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POSTFLIGHT EVALUATION OF ATLAS-CENTAUR AC-4 (Launched December 11, 1964)

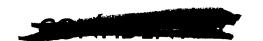
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Cleveland, Ohique Landing

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

WASHINGTON, D. C. • JULY 1965





POSTFLIGHT EVALUATION OF ATLAS-CENTAUR AC-4

(Launched December 11, 1964)

By Staff of the Lewis Research Center

Lewis Research Center Cleveland, Ohio

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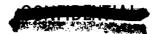
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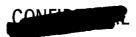
I. SUMMARY

The Atlas-Centaur AC-4 vehicle (Atlas 146D, Centaur 4C) was successfully launched at 0925:02:548 EST on December 11, 1964 from ETR Complex 36A. Included on board the Centaur stage was a mass model Surveyor of 2090 pounds. The major mission objectives (see II. INTRODUCTION) were satisfied; however, because of the inability to control the position of the hydrogen propellant within the tank under near weightless conditions, some of the secondary test objectives were not accomplished.

The AC-4 Atlas-Centaur vehicle was launched on an azimuth of 105° East of true North and was programed to a flight azimuth of 102.5° East of true North. The Centaur guidance system injected the AC-4 upper stage into a near perfect 90-nautical-mile circular orbit (94.92 n. mi. apogee altitude, 88.20 n. mi. perigee altitude). This was the first flight with the inertial guidance system operating as closed loop; velocity errors were well within nominal values. To ensure structural integrity of the nosecone during higher atmospheric heating than on Centaur flights AC-2 and AC-3, thermal insulation was applied to the forward section of the AC-4 vehicle. This Thermalag insulation maintained the maximum skin temperatures well within prescribed limits. No structural difficulties or serious vibration levels were experienced by the vehicle; the altitude wind loadings at the time of launch were relatively low.

During the coast phase of the AC-4 Centaur flight, the 4-pound thrust of the ullage motors was insufficient to position the remaining liquid hydrogen in the bottom of the propellant tank. During the first vent, liquid hydrogen instead of ullage gas was bled from the tank; consequently, uncontrollable vehicle forces were set in motion. Excessive hydrogen vent losses and vehicle tumbling precluded successful restarting of the Centaur main engines. An important result of the flight is the realization that, on main engine cutoff after orbital flight has been obtained, kinetic energies may be present within the propellant that far overshadow the intermolecular forces within the fluid. This finding has considerable significance not only to future Centaur two-burn vehicles but to other space vehicles where propellant management in a nearweightless condition may be a requirement.

Trajectory analysis of the AC-4 flight has indicated a deficiency in the models used in the computation of the predicted thrust acceleration. This deficiency was similar to the results obtained from the AC-2 and AC-3 flights and appears to be related to the estimate of the base drag. The significance of this discrepancy is that the payload at injection for an operational Centaur vehicle (AC-15) may be increased approximately 45 pounds.





II. INTRODUCTION

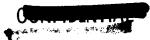
The AC-4 Atlas-Centaur vehicle, which was successfully launched from ETR on December 11, 1964 at 9:25 a.m. EST was the fourth in a series of developmental flights. Ultimately the Atlas-Centaur vehicle will be used to place a Surveyor spacecraft on the moon. A payload of 2090 pounds was carried aboard AC-4, making it the first Atlas-Centaur to date to carry a mock payload of the Surveyor. The objectives of the flight were as follows.

PRIMARY TEST OBJECTIVES

- (1) To demonstrate the structural integrity of the Atlas and Centaur vehicles during all powered phases of flight
- (2) To demonstrate the system integrity of the guidance system
- (3) To obtain data on the measuring accuracy of the guidance system during closed-loop flight
- (4) To demonstrate that the guidance system provides proper discrete and steering signals to Atlas and Centaur flight control systems
- (5) To verify the structural and thermal integrity of the Centaur nose fairings and insulation panels
- (6) To verify the satisfactory performance of the insulation-panel and nose-fairing-jettison systems

SECONDARY TEST OBJECTIVES

- (1) To demonstrate the restart capabilities of the Centaur main engine system in flight environment
- (2) To obtain data on the following flight environments: pressures, temperatures, and vibration levels
- (3) To verify the satisfactory operation of the Atlas-Centaur separation system
- (4) To verify that the flight control system supplies the proper signal for attitude control and dynamic stability of the Centaur vehicle
- (5) To demonstrate the capabilities of the coast motors and the attitude control system to retain the propellants in the proper attitude for engine restart





- (6) To obtain data on the vehicle acceleration, propellant behavior and heat transfer, and propellant tank ullage temperatures and pressure histories during coast phase
- (7) To obtain data on the performance of the H₂O₂ attitude control system, hydraulic system, pneumatic system, electrical system, radio-frequency systems (telemetry, Azusa, and C-band beacon), Centaur main engine system and all of the Atlas systems
- (8) To obtain data on the launch-on-time capability (fixed launch azimuth of the Atlas-Centaur
- (9) To demonstrate that the guidance equations and the associated trajectory parameters are satisfactory
- (10) To obtain data on the capability of the Centaur to perform a retromaneuver
- (11) To obtain data on the spacecraft environment during the launch-to-spacecraft separation phase of flight
- (12) To verify the ability of the Centaur propulsion system to start in the flight environment and burn to guidance cutoff
- (13) To obtain data on the orbital environments, terminal behavior, and general postmission performance of vehicle systems until loss of all data links

The coast motors in item (5) of the secondary objectives are two 2-pound thrust H_2O_2 propellant settling motors that burn continuously throughout the coast period. The spacecraft separation in item (ll) of the secondary objectives was only a simulated event, which provided a terminal point for obtaining spacecraft environmental data.

The flight events and the Centaur, sustainer, and booster-stage weights are presented in tables II-I and II, respectively. A schematic diagram of the AC-4 flight is shown in figure II-1, and an illustration of the general arrangement of the Centaur stage is presented in figure II-2.



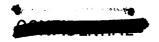
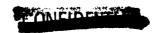


TABLE II-I. - SEQUENCE OF FLIGHT EVENTS a

Event	Nominal time (b)	Actual time
Lock LH ₂ vent valve Programer start; 2-in. rise Open LH ₂ vent valve BECO discrete Booster engine cutoff; close LH ₂ vent valve	T - 7 T + 0 T + 74 T + 150.36 T + 150.46	CT - 7.32 T + 0 T + 74.5 CT + 148.81 T + 149.05
Jettison booster package Open LH2 vent valve Jettison insulation panels Start Centaur boost pumps Unlatch nose fairings	T + 153.46 T + 160.36 T + 200.36 T + 209.36 T + 213.86	T + 151.75 T + 159.4 T + 198.47 T + 208.2 T + 211.89
Jettison nose fairing SECO/VECO Close LOX and LH2 vent valves; start hydraulic recirculating pump Atlas-Centaur separation	T + 214.36 T + 226.36 T + 226.46 T + 228.86	T + 212.38 T + 224.25 T + 225.6
Fire retrorockets	T + 228.86 T + 228.96	T + 226.76 T + 226.86
LOX and LH2 prestart; admit guidance for attitude control	T + 229.96	T + 227.9
First main engine start Admit guidance for steering control Main engine cutoff (MECO); ullage control engines on; admit guidance for attitude control	T + 235.96 T + 239.96 T + 573.4	T + 233.8 T + 237.6 T + 572.65
Open LH2 vent valve	T + 615.4	T + 615.2
Close LH ₂ vent valve Start boost pumps LH ₂ prestart; LOX prestart Second MES; ullage control engines off; inhibit guidance Admit guidance for steering control	T + 2006.4 T + 2010.4 T + 2045.4 T + 2050.4 T + 2054.4	CT + 2005.47 T + 2010.1 T + 2044.8 CT + 2049.75
Second MECO; inhibit fixed vector 2 Separate spacecraft Begin 180° turn End 180° turn; start retromaneuver thrust H ₂ O ₂ "All Off"; open LOX and LH ₂ vent valves End retromaneuver thrust	T + 2104.4 T + 2152.9 T + 2157.9 T + 2387.9 T + 3517.9 T + 3519.9	T + 2103.8

 $^{^{\}mathrm{a}}\mathrm{All}$ symbols and abbreviations are defined in appendix A.



bRef. 1.

c_{Ref. 2}.



TABLE II-II. - WEIGHT SUMMARY

Weight,		1811 102 4017 122 128 49 90	6191		500	00 00 00 00 00 00 00 00 00 00 00 00 00	1166	ျဖ	5 5	265 502													
Atlas booster stage	Basic hardware	Body group Separation and destruct systems Propulsion group Hydraulic and pneumatic group Electrical group Instrumentation group	Total	Residuals	Trapped RP-1	\$ 4 0	Unburned lubrication oil Total		1	lotal Atlas Weight at lift-oil													
Weight, 1b		1537 2308 319 1905 123	235	428	7177		496 515	845 2537	50 L	85 85	5102	12 279		74 589	176 176 15	73	243 866	sec)	683 2278 3	140	450	3644	
Sustainer stage	Basic hardware	Interstage adapter Body group Separation and destruct systems Propulsion group Prime power system Hydrallic and pneumatic group	† }	Environmentation group	Total	Residuals	Trapped RP-1 Trapped LOX	n impulse n impulse	Unburned lubrication oil GN2 CN2	N O O	Total	Total jettison	Flight expendables	Main impulse RP-1	Main impuise no. Lubrication oil Cascons ovidion went	Sustainer thrust decay	Total	Ground expendables (2.63 a	RP-1 expended LOX expended Lubrication oil expended Exterior frost dumped	LNS dumped TOX dumped TOX overhoard vent	Preignition GO2 loss	Total	
Weight, lb		1159 1284 328 136 163	000 k	2090	6553		2052 1278	3330		978	4712 106 201	1 L 4 G 7 G C	a 12	6158		3 906		200	8 8 9 4 7 8 8 6 9 8 8 6 8 6	200	23 807	39 848 - 107	39 741
Centaur stage	Basic hardware	Body group Propulsion group Guidance group Control group Pressurization group Electrical group	Separation equipment Missiph instrumentation Missiph	ntscertaireous equipment Payload	Total	Jettisonable hardware	Nose fairing Tank insulation	Total	Residuals	Unburned LH2	ned	α Ω΄ αν αν αν αν αν αν αν αν αν αν αν αν αν	ne Ice	Total	Expendables	Main impulse LH2 Main impulse LOX	Ground vent, H2	Inflight offil, LH2	Inflight chill, LOA Boost-phase vent, H2 Boost-phase vent, O2 H2O2	ne Ablated ice	Total	Total tanked weight Ground vent ^a	Total Centaur weight at lift-



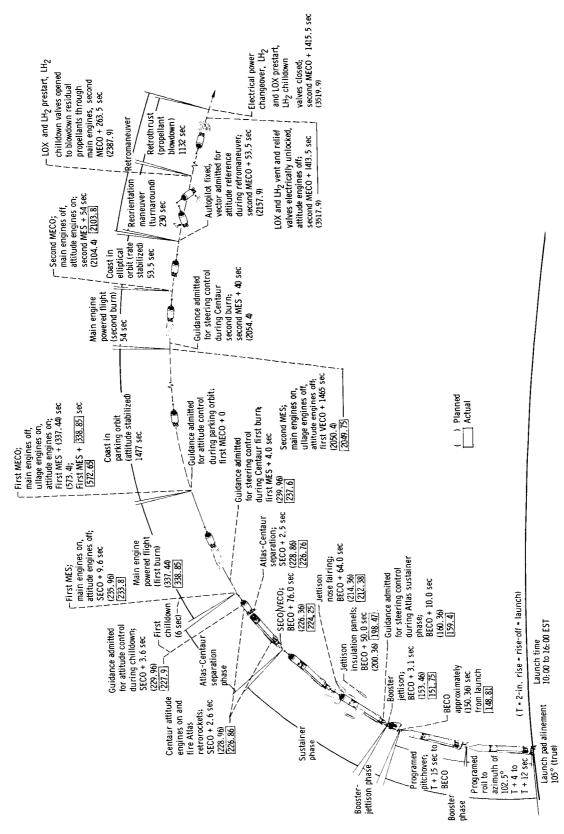
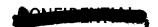


Figure II-1. - AC-4 flight compendium (ref. 3).



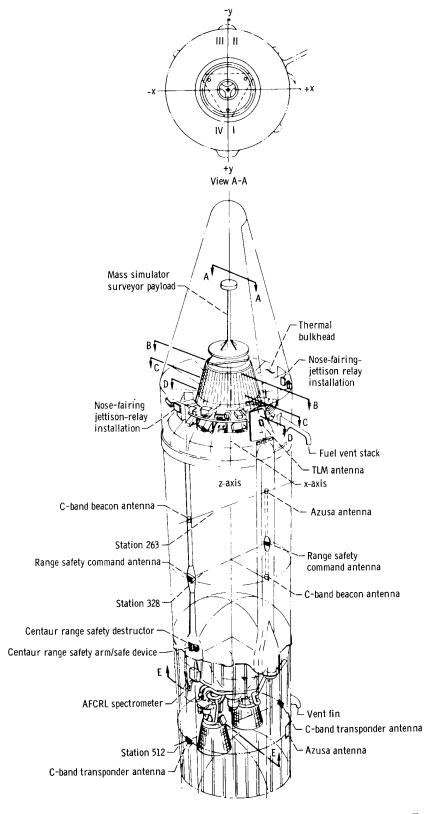
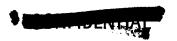
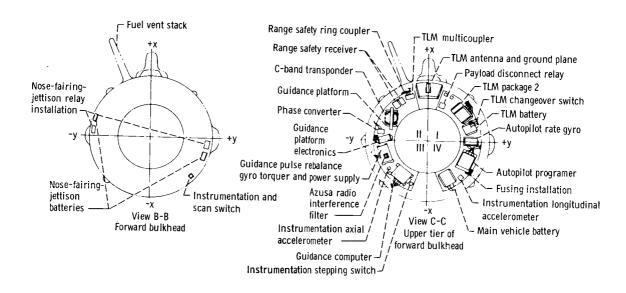
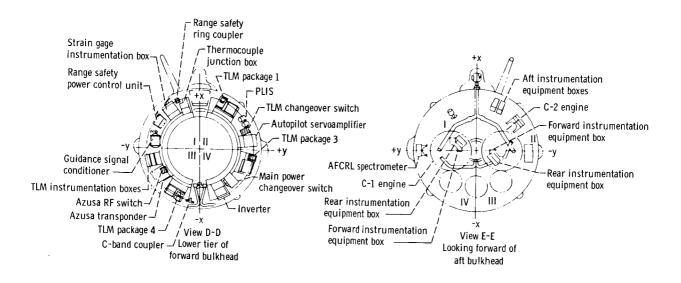


Figure II-2. - Centaur 4C general









arrangement (ref. 3).





III. LAUNCH OPERATIONS

ARRIVAL AND ERECTION

The Atlas 146D booster arrived at ETR on July 23, 1964 followed by the interstage adapter (I/A) on July 28. The Atlas booster was erected on Complex 36A on July 30 and the I/A was mated to the Atlas on August 4. The Centaur 4C arrived at ETR on August 14 and was mated with the Atlas on August 20.

The Atlas-Centaur launch vehicle was decrected and returned to the hangar on September 8 due to forecasts of Hurricane Dora approaching the coast of Florida. Recrection of the launch vehicle on Complex 36A began on September 14 with the Atlas, I/A on September 15, and Centaur 4C on September 16.

AUTOPILOT AND GUIDANCE INTEGRATED TEST

The initial test was conducted on October 16 and was completed, but because of a discrepancy that occurred, the Centaur programer was sent back to San Diego for rework. The problem involved a resistor of the wrong value in the timing circuit. (For additional information see section XII. FLIGHT CONTROL SYSTEM.) The second test was conducted on October 22. The test was completed and all results were satisfactory.

FLIGHT CONTROL AND PROPELLANT TANKING TEST (QUAD TANKING)

The first tanking test was conducted on October 27 (ref. 4). The test was proceeding normally until an indication of overpressurization was noted in the Centaur LOX tank during the LOX tanking phase. The overpressurization was due to a failure in the propellant level indicating system (PLIS) and the human error to acknowledge the 100-percent-propellant-level indicator light. (For additional information see section X. VEHICLE STRUCTURES.) The propellants were detanked and the test was scrubbed.

Prior to the second tanking test conducted on November 6 (ref. 5), a Stokes gage was installed on the intermediate bulkhead to check for leaks that might have occurred as a result of the overpressurization. A leak found in one of the PLIS sensing lines was also corrected. The test was completed after two holds, one at T - 80 minutes and the other at T - 45 minutes. The holds were due to a faulty heater circuit in the air-conditioning system.

The third and final tanking test was conducted on November 16 (ref. 6) and was completed with satisfactory results. Prior to this test, the insulation panels were removed to permit X-rays of the station 408 area. The X-ray results showed no defects from overpressurization of the Centaur LOX tank.





A special Centaur LOX tanking test was conducted on November 27 (ref. 7) to verify the modifications to increase the temperatures of the H₂O₂ system. The results of this test were satisfactory.

FLIGHT ACCEPTANCE COMPOSITE TEST

The flight acceptance composite test (FACT) was successfully accomplished on November 24 with only minor discrepancies encountered (ref. 8).

COMPOSITE READINESS TEST

The composite readiness test (CRT) was successfully accomplished on November 30 with no significant discrepancies encountered (ref. 7).

ENCAPSULATION

The first encapsulation of the mass model was accomplished on October 19 and was mated to Centaur prior to the first flight control and propellant tanking test. The encapsulated payload was demated and returned to Hangar AM on November 25 for final preparations for flight. The encapsulated mass model was remated to Centaur on December 1.

LAUNCH

The first launch attempt was conducted on December 4. After a hold for 5 hours and 13 minutes at T - 200 minutes, because of a short in the airborne side of the Atlas umbilical plug, Pl002, the countdown proceeded normally until T - 84 minutes. The launch attempt was scrubbed at this time due to a severe weather warning.

The second launch attempt was conducted on December 5. The countdown proceeded normally to T - 5 minutes for the scheduled 10-minute built-in hold. The hold was extended for weather and subsequently the launch attempt was scrubbed due to adverse weather conditions.

The third and successful attempt to launch was accomplished on December 11 at 0925:02:548 a.m. EST. The countdown proceeded normally to T - 90 minutes and the 60-minute built-in hold. This hold time was extended 35 minutes because of a problem in the launch stabilization system. After a total hold time of 95 minutes the count was resumed and proceeded normally to lift-off. The 10-minute built-in hold at T - 5 minutes was omitted due to the extended hold time at T - 90 minutes.

WEATHER

The weather conditions on launch day were favorable except for surface winds. The wind velocity recorded at the 90-foot level was 15 knots with gusts





up to 19 knots. The maximum critical allowable winds for Atlas-Centaur (AC-4) was 16.0 knots when fully tanked and at flight pressure.

Location of optical coverage	Percent coverage
Patrick Air Force Base Cocoa Beach Grand Bahama Island False Cape Melbourne Vero Beach	60 60 60 80 90

AC-4 MILESTONES

Event	Date (1964)
Arrival of Atlas 146D booster	July 23
Arrival of interstage adapter	July 28
Erection of Atlas 146D booster	July 30
Erection of interstage adapter	August 4
Arrival of Centaur 4C	August 14
Erection of Centaur 4C	August 20
Arrival of insulation panels	September 8
Deerection of Atlas-Centaur (Hurricane Dora)	September 8
Erection of Atlas 146D booster	September 14
Erection of interstage adapter	September 15
Erection of Centaur 4C	September 16
Erection of insulation panels	October 1
Arrival of nose fairing and mass model	October 6
A/P and guidance integrated test	October 16
Encapsulation of mass model	October 19
Mating of mass model	October 19
A/P and guidance integrated test	October 22
Flight control and propellant tanking test	October 27
Flight control and propellant tanking test	November 6
Flight control and propellant tanking test	November 16
Flight acceptance composite test	November 24
Demate encapsulated mass model	November 25
Centaur special IOX tanking	November 27
Composite readiness test	November 30
Mating of encapsulated mass model	December 1
Attempted launch	December 4
Attempted launch	December 5
Launch	December 11





AC-4 COUNTDOWN (REF. 9)

F - 2 Days

Atlas tanked with fuel (RP-1)

F - 1 Day

Atlas-Centaur A/P readiness test
Atlas-Centaur TLM/RF system test
Nose-fairing bottles storage
H₂O₂ tanking and passivation
Insulation panel jettison reservoir storage
Engine trich auto flushing
Main engine Hypergol purge
Boost-pump and attitude-engine firing
Installation of pyrotechnic devices

F - O (Launch) Day

	Starting time	Completion time
Atlas and Centaur range safety command destruct boxes installation	T - 360 min	T - 300 min
Atlas-Centaur A/P testing	T - 335 min	T - 300 min
Range safety command test	T - 230 min	T - 215 min
Guidance A/P integrated test	T - 145 min	$T - 70 \min$
Tower removal	T - 120 min	T - 80 min
Guidance final alinement	T - 80 min	$T-45 \mathrm{min}$
Centaur LOX tanking (55 percent)	T - 70 min	T - 60 min
Atlas LOX tanking	T - 60 min	T - 40 min
Centaur LH2 tanking	$T - 40 \min$	T-1 min 30 sec
Centaur LOX topping	T - 22 min	T - 6 min
Atlas LOX topping	T - 15 min	T - 2 min 35 sec
Guidance to flight mode	T - 4 min	
Programers to arm	T - 60 sec	
Guidance to internal	T - 8 sec	
Engine start - automatic sequence	T - 8 sec	
2-Inch rise	T - O	

LAUNCH-ON-TIME CAPABILITY ANALYSIS

On the third launch attempt on December 11, 1964, lift-off occurred at 9:25:02.548 a.m. EST. This obviously did not meet a 20-minute minimum lunar window opening at 9:00 a.m. The planned hold of 60 minutes at T - 90 minutes was extended to 95 minutes by weather and by problems in the Centaur main power changeover switch and in the launcher stabilization regulator. Utilization of the 10-minute absorbing hold at T - 5 minutes permitted launch at 9:25 a.m.; launch would have been at 9:35 a.m. without the availability of the 10-minute planned hold.



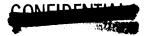


The second launch attempt on December 5, 1964 was scrubbed at T - 5 minutes by rapidly approaching thunderstorms; the vehicle was ready and holding at T - 5 minutes, but Range Safety did not permit launch because the ceiling was then below Range standards. The count proceeded normally to T - 5 minutes at 8:45 a.m. and held at this point, fully tanked, for 29 minutes prior to the initiating of abort procedures at 9:14 a.m. EST. Had weather not dictated an abort, this launch attempt apparently could have met the minimum lunar window on time.

The first launch attempt on December 4, 1964 was 313 minutes late at T - 90 minutes because of autopilot and instrumentation problems and was aborted at T - 84 minutes because of excessive ground winds. The first delay occurred at T - 200 minutes because of a problem in the autopilot system and lasted for 258 minutes. The hold at T - 200 minutes was extended an additional 55 minutes by telemetry instrumentation. There was a delay of 47 minutes at T - 90 minutes to catch up on procedures. After this, there was an additional hold at T - 90 minutes for 41 minutes because weather predictions at this time indicated possible decreasing winds. The count proceeded down from T - 90 minutes, and when the winds increased, launch was aborted at T - 84 minutes.

NOSE-FAIRING RECOVERY ATTEMPT

The objective of the recovery operation was to retrieve the nose fairing flown on the Atlas-Centaur AC-4 launch vehicle to evaluate the Thermolag effect on the structural integrity of the nose fairing. Recovery aids were three yellow-green fluorescein dye markers installed in each half of the fairing. Since the nose fairing is constructed of lightweight materials, it was expected to float on impact. Separation of the fairing occurred at 358 306 feet, and impact occurred 1026 seconds after lift-off.





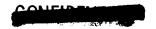
Specific items of interest								
Predicted impact point	25°50.4' N, 70°33.6' W							
Flight azimuth	102 ⁰ True of North							
Scheduled launch time	9:00 a.m. EST							
Actual launch time	9:25.02 a.m. EST							
Recov	ery force							
Unit	Position	Altitude, ft						
RIS Kilo	25°50' N, 70°30' W							
RIS Victor	25°37' N, 69°35' W							
Aircraft Silver 3 (JC-130)	26°15' N, 70°26' W	1000						
Aircraft Silver 4 (SC-131)	25°26' N, 70°41' W	500						
Impact a	rea weather							
Clouds	3/10 Cumulus at 2200 ft; cirrus, height unknown							
Wind	60° True of North, 20 knots							
Sea	Code 4-5 (8- to 10-ft waves)							
Sequenc	e of events							
Time, EST	Event							
0925.02	Lift-off							
0941	RIS Victor reported visual sighting of large charred-black rectangular object bearing 2850 true of North, elevation 300, range approximately 4 n. mi. Victor proceeded toward splash point.							
0948	RIS Kilo reported negative visual sighting.							
1000	recovery attempt.	RIS Kilo released from the recovery attempt. Silver 3 and 4 conducting visual search.						
RIS Victor reported unab locate object that was s Aircraft reported negati sults.								
1230	Recovery attempt terminated, negative results.							





CONCLUDING REMARKS

After a successful launch and separation, a large charred-black rectangular object believed to be a section of the nose fairing impacted approximately 4 nautical miles, bearing 285° true of North, from RIS Victor. Victor and the aircraft went immediately to the impact area and made a thorough visual search. No dye marker or fairing was sighted and it was assumed that it had sunk on impact. Victor and the aircraft searched the predicted impact area with negative results. The recovery attempt was terminated at 12:30 p.m. EST.



IV. FACILITIES AND GROUND SUPPORT EQUIPMENT

SUMMARY

The facility and ground support systems performed satisfactorily for the launch attempts and launch. A faulty regulator valve on launch day and a slow LH2 tanking rate on the launch attempt December 5 were the only problems. The environmental control system performed within the prescribed limits. Gas and propellant supplies were adequate. The propellant loading systems performed without problems, and the Atlas LOX red-line temperature was met without a hold to dump LOX as was necessary on AC-2 and AC-3.

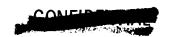
PROPELLANT LOADING SYSTEMS

During the launch attempt on December 5 the LH $_2$ vehicle tanking rate started normally then dropped to about one-half the normal transfer rate. This decrease in flow rate was attributed to contamination clogging the 150-micron filter in the LH $_2$ fill and drain valve. After detanking, samples were taken from the LH $_2$ storage tank.

Date	Remarks	Results				
December 8, 1964	The liquid was agitated by pressurizing and venting the tank then dumping approximately 500 gallons before sampling.	100 ppm N ₂ 5 ppm O ₂				
December 9, 1964 (a.m.)	This sample was taken after the tank was topped off.	190 ppm N ₂ 0.8 ppm O ₂				
December 9, 1964 (p.m.)	This sample was taken after the tank was topped off.	29 ppm N ₂ 0.7 ppm O ₂				

In addition, the $ext{LH}_2$ transfer line was purged and sampled for $ext{GN}_2$ and $ext{O}_2$.

The normal transfer line helium purge consists of a 1-hour purge at F - 2 days with no sample taken or further purge until LH₂ loading. At F - 2 days for the AC-4, the line was purged with helium from the fill and drain valve to the storage tank outlet valve for 1 hour and then sampled. The results showed 1.4 percent GN₂ and 0.38 percent O_2 . The purge was continued for an additional hour and sampled again. The results showed 0.045 percent GN₂ and 0.004 percent O_2 . These results indicated a lack of adequate purging of the transfer line in the past. On launch day, the line was purged for 1 hour and sampled prior to the start of LH₂ loading. The results showed 2.84 percent GN₂ and 0.74 percent O_2 . These results indicated an air leak into the LH₂ transfer line. The





tanking rate on launch day started at 11 percent per minute and leveled out at 8 percent per minute with the flow control valve wide open. This rate of flow is considered normal.

On AC-2 and AC-3, it was necessary to hold and dump Atlas LOX to meet the -284° F maximum redline on breakaway valve temperature. Low boiloff caused a low topping rate to maintain the LOX level between topping-low and topping-high probes allowing the LOX temperature in the topping line to exceed -284° F. On AC-4 the topping procedure was changed so that the topping-low probe was not reached until approximately T - 4 minutes. Since Atlas LOX is secured at T - 2:35 minutes, the LOX in the topping line does not have time to warm up. The breakaway valve temperature at LOX securing on AC-4 was -308° F (CN1165T).

PRESSURIZATION SYSTEM

All pneumatic systems performed within the limits. The only problem was a leaking regulator in the launch booster unit (P/N 27-8225-2). This valve regulates 6700 psig GN_2 from storage bottles to 2000 psig for the launcher stabilization system. During the hold at T - 90 minutes, this valve allowed the pressure to rise above 2000 psig. The valve was replaced, and the system was reported ready approximately 23 minutes prior to picking up the count at T - 90 minutes.

ENVIRONMENTAL CONTROL SYSTEMS

The air-conditioning-system temperatures and pressures were within the specified limits for launch. Some changes were required between the final tanking test and launch to achieve these limits. The tanking test and launch data are as follows:

Upper stage cooling limits
Temperature, OF
Temperature, 1 · · · · · · · · · · · · · · · · · ·
Pressure (minimum), psig
Final tanking test A/C duct temperature, OF
Final tanking test A/C duct temperature, F
To dow A/C dust temperatures. OF
F - 1 day A/C duct pressures, psig
F - 1 day A/C duct pressures, psig · · · · · · · · · · · · · · · · · · ·
Towards marriage A/C duct temperatures. The second
Laurier morning A/O date temperatures 1
Launch morning A/C duct pressures, psig · · · · · · · · · · · · · · · · · · ·
20.000

At T - 90 minutes (GN_2 flow start) the duct temperature increased from 46° to 50° F and remained steady to lift-off at a duct pressure of 0.82 psig. During the tanking test, the temperature was 8.4° F below the lower limit. This problem was solved by circumventing the dehumidifier cooling coils when proceeding to GN_2 flow (T - 90 min) since the dehumidifier is not required for GN_2 . The blower and the heater in this unit were still used. The temperature recorded at the dehumidifier showed a variation of 48° to 56° F; however, this measurement is not considered as reliable as that obtained by the duct transducer.

The land-line temperature measurements taken on the payload adapter and correlated with the duct temperature readings are shown in the following table.

CONTINUE

	r	200	
Time, min	Air-conditioning duct (CN1191T),	Payload adapter ring at station 171 (CA1468T), OF	
T - 90 hold	44 to 46	50 to 60	57 to 57.6
T - 40 (LH ₂ chill-down complete)	50	75	87 to 89
T - 25	50	0	84 to 85.5
T - 10	50	-25	83.5 to 84
Т - О	50	-25	84.2 to 87

Centaur Thrust Section Heating

Limits.

Temperature, OF			 	 	 	· · · 130±5
Pressure (minimum),	, psig		 	 	 	0.47
Final tanking test	duct temperature	∍, °F	 	 	 	127 to 130

The launch day duct temperature of 119° F gradually increased to 122° F, then to 125° F, then remained steady to lift-off. The duct pressure was 0.85 to 0.975 psig.

Atlas Pod Cooling

Limits.

Temperature (maximum),	С	F.													50
Pressure, psig					•										0.83 to 1.44
Final tanking test duc	t	tem	ре	ra	tu:	re	•	OF							• 47.5 to 50

The launch day duct temperature was steady at 43.4° F then decreased to 39.4° F at lift-off with a duct pressure of 1.02 psig. The temperature recorded at the A/C unit was 38° F for air and 34° F for GN₂ at launch. During the daytime tests, it is usual to gain 5° to 6° F temperature from the A/C unit to the vehicle as a result of duct warming.

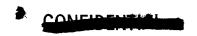




Atlas Thrust Section Heater

Atlas Thrust Section Heater
Limits.
LOX temperature (minimum), OF
Boom Retraction Times
Limits (2.2 to 3.5 sec to within 10° of vertical).
Upper boom (2-in. rise switch actuation)
Retraction start, sec
Lower boom (8-in. rise switch or TDPU relay K-4 actuated)
Retraction start, sec
The boom accumulator pressures were 2655 psig (redline is 2425 psig, minimum).
Launcher Holddown and Release System
The theoretical vehicle release point occurs when the holddown cylinders blow down from 5750 to 2480 psig. The parameter on blowdown time to 2480 psig is 0.45 second maximum. The release signal was sent at T - 0.81 second.
Blowdown start, sec
Gas and Propellants
Air-conditioning GN2 supply.
Total water volume including 28 tube bank trailers, cu ft

This 200 minutes is in addition to the 70 minutes required after start of detanking. The total time for $\rm GN_2$ flow was 90 minutes.

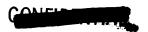




Helium insulation panel and engine purge.

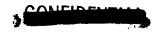
Total water volume from 12 tube bank trailers, cu ft	1 00 348
This 234 minutes does not include the 4 hours required for warmup after detanking.	
Helium for LOX transfer.	
Total water volume available from three tube bank trailers, cu ft 1 C Total available at 6:45 a.m., scf	381
Atlas thrust section heater GN2.	
Total water volume available from one tube bank trailer, cu ft 273 Total available, scf	200
The total time for GN_2 flow was 6 minutes.	
Launcher booster unit GN2.	
Ending pressure, psig	700 700 400
Facility GN ₂ (3000 psig).	
Ending pressure, psig	300 860 100
Facility helium (3000 psig).	
Ending pressure, psig	800 610 500
Facility helium (6000 psig).	
Ending pressure, psig	5600 1500 3550





Liquid oxygen.

Storage tank level at start, gal
The level gage transducers on both storage tanks were rejected after inspection, therefore, the preceding figures are an approximation.
Liquid helium.
Storage tank level at start, gal
Liquid hydrogen.
Storage tank level at start, gal





V. TRAJECTORY

SUMMARY

The AC-4 trajectory deviated only slightly from the preflight estimate. The major cause of these deviations was that the actual flight winds had more of a head-wind characteristic than did the nominal wind profile used in the preflight simulation. The thrust acceleration was also greater than that predicted during the atmospheric portion of the flight. The resultant trajectory was thus lofted, and BECO occurred approximately 1.5 seconds early. The actual trajectory was also slightly to the right of the predicted trajectory probably as the result of a small Atlas autopilot yaw drift and/or a deficiency in establishing the pitch over azimuth.

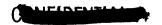
Subsequent to closing the Centaur guidance loop following BECO, the actual trajectory began to approach the predicted trajectory, and at MECO (parking orbit injection) the altitude error was approximately 1200 feet.

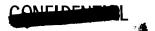
Reconstruction of the Atlas portion of the flight indicated that the reference specific impulse for the booster was 0.1 percent greater than nominal and for the sustainer was essentially as predicted. The reference thrusts were 0.4 percent greater than those predicted for the booster and essentially nominal for the sustainer. These values of thrust correspond to a lift-off weight of 302 954 pounds. In order to match the observed trajectory, it was also necessary to introduce a yaw drift of 0.21 degree per minute into the autopilot and to decrease the pitch rates by 0.2 percent.

Reconstruction of the Centaur phase resulted in an overall Centaur specific impulse of 431.9 seconds (+0.2 percent, table V-I), which is equivalent to an average engine specific impulse of 432.4 seconds. A deficiency in the calculated thrust acceleration has been noted in this and previous Atlas-Centaur postflight trajectory analyses. A possible cause of these discrepancies was the lack of an altitude sensitive term in the base drag calculation. The computed payload of an operational mission, such as AC-15, would be increased approximately 45 pounds if the modified AC-4 drag coefficients were used instead of the current nominal values.

TRAJECTORY EVALUATION

The AC-4 trajectory data were analyzed to obtain vehicle performance based on the observed trajectory. The "best estimate of trajectory," hereinafter called BET, obtained from the Data Processing Section AFETR (ref. 10) is a weighted combination of the outputs of the various tracking devices (see appendix B). A second objective was to evaluate further the capabilities of the preflight simulation techniques to predict the details of the flights. Also, it





may be possible to improve the accuracy of the various models used in the simulation and to refine the flight performance reserve propellant allotment on the basis of an analysis of the results of a number of flights.

Atmospheric Conditions

The atmospheric conditions that will exist at the time of launch cannot be accurately predicted, and therefore the deviation of the actual conditions from those assumed for the preflight simulation are the first items evaluated. The actual atmospheric conditions as determined by a Rawinsonde run made at 09:05 EST are presented in figure V-1. The temperature and pressure profiles (fig. V-1(a)) show relatively small deviations from the standard atmosphere used in the simulation. The measured wind profile is compared with the nominal seasonal profile used in the preflight simulation. The shift from the predicted tail wind to a head wind during the first 10 000 feet of altitude together with the lower velocity above this altitude tended to loft the trajectory. The Atlas pitch program was tailored to minimize the angles of attack with the assumed seasonal winds. Since the actual wind velocity was somewhat less than predicted, the angles of attack presented in figure V-2 resulted.

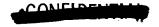
The dynamic pressure and flight Mach number histories presented in figure V-3 were generally greater than those predicted by the preflight simulation. This resulted in slightly higher drag forces than predicted; the drag at T + 72 seconds was approximately 2300 pounds greater than predicted.

Trajectory Parameters

The planned trajectory for AC-4 consisted of a powered boost flight to a 90-nautical-mile circular parking orbit with a coast phase of 1465 seconds. A second burn was then to be used to change the circular orbit into an eccentric orbit followed by a simulated payload separation sequence. As mentioned in section I and discussed elsewhere in this report, however, a second main engine start was not achieved. The trajectory analysis will be limited to the powered portion of the flight from launch to parking orbit.

The preflight simulation was generally a satisfactory prediction of the actual flight. Comparisons of the predicted and actual trajectories are presented in tables V-II and III and in figures V-4 to 6. The actual trajectory was higher during the atmospheric portion of the flight by approximately 0.4 nautical mile (fig. V-5). During this time, the vehicle was controlled by the Atlas autopilot, which was not designed to correct for changes in the wind profile or in engine performance. The error in altitude was gradually reduced by the Centaur guidance system, following its activation at BECO, so that the altitude error was only 0.2 nautical mile at orbit injection.

The actual flight path was up to 3 nautical miles to the right of the predicted flight path (fig. V-4). This error was probably the result of the vehicle pitching over at an azimuth slightly greater than planned and/or as a result of a slight yaw drift of the Atlas autopilot.





The energy added to the vehicle is indicated by the thrust acceleration (F-D)/W (fig. V-5). There is generally good agreement between the actual and predicted values except for the time period from T+70 seconds to BECO. During this time, the thrust acceleration was approximately 0.1 g greater than predicted. This discrepancy is similar to ones noted in the AC-2 and AC-3 analyses (ref. 11). The higher acceleration resulted in BECO occurring about 1.5 seconds early. A probable cause of this acceleration difference will be discussed later in this section.

The actual velocities were about 200 feet per second greater than those predicted during the boost phase (fig. V-6) as a result of the greater thrust acceleration. The velocity at BECO, however, was slightly less than the planned velocity due to premature BECO. There was good agreement between the actual and predicted velocities from BECO to first MECO.

The AC-4 Centaur stage was injected into a nearly nominal parking orbit (table V-III). The errors in perigee altitude, period, and eccentricity were 0.77 nautical mile, 0.02 minute, and 0.0005, respectively, which is indicative of satisfactory guidance system performance.

Vehicle Performance

Two techniques were used to evaluate the performance of the AC-4 vehicle. The most detailed was the trajectory reconstruction. In this method the preflight simulation program was used to find, by a process of iterations, those performance parameters which resulted in an analytical trajectory that best matched the observed positions and velocities. The second and more direct method was used to obtain the Centaur specific impulse. This method makes use of the relation between the observed thrust acceleration and specific impulse.

Centaur Specific Impulse

The overall specific impulse of a vehicle operating in a vacuum may be determined directly from the observed trajectory provided that the thrust is constant. As derived in reference 12, the overall specific impulse $\overline{\mathbf{I}}$ is defined as

$$\overline{I} = \frac{\text{Total vehicle thrust}}{\text{Total vehicle flow}} = \left[\frac{d}{dt} \frac{1}{\left(\frac{F - D}{W} \right)} \right]^{-1}$$

The inverse of the thrust acceleration W/(F-D) is a linear function of time if both the thrust-drag and the flow rates are constant. The Centaur stage operated in essentially a vacuum (zero drag), and the RL-10 engines were controlled to provide constant thrust and flow. Therefore it was possible to estimate from the BET a vehicle specific impulse \overline{I} of 431.8 seconds. This value was based on the time period from \overline{I} + 300 seconds to first MECO. Prior to \overline{I} + 300 seconds, the RL-10 engines had not reached equilibrium thrust, and therefore this method was not usable.





The average engine specific impulse of 432.3 seconds was obtained from the vehicle impulse by reducing the thrust 8.72 pounds and the flow 0.103 pound per second, which represent the contribution of the turbopump system.

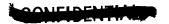
Trajectory Reconstruction

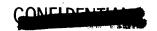
A good estimate of vehicle performance can be obtained by reconstructing the trajectory based on tracking data. This method makes use of a detailed trajectory simulation to determine a set of performance parameters, that is, thrust, weight flow, etc., that will yield a computed trajectory which will best fit the BET in a weighted least-square sense. The velocity and position residuals (differences between the reconstructed trajectory and the BET) may represent combined errors in the tracking data and in the simulation including the mathematical models describing engine and vehicle performance, for example, thrust, weight flow, and drag. If the residuals are small, there is a high probability that the derived values of the performance variables are a good estimate of those having occurred during the flight. If a consistent pattern in the residuals is observed over a series of flights, it may be possible to deduce the source of the error and improve the models used in the vehicle simulation.

The reconstruction of the AC-4 flight differed from that of AC-3 (ref. 11) in several ways. The Centaur guidance system supplied the steering signals for the flight following BECO, whereas, for the AC-3 flight, the guidance system was passive. Thus, for the AC-4 trajectory simulation it was necessary to simulate the guidance system. For this analysis, however, no attempt was made at a detailed evaluation of the guidance system. Secondly the sustainer residual propellant weight was used to determine the lift-off thrust and weight for the Atlas. In a similar manner, the estimated Centaur propellant weights (see section VII) were used to establish the Centaur thrust level.

The values of position, thrust acceleration, and velocity obtained from the reconstruction are compared with the preflight nominal trajectory and the BET in figures V-4 to 6, respectively, and tables V-II and III. struction agrees closely with the BET in all cases. The time of BECO, MES, and MECO listed as Reconstruction in table V-II are those times required to best fit the BET data using the preflight transient thrust and flow models. tempt was made in the AC-4 reconstruction to tailor these thrust and flow transient models to the observed data. Therefore, the reconstruction times are not directly comparable to the observed times. A summary of the propellant and vehicle weights used in the trajectory analysis are presented in table V-IV. hardware, or dry, weights were based on the summation of the weights of individual components. The weight at SECO was calculated from the dry weight plus the propellant residuals calculated from the measured propellant heads at SECO. The Centaur weight at SECO was based on the propellant loading calculated in The gross weight at lift-off was 302 954 pounds based on the preceding assumptions, which is approximately 290 pounds less than the estimate from the loading calculations (table II-II).

The derived propulsion parameters are presented in two forms in table V-I. The reference values are those values used in the propulsion models and cor-





respond to the values that would have been obtained at the standard engine inlet conditions. Since the engine inlet conditions are not generally at the standard values, a second ("specific") set of parameters is presented that are the values calculated to exist at the times specified.

