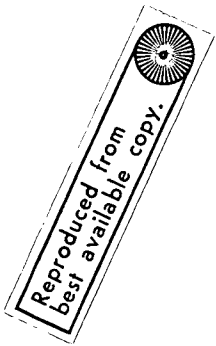
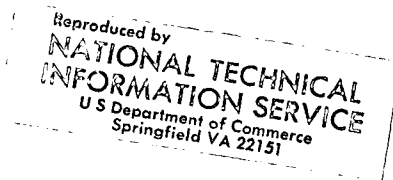


NASA CR-122417



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Antenna Control System

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Contracting Officer: Alton D. Payne, Jr.

Technical Monitor: N.A. Raumann

Prepared By:

Space Systems Department
Wolf Research and Development Corporation
6801 Kenilworth Avenue
Riverdale, Maryland

Project Manager: John J. Zarur

for

Goddard Space Flight Center
Greenbelt, Maryland

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ABSTRACT

The objective of the Antenna Control System is to utilize the analysis and software development performed for the simulated 40-foot antenna system to produce a unified software package providing complete computer control of the 40-foot antenna system at the NTTF.

The control system comprises a position programmer, scan generator and a digital controller.

The programs developed under this contract were meant to prove certain concepts with the emphasis placed on achieving operational status.

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SECTION 1.0 INTRODUCTION

This final report covers work performed under task order NAS 5-9756-192. During the period, beginning in April 1969 and ending in November 1970, a real-time antennna control system was developed and tested at the NTTF facilities. Programs developed under task orders NAS 5-9756-103, -112 and -117 were incorporated, some in substantially modified form, into the final version.

1.1 PURPOSE AND SCOPE OF WORK

The object of this work is to design, develop and test a real-time antenna control system, utilizing a digital computer and related peripherals, for the 40-ft antenna at NTTF. The control system comprises a position programmer, scan generator and a digital controller. The digital controller may be used to replace the servo-amplifier. When the digital controller is selected the antenna is completely controlled by the real-time program in all its modes of operation.

1.2 DESIGN PHILOSOPHY

By definition, digital systems are discrete as opposed to continuous for analog systems. For controlling analog devices, there is a lower bound to the frequency at which the digital device must operate. This will be determined in another section. The frequency of operation shall be referred to as the sampling frequency. A simple method to insure this condition is achieved by executing the necessary operations at the occurrence of an interrupt at the specified frequency.

The totality of operations to be performed make up the real-time program. It is divided into modules according to function. When the interrupt becomes active, a 12 entry schedule is executed. Each slot in the schedule references a particular module. Some entries are permanent while others are selected according to the mode of operation desired. The updating of the schedule is the function of the mode control program, while the executive program handles the interrupt and executes the current schedule.

It is obvious that one of the permanent entries must be the mode control program. Another is the display program which updates the real-time display to be found on the antenna console. These displays show the command time, real position and command position. Still another permanent entry will be discussed in the section on program mode.

SECTION 2.0

GENERAL DESCRIPTION OF THE SYSTEM

2.1 SYSTEM BLOCK DIAGRAM

Figure 1 shows the block diagram of the real-time system. The dotted line represents the boundary between the analog and digital components. Inputs to the program are handled by A/D converters and the outputs by D/A's. The time and position bias are transmitted by discrete inputs. This applies also to status information from the antenna console. Limit indicators as well as type I or type II operation are transmitted to the console via discrete outputs.

Moving from left to right the first block encountered in Figure 1 is the tape input to the predict interpolation program. The start address of this program is permanently stored in the schedule table. Essentially, this program outputs predict angles interpolated from data acquired from previous passes of the specific satellite or from knowledge of intended orbit before launch. This data is received in ENV coordinates. The ENV to XY conversion program prior to a pass reduces this data to XY angles one second apart. During a pass the data is interpolated to produce predict X and Y angles every 1/20 of a second. This program is always executed regardless of the mode of operation desired.

If stow mode is selected then the stow program is executed. It produces command angles corresponding to the stow position of the antenna.

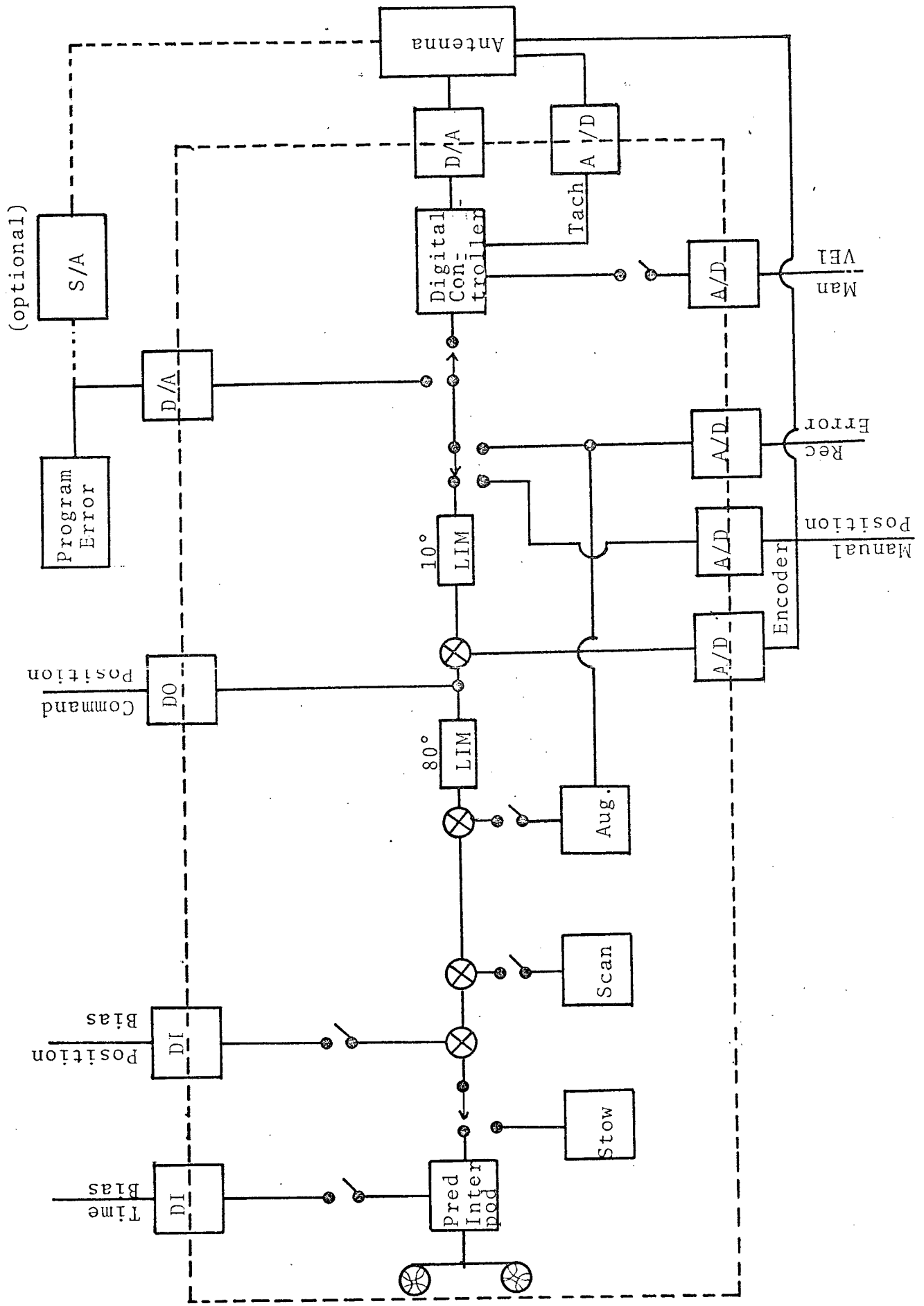


Figure 1. System Block Diagram (One axis)

At this point three options can be exercised. A position bias can be added to the command angle, scan can be superimposed over the predicts or augmentation may be added.

The modified command angle is then checked to insure its validity. The limits on the X and Y command angles are derived from the contour limits of the antenna.

The servo error is calculated next as the difference between the command angle and the real position of the antenna. This error is limited to 10° . If any of the position modes are selected then this error is used to point the antenna.

If manual position is selected the output of the joy stick after suitable processing by the demodulator is fed by an A/D to the real-time program. The angle is set to this value.

However, in the autotrack mode the receiver error is used to drive the antenna. The error can be fed either to the analog servo-amplifier or to the digital controller. The functions of both of these devices will be discussed in a later section. The outputs of either is a valve voltage, which operates the hydraulics that move the antenna.

SECTION 3.0

CONTROL PROGRAMS

The executive and the mode control programs define the operation of the system. The executive program executes the appropriate programs according to a priority scheme previously determined by the mode control program. The mode of operation is selected at the antenna console. Then mode control reinitializes the schedule table to reflect the status of the console.

3.1 ANTENNA EXECUTIVE

When the program interrupt occurs the $\Sigma 5$ operating system branches to the starting address of the antenna executive program. At this point, the interrupt is said to be in the active state. So long as the interrupt is active no lower priority operation will be executed by the computer.

The first task is to update the interface. This is performed by the subroutine APIO. The interface holds the previous values until it is updated. The inputs are read and used to calculate the appropriate outputs which are subsequently written to the interface.

Next, the real-time is obtained in BCD format and converted to seconds by the subroutine ASTIME. This time is used by the predict interpolation program in finding the correct predicts from the tape.

The schedule table is executed next. Typical schedules are discussed under mode control. Finally, the interrupt is reset and control is returned to the $\Sigma 5$. The execution time varies according to the mode of operation. The maximum time measured is less than 20 ms. Since the interrupt occurs every 50 ms, this allows 30 ms to be used in executing other programs until the next interrupt occurs.

3.2 MODE CONTROL

As described earlier, the schedule table (Table 1) contains several permanent entries, one of which must be mode control. The function of this program is to update the schedule to reflect the current status of the antenna console. The program is in two parts. The first part checks the discrete status function #1 (Table 2) for any changes. If no change is indicated the schedule is not updated. However, if the status has changed the second part is executed. The status function is scanned and the appropriate programs are entered into the schedule table.

Five modes are presently implemented, namely, program, manual velocity, manual position, autotrack and stow.

For program mode the antenna is driven according to data obtained from previous passes or projected orbits. Since this data is not necessarily exact, provisions are incorporated that allow improvements in tracking accuracy. Scan is used as an aid to acquisition of the satellite. Augmentation improves tracking by forcing a receiver null. Moreover, the add or subtract time, add X and add Y bias switches, allow manipulations of orbit data to improve tracking.

Manual velocity drives the antenna at a velocity proportional to the output of the joy stick. Similarly, in the manual position mode, the output of the joy stick is used to drive the antenna to the position indicated by the console synchroes.

For the Autotrack mode, the receiver error determines velocity of antenna. The stow mode drives the antenna to predetermined angles corresponding to the stow position of the antenna.

A proposed new schedule is shown in Table 3.

TABLE 1
SCHEDULE TABLE

APSCHDLE	APPRED
+ 1	Stow
+ 2	N/U*
+ 3	Apsec, Manual Position
+ 4	N/U*
+ 5	Aprjoy, Aprslav, AUTOTRAK
+ 6	N/U*
+ 7	N/U*
+ 8	Ap@dcomp1
+ 9	Ap@dcomp5, Apsaout
+10	APPMODE
+11	APDISPLY

* Not Used

Entries in Capital Letters are Permanent

TABLE 2
DISCRETE STATUS FUNCTION #1
AISTAT1 (APSTAT1)

BIT POSITION	
16	Digital Controller
17	Servo-Amplifier
20	Manual Position Mode
21	Manual Velocity Mode
22	Slave Mode (Not Implemented)
24	Stow Mode
25	Autotrack Mode
26	Program Mode

TABLE 3
PROPOSED NEW SCHEDULE TABLE

0	MODE CONTROL
1	STATION TIME
2	Add Time or Subtract Time
3	PROGRAM MODE
4	Manual Program Mode (Predicts = 0)
5	Add X Bias
6	Add Y Bias
7	Scan or Augmentation
8	Stow or Manual Position
9	Position Limit Check
10	Servo Error Calculation or Autotrack
11	Error Limit Check
12	Digital Position Loop or Manual Velocity
13	Digital Velocity Loop
14	Output to S/A or Value Driver
15	OUTPUT to DISPLAYS and INTERFACE I/O

SECTION 4.0

MODES OF OPERATION

4.1 PROGRAM MODE

Command angles generated by this program are derived from data obtained from a predict tape. The format of this data is shown in Figure 2. The predicts are read, ten records at a time, and written into either of two buffers, as shown in Figures 3 and 4. The choice of buffer depends on the mode of operation, which is itself determined by the location of the buffer pointer. If the pointer points to a record in the second buffer, the program is in mode 1 operation. Consequently, the data in buffer 1 is old and is replaced with new data from the predict tape. When the buffer pointer locates a record in the first buffer, the data in the second buffer is updated. The data in either buffer is exhausted in 10 seconds, which is much greater than the time needed to perform the I/O operations necessary to fill the other buffer. Once a buffer has been filled, a flag is set to guard against it being filled again until it has been used. This flag is reset when the other buffer is filled. Since the I/O is performed simultaneously with program processing the effective I/O time is negligible.

Assuming that the data in the buffers is current, then the buffer pointer is obtained as follows:

Assume that the station time is 00:10:23 or 623 secs. The difference between this quantity and the time in the first record of buffer 1 is calculated. Referring to Figure 3 we find that this difference is $623 - 610 = 13$. This will be the buffer pointer in mode 0 operation. In mode 1 operation, the predict time of the first record

WORD

1

Satellite ID

2

Time in Seconds

3

X-Command

4

Y-Command

5

X-Velocity

6

Y-Velocity

7

Date

8

For Future Use

Figure 2. Predict Tape Format

	SAT. ID	TIME	ETC.....		
BUFFER 1		610		Record	0
		611			1
					2
					3
BUFFER 2					4
					5
					6
		619			9
		620			10
					11
					12
					13
					14
		629			19

Figure 3. Predict Buffers - Mode 0

	SAT ID	TIME	ETC.....	
BUFFER 1		630		Record 0
		631		1
BUFFER 2				
		639		9
		620		10
		629		19

Figure 4. Predict Buffers - Mode 1

of buffer 1 is 630 (Figure 4). The difference between the station time and the predict time is then $623 - 630 = -7$. To obtain the buffer pointer, we add 20 to -7 and the pointer is 13 as before.

The buffer pointer locates the proper record which contains the current command angles. Since successive records contain coordinates corresponding to times 1 second apart and since the sampling frequency is 20 times a second, interpolation is necessary. The coordinate increments are calculated by taking the difference between the coordinates at time t and those at time $t + 1$ and dividing by 20. These increments are added to the previous X and Y command angles. New increments are calculated every time the buffer pointer changes.

Besides providing command angles corresponding to predicts, this program has provisions for searching the predict tape for the appropriate records and safeguards against tape mishaps.

When the initial position switch is pressed on the console, the predict tape is rewound and positioned at the first record if the initial predict time is ahead of the station time. Otherwise, it searches for a predict time in coincidence with station time.

4.1.1 Scan

As an aid in acquiring satellites a scan function is provided. It is of the form

$$X = \alpha \gamma \cos \omega \gamma \quad (1)$$

$$Y = \alpha \gamma \sin \omega \gamma \quad (2)$$

where X and Y are the scan offsets in degrees, $\alpha \gamma$ is the effective scan radius and ω is the radial velocity in radians/sec; also

$$\gamma = \gamma (\tau)$$

These are the equations of a spiral. It is desirable that the instantaneous tangential velocity be constant. This velocity is given by

$$v = \sqrt{\dot{X}^2 + \dot{Y}^2} \quad (3)$$

and

$$\dot{X} = \alpha \dot{\gamma} \cos \omega \gamma - \alpha \omega \gamma \dot{\gamma} \sin \omega \gamma \quad (4)$$

$$\dot{Y} = \alpha \dot{\gamma} \sin \omega \gamma + \alpha \omega \gamma \dot{\gamma} \cos \omega \gamma \quad (5)$$

Therefore,

$$\begin{aligned}
 v &= \sqrt{\alpha^2 \dot{\gamma}^2 + \alpha^2 \omega^2 \gamma^2 \dot{\gamma}^2} \\
 &= \sqrt{\alpha^2 \dot{\gamma}^2 (1 + \omega^2 \gamma^2)} \\
 &= \alpha \dot{\gamma} \sqrt{1 + \omega^2 \gamma^2} \quad (6)
 \end{aligned}$$

To simplify matters, we ignore the "1" under the square sign in the last expression and we will explore the consequences of this action later. Thus,

$$v' = \alpha \omega \gamma \dot{\gamma} = \text{constant} = k \quad (7)$$

Explicitly,

$$\gamma \frac{d\gamma}{dt} = \frac{k}{\alpha \omega}$$

and

$$\int \gamma d\gamma = \int \frac{k dt}{\alpha \omega}$$

or

$$\frac{\gamma^2}{2} = \frac{kt}{\alpha\omega} + C$$

Since γ must be zero at $t = 0$ then $C = 0$, therefore,

$$\gamma = \sqrt{\frac{2kt}{\alpha\omega}} \quad (8)$$

The distance along the spiral is given by:

$$\begin{aligned} D &= \int_0^{t_{\max}} v' dt = \int_0^{\gamma_{\max}} \alpha\omega\gamma \dot{\gamma} dt \\ &= \int_0^{\gamma_{\max}} \alpha\omega\gamma d\gamma \\ &= \frac{\alpha\omega\gamma_{\max}^2}{2} \\ &= \frac{\alpha\gamma_{\max} \cdot \omega\gamma_{\max}}{2} \quad (9) \end{aligned}$$

Comparing equation 9 with equations 1 and 2 one concludes that,

$$\alpha \gamma_{\max} = R_{\max} \quad \text{maximum scan radius} \quad (10)$$

and

$$\omega \gamma_{\max} = 5\pi \quad 2 \frac{1}{2} \text{ turns} \quad (11)$$

Consequently

$$D = \frac{5\pi}{2} R_{\max} \quad (12)$$

Since v' is constant then the time necessary to traverse the distance D is simply

$$t_{\max} = \frac{D}{v'} = \frac{D}{k} = \frac{5\pi}{2k} R_{\max} \quad (13)$$

From equation 8 we obtain

$$\gamma_{\max} = \sqrt{\frac{2k}{\alpha\omega} t_{\max}} \quad (14)$$

Since α and ω are defined in terms of $\gamma_{\max}$ (eq. 10 and 11) then one can choose $\gamma_{\max}$ at will. Let

$$\gamma_{\max} = t_{\max} \quad (15)$$

Then it follows that:

$$\gamma_{\max} = \frac{5\pi}{2k} R_{\max} \quad (16)$$

$$\alpha = \frac{R_{\max}}{\gamma_{\max}} \quad (17)$$

$$\omega = \frac{5\pi}{\gamma_{\max}} \quad (18)$$

and from equation 8 we have

$$\gamma = \sqrt{\gamma_{\max} t} \quad (19)$$

We note, at this point, that equations 1 and 2 describe the same spiral regardless of the functional form of γ . The dependence of γ on t determines only the rate of the execution of the spiral. The definitions 16 through 19 were obtained as a result of an approximation to equation 6. To illustrate the consequence of this approximation, we consider a typical case, where $R_{\max} = 1$ deg., $k = 0.5$ deg/sec. The velocity is found to be:

$$v = \frac{1}{32} \left[\frac{16}{t} + 256 \right]^{1/2}$$

The first term in the brackets is proportional to the error. In Figure 5 the velocity is plotted as a function of time. It is found that at $t = 0.1$ secs the velocity is 0.656 and at $t = 0.1$ v is 0.515 and at $t = 3$ secs v is very nearly 0.500. One concludes that this error is tolerable, especially in view of the fact that the error occurs at the "eye" of the spiral.

The scan program reads the scan radius from the antenna console and executes four spirals as shown in Figure 6. If hold-scan is selected the spiral is stopped and the last values held. When scan is selected the scan angles are added to the predicts.

4.1.2 Augmentation

Though predict data is normally quite good, it still contains a prediction error that can be nulled out by using augmentation. This scheme consists of adding the receiver error in an appropriate fashion to the predict data. As implemented, the augmentation scheme consists of a low-pass filter and an integrator. The operation of the filter and integrator will be discussed under Section 5. The characteristics of the filter are shown in Figure 7.

The filter is necessary since the receiver error signal can be excessively noisy. The integrator is used to force a receiver null. The output of the integrator is added to the predict data when augmentation is selected.

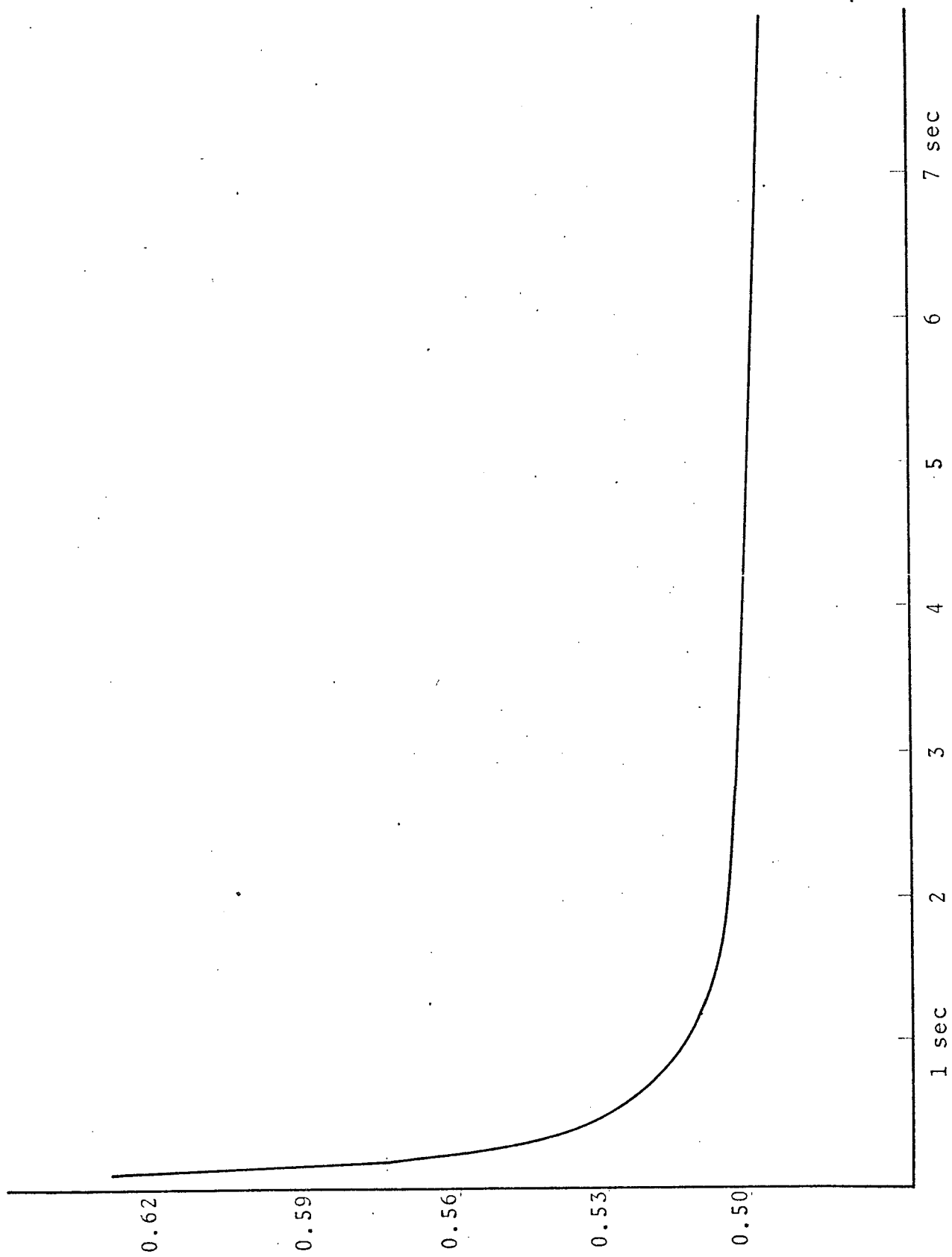


Figure 5. Spiral velocity vs. time

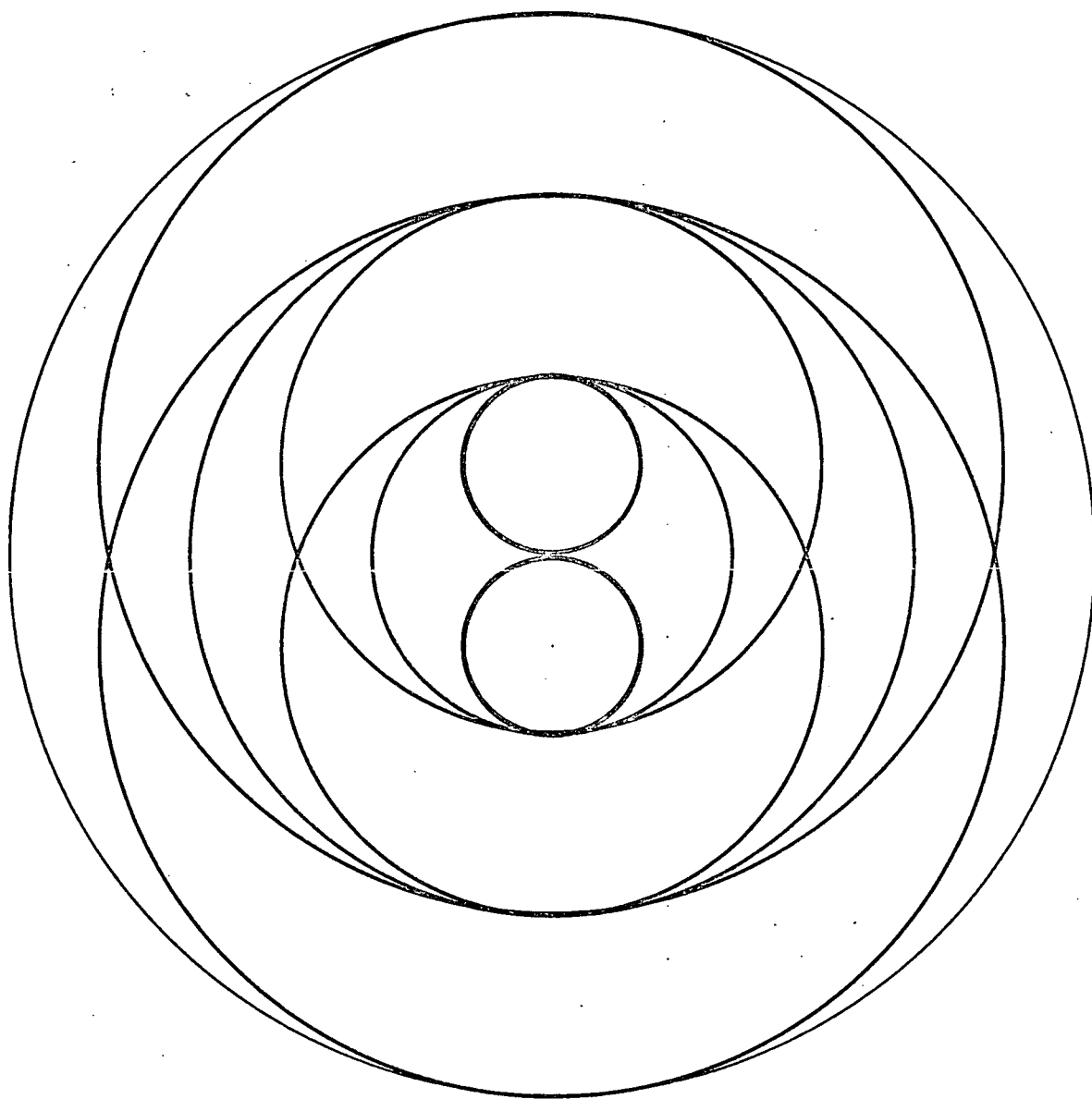


Figure 6. Scan Pattern

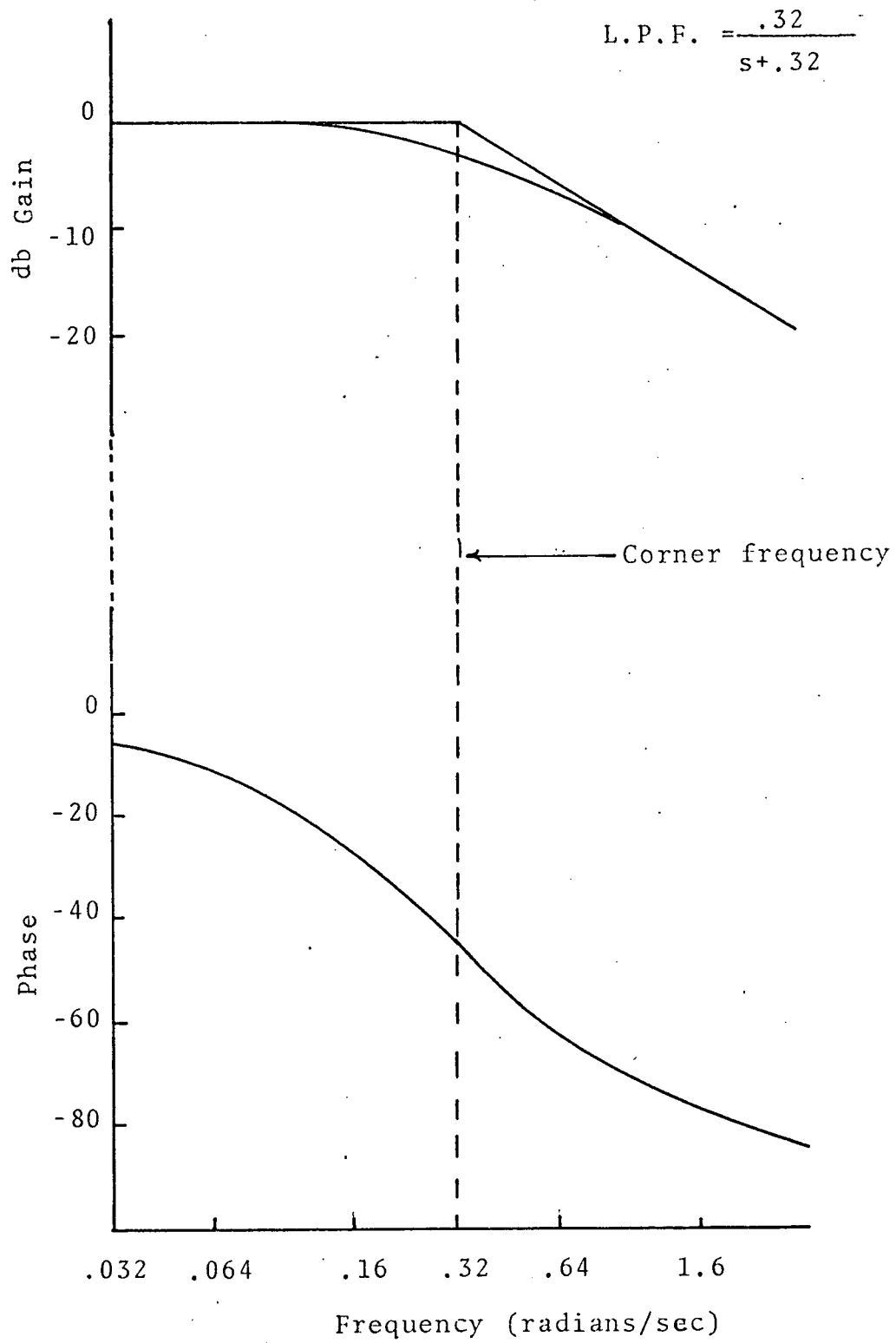


Figure 7. Low Pass Filter Characteristics

4.1.3 Manual Program Mode

In this mode the predicts are set to zero and the command angles are determined by the setting of the X and Y Bias digit switches.

4.2 MANUAL VELOCITY

The output of the joy stick is interpreted as a velocity command and fed to the velocity loop of the digital controller.

4.3 MANUAL POSITION

The output of the joy stick is interpreted as position error and is transmitted to the position loop of the digital controller.

4.4 STOW

Predetermined angles, corresponding to the stow position of the antenna (normally $X = Y = 0$), are fed to the position loop of the digital controller.

4.5 AUTOTRACK

The receiver error is a position error and is inserted into the position loop, which will be discussed in Section 5.

SECTION 5.0

SERVO-AMPLIFIER AND DIGITAL CONTROLLER

Both the servo-amplifier and the digital controller serve the same function, viz., to convert an input error signal into an appropriate drive voltage to the antenna hydraulic system. There are two types of errors: position and velocity errors. They are handled respectively by the by the position and velocity loops of either device. The digital controller is a program for a general purpose computer that performs the functions of the servo-amplifier. The method used to design the digital controller will be discussed later.

5.1 SERVO-AMPLIFIER OPTIONS

Either the analog servo-amplifier or the digital controller may be selected. This is indicated by the setting of the bits 16 and 17 of the discrete status function #1 (Table 1). In the first case, the position error is transmitted to the S/A and, in the other case, a voltage corresponding to the position error is applied by the digital controller to the hydraulic valve system.

5.2 DIGITAL CONTROLLER*

In Figure 9 we present a simplified circuit diagram of the servo-amplifier. It is composed of impedance elements and operational amplifiers. An operational amplifier is best described in terms of its characteristics. It is a d.c. amplifier designed such that:

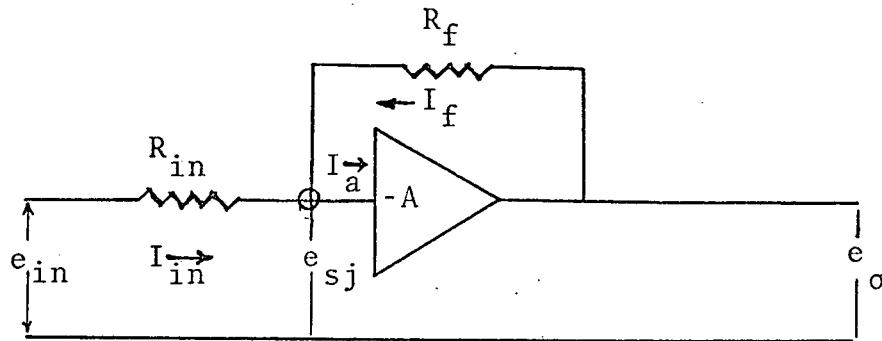


Figure 8. Simplified Amplifier Circuit

- 1) $e_o = -Ae_{sj}$ (within a specified range) (1)
- 2) $I_a \approx 10^{-9}$ amps. - negligible (2)
- 3) $A \approx 10^8$ at d.c. (3)

* The material discussed in this section is treated in greater detail in the books by B.C. Kuo. 1. "Automatic Control Systems." 2. "Analysis and Synthesis of Sampled-Data Control Systems."

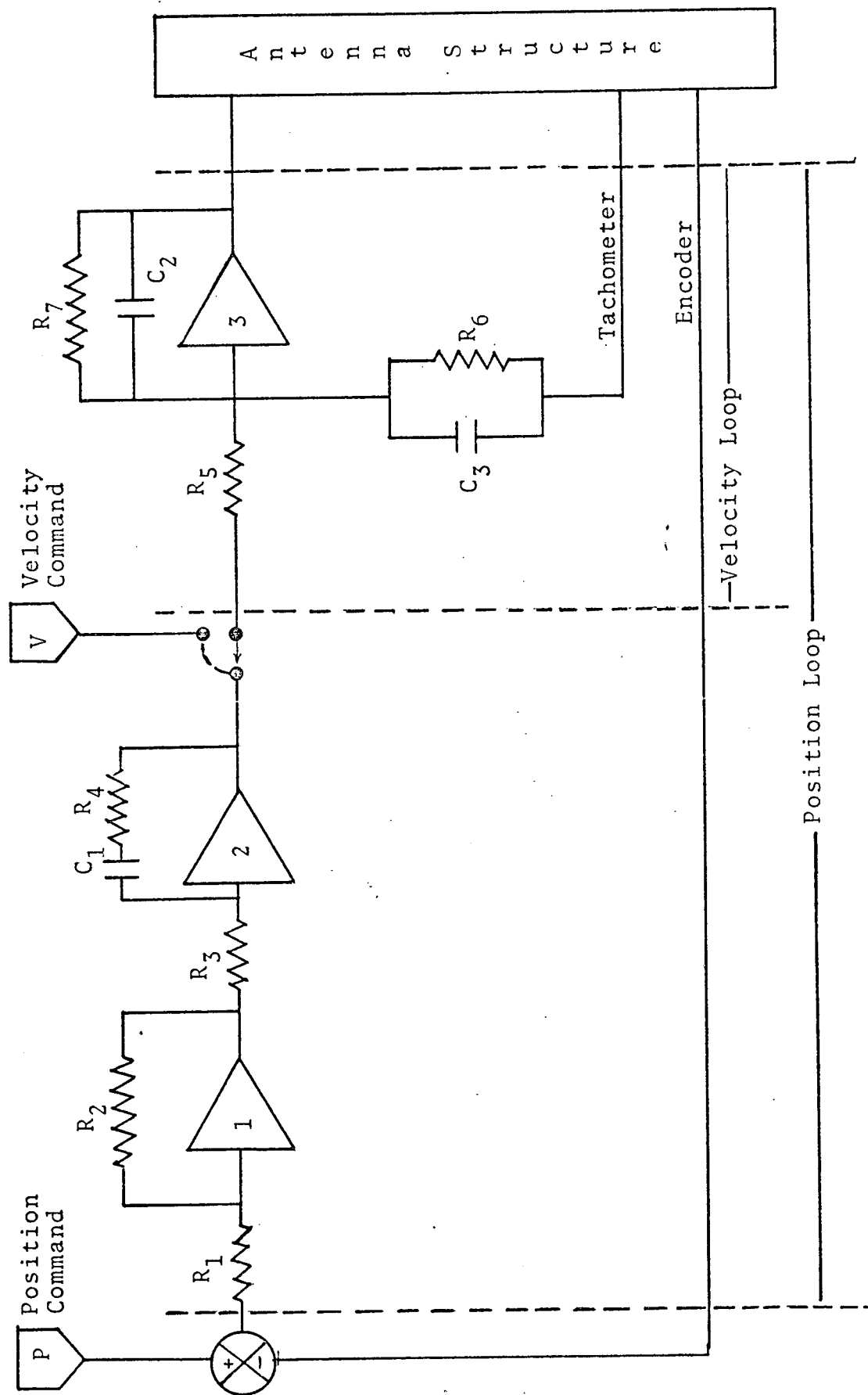


Figure 9. Simplified Diagram of Servo-Amplifier

By Kirchoff's rules, the currents at the summing junction (i.e., Θ) must add up to zero. Therefore,

$$I_a = I_{in} + I_f \approx 0$$

or

$$I_f = -I_{in} \quad (4)$$

and

$$\frac{e_o - e_{sj}}{R_f} = \frac{(e_{in} - e_{sj})}{R_{in}} \quad (5)$$

Solving for e_o we obtain:

$$e_o = \frac{-R_f}{R_{in}} e_{in} ; e_{sj} \approx 0 \quad (6)$$

We have neglected $e_{sj} \approx -10^{-9} e_o$. Thus, for an operational amplifier, the only important parameters are the input and output resistances. It can be shown that, in general,

$$e_o = \frac{-Z_f}{Z_{in}} e_{in} \quad (7)$$

Where Z_f and Z_{in} are the feedback and input impedences. In addition, for multiple inputs we have

$$e_o = -Z_f \sum_k \frac{e_{in}^{(k)}}{Z_{in}^{(k)}} \quad (8)$$

Laplace transform theory simplifies the analysis of physical systems. We will be concerned here with only two theorems, viz.:

$$(1) \quad L [Kf(t)] = KL[f(t)] = KF(s) \quad (9)$$

$$(2) \quad L \left[\int_0^t f(\tau) d\tau \right] = \frac{F(s)}{s} \quad (10)$$

The Laplace transform is a linear operator, i.e.

$$L[f(t) + g(t)] = F(s) + G(s) \quad (11)$$

Returning to the discussion of the operational amplifier we note that the results 6, 7 and 8 imply the following equivalent circuit:

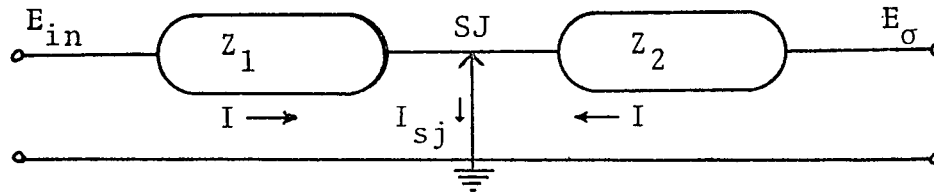


Figure 10. Equivalent Circuit *

The summing junction (SJ) is a virtual ground. This circuit is described by the relations

$$\begin{aligned} I_{sj} &= 0 \\ E_{in} &= IZ_1 \end{aligned} \tag{12}$$

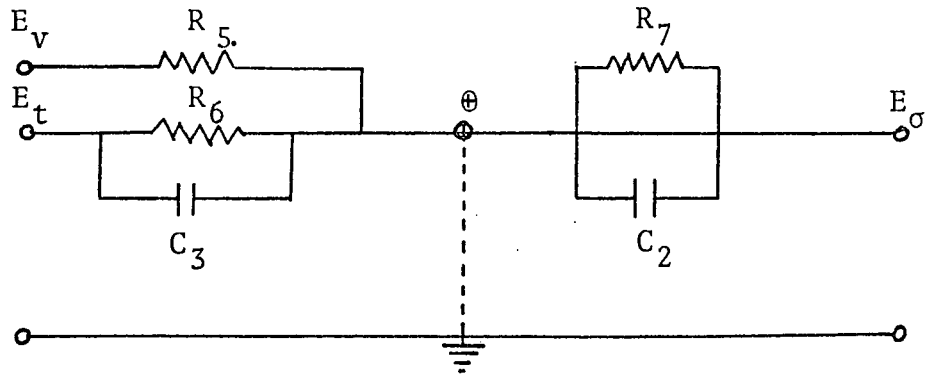
$$E_o = -IZ_2 \tag{13}$$

The transfer function for this circuit is given by:

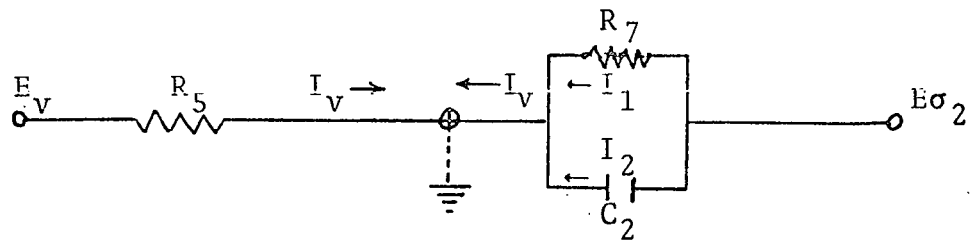
$$T(s) = \frac{E_o(s)}{E_{in}(s)} \tag{14}$$

* Millman, "Vacuum and Semiconductor Electronics," p. 466, McGraw-Hill Book Co., N.Y., 1958.

