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MOD-2 FAILURE MODE AND EFFECTS ANALYSIS

Robert Lynette and Robert Poore
Boeing Engineering and Construction Co.

July 1979

Prepared for
NATIONAL AERONAUTICS AND SPACE ADMINISTRATION
Lewis Research Center
Under Contract DEN 3-2

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U.S. DEPARTMENT OF ENERGY
Energy Technology
Distributed Solar Technology Division



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Boeing Engineering and Construction Co.
Boeing Company
Seattle, Washington

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Cleveland, Ohio 44135
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Washington, D.C. 20545
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INTRODUCTION

The failure mode and effects analyses (FMEA) were performed during preliminary and detail design in order to identify all MOD-2 failure modes and to ensure that the resultant effects are: (1) acceptable from a safety standpoint and (2) fail safe or, if not fail safe, represent least cost solutions (i.e., result in the lowest cost of electricity).

R

The FMEA's were completed by the cognizant designers and reviewed by system engineers and a reliability specialist. In general, fail safe design is employed wherever cost effective and a safe life design is employed for single thread structural items such as the rotor. The failure severity code used in the analysis is described in Table 1.

Completion of the FMEA's by the designers as an in-line part of the design process resulted in numerous design changes to either prevent serious failure modes or reduce their impact. The FMEA's contained herein reflect the detail design configuration. All major changes incorporated subsequent to the ØDR will be evaluated relative to personnel safety and cost of electricity.

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Whenever applicable, failure frequency data has been included in the analyses. This data was used to quantify the probability of occurrences and hence the impact on the cost of electricity.

SUMMARY OF RESULTS

Over 860 failure modes were analyzed and numerous corrective actions were implemented to preclude costly failures. Special attention was directed at all potentially catastrophic failure modes; the results of this effort are summarized in Table 2.

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Wherever practical, redundancy is used to preclude catastrophic failures. Safe life design is employed for items whose failure could cause serious damage, but could not be made redundant (e.g., blade fatigue cracks). The ability to control each rotor pitch control surface independent of the other precludes several potentially serious failure modes such as control linkage binding or bearing failures (the MOD-2 design provide for an orderly shutdown with just one control tip operative). The most probable, potentially catastrophic failure mode is the rapid progression of a fatigue crack in the blade. The MOD-2 design has incorporated a crack detection system which will cause an orderly WTS shutdown prior to suffering significant rotor damage.

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The detailed FMEA sheets are contained in Appendix A, and relevant electrical/hydraulic schematics are included in Appendix B. Appendix C contains the results of a staff analysis of WTS emergency shutdowns. Appendix D contains an FMEA of the cable runs and both slip rings.

Summary of Revisions (Initial Analysis at PDR; this revision at DDR)

The purposes for this revision are: (1) to update the FMEA based on changes to the MOD-2 configuration that have occurred since the preliminary design review (PDR), (2) to add a new section that contains an analysis of the possible effect of electrical failures that have a potential for causing numerous secondary failures (e.g., a wire shorts and causes other wires in the same bundle to short to ground or to other wires) and (3) to add a new section that contains an analysis of the possible effects of contact-to-contact shorts of adjacent slip rings in the two slip ring assemblies. The latter two sections could not be completed at the PDR since cable runs and slip ring assignments had not yet been established.

The major configuration changes covered by this revision are:

1. Addition of ice detection and crack detection systems.
2. Changes in the gearbox lubrication system to take advantage of the pump redundancy.
3. Deletion of the delta pressure sensors in the yaw hydraulics system.
4. Changes in the yaw drag brake caliper to make the drag proportional to hydraulic pressure rather than depending upon a mechanical spring.

The following pages have been added:

iii - new page

Pages 273 through 295 Appendix D (new section)

The following pages have been revised:

i, ii, v (was page iv)

1, 2, 29, 46, 69.1, 72, 82, 98, 129, 148, 169, 262, 263, 266a,
267 & 268

TABLE 1, SAFETY AND FAILURE SEVERITY CATEGORY GUIDE

HAZARD CATEGORY	IMPACT			
	FUNCTION	REPAIR COST	TIME TO REPAIR	PERSONNEL INJURY
Minimal	None (1)	and Under \$1000	and Under 2 Days	and None
Marginal	None Critical (2)	and Under \$1,000	and Under 2 Days	and First Aid
Critical	Loss of Function (3)	or Up to \$10,000	or Up to 10 Days	or Hospital
Catastrophic	Loss of System (4)	or Over \$10,000	or Over 10 Days	or Fatal or Permanent Disable

Impact values include the dollar and human cost of an unplanned event (a realized hazard).

Hospitalization is a severity category; includes wound stitches, extensive burn treatment, broken bone setting and equivalents.

Permanent Disablement includes loss of limb, sight or other majority body function.

*With the exception of flying objects emanating from the WTS, personnel injury can only occur during period of preventative and corrective maintenance.

- (1) Minor items that can be repaired with convenient.
- (2) No loss of generating capability, but repair must be accomplished within 2 weeks to avoid shutdown.
- (3) Causes WTS shutdown.
- (4) Destruction of major element such as rotor or gear box.

TABLE 1, SAFETY AND FAILURE CATEGORY GUIDE

Table 2, Summary of Major Failures and Effects – MOD-2-107

Failure	Effect	Corrective action
Structural failures Rotor <ul style="list-style-type: none"> • Ice forms and is thrown off • Blade fatigue cracks • Spar buckling • Fatigue crack at control tip spindle end thread or at tip-blade interface • Inboard joint-rotor to hub bolt or flange weld failure • Broken teeter trunnion or flange cracks • Buckling inboard sections or hub compression skins Drive <ul style="list-style-type: none"> • Broken low speed shaft • Broken quill shaft bulkhead joint • Teeter shaft or flange cracks Tower <ul style="list-style-type: none"> • Failure of structure or foundation 	<p>Could injure public – remote possibility Loss of part of rotor and possible secondary damage if allowed to progress</p> <p>Loss of load</p> <p>Possible extensive rotor damage</p> <p>Extensive damage</p>	<p>Ice detection system added Crack detection system shuts down WTS prior to incurring serious damage Safe life design Fatigue tests Inspection schedule Mid-blade assembly buckling test</p> <p>Emergency shutdown effected prior to reaching damaging overspeed Safe life design Strain gage correlation Safe life design</p> <p>Safe life design</p>
Control system failures <ul style="list-style-type: none"> • Signal to one tip incorrectly drives control surface to zero pitch • Control linkage to one tip jams • Control system signal to both pitch actuators incorrectly drives control surfaces to zero pitch • Power output sensor fails, calling for power increase when system is already at full power output 	<p>Emergency shutdown triggered by differential of tip position signals</p> <p>Emergency shutdown triggered by generator output power sensor</p> <p>Damaging overspeed possible if load drops off prior to initiating shutdown</p>	<p>None required, analysis verifies that one tip operative can safely stop rotor</p> <p>None required – shutdown occurs prior to damaging overspeed</p> <p>System changed to command shutdown prior to load dropping off Also, backup power sensor signal sent to controller</p>
Electrical power failures <ul style="list-style-type: none"> • Synchronizer provides signal to close bus tie contactor too soon or too late (WTS not proper phase relationship or voltage to mate with bus) • Loss of commercial power while WTS is at rated power 	<p>High current transient causing high torque load on the generator that could cause mechanical damage to generator or drive train</p> <p>Rotor speed increases</p>	<p>Synchronizer is fully redundant and fail safe</p> <p>None required – shutdown occurs prior to damaging overspeed</p>

APPENDIX A

MOD-2 FAILURE MODES AND EFFECTS ANALYSIS - DETAILED WORKSHEETS

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM ROTOR			COMPONENT SHELL STRUCTURE			PAGE 1 FMEA NO 4.1.1	
FUNCTION OF COMPONENT CARRY SHEAR AND BENDING LOADS TO BLADE ATTACHMENT AT HUB							
FAILURE MODES & EFFECTS 1 FATIGUE CRACK IN TENSION SKIN WELD. CAUSES LOSS OF PORTION OF						APPLICABLE OPERATING MODES ALL	
BLADE IF CRACK IS UNDETECTED.							
MAY CAUSE CHANGE IN BLADE STIFFNESS AND IN TURN INCREASE VIBRATION.							
2. ICE ACCUMULATIONS COULD SEPARATE FROM ROTOR AND STRIKE PEOPLE OR ANIMALS IF DETECTION SYSTEM FAILS						G	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	Cannot be accurately calculated				X	X*	
FAILURE DETECTION METHODS							
1 CRACK DETECTION SYSTEM.							
2. ICE DETECTORS ON BLADES.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1 IT IS POSSIBLE TO AVOID THIS FAILURE MODE BY USE OF A CRACK DETECTION SYSTEM. (INCORPORATED INTO SYSTEM)							
SAFE LIFE DESIGN OF THIS COMPONENT IS INTENDED TO AVOID THIS FAILURE MODE.							
* IF NOT DETECTED							
2. ICE DETECTORS ON BOTH BLADES PROVIDE REDUNDANCY. DETECTION CIRCUIT IS FAIL SAFE (I.E , OPEN OR SHORTED WIRE/CONNECTION RESULTS IN WTS SHUTDOWN).							
						NAME J. NOBLE	
						DATE 8/15/78	
Rev. 10/25/78							
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM ROTOR		COMPONENT SPARS		PAGE 2 FMEA NO 4.1.2		
FUNCTION OF COMPONENT CARRY SHEAR LOADS TO BLADE ATTACHMENT AT HUB.						
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES		
1 FATIGUE CRACK ACROSS SPAR. CAUSES OVERSTRESSING OF SHELL STRUCTURE				ALL		
2 BUCKLING OF SPARS BY HIGH RESIDUAL WELDING STRESSES CAUSES OVERSTRESSING OF SPAR TO SHELL WELDS				ALL		
3						
4						
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III
1	Cannot be accurately calculated				X	X*
2		" " "			X	X*
FAILURE DETECTION METHODS						
1 Crack Detection System						
2 Not directly observable						
3 Change in blade stiffness may be detected by an accelerometer as increased vibration						
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)						
THESE FAILURE MODES WOULD NOT IMMEDIATELY AFFECT WTS OPERATION, BUT COULD LEAD TO CATASTROPHIC FAILURE OF THE BLADE SHELL STRUCTURE IN A FAIRLY SHORT TIME.						
IT IS POSSIBLE TO AVOID MODE I BY USE OF A CRACK DETECTION SYSTEM. (INCORPORATED).						
SAFE LIFE DESIGN OF THIS COMPONENT IS INTENDED TO AVOID THESE FAILURE MODES.						
* IF NOT DETECTED						
				NAME J. NOBLE	DATE 8/15/78	
OPERATING MODES				Rev. 10/25/78		
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		3/8/79
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM ROTOR ASSY.			COMPONENT INBD JOINT			PAGE 3 FMEA NO 4.1.3	
FUNCTION OF COMPONENT ATTACHES ROTOR BLADE TO HUB							
FAILURE MODES & EFFECTS 1 BOLT FAILURE DUE TO CORROSION, FATIGUE, OR INTERNAL DEFECT - LOSS OF BLADE CAUSES SEVERE ASYMMETRIC LOADING ON TEETER BEARING, DRIVE TRAIN, NACELLE & TOWER.						APPLICABLE OPERATING MODES F, G, H	
2. FLANGE WELD FAILURE DUE TO INCLUSION, FATIGUE CORROSION OR OVER-LOAD - LOSS OF BLADE CAUSES SEVERE ASYMMETRIC LOADING ON TEETER BEARING, DRIVE TRAIN, NACELLE & TOWER.						F, G, H	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1		Cannot be accurately calculated			X	X*	
2		" "	" "		X	X*	
FAILURE DETECTION METHODS							
1 VISUAL INSPECTION (BOLTS MISSING - CRACKS IN WELD)							
2 CHANGE IN NATURAL FREQUENCY (OR STIFFNESS) OF ROTOR ASSY.							
3 INCREASE IN VIBRATION							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1. INSPECTION OF FLANGE WELD & CONSERVATIVE LOCAL DESIGN							
2. USE OF MANY, SMALL DIAMETER HIGH QUALITY BOLTS GIVES REDUNDANT LOAD PATH							
3. APPLICATION AND MAINTENANCE OF GOOD CORROSION PROTECTION SYSTEM (INSIDE & OUTSIDE) SHOULD PREVENT ANY FAILURE CAUSED BY CORROSION (ALSO FAY SURFACE SEALANT)							
4. LOW FATIGUE ALLOWABLES SHOULD PRECLUDE FAILURE DUE TO MOMENTARY OVERLOAD.							
5. SAFE LIFE DESIGN OF THESE COMPONENTS IS INTENDED TO AVOID FATIGUE FAILURES.							
JOINT FATIGUE TEST TO ESTABLISH FATIGUE ALLOWABLES							
* IF NOT DETECTED							
NAME Al Falco						DATE 8/16/78	
OPERATING MODES							
A SHUTDOWN		D - TRANSITION TO STANDBY		G - OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H - TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM ROTOR			COMPONENT PIVOT SPINDLE			PAGE 4 FMEA NO 4.1.4	
FUNCTION OF COMPONENT PROVIDE CONTROL AXIS AND STRUCTURAL RESTRAINT FOR CONTROL TIP.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 FATIGUE CRACK AT INBD. END THREAD. TIP WOULD FALL OFF CAUSING IMBALANCE & SHUTDOWN.						ALL	
2 FATIGUE CRACK AT TIP-BLADE INTERFACE. TIP WOULD FALL OFF CAUSING IMBALANCE & SHUTDOWN.						ALL	
3 OVERSPEED CAUSES BENDING OF SPINDLE. DISPLACED HINGELINE WOULD CAUSE IMBALANCE & SHUTDOWN.						ALL	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1		Cannot be accurately calculated					X
2		" "	"				X
3		" "	"			X	
FAILURE DETECTION METHODS							
1 OBSERVABLE							
2 OBSERVABLE							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
SAFE LIFE DESIGN OF THIS COMPONENT IS INTENDED TO AVOID THESE FAILURE MODES.							
REDUNDANCY COULD BE ACHIEVED BY AN ADDITIONAL CLAMP OR SIMILAR DEVICE AROUND SPINDLE AND PUT INBOARD OF THE OUTBOARD BEARING.							
NAME J. NOBLE						DATE 8/15/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM HUB		COMPONENT HUB		PAGE 5 FMEA NO 4.2			
FUNCTION OF COMPONENT ATTACHES ROTOR BLADE TO TEETER BEARING							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 LIGHTNING STRIKE - LOCALIZED PAINT DAMAGE, FAY SEAL PROTECTED BY CONSIDERABLE METAL-METAL CONTACT						ALL	
2 HAIL - OVERALL PAINT DAMAGE - MOST SEVERE ON LEADING EDGE						ALL	
3 SNIPER - LOCALIZED PAINT DAMAGE						ALL	
4 INTERNAL MOISTURE BUILDUP - ACCELERATES CORROSION LARGE AMOUNT COULD FREEZE AND CAUSE UNBALANCE						ALL	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	Frequency is site dependent		X				
2	Frequency is site dependent		X				
3	Frequency is site dependent		X				
4	Frequency is site dependent					X	
FAILURE DETECTION METHODS							
1, 2 and 3: VISUAL FOR PAINT DAMAGE & RESULTING CORROSION							
4 INTERNAL MOISTURE DETECTION SYSTEM							
IF UNBALANCE DUE TO ICE IS LARGE ENOUGH TO CAUSE A PROBLEM IT WILL BE DETECTED BY BEARING VIB DETECTOR AND SHUTDOWN WTS.							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
4 MOISTURE BUILDUP IS MINIMIZED BY PROVIDING VENTS AT OUTBD. END AND ALLOWING CENTRIFUGAL FORCE TO FORCE THE WATER OUT. CORROSION CONTROL SYSTEM WILL MINIMIZE CORROSION.							
1,2,3 NORMAL MAINTENANCE PAINTING SHOULD PREVENT ANY MAJOR DAMAGE DUE TO LOCALIZED PAINT REMOVAL.							
1,2 WTS INSPECTION FOLLOWING EXTREME WEATHER CONDITIONS.							
				NAME AL FALCO		DATE 8/6/78	
OPERATING MODES						Rev. 10/25/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM HUB		COMPONENT HUB		PAGE 6 FMEA NO 4.2		
FUNCTION OF COMPONENT ATTACHES ROTOR BLADE TO TEETER BEARING						
FAILURE MODES & EFFECTS 1 INBD. OF STA. 60: HUB FAILURE FROM FATIGUE CRACK PROPAGATION RESULTING IN SEVERE DEFORMATIONS AND POSSIBLE INTERFERENCE WITH				APPLICABLE OPERATING-MODES F, G, H		
2 NACELLE OR TOWER OUTBD OF STA 60: HUB FAILURE FROM FATIGUE CRACK PROPAGATION CAUSING LOSS OF BLADE RESULTING IN SEVERE ASYMMETRIC LOADING ON TEETER BEARING, NACELLE, DRIVE TRAIN & TOWER.				F, G, H		
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %		COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III
1		CANNOT BE ACCURATELY CALCULATED				X
2		" " "				X
FAILURE DETECTION METHODS 1, 2 VISUAL INSPECTION CHANGE IN FREQUENCY OF ROTOR ASSY. INCREASE IN VIBRATION						
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) 1, 2 SAFE LIFE DESIGN IS INTENDED TO AVOID FATIGUE FAILURES						
OPERATING MODES			NAME AL FALCO		DATE 8/ 6/78	
A SHUTDOWN B TRANSITION TO WARM-UP C WARM UP			D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE		G OPERATE H TRANSITION TO FEATHER I FEATHER	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM HUB		COMPONENT HUB		PAGE 7 FMEA NO 4.2		
FUNCTION OF COMPONENT ATTACHES ROTOR BLADE TO TEETER BEARING						
FAILURE MODES & EFFECTS BUCKLING OF COMPRESSION SKINS DUE TO OVERLOAD (SEVERE SNOW, ICE &/OR HURRICANE LOADS) RESULTING IN COLLAPSE OF BLADE AND WTS SHUT-DOWN INITIATED BY VIBRATION DETECTION SYSTEM AFTER STARTUP.				APPLICABLE OPERATING MODES A, F, G		
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %		FAILURE RATE $\times 10^{-6}$ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III
1	CANNOT BE ACCURATELY CALCULATED					X
2						
3						
4						
FAILURE DETECTION METHODS						
1	VIBRATION PICK-UP MOUNTED ON LOW SPEED SHAFT FRONT BEARING.					
2						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)						
ESTABLISHMENT OF CONSERVATIVE ENVIRONMENTAL OPERATING RANGE TO MINIMIZE RISK OF THIS FAILURE MODE.						
			NAME AL FALCO		DATE 8/16/78	
OPERATING MODES						
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM PITCH CHANGE MECHANISM			COMPONENT ACTUATORS			PAGE 8 FMEA NO 4.3.1.1	
FUNCTION OF COMPONENT POSITION THE VARIABLE PITCH PORTION OF THE WIND TURBINE ROTOR BLADE							
FAILURE MODES & EFFECTS 1 INTERNAL LEAK - REDUCES RATE OF MOTION, ACTUATOR CREEPS UNDER LOAD, HEATS FLUID.						APPLICABLE OPERATING MODES F, G, H	
2 EXTERNAL LEAK DISSIPATES SYSTEM FLUID						F, G, H	
3 JAMMED - UNABLE TO CONTROL BLADE PITCH ON ONE BLADE ONLY						F, G, H	
4 ROD-END SEPARATION - UNABLE TO CONTROL BLADE PITCH, ONE BLADE ONLY						F, G, H	
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2	.95	70	1.7		X	X *	
3	.04	70	41			X	
4	.01	70	164			X	
FAILURE DETECTION METHODS							
1 POOR SPEED CONTROL, OVERHEAT WARNING, MANUAL TEST							
2 VISUAL, LOW FLUID QUANTITY ALARM							
3 FEEDBACK SIGNALS FROM 2 BLADES DISAGREE, UNABLE TO FEATHER OR UNFEATHER ONE BLADE.							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
SYSTEM WILL SHUT DOWN.							
1. SUGGEST MANUAL TEST TO ALLOW MAINTENANCE PERSONNEL TO DETECT INTERNALLY LEAKY ACTUATOR. BY DISABLING FEEDBACK, ABSOLUTE RATE OF CHANGE DIFFERENCES CAN BE DETECTED AND ACTUATOR CAN BE REPLACED PRIOR TO FAILURE.							
3.4 SINGLE BLADE FEATHERED WILL STOP THE ROTOR. FREE TIP (#4) WILL ALIGN ITSELF STREAMLINE TO THE WIND.							
* IF UNDETECTED DURING INSPECTIONS.							
				NAME D. W. KING		DATE 8/9/78	
OPERATING MODES						Rev. 10/25/78	
A - SHUTDOWN		D - TRANSITION TO STANDBY		G - OPERATE			
B - TRANSITION TO WARM UP		E - STANDBY		H - TRANSITION TO FEATHER			
C - WARM UP		F - TRANSITION TO OPERATE		I - FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM PITCH CHANGE MECHANISM		COMPONENT RESERVOIR		PAGE 9 FMEA NO 4.3.1.2	
FUNCTION OF COMPONENT CONTAINS A SUPPLY OF HYDRAULIC FLUID FOR THE PITCH CONTROL HYDRAULIC SYSTEM.					
FAILURE MODES & EFFECTS 1 BAFFLE JAMS AND TUMBLES - ▷				APPLICABLE OPERATING MODES F,G,H, & I	
2 ROTARY SEAL FAILS - AIR SLOWLY ENTERS HYDRAULIC SYSTEM, &/OR OIL LEAKS FROM BREATHER				F, G,H, & I	
3 LIQUID LEVEL GAUGE FAILS - PRODUCES EMPTY INDICATION PRODUCES FALSE INDICATION - ▷				F,G,H, & I	
4 EXTERNAL JOINTS LEAKS - EVENTUALLY PRODUCES LOW LEVEL ALARM SPREADS OIL IN AREA OF LOW SPEED SHAFT				F,G,H,&I	

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	10	10	110			X	
2,4	100	20	5.7			X	
3	100	7	17			X	
4							

FAILURE DETECTION METHODS
1 **LOW LEVEL ALARM & VISUAL DETECTION OF OIL IN BREATHER WTS SHUT DOWNS.**
2,4 **LOS SYSTEM PRESSURE &/OR OIL IN BREATHER WTS SHUTS DOWN**
3 **WTS SHUTS DOWN.**
4

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)
 ▷ **LIQUID LEVEL INDICATOR PRODUCES INTERMITTENT LOW LEVEL ALARM, AIR ENTERS PUMP INLET, OIL ESCAPES FROM BREATHER.**
 ▷ **IF INDICATOR INCORRECTLY SHOWS A SATISFACTORY OIL LEVEL WHEN THE OIL LEVEL IS UNSATISFACTORY, THE OIL TEMPERATURE OR PRESSURE DETECTION SYSTEM WILL SHUT THE WTS DOWN.**
DEVELOPMENTAL TESTS TO BE CONDUCTED TO VERIFY RESERVOIR PERFORMANCE.

NAME D. W KING		DATE 7/20/8
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OPERATING MODES

A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER
C WARM-UP	F TRANSITION TO OPERATE	I FEATHER

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM PITCH CHANGE MECHANISM		COMPONENT ACCUMULATORS		PAGE 10 FMEA NO 4.3.1.3			
FUNCTION OF COMPONENT							
1. STORE HYDRAULIC ENERGY FOR FEATHERING							
2. STORE ENERGY FOR SHORT TERM PEAK DEMANDS DURING NORMAL OPERATION							
FAILURE MODES & EFFECTS					APPLICABLE OPERATING MODES		
1 GAS LEAKS INTO HYDRAULIC SYSTEM - SPRING RATE OF SYSTEM REDUCED, EVENTUAL LOSS OF ACCUMULATOR CAPABILITY.					F, G, H, & I		
2 GAS LEAKS EXTERNALLY - LOSS OF ACCUMULATOR CAPABILITY.					G, H, & I		
3 OIL LEAKS EXTERNALLY - DISSIPATES OIL FROM SYSTEM					A, F, G, H, & I		
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	30	42	9		X	X IF UNDETECTED	
2	20	42	14			X	
3	30	42	9		X	X IF UNDETECTED	
4							
FAILURE DETECTION METHODS							
1 LOW ACCUMULATOR GAS PRESSURE WHEN HYDRAULICS DE-PRESSURIZED-DISABLES START-UP ABILITY.							
2 GAS PRESSURE NOT EQUAL TO HYDRAULIC PRESSURE; SYSTEM SHUTS DOWN.							
3 LOSS OF HYDRAULIC PRESSURE AND VISUAL INSPECTION							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME D. W. KING		DATE 7/21/8	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM PITCH CHANGE MECHANISM			COMPONENT START-STOP VALVES			PAGE 11 FMEA NO 4.3.1.4.1	
FUNCTION OF COMPONENT APPLIES HYDRAULIC PRESSURE TO SERVO VALVES FOR NORMAL OPERATION							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 EITHER VALVE FAILS TO OPEN - UNABLE TO START TURBINE.						F	
2 EITHER VALVE FAILS TO CLOSE - TURBINE SHUTS DOWN NORMALLY.						H	
3 BOTH VALVES FAIL TO CLOSE - ▷						H	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	90	41	3.1			X	
2	10	41	278			X	
3	100	.003	.5 x 10 ⁶			X	
FAILURE DETECTION METHODS							
1 UNABLE TO START TURBINE-ALL OTHER SYSTEMS OK.							
2 PERIODIC CHECK FOR VALVE OPERATION.							
3 UNABLE TO IMPLEMENT NORMAL SHUTDOWN, BUT NO PROBLEM.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
▷ TWO VALVES PROVIDED TO INCREASE RELIABILITY.							
				NAME D. W. KING		DATE 7/21/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM PITCH CHANGE MECHANISM		COMPONENT SYSTEM RELIEF VALVE		PAGE 12 FMEA NO 4.3.1.4.2			
FUNCTION OF COMPONENT <u>RELIEVES PRESSURE IN EVENT PUMP COMPENSATOR FAILS</u>							
FAILURE MODES & EFFECTS 1 LEAKS INTERNALLY - UNABLE TO MAINTAIN SYSTEM PRESSURE, HEATS FLUID				APPLICABLE OPERATING MODES E,F,G,H			
2 LEAKS EXTERNALLY - DISSIPATES SYSTEM FLUID, MAKES A MESS				E,F,G,H			
3 FAILS TO OPEN - SYSTEM MAY BE OVER PRESSUREIZED IF PUMP COMPENSATOR ALSO FAILS.				E,F,G.			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	40	17	66.6		X	X IF UNDETECTED	
2	40	17	66.6		X		
3	20	17	33.3		X	X IF UNDETECTED	
FAILURE DETECTION METHODS							
1 LOW PRESSURE ALARM, OR OVERHEAT ALARM							
2 LOW FLUID QUANTITY ALARM							
3 NO DETECTION METHOD EXCEPT BENCH TEST - CONSTITUTES DOUBLE FAILURE.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
<input checked="" type="checkbox"/> PROBABILITY OF DOUBLE FAILURE IS NEGLIGIBLE							
				NAME D. W. KING	DATE 8/9/78		
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G - OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H - TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I - FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM PITCH CHANGE MECHANISM		COMPONENT TEETER BRAKE VALVE		PAGE 13			
				FMEA NO 4.3.1.4.3			
FUNCTION OF COMPONENT <u>CONTROLS HYDRAULIC PRESSURE TO RELEASE TEETER BRAKE.</u>							
FAILURE MODES & EFFECTS 1 <u>FAILS TO OPEN-TEETER BRAKE SLIPS, BRAKE LINING & PLATE WEARS.</u>				APPLICABLE OPERATING MODES G			
2 <u>FAILS TO CLOSE-TEETER BRAKE RELEASES TOO EARLY ON START-UP</u>				F			
3 _____							
4 _____							
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %		COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	90	21	6.2		X		
2	10	21	55.6		X		
FAILURE DETECTION METHODS							
1 <u>BRAKE SQUEAKS DURING NORMAL OPERATION, VISUAL INSPECTION</u>							
2 <u>MANUAL INSPECTION.</u>							
3 _____							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
<u>HYDRAULIC PRESSURE SWITCH ADDED TO INDICATE</u>							
<u>BRAKE RELEASE STATUS.</u>							
_____ _____ _____ _____ _____ _____ _____							
				NAME D. W. KING	DATE		
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM PITCH CHANGE MECHANISM		COMPONENT SERVO VALVE		PAGE 14 FMEA NO 4.3.1.4.4			
FUNCTION OF COMPONENT CONTROLS PITCH CHANGE ACTUATOR							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 FAILS TO RESPOND TO COMMANDS - ONE BLADE TIP MOVES TO LIMIT OF MOTION.				F,G H			
2 INTERNAL LEAKAGE - HEATS FLUID, REDUCES RATE OF PITCH CHANGE.				F,G H			
3 JAMS - ONE BLADE TIP WILL NOT MOVE				F,G,H			
4 EXTERNAL LEAKAGE - DEPLETES SUPPLY IF NOT DETECTED.				F,G,H			
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	9	74	17.1			X	
2, 4	90	74	1.7		X (4)	X (2)	
3	1	74	154			X	
FAILURE DETECTION METHODS							
1 POSITION FEEDBACK FROM 2 BLADES DISAGREE							
2 OVERHEAT WARNING							
3 SAME AS 1 ABOVE. 4. FLUID LEVEL SENSOR.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
FOR 1, 2, 3, 4 EMERGENCY STOP IS INITIATED WHICH BY-PASSES SERVO VALVE.							
				NAME D. W. KING		DATE 8/9/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM PITCH CHANGE MECHANISM		COMPONENT SHUTTLE VALVE		PAGE 15 FMEA NO 4.3.1.4.5	
FUNCTION OF COMPONENT DISABLES SERVO VALVE & APPLIES BLADE FEATHERING PRESSURE UPON LOSS OF NORMAL HYDRAULIC SYSTEM PRESSURE.					
FAILURE MODES & EFFECTS 1 FAILS TO SHUTTLE WHEN PRESSURIZED - UNABLE TO CONTROL ONE BLADE. TIP, BYPASSES FLUID				APPLICABLE OPERATING MODES F,G H	
2 FAILS TO SHUTTLE WHEN DE-PRESSURIZED- UNABLE TO FEATHER ONE BLADE TIP				H,I	
3 LEAKS				F,G,H,	
4					

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	10	27	41.7			X	
2	10	27	41.7		X		
3	90	27	4.6		X		

FAILURE DETECTION METHODS

1 UNABLE TO UN-FEATHER BLADE TIP ON START COMMAND
LOW PRESSURE ALARM, OVERTEMP ALARM

2 NO PRESSURE CHANGE IN FEATHERING ACCUMULATOR ON "FEATHER" COMMAND. SLOW FEATHERING OR NO FEATHERING.

3 INSPECTION DURING PREVENTATIVE MAINTENANCE PERIODS.

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

1,2. SHUTDOWN CAN BE ACCOMPLISHED BY FEATHERING ONE BLADE.

NAME D. W. King		DATE 8/9/78
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OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H - TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM PITCH CHANGING MECHANISM			COMPONENT FITTINGS & HOSES			PAGE 16 FMEA NO 4.3.1.5	
FUNCTION OF COMPONENT SUPPLIES PRESSURIZED HYDRAULIC FLUID TO CONTROL ACTUATORS AND FEATHER LATCHES							
FAILURE MODES & EFFECTS 1 TUBING TOTALLY FAILS - LOSS OF PRESSURE: OIL WOULD SPILL INTO RACEWAY AND/OR BLADE SECTIONS.						APPLICABLE OPERATING MODES F,G,H	
2 HYDRAULIC FLUID LEAKS - OIL WOULD LEAK INTO RACEWAY: POSSIBLE OIL COATING ON ELECTRICAL COMPONENTS.						F,G,H	
3 LINES CLOG - LOSS OF PRESSURE						F,G,H	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	20	29	20			X	
2	75	29	5.3		X	*	
3	5	29	80			X	
FAILURE DETECTION METHODS							
1 LOW OIL PRESSURE, LOW OIL QUANTITY. SYSTEM WOULD GO INTO EMERGENCY STOP.							
2 VISUAL AND OIL LEVEL INDICATOR							
3 SLOW FEATHERING RESPONSE PICKED UP BY MICRO PROCESSOR.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1. SYSTEM WOULD GO INTO AUTOMATIC STOP (FEATHER LATCH WOULD LOCK) IF FAILURE OCCURED AT 1250-1260 STATION. COMPARTMENT W/ELECTRICAL & MECHANICAL COMPONENTS MAY BE COATED WITH OIL. ELECTRICAL COMPONENTS SHOULD BE RESISTANT TO OIL. FLUID TRAPS IN BLADE SHOULD ALSO BE AVOIDED, (DRAINS).							
2. SMALL LEAKS COULD ENTER RACEWAY AREA: ELECTRICAL WIRING SHOULD BE OIL RESISTANT.							
3. THIS FAILURE MODE IS NOT VERY LIKELY SINCE THE SYSTEM HAS TWO FILTERS.							
* CRITICAL IF LEVEL OR PRESSURE SENSORS INITIATE SHUTDOWN PRIOR TO LEAK DETECTION BY MAINTENANCE PERSONNEL.							
				NAME JOSE A. BURRUEL		DATE 7/26/78	
OPERATING MODES						Rev. 10/25/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I - FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM PITCH CHANGE MECHANISM		COMPONENT FILTERS		PAGE 17 FMEA NO 4.3.1.6	
FUNCTION OF COMPONENT REMOVES SOLID PARTICLES FROM HYDRAULIC FLUID.					
FAILURE MODES & EFFECTS 1 FAILS TO REMOVE PARTICLES - ▷				APPLICABLE OPERATING MODES F, G H	
2 LEAKS EXTERNALLY - DISSIPATES SYSTEM FLUID MAKES A MESS				F, G H	
3 EXCESSIVE PRESSURE DROP - ▷ DUE TO FILTER CLOGGING				F, G, H	
4					

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	FILTER CLOGGED, SEE #3			X	X*		
2	100	14	8.3			X	
3	CANNOT BE ACCURATELY ESTIMATED			X	X*		

FAILURE DETECTION METHODS
 1 PERIODIC FLUID SAMPLING & FILTER ELEMENT REPLACEMENT
 2 LOW FLUID QUANTITY ALARM· VISUAL INSPECTION
 3 DIFFERENTIAL PRESSURE SWITCHES. WTS WILL STOP IF EXCESSIVE PRESSURE DROP IS INDICATED.

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)
 ▷ INCREASES WEAR RATE OF PUMP, MAY CAUSE MALFUNCTION OF VALVES.
 ▷ INTERNAL BYPASS VALVE OPENS PRODUCING SAME EFFECT AS FAILURE MODE NO. 1;
 MAY ALSO REDUCE PITCH CHANGE RATES WHICH WOULD BE DETECTED BY THE MICROPROCESSOR.
 * IF UNDETECTED BY MAINTENANCE PERSONNEL

NAME D. W. KING		DATE 8/9/78	
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OPERATING MODES
 A SHUTDOWN
 B TRANSITION TO WARM UP
 C WARM-UP
 D TRANSITION TO STANDBY
 E STANDBY
 F TRANSITION TO OPERATE

G - OPERATE
 H TRANSITION TO FEATHER
 I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM			COMPONENT			PAGE 18 FMEA NO 4.3.1.7&8	
PITCH CHANGE MECHANISM			MOTOR-PUMP ASSY.				
FUNCTION OF COMPONENT							
PROVIDE HYDRAULIC POWER FOR OPERATION OF PITCH CHANGE MECHANISM							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 LOW HYDRAULIC OR NO PRESSURE - PRODUCES LOW PRESSURE ALARM WTS SHUTDOWN						F,G,H	
2 LOW HYDRAULIC FLOW - REDUCES PITCH CHANGE RATES, MOMENTARY LOW PRESSURE ALARM - WTS SHUTDOWN						F,G,H	
3 EXCESSIVE HYDRAULIC PRESSURE - OVERHEATS HYDRAULIC FLUID. - WTS SHUTDOWN						F,G,H	
4 LEAKS - EXTERNAL						F G H	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	38	6.1			X	
2	20	38	15.2			X	
3	100	17	6.7			X	
FAILURE DETECTION METHODS					X	X*	
4 30 38 10.0							
1 LOW PRESSURE ALARM - WTS SHUTDOWN							
2 LOW PRESSURE ALARM - WTS SHUTDOWN							
3 OVERHEAT ALARM - WTS SHUTDOWN							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
* IF UNDETECTED							
				NAME D. W. KING		DATE 8/9/78	
OPERATING MODES							
A SHUTDOWN		D - TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H - TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM ROTOR - EPS		COMPONENT CONTROL CABLE TO TIP NO 1 ACTUATOR		PAGE 19 FILE NO 4.3.1.10.			
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF COMMANDS AND OPERATIONAL DATA FROM THE TEETER BEARING FLEXIBLE CABLE ASSEMBLY TO THE TIP NO. 1 ACTUATOR							
FAILURE MODES & EFFECTS 1 Wire in cable is open circuited: No path for a specific command or data to or from Tip No. 1 actuator. Tip is not controllable. 2 Cable is partially short circuited: False commands may result or false data may be transmitted, Tip No. 1 does not position properly. 3 Cable is partially grounded / Loss of data or command function to Tip No. 1. Tip No. 1 does not position properly. 4				APPLICABLE OPERATING MODES F,G,H F,G,H F,G,H			
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	20	.04	14×10^3			X	
2	10	.04	28×10^3			X	
3	70	.04	4×10^3			X	
FAILURE DETECTION METHODS 1 - 3 Tip No. 1 data displayed on CRT terminal indicates that commands are not executed. WTS SHUTS DOWN DUE TO DIFFERENTIAL IN THE TWO PITCH POSITION SIGNALS.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) Conservative mechanical design of cable will reduce occurrence of these failures. Fail-safe shutdown is initiated if tip control signals are not executed.							
				NAME G. TRUSK / H. Roth		DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev. 10/3/78	
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM ROTOR - EPS		COMPONENT CONTROL CABLE TO TIP NO 2 ACTUATOR		PAGE 20 FMEA NO 4.3.1.10.2	
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF COMMANDS AND OPERATIONAL DATA FROM THE TEETER BEARING FLEXIBLE CABLE ASSEMBLY TO THE TIP NO. 2 ACTUATOR					
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES	
1 Wire in cable is open circuited: No path for a specific command or data to or from tip No. 2 actuator, tip is not controllable.				F,G,H	
2 Cable is partially short circuited: False commands may result or false data may be transmitted, tip No. 2 does not position properly.				F,G,H	
3 Cable is partially grounded/ or high resistance. Loss of data or command function to tip No. 2 does not position properly.				F,G,H	
4 In 1,2, and 3 WTS may shut down.					

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTR. PHIC IV
1	20	.04	14 x 10 ³			X	
2	10	.04	28 x 10 ³			X	
3	70	.04	4 x 10 ³			X	

FAILURE DETECTION METHODS

1 - 3 Tip No. 2 data displayed on CRT terminal indicates that commands are not executed.

WTS shuts down due to differential of pitch position signals.

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

1-3 Conservative mechanical design of cable will reduce occurrence of these failures.

Failsafe shutdown initiated if tip control signals are not executed.

