
Experimental Aerodynamic Characteristics of Two V/STOL Fighter/Attack Aircraft Configurations at Mach Numbers From 0.4 to 1.4

Walter P. Nelms

Donald A. Durston, Ames Research Center, Moffett Field, California

J. R. Lummus, General Dynamics, Fort Worth Division, Fort Worth, Texas



National Aeronautics and
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Ames Research Center
Moffett Field, California 94035

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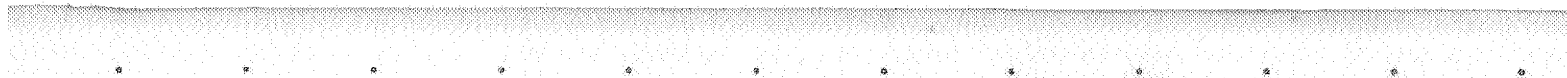


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NOMENCLATURE

The axis system and sign conventions are shown in figure 1. The longitudinal characteristics are presented in the stability-axis coordinate system and the lateral-directional characteristics are presented in the body-axis coordinate system.

A	aspect ratio
a.c.	aerodynamic center
B.L.	buttockline, spanwise distance from model centerline
b	wing span
$C_{A_{INT}}$	internal (duct) axial force coefficient
C_D	drag coefficient, drag/qS
C_L	lift coefficient, lift/qS
C_{L_α}	lift curve slope
C_{ℓ}	rolling-moment coefficient, rolling moment/qSb
C_{ℓ_β}	lateral stability derivative
C_m	pitching-moment coefficient, pitching moment/qS $\bar{c}$
C_{m_0}	zero-lift pitching moment
$C_{N_{INT}}$	internal (duct) normal-force coefficient
C_n	yawing-moment coefficient, yawing moment/qSb
C_{n_β}	directional stability derivative
C_R	root chord
C_T	tip chord
C_Y	side-force coefficient, side force/qS
C_{Y_β}	side-force derivative
$\bar{c}$	wing mean aerodynamic chord
F.S.	fuselage station
H.L.	hinge line

L/D lift-to-drag ratio
 M free-stream Mach number
 Re/l unit Reynolds number
 S wing area
 S.S. span station
 W.L. waterline, vertical distance from model centerline
 α angle of attack
 β angle of sideslip
 Λ sweep angle

Configuration Code

Note: Since there were no strake options on the RALS configuration, B₂ includes both body and strake.

<u>Component</u>	<u>Ejector</u>	<u>RALS</u>
Body	B ₁	B ₂
Strake		
Baseline	S ₁	
High-sweep	S ₂	
Off	S ₃	
Nacelles	N	N
Wing	W ₁	W ₂
Canard longitudinal location		
Mid (baseline)	C ₁	C ₁
Forward	C ₂	C ₂
Aft	C ₃	C ₃
Vertical tail and dorsal	V	V

Flap deflection and incidence of all-movable surfaces (common to both configurations)

	<u>Wing</u>	<u>Canard</u>	<u>Vertical Tail</u>
Leading-edge flap	LE-W	LE-C	---
Trailing-edge flap	TE-W	TE-C	---
Incidence (of all-movable surfaces)	---	Canard	Vert

EXPERIMENTAL AERODYNAMIC CHARACTERISTICS OF TWO V/STOL
FIGHTER/ATTACK AIRCRAFT CONFIGURATIONS

AT MACH NUMBERS FROM 0.4 TO 1.4

Walter P. Nelms and Donald A. Durston
Ames Research Center

and

J. R. Lummus
General Dynamics, Fort Worth Division

SUMMARY

A wind-tunnel test was conducted at Ames Research Center to measure the aerodynamic characteristics of two horizontal-attitude takeoff and landing V/STOL fighter/attack aircraft concepts. The concepts were developed by the General Dynamics Corporation, Fort Worth Division, during a contract study for Ames Research Center and the David Taylor Naval Ship Research and Development Center (DTNSRDC). One aircraft concept was configured to use an ejector to provide propulsive lift; the other used separately ducted and heated fan air to provide propulsive lift (remote augmentation lift system (RALS)). Neither of these propulsive lift devices was simulated during the tests reported here. The tests did investigate the aerodynamic uncertainties for these concepts over a Mach number range from 0.2 to 2.0. The present report covers tests, conducted in the Ames 11-Foot Transonic Wind Tunnel, for Mach numbers from 0.4 to 1.4.

The test results show the plotted effects of varying the angle of attack (0° to 27°), angle of sideslip (-4° to $+8^\circ$), Mach number (0.4 to 1.4), Reynolds number ($9.8 \times 10^6/\text{m}$ to $23.0 \times 10^6/\text{m}$ ($3.0 \times 10^6/\text{ft}$ to $7.0 \times 10^6/\text{ft}$)), and configuration buildup. In addition, the effects of wing trailing-edge flap deflections, canard incidence, and vertical tail deflections are presented. Variable canard longitudinal location and different shapes of the inboard nacelle-body strakes were also investigated. The results indicate that high lift characteristics ($C_{L_{\max}} \approx 2.0$) can be obtained with the baseline configurations of both models over most of the Mach number range. This is attributable to a combination of the beneficial effect of the inboard strake vortices over the wide body and the favorable interaction between the canard and wing flows. The baseline configurations exhibited relatively high longitudinal instability at low Mach numbers (over 28% at Mach number 0.4); they became nearly neutrally stable at supersonic speeds. Trailing-edge wing flaps were found to be the most effective trimming devices on both models. Variable canard incidence contributed somewhat, but lost effectiveness at the higher incidence angles (-20°) or at moderate aircraft angles of attack (12° - 15°).

Longitudinal stability was increased for the ejector configuration by an aft movement of the canard and by a reduction in the planform size of the strakes. In general, however, the canard located midway between the aft and forward location and the baseline strakes produced the most favorable lift and drag characteristics. Likewise, on the RALS configuration, the mid-canard location gave the higher lift, and the aft position produced the greater longitudinal stability.

INTRODUCTION

Ames Research Center has a number of research programs under way to develop aerodynamic and aerodynamic-propulsion integration technology for V/STOL fighter/attack aircraft of the post-1990 time period. One of these programs was a contract study that was jointly sponsored with the David Taylor Naval Ship Research and Development Center and the Naval Air Systems Command. In Phase I of the program, four contractors provided conceptual designs, estimated the aerodynamics of the designs, identified aerodynamic uncertainties, and proposed a wind-tunnel program to explore these uncertainties. References 1 through 5 give the detailed results of this Phase I effort, and reference 6 presents a summary of these studies and of several other related programs at Ames. In Phase II of the program, two contractors designed and built wind-tunnel models for tests in the Ames Unitary and 12-Foot Wind Tunnels; the tests cover a Mach number range of 0.2 to 2.0.

This report presents the results of transonic tests of two models designed and built in Phase II by the General Dynamics Corporation (ref. 1). Two concepts were investigated, both of which were horizontal-attitude take-off and landing V/STOL fighter/attack aircraft. One model was a representation of a V/STOL fighter aircraft employing a jet diffuser ejector for its propulsive lift system; the other model represents an aircraft featuring engine air ducting to a forward combustor and nozzles (remote augmentation lift system (RALS)).

The experimental investigation documented in this report was conducted in the Ames 11-Foot Transonic Wind Tunnel over a Mach number range of 0.4 to 1.4. The Reynolds number was held constant at $9.84 \times 10^6/\text{m}$ ($3.0 \times 10^6/\text{ft}$). Angle of attack was varied up to approximately 27° and angles of sideslip ranged from -4° to $+8^\circ$. Model variations investigated included component buildup, canard longitudinal location, inboard strake shape, and deflections of the canard, wing trailing-edge flaps, and vertical tail.

TEST FACILITY

The tests were conducted in the Ames 11-Foot Transonic Wind Tunnel, which is a variable-density, closed-circuit, continuous-flow facility. This tunnel has an adjustable nozzle (two flexible walls) and a slotted test section to permit transonic testing over a Mach number range that is continuously variable from 0.4 to 1.4.

MODEL DESCRIPTION

Two models were tested, one representative of a V/STOL fighter/attack aircraft using a jet diffuser ejector for its vertical lift system (identified as configuration E205) and the other representative of a concept with a remote augmentation lift system (RALS) for vertical takeoff and landing (configuration R104). The models were 9.39-percent scaled versions of the conceptual aircraft described in reference 1.

Configuration E205

A three-view drawing of the wind-tunnel model simulating a V/STOL fighter with a jet diffuser ejector vertical lift system (model E205) is shown in figure 2(a). Pertinent dimensions, areas, and other parameters are presented in table 1 and in figures 2(b) and 2(c). Figure 2(d) gives a cross-sectional area distribution of the wind-tunnel model. Photographs of the model and its installation in the 11-Foot Wind Tunnel are shown in figure 3.

Parametric variations available on the model (not all were investigated in the present test) included: component buildup, variable wing outboard and inboard trailing-edge flaps, variable wing leading-edge flaps, a variable incidence canard with variable leading- and trailing-edge flaps, three longitudinal canard locations, three inboard nacelle/body strake shapes, and an all-movable vertical tail. A wing-root bending moment gage was installed to obtain an indication of buffet onset. The term baseline configuration as used herein refers to the model with the mid-canard location (fig. 2(a)) and the baseline strake (S_1 in fig. 2(c)).

Configuration R104

Figure 4(a) is a three-view drawing of the wind-tunnel model of a V/STOL fighter employing RALS for vertical lift. Pertinent dimensions, areas, and other parameters are given in table 2 and in figure 4(b). Figure 4(c) shows the cross-sectional-area distribution of the wind-tunnel model. Photographs of the model and of the model installed in the Ames 11-Foot Transonic Wind Tunnel are presented in figure 5.

The parametric variations on the R104 configuration were the same as those of the E205 model except that only one inboard nacelle/body strake shape was available. The baseline configuration again has the mid-canard location (fig. 4(a)).

TEST CONDITIONS AND PROCEDURES

Tests were conducted at Mach numbers of 0.4 to 1.4 at a constant unit Reynolds number of $9.84 \times 10^6/\text{m}$ ($3.0 \times 10^6/\text{ft}$). Angle of attack was varied up

to the maximum allowable loading (about 27° at the lower Mach numbers), using a $+12.5^\circ$ bent sting arrangement; angle of sideslip ranged from -4° to $+8^\circ$. The angles of attack and angles of sideslip were corrected for wind-tunnel flow misalignment and for balance and sting deflections caused by aerodynamic loads. Runs to evaluate Reynolds number effects were made at Mach numbers 0.6, 0.9, and 1.2 for the E205 configuration.

The models were sting-supported through the base of the fuselage body on a 2.5-in. six-component strain-gage balance. The moment reference center for both models was located longitudinally at 3 percent of the mean aerodynamic chord, which represents a fuselage station of 0.737 m (29.002 in.) on the E205 model, and a fuselage station of 0.748 m (29.463 in.) on the R104 model. Measured axial forces have been adjusted to a condition corresponding to that of having free-stream static pressure acting on the fuselage cavity and on the base areas of the two nacelle choke plugs.

The data presented in this report have been adjusted for internal forces acting in the flow-through nacelles. These internal axial and normal forces were derived from a series of runs employing a duct exit rake in both nacelles. These rakes, each with 20 total head tubes, were calibrated prior to the test against known mass flows measured by standard ASME nozzles. The duct exit static pressures were measured during the internal flow survey, using a series of orifices located around the periphery of the nacelle choke plugs. Figure 6 shows the rake installation on the E205 model in the 11-Foot Tunnel. The resulting internal force coefficients that have been applied to the data are presented in table 3 (E205) and table 4 (R104) as a function of Mach number and angle of attack.

To assure an all turbulent boundary layer, transition strips consisting of a random distribution of 0.0175-0.0208-cm (0.0069-0.0082-in.) sieved glass spheres were placed near the leading edges of the wing, canard, and vertical tail, around the fuselage nose, and around the nacelle leading edges. Experience with the 11-Foot Wind Tunnel has shown that grit of this size would produce a turbulent boundary layer on the model, at the conditions of the test, without causing grit-associated drag.

RESULTS AND DISCUSSION

Experimental aerodynamic data for the two models are presented in figures 7 through 120. The E205 model results are shown in figures 7 through 80 and the R104 results are presented in figures 81 through 120.

To expedite publication of the data, only a brief description of the test results is presented in the following sections. An in-depth analysis of the data and comparison with theoretical estimates will be reported in subsequent publications.

Baseline E205 Configuration

Longitudinal characteristics (zero deflection on all surfaces)- The effect of Mach number on the longitudinal characteristics of the baseline configuration is presented in figure 7. Maximum permissible loading of the balance and sting limited angle of attack to about 25° to 27° at subsonic speeds and to about 20° at supersonic speeds. Lift coefficients continued to increase to these angles of attack at all test Mach numbers, and maximum lift could not be reached. Summary data for the effects of Mach number are given in figure 8.

Figures 9-11 show the effect of variations in Reynolds number at Mach numbers of 0.6, 0.9, and 1.2, respectively. Little or no effect on the longitudinal characteristics is displayed for the Reynolds number range that could be achieved in the 11-Foot Wind Tunnel within permissible maximum loading.

Longitudinal aerodynamic characteristics resulting from model component buildup are presented in figures 12 through 19. The body-nacelle-alone configuration exhibited relatively high lift coefficients (up to 0.9) resulting from a favorable interaction of the inboard nacelle/body strake on the wide area between the nacelles. Addition of the wing further increased this lift; the canard, through favorable interaction with the wing, improved both the lift and drag up to the maximum angles of attack of the test. It is believed that the high lift coefficients generated by this model are due to a combination of the favorable interaction of the inboard strake on the wide body together with the favorable interaction of the canard on the wing. The effects of component buildup on pitching moment coefficient were essentially as would be expected by locating lifting areas fore and aft of the moment reference center. Figure 20 presents a summary of the Mach number effects on longitudinal aerodynamics for a buildup of model components.

Lateral/directional characteristics- Figures 21-23 show the lateral/directional aerodynamic characteristics at various angles of attack for the baseline configuration. The model produced positive directional stability ($+C_{n\beta}$) and positive effective dihedral ($-C_{l\beta}$) up to angles of attack of about 17° at Mach 0.6. At Mach 0.9, $C_{n\beta}$ is positive to about 10° and the effective dihedral is positive at all angles of attack. At Mach number 1.2, changes in directional stability are exhibited between $\beta = \pm 2^\circ$ at positive angles of attack.

Canard-off effects on the lateral/directional characteristics of the baseline configuration are shown for two angles of attack in figures 25 and 26 for Mach numbers 0.9 and 1.2, respectively.

Trim characteristics- Figures 27 through 35 present the trim characteristics of the baseline configuration. Canard incidence variations (0° , $\pm 10^\circ$, -20°) and canard-off are shown for three wing trailing-edge flap deflections (0° , 10° , 25°) at Mach numbers of 0.6, 0.9, and 1.2. For these runs, the wing outboard and inboard trailing-edge flaps were deflected as a unit.

Although available, canard incidence of $+20^\circ$ and wing trailing-edge flap deflection of 20° were not run in order to conserve test time. Likewise, the effects on trim of canard leading- and trailing-edge flap deflections and wing leading-edge flap deflection (all available on the model) were not investigated during this tunnel entry, due to limited test time.

Figures 36 through 38 present some of the previous data replotted to show the effectiveness of the trailing-edge flap as a trimming device. The longitudinal aerodynamic characteristics are shown for three flap deflections (0° , 10° , 25°) with zero canard incidence at Mach numbers of 0.6, 0.9, and 1.2.

The results of the trim investigation indicate that the configuration could be trimmed over a range of angle of attack, using a combination of wing trailing-edge flap deflection and canard incidence. Of the two surfaces, the wing trailing-edge flaps proved to be the most effective trimming device. For the subsonic speeds, the canard became essentially ineffective at the negative deflections at relatively low angles of attack. This would suggest that for this particular configuration the canard would be scheduled with angle of attack and Mach number to give the most favorable interaction with the wing (provide the highest L/D), and the wing trailing-edge flaps would be used as the primary surface to provide trim.

Vertical tail effects- The longitudinal and lateral/directional aerodynamic characteristics resulting from deflection of the vertical tail are presented in figures 39 through 42 for Mach numbers 0.9 and 1.2. As expected, the vertical tail deflection is seen (figs. 39 and 40) to have little effect on the longitudinal characteristics, with the most significant effect being an increase in C_D and a reduction in L/D for the higher deflections.

The lateral/directional characteristics are shown in figures 41 and 42 for vertical-tail-off and for deflections of 0° , 5° , and 15° at two angles of attack for each Mach number. The results indicate that deflecting the vertical tail was effective in producing significant control forces over the angle-of-attack and angle-of-sideslip ranges of the test.

It should be noted that when an angle of attack is given in a figure caption, it is only the nominal value; more accurate angles (to within $\pm 0.5^\circ$) are given at the top of each plot page.

Effects of Alternative Components

Canard location effects- The effect on the longitudinal aerodynamic characteristics of varying the canard longitudinal location (see fig. 2(a) for positions) is given in figures 43 through 69. Data are presented for canard deflections of 0° and $\pm 10^\circ$ at Mach numbers of 0.6, 0.9, and 1.2 for each of the three strake options (baseline; high-sweep, and "off" as shown in fig. 2(c)). The most pronounced effect of canard location is seen in the pitching moment, where the forward canard (C_2) accounts for the greater instability, as expected. The mid-canard (C_1) generally has the most favorable lift and drag of the three positions over the range of strake options and Mach numbers.

Lateral/directional characteristics are shown in figures 70 through 73 at two angles of attack, with and without the vertical tail, for Mach numbers of 0.9 and 1.2. There are some slight differences in these characteristics among the three canard locations; the trends and magnitude of the differences vary with Mach number and angle of attack.

Strake effects- The longitudinal aerodynamic effects due to the strake variations on the model (fig. 2(c)) are presented in figures 74 through 76 for Mach numbers of 0.6, 0.9, and 1.2. The canard was held at the mid-position at 0° of incidence for these plots. With the baseline strake, the model L/D is greater, relative to the high-sweep and strake "off" configurations. However, a penalty is incurred in the pitching moment because of the baseline strake contributing to more longitudinal instability. This is primarily due to the slight increase in forward planform area of the baseline strake over the others (see fig. 2(c)).

The lateral/directional characteristics for the strake variations are plotted in figures 77 through 80 in a sequence similar to that for the canard location effects. Generally, the baseline strake configuration is slightly more stable than the other two in terms of yawing and rolling moments. There is little difference in side force due to the three strake variations.

Baseline R104 Configuration

Longitudinal characteristics (zero deflection on all surfaces)- The effect of Mach number on the longitudinal characteristics of the baseline configuration is presented in figure 81, and summary data are given in figure 82. In general, the results are similar to those previously discussed for the E205 configuration. However, the R104 configuration has higher minimum drag than the E205 configuration at supersonic speeds. It is felt that this increased drag is due to (1) changes from the flight vehicle lines as a result of using the E205 nose and cockpit section on the R104 model (to reduce costs), which resulted in a "necked down" section aft of the cockpit (see fig. 4(a)); (2) inefficient flow in the top channels between the aft portion of the nacelles and fuselages (these channels are narrower on the R104 configuration); and (3) an area distribution on the R104 configuration that exhibits greater peakedness (compare figs. 4(c) and 2(d)).

Longitudinal aerodynamic characteristics resulting from model component buildup are shown in figures 83 through 90; figure 91 presents a summary with Mach number. A canard-on with wing-off configuration, added to this series of runs, was not used during tests of the E205 model. Otherwise, the results are similar to those of the E205 configuration with exception of the aforementioned minimum drag difference.

Lateral/directional characteristics- Figures 92-94 show the lateral/directional aerodynamic characteristics at various angles of attack for the baseline configuration. The results are similar to those of the E205 configuration, except that the R104 concept appears to be slightly more directionally unstable at the higher angles of attack. Also, the changes in

directional stability exhibited by the E205 model between $\beta = \pm 2^\circ$ at Mach number 1.2 are not as evident on the R104 configuration. Figure 95 presents a summary with angle of attack of these basic lateral/directional characteristics.

Canard-off effects on the lateral/directional characteristics of the baseline R104 configuration are shown for two angles of attack in figures 96 and 97 for Mach numbers 0.9 and 1.2, respectively.

Trim characteristics- Figures 98 through 106 present the trim characteristics of the baseline R104 configuration, using canard incidence and wing trailing-edge flap deflections. Canard incidence variations (0° , $\pm 10^\circ$, -20°) and canard-off are shown for three wing trailing-edge flap deflections (0° , 10° , and 25°) at Mach numbers of 0.6, 0.9, and 1.2. Figures 107 through 109 show directly the effectiveness of the wing trailing-edge flap as a trimming surface. Generally the trim characteristics are similar to those of the E205 configuration, with some minor differences noted by comparison of the appropriate figures.

Vertical tail effects- The effects of vertical tail deflection on the longitudinal characteristics are presented in figures 110 and 111, and the lateral/directional results are shown in figures 112 and 113. These results are again similar to those of the E205 configuration, with some minor differences at the higher angles of attack, particularly at Mach number 1.2.

Effects of Canard Location

Figures 114 through 116 present the longitudinal aerodynamic effects of moving the canard forward and aft of the baseline mid-location (see fig. 4(a) for positions). The results are shown for Mach numbers 0.6, 0.9, and 1.2 with all control surfaces at zero deflection. Both alternative canard positions resulted in a slight loss in lift at the highest angles of attack, with the aft location generally producing the greater loss. The most notable effect of canard longitudinal location was the changes in stability where an aft movement of the canard reduced the instability of the model at all Mach numbers.

The effect of canard location on the lateral/directional characteristics, for Mach numbers 0.9 and 1.2 and at two angles of attack, is shown in figures 117-120. Both vertical tail-on and tail-off results are presented.

CONCLUDING REMARKS

Tests were conducted in the Ames 11-Foot Transonic Wind Tunnel at Mach numbers from 0.4 to 1.4 on two models representative of V/STOL fighter/attack aircraft configurations. Both were horizontal-attitude takeoff and landing concepts developed by the General Dynamics Corporation. The concepts differed in their approach to propulsive lift; one used a jet diffuser ejector system for vertical lift and the other a remote augmentation lift system (RALS).

Detailed effects of varying the angle of attack (up to 27°), angle of sideslip (-4° to $+8^\circ$), Mach number, Reynolds number, and configuration buildup were investigated. In addition, the effects of wing trailing-edge flap deflections, canard incidence, and vertical-tail deflections were explored. Variable canard longitudinal location and different shapes of the inboard nacelle/body strakes were also investigated. Results from these tests indicate the following:

1. The models produced high lift coefficients ($C_{L_{\max}} \approx 2.0$), which could be attributed to a favorable interaction between the canard and wing and between the inboard strake and the wide body. Maximum lift was not achieved within the test angle-of-attack limits of about 27° .
2. Addition of the canard increased lift coefficients and improved the drag polars at high angles of attack; however, it also increased the instability of both configurations.
3. Both models in the baseline configurations exhibited relatively high longitudinal instability at low Mach numbers (over 28 percent at Mach number 0.4). At supersonic speeds, the ejector concept became nearly neutrally stable, and the RALS configuration was still about 8 to 10 percent unstable.
4. The baseline configurations of both concepts had positive directional stability to angles of attack of about 17° at a Mach number of 0.6 and 10° at a Mach number of 0.9. At Mach 1.2, the ejector configuration was directionally stable to an angle of attack of about 6° ; the RALS concept was stable to an angle of attack of about 14° .
5. Using a combination of wing trailing-edge flap deflection and canard incidence, both configurations could be trimmed to an angle of attack of about 12° subsonically and to about 16° to 20° at Mach 1.2.
6. Wing trailing-edge flaps were found to be the most effective trimming surfaces, for the canard lost effectiveness at the higher negative incidence angles.
7. In general, the canard in the mid-longitudinal position and the baseline strakes produced the most favorable lift and drag characteristics for the ejector configuration. Likewise, the mid-canard location gave the higher lift for the RALS concept.
8. Longitudinal stability was increased for the jet diffuser ejector configuration by an aft movement of the canard and by a reduction in the planform size of the strakes. On the RALS concept, the aft canard location also produced the greater longitudinal stability.

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TABLE 1.- GEOMETRY OF E205 CONFIGURATION

	Wing	Horizontal canard (mid-position)	Vertical tail
Airfoil at			
C_R	NACA-64A204	NACA-64A005	5.3% biconvex
C_T	NACA-64A204	NACA-64A003	4.0% biconvex
Theoretical area, m ² (ft ²)	0.315 (3.3858)	0.0315 (0.3390) ^a	0.0389 (0.4188)
MAC, m (in.)	0.340 (13.398)	0.183 (7.197)	0.184 (7.256)
Aspect ratio	3.62	1.08 ^a	1.27
Taper ratio	0.190	0.37	0.43
Root chord, m (in.)	0.495 (19.505)	0.249 (9.815)	0.245 (9.638)
Tip chord, m (in.)	0.094 (3.706)	0.092 (3.631)	0.105 (4.144)
Span, m (in.)	1.067 (42.010)	0.184 (7.261)	0.222 (8.751)
Dihedral	0°	0°	—
Incidence	0°	—	—
Hinge line at			
B.L.	—	0.228 (8.996)	0
F.S.	—	0.620 (24.414)	1.252 (49.297)
W.L.	—	0.396 (15.587)	0.403 (15.869)
Hinge-line sweep	—	-1°46'	0°
Leading-edge sweep	40°	45°	47°30'
Trailing-edge sweep	4°58'	8°26'	24°52'
Body length, 153 m (60.10 in.)	—	—	—

^aArea of one panel.

TABLE 2.- GEOMETRY OF R104 CONFIGURATION

	Wing	Horizontal canard (mid-position)	Vertical tail
Airfoil at			
C_R	NACA-64A204	NACA-64A005	5.3% biconvex
C_T	NACA-64A204	NACA-64A003	4.0% biconvex
Theoretical area, m ² (ft ²)	0.293 (3.154)	0.0315 (0.3390) ^a	0.0389 (0.4188)
MAC, m (in.)	0.330 (12.973)	0.183 (7.197)	0.184 (7.256)
Aspect ratio	3.57	1.08 ^a	1.27
Taper ratio	0.1966	0.37	0.43
Root chord, m (in.)	0.479 (18.851)	0.249 (9.815)	0.254 (9.638)
Tip chord, m (in.)	0.094 (3.706)	0.092 (3.631)	0.105 (4.144)
Span, m (in.)	1.023 (40.270)	0.184 (7.261)	0.222 (8.751)
Dihedral	0°	0°	—
Incidence	0°	—	—
Hinge-line at			
B.L.	—	0.206 (8.126)	—
F.S.	—	0.620 (24.414)	1.247 (49.110)
W.L.	—	0.396 (15.587)	0.377 (14.836)
Hinge-line sweep	—	-1°46'	0°
Leading-edge sweep	40°	45°	47°30'
Trailing-edge sweep	4°58'	8°26'	24°52'
Body length, 147 m (57.90 in.)	—	—	—

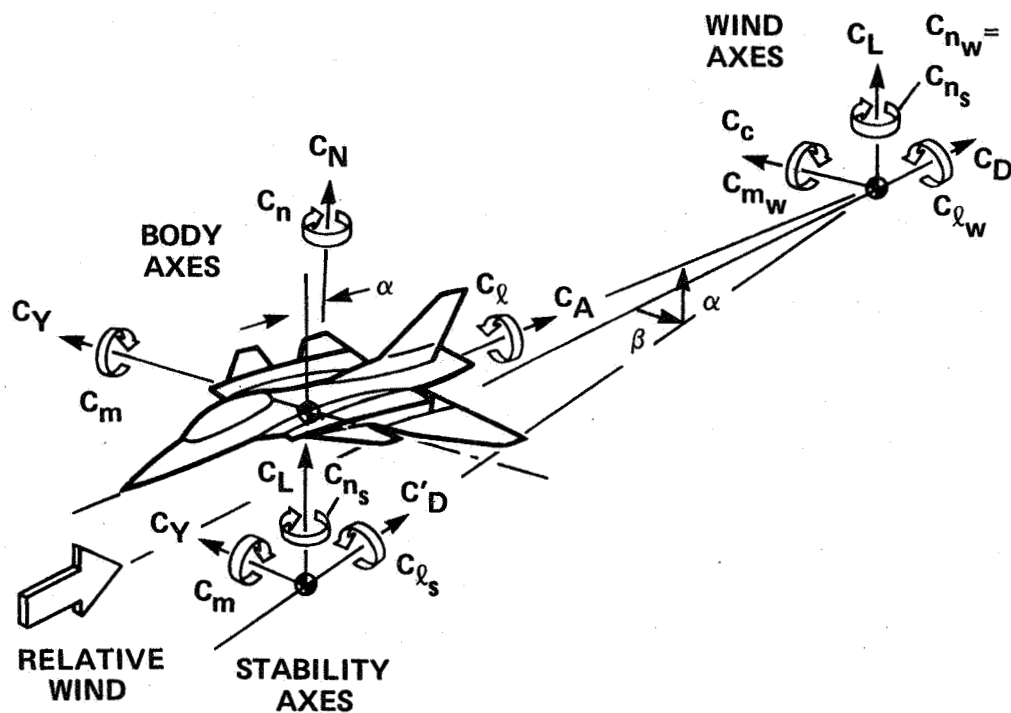
^a Area of one panel.

TABLE 3.- INTERNAL FORCE COEFFICIENTS OF E205 CONFIGURATION
(Values are totals of both ducts)

Angle of attack, force coefficient	Mach number							
	0.4	0.6	0.8	0.9	0.95	1.10	1.20	1.40
-4°, $C_{N_{INT}}$	-0.00240	-0.00240	-0.00240	-0.00240	-0.00225	-0.00225	-0.00252	-0.00252
$C_{A_{INT}}$	.00167	.00141	.00111	.00080	.00086	.00077	.00098	.00145
0°, $C_{N_{INT}}$	.00045	.00045	.00045	.00045	.00045	.00045	.00045	.00045
$C_{A_{INT}}$	.00175	.00143	.00109	.00079	.00076	.00053	.00065	.00121
4°, $C_{N_{INT}}$	.00327	.00327	.00327	.00327	.00306	.00320	.00341	.00360
$C_{A_{INT}}$	.00205	.00168	.00108	.00085	.00080	.00051	.00043	.00096
8°, $C_{N_{INT}}$	.00585	.00585	.00585	.00585	.00570	.00589	.00610	.00647
$C_{A_{INT}}$	.00389	.00316	.00202	.00131	.00110	.00064	.00034	.00072
12°, $C_{N_{INT}}$	.00814	.00819	.00819	.00814	.00817	.00831	.00855	.00900
$C_{A_{INT}}$	.00572	.00475	.00310	.00204	.00156	.00084	.00035	.00047
16°, $C_{N_{INT}}$	.01020	.01033	.01033	.01020	.01022	.01032	.01072	.01135
$C_{A_{INT}}$	.00757	.00640	.00416	.00275	.00215	.00108	.00043	.00030
20°, $C_{N_{INT}}$	.01202	.01220	.01220	.01210	.01202	.01220	.01266	.01364
$C_{A_{INT}}$	.00950	.00807	.00524	.00346	.00285	.00137	.00052	.00026
24°, $C_{N_{INT}}$	.01345	.01376	.01376	.01351	.01354	.01397	.01452	.01575
$C_{A_{INT}}$	.01148	.00990	.00633	.00419	.00357	.00169	.00063	.00032
28°, $C_{N_{INT}}$	.01454	.01502	.01502	.01458	.01495	.01563	.01627	.01575
$C_{A_{INT}}$	.01355	.01180	.00742	.00491	.00439	.00205	.00074	.00040
30°, $C_{N_{INT}}$	.01496	.01550	.01550	.01496	.01557	.01640	.01627	.01575
$C_{A_{INT}}$	.01460	.01276	.00795	.00525	.00484	.00222	.00080	.00045

TABLE 4. - INTERNAL FORCE COEFFICIENTS OF R104 CONFIGURATION
(Values are totals of both ducts)

Angle of attack, force coefficient	Mach number							
	0.4	0.6	0.8	0.9	0.95	1.10	1.25	1.40
-4°, $C_{N_{INT}}$	-0.00258	-0.00258	-0.00258	-0.00258	-0.00242	-0.00242	-0.00271	-0.00271
$C_{A_{INT}}$	.00179	.00151	.00119	.00086	.00092	.00083	.00105	.00156
0°, $C_{N_{INT}}$	.00048	.00048	.00048	.00048	.00048	.00048	.00048	.00048
$C_{A_{INT}}$	.00188	.00154	.00117	.00085	.00082	.00057	.00070	.00130
4°, $C_{N_{INT}}$	.00351	.00351	.00351	.00351	.00328	.00344	.00366	.00386
$C_{A_{INT}}$	.00220	.00180	.00116	.00085	.00086	.00055	.00046	.00103
8°, $C_{N_{INT}}$	.00628	.00628	.00628	.00628	.00612	.00632	.00655	.00695
$C_{A_{INT}}$	.00418	.00339	.00217	.00141	.00118	.00069	.00036	.00077
12°, $C_{N_{INT}}$	.00874	.00879	.00879	.00874	.00877	.00892	.00918	.00966
$C_{A_{INT}}$	.00614	.00510	.00333	.00219	.00167	.00090	.00038	.00050
16°, $C_{N_{INT}}$	.01095	.01109	.001109	.01095	.01097	.01108	.01151	.01218
$C_{A_{INT}}$	.00813	.00687	.00447	.00295	.00231	.00116	.00046	.00032
20°, $C_{N_{INT}}$	.01290	.01310	.01310	.01299	.01290	.01310	.01359	.01464
$C_{A_{INT}}$	.01020	.00866	.00562	.00371	.00306	.00147	.00056	.00028
24°, $C_{N_{INT}}$	.01444	.01477	.01477	.01450	.01453	.01500	.01559	.01691
$C_{A_{INT}}$	.01232	.01063	.00680	.00450	.00383	.00181	.00068	.00034
28°, $C_{N_{INT}}$	.01561	.01612	.01612	.01565	.01605	.01678	.01747	.01691
$C_{A_{INT}}$	.01455	.01267	.00797	.00527	.00471	.00220	.00079	.00043
30°, $C_{N_{INT}}$	.01606	.01664	.01664	.01606	.01671	.01760	.01747	.01691
$C_{A_{INT}}$	.01567	.01370	.00853	.00564	.00520	.00238	.00086	.00048

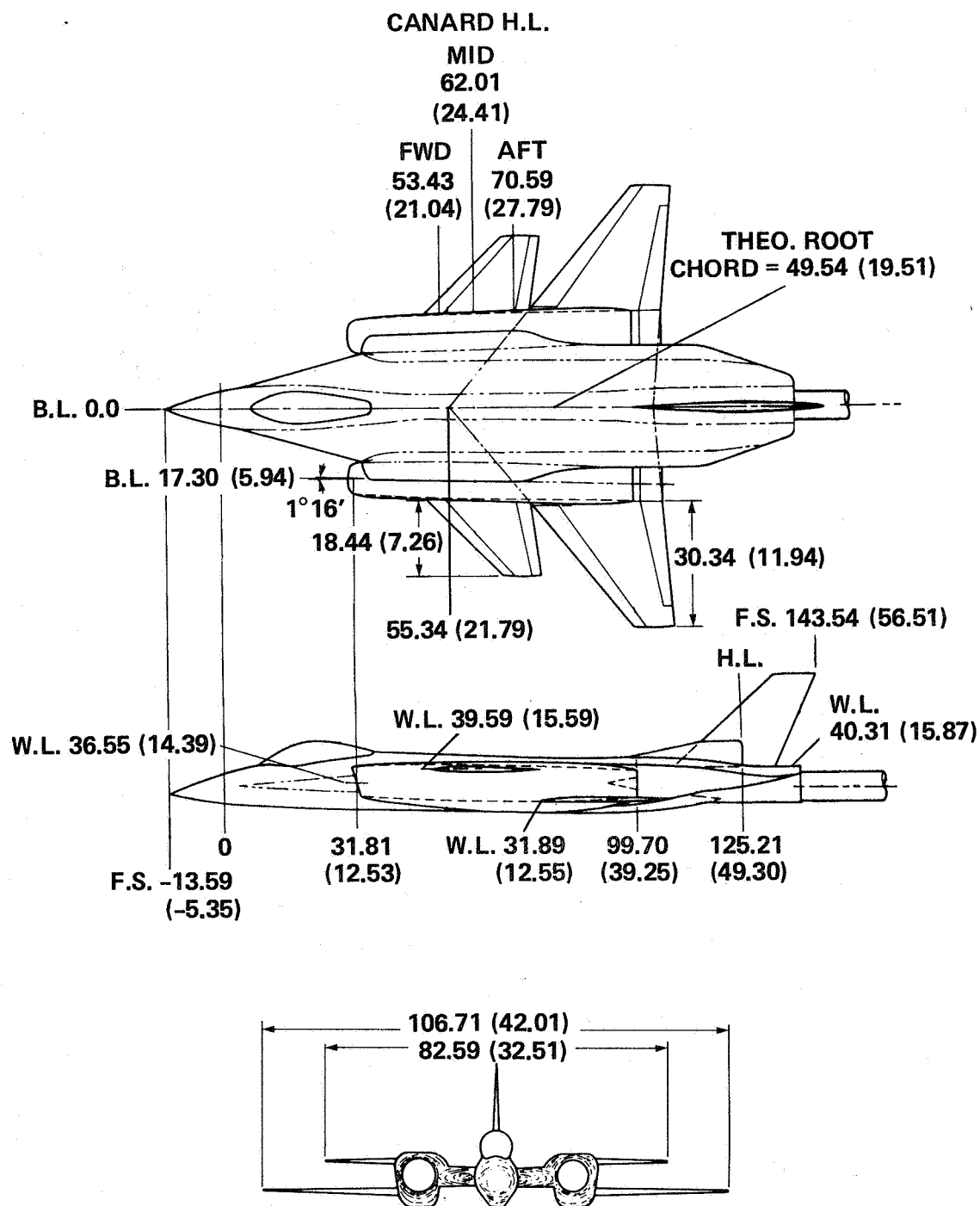


NOTE:

1. POSITIVE VALUES OF FORCE AND MOMENT COEFFICIENTS AND ANGLES ARE INDICATED.
2. ORIGINS OF WIND AND STABILITY AXES HAVE BEEN DISPLACED FROM CENTER OF GRAVITY FOR CLARITY.

$$+\beta \text{ (SIDESLIP)} = -\psi \text{ (YAW)}$$

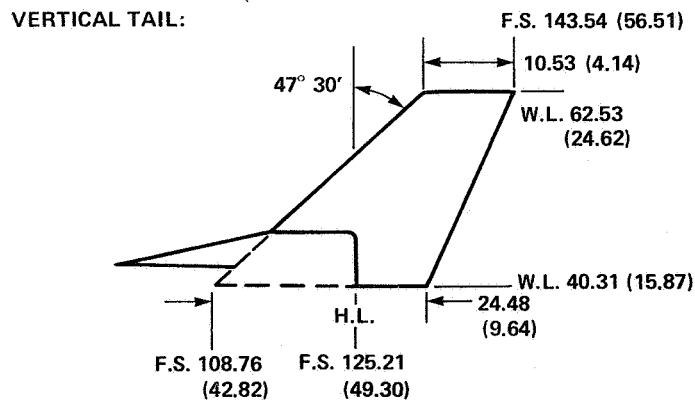
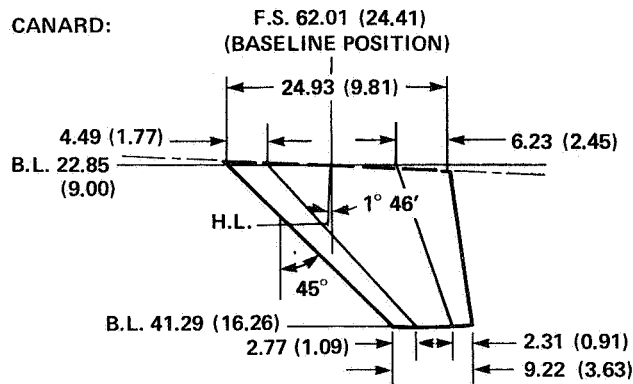
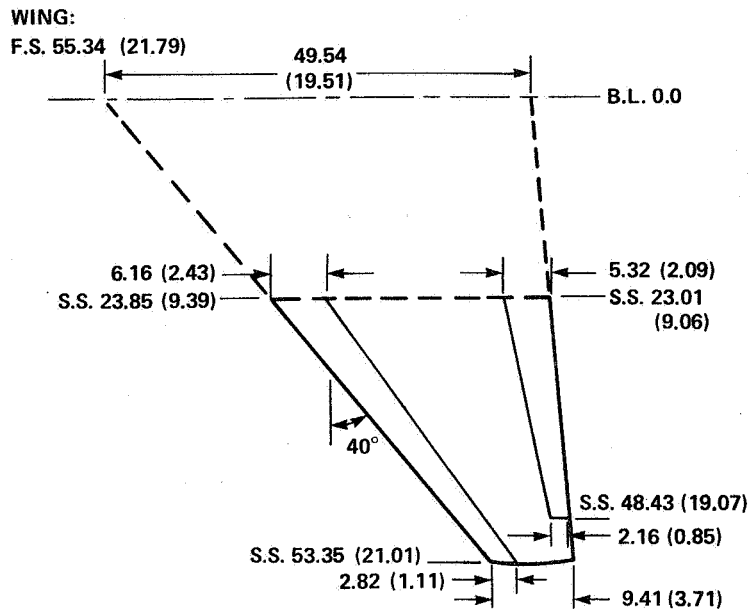
Figure 1.- Axis system and sign conventions.



**NOTE: ALL LINEAR DIMENSIONS
 ARE IN CENTIMETERS (INCHES).**

(a) Three-view drawing.

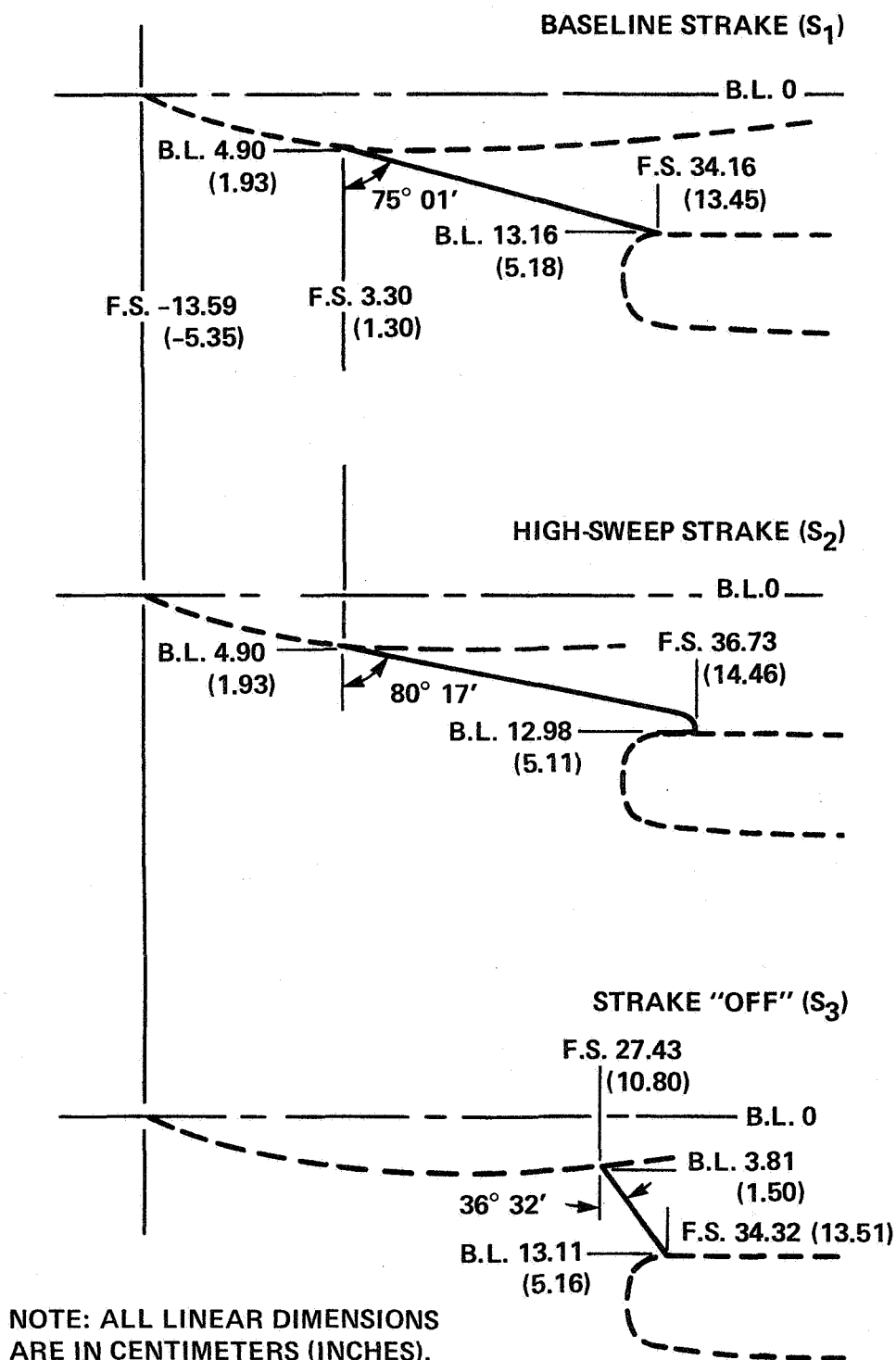
Figure 2.- Details of the E205 wind-tunnel model.



NOTE: ALL LINEAR DIMENSIONS
ARE IN CENTIMETERS (INCHES).

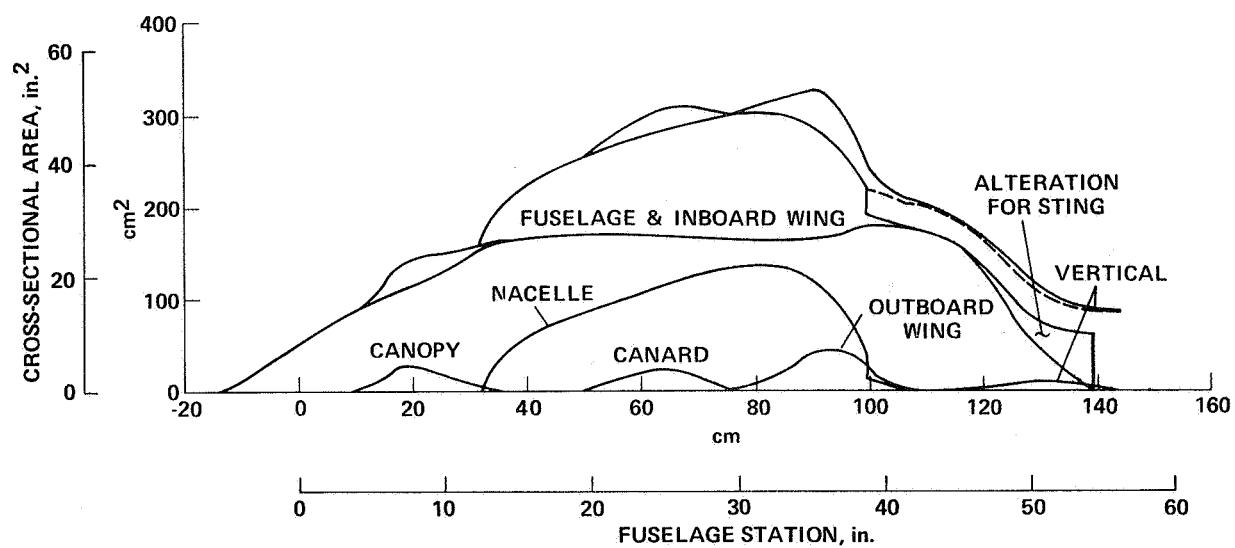
(b) Wing, canard and vertical tail detail.

Figure 2.- Continued.



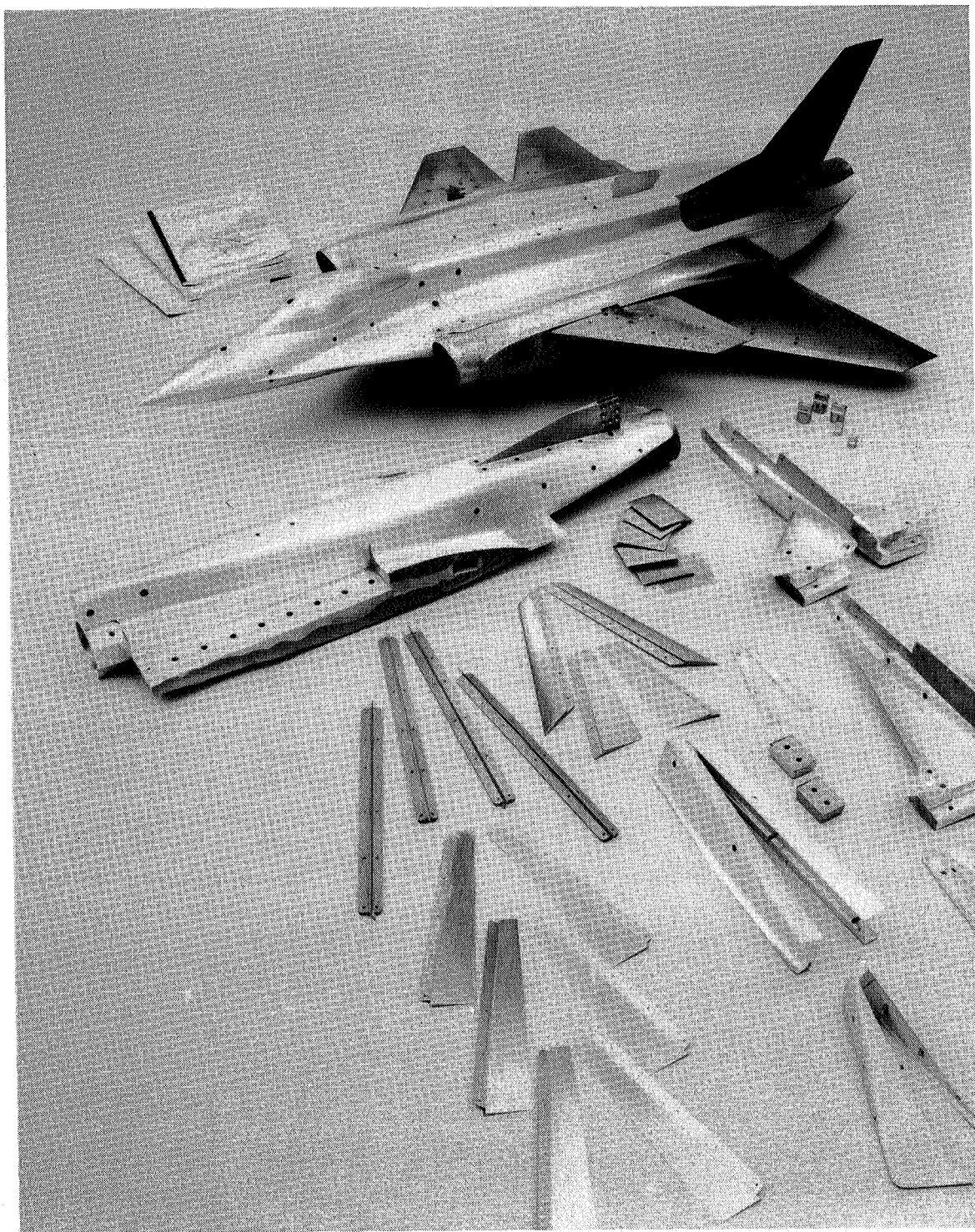
(c) Strake options.

Figure 2.- Continued.



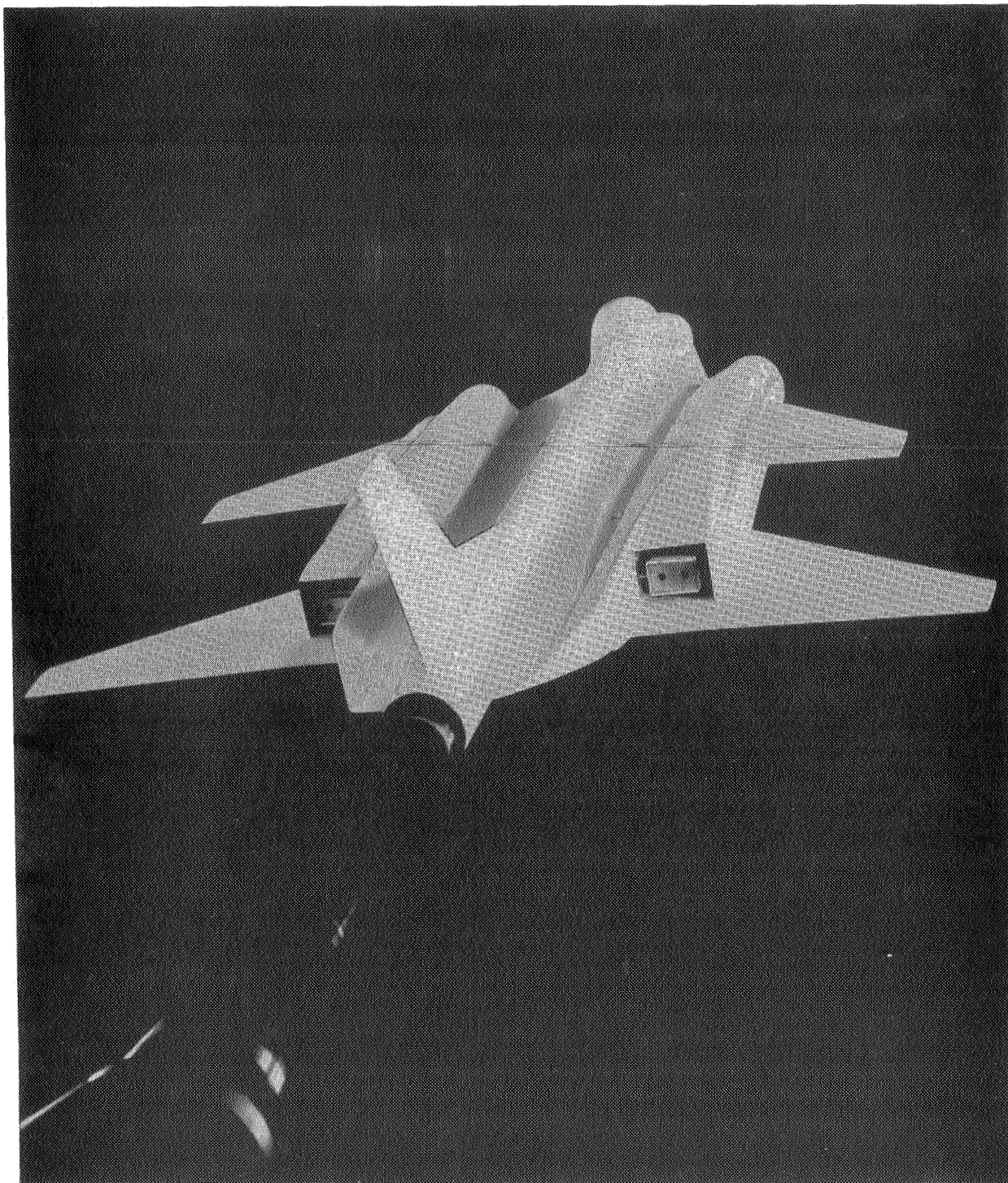
(d) Cross-sectional area distribution.

Figure 2.- Concluded.



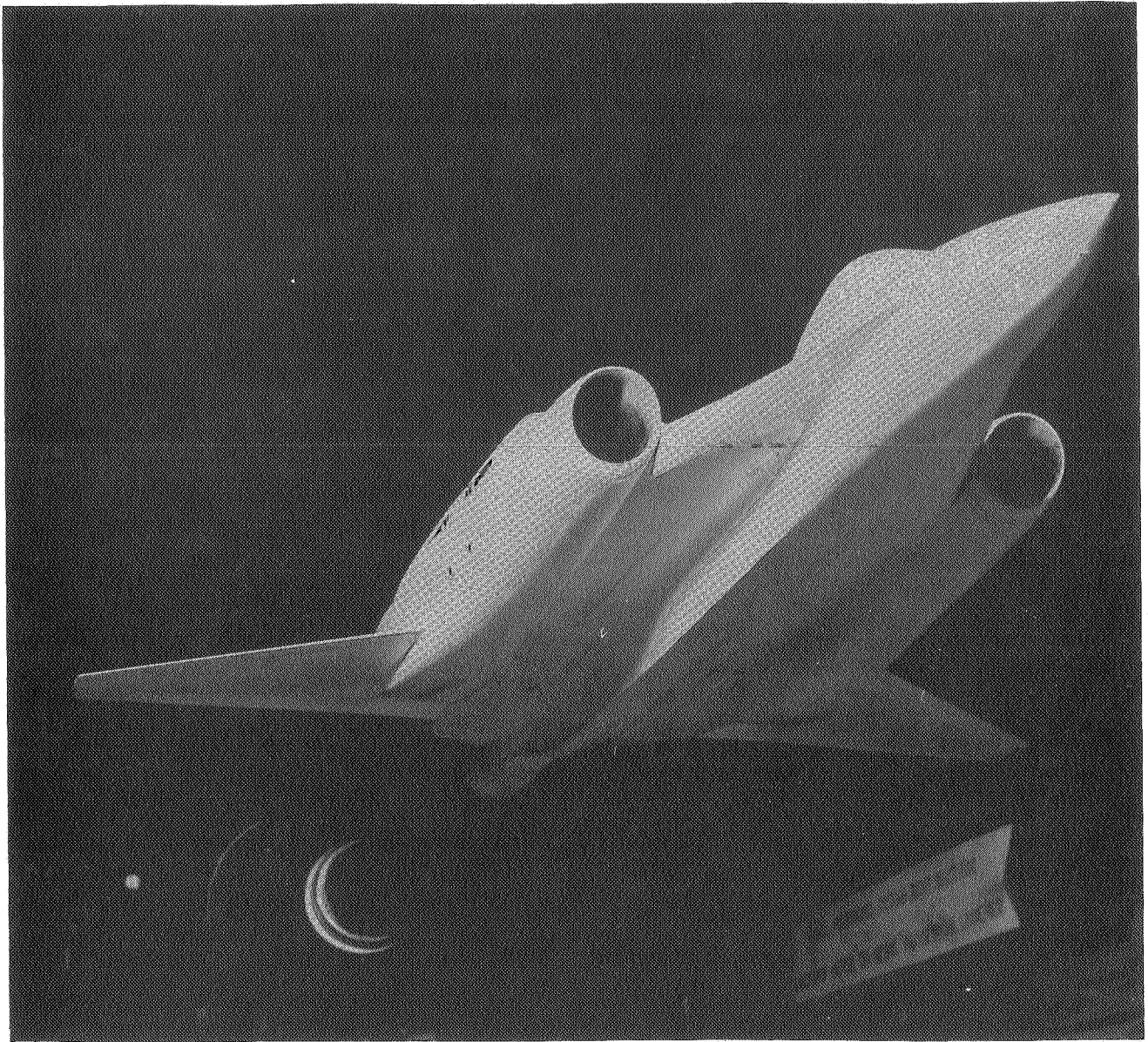
(a) E205 model, R104 body, and components.

Figure 3.- E205 model.



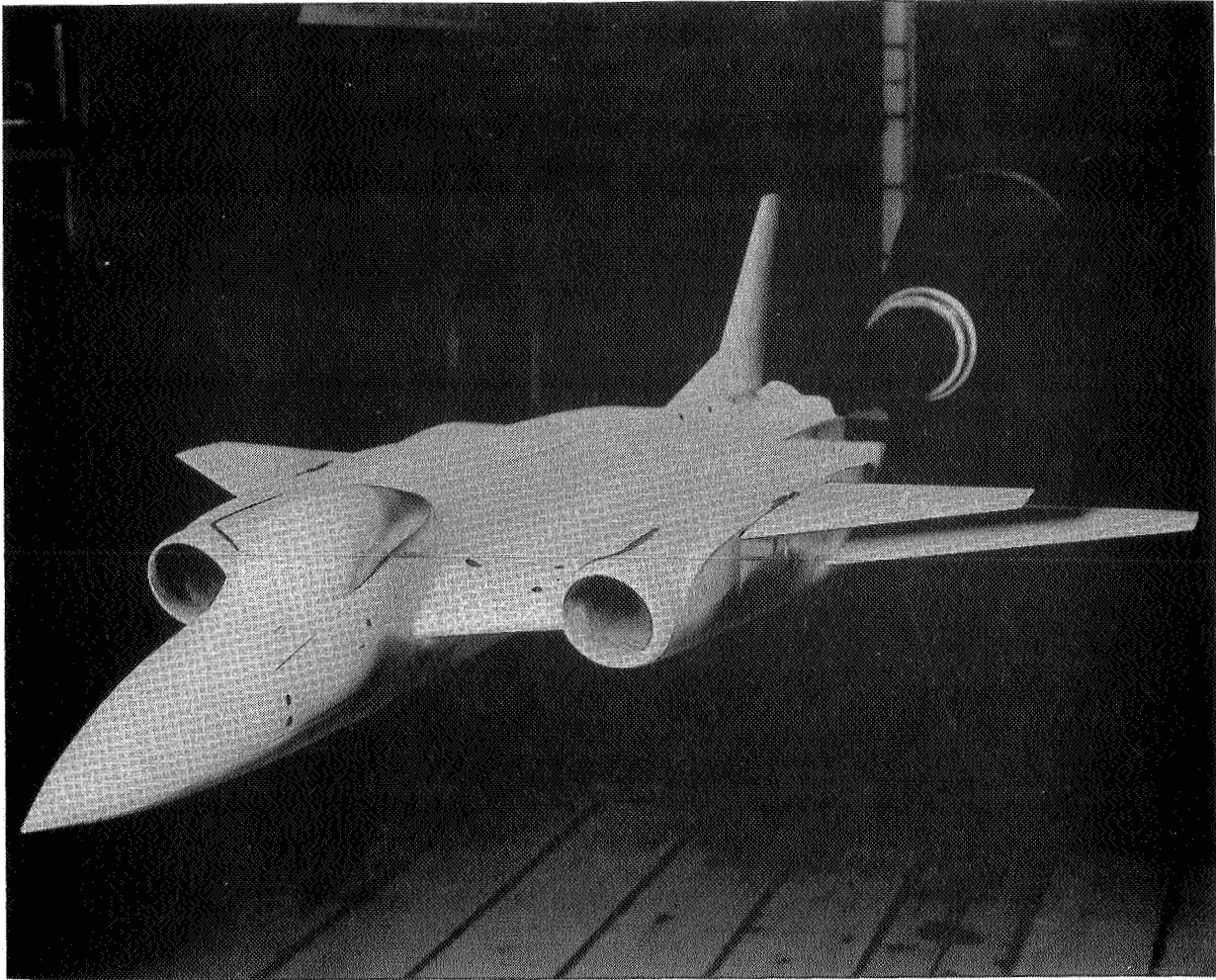
(b) E205 model installed in wind tunnel

Figure 3.- Continued.



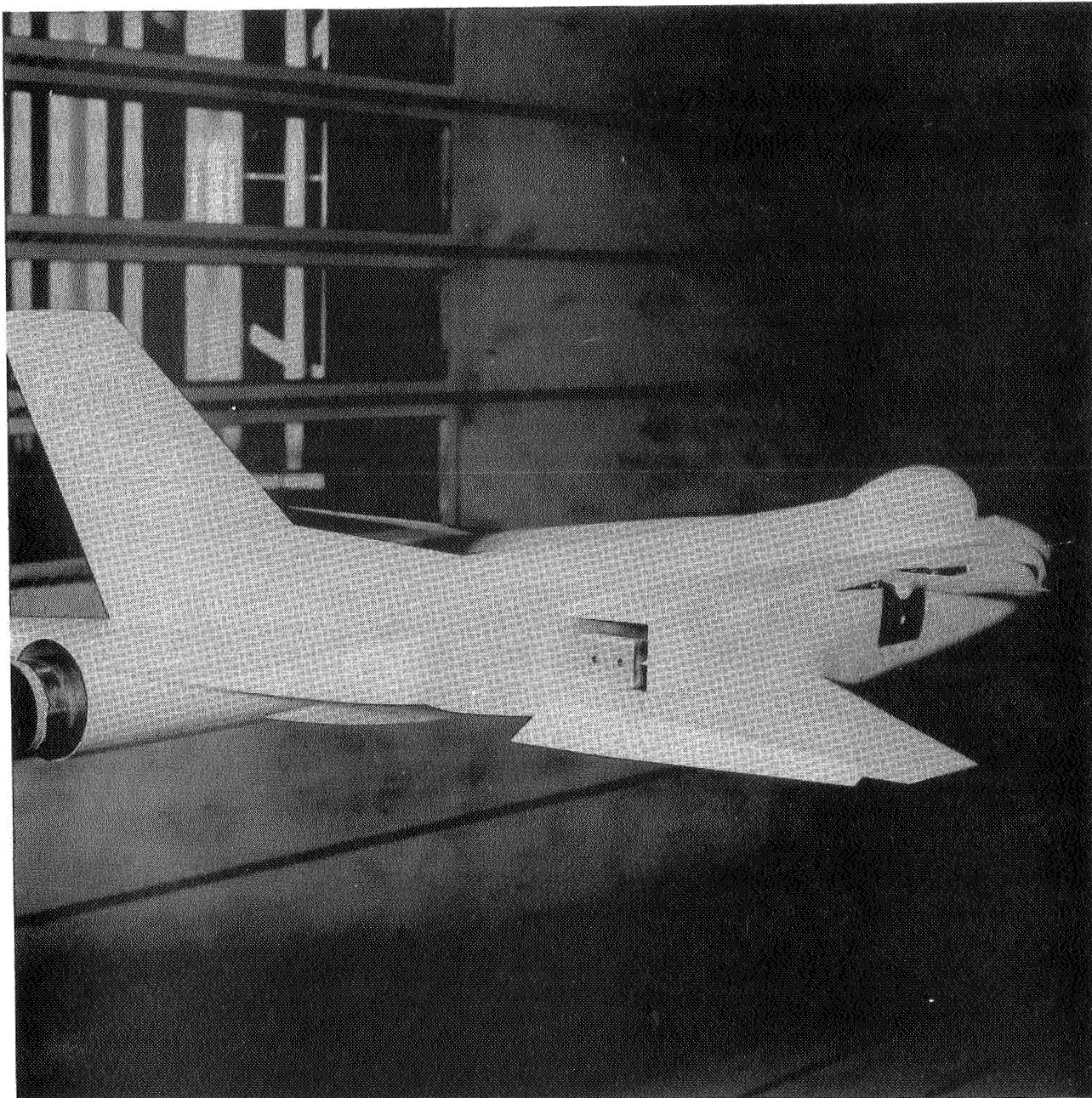
(c) E205 model with canard off.