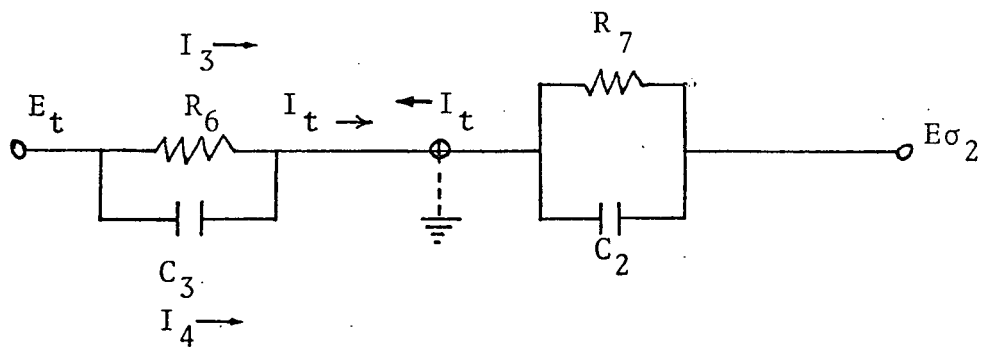
To illustrate how $T(s)$ is calculated we consider the velocity loop in Figure 8. The equivalent circuit is:



which can be divided into two separate circuits:



and



where $E_o = E_{o_1} + E_{o_2}$. The transform of E_v is simply:

$$E_v(s) = I_v(s) R_5 \quad (15)$$

For E_T we have

$$E_T = I_3 R_6 \quad (16)$$

$$= \frac{1}{C_3} \int_0^{\tau} I_4 dt \quad (17)$$

and

$$E_T(s) = I_3(s) R_6 \quad (18)$$

$$= \frac{I_4(s)}{C_3 s} \quad (19)$$

from which we conclude that:

$$I_4(s) = I_3(s) R_6 C_3 s \quad (20)$$

and

$$I_T(s) = I_3 (1 + R_6 C_3 s) \quad (21)$$

Since

$$E_T(s) = I_T(s) Z_T(s) \quad (22)$$

we must have using 16,

$$\begin{aligned} Z_T(s) &= \frac{I_3 R_6}{I_3 (1 + R_6 C_3 s)} \\ &= \frac{R_6}{1 + R_6 C_3 s} \end{aligned} \quad (23)$$

Similarly

$$E_{o1}(s) = -I_v(s) Z_{o1}(s) \quad (24)$$

where

$$Z_{o_1}(s) = \frac{R_7}{1 + R_7 C_2 s} \quad (25)$$

and

$$E_{o_2}(s) = -I_T(s) Z_{o_2}(s) \quad (26)$$

with

$$Z_{o_2}(s) = \frac{R_7}{1 + R_7 C_2 s} \quad (27)$$

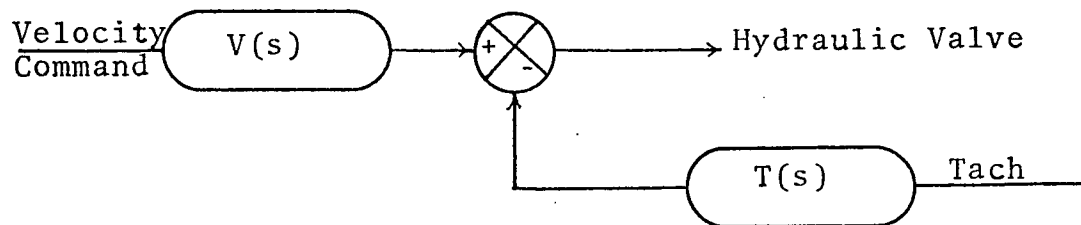
We define two transfer functions, viz.;

$$V(s) = \frac{E_{o_1}(s)}{E_V(s)} + \frac{R_7/R_5}{1 + R_7 C_2 s} \quad (28)$$

and

$$T(s) = \frac{E_{o_2}(s)}{E_T(s)} = -\frac{R_7}{R_6} \frac{1 + R_6 C_3 s}{1 + R_7 C_2 s} \quad (29)$$

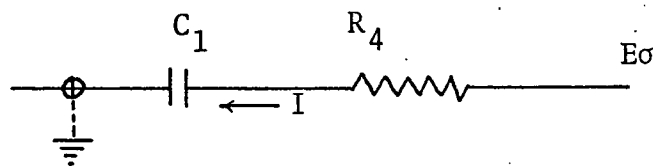
The velocity loop is then given by:



Amplifier #1 in Figure 8 is hooked up as a simple d.c. amplifier. Its transfer function is obtained directly from 6, i.e.:

$$G(s) = \frac{e_{in}}{e_o} = - \frac{R_2}{R_1} \quad (30)$$

Amplifier #2 is connected as a combination amplifier-integrator and the impedance of the feedback network is obtained as follows:



$$E_o = -I R_4 - \frac{1}{C_1} \int_0^T T dt$$

or

$$E_o(s) = -I(s) R_4 - \frac{I(s)}{C_1 s}$$

On the other hand:

$$E_{in}(s) = I(s) R_3$$

The transfer function of the integrator-amplifier is then:

$$\begin{aligned} IA(s) &= \frac{E_o(s)}{E_{in}(s)} = - \frac{R_4}{R_3} - \frac{1}{R_3 C_1 s} \\ &= - \frac{(R_4 C_1 s + 1)}{R_3 C_1 s} \end{aligned} \tag{31}$$

The s-transform equivalent of the servo-amplifier in Figure 9 is shown in Figure 11.

Since the servo-amplifier is to be duplicated on a digital computer, we will examine the nature of continuous and discrete data.

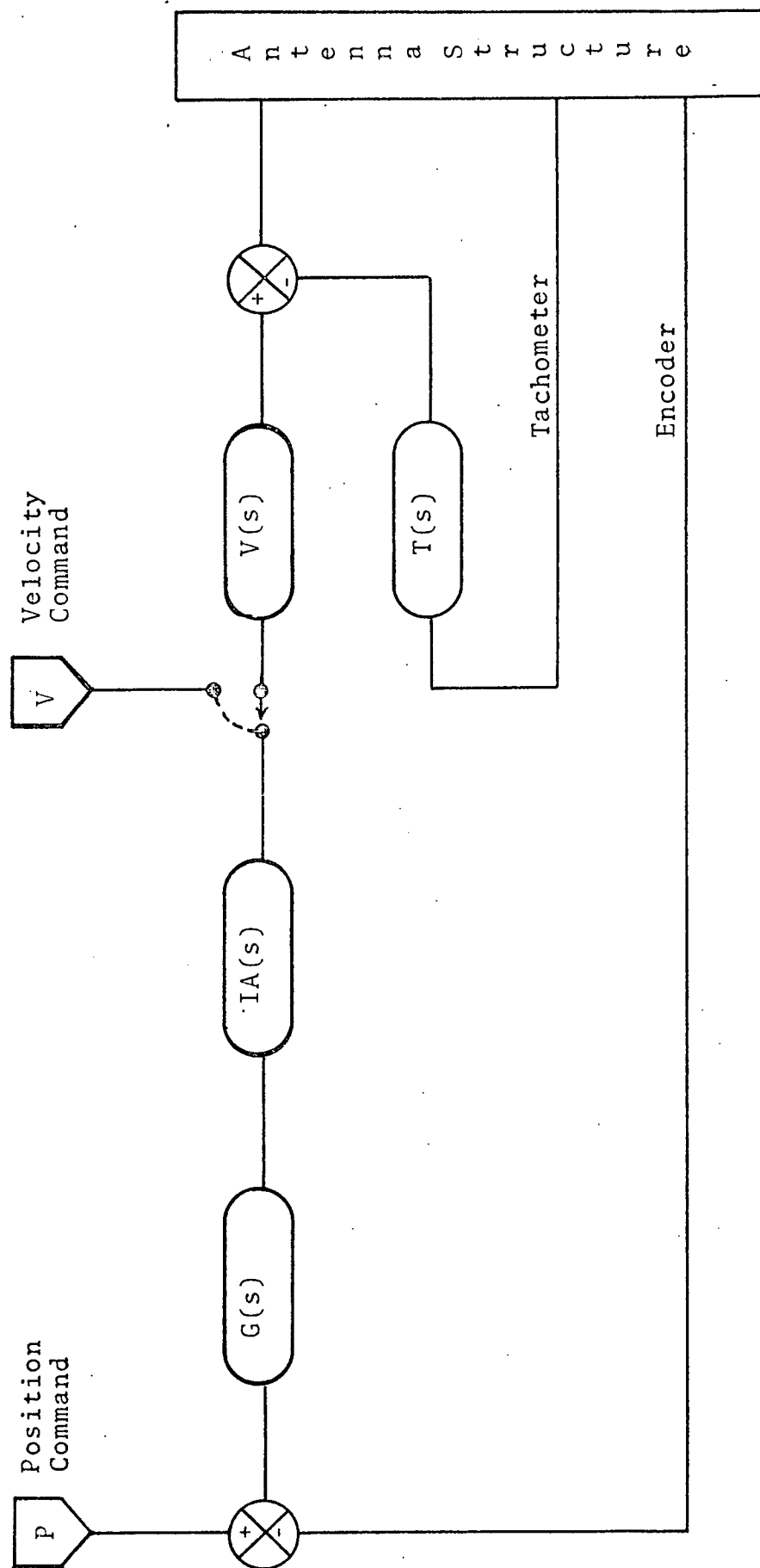
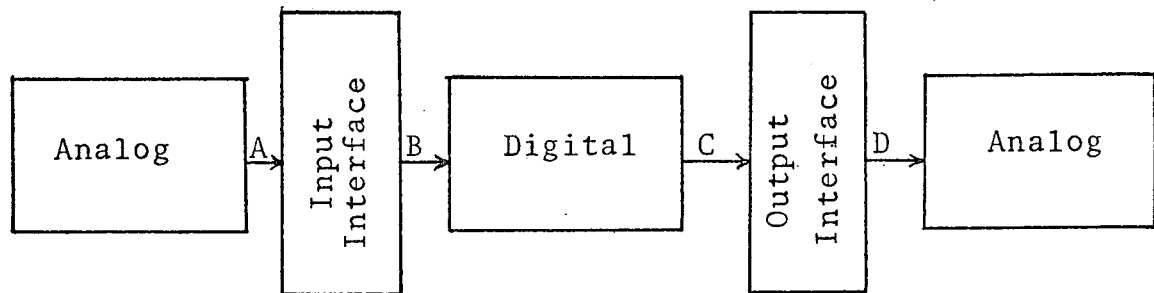


Figure 11. Servo-Amplifier (S-Form)

In a hybrid device the analog and digital components are connected together via an interface.



On input, the digital device will sample the interface at prescribed intervals separated by a period T . On output, the interface holds the last value until it is altered at the following interval. This is illustrated in Figure 12, where an analog signal is shown as it appears at the point A, followed by the digital input at the sampling moments nT . For the sake of simplicity the digital device merely transmits these values to the output interface at C. Finally, the resultant analog signal is shown as it appears at D. It is immediately obvious that a high sampling frequency is desirable to maintain the integrity of the signal.

In any case, we need a mathematical device to make the transition from A to D in Figure 12. This is the Z-transform. If the analog signal at A is described by the function $e(t)$ then the digital signal at B is given by

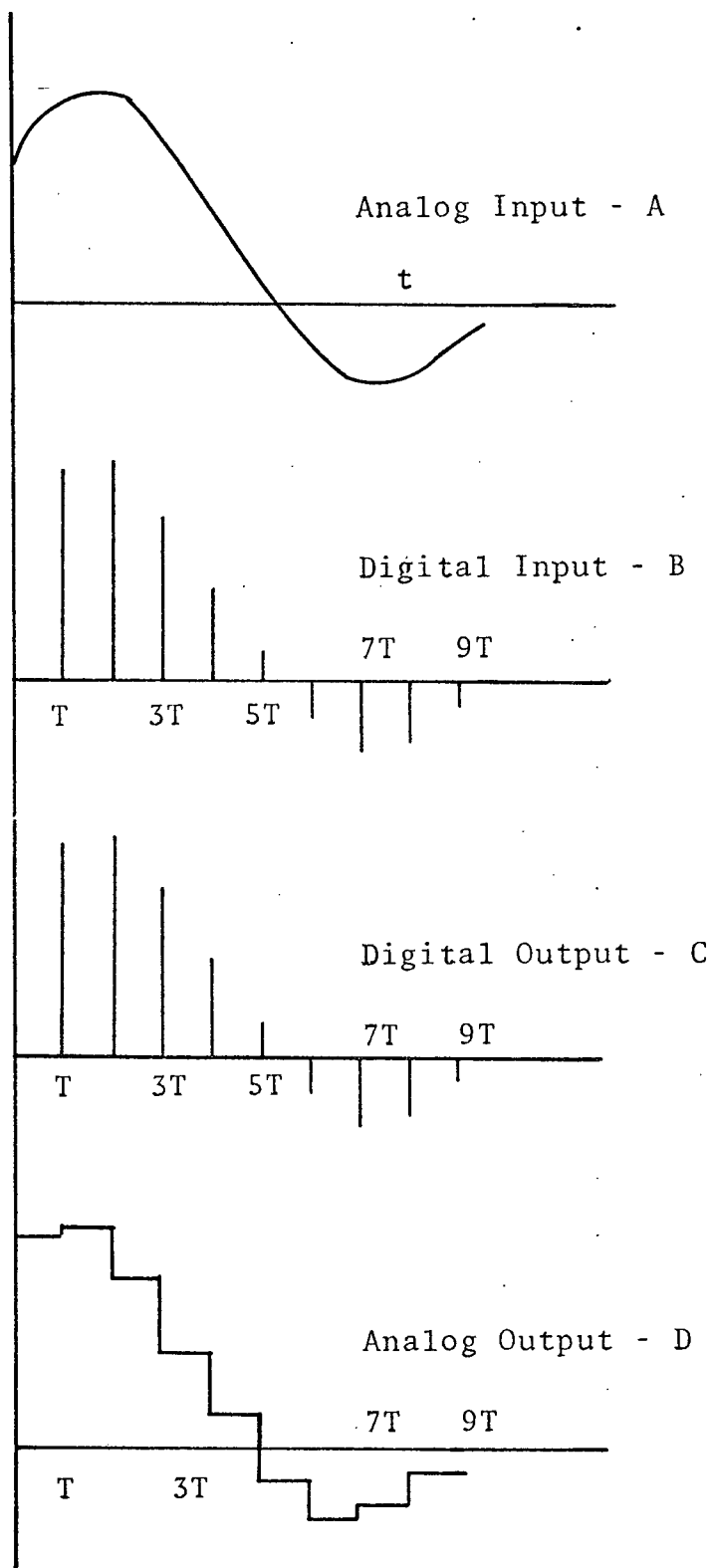


Figure 12. Digital Reconstruction of Analog Signal

$$e^*(t) = \sum_0^{\infty} e(t) \delta(t - nT) \quad (32)$$

where $\delta(x)$ is the Dirac delta function. Equation 32 can be simplified to read:

$$e^*(t) = \sum_0^{\infty} e(nT) \delta(t - nT) \quad (33)$$

The Laplace transform of the above is then:

$$E^*(s) = \sum_0^{\infty} e(nT) L[\delta(t - nT)] \quad (34)$$

$$= \sum_0^{\infty} e(nT) E^{-nTs}$$

If we define

$$z = e^{Ts} \quad (35)$$

then

$$E^*(s) = E(z) = \sum_0^{\infty} e(nT) z^{-n} \quad (36)$$

This is called the Z-transform of $e(t)$, which is in contrast to the Laplace transform

$$E(s) = \int_0^{\infty} e(t) e^{-st} dt \quad (37)$$

In general, it can be said that any time function that possesses a Laplace transform will also have a z-transform. It is important to note that the inverse z-transform is not unique, i.e., there exists a class of time functions $e(t)$ that have the same z-transform. This follows from the fact that the z-transform is computed according to the behavior of $e(t)$ at the sampling instants only. As an example, we show in Figure 13 two time functions

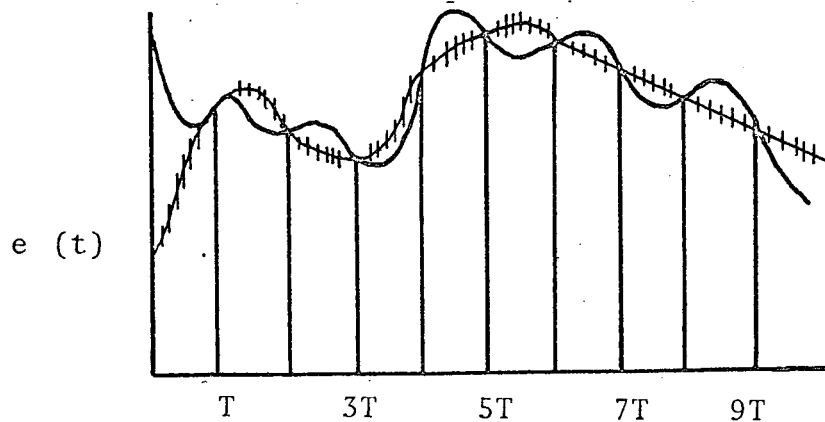


Figure 13. Non-Uniqueness of Z Transform

that have the same digital form; in other words, the value of the two functions coincide at the sampling instants.

One does not compute the z-transforms, usually, since z-transform tables are available. A digital circuit, whose z-transforms are obtained in this manner, does not necessarily have the same frequency response as the equivalent analog circuit. We, therefore, choose another method that ensures a closer correspondence between the frequency response of the digital and that of the analog system. It may be called the equal corner frequency approach.

It was shown earlier that, $z = e^{Ts}$ (eq. 35). Since the frequency response of an analog system is obtained by setting $s = i\omega$ we then have

$$z = e^{i\omega T} \quad (38)$$

Define the transformation

$$\omega = \frac{z-1}{z+1} \quad (39)$$

Then

$$\omega = \frac{e^{i\omega T} - 1}{e^{i\omega T} + 1} \quad (40)$$

Multiply both denominator and numerator by $e^{-i\omega T/2}$, thus:

$$\begin{aligned} \omega &= \frac{e^{i\omega T/2} - e^{-i\omega T/2}}{e^{i\omega T/2} + e^{-i\omega T/2}} \\ &= i \tan (\omega T/2) \end{aligned} \quad (41)$$

To analyze the response of the digital system in ω -space we set $\omega = i \gamma$ then:

$$\omega = i \gamma = i \tan \left(\frac{\omega T}{2} \right)$$

or

$$\gamma = \tan \left(\frac{\omega T}{2} \right) \quad (42)$$

The digital corner frequency γ is related to the analog corner frequency by equation 42. All of the transfer functions encountered in the analysis of the servo-amplifier can be reduced to the form $\frac{1}{s+\omega}$. To obtain the z-transfer function we calculate γ from the relation 42, substitute ω for S and finally use the relation 39, i.e.,

$$\frac{1}{S+\omega} \rightarrow \frac{1}{\omega+\gamma} = \frac{1}{\frac{z-1}{z+1} + \gamma}$$

or

$$T(z) = \frac{z+1}{(1+\gamma)z - (1-\gamma)} \quad (43)$$

As an example consider the filter used in the augmentation program, viz.:

$$\frac{.32}{s+.32} \rightarrow \frac{.32}{\omega+.008}$$

or

$$A(z) = \frac{.32(z+1)}{1.008 z - .992} \quad (44)$$

$$A(z) = \frac{.317(z+1)}{z - .984}$$

The final value theorem for Laplace transforms states that the final value is given by:

$$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} s F(s) \quad (45)$$

A transfer function is the ratio of two transforms, for example,

$$G(s) = \frac{A(s)}{B(s)}$$

and the final value of "d.c. gain" will be

$$\begin{aligned} [G(s)] \text{ final value} &= \lim_{s \rightarrow 0} s A(s) / \lim_{s \rightarrow 0} s B(s) \\ &= \lim_{s \rightarrow 0} \frac{A(s)}{B(s)} \end{aligned}$$

or

$$\text{d.c. gain} = \lim_{s \rightarrow 0} G(s) \quad (46)$$

Since $z = e^{Ts}$ then at $s = 0$, $z = 1$. Therefore

$$\text{d.c. gain} = \lim_{z \rightarrow 1} G(z) \quad (47)$$

Similarly

$$\text{d.c. gain} = \lim_{\omega \rightarrow 0} G(\omega) \quad (48)$$

A special case is the integrator, whose Laplace transform is $1/s$. Using equation 46 one finds that its gain is infinite. For a unit step input, the output of the integrator is a ramp with a slope of 1 (Figure 14).

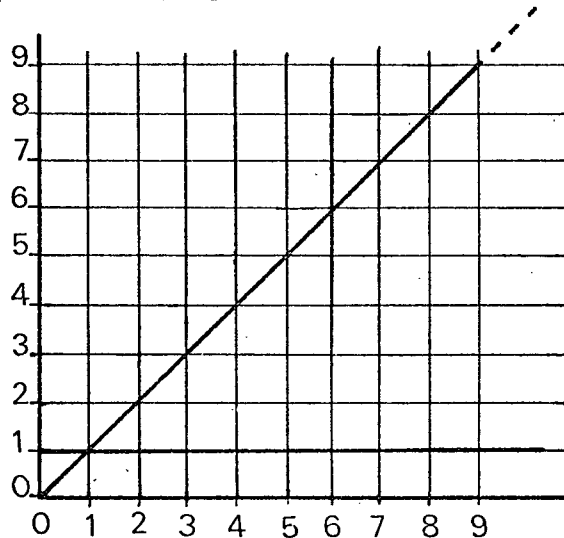


Figure 14. Integrator

Having obtained the z-transfer functions we are left with the task of implementing them on a digital computer. A physically realizable transfer function $D(z)$, i.e., one which can be realized by RC elements, may be expressed in the form

$$D(z) = \frac{E_2(z)}{E_1(z)} = \frac{A_0 + A_1 z^{-1} + \dots + A_m z^{-n}}{b_0 + b_1 z^{-1} + \dots + b_m z^{-m}} \quad (49)$$

where $b_0 \neq 0$ and m and n are positive integers. An alternate form is:

$$D(z) = \frac{A_0 \prod_{k=1}^m (1 + c_k z^{-1})}{b_0 \prod_{k=1}^m (1 + d_k z^{-1})} \quad (50)$$

This represents the product of n transfer functions as shown in Figure 15(b). The output of the one is the input of the next. Thus, it is only necessary to program $D_k(z)$, which is given by:

$$D_k(z) = \frac{E_{2k}(z)}{E_{1k}(z)} = \frac{1 + c_k z^{-1}}{1 + d_k z^{-1}} \quad (51)$$

Before we proceed to program $D_k(z)$, let us examine the z-transfer function of a delayed time function. From equation 32 we write:

$$e^*(t-kT) = \sum_{n=0}^{\infty} e(t-kT) \delta(t-nT) \quad (52)$$

where k is a positive integer. This can be simplified to read:

$$e^*(t-kT) = \sum_{n=0}^{\infty} e(nT-kT) \delta(t-nT) \quad (53)$$

Taking the Laplace transform we obtain:

$$L[e^*(t-kT)] = \sum_{n=0}^{\infty} e(nT-kT) e^{-nTs} \quad (54)$$

$$= \sum_{n=0}^{\infty} e(nT-kT) z^{-n} \quad (55)$$

$$= z^{-k} \sum_{n=0}^{\infty} e(nT-kT) z^{-(n-k)} \quad (56)$$

Since $e(t)$ is zero for $T < 0$ then

$$L[e^*(t-kT)] = z^{-k} \sum_{n=k}^{\infty} e(nT-kT) z^{-(n-k)} \quad (57)$$

Define a new integer variable $m = n-k$, then:

$$L[e^*(t-kT)] = z^{-k} \sum_{m=0}^{\infty} e(mT) z^{-m} \quad (58)$$

On comparison with equation 36 we conclude that

$$L[e^*(t-kT)] = z^{-k} E(z) \quad (59)$$

Returning to our main problem we cross-multiply in equation 51 to obtain:

$$E_{2k}(z) + d_k z^{-1} E_{2k}(z) = E_{1k}(z) + C_k z^{-1} E_{1k}(z) \quad (60)$$

which may be written; if we take equation 59 into account:

$$L[e_{2k}^*(t) + d_k e_{2k}^*(t-T)] = L[e_{1k}^*(t) + C_k e_{1k}^*(t-T)] \quad (61)$$

Upon taking the inverse transform of the above we have,

$$e_{2k}^*(t) + d_k e_{2k}^*(t-T) = e_{1k}^*(t) + C_k e_{1k}^*(t-T) \quad (62)$$

Setting $t = nT$ we write:

$$e_{2k}^*(nT) + d_k e_{2k}^*[(n-1)T] = e_{1k}^*(nT) + C_k e_{1k}^*[(n-1)T] \quad (63)$$

Define $IN_k = e_{1k}^*$ and $OUT_k = e_{2k}^*$ we then have:

$$OUT_k(n) = IN_k(n) + C_k IN_k(n-1) - d_k OUT_k(n-1) \quad (64)$$

This result is illustrated in Figure 15(d).

The last item to be discussed is the sampling frequency, $1/T$. As can be seen from Figure 12, the signal wave form input to a digital device can be reconstructed more faithfully at higher sampling frequencies. However, there is an upper bound due to the finite speed of computers and due to the number of operations to be performed in addition to sampling. A lower bound is placed on this frequency since there obviously exists a minimum below which signal reconstruction is virtually impossible. This minimum is determined according to the sampling theorem (see footnote at beginning of this section), which states

that if a signal contains no frequency higher than ω_e radians per second, it is completely characterized by the values of the signal measured at instants of time separated by $T = 1/2 \left(\frac{2\pi}{\omega_e} \right)$ seconds.

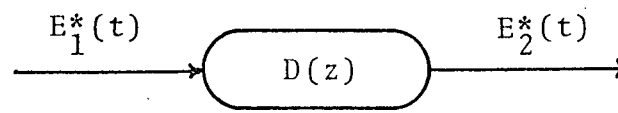
In order to determine the minimum sampling frequency we must examine the time constants and natural frequencies of the 40-ft antenna.

It can be shown that a transfer function may be written in the form:

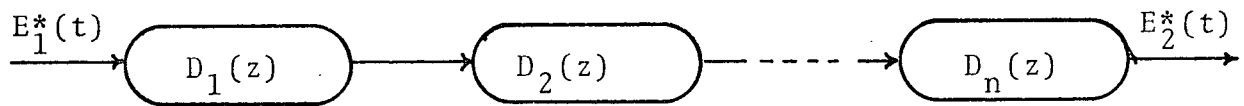
$$\frac{OUT(s)}{I_N(s)} = A(s) = \frac{K \prod_{j=1}^m (s + \gamma_j)}{\frac{k}{s} \prod_{i=1}^l (s + \sigma_i) \prod_{\rho=1}^{\ell} (s^2 + 2\alpha_{\rho} s + \omega_{n\rho}^2)} \quad (65)$$

Let us examine the response of this system to a unit step input, whose transform is $\frac{1}{s}$. Then,

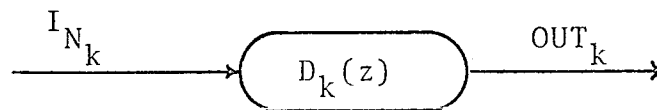
$$OUT(s) = \frac{K \prod_{j=1}^m (s + \gamma_j)}{\frac{k}{s} \prod_{i=1}^l (s + \sigma_i) \prod_{\rho=1}^{\ell} (s^2 + 2\alpha_{\rho} s + \omega_{n\rho}^2)} \quad (66)$$



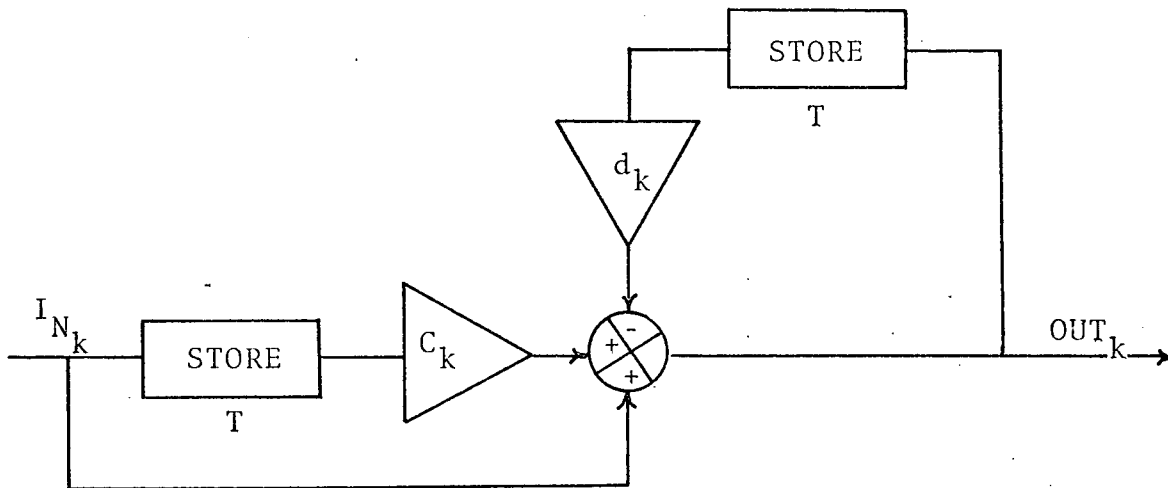
(a)



(b)



(c)



(d)

Figure 15. Cascade Programming for Z-transfer Function

Expanding by partial fractions one obtains:

$$\text{OUT}(s) = \frac{A}{S} + \sum_{i=1}^k \frac{B_i}{S + \sigma_i} + \sum_{\rho=1}^{\ell} \frac{C_{\rho} S + D_{\rho}}{S^2 + 2\alpha_{\rho} S + \omega_{n\rho}^2} \quad (67)$$

The inverse transform yields:

$$\text{OUT}(t) = A u(t) + \sum_{i=1}^k B_i e^{-\sigma_i t} + \sum_{\rho=1}^{\ell} D_{\rho} E_{\rho} e^{-\alpha_{\rho} t} \sin \left(\sqrt{\omega_{n\rho}^2 - \alpha_{\rho}^2} t - \phi \right) \quad (68)$$

where A , B_i , D_{ρ} , and E_{ρ} are constants depending on the poles and zeroes of $A(s)$. The function $u(t)$ is the Heaviside unit step.

The first term in (68) is the response to the step function. If the σ 's and α 's are all positive real numbers, then the exponential terms will decay to zero as time increases. Thus, the first term is the steady-state response and the others represent the transient response. The quantities $\frac{1}{\sigma_i}$ are the time constants of the system and $\omega_{n\rho}$ are the natural frequencies. In Figure 16 transient response to a unit step is shown.

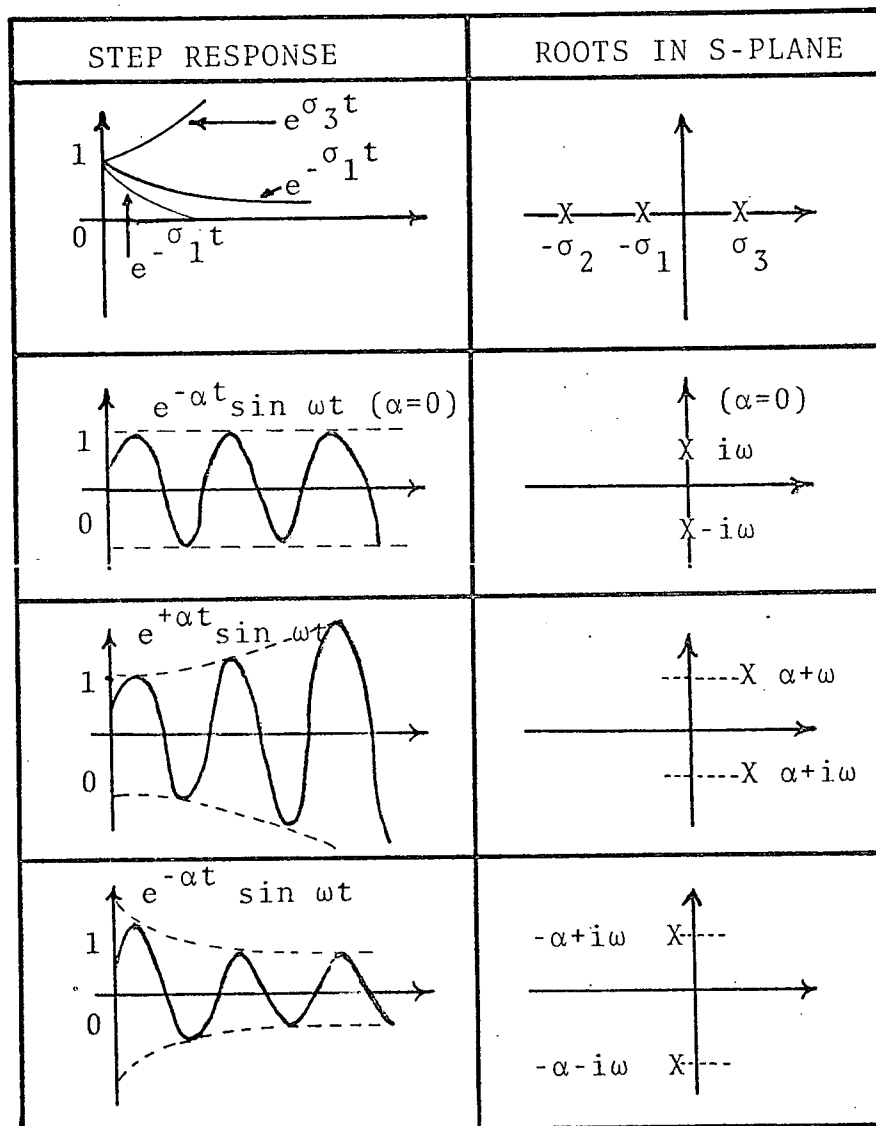


Figure 16. Response for Various Root Locations
In the S-Plane

The design for the NTTF 40 ft. antenna lists the following approximation to the antenna system transfer function:

$$A(s) = \frac{1.6 \times 10^{-4} s^2 + 1}{(0.0875 s + 1) (6.69 \times 10^{-4} s^2 + 9.6 \times 10^{-3} s + 1)} \quad (69)$$

$$= \frac{2.74 (s^2 + 6250)}{(s + 11.42) (s^2 + 14.37 s + 1500)} \quad (70)$$

Comparison with equation 66 yields the following results:

$$\sigma = 11.42 \quad (71)$$

and

$$T_{\sigma} = \frac{1}{11.42} = 0.0875 \text{ sec.} \quad (72)$$

also

$$\omega_n^2 = 1500$$

or

$$\omega_n = 38.7 \text{ rad/sec.} \quad (73)$$

The roots of the quadratic in equation 66 are:

$$\begin{aligned} s &= -\alpha \pm i \sqrt{\omega_n^2 - \alpha^2} \\ &= -\alpha \pm i \omega \end{aligned}$$

Therefore

$$\begin{aligned} \omega &= \sqrt{1500 - \left(\frac{14.37}{2}\right)^2} \\ &= 37.9 \text{ rad/sec} \end{aligned} \quad (74)$$

This is the actual frequency of oscillation; the period of oscillation is given by

$$\tau = \frac{2\pi}{37.9} = 0.166 \text{ sec} \quad (75)$$

The time constant governing the decay of the transient oscillation is

$$T_{\alpha} = \frac{1}{\alpha} = \frac{1}{14.37/2}$$

or

$$T_{\alpha} = \frac{1}{7.18} = 0.138 \text{ sec} \quad (76)$$

The smallest time constant is given by

$$\min(T_{\sigma}, T_{\alpha}, \tau) = 0.0875 \text{ sec.} \quad (77)$$

and the corresponding frequency is 11.42. Then by the sampling theorem the sampling frequency should be at least 23 cps. We have chosen 20 cps and it seems to be practical enough.

5.3 DIGITAL CONTROLLER PROGRAMS

There are two programs that handle the digital controller functions. The first manages position errors, while the other handles velocity inputs. In the position modes there are two types of operation. Type I operation concerns large position errors. In this case the integrator (IA) in Figure 11 is replaced by a gain factor (equivalent to a d.c. amplifier). In Type II operation, which is used for small

errors, the integrator is used to force a servo null. Indicators on the antenna console are activated to reflect the type of operation. The output of this program is a velocity signal, which is used by the second program. This program accepts either a velocity command from the joy stick on the antenna console or the output of the previous program. The output is a voltage that is applied to the hydraulic valve.

SECTION 6.0

UTILITY PROGRAMS

These programs perform subsidiary functions such as decoding data from the antenna interface or calculating real-time. They are divided into three categories: prepass, pass and postpass.

6.1 PREPASS PROGRAMS

These routines are not part of the real-time program. They are executed before a pass. The two programs in this series provide a listing of the passes contained on the NASA provided ENV predict tape and produce XY predict tapes for use with the real-time program.

6.1.1 Predict Listing

The data on the NASA tape is scanned and a listing is produced, which identifies the data by satellite identification number, orbit number, date and pass duration.

