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*Addendum*

*ELAS—A General-Purpose Computer Program for the  
Equilibrium Problems of Linear Structures*

*Volume II. Documentation of the Program*

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## **Preface**

The work described in this report was performed by the Engineering Mechanics Division of the Jet Propulsion Laboratory.

The program was developed by Dr. Senol Utku and Dr. Fevzican A. Akyuz, and is dedicated to the memory of Professor M. Inan of the Technical University of Istanbul.

## **Acknowledgment**

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## Abstract

A general-purpose digital computer program (named ELAS) for the in-core solution of linear equilibrium problems of structural mechanics is described for potential and actual users in Volume I of this report, and is documented in Volume II. The program requires minimum input for the description of the problem. The solution is obtained by means of the displacement method and the finite element technique. Almost any geometry and structure may be handled because of the availability of lineal, triangular, quadrilateral, tetrahedral, hexahedral, conical, triangular torus, and quadrilateral torus elements. The assumption of piecewise linear deflection distribution insures monotonic convergence of the deflections from the stiffer side with decreasing mesh size. The stresses are provided by the best-fit strain tensors in the least-squares sense at the mesh points where the deflections are given. The selection of local coordinate systems whenever necessary is automatic. The core memory is efficiently used by means of dynamic memory allocation, an optional mesh-point relabelling scheme, imposition of the boundary conditions during the assembly time, and the straight-line storage of the rows of the stiffness matrix within variable bandwidth and the main diagonal. The number of unsuppressed degrees of freedom that can be handled in a given problem is 500 to 600 for a typical structure, but might far exceed these average values for special types of problems; the execution time of such problems is about four minutes in 32K IBM 7094 Model I machines. The program is written in FORTRAN II language. The source deck consists of about 8000 cards and the object deck contains about 1400 binary cards. The physical program (standard ELAS) is available from COSMIC, the agency for the distribution of NASA computer programs.

## I. Introduction

Volume I, *User's Manual*, of this report gives a general description of ELAS,\* a general-purpose digital computer program for the in-core solution of linear equilibrium problems of structural mechanics, and contains the information necessary for input preparation, arrangement of the physical program, and interpretation of output and error messages. Volume II, *Documentation of the Program*, is published in two parts: the basic Volume II, which gives the theoretical background of the program and contains tables and figures describing the COMMON variables, their meanings, and their arrangement in COMMON; and this report—Addendum to Volume II—which contains program descriptions, flowcharts, and source program listings for all program elements of ELAS/Level 3. (The original version of the ELAS program made available from COSMIC\*\* in April 1968 is designated ELAS/Level 0. Subsequent program corrections made in January 1969, March 1969, and May 1969 updated the program to ELAS/Level 1, ELAS/Level 2, and ELAS/Level 3, respectively.)

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\* First two syllables of the word Elasticity.

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Sections II, III, IV, and V of the Addendum briefly describe the main programs and the subroutines of Links 1, 2, 3, and 4, respectively, of the ELAS program with reference to the flowcharts illustrated in Section VI, and the source program listings given in Section VII. Program descriptions include all subroutines that are not in the FORTRAN library. The standard ELAS is coded in FORTRAN II, with the exception of subroutines LEBIN, SEBIN, and TICK, which are in FAP. The subroutines are described in alphabetical order under each main program. The flowcharts, which are also in alphabetical order, present semidetained diagrams of the sequential logic and decision points in the program. The source program listings are a straight listing of the first file in the program tape that contains the physical program.

The user of this Addendum will need both Volume I and the basic Volume II for reference because of numerous cross-references to figures and tables contained therein. The information in the referenced figures and tables is essential to interpretation of the content of the Addendum. Reference is also made herein to program input and output items and error messages, which are described and identified by number in Volume I.



## II. Main Program and Subroutines of Link 1

### A. Main Program of Link 1

The flowchart and the source program listing of the main program of Link 1 are given in Fig. VI-1 and Table VII-1, respectively. The logical function of the program may be summarized as follows:

- (1) It defines IN, IT, IDEG, ITYPE, IGEM, ISTR, IH, IS, IBN, IP, IPRS, IMAT, NTIC, ISDT, ISDY, ISDZ, IARE, IMMX, IMMY, IMMZ, IMFI, INX, INP, ISHUF, ICOR, IBUN, IMES, IPIR, ITAP, ITAS, G1, G2, G3, ACEL directly from Input Item 2.
- (2) It computes constants ISUM, IND, IORD, IORD1, and ZGEM, and pointers J1, J2, J3, J4, J5, J6, J7, J8, J9, J10, IBB, IBO, IID, IIA, IDT, IDY, ITE, ICAR, ICIX, ICIIY, ICIZ, ICFI, IXX, IYY, IZZ, IIC, IDEF, IST, IIS, IU, and IDZ from the information given by Input Item 2.
- (3) It generates the vectors related with pointers J1, J2, J3, J4, J5, J6, J7, J8, J9, J10, IBB, IBO, IIC, IXX, IYY, IZZ, and IDEF (partially) directly or indirectly from the input information of the job.
- (4) Depending upon the value of INX, it transfers control either to statement 2700 or to the main program of Link 3.

Before using any input information, the main program checks it against the input specifications (see Sect. III and IV, Vol. I). If the program encounters an irrecoverable error in the input information, it always branches to statement 300, which prints out COMMON both in fixed- and floating-point modes and skips the related job. In transferring information from input cards into the proper locations in COMMON, the program uses DUMMY (also called IDUM) area in COMMON for temporary storage. The main program calls subroutine TABL to print out Output Item 1; subroutine TICK to measure time; subroutine BUNG to generate deflection boundary conditions (dbc) input units automatically, if IBUN = 1; subroutine CORG to generate coordinates of the nodes automatically, if ICOR = 1; subroutine MESH to generate mesh topology and element properties automatically, if IMES = 1; subroutine COOR to read in, examine, and store nodal coordinates; subroutine MEST to read in and store element data; subroutine TOPO to examine and separate the element data in storage; and finally, subroutine SRAT to obtain internal node labels in vector ISIR, and the highest internal label in the node set of each node in vector IMAX (refer to Input Item 17, Sect. IV, Vol. I). Among these subroutines, subroutine SRAT has its own subroutine. The contribution of the prescribed concentrated loads to the right-hand-side vector of the equilibrium equations before the displacement boundary conditions are imposed is stored in the

IDEF-pointer-related vector, first as in item (1) of the IDEF entry of Table III-3, Vol. II (basic), and then as in item (2) in the same entry. Probably the most important function of the main program is the generation of vectors defined by pointers IBB, IBO, and IIC. The meanings of the entries of these vectors are given in Table III-3, Vol. II (basic), and Table VI-2, Vol. I. These vectors are first generated as if all deflections were independent and with IBB numbers always equal to  $IND + 1$ . Then the numbers are modified with the dbc input units to recognize linear dependence. Finally, when vectors ISIR and IMAX are provided by subroutine SRAT, they are finalized. Vectors defined by pointers IBB, IBO, and IIC are first used in the main program to compute the contribution of the prescribed concentrated loads to the reduced right-hand-side vector in the IDEF-pointer-related vector. Later in Link 2, they are used in computing the contributions of the element stiffness matrices to the reduced stiffness matrix in the IST-pointer-related vector and the reduced load vector in the IDEF-pointer-related vector, and the contributions of the element load vectors to the reduced load vector in the IDEF-pointer-related vector. In Link 3, these three vectors are used in obtaining the deflections of all nodes from the reduced deflection vector in the IDEF-pointer-related vector. The standard ELAS Link 1 main program assumes that  $IN \leq 540$  and  $ISUM < 10000$ . (See Appendix, Vol. I, for instructions on how to change these limits.)

## B. Subroutines of Link 1

1. **Subroutine ARAN.** Subroutine ARAN is called by subroutine SRAT. The flowchart and the source program listing of ARAN are given in Fig. VI-2 and Table VII-2, respectively. The logical function of the subroutine may be summarized as follows:

- (1) Subroutine ARAN generates vector IMAX for subroutine SRAT.
- (2) If  $0 < ISHUF < 3$ , the subroutine modifies vector ISIR and computes vector IMAX accordingly, to minimize the shaded area of the coefficient matrix shown in Fig. II-1 (Vol. I).
- (3) If  $ISHUF = 2$ , the subroutine reads cards for vector ISIR, modifies matrix ABIN accordingly, and performs the function given in (2).
- (4) The subroutine produces relabelling output items (Output Item 5) according to Sect. VI-F, Vol. I.

In performing these tasks, subroutine ARAN expects that connectivity matrix ABIN, ISIR vector of labels,

row order IN, and column order ISUR of matrix ABIN are available in COMMON. In performing logical function (2), the subroutine also generates vector IMIN. Subroutine ARAN calls subroutine OUTPT to print out mesh topology (P) of Output Item 5 (see Sect. VI-F, Vol. I), subroutine EXCH to interchange to successive rows and their respective columns in the connectivity matrix ABIN, function LEBIN to find out if a node is connected with another node, and subroutine TICK to measure relabelling time. The algorithm for logical function (2) is given in Ref. 1. The standard ELAS assumes that a word consists of 36 binary bits, and this is assumed in subroutine ARAN. (See Appendix, Vol. I, for instructions on how to change this constraint.)

2. **Subroutine BUNG.** Subroutine BUNG is called by the main program of Link 1, if  $IBUN = 1$ . The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-3. If  $IBUN = 1$ , the subroutine should be rewritten by the user, as explained in Sect. V-D, Vol. I. The logical function of the subroutine is to place IBN number of dbc input units into DUMMY or IDUM area.

3. **Subroutine COOR.** Subroutine COOR is called by the main program of Link 1, if  $ICOR = 0$ . The flowchart and the source program listing of COOR are given in Fig. VI-3 and Table VII-4, respectively. The function of this subroutine is to read the cards of Input Item 14 in blocks of not greater than 1000 nodes, to examine whether the node labels are sequential, and to generate IXX-, IYY-, and IZZ-pointer-related vectors. If  $IGEM = 0$ , the IZZ-pointer-related vector will not be generated. In case of error, the subroutine returns control to the calling program with  $IERR = 1$ , without completing its function.

4. **Subroutine CORG.** Subroutine CORG is called by the main program of Link 1, if  $ICOR = 1$ . The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-5. If  $ICOR = 1$ , the subroutine should be rewritten by the user, as explained in Sect. V-B, Vol. I. The logical function of this subroutine, when  $ICOR = 1$ , is to generate vectors related with pointers IXX, IYY, and IZZ.

5. **Subroutine EXCH.** Subroutine EXCH is called by subroutine ARAN. The flowchart and the source program listing of EXCH are given in Fig. VI-4 and Table VII-6, respectively. The function of this subroutine is to interchange the  $I$ th row with the  $IP$ th row of the ABIN matrix, and  $I$ th binary column with the  $IP$ th binary column

of the same matrix; MI is the smallest binary column number of the first nonzero binary entry either in row I or in row IP; MX is the largest binary column number of the last nonzero binary entry either in row I or in row IP. Since ABIN is a symmetric binary matrix, MI and MX also define the limits of the *I*th and *IP*th columns. Interchange operation is carried out only within these limits. The subroutine expects ABIN, I, IP, MI, and MX to be available in COMMON, and it assumes that a word consists of 36 binary bits. (See Appendix, Vol. I for instructions on how to change this limit.) Subroutine EXCH calls function LEBIN to obtain the value of a certain bit of a word, and subroutine SEBIN to store 1 or 0 in a certain bit of a word.

**6. Function LEBIN.** The subprogram LEBIN is called by subroutines ARAN and EXCH. The flowchart and the source program listing of LEBIN are given in Fig. VI-5 and Table VII-7, respectively. The coding is in FAP for the IBM 7094. The logical function of LEBIN is to return as a FORTRAN integer the value of the bit, shown in the second argument, of the word shown in the first argument. It assumes that the word length is 36 binary bits. For any other machine, this function should be rewritten.

**7. Subroutine SEBIN.** Subroutine SEBIN is called by subroutines EXCH and SRAT. The flowchart and the source program listing of SEBIN are given in Fig. VI-6 and Table VII-7, respectively. The coding is in FAP for the IBM 7094. The logical function of SEBIN is to store 1 or 0 (as shown in the third argument) in to the bit (shown in the second argument) of the word (shown in the first argument). The subroutine assumes that a word consists of 36 binary bits. For any other machine, this subroutine should be rewritten.

**8. Subroutine MESC.** Subroutine MESC is called by the main program of Link 1, if  $IMES = 1$ . The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-8. If  $IMES = 1$ , the subroutine should be rewritten by the user, as explained in Sect. V-C, Vol. I. The logical function of this subroutine, when  $IMES = 1$ , is to generate vectors related with pointers J1, J2, J3, J4, J5, J6, J7, J8, J9, and J10.

**9. Subroutine MEST.** Subroutine MEST is called by the main program of Link 1, if  $IMES = 0$ . The flowchart and the source program listing of MEST are given in Fig. VI-7 and Table VII-9, respectively. The function of this subroutine is first to read the cards of Input Item 16, one or more at a time, into DUMMY area, and to check

the validity of M number of the element descriptors (see Table IV-3, Vol. I), then to store words J1W, J2W, J3W, J4W, J5W, and if they exist, J6W, J7W, J8W, J9W, J10W of the element descriptors into the proper locations in the respective vectors related with pointers J1, J2, J3, J4, J5, J6, J7, J8, J9, and J10, and to check the positiveness of the vertex labels. In case of error, the subroutine returns control to the calling program with  $IERR = 1$ , without completing its function. If no error is encountered, the subroutine performs its operations on the input cards of every element, sequentially, until all element data are processed.

**10. Subroutine OUTPT.** Subroutine OUTPUT is called by subroutine ARAN, if  $INP = 2$ . The flowchart and the source program listing of OUTPT are given in Fig. VI-8 and Table VII-10, respectively. The function of this subroutine is to print out Output Item 5(P) (see Sect. VI-F, Vol. I). This subroutine assumes that a word is 36 binary bits and  $IN \leq 540$ . (See Appendix, Vol. I for instructions on how to change these limits.) Subroutine OUTPT expects ISIR, IMIN, IMAX vectors, ABIN matrix, IN, and ISUR to be available in COMMON.

**11. Subroutine SRAT.** Subroutine SRAT is called by the main program of Link 1. The flowchart and the source program listing of SRAT are given in Fig. VI-9 and Table VII-11, respectively. The functions of this program may be summarized as follows:

- (1) If  $ISHUF = 3$ , subroutine SRAT reads the cards of Input Item 17 for the generation of internal node labels in vector ISIR, and the highest internal label in the node set of each node in vector IMAX (refer to Input Item 17, Sect. IV, Vol. I). If  $ISHUF \neq 3$ , subroutine SRAT generates vector ISIR by assuming that internal and external labels of the nodes are the same; computes ISUR, which is the number of words whose binary bits are enough to provide one bit for each of the IN nodes; generates connectivity matrix ABIN from the mesh-topology information of Input Item 16 and from the deflection boundary condition input units already in the IBO-pointer-related vector; and calls subroutine ARAN to obtain the finalized values of vectors ISIR and IMAX. (In generating the binary connectivity matrix ABIN, subroutine SRAT first clears matrix ABIN; then it processes elements one at a time by first listing the labels of the vertices of the element and the labels of the nodes connected with these vertices through the dbc

input items; and then indicates, by means of a binary 1 in the proper places in matrix ABIN, the fact that all these nodes are connected with each other. In matrix ABIN, one row and one column are assigned to every node so that ABIN is a symmetric matrix. If a node  $i$  is connected with a node  $j$ , the  $i$ th row and the  $j$ th column, and likewise the  $j$ th row and the  $i$ th column, of the binary matrix ABIN contain a binary bit 1. All diagonal elements of the binary matrix ABIN are binary bit 1. If a node is constrained completely by means of dbc input items the only nonzero bit in the row and the column of this node is on the diagonal. The ordering of rows and columns of the binary matrix ABIN is done by the order that is available in vector ISIR.)

- (2) If  $INP \neq 0$ , subroutine SRAT generates and prints out Output Item 6.
- (3) It generates the vector related with pointer IU, and if  $INP \neq 0$ , prints it as Output Item 9.
- (4) It computes the number of words between points D and F, and between the beginning of COMMON and point G, designated in Fig. III-1, Vol. II (basic), and prints out Output Items 7 and 8.
- (5) It prints Error Message 5 (see Table VII-1, Vol. I) if the number of words to the left of point G is less than 12,750, which is based on the assumption that the core memory is 32,768 words. (See Appendix, Vol. I for instructions on how to modify the program for other core memory sizes.)

Subroutine SRAT calls subroutine TOPO in obtaining the vertex labels of the elements, subroutine SEBIN in generating binary matrix ABIN, and subroutine ARAN to obtain vector IMAX and the corresponding vector ISIR.

**12. Subroutine TABL.** Subroutine TABL is called by the main program of Link 1. The flowchart and the source program listing of TABL are given in Fig. VI-10 and Table VII-12, respectively. The function of this subroutine is to print out Output Item 1. It expects the contents of Input Items 1 and 2 to be available in COMMON.

**13. Subroutine TICK.** Subroutine TICK is called by the main program of Link 1. It is also called by subroutine ARAN and by the main programs of Links 2, 3, and 4. The flowchart and the source program listing of subroutine TICK are given in Fig. VI-11 and Table VII-13, respectively. The coding is in FAP for the IBM 7094. The subroutine expects the time in units of 1/60 second in the absolute memory location 5 as a binary integer. Its function is to return, as a FORTRAN integer in the argument, the time, in 1/60-second units, elapsed since the first call. (See Appendix, Vol. I, for instructions on how to change this subroutine for other machines.)

**14. Subroutine TOPO.** Subroutine TOPO is called by the main program of Link 1. It is also called by subroutine SRAT. The flowchart and the source program listing of TOPO are given in Fig. VI-12 and Table VII-14, respectively. The function of this subroutine may be summarized as follows:

- (1) It extracts from J1-, J2-, J3-, J4-, J5-, J6-, J7-, J8-, J9-, and J10-pointer-related vectors for the  $M$ th element the vertex labels in  $N_i$  vector, the pressure type number in JPRS, the material type number in IMET, the thickness type number in ITIC, the temperature increase type number in ITEM, the temperature gradient in  $y$ -direction type number in JSDY, the temperature gradient in  $z$ -direction type number in JSDZ, the cross-sectional area type number in JARE, the torsional constant type number in JMMX, the  $y$ -moment of inertia type number in JMMY, the  $z$ -moment of inertia type number in JMMZ, and the angle for principal axes type number in JMFI, as described in Table III-2 (Vol. II, basic).
- (2) It checks whether the vertex labels and the property type numbers are within the bounds prescribed in Input Item 2. In case of error, the subroutine continues scanning the properties of the  $M$ th element and prints out Error Message 3 (see Table VII-1, Vol. I) after executing the implementation of the message.

### III. Main Program and Subroutines of Link 2

#### A. Main Program of Link 2

The flowchart and the source program listing of the main program of Link 2 are given in Fig. VI-13 and Table VII-15, respectively. The logical function of the program may be summarized as follows:

- (1) It clears the reduced stiffness matrix area (the IST-pointer-related vector of Table III-3, Vol. II, basic).
- (2) It generates the elemental matrices in S and P areas, and assembles these into IST- and IDEF-pointer-related vectors, sequentially.
- (3) It stores on tape ITAS (if available) the elemental matrices, sequentially.
- (4) Depending upon the value of INX, it transfers control either to the main program of Link 1 or to the main program of Link 3.

In carrying out function (2) listed above, the program executes a DO-loop on element labels M. In this loop, for any element M, it first clears a certain work area (see block \*133 in Fig. VI-13) and sets the variables

ITTT = 0, ITTM = NAV = 1, and CFE = 1. Variable ITTM is not in COMMON. For element types 1, 2, 3, 4, 5, 7, 9, 11, 13, 15, 17, and 18, ITTM = NAV = 1 and CFE = 1., and ITTT is made 1 at block 5100 of Fig. VI-13. For the remaining element types, that is, element types 6, 8, 10, 12, 14, and 16, the program establishes subelements as described in Table VI-5 (Vol. I). For element types 6, 8, 12, 14, and 16, the program obtains two triangles for every quadrilateral in two ways, as shown in Table VI-5 (Vol. I). Since such a procedure is equivalent to doubling the material volume of the structure, the elemental matrices are weighted with constant CFE = 1/2 (See block 4902 of Fig. VI-13); ITTM is the number of the subelements and ITTT is the subelement count in each way of subdivision, and NAV - 1 is the count of subdivisions. For example, NAV = 2, ITTT = 2 means the second triangle of the first way of subdivision, and NAV = 3, ITTT = 1 means the first triangle of the second way of subdivision. The same symbolism applies for element type 10, where ITTM = 5, which indicates that there are five tetrahedrons for every way of subdividing an hexahedron. The subdivision procedure is achieved as indicated in block 504 of Fig. VI-13, with the help of subroutine CUTE.

In the DO-loop on elements, after the initialization of block \*133 (Fig. IV-13), by means of subroutine TOPO, the descriptive words of the element (the quantities listed in J1- through J10-pointer-related vectors) are extracted and analyzed to obtain the vertex labels in N block and the property type numbers. Next, the vertex labels are copied to NOO block in preparation for the subdivision operation and IMS is established. Following this, the order of the element stiffness matrix IDS is determined, actual values of load and geometry constraints are obtained, and the material constants are prepared. Even if an element is subdivided, the same load, geometry, and material constants are used for the subelements. The following constants are prepared, as explained in Sect. III-C, Vol. I: E and G for element types 1, 2, 3, and 4; D21 for element types 9, 10, 15, and 16; D33 for element types 5, 6, 7, 8, 11, 12, 13, and 14; and E22 for element types 7, 8, 11, 12, and 18. The constant E is the Young's modulus, G is the shear modulus, D21 is the upper half of the  $6 \times 6$  material matrix, D33 is the material constants matrix for in-plane deformations, and E22 is the material constants matrix for out-of-plane deformations. Finally, arrays related with subelement vertex coordinates and labels are prepared (see block 5100, Fig. VI-13), the subelement count ITTT is set, and the number of entries in the free-free stiffness matrix, IDS2, is obtained; and S and P areas are cleared for elemental matrices of the subelement/element (see block 5600, Fig. VI-13).

In the DO-loop on elements, for every subelement/element, a free-free stiffness matrix and a load vector are generated in S and P, respectively. For this purpose the program calls subroutine STFS, which, in turn, calls the proper subroutine determined by the type number of the current element. These subroutines are S01, S02, S03, S04, S05, S07, S09, S11, S13, S15, S17, and S18. The numeral in these names corresponds to the type number of the element for which the subroutine is directly applicable. In all these subroutines, the input information is in X, Y, Z, XD, YD, ZD, DT, DG, DGY, DGZ, TE, AL1, AL2, AL3, E, G, D21, D33, E22, PRES, ACEL, N, CONS, UV, and COMMON 200-328 locations. The output consists of S, P, and sometimes IPBG and IPEN constants. The latter two constants indicate whether the element load vector in P is complete, or whether some additional operation is necessary in the main program. If IPBG is nonpositive and  $IPBG < IPEN$ , no additional operation is expected from the main program to modify load vector P. The thermal portion of load vector P is always completed by the main program. Before the subroutines

are called, the main program sets in vector UV the list of vertex deflections due to DT of the free-free element. The subroutines called by subroutine STFS modify this vector properly so that the portion of the element load vector due to temperature changes can be added to P as the product of the free-free stiffness matrix of the element (the quantities in S) times the deflections in UV by means of subroutine DMM. This is shown in block 951 of Fig. VI-13. In this figure, Block 953 corresponds to the inquiries on constants IPEN and IPBG. The modification to vector P in the main program consists of adding certain constant values derived from CONS, PRCO, and PD values to certain subvectors of P as indicated by IPEN and IPBG. The values of IPEN, IPBG, CONS, PRCO, and PD are determined by the subroutine that generates S and P.

After the generation of S and P in the DO-loop on elements, the main program scans each entry of S and P one at a time and assembles it to the governing equations of the system. This is the operation in block 9532 of Fig. VI-13, which ends just before block 95\*. The assembly procedure is described in Sect. II, Vol. II (basic). With the notation given there,  $\underline{a}$ ,  $\tilde{e}'_a$ ,  $i'_a$ , and  $\underline{b}$ ,  $\tilde{e}'_b$ ,  $j'_b$  are generated in IQE, CCCI, IBS and JQE, CCCJ, JBS locations of COMMON, respectively, by means of subroutine DARN. After the assembly of the subelement/element matrices S and P, if a scratch tape is available, the operations shown in block 9982 (Fig. IV-13) are for future reference. Next, ITTT is compared with ITTM, and the value of NAV (which is updated by subroutine CUTE) is inquired. When the last subelement of the last subdivision is completed, the process is repeated for the next element until all the elements are handled. Then, scratch tape ITAS (if prescribed) is rewound, the total time elapsed since the first entry to the main program is obtained by means of subroutine TICK and recorded, and the transfer of control is made.

The main program of Link 2 is also responsible for the production of Output Items 14, 15, 16, and 17, as prescribed by INP and subroutine CAS2 (see Table VI-1, Vol. I). At the end of Link 2, the coefficients in the shaded areas of Fig. II-1, Vol. I, are generated and stored in IST- and IDEF-pointer-related arrays of COMMON.

## B. Subroutines of Link 2

1. *Subroutine ADM.* Subroutine ADM is called by subroutines S05, S07, S09, S15, S17, and S18. The flow-chart and the source program listing of ADM are given

in Fig. VI-14 and Table VII-16, respectively. The subroutine has seven arguments. The function of the subroutine is to add a constant times a square matrix to another one which is symmetric. The constant is given by the seventh argument, the matrix to be added is given by the third argument, and the matrix to be increased is given by the first argument. The order of the latter matrix is given in the second argument, the order of the former by the fourth argument. Since the orders are different, the row and column numbers of the entry in the matrix of the first argument corresponding to the first entry of the matrix of the third argument are given with the fifth and sixth arguments. The addition operation is carried out such that the matrix of the first argument always remains symmetrical. Both matrices are assumed to be listed columnwise, with the column orders as prescribed by the second and fourth arguments. The order of the matrix in the third argument cannot be larger than 4. There is no error return of the subroutine. In all cases, the matrix in the first argument is the free-free stiffness matrix of various types of elements, and the matrix in the third argument is usually a submatrix related with given degree-of-freedom directions.

**2. Subroutine BEAM.** Subroutine BEAM is called by subroutines S02 and S04. The flowchart and the source program listing of BEAM are given in Fig. VI-15 and Table VII-17, respectively. This subroutine generates, in local coordinates, the free-free stiffness matrix of a planar beam element and stores it in A(6,6), which is located in COMMON (200). The matrix may be partitioned with respect to degrees of freedom (nine submatrices,  $2 \times 2$  each). In generation of the stiffness matrix, the shear deformations are ignored.

**3. Subroutine CAS2.** Subroutine CAS2 is called by the main program of Link 2. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-18. If Output Items 14, 15, and 16 are to be produced selectively, the subroutine should be rewritten by the user, as explained in Sect. V-G, Vol. I. The logical function of this subroutine is to change the value of INP as desired in the DO-loop on elements of the main program of Link 2.

**4. Subroutine CODI.** Subroutine CODI is called by subroutines S02, S03, and S04. The flowchart and the source program listing of CODI are given in Fig. VI-16 and Table VII-19, respectively. The subroutine generates the direction cosines of the local axes for element types 2, 3, and 4 in DIR(3,3) array, which is located in

COMMON(264). The first row of DIR corresponds to local  $x$ -axis, the second row corresponds to local  $y$ -axis, and the third row corresponds to local  $z$ -axis. (See Table III-3, Vol. I, and the description of Input Item 13, Sect. IV-B, Vol. I, for the rules covering the local coordinate systems of these elements.) The subroutine sets IERR = 1 and returns control to the calling program as soon as an error is detected.

**5. Subroutine CORT.** Subroutine CORT is called by subroutines S11 and S13. The flowchart and the source program listing of CORT are given in Fig. VI-17 and Table VII-20, respectively. The subroutine generates the direction cosines of the local coordinate axes for elements 11 and 13 in DIR(3,3) array, which is located in COMMON(264). The first, second, and third rows of DIR correspond to the first, second, and third local axis, respectively. (See Table III-3, Vol. I, for the rules in selecting the local coordinate system for elements 11 and 13.) After computation of direction cosines, the subroutine replaces X, Y, and Z values with the coordinates of the vertices in a coordinate system located usually at the centroid of the element and yet parallel to the local coordinate system of the element. Next, the subroutine computes in XD, YD, and ZD the coordinates of the second and third vertex in a coordinate system that is located at the first vertex, yet is parallel to the local coordinate system of the element. There is no error return in the subroutine.

**6. Subroutine CUTE.** Subroutine CUTE is called by the main program of Link 2. The flowchart and the source program listing of the subroutine are given in Fig. VI-18 and Table VII-21, respectively. This subroutine has the ITTM value as an argument (see Sect. III-A). The subroutine is called twice for element types 6, 8, 10, 12, 14, and 16 and is not called for other types of elements. Each time it is called for an element, the subroutine increments NAV (see Sect. III-A) by 1; determines ITTM, IMS, IELT, IDS values for the subelements; and generates in NOO array the list of mesh-point labels that conform to the (NAV - 1)st row in part A or B of Table VI-5, Vol. I, depending upon whether the value of ITTM is 2 or 5, respectively. For example, for a quadrilateral element with mesh-point labels 13, 8, 51, 16, the value of ITTM is 2, and if NAV = 2, according to the first line of Table VI-5A, Vol. I, the NOO array contains the following list: 13, 8, 51, 51, 16, 13. There is no error return in the subroutine.

**7. Subroutine DARN.** Subroutine DARN is called by the main program of Link 2. The flowchart and the

source program listing of the subroutine are given in Fig. VI-19 and Table VII-22, respectively. The subroutine has four arguments. The last three arguments, KBS, CCC, and KQE, correspond to  $i'_a$ ,  $\tilde{e}'_a$ , and  $\underline{a}$  (or  $j'_b$ ,  $\tilde{e}'_b$ , and  $\underline{b}$ ), respectively, of Sect. II, Vol. II (basic). The first argument is the label of the degree-of-freedom direction under question (see Sect. III-A). To achieve this function, subroutine DARN interprets the entries of IBB-, IBO-, and IIC-pointer-related vectors, as described in Table VI-2, Vol. I. In case of error, the last argument is set to zero, and the subroutine returns control to the calling program.

**8. Subroutine DMM.** Subroutine DMM is called by the main program of Link 2. The flowchart and the source program listing of the subroutine are given in Fig. VI-20 and Table VII-23, respectively. The subroutine has four arguments. The first argument is a square matrix, and the second and fourth are vectors of order given by the third argument. The square matrix is assumed to be listed columnwise (the number and orders of the vectors being equal to the third argument). The subroutine adds on the vector in the fourth argument the product of the matrix in the first argument by the vector in the second argument. There is no error return in the subroutine.

**9. Subroutine ELDI.** Subroutine ELDI is called by subroutines S01, S02, and S04. The flowchart and the source program listing of ELDI are given in Fig. VI-21 and Table VII-24, respectively. The subroutine generates in vector PD the direction cosines of the pressure direction for element types 1, 2, and 4. (See description of Input Item 4, Sect. IV-B, Vol. I, and Table III-3, Vol. I, for the rule for determining the pressure direction.) If the element is in the general wind direction, the pressure is set to zero. If an error is encountered, IERR is set to 1, and the subroutine returns control to the calling program.

**10. Subroutine PLBE.** Subroutine PLBE is called by subroutines S03, and S04. The flowchart and the source program listing of PLBE are given in Fig. VI-22 and Table VII-25, respectively. This subroutine generates, in local coordinates, the free-free stiffness matrix of a grid beam element in A(6,6), which is located in COMMON(200). The matrix may be partitioned with respect to degrees of freedom (nine submatrices,  $2 \times 2$  each). In generation of the stiffness matrix, the shear deformations are ignored.

**11. Subroutine RLOC.** Subroutine RLOC is called by subroutines S02, S03, and S04. The flowchart and the

source program listing of RLOC are given in Fig. VI-23 and Table VII-26, respectively. Its function is similar to that of subroutine ADM, described in Sect. III-B. The arguments in this subroutine are all implicit. They are S, A, IDS, II, JJ, IR, JR, NY. The subroutine assumes that S is an  $IDS \times IDS$  matrix; A is a  $6 \times 6$  matrix. The objective of the subroutine is to put  $NY \times NY$  submatrix of matrix A on matrix S. The constants II and JJ are the row and column numbers of the first word of  $NY \times NY$  submatrix of matrix A. The constants IR and JR are the row and column numbers of the corresponding word in matrix S. In contrast to subroutine ADM, subroutine RLOC does not add, but replaces the entries of matrix A on S. After the replacement, the processed portion of A is nullified. There is no error return in the subroutine.

**12. Subroutine S01.** Subroutine S01 is called by subroutine STFS. The flowchart and the source program listing of S01 are given in Fig. VI-24 and Table VII-27, respectively. The subroutine generates in S the free-free stiffness matrix of element type 1 in the overall coordinate system, and determines constants PRCO, CONS, IPBG, and IPEN for the generation of load vector P (also in overall coordinates) in the main program of Link 2, as described in Sect. III-A. The portion of the load vector related with the temperature change is also handled in the main program of Link 2. To obtain the direction cosines of the unit vector in the pressure direction, subroutine S01 calls subroutine ELDI. When an error condition is encountered, subroutine S01 sets IERR to 1 and returns control to the calling program.

**13. Subroutine S02.** Subroutine S02 is called by subroutine STFS. The flowchart and the source program listing of S02 are given in Fig. VI-25 and Table VII-28, respectively. The subroutine generates in S the free-free stiffness matrix of element type 2 in the overall coordinate system, determines constants PRCO, CONS, IPBG, IPEN, and modifies vector UV so that load vector P expressed in overall coordinates can be generated by the main program of Link 2 (see Sect. III-A). By calling subroutine CODI, subroutine S02 first generates the direction cosines of the local axes in DIR(3,3). Then subroutine BEAM is called to generate in A(6,6) the free-free stiffness matrix of the element in the local coordinate system. The direction cosines of the direction normal to the element are obtained and stored in PD(3) by means of subroutine ELDI. Then the free-free stiffness matrix, in local coordinates, is carried from A(6,6) into S by means of subroutine RLOC. Finally, by calling subroutine STRA, subroutine S02 obtains and stores in S the description of



the free-free stiffness matrix in the overall coordinate system. The content of COMMON location IERR is transmitted intact to the calling program for error handling.

**14. Subroutine S03.** Subroutine S03 is called by subroutine STFS. The flowchart and the source program listing of S03 are given in Fig. VI-26 and Table VII-29, respectively. The subroutine generates in S the free-free stiffness matrix of element type 3 in the overall coordinate system, modifies vector UV so that the portion of element load vector P related with the thermal loads can be generated in the main program of Link 2, and generates the remaining portion of element load vector P in the overall coordinate system. By calling subroutine CODI, subroutine S03 generates the direction cosines of the local axes in DIR(3,3). Then, by means of subroutine PLBE, the free-free stiffness matrix of the element in the local coordinate system is obtained and stored in A(6,6). The free-free stiffness matrix in local coordinates is carried from A(6,6) into S by means of subroutine RLOC. By calling subroutine STRA, subroutine S04 obtains and stores in S the description of the free-free stiffness matrix in the overall coordinate system. The load vector due to pressure and acceleration is obtained in the overall coordinate system and stored in P. The distortions of the free-free element due to temperature gradient are first obtained in the local coordinate system, then, by means of subroutine TRAN, in the overall coordinate system, and both descriptions are placed in UVG. Vector UVG is then added to vector UV, so that the main program of Link 2 can handle the thermal portion of P (see Sect. III-A). The content of COMMON location IERR is transmitted intact to the calling program for error handling.

**15. Subroutine S04.** Subroutine S04 is called by subroutine STFS. The flowchart and the source program listing of S04 are given in Fig. VI-27 and Table VII-30, respectively. The program generates in S the free-free stiffness matrix of element type 4 in the overall coordinate system, and the description of the element load vector P in the overall coordinate system is partly obtained. The remaining portion of element load vector P is obtained in the main program of Link 2. By calling subroutine CODI, subroutine S04 first obtains and stores in DIR(3,3) the direction cosines of the local axes. Then the contributions of the pressure and the acceleration loadings to the description of element load vector P in the overall coordinate system are partly obtained. In obtaining the pressure direction, subroutine S04 calls

subroutine ELDI. The stiffness matrix in the local coordinates is obtained in two steps. In the first step, subroutine BEAM is called to obtain the stiffness of the element in the local  $xy$  plane for storage in A(6,6). Then this matrix is carried into S by calling subroutine RLOC four times. In the second step, subroutine PLBE is called to obtain the stiffness of the element for deformations out of the local  $xy$  plane for storage in A(6,6), and the matrix is carried into S by calling subroutine RLOC once. The description of the free-free stiffness matrix is first obtained in local coordinates, then by means of subroutine STRA, in overall coordinates, for storage in S. So that the thermal load portion of P can be properly obtained in the main program of Link 2, subroutine S04 first computes into UVG the distortions of the free-free element due to temperature gradients, in the local coordinate system. Then, by means of subroutine TRAN, this vector is expressed in the overall coordinate system and added to vector UV. The content of COMMON location IERR is transmitted intact to the calling program for error handling.

**16. Subroutine S05.** Subroutine S05 is called by subroutines STFS, S11, S13, and S15. The flowchart and the source program listing of S05 are given in Fig. VI-28 and Table VII-31, respectively. When called by STFS (COMMON location IGEM is zero when called by STFS), subroutine S05 generates the free-free stiffness matrix S and partially generates load vector P of element type 5 in the overall coordinate system. When called by subroutines S11 and S13, it generates S and P (partially) in the local coordinates of the element, for element types 11 and 13, respectively, for membrane stretching. Actually, for the latter type of elements, X, Y, Z, XD, YD, and ZD contain local coordinates of the vertices. By calling subroutine TRIM, subroutine S05 first generates  $[M]$  and  $[N]$  matrices (defined in Ref. 2), in EM and EN locations in COMMON. The  $[D]$  matrix (Ref. 2) corresponds to D33 in the subroutine. As far as the free-free stiffness matrix is concerned, the objective of this subroutine is to generate the  $[K_M]$  matrix of Eq. (46) in Ref. 2 with  $a = b = c = d = e = 0$ . Submatrices  $[P]$ ,  $[Q]$ , and  $[R]$  (Ref. 2) are obtained by executing the triple matrix products by means of subroutine TRM, and then placed into S by means of subroutine ADM. For element types 11 and 13, pressure loading is not considered in this subroutine, but for element type 5, the pressure loading is handled in this routine. In the latter case, if the element is a subelement, the pressure is considered only for the first subelement of both ways of subdivisions (see Sect. III-A). Constants IPBG, IPEN, and CONS for

the handling of the acceleration loading in the main program of Link 2 are generated in this subroutine for all cases. The temperature loading portion of element load vector P is also handled in the main program of Link 2. When an error condition is encountered, the subroutine sets IERR to 1 and returns control to the calling program. The explicit expression of the free-free stiffness matrix may be obtained from Ref. 2.

**17. Subroutine S07.** Subroutine S07 is called by subroutines STFS and S11. The flowchart and the source program listing of S07 are given in Fig. VI-29 and Table VII-32, respectively. If the calling program is S11, then X, Y, Z, XD, YD, and ZD contain the local coordinates of the vertices; therefore S and P represent the free-free stiffness matrix and the element load vector for bending of element type 11, in local coordinates. If the calling program is STFS, S and P represent the free-free stiffness matrix and the element load vector of element type 7, in the overall coordinate system. The portion of P related with pressure loading is generated by subroutine S07. The constants IPBG, IPEN, and CONS are generated by subroutine S07 so that the portion of the vector P related with acceleration loading can be handled in the main program of Link 2 (see Sect. III-A). The portion of P related with the thermal loads is also handled in the main program of Link 2. Subroutine S07 generates in vector UV the distortions of the free-free element due to temperature gradient (see Sect. III-A). By calling subroutine TRIM, subroutine S07 first obtains  $[M]$ ,  $[N]$ , and  $[L]$  matrices of Ref. 2 in locations EM, EN, and EL. The matrices  $[D]$  and  $[D']$  of this reference correspond to D33 and E22 in the subroutine. The triple matrix products indicated by Eqs. (45) and (51) of Ref. 2 are carried out by means of subroutine TRM, and are properly placed into S by means of subroutine ADM. The objective of subroutine S07 in generating S is to obtain the shaded portions of  $[K_b]$  and  $[K_s]$  matrices given by Eqs. (49) and (55) of Ref. 2. In generating the shaded portion of  $[K_s]$  given by Eq. (55) of Ref. 2, the subroutine uses the "constant trace scheme" of Ref. 3. When an error condition is detected, the subroutine sets IERR to 1 and returns control to the calling program.

**18. Subroutine S09.** Subroutine S09 is called by subroutine STFS. The flowchart and the source program listing of S09 are given in Fig. VI-30 and Table VII-33, respectively. The objective of this subroutine is to compute the free-free stiffness matrix and the element load vector of element type 9, in the overall coordinate system, into locations S and P. The portion of P related with

pressure loading is generated in subroutine S09. The subroutine generates the values of IPBG, IPEN, and CONS values for the handling of the acceleration loading portion of P in the main program of Link 2, which also handles the thermal load portion. The submatrices of the free-free stiffness matrix are obtained in the form of triple matrix products computed by means of subroutine TRM. These submatrices are properly placed in S by means of subroutine ADM. If the volume of the element is too small relative to a reference volume, an error message is printed out and the generation of S and P is skipped. If an error condition is encountered during the execution of the subroutine, IERR is set to 1, and control is returned to the calling program.

**19. Subroutine S11.** Subroutine S11 is called by subroutine STFS. The flowchart and the source program listing of S11 are given in Fig. VI-31 and Table VII-34, respectively. The objective of this subroutine is to generate the free-free stiffness matrix and partially generate the element load vector in S and P, respectively, of element type 11, in the overall coordinate system. The matrix in S is that of Eq. (61) of Ref. 2, with  $a = b = c = d = e = 0$ . Subroutine S11 first calls subroutine CORT to obtain and store in X, Y, Z, XD, YD, ZD, the coordinates of the vertices in the local coordinate system, and the direction cosines of the local axes in DIR(3,3). Next, by calling subroutine S07, subroutine S11 generates the bending portion of S and P by assuming the order as 9. Next, the quantities in S and P are properly relocated so that S and P are of order 18. The same relocation is applied to vector UV, which is generated by subroutine S07. After this, subroutine S11 calls subroutine S05 to generate the membrane portion of S and P. The P vector is partially generated in subroutine S11. The acceleration loading and the thermal loading portions of P are handled in the main program of Link 2 (see Sect. III-A). Subroutine S11 calls subroutine TRAN to express P and UV in overall coordinates, and subroutine STRA to express S in overall coordinates. The content of COMMON location IERR is transmitted intact to the calling program for error handling.

**20. Subroutine S13.** Subroutine S13 is called by subroutine STFS. The flowchart and the source program listing of S13 are given in Fig. VI-32 and Table VII-35, respectively. The objective of this subroutine is to generate the free-free stiffness matrix and partially generate the element load vector in S and P, respectively, of element type 13, in the overall coordinate system. Subroutine S13 first calls subroutine CORT to obtain and store

in X, Y, Z, XD, YD, ZD the coordinates of the vertices in the local coordinate system, and the direction cosines of the local axes in DIR(3,3). Next, subroutine S13 calls subroutine S05 to generate the membrane rigidity and the corresponding load vector in S and P. The pressure load portion of P is generated in subroutine S13, and the acceleration loading portion and the thermal load portion of P are generated in the main program of Link 2 (see Sect. III-A). Having generated S and P in local coordinates, subroutine S13 calls subroutine TRAN to express P in the overall coordinate system, and subroutine STRA to express S in the overall coordinate system. The content of COMMON location IERR is transmitted intact to the calling program for error handling.

**21. Subroutine S15.** Subroutine S15 is called by subroutine STFS. The flowchart and the source program listing of S15 are given in Fig. VI-33 and Table VII-36, respectively. The objective of this subroutine is to generate the free-free stiffness matrix and the element load vector of element type 15, in locations S and P, expressed in the overall coordinate system. Only the thermal load portion of P is generated in the main program of Link 2 (see Sect. III-A). The generation of the free-free stiffness matrix is performed as described in Ref. 4. The terminology of Table VII-36 should be interpreted in the light of Ref. 4. Subroutine S15 calls subroutine TRIM to obtain the EM and EN arrays corresponding to M and N, respectively, of Ref. 4. The triple matrix products of Ref. 4 are performed by means of subroutine TRM, and properly placed in S by means of subroutine ADM. The first term in Eq. (9) of Ref. 4 is obtained in S by means of subroutine S05. In case of error, IERR location is set to 1 and control is returned to the calling program.

**22. Subroutine S17.** Subroutine S17 is called by subroutines STFS and S18. The flowchart and the source program listing of S17 are given in Fig. VI-34 and Table VII-37, respectively. The objective of this subroutine is to generate the free-free stiffness matrix and the element load vector of element type 17, in locations S and P, expressed in the overall coordinate system. Only the thermal load portion of P is generated in the main program of Link 2 (see Sect. III-A). The generation of the free-free stiffness matrix is performed as described in Ref. 5. The triple matrix products of this reference are performed by means of subroutine TRM, and properly placed in S by means of subroutine ADM. The terminology in Table VII-37 should be interpreted in the light of Ref. 5. In case of error, location IERR is set to 1 and control is returned to the calling program.

**23. Subroutine S18.** Subroutine S18 is called by subroutine STFS. The flowchart and the source program listing of S18 are given in Fig. VI-35 and Table VII-38, respectively. The objective of this subroutine is to generate the free-free stiffness matrix and the element load vector of element type 18, in locations S and P, expressed in the overall coordinate system. Only the thermal load portion of P is generated in the main program of Link 2 (see Sect. III-A). The generation of the free-free stiffness matrix is performed as described in Ref. 5. For this purpose, subroutine S18 first calls subroutine S17 to generate the membrane portion of S and P. The triple matrix products of Ref. 5 are performed by means of subroutine TRM, and properly placed in S by means of subroutine ADM. The terminology in Table VII-38 should be interpreted in the light of Ref. 5. Before returning control to the calling program, the subroutine modifies vector UV for the inclusion of thermal gradient effects. The content of COMMON location IERR is transmitted intact to the calling program for error handling.

**24. Subroutine STFS.** Subroutine STFS is called by the main program of Link 2. The flowchart and the source program listing of STFS are given in Fig. VI-36 and Table VII-39, respectively. The subroutine has one argument, which is the type number of the current element being processed by the calling program. The function of this subroutine is to call the proper subroutine from among S01, S02, S03, S04, S05, S07, S09, S11, S13, S15, S17, and S18 to suit the type number in the argument. The functions of these subroutines are to generate the free-free stiffness matrix, and partially generate the element load vector, in locations S and P, expressed in the overall coordinate system. There is no error return in the subroutine.

**25. Subroutine STRA.** Subroutine STRA is called by subroutines S02, S03, S04, S11, and S13. The flowchart and the source program listing of STRA are given in Fig. VI-37 and Table VII-40, respectively. The objective of this subroutine is to generate in S the description of the free-free stiffness matrix, in overall coordinates, from the description in local coordinates in S, and the directions cosines of local axes in DIR(3,3). The subroutine assumes that S is an  $IDS \times IDS$  matrix. By calling subroutine TRAN,  $IDS$  times, subroutine STRA first obtains and places the description of each of the  $IDS$  vectors of S, in overall coordinates, in the same S locations. Then it generates in S the transpose of  $IDS \times IDS$  free-free stiffness matrix. Finally, by calling subroutine TRAN, again  $IDS$  times, subroutine STRS obtains and

places the description of each of the IDS vectors of the transposed matrix, in overall coordinates, in the same S locations. The final matrix is the description of the free-free stiffness matrix in the overall coordinate system. There is no error return in the subroutine, and all arguments are implicit.

**26. Subroutine TICK.** Subroutine TICK is called by the main program of Link 2. It is identical with subroutine TICK of Link 1. For further information, see Sect. II-B-13. The source program listing of this program is given in Table VII-41.

**27. Subroutine TOPO.** Subroutine TOPO is called by the main program of Link 2. The flowchart and the source program listing of TOPO are given in Fig. VI-38 and Table VII-42, respectively. The objective of this subroutine is to extract and analyze the descriptive words of the element being currently processed by the main program of Link 2. The subroutine is identical with subroutine TOPO of Link 1 up to the statement whose number is 1450 (see Fig. VI-38). As a result of the analysis of the descriptive words, the vertex labels and the property type numbers of the element are obtained in N block and in locations IELT, IMET, JPRS, ITIC, ITEM, JSDY, JSDZ, JMMX, JMMY, JMMZ, JMFI, JARE, respectively. In case of error, the subroutine returns control to the calling program.

**28. Subroutine TRAN.** Subroutine TRAN is called by subroutines S03, S04, S11, S13, and STRA. The flowchart and the source program listing of TRAN are given in Fig. VI-39 and Table VII-43, respectively. The subroutine has two explicit arguments. The objective of this subroutine is to generate the description of a vector of order  $(IGEM + 1) * IMS * 3$  in the overall coordinates from the description of the vector in the local coordinates,

and DIR(3,3) (the directions cosines of local axes). The description of the vector in the local coordinate system is in the array indicated by the first argument, just after the entry indicated by the second argument. The subroutine first computes the description of the vector in the overall system in DUM block, and then carries it on the local description. There is no error return in the subroutine.

**29. Subroutine TRIM.** Subroutine TRIM is called by subroutines S05, S07, and S15. The flowchart and the source program listing of TRIM are given in Fig. VI-40 and Table VII-44, respectively. The objective of this subroutine is to obtain in blocks EM, EN, and EQ the matrices  $[M]$ ,  $[N]$ , and  $[L]$  of Ref. 2 from the information in XD and YD. There is no error return in the subroutine.

**30. Subroutine TRM.** Subroutine TRM is called by subroutines S05, S07, S09, S15, S17, and S18. The flowchart and the source program listing of TRM are given in Fig. VI-41 and Table VII-45, respectively. The objective of the subroutine is to perform triple matrix products of the type  $[B]^T[A][B]$  or  $[C]^T[A][B]$  where  $[A]$  is always a symmetric matrix of order 3 or less, and  $[B]$  and  $[C]$  matrices of order  $(3 \times 4)$  or less. The subroutine has five arguments. If the last argument is negative,  $[C]^T[A][B]$  is performed; if the last argument is positive,  $[B]^T[A][B]$  is performed. The order of the symmetric matrix  $[A]$  is given by the fourth argument. The absolute value of the last argument is the column order of  $[C]$  or  $[B]$ . The matrices  $[A]$ ,  $[B]$ , and  $[C]$  are indicated by the first, second, and third arguments, respectively. The subroutine returns control to the calling program by placing the triple product into the array indicated by the third argument. There is no error return in the subroutine.

## IV. Main Program and Subroutines of Link 3

### A. Main Program of Link 3

The flowchart and the source program listing of the main program of Link 3 are given in Fig. VI-42 and Table VII-46, respectively. The logical function of the program may be summarized as follows:

- (1) The program generates and stores the upper decomposed stiffness matrix in the IST-pointer-related vector, and the unknown deflections in the IDEF-pointer-related vector.
- (2) Possibly destroying some portions of the decomposed stiffness matrix, the program generates in BB array the complete list of nodal deflections, and carries them onto the IDEF-pointer-related vector.
- (3) If execution of the stress link is requested, i.e., if  $INX = 4$ , the program computes into the IST-pointer-related vector the forces acting on mesh points (see Output Item 20, Sect. VI-D, Vol. I).
- (4) If  $INX = 4$ , the program generates in the IST-pointer-related vector the list of labels of the elements meeting at the mesh points, immediately after the residual forces computed in (3), and saves this list on tape ITAS for use in Link 4.

- (5) Depending upon the values of  $INX$  and  $ITAS$ , the main program transfers the control either to Link 4 or to Link 1, as the logically last operation.

In carrying out function (1), the program calls subroutine VELAS, which requires as arguments the number of equations in the system, the pointer of the list of pointers of the diagonal elements of the coefficient matrix, the pointer of the coefficient matrix, and the pointer of the right-hand-side vector. The successful solution of linear equations is indicated by the zero content of the second argument. Function (2) is carried out with the help of the information in IBO-, IBB- and IIC-pointer-related arrays and within the framework of Table III-1, Vol. I. The program produces Output Item 19 from BB block, and calls subroutine PUNC for other modes of output (see Sect. V-F, Vol. I). Then, the information in BB block is carried out to the IDEF-pointer-related vector for use in Link 4. To carry out function (3), the program calls subroutine RESI, and to produce Output Item 20, it calls subroutine RESW. Function (4) is carried out by means of subroutine ELST. The main program, in measuring the elapsed time in executing Link 3, and solving the linear equations, calls subroutine TICK. Output Items 18, 19, and 21 are directly produced by the main program.

## B. Subroutines of Link 3

1. *Subroutine ELST.* Subroutine ELST is called by the main program of Link 3. The flowchart and the source program listing of ELST are given in Fig. VI-43 and Table VII-47, respectively. The function of the subroutine is to generate, for each node, information listing the labels of the non-one-dimensional elements meeting at a node. This information is listed as a one-dimensional array starting immediately after the residual forces produced by subroutine RESI (between points E and E' in Fig. III-1, Vol. II, basic). For this purpose, 13 words are assigned for every mesh point. The first word contains the number of non-one-dimensional elements meeting at the mesh point, and the remaining words the labels of these elements. Whenever there are more than 12 non-one-dimensional elements meeting at the mesh point, subroutine ELST returns control to the calling program by setting ITAS to zero, thus preventing the execution of Link 4 even if  $INX = 4$ . When the number of non-one-dimensional elements meeting at a mesh point and their labels are obtained successfully, the subroutine generates one logical record on tape ITAS for each mesh point to contain such information, and thus releases the corresponding core area. These records are listed after the elemental matrices, and are ordered with the labels of the mesh points. The subroutine also counts the one-dimensional elements and saves the total in COMMON location IONE. If a mesh point does not have any non-one-dimensional elements, the respective record in tape ITAS contains the label of this mesh point and two negative integers. The subroutine, before returning control to the calling program, positions the tape to the nodal set information of the first mesh point by means of IN number of BACKSPACE commands.

2. *Subroutine PUNC.* Subroutine PUNC is called by the main program of Link 3. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-48. If the user wishes to produce Output Item 19 in different media and format, he may do so by writing his version of this subroutine, as explained in Sect. V-F, Vol. I. The logical function of this subroutine is to copy deflections from BB block to the desired output media with the desired format.

3. *Subroutine RESI.* Subroutine RESI is called by the main program of Link 3. The flowchart and the source program listing of RESI are given in Fig. VI-44 and Table VII-49, respectively. The function of this subroutine is to generate the forces acting at the mesh points,

in the overall coordinate system, in the IST-pointer-related vector. Such forces consist of nonthermal element forces less the elastic forces (element stiffness matrix times the vertex deflections). In the absence of thermal loading, these forces represent the round-off errors at a nonboundary point, and the reaction force at a boundary point where the deflections are prescribed, or prescribed concentrated loads where the deflections are not prescribed. In this context, these forces are labelled as the residual forces. The residual forces are used in Link 4 to compute average stresses at the boundary points. To compute the residual forces, subroutine RESI clears the first IND words of the IST-pointer-related vector, and considers that the residual forces are to be listed as in Table III-3 with increasing mesh-point labels and conforming with Table III-1, Vol. I (i.e., the residual forces of the first mesh point are to be listed first, the residual forces of the second mesh point are to be listed second, etc.). Since tape ITAS is already positioned by the main program of Link 2 for this purpose, the subroutine reads in sequentially the element matrices (the stiffness matrix and the load vector without thermal load contribution) one at a time, and performs the operation of "element load vector less element stiffness matrix times vertex deflections," and assembles the resulting vector onto the vector of residual forces. In the case of subelements, the scaling factors discussed in Section III-A are properly considered. If an error is detected during the tape handling, the subroutine sets the contents of ITAS to zero and returns control to the calling program, thus preventing the execution of Link 4 even if  $INX = 4$ . The residual forces are kept intact in the core until the execution of Link 4 is completed.

4. *Subroutine RESW.* Subroutine RESW is called by the main program of Link 3, if  $INP \neq 0$ . The flowchart and the source program listing of RESW are given in Fig. VI-45 and Table VII-50, respectively. The purpose of this subroutine is to produce Output Item 20. This is achieved by looping on mesh points. At every loop cycle, the subroutine first abstracts the residual force of the respective mesh point from the list of residual forces in the IST-pointer-related vector, and arranges the components to a complete six-component vector in accordance with Table III-1, Vol. I, and finally prints a line for these components. The ordering of the residual forces is explained in Table III-3, Vol. II (basic). In arranging the components of a mesh point, the subroutine uses the constant IELT, which is generated by the main program of Link 3 for Output Item 19 (the ordering of Output Items 19 and 20 is similar). There is no error return in the subroutine.

5. *Subroutine TICK.* Subroutine TICK is called by the main program of Link 3. It is identical with subroutine TICK of Link 1. For further information see Section II-B-13. The source program listing of this program is given in Table VII-51.

6. *Subroutine VELAS.* Subroutine VELAS is called by the main program of Link 3. The flowchart and the source program listing of VELAS are given in Fig. VI-46 and Table VII-52, respectively. The purpose of this subroutine is to solve linear equations with positive-definite, symmetric, and variable-banded coefficient matrices. The subroutine has four explicit and no implicit arguments. The first argument is the order of the linear system (i.e., the number of equations); at entry to the program, the second argument contains the pointer of the vector listing the pointers of the diagonal elements of the coefficient matrix; the third argument is the pointer of the coefficient matrix; the fourth argument is the pointer of the right-hand-side vector. Subroutine VELAS assumes that the arrays related with the last three arguments are all in COMMON. By applying the Cholesky scheme, the subroutine first obtains the decomposed matrix (referred

to in Fig. VI-46 as  $U(I,J)$ ) on the coefficient matrix (referred to in Fig. VI-46 as  $A(I,J)$ ); then by a forward sweep it obtains the auxiliary solution (referred to in Fig. VI-46 as  $Y(I)$ ) in the right-hand-side vector (referred to in Fig. VI-46 as  $B(I)$ ); and finally, by a backward sweep, it obtains the solution vector (referred to in Fig. VI-46 as  $X(I)$ ) in the right-hand-side vector (referred to in Fig. VI-46 as  $B(I)$ ). During decomposition, if the quantity under the radical sign is nonpositive, the subroutine returns control to the calling program by setting the location of the associated diagonal element relative to the beginning of the coefficient matrix in the second argument. If the first argument is nonpositive, the return is made by setting the second argument to  $-1$ . The subroutine assumes that a quantity is positive if it is larger than the  $10^{-10}$  multiple of the smallest diagonal element (in magnitude) of the coefficient matrix. During decomposition, the subroutine uses NN locations immediately after the array related with the third argument to store the number of matrix elements in the columns of coefficient matrix within the shaded area shown in Fig. II-1, Vol. I. Here NN is the order of the system. The subroutine assumes that the coefficient matrix is arranged as described in Table III-3 under IST-pointer-related vector.

## V. Main Program and Subroutines of Link 4

### A. Main Program of Link 4

The flowchart and the source program listing of the main program of Link 4 are given in Fig. VI-47 and Table VII-53, respectively. The logical functions of the program may be summarized as follows:

- (1) For line elements, by means of subroutine DIMI, the program computes stress resultants at the end points of the elements and prints out Output Item 24.
- (2) For non-one-dimensional elements, it computes, with the method described in Sect. II, Vol. II (basic), the stresses at the mesh points and prints out Output Item 22, by means of Link 4 programs other than DIMI.
- (3) It transfers control to the main program of Link 1 as the logically last operation.

By checking the contents of IONE (see Sect. IV-B-1), the main program performs either function (1) or (2) or both.

If function (2) is to be performed, the program checks whether the starting point of vector FF (see Tables III-4

and III-5, Vol. II, basic) and point E (see Fig. III-1, Vol. II, basic) are overlapping. If overlapping occurs, Error Message 23 is produced and no stress computation is done. Otherwise the main program loops on mesh points with the objective of computing stresses at a mesh point for each material group and for each class group (see Output Item 22 in Sect. VI-E, Vol. I). When the loop on mesh points is satisfied, if there are line elements in the structure, the main program calls subroutine DIMI for function (1). During the performance of function (2), the program calls subroutines ABEQ, BOFI, CAS4, DINA, FINDQ, FINDX, GENE, INLZ, LEST, MDIN, META, SAME, SETA, and STRS. The program calls subroutine TICK to measure the time spent in Link 4. The main program is directly responsible for the production of Output Items 22 and 25.

### B. Subroutines of Link 4

*1. Subroutine ABEQ.* Subroutine ABEQ is called by the main program of Link 4, if the current mesh point ICN is on the boundary of a two- or three-dimensional continuum. The flowchart and the source program listing of ABEQ are given in Fig. VI-48 and Table VII-54, respectively. The objective of this subroutine is to generate



the first IEQ rows of the augmented matrix A (see Table III-5, Vol. II, basic), the corresponding weights in vector IWG, and the actual values of the prescribed stresses in vector SR. The first IEQ rows of the augmented matrix A correspond to the IEQ number of stress boundary conditions at the boundary point ICN. These equations are generated as discussed in Sect. II, Vol. II (basic). The subroutine first copies the residual vector (see Sect. IV-B-3) of mesh point ICN into RES vector. Then, depending upon the class type of current ICth group, it computes certain parameters listed in Table V-1. The program carries two right-hand-side vectors for class 6 and 8 structures in the strain deflection equations, because of the symmetry in strains and curvature changes (see Ref. 2). This is very useful in minimizing the column order of the strain deflection equations.

In Table V-1, the parameters used by the subroutine are defined. The meanings of these parameters are as follows: IEQ is the number of the stress boundary equations (note that the number of stress boundary conditions is the product of IEQ\*IRIG); IRIG is the number of right-hand sides in the strain deflection equations; ICOL is the column order of the coefficient matrix of strain deflection equations; vector N lists the component number (see Table VI-6, Vol. I) of the prescribed stress (as stated in Sect. VI-E, Vol. I, the local coordinate axes on a boundary point are such that the first axis is the outer normal of the boundary surface, and the second and the third axes are tangential to the boundary surface; the stress boundary conditions are expressed in the local coordinate system); IREB and IREN are the entry numbers of the beginning and the end, respectively, of the portion of vector RES to be used in generating the prescribed stress values for the right-hand sides of the stress boundary condition equations. Because of the ordering of the residual forces (first, force components, and then moment components) for the second right-hand side, the program takes IREB and IREN as IREB + 1 and IDEG, respectively. The first and second columns of matrix NEK list the labels of the local axes to be used in projecting the portion of vector RES for obtaining the prescribed stress components, for the first and second right-hand sides, respectively. Matrix REK, like matrix NEK, indicates whether any sign change is to be performed for the correct sign of the prescribed stress. Scale factors CR and CL are used in scaling a stress boundary condition equation to achieve similar orders of magnitude in the whole set strain deflection equations; CR is for the right-hand side, CL for the left-hand side. The basic format of a stress boundary condition equation is shown in Table V-1. To obtain the components of the

best-fit strain tensor from the strain deflection equations in a manner that satisfies the stress boundary conditions more correctly than the remaining equations, the subroutine assigns the stress boundary equations a weight of 100 in the corresponding entries of vector IWG. The subroutine also updates the equation count ICON, and saves the prescribed stress values in vector SR in the order shown in Table V-2. There is no error return in the subroutine.

**2. Subroutine AGEL.** Subroutine AGEL is called by subroutine DINA if the IPIR field of the control card (see Table IV-2, Vol. I) is 2. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-55. If the user wishes to prescribe local coordinate systems at the mesh points of shell structures, he may do so by writing his version of this subroutine, as explained in Sect. V-E, Vol. I. The logical function of this subroutine is to define matrix DIN for the direction cosines of the local axes of mesh point ICN.

**3. Subroutine BEST.** Subroutine BEST is called by subroutines BOFI and QUAD. The flowchart and the source program listing of BEST are given in Fig. VI-49 and Table VII-56, respectively. The objective of this subroutine is to obtain the direction cosines of the normal of the best-fit plane (in the least squares sense) related with the mesh points listed in the array referenced by the second argument and mesh point ICN. The number of mesh points listed in the second argument is given by the third argument. The subroutine places the direction cosines of the normal into the array indicated by the first argument. One condition equation is generated for each mesh point listed in the array referenced by the second argument to express the situation for that point to be in the sought-for plane. The mesh-point coordinates are obtained by means of subroutine FINDX. The equation of the plane is arbitrarily expressed in a coordinate system that is parallel to the overall, but located at a point with coordinates 1.15, 1.16, and 1.17 less than those of mesh point ICN. Once the condition equations are established, the coefficients of variables (i.e., quantities proportional to the direction cosines of the normal) are solved by least squares, by first premultiplying both sides of the condition equations by the transpose of the coefficient matrix, and then solving the resulting equations by means of subroutine INV. If the inversion fails in subroutine INV, subroutine BEST attempts to approximate the direction cosines of the normal, as explained in block 45 of Fig. VI-49. This latter process necessitates a vector product, which is carried out by means of subroutine VECT.

Table V-1. Values of important parameters used in subroutine ABEQ for various classes (see Sect. V-B-1 for discussion)

Class No.	IEQ	N(1)	N(2)	N(3)	IREB	IREN	IRIG, (NES(2))	NEK(1,1)	NEK(1,2)	REK(1,1)	REK(1,2)	ICOL, (NES(1))	CR	CL	IDR, (NES(3))
1	2	1	3		1	2	1	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$		3	$\frac{ARE}{TE*DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0
2	2	1	3		2	3	1	$\begin{Bmatrix} 2 \\ 1 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ -1. \end{Bmatrix}$		3	$\frac{-TE^2*ARE}{12*DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	1
3	2	1	3		1	2	1	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$		3	$\frac{ARE}{XX*DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0
4	3	1	3	5	1	3	1	$\begin{Bmatrix} 1 \\ 2 \\ 3 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ 1. \\ 1. \end{Bmatrix}$		6	$\frac{1}{DD_{1,1}}$	$\frac{ARE}{DD_{1,1}}$	0
5	1	1			1	2	1	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$		1	$\frac{ARE^2}{XX*DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0
6	1	1			1	2	2	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$	{2}	$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$	{1.}	3	$\frac{ARE^2}{XX*DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0
7	2	1	3		1	3	1	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$		3	$\frac{ARE}{DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0
8	2	1	3		1	3	2	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$	$\begin{Bmatrix} 2 \\ 1 \end{Bmatrix}$	$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$	$\begin{Bmatrix} 1. \\ -1. \end{Bmatrix}$	3	$\frac{ARE}{DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0

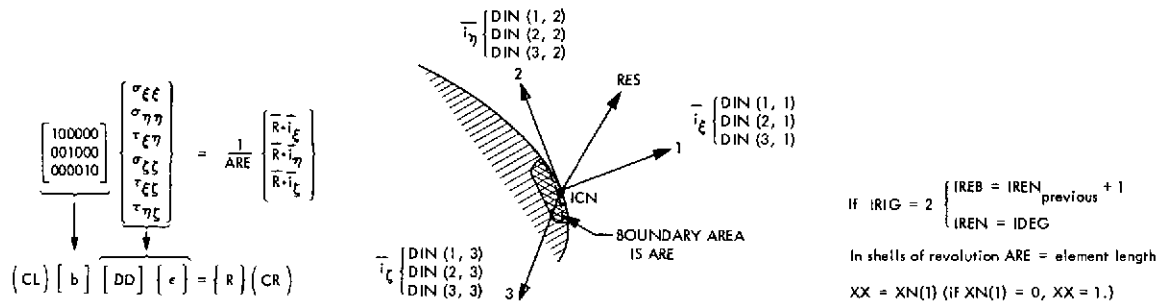


Table V-2. Arrangement of prescribed boundary forces by subroutine ABEQ in SR vector for the eight class<sup>a</sup> types

Class	1	2	3	4	5	6	7	8
SR(1)	$\sigma_{\xi}$	$M_{\xi}$	$\sigma_{\xi}$	$\sigma_{\xi}$	$N_{\xi}$	$N_{\xi}$	$N_{\xi}$	$N_{\xi}$
SR(2)	$\tau_{\xi\eta}$	$M_{\xi\eta}$	$\tau_{\xi\eta}$	$\tau_{\xi\eta}$		$M_{\xi}$	$N_{\xi\eta}$	$N_{\xi\eta}$
SR(3)				$\tau_{\xi\xi}$				$M_{\xi}$
SR(4)								$M_{\xi\eta}$

<sup>a</sup>See Table VI-6, Vol. I.

Before returning control to the calling program, subroutine BEST calls subroutine UNIT to normalize the vector in the first argument. There is no error return in the subroutine.

**4. Subroutine BOFI.** Subroutine BOFI is called by the main program of Link 4. The flowchart and the source program of BOFI are given in Fig. VI-50 and Table VII-57, respectively. The objective of this subroutine is to determine from the element set information in NEL whether mesh point ICN is on the boundary. If mesh point ICN is not on the boundary, the subroutine returns control to the calling program without any action. However, if mesh point ICN is found to be on the boundary, the subroutine sets  $INBON = 1$  and  $AST = IH^*$ , and computes the direction cosines of the outer normal of the boundary at mesh point ICN into vector BIR. To obtain the direction cosines, subroutine BOFI calls subroutine INER to obtain a general vector heading towards the structure, and calls subroutine BEST to obtain the direction cosines of the best-fit plane to boundary nodes neighboring mesh point ICN. After re-directing the normal of the plane with the general vector heading towards the structure, the normal of the best-fit plane is assumed to be the outer normal of the structure at the boundary node. If any trouble arises in finding the outer normal, subroutine BOFI will assume that mesh point ICN is an internal one. The subroutine also generates in ARE an average boundary surface area if mesh point ICN is on the boundary. The number of repeated interelement boundaries in the element set and the number of unrepeated element boundaries are used in determining whether mesh point ICN is on the boundary. In performing its function, BOFI also calls subroutines FINDX, SCAL, and UNIT. There is no error return in the subroutine.

**5. Subroutine CAS4.** Subroutine CAS4 is called by the main program of Link 4. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-58. If Output Item 23 is to be produced selectively, this subroutine should be rewritten by the user, as explained in Sect. V-H, Vol. I. The logical function of this subroutine is to change the value of INP as desired in the DO loop on mesh points in the main program of Link 4.

**6. Subroutine CODI.** Subroutine CODI is called by subroutine DIMI. It is identical with subroutine CODI of Link 2. For further information, see Section III-B-4.

The source program listing of this subroutine is given in Table VII-59.

**7. Subroutine DIMI.** Subroutine DIMI is called by the main program of Link 4, if IONE is positive. The flowchart and the source program listing of DIMI are given in Fig. VI-51 and Table VII-60, respectively. The objective of this subroutine is to obtain the end forces of the one-dimensional elements in the local coordinate system and to produce Output Item 24. For this purpose, the subroutine rewinds tape ITAS and processes the mesh elements one at a time. If a one-dimensional element is encountered, by means of subroutines CODI, STRA and TRAN, the element stiffness matrix, the element load vector, and the deflection vector of the vertices are first expressed in local coordinates of the element (see Fig. VI-1, Vol. I), and then the end forces are expressed as the product of the element stiffness matrix and the vector of vertex deflections less the element load vector. If an error is encountered during the tape handling, the subroutine sets  $IERR = 1$ ,  $ICN =$  the element number, and the explicit argument of the subroutine with the record number as read from the tape, and returns control to the calling program.

**8. Subroutine DINA.** Subroutine DINA is called by the main program of Link 4, if the current class group is of shell type (i.e., ICAS is equal to or larger than 5). The flowchart and the source program listing of DINA are given in Fig. VI-52 and Table VII-61, respectively. The objective of this subroutine is to determine the direction cosines of the axes in which the stresses are to be expressed in DIN and find the value of ANGLE associated with these axes. If the IPIR value of the control card (see Table IV-2, Vol. I) is larger than 1, subroutine DINA calls subroutine AGEL to do the job. Otherwise, subroutine DINA calls either subroutine QUAD or subroutine REVO, depending upon whether the shell is general or axisymmetrical type, respectively, to perform its function. There is no error return in the subroutine.

**9. Subroutine EPAN.** Subroutine EPAN is called by subroutine QUAD, if there are less than eight neighboring mesh points in the element set of mesh point ICN (subroutine QUAD is called only for the general shell case). The flowchart and the source program listing of EPAN are given in Fig. VI-53 and Table VII-62, respectively. The objective of this subroutine is to expand the vector containing the labels of the mesh points in the immediate neighborhood of the current mesh point ICN by the element set information of the mesh points in the immediate neighborhood of mesh point ICN. When

control is transferred to the subroutine, vector NSET contains the labels of the immediate neighbors of mesh point ICN, and NB contains the order of this vector. By minimum tape handling, the subroutine obtains the element set information of each of these immediate neighbors from tape ITAS and expands vector NSET with the mesh-point labels of the neighbors of neighbors of mesh point ICN and updates NB correspondingly. Before it returns control to the calling program, the subroutine repositions tape ITAS to the position at the time of entry. There is no error return in the subroutine.

**10. Subroutine FINDQ.** Subroutine FINDQ is called by the main program of Link 4 and by subroutine SETA. The flowchart and the source program listing of FINDQ are given in Fig. VI-54 and Table VII-63, respectively. The function of this subroutine is to compute, in overall coordinates, the deflection components of the mesh point indicated by the first argument into the vector indicated by the second argument. There is no error return in this subroutine.

**11. Subroutine FINDX.** Subroutine FINDX is called by the main program of Link 4 and subroutines BEST, BOFI, INER, INLZ, QUAD, REVO, and SETA. The flowchart and the source program listing of FINDX are given in Fig. VI-55 and Table VII-64, respectively. The function of this subroutine is to compute the overall coordinates of the mesh point indicated by the first argument into the vector indicated by the second argument. There is no error return in the subroutine.

**12. Subroutine GENE.** Subroutine GENE is called by the main program of Link 4. The flowchart and the source program listing of GENE are given in Fig. VI-56 and Table VII-65, respectively. The objective of this subroutine is to generate the columns of matrix NEL, other than the first (the first column of NEL is already generated by the main program of Link 4), the corresponding matrix MAC, vector ICLAS, and variable IMEL. The format of NEL and MAC matrices is given in Table VI-7, Vol. I. Since the rows of matrix NEL contain information about the elements meeting at mesh point ICN, subroutine GENE calls subroutine TOPO to extract such information from COMMON. Matrix MAC is generated by the information in completed matrix NEL. Vector ICLAS and variable IMEL are generated as a by-product of the generation of matrix MAC. Error conditions that may be encountered during the generation of matrix MAC may cause the production of Error Messages 18, 19, and 20. There is no error return in the subroutine.

**13. Subroutine INER.** Subroutine INER is called by subroutine BOFI, if mesh point ICN is on the boundary. The flowchart and the source program listing of INER are given in Fig. VI-57 and Table VII-66, respectively. The objective of this subroutine is to generate the components of a vector heading towards the structure at mesh point ICN, and store them in the vector indicated by the argument. At the time of entry to the subroutine, vector NSET contains the labels of the neighboring mesh point. The subroutine simply adds the vectors, joining mesh point ICN to its neighbors to obtain the required vector. The mesh-point coordinates are obtained by means of subroutine FINDX. There is no error return in the subroutine.

**14. Subroutine INLZ.** Subroutine INLZ is called by the main program of Link 4. The flowchart and the source program listing of INLZ are given in Fig. VI-58 and Table VII-67, respectively. The function of this subroutine is to initialize the values of IROT, BST, DIN, W, TE, DT, DG, ICOL, IRIG, IDR, ANGLE, ICON, IERR, and BAS quantities for the stress computation corresponding to the current values of ICN/IM/IC (see Table III-4). In initializing these values, the subroutine assumes that the mesh point is an internal one and the local coordinate system is parallel to the overall coordinate system. Values of TE, DT, and DG are obtained as the arithmetical average of those of the related mesh elements. Values of IRIG, ICOL, and IDR are obtained, depending upon the class type number of the current mesh-element group (see Tables III-4, Vol. II, basic, and V-1). To perform its functions, INLZ calls subroutines FINDX and UNIT. There is no error return in the subroutine.

**15. Subroutine INV.** Subroutine INV is called by subroutines BEST, LEST, QUAD, and REVO of Link 4. The flowchart and the source program listing of INV are given in Fig. VI-59 and Table VII-68, respectively. The purpose of the subroutine is to solve a set of linear equations by Gauss elimination. The coefficient matrix is referred by the first argument, and the right-hand-side vectors are referred by the third argument. The second argument is the order of the system, and the fourth argument is the number of right-hand-side vectors. When the subroutine returns control to the calling program, the fifth argument contains the value of the determinant of the coefficient matrix, the first argument contains the inverse of the coefficient matrix, and the third argument contains the solution vector if the fourth argument and the determinant are nonzero. This subroutine is borrowed from

the IBM 1620 library of the Jet Propulsion Laboratory as of September 1966.

**16. Subroutine LEST.** Subroutine LEST is called by the main program of Link 4. The flowchart and the source program listing of LEST are given in Fig. VI-60 and Table VII-69, respectively. The objective of this subroutine is to obtain the components of the best-fit strains from the strain deflection equations. At the time of entry to the subroutine, matrix A contains the augmented matrix of the strain deflection equations, ICON contains the number of equations, JMM the number of columns in the coefficient matrix, JMR the number of right-hand sides (therefore  $JMX = JMM + JMR$  is the column order of the augmented matrix), and IWC the weight assigned to each of the strain deflection equations. Considering the multiplicity of the equations as given in vector IWC, the subroutine premultiplies both sides of the strain deflection equations by the transpose of the coefficient matrix, then calls subroutine INV to obtain the best-fit strain components, and reorders the components in matrix C and redefines JMM and JMR such that the first column contains the usual strain components and the second column contains the angular strain (curvature change) components. For axisymmetrical structures, cases in which mesh point ICN is on the axis of revolution are handled separately in the subroutine by considering the thermal strains, if there are any. For shells of revolution, if mesh point ICN is on the axis, vectors DDIS, DROT, and DCOR contain the relative displacement, relative rotation, and relative coordinate of the opposite end of the nodal line with respect to mesh point ICN. These vectors are expressed in the local coordinate system of mesh point ICN. If the inversion performed by subroutine INV is not successful (indicated by zero determinant), subroutine LEST sets IERR = 1 and returns control to the calling program. If INP is 2, the best-fit strain components are printed out as part of Output Item 23.

**17. Subroutine MDIN.** Subroutine MDIN is called by the main program of Link 4, if mesh point ICN is on the boundary. The flowchart and the source program listing of MDIN are given in Fig. VI-61 and Table VII-70, respectively. The objective of this subroutine is to obtain the direction cosines of the local coordinate axes at mesh point ICN with the specifications described in Sect. VI-E, Volume I; i.e., the first local axis is always normal to the boundary. At the time of entry to the subroutine, matrix DIN contains the direction cosines of the local axes of mesh point ICN, assuming that the mesh point is not on

boundary, and vector BIR contains the direction cosines of the outer unit normal vector of the boundary surface at mesh point ICN. In reorienting the local axes, subroutine MDIN calls subroutines UNIT and VECT. There is no error return in the subroutine.

**18. Subroutine META.** Subroutine META is called by the main program of Link 4. The flowchart and the source program listing of META are given in Fig. VI-62 and Table VII-71, respectively. The objective of this subroutine is to obtain the material matrix (see Fig. III-2b, Vol. I) and thermal expansion coefficients of the current element group associated with ICN/IM/IC, in DD and AL1, AL2, AL3, respectively, in the local coordinate system of mesh point ICN. If the material axes of the current group are not parallel to the local axes of mesh point ICN, subroutine META calls subroutine ROTA to express the material matrix in the local coordinate system. Before returning control to the calling program, subroutine META rearranges the rows and the columns of DD such that the material matrix is arranged with the order of 11, 22, 12, 33, 13, 23. There is no error return in the subroutine.

**19. Subroutine QUAD.** Subroutine QUAD is called by subroutine DINA if a general shell structure is under question. The flowchart and the source program listing of QUAD are given in Fig. VI-63 and Table VII-72, respectively. The objective of the subroutine is to generate in DIN the direction cosines of the local axes of mesh point ICN of the shell structure, and find the value of ANGLE. The subroutine first obtains in vector MSET the labels of the nodes appearing in the mesh elements corresponding to the current values of ICN/IM/IC. Then it obtains in ZD a vector in the general direction of shell normal (block 10\* of Fig. VI-63). After this, the subroutine extracts from vector MSET a list of unrepeated labels in vector NSET. The order of NSET is in NB. If NB is not smaller than 9, a best-fit quadratic surface passing through mesh point ICN and its immediate neighbors may be possible. If NB is smaller than 9, subroutine QUAD calls subroutine EPAN to enlarge vector NSET and NB to include in the list the labels of the immediate neighbors of the mesh points that are already included in vector NSET, without repetition.

Next, by calling subroutine BEST, subroutine QUAD attempts to generate in vector ZTA the direction cosines of the normal of a best-fit plane (in the least squares sense) to the family of mesh points listed in vector NSET. If this fails, vector ZD is taken as vector ZTA. Then,

assuming that the first local axis is in the direction of vector BAS, the subroutine generates the first approximation of matrix DIN (the first, second, and third columns of matrix DIN are referred to as vectors XII, ETA, and ZTA). If NB is not smaller than 9, subroutine QUAD generates in matrix D the condition equations for a quadratic surface passing through the mesh points listed in vector NSET. The condition equations are obtained in the first approximation of the local axes. These equations are next solved by a least squares method with the help of subroutine INV. If the solution is successful, the local normal is taken as the normal direction of this quadratic surface, and matrix DIN is corrected accordingly. With the use of the new matrix DIN, the process of locating a best-fit quadratic surface is repeated to increase the accuracy. If the process of finding a best-fit quadratic surface fails, the subroutine prints out Error Message 21 and returns control to the calling program with the first approximation of matrix DIN. Otherwise, the subroutine examines the value of IPIR. If IPIR is larger than 1, the subroutine rotates the local axes about the normal until the first local axis is in the smaller principal curvature direction of the best-fit quadratic surface. Initially zero value of ANGLE is changed to the degrees value of the angle between vector BAS and the final orientation of the first local axis. In performing its functions, QUAD also calls subroutines FINDX, SCAL, UNIT, and VECT. There is no error return in the subroutine.

**20. Subroutine REVO.** Subroutine REVO is called by subroutine DINA if a shell of revolution is under question. The flowchart and the source program listing of REVO are given in Fig. VI-64 and Table VII-73, respectively. The objective of this subroutine is to generate in matrix DIN the direction cosines of the local axes by fitting, if possible, a fourth-order polynomial to the meridional curve. The normal of this curve is taken as the direction for the third local axis. For this purpose, the subroutine first finds the labels of the first four immediate neighbors of mesh point ICN and places them in vector NSET. Vector NSET also contains the label of ICN. The order of NSET is NB. If for some reason NB is less than 5, the subroutine fits a polynomial curve of degree NB-1 to the meridional curve. The conditions for the mesh points listed in vector NSET on the polynomial curve are generated on matrix B and vector C. The unknown coefficients of the polynomial are obtained from these conditions by means of subroutine INV. If the system is singular, and a polynomial curve fit is not possible, the program will use the line segment joining the mesh points confining mesh point ICN as the fitted curve and

cause the production of Error Message 22. The normal direction of the fitted curve is taken as the third local axis. The overall Z axis is taken as the negative of the second local axis. The first local axis is tangent to the fitted curve and heads towards the increasing arc distance on the meridian (the meridian curve is assumed directed). The first, second, and third columns of matrix DIN are named as vectors XII, ETA, and ZTA, and contain the direction cosines of the first, second, and third local axes. In obtaining the direction cosines of the local axes, subroutine REVO calls subroutines FINDX, SCAL, UNIT, and VECT.

**21. Subroutine ROTA.** Subroutine ROTA is called by subroutine META if the local axes are not parallel to the material axes. The flowchart and the source program listing of ROTA are given in Fig. VI-65 and Table VII-74, respectively. The objective of this subroutine is to express the material matrix DD in the local coordinate system defined by matrix DIN (see Table III-5, Vol. II, basic). There is no error return in the subroutine. In obtaining various unit vectors, subroutine ROTA calls subroutines SCAL, UNIT, and VECT.

**22. Subroutine SAME.** Subroutine SAME is called by the main program of Link 4. The flowchart and the source program listing of SAME are given in Fig. VI-66 and Table VII-75, respectively. The objective of this subroutine is to output stresses for the current ICN/IC/IM group, in the local coordinate system if mesh point ICN is a boundary point, and the group is not of shell type. Therefore, this subroutine produces the last portion of Output Item 22. There is no error return in the subroutine.

**23. Function SCAL.** Function SCAL is called by subroutines BOFI, QUAD, REVO, ROTA, and SETA of Link 4. The flowchart and the source program listing of SCAL are given in Fig. VI-67 and Table VII-76, respectively. The objective of the program is to return to the calling program the scalar product of the vectors referred by the first and second arguments. There is no error return.

**24. Subroutine SETA.** Subroutine SETA is called by the main program of Link 4 once for every mesh element in the group of current ICN/IM/IC. The flowchart and the source program listing of SETA are given in Fig. VI-68 and Table VII-77, respectively. The objective of the program is to add one additional row to the augmented matrix of strain deflection equations for each direction joining mesh point ICN to the remaining vertices of the mesh element. The subroutine assigns a

weight of 10 or 1 to the equation of a direction, depending upon whether the vertex is on the boundary or not. The weights are recorded in vector IWG. The subroutine generates the row of the augmented matrix as described in Sect. II, Vol. II (basic), by considering thermal strains. When a row is added to the augmented matrix, row count ICON is also updated. In obtaining the thermal strain per unit temperature in a given direction, subroutine SETA calls subroutine TEMP. In achieving various vector operations, it also calls function SCAL, and subroutines FINDQ, FINDX, UNIT, and VECT of Link 4. There is no error return in the program.

**25. Subroutine STRA.** Subroutine STRA is called by subroutine DIMI. It is identical with subroutine STRA of Link 2. For further information, see Sect. III-B-25. The source program listing of this subroutine is given in Table VII-78. In performing its function, STRA calls subroutine TRAN.

**26. Subroutine STRS.** Subroutine STRS is called by the main program of Link 4. The flowchart and the source program listing of STRS are given in Fig. VI-69 and Table VII-79, respectively. The objective of this subroutine is to obtain the components of the best-fit stress tensor for current ICN/IM/IC, and list them in vector SR to comply with Table VI-6, Vol. I. At the time of entry to the subroutine, matrix DD contains the material constants, matrix C contains the components of the best-fit usual and angular strains in the first and second columns, respectively, and SR contains the prescribed stresses in the order shown in Table V-2. The subroutine first generates in vector RED the best-fit stresses, then modifies them with the prescribed stresses in SR, and finally copies the final set into vector SR in the order shown in Table VI-6, Vol. I. There is no error return in the subroutine.

**27. Subroutine TEMP.** Subroutine TEMP is called by subroutine SETA if temperature loading of an anisotropic material is under question. The flowchart and the source program listing of TEMP are given in Fig. VI-70 and Table VII-80, respectively. The objective of this subroutine is to obtain the lineal strain in the direction given by the unit vector in XF (see the comment in Table VII-80) due to unit temperature increase, and to store this quantity in the explicit argument. To do this, the subroutine uses matrix W generated by subroutine

ROTA and XF generated by subroutine SETA as DCAR. There is no error return in the subroutine.

**28. Subroutine TICK.** Subroutine TICK is called by the main program of Link 4. It is identical with subroutine TICK of Link 1. For further information, see Sect. II-B-13. The source program listing of this program is given in Table VII-81.

**29. Subroutine TOPO.** Subroutine TOPO is called by subroutine GENE. It is identical with subroutine TOPO of Link 2. For further information, see Sect. III-B-27. The source program listing of this program is given in Table VII-82.

**30. Subroutine TRAN.** Subroutine TRAN is called by subroutines DIMI and STRA of Link 4. It is identical with subroutine TRAN of Link 2. For further information, see Sect. III-B-28. The source program listing of the program is given in Table VII-83.

**31. Subroutine UNIT.** Subroutine UNIT is called by subroutines BEST, BOFI, INLZ, MDIN, QUAD, REVO, ROTA, and SETA of Link 4. The flowchart and the source program listing of UNIT are given in Fig. VI-71 and Table VII-84, respectively. The objective of the subroutine depends upon the contents of the second argument. If the second argument is zero, the subroutine computes the magnitude squared of the vector indicated by the first argument and returns control to the calling program. If the second argument is nonzero, the subroutine replaces the vector in the first argument with a unit vector and the second argument with the magnitude of the original vector. If the second argument, at the beginning, is a positive number, the unit vector is parallel and in the same direction as the original vector. If the second argument, at the beginning, is a negative number, the unit vector is parallel and in the opposite direction of the original vector. There is no error return in the subroutine.

**32. Subroutine VECT.** Subroutine VECT is called by subroutines BEST, MDIN, QUAD, REVO, ROTA, and SETA of Link 4. The flowchart and the source program listing of VECT are given in Fig. VI-72 and Table VII-85, respectively. The objective of this subroutine is to obtain in the vector indicated by the first argument the cross-product of the vector in the second argument times the vector in the third argument. There is no error return in the subroutine.

## VI. Semidetailed Flowcharts

This section contains semidetailed flowcharts of ELAS/Level 3. The flowchart of each program element is treated separately, and given a figure number. The flowcharts are arranged alphabetically by the subroutine names, under the main program of each link. The meanings of the symbols used in the flowcharts may be obtained from the text description of the corresponding subroutine given in the preceding sections and/or Tables III-2 and III-4 of Vol. II (basic). Each flowchart should be considered together with the corresponding source program listing in Sect. VII, and the descriptive paragraph of the earlier sections. The number attached to a block in a flowchart is the number

of the first statement in the source program listing corresponding to this block. If the first statement does not have a statement number, the nearest statement number is used with an asterisk in the block. An asterisk before the number in the block means that the first statement of the block is before the statement indicated by the block number. An asterisk after the number in the block means that the first statement of the block is after the statement indicated by the block number. Multiple asterisks indicate qualitatively the distance between the statement with the number and the first statement of the block in the source program listing.