Figure 3.- Continued.



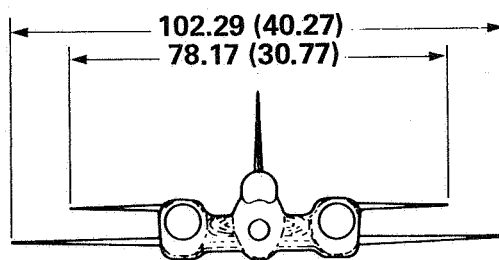
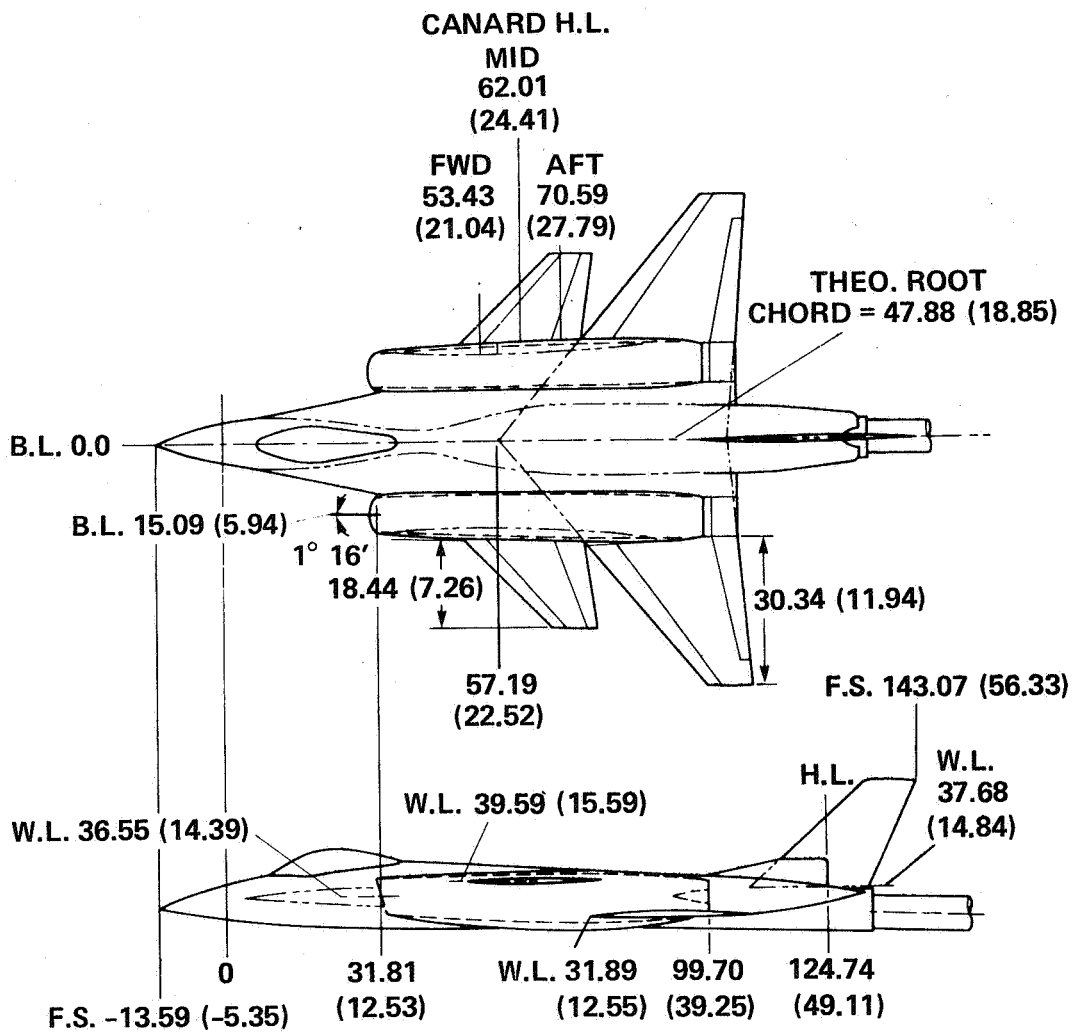
(d) E205 model with strake "off."

Figure 3.- Continued.



(e) E205 model with mid-canard at -10° , wing trailing-edge flaps at 25° .

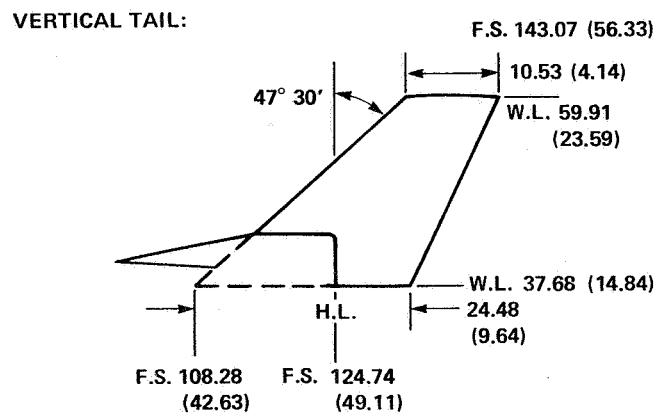
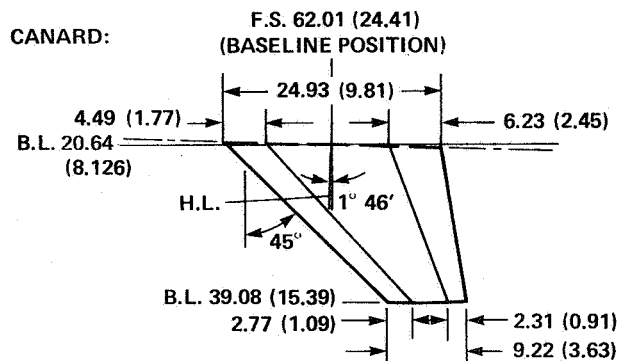
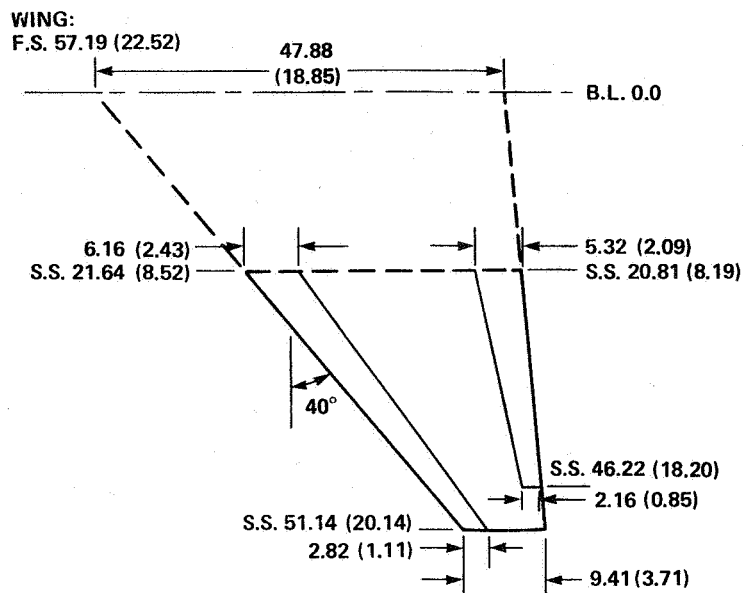
Figure 3.- Concluded.



NOTE: ALL LINEAR DIMENSIONS
ARE IN CENTIMETERS (INCHES).

(a) Three-view drawing.

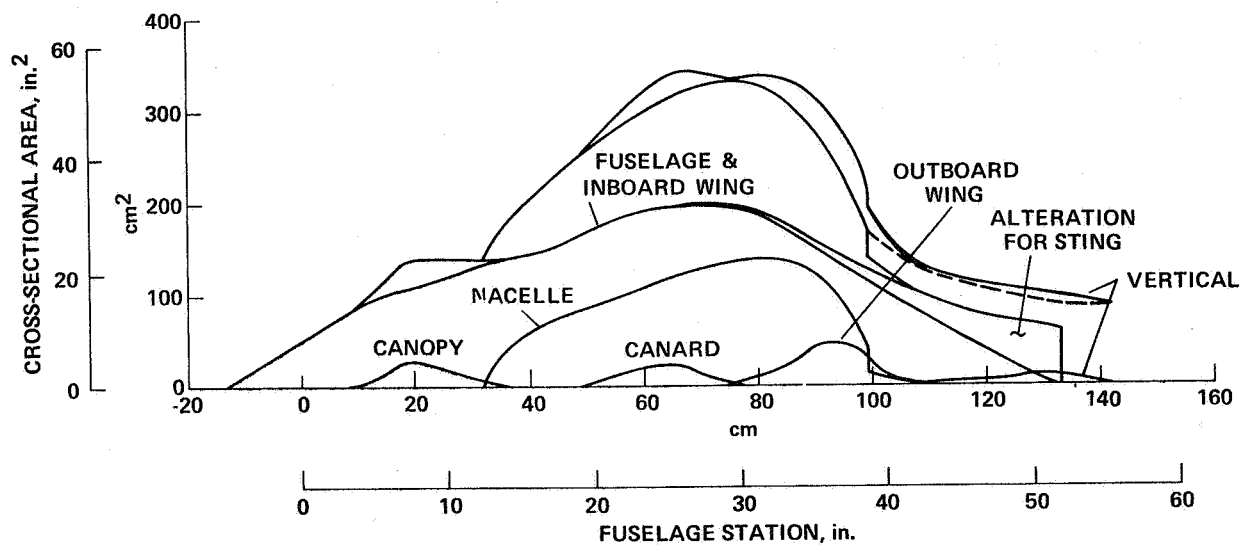
Figure 4.- Details of R104 wind-tunnel model.



NOTE: ALL LINEAR DIMENSIONS
ARE IN CENTIMETERS (INCHES).

(b) Wing, canard, and vertical tail detail.

Figure 4.- Continued.



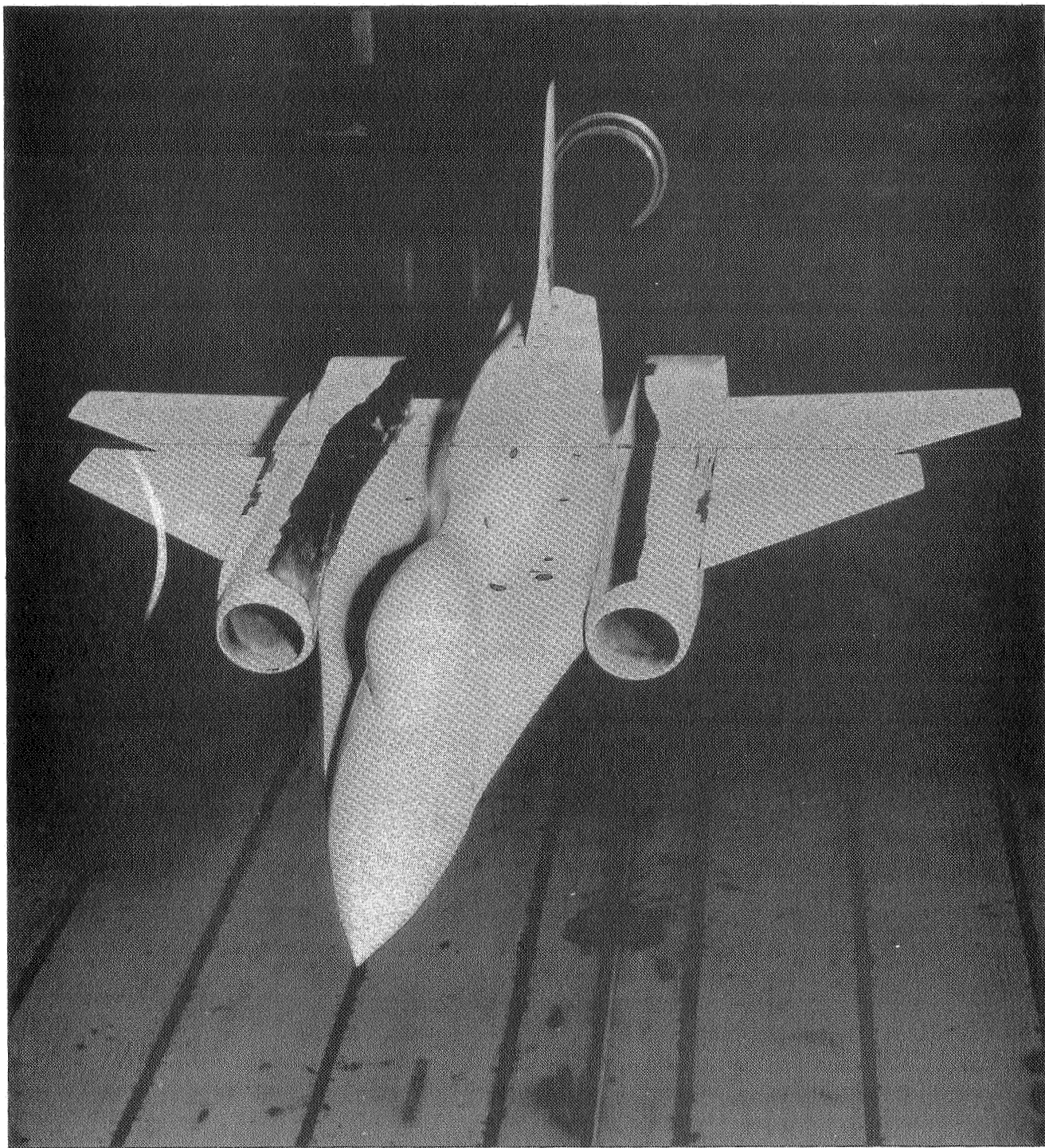
(c) Cross-sectional area distribution.

Figure 4.- Concluded.



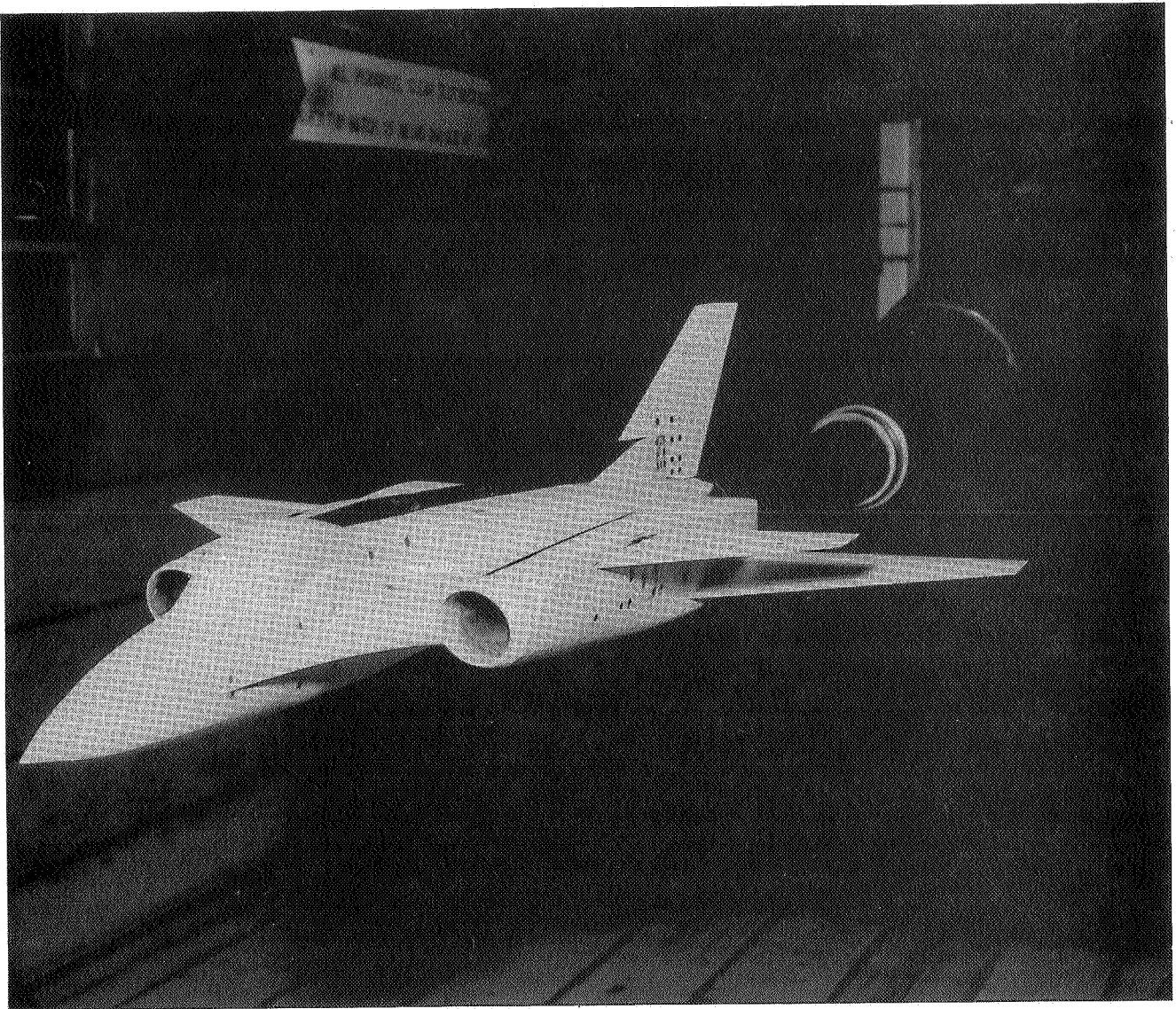
(a) R104 model.

Figure 5.- Views of R104 model.



(b) R104 model with forward canard.

Figure 5.- Continued.



(c) R104 model with vertical tail at 15° .

Figure 5.- Concluded.

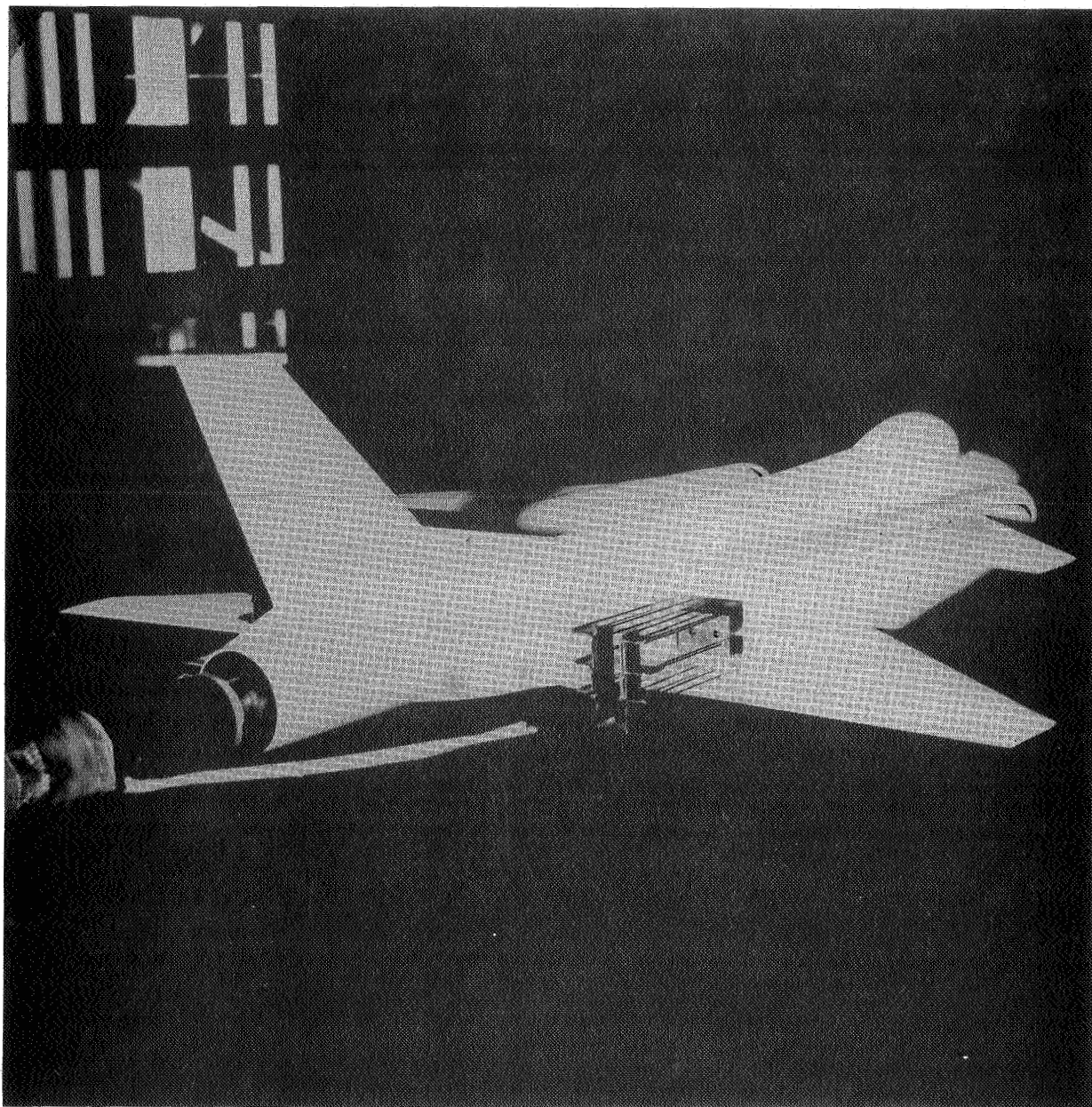


Figure 6.- Duct exit rake installation on E205 model.

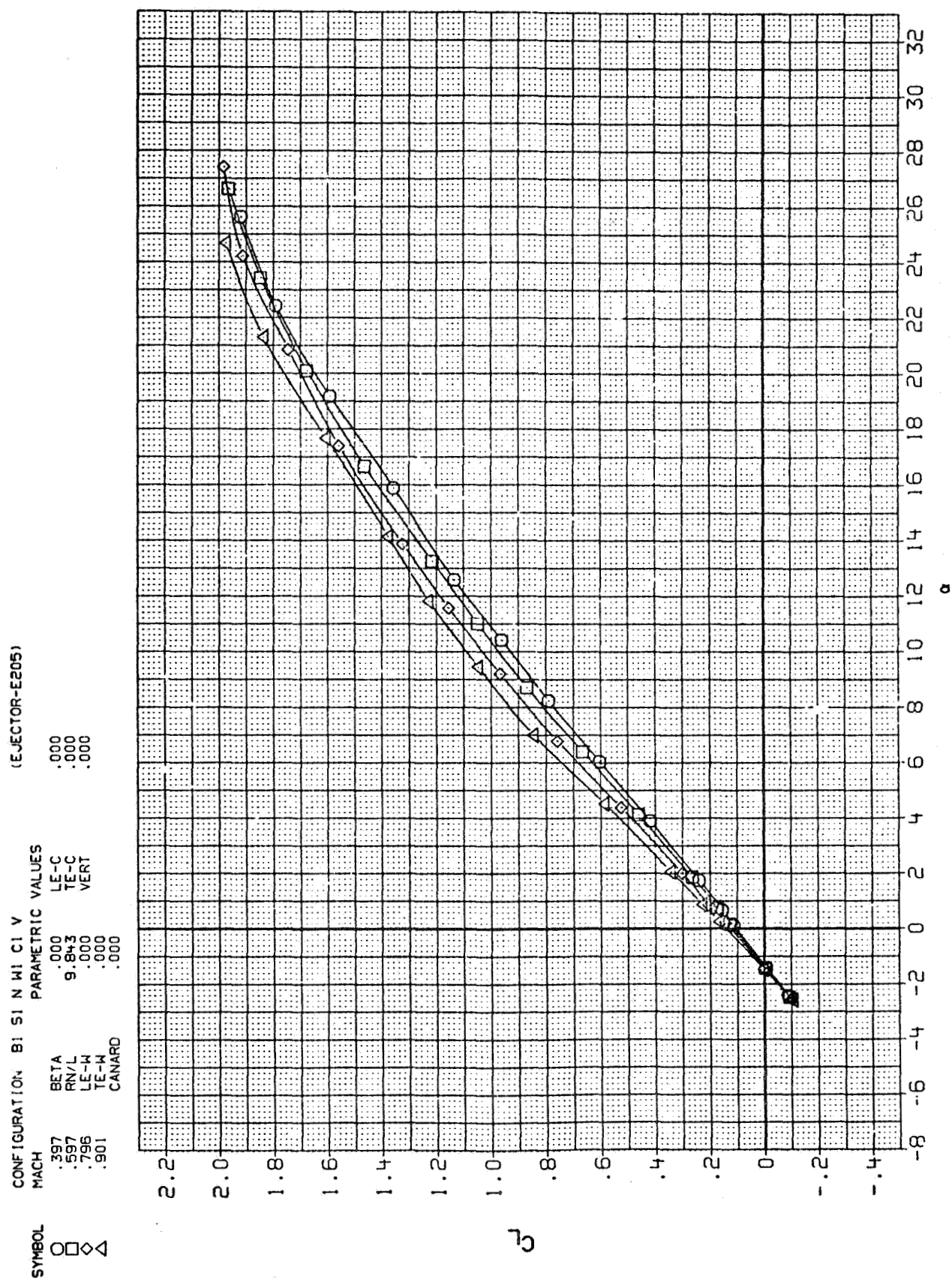


FIG. 7 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(EJECTOR-E205)

CONFIGURATION	BI	SI	N	WI	CI	V
MACH	.945					
BETA	.000					
RN/L	9.843					
LE-W	.000					
TE-W	.000					
CANARD	.000					

SYMBOL
 ○ □ △

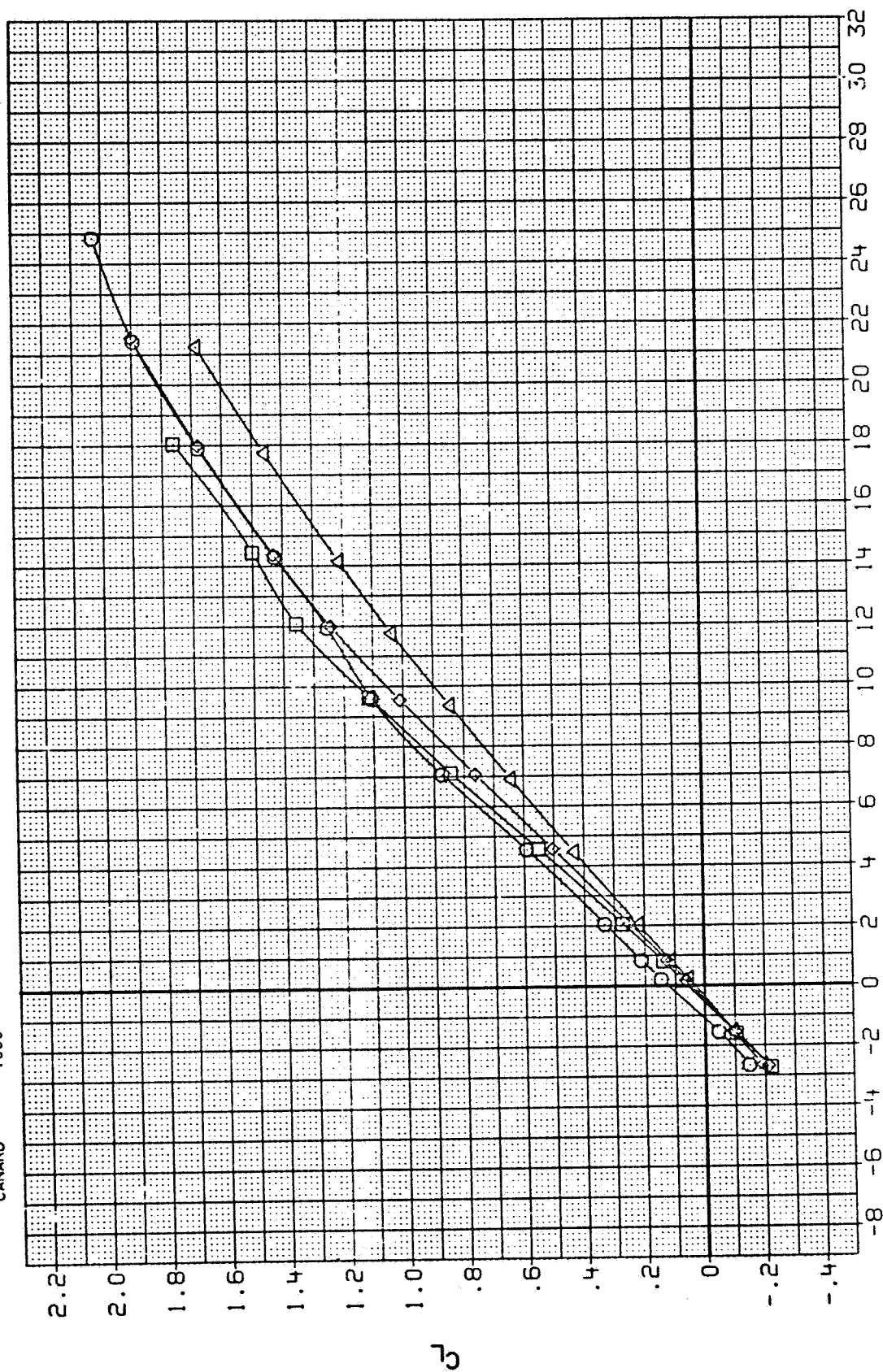


FIG. 7 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(EJECTOR-E205)

CONFIGURATION B I S I N W I C I V

PARAMETRIC VALUES	
BETA	.000
RN/L	9.843
LE-C	.000
TE-C	.000
LE-H	.000
TE-H	.000
CANARD	.000

SYMBOL
 ○ □ △

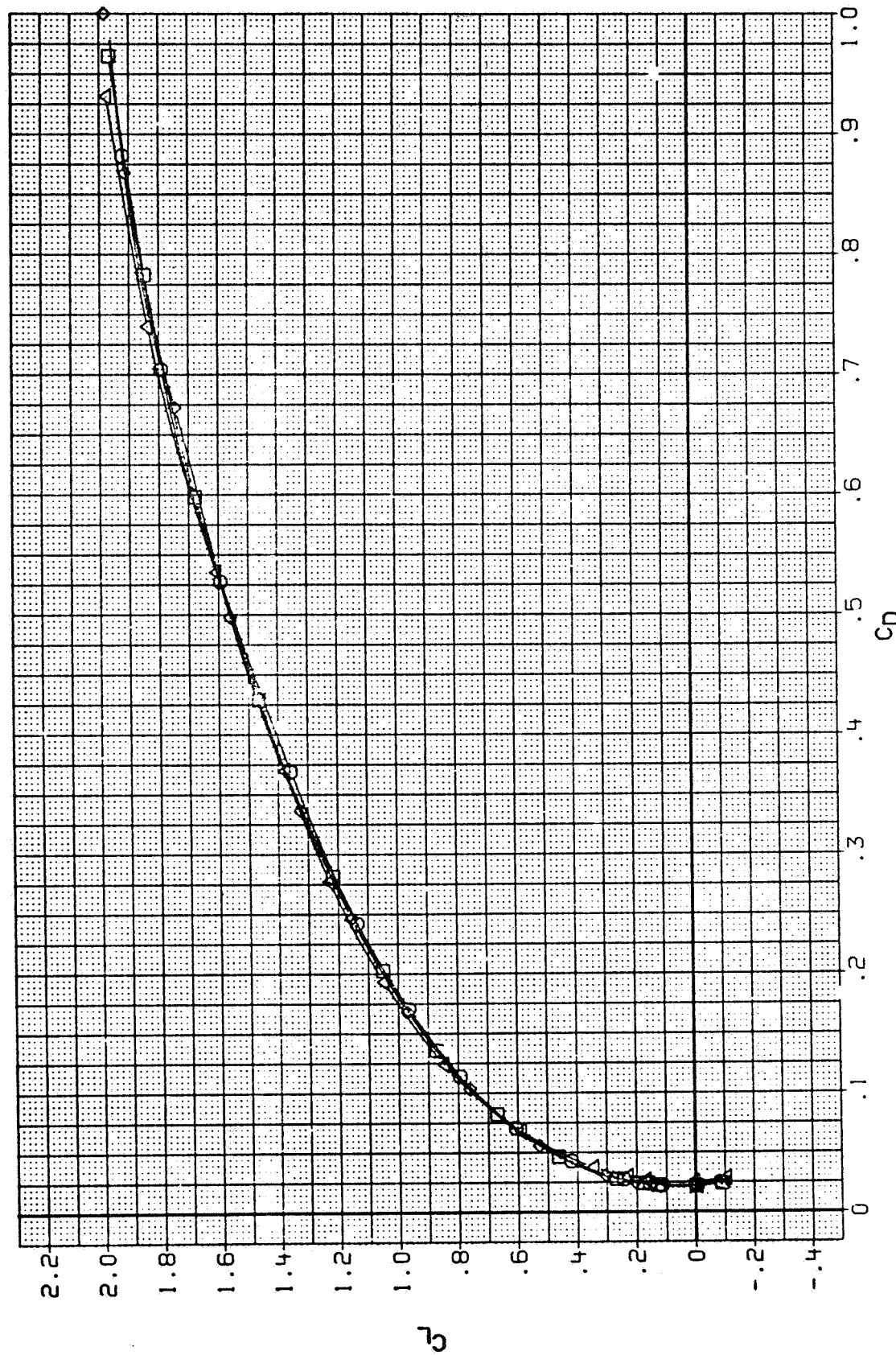


FIG. 7 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(EJECTOR-E205)

CONFIGURATION	BI	SI	N	WI	C1	V
MACH	.945					
BETA	.000					
RN/L	9.843					
LE-W	.030					
TE-W	.000					
CANARD	.000					

PARAMETRIC VALUES

PARAMETRIC VALUES	LE-C	TE-C	VERT
LE-C	.000		
TE-C	.000		
VERT	.000		

SYMBOL

○ □ △

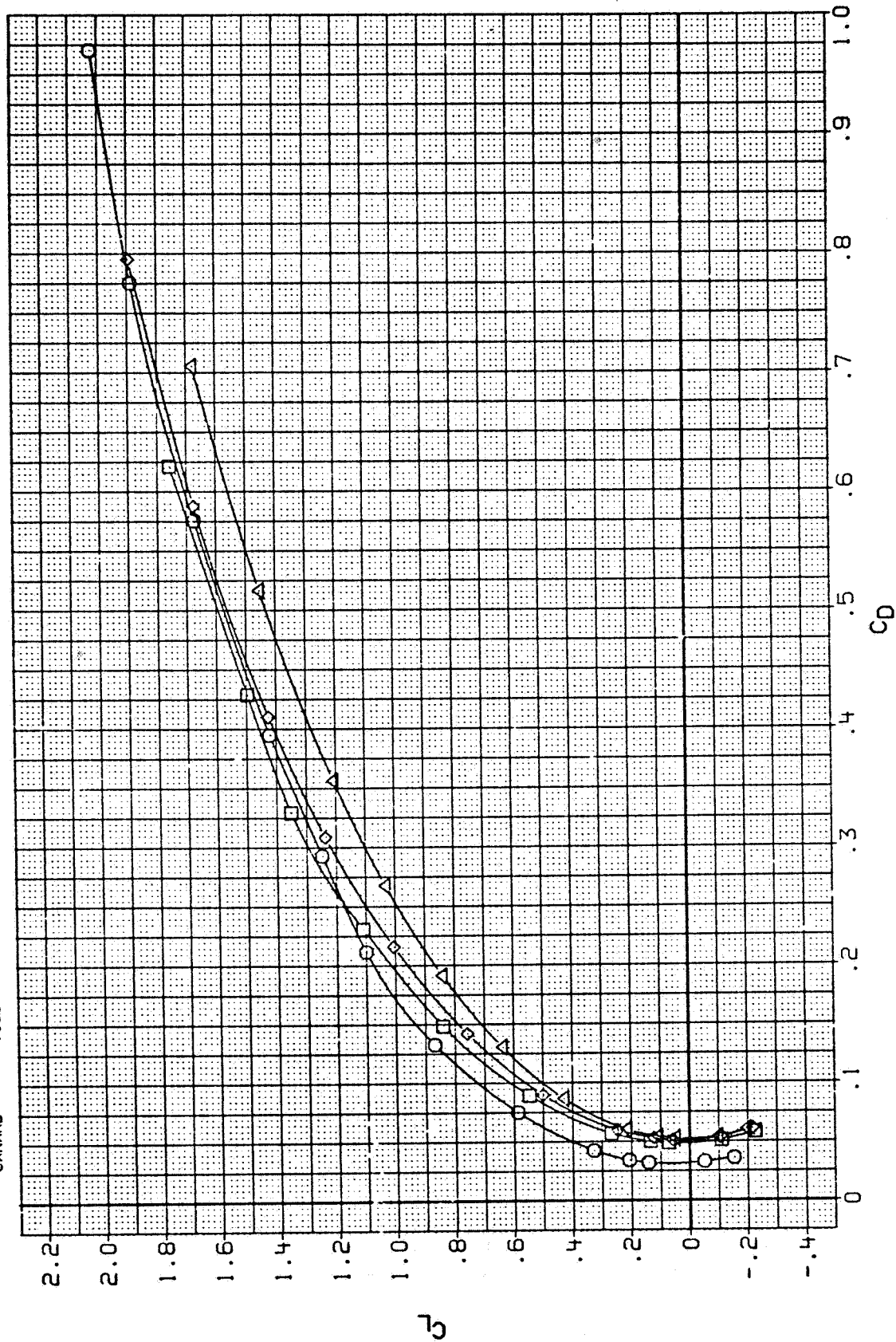


FIG. 7 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(EJECTOR-E205)

CONFIGURATION B I S I N W I C I V		
MACH	BETA	PARAMETRIC VALUES
.397	.000	LE-C
.597	9.843	TE-C
.796	.000	VERT
.901	.000	
	.000	CANARD

SYMBOL
□ ○ △

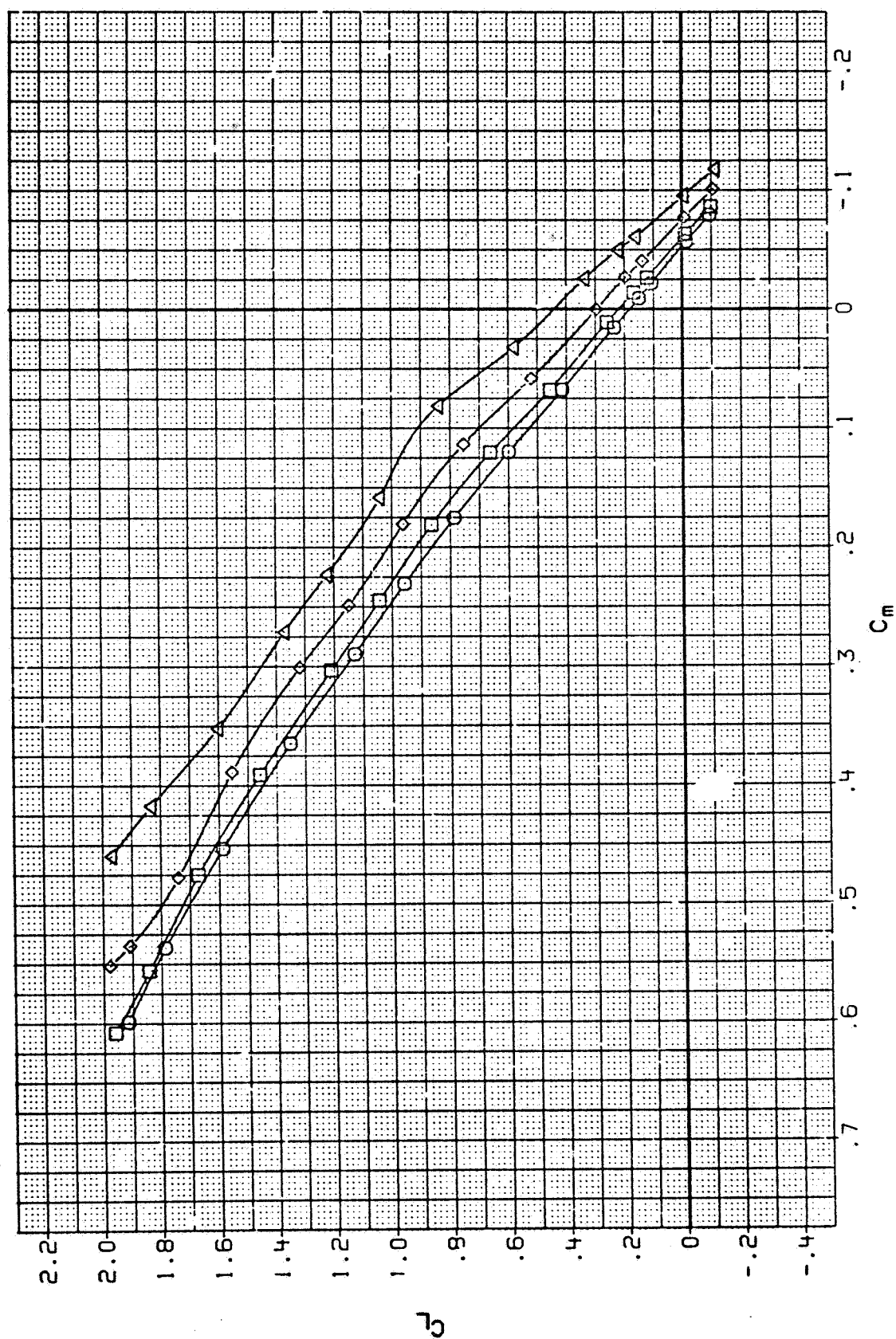


FIG. 7 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

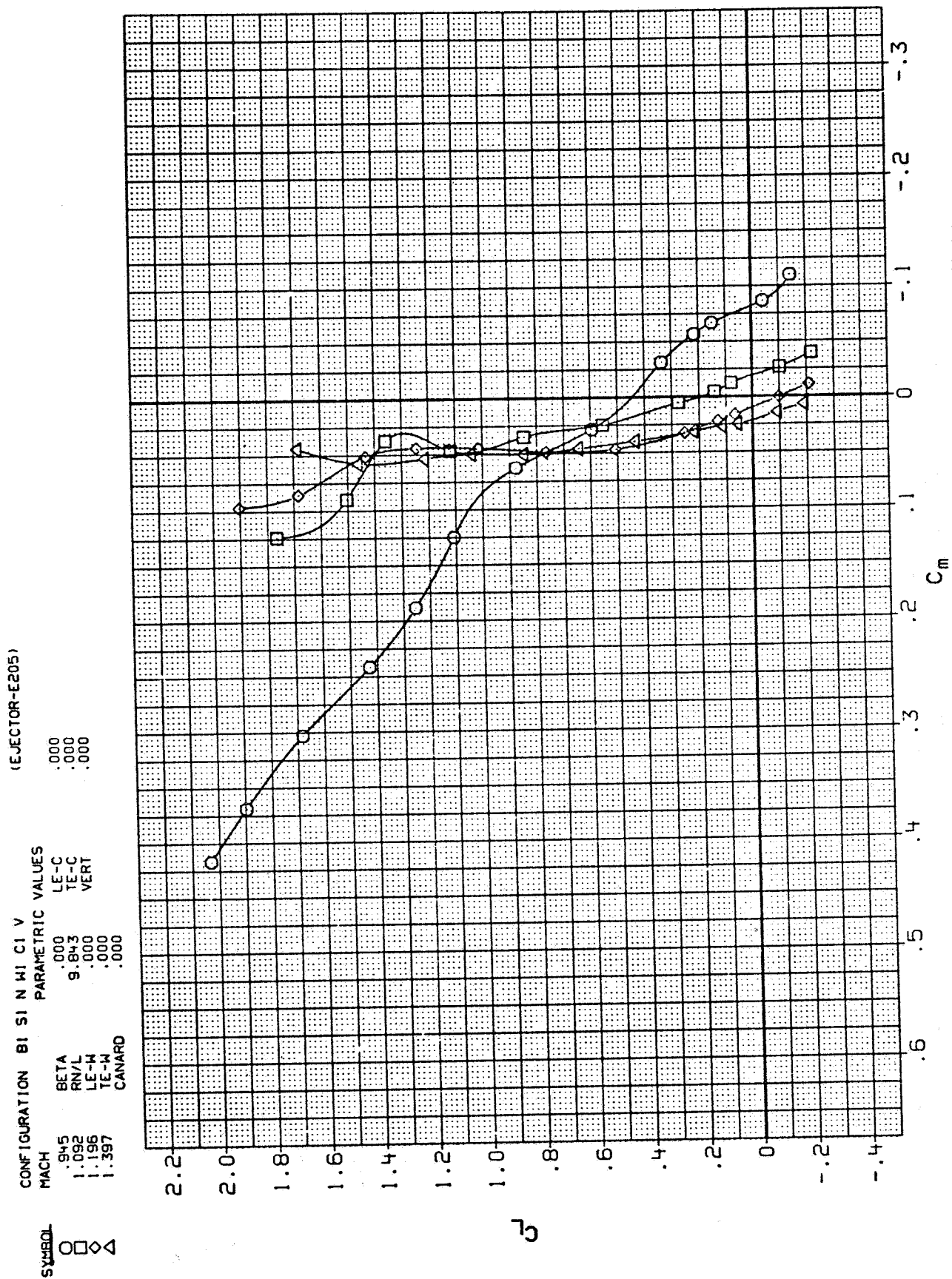


FIG. 7 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

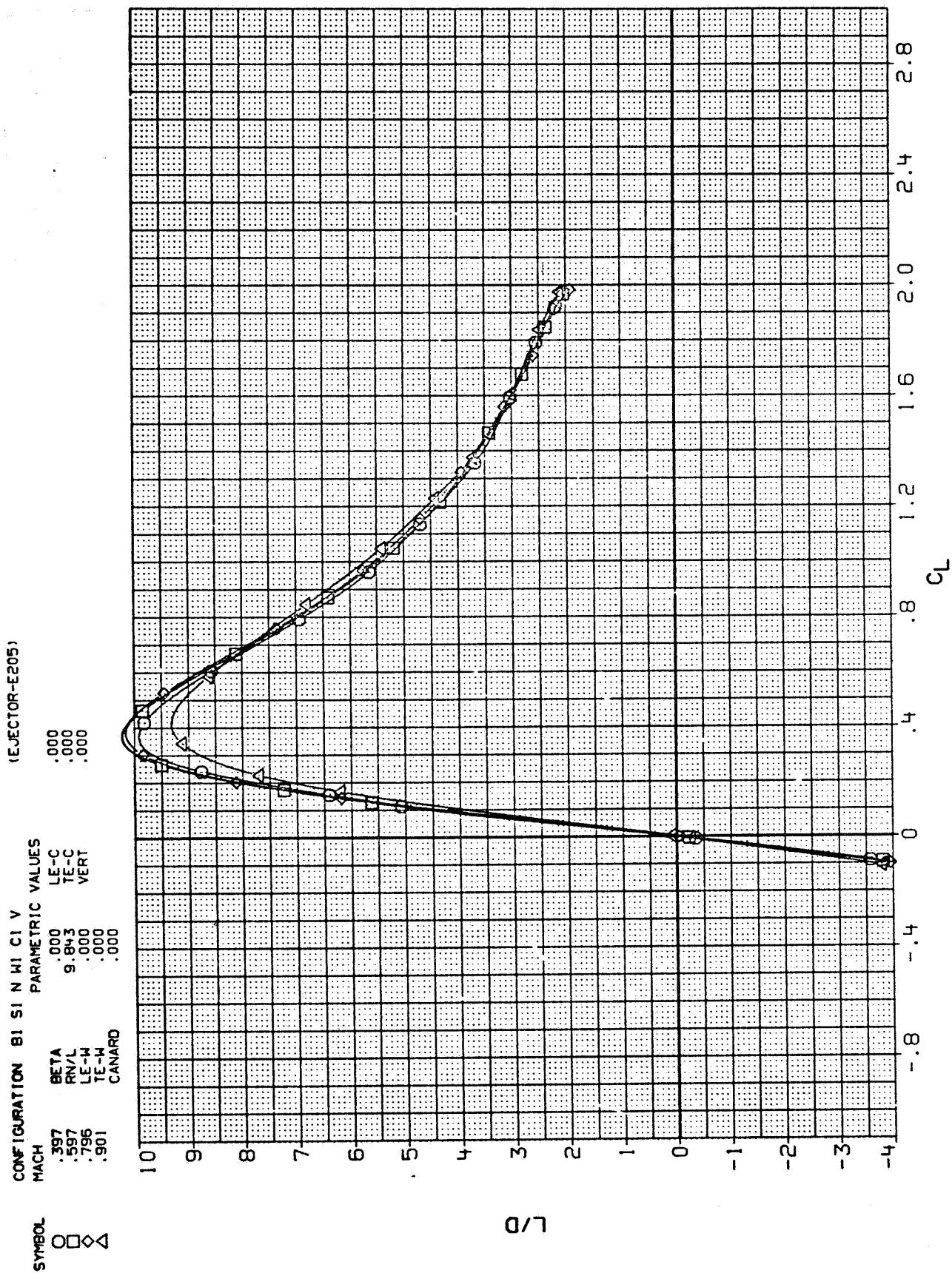


FIG. 7 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(EJECTOR-E205)

CONFIGURATION	BI	SI	N	WI	CI	V
MACH	.845					
BETA	.000					
RN/L	9.843					
LE-W	.000					
TE-W	.000					
CANARD	.000					

PARAMETRIC VALUES	LE-C	TE-C	VERT
	.000	.000	.000

SYMBOL
□ ◇ △

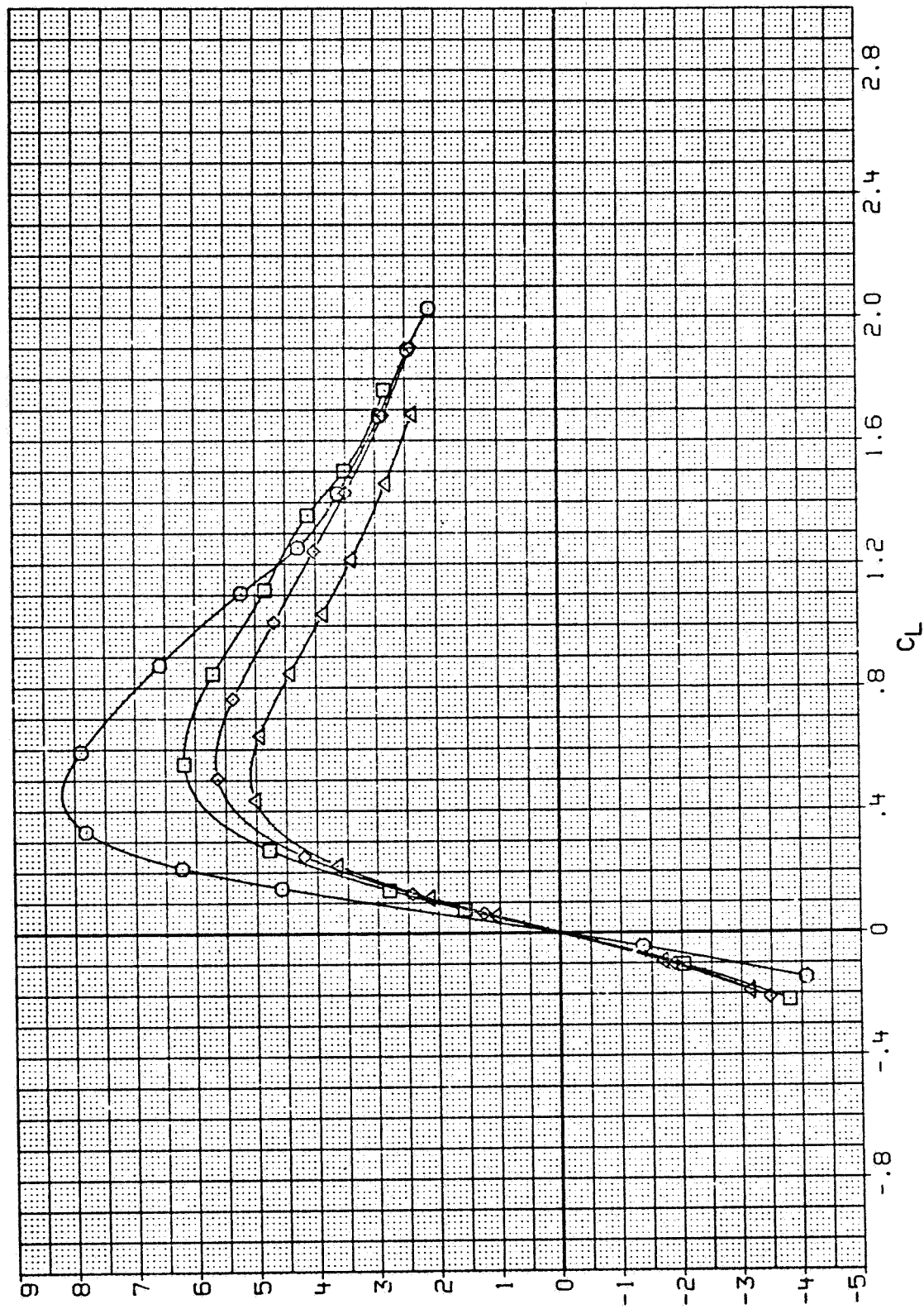


FIG. 7 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

L/D

(EJECTOR-E205)

CONFIGURATION B I S I N W I C I V
PARAMETRIC VALUES

BETA
RN/L
LE-W
TE-W
CANARD

.000
9.843
.000
.000
.000

LE-C
TE-C
VERT

.000
.000
.000
.000

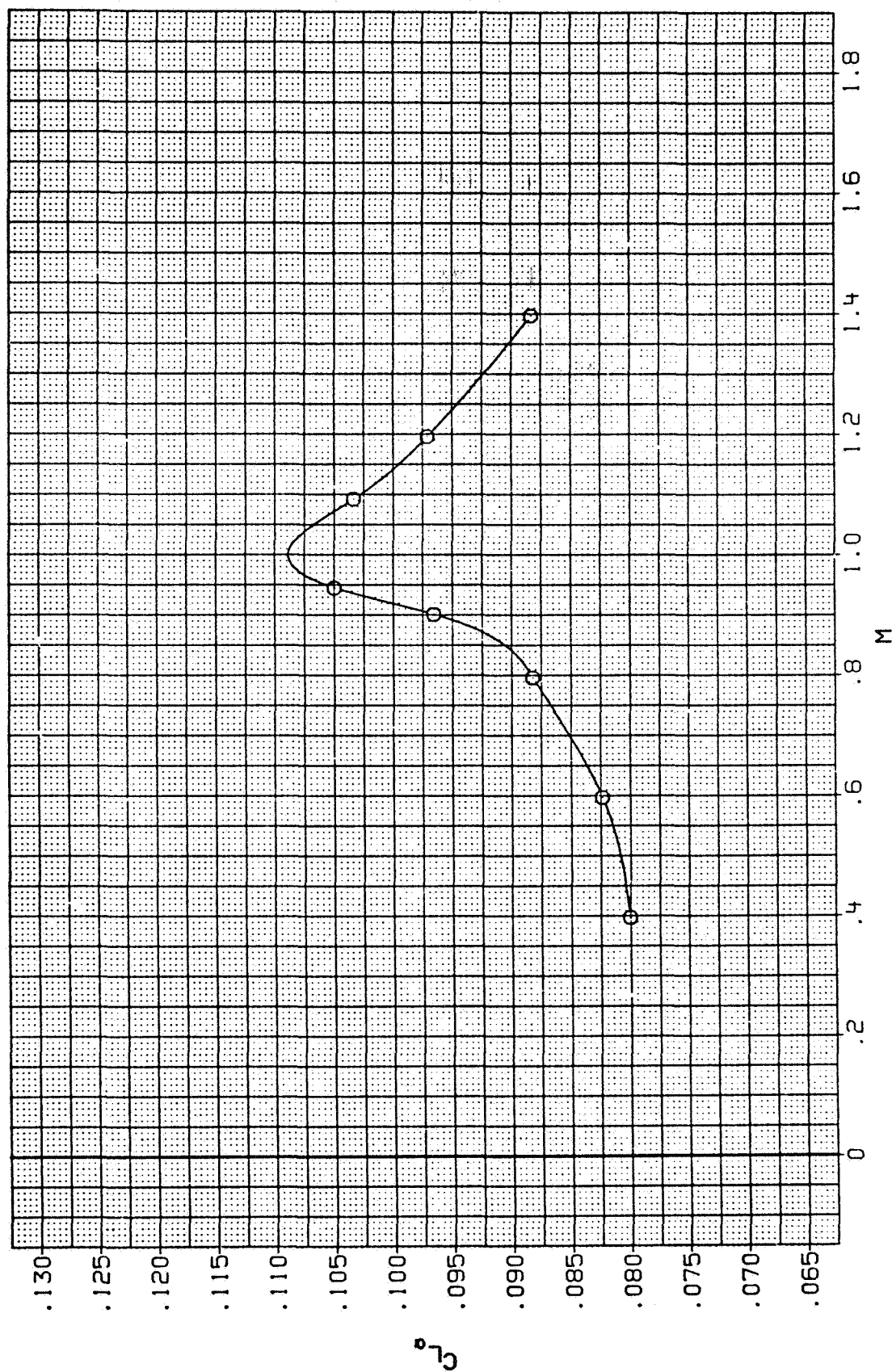


FIG. 8 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

(EJECTOR-E205)

CONFIGURATION B1 S1 N W1 C1 V
 PARAMETRIC VALUES
 BETA .000
 RN/L 9.843
 LE-W .000
 TE-W .000
 CANARD .000
 LE-C .000
 TE-C .000
 VERT .000

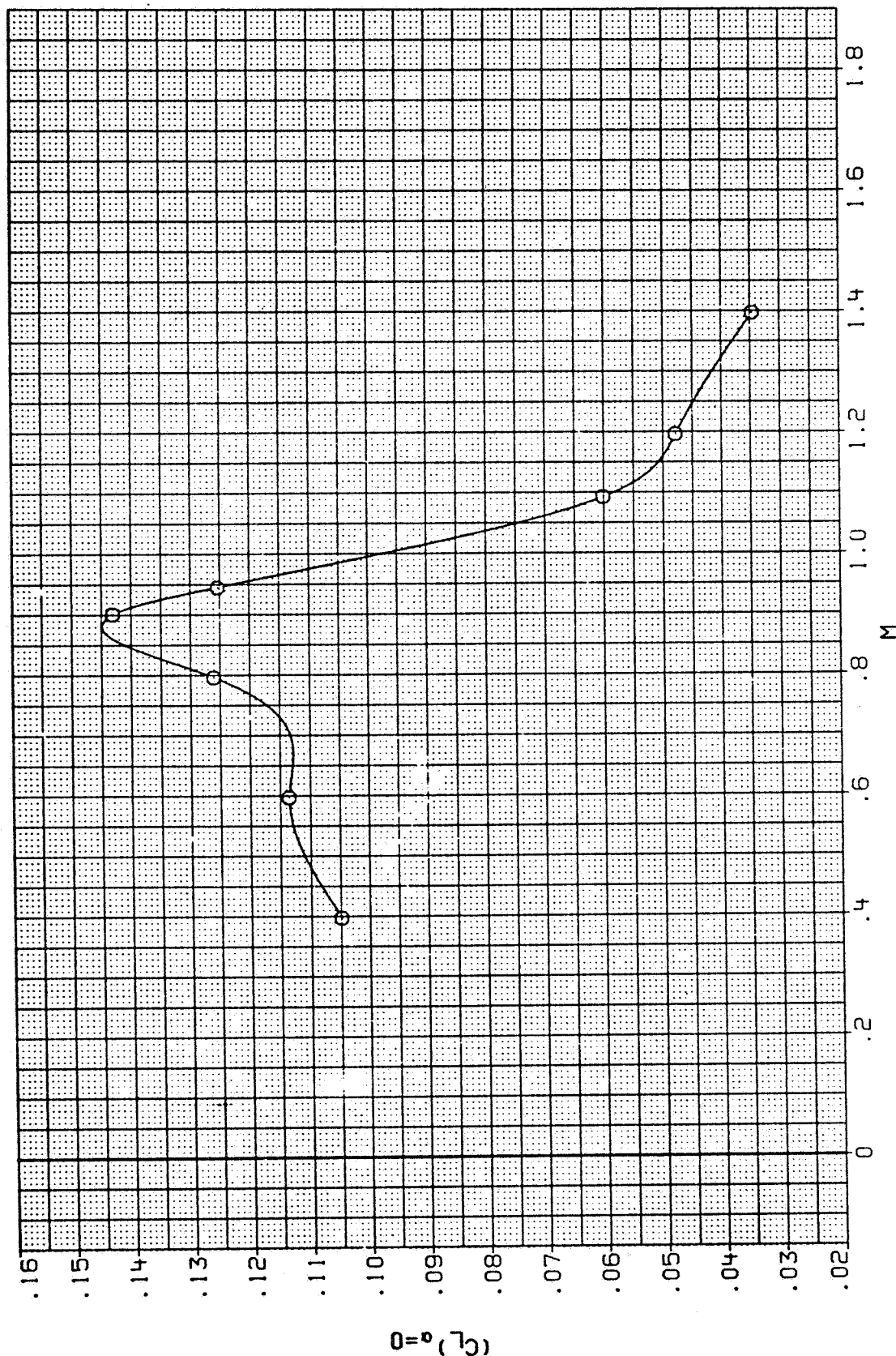


FIG. 8 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

(EJECTOR-E205)

CONFIGURATION B I S I N W I C I V
PARAMETRIC VALUES
BETA .000
RN/L 9.843
LE-W .000
TE-W .000
CANARD .000
LE-C .000
TE-C .000
VERT .000

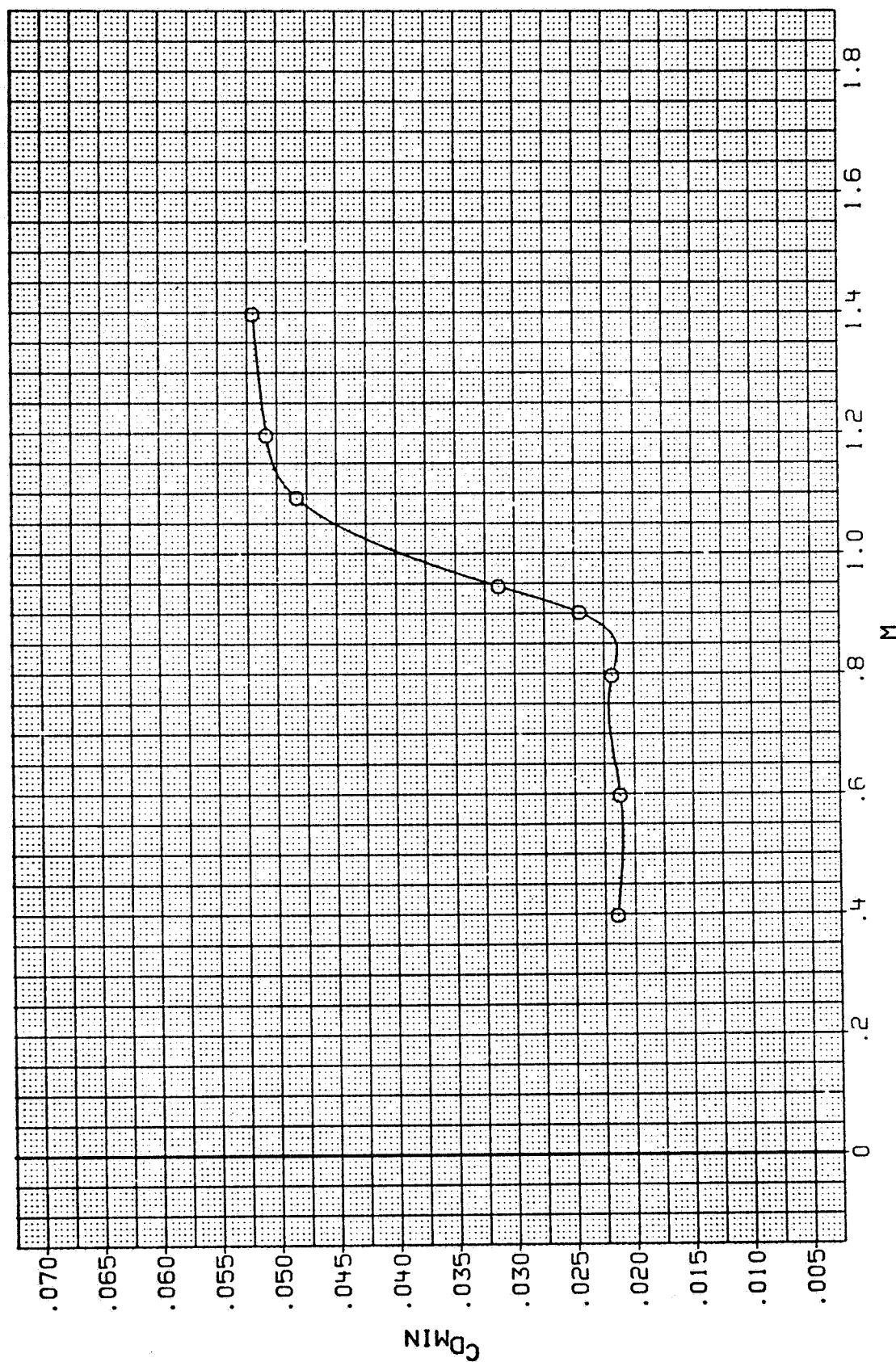


FIG. 8 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

(EJECTOR-E205)

CONFIGURATION B I S I N W I C I V
PARAMETRIC VALUES
BETA .000
RN/L 9.843
LE-W .000
TE-W .000
CANARD .000
LE-C .000
TE-C .000
VERT .000

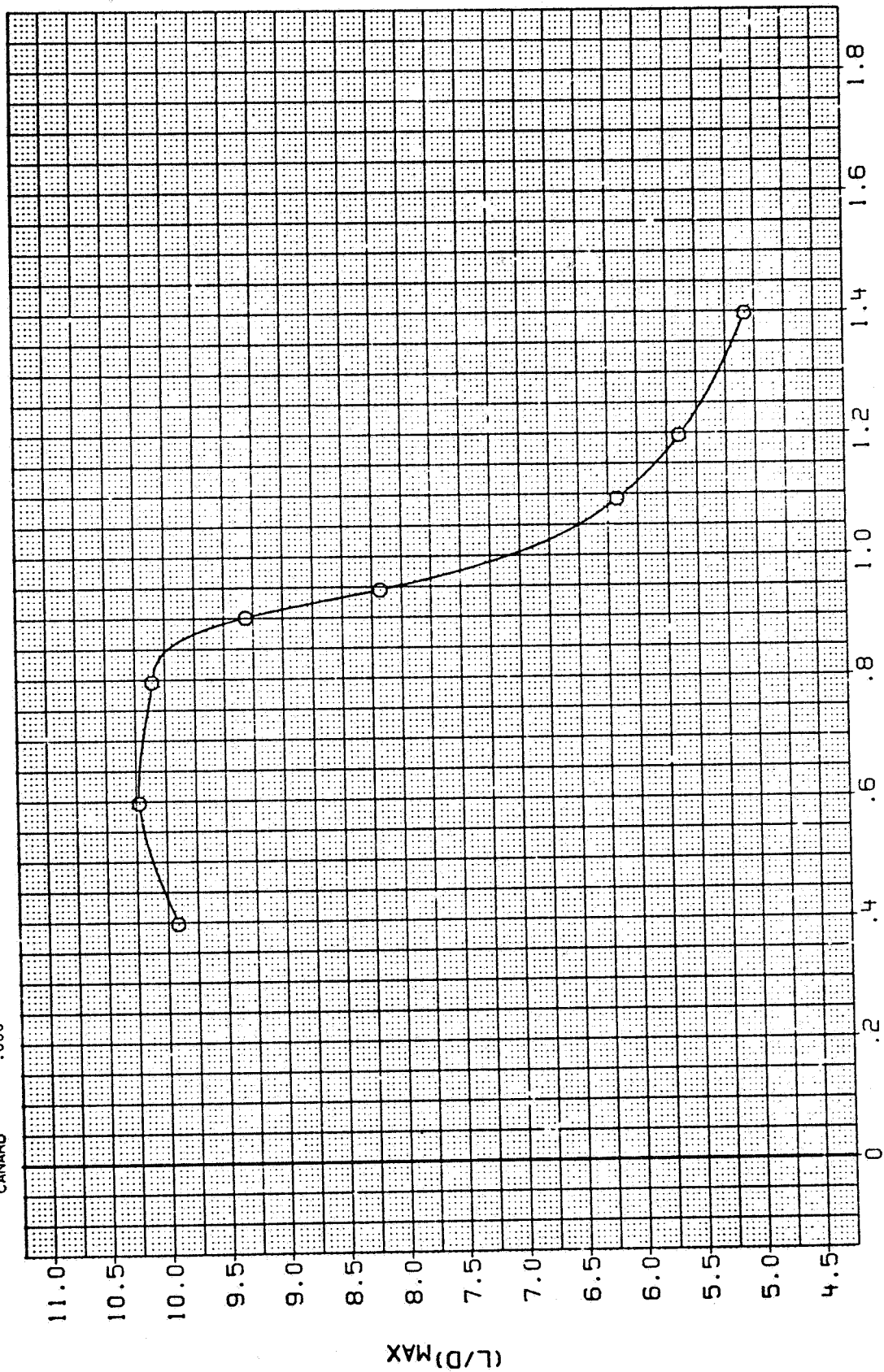


FIG. 8 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

(EJECTOR-E205)

CONFIGURATION BI SI N WI C1 V
PARAMETRIC VALUES
BETA .000
RN/L 9.843
LE-W .000
TE-W .000
CANARD .000

LE-C .000
TE-C .000
VERT .000

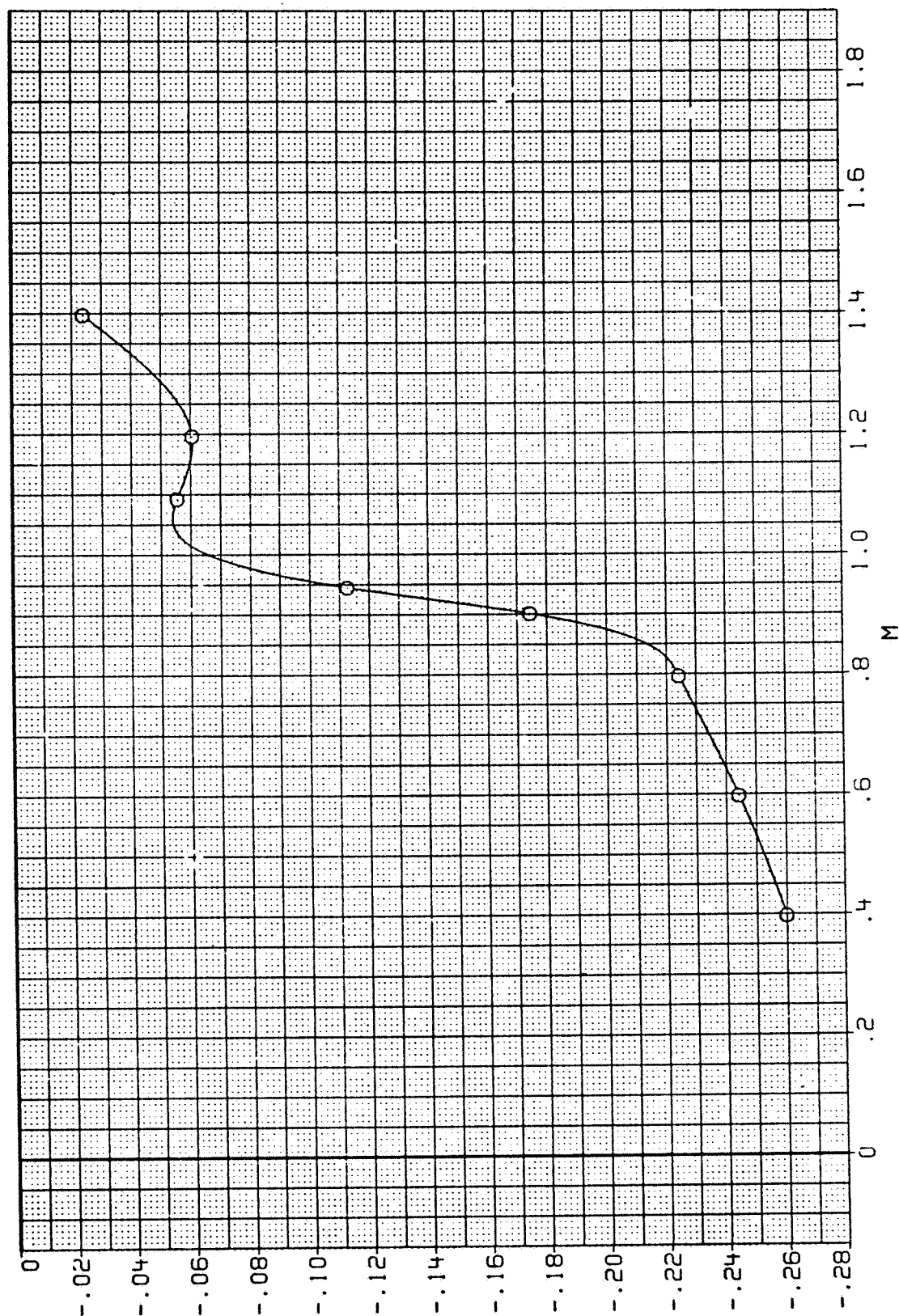


FIG. 8 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

A.C.