6.1.2 ENV to XY Conversion

Data on the NASA tape is in the form of ENV coordinates. Since the NTTF 40-ft antenna is of the XY variety, the data must be converted. The relationship between ENV and XY coordinates is illustrated in the figure below:

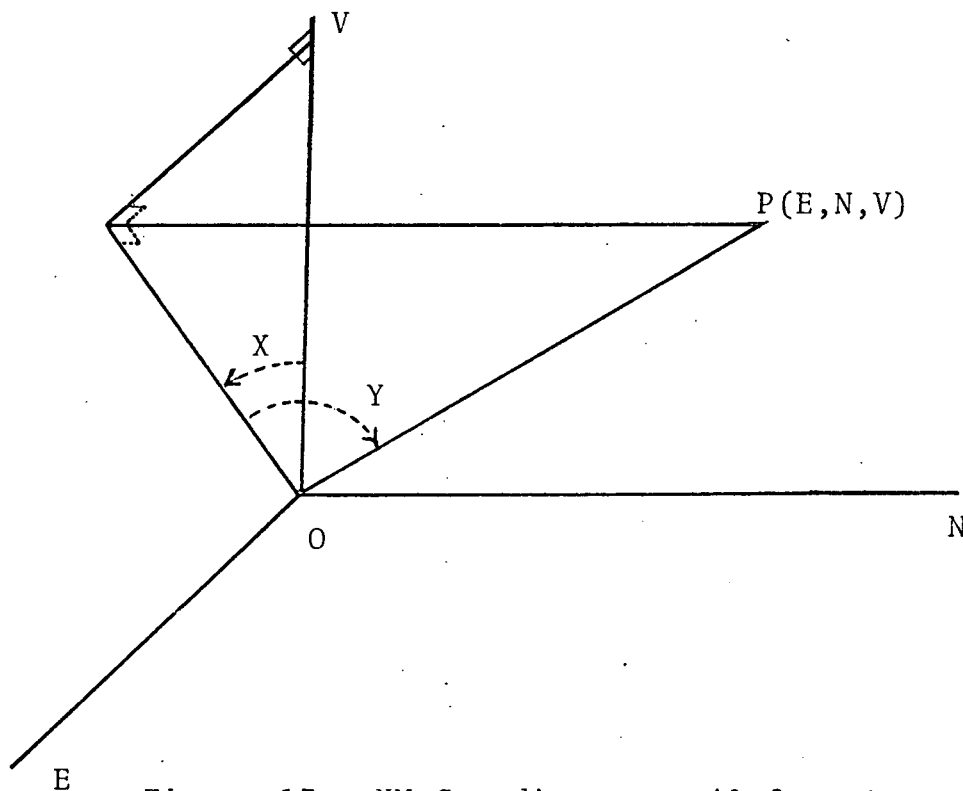


Figure 17. XY Coordinates - 40-foot Antenna

The ENV coordinates are referred to the origin 0, which is the location of the NTTF 40-ft antenna. The relationships between the two sets of coordinates are found, by inspection, to be:

$$X = \arctan \left[\frac{E}{V} \right] \quad (1)$$

and

$$Y = \arctan \left[\frac{N}{\sqrt{E^2 + V^2}} \right] \quad (2)$$

The ENV coordinates are provided at intervals of one minute or more. Since the real-time program needs new coordinates every 1/20 second, it was decided to interpolate, in the ENV to XY program, to provide predicts every second. Then in the real-time program a linear interpolation scheme is used to obtain coordinates at the required frequency.

The method used in this program is a polynomial interpolation method. We assume that

$$f(t_0 + ph) = f(t_0) + a(ph) + b(ph)^2 + c(ph)^3 + d(ph)^4 \quad (3)$$

where h is the time interval between points (usually 1 minute) and p is any number such that

$$-2 \leq p \leq 2 \quad (4)$$

For any five data points we can write

$$f(t_0 - 2h) = f(t_0) - 2ah + 4bh^2 - 8ch^3 + 16dh^4 \quad (5)$$

$$f(t_0 - h) = f(t_0) - ah + bh^2 - ch^3 + dh^4 \quad (6)$$

$$f(t_0) = f(t_0) \quad (7)$$

$$f(t_0 + h) = f(t_0) + ah + bh^2 + ch^3 + dh^4 \quad (8)$$

$$f(t_0 + 2h) = f(t_0) + 2ah^2 + 4bh^2 + 8ch^3 + 16dh^4 \quad (9)$$

The first differences are then given by:

$$\Delta_1 = f(t_0 - h) - f(t_0 - 2h) = ah - 3bh^2 + 7ch^3 - 15dh^4 \quad (10)$$

$$\Delta_2 = f(t_0) - f(t_0 - h) = ah - bh^2 + ch^3 - dh^4 \quad (11)$$

$$\Delta_3 = f(t_0 + h) - f(t_0) = ah + bh^2 + ch^3 + dh^4 \quad (12)$$

$$\Delta_4 = f(t_0 + 2h) - f(t_0 + h) = ah + 3bh^2 + 7ch^3 + 15dh^4 \quad (13)$$

It follows that:

$$\Delta_1 + \Delta_4 = 2ah + 14ch^3 \quad (14)$$

$$\Delta_2 + \Delta_3 = 2ah + 2ch^3 \quad (15)$$

$$\Delta_3 - \Delta_2 = 2bh^2 + 2dh^4 \quad (16)$$

$$\Delta_4 - \Delta_1 = 6bh^2 + 30dh^4 \quad (17)$$

Solving for a, b, c and d we obtain:

$$a = \frac{\Delta_2 + \Delta_3 - 2ch^3}{2h} \quad (18)$$

$$b = \frac{\Delta_3 - \Delta_2 - 2dh^4}{2h^2} \quad (19)$$

$$c = \frac{\Delta_1 + \Delta_4 - \Delta_2 - \Delta_3}{12h^3} \quad (20)$$

$$d = \frac{\Delta_4 - \Delta_1 - 3\Delta_3 + 3\Delta_2}{24h^4} \quad (21)$$

Using the values of the coefficients from above one can calculate the value of the function for any time in the interval $(t_0 - 2h) \leq t \leq (t_0 + 2h)$ from equation 3.

In addition, range, range rate and (X,Y) velocities are calculated from the following relations:

$$R = (E^2 + N^2 + V^2)^{1/2} \quad (22)$$

$$\dot{R} = \frac{R(t+\Delta t) - R(t)}{\Delta t} \quad (23)$$

$$\dot{X} = \frac{X(t+\Delta t) - X(t)}{\Delta t} \quad (24)$$

and

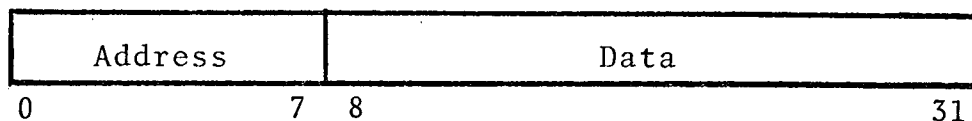
$$\dot{Y} = \frac{Y(t+\Delta t) - Y(t)}{\Delta t} \quad (25)$$

6.2 PASS PROGRAMS

These routines are part of the real-time program and perform secondary functions. A complete list with individual descriptions follows.

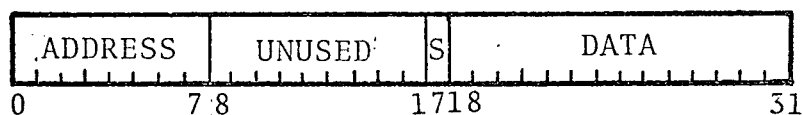
6.2.1 Interface I/O Program

Communication between the real-time program and the antenna is performed via the interface. This is performed by transmitting one or more 32 bit words to the interface in the form:



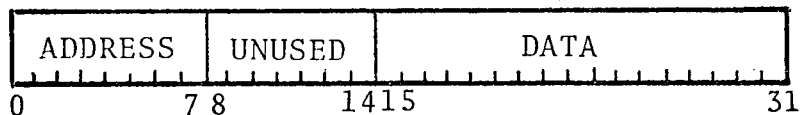
If bit "0" is set (i.e., "1") the address corresponds to an input, in which case the data bits are set to reflect the current status of that input. If bit "0" is reset, the address is interpreted as output. The data is transmitted to the antenna console. It is either discrete or analog. Discrete data is used, for example, to reflect the status of the real-time program and antenna or to operate indicator lights on the console. Analog data is used, for instance, to drive the antenna. Data input to the real-time program is shown in Table 4.

The analog to digital converter converts analog signals into a 15-bit integer, which is consequently placed into the command word according to the format below:



Since the data in positions 0 - 16 is not usable and since we use word arithmetic, the sign bit (17) is extended all the way to the left producing a properly signed 32 bit integer.

The encoder data has the format:



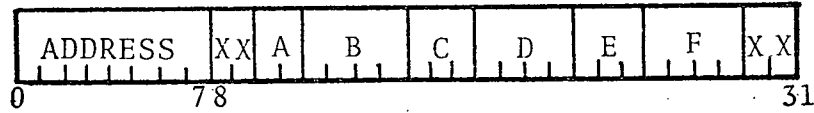
Since the encoder data is always positive but positions 0 - 14 are simply zeroed.

Table 4
INPUT FROM INTERFACE

ADDRESS		SYMBOL	USAGE	RESULT STORED IN
HEX	DEC			
96	150	A1XTACK	X - Tachometer	APDTACHX
97	151	A1YTACK	Y - Tachometer	APDTACHY
98	152	A1XER	X - Receiver Error	APXTRACK
99	153	A1YER	Y - Receiver Error	APYTRACK
9A	154	A1XJOY	X - Velocity Command	APXJOY
9B	155	A1YJOY	Y - Velocity Command	APYJOY
8A	138	A1XSLAV1	X - (Pos.) Joystick	APXSLAV
8B	139	A1YSLAV1	Y - (Pos.) Joystick	APYSLAV
F8	248	A1XENC	X - Encoder	APXENC
F9	249	A1YENC	Y - Encoder	APYENC
FA	250	A1XBIAS	X - Position Bias	APDXBIAS
FB	251	A1YBIAS	Y - Position Bias	APDYBIAS
FF	255	A1TBIAS	Time Bias	APDTBIAS
FE	254	A1STAT1	Status Word #1	APSTAT1
FD	253	A1STAT2	Status Word #2	APSTAT2
FC	252	A1STAT3	Status Word #3	APSTAT3
E3	227	A1TIME	REAL TIME	APSTSEC
E2	226	A1DAY	JULIAN DATE	-----

The status words contain information in all the bits beyond the address. Therefore only the address positions are zeroed.

Real-time is provided according to the format:



where

A = tens of hours
 B = hours
 C = tens of minutes
 D = minutes
 E = tens of seconds
 F = seconds

in BCD code. Real-time is converted to seconds in the program ASTIME.

The maximum encoder value occurs when all bits (15-31) are set to "1". This is equivalent to the decimal number $2^{17} - 1$. This reading corresponds to 360° . The resolution of the encoder is then

$$R = \frac{360^\circ}{2^{17} - 1} = \frac{360}{131071} = 0.00275^\circ \quad (1)$$

The maximum analog input or output is ± 10 volts which corresponds to $2^{14} - 1$ (14 bit and sign). The scale factor used for position error is 1 volt/degree. Then

$$10^\circ = 2^{14} - 1 \text{ counts} \quad (2)$$

or

$$1^\circ = \frac{2^{14} - 1}{10} = 1638.3 \text{ counts} \quad (3)$$

However, for the encoder we have:

$$1^\circ_{\text{enc}} = \frac{2^{17} - 1}{360} = 364.1 \text{ counts} \quad (4)$$

In order to have uniformity of units, one must multiply the encoder reading by the factor:

$$\text{Encoder scale factor} = \frac{1638.3}{364.1} = 4.5 \quad (5)$$

It was noticed that occasionally an encoder reading is abnormally large. An encoder "filter" was incorporated which rejects any reading that exceeds the previous valid reading by more than a degree. Recalling that the sampling frequency is 20 cps, one concludes, that if two successive readings differ by more than a degree, then the antenna must be moving at a velocity of $20^\circ/\text{sec}$. This is neither possible nor desirable. Thus, it seems that the choice of a maximum 1 degree difference between successive readings allows for normal operating speeds as well as reduces the effect of the large encoder error, which occasionally is of the order of 100° .

Since the encoder range is 0° - 360° and the desired range is -90° to $+90^{\circ}$, then encoder is set to a reading (encoder zero) anywhere in the range 90° - 270° when the antenna is at zenith. To obtain the true angle the, one subtracts the encoder reading from the encoder zero.

On output the D/A converter recognizes only the bits (17-31). Care is taken to assure that program outputs do not exceed $\pm 2^{14} - 1$. Thus, valid data is inserted into the bit positions (17-31) of the command word which already contains the appropriate interface address.

For discrete input and output, all data bits in the command word are processed.

The outputs to the antenna interface are shown in Table 5.

Table 5

OUTPUTS TO ANTENNA INTERFACE

ADDRESS		SYMBOL	USAGE
HEX	DEC		
00	0	AIMODOUT	Indicator Lights
12	18	A1XRDSP	X - Encoder
13	19	A1YRDSP	Y - Encoder
14	20	A1XCDSP	X - Command
15	21	A1YCDSP	Y - Command
16	22	A1CTDSP	Command Time
28	40	A1XSERVO	X - Valve Signal
29	41	A1YSERVO	Y - Value Signal
2A	42	A1XSAMP	X - Program Error
2B	43	A1YSAMP	Y - Program Error

6.2.2 Station Time (ASTIME)

Real-time is available at the antenna interface according to the format described in the previous section. This program converts real-time from hours, minutes and seconds to its decimal value in seconds.

6.2.3 Add (X,Y) Bias (ADDX)

When add position (X,Y) bias is selected, the setting of the digit switches on the antenna console is interpreted as a BCD number and is converted to units by the program according to 6.2.1 (equation 3). The format of the BCD number is XX.XXX degrees. The resultant bias is added to the command angle.

6.2.4 Add Time Bias (ADDT)

If add or subtract time is selected the setting of the time digit switches is converted to seconds. The format of the BCD output of the time switches is HH MM SS. The time bias is either added or subtracted from command time.

6.2.5 Limit Check (LIMTEST)

This routine checks whether the quantity in question is within certain bounds. If the quantity is outside the specified limits it is set equal to the closer limit. For example, the command angle should not exceed ± 80 degrees. If the command angle before the limit check is -84 degrees it will be set to -80 degrees.

6.2.6 Program Mode Error Output (APSAOUT)

This program forms the interface command word used to transmit the program mode error to the servo-amplifier. The command word is AlXSAMP (AlYSAMP). The 8 most significant bits contain the interface address of the input to the servo-amplifier while the signed program mode error is inserted into the 15 least significant bits.

6.2.7 Hydraulic Value Output (APSOUT)

This program is similar to the APSAOUT with the output of the digital controller substituted for program mode error and AlXSERVO, the output to the hydraulic valve, substituted for AlXSAMP.

6.2.8 Servo Error Calculation (APSEC)

The command angle is the sum of the predict, scan and augmentation. The servo error is calculated as the difference between the command angle and the encoder value (true position of the antenna). Prior to this computation the program ensures that the absolute value of the command angle does not exceed 80 degrees. This test is performed by the routine LIMTEST. There is an additional constraint on the command angles expressed by the equations:

$$\left. \begin{array}{l} |Lx| = 80^\circ \quad \text{-- } y < 54.5 \\ |Lx| = 80^\circ - 1.49 (|y| - 54.5) \quad \text{-- } y > 54.5 \end{array} \right\} \quad (1)$$

$$\left. \begin{array}{ll} |Ly| = 80^\circ & \text{-- } X < 42 \\ |Ly| = 80^\circ - 0.672 (|x| - 42) & \text{-- } X > 42 \end{array} \right\} \quad (2)$$

The two sets of equations are equivalent. This condition arises due to the mechanical design of the XY antenna. These relations describe a contour within the limits of the design. The X-command angle is checked for compliance with equation (1). If it is greater than the allowable limit expressed by these equations, it will be set equal to this limit.

The servo error is calculated next. The routine LIMTEST is used to limit this error to $\pm 10^\circ$. The result is stored in APXTF4IN(APYTF4IN).

6.2.9 Console Display Program (APDISPLY)

Command time, (X,Y) command angles as well as (X,Y) real angles are displayed at the antenna console once a second. This program converts these quantities to BCD via the routine AP@4BCD, then prepares the appropriate command words to the antenna interface.

6.2.10 BCD Conversion Program (AP@4BCD)

This routine converts a binary number into a BCD. Each decimal digit will be represented by 4 bits.

6.2.11 Brake-One Program (BRAKEON)

When the brakes are applied this program nulls the output to the hydraulic to prevent the antenna from driving while the brakes are applied.

6.2.12 Zero Predicts Program (APPREDZ)

In manual program mode, this routine is called to set the predicts equal to zero. The command angle will be determined solely by the setting of the Position Bias digit switches.

6.3 POSTPASS PROGRAMS

There is only one postpass program, viz., history analysis. There is an option to output the database onto a magnetic tape. The history analysis program produces a printout of selected items from the database.

SECTION 7.0

CONCLUSIONS AND RECOMMENDATIONS

Although the program ran satisfactorily improvement in speed of execution and in the quality of its performance can be achieved.

Speed of execution can be improved by fragmenting some of the larger programs into smaller subprograms which would be executed only when necessary. This should also prove to be a valuable asset in debugging the programs.

A new augmentation filter should be designed which would provide better performance than program mode without augmentation or autotrack mode.

Since the programs developed under this contract were meant to prove certain concepts, the main emphasis was placed on achieving operational status. Refinement of these programs should be attempted next.

APPENDIX I

FLOWCHARTS

In the following pages we present flowcharts for all programs and subprograms. Included with each flowchart is a brief description of each routine, together with a list of inputs, outputs, other routines required, and any other pertinent information.

Entry Name: ZEEXFM - Calculate output of
Z-transfer function.

Other Routines Required: None.

Input: Address of input provided in
register X7

Output: Output is stored in address
4 locations above that con-
tained in register X7

Method:

The general form of Z-transfer function used is:

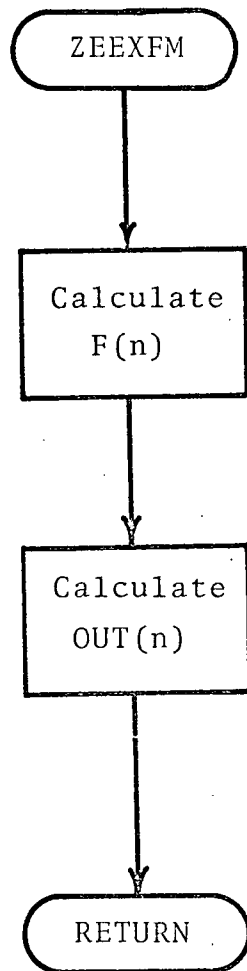
$$\frac{A_0 Z + A_1}{Z + b_1}$$

The output is calculated as follows:

$$F(nT) = \text{Input}(nT) - b_1 F[(n-1)T]$$

$$\text{Output}(nT) = A_0 * F(nT) + A_1 F[(n-1)T]$$

Note that $F(0)$ and $F(-kT)$ are zero.



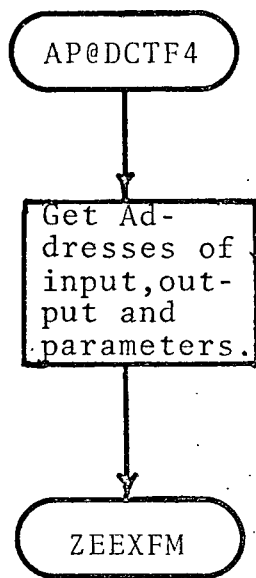
Entry Name: AP@DCTF4 - TF4

Other Routines Required: ZEEXFM

Input: None

Output: Addresses of input, output and parameters A_0 , A_1 , and b_1 of the Z-transfer function.

Functions: Obtains addresses described under output above and transmits them to ZEEXFM.



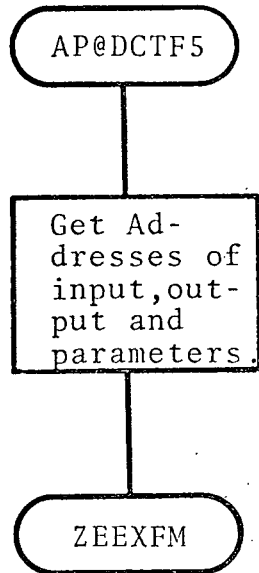
Entry Name: AP@DCTF5 - TF5 Velocity

Other Routines Required: ZEEXFM

Input: None

Output: Addresses of input, output and parameters A_0 , A_1 , and b_1 of the Z-transfer function.

Functions: Obtains addresses described under output above and transmits them to ZEEXFM.



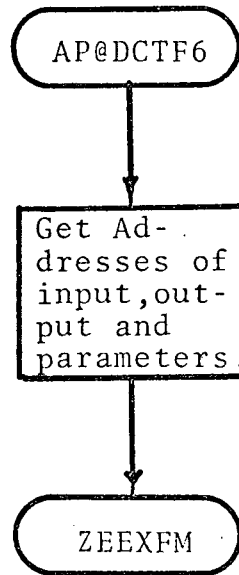
Entry Name: AP@DCTF6 - TF6 Tachometer

Other Routines Required: ZEEXFM

Input: None

Output: Addresses of input, output and parameters A_0 , A_1 , and b_1 of the Z-transfer function.

Functions: Obtains addresses described under output above and transmits them to ZEEXFM.



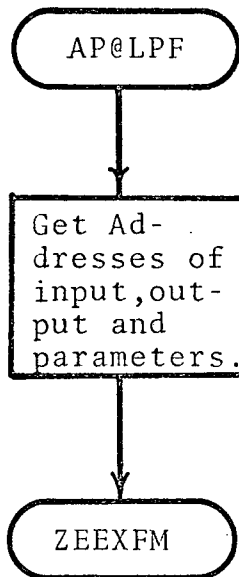
Entry Name: AP@LPF - Low Pass Filter

Other Routines Required: ZEEXFM

Input: None

Output: Addresses of input, output and parameters A_0 , A_1 , and b_1 of the Z-transfer function.

Functions: Obtains addresses described under output above and transmits them to ZEEXFM.



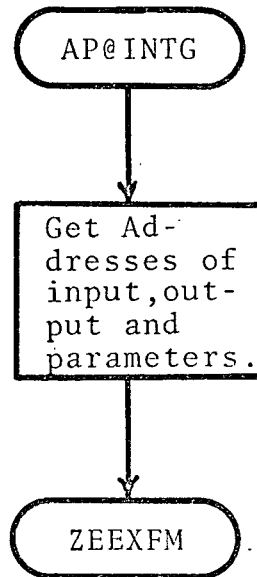
Entry Name: AP@INTG - Integrator

Other Routines Required: ZEEXFM

Input: None

Output: Addresses of input, output and parameters A_0 , A_1 , and b_1 of the Z-transfer function.

Functions: Obtains addresses described under output above and transmits them to ZEEXFM.



Entry Name: AP@AGMNT - Augmentation

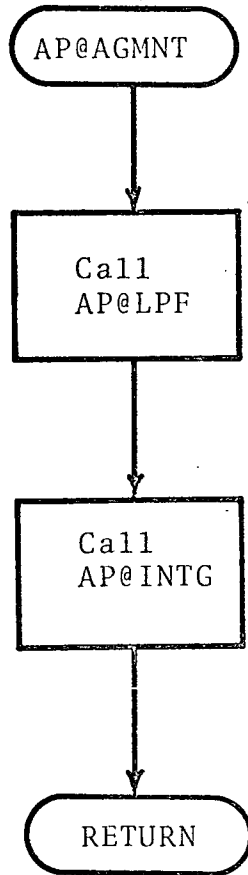
Other Routines Required: AP@LPF, AP@INTG

Input: APXTRACK - Receiver Error

Output: APXAUG - Augmentation increment to command angle.

Method:

The receiver error is passed through a low pass filter and an integrator, both in Z-transfer function form.



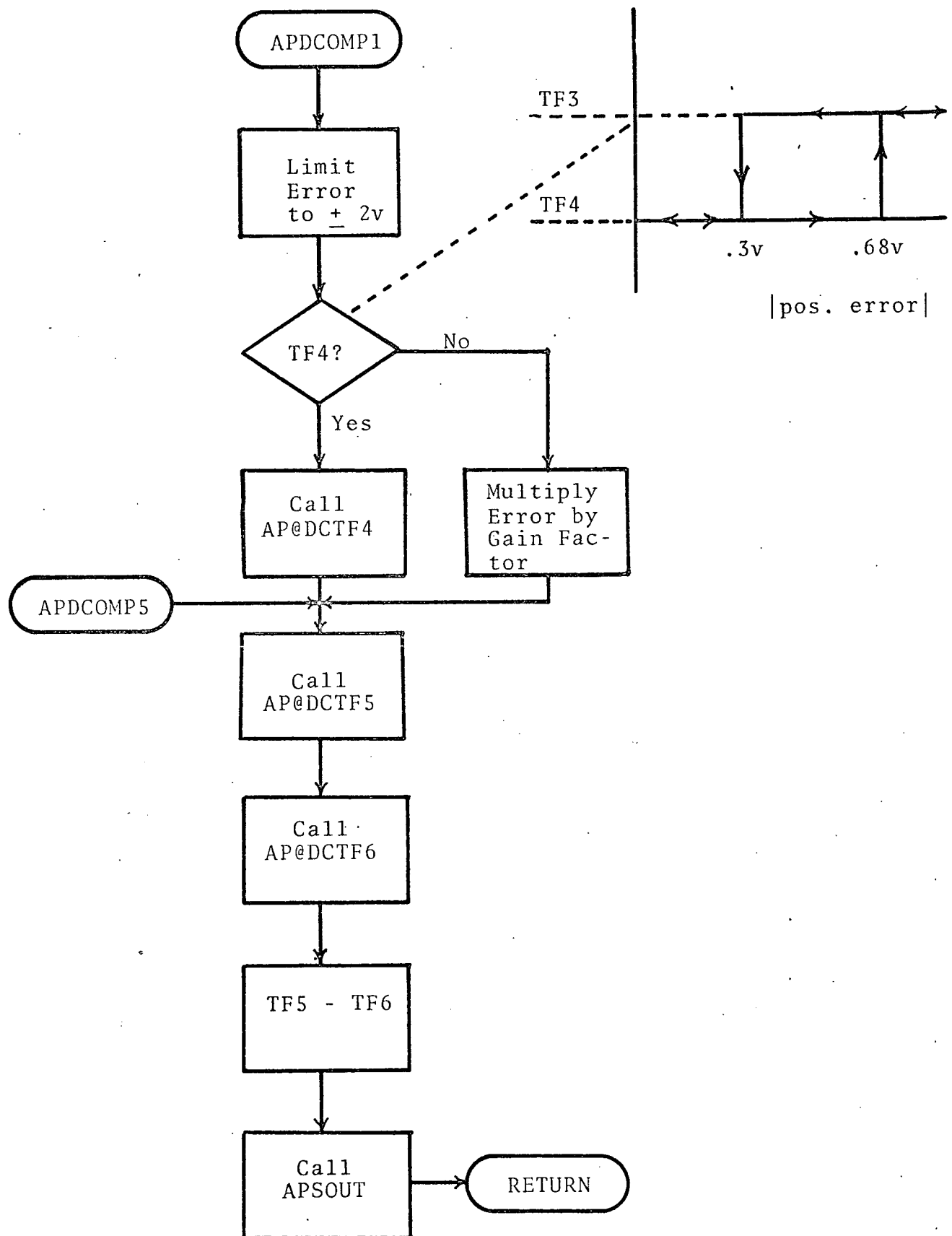
Entry Name: APDCOMP1, APDCOMP5 - Digital
Controller

Other Routines Required: AP@DCTF4, AP@DCTF5, AP@DCTF6,
APSOUT

Input: APDCOMP1 - Position Error -
APXTF4IN
APDCOMP5 - Velocity Error -
APXTF5IN

Output: APDCOMP1 - Velocity Error -
APXTF4OT (→APXTF5IN)
APDCOMP5 - Hydraulic Value
Voltage - APXSOUT

Function: The routine APDCOMP1 is used
in the position modes to produce
a velocity error. This error
is converted into a velocity
command by AP@DCTF5 which is
compared to the output of
AP@DCTF6, which is related to
the true velocity of the antenna.
The difference is converted to
a command (APXSOUT) to the hy-
draulic value. APDCOMP5 is also
used independently in the manual
velocity mode.



Entry Name: STRT - Executive routine

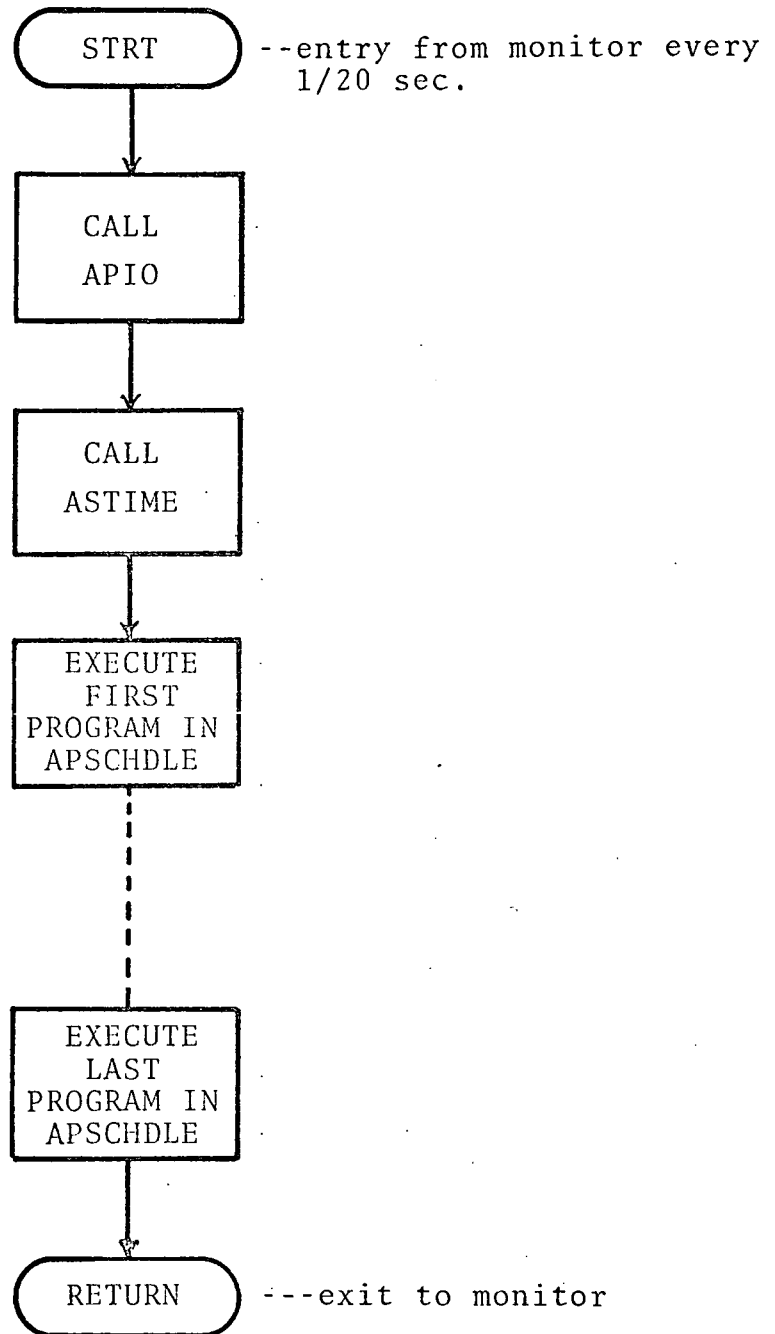
Other Routines Required: APIO, ASTIME

Input: APSCHDLE -- Schedule Table

Output: None

Function: This program executes routines whose entry points are stored in the schedule table APSCHDLE by the mode control program APPMODE. These programs are selected according to the setting of the bits in the status function words APSTAT1 and APSTAT2. The operating system (monitor) activates this program, via an external interrupt every 1/20 sec. After all the routines in the schedule are executed control is returned to the monitor. Prior to the execution of the programs in the schedule, all the necessary I/O is performed via the routine APIO and the real-time is converted to seconds via ASTIME.

EXECUTIVE



ENTRY NAME: APSEC

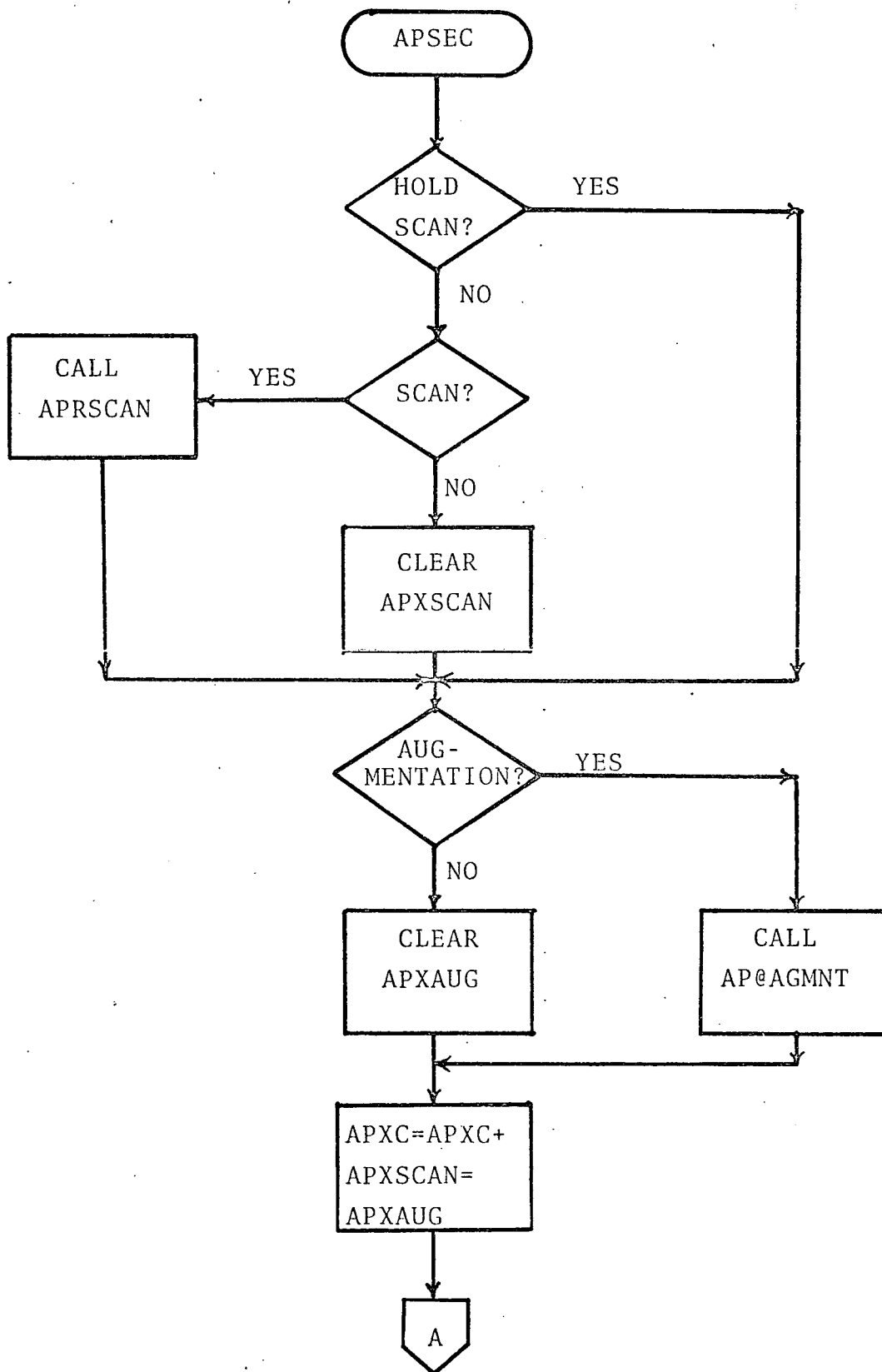
OTHER ROUTINES REQUIRED: APRSCAN, AP@AGMNT, LIMTEST

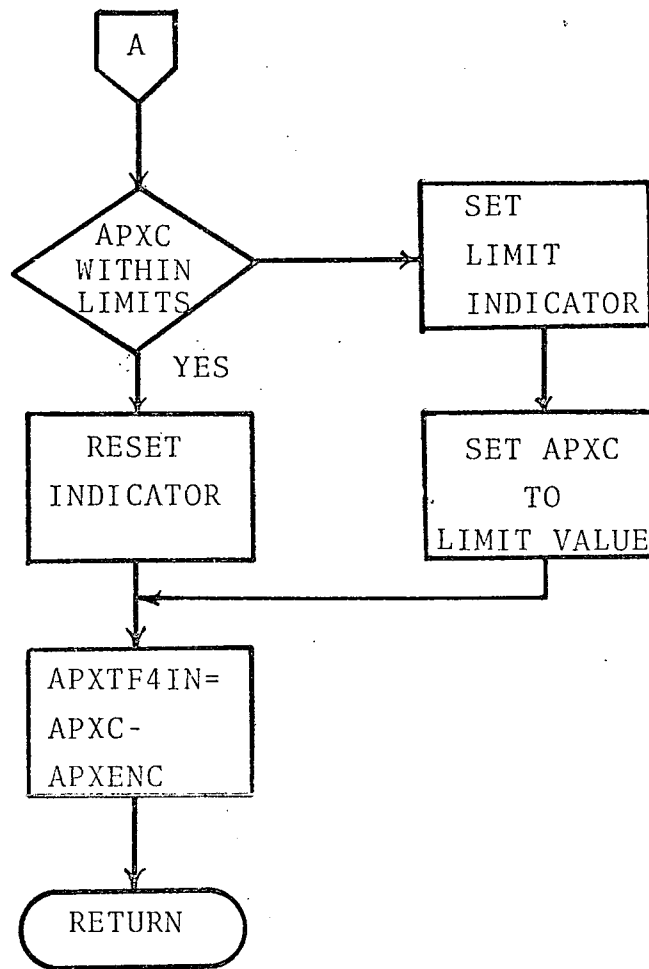
INPUT: APXC, APXSCAN, APXAUG, APXENC

OUTPUT: APXC, APXTF4IN

METHOD:

The command angle APXC is modified by adding the augmentation and scan increments (APXAUG, APXCAN) if these are selected. The modified angle is then limited to the allowable value, if necessary. The position error (APXTF4IN) is calculated as the difference between the command angle and the encoder value (real angle). The limit indicators are set when APXC exceeds the allowable limit and reset when it does not.





ENTRY NAMES: APRJOY
 APRJACH
 APMNPOS
 AUTOTRAK
 APRSTO

INPUT: (Corresponds to routines named above)

 APXJOY
 APDTACHX
 APXSLAV
 APXTRACK
 APXSTOW

OUTPUT: (Corresponds to inputs above)

 APXTF5IN
 APXTF6IN
 APXTF4IN
 APXTF4IN
 APXC

METHOD:

Transfer input from database to output location
in database.



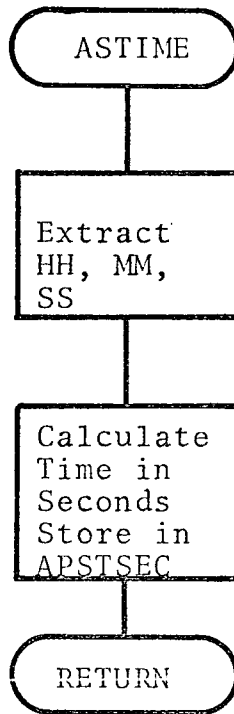
ENTRY NAME: ASTIME

INPUT: AETIME

OUTPUT: APSTSEC

METHOD:

Time in the form HHMMSS is extracted from AETIME
and converted to seconds and stored in APSTSEC.



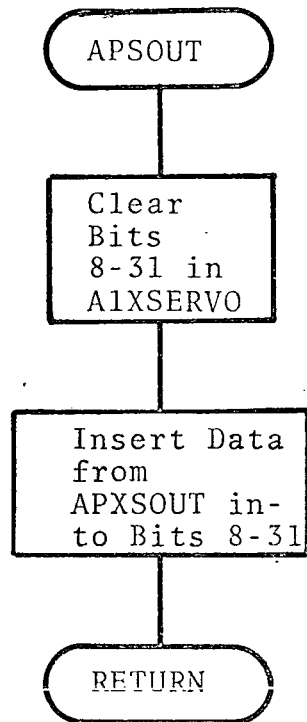
ENTRY NAME: APSOUT
 APSAOUT

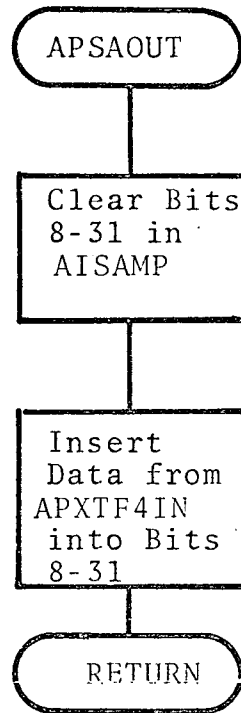
INPUT: APXSOUT }
 APXTF4IN } Corresponds to entry names above.