NAME G. TRUSK / H. Roth DATE 8/17/78

OPERATING MODES

A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER
C WARM UP	F TRANSITION TO OPERATE	I - FEATHER

- Rev. 10/5/78
Rev. 10/25/78

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM		COMPONENT		PAGE 21			
ROTOR - EPS FUNCTION OF COMPONENT		TIP NO. 1 BONDING STRAP		FMEA NO 4.3.1.10.3			
PROVIDE A PATH FOR THE FLOW OF LIGHTNING CURRENT FROM THE VARIABLE PITCH TIP OF THE ROTOR TO THE FIXED PITCH PORTION OF THE BLADE							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 Bonding strap is open circuited.				ALL			
2 Bonding strap has high resistance due to fraying.				ALL			
3 Bonding strap has high resistance due to poor bond connection.				ALL			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	20	.2	2.8×10^3				*1
2	40	.2	1.4×10^3				*1
3	40	.2	1.4×10^3				*1
FAILURE DETECTION METHODS							
1 - 3 Periodic inspection.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1 - 3 When lightning strikes the variable pitch tip of the rotor the resultant extremely high current will follow the path of least resistance to ground. If an infinite or high resistance path replaces the low resistance bond path the current will possibly flow through the tip pitch bearing or hydraulic lines causing local overheating, pitting or welding of parts. Redundant bonding straps will be used to preclude this failure mode. Straps will be designed to minimize strap fatigue failures.							
*1 Physical damage could be fatal at a manned site due to falling parts, or molten metal. Probability of site being manned in a thunder storm and also having failure of both straps is negligible. O&M manual will specify that no one is allowed in nacelle during lightning storms.							
				NAME G. TRUSK / H. Roth		DATE 8/17/78	
OPERATING MODES				REV. 10/5/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD 2, Failure Mode and Effects Analysis

SUBSYSTEM ROTOR - EPS			COMPONENT TIP NO. 2 BONDING STRAP			PAGE 22 FMEA NO 4.3.1.10.4	
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF LIGHTNING CURRENT FROM THE VARIABLE PITCH TIP OF THE ROTOR TO THE FIXED PITCH PORTION OF THE BLADE.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Bonding strap is open circuited.						ALL	
2 Bonding strap has high resistance due to fraying.						ALL	
3 Bonding strap has high resistance due to poor bond connection.						ALL	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ. %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	20	.2	2.8×10^3				1*
2	40	.2	1.4×10^3				1*
3	40	.2	1.4×10^3				1*
FAILURE DETECTION METHODS							
1 - 3 Periodic inspection.							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
<p>1-3 When lightning strikes the variable pitch tip of the rotor the resultant extremely high current will follow the path of least resistance to ground. If an infinite or high resistance path replaces the low resistance bond path the current will possibly flow through the tip pitch bearing or hydraulic lines causing local heating, pitting, or welding of parts.</p> <p>Redundant bonding straps will be used to preclude this failure mode, straps will be designed to minimize strap fatigue failures.</p> <p>* See page 21 for safety note.</p>							
				NAME G. TRUSK / H. Roth		DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

Rev. 10/5/78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM ROTOR			COMPONENT FEATHER LOCK MECHANISM			PAGE 23 FMEA NO 4.3.2	
FUNCTION OF COMPONENT TO HOLD BLADE TIP IN THE FEATHERED POSITION							
FAILURE MODES & EFFECTS 1 MECHANISM FAILS TO LOCK						APPLICABLE OPERATING MODES A,B,C,D,E,F,H,I	
2 MECHANISM FAILS TO UNLOCK						F,G	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	10	2.3	500			X	
2	90	2.3	55.6			X	

FAILURE DETECTION METHODS

1 TIP POSITION INDICATOR SHOWS MOVEMENT AND PITCH LOCK STATUS INDICATES UNLOCKED.

2 TIP DOES NOT RESPOND TO COMMAND - START-UP NOT POSSIBLE.

3

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

1. SINCE ONLY ONE TIP IS REQUIRED TO STOP WTS, A FAILURE TO LOCK WILL NOT PREVENT A WTS SHUTDOWN.

2. FAILING TO UNLOCK IS A FAIL-SAFE FEATURE. WTS WILL BE INSPECTED FOR FAILURE CAUSE.

NAME M. A. HOYT **DATE 8/15/78**

OPERATING MODES

A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER
C WARM UP	F TRANSITION TO OPERATE	I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM ROTOR			COMPONENT FASTENERS, ROD ENDS			PAGE 24 FMEA NO 4.3.2	
FUNCTION OF COMPONENT ATTACHEMENT OF ACTUATOR TO BLADE AND TIP.							
FAILURE MODES & EFFECTS 1 ROD END BEARINGS WEAR EXCESSIVELY. 2 ROD END BREAKS 3 4						APPLICABLE OPERATING MODES	
						G	
						G	
						G	
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)		FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %			COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III
1	98	6.8	17		X		
2	2	6.8	833			X	
FAILURE DETECTION METHODS							
1 INSPECTION, TIP POSITION INDICATOR.							
2 INSPECTION, TIP POSITION INDICATOR.							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1. EXCESSIVE WEAR WILL BE INDICATED BY TIP POSITION MOVEMENT AT A FIXED COMMAND.							
2. SINCE TIPS ARE CONTROLLED INDEPENDENTLY, FAILURE OF ONE TIP ROD END WILL NOT PREVENT AN EMERGENCY SHUT DOWN BY THE OTHER TIP.							
				NAME		MAURIE HOYT	
				DATE		8/15/78	
OPERATING MODES							
A SHUTDOWN		D - TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H - TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I - FEATHER			

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN		COMPONENT (PART OF LOW SPEED SHAFT & BEARINGS) SHAFT		PAGE 25 FMEA NO 5.1.1			
FUNCTION OF COMPONENT TO TRANSMIT TORQUE FROM ROTOR TO THE QUILL SHAFT AND REACT ROTOR MOMENT (FROM OVERHUNG WEIGHT).							
FAILURE MODES & EFFECTS 1 BROKEN TEETER SHAFT OR SHAFT FLANGE JOINT - ROTOR COULD FALL OFF				APPLICABLE OPERATING MODES G			
2 BROKEN QUILL SHAFT BULKHEAD JOINT - WOULD ALLOW ROTOR TO FREEWHEEL				G			
3 DEFORMED SHAFT STRUCTURE - COULD CAUSE IMBALANCE AND BEARING FAILURE				G			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	5	1.1	2000				X
2	5	1.1	2000				X
3	90	1.1	111				X
FAILURE DETECTION METHODS							
1 LOSS OF ROTOR CAUSES LOSS OF GENERATOR LOAD, INITIATES (ELECTRICAL) EMERGENCY SHUTDOWN AS UTILITY TRIES TO DRIVE GENERATOR							
2 LOSS OF GENERATOR RESULTS IN ACTIONS ABOVE (1) PLUS OVERSPEED OF ROTOR TRIGGERS FEATHERING OF BLADES AND SUBSEQUENT APPLICATIONS OF ROTOR BRAKE.							
3 VIBRATIONS & INCREASED TEMPERATURE SENSED AT BEARINGS WOULD INITIATE EMERG. SHUTDOWN.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1. SAFE LIFE DESIGN INCIPIENT FAILURE DETECTION DEVICES NOT PRACTICAL.							
2. EMERGENCY SHUTDOWN PROCEDURE PREVENTS ROTOR OVERSPEED IN EXCESS OF DESIGN LIMITS.							
3. NONE REQUIRED.							
				NAME ROLF LUTH		DATE 8/7/8	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN			COMPONENT RADIAL BEARING (FLUID)			PAGE 26 FMEA NO 5.1.2	
FUNCTION OF COMPONENT TO SUPPORT LOW SPEED SHAFT BY DECREASING RUNNING FRICTIONS AND TO REACT ROTOR MOMENT (FROM OVERTURNING) ROTOR WEIGHT.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 BEARING FAILURE WHILE IN MOTION - CAUSES HIGH VIBRATION AND OVER-TEMPERATURE.						F, G, H	
2 BEARING FAILURE WHILE PARKED - INCREASED BREAKAWAY MOMENT LEADING TO FM (1) WHEN BROKEN LOOSE						ALL	
3 DETERIORATED BEARING - INCREASED FRICTION AND TEMPERATURE						ALL	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	10	10.3	111			X	
2	Cannot be accurately estimated				X		
3	90	10.3	12.3			X	
FAILURE DETECTION METHODS							
1 TEMPERATURE AND VIBRATIONS SENSORS WOULD INITIATE EMERGENCY SHUTDOWN.							
2 THERE IS NO-INSTRUMENTATIONS THAT SENSES EXCESSIVE BREAKAWAY TORQUE, HOWEVER, ONCE IN MOTION FAILURE WOULD BE DETECTED PER FM(1) ABOVE							
3 EXCESSIVE TEMPERATURE INITIATES EMERGENCY SHUTDOWN.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
2. System will be designed to allow lubrication of bearing if stationary for extended periods.							
NAME ROLF LUTH						DATE 8/7/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN			COMPONENT TEETER BEARING			PAGE 27 FMEA NO 5.1.3	
FUNCTION OF COMPONENT ACCOMMODATES TEETER MOTION, TRANSMITS ROTOR TORQUE TO LOW SPEED SHAFT, SUPPORTS WEIGHT OF ROTOR, REACTS ROTOR DRAG LOAD							
FAILURE MODES & EFFECTS 1 SHEAR FAILURE OF ELASTOMER - 1 2						APPLICABLE OPERATING MODES ALL	
2 FAILURE OF BOND BETWEEN ELEASTOMER & METAL PARTS 1 2 3						ALL	
3 DETERIORATION OF ELASTOMER DUE TO OIL, OZONE, OR LIGHTNING - PRIMARILY SURFACE EFFECTS, BUT MAY SHORTEN LIFE.						ALL	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ. %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	33	22.8	15			X	
2	33	22.8	15			X	
3	33	22.8	15			X	
FAILURE DETECTION METHODS							
1 VISUAL							
2 VISUAL							
3 VISUAL							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1 MAY ALLOW EXCESSIVE DISPLACEMENT OF ROTOR DUE TO DEAD WEIGHT AND DRAG LOADS RESULTING IN INCREASED VIBRATION							
2 FAILURE PROGRESSES VERY SLOWLY AND IS VISUALLY DETECTABLE. IF FAILURE IS FIRST DETECTED AT 35% OF LIFE, BEARING WILL PROBABLY COMPLETE 100% OF LIFE CYCLES SATISFACTORILY.							
3 CORROSION OF METAL PARTS MAY ACCELERATE BOND FAILURE. PERIODIC INSPECTIONS REQUIRED.							
NAME D. W. KING						DATE 7/19/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN		COMPONENT RADIAL/THRUST BEARING		PAGE 28 FMEA NO 5.1.4		
FUNCTION OF COMPONENT SUPPORT LOW SPEED SHAFT BY DECREASING RUNNING FRICTIONS AND TO REACT ROTOR MOMENT (FROM OVERHUNG ROTOR WEIGHT) AND ROTOR THRUST						
FAILURE MODES & EFFECTS 1 BEARING FAILURE WHILE IN MOTION CAUSES HIGH VIBRATIONS AND TEMPERATURE AND COULD CAUSE FAILURE OF RADIAL BEARING AND GEARBOX BY 2 FAILURE TO REACH THRUST. 2. BEARING FAILURE WHILE PARKED - INCREASED BREAK-AWAY MOMENT LEADING 2 TO FM (1) ABOVE WHEN BROKEN LOOSE. 3. DETERIORATED BEARING - INCREASED FRICTION, TEMPERATURE AND VIBRATION 4 CORROSION WHILE STATIONARY OVER EXTENDED PERIODS DUE TO OIL DRAINING OFF BEARING SURFACES				APPLICABLE AND OPERATING MODES F, G, H, I ALL ALL		
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %		COMPONENT FAILURE RATE $\times 10^6$ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III
1	55	10.3	20.2		X	
2, 4		INCLUDED IN 1 AND 3			X	
3	45	10.3	24.7	X		
FAILURE DETECTION METHODS						
TEMPERATURE AND VIBRATIONS SENSORS WOULD INITIATE EMERGENCY SHUTDOWN. THERE IS NO INSTRUMENTATIONS THAT SENSES EXCESSIVE BREAKAWAY TORQUE, HOWEVER, ONCE IN MOTION FAILURE WOULD 2 BE DETECTED PER FM ABOVE.						
3 EXCESSIVE TEMPERATURE INITIATES EMERGENCY SHUTDOWN.						
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)						
SYSTEM WILL BE DESIGNED TO ALLOW LUBRICATION OF BEARING IF STATIONARY FOR EXTENDED PERIODS.						
				NAME R. LUTH		DATE 8/7/78
OPERATING MODES						
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN			COMPONENT TEETER STOP			PAGE 29 FMEA NO. 5.1.5	
FUNCTION OF COMPONENT RESTRAIN TEETERING MOTION OF THE ROTOR WHEN THE TURBINE IS SHUT DOWN. LIMITS TEETER ANGLE.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 BRAKE FAILS TO RELEASE - BRAKE LINING & PLATE WILL WEAR OUT DUE TO SLIPPAGE.						G	
2 BRAKE FAILS TO APPLY OR IS WORN OUT -ROTOR BANGS ON MOTION LIMIT STOPS						A,B,C,D,E,F,H,I	
3 MOTION STOP BUMPERS FAIL - EXCESSIVE TEETER ANGLE, MAY CONTACT TOWER						A,B,C,D,E,F,H,I	
4 LEAKS						G	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	20	22.8	25			X	
2	4	22.8	125			X	
3	1	22.8	500			X	
FAILURE DETECTION METHODS							
4 75 VISUAL INSPECTION			6.7		X		
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1. BRAKE WILL SLIP AND EVENTUALLY WEAR OUT. NO MAJOR DAMAGE RESULTS.							
2. REQUIRES PERIODIC INSPECTION & REPLACEMENT OF WORN BRAKE LINING.							
3,4 REQUIRES PERIODIC INSPECTION.							
				NAME	D. W. KING	DATE	7/18/78
OPERATING MODES							
A SHUTDOWN	B TRANSITION TO WARM UP	C WARM UP	D TRANSITION TO STANDBY	E STANDBY	F TRANSITION TO OPERATE	G OPERATE	H TRANSITION TO FEATHER
						I FEATHER	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN - EPS			COMPONENT SLIP RINGS			PAGE 30 FMEA NO 5.1.6.1	
FUNCTION OF COMPONENT PROVIDES THE ROTATING PORTION OF THE PATH FOR THE FLOW OF ELECTRICAL POWER AND SIGNALS BETWEEN THE NACELLE AND THE DRIVE TRAIN							
FAILURE MODES & EFFECTS 1 SLIP RING FAILURES RESULT IN LOSS OF POWER AND/OR SIGNALS. ALL POWER AND SIGNAL LINES ARE ADDRESSED UNDER THEIR RESPECTIVE SUBSYSTEMS.						APPLICABLE OPERATING MODES ALL	
2							
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
ALL	100	37.6	3				

FAILURE DETECTION METHODS
1
2
3

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

SEE INDIVIDUAL CABLES FOR FAILURE EFFECTS AND DETECTION METHODS

NAME G. TRUSK		DATE 8/17/78
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OPERATING MODES

A SHUTDOWN
B TRANSITION TO WARM UP
C WARM UP

D TRANSITION TO STANDBY
E STANDBY
F TRANSITION TO OPERATE

G OPERATE
H TRANSITION TO FEATHER
I FEATHER

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN - EPS		COMPONENT SLIP RING JUNCTION BOX		PAGE 31 FMEA NO 5.1.6.2			
FUNCTION OF COMPONENT PROVIDES A PROTECTED ELECTRICAL JUNCTION POINT FOR THE WIRES COMING OUT OF THE SLIP RINGS AND THE CABLES DISTRIBUTING POWER AND SIGNALS.							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 Open circuited conductor within junction box. Loss of associated function.				ALL			
2 Short circuited conductors within junction box. Loss of associated functions, erratic operation, or loss of meaningful data.				ALL			
3 Conductor grounded within junction box. Loss of associated function.				ALL			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY *			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.1	200				
2	25	1.1	400				
3	25	1.1	400				
FAILURE DETECTION METHODS							
1 - 3 *							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
<p>* See individual cables for failure effects and detection methods for each signal and power line.</p>							
				NAME G. TRUSK / H. Roth		DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM		COMPONENT		PAGE 32			
DRIVE TRAIN - EPS		POWER CABLE TO HYDRAULIC SYSTEM		FMEA NO 5.1.6.3.1			
FUNCTION OF COMPONENT							
PROVIDES A PATH FOR THE FLOW OF ACCESSORY POWER ON THE LOW SPEED SHAFT FROM THE SLIP RING JUNCTION BOX TO THE PITCH CONTROL HYDRAULIC SYSTEM.							
FAILURE MODES & EFFECTS							
1 Conductor is open circuited. Hydraulic pump motors may operate at reduced capacity. WTS may shutdown.					APPLICABLE OPERATING MODES F,G,H		
2 Conductor is short circuited. Hydraulic pump motors may operate at reduced capacity. WTS may shutdown.					F,G,H		
3 Conductor is grounded. Hydraulic pump motors may operate at reduced capacity. WTS may shutdown.					F,G,H		
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500			1*	
2	25	.15	>3000			1*	
3	25	.15	>3000			1*	
FAILURE DETECTION METHODS							
1 - 3 WTS may shutdown if hydraulic accumulator pressure cannot be maintained.							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1 - 3 Periodic review of CRT data should reveal that pitch accumulator pressure has been low.							
1* Pump motors can run on 2 of the 3 phases; however, motor temperature will increase and capacity will be reduced.							
NAME G. TRUSK /H. Roth DATE 8/17/78							
OPERATING MODES							
A SHUTDOWN		D - TRANSITION TO STANDBY		G OPERATE		H TRANSITION TO FEATHER	
B TRANSITION TO WARM UP		E STANDBY		I FEATHER			
C WARM UP		F TRANSITION TO OPERATE					

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN - EPS			COMPONENT CONTROL CABLE TO THE HYDRAULIC SYSTEM			PAGE 33 ITEM NO 5.1.6.3.2	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF COMMANDS AND OPERATIONAL DATA ON THE LOW SPEED SHAFT FROM THE SLIP RING JUNCTION BOX TO THE ROTOR PITCH CONTROL HYDRAULIC SYSTEM.							
FAILURE MODES & EFFECTS							APPLICABLE OPERATING MODES
1 A control or data wire is open circuited. Control function cannot be accomplished. WTS will shutdown.							F,G,H
2 A control or data wire is shorted to another wire. Incorrect commands or data present. WTS will shutdown.							F,G,H
3 A control of data wire is grounded Control function cannot be accomplished. WTS will shutdown.							F,G,H
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500			1	
2	25	.15	>2000			1	
3	25	.15	>3000			1	
FAILURE DETECTION METHODS							
1 - 3 WTS shutdown due to differential pitch signals.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME G. TRUSK / H. Roth		DATE 8/17/78	
OPERATING MODES							
A - SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN - EPS			COMPONENT ROTOR ACTUATOR CONTROL CABLE			PAGE 34 FMEA NO 5.1.6.3.3	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF COMMANDS AND OPERATIONAL DATA ON THE LOW SPEED SHAFT FROM THE SLIP RING JUNCTION BOX TO THE ROTOR JUNCTION BOX.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 A control or data wire is open circuited. Control function cannot be accomplished. WTS will shutdown.						ALL	
2 A control or data wire is shorted to another wire, incorrect commands or data present. WTS will shutdown.						ALL	
3 A control or data wire is grounded. Control function cannot be accomplished. WTS will shutdown.						ALL	
4							
FAILURE FREQUENCY				FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500			1	
2	25	.15	>3000			1	
3	25	.15	>3000			1	
FAILURE DETECTION METHODS							
1 - 3 WTS shutdown due to differential pitch position signals.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME	G. TRUSK / H. Roth		DATE 8/17/78
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN-EPS			COMPONENT FLEX CABLE ACROSS TEETER BEARING			PAGE 35 FMEA NO 5.1.6.3.4	
FUNCTION OF COMPONENT PROVIDES A PATH ACROSS THE TEETER BEARING FOR THE FLOW OF COMMANDS AND OPERATIONAL DATA FROM THE ROTOR JUNCTION BOX TO THE ROTOR.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MOLES	
1 A control or data wire is open circuited. Control function cannot be accomplished. WTS will shutdown.						ALL	
2 A control or data wire is shorted to another wire. Incorrect commands or data present. WTS will shutdown.						ALL	
3 A control or data wire is grounded. Control function cannot be accomplished. WTS will shutdown.						ALL	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2,3	100	11.41	10			X	
FAILURE DETECTION METHODS							
1 WTS shutdown due to differential pitch position signals.							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
						NAME	G. TRUSK
						DATE	8/17/78
OPERATING MODES						REV. 10/5/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN - EPS		COMPONENT TEETER BEARING BONDING STRAP		PAGE 36 FMEA NO 5.1.6.3.5			
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF LIGHTNING CURRENT AROUND THE TEETER BEARING FROM THE ROTOR TO THE DRIVE TRAIN.							
FAILURE MODES & EFFECTS 1 Bonding strap is open circuited.				APPLICABLE OPERATING MODES ALL			
2 Bonding strap has high resistance due to fraying.				ALL			
3 Bonding strap has high resistance due to poor bond connection.				ALL			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	5	1.1	2000			1*	
2	50	1.1	200			1*	
3	45	1.1	222			1*	
FAILURE DETECTION METHODS							
1 - 3 Periodic Inspection							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1-3 When lightning strikes a rotor blade the resultant extremely high current will follow the path of least resistance to ground. If an infinite or high resistance path replaces the low resistance bond path the current will possibly flow through the teeter bearing resulting in erratic operation and WTS shutdown. Redundant bonding straps will be used to preclude this failure mode. Straps will be designed to minimize strap fatigue failures. Straps will be inspected periodically. Probability of both straps failing is negligible.							
1* Rotor will operate with the teeter mechanism inoperative.							
				NAME	G. TRUSK / H. Roth	DATE 8/17/78	
OPERATING MODES						Rev. 10/5/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I - FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN - EPS			COMPONENT ROTOR JUNCTION BOX			PAGE 37 FMEA NO 5.1.6.4	
FUNCTION OF COMPONENT PROVIDES A PROTECTED ELECTRICAL JUNCTION POINT FOR THE RIGID CABLE COMING OUT THE SLIP RING JUNCTION BOX AND THE FLEXIBLE CABLE GOING AROUND THE TEETER BEARING.							
FAILURE MODES & EFFECTS 1 <u>Open circuited conductor within junction box. Loss of associated function.</u>						APPLICABLE OPERATING MODES ALL	
2 <u>Short circuited conductors within junction box. Loss of associated functions, erratic operation, or loss of meaningful data.</u>						ALL	
3 <u>Conductor grounded within junction box. Loss of associated function.</u>						ALL	
4 _____							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	5	44			X	
2	25	5	88			X	
3	25	5	88			X	
FAILURE DETECTION METHODS							
1 WTS shutdown. See individual signal and power lines.							
2 _____							
3 _____							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							

See individual signal wires for impacts.							

						NAME G. TRUSK / H. Roth	
						DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN		COMPONENT QUILL SHAFT		PAGE 38 FMEA NO 5.2.1	
FUNCTION OF COMPONENT TO TRANSMIT ROTOR TORQUE FROM THE LOWSPEED SHAFT TO THE GEAR BOX AND TO LIMIT TORSIONAL ROSONANCE					
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES	
1 SHAFT FAILURE - WOULD ALLOW ROTOR TO FREE WHEEL				F, G, H	
2					
3					
4					

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	100	3.4	33.3				X*
2							
3							
4							

FAILURE DETECTION METHODS

1 LOSS OF GENERATOR LOAD INITIATES (ELECTRICAL) EMERGENCY SHUTDOWN DUE TO SUDDEN DROP IN POWER OUTPUT. AS BACKUP TO THIS SHUTDOWN PROCEDURE, THE OVERSPEED SWITCH ON THE LOW SPEED SHAFT INITIATES SHUTDOWN.

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

STRUCTURAL AND FATIGUE ANALYSIS ACCOMPLISHED TO CONFIRM ADEQUATE SAFETY MARGIN IN DESIGN. WTS WILL NOT EXCEED DESIGN OVERSPEED LIMITS UNDER THESE CONDITIONS.

* DESIGNATED CATISTROPHIC DUE TO HIGH COST OF REPLACING THE QUILL SHAFT.

NAME ROLF LUTH		DATE 8/7/8
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OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM-UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN			COMPONENT QUILL SHAFT COUPLING			PAGE 39 FMEA NO 5.2.2	
FUNCTION OF COMPONENT TO TRANSMIT TORQUE FROM LOW SPEED SHAFT TO GEAR BOX AND TO ACCOMMODATE SHAFT MISALIGNMENT							
FAILURE MODES & EFFECTS 1 COUPLING STRUCTURAL FAILURE - WOULD PERMIT ROTOR TO FREEWHEEL						APPLICABLE OPERATING MODES F,G,H	
2 COUPLING INCIPIENT FAILURE OR DAMAGE DUE TO OVERLOAD						F,G,H	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	10	13.7	137			X	
2	90	13.7	9.3		X		
3							
4							

FAILURE DETECTION METHODS

1 BREAK IN LOAD PATH CAUSES LOSS OF GENERATOR LOAD WHICH INITIATES EMERGENCY SHUT DOWN AS UTILITY TRIES TO DRIVE GENERATOR.

2 INEFFICIENT JOINTS CAN CAUSE UNDETECTABLE TEMP. RISE - ULTIMATE FAILURE DETECTED PER FM(1) ABOVE

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

1 IF DETECTED BY INSPECTION PRIOR TO FAILURE MODE 1 OCCURRING.

ROTOR OVERSPEED IS WITHIN DESIGN LIMITS.

		NAME ROLF LUTH	DATE 8/7/8
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OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM-UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G - OPERATE

H TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN			COMPONENT GEARS AND SHAFTS			PAGE 41 FMEA NO 5.3.2	
FUNCTION OF COMPONENT TO TRANSFER ROTOR TORQUE AND INCREASE RPM (FROM 17.5 RPM TO 1800 RPM)							
FAILURE MODES & EFFECTS 1 LOSS OF LOAD PATH DUE TO CHIPPED GEAR OR SHEARED SHAFT - WOULD ALLOW ROTOR TO FREE WHEEL.						APPLICABLE OPERATING MODES F,G,H	
2 DAMAGED GEAR TEETH - COULD EVENTUALLY LEAD TO FM(1) ABOVE						F,G,H	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	5	3.4	667				X
2	95	3.4	35			X	
3							
4							

FAILURE DETECTION METHODS

1 LOSS OF GENERATOR LOAD DUE TO BROKEN LOAD PATH WILL INITIATE (TECHNICAL) EMERGENCY SHUTDOWN AS UTILITY TRIES TO DRIVE GENERATOR. (2) DAMAGED GEAR TEETH SHOULD BE INDICATED BY CHIP DETECTOR IN SUMP WHICH SHUTS DOWN SYSTEM. ROTOR OVERSPEED WILL ALSO INITIATE SHUTDOWN, VIA RPM SENSOR.

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

Rotor overspeed will be within design limits

NAME ROLF LUTH		DATE 8/7/8
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OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM-UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G - OPERATE

H TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN			COMPONENT GEAR BOX BEARINGS			PAGE 42 FMEA NO 5.3.3	
FUNCTION OF COMPONENT TO ALIGN GEAR TRAIN COMPONENTS AND REDUCE GEAR/SHAFT FRICTION							
FAILURE MODES & EFFECTS 1 BEARING FAILURE WHILE RUNNING - RESULTANT MISALIGNMENT OF GEARS						APPLICABLE OPERATING MODES F,G,H	
2 BEARING DETERIORATIONS - INCREASE IN TEMPERATURE AND NOISE LEVELS						A11	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	10	11.4	100				X
2	90	11.4	11.1			X	
3							
4							
FAILURE DETECTION METHODS							
1, 2 OIL TEMPERATURE AND VIBRATION SENSORS CAUSE SYSTEM SHUTDOWN.							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
TEMPERATURE AND VIBRATION SENSORS WILL PICK UP IMPENDING FAILURE PRIOR TO SERIOUS STRUCTURAL DAMAGE.							
						NAME R. LUTH	
						DATE 8/7/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN		COMPONENT HIGH SPEED SHAFT		PAGE 43 FMEA NO 5.4.1			
FUNCTION OF COMPONENT TO TRANSMIT TORQUE FROM GEARBOX TO GENERATOR							
FAILURE MODES & EFFECTS 1 - BROKEN SHAFT - WOULD ALLOW ROTOR TO FREE WHEEL 2 3 4				APPLICABLE OPERATING MODES F, G, H			
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)		FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %			COMPONENT FAILURE RATE $\times 10^6$ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III
	100	3.4	33.3			X	
FAILURE DETECTION METHODS							
1 LOSS OF GENERATOR LOAD WOULD SHUT DOWN GENERATOR AND FEATHER BLADES.							
SHUTDOWN INITIATED THROUGH OVERSPEED SENSORS.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
ROTOR OVERSPEED PRIOR TO SHUTDOWN WOULD BE WITHIN DESIGN UNITS.							
				NAME R. LUTH		DATE 8/7/78	
OPERATING MODES Rev. 10/25/78 <div style="display: flex; justify-content: space-between; font-size: small;"> <div> A SHUTDOWN B TRANSITION TO WARM UP C WARM UP </div> <div> D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE </div> <div> G OPERATE H TRANSITION TO FEATHER I FEATHER </div> </div>							

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN		COMPONENT HIGH SPEED SHAFT COUPLING		PAGE 44 FMEA NO 5.4.2			
FUNCTION OF COMPONENT TO TRANSMIT TORQUE FROM GEAR BOX TO GENERATOR AND TO ACCOMODATE SHAFT MISALIGNMENT							
FAILURE MODES & EFFECTS 1 COUPLING STRUCTURAL FAILURE - WOULD PERMIT ROTOR TO FREE WHEEL 2. COUPLING INCIPIENT FAILURE OR DAMAGE DUE TO OVERLOAD/OVERFLEX - - INCREASE IN TEMPERATURE AND DECREASE IN EFFICIENCY. 3 4				APPLICABLE OPERATING MODES F,G,H			
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ. %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	5	13.7	167			X	
2	95	13.7	8.8			X	
FAILURE DETECTION METHODS 1 BREAK IN LOAD PATH CAUSES LOSS OF GENERATOR LOAD WHICH INITIATES EMERGENCY SHUT DOWN 2 OF GENERATOR AND THE FEATHERING OF THE BLADES. INEFFICIENT JOINTS CAN CAUSE UNDETECTED TEMPERATURE RISE - ULTIMATE FAILURE DETECTED PER 3 FM(1) ABOVE.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) INSPECTION OF WTS @ 2-MONTH INTERVALS SHOULD DETECT INCIPIENT FAILURES.							
				NAME ROLF LUTH		DATE 8/7/78	
OPERATING MODES A SHUTDOWN B TRANSITION TO WARM UP C WARM UP D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I FEATHER							
Rev. 10/25/78							

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN			COMPONENT ROTOR BRAKE			PAGE 45 FMEA NO 5.5	
FUNCTION OF COMPONENT TO POSITION AND HOLD ROTOR							
FAILURE MODES & EFFECTS 1. HYDRAULIC/ELECTRIC FAILURE WOULD CAUSE BRAKE TO CLOSE WHICH WOULD BURN IT OUT AT FULL TORQUE. 2. FAILURE OF BRAKE TO OPERATE WOULD PERMIT BLADE TO STOP AT ANY ANGLE AND WOULD PRECLUDE HOLDING ROTOR IN SELECTED POSITION.						APPLICABLE OPERATING MODES F, G, H A, B, C, D, E, H, I	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1.	95	18.3	6.6			X	
2.	5	18.3	125		X		
FAILURE DETECTION METHODS							
1. WTS SHUTDOWN UPON LOSS OF HYDRAULIC PRESSURE SENSED. 2. VISUAL INSPECTION							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
MOD-2 DESIGN INCORPORATES CAPABILITY TO MANUALLY TURN ROTOR AND LOCK LOW SPEED SHAFT IN DESIRED POSITION.							
						NAME ROLF LUTH	
						DATE 8/7/78	
OPERATING MODES							
A SHUTDOWN B TRANSITION TO WARM UP C WARM UP			D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE			G OPERATE H TRANSITION TO FEATHER I FEATHER	

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN			COMPONENT GEARBOX LUBRICATION			PAGE 46 FMEA NO 5.6.1	
FUNCTION OF COMPONENT PROVIDE LUBRICATION, AND REMOVE HEAT FROM THE GEARBOX BEARINGS AND GEARS.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 LUBRICANT PUMP FAILURE - AUXILIARY PUMP IS STARTED -						F,G,H	
2 SEAL FAILURE - LOSS OF FLUID - LOSS OF GEARBOX IF UNDETECTED						F, G, H	
3 HEATER FAILURE - WTS WILL NOT START - LOW FLUID TEMPERATURE						F, G, H	
4 BLOCKED FILTER - PRESSURE DIFFERENTIAL ACROSS FILTER TRIPS BYPASS VALVE, WTS SHUTDOWN AFTER TIME DELAY.						F,G,H,	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MARGINAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	100	20	6		X		
2	100	10	12		X		
3	100	5	30			X	
4		Not Applicable				X	
FAILURE DETECTION METHODS							
1 VISUAL INSPECTION							
X							
X 2. WTS SHUTDOWN							
X 3. WTS DOES NOT START							
X 4. WTS SHUTDOWN							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
<p>▷ THE GEARBOX LUBE SYSTEM IS REDUNDANT. IF A PUMP FAILURE DOES NOT RESULT IN THE STARTING OF THE AUXILIARY PUMP THE WTS WILL SHUT DOWN.</p> <p>▷ PUMP AND SEALS ARE REDUNDANT. THIS FAILURE RATE IS FOR A SINGLE PUMP. PROBABILITY OF BOTH PUMPS FAILING BEFORE THE FIRST ONE IS REPAIRED IS NEGLIGIBLE.</p>							
NAME ROLF LUTH						DATE 10/20/78	
OPERATING MODES						Rev. 10/25/78	
A SHUTDOWN		D TRANSITION TO STBY		G OPERATE		3/8/79	
B TRANSITION TO WARM UP*		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO CRUISE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN			COMPONENT GENERATOR LUBRICATION			PAGE 48 FMEA NO 5.6.3	
FUNCTION OF COMPONENT PROVIDES LUBRICATION TO THE SLEEVE BEARINGS SUPPORTING THE GENERATOR ROTOR AT EACH END OF THE GENERATOR FRAME.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 LOSS OF OIL: LOSS OF LUBRICATION CAPABILITY						F,G	
2 DIRTY OIL: EXCESSIVE WEAR ON MOVING PARTS						F,G	
3 OIL TOO THICK (COLD)						F	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	100	10	11.4			X	
2		Negligible	with Preventative Maint.		X		
3	100	1	114			X	
4							
FAILURE DETECTION METHODS							
1 WTS SHUTDOWN WHEN BEARING OVER TEMPERATURE IS PRESENT.							
2 NONE, UNLESS OVERTEMP OCCURS							
3 WTS IS SHUTDOWN							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1 IF UNDETECTED BY INSPECTION PRIOR TO WTS SHUTDOWN.							
1. When oil level drops below oil ring, lubrication of the bearing begins to deteriorate until insufficient lubrication is possible. The bearings are excessively worn and temperature rises until bearing overtemperature protection initiates WTS shutdown. On-site review of stored data will identify the source of trouble. Check oil-level sight gauge at each end of generator housing for low level or presence of oil on floor. Inspect and replace bearing if necessary.							
2. Periodic maintenance should detect this condition.							
3. Generator space heaters will keep the oil warm. See also FMED 6.8.3.11.							
NAME H. ROTH						DATE 10/20/8	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM DRIVE TRAIN ASSEMBLY - EPS			COMPONENT GENERATOR			PAGE 49 FMEA NO 5.7	
FUNCTION OF COMPONENT CONVERTS SHAFT TORQUE AT 1800 RPM INTO ELECTRICAL POWER							
FAILURE MODES & EFFECTS 1 ELECTRICAL WINDING FAIL TO OPEN. CAUSES LOSS OF ELECTRICAL POWER OUTPUT AND WTS SHUTDOWN 2 ELECTRICAL WINDING FAIL SHORTED OR GROUNDED: CAUSES LOSS OF ELECTRICAL POWER OUTPUT AND WTS SHUTDOWN 3 GENERATOR OVERHEATS. CAUSES GENERATOR CIRCUIT BREAKER TO OPEN WHICH CAUSES WTS TO SHUT DOWN. 4 GENERATOR MECHANICAL FAILURE: CAUSES ABNORMAL POWER GENERATION WHICH OPENS GENERATOR CIRCUIT BREAKER WHICH CAUSES SHUTDOWN.							APPLICABLE OPERATING MODES F, G F, G F, G F, G
FAILURE FREQUENCY				FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ. %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2,3,4	100	10.3	11.1			X	

FAILURE DETECTION METHODS	
1	POWER PROTECTIVE RELAYS SEE SECTION 6.8
2	
3	

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

GENERATOR HAS MULTIPLE PROTECTIVE DEVICES SENSING CURRENT, VOLTAGE AND
 TEMPERATURE. EACH INITIATES WTS SHUTDOWN UPON WARNING SIGNAL.

