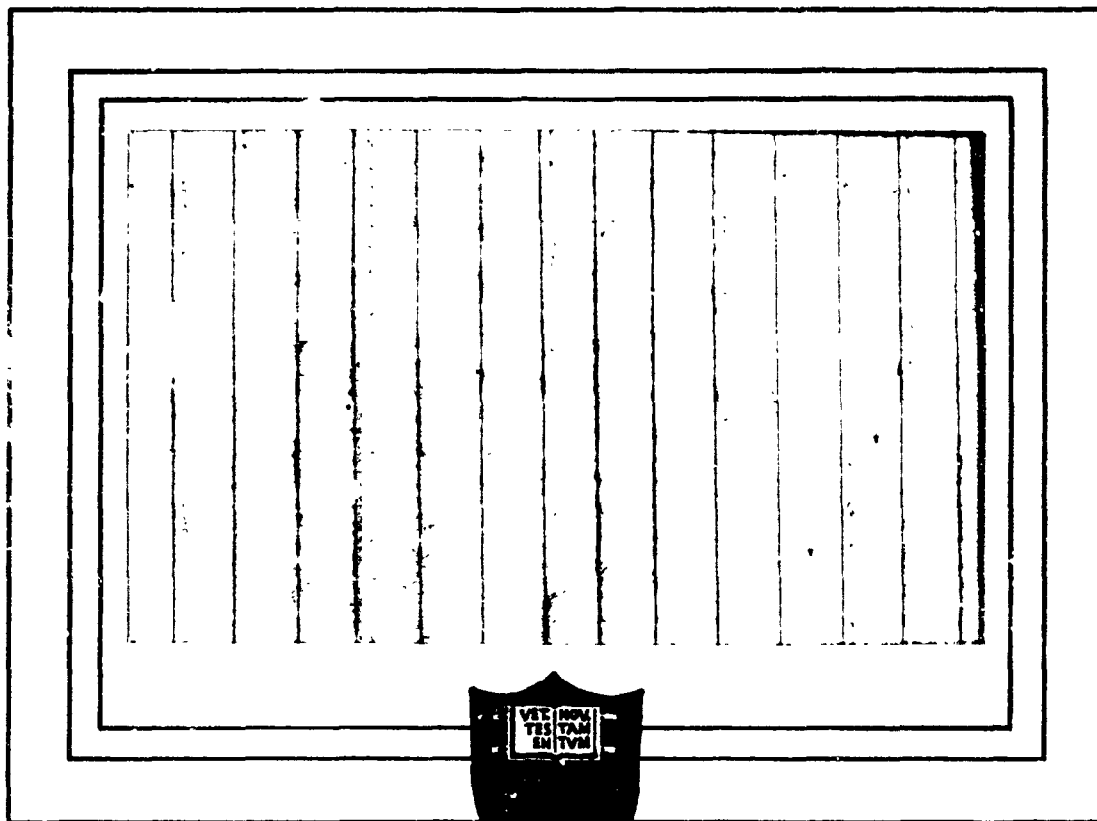


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PRINCETON UNIVERSITY

Fluid Mechanics of Continuous Flow Electrophoresis

Final Report

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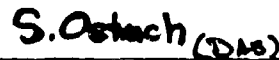
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TABLE OF CONTENTS

ABSTRACT	2
INTRODUCTION	3
SUMMARIES AND CONCLUSIONS	5
DESCRIPTIONS OF RESULTS	12
I. Flow and Temperature Fields	12
II. Hydrodynamic Stability	60
III. Modelling Electrophoretic Separation	68
ACKNOWLEDGMENTS	74
BIBLIOGRAPHY	75
COMPUTER PROGRAMS	76

ABSTRACT

The following aspects of continuous flow electrophoresis were studied: flow and temperature fields, hydrodynamic stability, separation efficiency, and characteristics of wide-gap chambers (the SPAR apparatus). Simplified mathematical models were developed so as to furnish a basis for understanding the phenomena and comparison of different chambers and operating conditions. Studies of the hydrodynamic stability disclosed that a "wide-gap" chamber may be particularly sensitive to axial temperature variations which could be due to uneven heating or cooling. The mathematical model of the separation process includes effects due to the axial velocity, electro-osmotic cross-flow and electrophoretic migration, all including the effects of temperature dependent properties.

INTRODUCTION

Hydrodynamics plays varied roles in the continuous flow electrophoresis of small particles, in some situations the suspending fluid does little more than carry particles through the apparatus, in others the flow is so convoluted that electrophoretic separation is impossible. One of the complicating factors is the role of buoyancy forces which can destabilize the flow or establish an unfavorable, but steady laminar flow. To circumvent such problems it has been suggested that the apparatus be operated in a microgravity environment where, due to the reduced size of buoyancy forces, the chamber could be made larger and field strength increased. Then populations of large biological particles could be fractionated into narrow subpopulations on the basis of unique surface characteristics which are reflected in the electrophoretic mobility. Such an undertaking obviously requires careful evaluations of many types. The purpose of this investigation is to furnish a basis for understanding the hydrodynamic characteristics of the chamber and their effects on the separation process. Particular emphasis is placed on the role buoyancy plays in establishing the basic flow and affecting its stability.

Work began on this project in February of 1977 with the objective of assembling and evaluating current knowledge of the hydrodynamics of continuous flow electrophoresis. Four tasks were specified for the one year contract period:

- (1) Develop models to describe the flow and temperature fields;
- (2) Investigate the hydrodynamic stability of the flow field;
- (3) Develop a model to predict electrophoretic separation efficiency;
- (4) Review the SPAR apparatus and experiment.

Work on these tasks is complete insofar as it is covered by this contract and results are described in this report. The studies begun here continue under a separate NASA contract with Princeton University. The main part of the report is divided into two parts: SUMMARIES AND CONCLUSIONS, and DESCRIPTION OF RESULTS, where more detailed information is set forth.

SUMMARIES AND CONCLUSIONS

More detailed information on the various subjects is contained in the DESCRIPTION OF RESULTS sections, here we simply summarize and discuss conclusions.

Flow and Temperature Fields

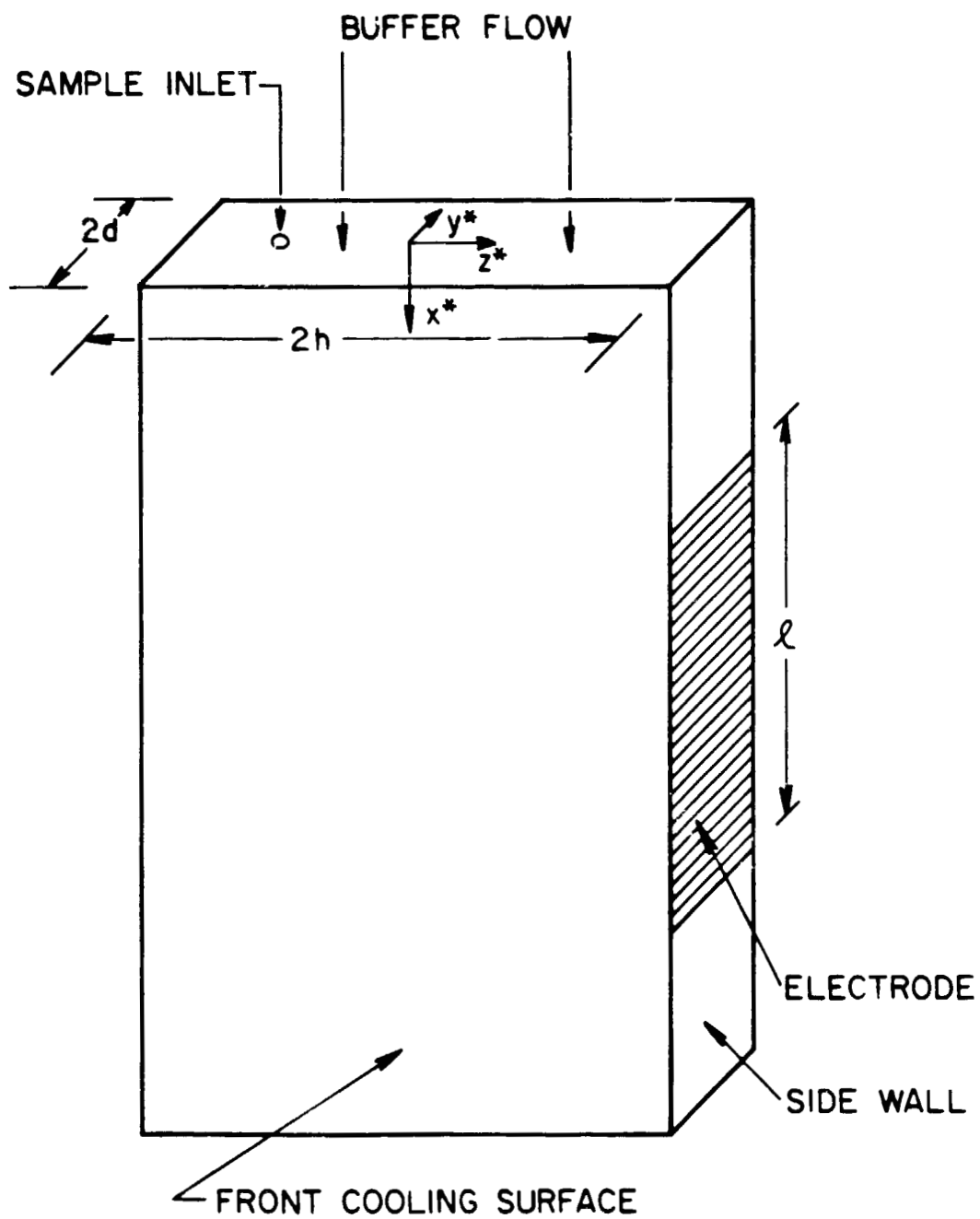
The temperature field enters the problem because it alters the electrophoretic mobility of the particles and causes density contrasts which lead to buoyancy driven flows. The non-uniform temperature field itself derives from heat effects associated with the electric field and current. Although the field is three-dimensional, it is possible to simplify matters using perturbation methods. For present purposes we sought to establish the edge effects due to cooling through the side walls containing the electrodes (cf. Figure 1)^{*}, the effects of temperature dependent conductivities for heat and electricity, and estimate time scales for thermal equilibration of the chamber.

The edge effects were found to be substantial in that they extend into the chamber for distances of 1-2 chamber thicknesses from each side. This alters the mobility of particles in these regions and has a dramatic effect on the flow through buoyancy effects. It was also found that the effects of temperature dependent conductivities were substantial, the calculated temperature rise being 70% larger for a wide-gap chamber (0.5 cm thick)^{*} than that calculated assuming constant properties. Although temperature relaxation times for the fluid are only 10-15 seconds for a narrow-gap chamber (0.15 cm) 2-3 minutes are required to establish the steady field in a wide-gap chamber.

* Representative dimensions, fluid properties, operating conditions, etc., are summarized on Table I, p. 72. A schematic diagram is on p. 7.

FIGURE 1.

Schematic representation of an electrophoresis chamber.



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For the flow field analytical solutions in two-dimensions were constructed to investigate ways buoyancy could alter the axial flow and to study edge effects. One-dimensional models were then developed to investigate the effects of temperature dependent transport properties on the axial flow and electro-osmotic cross flow.

Several conclusions can be drawn from this part of the study.

(a) It is necessary to include effects of temperature on transport properties. Models which ignore this, or treat matters inconsistently, can be qualitatively and quantitatively misleading, especially with wide-gap machines like the SPAR device. With narrow-gap machines operated with modest field strengths (cf. Table 1) the use of 'average' values is satisfactory since temperature variations are usually small.

(b) In wide-gap machines operating in a 1-g environment the steady-state axial velocity profile is unsatisfactory at modest field strengths insofar as electrophoretic separations are concerned. An earlier study by Ostrach (using a 'constant properties' one-dimensional model) identified a buoyancy-driven feature which made downflow operation unsatisfactory. Edge effects and alterations due to temperature depending properties accentuate the buoyancy feature making matters worse. Upflow, which was once suggested as a means of overcoming the difficulty, turns out to be only marginally better for the cases studied. In downflow the difficulty arises from a recirculating eddy in the center of the chamber; in upflow two eddys appear, attached to the front and rear cooling surfaces, and these restrict the area available for separation. A micro-gravity environment would suppress or eliminate secondary flows of this sort. Of course other means of eddy suppression ought not be ruled out.

(c) Experiments at General Electric using the wide-gap SPAR apparatus disclosed a meandering sample flow pattern thought to be evidence of the structure noted in (b). Subsequent calculations made with the models developed here showed that the actual power levels were far lower than those required according to the theory and thus the meandering flow must be due to another process.

Hydrodynamic Stability

In an attempt to ascertain the cause of the meandering observed in the General Electric experiments the stability of several chamber configurations was examined. Attention focussed on buoyancy driven instabilities for obvious reasons and investigations of other sorts of instability, e.g., those due to viscosity stratification or electrokinetic effects, etc., were deferred. Three sorts of instability were investigated: the inception of cellular motion due to heat generation in a quiescent layer, roll cells in a buoyancy driven shear flow and the effect of an axial temperature gradient on a fully developed flow. Critical temperature differences for the quiescent layer or the shear flow are much larger than those present in the experiments. For the vertical chamber with axial flow a new two-dimensional instability was identified with an especially low critical Rayleigh number. For conditions characteristic of the SPAR machine the critical axial gradient is (ca.) $0.5^{\circ}\text{C}/\text{cm}$.

Further experimental work will be required to establish whether or not the flow 'meandering' is a manifestation of the instability predicted by the current theory. If it is, then a micro-gravity environment will provide a means of avoiding it. Other types of instability mechanisms should also be investigated, however, so as to provide a comprehensive picture.

Prediction of Electrophoretic Separator Performance

Using the flow and temperature fields described earlier, a mathematical model of continuous electrophoretic separation was developed. The model (in brief):

(a) Accepts as input data the dimensions of the chamber, operating conditions and flowrates, transport properties of the buffer, location and size of the sample injection tube, mobility distribution of the sample, zeta-potential of the wall coating, number and size of the sample outlet streams, etc.

(b) Predicts the mobility distribution in each of the sample withdrawal streams.

Calculations were carried out using computer programs which have been tested on "model systems". Further refinements will be made under the current NASA contract with Princeton.

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SPAR Electrophoresis Experiment

Throughout the course of this investigation attention focussed on understanding the behavior of wide-gap machines and predicting their performance. We now have models of the flow and temperature fields and can estimate the electrophoretic separation characteristics of a given device.

Although refinements will be necessary, the requisite 'first generation' models now exist for interpreting results from SPAR (or other) experiments. Furthermore, the effects of changes in process variables can be examined so as to optimize the separation.

Final Comments

Work begun during this program is being carried on under a joint program coordinated by Dr. R.S. Snyder of MSFC. These tasks include:

(a) Experimental studies (at MSFC) to ascertain the reason for flow meandering in wide-gap machines at 1-g. This will serve to prove or disprove the proposal that observed unsatisfactory operation is due to a buoyancy driven instability and assist in developing ways to circumvent the problem.

(b) Case-studies with the flow and separation models developed here to ascertain the ultimate (theoretical) capabilities of continuous flow devices.

(c) Theoretical work to extend the capabilities of the model, to develop an understanding of three-dimensional effects and finite sample concentration, and to investigate other hydrodynamic instabilities which could limit resolution. Establishing the limitations due to gravity and those arising from other phenomena.

Frequent observations of particle agglomeration and 'clumping' phenomena with cells underscore the need for an investigation of effects due to particle concentration. Recent theoretical studies (Batchelor, 1972) suggest substantial changes in sedimentation velocity at particle concentrations of a few percent but none of the extant studies deal with electrokinetic effects present in electrophoresis.

(d) The development of experimental techniques to test the model using mixtures of well-characterized particles. This will include micro-gravity experiments where appropriate

DESCRIPTION OF RESULTS

I. Flow and Temperature Fields

Introduction

Inside a continuous flow electrophoresis chamber of the sort depicted on Figure 1 the temperature and velocity have a three-dimensional character. Cold buffer enters one end of the chamber and adjusts to the new geometry within a distance, x_e , which is given roughly by the formula (Schlichting, 1960)

$$x_e = 0.16 \text{ Re } d. \quad (1)$$

Here d stands for the half-thickness and Re for the Reynolds number, $u_0 d / \nu_0$; u_0 is the mean axial velocity and ν_0 the kinematic viscosity. Since the Reynolds number lies in the range 1-5, the entrance length is relatively short and here the velocity field can be modelled as being fully developed (viz. independent of x). As the buffer flow moves into the electrode region heat is added (volumetrically) through the action of the electric field and the associated current, so, to limit the temperature rise, the front and back walls are kept cold. For reasons that will be explained later (in the section on stability) the adjustment length for the temperature field can be substantial. Thus, in the electrode region the three-dimensional nature of the temperature field alters the structure of the velocity field through its effects on density and viscosity. Another contributory factor is the electro-osmotic cross-flow caused by the action of the field on the thin layer of charge in the fluid adjacent to the lateral boundaries. Although this velocity is typically much smaller than the axial velocity, it has a major role in altering the electrophoretic separation processes.

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The models developed here to describe the temperature and velocity fields take advantage of three facts:

- (i) The magnitude of the electro-osmotic velocity, w_o , is small compared to u_o .
- (ii) The axial variation of the temperature is slow.
- (iii) The effect of temperature on thermal conductivity and electrical conductivity is approximately linear over the temperature range of interest: $0^\circ - 35^\circ\text{C}$.

These facts justify the use of perturbation methods to develop a description of the temperature and velocity fields. First, because of (i), the velocity field can be split into two parts, an axial flow field due to forced and natural convection with a superimposed electro-osmotic flow. Next, due to the slow variation of the transport properties with axial position, (ii), the velocity fields can be split into a fully-developed part (independent of x) with corrections added later to allow for axial structure. Finally, the simple linear variation, (iii), makes the description of the temperature field particularly simple.

Separate parts of the sequel are devoted to:

- A. Mathematical models for the structure of the temperature field
 - a. A two-dimensional model in which the effects of temperature on thermal conductivity are suppressed. This provides a means of evaluating edge-effects due to heat transfer near the side wall electrodes.
 - b. A one-dimensional model to evaluate effects of a temperature dependent thermal conductivity.
 - c. A transient heat conduction model to estimate thermal relaxation times.

B. Models for the structure of the axial velocity field

- a. A two-dimensional, constant properties model provides a means of examining edge effects and buoyancy effects using the Boussinesq approximation.
- b. A one-dimensional, variable properties model is the basis for evaluating thermal effects and is used in the separation model described in Part III.

C. Models for the electro-osmotic cross-flow velocity

- a. A one-dimensional, variable properties model provides a basis for evaluating thermal effects and is used in the separation model (Part III).