OUTPUT: AIXSERVO }
 AIXSAMP } Corresponds to inputs above.

METHOD:

The input is inserted into the proper bits of the
interface output command word AIXSERVO (AIXSAMP).





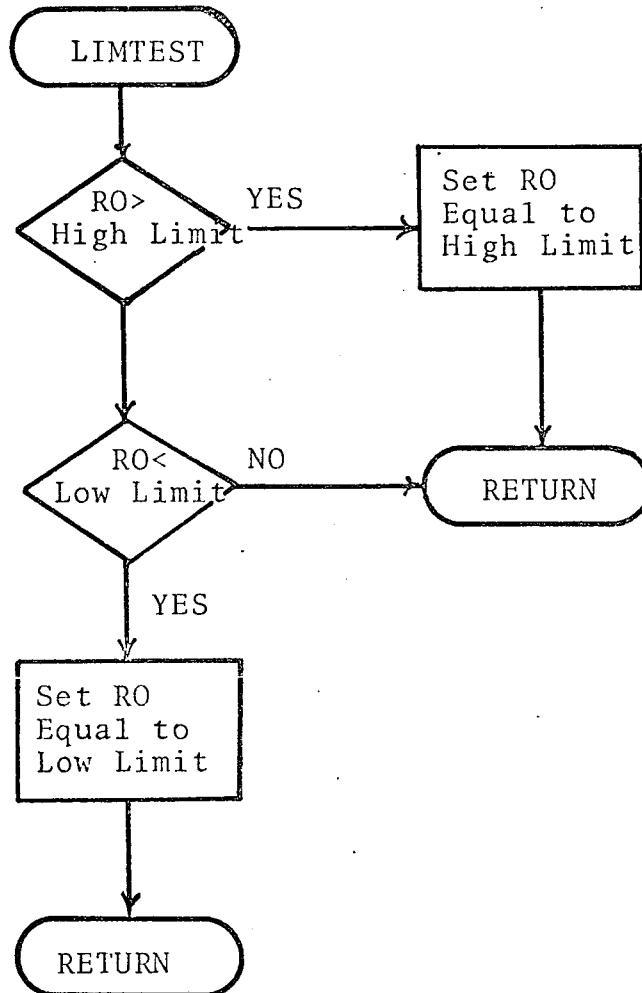
ENTRY NAME: LIMTEST

INPUT: R0, X3

OUTPUT: R0

METHOD:

The quantity to be tested against the limits is contained in R0. The proper test is selected by the value of X3. The output is a value that lies within the limits and is stored in R0.



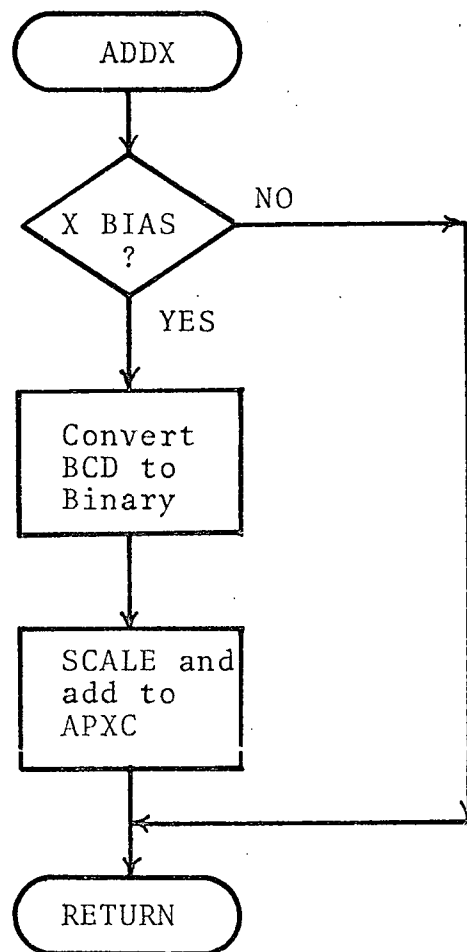
ENTRY NAME: ADDX

INPUT: APXC, APDXBIAS

OUTPUT: APXC

METHOD:

The setting of the X-Position Bias digit switches is stored in APDXBIAS. This value is converted from BCD and added to the command angle APXC, when X-Position Bias is selected.



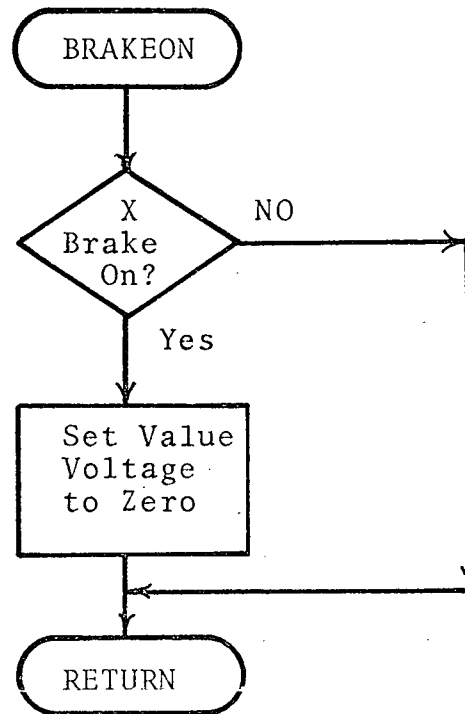
ENTRY NAME: BRAKEON

INPUT: APSTAT3

OUTPUT: AIXSERVO

METHOD:

The status word APSTAT3 is checked to determine if the brakes have been applied. If the brakes are on then the value output voltage AIXSERVO is set to zero, to avoid driving the antenna with the brakes on.



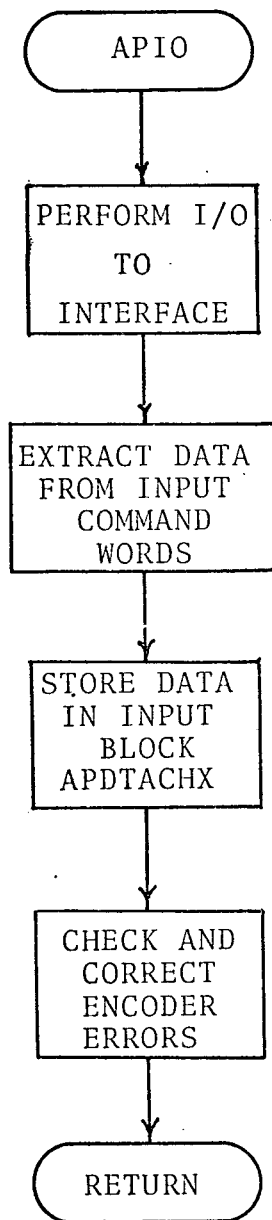
ENTRY NAME: APIO

INPUT: (See Table 4)

OUTPUT: (See Table 5)

METHOD:

I/O to the interface is performed. The input is derived from interface input command words. (See 6.2). An encoder filter is included which disregards the infrequent spurious readings of the encoder. The output to the interface is composed of output command words in which the current values of the outputs to the antenna are inserted.



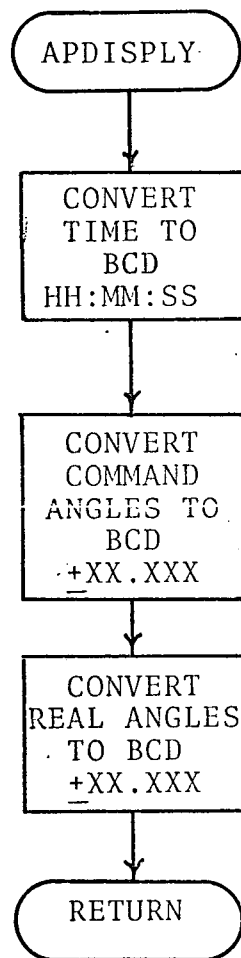
ENTRY NAME: APDISPLY

INPUT: APCTSEC, APXC, APXENC

OUTPUT: AICTDSP1, AIXCDSP1, AIXCDSP1

METHOD:

Command time and angles and real angle are converted to BCD. Then this data is inserted into the output command words to the antenna console displays.



ENTRY NAME: APRSCAN

INPUT: APSTAT2 (Contains scan radius)

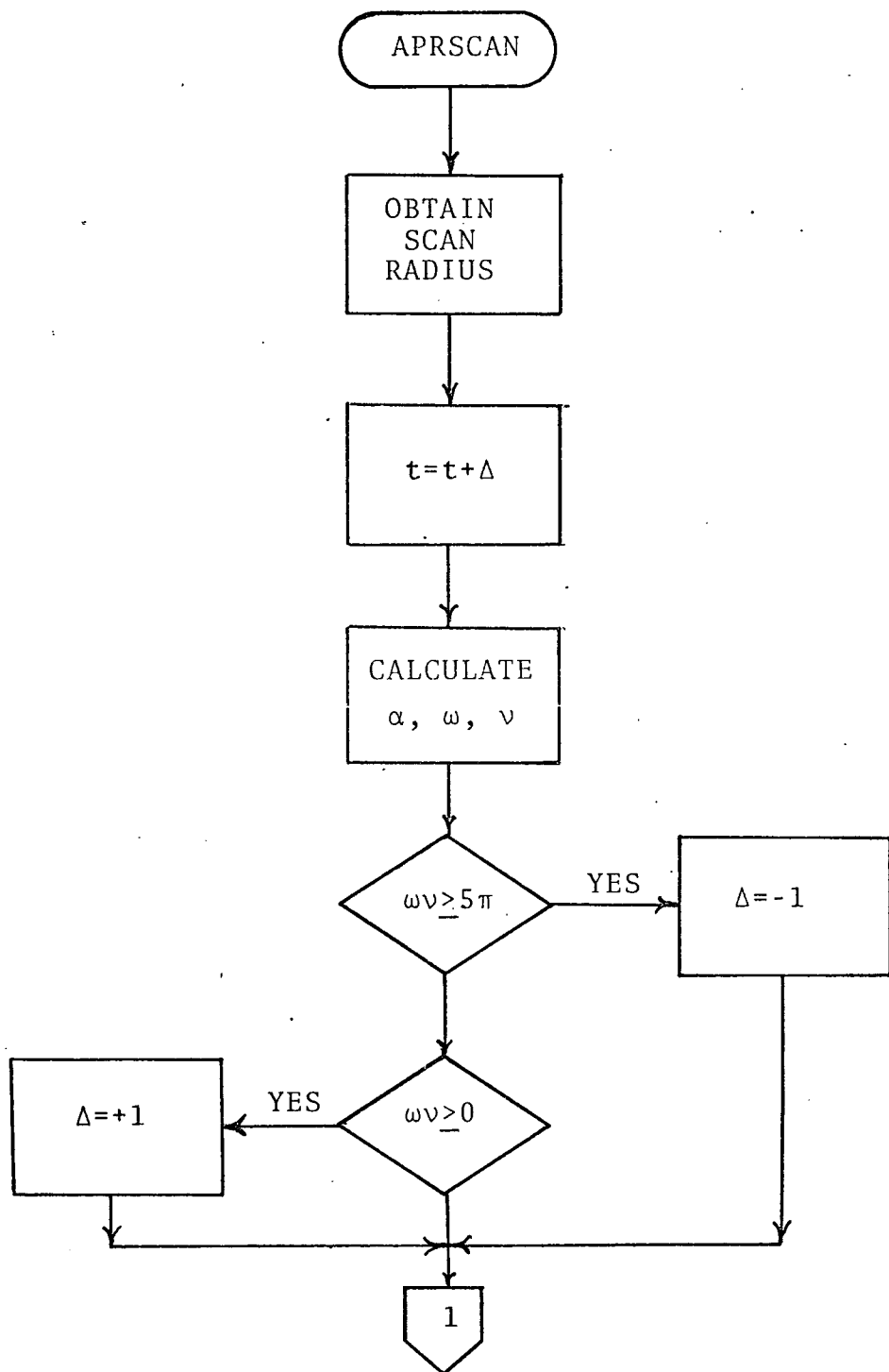
OUTPUT: APXSCAN

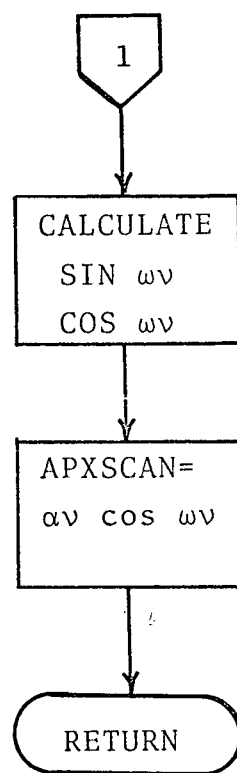
OTHER ROUTINES REQUIRED: SIN, COS

METHOD:

(See Section 4.1.1). When scan is selected the time t is initially zero. At the beginning of each new cycle t is increased by $1/20$ sec. When the scan angle reaches 5π ($2\frac{1}{2}$ turns) t is decreased by $1/20$ sec and the antenna spirals inward. The polarities of the X and Y scan increments are chosen at 0° and $5\pi^\circ$ to produce the spiral shown in Figure 5. Since the scan radius is selected via a rotary switch, which outputs a zero between positions, the scan radius is not altered until the new reading (APSTAT2) remains constant for 20 cycles; i.e., 1 sec. When changing scan radii the scan angle is kept constant to achieve the smallest change in antenna pointing attitude.

APXSCAN = $\alpha v \cos \omega v$





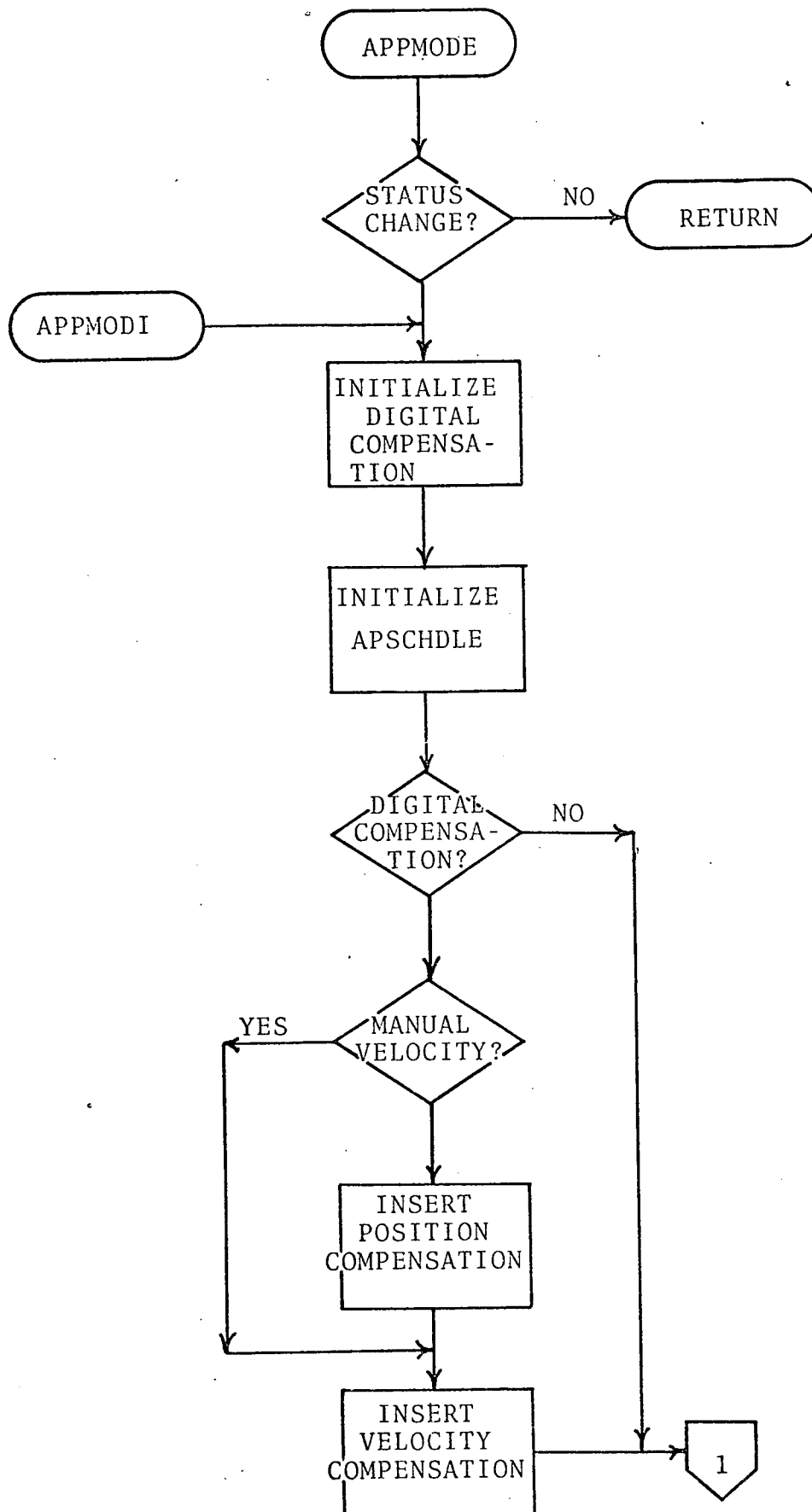
ENTRY NAME: APPMODE, APPMODI

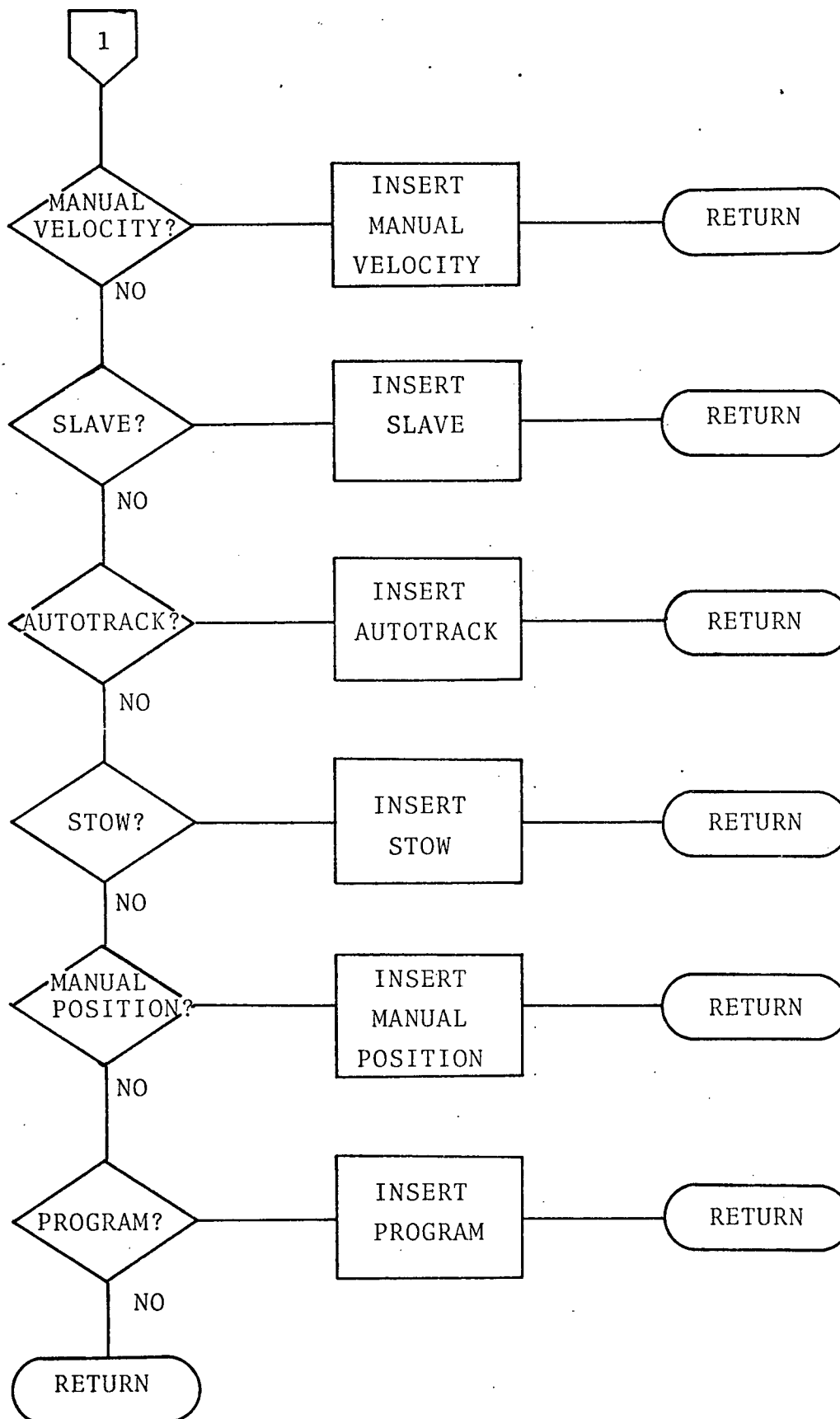
INPUT: APSTAT1, APSTAT2, APSTAT3

OUTPUT: APSCHDLE

METHOD:

 If the status indicators remain constant, the
 program exits immediately. Otherwise, a branch
 to APPMODI is performed and a new schedule
 (APSCHDLE) is formed to reflect the new status.





ENTRY NAME: APPRED

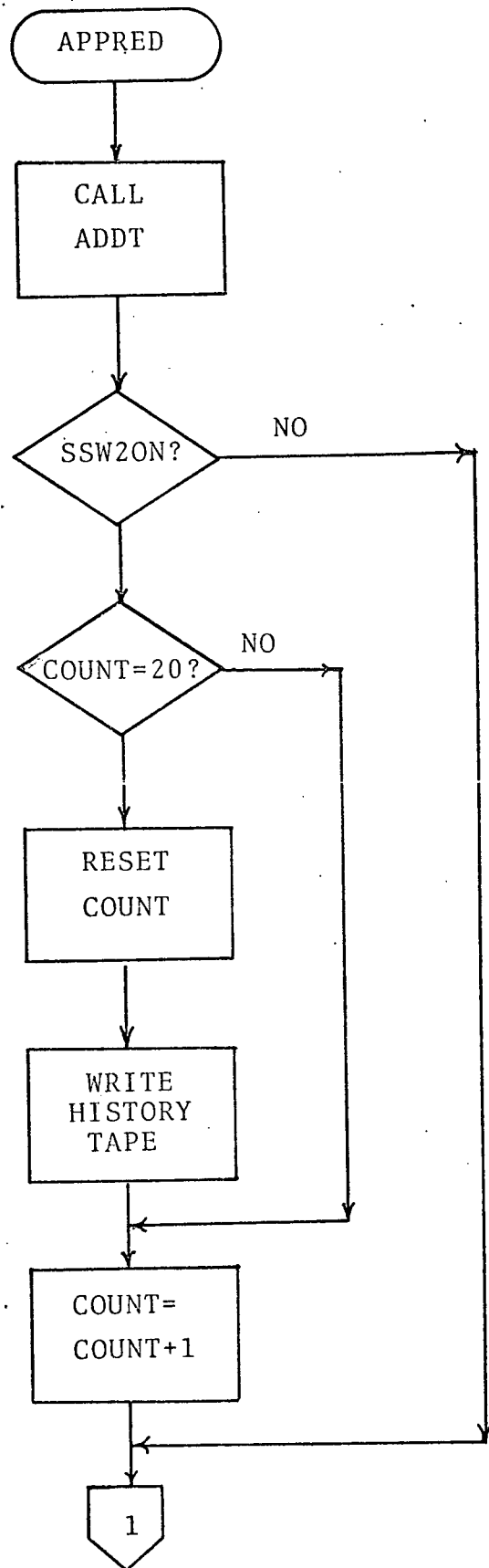
OTHER ROUTINES REQUIRED: ADDT, ADDX, APPREDZ

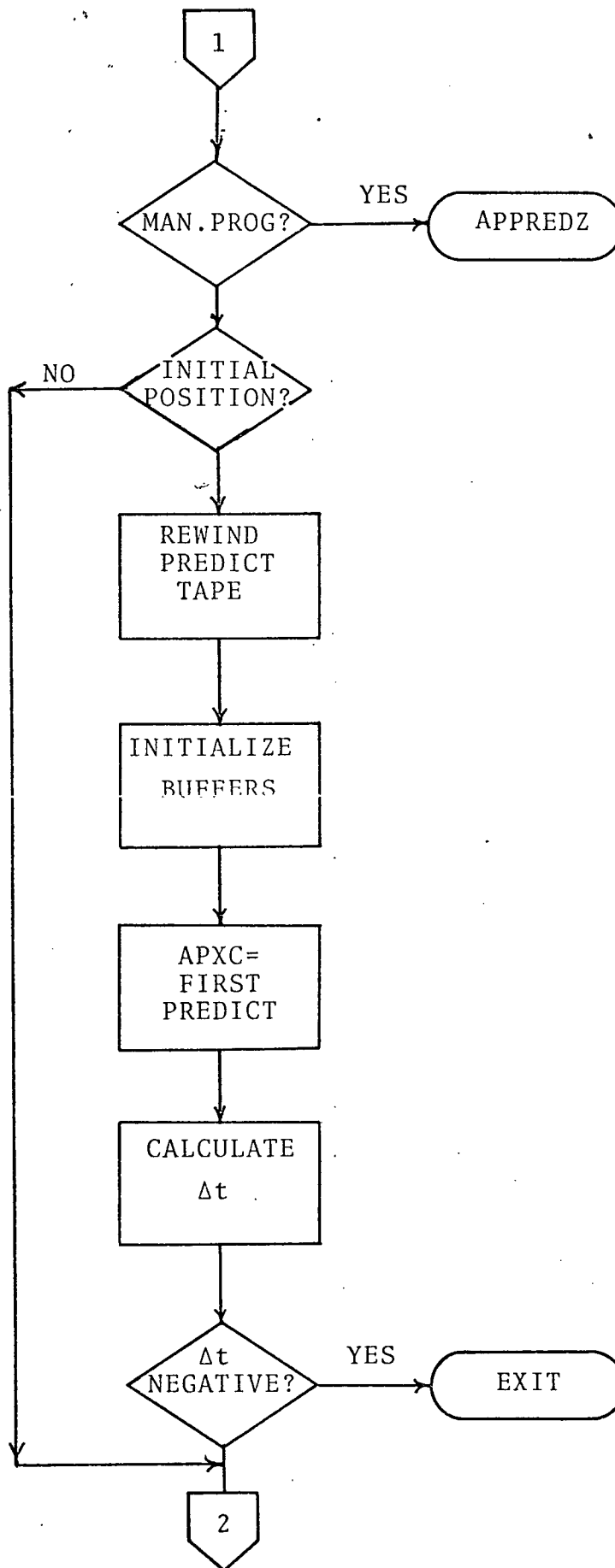
INPUT: APDXBIAS, APDTBIAS, APXPRED

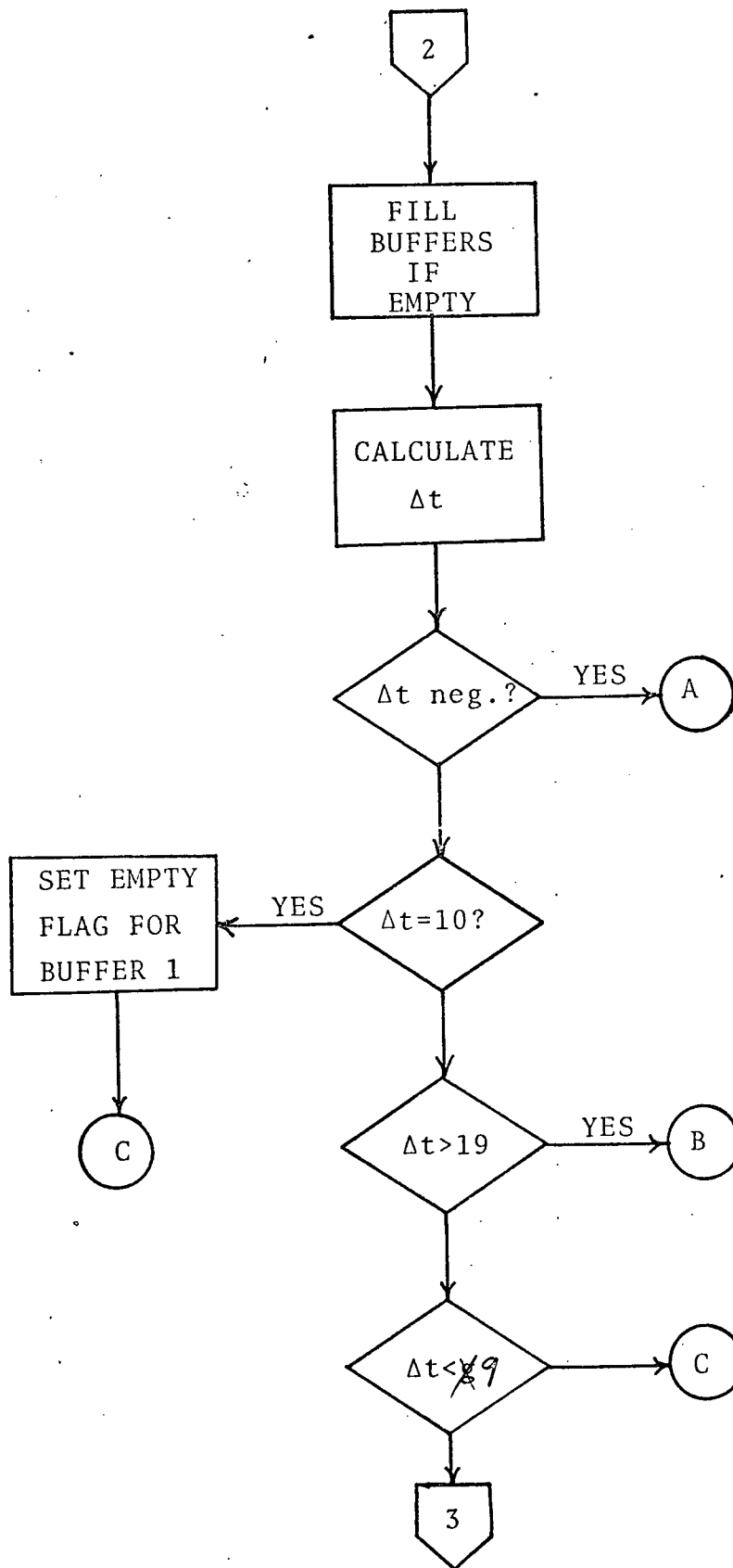
OUTPUT: APXC

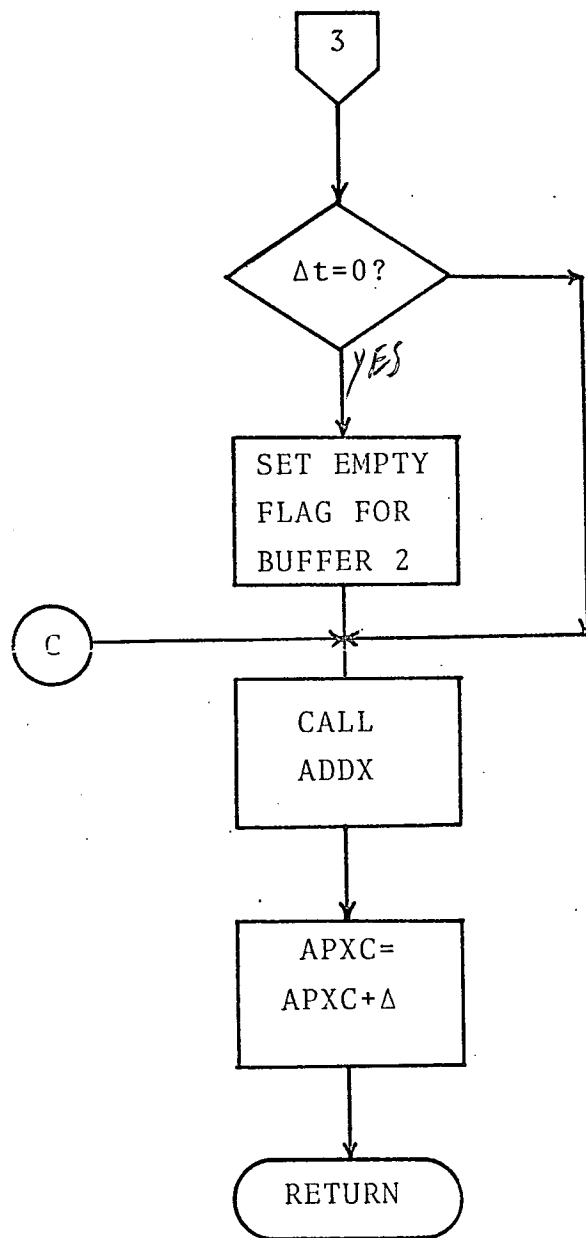
METHOD:

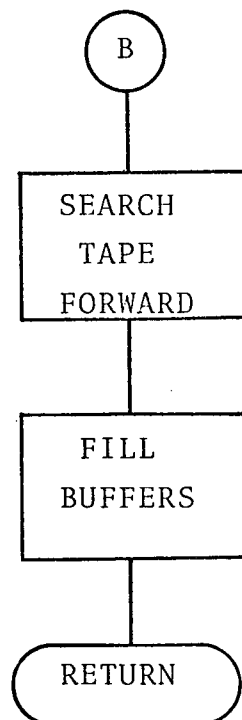
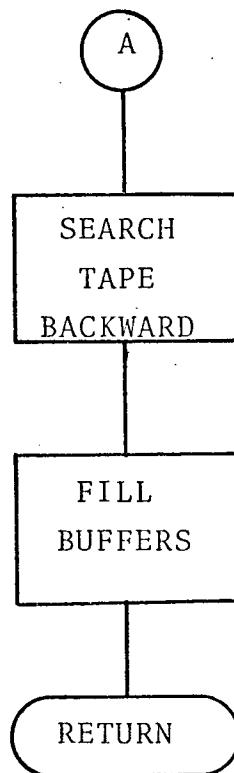
(See Section 4.1). There are two modes of operation: program mode and manual program mode. In the first case the command angle APXC is derived from the appropriate predict angle. In the second case the command angle is equal to the setting of the position bias digit switches.











PROGRAM NAME: ENV TO XY CONVERSION

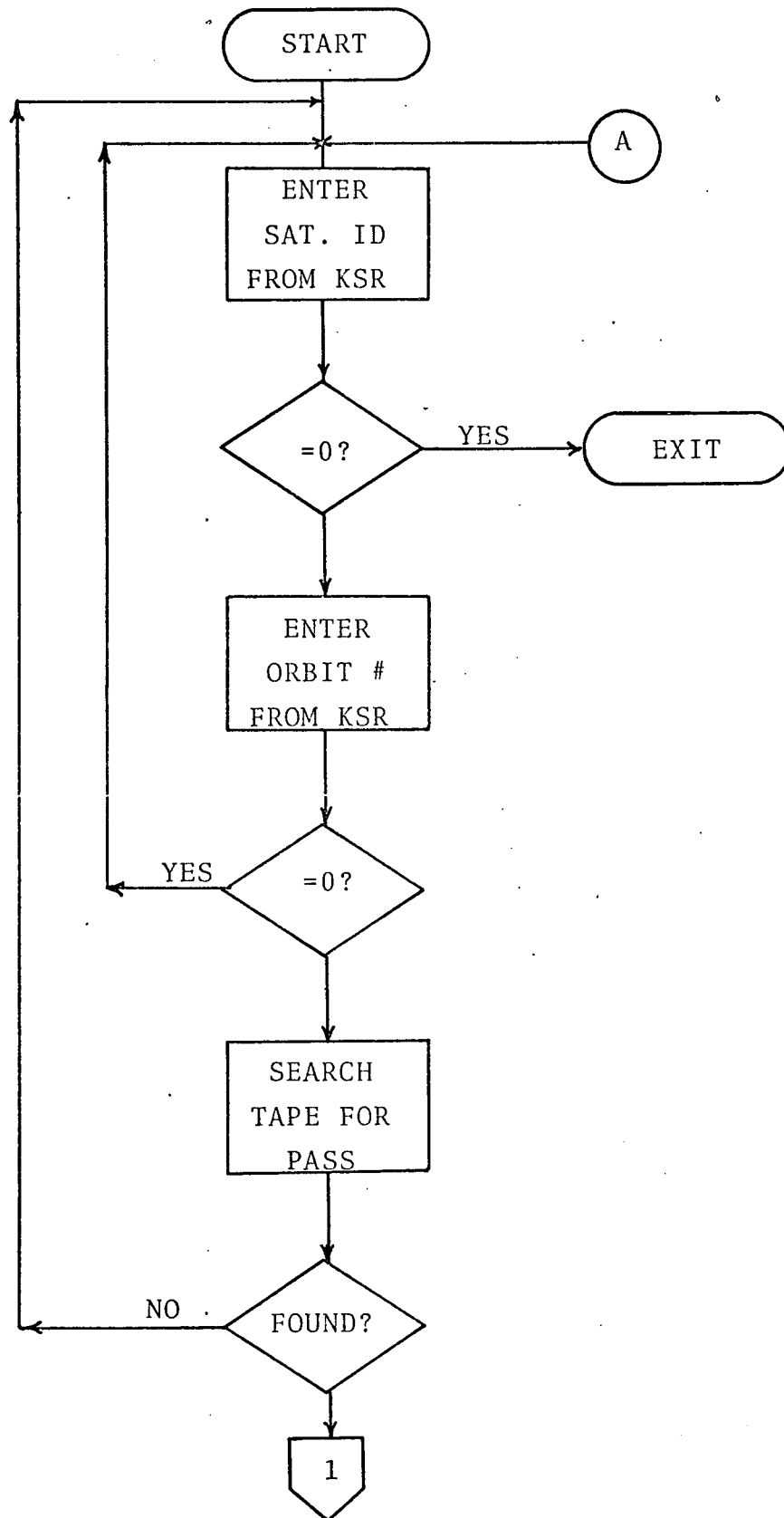
SOURCE LANGUAGE: FORTRAN IV .

