modulation of current.

Another assumption in separating magnetic and velocity effects on ionospheric probe current is that the velocity modulation of current should be strictly symmetrical about $\theta = 0$, and a function which gives the magnetic modulation of current should be nearly symmetrical about $\phi = 90^O$. The objective of the separation is to obtain the two functions, $V(\theta)$ and $M(\phi)$. $V(\theta)$ gives the satellite velocity induced modulation of $I/V^{\frac{1}{2}}$ as a function of field angle.

Define the experimental values of $I/V^{\frac{1}{2}}$ as the function $I(\theta,\phi)$. Then $I(\theta,\phi) = V(\theta) + M(\phi)$ where $V(\phi)$ and $M(\phi)$ have been defined and any interaction between velocity and magnetic effects has been assumed to be constant or negligible. $V(\theta)$ is zero at $\phi = 90^O$ and is symmetrical about $\theta = 0^O$. $M(\phi)$ represents the unperturbed electron current with a magnetically modulated current added. The first step in the separation procedure is to make one plot of $I(\theta,\phi)$ against forward aspect angle and another plot of $I(\theta,\phi)$ against field angle, where the data is taken at the maxima of the probe characteristics. For each value of $I(\theta,\phi)$, there corresponds a field angle and an aspect angle which are coupled to each other. $I(\pm 90^O,\phi_1) = M(\phi_1)$ because $V(\pm 90^O) = 0$. In the first approximation $M_1(\phi_1) = M_1(\phi_1{'})$ where ϕ_1 and $\phi_1{'}$ are supplements; therefore, $V_O(\theta_2) = I(\theta_2,\phi_1{'}) - M_1(\phi_1{'}) = I(\theta_2,\phi_1{'}) - I(90^O,\phi_1)$. Now $V_O(\theta_2) = V_O(-\theta_2)$, therefore,

$M_1(\phi_3) = I(-\theta_2,\phi_3) - V_o(-\theta_2)$. Since $M_1(\phi_3) = M_1(\phi_3{'})$, then,

$V_o(\theta_4) = I(\theta_4,\phi_3{'}) - M_1(\phi_3{'})$. $V_o(\theta_4) = V_o(-\theta_4)$ gives $M_1(\phi_5) =$

$I(-\theta_4,\phi_5) - V_o(-\theta_4)$. Continuing in this vein allows one to get

a first approximation, $M_1(\phi)$ to the function $M(\phi)$ by plotting

the values $M_1(\phi_1)$, $M_1(\phi_1{'})$, $M_1(\phi_3)$, $M_1(\phi_3{'})$, etc. against ϕ.

A numerical example of the first steps of the procedure is

presented in the Appendix. The values of $M_1(\phi)$ can be compared with

$I(\theta,\phi)$ to obtain the first approximation to $V(\theta)$.

If $V_1(\theta)$ is not symmetrical about zero aspect angle one can

get a second approximation to $V(\theta)$ and $M(\phi)$ by drawing a mean

curve for $V_1(\phi)$ which is the symmetrical $V_2(\phi)$. Then $I(\phi,\theta) -$

$V_2(\theta) = M_2(\phi)$.

The results of applying this procedure to the data which appears

in Figures 6 and 7 are shown in Figures 8 and 9. Similar results for

data taken at other altitudes are shown in Figures 10 through 13.

The final $V(\theta)$ curve represents the effect of a translational motion

on the electron flux to a rotating satellite's electrostatic probe

in the absence of a magnetic field where $V(\pm 90^\circ) = 0$. The final $M(\phi)$

curve represents the effect on the electron flux to a rotating

satellite's electrostatic probe due to a magnetic field when there is

no satellite orbital motion. The $M(\phi)$ curve shows the magnetic effect

superimposed upon a constant current.

CHAPTER III

CONCLUSIONS

The results of probe measurements which have been presented
illustrate the extent to which magnetic fields and satellite motion
can affect electron current collected by cylindrical electrostatic
probes. A mechanism for explaining these effects can be developed,
by viewing the sheath surrounding a positively charged cylindrical
probe as possessing a nearly uniform electron density, approximating
that of the surrounding medium and a nonuniform ion density
distribution. Within the sheath, the ion density will approach that
of the surrounding medium with increasing radial distance from the
probe. The sheath edge occurs at that surface where the sheath
volume contains sufficient charge to "shield" the charge associated
with the potential of the probe. Magnetic and velocity effects modify
the sheath structure by changing the charged particle distribution
within the sheath.

In general, discussions of the effects of satellite velocities
upon electrostatic probe currents have not emphasized the case of
electron currents in the accelerating region of probe characteristics
because the thermal velocities for electrons are so much greater than
the satellite velocities. However, the sheath structure for a positive
probe is modified as a consequence of the satellite velocity. The
results of the present data analysis suggest that current collection
depends upon sheath structure. When the satellite traverses its orbit
the satellite probe is rotating through a sea of electrons whose density

distribution is not greatly affected by the probe motion. However, the ion distribution in the probe sheath is affected because the ions do not move as rapidly as the probe. At 90° aspect angle, the ion distribution in the forward portion of the sheath is denser than in the rearward portion, resulting in a sheath which is not symmetrical about the probe axis. The spatial effect is that the sheath becomes elliptically shaped as shown in Figure 14. The equipotential surfaces which enclose circular areas near the probe, enclose elliptical areas as the sheath edge is approached. This deformation of sheath structure results in a modification in current collection as the aspect angle changes from 0° to 90°.

The Mott-Smith and Langmuir equations were derived for a sheath which was symmetrical about an infinite stationary cylindrical probe. These conditions are most nearly met at 0° aspect angle. However, the finite length of the probe makes current through the end of the cylindrical sheath a possibility. When the aspect angle is zero, the ion distribution near the end of the probe is altered because the ions are being overtaken by the probe. This situation requires that the sheath should extend farther from the probe end. The sheath deformation near the end of the probe causes extra amounts of electron current to be collected.

The velocity modulations of electron current depend upon the ion temperatures and masses rather than upon the electron properties as it is the ion motions which are producing the changes in sheath structures. The velocity modulation, neglecting end effects, decreases as ion temperatures increase because the ions are able to distribute themselves

about the probe more symmetrically at higher temperatures. In contrast,
it has been suggested (Bettinger, 1966) that the end effect
modulation for ion current to a negative cylindrical probe should
increase in angular width as ion temperatures increase. Under the
present mechanism one expects the same type of dependence for electron
current to a positive probe. Combining these temperature effects
suggests that at the lowest ion temperatures the function $V(\theta)$ should
become increasingly negative at decreasing θ. As the ion temperatures
increase, a positive effect will appear at small aspect angles which
gradually increases in magnitude while the negative effects at larger
aspect angles are gradually decreasing in magnitude. In some cases
a temperature will be reached at which the negative and positive
modulations cancel each other. Then $V(\theta) = 0$ for all $\theta \leq 90^{\circ}$. At
the highest ion temperatures, only an end effect velocity modulation
will appear, resulting in a positive valued $V(\theta)$ which increases in value
as θ decreases. Examples of all of these conditions can be seen in the
$V(\theta)$ curves presented in Figures 8, 10, and 12.

The magnetic field effects are complex to discuss because the
charged particles are constrained to spiral about the magnetic field
lines. This constraint means that the mean free path across the field
lines is the gyro-radius of the particles and that charged particles
move at faster rates along the field lines than across them. The concept
of a guiding center, the position of the instantaneous center of the
charged particle orbit, can be used to describe the charged particle
motions along magentic field lines. The electrons which enter the probe
sheath must have guiding centers that came from within a tube in space

of height $(R_e + L \sin \phi + 2R_s \cos \phi)$ where L is the length of the probe including the sheath thickness at the end, R_e is the electron gyro-radius, R_s is the outer radius of the sheath, and ϕ is the field angle, excluding zero. The width of the tube is $2(R_s + R_e)$ when the field angle is zero. The satellite adds to the modulation effects since the satellite presence interferes with some of the flux which would normally enter the probe sheath and is the reason that the field tube cross section abruptly changes at zero field angle. Figure 15 illustrates the interception of the magnetic field lines by the satellite.

Because of the magnetic field constraints on charged particle motions and the satellite presence, electron current to a satellite probe is less than for zero magnetic field. When the probe is perpendicular to the magnetic field lines, its sheath will be elliptically shaped about the probe axis as shown in Figure 16. When the probe is aligned with the field, the sheath will be circular about the probe axis with the sheath thickness increased from that at zero magnetic field. The elliptical sheath cross section and the increase in sheath thickness occur because sheath formation by ion repulsion requires motions across the magnetic field lines, which is difficult to achieve. The increased amount of positive charge remaining near the probe requires that more volume must be included in the sheath in order to encompass enough negative charge to cancel a positive probe potential.

Most electrons reaching the probe at $180°$ or zero field angles must cross field lines to do so. In contrast, many electrons arriving

at the probe for 90° field angle can do so by traveling along field lines and the elliptical sheath configuration intercepts more than the normal number of field lines. The magnetic field presence results in a current which reaches a maximum at 90° field angle and minima at 0° and 180° field angle. For no translational probe velocities, there may still be an end effect because it is easier for electrons to enter the end of the probe when the probe is aligned with the field lines. The plotted $M(\phi)$ curves do not conflict with the stated model.

