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**FINAL REPORT** 

**FOR** 

# **A DAY-NIGHT HIGH RESOLUTION INFRARED**

# **RADIOMETER EMPLOYING TWO-STAGE RADIANT COOLING**

**PART I1** 

## **BREADBOARD DAY-NIGHT RADIOMETER**

**Contract No. NAS 5-10113** 

**Prepared by** 

**ITT Industrial Laboratories** 

**Fort Wayne, Indiana 46803** 

1968

**For** 

**National Aeronautics and Space Adrnini** 

**Goddard Space Flight Center** 

**Greenbelt, Maryland 20771** 

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## **A** DAY-NIGHT HIGH RESOLUTION INFRARED

## RADIOMETER EMPLOYING TWO-STAGE RADIANT COOLING

## PART II

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## ABSTRACT

This part of the final project report covers Phase. **III**, the integration of the two-stage radiant cooler into a working breadboard model of^ a daynight radiometer. It describes the mechanical, optical, and electronic design of the radiometer. The characteristics of the infrared detector are given and the test instrumentation outlined. The radiometer operates in the 10.5 to 12.5 micron band and has a collecting aperture diameter of **4** inches. The mechanical drive and electronic bandwidth are designed for contiguous subpoint scanning at an altitude of 750 n mi and an instantaneous field-of-view of 2.5 mr on a side. The noise equivalent temperature is less than **170**  degrees **K,** and the noise equivalent temperature difference at 220 degrees K is less than 2 degrees K,

Part I of the final project report covers Phase **I,** preliminary design study, and Phase **11,**  two-stage radiant cooler.

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# **1.0** OVERALL CHARACTERISTICS

The breadboard radiometer is shown in Figure 1, and its characteristics are given in Table 1. The components added to the two-stage radiant cooler to form the radiometer are the scan head (Section 2.0), relay optics (Section **3.0),**  infrared detector (Section **4.0),** and radiometer electronics (Section 5.0). Electrical and thermal test instruments (Section  $6.0$ ) were used to measure the performance of **the** complete radiometer (Section **7.0).** 

#### Table 1

Overall Radiometer Characteristics



**Estimated** 

 $\mathbf{1}$ 



#### **2.0 SCANHEAD**

The scan head of the breadboard radiometer is shown in Figure **2.** It consists of a drive motor, gear box, casting,scanning mirror , primary telescope, and mechanical chopper, The drive motor is **a** Bodine model **246** lubricated with low vapor pressure silicone grease (General Electric Versilube **G-300).** The output **of** the gear box drives the scan mirror and chopper through flexible couplings; the gear train is shown in Figure 3, The casting (Figure **4)** is made of KIA magnesium alloy that has been stress relieved after machining and surface treated with Dow **23,** The scanning mirror and primary telescope are described in Section 3.0. The chopper disk is shown in Figure 5 and the chopper assembly in Figure **6.** 

For contiguous scan lines at the subpoint from an altitude of 750 n mi, the scan mirror must rotate at **100** rpm when the instantaneous field-of-view is **2.5**  milliradians (Section 7.0). The electronic post-demodulation bandwidth is then **2100** hz, The chopping frqquency must exceed twice this value; a rate of **6000** hz was selected. For a chopper with 180 teeth, the corresponding chopper wheel rotational rate is **2000** rpm.





**SANTA** 









![](_page_12_Figure_0.jpeg)

Figure 5 Chopper Disk

 $\overline{7}$ 

Figure 6 Chopper Disk Assembly

![](_page_13_Picture_14.jpeg)

![](_page_13_Figure_2.jpeg)

## **3.0** OPTICS

The optics consist of a scanning mirror, primary telescope, and relay lenses. Radiation from the source is reflected off the scanning mirror and focused on the chopper by the primary telescope; it is then transferred to the infrared detector by the relay lenses. The scanning mirror assembly is shown in Figure **7.**  The mirror is made of **304** stainless steel and polished to a flatness of **1.5** wavelengths of visible light. The primary telescope assembly is shown in Figure 8; it consists of a **4** inch, **f/l** paraboloid and a **2.4** inch diameter folding flat. The telescope has a blur circle (90 percent of energy)  $1.2 \times 10^{-3}$  inch in diameter at the primary (chopper) focus,