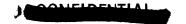
The Atlas performance was essentially nominal. Booster and sustainer reference specific impulse was less than 0.2 percent greater than the nominal reference values. The booster reference thrust was about 0.4 percent above nominal, whereas the sustainer was nominal. It was necessary to decrease the pitch attenuation factor of the Atlas autopilot from 1.020 to 1.018. This reduction in pitch rates is well within the predicted autopilot accuracy and may result from not simulating the time lags of the actual system. This factor was applied to all 10 pitch rates and no attempt was made to adjust individual rates to improve the match.

It was necessary in the reconstruction of the Centaur phase of the flight to simulate the operation of the guidance system. A simplified model of this system was employed in the trajectory reconstruction, which, although not accurately simulating the guidance system, permitted an otherwise satisfactory match of the trajectory. An analytical model of the Centaur propulsion was used in the postflight reconstruction that compensated for (1) the startup transients as reported in section VI, (2) the measured propellant temperatures and pressures, and (3) the observed nonequilibrium performance prior to T + 300 seconds. This nonequilibrium performance model agreed with the data in the engine specification (ref. 13). The preflight simulation, however, used constant values of thrust and specific impulse throughout the Centaur phase. Inclusion of the postflight model in the simulation of a typical operational mission, for instance, AC-15, will not change the payload at injection significantly (less than 1 lb increase); however, use of the postflight propulsion model improved the fit of the thrust acceleration data (fig. V-7). The apparent points of disagreement are due to the scatter in the tracking data. The component velocities were matched to within 10 feet per second and the positions to within 800 feet. nonrandom patterns observed in these residuals (figs. V-8 and 9) are attributed to the simplified model used in the reconstruction since the thrust acceleration residuals (fig. V-7(b)) do not exhibit the same trends. The Centaur had a specific impulse slightly better than predicted; the vehicle specific impulse was approximately 0.2 percent above, and the thrust was about 0.2 percent below the values predicted by the acceptance data.

A detailed trajectory listing is presented in appendix E. A modified set of drag coefficients was used in the calculation of these data. A discussion of the problems associated in achieving this match and its significance follows.

THRUST ACCELERATION DISCREPANCY

The magnitude and distribution of the position, velocity, and thrust acceleration residuals indicates how well the computed trajectory duplicates the actual flight. The reconstruction is considered satisfactory if the residuals are small and apparently random. A systematic pattern of these residuals would indicate a deficiency in one or more of the mathematical models used in the simulation or, some unaccounted for deviation in vehicle performance.



PONEIDENTIAL

The residuals in position, velocity, and thrust acceleration for the AC-4 reconstruction are presented in figures V-7 to 9. There is a deficiency in the calculated thrust acceleration indicated during the time period from T+60 to T+110 seconds when the nominal models are used. There is a corresponding variation in the velocity residuals. This pattern is similar to that noted in the AC-2 reconstruction (ref. 14) and in the AC-3 analysis (ref. 11).

The deficiency in calculated thrust acceleration could result from computing too low a level of thrust and/or flow, or too high a drag force. A maximum error of 10 000 pounds would be required in either thrust (5σ) or drag. A probable source of error in the thrust and flow calculations would be the LOX density. An error in LOX density of approximately 3 percent (14° F in LOX temperature) would be required, and this is not considered probable. Another possibility is the propulsion models themselves. These models assume linear variations of thrust and flow with inlet conditions. Nonlinearities amounting to 5 percent in thrust or 8 percent in flow would be required to satisfy the observed thrust acceleration, which again does not appear probable.

The time period during which the discrepancy occurs corresponds to the period of maximum dynamic pressure and thus to maximum drag (figs. V-3 and 10). The cause of the observed discrepancy in the AC-2 analysis was considered by STL (ref. 14) to be an error in the drag model. They derived a new drag curve (fig. V-11) that eliminated the observed thrust acceleration deficiency. This same curve was satisfactory for the AC-3 trajectory reconstruction and provided a better fit for the AC-4 data.

The drag on a vehicle may be divided into two parts: (1) the drag due to the air flow over the forebody and (2) the drag associated with the base area. The forebody drag is a function of flight Mach number and dynamic pressure and was evaluated for the Atlas-Centaur in the Lewis Research Center 8- by 6-foot supersonic wind tunnel.

The base drag, however, is not only a function of the Mach number and dynamic pressure but also of the effects of the jet interaction and the resulting mass recirculation at the vehicle base (refs. 15 and 16). For this configuration, in a supersonic free-stream Mach number regime, the recirculation of mass is directly proportional to the ratio of the jet to ambient pressure. Therefore the base pressure force will be less (i.e., the base drag is greater) for an Atlas-Centaur vehicle flying at a lower altitude than for one flying at the same Mach number but at a higher altitude.

The AC-4 vehicle flew a lower altitude trajectory than did the AC-2 and the AC-3. It would be anticipated that the base drag should be somewhat greater for the AC-4 flight than for the AC-2 and the AC-3. Examination of the AC-4 thrust acceleration residuals (fig. V-7) shows that the use of the drag coefficients derived by STL for the higher altitude trajectory did result in the calculation of too small an apparent drag force. A new set of drag coefficients shown in figure V-11 as modified AC-4 was used and a satisfactory match was obtained.

Use of the modified drag coefficients in the reconstruction resulted in reducing the thrust attenuation factor from 1.006 to 1.004 and improved the specific impulse for the booster approximately 0.2 percent. These are relatively





small changes in performance parameters and the modified coefficients were therefore used in this analysis.

It is not possible at this time to determine if the error is solely due to base drag and not to the propulsion model or other unknown causes. The desired result, however, could be achieved by incorporating any nonlinear altitude-dependent aspects of the propulsion model with the base drag coefficients. The significance of this is that, if the base drag model remains predictable from flight to flight, the computed payload of an operational vehicle, for instance, AC-15, would be increased by approximately 45 pounds.

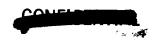


TABLE V-I. - PROPULSION PARAMETERS AS DERIVED BY TRAJECTORY RECONSTRUCTION

Stage	Parameter	Refe	Reference values ^a	lues ^a	Specific values ^b	values ^b
		Preflight	De	Derived	Preflight	Derived
			Ratio ^c	Value		
Booster	Thrust (sea level), lb Weight flow, lb/sec Specific impulse (sea level), sec Mixture ratio, O/F	309 000 1234.0 250.4 2.283	1.0040 1.0032 1.0008 1.0000	310 236.0 1238.0 250.6 2.283	306 083.6 1225.3 249.7 2.244	306 270.5 1225.6 249.9 2.215
Sustainer plus vernier	Thrust (sea level), lb Weight flow, lb/sec Specific impulse (sea level), sec Mixture ratio, O/F	59 000 275.1 214.4 2.270	1.0003 1.0003 1.0000	59 017.7 275.2 214.4 2.270	58 352.2 273.6 213.2 2.328	58 238.2 275.1 211.7 2.546
Centaurd	Thrust (vacuum), lb Weight flow, e lb/sec Specific impulse ^f (vacuum), sec Vehicle specific impulse, e sec Mixture ratio, f O/F	29 952.7 69.498 431.5 431.0 5.005	0.9976 .9955 1.0021 1.0021	29 880.8 69.185 432.4 431.9 5.005	29 952.7 69.498 431.5 431.0 5.005	30 206.8 70.166 431.0 f430.5 5.062

^aValues of the parameters specified for the propulsion models corrected to specified engine inlet conditions (appendix B of ref. 1, source of preflight data).

 $^{
m b}$ Uncorrected values at T + 4 sec for the Atlas stage and T + 300 sec for the Centaur stage. Ratio of derived to preflight nominal.

 $^{\rm d}\mathrm{Values}$ for combined C-1 and C-2 engines.

encludes minor flow of 0.103 lb/sec and associated thrust of 8.72 lb.

fvehicle specific impulse obtained from the slope method was 431.8 sec.



TABLE V-II. - TRAJECTORY PARAMETER COMPARISON

Parameter	BECOa	Insulation jettison	Nose-fairing jettison	SECO	Separationa	MES	MECO ^a			
		Tim	e from lift-of	f, ^b sec						
Planned ^C Actual Reconstruction	150.46 149.06 d149.06	200.36 198.47 198.47	214.36 212.38 212.38	226.36 224.25 224.25	228.96 226.65 226.65	235.96 233.87 d235.20	573.41 572.65 e573.09			
Altitude, n. mi.										
Planned Tracking ^f Reconstruction	30.102 30.425 30.398	52.566 53.033 53.028	58.127 58.607 58.597	62.704 63.146 63.137	63.666 64.037 64.028	66.121 66.602 67.013	90.791 90.990 90.998			
Range, n. mi.										
Planned Tracking Reconstruction	44.950 43.666 43.703	112.93 110.494 110.509	134.67 131.928 131.944	154.410 151.292 151.312	158.80 155.315 155.338	170.62 167.407 169.676	1039.270 1035.055 1036.778			
		Rela	ative velocity	g ft/sec						
Planned Tracking Reconstruction	8099 8070 8069	9622 9561 9559	10 168 10 106 10 096	10 704 10 618 10 622	10 694 10 611 10 622	10 650 10 567 10 569	24 267 24 254 24 284			
		Ine	rtial velocity	, ft/sec						
Planned Tracking Reconstruction	9343 9307 9306	10 916 10 852 10 850	11 471 11 409 11 397	12 014 11 926 11 930	12 004 11 921 11 931	11 966 11 881 11 884	25 607 25 596 25 625			
			Axial load fac	tor, g						
Planned Tracking Reconstruction	5.520 h _{5.49} 5.523	1.383 1.38 1.370	1.510 1.51 1.497	1.672 1.65 1.656	0.004	0	2.316 2.33 2.340			

aReferenced to beginning of thrust decay or weight separation. bTime from 2-in. motion (0925:02:548 EST).

CRef. 1.

dEffective time compatible with the transient model used in reconstruction.

eTime compatible with guidance simulation model.

fData from best estimate of trajectory (ref. 10).

gVelocity relative to the Earth.

hAccelerometer (CM101A) indicated 5.52 g's maximum at 149.06 sec from 2-in. motion (ref. 2).



TABLE V-III. - ORBITAL PARAMETERS

Parameter	Preflight ^a	Postflight ^b
Time of injection ^C Perigee altitude, ^d n. mi. Eccentricity Semimajor axis, n. mi. Period, min Inclination, deg Longitude of ascending node, ^e deg Argument of perigee, ^f deg	573.56 88.9067 0.000461 3534.536 87.845 30.7303 243.983 116.865	572.7 88.1341 0.00095 3535.493 87.86 30.69 243.96 179.5

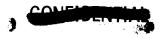
aData obtained from ref. 1.

TABLE V-IV. - WEIGHT SUMMARY FOR TRAJECTORY ANALYSIS

Weight, 1b	Preflight estimate ^a	Postflight estimate ^b	Trajectory reconstruction
Total at lift-off At BECO Booster, wet Insulation jettison Nose fairing Total at SECO Total at separation Sustainer, wet Unburned Atlas propellant at SECO Centaur at lift-offe Boost-phase vent Boost-phase jettison Centaur at separation At MECOe Centaur, wet plus payload Unburned Centaur propellants Payload (simulated mass)	304 002 79 399 7 410 1 219 1 990 48 204 48 165 9 006 2 781 39 698 71 3209 36 418 12 932 7 166 5 766 2 091	303 243 7 357 1 278 2 052 48 672 9 028 3 401 39 741 168 3 330 36 243 12 713 7 155 5 558 2 090	302 958 79 905 d7 357 d1 278 d2 052 48 724 48 684 d9 028 3 409 d39 741 d168 d3 330 d36 243 12 794 d7 155 5 639 d2 090

aAppendix B of ref. 1.

eIncludes payload weight.



bData obtained from ref. 2.

CTime from 2-in. motion (from 0925:02:548 EST).

 $d_{Measured}$ above spherical Earth, R_{O} = 3444 n. mi.

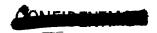
eMeasured East from launch meridian.

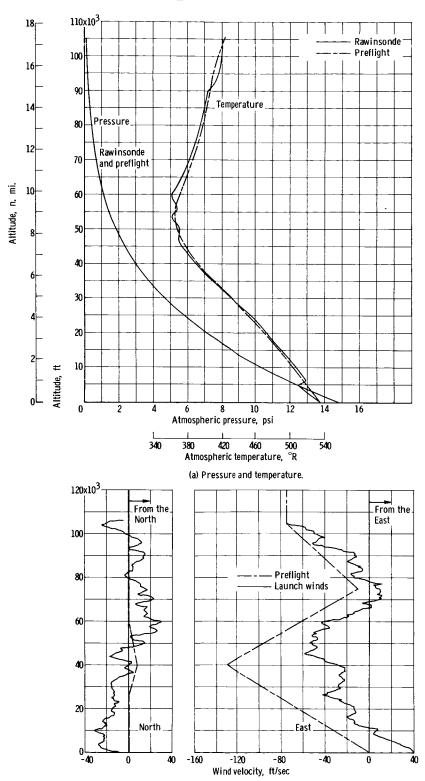
fMeasured in direction of motion from ascending node.

bData from section II.

^cDry hardware weight plus residuals (not including unburned propellant).

dAssumed for purposes of reconstruction.

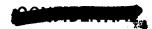


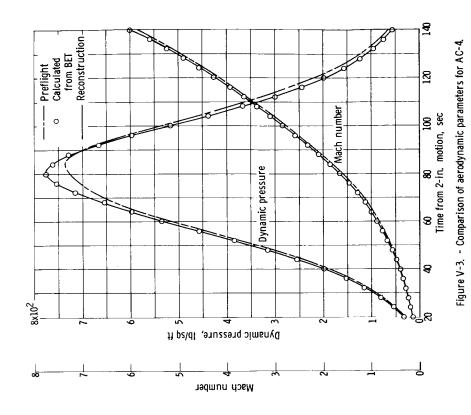


(b) Wind components.

Figure V-1. - Atmospheric conditions at time of launch. Rawinsonde run 1594 at 9:05 EST, December 11, 1964.







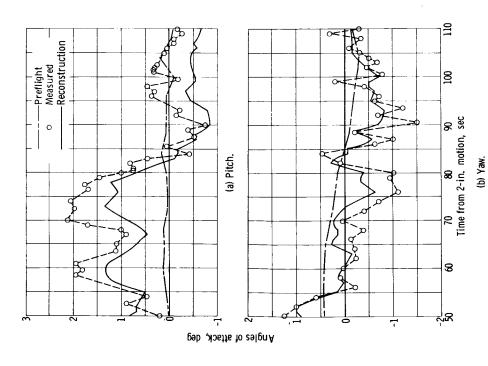


Figure V-2. - Comparison of pitch and yaw angles of attack.





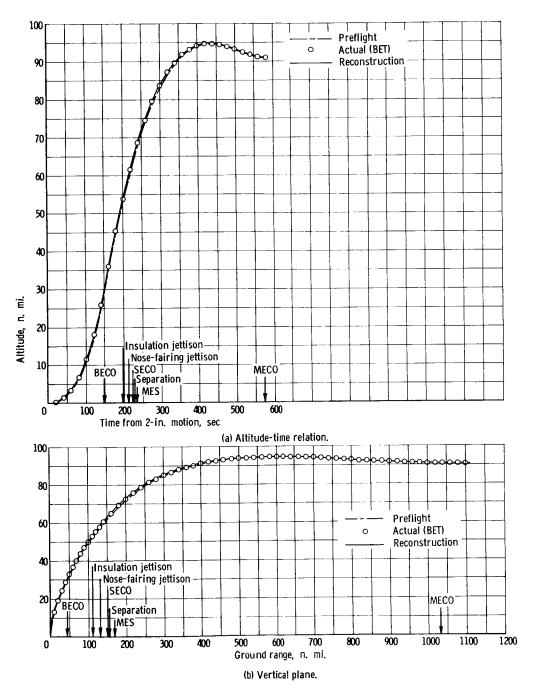


Figure V-4. - Trajectory position comparison.





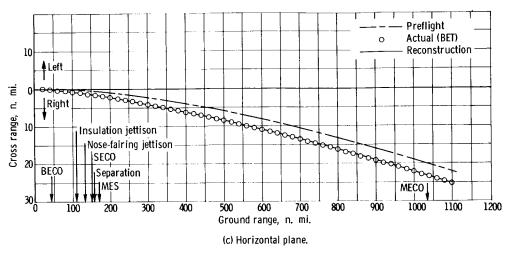


Figure V-4, - Concluded.

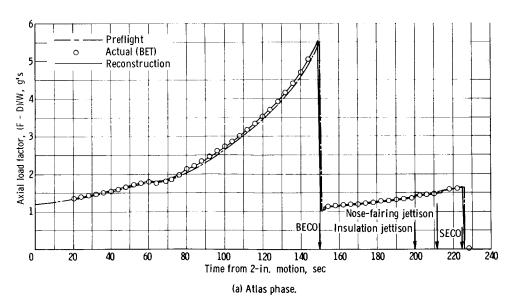
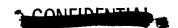


Figure V-5. - Trajectory comparison. Thrust acceleration (axial load factor).





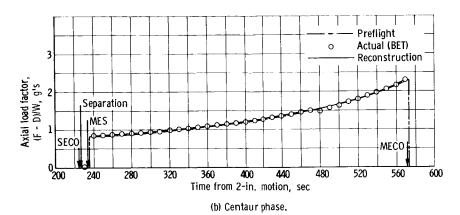


Figure V-5. - Concluded.

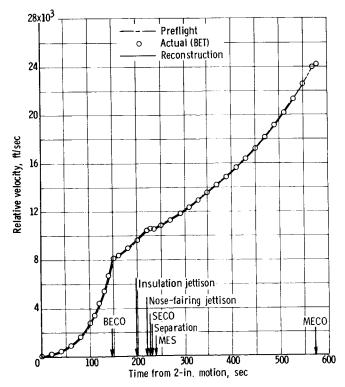


Figure V-6. - Trajectory comparison. Velocity relative to atmosphere including wind effects.





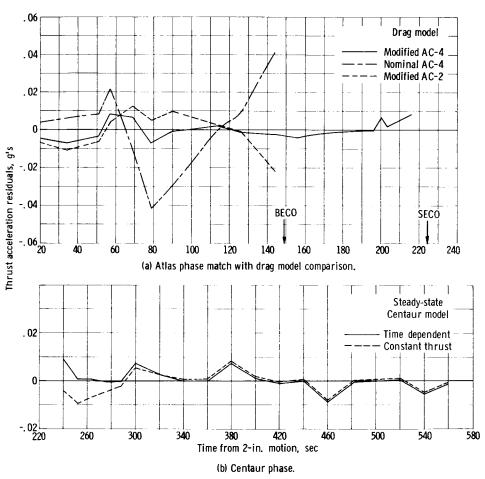
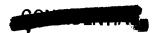


Figure V-7. – Thrust acceleration residuals (computed minus tracking) from AC-4 trajectory reconstruction.



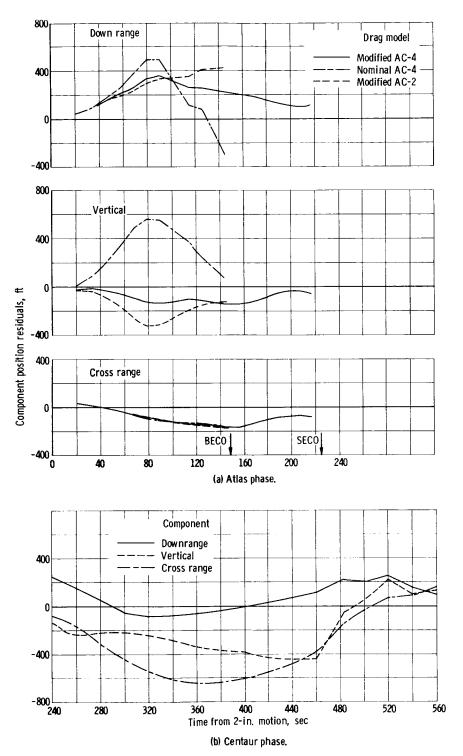
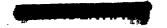


Figure V-8. - Component position residuals (computed minus tracking) for AC-4.





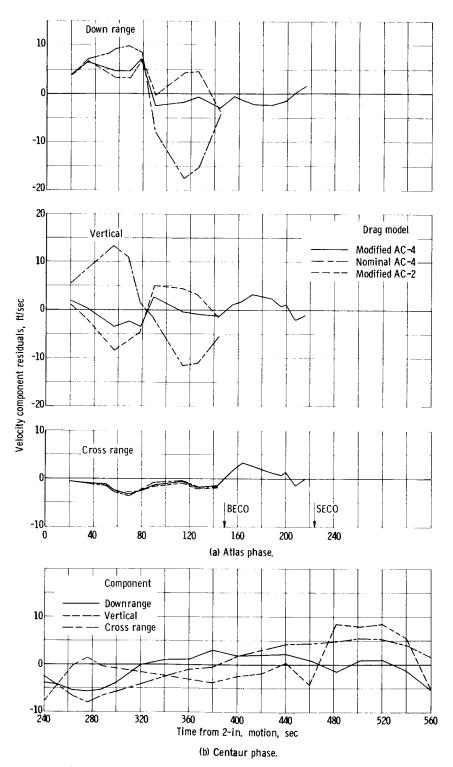
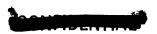


Figure V-9. - Component velocity residuals (computed minus tracking) for AC-4.



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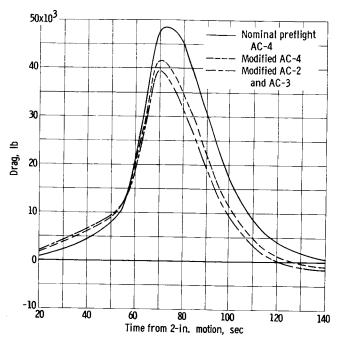


Figure V-10. - Comparison of drag computed with various drag coefficients and AC-4 BET data.

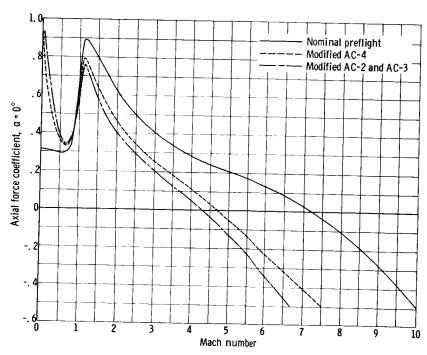


Figure V-11. - Comparison of drag curves used in AC-4 trajectory reconstruction.



VI. PROPULSION

SUMMARY

Atlas performance was almost as predicted throughout the booster phase of flight. The propulsion system operated satisfactorily during the Centaur first burn, but Centaur second burn was not obtained as planned.

ATLAS

Performance of the Atlas propulsion system in terms of thrust, specific impulse and mixture ratio at lift-off, booster engine cutoff, and sustainer engine cutoff is given in table VI-I. The DEPRO program (see appendix C) prediction is compared with values obtained using the DEPRO program based on flight data. The primary cause of values differing from those predicted is attributed to the different setting of the PU system. Previous Centaur boosters had been orificed to provide a mixture ratio of 2.359, whereas AC-4 (Atlas 146D) was orificed to 2.28. The PU valve positions were 1.80 below the nominal 26.70 setting at lift-off and 5.10 low (closed limit) at both BECO and SECO. Other factors causing values to be different from predicted are data inaccuracy and 146D having slightly hot boosters. All other Atlas propulsion values were nominal.

CENTAUR

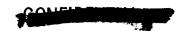
Centaur first burn was obtained as planned. AC-4 was the first Centaur flight utilizing a pre-SECO boost-pump start and a reduced-power fuel boost pump. The hydraulic system modifications incorporated since AC-3 proved to be adequate.

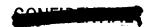
Although the ullage settling rockets fired as planned during the coast phase and the attitude control system functioned properly, the effect of vehicle tumbling and the lack of fuel at the boost-pump inlet prevented the second burn from being obtained as programed.

All valves actuated properly for the Centaur reorientation and retromaneuver; however, this experiment lost its effect because of vehicle tumbling.

MAIN ENGINES

Main engine performance during the start-transient, steady-state, and shut-down periods for the first burn were satisfactory. Performance compared favorably with acceptance and ground testing and with previous flight data.





The chamber pressure and pump inlet conditions during the start-transient period were normal and are illustrated in figures VI-1 to 3. The start total impulse (valued up to 90 percent of rated thrust) for the C-1 and C-2 engines was 3840 and 3900 pound-seconds, respectively.

Steady-state values in terms of thrust, specific impulse, and mixture ratio are listed in table VI-II. Off-nominal values in the Lewis method for determining performance are a result of the sensitivity of this method, data accuracy, and accuracy of some of the engine constants. Specification requirements for the engine are 15 000±300 pounds for thrust, 430 seconds for specific impulse (nominal), and 5.0±2.00 percent for mixture ratio. Engine measurements obtained during steady-state operation and nominal operating values are shown in table VI-III.

At main engine cutoff (MECO), the chamber pressure for both engines started to drop simultaneously. Both engines required approximately 0.04 second to reach 5 percent of rated thrust, which is well within the normal differential impulse shutdown range.

Figures VI-4 and 5 illustrate fuel and LOX pump housing temperatures, respectively, from lift-off through the first orbit. The temperature variations noted between the C-1 and C-2 engines are characteristic; however, the magnitude of the temperature difference for both the fuel and LOX pumps appears to be greater during the first burn than that experienced on previous flights. There is no apparent reason for the increase in temperature differential of the two engines. Figure VI-6 illustrates the turbopump skin temperature during the first burn and also indicates that the C-2 engine is warmer.

Thrust chamber skin temperatures from lift-off through the first orbit are illustrated in figure VI-7.

For the attempted second-burn portion of flight, the C-l chamber pressure started to rise at MES + 0.25 second and the C-2 engine at 3.7 seconds. rise in chamber pressure indicates that the engines ignited and burned at a very low level. The chamber pressure for both engines never exceeded 10 psia. cause of the longer time lag for ignition of the C-2 engine, the differential pressure across the turbine was sufficient to rotate the turbopump. hydraulic pressure momentarily reached a normal operating level during this time period. The lack of fuel at the pump inlet did not allow the engines to develop rated thrust. Second-burn operating conditions are given in table The fuel-pump-housing and thrust-chamber-skin temperatures were within engine specification requirements prior to second MES. The engine specification requires that the fuel-pump-housing temperature be 150° R or lower and the thrust-chamber-skin temperature be above 300° R. Figures VI-4(b) and 7(b) illustrate the flight temperatures prior to the second burn. Temperature excursions noted for the second burn, the retromaneuver, and the subsequent times followed engine programed activity.

BOOST PUMPS

AC-4 was the first Centaur flight that utilized a pre-SECO boost-pump start



in support of the first main-engine start sequence. Resulting flight data indicated that this sequence is entirely satisfactory with no detrimental effects on boost-pump or engine performance. This was also the first Centaur flight in which a reduced-power fuel boost pump was used. The fuel unit flown was orificed to operate at a steady-state turbine speed of 45 955 rpm with a corresponding headrise of 15.15 psid.

The LOX boost pump was orificed to provide 27.3 psid headrise with a corresponding steady-state turbine speed of 32 580 rpm.

The first-burn start sequence was very close to the planned times with the boost-pump-start signal initiated 16.2 seconds prior to SECO. The time from boost-pump start to prestart was 19.8 seconds, and from boost-pump start to main-engine start was 25.8 seconds. Flight data indicated a normal start and acceleration of both LOX and fuel boost pumps. Except for CP28P (fuel-boost-pump turbine nozzlebox pressure) the time from start signal to first indication of gas-generator and nozzlebox pressures was approximately 0.8 second for both the LOX and fuel boost pumps. CP28P failed to rise until 9 seconds after the start signal. The delay is attributed to a failure of the transducer since the upstream gas-generator pressure, headrise, and turbine speed rose immediately.

First-burn performance data are presented in table VI-V, together with the steady-state acceptance data for comparison purposes. The fuel-boost-pump turbine speed appears to be approximately 900 rpm higher than expected. not correlate with the flight headrise data, which show a value slightly lower than the acceptance test value. With a higher turbine speed, the headrise should be correspondingly higher. These differences are the result of inaccuracies involved in interpreting the data. Fuel-boost-pump gas-generator and nozzlebox pressures were normal with minor oscillations less than ±10 psia peak LOX-boost-pump gas-generator and nozzlebox pressures were slightly lower than the acceptance values, but had no significant effect on performance. These values were expected to be slightly low in flight because of an error during the acceptance test in which a hydrogen peroxide inlet pressure of 309 psia was used instead of the nominal inflight value of 296 psia. Preflight predictions estimated a reduction of nozzlebox pressure of approximately 3 psi and a corresponding reduction in LOX-boost-pump headrise of 1 to 1.5 psid. Minor oscillations of less than ±10 psi were also noted on the LOX-boost-pump gasgenerator and nozzlebox pressures, with no noticeable effect on performance.

Following first MECO, the fuel-boost-pump headrise essentially decayed to zero for 2 seconds before ΔP was reestablished, and normal decay resumed during coastdown of the boost pump (see fig. VI-8). Simultaneously with headrise going to zero, the turbine speed trace flattens out to a constant value (see fig. VI-9). This phenomenon has been noted on previous flights as well as in ground tests and is attributed to a combination "water-hammer" effect, due to sudden valve closing downstream, and backflow of gaseous and/or liquid hydrogen through the boost pump. The backflow through the boost pump is believed to be a result of relieving the high-pressure liquid hydrogen downstream of the mainengine fuel pump after the main fuel shutoff valve closes at MECO. The valve sequencing is such that the engine inlet valve remains open for approximately 0.4 second after MECO. Turbine speed coastdown for the LOX boost pump was l15 seconds, and became linear at approximately MECO + 20 seconds, which



corresponds with the time that LOX-boost-pump headrise becomes zero (approx. MECO + 19 sec).

Turbine speed coastdown for the fuel boost pump was 65 seconds, and became linear at approximately MECO + 20 seconds, which again corresponds with the time that fuel-boost-pump headrise goes to zero (MECO + 20 sec). It is felt that this phenomenon is due to loss of liquid at the boost-pump inlet under zero-gravity conditions and is of no significance provided adequate thrust is available to resettle the propellants prior to the second start attempt. Calculations were made which indicate that approximately 20 pounds of liquid hydrogen were pumped through the boost-pump volute bypass line during the post-MECO coastdown. This contributed to the propellant disturbances within the fuel tank during the coast phase.

During the coast phase, at lift-off + 610 seconds, the fuel-boost-pump turbine nozzle temperature transducer (CP29T) failed completely. The fuel-boost-pump discharge temperature (CP884T) began a gradual rise and eventually went off scale (high) indicating gaseous hydrogen in the propellant ducts. This was anticipated prior to flight, and 35 seconds of boost-pump deadhead operation were programed at the second start to ensure liquid in the ducts.

The fuel-boost-pump electrical-distribution-box and control-valve temperatures (CP336T and CP337T, respectively) went off scale (high) sometime after lift-off + 1080 seconds at a time when there was no telemetry coverage. (Schematic drawings of the fuel-boost-pump and oxidizer systems are shown in fig. VI-10.) The upper range capabilities of these transducers were 147.1° and 146.9° F, respectively. The temperature limit for the electrical distribution box is specified at 200° F maximum. The maximum operating temperature for the valve is specified at 160° F. The electrical distribution box is not considered a problem, but the valve temperature must be evaluated for future two-burn missions, since the maximum specification limit for hydrogen peroxide is 140° F. It should be noted, however, that the AC-4 second boost-pump start showed a normal gas-generator and nozzlebox pressure rise for both LOX and fuel with no indications of a vapor lock condition.

Second boost-pump start was initiated at lift-off + 2010.1±0.5 seconds followed by prestart at 2044.8 seconds and main-engine start signal at 2049.8 seconds.

The first indication of gas-generator and nozzlebox pressures was 0.6 and 0.2 second for the LOX and fuel boost pumps, respectively. Oscillations of ±20 psi were noted in the LOX-boost-pump gas generator, beginning at BPS + 32 seconds and continuing until cutoff. Similar oscillations of ±15 psi were evident in the LOX nozzlebox pressure, beginning at BPS + 32 seconds but ending at BPS + 55 seconds. Oscillations occurred in the fuel-boost-pump gas-generator and nozzlebox pressures (approx. ±20 psi) from BPS until over-speed trip-out occurred. Oscillations of similar magnitudes have been observed on several ground tests with no detrimental effects on boost-pump performance. The LOX boost pump started and operated successfully during the second-burn attempt (see table VI-VI).

The fuel-boost-pump performance for the attempted second start was not





normal. A detailed explanation is given in section XV. <u>COAST-PHASE PROPELLANT</u> AND VEHICLE BEHAVIOR.

HYDRAULIC SYSTEM PERFORMANCE

The analysis of data obtained from the AC-3 C-1 engine hydraulic system failure strongly indicated that the system remained intact and that the prime suspect trouble area was that of the interface between the RL-10 engine and the hydraulic power package. Schematic drawings of the AC-3 Centaur hydraulic system and the modified AC-4 system are shown in figure VI-11.

The hydraulic power package main pump assembly is driven by the engine LOX turbopump drive shaft, which is near liquid-hydrogen temperature during engine operation and prelaunch liquid-helium chilldown. The drive coupling interface therefore must provide an adequate thermal barrier through all phases of prelaunch and flight so that the hydraulic system temperature remains above -30° F at all times. The most significant failure modes that could have caused the hydraulic system loss are

- (1) Excessive cooling of the nylon drive coupling
- (2) Pump or pump shaft failure
- (3) Large-particle contamination of the pump
- (4) Engine accessory drive failure
- (5) Interface structural failure

Redesign of the hydraulic system and the new preflight testing program philosophy have been adapted to eliminate completely the possible failure modes. The redesigned system encompasses the following additions and changes:

- (1) Incorporation of ambient helium gas purges to the accessory drive cavity of the engine and the coupling area between the power package main pump and the open hydraulic power package adapter
- (2) Incorporation of a metallic bellows coupling to replace the nylon coupling; this new coupling provides greater flexibility, thermal isolation, and shielding between the engine drive and the power package
- (3) Incorporation of an open adapter to disperse any leakage from the hydraulic or engine system
- (4) Incorporation of a return line and main pump inlet filters
- (5) Incorporation of a main pump with a larger shaft and a face-type seal
- (6) Incorporation of a phenolic insulation block with more uniform distribution of expected loads



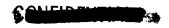


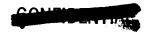
Associated changes were made to the remaining portions of the system to adapt to the modifications, but for the most part the basic schematic representation is the same as shown in figure VI-ll(b).

Evaluation of the data received from the AC-4 flight shows that both C-1 and C-2 hydraulic systems operated properly. Full system pressure was achieved in 1.5 seconds on both systems and held steady throughout main engine burn (figs. VI-12 and 13). At SECO + 0.1 second, the circulation systems of C-1 and C-2 engine hydraulics came up to their proper values. The C-1 and C-2 pressures were 111 and 110 psia, respectively. Both engines moved to null under circulation system power at a rate of approximately 0.3 degree per second. From SECO + 0.1 to MES + O second, the pressure profiles and the pitch and yaw feedbacks were quite similar to those of AC-2 and AC-3. Thrust buildup and the associated rate transients were such that, at MES + 4 seconds, the vehicle attitude was very close to that required by guidance when it was readmitted. Consequently, engine gimbal requirement and hydraulic demand were very low. The usual dip in pressure at MES + 4 seconds was nonexistent. C-1 and C-2 mainsystem pressures were steady at 1167 and 1188 psia, respectively.

The ambient helium purges to the accessory drive and coupling cavities during liquid helium ground chilldown were effective in thermally isolating the power packages from the engine accessory drive pad. Temperatures of the oil in the power packages and manifolds were maintained at 70° F prior to lift-off. The expected drop in temperatures through booster phase and the subsequent rise during engine operation were realized equally on both systems: the minimum and maximum were 60° and 155° F, respectively. The only discrepancy at this point of operation can be seen on the traces of hydraulic power package adapter temperatures as a function of time (fig. VI-12). The temperature drop of the C-1 adapter was more rapid than that of the C-2, and it is suspected that this was caused by a cooler C-1 engine or greater dynamic seal leakage from the accessory cavity of the engine. In any event, this temperature discrepancy was not reflected to the power package indicating that thermal isolation in space was adequately effective through coast and the second main-engine start. At mainengine cutoff, the manifold temperatures were as expected and approximately 250 higher than those of the power package pump discharge (fig. VI-14). temperatures of the power packages and manifolds throughout coast were above Therefore, thermostatic activation of the recirculation pump was not 80° F. commanded.

Temperature profiles of the power packages and the manifolds showed a dipping and separation at approximately T + 1260 seconds. An associated engine movement without hydraulic power occurred at this same point of flight. Engine movements (fig. VI-15) were more pronounced in pitch to the toed-in position and can be attributed to the predominance of tumble and acceleration forces that resulted. Manifold temperature profile separation, which started at this same time, is attributed possibly to the movement of hydraulic fluid by the actuator pistons. These combined with the effect of sun radiation and manifold shading due to vehicle tumble and roll provide the only positive explanation at





this time. Other heating or cooling environments near either manifold could also cause such a temperature dispersion, but no evidence of any extraneous source exists at this time.

ATTITUDE CONTROL AND HYDROGEN PEROXIDE SYSTEMS

A schematic diagram of the attitude control and ${\rm H}_{\rm 2}{\rm O}_{\rm 2}$ supply systems is shown in figure VI-16. The H2O2 system temperatures were normal during the first portion of the flight (fig. VI-17). The abrupt temperature change in the two fuel supply lines at T - 194 seconds was caused by pressurizing the bottle. Normally, any change at this time would be an increase in temperature caused by warmer H2O2 from the bottle entering the lines. A possible explanation for the drop in the P-2 fuel-supply-line temperature is that the line was not completely purged prior to pressurization, and when the system was pressurized, colder H2O2 in the upstream line moved to the location of the temperature probe. in all temperatures at lift-off is the result of discontinuing the ground air conditioning at this time. The temperature rise in both cluster manifolds at approximately T + 75 seconds is attributed to aerodynamic heating. Both fuelsupply-line temperatures increased after first MECO because of H2O2 flow in the lines as the attitude control and ullage settling engines were fired. after T + 1300 seconds, the P-2 cluster manifold temperature decreased sharply. Since flight data show that H2O2 is flowing to this cluster almost constantly during this period, there is no reason for a temperature drop. Therefore, it is assumed that the temperature patch separated from the manifold and came close to the tank bulkhead. The P-1 cluster manifold temperature went off scale (high) some time after T + 2340 seconds. This is attributed to instrumentation failure since there is no change in system operation before or after this time.

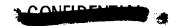
Figure VI-18 shows the combustion chamber temperatures on the ullage control engines. These temperatures are considered inaccurate from a quantitative standpoint. Their prime purpose was to confirm ullage engine firing. The sharp increase in temperature at first MECO and decrease after second MES show that the engines operated as programed.

The $\rm H_2O_2$ bottle pneumatic pressure was normal throughout the flight (fig. VI-19). After pressurizing the bottle on the ground, the pressure remained at 317 psia until the boost pumps started at T + 208 seconds when the pressure dropped to about 302 psia. This drop is normal and is explained by the fact that the bottle pressure regulator is referenced to ambient pressure and is set to give a nominal pressure of 300 psia in space. Therefore, it will regulate to a nominal 315 psia on the ground and will gradually decrease as the vehicle rises. The bottle pressure did not drop gradually because a check valve between the regulator and the bottle traps the initial pressure in the bottle until $\rm H_{2O_2}$ is first used at boost-pump start. The pressure remained at approximately 302 psia for the remainder of the flight.

Data that indicate attitude control engine firing times are shown in figure VI-20. Figures VI-20(a) to (b-3) show A-3 and A-4 engines firing with an almost constant duty cycle of 0.9 second on and 1.7 seconds off from shortly after first MECO to first MECO + 267 seconds. There are several possibilities or combinations of possibilities that could have caused this yaw error. If the

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propellants moved to the forward end of the tank after MECO, the center of gravity of the vehicle would move forward and the ullage control engines could create a couple about the center of gravity. A second possible cause could be exhaust gas impingement from the ullage control engines on the main engines. Another cause could be a leak in any pressure line on the vehicle. At first MECO + 267 seconds when the LH2 tank started venting, the A-3 and A-4 engines remained on almost constantly until sometime after MECO + 484 seconds (area of no data coverage). It is evident that the venting of LH2 caused a yaw torque on the vehicle above the recovery capability of the attitude control engines. By MECO + 784 seconds, the error had changed to a pitch-roll-yaw error, and the P-1 and A-3 engines came on and remained on for most of the remaining portion of flight. This type of error is attributed to a differential thrust from the two exhaust ducts of the LH2 vent valve (see section VII. CENTAUR PROPELLANT SYSTEMS).



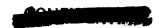


TABLE VI-I. - ATLAS PERFORMANCE - DEPRO PROGRAM^a

	Flight value	Predicted value
Thrust at]	ift-off + 10 sec	conds, lb
Boosters Sustainer Verniers, axial	307 320 56 600 1 710	306 940 56 650 1 710
Total	365 630	365 300
Th	rust at BECO, 11	
Boosters Sustainer Verniers, axial	357 810 79 710 1 970	356 600 7 9 760 1 970
Total	439 490	438 330
Th	rust at SECO, 11)
Sustainer Verniers, axial	76 910 1 460	79 100 1 460
Total	78 370	80 560
Specific i	mpulse at lift-c	off, sec
Boosters Sustainer	250.1 216.1	250.4 207.2
Total	244.5	243.6
Specific	impulse at BECC	, sec
Booster Sustainer	287.7 302.3	288.1 297.8
Total	289.9	291.4
Specific	impulse at SECC	, sec
Total	295.7	303.2
LO	X to fuel ratio	
Lift-off BECO SECO	2.321 2.356 2.035	2. 240 2. 336 2. 228

a See appendix C for explanation.

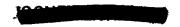




TABLE VI-II. - CENTAUR PERFORMANCEa

(a) C-1 engine (1847)

	Acceptance			Tir	ne from	MES, se	ec		
	test, P _c = 293.5	5	50	100	150	200	250	300	338
Thrust, 1b Lewis Venturi PWA Regression PWA C*	14 990	15 021	14 949	14 954	14 725 14 882 14 948	14 880	14 881	14 890	14 882
Specific impulse, sec Lewis Venturi PWA Regression PWA C*	432.0	425.3 430.4 431.3	431.6	431.6	432.8		432.8		424.5 432.8 431.1
Mixture ratio Lewis Venturi PWA Regression PWA C*	4.97	4.977 5.212 5.040		5.059	4.893	4.890	5.054 4.893 5.094	5.036 4.913 5.093	5.018 4.898 5.073

(b) C-2 engine (1858)

	Acceptance test,			Tiı	me from	MES, se	ec		
	$P_c = 299.3$	5	50	100	150	200	250	300	338
Thrust, 1b Lewis Venturi PWA Regression PWA C*	15 018	15 087	15 048	15 046	14 965	14 952 14 957 15 071	14 956	14 959	14 955
Specific impulse, sec Lewis Venturi PWA Regression PWA C*	431.0	419.9 429.8 433.8	430.4	430.5	431.9	432.0		1	
Mixture ratio Lewis Venturi PWA Regression PWA C*	5.0	4.985 5.157 4.656	5.074	5.067	4.882	4.867	4.868	4.875	1

^aSee appendix C for explanation of techniques.

