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# SUPER LOKI DART METEOROLOGICAL ROCKET SYSTEM

Prepared under Contract No. NAS 8-20797 by Bruce Bollermann and Robert L. Walker

SPACE DATA CORPORATION



For

NASA-GEORGE C. MARSHALL SPACE FLIGHT CENTER Huntsville, Alabama

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# SUPER LOKI DART METEOROLOGICAL ROCKET SYSTEM (Final Report)

By

Bruce Bollermann and Robert L. Walker

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SPACE DATA CORPORATION Phoenix, Arizona

For

Aero-Astrodynamics Laboratory

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NASA-GEORG C. MARSHALL SPACE FLIGHT CENTER

# FOREWORD

This document presents the results of work performed by the Space Data Corporation, Phoenix, Arizona, in support of the Aerospace Environment Division, Aero-Astrodynamics Laboratory, Marshall Space Flight Center, Huntsville, Alabama, under contract NAS8-20797.

Appreciation is given to Mr. Robert Turner of the above laboratory for his support of this program and to the personnel of the White Sands Missile Range for their cooperation in the initial flight testing of the Super Loki Dart.

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### 1. INTRODUCTION

The Super Loki Dart Meteorological rocket system has been developed for NASA - Marshall Space Flight Center to obtain high-altitude (85 km) wind data with a low cost rocket vehicle and a radar-reflective chaff payload. The Super Loki Dart consists of a scale-up of the older Loki Dart system which has been in use for many years to gather wind data to altitudes up to 65 km. The Super Loki Dart two-stage vehicle consists of a high-impulse solid-propellant rocket motor as the first stage, and a non-propulsive dart which contains the chaff payload as the second stage.

Altitudes as high as 125 km have been obtained with this vehicle system during the development flight tests at White Sands Missile Range. Altitudes to 113 km are expected for flights from sea level launch sites. A helical-rail launcher has been developed to impart spin or roll to the vehicle prior to release in order to minimize impact dispersion and associated range safety problems.

The basic Super Loki rocket motor can be used to propel larger diameter instrumented dart systems to altitudes on the order of 85 km to upgrade the atmospheric temperature profile measurements currently being conducted by the standard-size Loki.

# 2. DEVELOPMENT PROGRAM

The Super Loki Dart vehicle has been designed as a low cost replacement for the Cajun Dart for high altitude wind measurements. The goal of the Super Loki system was to achieve an altitude of at least 95 km at less than one-half the cost of the Cajun Dart. A further goal was versatility of the Super Loki rocket motor so that it could be used to propel darts of various sizes containing various kinds of meteorological payloads.

Design efforts were initiated during July 1967, and the first static firing of the rocket motor was conducted during November. Three additional static firings were conducted through January 1968 to verify the initial results and obtain a reliability history. All static firings were completely successful and the results were repeatable.

A series of five development flight tests were conducted at the White Sands Missile Range during the months of April and May 1968. The three units which were radar tracked over apogee achieved altitudes of about 125 km. Late radar aquisition of the descending chaff cloud from a fourth unit permitted an estimate of apogee altitude slightly over 125 km. A fifth unit was not tracked bv radar, and no estimate of performance could be made. The White Sands performance data indicated that the vehicle should be able to achieve altitudes of about 113 km from sea level launch sites. Therefore, the design was frozen, and the remaining twenty units in the contract were sent to Cape Kennedy for operational use. Complete range safety and performance documentation was supplied to conclude the current program.

# 3. VEHICLE DESCRIPTION

### 3.1 General.

The Super Loki Dart as shown in Figure 3.1 is a two-stage sounding vehicle consisting of a solid-propellant Super Loki rocket motor as the first stage and a non-propulsive dart containing the payload as the second stage. A dimensional sketch of the vehicle is shown in Figure 3.2. This vehicle is essentially a scaled-up version of the standard Loki Dart vehicle as indicated in Figure 3.3.

## 3.2 Rocket Motor.

The Super Loki rocket motor consists of an aluminum case with an internal burning cast-in-the-case solid propellant. Major design characteristics of the rocket motor are presented in Table 3.1. An aluminum interstage coupling structure is located at the head end of the rocket motor. The propellant fuel is a polysulfide polymer and the oxidizer is ammonium perchlorate. A photograph of the rocket motor is shown in Figure 3.4. The igniter consists of two parallel 1 watt/ 1 ampere nofire squibs and an appropriate ignition charge. The igniter is separable from the motor and is installed at the launch site. A cross-section view of the Super Loki rocket motor with the igniter installed is shown in Figure 3.5.

# 3.3 Dart.

The high altitude chaff dart as shown in Figure 3.6 for the Super Loki system consists of a steel cylindrical body with a steel ogive and an aluminum tail piece. The cylindrical body contains the chaff payload which is packaged into split steel staves. The ogive is retained at the forward end of body with shear-screws which are sheared during payload expulsion out from the forward end of the dart. The tail piece contains an electrically-actuated 145-second pyrotechnic time delay and a small payload ejection charge. Four steel fins are roll-pinned into the dart tail for flight stability. The aft end of the dart tail is boattailed to reduce aerodynamic drag and to be used to mate the dart to the booster. A cross-section view of the chaff dart is shown in Figure 3.7. Major chaff dart characteristics are presented in Table 3.2.