NAME G. TRUSK	DATE 8/17/78
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OPERATING MODES
 A SHUTDOWN
 B - TRANSITION TO WARM-UP
 C WARM UP

D TRANSITION TO STANDBY
 E STANDBY
 F TRANSITION TO OPERATE

G OPERATE
 H TRANSITION TO FEATHER
 I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE			COMPONENT PRIMARY TRUSS STRUCT.			PAGE 50 FMEA NO 6.1.1.	
FUNCTION OF COMPONENT							
PRIMARY TRUSS THAT SUPPORTS ROTOR SHAFT GEARBOX							
GENERATOR SECONDARY STRUCTURE MISC. EQUIPMENT.							
TRANSFERS LOAD TO YAW BEARING SUPPORT STRUCTURE							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 CRACK IN WELD OR TRUSS MEMBERS						ALL	
INITIATES COLLAPSE OF NACELLE							
2 CORROSION OF WELD OR MEMBER						ALL	
INITIATES COLLAPSE OF NACELLE							
3 EXCESSIVE NACELLE DEFLECTION						F, G, H.	
LONG TERM DAMAGE TO BEARINGS AND/OR COUPLING							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2,3	100	11.4	10		X		
FAILURE DETECTION METHODS							
1 HIGH LEVEL OF INITIAL INSPECTION OF WELDS AND STRUCTURE.							
2 MORE FREQUENT INSPECTION INTERVAL							
3 ALIGNMENT CHECK PERIODICALLY.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
WELD CRACKING FAILURE CAN BE REDUCED BY MORE EXTENSIVE INITIAL INSPECTION OF WELDS.							
PERIODIC INSPECTION OF CRITICAL WELDS SHOULD DETECT CRACK BEFORE TOTAL MEMBER FAILURE.							
MULTIPLE LOAD PATHS OF TRUSS STRUCTURE MAY ALLOW MORE EXTENDED INSPECTION INTERVAL.							
CORROSION MAY BE PREVENTED BY FREQUENT PAINT TOUCHING-UP AND INSPECTION AND REPAIR ON CRITICAL MEMBERS.							
NAME K. HERNLEY						DATE 8-16-78	
Rev. 10/25/78							
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE			COMPONENT SECONDARY SUPPORT STRUCT.			PAGE 51 FMEA NO 6.1.2	
FUNCTION OF COMPONENT SUPPORTS ENCLOSURE AND WALKWAYS AROUND GENERATOR BAY							
FAILURE MODES & EFFECTS 1 CRACKS IN WELDS ENCLOSURE DAMAGE - 2 CORROSION DAMAGE ENCLOSURE DAMAGE 3 4						APPLICABLE OPERATING MODES ALL ALL	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2	100	11.4	10		X		
FAILURE DETECTION METHODS							
1 HIGH LEVEL OF INITIAL WELD INSPECTION							
2 FREQUENT INSPECTION							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
WELD CRACKING CAN BE REDUCED BY MORE COSTLY INITIAL INSPECTION OR ENCLOSURE ISOLATION BY ELASTOMERIC MOUNTS. FREQUENT VISUAL INSPECTION WOULD DETECT FAILURES OF MEMBERS. MULTIPLE LOAD PATHS DECREASE PROBABILITY OF UNDETECTED FAILURE							
						NAME K. HERNLEY	
						DATE 8-16-78	
OPERATING MODES							
A SHUTDOWN B TRANSITION TO WARM UP C WARM UP			D - TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE			G OPERATE H TRANSITION TO FEATHER I - FEATHER	

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM		COMPONENT		PAGE			
NACELLE		YAW BEARING SUPPORT STRUCTURE		52			
FUNCTION OF COMPONENT		FMEA NO		6.1.3			
TRANSFERS LOADS FROM NACELLE TO YAW BEARING							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 CRACKS IN WELDS - NACELLE DISPLACEMENT				ALL			
2 CORROSION OF WELD OR MEMBER - NACELLE DISPLACEMENT				ALL			
3							
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1		Included in 6.1.1			X	X	
2					X	X	
FAILURE DETECTION METHODS							
1							
2 FREQUENT INSPECTION							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
WELD CRACKING CAN BE REDUCED BY HIGH LEVEL OF INITIAL INSPECTION.							
FREQUENT INSPECTION OF CRITICAL WELDS MAY DETECT CRACK BEFORE FAILURE.							
MULTIPLE WELDS & GUSSETS INCREASE TIME TO FAILURE							
IF DETECTED EARLY							
NAME K. HERNLEY							
DATE 8/16/78							
Rev. 10/25/78							
OPERATING MODES							
A SHUTDOWN							
B - TRANSITION TO WARM UP							
C - WARM-UP							
D TRANSITION TO STANDBY							
E STANDBY							
F TRANSITION TO OPERATE							
G OPERATE							
H TRANSITION TO FEATHER							
I - FEATHER							

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE			COMPONENT FWD BEARING SUPPORT			PAGE 53 FMEA NO 6.1.4	
FUNCTION OF COMPONENT TRANSFERS RADIAL LOAD FROM LIVE-SHAFT TO NACELLE TRUSS.							
FAILURE MODES & EFFECTS 1 WELD FAILURE RESULTS IN ROTOR DISPLACEMENT						APPLICABLE OPERATING MODES A11	
2 WILL DAMAGE/DESTROY BOTH SHAFT BEARINGS, LIVE SHAFT, AND COUPLING.						A11	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1 & 2		Included in 6.1.1			X	X*	
FAILURE DETECTION METHODS							
1 HIGH LEVEL INITIAL INSPECTION							
2 FREQUENT INSPECTION							
3 INCREASING VIBRATION SENSED BY #1 VIBRATION MONITOR RESULTING IN WTS SHUTDOWN.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) THE BEARING SUPPORT TO TRUSS WELD IS MOST VULNERABLE. ADDITIONAL WELD AREA & HIGH FACTOR OF SAFETY REDUCES POSSIBILITY OF CATASTROPHIC FAILURE. FREQUENT INSPECTION AND MAINTENANCE OF PROTECTIVE PAINT ELIMINATES CORROSIVE DAMAGE. REDUNDANT SUPPORT DESIGN REDUCES POSSIBILITY OF SUDDEN COLLAPSE.							
* IF UNDETECTED							
						NAME	K. HERNLEY
						DATE	8/16/78
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE		COMPONENT AFT BEARING SUPPORT		PAGE 54 FMEA NO 6.1.5			
FUNCTION OF COMPONENT TRANSFERS RADIAL & THRUST LOADS FROM LIVE SHAFT TO NACELLE TRUSS							
FAILURE MODES & EFFECTS 1 WELD FAILURE				APPLICABLE OPERATING MODES			
LIVE SHAFT LIFTS & JAMS DRIVE TRAIN				F, G, H			
2							
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	Included in 6.1.1					X	
FAILURE DETECTION METHODS							
1 HIGH LEVEL OF INITIAL INSPECTION							
FREQUENT INSPECTION BY MAINTENANCE PERSONNEL							
#2 VIBRATION SENSOR INITIATES WTS SHUTDOWN							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) THE BEARING SUPPORT TO TRUSS WELD IS MOST VULNERABLE. THERE ARE MULTIPLE LOAD PATHS, REDUNDANT STRUCTURE, AND HIGHER FACTORS OF SAFETY TO MINIMIZE PROBABILITY OF CATASTROPHIC FAILURE MAINTENANCE OF PAINT ELIMINATES CORROSIVE DAMAGE.							
				NAME K. HERNLEY		DATE 8/16/78	
OPERATING MODES							
A - SHUTDOWN		D - TRANSITION TO STANDBY		G - OPERATE		Rev 10/25/7	
B - TRANSITION TO WARM UP		E - STANDBY		H - TRANSITION TO FEATHER			
C - WARM-UP		F - TRANSITION TO OPERATE		I - FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE			COMPONENT ENCLOSURE			PAGE 55 FMEA NO 6.1.6	
FUNCTION OF COMPONENT PROVIDES ADEQUATE ENVIRONMENTAL CONDITIONS FOR THE MAINTENANCE PERSONNEL & EQUIPMENT.							
FAILURE MODES & EFFECTS 1 SKIN OR STRINGER CRACKS AT FASTENERS LEAKS - EVENTUAL PARTIAL SKIN LOSS 2 CORROSION OF FASTENERS LEAKS - EVENTUAL PARTIAL SKIN LOSS 3 CORROSION OF SKIN OR STRINGERS RESULTING IN LEAKS 4 DAMAGE DUE TO LIGHTNING STRIKE AND/OR HAIL							APPLICABLE OPERATING MODES A11 A11 A11 A11
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1-4	Included in 6.1.1		X				
FAILURE DETECTION METHODS							
1-3 FREQUENT INSPECTION							
4 GROUNDING OF STRUCTURE TO PROVIDE LIGHTNING PATH.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
MAINTENANCE OF PAINT AND CORRODED FASTENER REPLACEMENT WILL REDUCE CORROSIVE DAMAGE. CORRUGATED SKINS REDUCE NUMBER OF FASTENERS PERHAPS PERMITTING MORE COSTLY CORROSION RESISTANT FASTENERS.							
				NAME		DATE	
				K. HERNLEY		8/16/78	
OPERATING MODES							
A SHUTDOWN B TRANSITION TO WARM UP C WARM-UP		D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE		G OPERATE H TRANSITION TO FEATHER I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM		COMPONENT BRAKE DISC		PAGE 56 FMEA NO 6.3.1			
FUNCTION OF COMPONENT SUPPORTS YAW BEARING AND PROVIDES CLAMPING SURFACE FOR BRAKE CALIPERS							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 CRACKS, OR BREAKS - COULD CAUSE BRAKE FAILURE AND/OR YAW BEARING FAILURE				ALL			
2 BRAKE SURFACE WARPING, PITTING, OR GALLING - CAUSING ERRATIC BRAKING				ALL			
3 DIRT OR LUBRICANT ON DISC - ERRATIC OR CHATTERING BRAKES				ALL			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	33	4.6	75.8		X		X
2	33	4.6	75.8		X		
3	33	4.6	75.8		X		
FAILURE DETECTION METHODS							
1 VISUAL INSPECTION OF DISC							
2 ERRATIC BRAKING							
3 SLOW OR ERRATIC YAW MOTION							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) LOW ALLOWABLES WILL MINIMIZE POTENTIAL FAILURES							
1 - IF UNDETECTED TO POINT OF YAW BEARING FAILURE							
OPERATING MODES				NAME J. W. ACKER		DATE 8/7/78	
A - SHUTDOWN B - TRANSITION TO WARM UP C - WARM UP				D - TRANSITION TO STANDBY E - STANDBY F - TRANSITION TO OPERATE		G - OPERATE H - TRANSITION TO FEATHER I - FEATHER	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT BEARING, GEAR, PINIONS			PAGE 57 FMEA NO 6.3.2	
FUNCTION OF COMPONENT THE BEARING SUPPORTS THE NACELLE AND PERMITS IT TO YAW. THE GEAR (PART OF THE BEARING) AND PINION TRANSMIT YAW DRIVE TORQUE FROM THE DRIVE GEAR BOX TO THE YAW BEARING.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 BEARING STRUCTURAL FAILURE - COULD CAUSE WTS TO BECOME INOPERABLE						F, G, H	
2 GALLING, BRINELLING, FRETTING - COULD CAUSE YAW MOTION TO BE ERRATIC, SLOW, OR COMPLETELY STOPPED						F, G, H	
3 GEAR FAILURE COULD CAUSE LOSS OF YAW ROTATION						F, G, H	
4 PINION FAILURE - WOULD CAUSE LOSS OF YAW DRIVE							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2,3,4	100	1.1	100			X	
FAILURE DETECTION METHODS							
1 VISUAL INSPECTION.							
2 OBSERVATION OF ERRATIC YAW MOTION, OR LACK OF MOTION							
3 EXCESS OR UNUSUAL NOISE.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
EXERCISE OF YAW SYSTEM TO MINIMIZE BRINELLING							
BEARING GEAR AND PINION SHOULD BE DESIGNED WITH A "WEAK LINK" TO MINIMIZE DAMAGE TO EXPENSIVE COMPONENTS							
						NAME J. W. ACKER	DATE 8/7/78
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev. 10/25/78	
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 11/27/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT GEAR BOX			PAGE 58 FMEA NO 6.3.3	
FUNCTION OF COMPONENT THE GEAR BOX PROVIDES TWO STAGES OF GEAR REDUCTION PERMITTING A HIGHER SPEED HYDRAULIC MOTOR TO DRIVE THE LOWER SPEED DRIVE PINION (AND LOW SPEED GEAR)							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 OIL SEAL FAILURE - LOSS OF LUBRICANT AND SUBSEQUENT GEAR BOX FAILURE						F,G,H	
2 GEAR BOX SEIZES OR JAMS - WTS WILL NOT YAW: IN EXTREME WINDS COULD CAUSE STRUCTURAL FAILURE						F,G,H	
3 GEAR BOX FAILS TO TRANSMIT TORQUE - WTS WILL NOT YAW OR COMMAND						ALL	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	~85	14.8	9			X	
2	10	14.8	154			X	
3	5	14.8	308			X	
FAILURE DETECTION METHODS							
BI-MONTHLY INSPECTION							
2. WTS FAILURE TO YAW ON COMMAND							
3. ERRATIC YAW MOTION							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME J. W. ACKER		DATE 8/7/78	
OPERATING MODES							
A - SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B - TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I - FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM " YAW DRIVE SYSTEM		COMPONENT HYDRAULIC MOTOR		PAGE 59 FMEA NO 6:3.4			
FUNCTION OF COMPONENT THE HYDRAULIC MOTOR SUPPLIES THE PRIME POWER TO THE YAW DRIVE GEAR TRAIN, ON COMMAND, TO CAUSE THE WTS TO YAW. -							
FAILURE MODES & EFFECTS 1 FLUID LEAKS EXTERNALLY - SYSTEM MAY LOSE PRESS. (FLUID) & FAIL TO OPERATE: 2 MOTOR FAILS TO OPERATE - SYSTEM WILL NOT YAW ON COMMAND 3 4				APPLICABLE OPERATING MODES F, G, H F, G, H			
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %		COMPONENT FAILURE RATE $\times 10^6$ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	85	13.7	9.8	X	1 X		
2	15	13.7	55.6			X	
FAILURE DETECTION METHODS							
1 LEAKS - VISUAL, RESERVOIR LEVEL DEPLETION, LOW HYD. PRESSURE, LOW TORQUES.							
2 FAILURE TO YAW - WTS WILL NOT ASSUME COMMANDED POSITION							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1 CRITICAL IF UNDETECTED LEADING TO GEARBOX FAILURE.							
				NAME J. W. ACKER		DATE 8/8/78	
OPERATING MODES						Rev. 10/25/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT HYDRAULIC PUMP & MOTOR			PAGE 60 FMEA NO 6.3.5	
FUNCTION OF COMPONENT SUPPLIES HYDRAULIC FLUID AT CONTROLLED 2000 PSI PRESSURE, ON DEMAND, TO OPERATE YAW HYDRAULIC MOTOR, YAW BRAKE CALIPERS, AND ROTOR BRAKE CALIPERS.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 PUMP LEAKS EXTERNALLY - SYSTEM MAY BE DEPLETED, THEN FAIL TO OPERATE						F,G,H	
2 PUMP FAILS TO MAINTAIN PRESSURE - SYSTEM MAY NOT FUNCTION PROPERLY (NO BRAKE RELEASE, SLOW YAW)						F,G,H	
3 PUMP FAILS - RESULTING LOSS OF PRESSURE WOULD PROHIBIT BRAKE RELEASE OR YAW MOTION						F,G,H	
4 MOTOR FAILS - SAME AS #3						F,G,H	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	33	3.4	101		X		
2	10	3.4	34			X	
3,4	57	3.4	58.5			X	
FAILURE DETECTION METHODS							
1-4 WTS Shutdown (low pressure sensor)							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME J. W. Acker		DATE 8/8/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT RESERVOIR			PAGE 61 FMEA NO 6.3.6	
FUNCTION OF COMPONENT CONTAINS A SUPPLY OF HYDRAULIC FLUID FOR THE YAW HYDRAULIC SYSTEM							
FAILURE MODES & EFFECTS 1 EXTERNAL LEAK - EVENTUALLY PRODUCES A LOW LEVEL ALARM, SPREADS OIL IN NACELLE, SHUTS DOWN SYSTEM						APPLICABLE OPERATING MODES F, G, H	
2 LIQUID LEVEL GAGE FAILS - PRODUCES FALSE HIGH OR LOW READINGS						F, G, H	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	90	6.8	18.5		X - ▸		
2	10	6.8	68	X			

FAILURE DETECTION METHODS

1 VISUAL INSPECTION OF RESERVOIR, SPILLED OIL IN NACELLE

2 LOW SYSTEM PRESSURE OR LEVEL OR SYSTEM INOPERATIVE

3

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

▸ IF DETECTED BY INSPECTION PRIOR TO CRITICAL FAILURE

NAME **J. W. ACKER**
DATE **8/8/78**

OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM-UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G - OPERATE

H TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM		COMPONENT HEAT EXCHANGER		PAGE 62	
FUNCTION OF COMPONENT COOLS HYDRAULIC FLUID TO LIMIT MAXIMUM TEMPERATURE		FMEA NO 6.3.6.2			
FAILURE MODES & EFFECTS 1 LEAKS FLUID, DEPLETES RESERVOIR, WTS SHUTS DOWN. WON'T YAW, WON'T RELEASE ROTOR BRAKE 2 THERMOSTAT FAILS, SYSTEM OVERHEATS, WTS SHUTS DOWN. 3 FAN FAILS, SYSTEM OVERHEATS, WTS SHUTS DOWN. 4				APPLICABLE OPERATING MODES F, G, H F, G, H F, G, H	
FAILURE FREQUENCY			FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II
				CRITICAL III	CATASTROPHIC IV
1	20	2.3	250		X
2	40	2.3	125		X
3	40	2.3	125		X
FAILURE DETECTION METHODS					
1 OVERTEMPERATURE SIGNAL					
2 LEAKING OIL IN NACELLE - VISUAL/LOW PRESS. SIGNAL					
3 HYDRAULIC SYSTEM FAILURE - OVERTEMP SIGNAL					
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)					
CRITICAL IF NOT DETECTED PRIOR TO SHUTDOWN.					
NAME J. W. ACKER				DATE 8/8/78	
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OPERATING MODES					
A SHUTDOWN		D TRANSITION TO STANDBY		G - OPERATE	
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT ACCUMULATORS (2)			PAGE 63 FMEA NO 6.3.6.3	
FUNCTION OF COMPONENT							
STORE ENERGY TO MAINTAIN RELEASED ROTOR BRAKE IF SYSTEM FAILS.							
REDUCE PUMP RIPPLE, DAMPEN HYDRAULIC SYSTEM PULSATIONS							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 GAS LEAKS-LOSS OF ACCUMULATOR CAPABILITY, RESULTING IN LOSS OF ABOVE FUNCTIONS						F, G, H	
2 OIL LEAKS-LOSS OF ACCUMULATOR CAPABILITY, LOSS OF ABOVE FUNCTIONS POSSIBLE SYSTEM FAILURE						F, G, H	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	27.4	8.3			X	
2	50	27.4	8.3		X	X	
3							
4							
FAILURE DETECTION METHODS							
1 MONITOR GAS PRESSURES IN ACCUMULATORS							
2 VISUAL INSPECTION FOR OIL LEAKS							
MONITOR SYSTEM PRESSURE, RESERVOIR LEVEL							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1 If Undetected							
				NAME J. W. ACKER		DATE 8/8/78	
OPERATING MODES							
A - SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM		COMPONENT RELIEF VALVES (3)		PAGE 64 FMEA NO 6.3.6.4		
FUNCTION OF COMPONENT TO PREVENT OVERPRESSURE OF THE HYDRAULIC SYSTEM IN THE EVENT OF A PUMP PRESSURE COMPENSATOR FAILURE						
FAILURE MODES & EFFECTS 1 LEAKS EXTERNALLY - MAY DEplete RESERVOIR AND CAUSE SYSTEM FAILURE				APPLICABLE OPERATING MODES		
2 LEAKS INTERNALLY - SYSTEM PRESSURE WOULD BE LOW, MAY NOT OPERATE YAW OR BRAKE ACTUATORS				F, G, H		
3 FAILS TO OPEN AT PRESET PRESSURE, COULD CAUSE HYDRAULIC COMPONENT OVERPRESSURE IF PUMP COMPENSATOR FAILS				F, G, H		
4				F, G, H		
FAILURE FREQUENCY			FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III
1	70	51.3	3.2			X
2	20	51.3	11.1			X
3	10	51.3	22.2		X	X - D
FAILURE DETECTION METHODS						
1 VISUAL INSPECTION, WTS shutdown						
2 PERIODIC TESTING FOR PRESSURE SETTING - LOW PRESSURE, WTS SHUTDOWN						
3 SIGNAL SHUTS DOWN WTS.						
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)						
D CRITICAL IF PRESSURE LOSS SUFFICIENT TO INITIATE SHUTDOWN.						
				NAME J. W. ACKER		DATE 8/8/78
OPERATING MODES						Rev. 10/25/78
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT SOLENOID VALVES (2)			PAGE 65 FMEA NO 6.3.6.5	
FUNCTION OF COMPONENT TO RELEASE ROTOR BRAKE AND/OR YAW BRAKE; ON COMMAND							
FAILURE MODES & EFFECTS 1 VALVE FAILS TO OPERATE - ROTOR BRAKE, OR YAW BRAKE WILL NOT RELEASE - WTS CANNOT START						APPLICABLE OPERATING MODES F, G, H	
2 VALVE FAILS TO DEACTIVATE - ROTOR BRAKE OR YAW BRAKE WILL NOT APPLY UNTIL PRESSURE IS RELEASED BY FLUID BLEEDING BACK THROUGH						A, B, C, D, E, I	
3 SYSTEM, OR YAW CONTROL VALVE IS SHUTTLED.							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	95	27.4	4.4			X	
2	5	27.4	87.8			X	
FAILURE DETECTION METHODS							
PERIODIC CHECK FOR VALVE OPERATION							
2 BRAKE(S) FAIL TO RELEASE OR APPLY (WHEN SYSTEM IS OTHERWISE OK).							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME J. W. ACKER		DATE 8/8/78	
OPERATING MODES							
A - SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B - TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM		COMPONENT MOTOR CONTROL VALVE		PAGE 66 FMEA NO 6.3.6.6			
FUNCTION OF COMPONENT CONTROLS YAW MOTION BY CONTROLLING FLOW AND DIRECTION OF FLOW OF HYDRAULIC FLUID TO YAW DRIVE MOTOR.							
FAILURE MODES & EFFECTS 1 LEAKS INTERNALLY - COULD CAUSE UNCONTROLLED, ERRATIC YAW MOTION				APPLICABLE OPERATING MODES ALL			
2 FAILS TO OPEN - WTS WILL NOT YAW ON COMMAND				F, G, H			
3 FAILS TO CLOSE - WTS WILL NOT STOP. YAW BRAKE WILL NOT APPLY ON COMMAND				F, G, E, H, I			
4 LEAKS EXTERNALLY - COULD DEplete SYSTEM FLUID, CAUSE OPERATIONAL FAILURE IF UNDETECTED				F, G, H			
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	30	18.3	20.8		X		
2	10	18.3	62.6			X	
3	20	18.3	31.3		X		
FAILURE DETECTION METHODS 4 40 18.3 15.6 X							
1,2 ERRATIC MOTION IN YAW, DOES NOT FOLLOW COMMAND - MICROPROCESSOR SHUTS WTS DOWN.							
4. VISUAL INSPECTION: LOSS OF PRESSURE SENSED; LOSS OF LEVEL SENSED.							
3 WTS WILL SHUT DOWN IF YAW MOTOR MOVES NACELLE TO WRONG POSITION.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) 							
NAME J. W. ACKER				DATE 8/9/78			
OPERATING MODES A SHUTDOWN B TRANSITION TO WARM UP C WARM-UP D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I FEATHER							

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT FITTINGS, TUBES, HOSES - YAW SYSTEM			PAGE 67 FMEA NO 6.3.6.7	
FUNCTION OF COMPONENT SUPPLIES PRESSURIZED HYDRAULIC FLUID TO YAW HYDRAULIC MOTORS							
FAILURE MODES & EFFECTS 1 RUPTURE - LOSS OF SYSTEM PRESSURE & FLUID - SYSTEMS WOULD FAIL TO OPERATE.						APPLICABLE OPERATING MODES F, G, H	
2 LEAKAGE						F, G, H	
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	10	37.6	30.3			X	
2	90	37.6	3.4		▷ X	▷ X	

FAILURE DETECTION METHODS

VISUAL INSPECTION OF SYSTEM

LOW PRESSURE OR RESERVOIR LEVEL INDICATION RESULTING IN SHUTDOWN.

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

▷ DEPENDS ON SEVERITY OF LEAK. LOSS OF PRESSURE INITIATES SHUTDOWN. MINOR LEAKS
- MAY BE DETECTED BY VISUAL INSPECTION.

NAME J. W. ACKER		DATE 8/9/78
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OPERATING MODES

A SHUTDOWN

B - TRANSITION TO WARM UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F - TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT FITTINGS, TUBES, HOSES, YAW BRAKE			PAGE 68 FMEA NO 6.3.6.8	
FUNCTION OF COMPONENT SUPPLIES PRESSURIZED HYDRAULIC FLUID TO YAW BRAKE CALIPERS.							
FAILURE MODES & EFFECTS 1 RUPTURE - LOSS OF SYSTEM PRESSURE & FLUID SYSTEMS WOULD FAIL TO OPERATE						APPLICABLE OPERATING MODES F, G, H	
2 LEAK - LOSS OF SYSTEM PRESSURE & FLUID SYSTEMS WOULD FAIL TO OPERATE.						F, G, H	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	10	3.4	333			X	
2	90	3.4	37		X	X	

FAILURE DETECTION METHODS

VISUAL INSPECTION

LOW PRESSURE OR RESERVOIR LEVEL RESULTING IN SHUTDOWN

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

DEPENDS ON SEVERITY OF LEAK. LOSS OF PRESSURE INITIATES SHUTDOWN. MINOR LEAKS MAY
BE DETECTED BY VISUAL INSPECTION.

NAME J. W. ACKER		DATE 8 /78
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OPERATING MODES

A SHUTDOWN	D TRANSITION TO STANDBY	G - OPERATE
B TRANSITION TO WARM UP	E STANDBY	H - TRANSITION TO FEATHER
C WARM UP	F TRANSITION TO OPERATE	I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT FITTINGS, TUBES, HOSES, ROTOR BRAKE			PAGE 69 FMEA NO 6.3.6.9	
FUNCTION OF COMPONENT SUPPLIES PRESSURIZED HYDRAULIC FLUID TO ROTOR BRAKE CALIPER.							
FAILURE MODES & EFFECTS 1 RUPTURE - LOSS OF SYSTEM PRESSURE & FLUID, SYSTEM FAILS TO OPERATE						APPLICABLE OPERATING MODES F, G, H	
2 LEAKS - LOSS OF SYSTEM PRESSURE & FLUID, SYSTEM FAILS TO OPERATE						F, G, H	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	10	3.4	333			X	
2	90	3.4	37		1 X	X	

FAILURE DETECTION METHODS

VISUAL INSPECTION

LOW PRESSURE & RESERVOIR LEVEL RESULTING IN SHUTDOWN

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

▶ DEPENDS ON SEVERITY OF LEAK. LOSS OF PRESSURE INITIATES SHUTDOWN.

NAME J. W. ACKER		DATE 8/8/78
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OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM		COMPONENT HIGH PRESSURE AND LOW PRESSURE/FILTERS		PAGE 69.1 FMEA NO 6.3.6.10.11		
FUNCTION OF COMPONENT THE FILTERS REMOVE CONTAMINANTS FROM THE YAW DRIVE SYSTEM HYDRAULIC FLUID.						
FAILURE MODES & EFFECTS 1 EXTERNAL LEAKS - COULD DEplete HYDRAULIC SYSTEM FLUID, CAUSING SYSTEM FAILURE.				APPLICABLE OPERATING MODES F, G, H		
2 PLUGGED FILTER - COULD RESULT IN CONTAMINATION AS FILTERS ARE BY-PASSED.				F, G, H		
3						
4						
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %		FAILURE RATE $\times 10^{-6}$ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III
1	100	1	100	X	X	D
2		Not applicable			X	
3						
4						
FAILURE DETECTION METHODS						
1 VISUAL - LOOK FOR EXTERNAL LEAKS						
2 RESERVOIR OIL LEVEL INDICATOR WOULD INDICATE GROSS LEAK.						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)						
D IF NOT DETECTED BY INSPECTION PRIOR TO SYSTEM SHUTDOWN.						
2. FILTERS WILL BE CHANGED AT REGULAR MAINTENANCE INTERVALS.						
				NAME J. W. ACKER		DATE 10/23/8
OPERATING MODES			Rev. 10/25/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H - TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I - FEATHER		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM		COMPONENT CHECK VALVES (4)		PAGE 69.2 FMEA NO 6.3.6.12			
FUNCTION OF COMPONENT CHECK VALVES ARE USED TO PREVENT FLUID FROM FLOWING IN A REVERSE DIRECTION IN FLUID LINES.							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 FAILURE TO CHECK IN ROTOR BRAKE LINE - NO EFFECT UNLESS SOLENOID VALVE LEAKS ALSO. THEN ROTOR BRAKE WOULD CLAMP ON.				F, G, H			
2 FAILURE TO CHECK IN YAW BRAKE LINE - NO EFFECT.				F, G, H			
3 FAILURE TO CHECK IN PUMP OUTLET LINE - FLUID MAY BLEED BACK INTO PUMP ON SYSTEM SHUT-DOWN.				F, G, H			
4 FAILURE TO CHECK IN PUMP CASE DRIVE LINE - PUMP CASE COULD BE PRESSURIZED IF SYSTEM RETURN PRESSURE WAS EXCESSIVE.				F, G, H			
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	100	3	33		X		
2	100	3	33	X			
3	100	3	33	X			
4	100	3	33		X		
FAILURE DETECTION METHODS							
1-4 SYSTEM FUNCTIONAL TEST, OR REMOVE AND TEST COMPONENT.							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
NONE OF THESE FAILURES ARE CATASTROPHIC. MOST WOULD TAKE A DOUBLE FAILURE TO DO ANYTHING. THESE VALVES ARE IN THE SYSTEM AS A "BACK UP" ONLY.							
NAME				J. W. ACKER		DATE 10/23/8	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		H TRANSITION TO FEATHER	
B TRANSITION TO WARM UP		E STANDBY		I FEATHER			
C WARM UP		F TRANSITION TO OPERATE					

MOD-2 Failure Mode and Effects Analysis


SUBSYSTEM YAW DRIVE SYSTEM	COMPONENT NEEDLE VALVE	PAGE 69.3 FMEA NO 6.3.6.13
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FUNCTION OF COMPONENT

THE NEEDLE VALVE IS USED TO ISOLATE THE SYSTEM PRESSURE GAGE SO IT MAY BE SERVICED OR CALIBRATED.

FAILURE MODES & EFFECTS

FAILURE MODES & EFFECTS	APPLICABLE OPERATING MODES
1 EXTERNAL LEAK - COULD DEplete SYSTEM HYDRAULIC FLUID AND RESULT IN WTS SHUTDOWN.	F, G, H
2 FAILURE TO CLOSE OFF COMPLETELY - WOULD PRECLUDE DEAD-WEIGHT TESTING THE GAGE BECAUSE OF INTERNAL LEAK.	A
3	
4	

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	75	4.4	33			X 	
2	25	4.4	100	X			
3							
4							

FAILURE DETECTION METHODS

- EXTERNAL LEAK - VISUAL INSPECTION, OF RESERVOIR LEVEL INDICATOR
- FAILURE TO CLOSE - WOULD BE OBVIOUS TO MAN CHECKING OR SERVICING GAGE.
-
-

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

 If undetected by visual inspection prior to WTS shutdown.

NAME J. W. ACKER

DATE 0/23/8

OPERATING MODES

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A SHUTDOWN
B TRANSITION TO WARM-UP
C WARM UP

D TRANSITION TO STANDBY
E STANDBY
F TRANSITION TO OPERATE

G OPERATE
H TRANSITION TO FEATHER
I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT WEATHER SHIELD			PAGE 70 FMEA NO 6.3.7	
FUNCTION OF COMPONENT SHIELDS YAW DRIVE SYSTEM BEARING, BRAKE CALIPERS, AND DISC FROM THE WEATHER							
FAILURE MODES & EFFECTS 1 FAILURE OF THE WEATHER SHIELD WOULD HAVE ONLY LONG TERM DELETERIOUS EFFECTS ON YAW COMPONENTS						APPLICABLE OPERATING MODES ALL	
2 FAILURE DUE TO EXTREME WINDS, LIGHTNING STRIKE, AND/OR HAIL.							
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1		Negligible		X			
2		Site dependent		X			

FAILURE DETECTION METHODS

1-2 VISUAL INSPECTION AT REGULAR INTERVALS & AFTER SEVERE WEATHER CONDITIONS.

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

NAME J. W. ACKER		DATE 8/8/78
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OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM-UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT MISCELLANEOUS FASTENERS			PAGE 71 FMEA NO 6:3.8	
FUNCTION OF COMPONENT FASTENERS HOLD BEARING AND HYDRAULIC COMPONENTS IN PLACE							
FAILURE MODES & EFFECTS 1 FAILURE OF ANY ONE FASTENER HAS NO EFFECT ON OPERATION OF WTS BECAUSE OF REDUNDANCY.						APPLICABLE OPERATING MODES ALL	
2							
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1		Negligible		X			
FAILURE DETECTION METHODS							
1 VISUAL INSPECTION ON REGULAR SCHEDULE.							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME J. W. ACKER		DATE 8/8/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM YAW DRIVE SYSTEM			COMPONENT BRAKE CALIPERS			PAGE 72 FMEA NO 6 3.9	
FUNCTION OF COMPONENT							
1. CALIPERS ARE SPRING LOADED TO CLAMP ON DISC TO PROHIBIT YAW MOTION.							
2. WHEN HYDRAULIC PRESSURE IS APPLIED, 6 of 7 BRAKES, RELEASE, PERMITTING YAW MOTION (7th BRAKE MAINTAINS DRAG ON DISC FOR DAMPING PURPOSES).							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 MECHANICAL OR SPRING FAILURE - BRAKE WOULD RELEASE, REDUCING YAW HOLDING OR DRAG TORQUE. <input checked="" type="checkbox"/>						-ALL	
2 HYDRAULIC FAILURE - BRAKE WOULD NOT RELEASE, PROHIBITING OR INHIBITING YAW MOTION						E, G, L	
3 BRAKE PAD FAILURE - YAW BRAKE TORQUE MAY NOT BE ADEQUATE FOR HURRICANE WINDS						A, E, I	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)		FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR			MINIMAL I	MARGINAL II	CRITICAL III
1		Negligible	6 units for holding yaw position				<input checked="" type="checkbox"/> X
2			See 6 3.6.8				X
3	100	Negligible	6 Units for holding yaw position			<input checked="" type="checkbox"/>	X
FAILURE DETECTION METHODS							
1 VISUAL INSPECTION - ALL MODES OF FAILURE							
2 ERRATIC MOTION OR EXCESSIVE NOISE/LACK OF YAW MOTION ON COMMAND. WTS SHUTS DOWN							
3 (LOW HYDRAULIC PRESSURE OR LEVEL SIGNAL).							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
<input checked="" type="checkbox"/> REDUCING HOLDING TORQUE MAY ALLOW WTS TO WEATHERVANE. LOSS OF DRAG TORQUE MAY CAUSE YAW MOTION TO BE ERRATIC.							
<input checked="" type="checkbox"/> PROBABILITY OF FAILURE OF SPRING OR OTHER MECHANICAL ITEM ON THE SINGLE DRAG BRAKE IS APPROXIMATELY ONCE EVERY 10 YEARS AND WOULD BE DETECTED AT 2 MONTH INSPECTION PERIOD. PAD WEAR WILL BE CHECKED EVERY 2 MONTHS.							
					NAME J W. ACKER		DATE 8/8/78
OPERATING MODES							Rev. 10/25/78
A SHUTDOWN			D TRANSITION TO STANDBY		G OPERATE		Rev 11/27/78
B TRANSITION TO WARM UP			E STANDBY		H TRANSITION TO FEATHER		3/8/79
C WARM UP			F TRANSITION TO OPERATE		I FEATHER		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM ENVIRONMENTAL CONTROL SYSTEM			COMPONENT COOLING EQUIPMENT			PAGE 73 FMEA NO 6.5.1	
FUNCTION OF COMPONENT FANS EXHAUST HOT AIR FROM NACELLE, DRAW AMBIENT AIR INTO NACELLE TO MAINTAIN LESS THAN 10% NACELLE SUPERHEAT ON WARM DAYS.							
FAILURE MODES & EFFECTS 1 FAN OR MOTOR FAILS - NACELLE OVERHEATS - WTS shuts down if overheat affects components.						APPLICABLE OPERATING MODES F, G, H	
2							
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	100	1.1	100		X	▶	

FAILURE DETECTION METHODS

1 NACELLE TEMPERATURE SENSOR(S) INDICATE OVERTEMPERATURE

NACELLE OPERATING COMPONENTS INDICATE OVERTEMPERATURE

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

▶ IF COMPONENTS OVERHEAT SUFFICIENTLY TO CAUSE WTS SHUTDOWN.

THE USE OF A NACELLE OVERTEMPERATURE SIGNAL DIRECTLY SHUTTING THE
WTS DOWN IS CURRENTLY BEING CONSIDERED

NAME J. W. ACKER		DATE 8/7/78
------------------	--	-------------

OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM ENVIRONMENTAL CONTROL SYSTEM			COMPONENT HEATING EQUIPMENT			PAGE 74 FMEA NO 6.5.2	
FUNCTION OF COMPONENT TBD - THERE IS, AT THIS WRITING, NO KNOWN REQUIREMENT TO HEAT THE NACELLE							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1							
2							
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)		FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR			MINIMAL I	MARGINAL II	CRITICAL III
FAILURE DETECTION METHODS							
1							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
					NAME J. W. ACKER		DATE - 8/8/78
OPERATING MODES							
A SHUTDOWN			D TRANSITION TO STANDBY			G OPERATE	
B TRANSITION TO WARM UP			E STANDBY			H TRANSITION TO FEATHER	
C WARM UP			F TRANSITION TO OPERATE			I FEATHER	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT HIGH VOLTAGE POWER CABLE TO THE GENERATOR ACCESSORY UNIT			PAGE 74.1 FMEA NO 6.6.1.1.	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF HIGH VOLTAGE GENERATOR OUTPUT CURRENT FROM THE GENERATOR TO THE GENERATOR ACCESSORY UNIT.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Open circuit: One or more high voltage power phases go to zero; GCB* and BTC* open, WTS shuts down.						G	
2 Short circuit: Possible phase-to-phase or phase-to-neut fault; GCB and BTC open, WTS shuts down.						G	
3 Grounded conductor: Massive fault on one conductor; GCB and BTC open, WTS shuts down.						G	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.6	142			X	
2	25	1.6	284			X	
3	25	1.6	284			X	
4							
FAILURE DETECTION METHODS							
1- 3. Power output from WTS indicates zero; BTC and GCB position indicate "open".							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1. Differential current protection relay will cause the GCB to open, or as a backup, the differential current protection will cause the BTC to open within milliseconds.							
2. Generator or bus tie unit differential current protection or generator over-current protection circuits will cause the GCB and BTC to open within milliseconds.							
3. Same as #2 plus the ground current relay will cause the GCB to open within milliseconds.							
*GCB - Generator circuit breaker							
*BTC - Bus tie contactor				NAME H. Roth		DATE 9/27/78	
OPERATING MODES						Rev. 10/25/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT HIGH VOLTAGE POWER CABLES		PAGE 75 FMEA NO 6. 6.1			
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF HIGH VOLTAGE GENERATOR OUTPUT CURRENT FROM THE GENERATOR ACCESSORY UNIT TO THE CABLE TRANSITION MECHANISM.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Open circuit: One or more phases go to zero voltage; GCB* and BTC* open, WTS shuts down						G	
2 Short circuit: possible phase-to-phase fault; GCB and BTC open, WTS shuts down						G	
3 Grounded conductor: Massive fault on one conductor, GCB and BTC open, WTS shuts down.						G	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINJMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.6	142			X	
2	25	1.6	284			X	
3	25	1.6	284			X	
FAILURE DETECTION METHODS							
1 - 3. Power output from WTS indicates zero; BTC and GCB position indicate "open."							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1. Differential current protection relay will cause the GCB to open, or as a backup, the differential protection circuit will cause the BTC to open within milliseconds.							
2. Generator or bus tie contractor unit (BTCU) differential current protection or generator over-current protection circuits will cause the GCB and BTC to open within milliseconds.							
3. Same as #2 plus the ground current relay will cause the GCB to open within milliseconds.							
*GCB - Generator circuit breaker							
BTC - Bus tie contractor							
				NAME G. Trusk/ H. ROTH		DATE 8/17/78	
OPERATING MODES				Rev. 9/26/78 Rev. 10/25/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT AC POWER CABLE TO THE CONTROL SYS,	PAGE 77 FMEA NO 6.6.2.2					
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF ACCESSORY POWER FOR OPERATION OF THE CONTROL SYSTEM. CABLE RUNS FROM THE CB PANEL IN THE GENERATOR ACCESSORY UNIT TO THE NACELLE CONTROL UNIT.							
FAILURE MODES & EFFECTS 1 Cable is open circuited. Computer becomes inoperative. WTS shuts down.		APPLICABLE OPERATING MODES A11					
2 Cable is shorted to ground. Computer becomes inoperative. WTS shuts down.		A11					
3							
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	75	.15	>1000			X	
2	25	.15	>3000			X	
FAILURE DETECTION METHODS 1 & 2. Power output from WTS indicates zero. 2 3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) 1 & 2. WTS shut down will be initiated via the failsafe shutdown system. 							
				NAME G. Trusk / H. ROTH		DATE 8/17/78	
OPERATING MODES				Rev. 9/26/78 Rev. 10/25/78			
A SHUTDOWN B TRANSITION TO WARM UP C WARM UP		D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE		G OPERATE H TRANSITION TO FEATHER I - FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT DC (UNINTERRUPTABLE) POWER CABLE TO THE CONTROL SYSTEM		PAGE 78 FMEA NO 6.6.2.3			
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF UNINTERRUPTABLE DC FOR OPERATION OF THE CONTROL SYSTEM. CABLE RUNS FROM THE GENERATOR ACCESSORY UNIT TO THE NACELLE CONTROL UNIT.							
FAILURE MODES & EFFECTS <div style="border-bottom: 1px solid black; padding: 2px;">1 Cable is open circuit: WTS shuts down</div> <div style="border-bottom: 1px solid black; padding: 2px;">2 Cable is short to ground: WTS shuts down</div> <div style="border-bottom: 1px solid black; padding: 2px;">3</div> <div style="border-bottom: 1px solid black; padding: 2px;">4</div>				APPLICABLE OPERATING MODES A11 A11 			
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	75	.15	>1000			X	
2	25	.15	>3000			X	
FAILURE DETECTION METHODS							
1 & 2. Power output from WTS indicates zero.							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1 & 2. WTS shut down will be initiated via the failsafe shutdown system.							
				NAME G. TRUSKY H. ROTH		DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev. 9/26/78 Rev. 10/25/78	
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT POWER CABLE TO THE YAW DRIVE SYS			PAGE 79 FMEA NO 6. 6. 2.4	
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF ACCESSORY POWER FOR OPERATION OF THE YAW DRIVE SYSTEM. CABLE RUNS FROM THE CIRCUIT BREAKER PANEL IN THE GENERATOR ACCESSORY UNIT TO THE YAW DRIVE SYSTEM.							
FAILURE MODES & EFFECTS 1 Cable is open circuited. WTS shuts down						APPLICABLE OPERATING MODES F, G, H	
2 Cable is shorted to ground, protective circuitry clears, WTS shuts down						F, G, H	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	75	.15	>1000			X	
2	25	.15	>3000			X	

FAILURE DETECTION METHODS

1 & 2. Power output from WTS indicates zero.

2

3

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

Yaw drive hydraulic pump motor does not run or develop sufficient power to maintain yaw accumulator pressure. Excessive difference between nacelle position indicator and wind sensors initiates shutdown.