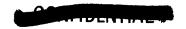




TABLE VI-III. - CENTAUR ENGINE STEADY-STATE OPERATING CONDITIONS

	Nominal	MES + 50 sec	MES + 338 sec
C-1	engine	<u></u>	l <u> </u>
LH ₂ pump total inlet pressure, psia LH ₂ pump inlet temperature, ^O R LOX pump total inlet pressure, psia LOX pump inlet temperature, ^O R LOX pump speed, rpm LOX pump discharge pressure, psia LH ₂ pump discharge pressure, psia Fuel Venturi upstream pressure, psia Turbine inlet temperature, ^O R Chamber pressure, psia	38.4 38.8 59.8 176.6 11 350 464 922 649 331 293.5	33.85 39.2 58.6 177.0 446 892 659.8 340.3 291.7	31.76 36.7 58.8 174.8 11 040 438 875 655.0 335.1
, -	engine		
LH ₂ pump total inlet pressure, psia LH ₂ pump inlet temperature, ^O R LOX pump total inlet pressure, psia LOX pump inlet temperature, ^O R LOX pump speed, rpm LOX pump discharge pressure, psia LH ₂ pump discharge pressure, psia Fuel Venturi upstream pressure, psia Turbine inlet temperature, ^O R Chamber pressure, psia	38.4 38.8 59.8 176.6 11 350 464 922 649 331 299.3	35.75 37.35 59.6 177.2 438 920 688.2 338.0 302.0	33.29 36.8 57.6 175.0 11 390 438 937 683.8 339.7 296.3





TABLE VI-IV. - CENTAUR SECOND-BURN OPERATING CONDITIONS

		Time,	sec	
	MES	+ 5	+30	+50
C-l en	gine			
LH ₂ pump inlet pressure, psia LH ₂ pump inlet temperature, ^O R LOX pump inlet pressure, psia LOX pump inlet temperature, ^O R Turbine inlet temperature, ^O R Chamber pressure, psia	15.7 108.0 275 0	505 8.0	14.9 ~37.5 108.4 ~177 505 7.2	14.4 108.4 505 7.2
C-2 en	gine		I	
LH ₂ pump inlet pressure, psia LH ₂ pump inlet temperature, ^O R LOX pump inlet pressure, psia LOX pump inlet temperature, ^O R Turbine inlet temperature, ^O R Chamber pressure, psia	15.8 113.3 260 0	15.6 108.8 505 9.9	15.0 37.5 109.0 ~177 505 7.0	14.5 108.8 505 5.8



				<u></u>
MECO ^b Initial acceptance test (steady state)		45 955 153.5 136.5 15.15		32 580 107.0 95.0 27.3
MECOP		46 830 152.1 141.9 14.9		32 500 c100.9 c112.5 26.2
MES + 60 seca	dwnd	46 650 151.6 	st pump	32 000 100.1 90.0 25.7
MESa	Fuel boost pump	47 950 149.6 140.0 22.9	Oxidizer boost pump	36 555 98.1 85.0 64.9
Prestarta	Fu	49 650 148.6 140.0 24.95	Oxid	37 705 97.1 84.4 66.9
Parameter		Turbine speed, rpm Gas-generator pressure, psia Nozzlebox pressure, psia Headrise, psid		Turbine speed, rpm Gas-generator pressure, psia Nozzlebox pressure, psia Headrise, psid

anata source, TEL II replay and Grand Bahama Island.

Data source, Antigua.

TABLE VI-VI. - AC-4 SECOND-BURN LOX-BOOST-FUMP PERFORMANCE®

Parameter	Prestart	MES	MECO
Oxidizer	Oxidizer boost pump		
Speed, rpm Gas-generator pressure, psia Nozzlebox pressure, psia Headrise, psid	37 890 b92.5 92.3 76.2	37 440 b96.5 92.3	38 140 b96.5 94.5

Chata are questionable; nozzlebox pressure cannot exceed gas-generator pressure.

afuel boost pump cavitated prior to prestart.

Data are questionable; do not correlate with turbine speed, nozzlebox pressure, and headrise.



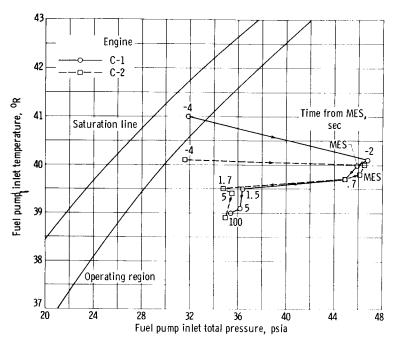


Figure VI-1. - Fuel pump inlet conditions near engine start.

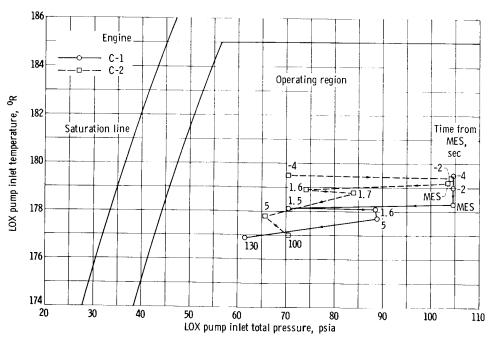
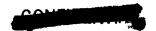


Figure VI-2. - LOX pump inlet conditions near engine start.



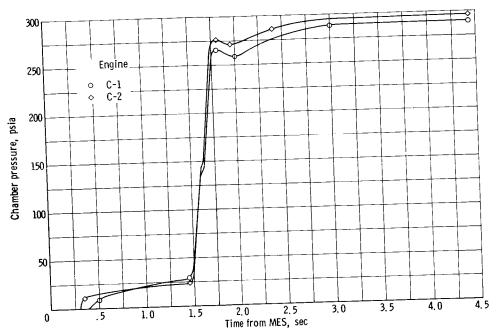


Figure VI-3. - Start transient chamber pressure.



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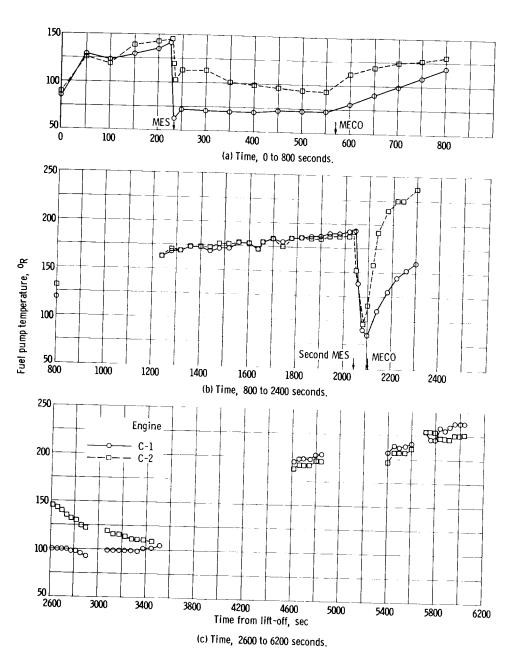
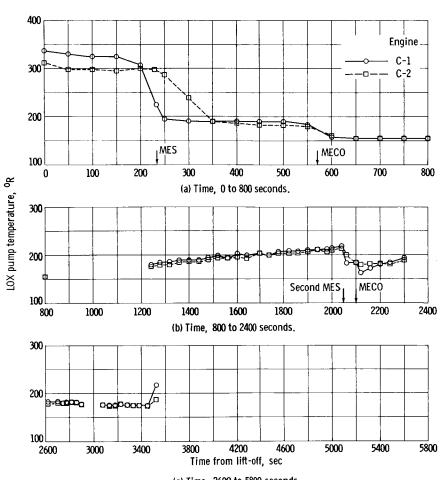


Figure VI-4. - Fuel pump housing temperature.





(c) Time, 2600 to 5800 seconds.

Figure VI-5. - LOX pump housing temperature.





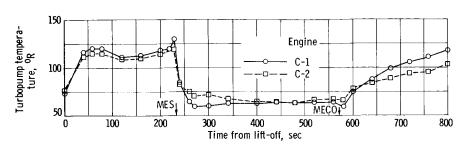


Figure VI-6. - Turbopump housing temperature.

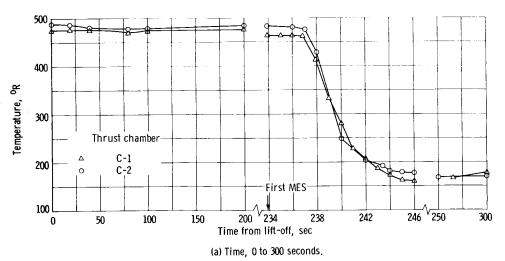
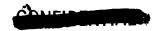


Figure VI-7. - Thrust chamber skin temperature.





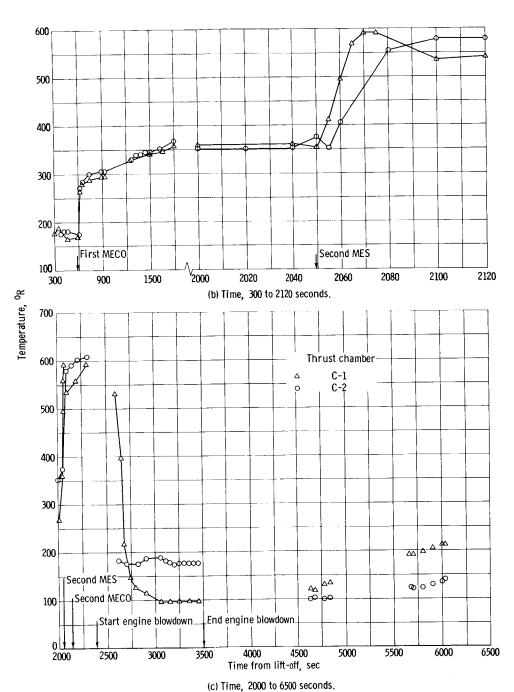
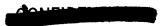


Figure VI-7. - Concluded.



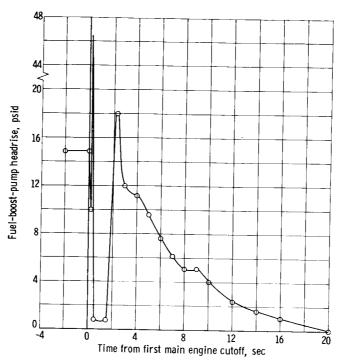


Figure VI-8. - Fuel-boost-pump headrise decay after first main engine cutoff.

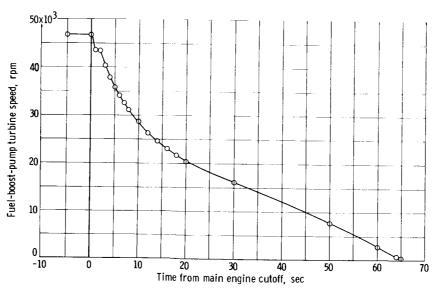
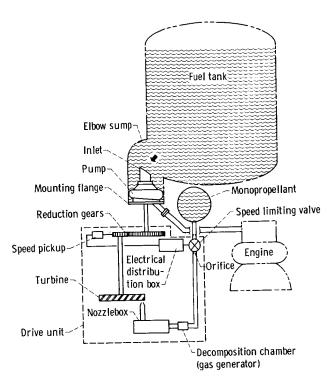


Figure VI-9. - Fuel boost pump turbine speed tail-off after MECO.





(a) Fuel system.

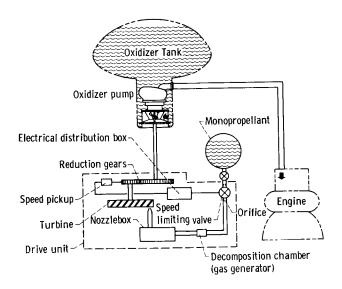
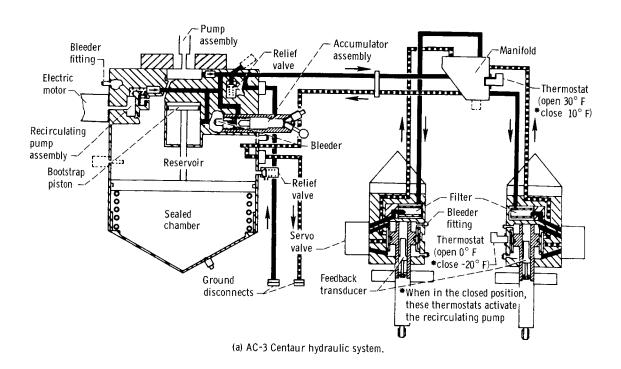
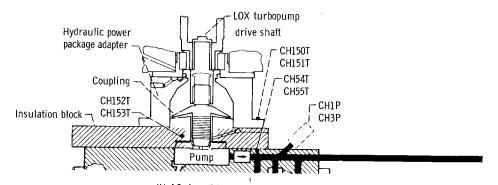


Figure VI-10. - Fuel-boost-pump system and oxidizer system schematic drawings.

(b) Oxidizer system.







(b) AC-4 modified Centaur hydraulic system.

Figure VI-11. - Schematic drawing of AC-3 Centaur hydraulic system and AC-4 modified hydraulic system.



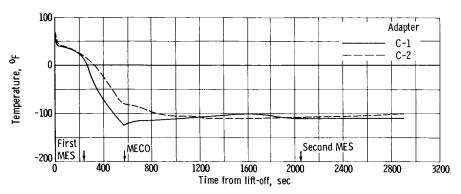


Figure VI-12. - Hydraulic power package adapter temperature.

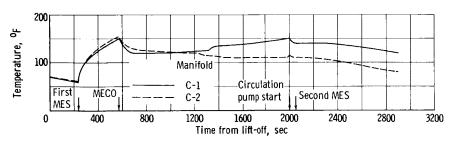


Figure VI-13. - Hydraulic manifold temperature.



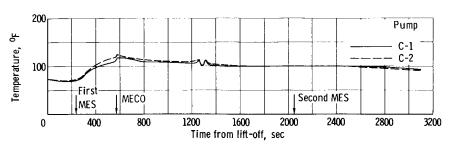


Figure VI-14. - Hydraulic power package pump discharge temperature.

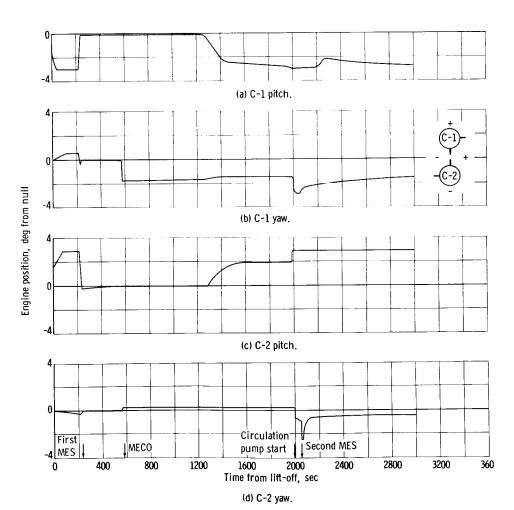


Figure VI-15. - Engine positions.



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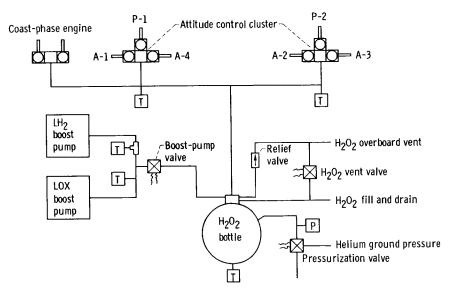


Figure VI-16. - Attitude control and hydrogen peroxide supply systems.

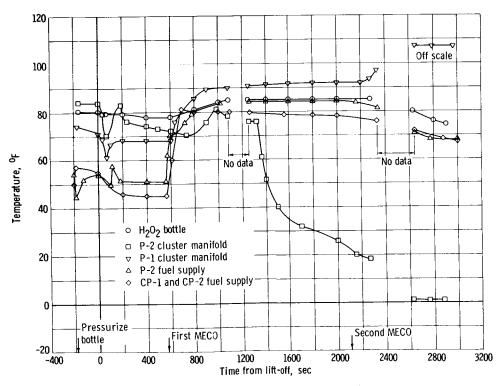


Figure VI-17. - Hydrogen peroxide system temperatures.





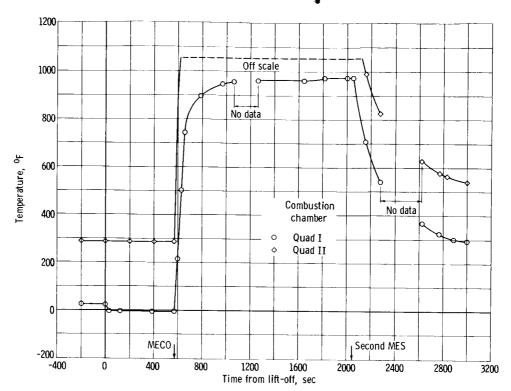


Figure VI-18. - Ullage control engine temperatures.

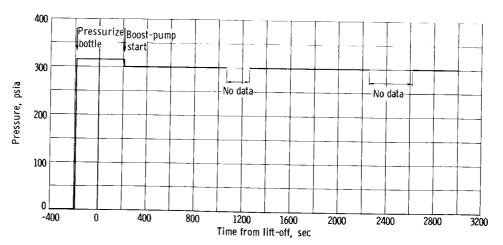


Figure VI-19. - Hydrogen peroxide bottle pressure.



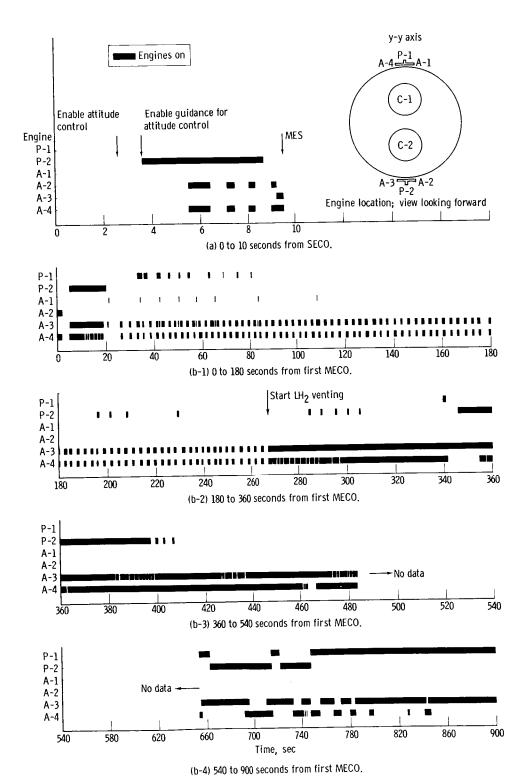


Figure VI-20. - Hydrogen peroxide engine commands.

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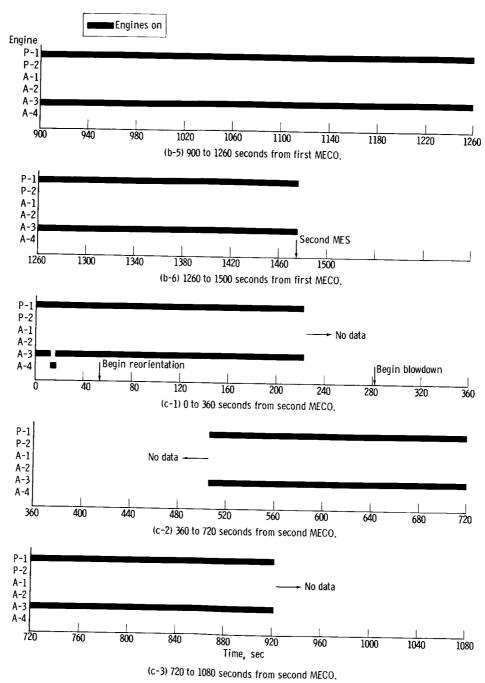


Figure VI-20. - Concluded.



VII. CENTAUR PROPELLANT SYSTEMS

SUMMARY

Centaur propellant system performance on the AC-4 flight was nominal with the exception of the coast-phase hydrogen venting and propellant behavior. Large fluid displacements, excited by vehicle transients at MECO, failed to settle out prior to venting. Unsettled propellants at the forward end of the tank resulted in liquid entrainment in the vent flow, with consequent high vent flow rates and impingement forces against the forward bulkhead that caused the vehicle to lose attitude control. The ensuing near liquid depletion, due to venting residual LH2 overboard, precluded achieving a programed second main engine start and retromaneuver.

Tank pressurization control during flight to maintain structural integrity and support main engine firing was satisfactory. Anomalous, however, was an uncontrolled pressure rise during the LH_2 venting period, from T + 1055 to T + 1366 seconds, resulting from the inability of the limited LH_2 flow rate to relieve the tank pressure fully. Also unusual was a rapid decrease in the hydrogen tank ullage pressure, at the time of second main engine start, caused by spraying LH_2 into the ullage from the boost-pump volute bleed line.

CENTAUR PROPELLANT LOADING

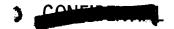
Propellant loading on the AC-4 vehicle to required flight levels was successfully accomplished with 100-percent level sensors and a ΔP propellant level indicating system (PLIS). Total propellants tanked at lift-off were 5080.8 pounds of LH₂ and 24 460 pounds of LOX.

Tanking of LH₂ and LOX propellants on the AC-4 Centaur vehicle was controlled with a liquid head pressure sensing system as shown in figure VII-1. The liquid level indication at any time was proportioned to the liquid head pressure, which was measured as a differential pressure between the sensing ports in the ullage and the bottom of the tank. These sensing lines were purged of cryogenics by bubbling helium through them at the rate of 1.5 scfh. During tanking, the differential pressure of the rising liquid was monitored on the pneumatics panel in the blockhouse as a percentage of the required ΔP for the planned 100-percent flight level.

In addition to the ΔP system, each tank utilized a hot-wire level sensor as a backup to indicate the 100-percent tanking level. Of the two, however, only the LOX 100-percent sensor functioned properly during the launch operation.

A malfunction in the $\triangle P$ PLIS in the LOX tank occurred during the quad





tanking test and resulted in an overfilling and overpressurizing of the LOX tank to 54 psia. An erroneous reading of the LOX level resulted from a leak in the ullage pressure sensing line at about the 20-percent level. This was corrected by capping the PLIS ullage sensing line and tying into the regular tank ullage pressure measurement line. System operation thereafter was acceptable.

A summary of the propellant loading conditions at lift-off for the AC-4 launch is given in the following table.

Prop- pellant	Ullage pressure, psia	Ullage volume, cu ft	Density, lb/cu ft	Station at lift-off	Volume at lift-off, cu ft	Weight at lift-off, lb
LH ₂	20.87	33.94	4.21	184.88	1206.80	5 080.8
LOX	31.10	48.30	68.65	381.39	356.30	24 460

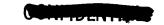
TANK PRESSURIZATION AND CONTROL

The tank pressurization control system operation on the AC-4 flight was essentially as predicted except for an unscheduled rise in fuel tank pressure above the primary vent valve operating range while venting during the coast phase, and a rapid decrease in fuel tank pressure during the attempted engine restart after coast. These anomalies, however, resulted from unpredicted propellant behavior rather than a system malfunction.

Propellant tank pressure control was effected in two ways: by controlled lockup or venting of GH_2 or GO_2 boil-off gases or by metering helium gas into the tank ullage. A schematic arrangement of the pressurization system is shown in figure VII-2.

The hydrogen tank venting was controlled with two pilot-operated relief valves: a primary (number 1) valve, with provisions for latching solenoid control by pulse signal, which regulated between 19.0 and 21.5 psia, and a secondary (number 2) valve, which regulated between 24.8 and 26.8 psia. The valves were connected in parallel between a single ullage standpipe in the tank and the nonpropulsive vent on the exit side. The latching solenoid control on the primary valve, actuated by programer signals, permitted the valve to relieve within the valve operating range when in the relief mode, but disabled the valve and prevented venting when in the locked mode. The secondary valve, however, was always in the relief mode and prevented overpressurizing the tank during the primary valve lockups. The controlled vent periods restricted overboard venting of hydrogen gas to nonhazardous times during the ascent and also provided sufficient tank pressure rise to satisfy structural integrity and/or engine start requirements.

LOX tank venting was accomplished using an almost identical vent valve with provisions for latching solenoid control and a 29.0- to 32.0-psia regulating range. The valve was connected to an ullage standpipe and vent duct and was actuated to the locked, nonventing mode just prior to and during main engine firing.



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Step increases in the LH_2 and LOX tank pressures, burp pressurization, to ensure adequate NPSH for boost-pump start were effected by locking the vent valves and metering helium into the tanks from the high-pressure helium storage bottle. Flow was controlled by a pilot-operated solenoid valve, a 0.125-inch-diameter orifice, and a check valve. A separate system was provided for each tank, and the solenoid valves were energized by programer signals to effect a given timed burp.

The respective pressure and temperature profiles for the LOX and LH₂ tanks during the AC-4 flight are shown in figures VII-3 and 4. Prior to initial primary vent valve lockup at T - 7 seconds, the hydrogen tank pressure was steady at 20.8 psi, and the corresponding oxygen tank pressure was 31.6 psia. During lift-off, the number 1 LH₂ vent valve was locked from T - 7 to T + 74 seconds. At T + 60.5 seconds, hydrogen tank pressure had reached 26.2 psia, causing the number 2 vent valve to relieve momentarily. An early venting had been predicted on the basis of a pressure rise rate of 6.0 psi per minute compared with 4.72 psi per minute obtained during flight. The AC-3 quad-tanking-test data had similarly indicated a pressure rise rate of 4.1 psi per minute compared with 3.87 psi per minute during flight. The added improvement between tanking and launch on AC-4 was accomplished by fixing poor seals and thermal shorts around the forward bulkhead.

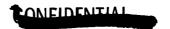
The overall higher pressure rise rate experienced on AC-4 was attributed to differences in thermal integrity and possibly a reduction in ullage volume. Ullage volume on AC-4 was about 30 cubic feet compared with 40 cubic feet on AC-3.

At T + 74 seconds the number 1 $\rm IH_2$ valve was pulsed to the relief mode, and the pressure dropped from 26.15 psia to the regulating range of the primary valve. The pressure profile through BECO, BECO lockup and blowdown, and through main engine start was as predicted. The LOX tankage was in a near state of equilibrium and the ullage pressure varied only slightly within the vent valve range.

The LOX and primary LH₂ vent valves were locked, prior to MES at T + 223 seconds, and the tanks pressurized with helium to ensure adequate NPSH for boost-pump start. This burping, as shown in figure VII-3(b), produced a step pressure increase to 34.6 psia in the LOX tank, a ΔP of 3.1 psi, and 21.2 psia in the hydrogen tank for a ΔP of 1.1 psia. During main engine firing the tank pressures then decreased, due to normal fuel depletion, to 26.9 psia on the LOX side and 16.6 psia on the LH₂ side at first MECO.

Following MECO (T + 572.8 sec), the vent valves were enabled at T + 614.4 seconds. Hydrogen tank pressure rose gradually to the primary valve cracking pressure of 20.6 psia at T + 840 seconds. The pressure rise rate during this coast-phase period was 0.90 psi per minute. While venting for the next 215 seconds, to T + 1055 seconds and loss of data, the LH $_2$ tank pressure varied because of mixed-phase or liquid flow but controlled within the number 1 valve range.

A gap in data coverage existed from T + 1100 to about T + 1235 seconds,



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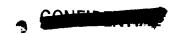
and at reacquisition of signal, as shown in figure VII-3(c), the LH₂ tank pressure was 2.0 psia higher and rising steadily, even though the primary valve was in the relief mode. Pressure continued to rise to 24.4 psia at T + 1366 seconds, and then abruptly reversed and relieved to a normal tank pressure of 20.4 psia at T + 1455 seconds. The venting flow data, as discussed in the section HYDROGEN VENTING, indicated liquid hydrogen was being vented during this time period, and the liquid flow rate was of insufficient volume to relieve tank pressure. In addition, the possible formation of ice deposits at the vent exits, due to liquid venting, may have further inhibited adequate venting. The pressure recovery then did not begin until the liquid had been largely depleted and the flow was transitioning back to a gaseous state. Once the tank pressure had recovered and the venting was normal, the primary valve again controlled properly within limits.

In preparation for the attempted second engine start, as shown in figure VII-3(d), the number 1 LH₂ and LOX valves were locked at T + 2005.4 seconds. Simultaneously, both tanks were burped; 4 seconds in the LOX tank and 8 seconds in the LH₂ tank. This burping increased the LOX tank pressure 2.5 psi, from 31.4 to 33.9 psia, and the LH₂ tank pressure 0.8 psi from 20.1 to 20.9 psia. After burping, however, the LH₂ pressure suddenly dropped 7.2 psi during the period T + 2014 to T + 2027 seconds. This pressure decay was attributed to cooling of the ullage gas by LH₂ sprayed forward from the boost-pump volute bleed and the propellant-duct-recirculation lines. Notably, the boost pump started 4 seconds after burp initiation, and the pressure decrease began 4 seconds later.

Calculation of heat-transfer effects due to spraying LH₂ into the hydrogen ullage indicated that, for an initial ullage temperature of 60° to 65° R, vaporization of 15 pounds of LH₂ would produce the observed pressure collapse, assuming all heat extraction was from the ullage. Boost-pump-performance data during this attempted restart period indicated that approximately 30 pounds of LH₂ were sprayed into the tank from the volute bleed. Further discussion of this phenomenon is given in the section CENTAUR PROPELLANT BEHAVIOR.

The hydrogen tank pressures remained depressed through the programed but unachieved second main engine firing. Then at programed second MECO, T + 2102 seconds, the pressure rose steadily as shown in figure VII-3(e) to the cracking pressure of the secondary valve, 26.8 psia at T + 2385. Venting occurred only momentarily, however, as 2 seconds later the programed retromaneuver blowdown began and the pressure blew down through the engines. The pressure rise rate during this interval, for essentially a gas-filled tank, was 2.8 psi per minute compared with a predicted pressure rise rate for this configuration of 2.5 psi per minute. The rapid pressure decay during the blowdown was due to gas flow and, therefore, additional evidence of liquid depletion. Had liquid blown down through the engines, increased boil-off gases would have acted to maintain tank pressure.

LOX tank pressures during the attempted second engine burn operation remained reasonably steady and decreased 1.8 psi. Failure to achieve a second burn and only normal venting during the coast phase resulted in a large LOX residual. Therefore, in contrast to the hydrogen tank, the LOX pressures showed





no significant drop during the blowdown portion of the retromaneuver, and the LOX boiloff was sufficient to maintain tank pressures.

A summary of these tank pressure data, pressure rise rates, helium consumption, etc., is given in tables VII-I and II.

HYDROGEN VENTING

The performance of the hydrogen vent system in safely discharging the boiloff gases from the vehicle, during boost-flight phase of the AC-4 flight, was
completely successful. However, after the first MECO during the near-zerogravity coast phase, the system performance was not satisfactory. Unexpected
liquid entrainment during this venting period resulted in excessive flow rates
beyond the design capability of the nonpropulsive vent and powerful reaction
forces that caused the vehicle to lose attitude control.

The hydrogen venting configuration for the AC-4 flight, as shown in figure VII-5, was much the same as on the previous AC-3 flight. Significant changes in the system were the inclusion of a Venturi-type flow-rate meter, a minimum ullage standpipe, and a redesigned nonpropulsive vent intended to cancel out reaction forces when venting under zero-gravity conditions.

The nonpropulsive vent, as shown in figure VII-5, was basically a plenum with internal baffles, with the vent flow discharged laterally from both sides. During initial boost flight, one side was capped and the vent flow was directed out through the 50-inch vent stack. At nose-fairing jettison, the ducting leading to the vent stack and cap were separated, and venting continued in the nonpropulsive mode.

Hydrogen venting during the flight was a controlled sequence and the venting schedule as shown in table VII-I was changed slightly from the AC-3 flight. The initial primary vent-valve lockup period was from T - 7 to T + 74 seconds, and the reenabling of the primary vent valve, 54 seconds after first MECO, was at T + 614.4 seconds.

The venting-flow-rate data during the boost-flight phase are shown in figure VII-6. As noted, the initial primary vent-valve lockup period was from T - 7 to T + 74 seconds, but the secondary vent valve relieved momentarily at T + 60.5 seconds. This venting was negligible and was not unexpected in view of the higher pressure rise rates observed during the AC-4 quad tanking tests. Scheduled blowdown after T + 74 seconds and after BECO lockup were accomplished without incident, and the flow rates were about the same as on AC-3. Maximum indicated flow rate was just under 0.7 pound per second during the first blowdown period. A total of about 72 pounds of hydrogen gas were vented during the boost phase.

Dynamic behavior of the vent valves during venting periods can be assessed only generally. Apparently cycling of the primary vent valve was indicated by the oscillations of the flow rate pressure measurements as the valve operated between its cracking and reseat pressures. Perturbations in Venturi pressure, of the order of 1 to 2 cps, developed just prior to the BECO lockup and con-



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tinued on through the second blowdown period. Prior to this time the pressures were steady, indicating a smooth modulating rather than cyclic mode of operation. The incipience of this cyclic mode, also experienced on the previous Centaur flights, can be attributed to the reduction in back pressure on the valve. At lower altitudes the increased back pressure tends to stabilize the valve operation.

Coast-phase venting after first MECO was initiated at T + 840 seconds as the tank pressure reached the primary vent valve cracking pressure of 20.6 psia. The presence of residual liquid hydrogen at the forward end of the tank resulted in liquid entrainment producing flow rates greater than predicted. Thrust cancellation in the axis of the vents was satisfactory, but large impingement forces of the expanding jets acting against the forward bulkhead and nearby equipment packages exceeded the capability of the attitude control system and forced the vehicle out of control in the positive yaw direction.

The presence of liquid at the forward end of the tank and possibly in the ullage standpipe is confirmed by the liquid temperature indications of the forward bulkhead skin temperature and ullage temperature measurements. Also, the vent flow temperature probe located downstream of the Venturi and just above the forward bulkhead dropped from -346° to -353° F 4 seconds prior to first venting, and then abruptly to -421° F in less than 1 second when the vent valve cracked. Further discussion of the post-MECO propellant location is contained in the section CENTAUR PROPELLANT BEHAVIOR.

The venting flow rates during this coast phase are shown in figure VII-7. Actual quality of the vent flow due to liquid entrainment cannot be established; but flow rates are shown for both the gas and liquid states based on the measured Venturi pressures. The saturated temperature indications and the pronounced fluctuations in the Venturi pressures, as seen in the flow rate data, were evidence of liquid entrainment and flash-off.

Vehicle tumbling excited by the impingement forces of the high flow rates then forced additional liquid forward, increasing the liquid entrainment in the vent flow. This saturated mixture rapidly absorbed any residual heat in the ducting, resulting in less flash-off and a stabilizing influence in the indicated vent pressure measurements. Venting relief, however, appeared adequate, and tank pressures (fig. VII-8), though somewhat unsteady, were maintained until about T+1055 seconds. Tank pressure then increased and continued upward until loss of data at about T+1100 seconds.

Data reacquisition, about 130 seconds later at T + 1230 seconds (fig. VII-8(a)), indicated rising tank pressures and high flow rates. Flow rate pressure measurements were extremely clean, and for a pure gas flow the vent rate would have been 0.50 to 0.60 pound per second. This would have been more than enough to relieve the tank pressure. Therefore, it appears that liquid was being vented (about 3 lb/sec) and that the liquid flow was of insufficient volume to relieve the tank pressure. It should also be noted that, in experimental tests, the expanding of a liquid or liquid-vapor mixture into near-vacuum conditions results in ice formation at the exits. Such a formation of hydrogen ice at the nonpropulsive vent exits, in this instance, would restrict the vent





capacity and further inhibit adequate pressure relief, as well as contribute to asymmetric thrust.

At T + 1366 seconds, the tank pressure peaked at 24.2 psia and then relieved to the normal tank pressure range by T + 1455 seconds. A decay in vent flow rate and a warming in the ullage gas temperature was coincident with the pressure recovery as shown in figure VII-8(a). Further evidence of liquid depletion was noted 50 seconds later as the vent gas temperature began to increase. Excursions noted in the flow rate data during this interval were attributed to possible buildup and breakaway of ice deposits at the nozzle exits and transition back from liquid to gas flow.

After the tank pressure recovery, T+1455 seconds through the vent valve lockup at T+2006 seconds, venting was again normal and proceeded in an intermittent mode, as shown in figure VII-8(b). This was characteristic of the vent valve cycling between its crack and reseat pressures. Ullage and vent gas temperatures continued to rise also, indicating the venting of a warm ullage gas. Average vent flow rate during this interval was about 0.10 pound per second.

The final venting occurrence during the coast phase was nearly coincident with the start of the retrothrust maneuver. At T + 2386 seconds, the tank pressure reached the cracking pressure of the secondary vent valve, and the engine cooldown valves opened at T + 2387 seconds to start propellant blowdown through the engines. Consequently, hydrogen tank pressure dropped off rapidly, and the closure of the vent valve 10 seconds later terminated the venting. The peak flow rate during this last relief period did not exceed 0.2 pound per second.

The estimated total amount of hydrogen vented overboard during the coast phase, from T + 840 seconds to primary vent valve lockup at T + 2006 seconds, was about 960 pounds. This estimate was obtained as shown in the following table.

Time, sec	Fluid state	Pounds vented
T + 840 to T + 1055 T + 1055 to T + 1366 T + 1366 to T + 1455 T + 1455 to T + 2006	Liquid-vapor Liquid Liquid-vapor Vapor	70 705 130 55
Total		960

At first MECO, the amount of residual LH $_2$ was about 1084 pounds. If 960 pounds were vented overboard during the coast phase, then only about 124 pounds of LH $_2$ remained in the tank at the time of attempted second main engine start.

CENTAUR PROPELLANT BEHAVIOR

Propellant behavior and location during boost and Centaur-powered phases





of flight were normal. Energy inputs to the tank and transients associated with engine cutoff, however, resulted in the forward displacement of LH₂ in the tank at MECO. Subsequent firing of small ullage settling rockets with a total thrust of 4 pounds for the next 267 seconds of coast failed to settle the propellants prior to venting. This resulted in venting liquid or mixed-phase flow, which, because of high impingement forces, forced the vehicle out of control in yaw.

The AC-4 vehicle was the first Centaur tank to be extensively instrumented to study propellant behavior in a near-zero-gravity environment. The hydrogen tank was instrumented with 41 high-response germanium temperature sensors and seven platinum sensors bonded to the tank skin. The location and orientation of these sensors, shown in figure VII-9, were selected to define propellant location or liquid level near the tank walls.

A typical tank skin temperature profile through the powered and controlled coast phase of flight is shown in figure VII-10. Sensor response to specific flight events as noted was very distinct. During boost, the sensors indicated a gradual cooling as the airborne insulation panel purge rate dropped to zero. A further cooling effect was evident at the time of hydrogen venting. An abrupt increase in temperature was noted simultaneously by all sensors at insulation panel jettison.

The most interesting results of the temperature sensor data, however, were the marked indications of liquid level decrease during Centaur main engine burn. Each sensor, as shown in figure VII-9, indicated an abrupt rise in temperature with the passage of the liquid level (fig. VII-10). Correlating these wet to dry indications made it possible to establish the variation of liquid level with time as shown in figure VII-11. The correlation was excellent, and as shown, the liquid level at MECO was accurately established at station 339. This level resulted in 1084 pounds of residual hydrogen at end of first burn.

The post-MECO propellant behavior, however, was not normal and was characterized by severe disturbances. The skin temperature sensors located in the forward bulkhead area at station 184, and the ullage gas temperature probe at station 162, as shown in figure VII-12, showed an abrupt drop to liquid hydrogen level about 4.5 seconds after MECO. The sudden wetting of the forward bulkhead was attributed to a violent forward motion of the residual LH₂ caused by vehicle transients at engine shutdown. Other major contributors were the discharge from the LH₂ boost-pump volute bypass line, which sprayed liquid forward into the ullage and against the forward bulkhead, and residual liquid slosh, which was greatly amplified under the low-gravity environment. These events are discussed in more detail in section XV. COAST-PHASE PROPELLANT AND VEHICLE BEHAVIOR.

AC-4 instrumentation was not adequate to define propellant behavior completely within the LH₂ tank; however, the initial displacement of the liquid surface appeared to be a wave moving up the positive x- and negative y-axes, continuing over the top and coming down the positive y-axis, as shown in figures VII-13 and 14. Fourteen seconds after MECO, all temperatures indicated wet and remained wet until about 50 seconds prior to venting, at which time a few sensors at the forward section of the tank indicated some drying. It





appeared then, that the propellants were either beginning to settle, in response to the ullage rockets, or that some local skin drying was taking place. In spite of these isolated drying indications, the ullage temperature probe and forward bulkhead skin temperatures in the very top of the tank remained wet, indicating the continued presence of liquid.

The presence of this liquid at the forward bulkhead area, and probably in the ullage standpipe at T+840 seconds, resulted in an abnormal venting. Liquid or mixed-phase flow produced excessive impingement forces causing the vehicle to tumble out of control. This tumbling motion, as well as other possible vehicle responses to the vent impingement forces, caused an unknown liquid distribution in the tank. Nevertheless, some quantity of liquid hydrogen was forced forward as evidenced by the continued venting of liquid fuel overboard until about T+1366 seconds. Further discussion of this venting phenomenon is presented in the venting section of this report.

It appears that a small amount of LH₂ remained in the aft end of the fuel tank until second MES and beyond. This is evidenced by the sudden wetting of tank skin sensors along the positive x-axis following fuel-boost-pump restart. However, the amount of fuel present was insufficient to sustain normal boost-pump and engine operation; consequently, the second engine burn was not achieved.

The amount of liquid hydrogen present in the fuel tank after second MECO was probably insignificant as evidenced by the fuel tank pressure, which rose steeply after second MECO, following the path of heat input to a pure gas.



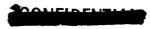


TABLE VII-I. - AC-4 FLIGHT TANK PRESSURE DATA

Event	Flight time,		Tank pressure,	sure, psia		Total	₽,	Pressure	Total AP, Pressure rise rate,
	യ	LI	LH2	TC	LOX	psia	g g	psi	psi/min
		Initial	Final	Initial	Final	2HI	TOX	ZHI	TOX
Initial vent valve lockup	-7 to +a60.5	20.8	26.1	!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	!	5.3	-	4.72	
BECO lockup	148 to 157.5	20.3	21.5] } ;	! ! !	1.2	! ! !	7.58	
Tank burp at MES	0.7-sec burp	20.1	21.2	31.6	34.7	1.1	3, 1	!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	1 1 1
First main engine burn	233.8 to 572.6	20.2	16.6	33.8	56.9	-3.6	6.9	635	-1.22
Coast after first burn	572.6 to b840	16.6	20.6	56.9	29.3	4.0	2.	თ •	. 539
Tank burp at second 8-sec LH2 burp	8-sec LH ₂ burp 4-sec LOX burp	20	20.3	31.4	52.7	, W	1.3	t I I	! ! ! !
Second main engine burn	2050 to 2100	13.8	13.6	33.2	32.1	N	1.1	! ! !	! ! ! !
Coast after second burn	2100 to 2385	13.6	26.9	32.1	52.2	13.3	-i	2. 8	!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!

aProgramed unlock at T + 74 sec. Number 2 valve relieved at T + 60.5 sec.

brirst indication of hydrogen venting during coast.