The design data for the relay optics are given in Table **2,** and the mechanical assembly is shown in Figures **9** and **10.** The clear apertures listed in the table are those of the axial beam. The first two germanium elements (doublet) in the relay optics (very nearly) collimate the f/l beam from the **0.25** mm square primary image at the chopper plane. The last two germanium elements, the  $f/8$  focusing and aplanatic lenses refocus the radiation on the 0.5 mm square infrared detector at the secondary focus. The  $f/1$  doublet has a blur circle of 1.5 x  $10^{-3}$  inch in diameter measured at the primary focus. The  $f/8$  lens has a blur circle of  $1 \times 10^{-3}$ inch and the aplanatic lens a blur circle of  $2.5 \times 10^{-3}$  inch, both measured at the secondary (detector) focus.

The relay optics magnify the **4** inch focal length of the primary telescope by **2X.** When combined with the infrared detectw of sensitive area **0.553** mm **x 0.449 mm, the nominal instantaneous field-of-view is then 2.6 mr x 2.2 mr.** 

The spectral response is determined by a **10,5** to 12.5 micron interference filter, whose transmission is shown in Figure **11.** The peak transmission is **<sup>90</sup>** percent at **10.8** microns; the transmislsion is 50 percent of the peak at **10.44** microns and **12,53** microns. Average transmission between the **50** percent of peak wavelengths is 80 percent. Transmission is less than **0.1** percent at **9,86** microns and below and from **13.07** microns to **18.25** microns.

# **Table 2**

# **Relay Optics Design**

![](_page_15_Picture_105.jpeg)

![](_page_16_Figure_0.jpeg)

![](_page_16_Figure_1.jpeg)

D-ASSEMBLY TO BE DIMAMCALLY<br>BALANCED TO WITHIN 50 MICRO-<br>INCHES.<br>D-BEFODE INSTALLING SCREWS.

![](_page_16_Picture_31.jpeg)

Figure 7 Scanning Mirror Assembly

![](_page_17_Figure_0.jpeg)

![](_page_17_Figure_1.jpeg)

Figure 8 Primary Telescope Assembly

![](_page_17_Figure_3.jpeg)

![](_page_18_Figure_0.jpeg)

![](_page_19_Figure_0.jpeg)

Figure 10 Optics Mounted in First-Stage Patch

![](_page_20_Figure_0.jpeg)

**Figure 11 Spectral Transmittance of Interference Filter** 

## **4.0** INFRARED DETECTOR

The infrared detector for the day-night radiometer may be a  $Cd_x Hg_{1-x}$  Te photovoltaic detector (C. Verie and J. Ayas, Appl. Phys. Lett. 10, 241, 1 May **1967)** or a **DLK21** photoconductive detector (Honeywell Radiation Center, Boston, Mass. ). Both detectors operate **at** or near liquid nitrogen temperature (77 degrees K). The usual characteristics **of** a photovoltaic detector with a maximum response between **10.5** and **12.5** microns and an area less than **1** square millimeter are given in Table 3 (private communication from C, Veri<sup>6</sup>). The best detectors have a D<sup>\*</sup> close to 1 x 10<sup>10</sup> cm hz<sup>1/2</sup> /watt, a value that is presently not reproducible. /watt, a value that is presently not reproducible.

#### Table **3**

# Typical Characteristics **of** Photovoltaic Detector

![](_page_21_Picture_196.jpeg)

The typical characteristics **of** a DLK **21** photoconductive detector are given in Table **4** together with those **of** the deteetor used in the day-night radiometer, The spectral response of the radiometer detector is shown in Figure **12.** 

#### Table **4**

#### Characteristics **of** Photoconductive Detector

![](_page_21_Picture_197.jpeg)

![](_page_22_Figure_0.jpeg)

Experimental Cd<sub>x</sub> Hg<sub>1-x</sub> Te detectors have been made by Santa Barbara Research Center, Goleta, California. These detectors have **a** resistance of 30 to 300 ohms per square, a response time of 1 to 100 nsec, and a spectral peak **of 9** to 13 microns.

