

260

No



MSC-CF-P-69-11  
NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

# CSM RENDEZVOUS PROCEDURES

## G MISSION

FINAL  
REVISION A



23 JUNE 1969

MANNED SPACECRAFT CENTER  
HOUSTON, TEXAS

N70-34718

(ACCESSION NUMBER)

(THRU)

67

(PAGES)

(CODE)

Tmx 64412

(NASA CR OR TMX OR AD NUMBER)

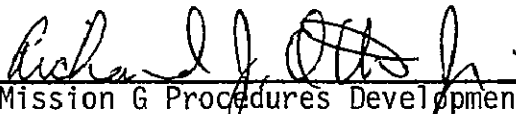
31


(CATEGORY)

FACILITY FORM 602

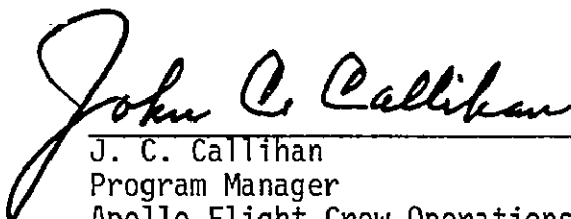
Reproduced by  
NATIONAL TECHNICAL  
INFORMATION SERVICE  
Springfield, Va 22151

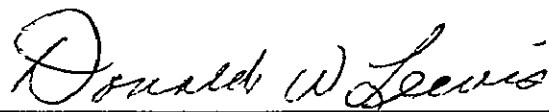
PREPARED BY:


  
Mission G Procedures Development Group  
Apollo Flight Crew Operations  
McDonnell Douglas Astronautics Company

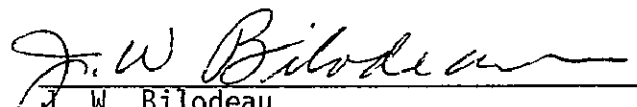
  
D. K. Mosel  
Technical Monitor (MDAC ED)  
Orbital Procedures Section  
Manned Spacecraft Center

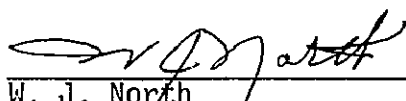
APPROVED BY:

  
J. C. Callihan  
Program Manager  
Apollo Flight Crew Operations  
McDonnell Douglas Astronautics Company

  
D. W. Lewis  
Technical Manager (MDAC ED)  
Flight Procedures Branch  
Manned Spacecraft Center

  
P. C. Kramer  
Chief Flight Procedures Branch  
Manned Spacecraft Center

  
J. W. Bilodeau  
Assistant Chief for Crew Integration  
Flight Crew Support Division  
Manned Spacecraft Center

  
W. J. North  
Chief Flight Crew Support Division  
Manned Spacecraft Center

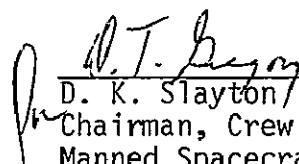
  
D. K. Slayton  
Chairman, Crew Procedures Control Board  
Manned Spacecraft Center

TABLE OF CONTENTS

	<u>PAGE</u>
1.0 PURPOSE -----	1
2.0 INTRODUCTION -----	2
3.0 DISCUSSION OF MAJOR EVENTS -----	12
3.1 Undocking and Separation -----	12
3.2 Descent Orbit Insertion -----	13
3.3 Powered Descent Initiation -----	13
3.4 Orbital Navigation -----	14
3.5 CSM Plane Change -----	14
3.6 Concentric Sequence Initiation -----	15
3.7 Constant <sup>7</sup> Delta Height and Plane Change -----	16
3.8 Terminal Phase Initiation -----	17
3.9 TPI to Station Keeping -----	18
4.0 NOMINAL ONBOARD RENDEZVOUS CHECKLIST -----	20
5.0 NOMINAL MAJOR PROCEDURES SUMMARY -----	47
5.1 Summary Timeline -----	48
5.2 Summary Checklist -----	58

	<u>PAGE</u>
6.0 NOMINAL DETAILED PROCEDURES -----	59
6.1 Procedures Ground Rules -----	59
6.2 Detailed Procedures -----	64
6.3 Rendezvous Navigation Summary with Sun Angles -----	105
6.4 CSM Attitude Summary -----	106
7.0 LM RESCUE CASES -----	108
7.1 Partial DOI (< 25 FPS) (CSM Active) -----	109
7.1.1 Summary -----	109
7.1.2 Plot and Pads -----	110
7.1.3 Checklist -----	111
7.2 Partial DOI ( $\geq$ 25 FPS) (CSM Active) -----	112
7.2.1 Summary -----	112
7.2.2 Plot and Pads -----	113
7.2.3 Checklist -----	114
7.3 No PDI <sub>1</sub> + 12 (LM Active) -----	115
7.3.1 Summary -----	115
7.3.2 Plot and Pads -----	116
7.3.3 Checklist -----	117

	<u>PAGE</u>
7.4 No $PDI_2 + 12$ (LM Active) -----	118
7.4.1 Summary -----	118
7.4.2 Plot and Pads -----	119
7.4.3 Checklist -----	120
7.5 $< 60$ No $PDI_1 + 12$ (CSM Active) -----	121
7.5.1 Summary -----	121
7.5.2 Plot and Pads -----	122
7.5.3 Checklist -----	123
7.6 $\geq 60$ No $PDI_1 + 12$ (CSM Active) -----	124
7.6.1 Summary -----	124
7.6.2 Plot and Pads -----	125
7.6.3 Checklist -----	126
7.7 $< 40$ No $PDI_2 + 12$ (CSM Active) -----	127
7.7.1 Summary -----	127
7.7.2 Plot and Pads -----	128
7.7.3 Checklist -----	129
7.8 40 - 90 No $PDI_2 + 12$ (CSM Active) -----	130
7.8.1 Summary -----	130
7.8.2 Plot and Pads -----	131
7.8.3 Checklist -----	132

	<u>PAGE</u>
7.9 $\geq 90$ No PDI <sub>2</sub> + 12 (CSM Active) -----	133
7.9.1 Summary -----	133
7.9.2 Plot and Pads -----	134
7.9.3 Checklist -----	135
7.10 PDI <sub>1</sub> < 10 Variable Insertion (LM Active) ---	136
7.10.1 Summary -----	136
7.10.2 Plot and Pads -----	137
7.10.3 Checklist -----	138
7.11 PDI <sub>1</sub> + 12 (10-12.5 Minutes) (CSM Active) ---	139
7.11.1 Summary -----	139
7.11.2 Plot and Pads -----	140
7.11.3 Checklist -----	141
7.12 PDI <sub>1</sub> + 14:12 (12.5-15 Minutes) (CSM Active)-	142
7.12.1 Summary -----	142
7.12.2 Plot and Pads -----	143
7.12.3 Checklist -----	144

	<u>PAGE</u>
7.13 PDI <sub>1</sub> + 21:24 Preferred Lift-off (T <sub>2</sub> ) (CSM Active) -----	145
7.13.1 Summary -----	145
7.13.2 Plot and Pads -----	146
7.13.3 Checklist -----	147
7.14 PDI <sub>2</sub> < 14.5 Variable Insertion (LM Active) -	148
7.14.1 Summary -----	148
7.14.2 Plot and Pads -----	149
7.14.3 Checklist -----	150
7.15 PDI <sub>2</sub> + 19:22 Preferred Lift-off (T <sub>2</sub> ) (CSM Active) -----	151
7.15.1 Summary -----	151
7.15.2 Plot and Pads -----	152
7.15.3 Checklist -----	153
8.0 REFERENCES -----	154

FIGURES

	<u>PAGE</u>
Relative Motion Profile (2-1) -----	5
LUNAR ORBIT RENDEZVOUS ATTITUDE TIME HISTORY	
Undocking - DOI (2-2) -----	6
PDI (2-3) -----	7
P22 Navigation (2-4) -----	8
CSM Plane Change (2-5) -----	9
Lift-off - CSI (2-6) -----	10
CDH - TPF (2-7) -----	11



LIST OF ACRONYMS AND ABBREVIATIONS

ACQ	Acquisition
ADJ	Adjust
AOH	Apollo Operations Handbook
AOS	Acquisition of Signal
ATT	Attitude
AWY	Away
BEF	Blunt End Forward
B/U	Backup
CALIB	Calibration
CB	Circuit Breaker
CDH	Constant Delta Height
CDR	Commander
CM	Command Module
CMC	Command Module Computer
CMD	Command Module Commander's Position
CMP	Command Module Pilot
COAS	Crew Optical Alignment Sight
CSI	Concentric Sequence Initiation
CSM	Command and Service Module
CT	Cease Tracking
DAP	Digital Autopilot
DH	Delta Height
DOI	Descent Orbit Insertion
DPS	Descent Propulsion System
DSKY	Display and Keyboard
DV	Delta Velocity
DWN	Down
EMS	Entry Monitor System
ET	Event Timer
FDAI	Flight Director Attitude Indicator
FPS	Feet Per Second

FWD	Forward
GDC	Gyro Display Coupler
GET	Ground Elapsed Time
GETI	Ground Elapsed Time of Ignition
GMBL	Gimbal
GND	Ground (Mission Control)
GPI	Gimbal Position Indicator
HA	Apogee Altitude
HGA	High-Gain Antenna
HOR	Horizon
HORIZ	Horizontal
HP	Perigee Altitude
IMU	Inertial Measurement Unit
INS	Insertion
IT	Initiate Tracking
IVC	Inter-Vehicular Communication
LEB	Lower Equipment Bay
LGC	LM Guidance Computer
LLMK	Lunar Landmark
LM	Lunar Module
LMK	Landmark
LMP	Lunar Module Pilot
LOI	Lunar Orbit Injection
LOS	Loss of Signal
LV	Launch Vehicle
MNVR	Maneuver
MCC	Midcourse Correction
MCC-H	Mission Control Center - Houston
MDC	Main Display Console
MGA	Middle Gimbal Angle
MSFN	Manned Space Flight Network
MTCS	Move to Command Seat
MTLEB	Move to Lower Equipment Bay
MTVC	Manual Thrust Vector Control
NAV	Navigation

OPT	Optics
ORDEAL	Orbital Rate Drive Earth and Lunar
OSS	Optical Subsystem
PAD	Data Voiced to Crew From Ground
PB	Pushbutton
PC	Plane Change
PDI	Powered Descent Initiation
PGNCS	Primary Guidance, Navigation, and Control System
PHS	Phasing
PIPA	Pulse Integrating Pendulous Accelerometers
PLM	LM Pitch Angle
PRO	Proceed
PROG	Program
PROP	Propellant
R	Range
RCS	Reaction Control System
RDOT	Range Rate
REFSMAT	Reference Stable Member Matrix
RHC	Rotation Hand Controller
RR	Rendezvous Radar
S	Shaft
SC	Spacecraft
SCS	Stabilization and Control System
SCT	Scanning Telescope
SECS	Sequence Events Control System
SEF	Small End Forward
SEP	Separation
S-IVB	Saturn S-IVB Stage
SM	Service Module
SPS	Service Propulsion System
S/U	Setup
SXT	Sextant
SYNC	Synchronize
TEI	Tranearth Injection
TEMCC	Tranearth Midcourse Correction

TFI	Time From Ignition
THC	Translation Hand Controller
THETA	Angle Between SC +X Axis and Local Horizontal
TIGN	Time of Ignition
TLI	Translunar Injection
TLM	Telemetry
TLMCC	Translunar Midcourse Correction
TPF	Terminal Phase Finalization
TPI	Terminal Phase Initiation
TRUN	Trunnion
TVC	Thrust Vector Control
VG	Velocity to be Gained
VHF	Very High Frequency
(XX:XX)	Indicates GET From Liftoff in Hours:Minutes
(XXX:XX:XX)	Indicates GET From Liftoff in Hours:Minutes:Seconds
(XXX,XXX/XXX,XXX)	Roll, Pitch ORDEAL/Pitch INERTIAL, Yaw
(XX,XX,XX)	Local Vertical DV's

#### Tracking Stations

ANG	Antigua Near Space Support Station
BDA	Bermuda Near Space Support Station
CRO	Carnarvon Near Space Support Station
CYI	Canary Near Space Support Station
GYM	Guaymas Near Space Support Station
HSK	Honeysuckle Deep Space Support Station
HTV	Huntsville Near Space Support Station
MAD	Madrid Deep Space Support Station
MER	Mercury Near Space Support Ship
MIL	MILA Near Space Support Station
RED	Redstone Near Space Support Ship
TEX	Corpus Christi Near Space Support Station
VAN	Vanguard Near Space Support Ship

## 1.0 PURPOSE

This document contains the nominal GNCS crew procedures for the CSM-107 spacecraft which will be the target vehicle for the LM-5 active lunar orbit rendezvous. The procedures are given in the form of an onboard rendezvous checklist and as a set of detailed CSM procedures. Also included are onboard rendezvous checklists for fifteen LM rescue and abort cases. Detailed Test Objective H, Reference 8.1, subject "Landing LM Location" will be satisfied during this portion of the mission.

The purpose of the CSM Rendezvous Procedures document is to provide a single source of procedures information for use in flight planning, in crew training, and in preparing onboard data.

This is a control document, subject to review by all elements of the Apollo Program and to approval by the Procedures Configuration Control Board. Comments should be directed to Mr. Duane K. Mosel, Flight Procedures Branch, Flight Crew Support Division, Extension 5340 or Mr. Richard J. Otto, Jr., Apollo Flight Crew Support Group, Houston Operations, McDonnell Douglas Astronautics Company, Extension 6101.

## 2.0 INTRODUCTION

The CSM-107/LM-5 lunar orbit rendezvous exercise will begin during the thirteenth revolution with undocking at 100:15:00 and end at approximately 127:40:38 with post rendezvous station keeping. The CSM procedures during this period are divided into nine segments of major activities which are discussed in detail in Section 3.0.

A nominal CSM-107/LM-5 mission profile is contained in Figure (2-1). This figure shows the locations in time and relative positions in space of the most significant nominal mission events. Trajectory data used to generate the mission profile and timeline for procedures development were obtained from Reference 8.18. The rendezvous navigation update schedule assumed in the procedures was obtained from References 8.3 and 8.5. The schedule indicates tracking periods and assumes a one mark per minute frequency for both SXT and VHF marks taken during a track period. The minimum number of marks required during a tracking period are specified in the rendezvous checklist. However, it is recommended that more than the minimum number be planned since systems monitoring requirements or target visibility problems often pre-empt taking all the planned marks. In addition, the general rules for SXT/VHF marking as defined in Reference 8.4 should be followed.

A history of the CSM body attitudes during the rendezvous accompanies the major events discussed and is presented in Figures (2-2) through (2-7). Each figure illustrates the body attitudes with respect to the Moon, Sun, and Earth and indicates FDAI roll, pitch, and yaw gimbal angles and the ORDEAL pitch angle for significant events during each lunar orbit. The orbital position of the CSM at each event is assumed and no attempt is made to show the LM orbital position other than the indication of it being above (below) and behind (ahead) the CSM.

Sections 4.0, 5.0, and 6.0 contain the onboard nominal rendezvous checklist; a summary timeline and summary checklist for the nominal mission, and the procedures ground rules, detailed nominal mission procedures, and CSM attitude summary, respectively. Section 7.0 includes a description of the 15 abort and rescue cases as described in Reference 8.14. Also the one-page onboard rescue checklist and relative motion plot and pad page for each of the 15 abort and rescue cases are included. These cases are:

- 1) Partial DOI ( $< 25$  FPS) (CSM Active)
- 2) Partial DOI ( $\geq 25$  FPS) (CSM Active)
- 3) No PDI<sub>1</sub> + 12 (LM Active)
- 4) No PDI<sub>2</sub> + 12 (LM Active)
- 5)  $< 60$  No PDI<sub>1</sub> + 12 (CSM Active)
- 6)  $\geq 60$  No PDI<sub>1</sub> + 12 (CSM Active)
- 7)  $< 40$  No PDI<sub>2</sub> + 12 (CSM Active)
- 8) 40 - 90 No PDI<sub>2</sub> + 12 (CSM Active)

- 9)  $\geq 90$  No  $PDI_2 + 12$  (CSM Active)
- 10)  $PDI_1 < 10$  Variable Insertion (LM Active)
- 11)  $PDI_1 + 12$  (10-12.5 Minutes) (CSM Active)
- 12)  $PDI_1 + 14:12$  (12.5-15 Minutes) (CSM Active)
- 13)  $PDI_1 + 21:24$  Preferred Lift-off ( $T_2$ ) (CSM Active)
- 14)  $PDI_2 < 14.5$  Variable Insertion (LM Active)
- 15)  $PDI_2 + 19:22$  Preferred Lift-off ( $T_2$ ) (CSM Active)



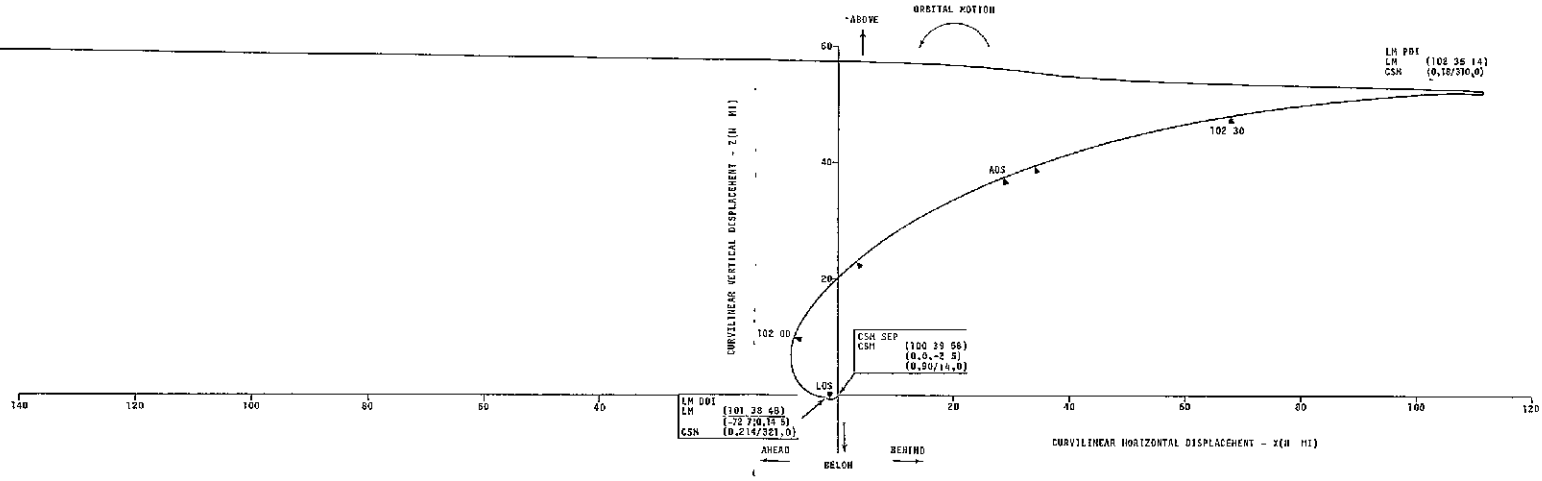
# MISSION 6 - RELATIVE MOTION FOR LM ACTIVE RENDEZVOUS LM CENTERED

FIGURE 2-1

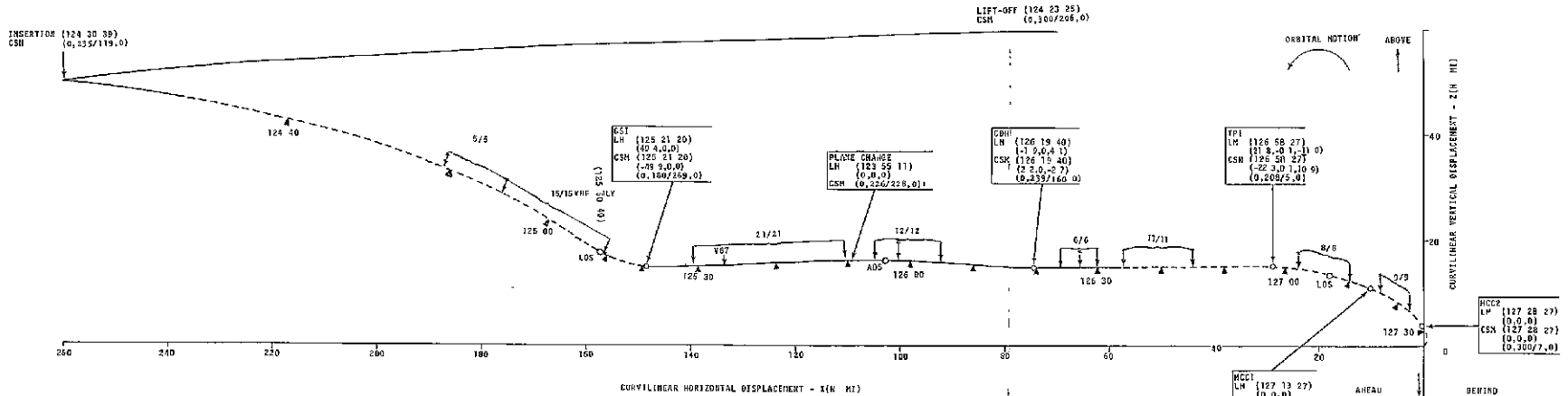
CSM SEP TO LM TOUCHDOWN

TOUCHDOWN (102.47 11)  
CSM (0.292/180.0)  
(221 N. H.)

- DARKNESS
- LOS EARTH IN VIEW
- LOS EARTH OUT OF VIEW
- LOS TEN MINUTES
- ORBITAL AND INERTIAL BALL ROLL ANGLE
- ORBITAL AND INERTIAL BALL PITCH ANGLE
- ORBITAL AND INERTIAL BALL YAW ANGLE
- 0,0/30,0
- [-.37 8,0,0] SPS-LOCAL VERTICAL DELTA VELOCITY COMPONENTS
- \* REINITIALIZE H-MATRIX



INSERTION TO TPI



FOLDOUT FRAME 1

FOLDOUT FRAME 2

MISSION G1 - LUNAR ORBIT RENDEZVOUS  
ATTITUDE TIME HISTORY FOR THE CSM

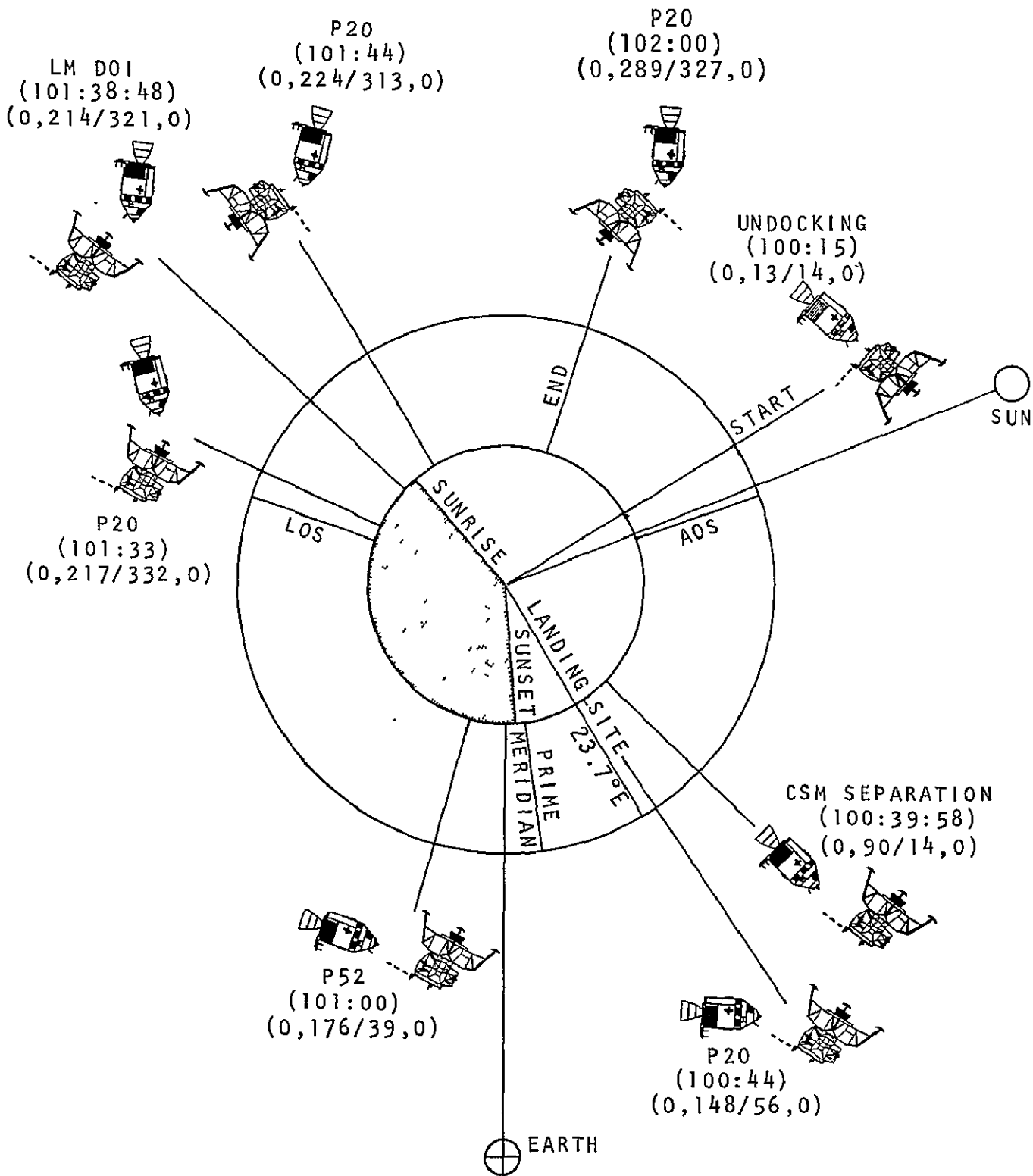
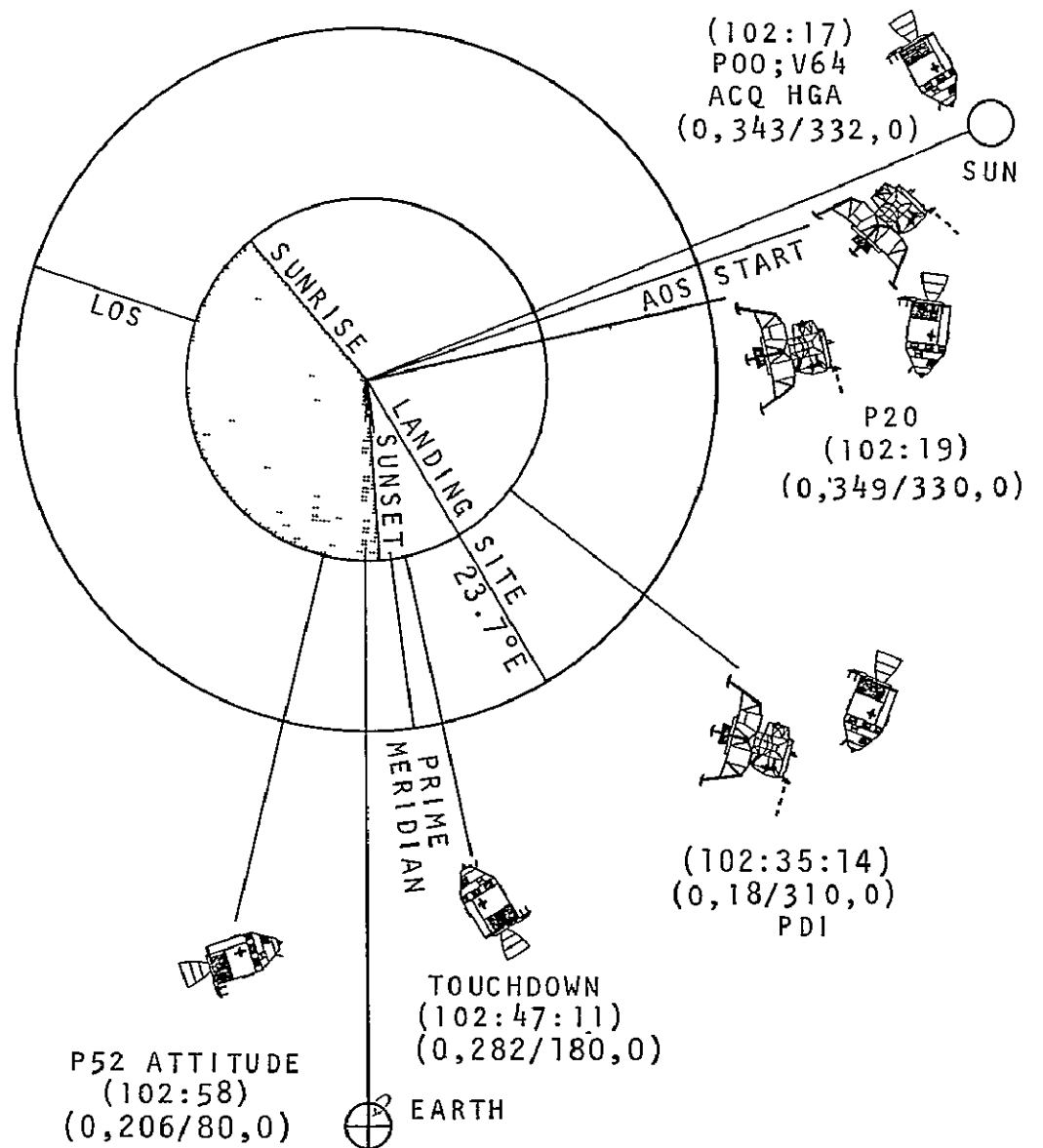
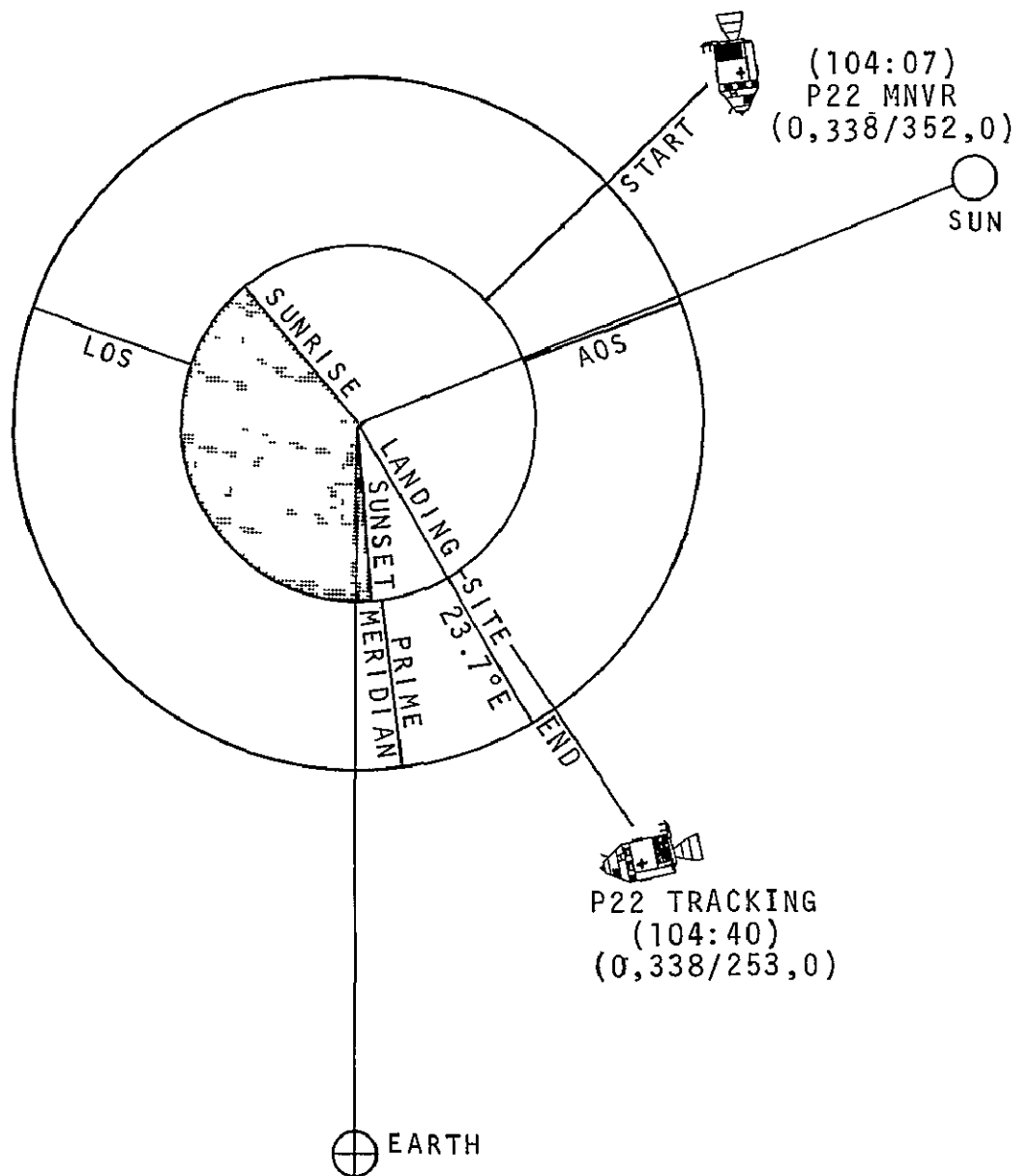


FIGURE 2-3

MISSION G1 - LUNAR ORBIT RENDEZVOUS  
ATTITUDE TIME HISTORY FOR THE CSM



MISSION G1 - LUNAR ORBIT RENDEZVOUS  
ATTITUDE TIME HISTORY FOR THE CSM



MISSION G1 - LUNAR ORBIT RENDEZVOUS  
ATTITUDE TIME HISTORY FOR THE CSM

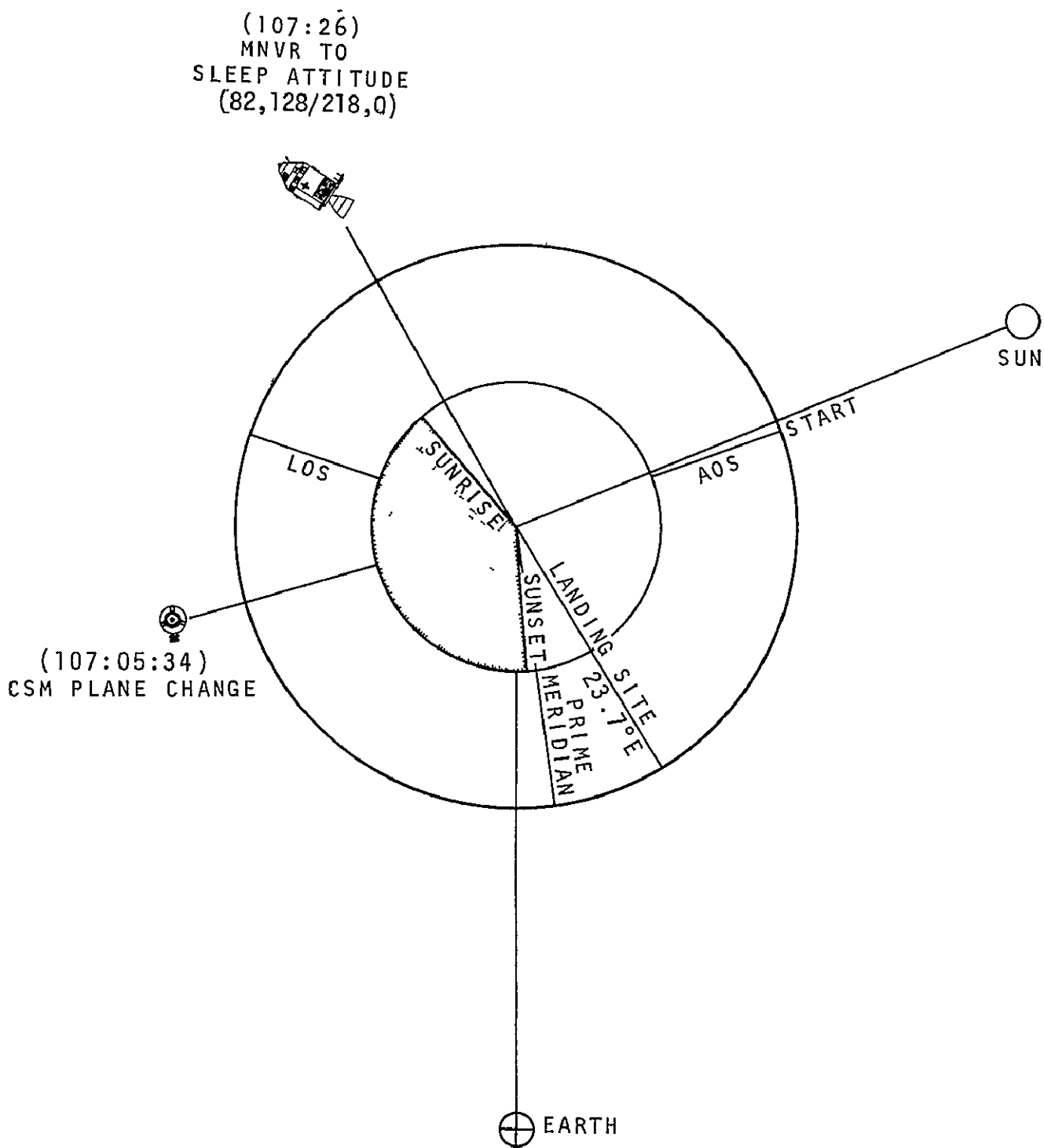


FIGURE 2-6

MISSION G1 - LUNAR ORBIT RENDEZVOUS  
ATTITUDE TIME HISTORY FOR THE CSM

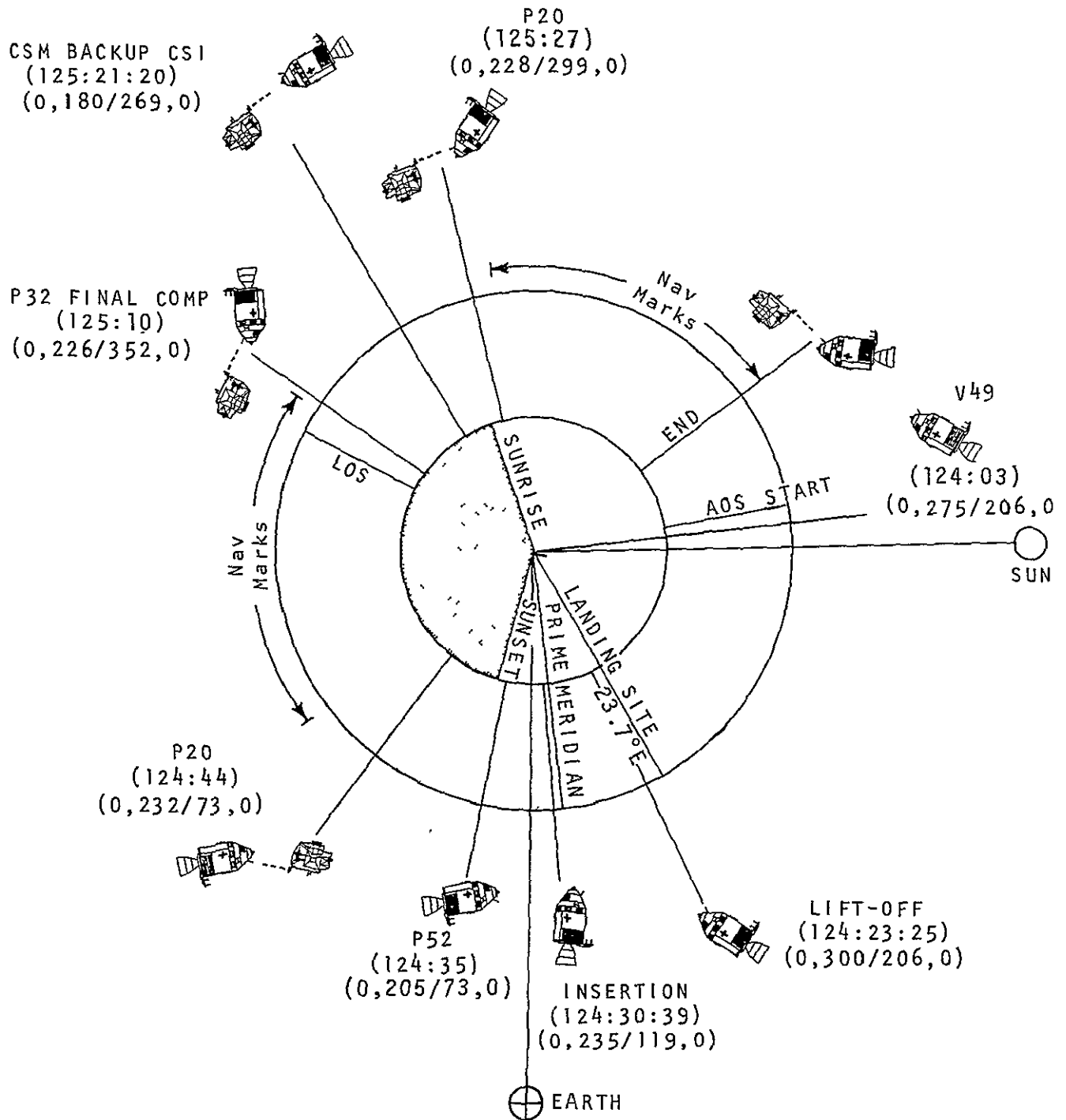
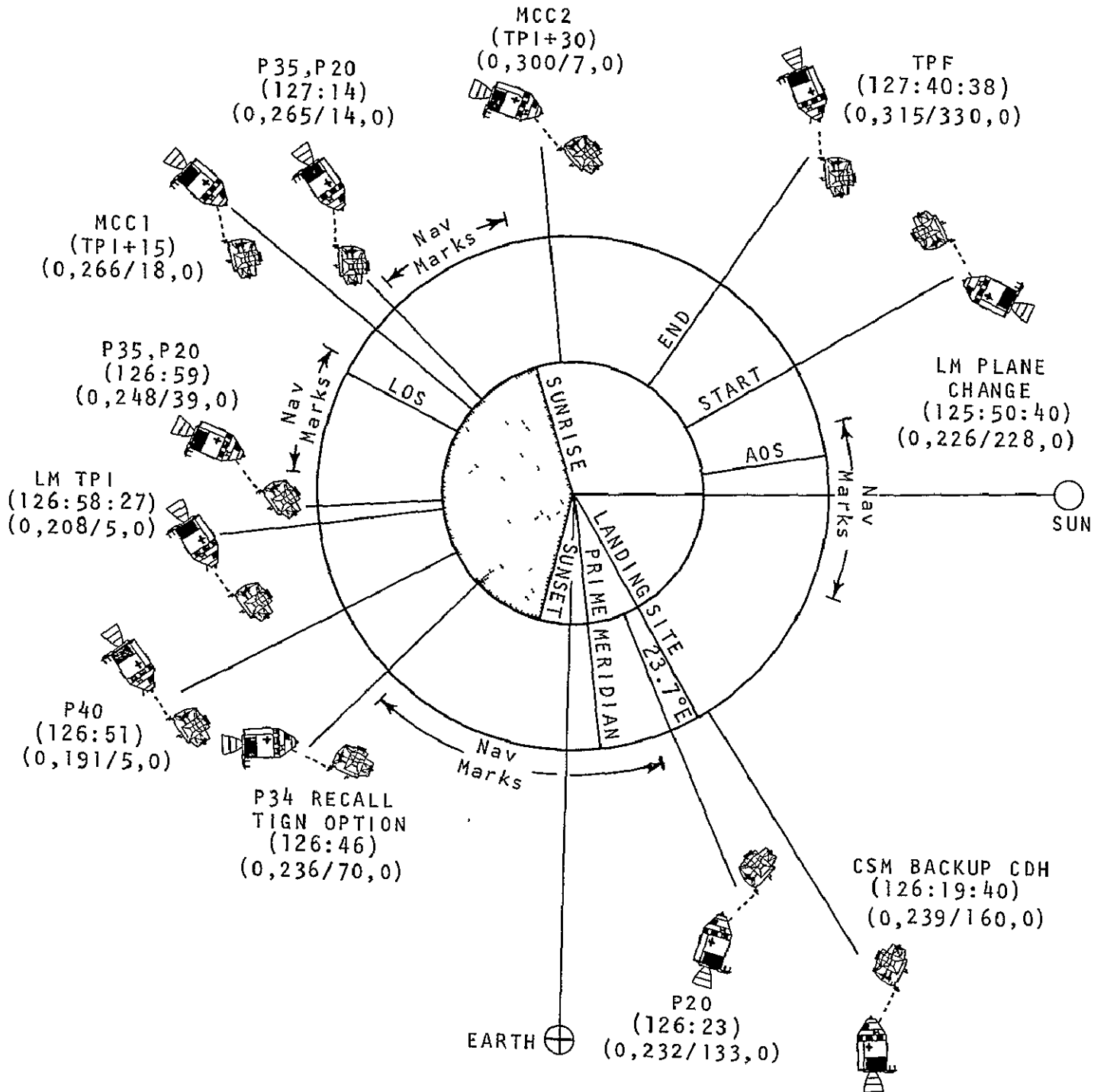


FIGURE 2-7

MISSION G1 - LUNAR ORBIT RENDEZVOUS  
ATTITUDE TIME HISTORY FOR THE CSM



### 3.0 DISCUSSION OF NOMINAL MAJOR EVENTS

#### 3.1 Undocking and Separation

The preparation for undocking includes obtaining a MCC-H uplink of the CSM vector and copying the separation maneuver pad at 99:10. Forty-three minutes prior to undocking an automatic maneuver to the undocking attitude is performed using extended verb 49. This attitude is identical inertially to the separation burn attitude except for the 14-degree yaw which is required during a pre-undocking LM AGS calibration. Prior to undocking, the CSM is yawed to zero degrees, a RR transponder check is made, the GDC is aligned to the IMU, the FDAI ORDEAL is verified, and the DAP is reloaded to reflect a CSM only configuration. At 100:15 undocking is performed after which the CSM will station keep in SCS control at about 40 feet. The CMP will then inspect and photograph the LM landing gear and descent engine bell as the LM does a 360-degree yaw maneuver. Prior to the CSM-active separation burn at 100:39:58, the CMP will load the External DV Program, P30, with a minus 2.5 FPS  $VG_z$  (local vertical). The RCS Thrust Program, P41, will be called and an automatic maneuver will be made to the burn attitude which is shown in Figure (2-2). (This should be a very small maneuver since the undocking attitude was the inertial separation burn attitude.) The burn will be accomplished by thrusting aft in the CSM minus X direction (i.e., radially down) and increasing the DSKY  $VG_x$  (body) from a plus 2.5 FPS to 5 FPS. The HGA can be utilized for communication during the separation burn.



### 3.2 Descent Orbit Insertion

Following the CSM separation burn, the Rendezvous Navigation Program, P20, will be called and the CSM maneuvered automatically 42 degrees to the preferred track axis for LM radar, VHF range, and optics checks. At 100:52 the LM P76 DOI and PDI + 12 abort pads, and the CSM rescue pad will be copied. An IMU realign to REFSMMAT will be performed after sunset at 101:00 using the IMU Realign Program, P52. At approximately 101:10 CSM and LM state vectors will be uplinked by MCC-H. Since the CSM does not backup the DOI burn, its only function will be to monitor the LM burn and hold an attitude which provides radar transponder coverage. This will be done in Program P20 with SXT tracking along the preferred track axis. The Target DV Program, P76, will be loaded with the LM DOI burn parameters and these data incorporated when the burn is confirmed by the LM. LM DOI occurs at 101:38:48.

The attitude of the CSM from the CSM separation burn through LOS prior to the LM DOI burn is favorable for HGA communications.