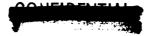


TABLE VII-II. - AC-4 HELIUM CONSUMPTION FOR TANK BURP

Event	Bottle pressure, psia	Bottle temperature,	Helium used,
Lift-off (T - 0)	3020	65.5	8.3
Prior to first burp	3020	65.5	
After first burp	2810	49.0	. 35
Prior to second burp	2570	44.0	
After second burp	1457	-31.0	2.2

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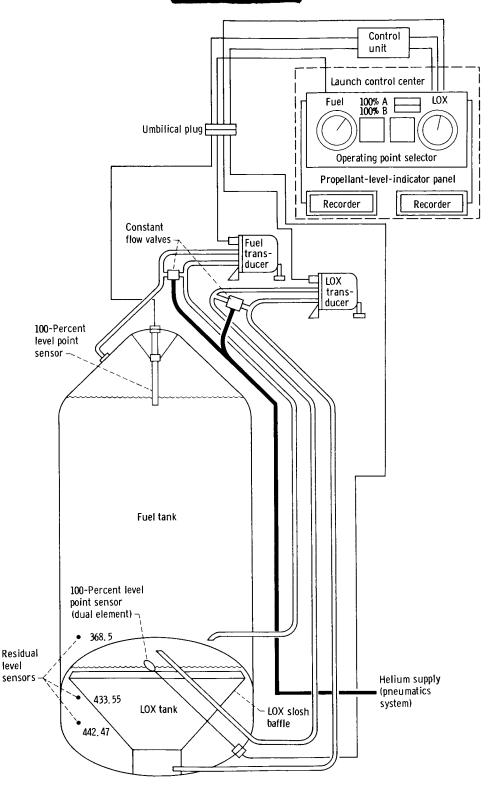
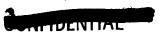


Figure VII-1. - Propellant-level-indicating system.



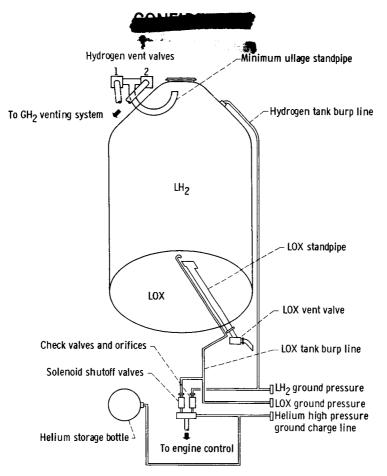


Figure VII-2. - Tank pressurization and control system.

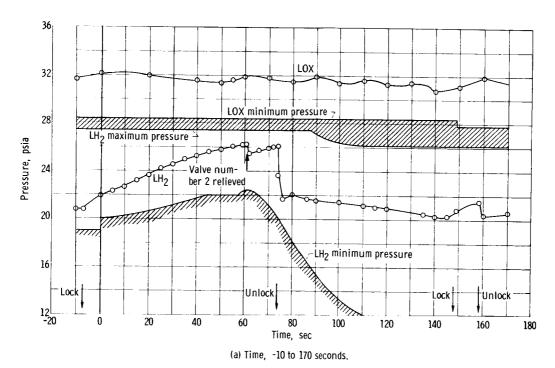
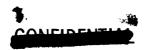


Figure VII-3. - AC-4 LOX and LH_2 tank pressures.





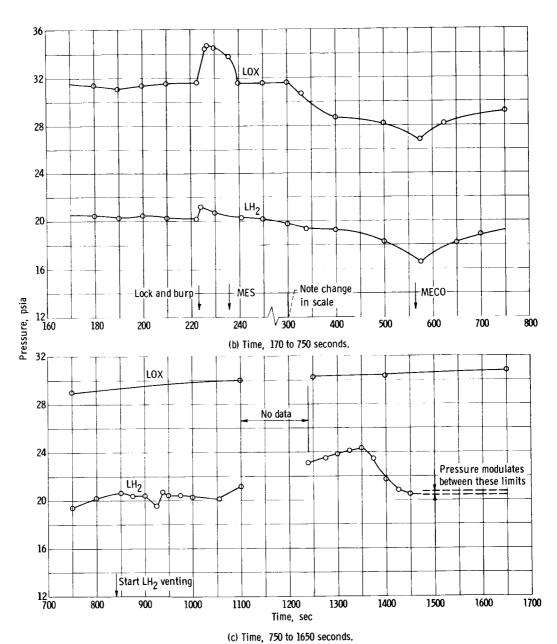
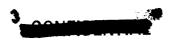
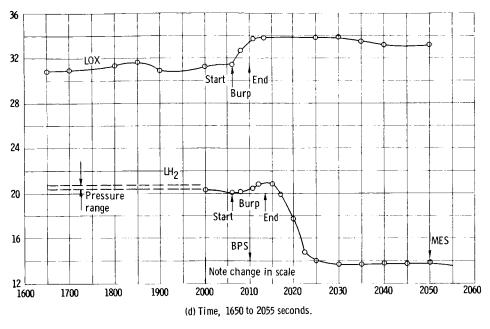
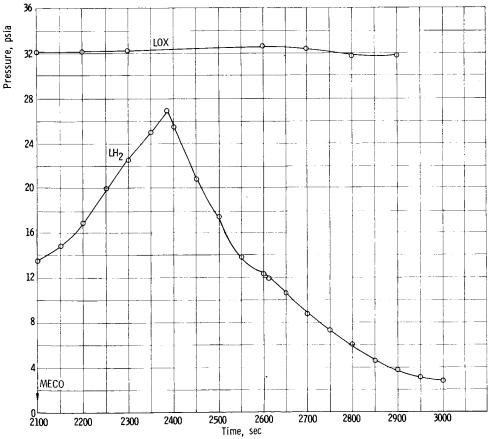


Figure VII-3. - Continued.









(e) Time, 2100 to 3000 seconds.

Figure VII-3. - Concluded.



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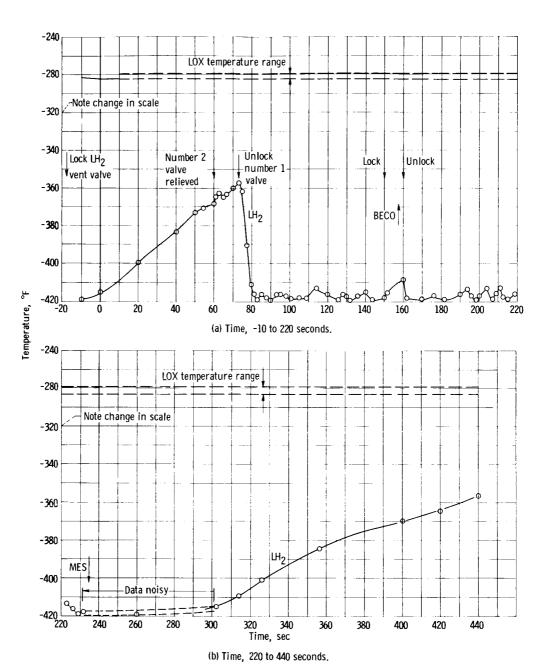
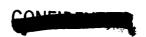
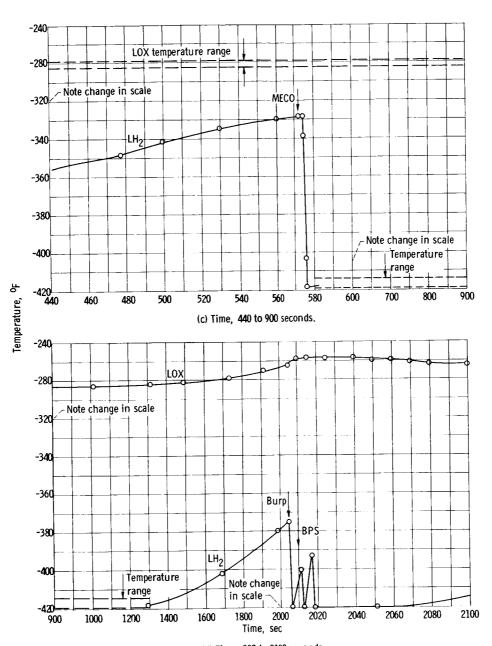


Figure VII-4. - AC-4 LOX and $\ensuremath{\text{LH}_2}$ ullage temperatures.

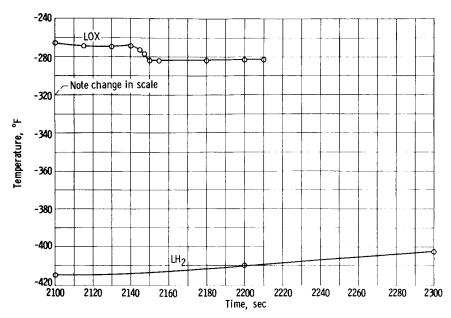




(d) Time, 900 to 2100 seconds.

Figure VII-4. - Continued.

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(e) Time, 2100 to 2300 seconds.

Figure VII-4. - Concluded.

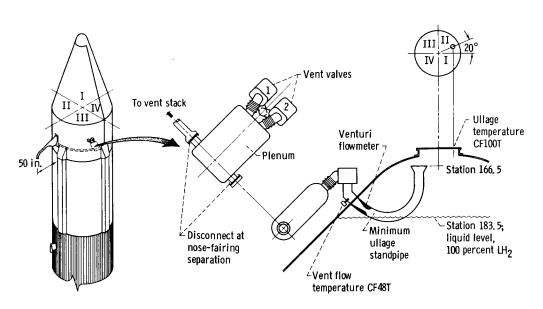
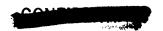


Figure VII-5. - AC-4 vent duct configuration.





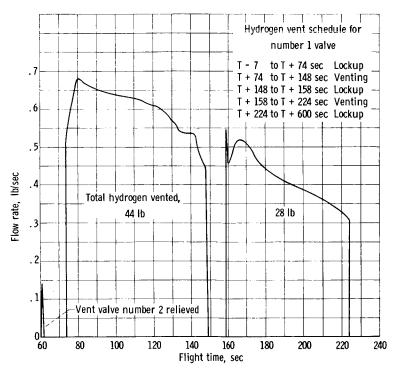


Figure VII-6. - Hydrogen venting flow rate.

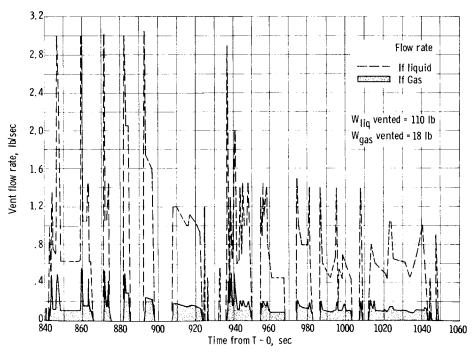
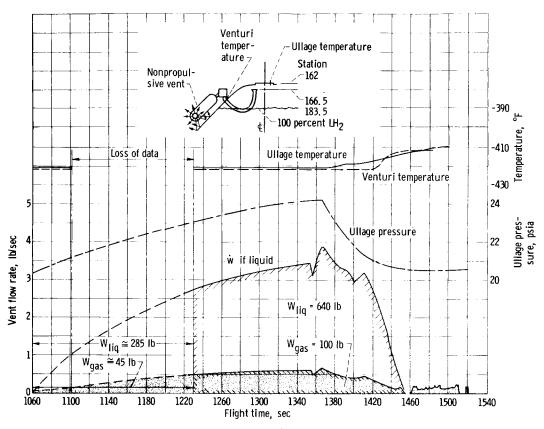


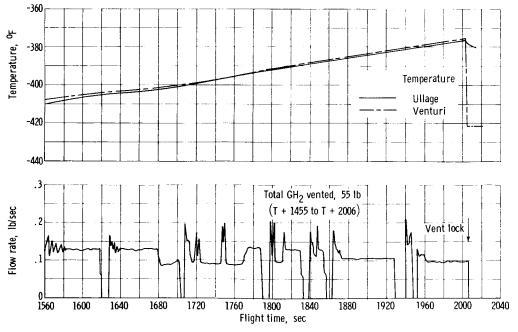
Figure VII-7. - Coast-phase hydrogen venting rates.





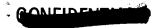


(a) Time, 1060 to 1540 seconds.



(b) Time, 1560 to 2040 seconds.

Figure VII-8. - Coast-phase hydrogen venting.





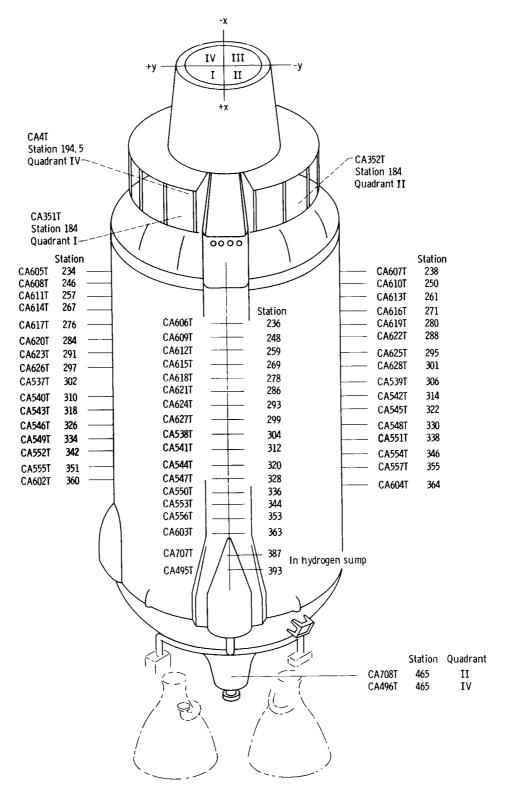


Figure VII-9. - Hydrogen tank skin temperatures.





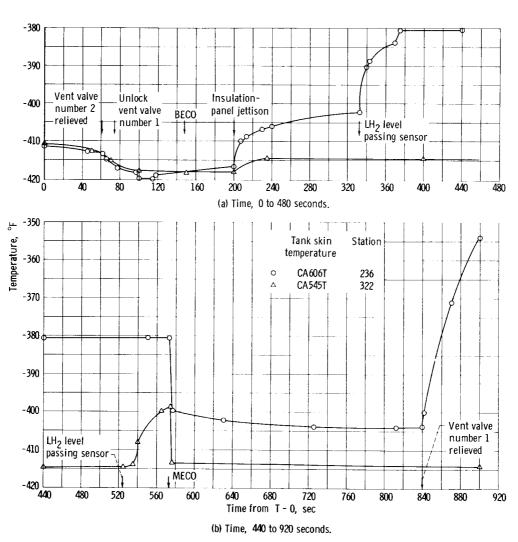


Figure VII-10. - Typical tank skin temperature history.

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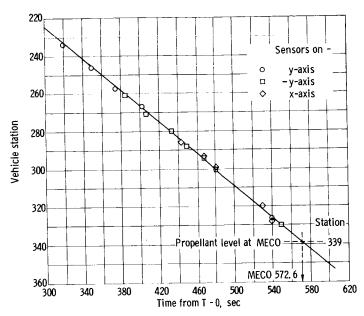


Figure VII-11. - LH_2 liquid level against time. Tank skin temperature data.

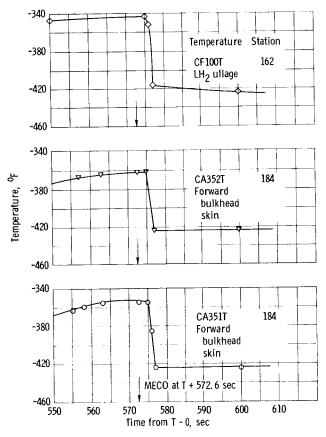
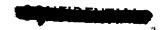


Figure VII-12. - Temperature history near MECO. Forward bulkhead area.





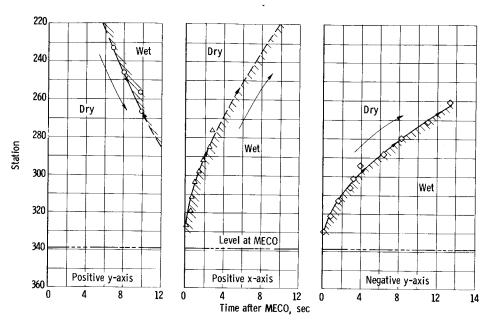


Figure VII-13. - LH2 tank skin wetting indication at MECO.

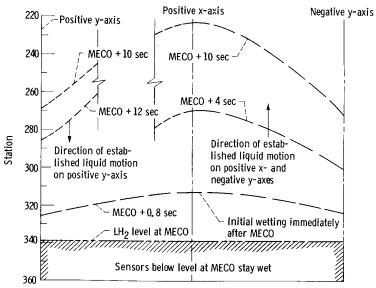


Figure VII-14. - LH₂ profile as indicated by tank skin temperatures. (LH₂ tank skin wetted entirely from MECO + 14 sec to approximately MECO + 210 sec, which is first drying of upper tank sensors.)



VIII. SEPARATION

SUMMARY

The separation systems on the AC-4 flight vehicle effected the jettison of (1) the insulation panels, (2) the nose fairing, and (3) the Atlas booster stage. The successful jettison of the insulation panels and the nose fairings satisfied one of the primary flight objectives, and the operation of the staging system satisfied a secondary objective.

The three systems performed as designed with no anomalies being noted. All four insulation panels jettisoned simultaneously, as indicated by two independent measurements. Subsequent to the AC-3 and prior to the AC-4 flights, tests of the nose-fairing-separation system were conducted at the Lewis Research Center in an effort to determine the cause of, and to effect a remedy for, shocks (measured on the equipment shelf) that were probably responsible for a guidance system malfunction on the AC-3 flight. Inasmuch as these shocks were coincident with nose-fairing jettison, the theory was advanced that this event was their cause. As a result of the test series, extensive modifications were made to the nose fairing and its jettison system, and no unaccounted for shock disturbances were noted on AC-4.

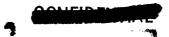
Vehicle staging occurred normally with only a low level of angular motion of the Atlas noted during the separation interval. As a result of the AC-4 flight, the level of confidence in the three separation systems has been increased.

INSULATION-PANEL

Breakwires were located on the insulation-panel-jettison hinges to record panel jettison. It can be concluded from these measurements that all the panels were jettisoned simultaneously at T + 198.47 seconds. This was verified by checking the termination of signals from other panel instrumentation. It was determined from the raw data that the panel instrumentation ceased to function at approximately T + 198.47 seconds, which is a further indication that the panels had separated from the vehicle at that time. It should be noted that the panel instrumentation disconnect (located at station 413) does not come apart until the panels have almost completely separated.

Another check was made by looking at the tank-strain-gage data. These data indicated that a definite increase in tank hoop strain occurred at the time of panel jettison. This would be expected inasmuch as the panels are under tension (circumferentially) and support part of the tank load prior to jettison.





From all these data it can be concluded that the insulation panels had parted simultaneously immediately subsequent to their shaped charge firing at T+198.47 seconds (BECO discrete +50.00 sec), which was the planned jettison time.

NOSE FAIRING

Nose-fairing separation was accomplished successfully with none of the indications of malfunction seen in the AC-3 flight. Since the nose-fairing flight-qualification tests run at Lewis included some of the flight transducers, it is possible to make a comparison of flight data with Lewis test data in this report.

Maximum pressure in the middle of the floor of the thrustor bottle cavity during flight jettison was indicated as 9.20 psia compared with 4.9 psia obtained from a similar transducer during the Lewis tests. The value 4.9 psia is somewhat doubtful, however, because an additional transducer located in the same place consistently indicated a pressure of about 8 psia. Pressure on the top of the Surveyor mass model was indicated to be 0.081 psia for the flight and 0.070 psia for the Lewis tests (although a maximum pressure limit has not been definitely established for this region). A value of 0.50 psia was observed during an overpressure test at Lewis with no resultant damage to the Surveyor mast, solar cells, or panels.

Accelerations were measured at the base and at the top of the mass model in the x- and y-directions during flight. The measurements at these locations never exceeded 0.6 g (rms) during the nose-fairing jettison.

During the AC-3 flight, acceleration peaks during nose-fairing separation were indicated to be approximately 15 g's (rms) by an accelerometer located near the equipment shelf. The accelerometer located on the AC-4 A/P gyro package indicated a maximum of 5 g's peak-to-peak at nose-fairing jettison. A plot of these accelerations is shown in figure VIII-1. Strain gages, which measured the nose-fairing vertical loads, were installed on both the Lewis and flight nose-fairing hinges. Figure VIII-2 shows the jettison loads placed on these hinges during flight and during the Lewis test. The maximum measured compressive load of 2600 pounds was well under the hinge load capacity of approximately 8000 pounds. The flight loads in figure VIII-2 were obtained by doubling the indicated load, since only one leg of the two-leg hinge was strain gaged.

Position-indicating transducers measured the angular rotation of the nose fairing about its flight hinge. Figure VIII-3 and 4 shows the angular motion of the fairings, for the flight and for the Lewis test as obtained from these transducers and for the Lewis test as obtained from photographic data. The two methods of obtaining angular rotation during the Lewis flight qualification tests were in close agreement. The angular rate of rotation during flight, as shown by these transducers, was less than that obtained during the Lewis tests possibly due to the weight of an ablative coating added to the flight fairing. Since transducers were located in each quadrant, rotation about the z-axis was also observed. In the quadrant II and III fairing half, data from the flight



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showed that the quadrant III rate of rotation was slightly more than the quadrant II rate, whereas the Lewis tests showed the opposite to be true. For the quadrant I and IV nosecone half, the quadrant IV rate of rotation was slightly higher than that of the quadrant I rate in both the flight and Lewis tests.

ATTLAS-CENTAUR

Inasmuch as the Atlas-Centaur staging sequence had been successfully accomplished twice on previous Atlas-Centaur flights, its successful completion constituted a secondary objective of this flight. As in earlier flights, the separation process was initiated by firing the linear shaped charge thereby severing the interstage adapter at station 413.

The retrorockets were fired at approximately T + 226.86 seconds to decelerate the Atlas; accelerometer and rocket-fairing-cap-breakwire data indicate that all eight rockets ignited.

Information obtained from gyros indicated that the Centaur did not rotate about its center of gravity to an appreciable amount during the separation process (less than 0.2°). Gyro data indicated that the Atlas did not rotate significantly about its pitch axis (which is the more critical axis) but that a rotational component about the yaw axis was experienced that resulted in a yaw of approximately 0.7° at the time the Atlas cleared the Centaur. The path of the forward edge of the interstage adapter resulting from the Atlas angular and z-axis motions is shown in figures VIII-5 and 6.

The flight rotational and translational motion components compared with the predicted values are shown in table VIII-I. It will be noted that the predicted and observed pitch (y-y) motions are both small, whereas the measured yaw (x-x) motion was significantly greater than predicted (7 in. compared with 2 in.). As shown in figure VIII-5, however, the indicated clearance between the engine and the interstage adapter in the plane of the x-x axis was a substantial 33 inches.





TABLE VIII-I. - MAGNITUDES AND DIRECTIONS OF

ATLAS COMPONENTS OF MOTION AT FORWARD

EDGE OF INTERSTAGE ADAPTER AFTER

9 FEET OF LONGITUDINAL MOTION

Component	Predicted, in.	Observed, in. (see figs. VIII-4, 5)
	Along x-	-x axis
Translation	0	
Rotation about center of gravity	2	7
Total	2	7
	Along y-y axis	
Translation	$-1\frac{1}{4}$	
Rotation about center of gravity	$-1\frac{1}{4}$ $-\frac{1}{4}$	-1
Total	-1 <u>1</u> 2	-1

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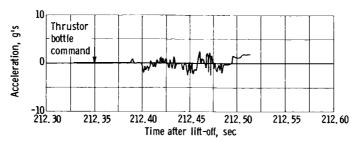
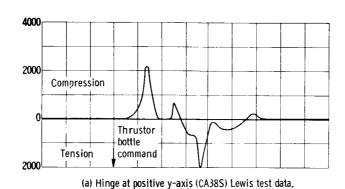
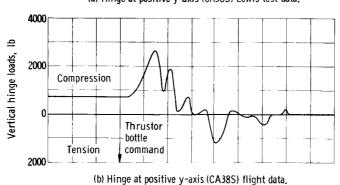
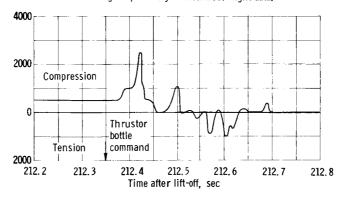


Figure VIII-1. - Equipment platform accelerations of A/P gyro at nosefairing separation measured along y-axis during AC-3 flight. (Signal attenuated by a factor of 2, 62,)







(c) Hinge at negative y-axis (CA39S) flight data.

Figure VIII-2. - Vertical hinge loads during nose-fairing separation.





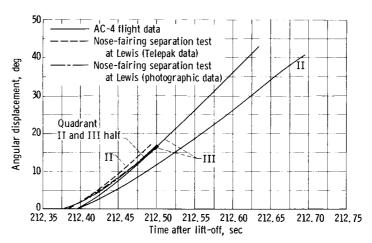


Figure VIII-3. - Quadrants II and III nosecone half angular motion of fairing at separation.

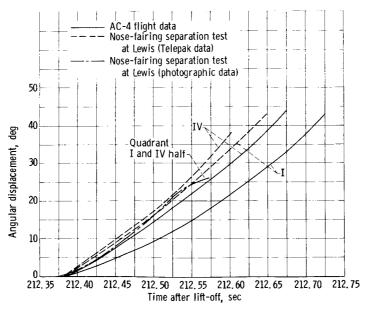
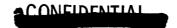


Figure VIII-4. - Quadrants I and IV nosecone half angular motion of fairing at separation.





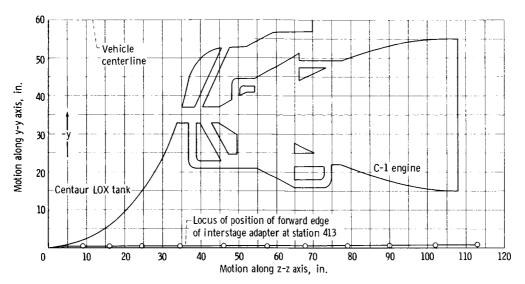


Figure VIII-5. - Motion in y-z plane of station 413 on Atlas with respect to Centaur during staging of AC-4 flight.

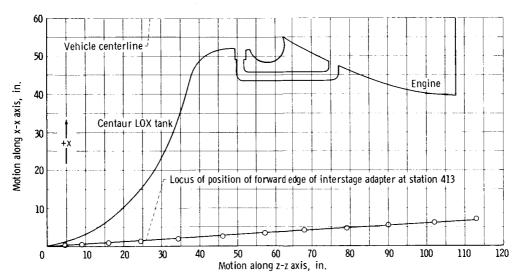


Figure VIII-6. - Motion in x-z plane of station 4 13 on Atlas with respect to Centaur during staging of AC-4 flight.



IX. ENVIRONMENTAL TEMPERATURES AND PRESSURES

SUMMARY

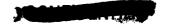
The exterior environmental temperatures experienced by the AC-4 vehicle were within the design limits and less than the predicted nominal values. The highest temperatures encountered were 585° F on the forwardmost point of the nose-fairing cap, and 976° F on the leading edge of the hydrogen vent stack, 18 inches outboard of the vehicle. Since the AC-4 trajectory would produce aerodynamic heating high enough to reduce the nose-fairing strength to a marginal value at the time of jettison, the nose-fairing and barrel sections were thermally protected with a subliming material (Thermolag T-230). Areas adjacent to protuberances on the insulation panels and interstage adapter were also protected with Thermolag. On the Atlas LOX tank, the maximum measured temperature was 320° F at station 580. At this temperature, the stress capability of the material far exceeds the loads.

The nose-fairing pressure environment was well within predicted values. A peak crushing pressure of 3 psi at T + 60 seconds was measured on the umbilical island. This pressure is below the design value of 5.2 psi. The thrustor bottle compartment pressure showed a peak value of 9.2 psi, which is not considered detrimental to any structure in this area. The insulation panel differential pressure history indicated that, through most of the flight, a crushing pressure is exerted on the panels whose peak value was recorded at 3.04 psi.

NOSE FAIRING

The nose fairing was a phenolic-Fiberglas honeycomb structure designed to withstand aerodynamic loads during the early boost-phase portion of the trajectory and nose-fairing-jettison loads. Preflight analysis of the nominal trajectory indicated temperatures between 500° and 600° F, which were in excess of the bondline strength and would have caused an adhesive failure between the outer skin and honeycomb core. This type of failure was encountered on a recent Agena-Mariner flight that had a similar nose-fairing structure. Also, ground tests have verified this adhesive type of failure on both the Centaur and Mariner nose-fairing structures. Therefore, to reduce these temperatures, a 0.040-inch-thick coating of Thermolag T-230 was applied to the nose-fairing conical and barrel sections. The areas coated are shown in figure IX-1. This coating effectively doubled the outer skin thickness or thermal mass because the Thermolag has a specific heat 25 percent higher than the phenolic.

In figure IX-2 the temperature-time curve is illustrated for various stations on the nose fairing. These temperatures were measured by thermocouples located under the first layer of Fiberglas, which, in turn, was covered by approximately 0.043 inch of Thermolag and phenolic. The sublimation temperature





of the Thermolag is a function of ambient pressure. At 1 millimeter of mercury the theoretical sublimation temperature is approximately 180° F. From the shape of the curves in figure IX-2, sublimation at stations 19 and 125 started at approximately 120 to 130 seconds; however, at station 181 on the barrel section, the Thermolag did not sublime but merely provided enough mass to keep the temperature extremely low. The nose cap, constructed of a phenolic-Fiberglas solid laminate structure 0.20 inch thick, was not coated with Thermolag, and peak temperatures ran just under 600° F, as illustrated in figure IX-3. The inner nose-fairing skin temperatures as well as the Surveyor compartment, remained relatively low throughout flight and showed little or no response to aerodynamic heating. Temperatures remained stable at lift-off values between 60° and 75° F.

The actual pressure environment during flight was less than predicted at all stations. Maximum crushing pressures encountered on the nose fairing occurred during transonic flight. Transducers at station 155 indicated peak crushing pressures of 0.3 psi in quadrant I, 0.44 psi in quadrant II, and 0.49 psi in quadrant III. These values compare with a design crushing pressure of 1.8 psi. At station 180, quadrant IV, a peak crushing pressure of 1.8 psi was recorded at T + 58 seconds; however, the design value in this area is 3.3 psi. The umbilical island showed a crushing pressure of 3 psi at T + 60 seconds, again well below the design value of 5.2 psi.

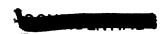
PROTUBERANCES

The maximum temperature measured on the Centaur vehicle was on the hydrogen vent stack. Measurement CA283T located on the leading edge of the vent stack, 18 inches outboard of the vehicle, indicated a maximum temperature of 978° F at T + 150 seconds, as shown in figure IX-4. Following maximum heating, the stack temperature cooled to 460° F at nose-fairing jettison.

A temperature profile along the quadrant T-II axis, including the umbilical island ramp and boost-pump fairing, is shown in figure IX-5. The umbilical island ramp was protected with a 0.1875-inch-thick layer of cork, and the maximum temperature under the cork was about 125° F. The boost-pump fairing did not have a protective Thermolag coating, and, as shown in figure IX-5, temperatures ran hotter, about 210° to 290° F. These temperatures were below the critical bondline temperatures and in no way impaired the integrity of the Fiberglas structure.

THRUSTOR BOTTLE COMPARTMENT PRESSURE

The thrustor bottle compartment pressure dropped from approximately 14.7 psi at lift-off to flight vacuum at nose-fairing jettison. At jettison, there is a pressure peak of about 9.2 psi due to thrustor bottle pressure. This pressure peak is higher than the pressures of 4.9 psi measured during Lewis Research Center SPC tests of the nose fairing but is not considered detrimental to any structure in this area.





PAYLOAD ADAPTER AND SPACECRAFT TEMPERATURES

All temperatures on the mass model, separation latch points, and payload adapter were within predicted values during the AC-4 flight. Temperatures ranged from 70° F at the top of the payload mast to -130° F at the payload adapter to tank attachment (station 171).

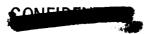
INSULATION PANELS

Locations of the various pressure measurements on the insulation panels are shown in figure IX-6. The external pressure decay history is shown in figure IX-7. At approximately T + 120 seconds, the external pressure reaches a value of zero. Insulation panel differential pressure history during the flight shows that a crushing pressure exists throughout most of the flight. Only in a few cases do the pressure curves become negative, which indicates a bursting pressure acting on the panels. The maximum crushing pressure recorded was 3.04 psi, and the maximum bursting pressure recorded was 0.38 psi. The maximum crushing pressure occurred at T + 70 seconds, immediately after the terminal shock wave passed down the panels. The movement of this shock wave is the cause of the pressure increase at this time. The differential pressure history is shown in figure IX-8. All the differential pressures are well within design limits for the insulation panels and lower than the predicted values.

The insulation panel temperature instrumentation to measure the thermal environment on AC-4 is shown in figure IX-6. The internal panel temperature data shown in figure IX-9 indicate temperatures at time of lift-off between -340° and -370° F. The predicted temperature at lift-off was -360° F, which corresponds very well with actual temperatures. One thermocouple (CA381T) did not fall within this temperature range, reading -260° F at lift-off. A reasonable explanation is that the thermocouple was near the helium purge ring and subject to impingement of warm helium while the vehicle was on the ground.

After lift-off, the temperature readings except for CA381T, gradually increased with time, and at panel jettison were indicating -290° to -330° F. This behavior was as expected because of the heat flux into the panels. The apparent anomaly with CA381T, however, was more a case of coming into equilibrium with the surrounding areas on termination of the helium purge. The airborne purge, activated at T - 16 seconds, provided a peak purge rate of 670 pounds per hour decaying to about 60 pounds per hour in 120 seconds.

The thermocouple locations on the outside of the insulation panels are shown in figure IX-6. These transducers were located directly outside the internal temperature patches and the time history of these measurements are presented in figure IX-10. The maximum temperature recorded by five of the thermocouples ranged from 140° to 175° F. These temperatures are much lower than predicted as shown in figure IX-11. The highest predicted temperature in the basic panel region (cylindrical section) was 420° F, and the highest actual temperature was 175° F read by CA701T located at station 280. The sixth thermocouple read a maximum temperature of only 95° F. This thermocouple was located on the wiring tunnel panel at station 395 in an area that was coated with





Thermolag. The Thermolag increased the mass of the panel, thus the panel was able to absorb more heat without an increase in temperature. These temperatures result in only a small decrease in insulation panel material strength allowables.

Thermocouples CA40T and CA41T read the outside temperatures in the area of the destruct package. These thermocouples were located in a Thermolag-coated area, thus the temperatures realized were much lower than those predicted. The highest temperature read by either of these thermocouples was 88° F as shown in figure IX-12, which is well within design limits.

ATLAS LOX TANK TEMPERATURES

A comparison of predicted and measured values of the Atlas LOX tank skin temperatures at various vehicle stations is shown in table IX-I. The flight data indicate a much less severe thermal environment than the analysis does. The slightly lofted boost phase may account for some margin, but analysis is still very conservative.





TABLE IX-I. - ATLAS LOX TANK SKIN TEMPERATURES

Vehicle station,	Peak temperature, OF					
in.	Predicated maximum for design trajectory with 165K engines	AC-4 measured				
574		292				
575	640	367				
580		320				



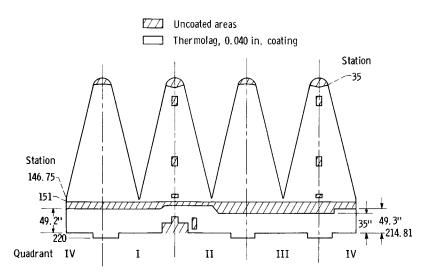


Figure IX-1. - Thermolag coated areas on AC-4 nose fairing.

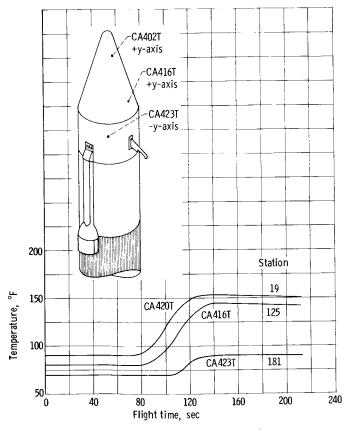


Figure IX-2. - Nose-fairing outside temperatures.



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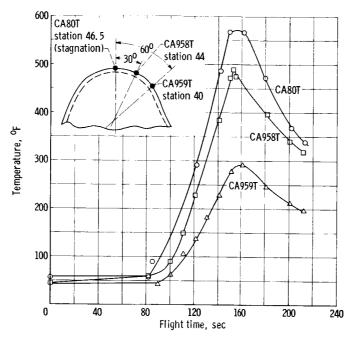


Figure IX-3. - Nose-fairing cap temperatures.

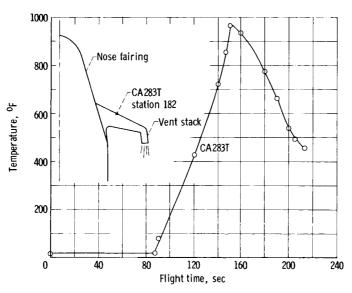
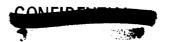


Figure IX-4. - Hydrogen vent stack temperatures.



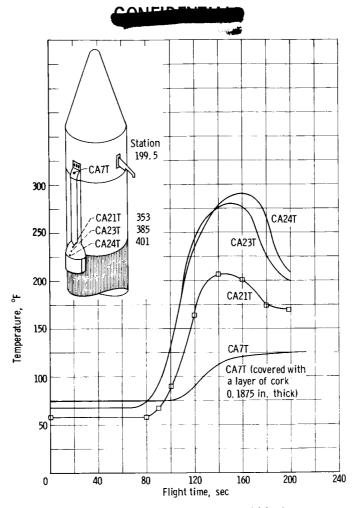


Figure IX-5. - Wiring tunnel and boost-pump-fairing temper - atures.

- o Inside temperature
- △ Outside temperature
 - Differential pressure
- ♦ Outside pressure

Thermolag coated regions

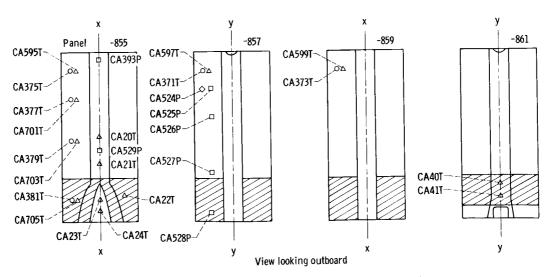
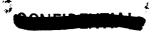
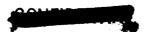


Figure IX-6. - Location of insulation panel instrumentation and Thermolag.





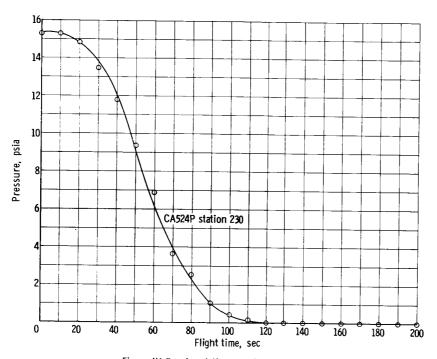
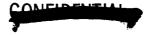


Figure IX-7. - Insulation-panel external pressure.



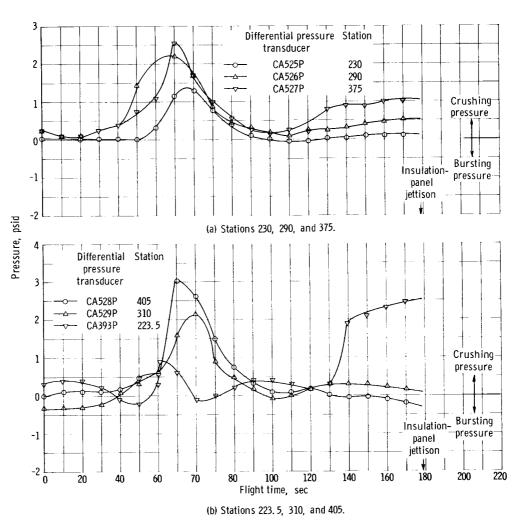
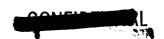


Figure IX-8. - Insulation-panel differential pressure.



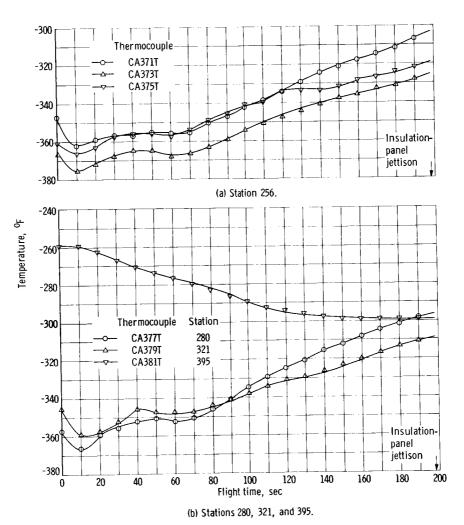
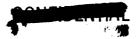


Figure IX-9. - Insulation-panel inside temperature.





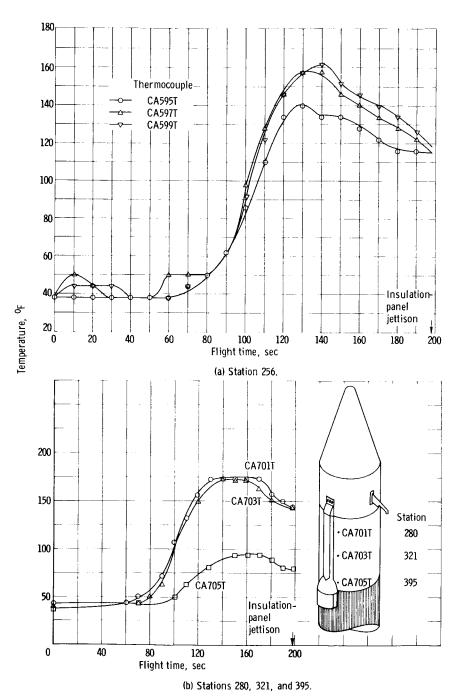
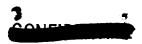


Figure IX-10. - Insulation-panel outside temperatures.



CONFIDENCE

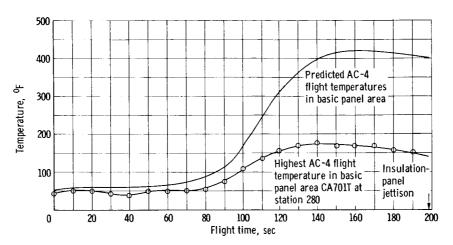


Figure IX-11. - Predicted outside insulation-panel temperature.

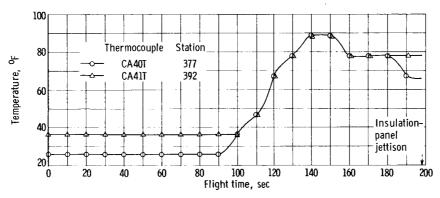


Figure IX-12. - Destruct fairing outside temperature.





X. VEHICLE STRUCTURES

SUMMARY

All mission objectives of structural significance were achieved. Structural integrity of the vehicle was successfully maintained throughout the peak loading periods. Though a few of the measurements were deleted prior to the flight and others were lost during the flight, information received was of acceptable quality and quite valuable in assessing structural performance.