There is no joule heating in the photovoltaic detector to increase the thermal load on the second-stage patch. Moreover, the joule heating of the photooonductive detector at optimum bias produces a temperature rise of only 0.7 degree K in a patch at **77** degrees K (Part I, Section 2.1.6.3).

The second-stage patch was initially designed to hold a detector package similar to that presently used for the PbSe element in Nimbus High Resolution Infrared Radiometer (Contract NAS5-668). This requires the use **of** an overcoat or encapsulating material to protect the sensing element from atmospheric effects. **At** present, however, no such coating is known for the DLK **21,** although an investigation is underway at Honeywell Radiation Center. The sensing element is therefore enclosed in a space filled with dry inert gas and radiation admitted through a clear Irtran **I1** (Eastman Kodak) window. This change, plus the desire of Honeywell to use an assembly similar to ones already in use, resulted in a detector package which extends beyond the height **(0.32** inch) of the rest of the second-stage patch.

The detector package is shown in Figure 13, The housing is made of Kovar to mtch the thermal expansion of the glass beads used to hermetically seal the electrical feed-throughs. This entire assembly containing a detector element was originally mounted in a dewar for laboratory teating.

![](_page_24_Figure_0.jpeg)

Figure 13 Detector Assembly

## **5.0 ELECTRONICS**

Figure **14** is a block diagram of the radiometer electronics. The infrared cell at the secondary image plane detects the signal modulated by a mechanical chopper at the primary image plane, The detector signal is amplified by the preamplifier and video amplifier. It is then synchronously demodulated by the reference signal, filtered, and combined with the correction voltage. The input to the reference signal generator is a ahopper modulated light beam, which is detected by the photodiode. The correction voltage is generated during the time the radiometer is viewing cold space. This interval is indicated by the space scan gate generator, which is operated by the magnetic pickup in the gear train to the scan mirror.

The signal from the infrared detector is fed to a transistor preamplifier manufaatwed by Perry Associates, Brookline, Mass. The specifications for the preamplifier are given in Table **5** and the broadband noise performance in Figure **15.** The device is specifically designed to match the low impedance of the infrared detector **(50** to 200 ohms) while preserving low noise performance without the aid of an input transformer or other inductive oowponent,

#### Table 5

# Preamplifier Specifications (Perry Model **600)**

![](_page_25_Picture_95.jpeg)

![](_page_26_Figure_0.jpeg)

Figure 14 Electronics Block Diagram

 $\overline{21}$ 

![](_page_27_Figure_0.jpeg)

Figure 15 Preamplifier Broadband Noise Performance

 $\mathbf{22}$ 

Schematics of the five remaining blocks are given in Figures **16** through **20.**  Most circuits utilize a microcircuit monolithic amplifier, the  $\mu$ A709. This circuit component can be used for a-c or d-c amplification, as a comparator, and as a multivibrator.

The video amplifier (Figure 16) serves as an amplifier and as a driver for the demodulator. The maximum amplifier gain is about 60 db with a variation of 6 db. The low frequency cutoff is about **700** hz, **and** the high frequency cutoff is **47** khz at maximum **gain** and **70** khz at minimum gain.

The demodulator (Figure **17)** synchronously rectifies the video amplifier output. The switching vdtage from the re€erence signal generator (Figure **18)** is fed in at LB039. The rectified output is applied at the common source connection of the CM602's.

The low-pass filter response in combination with the demodulator is shown in Figure **21.** The filter causes a delay that is constant **(184** microseconds) for all frequencies over the passband.

The output amplifier provides amplification of the demodulated and filtered signal from d-c to beyond the passband. It also serves as a mixing point for the video and chopper correction inputs.

The reference signal generator (Figure **18)** processes the **6** khz signal from the chopper photodiode to a 6 khz square wave for demodulation of the video signal. The first amplifier is an a-c amplifier with a voltage gain variation of **5.6** db. The second is a saturating amplifier which squares up the video signal until now , a sinusoidal signal, The output is a *6* **khz** square wave approximately **22** volts peak to peak.