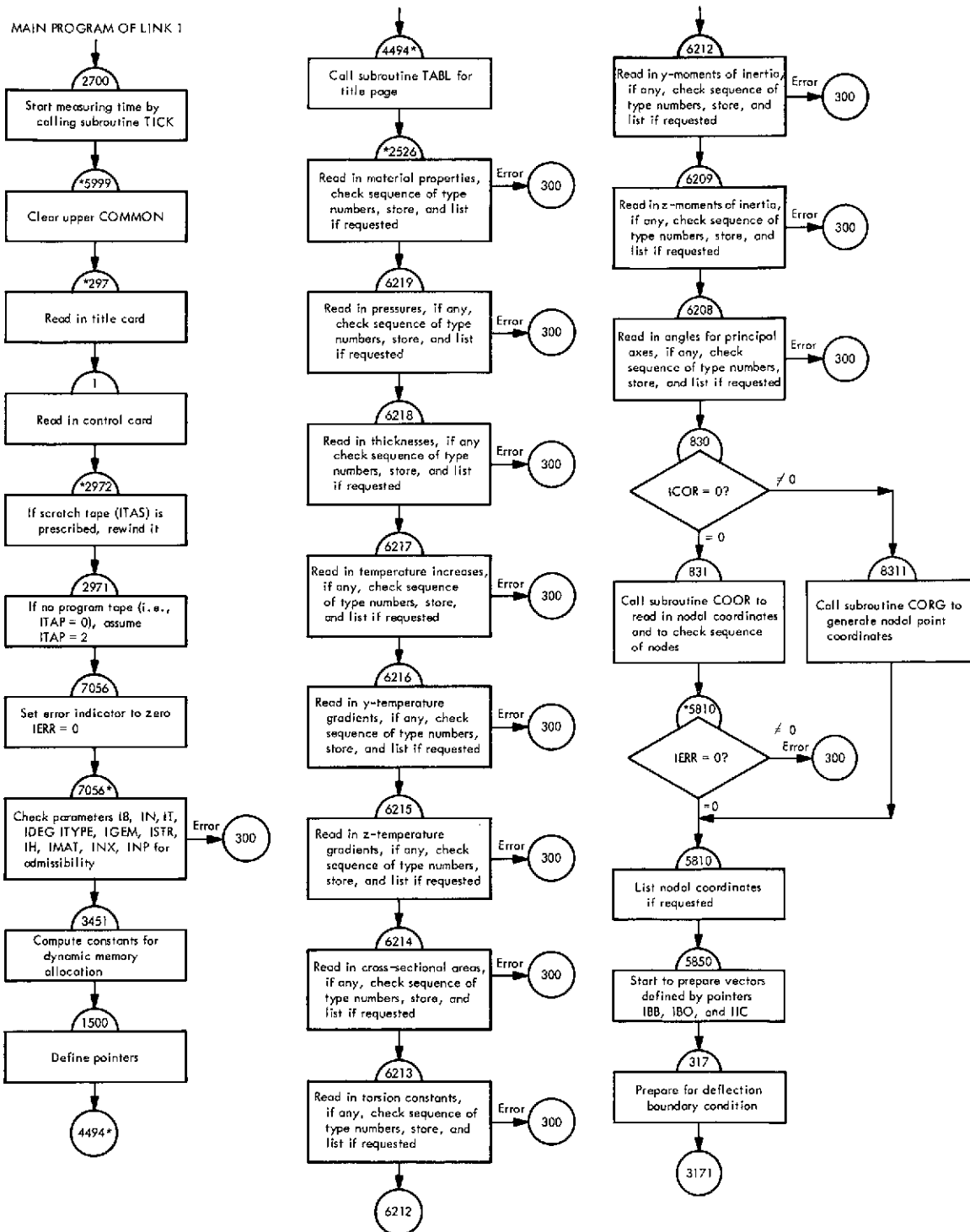


Fig. VI-1. Flowchart of main program of Link 1 (input link)

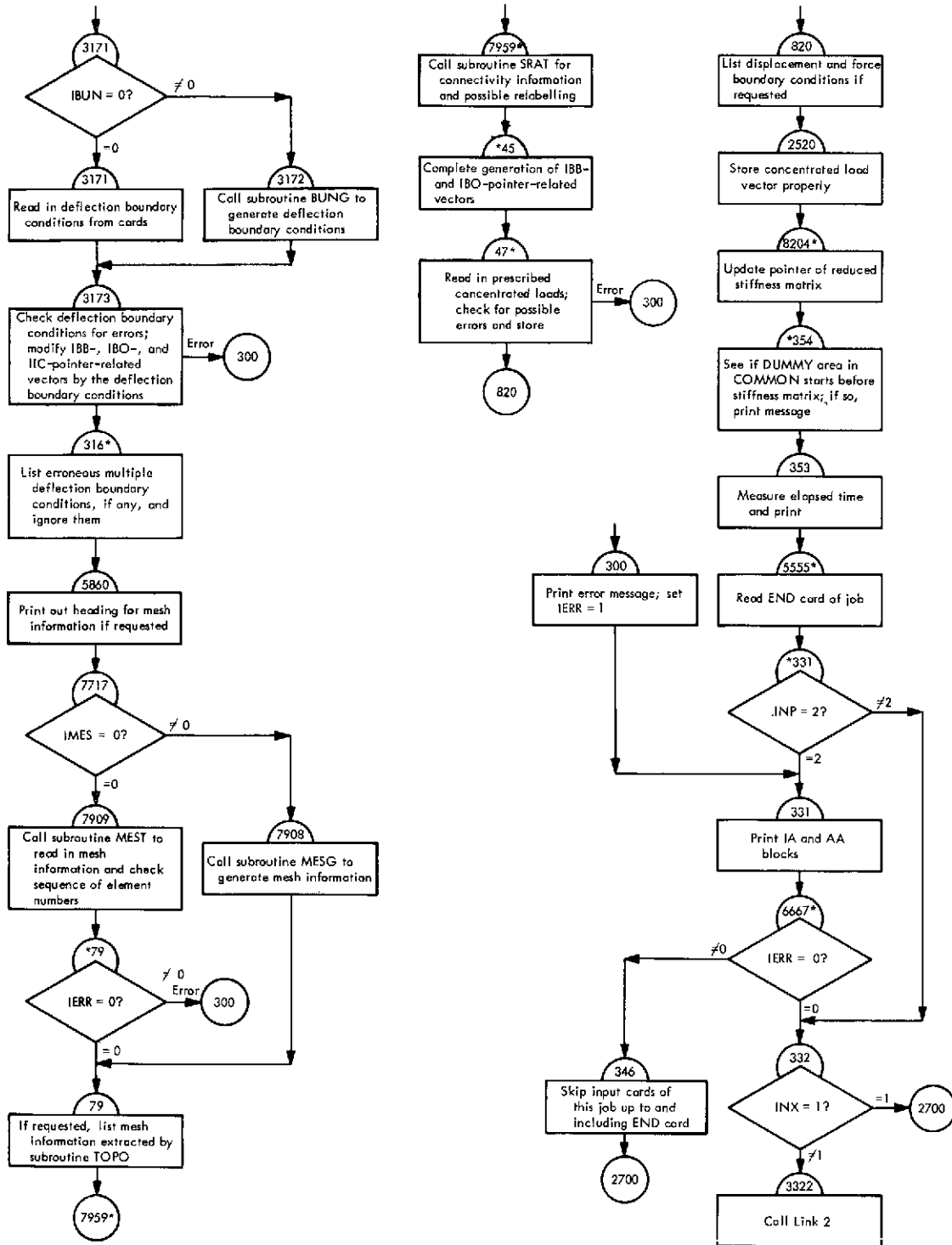


Fig. VI-1 (contd)



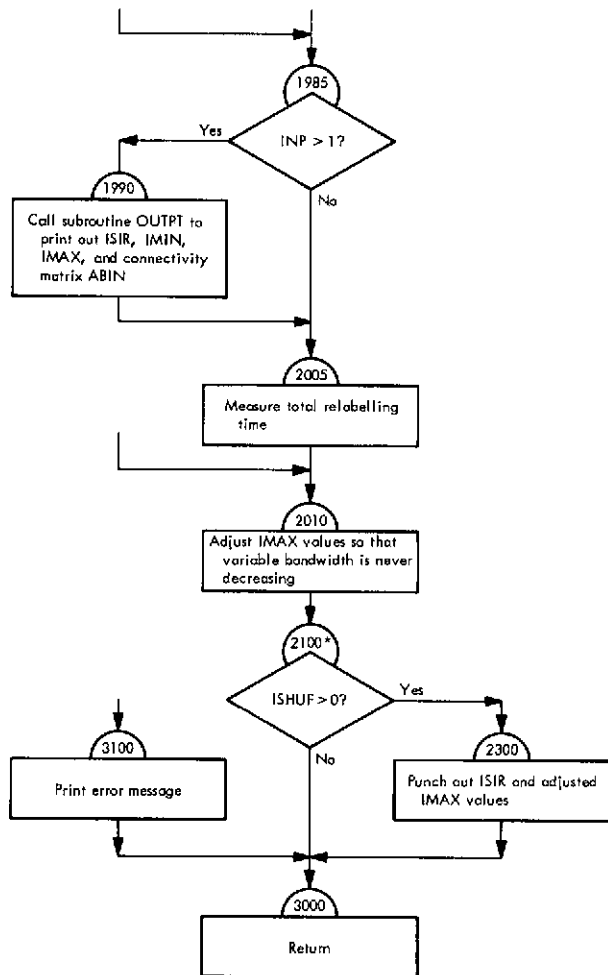
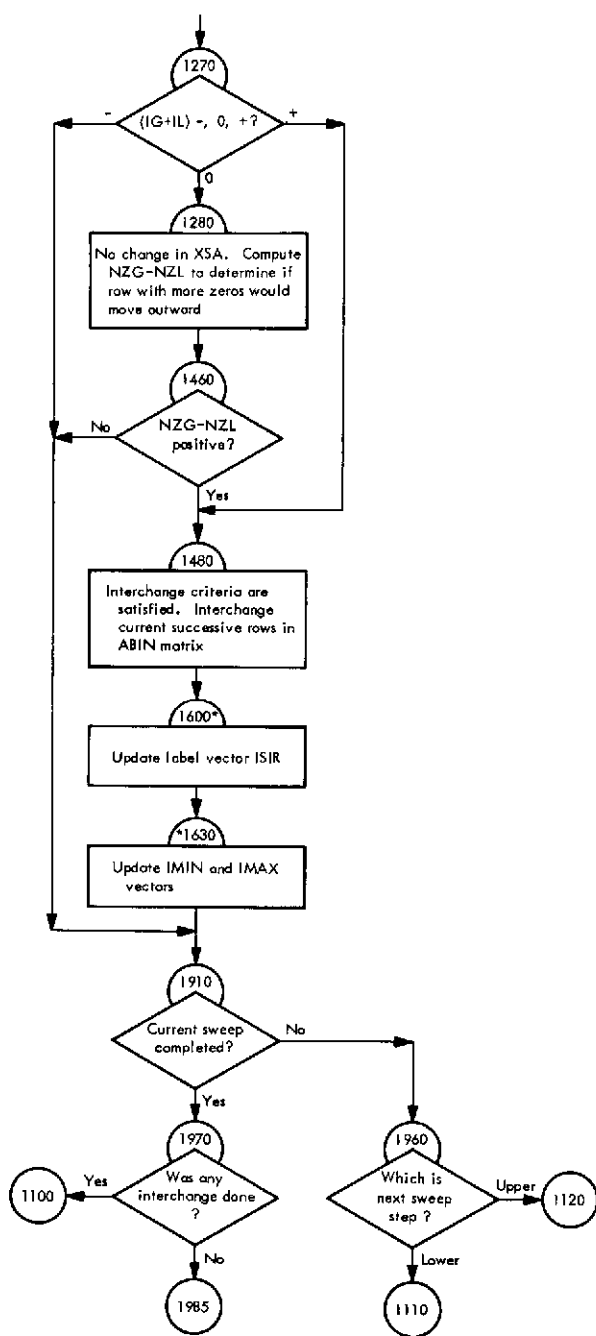
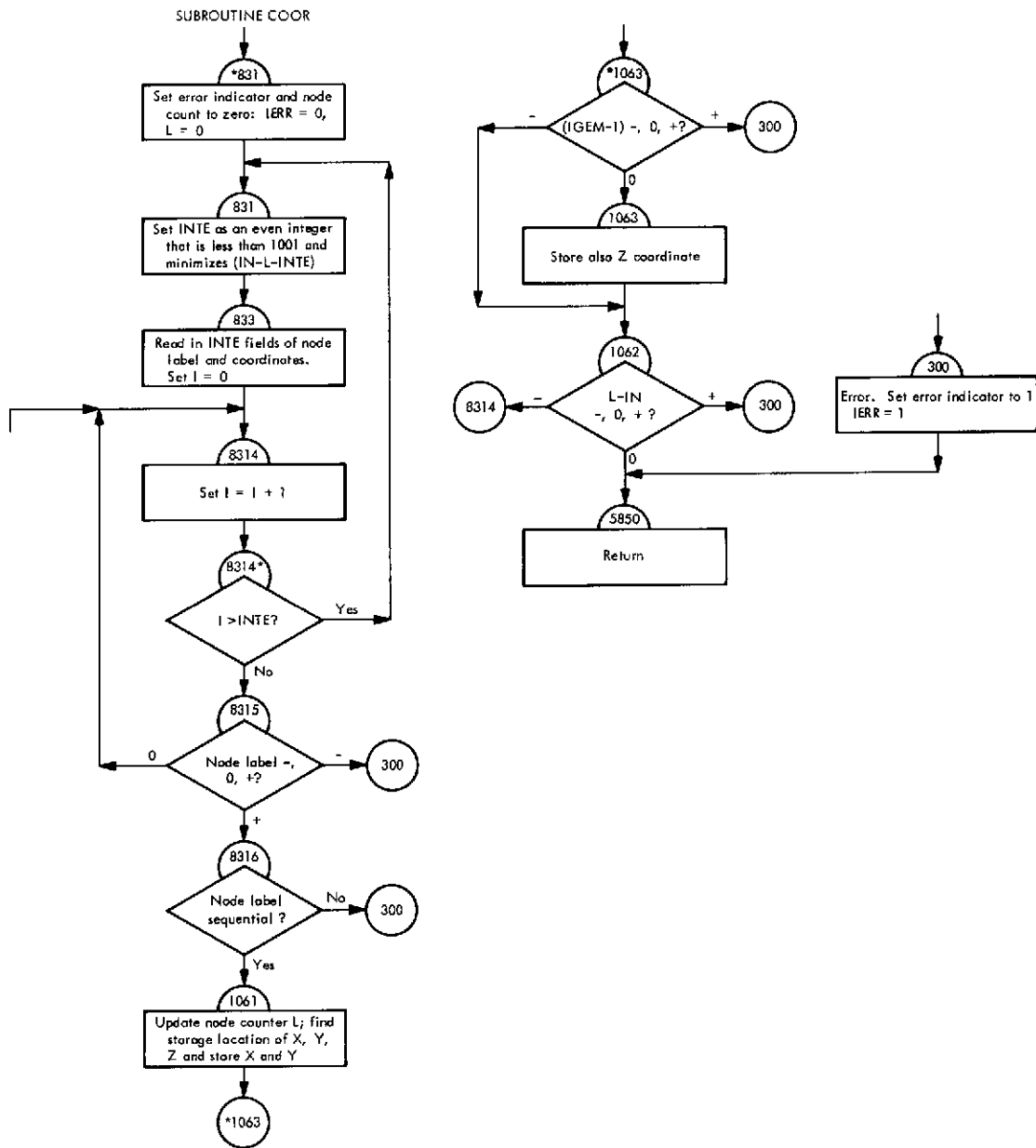


Fig. VI-2 (contd)



**Fig. VI-3. Flowchart of subroutine COOR (Link 1)**

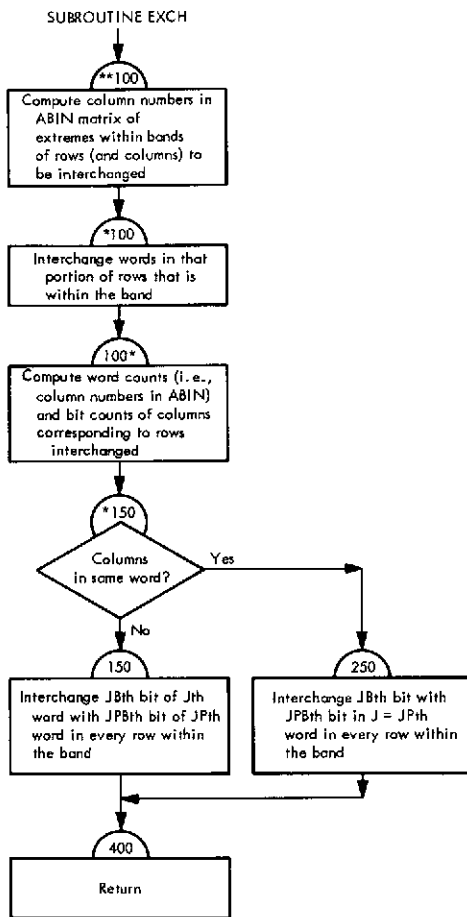


Fig. VI-4. Flowchart of subroutine EXCH (Link 1)

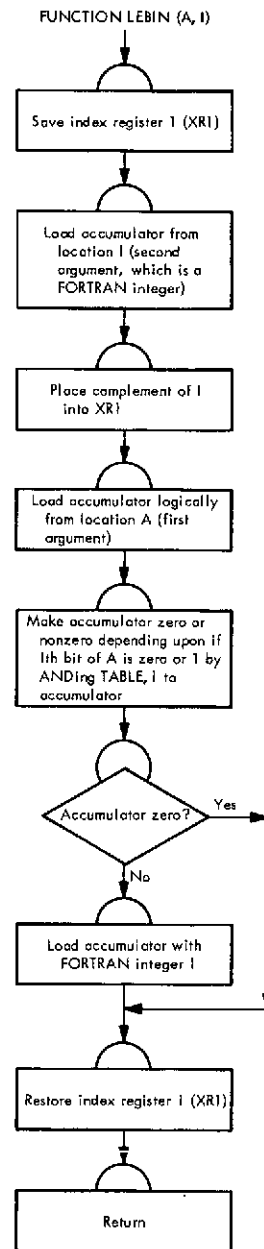
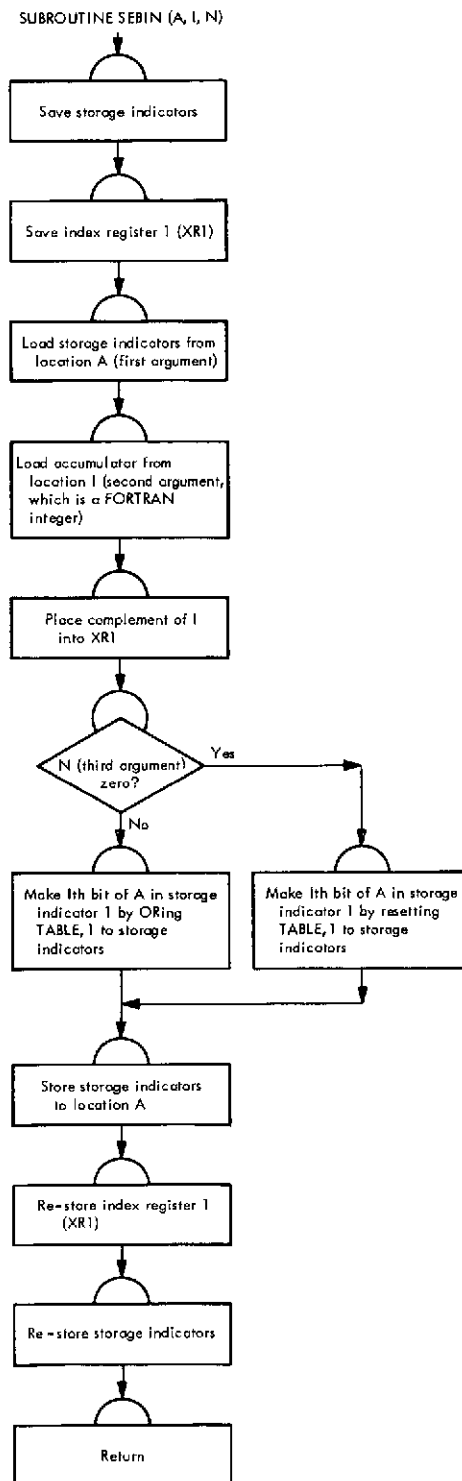


Fig. VI-5. Flowchart of function LEBIN (Link 1)



**Fig. VI-6. Flowchart of subroutine SEBIN (Link 1)**

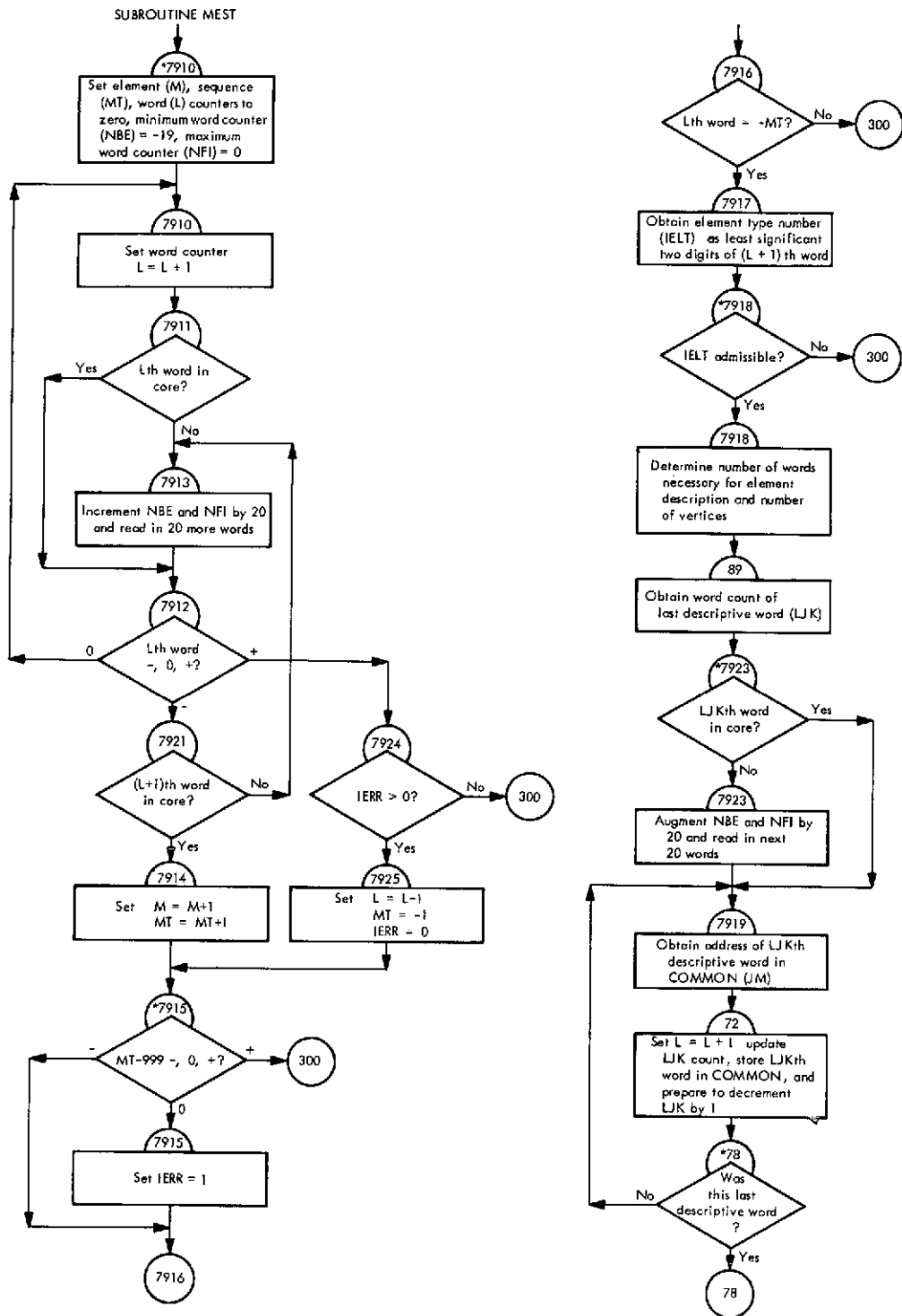


Fig. VI-7. Flowchart of subroutine MEST (Link 1)



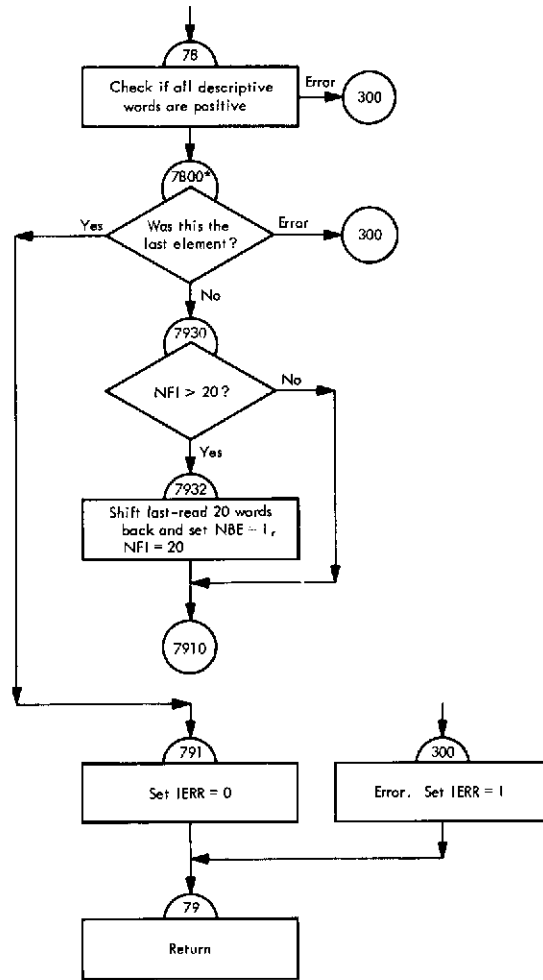


Fig. VI-7 (contd)

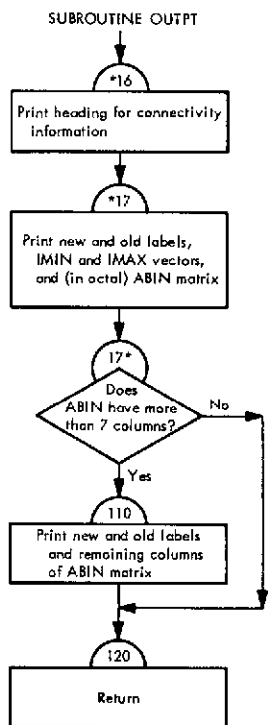


Fig. VI-8. Flowchart of subroutine OUTPT (Link 1)

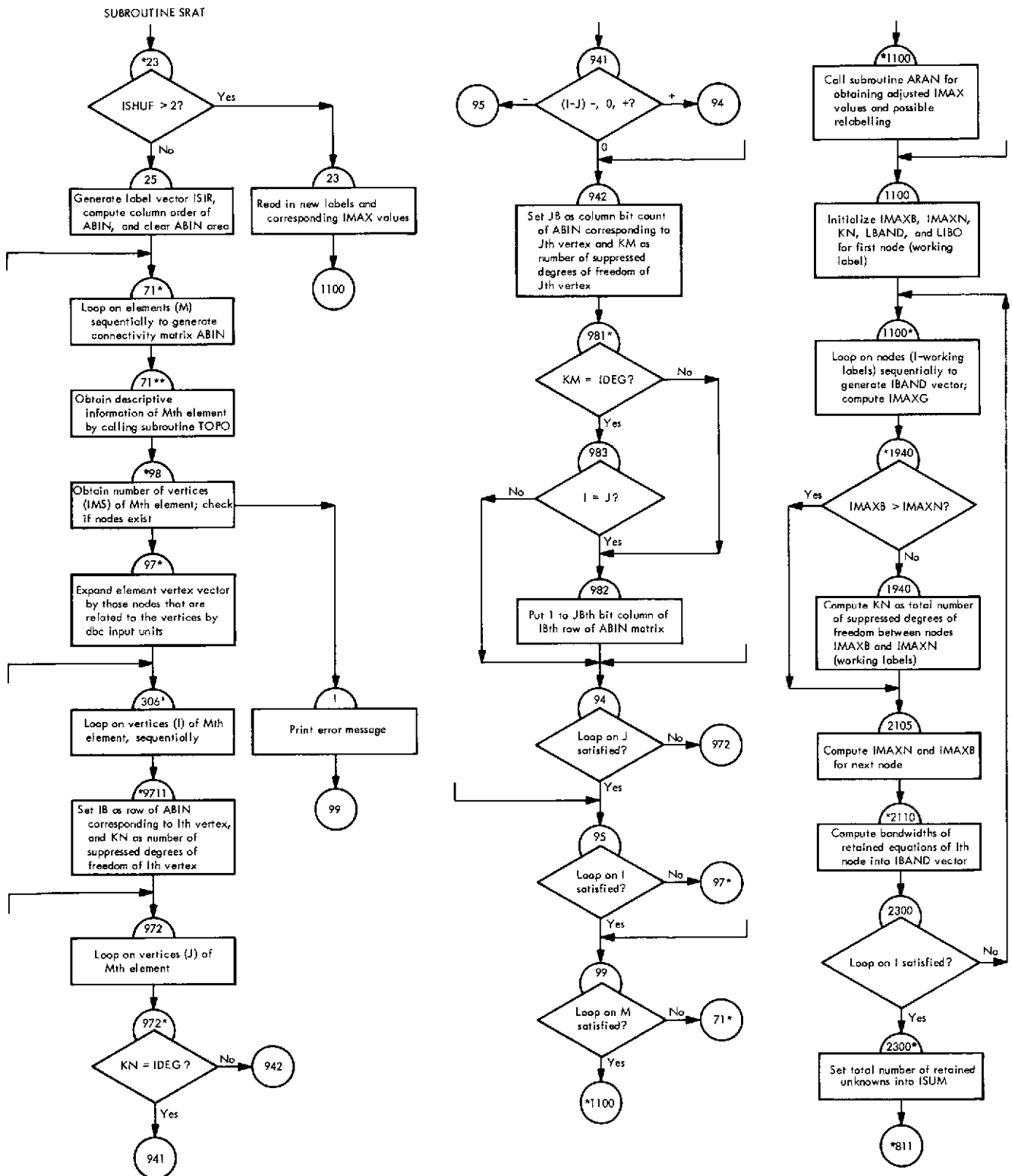


Fig. VI-9. Flowchart of subroutine SRAT (Link 1)

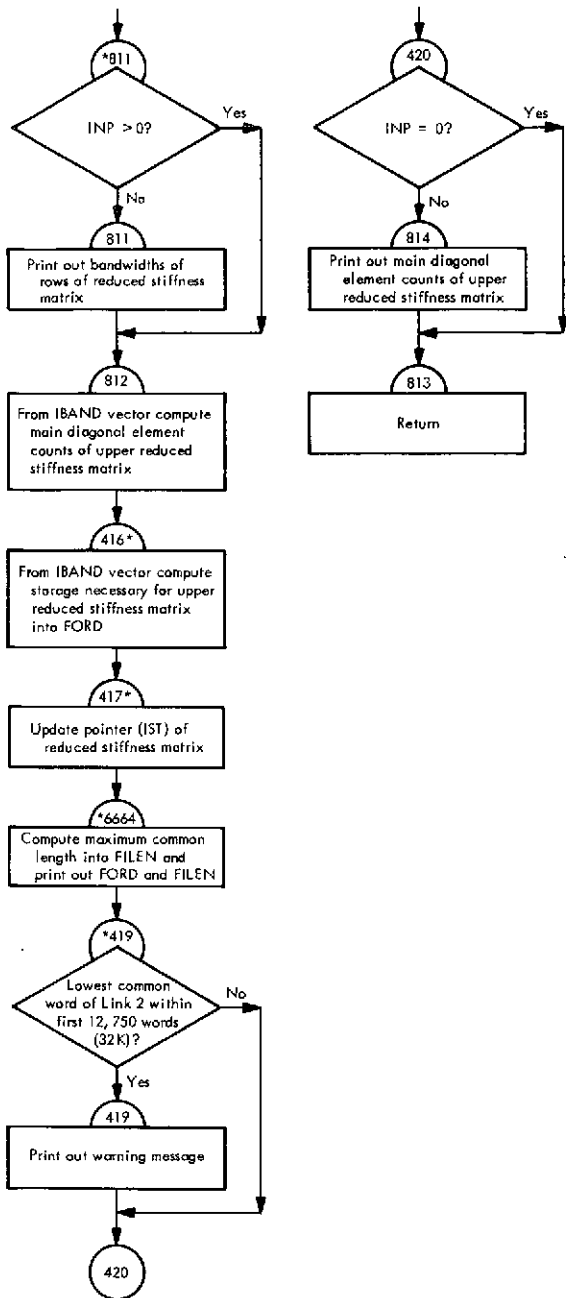


Fig. VI-9 (contd)

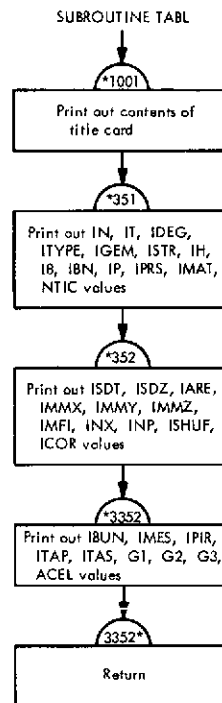
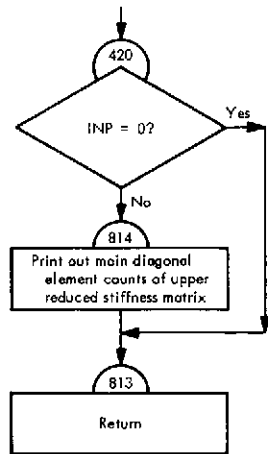
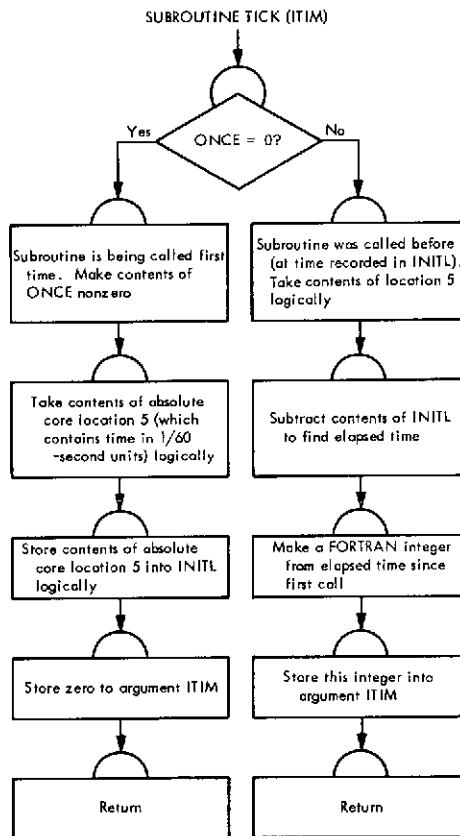


Fig. VI-10. Flowchart of subroutine TABL (Link 1)



**Fig. VI-11. Flowchart of subroutine TICK (Link 1)**

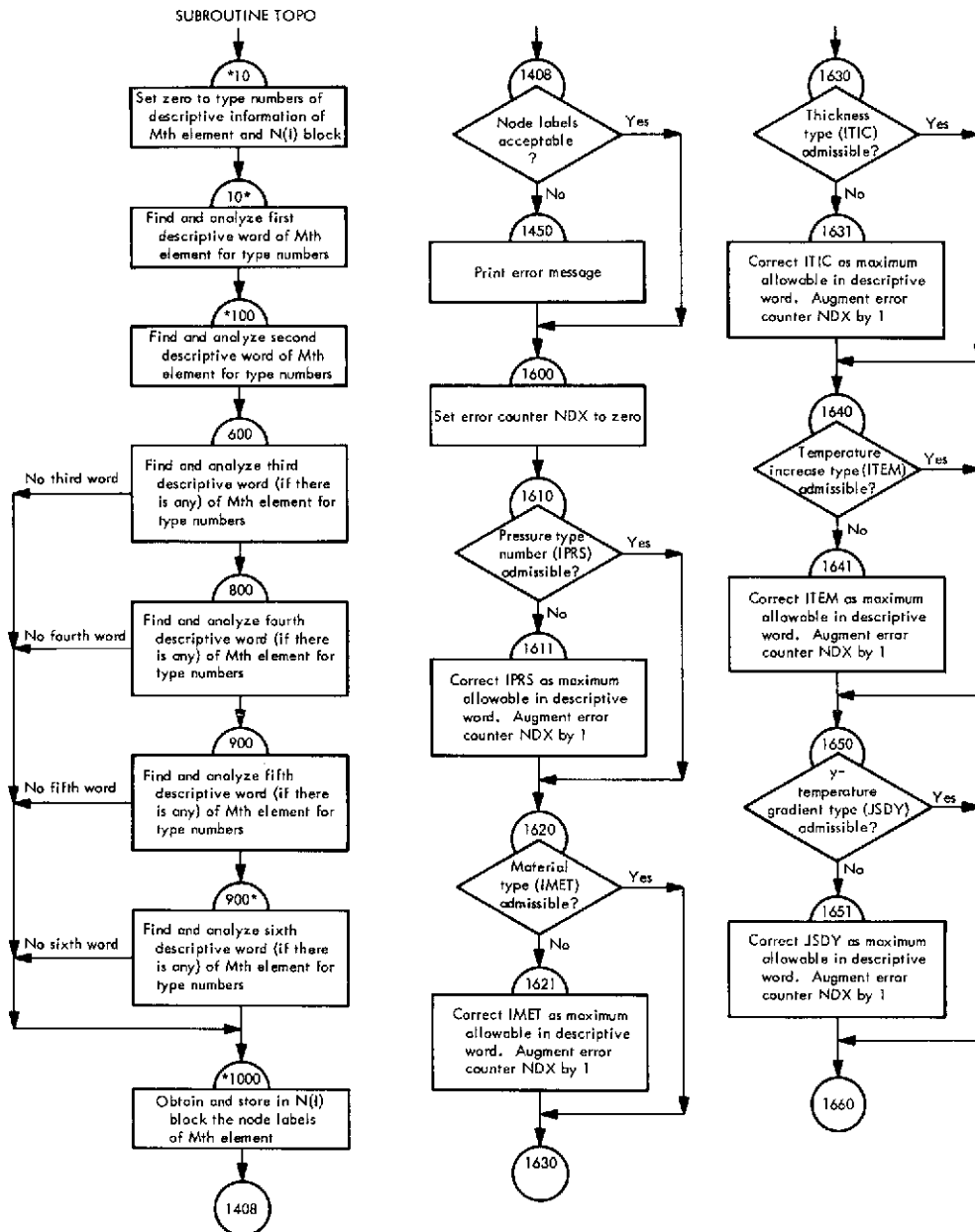


Fig. VI-12. Flowchart of subroutine TOPO (Link 1)

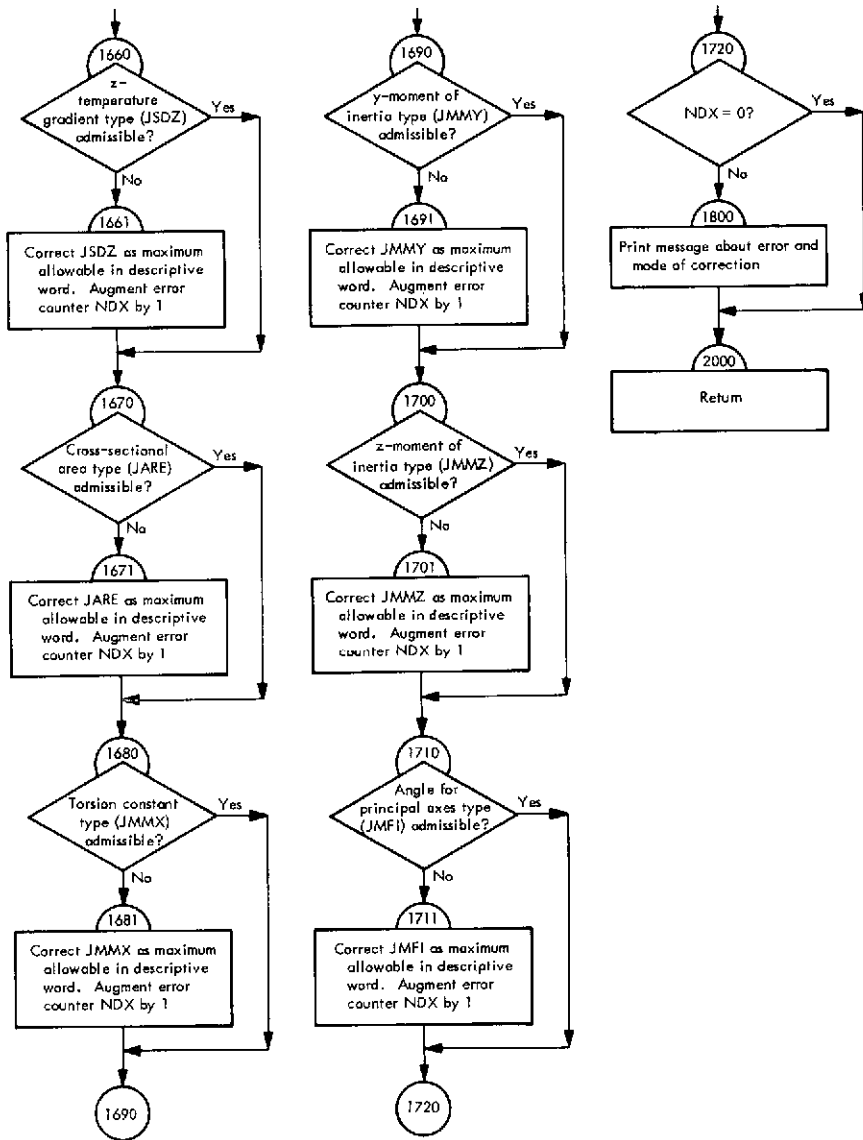


Fig. VI-12 (contd)

MAIN PROGRAM OF LINK 2

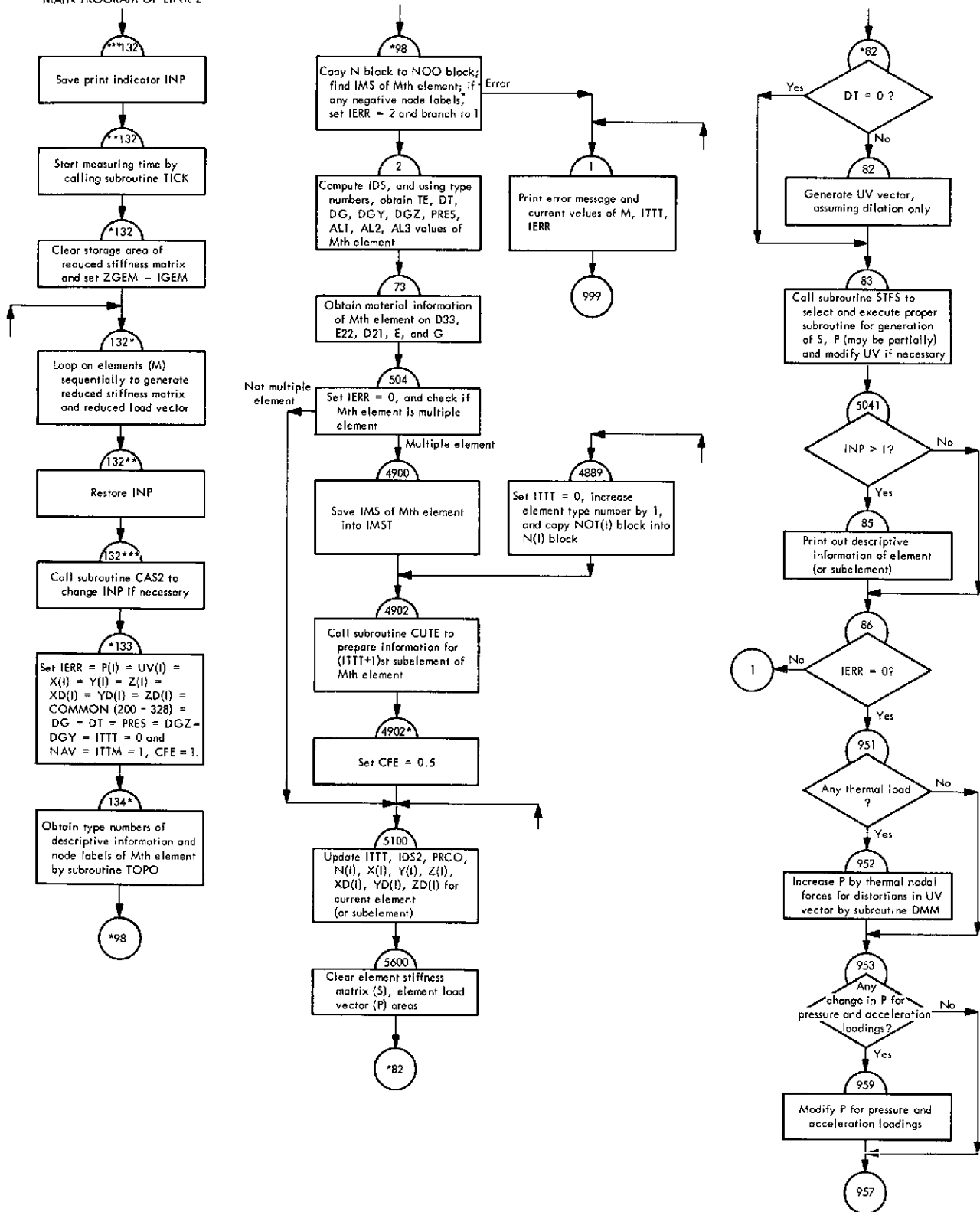


Fig. VI-13. Flowchart of main program of Link 2 (generation link)



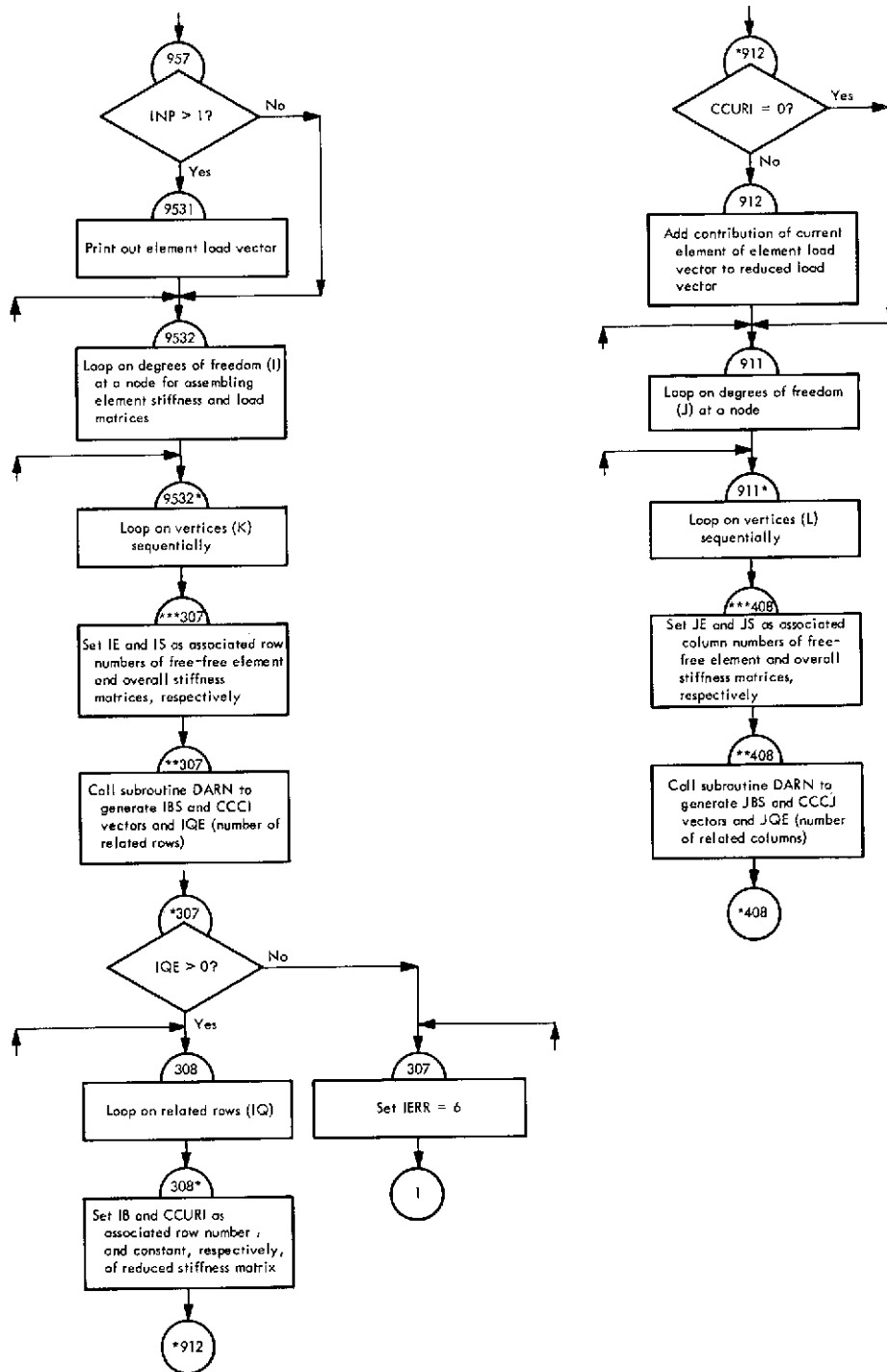


Fig. VI-13 (contd)

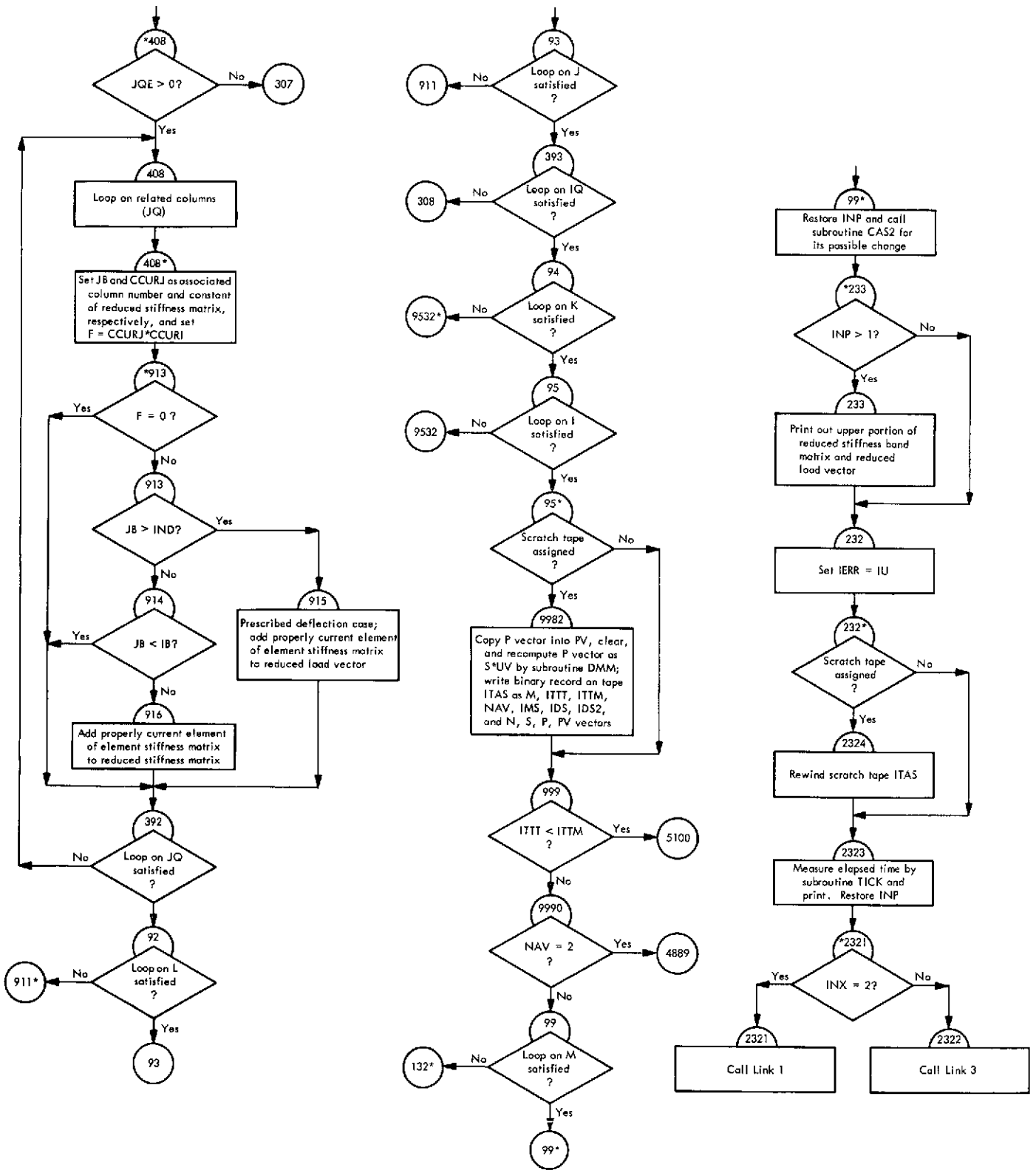


Fig. VI-13 (contd)

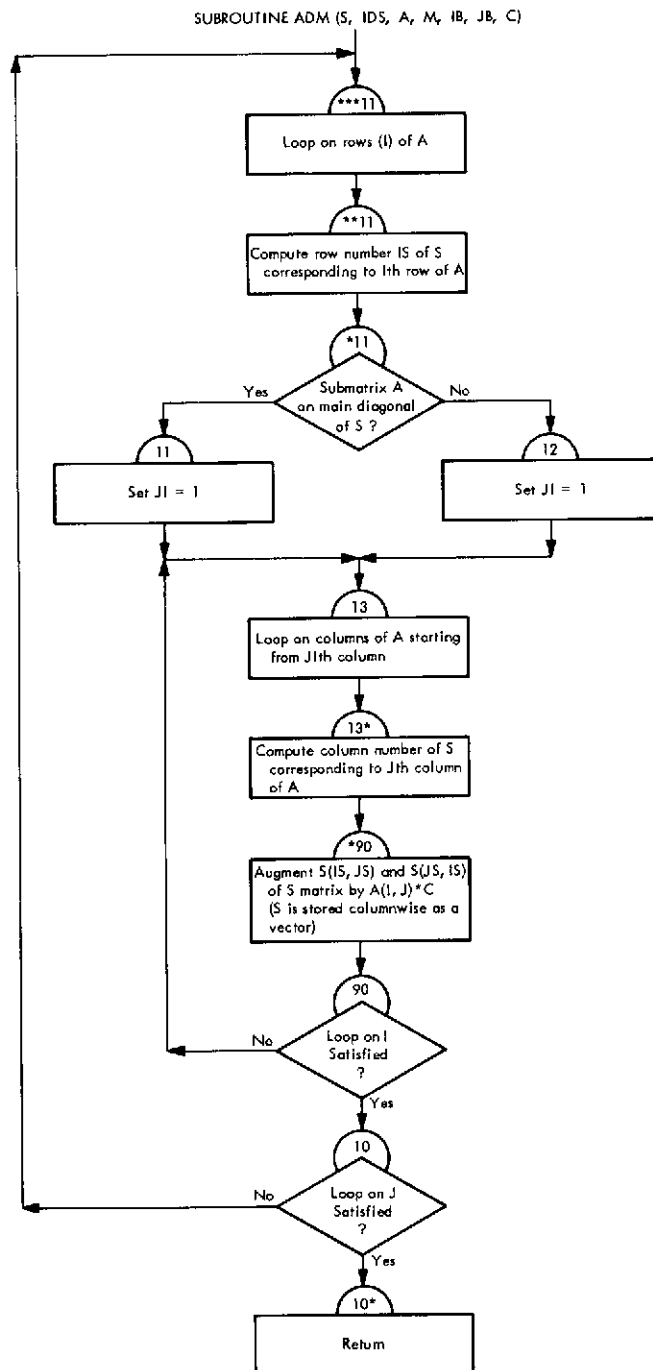


Fig. VI-14. Flowchart of subroutine ADM (Link 2)

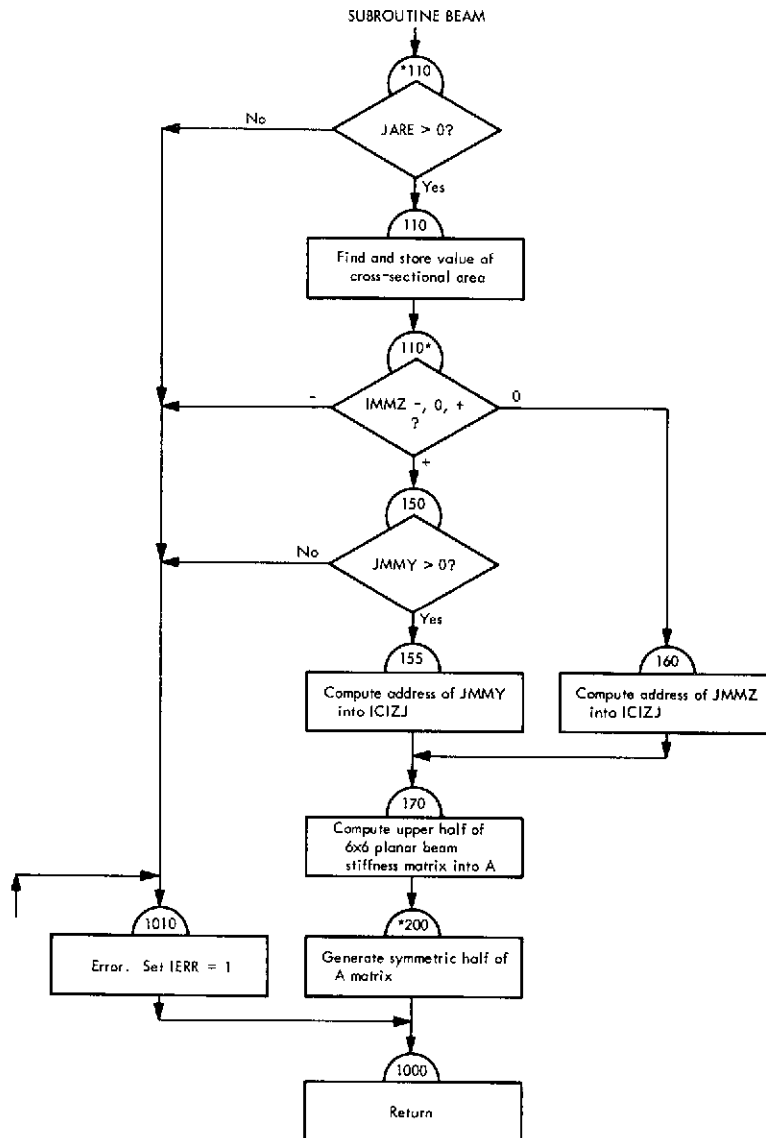


Fig. VI-15. Flowchart of subroutine BEAM (Link 2)

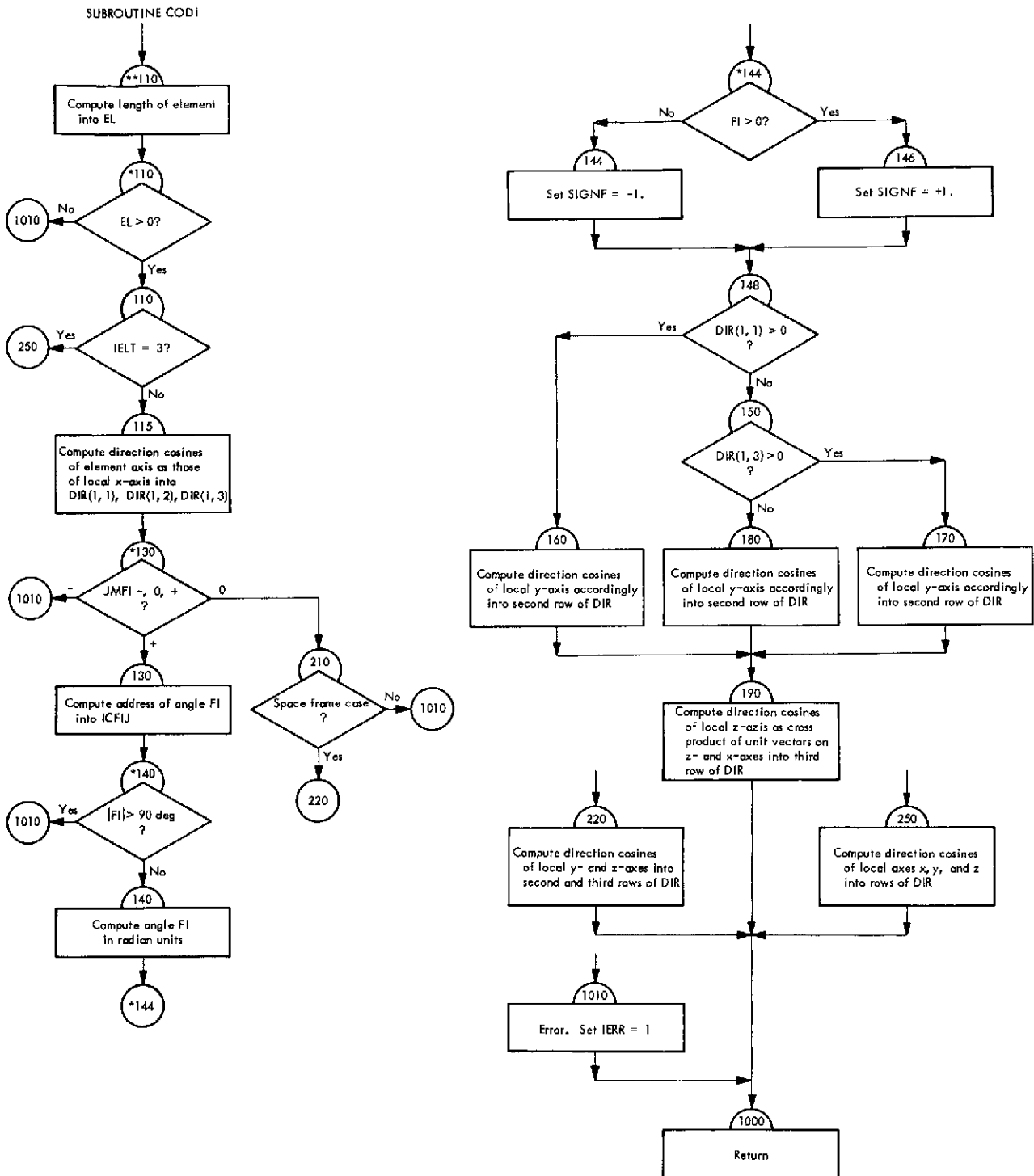


Fig. VI-16. Flowchart of subroutine CODI (Link 2)

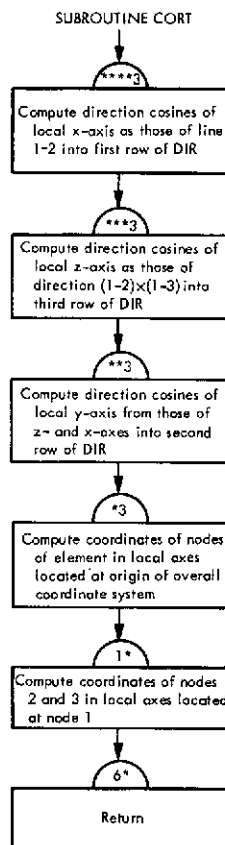


Fig. VI-17. Flowchart of subroutine CORT (Link 2)

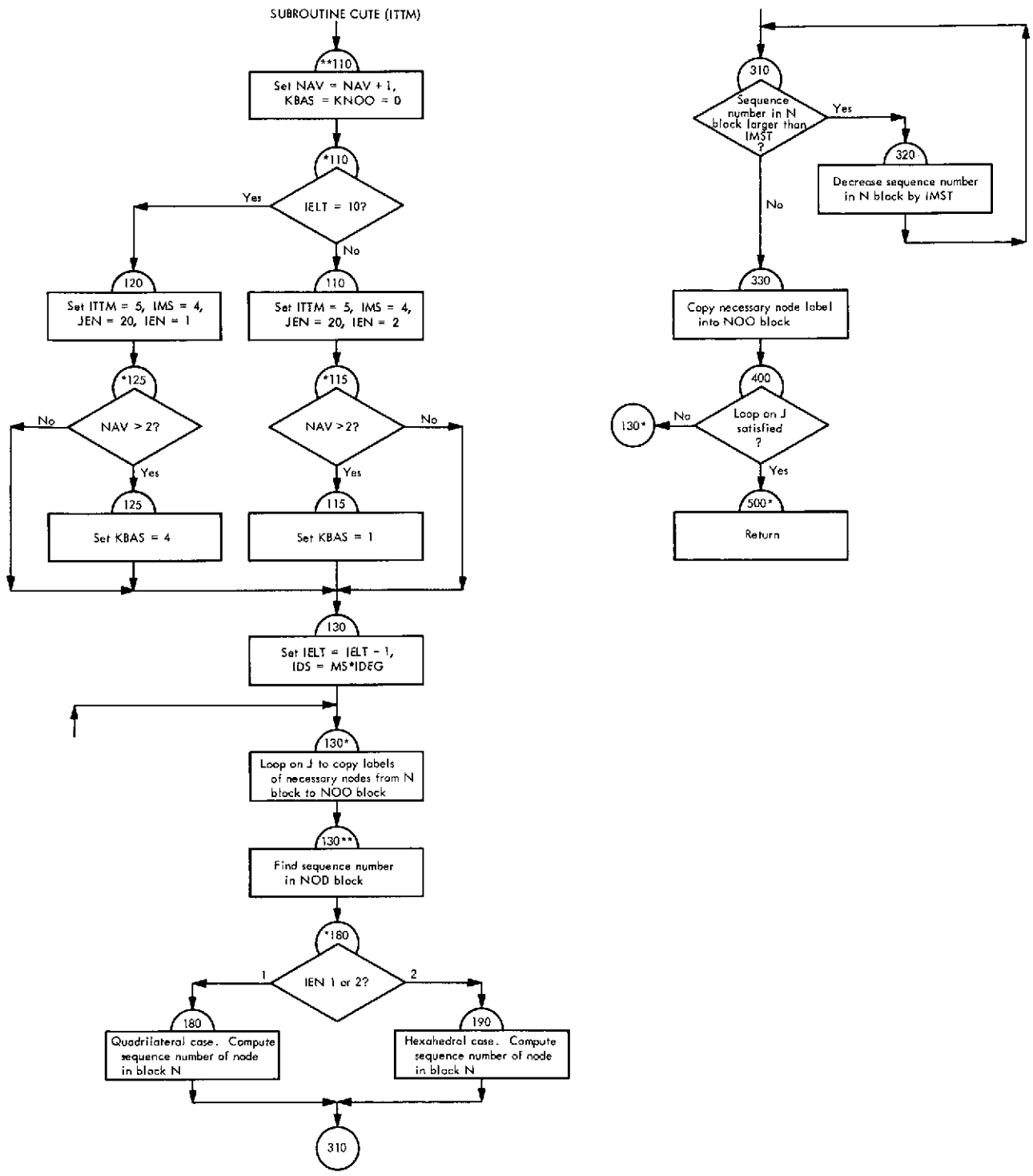


Fig. VI-18. Flowchart of subroutine CUTE (Link 2)

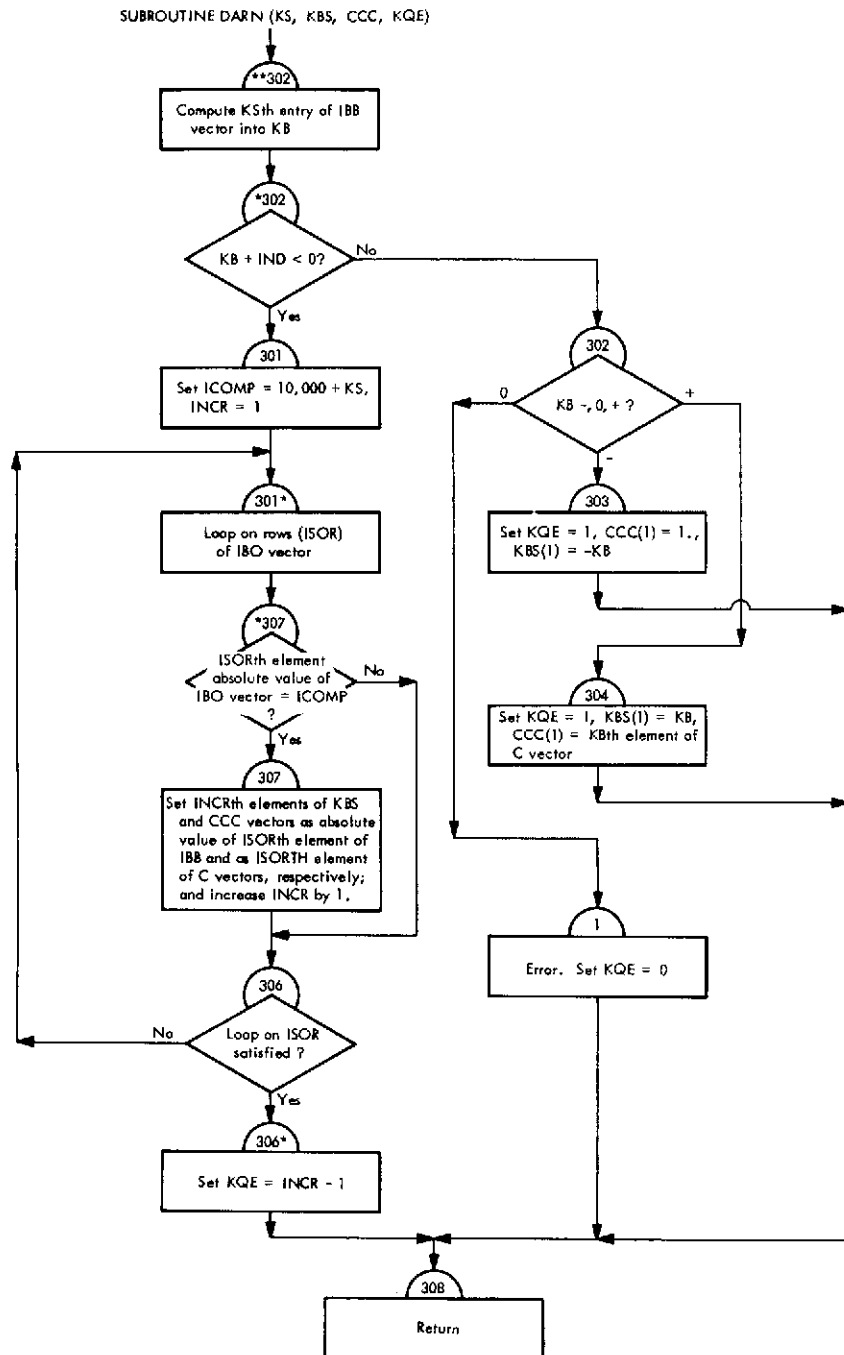


Fig. VI-19. Flowchart of subroutine DARN (Link 2)



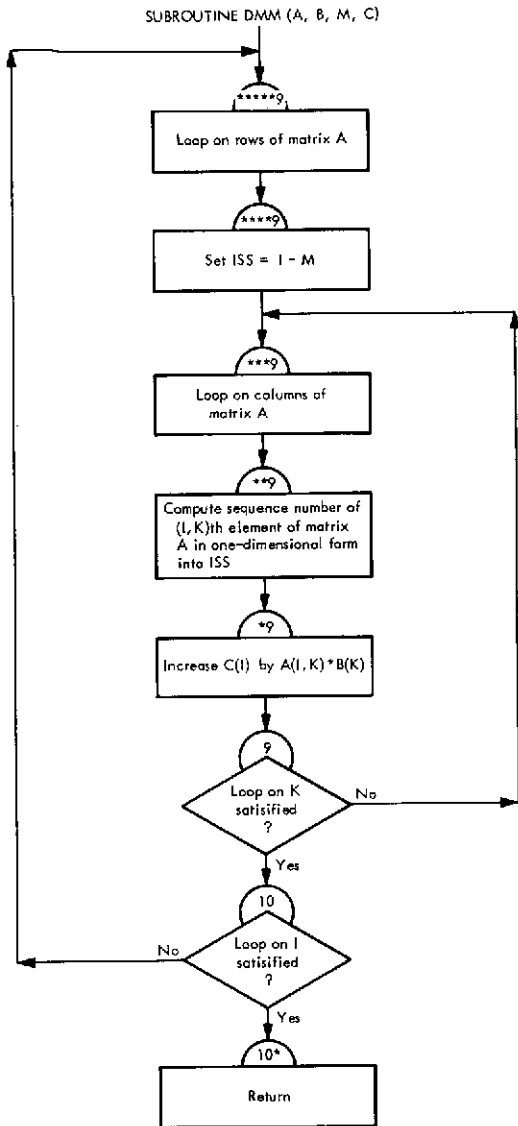


Fig. VI-20. Flowchart of subroutine DMM (Link 2)

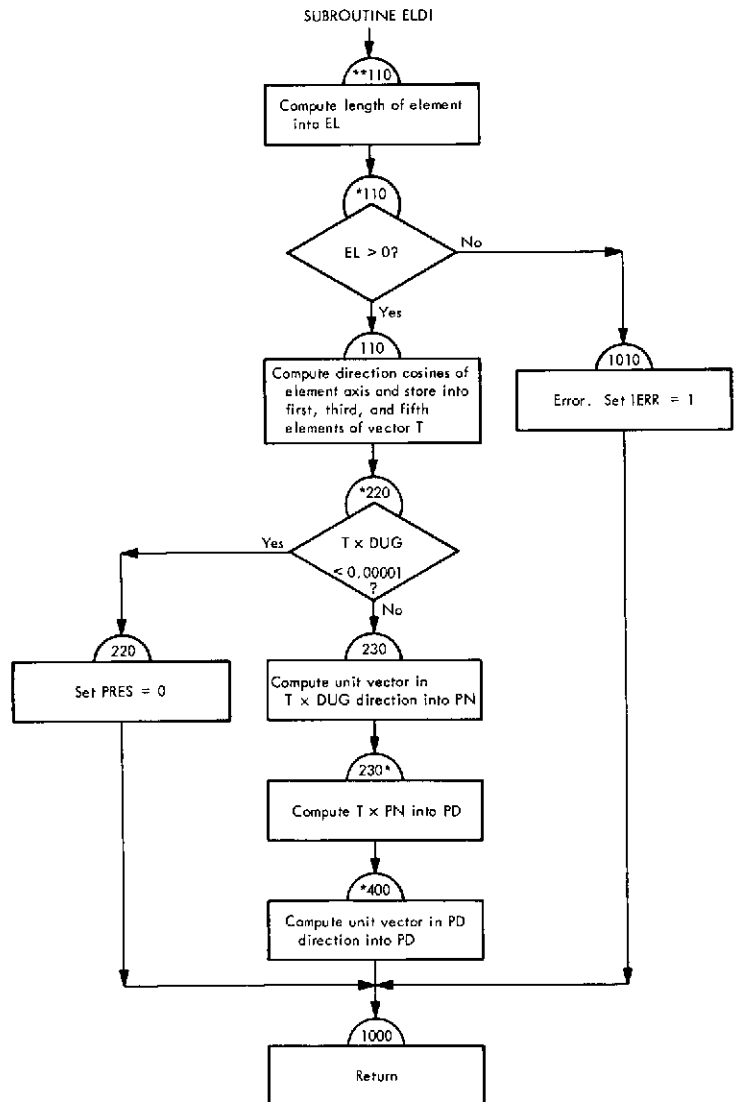


Fig. VI-21. Flowchart of subroutine ELDI (Link 2)

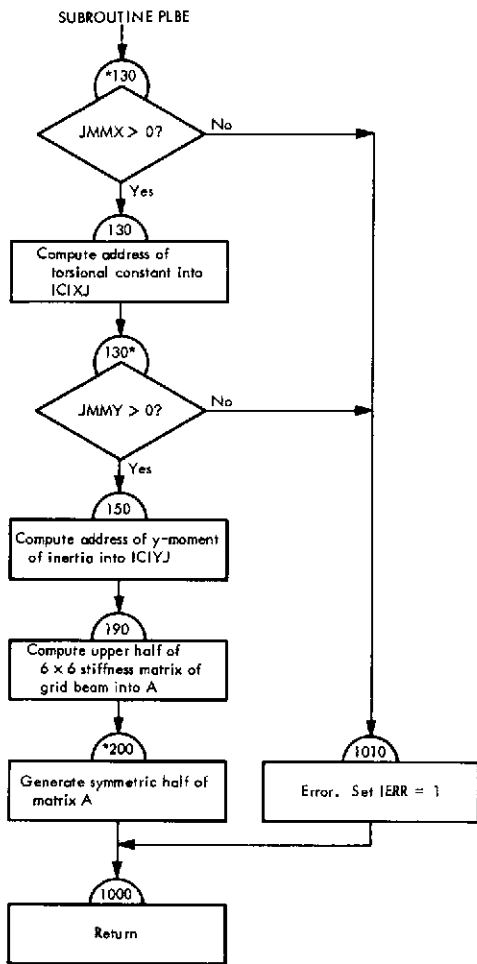


Fig. VI-22. Flowchart of subroutine PLBE (Link 2)

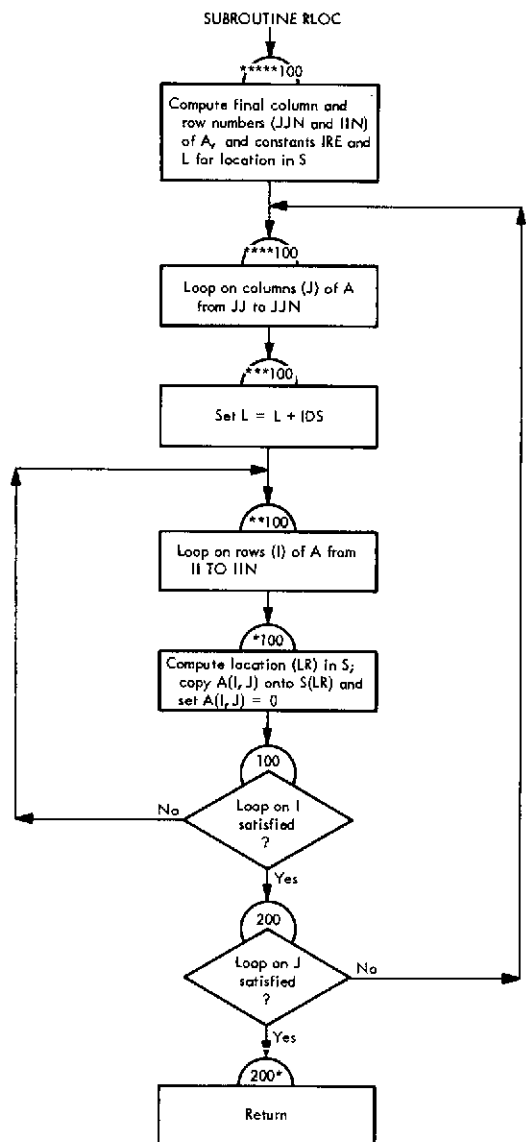


Fig. VI-23. Flowchart of subroutine RLOC (Link 2)

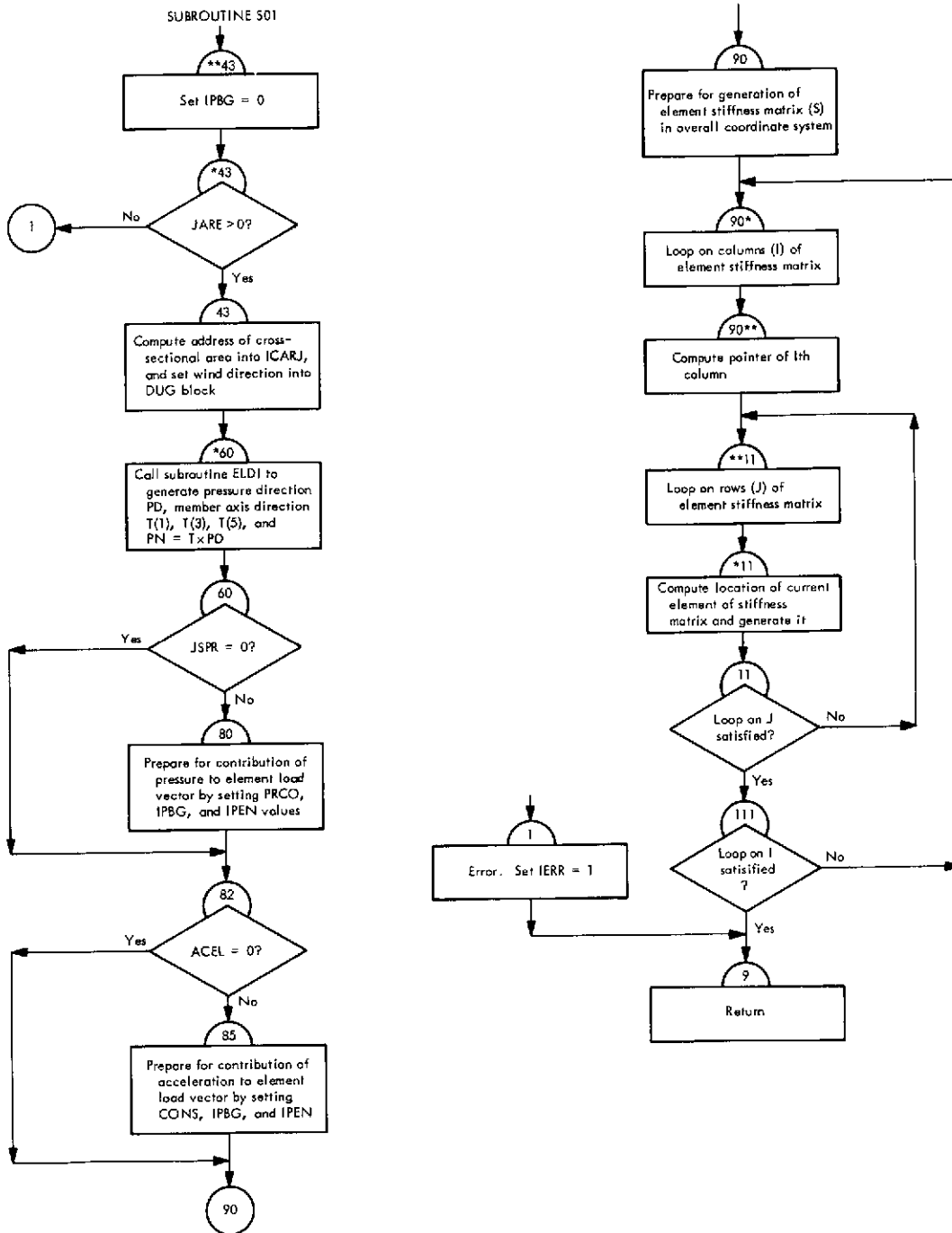


Fig. VI-24. Flowchart of subroutine S01 (Link 2)

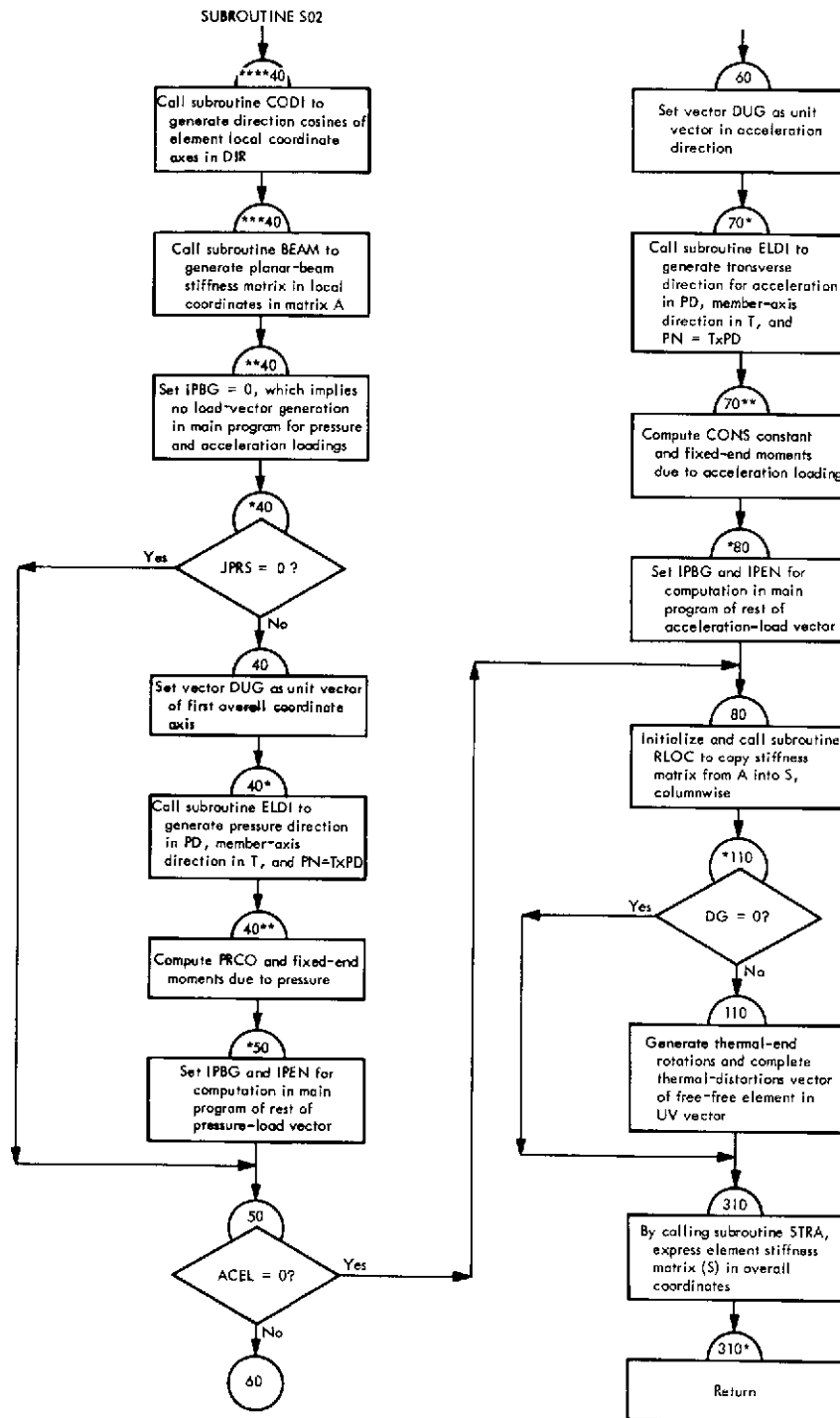


Fig. VI-25. Flowchart of subroutine S02 (Link 2)

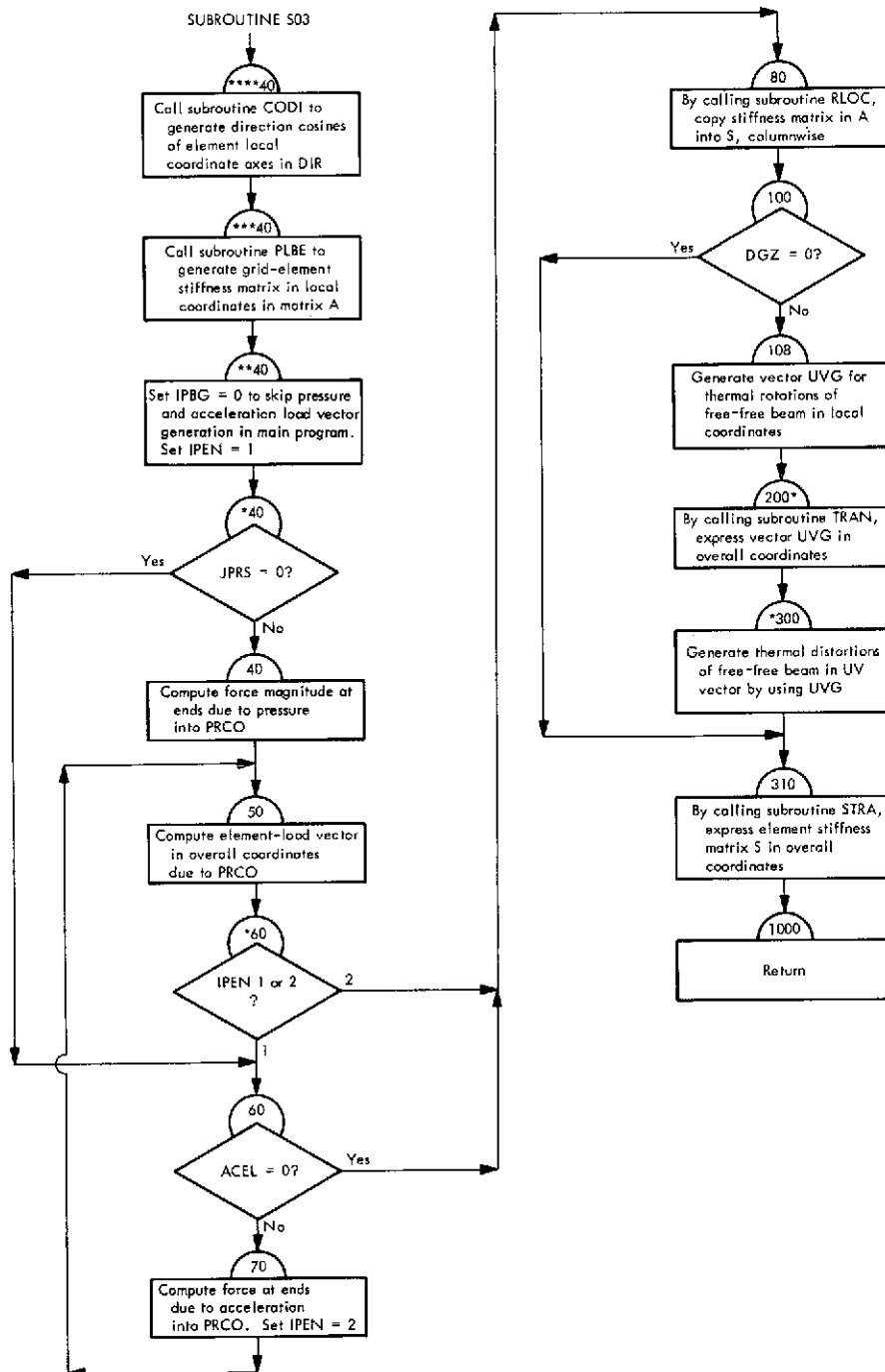


Fig. VI-26. Flowchart of subroutine S03 (Link 2)

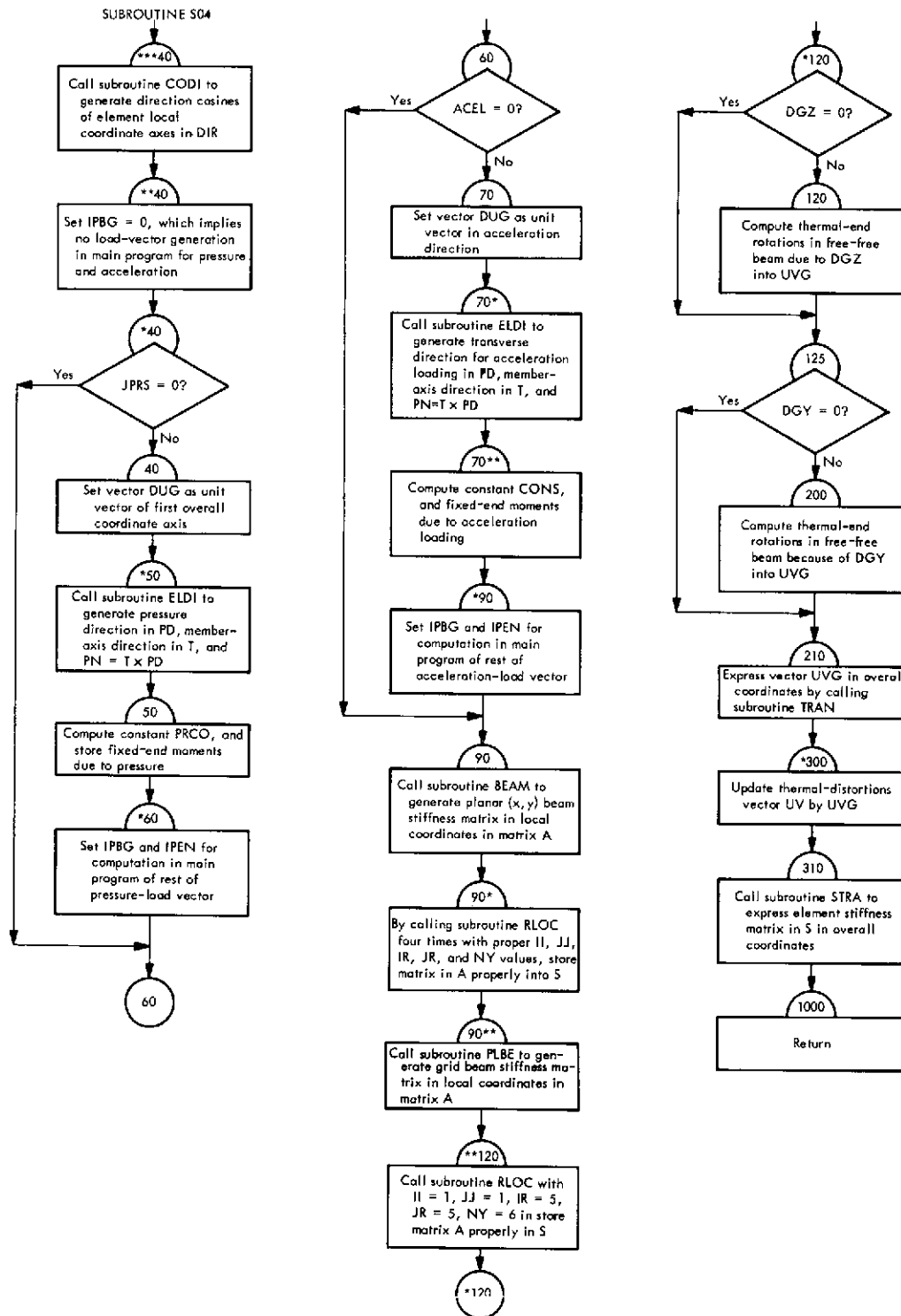
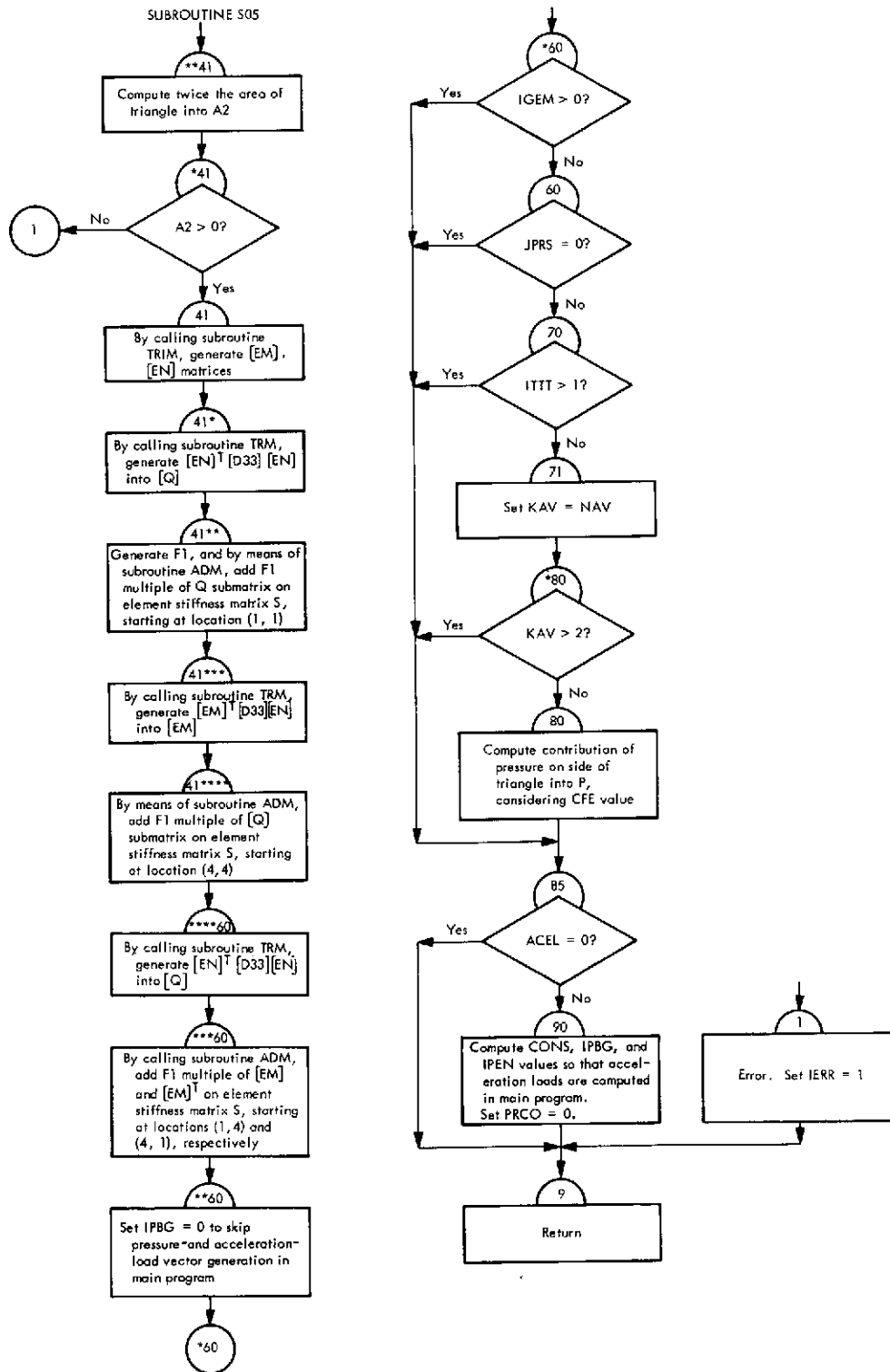