The state of theories concerning magnetic modulations of probe current collection was reviewed by Chen in 1965. The primary difficulty in accounting for magnetic field effects is that a collisionless theory may not be adequate. Magnetic collisions within the sheath can only be ignored if the gyro-radius, R_g, is greater than the Debye length, h. The mean gyro-radius for an ionospheric electron is $mc\bar{v}/Be$ where B is the geomagnetic field strength; and h is $(kT/4\pi ne^2)^{1/2}$ where n is the electron number density.

$$R_g/h = \frac{mc}{Be} \left(\frac{8kT}{\pi m}\right)^{1/2} [4\pi ne^2/kT]^{1/2} \sim \frac{5.7(mn)^{1/2}c}{B}$$

For the conditions of the present analysis

$$10^3/cc \le n \le 10^5/cc \text{ and } B \sim 0.4 \text{ gauss.}$$

Since

$$m \sim 10^{-27} \text{ gm and } c = 3 \times 10^{10} \text{ cm/sec}, R_g/h \sim 1.5$$

demonstrating that the magnetic collisions within the sheath should be almost negligible. Under these circumstances,

magnetic collisions within the probe sheath are of little

consequence in modifying electrostatic probe characteristics

for ionospheric electron current collection. On the other hand,

the altered charged particle diffusion in the presence of the

geomagnetic field, as discussed previously, may be important in

any case.

An alternate mechanism for explaining the $M(\phi)$ curves is

anisotropy in the pitch angle distribution for the electrons of

thermal energies. The magnetic moment, μ, of a charged particle

in a magnetic field is $U_\perp/B$ where $U_\perp$ is the kinetic energy of the

particle in a direction $\perp B$. If μ is conserved, then $v^2\sin^2\alpha/B$

is constant, where α, the pitch angle, is the angle between the

particle velocity and the magnetic field lines. Lenchek has shown

that for charged particles escaping from a collision dominated region

into a collisionless ionosphere, when μ is conserved, there is a

critical pitch angle, α_c, which satisfies the relationship

$\sin^2\alpha_c = B/B_0$. B is the magnetic field strength at a given radial

distance, R, from a magnetic dipole and B_0 is the magnetic field

strength at the base of the collisionless region. The critial angle

divides the pitch angle distribution at a given height into two

regions. For $\alpha \leq \alpha_c$ there is no specific upper bound to the velocities

which the charged particles might have. For $\alpha > \alpha_c$ there is a maximum

permissible velocity, v_m, which charged particles can have where

$$v_m^2 = f(\sin^2\alpha, R/R_0, B/B_0).$$

The effect of taking into account coulomb collisions in the "collisionless"

region is to reduce the anisotropy by increasing the value of v_m.

The important part of the Lenchek model of topside ionospheric escape fluxes of charged particles for the present study is the prediction of a flat pitch angle distribution of particles for $\alpha \leq \alpha_c$. When $\alpha > \alpha_c$, a rapid fall-off in the pitch angle distribution is predicted. This is precisely the behavior of many of the $M(\phi)$ curves.

If one accepts the shape of the $M(\phi)$ curves as an adequate indication of the dominant mechanism in producing the shape, one can state that of the curves plotted, six out of eleven show an anisotropic pitch angle distribution of electrons to be the dominant mechanism in producing magnetic field modulations in the ionospheric electron current to cylindrical probes. The distinction in curve shapes is that for a variation of field angle from 90° towards either 0° or 180° there should be a continuous decrease in electron current if slow diffusion across magnetic field lines is the dominant mechanism. Only two out of eleven displayed this behavior. In contract, the anisotropic pitch angle mechanism requires a region of almost constant current, centered around 90° field angle. Then at some critical angle there should be a rapid fall-off in current. The extra modulations in the $M(\phi)$ curves at 1550 km altitude indicate some mechanism in addition to those operating at the other altitudes studied. In this case, there appears a particular pitch angle about which there is a depletion of electrons.

Because of the location of the probes near the bottom of the

satellite, there should be an assymmetry in the M(ϕ) for all field angles if the satellite presence is an important factor in the modulation of normal electron current collection. The general symmetrical nature of the M(ϕ) curves indicates that the satellite presence has little effect on the curve shape. In some cases there is an assymmetry in M(ϕ) for field angles near 90°, but these assymmetries can be interpreted in terms of a net flux of electrons in one direction. The satellite presence affects such a flux because the satellite will tend to scatter the particles out of the field tube for electron collection at one field angle but not at the supplement of that field angle. The result is an assymmetric M(ϕ) curve. The assymmetry disappears for field angles such that $\alpha > \alpha_c$ because of the restriction on the velocities permissible to the lowest velocities. The net flux would tend to involve particles in the higher velocities of a Maxwellian distribution where collisions would be less important. In this study, assymmetries in M(ϕ) are of the order of 5% when they occur.

The results presented are important in explaining the effects of satellite velocity and the geomagnetic field on cylindrical probe measurements in the ionosphere. The modulations observed due to satellite velocity effects represented changes in the accelerated electron current from doubling of the current, through no effect what-soever, to reducing the current by one-half. When the satellite velocity effects were removed, the magnetic effects, which were always present, remained. The stationary probes' accelerated electron currents

contained a 20 - 60% modulation from magnetic field effects where both diffusion effects and pitch angle distributions for the electrons are the important contributing factors. Since electrostatic probe measurements are one of the principal methods for deducing plasma charged particle densities, the results of this analysis should be useful in determining how to extract an unambiguous value of ionospheric electron density from electrostatic probe data. In addition, the results suggest a possible means of determining the presence of charged particle fluxes and anisotropies in pitch angle distribution among the ionospheric electrons. Both of these phenomena are important in the theory of transport processes in the ionized atmosphere.

APPENDIX

A SAMPLE CALCULATION FOR MODULATION SEPARATIONS

The first few steps in the separation procedure can be illustrated by numerical calculations on the data taken from Pass #268 at the 750 km level. The curves labeled #268A of Figures 6 and 7 are used. Since there is a data point at 87° aspect angle, rather than 90°, one can use 87° as the starting point with little error. From our definitions, $V(\theta)$ is taken as zero at 87° aspect angle. Therefore, the electron current to the probe is only influenced by the magnetic modulation appropriate to ϕ, where $I(87^O, \phi_1) = M(\phi_1)$. The ϕ_1 is 37° and the value of the data point is 0.405. On a magnetic modulation plot the value of $I(87^O, 37^O)$ is taken for both $M_1(37^O)$ and $M_1(143^O)$.

If only magnetic effects were important, $I(\theta, \phi)$ would show a value of 0.405 at $\phi = 143^O$. However, $I(\theta, 143^O) = 0.348$ which indicates that velocity effects have lowered the current by 0.057 units. θ_2 is found by looking at $I(\theta, \phi)$ plotted against aspect angle for $20^O < \theta < 37^O$ with $I(\theta, \phi) = 0.348$ units. θ_2 is 27° from Figure 6 and $V_o(\theta_2) = -0.057$ units. $V_o(27^O) = V_o(-27^O)$, hence, subtracting $V_o(-27^O)$ from $I(-27^O, \phi_3)$ gives the electron current without a velocity modulation. $I(-27^O, \phi_3) = 0.488$ units and the subtraction of $V_o(-27^O)$ gives 0.545 units which only contains a magnetic modulation.

ϕ_3 corresponding to $I(-27^O, \phi_3) = 0.545$ current units is obtained by looking at $I(\theta, \phi)$ plotted against field angle to find $95^O < \phi < 116^O$ where $I(\theta, \phi) = 0.488$ units. From Figure 7 this angle is 101°. 0.545 is the value of $M_1(101^O)$ and $M_1(79^O)$. $I(\theta, 79^O) = 0.480$ and a value of $V_o(\theta)$ for another aspect angle can be determined as before. This process is continued until an approximate $M_1(\theta)$ curve can be drawn.