(EJECTOR-E205)

CONFIGURATION B I S I N H I C I Y
 PARAMETRIC VALUES
 BETA .000
 RN/L 9.843
 LE-H .000
 TE-H .000
 CANARD .000

LE-C .000
 TE-C .000
 VERT .000

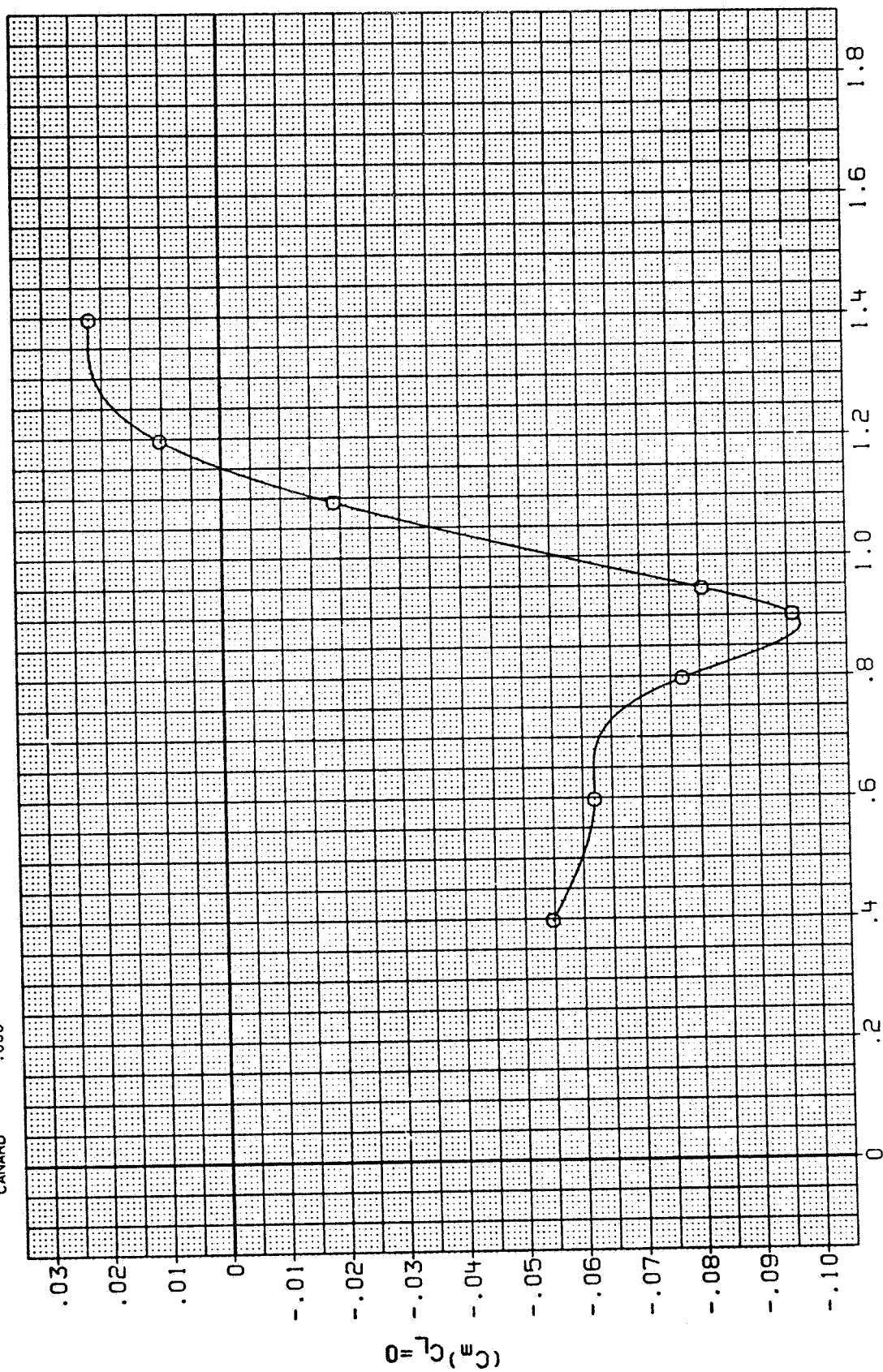


FIG. 8 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

SYMBOL

BI SI N HI CI V

DATA NOT AVAILABLE

BI SI N HI CI V

DATA NOT AVAILABLE

BI SI N HI CI V

CONFIGURATION

(EJECTOR-E205)

(EJECTOR-E205)

(EJECTOR-E205)

RN/L

9.843

13.123

14.764

16.404

19.685

22.966

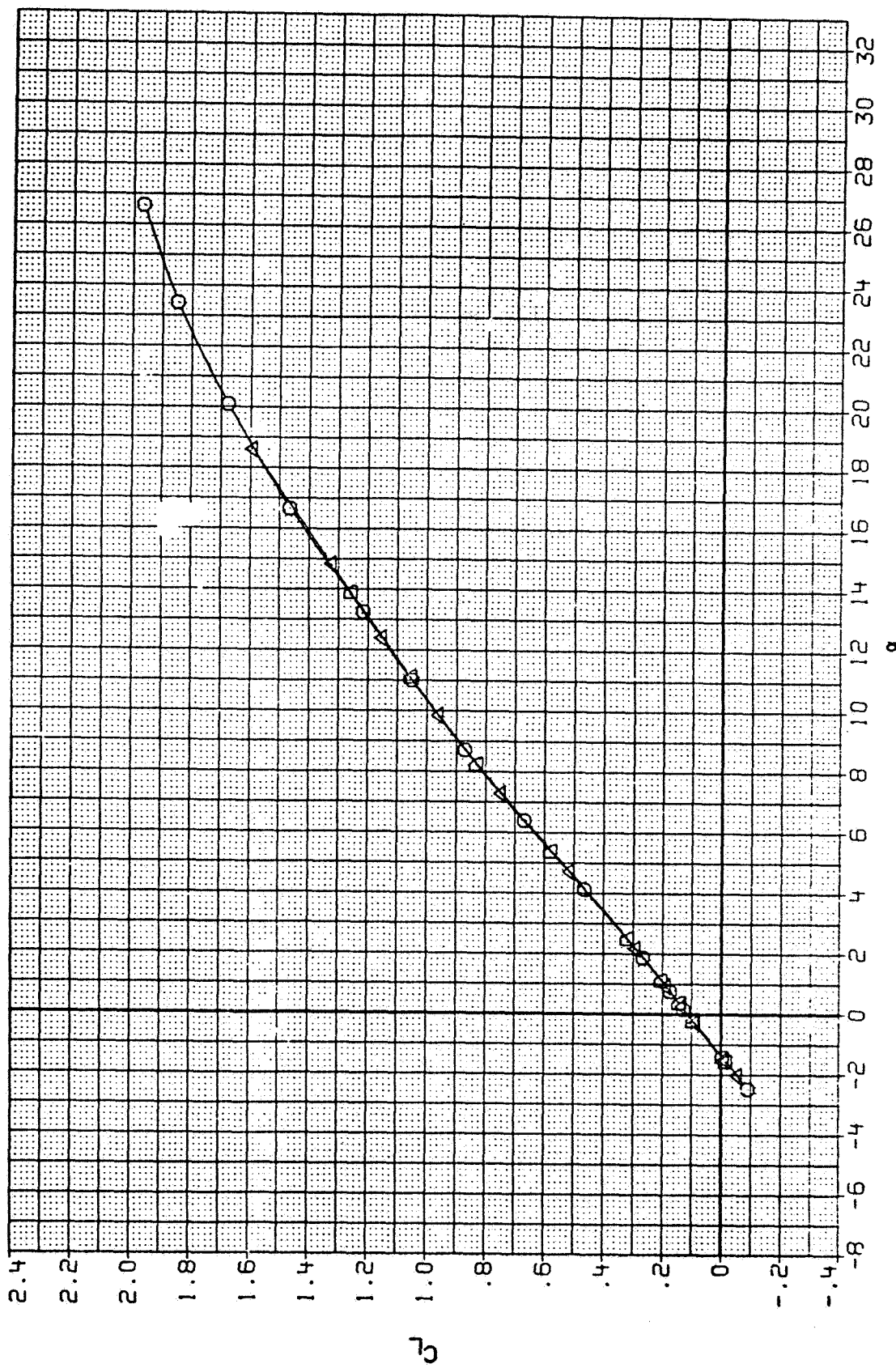
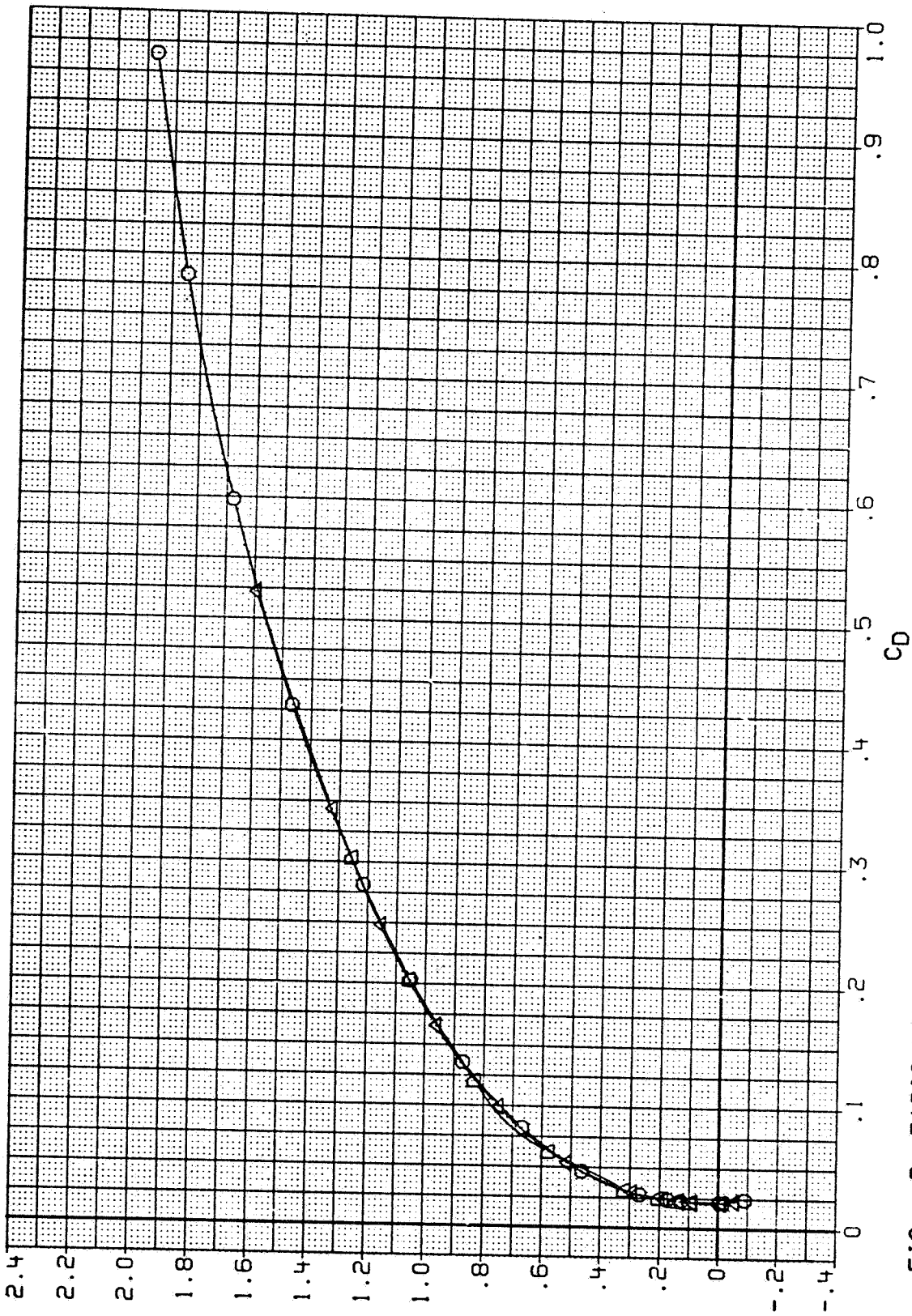


FIG. 9 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS REYNOLDS NUMBERS

MACH = .60

SYMBOL	CONFIGURATION	RN/L
BI SI N WI CI V	(EJECTOR-E205)	9.843
DATA NOT AVAILABLE		13.123
BI SI N WI CI V	(EJECTOR-E205)	14.764
DATA NOT AVAILABLE		16.404
BI SI N WI CI V	(EJECTOR-E205)	19.685
DATA NOT AVAILABLE		22.966



SYMBOL	CONFIGURATION	RN/L
BI SI N HI CI V	(EJECTOR-E205)	9.843
DATA NOT AVAILABLE		13.123
DATA NOT AVAILABLE		14.754
BI SI N HI CI V	(EJECTOR-E205)	16.404
DATA NOT AVAILABLE		19.685
BI SI N HI CI V	(EJECTOR-E205)	22.956

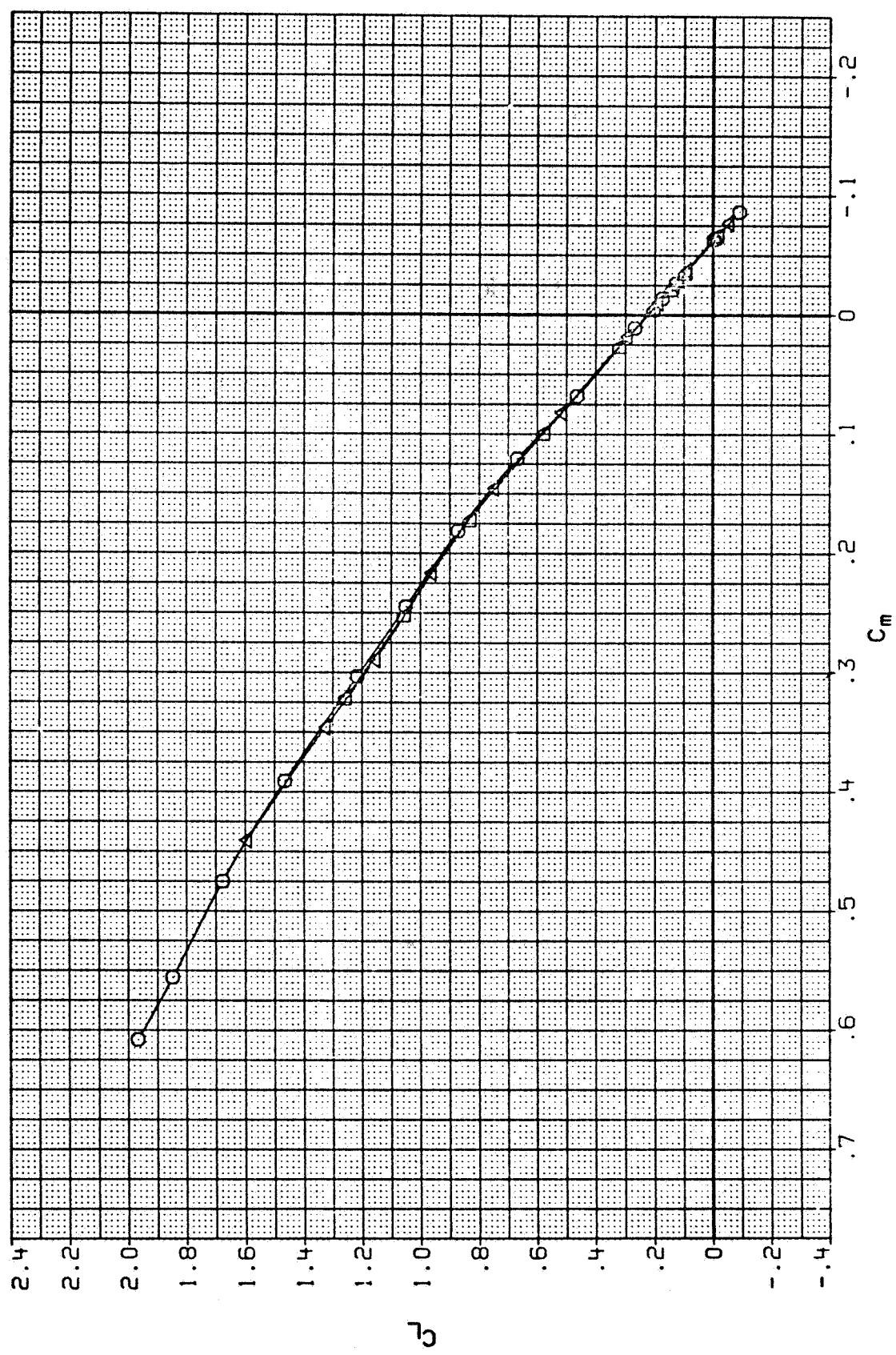


FIG. 9 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS REYNOLDS NUMBERS

MACH = .60

SYMBOL	CONFIGURATION	RN/L
□	BI SI N WI CI V	9.843
□	(EJECTOR-E205)	13.123
◇	DATA NOT AVAILABLE	14.764
◇	DATA NOT AVAILABLE	16.404
△	BI SI N WI CI V	19.685
△	(EJECTOR-E205)	22.966
△	DATA NOT AVAILABLE	
△	BI SI N WI CI V	
△	(EJECTOR-E205)	

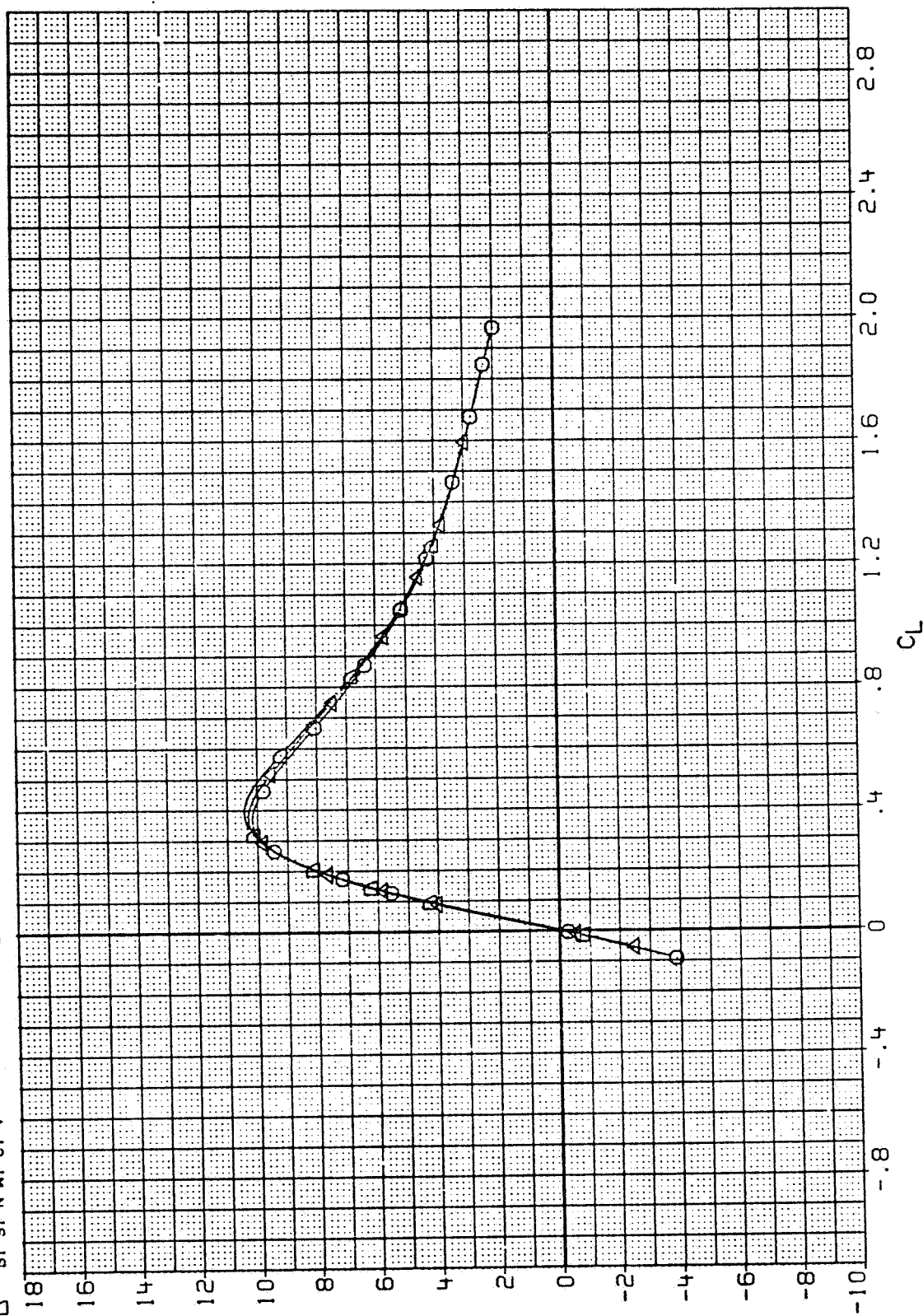


FIG. 9 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS REYNOLDS NUMBERS

MACH = .60

SYMBOL BI SI N WI CI V CONFIGURATION (EJECTOR-E205) RN/L
 ○ DATA NOT AVAILABLE (EJECTOR-E205) 9.843
 ◇ BI SI N WI CI V (EJECTOR-E205) 13.123
 △ DATA NOT AVAILABLE (EJECTOR-E205) 14.764
 □ BI SI N WI CI V 16.404
 DATA NOT AVAILABLE 19.685
 22.966

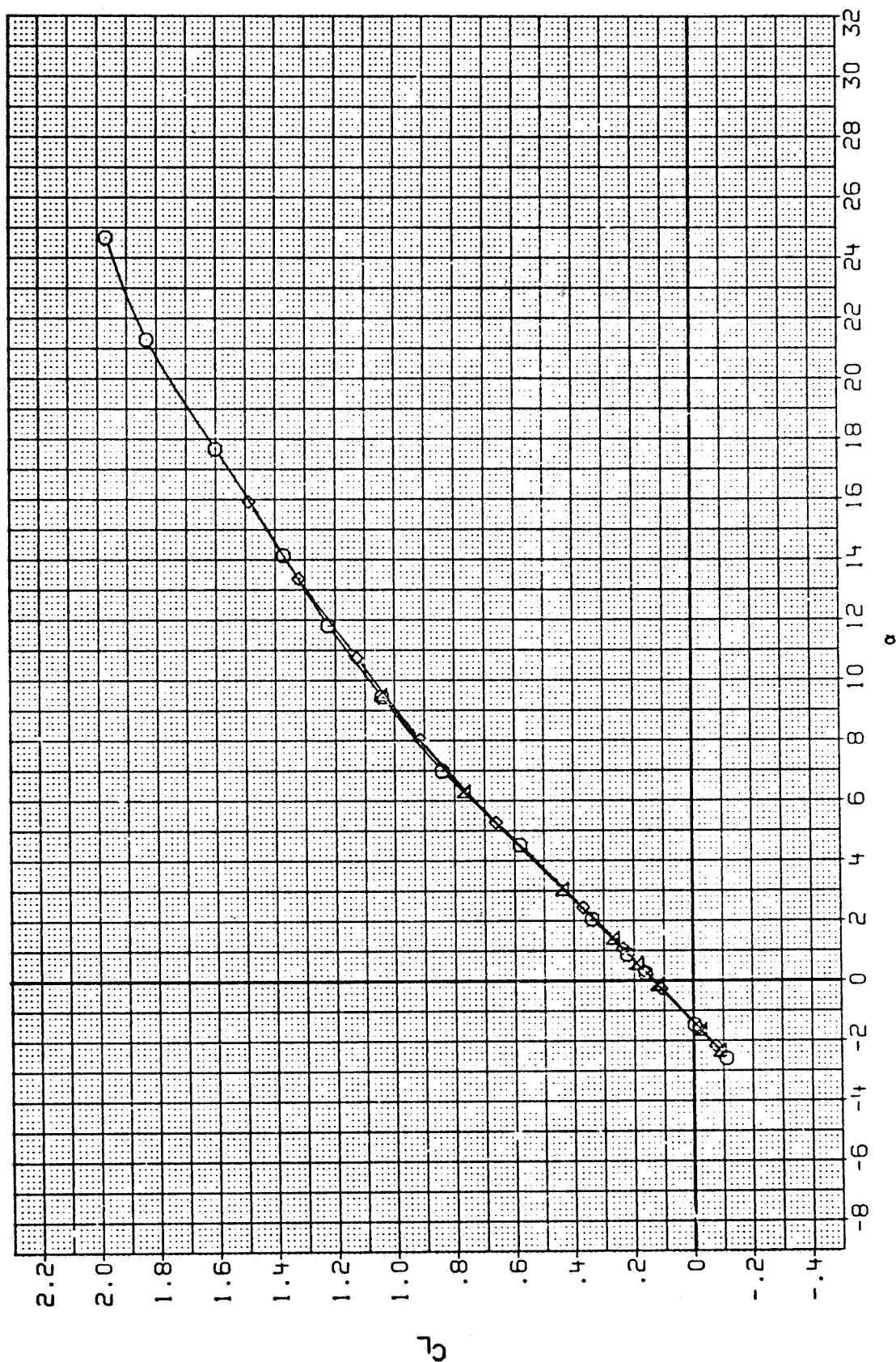


FIG. 10 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS REYNOLDS NUMBERS

MACH = .90

SYMBOL	CONFIGURATION	RV/L
BI SI N HI CI V	(EJECTOR-E205)	9.843
DATA NOT AVAILABLE		13.123
BI SI N HI CI V	(EJECTOR-E205)	14.754
DATA NOT AVAILABLE		16.404
BI SI N HI CI V	(EJECTOR-E205)	19.685
DATA NOT AVAILABLE		22.966

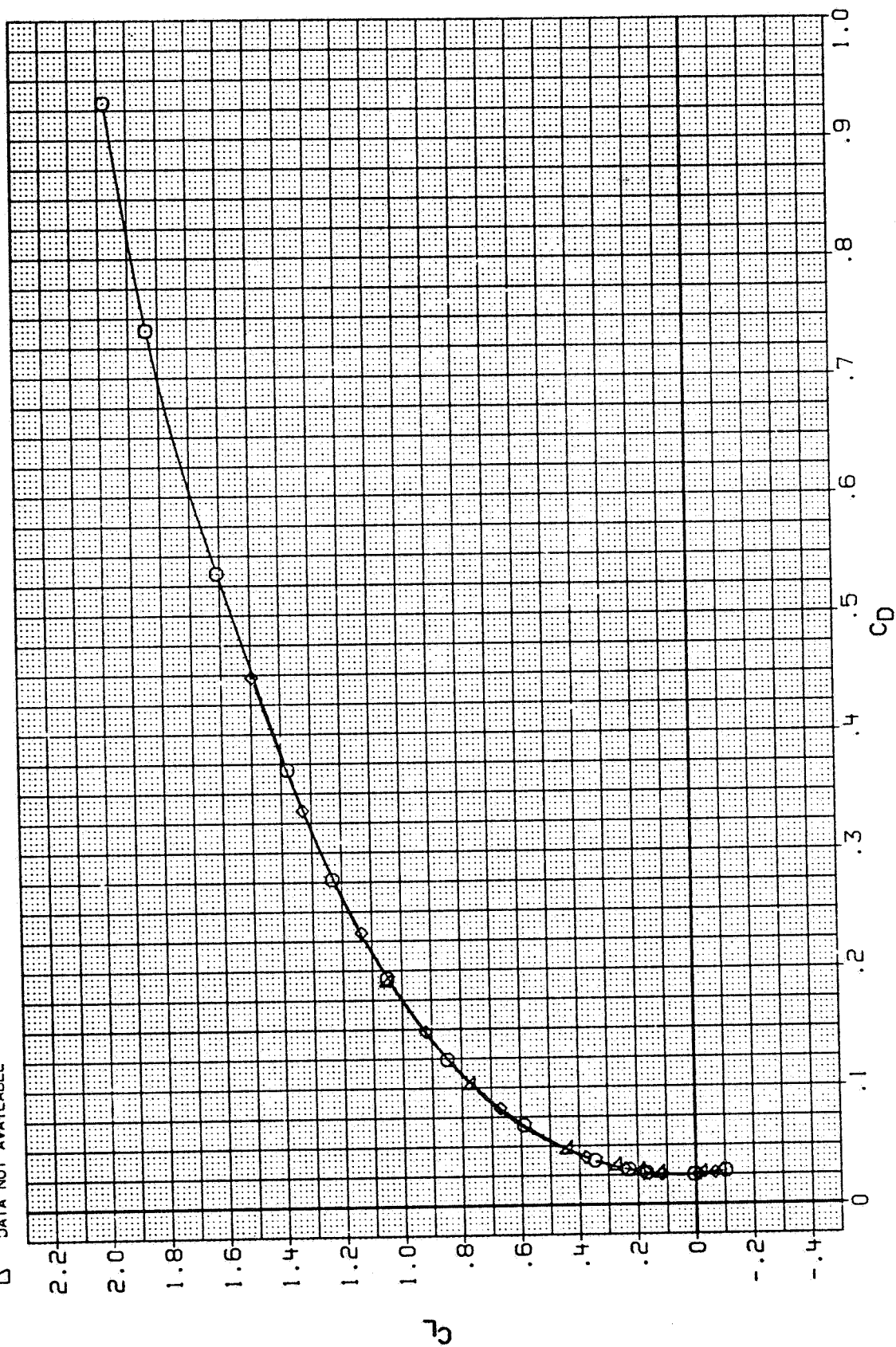
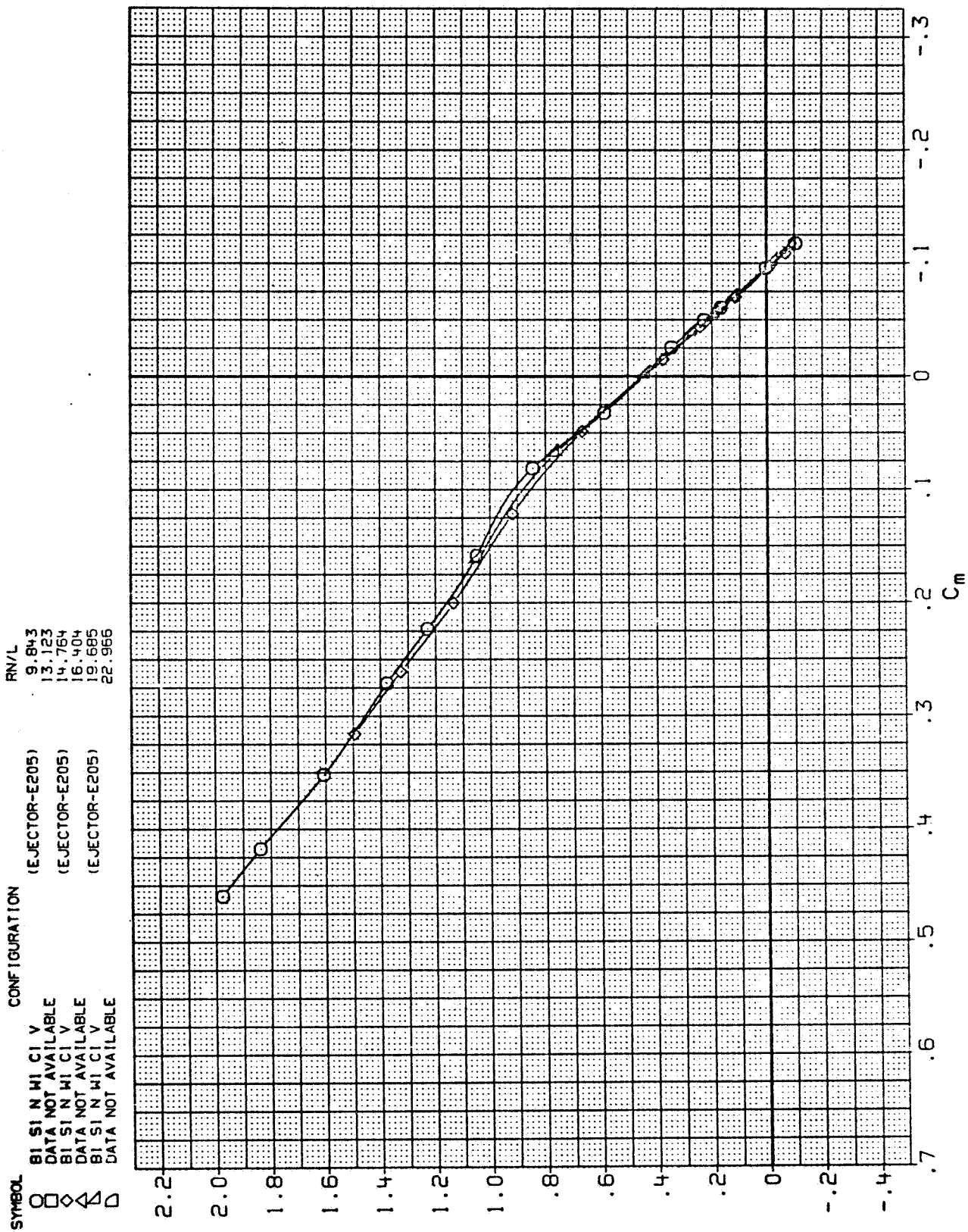


FIG. 10 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS REYNOLDS NUMBERS

MACH = .90



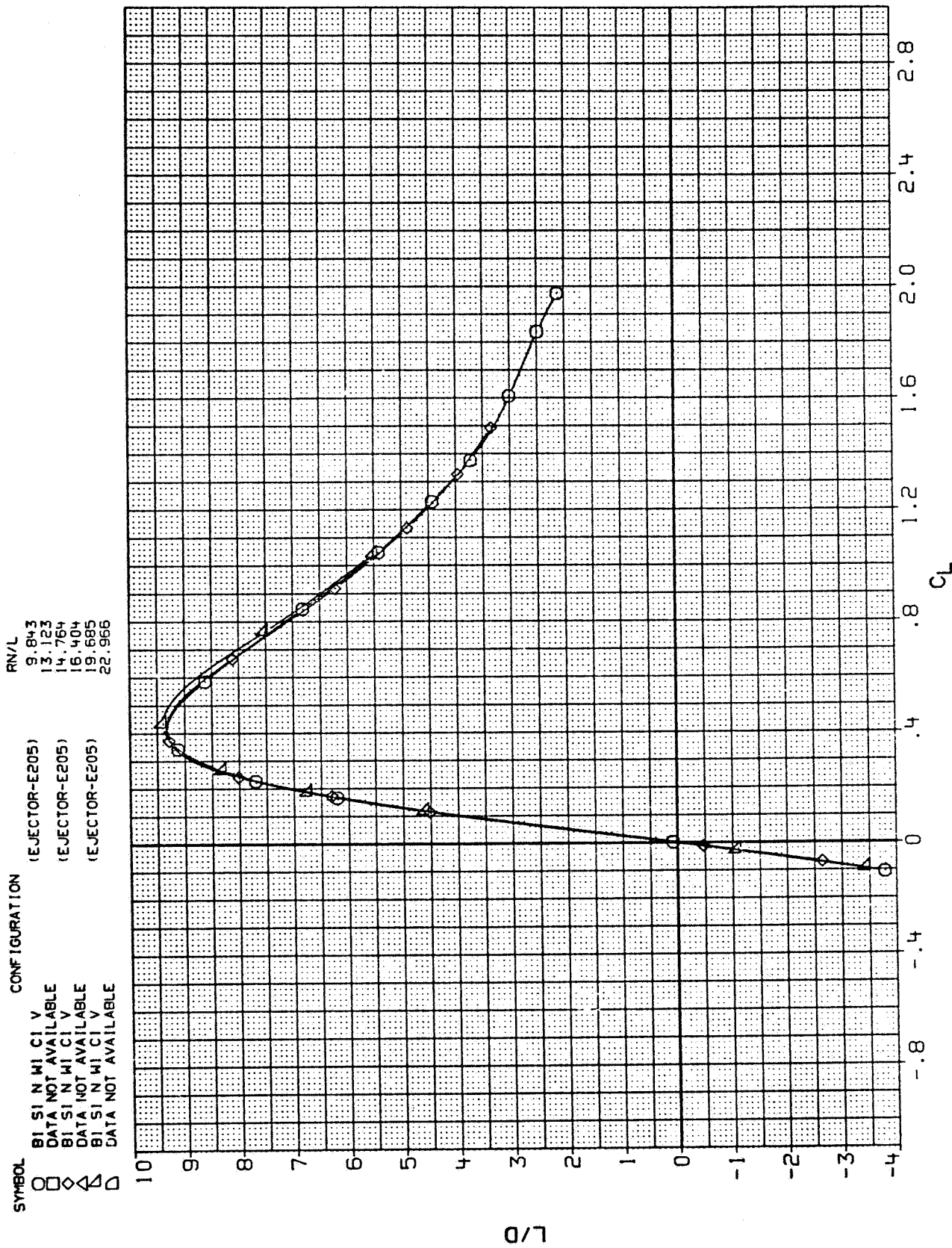


FIG. 10 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS REYNOLDS NUMBERS

MACH = .90

SYMBOL	CONFIGURATION	RN/L
○	BI SI N MI CI V	9.843
◇	BI SI N MI CI V	13.123
△	DATA NOT AVAILABLE	14.764
▽	BI SI N MI CI V	16.404
□	DATA NOT AVAILABLE	19.685
	DATA NOT AVAILABLE	22.966

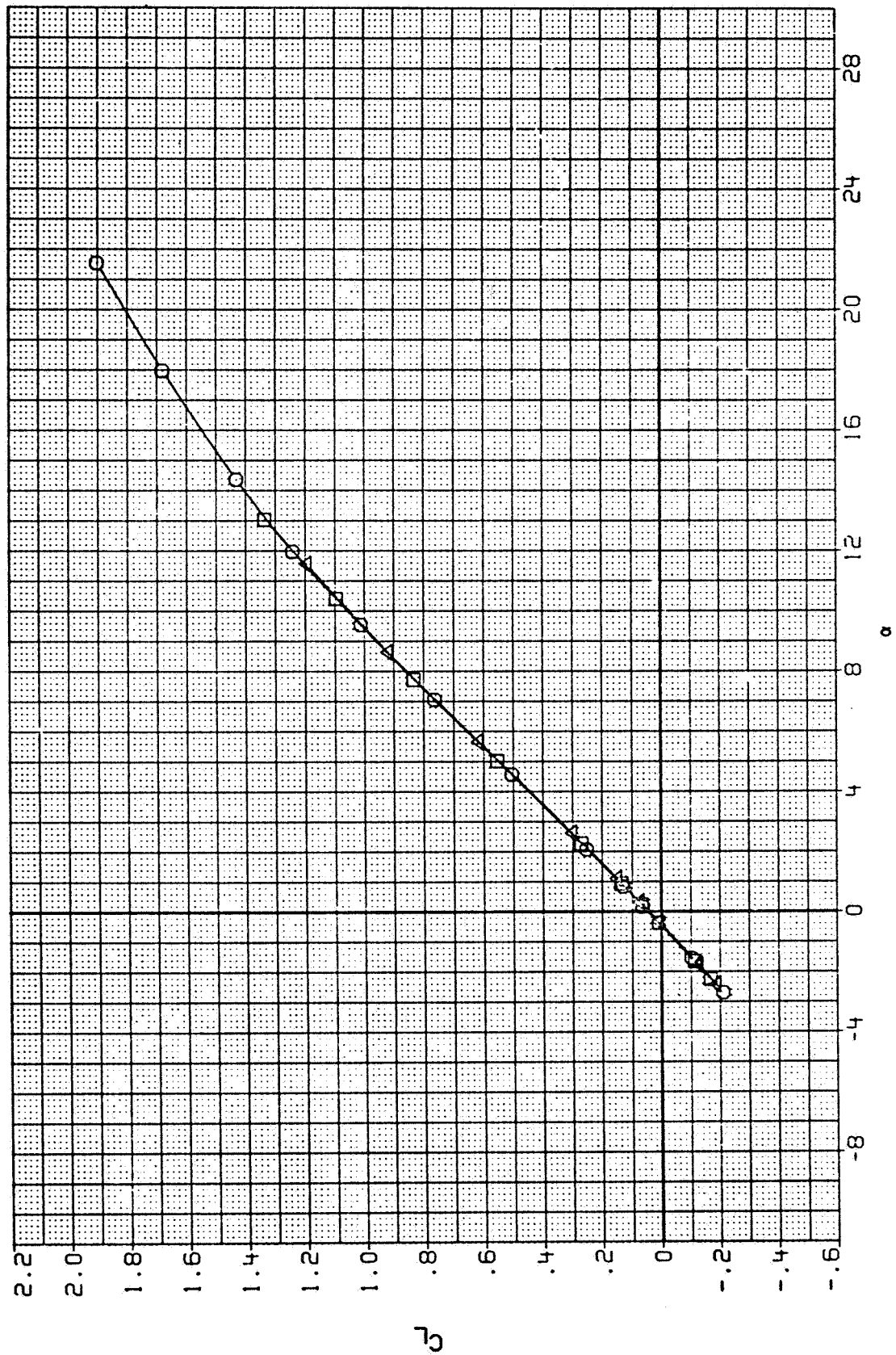


FIG. 11 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS REYNOLDS NUMBERS

MACH = 1.20

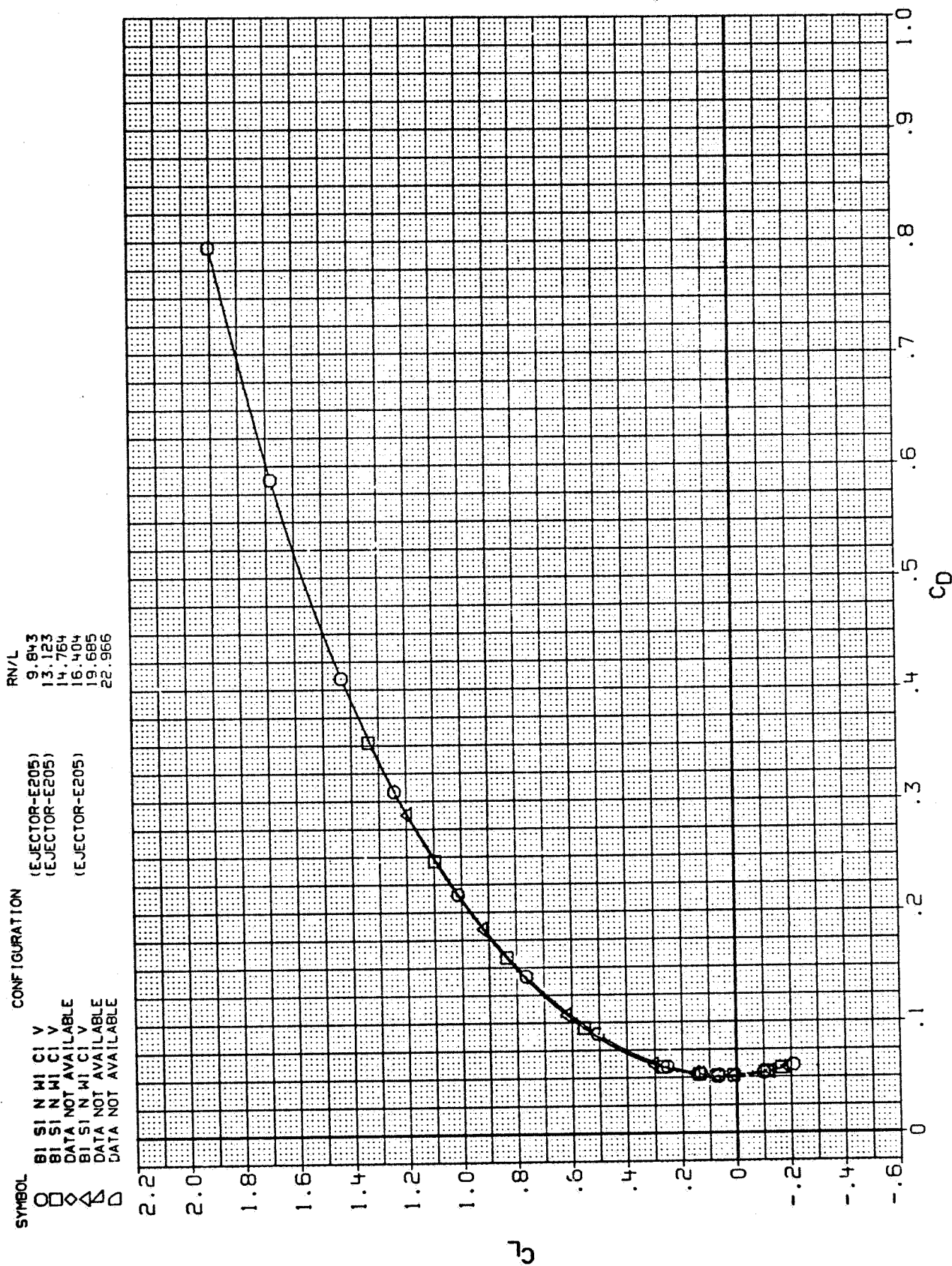


FIG. 11 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS REYNOLDS NUMBERS

MACH = 1.20

RN/L
9.843
13.123
14.764
16.404
19.685
22.956

(EJECTOR-E205)
(EJECTOR-E205)
(EJECTOR-E205)

CONFIGURATION

BI SI N WI CI V
BI SI N WI CI V
DATA NOT AVAILABLE
BI SI N WI CI V
DATA NOT AVAILABLE
DATA NOT AVAILABLE

SYMBOL
□
◇
△
□

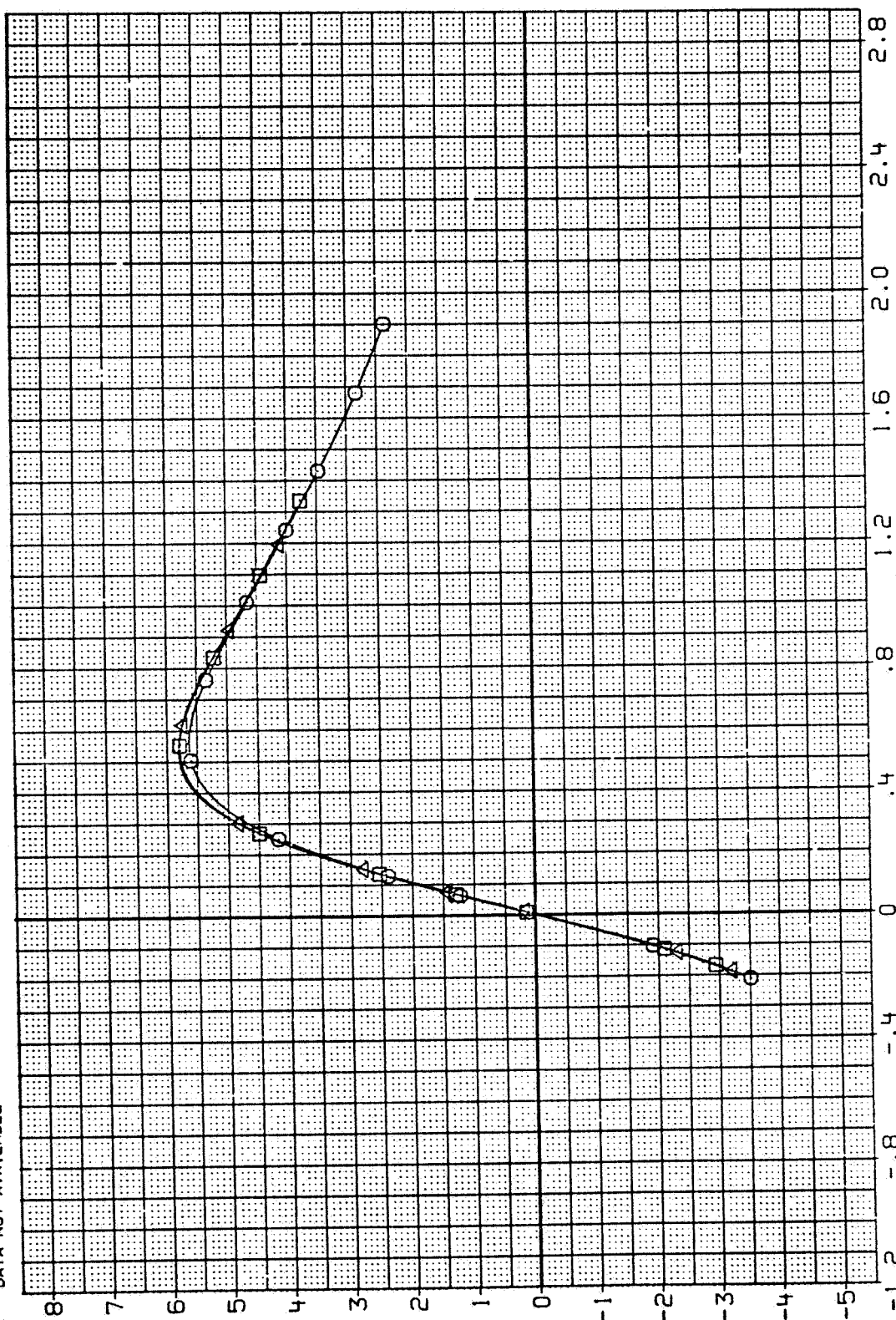


FIG. 11 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS REYNOLDS NUMBERS

MACH = 1.20

SYMBOL CONFIGURATION

- DATA NOT AVAILABLE (EJECTOR-E205)
- BI SI N V
- DATA NOT AVAILABLE (EJECTOR-E205)
- BI SI N W1 C1 V

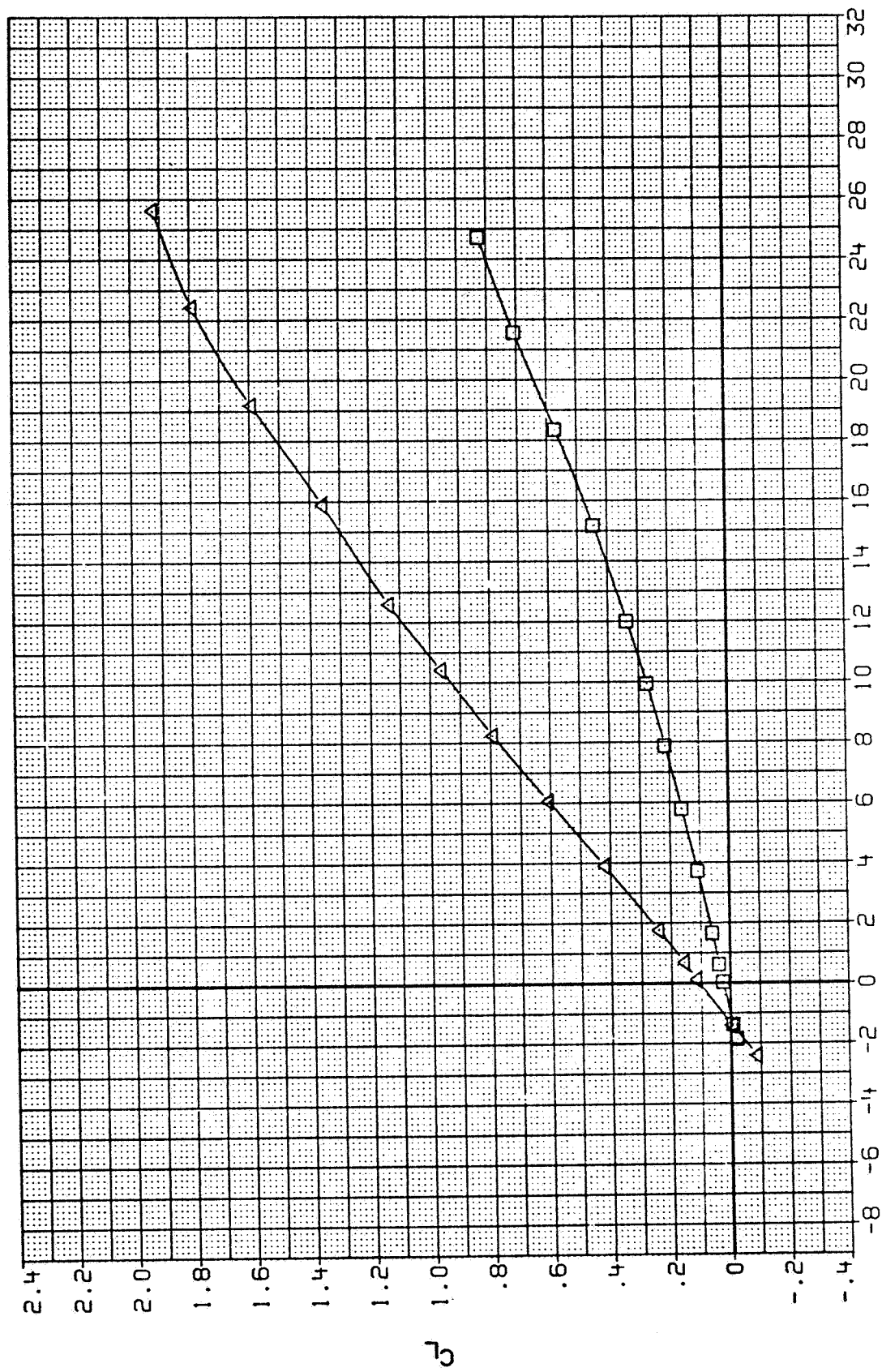


FIG. 12 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .40

SYMBOL CONFIGURATION

□ DATA NOT AVAILABLE (EJECTOR-E205)

◇ BI SI N V (EJECTOR-E205)

△ DATA NOT AVAILABLE (EJECTOR-E205)

△ BI SI N W C I V

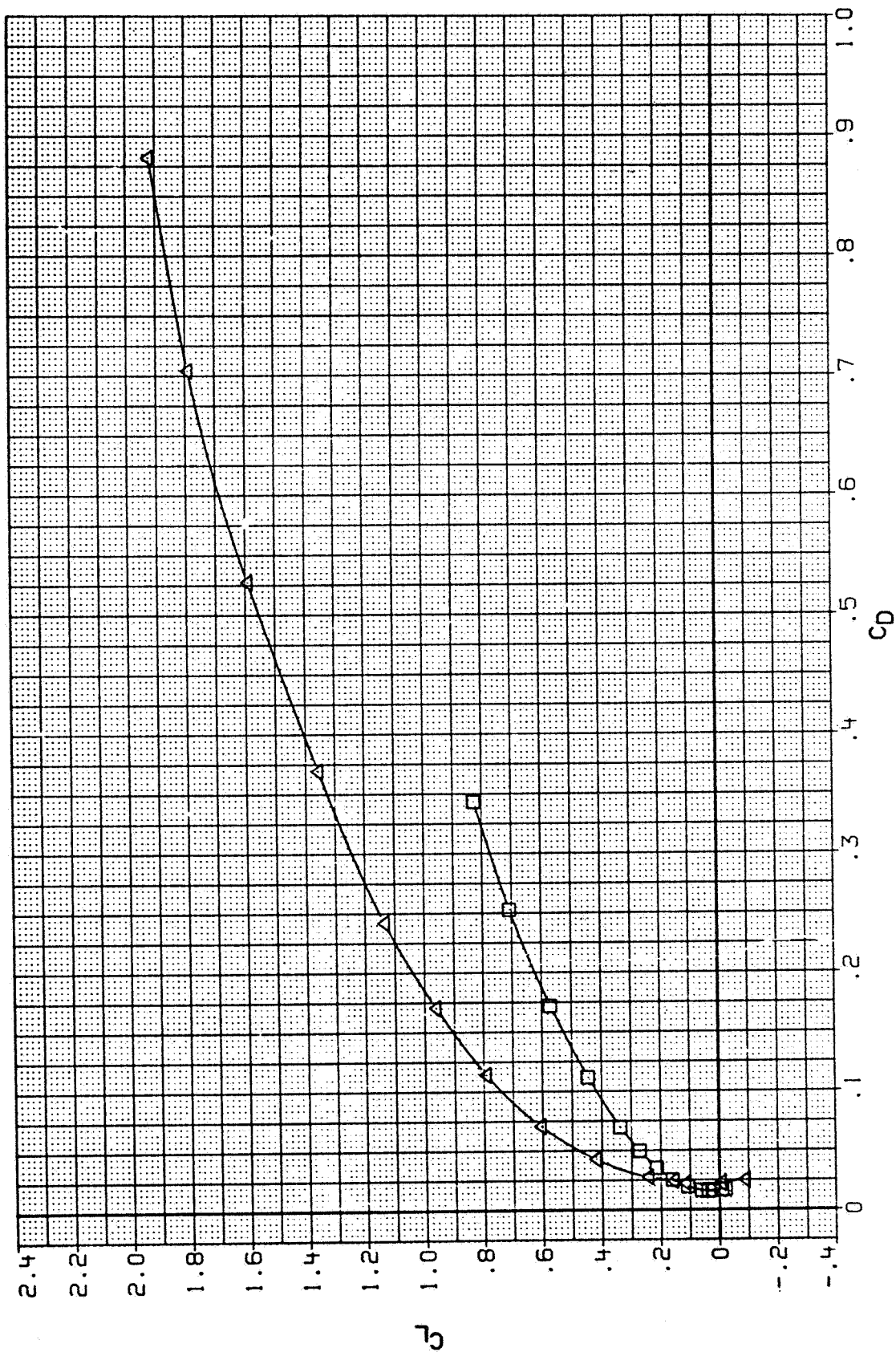


FIG. 12 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 0.40

SYMBOL CONFIGURATION
 DATA NOT AVAILABLE
 BI SI N V (EJECTOR-E205)
 DATA NOT AVAILABLE
 BI SI N W1 C1 V (EJECTOR-E205)