### 3.3 Powered Descent Initiation

Following the DOI burn, Program P20 will be called and the CSM attitude will be trimmed to the preferred track axis, if required. The CMP will confirm that the rendezvous navigation program is tracking the LM correctly. A period of SXT/VHF marking is scheduled at 101:52. At 102:17 the CMP will cease tracking and maneuver in order to acquire MSFN with the HGA. At 102:19 Program P20 will be called and the CSM will be

maneuvered to the preferred track axis. Four minutes prior to PDI the CMP will enter Program P00. The DAP will be loaded with a maneuver rate of .2 degree per second in order to maintain the LM in the SXT during powered descent. Extended verb 49 is used to initiate the pitch down rate at one minute after PDI initiation. At 102:35:14 the LM powered descent will be initiated with nominal touchdown occurring at 102:47:11. The CSM has HGA coverage from AOS until the P20 tracking is initiated. HGA coverage is again acquired during the LM powered descent.

#### 3.4 Orbital Navigation

Following LM touchdown, a IMU realign to REFSMMAT will be performed at 103:01, using the IMU Realign Program, P52. The GDC will be aligned to the IMU and ORDEAL will be verified. At 103:17 the orbital navigation PAD will be copied. At 104:01 a manual maneuver to the tracking attitude will be performed. At 104:07 a pitch rate will be initiated to offset orbital motion during the P22 tracking sequence. The Orbital Navigation Program, P22, will be called at 104:07 and the PAD information will be loaded. The CMP will take five SXT marks on the landing site.

#### 3.5 CSM Plane Change

Following the P22 tracking, the CSM is maneuvered at 104:43 to acquire MSFN. At about 104:59, MCC-H uplinks the plane change REFSMMAT. The IMU is aligned to the plane change REFSMMAT using the gyro torquing technique in the IMU

Realign Program, P52, at 105:04. The GDC is then aligned to the IMU. At 105:27 the Ground Track Determination Program, P21, may be called. At 106:15 the plane change PAD is recorded and the CSM state vector and target load are uplinked by MCC-H. At 106:37 the CSM is maneuvered to the plane change burn attitude. P30 is called at 106:52 and the plane change burn parameters are loaded. The SPS thrusting program, P40, is entered at 106:56. The CSM plane change burn occurs at 107:05:34. At 107:08 the CSM reacquires MSFN and the lift-off REFSMMAT is uplinked into the CMC. The platform is aligned to the lift-off REFSMMAT at 107:14 using the same procedure described above. The CSM is then maneuvered to the rest attitude.

### 3.6 Concentric Sequence Initiation

Immediately following the insertion burn, a P52 IMU realign to REFSMMAT will be performed and the MCC-H will uplink the LM state vector to the CMC. The LM vector will be that computed by the LM after insertion and relayed to the ground.

Program P20 will then be called and an automatic trim maneuver will be made to the preferred track attitude. At 124:48 the CSI Targeting Program, P32, is called and the CSM backup CSI targeting parameters are loaded. The CSM CSI burn will be targeted for 125:21:20 which is identical to the LM TIGN. A period of SXT/VHF marking will then take place from 124:50 to 124:55 followed by a period of VHF only marks to 125:09. Concurrently with the VHF only tracking, the CMP will obtain the LM and CSM out-of-plane velocities from extended verb 90 for inclusion in the LM and CSM CSI targeting programs.

Program P40 will be called at 125:13 and an automatic pitch maneuver of 76 degrees will be made to the backup CSI burn attitude. At approximately 125:15 the LM will voice over its CSI solution for P76. The LM CSI burn occurs at 125:21:20. After verification of the nominal LM CSI burn, the CMP will incorporate the LM burn parameters in Program P76.

The CSM attitude, as specified in Figure (2-6) is compatible with HGA coverage from insertion through LOS at 125:08.

### 3.7 Constant Delta Height and Plane Change

At 125:27 approximately five minutes after the LM CSI burn, Program P20 will be called and an automatic maneuver of 30 degrees will be made to the preferred track axis. A period of SXT/VHF marks occurs from 125:29 to 125:50. At 125:32 after three SXT/VHF marks, the WR matrix (2000,2) will be loaded. Extended verb 90 will be called at 125:43 and the out-of-plane targeting parameters for the LM plane change maneuver will be computed and voiced to the LM. The CSM onboard state vectors are used instead of the LM state vectors, because the CSM knowledge of the out-of-plane positions with SXT tracking is more accurate than the LM knowledge of out-of-plane positions with radar tracking. Following the LM plane change burn at 125:50:40, the target DV parameters are incorporated into the LM state vector. Since the CSM normally does not backup the LM plane change burn, a trim maneuver to the preferred track axis should not be required when Program P20 is called at 125:53. SXT and VHF marks will be taken ~

from 125:53 to 126:05, at which time tracking is terminated and the CSM will voice to the LM an extended verb 90 out-of-plane solution. At 126:10 the CDH Targeting Program, P33, will be called and the CSM backup CDH burn will be targeted for 126:19:40 which is the LM TIGN. The RCS Thrust Program, P41, is called at 126:14 and the burn attitude maneuver is bypassed for the nominally small burn. Approximately four minutes before the LM CDH burn, the CMP copies the LM CDH pad for later loading of Program P76. Following the LM CDH burn at 126:19:40, Program P76 is called and the LM CDH burn incorporated into the CMC LM state vector.

The CSM attitude, as specified in Figure (2-7), is not compatible with HGA coverage from AOS until the end of the track period at about 126:05.

### 3.8 Terminal Phase Initiation

After completion of the LM CDH burn, Program P20 will be called which will request an automatic maneuver of 27 degrees to the preferred tracking attitude. SXT and VHF marks are scheduled for a period starting at 126:24. It is probable that sun interference in the SXT will limit the total number of SXT marks to 11 taken in darkness. At 126:30, Program P34 will be called and the CSM backup TPI burn data will be loaded with the elevation angle option.

After obtaining a CSM TPI TIGN, P34 will be terminated by recalling P20. SXT and VHF marks are scheduled from 126:34 until 126:45. After moving to the command seat, the CMP will verify the ORDEAL FDAI. He will then recall P34, and using the TIGN option with the LM computed LM TIGN, compute the CSM TPI backup burn parameters. However, if the LM PGNCSS has failed, the CMP will obtain a TPI solution based upon the elevation angle option. Program P40 will be called and an automatic

maneuver of 52 degrees will be made to the TPI burn attitude. The TPI burn will nominally be performed at 126:58:27 with a CSM to LM elevation angle of 208.3 degrees. After the LM has completed the burn, the CMP will incorporate the LM target DV in Program P76. As seen in Figure (2-7), the CSM has HGA coverage from prior to CDH through the TPI burn.

### 3.9 TPI to Station Keeping

After the TPI burn, Program P20 will be called and the CSM will be automatically maneuvered 34 degrees to the preferred track attitude. The CMP will move to the LEB during the maneuver, call the MCC Targeting Program, P35, and take SXT and VHF marks for eight minutes starting at 127:02. After obtaining the MCC1 solution in Program P35 he will compare it with the LM solution and call Program P41 in preparation for the backup burn. The CSM will not maneuver from the preferred tracking attitude. The MCC1 burn will nominally be performed by the LM at 127:13:27 (TPI plus 15 minutes). After MCC1 the CMP will incorporate the LM MCC1 Target DV in Program P76.

Following MCC1, Program P35 will be called and an automatic trim to the preferred tracking attitude will be made if required. SXT and VHF marks will be taken for a period of nine minutes terminating at 127:25. The MCC2 solution will be compared with the LM MCC2 solution, after which Program P41 will be called. The CSM will remain at the preferred tracking attitude while the LM performs MCC2 at 127:28:27 (TPI plus 30 minutes). After MCC2 the CMP will incorporate the LM Target DV in Program P76.

The CSM will then be maneuvered automatically 37 degrees to the COAS tracking attitude using extended verb 89 while the CMP moves back to the command seat. The Thrust Monitor Program, P47, will be called at a range of 1.25 nautical miles and VHF ranging data and V83 will be used to monitor the LM line-of-sight control and braking. Should the LM experience difficulty, the CSM will perform the line-of-sight control and braking. The braking gates are specified in the checklist of Section 4.0. TPF nominally occurs at 127:40:38.

#### 4.0 NOMINAL ONBOARD RENDEZVOUS CHECKLIST

The nominal CSM onboard rendezvous checklist is presented in this section. The rendezvous checklist was formulated to be compatible with crew operations in simulators, and in flight. Therefore, the checklist reflects procedures in an extremely abbreviated form. The narrative presented in Section 3.0 provides a word description of the checklist events. The rendezvous checklist procedures have in part been verified on a man-in-the-loop simulator. Additional simulations will occur before launch and the rendezvous checklist updated accordingly to produce a verified checklist.

The nominal onboard rendezvous checklist includes procedures for performing CSM GNCS activities required during the LM active rendezvous. Activities required for the operation and/or monitoring of systems other than the GNCS are included in the rendezvous checklist by the appropriate systems personnel.



CSM RENDEZVOUS  
RESCUE PADS

CSM SEP PAD

33	00	000	0	.
81	+ 0000.0	+ 0000 0	- 0002 5	
22	XXX	XXX	XXX	

DOI PAD

84	.	.	.
33	.	.	.

PDI<sub>1</sub> +12 ABORT PAD

84	.	.	.
33	.	.	.

"CSM RESCUE" PAD

PHAS	33	00	000	0	.
TPI(PDI < 10)	37	00	000	0	.
TPI(PDI > 10)	37	00	000	0	.

"CSM RESCUE UPDATE" PAD

PHAS	33	00	000	0	.
TPI(PDI < 145)	37	00	000	0	.
TPI(T <sub>2</sub> )	37	00	000	0	.

RESCUE TWO PAD

47	+	.	+	00000	
48		.	.		
33	00	000	0		
81		.	.	.	
22	XXX	XXX	XXX		
ΔV <sub>C</sub>	X	.	.	.	.
11	00	000	0	.	
37	00	000	0	.	
N					

CSI ONE

11		000	0	.
81	.	.	.	.
N				

P22 PAD

T1	.	.	.		(HOR)
T2	.	.	.		(LMK)
	.				NM (N OR S)
89	.	.	.	.	
	LAT	LONG/2	ALT		

NOMINAL LM IGNITION TIMES

CSI 11	00	000	0	.
PC 33	00	000	0	.
TPI 37	00	000	0	.

CSI TWO

11	00	000	0	.
81	.	.	.	.
N				

CSI THREE

11	00	000	0	.
81	.	.	.	.
N				

CSI FOUR

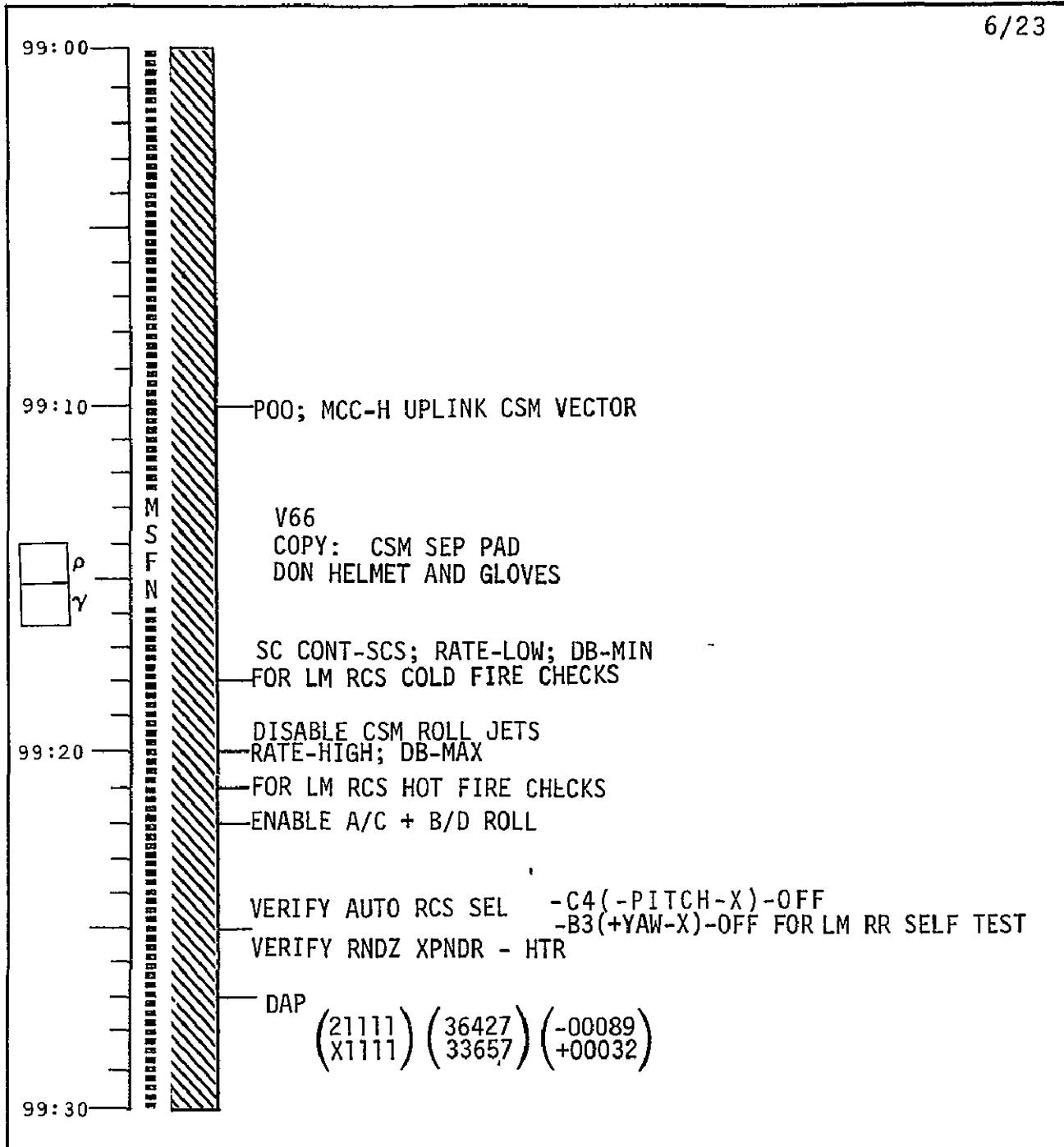
11	00	000	0	.
81	.	.	.	.
N				

CDH

13	00	000	0	.
81	.	.	.	.

TPI

37	00	000	0	.
81	.	.	.	.
59	.	.	.	.
LOS BT	XX	XX	XX	



99:30  
L  
O  
S  
99:40  
99:50  
100:00



V62-SC CONT-CMC-AUTO  
V49; MNVR TO UNDOCKING ATTITUDE (0,244/14,14)  
(INERTIAL SEP ATT EXCEPT 14° YAW)  
UNDOCK GET 100:15:00

CONFIGURE CAMERA:  
CM/SEQ/18/CEX-BRKT (RH WIN)  
MIR (f11,250, ∞) 6FPS, 15 MIN  
PREPARE TV CAMERA FOR USE (WINDOW NO.2)

CMC MODE-FREE (AS REQ FOR AGS CALIB)  
CMC MODE-AUTO (AFTER 32 SEC)  
VERIFY MAX DB FOR AGS CALIB  
SYSTEMS CHECKS AND SWITCH VERIFICATION  
WAIT FOR LM TO COMPUTE AGS ALIGN & GIVE GO, THEN  
YAW 14° LEFT AFTER LM AGS CALIB (0,313/14,0)

RR XPNDR CHECKS: (CONFIRM LM RR SELF TEST COMPLETE)  
RNDZ XPNDR ACTIVATION & SELF TEST  
cb RNDZ XPNDR FLT BUS - close (verifv)  
RNDZ XPNDR - HTR for 24 min (1 min if self test only)  
RNDZ XPNDR - PWR  
SYS TEST (Lh) - XPNDR; SYS TEST (rh) - A (RRT XMTR OUT PWR)  
SYS TEST ind -> 1 vdc

6/23

100:00

SYS TEST (rh) - B (RRT AGC SIG); RNDZ XPNDR - TEST (hold)  
 SYS TEST ind - >1 vdc  
 RNDZ XPNDR - OPERATE; SYS TEST ind - 0 -4.5 vdc  
 SYS TEST (rh) - C (RRT FREQ LOCK)  
 SYS TEST ind - <.8 vdc unlocked, > 4 vdc locked  
 SYS TEST (rh) - B

100:10

HAND CONTROLLER ADJ/ARMED; THC POWER - ON  
 SIMPLEX A RCV ONLY - B DATA  
 RECORD, FWD, LBR (AS REQUESTED BY LM)

GDC ALIGN TO IMU  
 ORDEAL (V83) (R=R=0)  
 SC CONT - SCS; LOAD DAP(11102); V46  
 DOCK PROBE CB(2)-1N  
 BMAGS-ATT 1/ RATE 2  
 START 16MM CAMERA  
 UNDOCKING (100:15:00)(0,13/14,0)

-25

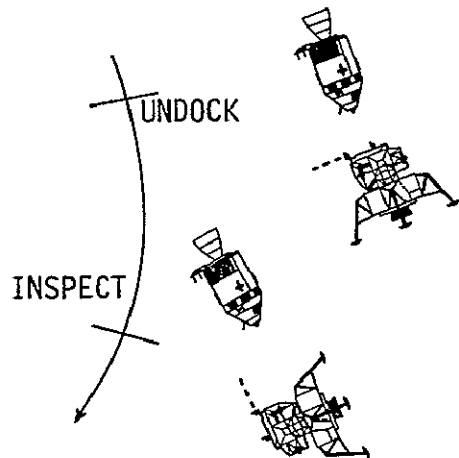
AUTO RCS SEL - B3 - MNA  
 DV CG-CSM C4 - MNB  
 RR XPNDR-PWR(VERIFY)

100:20

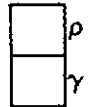
A  
O  
S

V64; ACQ HGA  
 PHOTOS: COLOR TV  
 INSPECT LM

(LM 360° YAW)



100:30



100:30  
-5  
-3  
100:40  
100:50  
101:00

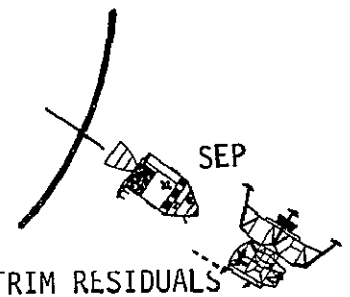
M  
S  
F  
N

SET EMS = 102.5  
BMAGS - RATE 2  
SC CONT - CMC - AUTO  
P30  
LOAD ( $VG_z = -2.5$ )  
P41 AUTO MNVR (TRIM)  
RCS SETUP

CSM SEP PAD					
33	00	:	000	:	0
81	+	0000.0	+	0000.0	- 0002.5
22	XXX		XXX		XXX

CSM SEP (100:39:58) (0, 0, -2.5)  
(THRUST AFT) (0, 90/14, 0)

(BURN 2.5, 0, 0 → 5, 0, 0) DON'T TRIM RESIDUALS  
THC AND RHC - LOCKED; FOUR ROLL THRUSTERS OFF  
P20; AUTO MNVR TO SXT TRACK (42°) (0, 148/56, 0)  
COORDINATE WITH LM  
VHF B - DUPLEX; RANGING - ON  
MONITOR LM RR CHECKS  
COMPARE EMS VHF AND V83 RANGE  
OPTICS CHECKS (ONLY DO NOT MARK)



DOI P76 PAD

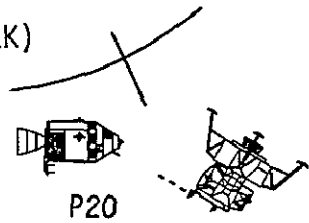
84	•	•	•
33	•	•	•

COPY  
PADS

PDI<sub>1</sub> +12 ABORT P76 PAD

84	•	•	•
33	•	•	•

P20  
(100:44)  
(0, 148/56, 0)



CSM RESCUE PAD

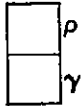
33	•	•	•
37	•	•	•
37	•	•	•

PHASING  
PDI<sub>1</sub> < 10  
PDI<sub>1</sub> > 10

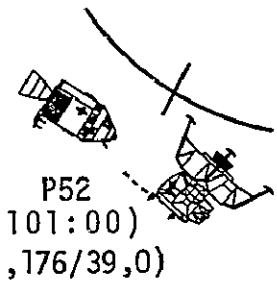
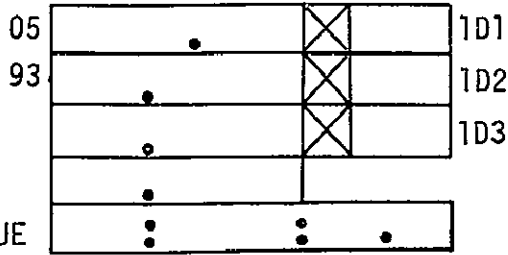
100:52  
R= 0.37  
R= 3.5

6/23

101:00  
 101:10  
 101:20  
 101:30

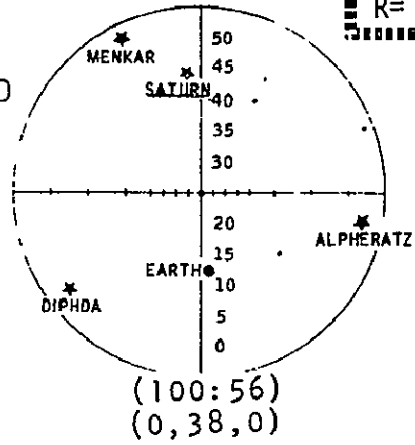


P52 (OPTION 3)



- GDC ALIGN TO IMU
- VERIFY ORDEAL (V83)
- POO; MCC-H UPLINK
- CSM AND LM VECTORS
- CONFIRM PROPER SOLO CONFIG
- ECS HOSES, COUCHES
- CAMERA, STOWAGE
- PANEL 10 SET FOR RELAY
- MASTER ALARM AMPLIFIER - RIGGED

101:09  
 R= 1.10  
 Ṙ= 4.8



101:26  
 R= 1.84  
 Ṙ= 2.9

SYSTEM CHECKS PRIOR TO LOS

LOS

101:30  
 101:40  
 101:50  
 102:00



VHF SIMPLEX A - REC ONLY - B DATA  
 (RECORD, FWD, LBR)  
 P20 AUTO MNVR TO SXT TRACK (67°) (0,217/332,0)

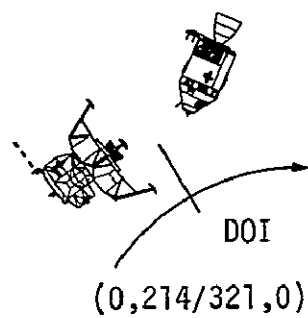
LM DOI (101:38:48)(-72.7, 0, 14.5)

VHF B - DUPLEX RANGING - ON  
 VHF RCV ONLY - OFF  
 COMPUTE RDOT FOR LM  
 CONFIRM LM DOI

P76 (ADD: 20 SEC); V82 (LM R2=2)(60X9)  
 P20 AUTO MNVR TO SXT TRACK (TRIM) (0,224/313,0)

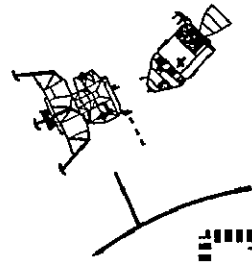
START CAMERAS REMOTE OPERATION  
 INITIATE OPTICS TRACK ONLY

V 93; V57; V87

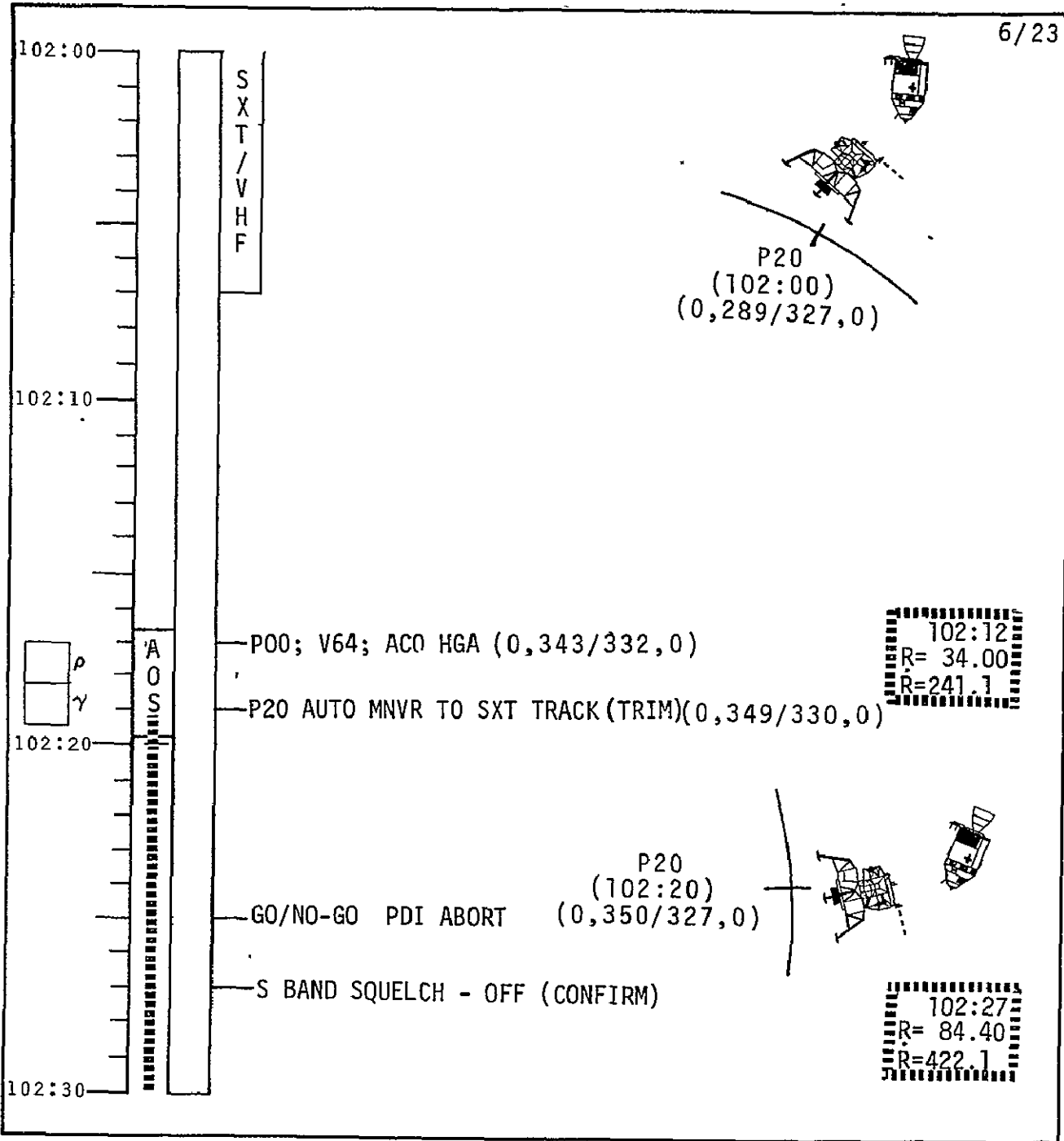


101:42  
 R= 3.67  
 R= 70.2

P20  
 (101:44)  
 (0,224/313,0)



101:57  
 R= 13.02  
 R= 68.7





102:30  
 102:40  
 102:50  
 103:00

MSFN

P00; V48 (11101) ; V49 LOAD (0,140,0)  
 (X1111)

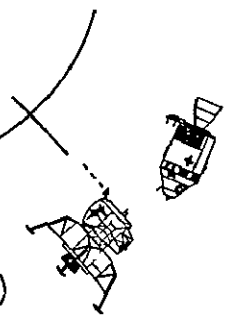
OPTICS - RESOLVED/MED/ZERO-OFF  
 TRACK LM MANUALLY

(EVENT TIMER START)

LM PDI (102:35:14)

PROCEED; PITCH DOWN  $-.2^{\circ}/\text{SEC}$   
 TO P52 ATT (0,206/80,0)

PDI  
 (0,18/310,0)



SWITCH TO OMNI-C (AS REQUIRED)

MSFN ENABLES S-BAND RELAY

LM TOUCHDOWN (102:47:11)

MAN ATT PITCH - ACC CMD

TOUCHDOWN  
 (0,282/180,0)



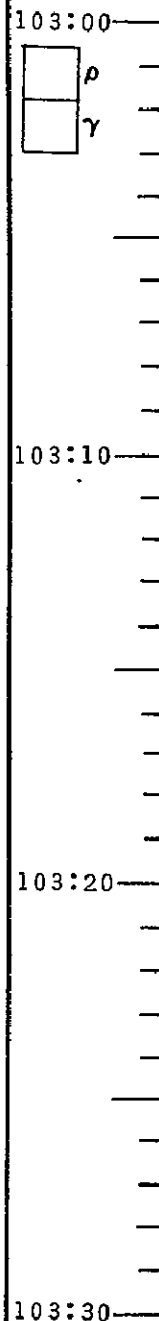
V44 SET LUNAR SURFACE FLAG

KEEP PITCHING TO P52 ATT  
 VHF RANGING - OFF

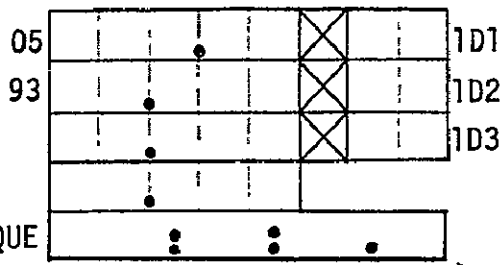
VHF T/R (PANEL 9) TO RECEIVE  
 RR XPNR - OFF

V46; STOP PITCH; MAN ATT PITCH - RATE CMD AT (0,206/80,0)





P52 (OPTION 3)

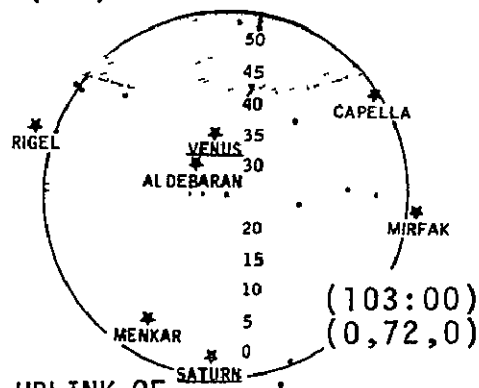


GDC ALIGN

VERIFY ORDEAL (V83)



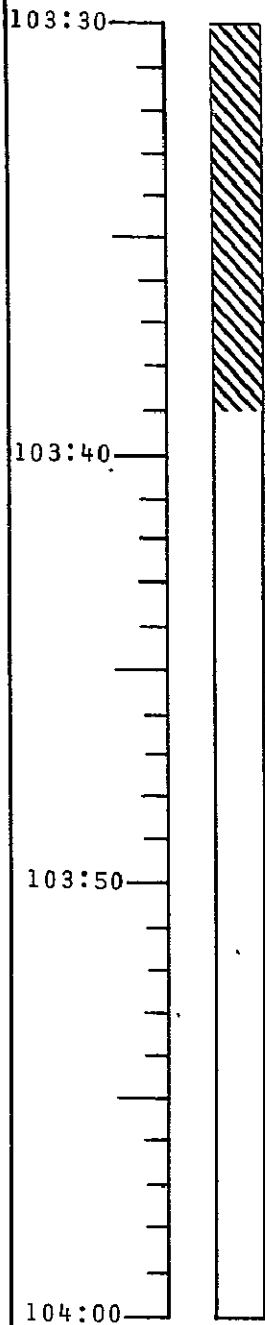
P52  
 (103:01)  
 (0,215/80,0)



COPY P22 PAD  
 AT 104:25  
 (POSSIBLE P27 UPLINK OF  
 RLS AND CSM S/V)

(103:00)  
 (0,72,0)

MNVR TO MSFN SUGGESTED ATT  
 SYSTEMS CHECKS PRIOR TO LOS



104:00

S/C CONT-SCS; MNVR +X BELOW HORIZON 2° (0,352,0)  
P00; V48 (11100) ; V49 LOAD (0,330,0)  
(X1111)

CMC - AUTO (0,338/352,0)  
PRO - PRO  
MAN ATT (PITCH) - ACCEL CMD  
P22:

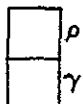
RESOLVED - MED - ZERO - CMC  
F 06 45 (R3=MGA)  
PRO  
F 05 70 LOAD 10000  
F 06 89 LOAD LANDING SITE  
LAT \_\_\_\_\_  
LONG/2 \_\_\_\_\_  
ALT \_\_\_\_\_

OPTICS ZERO - OFF; PRO  
06 92 SHAFT, TRUNNION

OPTICS MODE - MAN  
F 51

NOTE: POSSIBLE ALARM  
407 IF TRUN>50°  
RECALL 06 92  
AND RESET WHEN<50°

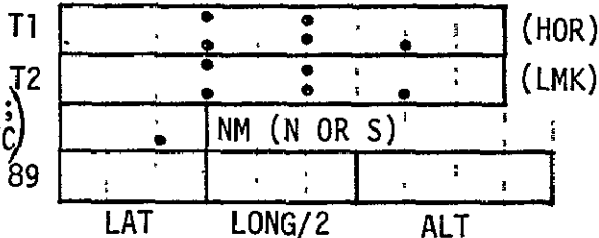
104:10



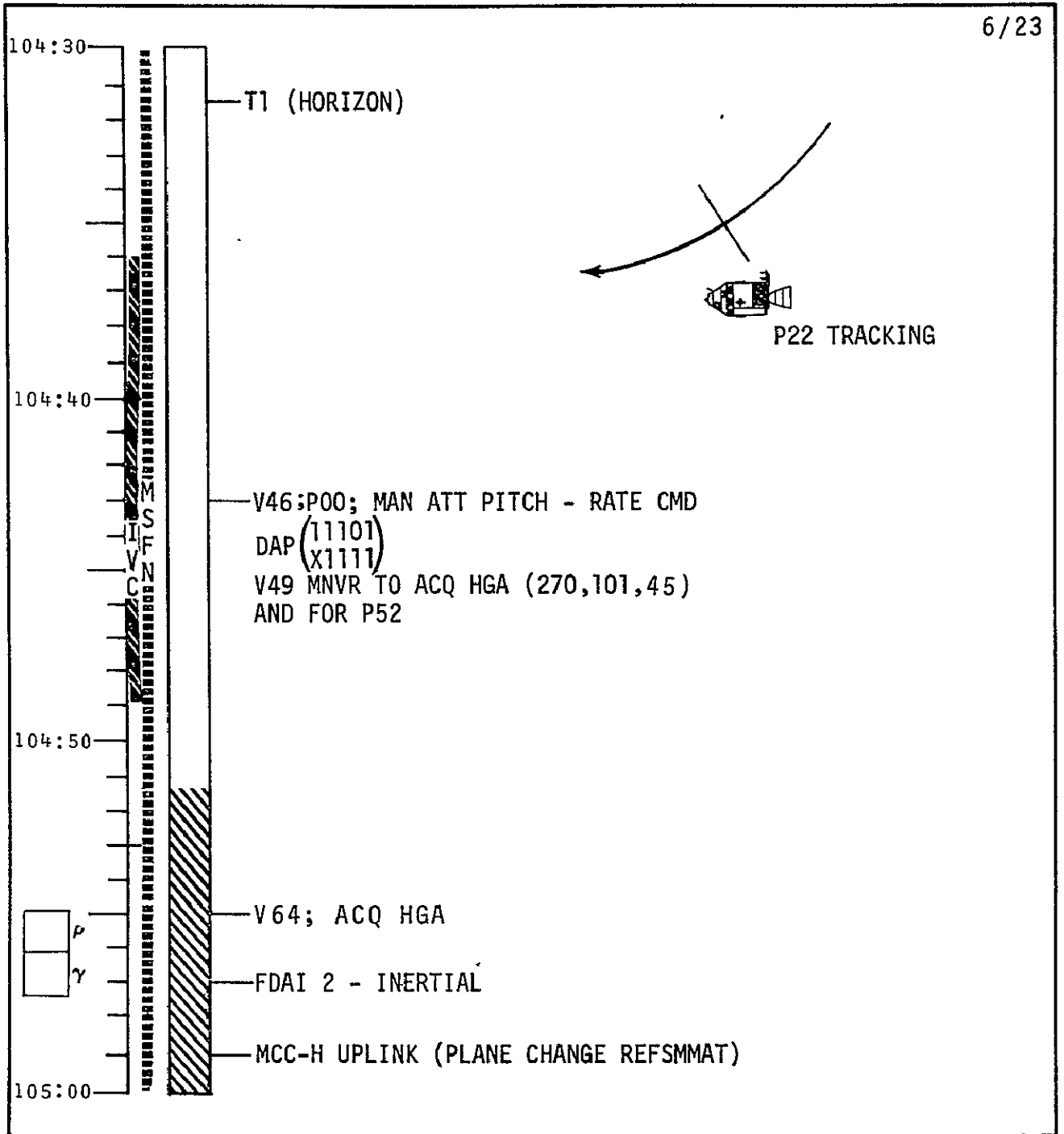
A  
O  
S

104:20

(TAKE 5 MARKS 30 SEC APART;  
HOLD AT F 06 49 FOR 30 SEC)



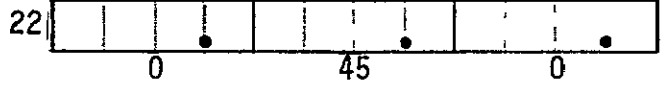
104:30



105:00  
105:10  
105:20  
105:30



CMC MODE - FREE  
P52 (OPTION 1) PLANE CHANGE REFSMMAT  
GYRO TORQUING



CMC - HOLD

GDC ALIGN TO IMU  
EAT PERIOD

SYSTEMS CHECKS PRIOR TO LOS  
(P21 IF DESIRED)

105:30  
105:40  
-25  
105:50  
106:00



MNVR AS REQUIRED FOR PHOTOGRAPHY

P=0

ROLL AS REQUIRED

Y=0

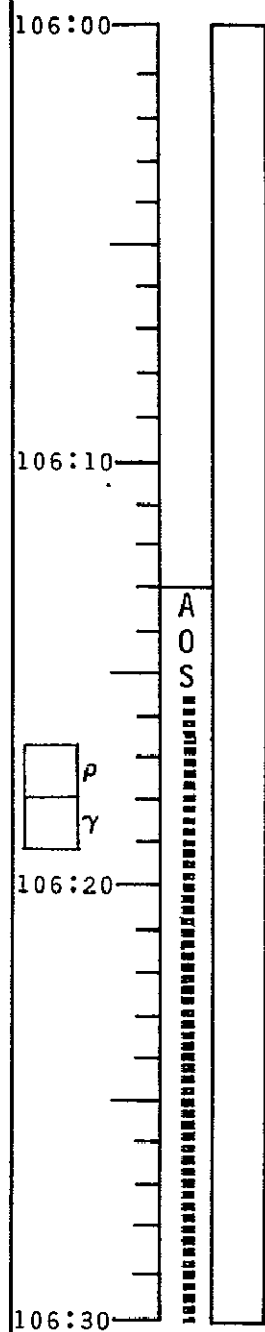
V37E 21E

F 04 06 R1 00002, SPECIFY VEHICLE  
R2 00001, CSM  
PRO

F 06 34 GET LAT, LONG  
LOAD DESIRED GET  
PRO

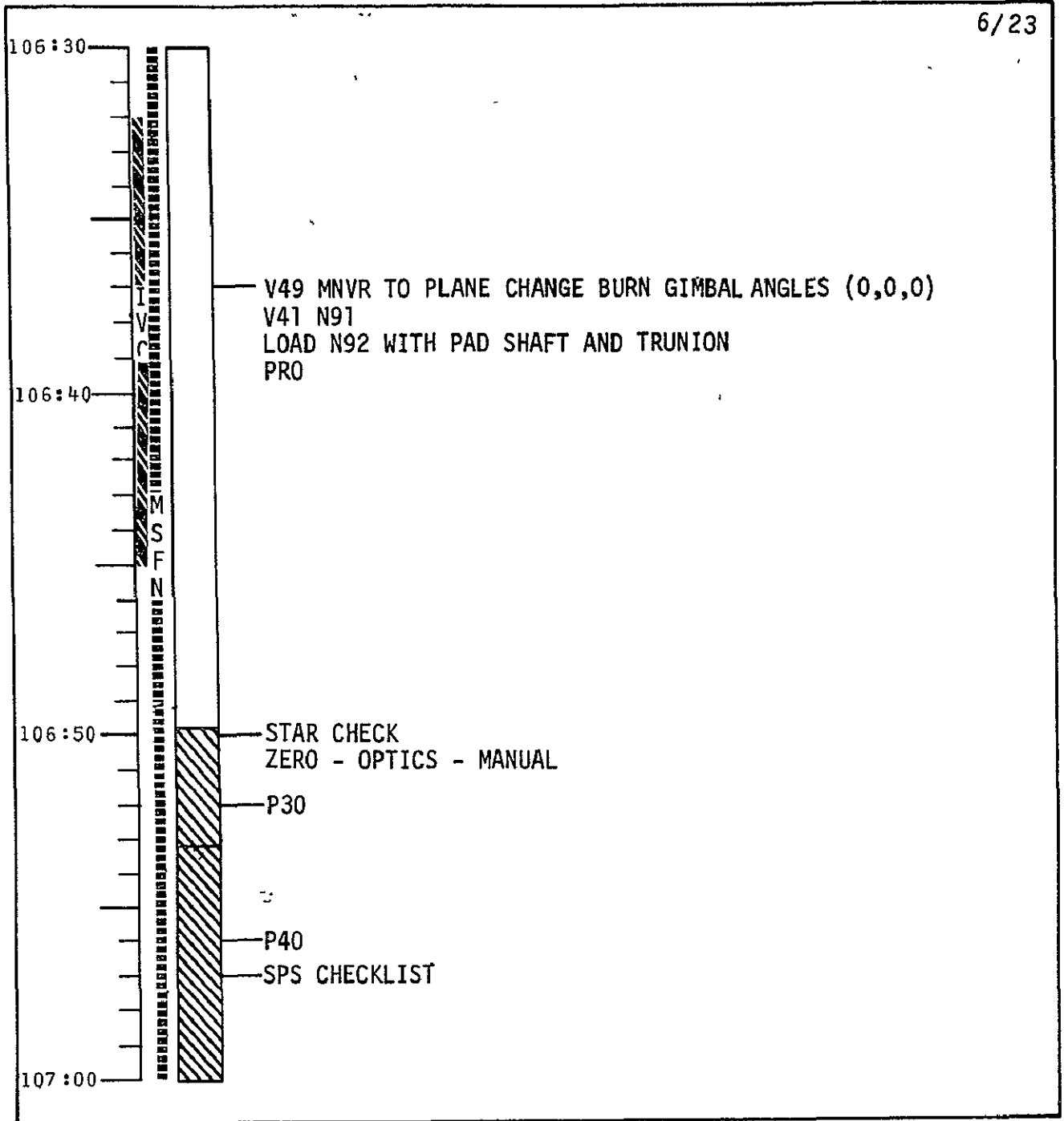
F 06 43 LAT, LONG, ALT  
(RECYCLE) V32E TO 2 (INCREMENT GET 10 MIN)  
(EXIT) PRO

F37



P00;V64;ACQ HGA  
MCC-H UPLINK CSM S/V AND TARGET LOAD  
RECORD PLANE CHANGE MNVR PAD





6/23

107:00

$\rho$

$\gamma$

107:10

r

N

107:20

L

O

S

107:30

BURN WITH  
APEX TOWARD  
NORTH  
(0,0,0)

PLANE CHANGE

CSM PLANE CHANGE (107:05:34) (0,16.6,0)

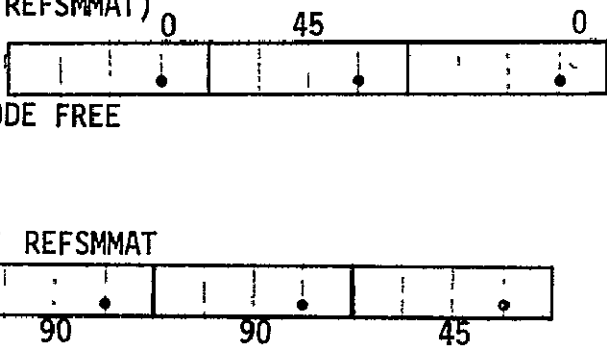
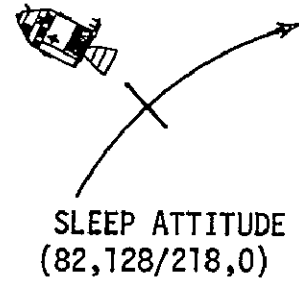
P00; V64; ACQ HGA  
MCC-H UPLINK (LIFTOFF; REFSMMAT)

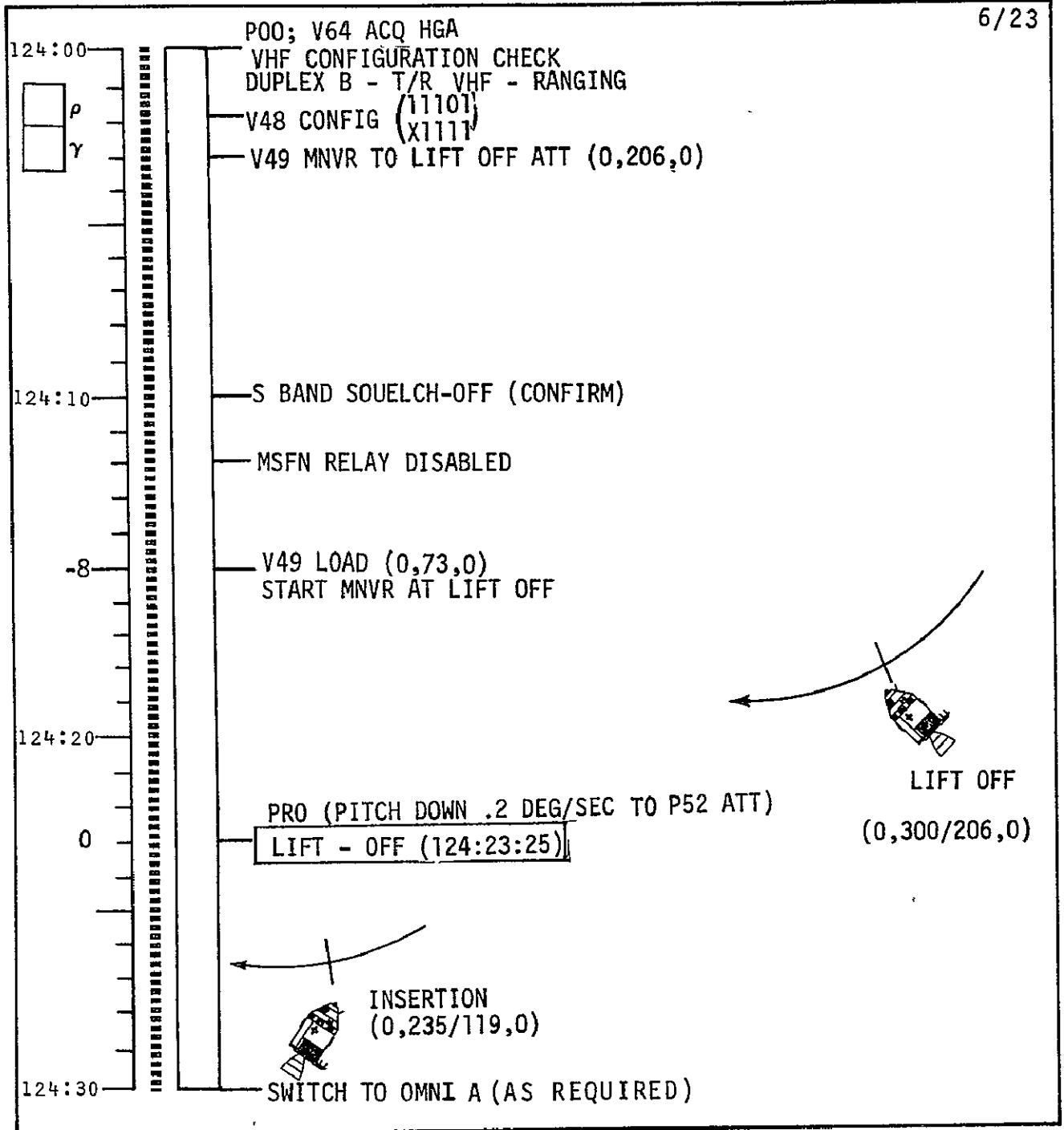
V49: LOAD → 22  
MNVR COMPLETE - CMC MODE FREE

