

NASA CASE NO. FRC-10053PRINT FIG. 1NOTICE

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AWARDS ABSTRACT

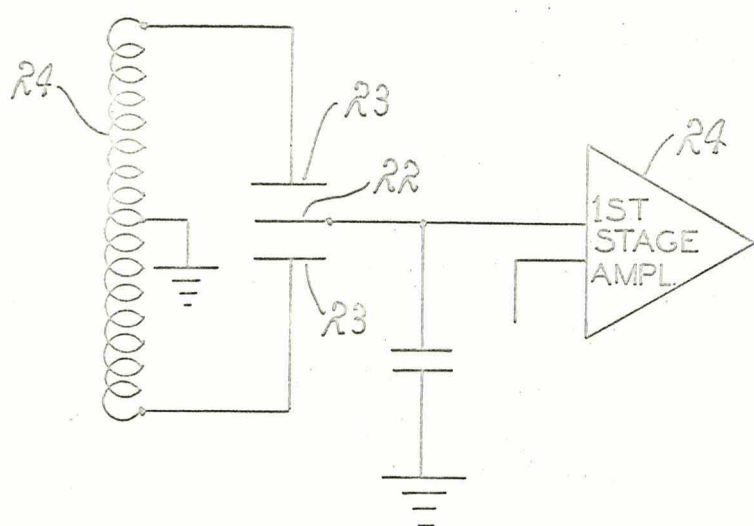
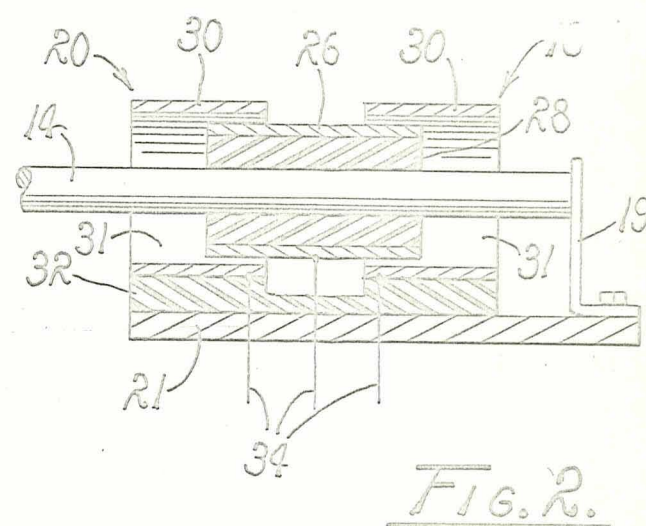
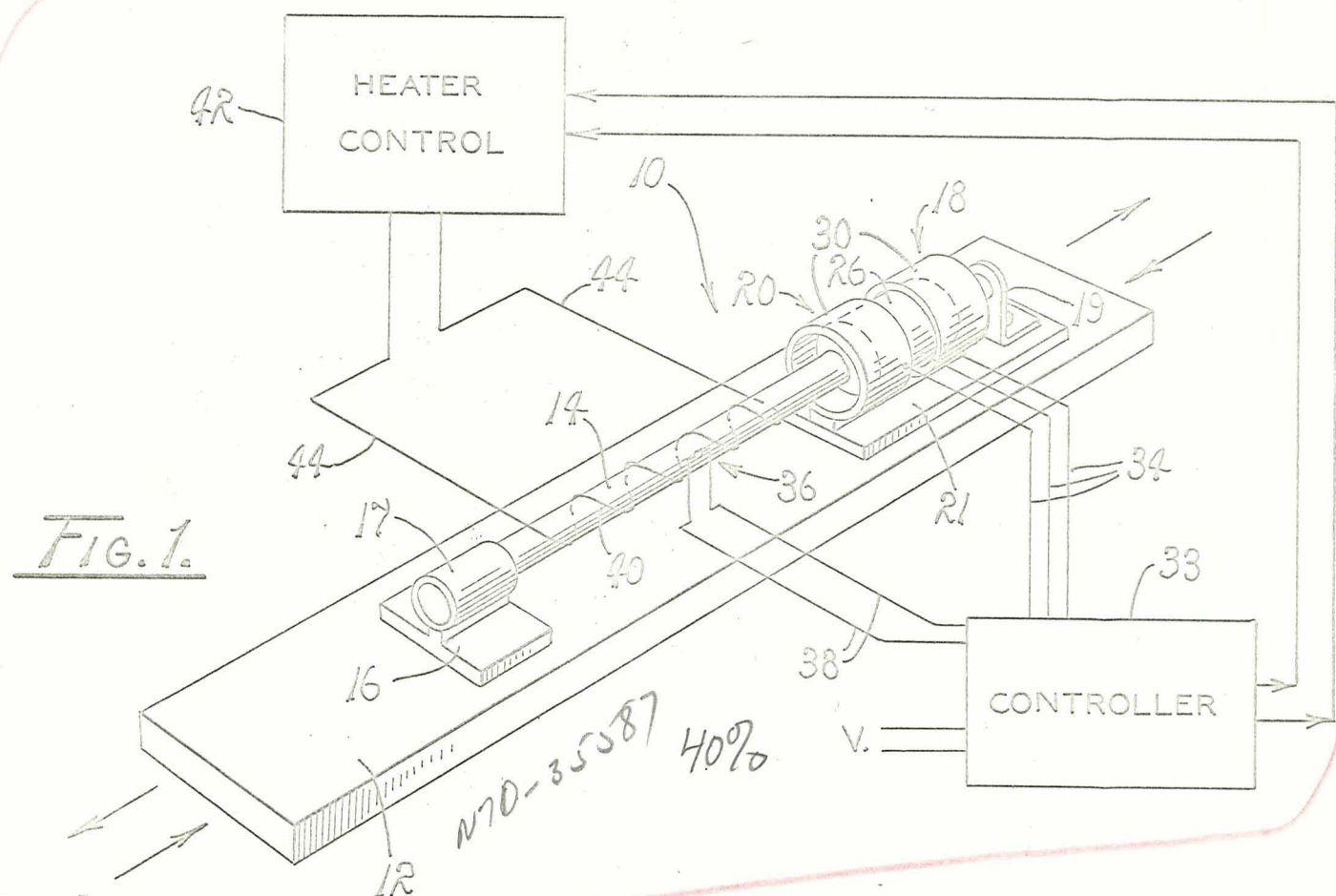
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STRAIN GAGE

This invention is directed to an improved strain gage particularly suited for use in detecting and measuring mechanical strain induced in thermally strained specimens.