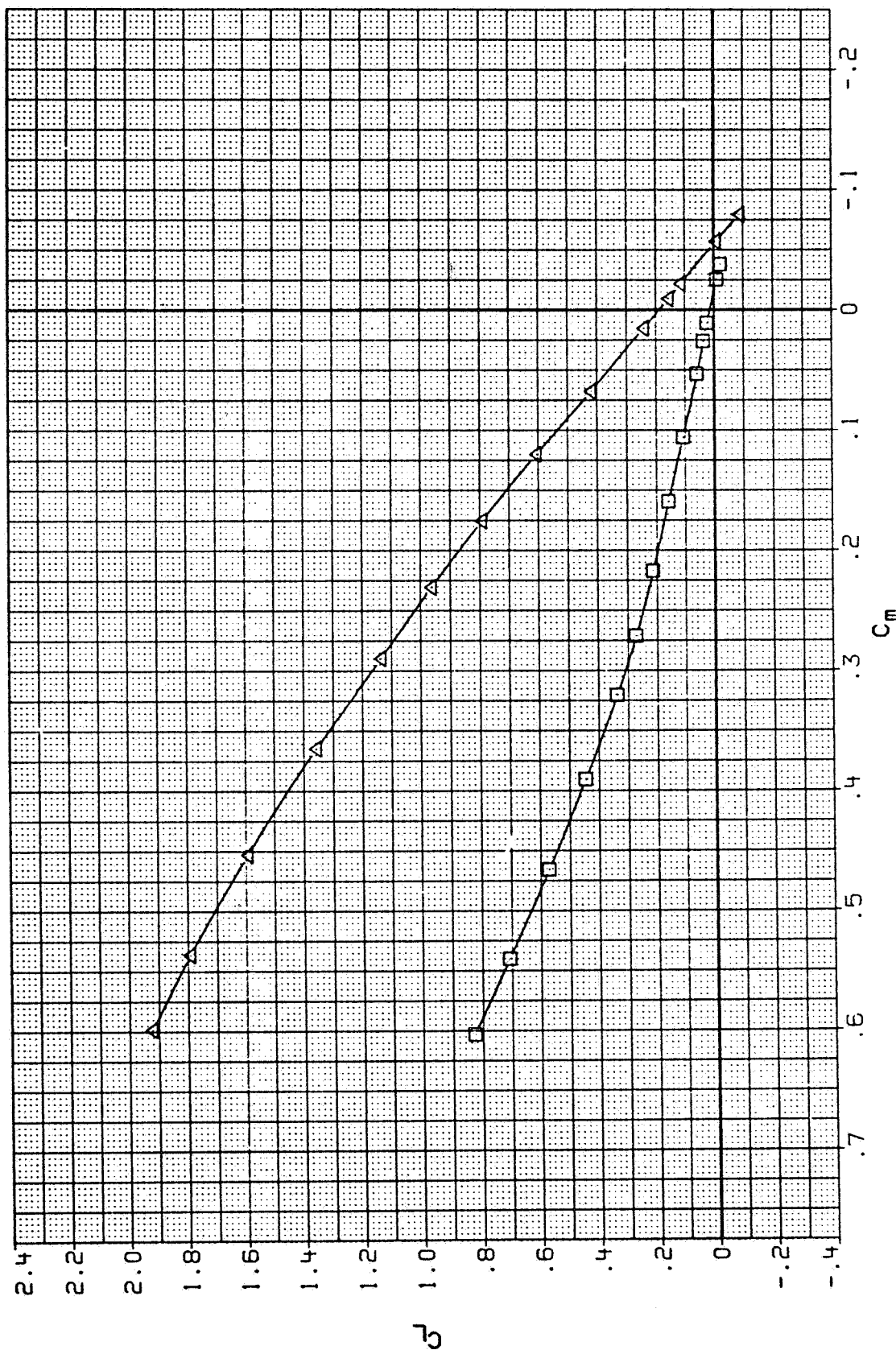


FIG. 12 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 0.40

SYMBOL CONFIGURATION
 ○ DATA NOT AVAILABLE (EJECTOR-E205)
 □ BI SI N V (EJECTOR-E205)
 ◇ DATA NOT AVAILABLE
 △ BI SI N HI CI V

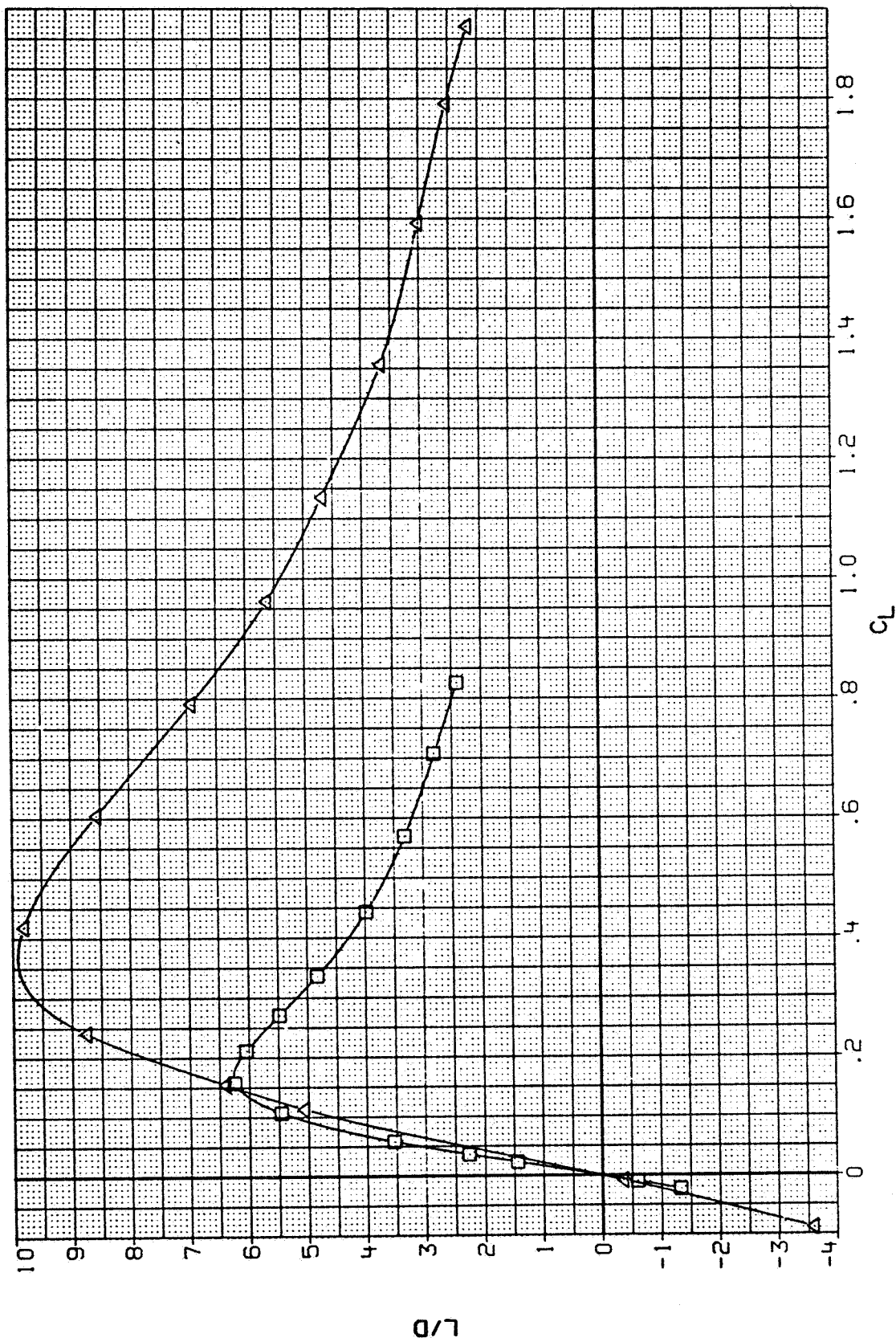


FIG. 12 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .40

SYMBOL CONFIGURATION
 BI SI N V (EJECTOR-E205)
 BI SI N V (EJECTOR-E205)
 BI SI N V (EJECTOR-E205)
 BI SI N V (EJECTOR-E205)

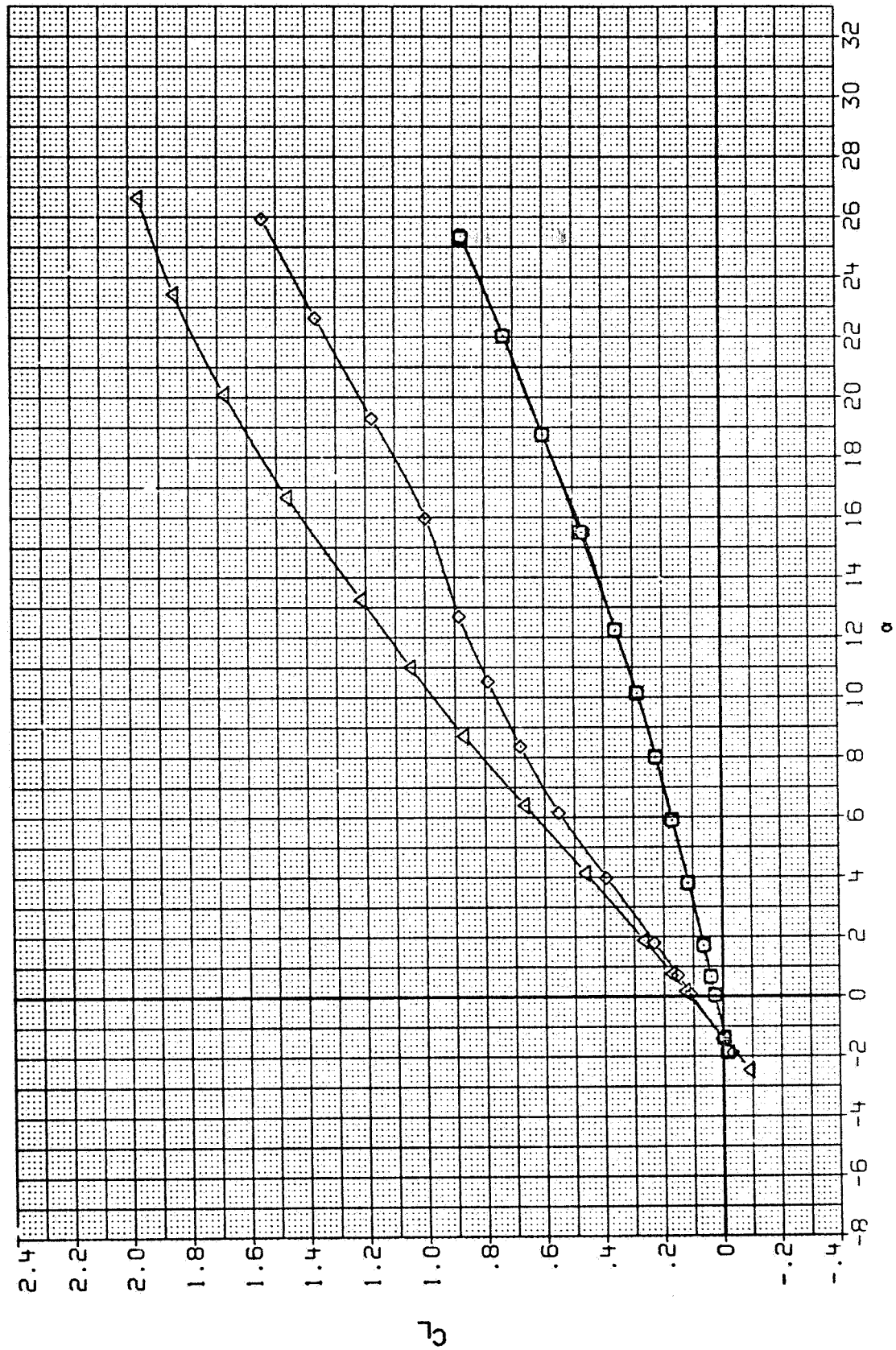


FIG. 13 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL CONFIGURATION

□ BI SI N V (EJECTOR-E205)
 ◇ BI SI N V (EJECTOR-E205)
 △ BI SI N V (EJECTOR-E205)
 △ BI SI N V (EJECTOR-E205)

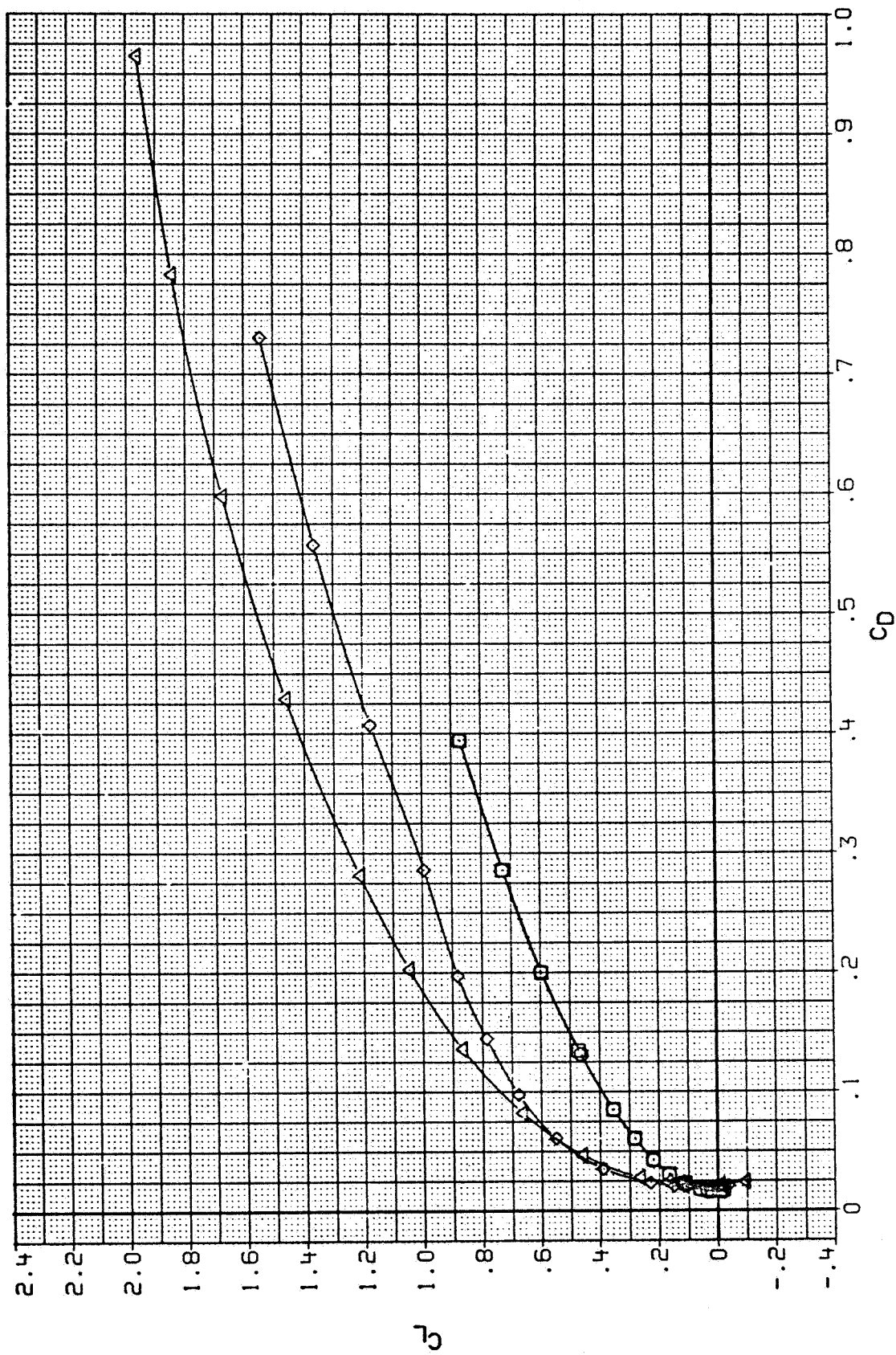


FIG. 13 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL
 BI SI N V
 BI SI N W V
 BI SI N W V
 BI SI N W V

CONF IGURATION
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

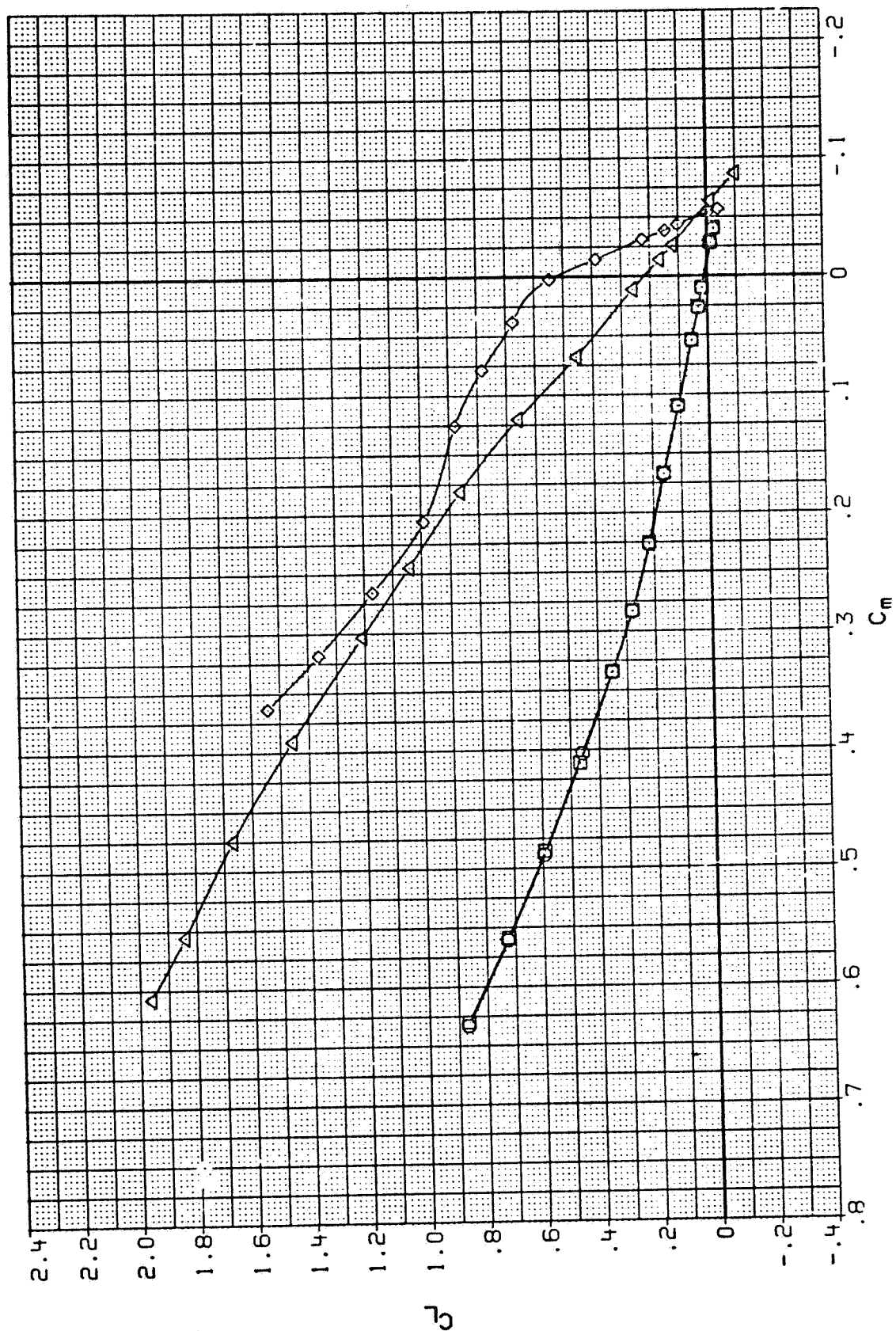


FIG. 13 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL CONFIGURATION

BI SI N V (EJECTOR-E205)
 BI SI N V (EJECTOR-E205)
 BI SI N V (EJECTOR-E205)
 BI SI N V (EJECTOR-E205)

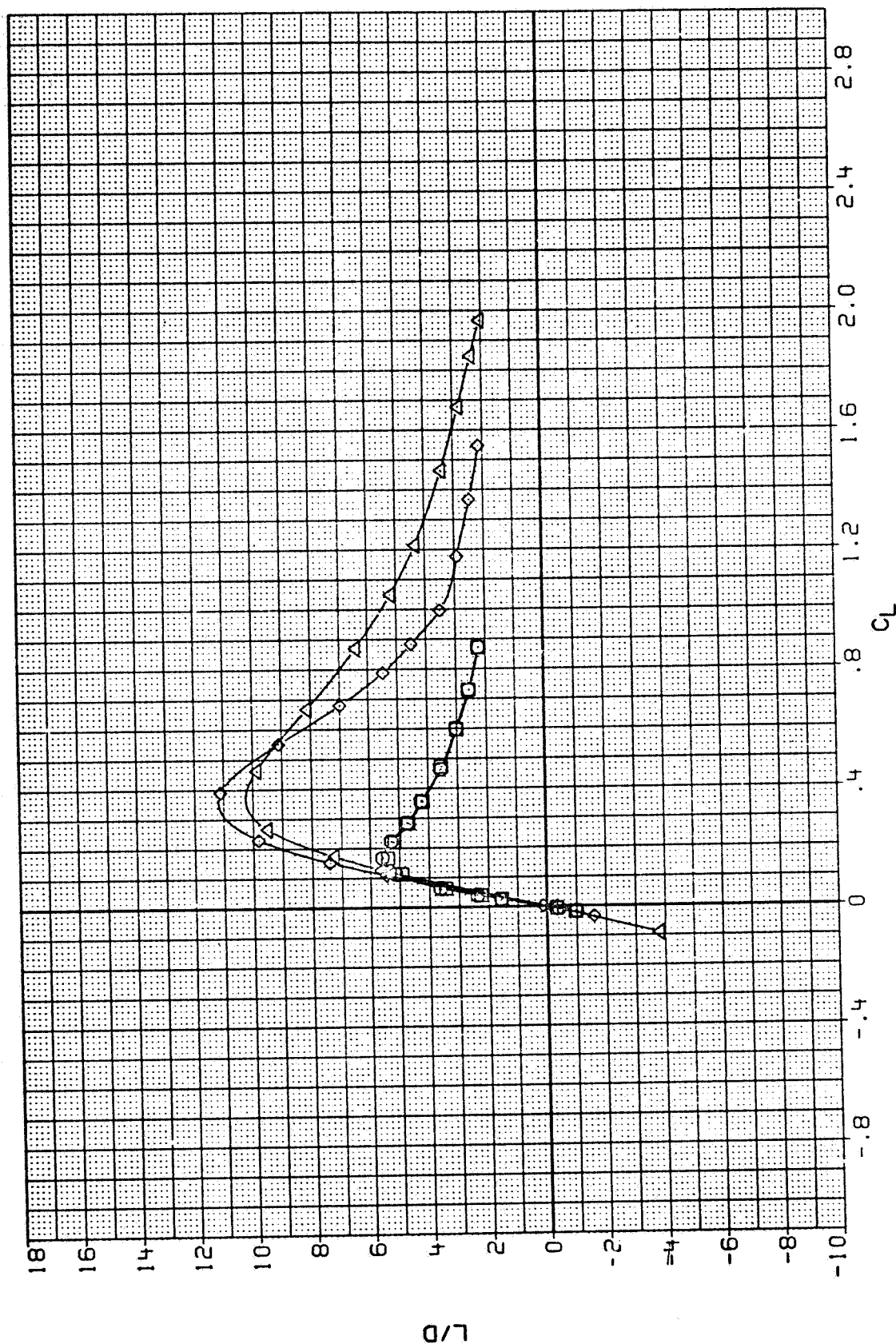


FIG. 13 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL CONFIGURATION

DATA NOT AVAILABLE
 BI SI N V
 DATA NOT AVAILABLE
 BI SI N HI CI V

(EJECTOR-E205)
 (EJECTOR-E205)

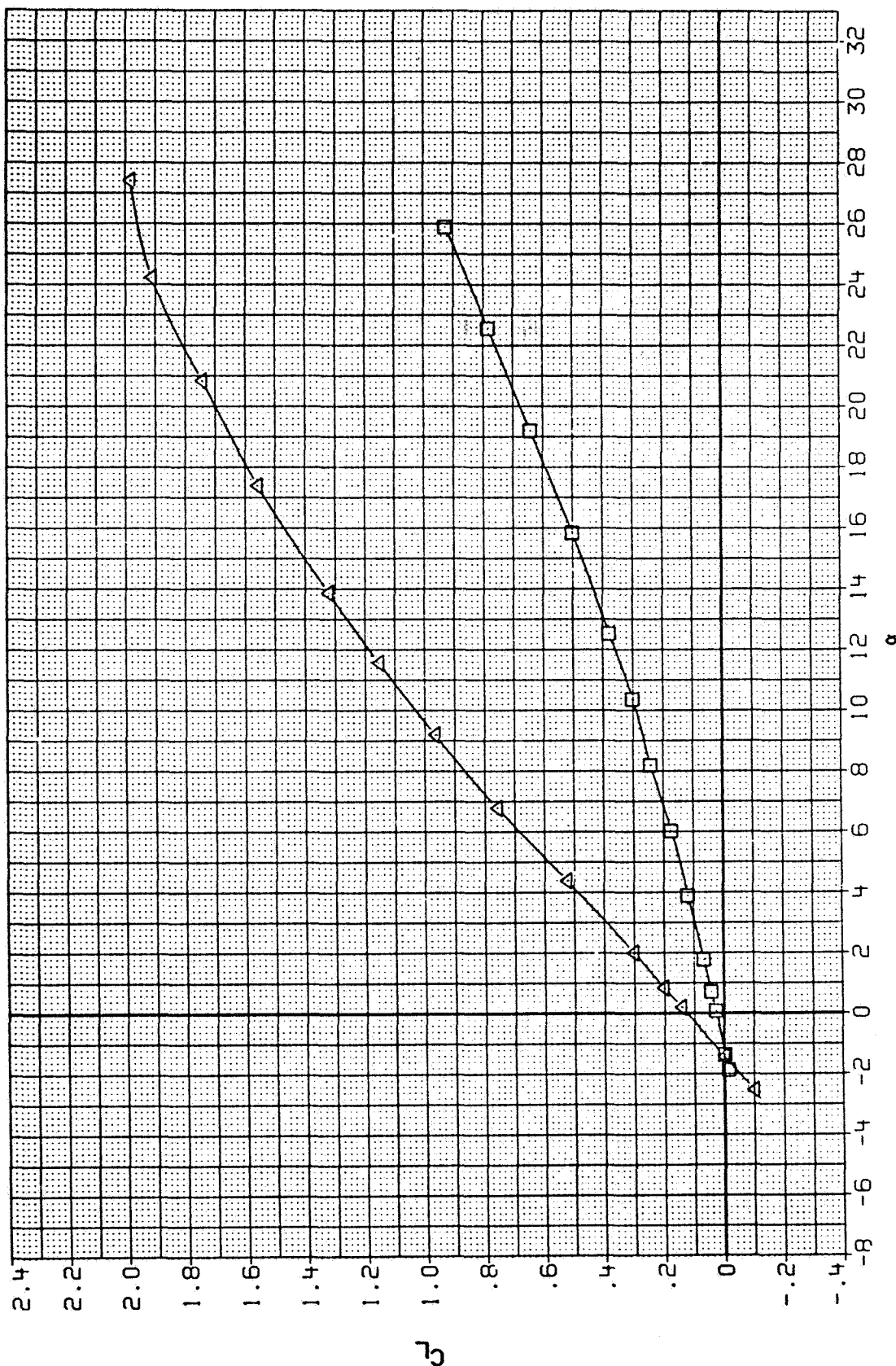


FIG. 14 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .80

SYMBOL CONFIGURATION
 DATA NOT AVAILABLE
 BI SI N V (EJECTOR-E205)
 DATA NOT AVAILABLE
 BI SI N W1 C1 V (EJECTOR-E205)

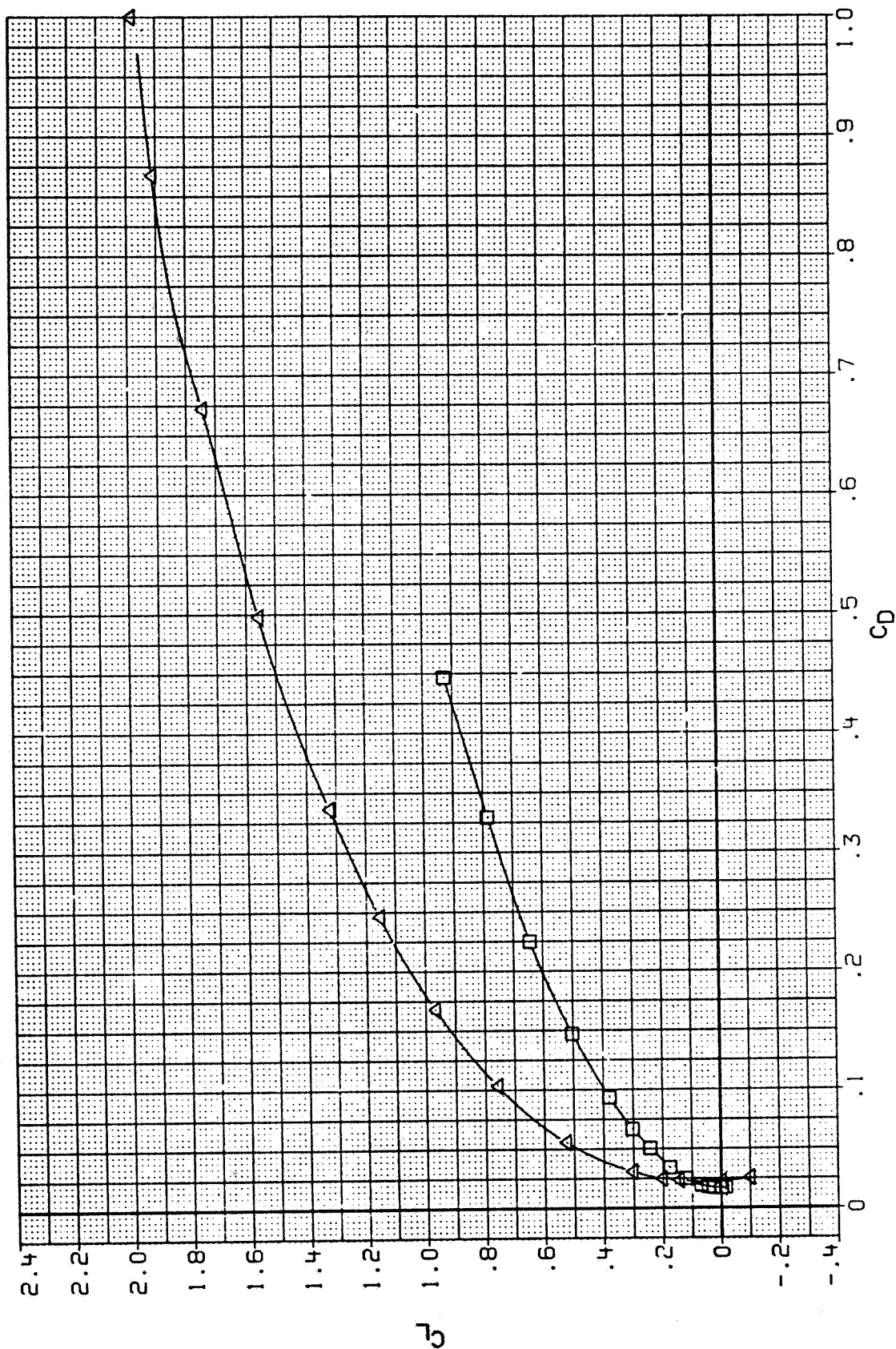


FIG. 14 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .80

SYMBOL CONFIGURATION

DATA NOT AVAILABLE (EJECTOR-E205)

BI SI N V (EJECTOR-E205)

DATA NOT AVAILABLE

BI SI N WI C V

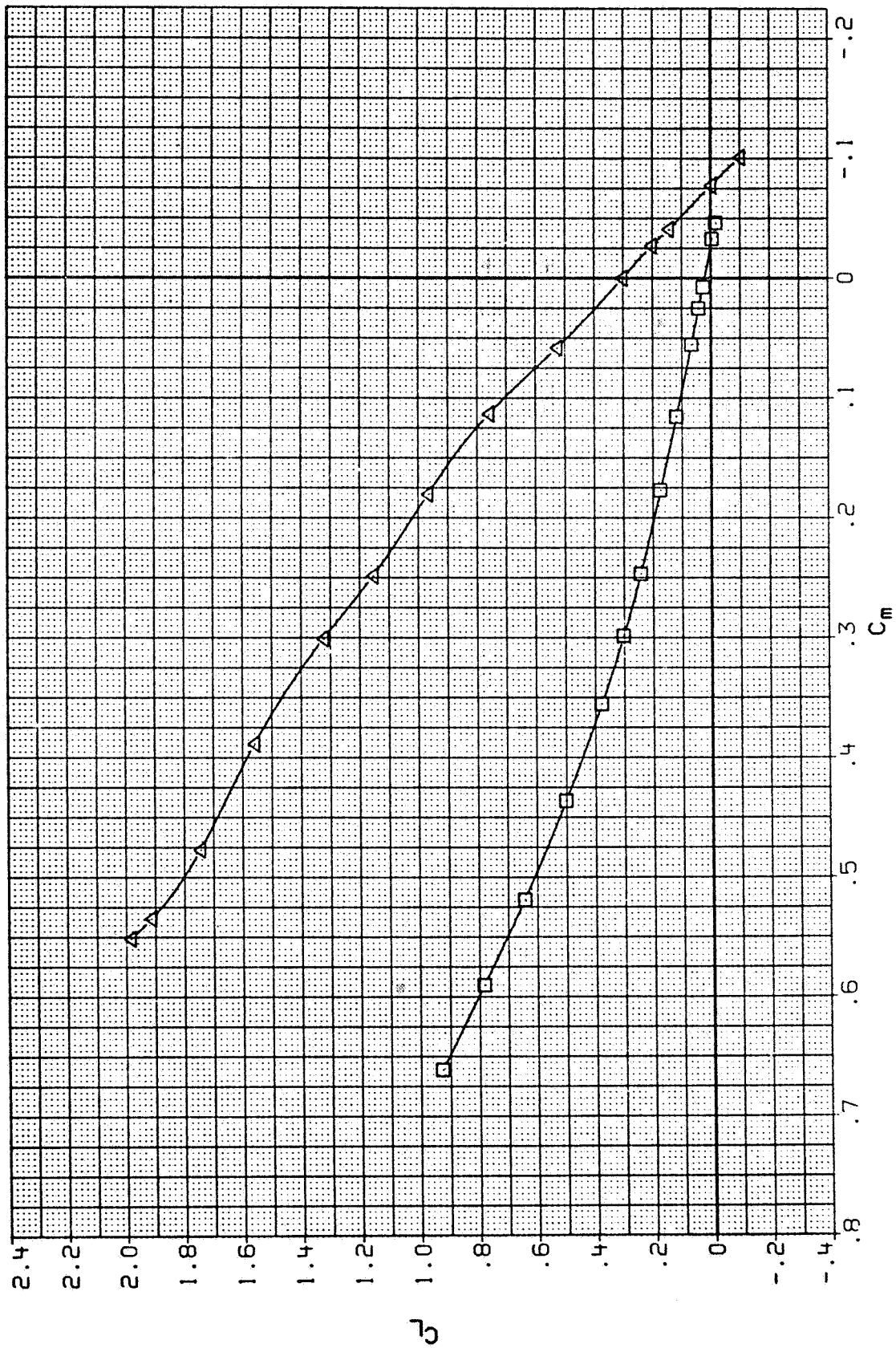


FIG. 14 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .80

SYMBOL CONFIGURATION
 DATA NOT AVAILABLE
 BI SI N V
 DATA NOT AVAILABLE
 BI SI N WI CI V

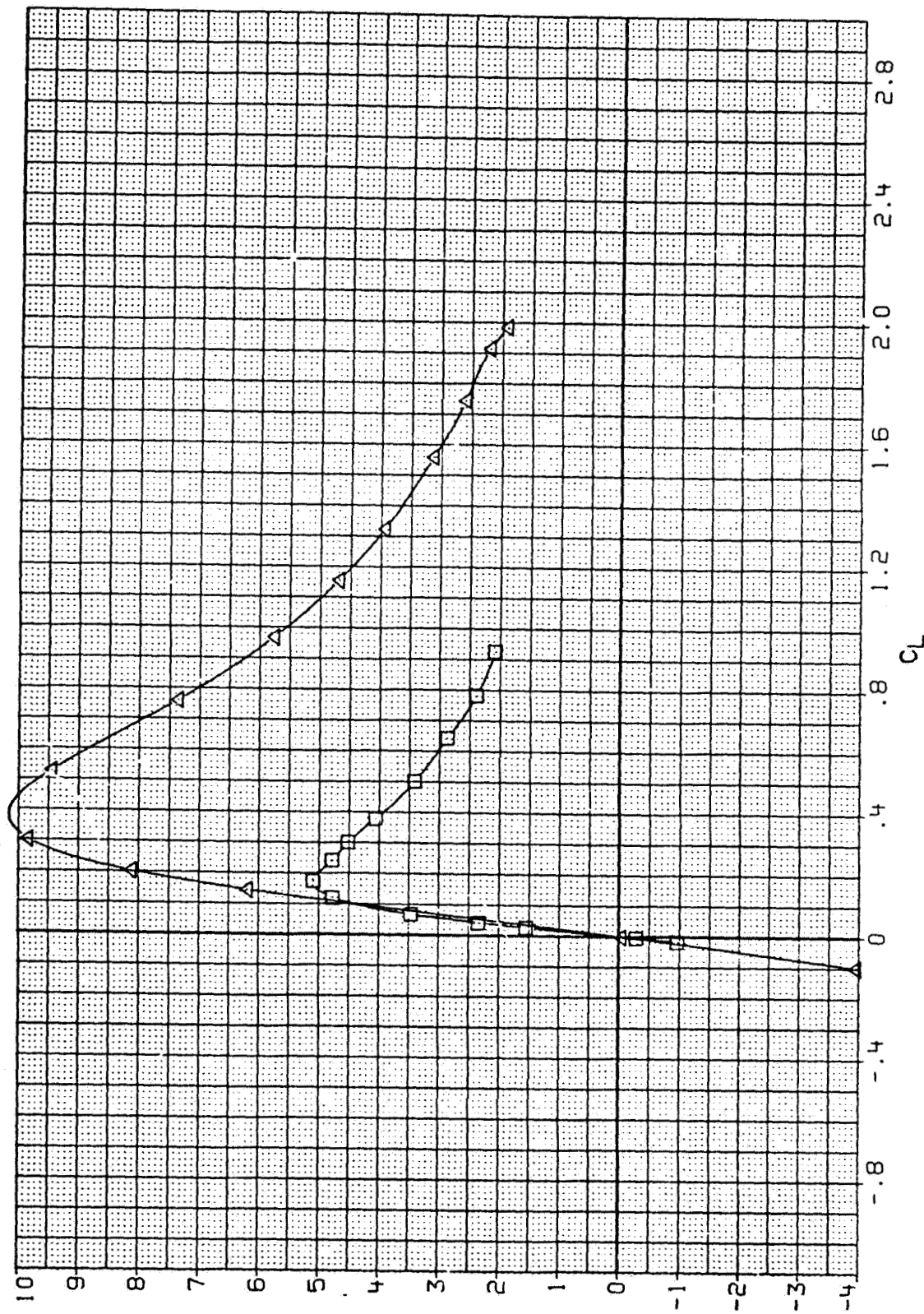


FIG. 14 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 0.80

SYMBOL CONFIGURATION
 □ BI SI N V (EJECTOR-E205)
 ◇ BI SI N W V (EJECTOR-E205)
 △ BI SI N CI V (EJECTOR-E205)

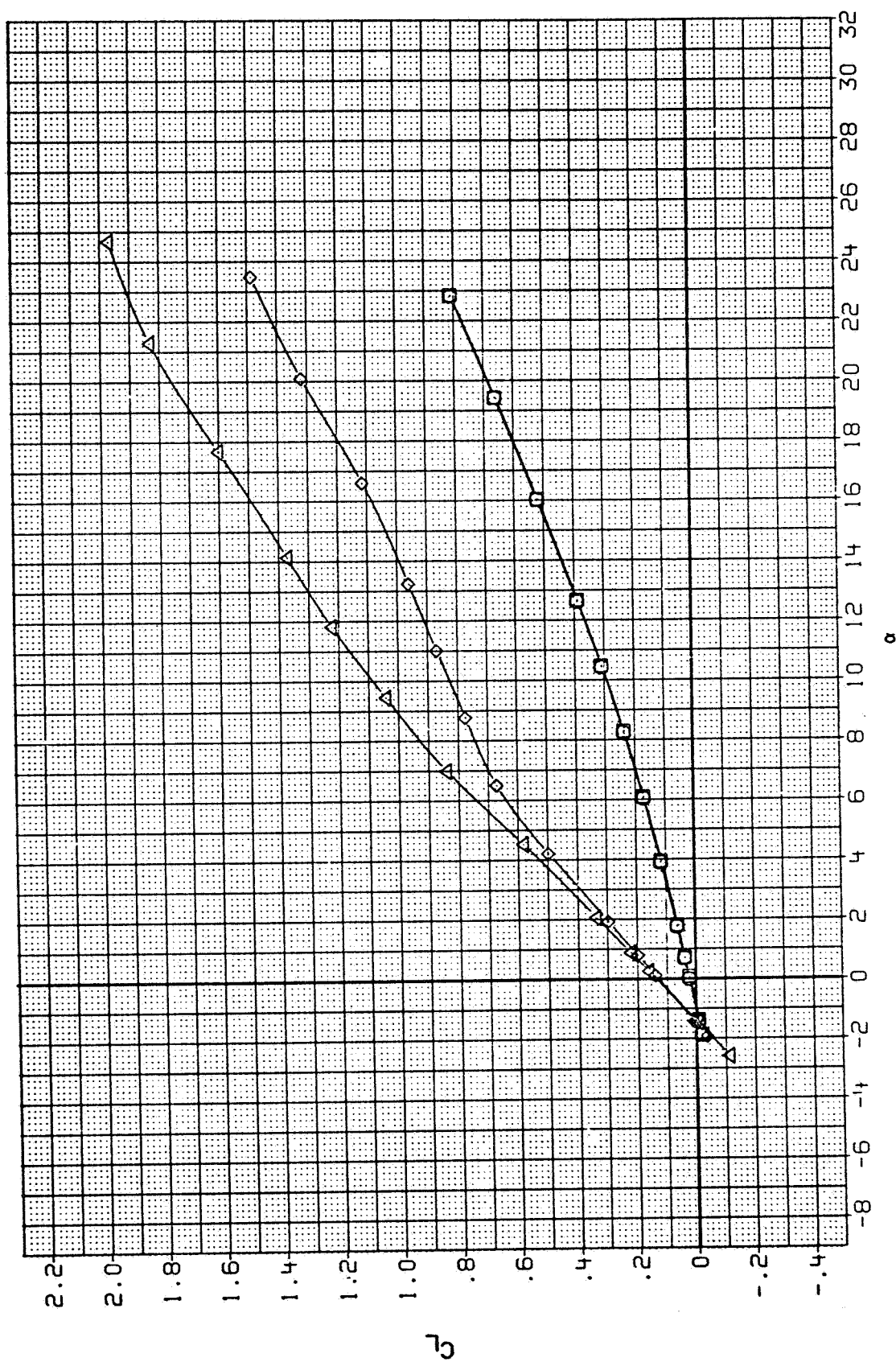


FIG. 15 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL	CONFIGURATION
□	BI SI N V (EJECTOR-E205)
◇	BI SI N WI V (EJECTOR-E205)
△	BI SI N WI CI V (EJECTOR-E205)

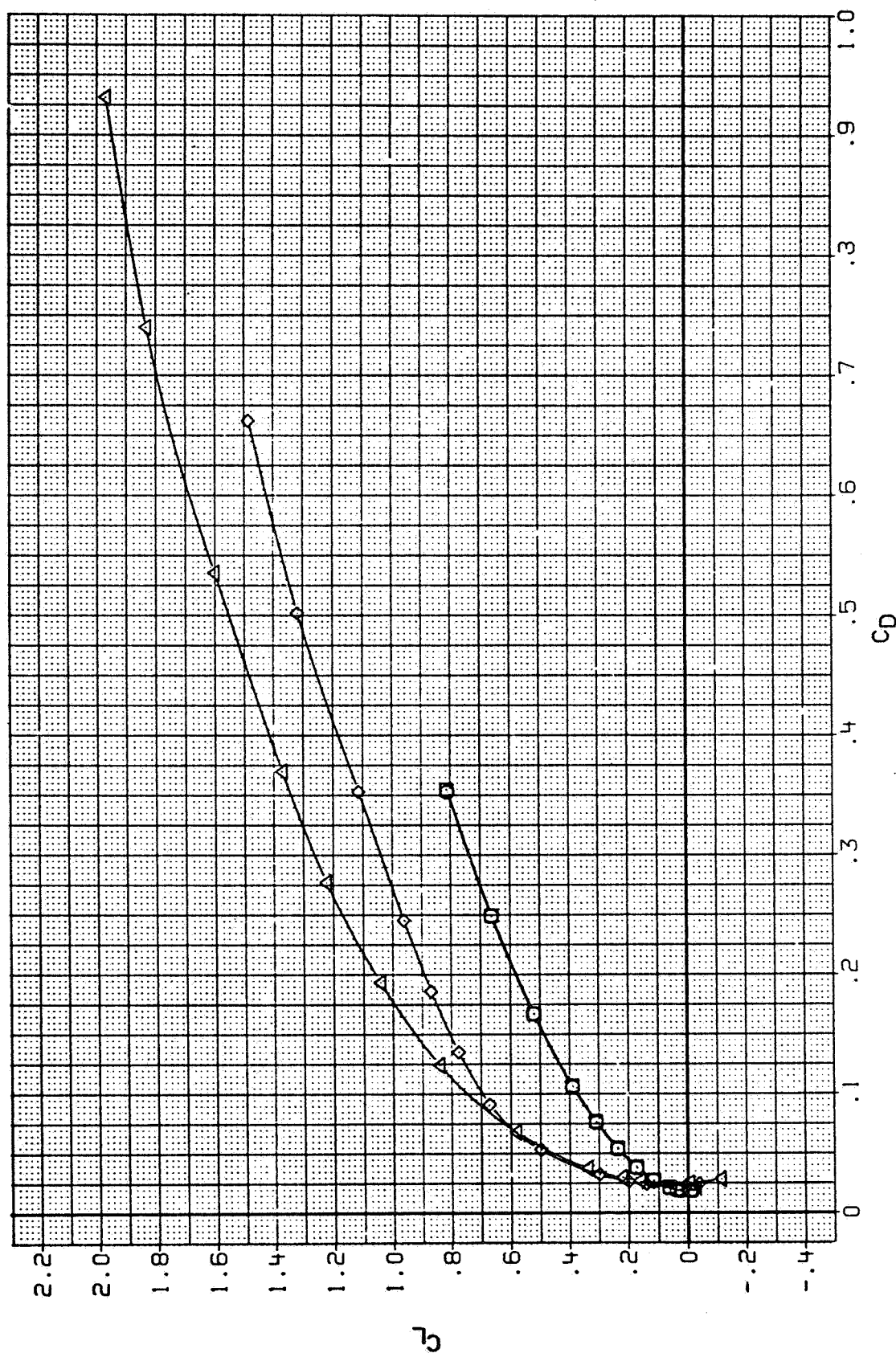


FIG. 15 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL	CONFIGURATION
□	BI SI N V (EJECTOR-E205)
○	BI SI N MI V (EJECTOR-E205)
△	BI SI N MI C1 V (EJECTOR-E205)
◇	BI SI N MI C1 V (EJECTOR-E205)

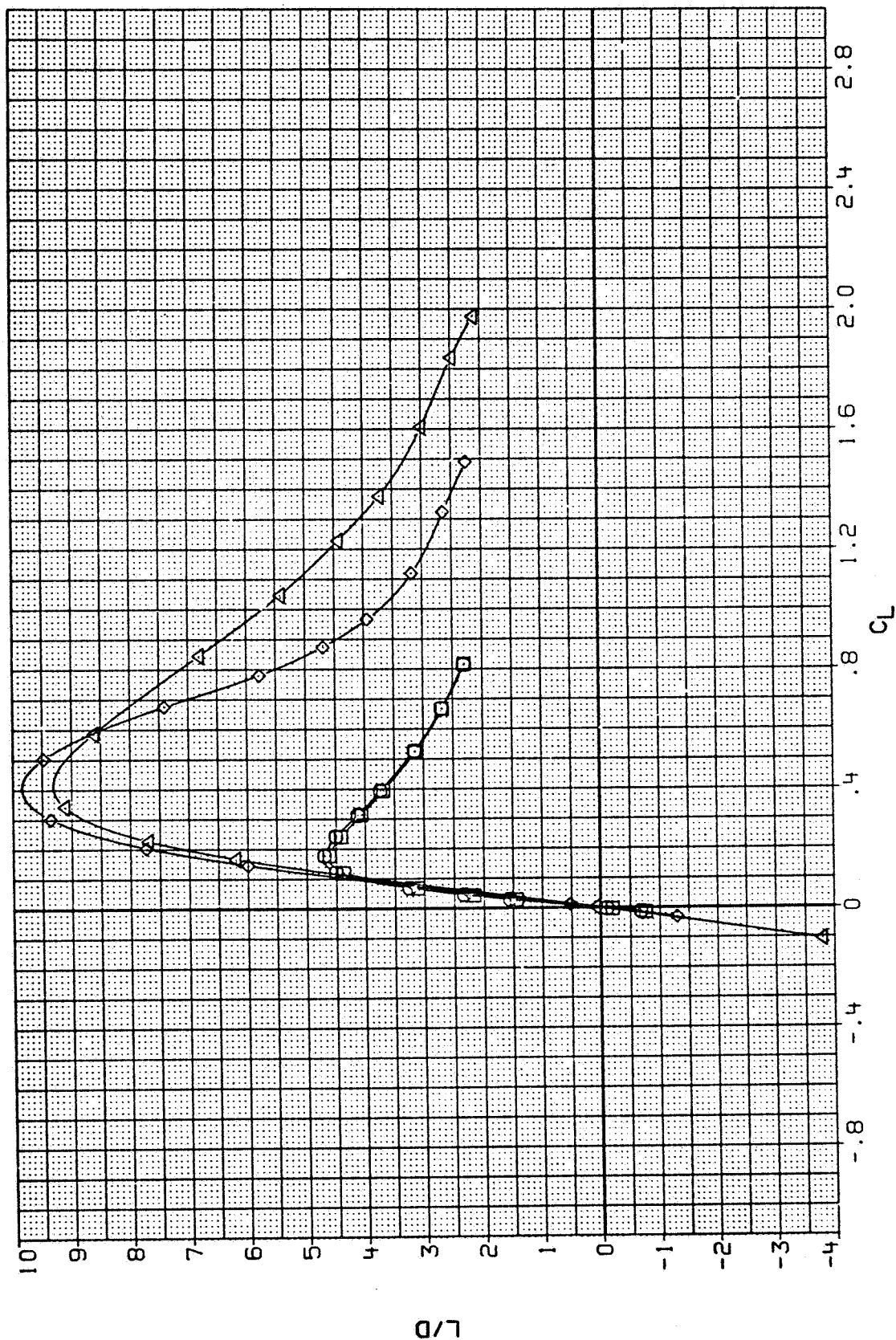


FIG. 15 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL CONFIGURATION
 DATA NOT AVAILABLE
 BI SI N V (EJECTOR-E205)
 DATA NOT AVAILABLE
 BI SI N WI CI V (EJECTOR-E205)

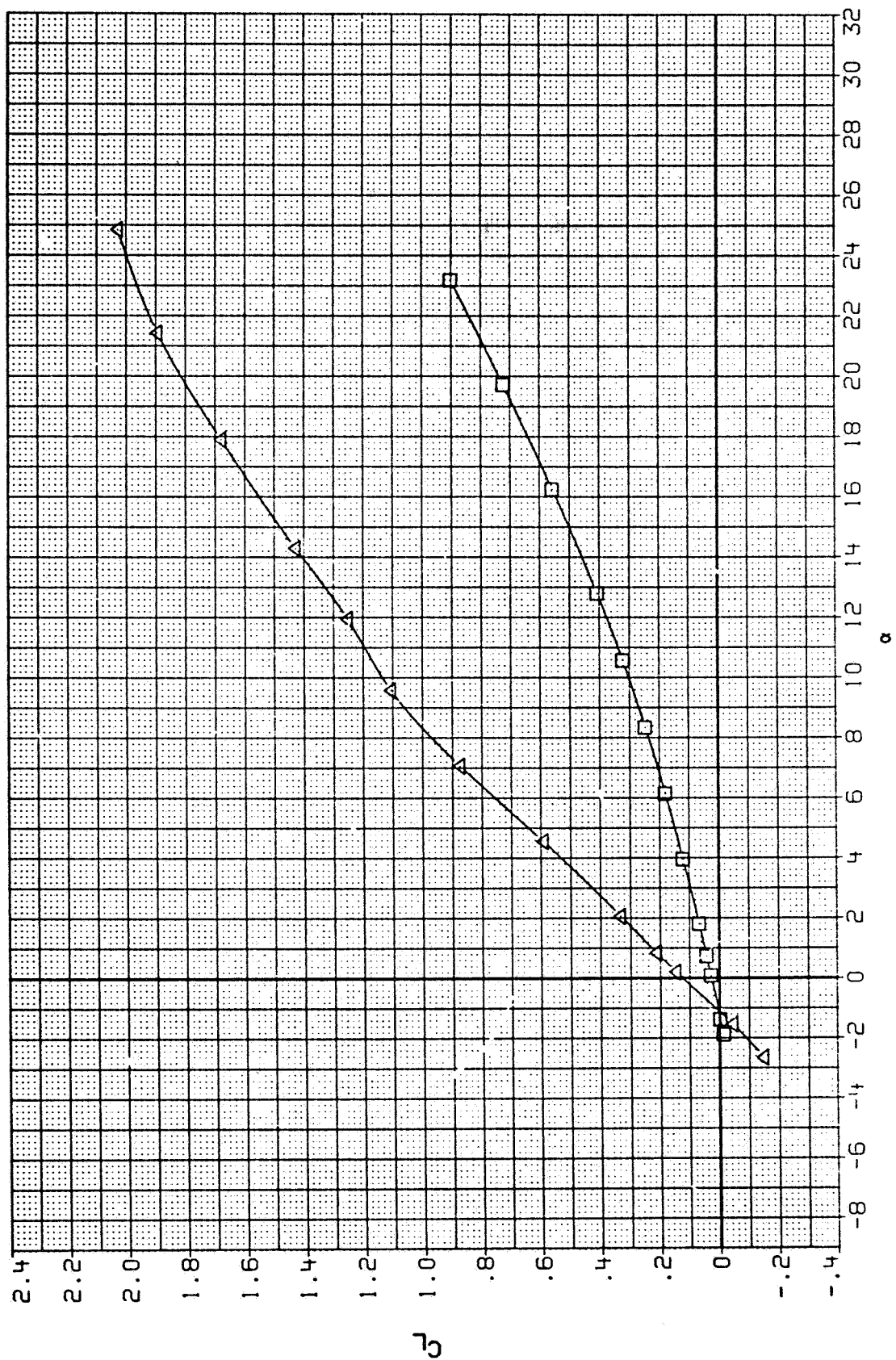


FIG. 16 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .95

SYMBOL CONFIGURATION

DATA NOT AVAILABLE (EJECTOR-E205)

BI SI N V (EJECTOR-E205)

DATA NOT AVAILABLE

BI SI N HI CI V

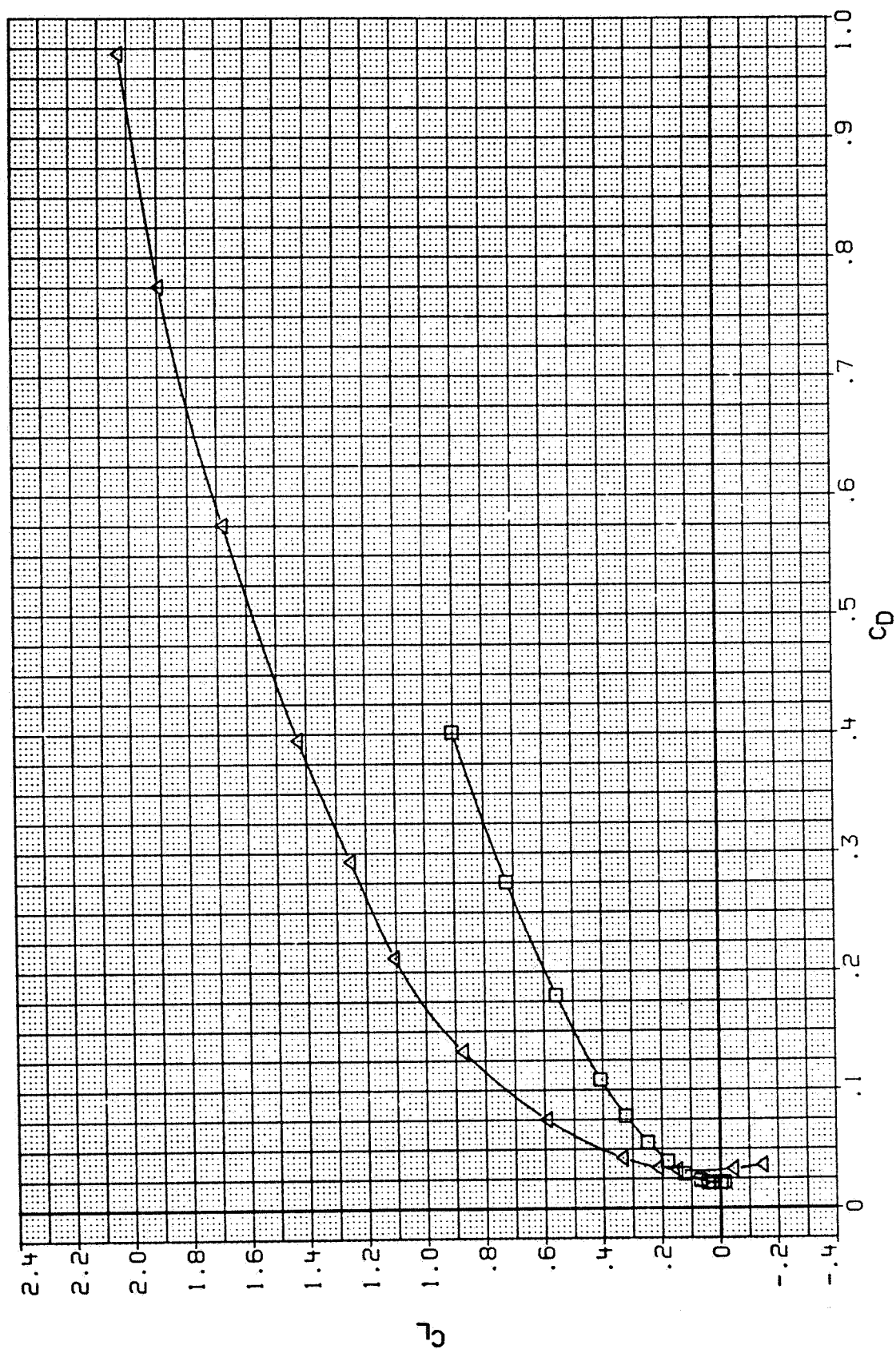


FIG. 16 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .95

SYMBOL CONFIGURATION
 DATA NOT AVAILABLE
 BI SI N V (EJECTOR-E205)
 DATA NOT AVAILABLE
 BI SI N MI CI V (EJECTOR-E205)

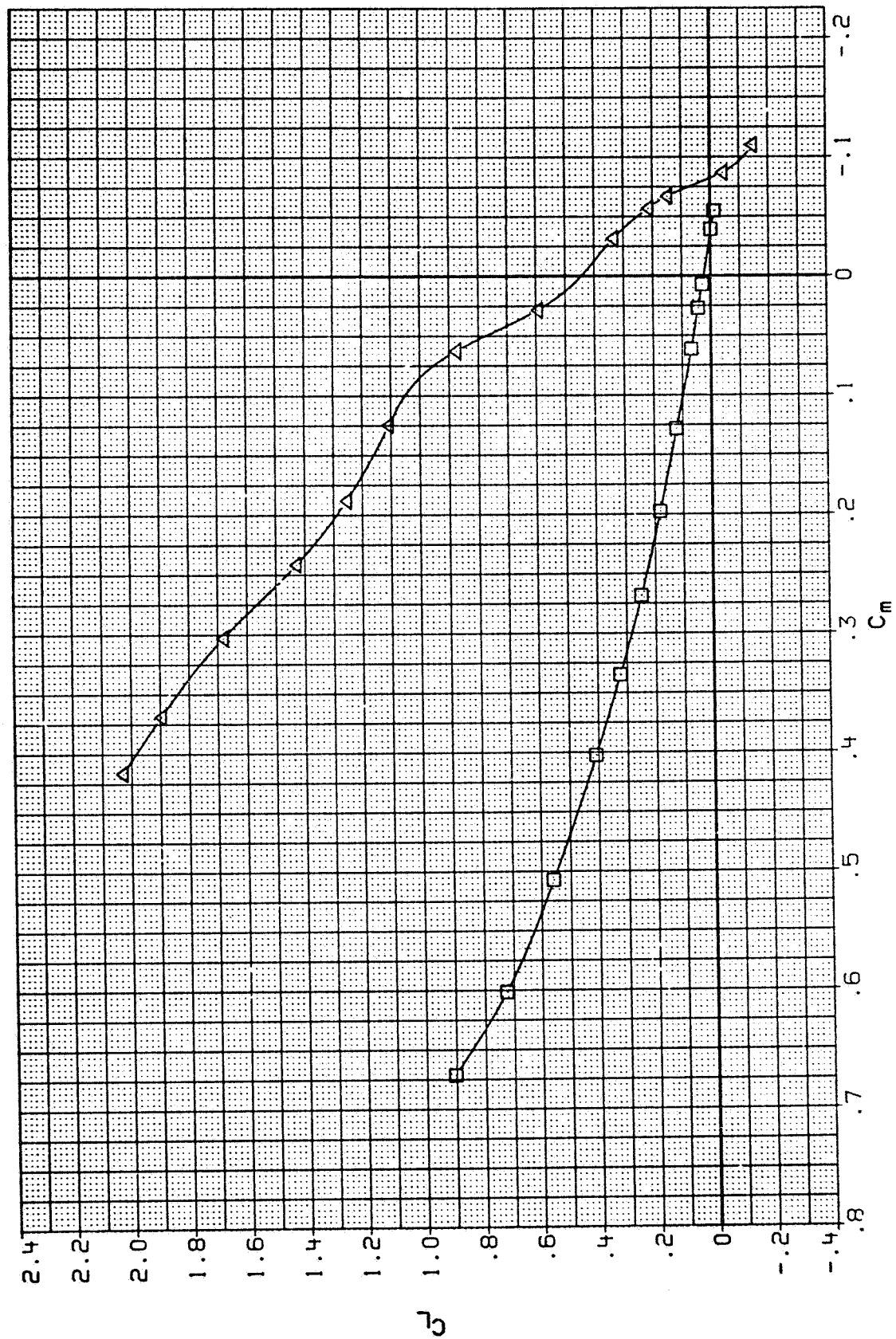


FIG. 16 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .95

SYMBOL CONFIGURATION
 DATA NOT AVAILABLE
 BI SI N V (EJECTOR-E205)
 DATA NOT AVAILABLE
 BI SI N WI CI V (EJECTOR-E205)

