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FLIGHT LOADS MEASUREMENTS OBTAINED FROM CALIBRATED STRAIN-GAGE BRIDGES MOUNTED EXTERNALLY ON THE SKIN OF A LOW-ASPECT-RATIO WING

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FLIGHT LOADS MEASUREMENTS OBTAINED FROM CALIBRATED STRAIN-GAGE BRIDGES MOUNTED EXTERNALLY ON THE SKIN OF A LOW-ASPECT-RATIO WING

I

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SUMMARY

Flight-test measurements of structural loads (shear, bending moment, and torque) were made at three spanwise stations on a low-aspect-ratio, thin, swept wing which had a structural skin, full-depth honeycomb core, sandwich construction. The measurements were made by using strain-gage bridges mounted on the external surface of the wing. Linear regression analysis was used to establish the relationship between loads applied during single-point calibration loadings and the measured electrical output of the strain-gage bridges. The established relationships are expressed by load equations applicable to each of three wing semispan stations for axis systems oriented parallel and perpendicular to the vehicle center line. The flight test was performed with a drone aircraft equipped with a large external fuel tank located beneath the fuselage in the area of the wing. During the flight test, this fuel tank was jettisoned. Therefore, the aircraft is considered to have two configurations, that is, external fuel tank on or external fuel tank off. For each configuration, there is essentially a linear relationship between wing structural load ratios and the aircraft angle of attack.

The wing structural loads (as determined from the strain-gage bridge measurements) were in close agreement with those determined from differential pressure measurements but were higher, in most cases, than theoretical estimates based on an aerodynamic finite-element analysis method.

INTRODUCTION

Calibrated strain-gage bridges have been used extensively to determine flight loads (shear, bending moment, and torque) on a variety of aircraft structures. For structures such as high-aspect-ratio wings with a spar-rib construction, the load paths between the wing and the fuselage are easily defined, and suitable methods of locating and calibrating the strain-gage bridges have been established (ref. 1). For low-aspect-ratio wings with multiple spars, the loads from the wing are carried into the fuselage at several places, and the problems of locating and calibrating strain-gage bridges for load measurements become more complex (refs. 2, 3, and 4). The use of strain-gage bridges for load measurements on low-aspect-ratio wings of structural skin, honeycomb core, sandwich construction introduces additional complications because there are no easily identifiable structural load paths on which to locate the strain-gage bridges. (For wings constructed with spars and ribs, the strain gages for the shear and bending-moment bridges are usually mounted on the spar vertical webs and flanges, respectively (ref. 1).) Reference 5 presents details on the use of four straingage bridges mounted on the exterior surface to measure flight loads on this type of lowaspect-ratio wing. The measurements presented in reference 5 are for a single inboard station with the reference axis system oriented parallel and perpendicular to the wing 40-percent chord line.

This report presents the results of a more detailed study of a wing identical to that of reference 5. The evaluation presented here is based on a larger number of exterior surface mounted strain-gage bridges and a more extensive loads calibration procedure.

Flight loads measurements are presented for three wing semispan stations for axis systems oriented parallel and perpendicular to the aircraft center line as discussed in the appendix of reference 5. The wing reported on herein was also instrumented to measure differential pressures on the wing semispan opposite to that containing the straingage bridges. The results for the differential pressures measured during the flight test are reported in detail in reference 6; however, in this paper, some wingloads determined from integration of differential pressure measurements are presented and compared with those obtained from the strain-gage bridges.

SYMBOLS

Values are given in SI Units. The measurements and calculations were made in U.S. Customary Units.

с	chord
g	acceleration due to gravity, 9.80 $\mathrm{m/sec^2}$
L _i	ith general load (that is, V, M, and T for each wing station)
M .	bending moment, N-m
\mathbf{q}^{∞}	free-stream dynamic pressure, Pa (In figs. 8, 9, and 12, q is used.)
Т	torque, N-m

v	shear, N
Х, Ү	reference axes (fig. 3)
α	angle of attack, deg
$\beta_{\mathbf{ij}}$	coefficient of jth bridge for ith load equation, $Load/mV$
$\mu_{\mathbf{j}}$	output of jth bridge, mV
Subscripts	and abbreviations:
В	bending-moment bridge

Т

torque bridge

WING AND INSTRUMENTATION

Wing

The low-aspect-ratio, thin, swept wing on which the flight loads measurements were obtained is the standard wing for the BQM-34E drone aircraft (supersonic Firebee II) shown in figure 1. The wing structure consists of upper and lower tapered thickness stainless steel skins which are bonded to a full-depth aluminum honeycomb core (there are no internal spar or rib-type structures in the wing). The wing has an aspect ratio of 2.5, a taper ratio of 0.3, a leading-edge sweep angle of 53° , and a maximum thickness of 3 percent of the chord length. The wing has no control surfaces and no incidence angle, dihedral angle, twist, or camber. The airfoil is an NACA 65-003 shape that has been modified to provide a finite thickness trailing edge. The wing has a span of 2.720 m, a reference area of 2.970 m², a net exposed area of 2.150 m², a projected center line root chord of 1.676 m, and a tip chord of 0.503 m. The total wing structure, including the fuselage crossover section, has a mass of approximately 67 kg.

Strain-Gage Bridges

The left semispan of the test wing was instrumented with strain-gage bridges mounted on the exterior surfaces at 11 locations (two at each location) as shown in figures 2 and 3. The bridges consisted of four strain gages each with each gage connected as an active arm in a Wheatstone bridge circuit. One bridge at each location was mounted entirely on the wing upper surface, with the four strain gages positioned in an X-pattern (see inset in fig. 2) so as to be sensitive primarily to skin shearing strains produced by torque loads. The bridges arranged in the X-pattern are identified by their location number (fig. 3) and by the addition of a letter T for torque bridge. The second bridge at each location consisted of two parallel gages on the upper surface and an identical set of two gages on the lower surface. These gages are arranged to be responsive to bending-moment loads (that is, compressive strain on the upper surface and tension strain on the lower surface for positive loads), they are identified by their location number and by the addition of a letter B for bending-moment bridge. Because of the sandwich construction of the wing, it was not possible to include bridges arranged in the usual manner for sensing shear loads as on a spar vertical web.

Axis Systems

The axis system for each strain-gage bridge station is oriented parallel and perpendicular to the vehicle center line as shown in figure 3. The X-axis for each semispan station passes through the respective sets of strain-gage bridges for that station. The Y-axes, which are coincident in orientation, pass through the intersection of the quarter chord line and the X-axis for the inboard station.

CALIBRATION PROCEDURE

The wing calibration procedure, which was performed prior to the flight test, consisted of applying calibration loadings to the wing and measuring the electrical imbalance, or output, of the strain-gage bridges. A regression analysis was then used, as explained in reference 1, to establish a relationship between the strain-gage bridge outputs and the wingloads shear (V), bending moment (M), and torque (T) resulting from the applied calibration loadings.