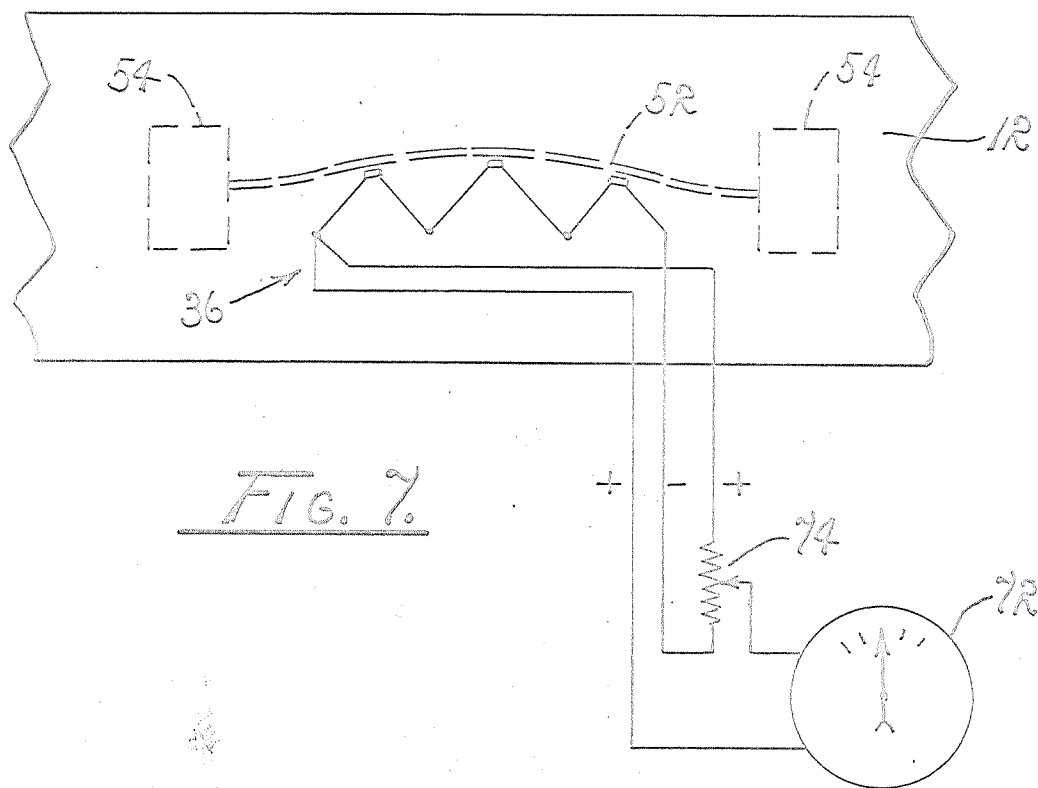
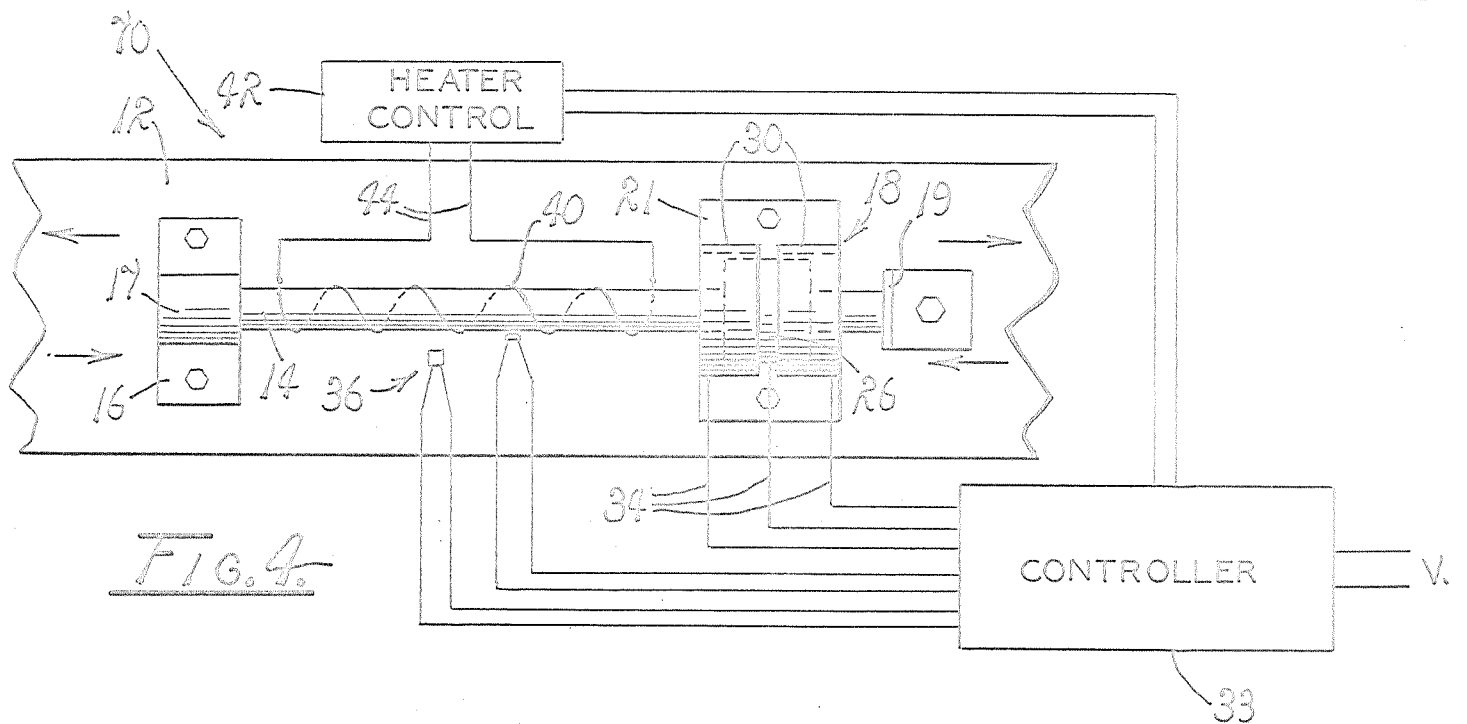
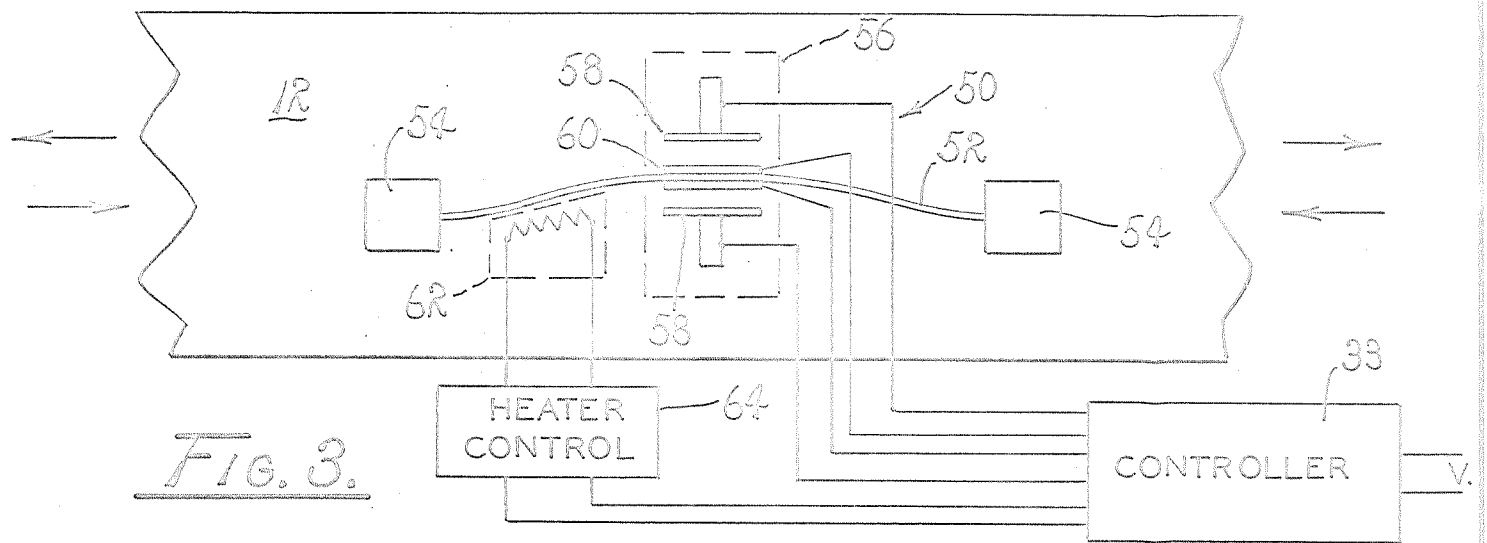
The present invention utilizes a compensating link rigidly fixed to the surface of a test specimen in a manner such that relative displacement operatively is achieved as the specimen is mechanically strained. The link is adapted to be thermally strained but is isolated from mechanical strain. Preferably the link is fabricated from a material similar to that of the specimen so that the specimen and the compensating link possess similar thermal expansion characteristics. Since ambient heat imparts thermal strain to the compensating link as it imparts thermal strain to the specimen, and therefore any relative motion which is achieved between the specimen and the compensating link results from strain inducing stress mechanically applied to the specimen. Through a determination of the amplitude of the achieved relative motion, the induced mechanical strain is detected and measured.