P52 (OPTION 1) LIFT OFF REFSMMAT  
GYRO TORQUING

CMC - HOLD  
GDC ALIGN TO IMU  
ORDEAL (V83)

BEGIN REST AND EAT PERIOD  
(82,128/218,0)  
FOLLOW FLIGHT PLAN UNTIL 124:00





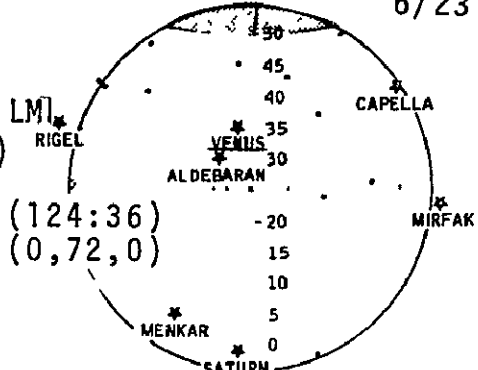
6/23

124:30  
-37  
-32  
124:50  
-22  
125:00

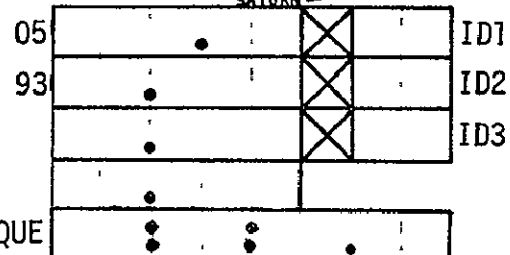
M  
S  
F  
N  
S  
X  
T  
V  
H  
F  
V  
H  
F  
O  
N  
L  
Y

LM INSERTION (124:30:39)

VHF RANGING LOCK ON; RELAY R TO LM  
 AUTO MNVR COMPLETE (0,202/73,0)  
 V48 (11102)  
 (X1111)  
 P52 (OPTION 3)



124:35  
 R=251.7  
 R=-430.5



P00; V64;  
 MCC-H UPLINK LM VECTOR  
 ZERO OPTICS  
 REQUEST LM TURN ON  
 TRACKER LIGHT

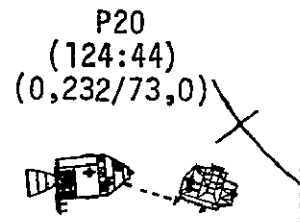
P20; AUTO MNVR TO SXT TRACK (TRIM) (0,232/73,0)

11				CSI TIGN
55	+00001,	+208.30	+130.00	N, ELEV, CENTANG
37				TPI TIGN

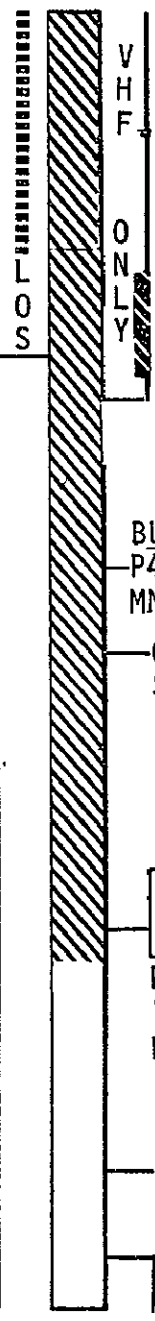
PRO TO N45

IF VHF; V93; VHF ONLY  
 IF NO VHF; V88; SXT ONLY

V93 (NOT BEFORE 5 SXT MARKS PROCESSED)  
 STOP SXT MARKS  
 V88 ; PRO ON V51  
 V90(R2=2) (N16=CSI TIGN) VOICE LM Y DOT TO LM =   
 V90(R2=1) (N16=CSI TIGN) CSM Y DOT =   
 V87  
 V16N45



125:00  
 -12  
 125:10  
 -8  
 -6  
 125:20  
 0  
 -51  
 125:30



SYSTEMS CHECKS AND EVENT TIMER

125:05  
 R=165:41  
 R=-139.0

PRO ON N45

75			
81			

$\Delta H$   
 $\Delta T$ -CSI/CDH  
 $\Delta T$ -CDH/TPI  
 $\Delta V$ CSI-LV

LOAD N81 VGY WITH (-) CSM YDOT

BUS TIES  
P40; AUTO

82			
----	--	--	--

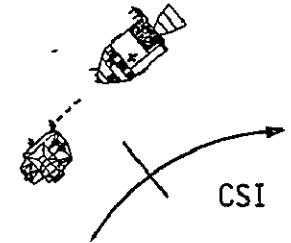
$\Delta V$ CDH-LV

MNVR (76°)(0,156/269,0) V56 (TERMINATE P20)

COPY LM CSI SOLUTION  
SPS CHECKLIST

84			
33			

LM CSI (125:21:20) (49.4, 0, 0)  
 CSM CSI (125:21:20) (-49.9, 0, 0)  
 P76(ADD: 23 SEC) (0,180/269,0)  
 V82(LM R2=2)(45x45)  
 BUS TIES



P20; AUTO MNVR TO SXT TRACK (30°)(0,228/299,0)

V57; V87

125:30

125:40

-30

125:50

-29

-27

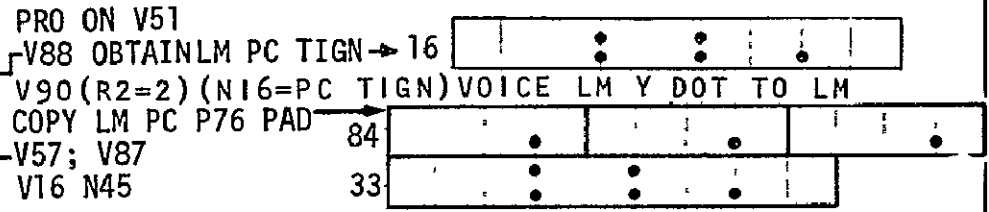
-24

126:00

S  
X  
T  
/  
V  
H  
F

PRO ON V51 AFTER 3 MARKS PROCESSED  
 V67; LOAD N99 (+02000,+00020,+00001)  
 V57  
 V16 N45

125:36  
 R= 113.77  
 R=-129.1



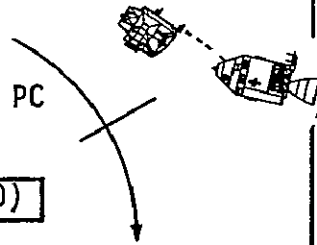
IF NO PLANE CHANGE CONTINUE MARKS  
 PRO ON V51; V88  
 P76 LOAD LM PC BURN DATA

LM PLANE CHANGE (125:50:40) (0,226/228,0)  
 P76 INCORPORATE

S  
X  
T  
/  
V  
H  
F

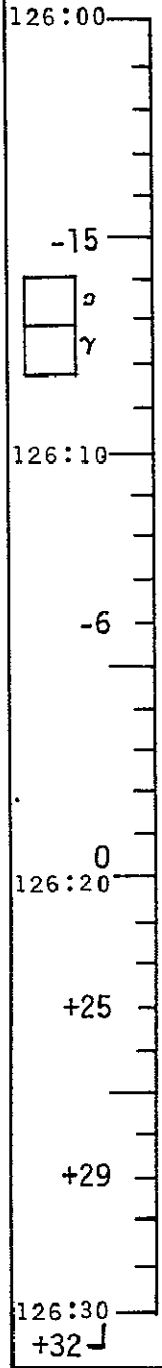
P20 V57; V87

V93 AFTER THREE MARKS PROCESSED



A  
O  
S

6/23



PRO ON V51; V88

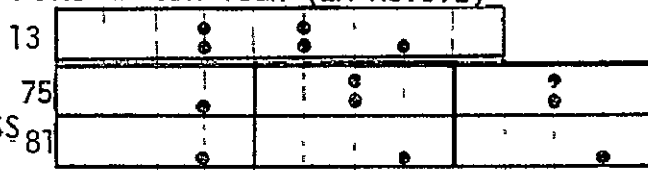
V90(R2=2)(N16=CDH TIGN) VOICE LM Y DOT TO LM =   •    
 V90 (R2=1) (N16=CDH TIGN) CSM Y DOT =   •  

```

126:05
R = 94.61
R = -131.4
  
```

LOAD LM CDH TIGN (LM ACTIVE)

P33  
FINAL COMP



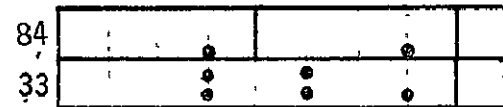
```

ΔH
ΔT-CDH/TPI
ΔT-TPI/TPI
ΔV CDH-LV
  
```

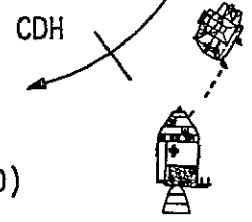
P41; BYPASS  
MNVR FOR  
SMALL BURNS;  
V56  
RCS SETUP

LOAD N81 WITH (-) CSM Y DOT

LM CDH P76 →



LM CDH (126:19:40) (-1.9, 0, 4.1)  
 CSM CDH (126:19:40) (2.2, 0, -2.7)  
 P76 (0, 239/160, 0)



P20; AUTO MNVR TO SXT TRACK( 27° )(0,232/133,0)

V57; V87

```

126:26
R = 69.91
R = -119.8
  
```

V93 (AFTER 3 MARKS)  
 CONTINUE MARKS UNTIL SUNSHAFTING)

PRO ON V51



TPI TIGN

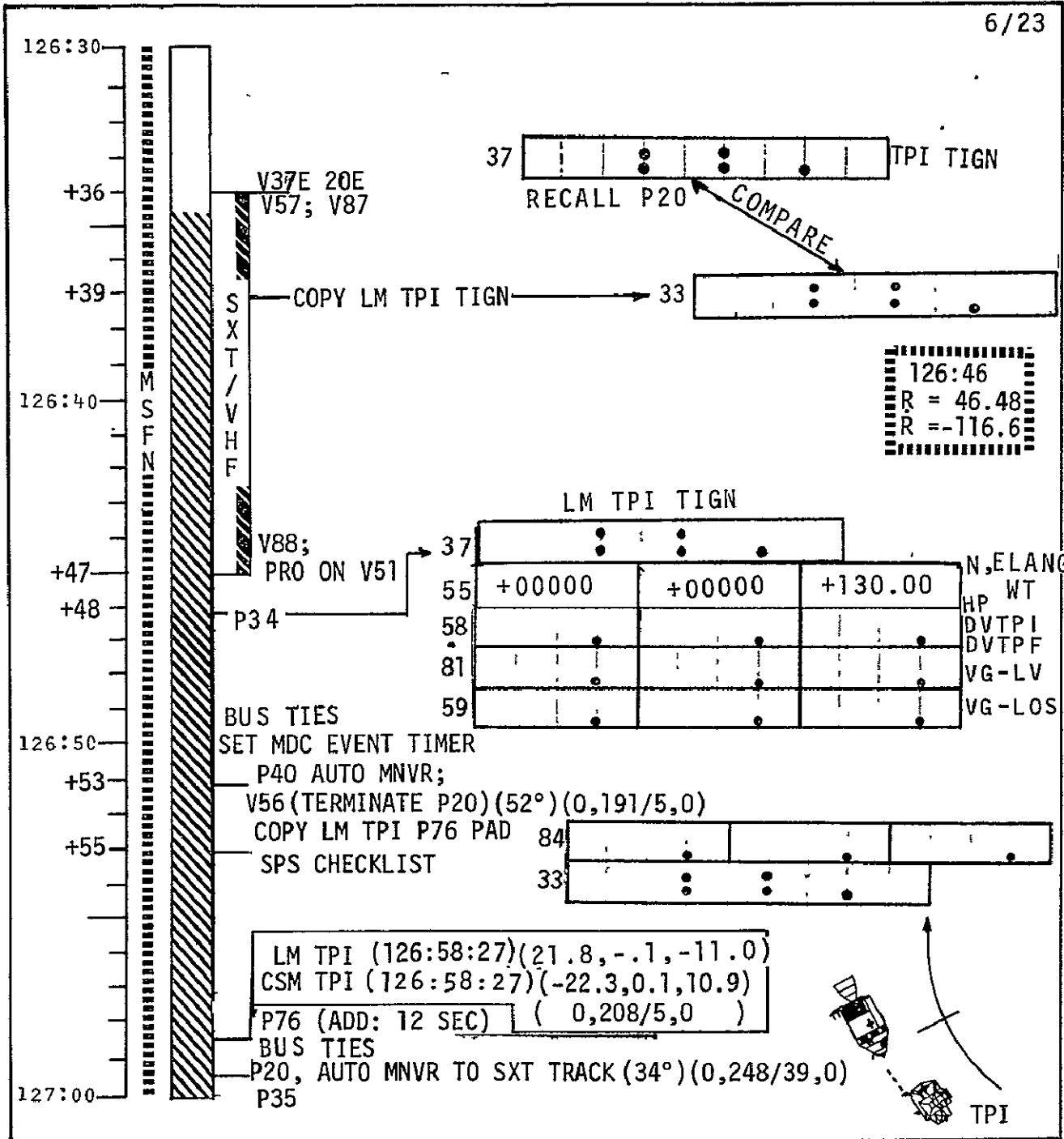
P34 (ELEVATION  
 ANGLE OPTION)



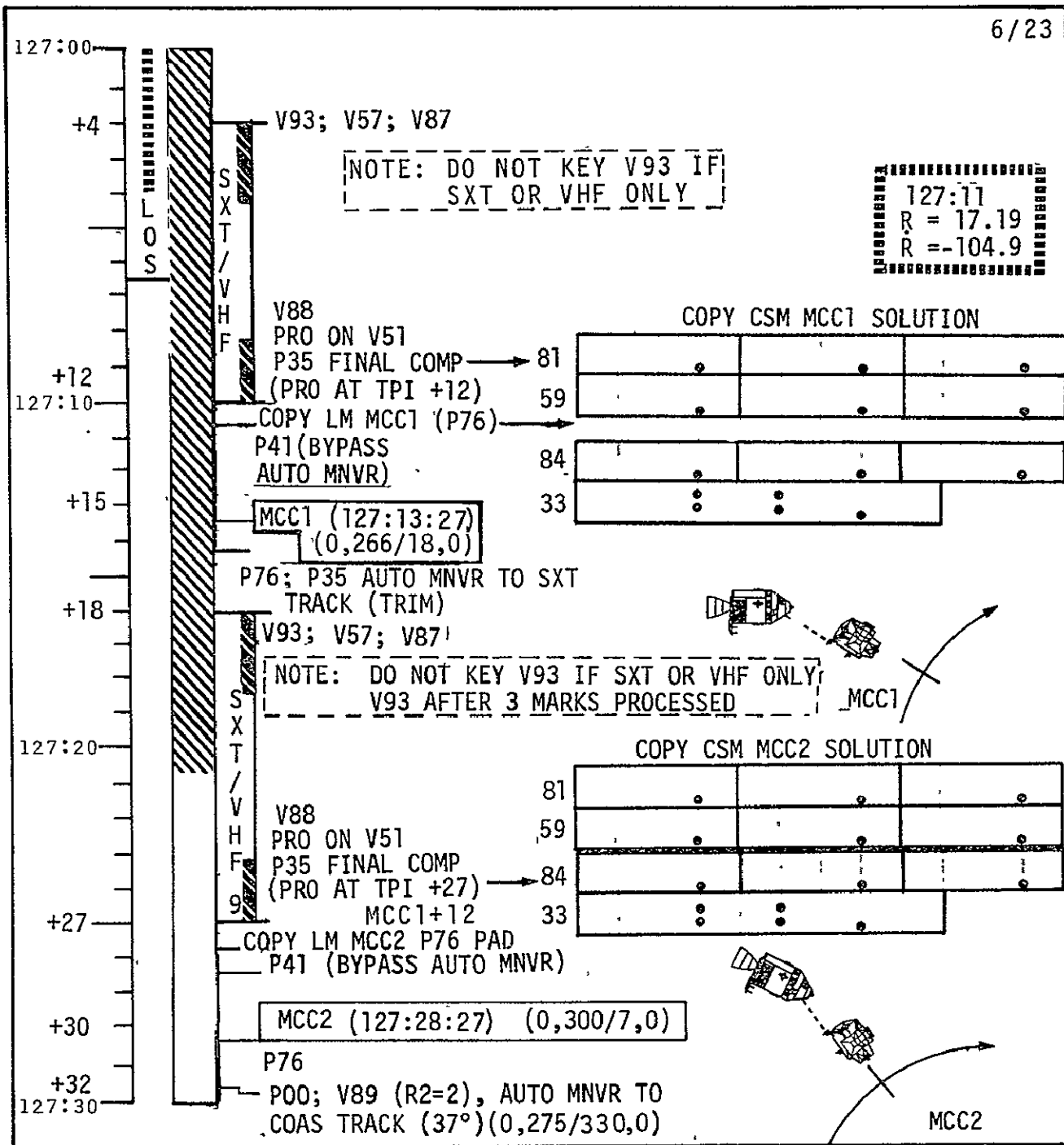
N, ELANG, WT

+00000 | +208.30 | +130.00  
 PRO ON N45

6/23







127:30

16 RCS JETS - ON

P47; V83 AT R = 1.25 N.M.

```

+-----+
| 127:26 |
| R = 5.60 |
| Ṙ = -52.2 |
+-----+

```

BRAKING GATES

+38

$\dot{R}$ (FPS)	R(FT)	R(N.M.)	RETICLE ANGLE (DEG)
30	6000	1.0	.13
20	3000	.5	.26
10	1500	.25	.54
5	500	.08	1.6
	300	.05	2.7
	200	.03	4.0
	100	.02	8.5

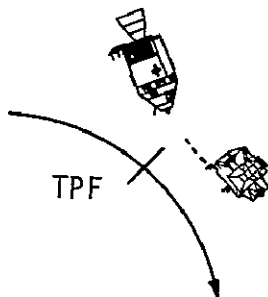
```

+-----+
| 127:41 |
| R = 0.06 |
| Ṙ = -12.3 |
+-----+

```

127:40

TPF (127:40:38)



127:50

- DOCK CHECKLIST;
- CB DOCK PROBE (2) - 1N
  - CB SECS ARM (2) - 1N
  - PROBE RETRACT -VERIFY
  - SECS PYRO ARM A AND B - ON
  - 4 QUADS - ON (8 T/B - GRAY)
  - CMC - AUTO

- AT CONTACT;
- CMC MODE FREE
  - NULL RATES
  - BOTTLES PRIM (2), SEC (2)

128:00

DAP (61112)  
(11111)

A  
O  
S

## 5.0 NOMINAL MAJOR PROCEDURES SUMMARY

The following sections present a summary timeline and checklist of major CSM activities during the nominal Mission G LM active rendezvous. The timeline in Section 5.0 will aid in interpreting the data included in the onboard rendezvous checklist and serves as a time correlated table of contents for the nominal detailed procedures which follow in Section 6.0. In addition, Section 5.2 includes a one-page summary checklist for the nominal mission.

5.1 SUMMARY TIMELINE

GET	EVENT	PRG	GET	EVENT	PRG
(99+10)	MCC-H UPLINK CSM STATE VECTOR TRANSFER THIS VEHICLE STATE VECTOR TO OTHER VEHICLE STATE VECTOR(V66) COPY CSM SEP PAD DON HELMET AND GLOVES	(P00)	(99+32)	LOS DISPLAY TOTAL ATTITUDE ERROR(V62) SC CONT = FMC CMC MODE = AUTO AUTO MNVR TO ( 0, 14, 14) (V49) (INERTIAL SEP ATT EXCEPT YAW)	
(99+18)	SC CONT = SCS RATE = LOW ATT DB = MIN LM RCS COLD FIRE CHECKS		(99+35)	CONFIGURE CAMERA	
(99+20)	DISABLE CSM ROLL JETS RATE = HIGH ATT DB = MAX		(99+42)	SUNUP	
(99+21)	LM RCS HOT FIRE CHECKS		(99+51)	CMC MODE=FREE (AS REQD FOR LM AGS CALIB) CMC MODE=AUTO (AFTER 32 SEC) VERIFY MAX DB FOR AGS CALIB PERFORM SYSTEMS CHECKS AND SWITCH VERIFICATION WAIT FOR LM TO COMPUTE AGS ALIGN AND GIVE GO, THEN YAW 14 DEG LEFT AFTER LM AGS CALIB (0, 313/14, 0)	
(99+22)	ENABLE A/C AND B/D POLL		(99+57)	RNDZ XPNDR CHECKS	
(99+25)	VERIFY AUTO RCS SEL -C4(-PITCH-X)-OFF -B3(+YAW-X)-OFF FOR LM RR SELF TEST VERIFY RNDZ XPNDR=FTR		(100+07)	HAND CONTROLLERS ADJ/ARMED THC POWER=ON VHF A-SIMPLEX VHF RCV ONLY=B DATA TAPE RECORDER=FWD PCM BIT RATE=LOW	
(99+27)	LOAD DAP WITH GROUND UPDATE (21111) (36427) (-00089) (X1111) (33657) (+00032)				

GET	EVENT	PRG
(100+10)	GDC ALIGN TO IMU	-3
(100+11)	VERIFY ORDEAL (V83)	
(100+13)	SC CONT-SCS RELOAD DAP (11102),(V46) (X1111) BMAG MODE - ATT 1/RATE 2	
-25 (100+15+00)	***** UNDOCKING (0, 13/14, 0) ***** AUTO RCS SEL-B3-MNA C4-MNR DV CG-CSM RNUZ XPNDR PWR-PWR(VERIFY)	
(100+19)	AOS ACQUIRE HGA (V64) (P00) ACTIVATE COLOR TV TAKE PHOTOS INSPECT LM DURING LM 360 DEG YAW	
(100+32)	SET EMS= 102.5	
(100+34)	BMAG MODE - RATE 2 SC CONT-CMC CMC MODE - AUTO	
-5 (100+35)	EXTERNAL DV TARGETING (P30) LOAD VGZ = -2.5	

GET	EVENT	PRG
(100+37)	RCS THRUST PROGRAM (P41) AUTO MNVR TO BURN ATTITUDE (TRIM)	
(100+38)	RCS THRUST SETUP (P41)	
(100+39+58)	***** CSM SEPARATION (0, 0, -2.5) (0, 90/14, 0) *****	
(100+44)	RENDEZVOUS NAV PROGRAM (P20) AUTO MNVR TO SXT TRACK (42 DEG) (0,148/56,0) VHF B-DUPLEX VHF RANGING-RANGING MONITOR LM RR CHECKS COMPARE EMS VHF AND V83 RANGE PERFORM OPTICS CHECKS	
(100+52)	COPY DOI P76 PAD COPY PDI1 + 12 P76 PAD COPY CSM RESCUE PAD	
(100+54)	SUNDOWN	
(101+00)	IMU REALIGN TO REFSMMAT (P52) (OPTION 3)	
(101+08)	COPY GYRO TORQUE ANGLES  GDC ALIGN TO IMU VERIFY ORDEAL(V83)	

GET	EVENT	PROG	GET	EVENT	PROG
(101+10)	MCC-H UPLINK GSM AND LM STATE VECTORS	(P00)	(101+44)	RENDEZVOUS NAV PROGRAM POSSIBLE AUTO MNVR TO SXT TRACK (TRIM) (0,224/313,0)	(P20)
(101+26)	SYSTEMS CHECK PRIOR TO LOS		(101+49)	START CAMERAS REMOTE OPERATION INITIATE OPTICS TRACK ONLY	
(101+28)	LOS		(101+52)	REINITIALIZE W MATRIX (V93) CALL MARKING ROUTINE (V57) SET VHF RANGE FLAG (V87)	
(101+31)	VHF A-SIMPLEX VHF RCV ONLY-B DATA TAPE RECORDER-FWD PCM BIT RATE-LOW		(102+07)	TERMINATE MARKS	
(101+33)	RENDEZVOUS NAV PROGRAM AUTO MNVR TO SXT TRACK (67 DEG) (0,217/332,0)	(P20)	(102+17)	AOS ACQUIRE HGA (V64)	(P00)
(101+38+48)	***** LM DOI (-72,7,0,14.5) ***** VHF B-DUPLEX VHF RANGING-RANGING VHF RCV ONLY-GFF COMPUTE RDOT FOR LM		(102+19)	RENDEZVOUS NAV PROGRAM AUTO MNVR TO SXT TRACK (TRIM) (0, 352/330, 0)	(P20)
(101+40)	SUNUP		(102+25)	OBTAIN GO/NO GO FOR PDI ABCRT	
(101+42)	CONFIRM LM DOI TARGET DV PROGRAM (P76) (ADD 20 SECONDS) LM ORBIT PARAMETER DISPLAY (V82) (60X9)		(102+27)	CONFIRM S-BAND SQUELCH-OFF	
			(102+32)	RELOAD DAP (11101) (X1111) AUTO MNVR TO (0, 140, 0) (V49)	
			(102+35+14)	MAINTAIN LM IN SXT FIELD OF VIEW ***** LM PDI *****	

GET	EVENT	PROG	GET	EVENT	PROG
(102+36)	PRO (PITCH DOWN AT .2 DEG/SEC TO P52 ATTITUDE)		(103+17)	COPY P22 PAD INTO CHECKLIST AT GET TIME OF 104+25 (POSSIBLE P27 UPLINK OF RLS AND CSM STATE VECTORS)	
(102+43)	SWITCH TO OMNI-C (AS REQUIRED)		(103+22)	MNVR TO MSFN SUGGESTED ATTITUDE SYSTEMS CHECKS PRIOR TO LOS	
(102+46)	MSFN ENABLES S-BAND RELAY		(103+29)	LOS	
(102+47+11)	***** LM TOUCHDOWN *****		(103+39)	SUNUP	
(102+53)	MAN ATT (PITCH) = ACCEL CMD		(104+01)	SC CONT = SCS MNVR +X AXIS TO 2 DEG BELOW HORIZON (0, 352, 0) CMC IDLING PROGRAM (P00) RELOAD DAP (11100) (X1111) AUTO MNVR TO (0, 330, 0) (V49)	
(102+55)	SUNDOWN SET LUNAR SURFACE FLAG (V44)		(104+07)	CMC MODE = AUTO PRO (START MNVR) MAN ATT (PITCH) = ACCEL CMC ORBIT NAV PROGRAM (P22) (TAKE 5 MARKS 30 SEC APART)	
(102+57)	VHF RANGING = OFF VHF T/R = RECEIVE		(104+15)	AOS	
(103+01)	RR XPDR-OFF STOP PITCH RATE MANUAL ATT (PITCH) = RATE CMD AT PITCH ANGLE OF 80 DEG (0, 206/80, 0)		(104+43)	CMC IDLING PROGRAM (P00) MAN ATT (PITCH) = RATE CMD RELOAD DAP (11101) (X1111) AUTO MNVR TO (270, 101, 45) (V49)	
(103+01)	IMU REALIGN TO REFSMMAT (P52) (OPTION 3)	(P52)			
(103+07)	COPY GYRO TORQUING ANGLES				
(103+09)	GDC ALIGN VERIFY ORDEAL (V83)				

GET	EVENT	PROG	GET	EVENT	PROG
(104+51)	SUNDOWN		(106+15)	ACQUIRE HGA (V64)	(P00)
(104+55)	ACQUIRE HGA (V64)			MCC-H UPLINK CSM STATE VECTOR AND TARGET LOAD	
(104+57)	FDAI SW 2 - INERTIAL			RECORD PLANE CHANGE MNVR PAD	
(104+59)	MCC-H UPLINK (PLANE CHANGE REFSMMAT)	(P27)	(106+37)	AUTO MNVR TO (0, 0, 0) (V49)	
(105+04)	CMC MODE - FREE			COARSE ALIGN CDU (V41)	
	IMU REALIGN TO REFSMMAT	(P52)		LOAD N92 WITH PAD SHAFT AND TRUNNION	
	PLANE CHANGE REFSMMAT (OPTION 1)			PRO	
	GYRO TORQUING		(106+50)	SUNDOWN	
(105+08)	CMC MODE - HOLD			STAR CHECK	
(105+11)	GDC ALIGN		(106+52)	EXTERNAL DV TARGETING	(P30)
(105+12)	INITIATE EAT PERIOD		(106+56)	BURN ATTITUDE MNVR	(P40)
(105+27)	SYSTEMS CHECKS PRIOR TO LOS (P21 IF DESIRED)		(106+57)	SPS THRUST SETUP	(P40)
(105+27)	LOS		(107+05+34)	*****	
(105+37)	SUNUP			CSM PLANE CHANGE (0, 16.6, 0)	
(106+13)	MNVR AS REQUIRED FOR PHOTOGRAPHY			{0, 0, 0}	
	AOS			*****	
			(107+08)	ACQUIRE HGA (V64)	(P00)
				MCC-H UPLINK (LIFT-OFF REFSMMAT)	(P27)
			(107+10)	AUTO MNVR TO (0, '45, 0) (V49)	
				AFTER MNVR COMPLETE	
				CMC MODE - FREE	



GET	EVENT	PRG	GET	EVENT	PRG
(107+14)	IMU REALIGN TO LANDING SITE REFSMMAT (OPTION 1) GYRO TORQUING	(P52)	(124+00)	ACQUIRE HGA(V64)	(P00)
(107+17)	CMC MODE - HOLD			VHF CONFIGURATION CHECK VHF B - DUPLEX VHF T/R - RECEIVE VHF HANGING - RANGING	
(107+18)	GDC ALIGN TO IMU		(124+02)	RELOAD DAP (11101) (X1111)	
(107+19)	ORDEAL (V83)		(124+03)	AUTO MNVR TO (0, 206, 0) (V49)	
(107+25)	LOS		(124+10)	CONFIRM S-BAND SQUELCH=OFF	
(107+26)	BEGIN REST AND EAT PERIOD AUTO MNVR TO REST ATTITUDE		(124+12)	MSFN RELAY DISABLED	
			(124+15)	AUTO MNVR TO (0, 73, 0) (V49) START MNVR AT LIFT=OFF	
			(124+23+25)	PRO(PITCH DOWN AT 2 DEG/SEC TO P52 ATTITUDE) ***** LIFT-OFF *****	
			(124+30)	SWITCH TO OMNI A(AS REQUIRED)	
			(124+30+39)	***** LM INSERTION *****	
			(124+32)	VHF HANGING LOCK ON RELAY RDOT TO LM	

GET EVENT PROG

(124+34) AUTO MNVR COMPLETE (0, 202/73, 0)  
RELOAD DAP (11102)  
(X1111)

(124+35) IMU REALIGN TO REFSMPAT (P52)  
(OPTION 3)  
COPY GYRO TORQUE ANGLES

(124+36) SUNDOWN

(124+40) MCC-H UPLINK LM STATE VECTOR(P00)

(124+42) REQUEST LM TURN ON TRACKER LIGHT

(124+44) RENDEZVOUS NAV PROGRAM (P20)  
AUTO MNVR TO SXT TRACK (TRIM)  
(0,232/73,0)

(124+47) CSI TARGETING PROGRAM (P32)(P20)  
LOAD CSI TARGETING DATA

(124+49) REINITIALIZE w MATRIX (V93)  
SET VHF RANGE FLAG (V87)  
CALL MARKING ROUTINE(V57)

(124+54) AFTER FIVE SXT MARKS PROCFSSED  
REINITIALZE w MATRIX (V93)  
TERMINATE SXT MARKS

-12

-8

-6

0

GET EVENT PROG

(124+59) TERMINATE VHF MARKS(V88)  
OUT OF PLANE DATA(V90)  
(CSM AND LM)  
VOICE LM Y DOT TO LM  
SET VHF RANGE FLAG (V87)

(125+08) LOS

(125+09) TERMINATE VHF MARKS  
CSI TARGETING FINAL COMP (P32)  
COPY CSM CSI SOLUTION  
LOAD N81 VGY WITH(-) CSM YCOT

(125+13) SPS THRUST PROGRAM (P40)  
TERMINATE P20 (V56)  
AUTO MNVR TO BURN ATTITUDE  
(76 DEG) (0, 156/269, 0)

(125+15) COPY LM CSI PAD  
SPS THRUST SETUP (P40)

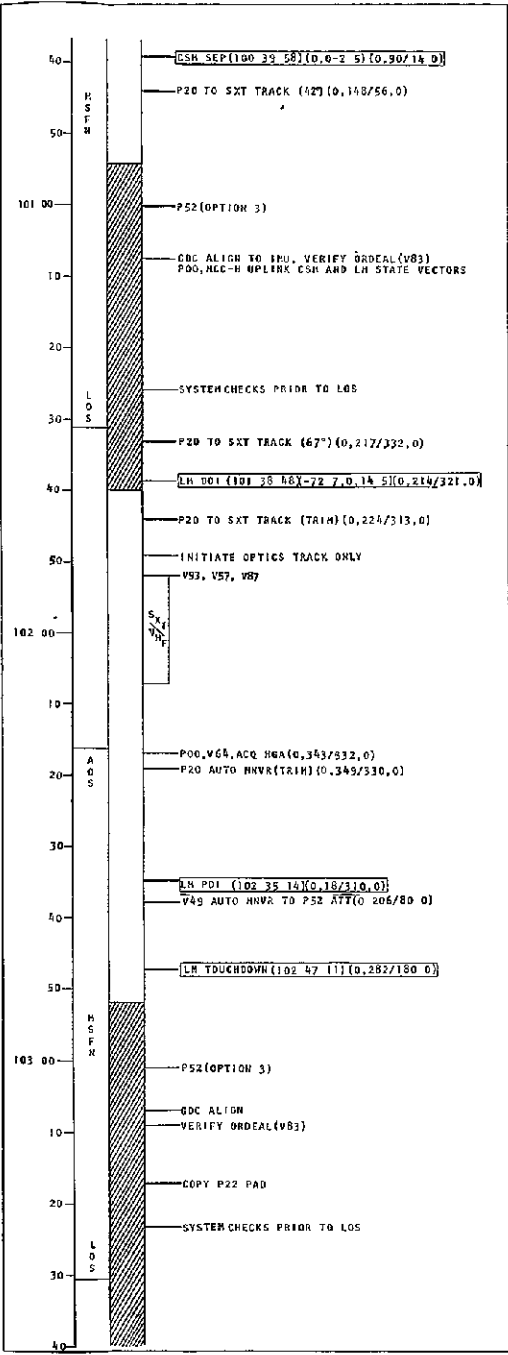
(125+21+20) \*\*\*\*\*  
LM CSI(49.4,0,0)  
\*\*\*\*\*  
\*\*\*\*\*  
CSM CSI (-49.9,0,0)  
(0, 180/269, 0)  
\*\*\*\*\*  
TARGET DV PROGRAM (P76)  
(ADD 23 SECONDS)  
LM ORBIT PARAMETER DISPLAY(V82)  
(45X45)

GET	EVENT	PRG	GFT	EVENT	PRG
(125+22)	SUNUP		(125+53)	RENDEZVOUS NAV PROGRAM (P20)	
(125+27)	RENDEZVOUS NAV PROGRAM (P20) AUTO MNVR TO SXT TRACK (30 DEG) (0,228/299,0)		(125+54)	POSSIBLE AUTO MNVR TO SXT TRACK (TRIM) CALL MARKING ROUTINE(V57) SET VHF RANGE FLAG (V87)	
-51 (125+29)	CALL MARKING ROUTINE(V57) SET VHF RANGE FLAG(V87)		(125+56)	AOS	
(125+32)	AFTER THREE MARKS PROCESSED, V67 LOAD N99(+02000,+00020,+00001) CALL MARKING ROUTINE (V57)	-24	(126+05)	AFTER THREE MARKS PROCESSED, REINITIALIZE W MATRIX (V93)	
(125+43)	TERMINATE VHF MARKING(V88) COPY LM PC TIGN OUT OF PLANE DATA(V90) VOICE LM YDOT TO LM COPY LM PC PAD	-15	(126+10)	TERMINATE MARKS OUT OF PLANE DATA(V90) VOICE LM YDOT TO LM	
(125+45)	CALL MARKING ROUTINE(V57)	-10	(126+14)	CDH TARGETING FINAL COMP (P33) COPY CSM CDH SOLUTION	
-30 (125+50)	TERMINATE MARKS LOAD TARGET DV PROGRAM (P76)	-6	(126+16)	RCS THRUST PROGRAM (P41) BYPASS BURN ATTITUDE MNVR FOR SMALL BURNS TERMINATE P20 (V56) RCS THRUST SETUP (P41)	
-29 (125+50+40)	***** LM PLANE CHANGE 0 ***** INCORPORATE P76 DATA		(126+19+40)	COPY LM CDH PAD ***** LM CDH(-1.9,0,4.1) ***** ***** CSM CDH (2.2,0,-2.7) (0, 239/160, 0) *****	

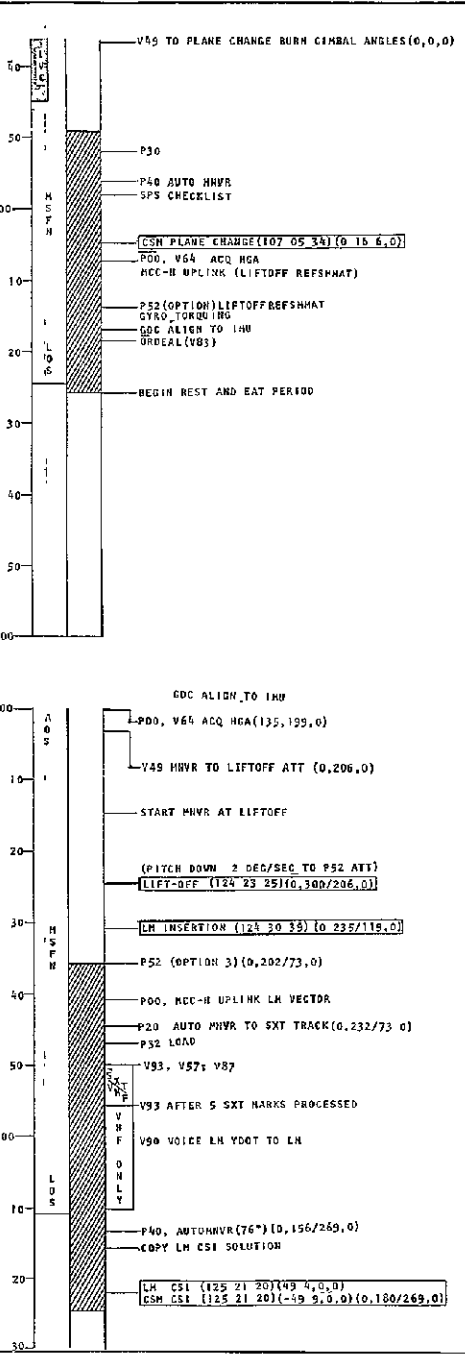
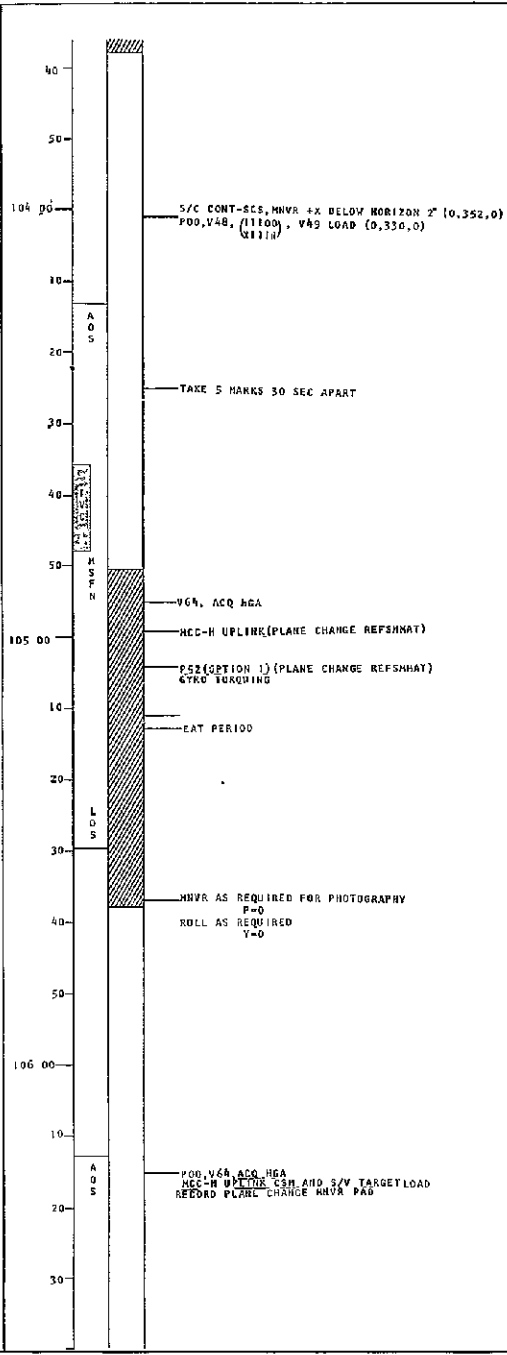
MISSION G SUMMARY TIMELINE

GET	EVENT	PHOG	GFT	EVENT	PHOG
	TARGET DV PROGRAM	(P76) 0	(126+58+27)	***** LM TPI (21.0,-.1,-11.0) ***** ***** CSM TPI (-22.3,0.1,10.9) (0, 208/5, 0) *****	
+25	(126+23) RENDEZVOUS NAV PROGRAM (P20) AUTO MNVR TO SXT TRACK (27 DEG) (0,232/133,0)			TARGET DV PROGRAM (P76) (ADD 12 SECONDS)	
	(126+24) CALL MARKING ROUTINE (V57) SET VHF RANGE FLAG (V87)		(126+59)	RENDEZVOUS NAV PROGRAM (P20) AUTO MNVR TO SXT TRACK (34 DEG) (0, 248/39, 0)	
+29	(126+27) AFTER THREE MARKS PROCESSED REINITIALIZE W MATRIX (V93)			MCC TARGETING PROGRAM (P35)	
+32	(126+30) TPI TARGETING PROGRAM (P34) (ELEVATION ANGLE OPTION)		(127+02)	REINITIALIZE W MATRIX (V93) CALL MARKING ROUTINE (V57) SET VHF RANGE FLAG (V87)	
+36	(126+34) CALL MARKING ROUTINE (V57)	+4		(127+06) LOS	
+39	(126+37) COPY LM TPI TIGN		(127+10)	TERMINATE MARKS MCC1 TARGETING FINAL COMP (P35) COPY CSM MCC1 SOLUTION COPY LM MCC1 PAD	
+47	(126+45) TERMINATE MARKS			(127+11) RCS THRUST PROGRAM (P41) BYPASS BURN ATTITUDE MNVR	
+48	(126+46) TPI TARGETING PROGRAM (P34) +12 (TIGN OPTION WITH LM TIGN) SET MDC EVENT TIMER				
+53	(126+51) SPS THRUST PROGRAM (P40) TERMINATE P20 (V56) AUTO MNVR TO BURN ATTITUDE (52 DEG) (0,191/5,0) COPY LM TPI P76 PAD				
+55	(126+53) SPS THRUST SETUP (P40)				

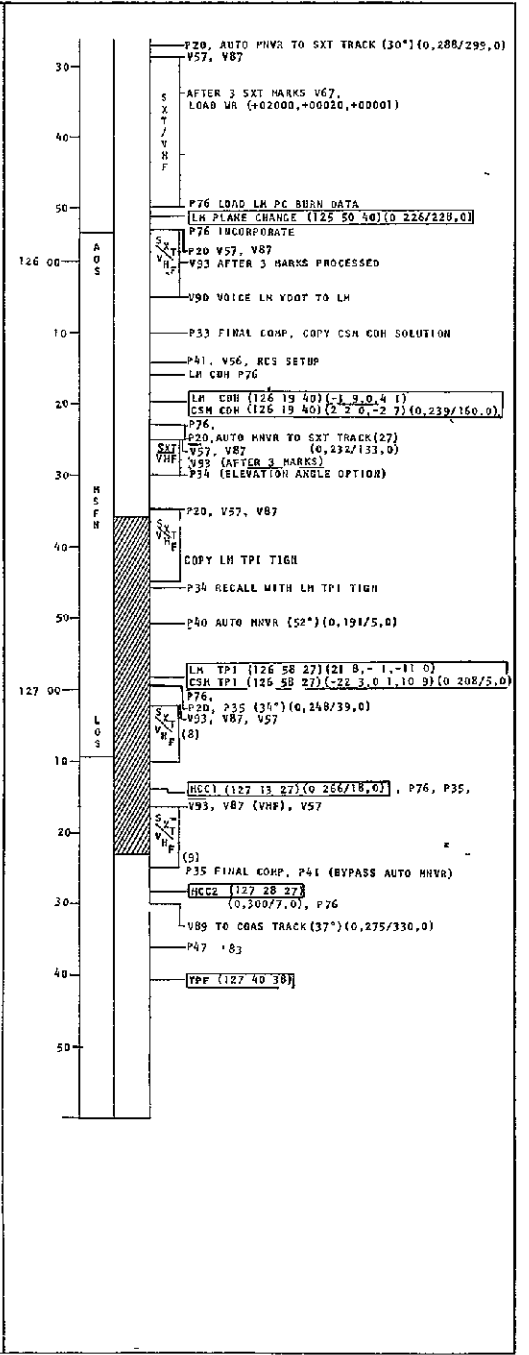
GET	EVENT	PRG	
+15	(127+13+27)		+32 (127+30)
	*****		
	LM MCC1		AUTO MNVR TO COAS TRACK (V89) (P00)
	*****		(37 DEG) (0,275/330,0)
	*****	+38 (127+36)	
	CSM MCC1 (0, 266/18, 0)		THRUST MONITORING PROGRAM (P47)
	*****		(KEY V89 AND MONITOR LM BRAKING)
	(127+14)		*****
	TARGET DV PROGRAM (P76)		#
	MCC2 TARGETING PROGRAM (P35) (P20)		# BRAKING GATES AND RET ANG,S #
	POSSIBLE AUTO MNVR TO SXT TRACK		#
	(TRIM)		# 30FPS AT 6000FT.(1.00NM)=-.13 DEG #
+18	(127+16)		# 20FPS AT 3000FT.(.50NM)=-.26 DEG #
	REINITIALIZE W MATRIX (V93)		# 10FPS AT 1500FT.(.25NM)=-.54 DEG #
	CALL MARKING ROUTINE (V57)		# 5FPS AT 500FT.(.08NM)-1.6 DEG #
	SET VHF RANGE FLAG (V87)		# 300FT.(.05NM)-2.7 DEG #
	(127+21)		# 200FT.(.03NM)-4.0 DEG #
	SUNUP		# 100FT.(.02NM)-8.5 DEG #
+27	(127+25)		*****
	TERMINATE MARKS		(127+40+38)
	MCC2 TARGETING FINAL COMP (P35)		*****
	COPY CSM MCC2 SOLUTION		TPF
	COPY LM MCC2 PAD		*****
+28	(127+26)		
	RCS THRUST PROGRAM (P41)		
	BYPASS BURN ATTITUDE MNVR		
+30	(127+28+27)		
	*****		
	LM MCC2		
	*****		
	*****		
	CSM MCC2 (0, 300/7, 0)		
	*****		
	TARGET DV PROGRAM (P76)		



FOLDOUT FRAME 1



FOLDOUT FRAME 2



FOLDOUT FRAME

## 6.0 NOMINAL DETAILED PROCEDURES

The following four sections contain 1) The procedural ground rules assumed when generating procedures, 2) The detailed nominal procedures, 3) A summary of the rendezvous navigation schedule including the angle between the LOS to the Sun and LOS to the LM, and 4) A Summary of the inertial roll gimbal angle and the ORDEAL pitch and inertial pitch gimbal angles during the nominal G Mission.