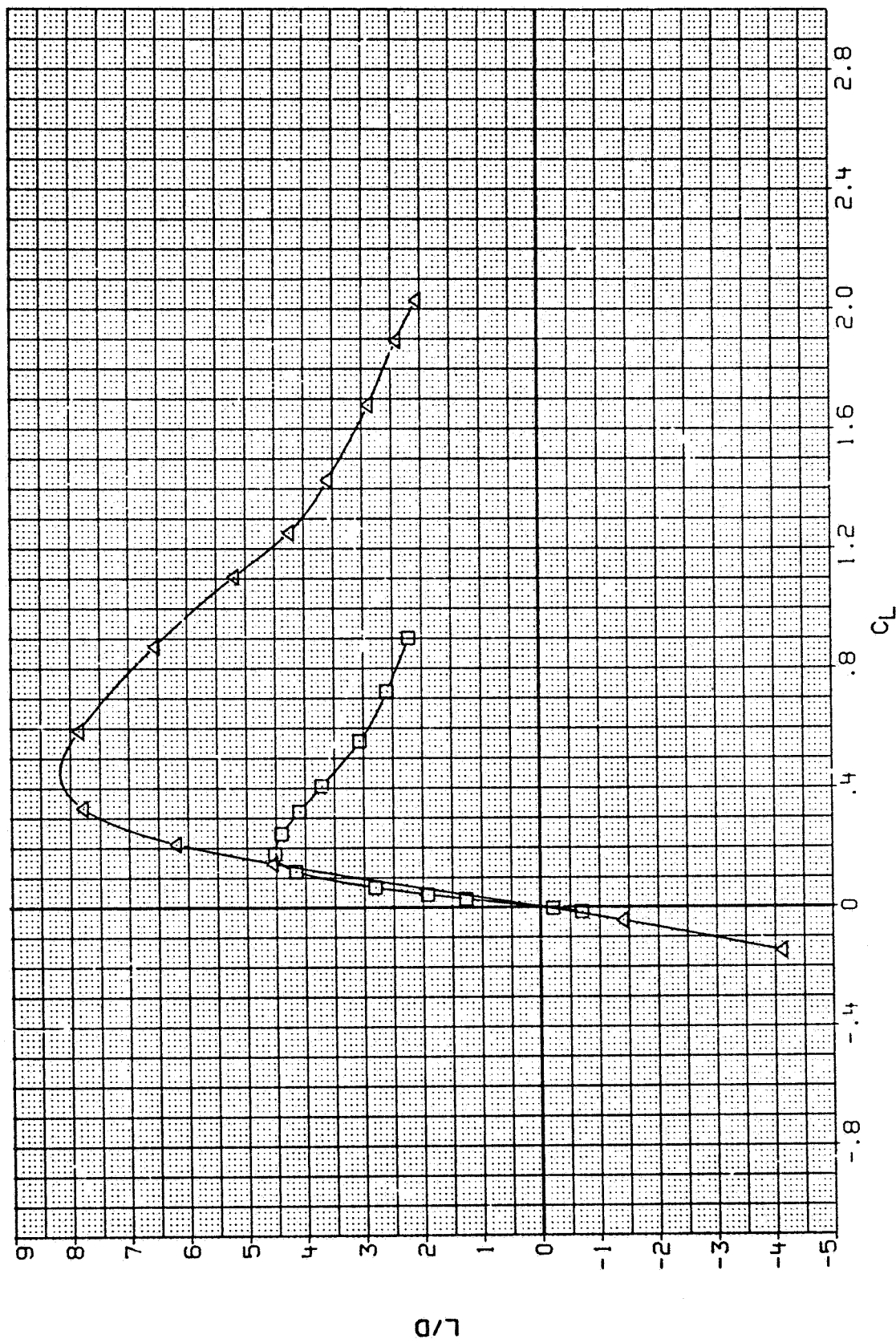


FIG. 16 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 0.95

SYMBOL CONFIGURATION

○ DATA NOT AVAILABLE (EJECTOR-E205)

□ BI SI N V

△ DATA NOT AVAILABLE (EJECTOR-E205)

◇ BI SI N WI CI V

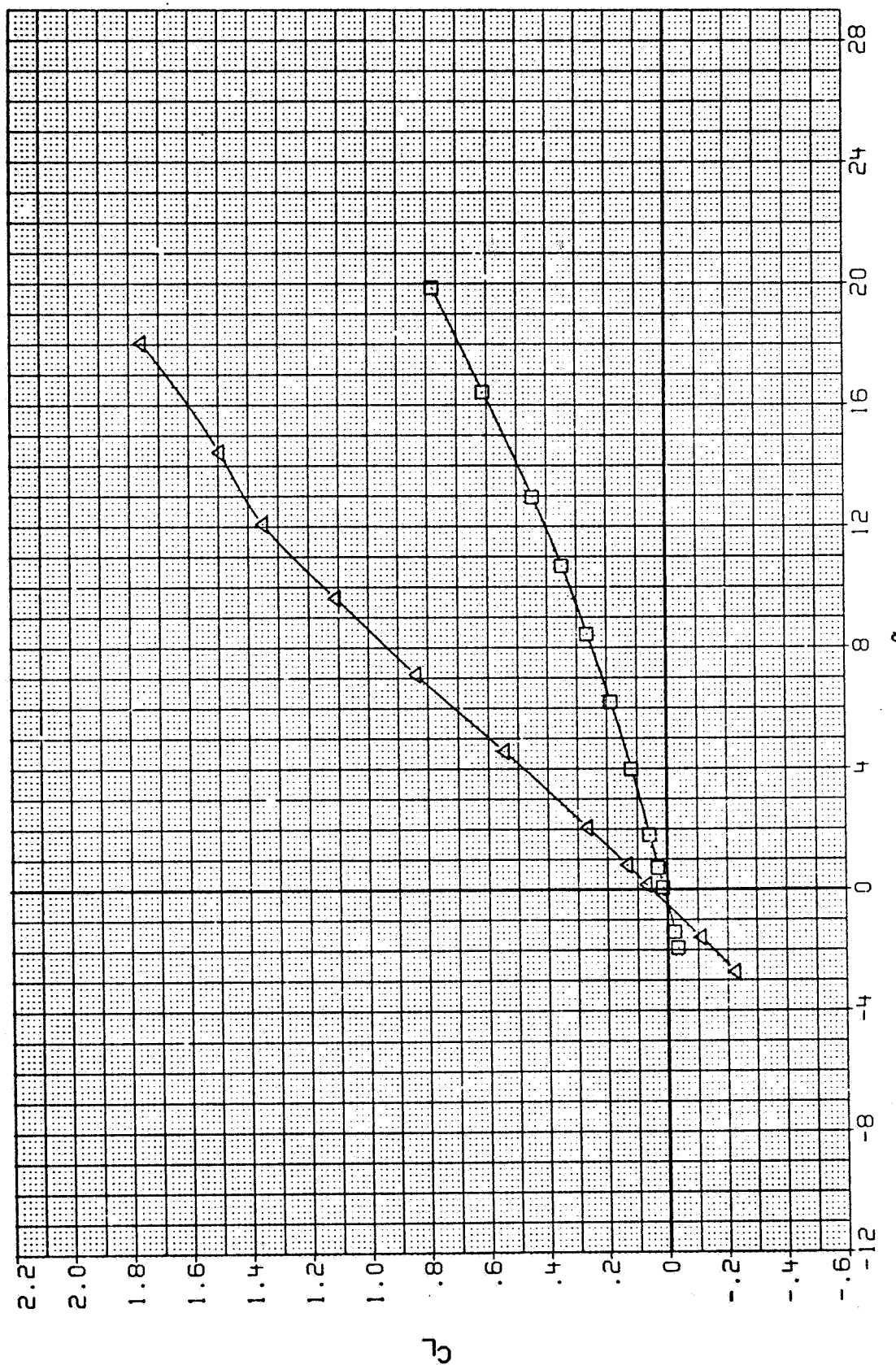


FIG. 17 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.10

SYMBOL CONFIGURATION
 □ DATA NOT AVAILABLE (EJECTOR-E205)
 BI SI N V
 △ DATA NOT AVAILABLE (EJECTOR-E205)
 BI SI N HI CI V

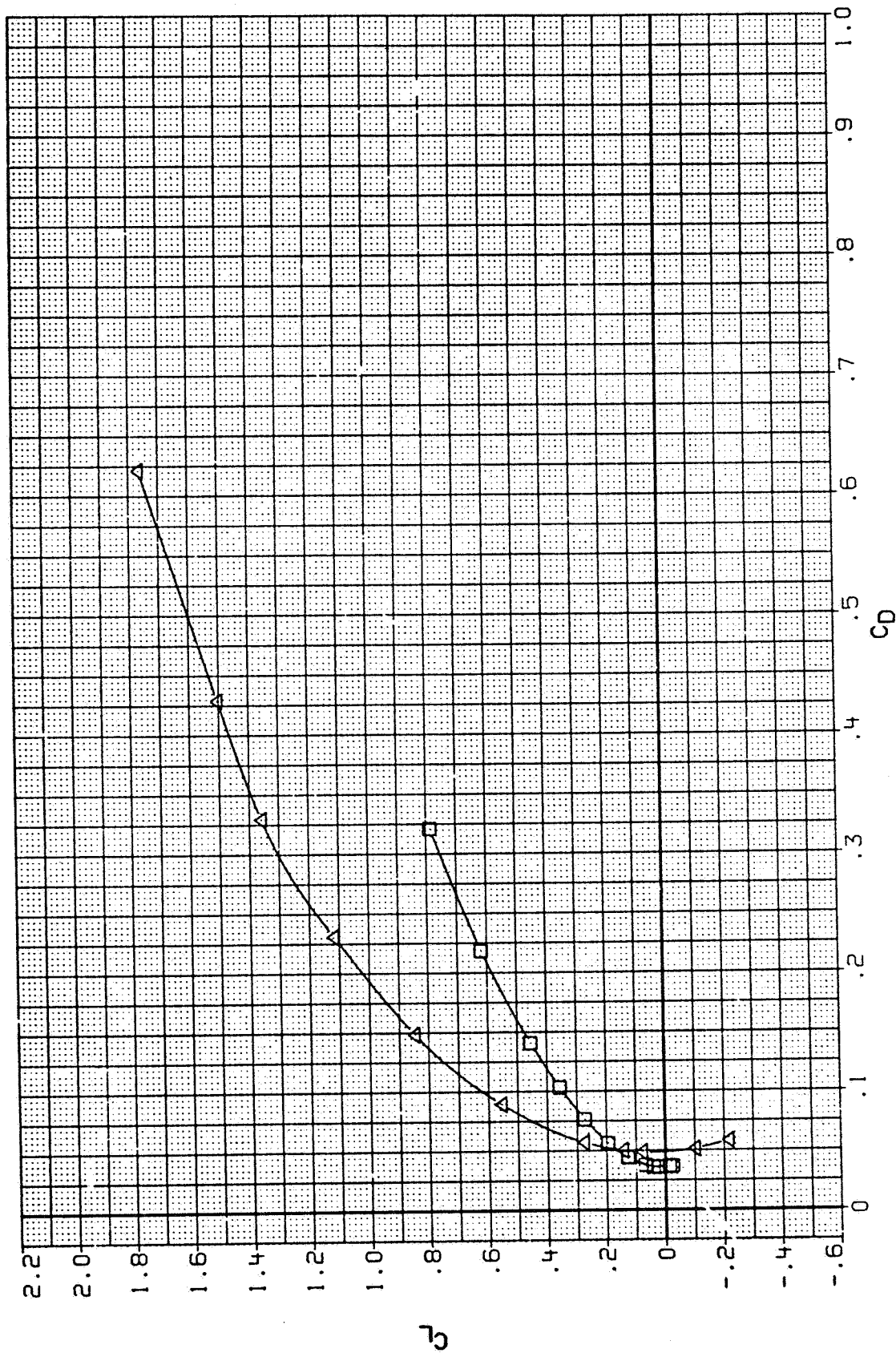


FIG. 17 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.10

SYMBOL CONFIGURATION

DATA NOT AVAILABLE (EJECTOR-E205)
 □ BI SI N V
 DATA NOT AVAILABLE
 △ BI SI N WI CI V

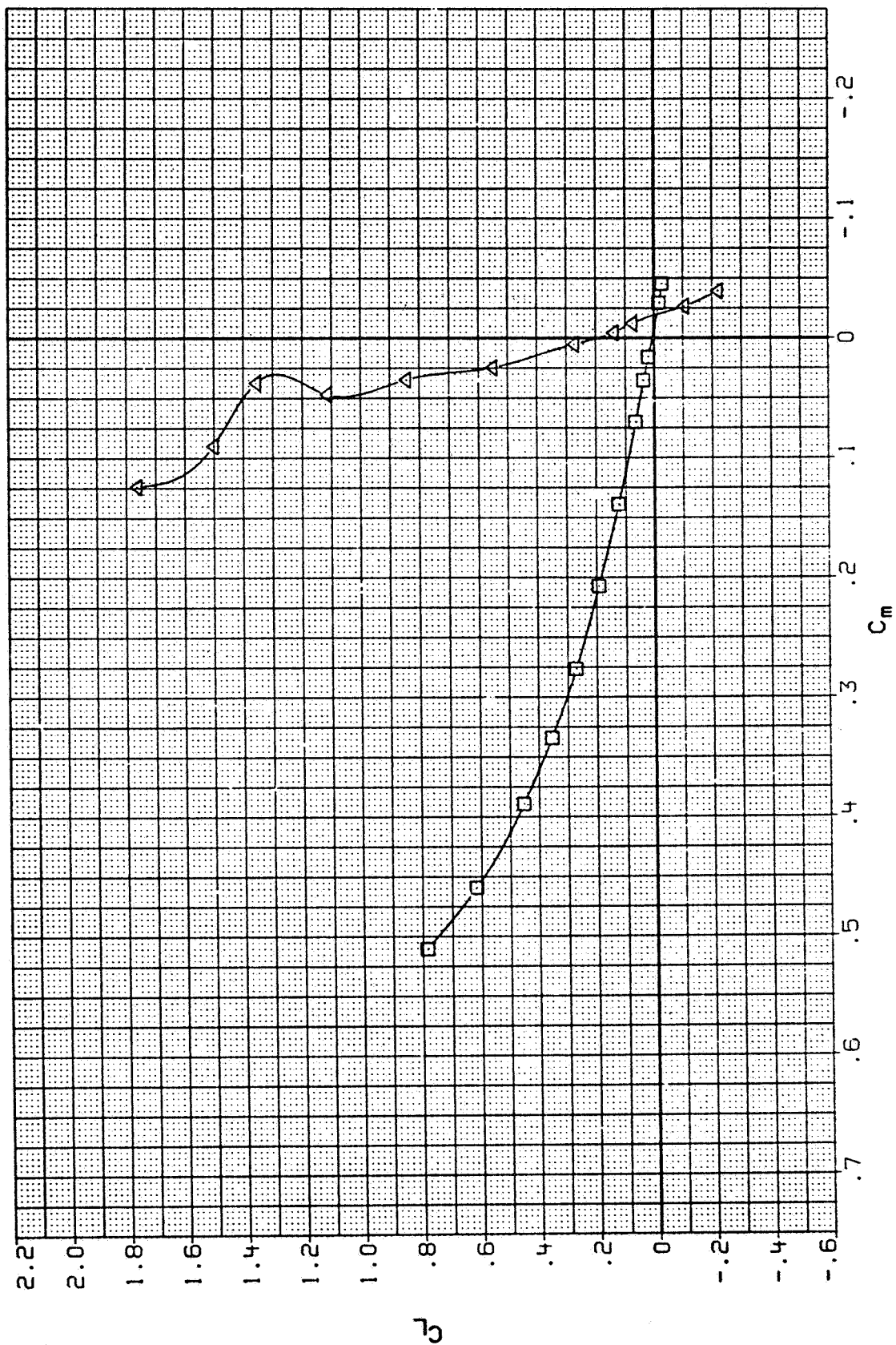


FIG. 17 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.10

SYMBOL CONFIGURATION
 DATA NOT AVAILABLE
 BI SI N V (EJECTOR-E205)
 DATA NOT AVAILABLE
 BI SI N WI CI V (EJECTOR-E205)

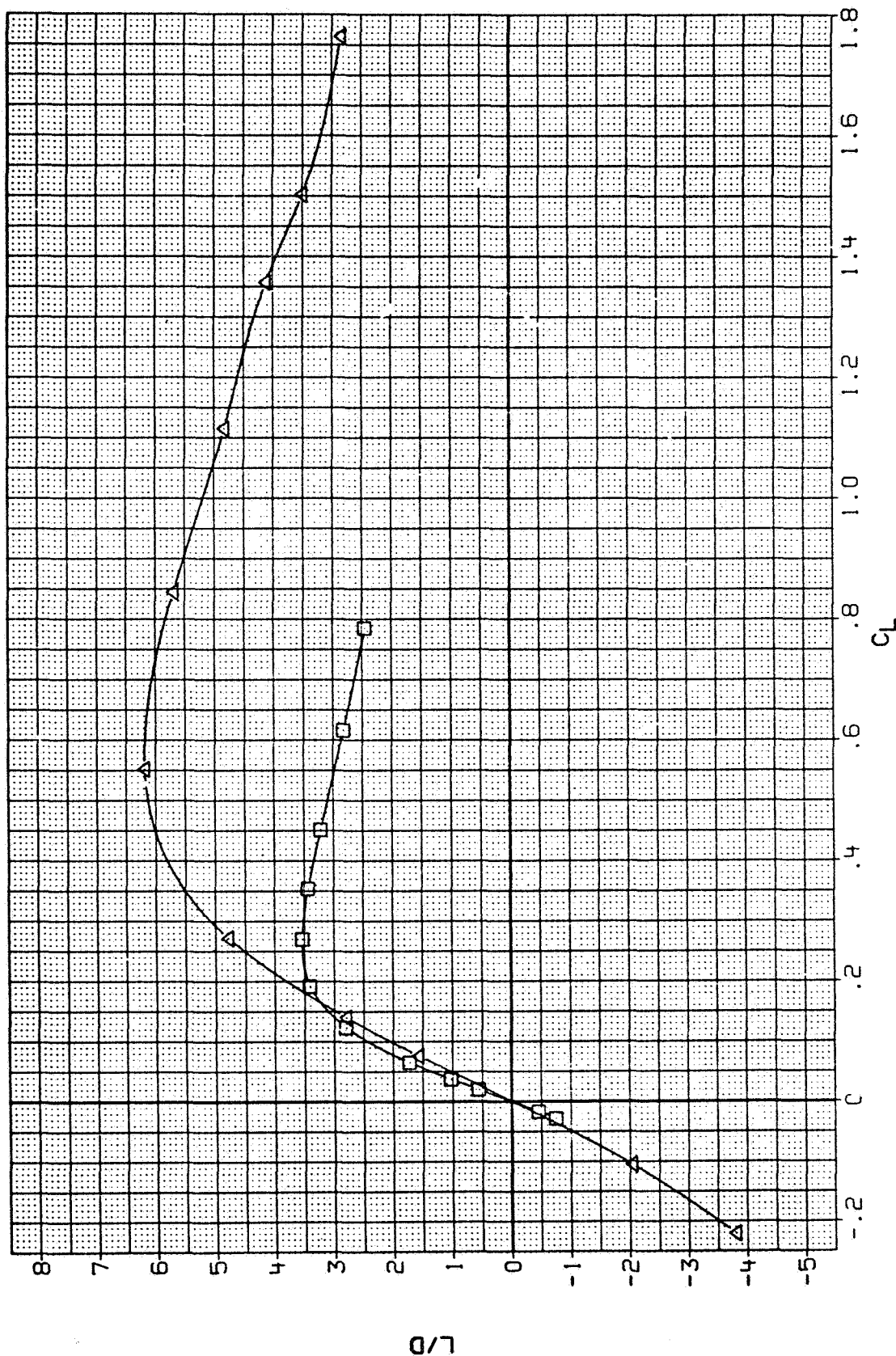


FIG. 17 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.10

SYMBOL CONFIGURATION
 □ BI SI N V (EJECTOR-E205)
 ◇ BI SI N MI V (EJECTOR-E205)
 △ BI SI N MI CI V (EJECTOR-E205)

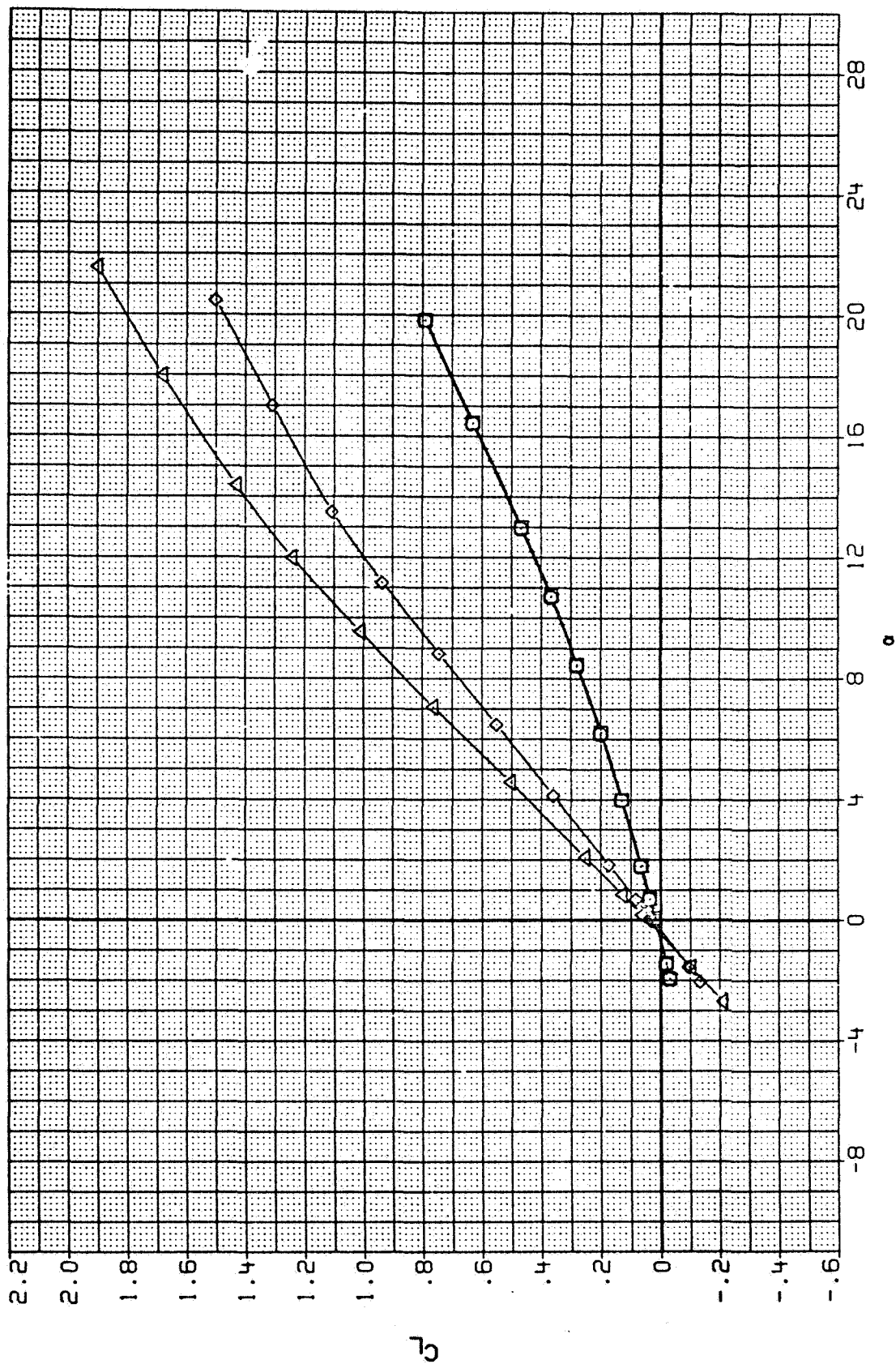


FIG. 18 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL		CONFIGURATION
□	BI SI N V	(EJECTOR-E205)
◇	BI SI N MI V	(EJECTOR-E205)
△	BI SI N MI C1 V	(EJECTOR-E205)

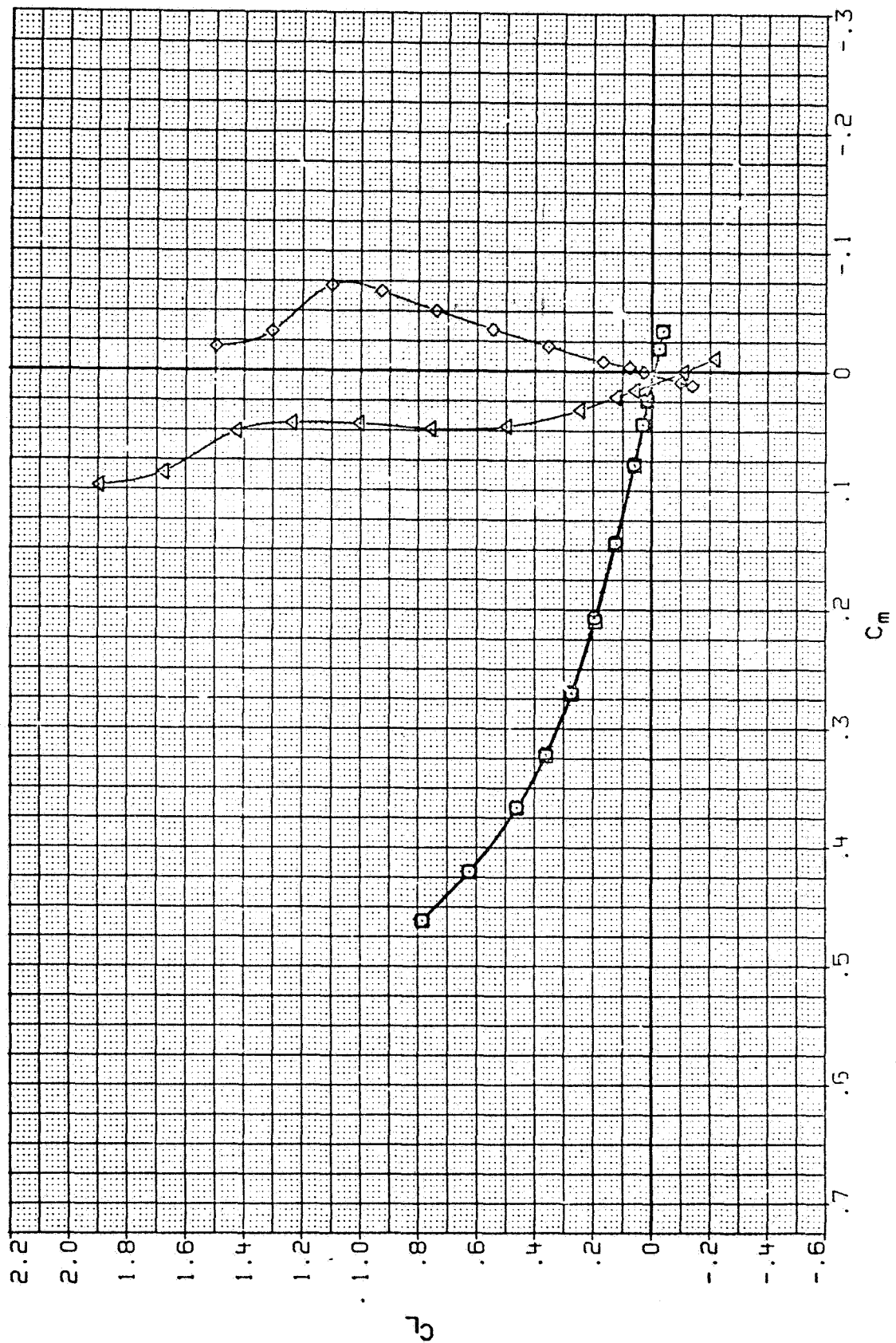


FIG. 18 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL	CONFIGURATION
○	BI SI N V (EJECTOR-E205)
□	BI SI N V (EJECTOR-E205)
△	BI SI N V (EJECTOR-E205)
◇	BI SI N V (EJECTOR-E205)

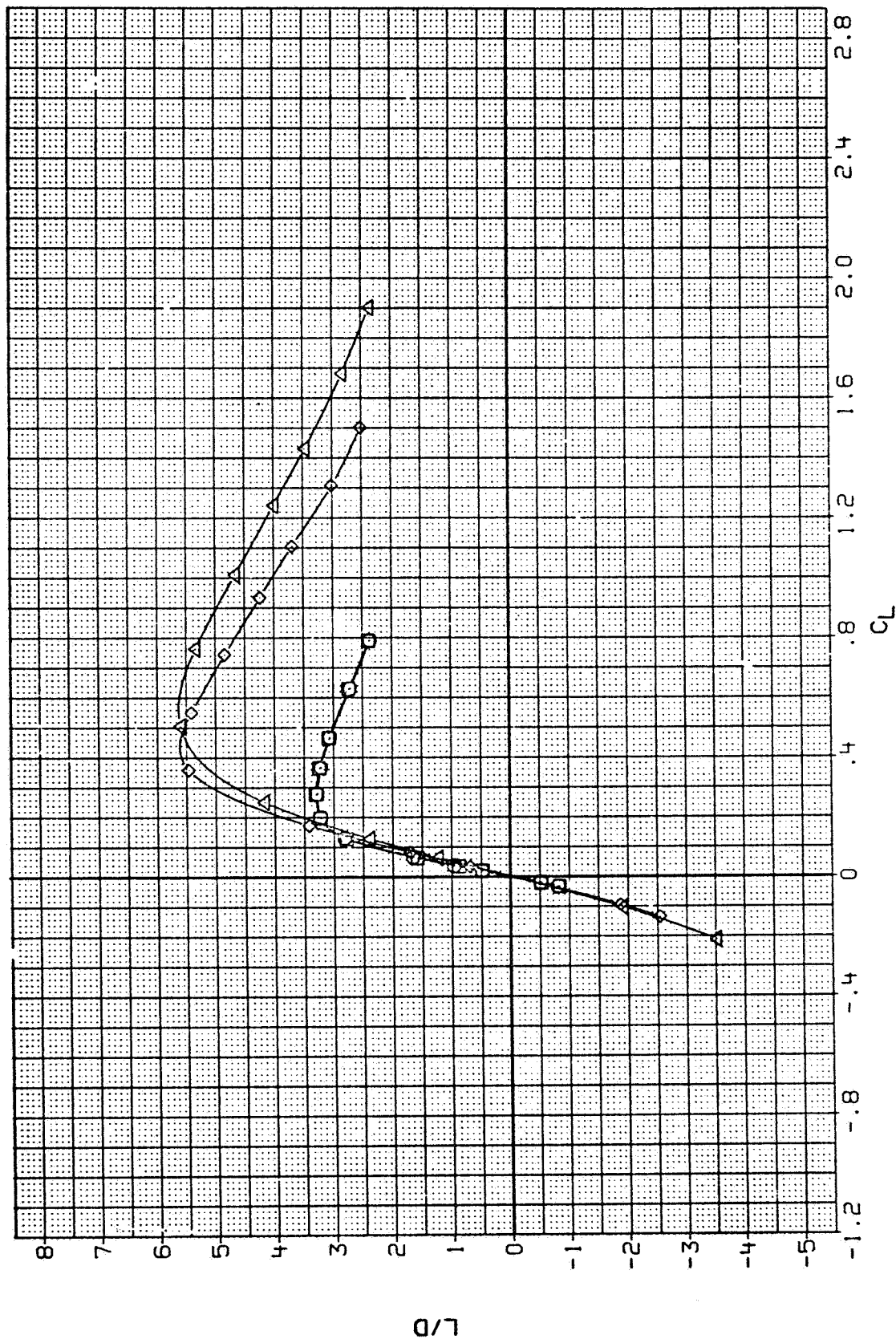


FIG. 18 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL CONFIGURATION

DATA NOT AVAILABLE
 (EJECTOR-E205)
 BI SI N V
 DATA NOT AVAILABLE
 (EJECTOR-E205)
 BI SI N WI CI V

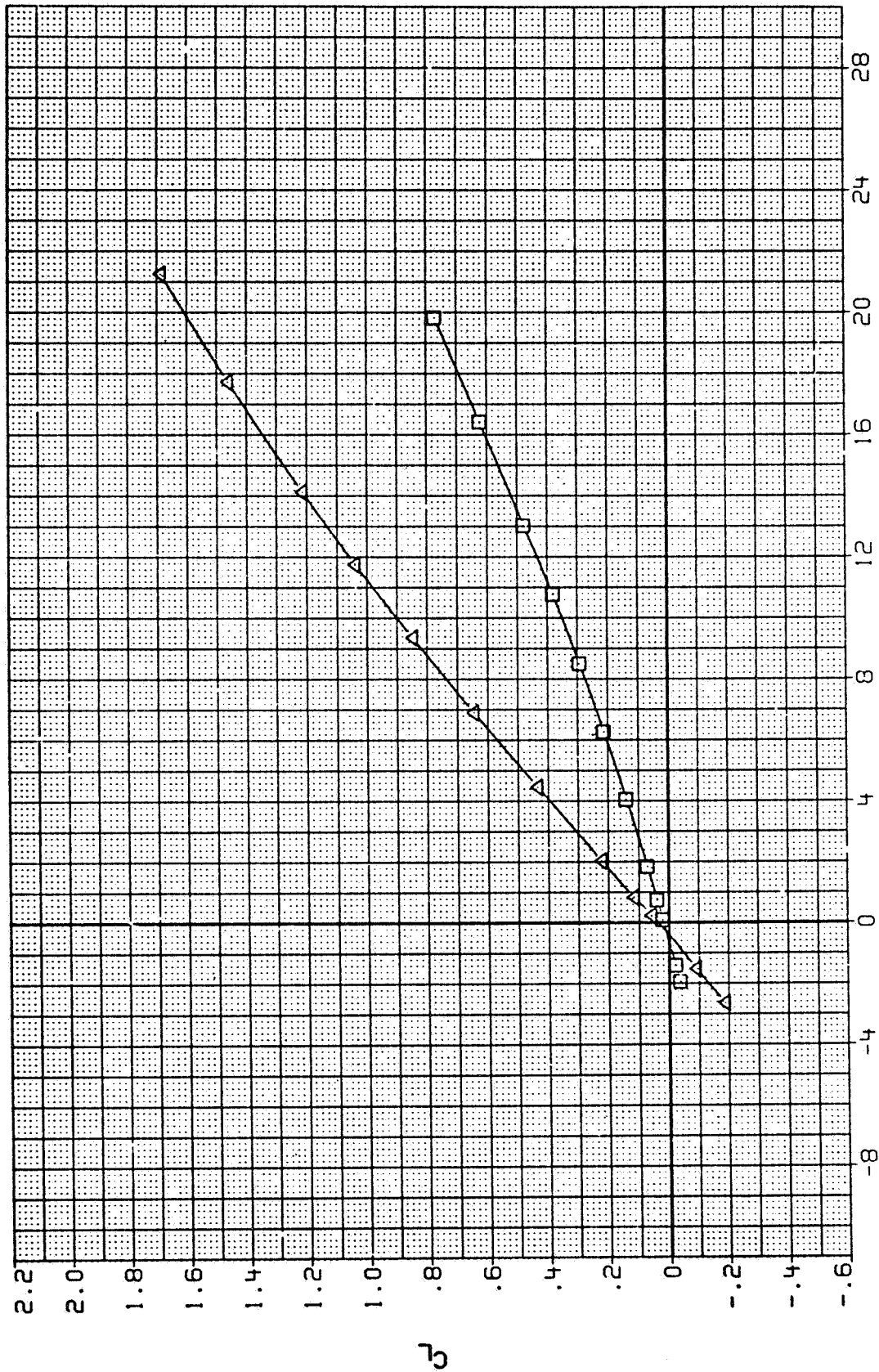


FIG. 19 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.40

SYMBOL CONFIGURATION
 DATA NOT AVAILABLE
 BI SI N V (EJECTOR-E205)
 DATA NOT AVAILABLE
 BI SI N HI CI V (EJECTOR-E205)

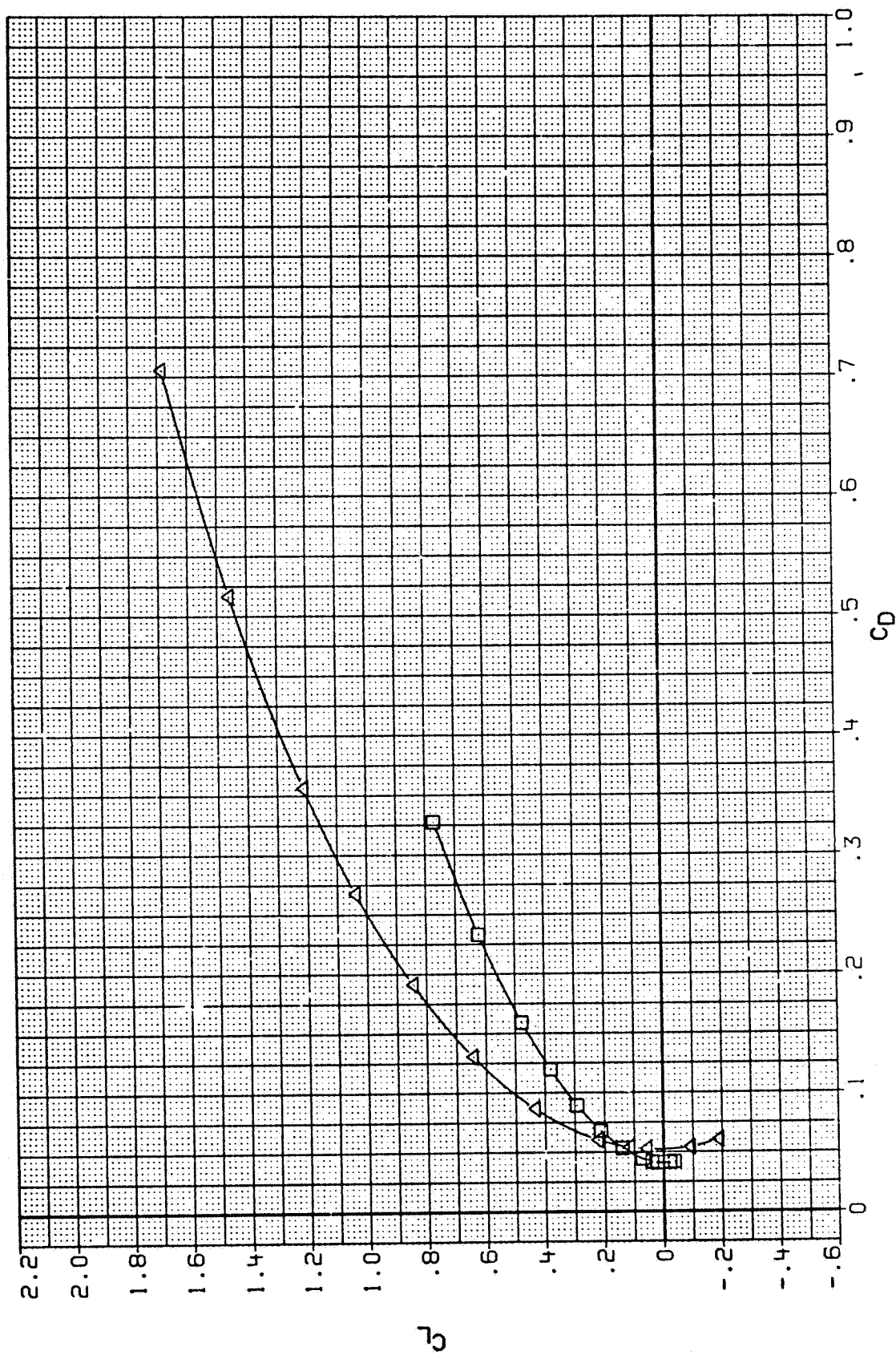


FIG. 19 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.40

SYMBOL CONFIGURATION

DATA NOT AVAILABLE

BI SI N V (EJECTOR-E205)

DATA NOT AVAILABLE

BI SI N WI CI V (EJECTOR-E205)

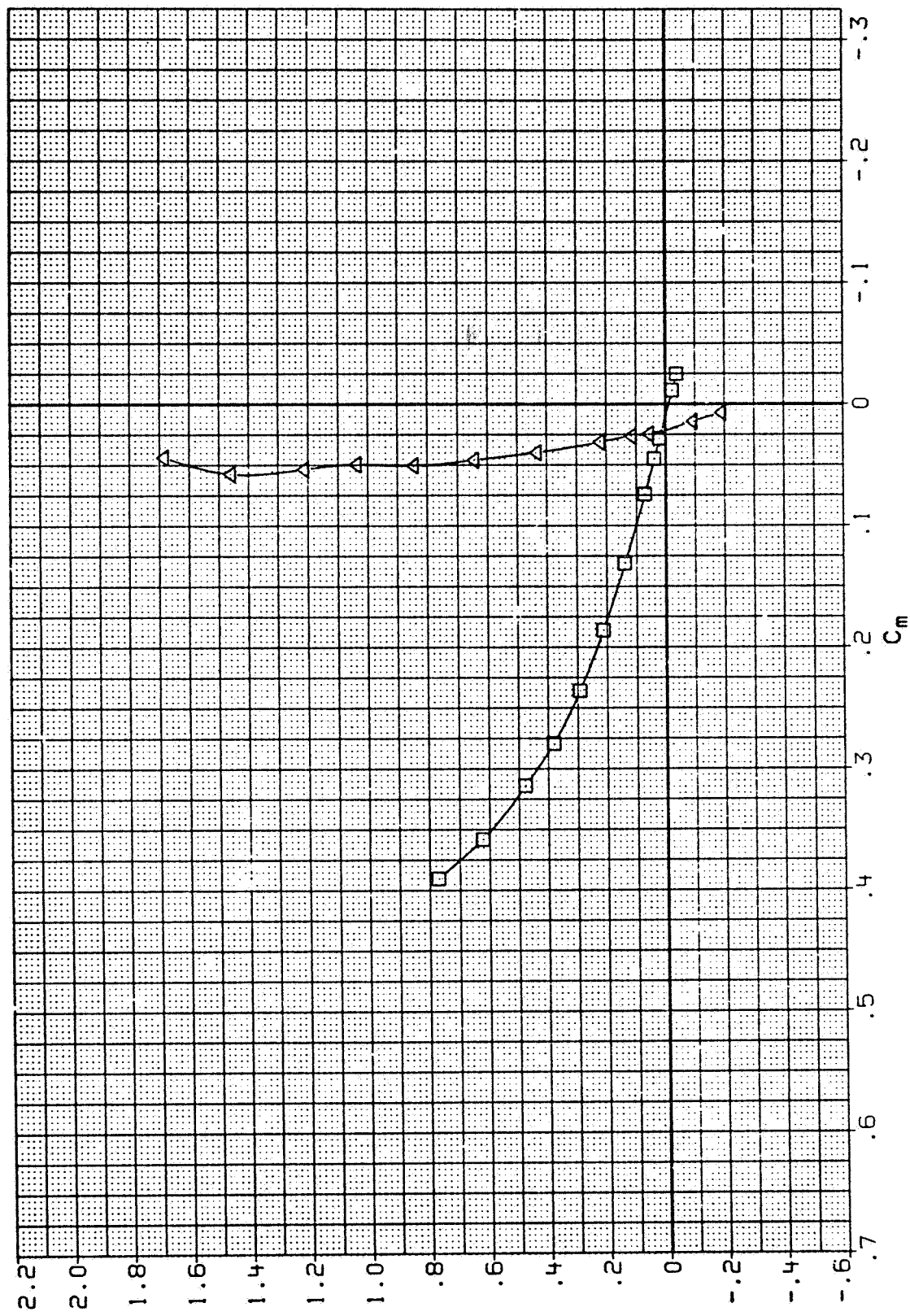


FIG. 19 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.40

SYMBOL CONFIGURATION
 DATA NOT AVAILABLE
 BI SI N V
 DATA NOT AVAILABLE
 BI SI N W C I V

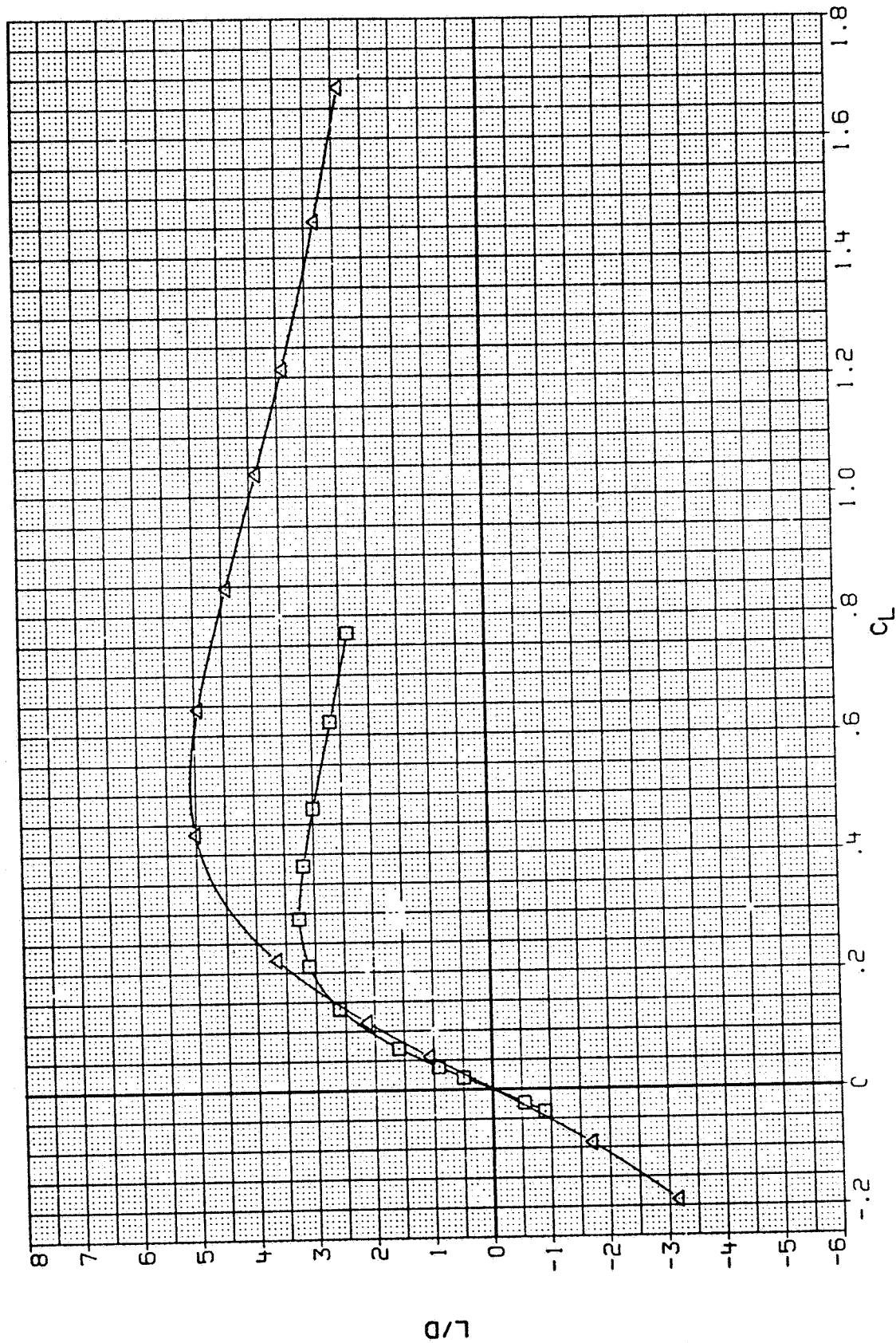


FIG. 19 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.40

SYMBOL CONFIGURATION
 □ BI SI N V (EJECTOR-E205)
 △ BI SI N V (EJECTOR-E205)
 ◇ BI SI N WI V (EJECTOR-E205)
 △ BI SI N WI C1 V (EJECTOR-E205)

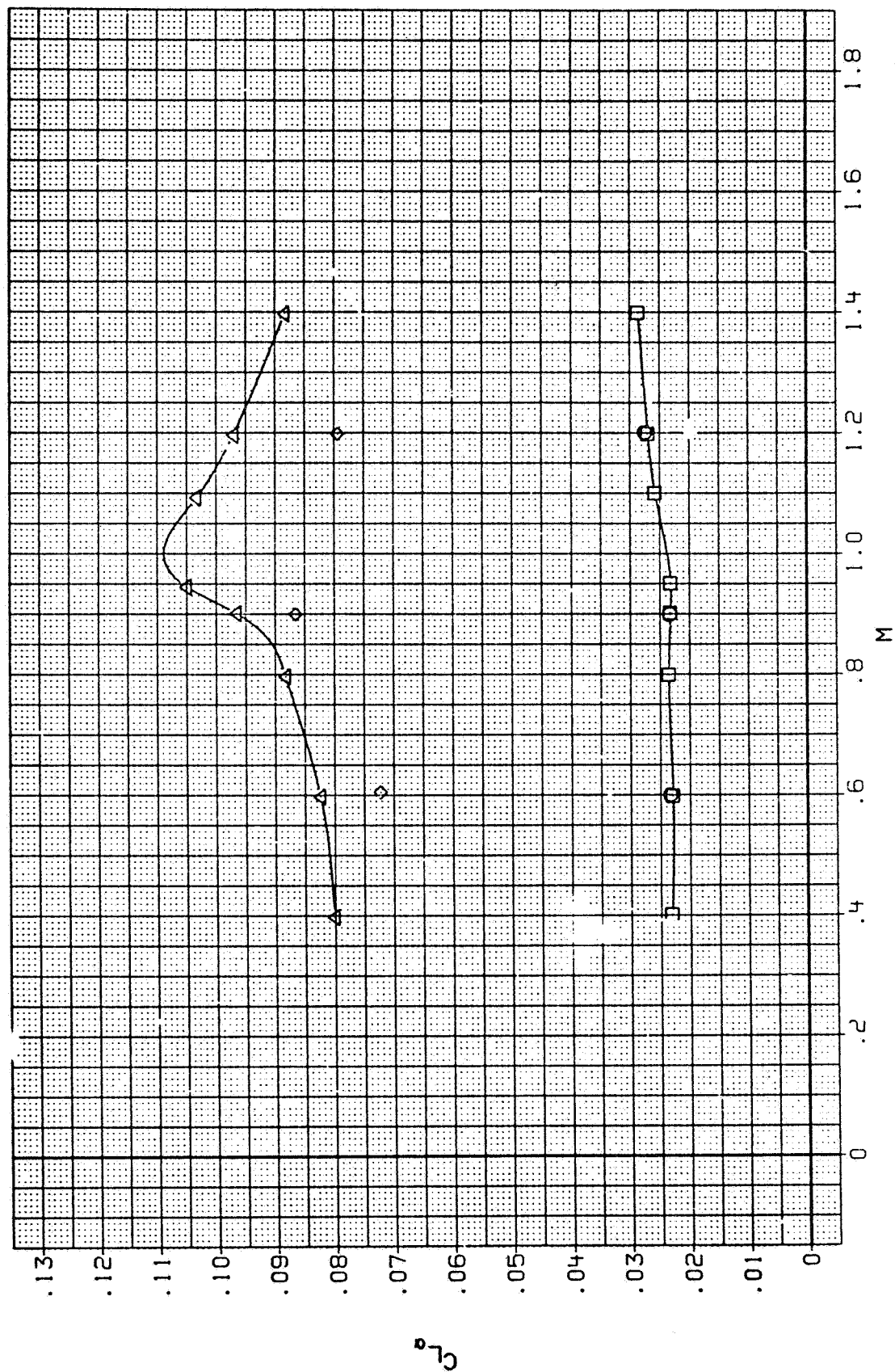


FIG. 20 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

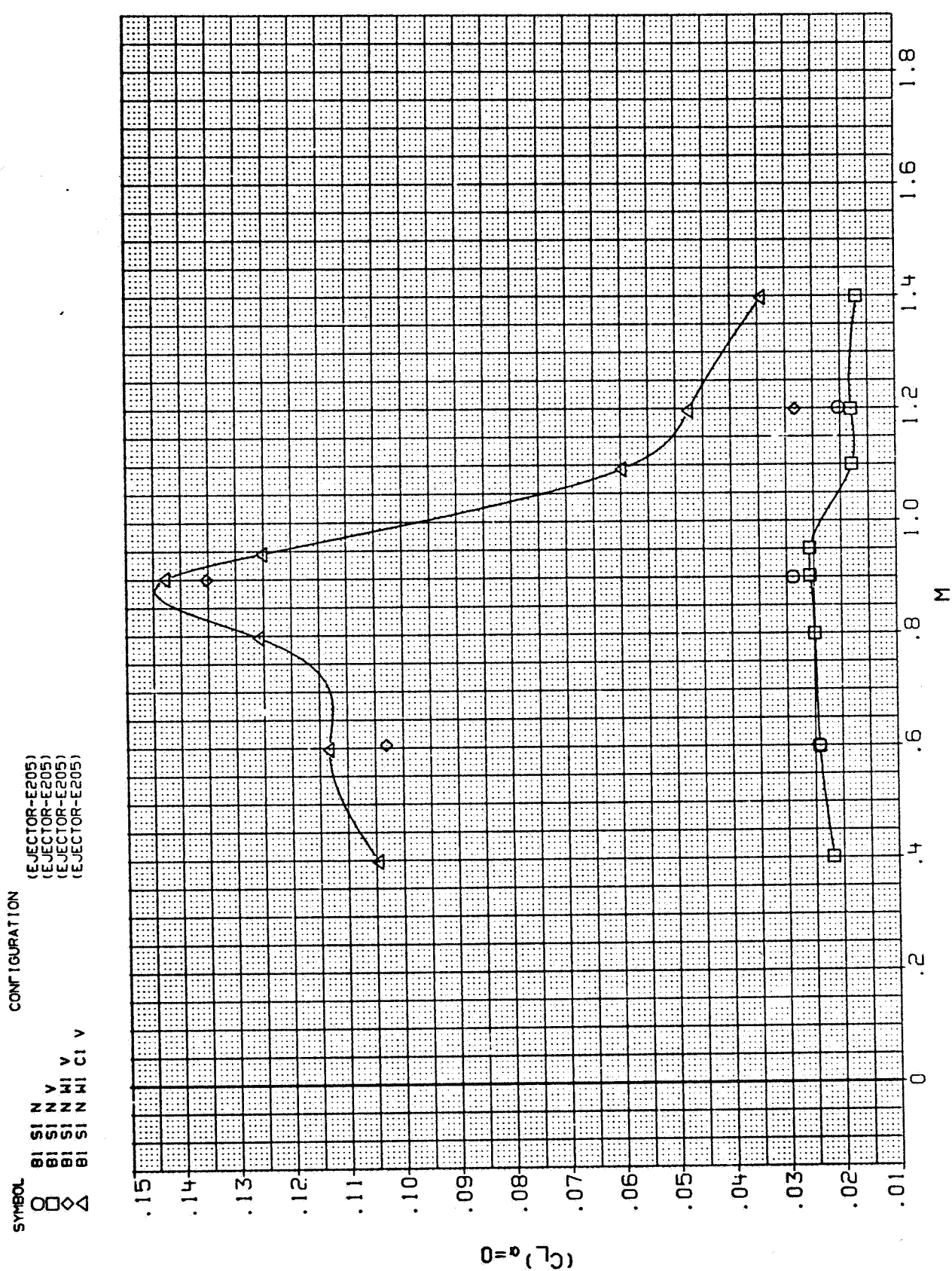


FIG. 20 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

SYMBOL	CONFIGURATION
BI SI N V	(EJECTOR-E205)
BI SI N V	(EJECTOR-E205)
BI SI N V	(EJECTOR-E205)
BI SI N V	(EJECTOR-E205)

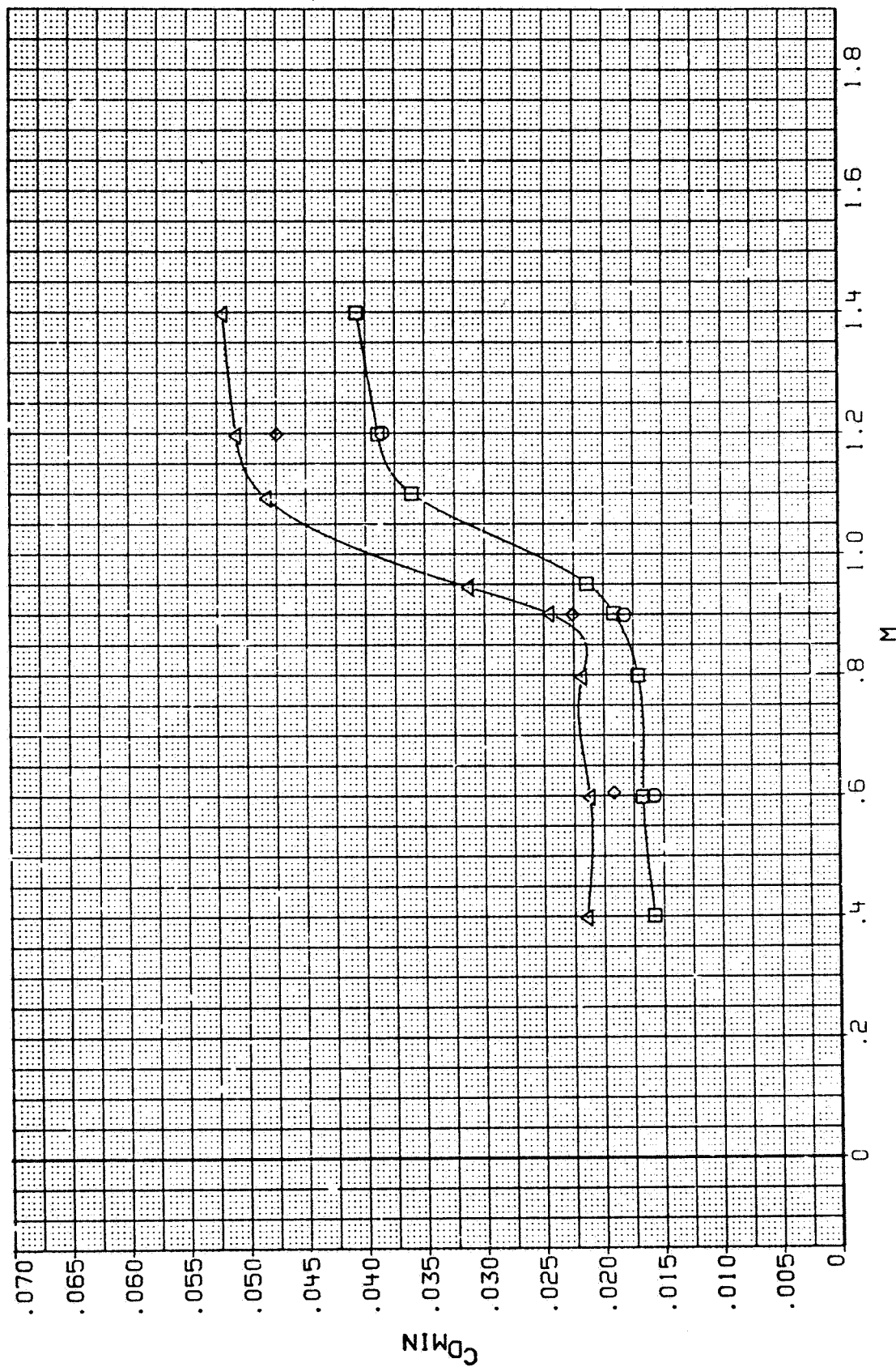


FIG. 20 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

SYMBOL CONFIGURATION
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

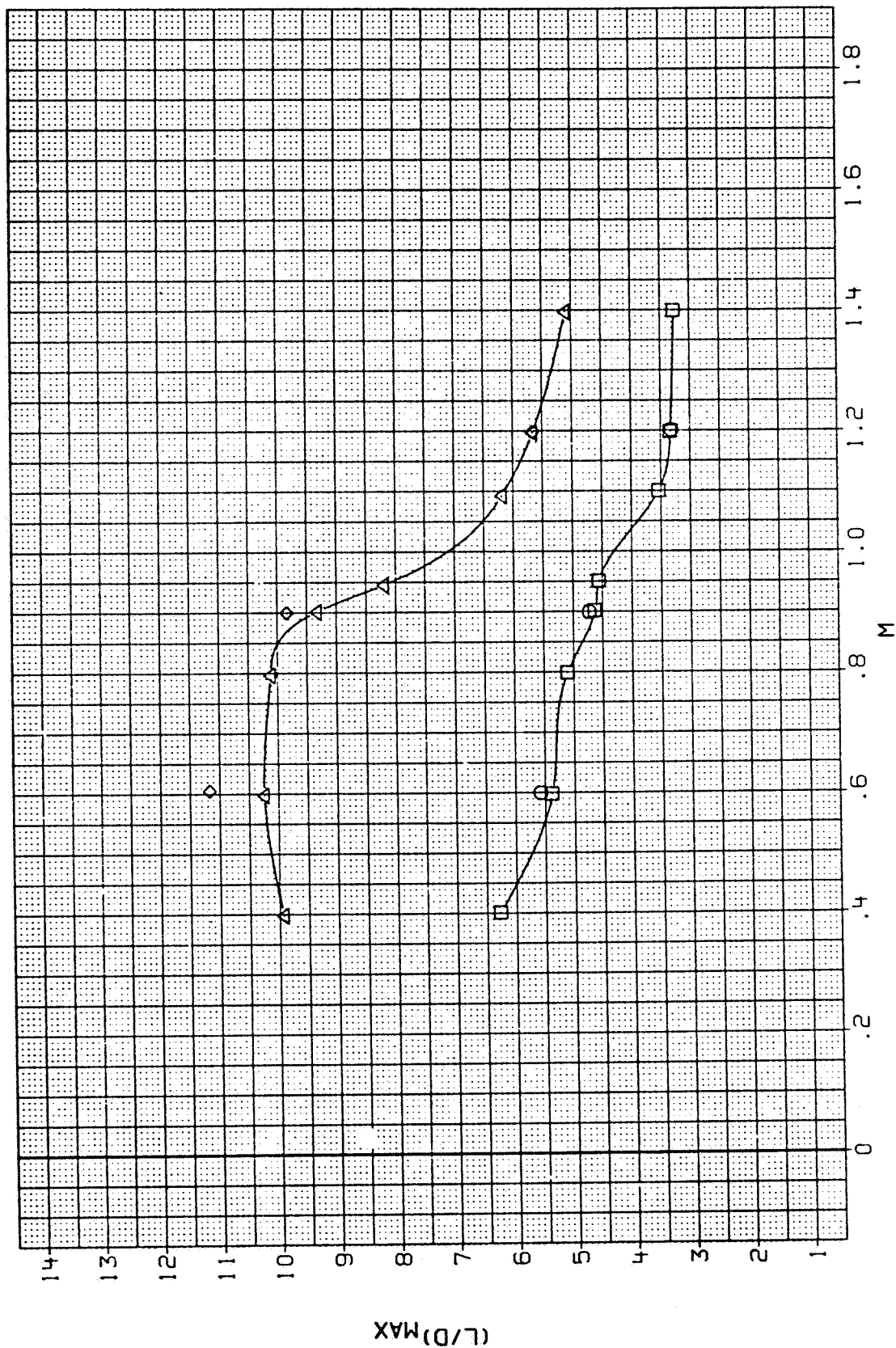


FIG. 20 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

SYMBOL	BI	SI	N	W	V	CI	Y	CONFIGURATION
○								(EJECTOR-E205)
□								(EJECTOR-E205)
◇								(EJECTOR-E205)
△								(EJECTOR-E205)

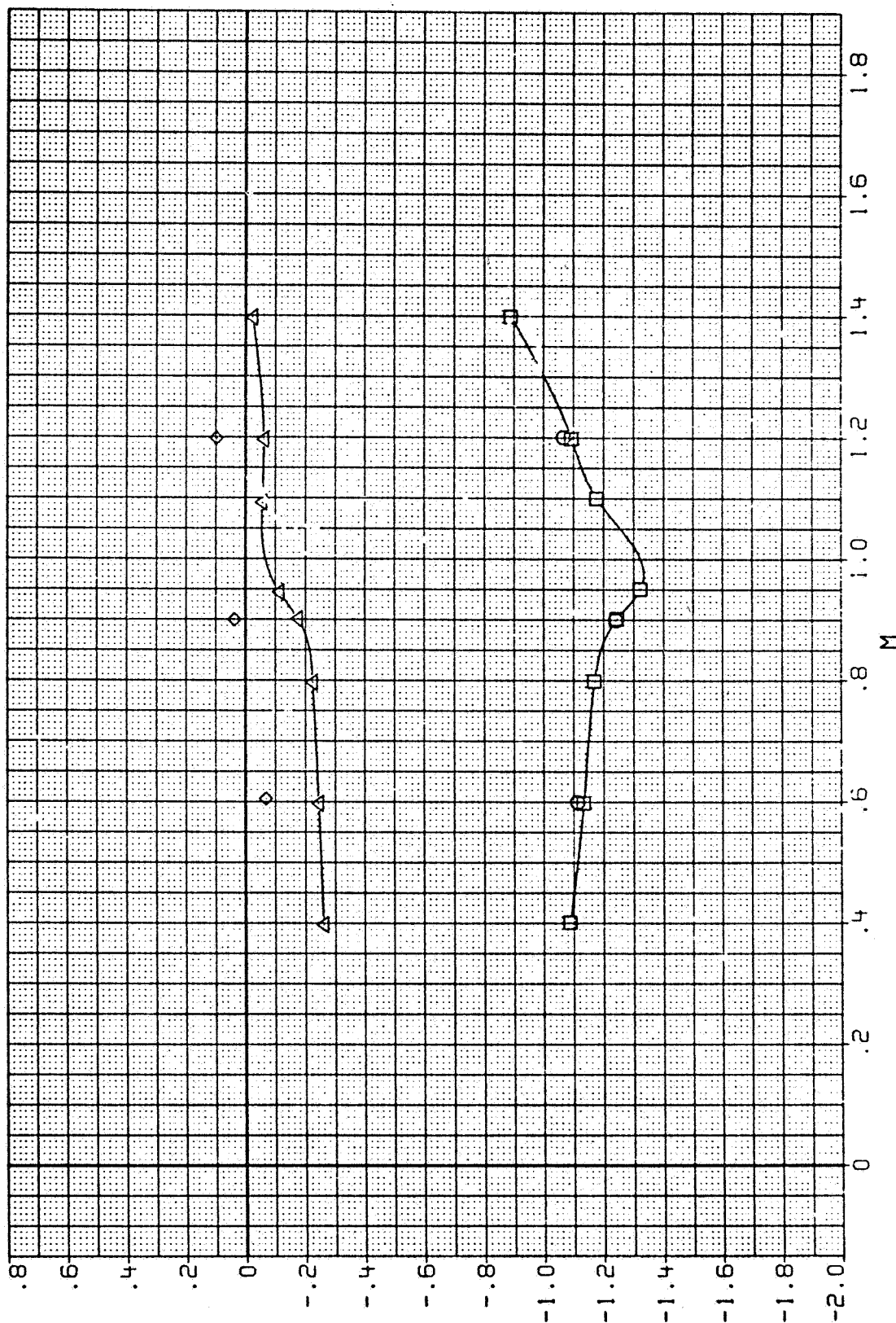


FIG. 20 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

SYMBOL CONFIGURATION
 BI SI N V (EJECTOR-E205)
 BI SI N V (EJECTOR-E205)
 BI SI N V (EJECTOR-F205)
 BI SI N V (EJECTOR-E205)