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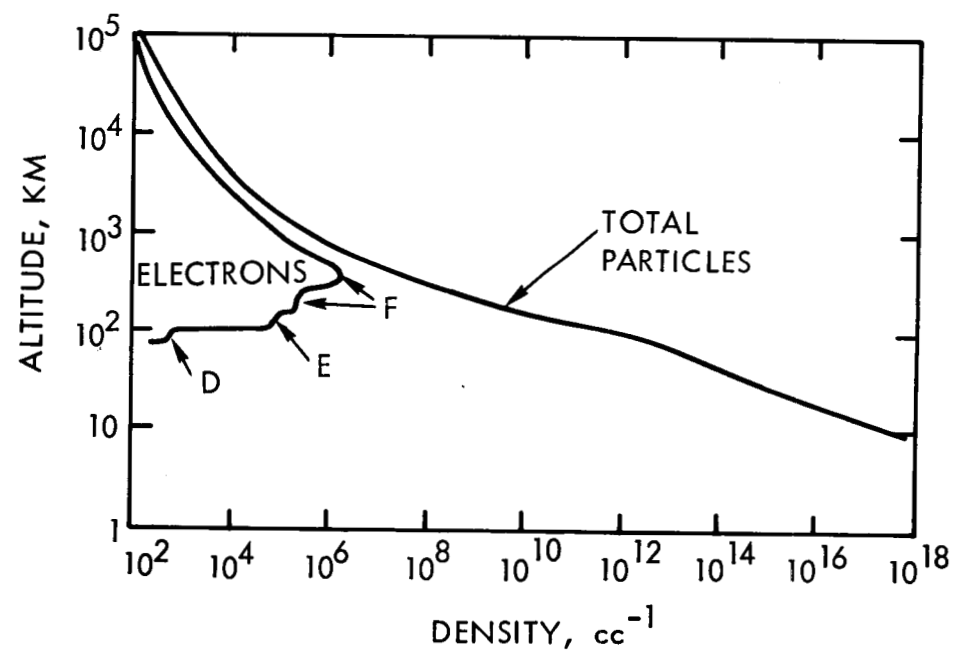
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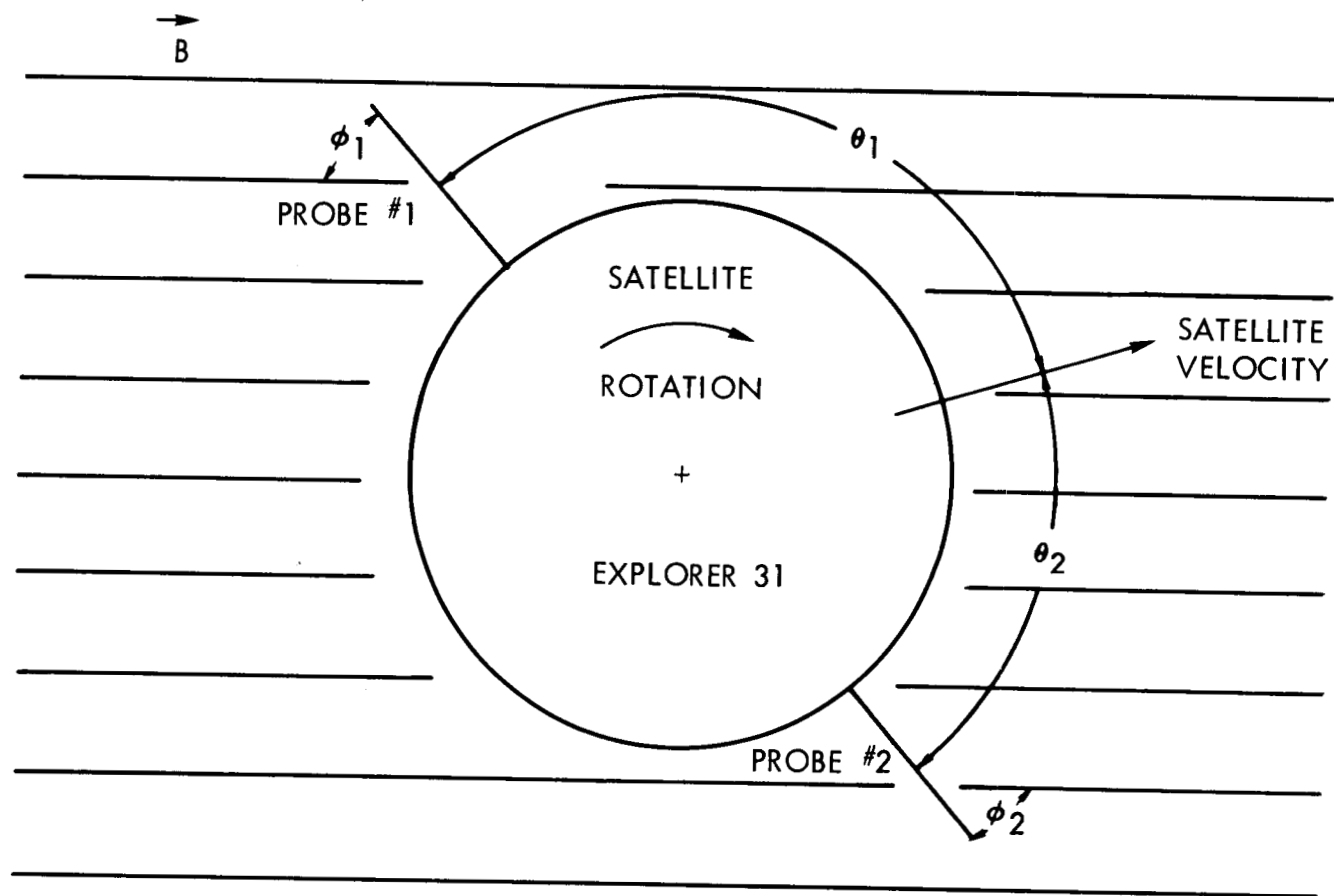