# SUPER LOKI VEHICLE CONFIGURATION

FIGURE 3.1





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A-1362

# TABLE 3.1

# SUPER LOKI ROCKET MOTOR DESIGN CHARACTERISTICS SUMMARY

Length (inches)	78	
Diameter (inches)	4	
Weights:		
Inert Motor With Interstage (kg)	5.26 (11.6 lb)	
Propellant (kg)	16.87 (37.2 lb)	
Total (kg)	22.14 (48.8 lb)	
Motor Mass Fraction	0.76	
Burning Time (seconds)	2.0	
Chamber Pressure:		
Maximum (Atmospheres)	100.02 (1470 PSIg)	
Average (Atmospheres)	83.69 (1230 PSIg)	
Thrust at Sea Level:		
Maximum (kg)	2608.20 (5750 lb)	
Average (kg)	2018.52 (4450 lb)	
Total Impulse at Sea Level (nt-sec)	3.96 (8900 lb-sec)	
Specific Impulse at Sea Level	239	

# TABLE 3.2 SUPER LOKI CHAFF DART DESIGN CHARACTERISTICS

Length	122.33 cm (48.16 inches)
Diameter	4.13 cm (1.625 inches)
Weight	6.12 kg (13.5 pounds)
Payload Volume	491.61 cm <sup>3</sup> (30 inches <sup>3</sup> )



# SUPER LOKI ROCKET MOTOR

FIGURE 3.4



# CROSS-SECTION VIEW OF SUPER LOKI ROCKET MOTOR WITH IGNITER INSTALLED



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# SUPER LOKI CHAFF DART

FIGURE 3.6



The payload consists of 0.0127 mm (0.5 mil) "S"-band, aluminumized-mylar chaff.

# 3.4 Launcher Description.

The Super Loki Launcher consists of four helical rails which complete approximately one-third of a revolution throughout the launch rail length. The launch rail assembly as shown in Figure 3.8 consists of six cast aluminum sections which are bolted together to form a continuous 4.39 m (12 feet) long rail assembly. The four internal rails are equally spaced and form four continuous helices throughout the 4.39 meter (12 feet) length. The edges of the rails are stepped to support the vehicle by the dart fins and the rocket motor nozzle ring. The outside diameter of the launch rail assembly is 26.04 cm (10-1/4 inches).

The purpose of the launch rail is to impart an 8.5 rps spin to the vehicle by constraining the dart fins to a helical path during their travel along the launch rails. The aft end of the motor travels for 4.39 meter (12 feet) prior to its release from the launcher.

The Super Loki Launch Rail Assembly can be mounted to any suitable launcher base by means of forward and aft mounting brackets. A launcher base specifically designed for this rail as shown in Figure 3.9.

A pullaway umbilical harness is provided with the launch rail assembly to retract the dart firing line during first motion of the vehicle.

# 3.5 Vehicle Mass Properties.

The mass properties of the Super Loki Dart Vehicle are presented in Table 3.3. Vehicle center-of-gravity vs time is presented in Figure 3.10. Vehicle pitch moment of inertia vs time is presented in Figure 3.11.



FIGURE 3.8 SUPER LOKI LAUNCH RAIL ASSEMBLY



## TABLE 3.3

# SUPER LOKI DART VEHICLE MASS PROPERTIES

# Chaff Dart:

Weight Center-of-Gravity

Pitch Moment of Inertia

### **Booster:**

Loaded Weight Expended Weight Loaded Center-of-Gravity

Expended Center-of-Gravity

Load Pitch Moment of Inertia Expended Pitch Moment of Inertia

### Vehicle:

Launch Weight Burnout Weight Launch Center-of-Gravity

**Burnout Center of Gravity** 

Launch Pitch Moment of Inertia Burnout Pitch Moment of Inertia 6.12 kg (13.50 lb) 87.63 cm (34.5 inches) from aft end of dart 0.610 kg-m<sup>2</sup> (0.450 slug/ft<sup>2</sup>)

22.19 kg (48.93 lb) 5.28 kg (11.63 lb) 85.6 cm (33.70 inches) from aft end of motor 85.09 cm (33.50 inches) from aft end of motor 7.28 kg-m<sup>2</sup> (5.37 slug/ft<sup>2</sup>) 3.08 kg-m<sup>2</sup>(2.27 slug/ft<sup>2</sup>)

28.32 kg (62.43 lb) 11.40 kg (25.13 lb) 118.36 cm (46.6 inches) from aft end of motor 173.74 cm (68.4 inches) from aft end of motor 20.42 kg-m<sup>2</sup> (15.06 slug/ft<sup>2</sup>) 10.56 kg-m<sup>2</sup> (7.79 slug/ft<sup>2</sup>)



CENTER OF GRAVITY-C.G. - INCHES FROMFIN TRAILING EDGE



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# 4. ARODYNAMIC DATA

The aerodynamic data for the Super Loki Dart vehicle is presented as follows:

Figure 4.1	$C_{N_{lpha}}$ vs Mach No., First Stage
Figure 4.2	C <sub>N∝</sub> vs Mach No., Dart
Figure 4.3	C <sub>P</sub> vs Mach No., First Stage
Figure 4.4	Cp vs Mach No., Dart

The Super Loki Dart is stable during two-stage propulsive flight at essentially a zero degree angle of attack. After dart separation at motor burnout, the dart coasts to apogee in a stable flight made at essentially a zero degree angle of attack in the sensible atmosphere. After rocket motor burnout and stage separation, the expended booster becomes unstable and tumbles. Eventually the booster descends in a flat spin to impact at a relatively slow rate of speed. The drag coefficients for the various stage configurations are presented in Table 4.1.



NOGWAT EOSCE COEFFICIENT - CNX - PER DEGREE



FIGURE 4.2

NOKWAT LOKCE COELLICIENT - CN $^{\alpha}$  - DEG DEG GEE

ļ



FIGURE 4.3

CENTER OF PRESSURE -CP - INCHES FROM NOZIE EXIT

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# TABLE 4.1

# DRAG COEFFICIENT DATA

Super Loki Dart Vehicle – Two Stages Reference Area 85.47 cm<sup>2</sup> (0.0920 ft<sup>2</sup>)

Dart - Coasting Reference Area 9.84 cm<sup>2</sup> (0.0107 ft<sup>2</sup>) Stage Weight - 6.12 kg (13.50 lb)