Fig. VI-27. Flowchart of subroutine S04 (Link 2)



**Fig. VI-28. Flowchart of subroutine S05 (Link 2)**

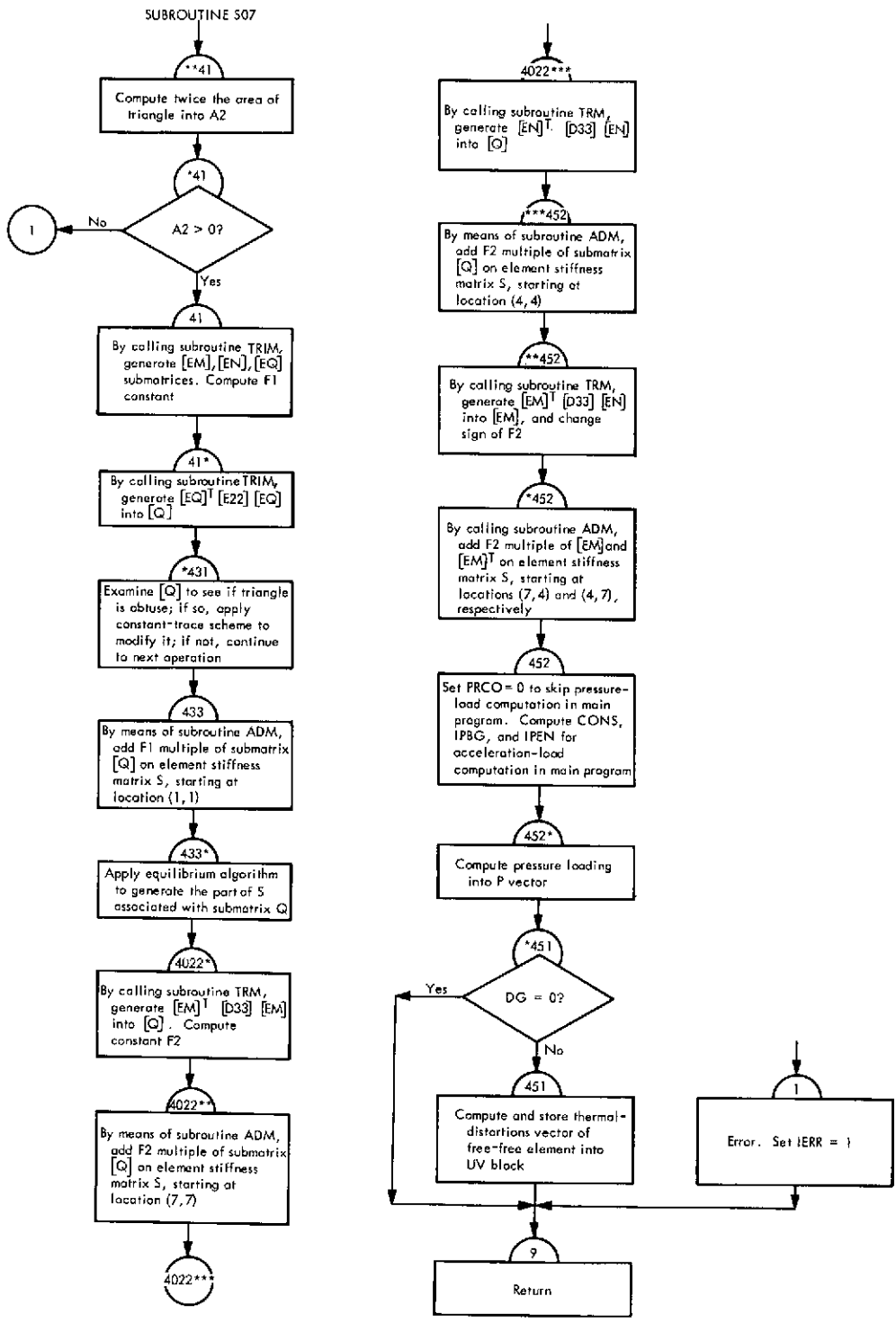


Fig. VI-29. Flowchart of subroutine S07 (Link 2)



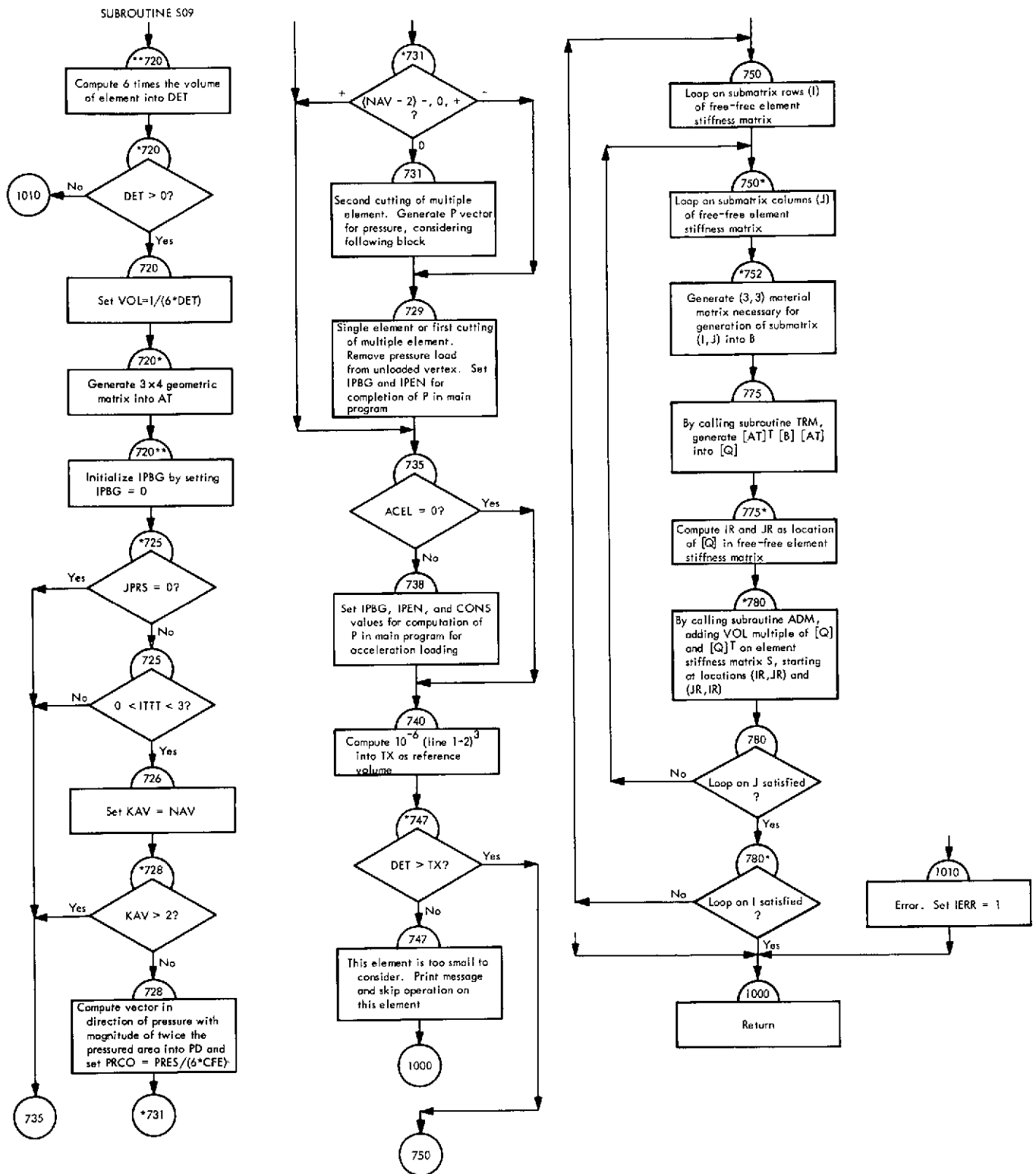


Fig. VI-30. Flowchart of subroutine S09 (Link 2)

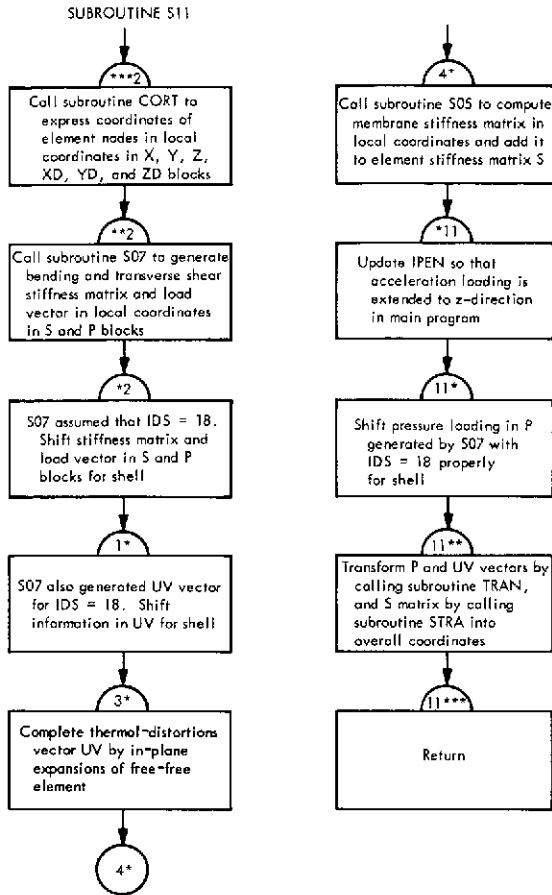


Fig. VI-31. Flowchart of subroutine S11 (Link 2)

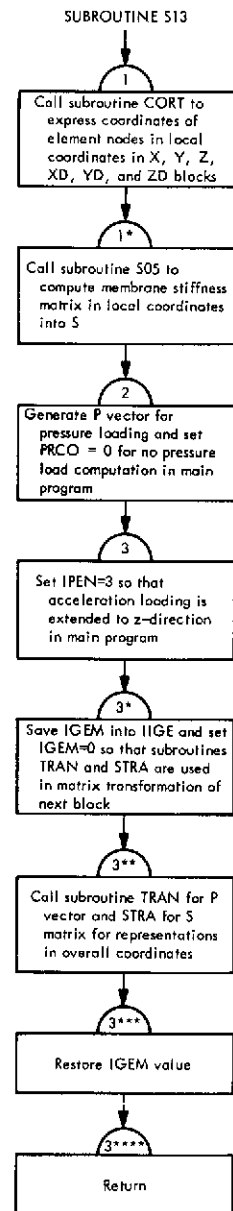
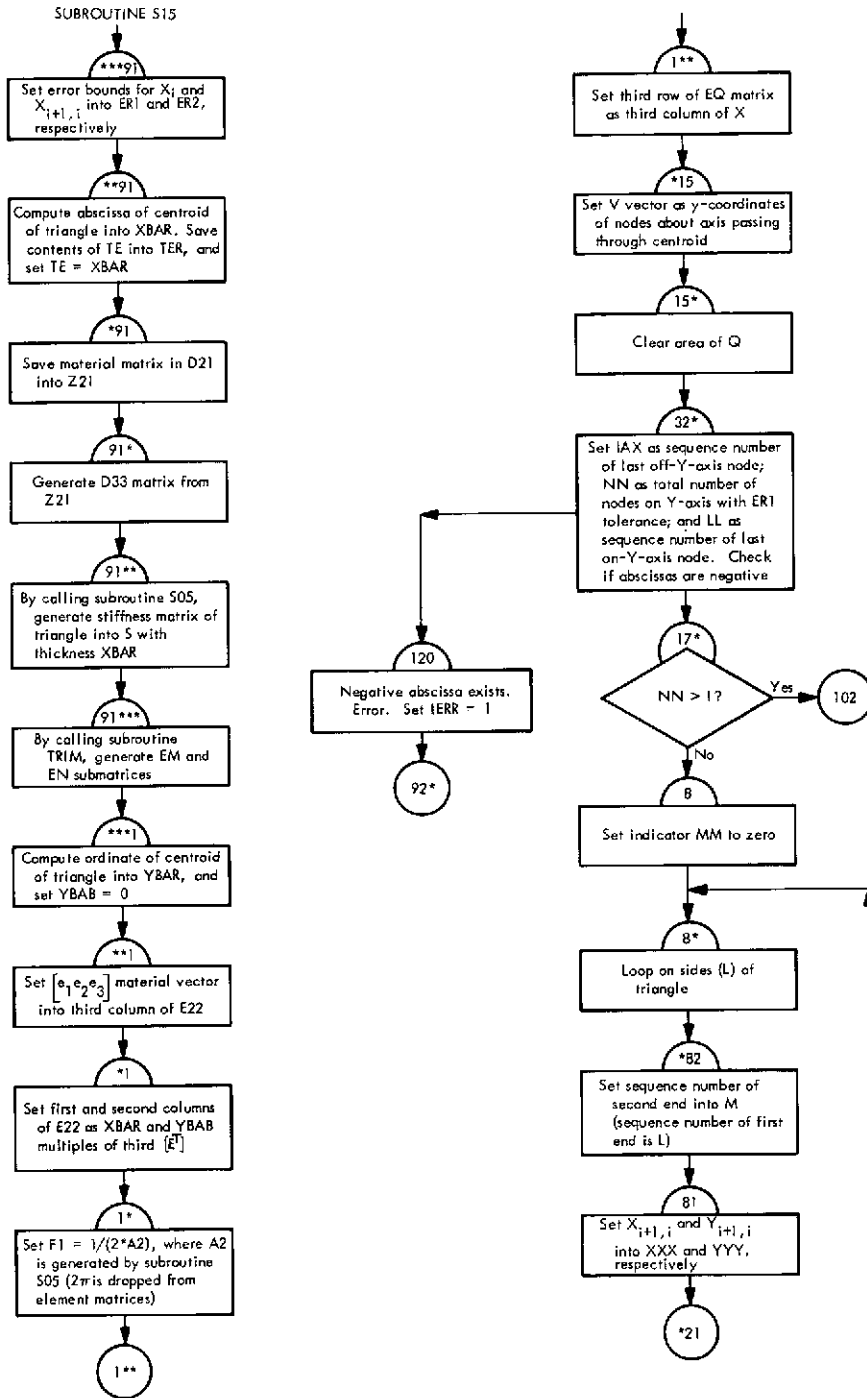


Fig. VI-32. Flowchart of subroutine S13 (Link 2)



**Fig. VI-33. Flowchart of subroutine S15 (Link 2)**

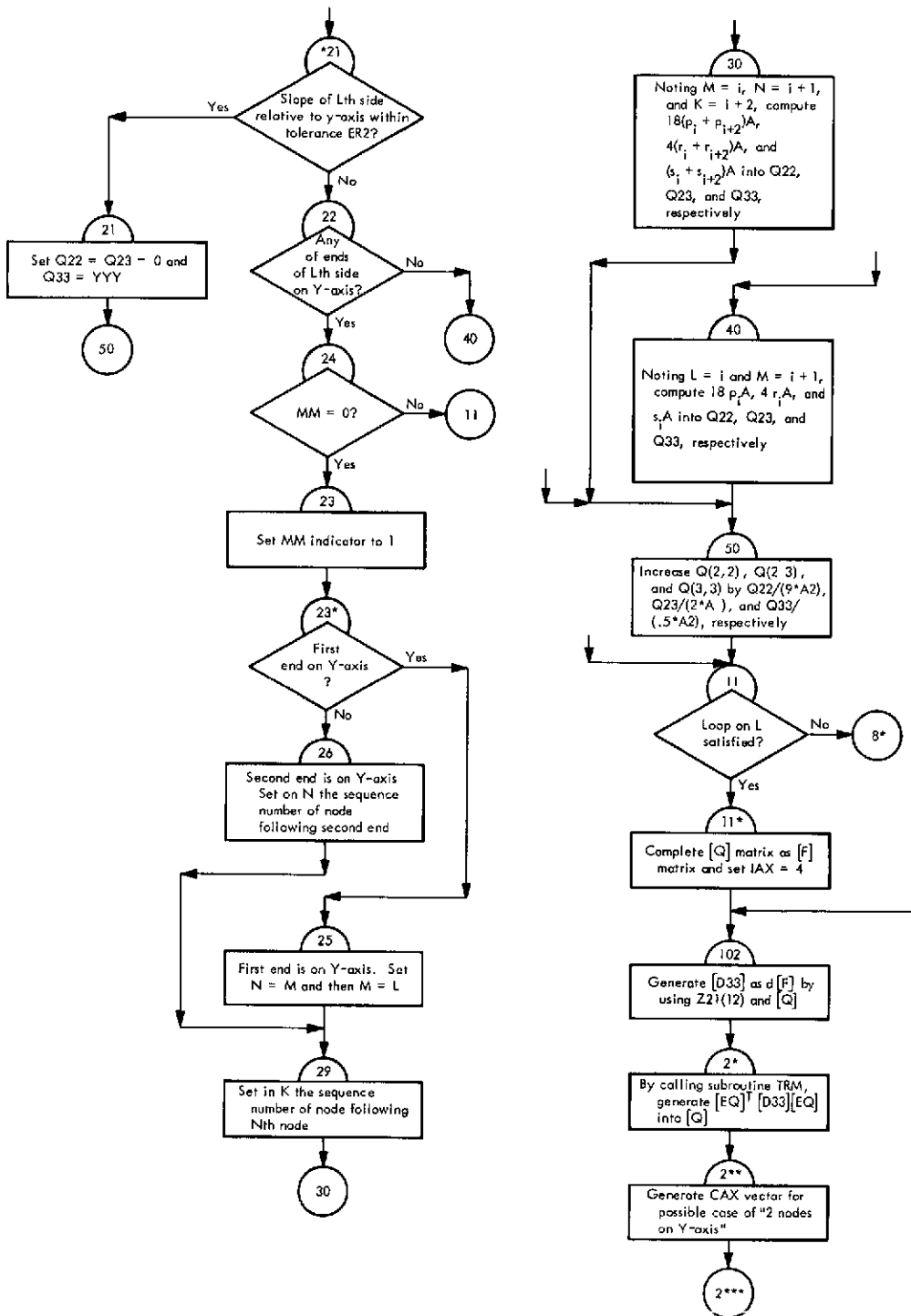


Fig. VI-33 (contd)

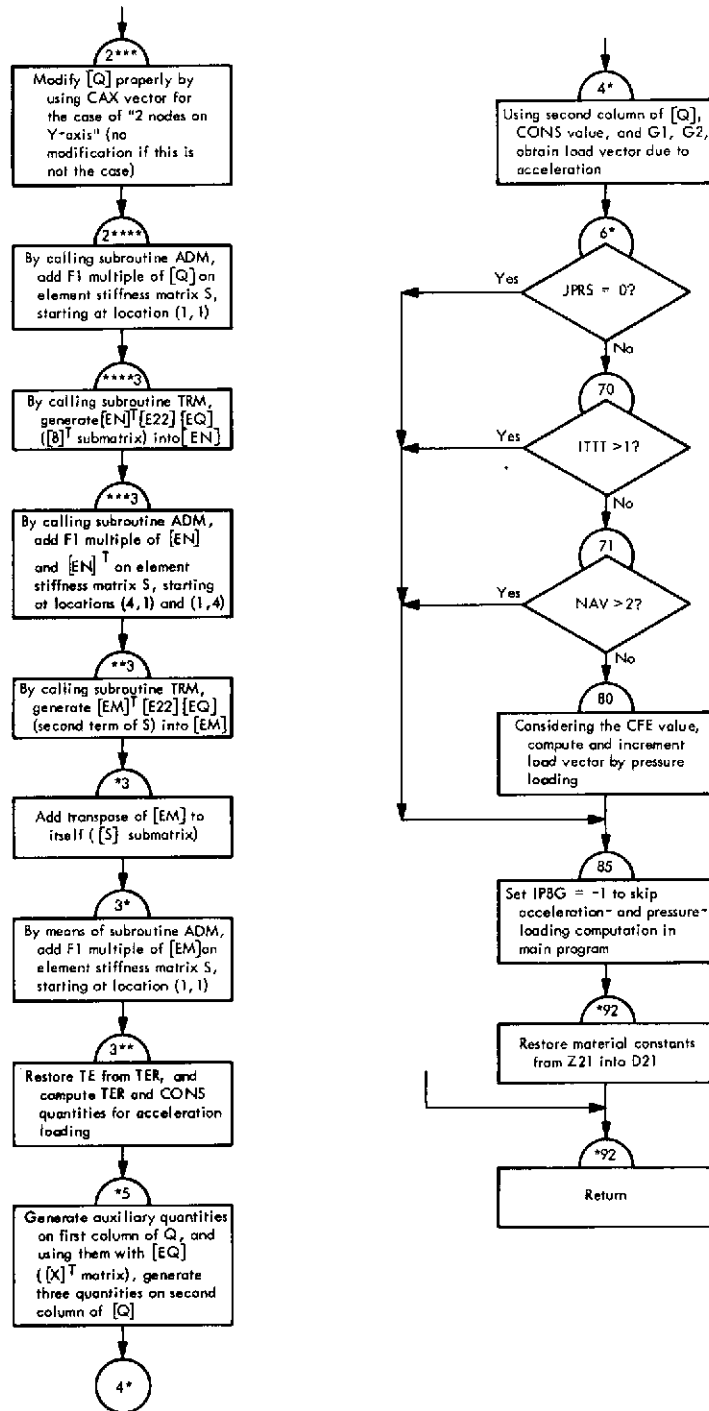


Fig. VI-33 (contd)

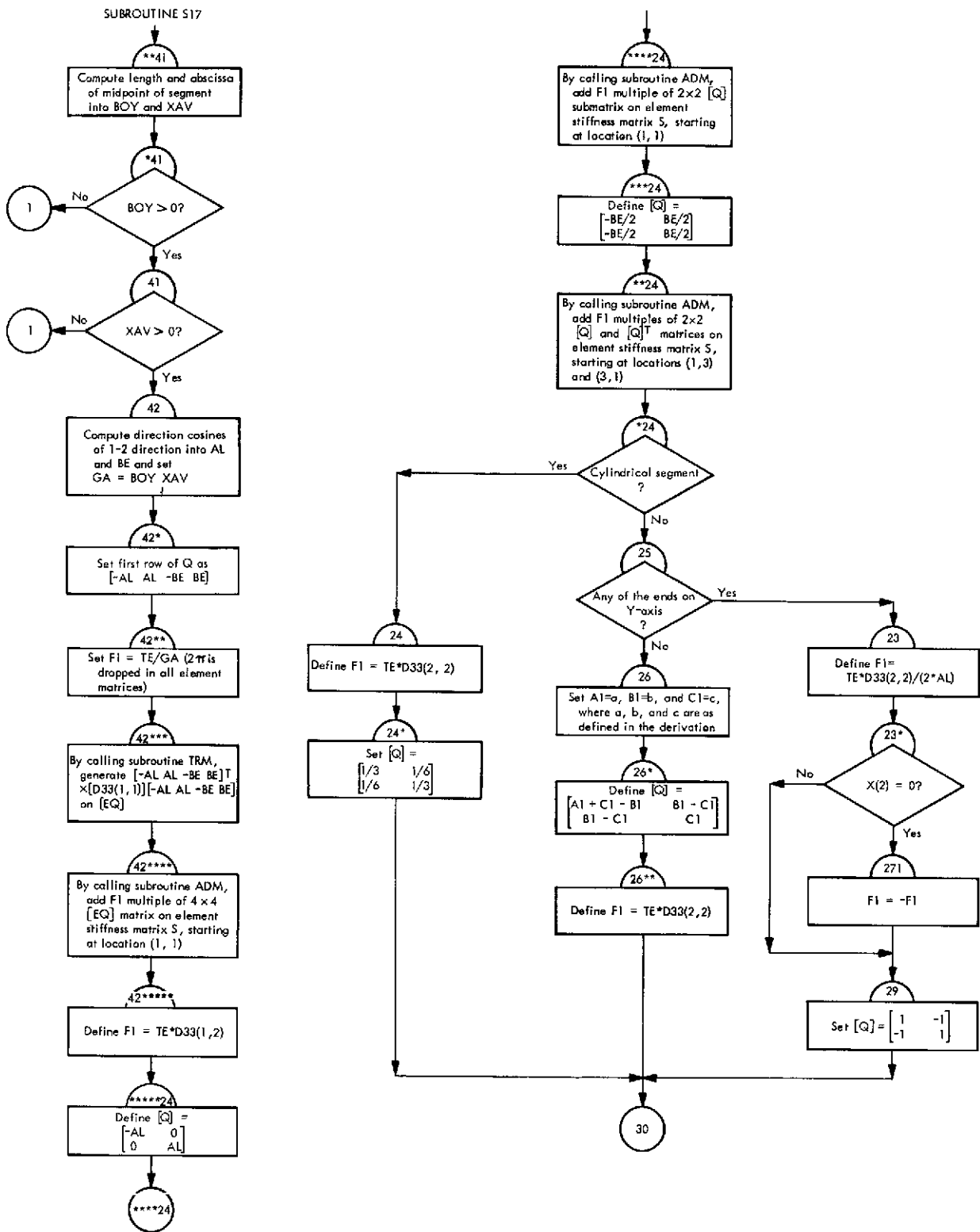


Fig. VI-34. Flowchart of subroutine S17 (Link 2)

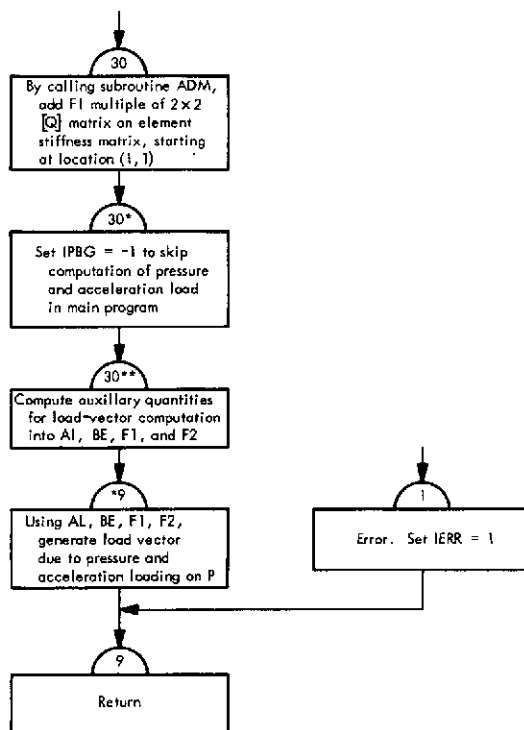


Fig. VI-34 (contd)

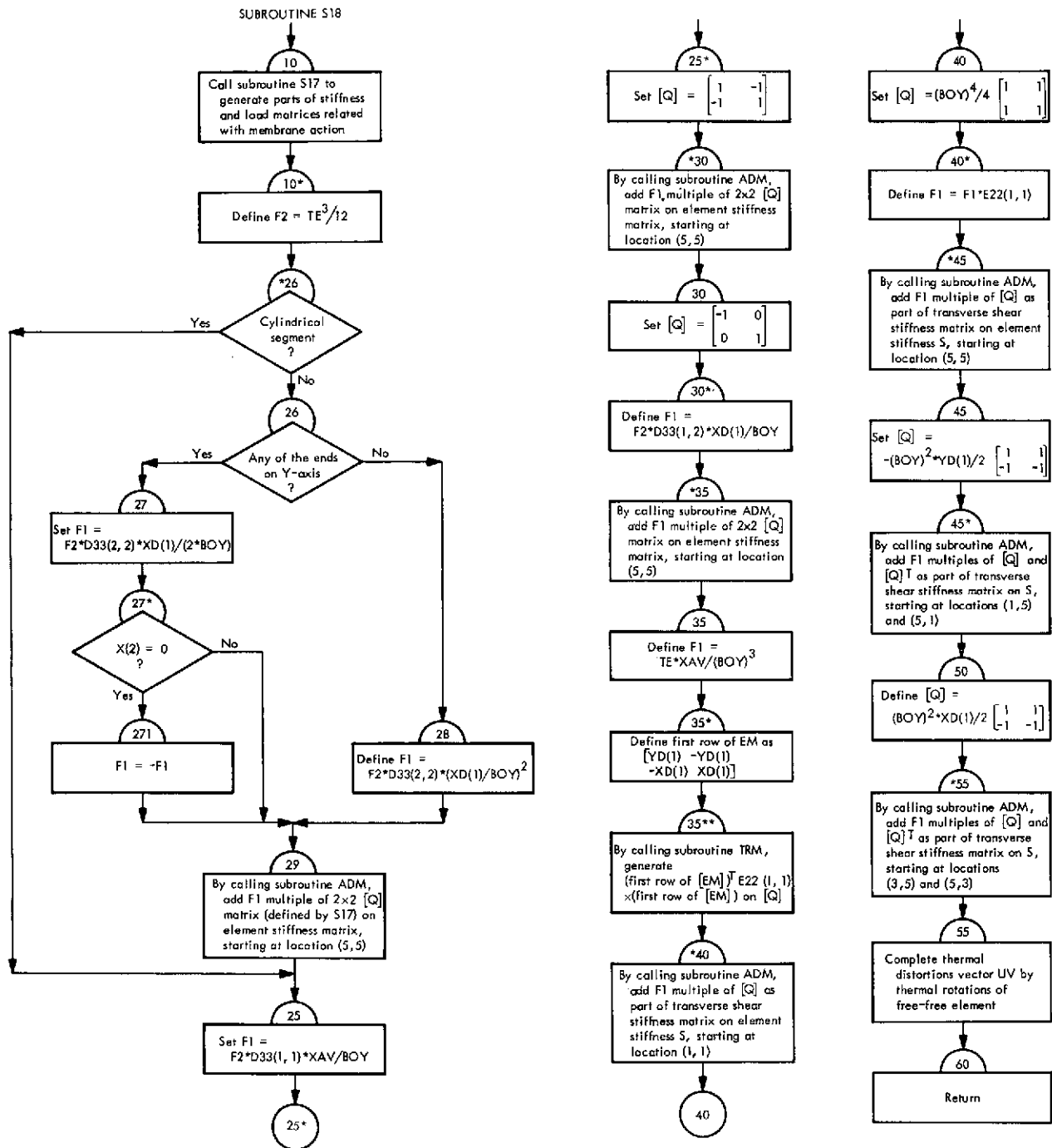


Fig. VI-35. Flowchart of subroutine S18 (Link 2)



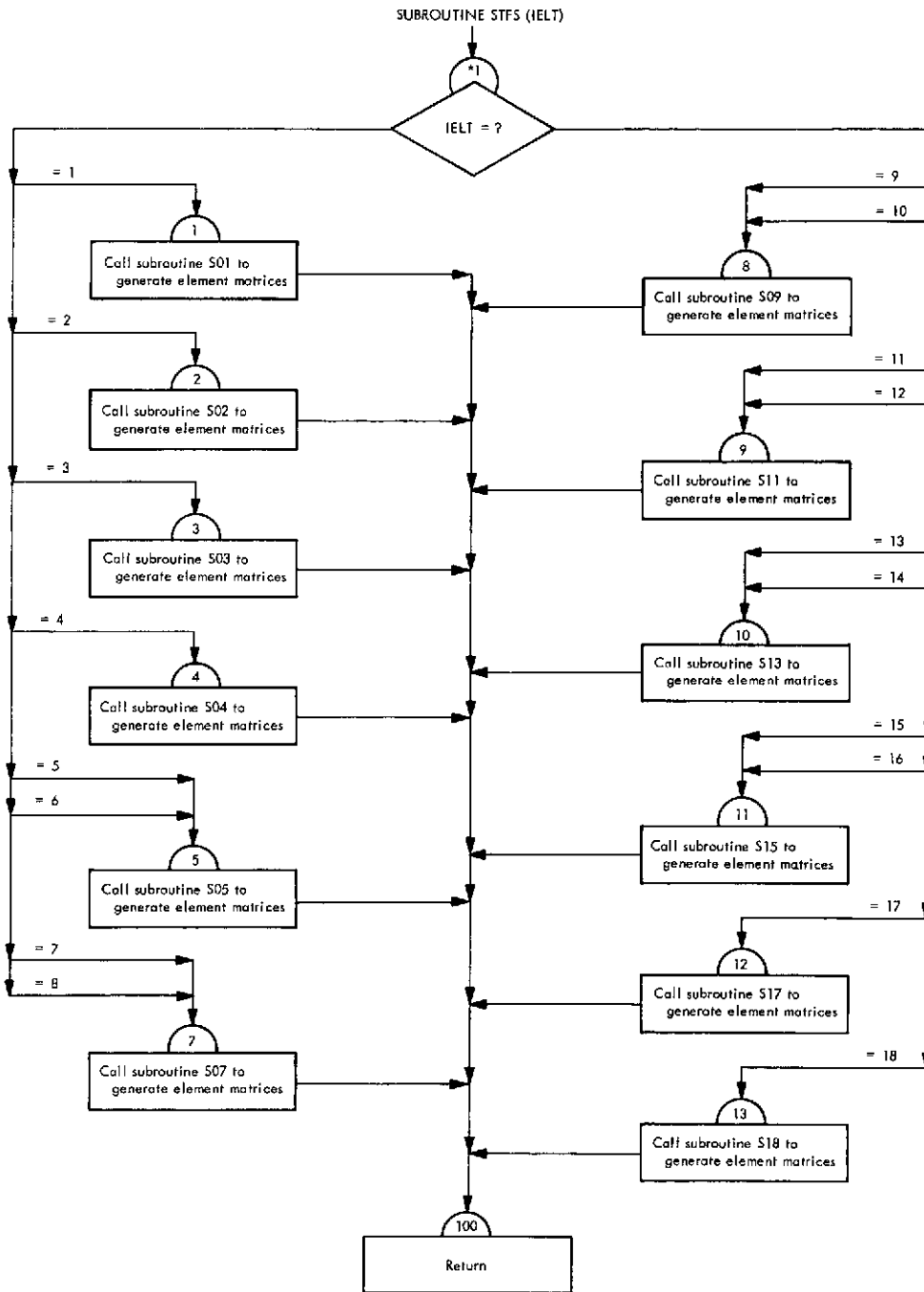


Fig. VI-36. Flowchart of subroutine STFS (Link 2)

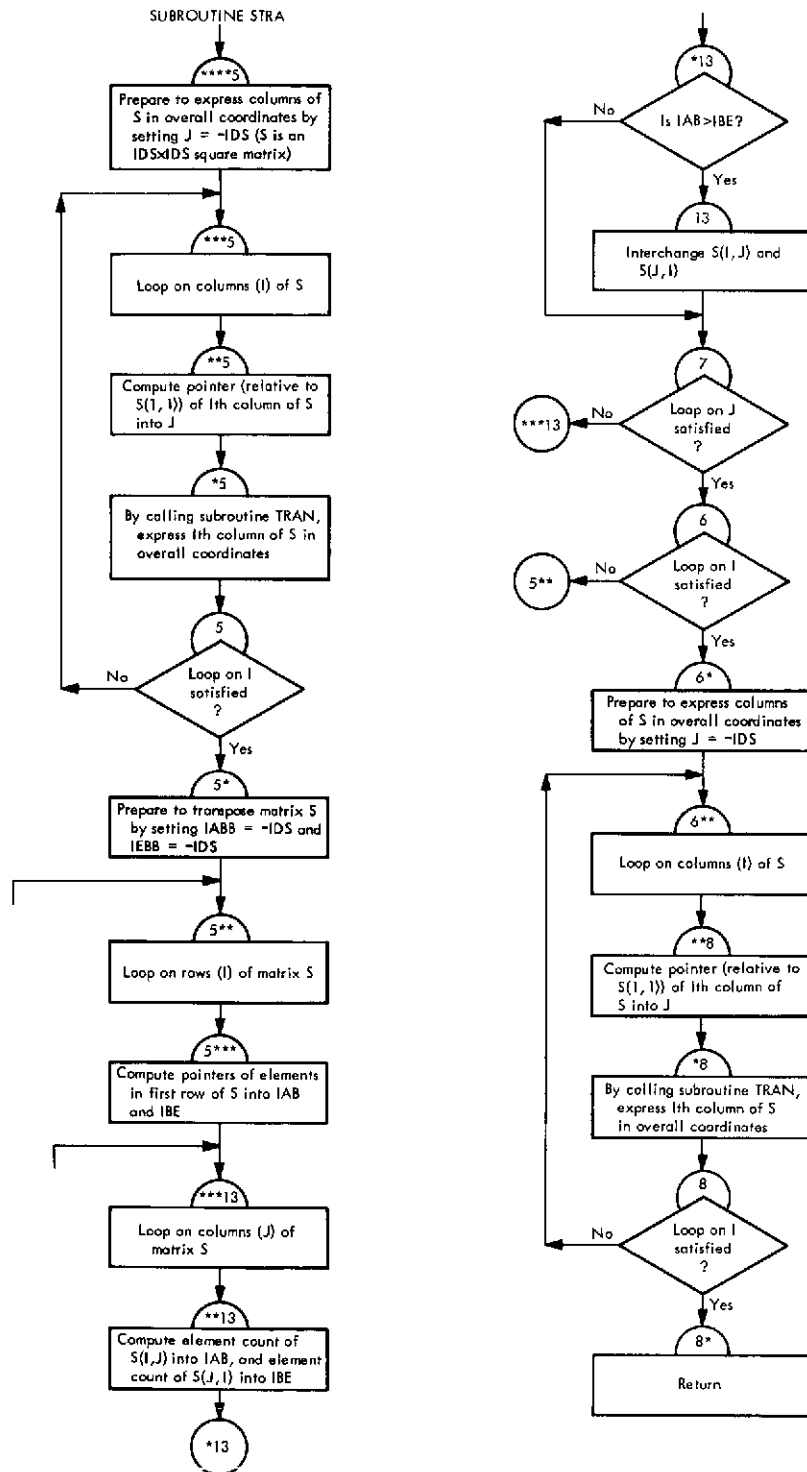


Fig. VI-37. Flowchart of subroutine STRA (Link 2)

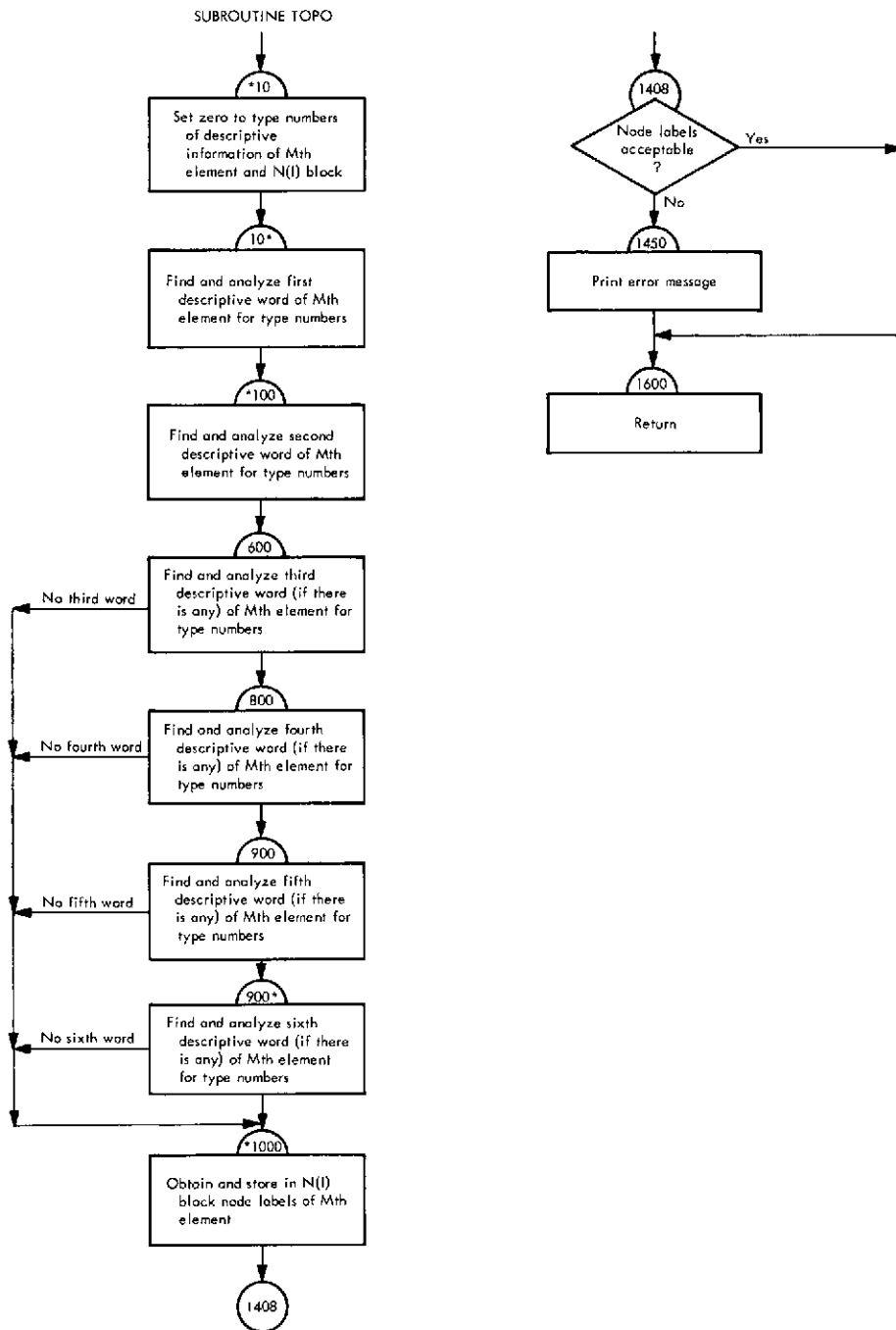


Fig. VI-38. Flowchart of subroutine TOPO (Link 2)

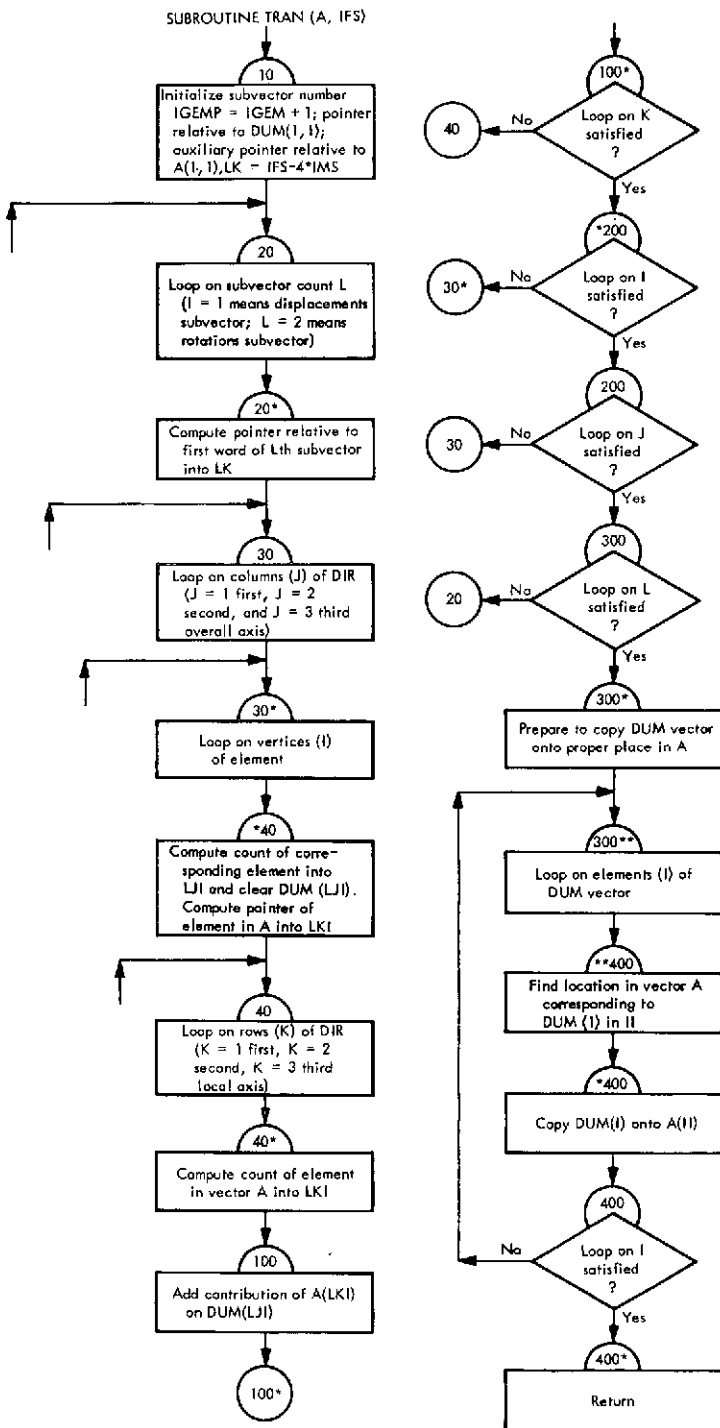


Fig. VI-39. Flowchart of subroutine TRAN (Link 2)

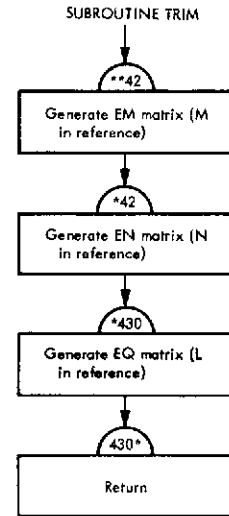


Fig. VI-40. Flowchart of subroutine TRIM (Link 2)

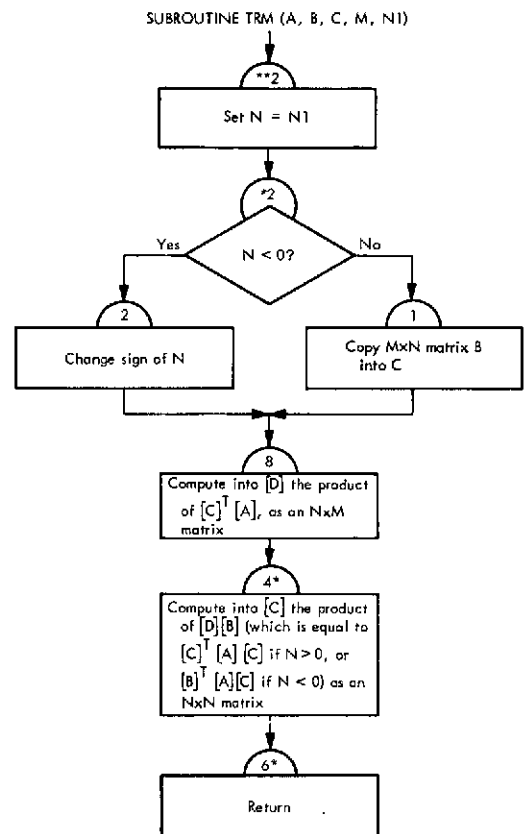


Fig. VI-41. Flowchart of subroutine TRM (Link 2)

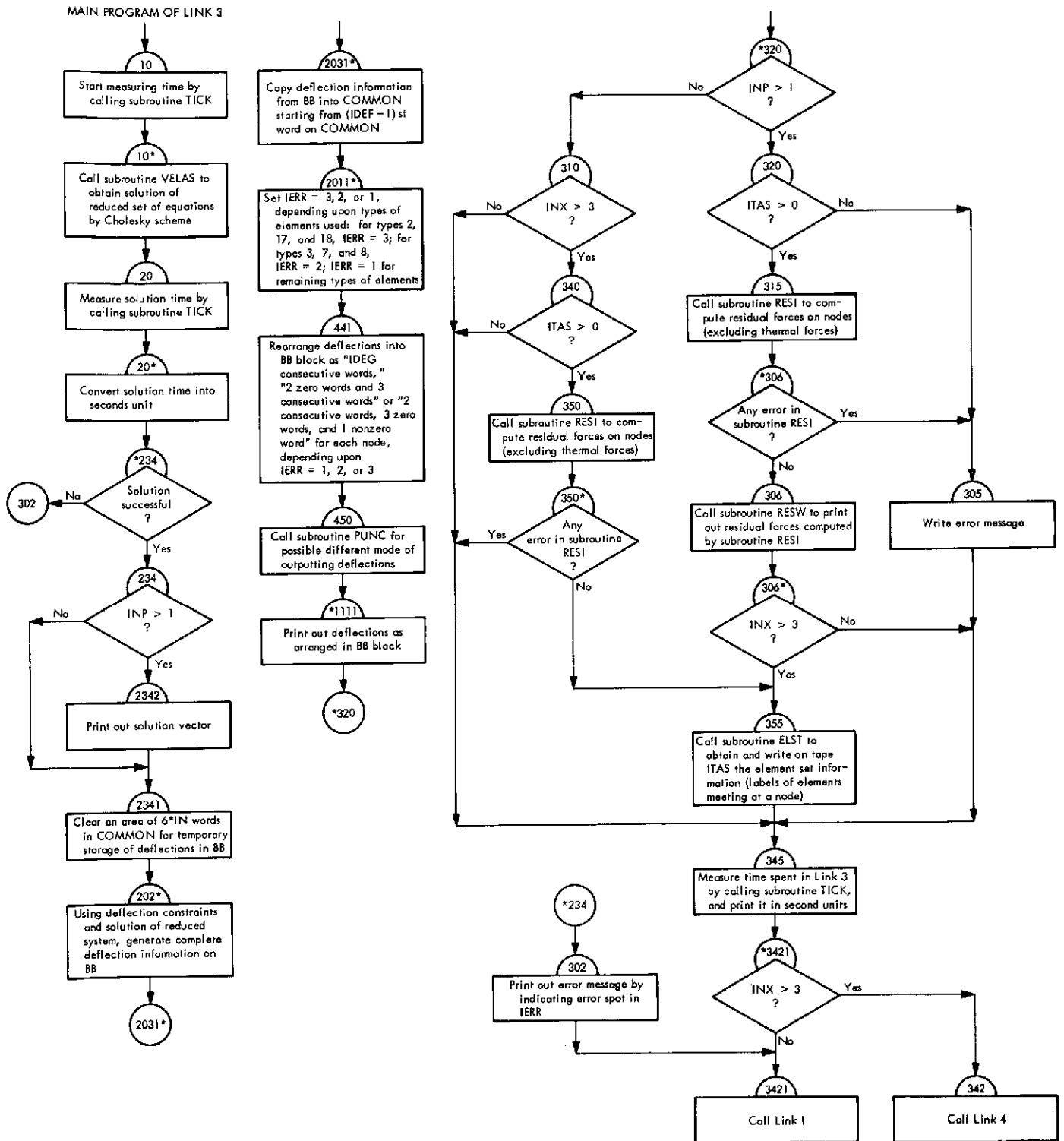


Fig. VI-42. Flowchart of main program of Link 3 (deflection link)

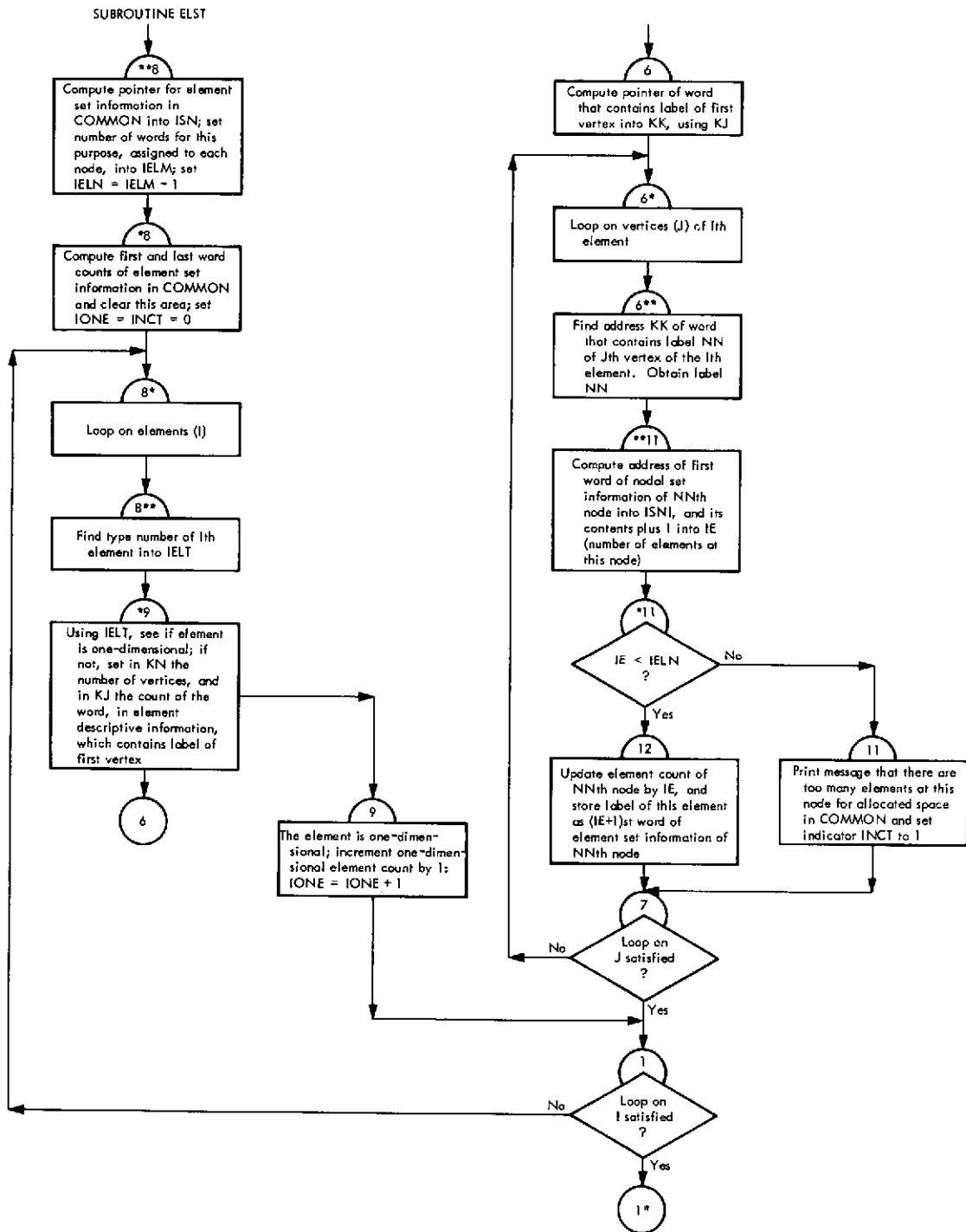


Fig. VI-43. Flowchart of subroutine ELST (Link 3)

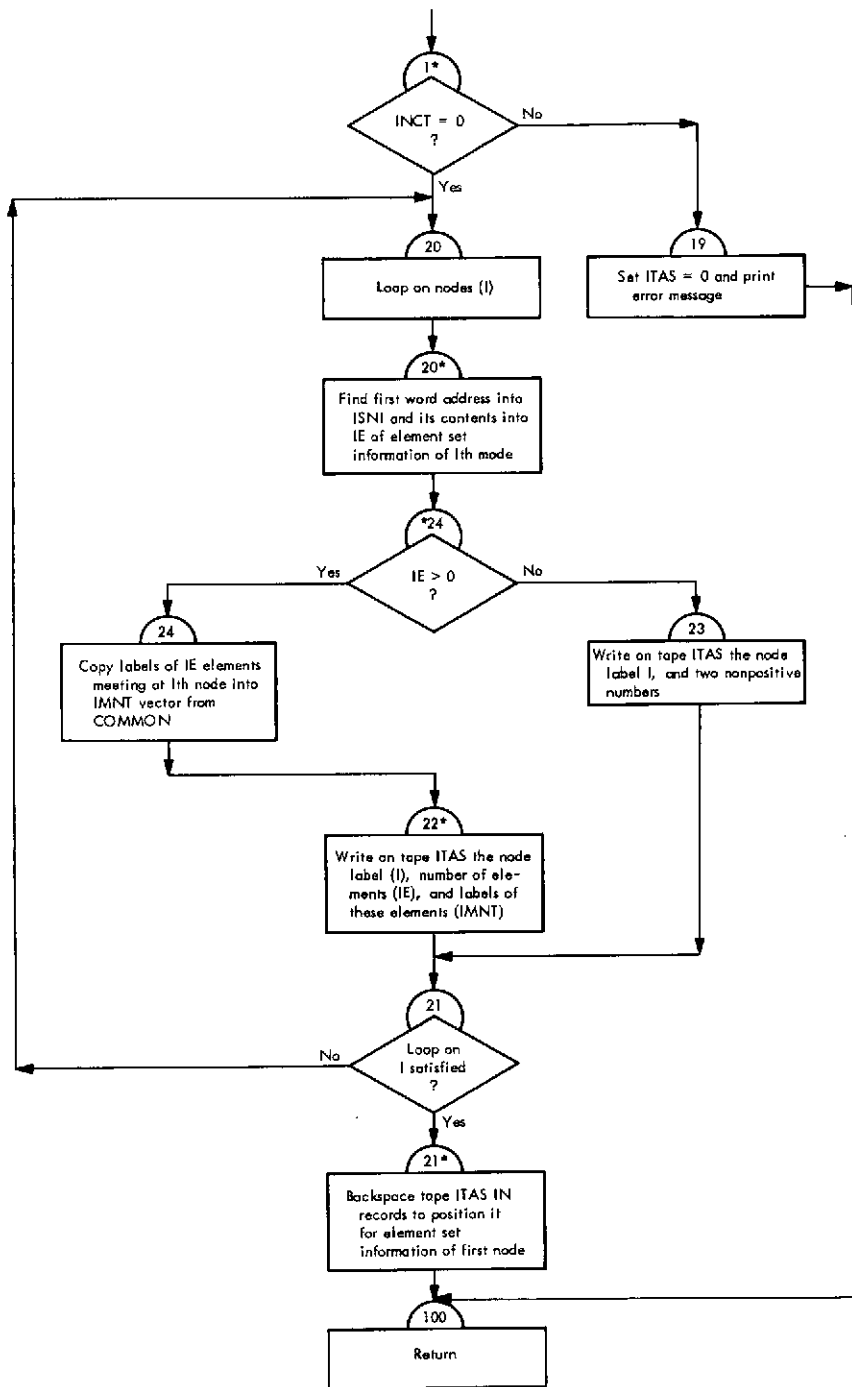


Fig. VI-43 (contd)

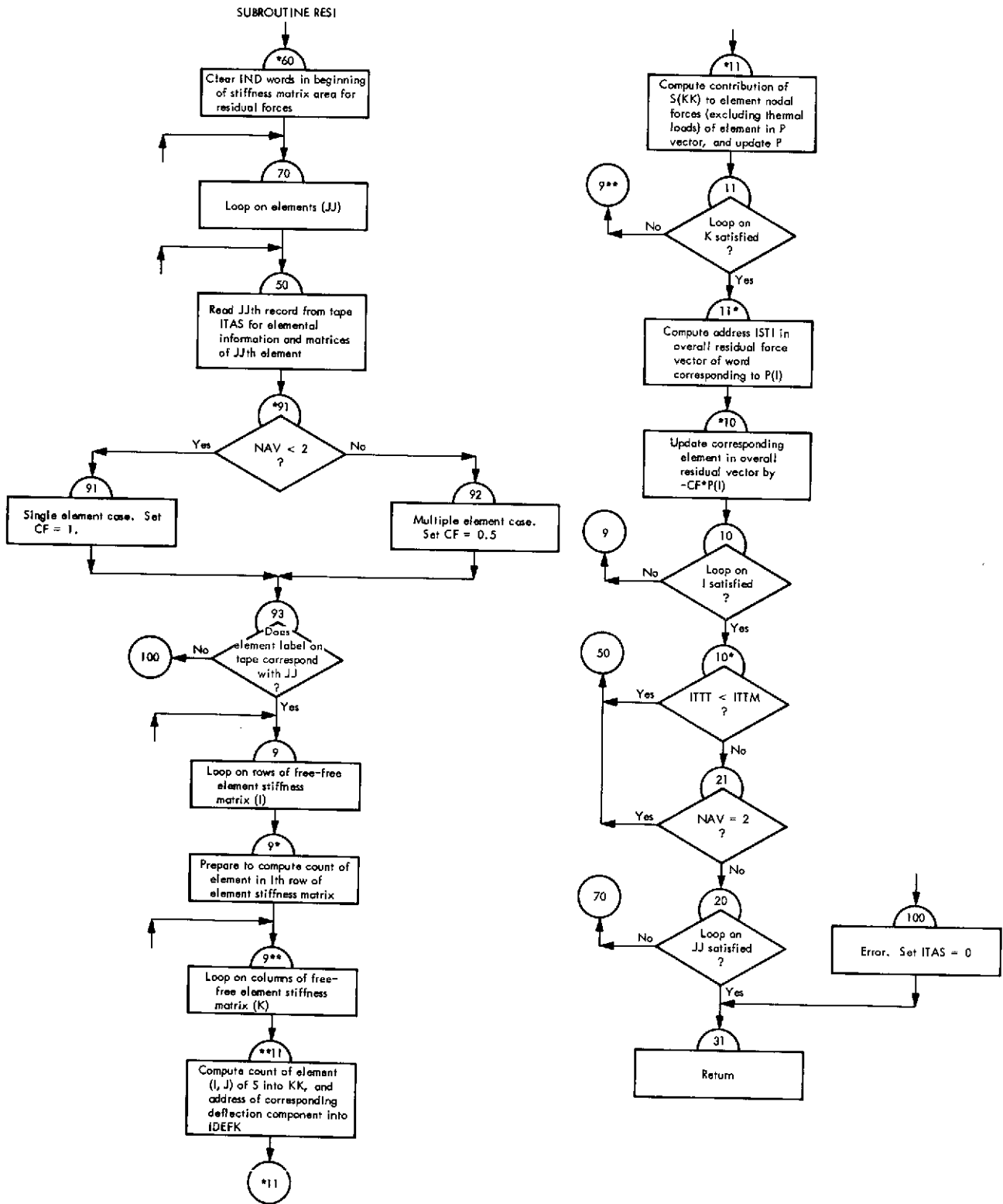


Fig. VI-44. Flowchart of subroutine RESI (Link 3)





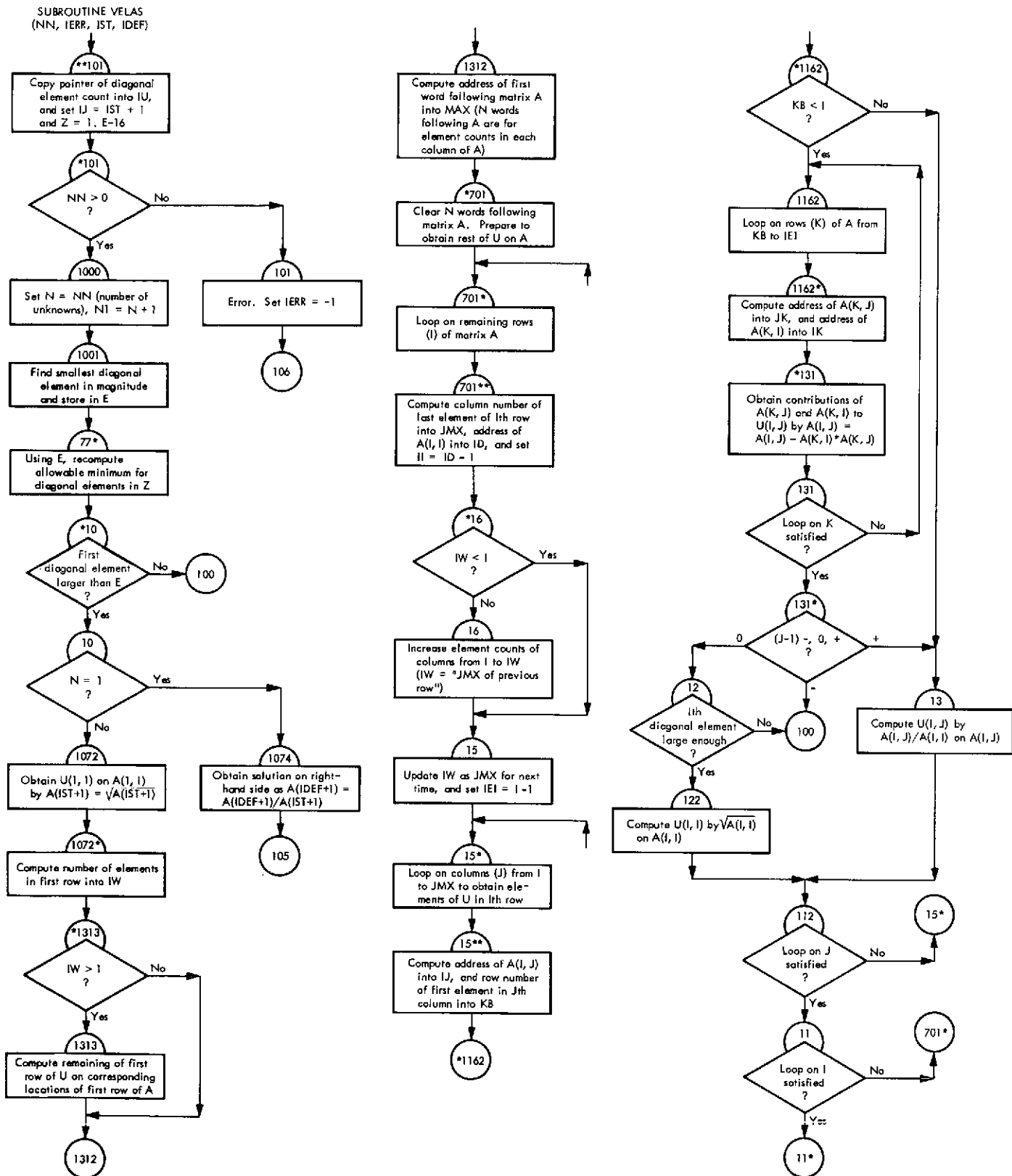


Fig. VI-46. Flowchart of subroutine VELAS (Link 3)

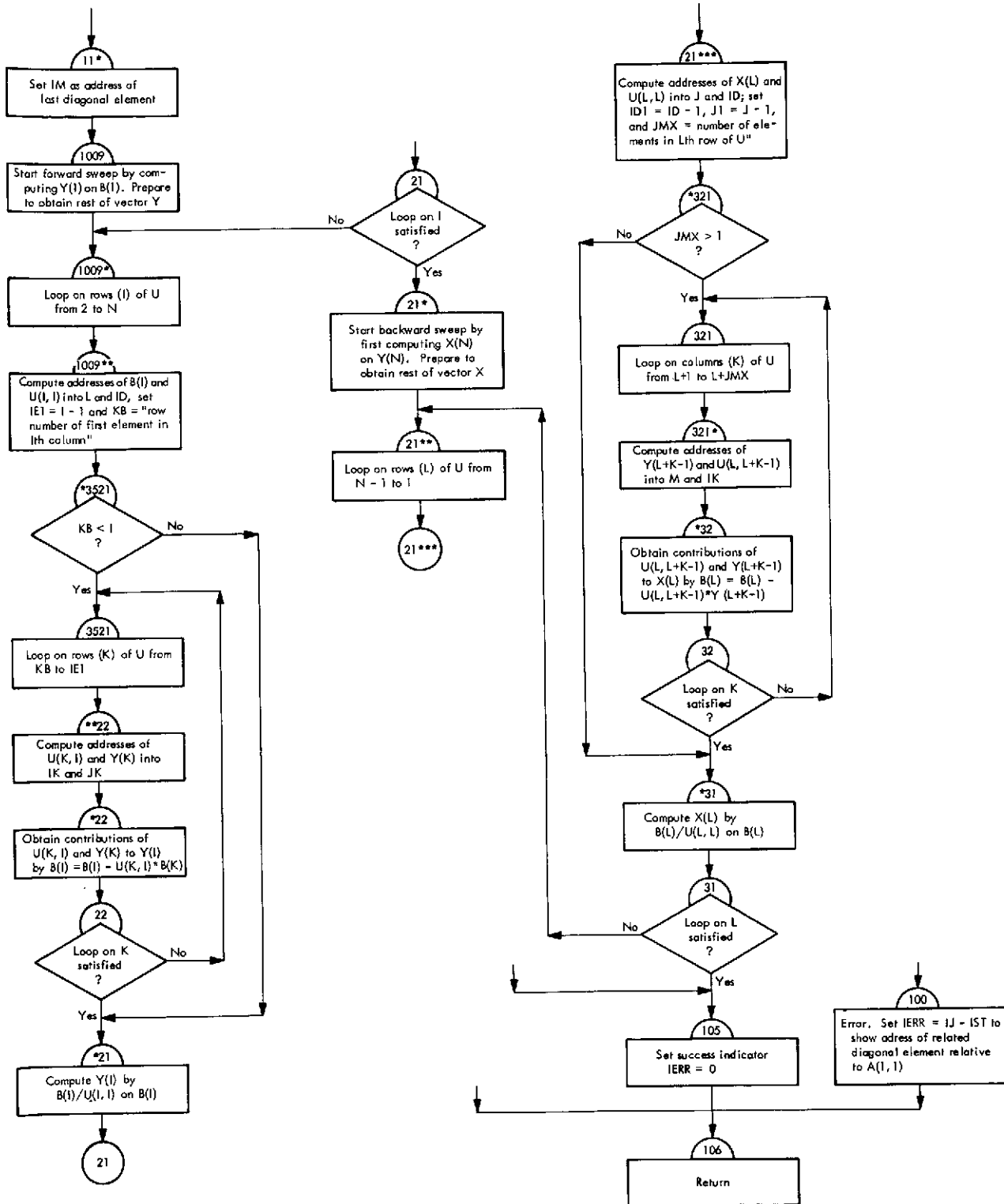


Fig. VI-46 (contd)

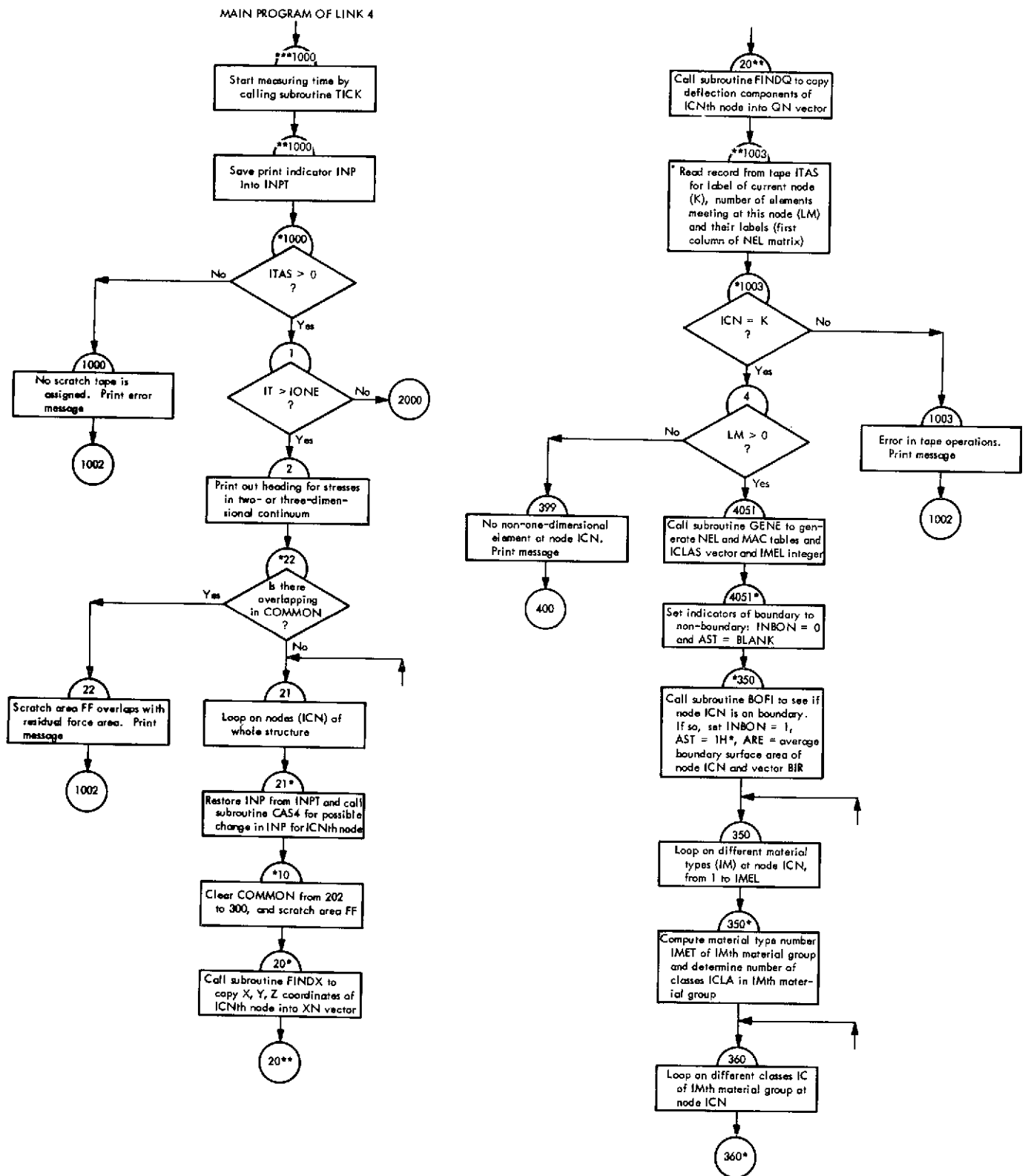


Fig. VI-47. Flowchart of main program of Link 4 (stress link)

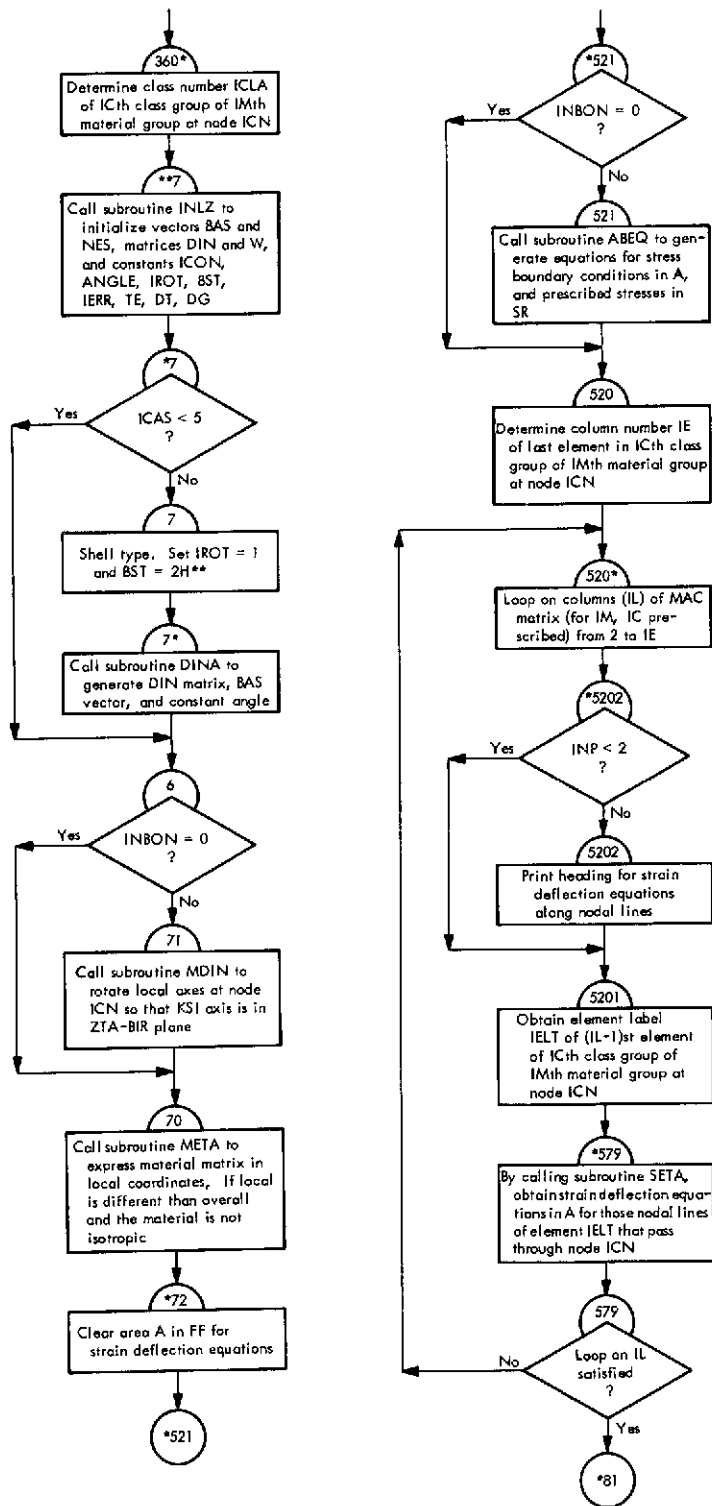


Fig. VI-47 (contd)

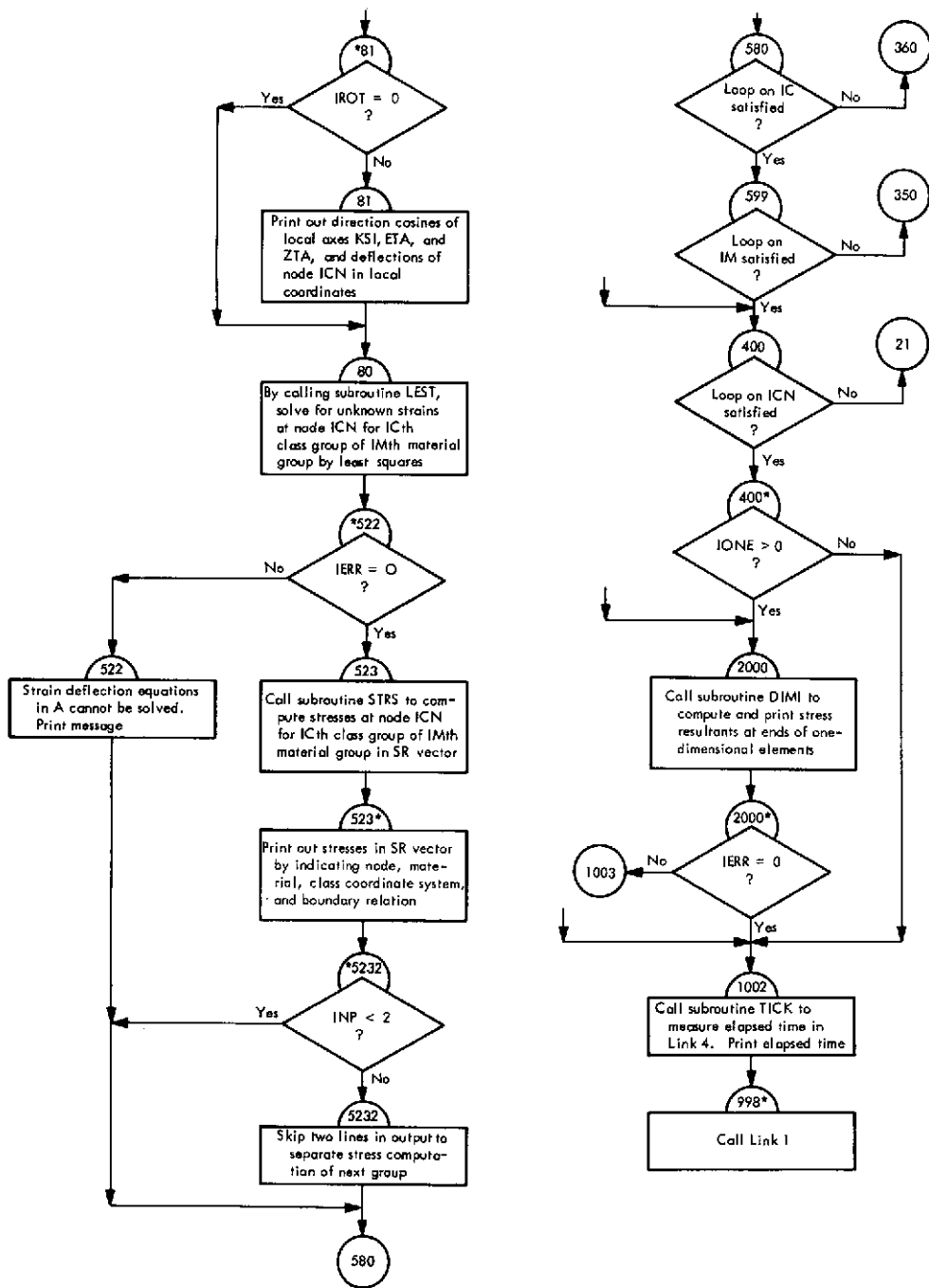


Fig. VI-47 (contd)

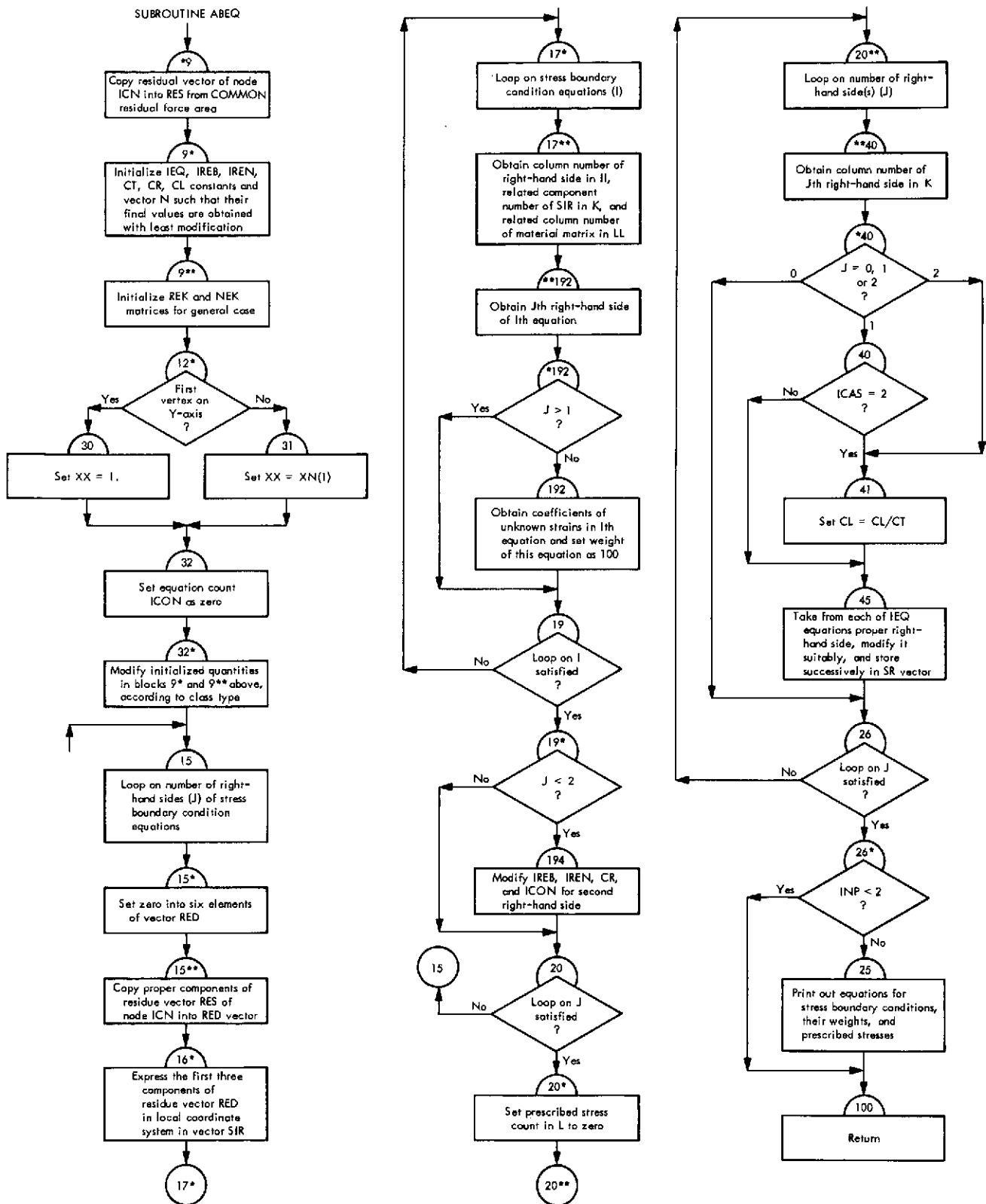


Fig. VI-48. Flowchart of subroutine ABEQ (Link 4)

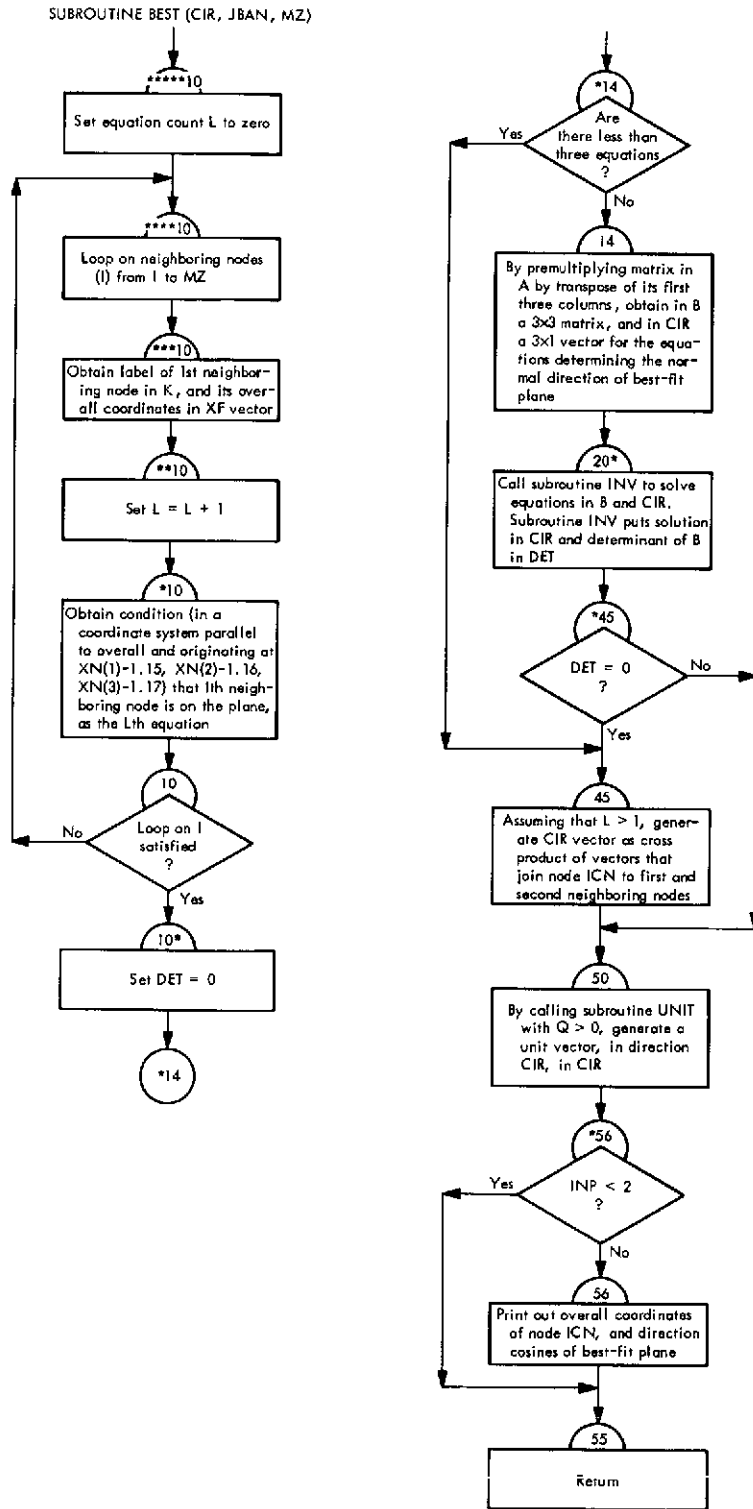


Fig. VI-49. Flowchart of subroutine BEST (Link 4)





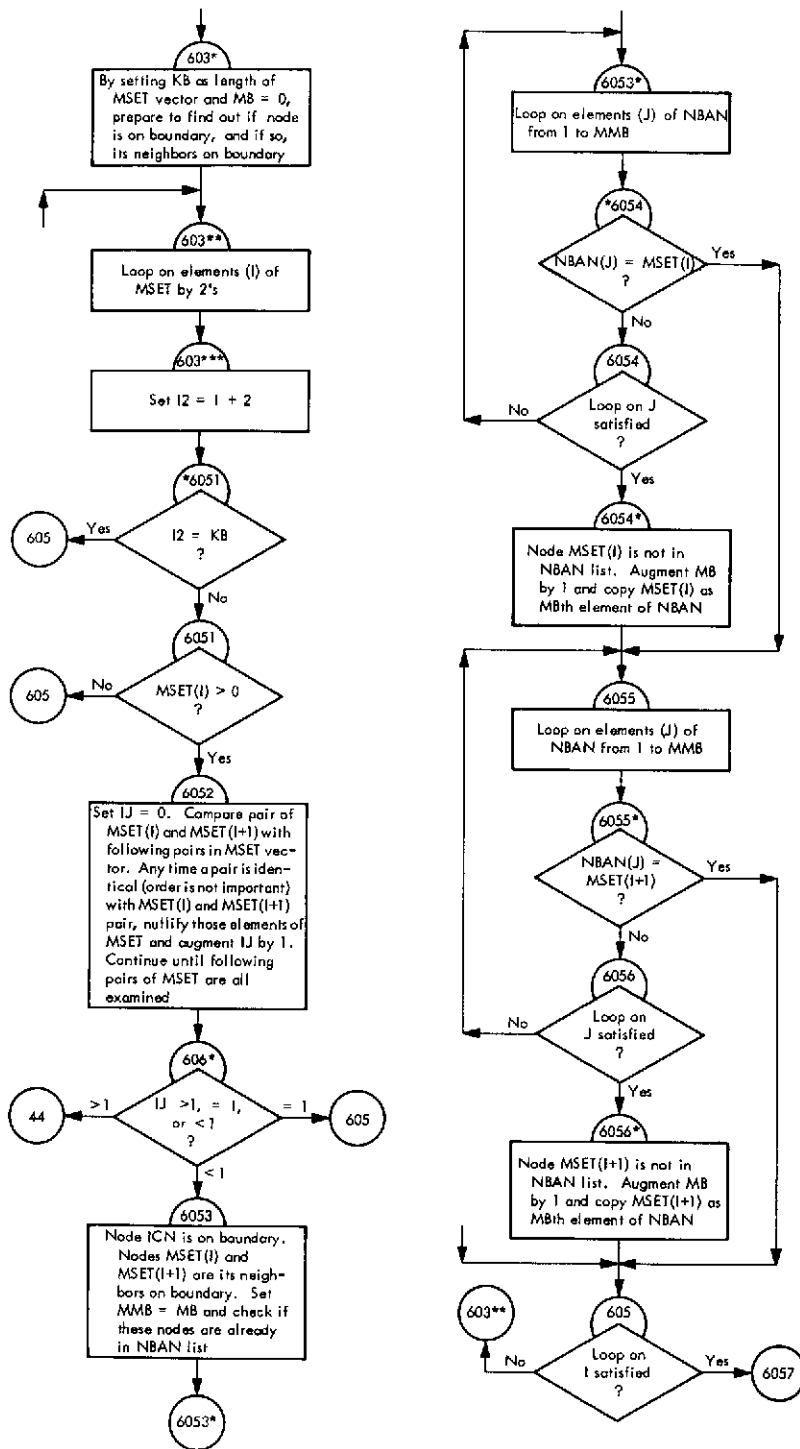


Fig. Vi-50 (conid)

