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NASA-CK-103952

SUBJECT: Aerospace Digital Computer Design Trends - Case 103 DATE: January 14, 1969

FROM: D. O. Baechler

MEMORANDUM FOR FILE

Attached is a copy of "Trends in Aerospace Digital Computer Design," an article which will be published in the January 1969 issue of the Institute of Electrical and Electronics Engineers' Computer Group News.

This article updates a previous article, "State-of-the-Art of Aerospace Digital Computers, 1962-1967," which appeared in the January 1968 issue of the Computer Group News.

1031-DOB-ml

Attachment

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D. O. Baechler

CASE FILE COPY

TRENDS IN AEROSPACE DIGITAL

COMPUTER DESIGN

Donald O. Baechler Bellcomm, Incorporated

INTRODUCTION

This article summarizes some of the recent trends in aerospace computer design that can be inferred from the changing characteristics of computers developed during the period 1962-1968. In an earlier paper,* characteristics of 40 computers developed during 1962-1967 were described. Since the time the earlier paper was written, at least 13 new aerospace computers have been introduced and at least 7 others are in development. This paper updates the information in the earlier paper with very little repetition. For a more detailed description and discussion of computer characteristics and how they have evolved, the reader is referred to the earlier paper.

Characteristics of the sixty computers used as a basis for this paper are given in Table 1, where the computers are listed according to their date of introduction. Table 2 provides an alphabetically listed cross-reference to Table 1. The list of computers includes those in the earlier report and is intended to be inclusive, but some computers of interest may have been omitted either because their characteristics are still considered proprietary by the manufacturer or because the information was not received from the manufacturer in time to be included.

GENERAL CHARACTERISTICS

Most aerospace computers perform parallel rather than serial operations on the computer word. Since logic hardware is built using integrated circuit (IC) techniques, the added cost of building a parallel computer becomes less important than the speed advantage that the parallel computer has over the serial computer. Therefore, general purpose machines will probably continue to be built as parallel processors, with serial machines designed only for special jobs with a low speed requirement and a need for extreme simplicity to achieve reliability.

Fixed point number representation is used in all except two of the computers listed in Table 1. As hardware

^{*&}quot;State-of-the-Art of Aerospace Digital Computers, 1962-1967," D. O. Baechler, IEEE Computer Group News, January 1968.

becomes smaller, lighter and more reliable, it is likely that floating point representation will become more common since fixed point representation places a burden on the programmer and makes program validation more difficult.

There is a trend toward a larger basic instruction set, with many of the more recently designed computers having more than fifty instructions. Also, the trend is toward single address instructions with provisions for designating operand and result locations from among central processing unit (CPU) registers.

Word lengths of 12 to 32 bits have been used, with some computers using different lengths for the data word, instruction word and memory word. The trend is toward a single word length. To obtain required precision without double precision operations and to provide adequate addressing and instruction decoding, 24 or 32 bits seem to be the sizes most often used.

SOFTWARE

There is an increasing attempt to reduce the problems associated with managing large programming efforts. All of the computers have assemblers; more are also being provided with compilers, diagnostic programs and simulators that can be run on commercial machines.

There is a trend toward designing families of computers, all with the same instruction set but of different sizes and operational capability. Sometimes, the family consists of both ground and aerospace computers, and the instruction set of the aerospace computer is a subset of the ground computer's instructions.

INSTRUCTION EXECUTION TIME

The execution time for the add, multiply and divide instructions are listed in Table 1 to give an indication of machine speed. Also, add times and multiply times are plotted against calendar time in Figures 1 and 2, respectively.

Add times have decreased to a range of from 2 µsec to 5 µsec and multiply and divide times have been reduced to the point that 10 µsec to 20 µsec times are not uncommon. Figures 1 and 2 also show a tendency for the times to cluster near the low end during the most recent years, with the upper limit decreasing much more than the lower limit.

MEMORY

Computers in Table 1 have memory cycle times ranging from 0.6 μsec to 27 μsec with the range from 2 μsec to 6 μsec being the most prevalent.

While core memories are used for most of the computers in Table 1, there are two emerging technologies. A plated wire memory is offered as an option on one computer in Table 1 and it is likely that such offerings will increase.

Semiconductor memories implemented using large scale integration (LSI) techniques are used in two computers in Table 1 and their use is expected to increase. LSI memories can be implemented as read-only storage or as read-write storage, and either metal-oxide-semiconductor (MOS) or bipolar devices can be used.

INPUT/OUTPUT (I/O)

The information in Table 1 concerning I/O channels and interrupts is not uniform because not all manufacturers define "channel" in the same way and because in some cases information was taken from a computer description that did not fully explain the numbers given. Most of the computers in Table 1 have at least one external interrupt and a means for input and output of parallel digital data and discrete signals. Often a separate I/O unit is required to handle analog and serial digital inputs and outputs.

It is likely that computers will continue to be built without rigidly defined I/O, but with features that will permit the addition of I/O units designed for a particular application. Among the features that will probably be provided are direct memory access, priority interrupts with automatic multi-level program status retention, and addressed I/O to permit selection of a large number of devices.