	-	oluge holghi 0.12 kg (15.50 lb)
Mach No.	CD	Mach No. CD
0	0.400	
0.50	0.420	0 0.350
0.80	0.430	0.90 0.350
0.81	0.930	1.00 0.576
1.40	0.930	1.50 0.576
1.50	0.880	1.75 0.489
1.75	0.770	2.00 0.432
2.00	0.682	2.25 0.393
2.25	0.620	<b>2.50</b> 0.365
2.50	0.570	2.75 0.345
2.75	0.533	3.00 0.329
3.00	0.500	3.50 0.308
3.25	0.470	4.00 0.294
3.50	0.440	4.50 0.284
3.75	0.420	5.00 0.277
4.00	0.397	6.00 0.277
4.25	0.380	7.00 0.262
4.50	0.360	8.00 0.262
4.75	0.345	
5.00	0.331	Expended Booster – Unstable
5.25	0.320	Stage Weight – 5.28 kg (11.63 lb)
5 <b>.50</b>	0.310	<b>Reference Area – 80.22 cm<sup>2</sup> (0.0872</b>
5 <b>.75</b>	0.300	ft <sup>2</sup> )
6.00	0.290	
7.00	0.260	Mach No. CD
		0 22.423
		1.00 22.423
		2.00 15.376
		3.00 6.407

4.00

5.00

10.00

1.068

0.945

0.945

# 5. VEHICLE PERFORMANCE

The nominal trajectory data for the Super Loki Dart launched from sea level altitudes is presented in the series of graphs as follows:

Figure 5.1	Altitude vs Range, 80° QE, Dart
Figure 5.2	Altitude vs Time, 80° QE, Dart
Figure 5.3	Velocity vs Time, 80 <sup>0</sup> QE Dart
Figure 5.4	Altitude vs Range, Various QE's
Figure 5.5	Apogee Altitude and Impact Range vs QE, Dart
Figure 5.6	Altitude vs Range, 80° QE, Booster
Figure 5.7	Altitude vs Time, 80 <sup>0</sup> QE, Booster
Figure 5.8	Apogee Altitude and Impact Range vs QE, Booster

A summary of the major trajectory points for the Super Loki Dart vehicle is presented in Table 5.1. The nominal trajectory details are presented in Table 5.2.

The dart trajectory is based upon stable dart flight prior to and after stage separation. The booster trajectory is based upon stable flight to the point of stage separation. After stage separation, the booster goes unstable and decelerates rapidly to a slow velocity. The booster then descends rather slowly in a flat spin.

The vehicle spin or roll rate profile is presented in Figure 5.9. The vehicle is launched from a helical-rail launcher which imparts a spin rate of 8.5 rps during launch. The booster and dart fins are canted to control the roll rate during the boost and coast phases of flight.



RANGE - KILOFEET



TIME - SECONDS



TIME - SECONDS



VTLILNDE - KITOLEEL




FICURE 5.6



TIME (SECONDS)

FIGURE 5.7



# TABLE 5.1

# NOMINAL TRAJECTORY SUMMARY SUPER LOKI DART, 80° Q.E. SEA LEVEL LAUNCH

	Booster	Dart
Burnout Altitude (m)	1577.6 m(5,176 ft)	1577.6 m (5, 176 ft)
Burnout Range (m)	298.1 m (978 ft)	298.1 m (978 ft)
Burnout Time (sec)	2.1	2.1
Apogee Altitude (m)	2318.9 m (7,608 ft)	113.4 km (372,000 ft)
Apogee Range (m)	446.2 m (1,464 ft)	41.8 km (137,000 ft)
Apogee Time (sec)	6.1	6.1
Impact Range (m)	462.4 m (1, 517 ft)	83.8 km (275,000 ft)
Impact Time (sec)	108	309

# TABLE 5.2

# SUPER LOKI DART TRAJECTORY DATA

COMPUTER PRINTOUTS

TWO DEGREE OF FREEDOM - POINT MASS SIMULATION SPACE DATA CORP

RUN 1 SUPER LOKI - DART 11.63 LB INERT WT 13.5 LB.1 5/8 DIA DART 80 DEG SEA LEVEL DRAG TABLES 3010 AND 4004

0.953	62•330	80.000	0.092	0.025
1000.000	0.000	0.000	150000.031	0.100
	10.000	0.000	0.000	0.000
	100.000	1.000	37.200	25.130