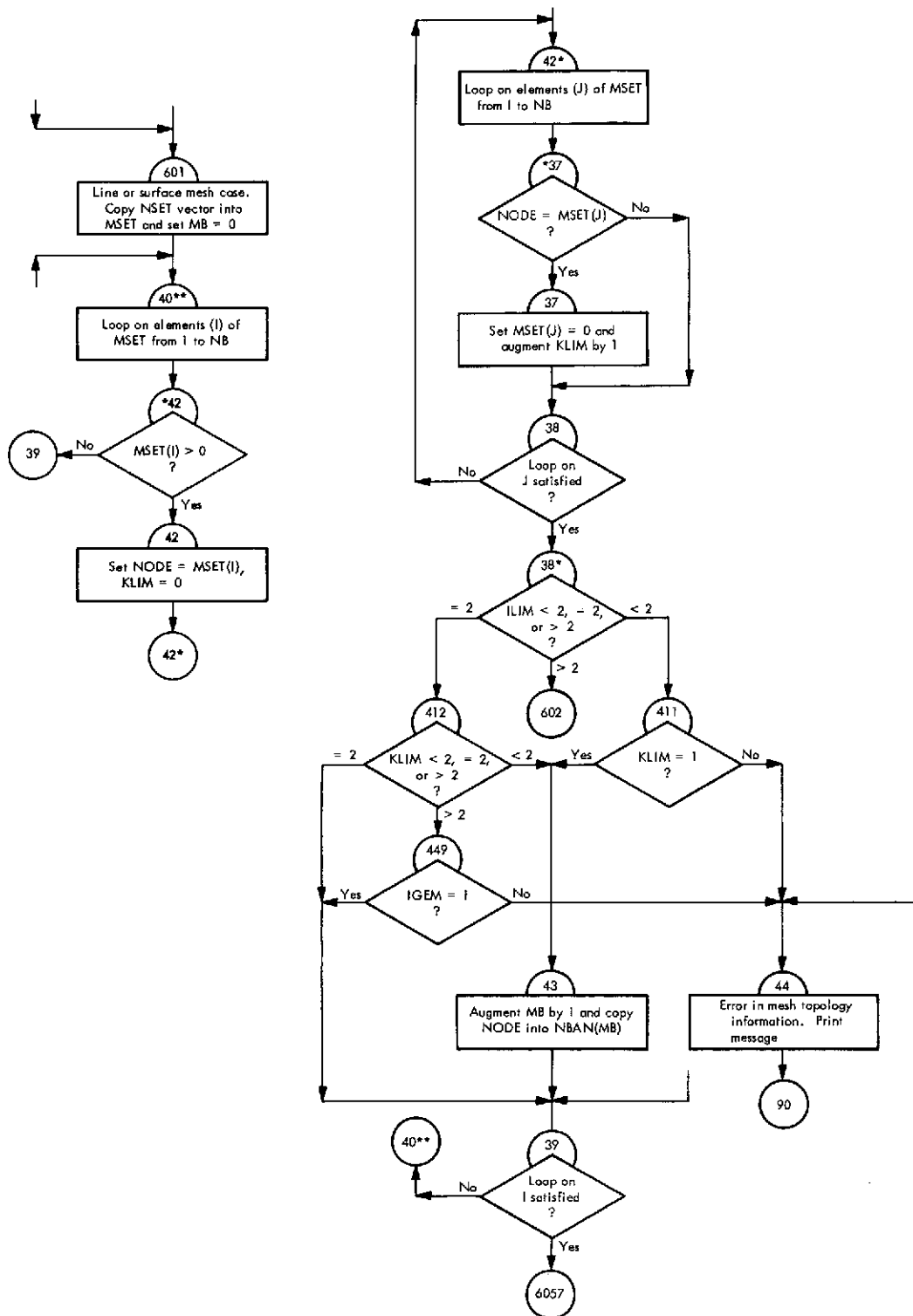


Fig. VI-50 (contd)

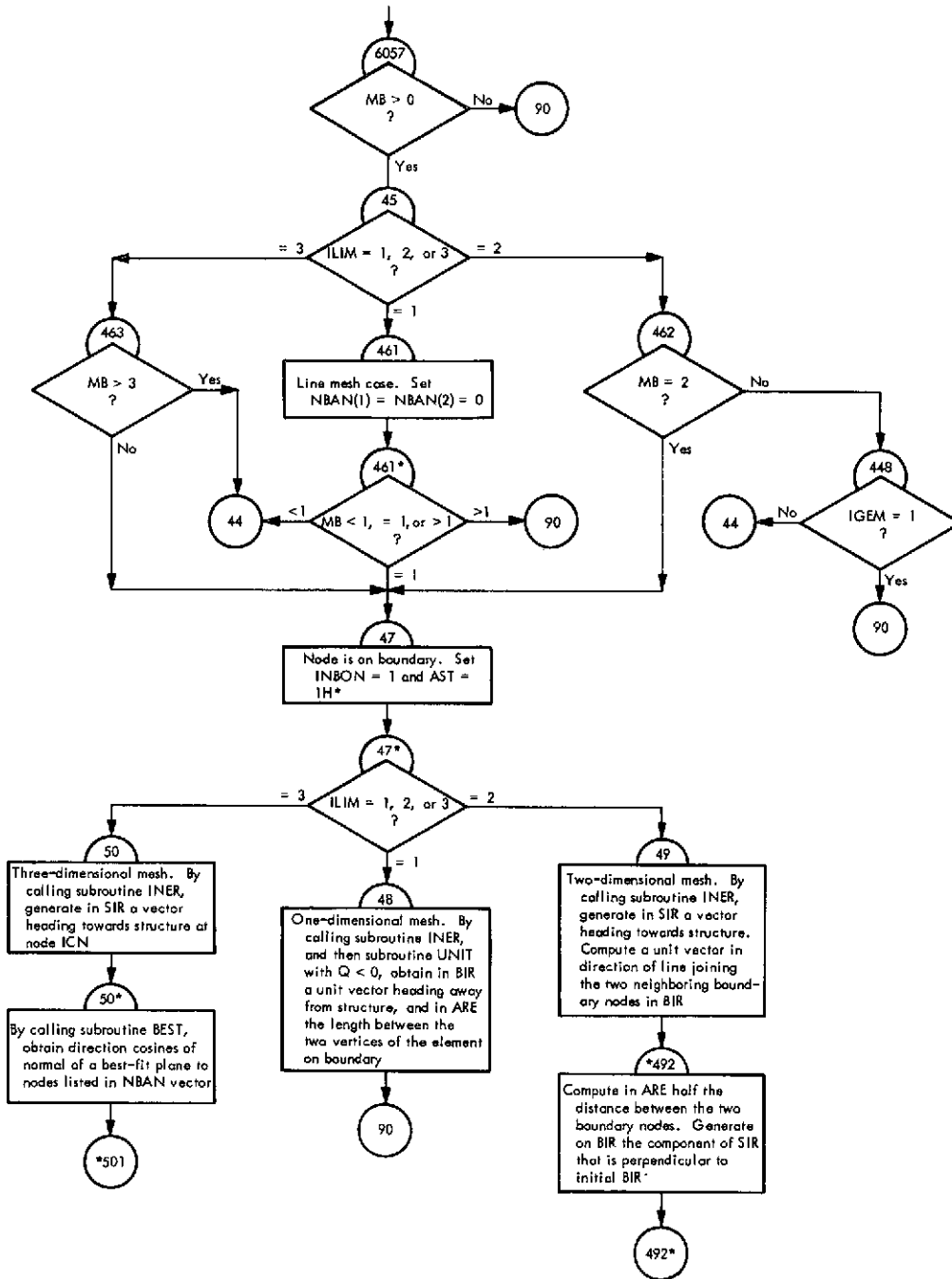


Fig. VI-50 (contd)

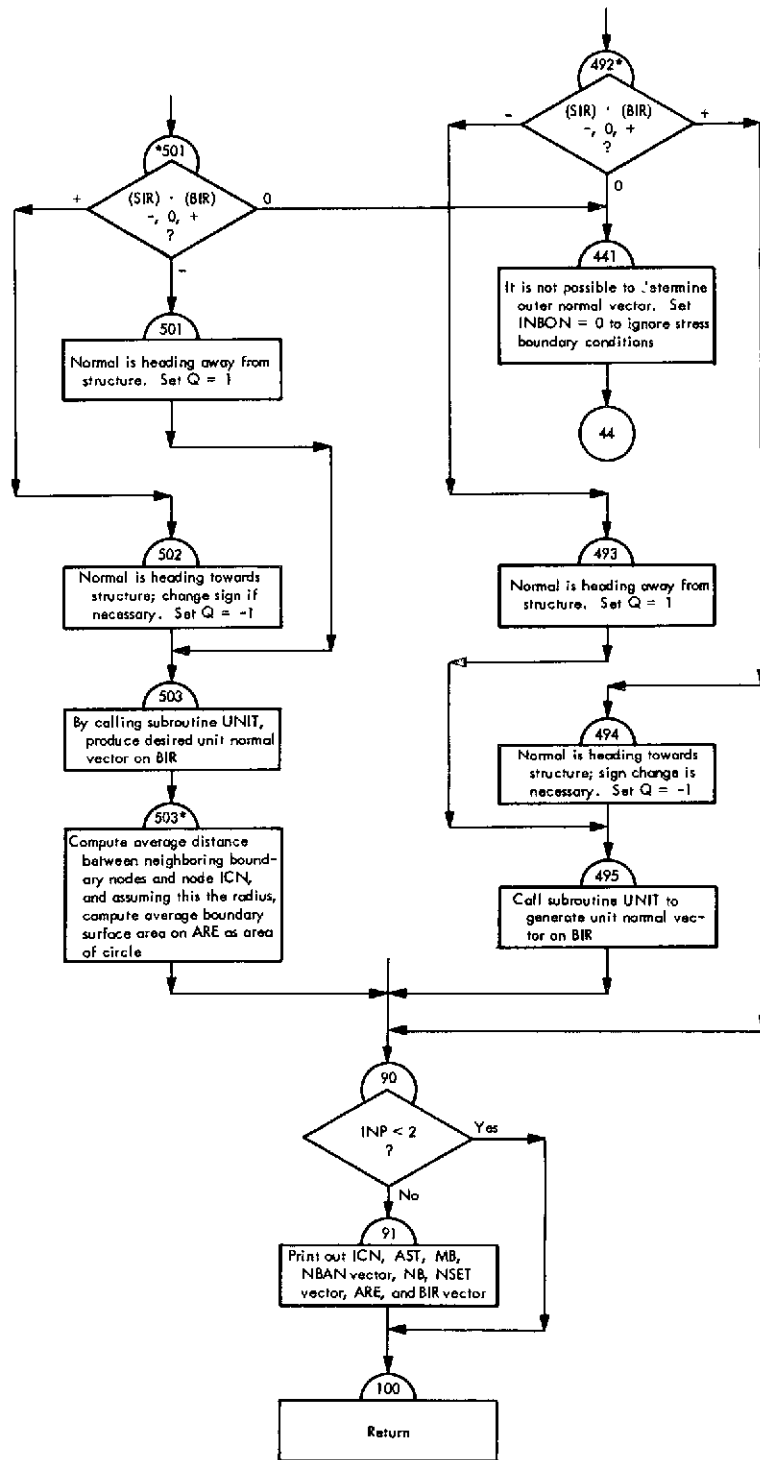


Fig. VI-50 (contd)

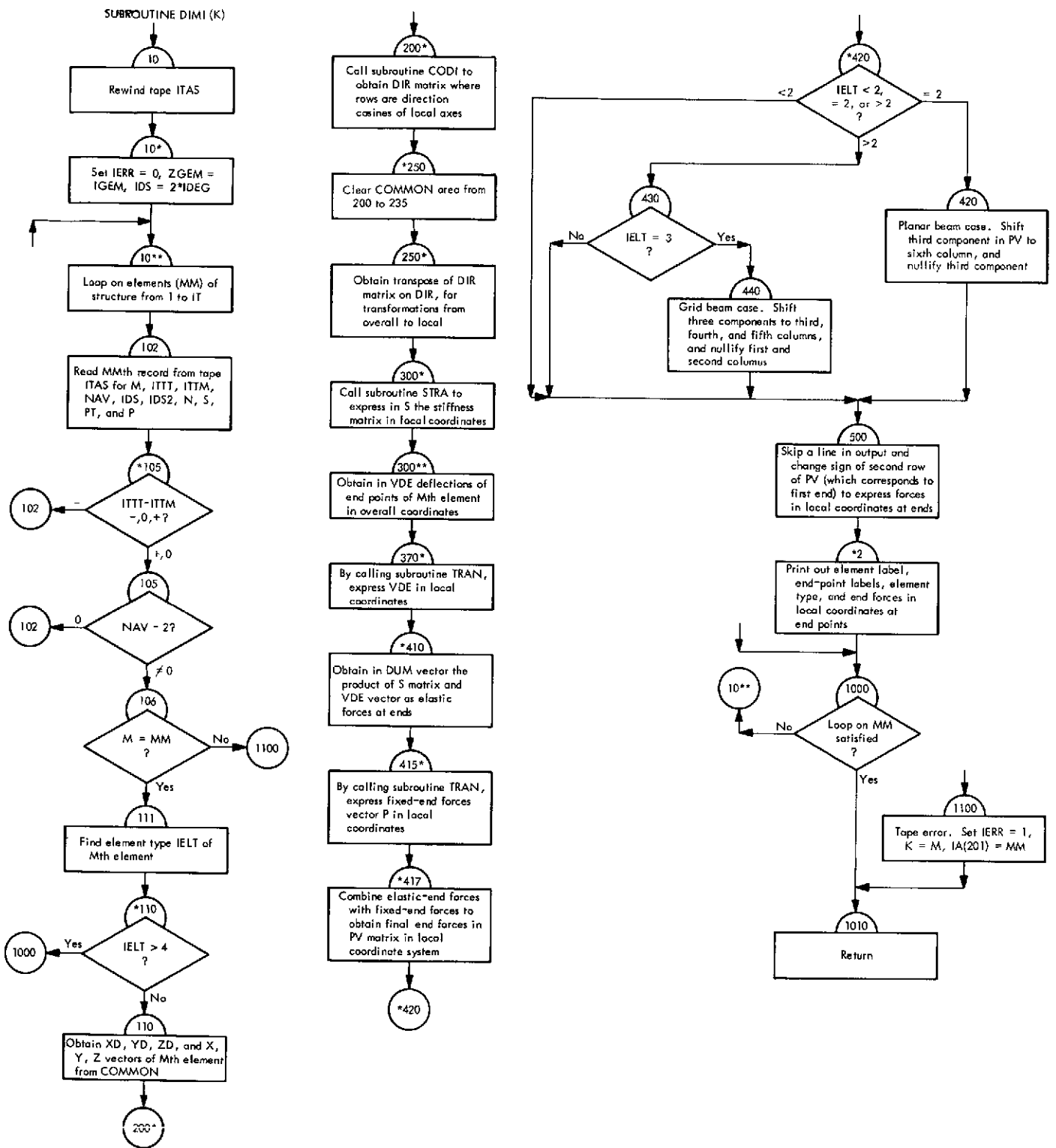


Fig. VI-51. Flowchart of subroutine DIMI (Link 4)

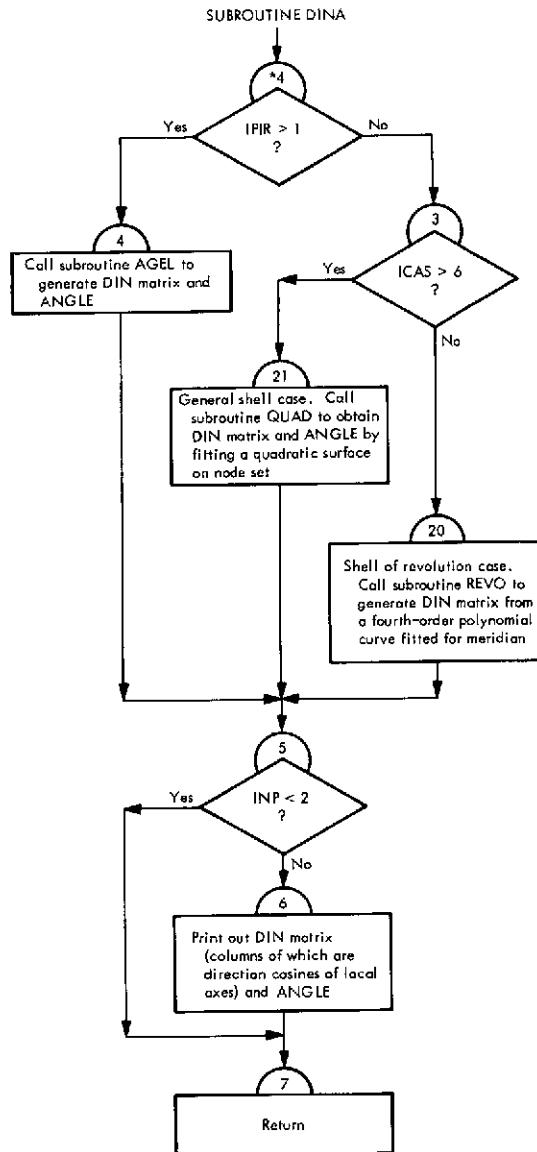


Fig. VI-52. Flowchart of subroutine DINA (Link 4)

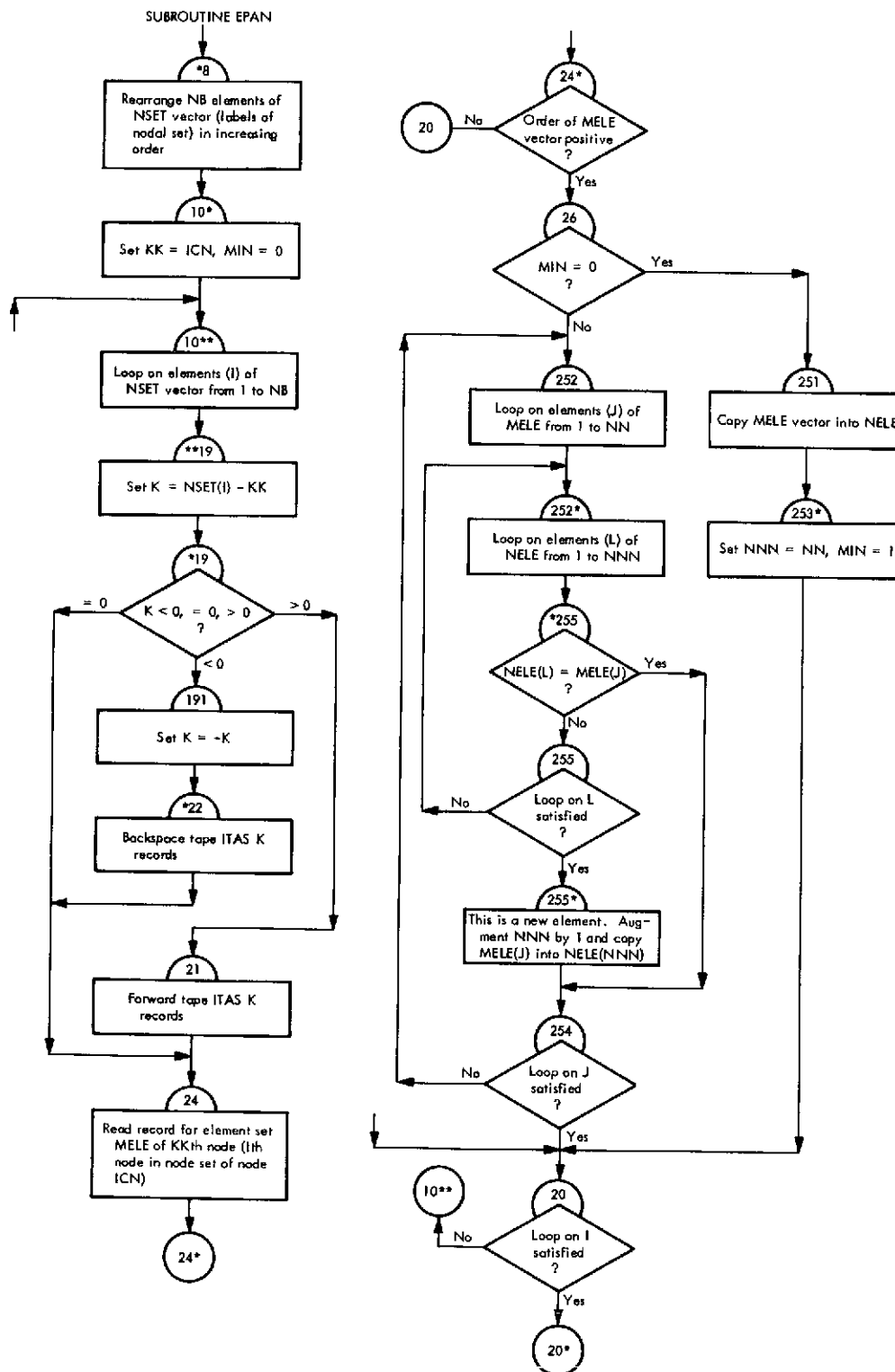


Fig. VI-53. Flowchart of subroutine EPAN (Link 4)



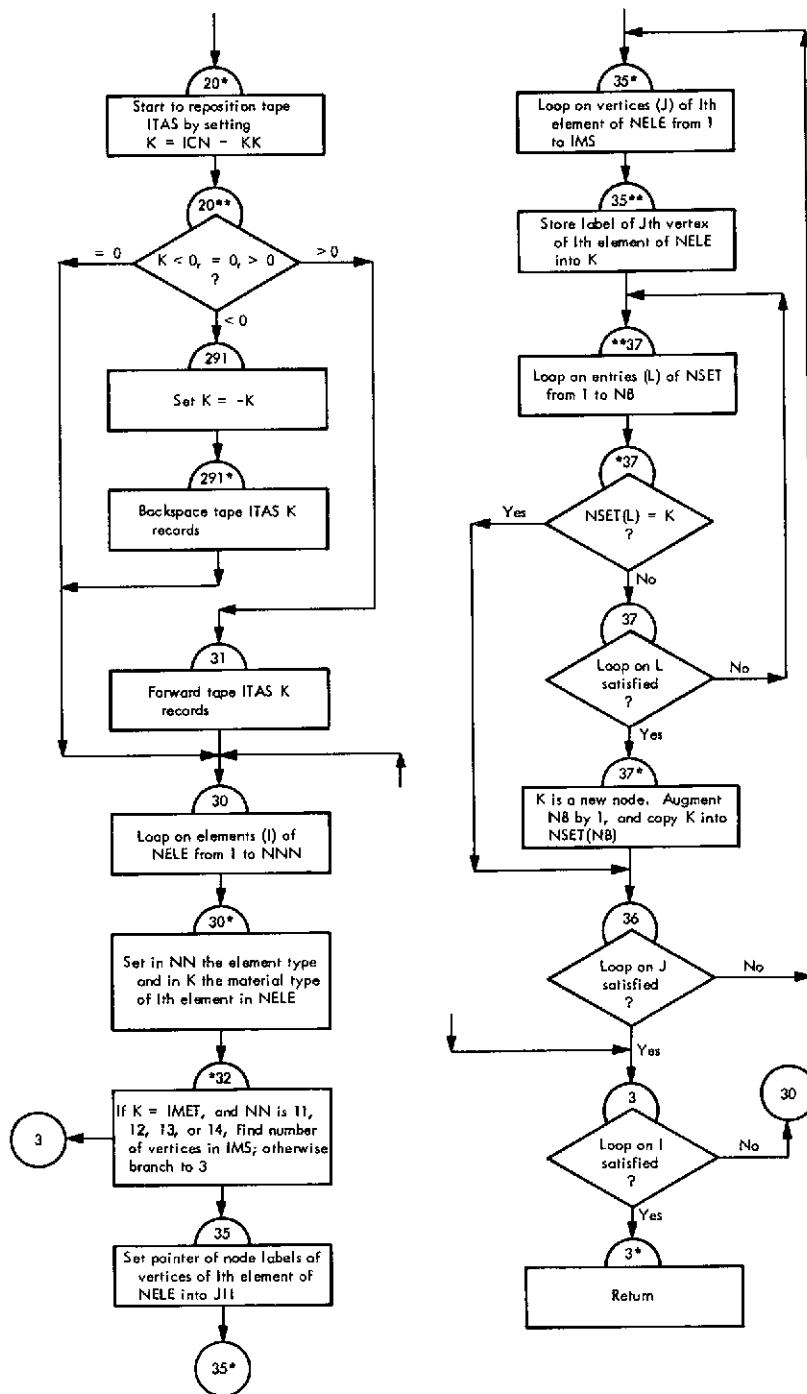


Fig. VI-53 (contd)

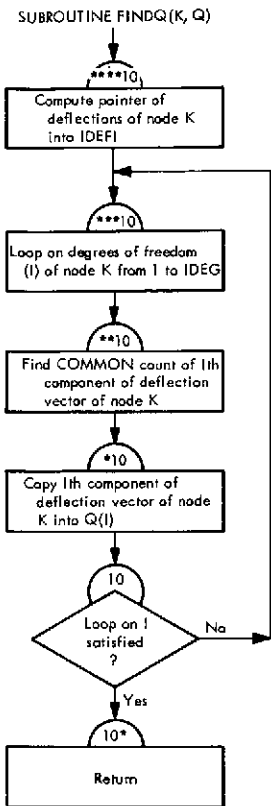


Fig. VI-54. Flowchart of subroutine FINDQ (Link 4)

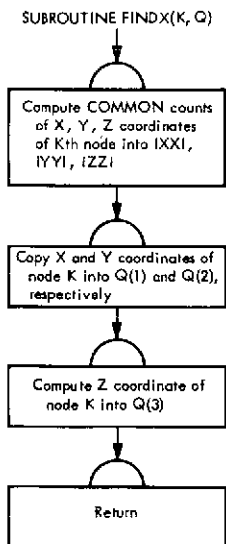


Fig. VI-55. Flowchart of subroutine FINDX (Link 4)

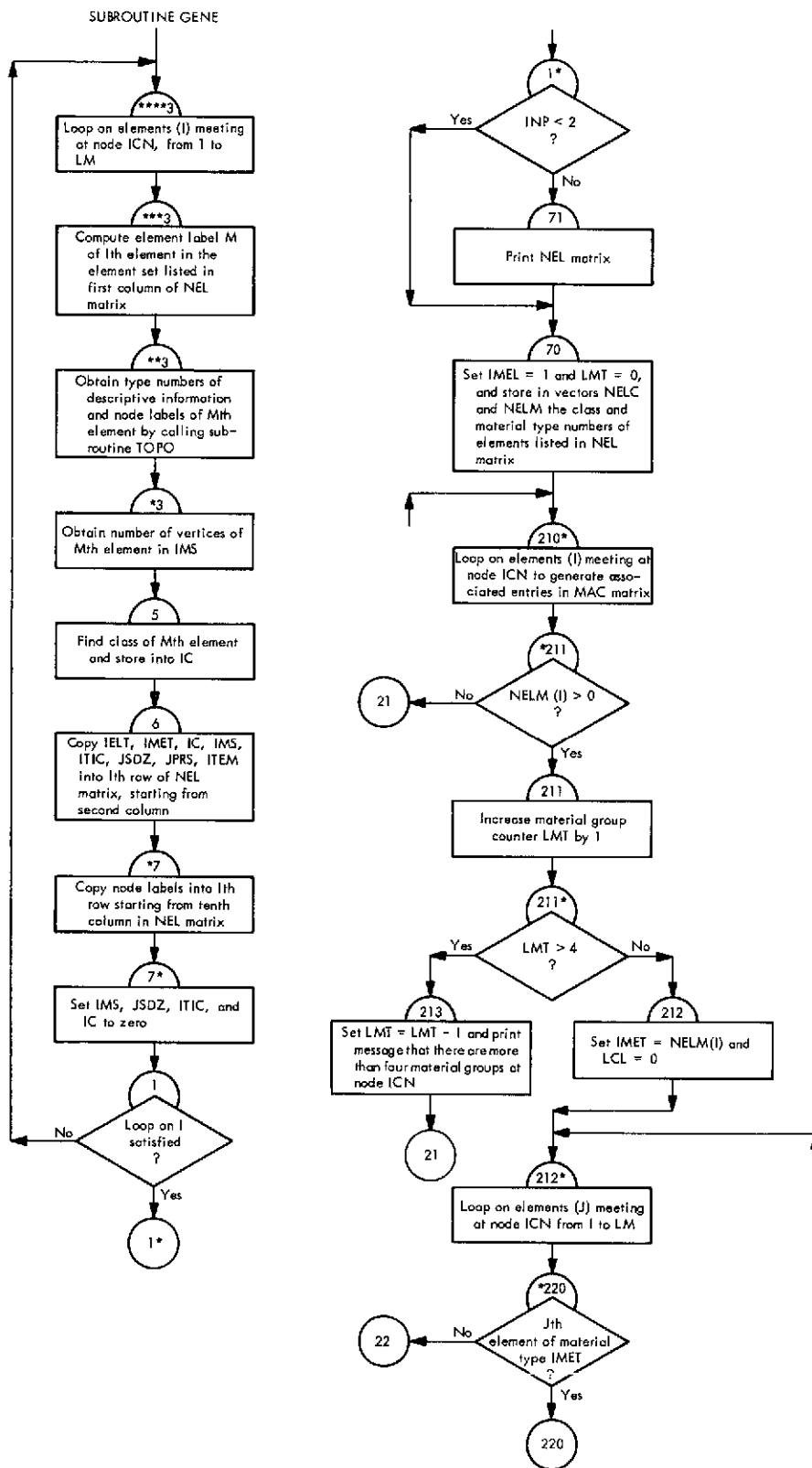


Fig. VI-56. Flowchart of subroutine GENE (Link 4)



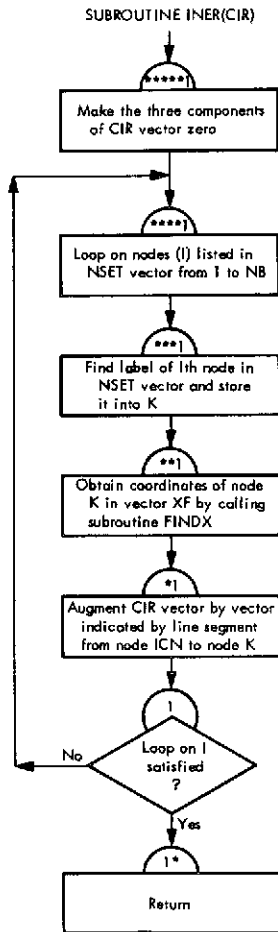


Fig. VI-57. Flowchart of subroutine INER (Link 4)

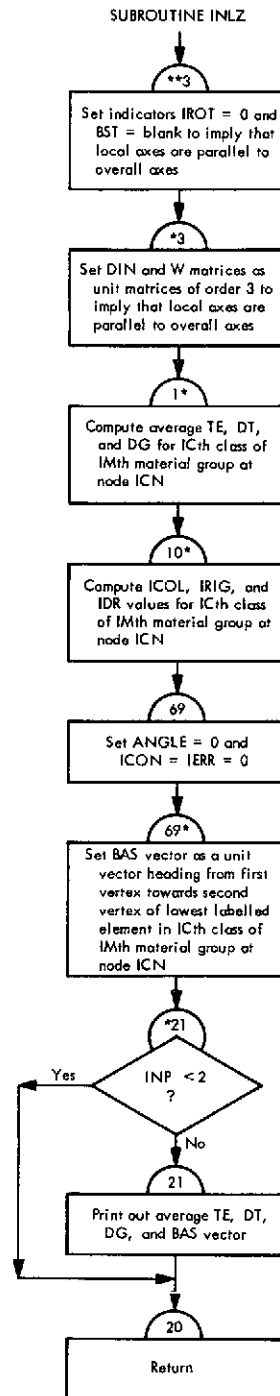


Fig. VI-58. Flowchart of subroutine INLZ (Link 4)

SUBROUTINE INV (A, N, B, M, DETERM)

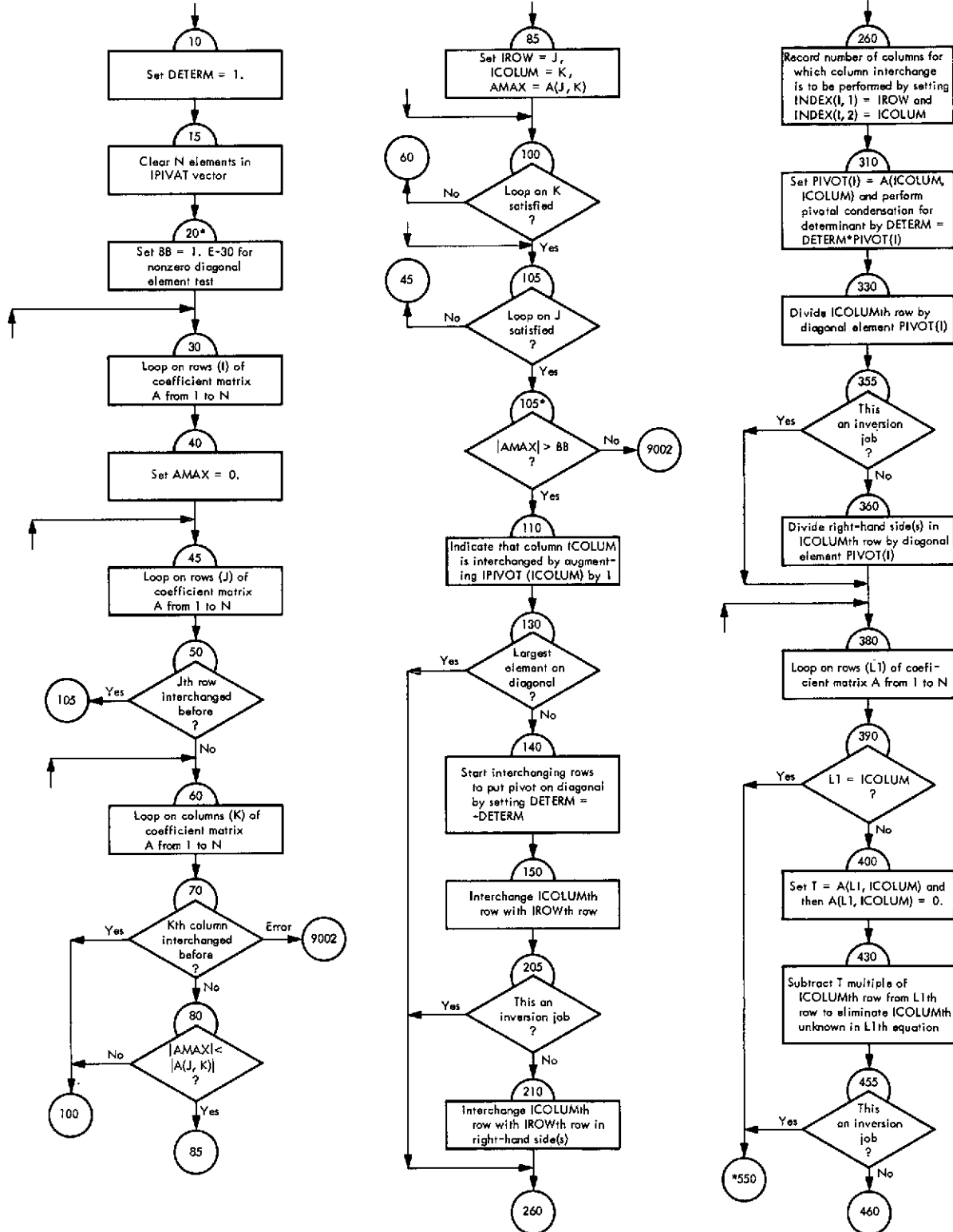


Fig. VI-59. Flowchart of subroutine INV (Link 4)

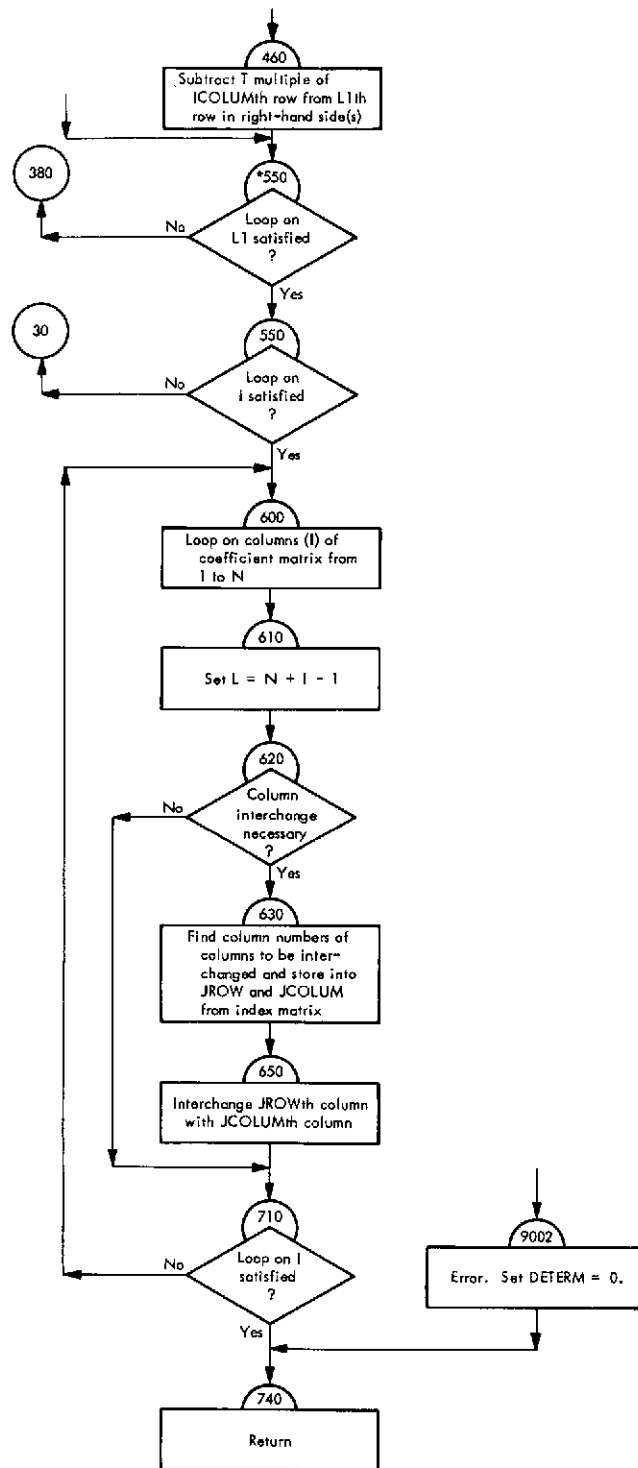


Fig. VI-59 (contd)

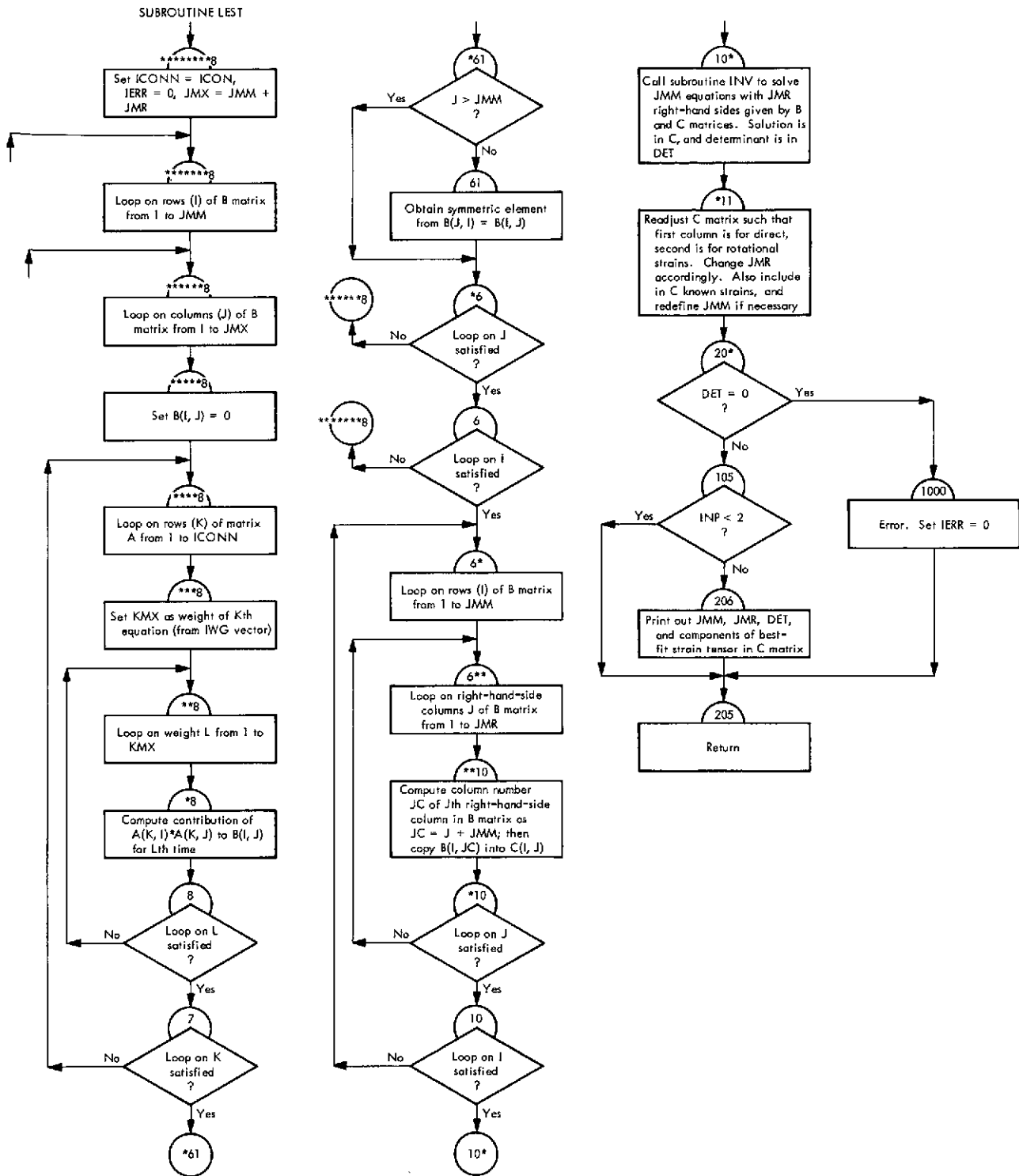


Fig. VI-60. Flowchart of subroutine LEST (Link 4)

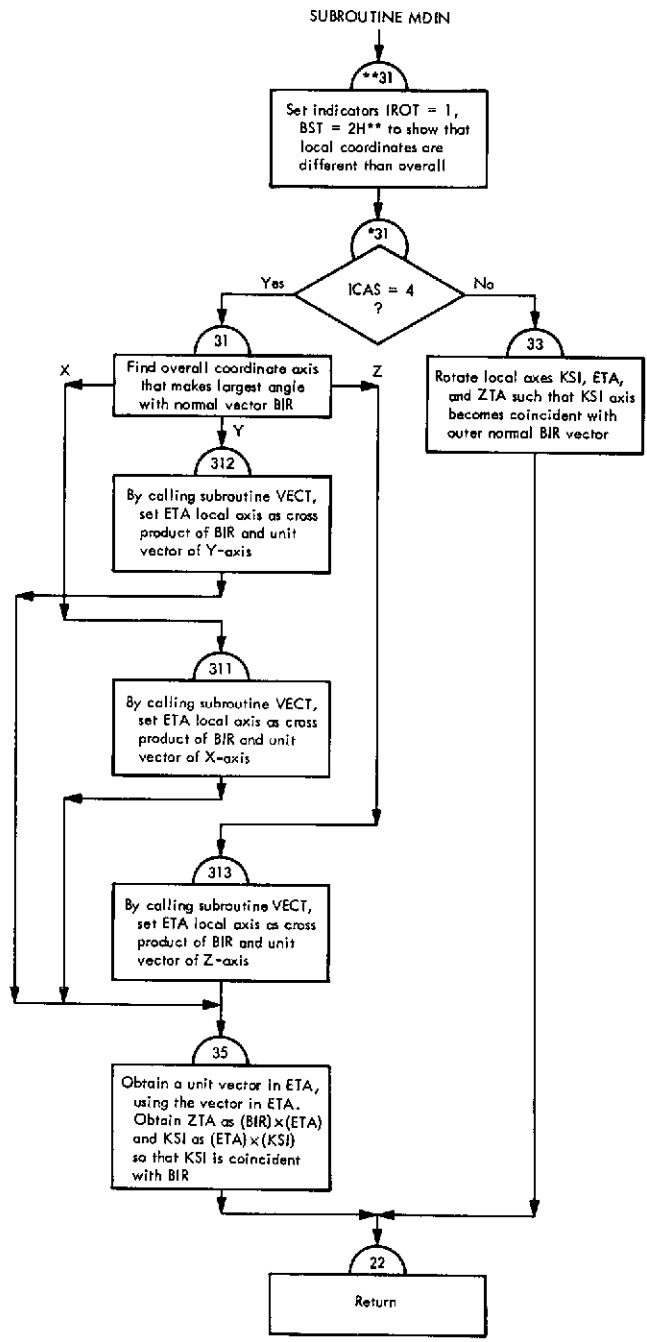


Fig. VI-61. Flowchart of subroutine MDIN (Link 4)



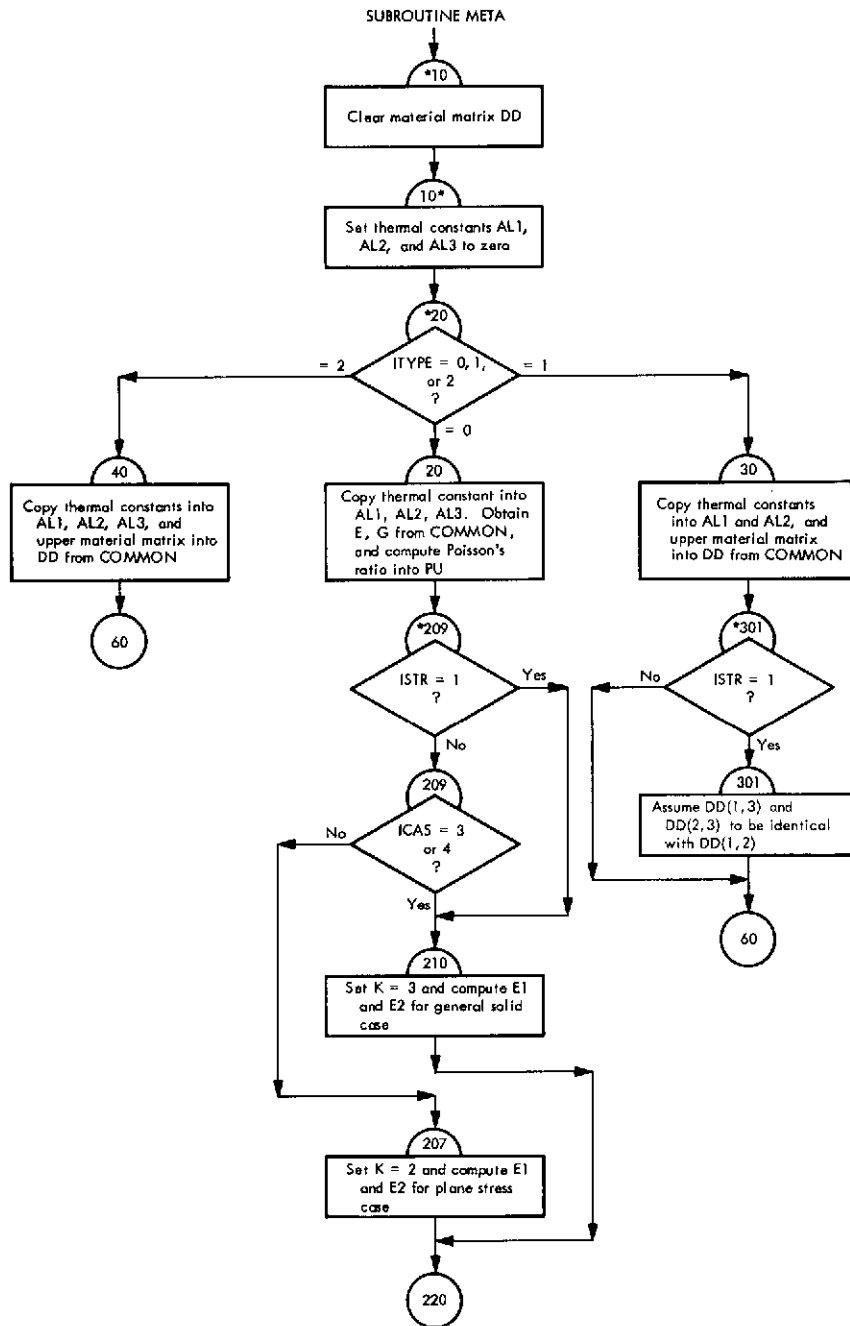


Fig. VI-62. Flowchart of subroutine META (Link 4)

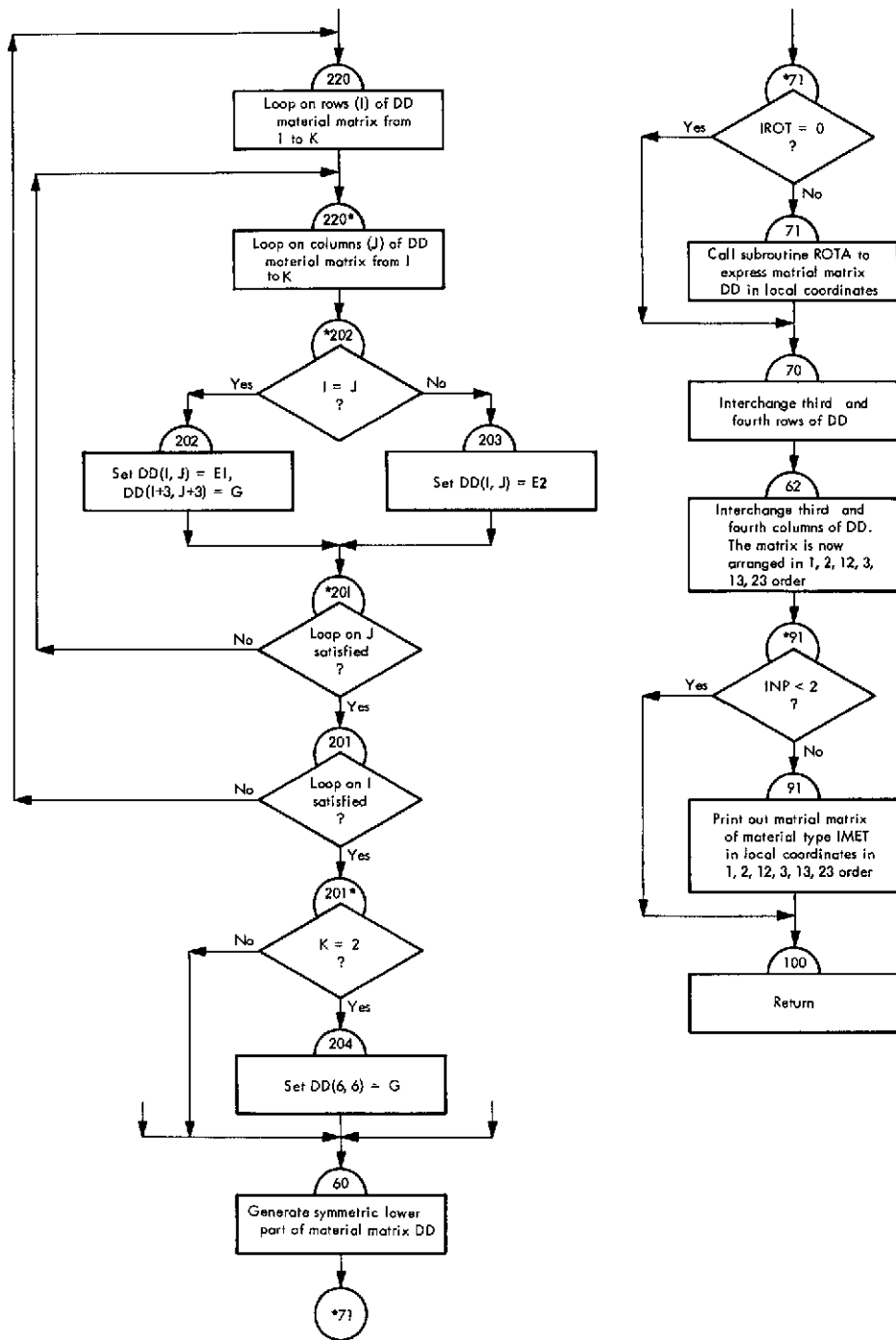


Fig. VI-62 (contd)

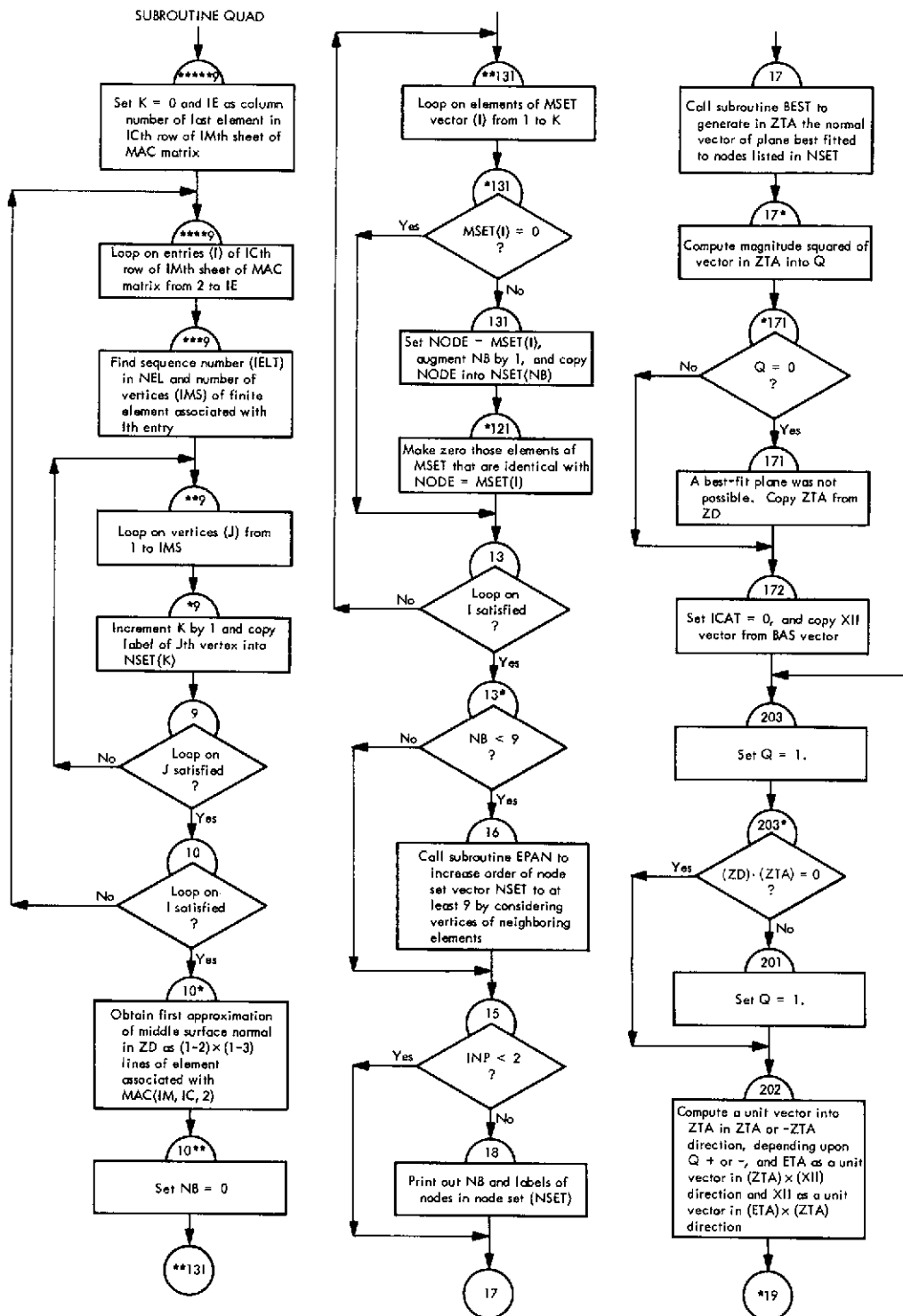


Fig. VI-63. Flowchart of subroutine QUAD (Link 4)

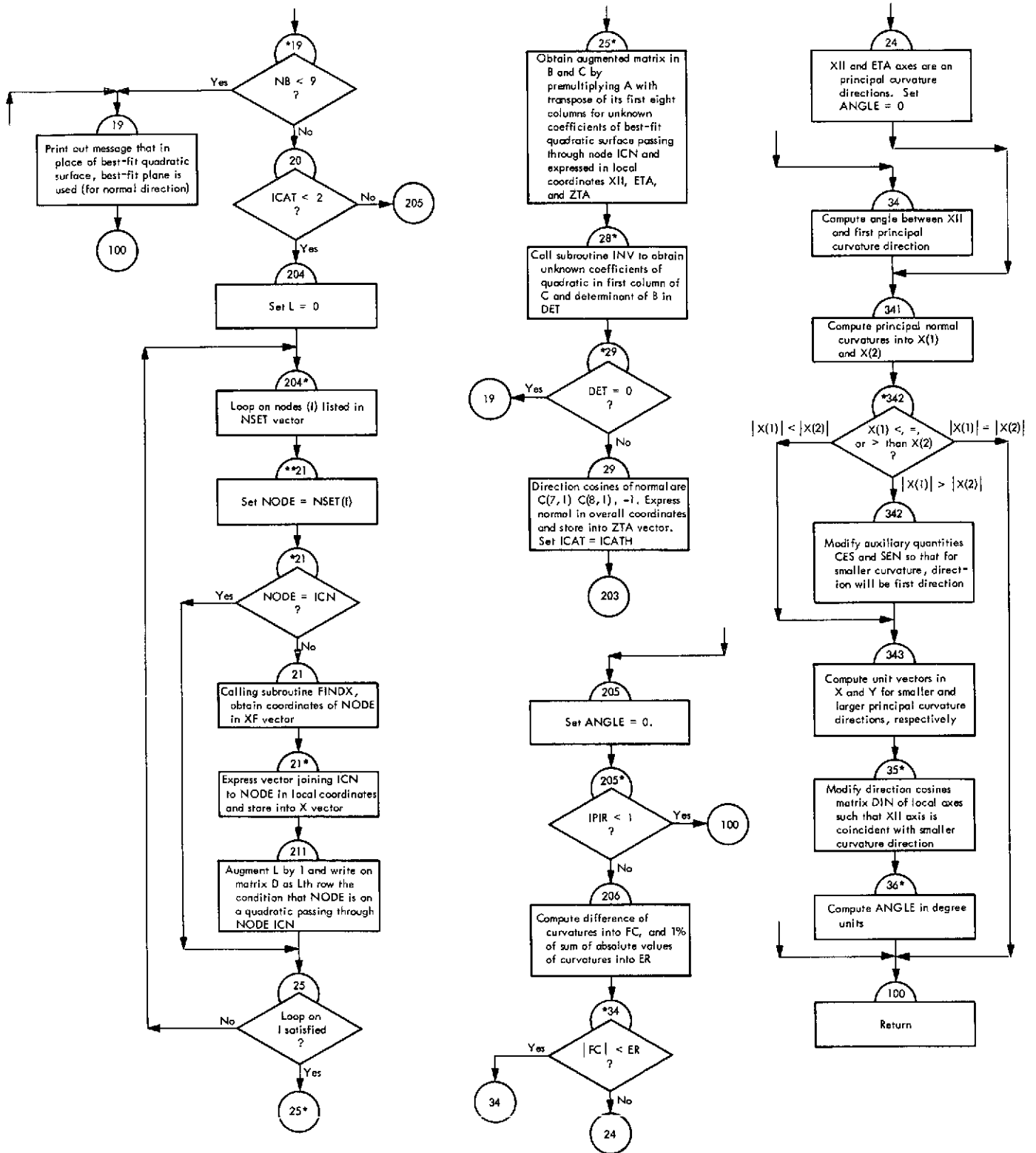


Fig. VI-63 (contd)

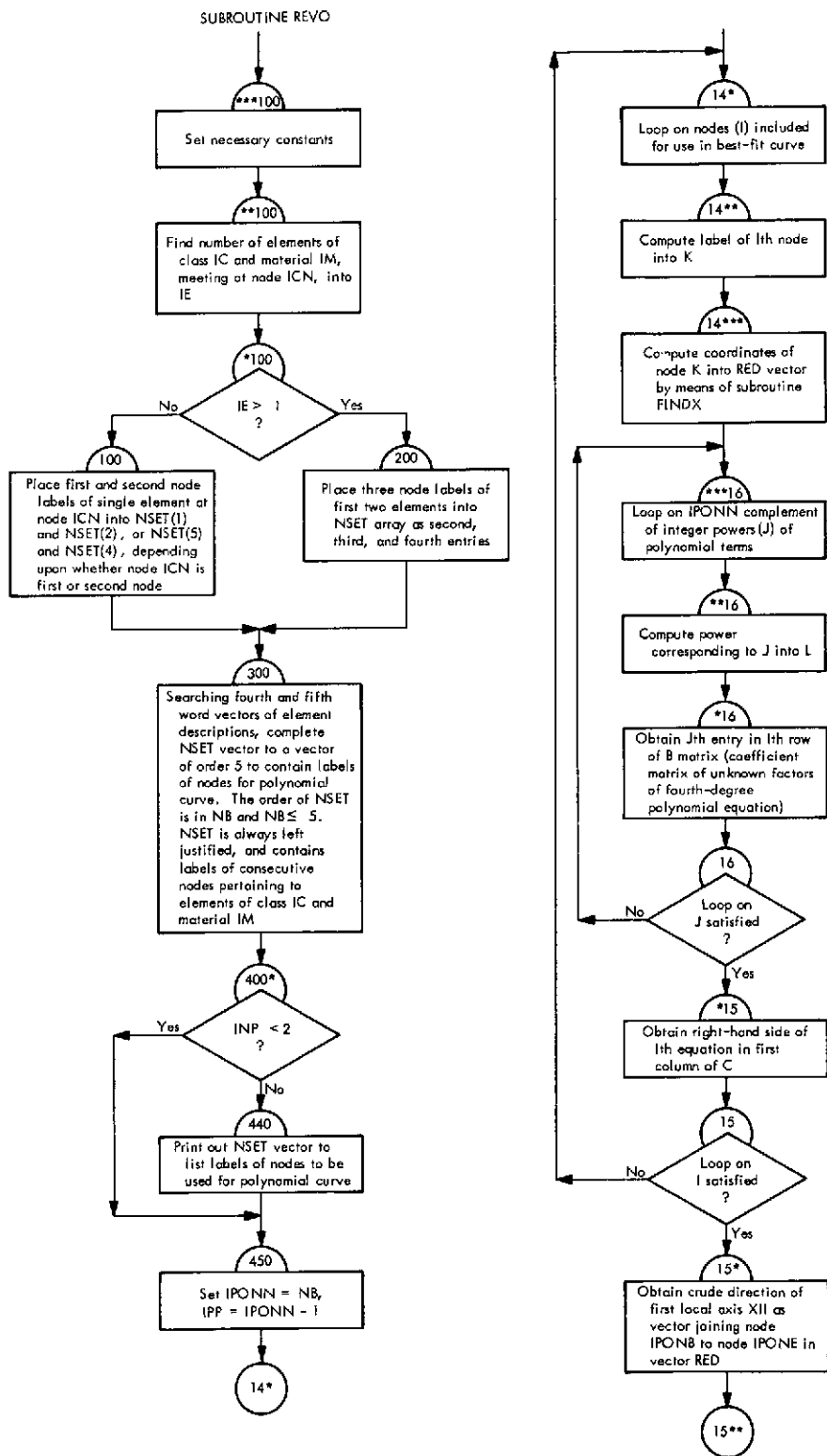


Fig. VI-64. Flowchart of subroutine REVO (Link 4)

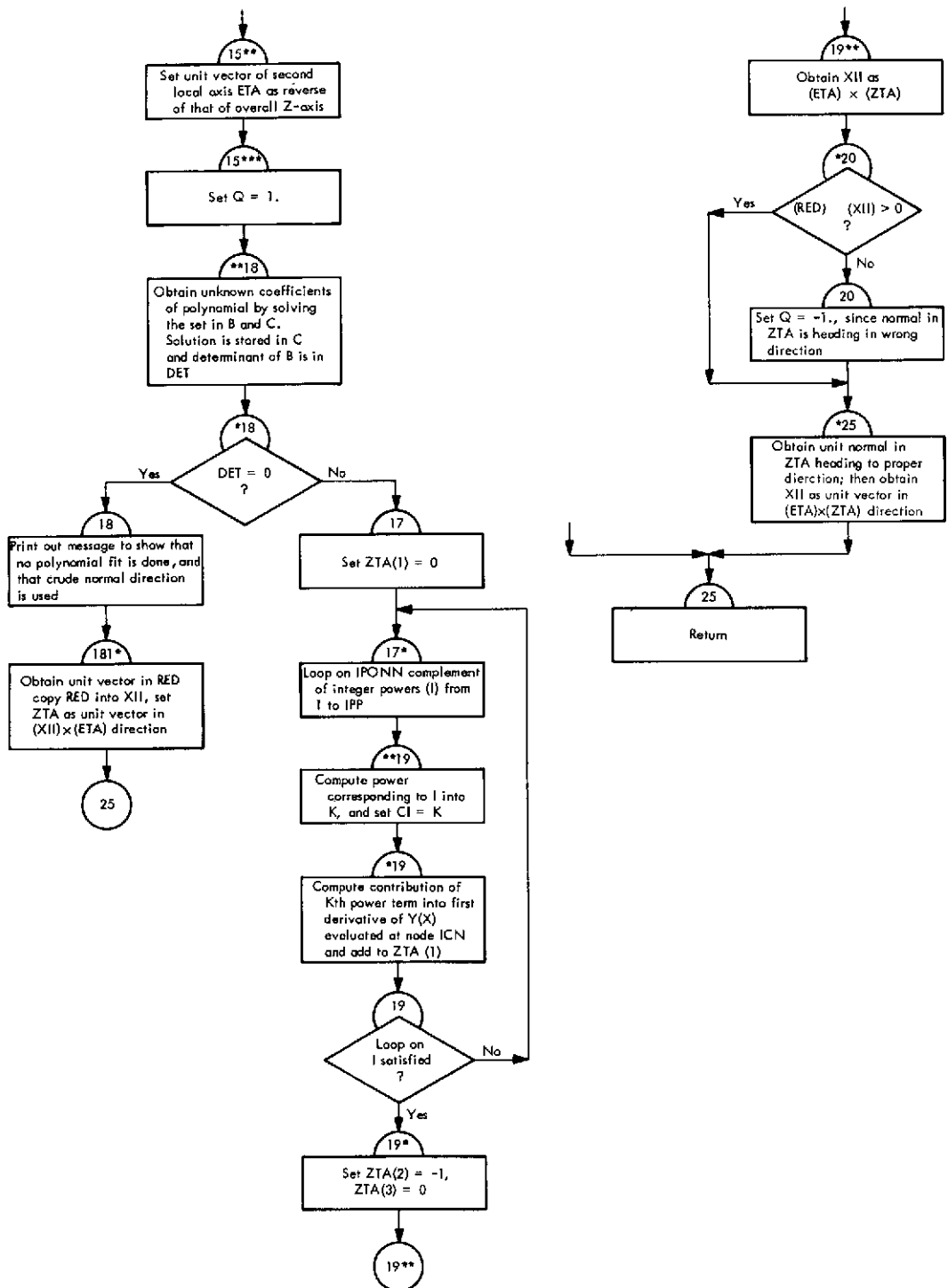


Fig. VI-64 (contd)

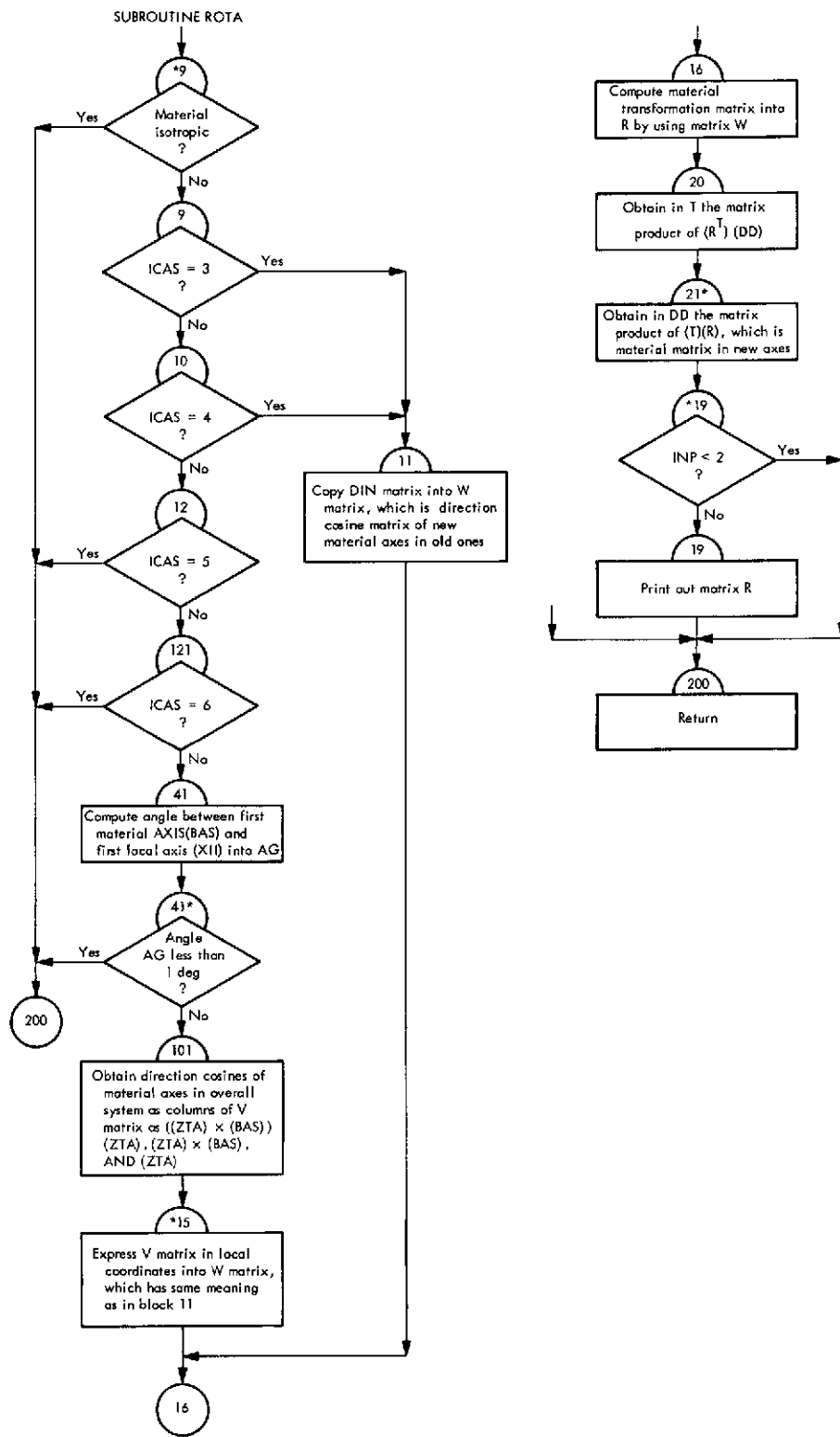


Fig. VI-65. Flowchart of subroutine ROTA (Link 4)





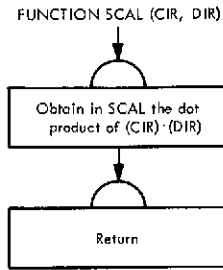


Fig. VI-67. Flowchart of function SCAL (Link 4)

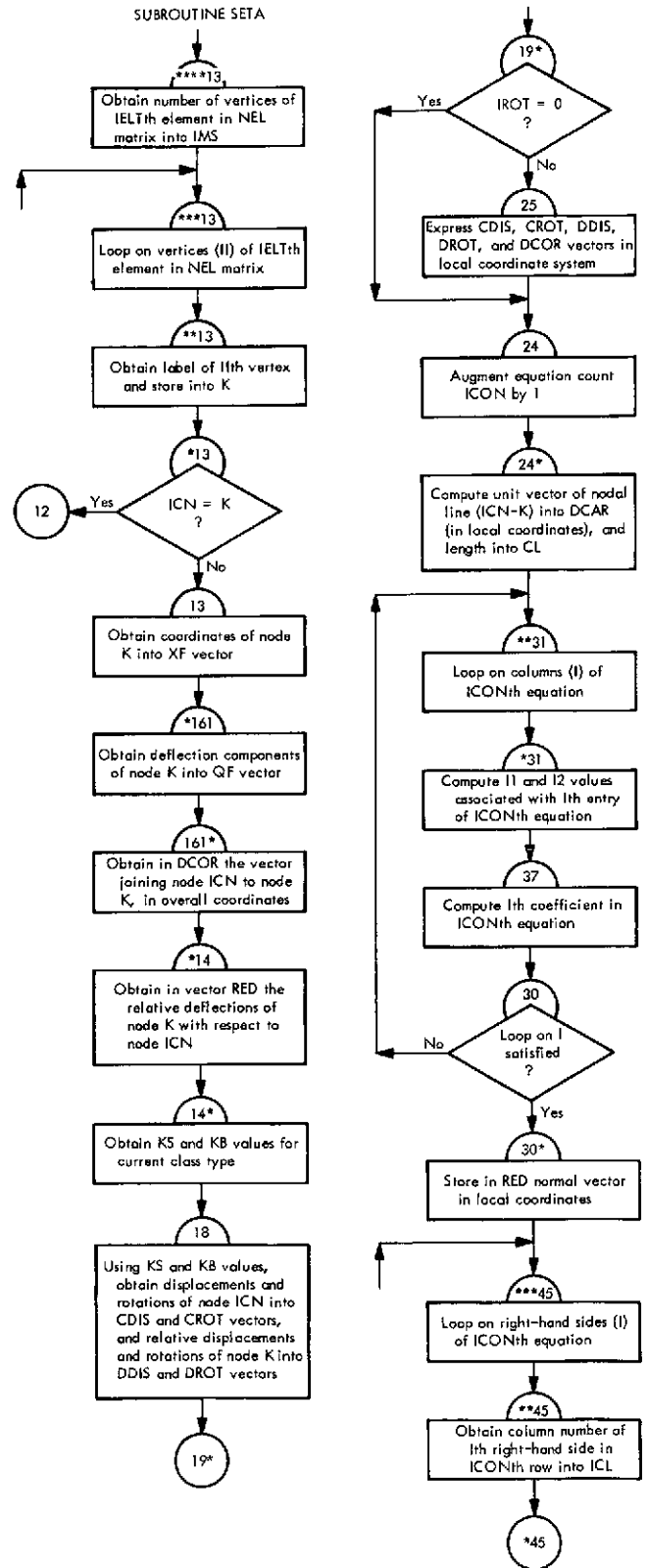


Fig. VI-68. Flowchart of subroutine SETA (Link 4)

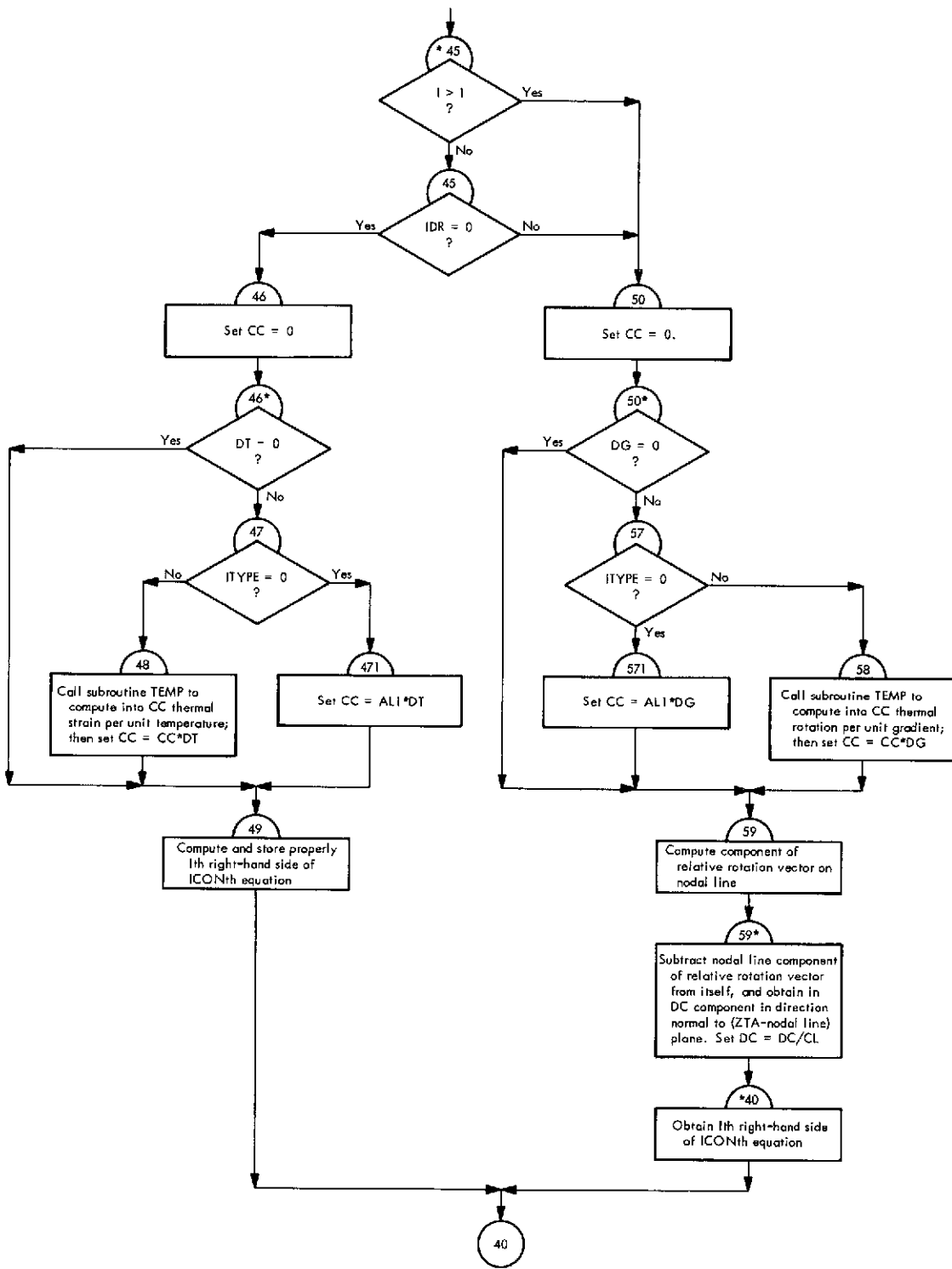


Fig. VI-68 (contd)

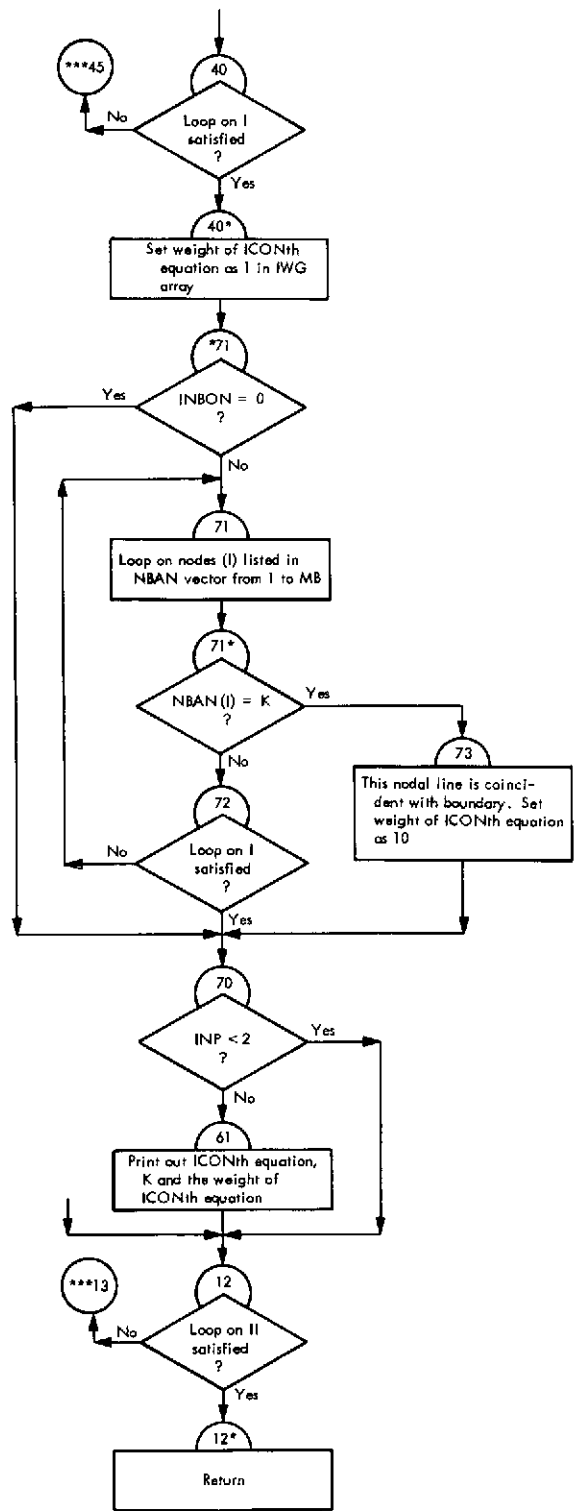


Fig. VI-68 (contd)

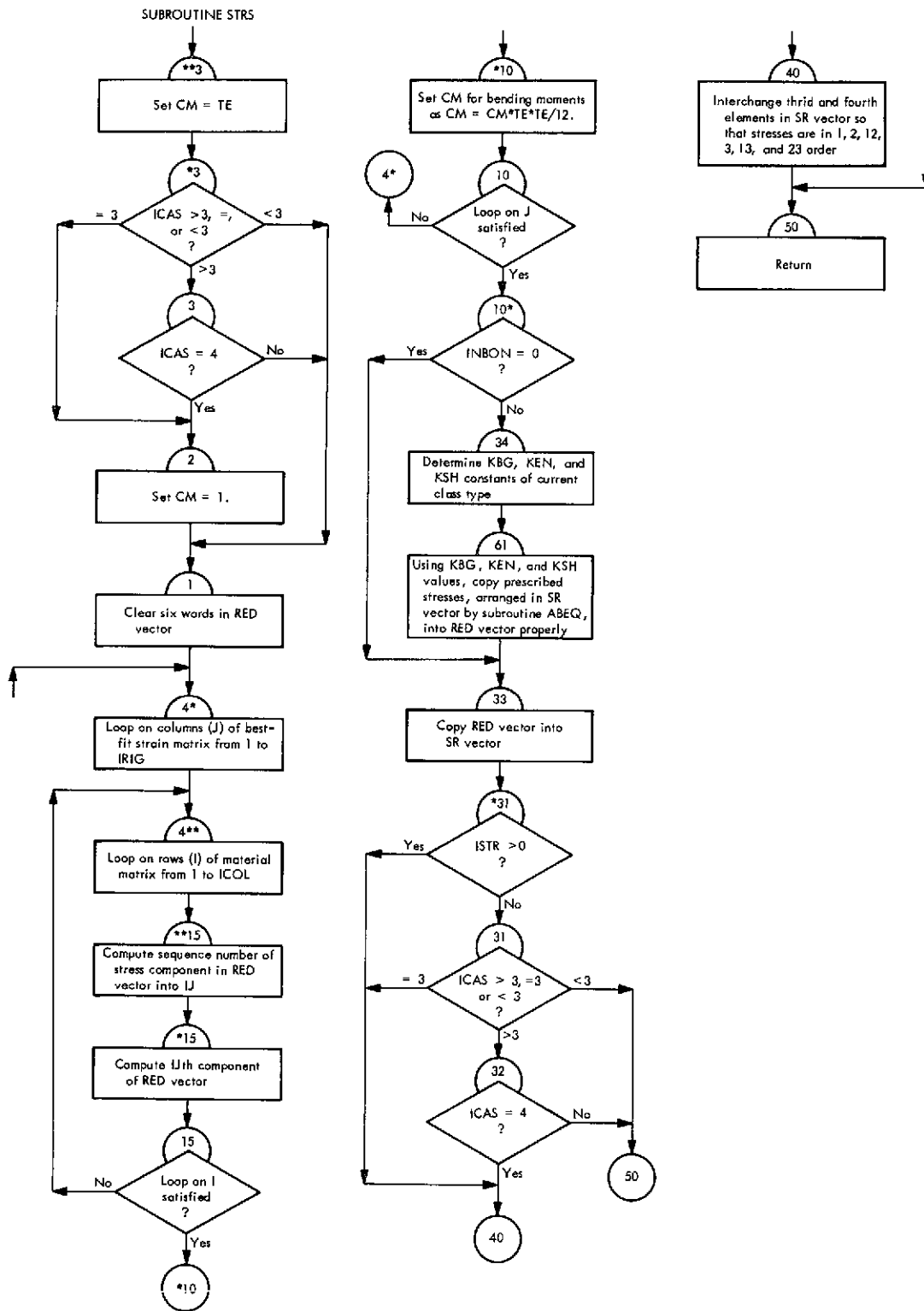


Fig. VI-69. Flowchart of subroutine STRS (Link 4)

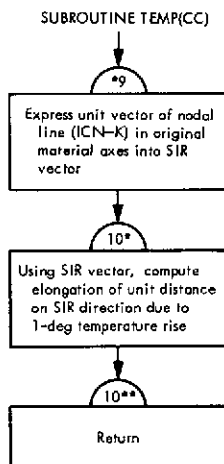


Fig. VI-70. Flowchart of subroutine TEMP (Link 4)

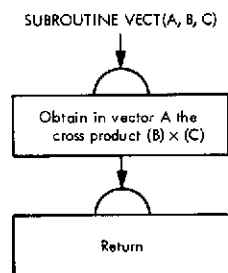


Fig. VI-72. Flowchart of subroutine VECT (Link 4)

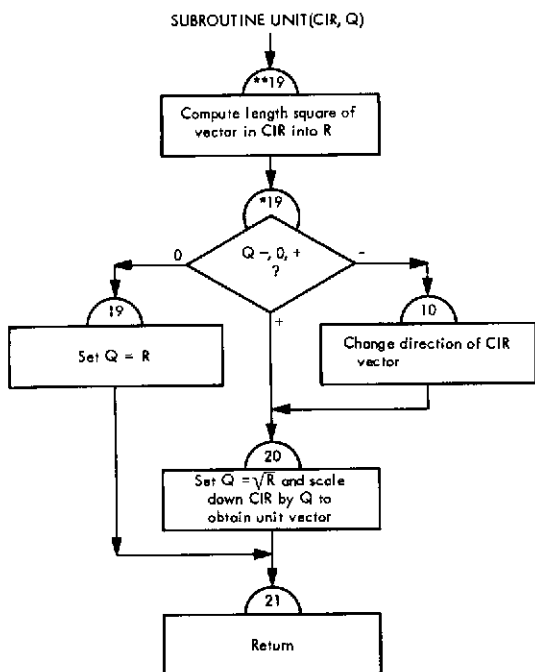


Fig. VI-71. Flowchart of subroutine UNIT (Link 4)

## VII. Source Program Listings

This section contains the source program listings of ELAS/Level 3. The listing of each program element is treated separately, and given a table number. The listings are arranged alphabetically by the subroutine names, under the main program of each link. The meanings of the variables used in the source program may be obtained from Tables III-2, III-3, and III-4 of Vol. II (basic). The organization of COMMON for each link is shown in Fig. III-1 of Vol. II (basic).



