# GRID AND METRIC GENERATION ON THE ASSEMBLY OF LOCALLY BI-QUADRATIC COORDINATE TRANSFORMATIONS ${ }^{+}$ 

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## ABSTRACT

The generation of metric coefficients of the coordinate transformation from a generally curved-sided domain boundary to the unit square (cube) is required for efficient solution algorithms in computational fluid mechanics. An algebraic procedure is presented for establishment of these data on the union of arbitrarily selected sub-domains of the global solution domain. A uniformly smooth progression of grid refinement is readily generated, including multiple specification of refined grids for a given macro-element domain discretization. The procedure is illustrated as generally applicable to non-simply connected domains in two- and three-dimensions.
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## COMPUTATIONAL REQUIREMENT

## Navier-Stokes Equations

$$
\begin{aligned}
& L\left(q_{i}\right)=\frac{\partial q_{i}}{\partial t}+\frac{\partial}{\partial x_{j}}\left[u_{j} q_{i}+f_{i j}\right]=0 \\
& \ell\left(q_{i}\right)=a_{1} q_{i}+a_{2} \frac{\partial q_{i}}{\partial x_{j}} \hat{n}_{j}+a_{3}=0
\end{aligned}
$$

Coordinate Transformation

$$
\begin{array}{lr}
x_{i}=x_{i}\left(\eta_{j}\right) & \frac{\partial}{\partial x_{j}}=\frac{\partial}{\partial \eta_{k}}[] \frac{\partial \eta_{k}}{\partial x_{j}} \\
j^{-1}=\left[\frac{\partial \eta_{k}}{\partial x_{j}}\right] & \bar{u}_{k}=\frac{\partial \eta_{k}}{\partial x_{j}} u_{j}
\end{array}
$$

Numerical Solution Algorithm

$$
\begin{gathered}
S_{e}\left[\{D E T \underline{J}\}_{e}^{\top}[M 3000]\{Q I\}_{e}^{\top}-\{U B A R K\}_{e}^{\top}[M 30 K \underline{O} 0]\{Q I\} e\right. \\
\left.-\{E T A K L\}_{e}^{\top}[M 30 \underline{K} 0]\{F \underline{L} I\} e\right] \equiv\{0\}
\end{gathered}
$$

## DISCUSSION

The Navier-Stokes equations contain the vector divergence operator. The required transformation projects $x_{i}$ onto $n_{j}$ with coordinate surfaces defined coincident with solution domain boundaries. The Cartesian description of dependent variables is retained, while the convection velocity is expressed in contravariant scalar components. The numerical solution implementation requires nodal distributions of components of the forward and inverse Jacobians, and $\underline{J}, \underline{K}$, and $\underline{L}$ are tensor summation indices.

LOCALLY BI-QUADRATIC COORDINATE TRANSFORMATION
PHYSICAL DOMAIN TRANSFORMED DOMAIN

$$
x_{i} \equiv\left\{N_{2}(\vec{n})\right\}^{\top}\left\{X_{I}\right\}_{e}
$$



Two-Dimensional


Three-Dimensional
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DISCUSSION
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The bi-quadratic cardinal basis $\left\{N_{2}(\vec{n})\right\}$ transforms the vertex and non-vertex node coordinate description of a smooth region of $R^{n}$ onto the unit square or cube spanned by the locally rectangular Cartesian coordinate system $\vec{\eta}$. The inverse transformation $\mathrm{g}^{-1}$ is non-singular for a range of non-midpoint definitions of the nonvertex node coordinates (x), yielding a non-uniform discretization on $R^{n}$.

## EXAMPLE: COMPRESSOR BLADE ROW



Three of the ten macro-domains, used to form the blade row discretization, are shown. The non-midside location of non-vertex nodes produces the non-uniform grid, only a few gridlines of which are shown. The inset illustrates a fine discretization of one macro-domain. The coordinates of all nodes on boundaries of macrodomains are unique.

## DETAILS OF THE COORDINATE TRANSFORMATION

Nodal COORDinates \{XI\}:

$$
x_{i} \equiv\left\{N_{2}\left(n_{j}\right)\right\}^{\top}\left\{X_{I}\right\}_{e}
$$

Where:

$$
\left\{N_{2}\left(n_{j}\right)\right\} \equiv \frac{1}{4}\left\{\begin{array}{l}
\left(1-n_{1}\right)\left(1-n_{2}\right)\left(-n_{1}-n_{2}-1\right) \\
\left(1+n_{1}\right)\left(1-n_{2}\right)\left(n_{1}-n_{2}-1\right) \\
\left(1+n_{1}\right)\left(1+n_{2}\right)\left(n_{1}+n_{2}-1\right) \\
\left(1-r_{1}\right)\left(1+n_{2}\right)\left(-n_{1}+n_{2}-1\right) \\
2\left(1+n_{1}\right)\left(1-n_{2}\right)\left(1-n_{2}\right) \\
2\left(1-n_{1}\right)\left(1+n_{2}\right) \\
2\left(1-n_{1}\right)\left(1+n_{2}\right)
\end{array}\right\}
$$

## Jacobians

$$
\begin{aligned}
J & \equiv\left[\frac{\partial x_{i}}{\partial n_{j}}\right]=J\left(n_{j}, \text { XI }\right) \\
J^{-1} \equiv\left[\frac{\partial n_{j}}{\partial x_{i}}\right] & =\frac{1}{\operatorname{det} J}[\operatorname{cofactors} \text { of } J] \\
& =J^{-1}\left(\eta_{j}, \text { XI }\right)
\end{aligned}
$$

## DISCUSSION

Within a macro-domain, the components of both $J$ and $\mathrm{J}^{-1}$ are continuous functions of $\eta_{j}$ and the global macro-node coordinate pairs (triples) $\{X I\}, 1 \leq I \leq n$. Each global coordinate $x_{i}$ possesses an independent transformation; the corresponding Jacobian must be of rank $n$ to assure existence of $\mathrm{J}^{-1}$. Once the matrix elements of $\{X I\}$ are defined, selection of any coordinate ( $\eta_{1}, \eta_{2}$ ) defines a unique coordinate pair ( $x_{1}, x_{2}$ ), i.e., a mesh point on the refined grid in physical space.