## **\*\*** OUTPUT UNITS **\*\***

FEEL SECUNDS FOUNDS(FORCE) FOUNDS(MASS)	DEGREES
---	---------

TIM	E ALT	VEL	RANGE	MACH	Q	ANG	THRUST	DRAG	MASS	ACC/G	VVERT
0.0	0.	0	0.	0.0	0•	80.0	0.	0	62.3	-0.98	0
0.1	6•	138	1.	0.1	22•	<b>79</b> •8	2887.	Ō	61.1	47.13	136
0.2	27•	289	4.	0.3	99•	79•6	2927.	3	59.9	47.59	285
0.3	63•	448	11.	0.4	238•	<b>79.5</b>	3041.	9	58.6	50.34	440
0.4	115.	619	21.	0.6	455•	79•5	3277.	17	57.2	55.28	609
0.5	185•	808	34.	0.7	773.	79.4	3513.	30	55.8	60.67	795
0.6	275.	1015	50.	0.9	1216.	79•4	3797.	104	54.1	66.33	998
0.7	386•	1242	71.	1.1	1815.	79•4	4082.	155	52.4	72.94	1221
0.8	520•	1491	96•	1.3	2604•	79•3	4367.	222	50.7	79.67	1465.
0.9	680•	1762	126.	1.6	3621.	79.3	4622.	281	48.7	87.00	1732
1.0	867•	205 <b>9</b>	161.	1.8	4914.	79•3	4875.	332	46.7	95.09	2023
1.1	1085•	2379	203.	2.1	6519•	79.3	5016.	388	44.5	101.82	2338`
1.2	1336•	2721	250•	2.4	8465•	79•3	5154.	451	42.4	108•74	2674
1.3	1621•	3083	304•	2.8	10777.	79•2	5196.	524	40.1	114.34	3029
1.4	1942•	3463	364•	3.1	13472•	79•2	5238.	601	37•9	120.23	3403
1.5	2302•	3864	432•	3.5	16588.	79•2	5277.	673	35.7	126.75	3796
1.6	2702•	4283	508•	3.9	20140.	79•2	5231.	757	33•4	131.89	4208
1.7	3145.	4728	592.	4.3	24219.	79.2	5350.	840	31.1	142.08	4645
1.8	3633.	5211	685.	4.7	28995•	79•2	5469•	923	28.8	154.61	5120
1.9	4168•	5662	786.	5.1	33684.	79•2	4312.	1005	26.7	126.90	5562
2.0	4739•	5925	895•	5.4	36259•	79•2	1744•	1047	25•3	42.26	5821
2.1	5176•	5893	978.	5.4	35388.	79•2	0.	1025	25.1	-33.91	578 <b>9</b>
****	*******	* * * * * *	******	*****	******	*****	******	*****	****	* * * * * * * *	****
COAST	STAGE	A=	0.0107	7	M= 13	50	<u> </u>	*	T2= 1.	1 0	1= 0
2.1	5320.	5886	1005.	5.4	35150.	79.2	0.	103	13.5	-8.64	5782
3.1	10976.	5637	2083.	5.3	27062.	79•1	0.	79	13.5	-6.90	5537
4.1	16411.	5437	3125.	5.2	21124.	79.1	0.	62	13.5	-5.61	5339
5.1	21666•	5272	4139.	5.1	16651.	79.0	0.	49	13.5	-4.63	5176
6.1	26773.	5136	5130.	5.1	13210.	78.9	0.	39	13.5	-3.88	5041
7.1	31756•	5021	6103.	5.1	10525•	78•9	0.	31	13.5	-3.29	4927
8.1	36634•	4923	7062•	5.1	8357•	78•8	0•	24	13.5	-2.81	4830
9•1	41421•	4839	8009•	5.0	6427•	78•7	0•	19	13.5	-2.39	4746
10.1	46131.	4767	8948•	4.9	4979.	78•6	0•	14	13.5	-2.07	4675
11.1	50774•	4704	9879•	4 • 9	3883•	78•6	0•	11	13.5	-1.83	4612
12+1	55358.	4648	10806.	4 • 8	3045.	78.5	0.	9	13.5	-1.65	4556
13+1	59888•	4598	11727.	4.7	2398•	78•4	0.	7	13.5	-1.51	4505
14.1	64369•	4551	12646•	4.7	1897.	78 <b>•3</b>	0.	5	13.5	-1.39	4458
15.1	<b>6</b> 8805•	4507	13561.	4.7	1500.	78•2	0•	4	13.5	-1.30	4414
16.1	73197.	4466	14474•	4•6	1188.	78•2	0.	3	13.5	-1.23	4372
17.1	77550•	4427	15386•	4•6	946•	78.1	0•	2	13.5	-1.18	4333
18.1	81863.	4390	16296.	4.5	755.	78.0	0•	2	13.5	-1.14	4295
19.1	86140.	4354	17205 •	4.5	605•	77•9	0•	1	13.5	-1.10	4258
20.1	90380•	4319	18113.	4•4	487•	77•8	0•	1	13.5	-1.08	4222
21.1	94585.	4284	19021	4.3	392.	77•7	0.	1	13.5	-1.05	4187
22.1	98755.	4250	19927.	4•2	317.	77•6	0•	0	13.5	-1.04	4153
23.1	102890.	4217	20834.	4•2	258•	77.5	0.	0	13.5	-1.02	4119
24 • 1	106992.	4184	21739 •	4.1	209•	77•4	0•	0	13.5	-1.01	4085
25.1	111061.	4152	22645.	<b>4</b> • 0	169.	77•4	0.	0	13.5	-1.00	4052
20.1	112171.	4119	235/30	4.0	136.	77•3	0.	0	13.5	-0.99	4018
2/01	119198.	4087	244/8	3.9	111.	77.2	0.	0	13.5	-0.99	2707 2000
20.1	12310/0	4055	253830	3.9	91.	77•1	0.	U A	10.5	-0.00	2020
27.1	12/104.	4023	202880	3.8	75.	77.0	0.	0	13.5		2720 2200
2041	1340080	2272	211920	3•8 ∽ 7	62.	16.9	0.	Ŭ	13.5		3000 305/
27.1	134880.	3020	2809/0	5.1	51.	76•7	0.	0	12.5		2020
2201	142527	2927	290010	5.0	43.	10.6	0.	0	1303	-0.91	2707
24 1	146303	2078	299000	5.0	36.	16.5	0.	U A	12.5	-0.90	2740
2401 25.1	160044	200/	20810e	ン•り コ =	30.	16.4	0.	0	12.5	-0.70	2720
2201	100400	2020	J1 (140	300	25 •	16.3	Ŭ •	U	1202	-0070	2120

-34.2-

			EX	DATMOSPHER	E RE	SULTS			
TIME		ALT		RANG	Ξ	ALT (KN	1)	RANGE	(KM)
0.420316E	02	U.175046E	06	0.378177E	05	Ú•533542E	02	U.115268E	02
0.493989E	02	0.200046E	0ó	0.443199E	05	0.609742E	02	0.135087E	02
0.573292E	02	0.225046E	06	0.519202E	05	0.685942E	02	0.158253E	02
0.659739E	02	0.250046E	06	0.595918E	05	0.762143E	02	J.161636E	02
0.755670E	02	0.275046E	96	0.681075E	05	U.838343E	Û2	U-207592E	02
0.865085E	02	U-300046E	06	0.778279E	05	0.914543E	02	0.237220E	02
0.995975E	02	0.325046E	06	0.894804E	05	0.990744E	02	0.272737E	02
0.117018E	03	0.3500465	06	0.105091E	06	0.106694E	03	0.320318E	02
0.209511E	03	0.325046E	06	0.185352E	06	0.990744E	02	0.564955E	02
0.222600E	03	0.300046E	ü6	U.197004E	06	0.914543E	02	0.600472E	02
0.233542E	03	0.275046E	06	0.206725E	06	0.838343E	02	0.630100E	02
0.243135E	03	0.250046E	06	0.215240E	06	0.762143E	02	0.656056E	02
0.251779E	03	0.225046E	06	0.222912E	06	0.685942E	02	0.679439E	02
0.259710E	03	0.200046E	06	0.230512E	06	0.6097425	02	0.702605E	02
0.267077E	03	0.175046E	06	0.237014E	06	0.533542E	02	0.722423E	02
0.273985E	03	0.150046E	06	0.743117E	06	0.457342E	02	0.741026E	02
0.280511E	03	0.125046E	06	0.243887E	06	0.381142E	02	0.758610E	02
0.286709E	03	0.100046E	06	0.254372E	06	0.304941E	02	0.775329E	02
0.292625E	03	0.750462E	05	0.260038E	06	0.228741E	02	0.792598E	02
0.298293E	03	0.500461E	05	0.265044E	06	0.152541E	02	0.807859E	02
0.303742E	03	0.250461E	05	0.269862E	06	0.763410E	01	0.822543E	02
0.308995E	03	0.461875E	02	0.274891E	06	0.140779E-	-01	0.837871E	02
0.314070E	03-	-0.249538E	05	0.279375E	06-	-0.760594E	01	0.851538E	02