PHYSICAL CHARACTERISTICS

Prior to 1963, the computers in Table 1 used discrete components or hybrid circuits. From 1963 until 1968, all the computers in Table 1 used bipolar silicon integrated circuits. This year represents the beginning of two changes in the hardware used. First, machines are being designed with LSI. One which is already built, the TI 2502 LSI, uses 100 to 200 gates/chip. And second, MOS technology is being used in designing a CPU. This is being done in the Autonetics D-200.

The changing hardware technology is reflected in a reduction in the characteristic size and weight of aerospace computers. An aerospace computer with an 8K memory used to be less than 1 cu. ft. in size and weighed less than 100 lbs. Now it is generally less than 0.5 cu. ft. and weighs less than 50 lbs. Characteristic power has remained at about 100 watts. It is likely that power as well as volume and weight will further decrease as LSI technology is more widely used.

RELIABILITY

In Table 1, the reliability of some of the computers is indicated by a predicted mean time between failures (MTBF). MTBF was not available for each of the computers in Table 1, and for those MTBF's listed, the method of calculation is in most cases not described. The comments associated with Texas Instruments TI 2540 and TI 2550 begin to describe the tradeoffs in designing and building reliable equipment and also to illuminate the problem in stating an MTBF without discussing the conditions under which it was calculated. Texas Instruments builds the TI 2540 and TI 2550 for an application in which a 500 hour MTBF is adequate, and the manufacturing costs necessary to achieve this reliability result in a particular price. If high reliability--and therefore more costly--parts were used in building the computers, the calculated MTBF's would increase. If these parts were carefully screened and burned in--another costly procedure -- the calculated MTBF's would increase further. if a lower operating temperature were assumed in the calculation, the MTBF's would increase once more. While it is not difficult to predict the reliability of a system, it is difficult to meaningfully compare the reliability of several systems unless their reliabilities have been predicted under the same assumed conditions and those conditions are carefully described. fore, it is difficult to identify trends in reliability.

SUMMARY

A summary of the state-of-the-art in aerospace computers can be acquired from the information in Table 1. The characteristics listed below summarize the data for all the computers in the 1967, 1968 and development categories, except that serial machines are excluded as being atypical. The values for weight, size and power are for computers with an 8K memory.

CHARACTERISTIC	MINIMUM	TYPICAL	MAXIMUM
Add Times (µsec)	∿2	4-9	∿20
Multiply Times (µsec)	6	20-40	66
Divide Time (μsec)	11.4	20-60	94.5
Weight (pounds)	12	20-50	120
Size (cubic feet)	0.18	0.2-0.7	0.96
Power (watts)	20	50-200	310
Memory Size (words)	lK	4K-32K	131K

To summarize the trends in aerospace computer design, a fictitious computer of the not-too-distant future will be described based on what the author expects the trends to be. This is one of many computers that might be used to illustrate the trends. Using the format of Table 1, the description is as follows:

The manufacturer's name and nomenclature indicates that this is one of a series of machines that are available. It may even be implied in the nomenclature that it is in some way compatible with the manufacturer's ground-based computers. The date of introduction is 1971.

It is a parallel machine with floating point number representation and has 75 instructions with provisions for register-to-register operations.

The add time is l µsec, multiply time is 8 µsec and divide time is 10 µsec. These times are possible because of the very fast MOS memory and because of features that allow some operations to overlap.

The MOS memory has a 500 nsec cycle time. It is $4K \times 32$ bits and can be expanded to 32K. There is another computer in this series which has a memory that can be expanded to 131K.

There is an interrupt that has a 12-bit address associated with it to designate one of the 4096 possible interrupt sources that can be connected to the computer through a specially designed I/O unit. There are two separate channels

that have direct access to the memory and there is a bus for transferring data and control words between the I/O unit and the CPU.

Bipolar LSI technology is used to implement the logic. With a 4K MOS memory, the computer weighs 20 pounds, has a volume of 0.20 cubic feet and uses 25 watts of power.

The listed MTBF is 450 days, or about 11,000 hours. It was calculated for 70° C using MIL HDBK 217B techniques but the failure rates for the LSI circuits were based on the manufacturer's own experience with these circuits. The computer also has multiprocessor capability.

TABLE 1 - CHARACTERISTICS OF AEROSPACE COMPUTERS.