### 6.1 Procedures Ground Rules

- 6.1.1 The CSM will be targeted for the same TIGN as the LM for the CSI, CDH, and TPI burns.
- 6.1.2 The CSM will obtain from the LM the CSI, CDH, and TPI times utilized in the LGC targeting programs. These TIGN's are loaded into the CMC targeting programs.
- 6.1.3 LM burn data will be incorporated into the CMC LM state vector using Program P76 following each LM burn. No attempt will be made to account for LM burn residuals. The LM burn TIGN loaded in Program P76 will be biased by a fixed number simulating an impulsive LM burn. The non-zero LM burns considered and the corresponding bias times are DOI (20 Sec), CSI (23 Sec), and TPI (12 Sec).

- 6.1.4 The CSM will compute using V90, the out-of-plane velocity of the LM prior to the CSI, Plane Change, and CDH burns for use in the LM targeting programs.
- 6.1.5 The ordeal setup on FDAI 2 will be verified approximately once per orbit.
- 6.1.6 The GDC will be aligned to the IMU prior to each backup CSM burn.
- 6.1.7 No burn attitude verification using stars or the horizon will be made in the CSM.
- 6.1.8 The PIPA bias determination, EMS DV test, and EMS accelerometer check, identified in the AOH as required before each SPS burn, need be scheduled only prior to the entire rendezvous sequence.
- 6.1.9 The SM RCS propulsion check identified in the AOH as required before each SPS burn, should not include recording the values monitored.
- 6.1.10 It is assumed that the CMP is able to move to the LEB or command seat during automatic attitude maneuvers and the time required to move is less than one-minute.
- 6.1.11 The procedures contained herein reflect the COMANCHE 44, 45 programs and routines.



6.1.12 The minimum times to be allowed for the CMC programs are:

- A. P52 5 Min.
- B. P76 1 Min.
- C. P30 2 Min.
- D. P32 Final Comp 3 Min.
- E. P33 Final Comp 3 Min.
- F. P34 Final Comp 3 Min.
- G. P35 Final Comp 1.5 Min.
- H. P41 (Excluding ATT Mnvr and Including RCS Setup) 1.5 Min.
- I. P40 (Excluding ATT Mnvr and Including SPS Setup) 5 Min.

6.1.13 All automatic maneuvers (DAP) are made at a rate of .5 Deg/Sec after LM Insertion.

6.1.14 The state vector of the active vehicle (LM) will be updated in the rendezvous navigation Program, P20.

6.1.15 The SXT navigation mark frequency during a tracking period is one per minute.

6.1.16 Recycles for CMC targeting Programs, P32 and P33, during mark periods have not been scheduled. They will be included, as desired, for solution comparison purposes, when they do not preclude taking the minimum number of SXT and VHF marks prior to a burn.

- 6.1.17 The delta time between the PRO for Final Comp in Program P35 and the MCC is three minutes.
- 6.1.18 Program P20 will be terminated (V56) in the thrust program prior to each backup CSM burn. This will necessitate calling Program P20 after the burn in addition to a pre-thrust program. Exceptions: Insertion (P00 does it) and the MCC burns.
- 6.1.19 The automatic star selection routine in Program P52 will be used during each IMU realignment.
- 6.1.20 The CSM attitude has been specified to be compatible with HGA communications when no other attitude constraint prohibits HGA coverage.
- 6.1.21 The G1 onboard checklist should closely resemble the F onboard checklist.
- 6.1.22 The SPS gimbal motors will not be activated for a CSM backup of a LM burn until the CSM knows it must become active.
- 6.1.23 Backup charts for the CSI, CDH, TPI, and MCC burns will not be used in the CSM.

6.1.24 VHF navigation marks cannot be taken at ranges greater than 327 nautical miles.

6.2 DETAILED PROCEDURES

```

*****
*
* MISSION G RENDEZVOUS PROCEDURES
*
*****

```

```

*****
* ASSUMED INITIAL SWITCH SETTINGS
*
*****

```

\*\*CDR SWITCH SETTINGS\*\*

```

CMC ATT=IMU
FDAI SCALE=5/1
FDAI SELECT=1/2
FDAI SOURCE=ATT SET
ATT SET=IMU
MAN ATT(3)=RATE CMD
LIMIT CYCLE=OFF
ATT DB=MAX
RATE=LOW
THC=LOCKED
RHC=LOCKED
TRANS CONT PWR=ON(UP)
ROT CONTR PWR NORMAL=1 OFF,2
AC/DC
ROT CONTR PWR DIRECT(BOTH)=
OFF
SC CONT=CMC
CMC MODE=AUTO
BMAG MODE(3)=RATE2
SPS THRUST DIRECT=NORMAL

```

```

DV THRUST(A,B)=OFF
SCS TVC (BOTH)=RATE CMD
SPS GMBL MTR(4)=OFF
DV CG=LM/CSM
IMU CAL=OFF
EMS ROT=OFF
.05 G=OFF
LV/SPS IND (BOTH)=PC,GPI
TVC GMBL DRIVE (BOTH)=1
FCSM(A,B)=RESET/OVERRIDE
EMS FUNCTION=OFF
EMS MODE=STBY
UP TLM MDC(CM,IU)=BLOCK
RCS TRNFR=SM
PANEL B CB CLOSED EXCEPT
RCS LOGIC(2)
DOCK PROBE(2)
ELS BAT A,BAT B
PL VENT FLT/PL
FLOAT BAG(3)
SECS ARM BAT A,BAT B
AUTO RCS SEL(16)=MNA
EXCEPT -C4(-PITCH-X)=OFF
-B3(+YAW=X)=OFF
TVC SERVO PWR (BOTH)=OFF
FDAI/GPI PWR=BOTH
LOGIC PWR 2/3=ON(UP)
SCS ELECT PWR=GDC/ECA
SIG COND/DRVR BIAS PWR(2)=AC1

```

BMAG PWR(BOTH)-ON  
COAS PWR (L WIND)-ON  
FDAI SW1-INERTIAL  
FDAI SW2-ORB RATE  
EARTH/LUNAR-LUNAR  
ALT SET KNOB TO AVE ALT  
MODE-OPR/SLOW

\*\*LMP SWITCH SETTINGS\*\*

G/N PWR-AC1  
MN BUS TIE(2)-OFF  
NONESS BUS-OFF  
PANÉL 5 G/N CB(10)-CLOSED  
PANÉL 229 CB CLOSED EXCEPT  
MN REL PYRO(2)

\*\*CMP SWITCH SETTINGS\*\*

G/N PWR OPTICS-ON  
G/N PWR,IMU-ON  
CONT SPEED-LO  
OPTICS MODE-CMC  
ZERO OPTICS-ZERO  
RNDZ XPONDER-OFF  
CONT COUPLING-RESOLVED  
SCT TRUN-SLAVE TO SXT  
CONDITION LAMPS-ON  
UP TLM(LEB)-ACCEPT  
C/W-NORMAL  
C/W-CSM  
C/W-POWER  
HIGH GAIN ANT TRACK-AUTO  
HIGH GAIN ANT BEAM-WIDE  
HIGH GAIN ANT PWR-ON(UP)  
HIGH GAIN ANT SERVO-PRIM

MISSION G DETAILED PROCEDURES

```

*****
*
*   TIMELINED RENDEZVOUS PROCEDURES
*
*
*****

```

```

*****
*
*   PROCEDURES THRU UNDOCKING
*
*****

```

(99+10)

\*\*MCC-H UPLINK CSM STATE VECTOR\*\*

```

P00      KEY V37E00E

        UP TLM(CM)(MDC)-ACCEPT
        MONITOR UPLINK ACT LT=ON
        MONITOR GND UPLINK
        MONITOR UPLINK ACT LT=OFF
        UP TLM(CM)(MDC)-BLOCK
        CONFIRM COMP LT=OFF
        KEY V66E

        COPY SEPARATION PAD
        DON HELMET AND GLOVES

```

(99+18)

```

BMAG MODE(3)-ATT1/RATE2
RATE = LOW
ATT DB = MIN
SC CONT = SCS
LM RCS COLD FIRE CHECKS

```

(99+20)

```

AUTO RCS SEL-A/C,
B/D ROLL-OFF

```

```

RATE = HIGH
ATT DB = MAX
LM RCS HOT FIRE CHECKS
AUTO RCS SEL-A/C,
B/D ROLL-MNA

```

(99+25)

```

VERIFY AUTO RCS SEL
B3(+YAW-X)-OFF
C4(-PITCH-X)-OFF
FOR LM RR SELF TEST
VERIFY RNDZ XPDR-HTR

```

(99+27)

\*\*LOAD DAP\*\*

```

KEY V48E
F 04 46 (DAP CONFIGURATION)
LOAD
      21111
      X1111
PRO
F 06 47 (CSM AND LM WT)
LOAD
      +36427
      +33657
PRO
F 06 48 (SPS GMBL TRIM)
LOAD
      -00089
      +00032
PRO
KEY V46E
KEY V62E
BMAG MODE(3)-RATE 2
SC CONT = CMC
CMC MORE = AUTO

SET MDC ET COUNTING DOWN TO

```

SEPARATION TIGN  
(100+39+58)

(99+32)

LOSS OF SIGNAL  
\*\*MANEUVER TO UNDOCKING ATTITUDE\*\*  
  
(INERTIAL SEP ATT EXCEPT 14  
DEG YAW)

KEY V49E  
F 06 22 (COMMANDED R,P,Y)  
LOAD (0, 14, 14)  
PRO  
F 50 18 (COMMANDED R,P,Y)  
PRO  
06 18 (COMMANDED R,P,Y)  
MONITOR AUTO MANEUVER  
F 50 18 (COMMANDED R,P,Y)  
( 0, 244/14, 14)  
KEY ENTER

(99+35)

CONFIGURE CAMERA  
CM/SEG/18/CEX-BRKT(RH WIN)  
MIR(F11,250,INFINITY)6FPS,  
15 MIN

(99+42)

SUNUP

(99+51)

CMC MODE-FREE(AS REQ FOR AGS  
CALIB)  
CMC MODE-AUTO(AFTER 32 SEC)  
  
VERIFY MAX DB FOR AGS CALIB  
PERFORM SYSTEMS CHECK AND  
SWITCH VERIFICATION

WAIT FOR LM TO COMPUTE AGS  
ALIGN AND GIVE GO AHEAD, THEN  
YAW 14 DEG LEFT AFTER  
LM AGS CALIBRATION  
(0,313/14,0)

(99+57)

MOVE TO LEB

\*\*RNDZ XPNDR ACTIVATION\*\*  
AND SELF TEST

CB RNDZ XPNDR FLT BUS=CLOSE  
RNDZ XPNDR=HTR FOR (1 MIN  
SELF TEST)  
RNDZ XPONDER PWR=ON  
SYS TEST (LH)=XPONDER  
SYS TEST(RH)=A(RRT XMTR OUT  
PWR)  
RNDZ XPNDR TEST-TEST (HOLD)  
SYS TEST IND-GREATER THAN 1 VD  
SYS TEST(RH)=B(RRT AGC SIG)  
RNDZ XPNDR TEST-TEST (HOLD)  
SYS TEST IND-GREATER THAN 1  
VDC  
RNDZ XPNDR TEST-OPERATE  
SYS TEST IND=0-4.5 VDC  
SYS TEST(RH)=C(RRT FRÉG LOCK)  
SYS TEST IND  
-LESS THAN .8 VDC UNLOCKED  
-MORE THAN 4 VDC LOCKED  
SYS TEST (RH)=B(RRT AGC SIG  
OPERATE)

MOVE TO CMD SEAT

(100+10)

\*\*GDC ALIGN TO IMU\*\*

KEY V16N20E  
16 20 (R,P,Y)  
FDAI SW2-INERTIAL  
ATT SET THUMBWHEELS TO N20  
FDAI SELECT-1  
NULL ATT ERROR NEEDLES  
ON FDAI 1 WITH ATT  
SET THUMBWHEELS  
FDAI SELECT-1/2  
ATT SET=GDC  
DEPRESS GDC ALIGN PB  
ATT SET-IMU  
FDAI SW2-ORB RATE

(100+11)

\*\*ORDEAL VERIFICATION\*\*

KEY V82E  
F 04 12 (VEHICLE OPTION)  
PRO  
F 16 44 (HA,HP,TFF)  
CALC AVE ALT  
PRO  
ALT SET KNOB TO AVE ALT  
  
KEY V83E  
F 16 54 (R,RDOT,THETA)  
VERIFY R=RDOT=0  
IF NOT,KEY V66E  
SLEW/ADJUST FDAI TO THETA  
PRO

(100+13)

S/C CONT=SCS  
BMAG MODE(3)=ATT1/RATE2

\*\*LOAD DAP\*\*

KEY V48E  
F 04 46 (DAP CONFIGURATION)  
LOAD  
11102  
XIII  
B  
PRO  
F 06 47 (CSM AND LM WT)  
PRO  
F 06 48 (SPS GMBL TRIM)  
PRO  
KEY V46E

\*\*PROCEDURES FOR UNDOCKING\*\*

INSTALL DOCKING TARGET  
RATE-HIGH  
ROT CONTR PWR DIRECT(BOTH)-  
MNA,MNB  
RHC-ARMED  
THC-ARMED  
CB DOCK PROBE(2)-CLOSED  
EVENT TMR RESET-DOWN  
EVENT TMR START(ON CDR SIGNAL)



-25 (100+15)

PROBE EXTD/REL-EXTD/REL (HOLD  
UNTIL SEP PLUS 5 SECONDS  
PROBE EXTU/REL TB(2) GRAY TO  
8P TO GRAY  
MONITOR LM UNDOCKING/MAINTAIN  
UNDOCKING ATTITUDE  
(0,13/14,0)  
PROBE EXTD/REL-RETR  
DV CG-CSM  
AUTO RCS SELECT  
-B3(+YAW-X)-MNA  
-C4(-PITCH-X)-MNA  
ROT CONT PWR DIR(BOTH)-OFF  
CB DOCK PROBE(2)-OPEN

MISSION 6 DETAILED PROCEDURES

\*\*\*\*\*  
 \* PROCEDURES FOR \*  
 \* UNDOCKING THRU SEPARATION \*  
 \*\*\*\*\*

-5

\*\*CSM STATION KEEPING\*\*

ATT DB-MIN  
 RNDZ XPNDR PWR-PWR VERIFY  
 PERFORM STATION KEEPING  
 MANEUVERS/MAINTAIN 40 FT  
 SEPARATION

(100+19)

\*\*ACQUIRE HGA\*\*

KEY V64E  
 F 06 51 (RH0,GAMMA,BLANK)  
 SLEW HI GAIN ANT  
 PRO  
 ACQUISITION OF SIGNAL  
 ACQUIRE HGA

ACTIVATE COLOR TV  
 TAKE PHOTOS  
 INSPECT LM DURING LM 360 DEG  
 YAW

(100+32)

EMS FUNCTION-DV SET  
 SET DV INU TO +102.5

(100+34)

BMAG MODE(3)-RATE 2  
 S/C CONT-CMC  
 CMC MODE-AUTO

THC-LOCKED  
 RMC-LOCKED

(100+35)  
 P30

KEY V37E30E  
 F 06 33 (GET OF SEP)  
 LOAD GET OF SEPARATION  
 (100+39+58)  
 PRO  
 F 06 81 (VG-LV)  
 LOAD (0,0,-2.5)  
 PRO  
 F 06 42 (HA,HP,VG)  
 VERIFY VG=2.5  
 PRO  
 F 16 45 (MKS,TFI,MGA)  
 SET MDC ET TO TFI,COUNTING  
 DOWN  
 CONFIRM MGA LESS THAN 45 DEG  
 PRO  
 F 37 88

-3

(100+37)

\*\*RCS SEPARATION BURN SETUP\*\*

P41

KEY 41E  
 F 50 18 (COMMANDED R,P,Y)  
 PRO  
 06 18 (COMMANDED R,P,Y)  
 MONITOR ATT TRIM  
 F 50 18 (COMMANDED R,P,Y)  
 RMC-ARMED  
 ALIGN C/C IN ROLL  
 PRO  
 06 18 (COMMANDED R,P,Y)  
 MONITOR ATT TRIM  
 F 50 18 (COMMANDED R,P,Y)

06 85 KEY ENTER  
(VG-BODY)  
MONITOR COMP ACTV LT  
BMAG MODE(3)-ATT 1/RATE 2  
RATE-LOW  
EMS FUNCTION-DV

EMS MODE-STBY  
RECORD DV IND  
EMS FUNCTION-OFF  
RHC-LOCKED  
THC-LOCKED  
BMAG MODE(3)-RATE2  
AUTO RPS SEL A/C ROLL(4)-OFF  
PRO

+00+40

MONITOR COMP ACTV LT-OUT

+00+35

DSKY BLANKS

F 37 BB

+00+30

16 85 (VG-BODY) (AVG G ON)  
COMP ACTV LT-2 SEC FLASH  
EMS MODE-NORMAL

+00+25

CK VG FOR HI PIPA BIAS  
(LESS THAN 2.0 FPS PER 5  
SEC)  
THC-ARMED

+00 (100+39+58)

F 16 85 (VG-BODY)  
SET MDC ET COUNTING UP  
FROM SEPARATION  
INCREASE VG-BODY FROM  
(+2.5,0,0) TO (+5.0,0,0)  
BY THRUSTING AFT

\*\*\*\*\*  
CSM PERFORMS SEPARATION BURN  
(0,0,-2.5)  
(0,90/14,0)  
\*\*\*\*\*

WHEN BURN COMPLETE, VOICE  
CONFIRMATION TO LM

MISSION G DETAILED PROCEDURES

```

*****
PROCEDURES FOR
SEPARATION THRU TOUCHDOWN
*****

```

(100+44) \*\*MANEUVER TO SXT TRACK ATTITUDE\*\*

P20 KEY 20E  
 F 50 18 (COMMANDED R,P,Y)  
 PRO  
 06 18 (COMMANDED R,P,Y)  
 MONITOR AUTO MANEUVER  
 F 50 18 (COMMANDED R,P,Y)  
 (0, 148/56, 0)  
 KEY ENTER

PERFORM RENDZ XPONDER CHECKS

VHF ANT-RT  
 EMS FUNCTION-VHF RNG  
 EMS MODE-VHF RNG  
 VHF A - OFF  
 VHF B - DUPLEX  
 VHF RCV ONLY-OFF  
 VHF RANGING-RNG  
 VHF RNG-RESET  
 MONITOR EMS FOR RANGE  
 KEY V83E  
 F 16 54 (R,R DOT,THETA)  
 COMPARE EMS AND V83 RANGE  
 COMPARE LM RR RANGE AND  
 RANGE RATE WITH EMS AND  
 V83 RANGE AND RANGE RATE  
 PRO

MOVE TO LEB

PERFORM OPTICS CHECKS  
 ZERO OPTICS-OFF  
 ZERO OPTICS-ZERO(15 SEC)  
 ZERO OPTICS-OFF  
 MONITOR LM IN SCT AND SXT  
 OPTICS MODE-MAN

(100+52)

COPY DOI P76 PAD  
 COPY NO PDI 1+12 P76 PAD  
 COPY CSM RESCUE PAD

(100+54)

SUNDOWN

(101+00)

\*\*REALIGN IMU TO REFSMMAT\*\*

P52 ADJUST RETICLE BRTNESS  
 KEY V37E52E  
 F 04 06 (ALIGN OPTION CODE)  
 LOAD 00003 IN R2 FOR  
 REALIGN TO REFSMMAT  
 PRO  
 F 50 25 (00015, PERFORM STAR ACQ)  
 OPTICS MODE-MANUAL  
 OHC-MANEUVER SCT TO AOC  
 TWO SUITABLE STARS  
 PRO  
 F 01 70 (STAR CODE)  
 CHECK FIRST STAR CODE  
 ZERO OPTICS-ZERO(15SEC)  
 ZERO OPTICS-OFF  
 OPTICS MODE-CMC  
 PRO  
 06 92 (SHAFT,TRUN,BLANK)

MONITOR OPT DRIVE TO STAR ONE  
 IDENTIFY STAR ONE  
 OPTICS MODE=MAN  
 F 51 88 (PLEASE MARK)  
 CENTER FIRST STAR IN SXT  
 MARK ON STAR ONE  
 F 50 25 (00016, TERMINATE MARK SEQ)  
 PRO  
 F 01 71 (MARKED STAR CODE)  
 PRO  
  
 F 01 70 (STAR CODE)  
 CHECK SECOND STAR CODE  
 ZERO OPTICS-ZERO (15SEC)  
 ZERO OPTICS-OFF  
 OPTICS MODE-CMC  
 PRO  
 06 92 (SHAFT,TRUN,BLANK)  
 MONITOR OPT DRIVE TO STAR TWO  
 IDENTIFY STAR TWO  
 OPTICS MODE=MAN  
 F 51 88 (PLEASE MARK)  
 CENTER SECOND STAR IN SXT  
 MARK ON STAR TWO  
 F 50 25 (00016, TERMINATE MARK SEQ)  
 PRO  
 F 01 71 (MARKED STAR CODE)  
 PRO  
 F 06 05 (ANGLE DIFF)  
 COPY DATA ON CHECKLIST  
 PRO  
 F 06 93 (GYRO TORQ ANGLES)  
 COPY DATA ON CHECKLIST  
 MOVE TO CMD SEAT  
  
 CMC MODE=FREE

PRO  
 F 50 25 (00014, PERFORM FINE ALIGN)  
 PRO  
 F 50 25 (00015,PERFORM STAR AOG)  
 PRO  
 F 01 70 (STAR CODE)  
 LOAD THIRD STAR CODE  
 CMC MODE=AUTO  
  
 MOVE TO LEB  
  
 ZERO OPTICS-ZERO (15SEC)  
 ZERO OPTICS-OFF  
 OPTICS MODE-CMC  
 PRO  
 06 92 (SHAFT,TRUN,BLANK)  
 MONITOR OPTICS DRIVE TO STAR  
 THREE  
 ZERO OPTICS-ZERO  
  
 P00 KEY V37E00E  
  
 SET LEB ET COUNTING DOWN  
 TO LM DOI TIGN  
 (101+38+48)  
  
 (101+08)  
  
 MOVE TO CMD SEAT  
  
 \*\*ALIGN GDC TO IMU\*\*  
  
 KEY V16N20E  
 16 20 (R,P,Y)  
 FDAI SW2-INERTIAL  
 ATT SET THUMBWHEELS TO N20  
 FVAI SELECT-1

MISSION 6 DETAILED PROCEDURES

NULL ATT ERROR NEEDLES  
ON FDAI 1 WITH ATT  
SET THUMBWHEELS  
FDAI SELECT-1/2  
ATT SET-GDC  
DEPRESS GDC ALIGN PB  
ATT SET-IMU  
FDAI SW2-ORB RATE

\*\*ORDEAL VERIFICATION\*\*

KEY V83E  
F 16 54 (R, RDOT, THETA)  
SLEW/ADJUST FDAI TO THETA  
PRO

(101+10)

\*\*MCC-H UPLINK(CSM AND LM VECTOR)\*\*

UP TLM(CM)(MDC)-ACCEPT  
MONITOR UPLINK ACT LT-ON  
MONITOR GND UPLINK  
MONITOR UPLINK ACT LT-OFF  
UP TLM(CM)(MDC)-BLOCK  
CONFIRM COMP ACT LT-OFF  
  
SET MDC ET COUNTING DOWN  
TO LM DOI TIGN

(101+30)

LOSS OF SIGNAL

(101+31)

VHF AM A-SIMPLEX  
VHF AM B-OFF  
VHF RCV ONLY-B DATA  
TAPE RCDR FWD-FWD

PCM HIT RATE-LOW

(101+3J)

\*\*MANEUVER TO SXT TRACK ATTITUDE\*\*

P20

KEY V37E20E  
F 50 18 (COMMANDED R,P,Y)  
PRO  
06 18 (COMMANDED R,P,Y)  
MOVE TO LEB DURING AUTO  
MANFUVER  
F 50 18 (COMMANDED R,P,Y)  
(0, 217/332, 0)  
KEY ENTER

ZERO OPTICS-OFF  
OPTICS MODE-CMC

0+00 (101+38+48)

\*\*\*\*\*  
LM DOI BURN  
(-72.7,0,14.5)  
\*\*\*\*\*

MOVE TO CMD SEAT  
CONFIRM LM DOI BURN COMPLETE

(101+40)

SUNUP

(101+42)

VHF AM A-OFF  
VHF AM B-DUPLEX  
VHF RCV ONLY-OFF  
VHF RANGING-RNG

VHF RANGING-RESET(NO VOICE 12  
SEC)  
COMPUTE ROOT FROM VHF RANGE

SET LEB ET COUNTING DOWN  
TO LM PDI TIGN

P76

KEY V37E76E  
F 06 84 (DVS OF LM DOI BURN)  
LOAD (-72.7.0,14.5)  
PRO  
F 06 33 (GETI OF DOI)  
LOAD LM DOI TIGN + 20 SEC  
(101+39+08)  
PRO  
F 37 88

(101+52)

KEY V93E  
KEY V57E  
F 51 88 (PLEASE MARK)  
KEY V87E  
OPTICS MODE MANUAL  
OHC-CENTER LM IN SXT  
TAKE 15 MARKS IN NEXT  
FIFTEEN MINUTES  
PRO/PROCESS LAST MARK

KEY V82E  
F 04 06 (VEHICLE OPTION CODES)  
LOAD R2=00007  
PRO  
F 16 44 (HA,HP,TFF)  
VERIFY (60X9)  
PRO  
F 37 88

(102+07)

CEASE TRACKING  
ZERO OPTICS-ZERO  
OPTICS MODE-CMC  
MOVE TO CMD SEAT

(101+44)

\*\*MANEUVER TO TRACK ATTITUDE\*\*

P20

KEY 20E  
MOVE TO LEB

(102+17)

P00

ACQUISITION OF SIGNAL  
KEY V37E00E  
KEY V64E  
F 06 51 (RHO,GAMMA,BLANK)  
SLEW HT GAIN ANT  
PRO

(101+49)

ZERO OPTICS-ZERO(15 SEC)  
ZERO OPTICS-OFF  
  
START CAMERAS REMOTE OPERATION  
INITIATE LM OPTICS TRACK

(102+19)

\*\*MANEUVER TO TRACK ATTITUDE\*\*

P20

KEY V37E20E  
F 50 18 (COMMANDED R,P,Y)  
PRO  
06 18 (COMMANDED R,P,Y)  
MOVE TO LEB DURING AUTO

TRIM  
 F 50 18 (COMMANDED R,P,Y)  
 (0,352/330,0)  
 KEY ENTER  
 ZERO OPTICS-OFF  
 INITIATE TRACK ONLY  
 (102+25)  
 OBTAIN GO/NO GO FOR PD1 ABORT  
 (102+32)  
 P00 KEY V37E00E  
 KEY V48E  
 F 04 46 (DAP CONFIGURATION)  
 LOAD  
 11101  
 X1111  
 PRO  
 F 06 47 (CSM AND LM WT)  
 PRO  
 F 06 48 (SPS GMBL TRIM)  
 PRO  
 KEY V49E  
 F 06 22 (COMMANDED R,P,Y)  
 LOAD (0,140,0)  
 PRO  
 F 50 18 (COMMANDED R,P,Y)  
 OPTICS MODE-MANUAL  
 OHC-CENTER LM IN SXT

(102+46) (PITCH DOWN .2 DEG/SEC TO  
 P52 ATT)  
 MSFN ENABLES S-BAND RELAY

(102+47+11)  
 \*\*\*\*\*  
 LM TOUCHDOWN  
 \*\*\*\*\*

(102+53) MAN ATT(PITCH)-ACCEL OMD  
 ZERO OPTICS-ZERO  
 SUNDOWN  
 KEY V4ZE (SET LUNAR SURFACE  
 FLAG)

(102+55) VHF RANGING = OFF  
 VHF T/R = RECEIVE

(102+57) RR XPNDR=OFF  
 KEY V46E  
 MANUAL ATT(PITCH) - RATE CMD  
 (0, 206/80, 0)

(102+35+14)  
 \*\*\*\*\*  
 LM PD1  
 \*\*\*\*\*

(102+36)  
 PRO  
 06 18 (COMMANDED R,P,Y)



PROCEDURES FOR TOUCHDOWN  
TO CSM PLANE CHANGE

(103+01)

\*\*REALIGN IMU TO REFSMMAT\*\*

P52

ADJUST RETICLE BRTNESS  
KEY V37E52E

F 04 06 (ALIGN OPTION CODE)  
LOAD 00003 IN R2 FOR  
REALIGN TO REFSMMAT

PRO  
F 50 25 (00015, PERFORM STAR ACQ)  
ZERO OPTICS-OFF  
OPTICS MODE-MAN  
OHC-MANEUVER SCT TO ACQ  
TWO SUITABLE STARS

PRO  
F 01 70 (STAR CODE)  
CHECK FIRST STAR CODE  
OPTICS MODE-CMC

PRO  
06 92 (SHAFT,TRUN,BLANK)  
MONITOR OPT DRIVE TO STAR ONE  
IDENTIFY STAR ONE  
OPTICS MODE-MAN

F 51 88 (PLEASE MARK)  
CENTER FIRST STAR IN SXT  
MARK ON STAR ONE

F 50 25 (00016, TERMINATE MARK SEQ)  
PRO

F 01 71 (MARKED STAR CODE)  
PRO

F 01 70 (STAR CODE)  
CHECK SECOND STAR CODE  
ZERO OPTICS-ZERO (15SEC)  
ZERO OPTICS-OFF  
OPTICS MODE-CMC  
PRO

06 92 (SHAFT,TRUN,BLANK)  
MONITOR OPT DRIVE TO STAR TWO  
IDENTIFY STAR TWO  
OPTICS MODE-MAN

F 51 88 (PLEASE MARK)  
CENTER SECOND STAR IN SXT  
MARK ON STAR TWO

F 50 25 (00016, TERMINATE MARK SEQ)  
PRO

F 01 71 (MARKED STAR CODE)  
PRO

F 06 05 (ANGLE DIFF)  
COPY DATA ON CHECKLIST  
PRO

F 06 93 (GYRO TORQ ANGLES)  
COPY DATA ON CHECKLIST

MOVE TO CMD SEAT  
CMC MODE-FREE  
PRO

F 50 25 (00014, PERFORM FINE ALIGN)  
PRO

F 50 25 (00015, PERFORM STAR ACQ)  
PRO

F 01 70 (STAR CODE)  
LOAD THIRD STAR CODE  
CMC MODE-AUTO

MOVE TO LEB

ZERO OPTICS-ZERO (15SEC)  
 ZERO OPTICS-OFF  
 OPTICS MODE-CMC  
 PRO  
 06 92 (SHAFT,TRUN,BLANK)  
 MONITOR OPTICS DRIVE TO STAR  
 THREE  
 ZERO OPTICS-ZERO  
 P00 KEY V37E 00E  
 (103+07) MOVE TO CMD SEAT  
 \*\*ALIGN GDC TO IMU\*\*  
 16 20 (R,P,Y)  
 FDAI SW2-INERTIAL  
 ATT SET THUMBWHEELS TO N20  
 FDAI SELECT-1  
 NULL ATT ERROR NEEDLES  
 ON FDAI 1 WITH ATT  
 SET THUMBWHEELS  
 FDAI SELECT-1/2  
 ATT SET-GDC  
 DEPRESS GDC ALIGN PB  
 ATT SET-IMU  
 FDAI SW2-ORB RATE  
 (103+09) \*\*ORDEAL VERIFICATION\*\*  
 F 16 54 (R,ROOT,THETA)  
 SLEW/ADJUST FDAI TO THETA

PRO  
 (103+17)  
 (103+29)  
 (103+39)  
 (104+01)  
 COPY P22 PAD AT GET 104+25  
 LOSS OF SIGNAL  
 SUNUP  
 SC CONT - SCS  
 MNVR +X TO 2 DEG BELOW HORIZON  
 KEY V48E  
 F 04 06 (DAP CONFIGURATION)  
 LOAD  
 11100  
 01111  
 PRO  
 F 06 47 (CSM AND LM WT)  
 PRO  
 F 06 48 (SPS GMBL TRIM)  
 PRO  
 KEY V49E  
 F 06 22 (COMMANDED R,P,Y)  
 LOAD (0,330,0)  
 PRO  
 F 50 18 (COMMANDED R,P,Y)  
 BMAG MODE (3)-RATE 2  
 SC CONTROL-CMC  
 (104+07)  
 PRO  
 06 18 (COMMANDED R,P,Y)  
 AFTER MANEUVER STARTED  
 MAN ATT (PITCH)-ACCEL CMD  
 MOVE TO LEB

\*\*ORBIT NAVIGATION PROGRAM \*\*

P22 KEY V37E22E  
 F 06 45 (BLANK, BLANK, MGA)  
 PRO  
 F 05 70 (BLANK, LMK CODE, BLANK)  
 KEY V22E10000E  
 F 06 89 (LAT, LONG/2, ALT)  
 LOAD (MK COORDS)  
 OPTICS ZERO-OFF  
 PRO  
 06 92 (SHAFT, TRUN)  
 OPTICS MODE-MANUAL  
 F 51 88 PLEASE MARK  
 TAKE 5 MARKS 30 SEC APART  
 PRO  
 F 05 71 (BLANK, LMK CODE, BLANK)  
 PRO  
 F 06 89 (LAT, LONG/2, ALT)  
 PRO  
 F 06 49 (DELTA R, DELTA V, BLANK)  
 HOLD FOR 30 SEC  
 PRO  
 F 06 89 (LAT, LONG/2, ALT)  
 KEY V34E  
 F 37 88  
 P00 KEY 00E  
 (104+15) --  
 AOS  
 (104+43) --  
 KEY V46E  
 MANUAL ATT PITCH-RATE CMD  
 KEY V48E  
 F 04 06 (DAP CONFIGURATION)  
 LOAD  
 11101  
 01111

PRO  
 F 06 47 (CSM AND LM WT)  
 PRO  
 F 06 48 (SPS GMBL TRIM)  
 PRO  
 KEY V49E  
 F 06 22 (COMMANDED R,P,Y)  
 LOAD (270,101,45)  
 F 50 18 (COMMANDED R,P,Y)  
 BMAG MODE (3)-RATE 2  
 SC CONTROL-CMC  
 PRO  
 06 18 (COMMANDED R,P,Y)  
 MONITOR AUTO MANEUVER  
 F 50 18 (COMMANDED R,P,Y)  
 (270,101,45)  
 KEY ENTER  
 SUNDOWN  
 KEY V64E  
 F 06 51 (RHO, GAMMA, BLANK)  
 SLEW HIGH GAIN ANT.  
 PRO  
 ACQUIRE HGA  
 F0AI 2-INERTIAL  
 (104+51)  
 (104+55)  
 (104+57)  
 (104+59)

\*\*MCC-H UPLINK (PLANE CHANGE)  
REFSMAT)

UP TLM (CM) (MDC) -ACCEPT  
 MONITOR UPLINK ACT LT-ON  
 MONITOR GND UPLINK  
 MONITOR UPLINK ACT LT-CFF

(105+04) UP TLM(CM)(MDC)-BLOCK  
CMC MODE -FREE  
\*\*REALIGN IMU TO PLANE CHANGE  
REFSMAT,GYRO TORQUING\*\*  
P52 KEY V37E52E  
F 04 06 (00001,00002,BLANK),  
PRO  
F 06 22 (R,P,Y)  
LOAD N22  
PRO  
F 50 25 (00013 GYRO TORQUE)  
KEY ENTER  
16 20 (R,P,Y)  
WHEN TORQUE COMPLETE  
F 50 25 (00014 ALIGNMENT CHECK)  
KEY ENTER  
F 37 BB  
(105+08) P00 KEY 00E  
CMC MODE-HOLD  
(105+11) \*\*ALIGN GDC TO IMU\*\*  
KEY V16N20E  
16 20 (R,P,Y)  
FDAI SW2-INERTIAL  
ATT SET THUMBWHEELS TO N20  
FDAI SELECT-1  
NULL ATT ERROR NEEDLES  
ON FDAI 1 WITH ATT  
SET THUMBWHFELS  
FDAI SELECT-1/?  
ATT SET-GUC  
DEPRESS GDC ALIGN PB

ATT SET-IMU  
(105+12) INITIATE EAT PERIOD  
(105+27) LOSS OF SIGNAL  
(105+37) SUNUP  
(106+13) ACQUISITION OF SIGNAL  
(106+15) KEY V64E  
F 06 51 (RHO,GAMMA,BLANK)  
SET ANTENNA TO THESE ANGLES  
PRO  
ACQUIRE HGA  
\*\*MCC-H UPLINK CSM STATE VECTOR\*\*  
AND PLANE CHANGE TARGET LOAD  
UP TLM(CM)(MDC)-ACCEPT  
MONITOR UPLINK ACT LT=ON  
MONITOR GND UPLINK  
MONITOR UPLINK ACT LT=OFF  
UP TLM(CM)(MDC)-BLOCK  
RECORD MNVR PAD  
(106+37) KEY V49E  
F 06 22 (COMMANDED R,P,Y)  
LOAD (0,0,0)  
PRO  
F 50 18 (COMMANDED R,P,Y)  
BMAG MODE (3)-RATE 2  
SC CONTROL-CMC  
CMC MADE-AUTO  
PRO

06 18 (COMMANDED R,P,Y)  
 MONITOR AUTO MANEUVER  
 F 50 18 (COMMANDED R,P,Y)  
 (0,0,0)  
 KEY ENTER  
 OPTICS MODE =CMC  
 ZERO OPTICS = OFF  
 KEY V41E N91E  
 F 21 92 SHAFT,TRUN  
 LOAD N92 WITH PAD SHAFT AND  
 TRUNION  
 41 OPTICS DRIVE  
 (106+50)  
 SUNDOWN  
 OPTICS MODE=MANUAL  
 VERIFY STAR IN SXT FIELD  
 OF VIEW  
 ZERO OPTICS = ZERO  
 OPTICS MODE=CMC  
 (106+52)  
 P30  
 KEY V37E30E  
 F 06 33 (GETI OF CSM PLANE CHANGE)  
 LOAD GET OF PLANE CHANGE  
 (107+05+34)  
 PRO  
 F 06 81 (VG - LV)  
 LOAD PAD PLANE CHANGE DV  
 PRO  
 F 06 42 (HA,HP,VG)  
 VERIFY VG= PAD DVR  
 PRO  
 F 16 45 (MKS,TFI,MGA)  
 SET MDC ET TO TFI,COUNTING  
 DOWN

CONFIRM MGA LESS THAN 45 DEG  
 PRO  
 F 37 88  
 (106+56)  
 P40  
 KEY 40E  
 F 50 18 (COMMANDED R,P,Y)  
 PRO  
 06 18 (COMMANDED R,P,Y)  
 MONITOR ATTITUDE TRIM  
 F 50 18 (COMMANDED R,P,Y)  
 (106+57)

\*\*SETUP SPS PLANE CHANGE\*\*

MN BUS TIE (2)-ON(UP)  
 SPS HE VLV TB (BOTH)-BF  
 SPS HE VLV (BOTH)-AUTO  
 NONESS BUS-MNA  
 RHC-ARMED  
 BMAG MODE(3)-ATT1/RATE2  
 PERFORM MTVC CHECK  
 TVC SERVO PWR 1-AC1/MNA  
 TVC SERVO PWR 2-AC2/MNB  
 TRANS CONTR PWR- ON  
 RHC PWR NORM 2-AC  
 GMBL MTRS PITCH 1 STRT-ON  
 GMBL MTRS YAW 1 STRT-ON  
 THC=CLOCKWISE  
 RHC-VERIFY NO MTVC  
 GMBL MTRS PITCH 2 STRT-ON  
 GMBL MTRS YAW 2 STRT-ON  
 SET SPS GIMBALS TW(2)-TRIM  
 RHC-VERIFY MTVC  
 THC-NEUTRAL  
 RHC PWR NORM 2-AC/DC

RHC-LOCKED  
 PRO  
 06 18 (COMMANDED R,P,Y)  
 MONITOR ATT TRIM  
 F 50 18 (COMMANDED R,P,Y)  
 KEY ENTER  
 F 50 25 (00204,GMBL DRIVE TEST)  
 RHC PWR DIRECT(BOTH)-MNA/MNR  
 RATE-HIGH  
 AUTO RCS SEL A/C ROLL(4)-MNA  
 PRO  
 MONITOR GMBL DRIVE  
 SEQ AND TRIM  
 06 40 (TFI,VG,DVM) +00+01

-2+00  
 FDAI SCALE=5/5  
 VERIFY SPS TH LT-OFF  
 EMS MODE-STBY  
 EMS FUNCTION-DV SET  
 LOAD PLANE CHANGE DV  
 EMS FUNCTION-DV  
 THC-ARMED  
 RHC-ARMED  
 DV THRUST(BOTH)-NORMAL

-00+35  
 DSKY BLANKS

-00+30  
 06 40 (TFI,VG,DVM)  
 EMS MODE-NORMAL

-00+25  
 CK DVM FOR HI PIPA BIAS  
 (LESS THAN 2 FPS/5 SEC)

-00+15  
 PERFORM ULLAGE

-00+05  
 F 99 40 (REQUEST FOR ENGINE ENABLE)

PRO  
 06 40 (TFI,VG,DVM)

(107+05+34)  
 \*\*\*\*\*  
 CSM PERFORMS PLANE CHANGE  
 BURN  
 \*\*\*\*\*  
 MONITOR  
 SPS THRUST LT-ON  
 DV INDICATOR-DECREASING

ULLAGE-OFF  
 06 40 (TFC,V<sup>TH</sup>,DVM)  
 MONITOR SPS OPERATION  
 PC INDICATOR-95-105 PSI  
 MONITOR SPS ENGINE CUTOFF  
 SPS THRUST LT-OFF  
 F 16 40 (TFC,VG,DVM)  
 DV THRUST(BOTH)-OFF  
 MONITOR  
 PC INDICATOR=0  
 SPS INJ VLV IND(4)-CLOSE  
 SPS HE VLV TB(BOTH)-BP  
 SPS GMBL RETURN TO SERVO  
 NULL  
 GMBL MTRS-OFF(SEQUENTIALLY)  
 TVC SERVO PWR(BOTH)-OFF  
 FDAI SCALE-5/1  
 RATE-LOW  
 ROT CONT PWR DIRECT(BOTH)-OFF  
 PRO  
 F 16 85 (VG-BODY)  
 THC=NULL VG COMPONENTS

AUTO RCS SEL, A/C ROLL(4)-OFF  
THC-LOCKED  
RHC-LOCKED  
BMAG MODE(3)-RATE2  
PRO

P00 F 37 BB  
(107+08)

KEY 00E  
KEY V64E  
F 06 51 (RHO GAMMA,BLANK)  
SET ANTEANA TO THESE ANGLES  
PRO  
ACQUIRE HGA

\*\*MCC-H UPLINK LIFTOFF REFSMMAT\*\*

UP TLM(CM)(MDC)-ACCEPT  
MONITOR UPLINK ACT LT-ON  
MONITOR GND UPLINK  
MONITOR UPLINK ACT LT-OFF  
UP TLM(CM)(MDC)-BLOCK

(107+10)

KEY V49E  
F 06 22 (COMMANDED R,P,Y)  
LOAD (0,45,0)  
PRO  
F 50 18 (COMMANDED R,P,Y)  
BMAG MODE(3)-RATE 2  
PRO  
06 18 (COMMANDED R,P,Y)  
AFTER MNVH COMPLETE  
CMC MODE - FREE

(107+14)

\*\*REALIGN IMU TO LANDING SITE  
REFSMMAT,GYRO TORQUING\*\*  
P52 KEY V37E52E

F 04 06 (00001,00001,BLANK)  
PRO  
F 06 22 (R,P,Y)  
LOAD N22  
PRO  
F 50 25 (00013 GYRO TORQUE)  
KEY ENTER  
16 20 (R,P,Y)  
WHEN TORQUE COMPLETE  
F 50 25 (00014 ALIGNMENT CHECK)  
KEY ENTER

F 37 BB  
(107+17)

P00 KEY 00E  
CMC MODE - HOLD

(107+18)

\*\*ALIGN GDC TO IMU\*\*

KEY V16N20E  
16 20 (R,P,Y)  
ATT SET THUMBWHEELS TO N20  
FDAI SELECT-1  
NULL ATT ERROR NEEDLES  
ON FDAI 1 WITH ATT  
SET THUMBWHEELS  
FDAI SELECT-1/2  
ATT SET-GDC  
DEPRESS GDC ALIGN PB  
ATT SET-IMU  
FDAI S<sub>W</sub>2-ORB RATE

(107+19)

\*\*ORDEAL VERIFICATION\*\*

KEY V83E  
F 16 54 (R,RDOT,THETA)  
SLEW/ADJUST FDAI TO THETA

(107+25) PRO  
LOSS OF SIGNAL

(107+26) MNVR TO ATTITUDE FOR REST  
PERIOD  
KEY V49E  
F 06 22 (COMMANDED R,P,Y)  
LOAD (135,97/199,0)  
PRO  
F 50 18 (COMMANDED R,P,Y)  
BMAG MODE (3)-RATE 2  
SC CONTROL-CMC  
CMC MODE-AUTO  
PRO  
06 18 (COMMANDED R,P,Y)  
MONITOR AUTO MANEUVER  
F 50 18 (COMMANDED R,P,Y)  
(82,128/218,0)  
KEY ENTER

(107+35) BEGIN REST AND EAT PERIOD



```

*****
*
*           PROCEDURES THRU
*           INSERTION
*
*****

```

(124+00)

P00

KEY V37E00E

KEY V64E.

```

F 06 51 (RHO GAMMA,BLANK)
SLEW HI GAIN ANT
PRO

```

(124+02)

KEY V48E

```

F 04 46 (DAP CONFIGURATION)
LOAD

```

11101

01111

```

PRO
F 06 47 (CSM AND LM WT)
PRO

```

```

F 06 48 (SPS GMBL TRIM)
PRO

```

(124+03)

KEY V49E

```

F 06 22 (COMMANDED R,P,Y)
LOAD (0,206,0)
PRO

```

```

F 50 18 (COMMANDED R,P,Y)
BMAG MODE (3)-RATE 2
SC CONTROL-CMC
CMC MODE-AUTO
PRO

```

06 18 (COMMANDED R,P,Y)

```

MONITOR AUTO MANEUVER
F 50 18 (COMMANDED R,P,Y)
(0,206,0)
KEY ENTER

```

(124+15)

KEY V49E

```

F 06 22 (COMMANDED R,P,Y)
LOAD (0,73,0)
PRO

```

F 50 18 (COMMANDED R,P,Y)

```

MOVE TO LEB
ZERO OPTICS-ZERO(15 SEC)
ZERO OPTICS-OFF
OPTICS MODE-MANUAL
OMC-CENTER LM IN SXT

```

(124+23+25)

PRO

```

06 18 (COMMANDED R,P,Y)
(PITCH DOWN AT 2 DEG/SEC
TO P52 ATT)

```

(124+23+25)

```

*****
LM LIFT-OFF
*****

```

(124+30+39)

```

*****
LM COMPLETES INSERTION BURN
*****

```

CONFIRM LM BURN COMPLETE

(124+34)

```

F 50 18 (COMMANDED R,P,Y)
(0,202/73,0)