NAME G. TRUSK/ H. ROTH

DATE 8/17/78
Rev. 9/26/78
Rev. 10/25/78

OPERATING MODES		
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE
B - TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER
C WARM UP	F - TRANSITION TO OPERATE	I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT POWER CABLE TO THE PITCH CONTROL SYSTEM	PAGE 80 FIG NO 6.6.2.5					
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF ACCESSORY POWER FOR OPERATION OF THE PITCH CONTROL SYSTEM. CABLE RUNS FROM THE CIRCUIT BREAKER PANEL IN THE GENERATOR ACCESSORY UNIT TO THE LOW SPEED SHAFT SLIP RING ASSEMBLY.							
FAILURE MODES & EFFECTS		APPLICABLE OPERATING MODES					
1 Cable is open circuited (one or more conductors). WTS shuts down		F, G, H					
2 Cable is short circuited to ground (one or more phase conductors). WTS shuts down		F, G, H					
3							
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	75	.15	>1000			X	
2	25	.15	>3000			X	
FAILURE DETECTION METHODS							
1 Power output from WTS indicates zero							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
<u>Pitch drive hydraulic pump motor does not run or developsufficient power to maintain pitch accumulator pressure Loss of pressure causes controls to shut WTS down. Verify power cable continuity, repair as required.</u>							
				NAME G. TRUSK / H. ROTH		DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev. 9/26/78	
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - FPS			COMPONENT POWER CABLE TO GEARBOX OIL HEATERS			PAGE 81 FMEA NO 6.6.2.6	
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF ACCESSORY POWER FOR OPERATION OF THE LUBE OIL HEATERS IN THE GEARBOX. CABLE RUNS FROM THE CIRCUIT BREAKER PANEL IN THE GENERATOR ACCESSORY UNIT TO THE GEAR BOX ASSEMBLY.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Cable open circuited (one or more conductors). If gearbox oil temp is low WTS will not enter "operate" mode						D, E, F, G, H	
2 Cable is short circuited to ground (one or more phase conductors). Protective circuitry clears If gearbox oil temp is low WTS will not enter "operate" mode.						D, E, F, G, H	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	75	.15	>1000			1*	
2	25	.15	>3000			1*	
FAILURE DETECTION METHODS							
1 Power output from WTS indicates zero.							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
If gearbox oil temperature is low, verify continuity of gearbox heaters and power cable. Repair as required.							
* If WTS has been operating, and/or air temp. is high enough to keep oil viscosity low failure will be "minimal."							
				NAME G. TRUSK / H. ROTH		DATE 8/17/78	
OPERATING MODES				Rev. 9/26/78 Rev. 10/25/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT POWER CABLE TO THE LUBRICATION SYSTEM		PAGE 82 FMEA NO 6 6.2.7		
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF ACCESSORY POWER FOR OPERATION OF THE LUBRICATION SYSTEM. CABLE RUNS FROM THE CIRCUIT BREAKER PANEL IN THE GENERATOR ACCESSORY UNIT TO THE LUBE SYSTEM.						
FAILURE MODES & EFFECTS <u>1 Cable is open circuited (one or more conductors). Lube system</u> <u>has redundant wiring and pumps.</u> <u>2 Cable is short circuited to ground (one or more conductors).</u> <u>Protective circuitry clears. Lube system has redundant pump.</u> <u>3</u> <u>4</u>				APPLICABLE OPERATING MODES		
				All		
				All		
FAILURE FREQUENCY			FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III
1	75	.15	>1000			X
2	25	.15	>3000			X
FAILURE DETECTION METHODS <u>1 Failure of one pump results in operation of backup pump. Periodic maintenance</u> <u>2 detects this change.</u> <u>3</u>						
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) <u>If both pumps fail loss of oil pressure results in WTS shutdown.</u> 						
				NAME G. TRUSK/ H. ROTH		DATE 8/17/78
OPERATING MODES A SHUTDOWN B TRANSITION TO WARM UP C WARM UP D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I FEATHER						

R'

Rev. 9/28/78
Rev. 10/25/78
Rev. 11/27/78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT POWER CABLE TO THE ENVIRONMENT CONTROL SYSTEM	PAGE 83 FMEA NO 6.6.2.8					
FUNCTION OF COMPONENT <u>PROVIDES A PATH FOR THE FLOW OF ACCESSORY POWER FOR OPERATION OF THE ENVIRONMENTAL CONTROL SYSTEM.</u> <u>CABLE RUNS FROM THE CIRCUIT BREAKER PANEL IN THE GENERATOR ACCESSORY UNIT TO THE ENVIRONMENTAL CONTROL SYSTEM.</u>							
FAILURE MODES & EFFECTS		APPLICABLE OPERATING MODES					
<u>1 Cable is open circuited (one or more conductors). ECS is inoperative. Nacelle temperatures may exceed allow limit</u>		All					
<u>2 Cable is shorted to ground (one or more conductors). Protective devices clear. Nacelle temperatures may exceed allowable limits.</u>		All					
<u>3 _____</u>							
<u>4 _____</u>							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
<u>1 & 2</u>	<u>100</u>	<u>.15</u>	<u>>760</u>	X		X*	
FAILURE DETECTION METHODS							
<u>1 _____</u>							
<u>2 _____</u>							
<u>3 _____</u>							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) <u>Will be inspected at 2 month intervals.</u> <u>* WTS will shut down if temperature falls or rises to unacceptable limits (control system will become inoperative resulting in shutdown).</u> <u>_____</u> <u>_____</u> <u>_____</u> <u>_____</u> <u>_____</u> <u>_____</u> <u>_____</u> <u>_____</u> <u>_____</u>							
				NAME G. TRUSK/ H. ROTH		DATE 8/17/78	
OPERATING MODES				Rev. 9/26/78 Rev. 10/25/78			
A SHUTDOWN B TRANSITION TO WARM UP C WARM UP				D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE		G OPERATE H TRANSITION TO FEATHER I FEATHER	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT POWER CABLE TO THE ELECTRICAL FACILITIES EQUIPMENT			PAGE 84 FMEA NO 6.6.2.9		
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF ACCESSORY POWER FOR THE OPERATION OF THE ELECTRICAL FACILITIES LOCATED IN OR ON THE NACELLE. CABLE RUNS FROM THE CIRCUIT BREAKER PANEL IN THE GENERATOR ACCESSORY UNIT TO LIGHTS, CONVENIENCE OUTLETS AND AIRCRAFT WARNING LTS							
FAILURE MODES & EFFECTS					APPLICABLE OPERATING MODES		
1 Cable is open circuited (one or more conductors). Affected function is inoperative (lights or portable equipment).					All		
2 Cable is short circuited to ground (one or more conductors). Protective devices clear.							
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1 & 2	100	.15	>760	X			
FAILURE DETECTION METHODS							
1 Function (lights or portable equipment) is inoperative.							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) Replace fuse/reset appropriate circuit breaker, repair as required							
				NAME	G. TRUSK / H. ROTH		
				DATE	8/17/78		
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G - OPERATE		Rev. 9/26/78	
B - TRANSITION TO WARM UP		E STANDBY		H - TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM-UP		F - TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT GENERATOR CONTROL CABLE	PAGE 86 FMEA NO 6.6.3.1.					
FUNCTION OF COMPONENT <u>PROVIDES A PATH FOR THE FLOW OF GENERATOR EXCITATION CURRENT AND GENERATOR WINDING TEMPERATURE SIGNALS BETWEEN THE GENERATOR AND THE GENERATOR ACCESSORY UNIT.</u>							
FAILURE MODES & EFFECTS		APPLICABLE OPERATING MODES					
<u>1 A conductor in cable is open circuited. Temperature data lost and/or generator excitation lost. WTS will shut down.</u>		F, G, H					
<u>2 One or more conductors in cable are short circuited. Same effect as #1. WTS shuts down.</u>		F, G, H					
<u>3 A conductor in cable is shorted to ground same effect as #1. WTS shuts down.</u>		F, G, H					
<u>4 _____</u>							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500			X	
2	25	.15	>3000			X	
3	25	.15	>3000			X	
4							
FAILURE DETECTION METHODS							
<u>1 For temperature - no remote display. For excitation - GCB and BTC tripped, power from WTS indicates zero.</u>							
<u>3 & 2 GCB and BTC tripped, power from WTS indicates zero.</u>							
<u>4 _____</u>							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME G. TRUSK/ H. ROTH		DATE 8/17/78	
OPERATING MODES				Rev. 9/27/78 Rev. 10/25/78			
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE					
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER					
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - FPS			COMPONENT - CONTROL CABLE TO THE GENERATOR ACCESSORY UNIT			PAGE 87 FMEA NO 6.6.3.2	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF COMMANDS AND OPERATIONAL DATA BETWEEN THE NACELLE CONTROL UNIT AND THE GENERATOR ACCESSORY UNIT.							
FAILURE MODES & EFFECTS 1 A conductor in cable is open-circuit. WTS shuts down.						APPLICABLE OPERATING MODES F, G, H	
2 Two or more conductors in cable are shorted together. WTS shuts down.						F, G, H	
3 A conductor with a control function is short-circuited to ground WTS shuts down						F, G, H	
4 A conductor carrying operational data is short-circuited to ground. WTS shuts down						F, G, H	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)		FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR			MINIMAL I	MARGINAL II	CRITICAL III
1	50	.15	> 1500				X
2	25	.15	> 3000				X
3,4	25	.15	> 3000				X
FAILURE DETECTION METHODS 1-4 Power output from WTS indicates zero, BTE is tripped.							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) 1-4. Either the generator field enable signal will not enable the field current relay, inhibiting excitation of the generator or a zero power signal generator output will prevent closing the BTC or cause it to trip.							
					NAME	G. TRUSK / H. ROTH	
					DATE		8/17/78
OPERATING MODES							
A SHUTDOWN B TRANSITION TO WARM UP C WARM UP		D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE		G OPERATE H TRANSITION TO FEATHER I FEATHER			

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Rev. 10/25/78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT CONTROL CABLE TO THE ROTOR		PAGE 88 FMEA NO 6.6.3.3			
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF CONTROL SIGNALS AND OPERATIONAL DATA BETWEEN THE NACELLE CONTROL UNIT AND THE LOW SPEED SHAFT-SLIP RING ASSEMBLY.							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 A conductor in the cable is open-circuited. Loss of associated command function or data. *				F, G, H			
2 Two or more conductors are shorted together. Loss of associated command function or erroneous data. *				F, G, H			
3 A conductor in the cable is short-circuited to ground. Loss of associated command function or erroneous data: *				F, G, H			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500			X	
2	25	.15	>2000			X	
3	25	.15	>3000			X	
FAILURE DETECTION METHODS							
1 - 3 None until WTS shuts down or fails to deliver power.							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
See FMEA sheets 7.7.13 through 7.7.26							
Failsafe system initiates shutdown if necessary.							
* WTS may be shutdown or control function may be locked out or improper commands are issued which ultimately would lead to WTS shutdown.							
NAME G. TRUSK /H. Roth DATE 8/17/78							
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev. 9/28/78	
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT CONTROL CABLE			PAGE 89 FMEA NO 6.6.3.4	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF CONTROL SYSTEM OPERATIONAL DATA BETWEEN THE NACELLE CONTROL UNIT AND THE NACELLE MOUNTED WIND SENSOR.							
FAILURE MODES & EFFECTS 1 A conductor in cable is open-circuited. Wind data is lost from one sensor. WTS shuts down						APPLICABLE OPERATING MODES E, F, G, H, I	
2 A conductor in cable is short circuited to another conductor. Wind data is lost from one sensor. WTS shuts down.						E, F, G, H, I	
3 A conductor in cable is shorted to ground. Wind data is lost from one sensor. WTS shuts down.						E, F, G, H, I	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500			X	
2	25	.15	>3000			X	
3	25	.25	>3000			X	
FAILURE DETECTION METHODS							
1 NCU detects wind sensor difference between two sensors.							
2							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
Data from one wind sensor does not agree with data from the other wind sensor which causes the WTS to be shut down in the lockout mode.							
						NAME G. TRUSK / H. ROTH	
						DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT CONTROL CABLE TO THE TOWER		PAGE 90 FMEA NO 6.6.3.5			
FUNCTION OF COMPONENT <u>PROVIDES A PATH FOR THE FLOW OF CONTROL SYSTEM COMMANDS AND OPERATIONAL DATA</u> <u>BETWEEN THE NACELLE CONTROL UNIT AND THE TOWER SLIP RING</u>							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 Wire in cable is open circuited. WTS may shut down, fail to connect WTS to utility, or not shut down when required.				ALL			
2 Wire in cable is short circuited to ground. Same effect as No. 1				ALL			
3 Wires in cable are shorted together. Same effect as No. 1				ALL			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	1400		X*	X*	
2	25	.15	2800		X*	X*	
3	25	.15	2800		X*	X*	
4							
FAILURE DETECTION METHODS							
1-3 Loss of manual control; WTS shutdown if critical systems involved.							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
* Manual command "auto/shutdown" or status signals originating at the base may not be received by control equipment in the nacelle. Commands originating in the nacelle may not be received at the base (i.e., "synchronizer enable" or "utility bus tie disconnect"). If failure occurs while WTS is in the operate mode and "utility bus tie disconnect" command cannot be sent via the control system, the EPS "directional power" relay will trip the BTC when power reverses due to low or no wind; generator in the nacelle is protected from damage by protection devices located in, and controlled by, circuits within the nacelle.							
NAME G. TRUSK/H. ROTH				DATE 8/17/78			
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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Rev. 10/25/78
Rev. 11/27/78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT CONTROL CABLE TO THE GEAR BOX			PAGE 91 FMEA NO 6.6.3.6	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF STATUS AND PERFORMANCE INFORMATION FROM THE GEARBOX TO THE NACELLE CONTROL UNIT							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Wire in cable is open circuited: WTS may shut down.						F, G, H	
2 Wire in cable is shorted to ground: WTS may shut down.						F, G, H	
3 Wires in cable are short circuited: WTS may shut down.						F, G, H	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	1400			X	
2	25	.15	2800			X	
3	25	.15	2800			X	
4							
FAILURE DETECTION METHODS *							
1-3 If WTS shuts down, power output indicated is zero.							
2 1-3							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1&2 WTS shuts down due to interpretation that data indicates rotor at zero speed, excessive vibration or excessive low speed bearing temperature.							
2 WTS shuts down due to interpretation that data indicates rotor speed is excessive. If fault is on vibration or bearing temperature circuits, redundant signals are provided to maintain data integrity.							
* See FMEA 7.7.7 through 7.7.12							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES				Rev 10/12/78 Rev 10/25/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT CONTROL CABLE TO THE LUBRICATION SYSTEM			PAGE 92 FMEA NO 6.6.3.7	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF COMMANDS AND OPERATIONAL DATA BETWEEN THE NACELLE CONTROL UNIT AND THE LUBRICATION SYSTEM.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Wire in cable is open circuited: WTS may shut down. Oil pump may not be turned on or off, but redundant path provided.						F, G, H	
2 Wire in cable is short circuited to ground: same effect as No. 1, additionally, data cannot be monitored.						F, G, H	
3 Wires in cable are short circuited: WTS may shut down						F, G, H	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY *			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	1400		X*	X*	
2	25	.15	2800		X*	X*	
3	25	.15	2800		X*	X*	
4							
FAILURE DETECTION METHODS *							
1							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
Pump on/off commands may not be obeyed if command wires are faulted.							
If status wires are faulted, WTS may shut down because data erroneously is interpreted to mean one of the following: excessive particles in lub oil, oil overtemperature, oil filter restricted or oil level is low. Oil pump may be erroneously commanded on or off.							
* Depends upon which wire(s) faulty for details. See FMEA 7.7.2.8.- 7.7.3.5.							
NAME G. TRUSK/H. ROTH						DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT - CONTROL CABLE TO THE YAW DRIVE SYSTEM			PAGE 92.1 FMEA NO 6.6.3.8	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF COMMANDS AND OPERATIONAL DATA BETWEEN THE NACELLE CONTROL UNIT AND THE YAW DRIVE SYSTEM CONTROLS.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Wire in cable is open circuited: WTS shuts down or hydraulic pump cannot be turned on or off.						F, G, H	
2 Wire in cable is short circuited to ground: same effect as #1 plus nacelle may yaw left or right.						F, G, H	
3 Wires in cable are short circuited: no data monitored on shorted wires or hydraulic motor cannot be turned on or off or nacelle may yaw right or left.						F, G, H	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.1	200			X	
2	25	1.1	400			X	
3	25	1.1	400			X	
4							
FAILURE DETECTION METHODS							
1-3 WTS shuts down. Manned substation receives alarm. On site data review will identify problem circuit, inspection is required to pinpoint specific problem.							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
See FMEAs 7.7.50 through 7.7.62.							
						NAME H. ROTH	
						DATE 10/12/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT SLIP RING BRUSH ASSEMBLY TRAIN)	PAGE FMEA NO	93 6.6.4
FUNCTION OF COMPONENT PROVIDES THE STATIONARY PORTION OF THE PATH FOR THE FLOW OF ELECTRICAL POWER AND SIGNALS BETWEEN THE NACELLE AND THE DRIVE TRAIN. ALSO PROVIDES A PROTECTED ELECTRICAL JUNCTION FOR INCOMING NACELLE CABLES			
FAILURE MODES & EFFECTS			APPLICABLE OPERATING MODES
1A brush fails to make contact with slip ring: loss of data or command function			ALL
2High impedance contact between brush and slip ring: same effect as No. 1.			ALL
3Conductive path between brushes			ALL
4Conductive path between brush and structure or case			ALL
FAILURE FREQUENCY			FAILURE SEVERITY
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)
1	98	37.6	3.0 ▶▶
2	1	37.6	303 ▶▶
3	1	37.6	303 ▶▶
4			
FAILURE DETECTION METHODS			
1 -4 Inspection and continuity tests			
2			
3			
4			
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)			
See FMEA sheets 7.7.13 through 7.7.26 and 6.6.3.3			
▶ Total for all signals			
		NAME G. TRUSK/H. ROTH	DATE8/17/78
OPERATING MODES			
A SHUTDOWN	B TRANSITION TO WARM UP	C WARM UP	D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE
G OPERATE	H TRANSITION TO FEATHER	I FEATHER	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT GENERATOR CIRCUIT BREAKER (GCB)	PAGE 94 FMEA NO 6.8.1																																															
FUNCTION OF COMPONENT PROVIDES A MEANS TO OPEN THE HIGH VOLTAGE POWER OUTPUT LINES FROM THE GENERATOR.																																																	
FAILURE MODES & EFFECTS 1 Breaker contacts cannot be closed, WTS cannot enter operate mode.		APPLICABLE OPERATING MODES E, F																																															
2 Breaker contacts cannot be opened, generator may carry excessive fault currents. 2		F, G, H																																															
3 Breaker contacts have high resistance. Excessive voltage drop causes heating of breaker		F, G, H																																															
4																																																	
<table border="1"><thead><tr><th colspan="3">FAILURE FREQUENCY</th><th rowspan="2">MEAN TIME BETWEEN FAILURE (YEARS)</th><th colspan="4">FAILURE SEVERITY</th></tr><tr><th>FAILURE MODE NO</th><th>FAILURE MODE FREQ %</th><th>FAILURE RATE x 10⁻⁶ PER HOUR</th><th>MINIMAL I</th><th>MARGINAL II</th><th>CRITICAL III</th><th>CATASTROPHIC IV</th></tr></thead><tbody><tr><td>1</td><td>25</td><td>2.3</td><td>200</td><td></td><td></td><td>X</td><td></td></tr><tr><td>2</td><td>25</td><td>2.3</td><td>200</td><td></td><td></td><td>X</td><td></td></tr><tr><td>3</td><td>50</td><td>2.3</td><td>100</td><td>X</td><td></td><td></td><td></td></tr><tr><td>4</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></tr></tbody></table>			FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY				FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV	1	25	2.3	200			X		2	25	2.3	200			X		3	50	2.3	100	X				4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY																																													
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV																																										
1	25	2.3	200			X																																											
2	25	2.3	200			X																																											
3	50	2.3	100	X																																													
4																																																	
FAILURE DETECTION METHODS 1 Generator circuit breaker position indicator indicates open 2 Generator circuit breaker position indicator indicates closed, zero power output. 3 None-on-site; inspection may reveal higher temps or lower voltage than normal. 4																																																	
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 1-3 Generator circuit breakers are in commercial use and should be very dependable. 2 Bus tie contactor unit has fuses that backup the GCB and protect the generator.																																																	
		NAME G. TRUSK/H. ROTH																																															
OPERATING MODES A SHUTDOWN B TRANSITION TO WARM-UP C WARM UP		D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I FEATHER																																															
		Rev 10/12/78 Rev 10/25/78																																															

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT VOLTAGE REGULATOR		PAGE 95 FMEA NO 6.8.2.1		
FUNCTION OF COMPONENT PROVIDES AND CONTROLS DC POWER TO THE GENERATOR EXCITER						
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES		
1 Output voltage is zero: GCB & BTC trip. WTS shuts down.				F, G, H		
2 Output voltage too low: GCB & BTC trip. WTS shuts down				F, G, H		
3 Output voltage too high: GCB & BTC trip. WTS shuts down.				F, G, H		
4						
FAILURE FREQUENCY			FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III
1	50	11.4	20			X
2	25	11.4	40			X
3	25	11.4	40			X
FAILURE DETECTION METHODS						
1, 2, 3 Power output from WTS indicates zero.						
2						
3						
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)						
1. Prior to BTC closure: BTC will not close since power output from generator is zero. After BTC closure: Loss of excitation protection trips GCB.						
2. Prior to BTC closure: Output voltage is high, synchronizer inhibits BTC closure. After BTC closure: Power factor becomes more leading, either power factor or overcurrent protection trips the GCB.						
				NAME G. TRUSK / H. Roth		DATE 8/17/78
OPERATING MODES						
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		
				REV. 10/9/78		
				REV. 10/25/78		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELL EPS			COMPONENT POWER FACTOR CONTROLLER (PFC)			PAGE 96 FMEA NO 6.8.2.2	
FUNCTION OF COMPONENT PROVIDES A FEEDBACK CONTROL SIGNAL TO THE VOLTAGE REGULATOR TO MAINTAIN A CONSTANT OUTPUT POWER FACTOR FROM THE GENERATOR.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 THE PFC DOES NOT PROVIDE CONTROL SIGNALS TO THE VOLTAGE REGULATOR (VR): POWER FACTOR IS NOT CONTROLLED, SEE <input type="checkbox"/>						G	
2 THE PFC PROVIDES TOO HIGH A SIGNAL TO THE VR: PF IS LESS THAN DESIRED, SEE <input type="checkbox"/>						G	
3 THE PFC PROVIDES TOO SMALL A SIGNAL TO THE VR: PF IS GREATER THAN DESIRED, SEE <input type="checkbox"/>						G	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE - FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2,3,	100	22.8	5		X	<input type="checkbox"/>	
FAILURE DETECTION METHODS							
1 -3 NO DETECTION OF FAILURE UNTIL CERTAIN ELECTRICAL PARAMETERS SUCH AS							
<input checked="" type="checkbox"/> DIFFERENTIAL CURRENT OR OVER-CURRENT ARE EXCEEDED.							
<input checked="" type="checkbox"/>							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1-3 UNDER NORMAL WIND CONDITIONS NO PROBLEMS ARE ENCOUNTERED, THE VR PROVIDES SUFFICIENT CONTROL; HOWEVER, IF HIGH WIND GUSTS ARE PRESENT THE GENERATOR MAY SLIP A POLE AND EITHER DIFFERENTIAL CURRENT OR OVER-CURRENT PROTECTION CIRCUITS WILL INITIATE WTS SHUT DOWN. IF A POLE IS NOT SLIPPED THERE WILL BE KNOWLEDGE THAT PF IS EXCESSIVE.							
2&3 IF PF IS OUT-OF-TOLERANCE, IT IS NOT DETECTED AND MAXIMUM REAL POWER IS NOT AVAILABLE FROM THE WTS.							
<input type="checkbox"/> UNDER GUSTY WIND CONDITIONS THE GENERATOR PULL-OUT TORQUE MAY BE EXCEEDED CAUSING THE GENERATOR TO SLIP A POLE WITH ATTENDANT VERY HIGH UNBALANCED PHASE CURRENTS, WTS MAY SHUT DOWN. <input type="checkbox"/> WTS SHUTS DOWN IF CURRENTS EXCEED CERTAIN LIMITS.							
						NAME	G. TRUSK/H. ROTH
						DATE	8/17/78
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev. 9/8/78	
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD 2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT OVER VOLTAGE RELAY			PAGE 98 FMEA NO 6.8.3.1	
FUNCTION OF COMPONENT MONITORS THE GENERATOR OUTPUT VOLTAGE AND PROVIDES A SIGNAL TO THE CONTROL SYSTEM INITIATING SHUTDOWN WHEN THE GENERATOR VOLTAGE EXCEEDS A PRESET LIMIT.							
FAILURE MODES & EFFECTS 1 Over voltage relay fails open. No effect.						APPLICABLE OPERATING MODES F, G, H	
2 Over voltage relay fails closed. WTS shutdown.						F, G, H	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42	X			
2	20	3.4	168			X	

FAILURE DETECTION METHODS 1 None	
2 GCB and BTC position indicates open	
3	

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

Voltage while on line controlled by utility buss. If over excitation occurs while on line, over temp sensors will initiate shutdown.

DELETED - FUNCTION PERFORMED WITHIN SYNCHRONIZER

NAME H. ROTH/G. TRUSK	DATE 8/17/78
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OPERATING MODES			Rev. 9/25/78 Rev. 10/25/78
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE	
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER	
C WARM UP	F TRANSITION TO OPERATE	I FEATHER	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM			COMPONENT			PAGE 99	
NACELLE - EPS			UNDER FREQUENCY RELAY			FMEA NO 6.8.3.2	
FUNCTION OF COMPONENT							
INITIATES THE GENERATOR OUTPUT VOLTAGE AND PROVIDES A SIGNAL TO TRIP THE GENERATOR CIRCUIT BREAKER WHEN THE GENERATOR POWER OUTPUT FREQUENCY FALLS BELOW A PRESET LIMIT.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Under frequency relay fails open. No effect.						F, G, H	
2 Under frequency relay fails closed. GCB trips and WTS shuts down.						F, G, H	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42	X			
2	20	3.4	168			X	
FAILURE DETECTION METHODS							
1 None							
2 GCB and BTC position indicates open.							
3							
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)							
1. Under frequency caused by low rpm; if off-line rpm sensor results in redundant system. If on-line, utility buss controls frequency, any fluctuations would be due to loss of utility power, initiating shutdown.							
OPERATING MODES				NAME H. ROTHG. TRUSK		DATE 8/17/78	
A SHUTDOWN				D TRANSITION TO STANDBY		G OPERATE	
B TRANSITION TO WARM UP				E STANDBY		H TRANSITION TO FEATHER	
C WARM UP				F TRANSITION TO OPERATE		I FEATHER	

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT OVERCURRENT RELAY	PAGE 100 FMEA NO 6.8.3.3				
FUNCTION OF COMPONENT MONITORS THE GENERATOR OUTPUT CURRENT AND PROVIDES A SIGNAL TO TRIP THE GENERATOR CIRCUIT BREAKER WHEN THE GENERATOR OUTPUT CURRENT EXCEEDS A PRESET LIMIT.						
FAILURE MODES & EFFECTS 1 Overcurrent relay fails open. No effect		APPLICABLE OPERATING MODES G				
2 Overcurrent relay fails closed. GCB trips and WTS shuts down.		G				
3						
4						
FAILURE FREQUENCY		FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ % COMPONENT FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42	X		
2	20	3.4	168		X	
FAILURE DETECTION METHODS						
1 None						
2 GCB and BTC position indicates open						
3						
DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE) 1. No overcurrent protection available to the generator; however, if overcurrent results from a fault condition, ground current sensing or differential current sensing will cause the GCB to open. 						
			NAME H. ROTH/ G. TRUSK	DATE 8/17/78		
OPERATING MODES						
A SHUTDOWN	B TRANSITION TO WARM UP	C WARM UP	D TRANSITION TO STANDBY	E STANDBY	F TRANSITION TO OPERATE	G OPERATE H TRANSITION TO FEATHER I FEATHER
						rev. 9/25/78 rev. 10/25/78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE-EPS			COMPONENT REVERSE POWER RELAY			PAGE 101 FMEA NO 6.8.3.4	
FUNCTION OF COMPONENT MONITORS THE GENERATOR OUTPUT POWER AND PROVIDES A SIGNAL TO TRIP THE GENERATOR CIRCUIT BREAKER WHEN THE GENERATOR OUTPUT POWER FALLS TO A LEVEL WHERE THE POWER FLOW MAY REVERSE.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 RELAY FAILS OPEN: GENERATOR MAY ACT AS A MOTOR IF A REAL REVERSAL OF POWER OCCURS.						G	
2 RELAY FAILS CLOSED: GCB TRIPS AND WTS SHUTS DOWN						G	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42	X			
2	20	3.4	168			X	
3							
4							

FAILURE DETECTION METHODS

1 GENERATOR POWER INDICATION INDICATES NEGATIVE POWER IS GENERATED.

2 GENERATOR POWER INDICATION INDICATES ZERO POWER IS GENERATED; GCB AND BTC POSITION

3 INDICATES "OPEN"

4

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

NAME G. TRUSK/H. ROTH		DATE 8/17/78
OPERATING MODES		Rev. 9/8/78 Rev. 10/25/78
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER
C WARM UP	F TRANSITION TO OPERATE	I FEATHER

MOD 2 Failure-Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT GROUND CURRENT RELAY			PAGE 102 FMEA NO 6.8.3.5	
FUNCTION OF COMPONENT <u>MONITORS THE GENERATOR OUTPUT CURRENT FLOW IN THE NEUTRAL LINE TO GROUND AND PROVIDES A SIGNAL TO TRIP THE GENERATOR CIRCUIT BREAKER WHEN THE CURRENT FLOW RISES TO A PRESENT LEVEL TO INDICATE AN ELECTRICAL FAULT.</u>							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 GCR fails open. No effect						G	
2 GCR fails closed. WTS shuts down.						G	
3							
4							

FAILURE FREQUENCY				FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42	X			
2	20	3.4	168			X	

FAILURE DETECTION METHODS

1 None - Requires periodic check

2 GCB and BTC position indicates open

3

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

2. OPR or OQR will probably initiate shutdown, over temp. sensors would initiate shutdown if fault continued.

NAME G. TRUSK / H ROTH DATE 8/17/78

OPERATING MODES

A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER
C WARM UP	F TRANSITION TO OPERATE	I FEATHER

 Rev. 9/25/78
 Rev. 10/25/78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT DIFFERENTIAL PROTECTION RELAY			PAGE 103 FMEA NO 6.8.3.6	
FUNCTION OF COMPONENT MONITORS THE DIFFERENTIAL CURRENT FLOW IN THE VARIOUS BRANCHES OF THE GENERATOR STATOR WINDING AND PROVIDES A SIGNAL TO TRIP THE GENERATOR CIRCUIT BREAKER WHEN THE DIFFERENTIAL CURRENT EXCEEDS A PRESET LIMIT TO INDICATE A FAULT WITHIN THE DIFFERENTIAL PROTECTION ZONE.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 DPR fails open, no effect						G	
2 DPR fails closed, WTS shuts down						G	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42	X			
2	20	3.4	168			X	

FAILURE DETECTION METHODS

1 None - Requires periodic checks

2 Generator power indication indicates zero power; GCB and BTC position indicates "open".

3

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

NAME H. ROTH/ G. TRUSK DATE 8/17/78
Rev. 9/25/78
Rev. 10/25/78

OPERATING MODES

A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER
C WARM UP	F TRANSITION TO OPERATE	I FEATHER

MOD 2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT GENERATOR WINDING OVER TEMPERATURE RELAY (OTR)	PAGE 103.1 FMEA NO 6.8.3.7
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FUNCTION OF COMPONENT

THE TEMPERATURE SIGNAL OF EACH GENERATOR FIELD WINDING AND PROVIDES A SIGNAL TO THE CONTROL SYSTEM INITIATING A SHUTDOWN WHEN ANY WINDING EXCEEDS A PRESET LIMIT.

FAILURE MODES & EFFECTS

1. Relay fails open: Generator may operate with overheated windings resulting in eventual destruction of interwinding insulation and massive

APPLICABLE OPERATING MODES

G

2. internal fault currents

2. Relay fails closed: WTS shuts down

G

3

4

FAILURE FREQUENCY

FAILURE SEVERITY

FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE $\times 10^6$ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42				1*
2	20	3.4	168			X	

DETECTION METHODS

1 & 2. GCB & BTBS open, power output from WTS indicates zero.

2

3

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

1. Excessive winding temperatures are caused by either internal or external faults that should be sensed by over-current, differential current or ground current protective circuits that trip the GCB and cause WTS shut-down. Once the generator is shut-down via the OTR the control system will prevent re-enabling the generator excitation until the winding temperature is within acceptable limits.

1* only if backup protection devices fail (i.e., Over-current, differential current, or ground fault) (Less than .1% chance per 30 years).

NAME H. ROTH

DATE 9/27/78

OPERATING MODES

A SHUTDOWN
B - TRANSITION TO WARM UP
C WARM UP

D - TRANSITION TO STANDBY
E STANDBY
F - TRANSITION TO OPERATE

G OPERATE
H - TRANSITION TO FEATHER
I - FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT GENERATOR BEARING OVERTEMPERATURE RELAY			PAGE 103.2 FMEA NO 6.8.3.8	
FUNCTION OF COMPONENT Provides a signal to the control system to shutdown the WTS if a bearing over-temperature signal is received from the temperature sensors.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Relay fails open: Generator may operate with overheated bearings resulting in eventual destruction of the bearing. 1*						G	
2 Relay fails closed: WTS shuts down.						G	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42				1*
2	20	3.4	168			X	
3							
4							
FAILURE DETECTION METHODS							
1 None remotely, until WTS shutdown.							
2 BTC open, power output from WTS indicates zero.							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
The most probable cause for an overheated bearing is loss of lubricant. Control system has redundant inputs to effect normal shutdown or failsafe shutdown in the event of generator bearing overheat.							
1* Bearing may seize and cause significant damage to the structure. This would require two relays to fail, due to redundant system. Probability of joint failure is less than .1% in 30 years.							
				NAME H. ROTH		DATE 9/27/78	
OPERATING MODES				Rev 10/25/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT LOSS OF EXCITATION RELAY			PAGE 103.3 FMEA NO 6.8.3.9	
FUNCTION OF COMPONENT Provides a means to trip the generator circuit breaker when excitation power to the generator field is lost.							
FAILURE MODES & EFFECTS 1 Open circuit: Relay does not operate						APPLICABLE OPERATING MODES F.G.	
2 Relay does not issue GCB trip signal						F.G.	
3 Relay issues GCB trip signal prematurely						F.G.	
4							
FAILURE FREQUENCY				FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42			X	
2	10	3.4	333			X	
3	10	3.4	333			X	
4							
FAILURE DETECTION METHODS							
1- 3 WTS Shut Down							
X							
X							
X							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1 & 2 Damage may occur to the generator if excitation is lost and GCB is not tripped in a timely manner. Other protection devices will trip the BTC to remove the generator from the system.							
					NAME H. ROTH		DATE 10-18-78
OPERATING MODES							
A SHUTDOWN			D TRANSITION TO STANDBY		G - OPERATE		
B TRANSITION TO WARM UP			E STANDBY		H TRANSITION TO FEATHER		
C WARM UP			F TRANSITION TO OPERATE		I FEATHER		

Rev. 10/25/78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT POWER FACTOR RELAY		PAGE 103.4 FMEA NO 6.8.3.10			
FUNCTION OF COMPONENT Provides a means to signal the control system to shut down if the power factor exceeds preset limits.							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 Relay does not operate: Power factor may exceed tolerable level causing generator heating.				G			
2 Relay operates prematurely: Frequent unnecessary shut downs.				G			
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42			X	
2	20	3.4	167			X	
3							
4							
FAILURE DETECTION METHODS							
1 WTS Shut Down When Generator Overtemperature Limits Are Exceeded.							
2 WTS Shut Down							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME H. Roth		DATE 10-18-78	
OPERATING MODES						Rev 10-25-78	
A SHUTDOWN		D TRANSITION TO STANDBY		G - OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C - WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT GENERATOR BEARING UNDERTEMPERATURE RELAY			PAGE 103.5 FMEA NO 6.8.3.11	
FUNCTION OF COMPONENT PROVIDES A SIGNAL TO THE CONTROL SYSTEM FOR INHIBITING START-UP OF THE WTS WHEN THE GENERATOR BEARING TEMPERATURE IS TOO LOW.							
FAILURE MODES & EFFECTS 1 Relay contacts stuck open: WTS rotor will not rotate or WTS will shut down. 2 Relay contacts remain closed: Generator may be rotated without lubrication. (Double failure) 3 4						APPLICABLE OPERATING MODES F, G, H G 	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	80	3.4	42			X	
2	20	3.4	167	X			
3							
4							
FAILURE DETECTION METHODS 1 WTS will not start. 2 If damage is severe, eventual bearing over-temperature shutdown during "operate" mode. 3 4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 2. Normally not detectable since relay contacts should be closed under conditions where maintenance personnel are at station. If relay is suspect, conduct operability test replace if required. This relay is a backup for the generator heater. If the heater fails, the relay protects the generator. 							
				NAME	H. Roth		DATE 10-19-78
OPERATING MODES A SHUTDOWN B TRANSITION TO WARM UP C WARM UP D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I - FEATHER							

Rev 10-25-78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT POTENTIAL TRANSFORMER (PT)			PAGE 104 FMEAN 6.8.4.1	
FUNCTION OF COMPONENT PROVIDES A 0-115 VOLT SIGNAL PROPORTIONAL TO THE 0-4160 VOLT OUTPUT OF THE GENERATOR. THIS SIGNAL IS USED BY THE GENERATOR PROTECTIVE RELAYS AND THE GENERATOR INSTRUMENTATION TRANSducers.							
FAILURE MODES & EFFECTS 1 Transformer is open-circuited, no effect						APPLICABLE OPERATING MODES G	
2 Transformer has short-circuited windings						G	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	25	1.1	400			X	
2	75	1.1	133			X	

FAILURE DETECTION METHODS							
1 WTS shutdown							
2 WTS shutdown 1*							
3							

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

Potential transformers are utilized for many functions: 1) Controls, 2) Voltage regulation, 3) Indication devices, 4) Over-voltage protection, 5) Watt-hour meters, 6) Watt-meter, and 7) Synchronizer circuits.

1* If PT is in a control circuit the WTS will shut down due to over-excitation

OPERATING MODES			NAME G. TRUSK / H ROTH	DATE 8/17/78
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE	Rev. 9/25/78 Rev. 10/25/78	
B TRANSITION TO WARM-UP	E STANDBY	H TRANSITION TO FEATHER		
C WARM UP	F TRANSITION TO OPERATE	I FEATHER		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT CURRENT TRANSFORMER (CT)			PAGE 105 FMEA NO 6.8.4.2	
FUNCTION OF COMPONENT PROVIDES A 0-5 AMP ANALOG SIGNAL PROPORTIONAL TO THE 0-433 AMP GENERATOR OUTPUT LINE CURRENT. THIS SIGNAL IS USED BY THE GENERATOR PROTECTIVE RELAYS AND THE GENERATOR INSTRUMENTATION TRANSDUCERS.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Open circuit in the current transformer secondary winding. no output from CT						G	
2 Short circuit between individual turns of the current transformer: lower output from CT						G	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	25	1.1	400			X	
2	75	1.1	133			X	

FAILURE DETECTION METHODS

1 WTS shutdown

2 WTS shutdown

3

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

Current transformers are utilized for many functions: 1) Controls; 2) Voltage regulation, 3) Indication devices, 4) Over-current protection, 5) Watt-hour meters, 6) Watt-meter, 7) Ground fault protection, and 8) Differential protection circuits.

NAME G TRUSK/ H. ROTH		DATE 8/18/78
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OPERATING MODES			Rev. 9/25/78 Rev. 10/25/78
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE	
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER	
C WARM UP	F TRANSITION TO OPERATE	I FEATHER	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT VOLTAGE TRANSDUCER			PAGE 106 FMEA NO 6.8.5.1	
FUNCTION OF COMPONENT PROVIDES A 0-1 MA OUTPUT ANALOG SIGNAL FROM THE 0-115 VOLT OUTPUT OF A POTENTIAL TRANSFORMER THIS SIGNAL IS PROVIDED TO THE CONTROL SUBSYSTEM AND TO A VOLTMETER DISPLAY.							
FAILURE MODES & EFFECTS 1 Open circuit in the voltage transducer. No output from transducer.						APPLICABLE OPERATING MODES G	
2 Short circuit between individual turns of the voltage transducer. No or incorrect output from transducer.						G	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	COMPONENT FAILURE RATE x 10 ⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	25	1.1	400	X			
2	75	1.1	133	X			

FAILURE DETECTION METHODS

1 & 2. None. Voltage signal is for data purposes only.