		L081C. 81TS.	<u> </u>	T		15 85	ATOR.		URRESIT	T			9_			ME I GRT
	COMMENTS	USES CORE MULL-DECODER REGISTERS FOR LDGIC. INSTRUCTIONS ARE 16 BITS, DATA IS 24 BITS. 50-BIT ROPE USED FOR MICROPROGRAMMING.	NDRO MEMORY HAS 50 MILLISEC WRITE TIME FROM EXTERNAL EQUIPMENT.	REGISTERS ARE DELAY LINES, MEMORY IS TWO-APERATURE CORE	CHOICE OF ONE OF THE THREE MEMORIES AVAILABLE.	CONCURRENT MULTIPLY/DIVIDE, 18 BITS OF MEMORY WORD ARE READ-ONLY, INSTRUCTION MORD, 18 RITS: DATA MIDD, 24 RITS	HAS INDEPENDENT, PROGRAMMERE INTEGRATOR. USES TWO ADDRESSES, OPERAND AND MEXT IN	OTHER MEMORY TYPES ARE AVAILABLE.	REGISTERS ARE GLASS DELAY LINES. CONCURRENT DAD AND MULLIPLY. TWO PARITY BITS IN MEMORY WARD	SOME 1/0 HANDLED THROUGH COUNTER INTERUPTS.	DATA WORD, 24 BITS; INSTRUCTION WORD, 16 BITS.	WEIGHT, SIZE AND POWER ARE GIVEN FOR SK MEMORY	MOST COMMON OPERATIONS USE 18-BIT INSTRUC- TION MODE, WITH 18-LIF OPERAND STORED IN OTHER MALE OF THE WIND	DATA WORD, 16 BITS; INSTRUCTION WORD, 32 BITS	WEIGHT, SIZE, POWER AND WIBF ARE GIVEN FOR ZK MENORY.	24-BIT WORD OPTION 18 AVAILABLE. 31ZE, WEIGHT AND FOWER ARE GIVEN FOR AN WENDORY.
	MTBF (HRS)	7000									10,000		0381	2300	9500	7200
SOI.	POWER (WATTS)	8	262	20	8	85	£30	99	881	125	9	8	98	8	5	8
PHYSICAL CHARACTERISTICS	SIZE (CU, FI.)	0.25	3	9.0		1.65	1.2		2.1	-	0.47	8.6	- e:	0.26	0.5	0.21
CAL CHAR	WEIGHT (LBS)	<u>•</u>	\$	2	15	59	8	15	8	19	31.5	3	8	ts.	29	æ
PHYSI	TYPE OF HARDWARE	MAGNETIC	DISCRETE	DISCRETE	DISCRETE	DISCRETE	DISCRETE	HYGRID THIR FILM	OTL HYBRID	DCTL 1C	DI 1C	2	ETL IC	E 5	2	DTL 1C
탈	CHANNEL NO. OF NTERRUPI		3	2	-	0	•	-	-		-		60	-	-	25*
<u> </u>	CYCLE OF TIME 10° (4. SEC)	5		72			-	8 9	 -	=	-		2.8 67	8	<u> </u>	#
	ACCESS CY TIME TI (# SEC) (# 5			7						==						3
									82		0.7		1.2		7	
MEMORY	CAPACITY (WORDS)		256 7K	2K 8K	4K 16K 1500K	¥	¥	512 4K	4K 32K	= ē	512 4K	HK 32K	*	M181	2K 8K	*
	WORD SIZE (BITS)	5 2 S	22	22	* * *	6	25	22	8	2 2	₹ 3	z	æ	32	\$Z	22
	TYPE	DRO CORE CORE ROPE CORE ROPE	ORO TRIN FILM NDRO THIN FILM	NDRO CORE	DRO CORE NDRO CORE DRUM	NDRO CORE	DRUM	DRO CORE NDRO THIM FILM	DRO CORE	DRO CORE CORE ROPE	DRO THIR FRLM NDRO THIR FILM	DRO CORE	DRO CORE	DRO CORE	DRO CORE	DRO CORE
LING	DIV	089	837	324	8	0118	¥	8	656	210	128		€.	 	921	
COMPUTING TIME, # SEC	WULT	88	E	135	52	420	¥	22	328	=	82	ĸ	8.8	5	8	•
SNOIJ	INSTRUCT	9 <u>9</u>	12	22	8	- 3	624		82	23.4	•		5.6	5.6	60	80
OE AbE	T ATA0	×	ž	T.	Fx 30	<u>ج</u> 5	Fx 12	Fx 30	×	=	-	Z# 3	9	8	15	я
	ATA0	۰.	<u>.</u>	o,	•	.			S F	£	e F	F.	e.	e T	e x	Œ.
	NAME. DATE INTRODUCED	1. BURROUGHS D210 PRE 1962	2 UNIVAC ADD-1000 PRE 1962	3. ARMA MICRO COMPUTER MID 1962	4 HUGHES HCM-201 MID 1962	COMPUTER EARLY 1963	ANJASN-24 MID 1963	7. HUGHES HCM-202. MID 1963	L IBM SATURN IB/V LVDC MID 1963	. MIT BLOCK I AGC LATE 1963	UNIVAC 1824 LATE 1963	BURROUGHS D84 MID 1964	SAAB CK 37 MID 1964	LITTON L-304 EARLY 1965	NORTRONICS NDC-1051 EARLY 1965	15. AUTONETICS D26.1 LATE 1965 LATE 1965
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*SEE ATTACHED EXPLANATION OF HEADINGS

TABLE 1 - CHARACTERISTICS OF AEROSPACE COMPUTERS (CONTINUED)