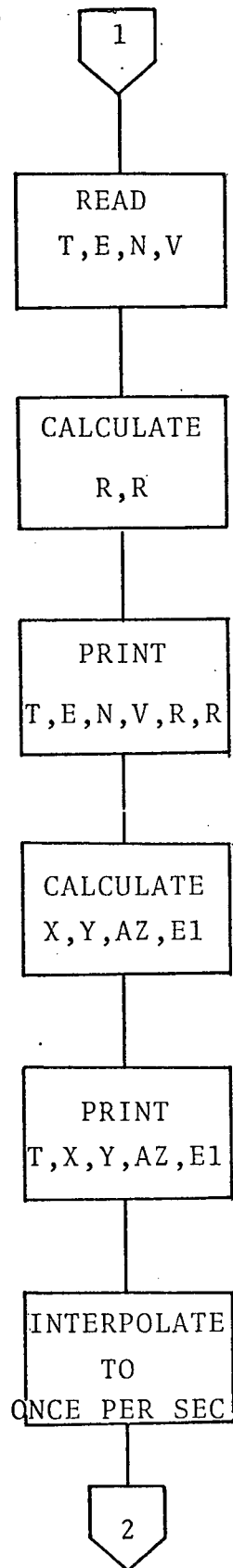
INPUT: ENV predicts

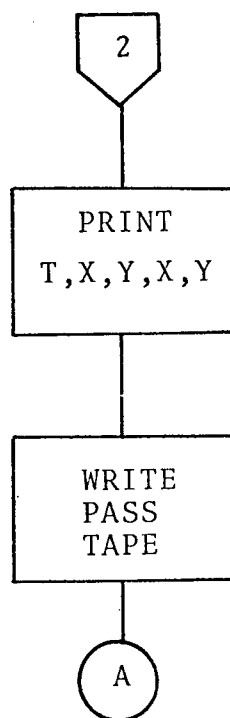
OUTPUT: XY predicts once per second

METHOD: (See Section 6.1.2)

ENV TO XY CONVERSION







PROGRAM NAME: Predict Listing

SOURCE LANGUAGE: FORTRAN IV

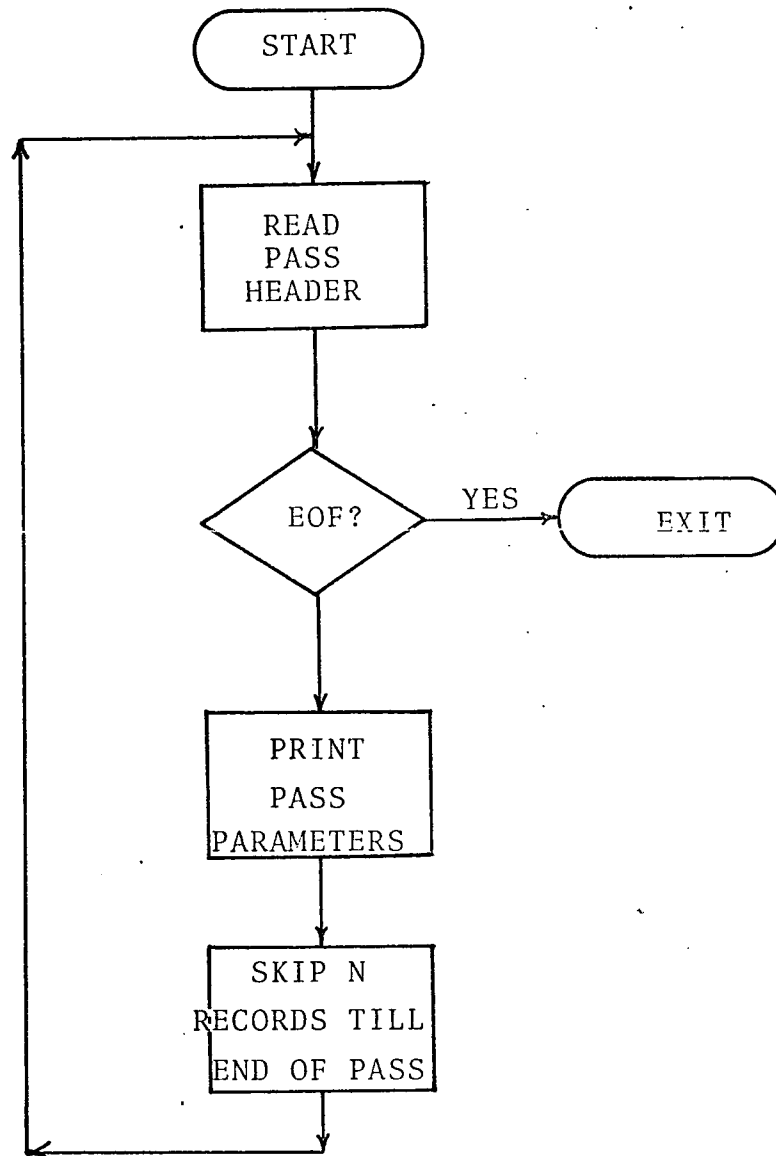
INPUT: OPSCON Pass Data Tape

OUTPUT: Predict Listing

METHOD:

Predict information on OPSCON Tape is listed giving satellite ID, date, orbit #, beginning of pass and pass duration.

PREDICT LISTING



PROGRAM NAME: HISTORY ANALYSIS

SOURCE LANGUAGE: FORTRAN IV

INPUT: History Tape

OUTPUT: Selected information from database

METHOD:

The History Tape contains a one per second dump of the database. Items to be printed are selected as follows:

$$X = \text{DATABASE}(N)$$

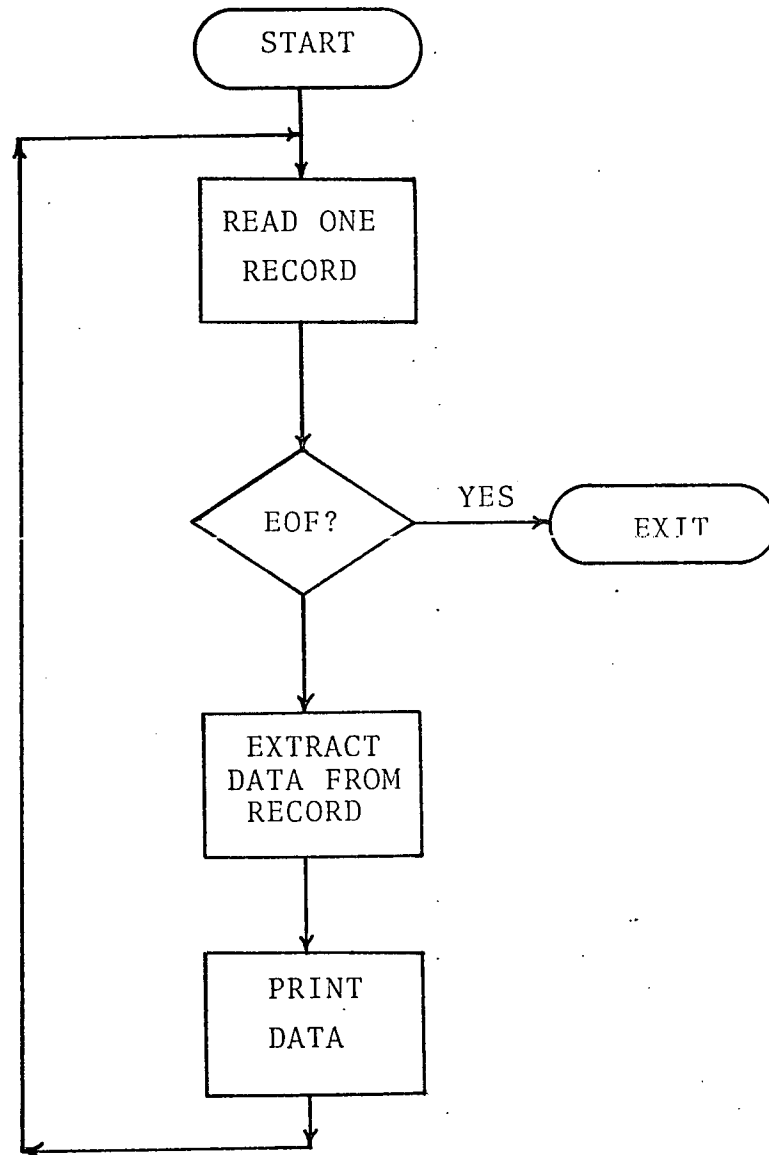
where X corresponds to the N^{th} item in the database (see real-time program listing). If scaling is needed, then the appropriate code is added, for example:

$$X = X * SF \quad \text{where SF is a scale factor.}$$

Finally a print statement is used to list X; i.e.,

$$\text{Print FFF}, X \quad \text{where FFF is a format statement}$$

HISTORY TAPE ANALYSIS



APPENDIX II

GLOSSARY OF TERMS

The following list of definitions is divided into two parts: database and program names.

Database

Input from interface (command words)

AIXTACK	X - tachometer reading
AIYTACK	Y - tachometer reading
AIXER	X - receiver error
AIYER	Y - receiver error
AIXJOY	X - velocity (Joystick)
AIYJOY	Y - velocity (Joystick)
AIXSLAV1	x - position error (Joystick)
AIYSLAV1	Y - position error (Joystick)
AIXENC	X - binary encoder (real position)
AIYENC	Y - binary encoder (real position)
AIXBIAS	X - BCD position bias (digit switches)
AIYBIAS	Y - BCD position bias (digit switches)
AITBIAS	Time bias (digit switches)
AISTAT1	Status function word 1
AISTAT2	Status function word 2
AISTAT3	Status function word 3

AITIME	Station time
AIDAY	Date

Output to interface (command words)

AIMODOUT	Limit indicators, type II indicators
AIXRDSP1	Real X display
AIYRDSP1	Real Y display
AISTDSP1	Station time
AICTDSP1	Command time
AIXSERVO	X - Valve voltage
AIYSERVO	Y - Valve voltage
AIXSAMP	X - Program mode error
AIYSAMP	Y - Program mode error

Decoded input from interface

The following 16 entries correspond one-to-one to the 16 quantities AIXTACK thru AISTAT3 described earlier under the heading input from interface. The only difference between them is that the following quantities are stripped of the address and any other irrelevant data.

APDTACHX
APDTACHY
APXTRACK
APYTRACK
APXJOY
APYJOY
APXSLAV
APYSLAV
APXENC
APYENC
APDXBIAS
APDYBIAS
APDTBIAS

APSTAT1
APSTAT2
APSTAT3

Antenna Parameters

APXEZCA	X - Encoder setting correspond to zenith
APYEZCA	Y - Encoder setting corresponding to zenith
APXSTOW	X - Stow angle
APYSTOW	Y - Stow angle

Digital Compensation Parameters

To evaluate the output of a Z-transfer function (see flowchart for ZEEXFM) the parameters a_0 , a_1 , b_1 and a previous value of the function $F(MT)$ are needed. Thus for each transfer function for each axis the following data is provided:

A0	a_0
A1	a_1
B1	b_1
IN	input
OT	output
FN1	$F[(n-1)T]$

Parameters for Low-pass Filter

APQLPFAO
APQLPFA1
APQLPFB1
APXLPFIN
APXLPFOT
FN1LPFX

Parameters for Integrator

APQINTA0
APQINTA1
APQINTB1
APXINTIN
APXINTOT
FN1INTX

Parameters for position compensation - TF4

APQTF4A0
APQTF4A1
APQTF4B1
APXTF4IN
APXTF4OT
FN1TF4X

Parameters for velocity compensation - TF5

APQTF5A0
APQTF5A1
APQTF5B1
APQTF5IN
APQTF5OT
FN1TF5X

Parameters for tachometer compensation - TF6

APQTF6A0
APQTF6A1
APQTF6B1
APQTF6IN
APQTF6OT
FN1TF6X

Miscellaneous Data

APSTSEC	Station time in seconds
APCTSEC	Command time in seconds
APXC	X - Command angle
APYC	Y - Command angle
APXPRED	X - Predict
APYPRED	Y - Predict
APXER	X - Flag used by encoder filter
APYER	Y - Flag used by encoder filter
APXAUG	X - Augmentation increment
APYAUG	Y - Augmentation increment
APXSCAN	X - Scan increment
APYSCAN	Y - Scan increment
APXSOUT	X - Output of APYSOUT program
APYSOUT	Y - Output of APYSOUT program
APDISPWK	Work area for APDISPY program
BUFF	Double buffer (160 words) for predicts
AISTAT1P	Previous status words (3)
APSCHDLE	Current Schedule Table
SCHEDULE	Initial Schedule

APPENDIX III

OPERATING INSTRUCTIONS

Predict Listing Program

A - Mount OPSCON Tape - ENV #

B - Load Program

- ENV to XY Conversion Program

A - Mount OPSCON Tape - ENV #

B - Mount Predict Tape - XY ##

C - Load program

D - Program will ask for satellite id; enter
satellite id on KSR - note that a zero will
cause program to exit.

E - Program will ask for orbit #; enter orbit #
on KSR

If satellite id or orbit # do not match those on
ENV #, a diagnostic will be output on KSR and program
returns to step D or E.

If the requested pass is found on ENV # the pass
is processed and control returns to step D.

History Analysis Program

A - Mount History Tape - HIST

B - Load Program

Real-time Program

It is assumed that the program resides on magnetic tape.

A - Load program (use load-deck)

B - When A is done, keyin:

!MEMORY SET, 6

C - Load run-deck

If operation in program mode is desired, load XY## and HIST tapes and press "start" on each unit - do not press "attention". Also keyin:

!MOUNT B80, XY

!MOUNT B81, HIST

Otherwise, continue here:

D - Keyin:

!INTC A,+63 (Arm Interrupt)

Program should be running at this point.

To terminate the program, keyin:

!F WOLF,R

To restart, keyin:

!F WOLF,L

If a history is needed, turn SSW2 on. To bypass history tape at any time, turn SSW2 off. SSW1 is used to exit. After such an exit the program cannot be restarted by an !F keyin. One must start with step C.

If program mode is selected and either of the tapes XY## or HIST are not mounted, program aborts. Since program mode is the default mode of operation, it is advised that the MAN. PROG switch on the antenna console be pressed prior to loading the program.

APPENDIX IV
Program Listing

DATABASE

D E F G H I J K L M N O P Q R S T U V W X Y Z

DATA	STR	BEGIN	F:8	F:9	APSEC	AFDCMP5	APDISPLY	APDCTF1	APDCTF2	APRJY	APRSLAV	APSAUT	APOTRAK	APMODI	APRED	APREDZ	ASCHEDULE	APBAGMT	APPMDE	DATABASE	APNOP	ASTIME	AITIME	BUFF	AN1	APXEZCA	APXEZCA	APXSTOW	APYSTOW	APOTBIAS	AIENXC	AIYENC	AIYER	AIYER	AIYBIAS	AIYBIAS	AIYBIAS
------	-----	-------	-----	-----	-------	---------	----------	---------	---------	-------	---------	--------	---------	--------	-------	--------	-----------	---------	--------	----------	-------	--------	--------	------	-----	---------	---------	---------	---------	----------	--------	--------	-------	-------	---------	---------	---------

DATABASE

DEF	AIXTACK
DEF	AIYTACK
DEF	AISTAT1
DEF	APSTAT1
DEF	AISTAT2
DEF	APSTAT2
DEF	ADGX
DEF	AISTAT3
DEF	APSTAT3
DEF	AIXJBY
DEF	AIYJBY
DEF	AIXSLAV1
DEF	AIYSLAV1
DEF	APSTINE
DEF	APSTSEC
DEF	APCTIME
DEF	APCTSEC
DEF	APXC
DEF	APYC
DEF	APXPRED
DEF	APYPRED
DEF	APXENC
DEF	APYENC
DEF	APXER
DEF	APYER
REF	AP2DCIF4
DEF	APGLPFAO
DEF	APXLPFFIN
DEF	APYLPFFIN
DEF	APGINTAO
DEF	APXINTIN
DEF	APYINTIN
DEF	APGTF4AO
DEF	APXTF4IN
DEF	APYTF4IN
DEF	APGTF5AO
DEF	APXTF5IN

DATABASE

83	DEF	APYTF5IN
84	DEF	APGTF6AO
85	DEF	APXTF6IN
86	DEF	APYTF6IN
87	DEF	APXTF5OT
88	DEF	APYTF5OT
89	DEF	APXSMCIN
90	DEF	APYSMCIN
91	DEF	APXERBR
92	DEF	APYERBR
93	DEF	APQXBIAS
94	DEF	APQYBIAS
95	DEF	APPXBIAS
96	DEF	APPYBIAS
97	DEF	APDTACHX
98	DEF	APDTACHY
99	DEF	APXAUG
100	DEF	APYAUG
101	DEF	APXSCAN
102	DEF	APYSCAN
103	DEF	APXDUT
104	DEF	APYDUT
105	DEF	APXJGY
106	DEF	APYJGY
107	DEF	APXSLAV
108	DEF	APYSLAV
109	DEF	APDISPMK
110	DEF	AIPEBUT
111	DEF	AIXSAMP
112	DEF	AIYSAMP
113	DEF	AIXSERV8
114	DEF	AIYSERV8
115	DEF	APXSUT
116	DEF	APYSUT
117	DEF	AISTDSP1
118	DEF	AICTDSP1
119	DEF	AIXCDSPI

DEF

DATABASE

DEF

BRAKE9N

DEF

AIYCDSP1

DEF

AIYRCDSP1

DEF

AIYRDSPI

DEF

AISTAT1P

DEF

APSCHOLE

DEF

APOSAVE

DEF

FG34X

DEF

FG34Y

REF

APDCOMP1

ANTENNA SIMULATOR DATA BASE

BOUND 8

01 00000

C1D5E3F1 A

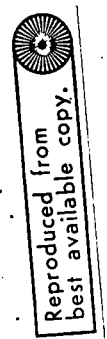
01 00000

ANT1

TEXT

ANT1

ANTENNA SIMULATOR



INPUT

01 00001

96000000

DATA

AIXTACK

X'96000000'

X TACHMETER

01 00002

97000000

DATA

AIYTACK

X'97000000'

Y TACHMETER

01 00003

98000000

DATA

AIYER

X'98000000'

X TRACKING RECEIVER ERROR

01 00004

99000000

DATA

AIYER

X'99000000'

Y TRACKING RECEIVER ERROR

01 00005

9A000000

DATA

AIYBY

X'9A000000'

X VELOCITY COMMAND (JBY STICK)

01 00006

9B000000

DATA

AIYBY

X'9B000000'

Y VELOCITY COMMAND (JBY STICK)

01 00007

9C000000

DATA

AIYSLAV1

X'9C000000'

SLAVE,PBS (JBY STICK)

01 00008

9D000000

DATA

AIYSLAV1

X'9D000000'

SLAVE,PBS (JBY STICK)

01 00009

9E000000

DATA

AIYENC

X'9E000000'

X ENCODER

01 0000A

9F000000

DATA

AIYENC

X'9F000000'

Y ENCODER

01 0000B

9A000000

DATA

AIYBIAS

X'9A000000'

X POSITION BIAS

01 0000C

9B000000

DATA

AIYBIAS

X'9B000000'

Y POSITION BIAS

01 0000D

9C000000

DATA

AIYBIAS

X'9C000000'

TIME OFFSET DIGIT SWITCHES


```

E00 0 : E E-
194 01 0002F 00000000 A APUTBIAS DATA DATA 0 DATABASE BIAS
195 01 00030 00000000 A APSTAT1 DATA DATA 0 TIME
196 01 00031 00000000 A APSTAT2 DATA DATA
197 01 00032 00000000 A APSTAT3 DATA DATA
198 *
199 *
200 *
201 *
202 *
203 01 00033 00000000 A APXEZCA DATA DATA
204 01 00034 00000000 A APYEZCA DATA DATA
205 01 00035 00000000 A APXSTGW DATA DATA
206 01 00036 00000000 A APYSTGW DATA DATA

      PREPASS INPUT DATA
      X ENCODER ZERO CORRECTION ANGLE
      Y ENCODER ZERO CORRECTION ANGLE
      X STGW POSITION
      Y STGW POSITION

```

EOO 0: E E-

207
208
209
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213
214

DATABASE

PAGE

ANTENNA INTERFACE INPUT

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E00

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DATABASE

24

252	01 00056	00000000 A	APYLPFIN	DATA	0
253	01 00057	00000000 A	APXLPFOT	DATA	0
254	01 00058	00000000 A	APYLPFOT	DATA	0
255	01 00059	00000000 A	FN1LPFX	DATA	0
256	01 0005A	00000000 A	FN1LPFY	DATA	0
257	01 0005B	00000000 A	APGINTAO	DATA	0
258	01 0005C	00000000 A	APGINTA1	DATA	0
259	01 0005D	00000000 A	APGINTB1	DATA	0
260	01 0005E	00000000 A	APXINTIN	DATA	0
261	01 0005F	00000000 A	APYINTIN	DATA	0
262	01 00060	00000000 A	APXINTOT	DATA	0
263	01 00061	00000000 A	APYINTOT	DATA	0
264	01 00062	00000000 A	FN1INTX	DATA	0
265	01 00063	00000000 A	FN1INTY	DATA	0
266	01 00064	00000000 A	APGTF4AO	DATA	0
267	01 00065	00000000 A	APGTF4A1	DATA	0
268	01 00066	00000000 A	APGTF4B1	DATA	0
269	01 00067	00000000 A	APXTF4IN	DATA	0
270	01 00068	00000000 A	APYTF4IN	DATA	0
271	01 00069	00000000 A	APXTF4OT	DATA	0
272	01 0006A	00000000 A	APYTF4OT	DATA	0
273	01 0006B	00000000 A	FN1TF4X	DATA	0
274	01 0006C	00000000 A	FN1TF4Y	DATA	0
275	01 0006D	00000000 A	FG34X	DATA	0
276	01 0006E	00000000 A	FG34Y	DATA	0
277	01 0006F	00000000 A	APGTF5AO	DATA	0
278	01 00070	00000000 A	APGTF5A1	DATA	0
279	01 00071	00000000 A	APGTF5B1	DATA	0
280	01 00072	00000000 A			0
281	01 00073	00000000 A			0
282	01 00074	00000000 A			0
283	01 00075	00000000 A			0
284	01 00076	00000000 A			0
285	01 00077	00000000 A			0
286	01 00078	00000000 A			0
287	01 00079	00000000 A			0
288	01 0007A	00000000 A			0

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best available copy.

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DATABASE

PAGE

ANTENNA PROGRAM SCHEDULE TABLE

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APSCDLE

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APNBP

DB

DATA

FIN

01 00135

00000008

01 00135 0000021F

01 00136

0000021F

01 00137

0000021F

01 00138

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01 00139

0000021F

01 0013A

0000021F

01 0013B

0000021F

01 0013C

0000021F

01 0013D

0000021F

01 0013E

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01 0013F

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APPMODI

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01 00149

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01 0014A

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01 0014B

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01 0014C

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APUSAVE

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01 0014D

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01 0014E

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= INITIAL PROGRAM SCHEDULE
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EOO      O : E E-
436      C1 00242 EA100139 APENTRY5 BAL,X1 *APSCHDLE+4
437      C1 00243 02000000 A N8P
438
439      C1 00244 EA10013A *APENTRY6 BAL,X1 *APSCHDLE+5
440      C1 00245 02000000 A N8P
441
442      C1 00246 EA10013B *APENTRY7 BAL,X1 *APSCHDLE+6
443      C1 00247 02000000 A N8P
444
445      C1 00248 EA10013C *APENTRY8 BAL,X1 *APSCHDLE+7
446      C1 00249 02000000 A N8P
447
448      C1 0024A *APENTRY9 BAL,X1 *APSCHDLE+8
449      C1 0024B 02000000 A N8P
450
451      C1 0024C EA10013E *APENTRY10 BAL,X1 *APSCHDLE+9
452      C1 0024D 02000000 A N8P
453
454      C1 0024E EA10013F *APENTRY11 BAL,X1 *APSCHDLE+10
455      C1 0024F 02000000 A N8P
456
457      C1 00250 EA100140 *APENTRY12 BAL,X1 *APSCHDLE+11
458      C1 00251 02000000 A N8P
459      C1 00252 32800054 A LW,RO X154
460      C1 00253 22800003 A LW,RO *RO
461      C1 00254 328000202 STN,RO TIMECK+1
462      C1 00255 0+900001 A M:EXIT 0
463      C1 00256 04100000A 02 RES 0
464      C1 00257 02000000 X M:W3F F:9
465      C1 00258 04100000 02 M:CLOSE F:8,(REM)
466
467      C1 00259 02000000 X M:CLOSE F:9,(REM)
468      C1 0025A 02000000 02
469      C1 0025B 15000000 X
470      C1 0025C 80000020 A
471      C1 0025D 02000000 A
472      C1 0025E 04100000 02
473      C1 0025F 15000000 X
474      C1 00260 80000020 A

```

EOO C : E E- DATABASE
 467 02 00010
 01 00259
 02 00011 02
 02 00011 02
 02 00012 7FFFFECC N
 02 00013 00000ACB 01
 02 00014 D709D6C7 A
 02 00015 D9C1D440 A
 02 00016 C1D9C5C1 A
 02 00017 43C4E4D4 A
 02 00018 D7404J40 A
 02 00016 02C000CC A
 02 00017 6800025A 01
 01 0025A 04900008 A

M:SNAP

M:TERM

TITLE 'API0'

* * * * *

468
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[illegible]

517	01 00270	2540046F A	SAS,4	-17
518	01 00271	2550046F A	SAS,5	-17
519	01 00272	25600311 A	SAD,6	17
520	01 00273	2560046F A	SAS,6	-17
521	01 00274	2570046F A	SAS,7	-17
522	01 00275	2580010F A	SLD,8	15
523	01 00276	25800071 A	SLS,8	-15
524	01 00277	25900071 A	SLS,9	-15
525	01 00278	25A00108 A	SLD,10	8
526	01 00279	25A00078 A	SLS,10	-8
527	01 0027A	25B00078 A	SLS,11	-8
528	01 0027B	25C00008 A	SLS,12	8
529	01 0027C	25C00078 A	SLS,12	-8

*****E N C O D E R F I L T E R *****

531	01 0027D	02200080 A	LCI	8
532	01 0027E	20000023	STM,0	APDTACHX
533	01 0027F	38800033	SW,8	APXEZCA
534	01 00280	38900034	SW,9	APYEZCA
535	01 00281	32700008 A	LW,7	8
536	01 00282	23700009 A	MI,7	9
537	01 00283	23900009 A	MI,9	9
538	01 00284	25700501 A	DWR,7	=20
539	01 00285	25700308		
540	01 00286	21700000 A		
	01 00287	69100289		
	01 00288	20700001 A		
	01 00289	2570047F A		
	01 0029A	25900001 A		
	01 0028B	36900328		
	01 0028C	21900000 A		
	01 0028D	6910028F		
	01 0028E	20900001 A		
	01 0028F	2590047F A		
541	01 00290	32500028	LW,5	APXENC
542	01 00291	3260002C	LW,6	APYENC
543	01 00292	33500007 A	SW,5	7

EOO	U :	E -	APIO
544	01 00293	A	SW,6
545	01 00294	A	LAW,5
546	01 00295	A	LAW,6
547	01 00296	A	CI,5
548	01 00297	A	BCR,2
549	01 00298	A	LW,0
550	01 00299	A	AI,0
551	01 0029A	A	STW,0
552	01 0029B	A	CI,0
553	01 0029C	A	BCS,1
554	01 0029D	A	STW,7
555	01 0029E	A	LI,0
556	01 0029F	A	STW,0
557	01 002A0	A	CI,6
558	01 002A1	A	BCR,2
559	01 002A2	A	LW,0
560	01 002A3	A	AI,0
561	01 002A4	A	STW,0
562	01 002A5	A	CI,0
563	01 002A6	A	BCS,1
564	01 002A7	A	STW,9
565	01 002A8	A	LI,0
566	01 002A9	A	STW,0
567	01 002AA	A	LCI
568	01 002AB	A	STW,10
569	01 002AC	A	LI,2
570	01 002AD	A	LI,2
571	01 002AE	A	LI,2
572	01 002AF	A	LI,2
573	01 002AG	A	LI,2
574	01 002AH	A	LI,2
575	01 002AI	A	LI,2
576	01 002AJ	A	LI,2
577	01 002AK	A	LI,2
578	01 002AL	A	LI,2
579	01 002AM	A	LI,2
580	01 002AN	A	LI,2

EQQ

O : E

E-

613 01 002DB

614 01 002DC

615 01 002DD

616 01 002DE

617 01 002DF

618

22800000 A

3580003B

3580003C

641002B1

630A0000 A

LI,PO

STM,RO

STM,RO

BAL,X1

B

TITLE

APIB

O

APXC

APYC

ADDX

O,X5

'BINDEC'

EOO 0: E E-
640
641

PAGE BINDEC
TITLE 'BINDEC'

BINDEC

DEF BINDEC
TEXT
DATA
DATA
RES
REG
EQU
LCFI
STM
LW
LI
LI
LW
LI
DW
LW
LD
BEZ
BR
SLD
LI
BIR
STM
LCFI
LM
B
END

'FO'
10
16
\$
0
REG1
BL
-4
-2
*14
0
TEN
2
2
*5
NUM
-8
0
DIV
*13
0
REG1
*15
BEGIN

BL
NUM
TEN
REG1
BINDEC

DIV

642	01	002F0	40404040	A
643	01	002E1	000003F0	A
644	01	002E2	0000000A	A
645	01	002E3		
646	01	002F3		
647	01	002F3	02300300	A
648	01	002F3	02300300	A
649	01	002F4	250002E3	
650	01	002F5	320002E0	
651	01	002F6	227FFFFC	A
652	01	002F7	226FFFFE	A
653	01	002F8	R230030E	A
654	01	002F9	22200300	A
655	01	002FA	362002E2	
656	01	002FB	32A00002	A
657	01	002FC	12800302	A
658	01	002FD	65300302	
659	01	002FE	49A002E1	
660	01	002FF	25A00178	A
661	01	00300	22200300	A
662	01	00301	657002FA	
663	01	00302	65800300	A
664	01	00303	02300300	A
665	01	00304	2A0002E3	
666	01	00305	E300030F	A
667	01	00220		
	01	00376	03008300	A
	01	00377	00000300	A
	01	00378	00000314	A
	01	00379	03400300	A
	01	00380	00200300	A
	01	00381	00100300	A

CONTROL SECTION SUMMARY: 01 0030C PT 0 02 00019 PT 0

A/00000001
APQREND/01 0014E
APENTRY5/01 00242
APENTRY6/01 00248
APENTRY11/01 0024E
APQINTA1/01 0005D
APQTF4A1/01 00069
APQTF6A1/01 00083
APXSL/01 00041
APYLPEFT/01 00058
B/00000000
DIV/01 002FA
FERP/00000000
FN1LPFX/01 0005A
FN1TF5Y/01 00080
L9FF/01 002C4
REG1/01 002F3
R2/0000000A
R5/0000000E
TEA/01 002E2
X2/00000002
X5/00000006
X6/00000007

EXTERNAL DEFINITIONS

ACCA/01 002A1
AISTAT1P/01 00132
AIBIAS/01 0000D
AIXCAC/01 000C9
AIXSAMP/01 00021
AIYELAS/01 0000C
AIYJY/01 000C6
AIYSLAV1/01 00008
APCIS/C/01 0003A
APQIBIAS/01 0002F
APNRP/01 0021F
APQINTAC/01 00052
APQTF6AC/01 00021

BINDEC

AENRP/01 00142
APENTRY2/01 0023C
APENTRY3/01 0023E
APENTY10/01 0024C
APEXLGP/01 0022A
APQLPFA1/01 00051
APQTF5A1/01 00077
APXINT9T/01 00063
APXTF68T/01 00089
APYTF49T/01 00070
CKY/01 002A0
ERR9R/01 002AD
FN1INTY/01 00066
FN1TF4Y/01 00072
FN1TF6Y/01 0008C
OPNFLG/01 00200
RO/00000008
R4/0000000C
STRX/01 0029D
TIMECK/01 00201
X4/00000004
YCHECK/01 00216

AIMQCBUT/01 00013
AISTAT3/01 00010
AIXRIAS/01 0000B
AIXJ9Y/01 00005
AIXSLAV1/01 00007
AIYENC/01 0000A
AIYSAMP/01 00022
ANT1/01 00000
APDTACHX/01 00023
APDYBIAS/01 0002E
APFXBIAS/01 00047
APQIF4A0/01 00067
APSTAT1/01 00030

AIDAY/01 00012
APENTRY6/01 00244
APENTRY9/01 0024A
APENTY12/01 00250
APINTFDW/01 0025C
APQLFFB1/01 00053
APQTF5B1/01 00079
APXLFFOT/01 00057
APYINT0T/01 00064
APYTF68T/01 0008A
CGNVXY/01 0026E
FBR/0000000F
FN1LPFX/01 00059
FN1TF5X/01 0007F
G9/01 00208
PRNT/01 00232
R1/00000009
R5/0000000D
STRY/01 002A7
X1/00000001
X5/00000005

AISTAT1/01 0000E
AISTDSP1/01 00018
AIXCDSP1/01 00019
AIXRDSPI/01 00014
AIXIACK/01 00001
AIYER/01 00004
AIYSERVE/01 00020
APCTIME/01 00039
APDTACHY/01 00024
API9/01 0025E
APPYBIAS/01 00048
APQTF5A0/01 00075
APSTAT2/01 00031

EOO 0 : E E-
 APSTAT3/01 00032
 APXC/01 00038
 APXERER/01 00045
 APXLRFIN/01 00055
 APXSMCIN/01 00043
 APXIF5IN/01 00073
 APYAG/01 00044
 APYER/01 00040
 APYCHY/01 00028
 APYSLAV/01 0002A
 APYTF4IN/01 0006E
 APYTRACK/01 00026
 BRAKEBN/01 0020E
 FG34Y/01 00074
 PRIMARY REFERENCES
 AP00CTF1
 APPMEDI
 AUTOTRAK
 ASTIME
 NO SECONDARY REFERENCES
 NO UNDEFINED SYMBOLS
 ERROR SEVERITY LEVEL: 0
 NO ERROR LINES

APSTIME/01 00037
 APXOUT/01 00040
 APXELCA/01 00033
 APXPRED/01 00030
 APXSGUT/01 00030
 APXIF50T/01 00070
 APYC/01 0003C
 APYEROR/01 00046
 APYLFFIN/01 00056
 APYXMCIN/01 00044
 APYTF5IN/01 0007C
 AP0SAVE/01 00140
 BUFF/01 00091
 SCHEDULE/01 00141

BINDEC
 APSTSEC/01 00038
 APXENC/01 0002B
 APXINTIN/01 00061
 APXSCAN/01 0004B
 APXSTOW/01 00035
 APXTF6IN/01 00087
 APYD9T/01 0004E
 APYEZCA/01 00034
 APYPRED/01 0003E
 APYSTOUT/01 0008E
 APYTF50T/01 0007E
 BEGIN/01 00220
 DATABASE/01 00000
 STRT/01 00222

AP0DCTF2
 APRJ8Y
 F:9

APDCOMP5
 APRSLAV
 M:LL

APDCOMP1
 APSAOUT

APDISPLY
 APSEC



[illegible]

```

200 0: I E- 0000000D
80 0000000F
81 0000000F
**** ENDLEVEL 1 DISPLAY OF COMMAND REGNAME
5
6 01 0000 3186000A LIMTEST
7 01 0001 68200005 BCR,2
8 01 0002 3186000B CW,RO
9 01 0003 68100007 BCR,1
10 01 0004 68020000 A
11 01 0005 3286000A LW,RO
12 01 0006 68020000 A
13 01 0007 3286000B LW,RO
14 01 0008 68020000 A
15
16 01 000A FFFFD47C A TEST1
17 01 000B 00002584 A
18 01 000C FFFFB334 A
19 01 000D 00004CCC A
20 01 000E FFFF3333 A
21 01 000F 00000000 A
22 01 0010 FFFFCCCE A
23 01 0011 00003332 A
24 01 0012 FFFF0001 A
25 01 0013 00003FFF A
26 01 0014 00000000 A
27 01 0015 00000000 A
28 01 0016 00000000 A
29 01 0017 00000000 A
30 01 0018 00000000 A
31 01 0019 00000000 A
32 01 001A 00000000 A
33 01 001B 00000000 A
34 01 001C 00000000 A
35 01 001D 00000000 A
36

```

STATION TIME
13 FORTAN IV-H BRANCH REGISTER
15 FORTAN IV BRANCH REGISTER

LIMTEST
TEST1,X3
\$+4
TEST1+1,X3
\$+4
0,X1
TEST1,X3
0,X1
TEST1+1,X3
0,X1
8
-11140,11140 6.8 V VALVE LIMIT
-19660,19660 12 V VELOCITY LIMIT
-3277,3277 ACCELERATION 2V
-13106,13106 ANTENNA LIMIT 80 DEG.
-16383,+16383 10V. LIMIT
0,0
0,0
0,0
0,0
0,0
TITLE
STATION TIME

EOO

0 : I E-

STATION TIME

DEF
REF
REF
REF
REF
RES
LW,R1
CW,R1
BCR,3
STW,R1
LW,X4
SLS,X4
SLD,X4
SLS,X5
SLD,X4
SLS,X5
SLD,X4
SLS,X5
LW,X4
SLS,X4
SLD,X4
STW,X4
SLS,R1
SLS,R0
SLD,R0
LW,R3
MW,R3
SLS,R0
SLD,R0
AW,R3
SLS,R0
SLD,R0
LW,R5
MW,R5
SLS,R0
SLD,R0
AW,R5
SLS,R0

ASTIME

01 0001E
01 0001E
01 0001F
01 00020
01 00021
01 00022
01 00023
01 00024
01 00025
01 00026
01 00027
01 00028
01 00029
01 0002A
01 0002B
01 0002C
01 0002D
01 0002E
01 0002F
01 00030
01 00031
01 00032
01 00033
01 00034
01 00035
01 00036
01 00037
01 00038
01 00039
01 0003A
01 0003B
01 0003C
01 0003D

32900000 X
3190004C
68300049
3590004C
32400009 A
2540007E A
25400179 A
2550007F A
25400179 A
2550007F A
2540017A A
2550007E A
32400000 X
25400068 A
25400118 A
35400000 X
2590000A A
25800020 A
25800102 A
32800008 A
37800004 A
25800020 A
25800104 A
30800008 A
25800020 A
25800103 A
32800008 A
37800004 A
25800020 A
25800104 A
30800008 A
25800020 A
30800008 A
25800020 A

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45
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47
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49
50
51
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60
61
62
63

ASTIME
AITIME
APSTSEC
AISTDSP1
0
AITIME
TAIM
EXIT
TAIM
R1
-2
-7
-1
-7
-1
-6
-2
AISTDSP1
-24
24
AISTDSP1
10
32
2
R0
TEN
32
4
R0
32
3
R0
TEN
32
4
R0
32


```
EOO 0: I E-
* SYMREL VALUES
  EXIT/01 00049
  R1/00000009
  R5/0000000D
  TAIM/01 0004C
  X2/00000002
  X6/00000006
* EXTERNAL DEFINITIONS
  ASTIME/01 0001E
* PRIMARY REFERENCES
  AISTDSP1 AITIME
* N9 SECONDARY REFERENCES
* N9 UNDEFINED SYMBOLS
* ERROR SEVERITY LEVEL: 0
* N0 ERROR LINES