Temperature Field

The equation for the conservation of thermal energy is

$$C_p u \frac{\partial T}{\partial x} = \nabla \cdot k \nabla T + \sigma_0 E_0^2 \quad (2)$$

The symbols are: C_p - volumetric heat capacity, k - thermal conductivity, σ - electrical conductivity, and E_0 - the electric field strength. E_0 is assumed to be a constant throughout the analysis. Both k and σ vary with temperature in a linear fashion (see Figure 2) and so we write

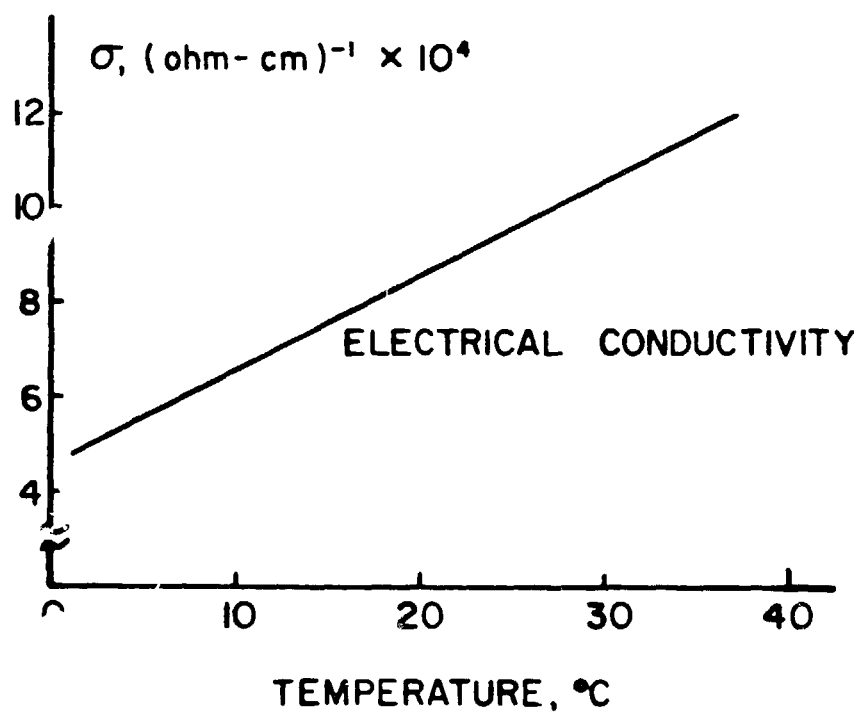
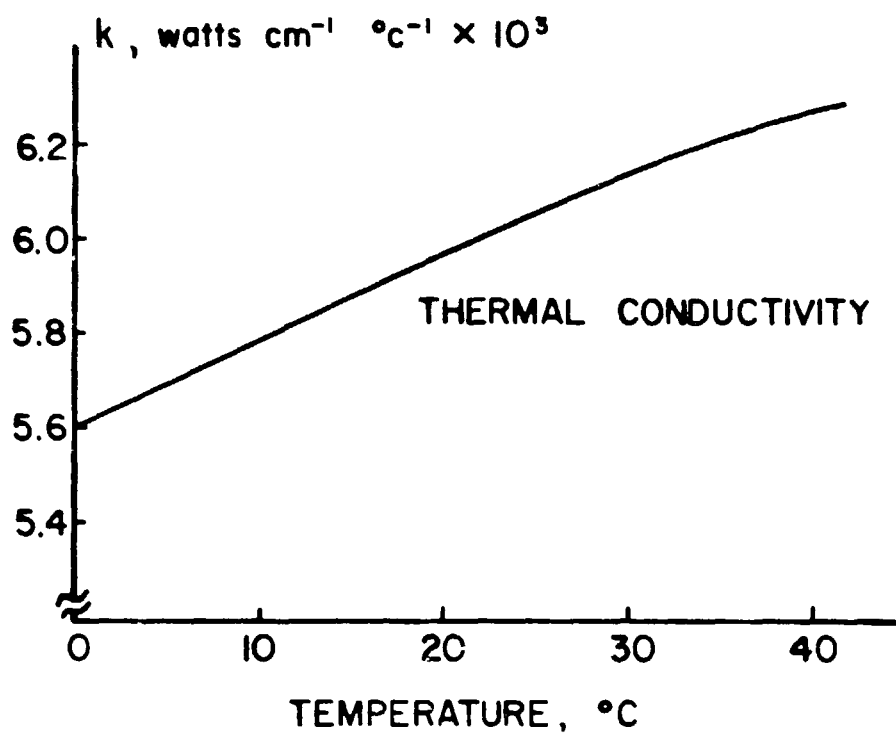
$$\sigma = \sigma_0 (1 + \sigma_1 \theta) \quad (3)$$

$$k = k_0 (1 + k_1 \theta) \quad (4)$$

where k_0 and σ_0 are reference values evaluated at the wall temperature and θ stands for a dimensionless temperature, i.e.,

FIGURE 2.

Thermal conductivity and electrical conductivity of the A-1 buffer.



$$T = T_w + \Delta T \theta \quad (5)$$

The wall temperature is T_w and ΔT is a characteristic temperature difference. If we transform to dimensionless variables with u_0 as the characteristic velocity and d the characteristic length, then

$$Pe u \frac{\partial \theta}{\partial x} = \nabla \cdot [(1 + k_1 \theta) \nabla \theta] + 1 + \sigma_1 \theta \quad (6)$$

where $Pe = C_p u_0 d / k_0$ and $\Delta T = \sigma_0 E_0^2 d^2 / k_0$.

Both k_1 and σ_1 are less than unity: k_1 is typically $O(10^{-2})$ while σ_1 is $O(10^{-1})$, and so it is convenient to represent the temperature by means of a perturbation series in k_1 , viz.

$$\theta = \theta^{(0)} + k_1 \theta^{(1)} + k_1^2 \theta^{(2)} + \dots \quad (7)$$

Substituting into (6) we generate a sequence of equations for $\theta^{(0)}$, $\theta^{(1)}$, ...

$$Pe u \frac{\partial \theta^{(0)}}{\partial x} = \nabla^2 \theta^{(0)} + \sigma_1 \theta^{(0)} + 1 \quad (8)$$

$$Pe u \frac{\partial \theta^{(1)}}{\partial x} = \nabla^2 \theta^{(1)} + \sigma_1 \theta^{(1)} + \nabla \cdot (\theta^{(0)} \nabla \theta^{(0)}) \quad (9)$$

etc.

From equation (8) we deduce that in the thermal entrance region $\partial \theta^{(0)} / \partial x$ is $O(Pe^{-1})$ and varies exponentially. Viscosity and density also depend on temperature so that a description of the temperature field to the order implied by equations (8) and (9) would entail an expansion for the axial velocity of the form

$$u = u^{(0)} + u^{(1)} + \dots \quad (10)$$

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where $u^{(0)}$ is the constant properties solution, $u^{(1)}$ accounts for temperature variations, etc. This expansion would be used to furnish complete velocity fields for (8) and (9). Because of the complexity of the problem it has not been practical here to attempt a solution which includes axial variations. Instead we have suppressed the axial structure and developed a 'zero-order' approximation with which we can assess the orders-of-magnitude of the thermal effects. An investigation of the details of the axial structure of the temperature and velocity fields is part of the work being done now under another NASA contract.

Two-Dimensional, Constant Thermal Conductivity Model

The major features of the fully developed temperature field can be found by solving equations (8) and (9), omitting the convective terms. The boundary conditions are:

- (i) isothermal side walls, $\theta = 0$, at $y = \pm 1$.
- (ii) heat transfer through the side walls at $z = \pm H$ modelled in terms of a heat transfer coefficient, h , i.e.,

$$-k \frac{\partial T}{\partial z} = h_o(T - T_B).$$

T_B stands for the coolant temperature. For the zero-order field we have, in dimensionless form:

$$0 = -\nabla^2 \theta^{(0)} + \sigma_1 \theta^{(0)} + 1 \tag{11}$$

$$\theta^{(0)} = 0, y = \pm 1, \frac{\partial \theta^{(0)}}{\partial z} = -Bi \theta^{(0)}, z = \pm H$$

The Biot number, Bi , is $h_0 d/k_0$; $H = h/d$. For $Bi = 0$ the end walls are perfectly insulating and the temperature field is one-dimensional. For $Bi \rightarrow \infty$ the end walls are isothermal with $\theta^{(0)} = 0$. Fourier transforms were used to solve equation (11) and the solution is

$$\theta^{(0)}(y, z) = \frac{2}{\pi} \sum_{n=1}^{\infty} [A_n \cosh \lambda_n z + B_n] \sin \frac{n\pi}{2} (1 + y) \quad (12)$$

where

$$A_n = \frac{Bi}{\lambda_n^2} \frac{(1+(-1)^n)}{n} (\lambda_n \sinh \lambda_n H - Bi \cosh \lambda_n H)^{-1}$$

$$B_n = \frac{1-(-1)^n}{n\lambda_n^2}$$

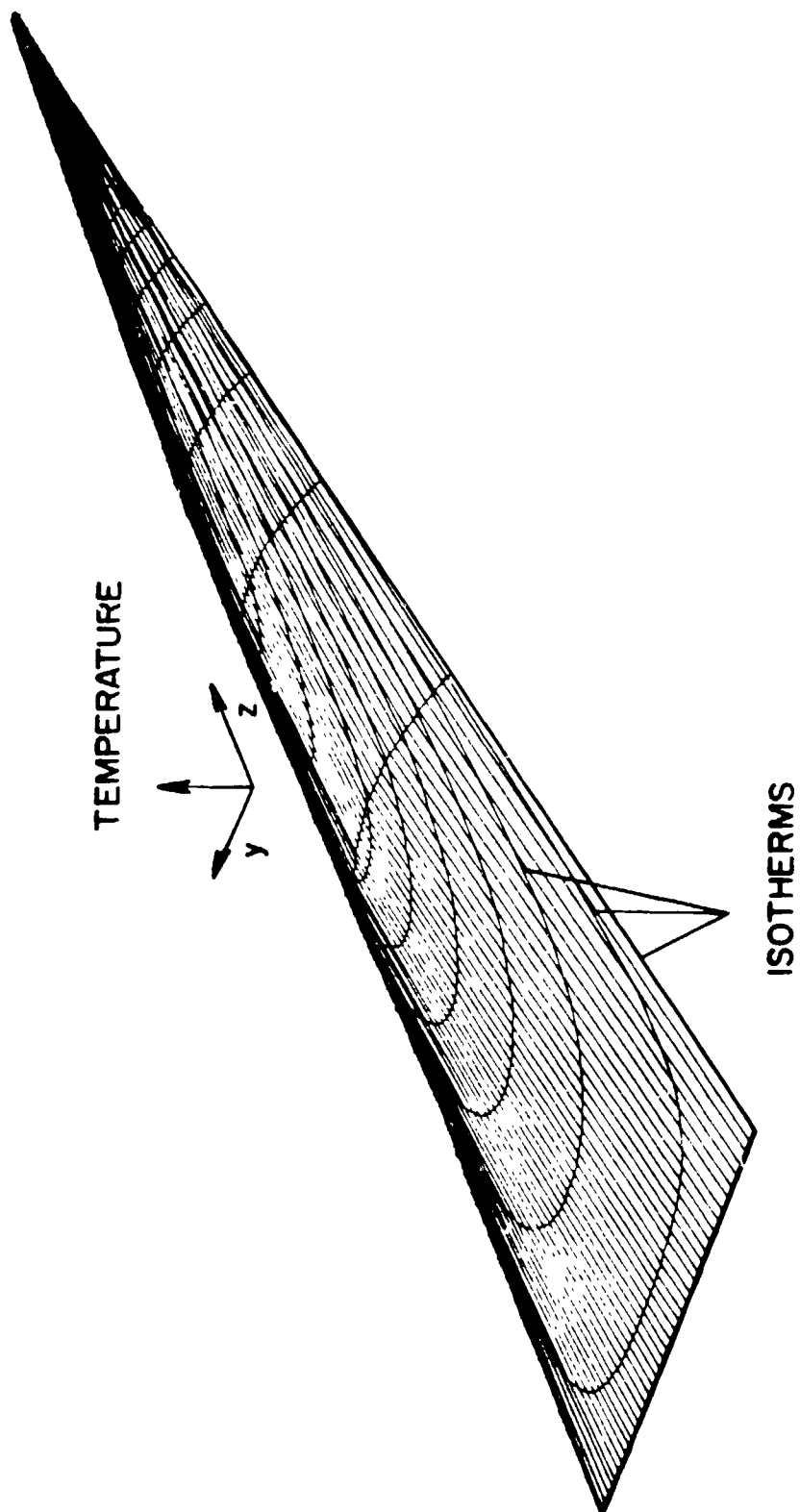
$$\lambda_n^2 = \frac{n^2 \pi^2}{4} - \sigma_1$$

Figures 3-6 display representative features of the temperature fields for narrow-gap and wide-gap chambers. Figures 3 and 5 are perspective views, Figures 4 and 6 are sections. A noteworthy feature is that the effect of side walls, shown on Figures 4 and 6, persists for a distance of 2-3 half thicknesses into the chamber at each side. For the wide-gap chamber (0.5 cm wide) this distance is (roughly) 0.75 cm and for the narrow-gap chamber (0.15 cm wide), 0.45 cm. Thus, due to the effect of temperature, particles within these regions will have a different electrophoretic mobility from those in the interior. In addition, buoyancy effects will be accentuated.

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FIGURE 3.

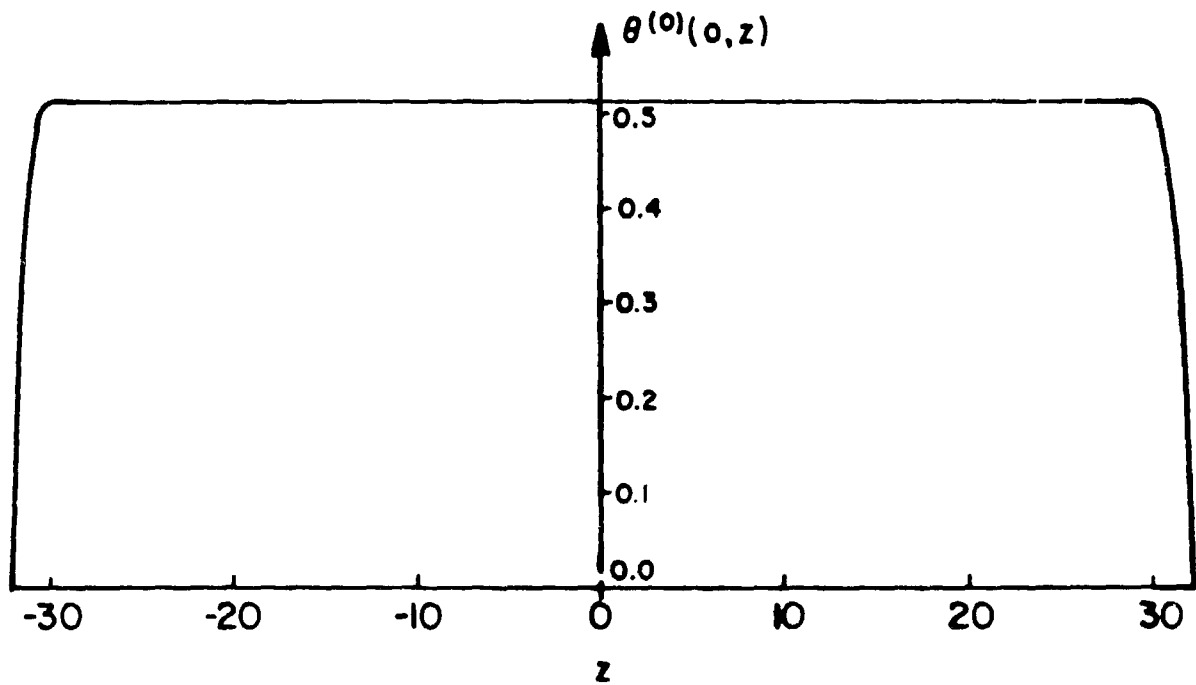
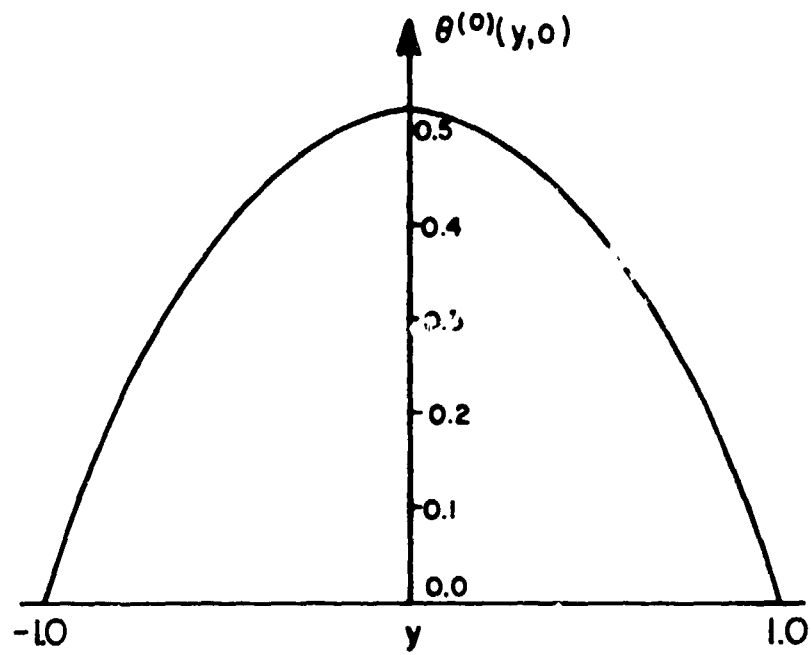
Perspective view of the temperature field for the narrow-gap chamber operating at conditions listed on Table I (uniform thermal conductivity).
Note: $2d = 0.15$ cm, $2h = 5$ cm. Eq. (12).



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FIGURE 4.

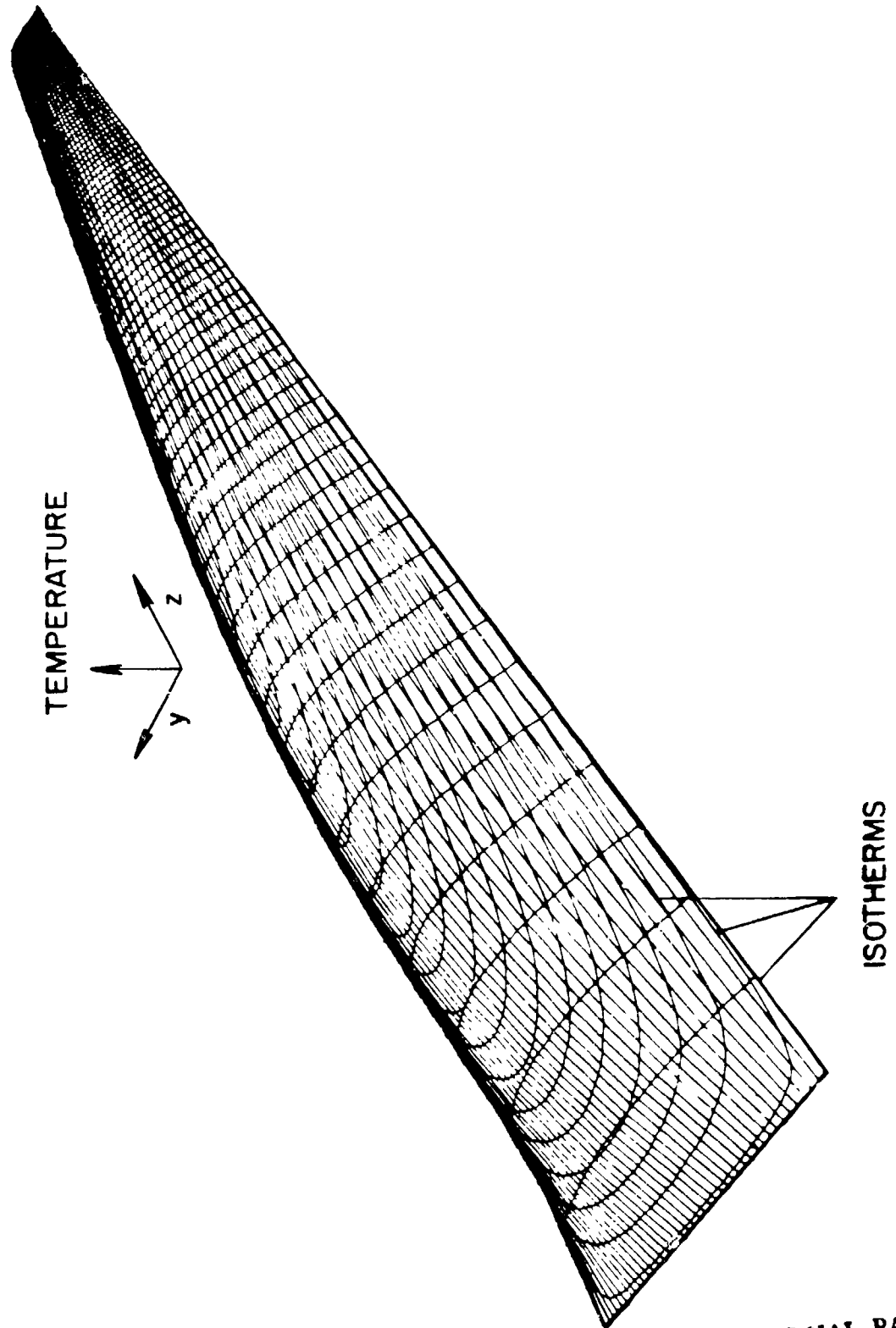
Sections of the temperature field as shown in Figure 3.