## ORBITAL PARAMETERS

E A P QC 0.998788E 00 0.106557E 08 0.258070E 05 0.220312E-01

## APOGEE CONDITIONS

TIMEALTRANGEALT(KM)RANGE(KM)0.154554E030.371891E060.137416E060.113352E030.418846E02

## IMPACT CONDITIONS

TIMEALTRANGEALT(KM)RANGE(KM)0.309004E030.000000E000.274891E060.000000E000.837871E02

TWO DEGREE OF FREEDOM - POINT MASS SIMULATION - SPACE DATA CORP. . . . . . . . . . . . . SUPER LOKI DART BOUSTER TRAJECTORY 11.63 LB INERT WT. 13.5 LB 1578 DIA DART 80 DEG SEA LEVEL - DRAG TABLE 3010 AND UNSTABLE B 0.025 0.092 80.000 62.330 0.953 0.100 150000.031 0.000 0.000 1000.000 0.000 0.000 20.000 25.130 37.200 1.000 100.000 \*\* OUTPUT UNITS \*\* FEET SECURDS POUNDS(FURCE) POUNDS(MASS) DEGREES

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TIVE	ALT	VEL	RANGE	SACH	ų	Â.G	THRUET	URAG		CC/6	VVEXT
	U.		· ····· ······························	 		86.00		Ű <sup>–</sup>	0	J • 9 5	ن.
0.1	6.	108	1.	U.L	22•	79.9	2887.	J	0101 4	7.13	130
(i • 2	27.	£89	4.	ق ف ن	99 <b>•</b>	79.6	69270	3	 ラン・ソール	7.05	250
د و ن	63.	448	11.	0.4	258.	79.5	3041.	9	50.00 5	بەۋ ۋ	ن به به
6.4	115•	619	21.	0∙6	455•	75.5	s277•	17	57.2 5	5.20	609
Ú•5	105.	ou B	34.	J.7	773•	19=4	3513•	30	<b>ງ</b> 5.8 ເ	0.07	755
0.0	215.	1015	50.	-0.9	1210.	79.4	3747.	104	5401 5	ود ان	555
6.7	386.	1242	71.	1.1	1815.	79.4	4082.	155	52.4 7	2.44	12.1
6.0	520.	1491	96.	1.3	2604.	74.3	4367.	222	50.77	9.67	1465
ັ ບ•ຯ	680.	1702	120.	1.6	3621.	79.3	4622.	281	48.7 8	7.30	1752
1.0	867.	2059	161•	1.8	4914.	19.3	4878.	2 ف 🕄	40.7 9	5.09	2023
1.1	1085.	2379	203•	2+1	6519.	79.3	5016.	388	44.510	1.32	2005
1.2	1336.	2721	250+	2.4	- 8465.	79.3	5154.	451	42.410	0.74	2074
1.3	1621.	5683	304.	2.0	10777 ·	79•2	5196.	524	40•111	++•34	3629
1.4	1942•	5463	364.	3.1	13472.	79.2	5238.	601	37.912	0.25	5405
1.5	2302•	2864	432.	3.5	16588.	74.2	5277.	673	35.712	6.75	3796
1.6	2752.	4283	<b>&gt;</b> 08●	3.9	20140.	79+2	5231.	757	33.413	1.59	4203
1.7	3145.	4728	592.	4.3	24219.	79.2	5350.	840	31.114	2.08	4045
1.8	3633.	5211	685.	<b>4</b> • 7	28995.	7902	5469.	923	20.015	4.61	5120
1.9	4168.	5662	786.	5.1	33684 ·	79.2	4312.	1005	26.712	5.90	5502
2.0	4739.	5925	895•	5.4	56259.	75.2	1744.	1647	23.3 4	2.26	2021
2.1	5176•	5895	978•	5.4	35388 ·	79.2	U 🛛	1025	25.1-3	ショウエ	5764
<b>华大北北水</b> 省	******	*****		*****	*	*****	*******	*****	*********	X ~ A # 4	3 6 6 6
COAST	STAGE	= <u>A</u>	0.0872	2	M= 11•	63	ŢÌ═₩₩₩₩	• <b>*</b>	T2= 2∙0		= 1
2.1	5318.	5692	1005.	5.2	52874 ·	79-2	Ú.	2709	11.6**	***	5592
4.1	7524	96	1429.	0.1	8.	76.0		17	11.6 -	2.45	7.5
6.1	7608.	14	1464	U.U	ບໍ <b>່</b>	14.5	Ú.	- · ·	11.6 -		
8.1	7556.	51 51	1489	0.0	2.	-76.5	Ü.	4	11.6	ا د د د د	- 2 Ú
10.1	7429	72	1504	0.1	5.		0.	0	11.5	0.15	-72
12.1	1211			ο.i	5-	-68.2		11	11.6	0.03	-77
14.1	7121.	78	1515.	0.1	5•	-89.2	<b>0</b> •	11	11.6	0.00	-75
16.1	6964.	78	1510.	0.1	5.	-89+6	Ú•	11	11.6 -	0.00	-73
18.1	6807.	78	1517.	0.1	5.	-89+8	0•	11	11.6 -	Ü•Uù	-78
20.1	6650.	78	1517.	0.1	5.	-89.9	0.	11	11.6 -	0.30	-73
22.1	6494.	78	1517.	0.1	5.	-69.9	0.	11	11.6 -	0.00	-75
24.1	6338.		1517.	-0.1	5.	-89.9	• 0	11	11.6 -	0.00	-77
26.1	6180.	77	1517.	0.1	5.	-59.9	C•	11	11.6 -	0.00	-77
28.1	6025.	77	1517.	0.1	5.	-34.9	<b>U</b> •	11	11.6 -	0.00	-77
30.1	5870.	77	1517.	0.1	5•	<b></b> 09+9	<b>ن</b> •	11	11.6 -	0.00	-77
32•ì	5716.	77	1517.	0.1	5•	-69.9	Ú.	11	11.6 <del>-</del>	0.00	-77
34.1	5562•	76	1517.	Ú•1	5.	-59.9	• تا	11	11.6 -	0.00	-70
36.1	5408.	76	1517.	U•1	5•	-54.4	U.	11	11.6 -	ປູບັບ	-75
- 38.1	5255•	76	1517.	6.1	5.	-89.9	Ü •	11	11.6 -	<b>u</b> • 0 0	-75
40.1	5102.	76	1517.	U•1	5.	-39-9	U •	11	11.0 -	ປະປປ	-70
42.1	4949.	76	1517.	0.1	5•	-89.9	Ú.	11	11.5 -	J • J J	-70
- 44.1	4797.	76	1517.	0.1	5•	<b>≈</b> 59•9	Je	11	1100 -	U L U U	-70
46.1	4645.	1 75	1517.	0.1	5•	<del>-</del> 89•9	0.	11	11.6 -	U 🖌 U Ü 👘	-75
48.1	4493.	75	1517.		5.	~ <u>-89.9</u>	U •	11	11.6 -	ບ∎ີບ	-75
50+1	4342•	75	1517.	0•1	5•	-89+9	() •	11	11.5 -	<b>U •</b> U U	-75
52+1	4191.	75	1517.	6.1	5.		1.	11	11.6 -		-75
- · · •		· •				-0905	U .			<b>v</b> • v v	
54•1	4040•	75	1517.	0.1	5.	-89•9 -89•9	0.	11	11.6 -	0.00 0.00	-75