The relationship between wingloads and the strain-gage bridge outputs was established by using data from single-point calibration loadings. The accuracy of the established relationship was then checked by use of data from multipoint calibration loadings.

Calibration Loadings and Measured Bridge Outputs

<u>Single-point loads.</u> - Single-point calibration loadings were applied to the wing at each of the 15 calibration load point locations shown by the circles in figure 3, and the electrical output of each of the strain-gage bridges was recorded for that loading. To accomplish these loadings, the test wing was mounted on a drone aircraft fuselage, and the whole assembly was inverted (fig. 4) so that the applied loads (inert weights) would produce stresses similar in direction to upward flight loads. The large diameter inert weights were placed on sponge rubber pads, 0.05 m by 0.05 m, to achieve the loading without inducing high local stress concentrations. Calibration loads of 1246 N were applied at load point locations 1 to 5; loads of 890 N at load point locations 6 to 10; and loads of 445 N at load point locations 11 to 15. These loads were applied in 25-percent increments from zero to the maximum value and removed in the same manner. The bridge outputs measured were then plotted as a function of applied load as a check to evaluate scatter and to insure that the bridge response was linear for all bridges and for all load points. The least-squares method was used to fit a straight line to the bridge output data. The slope of this line was used to calculate the bridge output for the maximum loading where it was assumed that the bridge output was zero for zero load.

The calculated bridge output values are presented in tables I, II, and III, as are the associated shear, bending-moment, and torque loads for the inboard, midwing, and outboard strain-gage stations, respectively. The shear loading is the same as the applied calibration load as long as the calibration load is applied outboard of the wing station of interest. Bending-moment loads are the product of the applied load and the y-distance from the point of load application to the wing station of interest. Torque loads are the product of the applied load and the x-distance to the point of load application. For the noninverted aircraft, loads applied upward on the wing outboard of the strain-gage bridge station of interest result in positive shear and positive bending-moment loads. Torque loads are considered positive if they produce an aircraft nose-down moment about the Y-axis. Calibration loads applied at load points inboard of the wing station of interest are considered as zero wingloads; however, the associated strain-gage bridge outputs were recorded as shown in tables II and III and are used in the appropriate regression analysis.

In general, for calibration loads applied outboard of the strain-gage bridge of interest, the bending-moment bridges responded with positive outputs, and the torque bridges responded with negative outputs. Notable exceptions to this pattern were the responses of bridges 4B and 5B to calibration loads applied at load points 3, 4, and 5, the responses of bridge 8B to loads at points 8, 9, and 10, and the responses of bridge 11B to loads at points 11 to 15. All these strain-gage bridges are located on the aft portion of the wing and possibly are affected by the notch or discontinuity at the inboard edge where the fuselage crossover section of the wing is much shorter in chord length than the exposed portion of the wing.

Multipoint loads. - The calibration procedure also included the application of multipoint loadings to the wing in two patterns of five load locations each. The first pattern (set A) used load point locations 1, 3, 6, 8, and 11, and the second pattern (set B) used load point locations 2, 4, 6, 10, and 12. Calibration loads were applied in increments of 667 N at locations 1, 2, 3, and 4, 445 N at locations 6, 8, and 10, and 222 N at locations 11 and 12. The maximum multipoint wing loading of 4893 N occurred when two increments of calibration load were applied at each load point location in the pattern. The loading step, the incremental applied load and its location, the resultant wing loadings, and the measured bridge outputs for these multipoint loadings are presented in tables IV to IX.

Load Equations

Load equations which give the applied wing loadings in terms of the output of selected strain-gage bridges were determined by means of the regression analysis method described in references 1 and 5. These load equations have the form:

where β_{ij} is the coefficient of the jth bridge for the ith load, and μ_j is the output of the jth bridge.

The regression analysis from which the coefficients β_{ij} are obtained can be performed using only one or as many of the available strain-gage bridges at each wing station as is desired. The regression analysis provides two statistical numbers which are useful in establishing which strain-gage bridge outputs should be used. One of these statistical numbers is the probable error of estimate of load. This number is essentially a measure of the scatter in the relationship between the selected strain-gage bridge outputs and the applied structural loads. The other statistical number is the estimate of probable error in each load coefficient. This value can be used to check for the inclusion of irrelevant or redundant bridges. In the initial evaluation it was observed that if a large number of strain-gage bridges were used, the probable error for the estimates of structural loads would be small but that the probable error for most of the load coefficients would be large. Large probable errors for load coefficients indicate the use of redundant strain-gage bridges. Generally, the use of more than three strain-gage bridges resulted in excessively large errors associated with one or more of the load coefficients.

For the single-point loading conditions (tables I, II, and III), load equations were derived for all possible combinations of one, two, and three strain-gage bridges for each of the strain-gage bridge semispan stations. (Bridges 11B and 11T at the outboard station were eliminated from consideration because of a limit on the number of telemetry channels available.) The resulting equations (175 combinations for the inboard station, 41 combinations for the midwing station, and 14 for the outboard station) were evaluated by using the probable error of the coefficients and the probable error of the estimates of the loads as criteria. The equations were also evaluated for their prediction of multipoint

wing-loading conditions for loading steps 6 to 15 of both set A and set B multipoint loading calibrations. The capability of the equations to predict the selected multipoint loading conditions is summarized in table X. The strain-gage bridges selected for use in each load measurement equation, the load coefficients established from the single-point load calibration, the associated probable errors for coefficients and estimates of loads, and the range of accuracy with which the equations could estimate the 20 selected multipoint loading conditions are presented in table XI.

Inboard strain-gage bridge station. - The wingloads at the inboard station can be measured more accurately for bending moment than for shear or torsion for this wing structure and for the arrangement of strain-gage bridges used. This capability is evidenced by the large number of combinations of bridges which can estimate multipoint bending-moment loading conditions accurately (table X) and the small probable error of load estimate for the bridge combination selected (table XI). The probable error of load estimate for the moment equation is less than ± 1 percent of the average applied calibration bending-moment load, and the selected equation was capable of estimating the bending moment loads applied during the multipoint loadings to within ± 3 percent.

For the torque load equation, the probable error of load estimate is ± 6 percent of the average applied calibration torque loading. The measured range of accuracy is slightly better at ± 5 percent.

For the shear load equation, the probable error of load estimate is ± 10 percent of the average applied calibration shear loading, and the measured range of accuracy is also ± 10 percent. This reduction in accuracy is not surprising since it was not possible to arrange strain-gage bridges specifically for the measurement of shear load as can be done for more conventional spar-stringer-rib structures.

Midwing strain-gage bridge station. - At the midwing station, the equation for determining bending-moment loads is again the most accurate as judged by both the probable error criteria and the measured range of accuracy. The probable error of load estimate is ± 5 percent of the average applied calibration bending-moment load, and the measured range of accuracy is ± 6 percent.