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FIGURE 5.

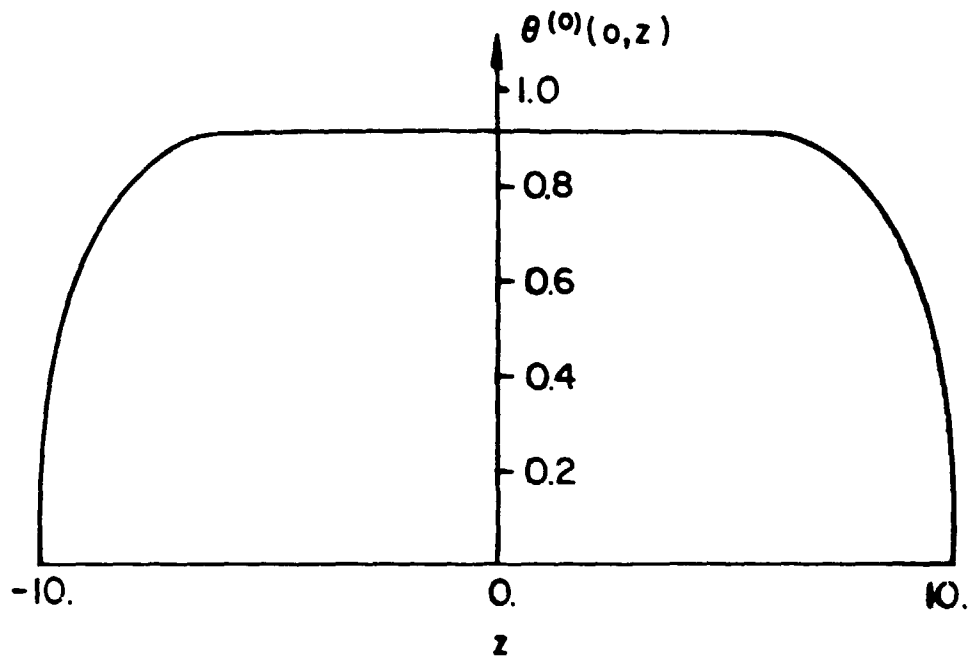
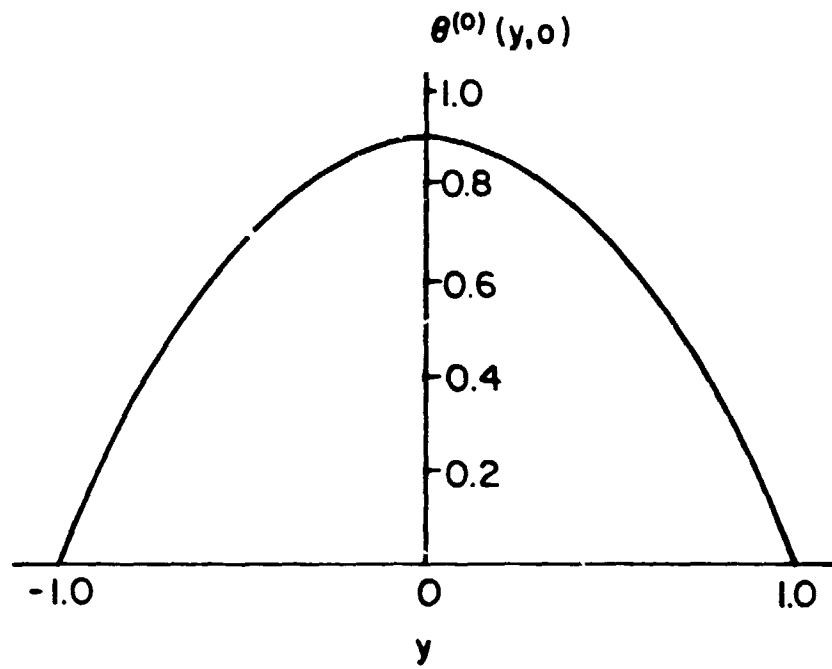
Perspective view of the temperature field for the wide-gap chamber operating at conditions listed on Table I (uniform thermal conductivity). Note: $2d = 0.5$ cm, $2h = 5$ cm. Eq. (12).



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FIGURE 6.

Sections of the temperature field as shown in Figure 5.



One-Dimensional, Variable Thermal Conductivity Model

A one-dimensional temperature field corresponds to a very wide chamber, $H \rightarrow \infty$, or one with insulated end walls at $z = \pm H$. The zero-order field is given by

$$\theta^{(0)}(y) = \frac{1}{\sigma_1} \left[\frac{\cos N_1 y}{\cos N_1} - 1 \right] \quad (13)$$

$$N_1^2 = \sigma_1$$

and perturbations are found from solutions to

$$\frac{d^2 \theta^{(1)}}{dy^2} + \sigma_1 \theta^{(1)} = -\frac{1}{2} \frac{d^2}{dy^2} [\theta^{(0)}]^2 \quad (14)$$

Using Fourier transforms the solution is found to be

$$\theta^{(1)}(y) = \frac{2}{\pi} \sum_{n=1}^{\infty} f_n(n) \sin \left[\frac{n\pi}{2} (1+y) \right] \quad (15)$$

where

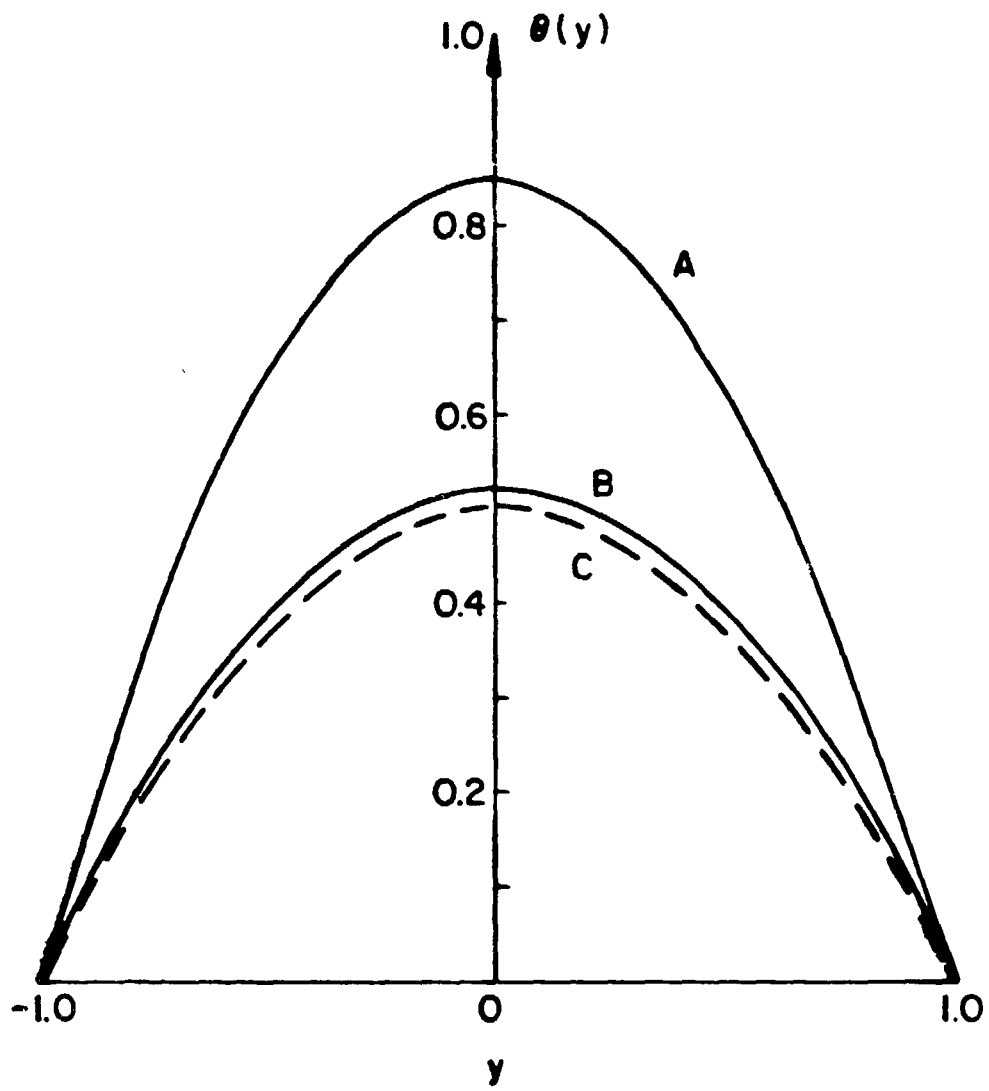
$$f_n(n) = -\frac{1}{2} \frac{n^2}{n^2 - 4\sigma_1/\pi^2} S_n\{(\theta^{(0)})^2\}$$

$$S_n\{(\theta^{(0)})^2\} = \text{sine transform of } (\theta^{(0)}(y))^2.$$

Temperature fields for narrow-gap and wide-gap chambers are shown on Figure 7, along with that for constant thermal and electrical conductivities. Figure 7 depicts matters in dimensionless form and it is seen that with the wide gap the temperature rise is 1.7 times that expected with constant properties at the conditions shown, for the A-1 buffer this is nearly 30°C.

FIGURE 7.

One-dimensional temperature field calculated so as to account for temperature dependent thermal conductivity and electrical conductivity, A - wide-gap, B - narrow-gap, C - constant properties (cf. Table I). Eqs. (13) and (15).



With the narrow-gap, the temperature rise is so small, about 1.5°C, that variable-property effects are negligible. Here we also see (upon comparison with Figure 5) that the influence of variable thermal conductivity serves to alter the temperature rise. Accounting for the variable thermal conductivity lowers this maximum by about 2°C for the wide-gap chamber at the conditions shown.

One-Dimensional, Transient Response Model

An estimate of the minimum time required to reach a steady thermal state can be made using a transient thermal model which ignores convection, since it tends to increase the equilibration time by adding colder fluid and withdrawing warm fluid from the region of interest. A rough estimate can be found from the characteristic relaxation time scale, d^2/α_0 . For the A-1 buffer $\alpha_0 = 1.39 \text{ cm}^2/\text{s}$ so that for a narrow-gap machine ($d = 0.075 \text{ cm}$) the time scale is about 4 seconds; for the wide-gap machine the time-scale is 45 seconds. To attain a condition near the steady-state generally requires 2-3 'relaxation times', as shown on Figures 8 and 9. Data for the graphs were calculated using the solution to a transient heat conduction problem with heat generation, viz.

$$\frac{\partial \theta}{\partial \tau} = \frac{\partial^2 \theta}{\partial y^2} + 1 + \sigma_1 \theta \quad (16)$$

with $\theta(\tau, -1) = 0$, $\theta(0, y) = 0$. The solution given by Carslaw and Jaeger (1959) is

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FIGURE 8.

Transient temperature response for a narrow-gap chamber (one-dimensional, constant thermal conductivity) (cf. Table I).
Eq. (17).

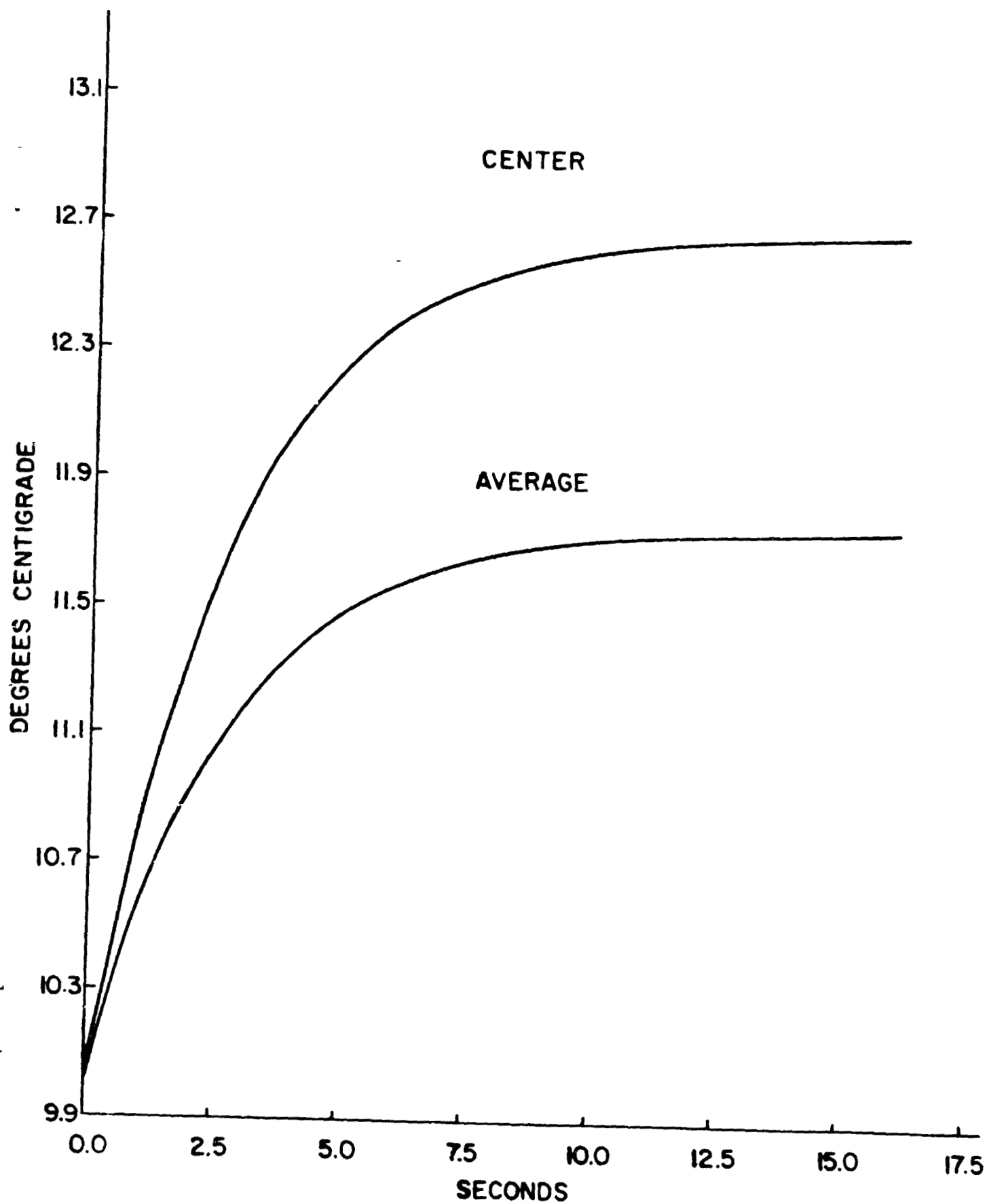
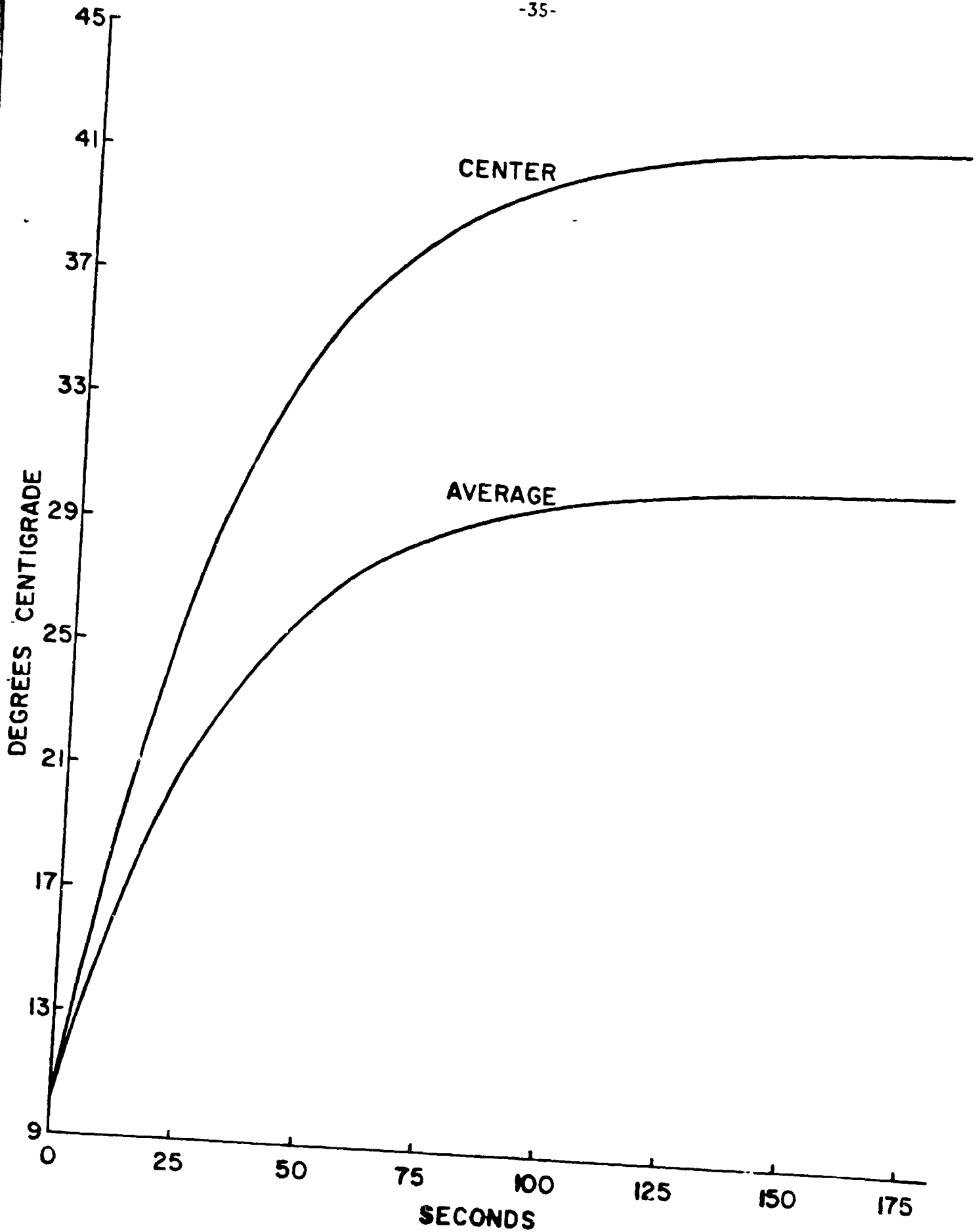


FIGURE 9.

Transient temperature response for a wide-gap chamber (one-dimensional, constant thermal conductivity) (cf. Table I).
Eq. (17).



$$\theta = \frac{1}{\sigma_1} \left[\frac{\cos N_1 y}{\cos N_1} - 1 \right] + \frac{16}{\pi} \sum_{n=0}^{\infty} (-1)^n \frac{\exp(\cdot) \cos[2n+1)\pi y/2]}{[4\sigma_1 - (2n+1)^2 \pi^2] [2n+1]}$$

$$(\cdot) = [-(2n+1)^2 \pi^2 + \sigma_1] \tau \quad (17)$$

$$\tau = \alpha_0 t / 4d^2, \quad y = y^* / d$$

Obviously a more refined estimate could be made by solving a two-dimensional with convection included, however, the characteristic time for equilibration would probably not change too much. Thus, in any experiment with wide-gap machine at least 2-3 minutes should be allowed for thermal equilibration.