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BELLCOMM,	-	COMMENTS	AVAILABLE OPTIONS INCLUDE DRO CORE WITH I SASE CYCLE TIME, MAD BUFFRED I/O WITH 7 CHAMMELS. ALSO DESIGNATED ANAWK-S.	WEIGHT, SIZE, POWER AND WIBF ARE GIVEN FOR 16K WEMORY.	NEWORY CAN BE PARTIALLY HARD-WIRED.	MEMORY CAN BE PARTIALLY HARD-WIRED.	(AVALLABLE WITH FAST CLOCK) MISF EXCLUDES POWER SUPPLY, AT 50 C. NO ENVIRONENTAL CONTROLS REQUIRED, -65°	TO +125C WEIGHT AND SIZE EXCLUDE POWER SUPPLY, WISF IS FOR 8K MEMORY. MISF IS 2425 FOR UK MEMORY.	WEIGHT, SIZE, POWER AND WTBF ARE GIVEN FOR 8K WENGRY. HAS ALTERABLE MICROPROGRAM.	MEMORY CAN BE PARTIALLY HARD-WIRED.	MEIGHT, SIZE AND POWER ARE GIVEN FOR UK MEMORY.	ALSO HAS DRO THIN FILM CONTROL MEMORY AND GHUMBR OF ROPE BODTSTRAP MEMORY.	WEIGHT, SIZE AND POWER ARE GIVEN FOR BK MEDGHT, SIZE AND POWER ARE GIVEN FOR BK MEDGHT, METTHORY ON THE TOTAL AND	HIGH-SPEED MEMORY USED FOR SCRATCH PAD.	4-WORD (96-BIT) READOUT FROM MORD MEMORY TO AM INSTRUCTION LOOK-AMEAD	MENGNY. HAS DOUBLE PRECISION ADD INSTRUCTION.	WELGHT, SIZE AND POWER ARE GIVEN FOR 2% NEWORY.
	ļ	MTBF (HRS)	1981	3060			10,000	1626	98			009h		15,600	2500	0001	0000
	TICS	POWER (WATTS)	150	225	250	52	8	98	240	250	350	299	120	175	011	92	0=
	ACTER 15	SIZE (CU. FT.)	1.2	0.87	s:	3.0	0.07	9.0	96.0	1.5] =	2.65	pp.0	0.65] =	0.49	0.2
	PHYSICAL CHARACTERISTICS	WEIGHT (LBS)	68	88	# 9	ħε	5.75	36	82	25	8	200	23	43	99	28	50
	PHYSI	TYPE OF HARDWARE	HLTTL 1C	DTL 1C	5	DTL 1C	Ę	5	5	5	ភ	2	. 9	5	ᄓ	DTL 1.C	DTL IC
1	<u> </u>	NO. OF NTERRUP	1 2	60		•	-	-	# # # # # # # # # # # # # # # # # # #		32	-	9	60	9	-	-
		CHANNEL NO OF		2	-	-	2	22	_	-	2	32	-	~	, vo	w	-
		CYCLE TIME (# SEC)	7	~		ro.	8.3	9	2		2	2	6	9-	2.5	2.0	2.0
		ACCESS TIME (# SEC)	-					5:	-							0.65	
	ΨŽ	CAPACITY (WORDS)	¥	32K		*	33.8	32K	32K		₩ <u>₩</u>	13.K	32K	32K		<u>₹</u>	¥6
	MEMORY	<u> </u>	¥	*	¥	¥	¥	¥	¥	*	¥	¥	¥	8K 256	¥ ×	, X	×
		WORD SIZE (BITS)		≛	21	_ ∞	<u>8</u>	5#	5	12	32	88	32	88	₹ %	50	■
		14 PE	DRO CORE	DRO CORE	DRO CORE	DRO CORE	DRO CORE	DRO CORE	DRO CORE	DRO CORE	DRO CORE	DRO CORE	DRO CORE	DRO CORE DRO CORE	DRO CORE NDRO THIN FILM	DRO CORE	DRO CORE
	SEC	ΛIQ	32	S		73	342	06	=		37	ng.	323		275	\$	52
1000	TIME, # SEC	TJUM	. ≢	26	99	2	342	8	0=	99	12	20	12	9₩	25	\$	25
_ L_	NOIT	INSTRUC ADD	⇒ ± 68	9	<u>8</u>	01	18 18 (12)		8 01	<u>5</u>	99	±	ž.	- 12	e.	# 	3
		T ATAU ON	×	ž	Ϋ́.	Ä.	×	Ž.	F.		ž	Fx 72	Fx 22	Fx 87	Fx 73	Fx 53	Fx 42
	MO7:	1 ATAO	۵.	٩	۵.	۰	υ	۵.	•	•	•	•	ν	•	۵	•	•
	!	NAME DATE INTRODUCED	. HONEYWELL ALERT LATE 1965	. NORTRONICS NDC-1051A EARLY 1966	. SPERRY MARK XII EARLY 1966	TRW MARCO 4418 EARLY 1966	ARMA MICRO D MID 1966	CDC 5360 MID 1966	COMPUTING DEVICES OF CANADA AN/UYK-501 MID 1966	SPERRY MARK XIV MID 1966	TI 2501 MID 1966	UNIVAC 1830-A MID 1966	AC ELECTRONICS MAGIC 321 LATE 1966	AUTONETIC D26C LATE 1966	CDC 5400 LATE 1966	HONEYWELL SIGN 111 LATE 1966	HUGHES HCM-205 LATE 1966
Ŀ			형	17.	었	6.	ଞ୍ଚ	27	22	ន	₹	ដ	શ્રં	27.	প্ৰ	&	

TABLE 1 - CHARACTERISTICS OF AEROSPACE COMPUTERS (CONTINUED)