2

3

DISCUSSION AND CORRECTIVE ACTION (IF APPLICABLE)

1 & 2. Independant over voltage protection in provided.

NAME G. TRUSK/ H. ROTH		DATE 8/17/78
OPERATING MODES		Rev. 9/25/78 Rev. 10/25/78
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE
B TRANSITION TO WARM-UP	E STANDBY	H TRANSITION TO FEATHER
C WARM UP	F TRANSITION TO OPERATE	I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT CURRENT TRANSDUCER		PAGE 107 FMEA NO 6.8.5.2			
FUNCTION OF COMPONENT PROVIDES A 0-1 MA OUTPUT ANALOG SIGNAL FROM THE 0-5 AMP OUTPUT OF A CURRENT TRANSFORMER. THIS SIGNAL IS PROVIDED TO AN AMMETER DISPLAY.							
FAILURE MODES & EFFECTS 1 Open circuit: control system or ammeter sense zero current.				APPLICABLE OPERATING MODES G			
2 Short circuited: same as #1.				G			
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	75	1.1	133	X			
2	25	1.1	400	X			
3							
4							
FAILURE DETECTION METHODS							
1-2 Zero current displayed at WTS site. No remote detection available.							
7							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) Approximate current can be derived from displayed or stored real power data. 							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES A SHUTDOWN B TRANSITION TO WARM UP C WARM UP D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I FEATHER							
REV 10/13/78							

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT REAL POWER TRANSDUCER	PAGE 108 FMEA NO 6.8.5.3					
FUNCTION OF COMPONENT PROVIDES A 0-1 MA OUTPUT ANALOG SIGNAL OF GENERATOR KW OUTPUT BASED ON INPUTS FROM POTENTIAL AND CURRENT TRANSFORMERS. THIS SIGNAL IS PROVIDED TO THE CONTROL SYSTEM AND TO A KW METER DISPLAY.							
FAILURE MODES & EFFECTS		APPLICABLE OPERATING MODES					
1 Output high: WTS shuts down.		G					
2 Output low: WTS shuts down.		G					
3							
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	100	1.1	100			X	
2	100	1.1	100			X	
3							
4							
FAILURE DETECTION METHODS							
1&2 WTS shuts down, zero power output, BTC indicates open.							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1. Real power signal is high. System operates at reduced power levels. Detected by comparison with other units in farm.							
2. Real power is low. Control system uses real power data to set the rotor blade pitch. WTS shutdown will be initiated when generator protection sensors approach overstress limits.							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN	B TRANSITION TO WARM UP	D TRANSITION TO STANDBY	E STANDBY	F TRANSITION TO OPERATE	G OPERATE	H TRANSITION TO FEATHER	I FEATHER
				REV 10/13/78			
				REV 10/25/78			
				REV 11/27/78			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT REACTIVE POWER TRANSDUCER		PAGE 109 FMEA NO 6.8.5.4	
FUNCTION OF COMPONENT PROVIDES A 0-1 MA OUTPUT ANALOG SIGNAL OF GENERATOR KVAR OUTPUT BASED ON INPUTS FROM POTENTIAL AND CURRENT TRANSFORMERS. THIS SIGNAL IS PROVIDED TO A KVAR METER DISPLAY.					
FAILURE MODES & EFFECTS 1 Output high: incorrect on-site displays.				APPLICABLE OPERATING MODES G	
2 Output low: incorrect on-site displays.				G	
3					
4					

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.1	200	X			
2	50	1.1	200	X			
3							
4							

FAILURE DETECTION METHODS	
1-2	No remote detection available. KVAR meter display is not compatible with voltage, current, power factor and KW meter displays.
3	
4	

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)
 KVAR's can be derived from other data displayed at site: voltage, current, power factor and real power.

OPERATING MODES A SHUTDOWN B TRANSITION TO WARM-UP C WARM-UP D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I - FEATHER	NAME G. TRUSK/H. ROTH DATE 8/17/78 REV 10/13/78
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MOD 2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT ACCESSORY POWER TRANSFORMER	PAGE 110 FMEA NO 6.8.6					
FUNCTION OF COMPONENT TRANSFORMS 480 VOLTS TO 115/230 VOLTS TO PROVIDE ELECTRICAL POWER TO ACCESSORIES MOUNTED IN THE NACELLE.							
FAILURE MODES & EFFECTS <u>1 Open circuit: WTS cannot start up or shut down via normal control system procedure.</u>		APPLICABLE OPERATING MODES B, C, D, E, F,G,H					
<u>2 Short circuit: Same as No. 1</u>		B, C, D, E, F,G,H					
<u>3 _____</u>							
<u>4 _____</u>							
FAILURE FREQUENCY MEAN TIME BETWEEN FAILURE (YEARS) FAILURE SEVERITY MINIMAL I MARGINAL II CRITICAL III CATASTROPHIC IV							
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.1	200			X	
2	50	1.1	200			X	
3							
4							
FAILURE DETECTION METHODS							
<u>1-2 Zero power output indicated at manned substation</u>							
<u>2 _____</u>							
<u>3 _____</u>							
<u>4 _____</u>							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) <u>1-2 Loss of nacelle 115/230 Vac incapacitates the control system. Generation system protection will function from uninterruptable power supply. Shutdown via this mode will not result in rotor overspeed beyond design limits.</u>							
NAME G. TRUSK/H. ROTH							DATE 8/17/78
OPERATING MODES A SHUTDOWN B TRANSITION TO WARM UP C WARM UP D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I FEATHER Rev 10/13/78 Rev 10/25/78							

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS			COMPONENT 115/230 VOLT CIRCUIT BREAKER PANEL			PAGE 112 FMEA NO 6.8.7.2	
FUNCTION OF COMPONENT PROVIDES FOR THE DISTRIBUTION AND PROTECTION OF 115/230 VOLT ACCESSORY POWER WITHIN THE NACELLE							
FAILURE MODES & EFFECTS 1 Individual circuit breakers open prematurely or fail to close.						APPLICABLE OPERATING MODES ALL	
2 Individual circuit breakers fail to trip when required						ALL	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.1	200	X		1*	
2	50	1.1	200	X		1*	
3							
4							

FAILURE DETECTION METHODS	
1	See FMEA sheets for individual items.
2	
3	
4	

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

1* Critical if faulty breaker affects critical control systems, otherwise minimal.

		NAME B. TRUSK/H. ROTH	DATE 7/17/78
--	--	-----------------------	--------------

OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

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MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT 480 VOLT CIRCUITS	PAGE 115 FMEA NO 6.8.8.2					
FUNCTION OF COMPONENT <u>PROVIDES A PATH FOR THE FLOW OF 480 VOLT POWER WITHIN THE GENERATOR ACCESSORY UNIT.</u>							
FAILURE MODES & EFFECTS		APPLICABLE OPERATING MODES					
<u>1 A circuit is open circuited:</u>		A11					
<u>2 A circuit is shorted to ground: protective circuit breaker trips</u>		A11					
<u>3 Two circuits are shorted:</u>		A11					
<u>4 _____</u>							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.1	200				
2	25	1.1	400				
3	25	1.1	400				
4							
FAILURE DETECTION METHODS							
<u>1 _____</u>							
<u>2 _____</u>							
<u>3 _____</u>							
<u>4 _____</u>							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) <u>See FMEA sheets for individual items receiving 480 volt power.</u>							
NAME G. TRUSK/H. ROTH							DATE 8/17/78
OPERATING MODES							
A SHUTDOWN D TRANSITION TO STANDBY G OPERATE							
B TRANSITION TO WARM UP E STANDBY H TRANSITION TO FEATHER							
C WARM UP F TRANSITION TO OPERATE I FEATHER							

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE			COMPONENT D.C. CIRCUITS			PAGE 117 FMEA NO 6.8.8.4	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF UNINTERRUPTIBLE DC POWER WITHIN THE GENERATOR ACCESS OXRY UNIT (GAU).							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Open circuit in individual circuit: loss of individual function						A11	
2 Short to ground on individual circuit: same as #1						A11	
3 Open circuit to the GAU: loss of generator protective functions, aircraft warning lights and WTS shuts down.						A11	
4							
FAILURE FREQUENCY				FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	75	1.1	133	*		X	
2	75	1.1	133	*		X	
3	25	1.1	400			X	
4							
FAILURE DETECTION METHODS							
1 & 2 Not remotely detectable.							
3							
WTS shuts down							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
See FMEA sheets for individual functions:							
Generator protective devices (6.8.1, 6.8.3.1 through 6.8.3.8)							
Aircraft warning lights (6.9.3)							
Control system (memory and fail-safe shutdown circuits 7.7.4 and 7.7.6)							
* Failure severity critical if WTS shuts down via fail-safe shutdown circuits.							
NAME G. TRUSK/H. ROTH						DATE 8/17/78	
OPERATING MODES						REV 10/13/78 REV 10/25/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT CONTROL CIRCUITS		PAGE 118				
				FMEA NO 6.8.8.5				
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF COMMAND, CONTROL AND INSTRUMENTATION SIGNALS WITHIN THE GENERATOR ACCESSORY UNIT.								
FAILURE MODES & EFFECTS <u>1 Individual path is open circuited</u>				APPLICABLE OPERATING MODES F, G, H				
<u>2 Individual path is shorted to ground</u>				F, G, H				
<u>3</u>								
<u>4</u>								
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)		FAILURE SEVERITY *			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR			MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	75	2.3	66.7					
2	25	2.3	200					
3								
4								
FAILURE DETECTION METHODS								
<u>1</u>								
<u>2</u>								
<u>3</u>								
<u>4</u>								
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) <u>* See FMEA sheets for individual functions and failure severity</u> <u>(6.8.1 through 6.8.5.5).</u>								
					NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES								
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE	REV 10/13/78					
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER	REV 10/25/78					
C WARM UP	F TRANSITION TO OPERATE	I FEATHER						

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS		COMPONENT CONVENIENCE OUTLETS		PAGE FMEA NO 6.9.2		
FUNCTION OF COMPONENT <u>MAKES ACCESSORY POWER AVAILABLE FOR TEMPORARY USE WITHIN THE NACELLE</u> <u>FOR ASSEMBLY MAINTENANCE AND REPAIR TASKS.</u>						
FAILURE MODES & EFFECTS 1 Individual circuit breakers supplying convenient outlets trip: No power available at outlet. 2 Open circuit to specific outlet: No power available at outlet. 3 115/230 V power failure: No power available at any nacelle convenience outlet 4				APPLICABLE OPERATING MODES A A A		
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ % FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50 11.4	20	X			
2	25 11.4	40	X			
3	25 11.4	40	X			
4						
FAILURE DETECTION METHODS 1-3 Portable equipment fails to function 2 3 4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 						
			NAME B. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES A SHUTDOWN B TRANSITION TO WARM UP C WARM UP D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I FEATHER						
Rev 10/13/78 Rev 10/25/78						

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM NACELLE - EPS	COMPONENT AIRCRAFT WARNING LIGHTS	PAGE 121 FMEA NO 6.9.3					
FUNCTION OF COMPONENT <u>COMPLIES WITH FAA REQUIREMENTS TO PROVIDE VISUAL WARNING OF OBSTRUCTION TO LOW FLYING AIRCRAFT.</u>							
FAILURE MODES & EFFECTS		APPLICABLE OPERATING MODES					
1 Circuit breaker is tripped: high-intensity flashing white obstruction (HIFWO) lights are extinguished.		A11					
2 Wire to individual (one of three) high-intensity flashing white obstruction lights is open circuit: one HIFWO is extinguished.		A11					
3 Lamp malfunctions (burns out): individual HIFWO light is extinguished.		A11					
4 _____							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	2	1140	5	X			
2	1	1140	10	X			
3	97	1140	.1	X			
4							
FAILURE DETECTION METHODS							
1-3 Alarm at manned substation. Visual observance at site. # # 4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES				REV 10/13/78 REV 10/25/78			
A SHUTDOWN B TRANSITION TO WARM UP C WARM UP		D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE		G OPERATE H TRANSITION TO FEATHER I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER SUBASSEMBLY			COMPONENT TOWER STRUCTURE			PAGE 122 FMEA NO 7.1.1	
FUNCTION OF COMPONENT THE TOWER STRUCTURE SUPPORTS AND PROVIDES MOUNTING PROVISIONS FOR THE YAW DRIVE SYSTEM, ELECTRICAL CABLES AND NACELLE ACCESS DEVICE.							
FAILURE MODES & EFFECTS 1 Structural failure to tower due to overload						APPLICABLE OPERATING MODES All modes	
2							
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	negligible						X
2							
3							
4							
FAILURE DETECTION METHODS							
1 Inspect tower if overload condition occurs.							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
The tower structure will be safe life designed, and no failures are anticipated unless loads greater than the design limit loads occur. Structural analysis will be performed using the MOD-2 WTS structural design criteria.							
NAME J. SHULTZ						DATE 8-14-78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER SUBASSEMBLY		COMPONENT LADDER		PAGE 124 FMEA NO 7.1.3			
FUNCTION OF COMPONENT THE LADDER PROVIDES A MEANS OF ENTERING AND EGRESSING THE NACELLE FROM THE POWER LIFT PLATFORM AND PROVIDES AN ALTERNATE SYSTEM IF THE POWER LIFT MALFUNCTIONS.							
FAILURE MODES & EFFECTS 1 Structural failure due to overload. failure. 2 3 4				APPLICABLE OPERATING MODES maintenance			
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1		Negligible		X			
2							
3							
4							
FAILURE DETECTION METHODS							
1 Periodic visual inspections							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) No failure anticipated - ladder and attachments will be safe life designed - structural analysis will be performed using the MOD-2 WTS structural design criteria.							
				NAME J. SHULTZ		DATE 8-14-78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER SUBASSEMBLY			COMPONENT TOWER FOUNDATION			PAGE 125 FMEA NO 7.1.4	
FUNCTION OF COMPONENT The TOWER FOUNDATION SUPPORTS AND PROVIDES MOUNTING PROVISIONS FOR THE TOWER STRUCTURE							
FAILURE MODES & EFFECTS 1 Structural failure of concrete foundation due to overload. 2 Structural failure of attachment bolts due to overload or corrosion. 3 Differential settlement of foundation due to overload resulting in excessive system tilt. 4						APPLICABLE OPERATING MODES All modes All modes All modes	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1		Negligible			X		
2		Negligible			X		
3		Negligible			X		
4							
FAILURE DETECTION METHODS							
1 Perioduc visual inspections							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
No failures anticipated unless loads greater than the design limit loads occur.							
Structural analysis will be performed using the MOD-2 WTS structural design criteria.							
Corrosion prevention finishes will be used and maintenance performed when required.							
NAME J. SHULTZ						DATE 8-14-78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD 2 Failure Mode and Effects Analysis

SUB-SYSTEM TOWER - EPS		COMPONENT TOWER-HIGH VOLTAGE CABLE		PAGE 126 FMEA NO 7 2 1 1		
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF HIGH VOLTAGE GENERATOR OUTPUT CURRENT FROM THE CABLE TRANSITION MECHANISM TO THE HIGH VOLTAGE JUNCTION BOX AT THE FOOT OF THE TOWER.						
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES		
1 OPEN CIRCUIT: ONE OR MORE PHASES GO TO ZERO VOLTAGE; GCB OPENS, BTC (BUS TIE CONTACTOR) OPENS, WTS SHUTS DOWN.				G		
2 SHORT CIRCUIT: POSSIBLE PHASE-TO-PHASE FAULT; GCB OPENS, BTC OPENS, WTS SHUTS DOWN.				G		
3 GROUNDED CONDUCTOR MASSIVE FAULT ON ONE CONDUCTOR; GCB OPENS, BTC OPENS, WTS SHUTS DOWN.				G		
4						
FAILURE FREQUENCY			FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III
1	50	.8	286			X
2	25	.8	578			X
3	25	.8	578			X
4						
FAILURE DETECTION METHODS						
1 GENERATOR POWER INDICATION INDICATES ZERO POWER;- BTC POSITION INDICATES "OPEN".						
2 -3 GENERATOR POWER INDICATION INDICATES ZERO POWER; GCB AND BTC POSITION INDICATES						
X ~ BOTH ARE "OPEN".						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)						
1 DIFFERENTIAL CURRENT PROTECTION RELAY WILL CAUSE THE GCB TO OPEN OR AS A BACKUP, THE DIFFERENTIAL CURRENT PROTECTION CIRCUIT WILL CAUSE THE BTC TO OPEN.						
2 GENERATOR OR BTCU DIFFERENTIAL CURRENT PROTECTION OR GENERATOR OVER-CURRENT PROTECTION CIRCUITS WILL CAUSE THE GCB AND BTC TO OPEN						
3 SAME AS 2 PLUS THE GROUND CURRENT RELAY WILL CAUSE THE GCB TO OPEN.						
				NAME G TRUSK/H. ROTH		DATE 8/17/78
OPERATING MODES						
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM			COMPONENT		PAGE		
TOWER - EPS			TOWER TO BTBU HIGH VOLTAGE CABLE		127 FMEA NO 7.2.1.2		
FUNCTION OF COMPONENT							
PROVIDES AN UNDERGROUND PATH FOR THE FLOW OF HIGH VOLTAGE GENERATOR CURRENT FROM THE JUNCTION BOX INSIDE THE FOOT OF THE TOWER TO THE BUS TIE BREAKER UNIT LOCATED OUTSIDE AND AWAY FROM THE TOWER.							
FAILURE MODES & EFFECTS					APPLICABLE OPERATING MODES		
1 Open circuit: one or more high voltage power phases go to zero volts: BTC opens, WTS shuts down					G		
2 Short circuit: possible phase-to-phase or phase-to-neutral fault; BTC opens, WTS shuts down					G		
3 Grounded conductor: massive fault on one high voltage conductor BTC opens, WTS shuts down					G		
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.4	571			X	
2	25	.4	1143			X	
3	25	.4	1143			X	
4							
FAILURE DETECTION METHODS							
1-3 WTS shut down							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1-3 Tower zone differential current protection relay will cause the BTC to open. As a backup: generator over-current or ground protection relay may trip the GCB; fused manual disconnect may fuse open.							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE					
B TRANSITION TO WARM-UP	E STANDBY	H TRANSITION TO FEATHER					
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS	COMPONENT BTBU TO TRANSFORMER HIGH VOLTAGE CABLE	PAGE 128 FMEA NO 7.2.1.3				
FUNCTION OF COMPONENT <u>PROVIDES AN UNDERGROUND PATH FOR THE FLOW OF HIGH VOLTAGE GENERATOR OUTPUT CURRENT FROM THE BUS TIE BREAKER UNIT TO THE INPUT SIDE OF THE POWER OUTPUT TRANSFORMER.</u>						
FAILURE MODES & EFFECTS		APPLICABLE OPERATING MODES				
1 Open circuit: one or more high voltage power phases go to zero volts: BTC opens, WTS shuts down, accessory power is distributed at other than 3-phase.		G				
2 Short circuit: possible phase-to-phase or phase-to-neutral fault; BTC opens, WTS shuts down, accessory power is distributed at other than 3-phase.		G				
3 Grounded conductor: Massive fault on one high voltage conductor BTC opens, WTS shuts down, accessory power is distributed at _____		G				
4 other than 3 phase.						
FAILURE FREQUENCY		FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ % FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50 .4	570			X	
2	25 .4	1140			X	
3	25 .4	1140			X	
4						
FAILURE DETECTION METHODS						
1-3 WTS shut down						
2						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 1-3 For generator protection see FMEA 7.2.1.2 1-3 For accessory power utilization equipment protection (TBA) see also FMEA 7.2.2.1						
				NAME G. TRUSK/H. ROTH	DATE 8/28/78	
OPERATING MODES						
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE				
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER				
C WARM UP	F TRANSITION TO OPERATE	I FEATHER				

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT ACCESSORY POWER FEEDER TO THE TOWER JUNCTION BOX		PAGE 130 FMEA NO 7.2.2.1			
FUNCTION OF COMPONENT PROVIDE AN UNDERGROUND PATH FOR THE FLOW OF NECESSARY POWER FROM THE BUS TIE BREAKER UNIT TO THE ACCESSORY POWER JUNCTION BOX AT THE BASE OF THE TOWER.							
FAILURE MODES & EFFECTS					APPLICABLE OPERATING MODES		
1 Open circuit: accessory power is distributed at other than 3-phase.					F, G, H		
2 Short circuit: fused manual disconnect may fuse and accessory power distributed at other than 3-phase.					F, G, H		
3 Grounded conductor: fused manual disconnect fuses and accessory power distributed at other than 3-phase.					F, G, H		
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.13	1800			X	
2	25	.13	3600			X	
3	25	.13	3600			X	
4							
FAILURE DETECTION METHODS							
1-3 WTS shut down.							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
If power phase faulted is supplying the control system, WTS will go into emergency shutdown; if one of the other two phases, the WTS will probably shut down.							
					NAME G. TRUSK/H. ROTH		DATE 8/17/78
OPERATING MODES					REV 10/16/78 Rev. 10/25/78		
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT ACCESSORY POWER FEEDER TO THE NACELLE		PAGE 131 FMEA NO 7.2.2.2			
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF NACELLE ACCESSORY POWER FROM THE JUNCTION BOX AT THE BASE OF THE TOWER TO THE CABLE TRANSITION MECHANISM AT THE YAW BEARING.							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 Open Circuit				F,G,H			
2 Short Circuit				F,G,H			
3 Grounded Conductor				F,G,H			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500			X	
2	25	.15	>3000			X	
3	25	.15	>3000			X	
4							
FAILURE DETECTION METHODS							
1-3 WTS shutdown.							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
Same as FMEA 7.2.2.1							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES				Rev. 10/16/78 Rev. 10/25/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT ACCESSORY POWER CABLE TO THE TOWER CONTROL UNIT		PAGE 132 FMEA NO 7.2.2.3			
FUNCTION OF COMPONENT PROVIDE AN UNDERGROUND PATH FOR THE FLOW OF ACCESSORY POWER FROM THE BUS TIE CIRCUIT BREAKER UNIT TO THE CONTROL SYSTEM'S TOWER CONTROL UNIT LOCATED INSIDE THE BASE OF THE TOWER.							
FAILURE MODES & EFFECTS 1 Open circuit: loss of capability to communicate with nacelle control system.				APPLICABLE OPERATING MODES Maintenance			
2 Short circuit: Same as #1				Maintenance			
3 Grounded Conductor. Same as #1				Maintenance			
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.13	1800	X	-		
2	25	.13	3600	X			
3	25	.13	3600	X			
4	-						
FAILURE DETECTION METHODS							
1-3 None remotely							
X 1-3 On Site: Inability to manually operate the WTS							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 							
				NAME G. TRUSK/H. ROTH		DATE 8/17/8	
OPERATING MODES							
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE	Rev 10/16/8				
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER	Rev. 10/25/78				
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT ACCESSORY POWER CABLE TO THE LIFT SYSTEM			PAGE 133 FMEA NO 7.2.2.4	
FUNCTION OF COMPONENT PROVIDE AN UNDERGROUND PATH FOR THE FLOW OF ACCESSORY POWER FROM THE BUS TIE BREAKER UNIT TO THE LIFT SYSTEM LOCATED IN THE BASE OF THE TOWER.							
FAILURE MODES & EFFECTS 1 Open Circuit: Elevator will not operate						APPLICABLE OPERATING MODES Maintenance	
2 Short Circuit: Elevator protective circuit breaker trips, elevator will not operate						Maintenance	
3 Grounded Conductor: Elevator protective circuit breaker trips, elevator will not operate						Maintenance	
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500	X			
2	25	.15	>3000	X			
3	25	.15	>3000	X			
4							

FAILURE DETECTION METHODS

1-3 On-site elevator does not operate, associated circuit breaker is tripped

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

Emergency egress from the lift is via a ladder with safety rail

NAME G. TRUSK/H. ROTH		DATE 8/17/78
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OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS	COMPONENT ACCESSORY POWER FEEDER TO TOWER ELECTRICAL FACILITIES	PAGE 134 FMEA NO 7.2.2.5					
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF ACCESSORY POWER FROM THE BUS TIE BREAKER UNIT TO THE ELECTRICAL FACILITIES LOCATED AT THE FOOT OF THE TOWER							
FAILURE MODES & EFFECTS 1 Open Circuit lights or utility outlets not functional		APPLICABLE OPERATING MODES Maintenance					
2 Short Circuit protective circuit breaker trips and lights or utility outlets not functional		Maintenance					
3 Grounded Conductor, Protective circuit breaker trips and lights or utility outlets not functional		Maintenance					
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500	X			
2	25	.15	>3000	X			
3	25	.15	>3000	X			
4							
FAILURE DETECTION METHODS							
1-3 None remotely							
1-3 On Site: Lights out or electrical outlets not functioning							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 							
				NAME G. TRUSK/H. ROTH		DATE 8/11/78	
OPERATING MODES				Rev. 10/16/78 Rev. 10/25/78			
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE					
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER					
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS	COMPONENT ACCESSORY POWER CABLE TO THE .POWER OUTPUT TRANSFORMER	PAGE 135 FMEA NO 7.2.2.6					
FUNCTION OF COMPONENT PROVIDE AN UNDERGROUND PART FOR THE FLOW OF ACCESSORY POWER FROM THE BUS TIE BREAKER TO THE HIGH VOLTAGE POWER OUTPUT TRANSFORMER							
FAILURE MODES & EFFECTS <u>1 Open Circuit:</u> WTS shuts down, accessory power distributed at less than 3-phase.		APPLICABLE OPERATING MODES A11					
<u>2 Short Circuit:</u> Same as #1, fused manual switch for accessory power may be fused open.		A11					
<u>3 Grounded Conductor:</u> Same as #2		A11					
<u>4</u>							
FAILURE FREQUENCY				FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500			X	
2	25	.15	>3000			X	
3	25	.15	>3000			X	
4							
FAILURE DETECTION METHODS							
<u>1 WTS Shut Down</u>							
<u>2</u>							
<u>3</u>							
<u>4</u>							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) <u>1-3 Differential protection will trip the BTC if WTS in "Operate" mode.</u>							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT UNINTERRUPTABLE POWER FEEDER TO THE TOWER JUNCTION BOX		PAGE 136 FMEA NO 7.2.2.7			
FUNCTION OF COMPONENT PROVIDE AN UNDERGROUND PATH FOR THE FLOW OF UNINTERRUPTABLE (DC) POWER FROM THE BUS TIE BREAKER TO THE JUNCTION BOX LOCATED INSIDE THE BASE OF THE TOWER.							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 Open Circuit: No power to operate protection devices in BTCU.				F, G			
2 Short Circuit: Same as #1				F, G			
3 Conductor Grounded: Same As #1				F, G			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500			*	
2	25	.15	>3000			*	
3	25	.15	>3000			*	
4							
FAILURE DETECTION METHODS							
1							
1-3 WTS shutdown.							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
Conservative and redundant design of cable run & careful fabrication techniques should minimize the probability of this failure mode. If the following faults occur WTS will non shut down: Utility transformer low oil or overtemperature, reverse power or differential protection.							
Utility transformer is protected against explosion and fire. Fused manual disconnect may fuse open under certain fault conditions.							
NAME G. TRUSK/H. ROTH				DATE 8/17/78			
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev. 10/16/78	
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		Rev. 11/27/78	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT UNINTERRUPTABLE POWER CABLE TO THE TOWER CONTROL UNIT		PAGE 137 FMEA NO 7.2.2.8	
FUNCTION OF COMPONENT PROVIDE AN UNDERGROUND PATH FOR THE FLOW OF UNINTERRUPTABLE POWER FROM THE BUS TIE BREAKER UNIT TO THE CONTROL SYSTEMS TOWER CONTROL UNIT MOUNTED INSIDE THE BASE OF THE TOWER.					
FAILURE MODES & EFFECTS 1 Open circuit. Loss of stored data				APPLICABLE OPERATING MODES Maintenance	
2 Short circuit. Same as #1				Maintenance	
3 Conductor Grounded Same as #1				Maintenance	
4					

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.13	1800	X			
2	25	.13	3600	X			
3	25	.13	3600	X			
4							

FAILURE DETECTION METHODS

1 - 3 Remotely, None

2 1-3*

3

4

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

Data stored in memory is lost, maintenance personnel are not able to use on-site
stored data for trouble identification. Trouble shooting procedures are adequate
to isolate and identify source of malfunctions.

NAME G. TRUSK/H. ROTH		DATE 8/17/78
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OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

Rev 10/17/78

Rev. 10/25/78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT UNINTERRUPTABLE POWER FEEDER TO THE NACELLE		PAGE 138 FMEA NO 7.2.2.9											
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF NACELLE UNINTERRUPTABLE (DC) POWER FROM THE JUNCTION BOX LOCATED INSIDE THE BASE OF THE TOWER TO THE CABLE TRANSITION MECHANISM AT THE YAW BEARING.															
FAILURE MODES & EFFECTS 1 Open Circuit				APPLICABLE OPERATING MODES A11											
2 Short Circuit: Same as #1				A11											
3 Conductor Grounded				A11											
4															
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY *											
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV								
1	50	.15	>1500			X									
2	25	.15	>3000			X									
3	25	.15	>3000			X									
4															
FAILURE DETECTION METHODS															
1-3 WTS shutdown.															
2															
3															
4															
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)															
Same as FMEA's 6.6.2.3 & 6.6.2.10															
				NAME G. TRUSK/H. ROTH		DATE 8/17/78									
OPERATING MODES				Rev. 10/16/78											
A SHUTDOWN				D TRANSITION TO STANDBY				G OPERATE				Rev. 10/25/78			
B TRANSITION TO WARM UP				E STANDBY				H TRANSITION TO FEATHER							
C WARM UP				F TRANSITION TO OPERATE				I FEATHER							

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER EPS	COMPONENT CONTROL CABLE TO THE NACELLE	PAGE 139 FMEA NO 7.2.3.1					
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF CONTROL SYSTEM COMMANDS AND DATA FROM THE TOWER CONTROL UNIT INSIDE THE BASE OF THE TOWER TO THE CABLE TRANSITION MECHANISM AT THE YAW BEARING.							
FAILURE MODES & EFFECTS		APPLICABLE OPERATING MODES					
1 Wire is open circuit		A11					
2 Wires short circuited		A11					
3 Wire shorted to ground		A11					
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.15	>1500			X	
2	25	.15	>3000			X	
3	25	.15	>3000			X	
4							
FAILURE DETECTION METHODS							
1 -3 WTS shutdown.							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
Same as FMEA 6.6.3.5							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev. 10/16/78	
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT CONTROL CABLE TO THE BTB UNIT			PAGE 140 FMEA NO 7.2.3.2	
FUNCTION OF COMPONENT PROVIDE AN UNDERGROUND PATH FOR THE FLOW OF CONTROL SYSTEM COMMANDS AND DATA FROM THE TOWER CONTROL UNIT LOCATED INSIDE THE BASE OF THE TOWER TO THE BUS TIE BREAKER UNIT.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Open circuit: BTB does not trip on WTS shutdown command, synchronizer cannot be enabled, utility bus tie or power status is not available.						F.G.	
2 Short circuit: same as #1						F.G.	
3 Grounded conductor: Same as #1						F.G.	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	.6	400	X			
2	25	.6	800	X			
3	25	.6	800	X			
4							
FAILURE DETECTION METHODS							
1-3 None remotely							
X 1-3 On-site Review of stored data							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
Protective devices in the EPS will trip the BTC as a result of reverse power if WTS is shut down.							
Also see FMEA 7.7.41 through 7.7.44							
						NAME G. TRUSK/H. ROTH	
						DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev 10/17/78	
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT CABLE TRANSITION MECHANISM		PAGE 141 FMEA NO 7.3.			
FUNCTION OF COMPONENT PROVIDE A MEANS OF TRANSFERRING POWER AND SIGNAL ELECTRICAL CIRCUITS FROM THE NACELLE TO TOWER AROUND THE YAW BEARING THUS ALLOWING THE NACELLE TO ROTATE IN RELATION TO THE TOWER.							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 Open circuits or high impedance				ALL			
2 Conductive path between brushes							
3 Conductive path to case							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	98	37.6	3.1				
2	1	37.6	303				
3	1	37.6	303				
4							
FAILURE DETECTION METHODS							
1							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
Total for all signals							
See FMEA's 6.6.1.1, 6.6.1.2, 6.6.2.1 through 6.6.2.10 for failure severity and fault detection methods.							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES				Rev 10/16/78 Rev 10/25/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT GENERATOR LIGHTING ARRESTORS			PAGE 143 FMEA NO 7.4.2	
FUNCTION OF COMPONENT PROVIDE A LOW IMPEDANCE PATH FOR THE FLOW OF LIGHTNING INDUCED CURRENT FROM THE GENERATOR WINDINGS TO THE STRUCTURAL GROUND PATH OF THE SYSTEM. (THESE ARRESTORS ARE IN THE GENERATOR TERMINAL BOX).							
FAILURE MODES & EFFECTS 1 Open circuit: No protection against lightning surge currents.						APPLICABLE OPERATING MODES	
						A11	
2							
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	100	1.1	100			X	
2							
3							
4							
FAILURE DETECTION METHODS							
1 WTS shutdown							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
If lightning surge currents reach the generator winding, because the arrestor is open circuit, insulation damage can occur leading to an internal fault. Backup protection is provided by differential protection and ground current protection. Careful attention to lightning arrestor installation should be sufficient to preclude this failure mode.							
NAME G. TRUSK/H. ROTH						DATE 8/17/78	
Rev 10/17/8							
OPERATING MODES							
A - SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS	COMPONENT TRANSFORMER LIGHTNING ARRESTORS	PAGE 144 FMEA NO 7.4.3					
FUNCTION OF COMPONENT PROTECT THE TRANSFORMER WINDINGS BY PROVIDING A LOW IMPEDANCE PATH TO EARTH GROUND FOR LIGHTNING INDUCED CURRENT. (THESE ARRESTORS ARE LOCATED IN THE TRANSFORMER TERMINAL BOX).							
FAILURE MODES & EFFECTS 1 Open circuit. No protection against lightning surge currents.		APPLICABLE OPERATING MODES A11					
2 _____ _____							
3 _____ _____							
4 _____ _____							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	100	1.1	100			X	
2							
3							
4							
FAILURE DETECTION METHODS							
1 WTS Shut down							
2 _____							
3 _____							
4 _____							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) If lightning surge currents reach the transformer windings, because the arrestor is open circuit, insulation damage or flashover can occur leading to an internal fault. Backup protection is provided by differential protection.							
NAME G. TRUSK/H. ROTH DATE 8/17/8							
OPERATING MODES							
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE	Rev. 10/17/8				
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER	Rev. 10/25/78				
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT EARTH GRID			PAGE 145 FMEA NO 7.4.4	
FUNCTION OF COMPONENT PROVIDE A SATISFACTORY ELECTRICAL CONNECTION WITH THE EARTH TO PROVIDE A CURRENT PATH FOR LIGHTNING AND ELECTRICAL FAULT CURRENTS.							
FAILURE MODES & EFFECTS 1 Open circuit possible: erratic relay operation, possible high potential between structures and earth.						APPLICABLE OPERATING MODES A11	
2 High resistance circuit: same as #1.						A11	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	25	1.1	400 ▶			X	▶
2	75	1.1	133 ▶			X	▶
3							
4							
FAILURE DETECTION METHODS							
1-2 None remotely.							
1-2 On-site: erratic relay operation.							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
During faults or lightning, lethal potential differences can occur between equipment and earth when the earth connection is either open circuited or has a high resistance. During normal operation protective relays may operate inadvertently to result in WTS shutdown and possible shock hazards to personnel may exist due to unbalanced loads. Special precautions will be taken to assure that grounds are properly installed and that earth/ground resistance is at safe levels.							
▶ If site is occupied- O&M Manual will prohibit maintenance during storms.							
▶ Without periodic inspections. With periodic inspections, frequency is over 100,000 years between failure.							
NAME G. TRUSK/H. ROTH						DATE 8/17/78	
OPERATING MODES						REV 10/17/78 Rev. 10/25/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT CONNECTION TO EARTH GRID		PAGE 146			
				FMEA NO 7.4.5			
FUNCTION OF COMPONENT PROVIDE A PATH FOR THE FLOW OF LIGHTNING INDUCED CURRENTS AND ELECTRICAL FAULT CURRENTS IN THE WTS STRUCTURE TO THE EARTH GRID TO ALLOW THEIR SAFE DISSIPATION.							
FAILURE MODES & EFFECTS 1 Same as FMEA 7.4.4				APPLICABLE OPERATING MODES A11			
2							
3							
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	100	1 1	100				
2							
3							
4							
FAILURE DETECTION METHODS							
1							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) Same as FMEA 7.4.4. 							
				NAME G. TRUSK/H. ROTH	DATE 8/17/78		
OPERATING MODES				REV 10/17/78 Rev. 10/25/78			
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE					
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER					
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS	COMPONENT BTBU ENCLOSURE	PAGE FMEA NO	147 7.6.1.1
FUNCTION OF COMPONENT PROVIDE A WEATHERPROOF HOUSING, A MOUNTING BASE AND A MEANS OF CONVENIENT ACCESS TO ALL THE EQUIPMENT AND WIRING PACKAGED WITHIN THE BUS TIE BREAKER UNIT.			
FAILURE MODES & EFFECTS 1 Enclosure leaks water or sand/dust into enclosure.		APPLICABLE OPERATING MODES ALL	
2			
3			
4			
FAILURE FREQUENCY		FAILURE SEVERITY	
FAILURE MODE NO	FAILURE MODE FREQ % FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I MARGINAL II CRITICAL III CATASTROPHIC IV
1	Negligible	X	
2			
3			
4			
FAILURE DETECTION METHODS			
1 Inspection			
2			
3			
4			
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) Proper positioning of parts to minimize water entering live circuits by baffling, channeling and drip proofing as well as close detail to weather-proofing or enclosure and drainage will preclude electrical failures due to water and particulate damage.			
NAME G. TRUSK/H. ROTH DATE 8/17/78			
OPERATING MODES A SHUTDOWN B TRANSITION TO WARM UP C WARM UP D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER -EPS			COMPONENT BUS TIE CONTACTOR (BTC)			PAGE 148 FMEA NO 7.6.1.2	
FUNCTION OF COMPONENT PROVIDE A REMOTELY OPERATED, HIGH VOLTAGE, HIGH CURRENT, ELECTRICAL SWITCH TO PERMIT THE FREQUENT CONNECTING AND DISCONNECTING OF THE WTS ELECTRICAL POWER OUTPUT TO THE UTILITY TRANSMISSION LINE.							
FAILURE MODES & EFFECTS 1 BTC FAILS OPEN. WTS CANNOT BE CONNECTED TO THE UTILITY TRANSMISSION LINE.						APPLICABLE OPERATING MODES F,G,H	
2 BTC FAILS CLOSED: GCB WILL OPEN, WTS SHUTS DOWN.						F,G,H	
3 BTC HAS INTERNAL SHORT: POSSIBLE PHASE-TO-PHASE FAULT; GCB OPENS, BTC OPENS (IF POSSIBLE), WTS SHUTS DOWN.						F,G,H	
4 BTC HAS INTERNAL FAULT TO GROUND: MASSIVE FAULT OF A PHASE CONDUCTOR: GCB OPENS, BTC OPENS (IF POSSIBLE), WTS SHUTS DOWN.						F,G,H	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	20	2.28	100			X	
2	30	2.28	167			X	
3	30	2.28	167			X	
4	20	2.28	100			X	
FAILURE DETECTION METHODS 1 GENERATOR POWER INDICATION INDICATES ZERO POWER, BTC INDICATES OPEN. 2 NOT DEFECTABLE UNTIL A DISCONNECT SIGNAL IS SENT AND NOT OBEYED. 3 & 4 GENERATOR POWER INDICATION INDICATES ZERO POWER, BTC AND GCB INDICATE OPEN. 4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 1-4 REPLACE THE BTC; THE BTC IS COMMERCIALY AVAILABLE AND IN EXTENSIVE USE BY THE UTILITIES AND SHOULD BE VERY DEPENDABLE. 2 PROTECTIVE CIRCUITS TRIP THE GCB IF THE BTC HAS NOT OPENED AFTER IT SHOULD.							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES A SHUTDOWN D TRANSITION TO STANDBY G OPERATE B TRANSITION TO WARM UP E STANDBY H TRANSITION TO FEATHER C WARM UP F TRANSITION TO OPERATE I FEATHER							