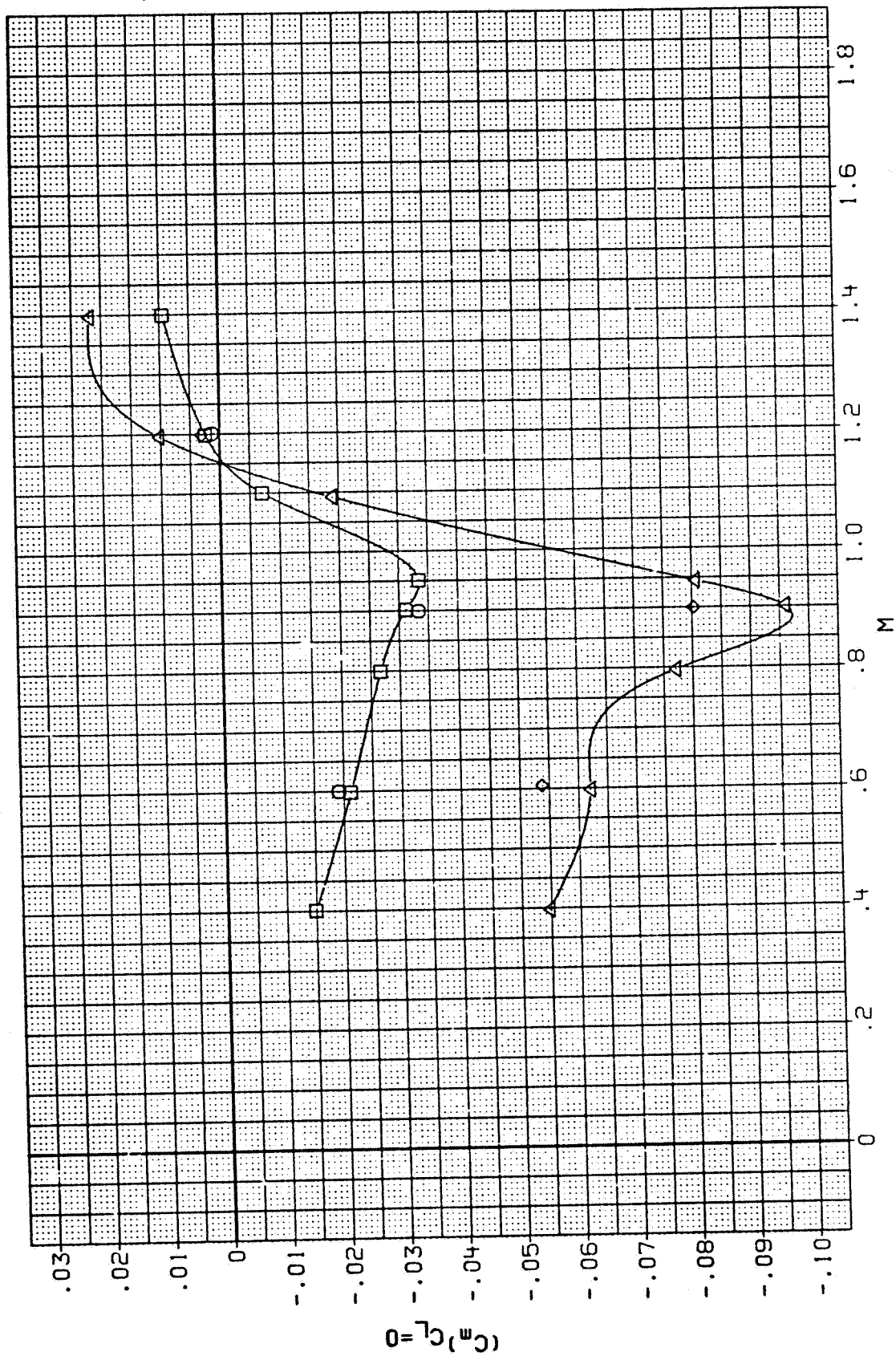


FIG. 20 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

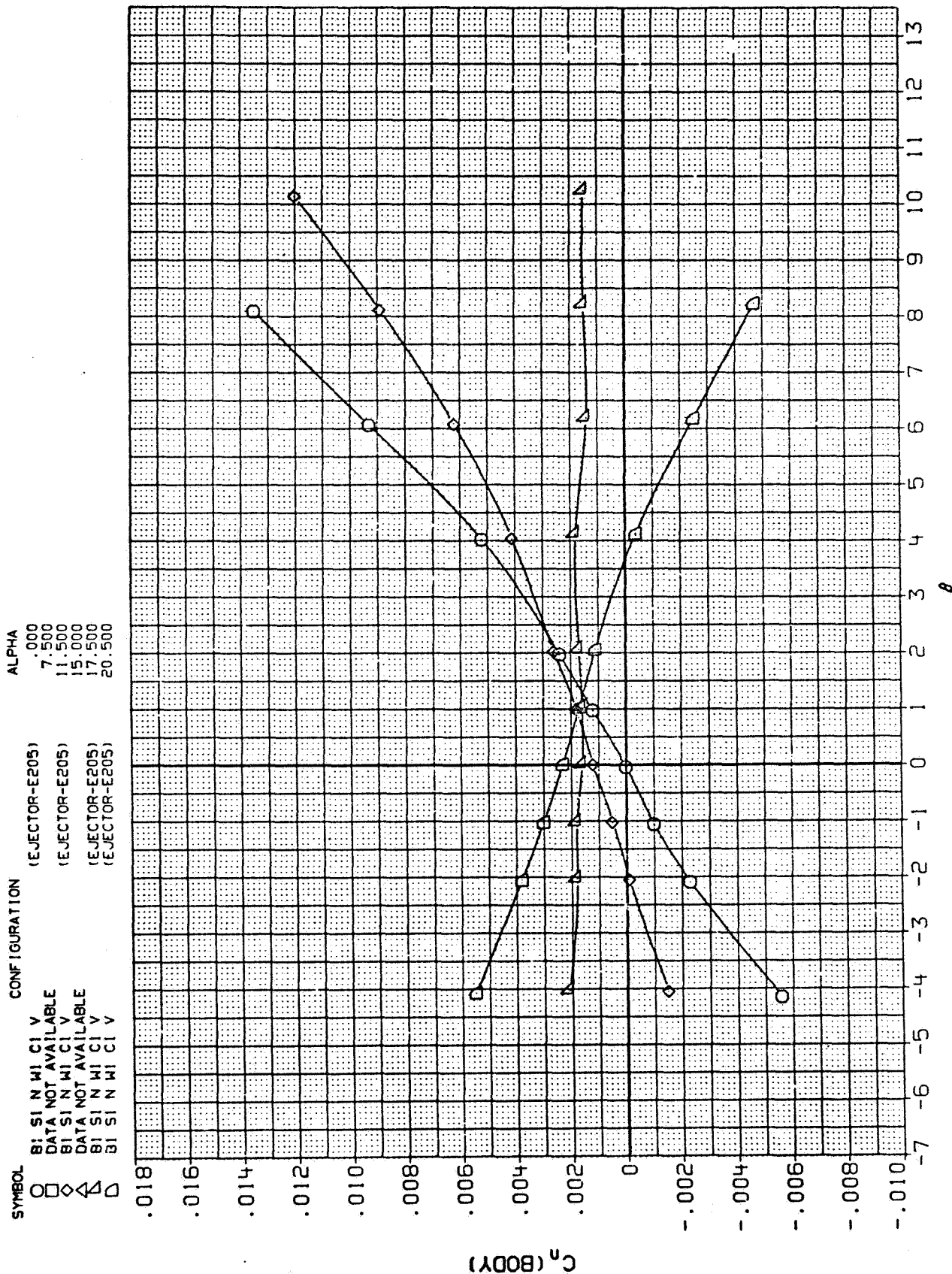


FIG. 21 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .60

SYMBOL		CONFIGURATION		ALPHA
○	BI SI N WI CI V	(EJECTOR-E205)		.000
◇	DATA NOT AVAILABLE			7.500
△	BI SI N WI CI V	(EJECTOR-E205)		11.500
△	DATA NOT AVAILABLE			15.000
◇	BI SI N WI CI V	(EJECTOR-E205)		17.500
◇	BI SI N WI CI V	(EJECTOR-E205)		20.500

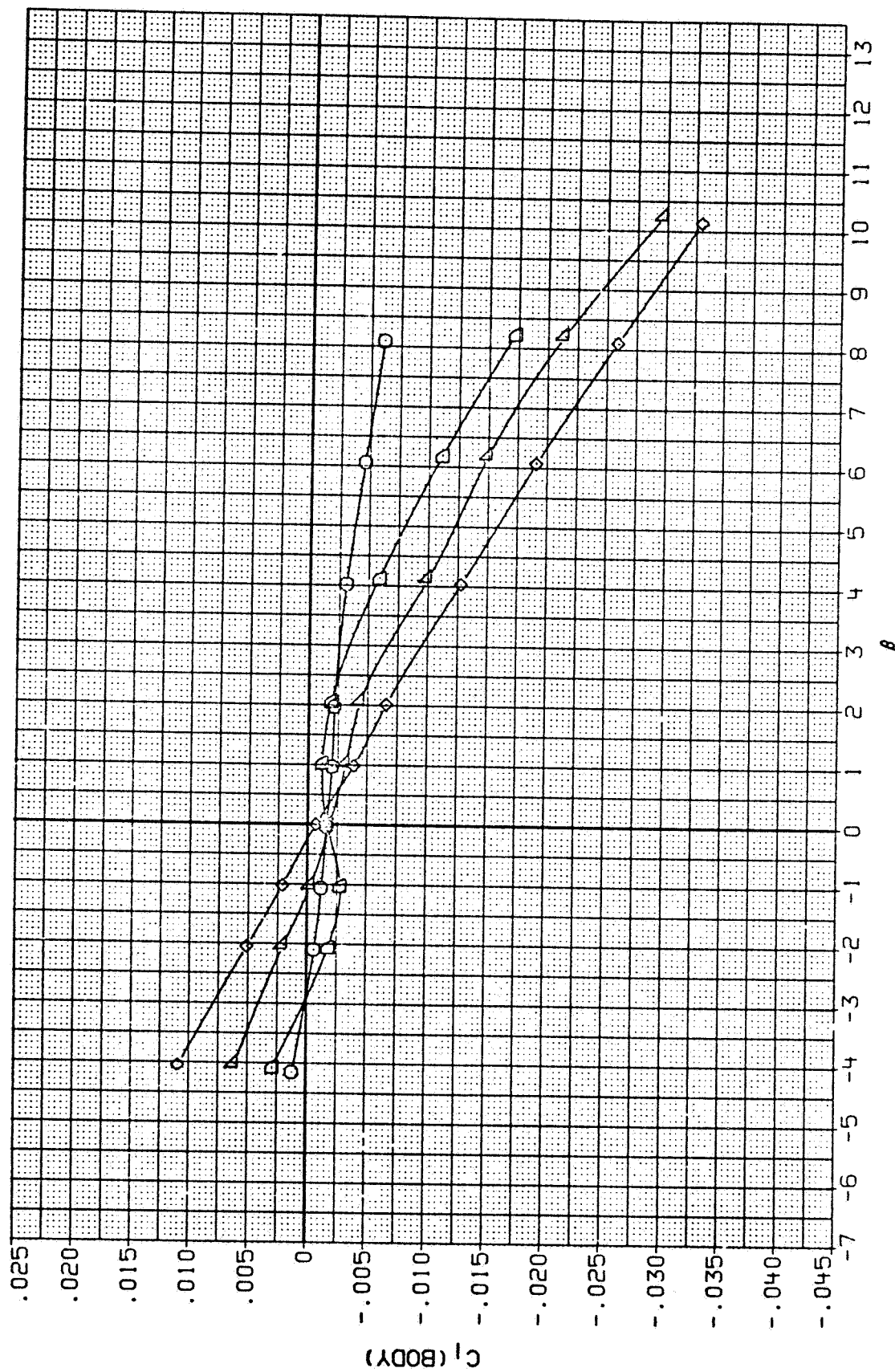


FIG. 21 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .60

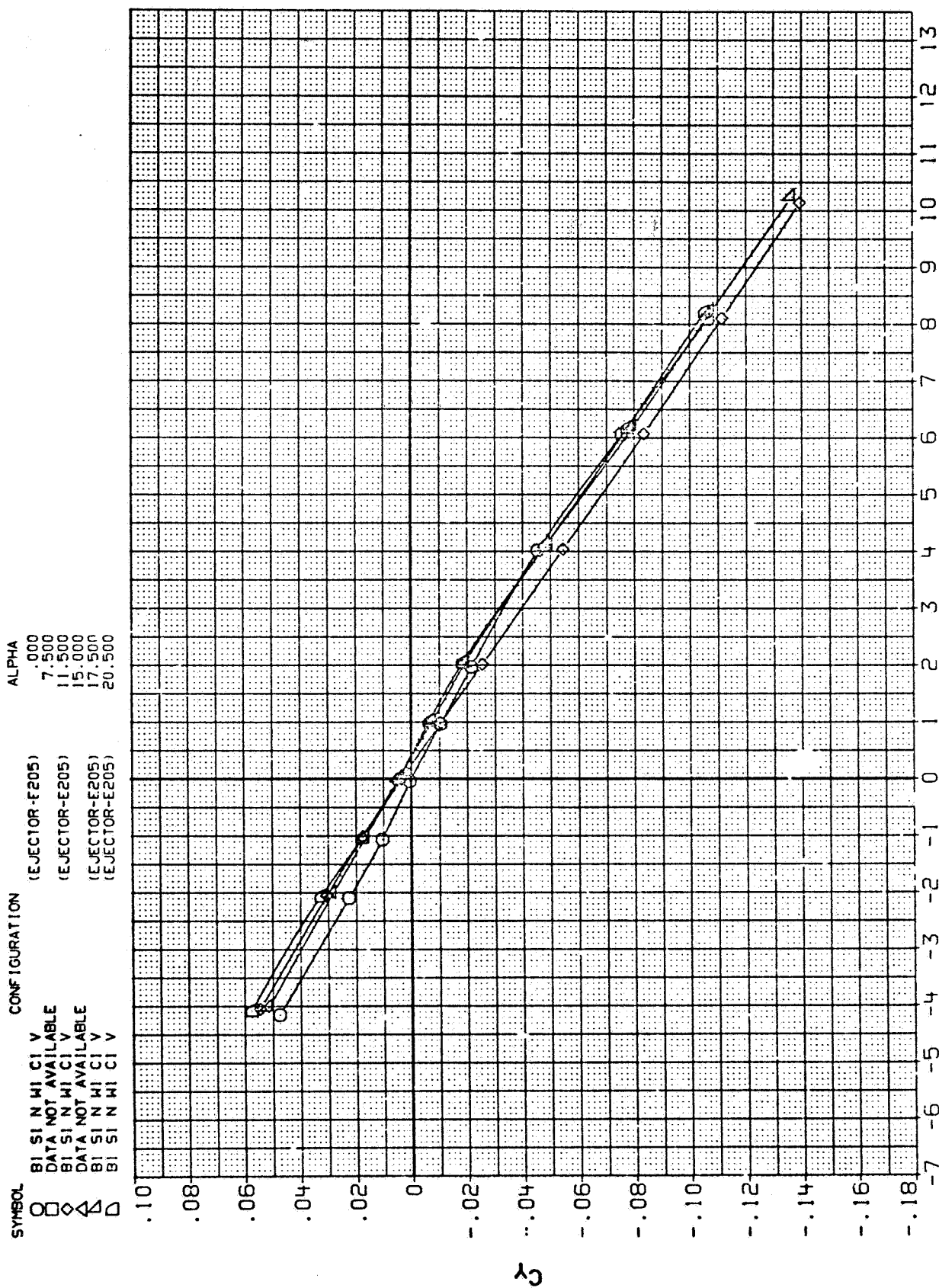


FIG. 21 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .60

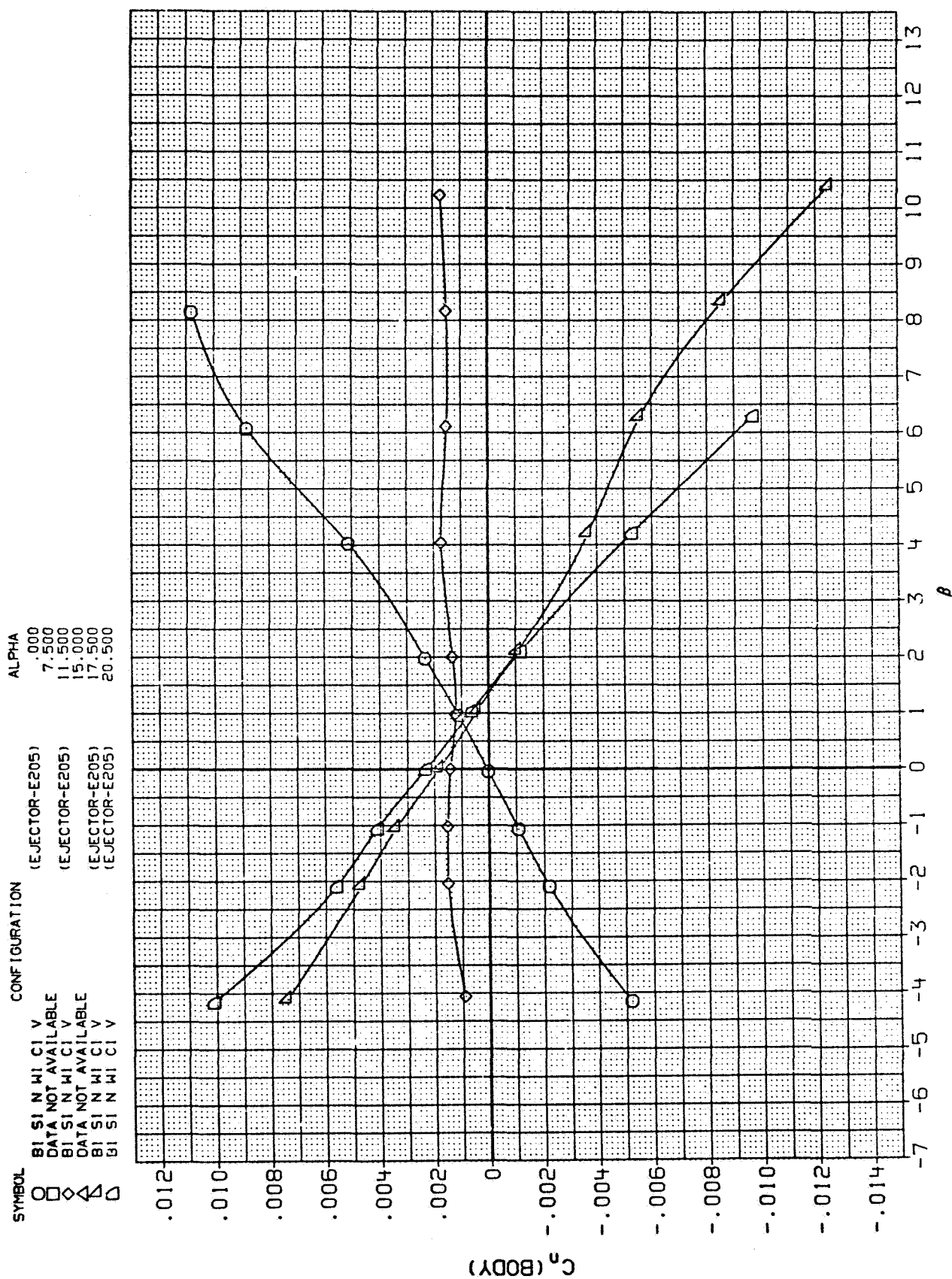


FIG. 22 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .90

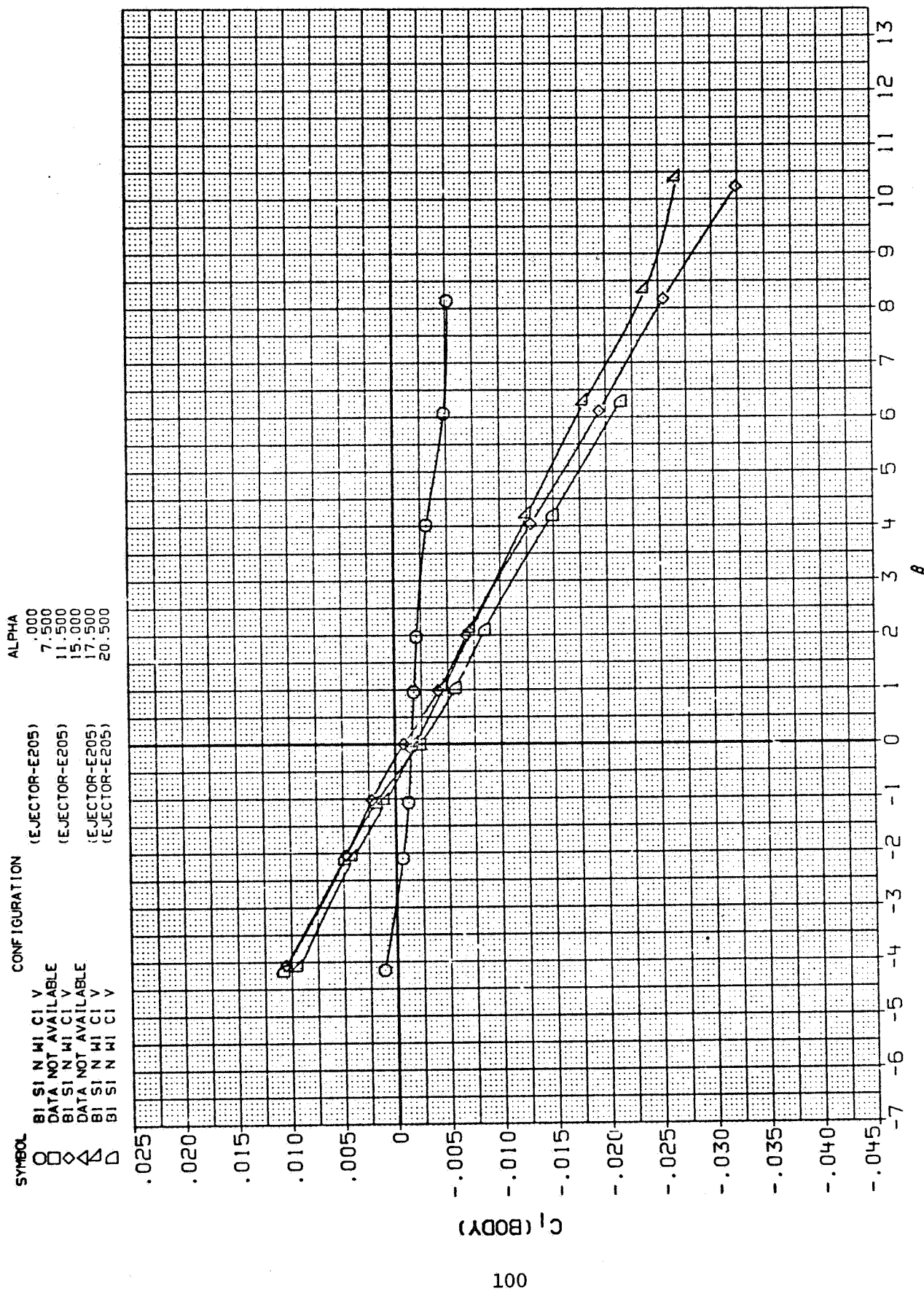


FIG. 22 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .90

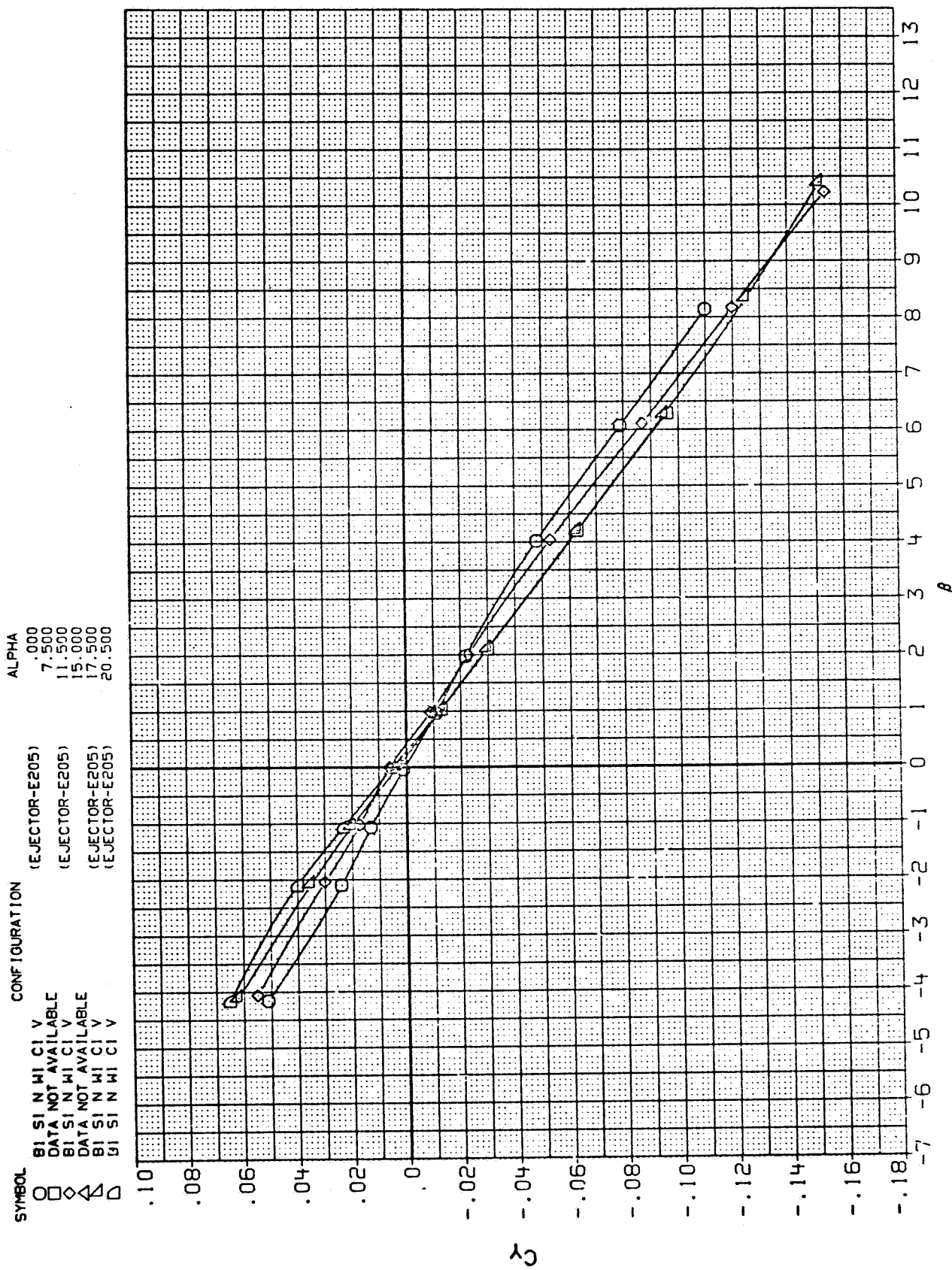


FIG. 22 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .90

SYMBOL	CONFIGURATION	ALPHA
BI SI N HI CI V	(EJECTOR-E205)	.000
BI SI N HI CI V	(EJECTOR-E205)	7.500
DATA NOT AVAILABLE		11.500
BI SI N HI CI V	(EJECTOR-E205)	15.000
BI SI N HI CI V	(EJECTOR-E205)	17.500
DATA NOT AVAILABLE		20.500

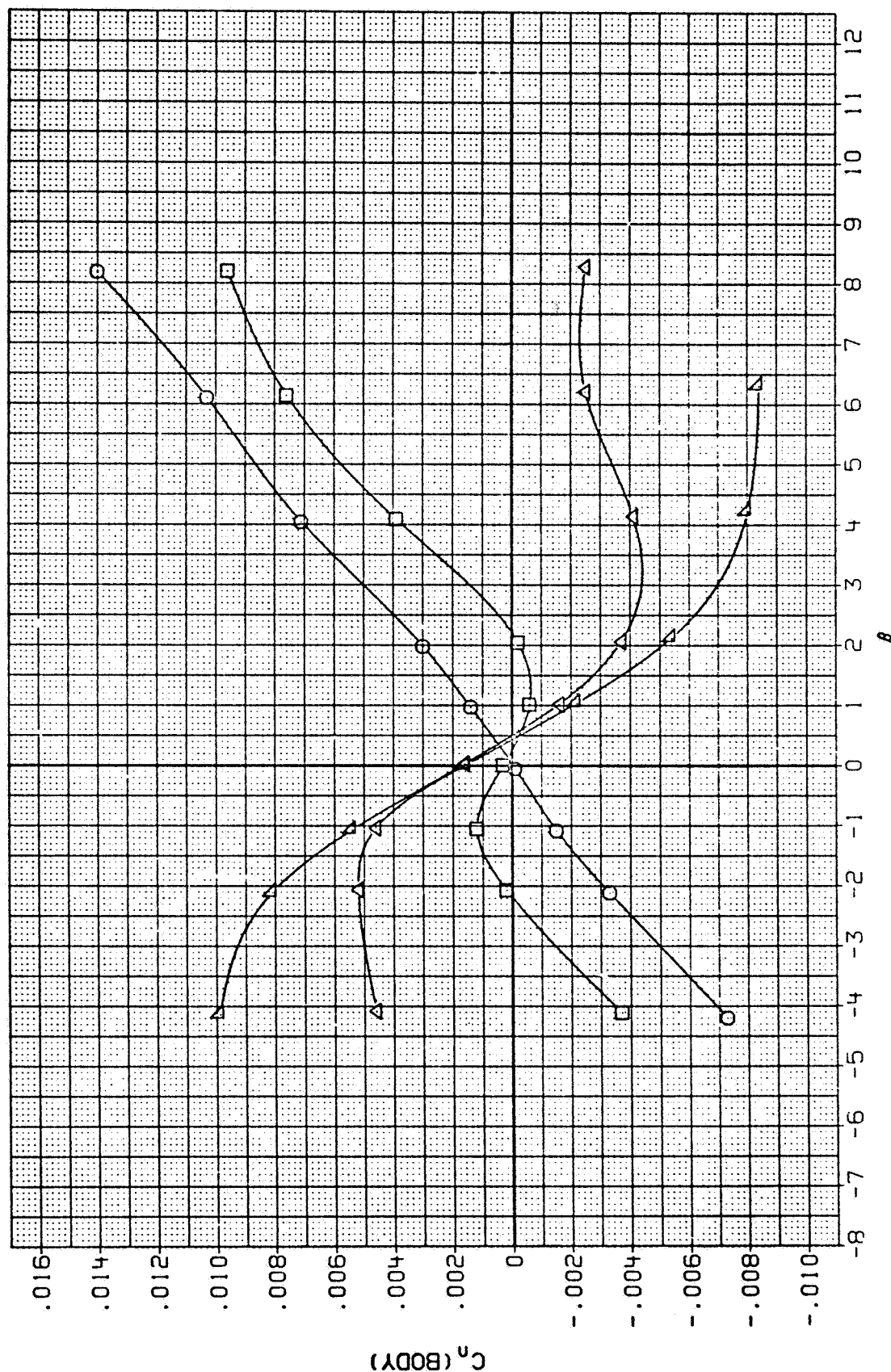


FIG. 23 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = 1.20

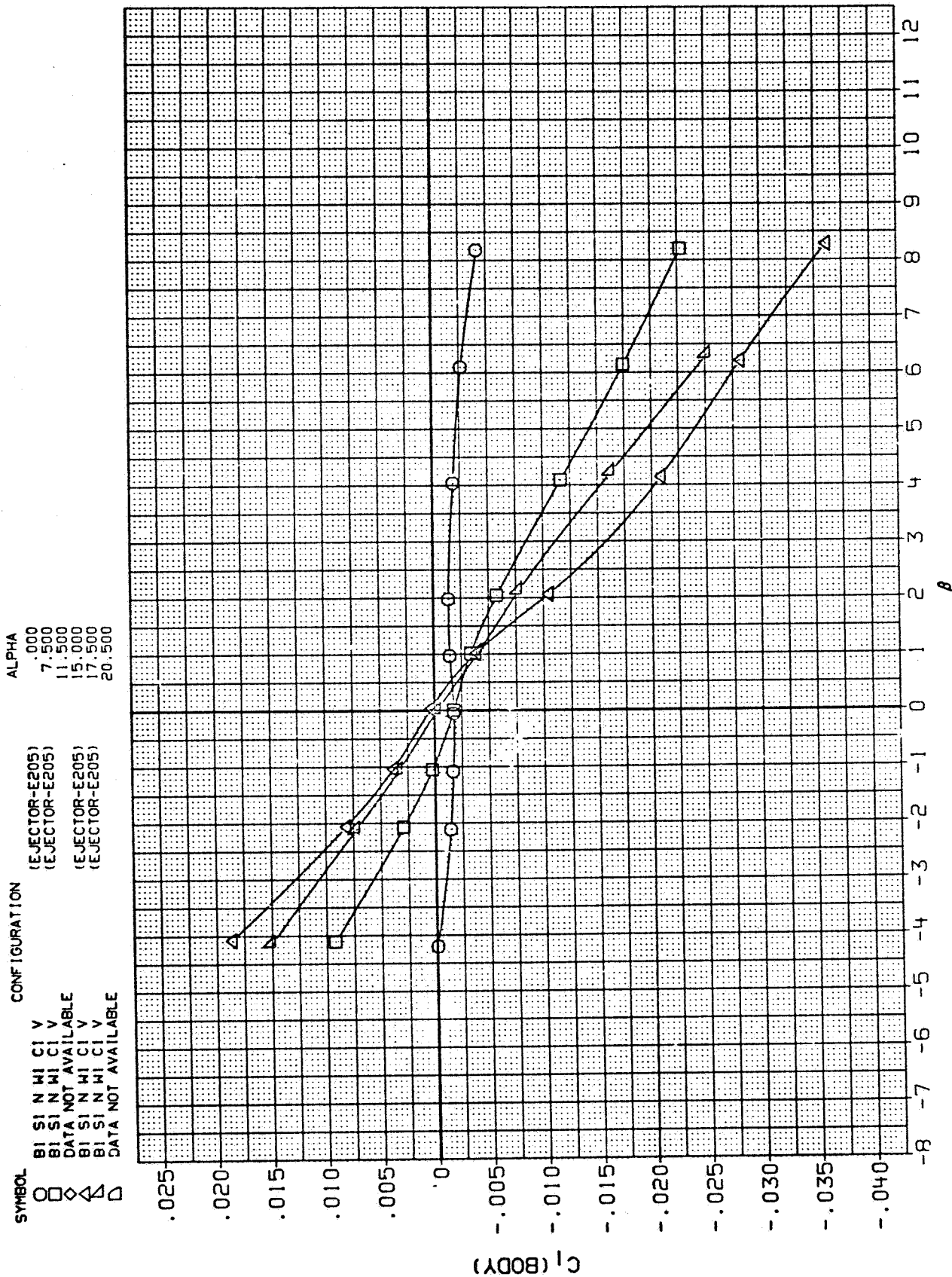


FIG. 23 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = 1.20

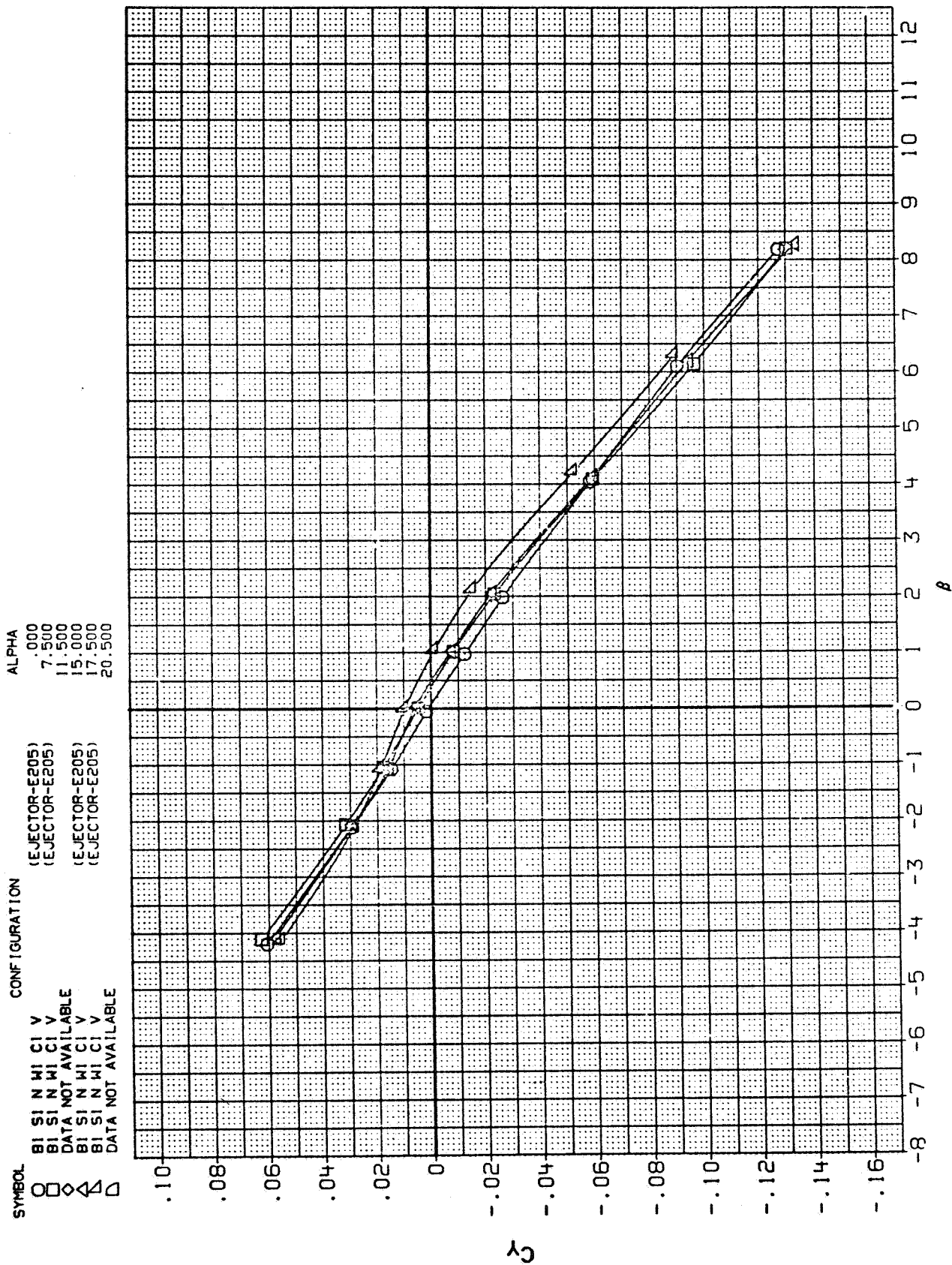


FIG. 23 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = 1.20

(EJECTOR-E205)

CONFIGURATION B1 S1 N1 W1 C1 V
MACH .601
.906
1.210
RN/L
LE-W
TE-W
CANARD
LE-C
PARAMETRIC VALUES
9.843
.000
.000
.000
TE-C
VERT
.000
.000

SYMBOL
□
◇

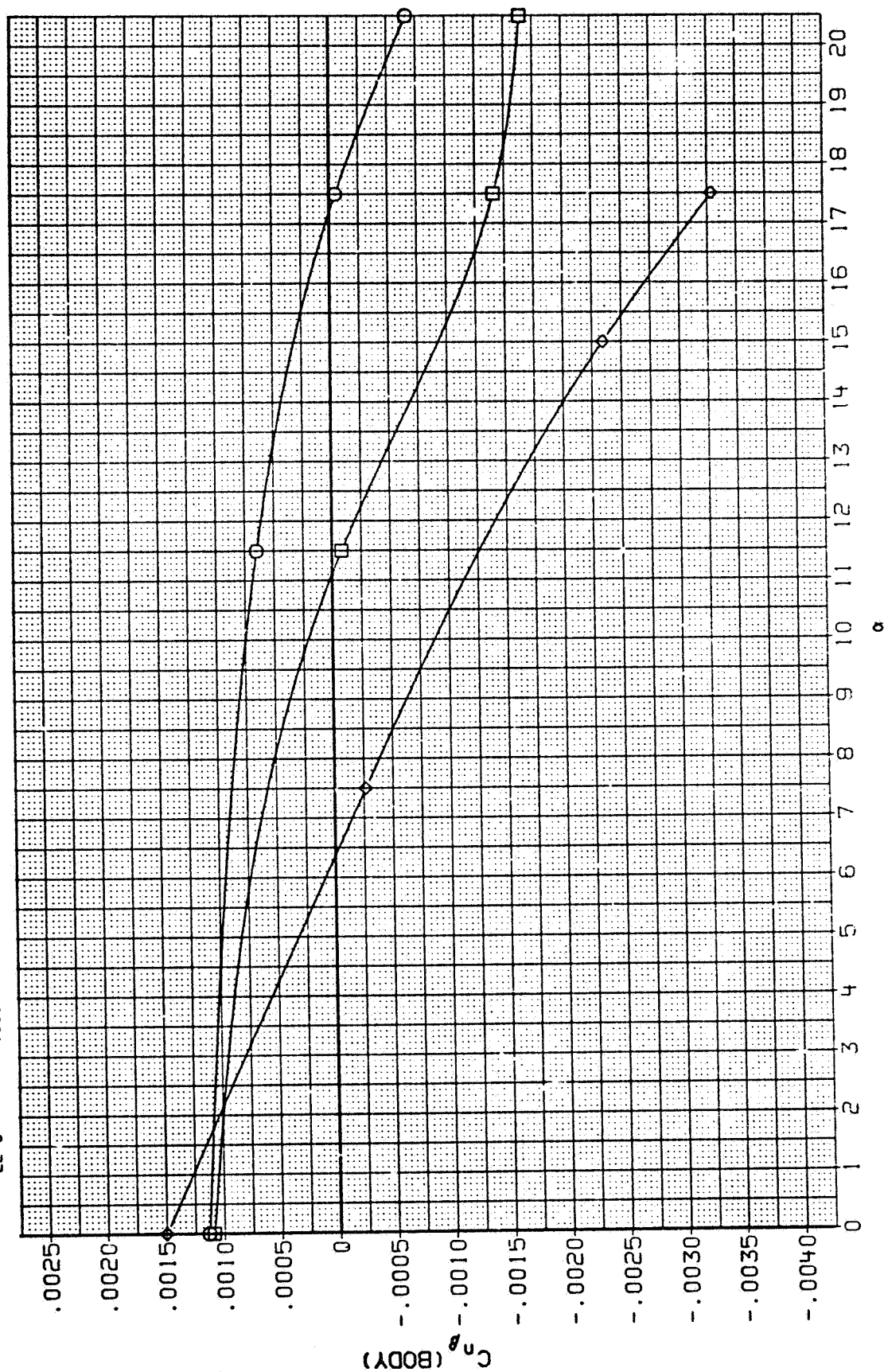


FIG. 24 SUMMARY OF BASIC LATERAL/DIRECTIONAL CHARACTERISTICS WITH ALPHA

SYMBOL CONFIGURATION B1 S1 N1 W1 C1 V1 (EJECTOR-E205)
 MACH PARAMETRIC VALUES
 .601 RN/L 9.843 TE-C
 .906 LE-W .000 VERT
 1.210 TE-W .000
 CANARD .000
 LE-C .000

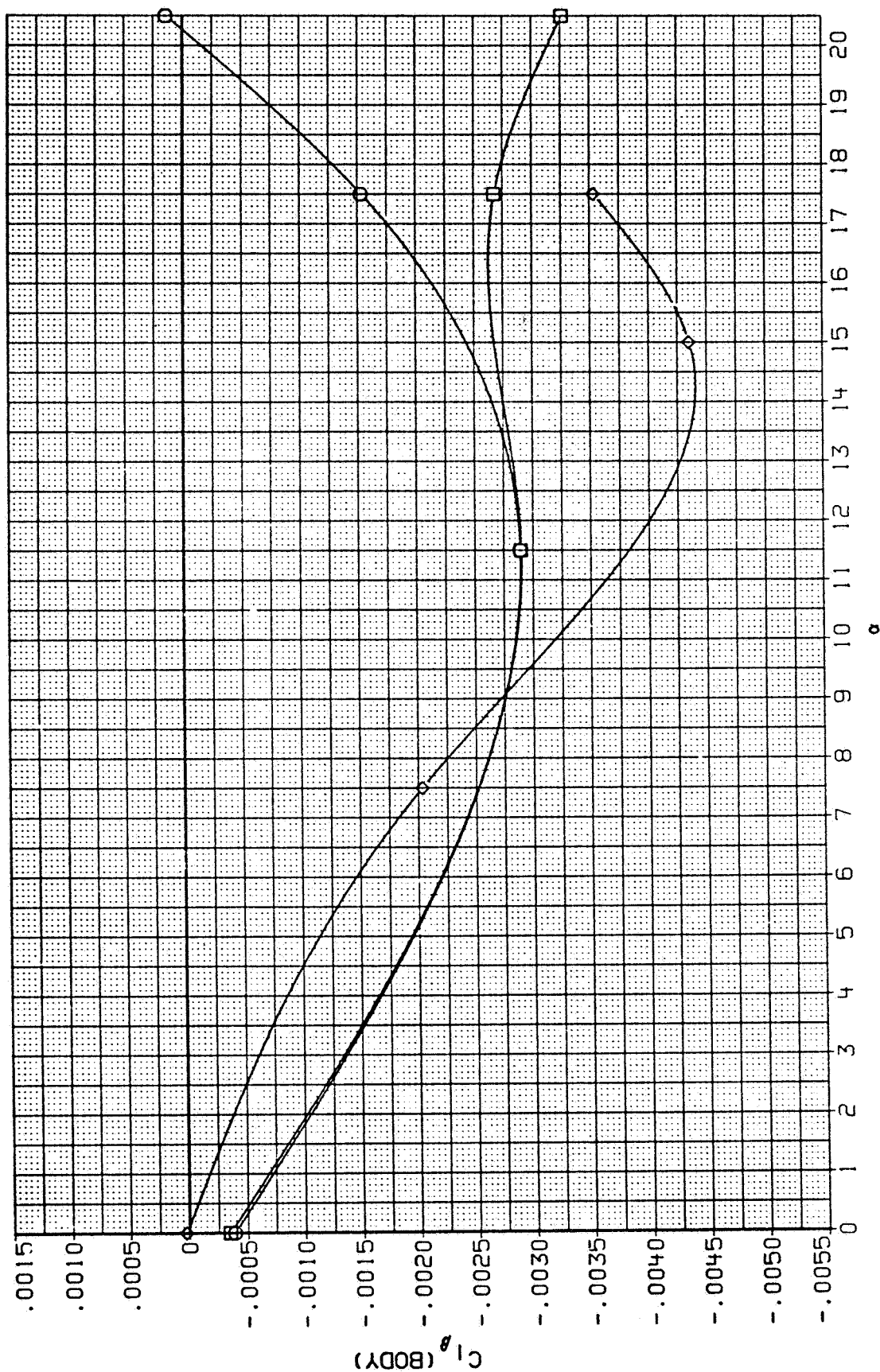


FIG. 24 SUMMARY OF BASIC LATERAL/DIRECTIONAL CHARACTERISTICS WITH ALPHA

(EJECTOR-E205)

CONFIGURATION B1 S1 N W1 C1 V
 MACH .601
 RN/L 9.843
 LE-H .000
 TE-H .000
 CANARD .000
 LE-C .000
 PARAMETRIC VALUES
 TE-C .000
 VERT .000

SYMBOL
 ○ □ ◇

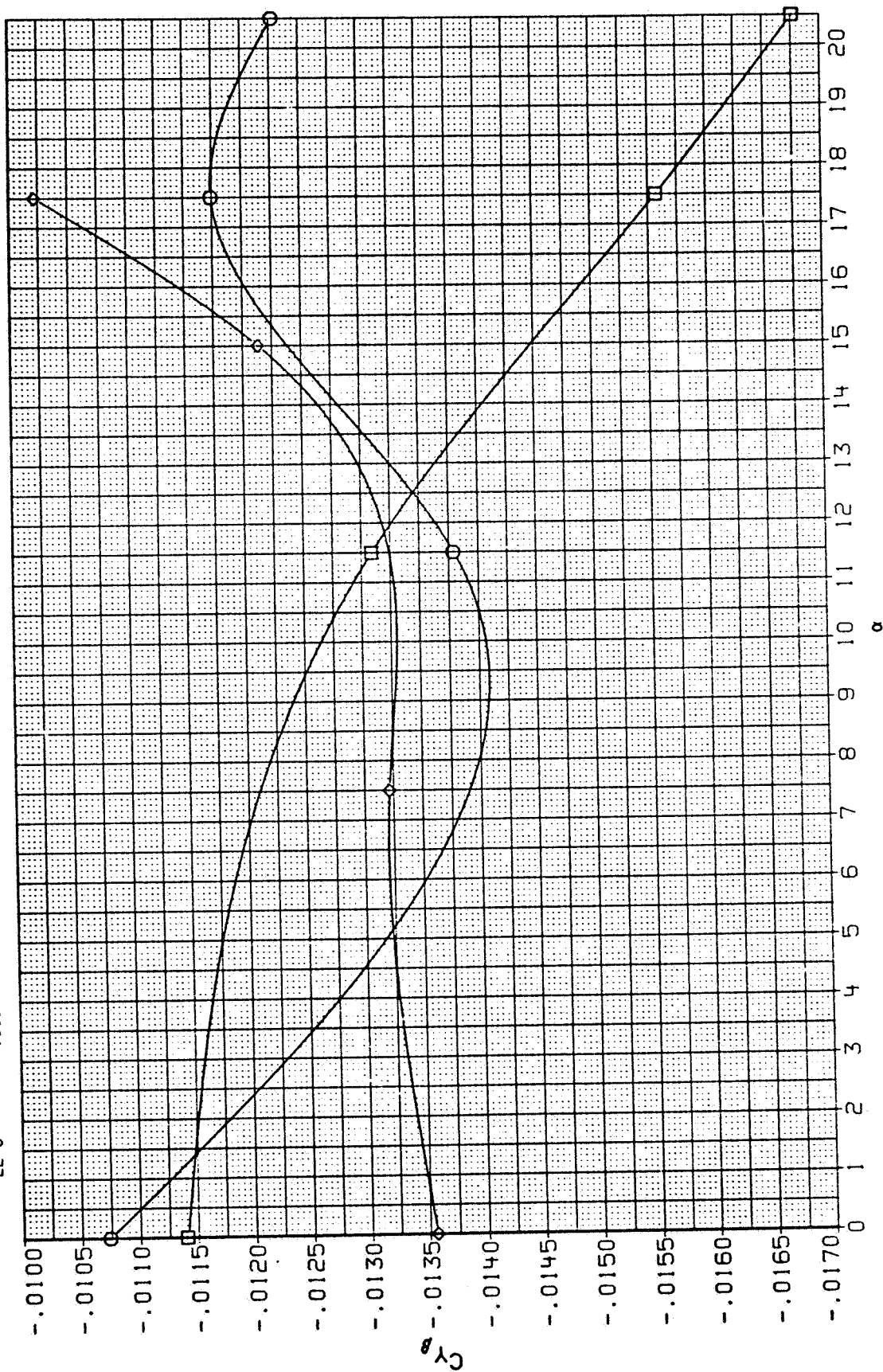


FIG. 24 SUMMARY OF BASIC LATERAL/DIRECTIONAL CHARACTERISTICS WITH ALPHA

SYMBOL CONFIGURATION ALPHA
 ○ (EJECTOR-E205) .000
 ◇ (EJECTOR-E205) .000
 △ (EJECTOR-E205) .000
 □ (EJECTOR-E205) .000
 BI SI N MI CI V
 BI SI N MI CI V
 BI SI N MI CI V
 BI SI N MI CI V

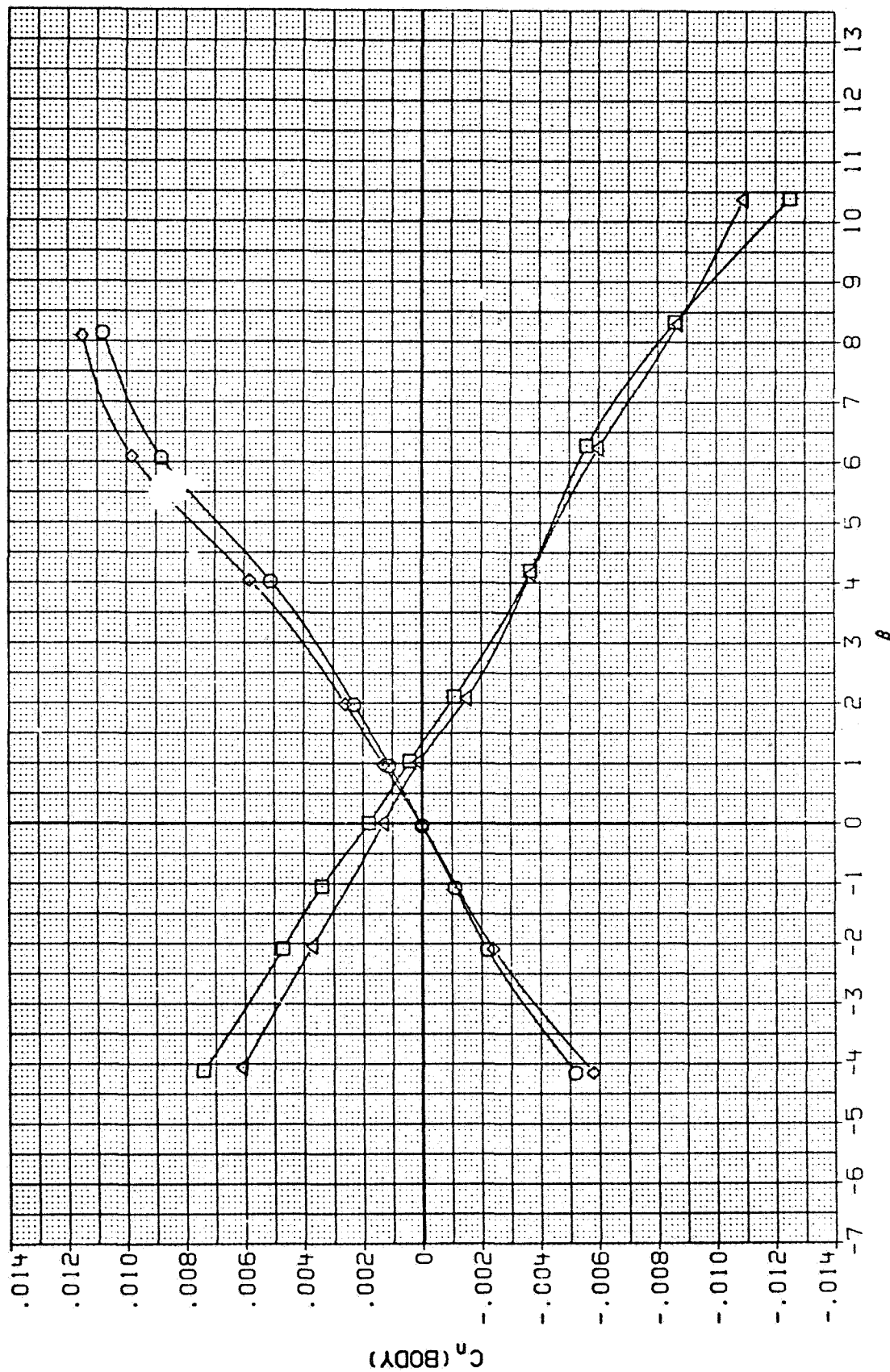


FIG. 25 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = .90

SYMBOL	BI	SI	N	MI	CI	V	CONFIGURATION	ALPHA
○	BI	SI	N	MI	CI	V	(EJECTOR-E205)	.000
□	BI	SI	N	MI	CI	V	(EJECTOR-E205)	17.500
◇	BI	SI	N	MI	CI	V	(EJECTOR-E205)	.000
△	BI	SI	N	MI	CI	V	(EJECTOR-E205)	16.500

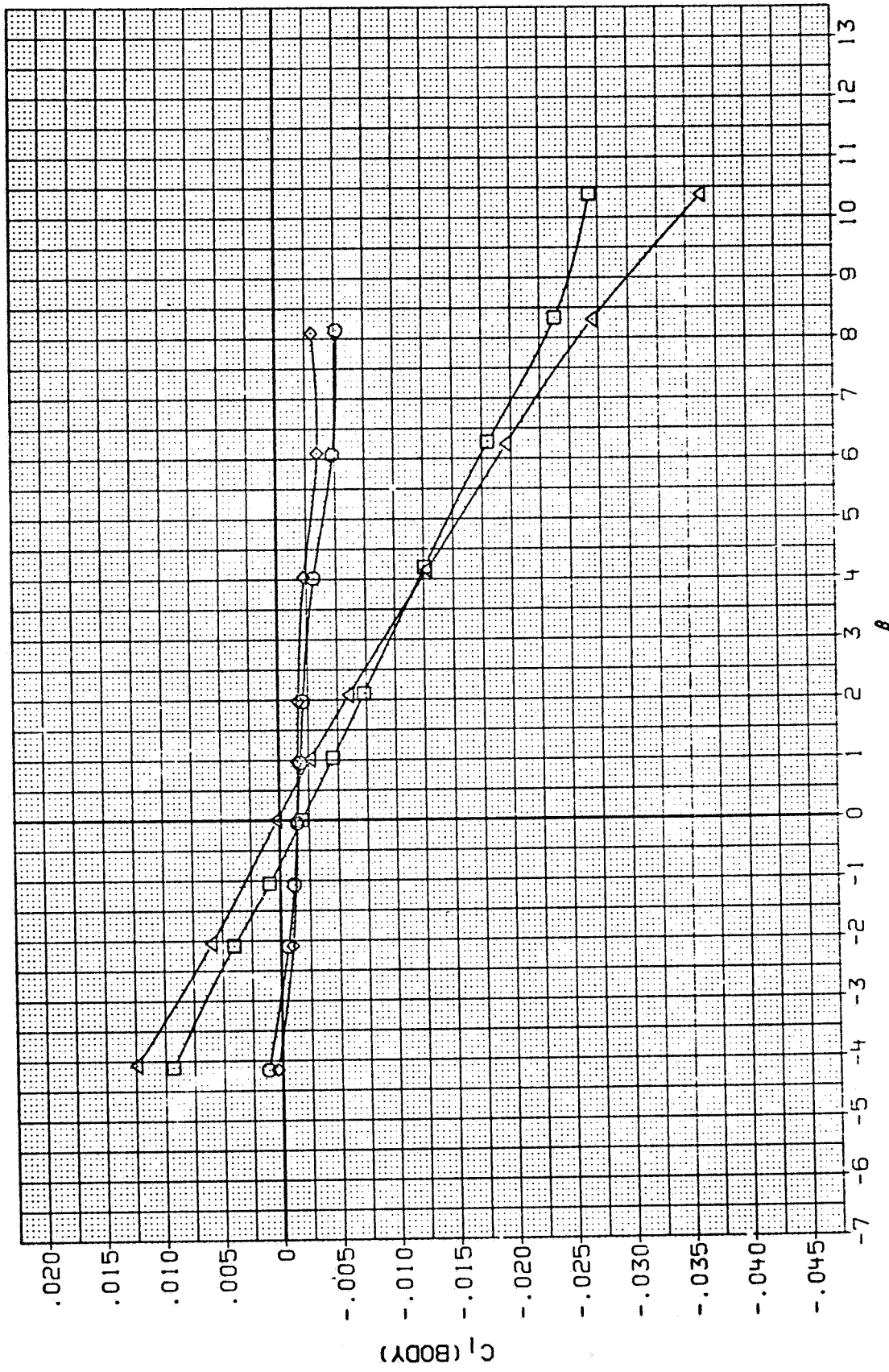


FIG. 25 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = .90

SYMBOL	CONFIGURATION	ALPHA
○	(EJECTOR-E205)	.000
□	(EJECTOR-E205)	17.500
△	(EJECTOR-E205)	.000
◇	(EJECTOR-E205)	16.500

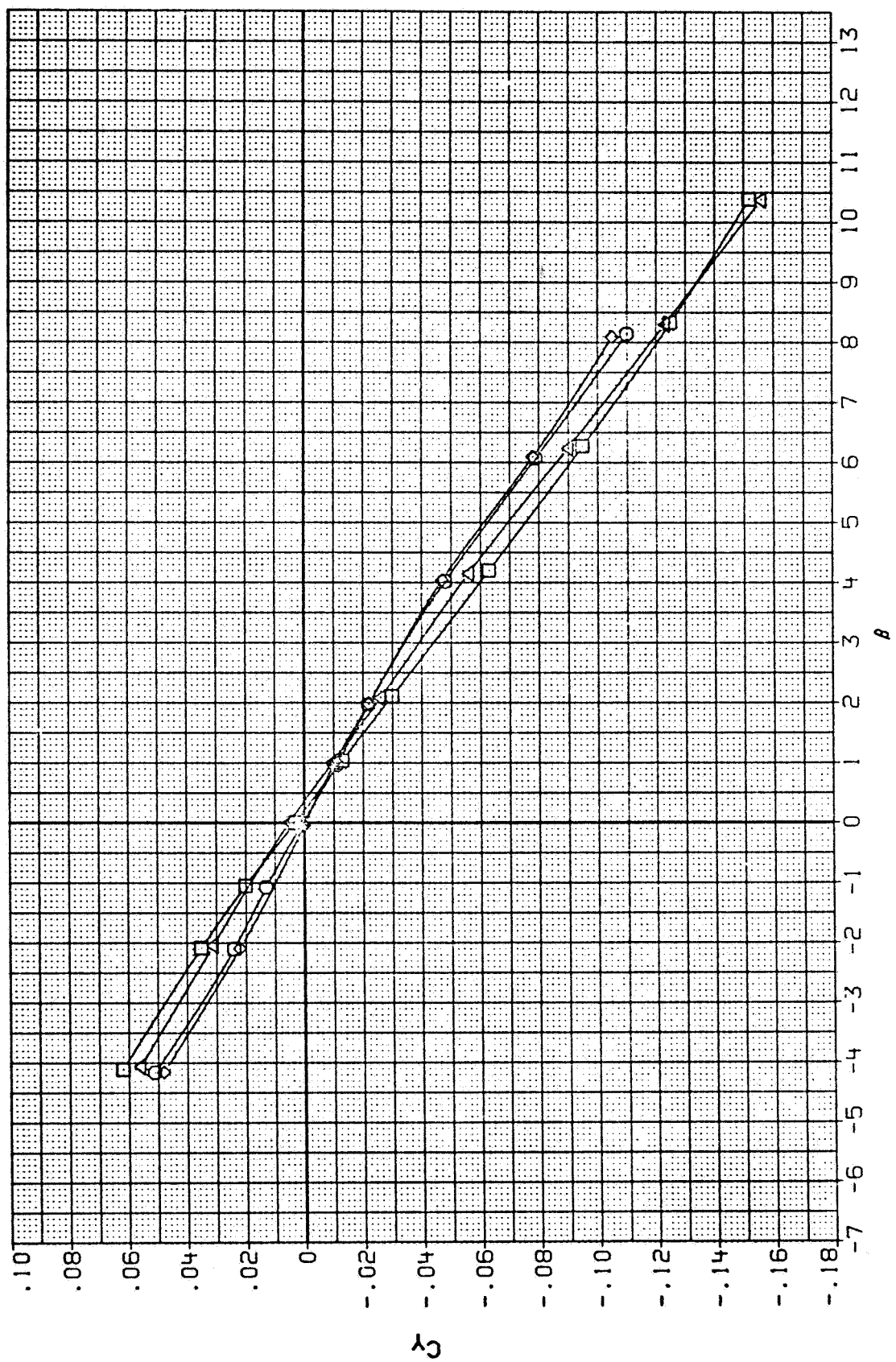


FIG. 25 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = .90

SYMBOL	CONFIGURATION	ALPHA
○	BI SI N HI CI V	.000
□	(EJECTOR-E205)	15.000
△	BI SI N HI CI V	.000
◇	(EJECTOR-E205)	11.000

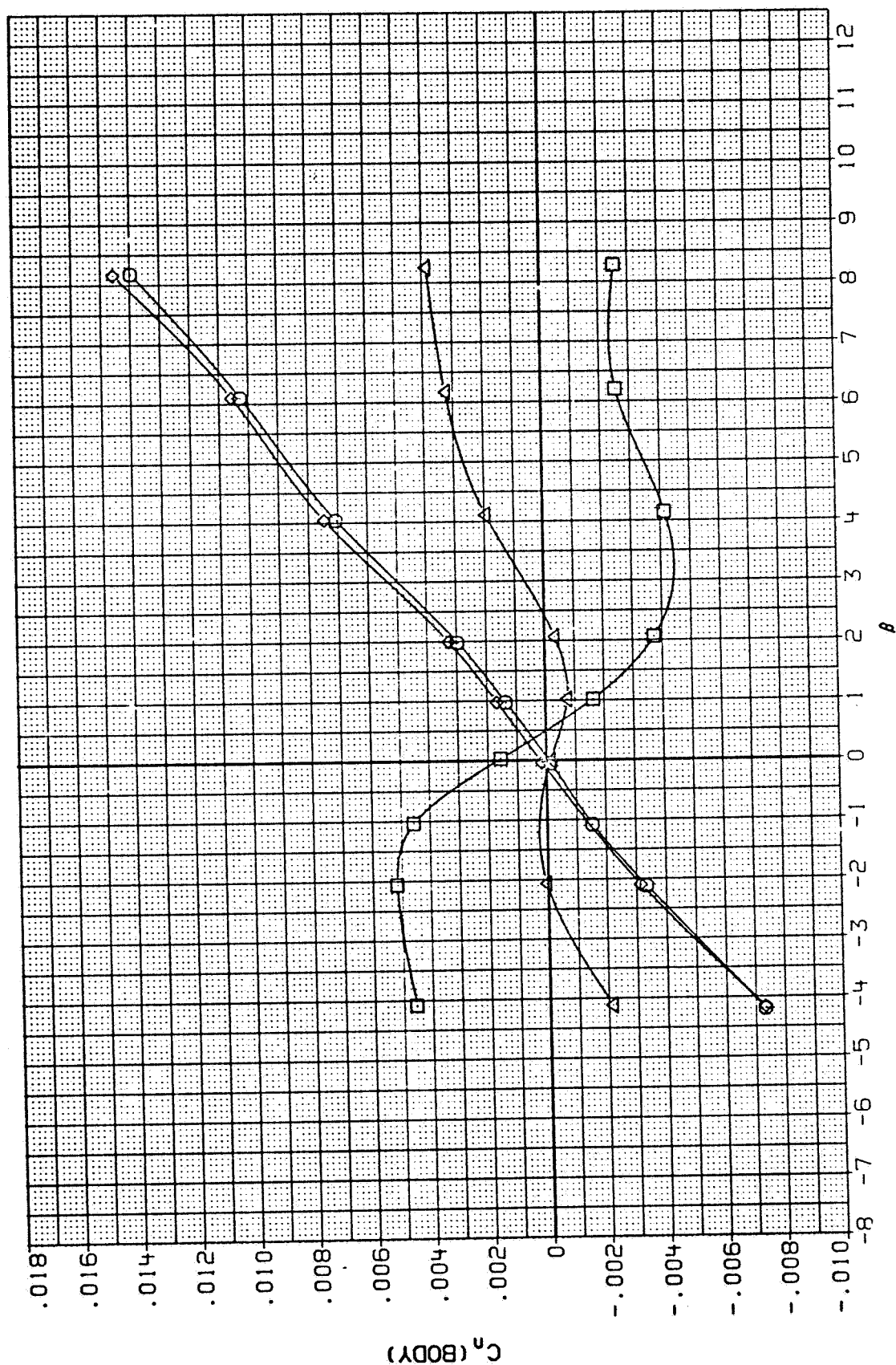


FIG. 26 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
○	(EJECTOR-E205)	.000
□	(EJECTOR-E205)	15.000
△	(EJECTOR-E205)	.000
◇	(EJECTOR-E205)	11.000