Axial Velocity Field

Equations to describe the axial velocity are derived from the Navier-Stokes equations using an expansion described earlier

$$u(y,z) = u^{(0)}(y,z) + u^{(1)}(y,z) + \dots \quad (10)$$

The effects of buoyancy on the two-dimensional flow field are described in the first part of this section. In the second, where the effects of the lateral boundaries at $z = \pm H$ are ignored, exact solutions are possible which account fully for the effects of temperature on viscosity and buoyancy.

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Two-Dimensional, Constant Transport Properties Model

The $0(1)$ -velocity is described by solutions to

$$0 = -K + N_2 - N_3 \theta^{(0)} + \nabla^2 u^{(0)} \quad (18)$$

where K is a constant (dimensionless) axial pressure gradient;

$N_2 = gd^3/\nu_0^2 \text{ Re}$ and $N_3 = gd^3\beta\Delta T/\nu_0^2 \text{ Re}$, $\text{Re} = du_0/\nu_0$. The parameter N_3 describes the magnitude of the buoyancy effect while $(-K + N_2)$ is a constant to be determined from the fact that the volumetric flowrate is independent of the temperature rise, since the velocity is scaled using the mean velocity, u_0 . Using Fourier Sine transforms we find

$$u^{(0)}(y, z) = \frac{2}{\pi} \sum_0^{\infty} g_s(n) \sin \frac{n\pi}{2} (1+y) \quad (19)$$

with

$$g_s(n) = B_n \cosh \frac{n\pi}{2} z + C_n \cosh \lambda_n z + D_n$$

The coefficients B_n , C_n , and D_n are found from the relations

$$\begin{aligned} B_n \cosh \frac{n\pi H}{2} + C_n \cosh \lambda_n H + D_n &= 0 \\ C_n &= -\frac{N_3 A_n}{\sigma_1} \\ D_n &= -\frac{4}{n^2 \pi^2} \left[\frac{K - N_2}{n} (1 - (-1)^n) + \frac{N_3}{n} \frac{(1 - (-1)^n)}{\lambda_n^2} \right] \end{aligned} \quad (20)$$

Finally $(-K + N_2)$ is found from the requirement that

$$\int_0^H \int_{-1}^1 u^{(0)}(y, z) dy dz = 4H \quad (21)$$

FIGURE 10.

Axial velocity field for the narrow-gap chamber (cf. Table I).
The velocity is almost indistinguishable from the fully developed
parabola, $3(1 - y^2)/2$ except near the side walls at $z = \pm 33.3$.
Eq. (19).

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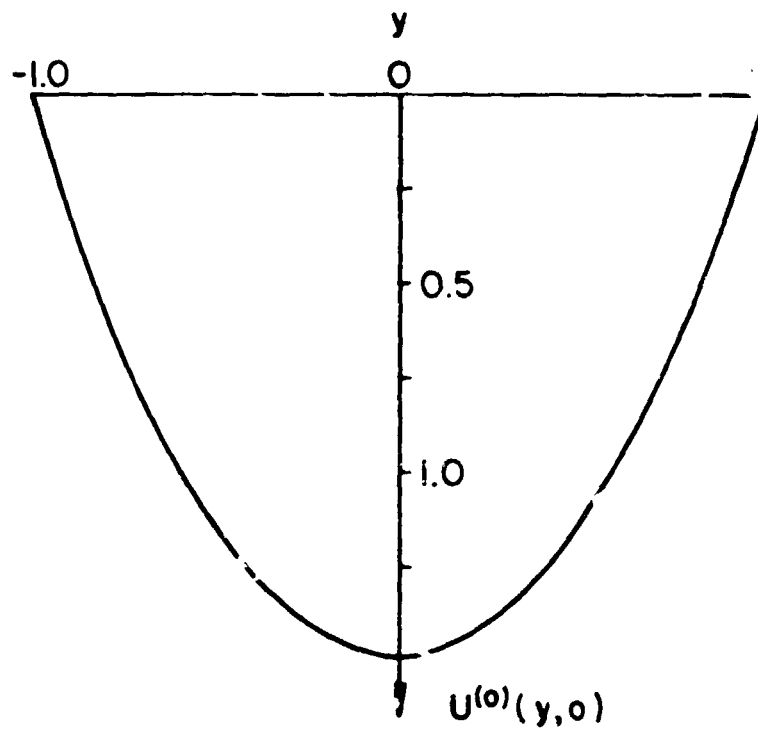
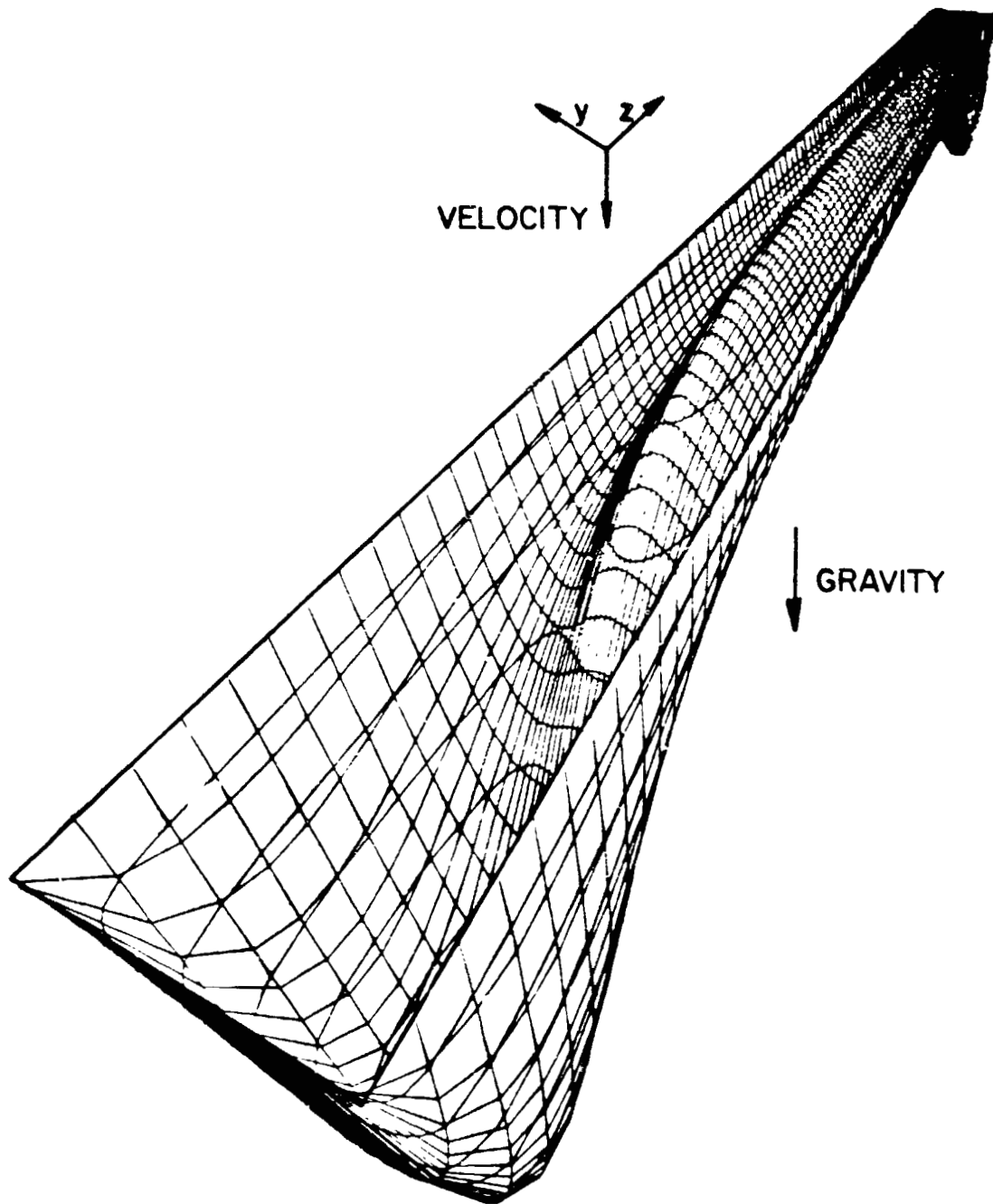


FIGURE 11.

Perspective view of the axial velocity field for the wide-gap chamber (cf. Table I). Downflow at $g = 980 \text{ cm/s}^2$. Eq. (19).

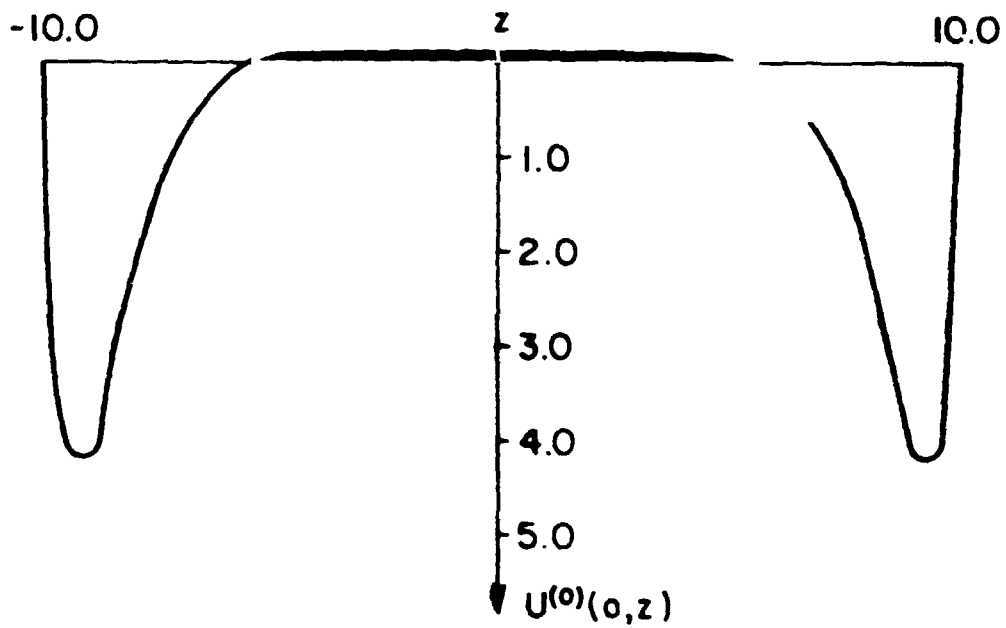
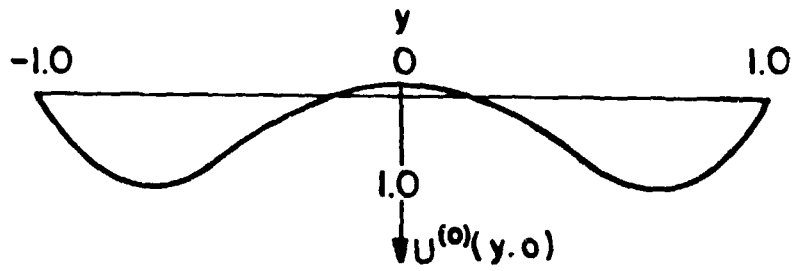
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FIGURE 12.

Central sections of the field shown on Figure 11. Note weak upflow in center and strong downflow along front and back cooling walls and near side walls at $z = \pm 10$.



↓ DIRECTION OF MAIN FLOW AND GRAVITY

FIGURE 13.

Perspective view of the axial velocity field for the wide-gap chamber (cf. Table I). Upflow at $g = 980 \text{ cm/s}^2$. Eq. (19).

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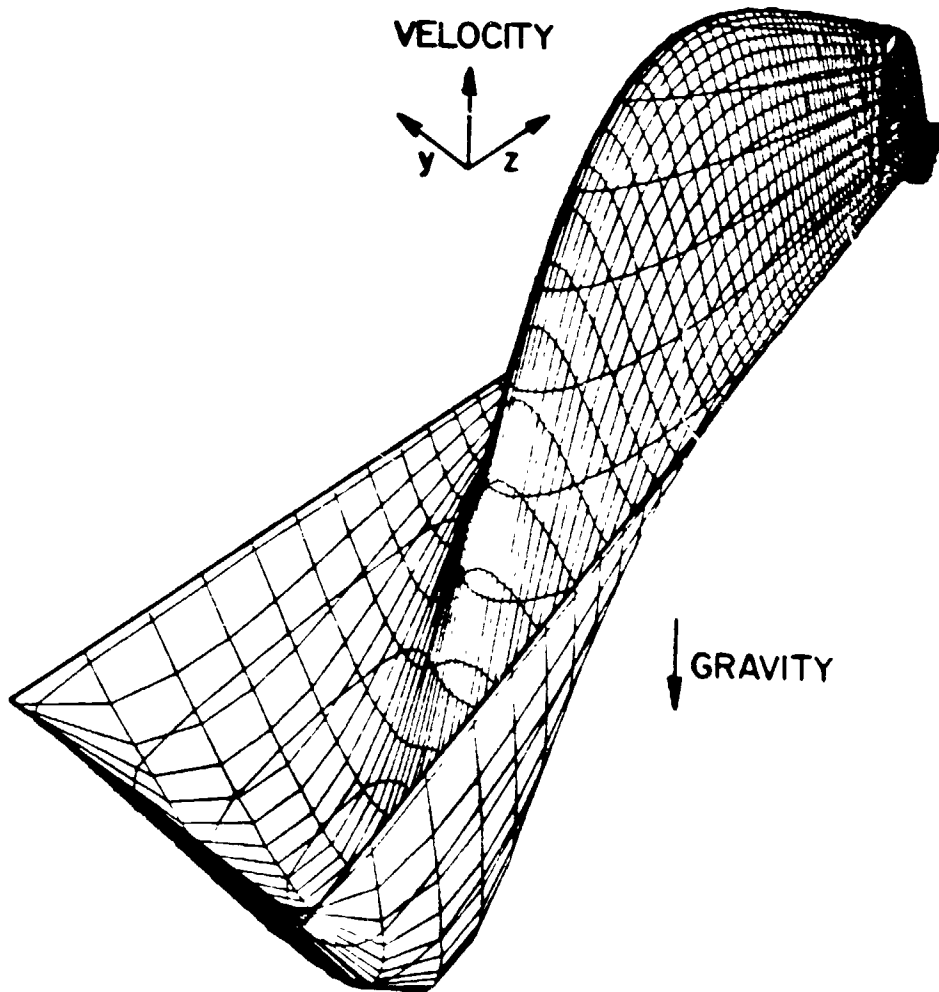
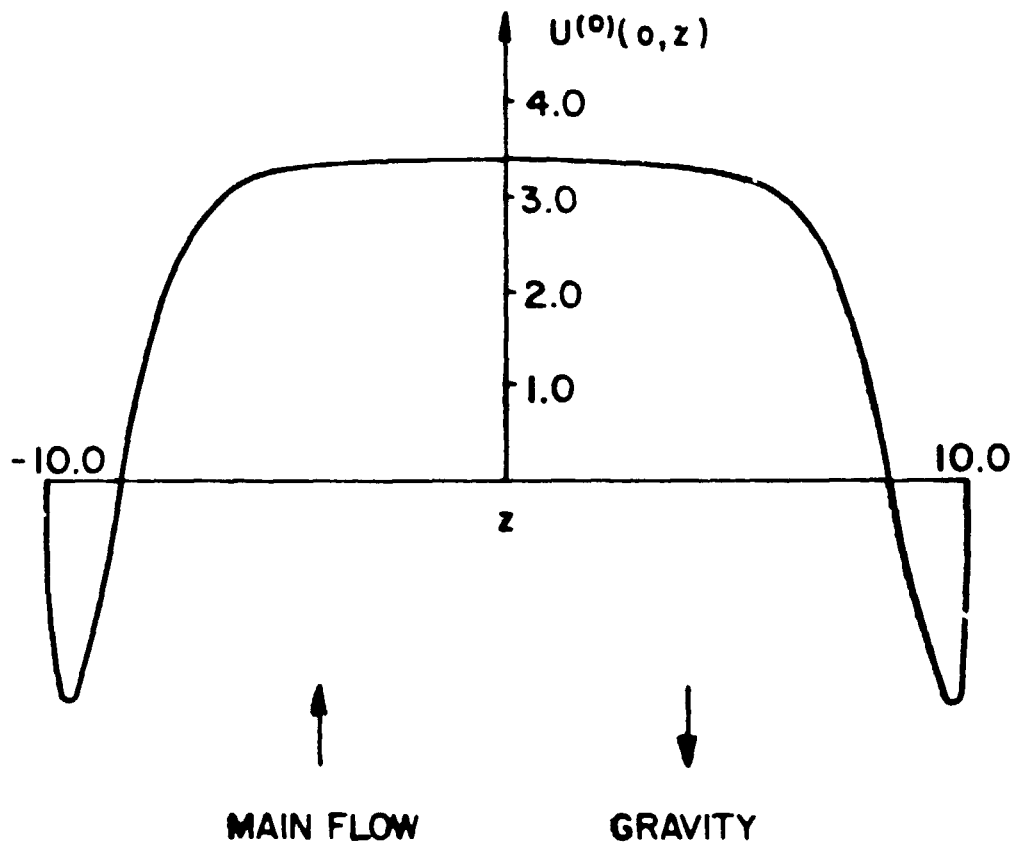
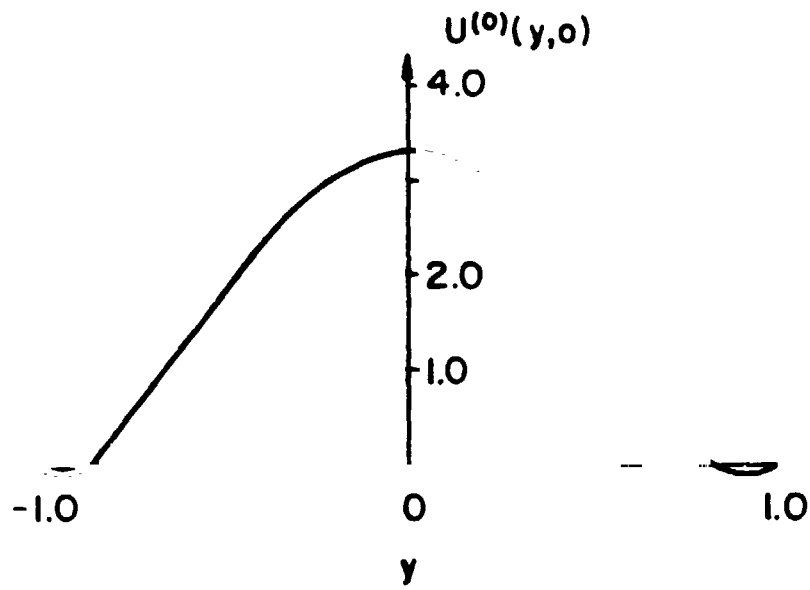


FIGURE 14.

Central sections of the field shown on Figure 13. Note downflow along front and rear cooling walls and near the side walls at $z = \pm 10$.

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Results of representative calculations are shown on Figures 10-14. Figure 10 shows that buoyancy has relatively little effect on a narrow-gap chamber due to the excellent heat transfer. The maximum temperature rise for this case is about 1°C. End effects due to the no-slip condition at $z = \pm H$ are similar to those encountered with the temperature field.

With the wide-gap chamber dramatic effects are present at unit gravity. Figure 11 is a perspective view, Figure 12 shows the velocity across two sections of the chamber with downflow. Here buoyancy causes regions of reversed flow throughout a large part of the central section. With a finite length chamber this implies that a large recirculating eddy would be present in the central section and the chamber would be difficult to use as an electrophoretic separation device. If the flow is reversed, the recirculating eddy splits apart and is attached to the side walls, as is shown on Figures 13 and 14. Since the recirculating regions are adjacent to the side walls, the central section allows more-or-less free passage of fluid and any sample. Of course, any sample that migrated into the eddy structures would be difficult to recover.