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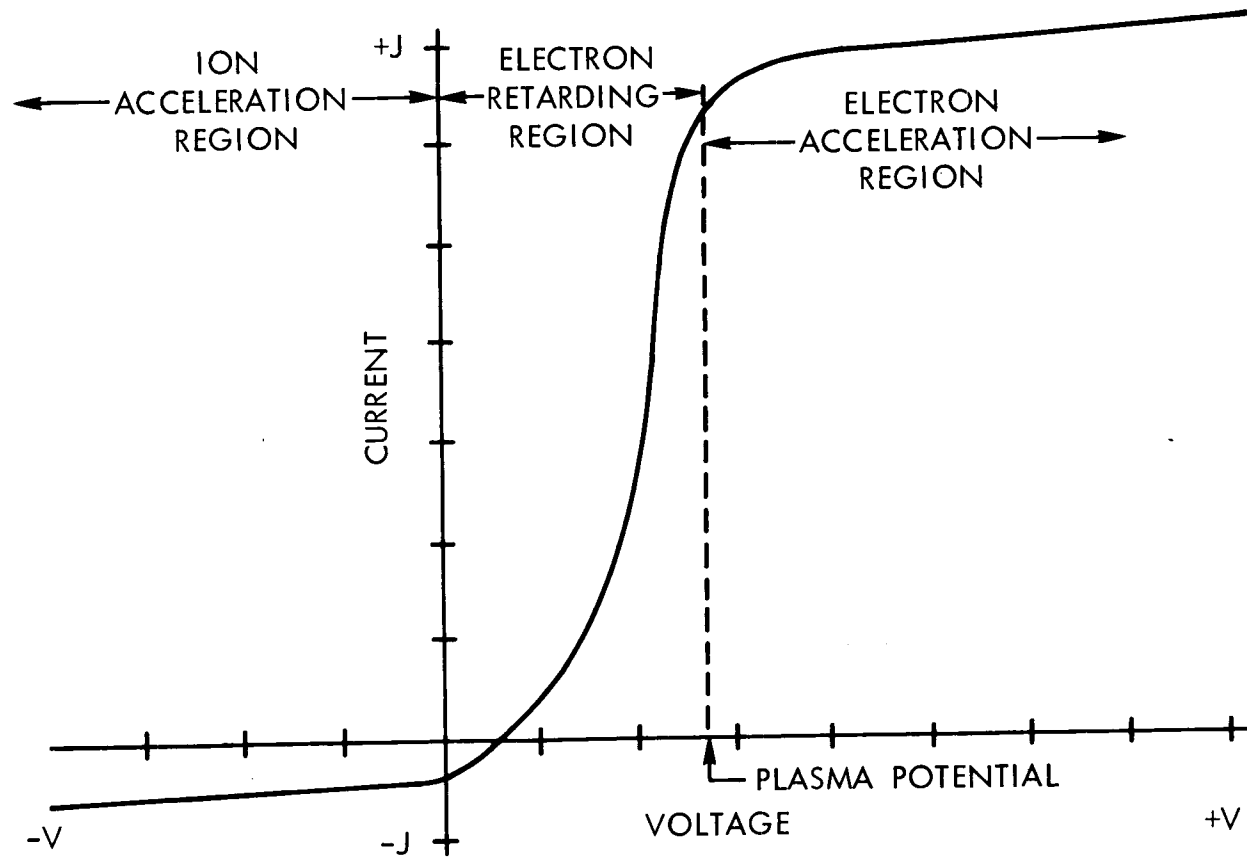
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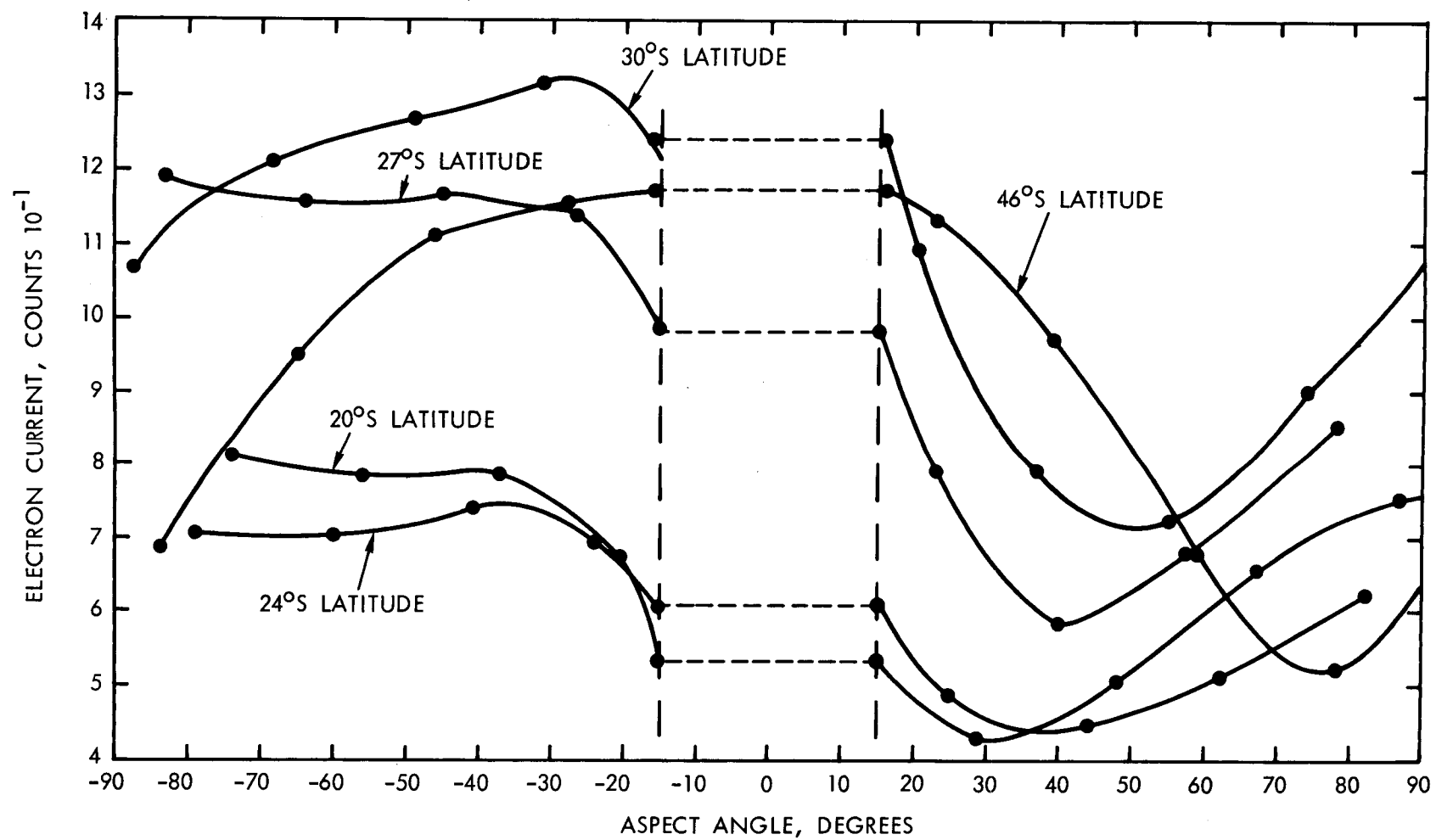
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