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DLANET - A DIGITAL COMPUTER PROGRAM

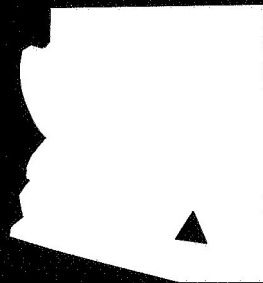
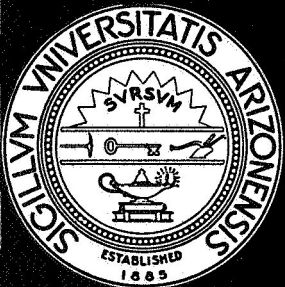
FOR THE ANALYSIS OF DISTRIBUTED-

LUMPED-ACTIVE NETWORKS

Prepared under Grant NGL-03-002-136 for the
Instrumentation Division of the Ames Research Center
National Aeronautics and Space Administration

by

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Abstract:- This report describes DLANET, a digital computer program for the analysis of Distributed-Lumped-Active NETworks, i.e., networks comprised of elements which are distributed, lumped, or active in nature. The program determines the sinusoidal-steady-state response of such a network over a prescribed frequency range. A subprogram is included to provide plots of the resulting magnitude and phase characteristics. A range of options are available to specify the taper of the distributed elements, select linear or logarithmic scales, produce punched card output, etc.

November 1968

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I. INTRODUCTION

This is one of a series of reports concerning the use of digital computational techniques in the analysis and synthesis of DLA (distributed-lumped-active) networks. This class of networks consists of three distinct types of elements, namely, distributed elements (modeled by partial differential equations), lumped elements (modeled by algebraic relations and ordinary differential equations), and active elements (modeled by algebraic relations). Such a characterization is especially applicable to the broad class of circuits referred to as linear integrated circuits, since the fabrication techniques for such circuits readily produce elements which may be referred to as "distributed", as well as producing elements which may be characterized as "lumped" or "active". The DLA class of networks is capable of realizing network functions with a wide range of properties. In addition, such realizations usually have fewer components and superior characteristics to realizations using only lumped elements or realizations using lumped and active elements. The analysis problem for the DLA class of networks, however, is considerably more complex than that for more restricted classes of networks. One of the more fruitful approaches to the analysis problem is that afforded by the digital computer. In this report, the results of such an approach are documented. Specifically, the report will describe the operation and use of the digital computer program DLANET, a program designed to make sinusoidal-steady-state analyses of DLA networks. The distributed elements will be restricted to being resistive and capacitive in behavior, since such elements most closely model those realized by integrated circuit techniques. The program is quite general and is easily extended to other network situations.

II. THEORY OF OPERATION

One of the major problems encountered in analyzing DLA networks is the problem of adequately modeling the distributed elements. An attractive approach to the modeling of such elements is the use of iterative techniques. Such an approach has the advantage that it is readily adaptable both to the uniform distributed element and to the tapered distributed element. Furthermore, the modeling is independent of the mathematical form of the taper, i.e., the taper need not be simply described. Since solutions to relatively simple tapers can be quite involved mathematically (for example, Bessel functions are required in the solution for linearly tapered distributed elements), this advantage can be of considerable importance.

The model which was chosen for the distributed elements for the program described in this report is a cascade of lumped RC "L" sections. A typical section is shown in Fig. 1. Assuming that this is the "kth" section, it may be considered as a two-port network, and voltage and current variables defined as indicated. Under conditions of sinusoidal steady-state excitation, the equations describing such a section may be written in the form

$$x_k = TD_k x_{k+1} \quad (1)$$

where

$$\begin{aligned} x_k &= \begin{bmatrix} V_k \\ I_k \end{bmatrix} & x_{k+1} &= \begin{bmatrix} V_{k+1} \\ I_{k+1} \end{bmatrix} \\ TD_k &= \begin{bmatrix} 1 + j2\pi f C_k R_k & R_k \\ j2\pi f C_k & 1 \end{bmatrix} \end{aligned} \quad (2)$$

and f is the frequency in Hz. The square matrix TD_k gives the transmission parameters of the k th section of the model for the distributed line. The transmission parameters of the overall distributed element may thus be represented as the product of the transmission parameters of the cascaded sections. If there are n such sections and if we let TD be the matrix of transmission parameters with elements td_{ij} for the overall distributed element, we may write

$$TD = \begin{bmatrix} td_{ij} \end{bmatrix} = TD_1 \times TD_2 \dots TD_n \quad (3)$$

Thus we have obtained a set of two-port parameters which model a distributed RC network.

Since the distributed element, in general, will be combined with lumped and active elements to form a DLA network, a more appropriate set of parameters to describe it is the admittance or y parameters. If we let YD be the 2×2 matrix containing the y parameters of the distributed network, we may express YD in terms of the elements td_{ij} of the TD matrix of (3) as

$$YD = \begin{bmatrix} yd_{ij} \end{bmatrix} = \frac{1}{td_{12}} \begin{bmatrix} td_{22} & -1 \\ -1 & td_{11} \end{bmatrix} \quad (4)$$

Finally, to facilitate an even greater generality of interconnection, it is most useful to generate the indefinite admittance parameters of the distributed element. If we let YDI be the 3×3 matrix with elements yd_{ij} containing the indefinite admittance parameters of the distributed element, we may express it in terms of the elements yd_{ij} of (4) as

$$\begin{aligned} YDI &= \begin{bmatrix} ydi_{ij} \end{bmatrix} \\ &= \begin{bmatrix} yd_{11} & yd_{12} & -yd_{11} - yd_{12} \\ yd_{21} & yd_{22} & -yd_{21} - yd_{22} \\ -yd_{11} - yd_{21} & -yd_{12} - yd_{22} & yd_{11} + yd_{12} + yd_{21} + yd_{22} \end{bmatrix} \end{aligned} \quad (5)$$

Thus, if we select d quantities R_i and d quantities C_i and a specific frequency f , we can calculate the indefinite admittance matrix for a distributed element under conditions of sinusoidal steady-state excitation at that frequency. The effect of choosing various values of d , i.e., using a model with different numbers of lumped sections has been discussed in a previous report.¹

The next step in the analysis of the DLA network is to interconnect the distributed element (or elements) with the specified lumped and active elements, and to solve the resulting network for the desired transfer function. The interconnection of the distributed and lumped elements is readily accom-

plished by adding their admittance parameters. The resulting parameters can then be constrained to include the effect of the active elements. Finally, the equations represented by the constrained parameters may be solved by conventional techniques. These steps are now discussed in detail.

We shall begin our discussion by considering the use of an interconnection network consisting of $n + 1$ nodes. For convenience we shall take node 1 as the input node, node 2 as the output node, and node $n + 1$ as the reference (ground) node. Thus, we will consider the interconnection network shown in Fig. 2 as the basic framework into which the various distributed, lumped, and active elements are to be imbedded. The (definite) admittance matrix describing an interconnection network of the type shown in Fig. 2 is simply an $n \times n$ null matrix. Thus, the effect of connecting a distributed network with admittance parameters as determined by the 3×3 matrix YDI to a set of any three terminals of the interconnection network is simply to add the elements of YDI to the appropriate elements of the $n \times n$ null matrix representing the interconnection network. Similarly, the effect of any lumped elements may be represented by adding the conductance (for resistors) or the susceptibility (for capacitors) to the appropriate elements of the admittance matrix. The resulting matrix, giving the combined effect of the distributed and lumped elements will be referred to as Y_T (for Y Total).

The next step in our analysis of the DLA network is to modify the parameters of the network of distributed and lumped elements to take account of the active elements. For simplicity, we shall consider the effect of connecting a VCVS (voltage-controlled voltage source) of gain $1/A$ from node n to node 2 of the interconnection network as shown in Fig. 3. The effect of such a source is to reduce the $n \times n$ array of the matrix Y_T to a $(n - 1) \times (n - 1)$ array, by reason of the constraint equation $V_2 = (1/A)V_n$ imposed on the network variables. Let Y_C be the $(n - 1) \times (n - 1)$ constrained array with elements $y_{c_{ij}}$. It is easily shown that²

$$Y_C = [y_{c_{ij}}]$$

$$= \begin{bmatrix} y_{t_{11}} & y_{t_{12}} + Ay_{t_{1n}} & y_{t_{13}} & \cdots & y_{t_{1,n-1}} \\ y_{t_{31}} & y_{t_{32}} + Ay_{t_{3n}} & y_{t_{33}} & \cdots & y_{t_{3,n-1}} \\ y_{t_{41}} & y_{t_{42}} + Ay_{t_{4n}} & y_{t_{43}} & \cdots & y_{t_{4,n-1}} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ y_{t_{n1}} & y_{t_{n2}} + Ay_{t_{nn}} & y_{t_{n3}} & \cdots & y_{t_{n,n-1}} \end{bmatrix} \quad (6)$$

The matrix Y_C interrelates certain of the voltage and current variables of the interconnection network. Thus, we may write

$$\begin{bmatrix} I_1 \\ I_3 \\ I_4 \\ \vdots \\ I_n \end{bmatrix} = [y_{c_{ij}}] \begin{bmatrix} V_1 \\ V_2 \\ V_3 \\ \vdots \\ V_{n-1} \end{bmatrix} \quad (7)$$

where the quantities I_i represent external excitation currents applied at the nodes of the interconnection network, and the quantities V_i are the nodal voltages. This procedure is easily generalized to include an arbitrary number of sources connected to any desired nodes, thus, the final size of the matrix YC will be $n - ng$, where ng is the number of VCVSs which are present in the network.

The final step in the analysis of the DLA network is the reduction of the $(n - ng) \times (n - ng)$ array YC to a 2×2 array from which the voltage transfer function of the network may be computed. To do this, we may note that since node 1 has been selected as the input node, only the current I_1 in the column vector on the left of (7) will be non-zero. Therefore, by simple matrix algebraic relations,³ if we write YC in the form

$$\begin{matrix} & & (n-ng-1) \text{ cols} \\ & YC & \\ (n-ng) \times (n-ng) & = & \left[\begin{array}{c|c} Y_{aa} & Y_{ab} \\ \hline Y_{ba} & Y_{bb} \end{array} \right] \begin{matrix} (n-ng-1) \text{ rows} \end{matrix} \end{matrix} \quad (8)$$

Then, we may write

$$\begin{matrix} & YC \\ (n-ng-1) \times (n-ng-1) & = Y_{aa} - Y_{ab} Y_{bb}^{-1} Y_{ba}. \end{matrix} \quad (9)$$

Equation (9) is easily programmed for the digital computer and avoids the need for a matrix inversion operation. Successive applications of (9) may be used to reduce the equations of (7) to those defining a two-port. These will be in the form

$$\begin{bmatrix} I_1 \\ 0 \end{bmatrix} = Y \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} \quad (10)$$

where Y is the 2×2 matrix with elements y_{ij} defining the two-port network. From the y_{ij} two-port parameters of (10), any desired network transfer function may be specified, for example, for the open-circuit voltage transfer function we obtain

$$\frac{V_2}{V_1} = \frac{-y_{21}}{y_{22}} \quad (11)$$

The algorithms for generating the parameters of the distributed element and for interconnecting the distributed, lumped, and active elements are readily programmed for the digital computer to produce a tabulation (or a plot) of the magnitude and phase of the voltage transfer function of the specified DLA network as a function of frequency. In the following section of this report, the operation of the program DLANET containing these algorithms is described.

III. THE DLANET PROGRAM - GENERAL CHARACTERISTICS

The DLANET program is a digital computer program written in FORTRAN IV and designed to provide a wide variety of options and features in the sinusoidal steady-state analysis of DLA networks, and in the display of the resulting data. It has been developed for a CDC-6400 computer but it is relatively machine independent. It is suitable for use on a wide range of

medium to large size computers. The program consists of a main program and a series of subprograms. A list of the name and function of each of the subprograms follows:

DISRP - a subroutine designed to read the data defining the distributed networks and to compute the values of the resistors and capacitors used to determine the lumped models for them. Options are provided to permit the specification of uniform, exponential, polynomial, or arbitrary taper.

XL4 - a function designed to provide a sequence of logarithmically spaced numbers. Thus it can be used to generate the values of frequency needed for plots in which the frequency scale is logarithmic rather than linear.

YDIST - a subroutine designed to compute the admittance parameters of the distributed networks, using the values of lumped resistors and capacitors determined by DISRP, and whatever value of frequency is desired. The subroutine also stores the parameters in the appropriate elements of the admittance matrix for the entire DLA network.

CONST - a subroutine designed to constrain the admittance matrix for the DLA network in such a way as to include the effects of the VCVS active elements in a manner similar to that shown in (6).

CMRED - a subroutine designed to reduce the order of the admittance matrix for the DLA network to 2×2 size, using the algorithm given in (9), thus, in effect providing a solution to the network equations.

PLOT - a subroutine designed to plot the magnitude and phase values which have been determined for each of the frequencies at which the program has been run.

The main program links the subprograms described above together in such a way as to provide the desired steady-state analysis capability for DLA networks. A flow chart of the main program is given in Fig. 4. This indicates the way in which the various subroutines are incorporated into the logic used in the program. It is readily verified that this flow chart follows the general theory outlined in Sec. II of this report.

The capabilities of the program DLANET are determined mainly by the dimensioning of the various variables. For the dimensioning given in the program listing included with this report, DLANET has the following maximum limits:

- Number of network nodes (not including the reference node) - 14
- Number of distributed networks - 5
- Number of sections permitted for each distributed network - 50
- Number of lumped elements - no limit
- Number of gain elements of VCVS type - 5

Several options and features are provided to make the program as flexible as possible for the user. These are:

1. A descriptive title is printed at the head of all output data listings and plots.
2. The frequencies at which the DLA network is to be analyzed are determined by specifying the lower and upper frequencies, the number of intermediate frequencies at which computation is desired, whether the frequency scale is to be linear or logarithmic, and whether the frequencies are specified in Hz or rad/sec.
3. The user may choose to suppress all plotting, to plot only the magnitude of the voltage transfer function, or to plot both the magnitude and the phase. To keep the size of the program reasonable, the plotting

subroutine has been simplified so that no internal scaling of data is provided. Thus, the user must select the necessary scale factor to be used in multiplying the magnitude and phase data as well as the maximum value of the ordinate desired on each of the plots.

4. The magnitude of the voltage transfer function is computed and expressed both as an actual magnitude and also in decibels. Either of these values may be used for the plot.

5. Uniform distributed networks may be computed by specifying the total resistance and capacitance, and the desired number of sections.

6. Exponential taper distributed networks may be computed by specifying the number of sections, and the initial values of the resistance and the capacitance and the taper. As an alternative, the taper may be computed by specifying the initial and final values of the capacitance or the resistance.

7. Polynomial taper distributed networks may be modeled by specifying the number of sections, the initial values of the resistance and the capacitance, the length of the lines, and the coefficients of the polynomial determining the taper. Up to 10 polynomial coefficients may be used, and these may be different for each of the distributed networks.

8. Arbitrarily tapered distributed networks may be modeled by reading in the actual values of the resistors and the capacitors for each section of the network.

9. An output listing is provided for each computation giving the values of frequency (in Hz and rad/sec), the magnitude of the voltage transfer function (in linear measure and in decibels) and the phase in degrees (if phase determinations are desired). As a convenience, punched card output of this data may also be requested.

10. Since the modeling of the distributed network parameters may be time consuming if many lumped network sections are used to model the distributed element, a provision is included which makes it possible to make only one computation of the distributed network parameters at a given frequency, and to use this data for all other distributed networks (assuming that they are identical).

11. The program includes a multiple-case option, in which, after the voltage transfer function has been computed for a range of frequencies, values of the parameters may be changed, and the computation repeated for the new parameter values. If desired, the user may choose to read in only selected parameter values rather than repeating all reading and computing operations. The data from these multiple cases may be plotted on the same plot, using the character A to represent the locus for the first set of data, the character B to represent the locus for the second, etc. Up to five simultaneous plots may be displayed.

Details of these and other features and options of the program are described more fully in the following sections of this report.

IV. THE DLANET PROGRAM - DETAILS OF OPERATION

In this section of the report, the details of the operation of the various portions of the DLANET digital computer program for the sinusoidal steady-state analysis of DLA networks is presented. In studying this material, reference should be made to the flow charts and listings presented in the Appendix of this report.