One-Dimensional Velocity Fields

Effects due to a temperature dependent viscosity and buoyancy can be investigated easily using a one-dimensional model and, in fact, exact solutions can be obtained. Since variations are confined to the y-direction we have

$$0 = K + N_2 \rho + \frac{d}{dy} \mu \frac{du}{dy} \quad (22)$$

with

$$u(\pm 1) = 0$$

The solution is

$$u(y) = -K \int_y^1 \frac{y_1}{\nu} dy_1 + N_2 \int_y^1 \frac{1}{\nu} \int_0^{y_2} \rho dy_1 dy_2 \quad (23)$$

with K determined from the fact that the velocity scale is the mean velocity. Thus

$$1 = -K \int_0^1 \int_y^1 \frac{y_1}{\nu} dy_1 dy + N_2 \int_0^1 \int_y^1 \frac{1}{\nu} \int_0^{y_2} \rho dy_1 dy_2 dy \quad (24)$$

Given expressions for the dimensionless viscosity, and density, both scaled on values evaluated at the wall, it is a straightforward task to evaluate the integrals. In the calculation a two-term expression was used for the temperature, viz.

$$\theta = \theta^{(0)} + k_1 \theta^{(1)} \quad (7)$$

For purposes of comparison we can evaluate the velocity field for uniform viscosity and buoyancy. The temperature field is

$$\theta^{(0)}(y) = \frac{1}{\sigma_1} \left[\frac{\cos N_1 y}{\cos N_1} - 1 \right], \quad N_1^2 = \sigma_1 \quad (13)$$

and the velocity works out to be

$$u^{(0)}(y) = \frac{3}{2} (1-y^2) - \frac{3N_3}{\sigma_1} \left[\frac{1}{\sigma_1} + \frac{1}{3} - \frac{1}{\sigma_1 N_1} \tan N_1 \right] (1-y^2) + \frac{N_3}{\sigma_1} \left[\frac{1}{\sigma_1} + \frac{1}{2} (1-y^2) - \frac{1}{\sigma_1} \frac{\cos N_1 y}{\cos N_1} \right] \quad (25)$$

For $\sigma_1 \rightarrow 0$ we recover an earlier result due to Ostrach (1976),

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$$u^{(0)}(y) = \frac{3}{2} (1-y^2) - \frac{N_3}{120} (1-y^2)(1-5y^2) \quad (26)$$

It is important to note that the magnitude of the buoyancy effect as compared to forced convection is contained in the dimensionless group N_3 , viz.

$$\frac{g\beta}{\nu_o u_o} \frac{\sigma_o E_o^2 d^4}{k_o}.$$

Here β represents an average coefficient of thermal expansion, $-\rho^{-1}(\partial\rho/\partial T)$. Thus, all other things being equal, going from a narrow-gap machine ($2d = 0.15$ cm) to a wide-gap machine ($2d = 0.5$ cm) alters the effect of gravity by a factor of $(10/3)^4$, roughly two orders-of-magnitude. It follows that whereas gravity forces play minor roles with narrow-gap machines the situation with wide-gap machines is quite the opposite.

For $|N_3| \ll 1$ the velocity differs very little from the familiar parabolic profile characteristic of forced convection. For $|N_3| \gg 1$ regions of reverse flow are present as illustrated on Figures 15 and 16. Qualitatively these profiles are similar to those derived from the two-dimensional model; quantitatively, however, they differ in the magnitude of the maximum velocity, which is higher here due to the effects of variable viscosity and buoyancy. Note regions of reversed flow in the center for downflow and adjacent to side walls for upflow (see insets).

The recirculating eddy present in the downflow configuration at *these operating conditions* renders this configuration almost useless for electrophoretic separation. Even if the flow was steady, the sample stream would be deflected towards the wall where electro-osmotic effects would be strong.

FIGURE 15.

One-dimensional velocity field calculated with allowance for variable viscosity and density (cf. Table I). Downflow, $g = 980 \text{ cm/s}^2$. Eq. (23).

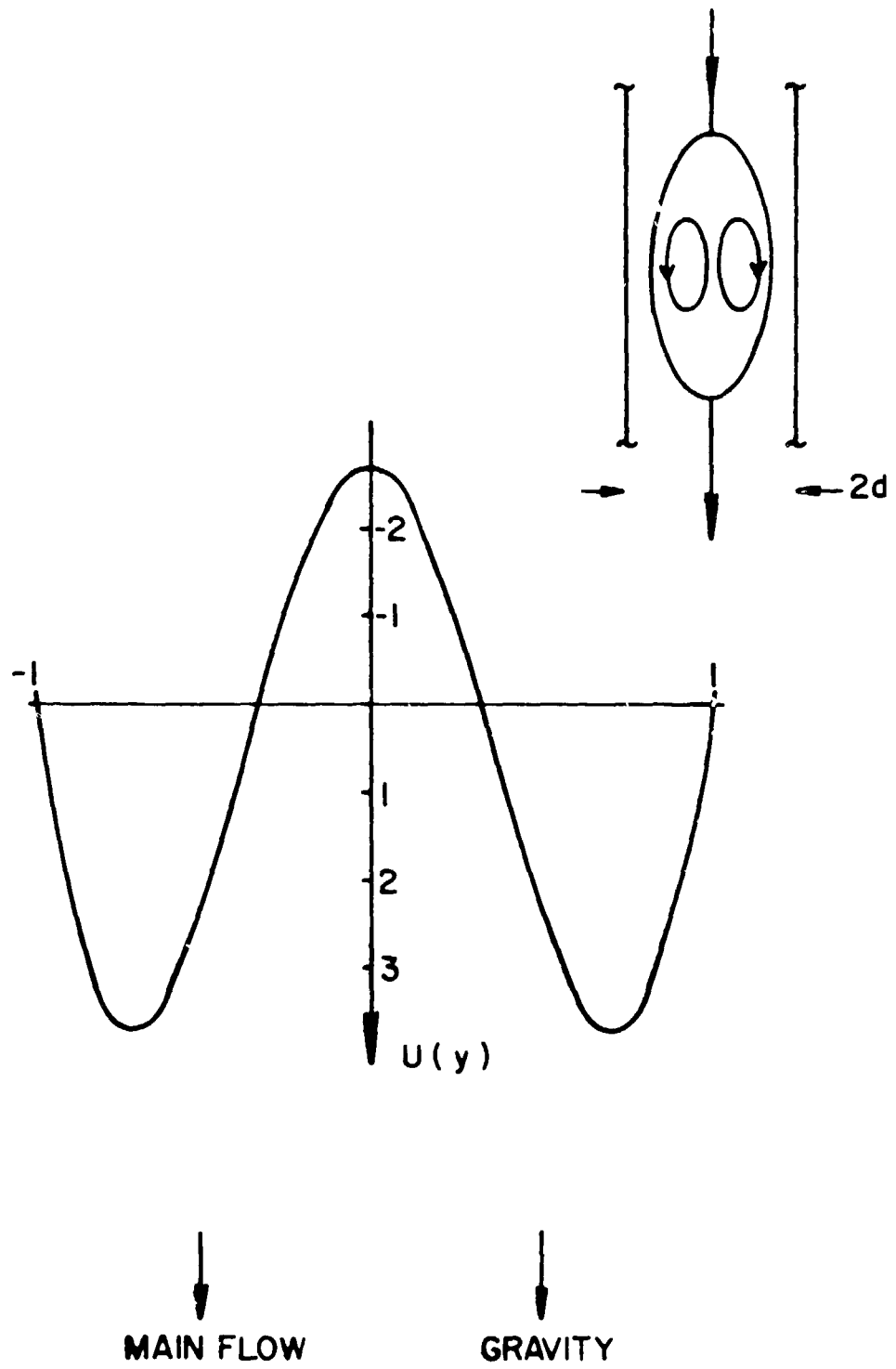
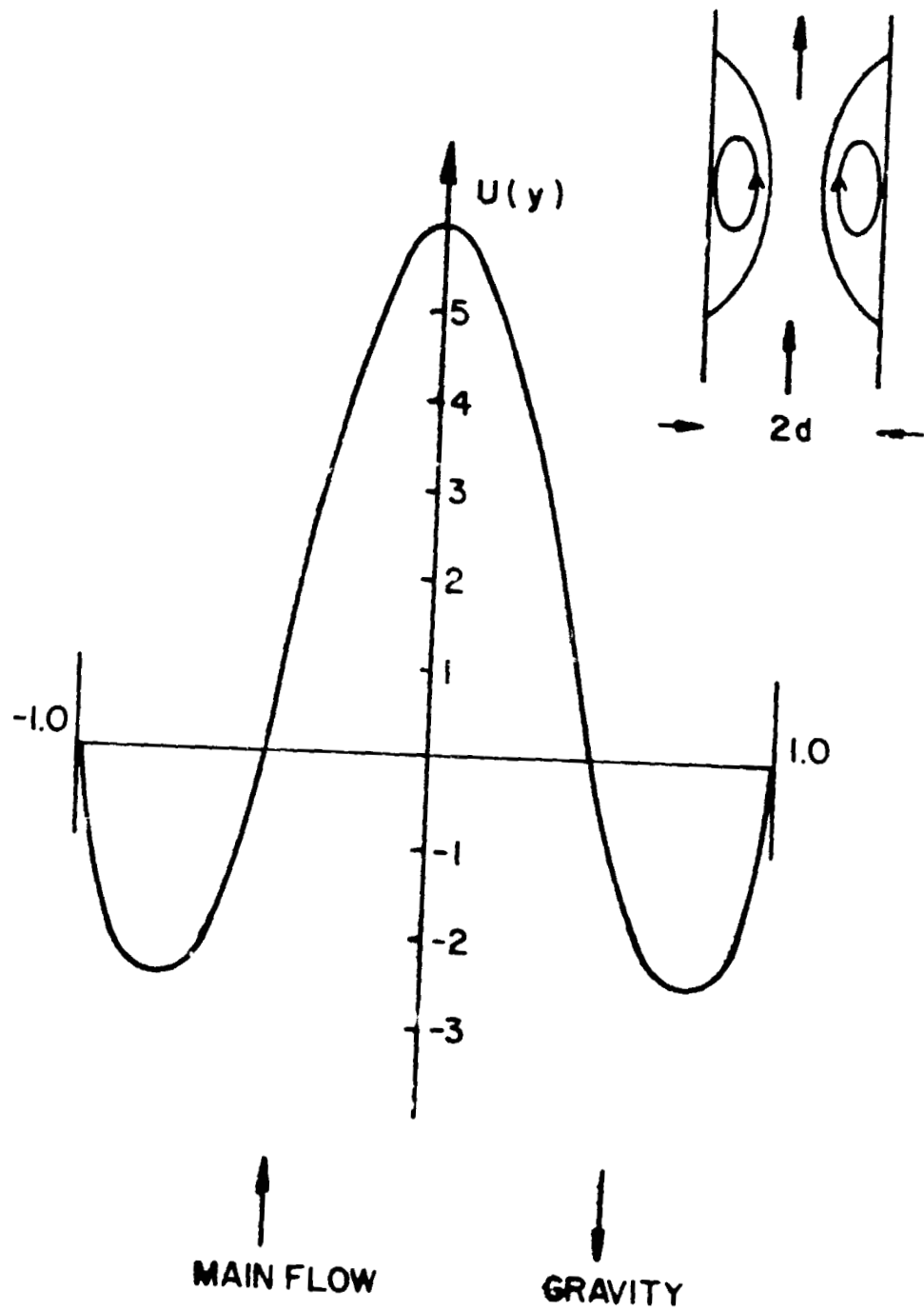


FIGURE 16.

One-dimensional velocity field calculated with allowance for variable viscosity and density (cf. Table I). Upflow, $g = 980 \text{ cm/s}^2$. Eq. (23).

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In the upflow configuration the eddys attached to the walls take up nearly 80% of the cross section and severely reduce the region available for sample separation.

At the same time, however, it must be recognized that the calculations presented here do not exhaust the set of configurations and operating conditions. The recirculations, for example, can be changed by independent control of the pressure gradient. Lowering the field strength has a dramatic effect on the buoyancy, since the temperature rise is proportional to E_0^2 , but would necessitate an increase in the length of the chamber, etc. There are, therefore, a number of options which remain to be investigated, the calculations given here simply illustrate the hydrodynamic phenomena.

Electro-osmotic Cross-flow Velocity Field

The presence of a thin layer of space charge adjacent to the boundaries in the y-z plane (cf. Figure 1) along with the transverse electric field causes a well-known electro-osmotic flow (Shaw, 1969). In a parallel plate system open to reservoirs at $z = \pm H$ where $H \gg 1$ the velocity profile would appear to be flat up to a very small distance from the wall (a few multiples) of the Debye thickness, κ^{-1}) where a rapid transition occurs to accommodate the no-slip condition. For most purposes the double-layer thickness, κ^{-1} is so small that we can approximate the velocity just outside this layer using one of the Smoluchowski equations,

$$w_0 = - \epsilon E_0 \zeta / \mu \quad (27)$$

where w_0 is the velocity in the z-direction, ϵ , the dielectric constant, E_0 , the field strength and, ζ , the zeta-potential of the wall material in

contact with the solution in question. This apparent slip-velocity is of the order of a few microns per second for a potential gradient of one volt per centimeter. When the flow is constrained by walls at $z = \pm H$ the profile is forced to be (roughly) parabolic so as to accommodate the condition of no net flow across the y - z plane. Although this velocity is too slow to affect the axial flow substantially the cross-flow interferes with any electrophoretic separation by stretching the sample cross section. To provide an estimate of thermal effects and furnish a consistent representation of the velocity field for use in the separations model a simplified model is used. In this model end effects are omitted except insofar as the walls force the flow to turn round as sketched in Figure 17. The electro-osmotic velocity can be calculated from solutions to

$$0 = -\frac{\partial p}{\partial z} + \frac{\partial}{\partial y} \mu \frac{\partial w}{\partial y} \quad (28)$$

with $w = w_0$ at $y = \pm d$.

The pressure gradient arises from the need to balance viscous forces outside the double-layer so as to produce a field with no net flow. If we scale the velocity using w_0 , and lengths using d , and write the viscosity as $\mu_0 \mu(\theta)$ to account for the thermal effects we obtain

$$0 = K_2 + \frac{d}{dy} \mu \frac{dw}{dy} \quad (29)$$

which can be integrated to

$$w = K_2 \int_1^y \frac{y_1}{\mu} dy_1 - 1 \quad (30)$$

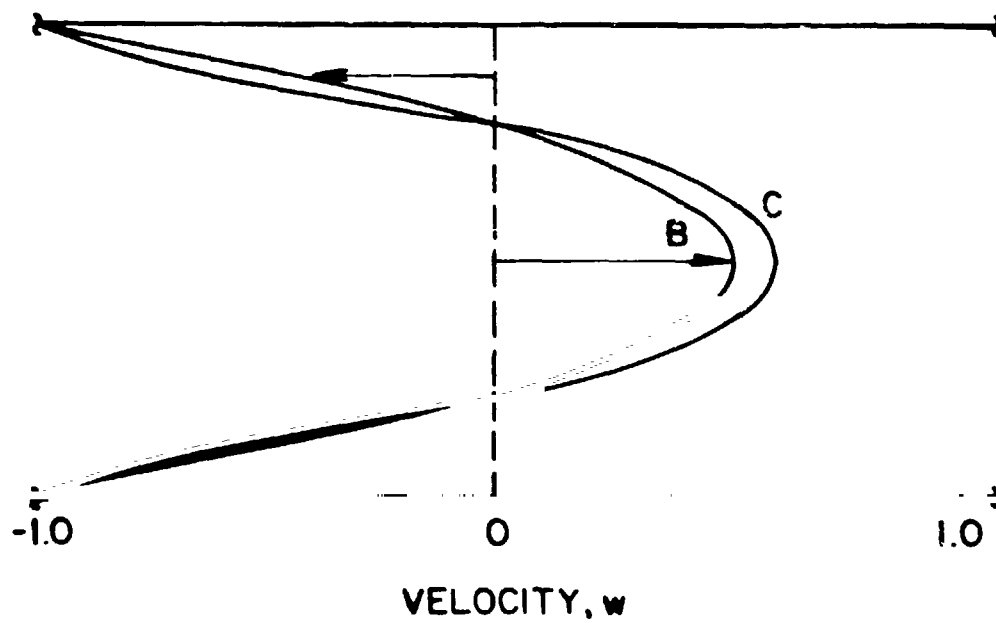
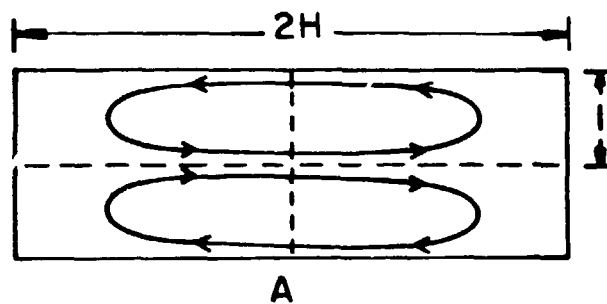
The constant k_2 is found from the requirement that the net flow across any cross section in the x-y plane be zero.

Although effects due to temperature dependent viscosity are relatively small and change the velocity only about 10% in the wide-gap chamber, these could be significant if one were modelling the separation of particles with small mobility differences.

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FIGURE 17.

Electro-osmotic crossflow velocity: A - plan view showing recirculation caused by end walls, B - velocity profile with constant viscosity, $(1 - 3y^2)/2$; C - velocity profile with wide-gap (cf. Table I).



II. HYDRODYNAMIC STABILITY

Introduction

During the early stages of development of the wide-gap machines large scale, irregular convective mixing was observed during experiments with dye tracers. One of the possible causes is the flow reversal caused by buoyancy (see Part I and Ostrach, 1976). At that time, the absence of quantitative data prevented a test of this hypothesis. Later experiments at General Electric by H. Semon (1977) provided additional data and disclosed a persistent "wavering" of the sample stream at low power inputs; higher power levels caused irregular mixing. However, the power levels corresponded to maximum (centerline) temperatures only a few degrees higher than the wall (buffer) temperature, far below those which could produce the w-shaped profiles described in Part I. According to the analysis in Section I the dimensionless group $g\beta_0 E_0^2 d^4 / \nu_0 k_0 u_0$ must be $O(10^2)$ or more for buoyancy to alter the velocity profile significantly; in the General Electric experiments it was $O(1)$. Changes in the orientation of the flow relative to gravity changed the allowable power levels somewhat but irregular flow persisted at voltage gradients necessary to give a significant electrophoretic separation. It was decided, therefore, to investigate the hydrodynamic stability of the flow.

Several sorts of phenomena are included under the general topic of hydrodynamic stability: the inception of motion in an otherwise quiescent system, the transition from one steady laminar flow to another and transition from laminar to turbulent flow. To establish orders-of-magnitude, theories for the stability of a horizontal layer and of a shear flow were reviewed. As a result it appears that neither of the buoyancy mechanisms involved in these

two situations would be able to destabilize the flow.

Previous work on the stability of stratified fluid layers has centered on quiescent layers (cf. Chandrasekhar, 1961; Ostrach, 1964). This body of literature was combed to locate reports of special significance to the problem at hand which is distinguished by the combined processes of volumetric heat generation and fluid motion. Sparrow, Goldstein and Jonsson (1964) studied the buoyancy driven instability of a quiescent, horizontal layer bounded above and below by rigid walls and heated internally. Although a nonlinear profile does lower the critical temperature difference considerably, calculations based on parameter values for the wide-gap chamber showed that the critical difference is about 10°C which is well above the values reported by General Electric for the horizontal (or vertical) configuration with flow. Allowance for the effect of temperature on the rate of heat generation (which is not part of the Sparrow-Goldstein-Jonsson theory) may lower the critical temperature difference somewhat but an extension of this sort was not attempted, since it seemed best to understand the behavior of the vertical configuration which would be used in electrophoretic separation.