```

KEY ENTER  
ZERO OPTICS-ZERO  
OPTICS MCUE-CMC  
KEY V48E  
F 04 46 (DAP CONFIGURATION)  
LOAD  
11102  
X1111  
PRO  
F 06 47 (CSM AND LM AT)  
PRO  
F 06 48 (SPS GMBL TRIM)  
PRO

```

*****
*          PROCEDURES FOR          *
*          INSERTION THRU CST      *
*****

```

(124+35)

```

SUNDOWN
SET LEB ET COUNTING DOWN TO
CSI-USING LM CSI TIGN
AND MISSION TIMER

```

```

P52      **REALIGN IMU TO REFSMMAT**
          KEY V37E52E

```

```

          ADJUST RETICLE BRTNES
F 04 06 (ALIGN OPTION CODE)
          LOAD 00003 IN R2 FOR
          REALIGN TO REFSMMAT
          PRO
F 50 25 (00015, PERFORM STAR ACQ)
          OPTICS MODE-MANUAL
          OHC-MANEUVER SCT TO ACQ
          TWO SUITABLE STARS
          PRO
F 01 70 (STAR CODE)
          CHECK FIRST STAR CODE
          ZERO OPTICS-OFF
          OPTICS MODE-CMC
          PRO
          06 92 (SHAFT,TRUN,BLANK)
          MONITOR OPT DRIVE TO STAR ONE
          IDENTIFY STAR ONE
          OPTICS MODE-MAN
F 51 8B (PLEASE MARK)
          CENTER FIRST STAR IN SXT
          MARK ON STAR ONE

```

```

F 50 25 (00016, TERMINATE MARK SEQ)
          PRO
F 01 71 (MARKED STAR CODE)
          PRO
F 01 70 (STAR CODE)
          CHECK SECOND STAR CODE
          ZERO OPTICS-ZERO (15SEC)
          ZERO OPTICS-OFF
          OPTICS MODE-CMC
          PRO
          06 92 (SHAFT,TRUN,BLANK)
          MONITOR OPT DRIVE TO STAR TWO
          IDENTIFY STAR TWO
          OPTICS MODE-MAN
F 51 8B (PLEASE MARK)
          CENTER SECOND STAR IN SXT
          MARK ON STAR TWO
F 50 25 (00016, TERMINATE MARK SEQ)
          PRO
F 01 71 (MARKED STAR CODE)
          PRO
F 06 05 (ANGLE DIFF)
          COPY DATA ON CHECKLIST
          PRO
F 06 93 (GYRO TORQ ANGLES)
          COPY DATA ON CHECKLIST
          MOVE TO CMD SEAT
          CMC MODE-FREE
          PRO
F 50 25 (00014, PERFORM FINE ALIGN)
          PRO
F 50 25 (00015,PERFORM STAR ACQ)
          PRO

```

MISSION G DETAILED PROCEDURES

F 01 70 (STAR CODE)  
 LOAD THIRD STAR CODE  
 CMC MODE-AUTO  
  
 MOVE TO LEB  
  
 ZERO OPTICS-ZERO (15SEC)  
 ZERO OPTICS-OFF  
 OPTICS MODE-CMC  
 PRO  
 06 92 (SHAFT,TRUN,BLANK)  
 MONITOR OPTICS DRIVE TO STAR  
 THREE  
 ZERO OPTICS-ZERO  
  
 (124+40)  
 P00 KEY V37E00E  
 KEY V64E  
 F 06 51 (RHO GAMMA,BLANK)  
 SLEW HI GAIN ANT  
 PRO  
  
 \*\*LM STATE VECTOR UPLINK\*\*  
  
 UP TLM(CM)(MDC)-ACCEPT  
 MONITOR UPLINK ACT LT-ON  
 MONITOR GND UPLINK  
 MONITOR UPLINK ACT LT-OFF  
 UP TLM(CM)(MDC)-BLOCK  
  
 (124+44)  
 \*\*MANEUVER TO TRACK ATTITUDE\*\*  
  
 P20 KEY V37E20E  
 F 50 18 (COMMANDED R,P,Y)  
 PRO  
 06 18 (COMMANDED R,P,Y)  
 MONITOR AUTO TRIM

F 50 18 (COMMANDED R,P,Y)  
 (0, 232/73, 0)  
 KEY ENTER  
 EMS FUNCTION-VHF RNG  
 EMS MODE-VHF RNG  
 VHF RNG-RESET

(124+47)

P32

KEY V37E32E  
 F 06 11 (GETI-CSI)  
 LOAD LM CSI TIGN  
 (125+21+20)  
 PRO  
 F 06 55 (N,E,CENTANG)  
 VERIFY R1=+00001  
 LOAD R2=+208.30  
 LOAD R3=+130.00  
 PRO  
 F 06 37 (GETI-TPI)  
 LOAD LM TPI TIGN  
 (129+58+27)  
 PRO  
 F 16 45 (MKS,TFI-CSI,-00001)  
 SET LEB ET=TFI  
 KEY V32E

(124+49)

KEY V93E/REINITIALIZE W MATRIX  
 KEY V57E  
 F 51 88 (PLEASE MARK)  
 KEY V87E (VHF RANGING)  
 ZERO OPTICS-OFF  
 OPTICS MODE-MAN  
 OHC-CENTER LM IN SXT  
 TAKE 5 MARKS IN NEXT 5  
 MINUTES  
 PRO/PROCESS LAST MARK

F 16 45 (MKS,TFI-CSI,-00001)  
 ZERO OPTICS-ZERO  
 OPTICS MODE-CMC  
 KEY V93E  
 TAKE 5 MARKS IN 5 MINUTES

MOVE TO COMMAND SEAT

(124+59)

KEY V88E  
 KEY V90E  
 F 04 12 (VEHICLE OPTION)  
 LOAD R2=00002  
 PRO  
 F 06 16 (TIME OF EVENT)  
 LOAD LM CSI TIGN  
 (125+21+20)  
 PRO  
 F 06 90 (Y,YDOT,PSI)  
 VOICE LM YDOT TO LM  
 PRO  
 F 16 45 (MKS,TFI-CSI,-00001)

KEY V90E  
 F 04 12 (VEHICLE OPTION)  
 LOAD  
 R2=00001  
 PRO  
 F 06 16 (TIME OF EVENT)  
 LOAD CSM CSI TIGN  
 (125+21+20)  
 PRO  
 F 06 90 (Y,YDOT,PSI)  
 COPY (-)CSM YDOT

ON CHECKLIST

PRO  
 F 16 45 (MKS,TFI-CSI,-00001)  
 KEY V87E  
 TAKE 8 MARKS IN 8 MINUTES

(125+08)

LOSS OF SIGNAL

-12 (125+09)

PRO/MAKE FINAL PASS  
 F 06 75 (DH,DT-CSI/CDH,DT-CDH/TPI)  
 COPY DATA ON CHECKLIST  
 PRO  
 F 06 81 (CSI VG-LV)  
 OVER WRITE N81 WITH  
 (-) CSM YDOT  
 COPY DATA ON CHECKLIST  
 PRO  
 F 06 82 (CDH VG-LV)  
 COPY DATA ON CHECKLIST  
 PRO  
 F 16 45 (MKS,TFI-CSI,MGA)  
 SET MD ET=TFI  
 PRO

F 37 BB

-8 (125+13)

P40  
 KEY 40E  
 F 50 18 (COMMANDED R,P,Y)  
 KEY V56E  
 PRO  
 06 18 (COMMANDED R,P,Y)  
 MONITOR MANEUVER  
 F 50 18 (COMMANDED R,P,Y)  
 (0, 156/269, 0)

-6 (125+15)

COPY LM CSI PAD (P76)

\*\*SETUP SPS CSI BACKUP\*\*

-2

EMS MODE=STBY  
EMS FUNCTION=DV SET  
LOAD CSI BURN VC  
EMS FUNCTION=DV  
FDAI SCALE=5/5  
RATE=HIGH  
RHC PWR DIRECT (BOTH)-MNA/MNB  
BMAG MODE (3)-ATT 1/RATE 2  
TVC GMBL DRIVE (BOTH)-AUTO  
AUTO RCS SEL A/C ROLL (4)-MNA  
RHC=ARMED

KEY ENTER  
06 40 (TFI,VG,DV)  
DV THRUST A-NORMAL  
THC=ARMED

-00+35

OSKY BLANKS

-00+30

06 40 (TFI,VG,DV) (AVE G ON)  
EMS MODE=NORMAL

-00+05

F 99 40 (TFI,VG,DV)

0+00 (125+21+20)

ALIGN S/C TO 0 DEG ROLL  
PRO

\*\*\*\*\*

LM CSI BURN  
(49.4,0,0)

06 18 (COMMANDED R,P,Y)

MONITOR ATT TRIM

\*\*\*\*\*

F 50 18 (COMMANDED R,P,Y)

\*\*GDC ALIGN\*\*

\*\*\*\*\*

ATT SET THUMBWHEELS TO N18  
FDAI SELECT-1  
NULL ATT ERROR NEEDLES  
ON FDAI 1 WITH ATT  
SET THUMBWHEELS

\*\*\*\*\*

IF LM CANNOT PERFORM THE BURN

\*\*\*\*\*

FDAI SELECT-1/2

ATT SET-GDC

GDC ALIGN PB-PUSH

ATT SET-IMU

\*-00+15

MN BUS TIE (2)-ON(UP)

NONESS BUS=MNA

SPS HE VLV TB (BOTH)-BF

SPS HE VLV (BOTH)-AUTO

VERIFY SPS TH LT-OFF

KEY ENTER

THC=APPLY ULLAGE

GMBL MTRS (4)-ON (SEQUENTIALLY)

TVC SERVO PWR 1-AC1/MNA

TVC SERVO PWR 2-AC2/MNB

PRO

F 50 25 (00204, GMBL DRIVE TEST)

\*\*\*\*\*

```

*          CSM BACKUP CSI BURN          *
*          (-49.9,0,0)                  *
*          (0,180/269,0)                 *
*          *****                       *
*          *+00+01                       *
*          06 40 (TFC,VG,DV)             *
*          THC-TERMINATE ULLAGE          *
*          MONITOR SPS BURN             *
*          F 16 40 (TFC,VG,DV)          *
*          DV THRUST A-OFF              *
*          GMBL MTRS(4)-OFF/SEQUENTIALLY*
*          PRO                           *
*          F 16 85 (VG-BODY)             *
*          THC=NULL VGS                 *
*          THC-LOCKED                   *
*          TVC SERVC PWR(BOTH)-OFF      *
*          EMS MODE-STBY                *
*          SPS HE VLV (BOTH)-OFF        *
*          MN BUS TIE (BOTH)-OFF        *
*          NONESS BUS-OFF               *
*          PRO                           *
*          F 37 8B                       *
*          (CONTINUE DETAILED PROCEDURES*
*          BUT DELETE P76)              *
*          *****                       *
*          CONFIRM LM BURN COMPLETE

```

```

P76          KEY V37E76E
F 06 84 (DV,S OF CSI BURN)

RHC-LOCKED
THC LOCKED
AUTO RCS SEL, A/C ROLL (4)-OFF
EMS FUNCTION-VHF RNG
EMS MODE-VHF RNG

```

MISSION G DETAILED PROCEDURES

```

VHF RNG-RESET
FOAI SCALE-5/1
RATE-LOW
ROT CONT PWR DIRECT (BOTH)-OFF
BMAG MODE(3)-RATE 2
TVC GIMBAL DRIVE(BOTH)-1
KEY V37E76E
F 06 84 (DV,S OF LM CSI BURN)
LOAD (50.1,0,0.1)
PRO
F 06 33 (GETI OF CSI)
LOAD LM CSI TIGN + 23 SEC
(125+21+43)
PRO
F 37 8B
KEY V82E
F 04 06 (VEHICLE OPTION CODES)
LOAD R2=00002
PRO
F 16 44 (HA,HP,TFF)
VERIFY (45X45)
PRO
F 37 8B
(125+22)
SUNUP

```

```

*****
*          PROCEDURES FOR          *
*          CSI THRU CDH            *
*****

```

(125+27)

\*\*MANEUVER TO TRACK ATTITUDE\*\*

P20

```

KEY 20E
F 50 18 (COMMANDED R,P,Y)
PRO
06 18 (COMMANDED R,P,Y)
MOVE TO LEB DURING
AUTO MANEUVER
F 50 18 (COMMANDED R,P,Y)
(0,228/299,0)
KEY ENTER

```

```

SET LEB ET COUNTING DOWN TO
CDH USING LM CDH TIGN
AND MISSION TIMER

```

ZERO OPTICS=OFF

51 (125+29)

```

KEY V57E
F 51 8B (PLEASE MARK)
KEY V87E
OPTICS MODE=MAN
OHC-CENTER LM IN SXT
MAKE 3 MARKS IN NEXT
3 MINUTES

```

(125+32)

```

PRO/PROCESS LAST MARK
KEY V67E

```

```

F 06 99 (POS ERR,VEL ERR,OPTION CODE)
LOAD W#
(+02000,+00020,00001)

```

```

PRO
KEY V57E

```

```

F.51 8B (PLEASE MARK)
MAKE 11 MARKS IN NEXT
11 MINUTES

```

(125+43)

```

PRO/PROCESS LAST MARK
OPTICS MODE=CMC

```

```

COPY LM PC TIGN
KEY V88E

```

KEY V90E

```

F 04 12 (VEHICLE OPTION)
LOAD R2=00002
PRO

```

```

F 06 16 (TIME OF EVENT)
LOAD LM PC TIGN
(125+50+40)

```

PRO

```

F 06 90 (Y, YDOT, PSI)
VOICE LM YDOT TO LM
PRO

```

COPY LM PC PAD

(125+45)

KEY V57E

```

F 51 8B (PLEASE MARK)
KEY V87E
OPTICS MODE=MAN
OHC-CENTER LM IN SXT

```



MAKE 5 MARKS IN NEXT  
5 MINUTES  
PRO/PROCESS LAST MARK  
OPTICS MODE-CMC

9 MINUTES  
PRO / PROCESS LAST MARK  
ZERO OPTICS-ZERO  
OPTICS MODE-CMC

(125+50)

-15 (126+05)

P76  
F 06 84 KEY V37E76E  
(DV,S OF LM PC BURN)  
LOAD LM PLANE CHANGE DV,S  
PRO  
F 06 33 (GETI OF PC BURN)  
LOAD GETI-PC BURN  
(125+50+40)

KEY V88E  
KEY V90E  
F 04 12 (VEHICLE OPTION)  
LOAD R2=00002  
PRO  
F 06 16 (TIME OF EVENT)  
OBTAIN LM CDH TIGN  
LOAD LM CDH TIGN  
(126+19+40)

-29 (125+50+40)

\*\*\*\*\*  
LM PLANE CHANGE  
\*\*\*\*\*

PRO  
F 06 90 (Y,YDOT,PSI)  
VOICE iM YDOT TO LM  
PRO

CONFIRM LM PC BURN

PRO/INCORPORATE P76

F 37 BB

-27 (125+53)

P20  
KEY20E  
KEY V57E  
F 51 BB (PLEASE MARK)  
KEY V87E (VHF RANGING)  
OPTICS MODE-MAN  
OHC-CENTER LM IN SXT  
TAKE 4 MARKS IN NEXT  
3 MINUTES

MOVE TO CMD SEAT  
KEY V90E  
F 04 12 (VEHICLE OPTION)  
LOAD R2=00001  
PRO  
F 06 16 (TIME OF EVENT)  
LOAD CSM CDH TIGN  
(126+19+40)

(125+54)

ACQUISITION OF SIGNAL

-24 (125+56)

KEY V93E (REINITIALIZE W MAT)  
TAKE 8 MARKS IN NEXT

-10 (126+10)

PRO  
F 06 90 (Y,YDOT,PSI)  
COPY (-) CSM YDOT  
ON CHECKLIST  
PRO

P33  
F 06 13 KEYV37E33E  
(GETI-CDH)

LOAD LM CDH TIGN  
 (126+19+40)  
 PRO  
 F 16 45 (MKS,TFI-CDH,-00001)  
 PRO/MAKE FINAL PASS  
 F 06 75 (DH,DT-CDH/TPI,DT-TPI/TPI)  
 COPY DATA ON CHECKLIST  
 PRO  
 F 06 81 (CDH VG-LV)  
 OVER WRITE N81 WITH  
 (-) CSM YDOT  
 COPY DATA ON CHECKLIST  
 PRO  
 F 16 45 (MKS,TFI-CDH,MGA)  
 SET MDC ET=TFI  
 PRO  
 F 37 BB  
 (126+14)  
 P41  
 F 50 18 KEY 41E  
 (COMMANDED R,P,Y)  
 KEY V56E  
 KEY ENTER(BYPASS MNVR)  
 06 85 (VG-BODY)  
 \*\*SETUP RCS CDH BACKUP\*\*  
 BMAG MODE(3)-ATT1/RATE2  
 AUTO RCS SEL A/C ROLL(4)-MNA  
 \*\*ALIGN GDC TO IMU\*\*  
 KEY V16N20E  
 16 20 (R,P,Y)  
 ATT SET THUMBWHEELS TO N20  
 FDAI SELECT-1  
 NULL ATT ERROR NEEDLES

ON FDAI 1 WITH ATT  
 SET THUMBWHEELS  
 FDAI SELECT-1/2  
 ATT SET-GDC  
 DEPRESS GDC ALIGN PB  
 ATT SET-IMU  
 KEY RELEASE  
 (126+16)  
 COPY LM CDH P76 PAD  
 DSKY BLANKS  
 16 85 (VG-BODY) (AVE G ON)  
 THC-ARMED  
 RHC-ARMED  
 F 16 85 (VG-BODY)  
 MONITOR LM IGNITION  
 (126+19+40)  
 \*\*\*\*\*  
 LM CDH BURN  
 (-1.9,0,4.1)  
 \*\*\*\*\*  
 \*\*\*\*\*  
 \* IF LM CANNOT PERFORM THE BURN \*  
 \* CSM BACKUP CDH BURN \*  
 (2.2,0,-2.7)  
 (0,239/151,0)  
 \*\*\*\*\*  
 \* THC-NUI L VGS \*  
 \* THC-LOCKED \*

6

PRO

F 37 BB

(CONTINUE DETAILED PROCEDURES\*  
BUT DELETE P76) \*

\*\*\*\*\*

CONFIRM LM BURN COMPLETE

PRO(TO BYPASS CSM-CDH BURN)

F 37 BB

RHC-LOCKED  
AUTO RCS SEL A/C ROLL(4)-OFF  
BMA6 MODE (3)-RATE 2

P76

KEY 76E

F 06 84 (DV+S OF LM CDH BURN)

LOAD (-1.9,0,4.1)

PRO

F 06 33 (GETI OF CDH BURN)

LOAD LM CDH GETI  
(126+19+40)

PRO

F 37 BB

MISSION G DETAILED PROCEDURES

```

*****
*          PROCEDURES FOR          *
*          CDH THRU TPI            *
*****

```

+25 (126+23)

P20 \*\*TARGET CSM TPI BACKUP\*\*

```

KEY 20E
F 50 18 (COMMANDED R,P,Y)
PRO
06 18 (COMMANDED R,P,Y)
MOVE TO LER DURING
AUTO MANEUVER
F 50 18 (COMMANDED R,P,Y)
(0,232/133,0)
KEY ENTER

```

+36 (126+34)

```

PRO
F 06 55 (+00000,ELANG,CENTANG)
LOAD R2 = +208.30(DEG)
LOAD R3 = +130.00 (DEG)

```

```

PRO
F 16 45 (MKS,TFI,-00001)

```

```

PRO
F 06 37 (GETI-TPI)
COPY DATA ON CHECKLIST

```

```

SUNDOWN
KEYV37E20E
KEY V57E
F 51 88 (PLEASE MARK)
KEY V87E
OPTICS MODE-MANUAL
OHC-CENTER LM IN SXT
TAKE 11 MARKS IN NEXT
11 MINUTES

```

P20

COPY LM TPI TIGN ON CHECKLIST

```

PRO/PROCESS LAST MARK
ZERO OPTICS-ZERO
OPTICS MODE CMC

```

MOVE TO CMD SEAT

(126+24)

```

KEY V57E
F 51 88 (PLEASE MARK)
KEY V87E (VHF RANGING)
ZERO OPTICS-OFF
OPTICS MODE-MAN
OHC-CENTER LM IN SXT
MAKE 4 MARKS IN NEXT
3 MINUTES (INCORPORATE 3)
OPTICS MODE-CMC

```

+39 (126+37)

+47 (126+45)

\*\*VERIFY ORDEAL\*\*

+29 (126+27)

KEY V93E(REINITIALIZE W MAT)

+32 (126+30)

```

KEY V83E
F 16 54 (R,RDOT,THETA)
ADJUST FDAI TO THETA
PRO
F 16 45 (MKS,TFI,-00001)

```

P34

```

PRO/PROCESS LAST MARK
KEY V37E34E
F 06 37 (GETI-TPI)
LOAD TPI TIG
(126+56+27)

```

+48 (126+46)  
P34  
F 06 37 KEY V37E34E  
(TPI TIGN)  
LOAD LM TPI TIGN  
(126+58+27)  
PRO  
F 06 55 (+00000,ELANG,CENTANG)  
LOAD R2 = +000.00  
PRO  
F 16 45 (MKS,TFI,-00001)  
PRO/MAKE FINAL PASS  
F 06 55 (+00000, ELANG, CENTANG)  
COPY DATA ON CHECKLIST  
PRO  
F 06 58 (HP,DVTPI,DVTPF)  
COPY DATA ON CHECKLIST  
PRO  
F 06 81 (VG-LV)  
COPY DATA ON CHECKLIST  
PRO  
F 06 59 (VG-LOS)  
COPY DATA ON CHECKLIST  
PRO  
F 16 45 (MKS,TFI,MGA)  
RESET MDC ET WITH TFI  
COUNTING UP  
PRO  
F 37 88

PRO  
06 18 (COMMANDED R,P,Y)  
MONITOR MANEUVER  
F 50 18 (COMMANDED R,P,Y)  
(0,191/5,0)  
COPY LM TPI PAD(P76)  
\*\*SETUP SPS TPI BACKUP\*\*  
EMS MODE-STBY  
EMS FUNCTION-DV SET  
LOAD TPI BURN VC  
EMS FUNCTION-DV  
FDAI SCALE-5/5  
RATE-HIGH  
RHC PWR DIRECT(BOTH)-MNA/MNB  
SMAG MODE (3)-ATT1/RATE2  
TVC GMBL DRIVE(BOTH)-AUTO  
AUTO RCS SEL A/C ROLL (4)-MNA  
RHC-ARMED  
ALIGN C/C TO ZERO ROLL  
PRO  
06 18 (COMMANDED R,P,Y)  
MONITOR ATT TRIM  
F 50 18 (COMMANDED R,P,Y)  
\*\*GDC ALIGN\*\*

+53 (126+51)  
\*\*MANEUVER TO TPI BACKUP ATTITUDE\*\*  
P40  
F 50 18 KEY 40E  
(COMMANDED R,P,Y)  
KEY V56E

ATT SET THUMBWHEELS TO N18  
FDAI SELECT-1  
NULL ATT ERROR NEEDLES  
ON FDAI 1 WITH ATT  
SET THUMBWHEELS  
FDAI SELECT-1/2  
ATT SET-GDC

GDC ALIGN PB-PUSH  
ATT SET-IMU

KEY ENTER

F 50 25 (00204, GMBL DRIVE TEST)  
KEY ENTER  
06 40 (TFI, VG, DV)  
DV THRUST A-NORMAL  
THC-ARMED

+59+25

DSKY BLANKS

+59+30

06 40 (TFI, VG, DV) (AVE G ON)  
EMS MODE-NORMAL

+59+55

0 F 99 40 (TFI, VG, DV)  
(126+58+27)

MONITOR LM ENGINE IGNITION

\*\*\*\*\*  
LM TPI BURN  
(21.8, -0.1, -11.0)  
\*\*\*\*\*

\*\*\*\*\*  
IF LM CANNOT PERFORM THE BURN  
\*\*\*\*\*

MN BUS TIE (2)-ON(UP)  
NONESS BUS-MNA  
SPS HE VLV (BOTH)-AUTO  
SPS HE VLV TB (BOTH)-RP  
VERIFY SPS TH LT-OFF

+00+15

THC-APPLY ULLAGE

GMBL MTRS(4)-ON(SEQUENTIALLY)\*  
TVC SERVO PWR 1-AC1/MNA \*  
TVC SERVO PWR 2-AC2/MNB \*  
PRO \*

0+00

\*\*\*\*\*  
CSM TPI BACKUP BURN  
(-22.3, 0.1, 10.9)  
(0, 208/5, 0)

\*\*\*\*\*

+00+01

06 40 (TFC, VG, DV)  
THC-TERMINATE ULLAGE  
MONITOR SPS BURN

F 16 40 (TFC, VG, DV)  
DV THRUST A-OFF  
GMBL MTRS(4)-OFF/SEQUENTIALLY\*  
PRO \*

F 16 85 (VG-BODY)  
THC=NULL VGS  
THC-LOCKED  
EMS MODE-STBY  
TVC SERVO PWR(BOTH)-OFF  
MN BUS TIE (BOTH)-OFF  
SPS HE VLV (BOTH)-OFF  
NONESS BUS-OFF  
PRO \*

F 37 88

(CONTINUE DETAILED PROCEDURES\*  
BUT DELETE P76)

CONFIRM LM BURN COMPLETE

P76

F 06 84 (DV'S OF LM TPT BURN)  
RMC=LOCKED  
THC LOCKED  
FDAI SCALE=5/1  
RATE=LOW  
ROT CONT PWR DIRECT (BOTH)=OFF  
BMAG MODE (3)=RATE 2  
TVC GIMBAL DRIVE(BOTH)=OFF  
EMS FUNCTION=VHF RNG  
EMS MODE=VHF RNG  
VHF RNG=RESET

LOAD (21.8,-0.1,-11.0)

PRO

F 06 33 (GETI OF TPI BURN)

LOAD LM GET-TPI

+12 SECS

(126+58+39)

PRO

F 37 RB

MISSION 6 DETAILED PROCEDURES

\*\*\*\*\*  
 \* PROCEDURES FOR \*  
 \* TPI THRU TPF \*  
 \*\*\*\*\*

LOSS OF SIGNAL

\* +12 (127+10)

PRO/PROCESS LAST MARK  
 F 16 45 (MKS,TFI,-00001)  
 ZERO OPTICS-ZERO  
 OPTICS MODE-CMC  
 MOVE TO 'COMMAND' SEAT

+2

\*\*MANEUVER TO SXT TRACK\*\*

+12+00 (TIGN=3.0 MIN)

P20 KEY 20E  
 F 50 18 (COMMANDED R,P,Y)  
 PRO  
 06 18 (COMMANDED R,P,Y)  
 MOVE TO LEB DURING AUTO  
 MANEUVER  
 F 50 18 (COMMANDED R,P,Y)  
 (0,248/39,0)  
 KEY ENTER

PRO/MAKE FINAL PASS  
 F 06 81 (VG-LV)  
 COPY DATA ON CHECKLIST  
 PRO  
 F 06 59 (VG-LOS)  
 COPY DATA ON CHECKLIST  
 PRO  
 F 16 45 (MKS,TFI,MGA)  
 PRO  
 F 37 8B

\*\*TARGET CSM MCC1 BACKUP\*\*

P35 KEY V37E35E  
 F 16 45 (MKS,TFI,-00001)  
 (TIME FROM TPI)  
 SET LEB ET TO TFI,  
 COUNTING UP  
 ZERO OPTICS-OFF

(127+11)

P41

COPY LM MCC1 PAD (P76)

KEY 41E  
 F 50 18 (COMMANDED R,P,Y)  
 KEY ENTER (BYPASS MNVR)  
 06 85 (VG-BODY)

+4 (127+02)

KEY V93E (REINITIALIZE W MAT)  
 KEY V57E  
 F 51 8B (PLEASE MARK)  
 KEY V87E (VHF RANGING)  
 OPTICS MCUE-MAN  
 OHC-CENTER LM IN SXT  
 MAKE 8 MARKS IN NEXT  
 8 MINUTES

+14+25

+14+30

\*\*SET UP MCC1 BACKUP\*\*

OSKY BLANKS

16 85 (VG-BODY) (AVE G ON)  
 THC-ARMED  
 RHC-ARMED

(127+06)



+15 (127+13+27)

F 16 85 (VG-BODY)  
 \*\*\*\*\*  
 LM PERFORMS MCC1 BURN  
 \*\*\*\*\*  
 \*\*\*\*\*  
 CSM MCC1 BACKUP BURN  
 (0,266/18,0)  
 \*\*\*\*\*

CONFIRM LM BURN COMPLETE

PRO (TO BYPASS CSM-MCC1 BURN)

F 37 BB

THC-LOCKED

RHC-LOCKED

P76

KEY 76E

F 06 84 (DV,S OF LM MCC1 BURN)

LOAD LM MCC1 DV,S

PRO

F 06 33 (GETI OF MCC1 BURN)

LOAD LM GET-MCC1

(127+13+27)

PRO

F 37 BB

MOVE TO LEH

\*\*TARGET CSM MCC2 BACKUP\*\*

P35

KEY 35E

F 16 45 (MKS,TFI,-00001)

ZERO OPTICS-OFF

OPTICS MODE-CMC

+18 (127+16)

KEY V93E (REINITIALIZE W MAT)  
 KEY V57E  
 F 51 BB (PLEASE MARK)  
 KEY V87E(VHF RANGING)  
 OHC-CENTER LM IN SXT  
 OPTICS MODE-MAN  
 MAKE 9 MARKS IN NEXT  
 9 MINUTES

(127+21)

SUNUP

+27 (127+25)

PRO/PROCESS LAST MARK

F 16 45 (MARKS,TFI,-00001)

ZERO OPTICS-ZERO

MOVE TO COMMAND SEAT

+27 (TIGN=3.0 MIN)

PRO/MAKE FINAL PASS

F 06 81 (VG-LV)

COPY DATA ON CHECKLIST

PRO

F 06 59 (VG-LOS)

COPY DATA ON CHECKLIST

PRO

F 16 45 (MARKS,TFI,MGA)

PRO

F 37 BB

+28 (127+27)

COPY LM MCC2 PAD

+28+30

P41

KEY 41E

F 50 18 (COMMANDED R,P,Y)

KEY V56E

MISSION G DETAILED PROCEDURES

KEY ENTER (BYPASS MNVR)  
06 85 (VG-BODY) +32

\*\*MANEUVER TO COAS TRACK ATTITUDE\*\*

\*\*SET UP MCC2 BURN\*\*

P00

+29+25

DSKY BLANKS

KEY 00E

+29+30

16 85 (VG-BODY) (AVE G ON)  
THC-ARMED  
RHC-ARMED

KEY V89E

F 04 06 (00003,00001,BLNK)

LOAD R2 = 00002

PRO

+30 (127+28+27)

F 16 85 (VG-BODY)

F 06 18 (COMMANDED R,P,Y)

PRO

\*\*\*\*\*

LM PERFORMS MCC2 BURN

F 50 18 (COMMANDED R,P,Y)

PRO

\*\*\*\*\*

06 18 (COMMANDED R,P,Y)

MOVE TO CMD SEAT

DURING AUTO MANUEVER

\*\*\*\*\*

CSM MCC2 BACKUP BURN

F 50 18 (COMMANDED R,P,Y)

(0,275/330,0)

(0,300/7,0)

\*\*\*\*\* +34

KEY ENTER

CONFIRM LM BURN COMPLETE

PRO (TO BYPASS CSM-MCC2 BURN)

THC-LOCKED

RHC-LOCKED

P76

F 37 88

KEY 76E

F 06 84 (DV,S OF LM MCC2 BURN)

LOAD LM MCC2 DV,S

PRO

F 06 33 (GETI OF MCC2 BURN)

LOAD LM GET-MCC2

(127+28+27)

PRO

F 37 88

\*\*\*\*\*  
\* PROCEDURES FOR BRAKING \*  
\*\*\*\*\*

RHC-ARMED  
CENTER LM IN RETICLE  
BMA $\bar{G}$  MODE (3)-ATT1/RATE 2  
MONITOR EMS FOR RANGE

+38 (127+36)  
P47

KEY V37E47E  
F 16 83 (DV-BODY)  
KEY V83E  
F 16 54 (R,RDOT,THE $\bar{T}$ A)

THC-ARMED  
MONITOR LOS CONTROL  
MONITOR R AND R DOT

\*\*\*\*\*

\* \* \*

\* BRAKING GATES AND RET ANG,S \*  
\* \* \*

\* 30FPS AT 6000FT.(1.00NM)-.13 DEG \*  
\* 20FPS AT 3000FT.(.50NM)-.26 DEG \*  
\* 10FPS AT 1500FT.(.25NM)-.54 DEG \*  
\* 5FPS AT 500FT.(.08NM)-1.6 DEG \*  
\* 300FT.(.05NM)-2.7 DEG \*  
\* 200FT.(.03NM)-4.0 DEG \*  
\* 100FT.(.02NM)-8.5 DEG \*  
\* \* \*

\*\*\*\*\*

USE RANGE ON DSKY TO CHECK EMS  
RANGE INDICATOR. USE  
RETICLE ANGLE AS THIRD  
VOTE.

(127+40+38)

\*\*\*\*\*

TPF

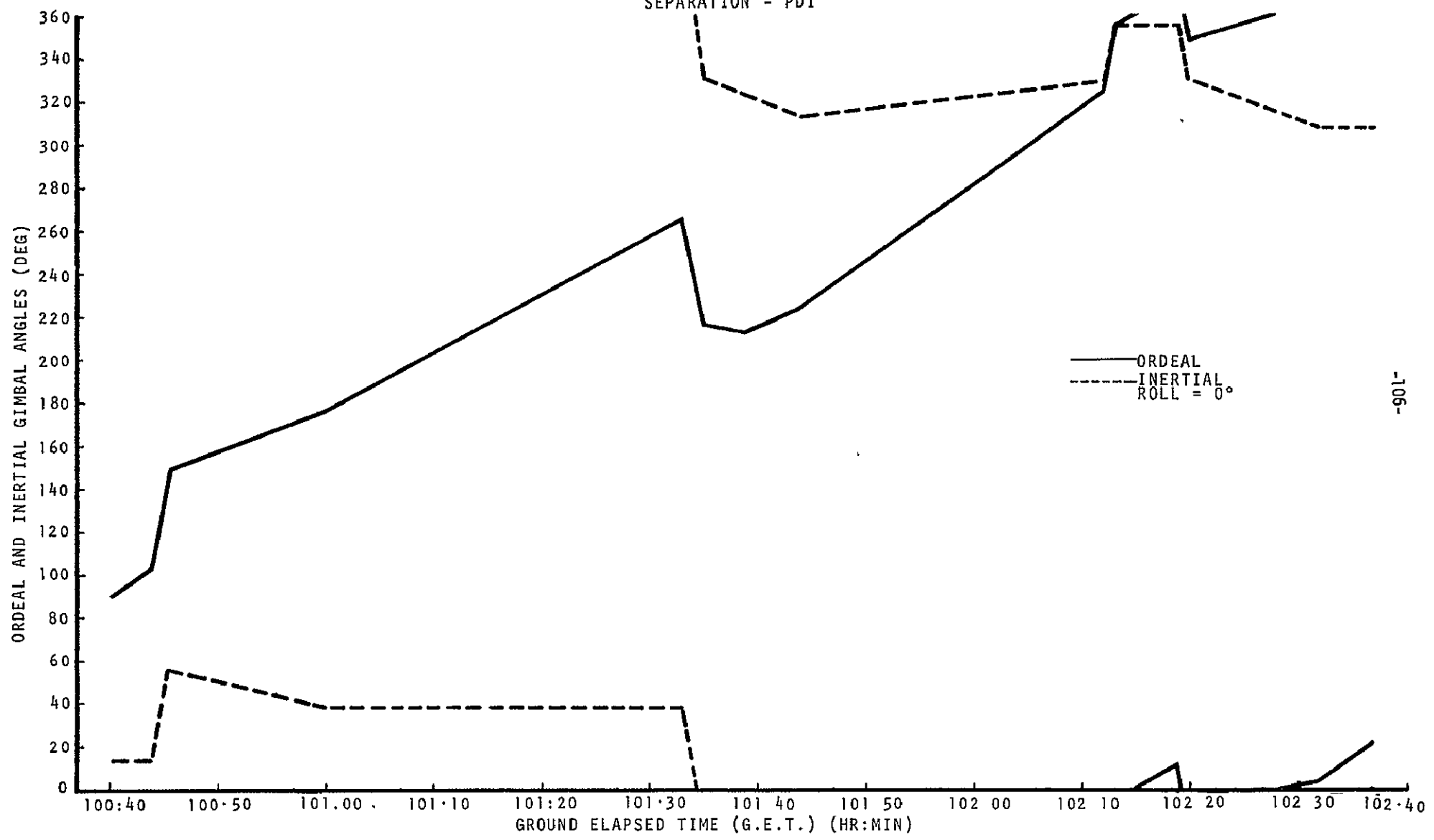
\*\*\*\*\*

6.3 P20 NAVIGATION SUMMARY WITH SUN ANGLES

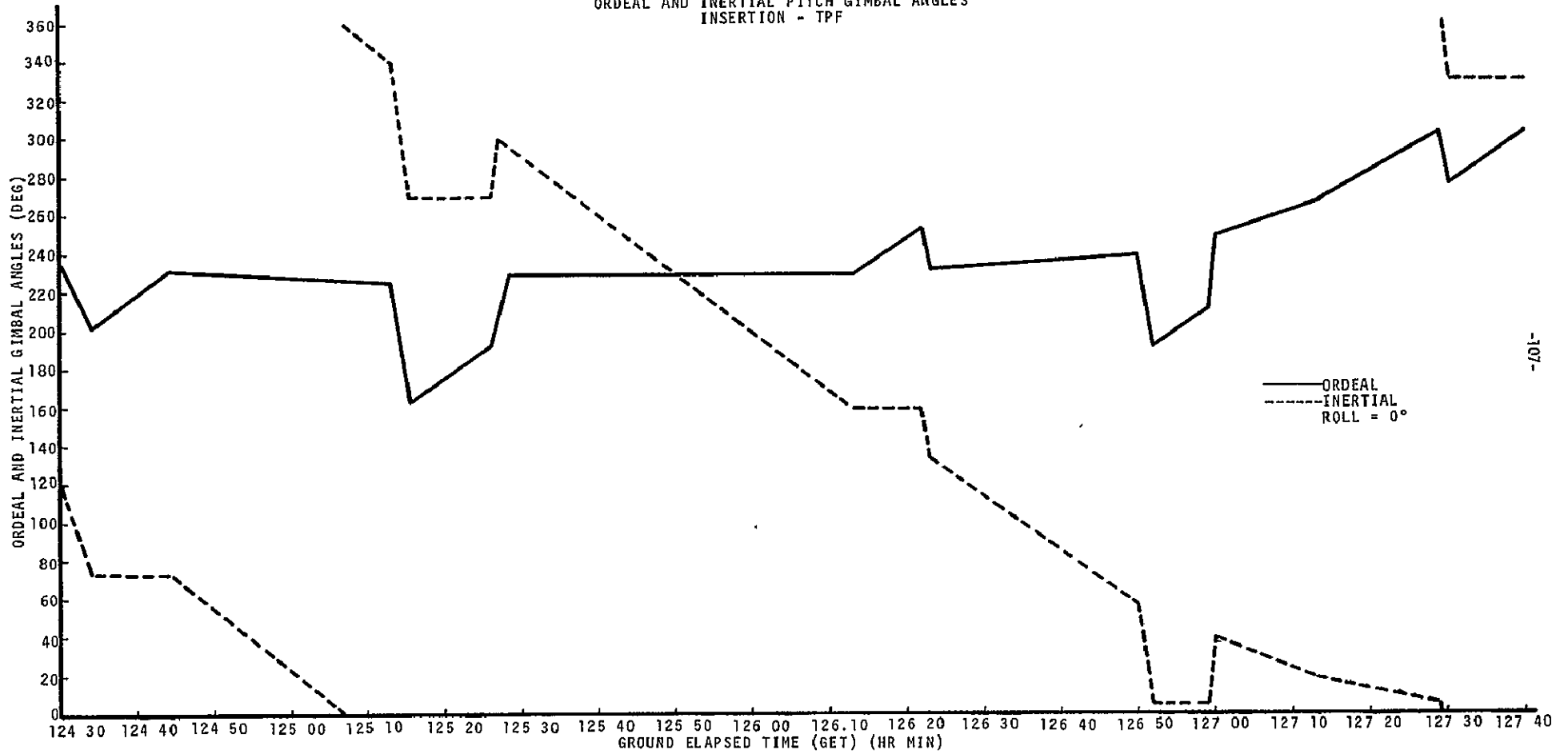
IT - INITIATE TRACK  
 CT - CEASE TRACK  
 X/Y; X = NUMBER OF MARKS  
 Y = MINUTES IN MARKING PERIOD

GET	EVENT	SUN ANGLE (LOS TO SUN) DEGREES
124:30:39	LM INSERTION	
124:36	SUNSET	
124:49	IT (SXT/VHF) (V93,5/5,V93, 15 VHF/15)	
124:54	CT (SXT)	
125:09	CT (VHF)	
125:21:20	LM CSI	
125:22	SUNRISE	
125:29	IT (SXT/VHF) (3/3;V67,02000,00020 00001;18/18)	173
125:34		172
125:39		158
125:45		141
125:50	CT	126
125:50:40	LM PLANE CHANGE	
125:53	IT (SXT/VHF) (3/3,V93,9/9)	117
125:59		99
126:05	CT (SXT/VHF)	81
126:19:40	LM CDH	
126:24	IT (SXT/VHF) (3/3,V93,2/2)	26
126:30	CT (SXT/VHF)	9
126:34	SUNSET	
126:34	IT (SXT/VHF) (11/11)	
126:45	CT (SXT/VHF)	
126:58:27	LM TPI	
127:02	IT (SXT/VHF) (V93,8/8)	
127:10	CT (SXT/VHF)	
127:13:27	LM MCC1	
127:16	IT (SXT/VHF) (V93,9/9)	
127:21	SUNRISE	97
127:25	CT (SXT/VHF)	97
127:28:27	MCC2	
127:40:38	TPF	

ORDEAL AND INERTIAL PITCH GIMBAL ANGLES  
SEPARATION - PDI



ORDEAL AND INERTIAL PITCH GIMBAL ANGLES  
INSERTION - TPF



## 7.0 LM RESCUE CASES

Numerous rescue cases occur for Mission G caused by a decision to abort the mission. These cases are either CSM passive where it is only necessary to monitor and back-up the LM activity or CSM active where it is necessary to rescue the LM. Investigation of the possible situations which might occur and the need for procedural support of these cases has led to the need for defining fifteen possible rescue cases. These cases are discussed in the following sections.

It should be noted that the particular rescue cases discussed in the following sections were based on the operational trajectory presented in Reference 8.2. The times have been adjusted to reflect the new operational trajectory given in Reference 8.18; however, the burns were assumed to be unchanged.

7.1 Partial DOI (< 25 FPS) (CSM Active)

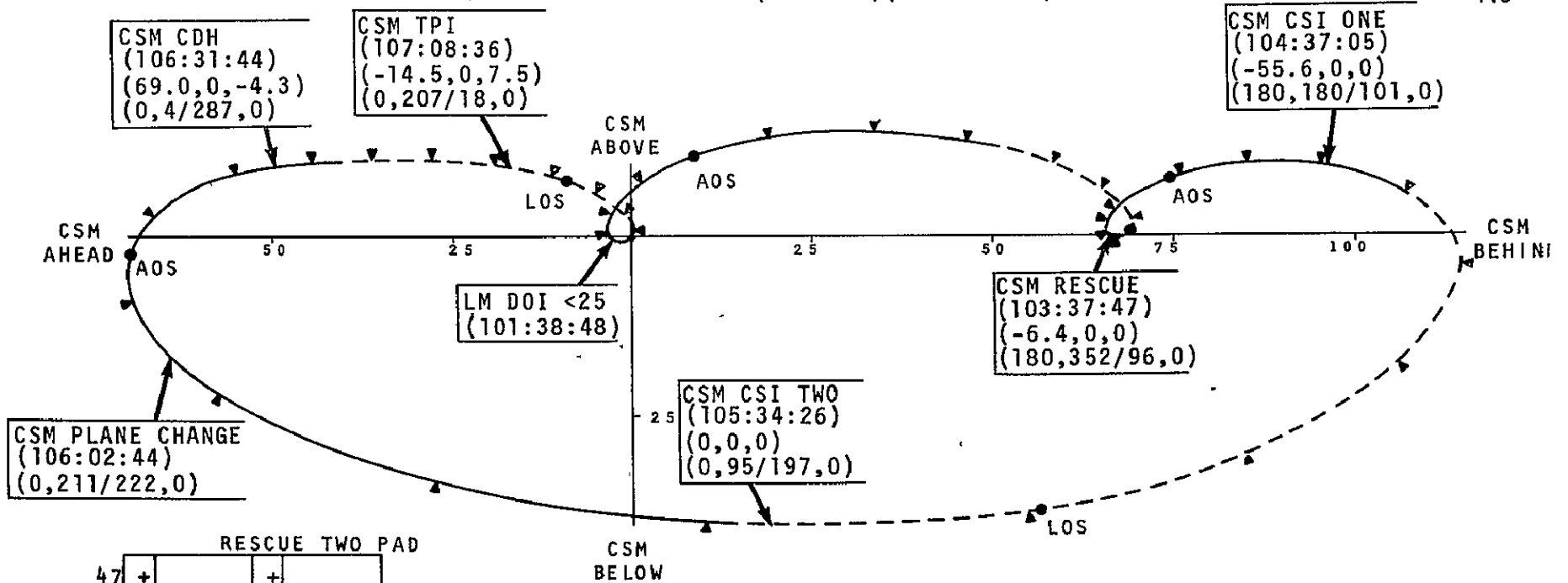
7.1.1 Summary

This rescue case provides for the situation where the LM applies less than 25 feet per second of the DOI burn and cannot perform a direct return. The CSM performs a height maneuver one rev after DOI. This height maneuver is a Rescue II burn and is targeted for a delta height of 10 nautical miles one half rev later.  $CSI_1$  occurs one half rev after the height maneuver and is a retrograde burn. The  $CSI$  burn lowers the CSM apogee allowing the CSM to catch up to the LM. A  $CSI_2$  burn (nominally zero) is scheduled halfway between  $CSI_1$  and CDH. CDH occurs one rev after  $CSI_1$  and results in a delta height of 10 nautical miles. TPI occurs on a CSM elevation angle of 208.3 degrees.

The relative profile and the burns shown in the following pages represent the particular situation where the LM applies 20 feet per second of the DOI burn. This data for other partial DOI burns will vary although the same basic checklist may be followed.



7.1.2. PARTIAL DOI (<25 FPS)(CSM ACTIVE)



RESCUE TWO PAD

47	+		+	
48	-		+	
33			:	:
81				-
22				
ΔV				
C				
11			:	:
37			:	:
N				

CSM CSI ONE COPY

11		:	:
37		:	:
75	.	:	:
81	.	.	.
82	.	.	.

LM CSI ONE COPY

84	.	.	.
33	:	:	

CSM BELOW

CSM CSI TWO COPY

11	:	:
37	:	:
75	.	:
81	.	.
82	.	.

LM CSI TWO P76

84	.	.	.
33	:	:	

CSM PC COPY

33	:	:
81	.	.

LM PC P76

84	.	.	.
33	:	:	

CSM CDH COPY

13	:	:
75	:	:
81	.	.