53•1	3740.	74	1517.	0.1	5.	-89.9	L •	11	11.6 -0.00	-74
60.1	3591.	74	1517.	لمال	2.	-64.9	Ú.	11	11.6 -0.000	-7
62.1	3442.	74	1517.	Ú•i	5.	-04.2		11	11.0 -0.00	-7.
64.1	3293.	74	1517.	Jel	<b>ה</b> ל	-69.9	ē.	11	11.0	- 74
06.1	3144.	74	1517.	U.L	5•	9•75-	Ú.		11.0 -U.U	-74
68.1	2996.	14	1517.	0.1	5.	-35.9	 ان	11	11.6 -0.00	- 14
70.1	2848.	15	1517.	J • 1	5•	-35.9	 	11	11.0 -0.00	-7.5
12.1	2700.	73	1517.	υ÷ì	5.		Ú.	11	11.0 -0.00	-73
74.1	2553.	73	1517.		5 •	-89.9	U •	1	11.0 -0.00	-73.
76.1	2406.	73	1517.	0.1	5.	-89.99	Ú •	11	11.0 -0.00	-75
78.1	2260.	73	1517.	U . i	۔ • ذ	-39.9	G I	11	11.5 -0.00	-75
80.1	2113.	73	1517.	Uel	5.	-04.9	C •	11	11.6 -0.00	-73 -
He l	1967.	72	1517.		5.	-89.9	6.	11	11.6 -0.00	-72
84.1	1822.	72	1517.	0.1	5.	-89.9	C •	1	1:.6 =0.00	-72
86.1	1676	72	1517.		······································					-72
88.1	1531	72	1517.	Ú.	5.		. •	11	11.6 -0.00	-72
90.1	1357	12	1517.		5.	-246		11	11.6 - J.J.	-12
92.1	1242	72	1517.		5.	-59-9	3.	11	11.6 -U.J	- / -
94.1	1098.	71	1517.		5.	-89.9	U •	11	11.6 -0.00	-71
96.1	995	71	1517.	0.1	5.	-24.44	0.	11		-71
98.1	811.	71	1517.	0.1			·····	1 1	11.00 -00.00	-71
100-1	668.	71	1517.	(i.a.l	5 e	-89.9	Ú.	11	11.6/-0.00	-71
102.1	525.	·····/ = 71	1517.	0.1	5.		0.	11		-7
104.1	382.	71	1517.		5.		U •	11	11.6 -0.00	-71
106.1	240	71	1517.	0.1	5.	-89.9	0.	11	11.6 -0.00	-71
108.1	68 -	70	1517.	0.1	5		0.	11	11.6 = 4.444	-74.
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FIGURE 5.9

TIME - SECONDS

# 6. RANGE SAFETY DATA

Complete range safety documentation has previously been presented in Space Data Corporation's TM-309, and the results are summarized as follows:

Table 6.1	Ordnance Data
Table 6.2	Impact Dispersion Data
Figure 6.1	Dart Wind-Weighting Data
Figure 6.2	Booster Wind-Weighting Data

TABLE 6.1

# ORDNANCE DATA

	Explo	sive	Electrical S	quib Characteri	stics
ten	Weight	Type	No-Fire	Resistance	All-Fire
Rocket Motor Propellant	16.87 kg 37.20 lb	Polysulfide, Ammonium Perchlorate	1	I	ŧ
Rocket Motor Igniter (2 squibs in parallel)	50 grams	Cupric Oxide Aluminum Powder	1 watt/ 1 amp 5- minutes each squib	1.15 ohms + 0.15 ohms ēach squib	5.0 amps each squib
Dart Payload Separation Device with 145-second Time Delay	5 grams	Boron Potassium Nitrate	1 watt/ 1 amp 5 - minute	1.05 ohms + 0.25 ohms -	5.0 amp