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT SYNCHRONIZER			PAGE 149 FMEA NO 7.6.1.3.1	
FUNCTION OF COMPONENT DETERMINE WHEN VOLTAGE AMPLITUDES AND PHASE RELATIONSHIPS OF THE GENERATOR OUTPUT AND THE UTILITY TRANSMISSION LINE ARE WITHIN ACCEPTABLE, PRESET LIMITS AND PROVIDE A SIGNAL TO CLOSE THE BUS TIE CONTACTOR.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 FAILS TO OPERATE: WTS IS NOT CONNECTED TO UTILITY TRANSMISSION LINES.						F,G,H	
2 OPERATES TO SYNC TOO EARLY: MECHANICAL DAMAGE POSSIBLE.						F,G,H	
3 OPERATES TO SYNC TOO LATE: MECHANICAL DAMAGE POSSIBLE.						F,G,H	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1-3	100	▷			X		
2							
3							
4							
FAILURE DETECTION METHODS							
1 GENERATOR POWER INDICATOR INDICATES ZERO POWER, BTC INDICATES OPEN.							
2 & 3 IN EXTREME OUT-OF-SYNC BTC CLOSURE, MECHANICAL DAMAGE MAY OCCUR TO THE GENERATOR OR DRIVE TRAIN.							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
▷ Synchronizer is redundant, failure of one circuit results in disabling synchronizer. Resultant failure rate is negligible.							
* FAILURE SEVERITY MAY BE CATASTROPHIC IF MECHANICAL FAILURE RESULTS.							
NAME G. TRUSK/H. ROTH				DATE 8/17/78			
OPERATING MODES				Rev. 9/8/78 Rev. 10/25/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER.			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT DIFFERENTIAL PROTECTION RELAY			PAGE 150 FMEA NO 7.6.1.3.2	
FUNCTION OF COMPONENT MONITORS THE DIFFERENTIAL CURRENT FLOW IN THE WTS POWER OUTPUT CIRCUIT ZONE FROM THE CABLE TRANSITION MECHANISM TO THE FUSED MANUAL DISCONNECT SWITCH AND PROVIDES A SIGNAL TO OPEN THE BUS TIE CONTACTOR WHEN THE DIFFERENTIAL CURRENT EXCEEDS A PRESET LIMIT THUS INDICATING AN ELECTRICAL FAULT WITHIN THE PROTECTED ZONE.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Open circuit in sensing wires: BTC trips or cannot be closed.						G	
2 Trip setting is too low: BTC will trip too often on unbalanced loads or transients.						G	
3 Trip setting too high: fault currents may continue to flow.						G	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	21	11.1			X	
2	25	21	22.2			X	
3	25	21	22.2			X	
4							
FAILURE DETECTION METHODS							
1 WTS shut down							
2 WTS shut down							
3 WTS shut down							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1. Differential protection senses differential current in open phase. Troubleshooting procedures will reveal source of trouble, repair as necessary.							
2. Reset trip setting or replace differential protection relay in BTCU.							
3. GCB will trip on overcurrent. Troubleshoot reset trip setting or replace differential protection relay as necessary.							
						NAME G. TRUSK/H. ROTH	DATE 8/17/78
Rev 10/17/78							
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT GENERATOR VOLTMETER		PAGE 151 FMEA NO 7.6.1.4.1		
FUNCTION OF COMPONENT PROVIDES A CONTINUOUS VISUAL DISPLAY OF THE MAGNITUDE OF THE OUTPUT VOLTAGE OF THE GENERATOR FOR USE DURING ACCEPTANCE TESTING, TROUBLE SHOOTING AND MAINTENANCE.						
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES		
1 Does not indicate: no effect				Maintenance		
2 Indicates high or low: no effect				Maintenance		
3						
4						
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III
1, 2	100	1.1	100	X		
2						
3						
4						
FAILURE DETECTION METHODS						
1 Visual inspection						
2 Visual inspection						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)						
See also FMEA 7.6.1.4.9						
				NAME G. TRUSK/H. ROTH		DATE 8/17/78
OPERATING MODES						
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		
				Rev 10/17/78 Rev. 10/25/78		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS	COMPONENT UTILITY VOLTMETER	PAGE 152 FMEA NO 7.6.1.4.2																																															
FUNCTION OF COMPONENT PROVIDES A CONTINUAL VISUAL DISPLAY OF THE MAGNITUDE OF THE UTILITY VOLTAGE AT ITS INTERFACE WITH THE WTS FOR USE DURING ACCEPTANCE TESTING, TROUBLE SHOOTING AND MAINTENANCE.																																																	
FAILURE MODES & EFFECTS 1 Does not indicate: no effect		APPLICABLE OPERATING MODES All																																															
2 Indicates high or low: no effect																																																	
3																																																	
4																																																	
<table border="1"><thead><tr><th colspan="3">FAILURE FREQUENCY</th><th rowspan="2">MEAN TIME BETWEEN FAILURE (YEARS)</th><th colspan="4">FAILURE SEVERITY</th></tr><tr><th>FAILURE MODE NO</th><th>FAILURE MODE FREQ %</th><th>FAILURE RATE x 10⁻⁶ PER HOUR</th><th>MINIMAL I</th><th>MARGINAL II</th><th>CRITICAL III</th><th>CATASTROPHIC IV</th></tr></thead><tbody><tr><td>1, 2</td><td>100</td><td>1.1</td><td>100</td><td>X</td><td></td><td></td><td></td></tr><tr><td>2</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></tr><tr><td>3</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></tr><tr><td>4</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></tr></tbody></table>			FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY				FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV	1, 2	100	1.1	100	X				2								3								4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY																																													
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV																																										
1, 2	100	1.1	100	X																																													
2																																																	
3																																																	
4																																																	
FAILURE DETECTION METHODS 1- 2 Visual Inspection 2 Periodic Calibration Check 3 4																																																	
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 																																																	
NAME G. TRUSK/H. ROTH		DATE 8/17/8																																															
OPERATING MODES A SHUTDOWN B TRANSITION TO WARM UP C WARM UP D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE G OPERATE H TRANSITION TO FEATHER I FEATHER																																																	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS	COMPONENT GENERATOR AMMETER	PAGE 153 FMEA NO 7.6.1 4.3					
FUNCTION OF COMPONENT PROVIDES A CONTINUOUS VISUAL DISPLAY OF THE CURRENT FLOWING OUT OF THE GENERATOR							
FAILURE MODES & EFFECTS 1 Meter does not indicate: no direct reading of generator output current		APPLICABLE OPERATING MODES G					
2 Meter indicates high or low incorrect generator output current data.		G					
3							
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2	100	1.1	100	X			
2							
3							
4							
FAILURE DETECTION METHODS							
1 - 2 Visual and calculations							
2 Periodic calibration check							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 							
				NAME G. TRUSK/H. ROTH		DATE 8/17/8	
OPERATING MODES				Rev. 8/18/8 Rev. 10/25/78			
A SHUTDOWN	B TRANSITION TO WARM-UP	C WARM UP	D TRANSITION TO STANDBY	E STANDBY	F TRANSITION TO OPERATE	G OPERATE	H TRANSITION TO FEATHER
I FEATHER							

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT GENERATOR KW METER			PAGE 155 FMEA NO 7.6.1.4.5	
FUNCTION OF COMPONENT PROVIDES A CONTINUOUS DISPLAY OF THE KW (POWER) BEING DELIVERED BY THE GENERATOR.							
FAILURE MODES & EFFECTS 1 Meter does not indicate: No direct reading of power delivered by generator.						APPLICABLE OPERATING MODES G	
2 Meter indicates high or low: incorrect generator output power reading						G	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2	100	1.1	100	X			
2							
3							
4							

FAILURE DETECTION METHODS

1 - 2 Visual and calculations

2 Periodic calibration check

3

4

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

NAME G TRUSK / H. ROTH	DATE 8/17/8
------------------------	-------------

OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

Rev. 10/18/8

Rev. 10/25/78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT GENERATOR POWER FACTOR METER		PAGE 156 FMEA NO 7.6.1.4.6			
FUNCTION OF COMPONENT PROVIDES A CONTINUOUS DISPLAY OF THE POWER FACTOR OF CURRENT BEING DELIVERED BY THE GENERATOR.							
FAILURE MODES & EFFECTS 1 Meter does not indicate no direct reading of power factor delivered by the generator.				APPLICABLE OPERATING MODES G			
2 Meter indicates high or low: incorrect power factor data.				G			
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2	100	1.1	100	X			
2							
3							
4							
FAILURE DETECTION METHODS							
1 -2 Visual and calculations							
2 Periodic Calibration Check							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME G. TRUSK/H. ROTH	DATE 8/17/8		
OPERATING MODES				Rev. 10/18/8 Rev. 10/25/78			
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE					
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER					
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT GENERATOR KILOWATT- HOUR METER			PAGE 157 FMEA NO 7.6.1.4.7	
FUNCTION OF COMPONENT PROVIDES A CONTINUOUS VISUAL DISPLAY OF THE ACCUMULATED KILOWATT-HOURS DELIVERED BY THE GENERATOR							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Meter does not operate: meter readings are incorrect.						G	
2 Meter indicates high or low: meter readings are incorrect.						G	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE, x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,2	100	1.1	100	X			
2							
3							
4							
FAILURE DETECTION METHODS							
1 -2 Periodic reasonableness check.							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME H. ROTH/G. TRUSK		DATE 8/17/8	
OPERATING MODES				Rev. 10/18/8 Rev. 10/25/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT POTENTIAL TRANSFORMER			PAGE 159 FMEA NO 7.6.1.4.9	
FUNCTION OF COMPONENT PROVIDES A 0-115 VOLT SIGNAL PROPORTIONAL TO THE 0-4160 VOLT LEVEL EXISTING AT THE POINT OF CONNECTION. THIS SIGNAL IS USED BY THE SYNCHRONIZER, VOLTMETER AND THE VOLTAGE TRANSDUCER							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Secondary or primary winding is open circuited: No output						F,G,H	
2 Secondary or primary windings or short circuited						F,G,H	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	20	1.1	500			X	
2	80	1.1	125			X	
3							
4							
FAILURE DETECTION METHODS							
1 WTS Shutdown							
2 WTS shutdown.							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
Failures of potential transformers associated with control or protective relaying will result in WTS shutdown:							
Voltage Transducer (voltage regulator)				See FMEA 6.8.2.1			
Underfrequency Protection				See FMEA 6.8.3.2			
Overvoltage Protection				See FMEA 6.8.3.1			
Synchronizer				See FMEA 7.6.1.3.1			
Synchronization Check				See FMEA 7.6.1.3.1			
Power Factor Protection				See FMEA 6.8.3.10			
Power Factor Control				See FMEA 6.8.2.2			
For Metering Errors See FMEAS: 7.6.1.4.1, 7.6.1.4.2, 7.6.1.4.5 through 7.6.1.4.8							
NAME G. TRUSK/H. ROTH						DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev 10/18/78	
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT CURRENT TRANSFORMER			PAGE 160 FMEA NO 7.6.1.4.10	
FUNCTION OF COMPONENT PROVIDES A 0-5 AMP SIGNAL PROPORTIONAL TO THE 0-433 AMP CURRENT IN THE LINE TO WHICH IT IS ATTACHED. THIS SIGNAL IS USED BY THE DIFFERENTIAL PROTECTION RELAY, AMMETER AND THE CURRENT TRANSDUCER.							
FAILURE MODES & EFFECTS 1 SECONDARY WINDING FAILS OPEN CIRCUIT: NO OUTPUT SIGNAL.						APPLICABLE OPERATING MODES F,G,H	
2 SHORT BETWEEN SECONDARY WINDINGS: INCORRECT TURNS RATIO.						F,G,H	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	20	1.1	500			X	
2	80	1.1	125			X	
3							
4							
FAILURE DETECTION METHODS							
1 WTS Shutdown							
2 WTS shutdown							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
Failures of current transformers associated with control or protective relaying will result in WTS shutdown.							
Reverse Power Protection		See FMEA	6.8.3.4				
Differential Protection		See FMEA	6.8.3.6 & 7.6.1.3.2				
Power Factor Controller		See FMEA	6.8.2.2				
Loss of Excitation Protection		See FMEA	6.8.3.9				
Time Over-Current Protection		See FMEA	6.8.3.3				
Ground Fault Protection		See FMEA	6.8.3.5				
For Metering Errors See FMEAS: 7.6.1.4.3 through 7.6.1.4.8							
						NAME G. TRUSK/H. ROTH	DATE 8/17/78
OPERATING MODES						Rev 10/18/78 Rev. 10/25/78	
A SHUTDOWN B TRANSITION TO WARM UP C WARM UP		D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE		G OPERATE H TRANSITION TO FEATHER I FEATHER			

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT 4.16 kV TO 480 VOLT TRANSFORMER		PAGE 167 FMEA NO 7.6.1.5.1			
FUNCTION OF COMPONENT PROVIDES ALL OF THE ACCESSORY POWER USED IN THE WTS							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 Open circuit in primary or secondary windings: No output or non 3-phase output.				ALL			
2 Internal short circuit: input fused manual switch fuses open, No output.				ALL			
3 Internal ground fault: input fused manual switch, fuses open, no output.				ALL			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.1	200			X	
2	25	1.1	400			X	
3	25	1.1	400			X	
4							
FAILURE DETECTION METHODS							
1-3 WTS is shut down.							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
No accessory power available for housekeeping and maintenance functions							
See also FMEAS 6.8.6, 6.8.7.1 and 6.8.7.2, 6.8.8.2-6.8.8.4, 6.9.1-6.9.3, 7.2.2.1-7.2.2.9, 7.6.1.6.2, 7.6.1.7.3-7.6.1.7.5							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev 10/17/78	
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS	COMPONENT TRANSFORMER 480 VOLT TO 115/230 VOLT	PAGE 168 FMEA NO 7.6.1.5.2																																															
FUNCTION OF COMPONENT PROVIDES ALL OF THE 115/230 VOLT ACCESSORY POWER USED IN THE TOWER BELOW THE CABLE TRANSITION MECHANISM.																																																	
FAILURE MODES & EFFECTS 1 No output due to no input: no power for tower and base lights, convenience outlets, housekeeping and maintenance functions. 2 No output due to internal fault: circuit breaker trips, then same as #1. 3 4		APPLICABLE OPERATING MODES Maintenance Maintenance																																															
<table border="1"><thead><tr><th colspan="3">FAILURE FREQUENCY</th><th rowspan="2">MEAN TIME BETWEEN FAILURE (YEARS)</th><th colspan="4">FAILURE SEVERITY</th></tr><tr><th>FAILURE MODE NO</th><th>FAILURE MODE FREQ %</th><th>FAILURE RATE x 10⁻⁶ PER HOUR</th><th>MINIMAL I</th><th>MARGINAL II</th><th>CRITICAL III</th><th>CATASTROPHIC IV</th></tr></thead><tbody><tr><td>1</td><td>-</td><td>-</td><td>-</td><td>X</td><td></td><td></td><td></td></tr><tr><td>2</td><td>100</td><td>1.1</td><td>100</td><td>X</td><td></td><td></td><td></td></tr><tr><td>3</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></tr><tr><td>4</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></tr></tbody></table>			FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY				FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV	1	-	-	-	X				2	100	1.1	100	X				3								4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY																																													
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV																																										
1	-	-	-	X																																													
2	100	1.1	100	X																																													
3																																																	
4																																																	
FAILURE DETECTION METHODS 1-2 None, remotely 1-2 On-site: no lights, stored data or convenience outlet power for troubleshooting/repair equipment. 3 4																																																	
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) Portable source of power required to effect troubleshooting/repair operations. Reset circuit breaker or replace transformer as required.																																																	
NAME G. TRUSK/H. ROTH DATE 8/17/78																																																	
OPERATING MODES A SHUTDOWN D TRANSITION TO STANDBY G OPERATE B TRANSITION TO WARM UP E STANDBY H TRANSITION TO FEATHER C WARM UP F TRANSITION TO OPERATE I FEATHER																																																	

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT BATTERY			PAGE 169 FMEA NO 7.6.1.6.1	
FUNCTION OF COMPONENT PROVIDES UNINTERRUPTIBLE POWER (DC) WHEN POWER FROM OTHER SOURCES IS NOT AVAILABLE. SUPPLIES THE ELECTRICAL POWER SYSTEM PROTECTIVE RELAYS AND PORTIONS OF THE CONTROL SYSTEM.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Discharged: WTS shuts down						A11	
2 Overcharged/Overheated. DC output voltage too high						A11	
3 Under temperature: DC output voltage is too low would result in WTS shut down.						A11	
4 Battery Internal Fault: Same as FM 1 if many cells are shorted WTS shutdown if open circuited.							
FAILURE FREQUENCY				FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,4	70	11.4	14.3			X	
2	29	11.4	34.5	X			
3	1	11.4	1000			X	
4							
FAILURE DETECTION METHODS							
1 WTS shuts down. On-site trouble shooting							
2 On-site inspection of data.							
3 None until needed, then emergency shut down							
4 Same as FM 1							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
Loss of battery supply 48V power results in WTS failsafe shutdown. Battery monitoring circuit detects open battery line.							
See also FMEA's 6.6.2.10, 6.8.8.4, 7.6.1.6.2 and 7.6.1.76							
				NAME G. TRUSK/H. ROTH		DATE 8/17/8	
OPERATING MODES						Rev. 10/17/8 Rev. -10/25/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		4/3/79	
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER -EPS			COMPONENT BATTERY CHARGER			PAGE 170 FMEA NO 7.6 1.6.2	
FUNCTION OF COMPONENT WHEN ENERGIZED, MAINTAINS THE BATTERY IN A STATE OF FULL CHARGE AND SUPPLIES UNINTERRUPTED POWER (DC).							
FAILURE MODES & EFFECTS							
1 Output remains high (not regulating properly): Battery overcharges					APPLICABLE OPERATING MODES		
DC voltage is high.					All		
2 Output low (not regulating properly): DC voltage is low and battery is undercharged.					All		
3 No output. battery will be discharged, WTS will shut down.					All		
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	25	2.3	200	X			
2	25	2.3	200			X	
3	50	2.3	100			X	
4							
FAILURE DETECTION METHODS							
1 None - Requires on-site check							
2 None - requires on-site check (if very low, WTS may shut down).							
3 WTS shutdown (after battery discharges)							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
Periodic inspection							
See also FMEA 7.6.1.6.1							
				NAME G. TRUSK/H. ROTH		DATE 8/17/8	
OPERATING MODES				Rev 10/17/8			
A SHUTDOWN				D TRANSITION TO STANDBY			
B TRANSITION TO WARM-UP				E STANDBY			
C WARM UP				F TRANSITION TO OPERATE			
				G OPERATE			
				H TRANSITION TO FEATHER			
				I FEATHER			
				Rev. 10/25/78			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT BATTERY HEATER			PAGE 171 FMEA NO 7.6.1.6.3	
FUNCTION OF COMPONENT MAINTAINS THE BATTERY TEMPERATURE AT OR ABOVE THE MINIMUM ACCEPTABLE LIMIT WHICH IN TURN MAINTAINS THE BATTERY OUTPUT VOLTAGE. HEATER IS ENERGIZED BY THE ACCESSORY POWER SYSTEM.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Heater is open circuit: Battery may be too cold. (See FMEA 7.6.1.6.1)						All	
2 Heater thermostat is short circuited or stuck shut: battery may overheat and fail.*						All	
3 No accessory power available: Same as #1						All	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	2.3	100	X			
2	25	2.3	200			X	
3	25	2.3	200	X			
4							
FAILURE DETECTION METHODS							
1 & 3 None until battery power is needed.							
2 None until battery is destroyed or maintenance personnel inspect.							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1 & 3 Redundant heaters are provided.							
2 Periodic inspection of battery electrolyte level and case temperature is necessary.							
See also FMEA 7.6.1.6.2							
* Pressure relief is provided to prevent dangerous pressure buildup.							
NAME G. TRUSK/H. ROTH						DATE 8/17/8	
OPERATING MODES						Rev 10/17/8, Rev. 10/25/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT HIGH VOLTAGE OUTPUT BUS.		PAGE 173 FMEA NO 7.6.1.7.2			
FUNCTION OF COMPONENT PROVIDES A POINT OF CONNECTION FOR THE OUTGOING HIGH VOLTAGE POWER CABLES AND A PATH FOR POWER FLOW TO THE UTILITY SIDE OF THE BUS TIE BREAKER.							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 Open circuit: WTS will not enter operate mode or will shut down.				F,G			
2 Short circuit: same as #1				F,G			
3 Grounded conductor: same as #1				F,G			
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.1	200			X	
2	25	1.1	400			X	
3	25	1.1	400			X	
4							
FAILURE DETECTION METHODS							
1-3 WTS is shut down.							
7							
7							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1-3 Control system will not permit "operate" mode if utility power is sensed as not present or diff. prot. will trip BTC.							
See also FMEA 7.2.1.1 through 7.2.2.9.							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES				REV 10/17/78 Rev. 10/25/78			
A - SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT 480 VOLT ACCESSORY POWER CIRCUIT BREAKER PANEL			PAGE 174 FMEA NO 7.6.1.7.3	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF 480 VOLT ACCESSORY POWER WITHIN THE BUS TIE BREAKER.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Open circuit: Loss of individual 480V load function.						ALL	
2 Short circuit. circuit breaker trips then same as No. 1						ALL	
3 Conductor grounded. Same as No. 2						ALL	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY *			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATÄSTROPHIC IV
1	50	1.1	200				
2	25	1.1	400				
3	25	1.1	400				
4							
FAILURE DETECTION METHODS							
1 -3 None, remotely							
2 1-3 Onsite: loss of individual function							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
See FMEA 7.2.2.1 through 7.2.2.9, 6.8.7.1							
						NAME H. ROTH/G. TRUSK	
						DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		Rev 10/17/78	
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER		Rev. 10/25/78	
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS	COMPONENT 115/230 VOLT ACCESSORY POWER CIRCUIT BREAKER PANEL	PAGE 175 FMEA NO 7.6.1.7.4					
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF 115/230 VOLT ACCESSORY POWER WITHIN THE BUS TIE BREAKER							
FAILURE MODES & EFFECTS		APPLICABLE OPERATING MODES					
1 Open circuit: loss of individual 115/230 V load function if feeder to tower.		A11					
2 Short circuit: circuit breaker trips, then same as #1.		A11					
3 Grounded conductor: same as #2.		A11					
4 _____							
FAILURE FREQUENCY			FAILURE SEVERITY *				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.1	200				
2	25	1.1	400				
3	25	1.1	400				
4							
FAILURE DETECTION METHODS							
1 - 3 None, remotely							
✓ 1-3 On-site: loss of individual function							
✗ _____							
4 _____							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
*See individual FMEA sheets. _____ _____ _____ _____ _____ _____							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES						REV 10/17/78 Rev. 10/25/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT UNINTERRUPTABLE POWER CIRCUIT		PAGE 176		FMEA NO 7.6.1.7.5	
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF UNINTERRUPTABLE POWER WITHIN THE BUS TIE BREAKER.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Open circuit: power not available for operating protective relays in BTCU or to tower/nacelle						AI-I	
2 Short circuit: same as No. 1						ALL	
3 Grounded conductor same as No. 1						ALL	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	1.1	200			X	
2	25	1.1	400			X	
3	25	1.1	400			X	
4							
FAILURE DETECTION METHODS							
1 -3 WTS shuts down							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
See FMEA's 6.8.8.4, 7.2.2.8, 7.2.2.9.							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES				Rev 10/17/78 Rev 10/25/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS		COMPONENT CONTROL CIRCUIT		PAGE 177 FMEA NO 7.6.1.7.6			
FUNCTION OF COMPONENT PROVIDES A PATH FOR THE FLOW OF CONTROL SYSTEM COMMANDS AND DATA WITHIN THE BUS TIE BREAKER.							
FAILURE MODES & EFFECTS 1 Open circuit: associated relay will not function, loss of circuit protection; loss of status data. 2 Short circuit: Same as No. 1, or relay functions inadvertently causing WTS shutdown. 3 Grounded conductor: same as No. 1 4				APPLICABLE OPERATING MODES F.G. F.G. F.G.			
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	50	2.3	100			X	
2	25	2.3	200			X	
3	25	2.3	200			X	
4							
FAILURE DETECTION METHODS 1-3 WTS shutdown 2 3 4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) Generator protective circuits will trip the GCB if failure in BTCU jeopardizes the generator. See also FMEA 7.2.3.2.							
				NAME G. TRUSK/H. ROTH		DATE 8/17/78	
OPERATING MODES				Rev 10/17/78			
A SHUTDOWN B TRANSITION TO WARM UP C WARM UP		D TRANSITION TO STANDBY E STANDBY F TRANSITION TO OPERATE		G OPERATE H TRANSITION TO FEATHER I FEATHER			

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM TOWER - EPS			COMPONENT FUSED MANUAL DISCONNECT SWITCH			PAGE 179 FMEA NO 7.6.3	
FUNCTION OF COMPONENT PROVIDES A MEANS OF TOTALLY ELECTRICALLY ISOLATING THE WTS FROM THE UTILITY AND PROVIDES A FAIL-SAFE VISUAL INDICATION THAT THE CIRCUIT IS OPEN.							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 Open circuit: WTS shuts down or cannot start up.						A11	
2 Stuck shut: cannot disconnect WTS from utility.						A11	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1	90	.7	185			X	
2	10	.7	1666	X			
3							
4							
FAILURE DETECTION METHODS							
1 WTS shut down.							
2 Requires manual check.							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
If switch cannot be closed or if it fuses open, WTS will either shut down or will not transition to operate.							
If switch is stuck shut, WTS cannot be disconnected from utility but fused protection is still available. Bus tie contactor and generator circuit breakers continue to function.							
						NAME G. TRUSK/H. ROTH	
						DATE 8/17/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

REV 10/17/78
REV 10/25/78

CONTROL SUBSYSTEM - FAILURE FREQUENCY

Based on the analysis contained in sheets 180-257, there are no catastrophic failure modes that can be caused by a control system failure. Trade studies completed during conceptual design concluded that a single thread system was most cost effective; therefore, no effort has been made to compute failure frequencies for individual signal lines. The cumulative failure rate for the entire control system is three failures per year.

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM (NCV)			COMPONENT POWER FAIL RESTART CKT			PAGE 180 FMEA NO - 7.7.1	
FUNCTION OF COMPONENT ORDERLY SHUT DOWN & RESTART OF COMPUTER DURING POWER INTERRUPTION.							
FAILURE MODES & EFFECTS <u>1 INTERRUPT LINE SHORTS POWER FAIL INTERRUPT ACTIVATES-EMERGENCY SHUT DOWN ACTIVATED.</u> <u>2 INTERRUPT LINE OPENS-POWER FAIL DOES NOT OPERATE ON POWER INTERRUPT.</u> <u>3 PF STATUS FAILS HIGH-CAUSES INITIALIZATION ON POWER FAIL INTERRUPT</u> <u>4 PF STATUS FAILS LOW-CAUSES POWER FAIL EMERGENCY SHUT DOWN ON START UP.</u>						APPLICABLE OPERATING MODES	
						ALL	
						ALL	
						ALL	
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %		FAILURE RATE $\times 10^{-6}$ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1,4					X		
2,3				X			
3							
4							
FAILURE DETECTION METHODS							
1 SYSTEM WILL NOT RESTART; POWER INDICATION MANUAL CONTROL BOX BLINKS.							
2 ERATIC OPERATION							
3 ERATIC OPERATION							
4 SYSTEM WILL NOT START							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
NAME J. HUTTON						DATE 8/11/78	
Rev 10/25/78							
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM (NCV)			COMPONENT INTERRUPT LOGIC			PAGE 182 FMEA NO 7.7.3	
FUNCTION OF COMPONENT PROVIDES CYCLING & SEQUENCING OF COMPUTER FUNCTIONS							
FAILURE MODES & EFFECTS 1 1/10 SEC INT PULSE FAILS-COMPUTER STOPS UPDATING DATA INPUTS & CONTROL OUTPUTS						APPLICABLE OPERATING MODES ALL	
2 1/10 SEC INT PULSE CDT PARTIAL FAILURE SHORTENING CONTROL CYCLE.						ALL	
3 IAB INTERRUPTS FAIL-ANALOG DATA INPUT STOPS						ALL	
4 SIO INTERRUPTS FAIL-CRT SERVICING STOPS						ALL	
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3						X	
4				X			
FAILURE DETECTION METHODS							
1 CRT & SYSTEM DOES NOT RESPOND TO CHANGES							
2 FAULT FLAG SHOWS INCOMPLETE CONTROL CYCLE.							
3 FAULT FLAG SHOWS INCOMPLETE CONTROL CYCLE.							
4 CRT DOES NOT RESPOND TO CHANGES.							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
						NAME J. HUTTON	
						DATE 8/11/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM (NCV)		COMPONENT SERIAL I/O CKTS.		PAGE 184 FMEA NO 7.7.5		
FUNCTION OF COMPONENT PROVIDES INTERFACE BETWEEN COMPUTER AND CRT TERMINALS.						
FAILURE MODES & EFFECTS 1 INTERMITTENT FAULTS AND NOISE-CRT DISPLAY WILL BE INCORRECT-CONTROL WILL BE INCORRECT.				APPLICABLE OPERATING MODES ALL		
2 HARD FAILURE-CRT DISPLAY AND CONTROL INOPERATIVE.				ALL		
3						
4						
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III
1				X		
2				X		
3						
4						
FAILURE DETECTION METHODS						
1 DISPLAY ERRATIC						
2 DISPLAY DOES NOT WORK						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)						
				NAME J. HUTTON		DATE 8/11/78
OPERATING MODES						Rev 10/25/78
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT RPM SIGNAL			PAGE 186 FMEA NO 7.7.7	
FUNCTION OF COMPONENT PROVIDES RPM DATA FOR THE CONTROL SYSTEM FROM THE LOW SPEED SHAFT.							
FAILURE MODES & EFFECTS <u>1</u> SHORT CIRCUIT TO GROUND; CONTROL WILL INDICATE "0" RPM RESULTING IN WTS SHUT DOWN <u>2</u> SHORT CIRCUIT TO VOLTAGE; CONTROL WILL INDICATE MAX RPM RESULTING IN WTS SHUT DOWN. <u>3</u> OPEN CIRCUIT; CONTROL INDICATES "0" RPM RESULTING IN WTS SHUT DOWN <u>4</u>						APPLICABLE OPERATING MODES	
						ALL, EXCEPT STANDBY	
						ALL	
						ALL, EXCEPT STANDBY	
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %		FAILURE RATE x 10 ⁻⁶ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1					X		
2					X		
3					X		
4							
FAILURE DETECTION METHODS							
1 CONTROL WILL BE IN LOCKOUT MODE							
2 CONTROL WILL BE IN LOCKOUT MODE							
3 CONTROL WILL BE IN LOCKOUT MODE							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) FAIL SAFE ALSO MONITORS HIGH RPM.							
					NAME R.K. HILDAHL		DATE 8/11/78
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT #1 VIBRATION SIGNAL			PAGE 187 FMEA NO 7.7.8	
FUNCTION OF COMPONENT <u>PROVIDES ALARM SIGNAL FOR EXCESSIVE VIBRATION MONITORED ON LOW SPEED SHAFT FRONT BEARING.</u>							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT, PRIMARY CONTROL WILL NOT MONITOR. REDUNDANTLY SENSORED BY FAIL SAFE SYSTEM.						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT, PRIMARY CONTROL WILL SHUT DOWN WTS						ALL	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATÄSTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 REQUIRES INSPECTION							
2 CONTROL WILL BE IN LOCKOUT MODE.							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) FAIL SAFE SYSTEM PROVIDES REDUNDANCY							
				NAME R. K. HILDAHL		DATE 8/11/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT BEARING OVERTEMPERATURE # 2			PAGE 190 FMEA NO 7.7.11	
FUNCTION OF COMPONENT PROVIDES OVER TEMPERATURE ALARM SIGNAL FOR LOW SPEED SHAFT REAR (NEAR GEAR BOX) BEARING.							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; PRIMARY CONTROL WILL NOT MONITOR						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT; PRIMARY CONTROL WILL SHUT DOWN WTS						ALL	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 REQUIRES INSPECTION							
2 CONTROL WILL BE IN LOCKOUT MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
1. FAIL SAFE SYSTEM PROVIDES REDUNDANCY							
NAME R. K. HILDAHL						DATE 8/11/78	
Rev 10/25/78							
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT TEETER BRAKE UNLOCK COMMAND SIGNAL			PAGE 192 FMEA NO 7.7.13	
FUNCTION OF COMPONENT PROVIDES COMMAND TO UNLOCK TEETER BRAKE							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT COMMAND TEETER BRAKE TO UNLOCK 2 OPEN CIRCUIT; CONTROL WILL NOT COMMAND TEETER BRAKE TO UNLOCK 3 4						APPLICABLE OPERATING MODES ALL	
						ALL	
						ALL	
						ALL	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 REQUIRES INSPECTION							
2 REQUIRES INSPECTION							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
						NAME R. K. HILDAHL	
						DATE 8/11/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM <u>CONTROL SUB SYSTEM</u>			COMPONENT <u>EMERGENCY ACCUMULATOR COMMAND SIGNAL</u>			PAGE <u>193</u> FMEA NO <u>7.7.14</u>	
FUNCTION OF COMPONENT <u>COMMANDS EMERGENCY ACCUMULATOR TO FEATHER ROTOR BLADES & SIGNALS FAIL SAFE CKT THAT CONTROL SYSTEM HAS SHUT DOWN SYSTEM</u>							
FAILURE MODES & EFFECTS <u>1 SHORT CIRCUIT; CONTROL WILL ACTIVATE EMERGENCY ACCUMULATOR.</u>						APPLICABLE OPERATING MODES	
						ALL	
<u>2 OPEN CIRCUIT; CONTROL WILL ACTIVATE EMERGENCY ACCUMULATOR.</u>						ALL	
<u>3 SHORT TO VOLTAGE: CONTROL WILL NOT ACTIVATE EMERGENCY ACCUMULATOR</u>						ALL	
<u>4</u>							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1					X		
2					X		
3					X		
4							
FAILURE DETECTION METHODS							
<u>1 CONTROL IN LOCKOUT MODE.</u>							
<u>2 CONTROL IN LOCKOUT MODE.</u>							
<u>3 FAIL SAFE DETECTS INVALID SEQUENCE</u>							
<u>4</u>							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
<u>FAIL SAFE SYSTEM PROVIDES REDUNDANCY.</u>							
				NAME <u>R. K. HILDAHL</u>		DATE <u>8/11/78</u>	
OPERATING MODES				Rev 11/1/78			
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT PITCH HYD PUMP ON COMMAND SIGNAL			PAGE 194 FMEA NO 7.7.15	
FUNCTION OF COMPONENT PROVIDES COMMAND TO START HYDRAULIC PUMP.							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT COMMAND PUMP ON AND CONTROL WILL MAINTAIN WTS SHUT DOWN						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT; CONTROL WILL NOT COMMAND PUMP ON, AND CONTROL WILL MAINTAIN WTS SHUT DOWN						ALL	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO.	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							

FAILURE DETECTION METHODS							
1 CONTROL WILL BE IN LOCKOUT MODE							
2 CONTROL WILL BE IN LOCKOUT MODE							
3							
4							

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

		NAME R. K. HILDAHL	DATE 8/11/78
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OPERATING MODES

A SHUTDOWN
 B TRANSITION TO WARM UP
 C WARM UP

D TRANSITION TO STANDBY
 E STANDBY
 F TRANSITION TO OPERATE

G OPERATE
 H TRANSITION TO FEATHER
 I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT PITCH HYD PUMP OFF SIGNAL			PAGE 195 FMEA NO 7.7.16	
FUNCTION OF COMPONENT PROVIDES COMMAND TO TURN OFF HYDRAULIC PUMP.							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT COMMAND PUMP OFF						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT; CONTROL WILL NOT COMMAND PUMP OFF						ALL	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1					X		
2					X		
3							
4							
FAILURE DETECTION METHODS							
1 CONTROL WILL BE IN LOCKOUT, HYD. PUMP RUNNING							
2 CONTROL WILL BE IN LOCKOUT, HYD. PUMP RUNNING.							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME R. K. HILDAHL		DATE 8/11/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM		COMPONENT #1 PITCH SERVO COMMAND SIGNAL		PAGE 196 FMEA NO 7.7.17		
FUNCTION OF COMPONENT <u>PROVIDES COMMANDS TO TIP ACTUATOR THAT CONTROLS BLADE TIP. #1</u>						
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES		
1 SHORT CIRCUIT; CONTROL WILL NOT COMMAND ACUATOR, CONTROL SYSTEM WILL SHUT DOWN WTS				ALL		
2 OPEN CIRCUIT; CONTROL WILL NOT COMMAND ACTUATOR; CONTROL SYSTEM WILL SHUTDOWN WTS				ALL		
3 INCORRECT SIGNAL COMMANDING FULL POWER						
4 INCORRECT SIGNAL COMMANDING FEATHER POSITION						
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III
1					X	
2					X	
3					X	
4					X	
FAILURE DETECTION METHODS						
1 CONTROL WILL BE IN LOCKOUT MODE						
2 CONTROL WILL BE IN LOCKOUT MODE						
3 WTS SHUTDOWN						
4 WTS SHUTDOWN						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 						
				NAME R. K. HILDAHL	DATE 8/11/78	
OPERATING MODES						
A SHUTDOWN		D TRANSITION TO STANDBY		G - OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM	COMPONENT #2 PITCH SERVO COMMAND SIGNAL	PAGE 197 FMEA NO 7.7.18					
FUNCTION OF COMPONENT PROVIDES COMMANDS TO TIP ACTUATOR THAT CONTROLS BLADE TIP #2							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT COMMAND ACTUATOR; CONTROL SYSTEM WILL SHUT DOWN WTS 2 OPEN CIRCUIT; CONTROL WILL NOT COMMAND ACTUATOR, CONTROL SYSTEM WILL SHUT DOWN WTS 3 INCORRECT SIGNAL COMMANDING FULL POWER 4 INCORRECT SIGNAL COMMANDING FEATHER POSITION		APPLICABLE OPERATING MODES ALL ALL					
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3						X	
4						X	
FAILURE DETECTION METHODS 1 CONTROL WILL BE IN LOCKOUT MODE 2 CONTROL WILL BE IN LOCKOUT MODE 3 WTS SHUTDOWN 4 WTS SHUTDOWN							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 							
				NAME R. K. HILDAHL		DATE 8/11/78 Rev 10/25/78	
OPERATING MODES A SHUTDOWN D TRANSITION TO STANDBY G OPERATE B TRANSITION TO WARM UP E STANDBY H TRANSITION TO FEATHER C WARM UP F TRANSITION TO OPERATE I FEATHER							