**<sup>I</sup>**The correction voltage generators (Figure **19)** provides output correction for the difference in signal between the chopper and space. The gate formed by the upper CM602 and associated components passes the video output to the comparator (first  $\mu$ A709) during the time the mirror is scanning space (about onetenth of a scan period). During the remainder of the scan, the lower CM602 gates the comparator input to ground.

If the output video  $(E_0)$  is positive with respect to the reference, the comparator has a negative going output and the opposite is true for a negative going video. If the comparator input is equal to the reference level, the comparator output is zero. This pulsed output with a one-tenth duty cycle is integrated by the components connecting the pair of  $\mu$ A709's. The integrated d-c level is amplified by the non-inverting amplifier formed by the second **pA709,** which provides the correcting input,  $E_c$ , to the output amplifier.

![](_page_29_Figure_0.jpeg)

Figure 16 Video Amplifier

 $\overline{24}$ 

![](_page_30_Figure_0.jpeg)

Figure 17 Demodulator, Low-Pass Filter, and Output Amplifier (Board No. 1)

25

 $\bullet$ 

![](_page_31_Figure_0.jpeg)

 $\overline{26}$ 

![](_page_32_Figure_0.jpeg)

Figure 19 Correction Voltage Generator (Board No. 3)

![](_page_33_Figure_0.jpeg)

 $\chi^2$ 

![](_page_34_Figure_0.jpeg)

![](_page_34_Figure_1.jpeg)

The correction voltage generator **has** a gain characteristic such that

$$
E_{\rm O} = mE_{\rm C} + V_{\rm th}
$$

where  $E_0$  is the input voltage level. If the reference level is perfectly adjusted, **Vth** is zero. **In** measurements taken in the laboratory, m had a value of 1/26.8 and  $V_{th}$  a value of  $+0.025$  volt.

Referring again to Figures 17 and 19, it can be seen that the significant part of the above loop with respect to the chopper error is **the** output amplifier and the correction voltage generator. The following definitions are made:

- $E_f$  = the demodulated and filtered video signal input to the output amplifier
- $E<sub>e</sub>$  = the chopper correction d-c input to the output amplifier
- $E_{\Omega}$  = the video output and the input to the correction voltage generator
- $E<sub>ch</sub>$  = that portion of the demodulated video signal caused by the chopper
- $E_{tar}$  = that portion of the demodulated video signal caused by the target

We then have  $E_f = E_{ch} - E_{tar}$ ,  $E_0 = K_1 E_F + K_2 E_c$ , and  $E_c = K_3 (E_0 + vth)$ . Then  $E_0 = K_1 (E_{ch} - E_{tar}) + K_2 E_c$ . If  $E_{tar} = 0$ , (which is the case when looking at space), then  $E_0$  ( $E_{tar}$  = 0) =  $K_1$   $E_{ch}$  +  $K_2$   $E_c$ . Therefore  $E_c$  =  $K_3$  ( $K_1$   $E_{ch}$  +  $K_2$ <sup>\*</sup>  $E_c$  + vth) or  $E_c = K_1 K_3 E_{ch}/(1 - K_2 K_3) + K_3$  vth/(1 - K<sub>2</sub> K<sub>3</sub>). This is the correction signal caused by a look at space. Working this back into the original equation  $E_0 = K_1$   $E_{ch}$  -K<sub>1</sub>  $E_{tar}$  + K<sub>2</sub>  $E_c$ , we have

$$
E_{O} = K_{1} E_{ch} - K_{1} E_{tar} + \frac{K_{1} K_{2} K_{3} E_{ch}}{(1 - K_{2} K_{3})} + \frac{K_{2} K_{3} v_{th}}{(1 - K_{2} K_{3})}
$$
  
\n
$$
E_{O} = \frac{K_{1} E_{ch}}{(1 - K_{2} K_{3})} - K_{1} E_{tar} + \frac{K_{2} K_{3} v_{th}}{1 - K_{2} K_{3}}
$$