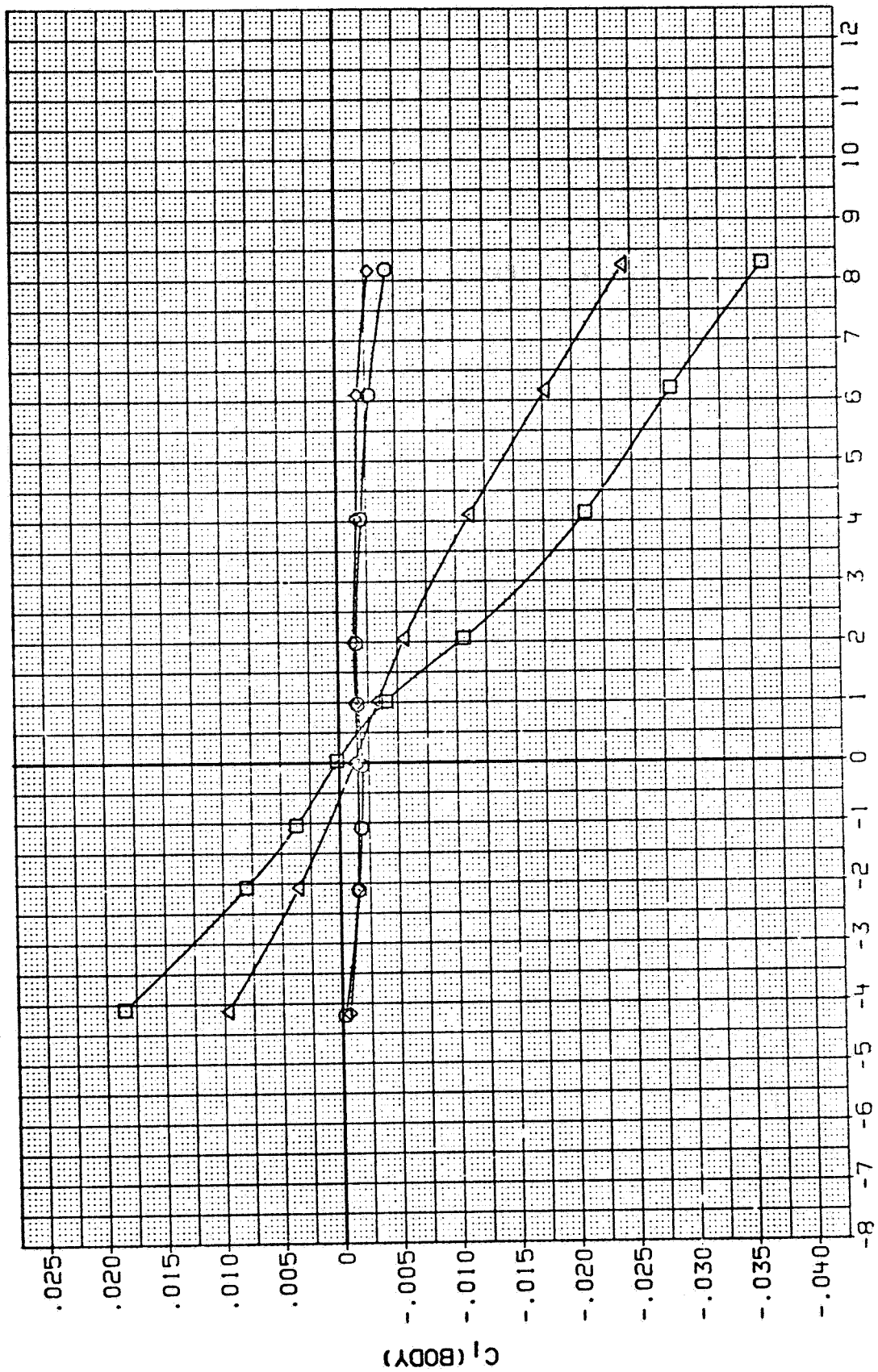


FIG. 26 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
□	(EJECTOR-E205)	.000
○	(EJECTOR-E205)	.15.000
△	(EJECTOR-E205)	.000
◇	(EJECTOR-E205)	.11.000

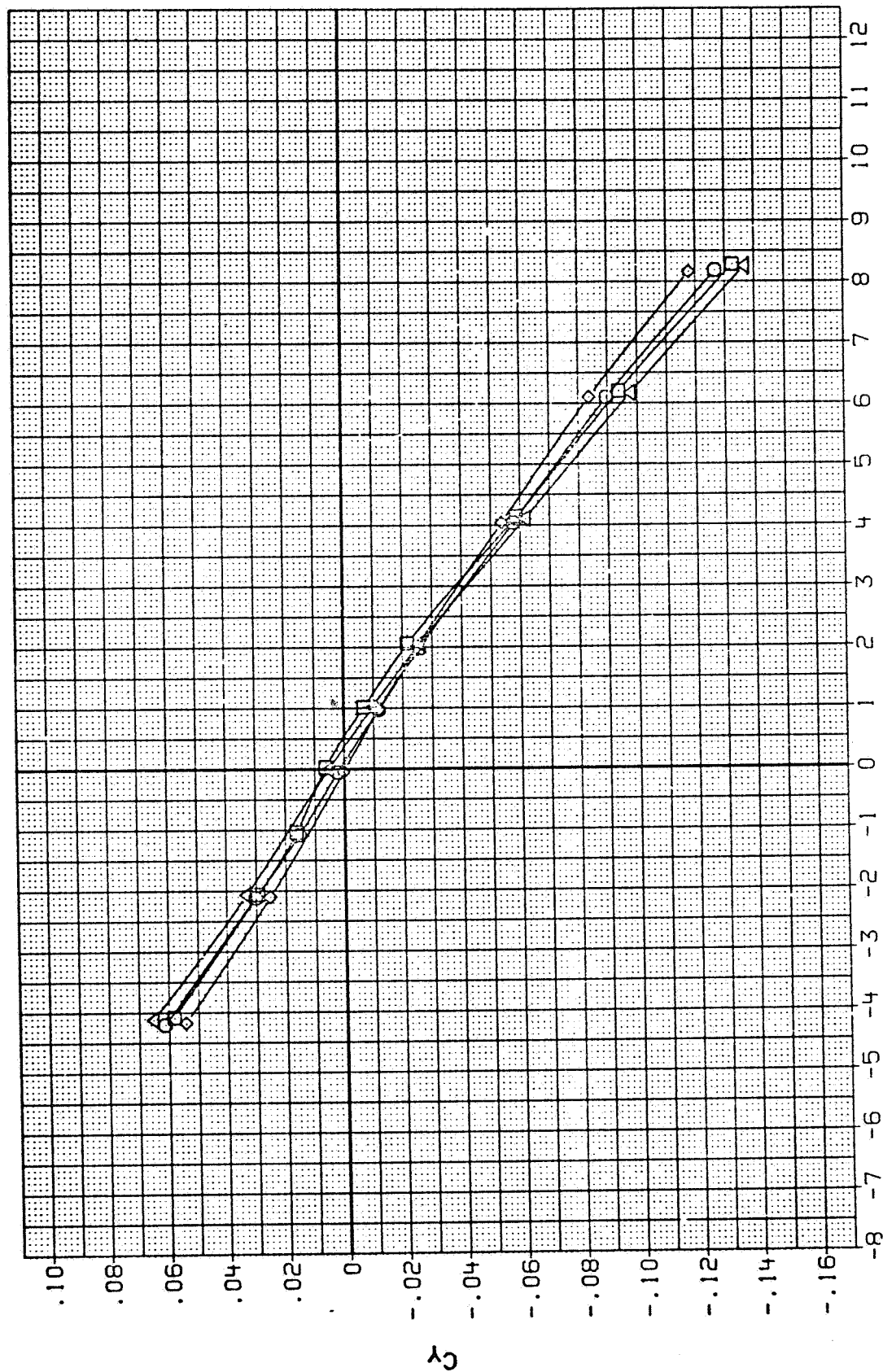


FIG. 26 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = 1.20

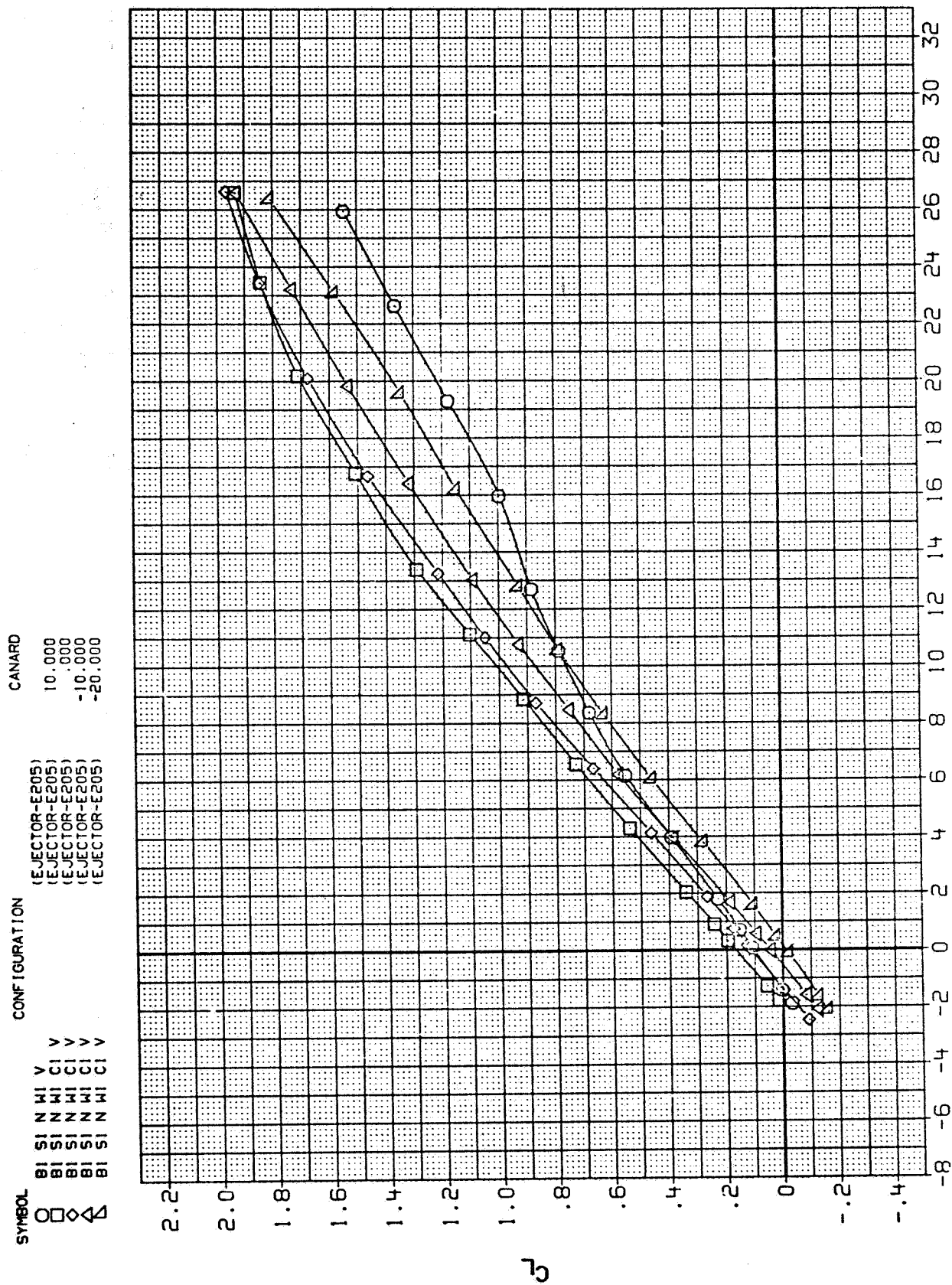


FIG. 27 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .60

SYMBOL	CONFIGURATION	CANARD
□	BI SI N MI V	10.000
○	BI SI N MI CI V	.000
△	BI SI N MI CI V	-10.000
◇	BI SI N MI CI V	-20.000

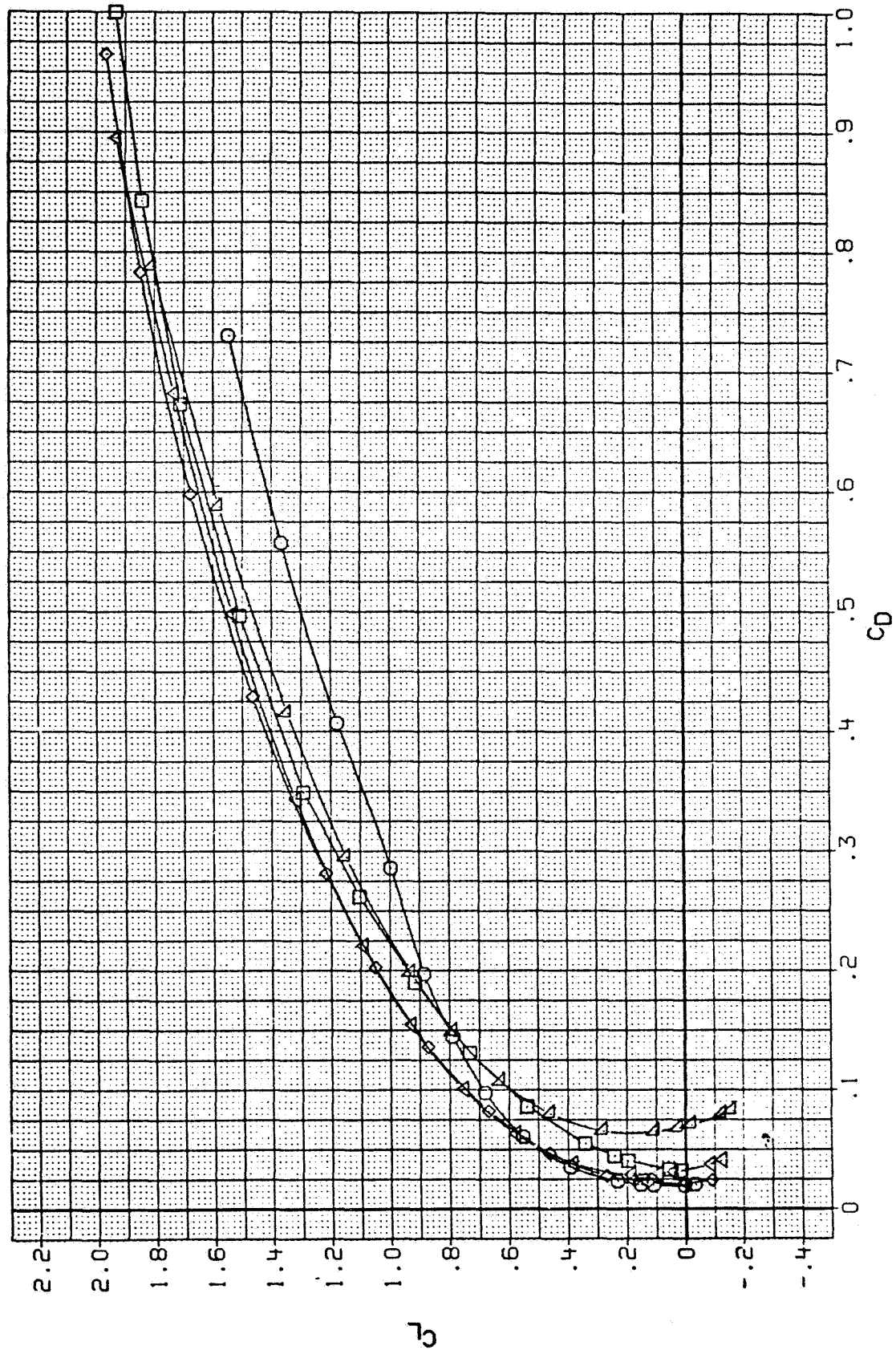


FIG. 27 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .60

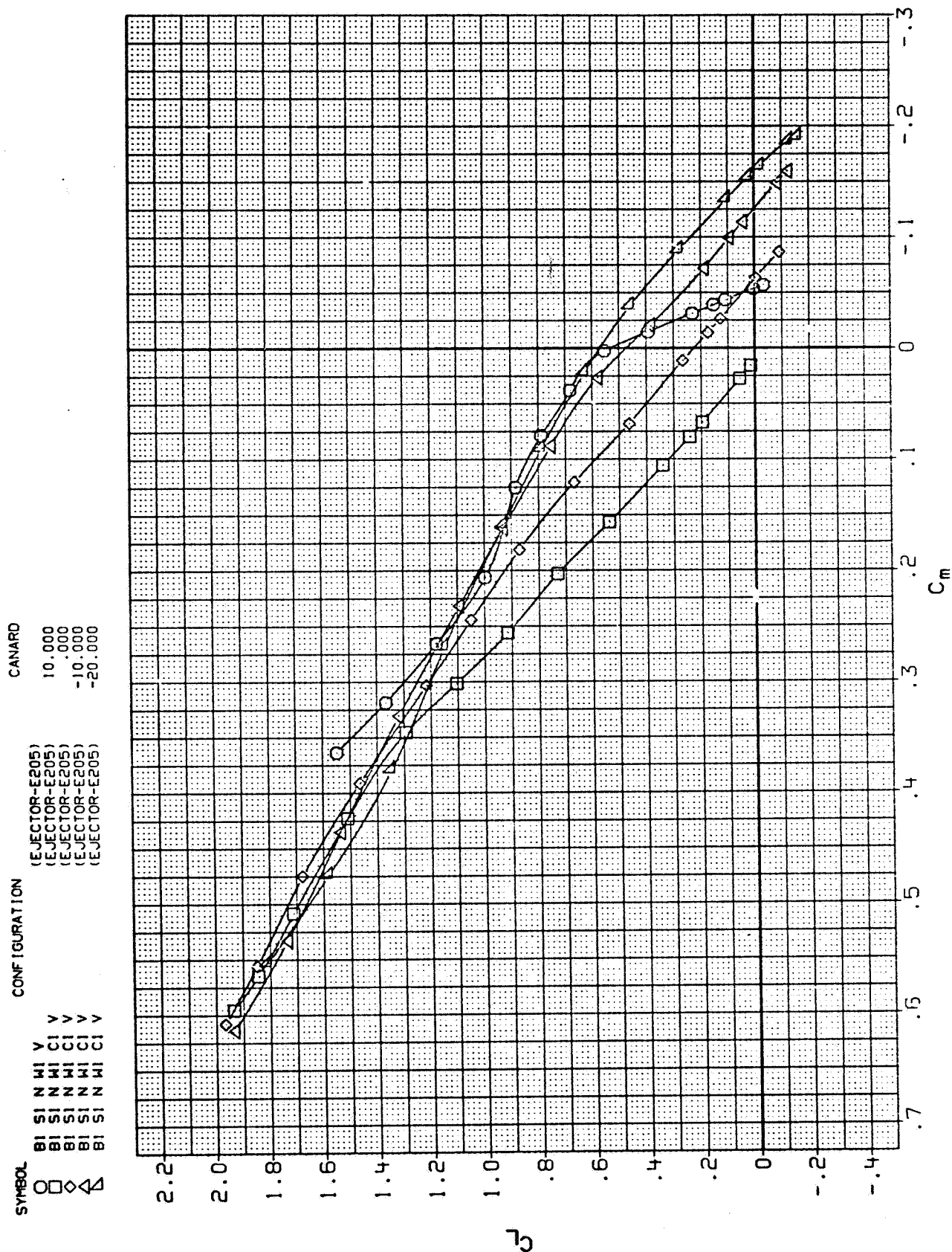


FIG. 27 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .60

SYMBOL	CONFIGURATION	CANARD
BI SI N HI V	(EJECTOR-E205)	10.000
BI SI N HI CI V	(EJECTOR-E205)	.000
BI SI N HI CI V	(EJECTOR-E205)	-10.000
BI SI N HI CI V	(EJECTOR-E205)	-20.000

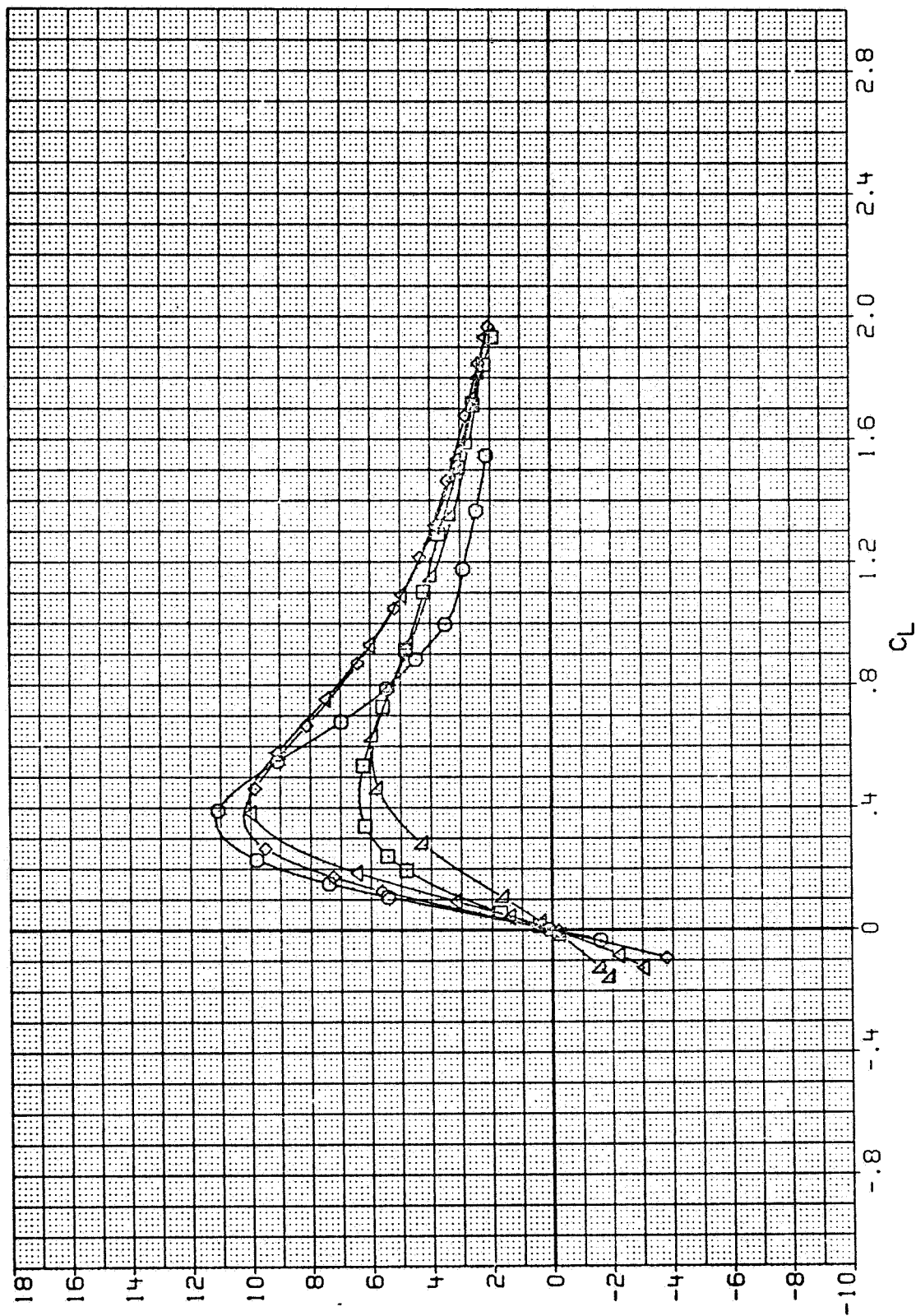


FIG. 27 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .60

SYMBOL		CONFIGURATION		CANARD	
○	BI SI N MI V	(EJECTOR-E205)	10.000		
◇	BI SI N MI CI V	(EJECTOR-E205)	.000		
△	BI SI N MI CI V	(EJECTOR-E205)	-10.000		
	BI SI N MI CI V	(EJECTOR-E205)	-20.000		

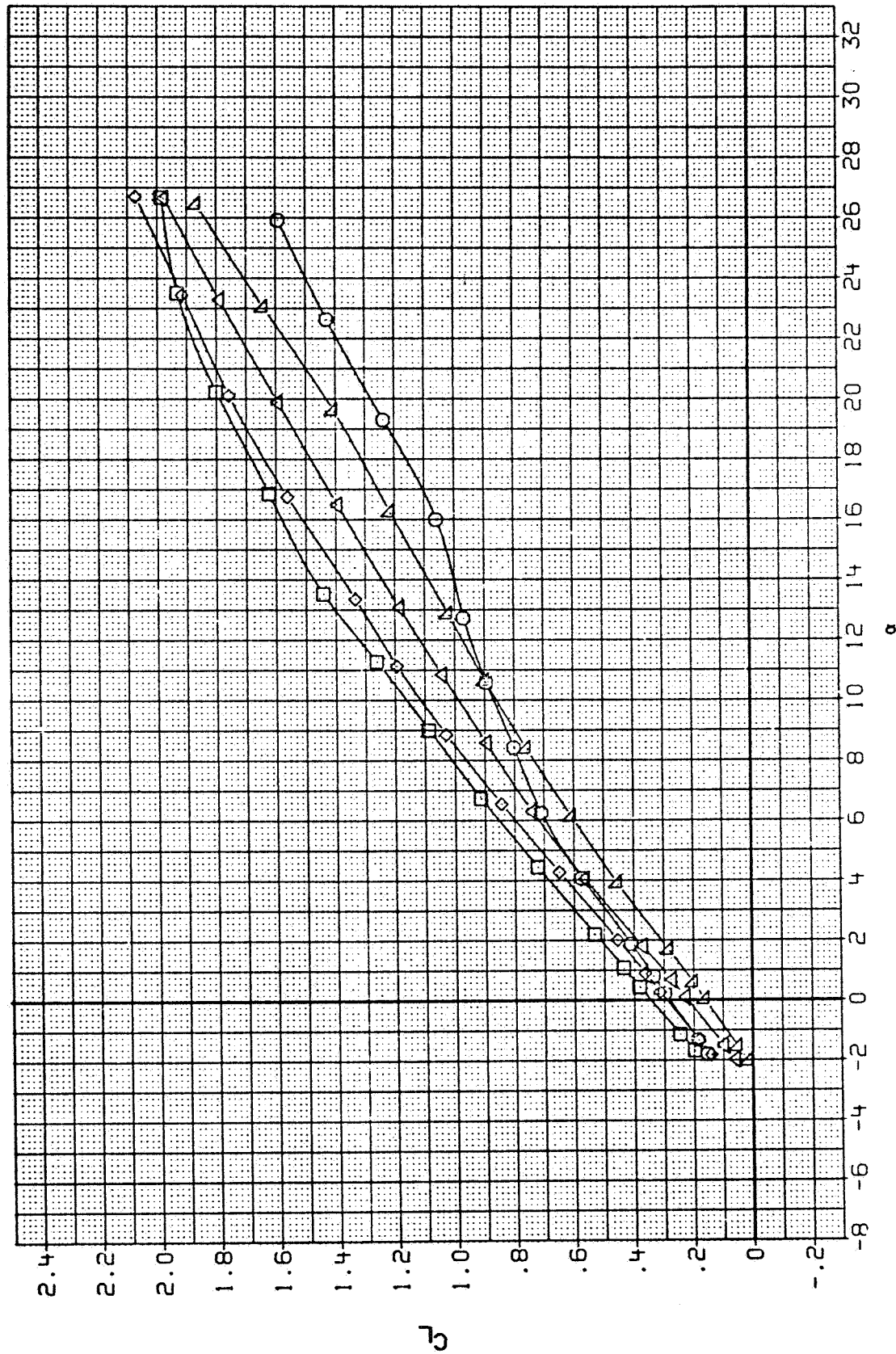


FIG. 28 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .60

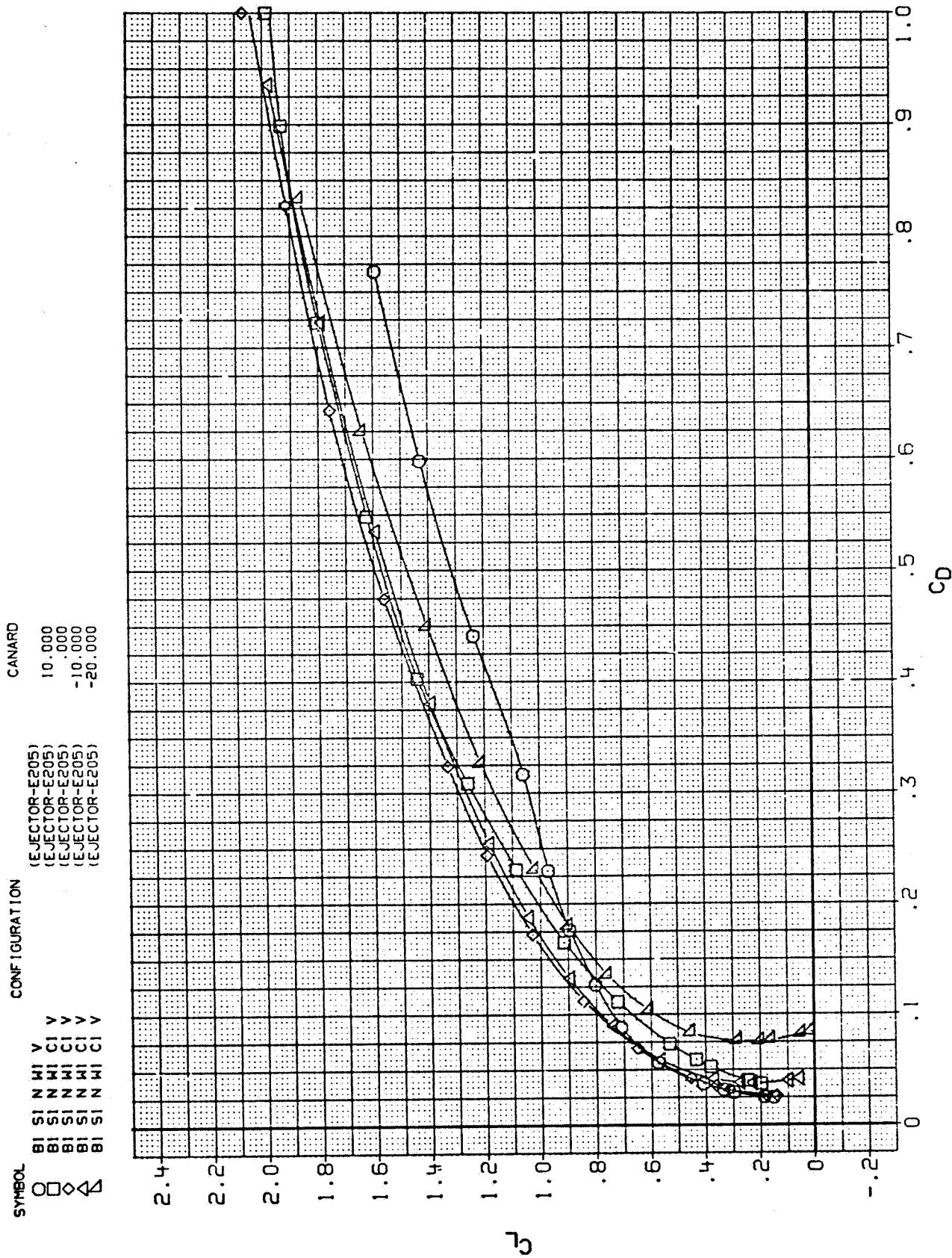


FIG. 28 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .60

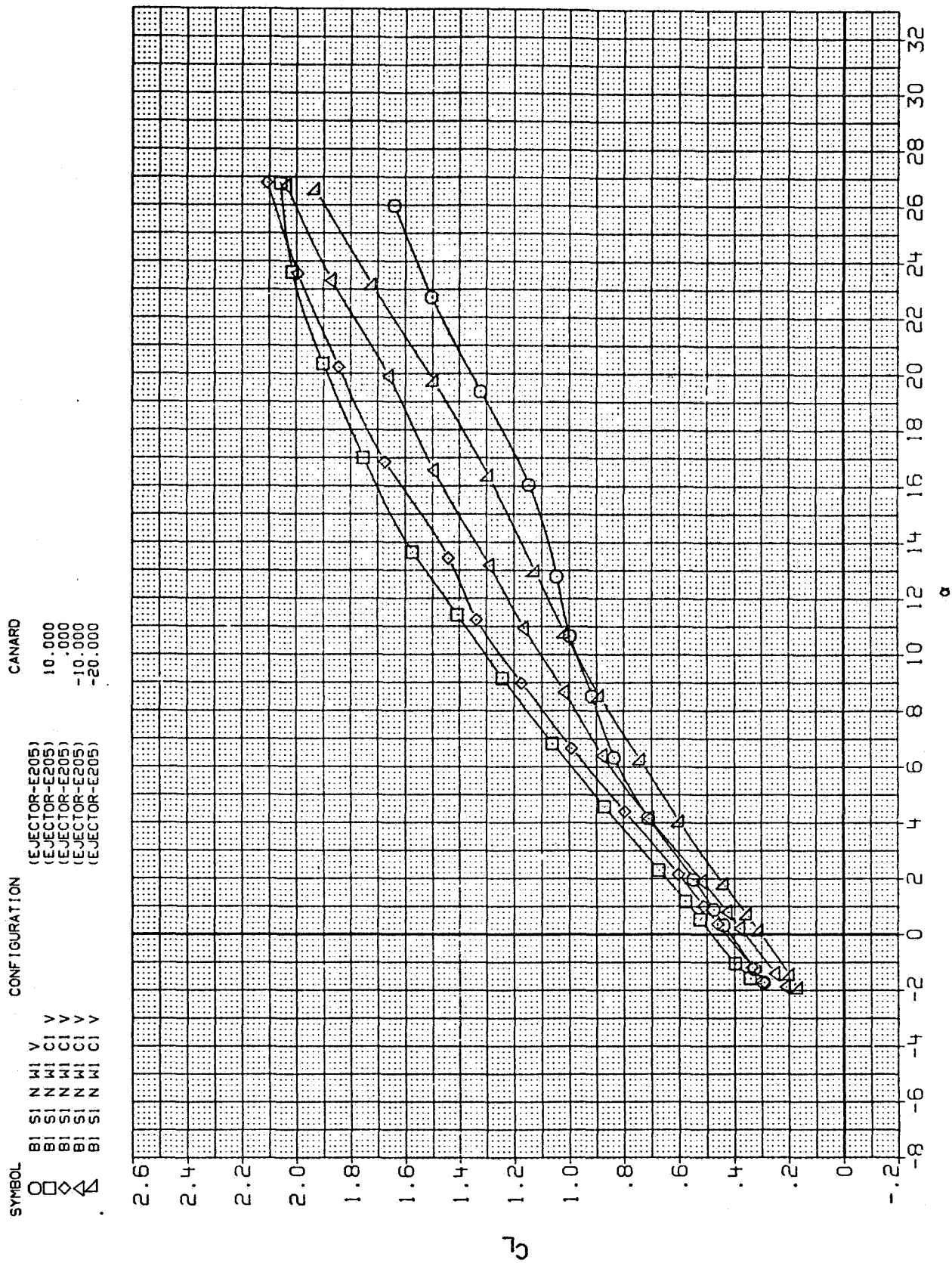


FIG. 29 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .60

SYMBOL		CONFIGURATION		CANARD	
○	BI SI N WI V	(EJECTOR-E205)	10.000		
□	BI SI N WI CI V	(EJECTOR-E205)	.000		
◇	BI SI N WI CI V	(EJECTOR-E205)	-10.000		
△	BI SI N WI CI V	(EJECTOR-E205)	-20.000		

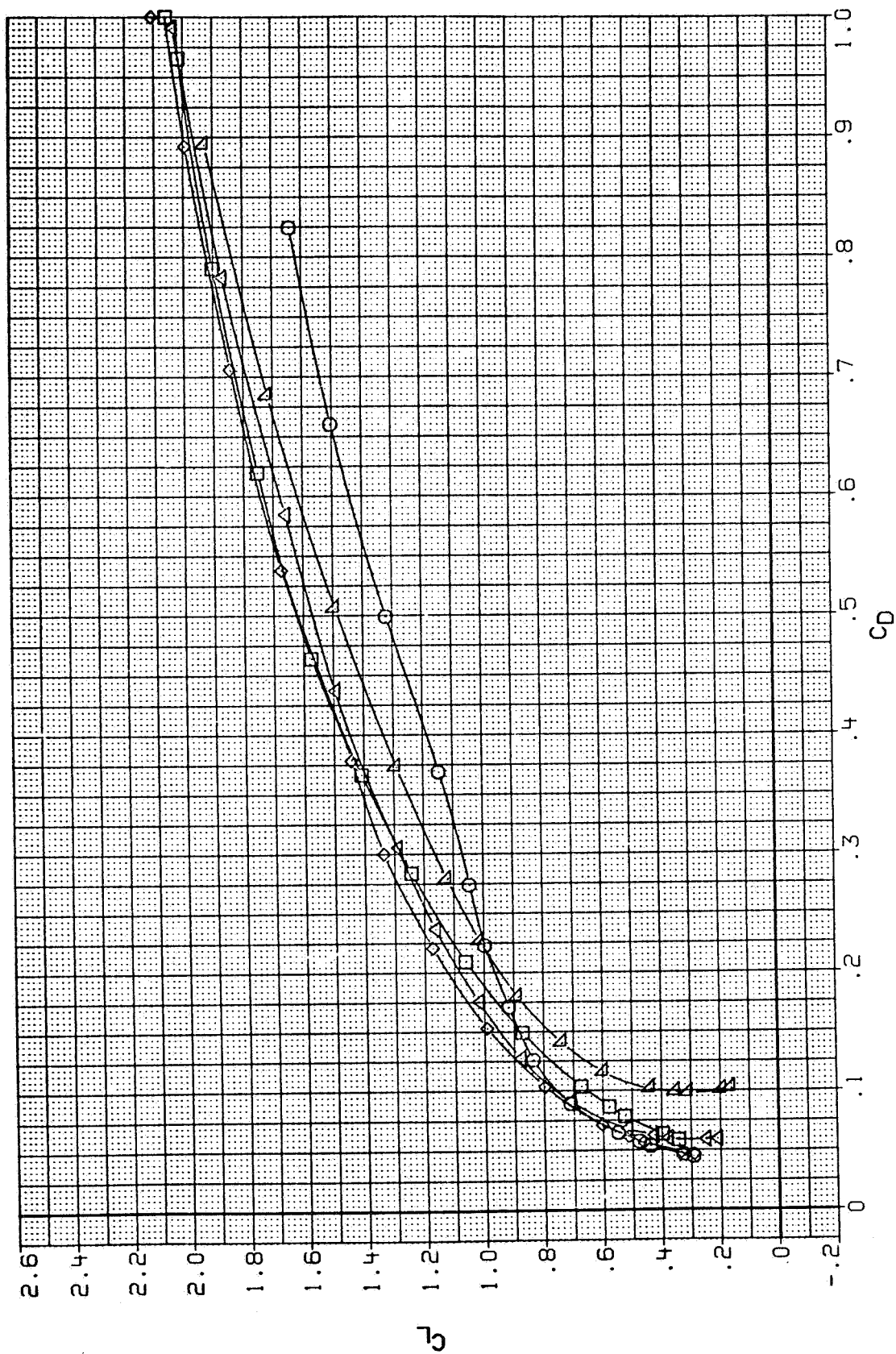


FIG. 29 CANARD INCIDENCE EFFECTS, $TE-W = 25$ DEGREES

MACH = .60

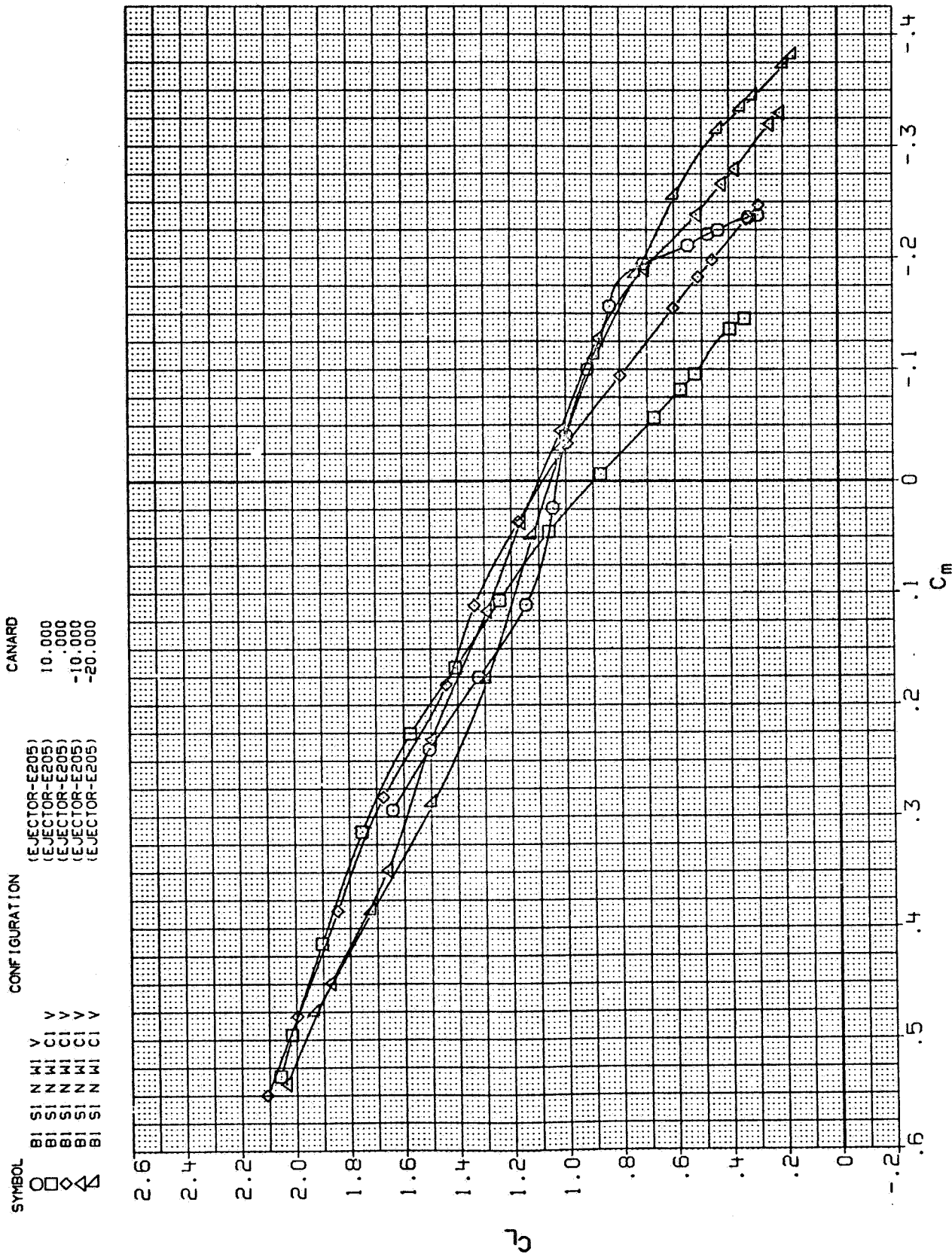


FIG. 29 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .60

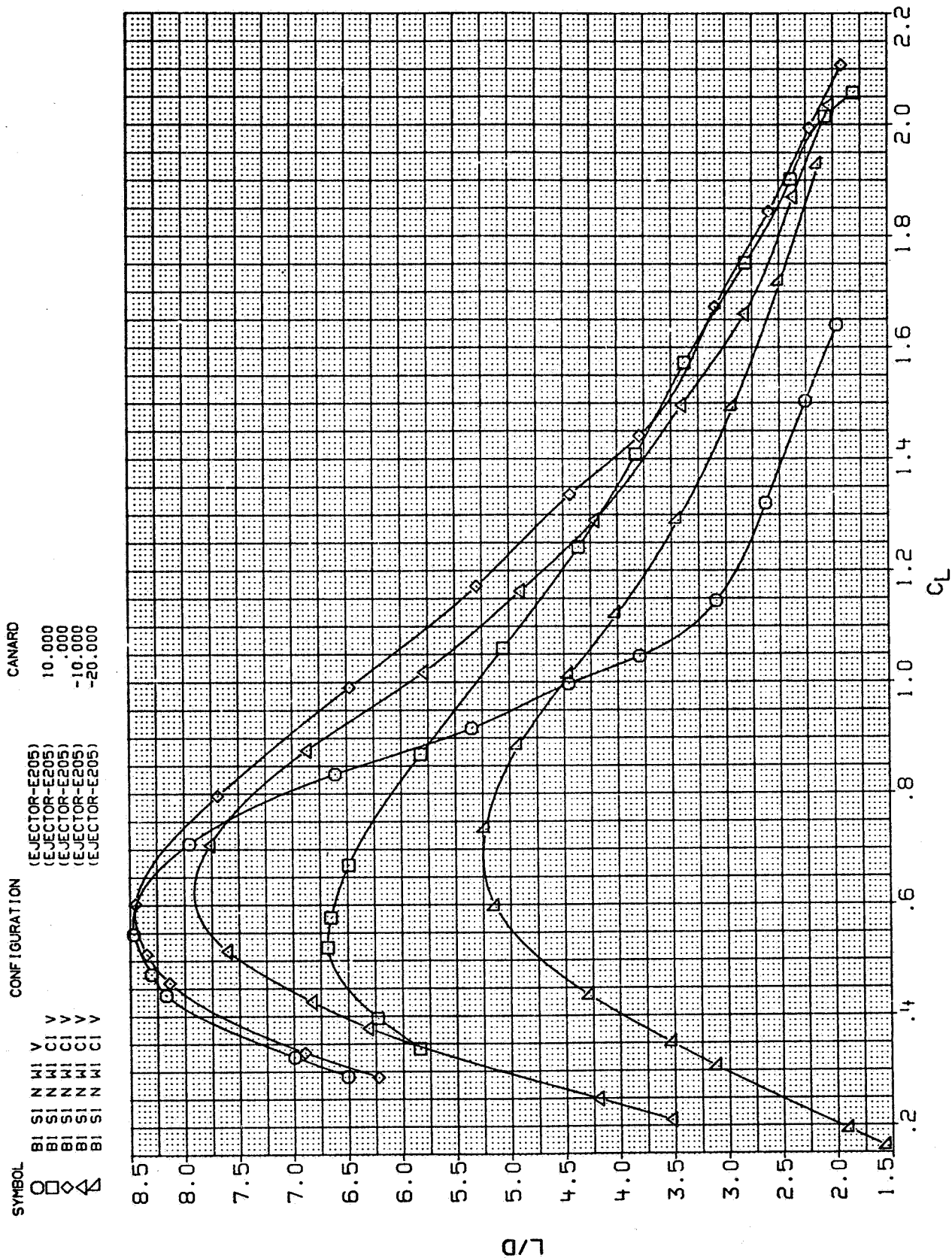


FIG. 29 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .60

SYMBOL	CONFIGURATION	CANARD
○	(EJECTOR-E205)	10.000
□	(EJECTOR-E205)	.000
△	(EJECTOR-E205)	-10.000
▽	(EJECTOR-E205)	-20.000

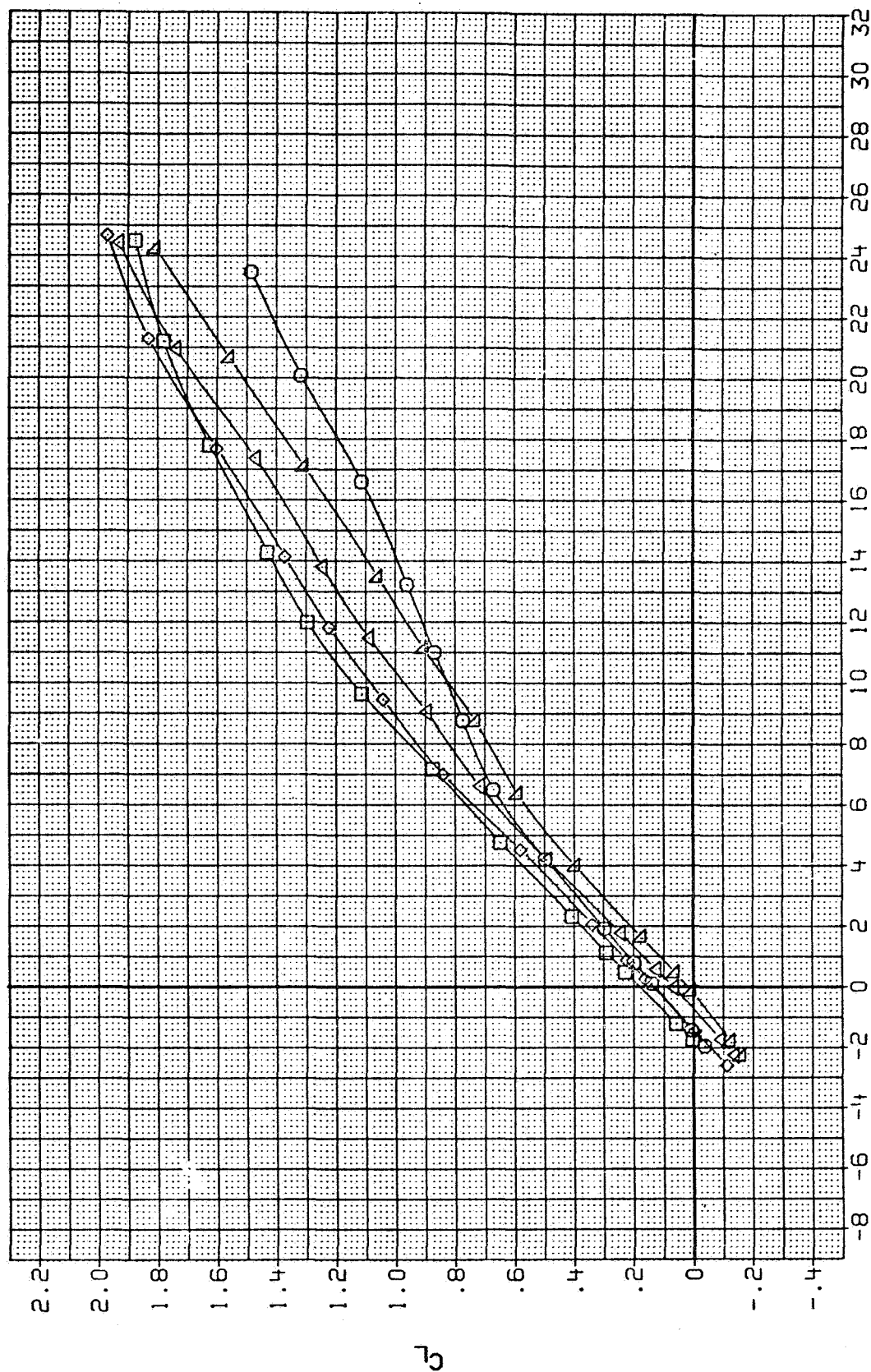


FIG. 30 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .90

SYMBOL		CONFIGURATION		CANARD	
○	BI SI N MI V	(EJECTOR-E205)	10.000		
◇	BI SI N MI CI V	(EJECTOR-E205)	.000		
△	BI SI N MI CI V	(EJECTOR-E205)	-10.000		
▽	BI SI N MI CI V	(EJECTOR-E205)	-20.000		

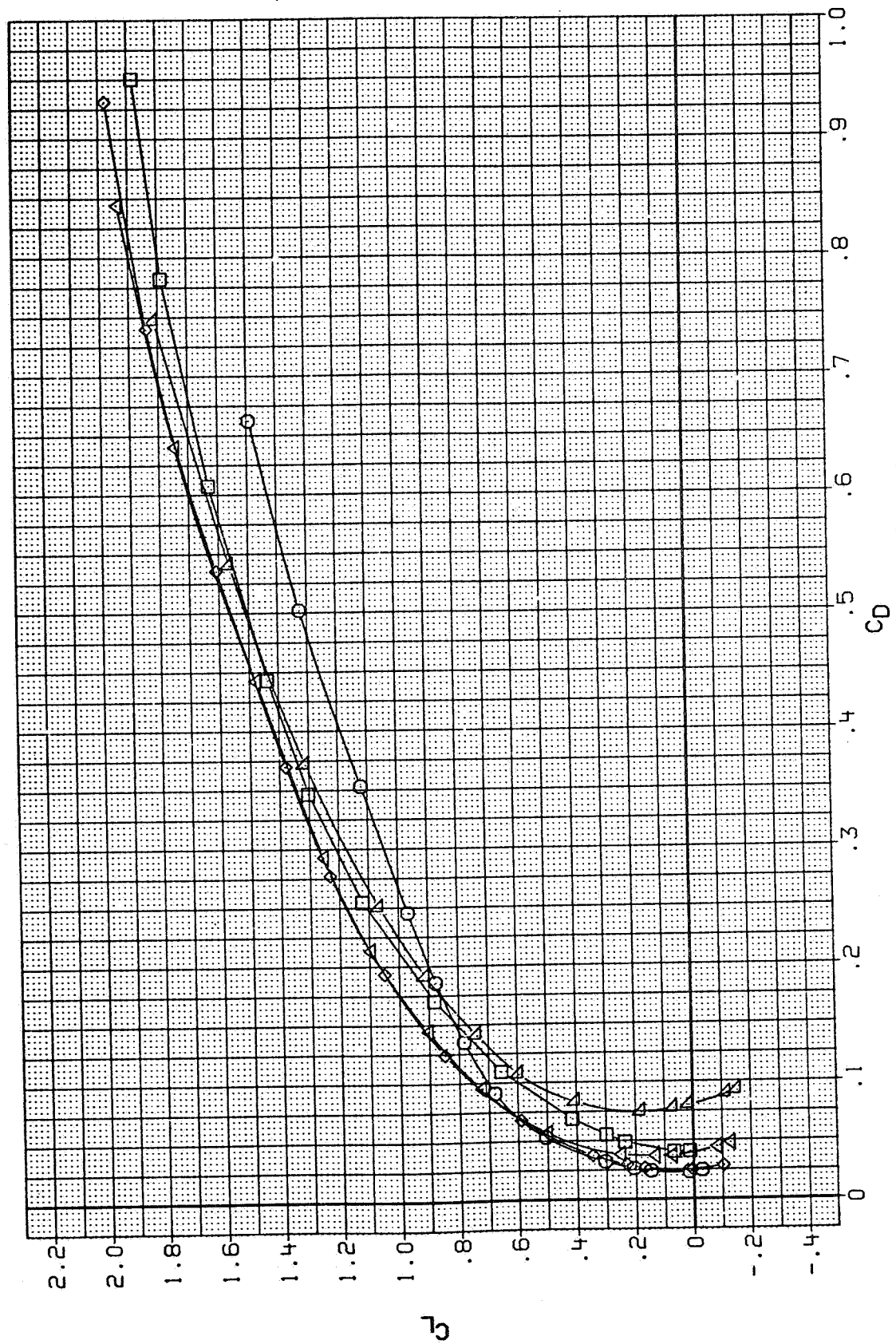
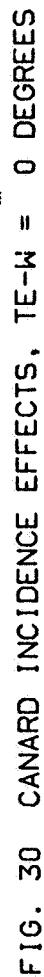


FIG. 30 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .90



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SYMBOL	CONF IGURATION	CANARD
□	BI SI N MI V	10.000
◇	BI SI N MI CI V	.000
△	BI SI N MI CI V	-10.000
▽	BI SI N MI CI V	-20.000

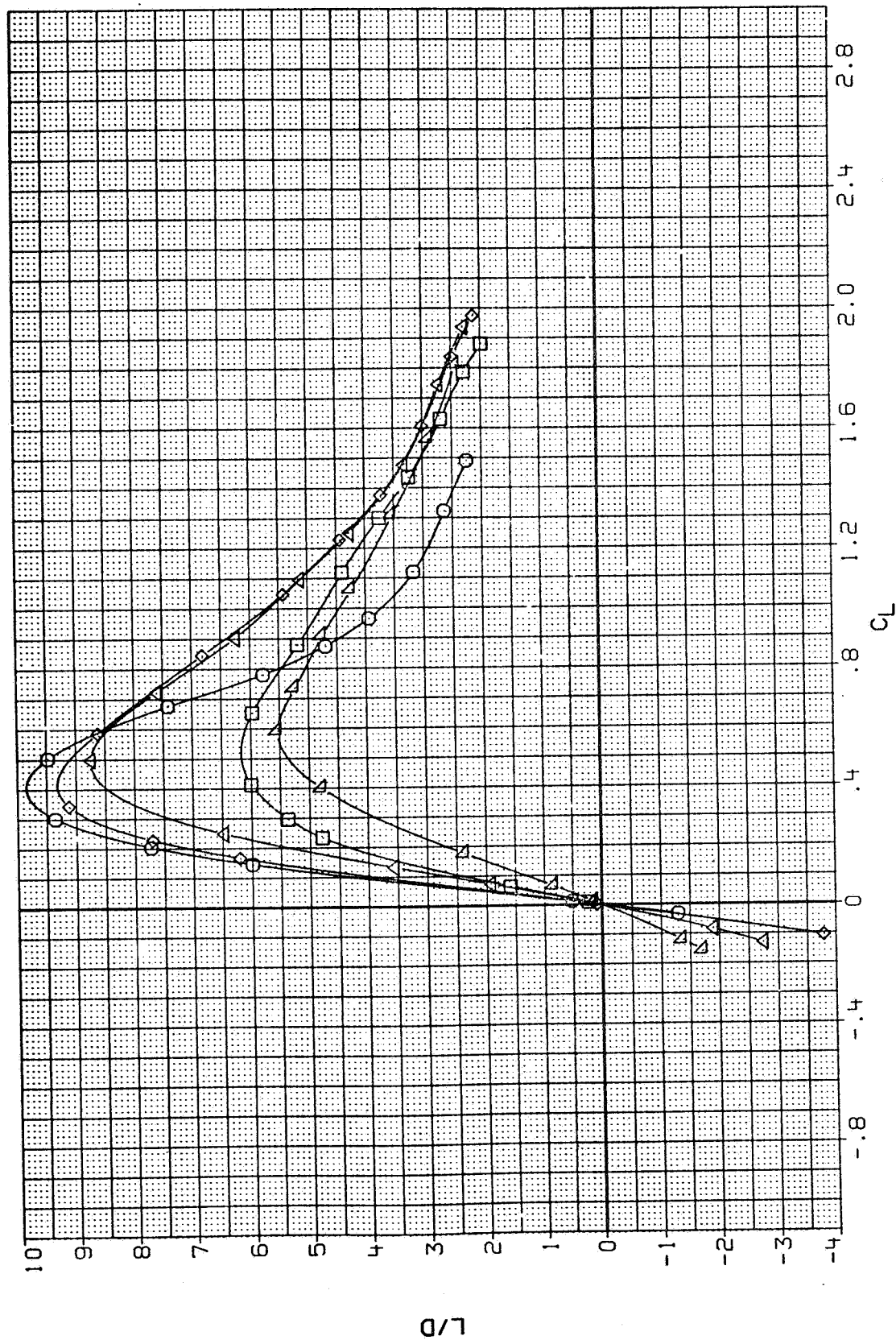


FIG. 30 CANARD INCIDENCE EFFECTS, $TE-W = 0$ DEGREES

$MACH = .90$

SYMBOL	CONFIGURATION	CANARD
□	BI SI N WI V	10.000
◇	BI SI N WI CI V	.000
△	BI SI N WI CI V	-10.000
	BI SI N WI CI V	-20.000