The main program, and the subroutines DISRP, YDIST, CONST, and CMRED described in the preceding section are linked through the use of commoned variables. A listing and description of these variables and their dimen-

sioning follows:

- YR(15,15) - This is a complex array in which are stored the values of the admittance parameters which have been computed at some specific value of frequency for the DLA network. These values are read in ohms, and are converted to mhos before storage in the array.
- R(15,15) - A real array in which is stored the admittance parameters of the resistive lumped elements which are used in the DLA network. These values are read in ohms, and are converted to mhos before storage in the array.
- C(15,15) - A real array in which is stored the values of the admittance parameters of the capacitive elements (without being multiplied by frequency) of the DLA network. The units are farads.
- RD(5,50) - A real array in which are stored the values of the series resistors used in the lumped approximation to the distributed RC networks. These are stored as RD(I,J) where I is the number of the distributed network and J is the number of the lumped section.
- CD(5,50) - A real array in which are stored the values of the shunt capacitors used in the lumped approximation for the distributed networks. These are stored as CD(I,J) where I is the number of the distributed network and J is the number of the lumped section.
- NSECT(5) - The number of sections to be used to approximate distributed networks 1 - 5.
- N1(5) - The numbers of the nodes to which the $x = 0$ end of the resistive layers of distributed networks 1 - 5 are connected.
- N2(5) - The numbers of the nodes to which the $x \neq 0$ end of the resistive layers of distributed networks 1 - 5 are connected.
- N3(5) - The numbers of the nodes to which the capacitive layers of distributed networks 1 - 5 are connected.
- NN - The number of nodes in the DLA network (not including the ground node).
- ND - The number of distributed networks in the DLA network.
- RAD - The value of the frequency variable in rad/sec.
- KD - An indicator giving the number of the distributed network whose admittance parameters are currently being computed by YDIST.
- NREP - A variable used to specify the repetition of all or certain portions of the main DLANET program so as to provide a multiple case capability.
- NGAIN - The number of VCVS gain elements.
- NG1(5) - The numbers of the nodes to which the positive polarity end of the source portion of VCVSs 1 - 5 are connected.
- NG3(5) - The numbers of the node voltages which control VCVSs 1-5.
- JL(5) - The number of the nodes which it is desired to eliminate in applying the constraints imposed by VCVSs 1 - 5.
- GA(5) - The value of the gains of VCVSs 1 - 5.

These variables will be referred to in the description of the operation of the various subprograms of the DLANET program which follows:

SUBROUTINE DISRP

This subroutine reads and prints the data for the distributed networks. All input and output variables are in common. It goes through ND cycles.

On the I th cycle it will read the values of NOPT, an indicator which determines the type of taper and must have a value from 1 - 4, NSECT(I), N1(I), N2(I), and N3(I). The values of RD(I,J) and CD(I,J) are computed for values of J from 1 to NSECT(I). If NOPT = 1 (a uniform network), values of RT (the total resistance) and CT (the total capacitance) are read, divided by the number of sections, and stored in RD and CD. If NOPT = 2 (an exponential network), the user may specify RA (the initial resistance), CA (the initial capacitance), and ALFA (the taper coefficient), after which the lumped values of resistance and capacitance are computed to match the relations

$$r(x) = r_a e^{\alpha x/d} \quad c(x) = c_a e^{-\alpha x/d} \quad (12)$$

where d is the total length of the line, and stored in RD and CD. If ALFA is read in as zero, then it will be computed from the values of RA and RB (the final resistance). If RB is read in as zero, ALFA will be computed using CA and CB (the final capacitance). If NOPT = 3 (a polynomial taper), NP (the number of polynomial coefficients), RI (the initial resistance), CI (the initial capacitance) and XT (the total length of the line) are read in, as are the NP coefficients P(I). The lumped resistors and capacitors are then computed to match the relations

$$r(x) = r_i (1 + p_1 x + p_2 x^2 + \dots) \quad c(x) = c_i / (1 + p_1 x + p_2 x^2 + \dots) \quad (13)$$

and stored in RD and CD. If NOPT = 4 (arbitrary taper), the values of RD and CD are read in directly.

FUNCTION XL4 (N, LO, LP)

This function uses a counter N to keep track of the number of logarithmically spaced frequency values which have been generated. This counter is advanced by 1 after each call of the function. It is set to 1 (variable NLG) in the main program before the first call of the function. The function generates LP logarithmically spaced numbers per decade starting with a value (corresponding to $N = 0$) equal to the antilogarithm of LO. The calling arguments used in the main program for LP and LO are NG and LOG1.

SUBROUTINE YDIST

This subroutine computes the admittance parameters for the distributed networks and stores them in the YR array. All input and output variables are in common. The values stored in RD and CD, and the current value of RAD is used to compute the transmission parameters of each section of the distributed network model. The complex 2×2 arrays AR, BR, and CR are used to store the transmission parameters during matrix multiplication. The final values of the transmission parameters are converted to the complex y parameters DR, ER, and GR, and these are entered as appropriate elements of the YR array according to the values specified for N1, N2, and N3. If NSECT(I) = 0, then the previously computed values of DR, ER, and GR are used, thus, the recomputation of the admittance parameters for identical distributed networks is eliminated by specifying NSECT(I) = 0 for any distributed network except the first ($I = 1$).

SUBROUTINE CONST

This subroutine constrains the YR array to take account of the effect of the VCVSs. All input and output variables are in common. It uses two arrays of indicators NRE(I) and NCE(I) which are initialized to zero, then set to unity for each row and column that is to be eliminated from the YR array. The rows that are eliminated are those corresponding with the nodes

at which VCVSs are connected. The columns that are eliminated are those associated with either the controlling node voltage or the node at which the source is located. Before eliminating the specified columns, the constraining operations are made, i.e., the column to be eliminated is added to the column which is not eliminated after first being multiplied or divided by the gain of the source. It should be noted that the data must not specify that a given column be eliminated more than once. In addition, the order in which the data for the sources is read into the program must be such that no operations are made on a column after it has been eliminated. For example, consider the cascade of sources shown in Fig. 5a. If it is desired to eliminate nodes a and b, then the data for source A must be entered before the data for source B. On the contrary, if it is desired to eliminate nodes b and c, then the data for source B must be entered before that for source A. If nodes a and c are to be eliminated, the order in which the data is entered is arbitrary. Similar conclusions hold for a parallel connection of sources as shown in Fig. 5b. If nodes a and c are to be eliminated, then the data for source A must be entered before that for source B. If nodes a and b are to be eliminated, then the data for source B must be entered before that for source A. Finally, if nodes b and c are to be eliminated, the order in which the data is entered is arbitrary.

SUBROUTINE CMRED

This subroutine reduces the YR array to a 2×2 array using the algorithm described in (9). All input and output variables are in common.

SUBROUTINE PLOT (Y, M, NS, NS)

This subroutine provides a plot of the data stored in the two dimensional Y array. The variable $Y(I,J)$ is used to store the Jth value of the Ith variable that it is desired to plot. The dimensions on the Y array are (5,100), thus, up to 100 values of each of five variables can be plotted. The argument M specifies the number of variables that are to be plotted. This argument must have a value from 1 to 5. The argument NF specifies the number of values of each variable that are to be plotted. This argument is normally set to some multiple of 10 between 10 and 100. If it is desired to contain the plot on a single page, NF should be set to 50. The argument NS determines the maximum value of the ordinate scale that is desired. The minimum value of the scale is automatically set to 100 units lower, thus, the data which is to be plotted must be scaled so as to fit within this range. The arguments listed above are automatically determined by the input data to the main program. In the main program the Y array is used to store the magnitude data and the Z array is used to store the phase data. Thus, if both magnitude and phase plots are desired, the subroutine PLOT is called twice, once to plot the data stored in the Y array, and a second time to plot the data stored in the Z array. A detailed description of the operation of this subroutine may be found in the literature.⁴

MAIN PROGRAM

The operation of the main program follows quite closely the general outline given in Fig. 4. The multiple-case feature provided in DLANET, however, may be better understood by examining the extended flow chart shown in Fig. 6. This chart shows the use of the variable NREP in determining whether or not multiple cases are to be computed. If a blank card (NREP = 0) is used, then the entire program is repeated, and a complete

new set of data must be supplied. The same is true if NREP is read in as 4. If it is desired only to modify the values of the gains of the VCVSs, then NREP is read in as 1. In this case, after reading in the new values of the gains, the original frequency data is used to repeat the computations. If it is desired only to modify the distributed network characteristics, then NREP is read in as 2. In this case after reading in new data for the distributed networks, the original frequency data is used to repeat the computations. If it is desired only to modify the values of the lumped elements, then NREP is read in as 3. In this case, the values read in are superposed on the previous values, thus, to "remove" an element, the negative of the value originally read in must be specified, or, to change the value of an element, only the change should be read in. After all such changes are made, the original frequency data is used to repeat the computations. Finally, if no data card is provided for NREP, an EOF (end-of-file) is used as an indicator to proceed to the plotting portion of the program.

Detailed flow charts and listings of the main program and the sub-routines described above may be found in the appendix of this report.

V. EXAMPLE

As an example of the type of computations performed by this program, consider the network shown in Fig. 7. This network was originally discussed by Kerwin.⁵ To make a logarithmic frequency plot from 0.1 to 10 rad/sec of this network using a 5 section model for the distributed network, and to repeat the computation for a 10 section model, the data cards shown in Fig. 8 are required. The resulting computer output is shown in the following sheets, Figs. 9-13.

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Input Data Format for DLANET Program

<u>Card No.</u>	<u>Variable</u>	<u>Columns</u>	<u>Format</u>	<u>Purpose</u>
1	LTR	1-80	8A10	Alphanumeric identification for problem
2	NN	1-3	I3	Number of nodes (not counting reference node)
	ND	4-6	I3	Number of distributed elements
	NF	7-9	I3	Number of frequencies at which response is to be calculated
	NSY	10-12	I3	Maximum ordinate scale value for plot of magnitude response (minimum is 100 units lower)
	NSP	13-15	I3	Maximum ordinate scale for plot of phase response (minimum is 100 units lower)
	KRAD	16	I1	Indicator for units of frequency (1 is rad/sec, 0 is Hz)
	LMAG	17	I1	Indicator for magnitude units (0 is db, 1 is linear)
	LPHS	18	I1	Indicator for phase computation (0 is no, 1 is yes)
	KPLT	19	I1	Indicator for whether plot is desired (0 is yes, 1 is no)
	LFRQ	20	I1	Indicator for type of frequency scale (0 is linear, 1 is logarithmic)
	OLDG	21-30	E10.0	Gain of first voltage-controlled voltage source (used only if NGAIN (cols. 72-74) is set to zero)
	FA	31-40	E10.0	Lowest frequency desired
	FB	41-50	E10.0	Highest frequency desired

SCALE	51-60	E10.0	Scale factor for magnitude plot
SCALP	61-70	E10.0	Scale factor for phase plot
KPUN	71	I1	Indicator for punched output (0 is no, 1 is yes)
NGAIN	72-74	I3	Number of voltage-controlled voltage sources

Note: There will be NGAIN of the following cards required. An alternate data input may be used if there is only one VCVS and it is connected from node 3 to node 2. In this case set NGAIN (cols. 72-74) of card 2 to 0, enter the gain of the VCVS in cols. 21-30 (format E10.0) of card 2, and skip the following card (card 3).

3	NG1(I)	1-3	I3	Node at which the Ith VCVS is located) (the other terminal is assumed to be grounded)
	NG3(I)	7-9	I3	Node at which the controlling voltage for the Ith VCVS is located (taken with respect to ground)
	JL(I)	13-15	I3	Node (either NG1(I) or NG3(I)) that it is desired to eliminate in taking account of the constraining effect of the Ith VCVS.
	GA(I)	21-30	E10.0	Gain of the Ith VCVS

As many of the following cards may be used as are required:

4	I	1-2	I2	First node to which lumped element (or elements) is connected
	J	3-4	I2	Second node to which lumped element (or elements) is connected (0 if ground node)
	RA	11-20	E10.0	Value of resistance of lumped element in ohms connected from node I to node J (zero if no resistor)
	CA	21-30	E10.0	Value of capacitance of lumped element in farads connected from node I to node J (zero if no capacitor)

5 Blank card indicating the end of set of No. 4 cards

Note: There will be MD sets of the following cards Nos. 6-12:

6	NOPT	1-3	I3	Indicator for type of data describing Ith distributed network (1-linear taper, 2-exponential taper; 3-values of all sections read in; 4-polynomial taper)
	NSECT(I)	4-6	I3	Number of sections to be used in Ith distributed network (set to zero if data is same as for (I-1)th distributed network)
	N1(I)	7-9	I3	Number of node to which one end of resistive layer of Ith distributed network is connected (use NN+1 if this is the ground node)
	N2(I)	10-12	I3	Number of node to which other end of resistive layer of Ith distributed network is connected (use NN+1 if this is the ground node)
	N3(I)	13-15	I3	Number of node to which capacitive layer of Ith distributed network is connected (use NN+1 if this is the ground node)

If NOPT=1, the following card is required:

7	RT	1-10	E10.0	Total value of resistance of Ith distributed line
	CT	11-20	E10.0	Total value of capacitance of Ith distributed line

If NOPT=2, the following card is required:

8	ALF	1-10	E10.0	Value of the constant alpha used in exponential taper for Ith distributed line
	RA	11-20	E10.0	Resistance per unit length at N1(I) end of exponentially tapered distributed line

RB	21-30	E10.0	Resistance per unit length at N2(I) end of exponentially Ith tapered distributed line ($RB > RA$)
CA	31-40	E10.0	Capacitance per unit length at N1(I) end of exponentially tapered Ith distributed line
CB	41-50	E10.0	Capacitance per unit length at N2(I) end of exponentially tapered Ith distributed line ($CB < CA$)

Note: If $ALF \neq 0$, sectional R and C will be calculated using ALF, RA and CA; if $ALF=0$, but $RB \neq 0$, sectional R and C will be calculated using RA, RB and CA; if $ALF=0$ and $RB=0$, sectional R and C will be calculated using RA, CA, and CB.

If NOPT=3, the following cards are required:

9	RD(I,J)	1-80	8E10.0	Values of resistance of various sections of Ith distributed line ($J=1, NSECT(I)$)
10	CD(I,J)	1-80	8E10.0	Values of capacitance of various sections of Ith distributed line ($J=1, NSECT(I)$)

If NOPT=4, the following cards are required:

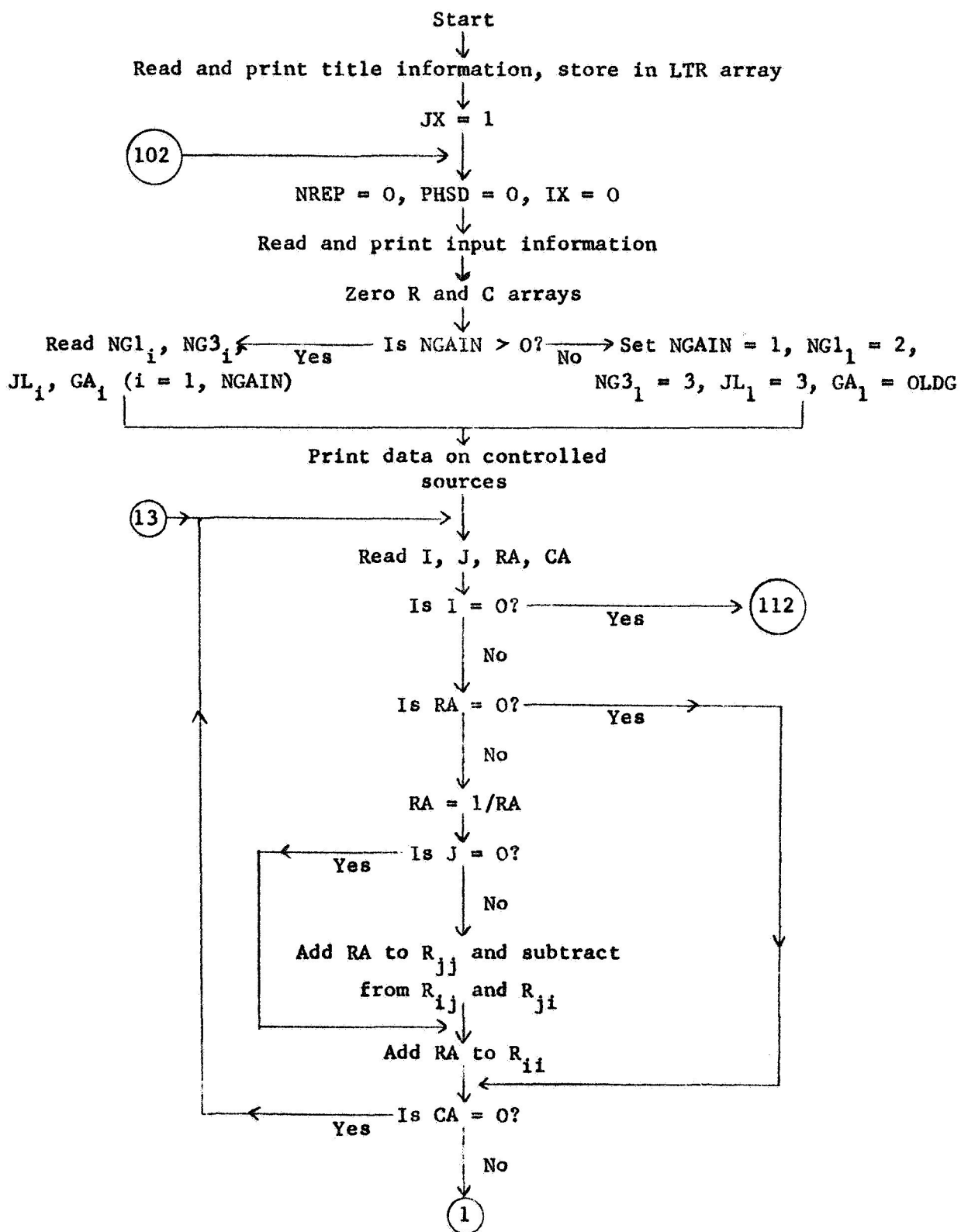
11	NP	1-3	I3	Degree of polynomial used in approximating taper of Ith distributed line (zero degree coefficient is assumed set to unity)
	RI	11-20	E10.0	Multiplier for polynomial expression for $r(x)$, i.e., initial resistance per unit length for Ith distributed line
	CI	21-30	E10.0	Multiplier for polynomial expression for $c(x)$, i.e., initial capacitance per unit length for Ith distributed line
	XT	31-40	E10.0	Total length of Ith distributed line, i.e., highest value of x
12	P(I)	1-80	8E10.0	Values of coefficients of polynomial expression $1 + p_1x + p_2x^2 + \dots$ for Ith distributed line ($I=1, NP$)

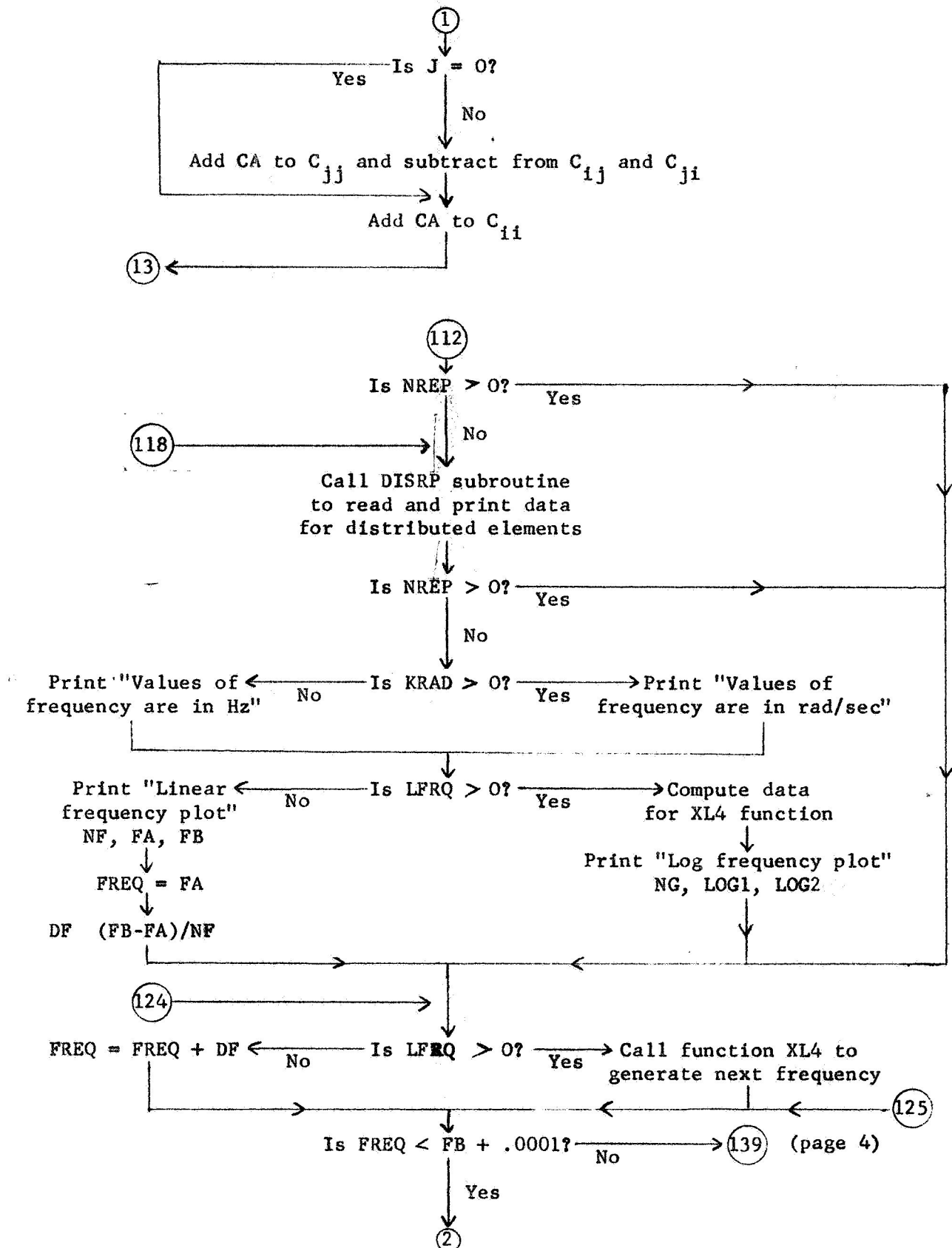
After the ND sets of cards specified above the following card is read:

13	NREP	-1-3	I3	Repetition indicator card
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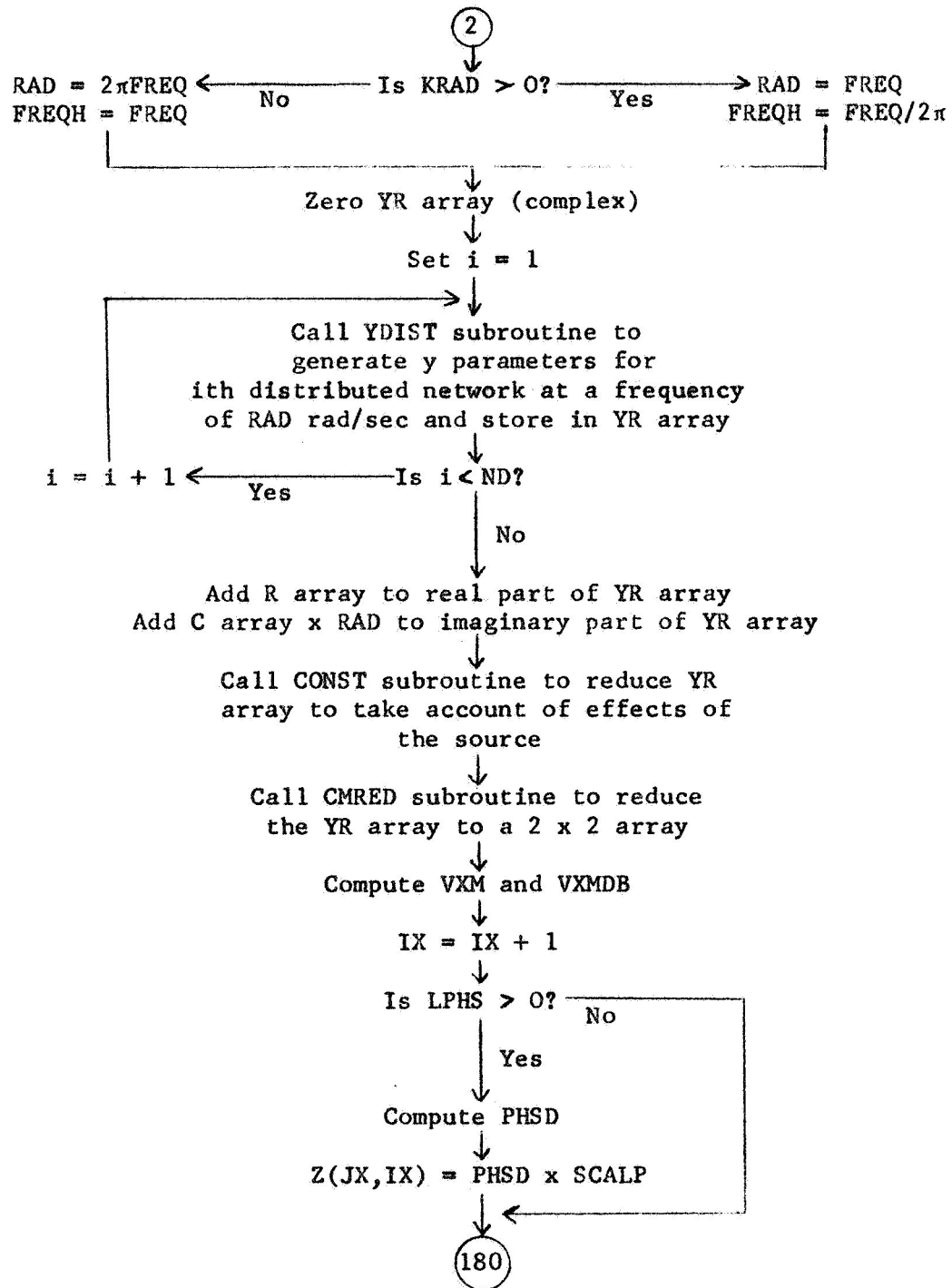
Note: If Card 13 is omitted, the program will plot the data after calculating the values for the first problem. No other data cards must be used in this case. The following other options are available: If NREP=1, the program will read new values of GA(I) (I=1,NGAIN), and repeat the frequency determination. (In this case a single data card is used to read GA(I) in format 8E10.0); if NREP=2, the program will re-read a set of ND groups of card Nos. 6-12 specifying the data for the distributed networks; if NREP=3, the program will read any data cards of type No. 4, until a blank card (No. 5) is encountered (such input will superpose itself upon the input for the lumped elements read on the first cycle of the program); if NREP=4, or if a blank card (NREP=0) is used, the entire read cycle will be repeated starting with card No. 2.

Flow Chart for DLANET Program

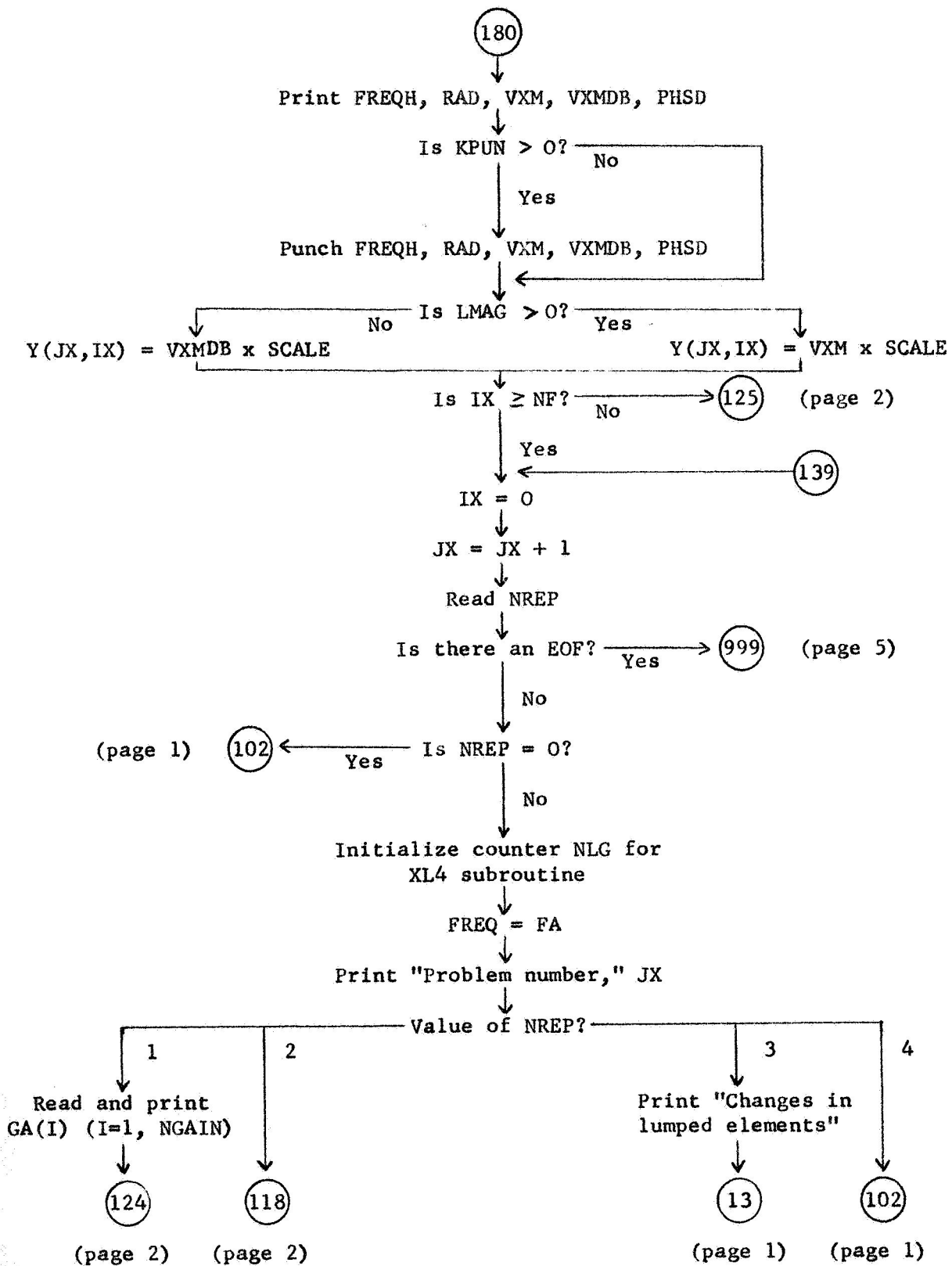




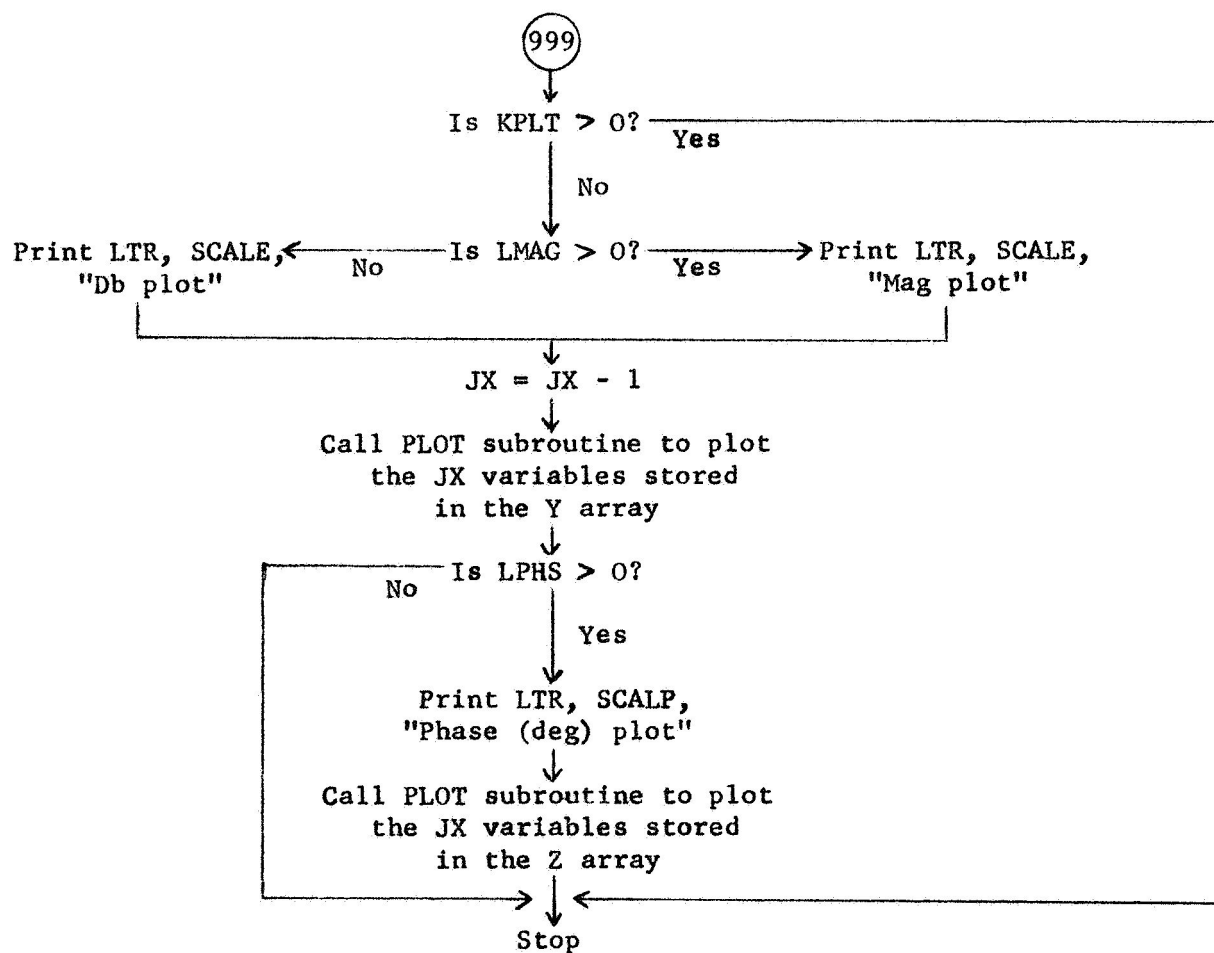
Flow Chart for DLANET Program (page 3)