The equation for determining shear loads exhibited the same measured range of accuracy as for the inboard station (± 10 percent). However, the probable error of the load estimate is much larger at ± 19 percent of the average applied calibration shear load. The equation for determining torque loads has a probable error of estimate of ± 17 percent of the average applied calibration torque load and a measured range of accuracy of ± 14 percent.

Outboard strain-gage bridge station. - At the outboard station, the equation for determining torque load is the most accurate when evaluated by both the probable error criteria and the measured range of accuracy. The probable error of load estimate for the torque equation is ± 5 percent of the average applied calibration torque load, and the measured range of accuracy is ± 7 percent. The probable errors of load estimate for the shear and bending-moment loads are ± 45 percent and ± 5 percent of the average applied calibration shear and bending-moment loads, respectively. The measured range of accuracy of each equation is ± 13 percent.

There is some concern about the adequacy of the calibration procedure used for the outboard station. Reference 1 states that the calibration loads should be applied at various chordwise and spanwise locations. As shown in figure 3, there are five or more variations in location of calibration load points in the chordwise direction for each strain-gage bridge station. However, there is less variation in calibration load point locations in the span-wise direction. For the outboard strain-gage bridge station, all five calibration load points are located at the same spanwise station. Because there was no variation in the spanwise location of the applied calibration loads, the calibration for the outboard station is considered inadequate for shear and bending-moment loads, and the accuracies presented for these loads for the outboard station are considered questionable.

FLIGHT TEST

The instrumented wing was flight-tested on the Firebee II aircraft by personnel at the U.S. Naval Air Missile Test Center, Pt. Mugu, California. The flight was initiated by by a rocket-assisted ground launch similar to the arrangement shown in figure 5. The flight consisted of climbs, straight and level cruise, dives, pullups, and sustained, constantaltitude coordinated turns at aircraft normal load factors ranging from 2g to 6g.

The drone aircraft was equipped with a large jettisonable fuel tank located beneath the fuselage in the area of the wing (see fig. 1). The initial aircraft mass was 1002 kg including 157.4 kg of fuel in the external tank and 119.3 kg of fuel in the fuselage tank. The jettisonable external fuel tank had a mass of 28.8 kg. The total wing structure, as shown in figure 2, had a mass of approximately 67 kg with no fuel or other added mass in the wing. Useful test data were acquired over a Mach number range of 0.25 to 0.95 with the aircraft in the external-fuel-tank-on configuration and from 0.70 to 1.25 in the external-fuel-tank-off configuration. The data for the tank-on configuration are all in the subsonic range because the drone aircraft is limited to subsonic flight until after the external fuel tank is jettisoned. The drone aircraft flight was terminated by parachute recovery with final recovery being accomplished by a helicopter with a mid-air retrieval system (MARS). A photograph of the helicopter with the recovered drone aircraft is presented in figure 6. Information relating to the preparation for and the conduct of a similar flight test is presented in reference 7. Drone aircraft performance data and wing instrumentation measurements (differential pressure transducer and strain-gage bridge outputs) were telemetered to ground receiving stations using an FM/FM telemetry system. The aircraft performance data were monitored on a continuous basis, whereas the wing instrumentation data were commutated at a rate of 30 samples per second. Sample data records for a portion of the flight are presented in figure 7 to show how the measurements varied with time during a turn maneuver.

Flight measurements of wing structural loads are presented in this report as a function of onboard measurements of aircraft angle of attack, flight Mach number, and free-stream dynamic pressure. A vane-type sensor mounted on the nose boom (see fig. 1) measured the angle of attack with respect to the horizontal reference plane of the aircraft. Static and total pressures were measured by the side-mounted pitot static tube from which Mach number and impact pressure were determined by an onboard air data computer. These measurements, as recorded at the ground telemetry receiving stations, are considered accurate to ± 0.04 for Mach number, ± 3.4 kPa for impact pressure, and $\pm 0.6^{\circ}$ for angle of attack in the subsonic Mach number range (≤ 0.95) to $\pm 1.1^{\circ}$ in the transonic and supersonic Mach number range (>0.95). (These estimates of error include considerations of position error, instrument error, and telemetry error as applicable.) Dynamic pressures were calculated during the data reduction process by using the measured values of Mach number and impact pressure as inputs. During the flight test, when telemetry accuracy was included, the strain-gage bridge measurements were accurate from 0.05 to 0.15 mV depending on the measurement range for each bridge. The straingage bridge output measurements recorded during the calibration procedures are considered accurate to ± 0.003 mV.

RESULTS AND DISCUSSION

Wing structural loads measurements were obtained during the flight test by means of the calibrated strain-gage bridges on the left wing of the aircraft. These results are presented in figures 8 and 9. Figures 8 and 9 also show, for a few selected test conditions, wing loads as determined from integration of differential pressure distributions measured on the right wing. Theoretical predictions of wing structural loads for the external-fueltank-off aircraft configuration are also shown in the appropriate figures. Although direct comparisons between measured and theoretical results are made, this report does not evaluate any differences which may exist. Details of the results obtained are presented in the following sections.

Wingloads From Strain-Gage Bridge Measurements

The load coefficients presented in table X were used with the bridge outputs measured during the flight test to determine the wing structural loads; i.e., shear (V), bending moment (M), and torque (T). These measured loads are presented in figure 8 for the external-fuel-tank-on aircraft configuration and in figure 9 for the external-fuel-tank-off aircraft configuration. The wing structural loads are presented as a ratio to the instantaneous free-stream dynamic pressure and as a function of aircraft angle of attack for various Mach number regions for the inboard, midwing, and outboard strain-gage bridge stations. The data symbols shown represent measurements taken at a rate of one to six samples per second. For both aircraft configurations (that is, tank-on or tank-off), there is essentially a linear relationship between the measured wing structural load ratios and the aircraft angle of attack (over the test range of angles of attack) for each of the Mach number ranges shown. The straight line represents the best fit to the data using a least-squares analysis method. The number of samples included and the dynamic pressure range over which each set of data was obtained are noted in the figures.

Data presented for angles of attack from 2.0° to 2.5° generally represent straight and level flight. For angles of attack from 2.5° to 3.5° , the data generally represent pullup and climb maneuvers, and for angles of attack greater than 3.5° , the data generally represent measurements taken during turn maneuvers. No attempts were made to differentiate between the measurements taken during steady conditions and the measurements taken at more transient conditions such as rapid changes in pitch or roll angles.

In figure 8 (for the tank-on aircraft configuration), all measured data are presented. In figure 9 (for the tank-off configuration), the data presented include only those measurements obtained when the free-stream dynamic pressure was less than 24 kPa. This limitation was imposed to reduce the effect of wing aeroelasticity on the results for the tankoff configuration. A further discussion of aeroelastic effects is presented in a later section.