By employing a compensating link having known thermal expansion characteristics, it is possible to detect and measure mechanical strain induced in a thermally strained specimen in a manner such that effects of thermal strain imparted to the specimen are negated.



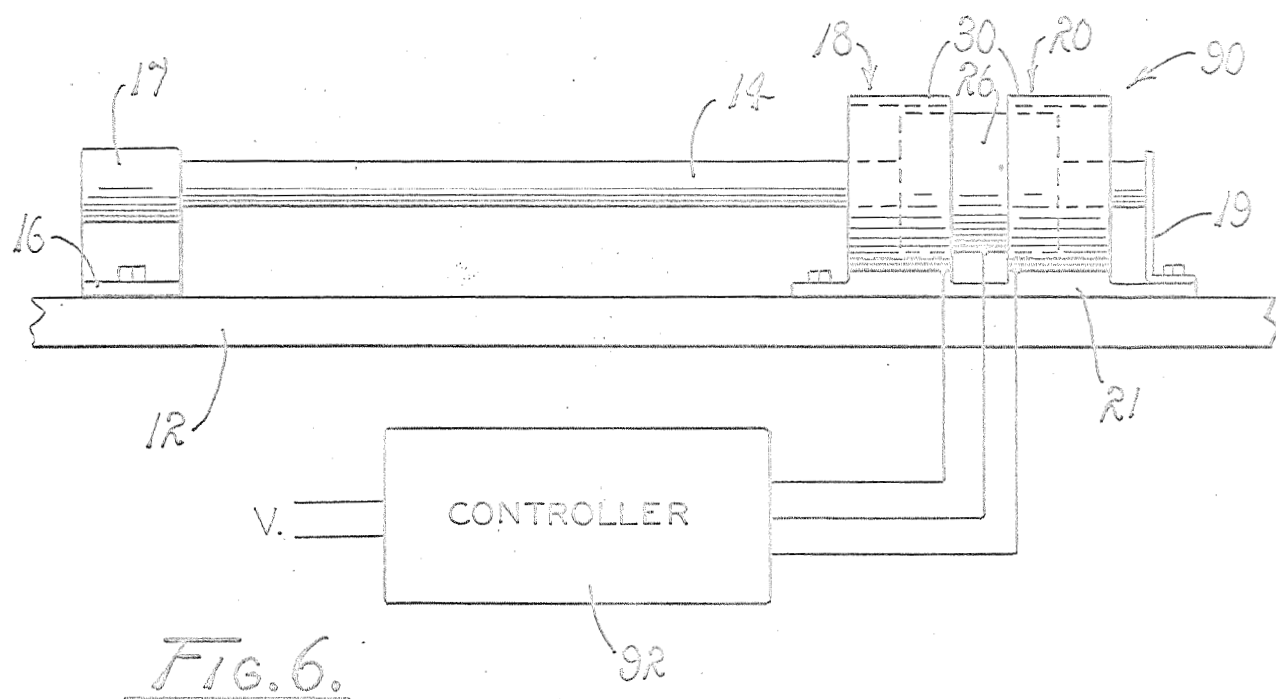
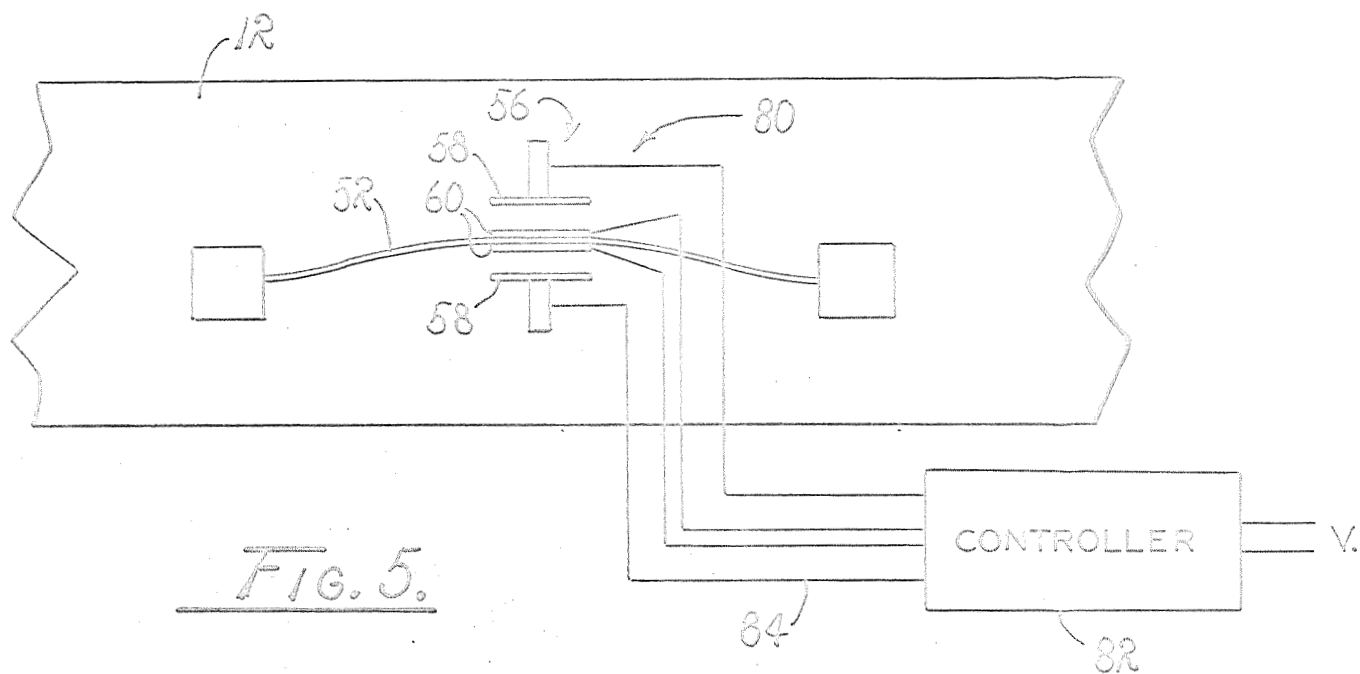
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BACKGROUND OF THE INVENTION

1. Field of the Invention:

The invention relates to strain gages and more particularly to strain gages adapted to be employed in an environment wherein elevated temperatures operatively are encountered.

2. Description of the Prior Art:

The prior art is replete with strain gages for measuring strain resulting from mechanical stress. Attempts have been made to employ various types of known strain gages in measuring mechanical strain imparted to specimens while the specimens are maintained at elevated temperatures, and accordingly are subjected to thermal stress. However, such attempts have not always met with success as various impediments normally are encountered. For example, where optical techniques are employed in measuring mechanically imparted strain, in samples subjected to thermal stress, an attendant inability to effectively cancel thermal strain persists. Where the techniques being employed require the use of devices based on a change in capacitance, an attendant change in dielectric constant and an inability to adequately cancel the effects of the source of thermal energy have impeded the use of such devices. Where devices, such as the device disclosed in United States Letters Patent No. 3,293,909, are employed, such devices fail to totally satisfy existing needs since these devices do not readily accommodate real-time observation of performance.

1 OBJECTS AND SUMMARY OF THE INVENTION

2 This invention overcomes many of the aforementioned
3 difficulties through the use of a simplified gage which employs a
4 differential capacitor, and a displaceable link coupled with the
5 specimen as the specimen is subjected to both mechanical and
6 thermal stresses.

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9 Accordingly, it is an object of the instant invention
10 to provide an improved strain gage which utilizes thermal strain
11 induced in a compensating link for acquiring intelligence
12 indicative of induced mechanical strain.

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15 It is another object of the instant invention to
16 provide an improved strain gage particularly suited for use in
17 detecting mechanical strain induced in thermally stressed
18 specimens.

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21 It is another object of the instant invention to
22 provide a strain gage capable of being employed in an environment
23 wherein elevated temperatures ranging between room temperature
24 and 1500° F. are encountered.

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27 It is another object of the instant invention to
28 provide an improved strain gage which is adapted for use in an
29 environment wherein a specimen simultaneously is subjected to
30 both thermal and mechanical loading for inducing both mechanical
31 and thermal strain.

1 These and other objects and advantages of the instant
2 invention are achieved by providing a strain gage for use in
3 detecting and measuring mechanically induced strain in given
4 specimens simultaneously subjected to mechanical and thermal
5 stresses, including a compensating link mounted on a specimen and
6 formed of a material having thermal expansion characteristics
7 consistent therewith, and a differential capacitor for detecting
8 mechanical strain as the effects of thermal strain are compensated
9 for through the use of the compensating link.

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15 BRIEF DESCRIPTION OF THE DRAWINGS

16 Fig. 1 is a perspective, diagrammatic view of a first
17 embodiment of the instant invention which employs a differential
18 capacitor.

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21 Fig. 2 is a partially sectioned side elevation of the
22 differential capacitor employed by the embodiment of the
23 invention illustrated in Fig. 1.

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26 Fig. 3 is a top plan view of a second embodiment of
27 the instant invention.

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30 Fig. 4 is a top plan view of a third embodiment of the
31 instant invention.
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1 Fig. 5 is a diagrammatic view of a fourth embodiment
2 of the instant invention.