Table VII-1 (contd)

2400	READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,NTIC)	ELAS1225	DUMMY(I+1000)=AA(IYYI)	ELAS1340
	DD 2600 I=1,NTIC	ELAS1226	DUMMY(I+2000)=AA(IZZI)*ZGEM	ELAS1341
	IF (IDUM(I)-1) 300,5500,300	ELAS1227	CONTINUE	ELAS1342
5900	I=I+I+I	ELAS1228	WRITE OUTPUT TAPE 6,8302,I1,DUMMY(I),DUMMY(I+1000),DUMMY(I+2000),I	ELAS1343
	AA(IIC)=DUMMY(I+100)	ELAS1229	L=L+1000	ELAS1344
2600	CONTINUE	ELAS1230	IF (L-NTP) 9010,9030,9030	ELAS1345
	IF (INP-1) 6217,2900,2900	ELAS1231	IN=NTP	ELAS1346
2900	WRITE OUTPUT TAPE 6,1302,(I,DUMMY(I+100),I=1,NTIC)	ELAS1232	C PREPARE VECTORS NECESSARY FOR IMPUSING BOUNDARY CONDITIONS	ELAS1347
1302	FORMAT (///4X,15HTHICKNESS TYPES//15(I5,F15.5,4X))	ELAS1233	DO 6 I=1,IND	ELAS1348
6217	IF (ISDT) 300,6216,5700	ELAS1234	I=I+100	ELAS1349
5700	READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,ISDT)	ELAS1235	I=I+100	ELAS1350
	DD 5720 I=1,ISDT	ELAS1236	I=I+100	ELAS1351
	IF (IDUM(I)-1) 300,5710,300	ELAS1237	I=I+100	ELAS1352
5710	I=I+100	ELAS1238	I=I+100	ELAS1353
	AA(IOTI)=DUMMY(I+100)	ELAS1239	I=I+100	ELAS1354
5720	CONTINUE	ELAS1240	I=I+100	ELAS1355
	IF (INP-1) 6216,5730,5730	ELAS1241	I=I+100	ELAS1356
5730	WRITE OUTPUT TAPE 6,1303,(I,DUMMY(I+100),I=1,ISDT)	ELAS1242	I=I+100	ELAS1357
1303	FORMAT (///4X,26HTEMPERATURE INCREASE TYPES//15(I5,E15.5,4X))	ELAS1243	I=I+100	ELAS1358
6216	IF (ISDY) 300,6215,3500	ELAS1244	I=I+100	ELAS1359
3500	READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,ISDY)	ELAS1245	I=I+100	ELAS1360
	DD 3700 I=1,ISDY	ELAS1246	I=I+100	ELAS1361
	IF (IDUM(I)-1) 300,3600,300	ELAS1247	I=I+100	ELAS1362
3600	I=I+100	ELAS1248	I=I+100	ELAS1363
	AA(IOTI)=DUMMY(I+100)	ELAS1249	I=I+100	ELAS1364
3700	CONTINUE	ELAS1250	I=I+100	ELAS1365
	IF (INP-1) 6215,3600,3600	ELAS1251	I=I+100	ELAS1366
3600	WRITE OUTPUT TAPE 6,1304,(I,DUMMY(I+100),I=1,ISDY)	ELAS1252	I=I+100	ELAS1367
1304	FORMAT (///4X,39HTEMPERATURE GRADIENT TYPES ALONG Y AXIS//15(I5,E15.5,4X))	ELAS1253	I=I+100	ELAS1368
6215	IF (ISDZ) 300,6214,4000	ELAS1254	I=I+100	ELAS1369
4000	READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,ISDZ)	ELAS1255	I=I+100	ELAS1370
	DD 4200 I=1,ISDZ	ELAS1256	I=I+100	ELAS1371
	IF (IDUM(I)-1) 300,4100,300	ELAS1257	I=I+100	ELAS1372
4100	I=I+100	ELAS1258	I=I+100	ELAS1373
	AA(IIDZ)=DUMMY(I+100)	ELAS1259	I=I+100	ELAS1374
4200	CONTINUE	ELAS1260	I=I+100	ELAS1375
	IF (INP-1) 6214,4300,4300	ELAS1261	I=I+100	ELAS1376
4300	WRITE OUTPUT TAPE 6,1305,(I,DUMMY(I+100),I=1,ISDZ)	ELAS1262	I=I+100	ELAS1377
1305	FORMAT (///4X,39HTEMPERATURE GRADIENT TYPES ALONG Z AXIS//15(I5,E15.5,4X))	ELAS1263	I=I+100	ELAS1378
6214	IF (IARE) 300,6213,4500	ELAS1264	I=I+100	ELAS1379
4500	READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,IARE)	ELAS1265	I=I+100	ELAS1380
	DD 4700 I=1,IARE	ELAS1266	I=I+100	ELAS1381
	IF (IDUM(I)-1) 300,4600,300	ELAS1267	I=I+100	ELAS1382
4600	I=I+100	ELAS1268	I=I+100	ELAS1383
	AA(ICAR)=DUMMY(I+100)	ELAS1269	I=I+100	ELAS1384
4700	CONTINUE	ELAS1270	I=I+100	ELAS1385
	IF (INP-1) 6213,4800,4800	ELAS1271	I=I+100	ELAS1386
4800	WRITE OUTPUT TAPE 6,1306,(I,DUMMY(I+100),I=1,IARE)	ELAS1272	I=I+100	ELAS1387
1306	FORMAT (///4X,10HAREA TYPES//15(I5,E15.5,4X))	ELAS1273	I=I+100	ELAS1388
6213	IF (IMMX) 300,6212,5000	ELAS1274	I=I+100	ELAS1389
5000	READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,IMMX)	ELAS1275	I=I+100	ELAS1390
	DD 5200 I=1,IMMX	ELAS1276	I=I+100	ELAS1391
	IF (IDUM(I)-1) 300,5100,300	ELAS1277	I=I+100	ELAS1392
5100	I=I+100	ELAS1278	I=I+100	ELAS1393
	AA(ICIX)=DUMMY(I+100)	ELAS1279	I=I+100	ELAS1394
5200	CONTINUE	ELAS1280	I=I+100	ELAS1395
	IF (INP-1) 6212,5300,5300	ELAS1281	I=I+100	ELAS1396
5300	WRITE OUTPUT TAPE 6,1307,(I,DUMMY(I+100),I=1,IMMX)	ELAS1282	I=I+100	ELAS1397
1307	FORMAT (///4X,22HTORSION CONSTANT TYPES//15(I5,E15.5,4X))	ELAS1283	I=I+100	ELAS1398
6212	IF (IMMY) 300,6209,6000	ELAS1284	I=I+100	ELAS1399
6000	READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,IMMY)	ELAS1285	I=I+100	ELAS1400
	DD 6200 I=1,IMMY	ELAS1286	I=I+100	ELAS1401
	IF (IDUM(I)-1) 300,6100,300	ELAS1287	I=I+100	ELAS1402
6100	I=I+100	ELAS1288	I=I+100	ELAS1403
	AA(ICIY)=DUMMY(I+100)	ELAS1289	I=I+100	ELAS1404
6200	CONTINUE	ELAS1290	I=I+100	ELAS1405
	IF (INP-1) 6209,6300,6300	ELAS1291	I=I+100	ELAS1406
6300	WRITE OUTPUT TAPE 6,1308,(I,DUMMY(I+100),I=1,IMMY)	ELAS1292	I=I+100	ELAS1407
1308	FORMAT (///4X,50HMODIMENT OF INERTIA TYPES ABOUT FIRST PRINCIPAL AXES//15(I5,F15.5,4X))	ELAS1293	I=I+100	ELAS1408
6209	IF (IMMZ) 300,6208,6500	ELAS1294	I=I+100	ELAS1409
6500	READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,IMMZ)	ELAS1295	I=I+100	ELAS1410
	DD 6700 I=1,IMMZ	ELAS1296	I=I+100	ELAS1411
	IF (IDUM(I)-1) 300,6600,300	ELAS1297	I=I+100	ELAS1412
6600	I=I+100	ELAS1298	I=I+100	ELAS1413
	AA(ICIZ)=DUMMY(I+100)	ELAS1299	I=I+100	ELAS1414
6700	CONTINUE	ELAS1300	I=I+100	ELAS1415
	IF (INP-1) 6208,6800,6800	ELAS1301	I=I+100	ELAS1416
6800	WRITE OUTPUT TAPE 6,1309,(I,DUMMY(I+100),I=1,IMMZ)	ELAS1302	I=I+100	ELAS1417
1309	FORMAT (///4X,51HMODIMENT OF INERTIA TYPES ABOUT SECOND PRINCIPAL AXES//15(I5,E15.5,4X))	ELAS1303	I=I+100	ELAS1418
6208	IF (IMF) 300,6830,7000	ELAS1304	I=I+100	ELAS1419
7000	READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,IMF)	ELAS1305	I=I+100	ELAS1420
	DD 7200 I=1,IMF	ELAS1306	I=I+100	ELAS1421
	IF (IDUM(I)-1) 300,7100,300	ELAS1307	I=I+100	ELAS1422
7100	I=I+100	ELAS1308	I=I+100	ELAS1423
	AA(ICFI)=DUMMY(I+100)	ELAS1309	I=I+100	ELAS1424
7200	CONTINUE	ELAS1310	I=I+100	ELAS1425
	IF (INP-1) 830,7300,7300	ELAS1311	I=I+100	ELAS1426
7300	WRITE OUTPUT TAPE 6,1310,(I,DUMMY(I+100),I=1,IMF)	ELAS1312	I=I+100	ELAS1427
1310	FORMAT (///4X,35HANGLE TYPES DEFINING PRINCIPAL AXES//15(I5,E15.5,4X))	ELAS1313	I=I+100	ELAS1428
830	IF (ICOR) 8311,8311,8311	ELAS1314	I=I+100	ELAS1429
8311	CALL CORR	ELAS1315	I=I+100	ELAS1430
	GO TO 5810	ELAS1316	I=I+100	ELAS1431
831	CALL CORR	ELAS1317	I=I+100	ELAS1432
	IF (IERR) 300,5810,300	ELAS1318	I=I+100	ELAS1433
5810	IF (INP-1) 5850,2519,2519	ELAS1319	I=I+100	ELAS1434
2519	L=0	ELAS1320	I=I+100	ELAS1435
	NTP=IN	ELAS1321	I=I+100	ELAS1436
9010	IF (L+1000-NTP) 9015,9020,9020	ELAS1322	I=I+100	ELAS1437
9015	IN=1000	ELAS1323	I=I+100	ELAS1438
	GO TO 9025	ELAS1324	I=I+100	ELAS1439
9020	IN=NTP-L	ELAS1325	I=I+100	ELAS1440
9025	DD 5800 I=1,IN	ELAS1326	I=I+100	ELAS1441
	IXX=IXX+I	ELAS1327	I=I+100	ELAS1442
	IYY=IYY+I	ELAS1328	I=I+100	ELAS1443
	IZZ=IZZ+I	ELAS1329	I=I+100	ELAS1444
	DUMMY(I)=AA(IXX)	ELAS1330	I=I+100	ELAS1445
		ELAS1331	I=I+100	ELAS1446
		ELAS1332	I=I+100	ELAS1447
		ELAS1333	I=I+100	ELAS1448
		ELAS1334	I=I+100	ELAS1449
		ELAS1335	I=I+100	ELAS1450
		ELAS1336	I=I+100	ELAS1451
		ELAS1337	I=I+100	ELAS1452
		ELAS1338	I=I+100	ELAS1453
		ELAS1339	I=I+100	ELAS1454



Table VII-1 (contd)

3,5R AREA,5H 1-XX,5H 1-YY,5H 1-ZZ,5H FI-Y??)	FLAS1455	IICJ=IIC+J	FLAS1524
717 IF (IMES) 7908,7909,7908	FLAS1456	2311 DUMMY (I+4000)=DUMMY (I+4000)+AA (IICJ)*DUMMY (I+2000)	FLAS1525
7408 CALL MESC	FLAS1457	121 FORMAT (51(A,11-E11,51)	FLAS1526
GO TO 79	FLAS1458	C PRINT OUT DISPLACEMENT AND FORCE BOUNDARY CONDITIONS	FLAS1527
7909 CALL MEST	FLAS1459	820 IF (INP-1) 2520,2521,2521	FLAS1528
IF (IEER) 300,79,300	FLAS1460	2521 DD 8201 J=1,10FG	FLAS1529
79 DD 9000 M=1,11	FLAS1461	IRJ=IRJ+J-1	FLAS1530
CALL TPO	ELAS1462	IRB=IRB+J-1	FLAS1531
IF (INP-1) 9000,5895,5895	ELAS1463	TIC=IIC+J-1	FLAS1532
5895 WRITE OUTPUT TAPE 6,7959,M,(N1),1=1,8),I,ELT,JPRS,IMPT,IIC,ITFM	ELAS1464	IDEFJ=IDEF+J-1	FLAS1533
1,JSDY,JSOZ,JARE,JMMX,JMMY,JMMZ,JMFI	FLAS1465	WRITE OUTPUT TAPE 6,8202,J	FLAS1534
4000 CONTINUE	FLAS1466	8202 FORMAT (1H1,30X,55#FORCF AND DISPLACEMENT BOUNDARY CONDITIONS IN	FLAS1535
7959 FORMAT (16,4X,815,10X,1215)	FLAS1467	1#RECTIM,157/215H NODE,7X,1HP,12X,3HIRG,4X,3HIBH,6X,1MC,1RX1/71	FLAS1536
CALL SRAT	FLAS1468	DD 8203 J=1,IND,IREG	FLAS1537
I=1	FLAS1469	IRJ=IRJ+1	FLAS1538
DU 461 K=1,IN	ELAS1470	IRB=IRB+1	FLAS1539
IK=ISIR(K)	ELAS1471	IIC=IIC+J	FLAS1540
(KD=IK-1)*IDEG	ELAS1472	IDEFJ=IDEFJ+1	FLAS1541
DD 46 J=1,IDEG	FLAS1473	K=I/IDEG+1	FLAS1542
I=IK+J	FLAS1474	DUMMY(K) =AA(10FFI)	FLAS1543
IRB=IRB+1	ELAS1475	IDUM(K+1000)=IA(IRH)	FLAS1544
IRJ=IRJ+1	ELAS1476	IDUM(K+2000)=IA(IRJ)	FLAS1545
N=IA(IRJ)	ELAS1477	8203 DUMMY(K+3000)=AA(IIC)	FLAS1546
IF (N) 45,46,46	FLAS1478	WRITE OUTPUT TAPE 6,8214,(K,DUMMY(K),IDUM(K+2000),IDUM(K+1000),	FLAS1547
45 IF (N+1) 451,452,46	FLAS1479	IDUM(K+3000),K=1,IN)	FLAS1548
451 IA(IRH)=J	FLAS1480	8214 FORMAT (215,E16,4,217,F15,4,10X1)	FLAS1549
GO TO 453	FLAS1481	8201 CONTINUE	FLAS1550
452 IA(IRH)=I	ELAS1482	L=L+1000	FLAS1551
453 I=I+1	ELAS1483	IF (L-NTP) 8000,2517,2517	FLAS1552
46 CONTINUE	ELAS1484	2517 IP=NTP	FLAS1553
461 CONTINUE	FLAS1485	2520 DD 8204 I=1,IND	FLAS1554
ISUM=I-1	FLAS1486	IDEFJ=IDEF+1	FLAS1555
DD 47 I=1,IND	FLAS1487	8204 AA(IDEFJ)=DUMMY(I+4000)	FLAS1556
IDJ=IRJ+1	ELAS1488	C COMPUTE IMPORTANT CONSTANTS	FLAS1557
N=IA(IDJ)	FLAS1489	IST=I+ISUM+1	FLAS1558
IF (N) 47,47,48	ELAS1490	LIST=IST-9000	FLAS1559
48 IF (N-10000)4R1,48Z,48Z	FLAS1491	IF (LIST) 353,354,354	FLAS1560
48Z IRH=IRH+1	ELAS1492	354 WRITE OUTPUT TAPE 6,355,LIST	FLAS1561
IA(IRH)=IND	FLAS1493	355 FORMAT (6X,54HDUMMY AREA OVERLAYS COMMON AREA BY 16,19H DECIMAL	FLAS1562
GO TO 47	FLAS1494	LOCATIONS,75X,87H RECOMPILE BY CHANGING THE EQUIVALENCES OF DUMMY	FLAS1563
461 IRH=IRH+N	FLAS1495	2ND BR IN LINKS 1 AND 3, RESPECTIVELY.1	FLAS1564
IRB=IRB+I	FLAS1496	353 CALL TICK (ITIM)	FLAS1565
IA(IRB)=IA(IRBN)	FLAS1497	CIT=ITIM	FLAS1566
47 CONTINUE	FLAS1498	CIT=CIT/60.	FLAS1567
READ IN EXTERNAL CONCENTRATED LOADS	ELAS1499	WRITE OUTPUT TAPE 6,555,CIT	FLAS1568
DD 2310 I=1,IND	FLAS1500	5555 FORMAT (16H INPUT LINK TOOK,F7.2,10H SECONDS.)	FLAS1569
IDEFJ=IDEF+1	FLAS1501	READ INPUT TAPE 5,2800,TEST	FLAS1570
DUMMY (I+4000)=0.	FLAS1502	IF (INP-1) 332,332,331	FLAS1571
2310 AA(IDEFJ)=0.	ELAS1503	331 N81=XLOC(IA(1))	FLAS1572
IF (IP) 300,820,5450	FLAS1504	N82=XLOC(IA(ID+1))	FLAS1573
5450 L=0	FLAS1505	N83=XLOC(IA(IST+1))	FLAS1574
NTP=IP	FLAS1506	NC1=N81-N82	FLAS1575
8000 IF (L+1000-NTP) 8100,8200,8200	ELAS1507	NC3=N81-N83	FLAS1576
8100 IP=1000	FLAS1508	WRITE OUTPUT TAPE 6,5666,(I,IA(1),I=1,NC1)	FLAS1577
GO TO 1211	FLAS1509	6666 FORMAT (1H1,RHAA BLOCK/120(A1)	FLAS1578
8200 IP=NTP-L	FLAS1510	WRITE OUTPUT TAPE 6,6667,(I,AA(1),I=1,NC3)	FLAS1579
1211 READ INPUT TAPE 5,121,(IDUM(I),IDUM(I+1000)+DUMMY(I+2000),I=1,IP)	FLAS1511	6667 FUKMAI (1H1,RHAA BLOCK/151(A,15,5,2X1)	FLAS1580
DD 2311 I=1,IP	FLAS1512	IF (ERR) 346,332,346	FLAS1581
N0=IDUM(I)	FLAS1513	346 READ INPUT TAPE 5,2800,TEST	FLAS1582
KD=IDUM(I+1000)	FLAS1514	IF (TEST-GTFS) 346,2700,346	FLAS1583
IF (KD-IDF) 326,327,300	ELAS1515	2800 FORMAT (7X,45)	FLAS1584
326 IF (KD) 300,300,327	FLAS1516	342 IF (INX-1) 300,3321,3322	FLAS1585
327 IF (NO-IN) 328,329,300	FLAS1517	3321 GO TO 2700	FLAS1586
328 IF (NO) 300,300,329	FLAS1518	3322 CALL CHAIN (2,ITAP)	FLAS1587
329 J=IDEG*(NO-1)+KCO	FLAS1519	300 WRITE OUTPUT TAPE 6,6665	FLAS1588
IDEFJ=IDEF+J	FLAS1520	6665 FORMAT (1H1,12H INPUT FRKMI	FLAS1589
AA(IDFJ)=DUMMY(I+2000)	FLAS1521	FRR=1	FLAS1590
IRB=IRB+J	ELAS1522	GO TO 331	FLAS1591
I=I+1	FLAS1523	END	FLAS1592

Table VII-2. Source program listing of subroutine ARAN (Link 1)

* LABEL	C1ARAN	C1ARAN000	1110 NEP=2	F1ARN114
SUBROUTINE ARAN		F1ARN001	N0=ANR0+1	F1ARN115
XLAFFLS MESC POINTS		F1ARN002	I=900	F1ARN116
1#DIMENSION IA(11,AA(1)),REF(11),N(110),DUMMY(5000),IDUM(5000),M(8)		F1ARN003	GO TO 1130	F1ARN117
1,P(24),HV(24),X(8),Y(8),Z(8),X1(7),Y1(7),Z1(7),RUMMY(27,9)		F1ARN004	1120 NEP=1	F1ARN118
2,R(121),S(11),G(1)		F1ARN005	NEQ=NEQ+1	F1ARN119
COMMON IA,AA		F1ARN006	I=NEQ	F1ARN120
EQUIVALENCE (IA,AA),(AA,9000),DUMMY)		F1ARN007	1130 I=I+1	F1ARN121
EQUIVALENCE (DUMMY,IDUM,NY,ARMY),DUMMY(11),REF)		F1ARN008	IG=IMAX(I)-IMAX(IP)	F1ARN122
EQUIVALENCE (IA(1),IN),(IA(2),IRN),(IA(3),IT),(IA(4),KK),(IA(5),		F1ARN009	IL=IMIN(I)-IMIN(IP)	F1ARN123
1)PHS),(IA(6),ITYPE),(IA(7),IA(11),IA(8),IDEG),(IA(9),JNK),(IA(10),F1ARN010		F1ARN010	IF (IG) 1140,1150,1150	F1ARN124
2)H),(IA(11),IR),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),F1ARN011		F1ARN011	1140 MX=IMAX(I)	F1ARN125
3)HFI),(IA(16),IARF),(IA(17),M(1)),IA(25),M),(IA(26),ITY),(IA(27),F1ARN012		F1ARN012	MX=IMAX(IP)	F1ARN126
4)ISTR),(IA(28),IELT),(IA(29),ITFM),(IA(30),TIC),(IA(31),IMPT),		F1ARN013	GO TO 1160	F1ARN127
5)IA(32),ISUM),(IA(33),IND),(IA(34),INS),(IA(36),ISJ),(IA(37),		F1ARN014	1150 MX=IMAX(IP)	F1ARN128
6)IRJ),(IA(38),IRB),(IA(39),ACEL),(IA(40),C(1)),IA(45),C(1),IA(45),		F1ARN015	KF=IMX(I)	F1ARN129
7)IA(52),JSDY,IA(53),JARE,IA(54),JMMX,IA(55),JMMY,IA(56),JMMZ,IA(57),F1ARN016		F1ARN016	IF (IL) 1170,1180,1180	F1ARN130
8)IA(58),JTY),(IA(59),IRG),(IA(60),IRB),(IA(61),ID),(IA(62),F1ARN017		F1ARN017	M1=IMIN(IP)	F1ARN131
9)IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITF),(IA(66),ITAP)		F1ARN018	GO TO 1190	F1ARN132
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69),		F1ARN019	1180 M1=IMIN(I)	F1ARN133
1)ICJ),(IA(70),ICF),(IA(71),IX),(IA(72),IY),(IA(73),IZ),		F1ARN020	M1=IMIN(IP)	F1ARN134
2)IA(74),ICG),(IA(75),IDF),(IA(76),IST),(IA(77),IIS)		F1ARN021	J=I+1/28+1	F1ARN135
3),IA(78),ICR),(IA(79),IFR),(IA(80),IFR),(IA(81),D(1)),IA(82),DC,		F1ARN022	ACH=ARIN(IP,J)	F1ARN137
4)AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P1,		F1ARN023	JRIT=1-36/(J-1)	F1ARN138
5)AA(131),HV),(AA(155),X1),(AA(163),Y1),(AA(171),Z1),(AA(179),XD),		F1ARN024	IP=LFJMINIACH,JRIT)	F1ARN139
6)AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZGM)		F1ARN025	IF (IP) 1270,1210,1270	F1ARN140
7),IA(42),IPG),(AA(43),IPNG),(AA(44),IPFG),(AA(45),DINS1),(AA(46),IUF)		F1ARN026	1210 IF (IMIN(I)-1) 1220,1230,1220	F1ARN141
8),IA(47),G1),(AA(48),G2),(AA(49),G3)		F1ARN027	1220 IF (IMIN(IP)-IP) 1240,1230,1240	F1ARN142
EQUIVALENCE (IA(35),ISUM),(IA(30),ISIR)		F1ARN028	1230 I=I+1	F1ARN143
EQUIVALENCE (AA(302),M),(AA(303),MX),(AA(304),1),(AA(305),IP)		F1ARN029	1240 IF (IMAX(I)-1) 1250,1260,1250	F1ARN144
EQUIVALENCE (IARH,IRHC),(IARIN,IRANI)		F1ARN030	1250 IF (IMAX(IP)-IP) 1270,1260,1270	F1ARN145
H)MNSJIN IRR(8000),IBAN(8000),ISIR(540),IMAX(540),IMIN(540),		F1ARN031	1260 IG=IG+1	F1ARN146
IARIN(540),ISIR(540)		F1ARN032	1270 IF (IG+IL) 1910,1280,1400	F1ARN147
EQUIVALENCE (DUMMY,ABIN),(DUMMY(8100),ISIR),(DUMMY(8640),IMAX),		F1ARN033	1280 NZL=0	F1ARN148
I)DUMMY(9180),IMIN),(DUMMY(8640),ISIR)		F1ARN034	NZRO	F1ARN149
CLT=0.		F1ARN035	DO 1300 J=1,IN	F1ARN150

Table VII-2 (contd)

<pre> XSAP=0 XN-IN NCYCL=0 NCYCN=IN/10+3 ISURP=ISUR+1 ICYCL=1 DO 80 I=1,90,40,10 10 READ INPUT TAPE 5,1,(ISIRI),I=1,INI 1 FORMAT (20I4) DO 20 I=1,IN 20 ISIRI(I)=I MI=1 MX=IN DO 30 IP=1,IN DO 23 JP=1,IN IF ((SIRI(I)-SIRI(J)))/ 23,24,23 23 CONTINUE GO TO 3100 24 IF ((IP-JP) 25,80,25 25 ISIRI(IP)=SIRI(J) CALL EXCH 80 CONTINUE 30 DO 100 I=1,IN IMINI(I)=0 100 IMAX(I)=0 DO 700 I=1,IN DO 400 J=1,ISIR ACH=ABIN(I,J) DO 300 JB=1,36 IF ((LFIN(ACH,JB)) 420,300,420 300 CONTINUE 400 CONTINUE GO TO 3100 420 IMINI(I)=36*(J-1)+JB JE=ISURP-J DO 600 J=1,JC JB=ISURP-J ACH=ABIN(I,JB) DO 500 JB=1,36 JBC=36-JB+1 IF ((LFIN(ACH,JBC)) 620,500,620 500 CONTINUE 600 CONTINUE GO TO 3100 620 IMAX(I)=36*(JB)-JB+1 700 CONTINUE IF ((ISURF-1) 2010,750,750 750 CALL TICK (ITIM) CRT=ITIM IF ((INP-1) 1100,1100,800 800 CALL OUTPT 1100 NBD=0 NFD=IN NCH=0 ICYCL=ICYCL+1 XSA=IN-IMAX(I) JMAXP=IMAX(I) XMAXP=XMAXP DO 1105 I=2,IN IF ((IMAX(I)-IMAXP) 1105,1105,1102 1102 IMAXP=IMAX(I) XMAXP=XMAXP 1105 XSA=XSA+XN-XMAXP IF (XSA-XSAP) 1106,1106,1107 1106 NCYCL=NCYCL+1 IF (NCYCL=NCYCN) 1108,1108,1985 1107 XSAP=XSA NCYCL=0 1108 CALL TICK (ITIM) CNT=ITIM CNT=(CNT-CRT)/60. IF (CNT-CLT) 1110,1109,1109 1109 CLT=CLT+100. WRITE OUTPUT TAPE 6,3,CNT,ICYCL,XSA IF (CNT-100.) 1110,1110,1111 1111 MIPCH=1+(SIRI(I)-1),INI 3 FORMAT (3H AT,47,2,10H REC. OF RELABELING,16,75H INTERCHANGES DONE) 1, UPPER OFF-DIAGONAL ELEMENT COUNT OF MESH TOPOLOGY MATRIX (S,EP,0) IJ=IP+J IF (IJ-IN) 1290,1290,1310 1290 IF ((MIN(IJ)-MIN) 1500,1500,1320 1300 CONTINUE 1310 MNN=IN GO TO 1330 1320 MNN=MIN(IJ)-1 1330 DO 1350 J=1,IP JI=J-J IF (JI-1) 1360,1360,1360 1360 IF ((IMAX(JI)-MXP) 1360,1360,1360 1370 CONTINUE 1380 MXA=1 GO TO 1370 1380 MXB=IMAX(JI)+1 1390 IF (MNN-NIM) 1410,1375,1375 1400 IF (MNN-1) 1390,1380,1380 </pre>	<pre> FIARN036 FIARN037 FIARN038 FIARN039 FIARN040 FIARN041 FIARN042 FIARN043 FIARN044 FIARN045 FIARN046 FIARN047 FIARN048 FIARN049 FIARN050 FIARN051 FIARN052 FIARN053 FIARN054 FIARN055 FIARN056 FIARN057 FIARN058 FIARN059 FIARN060 FIARN061 FIARN062 FIARN063 FIARN064 FIARN065 FIARN066 FIARN067 FIARN068 FIARN069 FIARN070 FIARN071 FIARN072 FIARN073 FIARN074 FIARN075 FIARN076 FIARN077 FIARN078 FIARN079 FIARN080 FIARN081 FIARN082 FIARN083 FIARN084 FIARN085 FIARN086 FIARN087 FIARN088 FIARN089 FIARN090 FIARN091 FIARN092 FIARN093 FIARN094 FIARN095 FIARN096 FIARN097 FIARN098 FIARN099 FIARN100 FIARN101 FIARN102 FIARN103 FIARN104 FIARN105 FIARN106 FIARN107 FIARN108 FIARN109 FIARN110 FIARN111 FIARN112 FIARN113 FIARN114 FIARN115 FIARN116 FIARN117 FIARN118 FIARN119 FIARN120 FIARN121 FIARN122 FIARN123 FIARN124 FIARN125 FIARN126 FIARN127 FIARN128 FIARN129 FIARN130 FIARN131 FIARN132 FIARN133 FIARN134 FIARN135 FIARN136 FIARN137 FIARN138 FIARN139 FIARN140 FIARN141 FIARN142 FIARN143 FIARN144 FIARN145 FIARN146 FIARN147 </pre>	<pre> 1300 MNN=I-1 GO TO 1370 1390 DO 1400 J=MIN,MNN JJ=J-1/36 JJP=JJ+1 ACH=ABIN(I,JJP) JB=J-36*JJ IF ((LFIN(ACH,JB)) 1395,1393,1395 1395 NZG=NZG+1 1395 ACH=ABIN(IP,JJP) JB=J-36*JJ IF ((LFIN(ACH,JB)) 1400,1397,1400 1397 NZL=NZL+1 1400 CONTINUE 1410 IF (MXB-MXM) 1415,1415,1460 1415 IF (MXB-IP) 1420,1420,1430 1420 MXR=IP+1 GO TO 1410 1430 DO 1450 J=MXB,MXM JJ=J-1/36+1 ACH=ABIN(I,JJ) ACH=ABIN(IP,JJ) JB=J-36*JJ IF ((LFIN(ACH,JB)) 1440,1435,1440 1435 NZL=NZL+1 1440 IF ((LFIN(ACH,JB)) 1450,1445,1450 1445 NZG=NZG+1 1450 CONTINUE 1460 IF (NZG-NZL) 1910,1910,1480 1480 ICYCL=ICYCL+1 CALL EXCH NCH=ISIR(I) ISIR(I)=ISIR(IP) IF (IIP) 1720,1430,1720 1630 IF ((IMAX(IP)-IP) 1650,1640,1650 1650 IMAX(IP)=IMAX(IP)-1 1650 IF ((IMAX(I)-I) 1670,1660,1670 1660 IMAX(I)=IMAX(I)+1 1670 IF ((MIN(I)-I) 1690,1680,1690 1690 IMIN(I)=IMIN(I)+1 1690 IF ((MIN(IP)-IP) 1720,1710,1720 1710 IMIN(IP)=IMIN(IP)-1 1720 NCH=IMAX(I) IMAX(I)=IMAX(IP) IMAX(IP)=NCH NCH=IMIN(I) IMIN(I)=IMIN(IP) IMIN(IP)=NCH DO 1900 J=MI,MX IF ((J-1) 1810,1900,1750 1750 IF ((MIN(J)-I) 1780,1760,1780 1760 JJ=J-1/36+1 ACH=ABIN(I,JJ) JB=J-36*(JJ-1) IF ((LFIN(ACH,JB)) 1900,1770,1900 1770 IMINI(J)=IMINI(J)+1 GO TO 1900 1780 IF ((MIN(J)-IP) 1900,1790,1900 1790 IMINI(J)=IMINI(J)-1 SD TO 1900 1810 IF ((IMAX(J)-I) 1830,1820,1830 1820 IMAX(J)=IMAX(J)+1 GO TO 1900 1830 IF ((IMAX(J)-IP) 1900,1840,1900 1840 JJ=J-1/36+1 ACH=ABIN(IP,JJ) JB=J-36*(JJ-1) IF ((LFIN(ACH,JB)) 1900,1850,1900 1850 IMAX(J)=IMAX(J)-1 1900 CONTINUE 1910 IF (MBO-NBO) 1960,1970,1970 1960 GO TO (1110,1120),NFP 1970 IF (MBO) 1100,1980,1100 1980 CONTINUE 1985 IF (INP-1) 2005,2005,1990 1990 CALL OUTPT 2005 CALL TICK (ITIM) CNT=ITIM CNT=(CNT-CRT)/60. WRITE OUTPUT TAPE 6,3,CNT,ICYCL,XSA DO 2100 I=1,NBO IP=I+1 IF ((IMAX(IP)-IMAX(I)) 2030,2100,2100 2030 IMAX(IP)=IMAX(I) 2100 CONTINUE IF ((ISURF-1) 3000,2300,2300 2300 PUNCH 1,(SIRI(I),IMAX(I),I=1,IN) 3000 RETURN 3100 WRITE OUTPUT TAPE 6,4,1 4 FORMAT (10H THE POINT,15,35H DOES NOT APPEAR IN MESH TOPOLOGY) GO TO 3000 END </pre>	<pre> FIARN148 FIARN149 FIARN150 FIARN151 FIARN152 FIARN153 FIARN154 FIARN155 FIARN156 FIARN157 FIARN158 FIARN159 FIARN160 FIARN161 FIARN162 FIARN163 FIARN164 FIARN165 FIARN166 FIARN167 FIARN168 FIARN169 FIARN170 FIARN171 FIARN172 FIARN173 FIARN174 FIARN175 FIARN176 FIARN177 FIARN178 FIARN179 FIARN180 FIARN181 FIARN182 FIARN183 FIARN184 FIARN185 FIARN186 FIARN187 FIARN188 FIARN189 FIARN190 FIARN191 FIARN192 FIARN193 FIARN194 FIARN195 FIARN196 FIARN197 FIARN198 FIARN199 FIARN200 FIARN201 FIARN202 FIARN203 FIARN204 FIARN205 FIARN206 FIARN207 FIARN208 FIARN209 FIARN210 FIARN211 FIARN212 FIARN213 FIARN214 FIARN215 FIARN216 FIARN217 FIARN218 FIARN219 FIARN220 FIARN221 FIARN222 FIARN223 FIARN224 FIARN225 FIARN226 FIARN227 FIARN228 FIARN229 FIARN230 FIARN231 FIARN232 FIARN233 FIARN234 FIARN235 FIARN236 FIARN237 FIARN238 FIARN239 FIARN240 FIARN241 FIARN242 FIARN243 FIARN244 FIARN245 FIARN246 FIARN247 FIARN248 FIARN249 FIARN250 FIARN251 FIARN252 FIARN253 FIARN254 FIARN255 FIARN256 FIARN257 FIARN258 FIARN259 FIARN260 FIARN261 FIARN262 </pre>
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Table VII-3. Source program listing of subroutine BUNG (Link 1)

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* LABEL
CEIBUNG
SUBROUTINE BUNG
C DUMMY SUBROUTINE FOR BOUNDARY CONDITION GENERATOR
RETURN
END
FIARN000
FIARN001
FIARN002
FIARN003
FIARN004

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**Table VII-4. Source program listing of subroutine COOR (Link 1)**

```

* LABEL
CEICOR SUBROUTINE COOR
      DIMENSION IA(11,AA(1)),REM(13),NT(10),DUMMY(5000),IDUM(5000),N(8)
      1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),RUMMY(27,9)
      2,DZ(12),S(1),G(1)
      COMMON IA,AA
      EQUIVALENCE (IA,AA),(AA,9000),DUMMY)
      EQUIVALENCE (DUMMY,IDUM,NT,RUMMY),(DUMMY(1),REM)
      EQUIVALENCE (IA(1),IN),(IA(2),IMN),(IA(3),IT),(IA(4),IP),(IA(5),
      1)PS),(IA(6),ITYPE),(IA(7),IMAF),(IA(8),IDEG),(IA(9),INX),(IA(10),EICOR00
      2)H),(IA(11),IB),(IA(12),IMMZ),(IA(13),IMMY),(IA(14),IMZ),(IA(15),EICOR01
      3)MFI),(IA(16),JARE),(IA(17),NI),(IA(18),P),(IA(19),IT),(IA(20),IT),EICOR02
      4)STR),(IA(21),IFL),(IA(22),ITM),(IA(23),ITC),(IA(24),ITC),(IA(25),ITC),
      5)IA(26),ISUM),(IA(27),IND),(IA(28),IMS),(IA(29),IUS),(IA(30),
      6)ORD),(IA(31),IORD),(IA(32),ACEL),(IA(33),J1),(IA(34),J2),
      7)IA(35),J3),(IA(36),J4),(IA(37),J5),(IA(38),J6),(IA(39),J7),(IA(40),J8),
      8),J8),(IA(41),J9),(IA(42),J10),(IA(43),J11),(IA(44),J12),(IA(45),J13),
      9)IA(46),J14),(IA(47),J15),(IA(48),J16),(IA(49),J17),(IA(50),J18),
      EQUIVALENCE (IA(66),ICAR),(IA(67),ICF),(IA(68),ICV),(IA(69),
      1)ICF),(IA(70),ICF),(IA(71),IX),(IA(72),IY),(IA(73),IZ),
      2)IA(74),IIC),(IA(75),IDF),(IA(76),IST),(IA(77),IIS)
      3),(IA(78),IRFM),(IA(79),IRK),(IA(80),IR),(IA(81),IR),(IA(82),OG),
      4)AA(83),ALL),(AA(84),AL2),(AA(85),AL3),(AA(86),O21),(AA(87),O),
      5)AA(88),OV),(AA(89),X),(AA(90),Y),(AA(91),Z),(AA(92),XD),
      6)AA(93),YD),(AA(94),ZD),(AA(95),S),(AA(96),G)
      7)AA(97),INP),(AA(98),IPBG),(AA(99),IPFN),(AA(100),CONS),(AA(101),
      8),(AA(102),G1),(AA(103),G2),(AA(104),G3)
      EQUIVALENCE (IA(349),NTIC),(IA(349),ISD),(IA(349),ISPY),(IA(349),
      1)ISD),(IA(349),J),(IA(349),J),(IA(349),JPRS),(IA(349),JSDY)
      2),(IA(349),JSDY),(IA(349),JARE),(IA(349),JMM),(IA(349),JMMY)
      3),(IA(349),JMM),(IA(349),JMM),(IA(349),ITAS),(IA(349),IT7)
      4),(IA(349),IPR),(AA(349),UGY),(AA(349),OG2),(AA(349),PREF)
      5),(IA(349),IPR)
      IARR=0
      LE0
      831 INTE=INT(L-1)/2
      INTE=2*(INTE+1)
      IF (INT(-10001/833,833,832)
      832 INTE=1000
      833 READ INPUT TAPE 5,102,(IDUM(1),DUMMY(1+1000),DUMMY(1+2000),DUMMY
      1)I+3000),I-1,-1,INTE)
      102 FORMAT (2I14,3E12.7)
      I=0
      8314 I=I+1
      IF (I-INTE) 8315,8315,831
      8315 IF (IDUM(I)) 300,8314,8314
      8316 IF (DUMMY(I)-L-1) 300,1061,300
      1061 I=I+1
      IXXL=IX+L
      IYYL=IY+L
      IZZL=IZ+L
      AA(IXL)=DUMMY(I+1000)
      AA(IYL)=DUMMY(I+2000)
      1063 IF (IGEM-1) 1062,1063,300
      1062 IF (L=IN) 8314,8314,300
      5850 RETURN
      300 IERR=1
      GO TO 5850
      END
  
```

**Table VII-5. Source program listing of subroutine CORG (Link 1)**

```

* LABEL
CEICORG SUBROUTINE CORG
      DUMMY SUBROUTINE FOR COORDINATE GENERATOR
      RETURN
      END
  
```

```

      1)COR000
      2)COR001
      3)COR002
      4)COR003
      5)COR004
      6)COR005
      7)COR006
      8)COR007
      9)COR008
      10)COR009
      11)COR010
      12)COR011
      13)COR012
      14)COR013
      15)COR014
      16)COR015
      17)COR016
      18)COR017
      19)COR018
      20)COR019
      21)COR020
      22)COR021
      23)COR022
      24)COR023
      25)COR024
      26)COR025
      27)COR026
      28)COR027
      29)COR028
      30)COR029
      31)COR030
      32)COR031
      33)COR032
      34)COR033
      35)COR034
      36)COR035
      37)COR036
      38)COR037
      39)COR038
      40)COR039
      41)COR040
      42)COR041
      43)COR042
      44)COR043
      45)COR044
      46)COR045
      47)COR046
      48)COR047
      49)COR048
      50)COR049
      51)COR050
      52)COR051
      53)COR052
      54)COR053
      55)COR054
      56)COR055
      57)COR056
      58)COR057
      59)COR058
      60)COR059
      61)COR060
  
```

**Table VII-6. Source program listing of subroutine EXCH (Link 1)**

```

* LABEL
CEIEXC SUBROUTINE EXCH
      INTERCHANGES CONSECUTIVE ROWS AND COLUMNS OF CONNECTIVITY MATRIX
      COMMON AA
      EQUIVALENCE (AA,9000),ARIN)
      EQUIVALENCE (AA(302),MT),(AA(303),MX),(AA(304),I),(AA(305),IP)
      DIMENSION ARIN(40,15)
      JMI=(MI-1)/36+1
      JMX=(MX-1)/36+1
      OJ=100-KMI,JMX
      ACH=ARIN(I,K)
      ARIN(I,K)=ARIN(IP,K)
      100 ARIN(IP,K)=ACH
      J=I-1/36+1
      JB=(J-1)/36+1
      JP=(J-1)/36+1
      JPB=JP-36*(JP-1)
      IF (J-JP) 150,250,150
      150 DO 200 K=MI,MX
      ACH=ARIN(K,J)
      BCH=ARIN(K,JP)
      NCH=LEBIN(ACH,JB)
      NCT=LEBIN(BCH,JPB)
      CALL SEBIN (ACH,JB,NCT)
      CALL SEBIN (BCH,JPB,NCH)
      ARIN(K,J)=ACH
      200 ARIN(K,JP)=BCH
      GO TO 400
      250 DO 300 K=MI,MX
      ACH=ARIN(K,J)
      NCH=LEBIN(ACH,JB)
      NCT=LEBIN(ACH,JPB)
      CALL SEBIN (ACH,JB,NCT)
      CALL SEBIN (BCH,JPB,NCH)
      300 ARIN(K,J)=ACH
      400 RETURN
      END
  
```

**Table VII-7. Source program listing of function LEBIN and subroutine SEBIN (Link 1)**

```

* FAP
COUNT 100
LEBL CLEED
REW
* THIS SUBPROGRAM IS CALLED USING FORTRAN 'SUBROUTINE' CONVENTIONS.
* CALLING SEQUENCE IS...
* CALL SEBIN(A,I,N)
* WHERE 'A' IS THE NAME OF A WORD (VARIABLE).
* 'I' IS THE INTEGER SPECIFYING DESIRED BIT (1-36) IN 'A'.
* 'N' IS A FORTRAN INTEGER ONE OR ZERO INDICATING THE NEW
* VALUE OF THE I' TH BIT OF 'A'.
      REM
      ENTRY SEBIN
      ENTRY LEBIN
      REM
      EVEN
      NAC
      SFBIN EQU *
      STJ INDKR SAVE INDICATORS
      SXA SAVX1,1 AND XR1
      LDI* 1,4 RESET
      CLAP* 2,4
      PDC *
      ZETP 3,4 DO WE SET OR RESET
      TRA SET SET
      RIS TABLE,1 RESET
      TRA EXIT
      SET OSI TABLE,1
      EXIT STI* 1,4
      SAVX1 AXI **,-1
      LDI INDKTR
      TRA 4,4
      REM
      INDKTR PZE **
      TABLE PZE 0
      DEC 1B1,1B2,1B3,1B4,1B5,1B6,1B7,1B8,1B9,1B10,1B11,1B12
      DEC 1B13,1B14,1B15,1B16,1B17,1B18,1B19,1B20,1B21,1B22
      DEC 1B23,1B24,1B25,1B26,1B27,1B28,1B29,1B30,1B31,1B32
      DEC 1B33,1B34,1B35
      SPACE 4
      * A FUNCTION SUBPROGRAM...
      * CALLING SEQUENCE 'X=LEBIN(A,I)'
      * WHERE 'A' IS THE NAME OF A VARIABLE
      * 'I' IS A FORTRAN INTEGER SPECIFYING THE DESIRED BIT IN 'A'.
      * ON RETURN THE CALLER THE AC CONTAINS A FORTRAN INTEGER
      * ONE OR ZERO DEPENDING ON WHETHER I' TH BIT OF 'A' IS
      * ONE OR ZERO.
      REM
      LEBIN EQU *
      SXA LEBX1,1
      CAL* 2,4 THIS BIT
      PDC *
      CAL* 1,4
      ANA TABLE,1
      TZE LEBX1
      CAL ONE
      LEBX1 AXI **,-1
      TRA 3,4
      RFM
      ONE PZE **,-1 A FORTRAN I I 1
      END
  
```

Table VII-8. Source program listing of subroutine MESHG (Link 1)

```

* LABEL
CEIMFS SUBROUTINE MESHG
C DUMMY SUBROUTINE FOR MESH GENERATOR
RETURN
END
FIMFS000
FIMFS001
FIMFS002
FIMFS003
FIMFS004
FIMFS005
FIMFS006
FIMFS007
FIMFS008
FIMFS009
FIMFS010
FIMFS011
FIMFS012
FIMFS013
FIMFS014
FIMFS015
FIMFS016
FIMFS017
FIMFS018
FIMFS019
FIMFS020
FIMFS021
FIMFS022
FIMFS023
FIMFS024
FIMFS025
FIMFS026
FIMFS027
FIMFS028
FIMFS029
FIMFS030
FIMFS031
FIMFS032
FIMFS033
FIMFS034
FIMFS035
FIMFS036
FIMFS037
FIMFS038
FIMFS039
FIMFS040
FIMFS041
FIMFS042
FIMFS043
FIMFS044
FIMFS045
FIMFS046
FIMFS047
FIMFS048
FIMFS049
FIMFS050
FIMFS051
FIMFS052
FIMFS053
FIMFS054
FIMFS055
FIMFS056
FIMFS057
FIMFS058
FIMFS059
FIMFS060
FIMFS061
FIMFS062
FIMFS063
FIMFS064

```

Table VII-9. Source program listing of subroutine MEST (Link 1)

```

* LABEL
CEIMFS SUBROUTINE MEST
C READS AND STORES MESH TOPOLOGY DATA
DIMENSION IA(1),AA(1),REM(13),NT(10),DUMMY(5000),IDUM(5000),N(8)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YE(7),ZD(7),RUMMY(27,9)
2,D(21),S(1),G(1)
COMMON JA,AA
EQUIVALENCE (IA,AA),(AA(9000),DUMMY)
EQUIVALENCE (DUMMY,IDUM,NT,RUMMY),(DUMMY(1),REM)
EQUIVALENCE (IA(1),IN),(IA(2),IHN),(IA(3),IT),(IA(4),IPI),(IA(5),
1,IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),FIM
2,HI),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMM2),(IA(15),FIM
3,MFI),(IA(16),IARE),(IA(17),NLI),(IA(18),M1),(IA(19),ITP),(IA(20),
4,ISTR),(IA(21),IFL1),(IA(22),IFPM),(IA(23),ITIC),(IA(24),IMF1),
5,(IA(25),ISUM),(IA(26),IND),(IA(27),IMS),(IA(28),IDS),(IA(29),
6,IRRH),(IA(30),IDRD),(IA(31),ACEL),(IA(32),J1),(IA(33),J2),
7,(IA(34),J3),(IA(35),J4),(IA(36),J5),(IA(37),J6),(IA(38),J7),(IA(39),
8),J8),(IA(40),JTY),(IA(41),IRB),(IA(42),IRO),(IA(43),IIO),(IA(44),
9,IA),(IA(45),IDT),(IA(46),IDY),(IA(47),ITE),(IA(48),ITAP)
EQUIVALENCE (IA(49),ICAR),(IA(50),ICR),(IA(51),ICIS),(IA(52),ICTY),(IA(53),
1,ICIZ),(IA(54),ICFI),(IA(55),ICX),(IA(56),IY),(IA(57),IZ),
2,(IA(58),IC1),(IA(59),ICF1),(IA(60),IST),(IA(61),IS)
3,(IA(62),IGFM),(IA(63),IGFR),(IA(64),IGT),(IA(65),IGT1),(IA(66),IGT2),
4,(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),B21),(AA(87),P),
5,(AA(131),UV1),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),
6,(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM)
7,(AA(42),INP),(AA(43),IPBS),(AA(44),IPFN),(AA(45),CONS),(AA(46),I
8),(IA(47),G1),(AA(48),G2),(AA(49),G3)
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346),
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)
3,(IA(337),JMM2),(IA(336),JMF1),(IA(335),JIAS),(IA(334),IDZ)
4,(IA(333),IPR),(AA(332),OGY),(AA(331),DG2),(AA(330),PRFS)
5,(IA(329),IPIR)
ERR=0
M=0
MT=0
L=0
NRE=19
NF=0
7910 C=1
7911 IF (L=NF) 7912,7912,7913
7913 NRE=NRE+20
NF=NF+20
7914 READ INPUT TAPE 5,7911,(IDUM(1),I=NRE,NF)
7915 FORMAT (20I4)
7912 IF (IDUM(1)) 7921,7910,7924
7921 IF (L=NF) 7914,7912,7913
7924 IF (L=ERR) 300,300,7925
7925 L=L-1
MT=1
ERR=0
7914 M=M+1
MT=1
IF (MT=999) 7916,7915,300
7915 ERR=1
7916 IF (M+IDUM(L)) 300,7917,300
7917 I=LT=IDUM(L+1)/100
IF (I=LT+I=LT-19) 7918,300,300
7918 GO TO (81,82,81,83,84,85,84,85,86,87,84,85,84,85,84,85,81,81),I,IFL
81 JK=5
JN=2
GO TO 89
82 JK=6
JN=2
FIMFS000
FIMFS001
FIMFS002
FIMFS003
FIMFS004
FIMFS005
FIMFS006
FIMFS007
FIMFS008
FIMFS009
FIMFS010
FIMFS011
FIMFS012
FIMFS013
FIMFS014
FIMFS015
FIMFS016
FIMFS017
FIMFS018
FIMFS019
FIMFS020
FIMFS021
FIMFS022
FIMFS023
FIMFS024
FIMFS025
FIMFS026
FIMFS027
FIMFS028
FIMFS029
FIMFS030
FIMFS031
FIMFS032
FIMFS033
FIMFS034
FIMFS035
FIMFS036
FIMFS037
FIMFS038
FIMFS039
FIMFS040
FIMFS041
FIMFS042
FIMFS043
FIMFS044
FIMFS045
FIMFS046
FIMFS047
FIMFS048
FIMFS049
FIMFS050
FIMFS051
FIMFS052
FIMFS053
FIMFS054
FIMFS055
FIMFS056
FIMFS057
FIMFS058
FIMFS059
FIMFS060
FIMFS061
FIMFS062
FIMFS063
FIMFS064

```

Table VII-10. Source program listing of subroutine OUTPT (Link 1)

```

* LABEL
CEIOUTP SUBROUTINE OUTPT
C WRITES INFORMATION RELATED WITH REMELLING
DIMENSION IA(1),AA(1),REM(13),NT(10),DUMMY(5000),IDUM(5000),N(8)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YE(7),ZD(7),RUMMY(27,9)
2,D(21),S(1),G(1)
COMMON JA,AA
EQUIVALENCE (IA,AA),(AA(9000),DUMMY)
EQUIVALENCE (DUMMY,IDUM,NT,RUMMY),(DUMMY(1),REM)
EQUIVALENCE (IA(1),IN),(IA(2),IHN),(IA(3),IT),(IA(4),IPI),(IA(5),
1,IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),FIM
2,HI),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMM2),(IA(15),FIM
3,MFI),(IA(16),IARE),(IA(17),NLI),(IA(18),M1),(IA(19),ITP),(IA(20),
4,ISTR),(IA(21),IFL1),(IA(22),IFPM),(IA(23),ITIC),(IA(24),IMF1),
5,(IA(25),ISUM),(IA(26),IND),(IA(27),IMS),(IA(28),IDS),(IA(29),
6,IRRH),(IA(30),IDRD),(IA(31),ACEL),(IA(32),J1),(IA(33),J2),
7,(IA(34),J3),(IA(35),J4),(IA(36),J5),(IA(37),J6),(IA(38),J7),(IA(39),
8),J8),(IA(40),JTY),(IA(41),IRB),(IA(42),IRO),(IA(43),IIO),(IA(44),
9,IA),(IA(45),IDT),(IA(46),IDY),(IA(47),ITE),(IA(48),ITAP)
EQUIVALENCE (IA(49),ICAR),(IA(50),ICR),(IA(51),ICIS),(IA(52),ICTY),(IA(53),
1,ICIZ),(IA(54),ICFI),(IA(55),ICX),(IA(56),IY),(IA(57),IZ),
2,(IA(58),IC1),(IA(59),ICF1),(IA(60),IST),(IA(61),IS)
3,(IA(62),IGFM),(IA(63),IGFR),(IA(64),IGT),(IA(65),IGT1),(IA(66),IGT2),
4,(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),B21),(AA(87),P),
5,(AA(131),UV1),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),
6,(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM)
7,(AA(42),INP),(AA(43),IPBS),(AA(44),IPFN),(AA(45),CONS),(AA(46),I
8),(IA(47),G1),(AA(48),G2),(AA(49),G3)
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346),
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)
3,(IA(337),JMM2),(IA(336),JMF1),(IA(335),JIAS),(IA(334),IDZ)
4,(IA(333),IPR),(AA(332),OGY),(AA(331),DG2),(AA(330),PRFS)
5,(IA(329),IPIR)
ERR=0
M=0
MT=0
L=0
NRE=19
NF=0
7910 C=1
7911 IF (L=NF) 7912,7912,7913
7913 NRE=NRE+20
NF=NF+20
7914 READ INPUT TAPE 5,7911,(IDUM(1),I=NRE,NF)
7915 FORMAT (20I4)
7912 IF (IDUM(1)) 7921,7910,7924
7921 IF (L=NF) 7914,7912,7913
7924 IF (L=ERR) 300,300,7925
7925 L=L-1
MT=1
ERR=0
7914 M=M+1
MT=1
IF (MT=999) 7916,7915,300
7915 ERR=1
7916 IF (M+IDUM(L)) 300,7917,300
7917 I=LT=IDUM(L+1)/100
IF (I=LT+I=LT-19) 7918,300,300
7918 GO TO (81,82,81,83,84,85,84,85,86,87,84,85,84,85,84,85,81,81),I,IFL
81 JK=5
JN=2
GO TO 89
82 JK=6
JN=2
FIMFS000
FIMFS001
FIMFS002
FIMFS003
FIMFS004
FIMFS005
FIMFS006
FIMFS007
FIMFS008
FIMFS009
FIMFS010
FIMFS011
FIMFS012
FIMFS013
FIMFS014
FIMFS015
FIMFS016
FIMFS017
FIMFS018
FIMFS019
FIMFS020
FIMFS021
FIMFS022
FIMFS023
FIMFS024
FIMFS025
FIMFS026
FIMFS027
FIMFS028
FIMFS029
FIMFS030
FIMFS031
FIMFS032
FIMFS033
FIMFS034
FIMFS035
FIMFS036
FIMFS037
FIMFS038
FIMFS039
FIMFS040
FIMFS041
FIMFS042
FIMFS043
FIMFS044
FIMFS045
FIMFS046
FIMFS047
FIMFS048
FIMFS049
FIMFS050
FIMFS051
FIMFS052
FIMFS053
FIMFS054
FIMFS055
FIMFS056
FIMFS057
FIMFS058
FIMFS059
FIMFS060
FIMFS061
FIMFS062
FIMFS063
FIMFS064

```

Table VII-11. Source program listing of subroutine SRAT (Link 1)

```

* LABEL
CF15RT
C SUPROUTINE SRAT F1SR1000 KN=0 F1SR1064
GENERATES CONNECTIVITY MATRIX AND PRECISES TOPOLOGY OF STIFF.MAT. F1SR1001 F1SR1065
DIMENSION I(A(1),JA(1)),RE(1:15),N(1:15),DUMMY(15*10),IDUM(15*10),N(8) F1SR1002 F1SR1066
1:PE(24),UV(24),X(8),Y(8),Z(8),X(7),Y(7),Z(7),RUMMY(27*9) F1SR1003 F1SR1067
2:OZ(12),S(11),G(11) F1SR1004 F1SR1068
COMMON IA,AA F1SR1005 9711 KN=KN+1 F1SR1069
EQUIVALENCE (IA,AA),(AA,9000),DUMMY) F1SR1006 971 CONTINUE F1SR1070
EQUIVALENCE (DUMMY,IDUM,NT,RUMMY),(DUMMY(11),RE) F1SR1007 F1SR1071
EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), F1SR1008 F1SR1072
1PR5),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),IMS),(IA(10), F1SR1009 F1SR1073
2EN),(IA(11),I8),(IA(12),IMX),(IA(13),IMMY),(IA(14),IMW2),(IA(15),F1SR1010 F1SR1074
3MF1),(IA(16),IAR5),(IA(17),N1),(IA(18),M),(IA(19),IY),(IA(20),F1SR1011 F1SR1075
4ISTR),(IA(21),IEL1),(IA(22),ITEM),(IA(23),ITIC),(IA(24),IYF1), F1SR1012 F1SR1076
5IA(25),ISUM),(IA(26),IND),(IA(27),IMS),(IA(28),I5),(IA(29), F1SR1013 F1SR1077
6TORO),(IA(30),IORD1),(IA(31),ACSL),(IA(32),J1),(IA(33),J2), F1SR1014 F1SR1078
7IA(34),J3),(IA(35),J4),(IA(36),J5),(IA(37),J6),(IA(38),J7),(IA(39),F1SR1015 F1SR1079
8),J8),(IA(40),J9),(IA(41),J10),(IA(42),J11),(IA(43),J12),(IA(44),F1SR1016 F1SR1080
9IA(45),J13),(IA(46),J14),(IA(47),J15),(IA(48),J16),(IA(49),J17),(IA(50),F1SR1017 F1SR1081
EQUIVALENCE (IA(66),ICAR),(IA(67),ICTX),(IA(68),IC1),(IA(69), F1SR1018 F1SR1082
1IC1Z),(IA(70),ICF1),(IA(71),IXX),(IA(72),IYV),(IA(73),IZZ), F1SR1019 F1SR1083
2IA(74),IC),(IA(75),IDF1),(IA(76),IST),(IA(77),IIS) F1SR1020 F1SR1084
3IA(78),IGF),(IA(79),IFRR),(IA(80),IF),(IA(81),DT),(IA(82),DG), F1SR1021 F1SR1085
4IA(83),AL1),(IA(84),AL2),(IA(85),AL3),(IA(86),AL4),(IA(87),AL5), F1SR1022 F1SR1086
5IA(88),AL6),(IA(89),AL7),(IA(90),AL8),(IA(91),AL9),(IA(92),AL10), F1SR1023 F1SR1087
6IA(93),AL11),(IA(94),AL12),(IA(95),AL13),(IA(96),AL14),(IA(97),AL15), F1SR1024 F1SR1088
7IA(98),AL16),(IA(99),AL17),(IA(100),AL18),(IA(101),AL19),(IA(102), F1SR1025 F1SR1089
8IA(103),AL20),(IA(104),AL21),(IA(105),AL22),(IA(106),AL23),(IA(107), F1SR1026 F1SR1090
9IA(108),AL24),(IA(109),AL25),(IA(110),AL26),(IA(111),AL27),(IA(112), F1SR1027 F1SR1091
EQUIVALENCE (IA(349),NTIC),(IA(350),ISOT),(IA(351),ISY),(IA(352), F1SR1028 F1SR1092
1ISD1),(IA(353),J9),(IA(354),J10),(IA(355),J11),(IA(356),J12),(IA(357),J13), F1SR1029 F1SR1093
2IA(358),J14),(IA(359),J15),(IA(360),J16),(IA(361),J17),(IA(362),J18), F1SR1030 F1SR1094
3IA(363),J19),(IA(364),J20),(IA(365),J21),(IA(366),J22),(IA(367),J23), F1SR1031 F1SR1095
4IA(368),J24),(IA(369),J25),(IA(370),J26),(IA(371),J27),(IA(372),J28), F1SR1032 F1SR1096
5IA(373),J29),(IA(374),J30),(IA(375),J31),(IA(376),J32),(IA(377),J33), F1SR1033 F1SR1097
6IA(378),J34),(IA(379),J35),(IA(380),J36),(IA(381),J37),(IA(382),J38), F1SR1034 F1SR1098
7IA(383),J39),(IA(384),J40),(IA(385),J41),(IA(386),J42),(IA(387),J43), F1SR1035 F1SR1099
8IA(388),J44),(IA(389),J45),(IA(390),J46),(IA(391),J47),(IA(392),J48), F1SR1036 F1SR1100
9IA(393),J49),(IA(394),J50),(IA(395),J51),(IA(396),J52),(IA(397),J53), F1SR1037 F1SR1101
DIMENSION IBS(25),CCC(125),JRS(25),CCC(25) F1SR1038 F1SR1102
EQUIVALENCE (IA(201),IRS),(IA(225),JRS),(AA(250),CCC), F1SR1039 F1SR1103
1AA(275),CCC) F1SR1040 F1SR1104
EQUIVALENCE (IA(135),ISHUF),(IA(301),ISUP) F1SR1041 F1SR1105
EQUIVALENCE (ABIN,IBAND),(ABIN,IBAND) F1SR1042 F1SR1106
DIMENSION IROC(800),IRAND(800),ISIR(1),IMAX(1),IMIN(800), F1SR1043 F1SR1107
1ABIN(800),IS) F1SR1044 F1SR1108
EQUIVALENCE (DUMMY,ABIN),(DUMMY(3700),ISIR),(DUMMY(8000),IMAX), F1SR1045 F1SR1109
1IDUMMY(9180),IMIN) F1SR1046 F1SR1110
IF ISHUF=2) 25,25,23 F1SR1047 F1SR1111
23 READ INPUT TAPE 5,100,ISIR(1),IMAX(1),IMIN(1) F1SR1048 F1SR1112
100 FORMAT (20I4) F1SR1049 F1SR1113
GO TO 1100 F1SR1050 F1SR1114
25 DO 22 I=1,IN F1SR1051 F1SR1115
22 ISIR(I)=1 F1SR1052 F1SR1116
ISUR=(IN-1)/26+1 F1SR1053 F1SR1117
DO 71 I=1,IN F1SR1054 F1SR1118
DO 71 J=1,ISUR F1SR1055 F1SR1119
71 ABIN(I,J)=0 F1SR1056 F1SR1120
DO 99 M=1,IT F1SR1057 F1SR1121
CALL TOP0 F1SR1058 F1SR1122
DO 98 I=1,1H F1SR1059 F1SR1123
L=IH+I F1SR1060 F1SR1124
IF IA(L) 98,98,97 F1SR1061 F1SR1125
98 CONTINUE F1SR1062 F1SR1126
1 WRITE OUTPUT TAPE 6,111,M F1SR1063 F1SR1127
111 FORMAT (8H ELEMENT,14,2X,29H IS UNACCEPTABLE. DISREGARDED.) F1SR1064 F1SR1128
DO 97 F1SR1065 F1SR1129
97 IM=1 F1SR1066 F1SR1130
THIS CARD (E1SR61A0) IS IMMEDIATELY AFTER CARD E1SR1061. F1SR1067 F1SR1131
EXPAND ELEMENT VECTOR, BY MULTIPLE DRG INPUT UNITS, IN IMX F1SR1068 F1SR1132
L=0 F1SR1069 F1SR1133
DO 300 I=1,IMS F1SR1070 F1SR1134
L=L+1 F1SR1071 F1SR1135
IMAX(L)=N(1) F1SR1072 F1SR1136
KN=(N(1)-1)*IDEG+190 F1SR1073 F1SR1137
DO 301 J=1,IDEG F1SR1074 F1SR1138
IROL=KN+J F1SR1075 F1SR1139
IF (IA(IROL)-10000) 301,302,307 F1SR1076 F1SR1140
302 KM=10000+IROL-180 F1SR1077 F1SR1141
IROL=180 F1SR1078 F1SR1142
DO 303 K=1,IND F1SR1079 F1SR1143
IROL=IROL+K F1SR1080 F1SR1144
IF (IA(IROL)+KM) 303,304,303 F1SR1081 F1SR1145
304 L=L+1 F1SR1082 F1SR1146
IMAX(L)=(K-1)/IDEG+1 F1SR1083 F1SR1147
303 CONTINUE F1SR1084 F1SR1148
301 CONTINUE F1SR1085 F1SR1149
300 CONTINUE F1SR1086 F1SR1150
IM<=1 F1SR1087 F1SR1151
DO 306 I=2,L F1SR1088 F1SR1152
KN=IMAX(I) F1SR1089 F1SR1153
DO 307 J=1,IMS F1SR1090 F1SR1154
IF (IMAX(J)-KN) 307,306,307 F1SR1091 F1SR1155
307 CONTINUE F1SR1092 F1SR1156
IM<=IMS+1 F1SR1093 F1SR1157
IMAX(I)=KN F1SR1094 F1SR1158
CONTINUE F1SR1095 F1SR1159
THIS CARD (E1SR61C9) IS IMMEDIATELY BEFORE CARD E1SR162. F1SR1096 F1SR1160
DO 95 I=1,IMS F1SR1097 F1SR1161
IA=IMAX(I) F1SR1098 F1SR1162
E1SR1063 F1SR1063 KN=0 F1SR1064
IROL=IB-1)*IDEG+190 F1SR1065
DO 971 J=1,IDEG F1SR1066
IROL=IROL+J F1SR1067
IF (IA(IROL)) 972,9711,9711 F1SR1068
9711 KN=KN+1 F1SR1069
971 CONTINUE F1SR1070
972 DO 94 J=1,IMS F1SR1071
IF (KN-IDEG) 942,941,942 F1SR1072
941 IF (I-J) 95,942,94 F1SR1073
942 JB=IMAX(J) F1SR1074
KN=0 F1SR1075
IROL=JB-1)*IDEG+190 F1SR1076
DO 981 I=1,IDEG F1SR1077
IROL=IROL+I F1SR1078
IF (IA(IROL)) 982,9811,9811 F1SR1079
9811 KN=KN+1 F1SR1080
981 CONTINUE F1SR1081
IF (KN-IDEG) 982,983,982 F1SR1082
983 IF (I-J) 94,982,94 F1SR1083
982 JJ=JB-1)/26+1 F1SR1084
ACH=ARIN(18+JJ) F1SR1085
JB=I+JJ F1SR1086
CALL SEBIN (ACH,JB,IT,1) F1SR1087
ABIN(I,J)=ACH F1SR1088
94 CONTINUE F1SR1089
95 CONTINUE F1SR1090
99 CONTINUE F1SR1091
CALL ARAN F1SR1092
IMAX=IMAX(1) F1SR1093
IMAX=1 F1SR1094
KN=0 F1SR1095
L BAND=0 F1SR1096
LIPD=0 F1SR1097
DO 2300 I=1,IN F1SR1098
IMAX=IMAX(1)+IDEG F1SR1099
IF (IMAX-IMAXN) 1940,1940,2105 F1SR1100
1940 DO 2100 J=IMAXB+IMAXN F1SR1101
IPOJ=ICD-IDEG+I+IR(J)-1 F1SR1102
DO 2100 K=1,IDEG F1SR1103
IPOK=IPOJ+K F1SR1104
IF (IA(IPOK)) 2000,1950,1950 F1SR1105
1950 KN=KN+1 F1SR1106
2000 CONTINUE F1SR1107
2100 CONTINUE F1SR1108
2105 IMAXN=IMAX(I+1) F1SR1109
IMAXB=IMAX(I)+1 F1SR1110
ILOB=(ISIR(I)-1)*IDEG+IPO F1SR1111
DO 2200 J=1,IDEG F1SR1112
IROL=ILOB+J F1SR1113
IF (IA(IROL)) 2110,2200,2200 F1SR1114
2110 L BAND=L BAND+1 F1SR1115
IBAND(L BAND)=IMAXB-L BAND-KN+1 F1SR1116
2200 CONTINUE F1SR1117
2300 CONTINUE F1SR1118
ISUM=L BAND F1SR1119
IF (I=0) 812,811,811 F1SR1120
811 WRITE OUTPUT TAPE 6,415 (I,IBAND(I),I),ISUM) F1SR1121
415 FORMAT (1H,13X,40HTOPOLOGY OF THE REDUCED STIFFNESS MATRIX////1TE1SR122
1X,85HNUMBER OF ELEMENTS RETAINED AT EACH ROW OF UPPER STIFFNESS MAE1SR123
2TRIX (DIAGONAL INCLUDED)////11014X,14,1X,1311) F1SR124
812 IUI=IU+1 F1SR125
IA(IUI)=I F1SR126
ISUM=ISUM+1 F1SR127
DO 416 I=2,ISUM) F1SR128
IUI=IU+I F1SR129
IA(IUI)=IA(IUI)-1+IBAND(I-1) F1SR130
IORD=IA(IUI)-1 F1SR131
FORD=0 F1SR132
DO 417 I=1,ISUM F1SR133
FKX=IBAND(I) F1SR134
FORD=FORD+FKX F1SR135
IST=IU+ISUM) F1SR136
FKT=IST F1SR137
FISUM=ISUM F1SR138
FILF4=FKT+FORD+FTSUM+1 F1SR139
IORD=IORD+1 F1SR140
WRITE OUTPUT TAPE 6,6664,FORD,FILFN F1SR141
6664 FORMAT (1X,35HSTIFFNESS MATRIX REQUIRES (DECIMAL),F6.0,19H F1SR142
1STORAGE LOCATIONS,1X,32HTOTAL COMMON LENGTH IS (DECIMAL),F9.0,19H) F1SR143
2 STORAGE LOCATIONS) F1SR144
IF (I9810.-FILEN+ISUM) 419,420,420 F1SR145
419 WRITE OUTPUT TAPE 8,421 F1SR146
4211 FORMAT (1X,63HWARNING, LESS THAN 12750 DECIMAL LOCATION IS AVF1SR147
1LABLE FOR THE NEXT LINK PROGRAM, 75X,47HTHOUGH IT MAY BE SUFFIC1SR148
2L, EXECUTION CONTINUES.) F1SR149
420 IF (INP-1) 813,814,814 F1SR150
814 DO 421 I=1,ISUM) F1SR151
IUI=IU+I F1SR152
421 IBAND(I)=IA(IUI) F1SR153
WRITE OUTPUT TAPE 6,422, (I,IBAND(I),I),ISUM) F1SR154
422 FORMAT (1H,30X,62HCOUNT OF MAIN DIAGONAL ELEMENTS OF ROW LISTED 6E1SR155
1TIFNESS MATRIX////1102X,14,1X,1511) F1SR156
813 RETURN F1SR157
END F1SR158

```

**Table VII-12. Source program listing of subroutine TABL (Link 1)**

```

* LABEL
CENTRAL SUBROUTINE TABL F1TRLO00
C PRINTS FIRST OUTPUT ITEM F1TRLO01
DIMENSION I4(1),AA(1),RFM(13),NT(10),DUMMY(5000),IDUM(5000),N(8) F1TRLO02
1,P(24),UV(24),X(8),Y(8),Z(8),XO(7),YO(7),ZO(7),RUMMY(27,9) F1TRLO03
2,D2(12),S(1),G(1) F1TRLO04
COMMON I4,AA F1TRLO05
EQUIVALENCE (I4,AA),(AA,9000),DUMMY) F1TRLO06
EQUIVALENCE (DUMMY,TDUM,NT,RUMMY),(DUMMY(11),RFM) F1TRLO07
EQUIVALENCE (I4(1),IN),(I4(2),JN),(I4(3),IT),(I4(4),IP),(I4(5), F1TRLO09
1PRS),(I4(6),ITYPE),(I4(7),IMAT),(I4(8),IDEG),(I4(9),INX),(I4(10),F1TRLO10
2IH),(I4(11),IR),(I4(12),IMM),(I4(13),IMMY),(I4(14),I1),(I4(15),F1TRLO11
3IMP),(I4(16),IARE),(I4(17),A(1)),(I4(18),M),(I4(19),IY),(I4(20),F1TRLO12
4ISTR),(I4(21),IFLT),(I4(22),IFRM),(I4(30),ITIC),(I4(31),IMFT) F1TRLO13
5IA(192),ISUM,(I4(33),IND),(I4(34),IMS),(I4(35),IOS),(I4(37), F1TRLO14
6IORD),(I4(39),IORD1),(I4(34),ACFL),(I4(40),J1),(I4(51),J2) F1TRLO15
7IA(192),J3,(I4(53),J4),(I4(54),J5),(I4(55),J6),(I4(56),J7),(I4(57),F1TRLO16
8J),(I4(58),JTY),(I4(59),J8),(I4(60),I80),(I4(61),I81),(I4(62),F1TRLO17
9IAT),(I4(63),I8T),(I4(64),I8Y),(I4(65),I8E),(I4(61),I8P) F1TRLO18
EQUIVALENCE (I4(66),ICAR),(I4(67),ICIX),(I4(68),ICFY),(I4(69), F1TRLO19
1ICIZ),(I4(70),ICFI),(I4(71),ICX),(I4(72),ICY),(I4(73),ICZ) F1TRLO20
2IA(174),IIC,(I4(75),IDH),(I4(76),IS),(I4(77),IIS) F1TRLO21
3IA(178),IDEM,(I4(79),IDEX),(I4(80),IDF),(I4(81),IDT),(I4(82),IDG) F1TRLO22
4IA(183),ALI,(I4(84),AL2),(I4(85),AL3),(I4(86),D1),(I4(107),P1) F1TRLO23
5AA(131),UV,(I4(155),X),(I4(163),Y),(I4(171),Z),(I4(179),XD) F1TRLO24
6AA(186),YD,(I4(193),Z),(I4(351),S),(I4(401),ZGFM) F1TRLO25
7IA(142),IMP,(I4(43),IPRG),(I4(44),IPEN),(I4(45),CONS),(I4(46),I1) F1TRLO26
8IA(147),G1,(I4(48),G2),(I4(49),G3) F1TRLO27
EQUIVALENCE (I4(349),NTIC),(I4(349),ISD),(I4(347),ISDY),(I4(346) F1TRLO28
1,ISD),(I4(345),J4),(I4(344),J10),(I4(343),JPRS),(I4(342),JSDY) F1TRLO29
2,(I4(341),JSDZ),(I4(340),JARE),(I4(339),JMMX),(I4(338),JMMY) F1TRLO30
3,(I4(337),JMMZ),(I4(336),JMF),(I4(335),I7AS),(I4(334),I8Z) F1TRLO31
4,(I4(333),IPR),(I4(332),OGY),(I4(331),DEZ),(I4(330),PRES) F1TRLO32
5,(I4(329),IPR),(I4(328),TCOR),(I4(327),TRUN),(I4(326),IMFS) F1TRLO33
DIMENSION IRR(50) F1TRLO34
EQUIVALENCE (I4(200),IRFR) F1TRLO35
DIMENSION ISIR(540) F1TRLO36
EQUIVALENCE (DUMMY(100),ISIR) F1TRLO37
EQUIVALENCE (I4(35),ISHU) F1TRLO38
WRITE OUTPUT TAPE 6,1001,(RFM(1),I4,14) F1TRLO39
1001 FORMAT (I11,36X,25HLINEAR ELASTICITY PROBLEM// 2X,1446) F1TRLO40
WRITE OUTPUT TAPE 6,351,IN,IT,IDEG,ITYPE,IGEM,ISTR,IN,IN,IP F1TRLO41
1,IPRS,IMAT,NTIC F1TRLO42
351 FORMAT (//22H TOTAL NUMBER OF NODES,14X,15/32H TOTAL NUMBER OF FEM,11H,1043
11E ELEMENTS,8X,15/29H DEGREES OF FREEDOM AT A NODE,11X,15/12H ITYPE,11H,1044
2HE VALUE,28X,15,10X,54H FOR ISOTROPIC, 1 FOR ORTHOTROPIC, 2 FOR ANISOTROPIC,
3GENERAL MATERIAL/11H IGEN VALUE,29X,15,10X,40H FOR 2-, 1 FOR 3-DIM,11H,1046
4ANISOTROPIC STRUCTURES/11H ISIR VALUE,29X,15,10X,34H FOR PLANE STRAIN,11H,1047
5H CASE, 0 OTHERWISE/44H MAXIMUM NUMBER OF CONTACTS IN AN ELEMENT,11H,1048
6/32H CONTACT NUMBER INCLUDING DUMMIES,11/210H IRR VALUE,30X,15,10H,11H,1049
7X,65HNUMBER OF SUPPRESSED DEGREES OF FREEDOM IF NO MULTIPLE CONNECTIONS,11H,1050
8IONS/35H TOTAL NUMBER OF CONCENTRATED LOADS,5X,15/19H PRESSURE TYPE,11H,1051
9ES,25X,15/15H MATERIAL TYPES,25X,15/15H THICKNESS TYPES,24X,15) F1TRLO52
WRITE OUTPUT TAPE 6,352,ISUT,ISDY,ISDZ,IRFR,IMMX,IMMY,IMMZ,IMEI F1TRLO53
1,INX,IMP,ISHU,ICOR F1TRLO54
352 FORMAT (25H TEMPERATURE CHANGE TYPES,15X,15/35H TEMPERATURE GRADIENT,11H,1055
1NT TYPES ALONG Y,5X,15/35H TEMPERATURE GRADIENT TYPES ALONG Z,5X,15/11H,1056
25/11H AREA TYPES,29X,15/23H TORSION CONSTANT TYPES,17X,15/26H Y MOMENT,11H,1057
3MOMENT OF INERTIA TYPES,14X,15/26H Z MOMENT OF INERTIA TYPES,14X,15/2) F1TRLO58
439H NUMBER OF ANGLES FIXING PRINCIPAL AXES,16/10X,INX VALUE,30X,15/11H,1059
5,10X,35HNUMBER OF THE LINK FROM WHICH RETURN-TO-BEGINNING IS MADE,11H,1060
610H IMP VALUE,30X,15,10X,50H MINIMUM PRINT, 1 PARTIAL PRINT, 2 COMPLETE PRINT,11H,1061
7MPLETE PRINT/12H ISHUF VALUE,29X,15,10X,43H NO LABELLING, 1 LABELLING,11H,1062
8AREL, 2 OR 3 READ CARDS FOR LABELLING/11H IGEN VALUE,29X,15,10X,11H,1063
9,520H READ CARDS, 1 CALL SUBROUTINE CURC FOR COORDINATES) F1TRLO64
WRITE OUTPUT TAPE 6,353,(DUM,IMFS,IMEI,IPR,ITAS,ACFL,G1,G2,G3) F1TRLO65
3532 FORMAT (11H IRR VALUE,29X,15,10X,40H READ CARDS, 1 CALL SUBROUTINE) F1TRLO66
1HE RING FOR BOUNDARY CONDITIONS/11H IMFS VALUE,29X,15,10X,54H READ CARDS,
20 CARDS, 1 CALL SUBROUTINE MESH FOR MESH TOPOLGY/38H IPR VALUE, F1TRLO68
3ON-SHELL LOCAL NODAL AXES,17,10X,54H ASSUME ZERO, 1 COMPUTE AS USUAL,11H,1069
4ING)PAL, 2 READ AS INPUT/26H CHAIN PROGRAM TAPE NUMBER,16X,15/20H, F1TRLO70
5SCRATCH TAPE NUMBER,20X,15,10X,50H NIK - DO NOT COMPUTE RESULTS, F1TRLO71
6 OTHERWISE COMPUTE/ 23H ACCELERATION UNIT MASS,17X,10,4/34H DIRECT,11H,1072
711H COSINES OF ACCELERATION,16,6,5X,10,5,4X,10,4//) F1TRLO73
RETURN F1TRLO74
END F1TRLO75

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**Table VII-13. Source program listing of subroutine TICK (Link 1)**

```

* FAP LABEL
COLUMN 25 TICK000
LBI TICK TICK001
ENTRY TICK TICK002
NZI ONCE TICK003
TRA FIRST TICK004
CAL 5 TICK005
SHR INITL TICK006
ALS 18 TICK007
SLW 1,4 TICK008
TRA 2,4 TICK009
FIRST STL ONCE TICK010
CAL 5 TICK011
NIZ 1,1,1 TICK012
SIZ 1,4 TICK013
TRA 2,4 TICK014
ONCE PZE TICK015
INITL PZE TICK016
END TICK017

```

**Table VII-14. Source program listing of subroutine TOPO (Link 1)**

```

* LABEL LABEL
CENTRAL SUBROUTINE TOPO EITOP000
C PREPARES ELEMENT PROPERTIES AND CHECKS EITOP001
DIMENSION I4(1),AA(1),REMI(13),NT(10),DUMMY(5000),IDUM(5000),N(8) EITOP002
1,P(24),UV(24),X(8),Y(8),Z(8),XO(7),YO(7),ZO(7),RUMMY(27,9) EITOP003
2,D2(12),S(1),G(1) EITOP004
COMMON I4,AA EITOP005
EQUIVALENCE (I4,AA),(AA,9000),DUMMY) EITOP006
EQUIVALENCE (DUMMY,TDUM,NT,RUMMY),(DUMMY(11),REMI) EITOP007
EQUIVALENCE (I4(1),IN),(I4(2),JN),(I4(3),IT),(I4(4),IP),(I4(5), F1TOP008
1PRS),(I4(6),ITYPE),(I4(7),IMAT),(I4(8),IDEG),(I4(9),INX),(I4(10),F1TOP010
2IH),(I4(11),IR),(I4(12),IMM),(I4(13),IMMY),(I4(14),I1),(I4(15),F1TOP011
3IMP),(I4(16),IARE),(I4(17),A(1)),(I4(18),M),(I4(19),IY),(I4(20),F1TOP012
4ISTR),(I4(21),IFLT),(I4(22),IFRM),(I4(30),ITIC),(I4(31),IMFT) E1TOP013
5IA(192),ISUM,(I4(33),IND),(I4(34),IMS),(I4(35),IOS),(I4(37), F1TOP014
6IORD),(I4(39),IORD1),(I4(34),ACFL),(I4(40),J1),(I4(51),J2) E1TOP015
7IA(192),J3,(I4(53),J4),(I4(54),J5),(I4(55),J6),(I4(56),J7),(I4(57),F1TOP016
8J),(I4(58),JTY),(I4(59),J8),(I4(60),I80),(I4(61),I81),(I4(62),F1TOP017
9IAT),(I4(63),I8T),(I4(64),I8Y),(I4(65),I8E),(I4(61),I8P) E1TOP018
EQUIVALENCE (I4(66),ICAR),(I4(67),ICIX),(I4(68),ICFY),(I4(69), F1TOP019
1ICIZ),(I4(70),ICFI),(I4(71),ICX),(I4(72),ICY),(I4(73),ICZ) E1TOP020
2IA(174),IIC,(I4(75),IDH),(I4(76),IS),(I4(77),IIS) E1TOP021
3IA(178),IDEM,(I4(79),IDEX),(I4(80),IDF),(I4(81),IDT),(I4(82),IDG) E1TOP022
4IA(183),ALI,(I4(84),AL2),(I4(85),AL3),(I4(86),D1),(I4(107),P1) E1TOP023
5AA(131),UV,(I4(155),X),(I4(163),Y),(I4(171),Z),(I4(179),XD) E1TOP024
6AA(186),YD,(I4(193),Z),(I4(351),S),(I4(401),ZGFM) E1TOP025
7IA(142),IMP,(I4(43),IPRG),(I4(44),IPEN),(I4(45),CONS),(I4(46),I1) E1TOP026
8IA(147),G1,(I4(48),G2),(I4(49),G3) E1TOP027
EQUIVALENCE (I4(349),NTIC),(I4(349),ISD),(I4(347),ISDY),(I4(346) E1TOP028
1,ISD),(I4(345),J4),(I4(344),J10),(I4(343),JPRS),(I4(342),JSDY) E1TOP029
2,(I4(341),JSDZ),(I4(340),JARE),(I4(339),JMMX),(I4(338),JMMY) E1TOP030
3,(I4(337),JMMZ),(I4(336),JMF),(I4(335),I7AS),(I4(334),I8Z) E1TOP031
4,(I4(333),IPR),(I4(332),OGY),(I4(331),DEZ),(I4(330),PRES) E1TOP032
5,(I4(329),IPR),(I4(328),TCOR),(I4(327),TRUN),(I4(326),IMFS) E1TOP033
DIMENSION IRR(50) E1TOP034
EQUIVALENCE (I4(200),IRFR) E1TOP035
DIMENSION ISIR(540) E1TOP036
EQUIVALENCE (DUMMY(100),ISIR) E1TOP037
EQUIVALENCE (I4(35),ISHU) E1TOP038
WRITE OUTPUT TAPE 6,1001,(RFM(1),I4,14) E1TOP039
1001 FORMAT (I11,36X,25HLINEAR ELASTICITY PROBLEM// 2X,1446) E1TOP040
WRITE OUTPUT TAPE 6,351,IN,IT,IDEG,ITYPE,IGEM,ISTR,IN,IN,IP E1TOP041
1,IPRS,IMAT,NTIC E1TOP042
351 FORMAT (//22H TOTAL NUMBER OF NODES,14X,15/32H TOTAL NUMBER OF FEM,11H,1043
11E ELEMENTS,8X,15/29H DEGREES OF FREEDOM AT A NODE,11X,15/12H ITYPE,11H,1044
2HE VALUE,28X,15,10X,54H FOR ISOTROPIC, 1 FOR ORTHOTROPIC, 2 FOR ANISOTROPIC,
3GENERAL MATERIAL/11H IGEN VALUE,29X,15,10X,40H FOR 2-, 1 FOR 3-DIM,11H,1046
4ANISOTROPIC STRUCTURES/11H ISIR VALUE,29X,15,10X,34H FOR PLANE STRAIN,11H,1047
5H CASE, 0 OTHERWISE/44H MAXIMUM NUMBER OF CONTACTS IN AN ELEMENT,11H,1048
6/32H CONTACT NUMBER INCLUDING DUMMIES,11/210H IRR VALUE,30X,15,10H,11H,1049
7X,65HNUMBER OF SUPPRESSED DEGREES OF FREEDOM IF NO MULTIPLE CONNECTIONS,11H,1050
8IONS/35H TOTAL NUMBER OF CONCENTRATED LOADS,5X,15/19H PRESSURE TYPE,11H,1051
9ES,25X,15/15H MATERIAL TYPES,25X,15/15H THICKNESS TYPES,24X,15) E1TOP052
WRITE OUTPUT TAPE 6,352,ISUT,ISDY,ISDZ,IRFR,IMMX,IMMY,IMMZ,IMEI E1TOP053
1,INX,IMP,ISHU,ICOR E1TOP054
352 FORMAT (25H TEMPERATURE CHANGE TYPES,15X,15/35H TEMPERATURE GRADIENT,11H,1055
1NT TYPES ALONG Y,5X,15/35H TEMPERATURE GRADIENT TYPES ALONG Z,5X,15/11H,1056
25/11H AREA TYPES,29X,15/23H TORSION CONSTANT TYPES,17X,15/26H Y MOMENT,11H,1057
3MOMENT OF INERTIA TYPES,14X,15/26H Z MOMENT OF INERTIA TYPES,14X,15/2) E1TOP058
439H NUMBER OF ANGLES FIXING PRINCIPAL AXES,16/10X,INX VALUE,30X,15/11H,1059
5,10X,35HNUMBER OF THE LINK FROM WHICH RETURN-TO-BEGINNING IS MADE,11H,1060
610H IMP VALUE,30X,15,10X,50H MINIMUM PRINT, 1 PARTIAL PRINT, 2 COMPLETE PRINT,11H,1061
7MPLETE PRINT/12H ISHUF VALUE,29X,15,10X,43H NO LABELLING, 1 LABELLING,11H,1062
8AREL, 2 OR 3 READ CARDS FOR LABELLING/11H IGEN VALUE,29X,15,10X,11H,1063
9,520H READ CARDS, 1 CALL SUBROUTINE CURC FOR COORDINATES) E1TOP064
WRITE OUTPUT TAPE 6,353,(DUM,IMFS,IMEI,IPR,ITAS,ACFL,G1,G2,G3) E1TOP065
3532 FORMAT (11H IRR VALUE,29X,15,10X,40H READ CARDS, 1 CALL SUBROUTINE) E1TOP066
1HE RING FOR BOUNDARY CONDITIONS/11H IMFS VALUE,29X,15,10X,54H READ CARDS,
20 CARDS, 1 CALL SUBROUTINE MESH FOR MESH TOPOLGY/38H IPR VALUE, F1TOP068
3ON-SHELL LOCAL NODAL AXES,17,10X,54H ASSUME ZERO, 1 COMPUTE AS USUAL,11H,1069
4ING)PAL, 2 READ AS INPUT/26H CHAIN PROGRAM TAPE NUMBER,16X,15/20H, F1TOP070
5SCRATCH TAPE NUMBER,20X,15,10X,50H NIK - DO NOT COMPUTE RESULTS, F1TOP071
6 OTHERWISE COMPUTE/ 23H ACCELERATION UNIT MASS,17X,10,4/34H DIRECT,11H,1072
711H COSINES OF ACCELERATION,16,6,5X,10,5,4X,10,4//) E1TOP073
RETURN E1TOP074
END E1TOP075

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Table VII-14 (contd)

```

N(I)=I*(JM)
I=I+1
JH=J10+M
N(I)=I*(JM)
IF (I-IH) 1408,1408,1402
1402 JHP=I+1
DO 1405 J=JHP,8
1405 N(J)=0
1408 DO 1410 J=1,IH
IF (N(I)-I) 1410,1410,1450
1410 CONTINUE
GO TO 1600
1450 WRITE OUTPUT TAPE 6,7,M
2 FORMAT (11H IN ELEMENT,15,59H ERROR IN MESH TOPOLOGY INFORMATION,
1 NO CORRECTION IS MADE)
1600 NDX=0
1610 IF ((JPRS+1)*(JPRS-IPRS-1)) 1620,1611,1611
1611 JPRS=IPRS
IF (IELT=4) 1612,1613,1614
1612 IF (IELT=2) 1614,1616,1616
1614 IF (IELT=9) 1618,1616,1617
1617 IF (IELT=10) 1618,1616,1618
1618 JH=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(JPRS+L
GO TO 1615
1613 JH=J+M
I*(JM)=JPRS
GO TO 1615
1618 JH=J+M
L=I*(JM)/100
I*(JM)=100*(JPRS
1615 CONTINUE
NDX=NDX+1
1620 IF (IMF+1)IMFT-1MAT-1)) 1630,1621,1621
1621 IMF=1MAT
JM=J+M
I*(JM)=100*(IELT+JMET
NDX=NDX+1
1630 IF (ITIC+1)*(ITIC-NTIC-1)) 1640,1631,1631
1631 ITIC=NTIC
JM=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(ITIC+L
NDX=NDX+1
1640 IF (ITEM+1)*(ITEM-ISOT-1)) 1650,1641,1641
1641 ITEM=ISOT
JM=J+M
L=I*(JM)/100
I*(JM)=100*(L+ITEM
NDX=NDX+1
1650 IF ((JSDY+1)*(JSDY-ISDY-1)) 1660,1651,1651
1651 JSDY=ISDY
JM=J+M
L=I*(JM)/100
I*(JM)=100*(L+JSDY
NDX=NDX+1
1660 IF ((JSD2+1)*(JSD2-ISD2-1)) 1670,1661,1661
1661 JSD2=ISD2
IF (IELT=4) 1662,1663,1664
1662 JM=J+M
L=I*(JM)/100
I*(JM)=100*(L+JSD2
GO TO 1665
1663 JM=J+M
GO TO 1666
1664 JM=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(JSD2+L
1665 CONTINUE
NDX=NDX+1
1670 IF ((JARE+1)*(JARE-IARE-1)) 1680,1671,1671
1671 JARE=IARE
JM=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(JARE+L
NDX=NDX+1
1680 IF ((JMMX+1)*(JMMX-IMMX-1)) 1690,1681,1681
1681 JMMX=IMMX
JM=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(JMMX+L
NDX=NDX+1
1690 IF ((JMMY+1)*(JMMY-IMMY-1)) 1700,1691,1691
1691 JMMY=IMMY
JM=J+M
L=I*(JM)/100
I*(JM)=100*(L+JMMY
NDX=NDX+1
1700 IF ((JMMZ+1)*(JMMZ-IMMZ-1)) 1710,1701,1701
1701 JMMZ=IMMZ
JM=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(JMMZ+L
NDX=NDX+1
1710 IF ((JMF+1)*(JMF-IMF-1)) 1720,1711,1711
1711 JMF=IMF
JM=J+M
L=I*(JM)/100
I*(JM)=100*(L+JMF
NDX=NDX+1
1720 IF (INDX) 2000,2000,1800
1800 WRITE OUTPUT TAPE 6,7,M,NDX
1 FORMAT(11H IN ELEMENT,15,2X,1H,15,2X,95HPROPERTY TYPE NUMBER IS
1 IS OUTSIDE THE PRESCRIBED RANGE. TYPE NO IS ASSUMED AS LARGEST POSSIBLE)
25T6L1
2000 RETURN
END

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Table VII-15. Source program listing of main program of Link 2 (generation link)

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* CHAIN (2,2)
* LABEL
CFLAS2
C MAIN PROGRAM FOR GENERATION LINK
C GENERATES GOVERNING EQUATIONS
DIMENSION IA(1),AA(1),SILV,N(1),D2L(2),D33(3,3),F22(3,3)
1,P(24),UV(124),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1)
COMMON IA,AA
EQUIVALENCE (IA,AA),D2L,D33,(D21(10),F22),(D21(19),F1,(D21(20),G)
EQUIVALENCE (IA(1),IA(1),IA(2),IA(2),IA(3),IA(3),IA(4),IA(4),IA(5),
1PKS),IA(6),ITYPE),(IA(7),IA(8),IA(9),IA(9),IA(10),IA(10),IA(11),
2EI),(IA(11),IA(12),IA(12),IA(13),IA(13),IA(14),IA(14),IA(15),IA(15),
3IMF),IA(16),IA(16),IA(17),IA(17),IA(18),IA(18),IA(19),IA(19),IA(20),
4ISIR),IA(20),IA(21),IA(21),IA(22),IA(22),IA(23),IA(23),IA(24),
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6IDRO),IA(28),IA(29),IA(29),IA(30),IA(30),IA(31),IA(31),IA(32),
7IA(32),IA(32),IA(33),IA(33),IA(34),IA(34),IA(35),IA(35),IA(36),
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2IAA(707),IAA(707),IAA(708),IAA(708),IAA(709),IAA(709),IAA(710),IAA(710),
3IAA(711),IAA(711),IAA(712),IAA(712),IAA(713),IAA(713),IAA(714),IAA(714),
4IAA(715),IAA(715),IAA(716),IAA(716),IAA(717),IAA(717),IAA(718),IAA(718),
5IAA(719),IAA(719),IAA(720),IAA(720),IAA(721),IAA(721),IAA(722),IAA(722),
6IAA(723),IAA(723),IAA(724),IAA(724),IAA(725),IAA(725),IAA(726),IAA(726),
7IAA(727),IAA(727),IAA(728),IAA(728),IAA(729),IAA(729),IAA(730),IAA(730),
8IAA(731),IAA(731),IAA(732),IAA(732),IAA(733),IAA(733),IAA(734),IAA(734),
9IAA(735),IAA(735),IAA(736),IAA(736),IAA(737),IAA(737),IAA(738),IAA(738),
EQUIVALENCE (IAA(739),IAA(739),IAA(740),IAA(740),IAA(741),IAA(741),IAA(742),IAA(742),
1IAA(743),IAA(743),IAA(744),IAA(744),IAA(745),IAA(745),IAA(746),IAA(746),
2IAA(747),IAA(747),IAA(748),IAA(748),IAA(749),IAA(749),IAA(750),IAA(750),
3IAA(751),IAA(751),IAA(752),IAA(7
```