The results of the strain-gage bridge measurements of wing structural loads presented in figures 8 and 9 are summarized in figure 10. Figure 10 presents the variation with Mach number of the slope and the intercept of the least-squares straight-line fit to the measured data for both the tank-on and the tank-off aircraft configurations. The data points shown in figure 10 are only for those Mach number conditions where data were available in figures 8 and 9 for an angle-of-attack range equal to or greater than 3⁰. For bending-moment loads, there is little variation of slope with change in Mach number or aircraft configuration, but there is a large change in the intercept angle with changes in aircraft configuration and changes in Mach number, particularly in the transonic speed range. For shear and torsion loads, there is some variation of slope with Mach number variation but essentially no difference in slope due to configuration changes. There are, however, large changes in intercept which occur because of both Mach number and configuration changes.

Wingloads From Measured Pressure Distributions

In addition to the instrumentation of the left semispan of the test wing (22 straingage bridges), instrumentation was installed on the right semispan to measure differential pressure at 29 locations. The results from these pressure measurements are reported in reference 6. For 13 of these test conditions, the chordwise differential pressure distributions, at semispan locations of 0.343, 0.802, and 1.306 m, were integrated to determine the normal (shear) force per unit width at each location. These values of normal force were plotted as a function of semispan location, and a curve was fitted to the data with the additional boundary condition that the normal force must be zero at the semispan tip. The area and the first moment of the area under each curve from the tip to each of the strain-gage bridge stations were then determined. These calculations gave the equivalent shear and bending moment at each strain-gage bridge station. The locations of the chordwise center of pressure, as a function of the semispan location, were also established from the measurements of differential pressures. These locations allowed determination of torque loads. The aerodynamic load from the pressure distribution is essentially the net load because the inertia loads are very small in comparison (that is, the weight of the wing is small in relation to the total weight of the aircraft).

The wingloads, shear (V), bending moment (M), and torque (T), as determined by use of pressure measurements, are shown in figures 8(e), 9(e), and 9(g) as are the loads measured by the calibrated strain-gage bridges. In most instances, there is good agreement between the two types of measurements. Although there was some concern about the adequacy of the strain-gage bridge calibration for the outboard station, the excellent agreement in loads measured by the two methods gives increased confidence in the strain-gage bridge calibration procedures used.

Wingloads From Calculated Pressure Distributions

Theoretical predictions of wing shear, moment, and torque loads as a function of angle of attack for each of the three wing stations were obtained for a limited number of Mach number values by the integration of calculated wing aerodynamic pressure distributions. The pressure distributions were calculated for a rigid structure by using the finite-element analysis method described in reference 8. The aerodynamic paneling scheme used for the analysis is shown in figure 11. The fuselage was represented as a cone cylinder, considered representative of the external-fuel-tank-off aircraft configuration. The analysis method used did not have provisions for properly modeling the external-fuel-tank-on aircraft configuration. The theoretical predictions of wing structural loads are presented in figure 9 (except for the transonic range) as are the measured wing structural loads in order to allow for direct comparisons with the measured values of loads for the tank-off aircraft configuration. For the bending-moment loads, the measured values at the inboard station are greater than the theoretical estimates. For the midwing and the outboard wing stations, the theoretical estimates for bending-moment loads are in close agreement with measured values. In all cases, the measured shear and torque loads are greater than the theoretical estimates.

Aeroelastic Effects on Wingloads

The standard wing for the drone aircraft is a relatively rigid structure because of its design load value (5g), construction method, and low aspect ratio. Even so, aeroelastic effects (structural deformation caused by applied aerodynamic loads) were anticipated. Sufficient data at significantly different dynamic pressure levels were available to evaluate aeroelastic effects at Mach numbers of 1.00 ± 0.025 for the tank-off aircraft configuration. Figure 12 presents the data for loads measurements obtained in this Mach number interval for both low and high levels of dynamic pressure. The lower level includes measurements acquired at dynamic pressures ranging between 13.5 and 18.5 kPa (identical to fig. 9(g)). The higher level includes measurements acquired at dynamic pressures ranging between 28.9 and 39.6 kPa. There is a more than a two to one difference in the midpoint dynamic pressure for the two ranges.

As indicated by figure 12, the largest aeroelastic effect occurs at the outboard wing station where there is a large change in the slopes for the load measurements. At the midwing station there is also a significant change in slope for the loads measurements. At the inboard station the torque load measurements still indicate a change in slope, whereas for shear and moment loads the primary difference between measurements obtained at low and high levels of dynamic pressure is in the intercept value and not in the slope changes.

Although some measurements were available at the high dynamic pressure level for other Mach numbers, there was insufficient data to establish trends. As mentioned earlier, the data presented in figure 9 were limited to values obtained at dynamic pressures of less than 24 kPa.

Comparison With Previous Measurements

Flight loads measurements obtained from calibrated strain-gage bridges were previously obtained on an identical wing for a single wing station with the reference axis system oriented parallel and perpendicular to the wing 40-percent chord line as reported in reference 5. The differences in axis system orientation and the noncoincidence of wing stations between the wing of reference 5 and that of the present report preclude an accurate direct comparison of measured loads. However, an indirect comparison of the measured loads can be obtained by considering the respective agreements between measured and

calculated loads for the two sets of data. Although different numbers and arrangements of panels were used for the respective calculations, the calculated load distributions were essentially the same.

The data from reference 5 indicate close agreement between measured and calculated values of shear, bending moment, and torque loads for the tank-off configuration at a Mach number of 0.8 (subsonic) and a Mach number of 1.2 (supersonic). The data presented in this report show fair to good agreement between measured and calculated values for a Mach number of 1.2 (fig. 9(k)). For a Mach number of 0.8 (fig. 9(c)) and for all subsonic speeds for which data were obtained, the measured data for angles of attack from 1° to 3° are generally in close agreement with calculated values; however, the data points obtained at higher angles of attack indicate substantially higher loads than calculated, particularly at the inboard station. The differences in slope between the measured and calculated loads are approximately 30 percent at the inboard station. Thus, the measured values of loads as presented in this report for subsonic conditions may be assumed to be higher than those of reference 5.

Although the evidence is not conclusive, some of the differences between the results of reference 5 and the results in this report may be caused by aeroelastic effects. It is noted that the test dynamic pressure range was relatively low and similar for the flights of both wings at a Mach number of 1.2, whereas the dynamic pressures at a Mach number of 0.8 for the reference 5 test conditions were approximately twice those for the data presented in this report.

CONCLUDING REMARKS

A low-aspect-ratio, thin, swept wing with a structural skin, full-depth honeycomb core construction was instrumented with strain-gage bridges mounted externally on the wing surface at three spanwise stations. The wing calibration procedure consisted of applying calibration loadings to the wing and measuring the electrical imbalance, or output, of the strain-gage bridges. Linear regression analysis techniques were then used to derive load coefficients for equations which gave the applied wing loadings as a function of the output of selected strain-gage bridges. Flight-test measurements of strain-gage bridge outputs were then used to compute the measured wing structural loads. Evaluation of the calibration procedure and comparison of the test results with pressure measurements and theoretical calculations indicate the following:

1. The statistical evaluation of errors provided by the regression analysis was useful in determining which strain-gage bridge outputs should be used for load equations.