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM		COMPONENT #1 BLADE PITCH POSITION SIGNAL		PAGE 198 FMEA NO 7.7.19		
FUNCTION OF COMPONENT PROVIDES POSITION STATUS FOR ONE TIP BLADE.						
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES		
1 ONE OR MORE SHORT CIRCUITS; CONTROL WILL NOT POSITION TIPS TOGETHER; WTS WILL SHUT DOWN				ALL		
2 ONE OR MORE OPEN CIRCUITS; CONTROL WILL NOT POSITION TIPS TOGETHER; WTS WILL SHUT DOWN				ALL		
3 COMBINATION OF SHORT & OPEN CIRCUITS; CONTROL WILL NOT POSITION TIPS TOGETHER. WTS WILL SHUT DOWN				ALL		
4						
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III
1					X	
2					X	
3					X	
4						
FAILURE DETECTION METHODS CONTROL TESTS POSITION IN STANDBY MODE.						
1 BLADE TIPS NOT POSITIONED THE SAME, POSSIBLE CONTROL IN LOCKOUT MODE						
2 SAME AS 1.						
3 SAME AS 1.						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) SHUT DOWN WILL OCCUR WHEN THE POSITION FEEDBACK FROM EACH TIP DIFFERS.						
				NAME R. K. HILDAHL		DATE 8/11/78
OPERATING MODES						
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM		COMPONENT #2 BLADE PITCH POSITION SIGNAL		PAGE 199			
FMEA NO 7.7.20							
FUNCTION OF COMPONENT PROVIDES POSITION STATUS FOR ONE TIP BLADE.							
FAILURE MODES & EFFECTS				APPLICABLE OPERATING MODES			
1 ONE OR MORE SHORT CIRCUITS; CONTROL WILL NOT POSITION TIPS TOGETHER. WTS WILL SHUT DOWN				ALL			
2 ONE OR MORE OPEN CIRCUITS; CONTROL WILL NOT POSITION TIPS TOGETHER. WTS WILL SHUT DOWN				ALL			
3 COMBINATION OF SHORT AND OPEN CIRCUITS; CONTROL WILL NOT POSITION TIPS TOGETHER; WTS WILL SHUT DOWN				ALL			
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3						X	
4							
FAILURE DETECTION METHODS CONTROL TESTS POSITION IN STANDBY MODE.							
1 BLADE TIPS NOT POSITIONED THE SAME, POSSIBLE CONTROL IN LOCKOUT MODE.							
2 SAME AS 1.							
3 SAME AS 1.							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 							
				NAME R. K. HILDAHL		DATE 8/11/78	
Rev 10/25/78							
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT BLADE LOCKED #1 SIGNAL			PAGE 200 FMEA NO 7.7.21	
FUNCTION OF COMPONENT PROVIDES STATUS SIGNAL FOR BLADE #1 LOCK							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT MONITOR BLADE LOCK						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT; CONTROL WILL SHUT DOWN WTS						ALL	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 REQUIRES INSPECTION							
2 CONTROL WILL BE IN LOCKOUT MODE.							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
						NAME R. K. HILDAHL	
						DATE 8/11/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM	COMPONENT	PAGE 201 FMEA NO 7.7.22				
CONTROL SUB SYSTEM		PITCH HYD FILTER CLOGGED SIGNAL				
FUNCTION OF COMPONENT PROVIDES STATUS SIGNAL FOR FILTER #1, 2 AND 3						
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT MONITOR		APPLICABLE OPERATING MODES ALL				
2 OPEN CIRCUIT; CONTROL WILL SHUT DOWN WTS		ALL				
3						
4						
FAILURE FREQUENCY		MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1			X			
2					X	
3						
4						
FAILURE DETECTION METHODS						
1 REQUIRES INSPECTION						
2 CONTROL WILL BE IN LOCKOUT						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 						
			NAME R K HTI DAHL			DATE 8/11/78 Rev 10/25/78
OPERATING MODES A SHUTDOWN D TRANSITION TO STANDBY G OPERATE B TRANSITION TO WARM UP E STANDBY H TRANSITION TO FEATHER C WARM UP F TRANSITION TO OPERATE I FEATHER						

MOD-2-Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM	COMPONENT BLADE LOCKED #2 SIGNAL	PAGE 202 FMEA NO 7.7.23					
FUNCTION OF COMPONENT PROVIDES STATUS SIGNAL FOR BLADE #2 LOCK.							
FAILURE MODES & EFFECTS		APPLICABLE OPERATING MODES					
1 SHORTED CONTACT: CONTROL WILL NOT MONITOR BLADE LOCK.		ALL					
2 OPEN CIRCUIT: CONTROL WILL SHUT DOWN WTS.		ALL					
3 SHORT CIRCUIT: CONTROL WILL SHUTDOWN WTS.		ALL					
4 _____							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3						X	
4							
FAILURE DETECTION METHODS							
1 REQUIRES INSPECTION.							
2 CONTROL WILL BE IN LOCKOUT MODE.							
3 CONTROL WILL BE IN LOCKOUT MODE.							
4 _____							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME D. Kenkman		DATE 11/1/78	
OPERATING MODES							
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE	H - TRANSITION TO FEATHER	I - FEATHER	B TRANSITION TO WARM-UP	E STANDBY	F TRANSITION TO OPERATE
C WARM UP							

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM		COMPONENT PITCH HYD OIL TEMP HIGH SIGNAL		PAGE 203 FMEA NO 7.7.24			
FUNCTION OF COMPONENT <u>PROVIDES INDICATION OF PITCH HYD OIL TEMP WHEN HIGH</u>							
FAILURE MODES & EFFECTS 1 <u>SHORT CIRCUIT; CONTROL WILL NOT MONITOR</u>				APPLICABLE OPERATING MODES ALL			
2 <u>OPEN CIRCUIT; CONTROL WILL SHUT DOWN WTS</u>				ALL			
3 _____							
4 _____							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 <u>REQUIRES INSPECTION</u>							
2 <u>CONTROL WILL BE IN LOCKOUT MODE.</u>							
3 _____							
4 _____							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) _____ _____ _____ _____ _____ _____ _____ _____ _____ _____							
				NAME R. K. HILDAHL	DATE 8/11/78		
OPERATING MODES A SHUTDOWN D TRANSITION TO STANDBY G OPERATE B TRANSITION TO WARM UP E STANDBY H TRANSITION TO FEATHER C WARM UP F TRANSITION TO OPERATE I FEATHER							

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM		COMPONENT PITCH ACCUMULATORS PRECHARGE LOW		PAGE 205 FMEA NO 7.7.26			
FUNCTION OF COMPONENT <u>PROVIDES STATUS SIGNAL FOR THE EMERGENCY AND OPERATIONAL ACCUMULATOR PRECHARGES.</u>							
FAILURE MODES & EFFECTS 1 <u>SHORT CIRCUIT; CONTROL WILL NOT MONITOR</u>				APPLICABLE OPERATING MODES ALL			
2 <u>OPEN CIRCUIT; CONTROL WILL SHUT DOWN WTS</u>				ALL			
3 _____				.			
4 _____							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 <u>CONTROL WILL TEST DURING STANDBY AND WILL GO INTO LOCKOUT MODE</u>							
2 <u>CONTROL WILL BE IN LOCKOUT MODE</u>							
3 _____							
4 _____							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) <u>FAIL SAFE SYSTEM PROVIDES REDUNDANCY</u> _____ _____ _____ _____ _____ _____ _____ _____							
				NAME R. K. HILDAHL	DATE 8/11/78		
OPERATING MODES							
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE					
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER					
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT PITCH HYD OIL LEVEL LOW SIGNAL			PAGE 206 FMEA NO 7.7.27	
FUNCTION OF COMPONENT WARNS CONTROL SYSTEM ON LOW OIL LEVEL							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT MONITOR						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT; CONTROL WILL SHUT DOWN WTS						ALL	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							

FAILURE DETECTION METHODS							
1 REQUIRES INSPECTION							
2 CONTROL WILL BE IN LOCKOUT MODE							
3							
4							

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

NAME R. K. HILDAHL		DATE 8/11/78
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OPERATING MODES

A SHUTDOWN
 B TRANSITION TO WARM UP
 C WARM UP

D TRANSITION TO STANDBY
 E STANDBY
 F TRANSITION TO OPERATE

G OPERATE
 H TRANSITION TO FEATHER
 I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT GEAR BOX OIL TEMP. HIGH SIGNAL			PAGE 207 FMEA NO 7.7.28	
FUNCTION OF COMPONENT PROVIDES ALARM SIGNAL FOR GEAR BOX OIL TEMPERATURE							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT MONITOR						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT; CONTROL WILL SHUT DOWN WTS						ALL	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							

FAILURE DETECTION METHODS

1 REQUIRES PERIODIC INSPECTION

2 CONTROL WILL BE IN LOCKOUT MODE

3

4

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

NAME D. KENKMAN		DATE 8/11/78
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OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

Rev 10/25/78

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT GEAR BOX OIL PRESSURE LOW SIGNAL			PAGE 208 FMEA NO 7.7.29	
FUNCTION OF COMPONENT PROVIDES ALARM SIGNAL FOR LOW OIL PRESSURE							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT MONITOR THIS SIGNAL IF WTS IS OPERATING-WILL NOT START IF IN STANDBY 2 OPEN CIRCUIT; CONTROL WILL SHUT DOWN WTS 3 4						APPLICABLE OPERATING MODES ALL ALL	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1					X		
2					X		
3							
4							
FAILURE DETECTION METHODS							
1 CONTROL WILL GO INTO LOCK OUT MODE							
2 CONTROL WILL BE IN LOCK OUT MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
FAIL SAFE SYSTEM PROVIDES REDUNDANCY							
NAME D. KENKMAN						DATE 8/11/78	
OPERATING MODES						Rev 10/25/78	
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM	COMPONENT GEAR BOX OIL LEVEL LOW SIGNAL	PAGE 209 FMEA NO 7.7 30				
FUNCTION OF COMPONENT <u>PROVIDES ALARM SIGNAL FOR LOW OIL LEVEL</u>						
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT MONITOR THIS SENSOR		APPLICABLE OPERATING MODES ALL				
2 OPEN CIRCUIT, CONTROL WILL SHUT DOWN WTS		ALL				
3						
4						
FAILURE FREQUENCY		FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ % FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1			X			
2					X	
3						
4						
FAILURE DETECTION METHODS						
1 REQUIRES PERIODIC INSPECTION						
2 CONTROL WILL BE IN LOCKOUT MODE						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 						
				NAME D. KENKMAN	DATE 8/11/78	
OPERATING MODES				Rev 10/25/78		
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE				
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER				
C WARM UP	F TRANSITION TO OPERATE	I FEATHER				

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM	COMPONENT GEAR BOX OIL TEMP. LOW	PAGE 210 FMEA NO 7.7.31					
FUNCTION OF COMPONENT <u>PROVIDES ALARM SIGNAL IF OIL TEMP. IS TOO LOW TO OPERATE</u>							
FAILURE MODES & EFFECTS <u>1 SHORT CIRCUIT; CONTROL WILL NOT MONITOR THIS SENSOR</u>		APPLICABLE OPERATING MODES ALL					
<u>2 OPEN CIRCUIT; CONTROL WILL SHUT DOWN WTS</u>		ALL					
<u>3</u>							
<u>4</u>							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
<u>1 REQUIRES PERIODIC INSPECTION</u>							
<u>2 CONTROL WILL BE IN LOCKOUT MODE</u>							
<u>3</u>							
<u>4</u>							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 							
				NAME D. KENKMAN		DATE 8/11/78	
OPERATING MODES							
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE					
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER					
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

[illegible]

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT GEAR BOX OIL PUMP ON COMMAND			PAGE 213 FMEA NO 7.7.34	
FUNCTION OF COMPONENT PROVIDES SIGNAL TO START GEAR BOX OIL PUMP							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT TURN OIL PUMP ON						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT; CONTROL WILL NOT TURN OIL PUMP ON						ALL	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							

FAILURE DETECTION METHODS							
1 CONTROL WILL GO INTO LOCKOUT MODE							
2 CONTROL WILL GO INTO LOCKOUT MODE							
3							
4							

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

NAME D. KENKMAN		DATE 8/11/78
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OPERATING MODES

A SHUTDOWN
 B TRANSITION TO WARM UP
 C WARM UP

D TRANSITION TO STANDBY
 E STANDBY
 F TRANSITION TO OPERATE

G OPERATE
 H TRANSITION TO FEATHER
 I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB-SYSTEM			COMPONENT GEAR BOX OIL PUMP OFF COMMAND			PAGE 214 FMEA NO 7.7.35	
FUNCTION OF COMPONENT PROVIDES SIGNAL TO TURN OFF GEAR BOX OIL PUMP							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL NOT TURN PUMP OFF 2 OPEN CIRCUIT; CONTROL WILL NOT TURN PUMP OFF 3 4						APPLICABLE OPERATING MODES	
						ALL	
						ALL	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 CONTROL WILL BE IN LOCKOUT MODE							
2 CONTROL WILL BE IN LOCKOUT MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
NAME D. KENKMAN						DATE 8/11/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT ROTOR BRAKE UNLOCKED SIGNAL			PAGE 217 FMEA NO 7.7.38	
FUNCTION OF COMPONENT INDICATES POSITION OF ROTOR BRAKE							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL ACT AS THOUGH BRAKE IS IN LOCKED POSITION AND WTS WILL GO INTO LOCKOUT						APPLICABLE OPERATING MODES E	
2 OPEN CIRCUIT-CONTROL WILL ACT AS THOUGH BRAKE IS IN UNLOCKED POSITION						ALL	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 CONTROL WILL GO INTO LOCKOUT MODE							
2 CONTROL WILL GO INTO LOCKOUT MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
						NAME D. KENKMAN	
						DATE 8/11/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT UTILITY POWER STATUS SIGNAL			PAGE 220 FMEA NO 7.7.41	
FUNCTION OF COMPONENT PROVIDES UTILITY POWER STATUS TO CONTROL SYSTEM							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL LOSE MONITORING CAPABILITY 2 OPEN CIRCUIT; CONTROL WILL SHUT DOWN WTS 3 4						APPLICABLE OPERATING MODES	
						ALL	
						ALL	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 INSPECTION REQUIRED							
2 WTS WILL NOT START-IN LOCKOUT MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
						NAME D. KENKMAN	
						DATE 8/10/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT BUS TIE CONTACTOR OPEN SIGNAL			PAGE 221 FMEA NO 7.7.42	
FUNCTION OF COMPONENT PROVIDES STATUS OF THE UTILITY BUS TIE BREAKER							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL WILL LOSE MONITORING CAPABILITY IF						APPLICABLE OPERATING MODES ALL	
OPERATING						ALL	
2 OPEN CIRCUIT; WTS WILL BE SHUT DOWN						ALL	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							

FAILURE DETECTION METHODS

1 CONTROL WILL GO INTO LOCKOUT MODE AFTER SHUT DOWN

2 CONTROL WILL BE IN LOCKOUT MODE

3

4

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

	NAME D. KENKMAN	DATE 8/10/78
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OPERATING MODES

A SHUTDOWN

B TRANSITION TO WARM UP

C WARM UP

D TRANSITION TO STANDBY

E STANDBY

F TRANSITION TO OPERATE

G OPERATE

H TRANSITION TO FEATHER

I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM		COMPONENT SYNC ENABLE SIGNAL		PAGE 222 FMEA NO 7.7.43			
FUNCTION OF COMPONENT <u>ENABLES THE AUTO SYNCHRONIZER TO SYNCHRONIZE THE WTS TO THE UTILITY NETWORK</u>							
FAILURE MODES & EFFECTS 1 <u>SHORT CIRCUIT; WILL PREVENT-ENABLE</u>				APPLICABLE OPERATING MODES ALL			
2 <u>OPEN CIRCUIT WILL PREVENT ENABLE</u>				F			
3 _____							
4 _____							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 <u>CONTROL WILL BE IN LOCKOUT MODE</u>							
2 <u>CONTROL WILL BE IN LOCKOUT MODE</u>							
3 _____							
4 _____							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) _____ _____ _____ _____ _____ _____ _____ _____ _____							
				NAME DONALD KENKMAN		DATE 8/10/7	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT BUS TIE DISCONNECT COMMAND SIGNAL			PAGE 223 FMEA NO 7.7.44	
FUNCTION OF COMPONENT COMMANDS THE GENERATOR SYSTEM TO DISCONNECT THE GENERATOR OUTPUT FROM THE UTILITY PWR LINE							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; CONTROL SYSTEM WILL NOT CONTROL DISCONNECT; PWR SYSTEM(GENERATOR) WILL CONTROL						APPLICABLE OPERATING MODES B THRU I	
2 OPEN CIRCUIT; DISCONNECT WILL OCCUR AND WTS WILL SHUT DOWN						ALL	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1					X		
2					X		
3							
4							
FAILURE DETECTION METHODS							
1 SYSTEM WILL NOT RECONNECT AND WILL REVERT TO LOCKOUT MODE							
2 SYNCHRONIZATION WILL NOT OCCUR AND WTS WILL REVERT TO LOCKOUT MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME D. KENKMAN		DATE 8/10/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT REMOTE RS 232 SIGNAL			PAGE 224 FMEA NO 7.7.45	
FUNCTION OF COMPONENT PROVIDES REMOTE CONTROL/MONITOR CAPABILITY FOR THE WTS							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT; TERMINAL WILL NOT OPERATE WTS IN MANUAL MODE; NOR DISPLAY DATA						APPLICABLE OPERATING MODES MANUAL	
2 OPEN CIRCUIT-SAME AS ABOVE						MANUAL	
3							
4							

FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2				X			
3							
4							

FAILURE DETECTION METHODS

1 INSPECTION

2 INSPECTION

3

4

FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)

NAME DON KENKMAN		DATE 8/11/78
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OPERATING MODES

A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER
C WARM UP	F TRANSITION TO OPERATE	I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM	COMPONENT LOCAL RS 232 SIGNAL	PAGE 225 FMEA NO 7.7.46					
FUNCTION OF COMPONENT <u>PROVIDES MANUAL CONTROL/MONITOR CAPABILITY AT THE WTS SITE</u>							
FAILURE MODES & EFFECTS <u>1 SHORT CIRCUIT; TERMINAL WILL NOT OPERATE WTS IN MANUAL MODE NOR DISPLAY DATA</u>		APPLICABLE OPERATING MODES					
<u>2 OPEN CIRCUIT; SAME AS 1, ABOVE</u>							
<u>3</u>							
<u>4</u>							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1			X				
2			X				
3							
4							
FAILURE DETECTION METHODS							
<u>1 INSPECTION</u>							
<u>2 INSPECTION</u>							
<u>3</u>							
<u>4</u>							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 							
				NAME D. KENKMAN		DATE 8/14/78	
OPERATING MODES				Rev 10/25/78			
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE	H TRANSITION TO FEATHER	I FEATHER			
B TRANSITION TO WARM UP	E STANDBY	F TRANSITION TO OPERATE					
C WARM UP							

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM	CONTROL SUB SYSTEM	COMPONENT	NCU TEMP. LOW SIGNAL		PAGE	228		
				FMEA NO	7.7.49			
FUNCTION OF COMPONENT								
PROVIDES ALARM SIGNAL WHEN UNDER TEMP. OCCURS IN THE NACELLE CONTROL UNIT. CONTROL SYSTEM WILL WAIT FOR LOSS OF SIGNAL PRIOR TO SYSTEM RESET.								
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES		
1 SHORTED CONTACTS-CONTROL WILL NOT MONITOR						ALL		
2 OPEN CIRCUIT-CONTROL WILL SHUT DOWN WTS						ALL		
3 SHORT TO GROUND-SAME AS 2								
4								
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV	
1				X				
2						X		
3						X		
4								
FAILURE DETECTION METHODS								
1 REQUIRES INSPECTION								
2 /3 CONTROL WILL BE IN WAIT MODE								
3								
4								
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)								
				NAME	D. KENKMAN		DATE	8/10/78
OPERATING MODES								Rev 10/25/78 Rev 11/27/78
A SHUTDOWN	B TRANSITION TO WARM-UP	C WARM UP	D TRANSITION TO STANDBY	E STANDBY	F TRANSITION TO OPERATE	G OPERATE	H TRANSITION TO FEATHER	I FEATHER

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM		COMPONENT YAW ACCUM PRECHARGE LOW SIGNAL		PAGE 229 FMEA NO 7.7.50			
FUNCTION OF COMPONENT							
PROVIDES ALARM SIGNAL FOR LOW ACCUMULATOR PRECHARGE PRESSURE							
FAILURE MODES & EFFECTS					APPLICABLE OPERATING MODES		
1 SHORTED CONTACT; CONTROL WILL NOT MONITOR WHILE WTS IS OPERATING-IF IN STANDBY-WTS WILL NOT START					ALL		
2 OPEN CIRCUIT; CONTROL WILL SHUT DOWN WTS					ALL		
3 SHORT TO GROUND-SAME AS 2							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3						X	
4							
FAILURE DETECTION METHODS							
1 CONTROL WILL MONITOR IN STANDBY MODE FOR "NO" PRESSURE AND GO INTO LOCKOUT MODE							
2 /3 CONTROL WILL BE IN LOCKOUT MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME D. KENKMAN		DATE 8/10/78	
Rev 10/25/78							
OPERATING MODES							
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE					
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER					
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM			COMPONENT		PAGE 231	
CONTROL SUB SYSTEM			YAW OIL PRESS LOW SIGNAL		FMEA NO 7.7.52	
FUNCTION OF COMPONENT						
PROVIDES ALARM SIGNAL FOR LOW HID. OIL PRESSURE						
FAILURE MODES & EFFECTS					APPLICABLE OPERATING MODES	
1 SHORTED CONTACTS; CONTROL WILL NOT MONITOR WHILE WTS IS OPERATING-IF IN STANDBY-WTS WILL NOT START					ALL	
2 OPEN CIRCUIT, CONTROL WILL SHUT DOWN WTS DUE TO THE ALARM					ALL	
3 SHORT TO GROUND-SAME AS 2						
4						
FAILURE FREQUENCY			FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III CATASTROPHIC IV
1					X	
2					X	
3					X	
4						
FAILURE DETECTION METHODS						
1 CONTROL WILL MONITOR IN STANDBY MODE FOR "NO" PRESSURE & GO INTO LOCKOUT MODE						
2 /3 CONTROL WILL BE IN LOCKOUT MODE.						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)						
				NAME	D. KENKMAN	DATE 8/9/78
OPERATING MODES						
A SHUTDOWN			D TRANSITION TO STANDBY			G - OPERATE
B TRANSITION TO WARM UP			E STANDBY			H TRANSITION TO FEATHER
C WARM UP			F TRANSITION TO OPERATE			I FEATHER

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MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT YAW OIL PUMP ON SIGNAL			PAGE 235 FMEA NO 7.7.56	
FUNCTION OF COMPONENT PROVIDES SIGNAL TO TURN ON THE YAW SYSTEMS OIL PUMP							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT WILL PREVENT PUMP TURN ON						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT WILL PREVENT PUMP TURN ON						ALL	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 NACELLE WILL NOT YAW AND CONTROL WILL END UP IN LOCKOUT MODE							
2 SAME AS #1							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
						NAME D. KENKMAN	
						DATE 8/9/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM-UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM	COMPONENT YAW OIL PUMP OFF SIGNAL	PAGE 236 FMEA NO 7.7.57				
FUNCTION OF COMPONENT <u>PROVIDES SIGNAL TO TURN OFF THE YAW SYSTEM OIL PUMP</u>						
FAILURE MODES & EFFECTS 1 <u>SHORT CIRCUIT WILL PREVENT PUMP TURN OFF</u>		APPLICABLE OPERATING MODES ALL				
2 <u>OPEN CIRCUIT WILL PREVENT PUMP TURN OFF</u>		ALL				
3 _____						
4 _____						
FAILURE FREQUENCY		FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ % x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV.
1					X	
2					X	
3						
4						
FAILURE DETECTION METHODS						
1 <u>CONTROL WILL END UP IN LOCKOUT MODE, PUMP RUNNING</u>						
2 <u>SAME AS #1</u>						
3 _____						
4 _____						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) _____ _____ _____ _____ _____ _____ _____ _____ _____						
				NAME D. KENKMAN	DATE 8/9/78	
OPERATING MODES				Rev 10/25/78		
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE				
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER				
C WARM UP	F TRANSITION TO OPERATE	I - FEATHER				

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM	COMPONENT	PAGE 237				
CONTROL SUB SYSTEM	YAW LEFT COMMAND SIGNAL	FMEA NO 7.7 58				
FUNCTION OF COMPONENT COMMANDS THE YAW SYSTEM TO MOVE THE NACELLE IN A LEFT DIRECTION						
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT CAUSES NACELLE TO TRAVEL LEFT IF PRESSURE IS UP		APPLICABLE OPERATING MODES ALL				
2 OPEN CIRCUIT; NACELLE WILL NOT MOVE LEFT AND WHEN REQUIRED, WTS WOULD BE SHUT DOWN		ALL				
3						
4						
FAILURE FREQUENCY		FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ % FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1					X	
2					X	
3						
4						
FAILURE DETECTION METHODS						
1 CONTROL WILL END UP ON LOCKOUT MODE						
2 SAME AS #1						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 						
				NAME D. KENKMAN	DATE 8/9/78	
OPERATING MODES				Rev 10/25/78		
A SHUTDOWN	D TRANSITION TO STANDBY	G OPERATE				
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER				
C WARM UP	F TRANSITION TO OPERATE	I FEATHER				

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT FAIL SAFE YAW HYD. PUMP OFF COMMAND SIGNAL			PAGE 240 FMEA NO 7.7.61	
FUNCTION OF COMPONENT TURNS OFF YAW HYD. POWER DURING A FAIL SAFE SHUT DOWN. 							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT PREVENTS F/S SYSTEM FROM TURNING HYD PUMP OFF.						APPLICABLE OPERATING MODES G	
2 OPEN CIRCUIT: CAUSING FAIL SAFE SYSTEM TO TURN HYD PUMP OFF.						G	
3							
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1			-			X	
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 INSPECTION REQUIRED							
2 WTS IN SHUTDOWN MODE FROM PRESSURE FAILURE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME D. Kenkman		DATE 11/1/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G - OPERATE			
B TRANSITION TO WARM-UP		E. STANDBY		H - TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SYSTEM			COMPONENT NCU TEMPERATURE LOW SIGNAL			PAGE 241 FMEA NO 7.7.6.2.	
FUNCTION OF COMPONENT PROVIDES INHIBIT TO CONTROL ELECTRONICS DURING LOW TEMP. CONDITIONS THROUGH INTERRUPT CONTROL.							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT: CONTROL WILL NOT MONITOR.						APPLICABLE OPERATING MODES	
2 OPEN CIRCUIT: INTERRUPT WILL OCCUR AND CONTROL WILL SHUT DOWN							
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 REQUIRES INSPECTION.							
2 CONTROL SYSTEM WILL BE INHIBITED.							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) FAIL SAFE SYSTEM IS NOT TEMPERATURE DEPENDANT AND WILL CONTROL DANGEROUS CONDITIONS.							
						NAME D. Kenkman	
						DATE 11/1/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT #1 WIND SPEED SIGNAL			PAGE 242 FMEA NO 7:7.63	
FUNCTION OF COMPONENT PROVIDES WIND SPEED DATA FROM #1 SENSOR							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT						ALL	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1					X		
2					X		
3							
4							
FAILURE DETECTION METHODS							
1 WIND SPEED WILL NOT AGREE WITH #2 SENSOR AND WTS WILL BE SHUT DOWN IN LOCKOUT MODE							
2							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME DON KENKMAN		DATE 8/9/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT #1 WIND DIRECTION SIGNAL			PAGE 244 FMEA NO 7.7.65	
FUNCTION OF COMPONENT PROVIDES WIND DIRECTION DATA FROM #1 SENSOR							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT						APPLICABLE OPERATING MODES	
2 OPEN CIRCUIT						ALL	
3 INCORRECT SIGNAL (RESULTING FROM ICING, ETC.)							
4							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 WIND DIRECTION WILL NOT AGREE WITH #2 SENSOR AND WTS WILL BE SHUT DOWN IN LOCKOUT							
2 MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
				NAME DON KENKMAN		DATE 8/9/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM		COMPONENT #2 WIND DIRECTION SIGNAL		PAGE 245 FMEA NO 7.7.66		
FUNCTION OF COMPONENT <u>PROVIDES WIND DIRECTION DATA FROM #2 SENSOR</u>						
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT				APPLICABLE OPERATING MODES ALL		
2 OPEN CIRCUIT				ALL		
3						
4						
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III
1					X	
2					X	
3						
4						
FAILURE DETECTION METHODS						
1 WIND DIRECTION WILL NOT AGREE WITH #1 SENSOR AND WTS WILL BE SHUT DOWN IN LOCKOUT MODE						
2						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 						
				NAME DON KENKMAN		
				DATE 8/9/78		
OPERATING MODES						
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM		COMPONENT FAIL SAFE GENERATOR BEARING OVERTEMPERATURE		PAGE 246 FMEA NO 7.7 67		
FUNCTION OF COMPONENT PROVIDES ALARM FOR GENERATOR BEARING OVERTEMPERATURE.						
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT - CONTROL WILL SHUT DOWN WTS.					APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT - WILL SHUT WTS DOWN.					ALL	
3 SHORTED CONTACT - WILL NOT MONITOR.					ALL	
4						
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III
1					X	
2					X	
3				X		
4						
FAILURE DETECTION METHODS						
1 WTS WILL BE IN LOCKOUT MODE.						
2 WTS WILL BE IN LOCKOUT MODE.						
3 REQUIRES INSPECTION.						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) REDUNDANT TO CONTROL SIGNAL.						
					NAME D. Kenkman	DATE 11/1/78
OPERATING MODES						
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM		COMPONENT FAIL SAFE ENABLE SIGNAL		PAGE 247 FMEA NO 7.7.68			
FUNCTION OF COMPONENT <u>PROVIDES SIGNAL TO CONTROL SYSTEM THAT FAIL SAFE SYSTEM IS OPERATING IN A READY TO OPERATE CONDITION</u>							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT CAUSING CONTROL SYSTEM TO BELIEVE THAT FAIL SAFE SYSTEM IS OPERATING AND CLEAR				APPLICABLE OPERATING MODES ALL			
2 OPEN CIRCUIT CAUSING CONTROL TO SHUT DOWN WTS				ALL			
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 INSPECTION REQUIRED							
2 WTS WILL NOT START & GOES INTO LOCKOUT MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) 							
			NAME D. KENKMAN	DATE 8/9/78			
OPERATING MODES							
A SHUTDOWN	D TRANSITION TO STANDBY	G - OPERATE					
B TRANSITION TO WARM UP	E STANDBY	H TRANSITION TO FEATHER					
C WARM UP	F TRANSITION TO OPERATE	I FEATHER					

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT FAIL SAFE EMERGENCY ACC. PRESSURE LOW SIGNAL			PAGE 248 FMEA NO 7.7.69	
FUNCTION OF COMPONENT <u>PROVIDE A SIGNAL TO THE FAIL SAFE SYSTEM INDICATING THE STATUS OF THE PITCH EMERGENCY ACCUMULATORS ARE WITHIN LIMITS.</u>							
FAILURE MODES & EFFECTS						APPLICABLE OPERATING MODES	
1 <u>SHORT CIRCUIT CAUSING FAIL SAFE TO NOT MONITOR</u>						ALL	
2 <u>OPEN CIRCUIT CAUSING FAIL SAFE TO SHUT DOWN WTS</u>						ALL	
3 _____							
4 _____							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 <u>REQUIRES INSPECTION</u>							
2 <u>WTS WILL GO INTO FAIL SAFE SHUT DOWN MODE</u>							
3 _____							
4 _____							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
<u>REDUNDANT TO CPU CONTROL SYSTEM WILL STILL SHUT DOWN IF THE ACCUMULATORS ARE OUTSIDE OF LIMITS.</u>							
NAME D. KENKMAN						DATE 8/9/78	
Rev 10/25/78							
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G - OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM UP		F TRANSITION TO OPERATE		I FEATHER			

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM	COMPONENT FAIL SAFE PITCH ACCUM SIGNAL	PAGE 249 FMEA NO 7.7.70					
FUNCTION OF COMPONENT <u>ACTIVATES THE EMERGENCY PITCH ACCUMULATOR TO FEATHER THE BLADES</u>							
FAILURE MODES & EFFECTS <u>1 OPEN CIRCUIT CAUSING BLADES TO FEATHER</u>		APPLICABLE OPERATING MODES ALL					
<u>2 SHORT CIRCUIT CAUSING BLADES TO FEATHER</u>		ALL					
<u>3</u>							
<u>4</u>							
FAILURE FREQUENCY			FAILURE SEVERITY				
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR	MEAN TIME BETWEEN FAILURE (YEARS)	MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1						X	
2						X	
3							
4							
FAILURE DETECTION METHODS							
<u>1 WTS WILL SHUT DOWN IN FAIL SAFE SHUT DOWN MODE</u>							
<u>2 WTS WILL SHUT DOWN IN FAIL SAFE SHUT DOWN MODE</u>							
<u>3</u>							
<u>4</u>							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) <u>REDENDANT TO CPU CONTROL</u>							
				NAME D. KENKMAN	DATE 8/9/78		
OPERATING MODES				Rev 10/25/78			
A SHUTDOWN	B TRANSITION TO WARM UP	C WARM UP	D TRANSITION TO STANDBY	E STANDBY	F TRANSITION TO OPERATE	G OPERATE	H TRANSITION TO FEATHER
I FEATHER							

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT FAIL SAFE PITCH HYD. PUMP OFF COMMAND SIGNAL			PAGE 250 FMEA NO 7.7.71	
FUNCTION OF COMPONENT TURNS OFF THE PITCH HYDRAULIC POWER DURING A FAIL SAFE EMERGENCY SHUT DOWN							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT CAUSING FAIL SAFE SYSTEM TO TURN OFF HYDRAULICS. 2 OPEN CIRCUIT CAUSING FAIL SAFE TO TURN PITCH HYDRAULICS OFF & STAY OFF 3 4						APPLICABLE OPERATING MODES	
						ALL	
						ALL	
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 WTS WILL BE IN SHUTDOWN MODE							
2 WTS WILL BE SHUT DOWN IN FAIL SAFE SHUT DOWN MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) REDUNDANT TO CPU CONTROL							
NAME D. KENKMAN						DATE 8/9/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I FEATHER			

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MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT FAIL SAFE BEARING TEMP. #1 AND #2 SIGNAL			PAGE 251 FMEA NO 7.7.72	
FUNCTION OF COMPONENT ALARMS THE FAIL SAFE SYSTEM WHEN EXCESSIVE BEARING TEMPERATURE IS PRESENT IN THE LOW SPEED SHAFT.							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT CAUSING FAIL SAFE TO NOT MONITOR SENSOR						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT CAUSING FAIL SAFE TO SHUT WTS DOWN OR STAY DISABLED						ALL	
3							
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE $\times 10^{-6}$ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2						X	
3							
4							
FAILURE DETECTION METHODS							
1 MANUAL INSPECTION REQUIRED							
2 WTS WILL BE SHUT DOWN IN FAIL SAFE SHUT DOWN MODE							
3							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) REDUNDANT TO CPU CONTROL SO THAT EXCESSIVE BEARING TEMPERATURES WILL BE DETECTED							
						NAME D. KENKMAN	DATE 8/8/78
OPERATING MODES							
A SHUTDOWN			D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM-UP			E STANDBY		H TRANSITION TO FEATHER		
C WARM UP			F TRANSITION TO OPERATE		I FEATHER		

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB-SYSTEM		COMPONENT FAIL SAFE GEAR BOX TEMP. HIGH SIGNAL		PAGE 254 FMEA NO. 7.7.75		
FUNCTION OF COMPONENT ACTIVATES FAIL SAFE SYSTEM WHEN GEAR BOX OIL TEMPERATURE IS HIGH						
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT CAUSING FAIL SAFE TO ACTIVATE AND SHUT DOWN WTS				APPLICABLE OPERATING MODES ALL		
2 OPEN CIRCUIT CAUSING FAIL SAFE TO ACTIVATE AND SHUTDOWN WTS				ALL		
3						
4						
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY		
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III
1				X		
2						
3						
4						
FAILURE DETECTION METHODS						
1 WTS WILL BE STOPPED IN FAIL SAFE SHUT DOWN MODE						
2 INSPECTION WILL BE REQUIRED						
3						
4						
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE) REDUNDANT TO CPU CONTROL.						
				NAME D. KENKMAN		DATE 8/9/78
OPERATING MODES						
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE		
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER		
C WARM UP		F TRANSITION TO OPERATE		I FEATHER		

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

[illegible]

MOD-2 Failure Mode and Effects Analysis

SUBSYSTEM CONTROL SUB SYSTEM			COMPONENT TEST VAN READY SIGNAL			PAGE 258 FMEA NO 7.7.79	
FUNCTION OF COMPONENT PROVIDES CAPABILITY FOR TEST VAN TO SHUT DOWN WTS DURING ALARMS OCCURING UNDER SPECIAL TEST CONDITIONS MONITORED BY THE TEST VAN.							
FAILURE MODES & EFFECTS 1 SHORT CIRCUIT: TO GROUND: CONTROL WILL SHUT DOWN WTS.						APPLICABLE OPERATING MODES ALL	
2 OPEN CIRCUIT: CONTROL WILL SHUT DOWN WTS.						ALL	
3 SHORTED CONTACTS: CONTROL WILL NOT MONITOR TEST VAN READY.						ALL	
4							
FAILURE FREQUENCY			MEAN TIME BETWEEN FAILURE (YEARS)	FAILURE SEVERITY			
FAILURE MODE NO	FAILURE MODE FREQ %	FAILURE RATE x 10 ⁻⁶ PER HOUR		MINIMAL I	MARGINAL II	CRITICAL III	CATASTROPHIC IV
1				X			
2				X			
3				X			
4							
FAILURE DETECTION METHODS							
1 WTS WILL GO INTO LOCKOUT MODE.							
2 WTS WILL GO INTO LOCKOUT MODE.							
3 REQUIRES INSPECTION.							
4							
FAILURE CAUSE AND CORRECTIVE ACTION (IF APPLICABLE)							
NAME D. Kenkman						DATE 11/1/78	
OPERATING MODES							
A SHUTDOWN		D TRANSITION TO STANDBY		G OPERATE			
B TRANSITION TO WARM UP		E STANDBY		H TRANSITION TO FEATHER			
C WARM-UP		F TRANSITION TO OPERATE		I - FEATHER			