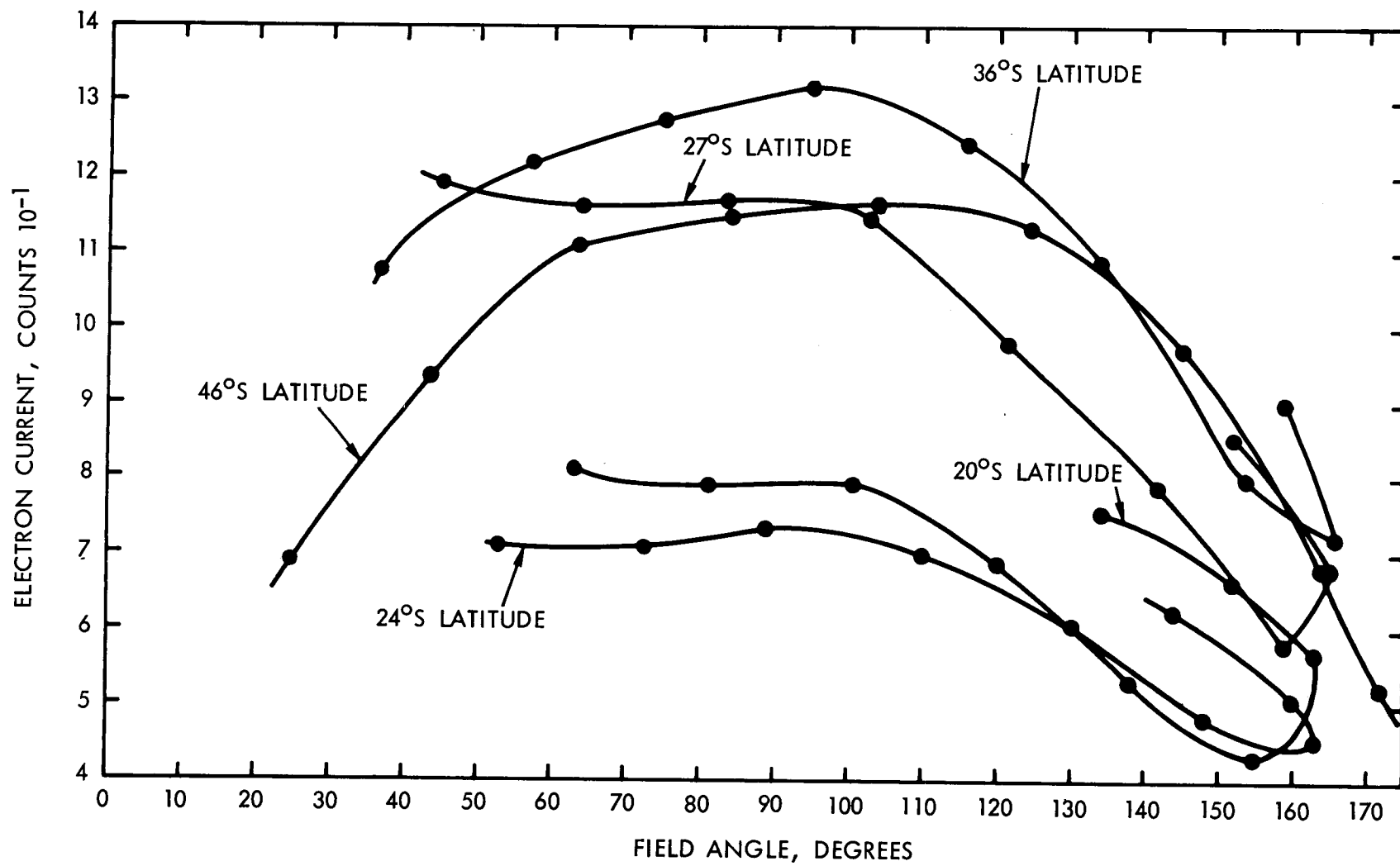
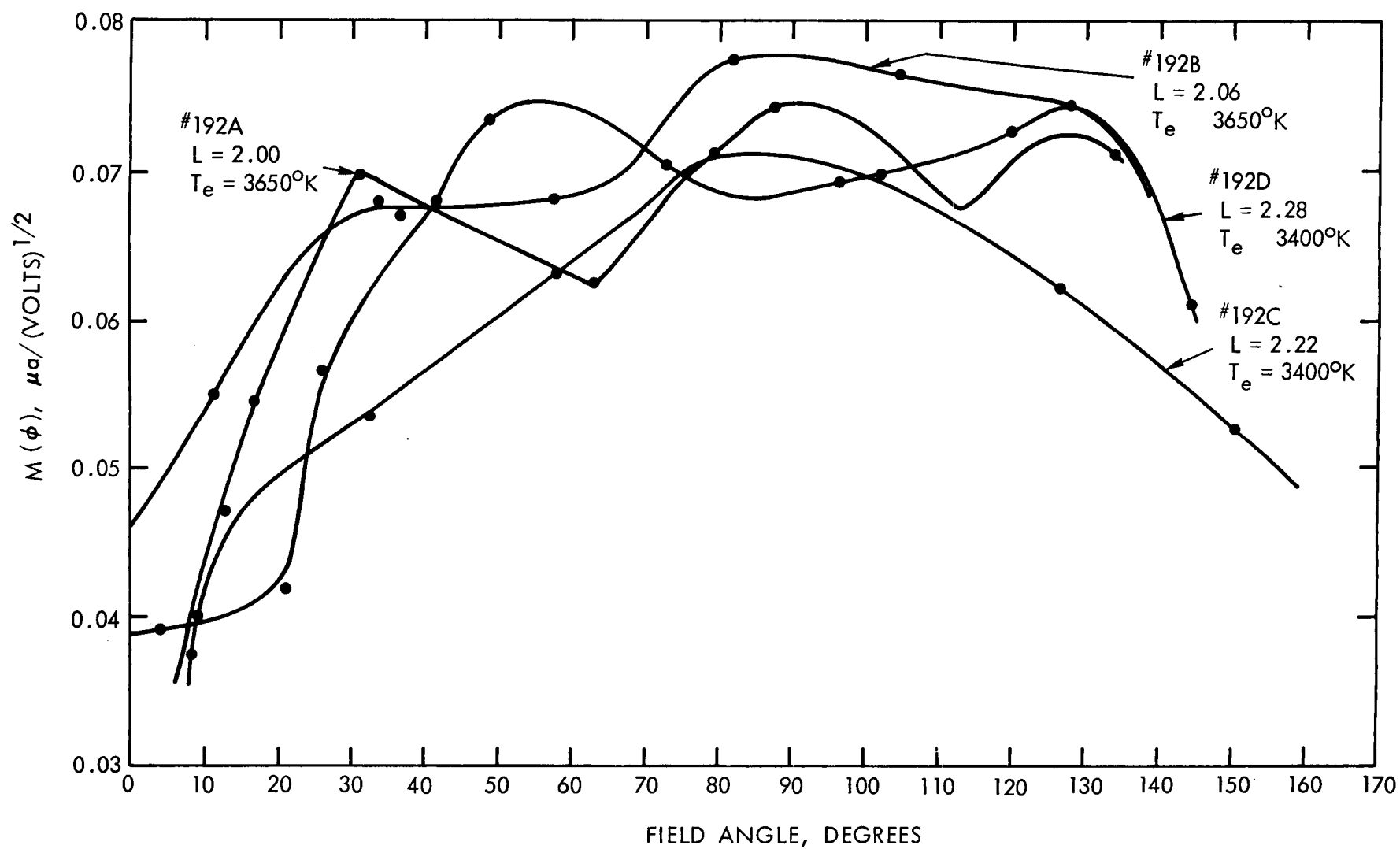Figure 5
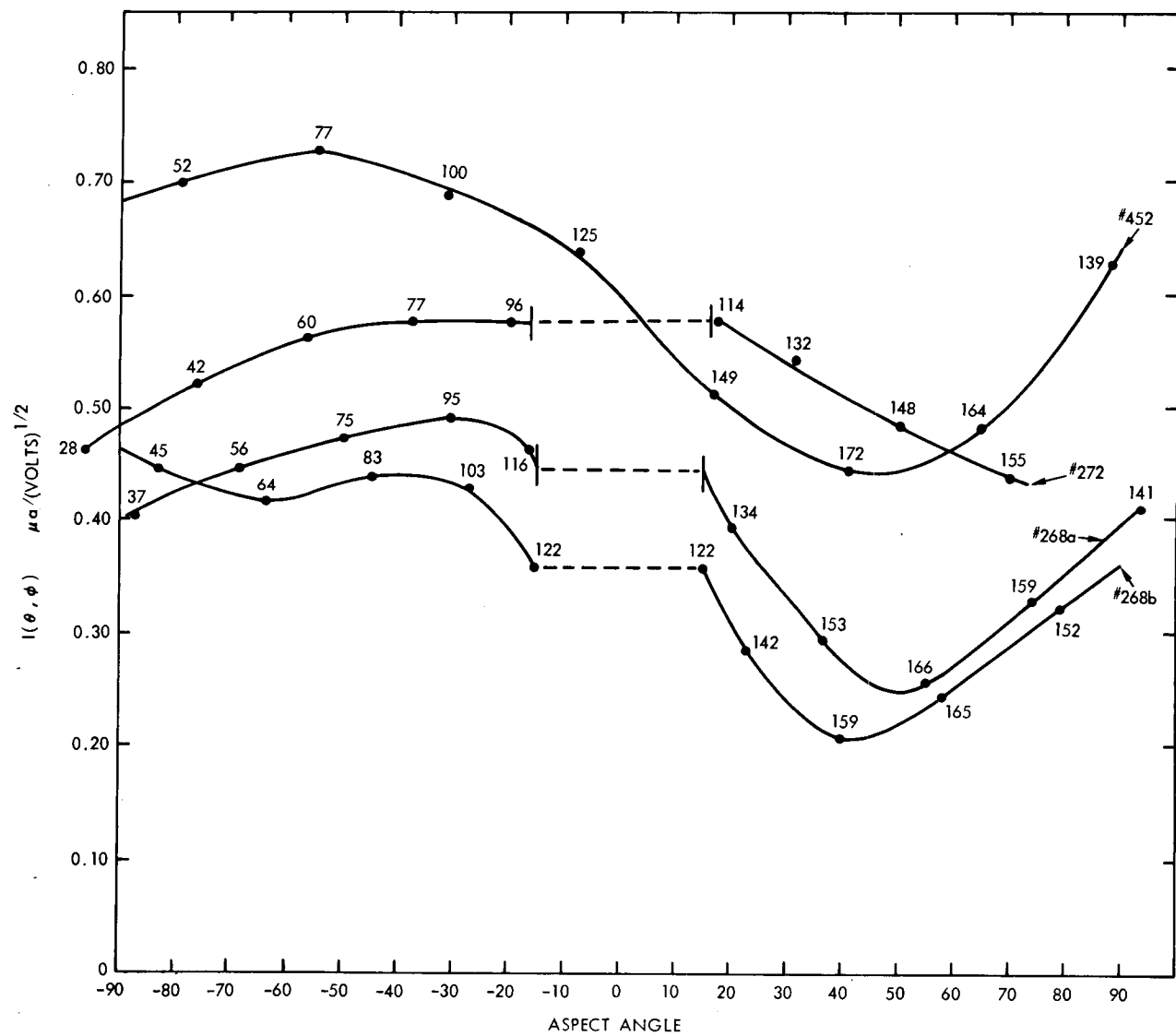
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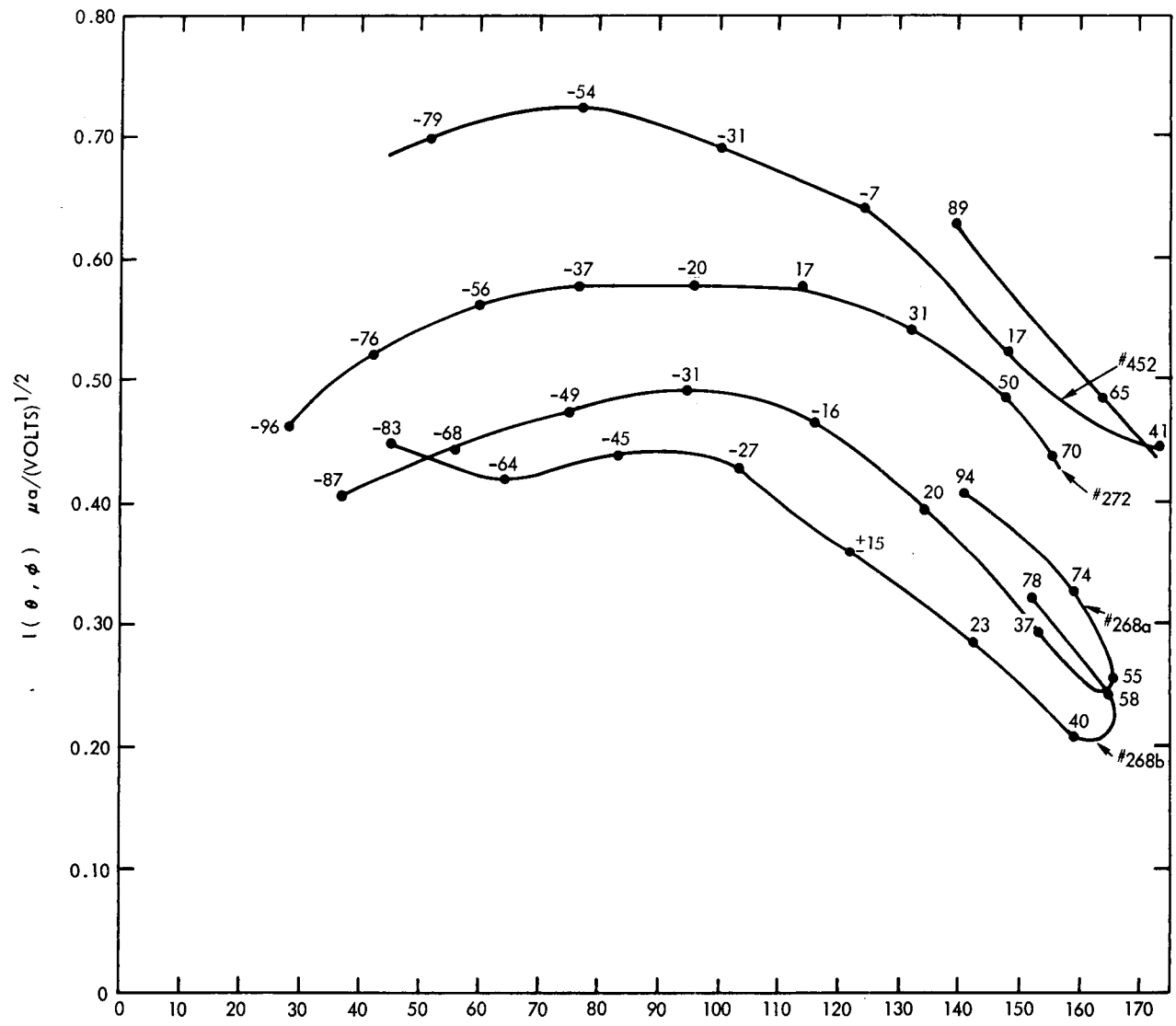