From laboratory measurements,  $K_1 = -12.8$ ,  $K_2 = 13.7$ ,  $K_3 = 26.8$ ,  $v_{\rm th} = +0.025$ ; so that

$$
E_O \quad \cong \quad 0.035 E_{Ch} + 12.8 E_{tar} + v_{th}
$$

For a maximum output of 6 volts,  $E_{tar} = 0.47$  volt for a 330 degree K target. **Considering the chopper to have a maximum effective temperature of 300**  degrees K, the chopper signal input to the output amplifier is 0.329 volt. With  $E_{\text{tar}} = 0$ ,  $E_0 = 0.0115 + 0.025$  and the maximum error at the output due to the **chopper correction is 11.5 millivolts.** 

#### 6.0 TEST EQUIPMENT

The test equipment for this program is patterned after the Nimbus bench checkout unit (Contract **NAS5-668)** with special emphasis on low temperature measurement and recording: Full advantage of existing designs and techniques has been taken.

The test equipment has been divided into two categories, that for the second phase (cooler testing) and that for the third phase (radiometer testing). Figure 22 is a block diagram of the test equipment required for both phases of the program. The test equipment for the radiant cooler is described in Section 3.0, Part I,

A photograph of the electronic test equipment is shown in Figure **23.** The cabinets contain the instruments listed in Table 6.

#### Table 6

#### Electronic Test Equipment

![](_page_37_Picture_169.jpeg)

\* Remainder is in spaoe chamber

An extended aluminum shroud was constructed to provide a cold space look for the breadboard radiometer. The portion facing the scanner (rather than the copper structure) was painted with  $3M$  Black Velvet. The outer surface of the aluminum is covered with aluminized mylar to offset the thermal loading or the black area and thus maintain the aluminum at a temperature of 100 to 150 degrees K. Figure 24 shows the shroud and the calibration blackbody target mounted in the space chamber.

![](_page_38_Figure_0.jpeg)

Equipment Required For  $\beta$  3

Test Equipment Block Diagram Figure 22

![](_page_39_Picture_0.jpeg)

# Figure 23 Electronic Test Equipment

 $\sim$ 

![](_page_40_Picture_0.jpeg)

Figure 24 Space Scan and Calibration Targets in Space Chamber

#### 7.0 RADIOMETER PERFORMANCE

Certain parameters affecting system sensitivity are imposed by the satel: lite orbital characteristics and the mapping geometry. The mapping of contiguous scan lines on the earth's surface or overlying cloud layers is accomplished by continuous rotation of a single-faced scan mirror which makes an angle **of** 45 degrees to **the** telescope optical axis. The day-night radiometer operates in much the same fashion as the earlier Nimbus HRIR except that the instantaneous field **of**  view is smaller. The parameters imposed by the satellite characteristics and mapping geometry which affect system sensitivity will be calculated first.

The satellite orbital velocity, v, is given by

$$
v = R \sqrt{\frac{g}{R+h}}
$$

where  $g = acceleration of gravity at the earth's surface$ 

 $R =$  radius of the earth  $= 3,440$  nautical miles

<sup>h</sup>- satellite altitude = **750** nautioal miles

For 
$$
g = 980 \text{ cm/sec}^2 = 5.26 \times 10^{-3} \text{ nautical miles/sec}^2
$$
  

$$
v = 3.85 \frac{\text{ nautical miles}}{\text{ miles}} = 7.18 \text{ km/sec}
$$

sec

In order to obtain contiguous scan lines the period of rotation of the scan mirror, T, must be

$$
T = \frac{h \phi}{v} (1 + \frac{h}{R})
$$

where  $\phi$  = width of instantaneous field-of-view.

Using the above values for the various parameters and  $\phi = 2.5$  milliradians.

 $T = 0.60$  second

The electronic post-demodulation bandwidth,  $\Delta f$ , necessary to record the video signal at this resolution is

$$
\Delta f = \frac{\pi}{T \phi} = 2100 \text{ hz}
$$

The sensitivity of the radiometer is given by the d-c output signal to rms noise ratio which can be written in the following form (modified from Quarterly Report XIII on Contract NAS5-668, Section 3.5).

$$
\frac{S_{dc}}{N_{\text{rms}}} = \frac{4 J_1 (T) P_1 (\Delta \lambda, T) D^* (\Delta \lambda, f_0, 1) T_0 D_e^2 \phi^2}{4 \sqrt{\Delta f_s A_c}}
$$

where  $\frac{4}{2}$  = signal attenuation due to chopping, synchronous demodulation, and electronic filtering (triangular waveform at detector) =