The peak longitudinal load factor experienced during the flight was 5.52 g's at BECO. Aerodynamic drag loads showed a peak of 52 400 pounds at T + 70 seconds. The measured drag load history deviated from the predicted in that the actual drag load appeared to build up and decay somewhat more rapidly than anticipated. Bending loads induced by wind shears and gusts on this flight were quite small. The peak bending moment experienced on this flight occurred at T + 83 seconds: at station 548 it attained a value of 1.43×10⁶ inch-pounds.

Intimate contact was maintained throughout the flight between the Centaur LH₂ tank and the insulation panels. Inadvertent overpressurization of the Centaur LOX tank during a preflight tanking test did not appear to have a deleterious effect on vehicle strength. Rework on the nose-fairing hinges apparently achieved their objective, that is, no compression load was transmitted through these hinges during preseparation flight, although some tension loads were reacted by the hinge on the positive y-axis. A positive differential pressure of at least 6.2 psi was maintained across the Atlas intermediate bulkhead during launch, its most critical period. This was very similar though slightly more severe than the AC-3 experience. Interstage adapter skin panels were subjected to sonic and aerodynamic buffeting excitation. A peak response of 30 g's (rms) at launch and 24 g's (rms) at T + 60 seconds was attained. Payload adapter strain measurements indicated that there were adequate structural margins of safety in this area.

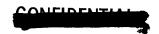
Details of structures instrumentation are shown in figures X-1 to 3. Instrumentation performance and failures are discussed in some depth in appendix D.

FLIGHT LOADS

Vehicle Bending Moments

The Atlas-Centaur vehicle is launch restricted by inflight winds, the launch availability being well below 1 for the worst months of the year. Though the winds aloft attain their peak values during the winter months, on





the AC-4 launch day, preflight balloon soundings indicated an unusually calm day even though surface winds were marginal. Peak winds through the high dynamic pressure region were all less than 30 knots. Thus, anticipated bending loads were quite small. This was verified by an analysis of loads measured during the flight by strain gage instrumentation on the vehicle.

The bending moment history at the interstage adapter station 548 is shown in figure X-4 about the two principal axes. It is seen that highest value of bending moment attained at this station was only 1.43×10^6 inch-pounds at T + 83 seconds. Although this is not the station of peak load, it is the station where a direct measurement of bending loads was made.

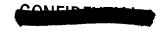
A comparison of actual and predicted loads is shown in figure X-5. The predicted bending loads range is based on T - O hour (905 EST) balloon sounding. It is seen that the measured values are approximately in the middle of the predicted range. The trends indicated analytically are confirmed by flight data, although the peak load was predicted at T + 71 seconds and actually occurred at T + 83 seconds. The only explanation that can be offered for this is a slight shift in winds between the balloon sounding and the flight. The relatively large predicted range is due to the use of a 30-foot-per-second (1 - cos) gust criteria. In view of this fact, the agreement between predicted and measured loads may be considered to be very good.

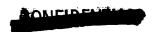
Gust Bending Moments

On this flight, the gust loads encountered were extremely small. The basic data by which gust response is measured are the high-frequency strain measurements at station 548. This high-frequency strain increment is assumed to result from the fine variations in the wind profile that are filtered out by the inherent inertia of the wind sounding instrumentation used. A review of this high-frequency strain response showed a maximum strain increment of 24×10^{-6} inch per inch. This corresponds to a bending moment equivalent to approximately 96 000 inch-pounds. The preflight analytical peak value of bending moment induced by a 30-foot-per-second (1 - cos) gust was 1.27×10^6 inch-pounds. It is apparent that the gust levels were at least an order of magnitude less than the design gust criteria.

Variation of Preflight Wind-Induced Bending Moments

Another factor in the consideration of the wind loads is the inherent time lag between the wind sounding used as the basis for launch decision and the actual launch. An evaluation of the relative changeability of the wind profile during this time becomes quite important. In figure X-6, the analytical bending moment histories are shown at vehicle station 770 on the Atlas LOX tank calculated on the basis of 2215, 0045, 0518, and 0905 EST balloon soundings. It can be seen that, on launch day, the variations in the winds were of a very minor nature. The maximum bending moment changes from 4.04×10^6 to 3.88×10^6 inchpounds in the last two consecutive soundings, a variation of 4 percent. This compares with a variation of 11 percent recorded for the AC-3 flight. These





data were obtained from unpublished GD/A analyses of simulated flight through the above winds.

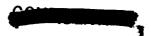
LONGITUDINAL LOADS

There are two sources of longitudinal loads on flight vehicles: one is the inertial load resulting from axial acceleration and the other is due to aerodynamic drag forces. Vehicle axial acceleration is known precisely both from onboard accelerometers and from a knowledge of total engine thrust. The inertial loads can then be calculated from known mass distribution. interest to see how well actual aerodynamic drag compared with analysis based on wind tunnel axial force coefficients. The total axial forces are calculated for station 548 from the strain gage data. Subtracting the inertial loads yields the drag forces. Comparison is shown in figure X-7. During the period of peak drag load, the agreement between the two is quite good; however, actual drag buildup and decay are much more rapid than predicted from wind tunnel data. For completeness, total axial load during this period of flight is also shown in figure X-7. From the data it appears that the total impulse resulting from atmospheric drag forces is actually less than that obtained analytically from axial force coefficient data.

ANALYSIS OF INSULATION-PANEL HOOP TENSION LOADS FOR AC-4 FLIGHT

The hoop tension loads in the AC-4 insulation panels were determined by using measured flight temperatures and pressures. The factors that affect the panel hoop tension are (1) panel installation pretension, (2) panel temperature variations, (3) panel delta pressures (crushing and bursting pressures), (4) tank temperature variations, and (5) tank pressure variations. Each of the panel and tank deflections due to these parameters were determined, and a total deflection was obtained. This total deflection indicates that, from T + O to panel jettison, an interference pressure existed between the panels and the This interference pressure was converted to panel hoop tension, and a plot of panel hoop load against flight time (fig. X-8) was obtained. load was determined at approximately the midpoint of the panels, which was station 340.

On installation, the panels were pretensioned to 75 pounds per inch with the tank at standby pressure. During cryotanking, the hoop tension begins to decrease because the tank shrinks more rapidly than the panels. The tank pressure at this time is also increasing, but this increase does not offset the ef-These factors cause the panel hoop tension to fects of thermal contraction. decrease until approximately lift-off. The panel hoop tension at lift-off was calculated to be 11 pounds per inch, which was the minimum hoop tension during the flight. After lift-off, the panel hoop tension increases gradually due to the increase in tank pressure. The deflections due to panel temperature and panel pressure remain somewhat constant. At T + 52 seconds, the panel pretension had recovered to its initial value of 75 pounds per inch. The panel hoop tension increases rapidly to about T + 80 seconds, when it peaks to a This hoop load is approximately 180 pounds per inch. After the peak is reached, which is only for less than 5 seconds, the hoop load decreases



rapidly. This decrease in hoop load is due primarily to the venting of the LH_2 tank at this time. In addition a decrease in crushing pressure and an increase in panel temperature tends to relieve the hoop tension, which decreases to a value of 42 pounds per inch at about T+120 seconds. After this point is reached, the hoop load starts to increase due to a lockup of the tank vent and a consequent increase in tank pressure. The hoop tension increases to 64 pounds per inch at T+140 seconds. At this time, the hoop load again decreases due to a second venting of the tank and increased panel temperatures. The hoop load gradually decreases to 45 pounds per inch at panel jettison.

Another means of analysis was utilized to obtain the panel hoop load. For this method, the increase in tank hoop strain at the time of panel jettison was used. This gives a value of hoop load at only one time, which is just prior to panel jettison. The value of hoop tension at panel jettison obtained by this method was 80 pounds per inch. Although higher than the 45 pounds per inch obtained by the other method, it definitely confirms that the panels and the tank were in contact throughout the flight.

INTERSTAGE ADAPTER PANEL FLUTTER

The interstage adapter configuration for the AC-4 flight was changed from that of the AC-2 and AC-3 adapters by deleting 10 ring stiffeners. This returned the adapter to its initial geometry, that is, the ring spacing used in the quarter section wind tunnel test specimen (ref. 11). The flutter boundary of reference ll and the longitudinal stiffener load history of figure X-9 were used to obtain an AC-4 flight flutter boundary. A comparison of actual flight flutter parameter and the flutter boundary in figure X-10 indicates that panel flutter was possible only for a few seconds subsequent to the time that the vehicle attained Mach 1 (T + 64 sec). It can be seen that, although the flutter parameter was outside the flutter boundary during most of the flight, the two values are quite close together. The boundary is a function of stiffener load, which in turn is a function of the wind profile bending moments. On the AC-4flight, the bending loads encountered were very small, as discussed earlier. Therefore, with existing geometry, panel flutter could occur during significant periods of time through the high dynamic pressure flight regime on launch days with a more severe wind environment.

As in the case for the AC-3 flight, accelerometer data indicated skin panel excitation through the first 100 seconds of flight. Pressure fluctuations and panel accelerometer data are illustrated in figures X-11 and 12. In the absence of panel flutter, dynamic response of the skin panels could only be the result of sonic excitation at launch, sonic and aerodynamic buffeting excitation through to Mach 1, and aerodynamic buffeting in the remaining atmospheric phases of flight. As the structural integrity of the adapter was maintained successfully throughout the flight, this level of skin panel excitation is considered within the fatigue capability of the aluminum alloy used.

NOSE-FAIRING HINGE LOADS

Nose-fairing hinges support the two fairings at jettison as each section





pivots away from the Centaur tank. Concern was evidenced prior to the flight that the nose-fairing lugs would bottom out on the hinge aft fork and transfer nose-fairing inertial and drag loads into the hinge. To alleviate this possibility, the fork opening was widened, and care was taken to create a gap between the nose-fairing lug and the aft fork of the hinge. (For hinge details see fig. X-13.)

The flight data seem to indicate that this procedure achieved its purpose. No compression was noticed in the hinges until T + 180 seconds, showing that no aft flight loads were felt by the hinges up to T + 180 seconds. There were, however, tension loads in the top y-y axis hinge during the transonic period indicating transfer of fairing bending that was overcoming positive acceleration forces. The flight loads were well within the hinge limit load capacity of 6000 pounds. For a summary of hinge loads during jettison of the fairing see section VIII. SEPARATION.

PAYLOAD ADAPTER LOADS AND STRESSES

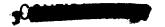
The three strain gages mounted on the payload adapter longerons (directly below the separation latch points) indicate compression in the adapter increasing in intensity from launch to BECO. At BECO, there is an abrupt decrease in payload adapter strains. Stress levels do not exceed 10 000 psi in the adapter longerons, indicating that good structural margins of safety exist in this area.

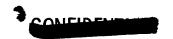
Payload adapter strains at MECO showed an oscillating type of loading (tension to compression reversals) at the separation latch points. Maximum tension and compression levels were approximately 1000 pounds per latch point. There were about four amplitudes at these levels. The loads then decayed rapidly at a frequency of 28 cps. These loads were equivalent to 1.43 g's acceleration of the payload. The normal 1.5 design factor is used to obtain an equivalent test acceleration of 2.15 g's. Previous separation latch DPT procedures called for a 1.4-g load factor limitation at the retromotor simulator. These loads have now been revised, as a result of the AC-4 data, to a 2.15-g limitation on the retromotor simulator (or 3.15 g's including gravity for laboratory test conditions). Separation latches on future vehicles will be qualified to these new loads.

INADVERTENT OVERPRESSURIZATION OF CENTAUR LOX TANK

DURING PREFLIGHT QUAD TANKING TEST

As a result of the overpressurization of the Centaur LOX tank during the first flight control and propellant tanking test on October 27 (see section III. LAUNCH OPERATIONS), there was some concern about the integrity of the structural intermediate bulkhead. Preceding the overpressurization, the fuel and LOX tanks were pressurized to 20.0 and 31.0 psia, respectively. At the time of maximum overpressurization of the LOX tank, the LOX tank ullage pressure had increased to approximately 53 psia. The differential pressure across the intermediate bulkhead including both ullage and fluid head pressure, was 33 psid at the top and 34.4 psid at the tangency point at station 405.6. For





structural details of this area see figure X-14. The design limit load allowable for the bulkhead differential pressure is 23.0 psid. The helium leak check and X-ray examination (described in section III) were augmented by an extensive series of specimen tests conducted at GD/A.

The specimens were made up in the configuration of the welds used at the bulkhead top and tangency points, prestressed to levels seen by the tank during factory and cryogenic proof tests, loaded to stress levels experienced by the bulkhead at maximum overpressurization, and then to failure, at various cryogenic temperatures. The specimen tests indicated that a moderate amount of yielding had probably occurred in the annealed weld beads and heat-affected zone of the parent material. The effect of this amount of yielding work-hardened the annealed material considerably (effectively raising the material yield point for subsequent loading) and to be insufficient to affect adversely the fracture toughness of the material at low temperature.

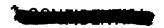
The maximum calculated stresses produced at the top and tangency points of the bulkhead during overpressurization were 106 000 and 130 600 psi, respectively. The stresses required to cause yielding in these areas (for loadings subsequent to the prestressing due to overpressurization) from the specimen tests were about 113 000 psi for the bulkhead top and 180 000 psi for the tangency point weld. The tests also indicated that the prestressing due to overpressurization raised the ultimate allowable stress for subsequent loadings at cryogenic temperature. These ultimate values were well over 200 000 psi. The maximum stresses expected in flight were 75 000 psi at the bulkhead top and 100 000 psi at the tangency point seam weld.

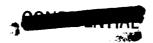
Based on the favorable results of the leak and X-ray examinations and the specimen test results, it was concluded that the structural integrity of the Centaur tank had not been impaired.

ATLAS INTERMEDIATE BULKHEAD DIFFERENTIAL PRESSURE

The measured value of the launch transient minimum differential pressure was 10.2 psi. Had the ullage pressures been at their most adverse (LOX tank, 31 psi; and RP-1 tank, 57 psi), the differential pressure across the bulkhead would have been 6.2 psi. The incremental longitudinal load factor acting on the LOX due to launch release dynamics was calculated to be 0.23 g from differential pressure data. This compares with 0.60 g assumed in the analysis.

The minimum differential pressure measured at T + 99 seconds was 9.0 psi. Again, had the ullage pressures been at their most adverse, the differential pressure across the bulkhead would have been 6.75 psi. At no time either during the flight or during launch release was the bulkhead differential pressure near its critical value of 2 psi for bulkhead reversal.





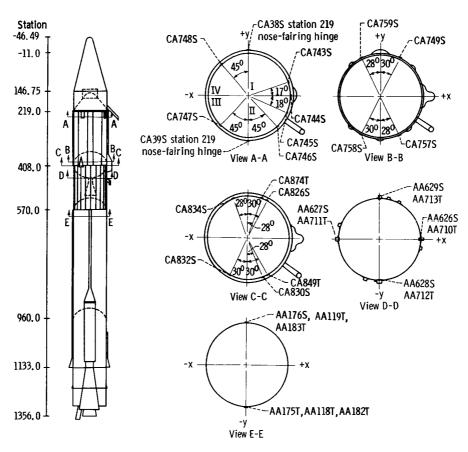
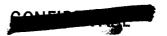


Figure X-1. - AC-4 flight structures instrumentation configuration (ref. 2). (Instrument numbers ending in S are strain gages and in T are thermocouples.)





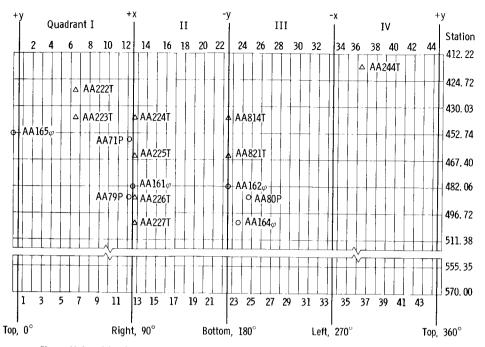


Figure X-2. - AC-4 interstage adapter instrumentation. Flat pattern external surface view.

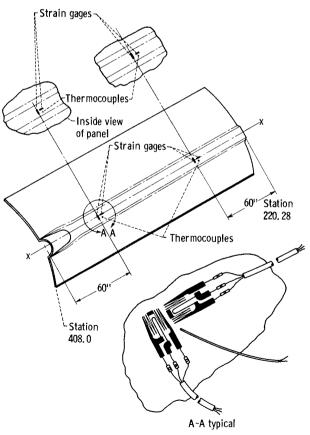


Figure X-3. - Landline insulation panel preload measurement instrumentation (ref. 17).



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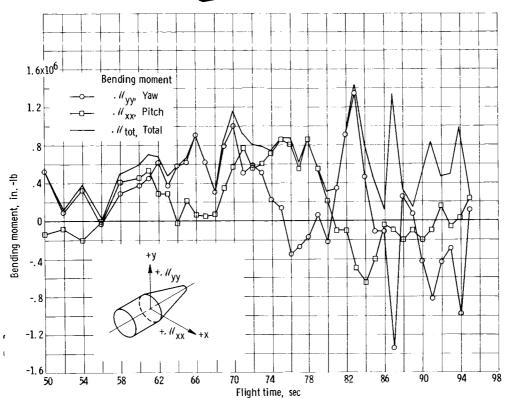


Figure X-4. - AC-4 flight bending moment history at station 548 through high $\,\alpha q\,$ region based on strain gage data.

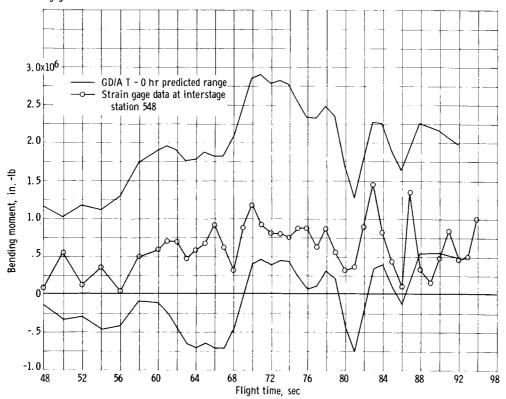


Figure X-5. - Comparison of predicted and measured AC-4 flight bending loads at station 548.





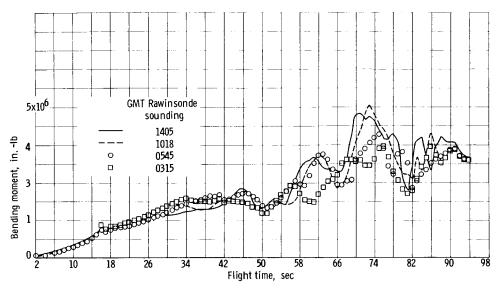


Figure X-6. - Analytical history of AC-4 flight limit bending moments based on four preflight Rawinsonde balloon soundings.

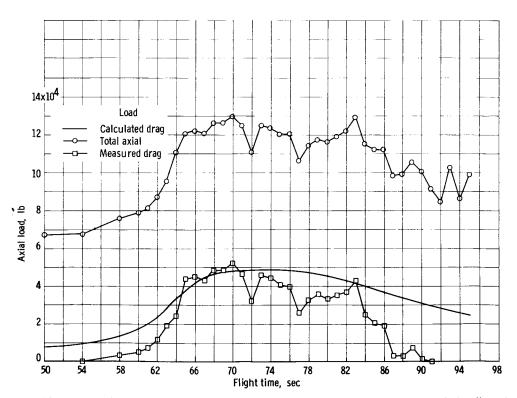
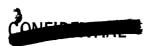


Figure X-7. - History of total axial load and comparison of measured and calculated aerodynamic drag through high q flight regime.





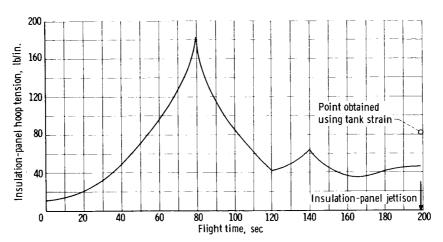


Figure X-8. - Insulation-panel hoop tension against flight time for Centaur AC-4.

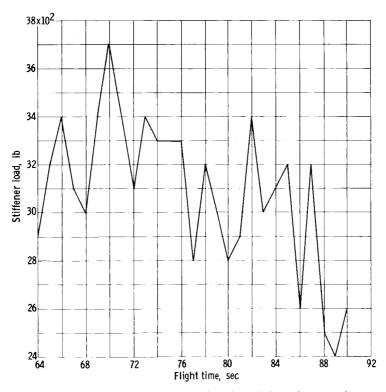
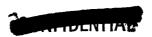


Figure X-9. - Flight history of AC-4 interstage adapter peak compression stiffener load.



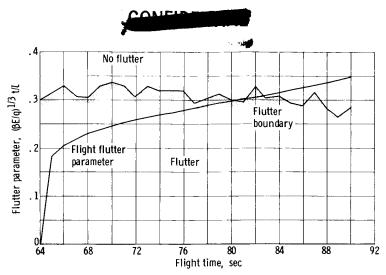


Figure X-10. - Interstage adapter skin panel flutter parameter history on AC-4 flight.

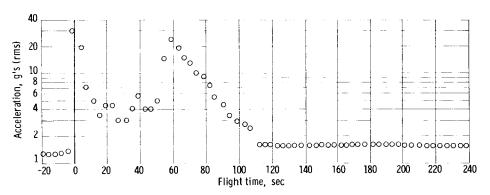


Figure X-11. - Vibration level as recorded by accelerometer $AA164\varphi$ mounted on skin panel midpoint at station 502 and negative y-axis. Data obtained from reference 2. Analysis band, 20 to 2100 cps; commutated data, one sample every 4 seconds.

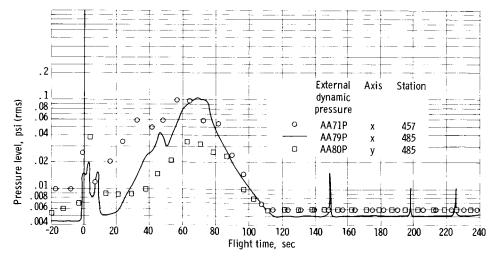


Figure X-12. - Fluctuating pressure level distribution around interstage adapter. AA71P and AA80P commutated data, one sample every 8 seconds (ref. 2).



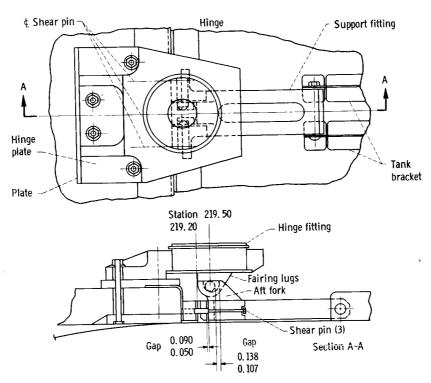


Figure X-13. - Details of nose-fairing-jettison hinge.

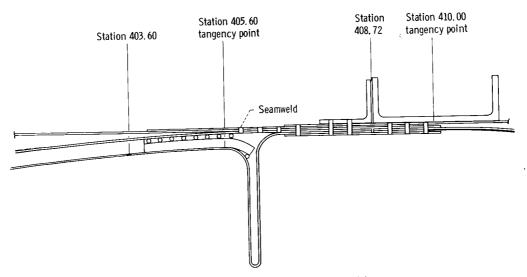
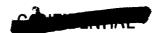


Figure X-14. - Details of station 408 joint of AC-4 vehicle.





XI. VEHICLE MODAL BENDING DYNAMICS AND VIBRATIONS

SUMMARY

During the booster phase of flight from launch to BECO, bending-mode oscillations were quite low in magnitude and, as in the AC-3 flight, this flight was relatively "quiet." Longitudinal and lateral oscillatory motions were similar to those in AC-3 except that second-mode lateral motions were prominent during the early booster phase of flight. Longitudinal frequencies at this time were of the same nominal values. Shortly after lift-off and also during MECO transient a brief-duration excitation occurred in the payload area.

The vibrational environment of the AC-4 flight, as monitored by 23 accelerometers (fig. XI-1), was similar to both AC-2 and AC-3 (table XI-I) and was well within design proof test levels. In general, the largest vibrations occurred either at lift-off or during the transonic region (50 to 80 sec after launch).

MODAL BENDING DYNAMICS

Longitudinal and lateral low-frequency oscillations during the booster phase of flight (launch to BECO) were of low amplitude and were comparable to those experienced on AC-3. Second-mode bending was most prevalent during the first half of booster phase and first-mode bending during the second half.

Three occurrences of longitudinal excitation were evident from the Atlas axial accelerometer (AAl65 ϕ), and were similar to excitations encountered on flights AC-2 and AC-3, as shown in figure XI-2. Lift-off perturbations resulting from Atlas LOX pressurization instability occurred at launch and decayed by approximately T + 12 seconds. The oscillatory frequency was 6 cps with a maximum of 0.15 g single amplitude near launch. The duration, frequency, and amplitude compare closely with the values from AC-2 and AC-3. "Pogo" type oscillations occurred several times from mid-booster phase to BECO with the frequency varying from 11.5 to 12 cps and a maximum single amplitude of 0.12 g. AAl65 ϕ indicated "pogo" from T + 80 to T + 92, T + 134 to T + 136, and T + 146 seconds to BECO. A 0.1-second-duration engine cutoff transient immediately after BECO was evident from the data that indicated an amplitude of 1.5 g's from zero to peak at a nominal frequency of 90 cps. The Atlas roll-rate gyro measurement (AS52R) showed this excitation at the same frequency.

Lateral modal bending was of very moderate magnitude being less, in general, then that on the AC-3 flight. First and second modal frequencies were of a higher value than those predicted by the GD/A analytical model. A comparison is shown in figure XI-3 including plots of data from Lewis Research Center vibration facility tests on an Atlas-Centaur vehicle. As shown, the flight data



more closely duplicate the vibration facility test frequencies than the predicted frequencies. The first mode is approximately 1/2 cps higher and the second mode 1/2 cps higher than the predicted modal frequencies. The lateral accelerometer measurements (CA8 ϕ and CAlO ϕ), the Centaur rate gyro measurements (CS70R, CS71R, CS69R, and CS73R)and, where applicable, the Atlas rate gyro measurements (AS53R and AS54R) indicated approximately the same frequencies at comparable flight times thereby adding confidence to the values.

The amplitudes of first modal bending were obtained by reduction of Centaur rate gyro data. Figures XI-4(a) and (b) show these amplitudes for pitch and yaw, respectively. Predicted mode shapes are shown normalized to the amplitudes measured by the rate gyros located at station 173. The gust design criteria at station 173 for T + 40 and T + 80 seconds are also plotted with the predicted mode shapes normalized to these criteria. Flight amplitudes are seen to be quite low and but a fraction of the design criteria. In figure XI-5, both first and second modal amplitudes from the flight data are shown as well as gust design criteria for several flight times. Second modal amplitudes are seen to be well below the design levels. Figure XI-6 depicts maximum first modal elastic bending amplitudes at station 173 for AC-2, AC-3, and AC-4. The AC-4 amplitudes are generally of smaller value or nonexistent.

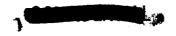
At approximately T+0.5 second, one cycle of 1.1-g (P-P) oscillation (at 6.5 cps) occurred at the forward end of Centaur (station 173), as indicated by the lateral accelerometer pitch plane measurement (CA8 ϕ). The retromotor mass measurement (CY72 ϕ , station 116) indicated a 2.6-g (P-P) excitation in the payload mass area at the same time increment. These amplitudes fit the second mode shape as defined by the Lewis vibration facility test data. To date, no event or disturbance has been uncovered that might have caused this perturbation.

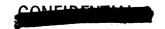
At MECO, as a result of engine shutdown transients, the payload area experienced a longitudinal oscillatory motion with a relatively high negative load. The disturbance started at MECO and lasted for 1/3 second with a frequency of 28.5 cps. Strain gages CA491S (0°), CA492S (120°), and CA493S (240°) gave the best indication of the amplitude of this disturbance and showed negative g values (zero to peak) of approximately 1.5, 1.6, and 1.6, respectively. The longitudinal accelerometers located in the payload area failed to indicate this disturbance because of time sharing. Also, the Centaur axial accelerometer (CM101A) failed to verify it because of the low-frequency response of the transducer.

VIBRATIONS

Maximum Vibrations

The vibration environment of the AC-4 flight, as monitored by 23 accelerometers (fig. XI-1), was similar to both AC-2 and AC-3 (table XI-I) and was well within design proof test levels. In general, the largest vibrations occurred either at launch or during the transonic region (50 to 80 sec after launch).





The largest vibrations (table XI-II) occurred in the interstage adapter during the transonic portion of flight. Measurement of panel radial acceleration (AAl64 ϕ) indicated 96.5 g's peak to peak (P-P) after 61.4 seconds of flight. The largest vibration in the propulsion area was measured on the boost-pump fairing, station 407 (CA398 ϕ), at 91.6 seconds, where the peak to peak value was 13.9 g's. The wire tunnel, station 223.5 (CA392 ϕ), indicated the largest vibration in the equipment area, 24.9 g's P-P at 79.5 seconds in the transonic region.

During launch, the payload experienced its maximum vibration (table XI-II). At T + 1.4 seconds, the transducer located at the top of mast sensing in the y-direction (CY75 ϕ) indicated 15.0 g's P-P at a frequency of 6.3 cps. The maximum vibration level of the lower end of the payload was also in the y-direction CY72 ϕ (retromotor mass y) indicated 2.64 g's P-P at a frequency that was approximately the second mode natural frequency: this occurred after 0.47 second of flight.

Vibration Profile

A spectrum analysis (Bruel and Kjaer one-third octave analyzer) was performed on the vibration accelerometer data to determine the frequencies of maximum energy concentration (the analysis frequency ranged from 40 cps to the upper frequency band of the data channel, or 2000 cps, depending on which was lower).

The vibration environment of the interstage adapter was predominately sinusoidal with a maximum energy concentration of 0.2 g²/cps and a frequency of 50 cps. There were other predominant sinusoids at both 200 and 1000 cps (fig. XI-7). In the propulsion area (fig. XI-7(b)) the largest energy concentration was experienced by the C-2 hydraulic power package y-axis a few seconds after first main engine start of the Centaur (0.0175 g²/cps at a frequency of 800 cps). In general, the vibration profile in this area was predominately random with sinusoids at only a few discrete frequencies. The Centaur equipment area vibration profile (fig. XI-7(c)) was predominately random with the largest energy concentration (0.13 g²/cps at 300 to 400 cps) evidenced at maximum q by the wire tunnel at station 223.5 (CA392 ϕ).





TABLE XI-I. - COMPARISON OF AC-3 AND AC-4 MAXIMUM VIBRATIONS

	T		-		
Event		1.83 211.5 to Nose-fairing 212.5 jettison	211.4 to Nose-fairing 212.4 jettison	1.7 to Booster 152.7 jettison	61.4 to Transonic 62.4
Time, sec	226.6 to 227.6	211.5 to 212.5	211.4 to 212.4	28.4 151.7 to Booster 152.7 jettis	61.4 to 62.4
AC-4 g's, P-P	5.5	1.83	5.6	28.4	
Event	216.6 to Nose-fairing 217.6 jettison	Transonic	Transonic	Lift-off	96.5
Time, sec	216.6 to 217.6	87.4 to 90.4	8.56 54.1 to 55.1	20.6 to 21.6	86.8 to 87.6
AC-3 g's, P-P	3.4	1.2	8.56	42.8	34.4
Measure-AC-3 ment g's, P-P	CA26p	CA27p	CA343p	AA161φ 42.8	AA164p
Location	Battery mounting x-axis	Near A/P gyro package z-axis	Umbilical island accelerometer S/94 Q1 CA343 ϕ	Adapter radial \mathbb{Q}_{1} and \mathbb{Q}_{2}	Panel radial Q_2 and Q_3

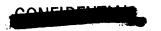
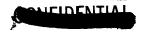
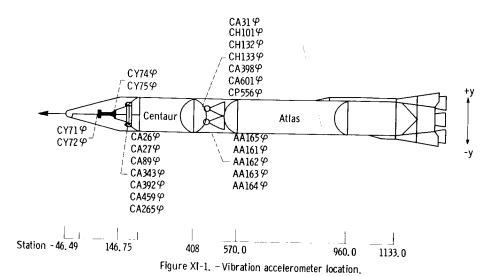


TABLE XI-II. - MAXIMUM VIBRATIONS

	Measure- Time, Maximum Frequency band of Comments ment sec g's data channel, reps	AA165φ 151.8 to 152.8 8.95 0 to 45 56.5 cps	(radial) AA161p 151.7 to 152.7 28.9 0 to 220 AA162p Only visible deflection 0 to 1200 was a 4 C separation 0 to 1200	O to 2000 High frequency, transonic regio	CASIQ 47.6 to 48.6 1.88 0 to	CH1359 432.1 to 433.1 7.35 0 CH1359 237.7 to 238.7 9.13 0	CA5380 91.6 to 92.6 13.90 0 to CA6010 58.4 to 59.4 3.81 0 to to case 504.8 to 505.8 4.42 0 to	2	CA26\$\therefore\ 226.6 to 227.6 \\ 5.5 \\ 0 to \\ 212.5 to 212.5 \\ 1.83 \\ 0 to \\ 2.0 to \\ 0.0 to \\ 0.	Ex. 5 CA3450 211.4 to 212.4 CA3450 79.5 to 80.5 25.5 CA4590 198.5 to 199.5 100.5 to 100.5		212.4 to .5 to 92.9 to	to 2.5
Location		Tutometode adanter Z-axis	rstage adapter (radial)	Ring Q1 and Q4 Panel radial Q2 and Q3			on			er S194 Q1 23.5	LH2 boil-off valve	Payload Retromotor mast x-direction Retromotor mast y-direction	Top of mast v-direction







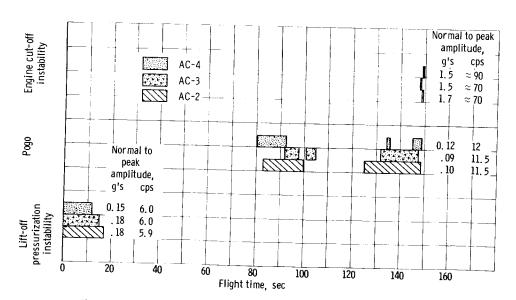


Figure XI-2. - Longitudinal oscillation occurrences, frequencies, and maximum amplitudes.

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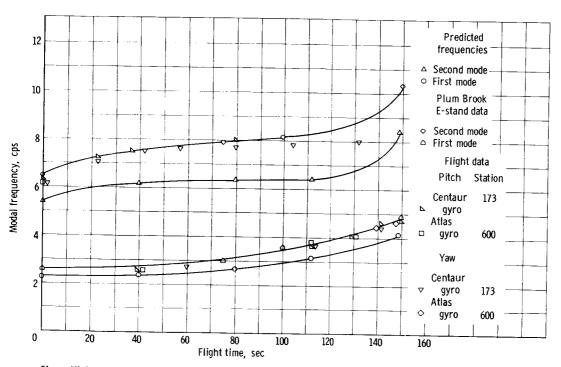
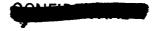


Figure XI-3. - Predicted, experimental, and flight data lateral modal frequencies for AC-4 Atlas-Centaur elastic bending.



CONCIDENTIAL

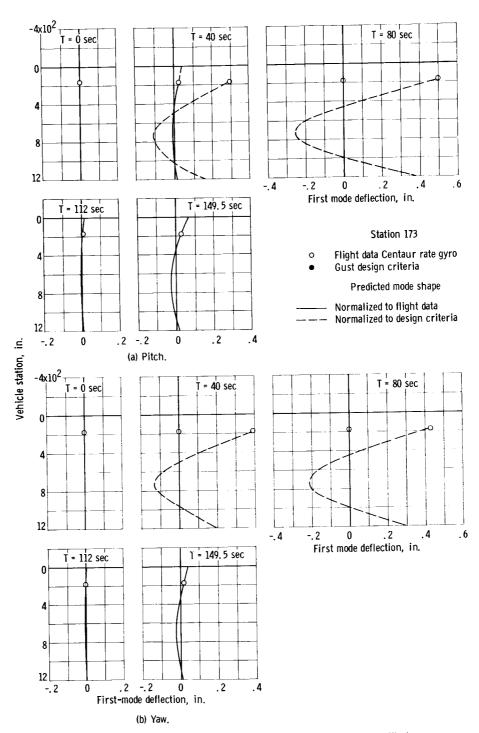


Figure XI-4. - Flight and design wind-gust lateral bending modal amplitudes.

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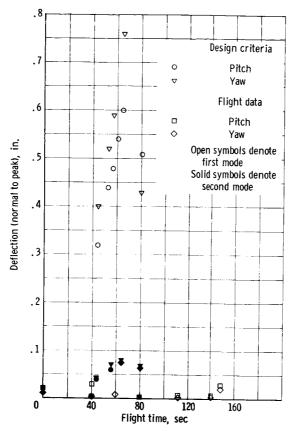


Figure XI-5, - Flight data and design criteria for wind-gust modal amplitudes pitch and yaw planes at station 173.

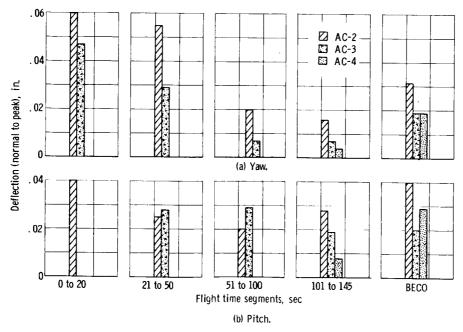


Figure XI-6. - Maximum first modal amplitudes at station 173 for AC-2, AC-3, and AC-4.



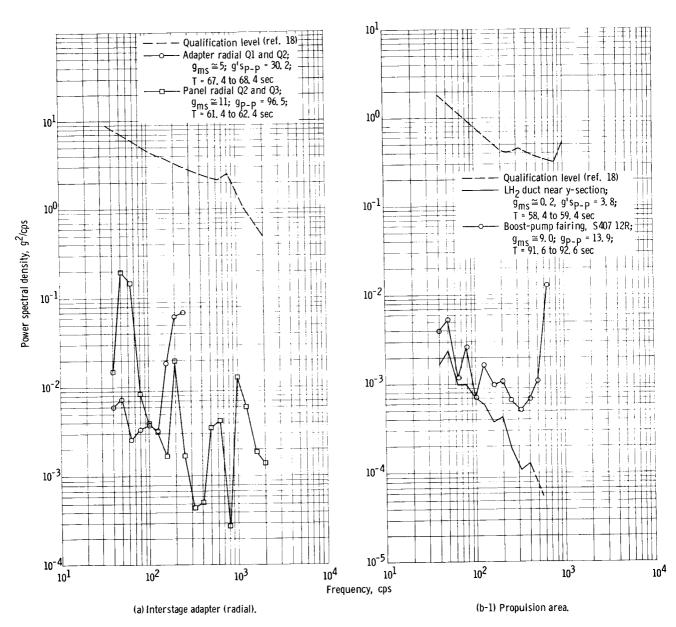
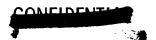


Figure XI-7. - AC-4 vibration levels.



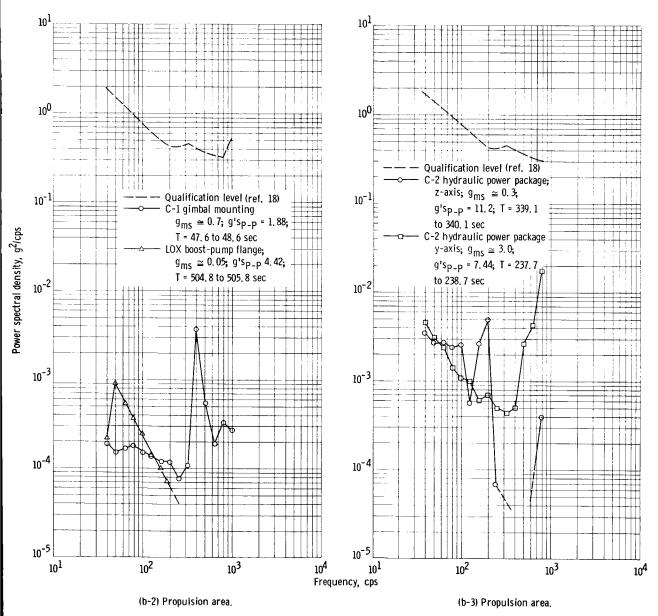
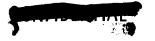


Figure XI-7. - Continued.



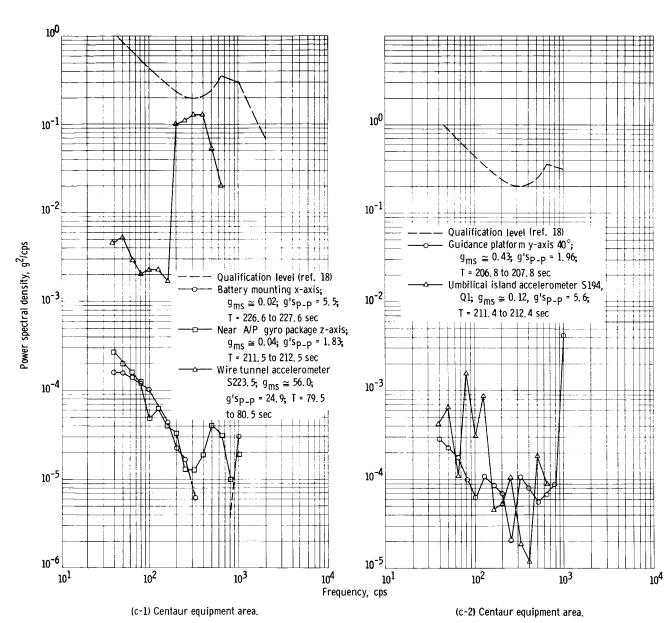
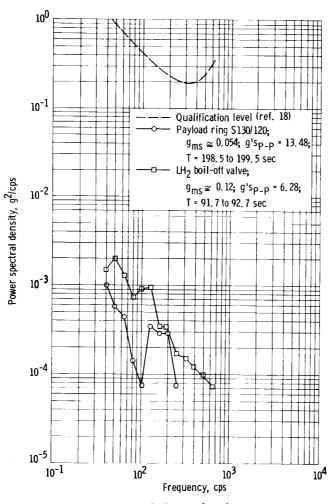


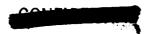
Figure XI-7. - Continued.





(c-3) Centaur equipment area.

Figure XI-7. - Concluded.



XII. FLIGHT CONTROL SYSTEM

SUMMARY

Analysis of telemetry data indicated that AC-4 control system performance was satisfactory until T + 840 seconds at the start of LH₂ venting during the first coast period. Observed responses during Atlas boost and Centaur first burn followed closely predicted limit cycle frequencies and amplitudes.

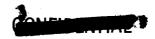
ATLAS

At lift-off, a high-frequency vibration near the natural frequency of the second bending mode (35 rad/sec) was observed in both pitch- and yaw-rate gyros. Peak-to-peak amplitudes averaged 0.1 degree per second in both planes and decayed in approximately 2 seconds after lift-off. Similar oscillations were observed on the AC-3 flight.