Table VII-15 (contd)

```

601 I101=I10+I1MFT-1)*2
GO TO 604
602 I101=I10+I1MFT-1)*9
GO TO 604
603 I101=I10+I1MFT-1)*21
604 E=AA(I101+1)
R=AA(I101+2)
MU=F/12.*G)-1.
KELT=IELT
GO TO 504,504,504,504,502,502,502,502,502,503,503,502,507,507,507,502.
1503,503,507,502).KELT
502 IF (I1TYPE=1) 5021,5022,5023
5021 IF (ISTR1 6021,6021,6022
6021 D3311,1)=2.*G/(1.-PU)
D3312,2)=D3311,1)
D3311,2)=D3311,1)*PU
GO TO 6025
6022 D3311,1)=2.*G*(1.-PU)/(1.-2.*PU)
D3312,2)=D3311,1)
D3311,2)=2.*G*PU/(1.-2.*PU)
6023 D3311,3)=0.
D3312,3)=0.
D3313,3)=G
IF (IEL1-5) 5024,5024,6025
6025 IF (IELT-6) 5024,5024,6024
6024 E2211,1)=G
E2212,2)=G
F2212,2)=G
GO TO 5024
5022 D3311,1)=AA(I101+1)
D3311,2)=AA(I101+2)
D3311,3)=AA(I101+3)
D3312,2)=AA(I101+4)
D3312,3)=AA(I101+5)
D3313,3)=AA(I101+6)
E2211,1)=AA(I101+7)
E2211,2)=AA(I101+8)
E2212,2)=AA(I101+9)
GO TO 5024
5023 D3311,1)=AA(I101+1)
D3311,2)=AA(I101+2)
D3311,3)=AA(I101+4)
D3312,2)=AA(I101+7)
D3312,3)=AA(I101+9)
D3313,3)=AA(I101+16)
E2211,1)=AA(I101+19)
E2211,2)=AA(I101+20)
F2212,2)=AA(I101+21)
D3312,1)=D3311,2)
D3313,1)=D3311,3)
D3313,2)=D3311,3)
E2212,1)=E2211,2)
GO TO 504
503 IF (I1TYPE=1) 5031,5031,5033
5031 EE=E
CG=0
DD 5032 I=1,21
5032 D2111)=0.
D2111)=2.*GG*(1.-PU)/(1.-2.*PU)
D2112)=D2111)*PU/(1.-PU)
D2113)=D2112)
D2117)=D2111)
D2118)=D2112)
D2112)=D2111)
D2116)=GG
D2119)=GG
D21121)=GG
GO TO 504
5033 DD 5034 I=1,21
I101=I10+1
5034 D2111)=AA(I1011)
504 IERR=0
C IS THERE MULTIPLE ELEMENT
IF (IELT=6) 5100,4900,4999
4999 IF (IELT=8) 5100,4900,4700
4700 IF (IELT=10) 5100,4900,4800
4800 IF (IELT=12) 5100,4900,4850
4850 IF (IELT=14) 5100,4900,4880
4880 IF (IELT=16) 5100,4900,5100
C THERE IS MULTIPLE ELEMENT.CUT IT IN PIECES
4888 I1TT=0
IELT=IELT+1
DU 4890 I=1,4
N(I)=N(I)+1
GO TO 4902
4900 I1NS=I1NS
DD 4901 I=1,4
4901 N(I)=N(I)+1
4902 CALL CUTE (ITTK)
CFE=45
5100 J1=ITTT*I1NS
PRCD=0.
ITTT=ITTT+1
I1D2=I1D2+I1D5
C1MS*I1MS
CX=0.
CY=0.
CZ=0.
DD 5500 I=1,I1MS
J1=J1+1
J=N(I)+1)
N(I)=J
5450 IF (J1 1,1,5450
I1XJ=I1X+J
I1YJ=I1Y+J
I1ZJ=I1Z+J
X(I)=AA(I1XJ)
Y(I)=AA(I1YJ)
Z(I)=AA(I1ZJ)+ZDEM
CX=CX+X(I)
CY=CY+Y(I)
CZ=CZ+Z(I)
IF (I-1) 5500,5500,5460
5460 X(I)-1)=X(I)-X(I)
Y(I)-1)=Y(I)-Y(I)
Z(I)-1)=Z(I)-Z(I)
5500 CONTINUE
CX=CX/I1MS
CY=CY/I1MS
CZ=CZ/I1MS
DD 5501 I=1,I1MS
FLAS2113
FLAS2114
FLAS2115
FLAS2116
FLAS2117
FLAS2118
FLAS2119
FLAS2120
FLAS2121
FLAS2122
FLAS2123
FLAS2124
FLAS2125
FLAS2126
FLAS2127
FLAS2128
FLAS2129
FLAS2130
FLAS2131
FLAS2132
FLAS2133
FLAS2134
FLAS2135
FLAS2136
FLAS2137
FLAS2138
FLAS2139
FLAS2140
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FLAS2142
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FLAS2145
FLAS2146
FLAS2147
FLAS2148
FLAS2149
FLAS2150
FLAS2151
FLAS2152
FLAS2153
FLAS2154
FLAS2155
FLAS2156
FLAS2157
FLAS2158
FLAS2159
FLAS2160
FLAS2161
FLAS2162
FLAS2163
FLAS2164
FLAS2165
FLAS2166
FLAS2167
FLAS2168
FLAS2169
FLAS2170
FLAS2171
FLAS2172
FLAS2173
FLAS2174
FLAS2175
FLAS2176
FLAS2177
FLAS2178
FLAS2179
FLAS2180
FLAS2181
FLAS2182
FLAS2183
FLAS2184
FLAS2185
FLAS2186
FLAS2187
FLAS2188
FLAS2189
FLAS2190
FLAS2191
FLAS2192
FLAS2193
FLAS2194
FLAS2195
FLAS2196
FLAS2197
FLAS2198
FLAS2199
FLAS2200
FLAS2201
FLAS2202
FLAS2203
FLAS2204
FLAS2205
FLAS2206
FLAS2206A
FLS2206B
FLS2206C
ELS2206D
FLAS2207
FLAS2208
FLAS2209
FLAS2210
FLAS2211
FLAS2212
FLAS2213
FLAS2214
FLAS2215
FLAS2216
FLAS2217
FLS2217A
FLS2217B
FLS2217C
FLAS2218
FLAS2219
FLAS2220
FLAS2221
FLAS2222
FLS2222A
FLS2222B
FLS2222C
ELS2222D
X(I)=X(I)-CX
Y(I)=Y(I)-CY
5501 Z(I)=Z(I)-CZ
5600 DD 6 I=1,I1D5
P(I)=0.
UV(I)=0.
I55=I-1D5
DD 7 J=1,I1D5
I55=I55+I05
7 I55=I55+0.
6 CONTINUE
IF (DT) 82,83,82
82 DR A4 I=1,I1MS
I1=I1MS+1
I2=I1MS+1
UV(I)=X(I)*OT*AL1
UV(I)=Y(I)*OT*AL2
R4 UV(I)=Z(I)*OT*AL3
83 CALL STFS(IEI)
5043 IF (I1N=1) 86,86,85
87 FORMAT (////2015/12F10.3/12F10.3//1516.F13.4,5X1)
85 WRITE OUTPUT TAPE 6,87,M,(N1),J=1,81,IELT,IMFT,ITTC,ITEM,JPPS,JARELAS2260
1E,JSDY,JSDZ,JNMX,JNFI,IDS,(X(J),Y(J),Z(J),J=1,81,I1,S11),I=1,I052)FLAS2261
86 IF (IERR) 1,951,1
921 IF (DT) 952,954,952
924 IF (DG) 952,955,952
9501 IF (DGZ) 952,953,952
952 CALL DMN (S,UV,I05,P)
953 IF (IPRG) 957,957,958
928 IF (IPRG-IPEN) 959,959,957
959 DD 955 I=IPRG,IPEN
DELP=CONS*G(I)
CPRS=PRCD*P(I)
I1=I1-IPRG*I1MS
DD 956 J=1,I1MS
I1=J+1
956 P(I)=P(I)+DELP+CPRS
955 CONTINUE
951 IF (I1N=1) 9532,9532,9531
9543 WRITE OUTPUT TAPE 6,9533,(I,P111,I=1,IDS)
9533 FORMAT (//1516.E13.4,5X1)
9537 DD 95 I=1,I0EG
DD 94 K=1,I1MS
I=I1MS+1-I+K
I5=IDEG*(N(I)-1)+I
I5E=I-1D5
CALL DARN (IS,IRS,CCCJ,I0E)
IF (I0E) 307,307,308
307 IERR=6
GO TO 1
308 DD 393 I=0,1,10E
I5S=I5E
CCUR=CCCC(I10)*CFE
IF (CCUR(I) 912,911,912
912 IDEF1=IDEF1+R
AA(IDEF1)=AA(IDEF1)+CCUR*IPIE)
911 DD 93 J=1,I0EG
DD 92 I=1,I1MS
I5S=I5S+I05
JE=I5S*(J-1)+L
JS=IDEG*(N(I)-1)+J
CALL DARN (JS,JRS,CCCJ,JOE)
IF (JOE) 307,307,408
408 DD 397 J=1,I0E
CCURJ=CCCJ*JOE
JR=JRS*JOE
F=CCURJ*CCURJ
IF (F) 913,392,913
913 IF (JR-IND) 914,914,915
915 AA(IDEF1)=AA(IDEF1)+F*(I5S)
GO TO 392
914 IF (JR-IB) 392,916,916
916 I1=I1+IB
IST1=IST1+I1(I1)+JB-IB
AA(IST1)=AA(IST1)+F*(I1SS)
392 CONTINUE
393 CONTINUE
394 CONTINUE
95 CONTINUE
9987 DD 9983 I=1,IDS
PV(I)=P(I)
9983 P(I)=0.
CALL DMMS(UV,I05,P)
WRITE TAPE (IAS,M,ITTT,ITTM,NAV,IMS,IDS,I052,(N(I),F=1,IMS),(S1))
I1=I1D52),(P(I),PV(I),I=1,IDS)
99H) CONTINUE
999 IF (ITTT-ITTM) 5100,9990,9990
9990 IF (INAV=2) 99,4889,99
99 CONTINUE
INP=INPT
CALL CAS?
IF (INP=1) 232,232,233
233 IEND=IST+IEND
I51=I51+1
WRITE OUTPUT TAPE 6,871,(I,AA(I),I=IST1,IEND)
871 FORMAT (I1H,62HUPPER HALF OF THE STIFFNESS MATRIX AFTER R.C.L. IMPROVE)ELAS2216
IED FOLLOWS./89H ROW LISTING. FOR BANDWIDTHS SEE THE TABLE FOR MESHELAS2219
2 TPOLOGY OF REDUCED STIFFNESS MATRIX,////1516.E14.5,4X1)
ELAS2220
IEND=IDEF+ISUM
WRITE OUTPUT TAPE 6,871,(I,AA(I),I=IDEF1,IEND)
871) FORMAT (I1H,31HREDUCED LOADING VECTOR FOLLOWS,////1516.F14.5,4X1)ELAS2224
232 IERR=LU
IF (I1AS) 2323,2323,2324
2324 REWIND I1AS
2323 CONTINUE
CALL TICC (ITTM)
C2T=ITTK
C2T=C2T/60.
WRITE OUTPUT TAPE 6,5555,C2T
5555 FORMAT 1 21H GENERATION LINK TOOK.FT.-2.10H SECONDS.)
INP=INPT
IF (INX=2) 2321,2321,2322
2321 CALL CHAIN (ITAP)
2322 CALL CHAIN (S,ITAP)
END
FLAS2222E
FLAS2222F
FLAS2222G
FLAS2222H
FLAS2222I
FLAS2222J
FLAS2222K
FLAS2222L
FLAS2222M
FLAS2222N
FLAS2222O
FLAS2222P
FLAS2222Q
FLAS2222R
FLAS2222S
FLAS2222T
FLAS2222U
FLAS2222V
FLAS2222W
FLAS2222X
FLAS2222Y
FLAS2222Z
FLAS2223
FLAS2224
FLAS2225
FLAS2226
FLAS2227
FLAS2228
FLAS2229
FLAS2230
FLAS2231
FLAS2232
FLAS2233
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FLAS2235
FLAS2236
FLAS2237
FLAS2238
FLAS2239
FLAS2240
FLAS2241
FLAS2242
FLAS2243
FLAS2244
FLAS2245
FLAS2246
FLAS2247
FLAS2248
FLAS2249
FLAS2250
FLAS2251
FLAS2252
FLAS2253
FLAS2254
FLAS2255
FLAS2256
FLAS2257
FLAS2258
FLAS2259
FLAS2260
FLAS2261
FLAS2262
FLAS2263
FLAS2264
FLAS2265
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FLAS2326
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FLAS2328
FLAS2329
FLAS2330
FLAS2331
FLAS2332
FLAS2333
FLAS2334
FLAS2335
FLAS2336
FLAS2337
FLAS2338

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**Table VII-22. Source program listing of subroutine DARN (Link 2)**

```

C LABEL
CE2DUM SUBROUTINE DARN (KS,KBS,CCC,KOE) F2D0N000
PREPARES INFORMATION RELATD WITH DIMSIRAINIS FOR ASSEMBLY F2D0N001
DIMENSION A(1),AA(1),S(1),N(1),D21(21),D33(3,3),E22(3,3) F2D0N002
1,P(24),UV(24),X(18),Y(18),Z(18),XD(7),YD(7),ZD(7),G(1) F2D0N003
COMMON IA,AA F2D0N004
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),F22), (D21(19),F1), (D21(20),G1) F2D0N005
EQUIVALENCE (IA(1),IN), (IA(2),IAM), (IA(3),II), (IA(4),IP1), (IA(5), F2D0N007
11PR5), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10),F2D0N008
21H), (IA(11),IR), (IA(12),IMAX), (IA(13),IMY), (IA(14),IMZ), (IA(15),F2D0N009
31MF1), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),ITY), (IA(27),F2D0N010
41STR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMF1), F2D0N011
5 (IA(32),ISUM), (IA(33),IND), (IA(34),IP5), (IA(35),I05), (IA(37), F2D0N012
61OR0), (IA(38),IDR01), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F2D0N013
7 (IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),F2D0N014
8), J8), (IA(58),JTY), (IA(59),IRK), (IA(60),IRU), (IA(61),IID), (IA(62),F2D0N015
91IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITF), (IA(67),ITAP) F2D0N016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICY), (IA(69), F2D0N017
11C12), (IA(70),ICF1), (IA(71),IXX), (IA(72),IYY), (IA(73),I72) F2D0N018
2 (IA(74),IIC), (IA(75),IDEF), (IA(76),I57), (IA(77),I15) F2D0N019
3 (IA(78),IDEP), (IA(79),IFRR), (IA(80),TF), (IA(81),DF), (IA(82),DF) F2D0N020
4 (IA(83),ALL), (IA(84),AL2), (IA(85),AL3), (IA(86),D21), (IA(107),P1), F2D0N021
5 (IA(131),UV1), (IA(135),X), (IA(139),Y), (IA(171),Z), (AA(179),XD), F2D0N022
6 (AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(40),ZGFM) F2D0N023
7, (AA(42),INP), (AA(43),IPRG), (AA(44),IPFN), (AA(45),CONS), (AA(46),IUF2D0N024
8), (AA(47),G1), (AA(48),G2), (AA(49),G3) F2D0N025
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346) F2D0N026
1, ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSY) F2D0N027
2, (IA(341),JSOZ), (IA(340),JARF), (IA(339),JMMX), (IA(338),JMMY) F2D0N028
3, (IA(337),JMMZ), (IA(336),JMF1), (IA(335),JTAS), (IA(334),IDZ) F2D0N029
4, (IA(333),IPR), (AA(332),DGY), (AA(331),DGZ), (AA(330),PRE5) F2D0N030
5, (IA(329),IPR) F2D0N031
DIMENSION IKS(25),CCC(25),JRS(25),CCC(25) F2D0N032
EQUIVALENCE (IA(200),I05), (IA(225),J05), (AA(250),CCC1), F2D0N033
1 (AA(275),K05), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSY) F2D0N034
DIMENSION KRS(1),CCC(1) F2D0N035
1RB1=JBB1 F2D0N036
KR=IA(1BB1) F2D0N037
IF (KB+IND) 301,302,302 F2D0N038
IF (KB) 303,1,304 F2D0N039
KOE=1 F2D0N040
IIC1=IICAKS F2D0N041
CCC1=AA(1)IIC1 F2D0N042
KRS(1)=KB F2D0N043
GO TO 308 F2D0N044
KOE=1 F2D0N045
CCC(1)=1 F2D0N046
KRS(1)=KB F2D0N047
GO TO 308 F2D0N048
301 ICOMP=1000+KS F2D0N049
INCR=1 F2D0N050
DO 306 ISOR=1,IND F2D0N051
1HOF=180+ISOR F2D0N052
IF (XARSF(IA(1801))-ICOMP) 306,307,306 F2D0N053
1BRE=180+ISOR F2D0N054
IIC1=IIC+ISOR F2D0N055
KRS1=INCR+XARSF(IA(1811)) F2D0N056
CCC(INCR)=AA(1)IIC1 F2D0N057
INCR=INCR+1 F2D0N058
CONTINUE F2D0N059
KOE=INCR-1 F2D0N060
RETURN F2D0N061
1 KOE=0 F2D0N062
GO TO 308 F2D0N063
END F2D0N064

```

**Table VII-23. Source program listing of subroutine DMM (Link 2)**

```

C LABEL F2D0M000
CE2DUM SUBROUTINE DMM (A,B,M,C) F2D0M001
OBTAINS THE PRODUCT OF ELEMENT STIFFNESS MATRIX IIMS A VECTOR F2D0M002
DIMENSION A(1),B(1),C(1) F2D0M003
DO 10 I=1,M F2D0M004
1SS=1,M F2D0M005
DO 9 K=1,M F2D0M006
1SS=SS+M F2D0M007
C(I)=C(I)+A(I)SS*B(K) F2D0M008
9 CONTINUE F2D0M009
RETURN F2D0M010
END F2D0M011

```

**Table VII-24. Source program listing of subroutine ELDI (Link 2)**

```

C LABEL F2FL0000
CE2ELL SUBROUTINE ELDI F2FL0001
OBTAINS UNIT VECTOR OF PRESSURE FOR LINE ELEMENT F2FL0002
DIMENSION A(1),AA(1),S(1),N(1),D21(21),D33(3,3),E22(3,3) F2FL0003
1,P(24),UV(24),X(18),Y(18),Z(18),XD(7),YD(7),ZD(7),G(1) F2FL0004
COMMON IA,AA F2FL0005
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),F22), (D21(19),F1), (D21(20),G1) F2FL0006
EQUIVALENCE (IA(1),IN), (IA(2),IAM), (IA(3),II), (IA(4),IP1), (IA(5), F2FL0007
11PR5), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10),F2FL0008
21H), (IA(11),IR), (IA(12),IMAX), (IA(13),IMY), (IA(14),IMZ), (IA(15),F2FL0009
31MF1), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),ITY), (IA(27),F2FL0010
41STR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMF1), F2FL0011
5 (IA(32),ISUM), (IA(33),IND), (IA(34),IP5), (IA(35),I05), (IA(37), F2FL0012
61OR0), (IA(38),IDR01), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F2FL0013
7 (IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),F2FL0014
8), J8), (IA(58),JTY), (IA(59),IRK), (IA(60),IRU), (IA(61),IID), (IA(62),F2FL0015
91IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITF), (IA(67),ITAP) F2FL0016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICY), (IA(69), F2FL0017
11C12), (IA(70),ICF1), (IA(71),IXX), (IA(72),IYY), (IA(73),I72) F2FL0018
2 (IA(74),IIC), (IA(75),IDEF), (IA(76),I57), (IA(77),I15) F2FL0019
3 (IA(78),IDEP), (IA(79),IFRR), (IA(80),TF), (IA(81),DF), (IA(82),DF) F2FL0020
4 (IA(83),ALL), (IA(84),AL2), (IA(85),AL3), (IA(86),D21), (IA(107),P1), F2FL0021
5 (IA(131),UV1), (IA(135),X), (IA(139),Y), (IA(171),Z), (AA(179),XD), F2FL0022
6 (AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(40),ZGFM) F2FL0023
7, (AA(42),INP), (AA(43),IPRG), (AA(44),IPFN), (AA(45),CONS), (AA(46),IUF2FL0024
8), (AA(47),G1), (AA(48),G2), (AA(49),G3) F2FL0025
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346) F2FL0026
1, ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSY) F2FL0027
2, (IA(341),JSOZ), (IA(340),JARF), (IA(339),JMMX), (IA(338),JMMY) F2FL0028
3, (IA(337),JMMZ), (IA(336),JMF1), (IA(335),JTAS), (IA(334),IDZ) F2FL0029
4, (IA(333),IPR), (AA(332),DGY), (AA(331),DGZ), (AA(330),PRE5) F2FL0030
5, (IA(329),IPR) F2FL0031
DIMENSION A(6,6),D1R(3,3),PVR(12),T(6),PDR(3),PR(3),DUG(3) F2FL0032
EQUIVALENCE (IA(200),A), (IA(236),EL1), (IA(231),AKEA), (AA(238),II) F2FL0033
1, (AA(239),J01), (AA(240),IR), (AA(241),JK), (AA(242),NY), (AA(264),DIR) F2FL0034
2, (AA(304),UVG), (AA(291),PD), (AA(294),PN), (AA(297),DUG), (AA(300),IUF2FL0035
31=SORFIX(11)*XD(1)+YD(1)+ZD(1)*ZD(1) F2FL0036
IF (EL1) 1010,1010,110 F2FL0037
110 ELI=1/VEL F2FL0038
T(1)=X(1)*VEL F2FL0039
113=YD(1)*VEL F2FL0040
T(5)=ZD(1)*VEL F2FL0041
PN(1)=DUG(2)*T(5)-DUG(3)*T(3) F2FL0042
PN(2)=DUG(3)*T(1)-DUG(1)*T(5) F2FL0043
PN(3)=DUG(1)*T(3)-DUG(2)*T(1) F2FL0044
VEL=SORF(PN(1)*PN(1)+PN(2)*PN(2)+PN(3)*PN(3)) F2FL0045
IF (VEL) 1E-4) 220,220,230 F2FL0046
220 PRES=0. F2FL0048
GO TO 1000 F2FL0049
230 VEL=1/VEL F2FL0050
DO 300 I=1,3 F2FL0051
300 PN(I)=PN(I)*VEL F2FL0052
PD(1)=T(3)*PN(3)-T(5)*PN(2) F2FL0053
PD(2)=T(5)*PN(1)-T(1)*PN(3) F2FL0054
PD(3)=T(1)*PN(2)-T(3)*PN(1) F2FL0055
VEL=1/VELK(I)*PD(1)*PD(1)+PD(2)*PD(2)+PD(3)*PD(3) F2FL0056
DO 400 I=1,3 F2FL0057
400 PD(I)=PD(I)*VEL F2FL0058
1000 RETURN F2FL0059
1010 IERR=1 F2FL0060
GO TO 1000 F2FL0061
END F2FL0061

```

Table VII-25. Source program listing of subroutine PLBE (Link 2)

```

* LABEL
CE2PLR
SUBROUTINE PLBE
  GENRATES SUBMATRICES FOR PLPMMT TYPE 3 AND 4
  DIMENSION I(1),AA(1),S(1),N(8),D21(21),D33(3),E22(3,3)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
  COMMON IA,AA
  EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),F), (D21(20),G)
  EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IT), (IA(4),IP), (IA(5),
  1)PRS1, (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDFG), (IA(9),INX), (IA(10),
  2)H), (IA(11),IB), (IA(12),IMMX), (IA(13),IMMY), (IA(14),IMMZ), (IA(15),
  3)MFI), (IA(16),IARE), (IA(17),ITEM), (IA(18),ITEM), (IA(19),ITEM), (IA(20),
  4)STR), (IA(21),IARE), (IA(22),ITEM), (IA(23),ITEM), (IA(24),ITEM), (IA(25),
  5)IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(35),IMS), (IA(36),IMS), (IA(37),
  6)IRD), (IA(38),IORD), (IA(39),ACEL), (IA(40),J), (IA(41),J), (IA(42),
  7)IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),
  8),J8), (IA(58),JTY), (IA(59),I8), (IA(60),I8), (IA(61),I8), (IA(62),
  9)IA), (IA(63),I8), (IA(64),I8), (IA(65),I8), (IA(66),I8), (IA(67),I8), (IA(68),
  1)C(2), (IA(70),ICF), (IA(71),ICX), (IA(72),IY), (IA(73),IZ),
  2)IA(74),IIC, (IA(75),IDEF), (IA(76),IST), (IA(77),IIS)
  3,IA(78),IGEM), (IA(79),IERR), (IA(80),TE), (IA(81),DT), (IA(82),DG),
  4)AA(83),AL1, (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P),
  5)AA(131),UV, (AA(155),X), (AA(156),Y), (AA(157),Z), (AA(179),XD),
  6)AA(186),YD, (AA(193),ZD), (AA(351),S), (AA(401),ZGFM)
  7, (AA(421),INP), (AA(443),IPBG), (AA(444),IPEN), (AA(465),CONS), (AA(466),IUE)
  8), (AA(477),G), (AA(488),G2), (AA(491),G3)
  EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346)
  1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),J50Y)
  2, (IA(341),J5DZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY)
  3, (IA(337),JMMZ), (IA(336),JMF), (IA(335),JIAS), (IA(334),I0Z)
  4, (IA(333),IPR), (AA(332),DGY), (AA(331),DGZ), (AA(330),PRFS)
  5, (IA(329),IPR)
  DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),RUG(13)
  EQUIVALENCE (AA(200),A), (AA(236),EL), (AA(237),AREA), (AA(238),I)
  1, (AA(239),J3), (AA(240),IR), (AA(241),JR), (AA(242),NY), (AA(264),DIR)
  2, (AA(306),UVG), (AA(291),PD), (AA(296),PN), (AA(297),RUG), (AA(300),T)
  IF (JMMX) I010,I010,I010
  150 ICX=ICX+JMMX
  IF (JMMY) I010,I010,I010
  150 ICY=ICY+JMMY
  150 A(1,1)=12, *E=AA(1)CYJ/(EL**3)
  A(1,2)=-A(1,1)
  A(2,1)=A(1,1)
  A(2,2)=E**AA(1)CYJ/(FL**2)
  A(7,6)=A(7,5)
  A(1,5)=-A(2,5)
  A(1,6)=-A(1,5)
  A(3,3)=G*AA(1)CXJ/FL
  A(3,4)=-A(3,3)
  A(4,4)=A(3,3)
  A(5,5)=4, *E=AA(1)CYJ/FL
  A(5,6)=-5*A(5,5)
  A(6,6)=-A(5,5)
  DD 200 J=1,4
  DD 200 J=1,6
  200 A(J,1)=A(1,J)
  1000 RETURN
  1010 IPR=1
  GO TO 1000
  END
  
```

Table VII-26. Source program listing of subroutine RLOC (Link 2)

```

* LABEL
CE2KLC
SUBROUTINE RLOC
  ADDS SUBMATRICES TO FORM ELEMENT STIFFNESS MATRICES OF LINE ELEMENT
  DIMENSION I(1),AA(1),S(1),N(8),D21(21),D33(3),E22(3,3)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
  COMMON IA,AA
  EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),F), (D21(20),G)
  EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IT), (IA(4),IP), (IA(5),
  1)PRS1, (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDFG), (IA(9),INX), (IA(10),
  2)H), (IA(11),IB), (IA(12),IMMX), (IA(13),IMMY), (IA(14),IMMZ), (IA(15),
  3)MFI), (IA(16),IARE), (IA(17),ITEM), (IA(18),ITEM), (IA(19),ITEM), (IA(20),
  4)STR), (IA(21),IARE), (IA(22),ITEM), (IA(23),ITEM), (IA(24),ITEM), (IA(25),
  5)IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(35),IMS), (IA(36),IMS), (IA(37),
  6)IRD), (IA(38),IORD), (IA(39),ACEL), (IA(40),J), (IA(41),J), (IA(42),
  7)IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),
  8),J8), (IA(58),JTY), (IA(59),I8), (IA(60),I8), (IA(61),I8), (IA(62),
  9)IA), (IA(63),I8), (IA(64),I8), (IA(65),I8), (IA(66),I8), (IA(67),I8), (IA(68),
  1)C(2), (IA(70),ICF), (IA(71),ICX), (IA(72),IY), (IA(73),IZ),
  2)IA(74),IIC, (IA(75),IDEF), (IA(76),IST), (IA(77),IIS)
  3,IA(78),IGEM), (IA(79),IERR), (IA(80),TE), (IA(81),DT), (IA(82),DG),
  4)AA(83),AL1, (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P),
  5)AA(131),UV, (AA(155),X), (AA(156),Y), (AA(157),Z), (AA(179),XD),
  6)AA(186),YD, (AA(193),ZD), (AA(351),S), (AA(401),ZGFM)
  7, (AA(421),INP), (AA(443),IPBG), (AA(444),IPEN), (AA(465),CONS), (AA(466),IUE)
  8), (AA(477),G), (AA(488),G2), (AA(491),G3)
  EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346)
  1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),J50Y)
  2, (IA(341),J5DZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY)
  3, (IA(337),JMMZ), (IA(336),JMF), (IA(335),JIAS), (IA(334),I0Z)
  4, (IA(333),IPR), (AA(332),DGY), (AA(331),DGZ), (AA(330),PRFS)
  5, (IA(329),IPR)
  DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),RUG(13)
  EQUIVALENCE (AA(200),A), (AA(236),EL), (AA(237),AREA), (AA(238),I)
  1, (AA(239),J3), (AA(240),IR), (AA(241),JR), (AA(242),NY), (AA(264),DIR)
  2, (AA(306),UVG), (AA(291),PD), (AA(296),PN), (AA(297),RUG), (AA(300),T)
  IF (JMMX) I010,I010,I010
  150 ICX=ICX+JMMX
  IF (JMMY) I010,I010,I010
  150 ICY=ICY+JMMY
  150 A(1,1)=12, *E=AA(1)CYJ/(EL**3)
  A(1,2)=-A(1,1)
  A(2,1)=A(1,1)
  A(2,2)=E**AA(1)CYJ/(FL**2)
  A(7,6)=A(7,5)
  A(1,5)=-A(2,5)
  A(1,6)=-A(1,5)
  A(3,3)=G*AA(1)CXJ/FL
  A(3,4)=-A(3,3)
  A(4,4)=A(3,3)
  A(5,5)=4, *E=AA(1)CYJ/FL
  A(5,6)=-5*A(5,5)
  A(6,6)=-A(5,5)
  DD 200 J=1,4
  DD 200 J=1,6
  200 A(J,1)=A(1,J)
  1000 RETURN
  1010 IPR=1
  GO TO 1000
  END
  
```

Table VII-27. Source program listing of subroutine S01 (Link 2)

```

* LABEL
CE2S01
SUBROUTINE S01
  GENRATES FOR ELEMENT TYPE 1 STIFFNESS AND LOAD MATRICES
  DIMENSION I(1),AA(1),S(1),N(8),D21(21),D33(3),E22(3,3)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
  COMMON IA,AA
  EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),F), (D21(20),G)
  EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IT), (IA(4),IP), (IA(5),
  1)PRS1, (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDFG), (IA(9),INX), (IA(10),
  2)H), (IA(11),IB), (IA(12),IMMX), (IA(13),IMMY), (IA(14),IMMZ), (IA(15),
  3)MFI), (IA(16),IARE), (IA(17),ITEM), (IA(18),ITEM), (IA(19),ITEM), (IA(20),
  4)STR), (IA(21),IARE), (IA(22),ITEM), (IA(23),ITEM), (IA(24),ITEM), (IA(25),
  5)IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(35),IMS), (IA(36),IMS), (IA(37),
  6)IRD), (IA(38),IORD), (IA(39),ACEL), (IA(40),J), (IA(41),J), (IA(42),
  7)IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),
  8),J8), (IA(58),JTY), (IA(59),I8), (IA(60),I8), (IA(61),I8), (IA(62),
  9)IA), (IA(63),I8), (IA(64),I8), (IA(65),I8), (IA(66),I8), (IA(67),I8), (IA(68),
  1)C(2), (IA(70),ICF), (IA(71),ICX), (IA(72),IY), (IA(73),IZ),
  2)IA(74),IIC, (IA(75),IDEF), (IA(76),IST), (IA(77),IIS)
  3,IA(78),IGEM), (IA(79),IERR), (IA(80),TE), (IA(81),DT), (IA(82),DG),
  4)AA(83),AL1, (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P),
  5)AA(131),UV, (AA(155),X), (AA(156),Y), (AA(157),Z), (AA(179),XD),
  6)AA(186),YD, (AA(193),ZD), (AA(351),S), (AA(401),ZGFM)
  7, (AA(421),INP), (AA(443),IPBG), (AA(444),IPEN), (AA(465),CONS), (AA(466),IUE)
  8), (AA(477),G), (AA(488),G2), (AA(491),G3)
  EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346)
  1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),J50Y)
  2, (IA(341),J5DZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY)
  3, (IA(337),JMMZ), (IA(336),JMF), (IA(335),JIAS), (IA(334),I0Z)
  4, (IA(333),IPR), (AA(332),DGY), (AA(331),DGZ), (AA(330),PRFS)
  5, (IA(329),IPR)
  DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),RUG(13)
  EQUIVALENCE (AA(200),A), (AA(236),EL), (AA(237),AREA), (AA(238),I)
  1, (AA(239),J3), (AA(240),IR), (AA(241),JR), (AA(242),NY), (AA(264),DIR)
  2, (AA(306),UVG), (AA(291),PD), (AA(296),PN), (AA(297),RUG), (AA(300),T)
  IF (JMMX) I010,I010,I010
  150 ICX=ICX+JMMX
  IF (JMMY) I010,I010,I010
  150 ICY=ICY+JMMY
  150 A(1,1)=12, *E=AA(1)CYJ/(EL**3)
  A(1,2)=-A(1,1)
  A(2,1)=A(1,1)
  A(2,2)=E**AA(1)CYJ/(FL**2)
  A(7,6)=A(7,5)
  A(1,5)=-A(2,5)
  A(1,6)=-A(1,5)
  A(3,3)=G*AA(1)CXJ/FL
  A(3,4)=-A(3,3)
  A(4,4)=A(3,3)
  A(5,5)=4, *E=AA(1)CYJ/FL
  A(5,6)=-5*A(5,5)
  A(6,6)=-A(5,5)
  DD 100 J=1,4
  DD 100 J=1,6
  100 A(J,1)=A(1,J)
  110 CONTINUE
  9 IPR=1
  GO TO 9
  END
  
```

Table VII-28. Source program listing of subroutine S02 (Link 2)

```

* LABEL
CEZS02
SUBROUTINE S02
  GENRALS FOR ELEMENT TYPE 2 STIFFNESS AND LOAD MATRICES
  DIMENSION IA(1),AA(1),S(1),M(1),D21(2),D33(3,3),E22(3,3)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1)
  COMMON IA,AA
  EQUIVALENCE (IA,A1),(D21,D33),(D21(10),F22),(D21(19),F), (D21(20),G)
  EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5),
  1)PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),
  2)H),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMMZ),(IA(15),F2502009
  3)MF),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),F2502010
  4)STR),(IA(28),IFLT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMFI),
  5)IA(32),ISUM,(IA(33),IND),(IA(34),IMS),(IA(36),IBS),(IA(37),
  6)IBRD),(IA(38),IDK1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2),
  7)IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57)F2502014
  8)J8),(IA(58),J9),(IA(59),IBB),(IA(60),IBO),(IA(61),IID),(IA(62),F2502015
  9)IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITF),(IA(41),ITAP)
  EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69),
  1)ICIZ),(IA(70),ICFI),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ),
  2)IA(74),IIC),(IA(75),IDEF),(IA(76),IST),(IA(77),IST),
  3)IA(78),IGEM),(IA(79),IERR),(IA(80),TE),(IA(81),DT),(IA(82),DG),
  4)IA(83),AL1),(IA(84),AL2),(IA(85),AL3),(IA(86),D21),(AA(107),P),
  5)AA(131),UV),(AA(135),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),
  6)AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZGEM)
  7,AA(42),INP),(AA(43),IPRG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IUEF2502024
  8),(AA(47),G1),(AA(48),G2),(AA(49),G3)
  EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346)
  1,ISD),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)
  2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)
  3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ)
  4,(IA(333),IPR),(AA(332),DGY),(AA(331),DG1),(AA(330),PRES)
  5,(IA(329),IPIR),(AA(324),PRCO)
  DIMENSION A(6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),DUG(3)
  EQUIVALENCE (AA(200),A),(AA(236),EL),(AA(237),AREA),(AA(238),I)
  1,AA(239),J1),(AA(240),J2),(AA(241),J3),(AA(242),NY),(AA(264),DIR)F2502032
  2,(AA(306),UVG),(AA(291),PD),(AA(294),PN),(AA(297),DUG),(AA(300),T)F2502035
  CALL CODI
  CALL BEAM
  IPBG=0
  IF (JPRS) 40,50,40
  DUG(1)=1
  DUG(2)=0
  DUG(3)=0
  CALL EL0
  PRCO=S*EL*PRES*PD(1)
  P(5)=-PRCO*EL/6.
  P(6)=-P(5)
  IPBG=1
  IPEN=2
  40 IF (ACEL) 60,80,60
  60 DD TO I=2
  70 DUG(1)=G1(1)
  CALL ELB
  CONS=S*EL*ACEL*AREA
  CADES=IDUG(1)*PD(1)+DUG(2)*PD(2)+CONS*EL/6.
  P(5)=P(5)-CADE
  P(6)=-P(5)
  IPBG=1
  IPEN=2
  80 II=1
  JR=1
  JR=1
  JR=1
  NY=6
  CALL RLOC
  IF (NG) 110,310,110
  110 UVG(5)=-5*DG*AL1*EL
  UVG(6)=-UVG(5)
  DD 300 I=1,INS
  300 UV(1)=UV(1)+UVG(1)
  310 CALL STRA
  RETURN
  END
  
```

Table VII-29. Source program listing of subroutine S03 (Link 2)

```

* LABEL
CEZS03
SUBROUTINE S03
  GENRALS FOR ELEMENT TYPE 3 STIFFNESS AND LOAD MATRICES
  DIMENSION IA(1),AA(1),S(1),M(1),D21(2),D33(3,3),E22(3,3)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1)
  COMMON IA,AA
  EQUIVALENCE (IA,AA),(D21,D33),(D21(10),F22),(D21(19),E1),(D21(20),G)
  EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5),
  1)PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),F2503008
  2)H),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMMZ),(IA(15),F2503009
  3)MF),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),F2503010
  4)STR),(IA(28),IFLT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMFI),
  5)IA(32),ISUM,(IA(33),IND),(IA(34),IMS),(IA(36),IBS),(IA(37),
  6)IBRD),(IA(38),IDK1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2),
  7)IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57)F2503014
  8)J8),(IA(58),J9),(IA(59),IBB),(IA(60),IBO),(IA(61),IID),(IA(62),F2503015
  9)IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITF),(IA(41),ITAP)
  EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69),
  1)ICIZ),(IA(70),ICFI),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ),
  2)IA(74),IIC),(IA(75),IDEF),(IA(76),IST),(IA(77),IST),
  3)IA(78),IGEM),(IA(79),IERR),(IA(80),TE),(IA(81),DT),(IA(82),DG),
  4)IA(83),AL1),(IA(84),AL2),(IA(85),AL3),(IA(86),D21),(AA(107),P),
  5)AA(131),UV),(AA(135),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),
  6)AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZGEM)
  7,AA(42),INP),(AA(43),IPRG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IUEF2503024
  8),(AA(47),G1),(AA(48),G2),(AA(49),G3)
  EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346)
  1,ISD),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)
  2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)
  3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ)
  4,(IA(333),IPR),(AA(332),DGY),(AA(331),DG1),(AA(330),PRES)
  5,(IA(329),IPIR),(AA(324),PRCO)
  DIMENSION A(6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),DUG(3)
  EQUIVALENCE (AA(200),A),(AA(236),EL),(AA(237),AREA),(AA(238),I)
  1,AA(239),J1),(AA(240),J2),(AA(241),J3),(AA(242),NY),(AA(264),DIR)F2503032
  2,(AA(306),UVG),(AA(291),PD),(AA(294),PN),(AA(297),DUG),(AA(300),T)F2503035
  CALL CODI
  CALL PLRF
  IPBG=0
  IPEN=1
  IF (JPRS) 40,60,40
  40 PRCO=S*EL*PRES
  P(1)=PKC*(P(1)
  50 P(2)=PKC*(P(2)
  P(3)=PKC*(P(3)+R1(2)/6.+P(3)
  P(4)=-P(3)+P(4)
  P(5)=PKC*(P(5)+R1(1)/6.+P(5)
  P(6)=-P(5)+P(6)
  G1 I= (60,80),IPEN
  60 IF (ACEL) 70,80,70
  70 PRCO=S*EL*ACEL*G3
  IPEN=2
  GO TO 50
  80 II=1
  JR=1
  JR=1
  JR=1
  NY=6
  CALL RLOC
  100 IF (DG2) 108,310,108
  108 DG=DG2
  110 CONTINUE
  UVG(5)=-5*DG*AL1*EL
  UVG(6)=-UVG(5)
  CALL TRAN (UVG,0)
  DD 300 I=1,INS
  300 UV(1)=UV(1)+UVG(1)
  310 CALL STRA
  1000 RETURN
  END
  
```

Table VII-30. Source program listing of subroutine S04 (Link 2)

```

* LABEL
CE2S04 SUBROUTINE S04 F2S04000
C GENERATES FOR ELEMENT TYPE 4 STIFFNESS AND LOAD MATRICES E2S04001
DIMENSION IA(1,AA1),S(1,NR),D21(21),D33(3,3),E22(3,3) E2S04002
1,PI(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11) E2S04003
COMMON IA,AA E2S04004
EQUIVALENCE(IA,AA),(D21,D33),(D21(10),E22),(D21(19),E),(D21(20),G) E2S04005
EQUIVALENCE(IA(1),IN),(IA(2),IRN),(IA(3),IT),(IA(4),IP),(IA(5), E2S04006
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),IMX),(IA(10), E2S04007
2IH),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMZ),(IA(15), E2S04008
3IMFI),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITV),(IA(27), E2S04009
4ISTR),(IA(28),ITELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET), E2S04010
5IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), E2S04011
6IORD),(IA(38),IORDI),(IA(39),ACEL),(IA(50),JI),(IA(51),J2), E2S04012
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57), E2S04013
8J),(IA(58),JY),(IA(59),IRN),(IA(60),IBO),(IA(61),IIO),(IA(62), E2S04014
9IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(67),ITAP) E2S04015
EQUIVALENCE(IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), E2S04016
1ICIZ),(IA(70),ICFI),(IA(71),IXX),(IA(72),IYY),(IA(73),ITZ), E2S04017
2IA(74),IC),(IA(75),IDEF),(IA(76),IST),(IA(77),IIS) E2S04018
3,(IA(78),IGEM),(IA(79),IFRR),(IA(80),TE),(IA(81),DT),(IA(82),DG), E2S04019
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(87),P), E2S04020
5(AA(131),UV),(AA(135),X),(AA(136),Y),(AA(137),Z),(AA(138),XD), E2S04021
6(AA(139),YD),(AA(143),ZD),(AA(151),S),(AA(40),ZGEM) E2S04022
7,(AA(42),IMP),(AA(43),IPRG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IIE) E2S04023
8),(AA(47),H),(AA(48),G),(AA(49),G3) E2S04024
EQUIVALENCE(IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346), E2S04025
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) E2S04026
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) E2S04027
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) E2S04028
4,(IA(333),IPR),(IA(332),DGY),(AA(331),S),(AA(330),PRES) E2S04029
5,(IA(329),IPR),(AA(324),PRCO) E2S04030
DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PN(3),PN(3),DUG(3) E2S04031
EQUIVALENCE(AA(200),A),(AA(236),EL),(AA(237),AREA),(AA(238),I) E2S04032
1,(AA(239),J),(AA(240),IR),(AA(241),JR),(AA(242),NY),(AA(264),DIR) E2S04033
2,(AA(306),UVG),(AA(291),PD),(AA(294),PN),(AA(297),DUG),(AA(300),T) E2S04034
CALL CDDI E2S04035
IPBG=0 E2S04036
IF(IPRS) 40,60,40 E2S04037
40 DUG(1)=1. E2S04038
DUG(2)=0. E2S04039
DUG(3)=0. E2S04040
CALL EL01 E2S04041
50 PRCD=5*EL*PRES*PD(1) E2S04042
P(7)=PRCD*EL*PN(1)/6. E2S04043
P(8)=-P(7) E2S04044
P(9)=PRCD*EL*PN(2)/6. E2S04045
P(10)=-P(9) E2S04046
P(11)=PRCD*EL*PN(3)/6. E2S04047
P(12)=-P(11) E2S04048
IPBG=1 E2S04049
IPEN=3 E2S04050
60 IF (ACEL) 70,90,70 E2S04051
70 DD 80 I=1,3 E2S04052
80 DUG(I)=G(I) E2S04053
CALL EL01 E2S04054
CUNS=5*EL*ACEL*AREA E2S04055
CACE=IDUG(I)*PD(1)+DUG(2)*PN(2)+DUG(3)*PD(3)+CUNS*EL/6. E2S04056
P(7)=P(7)+CACE*PN(1) E2S04057
P(8)=-P(7) E2S04058
P(9)=P(9)+CACE*PN(2) E2S04059
P(10)=-P(9) E2S04060
P(11)=P(11)+CACE*PN(3) E2S04061
P(12)=-P(11) E2S04062
IPRG=1 E2S04063
IPEN=3 E2S04064
90 CALL BEAM E2S04065
I1=5 E2S04066
JR=11 E2S04067
JR=3 E2S04068
NY=2 E2S04069
CALL RLDC E2S04070
J1=5 E2S04071
J1=11 E2S04072
CALL RLDC E2S04073
I1=1 E2S04074
I1=3 E2S04075
CALL RLDC E2S04076
I1=1 E2S04077
I1=11 E2S04078
I1=1 E2S04079
I1=11 E2S04080
I1=1 E2S04081
I1=11 E2S04082
CALL RLDC E2S04083
CALL PLHF E2S04084
IR=5 E2S04085
JR=5 E2S04086
NY=6 E2S04087
CALL RLDC E2S04088
IF (DGT) 120,125,120 E2S04089
120 UVG(9)=5*DDG*AL1*EL E2S04090
UVG(10)=UVG(9) E2S04091
125 IF (DGY) 200,210,200 E2S04092
200 UVG(11)=5*DDG*AL1*EL E2S04093
HVG(12)=UVG(11) E2S04094
210 CALL TRM (HVG,0) E2S04095
DO 300 I=1,IDS E2S04096
300 UV(I)=UV(I)+HVG(I) E2S04097
310 CALL STRA E2S04098
1000 RETURN E2S04099
END E2S04100

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Table VII-31. Source program listing of subroutine S05 (Link 2)

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* LABEL
CE2S05 SUBROUTINE S05 E2S05000
C GENERATES FOR ELEMENT TYPE 5 STIFFNESS AND LOAD MATRICES E2S05001
DIMENSION IA(1,AA1),S(1,NR),D21(21),D33(3,3),E22(3,3) E2S05002
1,PI(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11) E2S05003
COMMON IA,AA E2S05004
EQUIVALENCE(IA,AA),(D21,D33),(D21(10),E22),(D21(19),E),(D21(20),G) E2S05005
EQUIVALENCE(IA(1),IN),(IA(2),IRN),(IA(3),IT),(IA(4),IP),(IA(5), E2S05006
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),IMX),(IA(10), E2S05007
2IH),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMZ),(IA(15), E2S05008
3IMFI),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITV),(IA(27), E2S05009
4ISTR),(IA(28),ITELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET), E2S05010
5IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), E2S05011
6IORD),(IA(38),IORDI),(IA(39),ACEL),(IA(50),JI),(IA(51),J2), E2S05012
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57), E2S05013
8J),(IA(58),JY),(IA(59),IRN),(IA(60),IBO),(IA(61),IIO),(IA(62), E2S05014
9IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(67),ITAP) E2S05015
EQUIVALENCE(IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), E2S05016
1ICIZ),(IA(70),ICFI),(IA(71),IXX),(IA(72),IYY),(IA(73),ITZ), E2S05017
2IA(74),IC),(IA(75),IDEF),(IA(76),IST),(IA(77),IIS) E2S05018
3,(IA(78),IGEM),(IA(79),IFRR),(IA(80),TE),(IA(81),DT),(IA(82),DG), E2S05019
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(87),P), E2S05020
5(AA(131),UV),(AA(135),X),(AA(136),Y),(AA(137),Z),(AA(138),XD), E2S05021
6(AA(139),YD),(AA(143),ZD),(AA(151),S),(AA(40),ZGEM) E2S05022
7,(AA(42),IMP),(AA(43),IPRG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IIE) E2S05023
8),(AA(47),H),(AA(48),G),(AA(49),G3) E2S05024
EQUIVALENCE(IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346), E2S05025
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) E2S05026
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) E2S05027
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) E2S05028
4,(IA(333),IPR),(IA(332),DGY),(AA(331),S),(AA(330),PRES) E2S05029
5,(IA(329),IPR),(AA(324),PRCO) E2S05030
DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PN(3),PN(3),DUG(3) E2S05031
EQUIVALENCE(AA(200),A),(AA(236),EL),(AA(237),AREA),(AA(238),I) E2S05032
1,(AA(239),J),(AA(240),IR),(AA(241),JR),(AA(242),NY),(AA(264),DIR) E2S05033
2,(AA(306),UVG),(AA(291),PD),(AA(294),PN),(AA(297),DUG),(AA(300),T) E2S05034
CALL CDDI E2S05035
IPBG=0 E2S05036
IF(IPRS) 40,60,85 E2S05037
40 IF (IT1) 71,71,85 E2S05038
71 KAV=NAV E2S05039
GO TO 180,80,851,KAV E2S05040
80 P(11)=5*PRES*YD(1)/CFE E2S05041
P(2)=P(11) E2S05042
P(4)=-5*PRES*XO(1)/CFE E2S05043
P(5)=P(4) E2S05044
85 IF (ACEL) 90,9,90 E2S05045
90 CONS=TE*A2*ACFL/6. E2S05046
IPBG=1 E2S05047
IPEN=2 E2S05048
PRCD=0. E2S05049
9 RETURN E2S05050
1 IERR=1 E2S05051
GO TO 9 E2S05052
END E2S05053

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**Table VII-32. Source program listing of subroutine S07 (Link 2)**

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* LAREL
CE2S07
SUBROUTINE S07
GENERATES FOR ELEMENT TYPE 7 STIFFNESS AND LOAD MATRICES
DIMENSION I(41),AA(1),S(1),N(8),D2(21),D3(3),F2(2),F22(3,3)
1,P(24),UV(24),X(8),Y(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D2,D3), (D2(10),F22), (D2(19),F1), (D2(20),G) F2S0700A
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5), I F2S07001
1PRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10), E2S07008
2IH), (IA(11),IR), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15), F2S07009
3JMF), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),JTY), (IA(27), E2S07010
4ISTR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMEF), E2S07011
5IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IDS), (IA(37), F2S07012
6IDRD), (IA(38),IORD1), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F2S07013
7IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),E2S07014
8J), (IA(58),JTY), (IA(59),IBB), (IA(60),IBO), (IA(61),ID), (IA(62), E2S07015
9IA), (IA(63),IDT), (IA(64),IOY), (IA(65),ITE), (IA(6),ITAP) E2S07016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIV), (IA(69), I F2S07017
1IC12), (IA(70),ICF1), (IA(71),ICX), (IA(72),IY), (IA(73),IZZ), E2S07018
2IA(74),ITC), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS) F2S07019
3, (IA(78),IGEM), (IA(79),IERR), (IA(80),TE), (IA(81),DT), (AA(82),OG), E2S07020
4(AA(83),AL), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P), F2S07021
5(AA(131),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD), E2S07022
6(AA(186),YD), (AA(193),ZD), (AA(251),S), (AA(40),ZGEM) F2S07023
7, (AA(42),INP), (AA(43),IPRG), (AA(44),IPEN), (AA(45),CONS), (AA(46),JHE E2S07024
8, (AA(47),G1), (AA(48),G2), (AA(49),G3) E2S07025
EQUIVALENCE (IA(340),NTIC), (IA(348),ISOT), (IA(347),ISDY), (IA(346), I F2S07026
1,JSO2), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY) E2S07027
2, (IA(341),JSD2), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY) E2S07028
3, (IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ) E2S07029
4, (IA(333),IPR), (AA(332),RGY), (AA(331),OGZ), (AA(327),CFE) E2S07030
5, (IA(329),IPR1), (AA(324),PRCO) E2S07031
DIMENSION EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4)
EQUIVALENCE (IA(200),AT), (AA(201),AT), (AA(225),O), (AA(241),DET), (AA(2 E2S07033
1(300),MOD), (AA(324),PRCO), (AA(325),ITTT), (AA(291),PD) E2S07034
DET=XD(1)+YD(2)+ZD(3)+XD(2)+YD(3)+XD(3)+ZD(2)+YD(2)+ZD(1)+YD(1)+ZD(1) E2S07035
1)+ZD(1)+YD(2)+ZD(3)+XD(3)+YD(3)+ZD(2)+YD(2)+ZD(1)+YD(1)+ZD(1) E2S07036
IF (DET) 301,1010,720 F2S07037
720 VOL=L*(V6*DET)
AT(1,1)=YD(2)-YD(1)+ZD(3)-ZD(1)-YD(3)-YD(1)+ZD(2)-ZD(1) F2S07038
AT(1,2)=YD(2)+ZD(3)+YD(3)+ZD(2) F2S07039
AT(1,3)=YD(1)+ZD(3)+YD(3)+ZD(1) F2S07040
AT(1,4)=YD(1)+ZD(2)+YD(2)+ZD(1) F2S07041
AT(2,1)=XD(2)+XD(1)+ZD(3)+ZD(1)+XD(3)+XD(1)+ZD(2)+ZD(1) F2S07042
AT(2,2)=XD(2)+XD(1)+ZD(3)+ZD(1) F2S07043
AT(2,3)=XD(1)+ZD(3)+XD(3)+ZD(1) F2S07044
AT(2,4)=XD(1)+ZD(2)+XD(2)+ZD(1) F2S07045
AT(3,1)=XD(2)+XD(1)+YD(3)+YD(1)-XD(3)+XD(1)+YD(2)+YD(1) F2S07046
AT(3,2)=XD(2)+YD(3)+XD(3)+YD(2) F2S07047
AT(3,3)=XD(1)+YD(3)+XD(3)+YD(1) F2S07048
AT(3,4)=XD(1)+YD(2)+XD(2)+YD(1) F2S07049
IPBG=0 F2S07050
IF (JPRS) 725,735,725
725 IF (ITTT-1)*(ITTT-2) 735,726,735
726 KAV=NAV
GO TO I728,728,735,KAV
PD(1)=YD(1)+ZD(2)+YD(2)+ZD(1)
PD(2)=XD(1)+ZD(2)+XD(2)+ZD(1)
PD(3)=XD(1)+YD(2)+XD(2)+YD(1)
PRCO=PRC/(6.*CFE)
IF (NAV-2) 729,731,735
731 DO 737 I=1,3
IT=I-4
DO 736 J=1,3
IT=I+4
GU TO I732,733,733,I
732 P(I)=PRCO*PD(I)/2.
733 P(1)=PRCO*PD(1)/4.
736 CONTINUE
737 DO 730 I=1,3
I4=4*I
730 P(I)=PRCO*PD(I)
IPBG=3
IPEN=3
735 IF (ACFL) 738,740,738
738 CONS=DE*ACFL/24.
IPBG=1
IPEN=3
740 TX=0.
DO 745 I=1,3
745 TX=XD(1)+XD(1)+YD(1)+YD(1)+ZD(1)+ZD(1)
TX=3*TX
IF (DET-TX) 747,747,750
747 WRITE OUTPUT TAPE 6,I,M,ITTT,DET
1 FORMAT(2PHOTHP VOLUME OF ELEMENT,Z14,12MIS TOO SMALL,E12,4,13H DISE
11REGARDH..
GO TO 1000
750 DO 780 I=1,3
DO 780 J=1,3
GO TO I752,754,755,J
752 GO TO I753,754,755,J
753 R(1,1)=O21(1)
R(1,2)=O21(4)
R(1,3)=O21(6)
R(2,1)=O21(16)
R(2,2)=O21(18)
R(3,1)=O21(11)
R(3,2)=O21(12)
R(3,3)=O21(10)
GO TO 739
754 B(1,1)=O21(4)
B(1,2)=O21(2)
B(1,3)=O21(15)
B(2,1)=O21(16)
B(2,2)=O21(19)
B(2,3)=O21(10)
B(3,1)=O21(18)
B(3,2)=O21(11)
B(3,3)=O21(20)
GO TO 775
755 R(1,1)=O21(6)
R(1,2)=O21(15)
R(1,3)=O21(13)

```

**Table VII-33. Source program listing of subroutine S09 (Link 2)**

```

* LAREL
CE2S09
SUBROUTINE S09
GENERATES FOR ELEMENT TYPE 9 STIFFNESS AND LOAD MATRICES
DIMENSION I(41),AA(1),S(1),N(8),D2(21),D3(3),F2(2),F22(3,3)
1,P(24),UV(24),X(8),Y(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D2,D3), (D2(10),F22), (D2(19),F1), (D2(20),G) F2S0900A
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5), I F2S09001
1PRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10), E2S09002
2IH), (IA(11),IR), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15), F2S09003
3JMF), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),JTY), (IA(27), E2S09010
4ISTR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMEF), E2S09011
5IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IDS), (IA(37), F2S09012
6IDRD), (IA(38),IORD1), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F2S09013
7IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),E2S09014
8J), (IA(58),JTY), (IA(59),IBB), (IA(60),IBO), (IA(61),ID), (IA(62), E2S09015
9IA), (IA(63),IDT), (IA(64),IOY), (IA(65),ITE), (IA(6),ITAP) E2S09016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIV), (IA(69), I F2S09017
1IC12), (IA(70),ICF1), (IA(71),ICX), (IA(72),IY), (IA(73),IZZ), E2S09018
2IA(74),ITC), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS) F2S09019
3, (IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),DT), (AA(82),DC), F2S09020
4(AA(83),AL), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P), F2S09021
5(AA(131),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD), E2S09022
6(AA(186),YD), (AA(193),ZD), (AA(251),S), (AA(40),ZGEM) F2S09023
7, (AA(42),INP), (AA(43),IPRG), (AA(44),IPEN), (AA(45),CONS), (AA(46),JHE E2S09024
8, (AA(47),G1), (AA(48),G2), (AA(49),G3) E2S09025
EQUIVALENCE (IA(349),NTIC), (IA(348),ISOT), (IA(347),ISDY), (IA(346), I F2S09026
1,JSO2), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY) E2S09027
2, (IA(341),JSD2), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY) F2S09028
3, (IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ) E2S09029
4, (IA(333),IPR), (AA(332),RGY), (AA(331),OGZ), (AA(327),CFE) E2S09030
5, (IA(329),IPR1), (AA(324),PRCO) E2S09031
DIMENSION AT(4,4),B(3,3),O(4,4),MOD(20),PD(3)
EQUIVALENCE (IA(200),AT), (AA(201),AT), (AA(225),O), (AA(241),DET), (AA(2 E2S09033
1(300),MOD), (AA(324),PRCO), (AA(325),ITTT), (AA(291),PD) E2S09034
DET=XD(1)+YD(2)+ZD(3)+XD(2)+YD(3)+XD(3)+ZD(2)+YD(2)+ZD(1)+YD(1)+ZD(1) E2S09035
1)+ZD(1)+YD(2)+ZD(3)+XD(3)+YD(3)+ZD(2)+YD(2)+ZD(1)+YD(1)+ZD(1) E2S09036
IF (DET) 301,1010,720 F2S09037
720 VOL=L*(V6*DET)
AT(1,1)=YD(2)-YD(1)+ZD(3)-ZD(1)-YD(3)-YD(1)+ZD(2)-ZD(1) F2S09038
AT(1,2)=YD(2)+ZD(3)+YD(3)+ZD(2) F2S09039
AT(1,3)=YD(1)+ZD(3)+YD(3)+ZD(1) F2S09040
AT(1,4)=YD(1)+ZD(2)+YD(2)+ZD(1) F2S09041
AT(2,1)=XD(2)+XD(1)+ZD(3)+ZD(1)+XD(3)+XD(1)+ZD(2)+ZD(1) F2S09042
AT(2,2)=XD(2)+XD(1)+ZD(3)+ZD(1) F2S09043
AT(2,3)=XD(1)+ZD(3)+XD(3)+ZD(1) F2S09044
AT(2,4)=XD(1)+ZD(2)+XD(2)+ZD(1) F2S09045
AT(3,1)=XD(2)+XD(1)+YD(3)+YD(1)-XD(3)+XD(1)+YD(2)+YD(1) F2S09046
AT(3,2)=XD(2)+YD(3)+XD(3)+YD(2) F2S09047
AT(3,3)=XD(1)+YD(3)+XD(3)+YD(1) F2S09048
AT(3,4)=XD(1)+YD(2)+XD(2)+YD(1) F2S09049
IPBG=0 F2S09050
IF (JPRS) 725,735,725
725 IF (ITTT-1)*(ITTT-2) 735,726,735
726 KAV=NAV
GO TO I728,728,735,KAV
PD(1)=YD(1)+ZD(2)+YD(2)+ZD(1)
PD(2)=XD(1)+ZD(2)+XD(2)+ZD(1)
PD(3)=XD(1)+YD(2)+XD(2)+YD(1)
PRCO=PRC/(6.*CFE)
IF (NAV-2) 729,731,735
731 DO 737 I=1,3
IT=I-4
DO 736 J=1,3
IT=I+4
GU TO I732,733,733,I
732 P(I)=PRCO*PD(I)/2.
733 P(1)=PRCO*PD(1)/4.
736 CONTINUE
737 DO 730 I=1,3
I4=4*I
730 P(I)=PRCO*PD(I)
IPBG=3
IPEN=3
735 IF (ACFL) 738,740,738
738 CONS=DE*ACFL/24.
IPBG=1
IPEN=3
740 TX=0.
DO 745 I=1,3
745 TX=XD(1)+XD(1)+YD(1)+YD(1)+ZD(1)+ZD(1)
TX=3*TX
IF (DET-TX) 747,747,750
747 WRITE OUTPUT TAPE 6,I,M,ITTT,DET
1 FORMAT(2PHOTHP VOLUME OF ELEMENT,Z14,12MIS TOO SMALL,E12,4,13H DISE
11REGARDH..
GO TO 1000
750 DO 780 I=1,3
DO 780 J=1,3
GO TO I752,754,755,J
752 GO TO I753,754,755,J
753 R(1,1)=O21(1)
R(1,2)=O21(4)
R(1,3)=O21(6)
R(2,1)=O21(16)
R(2,2)=O21(18)
R(3,1)=O21(11)
R(3,2)=O21(12)
R(3,3)=O21(10)
GO TO 739
754 B(1,1)=O21(4)
B(1,2)=O21(2)
B(1,3)=O21(15)
B(2,1)=O21(16)
B(2,2)=O21(19)
B(2,3)=O21(10)
B(3,1)=O21(18)
B(3,2)=O21(11)
B(3,3)=O21(20)
GO TO 775
755 R(1,1)=O21(6)
R(1,2)=O21(15)
R(1,3)=O21(13)

```

Table VII-33 (contd)

```

B(2,1)= D21(1R)
B(2,2)= D21(17)
B(2,3)= D21(13)
B(3,1)= D21(21)
B(3,2)= D21(20)
B(3,3)= D21(15)
GD TO 775
/56 GD TO (1000,757,758)J
/57 B(1,1)= D21(16)
      B(1,2)= D21(9)
      B(1,3)= D21(17)
      B(2,2)= D21(7)
      B(2,3)= D21(10)
      B(3,3)= D21(19)
      GD TO 739
/58 B(1,1)= D21(18)
      B(1,2)= D21(17)
      B(1,3)= D21(13)
      B(2,1)= D21(11)
      B(2,2)= D21(110)
      B(2,3)= D21(18)
      B(3,1)= D21(20)
      B(3,2)= D21(19)
      B(3,3)= D21(114)
      GD TO 775
/59 B(1,1)= D21(21)
      B(1,2)= D21(20)
      B(1,3)= D21(115)
      B(2,2)= D21(19)
      B(2,3)= D21(124)
      B(3,3)= D21(12)
/59 B(2,1)=B(1,2)
      B(3,1)=B(1,3)
      B(3,2)=B(2,3)
/75 CALL TRN (B,AT,0,3,4)
      IR=0-1-3
      JC=4-7-3
      CALL ADMS,IDS,0,4,IR,JC,VOL1
/80 CONTINUE
1000 RETURN
1010 IERR=1
      GO TO 1000
      END

```

```

F2509114
F2509115
F2509116
F2509117
F2509118
F2509119
F2509120
F2509121
F2509122
F2509123
F2509124
F2509125
F2509126
F2509127
F2509128
F2509129
F2509130
F2509131
F2509132
F2509133
F2509134
F2509135
F2509136
F2509137
F2509138
F2509139
F2509140
F2509141
F2509142
F2509143
F2509144
F2509145
F2509146
F2509147
F2509148
F2509149
F2509150
F2509151
F2509152
F2509153
F2509154
F2509155
F2509156

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Table VII-34. Source program listing of subroutine S11 (Link 2)

```

* LABEL
CE2S11
SUBROUTINE S11
GENERATES FOR ELEMENT TYPE 11 STIFFNESS AND LOAD MATRICES
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),E), (D21(20),G)E2511000
EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IP), (IA(4),IP), (IA(5),E2511001
1IPRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),IMX), (IA(10),E2511002
2IH), (IA(11),IR), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),E2511003
3IMF), (IA(16),IARE), (IA(17),NI), (IA(25),M), (IA(26),ITY), (IA(27),E2511004
4ISTR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMET), F2511011
5(IA(32),ISUM), (IA(33),INQ), (IA(34),IMS), (IA(36),IDS), (IA(37),E2511012
6IRRD), (IA(38),IRPD), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F2511013
7(IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),E2511014
8), (IA(58),JTY), (IA(59),IRB), (IA(60),IRU), (IA(61),IRD), (IA(62),E2511015
9(IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITE), (IA(61),ITAP) E2511016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICLY), (IA(69),E2511017
1ICIZ), (IA(70),ICFI), (IA(71),ICX), (IA(72),ICY), (IA(73),ICZ), E2511018
2(IA(74),IDEF), (IA(76),IST), (IA(77),IIS) E2511019
3(IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),DT), (AA(82),DG), E2511020
4(AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P), E2511021
5(AA(121),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD), E2511022
6(AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(40),ZGEM) E2511023
7( (AA(42),INP), (AA(43),IPRG), (AA(44),IPEN), (AA(45),CONS), (AA(46),IUE2511024
8), (AA(47),G1), (AA(48),G2), (AA(49),G3) E2511025
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346),E2511026
1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY), E2511027
2(IA(341),JSDZ), (IA(340),JRE), (IA(339),IMX), (IA(338),JMY), E2511028
3(IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ), E2511029
4(IA(333),IPR), (AA(332),DRY), (AA(331),DG2), (AA(330),PRE5) E2511030
5(IA(329),IPR) E2511031
DIMENSION EM(4,4),FN(4,4),O(4,4),DIR(3,3),DUM(18) E2511032
EQUIVALENCE (AA(200),EM), (AA(216),DUM), (AA(232),E0), (AA(248),O), E2511033
1(AA(264),DIR), (AA(276),DUM), (AA(297),A2) E2511034
C TRIANGULAR SHELL ELEMENT
CALL CDRT E2511035
CALL S07 E2511036
ISHF=6+1IDS+1 E2511037
IES5=9+IDS E2511038
DO 1 I=1,9 E2511039
IES5=IES5-IDS E2511040
IES=IES E2511041
DO 2 J=1,9 E2511042
IF5=IES+1 E2511044
IYE=IES+ISHF E2511045
S(IYE)=S(IES) E2511046
S(IYE)=0 E2511047
CONTINUE E2511048
DO 3 I=4,9 E2511049
UV(I+6)=UV(I) E2511050
DO 4 I=1,IMS E2511051
II=IMS+I E2511052
I2=IMS+11 E2511053
UV(I)=X(I)*DT*AL1 E2511054
UV(I2)=Y(I)*DT*AL2 E2511055
CALL S05 E2511056
IPEN=3 E2511058
DO 11 I=1,3 E2511059
P(I+6)=P(I) E2511060
P(I)=0 E2511061
TRANSFORM S,P,UV INTO OVERALL SYSTEM E2511062
CALL TRAN (P,0) E2511063
CALL TRAN (UV,0) E2511064
CALL STRA E2511065
RETURN E2511066
END E2511067

```

Table VII-35. Source program listing of subroutine S13 (Link 2)

```

* LABEL
CE2S13
SUBROUTINE S13
GENERATES FOR ELEMENT TYPE 13 STIFFNESS AND LOAD MATRICES
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),E), (D21(20),G)E2513000
EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IP), (IA(4),IP), (IA(5),E2513007
1IPRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),IMX), (IA(10),E2513008
2IH), (IA(11),IR), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),E2513009
3IMF), (IA(16),IARE), (IA(17),NI), (IA(25),M), (IA(26),ITY), (IA(27),E2513010
4ISTR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMET), F2513011
5(IA(32),ISUM), (IA(33),INQ), (IA(34),IMS), (IA(36),IDS), (IA(37),E2513012
6IRRD), (IA(38),IRPD), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F2513013
7(IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),E2513014
8), (IA(58),JTY), (IA(59),IRB), (IA(60),IRU), (IA(61),IRD), (IA(62),E2513015
9(IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITE), (IA(61),ITAP) F2513016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICLY), (IA(69),E2513017
1ICIZ), (IA(70),ICFI), (IA(71),ICX), (IA(72),ICY), (IA(73),ICZ), E2513018
2(IA(74),IDEF), (IA(76),IST), (IA(77),IIS) E2513019
3(IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),DT), (AA(82),DG), E2513020
4(AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P), E2513021
5(AA(121),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD), E2513022
6(AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(40),ZGEM) E2513023

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7( (AA(42),INP), (AA(43),IPRG), (AA(44),IPEN), (AA(45),CONS), (AA(46),IUE2513024
8), (AA(47),G1), (AA(48),G2), (AA(49),G3) E2513025
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346),E2513026
1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY), E2513027
2(IA(341),JSDZ), (IA(340),JRE), (IA(339),IMX), (IA(338),JMY), E2513028
3(IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ), E2513029
4(IA(333),IPR), (AA(332),DRY), (AA(331),DG2), (AA(330),PRE5) E2513030
5(IA(329),IPR) E2513031
EQUIVALENCE (AA(291),A2), (AA(324),PRC0) E2513032
CALL CDRT E2513033
CALL S05 E2513034
CNT=PRCS*42/6 E2513035
P(B)=CNT E2513036
P(Y)=CNT E2513037
P(Z)=CNT E2513038
IPEN=3 E2513039
IGEM=IGEM E2513040
IGEM=0 E2513041
CALL TRAN (P,0) E2513042
CALL STRA E2513043
IGEM=IGEM E2513044
RETURN E2513045
END E2513046

```



Table VII-36. Source program listing of subroutine S15 (Link 2)

```

* LABEL
CE2S15 SUBROUTINE S15
GENERATES FOR ELEMENT TYPE 15 STIFFNESS AND LOAD MATRICES
DIMENSION IAL1,AA(1),S(1),T(1),O21(21),D33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (O21,O33), (O21(10),E22), (O21(19),E), (O21(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5),
1IPRS), (IA(6),IYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),IMK), (IA(10),
2IH), (IA(11),IB), (IA(12),IMKX), (IA(13),IMKY), (IA(14),IMMZ), (IA(15),
3IMF1), (IA(16),IARE), (IA(17),T(1)), (IA(25),O), (IA(26),IY), (IA(27),
4ISTR1), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMET),
5IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IOS), (IA(37),
6IURD), (IA(38),IDRO1), (IA(39),ACEL), (IA(50),J1), (IA(51),J2),
7IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),
8J8), (IA(58),J9), (IA(59),J8B), (IA(60),IBH), (IA(61),ID), (IA(62),
9IA(1), (IA(63),ID), (IA(64),IDY), (IA(65),ITF), (IA(66),ITPP)
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIX), (IA(69),
1ICIZ), (IA(70),ICF1), (IA(71),IXX), (IA(72),IYY), (IA(73),I77),
2IA(74),IIC), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS)
3, (IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),OT), (AA(82),DG),
4(AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P),
5, (AA(131),UV), (AA(135),X), (AA(163),Y), (AA(171),Z), (AA(179),XD),
6(AA(186),YD), (AA(193),ZD), (AA(195),S), (AA(401),ZGEM)
7, (AA(421),IMP), (AA(43),IPR), (AA(44),IPEN), (AA(45),CONS1), (AA(46),
8I, (AA(47),G), (AA(48),G2), (AA(49),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346),
1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),J50Y)
2, (IA(341),J50Z), (IA(340),JARE), (IA(339),JMKX), (IA(338),JMKY)
3, (IA(337),JMKZ), (IA(336),JMF1), (IA(335),IYAS), (IA(334),IDZ)
4, (IA(333),IPR), (AA(332),DRY), (AA(331),DG2), (AA(330),PRES)
5, (IA(329),IPR), (IA(328),NAV), (IA(327),GFF), (IA(325),ITTT)
DIMENSION EM(4,4),EN(4,4),O(4,4),EO(4,4),CAX(4),Z21(21),V(3)
EQUIVALENCE (AA(200),EM), (AA(216),EN), (AA(232),EO), (AA(248),O)
1, (AA(291),A2), (AA(292),IAX), (AA(293),CAX), (AA(264),Z21)
EQUIVALENCE (AA(297),XBAR), (AA(298),YBAR), (CAX,V)
C SET RUNDOS FOR X SUB1 AND X SUB1,I+1
IR2=0,1
ER1=1,E=4
XBAR=(X(1)+X(2)+X(3))/3,
TER=TE
TB=XBAR
DO 91 I=1,21
Z21(I)=O21(I)
D33(1,1)=Z21(1)
D33(1,2)=Z21(2)
D33(1,3)=Z21(3)
D33(1,4)=Z21(4)
D33(2,2)=Z21(7)
D33(2,3)=Z21(9)
D33(3,3)=Z21(16)
D33(2,1)=D33(1,2)
D33(3,1)=D33(1,3)
D33(3,2)=D33(2,3)
CALL S05
CALL TRM
YBAR=(Y(1)+Y(2)+Y(3))/3,
YBAR=0,
E22(1,3)=Z21(3)
E22(2,3)=Z21(8)
E22(3,3)=Z21(13)
DO I=1,3
E22(I,1)=XBAR*E22(1,3)
E22(I,2)=YBAR*E22(1,3)
F1=1/(2*AA2)
EQ(3,1)=X(2)*Y(3)-YBAR-X(3)*Y(2)-YBAR
EQ(3,2)=X(3)*Y(1)-YBAR-X(1)*Y(3)-YBAR
EQ(3,3)=X(1)*Y(2)-YBAR-X(2)*Y(1)-YBAR
C COMPUTE THE INTEGRATION CONSTANT
DO 15 I=1,3
V(I)=Y(I)-YBAR
DO 32 J=1,4
DO 32 K=1,4
U(I,J)=0,
LL=0
NN=0
DO 17 I=1,3
IF (X(I)) 120,20,121
121 IF (X(I)-ER1) 20,20,51
120 IERR=1
RETURN
IAX=1
GO TO 17
20 NN=NN+1
LL=1
C CONTINUE
IF (NN-1) 8,8,102
8 MM=0
DO 11 L=1,3
IF (L) 81,81,82
M=1
81 KX=X(M)-X(L)
YY=V(M)-V(L)
IF (ABSF(XXX/SDRTF(XXX*XXX+YYY*YYY))-EK2) 21,21,22
21 O22=0,
D23=0,
D33=YYY
GO TO 50
22 IF (ABSF(X(M)*X(L)-ER1) 24,24,40
24 IF (MM) 11,23,11
23 MM=1
IF (LL-L) 26,25,26
26 N=M+1
IF (N-3) 27,27,28
28 N=1
DO TD 29
29 N=M
M=L
29 K=N+1
IF (K-3) 30,30,31
31 K=1
30 GG=LNDFIX(X)/X(IN)
YRN=(X(-V)-X(V))
O33=(N*GG)
O23=2*V(IN)**2*GG+YRN*(2*V(M)+V(N)+V(K))
O22=6*V(M)**3*GG+YRN*(2*(V(IN)**2*V(N)+V(K)+V(K)**2)
1 +6*V(M)**2+1*V(M)*V(IN)+V(K))
GO TO 50
40 GG=LNDFIX(X)/X(L)
F=X(L)*V(N)-X(M)*V(L)/XXX
O33=F*GG
O23=YYY*3,GF+(X(L)*V(L)-X(M)*V(M))/XXX-2*GF**2*GG
O22=YYY*(V(M)**2+V(L)*X(M)**2-7*X(L)*X(M)+2*X(L)**2)
1 -V(L)*V(M)**5*X(L)**2+5*X(M)**2-22*X(L)*X(M))/XXX**2
2 +2*GF**3*GG
3 O(2,2)=O(2,2)+O22/19*AA2
O(2,3)=O(2,3)+O23/12*AA2
O(3,3)=O(3,3)+O33/10*AA2
11 CONTINUE
O(1,1)=XBAR
O(1,2)=YBAR
O(1,3)=1
O(2,1)=O(1,2)
O(3,1)=O(1,3)
O(3,2)=O(2,3)
IAX=4
102 CONTINUE
DO 2 J=1,3
D33(J,1)=Z21(121+O(J,1))
CALL TRM (D33,EO,Q,3,3)
CAX(1)=0,
CAX(2)=0,
CAX(3)=0,
CAX(IAX)=1,
O(1,AX)=Z71(12)*XBAR*(CAX(1)+N(3,1)+CAX(2)*EM(3,2)+CAX(3)*
1 EN(3,3))**2
CALL ADM IS,IDS,O,3,1,1,F1)
CALL TRM IE2,EO,EN,3,-3)
CALL ADM IS,IDS,EN,3,4,1,F1)
CALL TRM IE22,EO,EN,3,-3)
GO 3 J=1,3
DO 3 J=1,3
3 EM(1,J)=EM(1,J)+EM(J,1)
EM(2,1)=EM(1,2)
EM(3,1)=EM(1,3)
EM(3,2)=EM(2,3)
CALL ADM IS,IDS,EM,3,1,1,F1)
TE=TE
TER=(X(1)-XBAR)*(Y(2)-YBAR)-(X(2)-XBAR)*Y(1)-YBAR)/12*AA2
CONS=TE*AGEL*AA2/4,
O(1,1)=TER*(X(1)-XBAR)**2+(X(1)-XBAR)*X(2)-XBAR+(X(2)-XBAR)**2+
1 *XBAR**2
O(2,1)=TER*(Y(1)-YBAR)*2*(X(1)-XBAR)+(X(2)-XBAR)+Y(2)-YBAR*
1 (X(1)-XBAR)+2*(X(2)-XBAR)/12,
O(3,1)=XBAR
DO 4 I=1,3
O(1,2)=0,
DO 5 K=1,3
5 O(1,2)=O(1,2)+EO(I,K)*O(K,1)
4 CONTINUE
DO 6 J=1,3
P(1+3)=CONS*O(1,2)
6 P(1+3)=CONS*O(1,2)
IF (JPRS) 70,85,70
70 IF (ITTT-1) 71,71,85
71 KAV=NAV
GO TO (R0,80,85),KAV
CONS=M(1)/3+(X(2)/K,)*PRES/CFE
TER=(X(1)/6+(X(2)/5,)*PRES/CFE
P(1)=P(1)+O(1,1)*CONS
P(2)=P(2)+O(1,1)*TER
P(4)=P(4)-X(1)*CONS
P(5)=P(5)-X(1)*TER
85 CONS=0,
IERR=1
DO 92 I=1,21
D21(I)=Z21(I)
92 RETURN
END

```

Table VII-37. Source program listing of subroutine S17 (Link 2)

```

* LABEL
CE2S17
SUBROUTINE S17
GENERATES FOR ELEMENT TYPE 17 STIFFNESS AND LOAD MATRICES
DIMENSION I(11),AA(1),S(1),N(1),D2(2),D3(3),E22(3,3)
1 P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA),(D2,D3),(E22),(D21,D31),E,(D21,D31),G,E2S17006
EQUIVALENCE (IA(1),IN),(IA(2),IRN),(IA(3),IT),(IA(4),IP),(IA(5),  F2S17007
1)PKS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),F2S17008
2)H),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMZ),(IA(15),E2S17009
3)MF),(IA(16),IARE),(IA(17),N(1)),(IA(25),R),(IA(26),ITY),(IA(27),  E2S17010
4)STR),(IA(28),IFL1),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMEF),  F2S17011
5)IA(32),ISUM),(IA(33),INDI),(IA(34),IMS),(IA(35),IDS),(IA(37),  E2S17012
6)IRD),(IA(38),IRD1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2),  F2S17013
7)IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),F2S17014
8)J8),(IA(58),JTY),(IA(59),IBB),(IA(60),IROI),(IA(61),ID),(IA(62),E2S17015
9)IA),(IA(63),IDI),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP) F2S17016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69),  E2S17017
1)ICIZ),(IA(70),ICF1),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ),  F2S17018
2)IA(74),ITC),(IA(75),IDEF),(IA(76),IST),(IA(77),IS) F2S17019
3),(IA(78),IGEM),(IA(79),IFRR),(IA(80),TE),(IA(81),DT),(AA(82),DG), F2S17020
4)AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),O2),(AA(107),P), E2S17021
5)AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), F2S17022
6)AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F2S17023
7),(AA(42),INP),(AA(43),IPBG),(AA(44),IPEN),(AA(45),CONSI),(AA(46),IUE2S17024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F2S17025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISD1),(IA(347),ISDY),(IA(346)  F2S17026
1),ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPKS),(IA(342),JSOY) F2S17027
2),(IA(341),JSD2),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F2S17028
3),(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) F2S17029
4),(IA(333),IPR),(AA(332),DGY),(AA(331),DGZ),(AA(330),PRES) F2S17030
5),(IA(329),IPR) F2S17031
DIMENS ION EM(4,4),EN(4,4),O(4,4),EO(4,4) F2S17032
EQUIVALENCE (AA(200),EM),(AA(216),EN),(AA(232),EO),(AA(248),O), F2S17033
1)AA(264),F1),(AA(265),F2),(AA(266),RBY),(AA(267),XAV) F2S17034
ER1=1-E
BODY=SQRTF (XD(1)**2+YD(1)**2)
XAV=(X(1)+X(2))/2.
IF (BODY) 1,1,4
2 IF (XAV) 1,1,4
41 IF (X(11)) 1,4,4,3
42 IF (X(2)) 1,4,4,4
43 IF (X(11)/BODY
44 AL=XD(1)/BODY
RE=YD(1)/BODY
GA=BODY/XAV
Q(1,1)=-AL
Q(1,2)=AL
Q(1,3)=-BE
Q(1,4)=GE
F1=TE*GA
CALL TRM (D33,Q,F,4)
CALL ADM (S,IDS,FU,4,1,1,F1)
F1=TE*O33(1,2)
Q(1,1)=-AL
Q(2,1)=-AL
Q(1,2)=O
Q(2,1)=O
CALL ADM (S,IDS,Q,2,1,1,F1)
Q(1,1)=-BE*F
Q(2,1)=O(1,1)
Q(1,2)=-O(1,1)
Q(2,2)=O(1,2)
CALL ADM (S,IDS,Q,2,1,3,F1)
IF (ABS(F1)-ER1) 24,24,25
24 F1=TE*O33(2,2)*GA
Q(1,1)=O.3333333
Q(1,2)=O(1,1)/2.
Q(2,1)=O(1,2)
Q(2,2)=O(1,1)
GO TO 30
25 IF (X(11)*X(2)) 26,23,26
23 F1=TE*O33(2,2)/2.*AL
IF (X(2)) 27,27,29
27 F1=F2
Q(1,1)=1.
Q(1,2)=-1.
Q(2,1)=-1.
Q(2,2)=1.
GO TO 30
26 GUL=LGF(X(2)/X(1))
AL=BOY*GUL/XD(1)
R1=1.-X(1)*GUL/XD(1)*BOY/XD(1)
C1=(XAV/XD(1))-2.*X(1)/XD(1)+(X(1)/XD(1))**2*GUL/BOY/XD(1)
F1=TE*O33(2,2)
Q(1,1)=A1+C1-2.*R1
Q(1,2)=B1-C1
Q(2,1)=O(1,2)
Q(2,2)=C1
30 CALL ADM (S,IDS,Q,2,1,1,F1)
IPRG=-1
F1=PRE*YD(1)+BOY*ACEL*TE*G1
F2=PKF*X(1)+BOY*ACEL*TE*G2
AL=X(1)/3.+X(2)/3.
BE=X(1)/6.+X(2)/3.
P(1)=F1*AL
P(2)=F1*BE
P(3)=F2*AL
P(4)=F2*BE
9 RETURN
1 IERR=1
GO TO 9
END

```

Table VII-38. Source program listing of subroutine S18 (Link 2)

```

* LABEL
CE2S18
SUBROUTINE S18
GENERATES FOR ELEMENT TYPE 18 STIFFNESS AND LOAD MATRICES
DIMENSION I(11),AA(1),S(1),N(1),D2(2),D3(3),E22(3,3)
1 P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA),(D2,D3),(D21,D31),E,(D21,D31),G,E2S18006
EQUIVALENCE (IA(1),IN),(IA(2),IRN),(IA(3),IT),(IA(4),IP),(IA(5),  F2S18007
1)PKS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),F2S18008
2)H),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMZ),(IA(15),F2S18009
3)MF),(IA(16),IARE),(IA(17),N(1)),(IA(25),R),(IA(26),ITY),(IA(27),  E2S18010
4)STR),(IA(28),IFL1),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMEF),  F2S18011
5)IA(32),ISUM),(IA(33),INDI),(IA(34),IMS),(IA(35),IDS),(IA(37),  E2S18012
6)IRD),(IA(38),IRD1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2),  F2S18013
7)IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),F2S18014
8)J8),(IA(58),JTY),(IA(59),IBB),(IA(60),IROI),(IA(61),ID),(IA(62),E2S18015
9)IA),(IA(63),IDI),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP) F2S18016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69),  F2S18017
1)ICIZ),(IA(70),ICF1),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ),  F2S18018
2)IA(74),ITC),(IA(75),IDEF),(IA(76),IST),(IA(77),IS) F2S18019
3),(IA(78),IGEM),(IA(79),IFRR),(IA(80),TE),(IA(81),DT),(AA(82),DG), E2S18020
4)AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),O2),(AA(107),P), E2S18021
5)AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), F2S18022
6)AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F2S18023
7),(AA(42),INP),(AA(43),IPBG),(AA(44),IPEN),(AA(45),CONSI),(AA(46),IUE2S18024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F2S18025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISD1),(IA(347),ISDY),(IA(346)  F2S18026
1),ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPKS),(IA(342),JSOY) F2S18027
2),(IA(341),JSD2),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F2S18028
3),(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) F2S18029
4),(IA(333),IPR),(AA(332),DGY),(AA(331),DGZ),(AA(330),PRES) F2S18030
5),(IA(329),IPR) F2S18031
DIMENS ION EM(4,4),EN(4,4),O(4,4),EO(4,4) F2S18032
EQUIVALENCE (AA(200),EM),(AA(216),EN),(AA(232),EO),(AA(248),O), F2S18033
1)AA(264),F1),(AA(265),F2),(AA(266),RBY),(AA(267),XAV) F2S18034
ER1=1-E
BODY=SQRTF (XD(1)**2+YD(1)**2)
XAV=(X(1)+X(2))/2.
IF (BODY) 1,1,4
2 IF (XAV) 1,1,4
10 IF (X(11)) 26,23,26
26 IF (X(11)*X(2)) 28,27,28
27 F1=TE*O33(2,2)*F2*XD(1)/2.*BOY
IF (X(2)) 27,27,29
27 F1=F2
GO TO 29
28 F1=F2*O33(2,2)*(XD(1)/BOY)**2
29 CALL ADM (S,IDS,Q,2,5,5,F1)
25 F1=TE*O33(1,1)*XAV/BOY
Q(1,1)=1.
Q(1,2)=-1.
Q(2,1)=-1.
Q(2,2)=1.
CALL ADM (S,IDS,Q,2,5,5,F1)
Q(1,1)=1.
Q(2,1)=1.
Q(2,2)=1.
CALL ADM (S,IDS,Q,2,5,5,F1)
Q(1,1)=YD(1)
EM(1,2)=-YD(1)
EM(1,3)=-XD(1)
EM(1,4)=-XD(1)
CALL TRM (E22,EM,Q,1,4)
CALL ADM (S,IDS,Q,4,1,1,F1)
Q(1,1)=BOY**4/4.
Q(1,2)=O(1,1)
Q(2,1)=O(1,1)
Q(2,2)=O(1,1)
F1=FL*E22(1,1)
CALL ADM(S,IDS,Q,2,5,5,F1)
Q(1,1)=-BOY**2*YD(1)/2.
Q(1,2)=O(1,1)
Q(2,1)=-O(1,1)
Q(2,2)=-O(1,1)
CALL ADM (S,IDS,Q,2,1,5,F1)
Q(1,1)=-BOY**2)*XD(1)/2.
Q(1,2)=O(1,1)
Q(2,1)=-O(1,1)
Q(2,2)=-O(1,1)
CALL ADM (S,IDS,Q,2,3,5,F1)
UV(5)=O.
IF(6)=DG*BOY*AL1
RETURN
60 END

```

**Table VII-39. Source program listing of subroutine STFS (Link 2)**

```

* LABEL
CE2STF
SUBROUTINE STFS (JFLT)
SELECTS PROPER SUBROUTINE FOR GENERATION OF ELEMENT MATRICES
IELT=IELT
GO TO (1,2,3,4,5,5,7,7,8,8,9,9,10,10,11,11,12,13), IELT
1 CALL S01
GO TO 100
2 CALL S02
GO TO 100
3 CALL S03
GO TO 100
4 CALL S04
GO TO 100
5 CALL S05
GO TO 100
7 CALL S07
GO TO 100
8 CALL S09
GO TO 100
9 CALL S11
GO TO 100
10 CALL S13
GO TO 100
11 CALL S15
GO TO 100
12 CALL S17
GO TO 100
13 CALL S18
GO TO 100
100 RETURN
END
F2STF000
F2STF001
F2STF002
F2STF003
F2STF004
F2STF005
F2STF006
F2STF007
F2STF008
F2STF009
F2STF010
F2STF011
F2STF012
F2STF013
F2STF014
F2STF015
F2STF016
F2STF017
F2STF018
F2STF019
F2STF020
F2STF021
F2STF022
F2STF023
F2STF024
F2STF025
F2STF026
F2STF027
F2STF028
F2STF029

```

**Table VII-41. Source program listing of subroutine TICK (Link 2)**

```

* FAP COUNT 25
TICK CBL TICK
TICK ENTRY TICK
TICK NZT ONCE
TICK TRA FIRST
TICK CAL 5
TICK SUB INITL
TICK ALS 18
TICK SLW* 1,4
TICK TRA 2,4
TICK FIRST STL ONCE
TICK CAL 5
TICK SLW INITL
TICK SLZ* 1,4
TICK TRA 2,4
TICK ONCE PZE
TICK INIIL PZE
TICK END
TICK000
TICK001
TICK002
TICK003
TICK004
TICK005
TICK006
TICK007
TICK008
TICK009
TICK010
TICK011
TICK012
TICK013
TICK014
TICK015
TICK016
TICK017
TICK018

```

**Table VII-40. Source program listing of subroutine STRA (Link 2)**

```

* LABEL
CE2STR
SUBROUTINE STRA
TRANSFORMS DESCRIPTION OF ELEMENT MATRICES FROM LOCAL TO OVERALL
DIMENSION IA(1),AA(1),S(1),N(8),D2(2),D3(3),P(2),P2(3),3
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA-AA), (D2-D3), (D2(1)-E221, D2(15)-E), (D2(20)-G)
EQUIVALENCE (IA(1),IA(2),IA(3),IA(4),IA(5),IA(6),IA(7),IA(8),IA(9),IA(10),IA(11),IA(12),IA(13),IA(14),IA(15),IA(16),IA(17),IA(18),IA(19),IA(20),IA(21),IA(22),IA(23),IA(24))
11PRS1, (IA(16), ITYPE), (IA(17), IMA1), (IA(18), IDEG1), (IA(19), INK), (IA(20), INK), (IA(21), INK), (IA(22), INK), (IA(23), INK), (IA(24), INK)
2IH, (IA(11), I8), (IA(12), IMM), (IA(13), IMY), (IA(14), IMM2), (IA(15), IMM3)
3IMP11, (IA(16), IARE), (IA(17), N11), (IA(25), M), (IA(26), IY), (IA(27), IY)
4ISTR, (IA(12), IELT), (IA(29), IEM), (IA(30), ITC), (IA(31), IET)
5(IA(32), ISUM), (IA(33), IOR), (IA(34), IMS), (IA(35), IDS), (IA(37), IOR)
6IOR), (IA(38), IORD1), (IA(39), ACEL 1), (IA(50), J1), (IA(51), J2),
7(IA(52), J3), (IA(53), J4), (IA(54), J5), (IA(55), J6), (IA(56), J7), (IA(57), J8), (IA(58), J9), (IA(59), J10), (IA(60), IBD), (IA(61), IBD), (IA(62), IBD)
91IA, (IA(163), IOT), (IA(164), IOT), (IA(65), IPI), (IA(61), IAP)
EQUIVALENCE (IA(66), ICAR), (IA(67), ICIX), (IA(68), ICIX), (IA(69), ICIX)
11G12, (IA(70), ICF), (IA(71), IAK), (IA(72), IY), (IA(73), IZ),
2(IA(74), IIC), (IA(75), IDEF), (IA(76), IS), (IA(77), IS)
3(IA(78), IGM), (IA(79), IERK), (IA(80), TE), (IA(81), OT), (AA(82), DG)
4(AA(83), AL1), (AA(84), AL2), (AA(85), AL3), (AA(86), D21), (AA(107), P),
5(AA(131), UV), (AA(155), X), (AA(163), Y), (AA(171), Z), (AA(179), XD),
6(AA(186), YD), (AA(193), ZD), (AA(351), S), (AA(140), ZGEM)
7(AA(147), INP), (AA(143), IPBG), (AA(44), IPEN), (AA(45), GNS), (AA(46), IUE)
8(IA(47), G1), (AA(48), G2), (AA(49), G3)
EQUIVALENCE (IA(349), ATIC), (IA(348), ISD), (IA(347), ISD), (IA(346), ISD)
1( ISD), (IA(345), J9), (IA(344), J10), (IA(343), JPR5), (IA(342), JSBY)
2(IA(341), JSZ), (IA(340), JARE), (IA(339), JMMX), (IA(338), JMMY)
3(IA(337), JMMZ), (IA(336), JMF), (IA(335), IAS), (IA(334), IY)
4(IA(333), IPR), (IA(332), DGY), (IA(331), DZ), (IA(330), PRES)
5(IA(329), IPIR)
J=105
DO 5 I=1, IDS
J=J+IDS
CALL TRAN (S, J)
CONTINUE
IARB=-IDS
IEBB=-IDS
DO 6 I=1, IDS
IARB=IARB+I
IEBB=IEBB+IDS
IHE=IFBB
DO 7 J=1, IOS
IAB=IAB+IOS
IE=IE+I
IF IAB=IEI 7,7,13
TEMP=IAB
S(IAB)=S(IAB)
S(IAB)=TEMP
CONTINUE
CONTINUE
J=105
DO 8 I=1, IOS
J=J+IOS
CALL TRAN (S, J)
CONTINUE
RETURN
END
F2STR000
F2STR001
F2STR002
F2STR003
F2STR004
F2STR005
F2STR006
F2STR007
F2STR008
F2STR009
F2STR010
F2STR011
F2STR012
F2STR013
F2STR014
F2STR015
F2STR016
F2STR017
F2STR018
F2STR019
F2STR020
F2STR021
F2STR022
F2STR023
F2STR024
F2STR025
F2STR026
F2STR027
F2STR028
F2STR029
F2STR030
F2STR031
F2STR032
F2STR033
F2STR034
F2STR035
F2STR036
F2STR037
F2STR038
F2STR039
F2STR040
F2STR041
F2STR042
F2STR043
F2STR044
F2STR045
F2STR046
F2STR047
F2STR048
F2STR049
F2STR050
F2STR051
F2STR052
F2STR053
F2STR054
F2STR055
F2STR056
F2STR057
F2STR058
F2STR059