LM CDH P76

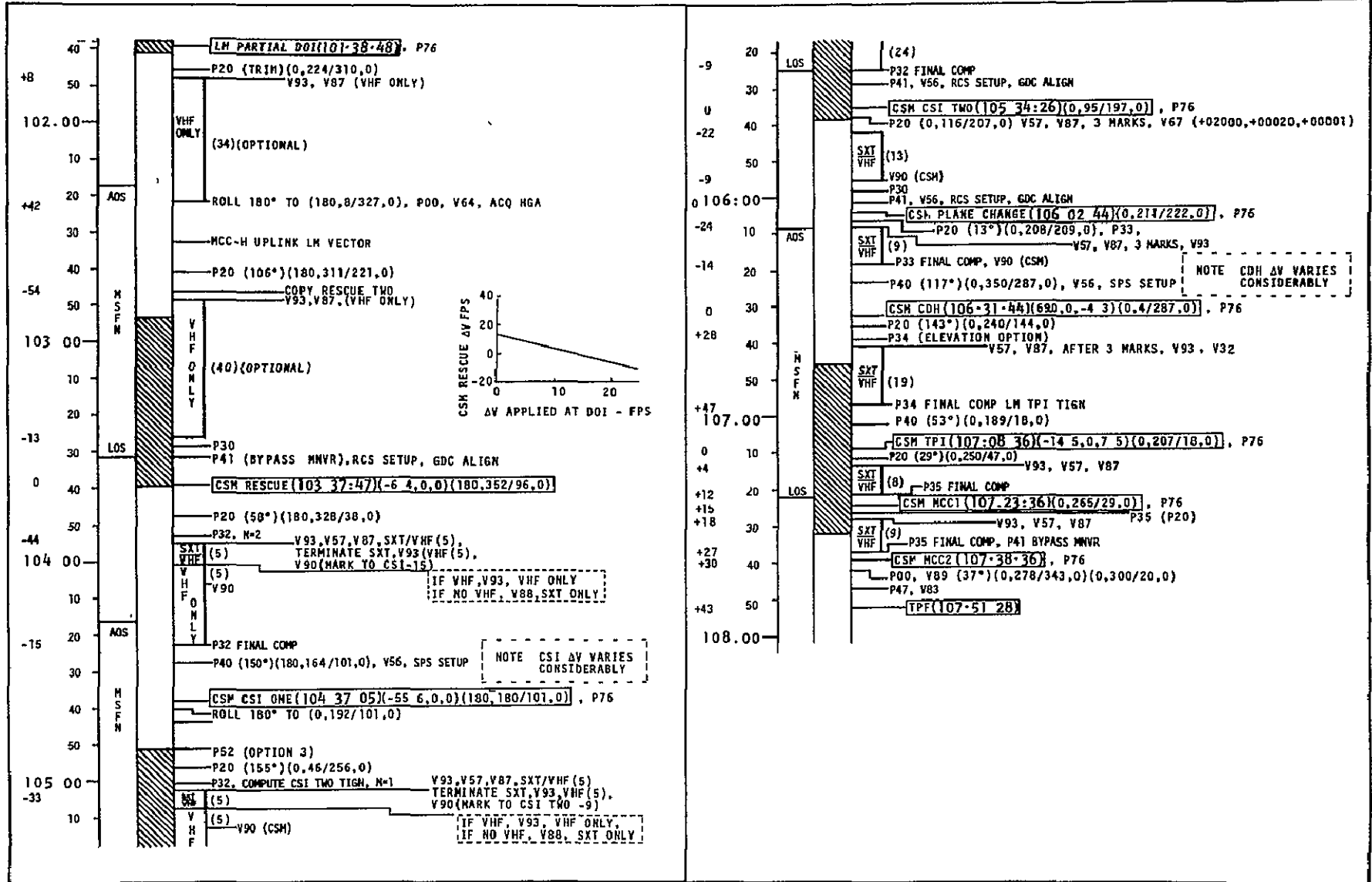
84	.	.	.
33	:	:	

CSM TPI COPY

37	:	:
58	.	.
81	.	.
59	.	.

LM TPI P76

84	.	.	.
33	:	:	



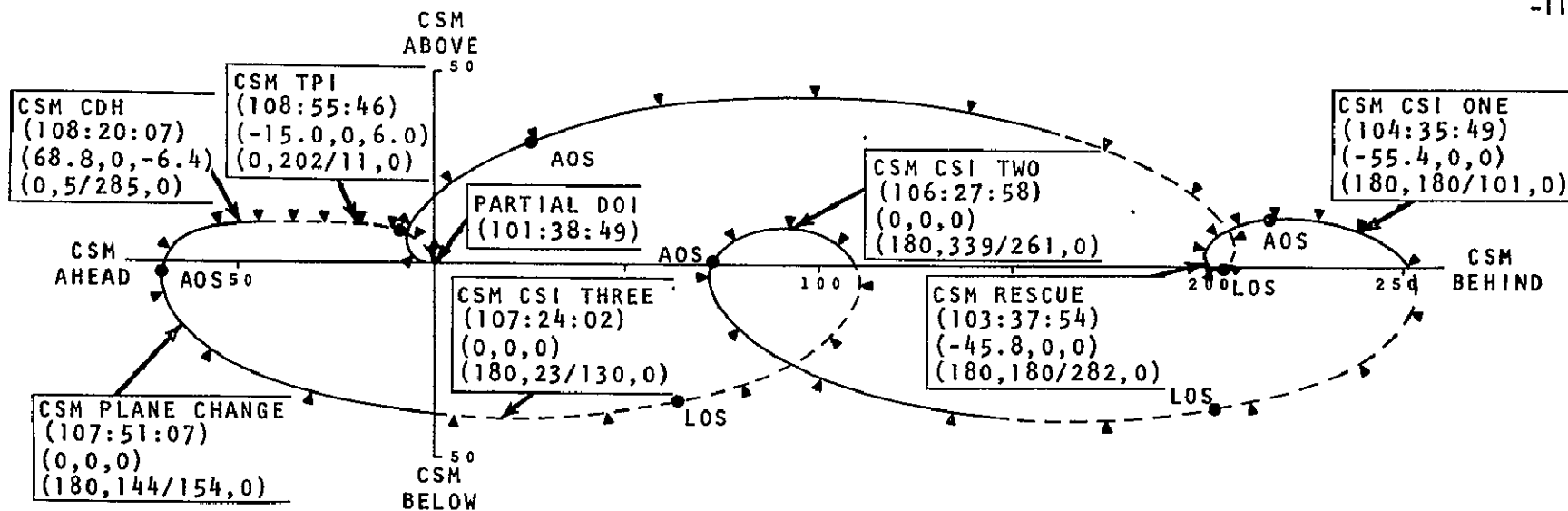
## 7.2 Partial DOI ( $\geq 25$ FPS) (CSM Active)

### 7.2.1 Summary

This rescue case provides for the situation where the LM applies more than 25 feet per second of the DOI burn and cannot perform a direct return. This case is identical to the Partial DOI  $<25$  Rescue except that there is one more rev between  $CSI_1$  and CDH and consequently an additional CSI burn.  $CSI_2$  (nominally zero) occurs one rev after  $CSI_1$  and  $CSI_3$  (nominally zero) is scheduled halfway between  $CSI_2$  and CDH.

The relative profile and the burns shown in the following pages represent the particular situation where the LM applies 60 feet per second of the DOI burn. This data for other partial DOI burns greater than 25 feet per second will vary although the same basic checklist may be followed.

7.2.2 PARTIAL DOI ( $\geq 25$  FPS) (CSM ACTIVE)



RESCUE TWO PAD

47			
48			
33	:	:	:
81			
22			
V C			
11	:	:	:
37	:	:	:
N			

CSM CSI TWO COPY

11	:	:	:
37	:	:	:
75	.	:	:
81	.	.	.
82	.	.	.

LM PC P76

84	.	.	.
33	:	:	:

LM CSI TWO P76

84	.	.	.
33	:	:	:

CSM CDH COPY

13	:	:	:
75	.	:	:
81	.	.	.

CSM CSI ONE COPY

11	:	:	:
37	:	:	:
75	.	:	:
81	.	.	.
82	.	.	.

CSM CSI THREE COPY

11	:	:	:
81	.	.	.

LM CDH P76

84	.	.	.
33	:	:	:

LM CSI ONE P76

84	.	.	.
33	:	:	:

LM CSI THREE P76

84	.	.	.
33	:	:	:

CSM TPI COPY

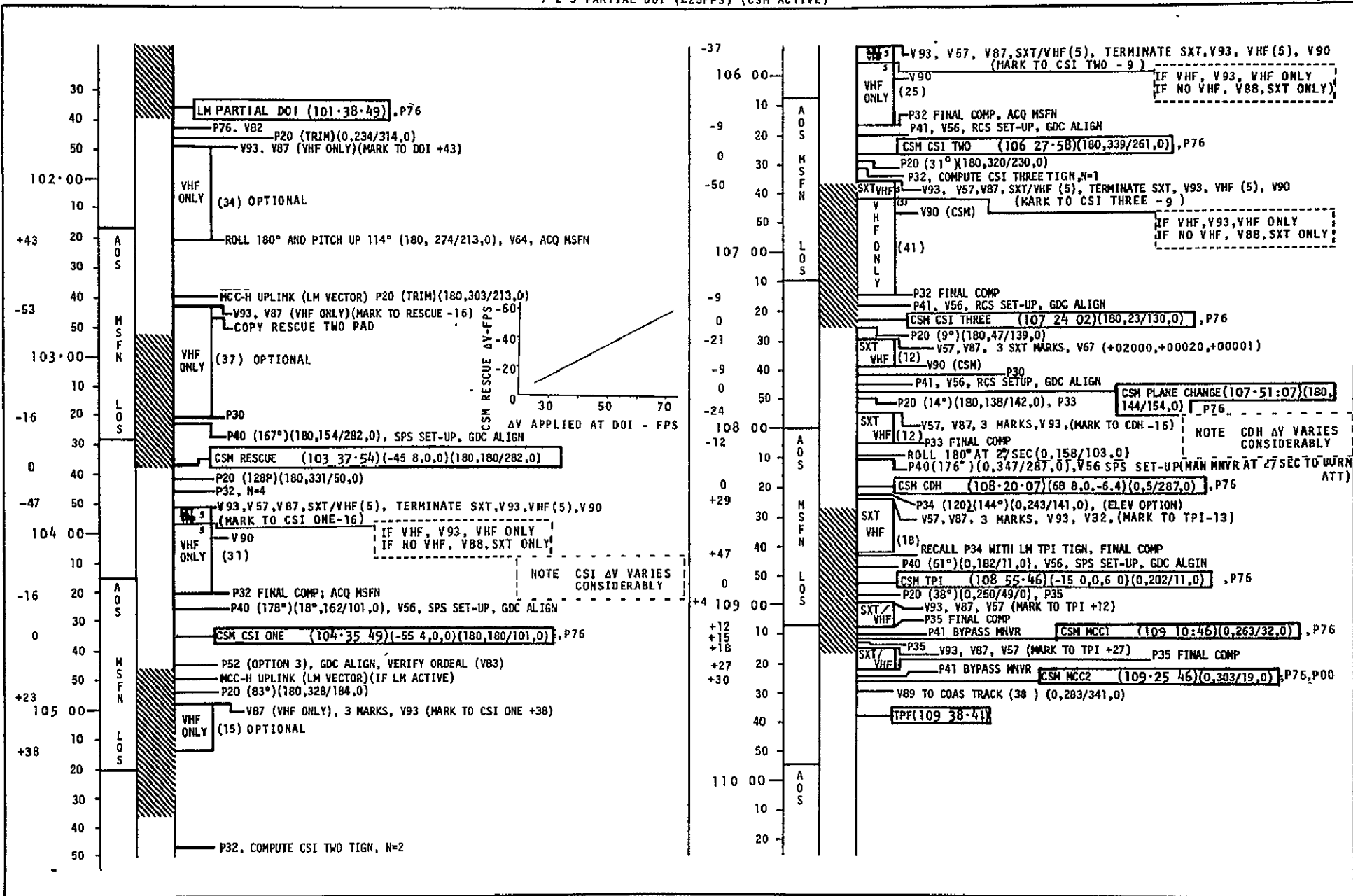
37	:	:	:
58	.	.	.
81	.	.	.
59	.	.	.

CSM PC COPY

33	:	:	:
81	.	.	.

LM TPI P76

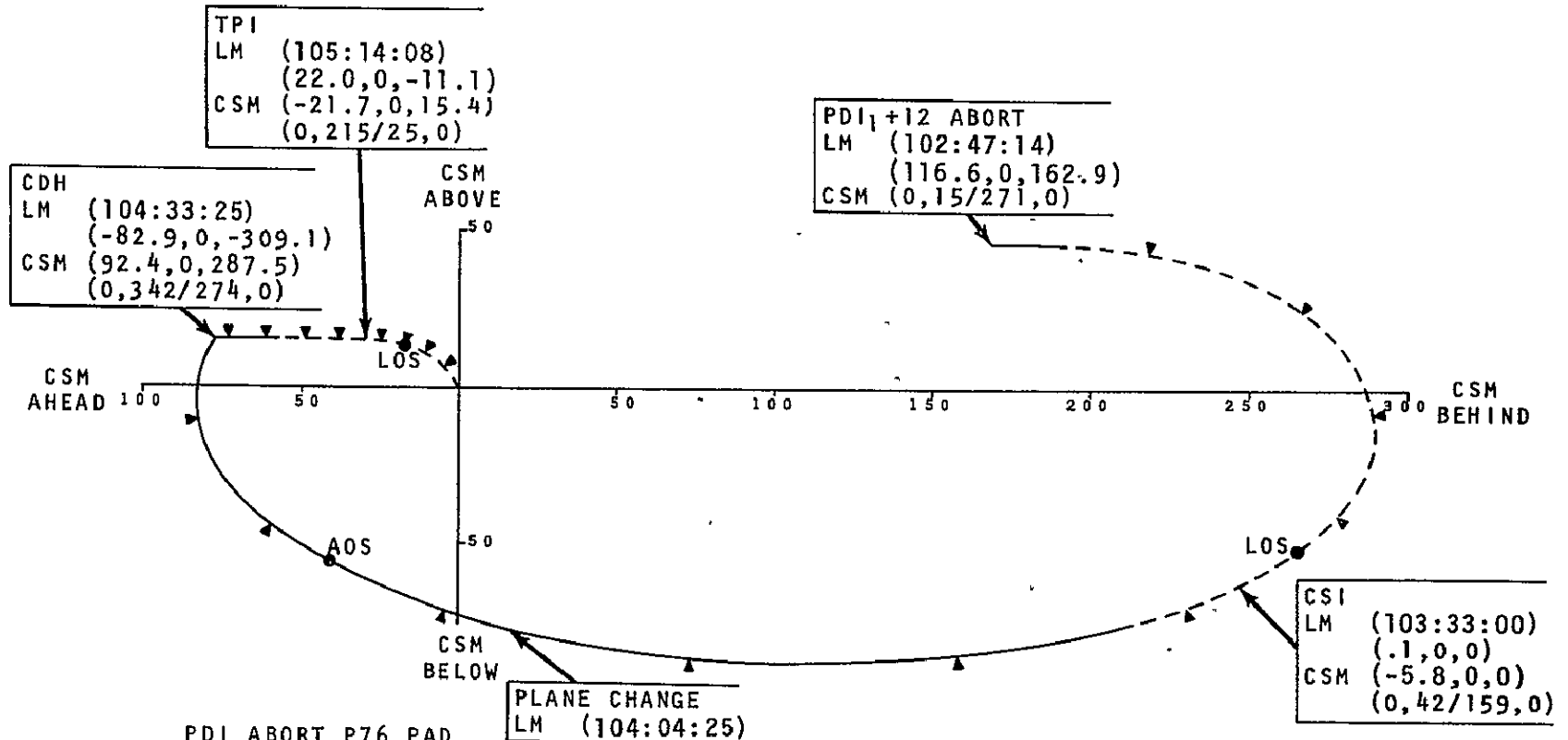
84	.	.	.
33	:	:	:



7.3 No PDI<sub>1</sub> + 12 (LM Active)

7.3.1 Summary

This situation arises when a failure prevents continuation of the planned mission after DOI and the LM initiates rendezvous with the CSM. The LM phasing burn is applied 12 minutes after nominal PDI<sub>1</sub> time and is targeted by the ground or obtained from onboard charts. The CSI maneuver is applied one-half revolution (LM) after phasing and the CDH maneuver is one-half rev later. TPI occurs approximately 40 minutes after CDH at a delta altitude of approximately 15 nautical miles and is targeted for a LM elevation angle of 26.6 degrees. The LM CSI burn is nominally zero; however, if it is necessary for the CSM to apply this burn, it is not nominally zero even though it is targeted for the LM CSI time.



PDI ABORT P76 PAD

84	•	•	•
33	•	•	•

CSM CSI COPY

11	•	•	•
37	•	•	•
75	•	•	•
81	•	•	•
82	•	•	•

LM CSI P76

84	•	•	•
33	•	•	•

CSM PC COPY

33	•	•
81	•	•

LM PC P76

84	•	•	•
33	•	•	•

CSM CDH COPY

13	•	•
75	•	•
81	•	•

LM CDH P76

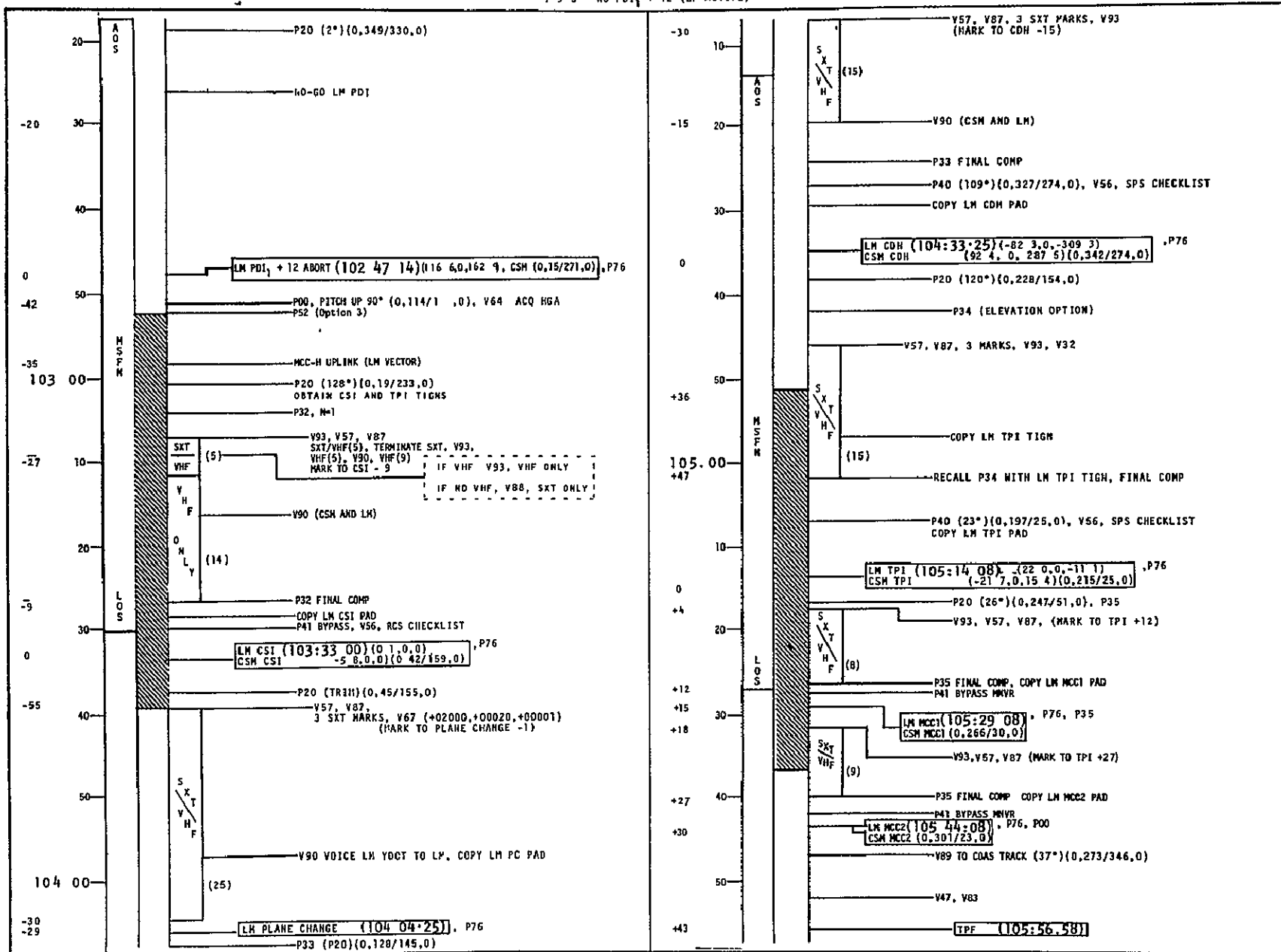
84	•	•	•
33	•	•	•

CSM TPI COPY

37	•	•
58	•	•
81	•	•
59	•	•

LM TPI P76

84	•	•	•
33	•	•	•

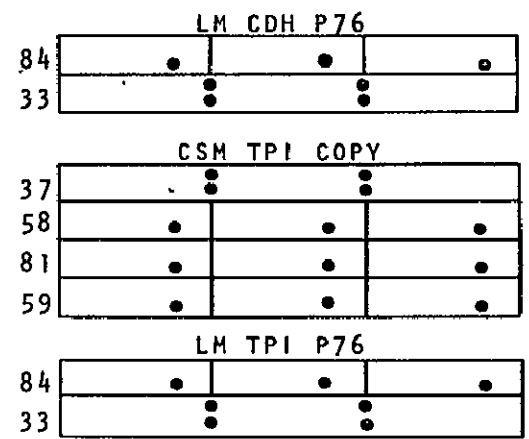
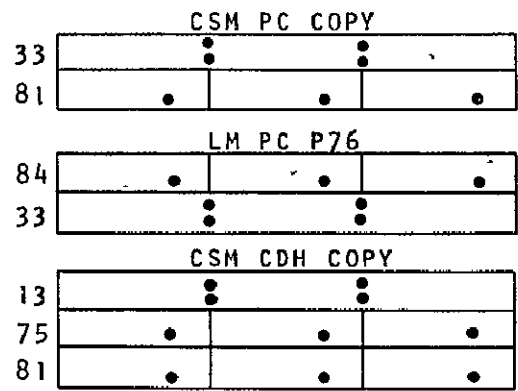
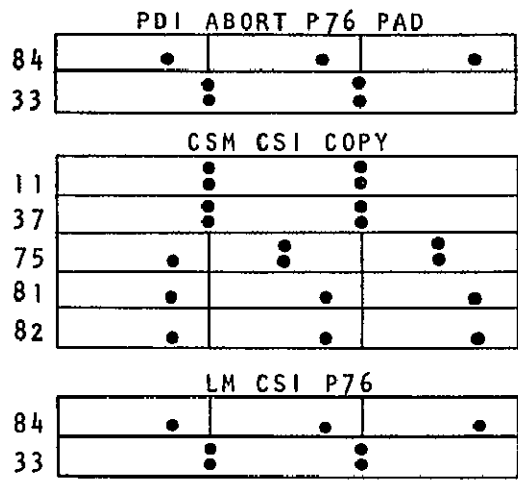
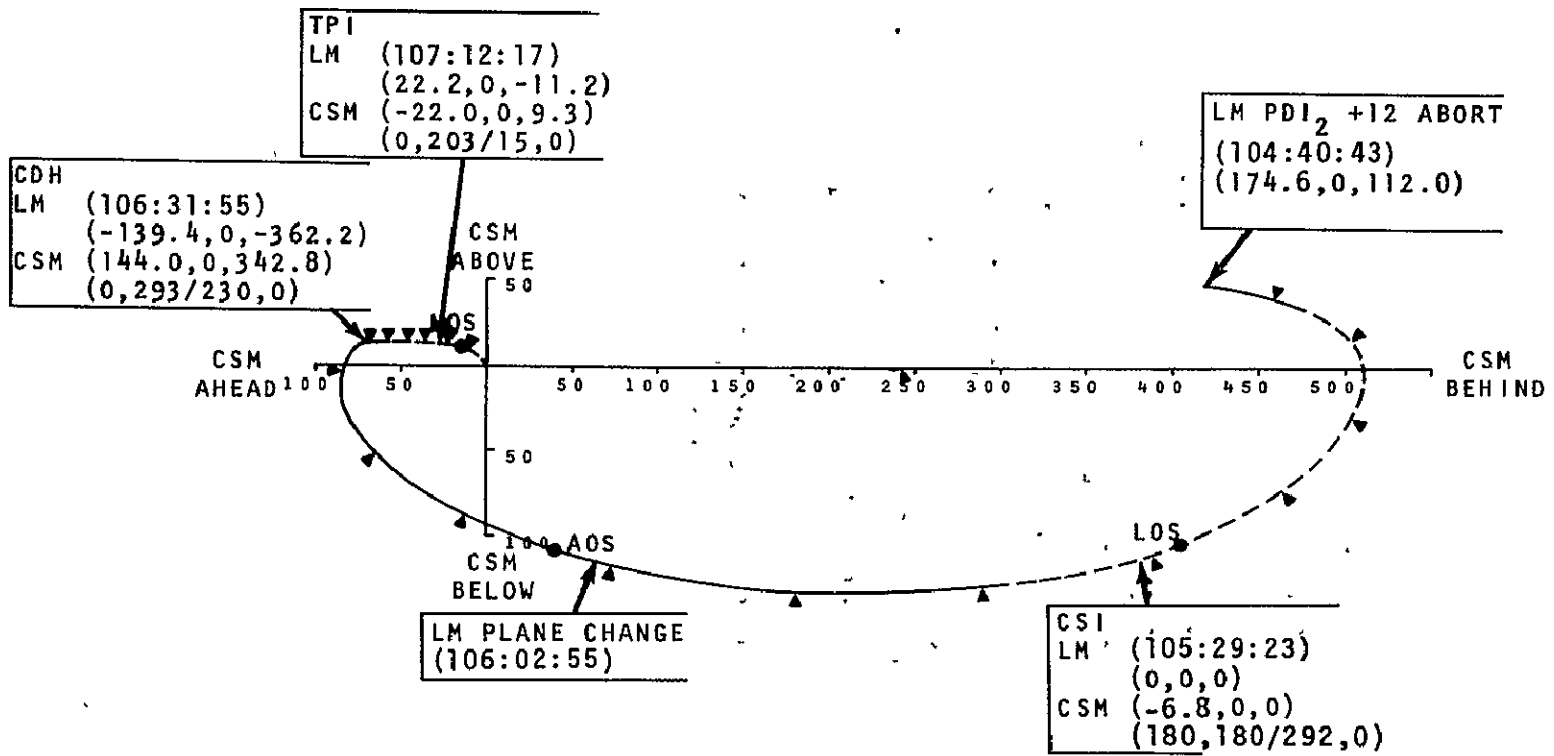


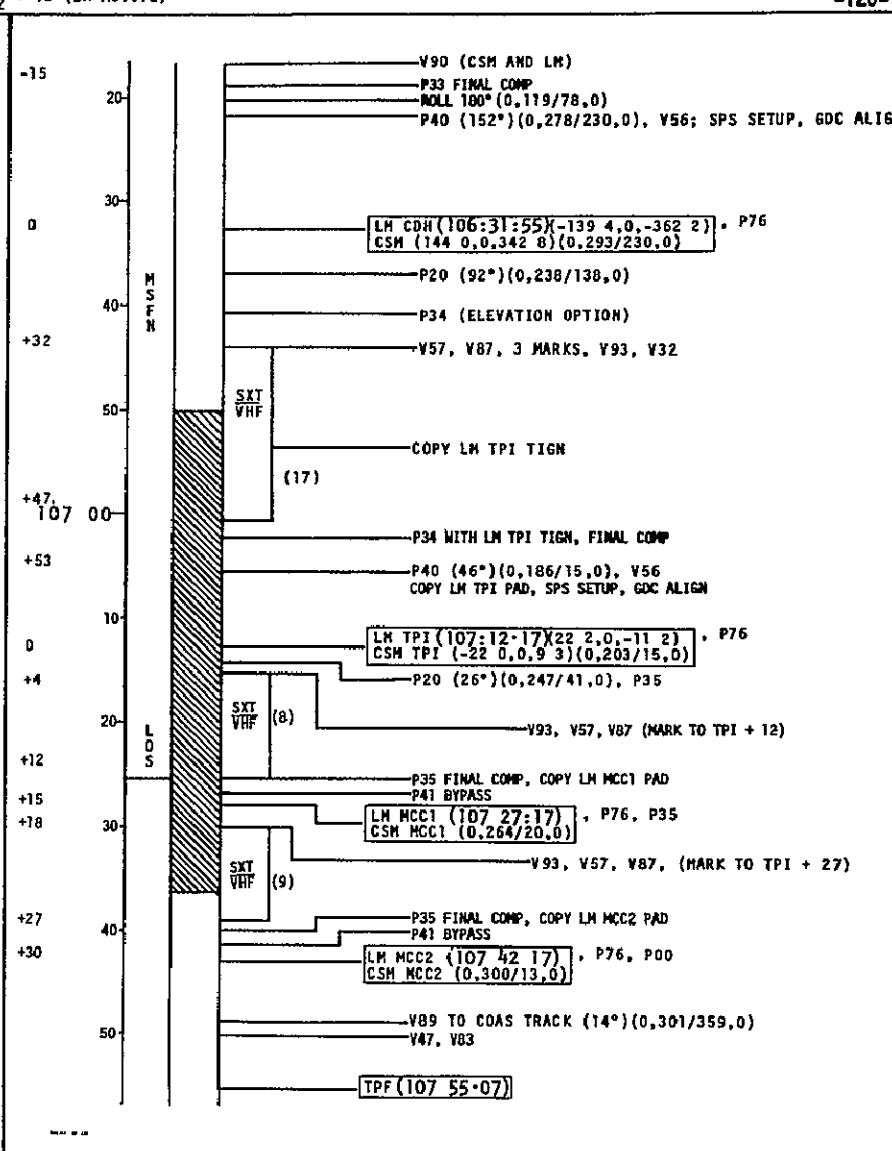
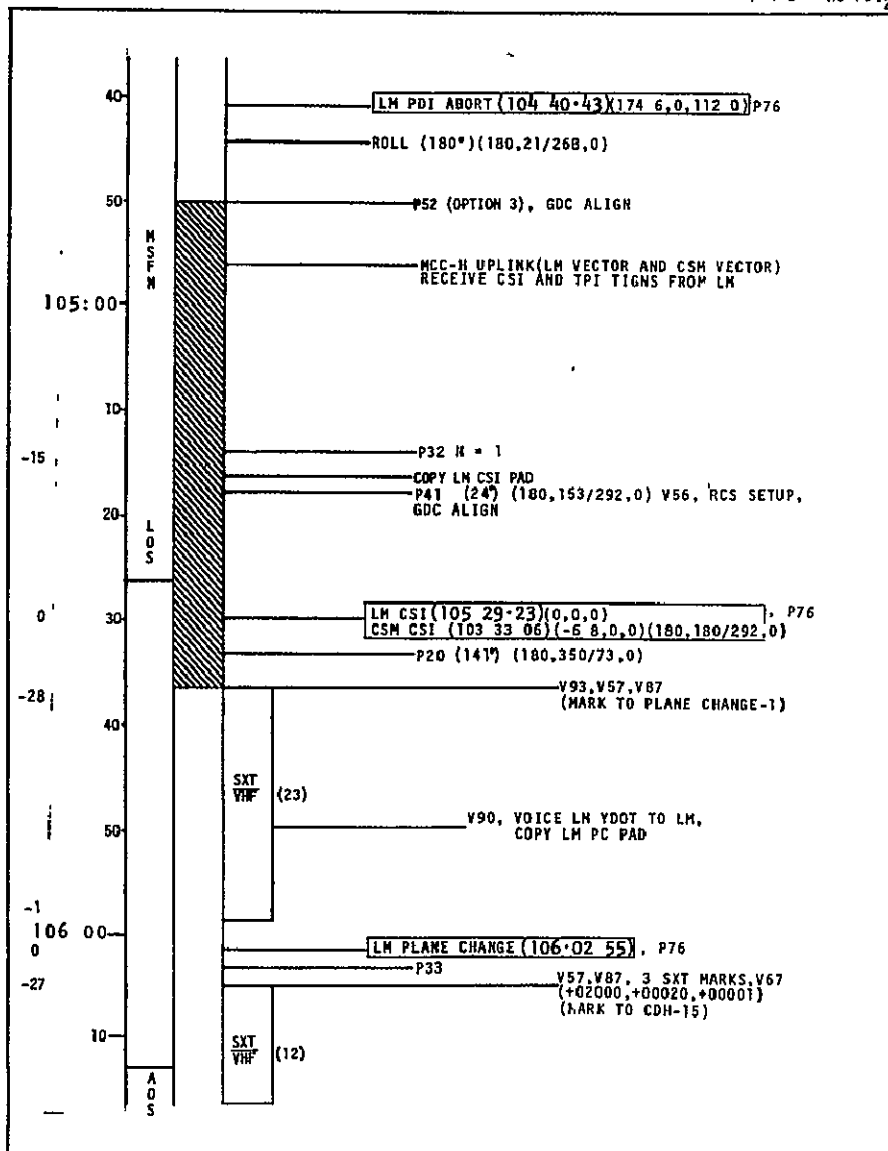


7.4 No PDI<sub>2</sub> + 12 (LM Active)

-7.4.1 Summary

This condition arises when the first PDI opportunity is passed due to some difficulty, but the difficulty is of such a nature that it is desired to try to initiate PDI at the second opportunity. If it is obvious at this time that the problem still exists, the LM initiates an abort. At 12 minutes after PDI<sub>2</sub> time, the phasing burn is applied. This burn is ground targeted or based on onboard charts. The CSI maneuver is applied one-half rev (LM) after phasing and the CDH maneuver is one-half rev later. TPI occurs at a delta altitude of 15 nautical miles and is targeted with a LM elevation angle of 26.6 degrees. The LM CSI burn is nominally zero; however, if it is necessary for the CSM to apply this burn, it is not nominally zero even though it is targeted for the LM CSI time.





7.5 < 60 No PDI<sub>1</sub> + 12 (CSM Active)

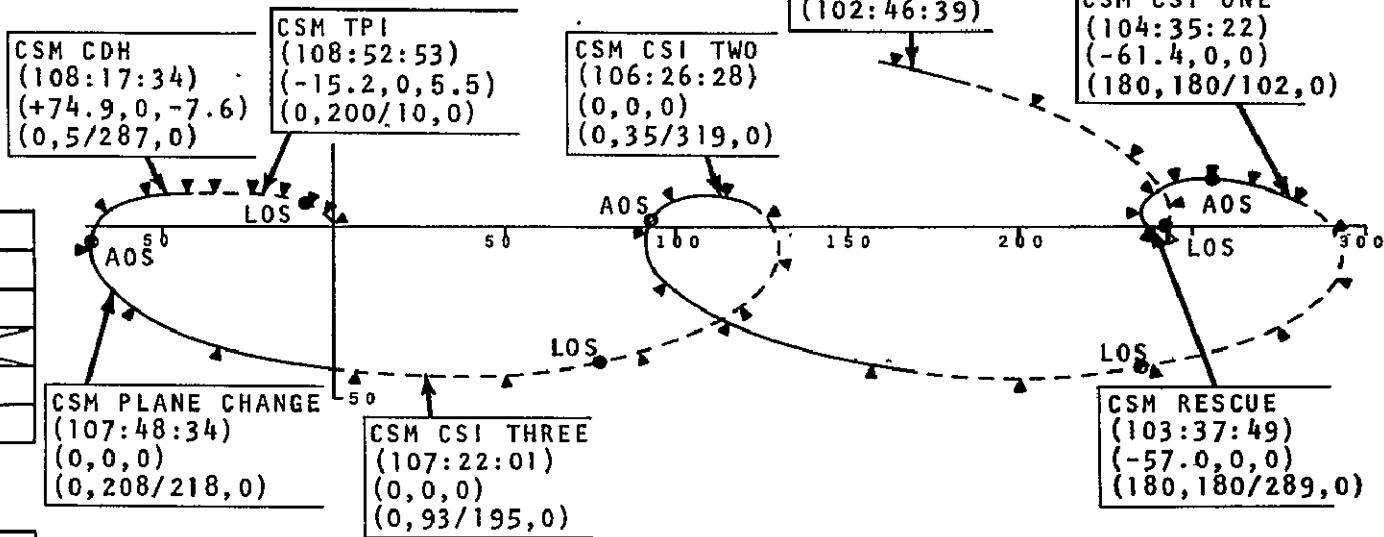
7.5.1 Summary

This situation occurs when the LM is completely inactive following the DOI burn or applies less than 60 feet per second of the phasing burn, i.e., the LM cannot apply the PDI burn nor can it complete the rendezvous. Under this condition, the CSM may accomplish the entire rendezvous. The first of the series of rescue burns is either ground targeted or taken from an onboard chart. This burn occurs at one rev after the DOI maneuver. A CSI<sub>1</sub> burn is applied one-half rev later and is targeted with a CDH to occur two revs later. A CSI<sub>2</sub> burn (nominally zero) is scheduled half way between CSI<sub>1</sub> and CDH. A third CSI (CSI<sub>3</sub>) again nominally zero is scheduled half way between CSI<sub>2</sub> and CDH. The CDH burn is targeted for a differential height of 10 nautical miles and the TPI burn is cued on a CSM elevation angle of 208.3 degrees.

The relative profile and the burns shown in the following pages represent the particular situation where the LM was not able to apply any of the phasing burn. This data for all cases where a partial burn less than 60 feet per second is applied will vary although the same basic checklist may be followed.

RESCUE TWO PAD

47	+		+		
48	-		+		
33	00	:	000	:	0
81					
22	XXX	:	XXX	:	XXX
ΔV <sub>c</sub>	X	:		:	
11	00	:	000	:	0
37	00	:	000	:	0
N					



CSM CSI ONE COPY

11	:	:	
37	:	:	
75	.	.	.
81	.	.	.
82	.	.	.

CSM CSI THREE COPY

11	:	:	
37	:	:	
75	.	:	:
81	.	.	.
82	.	.	.

CSM CDH COPY

13	:	:	
75	.	.	.
81	.	.	.

LM CSI ONE P76

84	.	.	.
33	:	:	

LM CSI THREE P76

84	.	.	.
33	:	:	

LM CDH P76

84	.	.	.
33	:	:	

CSM CSI TWO COPY

11	:	:	
37	:	:	
75	.	:	:
81	.	.	.
82	.	.	.

CSM PC COPY

33	:	:	
81	.	.	.

CSM TPI COPY

37	:	:	
58	.	.	.
81	.	.	.
59	.	.	.

LM CSI TWO P76

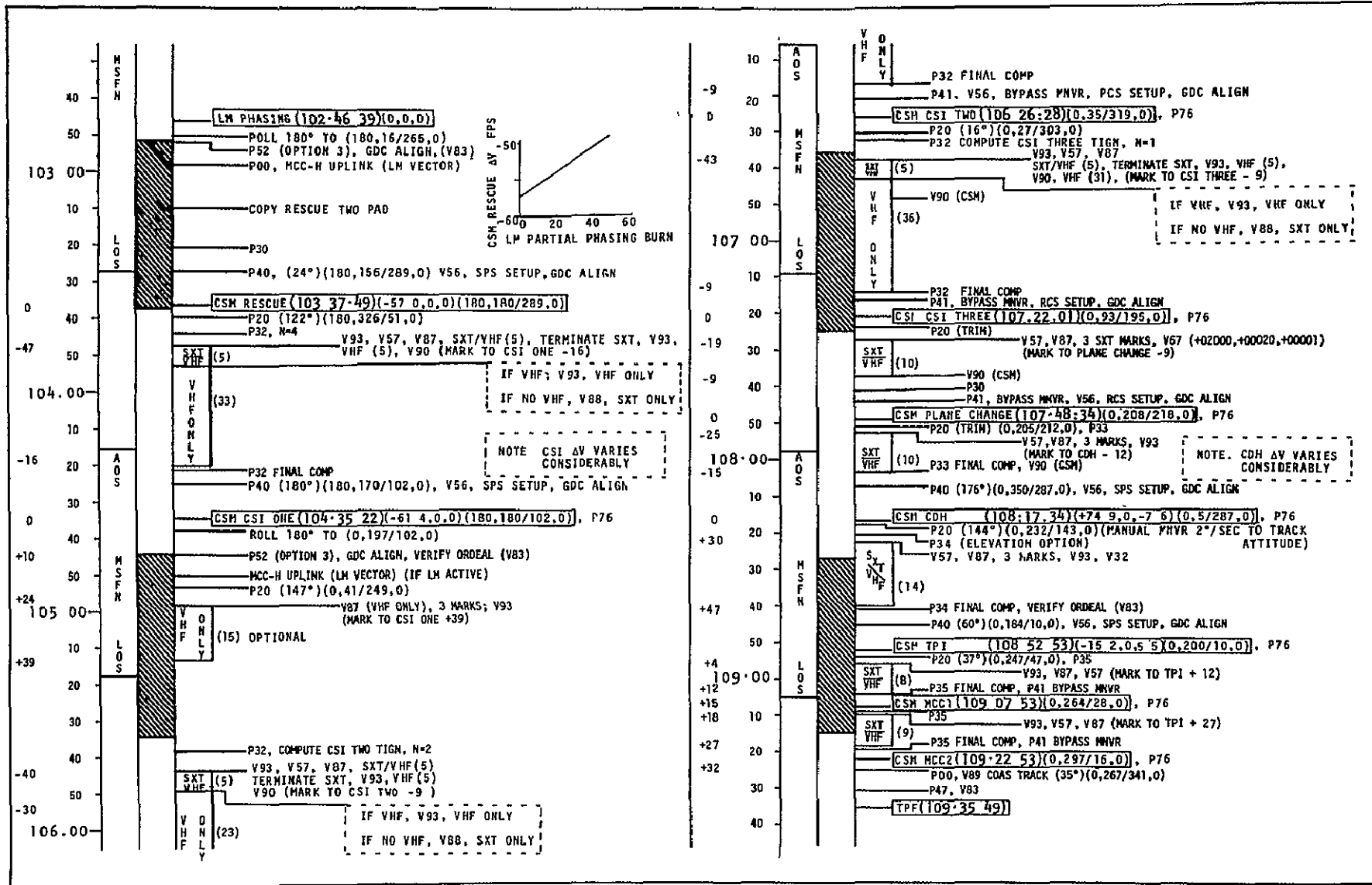
84	.	.	.
33	:	:	

LM PC P76

84	.	.	.
33	:	:	

LM TPI P76

84	.	.	.
33	:	:	

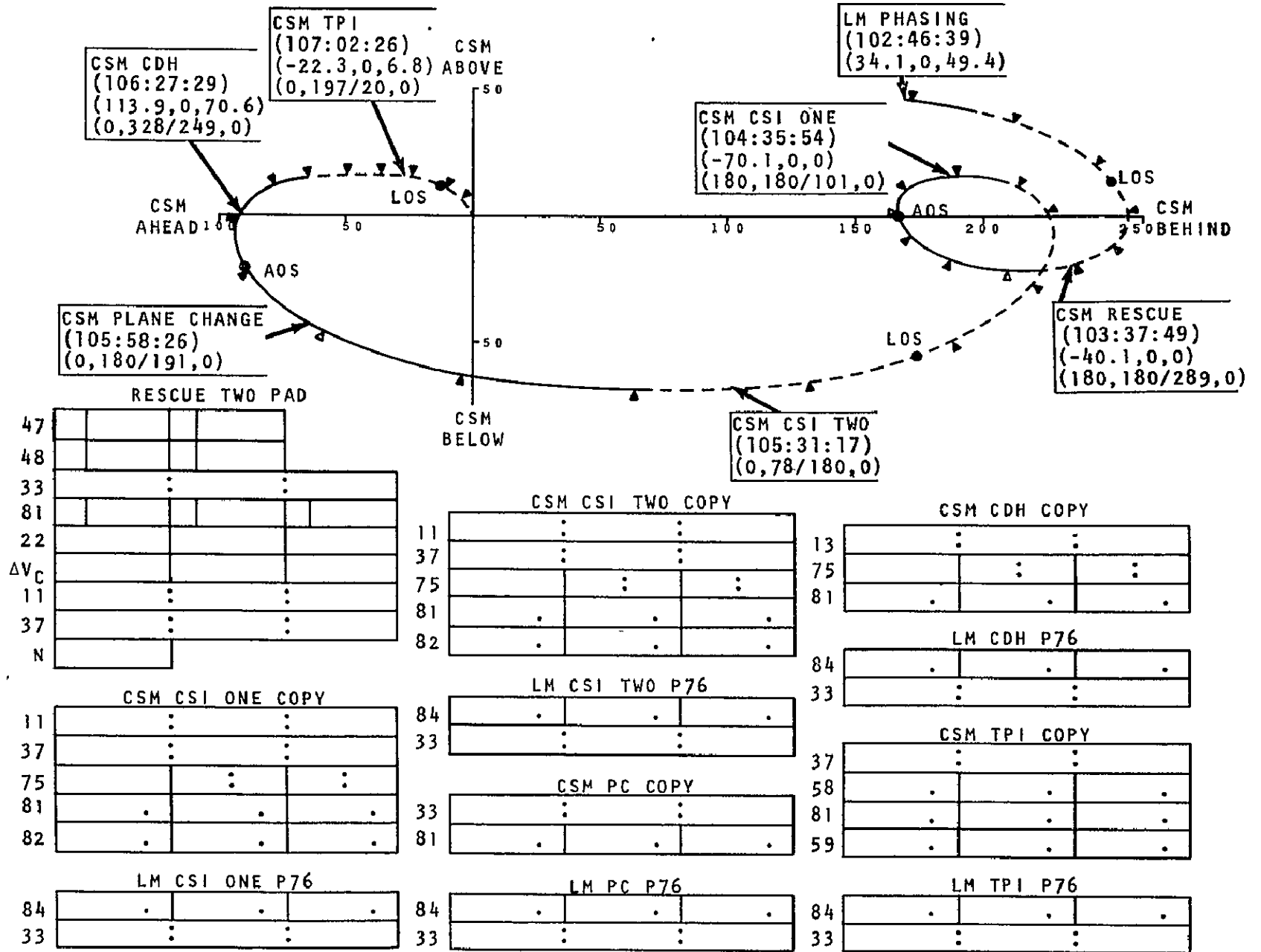


7.6  $\geq 60 \text{ No PDI}_1 + 12 \text{ (CSM Active)}$

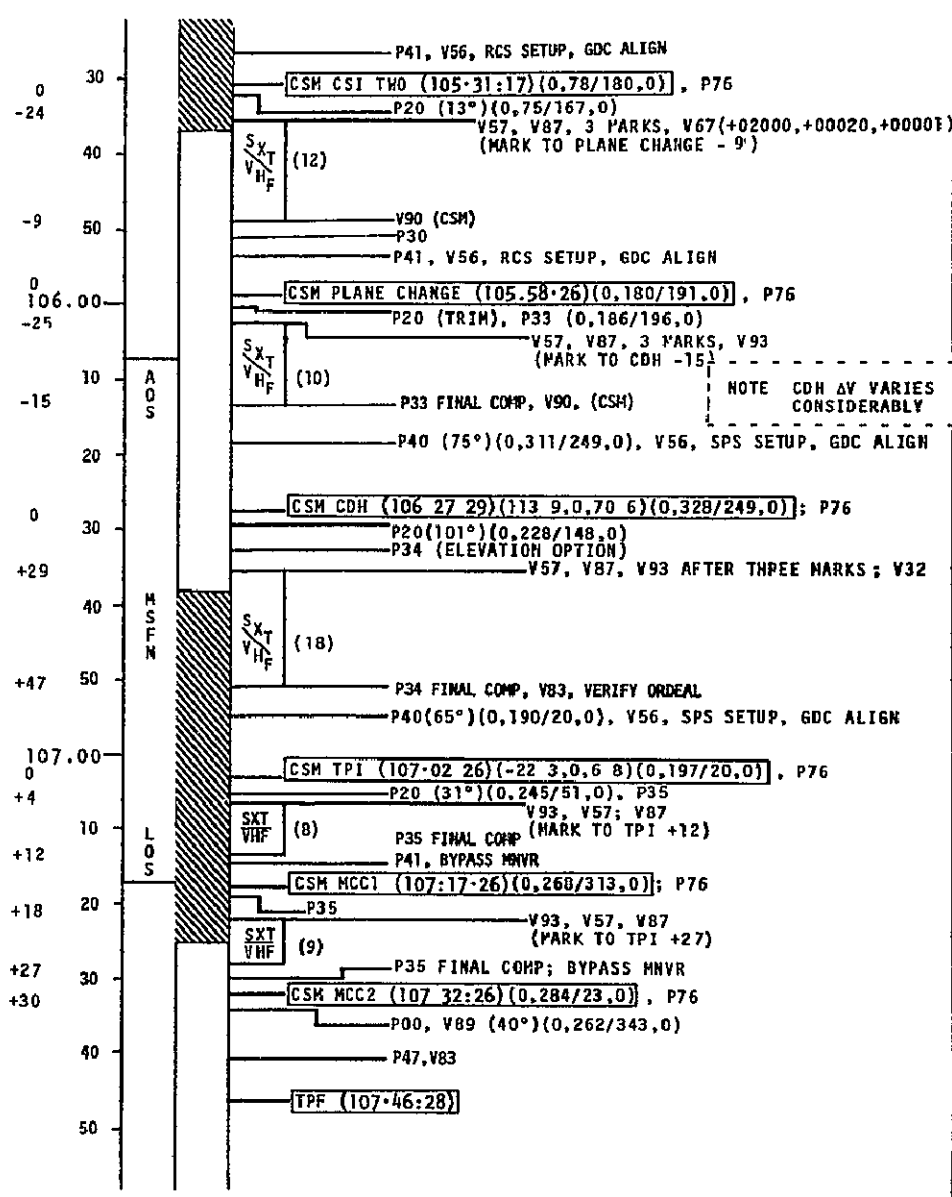
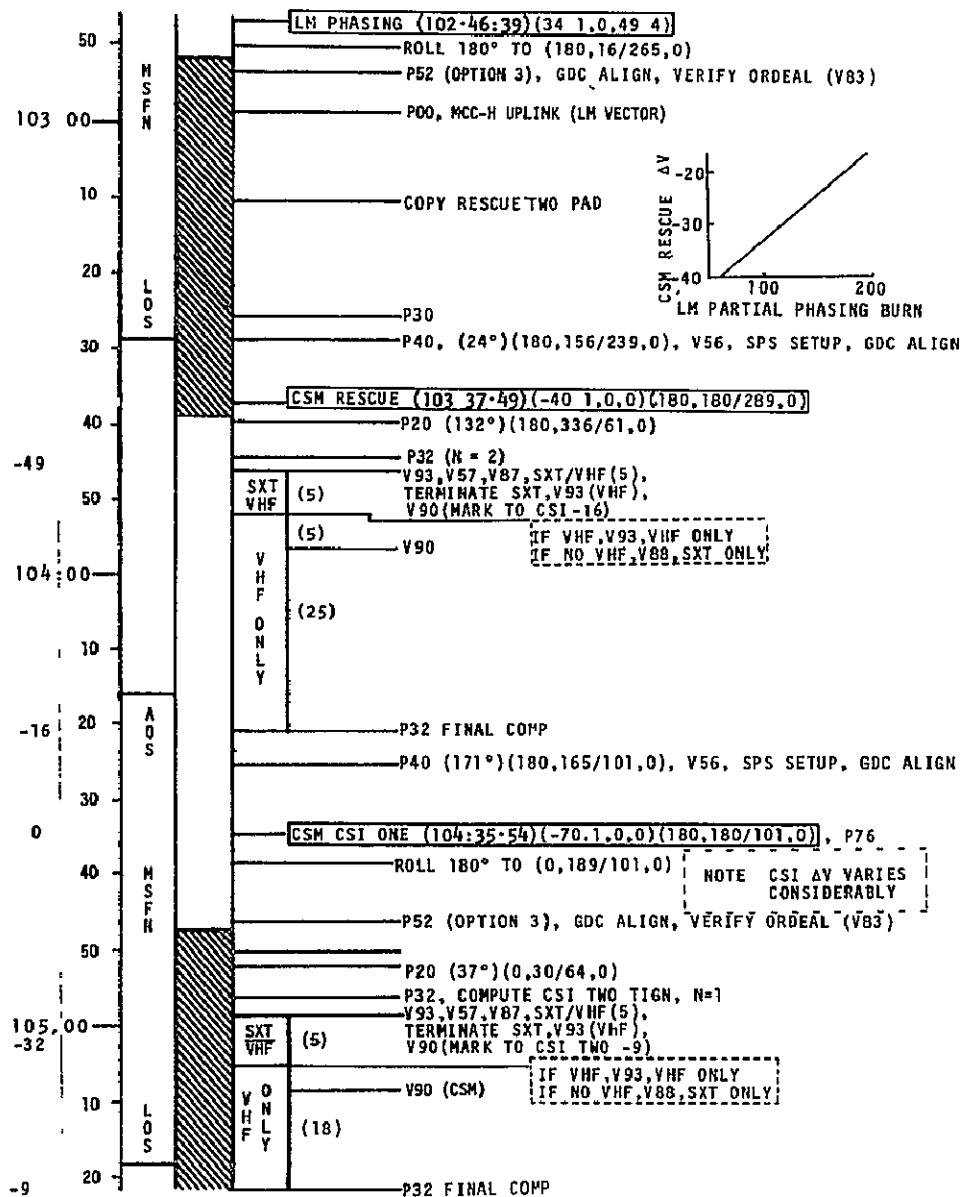
7.6.1 Summary

This rescue case provides for the situation where the LM applies at least 60 feet per second of the phasing burn but cannot complete the burn and it is necessary for the CSM to initiate a rescue. This case is similar to the previous case except that one less rev is required for rendezvous since at least a partial phasing burn was achieved. The initial rescue burn occurs one rev after DOI and is again ground targeted or taken from an on-board chart. The  $\text{CSI}_1$  burn occurs one-half rev after the initial rescue burn and is targeted for a CDH one rev later. A  $\text{CSI}_2$  burn, nominally zero, is scheduled one-half way between  $\text{CSI}_1$  and CDH. The CDH burn results in a differential height of approximately 15 nautical miles and the TPI burn is cued on a CSM elevation angle of 208.3 degrees.