	COMMENTS	HAS 1024-2049 WORD MICROPROBRAMMING MENORY, TO BITS/WORD, 155 NSEC ACCESS TIME. AVAILABLE THIS 51 OR T7 INSTRUCTIONS. AVAILABLE AS CP-2 WITH HARDWARE DECODE INSTEAD OF MICROPROGRAM.	SK × 100 BITS MICROPROGRAMMING WEMORY. FLOATING POINT OPTION, 32-BIT DATA WORD. I PARITY BIT PER 8-BIT BYTE.	HAS DOUBLE PRECISION ADD.	MEMORY CAN BE PARTIALLY HARD-WIRED.	NEWRY CAN BE PART HARD-WIRED, DATA WORD, 16 BITS; HASTRUCTION WORD, 8 BITS.	DATA WORD, 24 BITS + 2 PARITY; INSTRUCTION Word, 12 BITS + PARITY.	DATA WORD, 31 BITS + PARITY; INSTRUCTION WORD, 15 BITS + PARITY.	HICLIDES GATTERIES, EEYBOARD AND DIAL. REJOOJT. 12-817 PARALLEL, 2 BYTE SERIAL.	NEIGHT, SIZE AND PONER ARE GIVEN FOR By Neighy,	2 BYTE SERIAL, 8-BIT PARALLE. WENGY SIZE GIVEN IN TERMS OF 8-BIT BYTES. TAMA NOOD 12 S ENTES AND INSTRUCTION WIND IS 1, 2 OR 3 BYTES.	SOME DISCRETE COMPONENTS USED. VARIABLE, INSTRUCTIONS CONTROL WICEDPROSEDAL, WEIGHT, SIZE AND POMEN GIVEN FOR MY MEMORY.	WEIGHT, SIZE AND POWER ARE GIVEN For SK WENGRY.	MAS ADDITIONAL 1/0 FOR DISCRETES, PULSE GATE INFUTS. DATA WORD, 20 BITS; IN-	WEIGHT, SIZE, POWER AND MTBF ARE GIVEN FOR BE WEMORY.	PHYSICAL CHARACTERISTICS ARE FOR ONE IN THE SERIES.
MTRE		3000	5000	8013							7500		905		2367	3999
S	POWER (WATTS)	250	303	001	250	. 88	18	511	0.7	8	27	525	161	88	8	٤
PHYSICAL CHARACTERISTICS	SIZE (CU. FT.)	8.	6.9	1.0	5:1	8	0.28	0.35	86	0.61	97.0	3.0	0.7	0.35	0.87	0.18
CAL CHAR	WEIGHT (LBS)	52	62	58	8	6.2	2	ឌ	22	8	12	130	35	22	88	12
PHYSIC	TYPE OF HARDWARE	1F 16	月元	DCTL 1C	2	5	2	5	ر 5	51 170	분 일	2	5	DTL 1C	DT. IC	21
를 SI	NO. OF INTERRUP	ۍ	ro.	9		_	-	_	-	0		3	2	-	-	
IN/OUTPUT	CHANNEL OF	, ,	m	2	z i	7	-	-	-	2			22	LG.	8	3
	CYCLE TIME (# SEC)	2.5	2.5	# #. = =	ص	3	2.6	e e		م	2.5	3.0	88	. 7	2	→
	ACCESS TIME (# SEC)	6.0	6.9									. 326		-	_	
≿	CAPACITY (WORDS)	32K	128K		16K		:	32K		65X		32K	*	ž9	32K	*
MEMORY		*	*	36K	*	×	#	¥	3840 3840	*	16K	512	≠¥	. ≱	*	¥
	WORD SIZE (BITS)	32	36	91	21	60	<u> </u>	92	\$\$	<u></u>	60	88	22	0	₹	8
	TYPE	DRO CORE	DRO CORE	DRO CORE CORE ROPE	DRO CORE	DRO CORE	DRO CORE	DRO CORE	DRO THIN FILM NDRO (LBIAX	DRO CORE	DRO CORE	DRO CORE DRO CORE	DRO CORE CORE ROPE	DRO CORE	DRO CORE	DRO CORE
ING	DIV		.8.3	6.18		280	332	ξ. 2.					77		28	#
COMPUTING TIME, # SEC	WULT	28.	9.5	# #e.8	në.	96	101	34.5	109	8	120	99	z	8	8	33
	INSTRUCT	3t 6.6	135 5.8	34 23.4	± =	12 23	6	23 4.5	36 28.	e e	- 12	9.3	28	20	9	
	YT ATAU IO "ON		1d	Ϋ́ ε	¥ -	×	Fx 28	Fx 2	Fx 3	Fx . 23	₹.	7.	Fx 2	Fx 32	Fx 55	¥.
	J4 ATAO		a.	•	•	ø	ø	•	a.		•	•	۵.	8/P	•	•
	NAME DATE INTRODUCED	31. IBM 4 PI/CP LATE 1966	32 IBM 4 PIÆP LATE 1966	33. MIT BLOCK 11 AGC LATE 1966	34. SPERRY MARK XVI LATE 1966	35. AC ELECTRONICS MAGIC 301 EARLY 1967	36.AC ELECTRONICS MAGIC 311 EARLY 1967	37.AC ELECTRONICS MAGIC 331 EARLY 1967	38. CDC 449 EARLY 1967	39. ELLIOTT MCS 920 M EARLY 1967	40. IBM 4 PI/TC EARLY 1967	41. RCA VIC-36A EARLY 1967	42. UNIVAC 1818 EARLY 1967	43. GPI KEARFOTT GPK-20 MID 1967	44 NORTRONICS NDC-1060 MID 1967	45. TELEDYNE SERIES 20000 MID 1967

BELLCOMM, INC.