```

Table VII-42. Source program listing of subroutine TOPO (Link 2)

```

* LABEL
CEZTOP SUBROUTINE TOPO E270P000
PREPARES ELEMENT PROPERTIES E270P001
DIMENSION IA(11),AA(1),S(1),N(8),D21(21),D33(3,3),E27(3,3) E270P002
1,P(24),UV(24),X(8),Y(8),Z(8),XD(17),YD(17),ZD(17),G(11) E270P003
GUMMIN IA,AA E270P004
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),E22),(D21(19),E),D21(20),G E270P005
EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), E270P007
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),E270P008
2IH),(IA(11),I8),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),E270P009
3IMF),(IA(16),IARE),(IA(17),N(1)),(IA(18),M),(IA(19),ITV),(IA(20),E270P010
4ISTR),(IA(21),IELT),(IA(22),ITEM),(IA(30),ITIC),(IA(31),IMET), E270P011
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), E270P012
6IORD),(IA(38),IORD),(IA(39),AGEL),(IA(50),J),(IA(51),J2), E270P013
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E270P014
8)J8),(IA(58),JTY),(IA(59),IBB),(IA(60),I80),(IA(61),I1D),(IA(62),E270P015
9)IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(43),ITAP) E270P016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69), E270P017
1ICIZ),(IA(70),ICF),(IA(71),IXR),(IA(72),IYY),(IA(73),I2Z), E270P018
2(IA(74),IIC),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS) E270P019
3,(IA(78),IGEM),(IA(79),IERR),(IA(80),TE),(IA(81),DT),(IA(82),DG), E270P020
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P), E270P021
5(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), E270P022
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZGEM) E270P023
7,(AA(42),INP),(AA(43),IPRG),(AA(44),IPRN),(AA(45),CONS),(AA(46),IUE270P024
8),(AA(47),GL),(AA(48),G2),(AA(49),G3) E270P025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346) E270P026
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) E270P027
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) E270P028
3,(IA(337),JMMZ),(IA(336),JMF),(IA(335),ITAS),(IA(334),IDZ) E270P029
4,(IA(333),IPR),(IA(332),DGY),(AA(331),DG2),(AA(330),PRES) E270P030
5,(IA(329),IPR) E270P031
IELT=0 E270P032
ITEM=0 E270P033
ITJC=0 E270P034
IMET=0 E270P035
DO LO I=1,8 E270P036
N(1)=0 E270P037
K=1-395 E270P038
IAK=1+0 E270P039
JM=J1+M E270P040
IELT=IA(JM)/100 E270P041
IMET=IA(JM)-100*IELT E270P042
JM=J2+M E270P043
IF (IELT-4) 100,100,450 E270P044
IF (IELT-3) 200,300,200 E270P045
JARE=IA(JM)/100 E270P046
ITEM=IA(JM)-100*JARE E270P047
GO TO 400 E270P048
JPRS=IA(JM)/100 E270P049
JSDZ=IA(JM)-100*JPRS E270P050
IF (IELT-3) 600,800,800 E270P051
IF (IELT-10) 470,470,500 E270P052
IF (IELT-8) 500,500,480 E270P053
JPRS=IA(JM)/100 E270P054
ITEM=IA(JM)-100*JPRS E270P055
L=1 E270P056
GO TO 1000 E270P057
ITIC=IA(JM)/100 E270P058
ITEM=IA(JM)-100*ITIC E270P059
JM=J3+M E270P060
JSDZ=IA(JM)/100 E270P061
JPRS=IA(JM)-100*JSDZ E270P062
L=2 E270P063
GO TO 1000 E270P064
JM=J4+M E270P065
JPRS=IA(JM) E270P066
L=2 E270P067
IF (IELT-2) 1000,700,700 E270P068
JM=J4+M E270P069
JMMZ=IA(JM)/100 E270P070
JSDY=IA(JM)-100*JMMZ E270P071
L=3 E270P072
IF (IELT-4) 1000,900,1000 E270P073
JM=J3+M E270P074
JMMX=IA(JM)/100 E270P075
JMMY=IA(JM)-100*JMMX E270P076
L=2 E270P077
IF (IELT-4) 1000,700,1000 E270P078
JM=J5+M E270P079
JSDZ=IA(JM)/100 E270P080
JMF=IA(JM)-100*JSDZ E270P081
JM=J6+M E270P082
JPRS=IA(JM) E270P083
L=4 E270P084
GO TO (1100,1200,1300,1400),L E270P085
1100 JM=J3+M E270P086
N(1)=IA(JM) E270P087
I=1+L E270P088
1200 JM=J4+M E270P089
N(1)=IA(JM) E270P090
I=1+L E270P091
1300 JM=J5+M E270P092
N(1)=IA(JM) E270P093
I=1+L E270P094
JM=J6+M E270P095
N(1)=IA(JM) E270P096
I=1+L E270P097
1400 JM=J7+M E270P098
N(1)=IA(JM) E270P099
I=1+L E270P100
JM=J8+M E270P101
N(1)=IA(JM) E270P102
I=1+L E270P103
JM=J9+M E270P104
N(1)=IA(JM) E270P105
I=1+L E270P106
JM=J10+M E270P107
N(1)=IA(JM) E270P108
I=1+L E270P109
IF (I-IH) 1600,1600,1450 E270P110
DO 1500 I=1HP,8 E270P111
1500 N(1)=0, E270P112
1600 RETURN E270P113
END E270P114

```

Table VII-43. Source program listing of subroutine TRAN (Link 2)

```

* LABEL
CEZTRN SUBROUTINE TRAN (A,IFS) E270N000
TRANSFORMS THE DESCRIPTION OF A VECTOR FROM LOCAL TO OVERALL E270N001
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),F22(3,3) E270N002
1,P(24),UV(24),X(8),Y(8),Z(8),XD(17),YD(17),ZD(17),G(11) E270N003
GUMMIN IA,AA E270N004
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),E22),(D21(19),E),(D21(20),G)E270N005
EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), E270N007
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),E270N009
2IH),(IA(11),I8),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),E270N010
3IMF),(IA(16),IARE),(IA(17),N(1)),(IA(18),M),(IA(19),ITV),(IA(20),E270N011
4ISTR),(IA(21),IELT),(IA(22),ITEM),(IA(30),ITIC),(IA(31),IMET), E270N012
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), E270N013
6IORD),(IA(38),IORD),(IA(39),AGEL),(IA(50),J),(IA(51),J2), E270N014
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E270N015
8)J8),(IA(58),JTY),(IA(59),IBB),(IA(60),I80),(IA(61),I1D),(IA(62),E270N016
9)IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(43),ITAP) E270N017
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69), E270N018
1ICIZ),(IA(70),ICF),(IA(71),IXR),(IA(72),IYY),(IA(73),I2Z), E270N019
2(IA(74),IIC),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS) E270N020
3,(IA(78),IGEM),(IA(79),IERR),(IA(80),TE),(IA(81),DT),(AA(82),DG), E270N021
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P), E270N022
5(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), E270N023
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZGEM) E270N024
7,(AA(42),INP),(AA(43),IPRG),(AA(44),IPRN),(AA(45),CONS),(AA(46),IUE270N025
8),(AA(47),GL),(AA(48),G2),(AA(49),G3) E270N026
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346) E270N027
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) E270N028
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) E270N029
3,(IA(337),JMMZ),(IA(336),JMF),(IA(335),ITAS),(IA(334),IDZ) E270N030
4,(IA(333),IPR),(IA(332),DGY),(AA(331),DG2),(AA(330),PRES) E270N031
5,(IA(329),IPR) E270N032
DIMENSION EM(4,4),EN(4,4),D(4,4),DIR(3,3),DUM(1) E270N033
EQUIVALENCE (AA(200),EM),(AA(216),EN),(AA(232),EQ),(AA(248),O), E270N034
1(AA(264),DIR),(AA(273),DUM) E270N035
DIMENSION A(1) E270N036
IGEMP=IGFPM+1 E270N037
LJI=0 E270N038
LK=IFS-44IMS E270N039
DO 300 L=1,IGFPM E270N040
LK=LK+3IMS E270N041
DO 200 J=1,3 E270N042
DO 200 I=1,IMS E270N043
LJI=LJI+1 E270N044
DK=LK+1 E270N045
DO 100 K=1,3 E270N046
LK=LK+IMS E270N047
100 DUM(LJI)=DUM(LJI+DIR(K,J)+DK) E270N048
200 CONTINUE E270N049
300 CONTINUE E270N050
INI=3*IGEMP+IMS E270N051
DO 400 I=1,INI E270N052
I1=IFS+I E270N053
400 A(I)=DUM(I) E270N054
RETURN E270N055
END E270N056

```

Table VII-44. Source program listing of subroutine TRIM (Link 2)

```

* LABEL
CE2TRT SUBROUTINE TRIM F2TR1000
          GENERATES M, N AND L MATRICES OF THIN TRIANGULAR ELEMENT F2TR1001
          DIMENSION IA(2),AA(1),S(1),N(8),D21(21),D33(3,3),E22(3,3) F2TR1002
          1,P(24),UV(24),X(8),Y(8),Z(8),XN(7),YN(7),ZN(7),GL(1) F2TR1003
          COMMON IA,AA F2TR1004
          EQUIVALENCE(IA,AA),(D21,D33),(D2110),F22),(D2119),E),(D2120),G F2TR1005
          EQUIVALENCE(IA(1),IN),IA(2),IBN),IA(3),IT),IA(4),IP),IA(5), F2TR1006
          1)PRS),IA(6),ITYPE),IA(7),IMAT),IA(8),IDEG),IA(9),INX),IA(10), F2TR1007
          2)IM),IA(11),IB),IA(17),IMMX),IA(13),IMMY),IA(14),IMZ),IA(15), F2TR1008
          3)IMEF),IA(16),IARE),IA(17),N(1),IA(25),M),IA(26),ITY),IA(27), F2TR1009
          4)STR),IA(28),IELT),IA(29),ITFM),IA(30),ITIC),IA(31),IMET), F2TR1010
          5)IA(32),ISUM),IA(33),IND1),IA(34),IMS),IA(36),IDS),IA(37), F2TR1011
          6)ORD),IA(38),IGRD1),IA(39),ACEL),IA(50),J1),IA(51),J2), F2TR1012
          7)IA(52),J3),IA(53),J4),IA(54),J5),IA(55),J6),IA(56),J7),IA(57) F2TR1013
          8),J8),IA(58),J1Y),IA(59),J8),IA(60),IB),IA(61),ID),IA(62), F2TR1014
          9)IA),IA(63),OT),IA(64),IDV),IA(65),ITE),IA(4),ITAP) F2TR1015
          EQUIVALENCE(IA(66),ICAR),IA(67),ICIX),IA(68),ICLY),IA(69), F2TR1016
          1)C(2),IA(70),ICF1),IA(71),IXX),IA(72),IYY),IA(73),IZZ), F2TR1017
          2)IA(74),IIC1),IA(75),IUEP),IA(76),IST),IA(77),IIS) F2TR1018
          3),IA(78),IGEM),IA(79),IERK),AA(80),TE),AA(81),OT),AA(82),DGI, F2TR1019
          4)AA(83),AL1),AA(84),AL2),AA(85),AL3),AA(86),D21),AA(107),PI, F2TR1020
          5)AA(131),UV),AA(155),K),AA(163),V),AA(171),Z),AA(179),XD), F2TR1021
          6)AA(186),VD),AA(193),ZD),AA(351),S),AA(40),ZGEM) F2TR1022
          7),AA(42),INP),AA(43),IPBC),AA(44),IPEN),AA(45),CONS),AA(46), F2TR1023
          8),AA(47),GL),AA(48),G2),AA(49),G3) F2TR1024
          DIMENSION EM(4,4),EN(4,4),O(4,4),F(4,4) F2TR1025
          EQUIVALENCE(AA(200),EM),AA(216),EN),AA(232),E0),AA(248),O) F2TR1026
          EM(1,2)=YD(2) F2TR1027
          EM(1,3)=-YD(1) F2TR1028
          EM(1,1)=YD(1)-YD(2) F2TR1029
          EM(2,1)=0. F2TR1030
          EM(2,2)=0. F2TR1031
          EM(2,3)=0. F2TR1032
          EM(3,1)=XD(2)-XD(1) F2TR1033
          EM(3,2)=XD(2) F2TR1034
          EM(3,3)=XD(1) F2TR1035
          DD 42 J=1,3 F2TR1036
          EN(1,J)=EM(2,J) F2TR1037
          EN(2,J)=EM(3,J) F2TR1038
          EN(3,J)=EM(1,J) F2TR1039
          42 CONTINUE F2TR1040
          DD 63 J=1,3 F2TR1041
          EO(1,J)=EM(1,J) F2TR1042
          EO(2,J)=EM(3,J) F2TR1043
          430 RETURN F2TR1044
          END F2TR1045
          F2TR1046
    
```

Table VII-45. Source program listing of subroutine TRM (Link 2)

```

* LABEL
CE2TRM SUBROUTINE TRM (A,B,C,M,N) F2TRM000
          N=N1 F2TRM001
          DIMENSION A(3,3),B(4,4),C(4,4),D(4,4) F2TRM002
          IF (NT 2,I,1) F2TRM003
          2 N=N F2TRM004
          GO TO 5 F2TRM005
          1 DO 3 I=1,M F2TRM006
          DO 3 J=1,N F2TRM007
          3 C(I,J)=B(I,J) F2TRM008
          8 DO 4 I=1,N F2TRM009
          DO 4 J=1,M F2TRM010
          D(I,J)=0. F2TRM011
          DO 5 K=1,M F2TRM012
          5 D(I,J)=D(I,J)+C(K,I)*A(K,J) F2TRM013
          4 CONTINUE F2TRM014
          DO 6 I=1,N F2TRM015
          DO 6 J=1,N F2TRM016
          C(I,J)=0. F2TRM017
          DO 7 K=1,M F2TRM018
          7 C(I,J)=C(I,J)+D(I,K)*B(K,J) F2TRM019
          6 CONTINUE F2TRM020
          RETURN F2TRM021
          END F2TRM022
          F2TRM023
    
```

Table VII-46. Source program listing of main program of Link 3 (deflection link)

```

* CHAIN (3,2)
* LABEL
CELAS3
C MAIN PROGRAM FOR DEFLECTION LINK
C OBTAINS THE DEFLECTION COMPONENTS IN GLOBAL COORDINATES
DIMENSION I(11),AA(1),S(1),N(8),D21(21),Q33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7)
COMMON I,A,AA
EQUIVALENCE (I,A),AA,(D21,D33),(D21(10),E22,(D71(19),E1,(D71(20),G)
EQUIVALENCE (I(11),IN),(I(12),ISN),(I(13),IT),(I(14),IP),(I(15),
1)PRS),(I(16),ITYPE),(I(17),IMAT),(I(18),IDEG),(I(19),INX),(I(10),ELAS3008
2)H),(I(11),T8),(I(12),IMMX),(I(13),IMMY),(I(14),IMM2),(I(15),ELAS3009
3)MF),(I(16),IARE),(I(17),N(1)),(I(25),M),(I(26),ITY),(I(127),FLAS3010
4)STR),(I(28),IELT),(I(29),ITEM),(I(30),ITIC),(I(31),IME7),
5)IA(32),ISUM),(I(33),IND),(I(34),IMS),(I(36),IOS),(I(37),
6)ORD),(I(38),IORD1),(I(39),ACEF),(I(40),J1),(I(41),J2),
7)IA(52),J3),(I(45),J4),(I(46),J5),(I(47),J6),(I(48),J7),(I(49),J8),
8),J9),(I(50),JTY),(I(51),JBY),(I(52),JBY),(I(53),JBY),(I(54),JBY),
9)IA),(I(163),IDT),(I(164),IDY),(I(165),ITE),(I(166),ITAP)
EQUIVALENCE (IA(66),ICAR),(I(67),ICIX),(I(68),ICIZ),(I(69),
1)ICIZ),(I(70),ICFI),(I(71),ICFY),(I(72),IYX),(I(73),IZZ),
2)IA(74),ICG),(I(75),IDEF),(I(76),IST),(I(77),IIS)
3),(I(78),IGEM),(I(79),IERR),(I(80),ITE),(I(81),OT),(I(82),NG),
4)AA(83),ALL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(87),P),
5)AA(131),UV),(AA(155),X),(AA(156),Y),(AA(171),Z),(AA(179),XD),
6)AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM)
7),(AA(42),INP),(AA(43),IPRG),(AA(44),IPFN),(AA(45),CONS),(AA(46),I)
8),(AA(47),G1),(AA(48),G2),(AA(49),G3)
EQUIVALENCE (I(349),NTIC),(I(348),ISDT),(I(347),ISDY),(I(346)
1),ISDZ),(I(345),J8),(I(344),J10),(I(343),JPRS),(I(342),JSDY)
2),(I(341),JSDZ),(I(340),JAKF),(I(339),JMMX),(I(338),JMMY)
3),(I(337),JMMZ),(I(336),JMF1),(I(335),ITAS),(I(334),IDZ1)
4),(I(333),IPR),(I(332),DGY),(I(331),DGZ),(I(330),PRFS)
5),(I(329),IP1R)
DIMENSION RA(999,6)
EQUIVALENCE (AA(900),RB)
C SOLVE THE EQUILIBRIUM EQUATIONS FOR UNKNOWN DEFLECTIONS
10 CALL TICK (ITIM)
CALL VELAS(I,SUM,IERR,IST,IOEF)
20 CALL TICK (ITIM)
TINV=ITIM
TINV=INVT/60
IF (IERR) 302,234,302
234 IF (INP-1) 234,234,234
2342 IDEF1=DEF+1
IEND=DEF+ISUM
WRITE OUTPUT TAPE 6,2343,(I,AA(I),I=DEF1,IFND)
2343 FORMAT (1H,1,34)REDUCED DEFLECTION VECTOR FOLLOWS.///(5I16,F14.5,
14X)
C COMPLETE THE DEFLECTION VECTOR AND PRINT.
2341 DO 202 M=1,IN
DO 202 K=1,6
202 BB(M,K)=0.
JJ=-IOEG
DO 2031 M=1,IN
JJ=J+IDEG
DO 203 K=1,6DEG
J=JJ+K
1STJ=1S+J
100J=100+J
L=IA(180J)
IJC=IJC+J
204 IF (L) 204,205,206
2042 IF (L=1) 2042,2041,206
100J=100+J
I=IA(180J)
IDFF1=IDFF-7
BB(M,K)=AA(IDEF1)
11=(L-1)/DEG+1
L2=L-(L-1)*IOEG
BB(L1,L2)=BB(L1,L2)+AA(IJC)*BB(M,K)
GO TO 203
2041 IBB=IBB+J
J=IA(180J)
IDFF=IDFF+1
BB(M,K)=AA(IDEF1)
GO TO 203
205 BB(M,K)=AA(IJC)+BB(M,K)
GO TO 203
206 IF (L=1000) 2061,205,205
2061 LL=IA(LL)
IDFF=IDFF+LL
BB(M,K)=AA(IDEF1)+AA(IJC)
203 CONTINUE
2031 JJ=-IDEG
DO 2011 M=1,IN
JJ=J+IDEG
DO 201 K=1,6DEG
IDFF=IDFF+JJ+K
201 AA(IDEF1)=BB(M,K)
2011 CONTINUE
C REARRANGE DEFLECTIONS ACCORDING TO TYPE
C ASSUME NORMAL CASE
IELT=1
C CHECK THE SPECIAL CASES
IF (IOEG=3) 450,449,450
449 IF (IGEM) 450,449,450
448 IF (ITH=2) 450,447,443
C DISTINGUISH GRIDWORK CASE
447 IF (IMMY) 447,442,443
C PLATE AND/OR GRIDWORK CASE
443 IELT=2
GO TO 441
C SHELL OF REVOLUTION OR PLANAR FRAME CASE
442 IELT=3
441 DO 40 M=1,IN
GO TO 440,42,43,IELT
42 X(1)=BB(M,1)
X(2)=BB(M,2)
X(3)=BB(M,3)
BB(M,1)=0.
BB(M,2)=0.
BB(M,3)=X(1)
BB(M,4)=X(2)
BB(M,5)=X(3)
GO TO 40
43 X(1)=BB(M,3)
BB(M,3)=0.
BB(M,6)=X(1)
40 CONTINUE
C PUNCH OUT RESULTS IF NECESSARY
450 CALL PUNC
WRITE OUTPUT TAPE 6,1111,(M,(BB(M,K),K=1,6),M=1,IN)
1111 FORMAT (1H,1,39X,17)MODAL DEFLECTIONS//5H NODE,5X,13HDISP.,ALONG X,FLAS3126
15X,13HDISP.,ALONG Y,5X,13HDISP.,ALONG Z,5X,13HDISP.,ALONG X,
25X,13HDISP.,ALONG Y,5X,13HDISP.,ALONG Z,5X,13HDISP.,ALONG X,
IF (INP) 310,310,320
320 IF (ITAS) 305,305,315
310 CALL RESI
IF (ITAS) 305,305,306
306 CALL RESW
IF (INX=3) 345,345,355
305 WRITE OUTPUT TAPE 6,3051
3051 FORMAT (54H NO SCRATCH TAPE IS GIVEN OR ERROR IN THE SCRATCH TAPE)
GO TO 345
310 IF (INX=3) 345,345,340
340 IF (ITAS) 345,345,350
350 CALL RESI
IF (ITAS) 345,345,355
355 CALL ELST
345 CALL TICK (ITIM)
C3T=ITIM
C3T=C3T/60.
WRITE OUTPUT TAPE 6,5555,C3T,TINV
5555 FORMAT (21H DEFLECTION LINK TOOK,F7.2,2X,8)SECONDS.,75X,F7.2)
IF (INX=3) 3421,3421,342
3421 CALL CHAIN (1,ITAP)
342 CALL CHAIN (4,ITAP)
302 WRITE OUTPUT TAPE 6,3021,IERR
3021 FORMAT (42H STIFFNESS MATRIX IS NOT POSITIVE DEFINITE.15)
GO TO 3421
END

```

**Table VII-47. Source program listing of subroutine ELST (Link 3)**

```

* LABEL
CE3ELT SUBROUTINE ELST F3ELT000
WRITES ON TAPE ITAS ELEMENT SET INFORMATION F3ELT001
DIMENSION IA(1),AA(1),S(1),MIR(1),D21(21),D33(3,3),E22(3,3) F3ELT002
1,P(24),UV(24),X(R),Y(R),Z(R),XD(7),YD(7),ZD(7) F3ELT003
COMMON IA,AA F3ELT004
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),E22),(D21(19),F),(D21(20),G) F3ELT005
EQUIVALENCE (IA(1),IN),(IA(2),INR),(IA(3),IT),(IA(4),I),(IA(5), F3ELT006
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDFG),(IA(9),INX),(IA(10), F3ELT008
2IMI),(IA(11),I8),(IA(12),IMMX),(IA(13),IMY),(IA(14),IMZ),(IA(15), F3ELT009
3IMFI),(IA(16),IARE),(IA(17),M11),(IA(25),M),(IA(26),ITY),(IA(27), F3ELT010
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET),( F3ELT011
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F3ELT012
6IORD),(IA(38),IORD1),(IA(39),ACEL),(IA(50),J11),(IA(51),J2), F3ELT013
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57) F3ELT014
8),J8),(IA(58),JTY),(IA(59),IB8),(IA(60),IB0),(IA(61),ID),(IA(62), F3ELT015
9IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP) F3ELT016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69), F3ELT017
1ICIZ),(IA(70),ICFI),(IA(71),ICX),(IA(72),IY),(IA(73),IZ),( F3ELT018
2(IA(74),IGEM),(IA(79),IERR),(AA(80),TE),(AA(81),DT),(AA(82),DG), F3ELT019
3,(IA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P), F3ELT021
4(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), F3ELT022
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F3ELT023
7,(AA(42),INP),(AA(43),IPBG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IUE) F3ELT024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F3ELT025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISD1),(IA(347),ISD2),(IA(346) F3ELT026
1,ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F3ELT027
2,(IA(341),JSD2),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F3ELT028
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) F3ELT029
4,(IA(333),IPR),(AA(332),DCY),(AA(331),DG2),(AA(330),PRES) F3ELT030
5,(IA(329),IPR) F3ELT031
DIMENSION IMNT(24) F3ELT032
EQUIVALENCE (UV,IMNT),(IA(200),IONE) F3ELT033
ISN=IST+IND F3ELT034
IELM=13 F3ELT035
IELN=IELM-1 F3ELT036
ISN1=ISN+1 F3ELT037
ISNN=ISN+IN*IELM F3ELT038
INC1=0 F3ELT039
IONE=0 F3ELT040
DO 8 I=ISN1,ISNN F3ELT041
IA(I)=0 F3ELT042
DO 1 I=1,IT F3ELT043
JI I=JI+1 F3ELT044
IELT=IA(JI)/100 F3ELT045
GO TO 19,9,9,9,2,3,2,3,4,5,2,3,2,3,2,3,14,14,IELT F3ELT046
IONE=IONE+1 F3ELT047
GO TO 1 F3ELT048
KJ=4 F3ELT049
KN=3 F3ELT050
GO TO 6 F3ELT051
KJ=4 F3ELT052
KN=4 F3ELT053
GO TO 6 F3ELT054
KJ=3 F3ELT055
KN=4 F3ELT056
GO TO 6 F3ELT057
KJ=3 F3ELT058
KN=8 F3ELT059
GO TO 6 F3ELT060
KJ=4 F3ELT061
KN=2 F3ELT062
KK=J1+1+KJ-2)*11 F3ELT063
DO 7 J=1,KN F3ELT064
KK=KK+IT F3ELT065
NN=IA(KK) F3ELT066
ISN1=ISN+(NN-1)*IELM+1 F3ELT067
IE=IA(ISN1)+1 F3ELT068
IF (IE=IELN) 12,11,11 F3ELT069
WRITE OUTPUT TAPE 6,13,IELN,NN F3ELT070
FORMAT (10H MORE THAN 14,2X,31INDN-ONE-DIMENSNL ELMNTS AT NODE,15 F3ELT071
INCT=1 F3ELT072
GO TO / F3ELT073
ISNN=ISN1+IE F3ELT074
IA(ISN1)=IE F3ELT075
IA(ISNN)=I F3ELT076
CONTINUE F3ELT077
1 CONTINUE F3ELT078
IF (INC1) 19,20,19 F3ELT079
ITAS=0 F3ELT080
WRITE OUTPUT TAPE 6,19,1 F3ELT081
FORMAT(53H MODAL STRESS COMPUTATION IS DELETED DUE TO PRECEDING) F3ELT082
GO TO 100 F3ELT083
DO 21 I=1,IN F3ELT084
ISN1=ISN+(I-1)*IELM+1 F3ELT085
IE=IA(ISN1) F3ELT086
IF (IE) 23,23,24 F3ELT087
DO 22 J=1,IE F3ELT088
ISNN=ISN1+J F3ELT089
IMNT(J)=IA(ISNN) F3ELT090
WRITE TAPE ITAS,I,IE,(IMNT(J),J),IE) F3ELT091
GO TO 21 F3ELT092
WRITE TAPE ITAS,J,IE,IE F3ELT093
CONTINUE F3ELT094
DO 25 I=L,IN F3ELT095
BACKSPACE ITAS F3ELT096
RETURN F3ELT097
END F3ELT098

```

**Table VII-48. Source program listing of subroutine PUNC (Link 3)**

```

* LABEL F3PUNC000
CE3PUNC SUBROUTINE PUNC F3PUNC001
DUMMY SUBROUTINE F3PUNC002
RETURN F3PUNC003
END F3PUNC004

```

**Table VII-49. Source program listing of subroutine RESI (Link 3)**

```

* LABEL F3RES000
CE3RES SUBROUTINE RESI F3RES001
COMPUTES RESIDUAL FORCES AT THE NODES F3RES002
DIMENSION IA(1),AA(1),S(1),MIR(1),D21(21),D33(3,3),E22(3,3) F3RES003
1,P(24),UV(24),X(R),Y(R),Z(R),XD(7),YD(7),ZD(7) F3RES004
COMMON IA,AA F3RES005
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),E22),(D21(19),F),(D21(20),G) F3RES006
EQUIVALENCE (IA(1),IN),(IA(2),INR),(IA(3),IT),(IA(4),I),(IA(5), F3RES007
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDFG),(IA(9),INX),(IA(10), F3RES008
2IMI),(IA(11),I8),(IA(12),IMMX),(IA(13),IMY),(IA(14),IMZ),(IA(15), F3RES009
3IMFI),(IA(16),IARE),(IA(17),M11),(IA(25),M),(IA(26),ITY),(IA(27), F3RES010
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET),( F3RES011
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F3RES012
6IORD),(IA(38),IORD1),(IA(39),ACEL),(IA(50),J11),(IA(51),J2), F3RES013
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57) F3RES014
8),J8),(IA(58),JTY),(IA(59),IB8),(IA(60),IB0),(IA(61),ID),(IA(62), F3RES015
9IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP) F3RES016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69), F3RES017
1ICIZ),(IA(70),ICFI),(IA(71),ICX),(IA(72),IY),(IA(73),IZ),( F3RES018
2(IA(74),IGEM),(IA(79),IERR),(AA(80),TE),(AA(81),DT),(AA(82),DG), F3RES019
3,(IA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P), F3RES021
4(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), F3RES022
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F3RES023
7,(AA(42),INP),(AA(43),IPBG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IUE) F3RES024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F3RES025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISD1),(IA(347),ISD2),(IA(346) F3RES026
1,ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F3RES027
2,(IA(341),JSD2),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F3RES028
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) F3RES029
4,(IA(333),IPR),(AA(332),DCY),(AA(331),DG2),(AA(330),PRES) F3RES030
5,(IA(329),IPR) F3RES031
C FUNDAMENTAL MODAL FORCES AND ASSEMBLE FOR OBTAINING RESIDUALS F3RES032
DO 40 I=1,IND F3RES033
IST=IST+1 F3RES034
60 AA(IST)=0 F3RES035
70 DO 20 J=1,IT F3RES036
C READ THE QUANTITIES FOR ELEMENT JJ F3RES037
50 READ TAPE ITAS,I,IT,ITM,NAV,IMS,IDS,IDS2,INC(1),I=1,IMS,(S(1), F3RES038
1I=1,IDS2),(P(1),CF,I=1,IDS) F3RES039
C COMPUTE AND ASSEMBLE THE MODAL FORCES OF ELEMENT JJ F3RES040
IF (NAV-2) 91,92,92 F3RES041
CF=1 F3RES042
GO TO 93 F3RES043
92 CF=0.5 F3RES044
93 IF (M-JJ) 100,9,100 F3RES045
DO 10 I=1,IDS F3RES046
KK=IDS+I F3RES047
DO 11 K=1,IDS F3RES048
KK=KK+IDS F3RES049
KDEG=(K-1)/IMS+1 F3RES050
KNDD=K-(KDEG-1)*IMS F3RES051
KNOD=N(KNOD) F3RES052
IDEF=IDEF+(KNOD-1)*IDEG+KDEG F3RES053
P(I)=P(I)-S(KK)*AA(IDEF) F3RES054
KDEG=(I-1)/IMS+1 F3RES055
KNDD=N(KNDD)-1+IMS F3RES056
KNOD=N(KNOD) F3RES057
ND=(KNOD-1)*IDEG+KDEG F3RES058
IST=IST+ND F3RES059
AA(IST)=AA(IST)-P(I)*CF F3RES060
10 CONTINUE F3RES061
IF (ITM-ITM) 50,21,21 F3RES062
21 IF (NAV-2) 20,50,20 F3RES063
20 CONTINUE F3RES064
31 RETURN F3RES065
100 ITAS=0 F3RES066
GO TO 31 F3RES067
END F3RES068

```

Table VII-50. Source program listing of subroutine RESW (Link 3)

```

* LABEL
CF3HEW SUBROUTINE RESW F3REW000
C WRITES RESONANT FORCES AT THE NODES E3REW001
DIMENSION IA(1),AA(1),S(1),N(R),DZ(12),D3(3,3),E22(3,3) E3REW002
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7) F3REW003
COMMON IA,AA F3REW004
EQUIVALENCE (IA,AA),(D2,D3),(D21(10),E22),(D21(19),E),(D21(20),G) F3REW005
EQUIVALENCE IA(1),IN,IA(2),IBN,(IA(3),IT),(IA(4),IP),IA(5) F3REW006
11PR),(IA(6),ITYPE),IA(7),IMAT,(IA(8),IDEG),(IA(9),INX),(IA(10), F3REW007
21M),(IA(11),I8),(IA(12),IMM),(IA(13),IMMY),(IA(14),IMZ),(IA(15), F3REW008
31MF),(IA(16),IARL),(IA(17),W(1)),(IA(25),M),(IA(26),ITY),(IA(27), F3REW009
41STR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),INF) F3REW010
51IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IOS),(IA(37), F3REW011
61ORD),(IA(38),IORD),(IA(39),ACEF),(IA(50),J),(IA(51),J2), F3REW012
71IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57), F3REW013
81,J8),(IA(58),JTY),(IA(59),I8B),(IA(60),IRO),(IA(61),I10),(IA(62), F3REW014
91IA),(IA(63),I0T),(IA(64),I8Y),(IA(65),ITF),(IA(41),ITAP) F3REW015
EQUIVALENCE (IA(66),ICAR),(IA(67),ICEX),(IA(68),ICY),(IA(69), F3REW016
11CIZ),(IA(70),ICFI),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ), F3REW017
21IA(74),IIC),(IA(75),IDEP),(IA(76),IST),(IA(77),IIS) F3REW018
3,IA(78),IGEM),(IA(79),IERR),(AA(80),TF),(AA(81),DT),(AA(82),DG), F3REW019
4(AA(83),AL),(AA(84),AL2),(AA(85),AL3),(AA(86),D2),(AA(107),P), F3REW020
5IAA(131),UW),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), F3REW021
6IAA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F3REW022
7,IAA(42),INP),(AA(43),IPBG),(AA(44),IPEM),(AA(45),CONS),(AA(46),I F3REW023
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F3REW024
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346) F3REW025
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSY) F3REW026
2,IA(341),JSO2),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F3REW027
3,IA(337),JMMZ),(IA(336),JMF),(IA(335),ITAS),(IA(334),I07) F3REW028
4,IA(333),IPR),(IA(332),RGY),(AA(331),DG2),(AA(330),PRFS) F3REW029
5,IA(329),IPIR) F3REW030
IELT=IELT F3REW031
WRITE OUTPUT TAPE 6,74 F3REW032
74 FORMAT (1H1,40X,26HFORCES ACTING AT THE NODES//5H NODE=5X,13HFORCE F3REW033
1 ALONG X,5X,13HFORCE ALONG Y,5X,13HFORCE ALONG Z,4X,14HMOMENT ABOUT F3REW034
2T X,4X,14HMOMENT ABOUT Y,4X,14HMOMENT ABOUT Z//) F3REW035
DO 71 I=1,6 F3REW036
71 P(I)=0. F3REW037
DO 75 I=1,IN F3REW038
ND=(I-1)*IDEG F3REW039
IST=IST+ND F3REW040
DO 72 J=1,IDEG F3REW041
L=J F3REW042
JST=IST+J F3REW043
GO TO I72,2+31,IELT F3REW044
2 L=J+2 F3REW045
GO TO 72 F3REW046
3 IF (J-3) 72,4,72 F3REW047
4 L=J+3 F3REW048
72 P(L)=AA(IST+J) F3REW049
WRITE OUTPUT TAPE 6,76,1,(P(I),J=1,6) F3REW050
76 FORMAT (15,AE18,7) F3REW051
75 CONTINUE F3REW052
RETURN F3REW053
END F3REW054
F3REW055

```

Table VII-51. Source program listing of subroutine TICK (Link 3)

```

* FAP TICK000
COUNT 25 TICK001
LBL TICK TICK002
ENTRY TICK TICK003
TICK NZT ONCE TICK004
TRA FIRST TICK005
CAL 5 TICK006
SIR INITL TICK007
ALS 10 TICK008
SLW* 1,4 TICK009
TRA 2,4 TICK010
FIKST SIL ONCE TICK011
CAL 5 TICK012
SLW INITL TICK013
STZ* 1,4 TICK014
TRA 2,4 TICK015
ONCE PZE TICK016
INITL END TICK017
TICK018

```



Table VII-52. Source program listing of subroutine VELAS (Link 3)

```

* LABEL
CE3VEL SUBROUTINE VELAS (NN,IERR,IST,IDEF)
C SOLVES THE GOVERNING EQUATIONS BY VARIABLE BAND-WIDTH CHOLESKI METHOD
DIMENSION A(1),IA(1)
COMMON Z
EQUIVALENCE (A,IA)
IU=IERR
IJ=IST+1
Z=1.E-16
IF (NN) 101,101,1000
101 IERR=1
GO TO 106
1000 N=NN
NI=N+1
C FIND THE SMALLEST DIAGONAL ELEMENT.
1001 E=ABSF(A(IST+1))
DO 77 I=1,N
IU=IU+1
ID=IA(IU)+IST
76 IF (ABSF(A(ID))-E) 771,77,77
771 E=ABSF(A(ID))
77 CONTINUE
C SET ALLOWABLE MINIMUM ON DIAGONAL ELEMENTS.
E=E*Z
C OBTAIN U(1,1)
IF (A(IST+1) -F) 100,100,10
10 IF (N-1) 1072,1074,1072
1074 A(IDEF+1)=A(IDEF+1)/A(IST+1)
GO TO 105
1072 A(IST+1)=SQRTF(A(IST+1))
C OBTAIN THE REST OF FIRST ROW OF U.
IU=IU+2
IW=IA(IU)-1
IF (IW-1) 1312,1312,1313
1313 DO 1311 J=2,IW
IJ=IJ+J
1311 A(IJ)=A(IJ)/A(IST+1)
C OBTAIN THE OTHER ROWS OF U SEQUENTIALLY.
1312 IU=IU+NI
MAX=IA(IU)+IST
DO 701 J=1,N
JJ=MAX+J
701 IA(JJ)=0
DO 11 I=2,N
PREPARE FOR THE I TH ROW.
IU=IU+1
ID=IA(IU)
IDE=IA(ID)+1
JMX=IDE-ID+1-1
ID=ID+IST
II=ID-1
IF (II-1) 15,16,16
16 DO 702 J=1,IW
JJ=MAX+J
702 IA(IJ)=IA(IJ)+1
15 IW=JMX
IEI=I-1
DO 112 J=I,JMX
IJ=IJ+J
JJ=MAX+J
KB=1-IA(IJ)
E3VFL000
E3VFL001
E3VFL002
E3VFL003
E3VFL004
E3VFL005
E3VFL006
E3VFL007
E3VFL008
E3VFL009
E3VFL010
E3VFL011
E3VFL012
E3VFL013
E3VFL014
E3VFL015
E3VFL016
E3VFL017
E3VFL018
E3VFL019
E3VFL020
E3VFL021
E3VFL022
E3VFL023
E3VFL024
E3VFL025
E3VFL026
E3VFL027
E3VFL028
E3VFL029
E3VFL030
E3VFL031
E3VFL032
E3VFL033
E3VFL034
E3VFL035
E3VFL036
E3VFL037
E3VFL038
E3VFL039
E3VFL040
E3VFL041
E3VFL042
E3VFL043
E3VFL044
E3VFL045
E3VFL046
E3VFL047
E3VFL048
E3VFL049
E3VFL050
E3VFL051
E3VFL052
E3VFL053
E3VFL054
E3VFL055
E3VFL056
E3VFL057
E3VFL058
E3VFL059
E3VFL060
IF (KB-1) 1162,13,13
1162 DO 131 K=KB,IE1
IUK=IU+K
KD=IA(IUK)+IST
IK=KD+1-K
JK=KD+J-K
131 A(IJ)=A(IJ)-A(IK)*A(IK)
IF (J-I) 100,12,13
12 IF (A(IJ)-E) 100,100,122
122 A(II)=SQRTF (A(II))
GO TO 112
13 A(IJ)=A(IJ)/A(II)
112 CONTINUE
11 CONTINUE
IM=ID
C U IS NOW AVAILABLE COMPLETELY.
C SOLUTION IS REQUESTED. START FORWARD SWEEP. FIRST B(1)
1009 A(IDEF+1)=A(IDEF+1)/A(IST+1)
C THEN THE REST OF B.
DO 21 I=2,N
L=IDEF+1
IU=IU+1
ID=IA(IU)+IST
IEI=I-1
JJ=MAX+1
KB=1-IA(IJ)
IF (KB-1) 3521,21,21
3>21 DO 22 K=KB,IE1
IUK=IU+K
KD=IA(IUK)+IST
IK=KD+1-K
JK=IDEF+K
22 A(L)=A(L)-A(IK)*A(IK)
21 A(L)=A(L)/A(ID)
C FORWARD SWEEP IS COMPLETED. START BACKWARD SWEEP. B(N) FIRST.
L=IDEF+N
A(L)=A(L)/A(IM)
C THEN THE REST OF B IN BACKWARD DIRECTION.
DO 31 L=2,N
I=N1-L
J=I+IDEF
JI=J-1
II=I+1
IU=IU-I
ID=IA(IU)
IDE=IA(II)+1
JMX=IDE-ID
ID=ID+IST
IDI=ID-1
IF (JMX-1) 31,31,321
321 DO 32 K=2,JMX
M=JI+K
IK=IDI+K
32 A(IJ)=A(IJ)-A(M)*A(IK)
31 A(IJ)=A(IJ)/A(ID)
C THE SOLUTION IS OBTAINED SUCCESSFULLY ON B.
1009 IERR=0
C NOW GO HOME.
GO TO 106
100 IERR=IJ-IST
106 RETURN
END
E3VFL061
E3VFL062
E3VFL063
E3VFL064
E3VFL065
E3VFL066
E3VFL067
E3VFL068
E3VFL069
E3VFL070
E3VFL071
E3VFL072
E3VFL073
E3VFL074
E3VFL075
E3VFL076
E3VFL077
E3VFL078
E3VFL079
E3VFL080
E3VFL081
E3VFL082
E3VFL083
E3VFL084
E3VFL085
E3VFL086
E3VFL087
E3VFL088
E3VFL089
E3VFL090
E3VFL091
E3VFL092
E3VFL093
E3VFL094
E3VFL095
E3VFL096
E3VFL097
E3VFL098
E3VFL099
E3VFL100
E3VFL101
E3VFL102
E3VFL103
E3VFL104
E3VFL105
E3VFL106
E3VFL107
E3VFL108
E3VFL109
E3VFL110
E3VFL111
E3VFL112
E3VFL113
E3VFL114
E3VFL115
E3VFL116
E3VFL117
E3VFL118
E3VFL119
E3VFL120
E3VFL121
E3VFL122

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Table VII-54. Source program listing of subroutine ABEQ (Link 4)

```

* LABFL
CF4A7D
C SUBROUTINE ABEQ
GENERATES EQUATIONS FOR STRESS BOUNDARY CONDITIONS AT A NODE
DIMENSION IA(11),AA(1),S(1),WB(1),DZ(1),O33(3,3),E22(3,3)
1,P(24),UV(24),X(R1),Y(R1),Z(R1),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE(IA,AA),(D21,D33),(D21(10),E27),(D21(19),E1,(D21(20),G)
EQUIVALENCE(IA(11),IN),(IA(21),IBN),(IA(31),IT),(IA(4),IP),(IA(5),
11PR5),(IA(16),IYPP),(IA(17),IINT),(IA(18),IDEG),(IA(19),IMX),(IA(10),
2IM),(IA(11),IB),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),
3IMF1),(IA(18),IARF),(IA(17),IC1),(IA(21),IC2),(IA(26),ITV),(IA(27),
4ISTR1),(IA(28),IFLT),(IA(29),ITFM),(IA(30),IFIC1),(IA(31),IMFT),
5IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37),
6IORI),(IA(38),IQRD1),(IA(39),ACE1),(IA(50),J1),(IA(51),J2),
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),
8J8),(IA(58),J9),(IA(59),IIR1),(IA(60),IIR2),(IA(61),IIR3),(IA(62),
9I14),(IA(63),IOT),(IA(64),IOP),(IA(65),ITE),(IA(61),ITAP)
EQUIVALENCE(IA(16),ICAR),(IA(17),ICX),(IA(18),ICY),(IA(19),
1IC12),(IA(17),ICF1),(IA(71),ICX1),(IA(72),ICX2),(IA(73),ICZ),
2IA(74),IC1),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS)
3,(IA(78),IGEM),(IA(79),IFRR),(AA(80),TF),(AA(81),DT),(AA(82),DG)
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),O21),(AA(107),P),
5AA(111),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZFM)
7,(AA(421),IMP),(AA(439),IPBE),(AA(441),IPEN),(AA(445),CONS),(AA(446),IUE)
8,(AA(447),G1),(AA(448),G2),(AA(449),G3)
EQUIVALENCE(IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346)
1,ISDZ),(IA(345),J91),(IA(344),J101),(IA(343),JPRS),(IA(342),JSDY)
2,(IA(341),JSDZ),(IA(340),JARF),(IA(339),JMX1),(IA(338),JMY)
3,(IA(337),JMX2),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IOZ)
4,(IA(333),IPR1),(AA(332),D6Y),(AA(331),D6Y1),(AA(330),PRF5)
5,(IA(329),IPR1)
DIMENSION BIR(3),DIR(3),DIM(3),SR(6),XN(3),XF(3),ON(6),OF(6),
1RES(6),RED(6),BAS(3),ICLAS(4),NBAN(10),NU(3),NES(3)
EQUIVALENCE(AA(200),IMPE),(AA(201),ICN),(AA(202),LM),(AA(203),AST)
1,(AA(204),INRDN),(AA(205),ARE),(AA(206),ICLA),(AA(207),IMFL),
2(AA(208),IM),(AA(209),IC),(AA(210),ICDN),(AA(211),ANGLE),(AA(212),
3ICAS),(AA(213),EI),(AA(214),NB),(AA(215),MB)
4,(AA(216),IPI),(AA(217),RST)
EQUIVALENCE(IA(220),BIR),(AA(223),SIR),(AA(226),DIN),(AA(235),SR)
1,(AA(241),XN),(AA(244),XF),(AA(247),DN),(AA(253),OF),(AA(259),RFS)
2,(AA(269),RED),(AA(271),BAS),(AA(274),ICLAS),(AA(278),NRAN)
3,(AA(292),NU),(AA(295),NES)
DIMENSION NEL(20),L1,MAC(4,4),ZD1,ING(90),DD(6,6),A1,490,71,B(8,8),
1C(8,2),FF(11),MSET(100),MSET(100),W13,3)
EQUIVALENCE(AA(1000),FF),(M(1),J1),(M(2),JM1),(M(3),J51)
EQUIVALENCE(IEF11),NEL1,(FF(341),MAC),(FF(661),ING),(FF(751),D1),
1(FF(787),A),(FF(1417),B),(FF(1481),C),(FF(1497),MSET),(FF(1597),
2MSET),(FF(1697),W)
EQUIVALENCE(NES(1),ICOL),(MES(2),IRIG),(NES(3),IDR)
DIMENSION NFK(3),Z1,NEK(3,2)
EQUIVALENCE(X(1),REK1,Y(1),NEK)
ICOL=ICOL
IRIG=IRIG
C GENERATE THE RESIDUE VECTOR
1ST=15+(ICN-1)*IDFG
DU 9 I=1,1DFG
1ST=1ST+1
9 RES(1)=AA(1ST)
C INITIALIZE
IEQ=2
N1(1)=1
N2(1)=3
N3(1)=5
IREB=1
IREN=2
CT=TE**3/12
CR=ARE/UD(1,1)
CL=CR*ARE
DU 12 J=1,2
DU 12 I=1,7
REK(I,J)=1
NEK(I,J)=1
IF(XN(11) 31,30,3)
30 XX=1
GO TO 32
31 XX=XN(11)
32 ICN=0
GENERATE EQUATIONS ACCORDING TO CLASS
ICAS=ICAS
GO TO(1,2,3,4,5,6,7,8),ICAS
C PLANE STRESS AND PLANE STRAIN
CR=CR/TE
GO TO 15

```

Table VII-55. Source program listing of subroutine AGEL (Link 4)

```

A LABEL
CE*AGEL
SUBROUTINE AGEL
C DUMMY SUBROUTINE
RETURN
END
E44GFLO0
F44GFLO1
F44GFLO2
F44GEL03
E44GEL04

```

Table VII-57. Source program listing of subroutine BOFI (Link 4)

```

* LABEL
CF*BOFI
SUBROUTINE BOFI
C TO FIND IF THE NODE IS ON BOUNDARY
DIMENSION IA(1,AA(1),S11,N(8),D21(21),D33(3,3),F22(3,3)
L,P(24),UV(24),X(R),Y(R),Z(R),XP(7),Y(7),Z(7),G(11)
COMMON IA,AA
EQUIVALENCE IA,AA, ID21(033), (D21(10),F22(1021191,E), (D21(20),G)
EQUIVALENCE IA(11,IN),IA(12,IBN),IA(13,ITB),IA(14,ITP),IA(15,
1IPRS),IA(16,ITM),IA(17,IMX),IA(18,IMY),IA(19,IMZ),IA(20,
2IM),IA(21,IRI),IA(22,IMK),IA(23,IMW),IA(24,IMZ),IA(25,
3IMF),IA(26,IARE),IA(27,N(11),IA(28),M),IA(29,ITV),IA(27),
4ISTR),IA(28),IELT),IA(29),ITEM),IA(30),ITIC),IA(31),IME1),
5IA(32),ISUM),IA(33),INDI),IA(34),IMS),IA(35),J6),IA(36),
6IORD),IA(38),IORDI),IA(39),ACEL),IA(40),J1),IA(41),J2),
7IA(42),J3),IA(43),J4),IA(44),J5),IA(45),J6),IA(46),J7),IA(47),
8J8),IA(48),J9),IA(49),J10),IA(50),J11),IA(51),J12),IA(52),
9IA(53),J13),IA(54),J14),IA(55),J15),IA(56),J16),IA(57),
10IA(58),J17),IA(59),J18),IA(60),J19),IA(61),J20),IA(62),
11IA(63),J21),IA(64),J22),IA(65),J23),IA(66),J24),IA(67),
EQUIVALENCE IA(68),ICAR),IA(69),ICIX),IA(70),ICPY),IA(69),
1ICIZ),IA(71),ICFI),IA(72),ICX),IA(73),ICZ),IA(74),
2IA(75),ICF),IA(76),ICX),IA(77),ICZ),IA(78),ICF),IA(79),
3IA(80),ICF),IA(81),ICX),IA(82),ICZ),IA(83),ICF),IA(84),
4IA(85),ICF),IA(86),ICX),IA(87),ICZ),IA(88),ICF),IA(89),
5IA(90),ICF),IA(91),ICX),IA(92),ICZ),IA(93),ICF),IA(94),
6IA(95),ICF),IA(96),ICX),IA(97),ICZ),IA(98),ICF),IA(99),
7IA(100),ICF),IA(101),ICX),IA(102),ICZ),IA(103),ICF),IA(104),
8IA(105),ICF),IA(106),ICX),IA(107),ICZ),IA(108),ICF),IA(109),
9IA(110),ICF),IA(111),ICX),IA(112),ICZ),IA(113),ICF),IA(114),
10IA(115),ICF),IA(116),ICX),IA(117),ICZ),IA(118),ICF),IA(119),
11IA(120),ICF),IA(121),ICX),IA(122),ICZ),IA(123),ICF),IA(124),
EQUIVALENCE IA(125),ICAR),IA(126),ICIX),IA(127),ICPY),IA(126),
1ICIZ),IA(128),ICF),IA(129),ICX),IA(130),ICZ),IA(131),ICF),IA(132),
2IA(133),ICF),IA(134),ICX),IA(135),ICZ),IA(136),ICF),IA(137),
3IA(138),ICF),IA(139),ICX),IA(140),ICZ),IA(141),ICF),IA(142),
4IA(143),ICF),IA(144),ICX),IA(145),ICZ),IA(146),ICF),IA(147),
5IA(148),ICF),IA(149),ICX),IA(150),ICZ),IA(151),ICF),IA(152),
6IA(153),ICF),IA(154),ICX),IA(155),ICZ),IA(156),ICF),IA(157),
7IA(158),ICF),IA(159),ICX),IA(160),ICZ),IA(161),ICF),IA(162),
8IA(163),ICF),IA(164),ICX),IA(165),ICZ),IA(166),ICF),IA(167),
9IA(168),ICF),IA(169),ICX),IA(170),ICZ),IA(171),ICF),IA(172),
10IA(173),ICF),IA(174),ICX),IA(175),ICZ),IA(176),ICF),IA(177),
11IA(178),ICF),IA(179),ICX),IA(180),ICZ),IA(181),ICF),IA(182),
EQUIVALENCE IA(183),AL1),IA(184),AL2),IA(185),AL3),IA(186),
1IA(187),AL4),IA(188),AL5),IA(189),AL6),IA(190),AL7),IA(191),
2IA(192),AL8),IA(193),AL9),IA(194),AL10),IA(195),AL11),IA(196),
3IA(197),AL12),IA(198),AL13),IA(199),AL14),IA(200),AL15),IA(201),
4IA(202),AL16),IA(203),AL17),IA(204),AL18),IA(205),AL19),IA(206),
5IA(207),AL20),IA(208),AL21),IA(209),AL22),IA(210),AL23),IA(211),
6IA(212),AL24),IA(213),AL25),IA(214),AL26),IA(215),AL27),IA(216),
7IA(217),AL28),IA(219),AL29),IA(220),AL30),IA(221),AL31),IA(222),
8IA(223),AL32),IA(224),AL33),IA(225),AL34),IA(226),AL35),IA(227),
9IA(228),AL36),IA(229),AL37),IA(230),AL38),IA(231),AL39),IA(232),
10IA(233),AL40),IA(234),AL41),IA(235),AL42),IA(236),AL43),IA(237),
11IA(238),AL44),IA(239),AL45),IA(240),AL46),IA(241),AL47),IA(242),
EQUIVALENCE IA(243),AL48),IA(244),AL49),IA(245),AL50),IA(246),
1IA(247),AL51),IA(248),AL52),IA(249),AL53),IA(250),AL54),IA(251),
2IA(252),AL55),IA(253),AL56),IA(254),AL57),IA(255),AL58),IA(256),
3IA(257),AL59),IA(258),AL60),IA(259),AL61),IA(260),AL62),IA(261),
4IA(262),AL63),IA(263),AL64),IA(264),AL65),IA(265),AL66),IA(266),
5IA(267),AL67),IA(268),AL68),IA(269),AL69),IA(270),AL70),IA(271),
6IA(272),AL71),IA(273),AL72),IA(274),AL73),IA(275),AL74),IA(276),
7IA(277),AL75),IA(278),AL76),IA(279),AL77),IA(280),AL78),IA(281),
8IA(282),AL79),IA(283),AL80),IA(284),AL81),IA(285),AL82),IA(286),
9IA(287),AL83),IA(288),AL84),IA(289),AL85),IA(290),AL86),IA(291),
10IA(292),AL87),IA(293),AL88),IA(294),AL89),IA(295),AL90),IA(296),
11IA(297),AL91),IA(298),AL92),IA(299),AL93),IA(300),AL94),IA(301),
EQUIVALENCE IA(302),AL95),IA(303),AL96),IA(304),AL97),IA(305),
1IA(306),AL98),IA(307),AL99),IA(308),AL100),IA(309),AL101),IA(310),
2IA(311),AL102),IA(312),AL103),IA(313),AL104),IA(314),AL105),IA(315),
3IA(316),AL106),IA(317),AL107),IA(318),AL108),IA(319),AL109),IA(320),
4IA(321),AL110),IA(322),AL111),IA(323),AL112),IA(324),AL113),IA(325),
5IA(326),AL114),IA(327),AL115),IA(328),AL116),IA(329),AL117),IA(330),
6IA(331),AL118),IA(332),AL119),IA(333),AL120),IA(334),AL121),IA(335),
7IA(336),AL122),IA(337),AL123),IA(338),AL124),IA(339),AL125),IA(340),
8IA(341),AL126),IA(342),AL127),IA(343),AL128),IA(344),AL129),IA(345),
9IA(346),AL130),IA(347),AL131),IA(348),AL132),IA(349),AL133),IA(350),
10IA(351),AL134),IA(352),AL135),IA(353),AL136),IA(354),AL137),IA(355),
11IA(356),AL138),IA(359),AL139),IA(360),AL140),IA(361),AL141),IA(362),
EQUIVALENCE IA(363),AL142),IA(364),AL143),IA(365),AL144),IA(366),
1IA(367),AL145),IA(368),AL146),IA(369),AL147),IA(370),AL148),IA(371),
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3IA(377),AL153),IA(378),AL154),IA(379),AL155),IA(380),AL156),IA(381),
4IA(382),AL157),IA(383),AL158),IA(384),AL159),IA(385),AL160),IA(386),
5IA(387),AL161),IA(388),AL162),IA(389),AL163),IA(390),AL164),IA(391),
6IA(392),AL165),IA(393),AL166),IA(394),AL167),IA(395),AL168),IA(396),
7IA(397),AL169),IA(398),AL170),IA(399),AL171),IA(400),AL172),IA(401),
8IA(402),AL173),IA(403),AL174),IA(404),AL175),IA(405),AL176),IA(406),
9IA(407),AL177),IA(408),AL178),IA(409),AL179),IA(410),AL180),IA(411),
10IA(412),AL181),IA(413),AL182),IA(414),AL183),IA(415),AL184),IA(416),
11IA(417),AL185),IA(418),AL186),IA(419),AL187),IA(420),AL188),IA(421),
EQUIVALENCE IA(422),AL189),IA(423),AL190),IA(424),AL191),IA(425),
1IA(426),AL192),IA(427),AL193),IA(428),AL194),IA(429),AL195),IA(430),
2IA(431),AL196),IA(432),AL197),IA(433),AL198),IA(434),AL199),IA(435),
3IA(436),AL200),IA(437),AL201),IA(438),AL202),IA(439),AL203),IA(440),
4IA(441),AL204),IA(442),AL205),IA(443),AL206),IA(444),AL207),IA(445),
5IA(446),AL208),IA(447),AL209),IA(448),AL210),IA(449),AL211),IA(450),
6IA(451),AL212),IA(452),AL213),IA(453),AL214),IA(454),AL215),IA(455),
7IA(456),AL216),IA(457),AL217),IA(458),AL218),IA(459),AL219),IA(460),
8IA(461),AL220),IA(462),AL221),IA(463),AL222),IA(464),AL223),IA(465),
9IA(466),AL224),IA(467),AL225),IA(468),AL226),IA(469),AL227),IA(470),
10IA(471),AL228),IA(472),AL229),IA(473),AL230),IA(474),AL231),IA(475),
11IA(476),AL232),IA(477),AL233),IA(478),AL234),IA(479),AL235),IA(480),
EQUIVALENCE IA(481),AL236),IA(482),AL237),IA(483),AL238),IA(484),
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3IA(495),AL247),IA(496),AL248),IA(497),AL249),IA(498),AL250),IA(499),
4IA(500),AL251),IA(501),AL252),IA(502),AL253),IA(503),AL254),IA(504),
5IA(505),AL255),IA(506),AL256),IA(507),AL257),IA(508),AL258),IA(509),
6IA(510),AL259),IA(511),AL260),IA(512),AL261),IA(513),AL262),IA(514),
7IA(515),AL263),IA(516),AL264),IA(517),AL265),IA(518),AL266),IA(519),
8IA(520),AL267),IA(521),AL268),IA(522),AL269),IA(523),AL270),IA(524),
9IA(525),AL271),IA(526),AL272),IA(527),AL273),IA(528),AL274),IA(529),
10IA(530),AL275),IA(531),AL276),IA(532),AL277),IA(533),AL278),IA(534),
11IA(535),AL279),IA(536),AL280),IA(537),AL281),IA(538),AL282),IA(539),
EQUIVALENCE IA(540),AL283),IA(541),AL284),IA(542),AL285),IA(543),
1IA(544),AL286),IA(545),AL287),IA(546),AL288),IA(547),AL289),IA(548),
2IA(549),AL290),IA(550),AL291),IA(551),AL292),IA(552),AL293),IA(553),
3IA(554),AL294),IA(555),AL295),IA(556),AL296),IA(557),AL297),IA(558),
4IA(559),AL298),IA(559),AL299),IA(560),AL300),IA(561),AL301),IA(562),
5IA(563),AL302),IA(563),AL303),IA(564),AL304),IA(565),AL305),IA(566),
6IA(567),AL306),IA(567),AL307),IA(568),AL308),IA(569),AL309),IA(570),
7IA(571),AL310),IA(571),AL311),IA(572),AL312),IA(573),AL313),IA(574),
8IA(575),AL314),IA(575),AL315),IA(576),AL316),IA(577),AL317),IA(578),
9IA(579),AL318),IA(579),AL319),IA(580),AL320),IA(581),AL321),IA(582),
10IA(583),AL322),IA(583),AL323),IA(584),AL324),IA(585),AL325),IA(586),
11IA(587),AL326),IA(587),AL327),IA(588),AL328),IA(589),AL329),IA(590),
EQUIVALENCE IA(591),AL330),IA(591),AL331),IA(592),AL332),IA(593),
1IA(594),AL333),IA(594),AL334),IA(595),AL335),IA(596),AL336),IA(597),
2IA(598),AL337),IA(598),AL338),IA(599),AL339),IA(600),AL340),IA(601),
3IA(602),AL341),IA(602),AL342),IA(603),AL343),IA(604),AL344),IA(605),
4IA(606),AL345),IA(606),AL346),IA(607),AL347),IA(608),AL348),IA(609),
5IA(610),AL349),IA(610),AL350),IA(611),AL351),IA(612),AL352),IA(613),
6IA(614),AL353),IA(614),AL354),IA(615),AL355),IA(616),AL356),IA(617),
7IA(618),AL357),IA(618),AL358),IA(619),AL359),IA(620),AL360),IA(621),
8IA(621),AL361),IA(621),AL362),IA(622),AL363),IA(623),AL364),IA(624),
9IA(625),AL365),IA(625),AL366),IA(626),AL367),IA(627),AL368),IA(628),
10IA(629),AL369),IA(629),AL370),IA(630),AL371),IA(631),AL372),IA(632),
11IA(633),AL373),IA(633),AL374),IA(634),AL375),IA(635),AL376),IA(636),
EQUIVALENCE IA(637),AL377),IA(637),AL378),IA(639),AL379),IA(640),
1IA(641),AL380),IA(641),AL381),IA(642),AL382),IA(643),AL383),IA(644),
2IA(645),AL384),IA(645),AL385),IA(646),AL386),IA(647),AL387),IA(648),
3IA(649),AL388),IA(649),AL389),IA(650),AL390),IA(651),AL391),IA(652),
4IA(653),AL392),IA(653),AL393),IA(654),AL394),IA(655),AL395),IA(656),
5IA(657),AL396),IA(657),AL397),IA(658),AL398),IA(659),AL399),IA(660),
6IA(661),AL400),IA(661),AL401),IA(662),AL402),IA(663),AL403),IA(664),
7IA(665),AL404),IA(665),AL405),IA(666),AL406),IA(667),AL407),IA(668),
8IA(669),AL408),IA(669),AL409),IA(670),AL410),IA(671),AL411),IA(672),
9IA(673),AL412),IA(673),AL413),IA(674),AL414),IA(675),AL415),IA(676),
10IA(677),AL416),IA(677),AL417),IA(678),AL418),IA(679),AL419),IA(680),
11IA(681),AL420),IA(681),AL421),IA(682),AL422),IA(683),AL423),IA(684),
EQUIVALENCE IA(685),AL424),IA(685),AL425),IA(686),AL426),IA(687),
1IA(688),AL427),IA(688),AL428),IA(689),AL429),IA(690),AL430),IA(691),
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10IA(724),AL463),IA(724),AL464),IA(725),AL465),IA(726),AL466),IA(727),
11IA(728),AL467),IA(728),AL468),IA(729),AL469),IA(730),AL470),IA(731),
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6IA(802),AL541),IA(802),AL542),IA(803),AL543),IA(804),AL544),IA(805),
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8IA(810),AL549),IA(810),AL550),IA(811),AL551),IA(812),AL552),IA(813),
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3IA(836),AL576),IA(836),AL577),IA(837),AL578),IA(838),AL579),IA(839),
4IA(840),AL580),IA(840),AL581),IA(841),AL582),IA(842),AL583),IA(843),
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6IA(848),AL588),IA(848),AL589),IA(849),AL590),IA(850),AL591),IA(851),
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11IA(868),AL608),IA(868),AL609),IA(869),AL610),IA(870),AL611),IA(871),
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2IA(882),AL621),IA(882),AL622),IA(883),AL623),IA(884),AL624),IA(885),
3IA(886),AL625),IA(886),AL626),IA(887),AL627),IA(888),AL628),IA(889),
4IA(890),AL629),IA(890),AL630),IA(891),AL631),IA(892),AL632),IA(893),
5IA(894),AL633),IA(894),AL634),IA(895),AL635),IA(896),AL636),IA(897),
6IA(898),AL637),IA(898),AL638),IA(899),AL639),IA(900),AL640),IA(901),
7IA(902),AL641),IA(902),AL642),IA(903),AL643),IA(904),AL644),IA(905),
8IA(906),AL645),IA(906),AL646),IA(907),AL647),IA(908),AL648),IA(909),
9IA(910),AL649),IA(910),AL650),IA(911),AL651),IA(912),AL652),IA(913),
10IA(914),AL653),IA(914),AL654),IA(915),AL655),IA(916),AL656),IA(917),
11IA(918),AL657),IA(918),AL658),IA(919),AL659),IA(920),AL660),IA(921),
EQUIVALENCE IA(922),AL661),IA(922),AL662),IA(923),AL663),IA(924),
1IA(925),AL664),IA(925),AL665),IA(926),AL666),IA(927),AL667),IA(928),
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7IA(949),AL688),IA(949),AL689),IA(950),AL690),IA(951),AL691),IA(952),
8IA(953),AL692),IA(953),AL693),IA(954),AL694),IA(955),AL695),IA(956),
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11IA(965),AL704),IA(965),AL705),IA(966),AL706),IA(967),AL707),IA(968),
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1IA(972),AL711),IA(972),AL712),IA(973),AL713),IA(974),AL714),IA(975),
2IA(976),AL715),IA(976),AL716),IA(977),AL717),IA(978),AL718),IA(979),
3IA(980),AL719),IA(980),AL720),IA(981),AL721),IA(982),AL722),IA(983),
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5IA(988),AL727),IA(988),AL728),IA(989),AL729),IA(990),AL730),IA(991),
6IA(992),AL731),IA(992),AL732),IA(993),AL733),IA(994),AL734),IA(995),
7IA(996),AL735),IA(996),AL736),IA(997),AL737),IA(998),AL738),IA(999),
8IA(1000),AL739),IA(1000),AL740),IA(1001),AL741),IA(1002),AL742),IA(1003),
9IA(1004),AL743),IA(1004),AL744),IA(1005),AL745),IA(1006),AL746),IA(1007),
10IA(1008),AL747),IA(1008),AL748),IA(1009),AL749),IA(1010),AL750),IA(1011),
11IA(1012),AL751),IA(1012),AL752),IA(1013),AL753),IA(1014),AL754),IA(1015),
EQUIVALENCE IA(1016),AL755),IA(1016),AL756),IA(1017),AL757),IA(1018),
1IA(1019),AL758),IA(1019),AL759),IA(1020),AL760),IA(1021),AL761),IA(1022),
2IA(1023),AL762),IA(1023),AL763),IA(1024),AL764),IA(1025),AL765),IA(1026),
3IA(1027),AL766),IA(1027),AL767),IA(1028),AL768),IA(1029),AL769),IA(1030),
4IA(1031),AL770),IA(1031),AL771),IA(1032),AL772),IA(1033),AL773),IA(1034),
5IA(1035),AL774),IA(1035),AL775),IA(1036),AL776),IA(1037),AL777),IA(1038),
6IA(1039),AL778),IA(1039),AL779),IA(1040),AL780),IA(1041),AL781),IA(1042),
7IA(1043),AL782),IA(1043),AL783),IA(1044),AL784),IA(1045),AL785),IA(1046),
8IA(1047),AL786),IA(1047),AL787),IA(1048),AL788),IA(1049),AL789),IA(1050),
9IA(1051),AL790),IA(1051),AL791),IA(1052),AL792),IA(1053),AL793),IA(1054),
10IA(1055),AL794),IA(1055),AL795),IA(1056),AL796),IA(1057),AL797),IA(1058),
11IA(1059),AL798),IA(1059),AL799),IA(1060),AL8
```

Table VII-57 (contd)

```

6032 DO 603 I=1,NR,3
6031 DD 604 L=1,K
      K=K+1
      J=L/2
      IF (J-3) 6031,6032,6032
      J=0
      I1=1+J
604 MSET(K)=MSET(I1)
603 CONTINUE
      KR=K
      MR=0
      DU 605 I=1,KR,2
      I2=I+2
      IF (I2-KR) 6051,6051,605
6051 IF (MSET(I1)-MSET(I2)) 605,605,6052
6052 IJ=0
      DO 606 J=12,KR,2
      IF (MSET(I1)-MSET(I1+J)) 6061,6062,6061
6061 IF (MSET(I1)-MSET(I1+J)) 606,6063,606
6063 IF (MSET(I1+1)-MSET(I1)) 606,6064,606
6062 IF (MSET(I1+1)-MSET(I1+1)) 606,6064,606
6064 MSET(I1)=0
      MSET(I1+1)=0
      IJ=IJ+1
606 CONTINUE
      IF (IJ-1) 6053,605,44
6053 MRB=MB
      DO 6054 J=1,MRB
      IF (NBAN(J)-MSET(I1)) 6054,6055,6054
6054 CONTINUE
      MR=MR+1
      NBAN(MR)=MSET(I1)
6055 DO 6056 J=1,MRB
      IF (NBAN(J)-MSET(I1+1)) 6056,605,6056
6056 CONTINUE
      MR=MR+1
      NBAN(MR)=MSET(I1+1)
605 CONTINUE
      GO TO 6057
601 DO 40 I=1,NB
40 MSET(I)=MSET(I)
      MB=0
      DO 39 I=1,NB
      IF (MSET(I)) 39,39,42
42 NODE=MSET(I)
      KLIM=0
      DO 38 J=1,NB
      IF (NODE-MSET(J)) 38,37,38
37 MSET(I)=0
      KLIM=KLIM+1
38 CONTINUE
      IF (ILIM-2) 411,412,602
411 IF (KLIM-1) 44,43,44
412 IF (KLIM-2) 43,39,444
C MDRE: THAN 2 REPETITION IS POSSIBLE IF IGEN=1
444 IF (IGEN-1) 44,39,44
43 NB=NR-1
      NBAN(MR)=NODE
      GO TO 39
44 WRITE OUTPUT TAPE 6,96)+ICN
961 FORMAT (15,15X,44#ERROR IN MESH TOPOLOGY.NODE ASSUMED INTERNAL)
      GO TO 90
39 CONTINUE
8057 IF (MR) 90,90,45
45 GO TO (461,462,463),ILIM
      F480F114
      F480F115
      F480F116
      F480F117
      F480F118
      F480F119
      F480F120
      F480F121
      F480F122
      F480F123
      F480F124
      F480F125
      F480F126
      F480F127
      F480F128
      F480F129
      F480F130
      F480F131
      F480F132
      F480F133
      F480F134
      F480F135
      F480F136
      F480F137
      F480F138
      F480F139
      F480F140
      F480F141
      F480F142
      F480F143
      F480F144
      F480F145
      F480F146
      F480F147
      F480F148
      F480F149
      F480F150
      F480F151
      F480F152
      F480F153
      F480F154
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      F480F157
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      F480F159
      F480F160
      F480F161
      F480F162
      F480F163
      F480F164
      F480F165
      F480F166
      F480F167
      F480F168
      F480F169
      F480F170
      F480F171
      F480F172
      F480F173
      F480F174
      F480F175
      F480F176
      F480F177
      F480F178
461 NBAN(I)=0
      NBAN(2)=0
      IF (NB-1) 44,47,90
462 IF (NB-2) 448,47,448
C OTHER THAN 2 NEIGHBORING BOUNDARY NODES POSSIBLE IF IGEN=1
448 IF (IGEN-1) 44,40,44
463 IF (MR-3) 44,47,47
C THE NODE IS ON BOUNDARY
47 INRON=1
      EST=1#
C ESTABLISH OUTER NORMAL ON RIR AND AREA ON ARE
      GO TO (48,49,50),ILIM
C ONE-DIMENSIONAL CONTINUUM, SHELL OF REVOLUTION
48 CALL INER(SIR)
      Q=-1
      CALL UNIT(BIR,0)
      ARE=0
      GO TO 90
C TWO-DIMENSIONAL CONTINUUM
49 CALL INER(SIR)
      K=NBAN(I)
      CALL FINDX(K,X)
      K=NBAN(I+2)
      CALL FINDX(K,Y)
      DO 491 I=1,3
491 RTAIL=K(I)-Y(I)
      ARE=L
      CALL UNIT(BIR,ARE)
      ARE=ARE/2
      Q=SCAL(BIR,SIR)
      DO 492 I=1,3
492 AIR(I)=SIR(I)-Q*BIR(I)
      IF (SCAL(BIR,SIR)) 493,441,494
441 INRON=0
      GO TO 44
493 Q=1
      DO 10 495
494 Q=-1
495 CALL UNIT(BIR,0)
      GO TO 90
C THREE-DIMENSIONAL CONTINUUM
50 CALL INER(SIR)
      CALL BEST(BIR,NBAN,MR)
      IF (SCAL(BIR,SIR)) 501,441,502
501 Q=1
      GO TO 503
502 Q=-1
503 CALL UNIT(BIR,0)
      Q=0
      DO 504 I=1,MR
      K=NBAN(I)
      CALL FINDX(K,XF)
504 Q=Q+SORTF(1#XF(I))-XN(I))**2+(XF(2)-XN(2))**2+(XF(3)-XN(3))**2
      ARE=MB
      ARE=3.14159*(Q/(2.*ARE))**2
      IF (INP-2) 100,91,91
91 WRITE OUTPUT TAPE 6,92,ICN,AS1,MR,(NBAN(I),I=1,MR)
92 FORMAT (15,41,14X,21#BOUNDARY NODES FOLLOW,120/(20X,2015))
      WRITE OUTPUT TAPE 6,93,MR,(MSET(I),I=1,MR)
93 FORMAT (20X,14#MSET ARRAY FOLLOWS,120/(20X,2015))
      WRITE OUTPUT TAPE 6,94,ARE,BIR(I),I=1,3)
94 FORMAT (20X,5#AREA=E15.5,5X,12#OUTER NORMAL,2X,3E15.6)
100 RETURN
      END
      F480F179
      F480F180
      F480F181
      F480F182
      F480F183
      F480F184
      F480F185
      F480F186
      F480F187
      F480F188
      F480F189
      F480F190
      F480F191
      F480F192
      F480F193
      F480F194
      F480F195
      F480F196
      F480F197
      F480F198
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      F480F200
      F480F201
      F480F202
      F480F203
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      F480F211
      F480F212
      F480F213
      F480F214
      F480F215
      F480F216
      F480F217
      F480F218
      F480F219
      F480F220
      F480F221
      F480F222
      F480F223
      F480F224
      F480F225
      F480F226
      F480F227
      F480F228
      F480F229
      F480F230
      F480F231
      F480F232
      F480F233
      F480F234
      F480F235
      F480F236
      F480F237
      F480F238
      F480F239
      F480F240
      F480F241
      F480F242

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Table VII-58. Source program listing of subroutine CAS4 (Link 4)

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* LABEL
DE+CAS4 F4CAS400
C SUBROUTINE CAS4 F4CAS401
  DUMMY SUBROUTINE F4CAS402
  RETURN F4CAS403
  END F4CAS404

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**Table VII-59. Source program listing of subroutine CODI (Link 4)**