FBR/00000000F
R2/00000000A
R6/00000000E
TEN/01 0004A
X3/000000003
X7/000000007
LIMITEST/01 00000

STATION TIME
FDRH/00000000D
R3/00000000B
R7/00000000F
TEST1/01 0000A
X4/000000004

R0/00000000R
R4/00000000C
SIXTY/01 0004B
X1/000000001
X5/000000005
```

[illegible]

EOO 0: E- 0000000D 0000000F 1015PLAY 0F COMMAND FBRH FBRH SET SET REGNAME TITLE
80 81 ENDLEVEL 5
PROGRAM MODE
13 15
FORTRAN IV-H BRANCH REGISTER
FORTRAN IV BRANCH REGISTER

6	01 00000	32600001 A	REF	F:8	
7	01 00001	6A100050	REF	F:9	
8	01 00002	6C000000 A	DEF	APPRED	
9	01 00003	6840000C	REF	APXC	
10	01 00004	3280014F	REF	APXPRED	
11	01 00005	21800114 A	REF	APCTSEC	
12	01 00006	6980000A	REF	APSTAT2	
13	01 00007	22800000 A	REF	ANT1	
14	01 00008	3580014F	REF	APYPRED	
15	01 00009	04100000 02	REF	APYC	
16	02 00000	11000000 N	REF	API0	
17	02 00002	30000000	REF	AIXSAMP	
18	02 00003	00000000 X	REF	AIYSAMP	
19	01 0000A	00000000 A	REF	APDTBIAS	
20	01 0000A	22800001 A	REF	ADDX	
21			REF	BUFF	
22			REF	APXENC	
23			REF	APYENC	
24			REF	APCTSEC	
25			REF	APXDST	
26			REF	APYDST	
27			REF	APPREDZ	
28			LW,X6	X1	
29			BAL,X1	ADDT	
30			RD,C	C	
31			BCR,4	3+9	
32			LW,RO	COUNT	
33			CI,RO	20	
34			BCS,3	3+4	
35			LI,RO	C	
36			STW,RO	COUNT	
37			M:ARITF	F:9,(BUF,ANT1),(SIZE,2048)	
38			LI,RO	1	

E00

F-

12

P R O G R A M M O D E

AMM,RO

LW,RO

AND,RO

BCR,3

LW,RO

STW,RO

BAL,X1

B

6680014F

32800J00

4880015F

63300013

32800J00

35800000

6A100J00

680C0J00

32300J00

48800160

63300J19

22300000

35800042

35800J43

22300J00

31800043

69300J44

31800042

69300J34

04100004

01000000

04100J05

10000000

30500J10

00000J00

00000J2C

32800J01

20EFFFF8

35800150

04100J09

10000000

30000J10

0001FFFF

00000148

3P800001

3580015C

30800157

CKIP08

APSTAT2

APSTAT2

INITP9S

INITP9S

INITP9S

INITP9S

INITP9S

INITP9S

INITP9S

INITP9S

INITP9S

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C: 68 01 00027
 69 01 00028
 70 01 00029
 71 01 0002A
 72 01 0002H
 73 01 0002C
 74 01 0002D
 75 01 0002E
 76 01 0002F
 77 01 00030
 78 01 00031
 79 01 00032
 80 01 00033
 81 01 00034
 82 01 00035
 83 01 00036
 84 01 00037
 85 01 00038
 86 01 00039
 87 01 0004A
 88 01 0003B
 89 01 0003C
 90 01 0003D
 91 01 0003E
 92 01 0003F
 93 01 00040
 94 01 00041
 95 01 00042
 96 01 00043
 97 01 00044
 98 01 00045
 99 01 00046
 100 01 00047
 101 01 00048
 02 0000D
 02 0000F
 02 0000N

35800000 X
 32800002 N
 25800000 X
 35800000 X
 32800003 N
 35800000 X
 35800000 X
 35800000 X
 22800001 A
 358000150
 35800042
 35800155
 22800000 A
 35800151
 32F00000 X
 32800002 N
 35800000 X
 32800003 N
 35800000 X
 32E00001 N
 35E0014E
 35E00000 X
 30E000157
 31F0000E A
 69100000 A
 22800001 A
 35800043
 63000044
 00000000 A
 00000000 A
 22A00000 A
 22800001 A
 31A00150
 6930004A
 04100000 02
 10000000 N
 30000000
 0001FFFF N

TEST

P R O G R A M M O D E
 STW,RO APCTSEC
 LW,RO BUFF+2
 STW,RO APXC
 STW,RO APXPRED
 LW,RO RUFF+3
 STW,RO APYC
 STW,RO APYPRED
 LI,RO 1
 STW,RO BUF1
 STW,RO IPFLG
 STW,RO SET2
 LI,RO C
 STW,RO RUF2
 LW,RO APSTSEC
 LW,RO BUFF+2
 STW,RO APXC
 LW,RO BUFF+3
 STW,RO APYC
 LW,RO RUFF+1
 STW,RO TIIM
 STW,RO APCTSEC
 AW,RO SAVE
 CW,RO R6
 BCS,1 0,X6
 LI,RO 1
 STW,RO IPFLG
 B, FILL
 DATA 0
 DATA 0
 LI,RO 0
 LI,RO 1
 CW,RO BUF1
 BCS,3 CK2.
 M:READ F:8,(BUF,BUFF-1),(SIZE,328)

RECEIVED

003 : 003

STW,R3	BUF1	STW,R3	BUF2	STW,R3	BUF1	STW,R3	BUF1
CM,R2	BUF2	CM,R2	BUF2	CM,R2	BUF2	CM,R2	BUF2
BCS,3	CKT	BCS,3	CKT	BCS,3	CKT	BCS,3	CKT
M:READ	F:8,(BUF,BUFF+79),(SIZE,328)	M:READ	F:8,(BUF,BUFF+79),(SIZE,328)	M:READ	F:8,(BUF,BUFF+79),(SIZE,328)	M:READ	F:8,(BUF,BUFF+79),(SIZE,328)
00000148 A		00000148 A		00000148 A		00000148 A	
35300150		35300150		35300150		35300150	
31A00151		31A00151		31A00151		31A00151	
67300152		67300152		67300152		67300152	
04100153		04100153		04100153		04100153	
01000154		01000154		01000154		01000154	
10000155		10000155		10000155		10000155	
30000156		30000156		30000156		30000156	
00000157		00000157		00000157		00000157	
00000158		00000158		00000158		00000158	
00000159		00000159		00000159		00000159	
00000160		00000160		00000160		00000160	
00000161		00000161		00000161		00000161	
00000162		00000162		00000162		00000162	
00000163		00000163		00000163		00000163	
00000164		00000164		00000164		00000164	
00000165		00000165		00000165		00000165	
00000166		00000166		00000166		00000166	
00000167		00000167		00000167		00000167	
00000168		00000168		00000168		00000168	
00000169		00000169		00000169		00000169	
00000170		00000170		00000170		00000170	
00000171		00000171		00000171		00000171	
00000172		00000172		00000172		00000172	
00000173		00000173		00000173		00000173	
00000174		00000174		00000174		00000174	
00000175		00000175		00000175		00000175	
00000176		00000176		00000176		00000176	
00000177		00000177		00000177		00000177	
00000178		00000178		00000178		00000178	
00000179		00000179		00000179		00000179	
00000180		00000180		00000180		00000180	
00000181		00000181		00000181		00000181	
00000182		00000182		00000182		00000182	
00000183		00000183		00000183		00000183	
00000184		00000184		00000184		00000184	
00000185		00000185		00000185		00000185	
00000186		00000186		00000186		00000186	
00000187		00000187		00000187		00000187	
00000188		00000188		00000188		00000188	
00000189		00000189		00000189		00000189	
00000190		00000190		00000190		00000190	
00000191		00000191		00000191		00000191	
00000192		00000192		00000192		00000192	
00000193		00000193		00000193		000001	

P R O G R A M M O D E

NOTEN

M0D0

M0D1

PRINTER

134	01 00069	22800000	A	LI,RO	0
135	01 0006A	35800150		STW,RO	BUF1
136	01 0006B	35800155		STW,RO	SET2
137	01 0006C	22800001	A	LI,RO	1
138	01 0006D	35800154		STW,RO	SET
139	01 0006E	32800001	N	LW,RO	BUFF+1
140	01 0006F	3580014E		STW,RO	TIIM
141	01 00070	21D00013	A	CI,R5	19
142	01 00071	692000E8		BCS,2	F9XD
143	01 00072	22E00000	A	LI,R6	0
144	01 00073	31E00152		CK,R6	M0DE
145	01 00074	68300078		BCR,3	M0D0
146	01 00075	21D0000A	A	CI,R5	10
147	01 00076	69100088		BCS,1	M0D1
148	01 00077	68200130		B	RESET
149	01 00078	3280014E		LW,RO	TIIM
150	01 00079	31800001	N	CK,RO	BUFF+1
151	01 0007A	6830007D		BCR,3	\$+3
152	01 0007B	22800001	A	LI,RO	1
153	01 0007C	35800152		STW,RO	M0DE
154	01 0007D	21D00000	A	CI,R5	0
155	01 0007E	69300080		BCS,3	PRINT
156	01 0007F	31D00155		CK,R5	SET2
157	01 00080	6930008D		BCS,3	PRINT
158	01 00081	35800151		STW,R5	BUF2
159	01 00082	35800154		STW,R5	SET
160	01 00083	22800001	A	LI,RO	1
161	01 00084	35800155		STW,RO	SET2
162	01 00085	32800051	N	LW,RO	BUFF+31
163	01 00086	3580014E		STW,RO	TIIM
164	01 00087	6800008D		B	PRINT
165	01 00088	3280014E		LW,RO	TIIM
166	01 00089	31800051	N	CK,RO	BUFF+81
167	01 0008A	68300080		BCR,3	PRINT
168	01 0008B	22800000	A	LI,RO	0
169	01 0008C	35800152		STW,RO	M0DE
170	01 0008D	32E00153		LW,R6	BPTR

P R G R A M M O D E

171	01 0002E	21E00000	A	CI,R6	0	NEWB
172	01 0008F	68300093		BCR,3	1	
173	01 00070	20E00001	A	AI,R6	*R6	
174	01 00091	R1F0000E	A	CW,R7	DEL	
175	01 00092	6830009C		BCR,3	R5	
176	01 00093	32C0000D	A	LW,R5	1+2	
177	01 00094	68100096		BCR,1	20	
178	01 00095	20D00014	A	AI,R5	3	
179	01 00096	25D00003	A	SLS,R5	BUFF	
180	01 00097	22E00000	N	LI,R6	R5	
181	01 00098	32E00000	A	AK,R6	BPTR	
182	01 00099	35E00153		STM,R6	0	
183	01 0009A	22E00000	A	LI,R6	DFLG	
184	01 0009B	35E00156		STM,R6	0	
185	01 0009C	22C00000	A	LI,R5	DFLG	
186	01 0009D	31C00156		CW,R5	ADD	
187	01 0009E	69300008		BCS,3	APXPRED	
188	01 0009F	32F00000	X	LW,R7	APXC	
189	01 000A0	35F00000	X	STM,R7	APYPRED	
190	01 000A1	32B00000	X	LW,R3	APYC	
191	01 000A2	35B00000	X	STM,R3	BPTR	
192	01 000A3	32E00153		LW,R6	1	
193	01 000A4	20E00001	A	AI,R6	*R6	
194	01 000A5	B290000E	A	LW,R0	APCTSEC	
195	01 000A6	35800000	X	STM,R0	1	
196	01 000A7	20E00001	A	AI,R6	*R6	
197	01 000A8	B2C0000E	A	LW,R5	APXPRED	
198	01 000A9	35D00000	X	STM,R5	1	
199	01 000AA	20E00001	A	AI,R6	*R6	
200	01 000AR	B2A0000E	A	LW,R2	APYPRED	
201	01 000AC	35A00000	X	STM,R2	R3	
202	01 000AD	35A0000B	A	SW,R2	1	
203	01 000AE	20E00001	A	AI,R6	*R6	
204	01 000AF	B280000E	A	LW,R0	=X'FFFF'	
205	01 000B0	31E00163		CW,R0	ENND	
206	01 000B1	63300144		BCR,3	APXD8T	
207	01 000B2	35E00000	X	STM,R0		

PROGRAM MODE

```

EOO 0: 208 01 00023 20800001 A
      209 01 00024 R280000E A
      210 01 00025 35800000 X
      211 01 00026 3400000F A
      212 01 00027 32000000 A
      213 01 00028 6320002B A
      214 01 00029 2000000A A
      215 01 00030 6200000E C
      216 01 00031 200FFFFF6 A
      217 01 00032 34000015B
      218 01 00033 350000158
      219 01 00034 32900000A A
      220 01 00035 6420000C2
      221 01 00036 21900000A A
      222 01 00037 6300000C3
      223 01 00038 209FFFFF6 A
      224 01 00039 36900015B
      225 01 00040 359000159
      226 01 00041 229000001 A
      227 01 00042 359000156
      228 01 00043 64100000 X
      229 01 00044 325000158
      230 01 00045 66000000 X
      231 01 00046 320000159
      232 01 00047 66000000 X
      233 01 00048 63000000 A
      234 01 00049 25800017C A
      235 01 00050 259000064 A
      236 01 00051 228000005 A
      237 01 00052 25800017C A
      238 01 00053 259000064 A
      239 01 00054 23900000A A
      240 01 00055 308000009 A
      241 01 00056 25200017C A
      242 01 00057 259000064 A
      243 01 00058 320000009 A
      244 01 00059 25300017C A

      ADD
      EXIT
      CBNVT
      AI,R0
      LW,R0
      ST,R0
      SW,R5
      LW,R5
      BCR,2
      AI,R5
      B
      AI,R5
      DW,R5
      ST,R5
      LW,R1
      BCR,2
      AI,R1
      B
      AI,R1
      DW,R1
      ST,R1
      LI,R1
      ST,R1
      BAL,X1
      LW,R5
      ANX,R5
      LW,R5
      ANX,R5
      B
      SLD,RQ
      SLS,R1
      LW,R3
      SLD,R0
      SLS,R1
      MI,R1
      AN,R3
      SLD,R0
      SLS,R1
      LW,R5
      SLD,R0
      1
      *R6
      APYD0T
      R7
      R5
      $+3
      10
      $+2
      -10
      TWENTY
      DELTAX
      R2
      $+3
      10
      $+2
      -10
      TWENTY
      DELTAY
      1
      DFLG
      ADDX
      DELTAX
      APXC
      DELTAY
      APYC
      0,X6
      -4
      -28
      R1
      -4
      -28
      10
      R1
      -4
      -28
      R1
      -4

```

```

245 01 00008 A
246 01 00009 A
247 01 0000A A
248 01 0000B A
249 01 0000C A
250 01 0000D A
251 01 0000E A
252 01 0000F A
253 01 0000G A
254 01 0000H A
255 01 0000I A
256 01 0000J A
257 01 0000K A
258 01 0000L A
259 01 0000M A
260 01 0000N A
261 01 0000O A
262 01 0000P A
263 01 0000Q A
264 01 0000R A
265 01 0000S A
266 01 0000T A
267 01 0000U A
268 01 0000V A
269 01 0000W A
270 01 0000X A
271 01 0000Y A
272 01 0000Z A
273 01 0000A A
274 01 0000B A
275 01 0000C A
276 01 0000D A
277 01 0000E A
278 01 0000F A
279 01 0000G A
280 01 0000H A
281 01 0000I A

```

```

P R O G R A M M O D E
SLS,R1 -28
MI,R1 10
AW,R5 R1
MI,R5 60
AW,R5 R5
SLD,R0 -4
SLS,R1 -28
LW,R5 R1
SLD,R0 -4
SLS,R1 -28
MI,R1 10
AW,R5 R1
MI,R5 3600
AW,R5 R5
LW,R0 R3
B 0,X4
LW,R0 R5
AW,R0 BUFF+1
CW,R0 FINTIME
BCS,1 CLEAR
LW,R5 FINTIME
SW,R5 BUFF+1
BCS,2 #+2
B MARKTIM
LI,R0 1
STW,R0 FLAG
DW,R5 TEN
LI,X3 0
B I9S
LI,R0 0
STW,R0 FLAG
DW,R5 TEN
LI,X3 0
LI,R1 0
CW,R1 MODE
BCR,3 ZERM
AI,P5 -1

```

F8WD

CLEAR

EOO

E-:

232	01 000FD	680000FF	A	ZEMM
233	01 000FE	200FFFE	A	
234	01 000FF	21000000	A	
235	01 00100	68000130		
236	01 00101	68000124		
237	01 00102	210FFFE5	A	BACK
238	01 00103	69200088		
239	01 00104	32800000	A	
240	01 00105	30800001	N	
241	01 00106	31800150		
242	01 00107	63100116		
243	01 00108	22800001	A	
244	01 00109	3580015E		
245	01 0010A	32000001	N	
246	01 0010B	38000150		
247	01 0010C	3600015A		
248	01 0010D	21000000	A	
249	01 0010E	63000147		
250	01 0010F	32800152		
251	01 00110	21800000	A	
252	01 00111	63000114		
253	01 00112	20000003	A	
254	01 00113	68000124		
255	01 00114	20000002	A	
256	01 00115	63000124		
257	01 00116	22800000	A	KLEAR
258	01 00117	3580015E		
259	01 00118	3800015A		
260	01 00119	3600015A		
261	01 0011A	22800001	A	
262	01 0011B	38000000	A	
263	01 0011C	22800000	A	
264	01 0011D	31800152		
265	01 0011E	63000121		
266	01 0011F	20000002	A	
267	01 00120	63000122		
268	01 00121	20000003	A	ZER

P R O G R A M M O D E

19

B	AI,R5	\$+2
	CI,R5	-2
	BCR,3	0
	B	RESET
		18S
	CI,R5	-11
	BCS,2	MOD1
	LW,R0	R5
	AW,R0	BUFF+1
	CW,R0	INITIME
	BCR,1	KLEAR
	LI,R0	1
	ST,R0	FLAG
	LW,R5	BUFF+1
	SW,R5	INITIME
	DW,R5	TEN
	CI,R5	0
	BCR,3	MARKTIM
	LW,R0	MODE
	CI,R0	0
	BCR,3	\$+3
	AI,R5	3
	B	10S
	AI,R5	2
	B	18S
	LI,R0	0
	ST,R0	FLAG
	LW,R5	R5
	DW,R5	TEN
	LI,X3	1
	LW,R5	R5
	LI,R1	0
	CW,R1	MODE
	BCR,3	ZER
	AI,R5	2
	B	\$+2
	AI,R5	3

E00	O :	E-		P R O G R A M	M O D E
319	01 00122		21000000 A	CI,R5	
320	01 00123		68300130	BCR,3	RESET
321	01 00124			RES	0
322	01 00124		22800001 A	LI,R0	1
323	01 00125		3180015E	CW,R0	FLAG
324	01 00126		58300140	BCR,3	CKZER0
325	01 00127		21300000 A	CI,X3	0
326	01 00128		6330012C	BCR,3	FD-1
327	01 00129		39900017 02	STW,R5	BFPT+2
328	01 0012A		04100015 02	N:PREC0RD	F:8,(N,1),(REV)
	02 00015		10000000 N		
			88000010		
329	02 00017		00000001 A	B	REED
330	01 00128		6300012E	STW,R5	FFPT-2
331	01 0012D		3500001A 02	M:PREC0RD	F:8,(N,1),(FWD)
	02 00018		04100018 02		
			15000000 N		
			80000000		
			00050001 A		
332	01 0012E			RES	0
333	01 0012E		04100018 02	M:READ	F:8,(BUF,BUFF-1),(SIZE,328),(WAIT)
	02 00018		10000000 N		
			30000010		
	02 0001D		0001FFFF N		
	02 0001E		02000148 A		
334	01 0012F		0410001F 02	M:READ	F:8,(BUF,BUFF+79),(SIZE,328),(WAIT)
	02 0001F		10000000 N		
			30000010		
			0000004F N		
	02 00021		00000148 A		
335	01 00130		22800000 A	LI,R3	0
336	01 00131		35800152	STW,R3	MODE
337	01 00132		35800156	STW,R3	DFLG
338	01 00133		35800159	STW,R3	BPTR
339	01 00134		35800154	STW,R3	SET
340	01 00135		20300001 A	AI,R3	1
341	01 00136		35800155	STW,R3	SET2

P R O G R A M M O D E

```

EOO 0: 342 01 00137 35800150 STN,R3 BUF1
343 01 00138 35800151 STN,R3 BUF2
344 01 00139 32800001 N LW,RO BUFF+1
345 01 0013A 3580014E STN,RO TIIM
346 01 0013B 32800002 N LW,RO BUFF+2
347 01 0013C 32900003 N LW,R1 BUFF+3
348 01 0013D 35800000 X STN,RO APXPRED
349 01 0013E 35900000 X STN,R1 APYPRED
350 01 0013F 680C0000 A B 0,X6
351 01 00140 22800000 A CKZER0
352 01 00141 3180000D A LI,RO 0
353 01 00142 69200127 CW,RO R5
354 01 00143 68000147 BCS,3 10SS
355 01 00144 ENND RES 0 MARKTIM
356 01 00144 22800001 A LI,RO 1
357 01 00145 35800150 STN,RO BUF1
358 01 00146 35800151 STN,RO BUF2
359 01 00147 MARKTIM RES 0
360 01 00147 32800001 N LW,RO BUFF+1
361 01 00148 35800000 X STN,RO APCTSEC
362 01 00149 32800002 N LW,RO BUFF+2
363 01 0014A 32900003 N LW,R1 BUFF+3
364 01 0014B 35800000 X STN,RO APXC
365 01 0014C 35900000 X STN,R1 APYC
366 01 0014D 680C0000 A B 0,X6
367 01 0014E 00000000 A TIIM 0
368 01 0014F 00000001 A COUNT 1
369 01 00150 00000000 A BUF1 0
370 01 00151 00000000 A BUF2 0
371 01 00152 00000000 A MODE 0
372 01 00153 00000000 A GPR 0
373 01 00154 00000000 A SET 0
374 01 00155 00000001 A SET2 1
375 01 00156 00000000 A DFLG 0
376 01 00157 00000000 A SAVE 0
377 01 00158 00000000 A DELTAX 0
378 01 00159 00000000 A DELTAY 0

```

ECO	O :	E-		DATA	P R O G R A M	M O D E
379	01	0015A	0000000A A	TEN	10	
380	01	0015B	00000014 A	TWENTY	20	
381	01	0015C	00000000 A	INITIME	0	
382	01	0015D	00000000 A	FINIME	0	
383	01	0015E	00000000 A	FLAG	0	
384				END		
	01	0015F	00000200 A			
	01	00160	00040000 A			
	01	00161	00100000 A			
	01	00162	00080000 A			
	01	00163	0000FFFF A			

CONTROL SECTION SUMMARY: 01 00164 PT 0 02 00023 PT 0

P R O G R A M M O D E

E00 * O : E -
SYMBOL VALUES

ADD/01 000C3	BACK/01 00102	BAK/01 0012A
BFPT/02 00015	BUF1/01 00150	SUF2/01 00151
CKIP9S/01 00013	CKZER9/01 00140	CK2/01 0004A
CLEAR/01 000F5	COUNT/01 0014F	DEL/01 0009C
DELTA/01 00158	DELTA/01 00159	END/01 0005D
ENNC/01 00144	EXIT/01 000CC	FBRH/0000000
FD/01 0012D	FFPT/02 00018	FINTIME/01 0015D
FLAG/01 0015F	FOR3/01 000E8	INITIME/01 0015C
INITRES/01 00019	IRFLG/01 00042	I0SS/01 00127
IPFLG/01 00043	KLEAK/01 00116	MODE/01 00152
M000/01 00078	M001/01 00088	N00P/01 00060
N0TEN/01 00070	PRINTER/01 0008D	RESET/01 00130
R0/00000008	R1/00000009	R3/0000000B
R4/0000000C	R5/0000000D	R7/0000000F
SAVE/01 00157	SET/01 00154	SUBT/01 00056
TEN/01 0015A	TEST/01 00034	TIMOUT/01 0005E
TWENTY/01 0015B	X1/00000001	X3/00000003
X4/00000004	X5/00000005	X7/00000007
ZER/01 00121	ZERN/01 000FE	

* EXTERNAL DEFINITIONS

* APPRED/01 00000

* PRIMARY REFERENCES

ADDX	AIXSAMP	ANTI	APCTSEC	APDIBIAS	API0
APPREDZ	APSTAT2	APXC	APXD09T	APXENC	APXPRED
APYC	APYD0T	APYPRED	BUFF	F:8	F:9

* NO SFCANDARY REFERENCES

* NO UNDEFINED SYMBOLS

* ERROR SEVERITY LEVEL: 0

* NO ERROR LINES

EOO 0 : < E- 00000002

SYSTEM ANTENNA
SYSTEM SIG5FP

LEVEL 1 DISPLAY OF COMMAND WOLF

```
*****
*
* WW WW 00000 LL FFFFFFFF RRRRRR 000000
* WW W WW 00 LL FF 00 DD
* WW XNW WW 00 LL FF 00 DD
* WWWXWWW 00 LL FF 00 DD
* WW WW 00 LL FF 00 DD
* WW WW 00000 LLLLLL FF 00 DD
*
*
* SYSTEMS TECHNOLOGY DEPT.
* SPACE SYSTEMS GROUP
*****
```

ENDLEVEL 1 DISPLAY OF COMMAND WOLF

LEVEL 1 DISPLAY OF COMMAND REGNAME

```
00000001 x1 SET
00000002 x2 SET
00000003 x3 SET
00000004 x4 SET
00000005 x5 SET
00000006 x6 SET
00000007 x7 SET
00000008 x8 SET
00000009 x9 SET
0000000A x10 SET
0000000B x11 SET
0000000C x12 SET
0000000D x13 SET
0000000E x14 SET
0000000F x15 SET
```

ALL X REGISTERS ARE INDEX REGISTERS

ALL R REGISTERS ARE GENERAL USE REGISTERS

ECO 0 : < E- 00000000 FBKH SET 13 APDISPLY
20 0000000F FBR SET 15 F0RTRAN IV-H BRANCH REGISTER
81 ***** 1CISPLAY 0F C0MMAND REGNAME F0RTRAN IV BRANCH REGISTER
***** 5 TITLE 'APDISPLY'

80	< 01 00013	35800000 X	APMNP08	STW,RO	APDISPLY
81	01 00014	35800000 X		STW,RO	APYC
82	01 00015	60020000 A		B	APYTF4IN
83	01 00016	32800000 X		LW,RO	O,X1
84	01 00017	3A900000 X		LX,R1	APXSLAV
85	01 00018	35800000 X		STW,RO	APYSLAV
86	01 00019	35900000 X		STW,R1	APXTF4IN
87	01 0001A	60020000 A		B	APYTF4IN
88	01 0001B	FF000000 A	MASK1	DATA	O,X1
89	01 0001C	00007FFF A	MASK2	DATA	X'FF000000'
90	01 0001D	32800000 X	APSBUT	LW,RO	X'00007FFF'
91	01 0001E	32900000 X		LW,R1	APXSQUT
92	01 0001F	4880001C		AND,RQ	AIXSERV8
93	01 00020	4890001B		AND,R1	MASK2
94	01 00021	30200009 A		AW,RO	MASK1
95	01 00022	35200000 X		STW,RO	R1
96	01 00023	32800000 X		LW,RO	AIXSERV8
97	01 00024	32900000 X		LW,R1	APYSQUT
98	01 00025	4880001C		LW,R1	AIXSERV8
99	01 00026	4890001B		AND,RO	MASK2
100	01 00027	30800009 A		AND,R1	MASK1
101	01 00028	35800000 X		AW,RO	R1
102	01 00029	68020000 A		STW,RO	AIXSERV8
103	01 0002A	32800000 X	APSA9UT	B	O,X1
104	01 0002B	35100004 A		LW,RO	APXTF4IN
105	01 0002C	22300008 A		STW,X1	X4
106	01 0002D	6A100000 X		LI,X3	8
107	01 0002E	32900000 X		BAL,X1	LIMTEST
108	01 0002F	4880001C		LW,R1	AIXSAMP
109	01 00030	4890001B		AND,RQ	MASK2
110	01 00031	30800009 A		AND,R1	MASK1
111	01 00032	35800000 X		AW,RO	R1
112	01 00033	32800000 X		STW,RO	AIXSAMP
113	01 00034	6A100000 X		LW,RO	APYTF4IN
114	01 00035	35400001 A		BAL,X1	LIMTEST
115	01 00036	32900000 X		STW,X4	X1
116	01 00037	4880001C		LX,R1	AIXSAMP
				AND,RO	MASK2

```

EOO      0: < E-
117      01 00038      43900001B      AND,R1      MASK1      APDISPLY
118      01 00039      30800009 A      AM,R0      R1
119      01 0003A      35800000 X      STN,R0      AIYSAMP
120      01 0003B      68020000 A      B      O,X1
121      01 0003C      22800000 A      LI,R0      O
122      01 0003D      35800000 X      STN,R0      APXC
123      01 0003E      35800000 X      STN,R0      APYC
124      01 0003F      68020000 A      B      O,X1
125      01 00040      32000001 A      LW,R4      X1
126      01 00041      22910000 A      LI,R1      X'10000'
127      01 00042      44900000 X      AND,R1      APSTAT2
128      01 00043      69200004E      BCS,2      AUG
129      01 00044      22920000 A      LI,R1      X'20000'
130      01 00045      48900000 X      AND,R1      APSTAT2
131      01 00046      68300004A      BCR,3      N8SCAN
132      01 00047      6A200000 X      BAL,X2      APRSCAN
133      01 00048      22200000 A      LI,X2      O
134      01 00049      68000004E      B      AUG
135      01 0004A      22900000 A      LI,R1      O
136      01 0004B      35900000 X      STN,R1      APXSCAN
137      01 0004C      35900000 X      STN,R1      APYSCAN
138      01 0004D      35900000 X      STN,R1      TEE
139      01 0004E      22900000 A      LI,R1      X'800'
140      01 0004F      44900000 X      AND,R1      APSTAT2
141      01 00050      683000054      BCR,3      ZERO
142      01 00051      6A200000 X      BAL,X2      APXAGMNT
143      01 00052      22200000 A      LI,X2      O
144      01 00053      68000005B      B      CBN
145      01 00054      22800000 A      LI,R0      O
146      01 00055      35800000 X      STN,R0      APXAUG
147      01 00056      35800000 X      STN,R0      APYAUG
148      01 00057      358000004 N      STN,R0      APXLFFIN+4
149      01 00058      358000005 N      STN,R0      APXLFFIN+5
150      01 00059      358000004 N      STN,R0      APXINTIN+4
151      01 0005A      358000005 N      STN,R0      APXINTIN+5
152      01 0005B      223000006 A      LI,X3      6
153      01 0005C      32800000 X      LW,R0      APXC

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[illegible]

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E00 0: < E-
186 01 00082 35800000 X STORX APDISPLY
187 01 00083 32900000 X APXC
188 01 00084 33800009 A APXENC
189 01 00085 32900008 A R1
190 01 00086 2390000A A RO
191 01 00087 32800009 A 10
192 01 00088 22300008 A R1
193 01 00089 6A100000 X 8
194 01 0008A 35800000 X LIMTEST
195 01 0008B 22300006 A APXTF4IN
196 01 0008C 32800000 X 6
197 01 0008D 33800000 X APYC
198 01 0008E 32800000 X APYAUG
199 01 0008F 6A100000 X APYSCAN
200 01 00090 30900008 A LIMTEST
201 01 00091 21903332 A RO
202 01 00092 69100098 A 13106
203 01 00093 21803332 A YLIM3FF
204 01 00094 32A00000 X 13106
205 01 00095 49A00135 A AIM6D9UT
206 01 00096 35A00000 X =X'00100000'
207 01 00097 68000090 A AIM6D9UT
208 01 00098 32A00000 X STORY
209 01 00099 48A00136 A AIM6D9UT
210 01 0009A 35A00000 X =X'FFFFFFF'
211 01 0009B 35800000 X AIM6D9UT
212 01 0009C 32900000 X APYC
213 01 0009D 33800009 A APYENC
214 01 0009E 32900008 A R1
215 01 0009F 239FFFF6 A RO
216 01 000A0 32800009 A -10
217 01 000A1 22300008 A R1
218 01 000A2 6A100000 X 8
219 01 000A3 35800000 X LIMTEST
220 01 000A4 E500000C A APXTF4IN
221 01 000A5 22500000 A *R4
222 01 000A6 32800000 X 0
APSTSEC

```

E00

0 : < E-
 223 01 000A7
 224 01 000A8
 225 01 000A9
 226 01 000AA
 227 01 000AB
 228 01 000AC
 229 01 000AD
 230 01 000AE
 231 01 000AF
 232 01 000AO
 233 01 000A1
 234 01 000A2
 235 01 000A3
 236 01 000A4
 237 01 000A5
 238 01 000A6
 239 01 000A7
 240 01 000A8
 241 01 000A9
 242 01 000AA
 243 01 000AB
 244 01 000AC
 245 01 000AD
 246 01 000AE
 247 01 000AF
 248 01 000AO
 249 01 000A1
 250 01 000A2
 251 01 000A3
 252 01 000A4
 253 01 000A5
 254 01 000A6
 255 01 000A7
 256 01 000A8
 257 01 000A9
 258 01 000AA
 259 01 000AB

3180011B
 6330011A
 3580011B
 3580011B
 32400000 X
 683000AF
 25400060 A
 36400137
 35400000 X
 22400000 A
 32500005 A
 633000R4
 36400137
 25500010 A
 25400170 A
 6A700052
 620000C4
 32940000 X
 22800000 A
 36900132
 208000F0 A
 209000F0 A
 25900008 A
 30800009 A
 32A00008 A
 25A0017C A
 25A0007C A
 25A0017C A
 680E0000 A
 22400000 A
 26400110 A
 35400000 X
 25400110 A
 32500008 A
 25400170 A
 6A700028
 25A00108 A

APDISPTC

APDISP2

CW,RO
 BCR,3
 STW,RO
 STN,RO
 LW,X4
 BEZ
 SLD,X4
 DW,X4
 ST,X4
 LI,X4
 LW,X5
 BEZ
 DW,X4
 SLS,X5
 SLD,X4
 BAL,X7
 B
 LW,R1
 LI,RO
 DW,RO
 AI,RO
 AI,R1
 SLS,R1
 AW,RO
 LW,R2
 SLD,R2
 SLS,R2
 SLD,R2
 B
 LI,X4
 SLD,X4
 STW,X4
 SLD,X4
 LW,X5
 SLD,X4
 BAL,X7
 SLD,R2

APDISPLY

CFLG
 BUT
 CFLG
 CFLG
 APCISEC,X2
 \$+3
 -32
 L(60)
 APDISPWK,X2
 O
 X5
 \$+2
 L(50)
 16
 -16
 APDISPTC
 APDISP2
 APDISPWK,X2
 O
 L(10)
 X'FC'
 X'FC'
 8
 R1
 RO
 -4
 -4
 -4
 C,X7
 O
 16
 APDISPWK,X2
 16
 R3
 -16
 APDISPTC
 8

LOAD COMMAND TIME IN SECONDS

SHIFT FOR 64-BIT DIVIDEND
 DIVIDE BY 60 TO GET MINUTES
 STORE REMAINING SECONDS IN MEM.

DIVIDE MIN BY 60 TO GET HRS
 HOLD REMAINING MIN AND HRS IN
 X5 - IN FORM -XXXXMINXXHRS
 CALL BIN TO EBDIC FOR SECONDS

ROUTINE TO CONVERT TIME ELEMENTS
 TO BCD AND PACK INTO 4-BIT BCD
 CHARACTERS

PACK INTO 4-BIT BCD IN R3
 (2 CHAR)

STORE MIN IN MEM.

HOLD CONV. SEC IN H2 OF X5
 HOLD BIN. HRS IN H1 OF X5
 CALL ROUTINE TO CONV MIN

EOO	0	:	<	E		LI,X4	AFDISPLY	
260	01	0000C			22400000 A	LI,X4	0	
261	01	0000C			25400110 A	SLD,X4	16	STORE HRS IN MEM.
262	01	0000E			35400000 X	ST,X4	APDISPWK,X2	
263	01	0000F			32400000 A	LW,X4	R2	
264	01	0000D			25400178 A	SLD,X4	-8	HOLD BCD MIN/SEC IN X5 (H1)
265	01	00001			6A700008	BAL,X7	APDISPTC	CALL ROUTINE TO CONV HRS
266	01	00002			25A00108 A	SLD,R2	8	
267	01	00003			32400000 A	LW,X4	K2	STORE BCD CHAR IN DISPLAY
268	01	00004			25400178 A	SLD,X4	-8	
269	01	00005			32700005 A	LW,X7	X5	
270	01	00006			32400000 X	LW,X4	AICTDSP1,X2	INTERFACE ADDRESS WGRDS
271	01	00007			25400068 A	SLS,X4	-24	(RETAINING ADDRESSES)
272	01	00008			25400118 A	SLD,X4	24	
273	01	00009			35400000 X	STW,X4	AICTDSP1,X2	
274	01	0000A			48400139	AND,X4	=X'00FFFFFF'	
275	01	0000B			32800001 N	LW,R0	AICTDSP1+1	
276	01	0000C			48200018	AND,R0	MASK1	
277	01	0000D			30800004 A	AW,R0	X4	
278	01	0000E			35800001 N	STW,R0	AICTDSP1+1	
279	01	0000F			32840000 X	LW,R0	APXC,X2	
280	01	0000D			32700001 A	LW,X7	X1	(STORE X1 REGISTER)
281	01	00001			6A10011C	BAL,X1	AP@4BCD	CONVERT APXC TO 4BCD F9R
282	01	00002			02000000 A	NBP		COMMAND-X DISPLAY
283	01	00003			25800008 A	SLS,R0	8	
284	01	00004			32800008 A	LW,R3	R0	
285	01	00005			32A40000 X	LW,R2	AIXCDSP1,X2	
286	01	00006			25A00068 A	SLS,R2	-24	
287	01	00007			25A00118 A	SLD,R2	24	
288	01	00008			35A40000 X	STW,R2	AIXCDSP1,X2	STORE BCD CHAR IN DISPLAY1
289	01	00009			48A00139	AND,R2	=X'00FFFFFF'	INTERFACE ADDRESS WGRD
290	01	0000A			32200001 N	LW,R0	AIXCDSP1+1	
291	01	0000B			48800018	AND,R0	MASK1	
292	01	0000C			30800000 A	AW,R0	R2	
293	01	0000D			35800001 N	STW,R0	AIXCDSP1+1	
294	01	0000E			32840000 X	LW,R0	APYC,X2	
295	01	0000F			6A10011C	BAL,X1	AP@4BCD	CONVERT APYC TO 4BCD F9R
296	01	0000D			02000000 A	NBP		COMMAND-Y DISPLAY

```

E00      0: < E-
297      01 000F1      25800008 A      SLS,R0      APDISPLY
298      01 000F2      32800008 A      LW,R3
299      01 000F3      32A40000 X      LW,R2      AIYCDSP1,X2
300      01 000F4      25A00068 A      SLS,R2      -24
301      01 000F5      25A00118 A      SLD,R2      24
302      01 000F6      35A40000 X      STA,R2      AIYCDSP1,X2
303      01 000F7      43A00139 A      AND,R2      =X'00FFFFFFF'
304      01 000F8      32800001 N      LW,R0      AIYCDSP1+1
305      01 000F9      43800018 A      AND,R0      MASK1
306      01 000FA      3020000A A      AW,R0      R2
307      01 000FB      35800001 N      STW,R0      AIYCDSP1+1
308      01 000FC      32840000 X      LW,R0      APXENC,X2
309      01 000FD      6A10011C A      BAL,X1      AP34BCD  CONVERT APXENC TO 4BCD FOR
310      01 000FE      02000000 A      N6P      REAL-X DISPLAY
311      01 000FF      25800008 A      SLS,R0
312      01 00100      32800008 A      LW,R3
313      01 00101      32A40000 X      LW,R2      AIYRDSP1,X2
314      01 00102      25A00068 A      SLS,R2      -24
315      01 00103      25A00118 A      SLD,R2      24
316      01 00104      35A40000 X      STW,R2      AIYRDSP1,X2
317      01 00105      43A00139 A      AND,R2      =X'00FFFFFFF'
318      01 00106      32800001 N      LW,R0      AIYRDSP1+1
319      01 00107      43800018 A      AND,R0      MASK1
320      01 00108      3080000A A      AW,R0      R2
321      01 00109      35800001 N      STW,R0      AIYRDSP1+1
322      01 0010A      32840000 X      LW,R0      APXENC,X2
323      01 0010B      6A10011C A      BAL,X1      AP34BCD  CONVERT APXENC TO 4BCD FOR
324      01 0010C      02000000 A      N6P      REAL-Y DISPLAY
325      01 0010D      25800008 A      SLS,R0
326      01 0010E      32800008 A      LW,R3
327      01 0010F      32A40000 X      LW,R2      AIYRDSP1,X2
328      01 00110      25A00068 A      SLS,R2      -24
329      01 00111      25A00118 A      SLD,R2      24
330      01 00112      35A40000 X      STA,R2      AIYRDSP1,X2
331      01 00113      43A00139 A      AND,R2      =X'00FFFFFFF'
332      01 00114      32800001 N      LW,R0      AIYRDSP1+1
333      01 00115      43800018 A      AND,R0      MASK1

STORE BCD CHAR IN DISPLAY1
INTERFACE ADDRESS WORD

STORE BCD CHAR IN DISPLAY1
INTERFACE ADDRESS WORD

STORE BCD CHAR IN DISPLAY1
INTERFACE ADDRESS WORD

```

334	01 00116	3380000A A	AW,RO	APDISPLY	
335	01 00117	35200001 N	STM,RO	R2	
336	01 00118	32100007 A	LW,X1	AIYRDSPI+1	
337	01 00119	68020001 A	B	X7	RESTORE X1 REGISTER
338	01 0011A	68020000 A	B	1,X1	RETURN
339	01 0011B	00000000 A	DATA	0	
340			TITLE	'AP04BCD'	

```

E00 0: < E-
341 01 0011C 30000008 A AP04BCD DEF AP04BCD
342 01 0011D 37A0013A A AP04BCD LAX,R3
343 01 0011E 25A00001 A AP04BCD MW,R2
344 01 0011F 36A0013B A AP04BCD DMR,R2
01 00120 21E00000 A
01 00121 69100123 A
01 00122 29600001 A
01 00123 25B0047F A
01 00124 22200005 A
01 00125 22A00000 A
01 00126 36A00138 A
01 00127 35A000CC A
01 00128 25C0017C A
01 00129 64200125 A
01 0012A 22C00001 A
01 0012B 21800000 A
01 0012C 6810012E A
01 0012D 22C00000 A
01 0012E 25C00174 A
01 0012F 35D00006 A
01 00130 69020000 A

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01 00132 00000064 A
01 00133 00200000 A
01 00134 F0000000 A
01 00135 00100000 A
01 00136 F0000000 A
01 00137 0000003C A
01 00138 0000000A A
01 00139 00000000 A
01 0013A 00018000 A
01 0013B 00003000 A

MAX OF 5 DIGITS.
CLEAR REMAINDER TRAP.
DIVIDE BY 10
STORE REMAINDER
SAVE LOW ORDER 4 BITS.