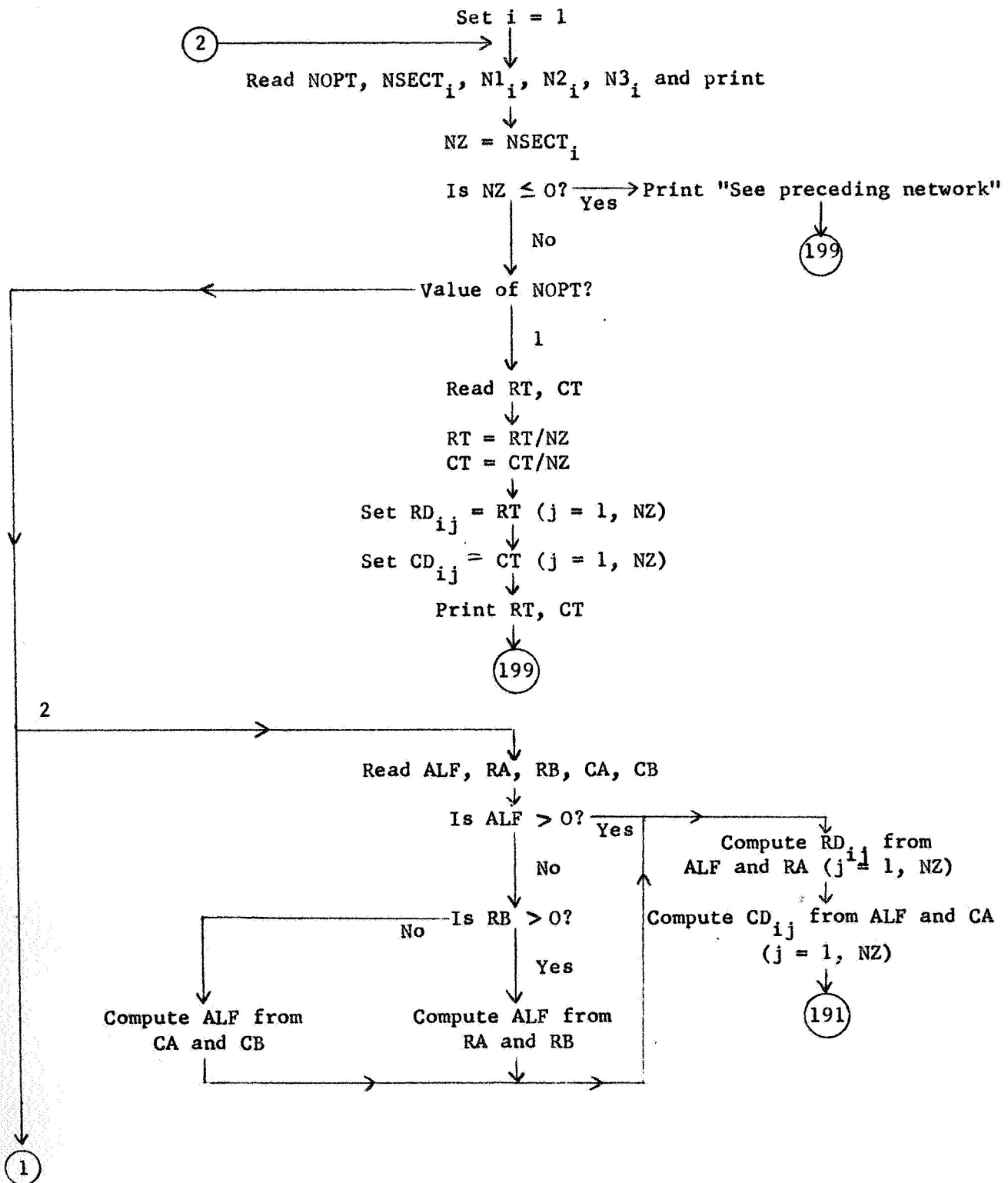
Flow Chart for DLANET Program (page 4)



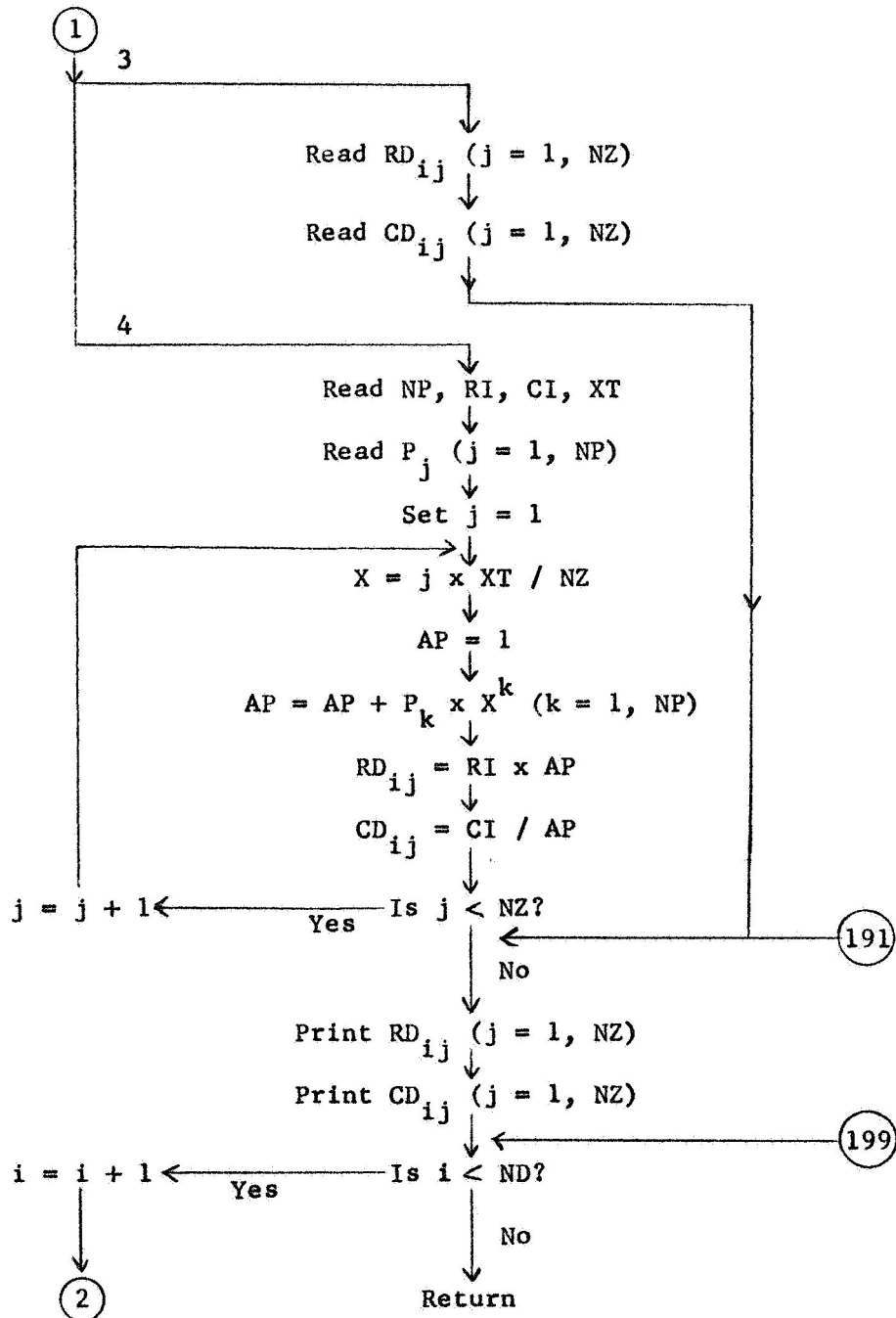
Flow Chart for DLANET Program (page 5)



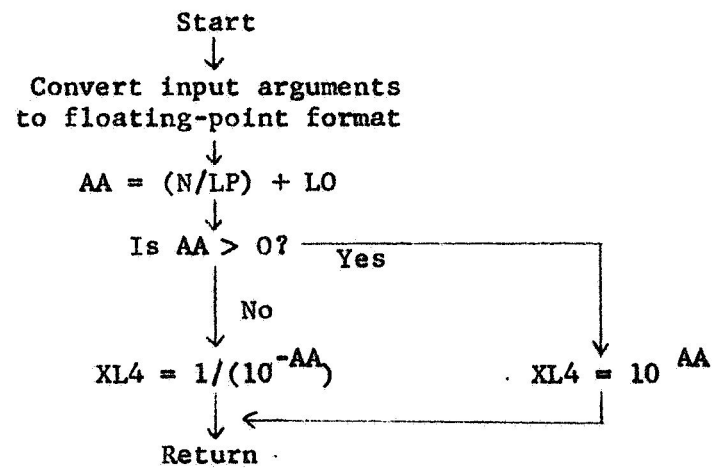
Flow Chart for DISRP subroutine



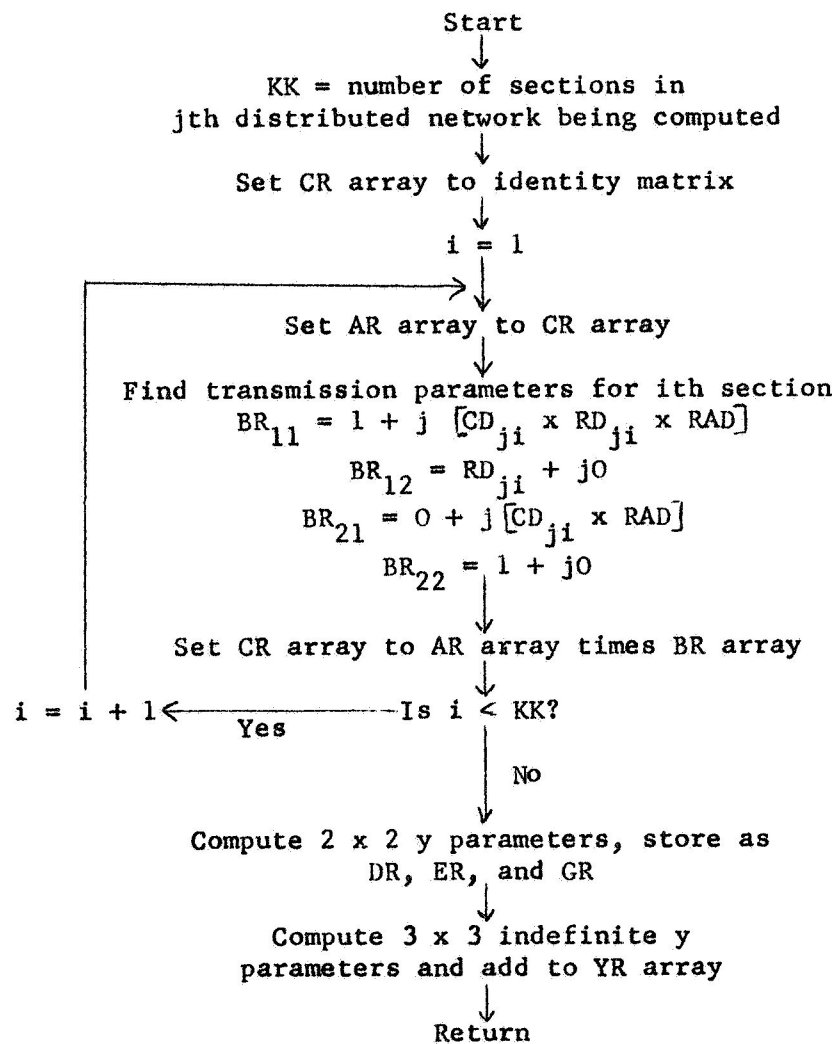
Flow Chart for DISRP subroutine (page 2)