Following lift-off, the Atlas booster flight was smooth through the entire atmospheric ascent. No transients or oscillations of unusual magnitude were observed from telemetry until BECO when the Atlas roll- and pitch-rate gyros showed a diverging oscillation at the limit cycle frequency of the Atlas LOX sloshing mode. The diverging oscillation started at approximately 7 seconds prior to BECO, reaching peak-to-peak rates of 3.47 degrees per second in roll and 1.18 degrees per second in pitch at a frequency of 1.6 cps as telemetered from the Atlas rate gyros. These oscillations discontinued with the initiation of BECO. Figure XII-1 shows the time history of the vehicle responses at BECO.

Root locus analysis had predicted a stable limit cycle for the Atlas LOX sloshing mode prior to BECO. The engine limit cycle amplitude from analysis is approximately 0.82 degree peak-to-peak. Figure XII-1 shows the booster 1 and 2 engines at a maximum peak-to-peak amplitude of 0.9 and 1.3 degrees, respectively. A similar divergence had occurred on AC-3, although amplitudes were smaller. The coupling into the roll plane, however, had not been predicted by analysis. Figure XII-2 shows a comparison of AC-3 and AC-4 roll rates as measured by the Centaur roll-rate gyros. Prior to BECO, the primary difference in the auto-pilot configuration is the nominal operating gain $(K_{\rm A})$ of 1.0 degree per degree; an increase of approximately 15 percent over the AC-3 position gain of 0.87 degree per degree. Consequently, larger amplitudes were to be expected over AC-3 responses. The following table shows a comparison of autopilot, engine, and sloshing parameters for AC-3 and AC-4.





Parameter	AC-3	AC-4
BECO (discrete), sec	147.8	148.3
Position gain, Ka, deg/deg	.87	1.0
Engine limit cycle amplitude (peak-to-peak), δ, deg	. 70	.82
Atlas LOX limit cycle frequency, $\omega_{ ext{A-LOX}}$, cps	1.6	1.6

The physical inertial properties of the vehicle show that pitch oscillations have a strong tendency to couple in roll. No diverging oscillations were observed which indicates booster engines gimbaling differentially (the primary source of booster-phase roll control). The booster engines, however, are complemented by a sensitive vernier roll-control moment that effectively reduces roll-limit-cycle amplitudes caused by booster-engine dead zones. Also, roll signals into the booster vernier engines are not led through an integrator-filtered feedback network. As a result, the unsymmetrical autopilot configuration tends to null out small oscillations in roll with the vernier engines.

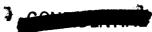
Attempts to duplicate the diverging oscillations at BECO on the GD/A six-degree-of-freedom analog simulation using nominal control gains and filter failed to show the type of responses observed from telemetered data. It was possible, however, to determine the control gains and filter required to obtain the diverging oscillation: (1) position gain, 115 percent of nominal; (2) rate gain, 126.5 percent of nominal; (3) filter, approximately 85 percent of nominal. Analog runs with these gains showed good correlation with test data, both in amplitude and frequency. Figure XII-3 shows the roll, pitch, and yaw rates that are directly comparable with those of telemetered data.

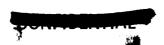
There appears to be no single cause for the diverging oscillation. Possible sources of gain and filter variations are (1) autopilot tolerances, (2) increased acceleration, which can be interpreted as a direct increase in static gain, (3) increases in the Atlas inverter frequency, and (4) unknown engine gimbal friction that determines engine dead-zone deflections.

Following BECO, telemetry shows small oscillations in rigid-body first-modal bending and Atlas LOX sloshing. Jettison of the insulation panels and the nose fairing excited the first bending mode as observed from the Centaur yaw-rate gyros. Peak-to-peak amplitudes were very small (0.1 deg/sec), thus, no oscillations were observed in pitch. Figure XII-4 shows a plot of predicted and flight test frequencies from lift-off to SECO. The predicted frequencies are limit-cycle frequencies as calculated by time-slice studies using rootlocus techniques. Flight test frequencies are those observed from telemetry of yaw- and pitch-rate-gyro outputs.

CENTAUR

The observed ignition transient was the smallest recorded to date (see fig.





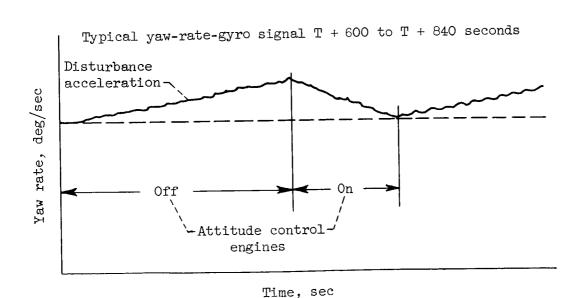
XII-5), indicating small differential thrust buildup of the RL-10 engines. Observed rates were 0.38 degree per second yaw, 1.02 degrees per second pitch, and 1.17 degrees per second roll. Centaur powered history was smooth, and no significant oscillations occurred during the remainder of the flight. From the Centaur rate gyros, frequency data were obtained and plotted with predicted frequencies against flight time. Figure XII-4 shows the good correlations between the predicted and flight test data.

The coast phase followed first MECO and was to terminate approximately 1477 seconds later with the initiation of second MES. The coast-phase attitude control system maintains an attitude reference that is alined with the local horizontal and in the plane of the trajectory, but allows roll drift to a threshold.

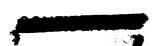
Telemetry showed that the vehicle was maintaining its attitude as commanded with sporadic corrections in pitch and roll, and a nearly constant 30-percent duty cycle in yaw until T + 840 seconds when venting forces exceeded the capability of the attitude control engines (see fig. VI-20).

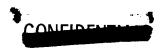
Failure of the ullage rocket to settle the propellant and the subsequent venting of liquid and gaseous mixtures of LH2 coupled with the large buildup of rotational rates and decline of fuel tank pressure, starved the fuel boost pump, aborting the second MES.

Temperature transducers at the forward bulkhead indicated wet immediately following MECO and continued to remain wet for the remainder of controlled coast (see section VII. CENTAUR PROPELLANT SYSTEMS). This indicated that the axial accelerations imparted to the vehicle by the forces of the two ullage rockets were insufficient to settle and maintain the propellants during the controlled coast period.



(a)





To obtain some indication as to the behavior of the propellants prior to venting, the yaw-rate-gyro signal was analyzed, since it showed a regular "on-off" pattern of the attitude control engines. The preceding sketch shows the rate-gyro pattern observed from telemetry. The disturbance acceleration, defined as the slope of the curve where the attitude control engines are off, is an indication of the disturbance torques acting on the vehicle. Major sources of these torques are

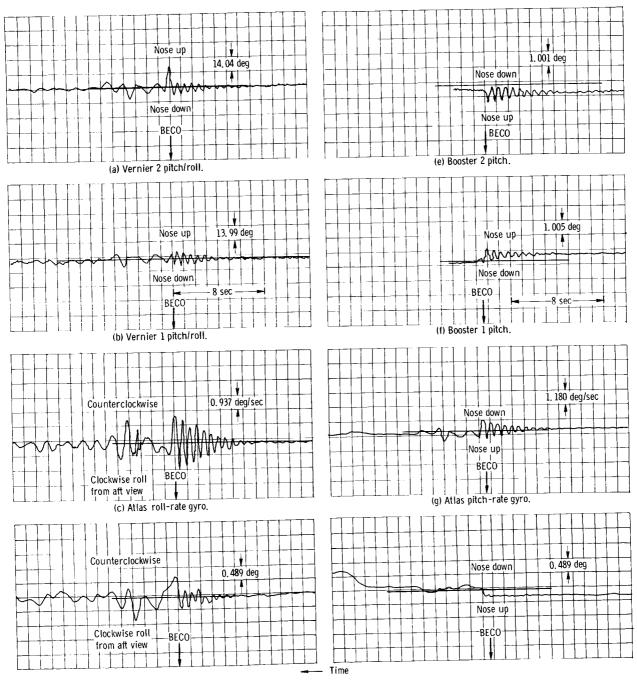
- (1) Ullage jet thrust misalinement
- (2) Ullage jet impingement against the main engine bells
- (3) Center of gravity offsets caused by propellant motion

Figure XII-6 shows the disturbance accelerations from approximately 100 seconds prior to LH₂ venting. A nearly constant disturbance acceleration is noted averaging 0.012 degree per second squared. This results in disturbance torques of 8.4 to 9.4 foot-pounds depending on the mass moment of inertia. Ullage jet thrust misalinements and impingement can account only for 5 foot-pounds of torque. Lateral center-of-gravity offset from the longitudinal axis is the only major contributing source of torque remaining. In figure XII-7 a curve relates center-of-gravity offset with ullage jet impingement forces. Analysis has shown that impingement forces are of the order of 0.26 pound. From figure XII-7 this results in center-of-gravity offsets averaging 12 inches. This is the center-of-gravity offset in the yaw plane on an axis toward the boost pump.

The relation between center-of-gravity location and mass moment of inertia as calculated from the vehicle dynamics and from the vehicle mass properties is shown in figure XII-8. No physical significance is meant to be given by the curve drawn through the points that relates center of gravity and moment of inertia by mass properties. Actually, several other points could be calculated by assuming other propellant locations that would not fall on a line between an empty vehicle case and a propellant settled and rigid case. The figure does show, however, the center of gravity and mass moment of inertia relation that must have existed to obtain the vehicle dynamics observed from telemetry. Venting force calculations using the range of center-of-gravity location and mass moment of inertia shown in figure XII-8 indicated forces between 8 and 10 pounds were acting on the vehicle.



- COMMITTEE TO



(d) Atlas roll-displacement gyro.

(h) Atlas pitch-displacement gyro.

Figure XII-1. - AC-4 responses at BECO.



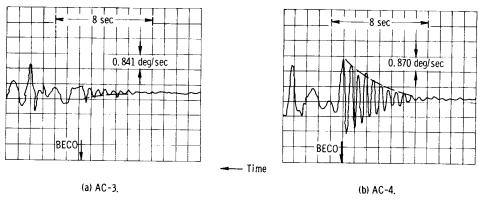


Figure XII-2. - Comparison of AC-3 and AC-4 roll rates at BECO measured by Centaur roll-rate gyro.



PONCIDENT

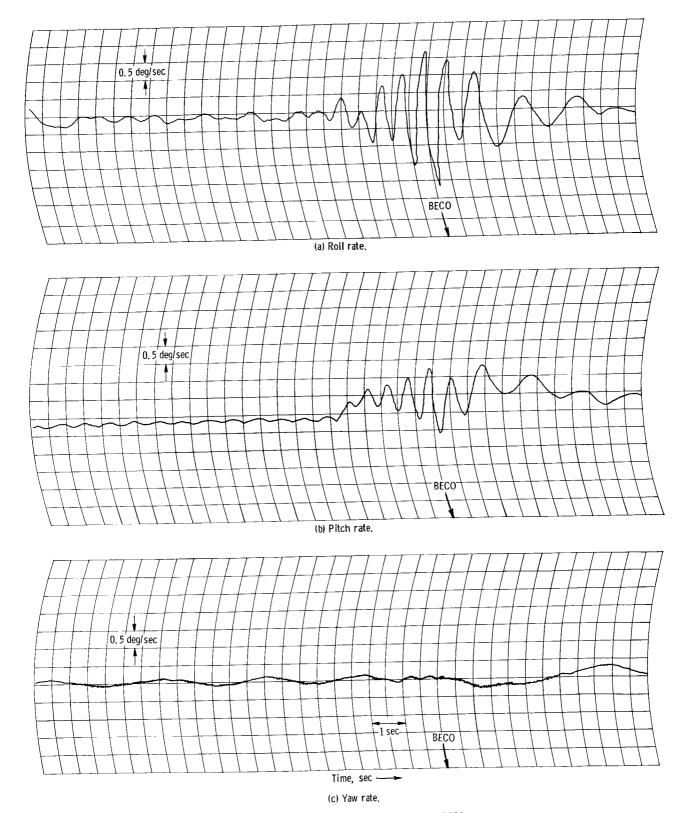
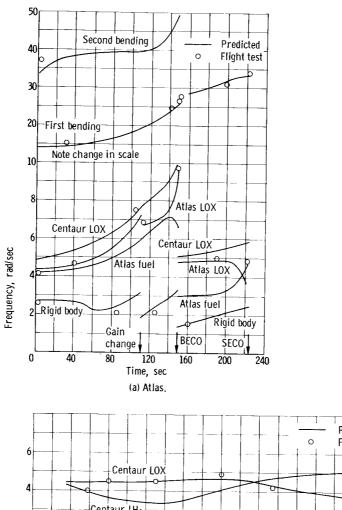


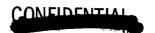
Figure XII-3. - Analog simulation outputs at BECO.





Predicted Flight test Centaur LH₂ Rigid body MES MECO 0 200 240 280 400 Time, sec 320 360 440 480 520 560 600 (b) Centaur.

Figure XII-4. - AC-4 Predicted and flight test frequencies during powered flight.



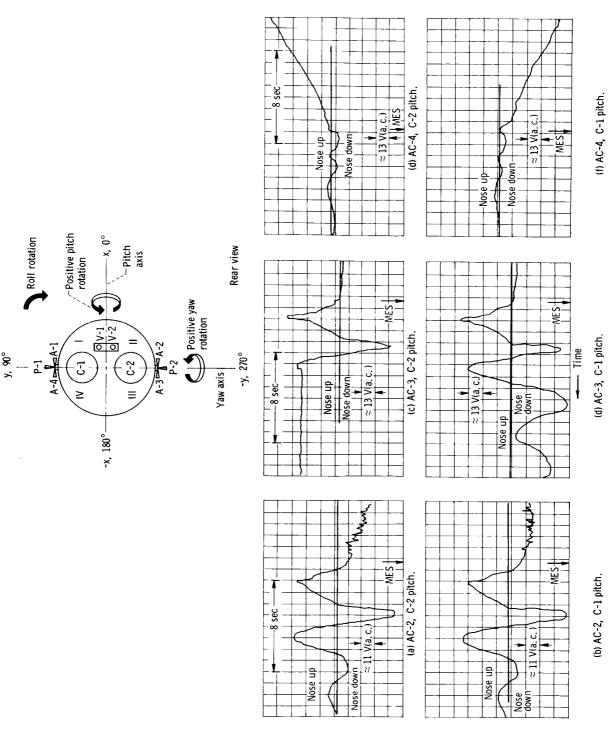


Figure XII-5. - Comparison of Centaur pitch-engine deflections as MES.

ACMEDENTIAL

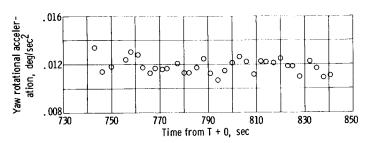


Figure XII-6. - Yaw rotational accelerations as function of time. Accelerations were measured with attitude engines off.

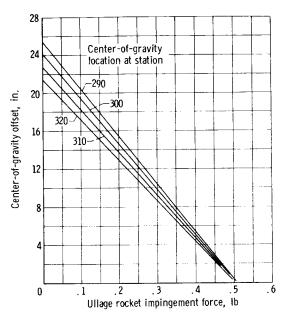


Figure XII-7. - Center-of-gravity offset determination as function of ullage rocket impingement.

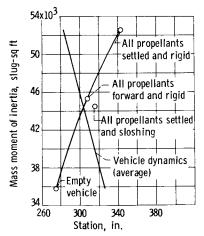
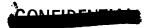


Figure XII-8. - Mass moment of inertia and center-of-gravity determination at time 14:38:00 (midcoast).





XIII. GUIDANCE

SUMMARY

The Centaur inertial guidance system performed satisfactorily throughout the prelaunch countdown and the flight with the velocity errors, shown in the following table, extrapolated to burnout (T + 580 sec).

Axis	Velocity error, ft/sec	Nominal specification value, ft/sec
U	0.5	<12
V	1.0	<23
W	7.0	<12

Figure XIII-1 shows a comparison of guidance minus BET velocity (ref. 19). A block diagram of the Centaur inertial guidance system is shown in figure XIII-2.

A discrepancy existed, however, between telemetered computer digital torquing command for the W-gyro and the analog output of this signal. From analysis of the guidance system velocity comparisons, it is concluded that the telemetered analog data were not a valid indication of the gyro torquing rate.

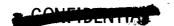
PERFORMANCE

Prelaunch Countdown

The Centaur inertial guidance system MGS 24 (table XIII-I) was calibrated on F - 1 day to verify parameter stability. Power was applied to the system throughout the night to ensure continued parameter stability (preclude any shutdown transient effects). On F - 0 (launch) day the system was again calibrated. Shifts in the critical gyro and accelerometer loop parameters were well within the specification limits.

The guidance countdown was normal until T - 90 minutes, when a momentary dropout of inverter power occurred during a Centaur power changeover. The guidance computer storage (D and J values) was read out to ensure that there had been no change. To verify that the power interruption had not affected inertial component calibration, the KSC ground computer was used to determine the U- and V-gyro constant torque parameters. These were consistent with





previous values. In addition, the W-accelerometer performance stability was indicated by a 10-minute count of acceleration pulses. This also was satisfactory.

Optical azimuth alinement was used for the first time on AC-4. The performance of this system was satisfactory throughout the countdown.

Flight

The guidance system was switched to the "inertial mode" at T - 7.755 seconds. Throughout the early portion of flight, normal response to the rigid body and sloshing frequencies was observed in the gimbal servoloops. The platform (gimbal 4) uncaged at 20° pitch angle (determined by integration of pitch-rate-gyro outputs). The guidance steering loop was closed at BECO + 10 seconds. Resolver chain outputs remained at null through SECO, indicating that the booster was steering to the computed vector. Transients observed on the resolver chain outputs and inputs at T + 224.37 seconds are the results of temporary loss of power to the signal conditioner, which normally occurs when the interstage umbilical is ejected. Since the resolver outputs were near null from MES through MECO, the vehicle continued to follow the computed vector. For computer operation regarding inflight telemetry sequence, discrete issuance, and codeword change times see tables XIII-II to IV.

The only guidance anomaly that occurred during powered flight was a step change in the W-gyro torquing potentiometer voltage (figs. XIII-5) at T + 212.47 seconds. The magnitude of this step change (about 2 percent) is approximately the same as TLM resolution and is believed to be attributable to a malfunction in the W-channel amplifier module in the guidance signal conditioner. The U-and V-gyro torquing traces (figs. XIII-3 and 4) are normal.

Functional Performance

The computer digital steering value minus the telemetered analog value as a function of time is shown in figures XIII-6 to 8. Analysis indicates that this difference was held to zero within instrumentation accuracy. The computer generated missile actual velocity and the missile nominal velocity that was expected to be generated are shown in figures XIII-9 to 11. The guidance computer correctly calculated the missile velocity that closely approximated the nominal expected velocity as a function of time.

Missile position and nominal position are shown in figures XIII-12 to 14. The guidance computer correctly calculated the missile position that closely approximated the nominal expected position as a function of time.

The guidance torque motor inputs shown in figure XTII-15 indicate that nominal performance with no abnormally high transients to the platform existed during the periods of Atlas boost, separation, and Centaur burn. Data recorded after Centaur MECO, during the initial coast, and subsequent vehicle tumbling indicated that the platform was maintaining stability.





Analysis of the resolver chain inputs and outputs (fig. XIII-16) indicates that after BECO (when guidance was admitted for steering) the vehicle followed the steering commands. Nominal transients occurred at BECO, SECO, and MECO.

The guidance system component temperature environment was within the specified range of 30° to 130° F (fig. XIII-17). There was an increase of approximately 25° F in all four units listed from the prelaunch temperatures of 40° to 55° F.

The guidance system platform skin temperature (fig. XIII-18) indicated a normal rise from lift-off to T + 800 seconds, where it appeared to stabilize within 5° for the next 2100 seconds of flight.

CONCLUDING REMARKS

An attempt was made to fit the velocity error curves with the known shapes of several possible sources of system errors. This yielded two solutions, both of which fit the V-error curve extremely well, but varied slightly in the U- and W-fits. Significant portions of inaccurate tracking information contributed largely to the uncertainty between the two solutions. Both solutions contain the identical error sources but differ somewhat in their magnitudes.

	Error source				
	V-gyro constant drift, deg/hr	W-accelerometer misalinement to U, mr	U-accelerometer scale factor, ppm	W-gyro constant drift, deg/hr	V-accelerometer misalinement to W, mr
Inflight shift spe-cifications	0.18	0.75	210	0.36	1.5
Solution: 1 2	-0.07 .15	0.16 .09	10 40	-0.085 .085	-0.24 .24

From these solutions, it is apparent that both are within the inflight shift specifications.



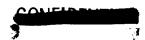


TABLE XIII-I. - MISSILE GUIDANCE SYSTEM 24

Component	Serial number	Accumulated hours
Platform	G7	1245
Platform Electronics	G8	819
Coupler	G12	556
Computer	007	1997
Signal Conditioner	G8	760

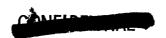
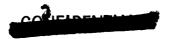


TABLE XIII-II. - AC-4 INFLIGHT TELEMETRY SEQUENCE

Telemetry order	Telemetered parameter	Discrete length (word times)	
02001	Definition	Symbol	(word ormed)
1	Thrust velocity, w-component	v_{tw}	6
2	Time	t_i	8
3	Thrust position, v-component	\mathtt{r}_{tv}	8
4	Thrust position, w-component	$r_{\sf tw}$	8
5	Thrust velocity, u-component	v _{tu}	8
6	Thrust position, u-component	$r_{ m tu}$	8
7	Thrust velocity, v-component	$v_{ ext{tv}}$	8
8	Inertial position, v-component	$r_{ m mv}$	8
9	Inertial position, w-component	r	8
10	Codeword	$A_0 \rightarrow A_{24}$	8
11	Inertial position, u-component	r _{mu}	8
12	Inertial velocity, w-component	v _{mw}	8
13	Inertial velocity, v-component	v_{mv}	8
14	Inertial platform torquing rate	ω du	8
15	Inertial platform torquing rate	ω _{dv}	8
16	Inertial platform torquing rate	w _{dw}	8
17	Square of thrust accelerationa	$\mathtt{a}_{\mathrm{Ti}}^{2}$	8
7.1	Energy to be gained ^b	$\epsilon_{ exttt{i}}$	8
18	Inertial velocity, u-component	v _{mu}	8
19	Steering vector	f*	10
20	Steering vector	f* w	10
21	Steering vector	f* v	10

^aTelemetered during booster phase only.



bTelemetered during sustainer and Centaur phases only.



TABLE XIII-III. - OUTPUT TIMES AND CRITERIA FOR DISCRETE ISSUANCE

Discrete	Time of ou	tput, sec	Criteria	Remarks
	Nominal	Actual		
BECO	150.36	148.807	$At^2 > E_5$ $E_5 = 0.2934 \times 10^5 \text{ ft}^2/\text{sec}^4$	Based on time when acceleration is sampled and when test is performed. Discrete would output at 5.51±0.08 g's. Actual was 5.50 g's. Time earlier than nominal due to booster high performance.
MECO	573.41	572.758	To enter cutoff subroutine $\varepsilon < E_{13}$ $13 = 0.12 \times 10^8 \text{ ft}^2/\text{sec}^4$	Actual was earlier than nominal due to higher than nominal energy gained during booster phase.

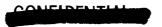
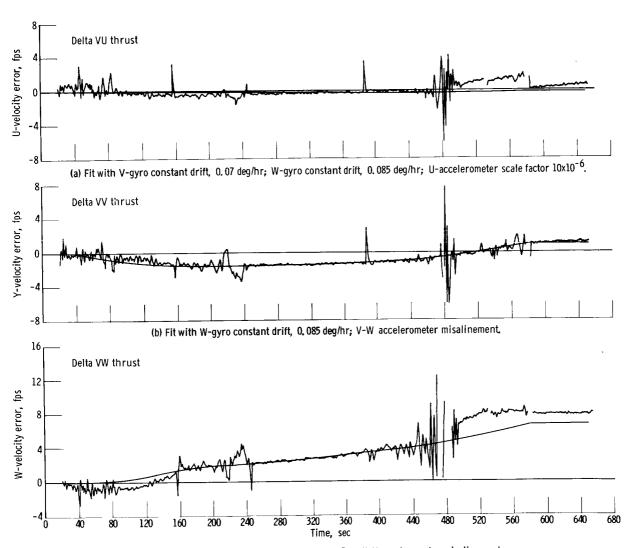


TABLE XIII-IV. - MAJOR CODEWORD CHANGE TIMES

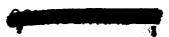
Ac- Initialize code word	Actual time of I telemetry,		
 		Nominal time of telemetry, sec (a)	
	1.415	1.415	First computer cycle - initialization per-
First cycle	2.545	2.545	
Second cycle	3.545	3.545	Second compute cycle of basic equations
test	147.731		Start performing test for BECO
	157.741		Pass BECO test
Sustainer guidance E6	160.031	015	Enter sustainer equations
Sustainer SR altitude Elo	165.041	165,805	Complete sustainer altitude control term
Sustainer integral E ₁	185.011	185.775	Enter integral control after stabilize to
control steering			I Vector
Centaur guidance Ell	236.469		Enter Centaur equations
ltitude	267.618	265.925	Complete Centaur altitude control term
correction			
Centaur integral El	280.148	278.454	Enter integral control after stabilize to "f" vertor
r.rug	(1
Rescale vector	201.00C	207.700	nescare i vector to racititado carta-
			Tartoll accuracy
Enter cut	579.511		Enter MECO test
Enter separate test	580.491		Els test
Enter postinjection E15	584.431	585.265	ed time from
de	585.431	586.265	Enter coast-phase rotating attitude con-
reference vector)			trol vector

anominal times from nominal closed-loop interpretive (COFLIC) run.



(c) Fit with V-gyro constant drift, 0, 07 deg/hr; W-U accelerometer misalinement, Figure XIII-1. - Comparison of guidance minus best estimate of trajectory velocity.





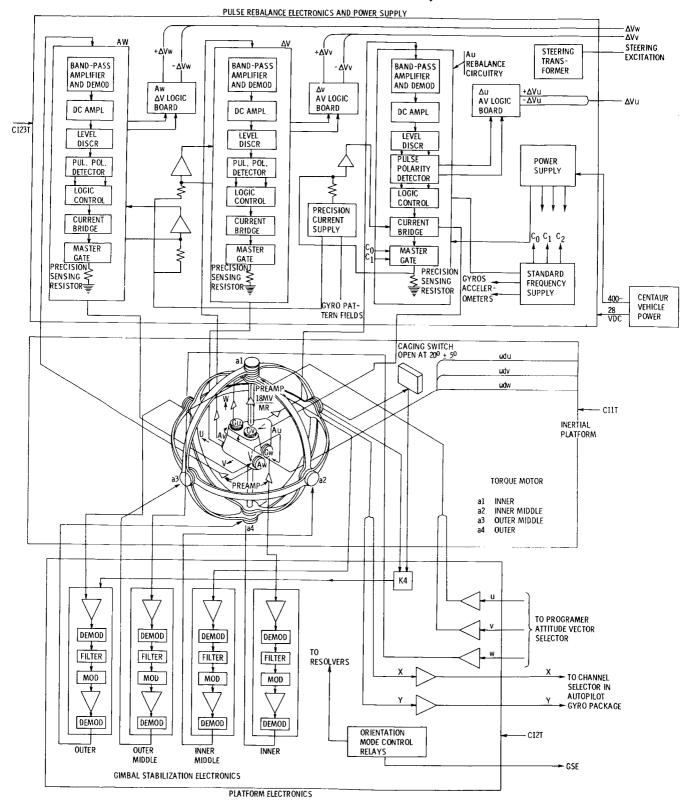
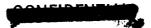
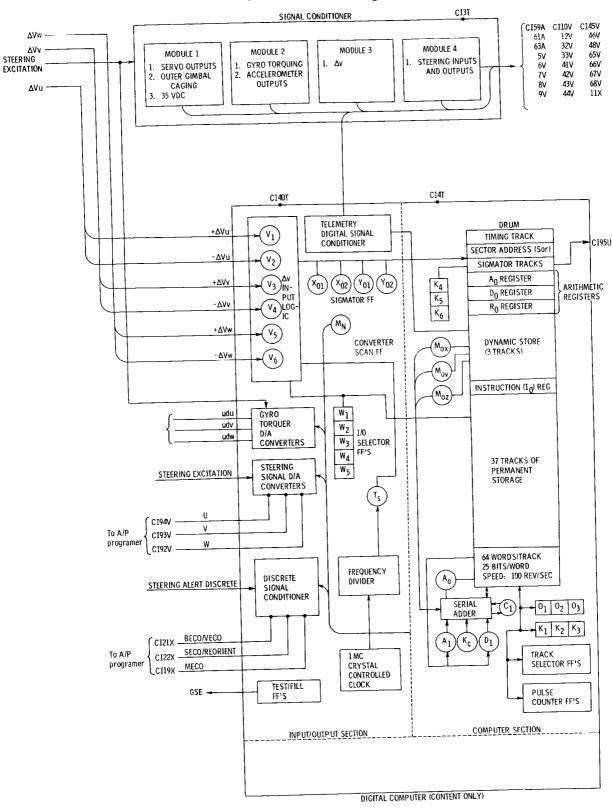


Figure XIII-2. - Centaur







quidance system.





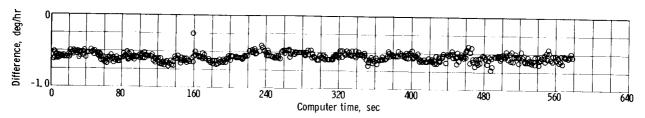


Figure XIII-3. - Computer gyro torquing digital value $W_{\mbox{DU}}$ minus telemetered analog value $\mbox{I 41 V}$ as function of time.

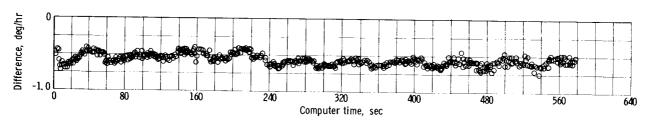


Figure XIII-4. - Computer gyro torquing digital value W_{DV} minus telemetered analog value I 42 V as function of time.

COMPLETE

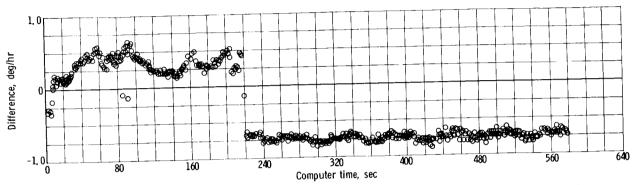


Figure XIII-5. - Computer gyro torquing digital value W_{DW} minus telemetered analog value I 43 V as function of time.

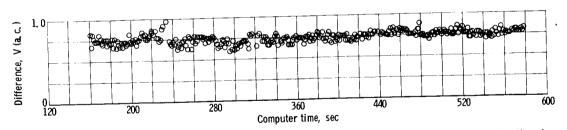
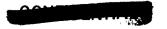


Figure XIII-6. - Computer digital steering value F_{CU} minus telemetered analog steering value I 8 V as function of time.



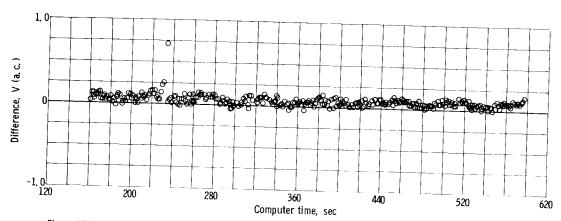


Figure XIII-7. - Computer digital steering value F_{CV} minus telemetered analog steering value I 9 V as function of time.

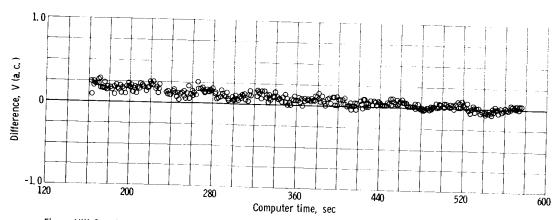


Figure XIII-8. - Computer digital steering value F_{CW} minus telemetered analog steering value $I\ 10\ V$ as function of time.

POWER

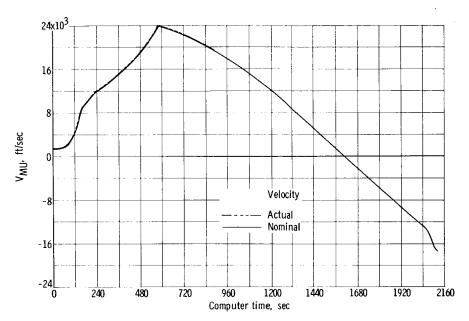


Figure XIII-9. - Missile velocity and nominal velocity as function of time for values of $\,{
m V_{MU}}$

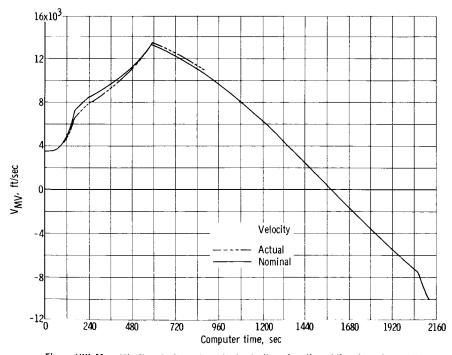


Figure XIII-10. - Missile velocity and nominal velocity as function of time for values of $\,V_{MV}$.



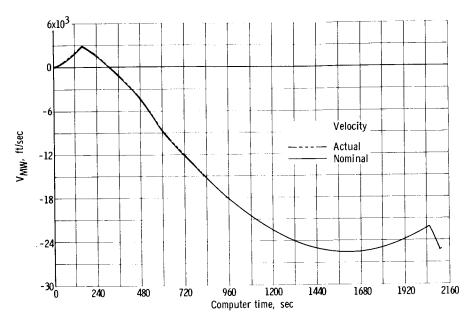


Figure XIII-11. - Missile velocity and nominal velocity as function of time for values of V_{MW} .

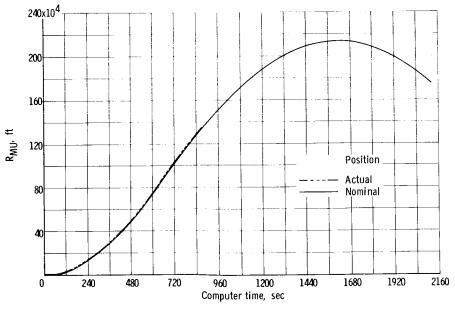


Figure XIII-12. - Missile position and nominal position as function of time for values of $\,R_{MU}$

20H

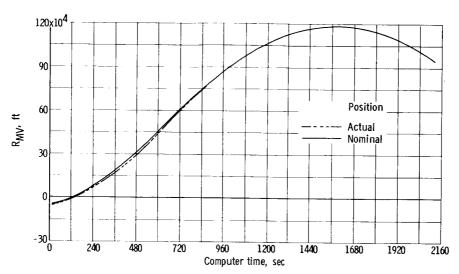


Figure XIII-13. - Missile position and nominal position as function of time for values of $\,R_{MV}$.

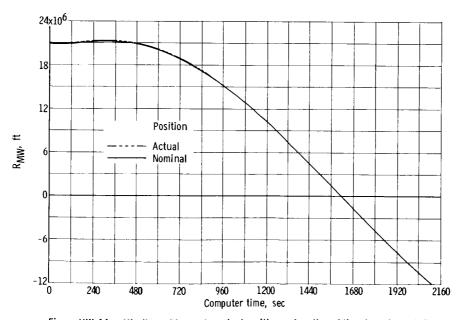


Figure XIII-14. - Missile position and nominal position as function of time for values of R_{MW}



CONFIDENTIAL

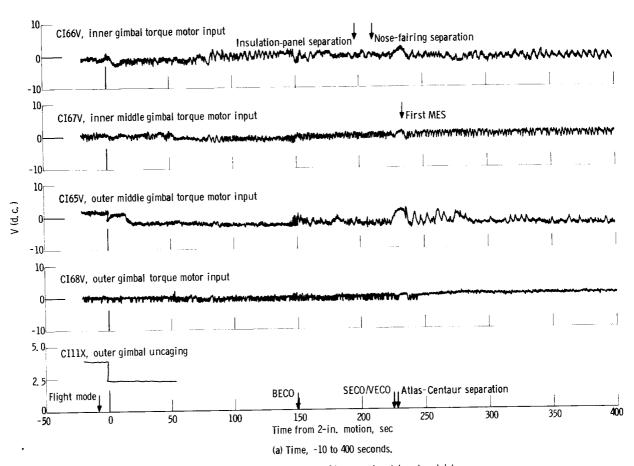
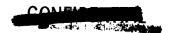
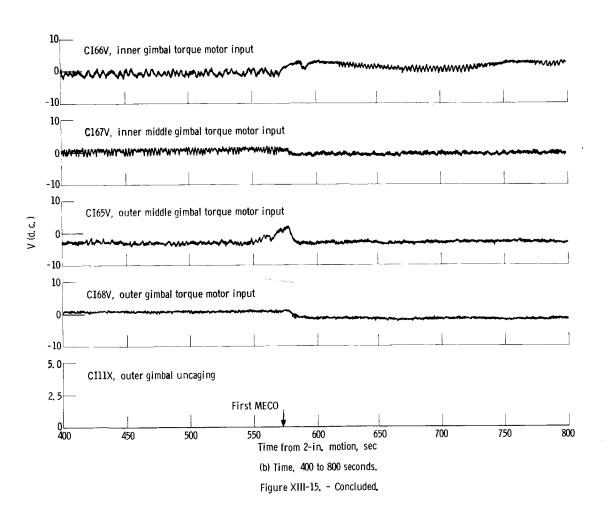


Figure XIII-15. - Centaur guidance system telemetered data.









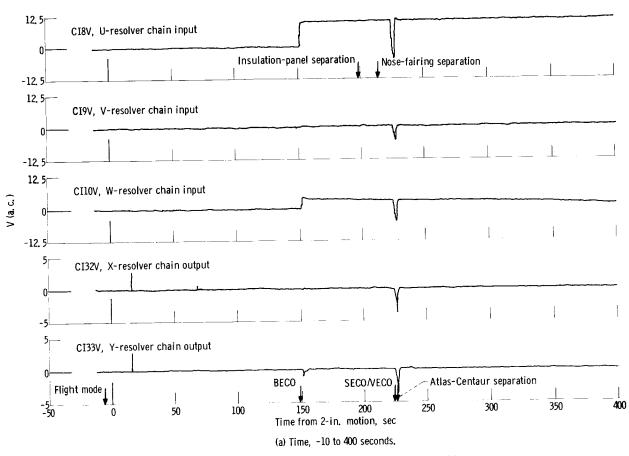
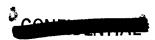
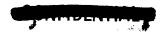
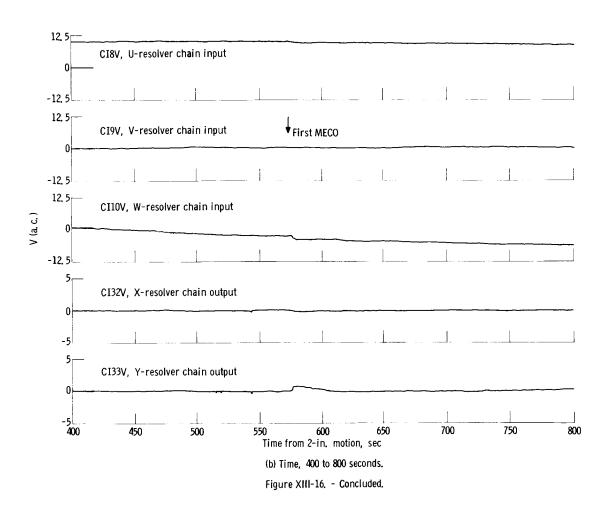


Figure XIII-16. - Centaur guidance system telemetered data.









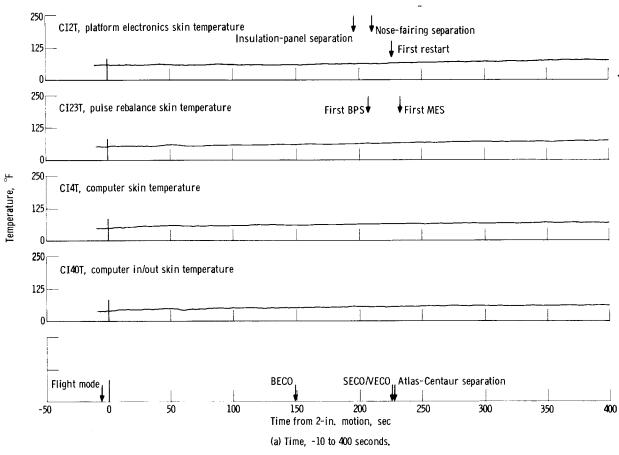
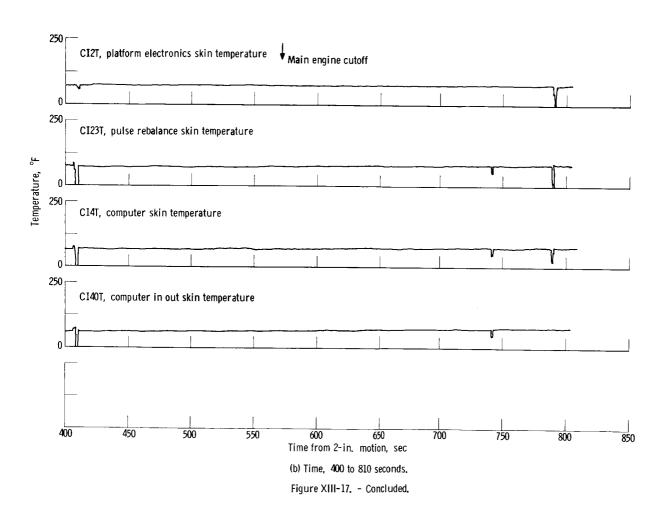
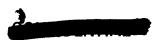


Figure XIII-17. - Centaur guidance system telemetered data.









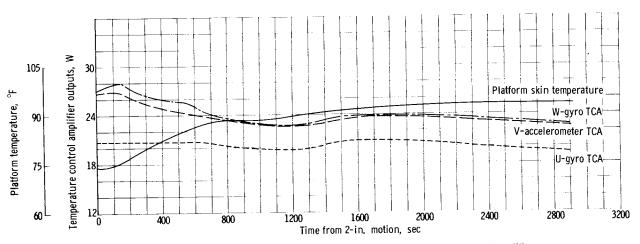
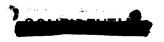
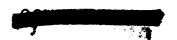


Figure XIII-18. - Platform skin temperature and component temperature control amplifier.





XIV. ELECTRICAL SYSTEMS

SUMMARY

The airborne electrical systems provide onboard electrical power storage, conversion, distribution, and protection, as well as fulfilling the requirements of instrumentation, telemetry, tracking, and range safety command systems. The electrical power system adequately supported the flight, with all red-line measurements within the specified limits and all other measurements at the expected levels. Figure XIV-1 shows the Centaur electrical system. The range safety system experienced no malfunctions during the flight, and performance of the tracking system was nominal.

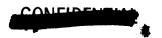
The operation of the Atlas-Centaur telemetry-instrumentation system was satisfactory. Normal operation was confirmed beyond the first four complete orbits. Generally, data quality was good. Continuous coverage was provided through T + 3480 seconds with the exception of a 100-second period between the range instrumentation ship, Timber Hitch, and Ascension Island. This data void occurred during coast phase after venting, and no significant data loss resulted. To measure Centaur vehicle performance, 455 measurements were telemetered; 97 percent of these yielded valid data. There were 175 Atlas booster measurements. The types of measurements made by the airborne system are shown in table XIV-I.