**2 J1 (T)=** total source emittance (watts/cm ) at temperature **T** 

$$
P_1 (\Delta \lambda T) = \text{fraction of blackbody radiation of temperature } T \text{ in}
$$
\nwavelength band  $\Delta \lambda$ , where  $\Delta \lambda$  is the 10.5 to 12.5  
\nmicron band

$$
D^*(\Delta \lambda, f_c, 1) = \text{detector detector}
$$
\n
$$
= \text{chopping frequency } f_c \text{ and electronic bandwidth}
$$
\n
$$
= \text{of } 1 \text{ cps}
$$

$$
T_0 = \text{optical transmission (including mirror reflection losses)}
$$

$$
D_{\alpha} = \text{effective optical diameter of collecting telescope}
$$

$$
\Delta f_{\rm S} = \qquad \text{electronic noise bandwidth} = 2 \Delta f
$$

 $A_{\alpha}$  = detector cell area.

The effective telescope optical diameter is defined **as** 

$$
D_e = \sqrt{D_p^2 - D_s^2}
$$

where  $D_p$  = diameter of telescope primary mirror

 $D_S$  = diameter of telescope secondary mirror

In the breadboard day-night radiometer,

$$
T_0
$$
 = 0.4  
\n $D_e$  = 3.2 inches  
\n $\Delta f_s$  = 4.2 x 10<sup>3</sup> hz  
\n $A_c$ <sup>1/2</sup>= 5 x 10<sup>-2</sup> cm

And the signal-to-noise equation becomes

$$
\frac{S_{dc}}{N_{rms}} = 5.166 \times 10^{-6} J_1 P_1 D^*
$$

The values of P<sub>1</sub>  $(\Delta \lambda, T)$  were determined from the Lowan and Blanch tables (JOSA 40, 70, 1940) for the 10.5 to 12,5 micron band. They are listed in Table 7 together with the values of  $J_1$  (T) and the product  $J_1$  (T)  $P_1$  ( $\Delta \lambda$ , T) over the range of expected blackbody temperatures. For a photovoltaic  $\bar{C}d_X Hg_{1-x}$  T<sub>e</sub> detector with a mazimum response between 10.5 and 12.5 microns, the typical **D\* is** 5 x  $10^9$  cm  $\frac{hz^{1/2}}{watt}$  and the best 1 x  $10^{10}$  (See Section 3.0). The signal-to-noise ratio as a function of temperature is shown in Figure 25 for a  $D^*$  of  $5 \times 10^9$ .

#### Table 7

Blackbody Emittance in the 10.5 to 12.5 Micron Band

![](_page_43_Picture_267.jpeg)

 $\Delta \lambda = 10.5$  to 12.5 microns  $\mu$  $D^*$  ( $\Delta \lambda$ ) = 5 x 10<sup>9</sup> cm hz <sup>1/2</sup>/watt  $T_0 = 0.4$  $D_c = 3.2$  **inches**  $\phi = 2.5 \times 10^{-3}$  radian  $A_c^{1/2} = 5 \times 10^{-2}$  cm  $\Delta f_{g}$  = 4.2 x 10<sup>3</sup> hz

![](_page_44_Figure_1.jpeg)

Figure 25 Signal-To-Noise Versus Temperature

The statement of work requires that the noise equivalent temperature be less than **170** degrees **K.** Figure **25** shows that at **170** degrees **K** the signal-tonoise ratio is  $6.1$  for a  $D^*$  of  $5 \times 10^9$ . The DLK21 photoconductive detector used in the breadboard radiometer has a  $D^*$  in the spectral band of about 6.9 x 10<sup>9</sup>. **The** system therefore has a noise equivalent temperature (temperature at which the signal-to-noise is unity) of less than **170** degrees K.