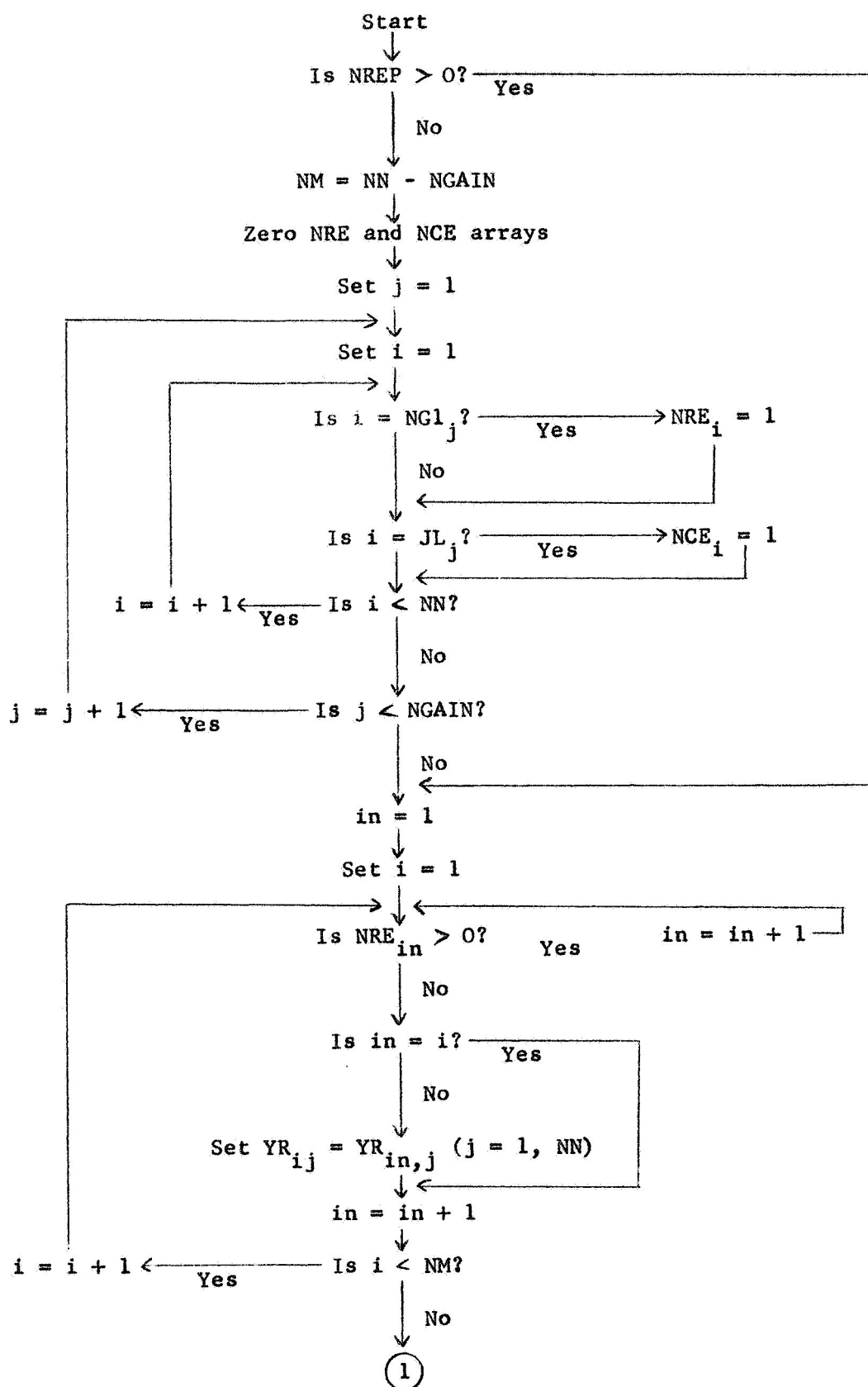
Flow Chart for XL4 Function



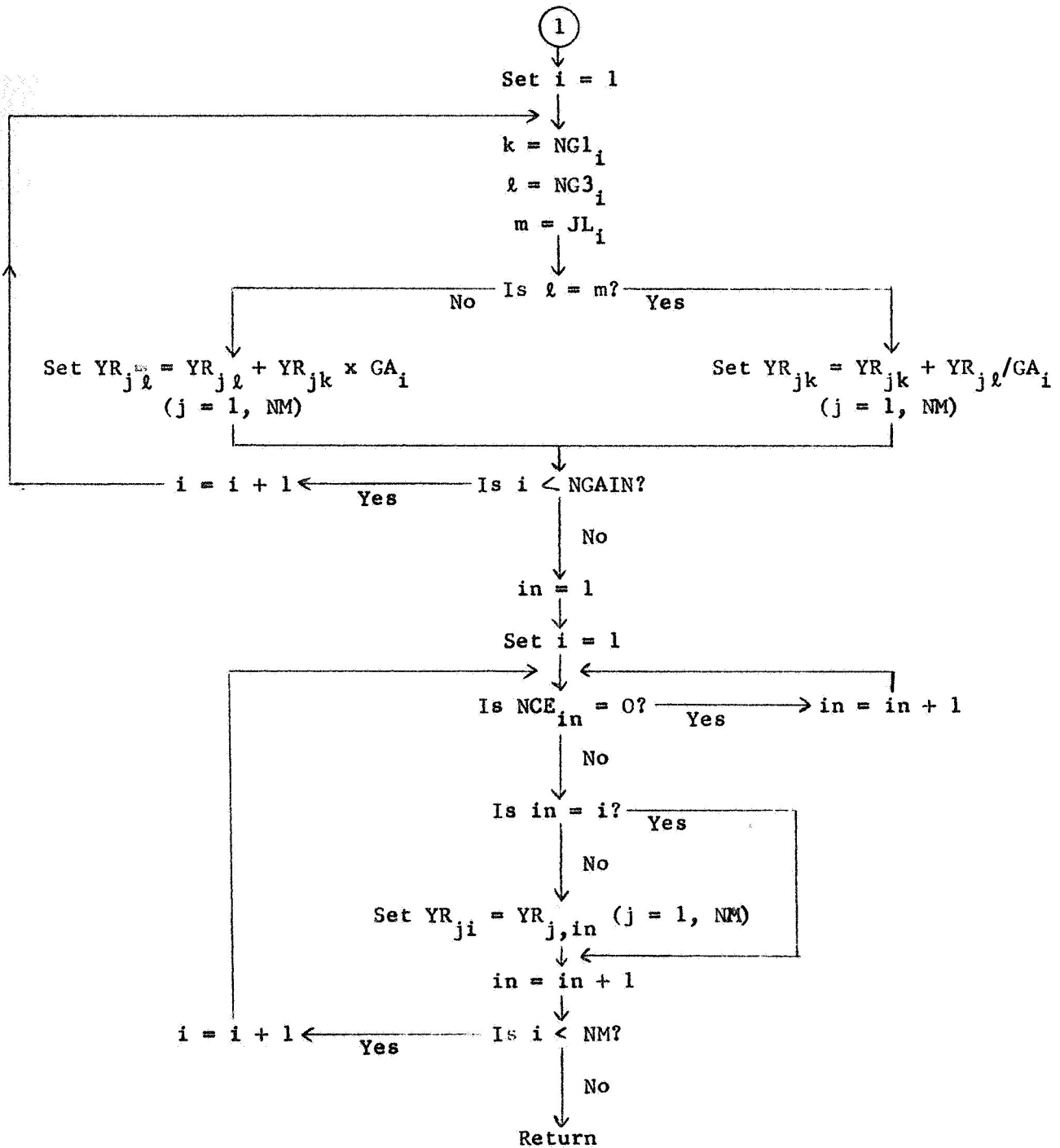
Flow Chart for YDIST subroutine



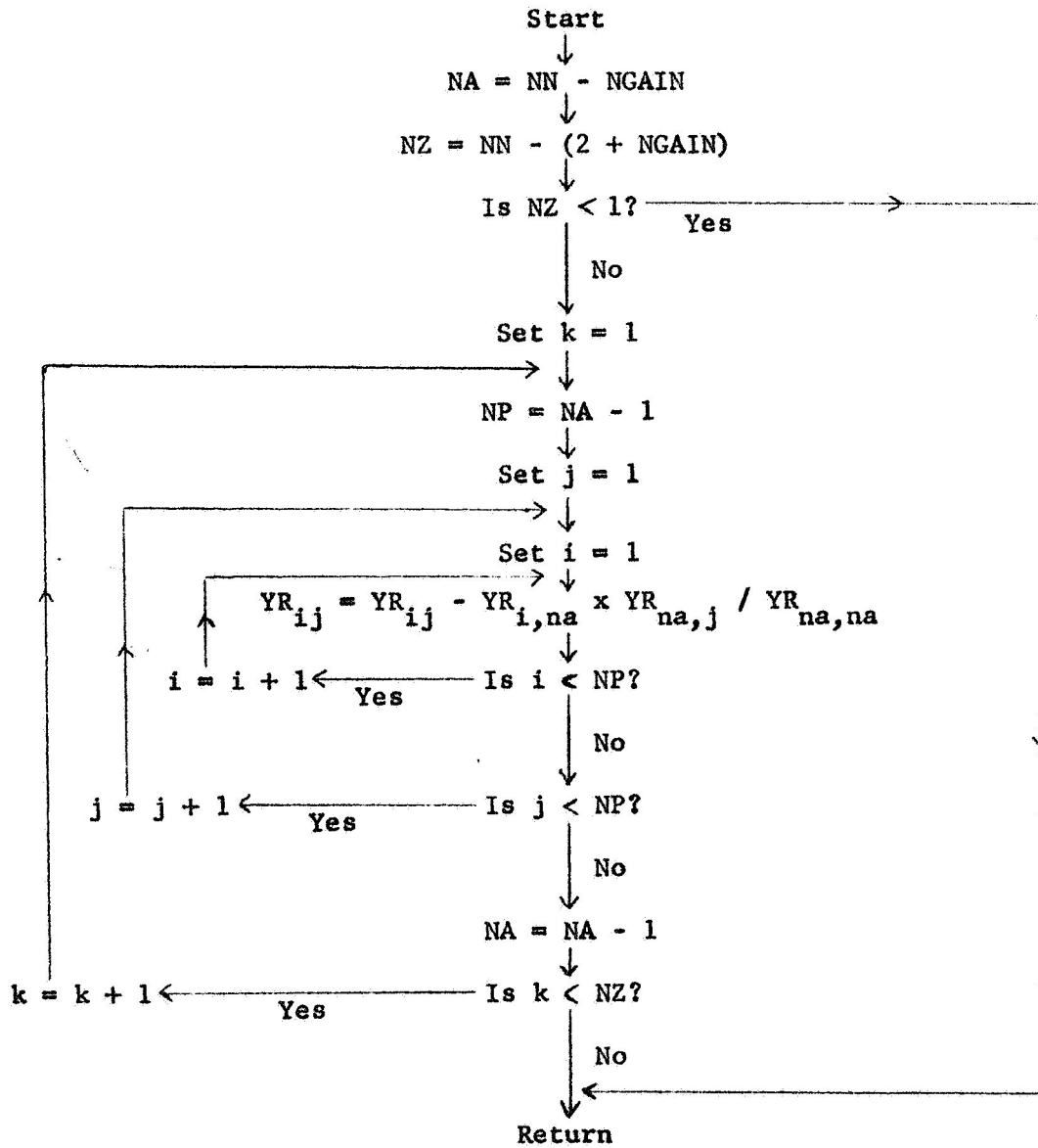
Flow Chart for CONST subroutine



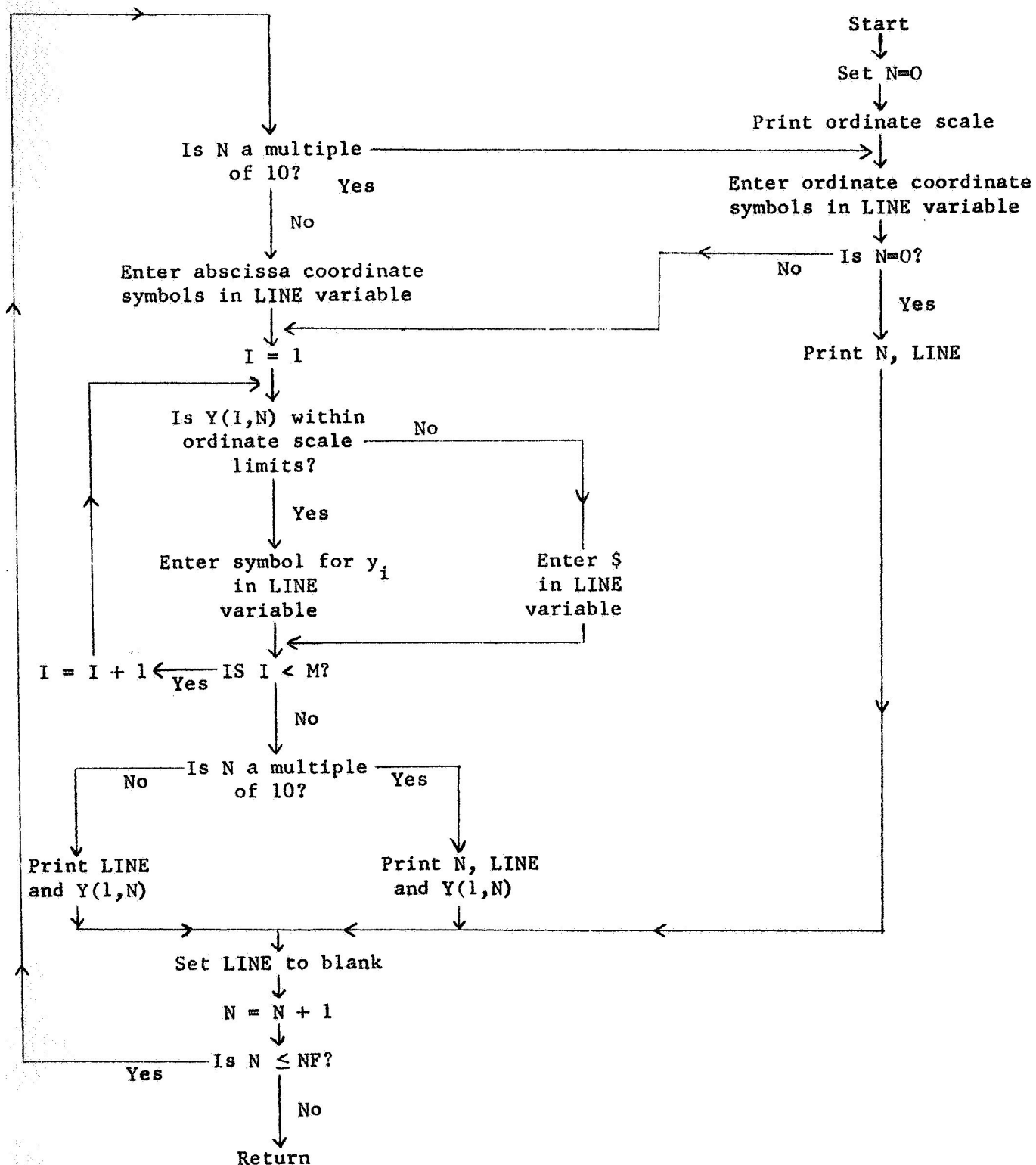
Flow Chart for CONST subroutine (page 2)



Flow Chart for CMRED Subroutine



Flow Chart for PLOT subroutine



FUNCTION XL4(N,LO,LP)	HUELSMAN
AN=N	HUELSMAN
ALO=LO	HUELSMAN
ALP=LP	HUELSMAN
AA=AN/ALP+ALO	HUELSMAN
IF (AA) 100,100,105	HUELSMAN
100 XL4=1./10.**(-AA)	HUELSMAN
GO TO 110	HUELSMAN
105 XL4=10.**AA	HUELSMAN
110 N=N+1	HUELSMAN
RETURN	HUELSMAN
END	HUELSMAN
SUBROUTINE PLOT (Y,M,NF,NS)	HUELSMAN
C SUBROUTINE FOR PLOTTING 5 X 100 INPUT ARRAY (FORTRAN 4)	HUELSMAN
DIMENSION Y(5,100), LINE(101),L(11),JL(5)	HUELSMAN
DATA (JL(I),I=1,5)/1HA,1HB,1HC,1HD,1HE/,JN,JP,JI,JBLANK,JZ/	HUELSMAN
11H-,1H+,1HI,1H ,1H\$/	HUELSMAN
DO 99 I=1,101	HUELSMAN
LINE(I)=JBLANK	HUELSMAN
99 CONTINUE	HUELSMAN
N=0	HUELSMAN
C PRINT ORDINATE SCALE	HUELSMAN
DO 101 I=1,11	HUELSMAN
L(I)=10*I-110+NS	HUELSMAN
101 CONTINUE	HUELSMAN
PRINT 105,(L(I),I=1,11)	HUELSMAN
105 FORMAT (3X,11(I4,6X),6HY(1,I))	HUELSMAN
GO TO 115	HUELSMAN
110 IF (N/10-(N-1)/10) 125,125,115	HUELSMAN
C CONSTRUCT ORDINATE GRAPH LINE	HUELSMAN
115 ND=0	HUELSMAN
DO 120 I=1,10	HUELSMAN
ND=ND+1	HUELSMAN
LINE(ND)=JP	HUELSMAN
DO 120 J=1,9	HUELSMAN
ND=ND+1	HUELSMAN
120 LINE(ND)=JN	HUELSMAN
LINE(101)=JP	HUELSMAN
IF (N) 135,121,135	HUELSMAN
121 PRINT 170,N,LINE	HUELSMAN
GO TO 185	HUELSMAN
C CONSTRUCT 1 LINE OF ABSCISSA GRAPH LINES	HUELSMAN
125 DO 130 I=1,101,10	HUELSMAN
LINE(I)=JI	HUELSMAN
130 CONTINUE	HUELSMAN
C CHANGE NUMERICAL DATA TO LETTERS	HUELSMAN
135 DO 160 I=1,M	HUELSMAN
XNS=NS	HUELSMAN
JA=Y(I,N)+101.49999-XNS	HUELSMAN
IF (JA-101) 140,155,145	HUELSMAN
140 IF (JA) 150,150,155	HUELSMAN
145 LINE(101)=JZ	HUELSMAN
GO TO 160	HUELSMAN
150 LINE(1)=JZ	HUELSMAN
GO TO 160	HUELSMAN
155 LINE(JA)=JL(I)	HUELSMAN
160 CONTINUE	HUELSMAN
C PRINT LINE OF DATA	HUELSMAN
IF (N/10-(N-1)/10) 175,175,165	HUELSMAN
165 PRINT 170,N,LINE,Y(1,N)	HUELSMAN