2. The use of more than three strain-gage bridges in any load equation generally resulted in large errors associated with one or more of the load coefficients.

3. Evaluation of all possible combinations of one, two, or three strain-gage bridges for load equations allowed selection based on accuracy of both the probable error criteria and the measured range of accuracy.

4. The measured range of accuracy for the selected load equations, as determined by their capability to estimate multipoint calibration loadings, varied from ± 3 percent for bending-moment loads at the inboard station to ± 14 percent for torque loads at the midwing station.

5. The slope of the linear relationship between structural load and angle of attack was essentially the same for both aircraft configurations (that is, external fuel tank on or external fuel tank off).

6. For each wing station, the slope of the linear relationship between structural load and angle of attack changed very little for bending-moment loads over the Mach number range tested, but there were small changes in slope with Mach number for shear and torsion loads.

7. There are significant differences in the angle of attack at zero wing loading (shear, bending moment, and torsion) between aircraft configurations and also for variations in Mach number in the transonic speed range.

8. Flight loads as determined from measurements of differential pressure on the opposite wing semispan were in reasonable agreement with those determined from the strain-gage bridge measurements.

9. Theoretical estimates of wingloads from an aerodynamic finite-element analysis method were lower than the measured values in most cases.

10. Measured aeroelastic effects indicated a trend to lower structural load ratios at higher dynamic pressures, a trend which is in agreement with theoretical analysis.

Langley Research Center National Aeronautics and Space Administration Hampton, VA 23665 November 22, 1976

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	Calibration		Wing load	ing	Strain-gage bridge output, mV, for –									
Load point	load, N	Shear, N	Bending moment, N-m	Torque, N-m	^μ 1Β	$^{\mu}2\mathrm{B}$	^µ 3В	$\mu_{4\mathrm{B}}$	μ_{5B}	^μ 1Τ	^μ 2Τ	μ_{3T}	^μ 4Τ	$\mu_{5\mathrm{T}}$
1	1246	1246	237	141	0.270	0.294	0.277	0.061	0.012	-0.105	-0.015	-0.012	-0.036	-0.002
2	1246	1246	237	387	.222	.267	.309	.041	.001	143	213	164	090	013
3	1246	1246	237	632	.180	.230	.262	006	037	171	303	410	184	030
4	1246	1246	237	897	.142	.202	.200	096	099	205	406	597	429	077
5	1246	1246	237	1124	.106	.167	.159	207	153	243	516	813	612	370
6	890	890	452	435	.293	.438	.608	.215	.078	236	381	416	310	075
7	890	890	452	570	.266	.406	.585	.203	.086	255	450	562	443	136
8	890	890	452	705	.240	.376	.551	.178	.097	274	513	699	583	215
9	890	890	452	840	.214	.348	.521	.147	.107	290	574	830	720	307
10	890	890	452	975	.189	.321	.488	.116	.114	311	642	964	858	402
11	445	445	339	351	.179	.286	.447	.196	.107	179	324	416	366	125
12	445	445	339	402	.166	.275	.430	.184	.110	185	346	467	418	159
13	445	445	339	454	ⁱ .158	.268	.421	.175	.115	193	371	518	472	192
14	445	445	339	505	.149	.254	.409	.164	.121	201	396	572	526	227
15	445	445	339	556	.138	.242	.397	.153	.124	208	419	620	575	258

TABLE I. - CALIBRATION WING LOADINGS AND STRAIN-GAGE BRIDGE OUTPUTS FOR INBOARD STATION

	Calibustian		Wind loadi	ng	Stra	in-gage	bridge	output,	mV, for	· - ·
Load point	load, N	Shear, N	Bending moment, N-m	Torque, N-m	^μ 6Β	^μ 7Β	^μ 8Β	^μ 6τ	^μ 7Τ	^μ 8Τ
1	1246	0	0	0	-0.003	0.001	0.003	0.001	0.006	0.002
2	1246	0	0	0	.034	009	008	019	013	003
3	1246	0	0	0	.018	029	030	062	049	008
4	1246	0	0	0	018	090	046	155	.009	004
5	1246	0	0	0	113	264	.130	278	.024	.303
6	890	890	113	435	.386	.159	.036	159	034	009
7	890	890	113	570	.282	.161	.011	364	183	048
8	890	890	113	705	.227	.135	067	453	374	114
9	890	890	113	840	.162	.048	137	556	256	294
10	890	890	113	975	.088	024	308	662	796	608
11	445	445	170	351	.296	.378	.181	365	330	128
12	445	445	170	402	.255	.343	.181	404	429	209
13	445	445	170	454	.226	.318	.194	446	528	309
14	445	445	170	505	.192	.287	.192	488	622	419
15	445	445	170	556	.159	.254	.185	526	708	522

TABLE II.- CALIBRATION WING LOADINGS AND STRAIN-GAGE BRIDGE OUTPUTS FOR MIDWING STATION

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	Calibration		Wing lo	ading	Strain-gage bridge output, mV, for -						
Load point	Calibration load, N	Shear, N	Bending moment, N-m	Torque, N-m	^μ 9Β	^μ 10Β	μ _{11B}	μ ₉ Τ	^μ 10T	^μ 11T	
1	1246	0	0	0	0.000	0.000	-0.000	-0.001	0.000	0.000	
2	1246	0	0	0	.002	001	002	002	.001	.000	
3	1246	0	0	0	.006	002	003	003	005	.000	
4	1246	0	0	0	007	002	.000	003	.003	.000	
5	1246	0	0	0	071	002	.050	017	.060	.026	
6	890	0	0	0	.000	001	002	.003	.003	.001	
7	890	0	0	0	.062	017	010	038	016	.000	
8	890	0	0	0	.039	047	050	095	092	020	
9	890	0	0	0	.006	113	100	145	006	040	
10	890	0	0	0	104	306	.080	389	037	.394	
11	445	445	56.5	351	.370	.188	.046	166	070	018	
12	445	445	56.5	402	.265	.179	.022	299	203	063	
13	445	445	56.5	454	.229	.170	019	382	397	127	
14	445	445	56.5	505	.175	.094	055	475	528	321	
15	445	445	56.5	556	.120	.033	176	559	656	564	