TABLE 1 - CHARACTERISTICS OF AEROSPACE COMPUTERS (CONTINUED)

	(HRS) COMMENTS	PHYSICAL CMARACTERISTICS INCLUDE POWER SUPPLY: HAS ADDITIONAL 1/0 FOR DISCRETES. PULSE RATE INPUTS.	2009	ALSO CALLED CELESTIAL DATA PROCESSOR. WEIGHT AND SIZE INCLUDE BATTERIES AND 1/0 DEVICES.	HAS DOUBLE PRECISION AND REBISTER- REGISTER OPERATIONS.	MTBF CALCULATED AT 71°C USING COMERCIAL PARTS WITH NO BURN-IN; HI-REL, BURNED-IN PARTS CAN BE PROVIDED AT ETRAL COST. DATA WORD. AS BURNED-IN WORD. AS 8 BURNED-IN WORD. AS 8 BURNED-IN WORD. AS 8 BURNED-IN WORD.	SOO ALL COMMENTS FOR TI 2540 APPLY.	HAS HARDMARE SQUARE ROOT, MEMORY IS ELPANDABLE TO 81. MEMORY SOUTH HAS IK 17,522 INSTRUCTIONS. I.D. CONSTANTS, AND 32	FORMER DE LINCONDO	WEIGHT, SIZE AND POMER ARE GIVEN FOR UK MENORY.	WE 189T, SIZE AND POWER ARE GIVEN FOR BK WENGRY, INSTRUCTION WORD ADDRESSES A HENGRY DESTRUCTION WORD ADDRESSES A HENGRY REGISTER	ME IGHT, SIZE AND POWER ARE GIVEN FOR BK MENGY. HALF-WORD INSTRUCTIONS USED FOR REGISTER, RESISTER OFFERSTORS.	3240 ONE OF A SERIES.	DATA WORD, 32 BITS; INSTRUCTION MORD, 16 BITS.	MULTIPPOCESSOR, EACH BY NEWRY MODULE CAM MANDLE PRIOR ITY REQUESTS AND PROVIDE A MUSY SIGHT	METONT, SIZE AND POMER ARE RIVEN ETO
SOL	POWER (WATTS)	8	8			310	310	8	8	2		.8	=	200		1
PHYSICAL CHARACTERISTICS	S1ZE (CU. FT.)	94.0	⇒ .0	0.195		8.0	. 96.0	0.13	0.096	0.116	.33	⊅ .0	0.27	0.45		2
AL CHAR	WEIGHT (LBS)	æ	8	≇		8	8	=	9.9	60	3	ន	35	3		
PHYSIC	TYPE OF HARDWARE	2		5	E Si	2	2	5	2		2	11. LSI	2	 3		
VOUTP 2	CHANNEL INTERRUP	88 ==	80	2	- ~	91	91 1	2 2	- 2		#5 -	16 256	. 2	1 15	- 2	
<u> </u>	CYCLE NO. OF		2		7	2	7					-	т.	2	2	,
	ACCESS TIME (# SEC)				-				0.7		1.6				0.7	
NEMORY	CAPACITY (WORDS) MIN MAX				Ућ9	32K	32K		32K	32K	131K	Mt.		32K	32K	žč
MEA	WORD CA SIZE (W	32 I EK	24 4K		16 84	32 ttK	32 tt	12 IK 18 128 18 32	<u>8</u>	7d ##	32 BK	32 8K	24 8K	32 #K	24 8K	<u> </u>
	TYPE S	DISC	CORE OF PLATED WIRE CORE		DRO CORE	DRO CORE		R0S R0S	CORE	SOM	CORE	CORE	DRO CORE	DRO CORE	DRO CORE	DRO CORE
				800	26	*	88	15 ES 15			0 8		080	DRO	DRO	
COMPUTING TIME, # SEC	AIQ WNF1	1025 1055	p.11 p.11		8 32	13.5	8 2	103	25 25			9.4 23.7	.5 230	23	55	₹ ₹
COMP TIME,	adA	70	2.6 11		س	<u>82</u> . ∌	e, ⇒	<u> </u>	6.6 2		3.3 6	2.t 9.	6 22.		# 29	9
	INSTRUC	32	9	98		53	82	32	36		95		142	98	3	
	T ATAO	Fx	č	×	×	Œ.	ž	ξ.	Fx		¥	ž	ž	×	ĸ.	Ĕ
мот	7 ATAO	s	•	-	8/8	a.	۵.	s	۵		•	۵.	•	_	۵	•
	NAME DATE INTRODUCED	GPI KEARFOTT GPK-10 LATE 1967	RAYTHEON RAC-230 LATE 1967	ARMA PORTABLE MICRO D EARLY 1968	NORTRONICS NDC-1070 MID 1968	TI 2540 MID 1968	TI 2550 MID 1968	HONEYWELL H-437 LATE 1968	ARMA ADVANCED MICRO D DEVELOPMENT	AUTONETICS D-200 DEVELOPMENT	LITTON L-3050 DEVELOPMENT	KAYTHEON ARGUS MULTI PROCESSOR DEVELOPMENT	TELEDYNE TDY 300 DEVELOPMENT	TI 2502 LSI DEVELOPMENT	TRW EW 20/24 DEVELOPMENT	UNIVAC 1819
		Æ	47.	84	49.	5	51. 1	52 +	53. /	54 A		ž	57. Т	58. T	59. T	09