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170 FORMAT (1X,I4,101A1,1X, E12.5)
GO TO 185
175 PRINT 180,LINE,Y(1,N)
180 FORMAT (5X,101A1,1X,E12.5)
C SET LINE VARIABLES TO ZERO
185 DO 190 I=1,101
LINE(I)=JBLANK
190 CONTINUE
195 N=N+1
IF (N-NF) 110,110,200
200 RETURN
END
SUBROUTINE CMRED
COMMON YR(15,15),R(15,15),C(15,15),RD(5,50),CD(5,50),
1NSECT(5),N1(5),N2(5),N3(5),NN,ND,RAD,KD,NREP
2,NGAIN,NG1(5),NG2(5),NG3(5),NG4(5),JL(5),GA(5)
COMPLEX YR
NA=NN-NGAIN
NZ=NN-(2+NGAIN)
IF (NZ.LT.1) RETURN
DO 110 K=1,NZ
NP=NA-1
DO 105 J=1,NP
DO 105 I=1,NP
YR(I,J)=YR(I,J)-YR(I,NA)*YR(NA,J)/YR(NA,NA)
105 CONTINUE
110 NA=NA-1
RETURN
END
SUBROUTINE YDIST
COMMON YR(15,15),R(15,15),C(15,15),RD(5,50),CD(5,50),
1NSECT(5),N1(5),N2(5),N3(5),NN,ND,RAD,KD,NREP
2,NGAIN,NG1(5),NG2(5),NG3(5),NG4(5),JL(5),GA(5)
COMPLEX YR
COMPLEX AR(2,2),BR(2,2),CR(2,2),DR,ER,GR
KK=NSECT(KD)
IF (KK) 121,121,109
109 DO 112 I=1,2
DO 110 J=1,2
110 CR(I,J)=(0.,0.)
112 CR(I,I)=(1.,0.)
DO 120 I=1,KK
DO 115 IA=1,2
DO 115 IB=1,2
AR(IA,IB)=CR(IA,IB)
115 CONTINUE
BR(1,1)=CMPLX(1.,CD(KD,I)*RD(KD,I)*RAD)
BR(1,2)=CMPLX (RD(KD,I),0.)
BR(2,1)=CMPLX (0.,CD(KD,I)*RAD)
BR(2,2)=(1.,0.)
CR(1,1)=AR(1,1)*BR(1,1)+AR(1,2)*BR(2,1)
CR(1,2)=AR(1,1)*BR(1,2)+AR(1,2)*BR(2,2)
CR(2,1)=AR(2,1)*BR(1,1)+AR(2,2)*BR(2,1)
CR(2,2)=AR(2,1)*BR(1,2)+AR(2,2)*BR(2,2)
120 CONTINUE
DR=(1.,0.)/CR(1,2)
ER=DR*CR(2,2)
GR=DR*CR(1,1)
121 L=N1(KD)
M=N2(KD)

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N=N3(KD)	HUELSMAN
YR(L,L)=ER+YR(L,L)	HUELSMAN
YR(M,M)=GR+YR(M,M)	HUELSMAN
YR(L,M)=-DR+YR(L,M)	HUELSMAN
YR(M,L)=YR(L,M)	HUELSMAN
YR(N,L)=DR-ER+YR(N,L)	HUELSMAN
YR(L,N)=YR(N,L)	HUELSMAN
YR(N,M)=DR-GR+YR(N,M)	HUELSMAN
YR(M,N)=YR(N,M)	HUELSMAN
YR(N,N)=ER+GR-(2.,0.)*DR+YR(N,N)	HUELSMAN
RETURN	HUELSMAN
END	HUELSMAN
SUBROUTINE CONST	HUELSMAN
C LPH SUBROUTINE 235 REPLACES PERRY 233, JULY 1968	HUELSMAN
COMMON YR(15,15),R(15,15),C(15,15),RD(5,50),CD(5,50),	HUELSMAN
INSECT(5),N1(5),N2(5),N3(5),NN,ND,RAD,KD,NREP	HUELSMAN
2,NGAIN,NG1(5),NG2(5),NG3(5),NG4(5),JL(5),GA(5)	HUELSMAN
COMPLEX YR	HUELSMAN
DIMENSION NRE(15),NCE(15)	HUELSMAN
IF (NREP.GT.0) GO TO 121	HUELSMAN
NM=NN-NGAIN	HUELSMAN
DO 110 I=1,NN	HUELSMAN
NRE(I)=0	HUELSMAN
110 NCE(I)=0	HUELSMAN
DO 120 J=1,NGAIN	HUELSMAN
DO 120 I=1,NN	HUELSMAN
IF (I.EQ.NG1(J)) NRE(I)=1	HUELSMAN
IF (I.EQ.JL(J)) NCE(I)=1	HUELSMAN
120 CONTINUE	HUELSMAN
121 IN=1	HUELSMAN
DO 145 I=1,NM	HUELSMAN
123 IF (NRE(IN)) 130,130,125	HUELSMAN
125 IN=IN+1	HUELSMAN
GO TO 123	HUELSMAN
130 IF (IN.EQ.I) GO TO 140	HUELSMAN
132 DO 135 J=1,NN	HUELSMAN
135 YR(I,J)=YR(IN,J)	HUELSMAN
140 IN=IN+1	HUELSMAN
145 CONTINUE	HUELSMAN
DO 165 I=1,NGAIN	HUELSMAN
K=NG1(I)	HUELSMAN
L=NG3(I)	HUELSMAN
M=JL(I)	HUELSMAN
IF (L.EQ.M) GO TO 155	HUELSMAN
DO 150 J=1,NM	HUELSMAN
150 YR(J,L)=YR(J,L)+YR(J,K)*GA(I)	HUELSMAN
GO TO 165	HUELSMAN
155 DO 160 J=1,NM	HUELSMAN
160 YR(J,K)=YR(J,K)+YR(J,L)/GA(I)	HUELSMAN
165 CONTINUE	HUELSMAN
IN=1	HUELSMAN
DO 190 I=1,NM	HUELSMAN
172 IF (NCE(IN)) 175,175,170	HUELSMAN
170 IN=IN+1	HUELSMAN
GO TO 172	HUELSMAN
175 IF (IN.EQ.I) GO TO 185	HUELSMAN
DO 180 J=1,NM	HUELSMAN
180 YR(J,I)=YR(J,IN)	HUELSMAN
185 IN=IN+1	HUELSMAN
190 CONTINUE	HUELSMAN

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RETURN
END
SUBROUTINE DISRP
COMMON YR(15,15),R(15,15),C(15,15),RD(5,50),CD(5,50),
1 NSECT(5),N1(5),N2(5),N3(5),NN,ND,RAD,KD,NREP
2,NGAIN,NG1(5),NG2(5),NG3(5),NG4(5),JL(5),GA(5)
COMPLEX YR
DIMENSION P(10)
DO 199 I=1,ND
READ 150,NOPT,NSECT(I),N1(I),N2(I),N3(I)
150 FORMAT (5I3)
PRINT 155,I,NSECT(I),N1(I),N2(I),N3(I)
155 FORMAT (1H0,19HDISTRIBUTED NETWORK,I2,5X,I3,9H SECTIONS,5X,
1 18HCONNECTED TO NODES,3I3)
NZ=NSECT(I)
IF (NZ) 156,156,159
156 PRINT 157
157 FORMAT (1H0,20X,21HSEE PRECEDING NETWORK)
GO TO 199
159 DIV=NZ
GO TO (160,180,190,200),NOPT
160 READ 165,RT,CT
165 FORMAT (8E10.0)
PRINT 170,RT,CT
170 FORMAT(1H0,17HTOTAL RESISTANCE=, E15.8,5X,18HTOTAL CAPACITANCE=,
1 E15.8)
RT=RT/DIV
CT=CT/DIV
DO 175 IA=1,NZ
RD(I,IA)=RT
175 CD(I,IA)=CT
PRINT 176,RT,CT
176 FORMAT(1H0,17HRESISTANCE/SECT.=, E15.8,5X,
1 18HCAPACITANCE/SECT.=,E15.8)
GO TO 199
180 READ 165,ALF,RA,RB,CA,CB
IF (ALF) 182,182,185
182 IF (RB) 184,184,183
183 ALF=ALOG (RB)-ALOG (RA)
GO TO 185
184 ALF=ALOG (CA)-ALOG (CB)
185 DIV=DIV-1.
DO 188 IA=1,NZ
DIA=IA-1
DB=ALF*DIA/DIV
RD(I,IA)=RA*EXP (DB)
188 CD(I,IA)=CA*EXP (-DB)
PRINT 189,ALF
189 FORMAT (1H0,17HEXPONENTIAL TAPER,1X,7HALPHA =, E17.8)
GO TO 191
190 READ 165, (RD(I,IA),IA=1,NZ)
READ 165, (CD(I,IA),IA=1,NZ)
GO TO 191
200 PRINT 202
202 FORMAT (1H0,42HPOLYNOMIAL TAPER, R(X)=R*POLY, C(X)=C/POLY )
READ 201,NP,RI,CI,XT
201 FORMAT (13,7X,7E10.0)
READ 165,(P(I),I=1,NP)
PRINT 205,NP
205 FORMAT(1H0,I2,47H COEFFICIENTS P(I) OF POLY 1+P(1)X+P(2)X**2+.../ )

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PRINT 193, (P(I),I=1,NP)	HUELSMAN
PRINT 210,XT,RI,CI	HUELSMAN
210 FORMAT (1H0,10HLENGTH X=, E10.3,5X,10HINITIAL R=,E10.3,	HUELSMAN
15X,*INITIAL C=*E10.3)	HUELSMAN
DO 220 IA=1,NZ	HUELSMAN
PIA=IA	HUELSMAN
X=PIA*XT/DIV	HUELSMAN
AP=1.	HUELSMAN
DO 215 IR=1,NP	HUELSMAN
AP=AP+P(IB)*X**IB	HUELSMAN
215 CONTINUE	HUELSMAN
RD(I,IA)=RI*AP	HUELSMAN
220 CD(I,IA)=CI/AP	HUELSMAN
191 PRINT 192	HUELSMAN
192 FORMAT (1H0,18HRESISTANCE/SECTION)	HUELSMAN
PRINT 193, (RD(I,IA),IA=1,NZ)	HUELSMAN
193 FORMAT (1X, 7E17.8)	HUELSMAN
PRINT 194	HUELSMAN
194 FORMAT (1H0,19HCAPACITANCE/SECTION)	HUELSMAN
PRINT 193, (CD(I,IA),IA=1,NZ)	HUELSMAN
199 CONTINUE	HUELSMAN
RETURN	HUELSMAN
END	HUELSMAN
PROGRAM MAIN (INPUT,OUTPUT,PUNCH,TAPE4=INPUT)	HUELSMAN
C MAIN PROGRAM, DLA NETWORK ANALYSIS,5VCVS VERSION	HUELSMAN
COMMON YR(15,15),R(15,15),C(15,15),RD(5,50),CD(5,50),	HUELSMAN
1NSECT(5),N1(5),N2(5),N3(5),NN,ND,RAD,KD,NREP	HUELSMAN
2,NGAIN,NG1(5),NG2(5),NG3(5),NG4(5),JL(5),GA(5)	HUELSMAN
COMPLEX YR	HUELSMAN
DIMENSION Y(5,100),LTR(8),Z(5,100)	HUELSMAN
COMPLEX VD	HUELSMAN
READ 99,LTR	HUELSMAN
99 FORMAT (8A10)	HUELSMAN
JX=1	HUELSMAN
96 PRINT 98,LTR	HUELSMAN
98 FORMAT (1H1,8A10)	HUELSMAN
102 NREP=0	HUELSMAN
PHSD=0.	HUELSMAN
IX=0	HUELSMAN
READ 107,NN,ND,NF,NSY,NSP,KRAD,LMAG,LPHS,KPLT,LFRQ,OLDG,FA,FB,	HUELSMAN
1SCALE,SCALP,KPUN,NGAIN	HUELSMAN
107 FORMAT (5I3,5I1,5E10.0,I1,I3)	HUELSMAN
PRINT 106,JX	HUELSMAN
106 FORMAT (/1H0,14HPROBLEM NUMBER,I2)	HUELSMAN
PRINT 110,NN,ND	HUELSMAN
110 FORMAT(1H0,I2,6H NODES,5X,I2,24H DISTRIBUTED SUBNETWORKS)	HUELSMAN
DO 101 I=1,NN	HUELSMAN
DO 101 J=1,NN	HUELSMAN
R(I,J)=0.	HUELSMAN
101 C(I,J)=0.	HUELSMAN
IF (NGAIN.GT.0) GO TO 95	HUELSMAN
NGAIN=1	HUELSMAN
NG1(1)=2	HUELSMAN
NG2(1)=0	HUELSMAN
NG3(1)=3	HUELSMAN
NG4(1)=0	HUELSMAN
JL(1)=3	HUELSMAN
GA(1)=OLDG	HUELSMAN
GO TO 92	HUELSMAN
95 DO 94 I=1,NGAIN	HUELSMAN


```

94 READ 93,NG1(I),NG2(I),NG3(I),NG4(I),JL(I),GA(I)
93 FORMAT (5I3,5X,E10.0)
92 PRINT 91,NGAIN
91 FORMAT (1H0,I2,1X,*GAIN ELEMENTS OF VCVS TYPE*)
  PRINT 90,(I,NG1(I),NG2(I),NG3(I),NG4(I),JL(I),GA(I),I=1,NGAIN)
90 FORMAT (1X*NO.*I2*, SOURCE AT NODES*I3,2H -,I3
  1*, CONTROL VOLTAGE AT NODES*I3,2H -,I3*, SUPRESS NODE*I3
  2*, GAIN=*E12.5)
  PRINT 115
115 FORMAT (1H0,15HLUMPED ELEMENTS)
  13 PRINT 116
116 FORMAT (5X,5HNODES,8X,7HR(OHMS),8X,9HC(FARADS))
113 READ 105,I,J,RA,CA
105 FORMAT (2I2,6X,2E10.0)
  IF (I) 112,112,111
111 PRINT 114,I,J,RA,CA
114 FORMAT (1X,2I5, 2E15.3)
  IF (RA) 104,103,104
104 RA=1./RA
  IF (J.EQ.0) GO TO 14
  R(J,J)=RA+R(J,J)
  R(I,J)=-RA+R(I,J)
  R(J,I)=R(I,J)
  14 R(I,I)=RA+R(I,I)
103 IF (CA.EQ.0.) GO TO 113
  IF (J.EQ.0) GO TO 15
  C(J,J)=CA+C(J,J)
  C(I,J)=-CA+C(I,J)
  C(J,I)=C(I,J)
  15 C(I,I)=CA+C(I,I)
  GO TO 113
112 IF (NREP.GT.0) GO TO 124
118 CALL DISRP
  IF (NREP.GT.0) GO TO 124
117 IF(KRAD) 160,160,161
160 PRINT 162
162 FORMAT (1H0,40HVALUES OF FREQUENCY ARE IN HERTZ)
  GO TO 165
161 PRINT 163
163 FORMAT (1H0,41HVALUES OF FREQUENCY ARE IN RADIAN/SECOND)
165 IF (LFRQ) 120,120,122
120 PRINT 121,NF,FA,FB
121 FORMAT( 1H0,16HLINEAR FREQ PLOT,I4,12H POINTS FROM, E15.8,4H TO ,
  1 E15.8)
  DNF=NF
  FREQ=FA
  DF=(FB-FA)/DNF
  GO TO 124
122 IF(FA-1.) 150,151,151
151 FL=ALOG10 (FA)
  GO TO 152
150 FL=-ALOG10 (1./(FA-.0001))
152 LOG1=FL
  IF (FB-1.) 153,154,154
154 FM=ALOG10 (FB)
  GO TO 155
153 FM=-ALOG10 (1./(FB-.0001))
155 LOG2=FM
  NG=NF/(LOG2-LOG1)
  PRINT 123,NG,LOG1,LOG2