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5 Fig. 6 is a side elevation of a fifth embodiment of the
6 instant invention.

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9 Fig. 7 illustrates a coupling of a thermopile with an
10 associated meter, as employed in detecting temperature
11 differentials.

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14 Fig. 8 is a diagrammatic view of a differential
15 capacitor which typifies the capacitors employed in the embodi-
16 ments illustrated in Figs. 1 and 3 through 6.

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21 DESCRIPTION OF THE PREFERRED EMBODIMENTS

22 First Embodiment

23 Referring now to the drawings wherein like reference
24 characters designate like or corresponding parts throughout the
25 several views, there is shown in Fig. 1 a strain gage 10, which
26 is a first embodiment of the instant invention, attached to a
27 surface of a specimen 12. This gage is, in effect, a thermal-
28 null strain gage. Consequentially, the effects of thermally
29 induced expansion or contraction, commonly called thermal strain,
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1 are canceled and strain is not detected, so long as the specimen
2 12 is not mechanically stressed. Preferably, this condition
3 prevails for a wide range of temperatures, between, for example,
4 room temperature and 1500° F.
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9 As illustrated in Fig. 1, the strain gage 10 is mounted
10 on the specimen 12 and is employed in either compression or
11 tension and at elevated temperatures. For purposes of describing
12 the invention, it will be assumed that the specimen 12 is in an
13 environment wherein it is subjected to tensile stress at elevated
14 temperatures and, consequently, experiences elongation due to
15 thermal stress as well as mechanical stress which results from a
16 mechanical loading thereof.
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21 Mounted along one surface of the specimen 12 there is an
22 elongated bar or link 14, preferably of a tubular configuration,
23 formed of a material having thermal characteristics matched with
24 the thermal characteristics of material of the specimen 12.
25 Preferably, the material from which the bar 14 is fabricated is
26 that of the specimen 12. It may, however, differ so long as the
27 relationship of the characteristics of the materials, over the
28 operating range, is a known factor. The link 14 rigidly is
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1 secured at one end thereof to the surface of the specimen 12
2 through a suitable bracket 16. The bracket is fixed to the
3 surface of the specimen 12, through any convenient means,
4 including commercially available high temperature epoxy resins,
5 welds and the like. The bracket 16 includes a unitary sleeve 17
6 which, in effect, serves as a receptacle for receiving therein in
7 a telescoping relationship, one end of the link 14 which rigidly
8 is coupled with the sleeve 17 and therefore rigidly is secured to
9 the specimen 12.

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14 Adjacent the opposite end of the link 14 there is a
15 motion detector 18 also fixedly secured to the surface of the
16 specimen 12. The purpose of the detector 18 is to detect
17 relative displacement, occurring between the link 14 and the
18 surface of the specimen 12 as either is strained. The particular
19 type of detector employed determines the manner in which the end
20 of the link 14 is mounted adjacent to the detector.

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25 As illustrated, particularly in Figs. 1 and 2, the
26 means employed in mounting the end of the bar 14 adjacent to the
27 position detector 18 includes a vertically disposed flexible
28 leaf 19. This leaf is coupled to the end surface of the link 14
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1 and supports the end of the link adjacent to a differential
2 capacitor 20 which functions as a motion detector. The
3 differential capacitor 20 and the leaf 19 are mounted on the
4 surface of the specimen 12 by means of a suitable bracket 21
5 fixed to the surface of the specimen in a manner similar to that
6 in which the bracket 16 is fixed to the surface of the specimen
7 12. It is to be understood that the leaf 19 is, in operation,
8 flexed in order to accommodate axial displacement of the end of
9 the link 14 relative to the surface of the specimen 12.

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14 While the principles of a differential capacitor are
15 well known, it is to be understood that the differential
16 capacitor 20, as employed by the various embodiments of the
17 instant invention, includes a plurality of capacitor plates
18 between which the capacitance is varied as displacement of the
19 link 14, relative to the surface of the specimen 12, is
20 achieved. A typical differential capacitor is illustrated in
21 Fig. 8.

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26 The differential capacitor illustrated in Fig. 8
27 includes a movable capacitor plate 22, disposed between a pair
28 of fixed capacitor plates 23. The capacitor plates 23, in turn,
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1 are coupled to the opposite ends of a center-tapped secondary
2 winding 24 of a carrier transformer. The capacitor plates 23
3 are fixed in a mutually spaced relationship, while the capacitor
4 plate 22 is displaceable therebetween for varying the capacitance
5 established between the movable plate and the fixed plates.
6 Hence, as the distance between the moving capacitor plate 22
7 and the fixed capacitor plates 23 is varied, a varying output
8 signal is delivered from the capacitor to a first stage
9 amplifier 24, whereupon the resulting signal can be delivered to
10 a suitable filter and phase correction network, not shown, for
11 further processing and utilization in a manner consistent with
12 known capacitance detecting techniques. Since the signal
13 processing circuits utilized in processing output signals of
14 differential capacitors are well known, a detailed description
15 of the circuits here employed is omitted in the interest of
16 brevity.

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21 As a practical matter, the differential capacitor 20,
22 Fig. 2, is so formed as to include a metallic cylinder 26 mounted
23 on, and insulated from the link 14. Mounting of the cylinder 26
24 is achieved through the use of suitable ceramic oxides,
25 designated 28, so that the cylinder 26, in effect, serves as a
26 moving capacitor plate as the link 14 experiences axial strain.

1 Disposed in coaxial relationship with the cylinder 26,
2 and concentrically disposed about the link 14, is a pair of
3 spaced tubular blocks 30. These blocks, in effect, function as
4 the fixed capacitor plates and are provided with coaxially related
5 bores 31 having a diameter slightly larger than the outside
6 diameter of the cylinder 26. The blocks 30 are so positioned,
7 relative to the cylinder 26, that the cylinder simultaneously is
8 telescopingly displaced relative to each of the bores 31 as
9 relative displacement is achieved between the link 14 and the
10 specimen 12. This telescoping displacement serves simultaneously
11 to vary the effective area of the external surface of the metallic
12 cylinder 26 relative to the surface of the bores 31 of the
13 blocks 30 so that the capacitance established between the
14 external surface of the metallic cylinder 26 and the surface of
15 each of the bores 31 is varied as telescoping displacement is
16 imposed on the link 14. The tubular blocks 30 are supported in
17 any suitable manner, however, it is preferred that the bracket 21
18 also serves to support the blocks through a mount 32 formed of
19 ceramic oxides, similar to the ceramic oxides employed in mounting
20 the metallic cylinder 26 on the link 14.