# TABLE 6.2

# IMPACT DISPERSION DATA

Vehicle Stage	Dart	Booster
80 <sup>0</sup> QE Impact Range	83.8 km (275,000 ft)	462 m (1, 517 ft)
Maximum Three-Sigma Impact Dispersion Radius	9, 516 m (31, 220 f <del>t</del> )	136 m (447 feet)





## 7. VEHICLE ASSEMBLY, CHECKOUT AND LAUNCH PROCEDURES

The Super Loki Dart system is supplied in three component parts shown in Figure 7.1, as follows:

- 1. Super Loki Rocket Igniter.
- 2. Super Loki Rocket Motor
- 3. Super Loki Chaff Dart

At the launch site the dart is assembled to the rocket motor, the vehicle is inserted into the launcher, the dart initiator leads are connected to the dart tail and the igniter is installed in the rocket motor. After a continuity check through the igniter and dart leads separately, the system is ready to launch.

A step-by-step procedure for vehicle assembly, checkout and launch is presented as follows:

- 1. Remove dart and rocket motor from shipping boxes.
- 2. Insert aft end of dart into forward end of rocket motor as shown in Figure 7.2, assuring that anti-roll pin in dart tail is aligned with slot in motor headplate dart alignment cup.
- 3. Insert aft end of assembled vehicle into forward end of launch rails as shown in Figure 7.3, and slide vehicle back until dart fins reach launch rails.
- 4. Align dart fins with the four launch rails as shown in Figure 7.4, so the booster fins will be located between the rails as shown in Figure 7.5.
- 5. Slide the vehicle completely back to the rear of the launcher as shown in Figure 7.6.
- 6. Assemble the dart firing leads to the dart tail by means of the respective connectors utilizing the pullaway harness shown in Figure 7.7.
- 7. Assemble igniter into aft end of rocket motor by screwing igniter base into rocket motor nozzle closure.



FIGURE 7.1 SUPER LOKI DART SYSTEM COMPONENTS

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FIGURE 7.4 LAUNCH INSTALLATION - INTERMEDIATE (FORWARD VIEW)

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FIGURE 7.5 LAUNCH INSTALLATION - INTERMEDIATE (REAR VIEW)





FIGURE 7.6 LAUNCH INSTALLATION - FINAL



FIGURE 7.7 DART FIRING LINE CONNECTION

- 8. Perform continuity test of dart initiator through firing leads. Resistance should be within 0.80 to 1.30 ohms.
- Perform continuity test of igniter through firing leads connector positions C and D. Resistance should be within 0.50 to 0.70 ohms.
- 10. Vehicle is now ready for launch. Provide at least 5.0 amperes to fire dart delay and 10.0 amperes to fire rocket motor igniter. Dart initiator ignition reliability will be enhanced by supplying initiation current of 5.0 amperes at T-5 seconds (i.e., 5 seconds before rocket motor is ignited.)

## 8. DEVELOPMENT FLIGHT TEST RESULTS

A series of five developmental flight tests of the Super Loki Dart were conducted at the White Sands Missile Range to prove out the vehicle system. As is the custom at White Sands for Loki Dart type vehicles, the launch angles were not adjusted for wind effects, and all vehicles were launched at an azimuth setting of 344 degrees, even though surface level winds varied from 1.03 m/sec to 12.87 m/ sec (2 to 25 knots). Complete radar tracks were obtained for flights number 2, 4 and 5, and these agreed quite well with the theoretical trajectory. A late radar aquisition of the descending chaff payload for flight number 1 permitted an estimate of apogee altitude for this flight. No radar data was obtained for flight number 3. A summary of the flight test results is presented in Table 8.1. Since, after apogee, the radar tracks the descending chaff target rather than the vehicle, the vehicle impact data had to be estimated from the apogee data.

A plot of the estimated dart impacts is presented in Figure 8.1. These impact displacements from the nominal include the full effect of the winds, since launcher adjustments were not made to compensate for wind effects.

At least four of the vehicles in this flight test series performed in accordance with the theoretical trajectories and demonstrated impact dispersions within predicted values. Although the fifth vehicle was not tracked by radar, visual observation indicated a normal flight at least through the propulsive phase. TABLE 8.1

# SUPER LOKI DART FLIGHT TEST SUMMARY

				· · · · · · · · · · · · · · · · · · ·	T		
P~://	Knots	25	20	20	2	10	I
C. infacto	Degrees	270	280	270	240	180	ſ
d Impact	(Degrees)	ar Track Apogee	340		349	347	344
Estimate	(Feet)	No Rad Over	306,000		316,000	311,000	301,113
Apogee Time	(Sec)	168 (est)	165	ır Track	160	162	162
Apogee	(Feet)	420, 000 (est)	410,000	No Rado	411,000	405,000	409, 500
Settings Azimuth	(degrees)	344	344	344	344	344	344
Launch S	(degrees)	85	80	80	80	80	80
l aunch	Location	WS <b>M</b> R	WSMR	WSMR	wsmr	WSMR	wsmr
Flinht	Date	22Apró8	ό <b>Μα</b> γ68	6May68	20 May 68	20 May 68	al yry
Eliaht	Number	-	3	R	4	2	Theoretic Trajects

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FIGURE 8.1

## 9. HIGH ALTITUDE WIND PROFILE MEASUREMENT

The Super Loki Dart payload consists of 0.0127mm (0.5 mil) thickness aluminized Mylar chaff. This chaff is cut to "S" band radar dipole length which is the same as full wavelength for the "C" band radar. Thus both "S" band and "C" band radars may be used for tracking. The advantage of this chaff, over other possible radar targets, is that it has the lowest sectional density available for a radar target, and therefore, results in the slowest fall rates for wind tracking.