TABLE III.- CALIBRATION WING LOADINGS AND STRAIN-GAGE BRIDGE OUTPUTS FOR OUTBOARD STATION

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			Wing loading					Strain-gage bridge output, mV, for -									
Loading step	Incremental applied load, N	Location	Shear, N	Bending moment, N-m	Torque, N-m	^μ 1Β	^μ 2Β	^μ 3Β	^μ 4Β	^μ 5Β	^μ 1Τ	^μ 2Τ	^μ 3Τ	μ ₄ Τ	μ_{5T}		
1	667	1	667	127	76	0.147	0.158	0.145	0.034	0.005	-0.050	0.004	-0.002	-0.019	-0.001		
2	667	3	1335	254	414	.244	.283	.284	.029	016	142	155	223	117	017		
3	444	6	1779	480	631	.396	.512	.592	.133	.022	259	347	433	277	062		
4	444	8	2224	706	984	.515	.704	.863	.222	.071	394	597	787	565	168		
5	222	11	2446	876	1160	.607	.850	1.082	.315	.125	487	760	-1.004	744	230		
6	667	1	3114	1003	1236	.774	1.019	1.239	.348	.133	542	748	-1.008	761	231		
7	667	3	3781	1130	1574	.881	1.149	1.386	.346	. 115	638	913	-1.238	857	245		
8	444	6	4226	1356	1791	1.045	1.376	1.704	.459	.159	765	-1.105	-1.453	-1.011	281		
9	444	8	4671	1582	2144	1.176	1.566	1.981	.547	.213	907	-1.362	-1.809	-1.293	384		
10	222	11	4893	1751	2320	1.272	1.714	2.209	.646	.270	-1.000	-1.526	-2.024	-1.474	445		
11	-667	1	4226	1624	2244	1.118	1.543	2.049	.606	.261	951	-1.540	-2.029	-1.456	443		
12	-667	3	3559	1497	1906	1.024	1.414	1.893	.603	.272	864	-1.386	-1.809	-1.362	432		
13	-444	6	3114	1271	1689	.877	1.185	1.570	.486	.228	749	-1.204	-1.600	-1.209	395		
14	-444	8	2670	1045	1336	.761	.994	1.285	.394	.176	618	958	-1.252	923	292		
15 ·	-222	11	2447	875	1160	.669	.848	1.059	.297	.120	525	797	-1.039	742	231		
16	-667	1	1779	749	1084	.521	.690	.907	.265	.112	474	806	-1.040	726	230		
17	-667	3	1112	621	746	.423	.563	.766	.270	.132	380	645	814	629	215		
18	-444	6	667	395	529	.273	.340	.460	.166	.093	256	457	599	477	176		
19	-444	8	222	169	176	.134	.151	.200	.087	.048	105	190	229	190	067		
20	-222	11	0	0	0	.019	.006	008	004	004	.003	011	~.009	009	004		

TABLE IV. - INBOARD STATION WING LOADINGS AND STRAIN-GAGE BRIDGE OUTPUTS

FOR MULTIPOINT LOADING CALIBRATION SET A

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TABLE V.- MIDWING STATION WING LOADINGS AND STRAIN-GAGE BRIDGE OUTPUTS

				Wing loadin	ng	Stra	in-gage	bridge	output, 1	mV, for	-
Loading step	Incremental applied load, N	Location	Shear, N	Bending moment, N-m	Torque, N-m	^μ 6Β	^μ 7Β	^μ 8Β	^μ 6τ	^μ 7τ	^μ 8τ
1	667	1	0	0	0	-0.002	0.001	0.002	0.001	0.002	0.001
2	667	3	0	0	0	.008	014	015	030	023	004
3	444	6	445	56.5	217.5	.205	.065	.005	108	035	004
4	444	8	889	112.9	570.0	.319	.128	030	331	249	058
5	222	11	1112	197.5	745.6	.466	.315	.058	514	414	124
6	667	1	1112	197.5	745.6	.464	.318	.061	511	409	124
7	667	3	1112	197.5	745.6	.475	.302	.045	544	438	130
8	444	6	1557	254.0	963.1	.695	. 393	.068	620	451	135
9	444	8	2001	310.5	1315.5	.815	.467	.039	848	669	190
10	222	11	2224	395.1	1491.1	.967	.662	.135	-1.037	842	258
11	-667	1	2224	395.1	1491.1	.967	.658	.131	-1.043	848	260
12	-667	3	2224	395.1	1491.1	.956	.673	.146	-1.009	818	255
13	-444	6	1779	338.6	1273.6	.736	.580	.121	932	803	252
· 14	-444	8	1335	282.1	921.2	.619	.510	.152	706	586	196
15	-222	11	1112	197.5	745.6	.469	.316	.059	520	415	130
16	-667	1	1112	197.5	745.6	.469	.314	.056	522	419	131
17	-667	3	1112	197.5	745.6	.460	.330	.074	488	391	126
18	-444	6	667	141.0	528.0	.259	.247	.053	413	377	123
19	-444	8	222	84.5	175.6	.147	.187	.089	186	162	068
20	-222	11	0	0	0	.001	0	.001	001	.004	003

FOR MULTIPOINT LOADING CALIBRATION SET A

.

			I	Wing loading	ng	Strai	n-gage	bridge	output	t, mV, :	for –
Loading step	Incremental applied load, N	Location .	Shear, N	Bending moment, N-m	Torque, N-m	^μ 9Β	^μ 10Β	^μ 11Β	μ ₉ Τ	^μ 10τ	^μ 11Τ
1	667	1	0	0	0	0	0.001	0	0	0	0.001
2	667	3	0	0	0	.003	0	002	002	003	0
3	444	6	0	0	0	.003	.001	002	.005	.003	.004
4	444	8	0	0	0	.023	021	027	040	039	004
5	222	11	222	84.6	175.6	.203	.071	005	128	075	012
6	667	1	222	84.6	175.6	.202	.071	005	129	075	012
7	667	3	222	84.6	175.6	.206	.071	007	132	072	013
8	444	6	222	84.6	175.6	.205	.072	005	126	075	011
9	444	. 8	222	84.6	175.6	.226	.049	031	172	121	022
10	222	11	445	169.2	351.2	.419	.152	005	264	161	033
11	-667	1	445	169.2	351.2	.419	.151	006	266	162	-:034
12	-667	3	445	169.2	351.2	.415	.152	005	264	158	033
13	-444	6	445	169.2	351.2	.416	.149	006	269	162	032
14	-444	8	445	169.2	351.2	.395	.173	.019	223	114	022
15	-222	11	222	84.6	175.6	.204	.072	006	132	074	012
16	-667	1	222	84.6	175.6	.204	.070	007	132	076	012
17	-667	3	222	84.6	175.6	.201	.072	004	130	071	011
18	-444	6	222	84.6	175.6	.201	.071	006	133	075	011
19	-444	8	222	84.6	175.6	.181	.093	.020	087	031	003
20	-222	11	0	0	0	.001	.001	002	.001	005	.007

TABLE VI. - OUTBOARD STATION WING LOADINGS AND STRAIN-GAGE BRIDGE OUTPUTS

FOR MULTIPOINT LOADING CALIBRATION SET A

.