Several GSE peculiarities were noted during preflight testing: (1) the possibility of losing Atlas programer reset command during transfer from external to internal power, (2) loss of "guidance ready" command on umbilical ejection, (3) ripple problem on 28-volt d-c main-power bus, as well as (4) operator error coupled with equipment failure during tanking operations.

ELECTRICAL

Atlas Main Battery and Inverter

The Atlas battery voltage at lift-off was 29.3 volts d.c. and exhibited a gradual drift upwards to about 30.2 volts at T + 226 seconds, Atlas-Centaur separation. At T + 235 seconds, the voltage jumped to 31 volts, while at T + 320 seconds it returned to 29.3 volts d.c. The inverter voltage output for the three phases remained reasonably constant at 114.8 to 115.1 volts. Phase A voltage displayed a gradual downward drift from 115.1 volts a.c. at lift-off to 114.8 volts a.c. at T + 300 seconds, about 70 seconds after Atlas-Centaur separation. The inverter frequency varied from 402.1 to 402.5 cps throughout the boost and sustainer portions of the flight.





The Atlas inverter was deliberately set at 402 cps to produce a 2-cycle beat with the Centaur inverter. The beat frequency is outside of the lowest resonance of the vehicle and would not interfere with the steering signals fed to Atlas from Centaur guidance on a closed-loop flight.

Staging Disconnect

The staging disconnect actuator temperature dropped from 62° F at lift-off to approximately 8° F at separation, while the receptacle temperature decreased to the same separation temperature from 32.4° F at T - 0. The temperature at staging disconnect is marginal. On future vehicles, red-line temperature at T - 0 will be increased.

Centaur Main Battery and Inverter

During the countdown, a malfunction of the Centaur power changeover switch for 20 milliseconds at T - 90 minutes caused the Centaur inverter to drop out for approximately 180 milliseconds. This, in turn, caused the guidance power failure indicator to illuminate. Fortunately, the information stored in the computer was not affected.

The Centaur battery was 28.4 volts d.c. at lift-off, while at T + 3000 seconds, it appeared to be holding steady at 28.2 volts. At MES (T + 235 sec), the battery voltage dropped to 27.4 volts, recovered to 27.6 volts during thrust, and rose to 28.0 volts at MECO (T + 572 sec). The battery internal temperature rose gradually from 106° F at lift-off to 138° F at T + 3000 seconds.

Comparison of the calculated battery-load-current - time profile with the measured current profile reveals close correlation between the sequential events, but with the absolute values of measured current being some 20 percent lower than predicted. Lift-off load current was approximately 44 amperes, while at T + 3000 seconds the same value was being delivered. The Centaur AC-4 load profile is shown in figure XIV-2.

The inverter phase voltages varied less than 0.4 volt throughout the 3000 seconds of telemetry data with an average output of 113.5 volts a.c. The load currents for each phase decreased gradually from lift-off to T + 3000 seconds by a factor of 0.8 to 0.3 ampere dependent on the particular phase. Since the inverter output voltage and frequency, as well as the operation of the equipment supplies by the inverter, were normal, the drift could be attributed to a malfunction in the telemetry circuit. The inverter frequency throughout the flight was essentially constant at 400 cps.

The inverter skin temperature was 78° F at lift-off and rose to a maximum value of 152° F at T + 900 seconds when LH₂ vented and produced a cooldown to 101° F at T + 1620 seconds. The inverter temperature again rose to 167° F at main power cutoff. Two additional points were obtained on the second pass and are shown in figure XIV-3.





TELEMETRY AND INSTRUMENTATION

Telemetry

Ten measurements of Centaur telemetry system parameters were made on AC-4. All yielded valid data, and all remained within the predicted limits except for the RF-4 skin temperature and the C-1 engine forward instrumentation box. No data were lost due to these anomalies. RF-4 temperature decreased from 550 F at T + 840 seconds, when venting occurred, to 20° F at T + 1600 seconds. After T + 1600 seconds, temperature decayed at a slower rate and stabilized at 50 F at T + 3000 seconds. The RF-4 package was mounted on the lower tier close to the vent. The C-1 engine forward-instrumentation-box temperature abruptly went off scale (high) at T + 2750 seconds, approximately 40 seconds after the vehicle entered the Earth's shadow. The C-l instrumentation-box temperature came back in band at 110° F and decreased linearly to 90° F at T + 2900 seconds (end of Uniform data). Temperature had stabilized at 20° F on the first pass over ETR. Telemetry battery current was 18 amperes as expected after T + 3000 seconds. Multiplexer, thermocouple-reference-junction, C-2 rear-instrumentation-box, and aft-instrumentation-box temperatures were all within expected limits. and instrumentation details are given in appendix B.

Centaur Instrumentation

Six measurements yielded no data on AC-4. Two failed during flight, and 20 experienced anomalies such as offset time delays or bonding failure. Eleven measurements were deleted prior to launch. The measurements in the following table, which were inaccessible for repair prior to flight, were deleted prior to launch.

	Station	
CA744S	Tank strain	225
CA757S	Tank strain	402
CA759S	Tank strain	402
CA408T	Outer nose	72
CA856T	Aft bulkhead skin	
CA866T	Aft bulkhead skin	
AAl76S	Strain	582
AA919T	Temperature	57 5
AA925T	Temperature	614
CA756T	Tank skin	
CA537T	Tank skin	302

The following measurements yielded no data during all or portions of the flight.

CA2650 LH₂ boil-off valve accelerometer. - This transducer failed to respond during vent-valve operation. Sensor or associated amplifier failure caused this loss of data, since no noise or bias shift was evidenced.

CA310 C-1 gimbal mounting z-axis vibration. - Full-scale noise due to an apparent open circuit appeared during the Centaur burn.





CA451P Nose-fairing differential pressure. - This measurement read zero throughout the flight. An open harness or transducer failure is suspected. Two other nose-fairing differential pressure transducers provided data on AC-4.

CH152T and CH153T C-1 and C-2 hydraulic insulation adapter temperatures. - These temperatures went off scale (low) prior to launch and remained off scale throughout flight. These thermocouples were reworked just prior to flight. Wire reversal is the probable cause of this data loss.

CUL2X LOX liquid level at station 433.5. - This measurement erroneously indicated dry from main-engine start until T + 860 seconds then indicated wet.

CM810V Air Force Cambridge Research Laboratories Spectrometer. - The commutator in this device failed prior to launch. After main-engine cutoff, the commutator began operating. Spectrometer data on the LH2 engine exhaust was not obtained as a result of this failure.

 $\overline{\text{CP29T IH}_2}$ boost-pump-turbine nozzlebox temperature. - Valid data were obtained until T + 610 seconds. At that time, the trace went off scale (low) due to an apparent short circuit.

CP28P LH₂ boost-pump turbine-inlet pressure. - An excessive 10-second time delay occurred in responding to pressure rise due to failure of the potentiometer drive linkage.

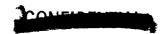
CP123T and CP125T C-2 engine fuel and LOX pump temperatures. - These measurements displayed an unexplained delay in response characteristic of a poor thermal bond. Identical measurements on the C-1 engine operated as expected. CP125T required 50 seconds to indicate a 100° F drop in temperature at measurement, while similar measurements on the C-1 engine showed a similar drop in less than 10 seconds. This is not a confirmed instrumentation failure, since several temperature measurements associated with the C-2 engine were high.

CP882T Ullage control unit quadrant I. - This temperature data was offset by 25 percent information bandwidth compared with a similar measurement (CP883T) in quadrant II. Both of these measurements clearly indicated identical temperature rise rates of H₂O₂ propellant settling motors; therefore, little data were lost as a result of this malfunction. Probable failure occurred in the thermocouple compensator.

The measurements in the following table yielded data until insulation-panel jettison. At that time apparent wiring damage caused each to go off scale.

	Measurement	Station
CA540T CA758S CA826S CA830S CA832S	Tank skin temperature Tank strain Ring strain Ring strain Ring strain	310 402 408 408 408





The temperature measurements in the following table indicated increased temperatures at insulation-panel jettison probably due to varying degrees of bonding failure. It appears that these measurements yielded erroneous data after panel jettison. Forty-three germanium sensors had been bonded to the Centaur tanks to determine liquid position during coast and to provide temperature data. Approximately 25 percent exhibited bonding anomalies.

Meas	Station	
CA543T	Tank skin	318
CA544T	Tank skin	320
CA546T	Tank skin	326
CA547T	Tank skin	328
CA549T	Tank skin	334
CA551T	Tank skin	338
CA707T	LH_2 pump	387
CA495T	LH_2 pump	393
CA600T	Tank skin	248
CA624T	Tank skin	293
CA626T	Tank skin	297

AC-4 RANGE SAFETY SUBSYSTEM

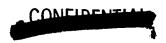
Operation of the Range Safety command subsystem was entirely satisfactory with no anomalies experienced. The system is designed to perform three functions, each on receipt of an appropriate radio command from the UHF command-control system operated by the AFETR under direction of the Range Safety Officer.

The first two functions are termination of thrust and dispersion of the propellants, produced by the MECO and DESTRUCT commands, respectively. Neither of these was required, since the trajectory and performance were well behaved until orbital velocity was achieved.

The last function of the system is to turn itself off on receipt of the DISARM command. This was accomplished at T+601.4 seconds. A summary of activities relating to the RSC subsystem is shown in the following table.

Event	Planned time, sec	Actual time, sec
Switch from Cape to GBI transmitter	T + 114	T + 115.6
Switch from GBI to San Salvador transmitter	T + 185	T + 185.2
Switch from San Salvador to Grand Turk transmitter	T + 310	T + 309.5
Switch from Grand Turk to Antigua transmitter	T + 520	T + 522.0
Send DISARM command	Within 30 after MECO	MECO + 28.5



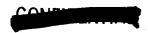


From T - 0 until the DISARM command was sent, the minimum signal strength at either receiver was 36.1 microvolts. Since the receivers have a nominal sensitivity of 5 microvolts, there was never less than a 17-decibel gain margin.

ELECTRICAL GROUND SUPPORT EQUIPMENT

Several GSE peculiarities discussed hereinafter occurred during preflight testing, and some latent problems were brought to light:

- (1) A safety measure was incorporated in the GSE logic to ensure that the Atlas programer reset command was provided during transfer from external to internal power until the cycle had positively been completed. There was concern that if there were a delay in transfer time of the changeover switch (max. specification time for transfer is 2 sec), the programer reset signal would have been removed for approximately 0.5 second. Any transient caused in the transfer would activate all the programer high-power switches, necessitating action by the test conductor to reset the engine-start logic prior to arming the engine start switch.
- (2) A new "guidance ready" circuit was installed to support guidance on the assumption that optical acquisition could not be obtained with gimbal 4 caged. It was discovered during the FACT test that the new circuitry was a function of "guidance caged" and dependent on airborne umbilical 600 P/J 402 being mated. The loss of 600 P 402 at "main engine complete" drops out the "function safe release" ladder resulting in cutoff. Systems testing verified that the circuit was unnecessary, and gimbal 4 was subsequently kept in the caged position by procedural change.
- (3) Power supply 3, which is the main source of the 28-volt d-c power backed up with a 10-cell nickel-cadmium battery on the line, was the target for much concern and criticism as the probable cause of excessive ripple appearing on the 28-volt d-c bus. This power supply is a 400A Christie unit similar to that used with the Atlas E series configuration. The specification calls for an output ripple of 0.28 volt (rms) or 0.8 volt P-P. The power supply had a ripple of 1.2 volts P-P. With the battery on the line, the ripple was reduced to 0.6 volt P-P. The measurements established that the power supply was at fault, and the trouble could no longer be attributed to extraneous ground feedback loops inherent in the equipotential grounding scheme employed at the complex. It was clear that the Christie unit (PS-3) had to be replaced to bring the ripple contact within acceptable limits. This was accomplished after the launch.
- (4) Operator error in combination with equipment failure resulted in the overtanking condition experienced during the quad tanking test. It is evident that some method must be devised to cut off tanking operations automatically at some predetermined level (90 to 95 percent). A manual override capability could be built in to alert the operator that the most critical phase of the tanking process was rapidly approaching.



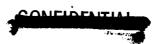
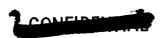


TABLE XIV-I. - AC-4 MEASUREMENT SUMMARY

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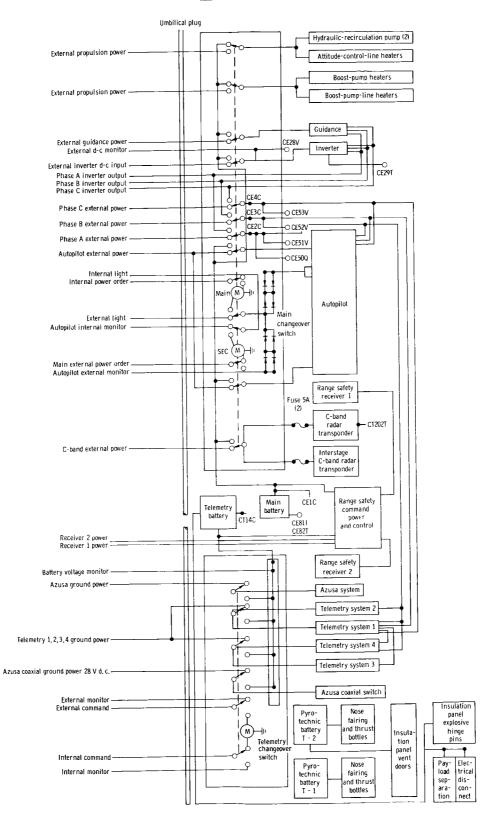


Figure XIV-1. - Centaur electrical system.





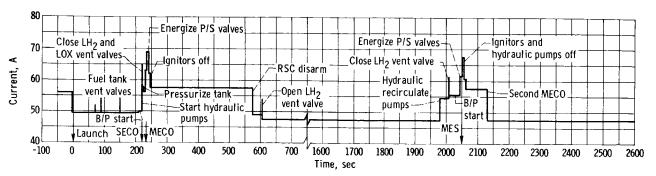


Figure XIV-2. - Centaur AC-4 missile battery current load profile.

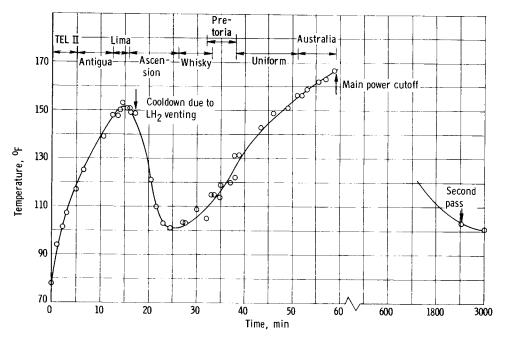
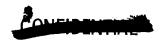


Figure XIV-3. - AC-4 static inverter temperature against flight time.





XV. COAST-PHASE PROPELLANT AND VEHICLE BEHAVIOR

SUMMARY

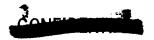
The AC-4 coast-phase vehicle behavior was not normal, and the programed mission requirements for controlled hydrogen venting, second main engine start, turnaround, and retromaneuver were not accomplished. Failure to accomplish these objectives resulted primarily from an uncontrolled propellant behavior excited by vehicle disturbances at first MECO. The combined effects of engine shutdown transients, vehicle dynamics, and other energy inputs to the propellants, induced a forward displacement and circulation of the liquid residuals within the tank. Viscous damping was insufficient to dissipate propellant energy, and the ullage motor thrust was inadequate to settle the propellants from the disturbed state. Failure to settle the LH2 at the time of venting resulted in mixed-phase or liquid flow, which, on expanding from the vent exits, produced high impingement forces in excess of the attitude control system capability, and the vehicle tumbled out of control. Continued tumbling and vent depletion of the LH2 residual prevented accomplishment of the coast-phase mission.

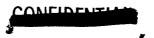
A composite correlation of these post-MECO coast-phase events is presented in the following time sequence: (1) First MECO to start of hydrogen venting, T+572.8 to T+840 seconds, (2) first phase hydrogen venting, T+840 seconds to loss of signal at T+1100 seconds, (3) second-phase hydrogen venting to second MES prestart, T+1255 to T+2006 seconds, and (4) second MES prestart through retromaneuver, T+2006 to T+3000 seconds.

FIRST MECO T + 572.8 SECONDS TO START OF

HYDROGEN VENTING T + 840 SECONDS

The vehicle at MECO was holding a flight-path angle of approximately -0.02 degree in pitch and was rolled counterclockwise approximately 15 degrees. Rates imparted to the vehicle following the MECO transient were -1.0 degree per second in pitch, 0.2 degree per second in yaw, and -0.5 degree per second in roll. Coincident with MECO, the attitude control and ullage engines were enabled. Attitude control engines A-2 and A-4 (see fig. XV-1) were activated immediately and burned for 1.6 seconds to null the roll rate below the 0.2 degree per second threshold. No other attitude control activity was observed until T + 577.8 seconds, approximately 5 seconds after MECO, when a programed change in the guidance-steering equations commanded an 8-degree pitch error (command nose down) and a 1-degree yaw error (command nose left). This maneuver was designed to give the vehicle an attitude parallel with the local horizontal and in the plane of the trajectory. The attitude control jets P-2, A-3,



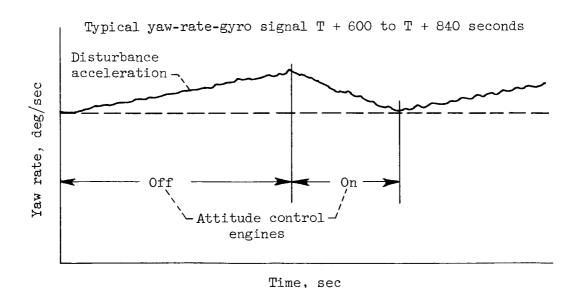


and A-4 responded to guidance commands immediately, and the desired attitude was achieved in 16 seconds.

Throughout the remainder of the controlled coast (to start LH_2 venting at T + 840 sec), sporadic corrections were observed in pitch and roll, and a nearly constant 30-percent duty cycle was observed in yaw (see fig. VI-20). Attitude control operation was more frequent than expected, and was probably due to

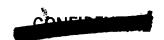
- (1) Unpredicted propellant behavior
- (2) Ullage engine exhaust impinging on the main engine bells and other components in the thrust section
- (3) Misalinement of the ullage thrust vector

The 30-percent duty cycle observed from the yaw rate gyro, is shown in sketch (a). The disturbance accelerations, defined as the slope of the curve where the attitude control engines are off, is an indication of the disturbing torques acting on the vehicle. During the controlled coast period, the disturbance accelerations averaged 0.012 degree per second per second with resulting disturbing torques of 100 to 113 inch-pounds, depending on chosen vehicle mass moment of inertia. Ullage motor misalinement and calculated impingement forces can account for only 60 inch-pounds of torque. The vehicle behavior could be characterized by an offset of the center of gravity from the vehicle longitudinal axis of approximately 12 inches. A center-of-gravity shift attributable to propellant location is not stable, and there were no indications of hardware movement. Therefore, motor misalinement beyond design tolerances and attitude control engine thrusts below nominal could account for the rate responses observed.



(a)

3 CANTOCK TO



Termination of Centaur powered flight appeared normal, but immediately on entering the coast phase, the propellant behavior was characterized by a predominant forward movement of LH2 in the tank. Within 14 seconds following MECO, all instrumented tank surfaces (see fig. VII-9) indicated the presence of LH2. Forward bulkhead skin temperatures and the LH2 ullage gas temperature dropped abruptly to LH2 temperatures within 4.5 seconds after MECO. This effect is shown in figure VII-12. This abnormal behavior of the LH2 residual has been attributed to the following disturbances, as illustrated in figure XV-2:

- (1) Fuel-boost-pump volute bleed spray toward the forward end of the tank during boost-pump coastdown
- (2) Hydrogen-duct-recirculation-line spray entering the tank at station 350 on the positive x-axis; this spray is directed across the tank
- (3) Residual slosh energy in the fluid at MECO
- (4) Springback of the intermediate bulkhead and lower cylindrical section of the tank by thrust termination at MECO
- (5) Backflow of mixed-phase hydrogen through the propellant ducting and boost-pump inlet at MECO due to expansion back to tank pressure and temperature of high energy LH₂ between pump and engine inlet valves

The fuel-boost-pump volute bleed-line flow was calculated to be initially about 340 gallons per minute. During pump coastdown, approximately 20 pounds of LH $_2$ were returned to the tank. Similarly, the hydrogen-duct-recirculation-line return flow was estimated initially at about 50 gallons per minute maximum.

The possible energy inputs to the LH2 residual from these five disturbing sources have been estimated as shown in the following table.

Source	Energy level, ft-lb
Fuel-boost-pump volute bleed	102
Hydrogen-duct-recirculation line	35
Slosh (10° slosh angle)	35
Bulkhead springback	.126
Backflow from propellant ducts	35

The initial displacement of the LH₂ in the tank by these disturbances, appeared to be a wave moving forward along the positive x-axis and negative y-axis as shown in figure XV-2. The more rapid flow along the positive x-axis was probably quickened by the volute bleed-line discharge, whereas the wetting along the negative y-axis progressed at a slower rate. Generally, this wetting sequence was attributed to spray from the recirculation line hitting the nega-





tive x-axis, dispersing laterally and wetting the negative y-axis in the forward direction. The wave motion then continued over the forward bulkhead and down the positive y-axis as evidenced by the wetting from fore to aft. (There were no sensors on the negative x-axis, so the wetting action on that wall could not be evaluated.)

All temperature sensors remained wet from MECO to until approximately 50 seconds prior to venting. The propellant behavior at this time was uncertain, but there was some evidence of drying toward the forward end of the tank, as sensors on the positive y-axis began drying from the top, as shown in figure XV-3. It may be conjectured that either the ullage motors were beginning to settle the propellants or some local skin drying was occurring (ref. 20).

START OF LH2 VENTING T + 840 SECONDS TO LOSS

OF SIGNAL T + 1100 SECONDS

The LH $_2$ vent valve was programed in the relief mode at T + 614.4 seconds. Fuel tank pressure at this time was below the valve cracking pressure but by T + 840 seconds had reached the valve cracking pressure. The first indications of hydrogen venting were noted at this time.

The presence of LH_2 at the forward end of the tank, however, resulted in mixed-phase and liquid flow through the vent system. Indicated flow rates were high, and Venturi flow temperature dropped abruptly to LH_2 levels.

Simultaneous with venting was the incipience of an overpowering yaw torque, which exceeded the capabilities of the attitude control system and produced an increasing yaw instability and vehicle spin-up.

A comparison of the predicted vehicle torques due to normal gaseous hydrogen venting with the actual measured results is shown in the following table.

Condition		le tor inlb	
	Pitch	Yaw	Roll
Inputs due to normal GH2 venting	0.4	33	2
Attitude control system predicted capability (based on center of gravity at station 343)	228	228	180
Estimated torque inputs from AC-4 flight data (maximum)	500	4500	240

The uncontrollable yaw torque experienced during venting was credited to large lateral impingement forces on the forward bulkhead due to liquid or mixed-phase flow. Calculated lateral forces of 2 to 10 pounds were required to produce the yaw torques noted. The predicted force for pure gaseous venting was





only 0.2 pound. Forward bulkhead skin temperatures and the LH₂ ullage temperature, indicating liquid temperatures prior to and during venting, support the evidence of an unknown quantity of LH₂ located in the forward end of the tank. Also, excellent correlation of uncontrolled vehicle rates with vent periods is evident in figure XV-4.

By T + 910 seconds, vehicle roll had increased to ±0.2 degree per second, and yaw had increased to ±0.5 degree per second. At T + 915 seconds, a torquing transient in pitch and roll coupled the yaw steering error into the pitch channel. At this time, the roll rate reversed, and the pitch rate began to increase, reaching ±0.2 degree per second by T + 925 seconds. By T + 1055 seconds, vehicle rates had increased to 2.4 degrees per second in yaw, 0.2 degree per second in pitch, and -1.3 degrees per second in roll.

Hydrogen tank pressure was unsteady but was controlled within limits until about T + 1055 seconds when it began a steady rise. This resulted from a vent flow of increasing liquid quality that was no longer of sufficient volume to relieve tank pressure. The centrifugal force due to the increasing tumbling rates was settling the $\rm LH_2$ in the forward end of the tank and pure liquid was being vented.

SECOND VENTING PERIOD T + 1225 to T + 2006 SECONDS

Reacquisition of data at T+1255 seconds, as shown in figure XV-5, indicated that the LH_2 tank pressure, vent flow rates, and vehicle yaw rates were up sharply and increasing steadily. Again the inability of the tank pressure to relieve under high indicated flow rates was further evidence of liquid vent flow, which, in turn, produced an excessive yaw torque to the vehicle.

These rates continued until about T+1366 seconds when the tank pressure, which had reached 24.2 psia, suddenly started to recover and there was evidence of liquid depletion at the forward end of the tank. Ullage and Venturi gas flow temperature data, shown in figure VII-8(a), show a distinct warming and liquid-to-vapor transition in the character of the vent flow. Complete tank pressure recovery was then accomplished by T+1455 seconds.

Vehicle motion during this time, obtained from the resolver chain output data, indicated that the vehicle was tumbling predominantly in the yaw plane with a slight nose-high attitude. Yaw rate increased from about 8.5 rpm at T + 1255 seconds to a maximum of about 21 rpm at about T + 1550 seconds. Corresponding pitch and roll rates were not excessive and varied in a random manner. This random nature of the pitch and roll rates is believed to be caused by the buildup and breakaway of solid hydrogen deposits at the vent exit ports. Experimental investigations by the National Bureau of Standards have indicated that solid deposits can build up at vent exits during extended venting of a liquid or a liquid-vapor mixture into a vacuum.

The response of the vehicle to venting was very pronounced as indicated at T+1350 seconds when depletion of liquid flow rate and transition to gas were coincident with changes in yaw rate (see fig. XV-5). Significantly, however, the vent impingement forces continued to spin-up the vehicle until about





T + 1550 seconds, about 100 seconds after the Venturi flow indicated nominal coast-phase gas flow rate. This lag was attributed to the purging of residual LH_2 in the vent system downstream of the Venturi, and sublimation of possible ice deposits built up on the forward bulkhead.

Once the hydrogen tank pressure and venting were stabilized, the vehicle began to respond to the attitude control system, and the rates started to attenuate slowly by the time of attempted second main engine start. During the total coast-vent period, however, it was estimated that about 960 pounds of LH₂ were vented overboard and only about 120 pounds remained in the tank. Temperature sensors indicated that the forward end of the tank was completely dry; however, tank skin temperature sensors, below station 344 on the positive x-axis, and the boost-pump-inlet temperature remained at liquid level, indicating some slight residual at the bottom of the tank and in the sump.

SECOND ENGINE PRESTART T + 2006 SECONDS TO END OF

RETROMANEUVER T + 3000 SECONDS

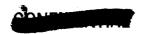
The prestart sequence for second MES began at approximately T + 2006 seconds, with the vent valve lockup and initiation of tank burp. At this time, however, as shown in figure VII-4(d), the LH $_2$ tank ullage temperature dropped from approximately -380° to -420° F. Apparently, a small quantity of LH $_2$ remained in the forward end of the tank and was entrained with the helium pressurizing gas as it blew across the forward bulkhead.

The LH₂ boost-pump start, as shown in figure XV-6, began at about T + 2010 seconds. Boost-pump headrise (ΔP) appeared normal (liquid being pumped) for the first 7 seconds of pump operation. Coincident with a drop in pump-inlet pressures and ullage pressure, the pump headrise became erratic, indicating the occurrence of cavitation or pull-through. By T + 2027 seconds boost-pump headrise had peaked-out at about 25 psid, and ullage pressure had dropped to approximately 14 psia. Within 5 seconds, headrise dropped to 2 psid and boost-pump over-speed trip-out occurred indicating an absence of liquid at the pump inlet.

Liquid hydrogen remaining in the tank by T + 2010 seconds had been reduced drastically because of the liquid venting during coast. This left a considerably large ullage at BPS, with probably a small amount of LH₂ in the aft end of the tank. The decay of the LH₂ ullage pressure at boost-pump start can in all probability be attributed to the cooling of the large ullage by the LH₂ boost-pump volute bleed spray. Calculations of heat-transfer effects show that if all heat to vaporize the sprayed LH₂ is extracted from ullage and the initial ullage temperature is 60° to 65° R, approximately 15 to 17 pounds of LH₂ would be required to produce the pressure drop noted. Calculations based on boost-pump pressure rise, also indicated that the boost pump returned approximately 30 pounds of LH₂ to the tank during this time.

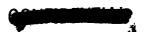
The command for second MES occurred at T+2049.7 seconds. Insufficient LH₂, as already discussed, was available to sustain boost-pump operation and normal engine start did not occur.





Liquid hydrogen tank pressures remained well below the cracking pressure of vent valve 1 throughout the planned second-engine-burn period. At MECO, LH2 tank pressure rapidly began to increase at about 2.8 psi per minute. Heattransfer calculations show that this pressure-rise rate would be associated with a full tank of hydrogen gas. At T + 2385 seconds, the hydrogen tank pressure reached the cracking pressure of the secondary vent valve and relieved momentarily (valve 1 was locked at burp). Two seconds later, the retrothrust signal was commanded, and the engine inlet valves were opened. This allowed the LOX and LH2 tanks to blow down and should have produced an axial thrust of approximately 30 pounds. Propellant tank pressures should have remained relatively steady during the blowdown, with liquid in the tanks. The absence of residual LH2, however, resulted in the hydrogen pressure dropping off rather rapidly to 3 psia at T + 3000 seconds. LOX tank pressure, however, remained fairly constant indicating that a quantity of LOX still remained in the tank, and the boil-off was sufficient to maintain pressure. Actual thrust levels produced by the engine blowdown could not be assessed because the data were obscured by the vehicle spinning motion.

Tank pressure recovered gradually on subsequent orbits of the vehicle as they were influenced by solar heating and vehicle position in and out of the Earth's shadow. The vehicle impacted in the South Pacific Ocean after completing 10 orbits.



Engine	Thrust, lb	Function
A-1	1.5	Attitude
A-2	1.5	control
A-3	1.5	
A-4	1.5	
P-l	3.0	Attitude
P-2	3.0	control
V-1	2.0	Propellant
V-2	2.0	setting

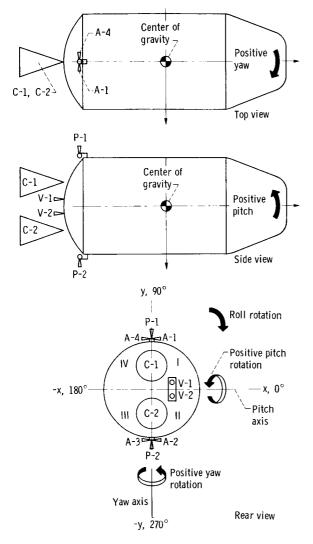


Figure XV-1. - Location of attitude control and propellant settling engines.

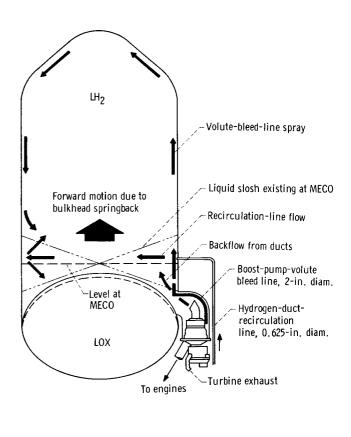
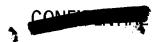
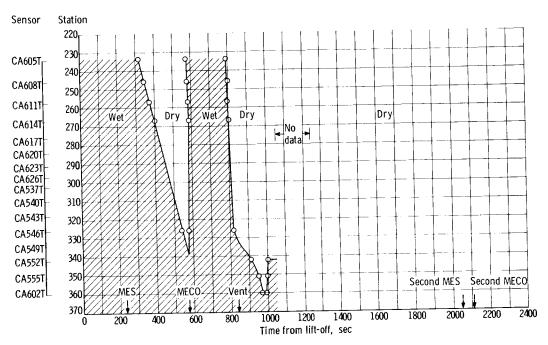
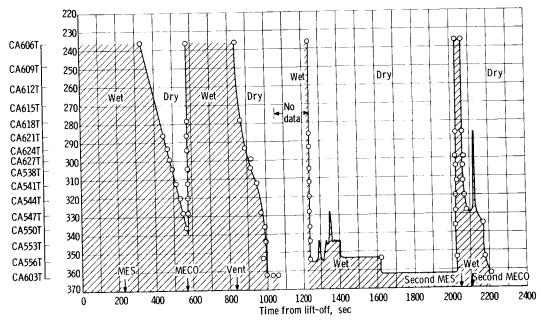


Figure XV-2. - Residual LH_2 motion after MECO.



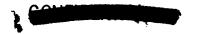






(b) Positive x-axis.

Figure XV-3. - LH₂ tank wall liquid indication.



CONFIDENTIAL

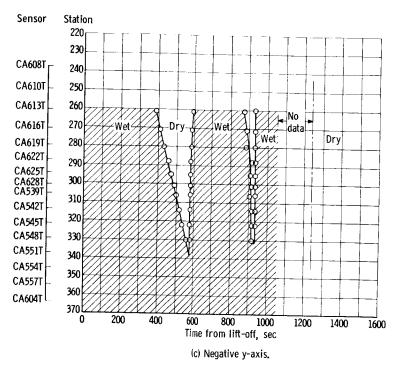


Figure XV-3. - Concluded.

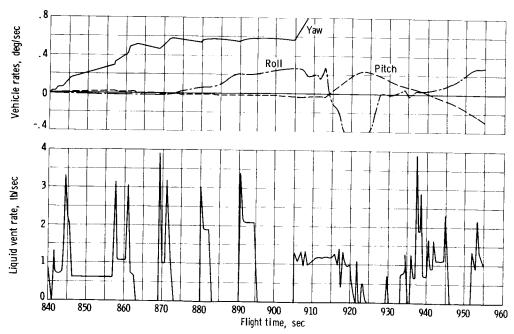


Figure XV-4. - Coast-phase vent and vehicle instability.



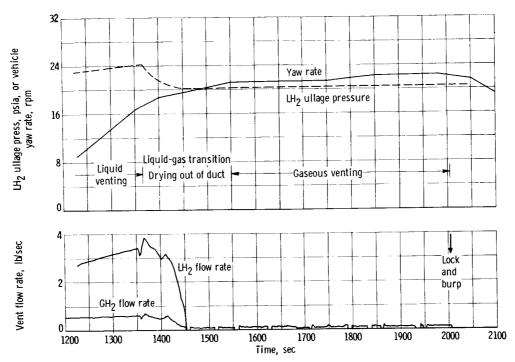


Figure XV-5. - Coast-phase venting and vehicle yaw rate.

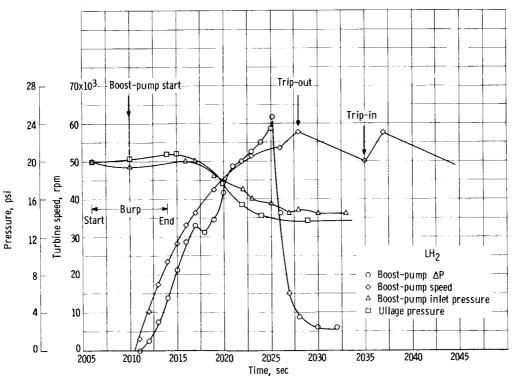


Figure XV-6. - Hydrogen tank pressure and boost-pump performance at second MES.





APPENDIX A

ABBREVIATIONS AND SYMBOLS

ABBREVIATIONS

A/B automatic tracking of beacon

A-C Atlas-Centaur

A/C air conditioning

AFCRL Air Force Cambridge Research Laboratories

AFETR Air Force Eastern Test Range

ANT Antigua

AOS acquisition of signal

A/P autopilot

A/S automatic skin track

a.c. alternating current

BECO booster engine cutoff

BET best estimate of trajectory

BPS boost pump start

CAPE Cape Kennedy

CPT composite readiness test

cps cycles per second

DEPRO detailed propulsion simulation of three engines used by Atlas vehicle

DPT design proof test

d.c. direct current

EST Eastern Standard Time

ETR Eastern Test Range

F- days prior to launch day



SAVEIDENTIAL!

F+ days after launch day

FACT flight acceptance composite test

GBI Grand Bahama Island

GD/A General Dynamics/Astronautics

GH₂ gaseous hydrogen

GLOTRACK global tracking

GMT Greenwich Mean Time

GN₂ gaseous nitrogen

GO₂ gaseous oxygen

GSE guidance support equipment

gal U.S. gallon

He helium

H₂O₂ hydrogen peroxide

I/A interstage adapter

IGS inertial guidance system

IHe liquid helium

LH₂ liquid hydrogen

LOX liquid oxygen

MECO main engine cutoff

MES main engine start

NPSH net pump suction head

NPSP net pump suction pressure

PAFB Patrick Air Force Base

PETN pentaerythritol tetra nitrate

P/L payload

PLIS propellant level indicating system

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P-P peak to peak

PU propellant utilization

ppm parts per million

psi pounds per square inch

psia pounds per square inch absolute

psid pounds per square inch differential

Q quadrant

QUAD quadrant

 $Q_1, Q_2,$ quadrants I, II, III, IV, respectively

 Q_3,Q_4

RF radiofrequency

RIS range instrumentation ship

rms root mean square

RP-1 rocket propulsion fuel

rpm revolutions per minute

RSC range safety command

SANSAL San Salvador

SECO sustainer engine cutoff

SPC Lewis Research Center Space Power Chamber

STL Space Technology Laboratories

scf standard cubic feet

scfh standard cubic feet per hour

T time of launch

T- time prior to launch (2-in. motion)

T+ time after launch (2-in. motion)

TCA temperature control amplifier

TDPU time delay pickup

TEL telemetry receiving station

TLM telemetry

TRW Thompson Ramo Wooldridge

UHF ultra high frequency

VECO vernier engine cutoff

VHF very high frequency

SYMBOLS

D drag

E modulus of elasticity

F vehicle thrust

g acceleration due to gravity

T specific impulse

ka normal operating gain

panel length (streamwise)

M Mach number

bending moment

Atot total bending moment

Axx pitch plane bending moment

Myy yaw plane bending moment

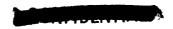
q dynamic pressure

t skin thickness

W weight

α pitch plane angle of attack, deg

β yaw plane angle of attack, deg



 β $\sqrt{M^2 - 1}$

δ cycle amplitude

ω cycle frequency

Subscripts:

gas gas or gaseous

liq liquid

ms mean square



TELEMETRY AND INSTRUMENTATION DETAILS

Four VHF telemetry links were carried on the Centaur stage: RF-1, 225.7 megacycles, RF-2, 235.0 megacycles, RF-3, 243.8 megacycles, and RF-4, 251.5 megacycles, all at 4 watts power. Two VHF links were carried on the Atlas booster: RF-1, 229.9 megacycles at 3.5 watts power, and RF-2, 232.4 megacycles at 2.8 watts power. Telemetry coverage from the ETR stations is shown in figure B-1. Continuous coverage was obtained from T - 420 to T + 3030 seconds, with the exception of 91 seconds from T + 1101 to T + 1192. The following ETR stations supported the test:

Station	Location
1	TEL II at Cape Kennedy
3	Grand Bahama Island
7	San Salvador Island
91	Antigua Island
Lima	Timber Hitch, ship located approximately 14.6° N latitude, 42.7° W longitude
12	Ascension Island
Whiskey	Coastal Crusader, ship located approxi- mately 19.0° S latitude, 10.0° E longitude
13	Pretoria
Yankee	Sword Knot, ship located approximately 29.00 S latitude, 53.00 E longitude
Uniform	Twin Falls, ship located approximately 31.00 S latitude, 78.00 E longitude

In addition to coverage by ETR, the four Centaur telemetry links were recorded by the following stations of the Manned Space Flight Network.

Sta- tion		Orbits covered	Sta- tion		Orbits covered
1 2	Cape Kennedy Grand Bahama Island	1,2 1,2	11	Sword Knot (ship)	l only
3 4	Grand Turk Island Bermuda	1,2 1 only	12	Twin Falls Victory (ship)	l only
5	Antigua	1,2	13	Carnarvon	1,2
6	Timber Hitch (ship)	l only	14 15	Hawaii Saint Nicolas	1,2,3,4 1,2,3,4
7	Ascension	l only	16	California	1,2
8	Coastal Crusader (ship)	l only	17 18	Guaymas White Sands	1,2,3 1 only
9	Pretoria	l only	19	Texas	1,2
10	Tananarive	1,2,3,4,5	20	Elgin	l only



The four Centaur links were in operation for a total of 6 hours and 45 minutes. Acquisition was lost on the fifth Earth orbit between Tananarive and Hawaii. Radar and Azusa - GLOTRACK provided additional tracking coverage in addition to the telemetry links (figs. B-2 and 3).





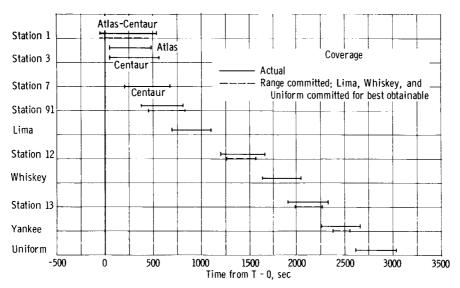
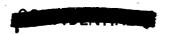
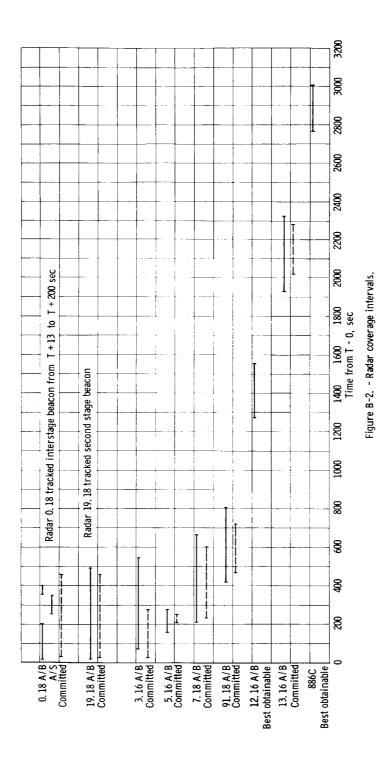


Figure B-1. - Telemetry coverage from Eastern Test Range.









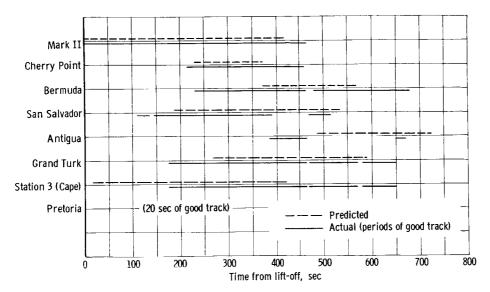


Figure B-3. - Azusa - GLOTRACK coverage.





APPENDIX C

PROPULSION SYSTEM PERFORMANCE TECHNIQUES

The Lewis Venturi technique (LEWP) utilizes three curves based on ground testing to determine Centaur performance. Liquid-hydrogen flow rate is determined from a curve of \dot{w}_{LH_2} as a function of a ratio of fuel Venturi upstream pressure to the square root of fuel turbine inlet temperature. LOX flow is then determined from a curve of mixture ratio as a function of fuel turbine inlet temperature. A curve of the vacuum thrust coefficient as a function of mixture ratio then allows one to determine the propulsion system performance.