CHECK FOR NEGATIVE SIGN.

RIGHT ADJUST SIGNED RESULT.
STORE RESULT IN R0
RETURN.

```

CONTROL SECTION SUMMARY: 01 0013C PT 0 02 00000 PT 0

EOO 0 : < E-
* SYMREL VALUES

A/00000001
B/00000000
FRRH/00000000
MASK2/01 0001C
R1/00000000
R5/00000000
STORY/01 0009B
X3/00000003
X7/00000007

* EXTERNAL DEFINITIONS

AP24BCC/01 0011C
APRSLAV/01 0000F
APSEC/01 00040

* PRIMARY REFERENCES

AICTDSP1 AIMDELT
AIYCDSP1 AIYRDSPI
APDIACHX APDIACHY
APYENC APXINTIN
APXTF4IN APXTF5IN
APYJ0Y APYSCAM
APYTRACK LIMTEST

* N9 SECONDARY REFERENCES
* N9 UNDEFINED SYMBOLS
* ERROR SEVERITY LEVEL: 0
* N9 ERROR LINES

APDISPITC/01 000B8
CFLG/01 0011B
HLSCAN/01 00041
N9SCAN/01 0004A
R2/0000000A
R6/0000000E
XLIMOFF/01 0007F
X4/00000004
YLIMOFF/01 00038

APDISPLY/01 000A5
APFST0/01 0003C
APSOUT/01 0001D

AISTAT3
AIYSAMP
APRSCAN
APXJ0Y
APXTF6IN
APYSLAV
TEE

AP24HCD

APDISP2/01 000C4
C8N/01 0005B
LIM/01 00077
DUTT/01 0011A
R3/0000000B
R7/0000000F
X1/00000001
X5/00000005
ZER3/01 00054

APMNPUS/01 00016
APRIACH/01 00005
AUTOTRAK/01 0000A

AIXCDSP1 AIXRDSPI
AIYSERV0 AP0AGMNT
APSTAT2 APSTSEC
APXLFFIN APXSCAN
APXTRACK APYAUG
APYS0UT APYTF4IN

AUG/01 0004E
FBR/0000000F
MASK1/01 0001B
R0/00000000R
R4/0000000C
ST0RX/01 00082
X2/0000000C2
X5/000000006

APRJ0Y/01 00000
APSA0UT/01 0002A

AIXSAMP AIXSERV0
APCTSEC APDISPWK
APXAUG APXC
APXSLAV APXS0UT
APYC APYENC
APYTF5IN APYTF6IN


```
EOO 0 : + E- 00000000 FBRH SET APDCOMPS
80 0000000F FBR SET 13 F0RTRAN IV-H BRANCH REGISTER
81 10150000F REGNAME 15 F0RTRAN IV BRANCH REGISTER
**** ENDLEVEL 5 TITLE 'APDCOMPS'
```

APDCOMP5

HEADER

DEF	AP@AGMNT
REF	APXTRACK
REF	APXAUG
REF	APYTRACK
REF	APYLPFIN
REF	APYINTIN
REF	APYAUG
RES	0
	X2
LCN,RO	APXTRACK
STN,RO	APXLPFIN
LI,X5	0
BAL,X1	AP@LPF
LW,RO	APYTRACK
STN,RO	APYLPFIN
LI,X5	1
BAL,X1	AP@LPF
LW,RO	APXLPFIN+2
STN,RO	APXINTIN
LI,X5	0
BAL,X1	AP@INTG
LW,RO	APYLPFIN+2
STN,RO	APYINTIN
LI,X5	1
BAL,X1	AP@INTG
LX,RO	APXINTIN+2
STN,RO	APXAUG
LW,RO	APYINTIN+2
STN,RO	APYAUG
B	0,X6
REF	APRIACH
REF	AIMGDAUT
REF	APSOUT
DEF	APDCOMP5

EOO 0: + E-

6	01 00000	32600002 A
7	01 00000	34800000 X
8	01 00001	35800000 X
9	01 00002	22500000 A
10	01 00003	6A100000
11	01 00004	32800000 X
12	01 00005	35200000 X
13	01 00006	22500001 A
14	01 00007	6A100000
15	01 00008	32800000 X
16	01 00009	35600000 X
17	01 0000A	22500000 A
18	01 0000B	6A100001
19	01 0000C	32800002 N
20	01 0000D	35600000 X
21	01 0000E	22500001 A
22	01 0000F	6A100001
23	01 00010	32800002 N
24	01 00011	35600000 X
25	01 00012	32800000 X
26	01 00013	32800002 N
27	01 00014	35600000 X
28	01 00015	65000000 A
29	01 00016	
30	01 00017	
31	01 00018	
32	01 00019	
33	01 00020	
34	01 00021	
35	01 00022	
36	01 00023	
37	01 00024	
38	01 00025	
39	01 00026	
40	01 00027	
41	01 00028	
42	01 00029	

[illegible]

[illegible]

EOO	00	01 00054	32900002 N	OUT	LW,R1	APDC6MP5
117	01 00055	23900003 A			MI,R1	APXTF4IN+2
118	01 00056	22300002 A			LI,X3	3
119	01 00057	32800009 A			LW,RO	2
120	01 00058	6A100000 X			BAL,X1	R1
121	01 00059	35800000 X			STW,RO	LIMTEST
122	01 0005A	32900002 N			LW,R1	APXTF5IN
123	01 0005B	23900004 A			MI,R1	APYTF4IN+2
124	01 0005C	22300002 A			LI,X3	4
125	01 0005D	32800009 A			LW,RO	2
126	01 0005E	6A100000 X			BAL,X1	R1
127	01 0005F	35800000 X			STW,RO	LIMTEST
128	01 00060	68000000 A			B	APYTF5IN
129	01 00062	000001F4 A		TST1	B9UND	0,X6
130	01 00063	0000047E A			DATA	8
131	01 00064	00000000 A			DATA	500,1150
132	01 00065	00000000 A		SCAF	DATA	11
133	01 00066	00000000 A		TEN	DATA	10
134	01 00067	00000000 A		THOUS	DATA	1000
135				*		
136				*		
137				*		
138				*		
139	01 00067	32600001 A		APDC9MP5	LW,X6	X1
140	01 00068	22500001 A			LI,X5	1
141	01 00069	6A100002 N			BAL,X1	APDCIF5
142	01 0006A	32900002 N			LW,R1	APYTF5IN+2
143	01 0006B	23900005 A			MI,R1	981
144	01 0006C	25900001 A			DWR,R1	THOUS
145	01 0006D	36900006 A				
146	01 0006E	21900000 A				
147	01 0006F	69100071 A				
148	01 00070	20900001 A				
149	01 00071	2590007F A				
150	01 00072	35900002 N			STW,R1	APYTF5IN+2
151	01 00073	6A100000 X			BAL,X1	APRTACH
						TACHOMETER READ AND SUBTRACT

EOG		C : + E-		APDCOMPS		ERROR RETURN	
148	01	00074	02000000	A			
149							
150	01	00075	32900000	X	LW,R1	APXTF5IN	
151	01	00076	35900000	X	STW,R1	APXSOUT	
152							
153	01	00077	22500001	A	LI,X5	1	
154	01	00078	6A1000A7		BAL,X1	APSDCIF6	
155	01	00079	22300000	N	LI,X3	WA(APXTF5IN)	
156	01	0007A	22700000	N	LI,X7	WA(APXTF6IN)	
157	01	0007B	329E0003	A	LW,R1	3,X7	
158	01	0007C	23900038	A	MI,R1	900	
159	01	0007D	25900001	A	DWR,R1	THEUS	
160							
161	01	00084	30960003	A	AW,R1	3,X3	
162	01	00085	35900000	X	STW,R1	APXSOUT	
163	01	00085	22300000	A	LI,X3	0	
164							
165	01	00086	32890000	X	LW,RO	APXSOUT	
166	01	00087	6A100000	X	BAL,X1	LIMITEST	
167	01	00088	35800000	X	STW,RO	APXSOUT	
168	01	00089	6A100000	X	BAL,X1	APXSOUT	
169	01	0008A	32900000	X	LW,R1	APXTF4IN	
170	01	0008B	23900003	A	MI,R1	3	
171	01	0008C	2590007F	A	SLS,R1	-1	
172	01	0008D	35900000	X	STW,R1	APXTF4IN	
173	01	0008E	22900000	X	LW,R1	APYTF4IN	
174	01	0008F	23900003	A	MI,R1	3	
175	01	00090	2590007F	A	SLS,R1	-1	
176	01	00091	35900000	X	STW,R1	APYTF4IN	
177	01	00092	22300008	A	LI,X3	8	
178	01	00093	32800000	X	LW,RO	APXTF4IN	
179	01	00094	6A100000	X	BAL,X1	LIMITEST	
	01	00095	35800000	X	STW,RO	APXTF4IN	

SERVO OUTPUT

E00
C :
+ E-
' , '
180 01 00096 328C0000 X
181 01 00097 6A100000 X
182 01 00098 35300000 X
183 01 00099 6A100000 X
* *
184
185 01 0009A 680C0000 A
*
186
187
*
188

E00

0 : + E-

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AP@DCTF5

15

189	01 0009B	68020001	A	AP@DCTF1	DEF	AP@DCTF1
190	01 0009C	68020001	A	AP@DCTF2	DEF	AP@DCTF2
191	01 0009D	22300000	N	AP@DCTF4	DEF	AP@DCTF4
192	01 0009E	22700000	N		DEF	AP@DCTF5
193	01 0009F	30700005	A		DEF	AP@DCTF6
194	01 000A0	30300005	A		REF	AP@DCTF4A0
195	01 000A1	630000R5			REF	AP@DCTF5A0
196	01 000A2	22300000	N		REF	AP@DCTF6A0
197	01 000A3	22700000	N		REF	AP@DCTF4A0
198	01 000A4	30700005	A		REF	AP@DCTF5A0
199	01 000A5	30300005	A		REF	AP@DCTF6A0
200	01 000A6	630000R5			REF	AP@DCTF4A0
201	01 000A7	22300000	N		REF	AP@DCTF5A0
202	01 000A8	22700000	N		REF	AP@DCTF6A0
203	01 000A9	30700005	A		REF	AP@DCTF4A0
204	01 000AA	30300005	A		REF	AP@DCTF5A0
205	01 000AB	630000R5			REF	AP@DCTF6A0
206	01 000AC	22300000	N		REF	AP@DCTF4A0
207	01 000AD	22700000	N		REF	AP@DCTF5A0
208	01 000AE	30700005	A		REF	AP@DCTF6A0
209	01 000AF	30300005	A		REF	AP@DCTF4A0
210	01 000B0	630000R5			REF	AP@DCTF5A0
211	01 000B1	22300000	N		REF	AP@DCTF6A0
212	01 000B2	22700000	N		REF	AP@DCTF4A0
213	01 000B3	30700005	A		REF	AP@DCTF5A0
214	01 000B4	30300005	A		REF	AP@DCTF6A0
215	01 000B5	630000R5			REF	AP@DCTF4A0
216	01 000B6	22300000	N		REF	AP@DCTF5A0
217	01 000B7	22700000	N		REF	AP@DCTF6A0
218	01 000B8	30700005	A		REF	AP@DCTF4A0
219	01 000B9	30300005	A		REF	AP@DCTF5A0
220	01 000BA	630000R5			REF	AP@DCTF6A0
221	01 000BB	22300000	N		REF	AP@DCTF4A0
222	01 000BC	22700000	N		REF	AP@DCTF5A0
223	01 000BD	30700005	A		REF	AP@DCTF6A0
224	01 000BE	30300005	A		REF	AP@DCTF4A0
225	01 000BF	630000R5			REF	AP@DCTF5A0

AP0DCTF5

EOO 0 : + E- , ' ,
01 00003 FEFEEFF A
01 00004 00400000 A

CENTREL SECTION SUMMARY: 01 00005 PT 0 02 00000 PT 0

EOO 0 : + E -
* SYMBOL VALUES

A/00000001
FBR/0000000F
GUT/01 00054
R3/0000000B
R7/0000000F
TF3X/01 00023
TH9US/01 00066
X2/00000002
X6/00000006

* EXTERNAL DEFINITIONS
APRAGM1/01 00000
APRDCIF2/01 0009C
APCCOMP5/01 00037

* PRIMARY REFERENCES
AIPDOUT
APSAUT
APXIF5IN
APYTF4IN
APYTF5IN

* NO SECONDARY REFERENCES
* NO UNDEFINED SYMBOLS
* ERROR SEVERITY LEVEL: 0
* NO ERROR LINES

ALS9A/01 00020
FBRH/0000000D
R0/00000008
R4/0000000C
SCAF/01 00064
TF3Y/01 00041
TS11/01 00062
X3/00000003
X7/00000007

APRDCIF4/01 0009D
APRDCIF1/01 0009B
APDCOMP1/01 00016

APRDCIF5

ALS9Y/01 0003E
HOLD/01 000D0
R1/00000009
R5/0000000D
SCALE/01 000CF
TF4X/01 0002D
WYE/01 00035
X4/00000004
ZEEXFM/01 00085

APRDCIF6/01 000A7
AP@INTG/01 000B1

APQTF4A0
APXINTIN
APYAUG
FG34X

APQTF5A0
APXLPFIN
APYINTIN
FG34Y

B/000000000
L89P/01 000B5
R2/0000000CA
R6/0000000CE
TEN/01 00065
TF4Y/01 0004C
X1/000000001
X5/000000005

APRDCIF5/01 000A2
AP@LPF/01 000AC

APQTF6A0
APXSOUT
APYLPFIN
LIMTEST

APRTACH
APXTF4IN
APYSOUT

00000000
0000000F
1015PLAY OF COMMAND
FBRH
FBR
SET
SET
REGNAME
TITLE
APPM001 AND APPM00E
13
15
FORTRAN IV-H BRANCH REGISTER
FORTRAN IV BRANCH REGISTER
APPM001 AND APPM00E

APPM0DI AND APPM0DE

```

80 0: 01 00031 22800000 N
81 01 00032 35200001 N
82 01 00033 22800000 N
83 01 00034 35800003 N
84 01 00035 60200000 A
85 01 00036 22900000 A
86 01 00037 45900000 X
87 01 00038 6830003C
88 01 00039 22800000 N
89 01 0003A 35800003 N
90 01 0003B 68020000 A
91 01 0003C 22900020 A
92 01 0003D 45900000 X
93 01 0003E 68320000 A
94 01 0003F 22800000 N
95 01 00040 35800000 X
96 01 00041 22800000 N
97 01 00042 35800003 N
98 01 00043 68020000 A
99 01 00044 32300000 X
100 01 00045 42300054 X
101 01 00046 32400000 X
102 01 00047 42400055
103 01 00048 31300000 X
104 01 00049 68300048
105 01 0004A 68000000
106 01 0004B 31400001 N
107 01 0004C 68320000 A
108 01 0004D 68000000
109 01 0004E 00000000 A
01 0004F 00000000 A
01 00050 00000000 A
01 00051 00000000 A
01 00052 00000000 A
01 00053 00000000 A
110 01 00054 00000000 A

```

MANP0S

PR0G

APPM0DE

C0NT

Z0R0

DATA

END

```

LI,R0
STW,R0
LI,R0
STW,R0
B
LI,R1
AND,R1
BCR,3
LI,R0
STW,R0
B
LI,R1
AND,R1
BCR,3
LI,R0
STW,R0
LI,R0
STW,R0
B
LW,X3
AND,X3
LW,X4
AND,X4
CW,X3
BCR,3
B
CW,X4
BCR,3
B
DATA

```

APPM0DI

APRSTP

APSCHDLE+1

APSEC

APSCHDLE+3

O,X1

X18001

APSTAT1

PR0G

APPM0DS

APSCHDLE+3

O,X1

X1201

APSTAT1

O,X1

APPRID

APSCHDLE

APSEC

APSCHDLE+3

O,X1

APSTAT1

=X1CEEC1

APSTAT2

=X17FF8001

A1STAT1P

C0NT

APPM0DI

A1STAT1P+1

O,X1

APPM0DI

O,0,0,0,0,0

APPM9DI AND APPM9DE

ECO 0 : I E- ' 01 00055 ' 007FF600 A

CENTROL SECTION SUMMARY: 01 00056 PT 0 02 00000 PT 0

APPM0DI AND APPM0DE

E00 0:1 E-
* SYMBOL VALUES

CON/01 0004B
JRY/01 0001C
R1/00000009
R5/00000000
ST0/01 0002E
X1/00000001
X5/00000005
DIGCOMP/01 00012
KALPUS/01 00036
R2/00000000A
R6/00000000E
ST0R/01 0000B
X2/00000002
X6/00000006
FBR/00000000F
PR0G/01 0003C
R3/00000000B
R7/00000000F
TF5/01 0001A
X3/00000003
X7/00000007
FERH/00000000D
R0/00000008
R4/0000000CC
SLAVE/01 00022
TRAK/01 00028
X4/00000004
ZER0/01 0004E

* EXTERNAL DEFINITIONS

APPM0DE/01 00044

* PRIMARY REFERENCES

AISIAT1F
APR0Y
APSTAT1
AUT0TRAK
AP0AGMNT
APR0CAN
APSTAT2
SCHEDULE

APDC0MP5
APRST0
APXLPFIN
APMNP0S
APSA0UT
APXTF4IN

APPRED
APSCHDL
APXTF5IN

APPREDZ
APSEC
APXTF6IN

* NO SECONDARY REFERENCES

* NO UNDEFINED SYMBOLS

* ERROR SEVERITY LEVEL: 0

* NO ERROR LINES

SYSTEM
SYSTEM
WOLF

E- , ,
C000C0C2
LEVEL 1 DISPLAY OF COMMAND WOLF

003

2000000

LEVEL 1 DISPLAY OF COMMAND WOLF

[illegible]

SYSTEMS
SPACE
TECHNOLOGY DEPT.
SYSTEMS GROUP

1015 DISPLAY OF COMMAND WELF

LEVEL 37A

LEVEL 10ISPLAY 6F COMMAND

REGNAME

ALL X REGISTERS ARE INDEX REGISTERS

ALL R REGISTERS ARE GENERAL USE REGISTERS

LEVEL	1 DISPLAY OF COMMAND	REGNAME
65	00000001	SET X1
66	00000002	SET X2
67	00000003	SET X3
68	00000004	SET X4
69	00000005	SET X5
70	00000006	SET X6
71	00000007	SET X7
72	00000008	SET R0
73	00000009	SET R1
74	0000000A	SET R2
75	0000000B	SET R3
76	0000000C	SET R4
77	0000000D	SET R5
78	0000000E	SET R6
79	0000000F	SET R7

EOO 0 : 8 E- 00000000 FBRH SET
80 0000000F FBR SET
81 1DISPLAY OF COMMAND REGNAME
**** ENDLEVEL 5 TITLE
S ** C ** A ** N
13 FORTRAN IV-H BRANCH REGISTER
15 FORTRAN IV BRANCH REGISTER
IS ** C ** A ** N'

E00	C :	S	E-
6			
7			
8			
9			
10			
11			
12			
13			
14			
15	01	0000Q	ITER
16	01	000G1	A
17	01	000C2	A
18	01	000C3	A
19	01	000C4	A
20	01	000C5	A
21	01	000C6	A
22	01	000C7	A
23	01	000C8	EXP1
24	01	000C9	RT01
25	01	000CA	
26	01	000CB	
27			
28	01	000CC	EXP2
29	01	000CD	APRSCAN
30	01	000CE	
31	01	000CF	
32	01	000CG	TOK
33	01	000CH	
34	01	000CI	
35	01	000CJ	
36	01	000CK	X
37	01	000CL	
38	01	000CM	
39	01	000CN	
40	01	000CO	
41	01	000CP	

S * C * A * N

FLAG

CK

RADIUS

AGAIN

WTFG

20

0K2

1

WTFG

0K+1

RMAX

0K

1

FLAG

WTFG

RADIUS

0K+1

1

WTFG

RADIUS

0K+1

1

NUFG

RMAX

=X'41F653D1'

VEL9CT

RMAX

R1

=X'40100000'

NUFG

1

0KK

TEPR

R3

NUMAX

TEPR

R1

5*PI

CW,R1

BCS,3

CW,R0

BCS,3

LW,R2

CI,R2

BCR,3

AI,R2

ST,R2

B

CW,R0

BCR,3

LI,R1

ST,R1

ST,R1

ST,R0

B

LI,R1

ST,R1

ST,R0

B

LI,R2

ST,R2

ST,R0

LX,R3

LW,R1

FMS,R3

FDS,R3

FAS,R3

LW,R2

CI,R2

BCS,3

LW,R1

FMS,R1

FDS,R1

ST,R1

LW,R0

CK

AGAIN

0K2

0K

EOO

42 01 0001B

43 01 0001C

44 01 0001D

45 01 0001E

46 01 0001F

47 01 00020

48 01 00021

49 01 00022

50 01 00023

51 01 00024

52 01 00025

53 01 00026

54 01 00027

55 01 00028

56 01 00029

57 01 0002A

58 01 0002B

59 01 0002C

60 01 0002D

61 01 0002E

62 01 0002F

63 01 00030

64 01 00031

65 01 00032

66 01 00033

67 01 00034

68 01 00035

69 01 00036

70 01 00037

71 01 00038

72 01 00039

73 01 0003A

74 01 0003B

75 01 0003C

76 01 0003D

77 01 0003E

78 01 0003F

319000A5

69300025

318000A3

6930002C

32A000A6

21A00014 A

69300030

20A00001 A

35A000A6

63000033

3180009D

63300032

229000C1 A

359000A5

359000A6

358000A3

64000033

229000C01 A

359000A6

355000A3

63000033

22A000C1 A

35A000A4

3580009C

328000A7

329000A1

3F80009C

3E800099 A

308000A8

32A000A4

21A000C1 A

693000A5

329000A0

3F9000C0B A

3E90009F

359000A0

328000C9 A

E00

O : S E
79 01 00040
80 01 00041
81 01 00042
82 01 00043
83 01 00044
84 01 00045
85 01 00046
86 01 00047
87 01 00048
88 01 00049
89 01 0004A
90 01 0004B
91 01 0004C
92 01 0004D
93 01 0004E
94 01 0004F
95 01 00050
96 01 00051
97 01 00052
98 01 00053
99 01 00054
100 01 00055
101 01 00056
102 01 00057
103 01 00058
104 01 00059
105 01 0005A
106 01 0005B
107 01 0005C
108 01 0005D
109 01 0005E
110 01 0005F
111 01 00060
112 01 00061
113 01 00062
114 01 00063
115 01 00064

6A600006
35800099 A
22000000
352000A4
359000A5
3520000F
329000A9
3F90000D
3E90000F
25900098
3F8000A0
2E8000AA
32A0000B A
6A600000 X
3580000E
32900008 A
3F9000A7
3E90000F
319000A7
6310005D
21900000 A
69200073
22A00001 A
35A0000C
66A0000A
22900000 A
35900099
3590000E
6A000073
3280009D
21900000 A
69300069
3580000C A
32800098
22800001 A
35800099

GKK

F6S

NEG

BAL,6
STW,RO
LI,R1
STW,R1
STW,R1
STW,R3
LW,R1
FMS,R1
FDS,R1
STW,R1
FMS,R3
FDS,R3
LV,FO
BAL,6
STW,RO
LW,R1
FMS,R1
FDS,R1
CW,R1
BCR,1
CI,R1
BCS,2
LI,R2
STW,R2
AMP,R2
LI,R1
STW,R1
STW,R1
B
RES
LW,FO
CI,RO
BCS,3
STW,RO
STW,RO
LI,RO
STW,RO

S ** C ** A ** N

RT9I
TEE
O
NUFG
FLAG
NUMAX
=X'42A40000'
RMAX
NUMAX
ALPHA
TEPR
=X'42140000'
R3
SGRT
NU
RO
=X'41FB53D1'
NUMAX
=X'41FB53D1'
NEG
O
ANGLE
1
DEL
CTR
O
TEE
NU
ANGLE
O
RMAX
O
OKA
R1
ALPHA
1
TEE

164=1 DEGREE

S ** C ** A ** N

E00	0 :	8	E-	116	01	00064	3530009A	STM,RO	CTR
				117	01	00065	3580009C	STM,RO	DEL
				118	01	00066	323000AB	LW,RO	=X,7CFFFFFF
				119	01	00067	3580009F	STM,RO	NUMAX
				120	01	00068	68000073	B	ANGLE
				121	01	00069	22AFFFFF	LI,P2	-1
				122	01	0006A	35A0009C	STM,R2	DEL
				123	01	0006B	3AA000A	LW,R2	R2
				124	01	0006C	66A0009A	AWM,R2	CTR
				125	01	0006D	3280009F	LW,RO	NUMAX
				126	01	0006E	6A6000C6	BAL,6	RT01
				127	01	0006F	32900008	LW,R1	RO
				128	01	00070	23900014	MI,R1	20
				129	01	00071	35900099	STM,R1	TEE
				130	01	00072	329000A7	LW,R1	=X,41FB53D1
				131	01	00073		RES	0
				132	01	00073	328000C9	LW,RO	R1
				133	01	00074	358000CF	STM,RO	R7
				134	01	00075	6A6000C0	BAL,6	SIN
				135	01	00076	358000C0	STM,RO	R5
				136	01	00077	328000CF	LW,RO	R7
				137	01	00078	6A6000C0	BAL,6	C9S
				138	01	00079	3580000B	STM,RO	R3
				139	01	0007A	3FD00098	FMS,R5	ALPHA
				140	01	0007B	3FB00098	FMS,R3	ALPHA
				141	01	0007C	3FD0009E	FMS,R5	NU
				142	01	0007D	3FB0009E	FMS,R3	NU
				143	01	0007E	328000C0	LW,RO	R3
				144	01	0007F	6A6000C6	BAL,6	RT01
				145	01	00080	358000C0	STM,RO	R3
				146	01	00081	328000C0	LW,RO	R5
				147	01	00082	6A6000C6	BAL,6	RT01
				148	01	00083	35800009	STM,RO	R1
				149	01	00084	3240009A	LW,X4	CTR
				150	01	00085	21400005	CI,X4	5
				151	01	00086	69100089	BCS,1	\$+3
				152	01	00087	224000C1	LI,X4	1

[illegible]

EOC 0 : 8 E-

CONTROL SECTION SUMMARY: 01 000AC PT 0

S ** C ** A** N

02 00000 PT 0

EOO 0: K E-

1	SYSTEM	SIG5FP
2	DEF	SIN
3	DEF	COS
4	REF	8TO
5	REF	8T1
6		
7	EQU	4
8	EQU	5
9	EQU	8
10	EQU	R8+1
11	SPACE	3

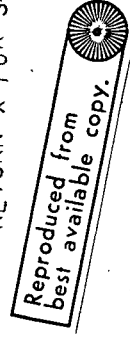
* R2 EQU 4
 * R6 EQU 5
 * R8 EQU 8
 * R9 EQU R8+1

LINK
 REAL
 ACCUMULATOR
 TEMP

12	* CONSTANTS	
13		
14	* COMCO	X'3FD3C6A8', -X'3FD3C6A8', +-(120/16**6)**-4=0.051703125
15	BIG	X'4610C000', X'80' SCALE, ROUND
16	TW98PI	X'40A2F983', X'6E4E415', 2/PI=0.6366197723675813+1
17	CO	X'4110C000', 1.0
18	ONE	CO
19	C1	X'EEC42C7', -1.233697
20	C2	X'4040E8D7', 0.2535986
21	C3	X'COAC6865', -0.020408255
22	NC3	X'3F539793', 0.020408255
23	S0	X'411921F3', 1.5707963
24	S1	X'BF5AA223', -0.6459635
25	S2	X'401465EC', 0.07968022
26	S3	X'COED2643', -0.004602163
27	NS3	X'3F1209B3', 0.004602163
28	SIXTH	-X'402AAAAA', -1/6 TRUNCATED
29	MASK	X'FFFFFFF0', T0 COMPLEMENT
30	SPACE	3

31	01 00012	SIN	RES	0
32	01 00012		LI,R2	0
33	01 00013		CLM,R8	COMCO
34	01 00014		BG	2A4
35	01 00015		LI,R2	2
36	01 00016		BCS,4	2A1
37	01 00017		STW,R8	8T1
38	01 00018		FMS,R8	8T1
39	01 00019		FMS,R8	SIXTH
40	01 0001A		FAS,R8	ONE
41	01 0001B		FMS,R8	8T1
42	01 0001C		B	0,R6
43			SPACE	3

INDICATE SIN
CHECK FOR VERY SMALL X
BRANCH IF LARGE +
INDICATE -
BRANCH IF LARGE -
X FIRST
TWS
TERMS OF
SERIES
RETURN X FOR SIN(SMALL X)



44	01 0001D	COS	RES	0
45	01 0001D		LI,R2	1
46	01 0001E		LAW,R8	R8
47	01 0001F		LI,R9	0
48	01 00020		FML,R8	TWOPI
49	01 00021		CM,R8	BIG
50	01 00022		BL	3A1
51	01 00023		B	0,6
52	01 00024		FAL,R8	BIG
53	01 00025		AW,R2	R8
54	01 00026		LI,R8	X'40
55	01 00027		AI,R9	0
56	01 00028		BLZ	3A2
57	01 00029		CI,R2	1
58	01 0002A		BAZ	4A6
59	01 0002U		RES	0
60	01 0002H		SLD,R8	24
61	01 0002C		FMS,R8	R8
62	01 0002D		STW,R8	8T1
63	01 0002E		CI,R2	2

INDICATE COS
ABS
CLEAR LSH
CONVERT TO QUADRANTS
CHECK FOR NO SIGNIFICANCE

SCALE AND ROUND
COPY AND MODIFY INTEGER PART
INSERT EXPONENT
FRACTION : 0.5
BRANCH IF F >= 0.5
CHECK ODD/EVEN QUADRANT
IF EVEN, BRANCH TO SIN EXPANSION
PLACE
POSITION F
H=F*F
COPY H
CHECK FOR + OR - RESULT

EOO

0: K E-

64

4A5

BRANCH IF +

NEG-

7

64	01 0002F	69400037	EAZ	4A5	BRANCH IF +
65	01 00030	3F8000CA	FMS,R8	MC3	NEG-
66	01 00031	3F8000C8	FSS,R8	C2	ACTIVE
67	01 00032	3F8000C0	FMS,R8	8T1	POLY-
68	01 00033	3C8000C7	FSS,R8	C1	NOMIAL
69	01 00034	3F8000C0	FMS,R8	8T1	EX-
70	01 00035	3C8000C6	FSS,R8	C0	PANSION
71	01 00036	680C00C0	B	0,R6	RETURN
72	01 00037	3F8000C9	FMS,R8	C3	P6S-
73	01 00038	3C8000C8	FAS,R8	C2	ITIVE
74	01 00039	3F8000C0	FMS,R8	8T1	POLY-
75	01 0003A	3D8000C7	FAS,R8	C1	NOMIAL
76	01 0003B	3F8000C0	FMS,R8	8T1	EX-
77	01 0003C	3D8000C6	FAS,R8	C0	PANSION
78	01 0003D	680C00C0	R	0,R6	RETURN
79	01 0003E	43900011	EGR,R9	MASK	1-F
80	01 0003F	21400001	C1,R2	1	CHECK 6DD/EVEN QUADRANT
81	01 00040	6340002F	BAZ	4A1	IF EVEN, BRANCH TO CUS EXPANSION
82	01 00041	2550011B	RES	C	PLACE
83	01 00041	352000C0	SLD,R8	24	POSITION F
84	01 00042	3F8000C0	STM,R8	8T0	COPY F
85	01 00043	3F8000C0	FMS,R8	8T0	H=F*F
86	01 00044	358000C0	STM,R8	8T1	COPY H
87	01 00045	214000C2	C1,R2	2	CHECK FOR + OR - RESULT
88	01 00046	6840004F	BAZ	5A1	BRANCH IF +
89	01 00047	3F8000C0	FMS,R8	MS3	NEG-
90	01 00048	3C8000C0	FSS,R8	S2	ACTIVE
91	01 00049	3F8000C0	FMS,R8	8T1	POLY-
92	01 0004A	3C8000C0	FSS,R8	S1	NOMIAL
93	01 0004B	3F8000C0	FMS,R8	8T1	EX-
94	01 0004C	3C8000C0	FSS,R8	S0	PAN-
95	01 0004D	3F8000C0	FMS,R8	8T0	SIGN
96	01 0004E	680C00C0	E	0,R6	RETURN
97	01 0004F	3F8000C0	FMS,R8	S3	P6S-
98	01 00050	3D8000C0	FAS,R8	S2	ITIVE
99	01 00051	3F8000C0	FMS,R8	8T1	POLY-
100	01 00052	3D8000C0	FAS,R8	S1	NOMIAL

EOO 0 : K E-
101 01 00053 3F800000 X
102 01 00054 3D800000B
103 01 00055 3F8000000 X
104 01 00056 680C0000 A
105
FMS,R8 8T1
FAS,R8 SO
FMS,R8 8T0
B 0,R6
END
RETURN
EX PAN-
SIGN

CONTROL SECTION SUMMARY: 01 00057 PT 0

```

EOO 0 : K E-
*   SYMBOL VALUES
    BIG/01 00002
    C2/01 00008
    N53/01 0000F
    R3/000000008
    S1/01 0000C
    2A1/01 0001E
    4A1/01 0002B
    4A6/01 00041
*   EXTERNAL DEFINITIONS
    C95/01 0001D
*   PRIMARY REFERENCES
    8TO
    8T1
*   NO SECONDARY REFERENCES
*   NO UNDEFINED SYMBOLS
*   ERROR SEVERITY LEVEL: 0
*   NO ERROR LINES
    CO/01 00006
    C3/01 00009
    BRE/01 00006
    R9/000000009
    S2/01 0000D
    2A4/01 0001F
    4A3/01 0002D
    4A8/01 00041
    SIN/01 00012
    COMCO/01 00000
    MASK/01 00011
    R2/000000004
    SIXTH/01 00010
    S3/01 0000E
    3A1/01 00024
    4A4/01 0002E
    5A/01 00057
    C1/01 00007
    MC3/01 0000A
    R6/000000006
    SC/01 0000B
    TW85PI/01 00004
    3A2/01 0003E
    4A5/01 00037
    5A1/01 0004F

```

EOO 0: K E-

SYSTEM SIG5FP

1
2
3
4
5
6
7
8

* R2
R6
R8
R9
R10

00000004
00000006
00000008
00000009
0000000A

4
6
8
9
10
3

EQU
EQU
EQU
EQU
EQU
SPACE

LINK
ACCUMULATOR
TEMP
TEMP

* CONSTANTS

9
10
11
12
13
14
15
16
17
18
19
20
21
22

01 00000
01 00001
01 00002
01 00003
01 00004
01 00005
01 00006
01 00007
01 00008
01 00009
01 0000A
01 0000A

80FFFFF A
3FC00000 A
41400000 A
41570566 A
413504F3 A
4128AEE4 A
41224C29 A
3FAFB00CB A
4013C789 A
40190AAC A
401DC78A A

X80F
X3F
F8UR
A
A
B

DATA
DATA
DATA
DATA
DATA
DATA
DATA
DATA
DATA
DATA
DATA
DATA
SPACE

X'80FFFFFF'
X'3FC00000'
FS'4.0'
X'4157D856'
X'413504F3'
X'4128AEE4'
X'41224C29'
X'3FAFB00CB'
X'4013C789'
X'40190AAC'
X'401DC78A'

4.0
5.4903312
8(RT(2)-1)=3.3137085
8(RT(3)-RT(2))=2.542698
8(2-RT(3))=2.1435935
•0428932125
(12RT(2)-15)/(64(RT(2)-1))=.074333739
(20RT(6)-47)/(64(RT(3)-RT(2)))=.097819072
(56RT(3)-95)/(64(2-RT(3)))=.116326

23
24
25
26
27
28
29
30
31

01 0000B
01 0000C
01 0000C
01 0000D
01 0000E
01 0000F
01 00010

72AC0008 A
4B80000C
6220000F A
633C0000 A
49800001
35800023

SQRT
8TO,8T:
0
R8
X80F
3A1
0,R6
X3F
8TO

DEF
DEF
RES
LB,R10
AND,R8
BGZ
BEZ
BR,R8
STW,R8

BRANCH IF X>0
RETURN 0.0 FOR SQRT(0.0)
COPY F

E00

C: K E-

32 01 00011 52400023
 33 01 00012 2540007A A
 34 01 00013 3F89FFC7
 35 01 00014 3089FF0B
 36 01 00015 35800024
 37 01 00016 32800023
 38 01 00017 3E800024
 39 01 00018 30800024
 40 01 00019 45800023
 41 01 0001A 3F800002
 42 01 0001B 3E800023
 43 01 0001C 30800023
 44 01 0001D 25A0002F A 3A4
 45 01 0001E 20A00020 A
 46 01 0001F 75A000C8 A
 47 01 00020 681C00C0 A
 48 01 00021 3F8000C2
 49 01 00022 650C00C0 A
 50

LH,R2 8T0
 SLS,R2 -6
 FMS,R8 A-252,R2
 FAS,R8 B-252,R2
 STW,R8 8T1
 LW,R8 8T0
 FDS,R8 8T1
 FAS,R8 8T1
 XW,R8 8T0
 FMS,R8 FOUR
 FDS,R8 8T0
 FAS,R8 8T0
 SCS,R10 -1
 AI,R10 X'20'
 STB,R10 R8
 BGEZ 0,R6
 FMS,R8 F6UR
 B 0,R6
 SPACE 3

INDEX
 T0 A AND B
 LINEAR APPROXIMATION
 TO RESULT
 COPY G
 F
 F/G
 G+F/G
 G<=> F
 4*F
 4*F/G
 G+4*F/G
 HALVE EXPONENT, REMAINDER IN BIT 0
 FIX BIAS, CHECK REMAINDER
 INSERT EXPONENT
 RETURN IF NO REMAINDER
 *SQRT(16)

51 01 00023 00000000 A 8T0
 52 01 00024 00000000 A 8T1
 53 3A

DATA
 DATA
 END

CONTROL SECTION SUMMARY: 01 00025 PT 0

```

EOO 0 : K E-
* SYMBOL VALUES
  A/01 00003
  R2/00000004
  X3F/01 00001
  3A1/01 0000F
* EXTERNAL DEFINITIONS
  SGRT/01 0000B
* NO PRIMARY REFERENCES
* NO SECONDARY REFERENCES
* NO UNDEFINED SYMBOLS
* ERROR SEVERITY LEVEL: 0
* NO ERROR LINES

  B/01 00007
  R6/000000006
  X8CF/01 00000
  3A3/01 00010
  8T0/01 00023

  F0UR/01 00002
  R3/000000008
  1A1/01 0000E
  3A4/01 0001D
  8T1/01 00024

  R10/00000000A
  R9/000000009
  3A/01 00025

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```

1: DIMENSION IDATA( 50,24)
2: DIMENSION XX(300),YY(300),EXX(50),EYY(50),EEE(50),ENN(50)
3: *VEE(50),XCRF(5),YCRF(5),N(8,10),IHR(50),IMN(50)
4: DIMENSION RANGE(50),RATE(50),AZ(50),EL(50)
5: INTEGER SATIE,SATID,CAL,DAY,MIN,MIN,HR,HP,SEC,DEL,ORBN1,ORBN2
6: DATA ISLASH/4H/ /,IEND/4H MSG/,IBLANK/4H /
7: REWIND 7
8: REWIND 8
9: CALL EUFSET(236S)
10: 200 WRITE(101,1700)
11: REWIND 7
12: REWIND 8
13: READ(101,1710,ERR=200) SATIE
14: IF (SATIE.EQ.0) CALL EXIT
15: 201 WRITE(101,1720)
16: READ(101,1730,ERR=201) ORBN1
17: IF (ORBN1.EQ.0) GO TO 200
18: REWIND 7
19: REWIND 8
20: READ(8,1500)DAY,YEAR,MGN,DAYY
21: READ(8,1510) SATID
22: IF (SATIE.NE.SATID)GO TO 777
23: GO TO 901
24: 236 WRITE(101,1740)
25: GO TO 201
26: 777 WRITE(101,1750)
27: GO TO 200
28: 900 READ(8,1500)DAY,YEAR,MGN,DAYY
29: READ(8,1510) SATID
30: 901 READ(8,801) DAY,HR,MIN,SEC,DEL
31: I=1
32: 902 READ(8,803) (IDATA(I,J),J=1,24)
33: IF (IDATA(I,4).EQ.ISLASH) GO TO 903
34: I=I+1
35: GO TO 902
36: 903 BACKSPACE 3
37: READ(8,107) ORBN2
38: IF (ORBN1.EQ.ORBN2) GO TO 202
39: READ(8,904) INC
40: IF (INC.EQ.IEND) GO TO 900
41: GO TO 901
42: 202 4R=180./3.1416
43: LUK=0
44: IF (SATID.EQ.6903701) IJK=3
45: IF (SATID.EQ.7002501) IJK=4
46: PRINT 1000,IJK
47: PRINT 1010
48: PRINT 1020,SATIE
49: PRINT 1030, ORBN1
50: ITIM=3600*HR+60*MIN+SEC
51: JTIM=ITIM+2*DEL*60
52: ITIM=JTIM-1

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53: NC=I
54: DO 203 I=1,NC
55:   BACKSPACE 3
56:   NC=NC-1
57:   PRINT 1040, DAY, MON, YEAR
58:   PRINT 1050, DAY
59:   HHR=HR
60:   MMIN=MIN+2
61:   IF (MMIN.LT.59) GO TO 1530
62:   HHR=HHR+1
63:   MMIN=MMIN-60
64:   IF (HHR.LT.24) GO TO 1530
65:   HHR=HHR-24
66:   PRINT 1060, HHR,MMIN,SEC
67:   PRINT 1100
68:   PRINT 1110
69:   PRINT 1120
70:   PRINT 1130
71:   PRINT 1600
72:   DO 604 J4=1,NC
73:     IHR(J4)=HR
74:     IMN(J4)=MIN+(J4-1)*DEL
75:     IF (IMN(J4)-60) 604,603,603
76:     IHR(J4)=IHR(J4)+1
77:     IMN(J4)=IMN(J4)-60
78:   CONTINUE
79:   READ (8,101) (EEE(I),ENN(I),VEE(I),I=1,NC)
80:   RATE(I)=0.
81:   DO 1145 I=1,NC
82:     EEE(I)=EEE(I)/10.
83:     VEE(I)=VEE(I)/10.
84:     ENN(I)=ENN(I)/10.
85:     RANGE(I)=SORT(EEE(I)**2+VEE(I)**2+ENN(I)**2)
86:     IF (I.EQ.1) GO TO 1135
87:     RATE(I)=(RANGE(I)-RANGE(I-1))/(60*DEL)
88:     PRINT 1140, IHR(I),IMN(I),EEE(I),ENN(I),VEE(I),RANGE(I),RATE(I)
89:   CONTINUE
90:   PRINT 1200
91:   PRINT 1210
92:   PRINT 1220
93:   PRINT 1230
94:   PRINT 1600
95:   DO 205 I=1,NC
96:     EXX(I)=RR*ATAN(EEE(I),VEE(I))
97:     WYE(I)=RR*ATAN(ENN(I)/SORT(EEE(I)**2+VEE(I)**2))
98:     AZ(I)=RR*ATAN(VEE(I),ENN(I))
99:     EL(I)=RR*ATAN(VEE(I),SORT(EEE(I)**2+ENN(I)**2))
100:   PRINT 1240, IHR(I),IMN(I),EXX(I),WYE(I),AZ(I),EL(I)
101:   PRINT 1300
102:   PRINT 1310
103:   PRINT 1320
104:   PRINT 1330
105:   PRINT 1600

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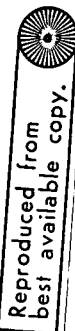
106: REWIND 8
107: NC=NC-4
108: NP=60*DEL
109: ICS=0
110: KC=1
111: NYX=0
112: NYB=0
113: NREC=0
114: DS 206 J=2,NC
115: KC=X0+1
116: CALL COEF(EXX(KG),XC0F)
117: CALL COEF(MYE(KG),YC0F)
118: IFLAG=1
119: CALL INTERPQL (XX,XC0F,NP)
120: CALL INTERPQL (YY,YC0F,NP)
121: M=NP/10
122: DO 208 J=1,M
123: L=(J-1)*10
124: DS 207 K=1,10
125: L=L+1
126: IF (XX(L)-82.) 300,301,301
127: 301 XX(L)=82.
128: GS TO 303
129: 303 IF (XX(L)+82.) 302,302,303
130: 302 XX(L)=-82.
131: 303 IF (YY(L)-82.) 304,305,305
132: 305 YY(L)=82.
133: GS TO 307
134: 304 IF (YY(L)+82.) 306,306,307
135: 306 YY(L)=-82.
136: 307 ITIM=ITIM+1
137: IP=ITIM/3600
138: IM=(ITIM-IP*3600)/60
139: IS=ITIM-IP*3600-IP*60
140: AX=28S(XX(L))
141: AY=28S(YY(L))
142: IF (AX-45.) 712,712,701
143: YL=82.-.514*(AX-45.)
144: 703 IF (AY-YL) 712,712,709
145: 709 IF (ICS) 207,735,207
146: 735 JTIV=ITIM
147: ICS=1
148: GS TO 207
149: 712 IF (ICS) 720,730,720
150: 720 ICS=0
151: NR=(ITIM-JTIM)/10+1
152: JTIM=10*(JTIM/10)-1
153: L=J*10
154: IF (XX(L)-82.) 500,501,501
155: 501 XX(L)=82.
156: GS TO 503
157: 500 IF (XX(L)+82.) 502,502,503
158: 502 XX(L)=-82.