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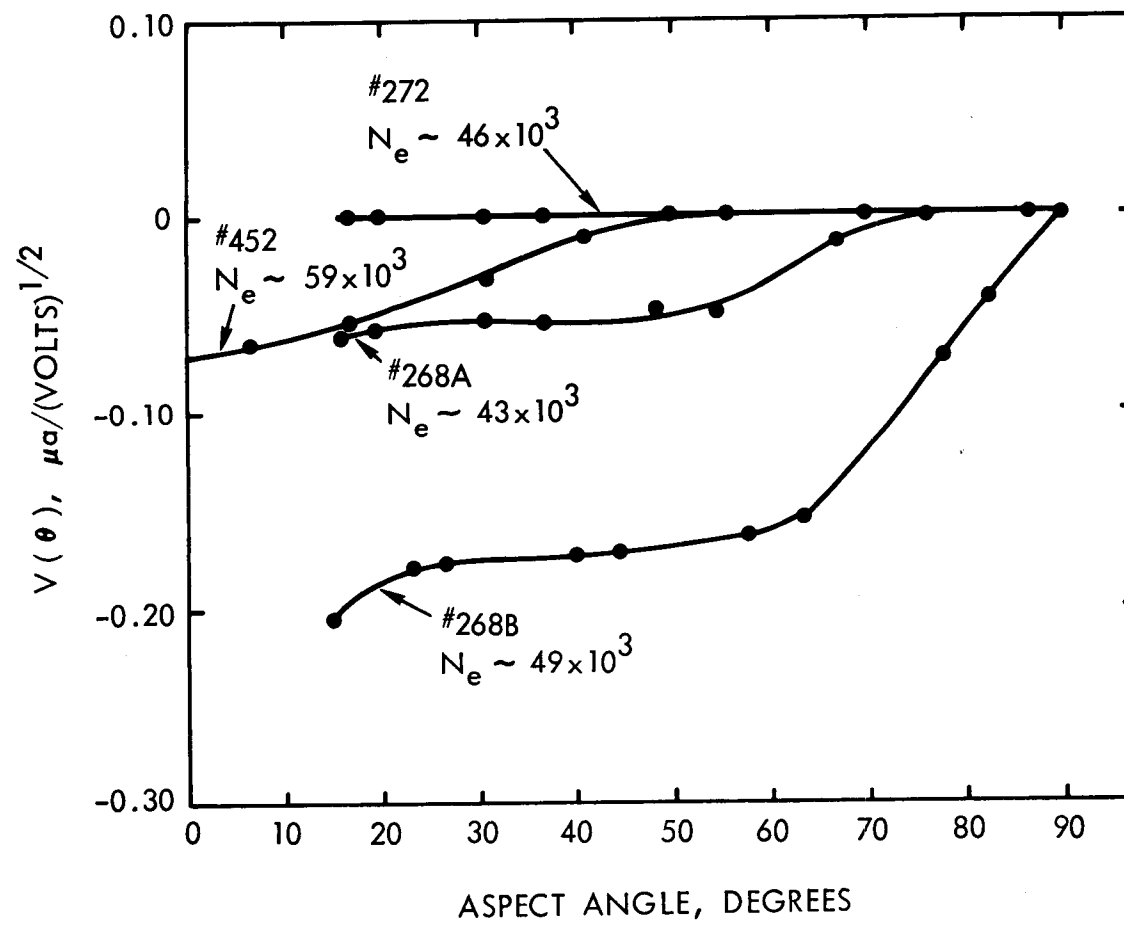
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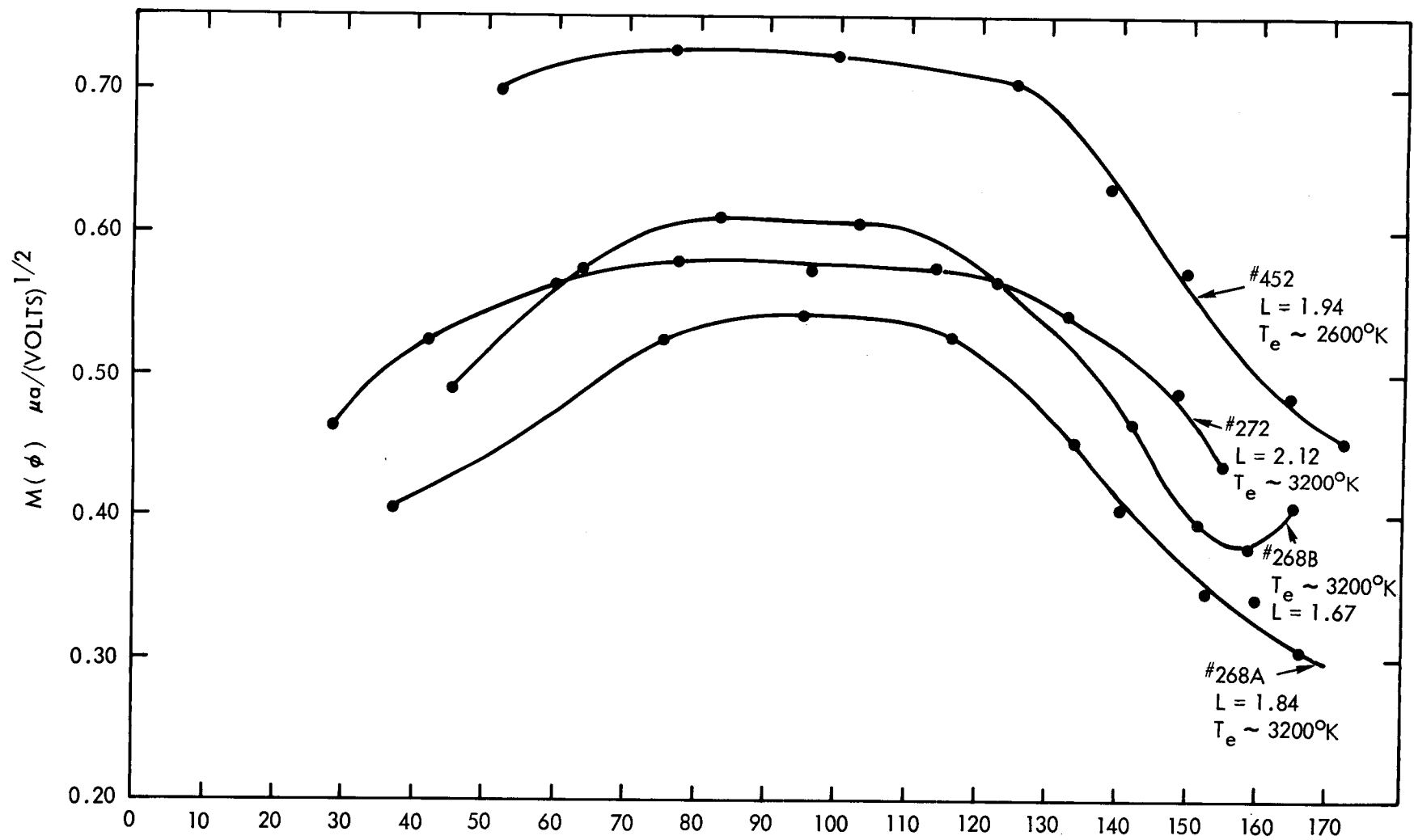
FIELD ANGLE, DEGREES