TABLE 1: CHARACTERISTICS OF AEROSPACE COMPUTERS (CONTINUED)

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	HEADINGS:
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	TICN
	LANA
	ËXP

- NUMBER: PROVIDES CROSS-REFERENCE FROM ALPHABETICAL LIST TO THIS CHROMOLOGICAL LIST.
- NAME: MANUFACTURER'S NAME, FOLLOWED BY OTHER IDENTIFY-ING NAMES OR NUMBERS. DATE OF INTRODUCTION IS DATE THAT MANUFACTURER HAD WORKING HARDWARE.
- DATA FLOW: S = SERIAL, OR P = PARALLEL, INDICATES THE WAY DATA FLOWS! IN THE ARTHWETIC UNIT; S/P !HDICATES A COMBINATION OF SERIAL AND PARALLEL, AND IS EXPLAINED IN THE "COMMENTS" COLUMN.
- DATA TYPE: Fx = FIXED POINT, FL = FLOATING POINT.
- NO. OF INSTRUCTIONS: THIS THE NUMBER'OF INSTRUCTIONS IN THE INSTRUCTION SET, AND DOES NOT INCLUDE VARIATIONS OF BASIC INSTRUCTIONS.

- COMPUTING TIMES. NO MEMORY OVERLAP IS ASSUMED. ONE INSTRUCTION FETCH AND OME OPERAND FETCH FROM MEMORY IS INCLUDED.
- NEMORY: "CAPACITY (NIN)" IS THE STANDARD NEMORY SIZE FOR THE MAXIMIS, AND "CAPACITY (MAX)" IS THE MAXIMIS SIZE OF DIRECTLY ADDRESSABLE NEMORY ATTAINABLE BY ADDING STANDARD MODULES.
- INPUT/OUTPUT: THESE NUMBERS WERE OBTAINED FROM MANU-FACTURER'S DESCRIPTIONS. DIFFERENT MANUFACTURERS DEFINE "CHANNEL" IN DIFFERENT WAYS, AND INTERRUPTS LISTED IN SPECIFICATIONS SOMETHMES INCLUDE INTERNAL INTERRUPTS AS WILL AS EXTERNAL INTERRUPTS. THEREFORE CARE SHOULD BE TAKEN IN USING THE NUMBERS LISTED.
- PHYSICAL CHARACTERISTICS: UNDER "TYPE OF HARDWARE" THE FOLLOWING ABBREVIATIONS ARE USED:
- MOS METAL OXIDE SENICONDUCTOR
 - IC INTEGRATED CIRCUITS
- DCTL DIRECT-COUPLED TRANSISTOR 11081C DTL DIODE-TRANSISTOR 11081C TTL TRANSISTOR-TRANSISTOR LOGIC

 - HL HIGH LEVEL, AS IN NLTTL. LSI LARGE SCALE INTEGRATION
- THE WEIGHT, SIZE, AND POWER REQUIREMENTS ARE GIVEN FOR A MACHINE WITH A "STANDARD SIZE" MEMORY.
- WTBF: THIS IS A FIGURE OBTAINED FROM THE MAMUFACTURER. THE NETHOD OF CALCULATING THE RELIABILITY MAY VARY FROM MANUFACTURER TO MANUFACTURER. •
- ◆ COMMENTS: COMMENTS DESCRIBE UNIQUE OR INTERESTING FEATURES, OR FURTHER EXPLAIN AN ENTRY IN THE PRECED-ING COLLAM.