The statement of work also requires that the system must have a noise equivalent temperature difference,  $\Delta T_{\alpha}$ , less than 2 degrees K at a target temperature of **220** degrees **K.** The noise equivalent temperature difference is that temperature change required to produce a change in signal,  $\Delta S$ , equal to the rms noise. Returning **to** the signal-to-noise equation we see that

$$
\frac{\Delta S}{N_{\text{rms}}} = k \Delta [J_1 (T) P_1 (\Delta \lambda, T)]
$$

where  $\Delta$  denotes a change in the quantity enclosed in the brackets with temperature. For a temperature change from **220** to **222** degrees **K** 

$$
\Delta J_1[(T) P_1 (\Delta \lambda, T)] = 6.67 \times 10^{-5} \text{ watts/cm}^2
$$

in the 10.5 to 12.5 micron band. The change-in-signal-to-noise ratio for a  $D^*$ of  $5 \times 10^9$  is then

$$
\frac{\Delta S}{N_{rms}} = 1.7
$$

The requirement for a noise equivalent temperature difference of less than **2** degrees K at a blackbody target temperature of **220** degrees K is therefore met.

Since the statement of work permits a telescope diameter of **5** inches, the sensitivity can be improved by increasing the size of the primary optic. The signal-to-noise varies as the square of the effective optical diameter. If the outside diameter of the telescope is increased from **4** to **5** inches with the design unchanged, the signal-to-noise is increased by **1.56** *X.* The larger collecting aperture can also be used to obtain a smaller instantaaeous field-of-view (higher resolution) at the same sensitivity. Including the dependence of the electronic bandwidth on the field-of-view, the signal-to-noise varies as the cube of the field-of-view

The breadboard radiometer was calibrated in the space chamber at a detector (second-stage patch) temperature of **83** degrees **K.** The results are shown in Figure **26** for blackbody targets from 180 to **340** degrees **K.** The **10.5**  to **12.5** micron interference filter was mounted in the first-stage patch, which was at a temperature of **103** degrees K.

![](_page_46_Figure_0.jpeg)

Radiometer Output - DC Volts

Tbe reference blackbody was at **220** degrees K. This ia the temperature of an extension of the aluminum shroud used as a "cold space" Scan by the"radiometer. In the original data, the output was therefore zero at.220 degrees K and negative for temperatures below 220. The data was modified.to a voltage output of zero at 180 degrees K by adding 0.95 volts (the magnitude of the 180 output) to all the voltages, **3[n** this way, tbe calibraticm curve **shown** in **Figure 26** was obtained.

A comparison with the theoretical calibration, curve waa obtained from the data in Table 7. The value of  $J_1$   $P_1$  at 180 degrees K was subtracted from the  $J_1$ **Pi** values over the temperature range of 180 to **310** degrees **K.** The output (proportiond to **J1 Pi)** at 310 degrees K **was** then set at 4.02 volts (the experimental value), and the theoretical output voltages calculated for 8 temperatures between **180** and 310 degrees K. me results are ahown by the crosses in Figure **26.**  The theoretical points appear to matoh the experimental data within the accuracy of the temperature measurements on the calibration target; the maximum difference on the temperature scale **is** about **3** degrees K.

**A** typical Visicorder tracing of a complete **(360** degree) scan line of the radiometer **is** shown in Figure 27. It shows the reference at 220 degrees **X,** the radiometer housing, the calibration target at 190 degrees K, and the output produced by the ion gauge at the top of the chamber.

![](_page_48_Figure_0.jpeg)

 $\label{eq:2.1} \begin{split} \mathcal{G}(\mathbf{S}) = \mathbf{S}^{\mathsf{T}} \quad & \text{and} \quad \mathcal{G}(\mathbf{S}) = \mathcal{G}^{\mathsf{T}} \quad & \text{$ 

 $\begin{array}{c} \frac{1}{2} \\ \frac{1}{2} \end{array}$ 

- Radiometer Housing (Back Scan; Not Black)<br>Calibration Target at 190<sup>0</sup>K
- $4A00$

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Ion Gauge

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![](_page_48_Figure_4.jpeg)

![](_page_48_Figure_5.jpeg)

# **8.0 NEW TECHNOLOGY**

No items which are considered new technology according to the NASA new **technology clause** of **September 1964 were developed during the third phase of the contract (breadboard day-night radiometer). However, the breadboard radiometer incorporated the new technology items reported in the first part** of **the final report (firqt and** second **phases of the contract).**