Vest and Arpaci (1969) studied the stability of natural convection in a vertical slot, where however, since the base flow is driven by an anti-symmetric temperature, it is different from that in a continuous flow electrophoresis chamber. The stability with respect to roll waves, oriented perpendicular to the main flow was examined and a critical Grashof number of 7880 was found for this sort of instability. In the General Electric experiment the Grashof number based on the maximum centerline temperature is roughly 10 and, although the circumstances are quite dissimilar, it seems unlikely

that the observed meandering derives from a shear instability of the sort studied by Vest and Arpaci.

If the meandering and subsequent large scale convection are the result of an instability, then it must be one where the critical Rayleigh number is small. One possibility is that the instability derives from small axial temperature gradients which result from uneven heating or cooling. In addition the thermal region near the entrance to the electrode section extends over a region of several chamber half-thicknesses. This gradient can be estimated from an earlier equation describing the balance between convection, conduction and generation,

$$Pe \, u(y) \frac{\partial \theta(0)}{\partial x} = \frac{\partial^2 \theta(0)}{\partial y^2} + 1 + \sigma_1 \theta(0) \quad (8)$$

for temperature-independent properties. This equation has solutions which decay exponentially with x and have the form

$$e^{-\lambda_n^2 x} Pe^{-1} f_n(y)$$

The mode which has the smallest eigenvalue, λ_n , fixes the relaxation distance, x_e . An estimate of the smallest eigenvalue can be found from the problem where the variable velocity $u(y)$ is approximated by the (constant) average velocity. A more exact calculation would refine this estimate but would not change the order-of-magnitude. It is found that the distance over which the temperature adjusts to the ohmic heating is approximately $(Pe)(d)$. For the wide-gap chamber operation at the conditions listed on Table I the Peclet number is about 50. Thus, since the temperature rise here is over 30 degrees, axial gradients at the inlet (and outlet) are of the order of $1^\circ\text{C}/\text{cm}$.

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Stability of a Fully Developed Flow with an Axial Temperature Gradient

The presence of cold fluid above warmer fluid (in the region above the electrodes with the downflow configuration and in the electrode "outlet" region with upflow) is an unstable configuration. To study the stability of the velocity and temperature fields they were modelled with a fully developed axial flow in a rectangular channel. The basic temperature field consists of an axial gradient of magnitude denoted by A , with lateral variations due to the balance between heat generation and conduction through the walls, i.e.,

$$T = T_w + Ax + \Delta T \theta(y, z) \quad (31)$$

If we scale lengths, velocities, etc., as before we obtain

$$\frac{\partial u}{\partial \tau} = - \frac{\partial p}{\partial x} + N_2(1 - \beta \Delta T) - \frac{Ra}{Pr Re} x - \frac{Gr}{Re} \theta + \nabla^2 u \quad (32)$$

$$Pr \frac{\partial \theta}{\partial \tau} + \frac{Ra Re}{Gr} u = \nabla^2 \theta + 1 \quad (33)$$

where

$$Gr = g \beta \Delta T d^3 / \nu_0^2 \quad \text{Grashof number}$$

$$Ra = g \beta A d^4 / \nu_0 \alpha_0 \quad \text{Rayleigh number}$$

$$Re = u_0 d / \nu_0 \quad \text{Reynolds number}$$

$$Pr = \nu_0 / \alpha_0 \quad \text{Prandtl number}$$

with $u = \theta = 0$ on boundaries at $y = \pm 1$, $z = \pm H$.

The mathematical problem is to identify conditions under which temperature and velocity fields other than the steady-state, symmetric forms exist. In particular we are interested in forms with an exponential time dependence, $e^{\omega t}$. The demarcation between stable and unstable flows is $\omega = 0$. Because of the linear structure of the equations we can show that the imaginary part of ω , $I_m(\omega)$, is zero so that the so-called "exchange of stabilities" principle is satisfied and any disturbance will grow exponentially. Thus, we simply look for conditions where $\omega = 0$. The problem is decomposed into the sum of the steady parts u, θ and perturbations \hat{u} and $\hat{\theta}$.

This problem is very similar to one solved earlier by Ostrach (1955). Here those results are extended to include two-dimensional effects and other disturbance planforms. In the early work the instability was identified through a degeneracy in a base flow, now we see that the disturbances are superimposed on a symmetric base flow.

For the disturbance flow, \hat{u} , and temperature, $\hat{\theta}$, we have

$$\begin{aligned} \nabla_{II}^4 \hat{u} &= Ra \hat{u} \\ \hat{\theta} &= Ra^{-1} \nabla_{II}^2 \hat{u} \end{aligned} \tag{34}$$

where ∇_{II}^2 stands for the two-dimensional Laplace operator. $\hat{u} = \hat{\theta} = 0$ on the boundaries. One set of solutions will, of course, simply be multiples of the symmetric (with respect to the x-z and x-y planes) steady-state solutions. We are interested in anti-symmetric solutions, which represent no change in the volumetric flow rate through the y-z plane. In general, the solutions to these equations can be written

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$$\hat{u} = u_1 + u_2 \quad (35)$$

where

$$\nabla_{II}^2 u_1 = \lambda^2 u_1 \quad (36)$$

$$\nabla_{II}^2 u_2 = -\lambda^2 u_2$$

$$\lambda^4 = Ra$$

The temperature is

$$\theta = Ra^{-1/2} (u_1 - u_2), \quad (37)$$

Solutions are

$$\begin{aligned} u_1 = & \sin qz (A_1 \sinh \gamma_1 y + B_1 \cosh \gamma_1 y) \\ & + \cos qz (A_2 \sinh \gamma_1 y + B_2 \cosh \gamma_2 y) \\ \gamma_1^2 = & q^2 + \lambda^2 \end{aligned} \quad (38)$$

$$\begin{aligned} u_2 = & \sin qz (A_3 \sinh \gamma_2 y + B_3 \cosh \gamma_2 y) \\ & + \cos qz (A_4 \sinh \gamma_2 y + B_4 \cosh \gamma_2 y) \\ \gamma_2^2 = & q^2 - \lambda^2 \end{aligned}$$

To satisfy the boundary conditions on the walls at $z = \pm H$ either

$$(i) \quad \sin qH = 0, A_2 = B_2 = A_4 = B_4 = 0, \quad q = n\pi/H; \quad (39)$$

or

$$(ii) \quad \cos qH = 0, A_1 = B_1 = A_3 = B_3 = 0, \quad q = \frac{2n-1}{2} \frac{\pi}{H}. \quad (40)$$

The first condition, (i), corresponds to a disturbance that is anti-symmetric with respect to the x - y plane with upflow on one side and downflow on the

other. This form preserves the volumetric flow rate. The second condition, (ii), describes a flow with the requisite asymmetry if $B_2 = B_4 = 0$.

Next, with (i), either $B_1 = B_3 = 0$ so that $A_3 = 0$ and $\gamma_1 = \pm i n \pi$ which gives

$$\lambda^4 = n^4 \pi^4 (1 + H^{-2})^2 \quad (41)$$

or $A_1 = A_3 = 0$ so that $B_3 = 0$ and $\gamma_1 = i(2n - 1)\pi/2$ which gives

$$\lambda^4 = \pi^4 [(2n - 1)^2/4 + n^2/H^2]^2 \quad (42)$$

With (ii), $A_4 = 0$ and $\gamma_2 = \pm i n \pi$ so that

$$\lambda^4 = \pi^4 [n^2 + (2n-1)^2/4H^2]^2 \quad (43)$$

The mode with the lowest critical Rayleigh number corresponds to the velocity field

$$u_1 = \sin \frac{\pi z}{H} \cos \frac{\pi y}{2} \quad (44)$$

with the critical Rayleigh number

$$Ra_c = \frac{\pi^4}{16} (1 + H^{-2})^2 \quad (45)$$

For the wide-gap chamber with dimensions noted on Table I, $Ra_c = 6.58$ and with a narrow-gap, $Ra_c = 6.11$. Using data for water at 10°C the critical temperature gradient is 0.5°C/cm for the wide-gap and 53°C/cm for the narrow-gap chambers. These results agree *qualitatively* with experimental observation in that they disclose a great deal of sensitivity to axial

temperature gradients for the wide-gap machine. With a narrow-gap it would be rather difficult to achieve the axial gradients large enough to excite the instability.

Although this explanation is consistent with experimental findings for a vertical configuration, questions still remain with regard to tilted or horizontal configurations. These cases have not been analyzed in detail but it is easy to show (mathematically) that buoyancy effects coupled with an axial gradient will destroy the unidirectional character of the flow. At present, however, neither experimental data or quantitative theoretical results are sufficient to assess this matter fully.

III. MODELING THE ELECTROPHORETIC SEPARATION IN CONTINUOUS FLOW ELECTROPHORESIS

Introduction

We turn now to the task of describing how a sample with a particular mobility distribution will be altered in its passage through a continuous flow electrophoresis chamber. To provide a first approximation we have chosen to base the model on one-dimensional approximations to the various flow and temperature fields and ignore, for the present, two-dimensional effects due to side walls at $z = \pm h$ (except insofar as they cause the electro-osmotic flow to recirculate). Consequently, the temperature and velocity fields and the particle mobility are functions of y alone. This procedure is accurate as long as $d/h \ll 1$ and regions near the side walls are ignored. The effect of the side walls requires much more extensive analysis and remains to be done.

The model for separation is based on the fact that the velocity of a particle of a given mobility can be written as a superposition of an axial velocity, $u(y)$, and a transverse component made up of the electro osmotic flow velocity, $w(y)$ and the particle velocity due to electrophoresis, $v_m(y)$. Thus for a particle of mobility, m , say, the velocity is

$$\hat{u}(y) + \hat{k}[w(y) + v_m(y)] \quad (46)$$

and particles which enter with the sample at y_0, z_0 will exit at $y = y_0$, $z = z_0 + L[w(y) + v_m(y)]/u(y)$. If we denote the mobility distribution as $N_m(x, y, z)$, to represent the number density of particles with mobility, m , then

$$u(y) \frac{\partial N_m}{\partial x} + [w(y) + v_m(y)] \frac{\partial N_m}{\partial z} = 0 \quad (47)$$

describes the fact that the particles are conserved. The number density at a point x, y, z , is, therefore,

$$N_m\{0, y, z - x[w(y) + v_m(y)]/u(y)\}$$

and the problem is simply one of "tracking".

To predict the mobility distributions at the exit from the separator we suppose that there are a number of collector tubes of area $(2d)(\Delta)$ at the outlet plane. The mobility distribution in a given collector is simply

$$\langle N_m \rangle_i = \frac{1}{\Delta} \int_{z_i}^{z_i + \Delta} \bar{N}_m(z) dz \quad (48)$$

$$\bar{N}_m(z) = \frac{\int_{-d}^d N_m(L, y, z) u(y) dy}{\int_{-d}^d u(y) dy} \quad (49)$$

A computer program was written to implement this scheme; representative results are tabulated in Table II.

Outline of the Computation Method

The computation of the mobility distribution in the collection streams proceeds as follows

Main Input Data are:

Chamber dimensions ($2d$ and $2h$)

Electrode length (ℓ)

Number of collection streams

Electric field strength

Buffer flowrate

Buffer temperature

Constants in the linear equation for buffer electrical conductivity

Constants in the linear equation for buffer thermal conductivity

Buffer conductivities for heat and electricity at the wall temperature

Coating mobility at 20°C

Mobility distribution of sample at 20°C

Location and size of sample stream.

The program then evaluates the temperature field using Eqs. (7), (13) and (15) and calculates the local values of density and viscosity using analytical formulas supplied. (Other relations can be used if necessary.) Then the local axial and electro-osmotic velocities are calculated using the appropriate equations for temperature dependent properties cited in Part I, Eqs. (23) and (30). Finally, particles on the edge of the sample are tracked to the outlet, using mobilities which reflect the local temperature, and the mobility distribution for each collector calculated. Numerical output includes

Temperature field

Axial velocity field

Electro-osmotic velocity field

Mobility distribution for each collector.

Results of two representative calculations, one with a narrow-gap chamber, the other with a wide-gap, are shown on Table II. General conditions are as shown on Table I. The sample contained two types of particles in equal amounts. Although both configurations show complete separation the wide-gap configuration separates the sample into two widely spaced collectors; the narrow-gap chamber barely separates the two fractions and if either fraction contained a distribution of mobilities there would be overlap. It was not possible to operate the wide-gap chamber model at 1-g without the recirculating flows described in Part II - so gravity had to be suppressed in the calculation.

These calculations are intended to be *illustrative* of the sorts of results that can be obtained using the models derived here. Much more extensive calculations are required to establish the differences in the separatory capabilities of various continuous flow devices.

TABLE I.

Parameters used in numerical calculations

Fluid Properties (A-1 Buffer)

Buffer Temperature	10	°C
Density	1.0	g/cm ³
Viscosity	1.33×10^{-2}	g/cm-s
Thermal Conductivity	5.82×10^{-3}	watts/cm-°C
Electrical Conductivity	6.9×10^{-4}	(ohm-cm) ⁻¹
Coefficient of Expansion	8.62×10^{-5}	(°C) ⁻¹
Thermal Conductivity Coefficient	2.58×10^{-3}	(°C) ⁻¹
Electrical Conductivity Coefficient	3.12×10^{-2}	(°C) ⁻¹

Chamber Parameters

	<u>Narrow-Gap</u>	<u>Wide-Gap</u>
Electric Field Strength, v/cm	70	70
Gravitational Constant*, cm/s ²	980	980
Gap Distance (2d), cm	0.15	0.5
Width (2h), cm	5	5
Length, cm	16	10
Volumetric Flow, cm ³ /s	0.35	0.7
Average Velocity, cm/s	0.467	0.28
ΔT_T , °C	3.17	35.2
Re	2.63	5.26
N ₂	8.88×10^2	1.64×10^4
N ₃	2.4×10^{-1}	4.98×10^1
k ₁	8.2×10^{-3}	9.1×10^{-2}
σ_1	9.9×10^{-2}	1.1

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* except where noted

TABLE II

Red-Blood Cell Separation in Narrow-Gap and Wide-Gap Machines

To demonstrate the use of the separation model two runs were made at conditions shown on Table I with samples made up of equal amounts of particles ('red-blood cells') with mobilities of $2.15 \mu\text{m-cm/v-s}$ ($m=1$) and $4.15 \mu\text{m-cm/v-s}$ ($m=2$) (at 20°C).

Other conditions were:

Coating mobility $2.15 \mu\text{m-cm/v-s}$

Sample inlet size 0.05 cm

Number of collectors 100

Locations of Separated Particles

Narrow-Gap Chamber

Chamber #	<u>1-13</u>	<u>14</u>	<u>15</u>	<u>16</u>	<u>17</u>	<u>18</u>	<u>19</u>	<u>20</u>	<u>21-100</u>
$m = 1$	0	.177	.590	.233	0	0	0	0	0
$m = 2$	0	0	0	0	.159	.477	.353	.021	0

Wide-Gap Chamber^{*}

Chamber #	<u>1-20</u>	<u>21</u>	<u>22</u>	<u>23</u>	<u>24-29</u>	<u>30</u>	<u>31</u>	<u>32</u>	<u>33-100</u>
$m = 1$	0	.043	.546	.411	0	0	0	0	0
$m = 2$	0	0	0	0	0	.282	.610	.108	0

* $g = 0$

ACKNOWLEDGMENTS

Dr. R.S. Snyder of MSFC, Dr. G.V.F. Seaman of the University of Oregon and Dr. R.N. Griffin of General Electric have each helped us to understand the many problems involved in the electrophoresis of small particles. Kurt Hebert of Princeton University did much of the computer programming.

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COMPUTER PROGRAMS

Four programs were written in FORTRAN IV:

ZTEMP - the two-dimensional temperature field, Eq. (12)

VELO - the two-dimensional velocity field, Eq. (19)

TRANST - the transient temperature field, Eq. (17)

TEMP - the separation model.

Listings of these are given on the following pages.

ORIGINAL PAGE IS
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FORTRAN IV G LEVEL 21