The relative profile and the burns shown in the following pages represent the particular situation where the LM applies a partial burn of 60 feet per second. This data for all cases where a partial burn greater than 60 feet per second is applied will vary although the same basic checklist may be followed.





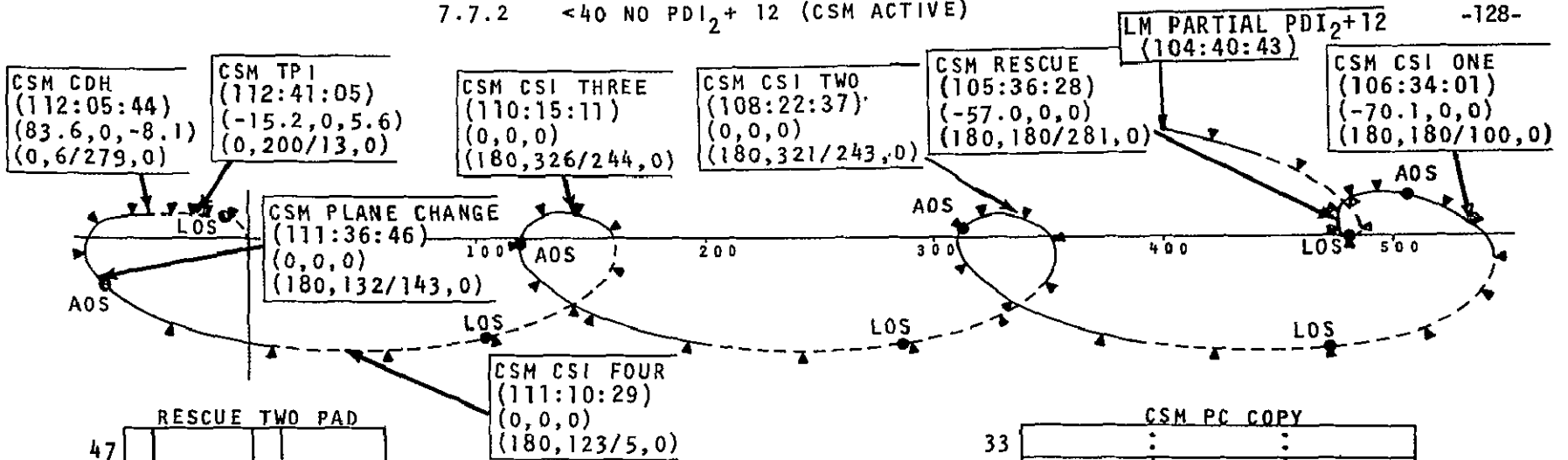


7.7 < 40 No PDI<sub>2</sub> + 12 (CSM Active)

7.7.1 Summary

This situation occurs when the LM is inactive and unable to apply the PDI<sub>2</sub> maneuver and is able to achieve less than 40 feet per second of the phasing maneuver. Under these conditions, the CSM initiates a rescue with the first burn occurring two revs after DOI. CSI<sub>1</sub> occurs 180 degrees later with a CSI<sub>2</sub> and CSI<sub>3</sub> (both nominally zero) occurring one and two revs later, respectively. CSI<sub>4</sub> occurs 180 degrees after CSI<sub>3</sub> and CDH occurs three revs after CSI<sub>1</sub> at a delta altitude of 10 nautical miles. With this rendezvous situation, rendezvous would be completed approximately 12 hours after DOI.

The relative profile and the burns shown in the following pages represent the particular situation where the LM is unable to apply any of the phasing burn. This data for all cases where the LM applies a partial burn less than 40 feet per second will vary although the same basic checklist may be followed.



RESCUE TWO PAD

47			
48			
33	:	:	:
81			
22			
ΔV <sub>C</sub>			
11	:	:	:
37	:	:	:
N			

LM CSI TWO P76

84	.	.	.
33	:	:	:

CSM PC COPY

33	:	:	:
81	.	.	.

LM PC P76

84	.	.	.
33	:	:	:

CSM CSI THREE COPY

11	:	:	:
81	.	.	.

CSM CDH COPY

13	:	:	:
75	.	:	:
81	.	.	.

CSM CSI ONE COPY

11	:	:	:
37	:	:	:
75	.	:	:
81	.	.	.
82	.	.	.

LM CSI THREE P76

84	.	.	.
33	:	:	:

LM CDH P76

84	.	.	.
33	:	:	:

CSM CSI FOUR COPY

11	:	:	:
37	:	:	:
75	.	:	:
81	.	.	.
82	.	.	.

CSM TPI COPY

37	:	:	:
58	.	.	.
81	.	.	.
59	.	.	.

LM CSI ONE P76

84	.	.	.
33	:	:	:

LM CSI FOUR P76

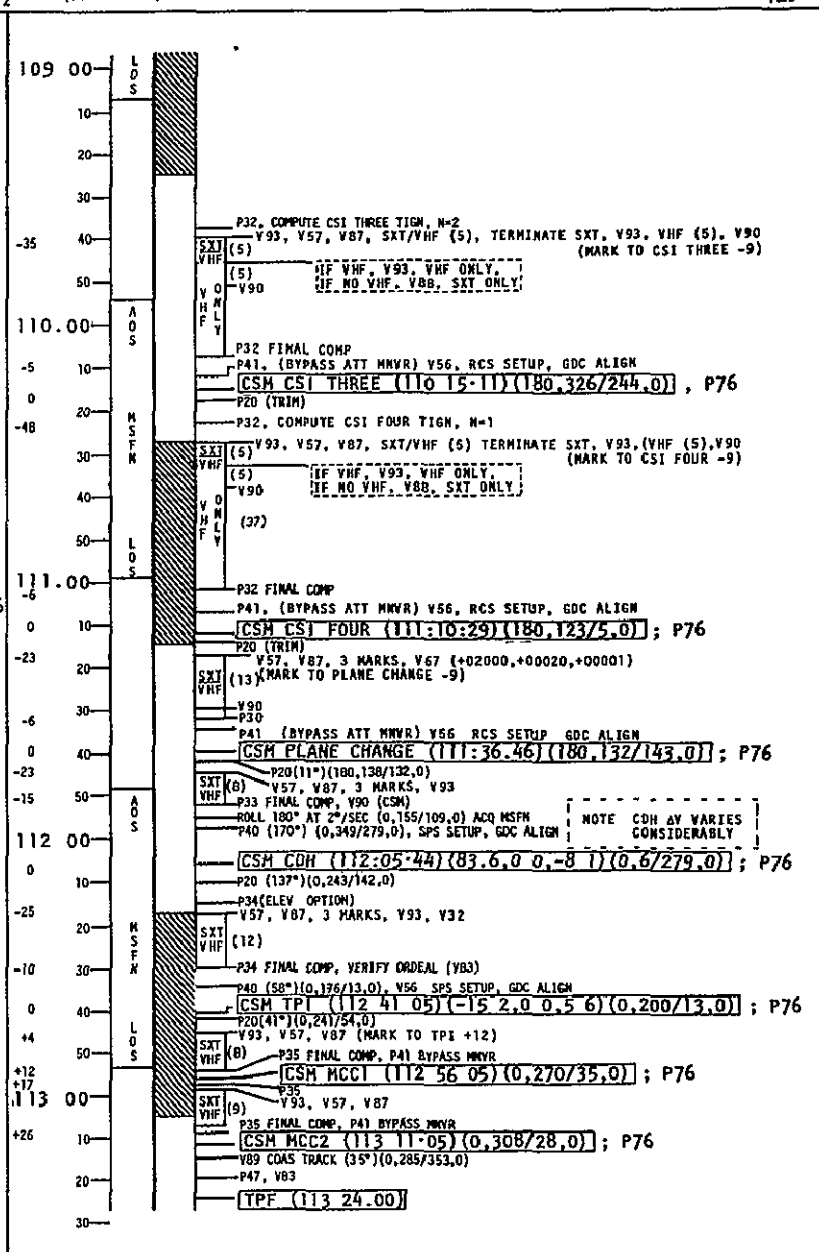
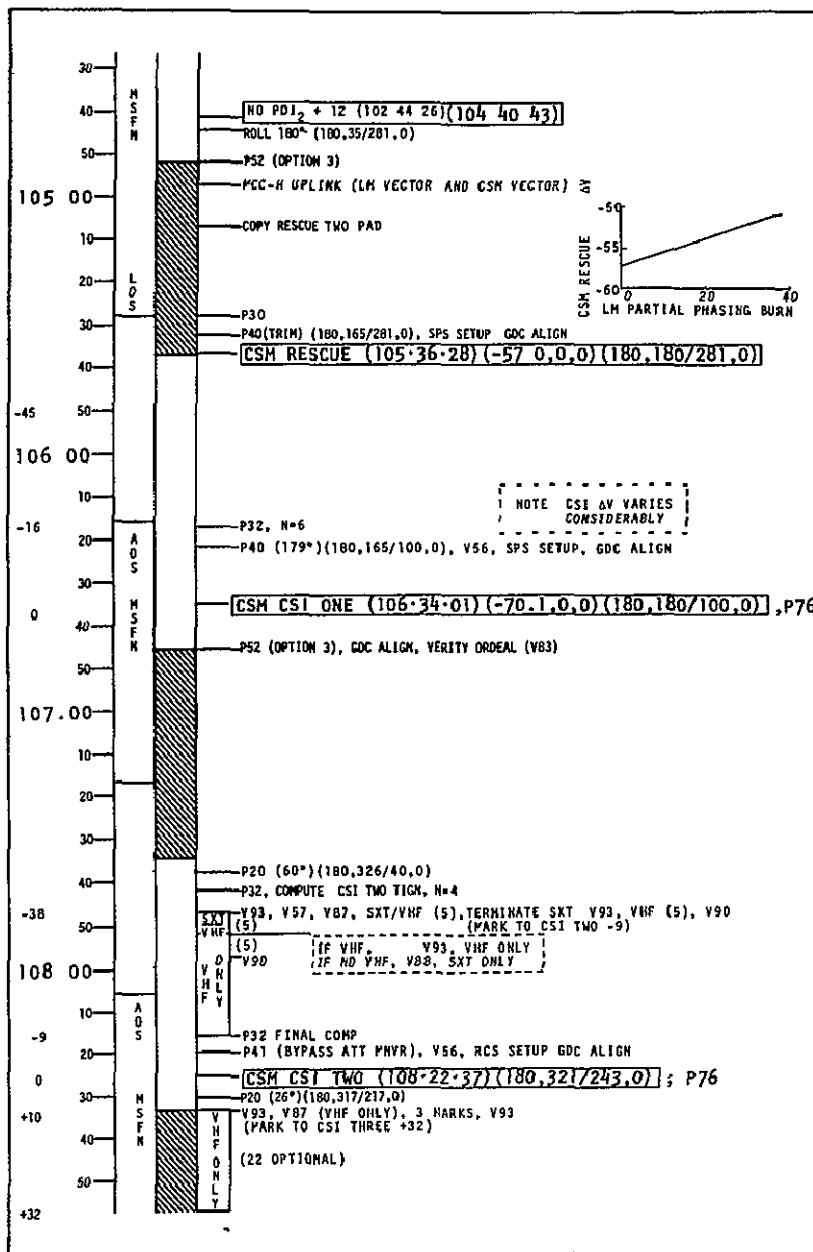
84	.	.	.
33	:	:	:

LM TPI P76

84	.	.	.
33	:	:	:

CSM CSI TWO COPY

11	:	:	:
81	.	.	.

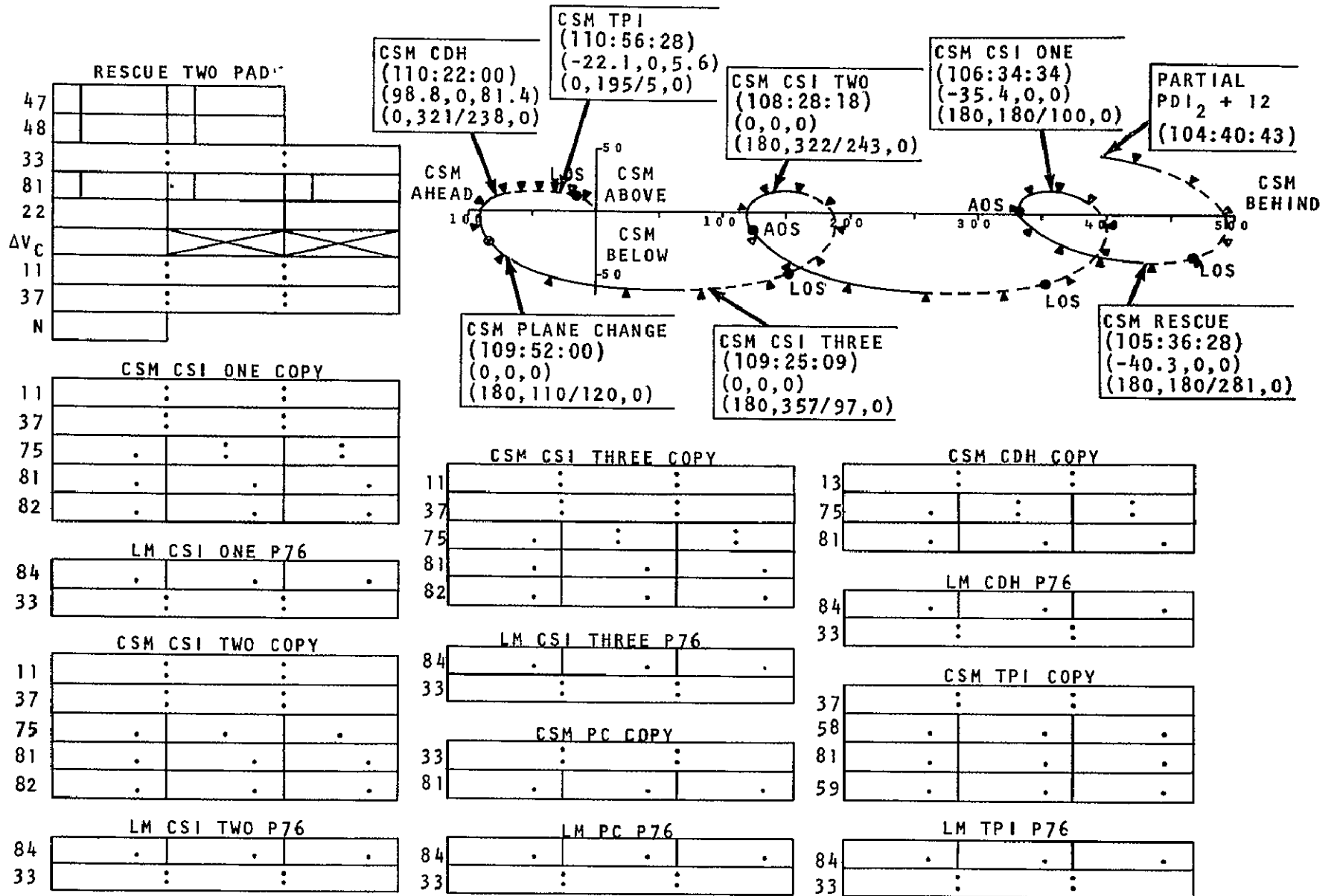


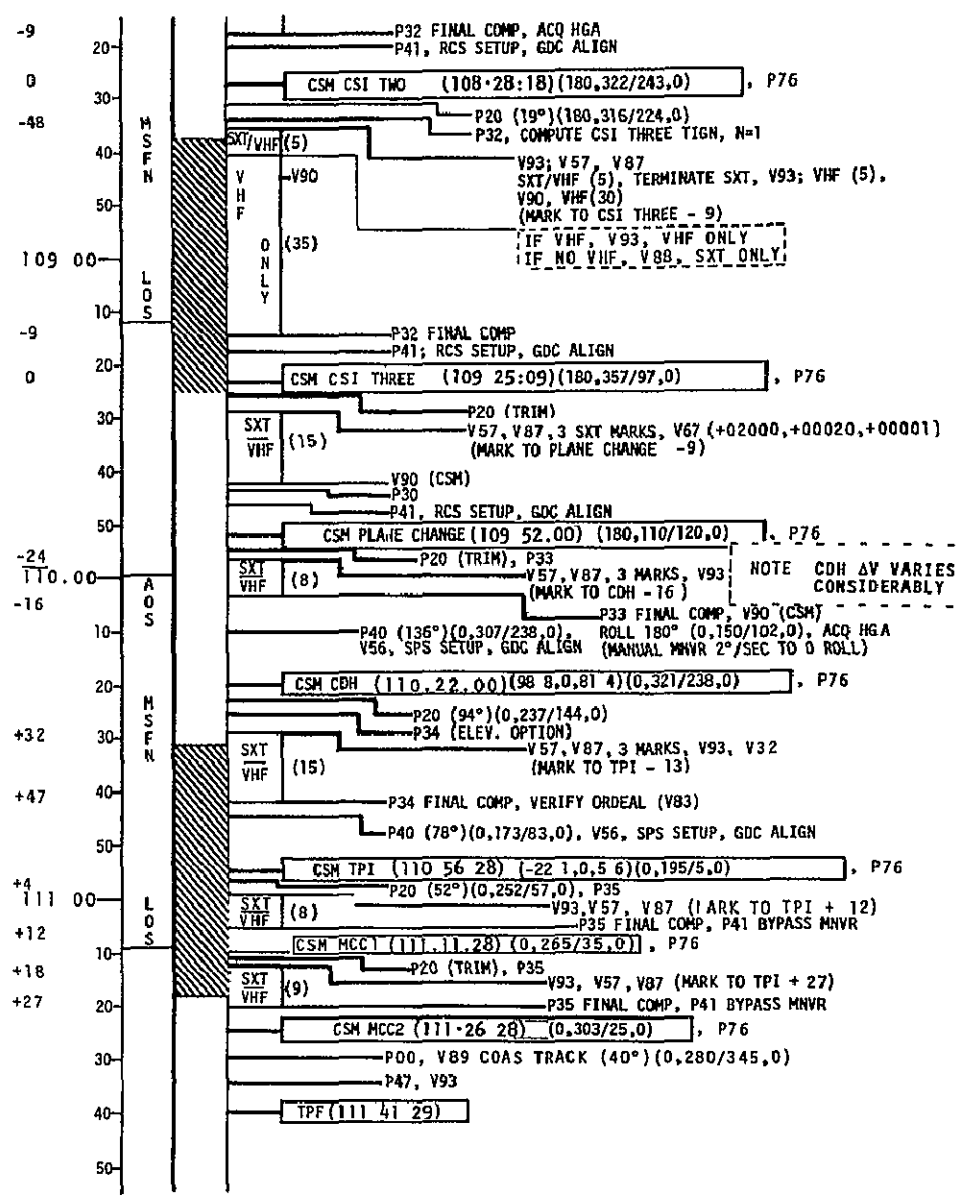
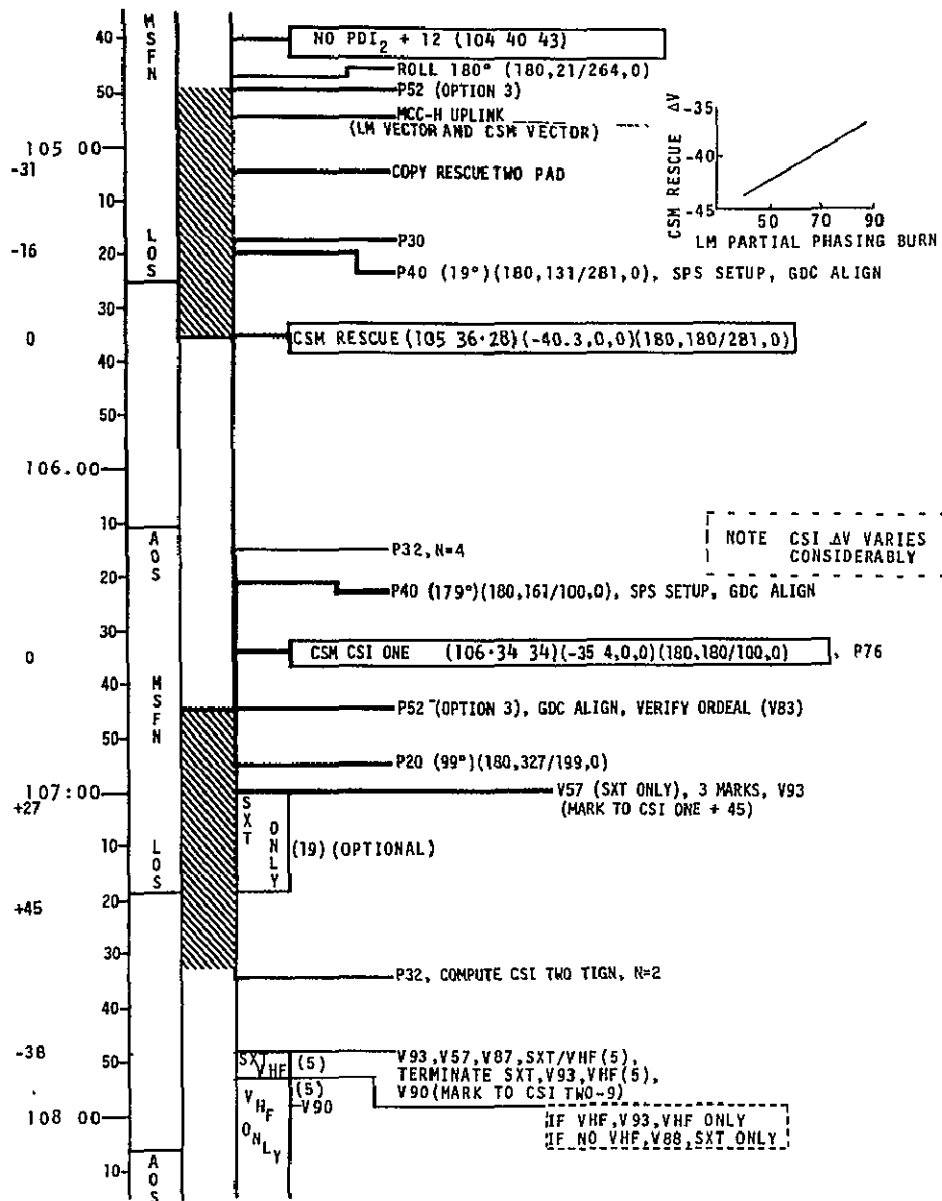
7.8 40-90 No PDI<sub>2</sub> + 12 (CSM Active)

7.8.1 Summary

This rescue case provides for the situation where the LM could not complete the phasing burn after initiating an abort at PDI<sub>2</sub>. The first rescue burn occurs two revs after DOI and is followed by CSI<sub>1</sub> one-half rev later. The CSI<sub>1</sub> burn is targeted for a CDH to occur two revs later at a delta altitude of 15 nautical miles with the CSI<sub>2</sub> burn (nominally zero) scheduled half way between CSI<sub>1</sub> and CDH. The rendezvous would be completed approximately 10 hours after DOI.

The relative profile and the burns shown in the following pages represent the particular situation where the LM applies a partial burn of 65 feet per second. This data for other cases where a partial burn between 40 and 90 feet per second is applied will vary although the same basic checklist may be followed.





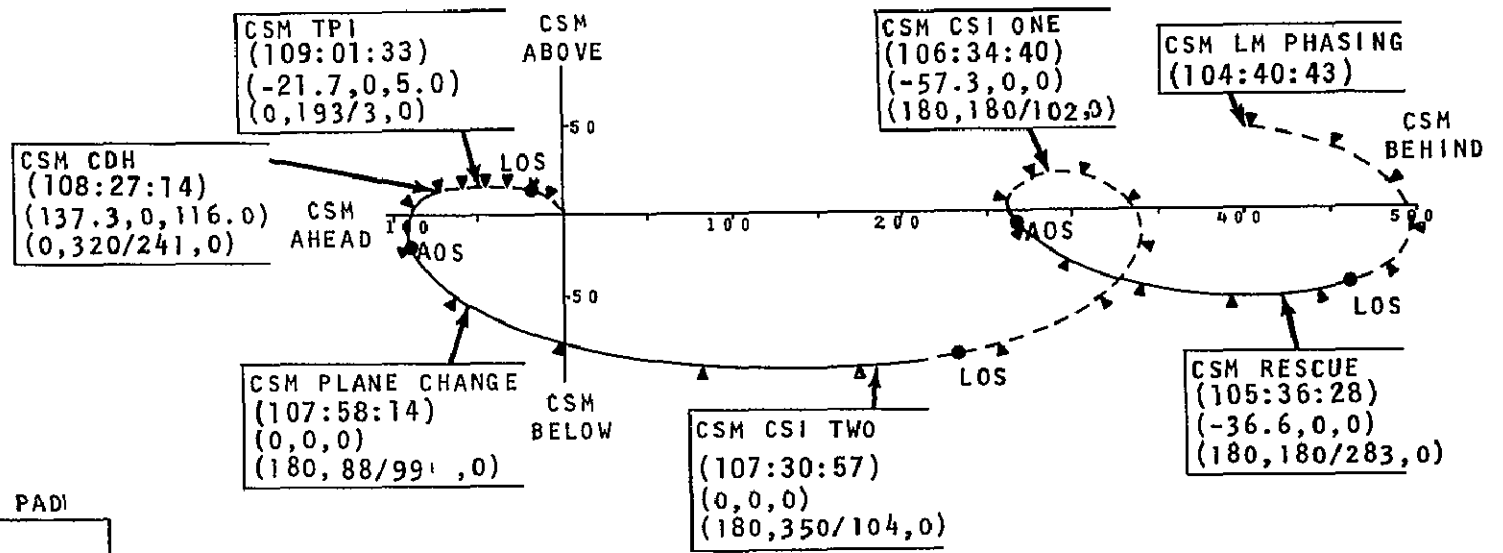
7.9 ≥ 90 No PDI<sub>2</sub> + (CSM Active)

7.9.1 Summary

This rescue provides for the situation where the LM completes a partial phasing burn greater than 90 feet per second. This case is similar to the previous 40-90 No PDI<sub>2</sub> + 12 Rescue except that one less rev is required between CSI<sub>1</sub> and CDH. This rendezvous would be completed approximately 8 hours after DOI.

The relative profile and the burns shown in the following pages represent the particular situation where the LM applies a partial burn of 90 feet per second. This data for all cases where a partial burn greater than 90 feet per second is applied will vary although the same basic checklist may be followed.





RESCUE TWO PADI

47			
48			
33	:	:	
81			
22			
$\Delta V$			
11	:	:	
37			
N			

CSM CS1 TWO COPY

11	:	:	
37	:	:	
75	.	:	:
81	.	.	.
82	.	.	.

CSM CDH COPY

13	:	:	
75	.	.	.
81	.	.	.

CSM CS1 ONE COPY

11	:	:	
37	:	:	
75	.	:	:
81	.	.	.
82	.	.	.

LM CS1 TWO P76

84	.	.	.
33	:	:	

LM CDH P76

84	.	.	.
33	:	:	

LM CS1 ONE P76

84	.	.	.
33	:	:	

CSM PC COPY

33	:	:	
81	.	.	.

CSM TPI COPY

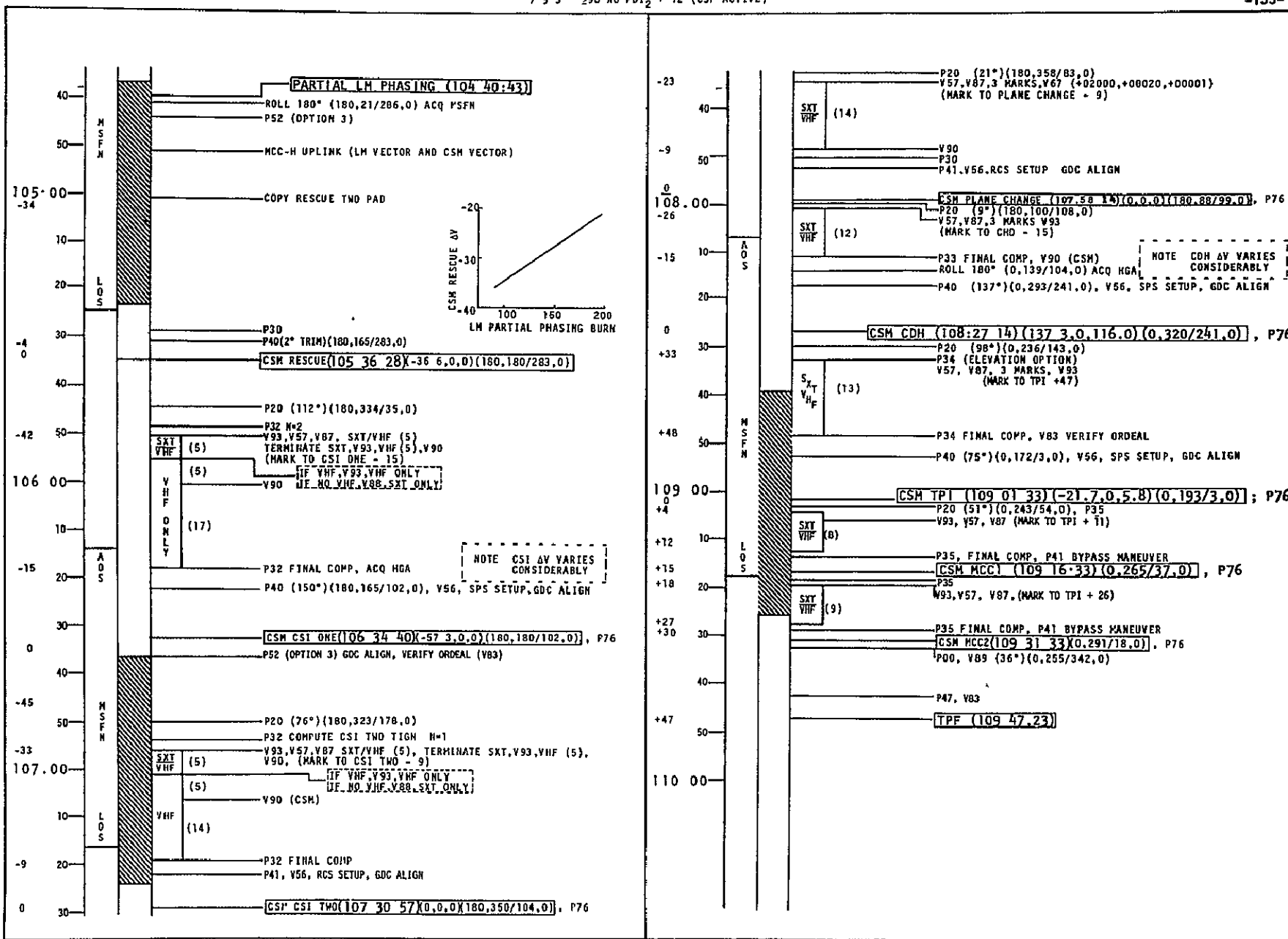
37	:	:	
58	.	.	.
81	.	.	.
59	.	.	.

LM PC P76

84	.	.	.
33	:	:	

LM TPI P76

84	.	.	.
33	:	:	



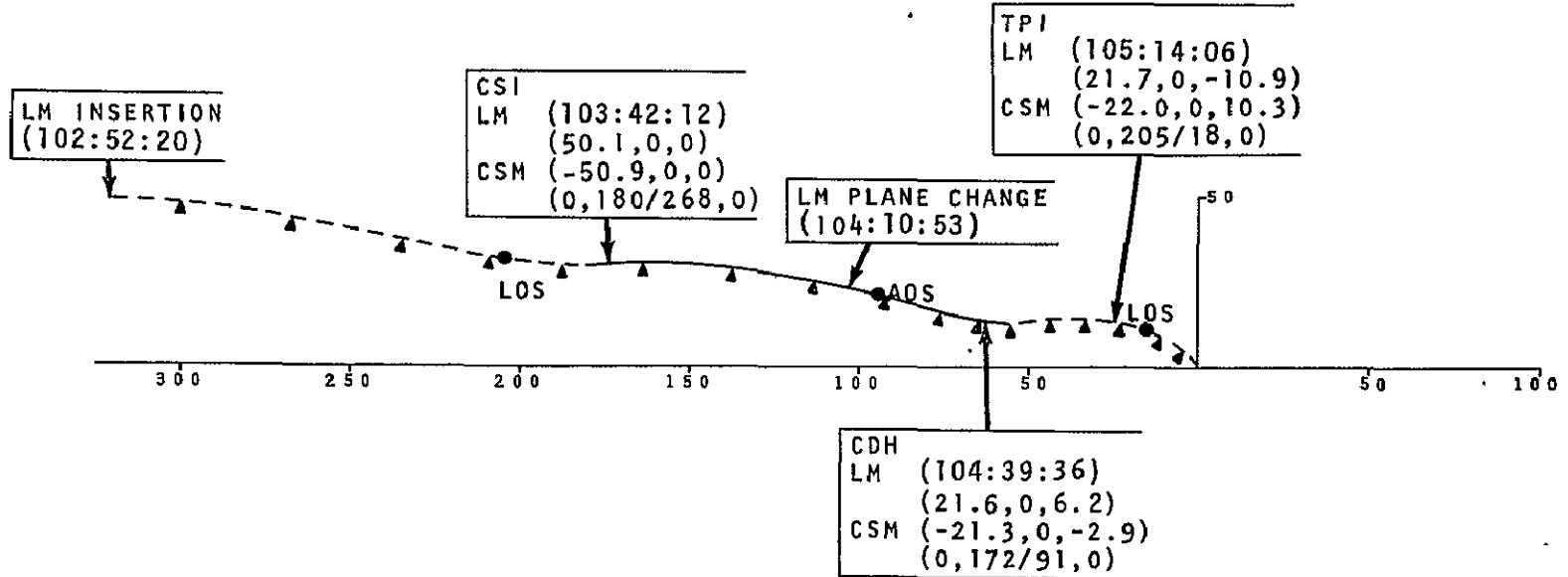
7.10 PDI<sub>1</sub> < 10 Variable Insertion (LM Active)

7.10.1 Summary

This rescue results from an abort less than 10 minutes into the powered descent. Under these conditions, the LM inserts into a variable insertion orbit. No rescue burn is required for this rendezvous. The first burn, CSI is scheduled at 50 minutes after LM insertion with CDH one-half rev later.

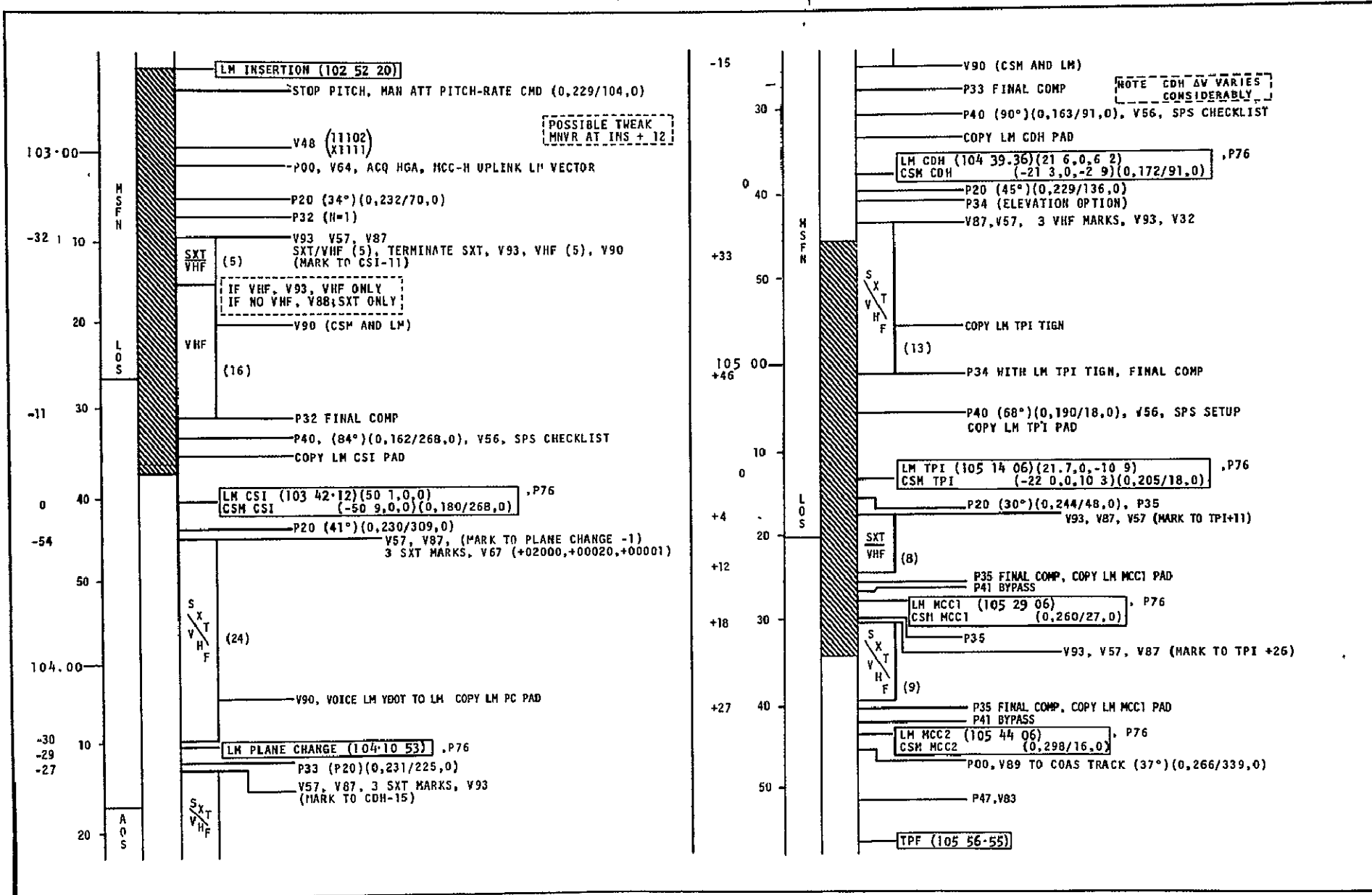
The relative profile and the burns shown in the following pages represent the particular situation where the abort occurs at PDI<sub>1</sub> + 10 minutes. This data for other cases where the abort is initiated less than 10 minutes into the descent will vary particularly for the CDH burn. However, the same basic checklist is applicable.

7.10.2. PDI<sub>1</sub> <10 VARIABLE INSERTION (LM ACTIVE)



CSM CSI COPY			CSM PC COPY			LM CDH P76			
11	.	.	33	:	:	84	.	.	.
37	.	.	81	.	.	33	:	:	.
75	.	:	84	.	.	37	:	:	.
81	.	.	33	:	:	58	.	.	.
82	.	.	33	:	:	81	.	.	.
						59	.	.	.
LM CSI P76			CSM CDH COPY			LM TPI COPY			
84	.	.	13	:	:	84	.	.	.
33	:	:	75	.	:	84	.	.	.
			81	.	.	33	:	:	.

7 10 3 PDI, <10 VARIABLE INSERTION (LM ACTIVE)  
 CHECKLIST GENERATED FOR ABOPT AT PDI, +10

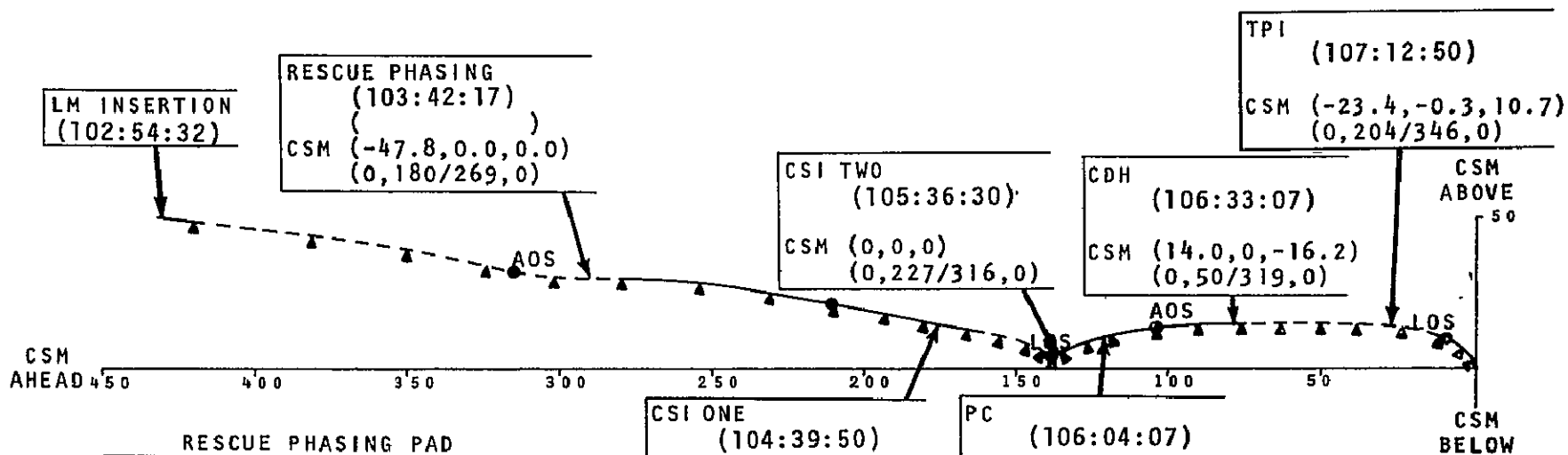


7.11 PDI<sub>1</sub> + 12 (10-12.5 Minutes) (CSM Active) -

7.11.1 Summary

This rescue results from an abort during the powered descent. It is assumed that following the decision to abort, the LM will be able to insert into a fixed 10 X 30 orbit and that the CSM will then complete the rendezvous. The initial rescue phasing burn will be performed at a fixed GET defined as 50 minutes from that insertion cut off time associated with an abort at PDI<sub>1</sub> + 10 minutes. This rescue phasing burn will be a constant 47.8 feet per second retrograde burn for cases where an abort is initiated between PDI<sub>1</sub> + 10 and PDI<sub>1</sub> + 12.5 minutes. The CSI<sub>1</sub> burn is targeted for the LM CSI time and occurs approximately one-half rev after the rescue phasing burn. The CDH burn is scheduled for one rev after CSI<sub>1</sub> with a nominally zero CSI<sub>2</sub> burn half way between CSI<sub>1</sub> and CDH. For this rescue situation, rendezvous is completed approximately six hours after DOI.