**Table VII-60. Source program listing of subroutine DIMI (Link 4)**

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*      LAREL
CE4CUD
SUBROUTINE CODI
  TO GENERATE LOCAL-OVERALL COORDINATE TRANSFORMATION MATRIX
  DIMENSION IA(11),AA(1),S(1),N(8),D21(21),D33(3,3),E27(3,3)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
  COMMON IA,AA
  EQUIVALENCE(IA,AA), (D21,D33), (D21(10),E27), (D21(19),E1), (D21(20),G)
  EQUIVALENCE(IA(1),IN), (IA(2),IRN), (IA(3),IT), (IA(4),IP), (IA(5),
  1PRIS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INXI), (IA(10),
  31MF1), (IA(11),IB), (IA(12),IMNX), (IA(13),IMY1), (IA(14),IMZ1), (IA(15),
  41STR), (IA(16),IELT), (IA(17),ITEM), (IA(18),ITIC), (IA(19),IMET),
  5(IA(20),ISUM), (IA(21),IND), (IA(22),IMS1), (IA(23),IOS1), (IA(24),
  6IORD), (IA(25),IORD1), (IA(26),ACEL), (IA(27),J1), (IA(28),J2),
  7(IA(29),J3), (IA(30),J4), (IA(31),J5), (IA(32),J6), (IA(33),J7), (IA(34),
  8J8), (IA(35),J9), (IA(36),J10), (IA(37),J11), (IA(38),J12),
  9(IA(39),J13), (IA(40),J14), (IA(41),J15), (IA(42),J16), (IA(43),J17),
  10(IA(44),J18), (IA(45),J19), (IA(46),J20), (IA(47),J21), (IA(48),J22),
  11(IA(49),J23), (IA(50),J24), (IA(51),J25), (IA(52),J26), (IA(53),J27),
  12(IA(54),J28), (IA(55),J29), (IA(56),J30), (IA(57),J31), (IA(58),J32),
  13(IA(59),J33), (IA(60),J34), (IA(61),J35), (IA(62),J36), (IA(63),J37),
  14(IA(64),J38), (IA(65),J39), (IA(66),J40), (IA(67),J41), (IA(68),J42),
  15(IA(69),J43), (IA(70),J44), (IA(71),J45), (IA(72),J46), (IA(73),J47),
  16(IA(74),J48), (IA(75),J49), (IA(76),J50), (IA(77),J51), (IA(78),J52),
  17(IA(79),J53), (IA(80),J54), (IA(81),J55), (IA(82),J56), (IA(83),J57),
  18(IA(84),J58), (IA(85),J59), (IA(86),J60), (IA(87),J61), (IA(88),J62),
  19(IA(89),J63), (IA(90),J64), (IA(91),J65), (IA(92),J66), (IA(93),J67),
  20(IA(94),J68), (IA(95),J69), (IA(96),J70), (IA(97),J71), (IA(98),J72),
  21(IA(99),J73), (IA(100),J74), (IA(101),J75), (IA(102),J76), (IA(103),J77),
  22(IA(104),J78), (IA(105),J79), (IA(106),J80), (IA(107),J81), (IA(108),J82),
  23(IA(109),J83), (IA(110),J84), (IA(111),J85), (IA(112),J86), (IA(113),J87),
  24(IA(114),J88), (IA(115),J89), (IA(116),J90), (IA(117),J91), (IA(118),J92),
  25(IA(119),J93), (IA(120),J94), (IA(121),J95), (IA(122),J96), (IA(123),J97),
  26(IA(124),J98), (IA(125),J99), (IA(126),J100), (IA(127),J101), (IA(128),J102),
  27(IA(129),J103), (IA(130),J104), (IA(131),J105), (IA(132),J106), (IA(133),J107),
  28(IA(134),J108), (IA(135),J109), (IA(136),J110), (IA(137),J111), (IA(138),J112),
  29(IA(139),J113), (IA(140),J114), (IA(141),J115), (IA(142),J116), (IA(143),J117),
  30(IA(144),J118), (IA(145),J119), (IA(146),J120), (IA(147),J121), (IA(148),J122),
  31(IA(149),J123), (IA(150),J124), (IA(151),J125), (IA(152),J126), (IA(153),J127),
  32(IA(154),J128), (IA(155),J129), (IA(156),J130), (IA(157),J131), (IA(158),J132),
  33(IA(159),J133), (IA(160),J134), (IA(161),J135), (IA(162),J136), (IA(163),J137),
  34(IA(164),J138), (IA(165),J139), (IA(166),J140), (IA(167),J141), (IA(168),J142),
  35(IA(169),J143), (IA(170),J144), (IA(171),J145), (IA(172),J146), (IA(173),J147),
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  67(IA(329),J303), (IA(330),J304), (IA(331),J305), (IA(332),J306), (IA(333),J307),
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  130(IA(644),J618), (IA(645),J619), (IA(646),J620), (IA(647),J621), (IA(648),J622),
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  144(IA(714),J688), (IA(715),J689), (IA(716),J690), (IA(717),J691), (IA(718),J692),
  145(IA(719),J693), (IA(720),J694), (IA(721),J695), (IA(722),J696), (IA(723),J697),
  146(IA(724),J698), (IA(725),J699), (IA(726),J700), (IA(727),J701), (IA(728),J702),
  147(IA(729),J703), (IA(730),J704), (IA(731),J705), (IA(732),J706), (IA(733),J707),
  148(IA(734),J708), (IA(735),J709), (IA(736),J710), (IA(737),J711), (IA(738),J712),
  149(IA(739),J713), (IA(740),J714), (IA(741),J715), (IA(742),J716), (IA(743),J717),
  150(IA(744),J718), (IA(745),J719), (IA(746),J720), (IA(747),J721), (IA(748),J722),
  151(IA(749),J723), (IA(750),J724), (IA(751),J725), (IA(752),J726), (IA(753),J727),
  152(IA(754),J728), (IA(755),J729), (IA(756),J730), (IA(757),J731), (IA(758),J732),
  153(IA(759),J733), (IA(760),J734), (IA(761),J735), (IA(762),J736), (IA(763),J737),
  154(IA(764),J738), (IA(765),J739), (IA(766),J740), (IA(767),J741), (IA(768),J742),
  155(IA(769),J743), (IA(770),J744), (IA(771),J745), (IA(772),J746), (IA(773),J747),
  156(IA(774),J748), (IA(775),J749), (IA(776),J750), (IA(777),J751), (IA(778),J752),
  157(IA(779),J753), (IA(780),J754), (IA(781),J755), (IA(782),J756), (IA(783),J757),
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  159(IA(789),J763), (IA(790),J764), (IA(791),J765), (IA(792),J766), (IA(793),J767),
  160(IA(794),J768), (IA(795),J769), (IA(796),J770), (IA(797),J771), (IA(798),J772),
  161(IA(799),J773), (IA(800),J774), (IA(801),J775), (IA(802),J776), (IA(803),J777),
  162(IA(804),J778), (IA(805),J779), (IA(806),J780), (IA(807),J781), (IA(808),J782),
  163(IA(809),J783), (IA(810),J784), (IA(811),J785), (IA(812),J786), (IA(813),J787),
  164(IA(814),J788), (IA(815),J789), (IA(816),J790), (IA(817),J791), (IA(818),J792),
  165(IA(819),J793), (IA(820),J794), (IA(821),J795), (IA(822),J796), (IA(823),J797),
  166(IA(824),J798), (IA(825),J799), (IA(826),J800), (IA(827),J801), (IA(828),J802),
  167(IA(829),J803), (IA(830),J804), (IA(831),J805), (IA(832),J806), (IA(833),J807),
  168(IA(834),J808), (IA(835),J809), (IA(836),J810), (IA(837),J811), (IA(838),J812),
  169(IA(839),J813), (IA(840),J814), (IA(841),J815), (IA(842),J816), (IA(843),J817),
  170(IA(844),J818), (IA(845),J819), (IA(846),J820), (IA(847),J821), (IA(848),J822),
  171(IA(849),J823), (IA(850),J824), (IA(851),J825), (IA(852),J826), (IA(853),J827),
  172(IA(854),J828), (IA(855),J829), (IA(856),J830), (IA(857),J831), (IA(858),J832),
  173(IA(859),J833), (IA(860),J834), (IA(861),J835), (IA(862),J836), (IA(863),J837),
  174(IA(864),J838), (IA(865),J839), (IA(866),J840), (IA(867),J841), (IA(868),J842),
  175(IA(869),J843), (IA(870),J844), (IA(871),J845), (IA(872),J846), (IA(873),J847),
  176(IA(874),J848), (IA(875),J849), (IA(876),J850), (IA(877),J851), (IA(878),J852),
  177(IA(879),J853), (IA(880),J854), (IA(881),J855), (IA(882),J856), (IA(883),J857),
  178(IA(884),J858), (IA(885),J859), (IA(886),J860), (IA(887),J861), (IA(888),J862),
  179(IA(889),J863), (IA(890),J864), (IA(891),J865), (IA(892),J866), (IA(893),J867),
  180(IA(894),J868), (IA(895),J869), (IA(896),J870), (IA(897),J871), (IA(898),J872),
  181(IA(899),J873), (IA(900),J874), (IA(901),J875), (IA(902),J876), (IA(903),J877),
  182(IA(904),J878), (IA(905),J879), (IA(906),J880), (IA(907),J881), (IA(908),J882),
  183(IA(909),J883), (IA(910),J884), (IA(911),J885), (IA(912),J886), (IA(913),J887),
  184(IA(914),J888), (IA(915),J889), (IA(916),J890), (IA(917),J891), (IA(918),J892),
  185(IA(919),J893), (IA(920),J894), (IA(921),J895), (IA(922),J896), (IA(923),J897),
  186(IA(924),J898), (IA(925),J899), (IA(926),J900), (IA(927),J901), (IA(928),J902),
  187(IA(929),J903), (IA(930),J904), (IA(931),J905), (IA(932),J906), (IA(933),J907),
  188(IA(934),J908), (IA(935),J909), (IA(936),J910), (IA(937),J911), (IA(938),J912),
  189(IA(939),J913), (IA(940),J914), (IA(941),J915), (IA(942),J
```

Table VII-60 (contd)

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JM4=JM-4
PV(IM,J)=PV(IM4,J)
PV(IM4,J)=0.
450 CONTINUE
500 WRITE OUTPUT TAPE 6,3
3 FORMAT (1H )
DO 510 J=1,6
510 PV(I,J)=-PVT(I,J)
WRITE OUTPUT TAPE 6,2,(M,N(I)),TFLT,(PV(J,I),J=1,6),I=1,2)
2 FORMAT (1X,14,216,3X,6E15,5)
1000 CONTINUE
1010 RETURN
1100 IERR=1
K=M
IA(201)=MM
GO TO 1010
END

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E401M114
E401M115
E401M116
E401M117
E401M118
E401M119
E401M120
E401M121
E401M122
E401M123
E401M124
E401M125
E401M126
E401M127
E401M128
E401M129
E401M130

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Table VII-61. Source program listing of subroutine DINA (Link 4)

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* LABEL
CE4DIN SURROUTINE DINA
C OBTAINS LOCAL COORDINATE AXES AT A NODE IN SHELLS
C TO GENERATE BAS VECIDR, DIN MATRIX AND ANGLE
C DIMENSION IA(1),AA(1),S(1),N(1),O21(21),O33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
COMMON IA,AA
EQUIVALENCE (IA,AA), (O21,O33), (O21(10),E22), (O21(19),E), (O21(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5),
1)PRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEC), (IA(9),INXI), (IA(10),E401N007
EQUIVALENCE (IA(11),I8), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),E401N009
2)H), (IA(16),IARF), (IA(17),M(11)), (IA(25),M), (IA(26),ITY), (IA(27),E401N010
3)MFI), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IME7),
4)STR), (IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IUS), (IA(37),
5) (IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IUS), (IA(37),
6)ORD), (IA(38),IORD), (IA(39),ACFL), (IA(50),JL), (IA(51),J2),
7) (IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),E401N015
8)JRI), (IA(58),JTY), (IA(59),IBO), (IA(60),IBO), (IA(61),IID), (IA(62),E401N016
9)IA), (IA(63),IDI), (IA(64),IDY), (IA(65),ITF), (IA(41),ITAP)
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIV), (IA(69),
1)CIZ), (IA(70),ICFI), (IA(71),ICX), (IA(72),IY), (IA(73),I2Z),
2) (IA(74),IC), (IA(75),IDF), (IA(76),IST), (IA(77),IIS)
3, (IA(78),IGEM), (IA(79),IERR), (AA(80),IF), (AA(81),DT), (AA(82),DG),
4) (AA(83),ALI), (AA(84),AL2), (AA(85),M3), (AA(86),O21), (AA(107),P),
5) (AA(131),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD),
6) (AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(40),ZREM)
7, (AA(42),INP), (AA(43),IPBG), (AA(44),IPEN), (AA(45),CONS), (AA(46),J)
8), (AA(47),G1), (AA(48),G2), (AA(49),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISHY), (IA(346)
1),ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSOY)
2, (IA(341),JSOZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY)
3, (IA(337),JMNZ), (IA(336),JMF), (IA(335),IAS), (IA(334),IDZ)
4, (IA(333),IPR), (AA(332),DGY), (AA(331),DGZ), (AA(330),PRFS)
5, (IA(329),IPR)
DIMENSION BIR(3),SIR(3),DIM(3,3),SR(6),XM(3),XF(3),DN(6),OF(6),
1)RES(6),RE(6),BAS(3),ICLAS(4),NRAN(10),N(13),NFS(3)
EQUIVALENCE (AA(200),JONE), (AA(201),ICN), (AA(202),LMI), (AA(203),ASTF)
1), (AA(204),JNBON), (AA(205),ARE), (AA(206),ICLA), (AA(207),IMFL),
2) (AA(208),INI), (AA(209),IC), (AA(210),ICUN), (AA(211),ANGLE), (AA(212),
3) ICAS), (AA(213),IE), (AA(214),NRI), (AA(215),MB)
4, (AA(216),IROT), (AA(217),RST)
EQUIVALENCE (AA(220),BR), (AA(223),SIR), (AA(226),DIM), (AA(235),SR)
1, (AA(241),XN), (AA(244),XF), (AA(247),ON), (AA(253),OF), (AA(259),RES)
2, (AA(265),RED), (AA(271),BAS), (AA(274),ICLAS), (AA(278),NRAN)
3, (AA(292),NII), (AA(295),NES)
DIMENSION NEL(20,17),MAC(4,4,20),TWR(90),MD(6,6),A(90,7),R(8,8),
1) (AA(241),XN), (AA(244),XF), (AA(247),ON), (AA(253),OF), (AA(259),RES)
2, (AA(265),RED), (AA(271),BAS), (AA(274),ICLAS), (AA(278),NRAN)
3, (AA(292),NII), (AA(295),NES)
EQUIVALENCE (AA(1000),FF), (M(11),JP1), (M(2),JM1), (M(3),JS1)
EQUIVALENCE (FF(1),NEL), (FF(341),MAC), (FF(661),ING), (FF(751),DD)
1) (FF(787),A), (FF(1417),B), (FF(1481),C), (FF(1497),NSF), (FF(1597),
2) MSET), (FF(1697),W)
C SEE IF DIN AND ANGLE ARE TO BE OBTAINED VIA SUBROUTINE AGLF
IF (IPTR-1) 3,3,4
C CALL SUBROUTINE AGLF FOR DIN AND ANGLE
CALL AGLF
GO TO 5
C IS IT SHELL OF REVOLUTION
IF (ICAS-6) 20,20,21
C SHELL OF REVOLUTION
CALL REVU
GO TO 5
C GENERAL SHELL. DETERMINE DIN AND ANGLE BY BEST FIT QUADRATIC
CALL QUAD
IF (INP-2) 7,6,6
WRITE OUTPUT TAPE 6,61,ANGLE, ((DIN(I,J),I=1,3),J=1,3)
6) FORMAT(20X
,5HANGLE,2X,F10,3/
120X,3HDIN,5X,3HMS1,2X,3F7,4,5X,3HETA,2X,3F7,4,5X,4HZETA,1X,3F7,4)
RETURN
7)
END

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Table VII-63. Source program listing of subroutine FINDQ (Link 4)

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* LABEL
CE4FNQ SUBROUTINE FINDQ(K,0)
C OBTAINS DEFLECTIONS OF A NODE IN OVERALL COORDINATES
C TO GENERATE THE DEFLECTIONS OF NODE K ON VECTOR 0
DIMENSION IA(11),AA(21),S(11),N(8),D21(21),D33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),E1), (D21(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5),
1)PRS), (IA(6),ITYPE), (IA(7),IMAI), (IA(8),IDEG), (IA(9),INX), (IA(10),
2)M), (IA(11),IB), (IA(12),IMMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),
3)MF1), (IA(16),IARE), (IA(17),NI1), (IA(18),M), (IA(19),IT), (IA(20),
4)STR), (IA(21),IELT), (IA(22),ITEM), (IA(23),ITIC), (IA(24),IMET),
5)IA(25),ISUM), (IA(26),INDI), (IA(27),AGEL), (IA(28),J1), (IA(29),
6)J2), (IA(30),IORD1), (IA(31),IORD2), (IA(32),IORD3), (IA(33),IORD4),
7)J3), (IA(34),J4), (IA(35),J5), (IA(36),J6), (IA(37),J7), (IA(38),
8)J8), (IA(39),J9), (IA(40),J10), (IA(41),J11), (IA(42),J12),
9)IA(43),IA(44),IA(45),IA(46),IA(47),IA(48),IA(49),IA(50),IA(51),IA(52),
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICY), (IA(69),
1)ICIZ), (IA(70),ICF), (IA(71),IX), (IA(72),IY), (IA(73),IZ),
2)IA(74),IIG), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS),
3)IA(78),IGEM), (IA(79),IERR), (IA(80),TE), (IA(81),DT), (IA(82),DG),
4)AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(87),P),
5)AA(88),UV), (AA(89),X), (AA(90),Y), (AA(91),Z), (AA(92),XD),
6)AA(93),VD), (AA(94),ZD), (AA(95),S), (AA(96),ZGEM)
7)IA(97),INP), (AA(98),IPRR), (AA(99),IPRN), (AA(100),CONS), (AA(101),
8)IA(102),G1), (AA(103),G2), (AA(104),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISD1), (IA(347),ISD2), (IA(346),
1)ISD3), (IA(345),J91), (IA(344),J10), (IA(343),JPHS1), (IA(342),JSDY)
2)IA(341),JSDZ), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY)
3)IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ)
4)IA(333),IPR), (AA(332),DGY), (AA(331),DG1), (AA(330),PRES)
5)IA(329),IPR)
DIMENSION BIR(3),SIR(3),DIN(3,3),SR(6),XN(3),XF(3),ON(6),OF(6),
1)RES(6),RED(6),BAS(3),ICLAS(4),NRAN(10),NU(3),NES(3)
EQUIVALENCE (AA(200),IDNE), (AA(201),ICN), (AA(202),LM), (AA(203),ASTE)
1), (AA(204),INBDN), (AA(205),ARE), (AA(206),ICLA), (AA(207),IMF1),
2)AA(209),IM), (AA(209),IC), (AA(210),ICDN), (AA(211),ANGLE), (AA(212),
3)ICAST), (AA(213),IE), (AA(214),NR), (AA(215),MB)
4)IA(216),IRH), (AA(217),BST)
EQUIVALENCE (AA(220),BIR), (AA(223),SIR), (AA(226),DIN), (AA(235),SR)
1)AA(241),XN), (AA(244),XF), (AA(247),ON), (AA(253),OF), (AA(259),RES)
2)AA(265),RED), (AA(271),BAS), (AA(274),ICLAS), (AA(278),NRAN)
3)AA(292),NU), (AA(295),NES)
DIMENSION NEL(20,17),MAC(4,4,20),IMG(90),DD(6,6),A(90,7),R(6,8),
1)C(8,2),FF(11),NSFT(100),MSFT(100),W(3,3)
EQUIVALENCE (AA(14000),FF), (MU(1),JPI), (MU(2),JMI), (MU(3),JSJ)
EQUIVALENCE (FF(1),NEL), (FF(34),MAC), (FF(166),IMG), (FF(175),DD),
1)FF(177),A), (FF(1417),B), (FF(1481),C), (FF(1497),NSET), (FF(1597),
2)MSFT), (FF(1697),N)
DIMENSION O(16)
IDEF1=IDFF+K-1)*IDEG
DD LO I=1,IDEG
IDEF1=IDFF+I
O(1)=AA(1)DEF1
CONTINUE
RETURN
END

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Table VII-64. Source program listing of subroutine FINDX (Link 4)

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* LABEL
CE4FNX SUBROUTINE FINDX(K,0)
C OBTAINS OVERALL COORDINATES OF A NODE
C TO GENERATE THE COORDINATES OF NODE K ON VECTOR 0
DIMENSION IA(11),AA(1),S(11),N(8),D21(21),D33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),E1), (D21(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5),
1)PRS), (IA(6),ITYPE), (IA(7),IMAI), (IA(8),IDEG), (IA(9),INX), (IA(10),
2)M), (IA(11),IB), (IA(12),IMMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),
3)MF1), (IA(16),IARE), (IA(17),NI1), (IA(18),M), (IA(19),IT), (IA(20),
4)STR), (IA(21),IELT), (IA(22),ITEM), (IA(23),ITIC), (IA(24),IMET),
5)IA(25),ISUM), (IA(26),INDI), (IA(27),AGEL), (IA(28),J1), (IA(29),
6)J2), (IA(30),IORD1), (IA(31),IORD2), (IA(32),IORD3), (IA(33),IORD4),
7)J3), (IA(34),J4), (IA(35),J5), (IA(36),J6), (IA(37),J7), (IA(38),
8)J8), (IA(39),J9), (IA(40),J10), (IA(41),J11), (IA(42),J12),
9)IA(43),IA(44),IA(45),IA(46),IA(47),IA(48),IA(49),IA(50),IA(51),IA(52),
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICY), (IA(69),
1)ICIZ), (IA(70),ICF), (IA(71),IX), (IA(72),IY), (IA(73),IZ),
2)IA(74),IIG), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS),
3)IA(78),IGEM), (IA(79),IERR), (IA(80),TE), (IA(81),DT), (IA(82),DG),
4)AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(87),P),
5)AA(88),UV), (AA(89),X), (AA(90),Y), (AA(91),Z), (AA(92),XD),
6)AA(93),VD), (AA(94),ZD), (AA(95),S), (AA(96),ZGEM)
7)IA(97),INP), (AA(98),IPRR), (AA(99),IPRN), (AA(100),CONS), (AA(101),
8)IA(102),G1), (AA(103),G2), (AA(104),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISD1), (IA(347),ISD2), (IA(346),
1)ISD3), (IA(345),J91), (IA(344),J10), (IA(343),JPHS1), (IA(342),JSDY)
2)IA(341),JSDZ), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY)
3)IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ)
4)IA(333),IPR), (AA(332),DGY), (AA(331),DG1), (AA(330),PRES)
5)IA(329),IPR)
DIMENSION BIR(3),SIR(3),DIN(3,3),SR(6),XN(3),XF(3),ON(6),OF(6),
1)RES(6),RED(6),BAS(3),ICLAS(4),NRAN(10),NU(3),NES(3)
EQUIVALENCE (AA(200),IDNE), (AA(201),ICN), (AA(202),LM), (AA(203),ASTE)
1), (AA(204),INBDN), (AA(205),ARE), (AA(206),ICLA), (AA(207),IMF1),
2)AA(209),IM), (AA(209),IC), (AA(210),ICDN), (AA(211),ANGLE), (AA(212),
3)ICAST), (AA(213),IE), (AA(214),NR), (AA(215),MB)
4)IA(216),IRH), (AA(217),BST)
EQUIVALENCE (AA(220),BIR), (AA(223),SIR), (AA(226),DIN), (AA(235),SR)
1)AA(241),XN), (AA(244),XF), (AA(247),ON), (AA(253),OF), (AA(259),RES)
2)AA(265),RED), (AA(271),BAS), (AA(274),ICLAS), (AA(278),NRAN)
3)AA(292),NU), (AA(295),NES)
DIMENSION NEL(20,17),MAC(4,4,20),IMG(90),DD(6,6),A(90,7),R(6,8),
1)C(8,2),FF(11),NSFT(100),MSFT(100),W(3,3)
EQUIVALENCE (AA(14000),FF), (MU(1),JPI), (MU(2),JMI), (MU(3),JSJ)
EQUIVALENCE (FF(1),NEL), (FF(34),MAC), (FF(166),IMG), (FF(175),DD),
1)FF(177),A), (FF(1417),B), (FF(1481),C), (FF(1497),NSET), (FF(1597),
2)MSFT), (FF(1697),N)
DIMENSION O(16)
IDEF1=IDFF+K-1)*IDEG
DD LO I=1,IDEG
IDEF1=IDFF+I
O(1)=AA(1)DEF1
CONTINUE
RETURN
END

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Table VII-65. Source program listing of subroutine GENE (Link 4)

C	CE4GEN	LABEL	PROGRAM	LINE	CODE	COMMENT
		SUBROUTINE GENE	E4GEN000	13	IC=3	F4GEN076
		GENERATES NEL AND MAC MATRICES OF A NODE	E4GEN001	15	GO TO 6	E4GEN077
		TO GENERATE NEL(I,J),MAC(I,J,K),IMEL AND ICLAS(I)	E4GEN002		IC=5	E4GEN078
		DIMENSION IA(1,AA(1),S(1),N(1),D21(21),D33(3,3),E22(3,3))	E4GEN003	16	IC=6	F4GEN079
		1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)	E4GEN004	6	NEL(I,2)=I*ELT	F4GEN080
		COMMON IA,AA	E4GEN005		NEL(I,3)=I*MET	E4GEN081
		EQUIVALENCE(IA,AA),(D21,D33),(D21(10),E22),(D21(19),E),(D21(20),G)	E4GEN006		NEL(I,4)=I*IC	E4GEN082
		EQUIVALENCE(IA(1),IA(2),IRN),(IA(3),IT),(IA(4),IP),(IA(5),	E4GEN007		NEL(I,5)=I*MS	F4GEN083
		1PRS),(IA(6),IYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),IMX),(IA(10),F4GEN009	E4GEN008		NEL(I,6)=I*III	F4GEN084
		2IM),(IA(11),IB),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),F4GEN010	E4GEN009		NEL(I,7)=JSDZ	F4GEN085
		3IMF),(IA(16),IARE),(IA(17),NII),(IA(18),M),(IA(19),IY),(IA(20),F4GEN011	E4GEN010		NEL(I,8)=JPRS	F4GEN086
		4ISTR),(IA(21),IEL),(IA(22),ITEM),(IA(23),ITIC),(IA(24),IMET),	E4GEN011		NEL(I,9)=ITEM	E4GEN087
		5(IA(25),ISUM),(IA(26),INNI),(IA(27),IMS),(IA(28),IDSI),(IA(29),F4GEN012	E4GEN012		DO 7 J=1,IMS	E4GEN088
		6IDRD),(IA(30),IDRDI),(IA(31),ACEL),(IA(32),J),(IA(33),J2),	E4GEN013	7	NEL(I,J)=J*(I	E4GEN089
		7(IA(34),J3),(IA(35),J4),(IA(36),J5),(IA(37),J6),(IA(38),J7),(IA(39),F4GEN014	E4GEN014		IMS=0	E4GEN090
		8),J8),(IA(39),JTY),(IA(40),IBB),(IA(41),IBD),(IA(42),IID),(IA(43),F4GEN015	E4GEN015		JSDZ=0	E4GEN091
		9(IA(44),IDJ),(IA(45),IDY),(IA(46),IDZ),(IA(47),IIS),(IA(48),IIP),	E4GEN016		ITIC=0	E4GEN092
		EQUIVALENCE(IA(66),ICAR),(IA(67),ICX),(IA(68),ICY),(IA(69),	E4GEN017		IC=0	E4GEN093
		1(IA(70),ICF),(IA(71),ICX),(IA(72),IY),(IA(73),IZ),	E4GEN018	1	CONTINUE	E4GEN094
		2(IA(74),IIC),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS)	E4GEN019	71	IF (INP-2) 70,71,71	E4GEN095
		3,(IA(78),IGEM),(IA(79),IERR),(IA(80),TE),(IA(81),DT),(AA(82),DC),	E4GEN020	72	WRITE OUTPUT TAPE 6,72,ICN,LM,(NEL(I,J),J=1,7),I=1,LM1	E4GEN096
		4(IA(83),AL1),(IA(84),AL2),(IA(85),AL3),(IA(86),O21),(AA(107),P),	E4GEN021	70	FORMAT (15,15X,18HNEEL MATRIX FOLLOWS,120(10X,1715))	E4GEN097
		5(IA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),	E4GEN022	72	IMEL=	E4GEN098
		6(IA(181),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM),	E4GEN023		DO 210 I=1,LM	F4GN100
		7,(AA(42),INP),(AA(43),IPBG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IUE4GEN025	E4GEN024	210	NEL(I)=NEL(I,4)	F4GEN101
		8),(AA(47),G1),(AA(48),G2),(AA(49),G3)	E4GEN025		NEL(I)=NEL(I,3)	E4GEN102
		EQUIVALENCE(IA(349),NTIC),(IA(348),ISDIT),(IA(347),ISDY),(IA(346)	E4GEN026		LM=0	E4GEN103
		1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)	E4GEN027		DO 21 I=1,LM1	F4GEN104
		2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)	E4GEN028	211	IF (NELM(I)) 21,21,211	F4GEN105
		3,(IA(337),JMMZ),(IA(336),JMF),(IA(335),IAT5),(IA(334),IDZ)	E4GEN029		LM=LM+1	F4GEN106
		4,(IA(333),IPR),(IA(332),DGY),(AA(331),DGZ),(AA(330),PRES)	E4GEN030		IF (LMT-4) 212,212,213	F4GEN107
		5,(IA(329),IPR)	E4GEN031	213	WRITE OUTPUT TAPE 6,214,ICN	E4GEN108
		DIMENSION BIR(3),SIR(3),DIR(3),SR(4),XN(3),XF(3),ON(6),OF(6),	E4GEN032	214	FORMAT (15,15X,4)HMORE THAN 4 MATERIALS, FIRST 4 CONSIDERED	E4GEN109
		1RES(6),KFD(1),BAS(3),ICLAS(4),NBAN(10),NU(3),NES(3)	F4GEN033		LMT=LMT+1	F4GEN110
		EQUIVALENCE(AA(200),TONE),(AA(201),ICN),(AA(202),LM),(AA(203),ASTF4GEN035	E4GEN034	212	IMET=NELM(I)	F4GEN111
		1,(AA(204),INBN),(AA(205),ARE),(AA(206),ICLA),(AA(207),IMEL),	E4GEN035		LCL=0	F4GEN112
		2,(AA(208),IM),(AA(209),IC),(AA(210),ICON),(AA(211),ANGLE),(AA(212),	E4GEN036		DO 22 J=1,LM	E4GEN113
		3ICAS),(AA(213),IE),(AA(214),NB),(AA(215),MB)	F4GEN037		IF (IMET-NELM(J)) 22,220,22	E4GEN114
		4,IAA(216),IROT),(AA(217),RST)	E4GEN038	220	IF (IMET-NELM(J)) 22,220,22	E4GEN115
		EQUIVALENCE(AA(220),BIR),(AA(221),SIR),(AA(226),DIR),(AA(235),SR)E4GEN040	E4GEN039	221	LCL=LCL+1	E4GEN116
		1,IAA(241),XN),(AA(244),XF),(AA(247),ON),(AA(251),OF),(AA(259),RES)E4GEN041	E4GEN040		IF (LCL-4) 222,222,223	E4GEN117
		2,(AA(265),RED),(AA(271),BAS),(AA(274),ICLA),(AA(278),NBAN)	E4GEN042	223	WRITE OUTPUT TAPE 6,224,ICN,IMET	E4GEN118
		3,IAA(292),NU),(AA(295),NES)	F4GEN043	224	FORMAT (15,10X,3)HMORE THAN 4 CLASSES, FIRST 4 CONSIDERED	E4GEN119
		DIMENSION NEL(20,17),MAC(4,4,20),IWS(90),DD(6,6),A(90,7),B(8,8),	F4GEN044		LCL=LCL-1	E4GEN120
		1C(8,2),FF(1),MSET(100),MSET(100),W(3,3)	F4GEN045	222	ICLA=NELC(I)	F4GEN121
		EQUIVALENCE(AA(14000),FF),INUI(1),JP1),(NU(2),JM),(NU(3),JS1)	E4GEN046		L=1	F4GEN122
		EQUIVALENCE(FF(1),NEL),(FF(341),MAC),(FF(661),IWS),(FF(751),DD),	E4GEN047		MAC(LMT,LCL,L)=0	E4GEN123
		1(FF(787),A),(FF(1417),B),(FF(1481),C),(FF(1497),MSET),(FF(1597),	E4GEN048		DO 23 K=J,LM	F4GEN124
		2MSET),(FF(1697),W)	F4GEN049		IF (IMET-NELM(K)) 23,231,23	E4GEN125
		DIMENSION NELM(20),NELC(20)	F4GEN050	231	IF (ICLA-NELC(K)) 23,232,23	E4GEN126
		EQUIVALENCE(IMSET,NFLM),(MSET(21)-NELC)	F4GEN051	232	NELM(K)=0	E4GEN127
		LM=LM	F4GEN052		NELC(K)=0	E4GEN128
		OO 1 I=1,LM	F4GEN053		L=L+1	E4GEN129
		M=NFL(I,1)	F4GEN054		IF (L-20) 233,233,234	E4GEN130
		CALL TOPU	F4GEN055		WRITE OUTPUT TAPE 6,235,ICN,IMET,ICLA	F4GEN131
		KELT=IELT	F4GEN056	234	FORMAT (15,15X,4)HMORE THAN 19 ELEMENTS, FIRST 19 CONSIDERED	E4GEN132
		GO TO 11,1+1,1+3,4,3,4,4,0,3,4,3,4,3,4,2,2),KELT	F4GEN057	235	LCL=	E4GEN133
		IMS=3	F4GEN058		GO TO 23	F4GEN134
		GO TO 5	F4GEN059		MAC(LMT,LCL,L)=K	F4GEN135
		IMS=4	F4GEN060		MAC(LMT,LCL,L)=MAC(LMT,LCL,L+1)	F4GEN136
		GO TO 5	F4GEN061		CONTINUE	F4GEN137
		IMS=8	F4GEN062	23	CONTINUE	F4GEN138
		GO TO 8	F4GEN063	22	ICLAS(LMT)=LCL	F4GEN139
		IMS=2	F4GEN064		CONTINUE	E4GEN140
		GO TO 11,1+1,1+11,1+12,12,14,14,18,18,17,17,13,13,15,16),KELT	F4GEN065		IMEL=LMT	F4GEN141
		IC=1	F4GEN066		IF INP-2) 90,81,81	F4GEN142
		GO TO 6	E4GEN067		DO 83 I=1,LM1	F4GEN143
		IC=2	E4GEN068	81	ICLA=ICLAS(I)	E4GEN144
		GO TO 6	F4GEN069		WRITE OUTPUT TAPE 6,82,ICN,I,(J,(MAC(I,J,K),K=1,20),J=1,ICLA)	E4GEN145
		IC=4	F4GEN070		FORMAT(15,15X,36)HMAC MATRICE(S) FOLLOWS(5) MAT,SEQ=I3/	E4GEN146
		GO TO 6	F4GEN071		1(17X,13,2015)	F4GEN147
		IC=8	F4GEN072		CONTINUE	F4GEN148
		GO TO 6	E4GEN073	83	CONTINUE	F4GEN149
		IC=7	E4GEN074	90	RETURN	E4GEN150
		GO TO 6	F4GEN075		END	F4GEN151
						F4GEN152

Table VII-66. Source program listing of subroutine INER (Link 4)

C	CE4INR	LABEL	PROGRAM	LINE	CODE	COMMENT
		SUBROUTINE INER(CIR)	E4INR000	4	(IA(333),IPR),(IA(332),DGY),(AA(331),DGZ),(AA(330),PRES)	F4INR031
		OBTAINS A VECTOR HEADING TOWARDS THE STRUCTURE AT A BOUNDARY NODE	E4INR001	5	(IA(329),IPR)	E4INR032
		TO GENERATE A VECTOR HEADING INTO THE STRUCTURE ON CIR(I)	E4INR002		DIMENSION BIR(3),SIR(3),DIR(3),SR(4),XN(3),XF(3),ON(6),OF(6),	E4INR033
		DIMENSION IA(1,AA(1),S(1),N(1),D21(21),D33(3,3),E22(3,3))	E4INR003		1RES(6),RED(6),BAS(3),ICLAS(4),NBAN(10),NU(3),NES(3)	F4INR034
		1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)	E4INR004		EQUIVALENCE(AA(200),TONE),(AA(201),ICN),(AA(202),LM),(AA(203),ASTF4INR035	F4INR035
		COMMON IA,AA	E4INR005		1,(AA(204),INBN),(AA(205),ARE),(AA(206),ICLA),(AA(207),IMEL),	F4INR036
		EQUIVALENCE(IA,AA),(D21,D33),(D21(10),F22),(D21(19),E),(D21(20),G)	E4INR006		2(IA(208),IM),(AA(209),IC),(AA(210),ICON),(AA(211),ANGLE),(AA(212),	F4INR037
		EQUIVALENCE(IA(1),IA(2),IRN),(IA(3),IT),(IA(4),IP),(IA(5),	E4INR007		3ICAS),(AA(213),IE),(AA(214),NB),(AA(215),MB)	E4INR038
		1PRS),(IA(6),IYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),IMX),(IA(10),F4INR009	E4INR008		4,IAA(216),IROT),(AA(217),RST)	E4INR039
		2IM),(IA(11),IB),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),F4INR010	E4INR009		EQUIVALENCE(AA(220),BIR),(AA(221),SIR),(AA(226),DIR),(AA(235),SR)E4INR040	F4INR040
		3IMF),(IA(16),IARE),(IA(17),NII),(IA(18),M),(IA(19),IY),(IA(20),F4INR011	E4INR010		1,IAA(241),XN),(AA(244),XF),(AA(247),ON),(AA(251),OF),(AA(259),RES)E4INR041	F4INR041
		4ISTR),(IA(21),IEL),(IA(22),ITEM),(IA(23),ITIC),(IA(24),IMET),	E4INR011		2,(AA(265),RED),(AA(271),BAS),(AA(274),ICLA),(AA(278),NBAN)	E4INR042
		5(IA(25),ISUM),(IA(26),INNI),(IA(27),IMS),(IA(28),IDSI),(IA(29),F4INR012	E4INR012		3,IAA(292),NU),(AA(295),NES)	E4INR043
		6IDRD),(IA(30),IDRDI),(IA(31),ACEL),(IA(32),J),(IA(33),J2),	E4INR013		DIMENSION NEL(20,17),MAC(4,4,20),IWS(90),DD(6,6),A(90,7),B(8,8),	E4INR044
		7(IA(34),J3),(IA(35),J4),(IA(36),J5),(IA(37),J6),(IA(38),J7),(IA(39),F4INR015	E4INR014		1C(8,2),FF(1),MSET(100),MSET(100),W(3,3)	F4INR045
		8),J8),(IA(39),JTY),(IA(40),IBB),(IA(41),IBD),(IA(42),IID),(IA(43),F4INR016	E4INR015		EQUIVALENCE(AA(14000),FF),INUI(1),JP1),(NU(2),JM),(NU(3),JS1)	F4INR046
		9(IA(44),IDJ),(IA(45),IDY),(IA(46),IDZ),(IA(47),IIS),(IA(48),IIP),	E4INR016		EQUIVALENCE(FF(1),NEL),(FF(341),MAC),(FF(661),IWS),(FF(751),DD),	F4INR047
		EQUIVALENCE(IA(66),ICAR),(IA(67),ICX),(IA(68),ICY),(IA(69),	E4INR017		1(FF(787),A),(FF(1417),B),(FF(1481),C),(FF(1497),MSET),(FF(1597),	E4INR048
		1(IA(70),ICF),(IA(71),ICX),(IA(72),IY),(IA(73),IZ),	E4INR018		2MSET),(FF(1697),W)	E4INR049
		2(IA(74),IIC),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS)	E4INR019		DIMENSION CIR(3)	E4INR050
		3,(IA(78),IGEM),(IA(79),IERR),(AA(80),TE),(AA(81),DT),(AA(82),DC),	E4INR020		CIR(1)=0	F4INR051
		4(IA(83),AL1),(IA(84),AL2),(IA(85),AL3),(IA(86),O21),(AA(107),P),	E4INR021		CIR(2)=0	E4INR052
		5(IA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),	E4INR022		OO 1 I=1,NB	E4INR053
		6(IA(181),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM),	F4INR023		K=NET(I)	F4INR054
		7,(AA(42),INP),(AA(43),IPBG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IUE4INR025	E4INR024		CALL FINDIK,XF)	F4INR055
		8),(AA(47),G1),(AA(48),G2),(AA(49),G3)	E4INR025		CIR(I)=CIR(I)+XF(I)-XN(I)	F4INR056
		EQUIVALENCE(IA(349),NTIC),(IA(348),ISDIT),(IA(347),ISDY),(IA(346)	E4INR026		CIR(I)=CIR(I)+XF(2)-XN(2)	F4INR057
		1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)	E4INR027	1	CIR(I)=CIR(I)+XF(3)-XN(3)	F4INR058
		2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)	E4INR028		RETURN	F4INR059
		3,(IA(337),JMMZ),(IA(336),JMF),(IA(335),IAT5),(IA(334),IDZ)	E4INR029		END	F4INR060
			E4INR030			F4INR061

Table VII-67. Source program listing of subroutine INLZ (Link 4)

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* LABEL
CE+INZ SUBROUTINE INLZ E4INZ000
C INITIALIZES SCALARS, VECTORS AND MATRICES AT A NODE E4INZ001
C TO INITIALIZE ICON,ANGLE,BAS,DIN,N,IRROT,BST,IERR,TE,DT,DF,AND NFS E4INZ002
DIMENSION I(41),AA(1),S(1),N(8),D2(21),D3(2,3),E2(3,3) E4INZ003
1,P(24),UV(24),X(8),Y(8),Z(8),XDI(7),YDI(7),ZD(7),GL(1) E4INZ004
COMMON IA,AA E4INZ005
EQUIVALENCE IA,AA,(D2,D3),(D2(10),F22),(D2(19),F),(D2(20),G) E4INZ006
EQUIVALENCE I(41),IN,(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), E4INZ008
1PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10), E4INZ009
21HI),(IA(11),IR),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15), E4INZ010
3INF),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27), E4INZ011
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIG),(IA(31),IMET), E4INZ012
5I(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IOS),(IA(37), E4INZ013
6IORD),(IA(38),IORD1),(IA(39),JCEL),(IA(50),J1),(IA(51),J2), E4INZ014
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57), E4INZ015
8),J8),(IA(58),JTY),(IA(59),IBB),(IA(60),IRBI),(IA(61),IID),(IA(62), E4INZ016
9IA),(IA(63),IDI),(IA(64),IDY),(IA(65),ITE),(IA(41),IAP) E4INZ017
EQUIVALENCE I(466),ICAR,(IA(67),ICIX),(IA(68),ICLY),(IA(69), E4INZ018
IICIZ),(IA(70),ICFI),(IA(71),IX),(IA(72),IYY),(IA(73),IZZ), E4INZ019
2(IA(74),IIC),(IA(75),IDEP),(IA(76),ISJ),(IA(77),IIS) E4INZ020
3,(IA(78),IGEM),(IA(79),IERR),(AA(80),TE),(IA(81),DT),(AA(82),DG), E4INZ021
4(AA(83),AL1),(IA(84),AL2),(AA(85),AL3),(IA(86),D21),(AA(107),P), E4INZ022
5(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), E4INZ023
6(AA(186),YI),(AA(193),ZD),(AA(351),S),(AA(40),ZGM) E4INZ024
7,(AA(42),INP),(AA(43),IPBG),(AA(44),IPFN),(AA(45),COMS),IAA(46),IUE E4INZ025
8),(AA(47),GI),(AA(48),G2),(AA(49),G3) E4INZ026
EQUIVALENCE I(1349),RTIC,(IA(348),ISOT),(IA(347),ISPY),(IA(346) E4INZ027
1,ISDZ),(IA(345),J9),(IA(344),J30),(IA(343),JPRS),(IA(342),ISDY) E4INZ028
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMX),(IA(338),JMY) E4INZ029
3,(IA(337),JMMZ),(IA(336),JMF),(IA(335),ITAS),(IA(334),IDZ) E4INZ030
4,(IA(333),JPK),(IA(332),OGY),(IA(331),OGZ),(AA(330),PRES) E4INZ031
5,(IA(329),IPRI) E4INZ032
DIMENSION BJR(3),SJR(3),DIN(3,3),SR(6),XN(3),YF(3),DN(6),DF(6), E4INZ033
1RES(6),RED(6),BAS(3),ICLAS(4),NBN(10),NUS(3),NES(3) E4INZ034
EQUIVALENCE I(41200),IDNE,(AA(201),ICN),(AA(202),LN),(AA(203),ASTE) E4INZ035
1),(AA(204),INRDN),(AA(205),ARE),(AA(206),ICLA),(AA(207),IMEL), E4INZ036
2(AA(208),IM),(AA(209),IC),(AA(210),ICOM),(AA(211),ANGLE),(AA(212), E4INZ037
3ICAS),(AA(213),IS),(AA(214),NB),(AA(215),MH) E4INZ038
4,(AA(216),IRDT),(AA(217),BST) E4INZ039
EQUIVALENCE (AA(220),BIR),(AA(223),SJR),(AA(226),DIN),(AA(235),SR) E4INZ040
1,(AA(241),XN),(AA(244),YF),(AA(247),DN),(AA(253),DF),(AA(259),RES) E4INZ041
2,(AA(265),RED),(AA(271),BAS),(AA(274),ICLAS),(AA(278),NBN) E4INZ042
3,(AA(292),NUS),(AA(295),NES) E4INZ043
DIMENSION MEL(20,17),MAC(4,4,20),ING(90),DD(A,6),A(90,7),B(8,8), E4INZ044
1C(8,2),FF(1),MSET(100),MSET(100),W(3,3) E4INZ045
EQUIVALENCE (AA(14000),FF),INU(1),JP1),(MU(2),JM1),INUI(3),JS1) E4INZ046
EQUIVALENCE (FF(1),NEL),(FF(341),MAC),(FF(681),ING),(FF(751),DD), E4INZ047
1,FF(787),A),(FF(1417),B),(FF(1481),C),(FF(1497),MSET),(FF(1547), E4INZ048
2MSET),(FF(1697),W) E4INZ049
EQUIVALENCE (NES(1),ICOL),INES(2),IRIG),INES(3),IDR1 E4INZ050
C SET INDICATORS TO LOCAL=OVERALL E4INZ051
IROT=0 E4INZ052
BST=7H A E4INZ053
C GENERATE DIN AND W TRANSFORMATION MATRICES FOR LOCAL=OVERALL E4INZ054
DO I=1,3 E4INZ055
IF (I-J)=2,3,2 E4INZ057
DIN(I,J)=1. E4INZ058
W(I,J)=1. E4INZ059
GO TO 1 E4INZ060
2 DIN(I,J)=0. E4INZ061
W(I,J)=0. E4INZ062
1 CONTINUE E4INZ063
C COMPUTE AVERAGE THICKNESS,TEMP,INCREASE,TEMP GRADIENT E4INZ064
TE=0. E4INZ065
DT=0. E4INZ066
DG=0. E4INZ067
IM=1 E4INZ068
IC=1 E4INZ069
IE=MAC(1M,IC,1)+1 E4INZ070
DO 10 IL=2,IE E4INZ071
K=MAC(1M,IC,IL) E4INZ072
K1=NEL(K,6) E4INZ073
IF (K1) 11,11,12 E4INZ074
12 K1=ITE+K1 E4INZ075
TE=TE+AA(K1) E4INZ076
K1=NEL(K,9) E4INZ077
IF (K1) 13,13,14 E4INZ078
14 K1=IDT+K1 E4INZ079
DT=DT+AA(K1) E4INZ080
13 K1=NEL(K,7) E4INZ081
IF (K1) 10,10,15 E4INZ082
15 K1=IDZ+K1 E4INZ083
DG=DG+AA(K1) E4INZ084
10 CONTINUE E4INZ085
CC=IE-1 E4INZ086
IE=IE/CC E4INZ087
DG=DG/CC E4INZ088
DT=DT/CC E4INZ089
C DETERMINE NECESSARY PARAMETERS ACCORDING TO CLASS E4INZ090
IRIG=3 E4INZ091
IDR=0 E4INZ092
ICAS=ICAS E4INZ093
GO TO (69,62,69,64,65,66,69,68),ICAS E4INZ094
62 IDR=1 E4INZ095
GO TO 69 E4INZ096
64 ICOL=6 E4INZ097
GO TO 69 E4INZ098
65 ICOL=1 E4INZ099
GO TO 69 E4INZ100
66 ICOL=1 E4INZ101
IRIG=2 E4INZ102
GO TO 69 E4INZ103
68 IRIG=2 E4INZ104
C INITIALIZE THE OTHER CONSTANTS E4INZ105
ANGLE=0. E4INZ106
ICON=0 E4INZ108
IERR=0 E4INZ109
C GENERATE BAS VECTOR E4INZ110
IE=MAC(1M,IC,2) E4INZ111
K=NEL(IE,10) E4INZ112
CALL FNDX(K,X) E4INZ113
K=NEL(IE,11) E4INZ114
CALL FNDX(K,Y) E4INZ115
BAS(1)=Y11-X(1) E4INZ116
BAS(2)=Y12-X(2) E4INZ117
BAS(3)=Y13-X(3) E4INZ118
CC=1 E4INZ119
CALL UNIT(BAS,CC) E4INZ120
IF (INP-2) 20,21,21 E4INZ121
21 WRITE OUTPUT TAPE 6,22,TE,DT,DG,BAS(1),BAS(2),BAS(3) E4INZ122
22 FORMAT 120X,5HTHICK,2X,F11.4,3X,1HTEMP,INCRSF,2X,F11.4,3X,10HTEMP E4INZ123
1,IRROT,2X,E11.4,3X,3HRAS,2X,3F7.3 E4INZ124
20 RETURN E4INZ125
END E4INZ126

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Table VII-70. Source program listing of subroutine MDIN (Link 4)

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A LABEL
CE4MDN F4MND000
SUBROUTINE MDIN F4MND001
C ORIENTS LOCAL AXES PROPERLY AT A BOUNDARY NODE IN SHELLS F4MND002
C TO ROTATE LOCAL AXES TO THAT KS1 IS IN 71A-BIR PLANE F4MND003
DIMENSION I(11),AA(11),S(1),N(8),D21(21),D33(3,3),E21(3,3) F4MND004
I(1)=24,UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1) F4MND005
COMMON IA,AA F4MND006
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),F22), (D21(19),E), (D21(20),G) F4MND007
EQUIVALENCE (IA(1),IN), (IA(2),IM), (IA(3),IF), (IA(4),IP), (IA(5), F4MND008
1IPRS), (IA(6),ITYP), (IA(7),INAT), (IA(8),IDEG), (IA(9),IWA), (IA(10), F4MND009
2IHS), (IA(11),IR), (IA(12),IMK), (IA(13),IMW), (IA(14),IMZ), (IA(15), F4MND010
3IMF), (IA(16),IARE), (IA(17),NI), (IA(25),NI), (IA(26),IY), (IA(27), F4MND011
4ISTR), (IA(28),IFLT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMET), F4MND012
5(IA(32),ISUM), (IA(33),INO), (IA(34),IMS), (IA(36),IDS), (IA(37), F4MND013
6IORD), (IA(38),IORD1), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F4MND014
7(IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57), F4MND015
8J8), (IA(58),JTY), (IA(59),I88), (IA(60),I80), (IA(61),I8), (IA(62), F4MND016
9IAT), (IA(63),ID), (IA(64),IDY), (IA(65),ITE), (IA(66),IAP), F4MND017
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIX), (IA(69), F4MND018
1ICIZ), (IA(70),ICFI), (IA(71),ICX), (IA(72),IYY), (IA(73),IZZ), F4MND019
2(IA(74),IIC), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS) F4MND020
3, (IA(78),IGEM), (IA(79),IFRK), (AA(80),TF), (AA(81),DT), (AA(82),DG), F4MND021
4(AA(83),ALL), (AA(84),AL2), (AA(85),AL3), (AA(86),D2), (AA(87),P), F4MND022
5(AA(88),X), (AA(89),Y), (AA(90),Z), (AA(91),X), (AA(92),Y), (AA(93),Z), F4MND023
6(AA(94),D), (AA(95),Z), (AA(96),S), (AA(97),S), (AA(98),Z), F4MND024
7, (AA(99),IPR), (AA(100),IPR), (AA(101),IPR), (AA(102),IPR), (AA(103),IPR), F4MND025
8, (AA(104),G1), (AA(105),G2), (AA(106),G3) F4MND026
EQUIVALENCE (IA(349),NIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346), F4MND027
1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY) F4MND028
2, (IA(341),JSDZ), (IA(340),JARE), (IA(339),JMK), (IA(338),JPMY) F4MND029
3, (IA(337),JMK), (IA(336),JMP), (IA(335),IAS), (IA(334),I02) F4MND030
4, (IA(333),JPR), (AA(332),NGV), (AA(331),DG2), (AA(330),PREF) F4MND031
5, (IA(329),IPR) F4MND032
DIMENSION BIR(3),SIR(3),DINI(3,3),SKI(1),XN(2),XF(3),ON(6),OF(6), F4MND033
1RES(6),RED(6),BAS(3),ICLAS(4),NBAN(10),NH(3),NFS(3) F4MND034
EQUIVALENCE (AA(200),I0NE), (AA(201),ICN), (AA(202),IM), (AA(203),ASTR) F4MND035
1), (AA(204),ININ), (AA(205),ARE), (AA(206),ICL), (AA(207),IMEL), F4MND036
2(AA(208),IM), (AA(209),IC), (AA(210),ICOM), (AA(211),ANGL1), (AA(212), F4MND037
3ICAS), (AA(213),IE), (AA(214),NH), (AA(215),MR) F4MND038
4, (AA(216),IROT), (AA(217),BST) F4MND039
EQUIVALENCE (AA(220),BIR), (AA(223),SIR), (AA(226),DIN), (AA(235),SR) F4MND040
1, (AA(241),XN), (AA(244),XF), (AA(247),ON), (AA(253),OF), (AA(259),RES) F4MND041
2, (AA(265),RED), (AA(271),BAS), (AA(274),ICLAS), (AA(278),NBAN) F4MND042
3, (AA(292),NH), (AA(295),NFS) F4MND043
DIMENSION MEL(20),MAC(4,4,20),IMG(90),DD(6,6),A(90,7),B(8,8), F4MND044
1C(8,2),FF(1),NSET(100),MSET(100),W(3,3) F4MND045
EQUIVALENCE (AA(14000),FF), (NU(1),JP1), (NU(2),JM1), (NU(3),JS1) F4MND046
EQUIVALENCE (FF(1),NEL), (FF(341),MAC), (FF(661),IMG), (FF(751),D0), F4MND047
1(FF(787),A), (FF(1417),B), (FF(1481),C), (FF(1497),NSET), (FF(1597), F4MND048
2MSET), (FF(1697),N) F4MND049
DIMENSION XI(3),ETA(3),ZTA(3) F4MND050
EQUIVALENCE (DIN(1),XI1), (DINI(4),ETA), (DINI(7),ZTA) F4MND051
C SET INDICATORS TO LOCAL IS DIFFERENT THAN OVERALL F4MND052
IROT=1 F4MND053
BST=2H** F4MND054
C SEE IF A SOLID F4MND055
IF (ICAS=4) 33,31,33 F4MND056
C SOLID CASE. FIND THE AXIS WHICH MAKES LARGEST ANGLE WITH BIR F4MND057
31 IF (ABS(FBIR(1))-ABS(FBIR(2))) 315,315,316 F4MND058
315 IF (ABS(FBIR(1))-ABS(FBIR(3))) 311,311,313 F4MND059
316 IF (ABS(FBIR(2))-ABS(FBIR(3))) 312,317,313 F4MND060
311 CALL VECT(ETA,BIR,XII) F4MND061
GO TO 35 F4MND062
312 CALL VECT(SIR,BIR,ETA) F4MND063
ETA(1)=SIR(1) F4MND064
ETA(2)=SIR(2) F4MND065
ETA(3)=SIR(3) F4MND066
GO TO 35 F4MND067
313 CALL VECT(ETA,BIR,ZTA) F4MND068
CC=1 F4MND069
CALL UNIT(ETA,CC) F4MND070
CALL VECT(ZTA,BIR,ETA) F4MND071
CALL UNIT(ZTA,CC) F4MND072
CALL VECT(XII,ETA,ZTA) F4MND073
CALL UNIT(XII,CC) F4MND074
GO TO 22 F4MND075
C MIN-SOLID CASE F4MND076
33 CC=1 F4MND077
CALL VECT(ETA,ZTA,BIR) F4MND078
CALL UNIT(ETA,CC) F4MND079
CALL VECT(XII,ETA,ZTA) F4MND080
CALL UNIT(XII,CC) F4MND081
22 RETURN F4MND082
END F4MND083

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Table VII-71. Source program listing of subroutine META (Link 4)

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CE4MET          SUBROUTINE META                      E4MET000
C              TO GENERATE MATERIAL MATRIX DD IN THE ORDER OF 1,2,12,3,13,23  E4MET001
C              IN LOCAL COORDINATE SYSTEM                      E4MET002
C              DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),E22(3,3)  E4MET003
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1)  E4MET004
COMMON IA,AA  E4MET005
EQUIVALENCE(IA,AA1,(D21,D33),(D21(10),E22),(D21(19),E1,(D21(20),G)E4MET007
EQUIVALENCE(IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5),  E4MET008
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),E4MET009
2IHI),(IA(11),IB),(IA(12),IMMS),(IA(13),IMMY),(IA(14),IMW),(IA(15),E4MET010
3IMFI),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),E4MET011
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),IIC),(IA(31),IMET),  E4MET012
5(IA(32),SUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37),  E4MET013
6IDRD),(IA(38),JORDI),(IA(39),ACEL),(IA(50),JI),(IA(51),J2),  E4MET014
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E4MET015
8(J1),J2),(IA(58),JTY),(IA(59),IBB),(IA(60),IBO),(IA(61),IBD),(IA(62),E4MET016
9(IA(63),IDT),(IA(64),IUY),(IA(65),IF1),(IA(61),ITAP)  E4MET017
EQUIVALENCE(IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69),  E4MET018
1ICIZ),(IA(70),ICF),(IA(71),ICX),(IA(72),IY),(IA(73),IZ),  E4MET019
2(IA(74),IIC),(IA(75),IDEF),(IA(76),IST),(IA(77),IIS)  E4MET020
3,IA(78),IGEM),(IA(79),IERR),(AA(80),TE),(AA(81),DT),(AA(82),BG),  E4MET021
4(AA(83),AL),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P),  E4MET022
5(AA(131),UV),(AA(135),X),(AA(136),Y),(AA(171),Z),(AA(179),XD),  E4MET023
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZGEM)  E4MET024
7,AA(421),IMP),(AA(431),IPBG),(AA(441),IPEN),(AA(451),CONS),(AA(461),IIE4MET025
8,(AA(471),GL),(AA(481),G2),(AA(491),G3)  E4MET026
EQUIVALENCE(IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(1346)  E4MET027
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)  E4MET028
2,IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)  E4MET029
3,IA(337),JMMZ),(IA(336),JMF1),(IA(335),JMF2),(IA(334),JMF3)  E4MET030
4,IA(333),JPR),(IA(332),DGY),(IA(331),OGZ),(IA(330),PRES)  E4MET031
5,IA(329),IPR)  E4MET032
DIMENSION BIR(3),SIR(3),DIN(3,3),SR(6),XN(3),XF(3),DN(6),DF(6),  E4MET033
IRES(6),RED(6),BAS(3),ICLAS(4),NBRAN(10),NI(3),NES(3)  E4MET034
EQUIVALENCE(AA(200),IDNE),(AA(201),ICN),(AA(202),LMI),(AA(203),ASTE4MET035
1),(AA(204),JNHUN),(AA(205),ARE),(AA(206),ICLA),(AA(207),IMEL),  E4MET036
2(AA(208),IM),(AA(209),IC),(AA(210),ICDN),(AA(211),ANGLE),(AA(212),E4MET037
3ICAS),(AA(213),IE),(AA(214),NB),(AA(215),NR)  E4MET038
4,(AA(216),IRDT),(AA(217),BS)  E4MET039
EQUIVALENCE(IA(1220),BIR),(AA(223),SIR),(AA(226),DIN),(AA(235),SR)E4MET040
1,(AA(241),XN),(AA(244),XF),(AA(247),DN),(AA(253),DF),(AA(259),RES)E4MET041
2,(AA(265),RED),(AA(271),BAS),(AA(274),ICLAS),(AA(278),NBRAN)  E4MET042
3,(AA(292),NI),(AA(295),NES)  E4MET043
DIMENSION NEL(20,17),MAC(4,4,20),IWC(90),DD(6,6),A(90,7),B(8,8),  E4MET044
IC(8,2),FF(1),NSET(100),MSE(100),M(3)  E4MET045
EQUIVALENCE(IA(14000),FF),(NU(1),JP1),(NU(2),JM1),(NU(3),JS1)  E4MET046
EQUIVALENCE(FF(1),NEL),(FF(341),MAC),(FF(661),IWC),(FF(751),DD),  E4MET047
1(FF(787),A),(FF(1417),B),(FF(1481),C),(FF(1497),NSET),(FF(1597),  E4MET048
2MSET),(FF(1697),M)  E4MET049
C              INITIALIZE DD ALPHA CONSTANTS                    E4MET050
DD IO J=1,6  E4MET051
DD IO J=1,6  E4MET052
10 DD(I,J)=0,  E4MET053
AL=0,  E4MET054
AL2=0,  E4MET055
AL3=0,  E4MET056
C              INQUIRE THE TYPE AND GENERATE DD IN THE ORDER OF 1,2,3,12,13,23  E4MET057
IF (ITYPE=1) 20,30,40  E4MET058
C              ISOTROPIC MATERIAL                              E4MET059
20 IJD=IJD+(IMET-1)*2  E4MET060
E=AA(IJD+1)  E4MET061
G=AA(IJD+2)  E4MET062
IIA=IA+IMET  E4MET063
AL2=ALL  E4MET064
AL3=ALL  E4MET065
PUE=E(2,9G)-1  E4MET066
IF (ISTR=1) 209,210,209  E4MET067
209 IF (ICAS=3) 208,210,208  E4MET068
E4MET069
208 IF (ICAS=4) 207,210,207  E4MET070
207 E1=F/1,-PUEPUI  E4MET071
E2=E1*PUI  E4MET072
K=2  E4MET073
GO TO 220  E4MET074
K=3  E4MET075
E1=E*(1,-PUI)/(1,-2*PUI)*(1,+PUI)  E4MET076
E2=E*PUI/(1,-2*PUI)*(1,+PUI)  E4MET077
220 DO 201 J=1,K  E4MET078
IF (I-J) 203,202,203  E4MET079
202 DD(I,J)=E1  E4MET080
DD(I+3,J+3)=G  E4MET081
GO TO 201  E4MET082
203 DD(I,J)=E2  E4MET083
201 CONTINUE  E4MET084
IF (K=2) 60,204,60  E4MET085
DD(6,6)=G  E4MET086
204 DD(1,6)=G  E4MET087
C              ORTHOTROPIC MATERIAL                          E4MET088
30 IIA=IIA+(IMET-1)*2  E4MET089
AL2=AA(IIA+1)  E4MET090
AL3=AA(IIA+2)  E4MET091
IJD=IJD+(IMET-1)*9  E4MET092
DD(I,J)=AA(IJD+1)  E4MET093
DD(I+2)=AA(IJD+2)  E4MET094
DD(I+4)=AA(IJD+3)  E4MET095
DD(2+2)=AA(IJD+4)  E4MET096
UD(2+4)=AA(IJD+5)  E4MET097
DD(4+4)=AA(IJD+6)  E4MET098
DD(1+5)=AA(IJD+7)  E4MET099
DD(5+6)=AA(IJD+8)  E4MET100
DD(6+6)=AA(IJD+9)  E4MET101
IF (ISTR=1) 60,301,60  E4MET102
301 DD(1,3)=DD(1,2)  E4MET103
DD(2,3)=DD(1,2)  E4MET104
GO TO 60  E4MET105
C              GENERAL HOOKIAN MATERIAL                      E4MET106
40 IIA=IIA+(IMET-1)*3  E4MET107
AL1=AA(IIA+1)  E4MET108
AL2=AA(IIA+2)  E4MET109
AL3=AA(IIA+3)  E4MET110
IJD=IJD+(IMET-1)*21  E4MET111
DO 401 J=1,6  E4MET112
DO 401 J=1,6  E4MET113
IJD=IJD+1  E4MET114
401 DD(I,J)=AA(IJD)  E4MET115
C              OBTAIN THE SYMMETRIC HALF                    E4MET116
60 DD 61 J=1,6  E4MET117
DD 61 J=1,6  E4MET118
DD(I,J)=DD(I,J)  E4MET119
C              ROTATE MATERIAL AXES IF NECESSARY SO THAT THEY COINCIDE WITH DIN  E4MET120
IF (IRDT) 71,70,71  E4MET121
CALL ROTA  E4MET122
C              SWITCH COLUMNS AND ROWS 3 AND 4 TO GET THE ORDER 1,2,12,3,13,23  E4MET123
70 DD 62 I=1,6  E4MET124
E1=DD(4,I)  E4MET125
DD(4,I)=DD(3,I)  E4MET126
DD(3,I)=E1  E4MET127
DD 63 I=1,6  E4MET128
E1=DD(1,4)  E4MET129
DD(1,4)=DD(1,3)  E4MET130
DD(1,3)=E1  E4MET131
63 IF (INP=2) 100,91,91  E4MET132
91 WRITE OUTPUT TAPF 6,92,ICN,BST,IMET,((DD(I,J),J=1,6),I=1,6)  E4MET133
92 FORMAT (15,10X,A2,3X,57H MATERIAL MATRIX (IN 1,2,12,3,13,23 ORDER)  E4MET134
1 FOLLOWS, MAT,=,13/(20X,6E14.5))  E4MET135
100 RETURN  E4MET136
END  E4MET137
E4MET138

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Table VII-73. Source program listing of subroutine REVO (Link 4)

```

* LABEL
CE4REV          E4RFV000          350 J4B=J4+IJ-11*IT          E4RFV004
SUBROUTINE REVO E4RFV001          J4C=J4+(7-JI4)IT          E4RFV005
FINDS LOCAL AXES BY BEST FIT & 4TH ORDER POLYNOMIAL IN SHELLS OF NYV4REV002          LDOE=0          E4RFV006
TO FIND DIRECTION FOR SHELLS OF REVOLUTION BY 4TH ORDER POLYNOMIAL FIT E4RFV003          DO 355 K=1,IT          E4RFV007
DIMENSION I(41),AA(1),S(1),N(8),D21(2),D33(3),F22(3,3) E4RFV004          L1=J4+K          E4RFV008
1, F(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1) E4RFV005          L2=J4+K          E4RFV009
COMMON I,AA,         E4RFV006          L3=J1+K          E4RFV010
EQUIVALENCE (IA,AA),I(21),O(3),I(21),I(1),F22(1),F1, I(21),O(21),G E4RFV007          IF (I(11)-I(17)) 358,356,358
EQUIVALENCE (IA(1),IN),IA(21),IBN),IA(31),IT,IA(14),IP,IA(5), E4RFV008          358 IF (I(13)-I(14)) 355,356,355
1IPR5),IA(16),ITYPE1,IA(7),IPATI,IA(8),IDFG,IA(19),IMX),IA(10),E4RFV009          356 IF (I(11)-MOD1) 355,357,355
2IH1,IA(11),IR,IA(12),IMMX),IA(13),IMNY),IA(14),IMM2),IA(15),E4RFV010          GO TO 359
3IMF1),IA(11),JARE),IA(17),N(11),IA(25),M),IA(26),ITY),IA(127),E4RFV011          359 CONTINUE
4FSTR),IA(12),IELT),IA(29),ITEM),IA(30),ITIC,IA(31),IMET), E4RFV012          359 IF (LDOE) 360,360,370
5IA(132),ISUM),IA(133),IND),IA(34),INS),IA(36),IDS),IA(37), E4RFV013          360 IF (L-1) 365,390,365
6IGRD),IA(38),IGRD1),IA(39),ACEL),IA(50),J1,IA(51),J2), E4RFV014          365 NB=K-KL+1
7IA(52),J3),IA(53),J4),IA(54),J5),IA(55),J6),IA(56),J7),IA(57),E4RFV015          DO 366 L=1,NB
8JUB1,IA(58),JTY),IA(59),IBB),IA(60),IBO),IA(61),ID1,IA(62),E4RFV016          IF (J-1) 362,362,361
9IA1,IA(63),IDT),IA(64),IDY),IA(65),ITF),IA(61),IAP) E4RFV017          L1=L
EQUIVALENCE (IA(66),ICMR),IA(67),ICIX),IA(68),ICIV),IA(69), E4RFV018          L2=KL+L-1
1ICIZ),IA(70),ICFI),IA(71),IXX),IA(72),IYY),IA(73),IZZ), E4RFV019          GO TO 366
2IA(74),IIL),IA(75),IDEF),IA(76),ISJ),IA(177),IIS) E4RFV020          L1=0-L
3IA(178),IGEM),IA(79),IERR),IA(80),TF1,AA(81),DT),AA(82),DR), E4RFV021          L2=KR+L
4AA(83),AL1),AA(84),AL2),AA(85),AL3),AA(86),O21),AA(107),P), E4RFV022          366 NSET(I)=NSET(L2)
5AA(131),UV),AA(135),X),AA(163),Y),AA(171),Z),AA(179),XD), E4RFV023          IF (J-1) 364,364,363
6AA(186),YD),AA(193),ZD),AA(185),S),AA(160),ZGEM) E4RFV024          KL=1
7AA(42),INP),AA(43),IPB),AA(44),IPEN),AA(45),CONS),AA(46),IUE4RFV025          KR=NB
8),AA(47),G),AA(48),G2),AA(49),G3) E4RFV026          LL=1
EQUIVALENCE (IA(349),MTC),IA(349),ISDT),IA(347),ISDY),IA(346) E4RFV027          GO TO 390
1,ISD2),IA(345),J9),IA(344),J10),IA(343),JPK5),IA(342),JSD1) E4RFV028          KR=5
2,IA(341),JSD2),IA(340),JARE),IA(339),JMX),IA(338),JMMY) E4RFV029          KL=6-NB
3,IA(337),JMM2),IA(336),JMF1),IA(335),IAS),IA(334),ID2) E4RFV030          GO TO 390
4,IA(333),IPR),AA(332),OCY),AA(331),OG2),AA(330),PKES) E4RFV031          IF (J-1) 375,375,380
5IA(329),IPR) E4RFV032          KR=KR+L
DIMENSION DIR(3),SIR(3),DIN(3,3),SR(6),XN(3),XF(3),ONI(6),OF(6), E4RFV033          NSET(KR)=LUDE
1RES(6),RED(6),BAS(3),ICLAS(4),NBSAN(10),NU(3),NES(3) E4RFV034          GO TO 390
EQUIVALENCE (AA(200),ONE),AA(201),ICN),AA(202),LM),AA(203),AST E4RFV035          KL=KL-1
1),AA(204),INBN),AA(205),ARE),AA(206),ICLA),AA(207),IMFL), E4RFV036          NSET(KL)=LDOF
2AA(208),IM),AA(209),IC),AA(210),ICOM),AA(211),ANGLE),AA(212), E4RFV037          CONTINUE
3ICAS),AA(213),IF),AA(214),NB),AA(215),MH) E4RFV038          400 NB=KR
4IA(216),IROT),AA(217),B5T) E4RFV039          IF (INP-2) 450,440,440
EQUIVALENCE (IA(220),RIR),IA(223),SIR),AA(226),DIN),AA(235),SR) E4RFV040          WRITE OUTPUT TAPE 6,441,IE,NB,(NSET(I),I)=1,NB)
1AA(241),XN),AA(244),XF),AA(247),OM),AA(253),OF),AA(259),RES) E4RFV041          FORMAT (20X,55HNODE SET FOR FOURTH (OR LESS) DEGREE POLYNOMIAL FOL
2AA(265),RED),AA(271),BAS),AA(274),ICLAS),AA(278),NBSAN) E4RFV042          LDOE,2110/(20X,2015))
3AA(297),NU),AA(295),NES) E4RFV043          420 IPONN=NB
DIMENSION NEL(20,17),MAC(6,4,20),IWC(90),DO(6,6),A(90,7),R(8,R), E4RFV044          C SET THE EQUATIONS FOR THE COEFFICIENTS
1C(8,2),JF(1),NSET(100),MSET(100),W(2,3) E4RFV045          14 IPP=IPONN-1
EQUIVALENCE (AA(1400),FF),NU(1),JP1),NU(2),JM),NU(3),JS1) E4RFV046          DO 15 I=1,IPONN
EQUIVALENCE (FF(11),NEL),FF(341),MAC),FF(661),IWC),FF(175),DD), E4RFV047          K=NSET(I)
1FF(178),A),FF(147),B),FF(148),C),FF(149),NSET),FF(1597), E4RFV048          CALL UNIT (K,RED)
2NSET),FF(1697),W) E4RFV049          IJ=16,JP1,IPP
DIMENSION XII(3),ETA(3),ZTA(3) E4RFV050          L=IPONN-J
EQUIVALENCE (DIN(1),XII),DIN(4),ETA),DIN(7),ZTA) E4RFV051          B(I,J)=RED(I)*L
1JW=J E4RFV052          C(I,I)=RED(I)
IC=IC E4RFV053          C
OBTAIN THE CRUDE DIRECTION OF XII AND SET THE DIRECTION OF ETA
1J7M)=MET+1700 E4RFV054          RED(1)=B(IPONN,IPONN-1)-B(1,IPONN-1)
1J8M)=MET+1800 E4RFV055          RED(2)=C(IPONN,1)-C(1,1)
LL=0 E4RFV056          RED(3)=0.
IE=MAC(1M,IC,1) E4RFV057          ETA(1)=0.
IF (IE=1) 100,100,200 E4RFV058          ETA(2)=0.
IEL=MAC(1M,IC,2) E4RFV059          ETA(3)=-1.
100 IF (NEL(IELT,10)-ICN) 102,101,102 E4RFV060          D=1.
101 KL=1 E4RFV061          C
FIND THE COEFFICIENTS
KR=2 E4RFV062          CALL INV (8,IPONN,C,1,DET)
LL=1 E4RFV063          IF (DET) 17,18,17
NSET(KL)=ICN E4RFV064          18 WRITE OUTPUT TAPE 6,181,ICN
NSET(KR)=NEL(IELT,11) E4RFV065          181 FORMAT (15,13X,89HNOT ENOUGH INFORMATION FOR MIDDLE SURFACE NORMAL
GO TO 300 E4RFV066          1, APPROXIMATE XII AND ZTA VALUES ARE USED)
102 KL=4 E4RFV068          CALL UNIT (RED=0)
KR=5 E4RFV069          XII(1)=RED(1)
NSET(KL)=NEL(IELT,10) E4RFV070          XII(2)=RED(2)
NSET(KR)=ICN E4RFV071          XII(3)=RED(3)
GO TO 300 E4RFV072          CALL VECT (ZTA,XII,ETA)
I=2 E4RFV073          CALL UNIT (ZTA,0)
200 IEL=MAC(1M,IC,1) E4RFV074          GO TO 25
IF (NEL(IELT,10)-ICN) 202,201,202 E4RFV075          C
COMPUTE DIRECTION COSINES
1/ IF (IE=2) 171,171,172 E4RFV076          1/ IF (IE=2) 171,171,172
2/ IF (NEL(IELT,10)-ICN) 202,201,202 E4RFV077          2/ IF (NEL(IELT,10)-ICN) 202,201,202
201 NSET(3)=ICN E4RFV078          171 ZTA(1)=0.
NSET(4)=NEL(IELT,11) E4RFV079          DO 19 I=1,IPP
GO TO 210 E4RFV080          K=IPONN-I
I=3 E4RFV081          CI=K
210 IF (I-3) 215,216,216 E4RFV082          19 ZTA(1)=ZTA(1)+C*I(1,1)*XN(I)**(K-1)
KL=2 E4RFV083          ZTA(2)=0.
KR=4 E4RFV084          ZTA(3)=0.
DO 300 I=1,3 E4RFV085          CALL VECT (XII,ETA,ZTA)
IF (KL=1) 301,301,302 E4RFV086          IF (SCAL(RED,XII)) 20,20,21
300 J=2 E4RFV087          D=-1.
NOD1=NSET(KL) E4RFV088          20 CALL UNIT (ZTA,0)
GO TO 350 E4RFV089          CALL VECT (XII,ETA,ZTA)
301 IF (KR=5) 303,400,400 E4RFV090          CALL UNIT (XII,0)
J=1 E4RFV091          RETURN
303 NU(1)=NSET(KR) E4RFV092          END
E4RFV093

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Table VII-74. Source program listing of subroutine ROTA (Link 4)

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* LABEL
CE&KOT SUBROUTINE ROTA F4R0T000
C EXPRESSES MATERIAL MATRIX IN LOCAL AXES F4R0T001
C TO ROTATE MATERIAL AXES IF NECESSARY SO THAT THEY COINCIDE W. DIM F4R0T003
C DIMENSION I(1),AA(1),S(1),N(4),D21(2),D33(3,3),FZ(3,3) F4R0T004
1,P(24),UV(24),X(R),Y(B),Z(L),XD(7),YD(7),ZD(7),G(1) F4R0T005
COMMON I,AA F4R0T006
EQUIVALENCE(I,AA),(D21,D33),(D21(10),E22),(D21(19),E1),(D21(20),G)F4R0T007
EQUIVALENCE(I(1),IM),(I(12),IBM),(I(13),IT),(I(14),IP),(I(15), F4R0T008
1PR5),(I(16),ITYP),(I(17),IMAT),(I(18),IDEG),(I(19),INX),(I(110), F4R0T009
2IH),(I(111),IB),(I(112),IMX),(I(113),IMMY),(I(114),IMW),(I(115),F4R0T010
3IMF),(I(116),IARH),(I(117),N(1)),(I(125),M),(I(126),ITY),(I(127),F4R0T011
4ESTR),(I(128),IELT),(I(129),ITEM),(I(130),ITIC),(I(131),IMET), F4R0T012
5(I(132),ISUM),(I(133),IND),(I(134),IMS),(I(136),IDS),(I(137), F4R0T013
6IORD),(I(138),IORD1),(I(139),ACEL),(I(140),J1),(I(151),J2), F4R0T014
7(I(152),J3),(I(153),J4),(I(154),J5),(I(155),J6),(I(156),J7),(I(157),F4R0T015
8),J8),(I(158),JTY),(I(159),IBB),(I(160),IBO),(I(161),I1D),(I(162),F4R0T016
9IA),(I(163),IDT),(I(164),IDY),(I(165),ITE),(I(164),ITAF) F4R0T017
EQUIVALENCE(I(166),ICAR),(I(167),ICIX),(I(168),ICIV),(I(169), F4R0T018
11C12),(I(170),ICF),(I(171),IXX),(I(172),IYY),(I(173),IZZ), F4R0T019
2(I(174),IC),(I(175),IDEF),(I(176),IST),(I(177),IISI) F4R0T020
3,I(178),IGEM),(I(179),IERR),(I(180),TE),(I(181),D1),(I(182),D5), F4R0T021
4,AA(183),AL1),(AA(184),AL2),(AA(185),AL3),(I(186),O21),(I(187),P), F4R0T022
5,AA(181),UV),(AA(185),X),(AA(183),Y),(AA(171),Z),(AA(179),XD), F4R0T023
6,AA(186),YD),(AA(193),ZD),(AA(195),S),(AA(40),ZGEM) F4R0T024
7,(AA(42),JNP),(AA(43),IPB),(AA(44),JPN),(AA(45),CONS),(AA(46),IUF4R0T025
8),(AA(47),GL),(AA(48),G2),(AA(49),G3) F4R0T026
EQUIVALENCE(I(1349),NIC),(I(1348),ISDT),(I(1347),ISDY),(I(1346) F4R0T027
1,ISDT),(I(1345),J9),(I(1344),J10),(I(1343),JPR5),(I(1342),JSDY) F4R0T028
2,II(1341),JSD2),(I(1340),JRF),(I(1339),JMK),(I(1338),JMW) F4R0T029
3,I(1337),JMM),(I(1336),JMT),(I(1335),ITAS),(I(1334),JNZ) F4R0T030
4,I(1333),JPR),(I(1332),OGY),(I(1331),DGT),(I(1330),PRES) F4R0T031
5,(I(1329),JPK) F4R0T032
DIMENSION BIR(3),SIR(3),DIN(3,3),SR(4),XN(3),XF(3),ONI(6),OF(6), F4R0T033
1RES(6),RED(6),BAS(3),TCLAS(4),NBAN(10),NU(3),NES(3) F4R0T034
EQUIVALENCE(I(1200),IDNE),(I(1201),ICW),(I(1202),LM),(I(1203),AST)F4R0T035
1,(I(1204),INRW),(I(1205),ARE),(I(1206),ICL4),(I(1207),IMEL), F4R0T036
2,IA(1208),IM),(I(1209),ICI),(I(1210),ICDN),(I(1211),ANGLE),(I(1212),F4R0T037
3ICAS),(I(1213),JE),(I(1214),NR),(I(1215),MB) F4R0T038
4,(I(1216),JROT),(I(1217),RST) F4R0T039
EQUIVALENCE(I(1220),BIR),(I(1223),SIR),(I(1226),DIN),(I(1235),SR)F4R0T040
1,(I(1241),XN),(I(1244),XF),(I(1247),ON),(I(1253),OF),(I(1259),RF)F4R0T041
2,(I(1265),RED),(I(1271),NBAS),(I(1274),TCLAS),(I(1278),NBAN) F4R0T042
3,(I(1292),NU),(I(1295),NES) F4R0T043
DIMENSION NEL(20,17),MAC(4,4,20),IMG(90),D016,6),A190,7),R18,R1, F4R0T044
1C(R,2),FF(1),MSET(100),MSET(100),M(3,3) F4R0T045
EQUIVALENCE(I(14000),FF),(I(14011),JP1),(I(1402),JM1),(I(1403),JS1) F4R0T046
EQUIVALENCE(FF(1),NEL),(FF(341),MAC),(FF(461),IMG),(FF(751),DD1), F4R0T047
1,FF(787),4),(FF(1347),B),(FF(1481),C),(FF(1497),NSFT),(FF(1597), F4R0T048
2MSET),(FF(1697),M) F4R0T049
DIMENSION X1(3),ETA(3),ZTA(3) F4R0T050
EQUIVALENCE(DIN(1),X1),(DIN(4),ETA),(DIN(7),ZTA) F4R0T051
DIMENSION R(6,6),T(6),V(3,3),S1(3),R1(3) F4R0T052
EQUIVALENCE(A(1),R),(I(137),T),(V(1),S1),(V(4),T),(V(7),R1) F4R0T053
NO ROTATION IF MATERIAL IS ISOTROPIC F4R0T054
IF (ITYPE) 200,200,9 F4R0T055
SEE IF SOLID F4R0T056
IF (ICAS=3) 10,11,10 F4R0T057
IF (ICAS=4) 12,11,12 F4R0T058
IF SHELL OF REVOLUTION, DO NOT TRANSFORM F4R0T059
IF (ICAS=5) 121,200,121 F4R0T060
IF (ICAS=6) 41,200,41 F4R0T061
COMPUTE THE ANGLE BETWEEN BAS AND KSI F4R0T062
ANG=SCAL(BAS,X1) F4R0T063
NO ROTATION IF THE ANGLE IS SMALL F4R0T064
IF (1.-ABS(ANG))-1.E-4) 200,200,101 F4R0T065
NON-SOLID, MATERIAL AXES ARE (ZTAXBAS)XZTA,ZTAXBAS,7TA F4R0T066
CC=1 F4R0T067
CALL VECT (T,ZTA,BAS) F4R0T068
CALL UNIT (T,CC) F4R0T069
CALL VECT (S1,T,ZTA) F4R0T070
CALL UNIT (S1,CC) F4R0T071
CALL VECT (R1,S1,T) F4R0T072
DD 14 I=1,3 F4R0T073
DD 14 J=1,3 F4R0T074
MIJ,1=0 F4R0T075
DO 15 K=1,3 F4R0T076
MIJ,1)=MIJ,1)+DINIK,1)*V(K,J) F4R0T077
CONTINUE F4R0T078
GO TO 16 F4R0T079
SOLID MATERIAL AXES ARE PARALLEL TO OVERALL SYSTEM, F4R0T080
DD 13 I=1,3 F4R0T081
DD 13 J=1,3 F4R0T082
MIJ,1)=0*(MIJ,1) F4R0T083
GO TO 16 F4R0T084
GENERATE R OF (R)TRANS*(DD)*(R) F4R0T085
DD 17 J=1,3 F4R0T086
DD 17 I=1,3 F4R0T087
R(I,J)=MIJ,1) F4R0T088
DO 18 I=1,3 F4R0T089
R(I,4)=R(I,1)*W(1,2) F4R0T090
R(I,5)=R(I,1)*W(1,3) F4R0T091
R(I,6)=R(I,2)*W(1,3) F4R0T092
R(I,4)=R(I,1)*W(2,1)*2, F4R0T093
R(I,5)=R(I,1)*W(2,1)*2, F4R0T094
R(I,6)=R(I,2)*W(2,1)*2, F4R0T095
R(I,4)=R(I,1)*W(2,2)+W(2,1)*W(1,2) F4R0T096
R(I,5)=R(I,1)*W(2,3)+W(2,1)*W(1,3) F4R0T097
R(I,6)=R(I,2)*W(2,3)+W(2,1)*W(1,3) F4R0T098
R(I,4)=R(I,1)*W(3,2)+W(3,1)*W(1,2) F4R0T099
R(I,5)=R(I,1)*W(3,3)+W(3,1)*W(1,3) F4R0T100
R(I,6)=R(I,2)*W(3,3)+W(3,1)*W(1,3) F4R0T101
R(I,4)=R(2,1)*W(3,2)+W(3,1)*W(2,2) F4R0T102
R(I,5)=R(2,1)*W(3,3)+W(3,1)*W(2,3) F4R0T103
R(I,6)=R(2,2)*W(3,3)+W(3,2)*W(2,3) F4R0T104
DD 21 I=1,6 F4R0T105
DD 21 J=1,6 F4R0T106
TIJ=0 F4R0T107
DO 23 K=1,6 F4R0T108
TIJ)=TIJ)+R(K,1)*R(K,J) F4R0T109
CONTINUE F4R0T110
DD 24 J=1,6 F4R0T111
DD(I,J)=T(I,J) F4R0T112
CONTINUE F4R0T113
DD 31 J=1,5 F4R0T114
DD 32 I=1,6 F4R0T115
TI=0 F4R0T116
DD 33 K=1,6 F4R0T117
TI)=TI)+R(K,1)*DD(K,J) F4R0T118
CONTINUE F4R0T119
DD(I,31)=1 F4R0T120
CONTINUE F4R0T121
DDIRECTION COSINES OF NEW MATE.AXES IN THE OLD ARE IN W(3,3) F4R0T122
IF (INP=2) 200,19,19 F4R0T123
WRITE OUTPUT TAPE 6,19,1,(R(I,J),J=1,6),I=1,6) F4R0T124
FORMAT (20X,57#POSTMULTIPLYING MATRIX IN MATERIAL TRANSFORMATION F4R0T125
10LLWS/(20X,6F12,5)) F4R0T126
RETURN F4R0T127
END F4R0T128
F4R0T129

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Table VII-77. Source program listing of subroutine SETA (Link 4)

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* LABEL
CE4SET          E4SET000          14 DROT(IK)=REC(I)
SUBROUTINE SETA E4SET001          C CONTINUE
GENERATES STRAIN-DEFLECTION RELATIONSHIP AT A NODAL LINE E4SET002          TRANSFORM COORDINATES AND DEFLEMS INTO LOCAL IF NECESSARY
DIMENSION IA(1),AA(11),S(1),N(8),D21(21),O33(3),31+72(3,3) E4SET003          IF (IRDT) 25,24,25
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YM(7),ZD(7),G(11) E4SET004          DO 26 J=1,5
COMMON IA,AA E4SET005          DO 27 I=1,3
EQUIVALENCE(IA,AA), (D21,O33), (D21(10),F221,(D21(19),F), (D21(20),G) E4SET006          SIR(I)=D.
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5), F4SET007          DO 28 L=1,3
11PKS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDRG), (IA(9),INX), (IA(10),E4SET008          SIR(I)=SIR(I)+DIN(L)+U(L),J)
2H), (IA(11),IR), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),F4SET009          CONTINUE
3MF), (IA(16),JARE), (IA(17),N11), (IA(125),M), (IA(20),ITV), (IA(21),E4SET010          DO 29 I=1,3
4STR), (IA(28),IELT), (IA(29),IEM), (IA(30),ITIC), (IA(31),IMET), F4SET011          U(I,J)=SIR(I)
5(IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),DS), (IA(37), F4SET012          CONTINUE
6JORD), (IA(38),IORD), (IA(39),ACEL ), (IA(50),J1), (IA(51),J2), F4SET013          ICON=ICON+1
7(IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),E4SET014          ICOL=ICOL
8), (J8), (IA(58),JTY), (IA(59),IB), (IA(60),IBO), (IA(61),IBD), (IA(62),F4SET015          C COMPUTE THE LENGTH AND THE UNIT VECTOR OF THE NODAL LINE
9(IA), (IA(63),ID), (IA(64),IDY), (IA(65),IFE), (IA(61),ITAP) F4SET016          DCAR(1)=DCAR(1)
EQUIVALENCE (IA(66),ICAR), (IA(67),ICF), (IA(68),ICL), (IA(69), E4SET017          DCAR(2)=DCAR(2)
11C12), (IA(70),ICF1), (IA(71),ICX), (IA(72),IY), (IA(73),I22), F4SET018          DCAR(3)=DCAR(3)
2(IA(74),IC), (IA(75),IDFF), (IA(76),IST), (IA(77),ITS) E4SET019          CL=1.
3, (IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),DT), (AA(82),DC), E4SET020          CALL UNIT(OCAR,CL)
4(AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P), E4SET021          GENERATE LEFTHAND SIDE
5(AA(131),UV), (AA(135),X), (AA(136),Y), (AA(171),Z), (AA(179),XD), F4SET022          I=1
6(AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(401),ZEM) F4SET023          I2=I
7, (AA(142),IMP), (AA(143),IPB), (AA(144),IPM), (AA(145),CONS), (AA(146),TUE4SET024          IS=I
8(IAA(471),G1), (AA(481),G2), (AA(491),G3) E4SET025          GO TO (37,37,31,32,33,34),IS
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346) E4SET026          I1=1
1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSOY), E4SET027          I2=2
2, (IA(341),JSOZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY), E4SET028          GO TO 37
3, (IA(337),JMZ), (IA(336),JMF), (IA(335),JAS), (IA(334),JZ) F4SET029          I3=3
4, (IA(333),JPR), (AA(332),OCY), (AA(331),OG2), (AA(330),PRES) F4SET030          I2=3
5, (IA(329),JPR) F4SET031          GO TO 37
DIMENSION BIR(3), SIR(3), DIN(3), SR(6), XN(3), XF(3), ON(6), DF(6), E4SET032          I1=1
1,NES(6), RED(6), BAS(3), ICLAS(4), NBSAN(10), NU(3), NES(3) E4SET033          I2=3
EQUIVALENCE (AA(200),IONF), (AA(201),ICN), (AA(202),LM), (AA(203),AST) F4SET034          GO TO 37
1, (AA(204),INBN), (AA(205),AKE), (AA(206),ICLA), (AA(207),IMEL), E4SET035          I1=2
2(AA(208),IM), (AA(209),IC), (AA(210),ICUN), (AA(211),ANGLE), (AA(212), F4SET036          I2=3
3(CAS), (AA(213),IE), (AA(214),AM), (AA(215),MB) E4SET037          I3=3
4, (AA(216),JROT), (AA(217),KST) E4SET038          GO TO 37
EQUIVALENCE (AA(220),RIR), (AA(223),SIR), (AA(226),DIN), (AA(235),SR) E4SET039          I1=1
1, (AA(241),XN), (AA(244),XF), (AA(247),ON), (AA(253),OF), (AA(259),RS) E4SET040          RED(1)=0.
2, (AA(265),RED), (AA(271),BAS), (AA(274),ICLAS), (AA(278),NRAW) E4SET041          RED(2)=0.
3, (AA(292),NU), (AA(295),NES) E4SET042          RED(3)=1.
DIMENSION NEL(20,17), MAC(4,4,20), IN(400), DR(16,6), A(90,7), B(8,8), E4SET043          GENERATE RIGHAND SIDE(S)
1C18,21,FF(1),MSET(100),MSET(100),MSET(100),MSET(100),DCAR(3) E4SET044          JRI8=IRIG
EQUIVALENCE (AA(1400),FF), (NU(11),J1), (NU(12),J2), (NU(13),J3) E4SET045          DO 40 I=1,IRIG
EQUIVALENCE (FF(1),NEL), (FF(341),MAC), (FF(166),IWG), (FF(175),DO), E4SET046          ICL=ICOL+1
1, (FF(787),A), (FF(1417),B), (FF(1481),C), (FF(1497),MSET), (FF(1597),) E4SET047          IF (I-1) 45,45,50
2MSET), (FF(1697),W) E4SET048          IF (IDR) 50,46,50
DIMENSION U(3,5), CDIS(3), CROT(3), DDIS(3), DRD(13), DCOR(3), ZTA(3) E4SET049          LINEAR STRAIN CASE
EQUIVALENCE (X(1),U,DCOR), (X(4),CDIS), (X(7),CROT), (X(10),DDIS) E4SET050          CC=0.
1(X(13),DROT), (DCAR,XF) F4SET051          IF (DT) 47,49,47
EQUIVALENCE (NES(1),ICOL), (NES(2),TRIG), (NES(3),IDR), (DIN(7),ZTA) E4SET052          IF (ITYPE) 48,47,48
C INITIALIZE F4SET053          C CALL ALLDOT
IELT=IELT F4SET054          GO TO 49
IMS=NEL(IELT,5) F4SET055          CALL TEMP(CC)
C GENERATE STRAIN-DEFLECTION EQUATIONS FOR EVERY NODAL LINE E4SET056          CC=CC+DT
DO 12 I=1,IMS E4SET057          A(ICON,ICL)=SCALIDD(1,DCAR)/CL-CC
K=NEL(IELT, I+9) E4SET058          GO TO 40
IF IK=ICN(13,12,13) E4SET059          CHANGE OF CURVATURE CASE
C FIND RELATIVE COORDINATES AND DEFLEMS OF NODE K IN OVERALL SYSTEM E4SET060          CC=0.
13 CALL FINDX(K,XF) E4SET061          IF (DG) 57,59,57
CALL FINDX(K,OF) E4SET062          IF (ITYPE) 58,57,58
DO L61 I=1,15 E4SET063          CC=ALL+DG
X(I)=0. E4SET064          GO TO 59
DCOR(1)=XF(1)-XN(1) E4SET065          CALL TEMP(CC)
DCOR(2)=XF(2)-XN(2) E4SET066          CC=CC+DG
DCOR(3)=XF(3)-XN(3) E4SET067          DC=SCAL(DROT,DCAR)
JDEG=IDEG E4SET068          DO 592 J=1,3
DO 14 I=1,IDEG E4SET069          DROT(I)=DROT(I)+DC*DCAR(J)
14 RFD(I)=OF(I)-QNI(I) E4SET070          CALL VECT (SIR,RED,DCAR)
SEPARATE DEFLECTIONS INTO DISPLACEMENTS AND ROTATIONS E4SET071          DC=1.
K=0 E4SET072          CALL UNIT(SIR,DC)
IF (ICAS=2) 16,15,16 E4SET073          DC=SCAL(SIR,BRUI)/CL
IF (ICAS=6) 18,17,18 E4SET074          A(ICON,ICL)=DC-CC
16 KS=2 E4SET075          CONTINUE
GO TO 18 E4SET076          IWS(ICON)=1
17 KS=3 E4SET077          MB=MB
GO TO 18 E4SET078          IF (INBN) 71,70,71
18 DO 19 I=1,IDEG E4SET079          DO 72 I=1,MB
IK=1 E4SET080          IF (INBN(1)-K) 72,73,72
IF (I-KB121,20,20) E4SET081          CONTINUE
20 IK=1+KS E4SET082          GO TO 70
IF (I-K-3) 22,22,23 E4SET083          IWS(ICON)=I0
21 IF (I-K-3) 22,22,23 E4SET084          IF (IMP=2) 12,61,61
22 CDS(I,K)=QNI(I) E4SET085          WRITE OUTPUT TAPE 6,62,ICN,K,(A(ICON,J),J=1,7),IWG(ICON)
DDIS(I,K)=RED(I) E4SET086          FORMAT (15,3X,2HT0,15,5X,7F13.5,15)
GO TO 19 E4SET087          CONTINUE
23 IK=IK-3 E4SET088          RETURN
CROT(I,K)=ON(I) E4SET089          END

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**Table VII-78. Source program listing of subroutine STRA (Link 4)**

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* LABEL
CE4STA SUBROUTINE STRA F4STAD00
DIMENSION I(41),AA(1),S(1),N(1),D2(21),D3(3),E(22),3*3
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA),(D21,D33),(D2110),F22,(D2119),E),(D2120),G
EQUIVALENCE (IA11),IN1,(IA12),IN2,(IA13),IT1,(IA14),IP1,(IA15),
1IPRS),(IA16),ITYPE1,(IA17),IMAT),(IA18),IDFG1,(IA19),INX),(IA110),F4STAD00
2IM),(IA111),IAR1,(IA112),IMX),(IA113),IMY),(IA114),IMZ),(IA115),F4STAD00
3IMF1),(IA116),IARE1,(IA117),N(1),(IA125),M),(IA126),ITY),(IA127),F4STAD00
4ISTR),(IA128),IELT),(IA129),ITEM),(IA130),ITIC),(IA131),IMFT) F4STAD01
5IA(32),ISUM),(IA133),IND),(IA134),IMS1,(IA136),IDS),(IA137), F4STAD12
6IORD),(IA138),IORD1),(IA139),ACEL),(IA150),J1,(IA151),J2, F4STAD13
7IA(52),J3),(IA153),J4),(IA154),J5),(IA155),J6),(IA156),J7),(IA157),F4STAD14
8I,JR),(IA158),JTY),(IA159),JRB),(IA160),IRB),(IA161),IIO),(IA162),F4STAD15
9IA(17),IDT),(IA164),IDY),(IA165),ITE),(IA161),ITAP) F4STAD16
EQUIVALENCE (IA168),ICAR1,(IA167),ICIX),(IA168),ICIX),(IA169), F4STAD17
1IC12),(IA170),IEF1),(IA171),IXX),(IA172),IYY),(IA173),IZZ), F4STAD18
2IA(74),IIC),(IA175),IDFF),(IA176),IST),(IA177),IIS) F4STAD19
3,(IA178),IGEM),(IA179),IERK),(AA180),TE),(AA181),DT),(AA182),DC) F4STAD20
4AA(83),AL1),(AA184),AL2),(AA185),AL3),(AA186),D21),(AA187),P) F4STAD21
5AA(131),OV),(AA185),X),(AA183),Y),(AA181),Z),(AA179),XD) F4STAD22
6AA(186),YD),(AA193),ZD),(AA191),S),(AA140),ZGEM) F4STAD23
7AA(42),INP1),(AA(43),IPRS),(AA(44),IPENT),(AA(45),COMS),(AA(46),IUF4STAD24
8I,(AA(47),G1),(AA(48),G2),(AA(49),G3) F4STAD25
EQUIVALENCE (IA1349),NTIC),(IA1348),ISD1),(IA1347),ISD2),(IA1346) F4STAD26
1,ISD2),(IA1345),J9),(IA1344),J10),(IA1343),JPRS),(IA1342),JSDY) F4STAD27
2,(IA1341),JSDZ),(IA1340),JARP),(IA1339),JMMX),(IA1338),JMY) F4STAD28
3,(IA1337),JMMZ),(IA1336),JMF),(IA1335),ITAS),(IA1334),ID1) F4STAD29
4,(IA1333),IPR),(IA1332),DGY),(IA1331),DGZ),(AA(330),PRES) F4STAD30
J=IOS F4STAD31
DO 5 I=1,IDS F4STAD32
J=J+IDS F4STAD33
CALL TRAN (S,J) F4STAD34
CONTINUE F4STAD35
IARR=IDS F4STAD36
IERR=IDS F4STAD37
DO 6 I=1,IOS F4STAD38
IARR=IARR+1 F4STAD39
IAB=IAB F4STAD40
IERR=IERR+IDS F4STAD41
IIE=IERR F4STAD42
DO 7 J=1,IDS F4STAD43
IAB=IAB+IDS F4STAD44
IIE=IIE F4STAD45
IF (IAR-IIE) 7,7,13 F4STAD46
IFMP=5(IIE) F4STAD47
S(IIE)=S(IAB) F4STAD48
S(IAR)=TEMP F4STAD49
CONTINUE F4STAD50
CONTINUE F4STAD51
J=IDS F4STAD52
DO 8 I=1,IDS F4STAD53
J=J+IDS F4STAD54
CALL TRAN (S,J) F4STAD55
CONTINUE F4STAD56
RETURN F4STAD57
END F4STAD59

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**Table VII-79. Source program listing of subroutine STRS (Link 4)**

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* LABEL
CF4STR SUBROUTINE STRS F4STR000
COMPUTE STRESSES FROM STRAINS F4STR001
DIMENSION I(11),AA(1),S(1),N(1),D2(21),D3(3),E(22),3*3 F4STR002
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1) F4STR003
COMMON IA,AA F4STR004
EQUIVALENCE (IA,AA),(D21,D33),(D2110),E22,(D2119),E),(D2120),G F4STR005
EQUIVALENCE (IA11),IN1,(IA12),IN2,(IA13),IT1,(IA14),IP1,(IA15), F4STR006
1IPRS),(IA16),ITYPE1,(IA17),IMAT),(IA18),IDFG1,(IA19),INX),(IA110),F4STR007
2IM),(IA111),IAR1,(IA112),IMX),(IA113),IMY),(IA114),IMZ),(IA115),F4STR008
3IMF1),(IA116),IARE1,(IA117),N(1),(IA125),M),(IA126),ITY),(IA127),F4STR009
4ISTR),(IA128),IELT),(IA129),ITEM),(IA130),ITIC),(IA131),IMFT) F4STR010
5IA(32),ISUM),(IA133),IND),(IA134),IMS1,(IA136),IDS),(IA137), F4STR011
6IORD),(IA138),IORD1),(IA139),ACEL),(IA150),J1,(IA151),J2, F4STR012
7IA(52),J3),(IA153),J4),(IA154),J5),(IA155),J6),(IA156),J7),(IA157),F4STR013
8I,JR),(IA158),JTY),(IA159),JRB),(IA160),IRB),(IA161),IIO),(IA162),F4STR014
9IA(17),IDT),(IA164),IDY),(IA165),ITE),(IA161),ITAP) F4STR015
EQUIVALENCE (IA168),ICAR1,(IA167),ICIX),(IA168),ICIX),(IA169), F4STR016
1IC12),(IA170),IEF1),(IA171),IXX),(IA172),IYY),(IA173),IZZ), F4STR017
2IA(74),IIC),(IA175),IDFF),(IA176),IST),(IA177),IIS) F4STR018
3,(IA178),IGEM),(IA179),IERK),(AA180),TE),(AA181),DT),(AA182),DC) F4STR019
4AA(83),AL1),(AA184),AL2),(AA185),AL3),(AA186),D21),(AA187),P) F4STR020
5AA(131),OV),(AA185),X),(AA183),Y),(AA181),Z),(AA179),XD) F4STR021
6AA(186),YD),(AA193),ZD),(AA191),S),(AA140),ZGEM) F4STR022
7AA(42),INP1),(AA(43),IPRS),(AA(44),IPENT),(AA(45),COMS),(AA(46),IUF4STR023
8I,(AA(47),G1),(AA(48),G2),(AA(49),G3) F4STR024
EQUIVALENCE (IA1349),NTIC),(IA1348),ISD1),(IA1347),ISD2),(IA1346) F4STR025
1,ISD2),(IA1345),J9),(IA1344),J10),(IA1343),JPRS),(IA1342),JSDY) F4STR026
2,(IA1341),JSDZ),(IA1340),JARP),(IA1339),JMMX),(IA1338),JMY) F4STR027
3,(IA1337),JMMZ),(IA1336),JMF),(IA1335),ITAS),(IA1334),ID1) F4STR028
4,(IA1333),IPR),(IA1332),DGY),(IA1331),DGZ),(AA(330),PRES) F4STR029
5,(IA1329),IPR) F4STR030
DIMENSION STR(3),SIR(3),DIN(3),SR(6),XN(3),XF(3),ON(6),OF(6) F4STR031
1,RED(6),BAS(3),ICLAS(4),NBR(10),M(3),NES(3) F4STR032
EQUIVALENCE (AA1200),IUNE1,(AA1201),ICN1,(AA1202),LM),(AA1203),AST F4STR033
1),(AA1204),INRON),(AA1205),ARE),(AA1206),ICL41,(AA1207),TMEL), F4STR034
2IAA(208),IM),(AA1209),IC),(AA1210),ICGN),(AA1211),ANGLF),(AA1212), F4STR035
3ICAS),(AA1213),IF),(AA1214),NB),(AA1215),MR) F4STR036
4,(AA1216),IROT),(AA1217),BST) F4STR037
EQUIVALENCE (AA1220),RIR1,(AA1221),SIR),(AA1226),D19),(AA1231),SR F4STR038
1),(AA1241),XN1),(AA1244),XF1),(AA1247),ON),(AA1251),OF),(AA1259),RES F4STR039
2,(AA1265),RED),(AA1271),BAS),(AA1274),ICLAS),(AA1278),NBR) F4STR040
3,(AA1292),NO),(AA1295),NES) F4STR041
DIMENSION NEL(20),L1,MAC(4,4,20),IWI(50),DD(6,6),A19(7),R(8,R), F4STR042
1C(8,2),FF(1),NSET(100),MSF(100),M(3,3) F4STR043
EQUIVALENCE (AA14000),FF),(N(1),J1),(M(2),J2),(M(3),J3) F4STR044
EQUIVALENCE (FF(1),NEL),(FF(1341),MAC),(FF(1661),IWI),(FF(751),NO), F4STR045
1,FF(1781),A),(FF(1417),B),(FF(1481),C),(FF(1497),NSET),(FF(1597), F4STR046
2MSET),(FF(1697),W) F4STR047
EQUIVALENCE (NES(1),ICDL),(NES(2),TRIC),(NES(3),IUR) F4STR048
COMPUTE GEOMETRIC CONSTANT F4STR049
ICDL=ICDL F4STR050
IRIG=IRIG F4STR051
CM=TE F4STR052
IF ICAS=31 1,2,3 F4STR053
IF ICAS=4) 1,2,1 F4STR054
CM=1. F4STR055
INITIALIZE STRESS AREA F4STR056
DO 4 I=1,6 F4STR057
RED(I)=0. F4STR058
DO 10 J=1,IRIG F4STR059
DO 15 I=1,ICDL F4STR060
IJ=J-1)*3+I F4STR061
DO 20 K=1,ICOL F4STR062
RED(IJ)=K*(I,J)+DD(I,K)*C(K,J)*CM F4STR063
CONTINUE F4STR064
CM=CM*TE/TE/12. F4STR065
CONTINUE F4STR066
MODIFY THE COMPUTED STRESSES WITH THE PRFSCHHEID ONES IF ANY F4STR067
IF (INRON) 34,33,34 F4STR068
KRG=1 F4STR069
KEN=3 F4STR070
KSH=1 F4STR071
ICAS=ICAS F4STR072
GO TO (61,62,61,64,65,66,61,68,1),ICAS F4STR073
GO TO 61 F4STR074
GO TO 61 F4STR075
GO TO 61 F4STR076
GO TO 61 F4STR077
GO TO 61 F4STR078
GO TO 61 F4STR079
GO TO 61 F4STR080
GO TO 61 F4STR081
GO TO 61 F4STR082
GO TO 61 F4STR083
GO TO 61 F4STR084
GO TO 61 F4STR085
K=0 F4STR086
DO 69 I=1,KSH F4STR087
DO 70 J=KRG*KFN,? F4STR088
K=K+1 F4STR089
70 RED(IJ)=SR(IK) F4STR090
KRG=KRG+3 F4STR091
KFN=KFN+3 F4STR092
CONTINUE F4STR093
ASKRANGE STRESSES IN ORDER OF 1,2,3,12,13,23 IN SR BLOCK F4STR094
DO 30 I=1,6 F4STR095
SR(I)=RED(I) F4STR096
IF (ISTR) 31,31,40 F4STR097
IF (ICAS=3) 50,40,32 F4STR098
IF (ICAS=4) 50,40,50 F4STR099
SR(3)=RED(4) F4STR100
SR(4)=RED(3) F4STR101
RETURN F4STR102
END F4STR104

```



**Table VII-83. Source program listing of subroutine TRAN (Link 4)**

```

* LABEL
CE4TRN
SUBROUTINE TRAN (A,IFS)
FOR LOCAL-OVERALL COORDINATE TRANSFORMATION FOR VECTORS
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),F22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
COMMON IA,AA
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),E22),(D21(19),E1),(D21(20),G)
EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5),I)
1PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INXI),(IA(10),E4TRN008
2IH),(IA(11),I8),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMMZ),(IA(15),E4TRN009
3IMFI),(IA(16),IARE),(IA(17),M(3)),(IA(25),M),(IA(26),IY),(IA(27),E4TRN010
4ISTJ),(IA(28),IPLT),(IA(29),ITEM),(IA(30),ITTC),(IA(31),IMET), E4TRN011
5IA(32),ISOM),(IA(33),INDI),(IA(34),IMS),(IA(36),IOS),(IA(37), E4TRN012
6IDRO),(IA(38),IDROL),(IA(39),ACH),(IA(50),J1),(IA(51),J2), E4TRN013
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E4TRN014
8J1),(IA(58),J7Y),(IA(59),I8H),(IA(60),IBD),(IA(61),ID),(IA(62),E4TRN015
9IIA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(41),ITAP) E4TRN016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICEY),(IA(69), E4TRN017
1ICIZ),(IA(70),ICFI),(IA(71),ICX),(IA(72),IYY),(IA(73),IZZ), E4TRN018
2IA(74),IIC),(IA(75),IDEP),(IA(76),IST),(IA(77),IIS) E4TRN019
3IA(78),IGEM),(IA(79),IFRR),(AA(80),TE),(AA(81),D11),(AA(82),DG), E4TRN020
4AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P1, E4TRN021
5AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), E4TRN022
6AA(186),YD),(AA(193),ZD),(AA(125),S),(AA(40),ZGEM) E4TRN023
7AA(42),IMP),(AA(43),IPB6),(AA(44),IPFN),(AA(45),CONS),(AA(46),IIE4TRN024
8AA(47),S),(AA(48),G2),(AA(49),G3) E4TRN025
EQUIVALENCE (IA(349),NYIC),(IA(349),ISDT),(IA(347),ISDY),(IA(346) E4TRN026
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPR5),(IA(342),JSDY) E4TRN027
2IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) E4TRN028
3IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) E4TRN029
4IA(333),IPR),(AA(332),DGY),(AA(331),DGZ),(AA(330),PRES) E4TRN030
5IA(329),IPR) E4TRN031
DIMENSION EM(4,4),EN(4,4),O(4,4),DIR(3,3),DUM(3) E4TRN032
EQUIVALENCE (AA(200),EM),(AA(216),EN),(AA(232),EQ),(AA(246),O), E4TRN033
1AA(264),DIR),(AA(273),DUM) E4TRN034
DIMENSION A(1) E4TRN035
10 IGEMP=IGEM+1 E4TRN036
LJI=0 E4TRN037
20 LK=IFS-4*IMS E4TRN038
DO 300 L=1,IGEMP E4TRN039
LK=LK+3*IMS E4TRN040
30 DO 200 J=1,3 E4TRN041
DO 200 I=1,IMS E4TRN042
LJI=LJI+1 E4TRN043
DUM(LJI)=O E4TRN044
LK=LK+1 E4TRN045
40 DO 100 K=1,3 E4TRN046
LK=LK+IMS E4TRN047
100 DUM(LJI)=DUM(LJI+DIR(K,J))*A(LK) E4TRN048
200 CONTINUE E4TRN049
300 CONTINUE E4TRN050
IMS=3*IGEMP*IMS E4TRN051
DO 400 I=1,IN E4TRN052
II=IFS+1 E4TRN053
400 A(II)=DUM(II) E4TRN054
RETURN E4TRN055
END E4TRN056

```

**Table VII-84. Source program listing of subroutine UNIT (Link 4)**

```

* LABEL
CE4UNT
SUBROUTINE UNIT(CIR,Q)
OBTAINS A UNIT VECTOR ALONG A LINE SEGMENT
IF Q=NEGATIVE, CHANGE DIRECTION AND REPLACE WITH UNITY, Q=LENGTH
IF Q=0, MAKE Q=LENGTH*LENGTH AND RETURN
IF Q=POSITIVE, REPLACE WITH UNITY, Q=LENGTH
DIMENSION CIR(3)
R=CIR(1)**2+CIR(2)**2+CIR(3)**2
IF (Q) 10,-19,20
19 Q=R
GO TO 21
20 CIR(1)=-CIR(1)
CIR(2)=-CIR(2)
CIR(3)=-CIR(3)
D=SQRT(F)
CIR(1)=CIR(1)/Q
CIR(2)=CIR(2)/Q
CIR(3)=CIR(3)/Q
21 RETURN
END

```

**Table VII-85. Source program listing of subroutine VECT (Link 4)**

```

* LABEL
CE4VCT
SUBROUTINE VECT(A,B,C)
PERFORMS VECTORIAL VECTOR PRODUCT
TO OBTAIN A AS XC
DIMENSION A(3),B(3),C(3)
A(1)=B(2)*C(3)-B(3)*C(2)
A(2)=B(3)*C(1)-B(1)*C(3)
A(3)=B(1)*C(2)-B(2)*C(1)
RETURN
END

```

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