			V	Wing loadi	ng	Strain-gage bridge output, mV, for -										
Loading step	Incremental applied load, N	Location	Shear, N	Bending moment, N-m	Torque, N-m	^μ 1Β	^μ 2Β	^µ 3в	^μ 4Β	^μ 5Β	^μ 1Τ	^μ 2Τ	^μ 3τ	^μ 4τ	μ _{5T}	
1	667	2	667	127	207	0.115	0.142	0.164	0.022	-0.001	-0.075	-0.112	-0.086	-0.047	-0.006	
2	667	4	1335	254	678	.194	.248	.266	036	055	186	327	404	277	041	
3	444	6	1779	480	895	.339	.465	.570	.070	017	303	518	615	437	075	
4	444	10	2224	706	1383	.450	.624	.803	.123	.040	469	851	-1.106	861	271	
5	222	12	2446	876	1584	.555	.762	1.004	.206	.097	578	-1.034	-1.352	-1.063	343	
6	667	2	3114	1003	1791	.689	.920	1.180	.232	.099	665	-1.150	-1.445	-1.117	348	
7	667	4	3781	1130	2262	.782	1.032	1.278	.172	.054	795	-1.377	-1.783	-1.337	381	
8	444	6	4226	1356	2479	.945	1.256	1.581	.279	.097	927	-1.571	-2.000	-1.488	418	
' 9	444	10	4671	1582	2967	1.048	1.419	1.819	.329	.164	-1.077	-1.902	-2.500	-1.899	609	
10	222	12	4893	1751	3168	1.136	1.557	2.028	.413	.223	-1.179	-2.083	-2.742	-2.098	682	
11	-667	2	4226	1624	2960	1.023	1.398	1.839	.379	.216	-1.107	-1.979	-2.655	-2.049	676	
12	-667	4	3559	1497	2490	.953	1.289	1.720	.426	.256	-1.001	-1.770	-2.331	-1.826	643	
13	-444	6	3114	1271	2273	.809	1.065	1.406	.314	.213	887	-1.587	-2.120	-1.673	607	
14	-444	10	2670	1045	1785	.720	.905	1.157	.256	.145	735	-1.274	-1.635	-1.256	416	
15	-222	12	2447	875	1584	.637	.769	.943	.168	.088	643	-1.105	-1.401	-1.053	341	
16	-667	2	1779	749	1377	.519	.624	.776	.148	.087	567	992	-1.312	-1.007	336	
17	-667	4	1112	621	906	.443	.517	.671	.206	.138	454	778	990	784	303	
18	-444	6	667	395	689	.294	.295	.373	.104	.101	331	588	771	633	265	
19	-444	10	222	169	201	.180	.131	.145	.058	.046	159	255	264	212	066	
20	-222	12	0	0	0	.071	[;] 008	050	023	007	047	061	010	006	.012	

TABLE VIL - INBOARD STATION WING LOADINGS AND STRAIN-GAGE BRIDGE OUTPUTS

FOR MULTIPOINT LOADING CALIBRATION SET B

TABLE VIIL- MIDWING STATION WING LOADINGS AND STRAIN-GAGE BRIDGE OUTPUTS

			Ţ	Wing loadi	ng	Str	ain-gag	e bridge	e output,	mV, fo	r —
Loading step	Incremental applied load, N	Location	Shear, N	Bending moment, N-m	Torque, N-m	^µ 6В	^μ 7Β	μ _{8Β}	^µ 6Т	μ_{7T}	^μ 8τ
1	667	2	0	0	0	0.018	-0.005	-0.004	-0.012	-0.007	0
2	667	4	0	0	0	.008	052	028	092	001	004
3	444	6	445	56.5	217.5	.196	.024	010	173	018	010
4	444	. 10	889	112.9	705.0	.240	.011	166	504	412	309
5	222	12	1112	197.5	906.3	.368	.182	075	706	279	414
6	667	2	1112	197.5	906.3	.386	.177	078	720	636	418
7	667	4	1112	197.5	906.3	.377	.128	103	806	632	424
8	444	6	1557	254.0	1123.8	.582	.212	083	889	648	431
9	444	10	2001	310.5	1611.3	.627	.201	233	-1.227	-1.051	738
10	222	12	2224	395.1	1812.5	.754	.371	142	-1.430	-1.266	845
11	-667	2	2224	395.1	1812.5	.736	.375	140	-1.415	-1.260	845
12	-667	4	2224	395.1	1812.5	.746	.425	115	-1.328	-1.265	838
13	-444	6	1779	338.6	1595.0	.540	.338	137	-1.246	-1.250	833
14	-444	10	1335	282.1	1107.5	.497	.349	.013	912	847	524
15	-222	12	1112	197.5	906.3	.371	.181	075	712	634	421
1 6	-667	2	1112	197.5	906.3	.352	.186	072	699	627	420
17	-667	4	1112	197.5	906.3	.362	.232	048	618	633	415
18	-444	6	667	141.0	688.7	.173	.155	066	536	616	410
19	-444	10	222	84.5	201.3	.128	.168	.089	204	220	110
20	-222	12	0	0	0	.001	003	0	002	004	006

FOR MULTIPOINT LOADING CALIBRATION SET B

TABLE IX. - OUTBOARD STATION WING LOADINGS AND STRAIN-GAGE BRIDGE OUTPUTS FOR MULTIPOINT LOADING CALIBRATION SET B

			ł	V	Wing loading	Strain-gage bridge output, mV, for -						
	oading step	Incremental applied load, N	Location	Shear, N	Bending moment, N-m	Torque, N-m	^μ 9Β	^μ 10Β	^μ 11Β	^μ 9τ	^μ 10τ	^μ 11Τ
	1	667	2	0	0	0	0.001	-0.002	-0.001	-0.002	-0.001	0
	2	667	4	0	0	0	004	001	001	004	001	002
	3	444	6	0	0	0	004	0	001	003	.001	002
	4	444	10	0	0	0	054	150	.036	194	017	.190
	5	222	12	222	84.6	201.3	.077	062	.047	344	122	.156
	6	667	2	222	84.6	201.3	.077	063	.045	347	126	.154
	7	667	4	222	84.6	201.3	.073	063	.045	349	126	.153
	8	444	6	222	84.6	201.3	.073	062	.046	346	123	.154
	9	444	10	222	84.6	201.3	.073	219	.084	547	148	.373
	10	222	12	445	169.2	402.6	.020	136	.092	695	249	.345
	11	-667	2	445	169.2	402.6	.148	136	.093	694	248	.344
	12	-667	4	445	169.2	402.6	.147	136	.094	691	248	.345
	13	-444	6	445	169.2	402.6	.152	138	.094	694	251	.343
1	14	-444	10	445	169.2	402.6	.205	.019	.056	494	226	.124
	15	-222	12	222	84.6	201.3	.078	063	.047	347	126	.153
	16	-667	2	222	84.6	201.3	.077	062	.048	345	126	.152
	17	-667	4	222	84.6	201.3	.081	063	.049	343	i 127	.152
	18	-444	6	222	84.6	201.3	.080	063	.049	345	129	.151
	19	-444	10	222	84.6	201.3	.131	.087	.009	152	112	041
	20	-222	12	0	0	0	001	001	001	003	009	009

TABLE X. - SUMMARY OF CAPABILITY OF LOAD EQUATIONS (BASED ON POINT LOAD CALIBRATION DATA) TO ESTIMATE 20 MULTIPOINT LOADING CONDITIONS