The relative profile and burns shown in the following pages represent the particular situation where the abort occurs at PDI<sub>1</sub> + 12 minutes. This data for other cases where the abort is initiated between 10 and 12.5 minutes after PDI will vary; however, the same basic checklist is applicable.



RESCUE PHASING PAD

47				
48				
33				
81				
22				
ΔV <sub>C</sub>				
11				
37				
N				

CSI ONE (104:39:50)  
CSM (-34.8, 0.0, 0.0)  
(0, 180/90, 0)

PC (106:04:07)  
CSM (0, 0, 0)  
(0, 230/231, 0)

CSM CSI TWO COPY

11	:	:
37	:	:
75	.	:
81	.	.
82	.	.

CSM CDH COPY

13	:	:
75	.	:
81	.	.

CSM CSI ONE COPY

11	:	:
37	:	:
75	.	:
81	.	.
82	.	.

LM CSI TWO P76

84	.	.	.
33	:	:	:

CSM PC COPY

33	:	:
81	.	.

LM CDH P76

84	.	.	.
33	:	:	:

CSM TPI COPY

37	:	:
58	.	.
81	.	.
59	.	.

LM CSI ONE P76

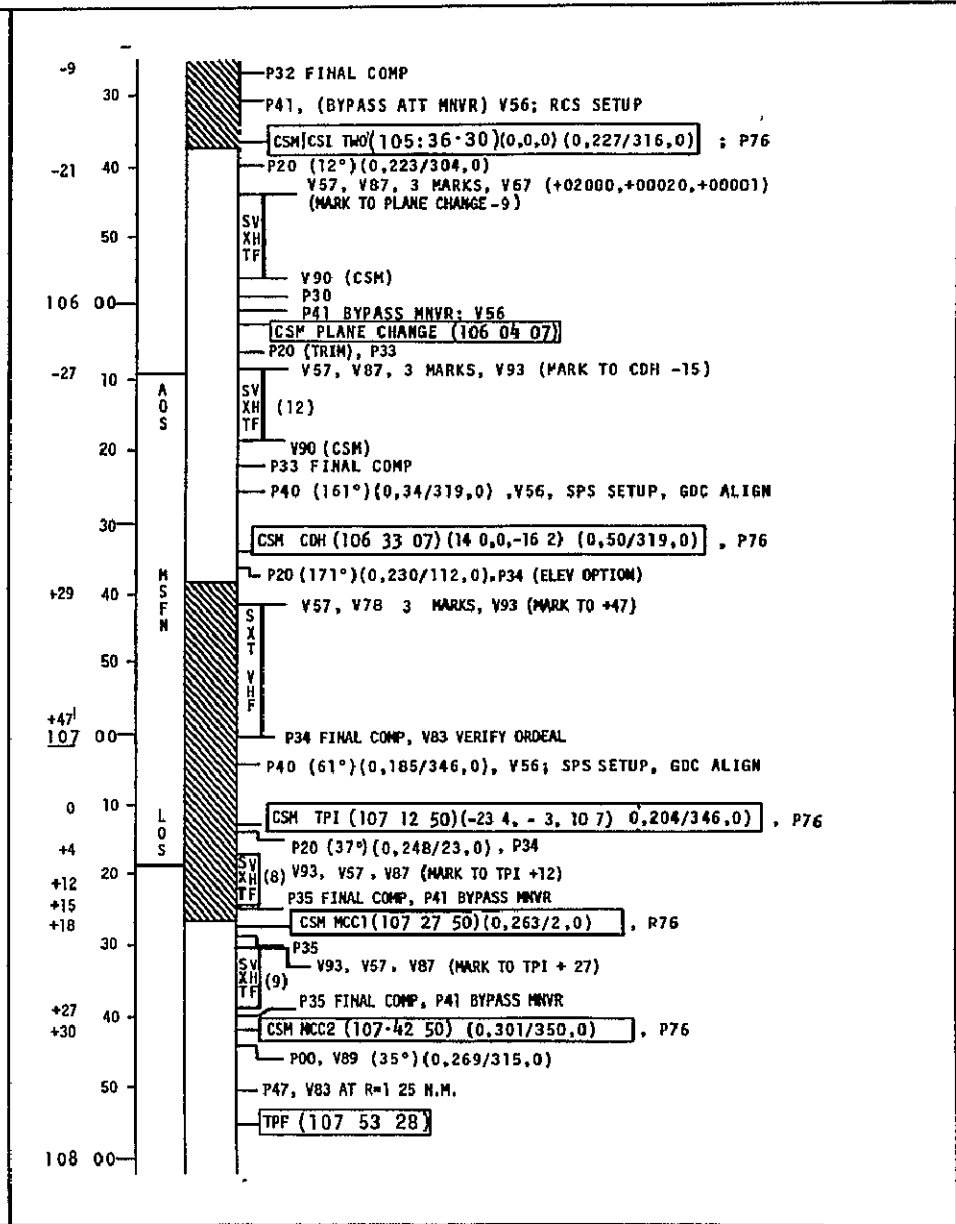
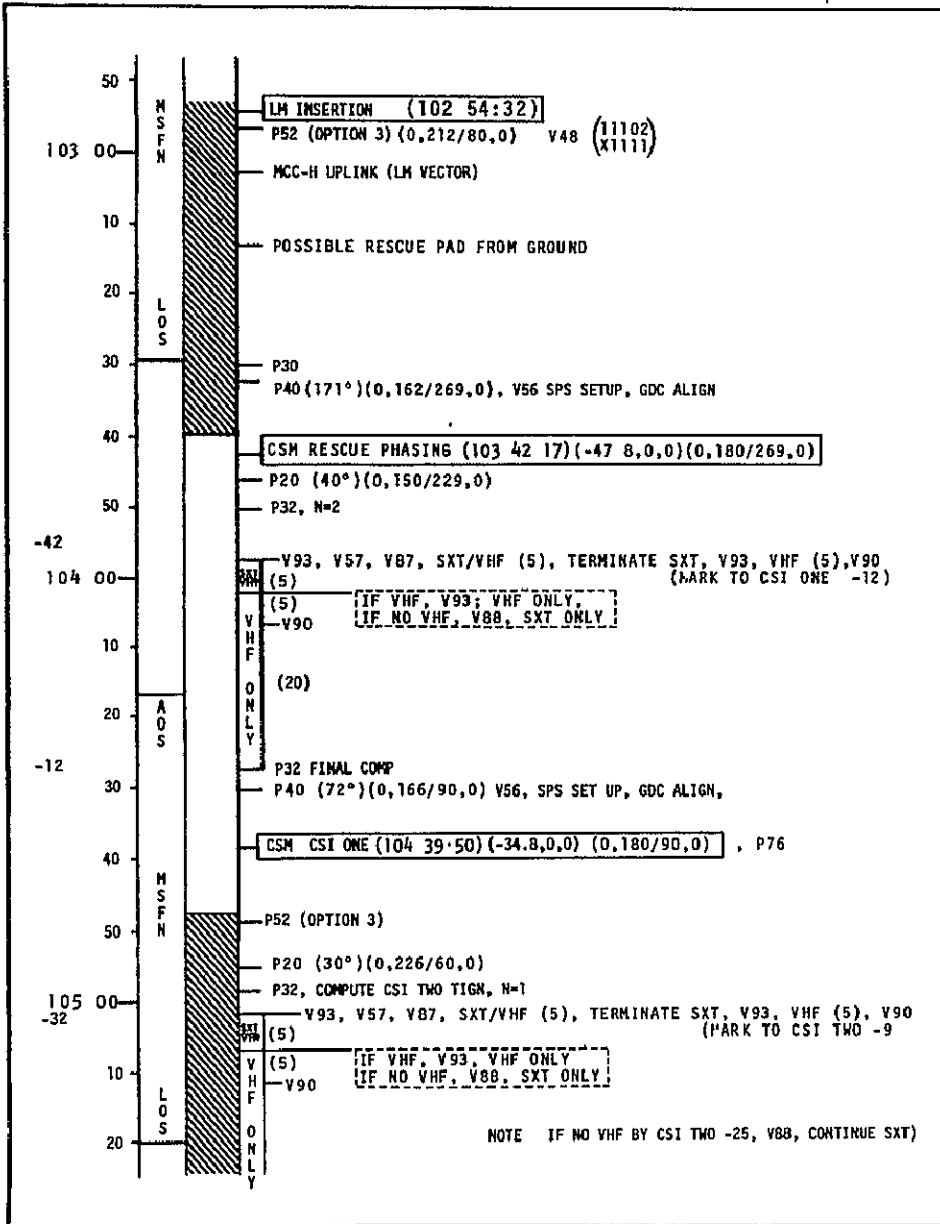
84	.	.	.
33	:	:	:

LM PC P76

84	.	.	.
33	:	:	:

LM TPI P76

84	.	.	.
33	:	:	:



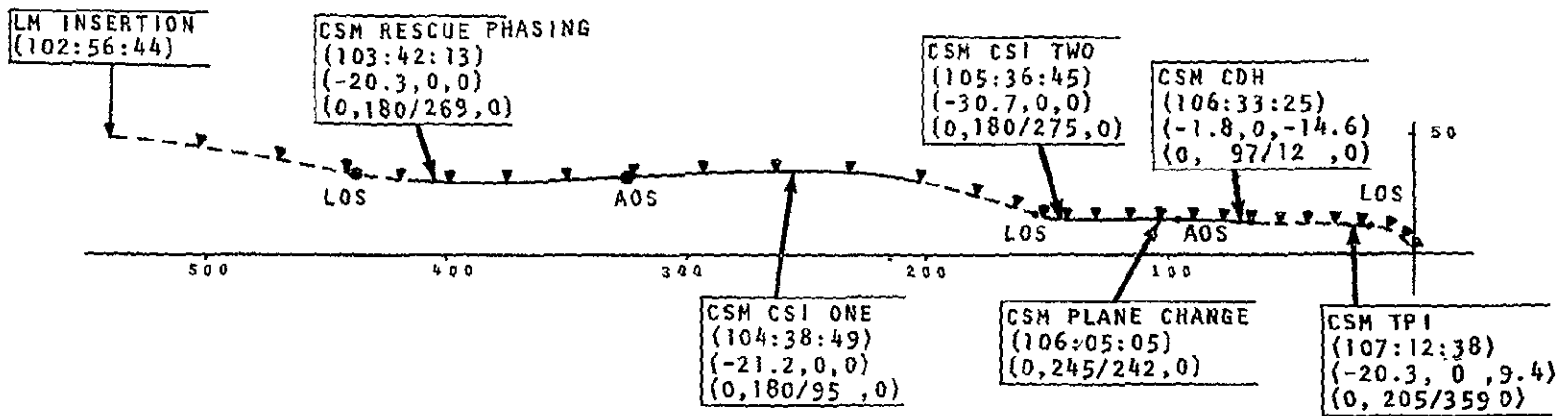


7.12 PDI<sub>1</sub> + 14:12 (12.5-15 Minutes) (CSM Active)

7.12.1 Summary

This rescue also results from an abort during the powered descent. This rescue is similar to the PDI<sub>1</sub> + 12 Rescue except that for those cases from PDI<sub>1</sub> + 12.5 to PDI<sub>1</sub> + 15 minutes, the CSM rescue phasing burn is a mirror image of the desired LM phasing burn. Also the CSI<sub>1</sub> burn is targeted for a CDH one-half rev later. However, this CDH burn is not applied but replaced by a CSI<sub>2</sub> which make the two orbits co-elliptic. For this rescue situation, rendezvous is completed approximately six hours after DOI.

The relative profile and the burns shown in the following pages represent the particular situation where the abort occurs at PDI<sub>1</sub> + 14:12. This data for other cases where the abort is initiated between 12.5 and 15 minutes after PDI will vary; however, the same basic checklist is applicable.



RESCUE PHASING PAD

47			
48			
33	:	:	:
81			
22			
ΔV <sub>C</sub>			
11	:	:	:
37	:	:	:
N			

CSM CSI TWO COPY

11	:	:	:
37	:	:	:
75	.	:	:
81	.	.	.
82	.	.	.

CSM CDH COPY

13	:	:	:
75	.	:	.
81	.	.	.

CSM CSI ONE COPY

11	.	:	:
37	:	:	:
75	.	:	:
81	.	.	.
82	.	.	.

LM CSI TWO P76

84	.	.	.
33	:	:	:

LM CDH P76

84	.	.	.
33	:	:	:

LM CSI ONE P76

84	.	.	.
33	:	:	:

CSM PC COPY

33	:	:	:
81	.	.	.

CSM TPI COPY

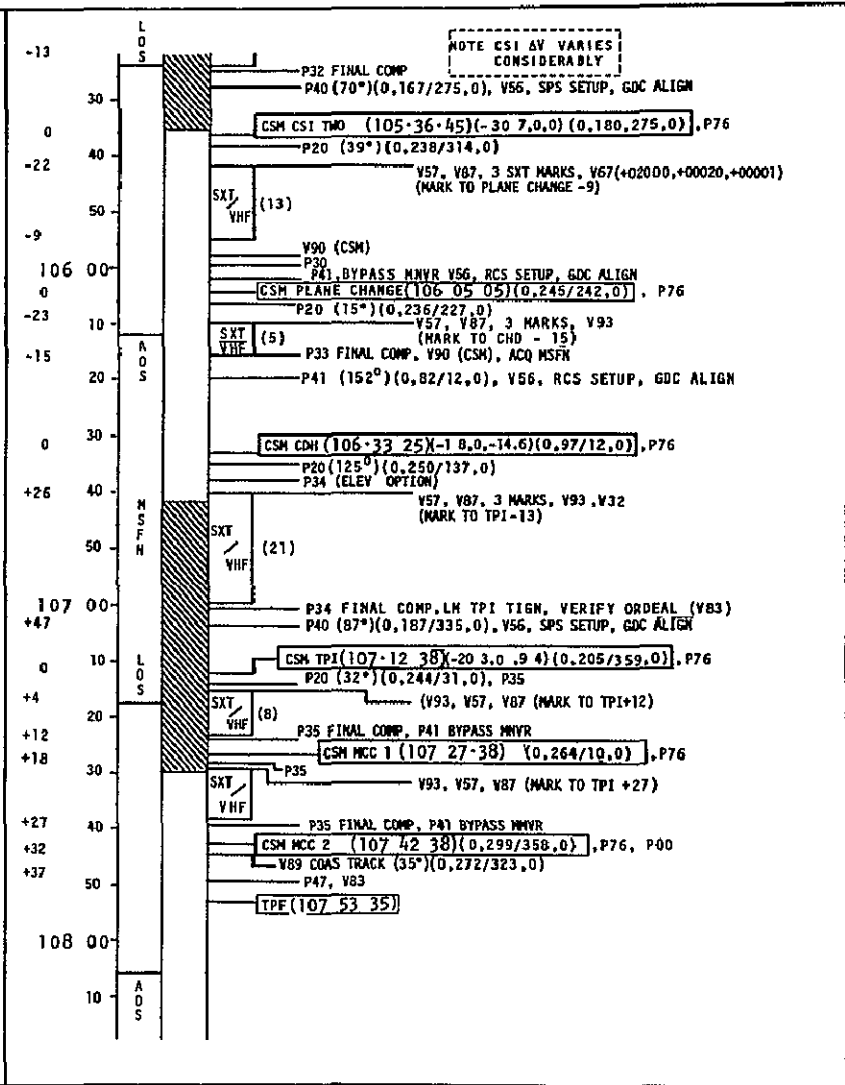
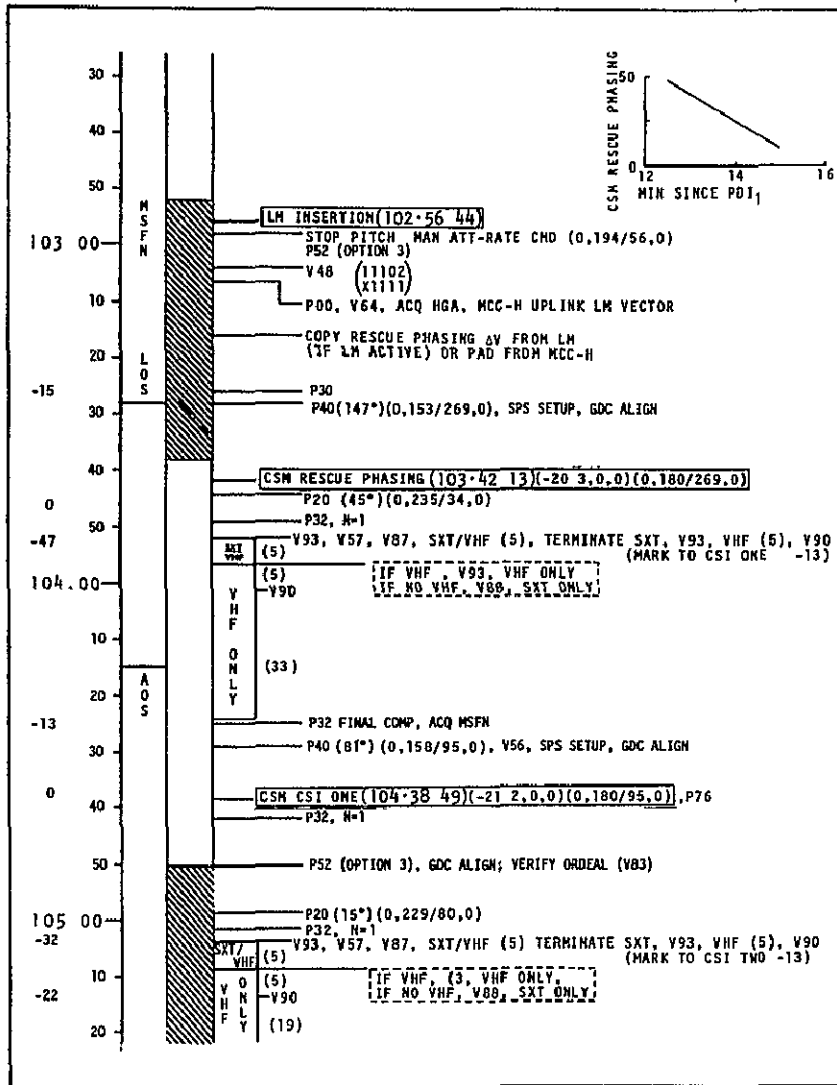
37	:	:	:
58	.	.	.
81	.	.	.
59	.	.	.

LM PC P76

84	.	.	.
33	:	:	:

LM TPI P76

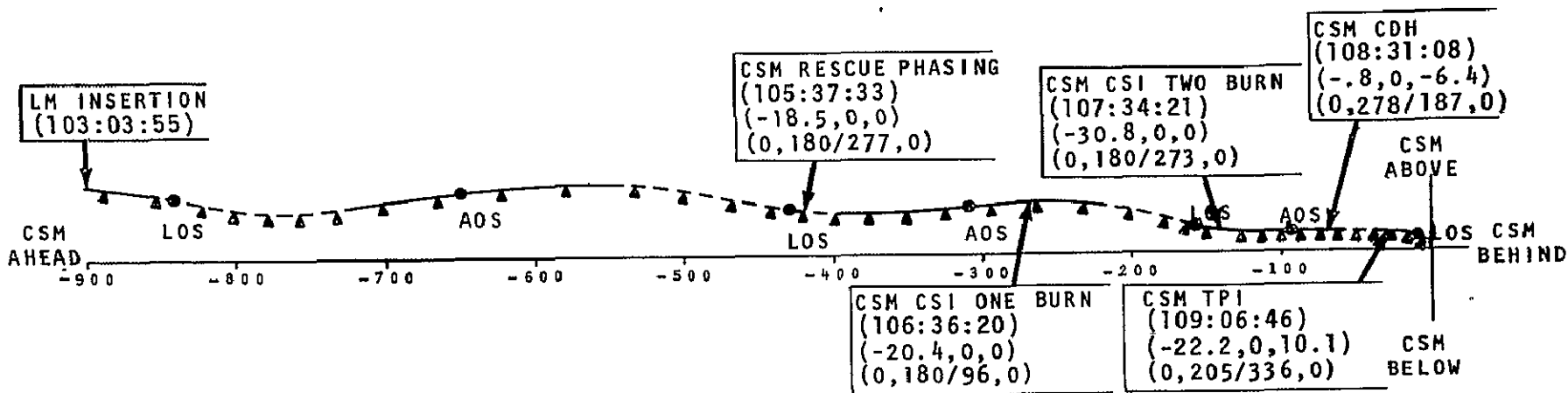
84	.	.	.
33	:	:	:



7.13 PDI<sub>1</sub> + 21:24 Preferred lift-off (T<sub>2</sub>) (CSM Active)

7.13.1 Summary

This rescue results from an abort 21 minutes and 24 seconds after initiation of the powered descent. This coincides with the first preferred lift-off time (T<sub>2</sub>) after PDI. The initial rescue phasing burn will be performed at a fixed GET which is approximately 153 minutes after LM insertion cut off (when the CSM reaches the longitude where the LM would have done phasing). This delay is due to the fact that the CSM cannot back-up the phasing burn at the LM phasing time because of the lack of spacecraft communications at that time. CSI<sub>1</sub> occurs one-half rev after the rescue phasing burn with CSI<sub>2</sub> occurring half-way between CSI<sub>1</sub> and CDH. For this rescue situation, rendezvous is completed approximately eight hours after DOI.



RESCUE PHASING PAD

47			
48			
33	:	:	
81			
22			
ΔV C			
11	:	:	
37	:	:	
N			

CSM CSI TWO COPY

11	:	:	
81	.	.	.

LM CSI TWO P76

84	.	.	.
33	:	:	

CSM CSI THREE COPY

11	:	:	
81	.	.	.

LM CSI THREE P76

84	.	.	.
33	:	:	

CSM PC COPY

33	:	:	
81	.	.	.

CSM CSI ONE COPY

11	:	:	
37	:	:	
75	:	:	
81	.	.	.
82	.	.	.

LM CSI ONE P76

84	.	.	.
33	:	:	

LM PC P76

84	.	.	.
33	:	:	

CSM CDH COPY

13	:	:	
75	:	:	
81	.	.	.

LM CDH P76

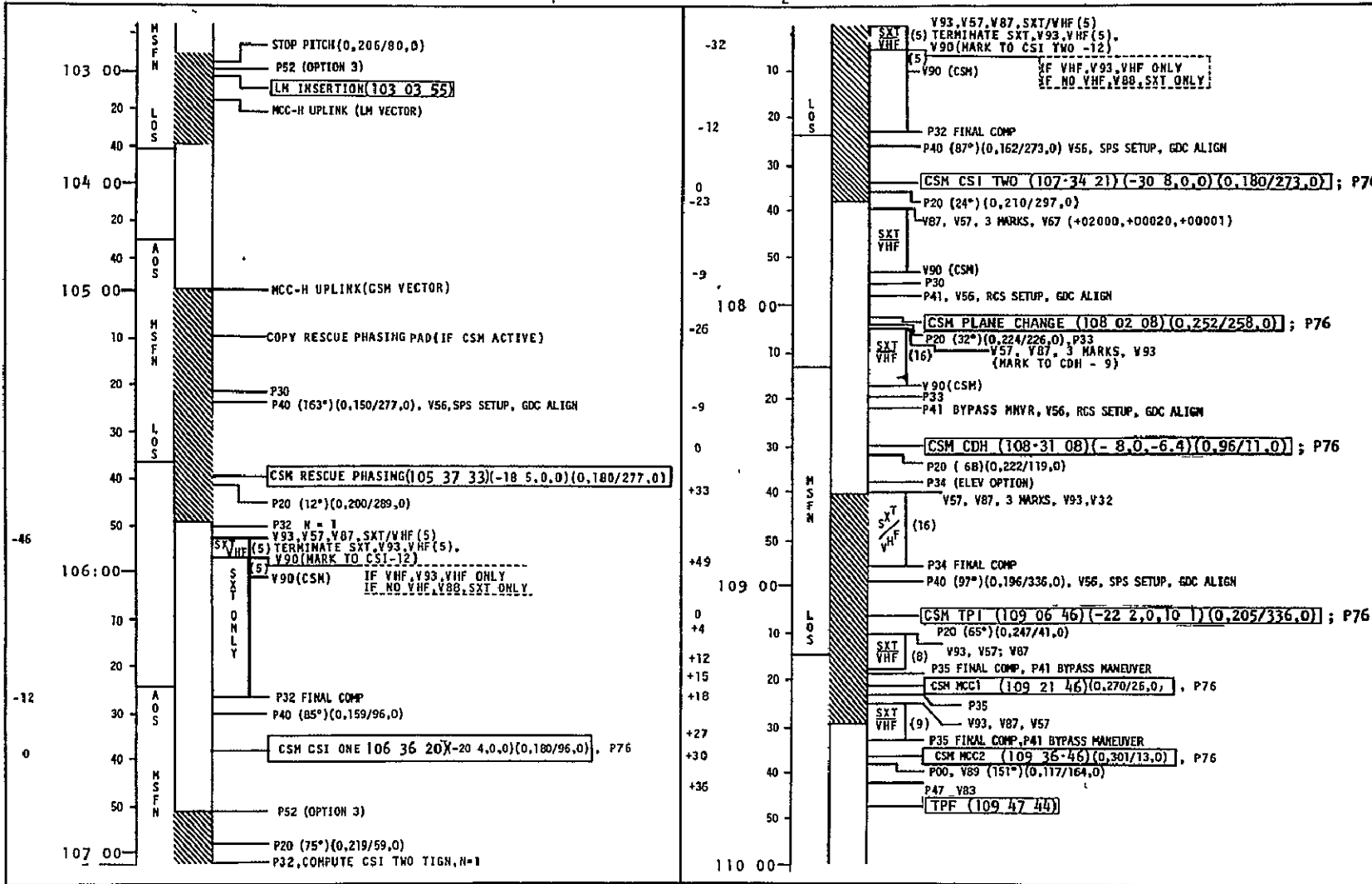
84	.	.	.
33	:	:	

CSM TPI COPY

37	:	:	
58	.	.	.
81	.	.	.
59	.	.	.

LM TPI P76

84	.	.	.
33	:	:	

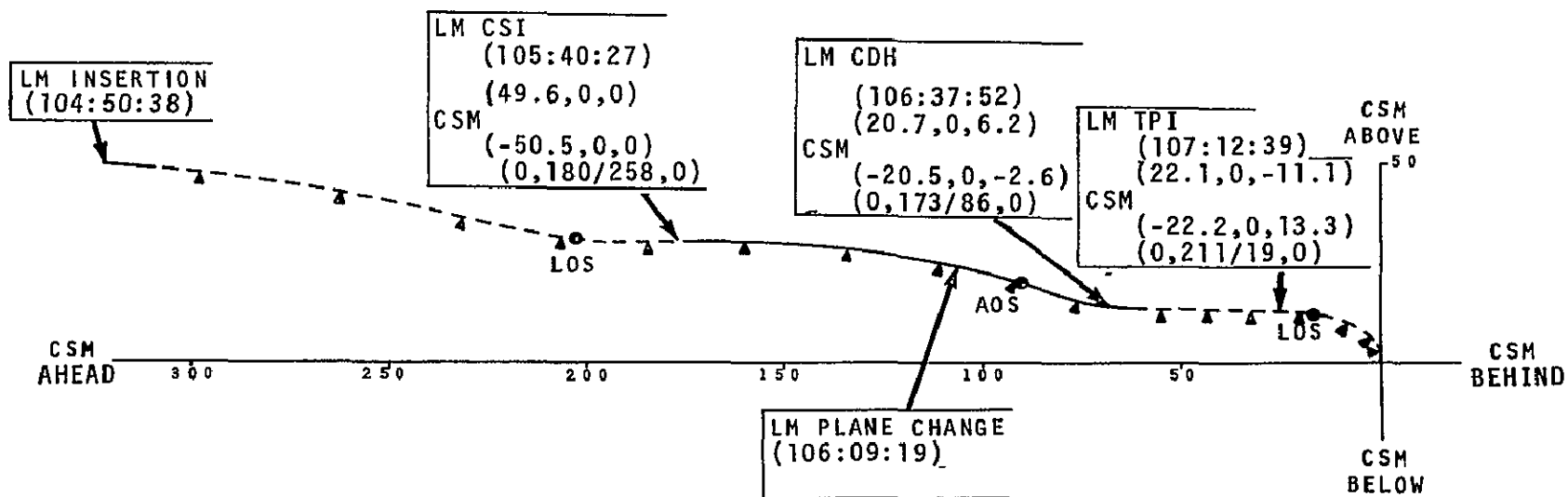


7.14 PDI<sub>2</sub> < 14.5 Variable Insertion (LM Active)

7.14.1 Summary

This rescue results from an abort during the powered descent where the descent was initiated at the second opportunity. It is assumed that following the decision to abort, the LM will be able to insert into orbit and that the CSM will then complete the rendezvous. This case is similar to the PDI<sub>1</sub> case described in Section 7.10. The LM is assumed to achieve a variable insertion orbit followed by a CSI burn (LM active) 50 minutes after insertion. The CDH burn is scheduled one-half rev after CSI<sub>1</sub>.

The relative profile and the burns shown in the following pages represent the particular situation where the abort occurs at PDI<sub>2</sub> + 14:24. This data for other cases where the abort is initiated less than 14 1/2 minutes into the descent will vary particularly for the CDH burn. However, the same basic checklist is applicable.



11	:	:
37	:	:
75	.	:
81	.	.
82	.	.

84	.	.
33	:	:

33	:	:
81	.	.

84	.	.
33	:	:

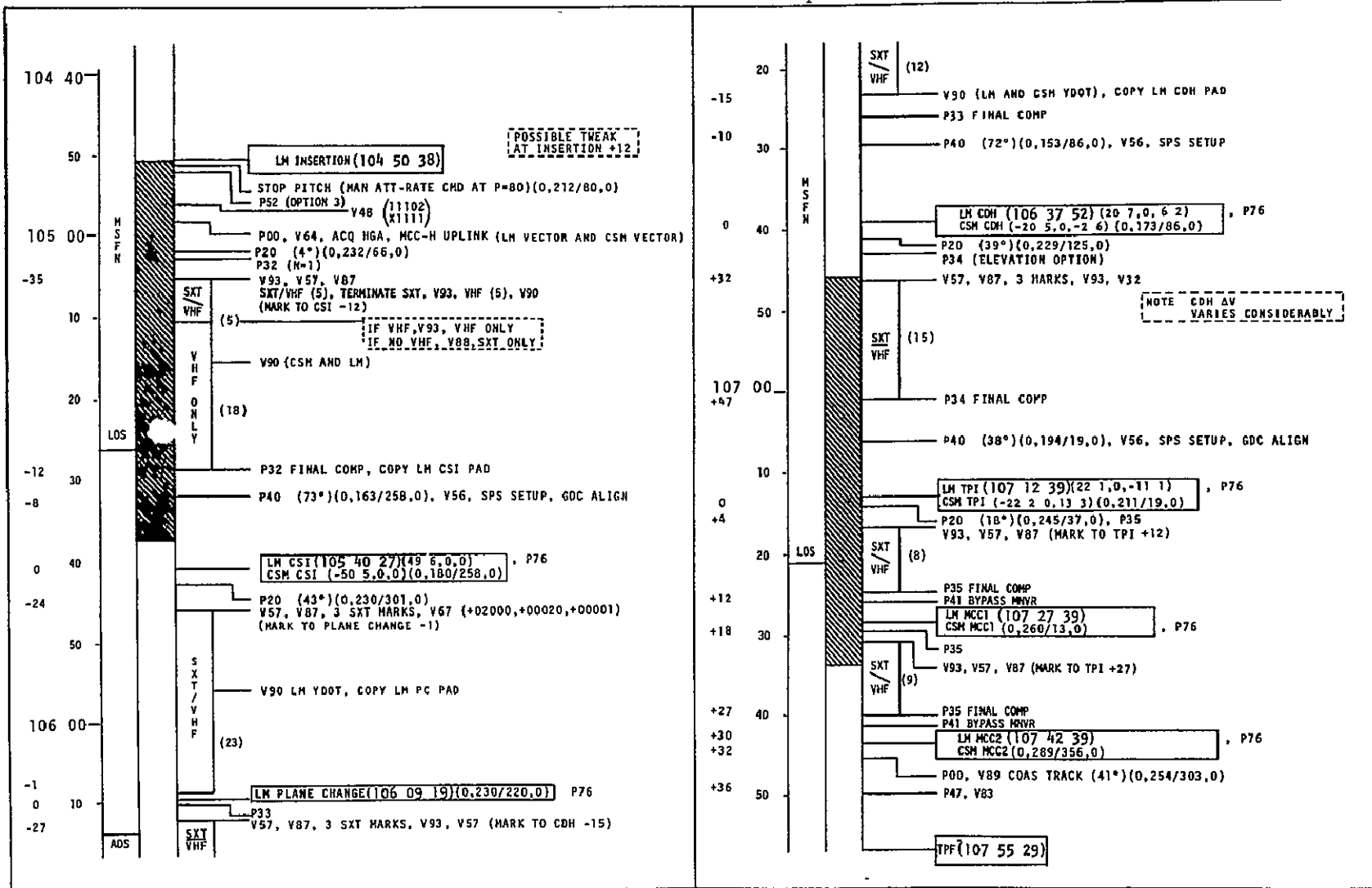
13	:	:
75	.	.
81	.	.

84	:	:
33	:	:

37	:	:
58	.	.
81	.	.
59	.	.

84	.	.
33	:	:

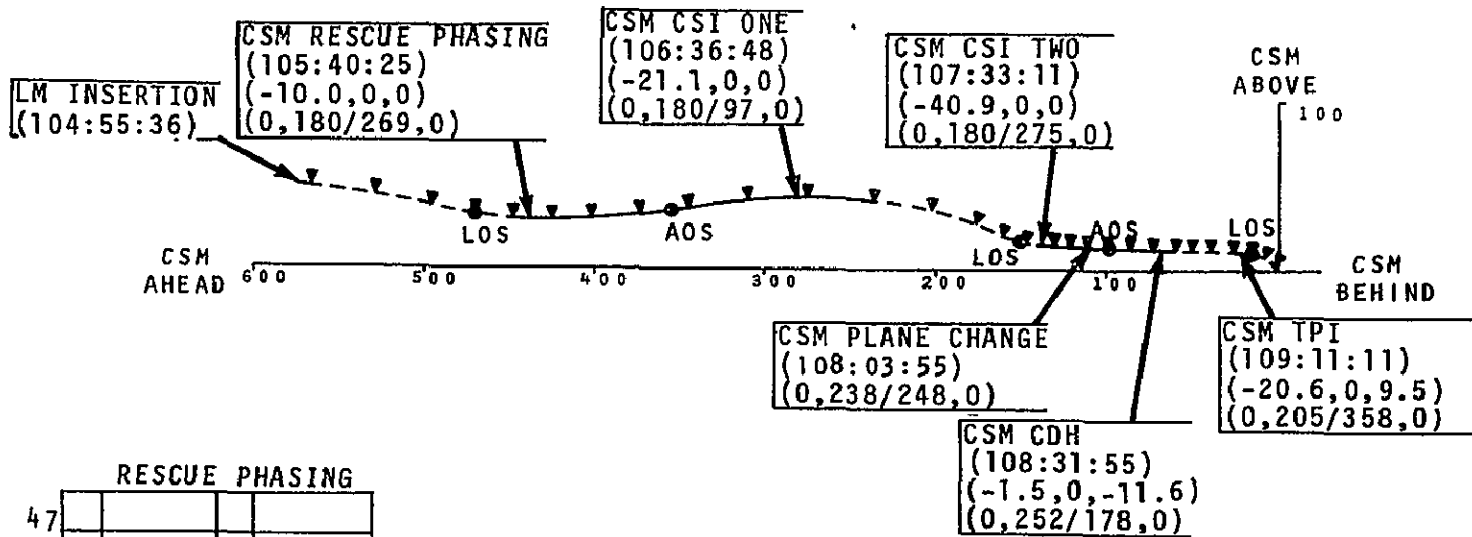




7.15 PDI<sub>2</sub> + 19:22 Preferred Lift-off (T<sub>2</sub>) (CSM Active)

7.15.1 Summary

This rescue results from an abort approximately 19 minutes and 22 seconds into powered descent where the descent was initiated at the second opportunity. This coincides with the first preferred lift-off (T<sub>2</sub>) after PDI<sub>2</sub>. The LM is assumed to have reached a fixed 10 X 30 orbit. The rescue phasing burn occurs at a fixed GET defined as 50 minutes from that insertion cut-off time associated with an abort at PDI<sub>2</sub> + 14.5 minutes. CSI<sub>1</sub> occurs one-half rev after the rescue phasing burn, with CSI<sub>2</sub> occurring one-half rev later. CDH occurs one-half rev after CSI<sub>2</sub>.



**RESCUE PHASING**

47			
48			
33	:	:	:
81			
22			
ΔV <sub>C</sub>			
11	:	:	:
37	:	:	:
N			

**CSM CSI ONE COPY**

11	:	:	:
37	:	:	:
75	.	:	:
81	.	.	.
82	.	.	.

**LM CSI ONE P76**

84	.	.	.
33	:	:	:

**CSM CSI TWO COPY**

11	:	:	:
37	:	:	:
75	.	:	:
81	.	.	.
82	.	.	.

**LM CSI TWO P76**

84	.	.	.
33	:	:	:

**CSM PC COPY**

33	:	:	:
81	.	.	.

**LM PC P76**

84	.	.	.
33	:	:	:

**CSM CDH COPY**

13	:	:	:
75	.	:	:
81	.	.	.

**LM CDH P76**

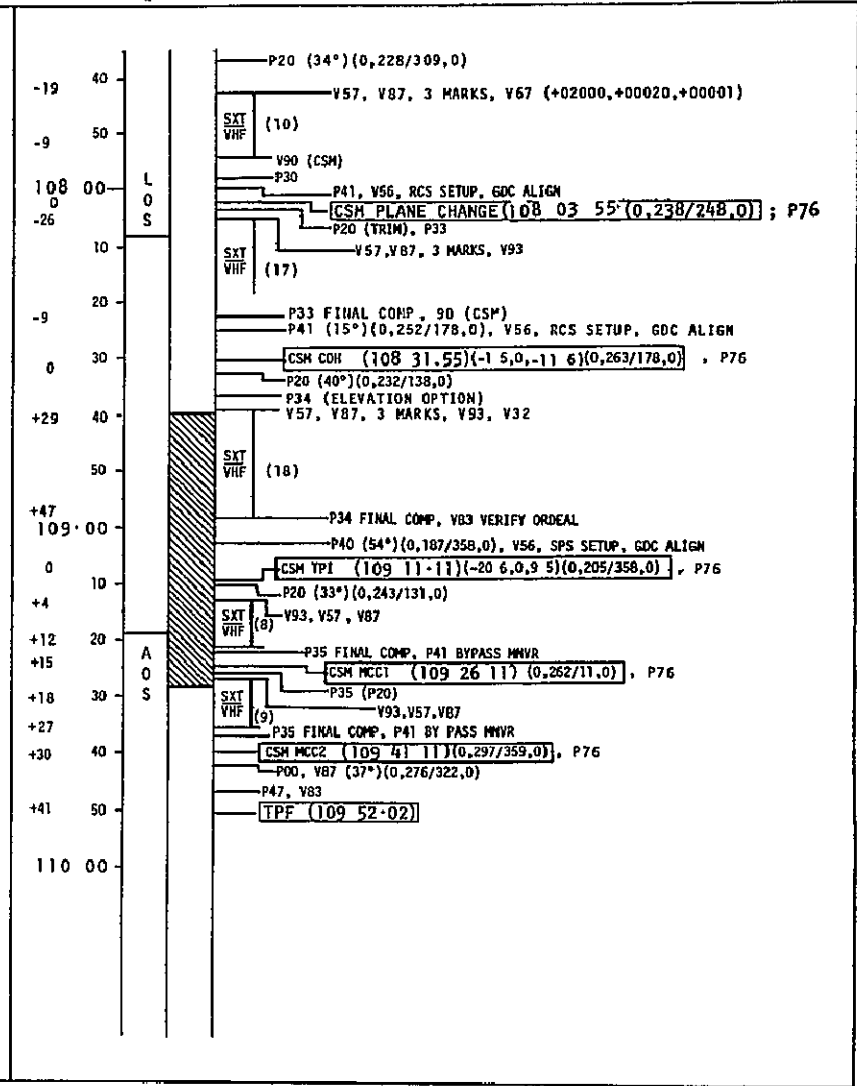
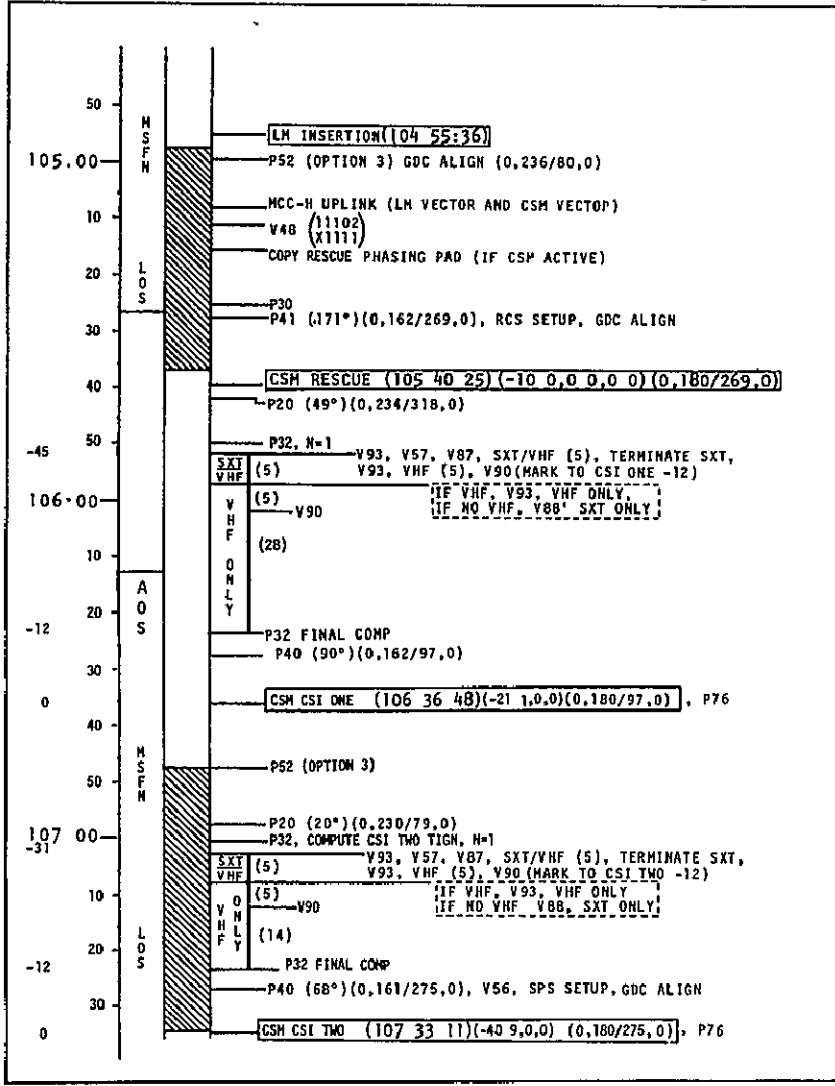
84	.	.	.
33	:	:	:

**CSM TPI COPY**

37	:	:	:
58	.	.	.
81	.	.	.
59	.	.	.

**LM TPI P76**

84	.	.	.
33	:	:	:



8.0 REFERENCES

- 8.1 Mission Requirements SA-506/CSM-107/LM-5, "G" Type Mission, Lunar Landing; dated 5 March 1969.
- 8.2 Spacecraft Operational Trajectory, Volume 1; Operational Mission Profile Launched 16 July 1969; MSC Internal Note No. 69-FM-98; dated 16 May 1969.
- 8.3 Shreffler, J. H.; Onboard Tracking Schedules for Mission F and G; Memo No. 69-FM46-29, dated 7 February 1969.
- 8.4 Shreffler, J. H.; On the Efficacious Utilization of VHF Range Data when Sextant Marking is Interrupted; Memo No. 68-FM46-482; dated 19 December 1968.
- 8.5 Pixley, P. T.; F Rendezvous Navigation Mission Techniques Panel Meeting; MSC Memorandum 69-FM46-107; dated 10 April 1969.
- 8.6 Guidance System Operations Plan for Manned CM Earth Orbital and Lunar Missions Using Program COLOSSUS 2 (COMANCHE REV. 44,45) Section 4 Operational Modes, Revision 7; dated March 1969.
- 8.7 Guidance Navigation and Control Command Module Functional Description and Operations Using Flight Program COLOSSUS 2A (COMANCHE 55) Volume II, Normal Procedures; dated June 1969.

- 8.8 Apollo Operations Handbook Command and Service Modules - Volume II, Operational Procedures; dated 17 April 1969.
- 8.9 Diekelman, D.P.; MDAC Apollo Design Note No. 114, "Evaluation of the Current Navigation Schedule for Mission G Lunar Rendezvous;" dated 4 June 1969.
- 8.10 Worley, N.; MDAC Apollo Design Note No. 111, "Mission G Nominal Reference Trajectory;" dated 7 May 1969.
- 8.11 Preliminary Apollo 11 Flight Plan; AS-506/CSM-107/LM-5; dated 15 April 1969.
- 8.12 Puschinsky, R. W.; McRae, M.; Otto, R.; CSM Rendezvous Procedures D Mission, Final Revision A; dated 1 February 1969.
- 8.13 Tindall, H. W.; Apollo Mission Techniques Mission F and G Lunar Orbit Activities - Volume I, Techniques Descriptions, MSC Internal Note No. S-PA-9T-044, dated 28 February 1969.
- 8.14 Lunar Contingency Rendezvous Group; "Preliminary Operational LM Abort and Rescue Plan for Apollo 11 (Lunar Landing Mission);" dated 6 June 1969.

- 8.15 Arceneaux, W.K.; MDAC Apollo Design Note No. 117, "Evaluation of the Nominal Mission G Lunar Rendezvous Navigation Mark Types and the A Priori Measurement Range Variance (VARMIN);" dated 12 June 1969.
- 8.16 Fudurich, R.; MDAC Apollo Design Note No. 107, "Effects of a LM Tracker Light Failure Upon a CSM Active Rendezvous During Mission F;" dated 21 April 1969.
- 8.17 Carrico, L. D.; Paddock, S. G.; MDAC Apollo Design Note No. 113, "The Effects of VHF Only Navigation on the Terminal Rendezvous Phase of Mission F;" dated 16 May 1969.
- 8.18 Revision 1 to Spacecraft Operational Trajectory for Mission G, Volume 1; Operational Mission Profile Launched 16 July 1969.
- 8.19 Diekelman, D., MDAC Apollo Design Note No. 114, "Evaluation of the Nominal Mission G Lunar Rendezvous Navigation W-Matrix Diagonal Elements and Initialization Schedule."
- 8.20 Mangiaracina, C., Diekelman, D., MDAC Apollo Design Note No. 118, "Evaluation of the Current Mission G CSM Nominal Lunar Rendezvous Navigation W-Matrix Diagonal Elements and Initialization Schedule."