```

```

123 FORMAT( 1H0,13HLOG FREQ PLOT,15,21H POINTS/DEC FROM 10**,12,
1 9H TO 10**,12)
NLG=1
124 PRINT 144
144 FORMAT (1H0,3X,2HJX,3X,2HIX,8X,8HFREQ(HZ),15X,3HRAD,17X,3HVXM,15X,
17HVXM(DB),11X,10HPHASE(DEG))
125 IF (LFRQ) 126,126,127
126 FREQ=FREQ+DF
GO TO 128
127 FREQ=XL4(NLG,LOG1,NG)
128 IF(FREQ-FB-.0001) 129,129,139
129 IF (KRAD) 170,170,171
170 RAD=FREQ*6.283185307
FREQH=FREQ
GO TO 130
171 RAD=FREQ
FREQH=FREQ/6.283185307
130 DO 131 I=1,NN
DO 131 J=1,NN
131 YR(I,J)=(0.,0.)
DO 132 I=1,ND
KD=I
132 CALL YDIST
DO 134 I=1,NN
DO 134 J=1,NN
134 YR(I,J)=YR(I,J)+CMPLX(R(I,J),C(I,J)*RAD)
CALL CONST
CALL CMRED
VD=-YR(2,1)/YR(2,2)
VXM=CABS (VD)
VXMDB=20.*ALOG10 (VXM)
IX=IX+1
IF (LPHS) 180,180,181
181 PHSD=ATAN2(AIMAG(VD),REAL(VD))*57.2957795
Z(JX,IX)=PHSD*SCALP
180 PRINT 145,JX,IX,FREQH,RAD,VXM,VXMDB,PHSD
145 FORMAT (1X,2I5,5E20.8)
IF (KPUN.GT.0) PUNCH 200,IX,FREQH,RAD,VXM,VXMDB,PHSD
200 FORMAT (14,1X,5E15.8)
IF (LMAG) 137,137,136
136 Y(JX,IX)=VXM*SCALE
GO TO 135
137 Y(JX,IX)=VXMDB*SCALE
135 IF (IX-NF) 125,139,139
139 IX=0
JX=JX+1
READ 107,NREP
IF (EOF,4) 999,193
193 IF (NREP.EQ.0) GO TO 102
NLG=1
FREQ=FA
PRINT 106,JX
GO TO (190,118,194,102 ),NREP
190 READ 191,(GA(I),I=1,NGAIN)
191 FORMAT (8E10.0)
PRINT 89
89 FORMAT (1H0*CHANGES IN GAIN ELEMENTS*)
PRINT 90,(I,NG1(I),NG2(I),NG3(I),NG4(I),JL(I),GA(I),I=1,NGAIN)
GO TO 124
194 PRINT 195

```

195	FORMAT (1H0,26HCHANGES IN LUMPED ELEMENTS/)	HUELSMAN
	GO TO 13	HUELSMAN
999	IF (KPLT.GT.0) STOP	HUELSMAN
	IF (LMAG) 172,172,174	HUELSMAN
172	PRINT 173,SCALE,LTR	HUELSMAN
173	FORMAT (1H1,12HDB SCALED BY, E9.2,5X,8A10/)	HUELSMAN
	GO TO 179	HUELSMAN
174	PRINT 175,SCALE,LTR	HUELSMAN
175	FORMAT (1H1,13HMAG SCALED BY, E9.2,5X,8A10/)	HUELSMAN
179	JX=JX-1	HUELSMAN
	CALL PLOT (Y,JX,NF,NSY)	HUELSMAN
146	IF (LPHS) 183,183,184	HUELSMAN
184	PRINT 185,SCALP,LTR	HUELSMAN
185	FORMAT (1H1,21HPPHASE(DEG), SCALED BY,E9.2,5X,8A10/)	HUELSMAN
	CALL PLOT (Z,JX,NF,NSP)	HUELSMAN
183	STOP	HUELSMAN
	END	HUELSMAN

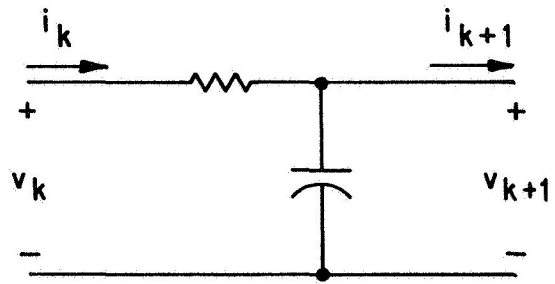


Fig. 1

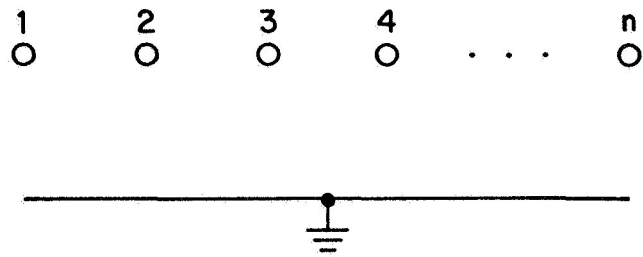


Fig. 2

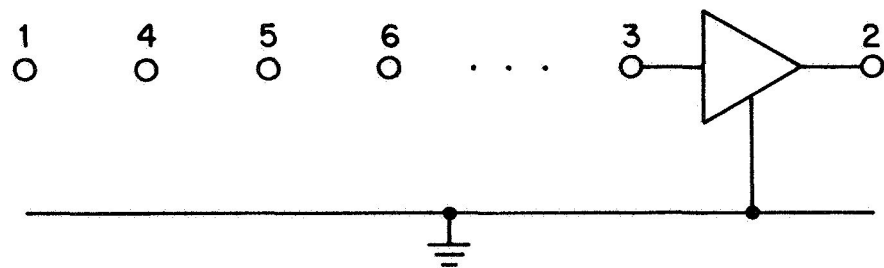


Fig. 3

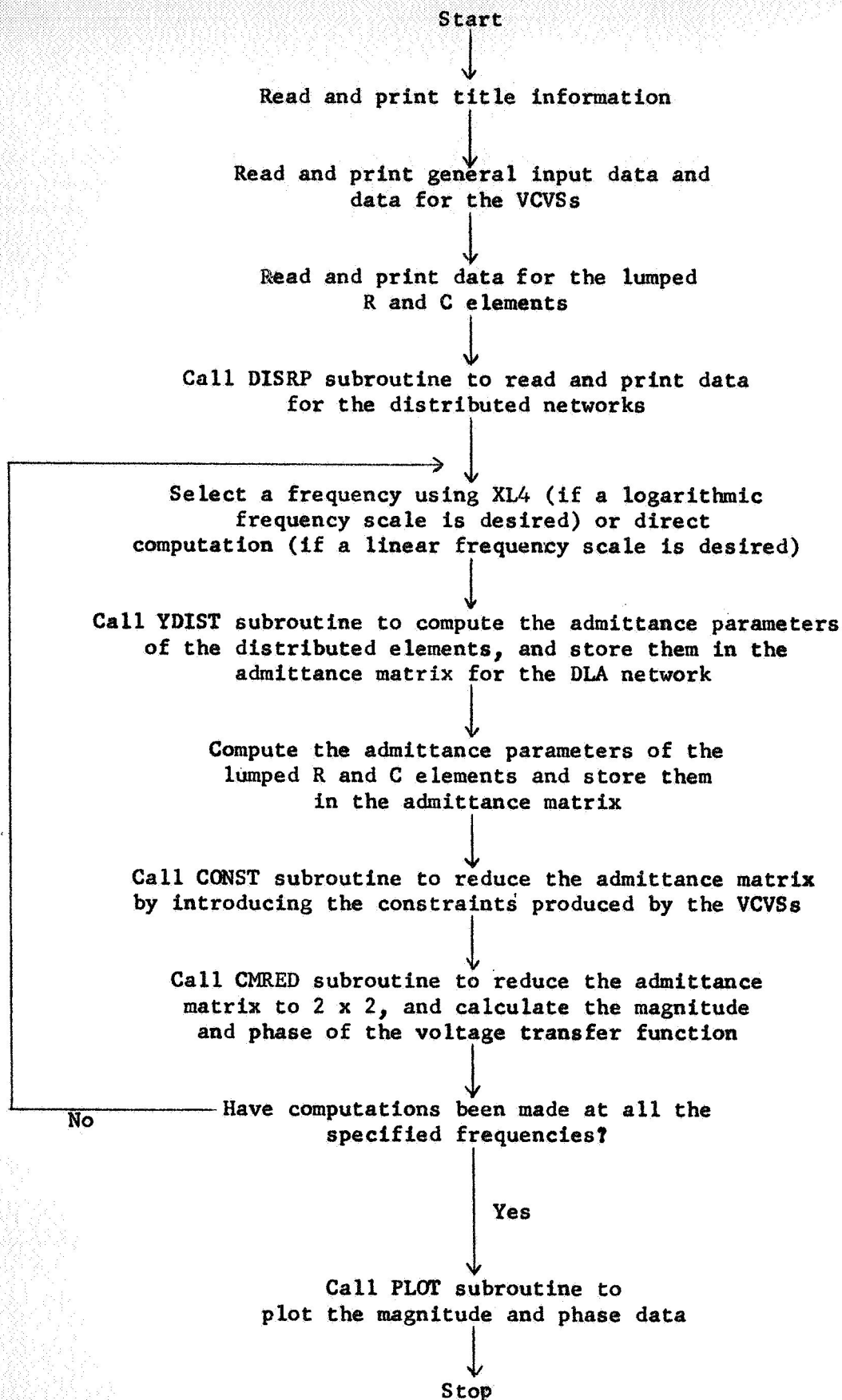


Fig. 4 Flow Chart for the Digital Computer Program DLANET

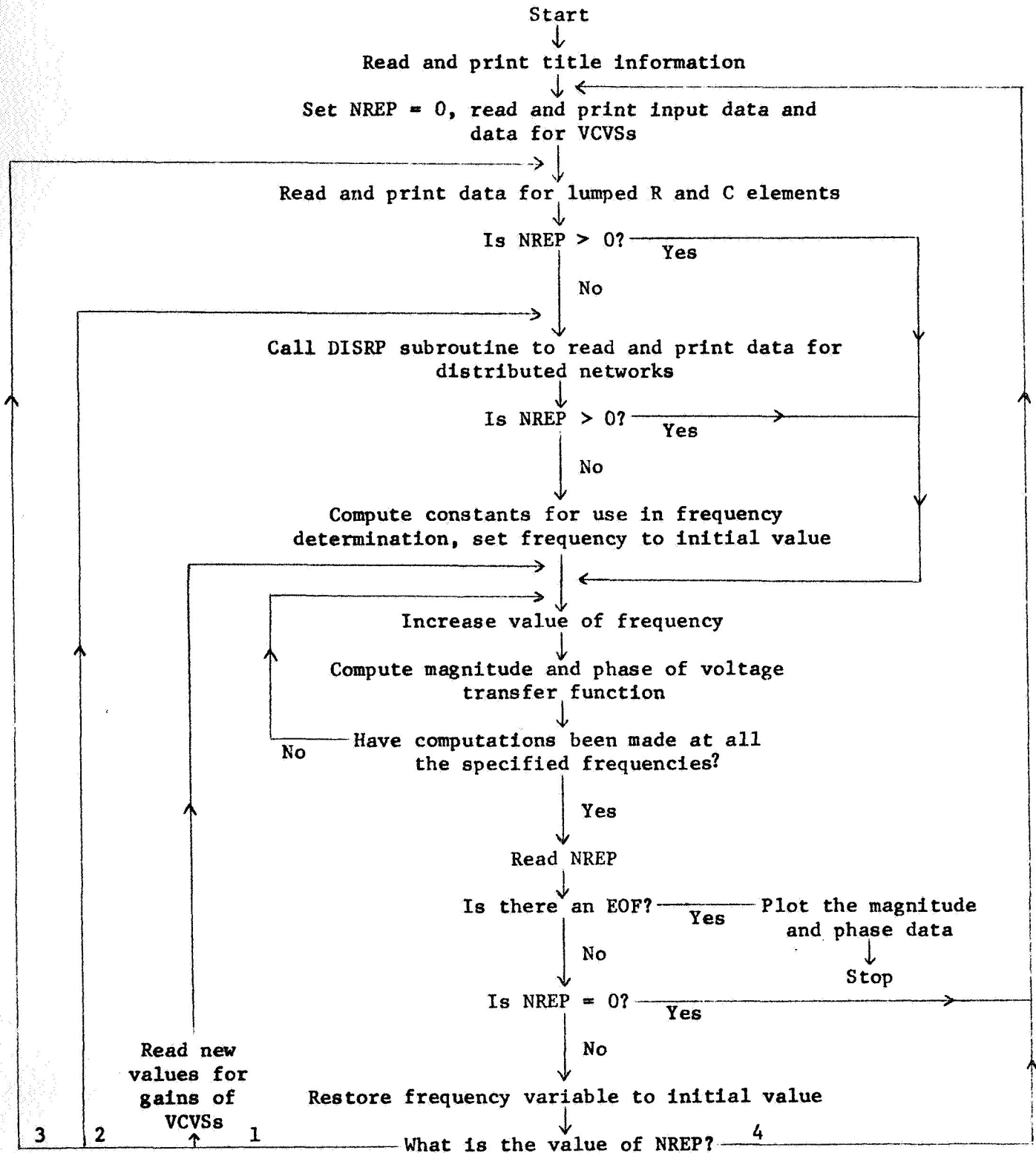


Fig. 6 Flow Chart for Multiple-Case feature of DLANET Program

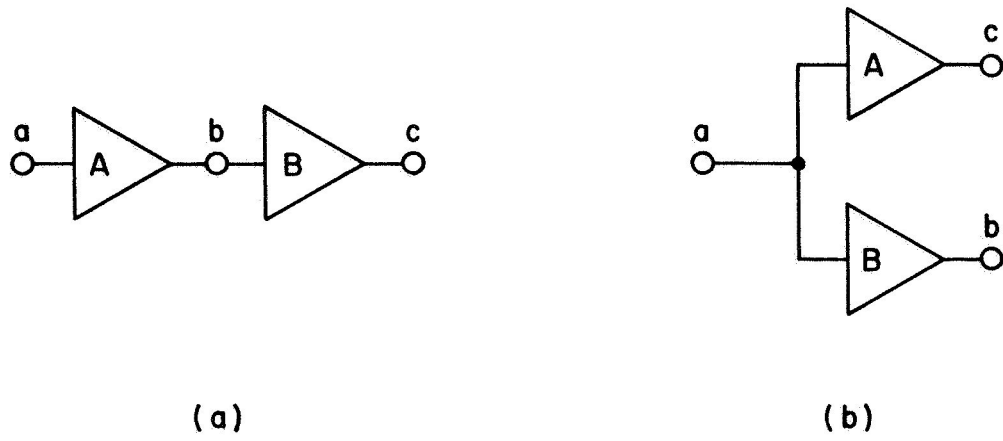


Fig. 5

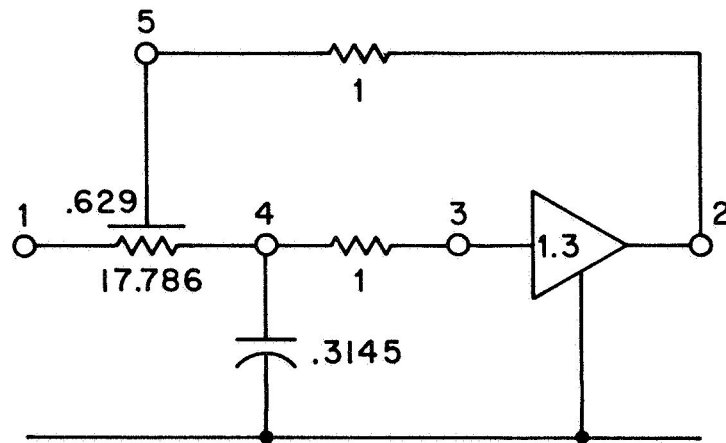


Fig. 7

TEST OF KERWIN TEST FOR DLA 5VCVS MOD

5	1	50	100	101	1	1	.1	10.	1.	.5	1
2	0	3	0	3			1.3				
2	5						1.				
3	4						1.				
4	0						.3145				