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159: IF(YY(L)-82.) 504,505,505
160: YY(L)=82.
161: GO TO 507
162: IF(YY(L)+82.)506,506,507
163: YY(L)=-82.
164: XX=XX(L)*164
165: YY=YY(L)*164
166: XAA=XX(L)
167: YAA=YY(L)
168: D9 729 JA=1,NR
169: D9 728 JB=1,10
170: JTIM=JTIM+1
171: IH=JTIM/3600
172: IM=(JTIM-IH*3600)/60
173: IS=JTIM-IH*3600-IM*60
174: XD9T=0.
175: YD9T=0.
176: IF(IFLAG.EQ.1) GO TO 1345
177: PRINT 1340, IH,IM,IS,XAA,YAA,XD9T,YD9T
178: GO TO 1365
1345: FRINT 1350,IH,IM,IS,XAA,YAA,XD9T,YD9T,(XC9F(II),II=1,5)
180: PRINT 1360,(YC9F(II),II=1,5)
181: IFLAG=0
182: CONTINUE
183: N(1,JB)=SATID
184: N(2,JB)=JTIM
185: N(3,JB)=XXX
186: N(4,JB)=YYY
187: N(5,JB)=0
188: N(6,JB)=0
189: N(7,JB)=DAY
190: NX3=N(3,10)
191: NYB=N(4,10)
192: NREC=NREC+1
193: WRITE(7) N
194: ITIM=JTIM
195: GO TO 208
196: CENTIME
197: N(1,K)=SATID
198: N(2,K)=ITIM
199: N(3,K)=XX(L)*164
200: N(4,K)=YY(L)*164
201: N(5,K)=N(3,K)-NXB
202: N(6,K)=N(4,K)-NYB
203: NX3=N(3,K)
204: NYB=N(4,K)
205: N(7,K)=DAY
206: XD9T=N(5,K)/164.
207: YD9T=N(6,K)/164.
208: IF(IFLAG.EQ.1) GO TO 1367
209: PRINT 1340,IH,IM,IS,XX(L),YY(L),XD9T,YD9T
210: GO TO 1369
1367: PRINT 1350,IH,IM,IS,XX(L),YY(L),XD9T,YD9T,(XC9F(II),II=1,5)

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212: PRINT 1360,(YCSF(11),11=1,5)
213: IFLAG=0
214: 1363 CONTINUE
215: 207 CONTINUE
216: IF(ICS) 208,397,208
217: 397 WRITE(7) N
218: NREC=NREC+1
219: 208 CONTINUE
220: 206 CONTINUE
221: 711 DO 658 I=1,10
222: N(5,I)=0
223: N(6,I)=0
224: N(3,I)=N(3,10)
225: 658 N(4,I)=N(4,10)
226: IF(ICS) 794,795,794
227: 794 ITIM=10*(JTIM/10)-1
228: 795 DO 667 I=1,12
229: DO 666 J=1,10
230: ITIM=ITIM+1
231: N(5,J)=65535
232: 666 N(2,J)=ITIM
233: NREC=NREC+1
234: 667 WRITE(7) N
235: PRINT 1400
236: PRINT 1410
237: PRINT 1420
238: PRINT 1430
239: PRINT 1440
240: PRINT 1450,N
241: REWIND 7
242: ITF=ITIM+1
243: WRITE(9) ITF
244: DO 9573 I=1,NREC
245: READ(7) N
246: 9573 WRITE(9) N
247: REWIND(9)
248: WRITE(101,9876)
249: GO TO 200
250: 100 FORMAT(313)
251: 101 FORMAT(315)
252: 105 FORMAT(17/15)
253: 106 FORMAT(14RANG PREDICT TAPE-----JOB ENDED')
254: 107 FORMAT(4N,16)
255: 230 FORMAT('ENTER SATELLITE ID AND ORBIT # (17/15) ---TO EXIT PUSH NEW
256: 3 LINE TWICE',/)
257: 240 FORMAT(' DAY HOUR MIN SFC DEL')
258: 400 FORMAT(2(2X,12),2X,3F18.6)
259: 401 FORMAT(' TIME EAST NORTH VERTIC
260: *ALL)
261: 402 FORMAT(' TIME X Y')
262: 405 FORMAT(////)
263: 407 FORMAT(1X,3(12,1X),2F15.3)
264: 800 FORMAT(//17////)

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265: 801 FORMAT (I5,I1X,I12,I1X,I13)
266: 802 FORMAT (8I8)
267: 803 FORMAT (24A1)
268: 804 FORMAT (/4X,A4)
269: 1000 FORMAT(1)
270: 1010 FORMAT(1)
271: 1020 FORMAT(10)
272: 1030 FORMAT(10)
273: 1040 FORMAT(10)
274: 1050 FORMAT(10)
275: 1060 FORMAT(10)
276: 1100 FORMAT(11)
277: 1110 FORMAT(1)
278: 1120 FORMAT(10) TIME EAST NORTH VERTICAL RANGE RANGERRATE(1)
279: 1130 FORMAT(1) HRS MIN KM KM KM KM/SEC(1)
280: 1140 FORMAT(12(2X,I2),4(2X,F7.1),2X,F7.3)
281: 1200 FORMAT(11)
282: 1210 FORMAT(1)
283: 1220 FORMAT(10) TIME X DEGREES DEGREES DEGREES EL(1)
284: 1230 FORMAT(1) HRS MIN DEGREES DEGREES DEGREES EL(1)
285: 1240 FORMAT(12(2X,I2),4(2X,F8.3))
286: 1300 FORMAT(11)
287: 1310 FORMAT(1)
288: 1320 FORMAT(1) TIME X INTERPOL. INTERPOL. INTERPOL. INTERPOL.
289: 1330 FORMAT(1) HRS MIN SEC DEGREES DEGREES DEG/SEC DEG/SEC COEFF. 0
290: 1340 FORMAT(3(2X,I2),4(2X,F7.3))
291: 1350 FORMAT(3(2X,I2),4(2X,F7.3),5(2X,E10.3),2X,'FOR X COEFFICIENTS')
292: 1360 FORMAT(4X,5(2X,E10.3),2X,'FOR Y COEFFICIENTS')
293: 1400 FORMAT(1)
294: 1410 FORMAT(1)
295: 1420 FORMAT(10,4X,11,10X,12,10X,13,10X,14,10X,15,10X,16,10X,17,10X,18)
296: 1430 FORMAT(1X,'SATELLITE TIME 164*X 164*Y 164*X DGT
297: 1440 FORMAT(1X,'ID NUMBER SECONDS DEGREES DEGREES DEG/SEC
298: 1450 FORMAT(8(18,3X))
299: 1460 FORMAT(1)
300: 1470 FORMAT(1)
301: 1500 FORMAT(13,1X,3I2)
302: 1510 FORMAT(17)
303: 1600 FORMAT(1)
304: 1700 FORMAT(1)
305: 1710 FORMAT(17)
306: 1720 FORMAT(1)
307: 1730 FORMAT(15)
308: 1740 FORMAT(1)
309: 1750 FORMAT(1)
310: 1760 FORMAT(1)
311: 1770 FORMAT(1)
312: 1780 FORMAT(1)
313: 1790 FORMAT(1)
314: 1800 FORMAT(1)
315: 1810 FORMAT(1)
316: 1820 FORMAT(1)
317: 1830 FORMAT(1)
318: 1840 FORMAT(1)
319: 1850 FORMAT(1)
320: 1860 FORMAT(1)
321: 1870 FORMAT(1)
322: 1880 FORMAT(1)
323: 1890 FORMAT(1)
324: 1900 FORMAT(1)
325: 1910 FORMAT(1)
326: 1920 FORMAT(1)
327: 1930 FORMAT(1)
328: 1940 FORMAT(1)
329: 1950 FORMAT(1)
330: 1960 FORMAT(1)
331: 1970 FORMAT(1)
332: 1980 FORMAT(1)
333: 1990 FORMAT(1)
334: 2000 FORMAT(1)
335: 2010 FORMAT(1)
336: 2020 FORMAT(1)
337: 2030 FORMAT(1)
338: 2040 FORMAT(1)
339: 2050 FORMAT(1)
340: 2060 FORMAT(1)
341: 2070 FORMAT(1)
342: 2080 FORMAT(1)
343: 2090 FORMAT(1)
344: 2100 FORMAT(1)
345: 2110 FORMAT(1)
346: 2120 FORMAT(1)
347: 2130 FORMAT(1)
348: 2140 FORMAT(1)
349: 2150 FORMAT(1)
350: 2160 FORMAT(1)
351: 2170 FORMAT(1)
352: 2180 FORMAT(1)
353: 2190 FORMAT(1)
354: 2200 FORMAT(1)
355: 2210 FORMAT(1)
356: 2220 FORMAT(1)
357: 2230 FORMAT(1)
358: 2240 FORMAT(1)
359: 2250 FORMAT(1)
360: 2260 FORMAT(1)
361: 2270 FORMAT(1)
362: 2280 FORMAT(1)
363: 2290 FORMAT(1)
364: 2300 FORMAT(1)
365: 2310 FORMAT(1)
366: 2320 FORMAT(1)
367: 2330 FORMAT(1)
368: 2340 FORMAT(1)
369: 2350 FORMAT(1)
370: 2360 FORMAT(1)
371: 2370 FORMAT(1)
372: 2380 FORMAT(1)
373: 2390 FORMAT(1)
374: 2400 FORMAT(1)
375: 2410 FORMAT(1)
376: 2420 FORMAT(1)
377: 2430 FORMAT(1)
378: 2440 FORMAT(1)
379: 2450 FORMAT(1)
380: 2460 FORMAT(1)
381: 2470 FORMAT(1)
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383: 2490 FORMAT(1)
384: 2500 FORMAT(1)
385: 2510 FORMAT(1)
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390: 2560 FORMAT(1)
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401: 2670 FORMAT(1)
402: 2680 FORMAT(1)
403: 2690 FORMAT(1)
404: 2700 FORMAT(1)
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427: 2930 FORMAT(1)
428: 2940 FORMAT(1)
429: 2950 FORMAT(1)
430: 2960 FORMAT(1)
431: 2970 FORMAT(1)
432: 2980 FORMAT(1)
433: 2990 FORMAT(1)
434: 3000 FORMAT(1)
435: 3010 FORMAT(1)
436: 3020 FORMAT(1)
437: 3030 FORMAT(1)
438: 3040 FORMAT(1)
439: 3050 FORMAT(1)
440: 3060 FORMAT(1)
441: 3070 FORMAT(1)
442: 3080 FORMAT(1)
443: 3090 FORMAT(1)
444: 3100 FORMAT(1)
445: 3110 FORMAT(1)
446: 3120 FORMAT(1)
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454: 3200 FORMAT(1)
455: 3210 FORMAT(1)
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457: 3230 FORMAT(1)
458: 3240 FORMAT(1)
459: 3250 FORMAT(1)
460: 3260 FORMAT(1)
461: 3270 FORMAT(1)
462: 3280 FORMAT(1)
463: 3290 FORMAT(1)
464: 3300 FORMAT(1)
465: 3310 FORMAT(1)
466: 3320 FORMAT(1)
467: 3330 FORMAT(1)
468: 3340 FORMAT(1)
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470: 3360 FORMAT(1)
471: 3370 FORMAT(1)
472: 3380 FORMAT(1)
473: 3390 FORMAT(1)
474: 3400 FORMAT(1)
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501: 3670 FORMAT(1)
502: 3680 FORMAT(1)
503: 3690 FORMAT(1)
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525: 3910 FORMAT(1)
526: 3920 FORMAT(1)
527: 3930 FORMAT(1)
528: 3940 FORMAT(1)
529: 3950 FORMAT(1)
530: 3960 FORMAT(1)
531: 3970 FORMAT(1)
532: 3980 FORMAT(1)
533: 3
```

NAME	TYPE	CLASS	HEX LOC	DEC WORDS	NAME	TYPE	CLASS	HEX LOC	DEC WORDS	NAME	TYPE	CLASS	HEX LOC	DEC WORDS
ABS	R	SPR0G	009B1	1	ATAN	R	SPR0G	INTRIN		AX	R	SCALR	00980	1
AY	R	SCALR	0098E	1	AZ	R	ARRAY	00924	50	COEF	R	SPR0G	EXTERN	
CAI	I	UNUSED	0079E	50	DAY	I	SCALR	0098A	1	DAYY	R	SCALR	00926	1
DEL	I	SCALR	00708	50	EEE	R	ARRAY	0076C	50	EL	R	ARRAY	00956	50
ENN	R	ARRAY	0098C	1	E9FSET	R	SPR0G	EXTERN		EXIT	R	SPR0G	EXTERN	
EXX	R	ARRAY	00993	1	HHR	R	SCALR	009A0	1	HP	I	UNUSED		
HR	I	SCALR	00992	1	I	I	SCALR	00997	1	IB	I	SCALR	0099F	1
IBLANK	I	SCALR	00993	1	ICS	I	SCALR	009A4	1	IDATA	I	ARRAY	00000	1200
IEND	I	SCALR	00992	1	IFLAG	I	SCALR	009A9	1	IH	I	SCALR	009AD	1
IHR	I	SCALR	00992	1	II	I	SCALR	009BC	1	IJK	I	SCALR	00995	1
IM	I	SCALR	00992	1	IMN	I	ARRAY	0098E	50	IND	I	SCALR	00999	1
INTERPOL	I	SPR0G	EXTERN		IS	I	SCALR	009AF	1	ISLASH	I	SCALR	00991	1
ITF	I	SCALR	00998	1	ITIM	I	SCALR	0099C	1	J	I	SCALR	00998	1
JA	I	SCALR	009A2	1	JB	I	SCALR	00999	1	JTIM	I	SCALR	0099D	1
U4	I	SCALR	009A2	1	K	I	SCALR	009AC	1	K0	I	SCALR	0099D	1
L	I	SCALR	009A2	1	M	I	SCALR	009AA	1	MIM	I	SCALR	009A5	1
MIN	I	SCALR	009A8	1	MMIN	I	SCALR	009A1	1	M6N	I	SCALR	00995	1
N	I	ARRAY	009CC	80	NC	I	SCALR	0099E	1	NP	I	SCALR	009A3	1
NR	I	SCALR	00993	1	NREC	I	SCALR	009A8	1	NXB	I	SCALR	009A6	1
NYB	I	SCALR	009A7	1	ORBN1	I	SCALR	009AF	1	OREN2	I	SCALR	00990	1
RANGE	R	ARRAY	009C0	50	RATE	R	ARRAY	009F2	50	RR	R	SCALR	0099A	1
SATID	I	SCALR	00989	1	SATIE	I	SCALR	009A8	1	SEC	I	SCALR	0098D	1
SGRT	R	SPR0G	INTRIN		VEE	R	ARRAY	007D0	50	WYE	R	ARRAY	0073A	50
XAA	R	SCALR	00926	1	XC0F	R	ARRAY	00802	5	XD8T	R	SCALR	0098A	1
XX	R	ARRAY	00480	300	XXX	R	SCALR	009B4	1	YAA	R	SCALR	009B7	1
YC0F	R	ARRAY	00807	5	YD8T	R	SCALR	009B6	1	YEAR	R	SCALR	00994	1
YL	R	SCALR	009B2	1	YY	R	ARRAY	005DC	300	YYY	R	SCALR	009B5	1

NAME	TYPE	CLASS	HEX LOC	DEC WORDS	NAME	TYPE	CLASS	HEX LOC	DEC WORDS	NAME	TYPE	CLASS	HEX LOC	DEC WORDS
100	R	SCALR	003C5		107	R	SCALR	003D8		200	R	SCALR	00008	
201	R	SCALR	00019		206	R	SCALR	0035C		207	R	SCALR	00348	
203	R	SCALR	00357		300	R	SCALR	001FC		301	R	SCALR	001F8	
302	R	SCALR	00200		306	R	SCALR	0020F		307	R	SCALR	00212	
337	R	SCALR	00351		405	R	SCALR	0041E		407	R	SCALR	00421	
500	R	SCALR	00257		504	R	SCALR	00266		505	R	SCALR	00262	
506	R	SCALR	0026A		654	R	SCALR	0036C		666	R	SCALR	00382	
667	R	SCALR	00337		711	R	SCALR	00361		712	R	SCALR	0023E	
720	R	SCALR	00240		730	R	SCALR	002EF		735	R	SCALR	00239	
777	R	SCALR	00042		801	R	SCALR	0042B		802	R	SCALR	00431	
803	R	SCALR	00434		902	R	SCALR	0005F		903	R	SCALR	00074	
1000	R	SCALR	0043A		1040	R	SCALR	0046A		1050	R	SCALR	00477	
1060	R	SCALR	0047F		1130	R	SCALR	00489		1135	R	SCALR	00141	
1140	R	SCALR	004C9		1210	R	SCALR	004EC		1230	R	SCALR	004FA	
1240	R	SCALR	00509		1320	R	SCALR	0052C		1340	R	SCALR	00566	
1345	R	SCALR	002A5		1365	R	SCALR	002C7		1369	R	SCALR	00348	
1400	R	SCALR	00589		1440	R	SCALR	005D2		1450	R	SCALR	005E8	

1460	005EC	1470	005FA	1500	005FD	1510	00601	1530	000DE	1600	00604
1700	00606	1710	00617	1720	00619	1730	00621	1740	00623	1750	00623
9573	003E4	9876	0063A								

LOCAL VARIABLES (2494 WORDS):

00000	IDATA	00400	XX	00500	YY	00700	EXX	00730	WYE	00760	EEE
00700	ENN	00700	VEE	00800	XC0F	00807	YCRF	00800	N	00850	IHR
00850	IMN	00800	RANGE	00802	RATE	00924	AZ	00956	EL	00923	SATIE
00900	SATID	00900	DAY	00908	MIN	00980	HR	00980	SEC	00980	DEL
00900	GRN1	00900	GRN2	00991	ISLASH	00992	IEND	00993	ISLANK	00994	YEAR
00995	MBN	00996	DAY	00997	I	00998	J	00999	IND	0099A	RR
00998	IJK	00990	ITIM	0099D	JTIM	0099E	NC	0099F	IB	009A0	HHR
009A1	KMIN	009A2	J4	009A3	NP	009A4	ICS	009A5	K0	009A6	NXB
009A7	NYB	009A8	NREC	009A9	IFLAG	009AA	M	009AB	L	009AC	K
009AD	IH	009AE	IM	009AF	IS	009B0	AX	009B1	AY	009B2	YL
009B3	NR	009P4	XXX	009B5	YYY	009B6	XAA	009B7	YAA	009B8	JA
009B9	JB	009RA	XD0T	009B8	YD0T	009BC	II	009BD	ITF		

BLANK COMMON (0 WORDS)

INTRINSIC SUBPROGRAMS USED:

AES	ATAN	SGRT
-----	------	------

EXTERNAL SUBPROGRAMS REQUIRED:

COEF	EOFSET	EXIT	INTERP0L	F:101	F:108	M:00	9ATAN1
9ATAN2	9BCCRDEE	9BCDREAD	9BCDARIT	9BINREAD	9BINWRIT	9BKSPACE	9ENDI0L
9INITIAL	9IEDATA	9IELUSA	9IT0R	9PRINT	9REWIND	9RTGI	9SORT
9STOP							

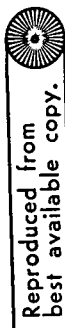
HIGHEST ERROR SEVERITY: 0 (NO ERRORS)

GENERATED CODE:	1609	00649
CONSTANTS:	17	00011
LOCAL VARIABLES:	2424	0099E
TEMP:	2	00002
TOTAL PROGRAM:	4122	0101A

```

1: SUBROUTINE INTERPOL(A,COF,NN)
2: DIMENSION A(900),COF(5)
3: EN=NN
4: T=-1
5: DO 1 I=1,NN
6:   A(I)=COF(1)+COF(2)*T+COF(3)*T+COF(4)*T+T+COF(5)*T+T+T+T
7:   T=T+1./EN
8: RETURN
9: END

```



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NAME	TYPE	CLASS	HEX L0C	DEC WORDS	NAME	TYPE	CLASS	HEX L0C	DEC WORDS
A	R	ARRAY	*00004	V DUMMY	CGF	R	ARRAY	*00005	V DUMMY
I	I	SCALR	00003	V 1	INTERP0L	R	SPREG	00000	P
NN	I	SCALR	*00006	V DUMMY	T	R	SCALR	00002	V 1

HEX L0C	HEX L0C	HEX L0C	HEX L0C	HEX L0C
1 00C2A				

LOCAL VARIABLES (4 WORDS):

00000 INTERP0L 00001 EN 00002 T 00003 I

BLANK COMMON (0 WORDS)

ENTRY POINTS:

00000 INTERP0L

EXTERNAL SUBPROGRAMS REQUIRED:

M:09 9ITER 9SETUPN

HIGHEST ERROR SEVERITY: 0 (NO ERRORS)

	DEC WORDS	HEX WORDS
GENERATED CODE:	51	00033
CONSTANTS:	2	00002
LOCAL VARIABLES:	4	00004
TEMPS:	7	00007
TOTAL PROGRAM:	64	00040

```

1: SUBROUTINE COFF(R,CUF)
2: DIMENSION B(5),CUF(5)
3: DEL1=B(2)-B(1)
4: DEL2=B(3)-B(2)
5: DEL3=B(4)-B(3)
6: DEL4=B(5)-B(4)
7: CUF(1)=B(3)
8: CUF(4)=(-DEL3-DEL2+DEL1+DEL4)/12.
9: CUF(5)=(-3.*DEL3+3.*DEL2+DEL4-DEL1)/24.
10: CUF(2)=(DEL3+DEL2-2.*CUF(4))/2.
11: CUF(3)=(DEL3-DEL2-2.*CUF(5))/2.
12: RETURN
13: END

```

NAME	TYPE	CLASS	HEX LBC	DEC WORDS	NAME	TYPE	CLASS	HEX LBC	DEC WORDS	NAME	TYPE	CLASS	HEX LBC	DEC WORDS
B	R	ARRAY	00005	V DUMMY	CDEF	R	SCALR	00000	V 1	CDEF	R	SCALR	00000	P 1
CUF	R	ARRAY	00006	V DUMMY	DEL1	R	SCALR	00001	V 1	DEL2	R	SCALR	00002	V 1
DEL3	R	SCALR	00003	V 1	DEL4	R	SCALR	00004	V 1					

LOCAL VARIABLES (5 WORDS):

00000 CDEF	00001 DEL1	00002 DEL2	00003 DEL3	00004 DEL4
------------	------------	------------	------------	------------

BLANK COMMON (0 WORDS)

ENTRY POINTS:

00000 CDEF

EXTERNAL SUBPROGRAMS REQUIRED:

M:00 9SETUP2

HIGHEST ERROR SEVERITY: 0 (NO ERRORS)

	DEC WORDS	HEX WORDS
GENERATED CODE:	69	00045
CONSTANTS:	4	00004
LOCAL VARIABLES:	5	00005
TEMPS:	4	00004
TOTAL PROGRAM:	82	00052

MESSAGE TAPE: ENV#: GSFC PREDICTION TAPE (ENV)
ASSIGN M:BG,(DEVICE,CPB04)
FORTRAN SI,G0,RT

1: INTEGER SATID,HR,SEC,DAY,DEL
55: END

NAME	TYPE	CLASS	HEX L9C	DEC WORDS	NAME	TYPE	CLASS	HEX L9C	DEC WORDS	NAME	TYPE	CLASS	HEX L9C	DEC WORDS
DAY	I	SCALR	00003 V	1	DAY	I	SCALR	00006 V	1	DEL	I	SCALR	00004 V	1
EXIT	I	SPROG	EXTERN	4800	HR	I	SCALR	00001 V	1	I.	I	SCALR	012CC V	1
IDATA	I	ARRAY	00009 V	1	IEND	I	SCALR	00008 V	1	IND	I	SCALR	012CE V	1
ISLASH	I	SCALR	00007 V	1	J	I	SCALR	012CD V	1	KK	I	SCALR	012CA V	1
MIN	I	SCALR	012CB V	1	MGN	I	SCALR	012C9 V	1	SATID	I	SCALR	00000 V	1
SEC	I	SCALR	00002 V	1	YEAR	I	SCALR	00005 V	1					

LABEL	HEX L9C	LABEL	HEX L9C	LABEL	HEX L9C	LABEL	HEX L9C
100 00036	101 0009A	102 000A0	103 000A3	104 000A6	105 000A9		
106 000AC	107 000B3	108 000C1	109 000D1	110 000DD	111 000EB		
112 000F8	113 000FB	201 00045	202 00052	203 00067	205 00079		
301 00036	305 00104						

LOCAL VARIABLES (4915 WORDS):

00000 SATID	00001 HR	00002 SEC	00003 DAY	00004 DEL	00005 YEAR
00006 DAY	00007 ISLASH	00008 IEND	00009 IDATA	012C9 MGN	012CA KK
012CB MIN	012CC I	012CD J	012CE IND		

BLANK COMMON (0 WORDS)

EXTERNAL SUBPROGRAMS REQUIRED:

EXIT	F:108	M:08	SBCDRDEE	9BCDRFAD	9ENDI0L	9INITIAL	9I0DATA
SPRINT	9REXIND	9STOP					

HIGHEST ERROR SEVERITY: 0 (NO ERRORS)

	DEC WORDS	HEX WORDS
GENERATED CODE:	266	0010A
CONSTANTS:	2	00002
LOCAL VARIABLES:	4815	012CF
TEMPS:	0	00000
TOTAL PROGRAM:	5083	0130B



HIGHEST ERROR SEVERITY: 0 (NO ERRORS)

	DEC	HEX
WORDS	WORDS	WORDS
GENERATED CODE:	266	0010A
CONSTANTS:	2	00002
LOCAL VARIABLES:	4815	012CF
TEMPS:	0	00000
TOTAL PROGRAM:	5083	013DB

NAME	TYPE	CLASS	HEX L8C	DEC W8RDS	NAME	TYPE	CLASS	HEX L8C	DEC W8RDS	NAME	TYPE	CLASS	HEX L8C	DEC W8RDS
DAY	I	SCALR	00003 V	1	DAY	I	SCALR	00006 V	1	DEL	I	SCALR	00004 V	1
EXIT	I	SFRUG	EXTERN		HR	I	SCALR	00001 V	1	I	I	SCALR	012CC V	1
IDATA	I	ARRAY	00009 V	4800	IEND	I	SCALR	00008 V	1	IND	I	SCALR	012CE V	1
ISLASH	I	SCALR	00007 V	1	J	I	SCALR	012CD V	1	KK	I	SCALR	012CA V	1
MIN	I	SCALR	012CB V	1	MGN	I	SCALR	012C9 V	1	SATID	I	SCALR	00000 V	1
SEC	I	SCALR	00002 V	1	YEAR	I	SCALR	00005 V	1					

LABEL	HEX L8C	LABEL	HEX L8C	LABEL	HEX L8C
100 00096	101 0009A	102 000A0	103 000A3	104 000A6	105 000A9
106 000AC	107 000B8	108 000C1	109 000D1	110 000DD	111 000EB
112 000F8	113 000FB	201 00045	202 00052	203 00067	205 00079
301 00036	305 00104				

LOCAL VARIABLES (4815 WORDS):

00000 SATID	00001 HR	00002 SEC	00003 DAY	00004 DEL	00005 YEAR
00006 DAY	00007 ISLASH	00008 IEND	00009 IDATA	012C9 MGN	012CA KK
012CB MIN	012CC I	012CD J	012CE IND		

BLANK COMMON (0 WORDS)

EXTERNAL SUBPROGRAMS REQUIRED:

EXIT	F:108	M:D9	9BCORDEE	9BCDREAD	9END18L	9INITIAL	9I0DATA
9PRINT	9REWIND	9STOP					

53: 305 REWIND 9
54: CALL EXIT
55: END

```

53: GO TO 120
54: 105 IF (STAT1(23)+STAT1(24)) 115,115,110
55: 110 MODE1=SLAVE
56: IF (STAT1(23).EQ.1) MODE2=ONE
57: IF (STAT1(24).EQ.1) MODE2=TWO
58: GO TO 120
59: 115 IF (STAT1(25).EQ.1) MODE1=STBW
60: IF (STAT1(26).EQ.1) MODE1=AUTO
61: IF (STAT1(27).NE.1) GO TO 120
62: MODE1=PRSG
63: IF (STAT2(21).EQ.1) MODE2=AUG
64: IF (STAT2(23).EQ.1) MODE2=MAN
65: IF (STAT2(21)+STAT2(23).EQ.2) MODE2=MANAUG
66: 120 CONTINUE
67: IF (STAT2(15).EQ.1) SCAN=YES
68: IF (STAT2(22).EQ.1) RCVR=YES
69: IF (IS.AE.0) GO TO 200
70: PRINT 10
71: PRINT 11
72: PRINT 12
73: 200 PRINT 13, IH, IM, IS, JH, JM, JS, RX, CX, RY, CY, PEX, PEY, REX, REY, MODE1, MODE2
74: 1, SCAN, RCVR
75: MODE1=BLANK
76: MODE2=BLANK
77: SCAN=0
78: RCVR=0
79: GO TO 20
80: 4 STOP
81: 10 FORMAT(1, REAL COMMAND REAL COMMAND P
82: 1 PROGRAM RECEIVE RECEIVE OPERATION SCAN RCVR')
83: 11 FORMAT(1, TIME X ANGLE X ANGLE Y ANGLE Y ANGLE X
84: 1 ERROR Y ERROR X ERROR Y ERROR MODE LOCK')
85: 12 FORMAT(1, H M S H P S DEGREES DEGREES DEGREES DEGREES D
86: 1 DEGREES DEGREES DEGREES DEGREES)
87: 13 FORMAT(3I3,1X,3I3,8F9.3,1X,2(1X,A4),2(2X,A4))
88: 555 FORMAT (7CX,2(5X,11,4(1X,4I1)),4X,11)
89: END

```

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DEC
WORDS

HEX
WORDS

GENERATED CODE: 394
CONSTANTS: 9
LOCAL VARIABLES: 682
TEMPS: 0

TOTAL PROGRAM: 1085

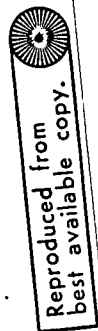
0018A
000C9
002AA
00000

0043D

```

1: INTEGER SATID,HR,SEC,DAY,DEL
2: INTEGER YEAR, DAY
3: DATA ISLASH/4H/ /, IEND/4H MSG/
4: DIMENSION IDATA(200,24)
5: READ(9,100) DAY, YEAR, M0N, DAY
6: READ(9,105) SATID
7: KK=0
8: IF(SATID.EQ.6903701) KK=3
9: IF(SATID.EQ.7002501) KK=4
10: PRINT 106, KK
11: PRINT 107, SATID
12: PRINT 108, DAY, M0N, YEAR
13: PRINT 109, DAY
14: PRINT 110
15: PRINT 111
16: PRINT 112
17: GO TO 201
18: 301 READ(9,100,END=305) DAY, YEAR, M0N, DAY
19: READ(9,105) SATID
20: 201 READ(9,101,END=305) DAY, HR, MIN, SEC, DEL
21: I=1
22: 202 READ(9,103) (IDATA(I,J), J=1,24)
23: IF(IDATA(I,4).EQ.ISLASH) GO TO 203
24: I=I+1
25: GO TO 202
26: 203 I=I-1
27: DEL=DEL+I-4
28: MIN=MIN+2
29: IF(MIN.LT.60) GO TO 205
30: MIN=MIN-60
31: HR=HR+1
32: IF(HR.LT.24) GO TO 205
33: HR=HR-24
34: DAY=DAY+1
35: 205 PRINT 113, DAY, (IDATA(I+1,J), J=6,10), HR, MIN, SEC, DEL
36: READ(9,104) INC
37: IF (INC.EQ.IEND) GO TO 301
38: GO TO 201
39: 100 FORMAT (/13,1X,3I2)
40: 101 FORMAT (2X,13,1X,3I2,1X,13)
41: 102 FORMAT (6I3)
42: 103 FORMAT (24A1)
43: 104 FORMAT (/4X,A4)
44: 105 FORMAT (17////)
45: 106 FORMAT ('1
46: 107 FORMAT ('OSATFLLITE ID NUMBER: ',I7)
47: 108 FORMAT ('PERIOD STARTING (DAY,MONTH,YEAR): ',I2,1X,I2,1X,I2,1X,I2)
48: 109 FORMAT('
49: 110 FORMAT ('JULIAN ORBIT
50: 111 FORMAT (' DAY
51: 112 FORMAT ('
52: 113 FORMAT (3X,13,6X,5A1,3(4X,I2),5X,I2)

```



```

1: INTEGER STAT1(32),STAT2(32),DATABASE(512)
2: INTEGER MAX/'MAN'//,STOW/'STOW'//,SLAVE/'SLAVE'//,
3: 1AUG/'AUG'//,PRG/'PRG'//,POS/'POS'//,T8/'12 X'//,8NE/'11 X'//
4: INTEGER BLANK/' '//,MANAUG/'MANAUG'//,AUG/'AUG'//,VEL/'VEL'//
5: INTEGER YES/'YES'//,NO/'NO'//,SCAN,RCVR
6: INTEGER ENCX(32),ENCY(32)
7: DATA Z/16383/
8: PRINT 10
9: PRINT 11
10: PRINT 12
11: REWIND 9
12: 20 CALL BUFFER IN (9,1,DATABASE,512,J,N)
13: 2 GO TO (2,3,4,3),J
14: 3 RT=DATABASE(57)
15: CT=DATABASE(59)
16: RX=DATABASE(44)
17: RY=DATABASE(45)
18: FLAG=C
19: IF (RX-RXPAST).EQ.0)FLAG=1
20: IF (RY-RYPAST).EQ.0)FLAG=2
21: RXPAST=RX
22: RYPAST=RY
23: CX=DATABASE(60)
24: CY=DATABASE(61)
25: PEX=DATABASE(110)
26: PEY=DATABASE(111)
27: WEX=DATABASE(33)
28: WEY=DATABASE(39)
29: IH=CT/3600
30: TN=RT-3600.*IH
31: IM=TN/60.
32: IS=TN-60.*IM
33: JH=CT/3600
34: SH=CT-3600.*JH
35: SM=SH/60.
36: SS=SH-60.*JM
37: RX=(RX*100.)//Z
38: RY=(RY*100.)//Z
39: CX=(CX*100.)//Z
40: CY=(CY*100.)//Z
41: PEX=(PEX*10.)//Z
42: PEY=(PEY*10.)//Z
43: WEX=(WEX*10.)//Z
44: WEY=(WEY*10.)//Z
45: CALL IXBIT(1,DATABASE(10),ENCX)
46: CALL IXBIT(1,DATABASE(11),ENCY)
47: CALL IXBIT (1,DATABASE(49),STAT1)
48: CALL IXBIT (1,DATABASE(50),STAT2)
49: IF (STAT1(21)+STAT1(22)) 105,105,100
50: 100 MODE1='MAN'
51: IF (STAT1(21).EQ.1) MODE2='PS'
52: IF (STAT1(22).EQ.1) MODE2='VEL'

```