As can be seen from the theoretical fall rate curves of Figure 9.1, the higher the apogee and ejection altitude, the faster the descent velocity is at altitudes above 85 km. Wind shear measurement error is a function of the square of the descent velocity, therefore, it is important to obtain as slow a descent rate as possible throughout the altitude region of interest. Since the current program requires wind data for sea level launch sites from an altitude of 85 km to 65 km, the apogee altitude of the system should be about 90 km.

The developmental flight tests at the White Sands Missile Range (1219 m -4,000 ft. launch elevation) were primarily to test vehicle performance and the apogee altitudes were too high for aptimum wind measurement. The sea level launches should result in apogees close to the optimum for the stated measurement requirements.

Although the flights at White Sands were too high for optimum wind measurement, the data is presented here as an example. The chaff descent profiles for the White Sands flights were quite similar and are represented by Figure 9.2. The matching fall rate profile as shown in Figure 9.3 indicates that maximum descent velocities of over 609.6 m/sec (2,000 fps) were obtained at an altitude of about 90 km.

The high altitude wind profiles derived from the Super Loki flights at White Sands are presented in Figure 9.4. The wind profiles obtained from the High Energy Loki (apogee 85 km) and the regular Loki (apogee 65 km) chaff targets are also plotted for comparison purposes. From sea level launch sites wind data is expected at higher altitudes with the Super Loki system since the vehicle apogee will be lower and the chaff descent rates not as great.

# THEORETICAL FALL RATE OF 0.5 mil MYLAR CHAFF (289 m/sec (950 fps) HORIZONTAL VELOCITY AT APOGEE)



FIGURE 9.1

TYPICAL CHAFF DESCENT PROFILE WSMR FLIGHT TEST SERIES FIGURE 9.2



<sup>- 54 -</sup>

## FIGURE 9.3 TYPICAL CHAFF FALL RATE PROFILE FOR WSMR FLIGHTS SUPER LOKI #4 - FALL RATE vs ALTITUDE

20 May 1968





- 56 -



- 57 -



STATITUDE - KILOMETER

-58-

FIGURE 9.4 (Cont.)

20 May 1968 N-S Component

HIGH ALTITUDE WIND DATA



HIGH ALTITUDE WIND DATA

20 May 1968 E-W Component



SAATAMOT - KILOMETERS
## 10. OTHER APPLICATIONS

The development of a two-inch (5.08 cm) diameter instrument dart for the Super Loki system is proposed as a follow-on to the chaff dart system development to improve the altitude and measurement capability of current instrumented systems. An 85 km apogee is achievable with the proposed instrumented dart system, and the payload volume is more than double that of the current instrumented dart systems. This increased volume can be used for additional sensors, a transponder/telemetry sonde, and most important, an increased-size parachute to obtain significantly slower descent rates of the sonde during the measurement period. Temperature and wind measurement errors of current systems are functions of the square of the descent velocity, and a significant improvement in measurement accuracy can accrue by reducing the parachute descent rate. The cost of this instrumented dart systems should not be significantly greater than the current instrumented dart systems.

The proposed Super Loki Instrumented Dart system consists of the Super Loki rocket motor and a two-inch diameter (5.08 cm) dart. The dart is designed to contain a maximum diameter parachute to extend the altitude and improve the accuracy of wind and temperature measurements. Performance of this system is as follows:

85
14 lb (6.35 kg)
85 km
15 km
132 sec.
Mach 5.4
102 g

A nominal trajectory is plotted in Figure 10.1

The two-inch (5.08cm) diameter instrumented dart contains a payload volume of 80 cubic inches (1311.2 cm<sup>3</sup>). This is more than twice the payload volume of the 1.437 inch diameter (3.65 cm) instrumented dart which is currently being used. Either a 1680 mc/GMD-(x) or a 403 mc/SMQ-1 sonde can be used with the proposed dart depending upon ground-station equipment. SDC is currently manufacturing both kinds of sondes for the USAF, PMR and WSMR and the Navy, respectively. Descent rates of the sonde system can be slowed to 230 fps (70.1 m/sec) at 61 km with a Super Loki system ( $\frac{W}{CDA}$  = 0.015 lb/ft<sup>2</sup>), or 0.073 kg/m<sup>2</sup>. Advantages of the Super Loki two-inch (5.08 cm) Instrumented Dart over the current Loki 1.437 (3.65 cm) inch Instrumented Dart are presented in Table 10.1.





FIGURE 10.1

## TABLE 10.1

## COMPARISON OF THE SUPER LOKI 5.08 CM INSTRUMENTED DART SYSTEM WITH THE CURRENT 3.65 CM INSTRUMENTED DART SYSTEM

Super Loki	Standard Loki
System	System
85 km	63 km
2.0 in (5.08 cm)	1.437 in (3.65 cm)
80 cu in.	33 cu. in.
(1311.2 cm <sup>3</sup> )	(540.9 cm <sup>3</sup> )
67 cu in.	20 cu in.
(1098.1 cm <sup>3</sup> )	(327.8 cm <sup>3</sup> )
0.073 kg/m <sup>2</sup>	0.146 kg/m <sup>2</sup>
(0.015 lb/ft <sup>2</sup> )	(0.030 lb/ft <sup>2</sup> )
70.1 m/sec	100.6 m/sec <sup>2</sup>
(230 ft/sec)	(330 ft/sec)
Not Required	Required
	Super Loki <u>System</u> 85 km 2.0 in (5.08 cm) 80 cu in. (1311.2 cm <sup>3</sup> ) 67 cu in. (1098.1 cm <sup>3</sup> ) 0.073 kg/m <sup>2</sup> (0.015 lb/ft <sup>2</sup> ) 70.1 m/sec (230 ft/sec) Not Required

An inflatable falling sphere payload has been suggested by the Army personnel at White Sands Missile Range for use with the existing chaff dart design. Since altitudes of 125 km were obtained at White Sands, reasonably good density data may be derived with the Robin falling sphere payload to altitudes below 90 km with the Super Loki. Since the apogee altitude for a sea level launch will only be about 113 km, the falling sphere density data may be restricted to a maximum altitude of 85 km for sea level sites.

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