1	5	1	4	5
17.786			.629	

2

1	10	1	4	5
17.786			.629	

Fig. 8

PROBLEM NUMBER 1

5 NODES 1 DISTRIBUTED SUBNETWORKS

1 GAIN ELEMENTS OF VCVS TYPE

NO. 1, SOURCE AT NODES 2 - 0, CONTROL VOLTAGE AT NODES 3 - 0, SUPPRESS NODE 3, GAIN= 1.30000E+00

LUMPED ELEMENTS

NODES	R (OHMS)	C (FARADS)
2	1.000E+00	-0.
3	1.000E+00	-0.
4	-0.	3.145E-01

DISTRIBUTED NETWORK 1 5 SECTIONS CONNECTED TO NODES 1 4 5

TOTAL RESISTANCE= 1.77860000E+01 TOTAL CAPACITANCE= 6.29000000E-01

RESISTANCE/SECT.= 3.55720000E+00 CAPACITANCE/SECT.= 1.25800000E-01

VALUES OF FREQUENCY ARE IN RADIAN/SECOND

LOG FREQ PLOT 25 POINTS/DEC FROM 10**1 TO 10**1

JX	IX	FREQ(HZ)	RAD	VXM	VXM (DB)	PHASE (DEG)
1	1	1.74509925E-02	1.09647820E-01	1.33647759E+00	2.51923364E+00	-2.40335232E+01
1	2	1.91346328E-02	1.20226443E-01	1.34194994E+00	2.55472633E+00	-2.66947552E+01
1	3	2.09807076E-02	1.31825674E-01	1.34755156E+00	2.59090784E+00	-2.97199742E+01
1	4	2.30048884E-02	1.44543977E-01	1.35278907E+00	2.62460173E+00	-3.31756968E+01
1	5	2.52243586E-02	1.58489319E-01	1.35679358E+00	2.65027560E+00	-3.71416328E+01
1	6	2.76579592E-02	1.73780083E-01	1.35811681E+00	2.65874247E+00	-4.17107694E+01
1	7	3.03263492E-02	1.90546072E-01	1.35446450E+00	2.63535253E+00	-4.69860416E+01
1	8	3.32521807E-02	2.08929613E-01	1.34241664E+00	2.55774652E+00	-5.30701449E+01
1	9	3.64602911E-02	2.29086765E-01	1.31729876E+00	2.39368567E+00	-6.00437534E+01
1	10	3.99779142E-02	2.51188643E-01	1.27355079E+00	2.10032537E+00	-6.79285139E+01
1	11	4.38349113E-02	2.75422870E-01	1.20604339E+00	1.62725864E+00	-7.66390264E+01
1	12	4.80640244E-02	3.01995172E-01	1.11241762E+00	9.25357211E-01	-8.59449960E+01
1	13	5.27011548E-02	3.31131121E-01	9.95400869E-01	4.00396856E-02	-9.54793441E+01
1	14	5.77856671E-02	3.63078055E-01	8.63121603E-01	-1.27856026E+00	-1.04812461E+02
1	15	6.33607241E-02	3.98107171E-01	7.26538782E-01	-2.77482397E+00	-1.13561559E+02
1	16	6.94736524E-02	4.36515832E-01	5.95683250E-01	-4.49969223E+00	-1.21470023E+02
1	17	7.61763451E-02	4.78630092E-01	4.77226582E-01	-6.42550747E+00	-1.28419692E+02
1	18	8.35257015E-02	5.24807460E-01	3.74180313E-01	-8.53838132E+00	-1.34390982E+02
1	19	9.15841105E-02	5.75439937E-01	2.86865236E-01	-1.08464416E+01	-1.39404232E+02
1	20	1.00419980E-01	6.30957344E-01	2.14095839E-01	-1.33878355E+01	-1.43458583E+02
1	21	1.10108319E-01	6.91830971E-01	1.54070890E-01	-1.62455882E+01	-1.46454015E+02
1	22	1.20731371E-01	7.58577575E-01	1.04910203E-01	-1.95836455E+01	-1.48024528E+02
1	23	1.32379316E-01	8.31763771E-01	6.49738455E-02	-2.37452286E+01	-1.46972163E+02
1	24	1.45151033E-01	9.12010839E-01	3.33345675E-02	-2.95421035E+01	-1.38279369E+02
1	25	1.59154943E-01	1.00000000E+00	1.39796901E-02	-3.70900491E+01	-8.95850943E+01
1	26	1.74509925E-01	1.09647820E+00	2.29441904E-02	-3.27865452E+01	-2.42090268E+01
1	27	1.91346328E-01	1.20226443E+00	3.88059675E-02	-2.82220297E+01	-1.10715421E+01
1	28	2.09807076E-01	1.31825674E+00	5.25615936E-02	-2.55866295E+01	-8.05015585E+00
1	29	2.30048884E-01	1.44543977E+00	6.38139065E-02	-2.39016934E+01	-7.72859185E+00
1	30	2.52243586E-01	1.58489319E+00	7.28248564E-02	-2.27544073E+01	-8.45163064E+00
1	31	2.76579592E-01	1.73780083E+00	7.99072823E-02	-2.19482728E+01	-9.66495420E+00
1	32	3.03263492E-01	1.90546072E+00	8.53450131E-02	-2.13764370E+01	-1.11340995E+01
1	33	3.32521807E-01	2.08929613E+00	8.93830028E-02	-2.09749012E+01	-1.12743182E+01
1	34	3.64602911E-01	2.29086765E+00	9.22311657E-02	-2.07024461E+01	-1.14427713E+01
1	35	3.99779142E-01	2.51188643E+00	9.40706705E-02	-2.05309152E+01	-1.16148244E+01
1	36	4.38349113E-01	2.75422870E+00	9.50597538E-02	-2.04400663E+01	-1.17879038E+01
1	37	4.80640244E-01	3.01995172E+00	9.53381659E-02	-2.04146641E+01	-1.19603047E+01
1	38	5.27011548E-01	3.31131121E+00	9.53381659E-02	-2.04146641E+01	-1.19603047E+01

1	39	5.77856671E-01	3.63078055E+00	9.42452582E-02	-2.05148098E+01	-2.29945810E+01
1	40	6.33607241E-01	3.98107171E+00	9.30797304E-02	-2.06228977E+01	-2.46581462E+01
1	41	6.94736524E-01	4.36515832E+00	9.16149057E-02	-2.07606772E+01	-2.63063475E+01
1	42	7.61763451E-01	4.78630092E+00	8.99172150E-02	-2.09231431E+01	-2.79495091E+01
1	43	8.35257015E-01	5.24807460E+00	8.80378533E-02	-2.11066111E+01	-2.96013660E+01
1	44	9.15841105E-01	5.75439937E+00	8.60132938E-02	-2.13086884E+01	-3.12776304E+01
1	45	1.00419980E+00	6.30957344E+00	8.38666847E-02	-2.15282105E+01	-3.29943299E+01
1	46	1.10108319E+00	6.91830971E+00	8.16100766E-02	-2.17651243E+01	-3.47661236E+01
1	47	1.20731371E+00	7.58577575E+00	7.92472640E-02	-2.20203145E+01	-3.66047987E+01
1	48	1.32379316E+00	8.31763771E+00	7.67769368E-02	-2.22953844E+01	-3.85181006E+01
1	49	1.45151033E+00	9.12010839E+00	7.41958237E-02	-2.25924108E+01	-4.05089839E+01
1	50	1.59154943E+00	1.00000000E+01	7.15015387E-02	-2.29136922E+01	-4.25753090E+01

PROBLEM NUMBER 2

DISTRIBUTED NETWORK 1	10 SECTIONS	CONNECTED TO NODES	1	4	5
TOTAL RESISTANCE=	1.77860000E+01	TOTAL CAPACITANCE=	6.29000000E-01		
RESISTANCE/SECT.=	1.77860000E+00	CAPACITANCE/SECT.=	6.29000000E-02		

JX	IX	FREQ(HZ)	RAD	VXM	VXM(DB)	PHASE(DEG)
2	1	1.74509925E-02	1.09647820E-01	1.33318842E+00	2.49783064E+00	-2.51271051E+01
2	2	1.91346328E-02	1.20226443E-01	1.33781648E+00	2.52793082E+00	-2.79003655E+01
2	3	2.09807076E-02	1.31825674E-01	1.34232689E+00	2.55716578E+00	-3.10492322E+01
2	4	2.30048884E-02	1.44543977E-01	1.34614872E+00	2.58186085E+00	-3.46407311E+01
2	5	2.52243586E-02	1.58489319E-01	1.34831640E+00	2.59583634E+00	-3.87543504E+01
2	6	2.76579592E-02	1.73780083E-01	1.34727104E+00	2.58909951E+00	-4.34814654E+01
2	7	3.03263492E-02	1.90546072E-01	1.34061461E+00	2.54607893E+00	-4.89210167E+01
2	8	3.32521807E-02	2.08929613E-01	1.32488087E+00	2.44335365E+00	-5.51680786E+01
2	9	3.64602911E-02	2.29086765E-01	1.29550157E+00	2.24875888E+00	-6.22911151E+01
2	10	3.99779142E-02	2.51188643E-01	1.24730161E+00	1.91942968E+00	-7.02956578E+01
2	11	4.38349113E-02	2.75422870E-01	1.17588748E+00	1.40731531E+00	-7.90806420E+01
2	12	4.80640244E-02	3.01995172E-01	1.07984151E+00	6.67200342E-01	-8.84092179E+01
2	13	5.27011548E-02	3.31131121E-01	9.62606596E-01	3.31023332E-01	-9.79256562E+01
2	14	5.77856671E-02	3.63078055E-01	8.32356643E-01	-1.59381100E+00	-1.07230540E+02
2	15	6.33607241E-02	3.98107171E-01	6.99402140E-01	-3.10546086E+00	-1.15980589E+02
2	16	6.94736524E-02	4.36515832E-01	5.72848932E-01	-4.83919784E+00	-1.23956213E+02
2	17	7.61763451E-02	4.78630092E-01	4.58607312E-01	-6.77118051E+00	-1.31069558E+02
2	18	8.35257015E-02	5.24807460E-01	3.59261078E-01	-8.89179662E+00	-1.37329932E+02
2	19	9.15841105E-02	5.75439937E-01	2.74982477E-01	-1.12138996E+01	-1.42797367E+02
2	20	1.00419980E-01	6.30957344E-01	2.04594949E-01	-1.137821018E+01	-1.47541753E+02
2	21	1.10108319E-01	6.91830971E-01	1.46362749E-01	-1.66913888E+01	-1.51606045E+02
2	22	1.20731371E-01	7.58577575E-01	9.84570269E-02	-2.01350657E+01	-1.54948820E+02
2	23	1.32379316E-01	8.31763771E-01	5.91889019E-02	-2.45551943E+01	-1.57254284E+02
2	24	1.45151033E-01	9.12010839E-01	2.71340510E-02	-3.13297073E+01	-1.56673664E+02
2	25	1.59154943E-01	1.00000000E+00	3.44446872E-03	-4.92575551E+01	-8.76443857E+01
2	26	1.74509925E-01	1.09647820E+00	2.10499595E-02	-3.35349747E+01	1.00904511E+00
2	27	1.91346328E-01	1.20226443E+00	3.83250832E-02	-2.83303379E+01	2.51627056E+00
2	28	2.09807076E-01	1.31825674E+00	5.23482627E-02	-2.56219545E+01	1.33766078E+00
2	29	2.30048884E-01	1.44543977E+00	6.36108677E-02	-2.39293736E+01	-4.25838786E+01
2	30	2.52243586E-01	1.58489319E+00	7.25502474E-02	-2.27872220E+01	-2.36983252E+00
2	31	2.76579592E-01	1.73780083E+00	7.95282495E-02	-2.19895715E+01	-4.36645036E+00
2	32	3.03263492E-01	1.90546072E+00	8.48426764E-02	-2.14277128E+01	-6.36299614E+00
2	33	3.32521807E-01	2.08929613E+00	8.87403757E-02	-2.10375747E+01	-8.33210992E+00
2	34	3.64602911E-01	2.29086765E+00	9.14289019E-02	-2.07783299E+01	-1.02555157E+01
2	35	3.99779142E-01	2.51188643E+00	9.30863510E-02	-2.06222799E+01	-1.21179593E+01
2	36	4.38349113E-01	2.75422870E+00	9.38693272E-02	-2.05495259E+01	-1.39050386E+01
2	37	4.80640244E-01	3.01995172E+00	9.39190041E-02	-2.05449304E+01	-1.56028612E+01
2	38	5.27011548E-01	3.31131121E+00	9.33652325E-02	-2.05962963E+01	-1.71987130E+01
2	39	5.77856671E-01	3.63078055E+00	9.23286992E-02	-2.06932657E+01	-1.86823103E+01
2	40	6.33607241E-01	3.98107171E+00	9.09212782E-02	-2.08266893E+01	-2.00472954E+01
2	41	6.94736524E-01	4.36515832E+00	8.92449215E-02	-2.09883298E+01	-2.12926387E+01
2	42	7.61763451E-01	4.78630092E+00	8.73896475E-02	-2.11708002E+01	-2.24236050E+01

2	44	9.15841105E-01	5.75439937E+00	8.34299848E-02	-2.15735567E+01	-2.43955575E+01
2	45	1.00419980E+00	6.30957344E+00	8.14291387E-02	-2.17844032E+01	-2.52764881E+01
2	46	1.10108319E+00	6.91830971E+00	7.94564939E-02	-2.19974121E+01	-2.61194874E+01
2	47	1.20731371E+00	7.58577575E+00	7.75258712E-02	-2.22110669E+01	-2.69495426E+01
2	48	1.32379316E+00	8.31763771E+00	7.56400525E-02	-2.24249636E+01	-2.77899758E+01
2	49	1.45151033E+00	9.12010839E+00	7.37940278E-02	-2.26395757E+01	-2.86610263E+01
2	50	1.59154943E+00	1.00000000E+01	7.19781382E-02	-2.28559878E+01	-2.95791238E+01

-90	-80	-70	-60	-50	-40	-30	-20	-10	0	10	Y(1,I)
I	I	I	I	I	I	I	I	I	I	I	2.51923E+00
I	I	I	I	I	I	I	I	I	I	I	2.55473E+00
I	I	I	I	I	I	I	I	I	I	I	2.59091E+00
I	I	I	I	I	I	I	I	I	I	I	2.62460E+00
I	I	I	I	I	I	I	I	I	I	I	2.65028E+00
I	I	I	I	I	I	I	I	I	I	I	2.65874E+00
I	I	I	I	I	I	I	I	I	I	I	2.63535E+00
I	I	I	I	I	I	I	I	I	I	I	2.55775E+00
I	I	I	I	I	I	I	I	I	I	I	2.39369E+00
I	I	I	I	I	I	I	I	I	I	I	2.10033E+00
I	I	I	I	I	I	I	I	I	I	I	1.62726E+00
I	I	I	I	I	I	I	I	I	I	I	9.25357E-01
I	I	I	I	I	I	I	I	I	I	I	4.00397E-02
I	I	I	I	I	I	I	I	I	I	I	1.27856E+00
I	I	I	I	I	I	I	I	I	I	I	2.77482E+00
I	I	I	I	I	I	I	I	I	I	I	4.49969E+00
I	I	I	I	I	I	I	I	I	I	I	6.42551E+00
I	I	I	I	I	I	I	I	I	I	I	8.53838E+00
I	I	I	I	I	I	I	I	I	I	I	1.08464E+01
I	I	I	I	I	I	I	I	I	I	I	1.33878E+01
I	I	I	I	I	I	I	I	I	I	I	1.62456E+01
I	I	I	I	I	I	I	I	I	I	I	1.95836E+01
I	I	I	I	I	I	I	I	I	I	I	2.37452E+01
I	I	I	I	I	I	I	I	I	I	I	2.95421E+01
I	I	I	I	I	I	I	I	I	I	I	3.70900E+01
I	I	I	I	I	I	I	I	I	I	I	3.27865E+01
I	I	I	I	I	I	I	I	I	I	I	2.82220E+01
I	I	I	I	I	I	I	I	I	I	I	2.55866E+01
I	I	I	I	I	I	I	I	I	I	I	2.39017E+01
I	I	I	I	I	I	I	I	I	I	I	2.27544E+01
I	I	I	I	I	I	I	I	I	I	I	2.19483E+01
I	I	I	I	I	I	I	I	I	I	I	2.13764E+01
I	I	I	I	I	I	I	I	I	I	I	2.09749E+01
I	I	I	I	I	I	I	I	I	I	I	2.07024E+01
I	I	I	I	I	I	I	I	I	I	I	2.05309E+01
I	I	I	I	I	I	I	I	I	I	I	2.04401E+01
I	I	I	I	I	I	I	I	I	I	I	2.04147E+01
I	I	I	I	I	I	I	I	I	I	I	2.04428E+01
I	I	I	I	I	I	I	I	I	I	I	2.05148E+01
I	I	I	I	I	I	I	I	I	I	I	2.06229E+01
I	I	I	I	I	I	I	I	I	I	I	2.07607E+01
I	I	I	I	I	I	I	I	I	I	I	2.09231E+01
I	I	I	I	I	I	I	I	I	I	I	2.11066E+01
I	I	I	I	I	I	I	I	I	I	I	2.13087E+01
I	I	I	I	I	I	I	I	I	I	I	2.15282E+01
I	I	I	I	I	I	I	I	I	I	I	2.17651E+01
I	I	I	I	I	I	I	I	I	I	I	2.20203E+01
I	I	I	I	I	I	I	I	I	I	I	2.22954E+01
I	I	I	I	I	I	I	I	I	I	I	2.25924E+01
I	I	I	I	I	I	I	I	I	I	I	2.29137E+01

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