MAIN

DATE = 78110

09/10/45

```

C
C
C *****
C *
C * ZTEMP DETERMINES THE TEMPERATURE IN THE ELECTROPHORESIS CELL AS A
C * FUNCTION OF BOTH Y AND Z. THROUGH A CALL TO THE PROCEDURE PERVUE, IT
C * THEN PLOTS A PERSPECTIVE VIEW OF THE TEMPERATURE SURFACE. ZTEMP ACCUMULATES
C * AS INPUT PARAMETERS VALUES OF THESE VARIABLES--
C *
C * SIGMA1 - PARAMETER IN THE EXPRESSION FOR ELECTRICAL CONDUCTIVITY.
C * BI - THE BICI NUMBER
C * W - THE ASPECT RATIO OF THE CHANNEL
C * NTERMS - THE NUMBER OF TERMS TO BE TAKEN IN THE SERIES FOR TEMPERATURE
C * TURE
C * NYPTS - THE NUMBER OF EQUALLY SPACED CONSTANT-Y LINES FROM (AND
C * INCLUDING) Y=0 TO Y=1 ALONG WHICH TEMPERATURE IS EVALUATED.
C * NZPTS - THE NUMBER OF EQUALLY SPACED CONSTANT-Z LINES FROM (AND
C * INCLUDING) Z=0 TO Z=W ALONG WHICH TEMPERATURE IS EVALUATED.
C *
C *****
C
C
0001 DIMENSION TEMP (201,101),
      X YY (101),
      X ZZ (101),
      REAL LAMBDA, LAMBDA2
0002 100 FORMAT (1H1)
0003 110 FORMAT ('0', 'SIGMA1 =', 1P59.2, 4X, 'NO. TERMS =', 17, 2X,
0004 X 'ASPECT RATIO =', 1P59.2/'0', 'BICI NO. =', 1P59.2, 2X,
      X 'NO. Y POINTS =', 14, 2X, 'NO. Z POINTS =', 14,
0005 101 FORMAT ('0', 9X, '2', 10X, 'TEMPERATURE')
0006 130 FORMAT (' ')
0007 103 FORMAT ('2 (2X, 1P14.6)')
0008 150 FORMAT ('3E10.3, 3I5')
0009 READ (5, 150) SIGMA1, BI, W, NTERMS, NYPTS, NZPTS
0010 PI=3.1415926
C
C
0011 CY=1./ (NYPTS-1.)
0012 CZ=W/ (NZPTS-1.)
C
C THE OUTER LOOP INCREMENTS Y, THE NEXT INNERMOST LOOP INCREMENTS Z, AND THEN
C INNERMOST TWO LOOPS TAKE THE SERIES FOR TEMPERATURE OUT TO NTERMS TERMS.
C THE PROGRAM STORES THE TEMPERATURE IN THE ARRAY TEMP(I,J), WITH INDICES I
C J REFERRING TO THE Y-DIRECTION COORDINATE AND Z-DIRECTION COORDINATE
C RESPECTIVELY. THE ACTUAL Y AND Z COORDINATES ARE STORED IN ARRAYS YY AND ZZ
C
0013 Y=-CY
0014 DO 30 I=1, NYPTS
0015 Y=Y+CY
0016 A=PI*(1.+Y)/2.
0017 Z=-CZ
0018 DO 20 J=1, NZPTS
0019 Z=Z+CZ
0020 SUB=C.
0021 DO 10 K=1, NTERMS

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PORTMAN IV G LEVEL 21

MAIN

DATE = 78110

09/10/45

0022		N=2*K-1	J570
0023		LAMBDA2=N*N*Z1*FI/4.-SIGMA1	0580
0024		T=(1.-(-1.)**N)/N/LAMBDA2	0590
0025		LAMBDA=LAMBDA2**0.5	0600
0026		AE1=LAMBDA*(Z-W)	0610
0027		AE2=-LAMBDA*(Z+W)	0620
0028		AE3=-2.*LAMBDA*N	0630
0029		IF (AE1+50.) 1,1,2	0640
0030	1	E1=0.	0650
0031		GO TO 3	0660
0032	2	E1=EXP(AE1)	0670
0033	3	IF (AE2+50.) 4,4,5	0680
0034	4	E2=0.	0690
0035		GO TO 6	0700
0036	5	E2=EXP(AE2)	0710
0037	6	IF (AE3+50.) 7,7,8	0720
0038	7	E3=0.	0730
0039		GO TO 9	0740
0040	8	E3=EXP(AE3)	0750
0041	9	CONTINUE	0760
0042		I'=(E1+E2)/(LAMBDA*(1.-E3)-E1*(1.+E3))	0770
0043		Z=C+T*BI*T1	0780
0044	10	SUM=SUM+E*SIGN(N*K)	0790
0045		TEMP(J,I)=2.*SUM/PI	0800
0046	20	ZZ(J)=Z	0810
0047	30	YY(I)=Y	0820
0048		TEMP1=TEMP(1,1)	0830
			0840
			0850
			0860
			0870
			0880
			0890
			0900
			0910
			0920
			0930
			0940
			0950
			0960
			0970
			0980
			0990
			1000
			1010
			1020
			1030
			1040
			1050
			1060
			1070
			1080
			1090
			1100
			1110
			1120

PLCI THE TEMPERATURE FIELD AS A SURFACE VIEWED IN PERSPECTIVE.

0049		K=2*NYPTS	
0050		DO 60 I=1, NYPTS	
0051		K=K-1	
0052		L=2*NZPTS	
0053		DO 50 J=1, NZPTS	
0054		L=L-1	
0055	50	TEMP(L,K)=TEMP(NZPTS+1-J, NYPTS+1-L)	
0056	60	CONTINUE	
0057		NYM=NYPTS-1	
0058		NZM=NZPTS-1	
0059		K=2*NYPTS	
0060		DO 62 I=1, NYPTS	
0061		K=K-1	
0062		DO 62 J=1, NZM	
0063	62	TEMP(NZPTS-J,K)=TEMP(NZPTS+J,K)	
0064		NY=NYPPTS-1	
0065		NZ=NZPTS-1	
0066		DO 65 J=1, NZ	
0067		DO 65 I=1, NYM	
0068	65	TEMP(J, NYPTS-I)=TEMP(J, NYPTS+I)	
0069		Z=-T2-W	
0070		DO 70 J=1, NZ	
0071		Z=Z+LZ	
0072	70	ZZ(J)=Z	
0073		Y=-LY-1.	
0074		DO 80 I=1, NY	

FORTRAN IV G LEVEL 21

MAIN

DATE = 78110

09/10/45

0075	Y=Y+CY	1130
0076	8) YY(1)=Y	1140
0077	JT=1F*E1*10.+1.	1150
0078	NCONIB=JT*2	1160
0079	TMAX=JT/10.	1170
	C	1180
	C PRINT THE FIELD FOR Y=0.	1190
	C	1200
0080	WRITE (6,100)	1210
0081	WRITE (6,110) SIGMA1, NTERMS, W, BI, NYPTS, NZPTS	1220
0082	WRITE (6,101)	1230
0083	WRITE (5,120)	1240
0084	DO 40 J=1, N2	1250
0085	40 WRITE (6,103) ZZ(J), TEMP(J, NYPTS)	1260
	C	1270
	C PRINT THE FIELD FOR Z=0.	1280
	C	1290
0086	WRITE (6,102)	1300
0087	102 FORMAT ('J', 9X, 'Y', 10X, 'TEMPERATURE')	1310
0088	DO 41 I=1, NY	1320
0089	41 WRITE (6,103) YY(I), TEMP(NZPTS, I)	1330
0090	CALL PELVUF (11, 22, YY, 1E+6, 4+0.5, 4., TMAX+1.5, 201, 101, NZ, NY, C,	1340
	X NCONIB, J, -.1, TMAX, 0, 0, 0, 9., 4., -1, 17, 'TEMPERATURE FIELD')	1350
0091	STOP	1360
0092	END	1370

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FORTRAN IV G LEVEL 21

MAIN

DATE = 78110

03/14/24

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C
C
C
C *****
C *
C * VELO DETERMINES THE DOWNWARD VELOCITY IN THE ELECTROPHORESIS CELL AS A
C * FUNCTION OF BOTH Y AND Z. THROUGH A CALL TO THE PROCEDURE PERVUE, 11
C * THEN PLOTS A PERSPECTIVE VIEW OF THE VELOCITY SURFACE.
C
C *      SIGNAL -PARAMETER IN THE EXPRESSION FOR THE ELECTRICAL
C *              CONDUCTIVITY
C *      SI      -THE SIOT NUMBER
C *      W       -THE ASPECT RATIO OF THE CHANNEL
C *      NTERMS  -THE NUMBER OF TERMS TO BE TAKEN IN THE SERIES FOR THE
C *              VELOCITY
C *      NYPTS   -THE NUMBER OF EQUALLY SPACED CONSTANT-Y LINES FROM (AND
C *              INCLUDING) Y=0 TO Y=1 ALONG WHICH THE VELOCITY IS
C *              EVALUATED
C *      NZPTS   -THE NUMBER OF EQUALLY SPACED CONSTANT-Z LINES FROM (AND
C *              INCLUDING) Z=0 TO Z=W ALONG WHICH VELOCITY IS EVALUATED
C *
C *****
C
C
0001      DIMENSION U(201,101),YY(101),ZZ(201)
0002      REAL BASEDA,LAMBDA2,N2,N3
0003      100 FORMAT (1H1)
0004      110 FORMAT (' ',2X,'SIGNAL =',E10.3,2X,'SIOT NO. =',E10.3,2X,
0005      ' ',2X,'ASPECT RATIO =',E10.3,2X,'N2 =',E10.3,2X,'N3 =',E10.3)
0006      111 FORMAT (' ',2X,'NTERMS =',I5,2X,'NYPTS =',I5,2X,'NZPTS =',I5)
0007      120 FORMAT (' ',9X,'Z',11X,'X VELOCITY')
0008      130 FORMAT (' ')
0009      140 FORMAT (2(2X,1P,14.6))
0010      150 FORMAT (5F10.3,3I5)
0011      160 FORMAT (' ',9X,'Y',11X,'X VELOCITY')
0012      READ (5,15),END=999) SIGNAL,SI,N2,N3,NTERMS,NYPTS,NZPTS
0013      WRITE (6,100)
0014      WRITE (6,111) SIGNAL,SI,N2,N3
0015      WRITE (6,111) NTERMS,NYPTS,NZPTS
0016      DMIN=0.
0017      DMAX=0.
0018      FI=3.1415926
0019      FI2=FI*FI
0020      FI24=FI2/4.
0021      FI4=FI/4.
0022      FIW=FI*W
0023      WEI2=FI2*W/2.
0024      TPI=2./PI
0025      SUM1=0.
0026      SUM2=0.
0027      SUM3=0.
0028      K=-1
C
C DETERMINE THE CONSTANT, K, FROM THE INTEGRATED VELOCITY.
C
C      DO 5 N=1,NTERMS

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PORTMAN IV G LEVEL 21

MAIN

DATE = 76110

09/14/24

0029	K=K+2	0570
0030	LAMBDA2=K*K*PI24-SIGMA1	0580
0031	LAMBDA=LAMBDA2**0.5	0590
0032	FN2=K*K	0600
0033	FN4=FN2*FN2	0610
0034	F1=F1/K	0620
0035	PTANH1=TANH(X*F12)	0630
0036	PTANH2=TANH(LAMBDA*W)	0640
0037	S1=(21*PTANH1-W)/FN4	0650
0038	S2=S1/LAMBDA2	0660
0039	S3=((21*PTANH1-PTANH2/LAMBDA)/(LAMBDA*PTANH2-BI))/FN2/LAMBDA2	0670
0040	SUM1=SUM1+S1	0680
0041	SUM2=SUM2+S2	0690
0042	SUM3=SUM3+S3	0700
0043	CONTINUE	0710
0044	A1=SUM1*32./W/(PI**4)	0720
0045	A2=SUM2*32./W/(PI**4)	0730
0046	A3=SUM3*32./SIGMA1/F1/PI/W	0740
0047	FK=(1.+A2*A1-N3*A2-N3*BI*A3)/A1	0750
0048	WRITE (6,112) FK	0760
0049	112 FORMAT (' ',2X,E10.3)	0770
	C	0780
	C EVALUATE VELOCITY AT EACH (Y,2) POINT TAKEN.	0790
	C	0800
0050	DY=1./(NYPTS-1.)	0810
0051	DZ=1./(NZPTS-1.)	0820
0052	Y=-DY	0830
0053	FK1=FK-N2	0840
0054	F1=8./PI2	0850
0055	F2=2.*N3*EI/SIGMA1	0860
0056	DO 30 I=1,NYPTS	0870
0057	Y=Y+DY	0880
0058	Z=F1*(1.+Y)/2.	0890
0059	Z=-DZ	0900
0060	DO 20 J=1,NZPTS	0910
0061	Z=Z+DZ	0920
0062	SUM=0.	0930
0063	K=-1	0940
0064	DO 10 N=1,NTERMS	0950
0065	K=K+2	0960
0066	LAMBDA2=K*K*PI24-SIGMA1	0970
0067	LAMBDA=LAMBDA2**0.5	0980
0068	FK3=K**3	0990
0069	PTANH=TANH(LAMBDA*W)	1000
0070	C1=F1*(FK1+N3/LAMBDA2)/FK3	1010
0071	C3=F2/K/LAMBDA2	1020
0072	C2=C3/(LAMBDA*PTANH-BI)	1030
0073	ARG1=K*(Z-b)/TPI	1040
0074	ARG2=-K*(Z+b)/TPI	1050
0075	ARG3=-K*F1W	1060
0076	ARG4=LAMBDA*(Z-b)	1070
0077	ARG5=-LAMBDA*(Z+b)	1080
0078	ARG6=-2.*LAMBDA*W	1090
0079	IF (ARG1.LE.-100.) E1=0.	1100
0080	IF (ARG1.GT.-100.) E1=EXP(ARG1)	1110
0081	IF (ARG2.LE.-100.) E2=0.	1120

ORIGINAL PAGE 2
OF POOR QUALITY

FORTRAN IV G LEVEL 21

MAIN

DATE = 7-11-70

09/14/74

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0082      IF (ARG2.GT.-100.) E2=EXP(ARG2)      1130
0083      IF (ARG3.LE.-100.) E3=0.             1140
0084      IF (ARG3.GT.-100.) E3=EXP(ARG3)       1150
0085      IF (ARG4.LE.-100.) E4=0.             1160
0086      IF (ARG4.GT.-100.) E4=EXP(ARG4)       1170
0087      IF (ARG5.LE.-100.) E5=0.             1180
0088      IF (ARG5.GT.-100.) E5=EXP(ARG5)       1190
0089      IF (ARG6.LE.-100.) E6=0.             1200
0090      IF (ARG6.GT.-100.) E6=EXP(ARG6)       1210
0091      E=(E1+E2)/(1.+E3)                    1220
0092      A1=C1+E                               1230
0093      A2=C2+E                               1240
0094      A3=-C3*(E4+E5)/(LAMBDA*(1.-E6)-E1*(1.+E6)) 1250
0095      A4=-C1                                1260
0096      SUM=SUM+(A1+A2+A3+A4)*SIN(A*X)        1270
0097      CONTINUE                             1280
0098      U(J,I)=-2.*SUM/PI                    1290
0099      IF (J(J,I).LE.UNIM) UMIN=U(J,I)       1300
0100      IF (U(J,I).GE.UMAX) UMAX=U(J,I)       1310
0101      ZC(J)=Z                             1320
0102      YC(I)=Y                             1330
C                                           1340
C      PLOT THE VELOCITY FIELD AS A SURFACE VIEWED IN PERSPECTIVE. 1350
C                                           1360
0103      K=2*NYPTS                            1370
0104      DO 60 I=1,KYPTS                      1380
0105      A=K-1                                1390
0106      L=2*NZPTS                            1400
0107      DO 50 J=1,NYPTS                     1410
0108      L=L-1                                1420
0109      U(L,K)=U(NYPTS+1-J,NYPTS+1-I)       1430
0110      50 CONTINUE                         1440
0111      NY=NZPTS-1                          1450
0112      NZ=NZPTS-1                          1460
0113      K=2*NYPTS                            1470
0114      DO 62 I=1,NYPTS                     1480
0115      K=K-1                                1490
0116      DO 62 J=1,NZPTS                     1500
0117      62 U(NZPTS-J,K)=U(NZPTS+J,K)         1510
0118      NZ=2*NZPTS-1                        1520
0119      NY=2*NYPTS-1                        1530
0120      DO 65 J=1,NZ                        1540
0121      DO 65 I=1,NY                        1550
0122      65 U(J,NYPTS-I)=U(J,NYPTS+I)       1560
0123      U(1,1)=0.                          1570
0124      U(NZ,1)=0.                          1580
0125      U(1,NY)=0.                          1590
0126      U(NZ,NY)=0.                        1600
0127      Z=-LZ-W                             1610
0128      DO 70 J=1,NZ                        1620
0129      Z=Z+LZ                              1630
0130      70 ZC(J)=Z                          1640
0131      Y=-DY-1.                             1650
0132      DO 80 I=1,NY                        1660
0133      Y=Y+DY                              1670
0134      80 YY(I)=Y                          1680

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PORTMAN IV C LEVEL 21

MAIN

DATE = 76110

09/14/24

0135	WRITE (6,120)	1690
0136	WRITE (6,130)	1700
0137	DO 40 I=1,NZ	1710
0138	40 WRITE (6,140) ZZ(I),U(I,NYPTS)	1720
0139	WRITE (6,160)	1730
0140	WRITE (6,130)	1740
0141	DO 90 I=1,NY	1750
0142	90 WRITE (6,140) YY(I),U(NZPTS,I)	1760
0143	UMIN=1.1*UMIN	1770
0144	UMAX=1.1*UMAX	1780
0145	CALL PERVEE(11,ZZ,YY,U,U+.5,3.,3.,201,101,NZ,NY,0,10,0,UMIN,UMAX, X 0,0,0,9.,9.,-1,14,'VELOCITY FIELD')	1790
0146	999 STOP	1800
0147	END	1810
		1820

FORTRAN IV G LEVEL 21

MAIN

DATE = 7E104

15/00/50

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C
C
C .....
C *
C * TRANSAT DETERMINES THE AVERAGE TEMPERATURE AND CENTER TEMPERATURE OF
C * THE ELECTROPHORESIS CHANNEL AS FUNCTIONS OF TIME. THE REQUIRED INPUT
C * DATA IS LISTED IN THE OUTPUT OF THE PROGRAM. ALL THE INPUT VARIABLES
C * SELF-EXPLANATORY EXCEPT THE FOLLOWING-
C *
C * NUNTAU - THE NUMBER OF TIMES AT WHICH TEMPERATURE IS EVALUATED.
C * CTAU - THE DIMENSIONLESS TIME TO WHICH TEMPERATURE IS EVALUATED
C * NTERMS - THE NUMBER OF TERMS TAKEN FOR TAU = 0 IN THE SERIES FOR
C * TEMPERATURE. FOR TAU GREATER THAN ZERO, THE NUMBER OF TERMS
C * TAKEN IS CONTROLLED BY NUMBER.
C .....
C
0001 DIMENSION CTMP(1001)
0002 DIMENSION AVTIME(1001)
0003 DIMENSION T(1001)
0004 DIMENSION TIME(1001)
0005 DIMENSION NUMBER(1001)
0006 101 FORMAT (7E10.3)
0007 102 FORMAT (21E,2E10.3)
0008 103 FORMAT (1H1)
0009 104 FORMAT ('0','THERMAL CONDUCTIVITY -',1PE10.2,1X,'WATTS/CM-C',2X,
X 'DENSITY -',1PE10.2,1X,'G/CC',2X,'SPECIFIC HEAT -',1PE10.2
X 'CAL/C-G',1X,'ELECTRIC CONDUCTIVITY -',1PE10.2,1X,
X '/OHM-CM',2X,'FIELD STRENGTH -',1PE10.2,1X,'V/CM',1X,
X 'CHANNEL DEPTH -',1PE10.3,1X,'CM',2X,'SUPPORT TEMP. -',1PE10.3
X 'C')
0010 105 FORMAT ('0','NUNTAU =',17,2X,'NTERMS =',17,2X,'SIGMA1 =',1PE10.2,
X 'CTAU =',1PE10.3)
0011 106 FORMAT ('0',6X,'SILICON',9X,'AVTIME-C',6X,'CTEMP-C')
0012 107 FORMAT (' ')
0013 108 FORMAT (3(2X,1PE14.6))
0014 READ (5,101) THCOND,DENSITY,SPHT,ELCOND,IO,DEPTH,TBUFF
0015 READ (5,102) NUNTAU,NTERMS,SIGMA1,CTAU
0016 WRITE (6,103)
0017 WRITE (6,104) THCOND,DENSITY,SPHT,ELCOND,IO,DEPTH,TBUFF
0018 WRITE (6,105) NUNTAU,NTERMS,SIGMA1,CTAU
0019 FN1=SIGMA1**0.5
0020 CSN=CLS(FN1)
0021 PI=3.1415926
0022 A=(1./CSN-1.)/SIGMA1
0023 B=TAN(FN1)/FN1/SIGMA1-1./SIGMA1
0024 CTAU=CTAU/(NUNTAU-1)
C
C COMPUTE THE TIME AND TEMPERATURE SCALES FROM THE DIMENSIONED INPUT VARIABLES
C
0025 TIME=ELCOND*IO*DEPTH*DEPTH/THCOND
0026 TIME=4*DEPTH*DEPTH*DENSITY*SPHT/THCOND*4.1e4
C
C NUMBER SPECIFIES THE NUMBER OF TERMS TAKEN IN THE SERIES FOR TEMPERATURE,

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FORTRAN IV G LEVEL 21

MAIN

DATE = 76104

15/00/50

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C FOR TAU GREATER THAN ZERO. IF MORE THAN NUMBER TEMPS ARE TAKEN, LAPC=1007J
C UNDERFLOW MAY OCCUR.
C
0027      HC=ACPTAU-1
0028      DO 4 J=1,HC
0029          Z=J+1
0030          TAU=(I-1)*ETAU
0031          + NUMBER(1)=.5*((16./TAU)**.5-1.)
0032      NUMBER(1)=NTEMP5
C
0033      TAU=-ETAU
0034      DO 7 JTAU=1,NUMTAU
0035          TAU=TAU+ETAU
0036          AVSUM=0.
0037          CSUM=C.
0038          N1=1+NUMBER(JTAU)
0039          DO 6 N=1,N1
0040              N=N-1
0041              TN=2*N+1
0042              TN2=TN*TN
0043              C1=EXP((-TN2*PI*PI+4.*SIGNA1)*TAU)
0044              L=(4.*SIGNA1-TN2*PI*PI)
0045              AVSUM=AVSUM+C1/TN2/C
0046              CSUM=CSUM+EX*(-1.)**N/E/TN
0047          AVTEMP(JTAU)=5+32./PI/PI*AVSUM
0048          AVTEMP(JTAU)=TEMPF+TEMPSCI*AVTEMP(JTAU)
0049          CTEMP(JTAU)=A+16./PI*CSUM
0050          7      CTEMP(JTAU)=TEMPF+TEMPSCI*CTEMP(JTAU)
C
C PRINT AND PLOT (THROUGH DEIPS) THE TEMPERATURE AS A FUNCTION OF TIME.
C
0051      WRITE (6,106)
0052      WRITE (6,107)
0053      TAU=-ETAU
0054      DO 5 K=1,NUMTAU
0055          TAU=TAU+ETAU
0056          TA=TAU*TIMSCI
0057          TIME(F)=TA
0058          5      WRITE (6,108) TIME(K),AVTEMP(K),CTEMP(K)
0059      SX=7.5
0060      CALL DEIPS1(TIME,CTEMP,NUMTAU,01,SX,
X          ' (RELAXATION) ',0,' (SECONDS) ',0,
X          ' (LIGRES CENTIGRADES) ',0)
0061      CALL DEIPS2(TIME,AVTEMP,NUMTAU,11)
0062      CALL DEIPS3(3.,5.,2,' (AVERAGE) ',0)
0063      CALL DEIPS3(3.,7.5,2,' (CENTER) ',0)
0064      STOP
0065      END

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C *****
C * TEMP EVALUATES AS FUNCTIONS OF Y THE TEMPERATURE PROFILE AND X- AND
C * Z- DIRECTION VELOCITY PROFILES FOR AN ELECTROPHORESIS CELL WITH HEAT
C * CONDUCTION IN THE Y-DIRECTION. IT ALSO MODELS PARTICLE SEPARATION FOR
C * AN INPUT STREAM OF GIVEN SIZE, LOCATION AND MOBILITY DISTRIBUTION.
C * THERE ARE TWO SUBROUTINES- SIMPS, WHICH PERFORMS INTEGRATION BY
C * SIMPSON'S RULE, AND TEMP, WHICH COMPUTES THE TEMPERATURE FIELD.
C * AMONG THE INPUT VARIABLES ARE--
C *
C *
C * NVEL -NUMBER OF POINTS AT WHICH THE VELOCITY IS EVALUATED
C * NVEL MUST BE ODD
C * NCOL -THE NUMBER OF COLLECTION UNITS
C * NPCOL -THE NUMBER OF POINTS IN EACH COLLECTOR
C * NPCOL MUST BE ODD
C * NM -THE NUMBER OF POINTS TAKEN IN THE MOBILITY DIST.
C * FMOBL -ARRAY REPRESENTING MOBILITIES
C * NSUM -NUMBER OF TERMS TAKEN IN THE INFINITE SERIES FOR THE
C * FIRST ORDER TEMPERATURE FIELD
C * FMOBL -ARRAY REPRESENTING THE MOBILITIES
C * FMOBL -ARRAY REPRESENTING THE MOBILITY CONCENTRATIONS.
C *****
C
C
C
C
0001 DIMENSION T(1001),VX(1001),VY(1001),FMO(1001),S1(1001),S2(501)
      A ,H(501),A(501),X1(501),Z1(501),ZMAX(501),
      X ZMAX(1001),ZF(1001),ZF2(1001),AN(1001),BN(1001),
      A FNEAR(1001),
      X FMOBL( 50),FMOBL( 50),FMOBL(1001)
0002 REAL EDC MD1
C
0003 101 FORMAT (5I5)
0004 102 FORMAT (4E10.3)
0005 103 FORMAT (2E10.3)
0006 104 FORMAT (2E10.3)
0007 105 FORMAT (4E10.3)
0008 106 FORMAT (2E10.3)
0009 110 FORMAT ('1','INTEGER INPUT VARIABLES')
0010 111 FORMAT (' ','NVEL -',I5,2X,'NCOL -',I5,2X,'NPCOL -',I5,2X,
      X 'AN -',I5,2X,'NSUM -',I5)
0011 112 FORMAT ('0','1','0','BUFFER PROPERTIES (CONSTANT)')
0012 113 FORMAT (' ','VISCOSITY -',1PE10.2,1X,'GM/CM-S',2X,'DENSITY -',
      X 1E10.2,1X,'G/CC',2X,'INHPAL CONDUCTIVITY -',1PE10.2,
      X 1X,'WATTS/CM-C'/' ELECTRIC CONDUCTIVITY -',1PE10.2,
      X 1X,'/CM-DM')
0013 114 FORMAT ('0','1','0','
      X 'BUFFER PROPERTIES (TEMPERATURE VARYING, DIMENSIONLESS)',
0014 115 FORMAT ('0','1','IFERE. COND.',6X,'ELECT. COND.')
0015 116 FORMAT (' ','PKP1 =',1PE10.3,2X,'FSIT =',1PE10.3)
0016 117 FORMAT (' ','PKP2 =',1PE10.3,2X,'FSZF =',1PE10.3)
0017 118 FORMAT ('0','1','0','CHAMBER DIMENSIONS')
0018 119 FORMAT (' ','WIDTH -',1PE10.2,1X,'CM',2X,'LENGTH -',1PE10.2,1X,
      X 'CM',2X,'DEPTH -',1PE10.2,1X,'CM')
0019 120 FORMAT ('1','2X,'MOBILITY (MICRONS-CM/VOLT-S)',2X,'COLLECTOR',2X,

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FORTRAN IV G LEVEL 21

MAIN

DATE = 7/1/74

10/31/74

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C
C EVALUATE VISCOSITY AT EVERY OTHER TEMPERATURE POINT- ARRAY MU
C
0058      J=-1
0059      ARG =TEUFF-20.
0060      ARG=3.00067/(1.+C.JC82*ARG)
0061      ARG=-7.6039+ARG
0062      MUC=EXP(ARG)
0063      MU1=J.JJ3937
0064      CTMCBL=CTMCBL*MU1/MU0
0065      VISC=MUJ
0066      DO 3 I=1,NDF
0067          J=J+2
0068      ARG=TSSCALE*T(J)+TEUFF-20.
0069      ARG=3.00067/(1.+C.JC82*ARG)
0070      ARG=-7.6039+ARG
0071      FMU(I)=EXP(ARG)/MUJ
0072      3 CONTINUE
0073      WRITE (6,11)
0074      WRITE (6,111) NVVL,NCCL,APCOL,M1,MUJ
0075      WRITE (6,112)
0076      WRITE (6,113) VISC,ELASTY,THCOND,ZICOND
0077      WRITE (6,114)
0078      WRITE (6,115)
0079      WRITE (6,116) FAP1,FSP1
0080      WRITE (6,117) FKE2,FSE2
0081      WRITE (6,118)
0082      WRITE (6,119) WIDTH,XLONG,DEPTH
0083      WRITE (6,122) ID,TEUFF,TEUFF,CTMCBL
0084      WRITE (6,129) Y1,Z1,Z
0085      WRITE (6,132) GRAV
0086      WRITE (6,123)
0087      WRITE (6,121) (FMUCL(I),FMUCL(I),I=1,NDF)
C
C
C COMPUTE DENSITY INTEGRAL AS ARRAY FMBCL REPRESENTING DENSITY INTEGRAL
C Y=0 TO EVERY OTHER DENSITY-TEMPERATURE POINT
C
0088      DY=1./(NTEMP-1.)
0089      FMBCL(1)=C.
0090      M1=1
0091      M2=3
0092      DO 4 I=2,NDF
0093          A=DY*(MHC(M1)+4.*MHC(M1+1)+MHC(M2))/3.
0094          M1=M2
0095          M2=M2+2
0096      FMBCL(I)=A+FMBCL(I-1)
0097      4 CONTINUE
C
C COMPUTE Y/FMU INTEGRAL AS ARRAY REPRESENTING Y/FMU INTEGRAL FROM Y=0 TO
C EVERY OTHER VISCOSITY POINT (I.E., EVERY FOURTH DENSITY-TEMPERATURE POINT)
C FIRST EVALUATE Y/FMU AS ARRAY S1.
C
0098      DY=1./(NDF-1.)
0099      S1(1)=C.
0100      DO 5 I=2,NDF

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PGTIBAN IV G LEVEL 21

MAIN

DATE = 76104

15/11/34

0101	Y=CY*(I-1)	1690
0102	S1(I)=Y/FNU(I)	1700
0103	5 CCNTINUE	1710
0104	U1(I)=C.	1720
0105	N1=1	1730
0106	N2=3	1740
0107	DO 6 I=2,NVEL	1750
0108	A=CY*(S1(N1)+4.*S1(N1+1)+S1(N2))/3.	1760
0109	N1=N2	1770
0110	N2=N1+2	1780
0111	U1(I)=A+U1(I-1)	1790
0112	6 CCNTINUE	1800
C	EVALUATE FRHCI/FNU AS ARRAY U2 REPRESENTING FRHCI/FNU INTERPOLATED FROM 1 TO	1810
C	EVERY OTHER VISCOSITY POINT. FIRST EVALUATE FRHCI/FNU AS ARRAY S1.	1820
C		1830
0113	S1(1)=C.	1840
0114	DO 7 I=2,NDF	1850
0115	S1(I)=FRHCI(I)/FNU(I)	1860
0116	7 CCNTINUE	1870
0117	U2(1)=C.	1880
0118	N1=1	1890
0119	N2=N1+2	1900
0120	DO 8 I=2,NVEL	1910
0121	A=CY*(S1(N1)+4.*S1(N1+1)+S1(N2))/3.	1920
0122	N1=N2	1930
0123	N2=N1+2	1940
0124	U2(I)=A+U2(I-1)	1950
0125	8 CCNTINUE	1960
C	CHANGE U1 AND U2 FROM INTEGRALS TAKEN FROM 2000 TO Y TO THEIR POINT IN THE	1970
C	VELOCITY EXPRESSION- TAKEN FROM Y TO 1.	1980
C		1990
0126	DO 11 I=1,NVEL	2000
0127	U1(I)=U1(NVEL)-U1(I)	2010
0128	11 U2(I)=U2(NVEL)-U2(I)	2020
C	EVALUATE THE CONSTANT FK BY INTEGRATING -FK*U1 + U2*U2 FROM Y=1 TO A=1	2030
C	AND SETTING RESULT EQUAL TO ONE.	2040
C		2050
0129	CY=1./(NVEL-1.)	2060
0130	N1=1	2070
0131	CALL SIMPS(CY,U1,N1,NVEL,A1)	2080
0132	CALL SIMPS(CY,U2,N1,NVEL,A2)	2090
0133	FNU=VISC/DENSTY	2100
0134	USCAL1=2*BUFF/WIDTH/DEPTH	2110
0135	FN2=GRAV*DEPTH*DEPTH/FNU/USCAL1/4.0	2120
0136	FK=(-1.+FN2*FN2)/A1	2130
C	EVALUATE THE AL VELOCITY	2140
C		2150
0137	USUM=).	2160
0138	DO 9 I=1,NVEL	2170
0139	U(I)=-FK*U1(I)+FN2*U2(I)	2180
0140	9 USUM=USUM+U(I)	2190
C		2200

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FORTRAN IV G LEVEL 21

MAIN

DATE = 78104

10/31/54

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C COMPUTE THE ELECTROSTATIC (Z-DIRECTION) VELOCITY. THIS HAS THE FORM OF
C SO MERELY USE INTEGRATED U1 TO DETERMINE CONSTANT, AND THEN SUBTRACT 1.
C
0141      USCALE=CTNCBI*EC*.0001
0142      PA2=-1./A1
0143      NSUM=0.
0144      J=-1
0145      DO 12 I=1,NVEL
0146      J=J+2
0147      CMCHI(I)=0.0001*U1/(RUC*FNU(J))
0148      W(I)=-PA2*U1(I)-1.
0149      12  NSUM=NSUM+W(I)

C
C PRINT TEMPERATURE AND U- AND W- VELOCITY FIELDS AT VALUES OF Y CORRESPONDING
C TO THE VELOCITY POINTS.
C
0150      DY=1./(NVEL-1)
0151      WRITE (6,135)
0152      WRITE (6,134)
0153      WRITE (6,125)
0154      DO 30 I=1,NVEL
0155      Y=DY*(I-1)
0156      J=1+(I-1)*4
0157      30 WRITE (6,126) Y,T(J),U(I),W(I)
0158      DY=DY*DEFTL/2.
0159      WRITE (6,135)
0160      WRITE (6,124)
0161      WRITE (6,125)
0162      DO 10 I=1,NVEL
0163      Y=DY*(I-1)
0164      J=1+(I-1)*4
0165      U(I)=U(I)*USCALE
0166      W(I)=W(I)*USCALE
0167      T(J)=T(J)*ISCALE+TEUFF
0168      10  WRITE (6,126) Y,T(J),U(I),W(I)

C
C
0169      J=2*NVEL
0170      DO 14 I=1,NVEL
0171      J=J-1
0172      CMCHI(J)=CMCHI(NVEL+1-I)
0173      U(J)=U(NVEL+1-I)
0174      W(J)=W(NVEL+1-I)
0175      NVELN=NVEL-1
0176      DO 15 I=1,NVELN
0177      CMCHI(NVEL-I)=CMCHI(NVEL+I)
0178      U(NVEL-I)=U(NVEL+I)
0179      W(NVEL-I)=W(NVEL+I)
0180      NV=2*NVEL-1
0181      YZ=LZ*FTL/2.
0182      Y=-YZ-DY
0183      DO 16 I=1,NV
0184      Y=Y+DY
0185      YY(I)=Y
0186      16 CONTINUE

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PCBTRAN IV G LEVEL 21

MAIN

DATE = 7-10-84

15/01/84

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C SET THE Z-COORDINATE ARRAY AND THE Z-DIRECTION STEP SIZE.
C
0187      ZCCL=WIDTH/NCCL
0188      CZ=ZCCL/(NFCCL-1)
0189      NZ=(NFCCL-1)*NCCL+1
0190      Z=WIDTH/2.
0191      NYPTS=NVEL
0192      NZPTS=(NZ-1)/2+1
0193      Z=-ZC-CZ
0194      DO 190 I=1,NZ
0195          Z=Z+CZ
0196      190 ZZ(I)=Z
C
C ROUND THE CENTER AND RADIUS OF THE SAMPLE STREAM TO THE NEAREST MULTIPLES
C OF DY.
C
0197      IY1=(Y1/DY+.5)+NYPTS
0198      IZ1=(Z1/CZ+.5)+NZPTS
0199      Y1=YY(IY1)
0200      Z1=ZZ(IZ1)
0201      XR=R/DY+.5
0202      R=NR*CY
0203      WRITE (6,133) IY1,Y1,IZ1,Z1,R
C
C FOR EACH MOBILITY TAKEN IN THE SAMPLE DISTRIBUTION, DETERMINE THE EXACT
C LOCATIONS OF PARTICLES ON THE EDGE OF THE SAMPLE STREAM.
C
0204      I=IY1-R/DY-1
0205      NYM=2.*(R/DY)+1.
0206      DO 200 J=1,NYM
0207          I=J+M
0208          P=(ABS(R*R-(YY(I)-Y1)*(YY(I)-Y1))**.5
0209          ZMIN(J)=Z1-P
0210      200 CONTINUE
0211      WRITE (6,120)
0212      DO 270 J=1,NYM
0213          DO 270 K=1,NYM
0214              I=K+M
0215              ZF(K)=ZMIN(K)+XLONG*(W(L)+XO*FNCCL(J)*CAGCL(L))/U(L)
0216              IF (YY(L).GE.YD.OR.YY(L).LE.-YD)
C
C          X
C              ZF(K)=999.
C          F=(ABS(R*R-(YY(I)-Y1)*(YY(I)-Y1))**.5
0217              ZF2(K)=ZF(K)+2.*P
0218              IF (ZF(K).LE.-2W)
C
C          X
C              WRITE (6,126) FNCCL(J),YY(L)
0219              IF (ZF2(K).GE.2W)
C
C          X
C              WRITE (6,126) FNCCL(J),YY(L)
C
C FIND THE Y-AVERAGED MOBILITY DISTRIBUTIONS AT EACH Z POINT.
C
0221      DO 230 I=1,NZ
0222          DO 210 K=1,NYM
0223              I=K+M
0224              IF (ZZ(I).GE.ZF(K).AND.ZZ(I).LE.ZF2(K))
C
C          X
C              AM(K)=FNCCL(J)*U(L)
0225      210      IF (ZZ(I).LT.ZF(K).OR.ZZ(I).GT.ZF2(K))

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PCSTRAN IV G LEVEL 21

MAIN

DATE = 76104

15/01/54

	X	AS(K)=0.	337
0226		CALL SIMPS(DY,AM,1,MYH,D)	338
0227		FNBAR(I)=D/USCAL/DEPTH	339
0228	230	CONTINUE	340
	C		341
	C	FIND THE AVERAGE MOBILITY DISTRIBUTION IN EACH SAMPLE COLLECTOR.	342
	C		343
0229		NDIV=NFCC1-1	344
0230		DO 260 J=1,NCCL	345
0231		JINIT=(1-1)*NDIV	346
0232		DO 240 K=1,NCCL	347
0233		I=K+JINIT	348
0234	240	BM(K)=FNBAR(I)	349
0235		CALL SIMPS(DZ,BM,1,NCCL,C)	350
0236		C=C/ZCCL	351
	C		352
	C	PRINT THE COLLECTOR MOBILITY DISTRIBUTIONS.	353
	C		354
0237		WRITE (6,127) FMOEL(J),I,C	355
0238	260	CONTINUE	356
0239	300	CONTINUE	357
0240	99	STOP	358
0241		END	359

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FORTRAN IV G LEVE 21

TEMP

DATE = 78104

15/01/34