Figure 9
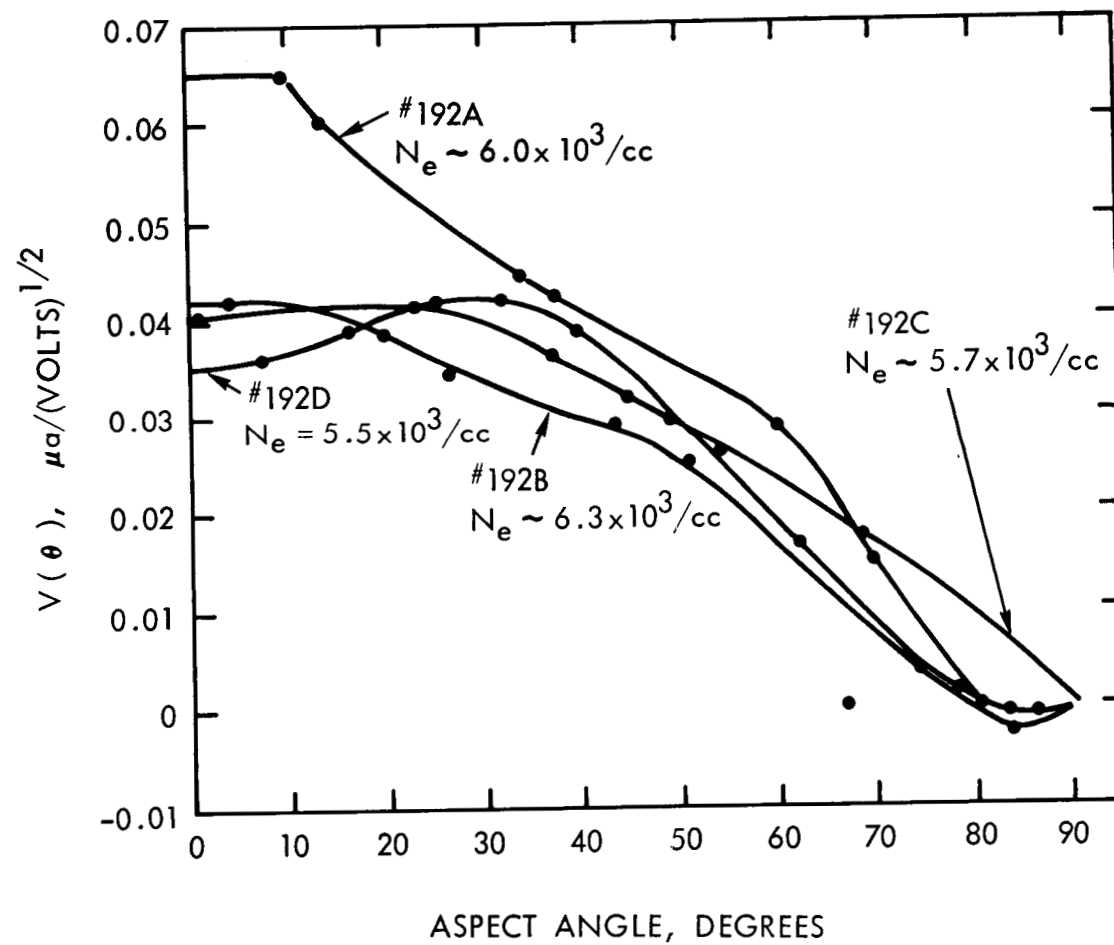
Figure 10

Figure 11

Figure 12
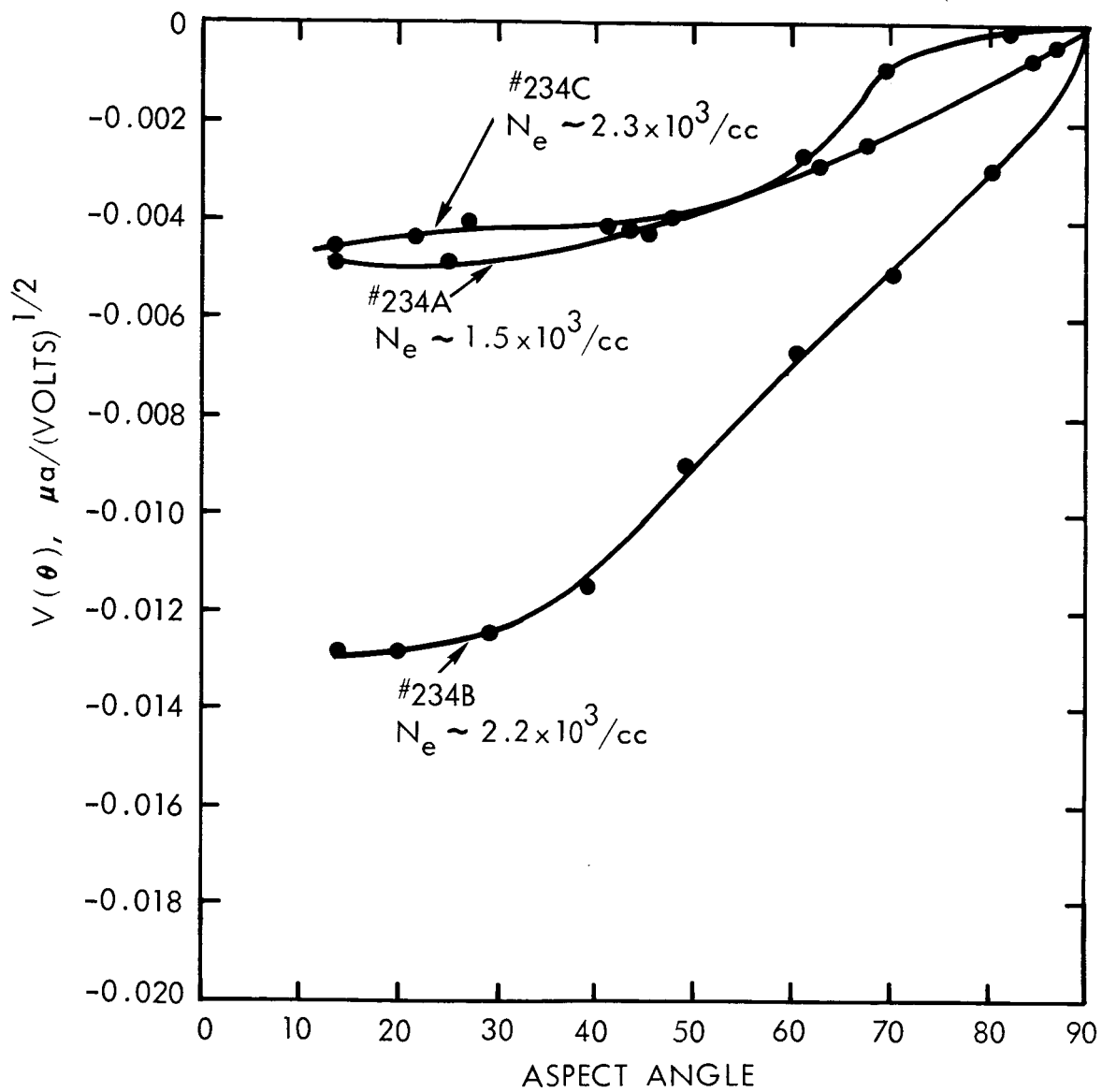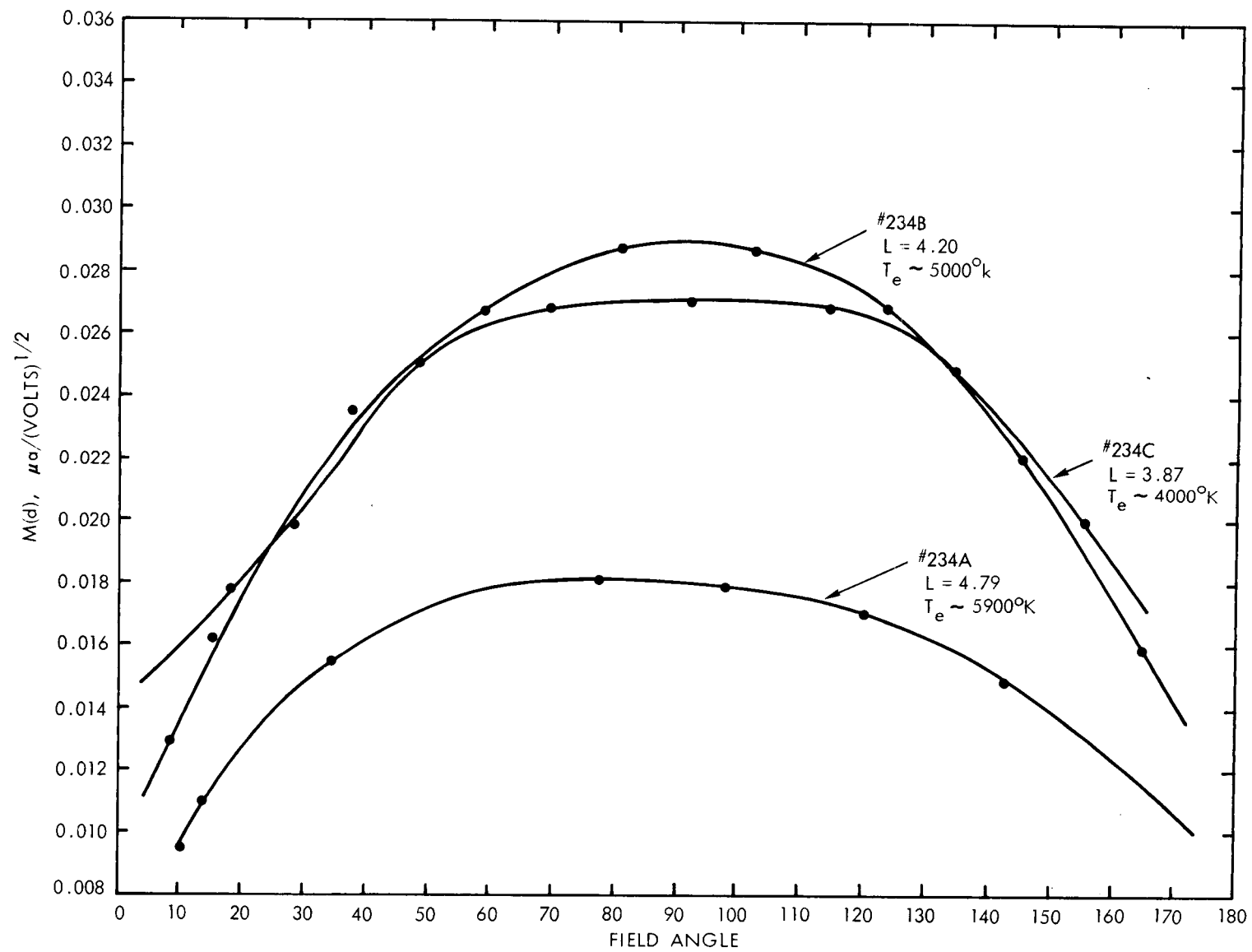
Figure 13