Range of ratios of estimated to actual load	Number of combinations capable of estimating loads in each range			
	Shear load	Bending-moment load	Torsion load	
0.95 to 1.05	0	29	1	
0.90 to 1.10	9	70	13	
0.80 to 1.20	43	116	75	
0.70 to 1.30	89	154	121	
<0.70 or >1.30	86	21	54	

(a) Inboard station: (175 possible combinations using 1, 2, or 3 of 10 strain-gage bridges)

(b) Midwing station: (41 possible combinations using 1, 2, or 3 of 6 strain-gage bridges)

Range of ratios of estimated to actual load	Number of combinations capable of estimating loads in each range			
	Shear load	Bending-moment load	Torsion load	
0.95 to 1.05	0	1	0	
0.90 to 1.10	3	2	0	
0.80 to 1.20	8	12	11	
0.70 to 1.30	12	17	19	
<0.70 to >1.30	29	24	22	

(c) Outboard station: (14 possible combinations using 1 or 2 of 4 strain-gage bridges)

Range of ratios of estimated to actual load	Number of combinations capable of estimating loads in each range			
	Shear load	Bending-moment load	Torsion load	
0.95 to 1.05	0	0	0	
0.90 to 1.10	0	0	2	
0.80 to 1.20	1	1	3	
0.70 to 1.30	3	3	3	
<0.70 or >1.30	11	11	11	

TABLE XL - SUMMARY OF SELECTED STRAIN-GAGE BRIDGES, LOAD COEFFICIENTS,

Load measurement	Selected bridges	Load coefficient ± probable error	Average wing calibration loading	Probable error of load estimate	Measured range of accuracy, percent (a)	
Inboard station						
v	2B	4894 ± 218	860 N	±85 N	±10	
	4B	-4129 ± 236				
	3Т	292 ± 88				
М	2 B	528 ± 16	343 N-m	±2.5 N-m	±3	
	3B	277 ± 12				
	4T	-174 ± 3				
T	3B	388 ± 62	598 N-m	±33 N-m	±5	
	5B	-1947 ± 136	1			
	3Т	-998 ± 36				
	·	Midwing	station			
v	6B	1445 ± 258	667 N	±130 N	±10	
	6Т	-1215 ± 253				
	7т	483 ± 225				
М	6B	89 ± 22	142 N-m	±7 N-m	±6	
	7B	218 ± 17				
	6Т	-173 ± 7				
Т	6B	519 ± 196	579 N-m	±99 N-m	±14	
	6Т	-1028 ± 102	I			
Outboard station						
v	10B	1276 ± 63	44.5 N	±23 N	±13	
	9Т	-935 ± 59				
	10 T	220 ± 66				
М	10B	162 ± 8	56.5 N-m	±3 N-m	±13	
	9Т	-118 ± 7				
	10 T	2 8 ± 8				
т	10B	968 ± 51	454 N-m	±19 N-m	±7	
	9 T	-684 ± 48				
	10 T	-171 ± 54				

PROBABLE ERRORS, AND ACCURACY EVALUATION FOR WING STATIONS

^a Accuracy of load equations in estimating multipoint loading conditions 6 to 15 of both sets A and B.



Figure 1.- Three views of test vehicle. Dimensions are in meters.



Figure 2.- Upper surface of test wing before strain-gage bridge protective coatings were applied. (Wing tip section removed.)



Figure 3.- Calibration load point and strain-gage bridge locations.



Figure 4.- Single-point calibration loading with aircraft in inverted position.



Figure 5.- Arrangement for rocket-assisted ground launch of drone aircraft.



Figure 6.- Drone aircraft suspended beneath helicopter used for mid-air retrieval system (MARS) recovery.



Figure 7.- Sample record of flight measurements (externalfuel-tank-on aircraft configuration).



Figure 7.- Continued.

Figure 7.- Concluded.

(a) Mach numbers 0.25 to 0.75; 7.5 kPa < q_{∞} < 33.2 kPa; 174 samples. Figure 8.- Flight-test measurements of wing structural loads for tank-on aircraft configuration.

Figure 8.- Continued.

(c) Mach numbers 0.80 \pm 0.025; 37.6 kPa < $q_{\infty} <$ 45.0 kPa; 133 samples. Figure 8.- Continued.

(d) Mach numbers 0.85 \pm 0.025; 34.1 kPa < $q_{\infty} <$ 46.6 kPa; 108 samples. Figure 8.- Continued.

(e) Mach numbers 0.90 \pm 0.025; 28.8 kPa < $q_{\infty} <$ 51.0 kPa; 382 samples. Figure 8.- Continued.

(f) Mach numbers 0.95 \pm 0.025; 19.4 kPa < $q_{\infty} <$ 52.3 kPa; 205 samples. Figure 8.- Concluded.

(a) Mach numbers 0.70 ± 0.025 ; 13.2 kPa < q_{∞} < 16.0 kPa; 38 samples. Figure 9.- Flight-test measurements of wing structural loads for the tank-off aircraft configuration.

(b) Mach numbers 0.75 \pm 0.025; 13.9 kPa < $q_{\infty} <$ 17.3 kPa; 24 samples. Figure 9.- Continued.

(c) Mach numbers 0.80 \pm 0.025; 15.1 kPa < q_{∞} < 21.1 kPa; 32 samples. Figure 9.- Continued.

(d) Mach numbers 0.85 \pm 0.025; ~ 17.4 kPa < q_{_{\infty}} < 23.7 kPa; 97 samples. Figure 9.- Continued.

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Figure 9.- Continued.

(f) Mach numbers 0.95 \pm 0.025; 14.0 kPa < $q_{\infty}^{} <$ 19.7 kPa; 52 samples. Figure 9.- Continued.

(g) Mach numbers 1.00 \pm 0.025; 13.5 kPa < $\rm q_{\infty} <$ 18.5 kPa; 77 samples. Figure 9.- Continued.

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(h) Mach number 1.05 \pm 0.025; 16.0 kPa < q_{∞} < 19.2 kPa; 84 samples. Figure 9.- Continued.

(i) Mach numbers 1.10 \pm 0.025; 13.2 kPa < q_{∞} < 21.5 kPa; 190 samples. Figure 9.- Continued.

(j) Mach numbers 1.15 \pm 0.025; 14.1 kPa < $q_{_\infty} <$ 23.2 kPa; 125 samples. Figure 9.- Continued.

Figure 9.- Continued.

(1) Mach numbers 1.25 \pm 0.025; 16.5 kPa < $q_{\infty} <$ 20.3 kPa; 41 samples. Figure 9.- Concluded.

(a) Shear.

Figure 10.- Variation of wingload slope and intercept with Mach number.

(b) Bending moment.

Figure 10.- Continued.

(c) Torsion.

Figure 10.- Concluded.

Figure 11.- Mathematical model of research vehicle.

Figure 12.- Differences in wingloads for high and low levels of flight dynamic pressure, inboard station.

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