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25 A capacitor circuit, including a first stage amplifier
26 24, is coupled with the cylinder 26 and blocks 30, which function
27 in a manner similar to capacitor plates 22 and 23, Fig. 8, and is
28 included within a controller circuit, generally designated 33,
29 Fig. 1. The controller 33 is coupled with the differential
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1 capacitor 20, through suitable leads 34. The controller 33 also
2 is connected with a thermopile, generally designated 36, through
3 leads 38, and a resistance heater coil 40, through a current
4 controller 42 and leads 44.

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9 Since the design and function of thermopiles are well
10 known, a detailed description is omitted in the interest of
11 brevity. However, it is to be understood that the thermopile 36,
12 as employed, includes a series of thermocouples having alternate
13 terminals connected to the link 14 and the surface of the specimen
14 12 and is employed in detecting a temperature differential as it
15 is established between the link 14 and the specimen 12 through an
16 energization of the heater coil 40.

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21 As illustrated, the heater coil 40 is wound about the
22 link 14, however, it could be concentrically disposed within the
23 link 40. Current through this coil is controlled through the
24 heater controller 42, which, as a practical matter, is coupled
25 with a suitable source of electrical energy, not shown. The
26 current controller circuit 42 is of any suitable design and, in
27 operation, is controlled by signals delivered from the controller
28 circuit 33 so that the flow of current through the coil 40 is,
29 in effect, dictated by the output of the controller 33. The
30 circuit which is employed in the heater current controller is of
31 any suitable design, and therefore a detailed description
32 thereof is omitted.

Operation Of The First Embodiment

The operation of the thermal-null strain gage 10 can readily be understood when it is appreciated that the resistance heater coil 40 is employed to impart to the link 14 thermal strain which is equal to the mechanical strain imposed on the specimen 12 and that the detector 18 serves to detect the relative position of the link 14 as it thermally is strained in response to a current flowing through the coil 40. Since the link 14 and the specimen 12 possess similar thermal expansion characteristics, ambient or environmental temperature tends to induce a similar strain in the link as in the specimen.

Hence, it is to be understood that the link 14 is mounted on the surface of a specimen 12 employing the brackets 16 and 21, and that the specimen 12 operatively is subjected to a mechanical load for thus imposing mechanical strain thereon. As strain occurs, relative displacement between the link 14 and the surface of the specimen 12 is experienced. This displacement, in turn, repositions the metallic cylinder 26 relative to the surfaces of the bores 31 of the tubular blocks 30, for thus varying the capacitance of the differential capacitor 20. The initiated change in capacitance is detected within the controller circuit 33, whereupon a control signal is delivered through the leads 44 to the heater current controller circuit 42 for causing the heater coil 40 to be energized and heated sufficiently for

1 imparting thermal strain to the link 14. As the link thermally
2 is strained, the cylinder 26 is repositioned relative to the bores
3 of the blocks 30, whereupon the initial capacitance of the
4 differential capacitor 20 is re-established. As repositioning
5 of the metallic cylinder 26 is achieved, the thermopile 36
6 continuously detects the temperature differential, as it is
7 established between the link 14 and the specimen 12, so that at
8 the instant the cylinder 26 is repositioned, for re-establishing
9 the capacitance, the temperature differential is a known value.
10 Since the thermal characteristics of the link 14 are known, and
11 preferably matched with those of the specimen, the extent of
12 thermal strain imposed upon the link 14 is a known value. Since
13 the thermal strain thus imposed on the link 14 is equal to the
14 mechanical strain imposed on the specimen 12, in repositioning
15 the cylinder 26, the mechanical strain imposed on the specimen 12,
16 through mechanical loading, becomes a known value.

21 Second Embodiment

22 A second embodiment of the invention is illustrated in
23 Fig. 3. This embodiment is a strain gage, designated 50, which
24 is quite similar in function to the embodiment illustrated in
25 Fig. 1. The embodiment of Fig. 3 is particularly useful in
26 instances wherein mechanical strain imposed on a specimen 12
27 involves minimal motion and therefore requires amplification of
28 the resulting motion.

1 The strain gage 50 includes a flexible link 52 rigidly
2 supported at its opposite ends by suitable mounting posts 54.
3 These posts are fixed to the surface of a specimen 12 in a
4 mutually spaced relationship, in a manner similar to that in
5 which the brackets 16 and 21 are mounted. The link 52, however,
6 is a thin, elongated member which is fabricated from a given
7 material, preferably the material of the specimen 12. Hence, the
8 link 52 also possesses thermal expansion characteristics which
9 substantially match those of the specimen. In practice, the
10 link 52 mechanically is loaded or bowed, as it is secured to the
11 surface of the specimen 12 by the mounting post 54. Of course,
12 as can be appreciated, where desired the mounting post 54 can be
13 fabricated as a unitary portion of the link 52 so that the link,
14 in effect, is configured to conform to an inverted U-shaped
15 configuration.

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20 The link 52 is deflected in lateral directions as the
21 specimen 12 is axially strained. This laterally directed
22 deflection acts to amplify the resulting motion as strain is
23 imposed on the specimen 12. This motion then is detected through
24 a differential capacitor 56, which possesses a mode of operation
25 also conforming to that of the differential capacitor, illustrated
26 in Fig. 8.

1 It is important to note that the capacitor 56 is so
2 fabricated as to include a pair of fixed capacitor plates,
3 designated 58, mounted in a manner such that the spacing
4 established therebetween remains constant in dimension. A pair
5 of movable plates, designated 60, is fixedly mounted on the link
6 52, at opposite sides thereof, so that the pair of movable plates
7 is oppositely and simultaneously displaced relative to the
8 adjacent fixed plates 58 as lateral deflection is imparted to the
9 link 52. Thus, the capacitor 56 serves to provide an output
10 signal indicative of changes in its established capacitance for
11 purposes of indicating the relative motion achieved by the link 52
12 as the link is flexed, or deflected, due to mechanical strain
13 imposed on the specimen 12.