NORMAL SHEATH

SHEATH

PROBE

SHEATH WITH VELOCITY

SHEATH
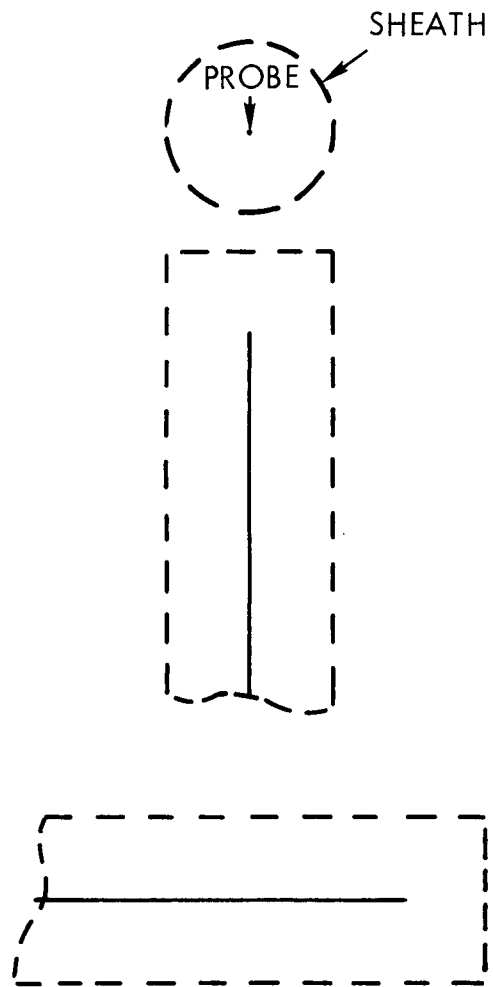
PROBE

PROBE
VELOCITY

PROBE VELOCITY

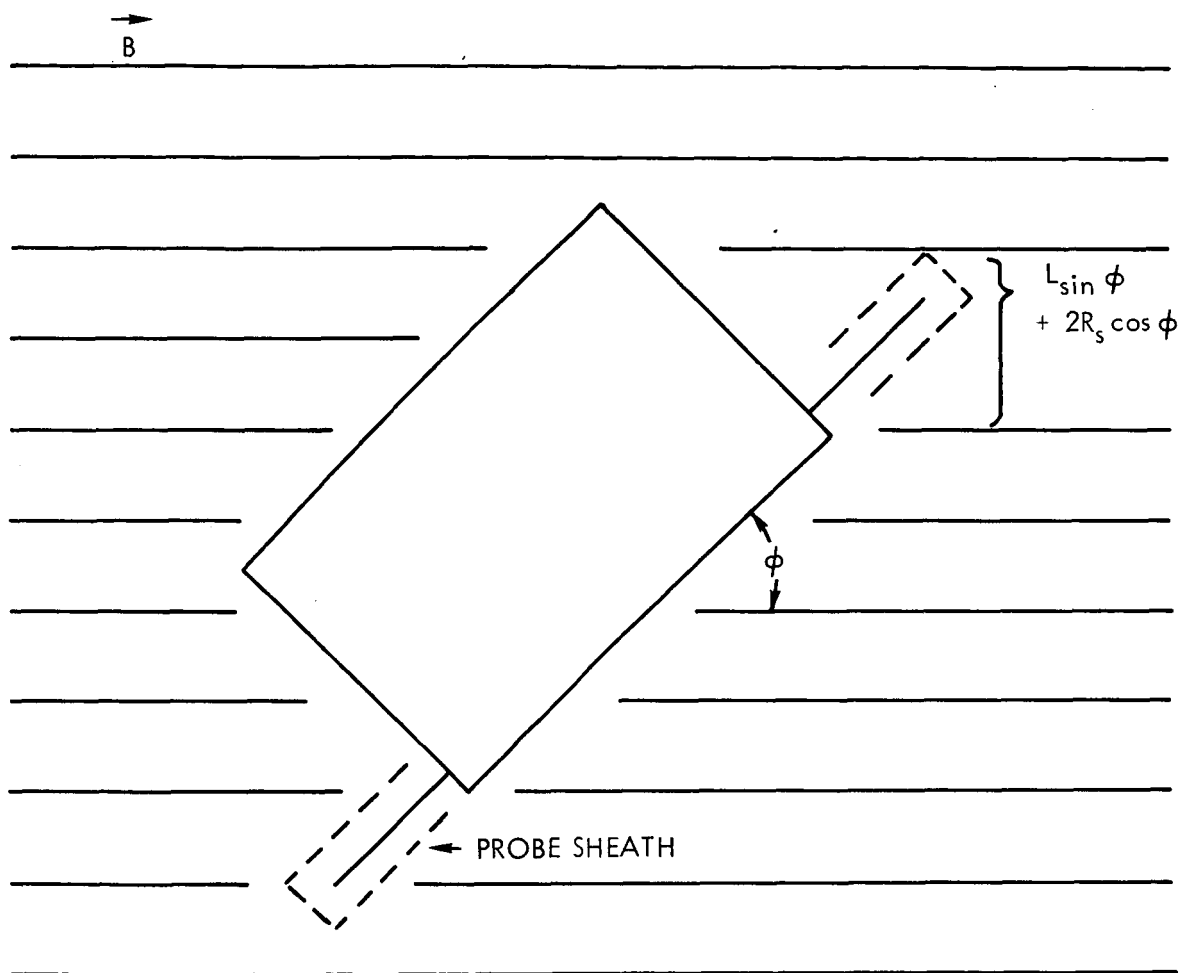Figure 14

B

$L_{\sin \phi}$
$+ 2R_s \cos \phi$

ϕ

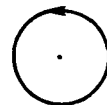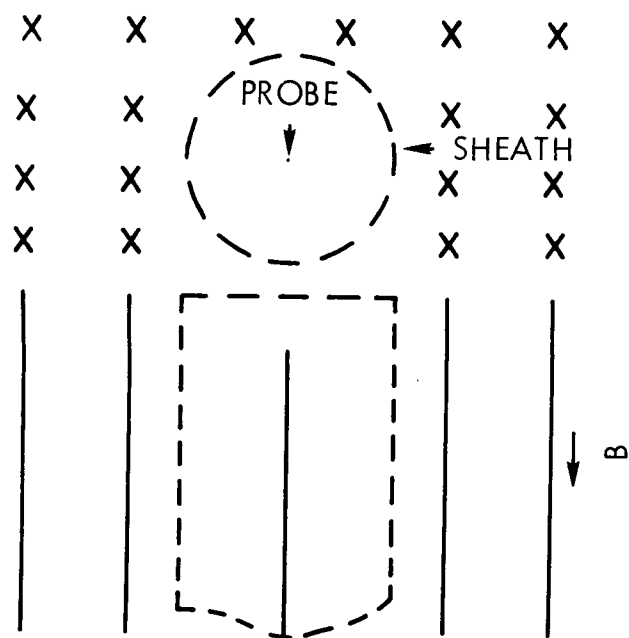← PROBE SHEATH
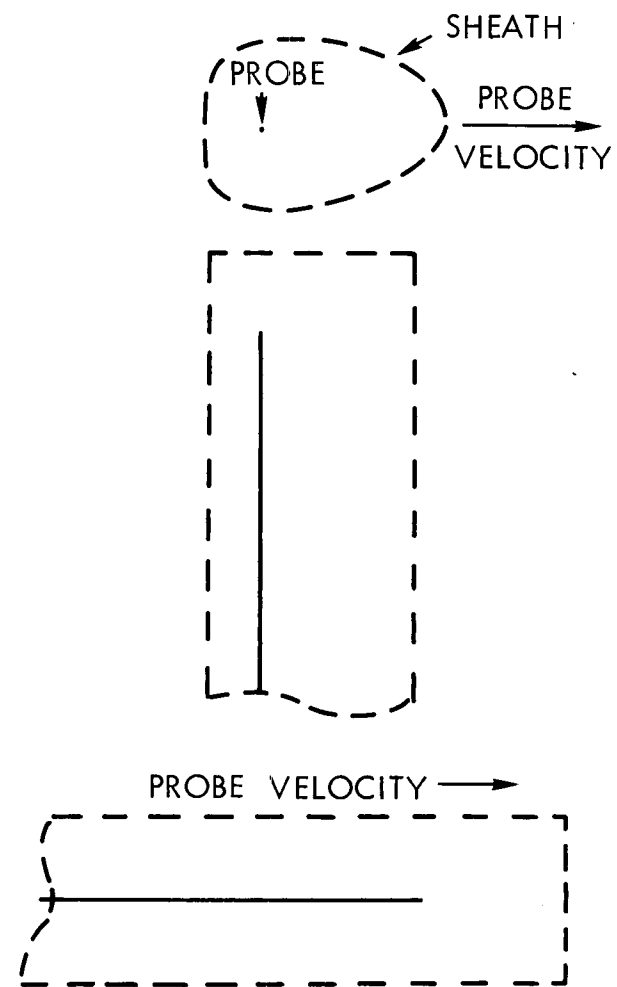
ELECTRON
ORBIT OF
RADIUS R_e

Figure 15

PROBE || MAGNETIC FIELD

PROBE ⊥ MAGNETIC FIELD

Figure 16