```

0001      SUBROUTINE TEMP(MI,NS,FS,FKP,T)
C
C THE TEMP SUBROUTINE EVALUATES THE TEMPERATURE FIELD T = TZERO + FKP*TCNE
C TZERO IS THE ZERO ORDER FIELD- TONE THE FIRST ORDER FIELD. THE TEMP GIVES
C THE TEMPERATURE AT NTEMP POINTS FROM Y=0 TO Y=1
C
0002      DIMENSION T(1000)
C
C      CALCULATE ZERO ORDER FIELD
C
0003      FI=3.1415926
0004      FN1=FS** (0.5)
0005      CFN1=CCS (FN1)
0006      TFN1=2.*FN1
0007      EY=1./(NI-1)
0008      DO 2 J=1,NI
0009          Y=EY*(J-1)
0010          X=(1.+Y)*FI/2.
0011          TZERO=(CCS (FN1*Y)-CFN1)/CFN1/FS
C
C      CALCULATE FIRST ORDER FIELD
C
0012      SUM=0.
0013      FKP=4.*FS/PI/PI
0014      DO 3 JI=1,NS
0015          FNP=JI*PI/2.
0016          FK1=SIN (FNP)
0017          FC1=TFN1*FNP
0018          FC2=TFN1-FNP
0019          A=SIN (FC1)/4./FC1+SIN (FC2)/4./FC2+FN1/YNE/2.
0020          B=A*FI*FK1
0021          FC1=FN1-FNP
0022          FC2=FN1+FNP
0023          B=SIN (FC1)/2./FC1+SIN (FC2)/2./FC2
0024          E=-E*2.*FI*FK1*CFN1
0025          NC=1-(-1)**JI
0026          C=CFN1*CFN1*NC/JI
0027          FJIS=JI*JI
0028          ASUM=(A+B+C)*FJIS/2./(FJIS-FK3)
0029          ASUM=ASUM*SIN (JI*X)
0030      3      SUM=SUM+ASUM
0031      TONE=-SUM/FS/FS/CFN1/CFN1
0032      TCNE=TCNE*2./FI
0033      2      T(J)=TZERO+FKP*TCNE
0034      RETURN
0035      END

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FORTRAN IV G LEVEL 21

SIMPS

DATE = 7-10-64

15/01/34

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0001      SUBROUTINE SIMPS(H,A,N1,N2,AREA)
C
C      THE SIMPS SUBROUTINE USES SIMPSON'S RULE TO INTEGRATE AN ARRAY
C
0002      REAL PIDSUM
0003      DIMENSION A(1001)
0004      ENDSUM=0.
0005      PIDSUM=0.
0006      NI=(N2-N1)/2
0007      J=N1-1
0008      DO 1 I=1,NI
0009          J=J+1
0010          ENDSUM=ENDSUM+A(J)
0011          J=J+1
0012          PIDSUM=PIDSUM+A(J)
0013      1 AREA=H*(2.*ENDSUM+4.*PIDSUM-A(N1)+A(N2))/3.
0014      RETURN
0015      END

```

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