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18 As schematically illustrated, the strain gage 50 also
19 includes a heater unit 62 coupled with a heater control circuit
20 64. This circuit is similar to the circuit 42 coupled with the
21 heater coil 40 and functions to achieve a similar result. The
22 unit 62 preferably is a heater coil wound about the link 52,
23 however, the unit 62 can be of any suitable configuration.

1 It is important to note that the link 52 possesses
2 thermal expansion characteristics which match those of the
3 specimen 12. Therefore, ambient heat serves similarly to impose
4 thermal strain on both the specimen 12 and the link 52 so that the
5 variation which occurs in the spacing of the plates 58 and 60 is
6 a function of the mechanical strain imposed on the specimen 12.
7 Hence, as the specimen 12 mechanically is loaded for imposing
8 thereon mechanical strain, detectable thermal strain can be
9 imposed on the link 52 in order that the extent of the imposed
10 mechanical strain can be determined. This determination is made
11 simply by driving the heater unit 62 to a temperature sufficient
12 for thermally straining the link 52 until the link is strained
13 for again centering the pair of moving plates 60 relative to the
14 fixed plates 58.

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19 A differential temperature sensor, similar to the
20 thermopile 36 is employed in detecting the established
21 temperature differential required in repositioning the plates of
22 the capacitor 56. It is preferred that the current through the
23 heater 62 be detected, through a suitable ammeter, not shown,
24 for purposes of determining the temperatures at which thermal
25 strain sufficient for repositioning the plates is achieved.

Operation Of The Second Embodiment

The mode of operation of the embodiment illustrated in Fig. 3 is quite similar to that of the embodiment shown in Fig. 1. It is, however, to be understood that the link 52 is a flexible member rigidly mounted at its opposite ends on a surface of the specimen 12 and that the link is, in operation, laterally deflected from an initial position as an axially directed mechanical load is imposed on the specimen 12. The imposed lateral deflection is, in effect, a magnification of axially directed, relative motion established between the link and the specimen, as a consequence of mechanical loading. As deflection of the link 52 thus occurs, a variation in the spacing between the moving plates 60 and the adjacent fixed capacitor plates 58 is achieved. Repositioning of the moving plates 60 is effected through thermal strain imposed on the link 52 and this strain is a function of the temperature of the link. The imposed thermal strain is proportional to the strain mechanically imposed on the specimen 12 and is therefore indicative of the mechanical strain imposed on the specimen.

Third Embodiment

Turning now to Fig. 4, therein is illustrated a strain gage 70 which is a third embodiment of the instant invention. The structure of this device is quite similar, in many respects, to the device illustrated in Fig. 1. However, the mode of operation of this embodiment substantially is different.

1 It should be noted that the embodiment illustrated in
2 Fig. 1 employs a detected temperature differential for purposes
3 of providing an electrical signal indicative of thermal strain
4 achieved by the link 14. This signal then is converted into
5 intelligence indicative of the mechanical strain imposed on the
6 specimen at the instant the link 14 has been thermally strained
7 to achieve the length commensurate with the mechanically strained
8 specimen 12. Conversely, the embodiment of the invention, as
9 illustrated in Fig. 4, attempts to maintain a constant temperature
10 differential between the link 14 and the specimen 12. The
11 initiated change in capacitance of the differential capacitor 20,
12 therefore, is employed to provide a signal which is indicative of
13 mechanical strain.

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18 The embodiment depicted in Fig. 4 particularly is suited
19 for use in instances wherein the test specimen 12 is subjected to
20 changes in temperature. When changing temperatures are
21 encountered, the specimen 12 necessarily experiences a change in
22 its dimensions, due to changing thermal effects. Should the test
23 specimen 12 simultaneously be thermally and mechanically loaded,
24 it necessarily is subjected to mechanical stress as well as
25 thermal stress. Where a simultaneous mechanical and thermal
26 stressing of the specimen 12 is encountered, it is imperative
27 that the effects of thermal strain be nullified in order to obtain
28 an accurate measurement of the mechanical strain. Therefore, the
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1 heater coil 40 is utilized for initiating changes in the
2 temperature of the link 14 in a manner such that the temperature
3 of the link is caused to follow the temperature of the
4 specimen 12.
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9 It, therefore, is important to understand that the
10 thermopile 36, as illustrated in Fig. 4, is employed in
11 detecting thermal differentials established between the link 14
12 and the specimen 12, which, in the simplest case, is a zero
13 differential. This condition is achieved simply by energizing
14 the heater coil 40 sufficiently for causing the temperature of
15 the link 14 to follow the temperature of the specimen 12.
16 Consequently, the thermal strain of the link 14 always matches
17 the thermal strain of the specimen 12. Any change in position,
18 as detected by the differential capacitor 20, then is indicative
19 of the mechanical strain imposed upon the specimen 12.
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24 Operation Of The Third Embodiment

25 The operation of the third embodiment of the invention
26 illustrated in Fig. 4, is similar to the operation of the
27 embodiment illustrated in Fig. 1, with one important exception.
28 This exception is typified by the particular use of the heating
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coil 40. Instead of heating the link 14 in order to establish a temperature differential between the link and the specimen 12, sufficient to impart a greater thermal strain to the link 14, the heater coil 40 is driven in a manner such as to establish a zero temperature differential between the link and the specimen.

It is to be understood, of course, that due to the various combinations of masses, orientation of the gage relative to external sources of heat, and for various similar reasons, it is possible to employ a preselected temperature differential, which is not zero, for achieving a desired matched thermal expansion of the link 14 and the specimen 12.

Referring for a moment particularly to Fig. 7, therein is illustrated one manner in which the thermopile 36 can be coupled with a suitable voltage drive meter 72 for providing gage read-outs over large temperature ranges. In order to maintain the voltage level of the output signal of the thermopile 36 within a usable range for use with the meter 72, the links between the opposite ends of the thermopile can be coupled through a potentiometer 72 so that a continuous sampling of total specimen temperature is, in effect, applied proportionally at both

1 sides of the meter 72 for reducing the effect of the large
2 temperature changes encountered as the temperature of the specimen
3 is increased throughout the total operative range. This manner
4 of coupling can be employed with any of the gages hereinbefore
5 described.

10 Fourth Embodiment

11 Referring now to Fig. 5, there is illustrated a
12 fourth embodiment of the invention. This embodiment is a gage
13 80, quite similar in design and function to the gage 50
14 illustrated in Fig. 3.