The Pratt & Whitney C* Iteration technique (PWAP) determines the fuel flow rate in a manner similar to the LEWP. A value of LOX flow rate is assumed and another value is then calculated utilizing the characteristic exhaust velocity efficiency. Iterations are then used until the value of LOX flow rate assumed is equal to the value calculated. When the values are equal, the ideal specific impulse can be determined from a curve of ideal specific impulse plotted against mixture ratio. Actual specific impulse can then be determined by multiplying the ideal specific impulse times the impulse efficiency for that particular engine. The remainder of the performance values can then easily be determined.

The Pratt & Whitney Regression technique utilizes the engine pump inlet conditions (i.e., pressures and temperatures) and correlates them with a nominal engine performance. The degree to which the engines are off nominal is determined from the engine acceptance data. Combination of these effects determines engine performance.

The DEPRO Program uses the pump inlet conditions, the PU valve setting, and altitude to determine engine performance in a manner similar to the Centaur Regression program.

These four methods are strongly dependent on ground test data.



APPENDIX D

STRUCTURES INSTRUMENTATION

The structural instrumentation consisted of strain gages, pressure and temperature transducers, accelerometers, and angle-of-attack differential pressure transducers. In general, the instrumentation yielded data of acceptable quality. The instrumentation configuration is shown in figures IX-1 and X-1 to 3. Of the strain gages, two at station 402 and one at station 225 were not functional at launch. The necessity of removing the insulation panels to repair these gages rendered this repair impractical. An additional strain gage at station 225 was lost during the flight. All four strain gages at interstage adapter station 548 yielded valid data. One of the two strain gages on the Atlas LOX tank at station 582 was deleted prior to the flight, and the other appeared to drift during the flight. Strain gages on the payload adapter and nose-fairing hinges yielded valid data throughout the flight.

Pressure measurements of prime interest, structurally, were the ullage pressure transducers in each of the four main propellant tanks. In addition, there were pressure surveys of the nose-fairing and insulation panels. Valuable data were obtained from these transducers.

The AC-4 flight trajectory was aerodynamically "hotter" than the AC-3 flight, and there were many thermocouples on the vehicle for temperature survey of critical areas on the vehicle. In general, good coverage was achieved, and valuable data were retrieved.

Accelerometers and high-frequency fluctuating pressure transducers located at various points on the interstage adapter were reading throughout the flight. Reasonable data were obtained, and there were no apparent failures in these transducers. The differential-pressure angle-of-attack transducers appeared to yield valid data. The associated dynamic pressure measurement, however, did not yield usable data. As dynamic pressure can be accurately determined from tracking and atmospheric data, loss of this measurement was of little consequence.



SYMBOLS AND DETAILED LISTING OF TRAJECTORY RECONSTRUCTION FOR AC-4 FLIGHT

DESCRIPTIONS

TIME

elapsed time from lift-off

WEIGHT

total weight of vehicle

TOTAL FLOW

total weight flow

GRND RANGE

ground-range great-circle distance (spherical earth, $R_0 = 3443.9$

n. mi.) from launch pad to vehicle subpoint

THETA I

inertial range angle, measured between launch radius vector and

present radius vector

Q*ALPHA

product of ALPHA and dynamic pressure

ALTITUDE

altitude above oblate spheroidal earth

RADIUS

magnitude of radius vector from Earth center to vehicle

VEL E

magnitude of velocity with respect to Earth

VEL R

magnitude of velocity with respect to air

VEL I

magnitude of velocity in inertial system

Q*BETA

product of BETA and dynamic pressure

ALPHA

angle of attack in pitch (XI, ZETA) plane positive for ship above relative velocity vector, V_{R}

BETA

angle of attack in yaw (XI, ETA) plane positive for ship left of relative velocity vector, V_{R}

PSI

inertial attitude angle, measure of angle between ship longitudinal axis and inertial u-v plane, positive above plane

PSIDOT

time rate of change of PSI

CROSS RANGE

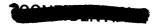
minimum ground distance from vehicle subpoint to plane formed by launch vertical vector and launch down-range vector

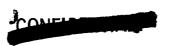
DOWN RANGE

distance from vehicle subpoint to launch site along Great Circle at 100.50 azimuth through launch site

GEOCENT LAT

geocentric latitude, degrees north of equator





degrees from Greenwich, positive east LONGITUDE

azimuth of VEL E, angle between projection of VEL E into azimuth AZI E plane (plane perpendicular to radius vector) and north direc-

tion, positive clockwise from north

azimuth of VEL R AZI R

azimuth of VEL I AZI I

inertial attitude angle - angle between projection of minus ZETA PHI

axis in u-v plane and the u-axis

THRUST FIXED fixed thrust magnitude - nongimbaled engines thrust

controlled thrust magnitude - gimbaled engines THRUST CONTL

flight path angle of VEL E, measured angle between velocity vec-GAMMA E

tor and local horizontal, positive above horizontal

GAMMA R flight path angle of VEL R

GAMMA I flight path angle of VEL I

magnitude of wind velocity component from east EAST WIND

aerodynamic force along longitudinal axis, XI AXL FORCE

aerodynamic force along side axis, ETA SIDE FORCE

NORM FORCE aerodynamic force normal to vehicle along ZETA

instantaneous value of thrust-drag/weight AXL LD FCTR

WIND VEL magnitude of wind velocity

magnitude of wind velocity component from north NORTH WIND

atmospheric (ambient) pressure ATM PRESS

dynamic pressure, $\frac{1}{2} \rho_{\mathbf{a}} V_{\mathbf{r}}^2$ DYNM PRESS

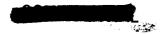
heating parameter, integrated product of air density and rela-HEAT PARAM

tive velocity squared divided by time

Mach number, ratio of VEL R and local speed of sound MACH NUMBER

RHO-VR CUBED product of air density and VEL R cubed

instantaneous quotient of total axial thrust by total flow TOTAL ISP



DETAILED PROPULSION (DEPRO) DESCRIPTIONS

THRUST (I) total thrust of booster, sustainer or vernier engines, respectively (vernier gimbaled) THRUST TOT total thrust of all engines THRUST CORR (B) booster thrust correction for nonlinearities of model sustainer thrust correction, due to propellant-utilization-THRUST CORR (S) system effects PC(B) effective chamber pressure of booster engines FUEL FLOW (I) total fuel flow of booster, sustainer or vernier engines, respectively; vernier flow included in sustainer FUEL FLOW TOT total fuel flow for all engines F FLOW CORR (B) booster fuel flow correction (nonlinear) F FLOW CORR (S) sustainer fuel flow correction (PU) PC(S) effective chamber pressure of sustainer engine OXID FLOW (I) total LOX flow of booster, sustainer or vernier engines, respectively; vernier flow included in sustainer OXID FLOW TOT total LOX flow for all engines O FLOW CORR (B) booster LOX flow correction (nonlinear) O FLOW CORR (S) sustainer LOX flow correction (PU) PC(V)effective chamber pressure of vernier engines FP INLTP (I) fuel pump inlet pressure, booster or sustainer FUEL DENSITY fuel density OXID DENSITY LOX density based on telemetry measurements MIX RATIO (B) ratio of LOX to fuel-booster MIX RATIO (S) ratio of LOX to fuel-sustainer OP INLTP (I) LOX pump inlet pressure, booster or sustainer FUEL WEIGHT weight of fuel above sustainer pump inlet



weight of LOX above sustainer pump inlet

OXID WEIGHT

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AXI LD FCTR axial load factor, required by propulsion model to calculate effect of headrise on pump inlet conditions

CAP RATIO (PU) capacitance output from fuel manometer divided by capacitance output from oxidizer manometer; this ratio is calculated

from telemetry values of PU valve angle position

OIL WEIGHT (I) weight of lubrication oil remaining, booster or sustainer

FUEL LEVEL height of fuel above sustainer pump inlet

OXID LEVEL height of LOX above sustainer pump inlet

NPSH net positive suction head of sustainer LOX pump

VALVE ANGLE (PU) propellant utilization fuel valve angle, value used from

telemetry

ATM PRESS atmosphere (ambient) pressure

VAPOR PRESS vapor pressure of LOX

FUEL TNK PR (G) gage pressure of fuel tank (telemetry)

OXID TNK PR (G) gage pressure of LOX tank (telemetry)

ACS ITER internal counter

CENTAUR DESCRIPTIONS

THRUST total Centaur thrust

LH2 FLOW total LH2 flow

LO2 FLOW total LO2 flow

RATTO ratio LO₂/LH₂

C-1 THRUST thrust of C-1 engine

C-1 LH2 FLOW LH2 flow for C-1 engine

C-1 LO2 FLOW LO2 flow for C-1 engine

C-1 RATTO ratio LO₂/LH₂ for C-1 engine

C-2 THRUST thrust of C-2 engine

C-2 LH2 FLOW LH2 flow for C-2 engine



C-2	LO2	FLOW	T _i O ₂	flow	for	C-2	engine
	1100	TION	1107	TTOM	エハエ	V-0	CITETIO

C-2 ISP specific impulse of C-2 engine equals C-2 thrust/C-2 flow

C-2 FLOW total propellant flow for C-2 engine

C-1 LO2 TEMP pump inlet	temperature for C)-1 engine LO2 ((telemetry)
-------------------------	-------------------	------------------	-------------

C-2 LO2 TEMP pump inlet temperature for C-2 engine LO2 (telemetry)

ORBIT ELEMENTS DESCRIPTIONS

PERIGEE RAD	radius	at.	nericee	of	instantaneous	conic

APOGEE RAD radius at apogee of instantaneous conic

PERIGEE ALT perigee altitude (above spherical Earth with radius = 3443.9

n. mi.)

APOGEE ALT apogee altitude (above spherical Earth with radius = 3443.9

PERIGEE VEL velocity at perigee



n. mi.)

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APOGEE VEL velocity at apogee

SEMI LAT REC semilatus rectum

PERIOD period

SEMI MAJ AXIS semimajor axis

ENERGY energy, $v^2/2 - \mu/r$

ECCENTRICITY orbit eccentricity

INCLINATION orbital inclination

TRUE ANOMALY true anomaly

ASCEND NODE ascending node

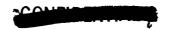
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PRTS PARAM NIJMRER R CIPRED TSO	SOD ET SOD CUBED	55.55 25.55 7 PR (5)		XI-ETA ETA-ZFIA XI*ZFIA	500 500 500	4 2 5 5 5	ፋ ኤ ድ ጭ ፎ	
ATM PRESS DYNM PRESS HEAT PARAM MACH NIMMER PHO-VR CURED TOTAL ISP	PSI LASZET SOD ETTLASZET SOD LASZSEC CUBED SEC	ATM PRESS VAOD PRESS FIJEL TWY OR OXIO TWK PR ACS TTER	Isa Isa	INERTIA INERTIA INERTIA	SUJG-FT SUJG-FT SUJG-ST	14.826744 0.7187242 0.0.2192946E-01 1148.3735 241.58075	14.825744 27.16683 58.57325 29.973255 5.000000	ଦେବର
AXL FORCE STOE FORCE NORM FORCE AXL LD FCTR WIND VEL	LBS LBS LBS FT/SEC FT/SEC	OIL WEISHT (B) OIL WEIGHT (S) EUFL LEVEL OXID LEVEL NPSH VALVE ANGLE (PU)	L9S L9S INCHES FEFT PEG	INERTIA XI Inertia fta Inertia zeta	SLUG-FT SON SLUG-FT SON SLUG-FT SOO	-52,123972 357,99565 279,99281 1,1982455 24,830523 -11,781998	166.00000 53.000000 939.21946 553.51569 77.342275 17.050000	ငဝင
THRUST FIXED THRUST CONTL GAMMA E GAMMA R GAMMA I EAST WIND	L9S L9S DEG DEG PEG FT/SEC	OP INLTP (8) OP INLTP (5) FUEL WEIGHT OXIO WEIGHT AXL LO FCTR CAP RATIO (PU)	PS1 PS1 L9S L8S	AERO MOM XI AERO MOM ETA AERO MOM ZETA	FT-LBS FT-LBS FT-LBS	56915.743 306155.89 -1.3868513 -0.9536743E-06 0.9536743E-06 21.857250	58.596910 64.274861 75673.645 171829.45 1.1982456 0.4543835	0 -140475.43 61843.021
GEOCENT LAT LONGITUDE AZI E AZI R AZI I PHI	DEG DEG DEG DEG DEG	FP INLTP (B) FP INLTP (S) FUEL DENSITY OXID DONS ITY MIX RATIO (R) MIX RATIO (S)	PS1 PS1 LBS/CUBIC FT LBS/CUBIC FT	CP NORM	INCHES	28.310592 -80.537986 93.055058 118.32658 89.999999	71.661651 71.675674 50.350000 69.089998 2.2142736 1.8779579	295.29673 624.75014
ALPHA BETA PSI PSIDOT CROSS RANGE DOWN RANGE	DEG DEG DEG DEG/SEC N.MI.	DXID FLOW (8) OXID FLOW (S) OXID FLOW (V) OXID FLOW TOT O FLOW CORR (8) PC(V)	LBS/SEC LBS/SFC LBS/SEC LBS/SEC LBS/SEC LBS/SEC PSIA	CG XI CG ETA CG ZETA	I NCHE S I NCHE S I NCHE S	90.061818 90.261275 89.958259 0.4100833E-04 0.9107653E-05	844,22995 179,74974 0 1023,9797 0,7102200E-01 308,03659	798,06546 0,5000727 0,3901455
ALTITUDE RADIUS VEL E VEL R VEL I	FT FT FT/SEC FT/SEC FT/SEC N.MI	FUEL FLOW (8) FUEL FLOW (Y) FUEL FLOW (V) FUEL FLOW CORR (B) F FLOW CORR (S) PC(S)	LBS/SEC LBS/SEC LBS/SEC LBS/SEC LBS/SEC LBS/SEC PSIA	DEL XI-ETA DEL XI-ZETA	DEG DEG	-91,250000 0,2090977E 08 0,4925779E-04 24,830520 1342,3866 -0,1501782E-01	381.26722 95.715529 0 476.98275 0.3168766E-01 11.362500 675.46138	0.9279586E-01 0.1075579
TIME WEIGHT TOTAL FLOW GRND RANGE THETA I Q*ALPHA TOT	S EC L BS L BS/SEC N. MI. DEG DEG-PSF	THRUST (8) THRUST (S) THRUST (V) THRUST CORR (B) THRUST CORR (S) PC(B)	LBS LBS LBS LBS LBS LBS PS PS PS PS PS PS PS PS PS PS PS PS PS	THRUST XI THRUST ETA THRUST ZETA	ר 98 ר 98 ר 98	0 302958.09 1502.2778 0.4200749E-04 0.7002325E-06 64.641945	306155.89 55205.240 1710.5033 363071.63 -55.678170 -1201.7500	363070.31 588.02676 681.57074
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28.310632 -80.538034 53.339885 117.49613 89.900731 2.4472004	71.104920 71.242257 50.350000 69.074999 2.2166579 2.2847680	297.95220 624.74998	28.310669 -80.538079 24.103556 120.10998 89.878240 2.4296005 70.841620 71.0.85792	2.2173516 2.2173516 2.3080811 298.99172 624.74998	28.310714 -80.537758 91.378385 91.7.44130 90.026930 2.3944007	73.029760 50.35000 69.059998 2.2188258 2.3281154 299.33569 624.74998
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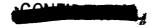


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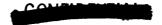
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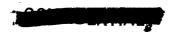


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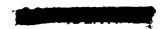
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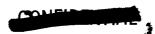
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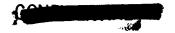




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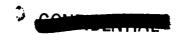
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0.1093610E-05 0.1118462E-01 0.9105486E 08 10.072775 7153.7345	0.109361)E-05 31.587852 53.876928 32.899998 3284.0000	0.8629974E-06 0.9105509E-02 0.9105509E-02 9.5788537 5086.2425 302.07665 0.8629974E-06 31.532108 32.899998 32.899998	0.8679974E-06 0.7865507E-07 0.9105509F-07 9.5084532 5086.2425 302.07755 0.8629974E-05 31.532109 53.657229 32.89998 3295.0000
-0.2484720 0.3364906E-01 0.4530170 1.4793786 50.000000	0 21.500001 1167.6998 920.72733 31.544178 -5.1499999 0	-0.1747360 0.236609E-01 0.3261872 1.4966295 50.000000 -0.6146729E-05 0 21.143000 1168.8225 922.00127 31.911768 -5.1499999	-0.1747360 -0.2366069E-01 0.35618372 1.555883 50.000000 -0.6146729F-05 0 21.143000 1168.8225 922.00127 33.321890 -5.1499999
1581.2112 79169.040 13.867694 13.934506 12.246757 -50.000000	27.881701 46.588388 2342.4308 5701.4518 1.4793786 0.4338280 0 0	1581.2378 79158.443 13.617264 13.677234 -50.000000 27.881701 46.709158 2158.3477 5249.7181 1.4966295 0.4338280	1581.2477 79162.984 13.612264 13.677234 12.033834 -50.000000 27.881701 47.379804 2158.3477 5249.7181 1.5558832 0.4338280
27.808677 -78.187296 104.78709 104.45141 102.61073 2.6547566	50.236234 44.607235 50.350000 68.477837 2.0862122 2.4540157 410.03476 382.66088	27.793115 -78.118752 104.82855 104.48755 102.65884 2.6547570 50.236234 44.36891 50.4350000 68.485555 2.0862122 2.4539142	27.793115 -78.118752 104.48285 104.48285 102.65884 2.6547570 50.236234 44.467499 50.350000 68.485555 2.6962122 2.4539860
6.2810651 0.5536286 17.266645 0 1.2244045 128.17982	0 189.81641 0 189.81641 0.6753274 6.8537498 354.50630 605.26170 1.2335937		1.95/3943 6.3803362 0.5535569 17.037514 0 1.2752739 131.93918 0 189.80199 0.6753274 6.8537498 354.51441 584.47345 1.3091874 2.0503575
350380.75 0.2126075E 08 10000.673 9953.6653 11299.932 57.665255	0 77.349304 0 77.349304 0.2980261 -6.0374998 673.60709 0.1165029 0.1822191	356044.75 0.2126643E 08 10.2126643E 08 10065.249 11397.123 58.597430 0 77.341846 0 77.341846 0 0 77.341846 0 0 0 17.341846 0.2980261 -6.0374998 673.51692 0.1172382 0.1172382	356044.75 0.2126643E 08 10096.349 10049.298 11397.123 58.597430 0 77.344366 0.2980261 -6.0374998 673.55556
0*1 209.99999 P 2 54583.333 1 3 267.31571 4 128.18510 5 2.8924314 6 0.7051939E-01	E 2 79165.040 P 3 1581.2112 R 4 80750.251 O 5 -524.80187 ¢ -157.49999 7 0.2336633E-01 O 1 80749.663 P 2 164.19337 5 3 256.81089	0*1 212.38000 P 2 53947.159 1 3 267.22.10 4 131.94477 5 2.963540 6 0.5036996E-01 D 1 0 E 2 79158.443 P 3 1581.2378 R 4 80739.681 O 5 -524.80187 6 -157.49999 7 0.2336633E-01 P 2 165.20790	*



CONFIDENCE

0.4819165E-16 0.3332103E-12 0.9105549E 08 8.2821482 2225.9537	0.4819165E-75 31.353622 52.953845 32.899998 3320.0000	C C O	0.3751541F-06 0.2324257E-02 0.9105561E n8 7.8398361 1581.6271	0.3751541E-06 31.254770 52.561537 32.89999 3329.0000	000
-0.7402432E-01 0.9987276E-02 0.1438762 1.6187246 50.000000 -0.6146729E-05	0 20.000001 1173.0209 926.80141 34.534568 -5.1499999	000	-0.5163454E-01 0.6946930E-02 0.1011999 1.6560168 50.000000	0 19.362500 1175.8558 930.19415 35.142348 -5.1499999	000
1581.3300 79127.674 12.840951 12.900310 11.392188 -50.000000	27.881701 47.783988 1569.0775 3803.7578 1.6187246 0.4338280	0 -20.750300 2.6162211	1581.3731 79106.739 12.434006 12.490442 11.052932	27.881701 47.976960 1240.4983 2991.5777 1.6560168 0.4338280	0 -13.298141 1.7378443
27.741881 -77.89444 104.96087 104.60405 102.81577 2.6543081	50.236234 43.671519 50.350000 68.510268 2.0862122 2.4536391	416.36102 382.65396	27.112337 -77.766000 105.03606 104.67031 102.90442 2.6538625	50,236,234 43,200,425 50,350000 68,524053 2,086,2122 2,4534,259	417.20313 382.64878
6.5531623 0.5513231 16.201107 0 1.4439840 144.25005	0 189.71468 0 189.71468 0.6753274 6.8537498 354.53269	566.03841 1.3704381 2.1415065	6.5893821 0.5495964 15.694752 0 1.5419794 151.30495	0 189.66278 0 189.66278 0.6753274 6.8537498 354.5428	554.01657 1.4071715 2.1915975
373873,75 0.2128431E 08 10428,786 10381,609 11734,037 61,531705	0 77.319717 0 77.319717 0.286261 -6.0374998 673.25511	0.1215584 0.1899704	383629.00 0.2129409E 08 10622.346 10575.108 11929.902 63.137213	0 77.305283 0 77.305283 0.2980261 -6.0374998 673.07700	0.1225351 0.1908532
219.99999 49859.185 267.1844C 144.25651 3.1958002	0 79127.674 1581.3300 60709.003 -524.80187 -157.49999 0.2336633E-01	80708.362 171.23067 267.59831	224.25000 48723.789 267.11806 151.31202 3.3284844 0.1536767E-01	0 79106.739 1581.3731 80688.112 -524.80187 -157.49995 0.2336633E-01	80687.466 172.56186 268.77234
0 4 1 2 4 4 6 7	O H O K O	0 1 P 2 5 3	1	0 M P M 0 L 0 M P M 0 L 0 M P M P M P M P M P M P M P M P M P M	0 1 P 2 5 3

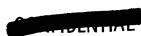
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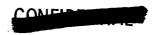
ATM PRESS DYNM PRESS HEAT PARAM MACH NUMPER RHO-VR CURED TOTAL ISP PSI LBS/FT SOD FT*LRS/FT SOD	SEC COBEST SEC TRUE ANOMALY ASCEND NODE DEG	0.3751541E-96 0.2324257E-02 0.9105561F 08 7.8398361 1581.6271	177.07429	0.3635055F-06 0.221443E-02 0.9105562E 08 7.774016 1508.1105	177.08295 165.94000	0.364535555-06 0.22144345-02 0.9105562E 38 7.7740168 1508.1105 27964.607	165.94030 165.94030 0.3522351F-06 0.2105564F-02 0.9105564F-02 7.7067233
AXL FORCE SIDE FORCE NORM FORCE AXL LD FCTR WIND VEL NORTH WIND LBS LBS	FT/SEC FT/SEC ECCENTRICITY INCLINATION DEG	-0.5163454E-01 0.6946939E-02 0.1011999 1.6560301 50.103000	0.7936512 30.352316	-0.4919473E-01 0.6609856E-02 0.983254E-01 0.8616025E-01 50.000000	0.7932379 30.352838	-0.4919473E-01 0.6609856E-02 0.9833254E-01 0.8616025F-01 50.000000 -0.6146729E-05	0.192219 30.352838 -0.4677483E-01 0.9552980E-01 0.5390631E-01 50.000000
THRUST FIXED THRUST CONTI GAMMA E GAMMA R GAMMA I EAST MIND LBS UBS DEG DEG	FT/SEC SEMI MAJ AXIS ENERGY NM FT##2/SEC##2	80688.113 0 12.434006 12.490442 11.052932 -50.000000	1963.6635 -0.5898924E 09	4194.6910 0 12.366856 12.422944 10.994076 -50.000000	1964.1564 -0.5897443E 09	4194.6910 0 12.366856 12.422944 10.994076 -50.000000	2624.4268 0 12.290920 12.346681 10.926112
GEDCENT LAT LONGITUDE AZI R AZI I PHI I DEG DEG	DEG SEMI LAT REC PERIOD NH MIN	27.712337 -77.766000 105.03606 104.67031 102.90442 2.6538625	726.78672 36.376448	27.708209 -77.748108 105.04769 104.8084 102.91521 2.6517998	728.25743 36.390146	27.708209 -77.748108 105.04769 104.68084 102.91521 2.6517998	27.703979 -77.729787 105.06010 104.69220
ALPHA BETA BETA PSI PSI CROSS RANGE DOWN RANGE DEG DEG DEG DEG	N.MI. PERIGEE VEL APOGEE VEL FT/SEC FT/SEC	6.5893821 0.5495964 15.694752 0 1.5419794 151.30495	101267.35 11650.199	6.6753512 0.5487771 15.694752 0 1.5556711 152.28798	101141.73 11661.742	6.6753512 0.548771 15.694752 0 1.5556711 152.28798	11661.742 6.7705284 0.5485377 15.694752 0
ALTITUDE RADIUS VEL E VEL R VEL I ALT FT FT FT FT/SEC FT/SEC	N.MI PERIGEE ALT APOGEE ALT NM	383629.00 0.2129409E 08 10522.346 10555.108 11929.902 63.137213	-3038.7339 78.193848	384963.00 0.2129543E 08 10630.902 10583.654 11938.827 63.356761	-3037.8204 78.266144	384963.00 0.2129543E 08 10630.902 10583.654 11938.827 63.356761	78.266144 386320.00 0.2129679E 08 10628.290 10581.031
1 TIME 2 WEIGHT 3 TOTAL FLUW 4 GRND RANGE 5 THETA I 6 Q*ALPHA TOT 1 SEC 2 LBS 2 LBS 3 LBS/SEC 5 DE	DEG-PSF PERIGEE RAD APOGEE RAD NM	224.25000 48723.789 267.11806 151.31202 3.3284844 0.1536767E-01	405.19958 3522.1274	224.8360C 48684.186 0.1500000 152.29516 3.3469507 0.1483109E-01	406.11311 3522.1997	224.83 48684. 0.150C 152.29 3.3469 0.1483	
	6 1 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	0 4 1 8 4 8 4 8	0 1	# C = 1 # C = 2 # C = 4 P & 6	0 1 4 2	★	4 Dd 4





•	6 0.1430122E-01	63.580095	153,29480	2.6496878	-50.000000	-0.6146729E-05	17496-179
04		-3037.7214 78.273834	101128.13 11662.992	728.41684 36.391629	1964.2098 -0.5897283E 09	0.7931931 30.352935	177.10083 166.93955
1 P 0 4 2 4 2 4 2 4 2 4 2 4 2 4 2 4 2 4 2 4		386320.00 0.2129679E 08 10628.290 10581.031 11936.627	6.7937682 0.5531541 15.717998 0	27.703979 -77.729787 105.06010 104.6920 102.92515	2624.4268 0 12.290920 12.346681 10.926112	-0.4677482E-01 0.6329569E-07 0.9602954E-01 0.5390631E-01 50.009000	0.3522351E-06 0.3105504E-02 0.9105564E 18 7.707222 1433.5707
04	6 0.1435076E-01 1 406.21216 2 3522.2074	63.580095 -3037.7214 78.273834	101128.13	728.41684 36.391629	1964.2098 -0.5897283E 09	0.7931931 30.352935	177,10083 166,93955
* 1 7 4 4 5 7 4 5 7 5 7 5 7 5 7 5 7 5 7 5 7	1 226.65000 2 4868.914 3 0.1500000 4 15.33902 5 3.404127 6 0.1349856E-C1 1 406.32396	389040.50 0.2129952E 08 10621.874 10574.593 11931.043 64.027831	7.0541269 0.5575332 15.784914 0 1.5985922 155.33158 101112.79	27.695410 -77.692724 105.08526 104.71524 102.94511 2.6547633 728.59477	1772.1571 0 12.136397 12.191496 10.787706 -50.000000 1964.2699 -0.5897103E 09	-0.4234134E-01 0.5775707E-72 0.9215604E-01 0.3440047E-01 50.000000 -0.6146729E-05 0.7931425	0.3312478E-36 0.1007735E-02 0.9105567E 39 1298.1285 11814.380 177.13795
1 2 2 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	1 226.65000 2 36243.000 3 0.1500000 4 155.33902 5 3.4041227 6 0.1349856E-C1	389040.50 0.2129952E 08 10621.874 11931.043 64.027831	7.0541269 0.5575332 15.784914 0 1.5985922 155.33158	27.695410 -77.692724 105.08526 104.71524 102.94511 2.6547633	1772.1589 0 12.136397 12.136397 12.191496 10.787706 -50.000000	-0.4238138E-01 0.57757075-02 0.9215604E-01 0.4889541E-01 50.000000	0.3312478E-06 1.1907739E-07 0.9105567F
0 4	1 406.32396 2 3522.2158 \$\$ SEPARATION	-3037.6096 78.282227	101112.79 11664.405	728.59677 36.393300	1964.2699 -0.5897103E 09	0.7931425 30.353085	177.13795 165.93885





ATM PRESS DYNM PRESS HEAT PARAM MACH NUMBER RHO-VR CUBED TOTAL ISP	PSI LBS/FT SQD FT:LBS/FT SQD LBS/SEC CUBFD SEC	TRUE ANOMALY ASCEND NODE DEG DES	0.3312478F-06 0.1907739E-02 0.9105567E 18 7.5587977 1298.1285 1.8166667	0.3110198E-06 0.1723571E-02 0.910559E 08 7.4146435 1171.9727	165.93847 0.311/198E-05 0.1723571E-02 0.9105569E 78 7.4145435 1171.8727	177.17926 165.93843 0.2836838E-75 0.1485962E-72 0.9105572E 08 7.2085905
AXL FORCE SINE FORCE NORM FORCE AXL LD FCTR WIND VEL NORTH WIND	LBS LRS L9S FT/SEC FT/SEC	ECCENTRICITY INCLINATION DEG	-0.1497575 0 0.2364661E-03 50.000000 -0.6146729E-05 0.7931425	-0.1353003 0.0.2369061E-03 50.000000 -0.6146729F-05	30.353183 -0.1353003 0 0.2369061E-03 50.000000 -0.6146729E-05	0.7931417 30.353183 -0.1166480 0.2374850E-03 50.000000
THRUST FIXED THRUST CONTL GAMMA E GAMMA R GAMMA I FAST MIND	LBS LBS DEG DEG DEG FT/SEC	SEMI MAJ AXIS ENERGY NM FT**2/SEC**2	8.7199999 0 12.136397 12.191496 10.787706 -50.000000 1964.2699 -0.5897103F 09		-0.5897101E 09 8.7199999 0.11.968357 12.022741 10.637064 -50.000000	1964.2706 -3.5897101E 09 3.7199999 11.706170 11.759435
GEOCENT LAT LONGITUDE AZI E AZI R AZI I PHI	0 E G 0 E G 0 E G 0 E G 0 E G	SEMI LAT REC PERIOD NM MIN	27.695410 -77.692724 105.08526 104.71524 102.94511 2.6547633 728.59677	27.686152 -77.652748 105.11246 104.74016 102.96648 2.6547633	36.393318 27.686152 -77.652748 105.11246 104.74016 102.96648 2.6547633	728,59939 36,393318 27,671710 -77,590535 105,15477 104,77892
ALPHA BETA PSI PSIDOT CROSS RANGE DOWN RANGE	DEG DEG DEG DEG/SEC N.MI.	PERIGEE VEL APOGEE VEL FT/SEC FT/SEC	7.0541269 0.5575332 15.784914 0 1.5985922 155.33158 101112.79	7.2641584 0.5617750 15.784914 0 1.6297189 157.52896.	11664.427 7.2641584 0.5617750 15.784914 0 1.6297189 157.52896	101112.57 11664.427 7.5917206 0.5684011 15.784914 0
ALTITUDE RADIUS VEL E VEL R VEL I	FT FT SEC FT/SEC FT/SEC FT/SEC M.MI	PERIGEE ALT APUGEE ALT NM	389040.50 0.2129952E 10621.874 10574.593 11931.043 64.027831 -3037.6096 78.282227	391935.25 0.2130243E 08 10613.446 10566.139 11923.506 64.504246	78.281952 391935.25 0.2130243E 08 10613.446 10566.139 11923.506 64.504246	-3037.6079 78.281952 396359.75 0.2130687E 08 10600.557 10553.214
TIME WEIGHT TOTAL FLOW GRND RANGE THETA I	S E C L B S S E C L B S S E C N M M N M N M N M N M N M N M N M N M N	PERIGEE RAD APOGEE RAD NM	226.65000 36243.000 4.8000000 155.33902 3.4041227 0.1349856E-C1 406.32396 3522.2158	227.9600 36236.71 4.800000 157.5365 3.445401 0.125568	3522.2155 227.96000 36236.712 4.8000000 157.53655 3.4454010 0.1255688E-01	406.32560 3522.2155 230.00000 36226.920 160.95737 3.5096611
126450	O C S 4 . 2 . 4	0 1 2 4 5 2 4 5 5 5 6 1 1 6 5 6 1 1 6 6 6 6 6 6 6 6 6	00dm 04 #0400400 10	0 d d d d d d d d d d d d d d d d d d d	*	0 1 4 5 1 1 3 3 4 4 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5





CONFID

ATM PRESS DYNM PRESS HEAT PARAM MACH NUMBEP RHO-VR CUBED TOTAL ISP PSI LBS/FT SQD FT!LBS/FT SQD ET!LBS/FT SQD	TRUE ANOMALY ASCEND NODE DEG DEG	C-1 PU VALVE C-2 PU VALUE C-1 LO2 TEMP C-2 LO2 TEMP DEG DEG P DEG P	0.2185029E-03 0.9793392E-03 0.9105531E 03 6.55651 663.82648 430.79899 177.44029 166.93155	-281.64915 -281.44914 0.2102753E-06 0.9756751E-03 0.910582E 09 6.5053881 628.48456 430.99631 177.45329 165.92569
AXL FORCE SIDE FORCE NORM FORCE AXL LD FCTR WIND VEL NORTH WIND LBS LBS FT/SEC FT/SEC	ECCENTRICITY INCLINATION DEG	C-2 ISP C-2 FLOW C-1 LH2 TEMP C-2 LH2 TEMP SEC DEG R	-0.7687813E-01 0 0.8452268 50.000000 -0.6146729E-05 0.7924237 30.354679 430.65209 35.368801	-420.39999 -420.39999 -0.7261839F-01 0.8459106 50.000000 -0.6146729F-05 0.7913917 30.355963
THRUST FIXED THRUST CONTI CAMMA E GAMMA R GAMMA I EAST WIND LRS LRS DEG DEG DEG FT/SEC	SFMI MAJ AXIS ENERGY NW FT**2/SEC**2	C-1 ISP C-1 FLOW C-1 LOZ PRESS C-2 LOZ PRESS SEC LBS/SEC PSI	30551.359 0 10.851653 10.901141 9.6393986 -50.000000 1965.1179 -0.5894558E 09 431.95137 35.446099	67.590700 66.467526 30507.387 0.729560 10.778380 9.5331697 -50.000000 1966.3377 -0.5890901E 09
GEOCENT LAT LONGITUDE AZI E AZI R AZI I PHI DEG DEG DEG DEG	SEMI LAT REC PERIOD NM MIN	LHZ WEIGHT LO2 WEIGHT C-1 LHZ PRESS C-2 LHZ PRESS LBS LBS LBS/SEC PSI	27.623670 -77.384869 105.29341 104.90570 103.11165 2.6547633 731.15109 36.416870 4983.8120 24357.911	36.396900 39.208487 27.615460 -77.349907 105.31563 104.92572 103.13330 2.6547633 734.81866 36.450784
ALPHA BETA BETA PSI PSIDOT CROSS RANGE DOWN RANGE DEG DEG DEG DEG DEG/SEC N.MI.	PERIGEE VEL APOGEE VEL FT/SEC	C-2 THRUST C-2 LH2 FLOW C-2LOZ FLOW C-2 RATIO LBS LBS/SEC LBS/SEC	8.6625988 0.5892965 15.784914 0.8451960 172.26479 100895.55 11684.475 15231.648 5.8159851	29.552816 5.0813087 8.8215104 0.5913053 15.784914 0 1.8740665 174.18942 100585.51 11713.221
ALTITUDE RADIUS VEL E VEL I VEL I ALT FT FT FT FT/SEC FT/SEC N.MI	PERIGEE ALT APOGEE ALT NM NM	C-1 THRUST C-1 LH2 FLOW C-1 LOZ FLOW C-1 RATIO LBS LBS/SEC LBS/SEC	410280.75 0.2132084E 08 10581.289 10533.832 11896.953 67.523527 -3036.0215 78.390259 15319.711 5.7450033	29.701096 5.1699005 412545.25 0.2132311E 08 10605.497 10558.024 11921.749 67.896215 -3033.7392 78.547638
0 1 TIME P 2 WEIGHT 1 3 TOTAL FLOW 4 GRND RANGE 5 THETA I 6 Q*ALPHA TOT 0 1 SEC P 2 LBS 1 A N. MI. 5 DEG 6 DEG-PSF	1 PERIGEE RAD 2 APOGEE RAD 1 NM 2 NM	1 THRUST 2 LH2 FLOW 3 LO2 FLOW 4 RATIO 1 LBS 2 LBS/SEC 4 BS/SEC 4	1 236.75395 2 36145.664 3 70.917899 4 172.27346 5 3.7222593 6 0.8502640E-02 1 407.91199 2 3522.3238 1 30551.359	3 55.253911 4 5.1253327 1 237.90000 2 36064.466 3 70.783407 4 174.19850 5 3.7584106 6 0.8178300E-02 1 410.19428 2 3522.4812 1 30507.387



CUMEIDE

-0 -281.87096 -281.67096	0.2102753F-06 0.9250751E-03 6.9105587E 08 6.5053882 628.48463 430.99631 177.45329 166.92569	-0 -281.87096 -281.67096 -281.67096 0.1964323E-06 0.8373766E-03 0.9105584E 08 6.5031601 571.29837	177.47620 166.91470 -0 -282.19999 -282.0000	0.1486143F-76 0.5602209E-73 0.9105591F 78 5.1152771 397.00945 431.882921 177.58730	-0 -282.45365 -282.43048 -282.43048 0.1263950F-06 0.4105595E 08 5.9174991 315.14196
35,330849 -420,34515 -420,39999	-0.7261839E-01 0.8459106 50.000000 -0.6146729E-05 0.7913917 30.355963	430.70580 430.70580 54.30849 -420.39599 -0.6573430E-01 0 0 0.8474691 50.000000 -0.6146729E-05	0.7895043 30.358381 430.87543 35.260392 -420.43999	-0.4397734F-01 0.0.8604904 50.0000000 -0.6146729E-05 0.7803189 30.369774	431.43251 35.042048 -420.53841 -420.43840 0 0.8712043 50.000000 -0.614672 9F-05
35.349560 63.487094 64.064515	30507.387 0 10.729560 10.778380 9.5331697 -50.000000 1966.3377 -0.5890901E 09	432.29579 432.29579 53.48794 64.064515 30437.817 0 10.560770 9.3448696 -50.000000	1968.5781 -0.5884197E 09 432.88560 35.196968 57.119999 59.860000	30300.625 0 9.5185270 9.568644 8.4781723 -50.000000 1979.5040 -0.5851719£ 09	433.24712 35.023028 54.299999 54.876218 30245.424 0 8.8502674 8.8890076 7.8945599 -50.000000
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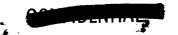


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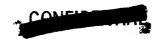
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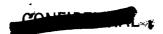


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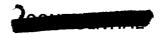


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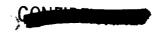


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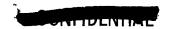
ATM PRESS DYNM PRESS HFAT PARAM MACH NUMBER RHO-WR CURED TOTAL ISP PSI LBS/FT SQD FT*LRS/FT SQD ET*LRS/FT SQD SEC	TRUE ANOMALY ASCEND NODE DEG	0.47394536-07 0.47433396-03 0.91057255 08 9.9643199 739.41037 101.16926 -42.117909	0.4739804E-07 0.4745897E-03 0.9105725E 08 9.9676880 740.60809 101.15926 -31.833172	0,4739804E-07 0,4746897E-03 0,9105725F 08 9,9675989 742,60809 101,16926 -31,833172 165,78303
AXL FORCE SIDE FORCE NORM FORCE AXL LD FCTR WIND VEL NORTH WIND LBS LBS LBS FT/SEC	ECCFNTRICITY INCLINATION DEG	-0.3723521E-01 0 1.3548418 50.000000 -0.6145729E-05 0.1928170E-02	-0.3726314E-01 0 1.3581553 50.000000 -0.6146729E-05 0.2416869E-02	-0.3726314E-01 0 1.3581553 50.000000 -0.6146729E-05 0.2416869E-02 30.688760
THRUST FIXED THRUST CONTL GAMMA E GAMMA R GAMMA I EAST WIND LBS DEG DEG DEG DEG	SEMI MAJ AXIS ENERGY NM FT**2/SEC**2	17333.330 0 -0.7951450E-01 -0.7535267E-01 -50.000000 3538.3136 -0.3273735E 09	17333.330 0 -0.7776642E-01 -0.7791328E-01 -0.7369709E-01 -50.000000 3540.5085	17333.330 0 .7776642E-01 -0.7791328E-01 -0.7369709E-01 -50.000000 3540.5085 -0.3271706E 09
GEOCENT LAT LONGITUDE AZI E AZI I PHI DEG DEG DEG DEG	SEMI LAT REC PERIOD NM MIN	23.005694 -62.289019 113.03904 112.14796 110.89108 2.9916047 3538.3004	23.001249 -62.277132 113.04410 112.15288 110.89609 2.9916047 3540.4878	23.001249 -62.277132 113.04410 112.15288 110.89609 2.9916047 3540.4878 88.068005
ALPHA BETA PSI PSIDOT CROSS RANGE DOWN RANGE DEG DEG DEG N.MI.	PERIGEE VEL APOGEE VEL FT/SEC	5.3028592 1.0963539 -14.153330 0 23.220815 1036.5732 25637.411 25538.734	5.3135678 1.0963791 -14.153330 0 23.242865 1037.2823 25641.991 25518.343	5,3135678 1,0963791 -14,153330 0 23,242865 1037,2823 25641,991 25518,343
ALTITUDE RADIUS VEL R VEL I VEL I ALT FT FT FT/SEC FT/SEC FT/SEC	PERIGEE ALT APOGEE ALT NM	552912.25 0.2146785E 08 24284.583 2428.266 25625.372 90.997653 87.557587	552902.00 0.2146/84E 24292.512 24245.12 24246.196 25633.298 90.995966 88.018036 105.13187	552902.00 0.2146784E 08 24292.512 24246.196 25633.298 90.995966 88.018036 105.13187
TIME MEIGHT TOTAL FLOW GRND RANGE THETA I Q*ALPHA TOT SEC LBS LBS/SEC N•M!• DEG-PSF	PERIGEE RAD APGEE RAD NM	573.09016 12793.592 171.33000 1036.7813 19.32029 0.2567923E-02 3531.4911	573.27234 12762.379 171.33000 1037.4906 19.332490 0.2574828E-02 3531.9516	573.27234 12762.379 17.33000 1037.4906 19.332490 0.2574828E-02 3531.9516 3549.0654
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