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APPENDIX B

Figure 1, MOD-2 Safety System

R

Figure 2, Control System Block Diagram

Figure 3, Electrical Power System Schematic

Figure 4, Hydraulic Schematic, Pitch Control

Figure 5, Hydraulic Schematic, Yaw System

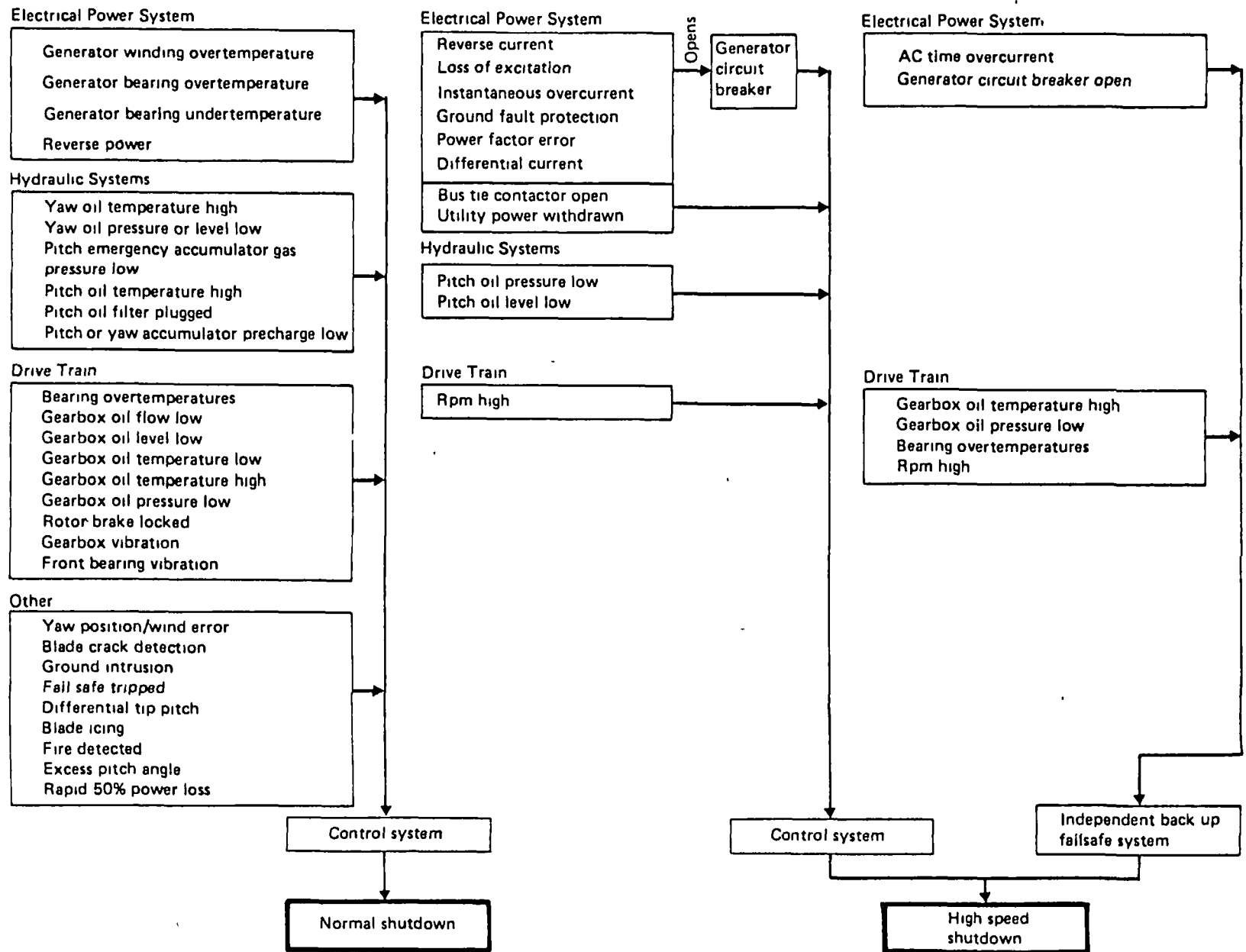


Figure 1, MOD-2 Safety System

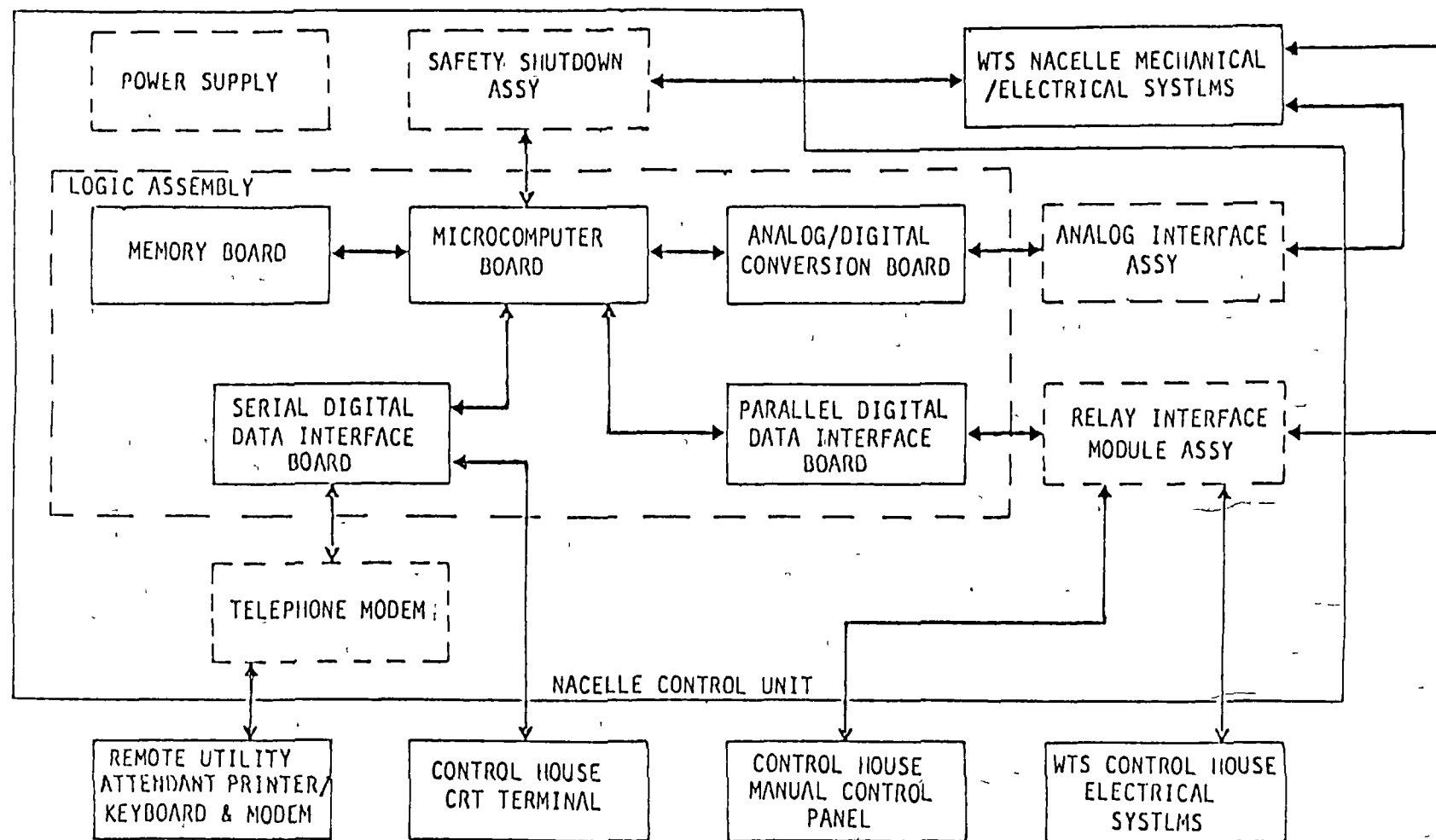


FIGURE 2, CONTROL SYSTEM BLOCK DIAGRAM

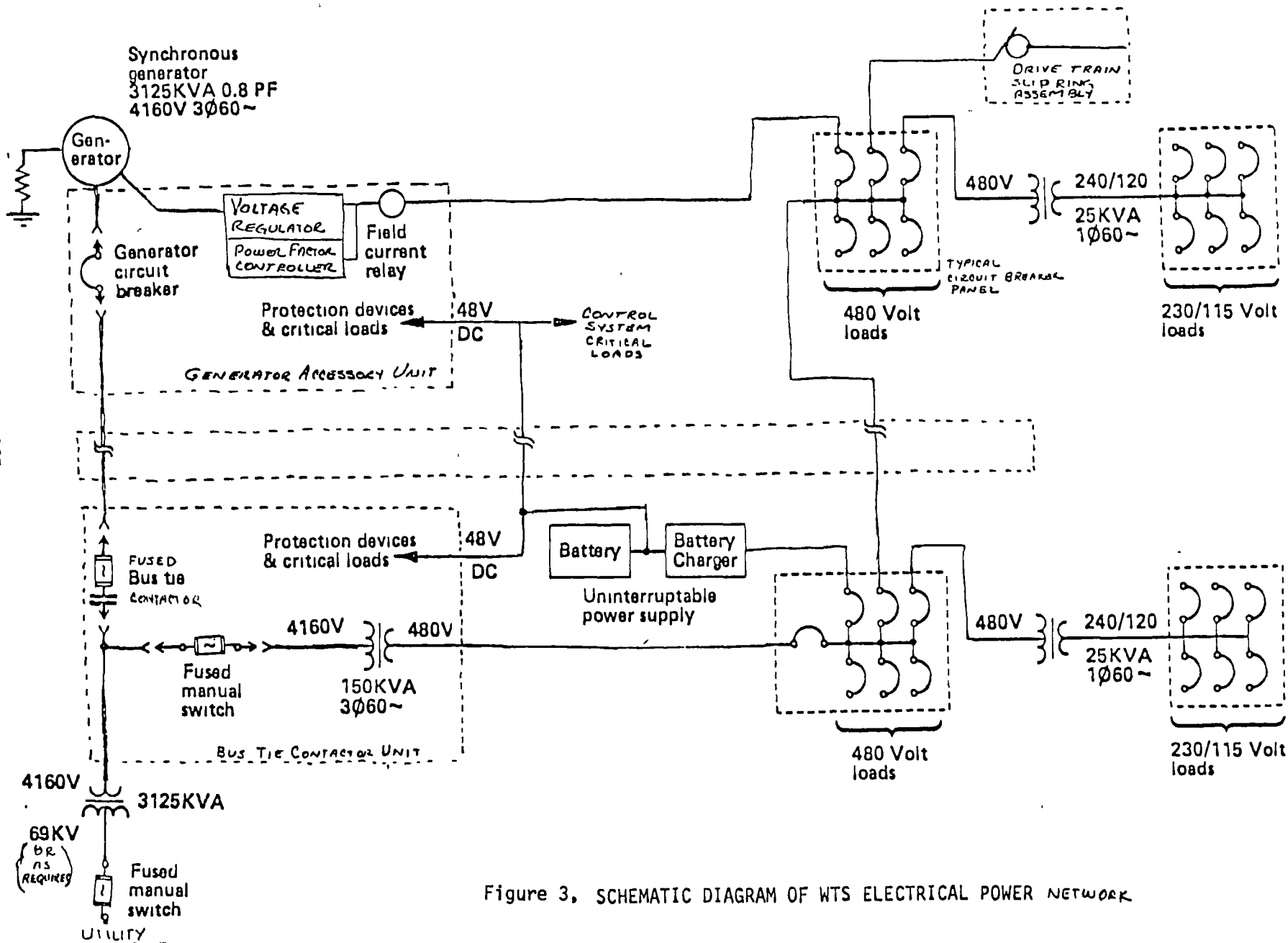
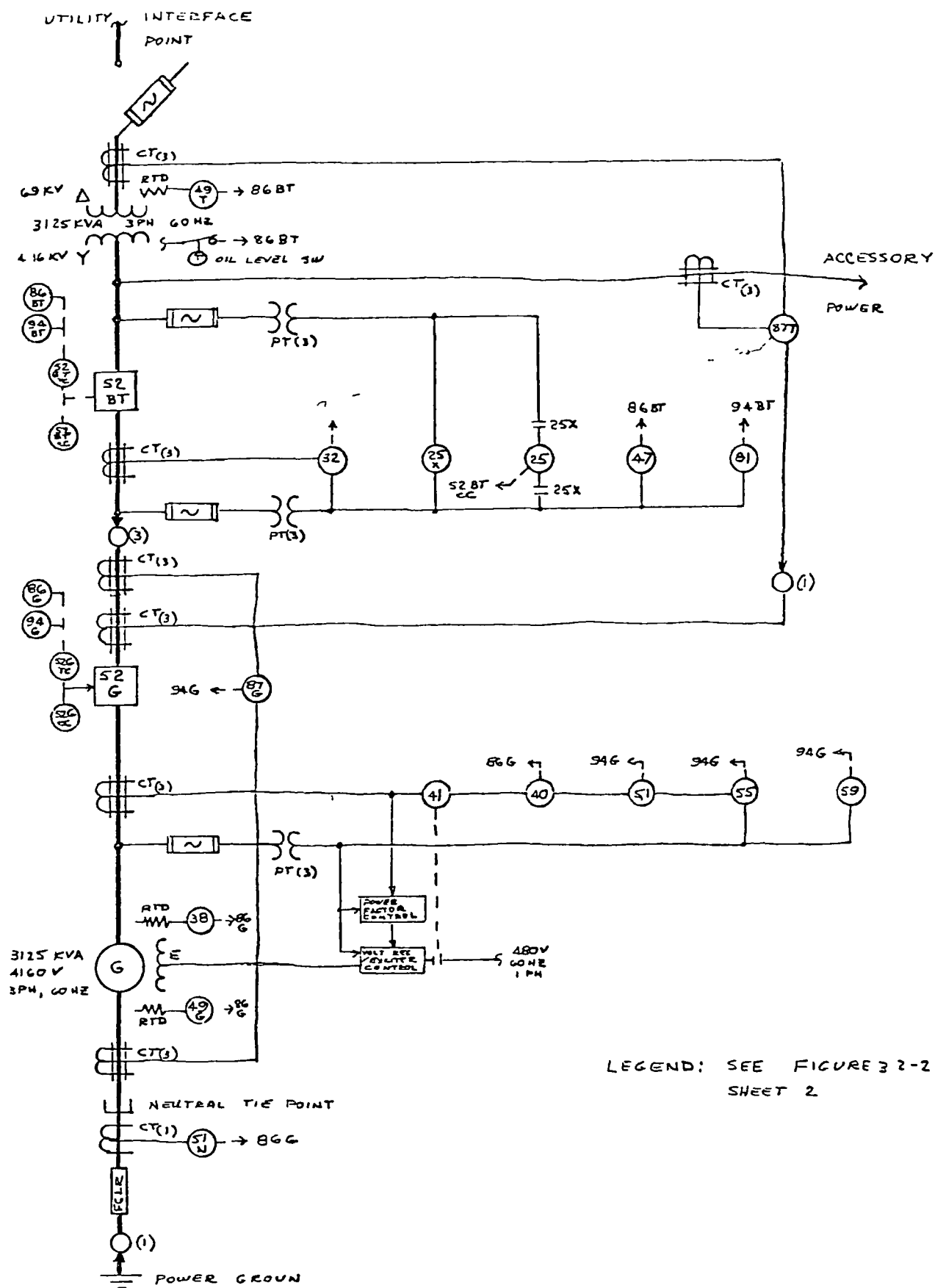


Figure 3. SCHEMATIC DIAGRAM OF WTS ELECTRICAL POWER NETWORK



LEGEND: SEE FIGURE 32-2
SHEET 2

Figure 3, SCHEMATIC DIAGRAM OF WTS ELECTRICAL PROTECTION
(SHEET 1 OF 2) (Con't)

LEGEND:

25	SYNCHRONIZING RELAY
25X	SYNCHRONIZATION CHECK RELAY
32	DIRECTIONAL POWER RELAY
38	GENERATOR BEARING OVER TEMPERATURE RELAY
40	LOSS OF EXCITATION RELAY
41	FIELD CURRENT RELAY
47	PHASE SEQUENCE RELAY
49	THERMAL RELAY
51	AC TIME OVERCURRENT RELAY
52G	GENERATOR CIRCUIT BREAKER
52BT	BUS TIE CONTACTOR
55	POWER FACTOR RELAY
59	OVER VOLTAGE RELAY
51N	GROUND PROTECTION RELAY
81	UNDER FREQUENCY RELAY
86	LOCKING OUT RELAY
87	DIFFERENTIAL PROTECTIVE RELAY
94	TRIPPING RELAY
FELR	FAULT CURRENT LIMITING RESISTOR
(X)	SUBSCRIPT = QUANTITY USED
→○	SLIP RING (ARROW DENOTES BRUSH)
 N 	FUSED MANUAL DISCONNECT DEVICE
BT	BUS TIE
CC	CLOSE COIL
CT	CURRENT TRANSFORMER
E	EXCITER
G	GENERATOR
PT	POTENTIAL TRANSFORMER
RTD	RESISTANCE TEMPERATURE DEVICE
T	TRANSFORMER
TC	TRIP COIL

Figure 3, SCHEMATIC DIAGRAM OF WTS' ELECTRICAL PROTECTION (SHEET 2 OF 2) (Con't)



WIND TURBINE SYSTEM

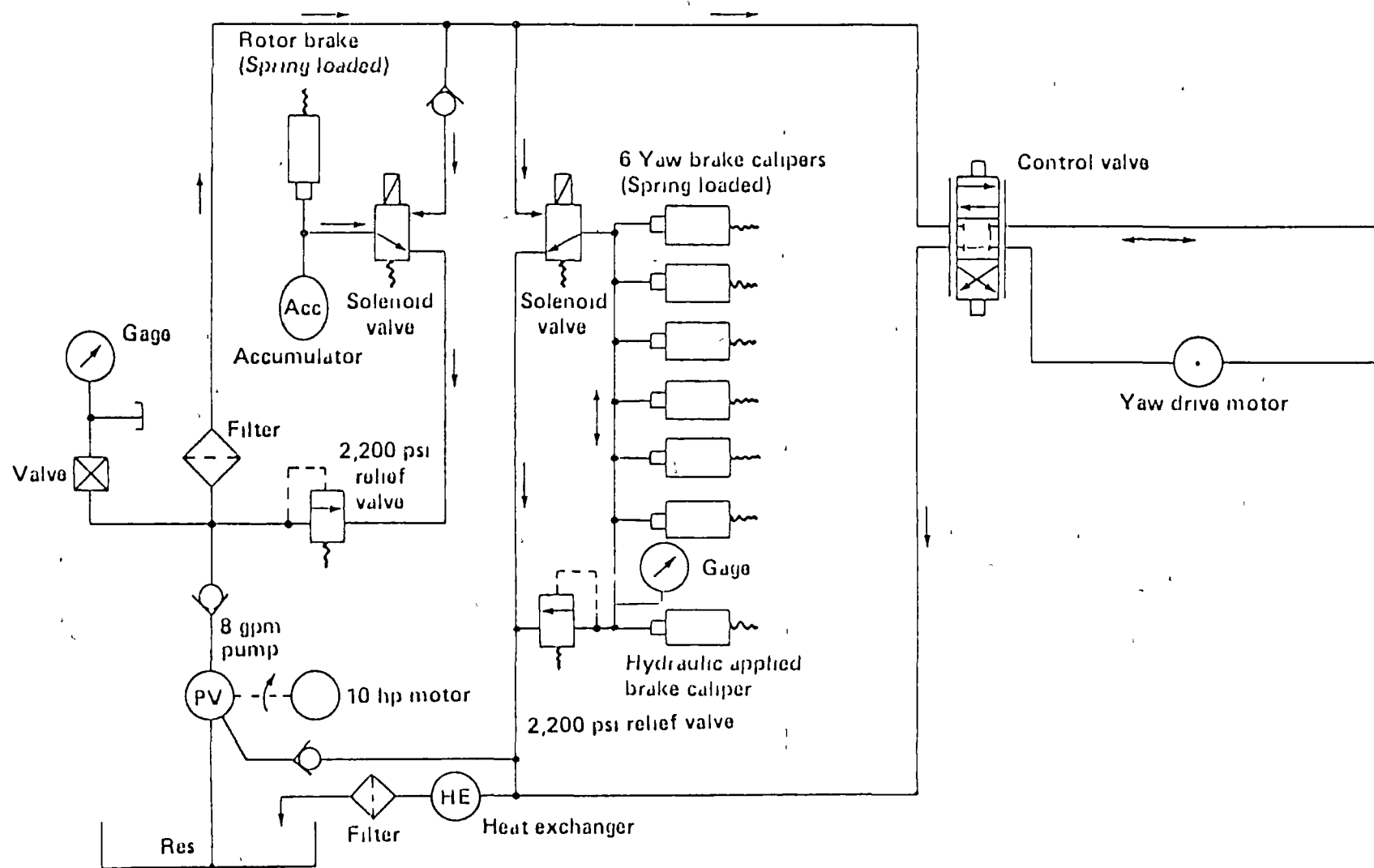


FIGURE 5, HYDRAULIC SCHEMATIC, YAW SYSTEM R

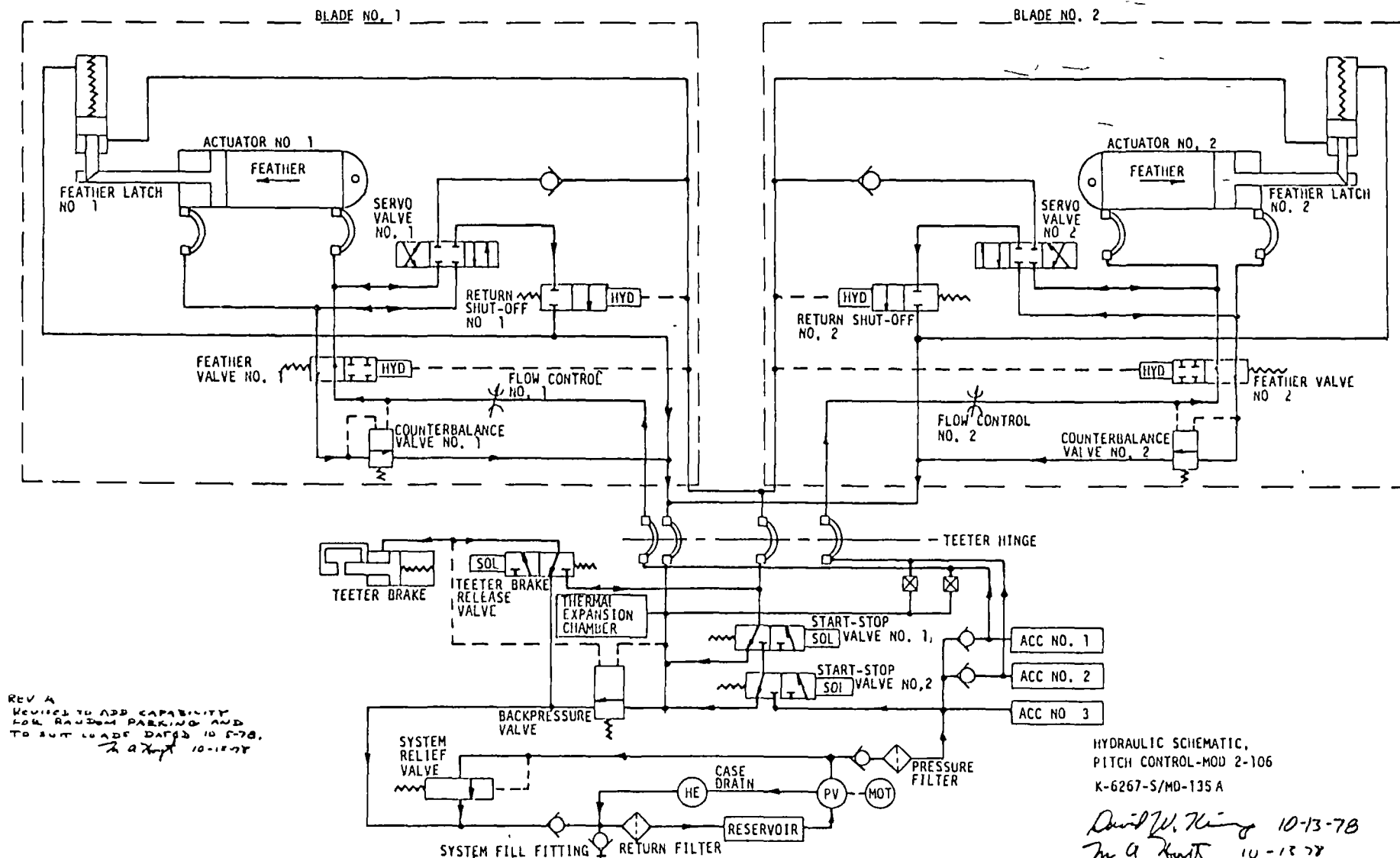


FIGURE 4, HYDRAULIC SCHEMATIC - PITCH B

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APPENDIX C

MEMO K-6265-SS-487, DATED 18 October, 1978, MOD-2 FAILURE MODE AND EFFECTS ANALYSIS

October 18, 1978

K-6265-SS-487

To: W. Wiesner

cc: G. Davison
R. Douglas
J. Erickson
W. Engle
H. Davis

Subject: MOD-2 Failure Mode and Effects Analysis




Reference: K-6266-RL-177, Same Subject, Sept. 14, 1978

The shut down analysis requested in the subject reference has been performed as part of a more comprehensive study on emergency shutdown conditions. The following shutdown analyses were performed:

<u>Condition</u>	<u>Description</u>	<u>Shutdown Procedure</u>
#1	Normal shutdown	Feather at 1° per second, drop load at 125 kw
#2	Emergency shutdown	Feather at 4° per second for 6 seconds and 1° per second thereafter, drop load at 125 kw
#3	Drop load, emergency shutdown	Drop load, feather at 4° per second for 6 second and 1° per second thereafter
#4	Control system malfunction Emergency shutdown	Power exceeds 2X rated, drop load, feather at 4° per second for 6 seconds and 1° per second thereafter
#5	One tip jams Emergency shutdown	One tip jams, feather other tip at 6° per second for 8 seconds and 1° per second thereafter, drop load at 125 kw
#6	Lose one tip Emergency shutdown	Lose one tip, feather other tip at 6° per second for 8 seconds and 1° per second thereafter, drop load at 125 kw.

The maximum rotor overspeeds resulting from the shutdown condition are presented below.

<u>SHUT DOWN CONDITION</u>	<u>MAX ROTOR SPEED (RPM)</u>	
	<u>45 MPH</u>	<u>28 MPH</u>
#1	17.530	17.529
#2	17.516	17.515
#3	18.536	19.771
#4	20.016	17.529
#5	17.519	17.515
#6	17.526	17.526

-  1.5 gust required to drop load
 Unable to drop load with 1.5 gust
 Have not run these cases but rotor speed should not be much different than condition 5 or 6 for 45 mph since load is not disconnected.

Shutdown condition #4 and #5 correspond most closely to the conditions requested in the reference memo. The worst overspeeds result when the load is dropped before initiation of the shutdown procedure (Conditions #3 and #4). The max overspeed, however, does not exceed 15 percent. Under the other shutdown condition, the load is not dropped until the aerodynamic torques are small resulting in negligible overspeeds.

Prepared by: S. A. Shipley
S. A. Shipley

Approved by: J. S. Andrews
J. S. Andrews

APPENDIX D

CABLE RUNS AND SLIP RING ANALYSES

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
Crack Detection- Power Cable to Motor	Crack detection system	Phase-to-phase short or short to ground	Crack detection system dis- abled. "No flow" switches activate resulting in WTS shutdown.
Crack Detection - wires to no flow and flow sensor switches	Crack detection system	Wires short to each other	Switches disabled such that crack would go unnoticed. No serious problem since upon first WTS shutdown NCU would detect a fault and inhibit restart.
Ice detector sig- nal cable	Ice detection system	Wires short together.	Wires short together-causes WTS shutdown. Wires open-detector inoperative-Detector on other blade still operative. Short to ground-damages NCU I/O module when detector activates. Damage not significant
Control system - 48 VDC power sup- ply cable and 208/ 120 VAC power supply	Control system (NCU)	Power line shorts to ground or to negative wire, or an AC short occurs.	Circuit breaker opens result- ing in WTS shutdown. No secondary damage. (Shutdown initiated by remov- ing power to pitch control accumulators resulting in blade tips feathering)

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
Tip Control Cables to each Tip (from low speed shaft)	Rotor - Pitch Control	Worst Case - Short in Cable such that tip is driven hard over.	WTS shuts down via micro-processor command. Tip still under control stops WTS. No significant damage to WTS (Microprocessor detects rapid change in power output and large difference in tip positions).
Power cable to pitch hydraulic motor	Pitch control and teeter brake	Worst case is loss of power to pump motor and subsequent loss of hydraulic pressure	WTS shuts down upon detection on loss of pressure. No damage to WTS.
Pitch hydraulic pump on cable	Pitch control and teeter brake	Short - wire to wire, short to ground	Both failures result in pump shut down and WTS shut down.
Pitch and teeter brake status signals and solenoid command signals	Pitch control and teeter brake	Short such that 115 VAC is applied to all or some lines.	Possible combinations: 1. Start-stop solenoids disabled-WTS shuts down (115 VAC short to ground) 2. Teeter brake disabled, 115 VAC line shorts to ground, WTS shuts down 3. Sensors by-passed. NCU thinks all status signals are o.k. Lack of detection of second fault possible until WTS has a normal shut down. Then it will detect fault and not restart. Probability of shorting to all related sensors is negligible.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
Generator to Generator Accessory Unit - Power Cable	Electrical Power	Short to ground, wire-to- wire shorts	Differential current protec- tion relay causes generator circuit breaker to open in both cases.
Generator to Generator Accessory Unit - Sensor Outputs	Electrical Power	Short to ground, wire-to- wire shorts	Sensor signals are at 110 VAC and a short to ground will result in WTS shutdown via I/O module opening. Wire-to-wire shorts would dis- able sensor, and therefore must be checked during preventative maintenance. A short to the exciter will result in ab- normal generator output which will be detected by the G.A.U. resulting in WTS shutdown.
D.C. power panel to Generator Accessory Unit	Electrical Power, Controls	Short to ground.	Opens circuit breaker result- ing in WTS shutdown.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
Oil Reservoir to Gearbox	Drive Train	Short to ground or wire-to-wire short.	Short to ground opens I/O or circuit breaker and WTS shuts down. Wire-to-wire short could render "oil pressure low" or "oil temp high" sensors inoperative, but these signals are redundant.
Environmental Control - All Cables	Environmental Control	Short to ground or phase to phase short	Circuit breaker opens disabling fans. Not detected by N.C.U. May cause failure in N.C.U. which could result in erroneous signals to pitch, yaw or electrical controls. Similar to a random N.C.U. failure. Fail safe system shuts down WTS (see FMEA controls for analyses of each N.C.U. control line).

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
Fire Detector Cable	Fire detection and extinguishing system	Wire-to-wire short resulting in the detector being ineffective.	Fire would not be detected until second detector picked up smoke. Integrity of wiring checked during preventative maintenance. Emergency egress for personnel provided.
460 VAC cable from power distribution box to yaw drive system; 120 VAC single phase	Yaw drive system	Short - phase-to-phase or to ground	Circuit breaker opens rendering yaw drive system inoperative and resulting in WTS shut down as NCU detects that yaw drive system is inoperative.
Yaw drive signal and status lines	Yaw drive system	Both status and command signals are 110 VAC, so wire-to-wire shorts are very unlikely. A short from any wire to ground possible.	Shorts to ground result in I/O or circuit breaker opening and WTS shutdown. Wire-to-wire short renders command lines or status lines inoperative. Inoperative command line results in WTS shutdown via NCU. Status signals have back-up (i.e., yaw oil pressure low results in unresponsive yaw system which is detected by NCU).

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
Generator Accessory Unit Outputs to NCU	Power output circuits including generator	Short to ground on any single wire. Since all wires but one in this cable are at 110 VAC, the probability of a wire-to-wire short is very small, but long term insulation creep could result in this failure mode. The remaining wire is the power transducer.	<p>Short to ground results in circuit breaker opening and WTS shutdown via pitch accumulators firing and driving blades to feather position.</p> <p>Results of a wire-to-wire short is to render the status signal inoperative since sensor output would be bypassed. Can be detected by periodic wrap-around check during preventative maintenance; second failure required before any problem exists.</p> <p>Shorts to the power transducer result in immediate WTS shutdown via NCU.</p>
Cables to wind sensors	Yaw system, control system at start-up	Wire-to wire-short or short to ground	Cables from both sensors are separated so that a failure within one cable causes a disparity in signals resulting in WTS shutdown.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
NCU to Drive Train	Drive Train	Wire to wire short applies 110 VAC to other 110 VAC lines or to 5 VDC failsafe lines.	Short of 110 VAC to other 110 VAC lines would bypass protection sensors (bearing overtemp. - #1 and #2). Highly unlikely and detectable by checking during preventative maintenance. Short to 5 VDC lines (overspeed and RPM sensors) would result in shutdown via N.C.U.
460 VAC power distribution to gearbox controls	Drive train - controls	Phase to Phase short or short to ground	Circuit breaker fails and WTS shuts down.
NCU to Drive Train Oil Reservoir	Drive Train	Short to ground or wire-to-wire short.	Short to ground results in circuit breaker opening and WTS shutdown (all wires are 110 VAC). Wire-to-wire short could disable "oil pressure low" line, but it is redundant and is therefore not a problem.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
208/120 volt Power Distribution Panel - Housekeeping Circuits and EPS	Aircraft Warning Lights, Generator Protection Circuits	Short to ground, wire-to-wire short	All shorts to ground open circuit breakers. Wire-to-wire shorts would open circuit breaker if different phases short together or if 208 volt line shorts to 120 volt line. Other wire-to-wire shorts have no impact
460 VAC Power Distribution Panel - Housekeeping Circuits	Generator Heaters, Housekeeping, 208/120 VAC supply	Short to ground, wire-to-wire short	Same as 208/120 volt cable above
NCU to Yaw Slip Rings	CRT, Ground Intrusion System, Telephone Line, WTS status indicators, Bus Tie Contactor	Short to ground, wire-to-wire short	CRT, telephone and status indicators not critical functions and no significant damage occurs. Control wire to Bus Tie Contactor shorts to ground or open circuit causes Bus Tie Contactor to open resulting in WTS shutdown. Bus Tie Contactor status lines shorts or opens results in WTS shutdown. Short or open sync. enable line inhibits WTS start-up.

LOW SPEED SHAFT
SLIP RING ANALYSIS

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

LOW SPEED SHAFT SLIP RING ANALYSIS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
<u>LOW SPEED SHAFT</u> <u>SLIP RINGS</u> Rings 1-10	Power Circuits - 460 VAC and 28 volts DC	Ring to adjacent ring short	All of these shorts result in a circuit breaker opening and loss of pitch hydraulic pressure or pitch control. WTS shuts down via hydraulic pressure low or erroneous pitch position feedback signal
#11	Command return (ground)	Short to #10 (280 DC) Short to #12 (110 VAC)	Same as above. Fires emergency accumulator resulting in safe WTS shutdown
#12	Accumulator inhibit command	Short to #13 (110 VAC)	Would prevent firing emergency accumulator on one side, but second accumulator would fire and safely shutdown the WTS.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
<u>LOW SPEED SHAFT</u> SLIP RINGS (Con't) #13	Teeter brake unlock command	Short to #14 (110 VAC)	110 VAC would remain on fail-safe emergency accumulator status line when shutdown. No impact.
Failsafe Emergency Accumulator Low #14	Highspeed shutdown	Short to #15 (110 VAC)	Short would give false signal indicating that emergency accumulator pressure to fail-safe system was normal when it could be failed. NCU signal is redundant with this function and would shut down WTS. Failsafe wiring should be checked every 2 months.
Failsafe Emergency Accumulator Return #15	Highspeed shutdown	Short to #16 (110 VAC)	Same as #14 above.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
Status signal line #16	Pitch Control	Short to #17 (110 VAC)	Would not provide oil low information. Pressure low and/or temperature high would result in shutdown.
Pitch Hydraulic Oil Level Low #17	Pitch Control	Short to #18 (110 VAC)	Same as #16 above
Pitch Hydraulic Oil Filter Clogged #18	Pitch Control	Short to #19 (110 VAC)	Would not provide oil filter clogged information. Filter would be by-passed by relief valve.
Pitch Hydraulic Pressure Low #19	Pitch Control	Short to #20 (110 VAC)	Would not provide pressure low information. Would be detected by fail-safe system and WTS would shut down.
Pitch Hydraulic Oil Temperature High #20	Pitch Control	Short to #21 (110 VAC)	Would not provide oil temperature high information. If WTS performance suffered, the control system would detect it. No major damage would occur if undetected.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
Pitch Hydraulic Accumulator Precharge Pressure Low #21	Pitch Control	Short to #22 (110 VAC)	Would not provide status. Backed up by fail safe system
Pitch emergency accumulator gas pressure low #22	Pitch Control	Short to #23 (110 VAC)	Would not provide gas pressure low signal. Fail-safe system backs up this detector. (See #14)
Crack detection status signal #23	Crack detection	Short to #24 (110 VAC)	Would not provide crack detection capability.
Crack detection status signal return #24	Crack detection	Short to #25 (110 VAC)	Same as #23 above
Emergency Accum. Inhibit Command #25	Pitch Control	Short to #26 (spare) Short to #24 (110 VAC)	No impact Same as number 12.
#26	Spare	- - - - -	- - - - -

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
Low Speed Shaft Slip Rings 27-34	Ice Detection	Shorts to adjacent slip rings	Would render one side of rotor ice detection inoperative. Signals to each detector separated so both sides would not fail. Test signals checks circuit integrity.
#35 - 36	Spares		
Servo valve, Tip #1 #37-41 Position sensor, Tip #1, #42-46 Servo Valve, Tip #2, #44-51 Position sensor, Tip #2, 52-56	Pitch control	Slip ring to slip ring short	WTS would shut down since the NCU would detect an error between the two blade tip positions. Worse case would be loss of a servo amp in the NCU.
#57	Spare		
#58 - 72	Test Instrumentation	Slip ring-to-slip ring shorts	Not a part of the in-line WTS functions - would not inhibit normal or high speed shut downs.

YAW SLIP RING ANALYSIS

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
<u>YAW SLIP RINGS</u> Ground - #1 & #6 Primary Power out - #2-4 Neutral - #5	Electrical power	Ring-to-ring short	Short would probably vaporize. If not, instantaneous over-current and/or ground fault relays would trip the generator circuit breaker and open the bus tie contactor. As a back-up, the BTC is fused.
480 volts A.C. #7-9	All systems that utilize 480 and 240/120 VAC. (Controls, electrical)	Ring-to-ring short	Minor shorts (a wire strand) would vaporize. A major short would trip the 480 VAC circuit breaker(s) resulting in WTS shutdown.
48 VDC lines #10-13	Control system	Ring-to-ring short	Loss of 48 VDC to controls would result in shutdown. The uninterruptable power to the BTC would be maintained since there is a fuse between the battery output and the slip rings, but the wire to the BTC is on the battery side of the fuse.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
YAW SLIP RINGS Fault current Limiting device (FCLD) #14	Electrical power	Short to #15 (low level current is on #15 - differential CT).	Would create imbalance which would trigger differential CT.
Differential CT ØA #15	Electrical Power	Short to #16 (FCLD)	Same as #14 above
Fault current Limiting device #16	Electrical power	Short to #17 (low level current)	Same as #14 above
Differential CT ØB, ØC and Common #17, 18, 19	Electrical power	Ring-to-ring shorts 17-18, 18-19 Short #19 - #20	Same as #14 above
Sync. Enable Relay #20	Electrical Power	Short to #21 (BTC Tripping relay - 110 VAC when closed).	No impact on sync. enable relay since it already has 110 VAC applied. No impact on the BTC relay since it too has 110 VAC applied when rotating. During shutdown, both #20 and #21 have "0" volts applied, so no impact from a short.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
<u>YAW SLIP RINGS</u> BTC Tripping Relay - #21	Electrical Power	Short to ring #22	Would short I/O module and disconnect BTC resulting in WTS shutdown.
Command return #22 (from BTC and sync. enable relay.)	Electrical Power	Short to #23	None, #23 is a spare
Spares - #23 and #24	-	-	-
Generator Circuit Breaker (GCB) Closed indicator return #25	Electrical Power	Short to #26 (Generator field current meter)	Would apply 48 VDC to the Generator Field Current meter. Could cause 48 VDC circuit breaker to open, shutting down the WTS. No serious consequences if current draw is insufficient to trip the breaker.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
YAW SLIP RINGS Generator Field Current Meter (+) #26	Electrical Power	Short to #27 (48 VDC)	Same as #25 above.
Generator Circuit Breaker Closed Indicator	Electrical Power	Short to #28 (current meter)	Same as #25 above.
Generator Field Current Meter (-) #28	Electrical Power	Short to #29 (110 VAC)	Would cause ammeter to act erratic. No WTS operational consequence.
BTC Tripped #29	Electrical Power	Short to #30 (110 VAC)	Would incorrectly indicate that the BTC was closed when it was opened. NCU will detect and lock out the WTS.
Utility Power Present #30	Electrical Power	Short to #31 (110 VAC)	Would indicate that utility power was present when it wasn't. NCU would not have AC power so could not start up. If the short occurred during operation and subsequently, power was lost, the WTS would shift from 60 HZ frequently and shut down.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
YAW SLIP RINGS 110 VAC for BTC signals (Ident. #90 and 91 Slip ring #31)	Electrical power	Short to #32 (110 VAC)	None. #32 is the instrumentation van signal that is either at "0" or 110 VAC. In operational use, this line will be 110 VAC.
Instrumentation Van Not Ready Signal #32	Instrumentation	Short to #33 (48 VDC ground return)	Would destroy 110 VAC test signal I/O in NCU. No operational impact.
D.C. Return for 48 VDC signals #33	Manual control panel indicators	Short to #34 (48 VDC)	Same as #32 above.
Auto Mode Indicator #34	Manual control panel indicators	Short to #35 (48 VDC or 0)	Could erroneously indicate that the control system was in auto mode. Would be obvious fault since the manual mode light would also be on.
C/S Enabled Indicator #35	Manual control panel indicators	Short to #36 (48 VDC or 0)	Could erroneously indicate that the WTS was shut down. Indicators would be in conflict and failure obvious.
Shut Down Indicator #36	Manual control panel indicators	Short to #37 (48 VDC or 0)	Could erroneously indicate that the WTS was in manual mode. Failure would be obvious.

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
<u>YAW SLIP RINGS</u> Manual mode indicator #37	Manual control panel.	Short to #38 (110 VAC or "0")	Would put 48 VDC onto 110 VAC line if in manual mode. Could damage NCU I/O Module, but would not result in secondary damage.
Shutdown Switch #38	Manual control of WTS	Short to #39 (110 VAC)	Both lines are at 110 VAC or one is at 0. Shutdown would occur if short happens while running.
120 VAC supply #39	Manual control panel	Short to #40 (48 VDC)	Could damage NCU I/O module. No secondary damage. Failure would be obvious since several functions on the panel would be disabled.
Emergency Stop #40 & 41	Manual control panel	Short to #41 and/or 42	By-passes switch and stops WTS. Short to #42 could damage NCU I/O. No other damage.
Ground Intrusion Switch #42 and 43	Ground Intrusion	Short to #43 or #44	Would erroneously indicate a ground intrusion. Short to #44 no problem. (#44 is a spare)

FAILURE MODE AND EFFECTS ANALYSIS -- CABLE RUNS

CABLE RUN	SYSTEMS AFFECTED	FAILURE MODE(S)	EFFECTS
<u>YAW SLIP RINGS</u> #44 - 51	None - Spares	----	---
Remote telephone lines #52 - 56	Communications to remote utility control console	Ring-to-ring shorts. All circuits are low level TTL.	Loss of communications with site. No damage to WTS.
Local CRT #57 - 61	Local CRT signals	Ring-to-ring shorts. Circuits are low level TTL.	Loss of information to local CRT. No damage to WTS.
#62 - 120	Test Signals - used during initial test only. Disabled prior to turn-over.	-----	-----

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