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19 The gage 80 includes a flexible link 52 and a
20 differential capacitor 56 mounted on the surface of a specimen 12.
21 The link 52 and differential capacitor 56 function in the manner
22 hereinbefore described. However, the output signal developed by
23 the differential capacitor 56 is delivered to a controller
24 circuit 82, through suitable leads 84 and acts to drive a
25 recorder, not shown, which serves to record detected changes in
26 capacitance initiated as the specimen 12 is strained, as
27 hereinbefore described.

1 The gage 80 preferably is employed in an operative
2 environment wherein the gage is heated by environmental sources
3 of heat, not shown. Hence, the link 52 operatively is
4 maintained at a temperature such that the instantaneous
5 temperature differential existing between the specimen 12 and
6 the link is a constant value. It is important here to note that
7 the embodiment illustrated in Fig. 5 does not include a heating
8 element, as it is heated, in its entirety, by energy derived
9 from the environmental source of heat. Due to the fact that the
10 gage 80 can be calibrated, the recorded output of changes in
11 capacitance of the differential capacitor 56 is suitable for use
12 in detecting and determining mechanical strain as it is imparted
13 to the specimen 12.

14 15 16 17 18 Operation Of The Fourth Embodiment

19 In operation, the gage shown in Fig. 5 is mounted on
20 the surface of a specimen 12 and the specimen is loaded in either
21 compression or tension. As the specimen 12 responsively is
22 strained, resulting motion imparted to the specimen 12 is
23 amplified as lateral deflection of the link 52 is experienced.
24 This deflection serves to vary the capacitance established
25 between the fixed plates 58 and 60 of the differential capacitor
26 56. This capacitance differential is detected at the controller
27 circuit 82 and the resulting signal is applied to a recorder.
28 The recorded signal then is employed in determining the extent
29 of mechanical strain.
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1 Thermal strain imposed on the specimen can be ignored
2 since the link 52 and the specimen 12 have substantially matched
3 thermal expansion characteristics and the gage is heated by the
4 same source which serves to heat the specimen 12.
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9 Fifth Embodiment

10 The embodiment of the invention as illustrated in
11 Fig. 6 is a gage 90. This gage is quite similar in design and
12 function to the gage 10, illustrated in Fig. 1, the gage 70,
13 illustrated in Fig. 4, and the gage 80, depicted in Fig. 5.
14 However, it is important to note that the gages 10 and 70 employ
15 heating coils 40 for purposes of heating the link 14. While,
16 as is the case with the embodiment illustrated in Fig. 5, the
17 gage 90 does not employ a heating element. Otherwise the
18 structure of the gage 90 is similar in design and function to
19 the structure shown in Fig. 1. Therefore, a detailed description
20 of the structure is here omitted.
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25 Operation Of The Fifth Embodiment

26 In practice, the link 14 is supportingly mounted on
27 the surface of the specimen 12, employing brackets 16 and 19,
28 as illustrated in Fig. 1. The differential capacitor 20 is
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1 employed in providing an output signal to a controller 92 which
2 serves to drive a recorder, in a manner quite similar to that in
3 which the controller 82 drives a similar recorder. Since the
4 link 14 and the specimen 12 are provided with matched thermal
5 expansion characteristics, the temperature of the environment
6 serves to initiate an elongation, or contraction, such that the
7 thermal strain of the link 14 is commensurate with that of the
8 specimen 12 as the link and the specimen simultaneously are
9 thermally stressed. Since the gage 90 and the specimen 12 are
10 heated from the same source of heat achieved, relative displacement
11 initiated between the mechanically loaded specimen 12 and the
12 link 14 is a function of mechanical strain and therefore changes
13 detected in the capacitance of the differential capacitor are
14 initiated as a consequence of mechanically imposed strain. By
15 detecting the changes in capacitance of the differential
16 capacitor 20 the extent of the mechanical strain imposed on the
17 specimen 12 is detected and can be determined through an
18 empirical calibration of the gage.

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23 In view of the foregoing, it is to be understood that
24 the various embodiments of the instant invention have utility in
25 detecting mechanically induced strain through the use of
26 capacitors. Such utility is particularly significant in
27 instances wherein the specimen being tested operatively is
28 subjected to extreme temperatures. Furthermore, the various
29 embodiments are readily adaptable for use where the specimen
30 is to be subjected to compression as well as to tension.
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1 The specific embodiment employed in measuring strain
2 for any given specimen is somewhat dependent upon the particular
3 environment of the specimen. For example, where ambient
4 temperature remains constant, the embodiment illustrated in
5 Fig. 1 serves quite satisfactorily, particularly where the
6 imposed mechanical strain is significant. Of course, in the
7 event the resulting motion induced by the mechanical strain is
8 minimal, a motion magnification may be required. In such
9 instances, the embodiment illustrated in Fig. 3 can readily be
10 employed.

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15 In employing the device of Fig. 1, a linear output can
16 be expected, whereas when employing the invention embodied in the
17 device of Fig. 3, the resulting output may require an empirical
18 determination or calibration of the gage 50 in order that the
19 derived intelligence be rendered useful. In instances wherein
20 a gage being employed is subjected to rapidly changing
21 temperatures, such as may be encountered upon the leading edge of
22 aircraft or wind-tunnel models, the embodiment of Fig. 4
23 preferably is employed. In such instances, changing thermal
24 conditions continuously are monitored and effects thereof are
25 neutralized by driving the temperature of the link 14 in a manner
26 such that it follows closely the temperature of the specimen 12.
27 Hence, any relative motion achieved between the link 14 and the
28 surface of the specimen 12 is a function of a mechanical strain.
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1 Conversely, where the temperature differential operatively
2 established between the link and the specimen is zero, the
3 heating coils or units are eliminated and the output signal
4 derived from the differential capacitor is employed in determining
5 the quantity of mechanical strain imposed on the specimen.

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10 Hence, the present invention provides a suitable
11 solution to a perplexing problem, while yet providing a strain
12 gage which functions accurately and efficiently at excessively
13 high temperatures over increased ranges.

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18 Although the invention has been herein shown and
19 described in what are conceived to be the most practical and
20 preferred embodiments, it is recognized that departures may be
21 made therefrom within the scope of the invention, which is not
22 to be limited to the illustrative details disclosed.