TABLE 2. ALPHABETICAL LIST OF COMPUTERS

Number From Table 2	Name Name	Year <u>Introduced</u>
35 36	AC Electronics Magic 301 AC Electronics Magic 311	Early 1967 Early 1967
26 37 53	AC Electronics Magic 321 AC Electronics Magic 331 ARMA Advanced Micro D	Late 1966 Early 1967
3 20	ARMA Micro Computer ARMA Micro D	Development Mid 1962 Mid 1966
48 27 15	ARMA Portable Micro D Autonetics D26C Autonetics D26J	Early 1968 Late 1966
54 11	Autonetics D-200 Burroughs D84	Late 1965 Development Mid 1964
1 38 21	Burroughs D210 CDC 449 CDC 5360	Pre 1962 Early 1967
28 22	CDC 5400 Computing Devices of Canada AN/UYK-501	Mid 1966 Late 1966 Mid 1966
39 6 46	Elliott MCS 920M General Precision AN/ASN-24 General Precision Kearfott GPK-10	Early 1967 Mid 1963 Late 1967
43 16 52	General Precision Kearfott GPK-20 Honeywell ALERT Honeywell H-437	Mid 1967 Late 1965
29 4	Honeywell SIGN III Hughes HCM-201	Late 1968 Late 1966 Mid 1962
7 30 5 8	Hughes HCM-202 Hughes HCM-205 IBM Gemini Guidance Computer	Mid 1963 Late 1966
8 32 ∙31	IBM Saturn IB/V LVDC IBM 4 PI/EP IBM 4 PI/CP	Early 1963 Mid 1963 Late 1966
40 13	IBM 4 PI/TC Litton L-304	Late 1966 Early 1967 Early 1965
55 33 9	Litton L-3050 MIT Block II AGC MIT Block I AGC	Development Late 1966
14 17 44	Nortronics NDC-1051 Nortronics NDC-1051A	Late 1963 Early 1965 Early 1966
49 56	Nortronics NDC-1060 Nortronics NDC-1070 Raytheon ARGUS Multiprocessor	Mid 1967 Mid 1968 Development
47 41 12	Raytheon RAC-230 RCA VIC-36 SAAB CK37	Late 1967 Early 1967
18 23	Sperry Mark XII Sperry Mark XIV	Mid 1964 Early 1966 Mid 1966
34 45 57	Sperry Mark XVI Teledyne TDY-210 Teledyne TDY-300	Late 1966 Mid 1967
24 58 50	Texas Instruments 2501 Texas Instruments 2502 LSI Texas Instruments 2540	Development Mid 1966 Development
51 59	Texas Instruments 2550 TRW EW 20/24 Multiprocessor	Mid 1968 Mid 1968 Development
19 2 42	TRW MARCO 4418 Univac ADD-1000 Univac 1818	Early 1966 Pre 1962
60 10 25	Univac 1819 Univac 1824 Univac 1830-A	Early 1967 Development Late 1963 Mid 1966

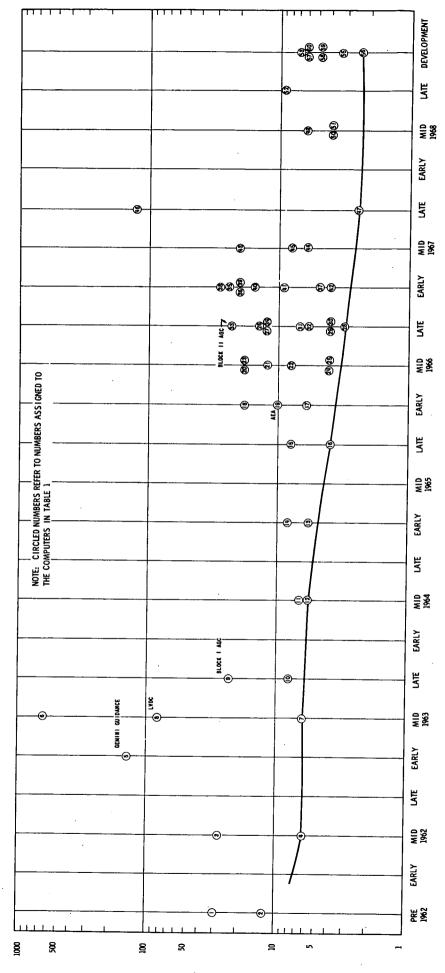


FIGURE 1 - ADD TIMES OF AEROS PACE COMPUTERS

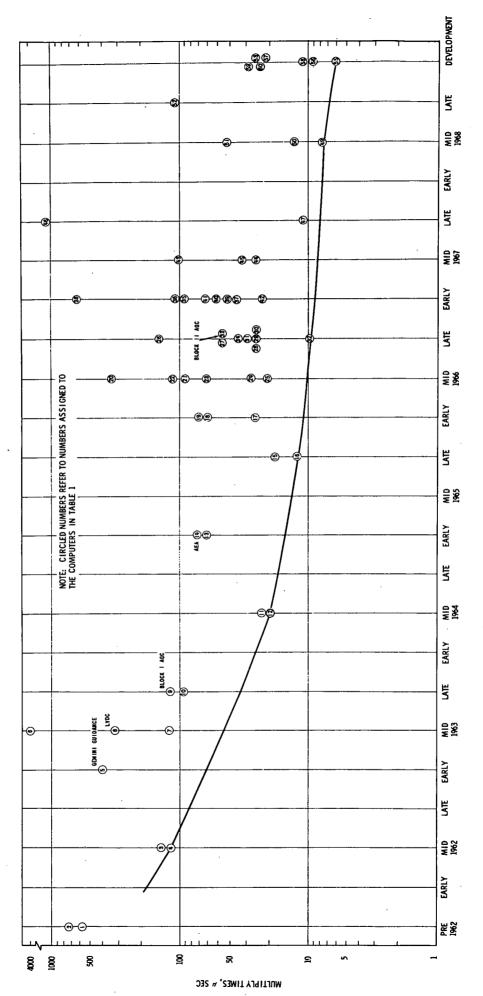


FIGURE 2 - MULTIPLY TIMES OF AEROSPACE COMPUTERS

BELLCOMM, INC.

Subject: Aerospace Digital Computer

Design Trends - Case 103

From: D. O. Baechler

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