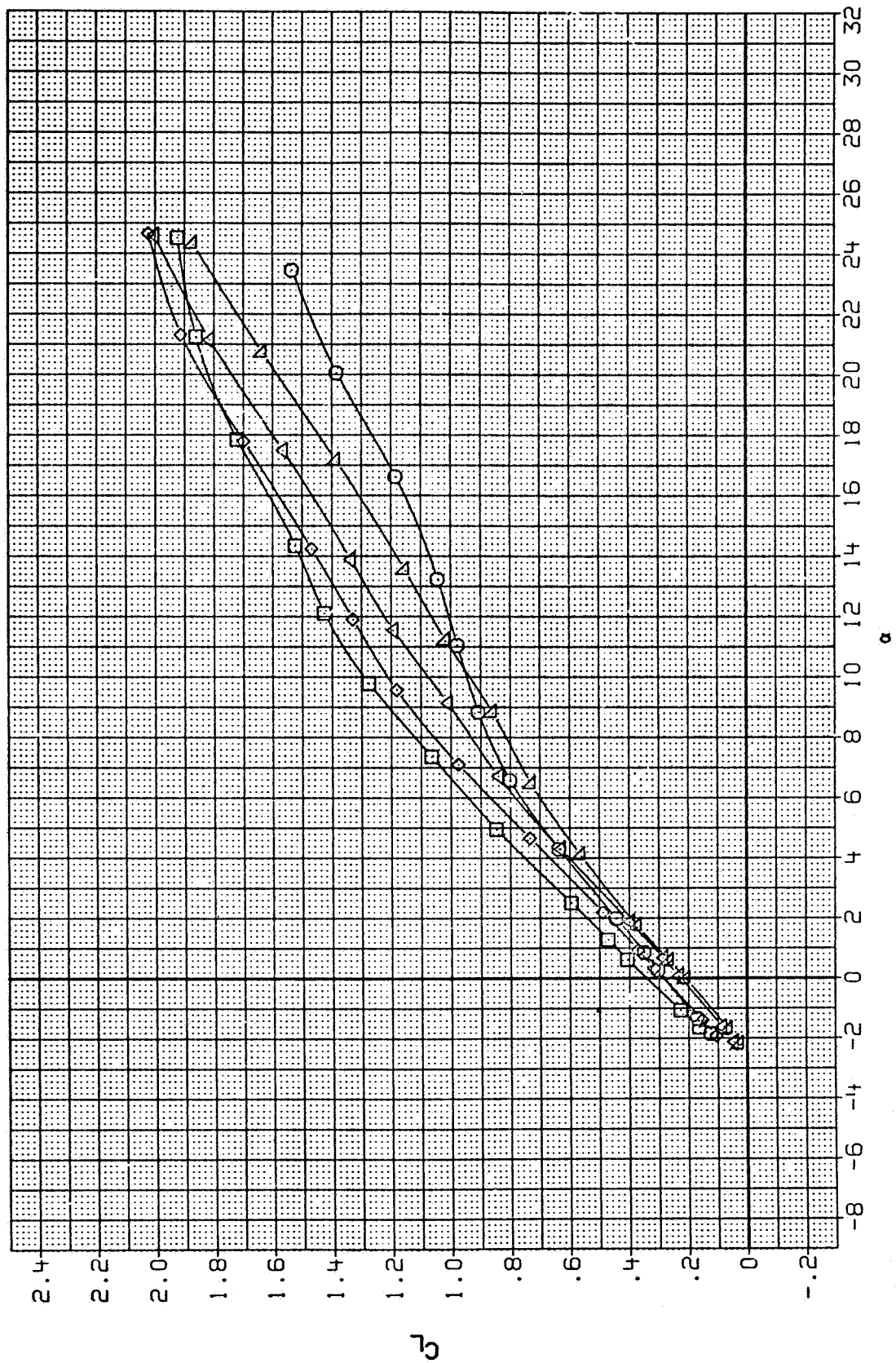


FIG. 31 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .90

SYMBOL	CONFIGURATION	CANARD
BI SI N MI V	(EJECTOR-E205)	10.000
BI SI N MI CI V	(EJECTOR-E205)	.000
BI SI N MI CI V	(EJECTOR-E205)	-10.000
BI SI N MI CI V	(EJECTOR-E205)	-20.000

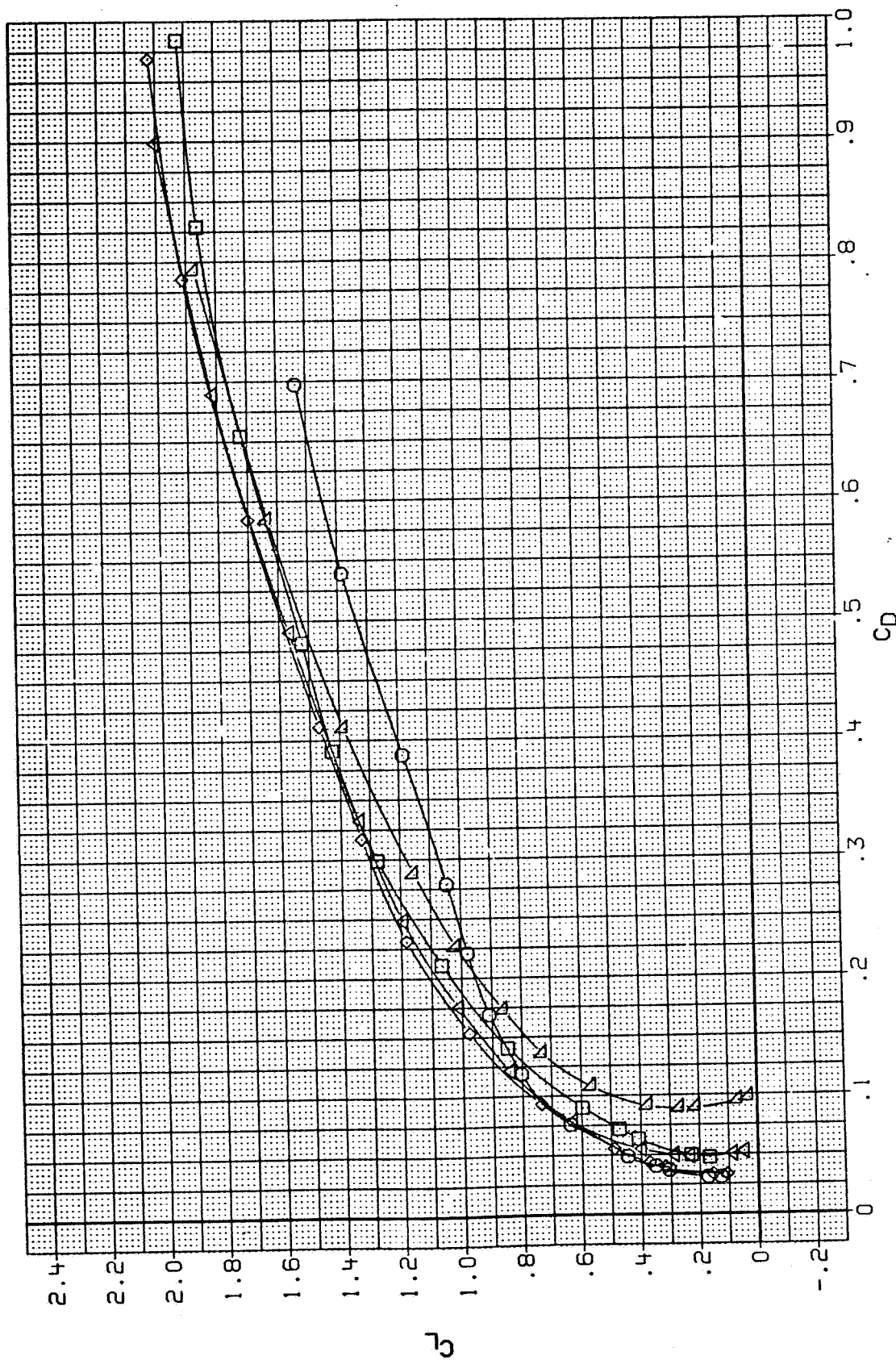


FIG. 31 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .90

SYMBOL	CONFIGURATION	CANARD
○	BI SI N WI V	10.000
◇	BI SI N WI CI V	.000
□	BI SI N WI CI V	-10.000
△	BI SI N WI CI V	-20.000

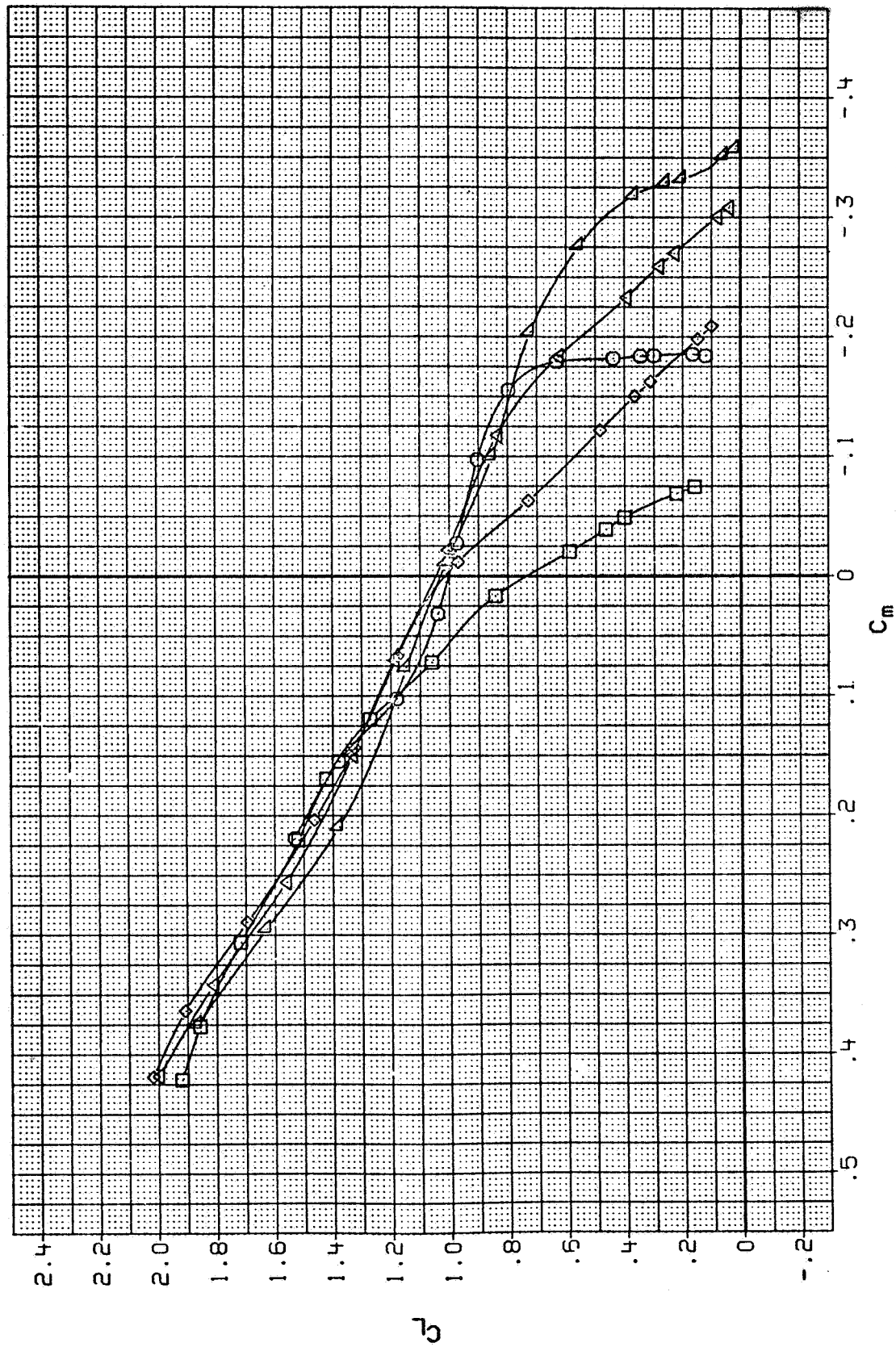


FIG. 31 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .90

SYMBOL	CONFIGURATION	CANARD
○	BI SI N WI V	10.000
□	BI SI N WI CI V	.000
△	BI SI N WI CI V	-10.000
◇	BI SI N WI CI V	-20.000

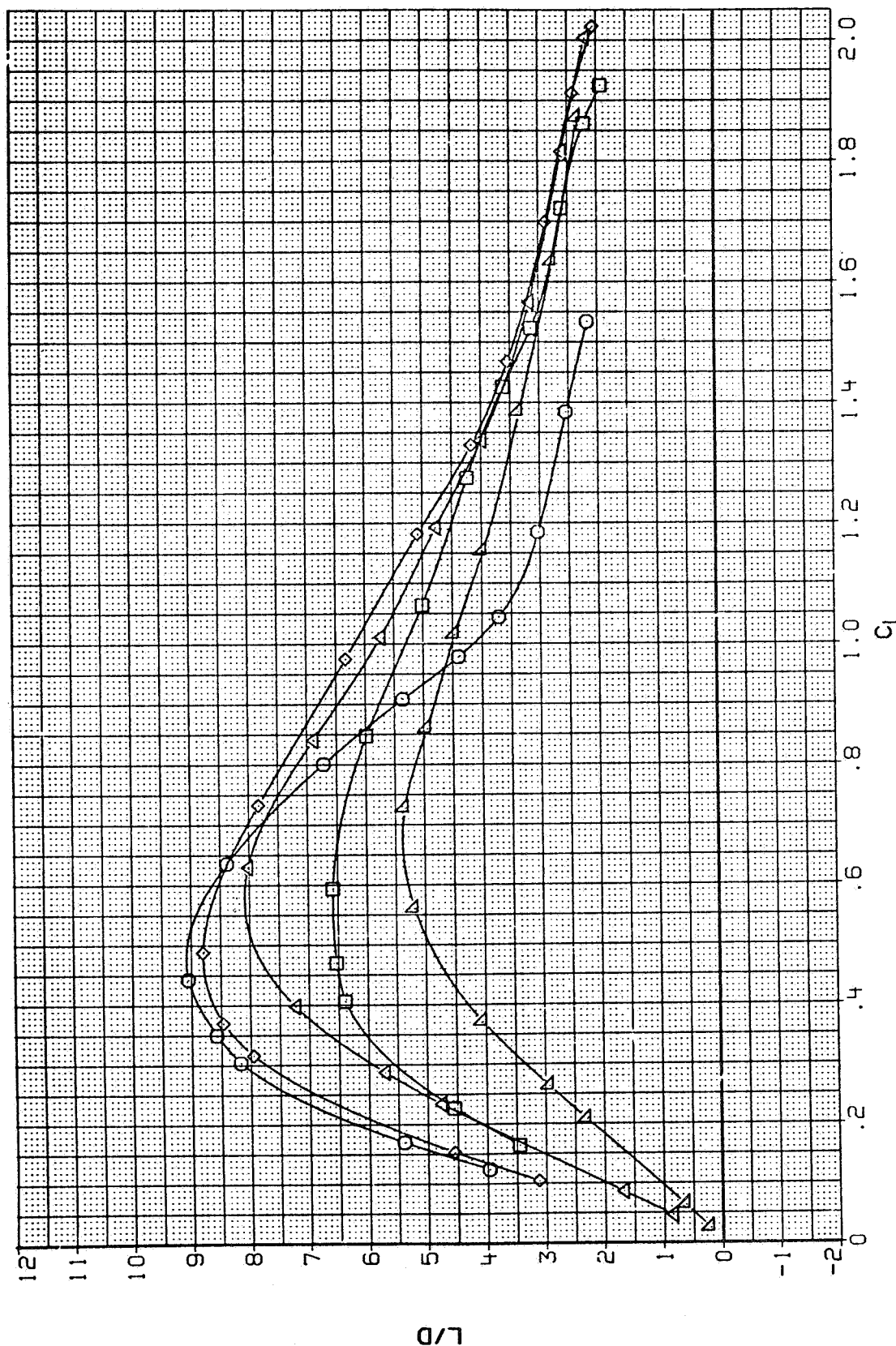


FIG. 31 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .90

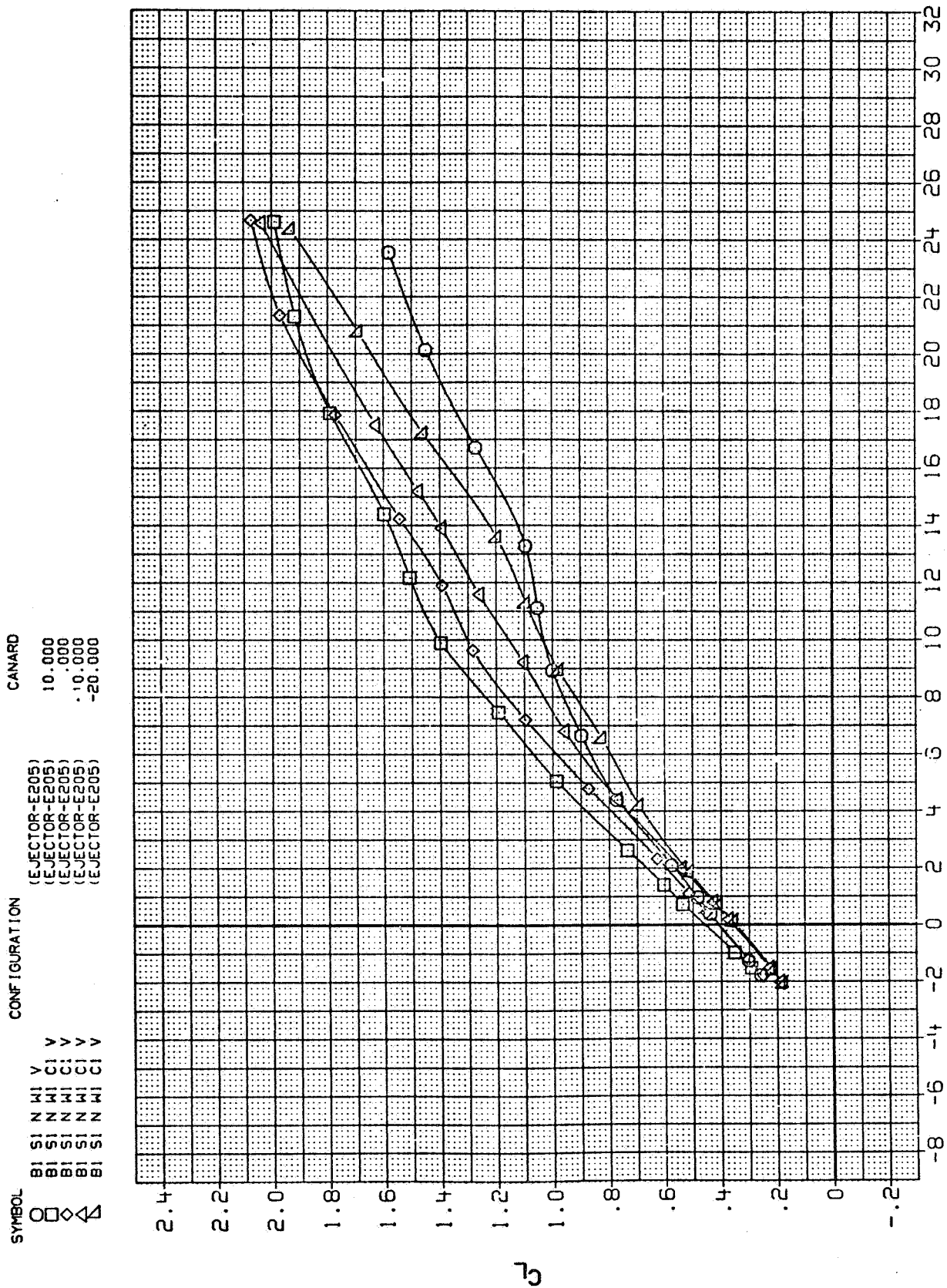


FIG. 32 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .90

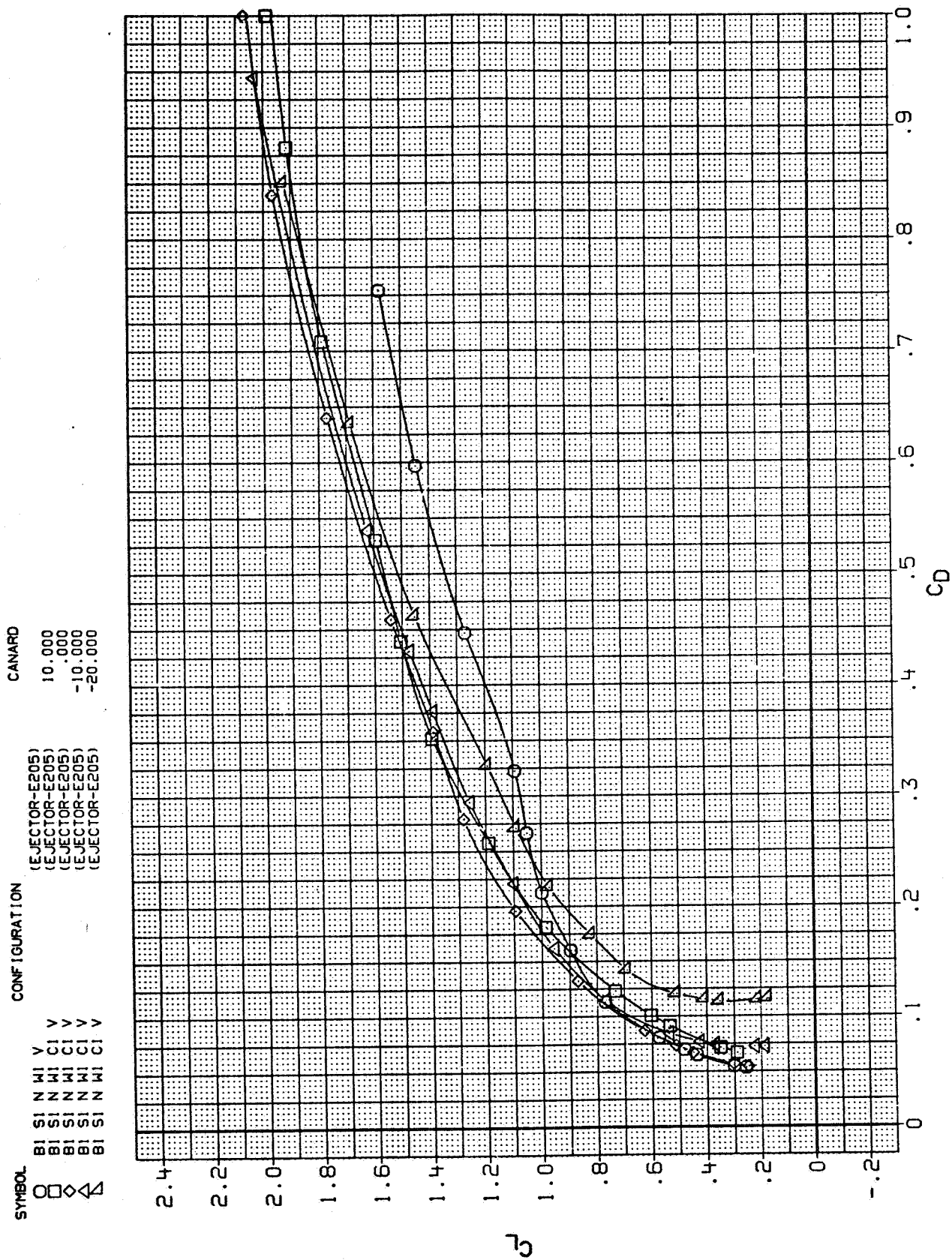


FIG. 32 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .90

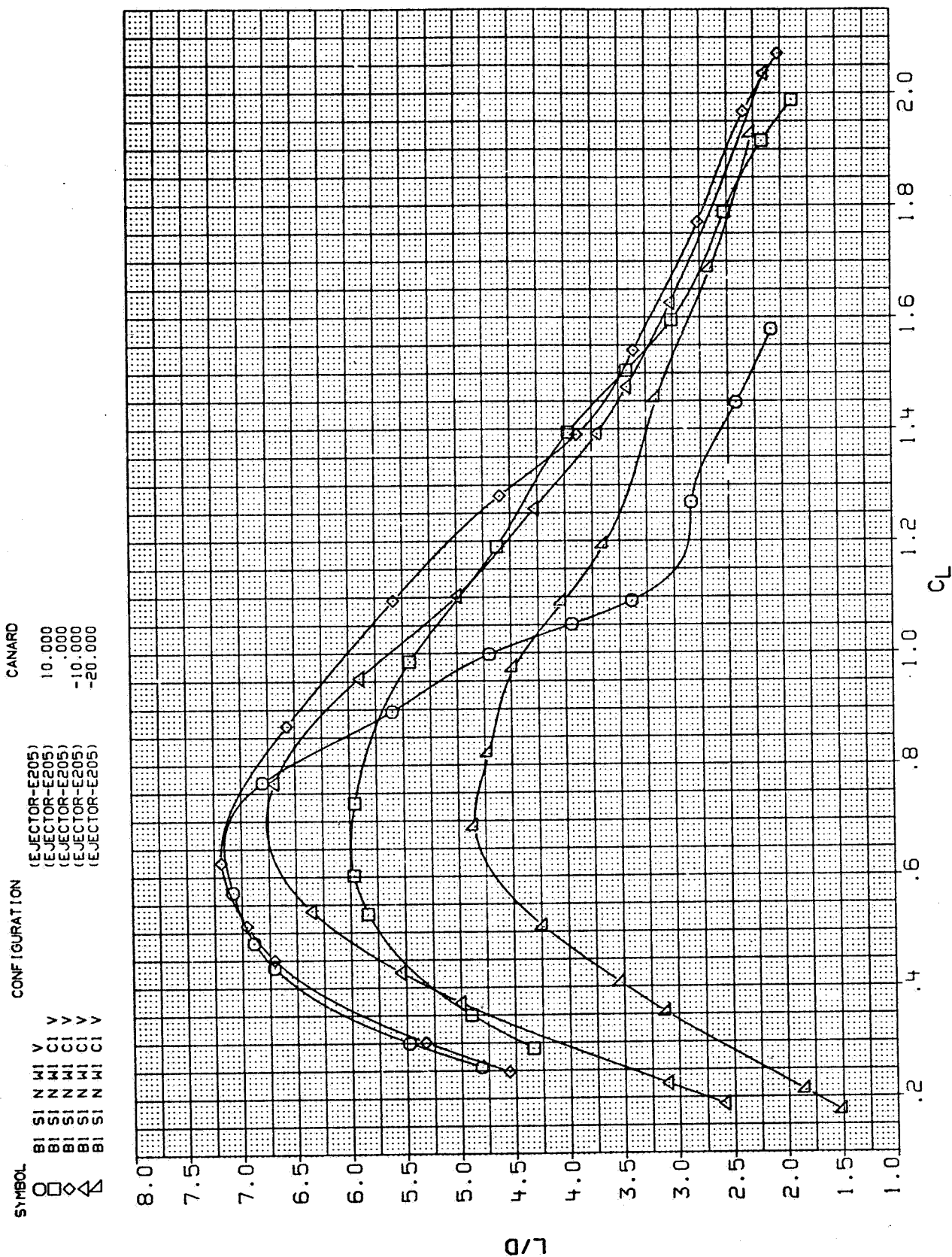


FIG. 32 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .90

SYMBOL		CONFIGURATION		CANARD	
○	BI SI N WI V	(EJECTOR-E205)	10.000		
□	BI SI N WI CI V	(EJECTOR-E205)	.000		
◇	BI SI N WI CI V	(EJECTOR-E205)	-10.000		
△	BI SI N WI CI V	(EJECTOR-E205)	-20.000		

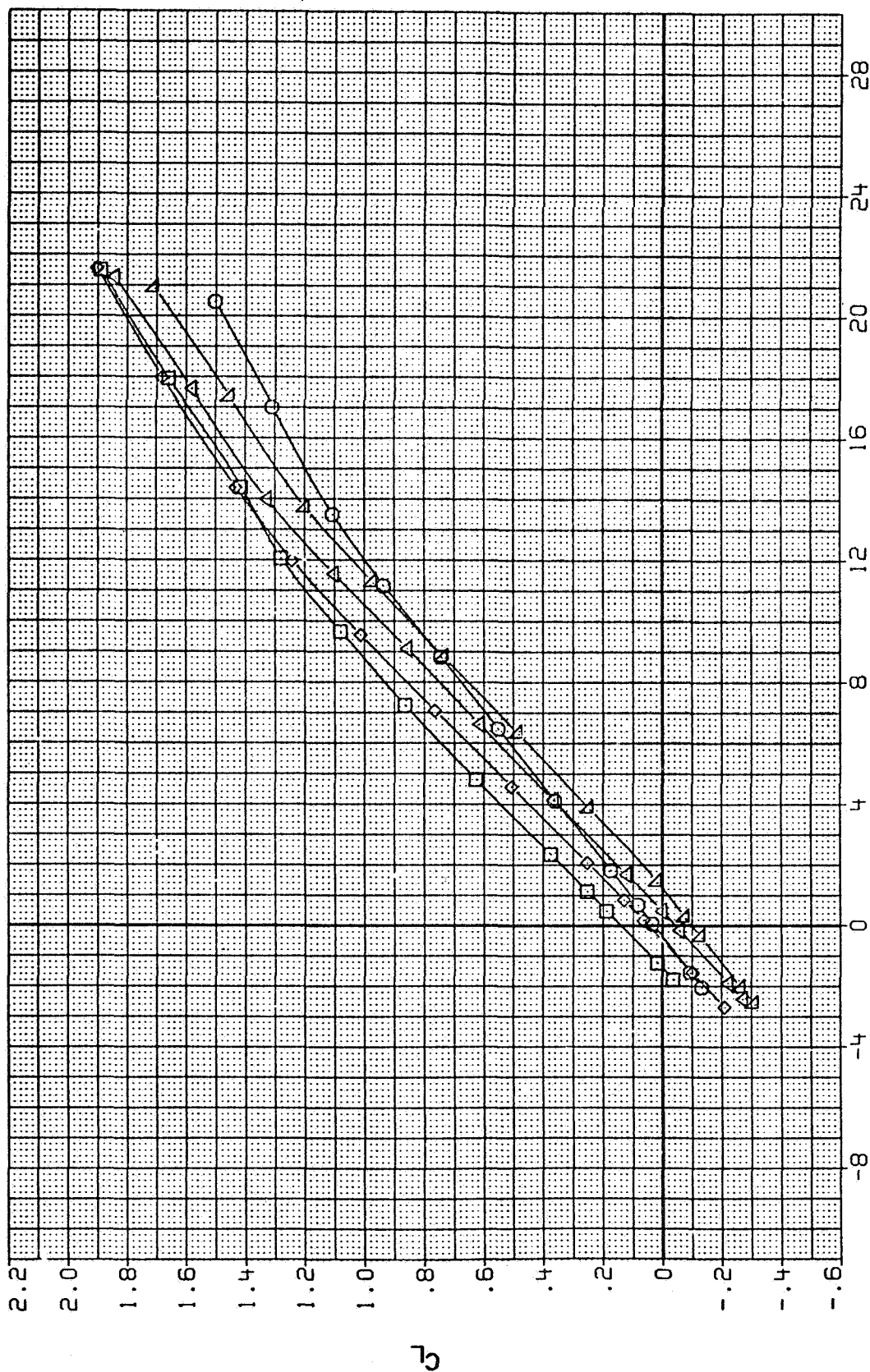


FIG. 33 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = 1.20

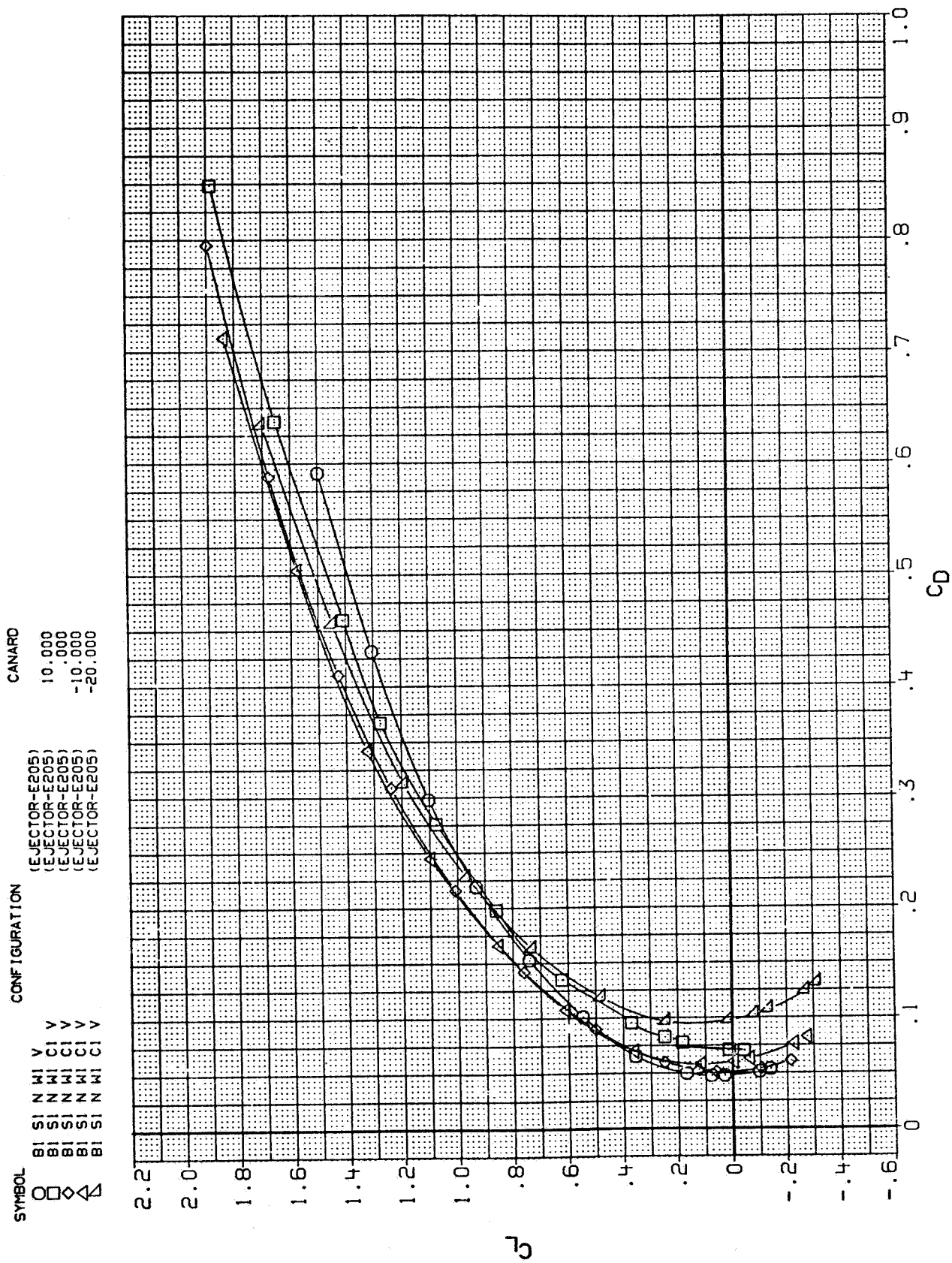


FIG. 33 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = 1.20

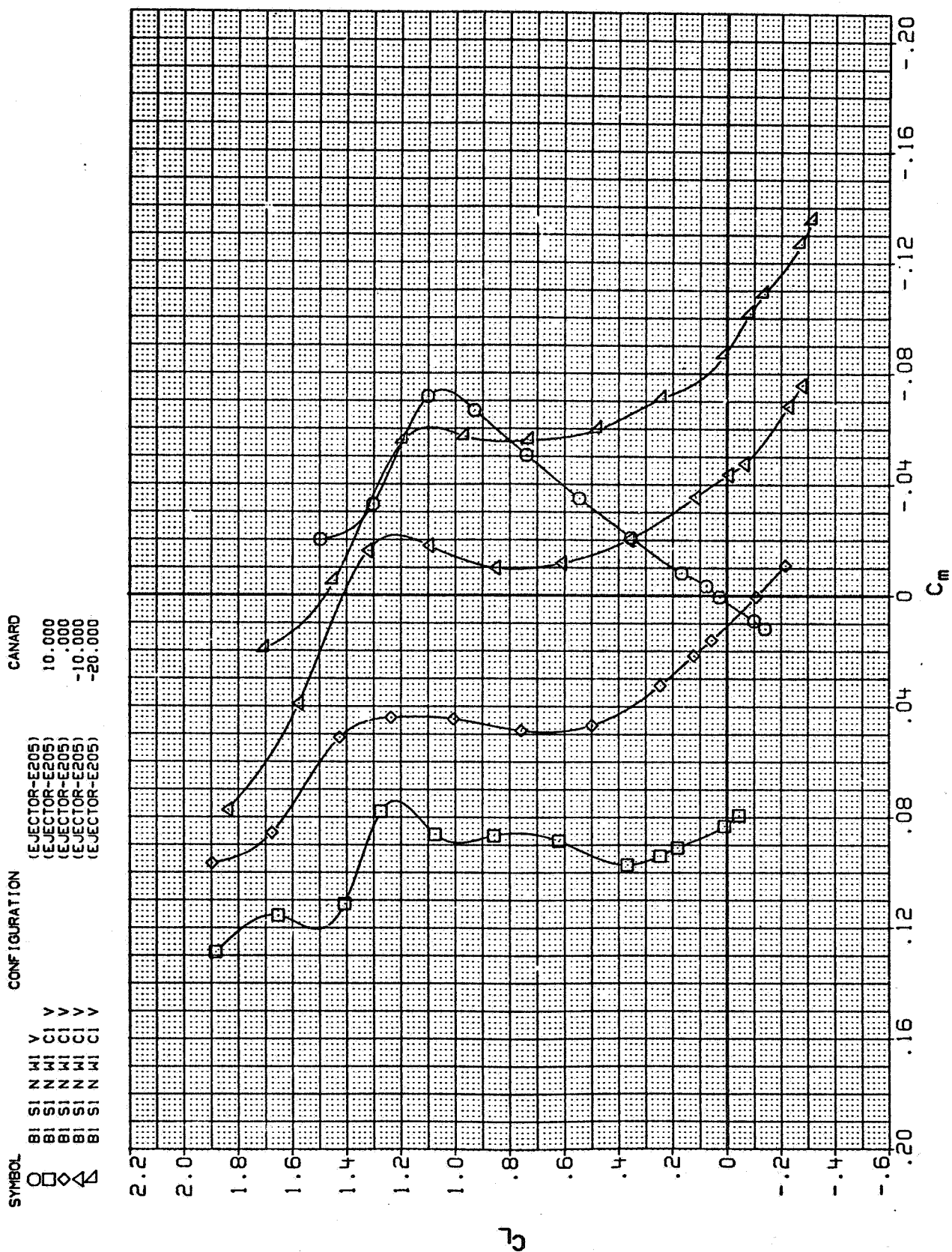


FIG. 33 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = 1.20

SYMBOL	CONFIGURATION	CANARD
□	BI SI N MI V	10.000
◇	BI SI N MI CI V	.000
△	BI SI N MI CI V	-10.000
▽	BI SI N MI CI V	-20.000

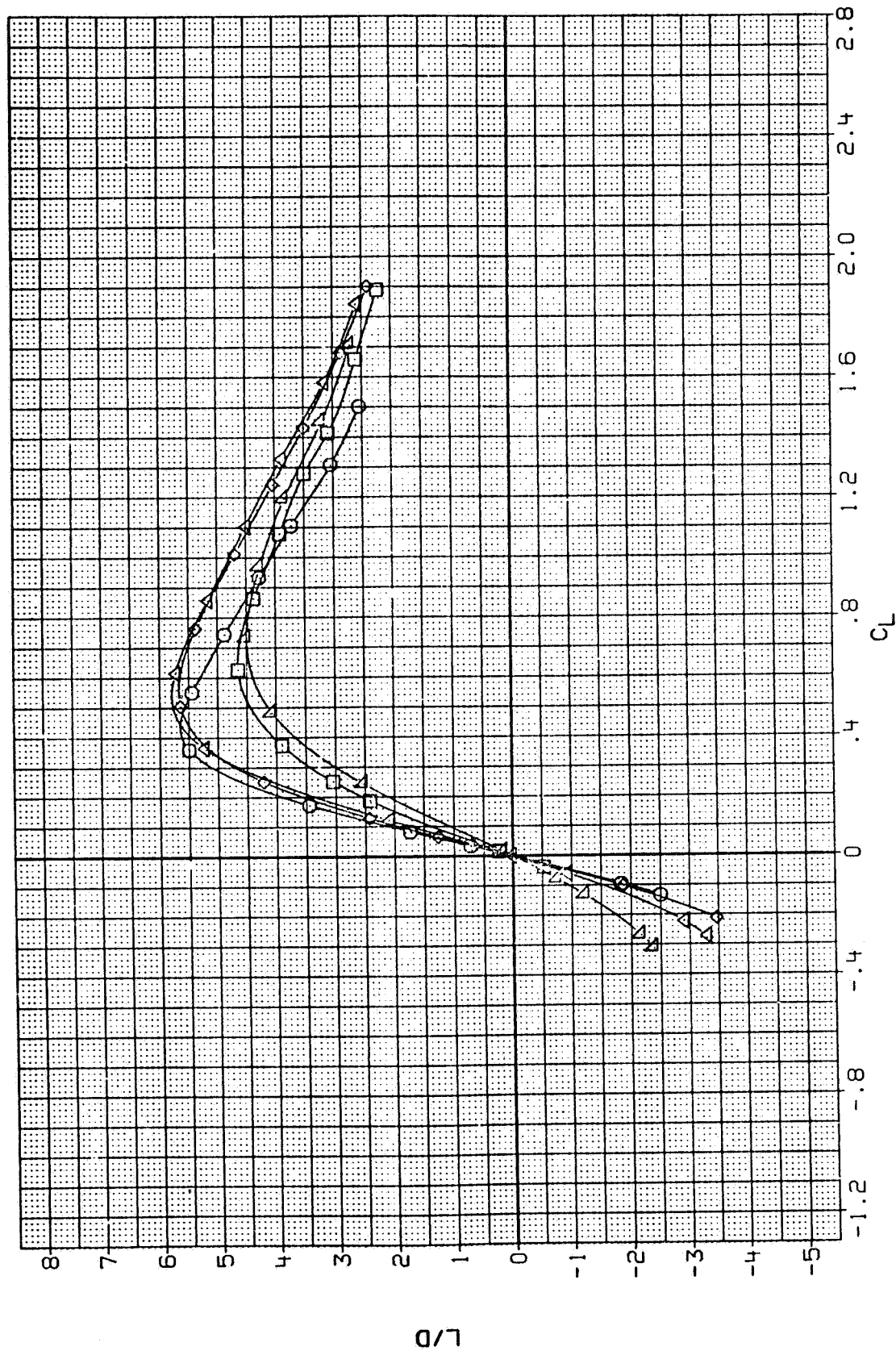


FIG. 33 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = 1.20

L/D

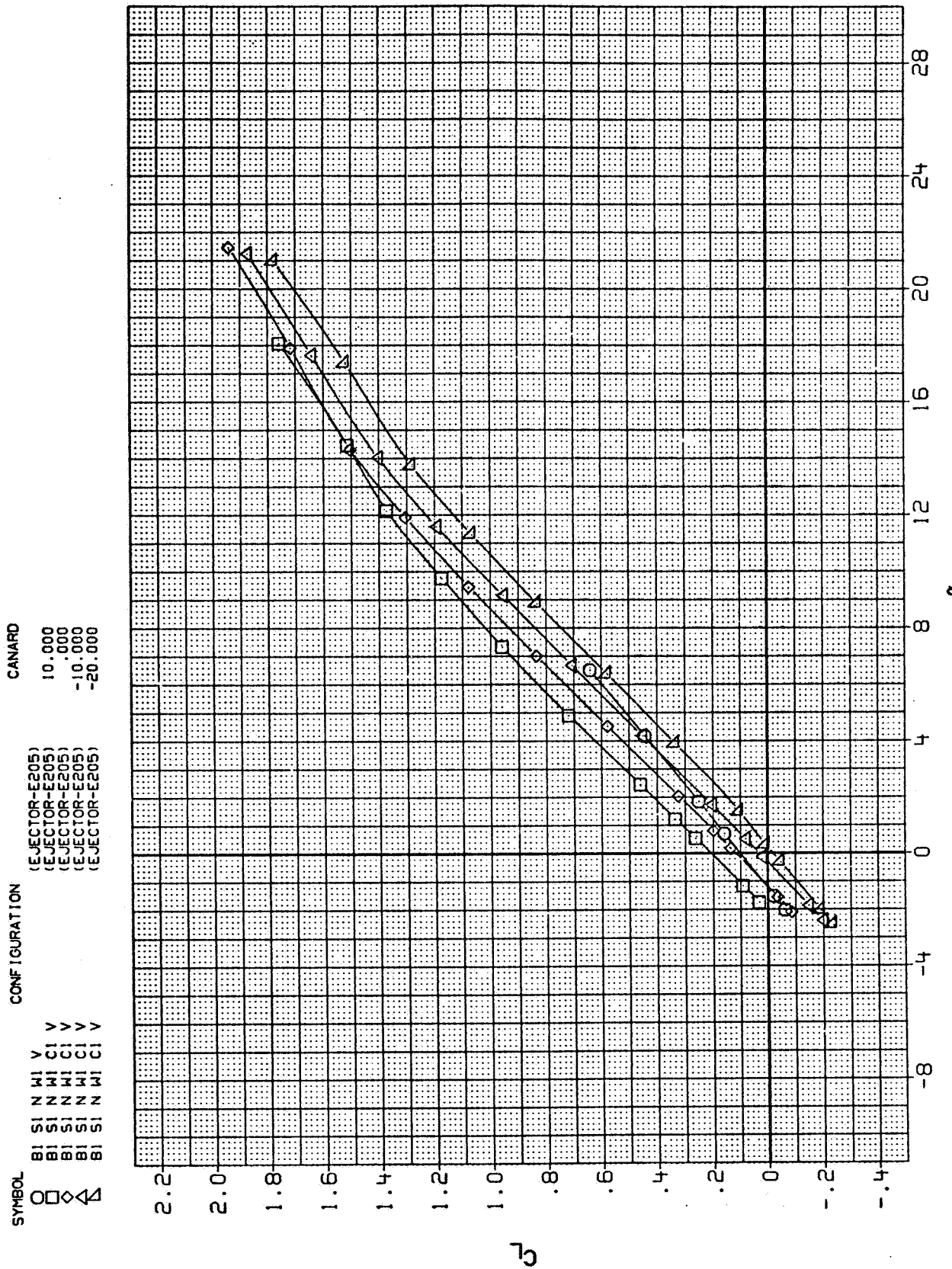


FIG. 34 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = 1.20

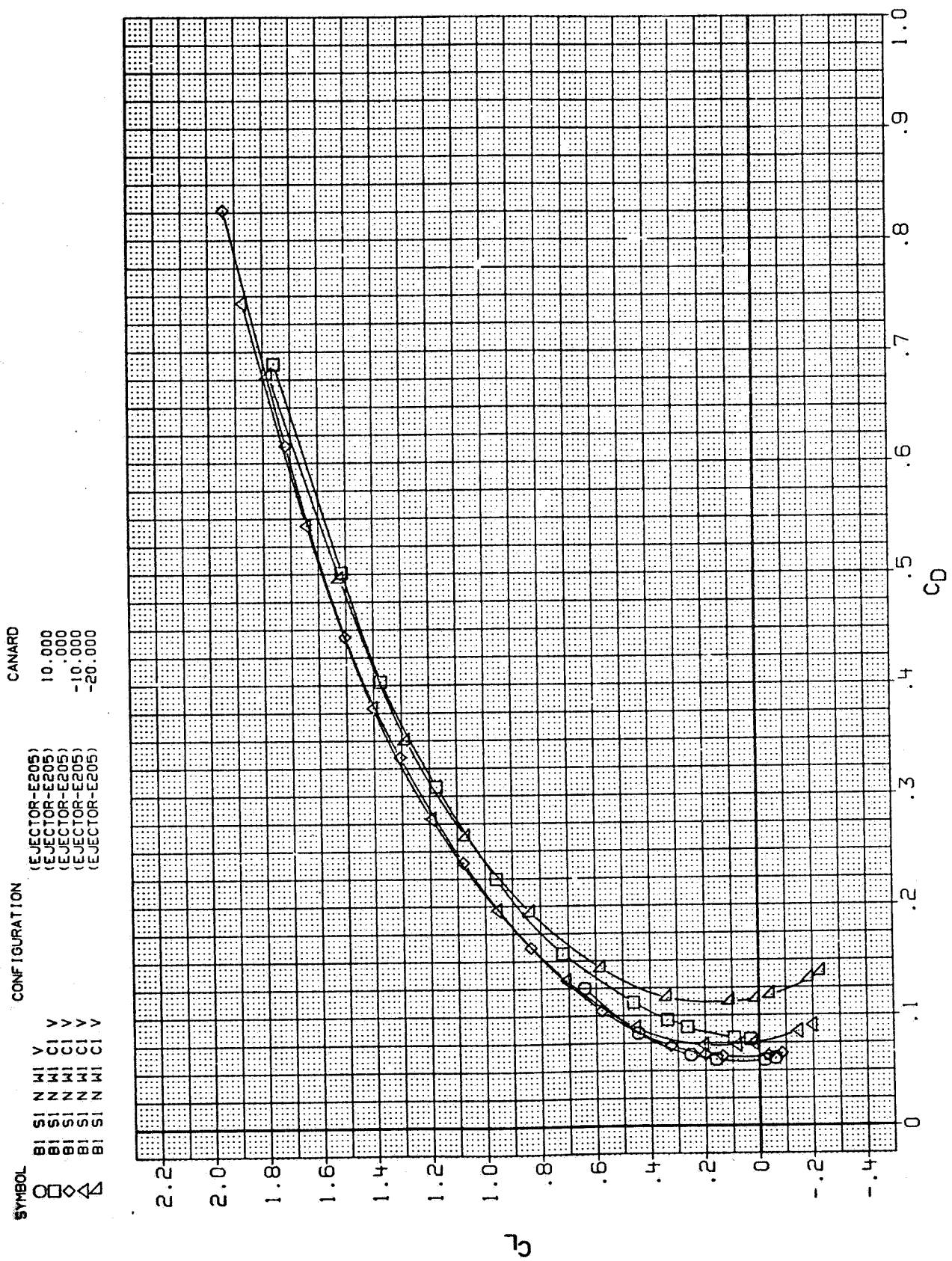


FIG. 34 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = 1.20

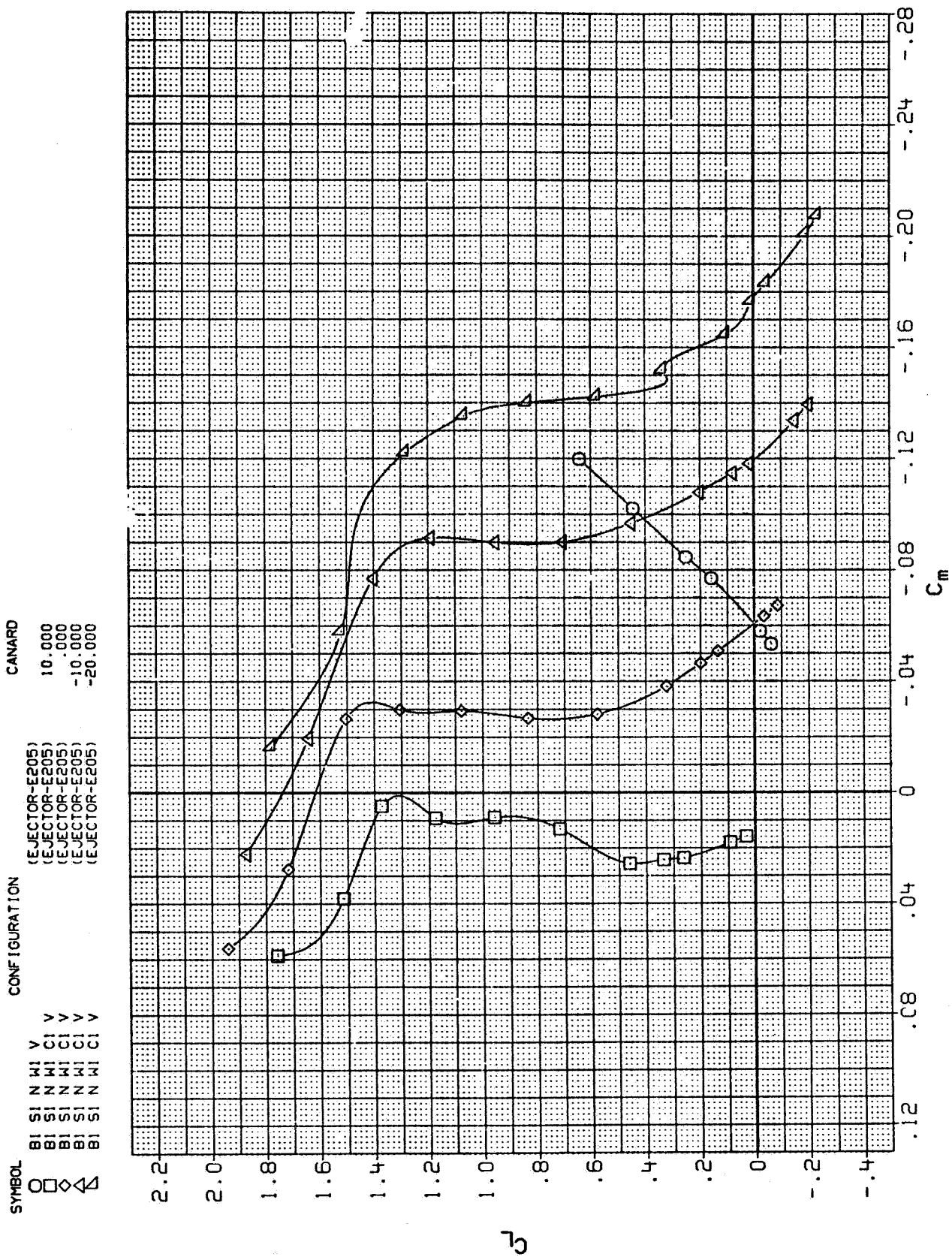


FIG. 34 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = 1.20

SYMBOL	CONFIGURATION	CANARD
BI SI N WI V	(EJECTOR-E205)	10.000
BI SI N WI CI V	(EJECTOR-E205)	.000
BI SI N WI CI V	(EJECTOR-E205)	-10.000
BI SI N WI CI V	(EJECTOR-E205)	-20.000

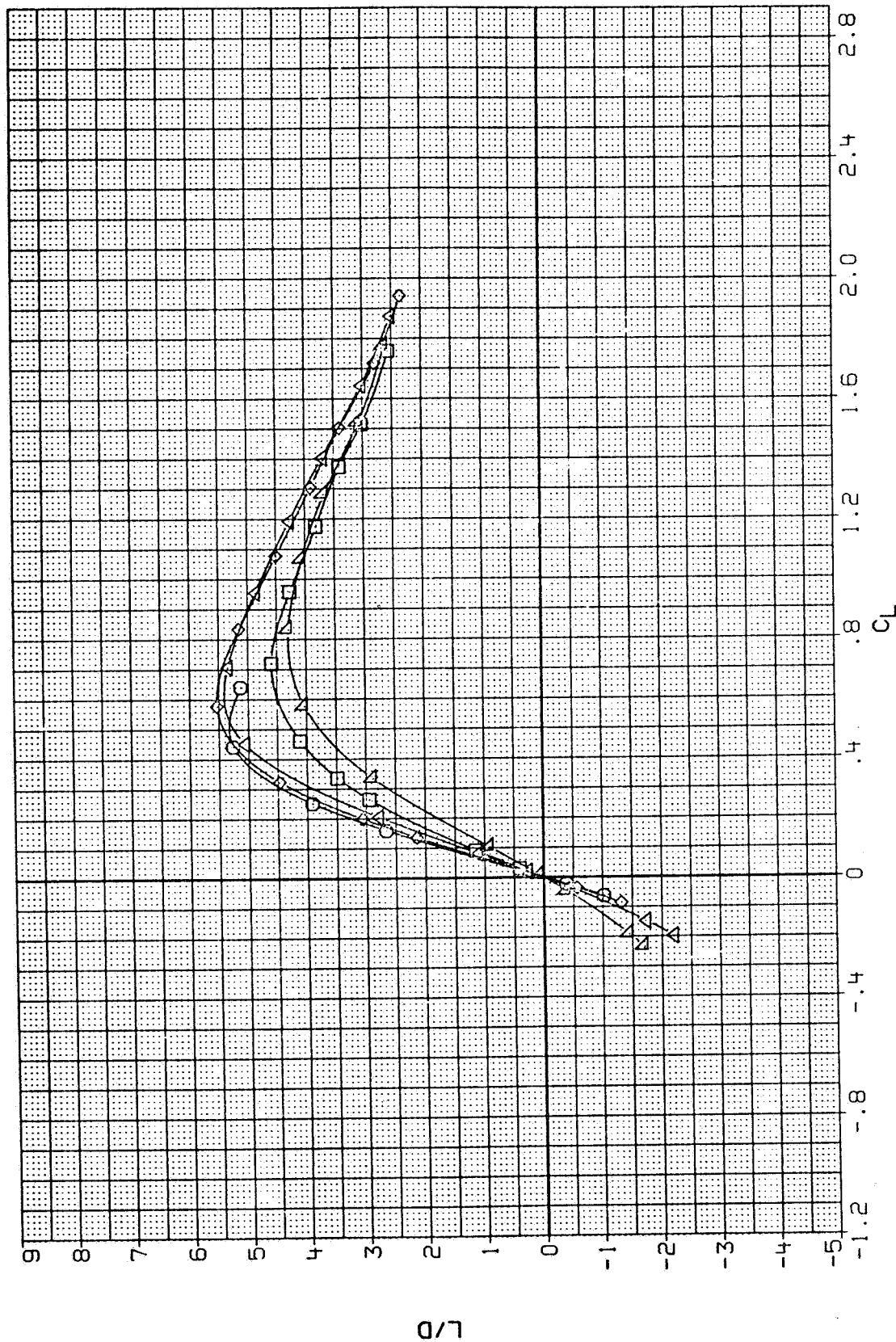


FIG. 34 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = 1.20

0/7

SYMBOL		CONFIGURATION		CANARD	
□	BI SI N WI V	(EJECTOR-E205)	10.000		
◇	BI SI N WI CI V	(EJECTOR-E205)	.000		
△	BI SI N WI CI V	(EJECTOR-E205)	-10.000		
▽	BI SI N WI CI V	(EJECTOR-E205)	-20.000		

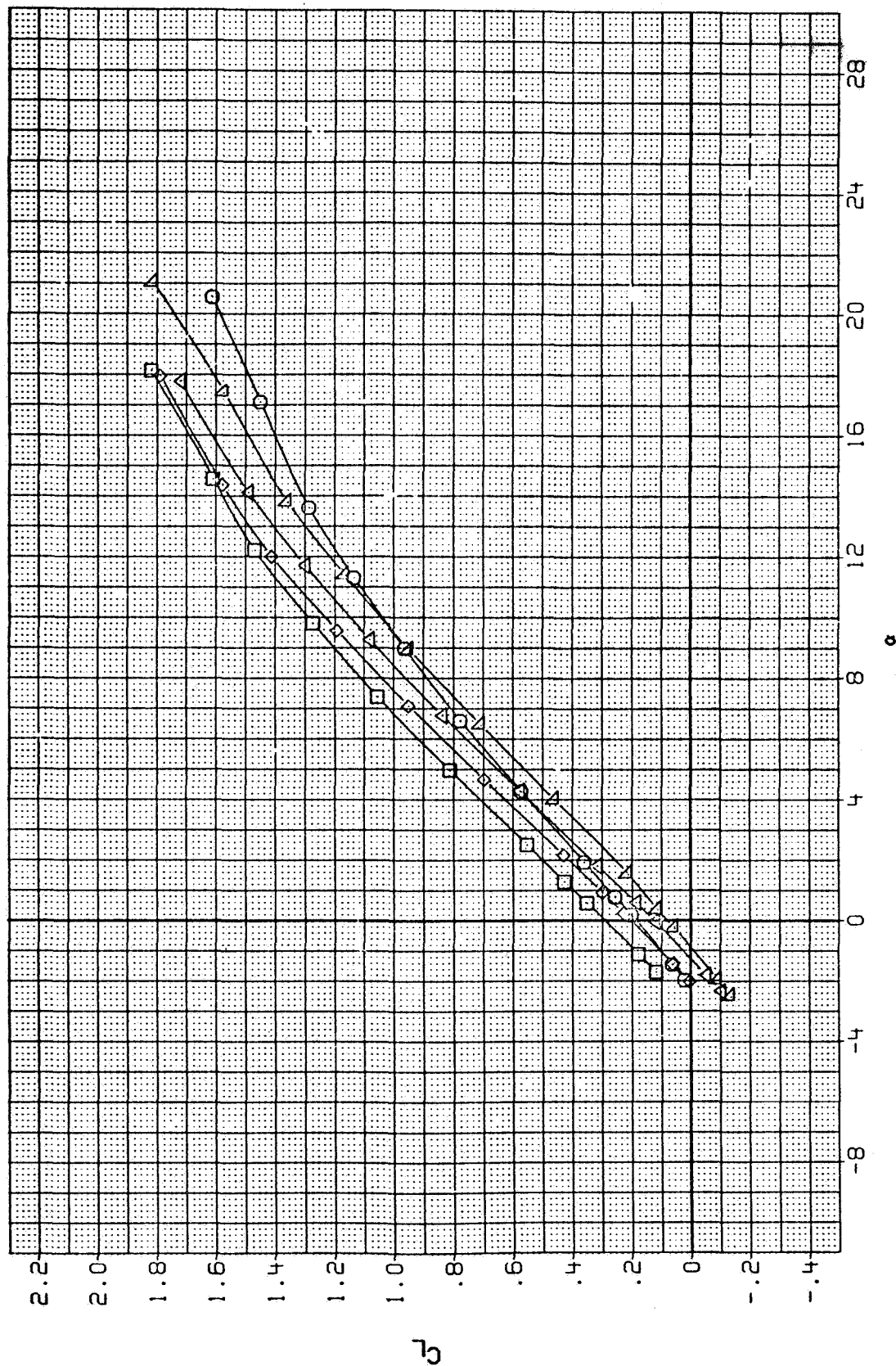


FIG. 35 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = 1.20

SYMBOL		CONFIGURATION		CANARD	
○	BI SI N MI V	(EJECTOR-E205)	10.000		
□	BI SI N MI CI V	(EJECTOR-E205)	.000		
◇	BI SI N MI CI V	(EJECTOR-E205)	-10.000		
△	BI SI N MI CI V	(EJECTOR-E205)	-20.000		

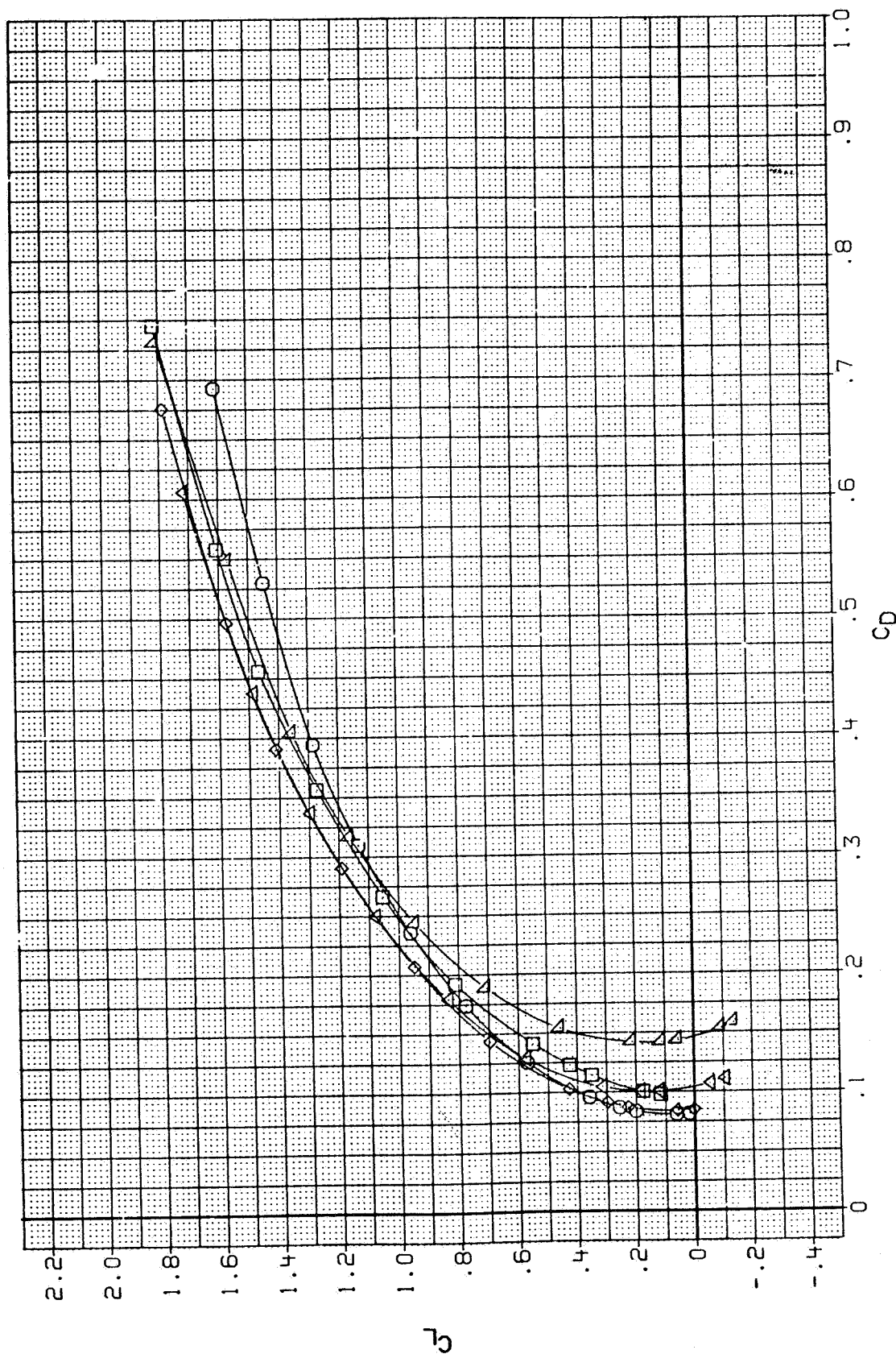


FIG. 35 CANARD INCIDENCE EFFECTS, $TE-W = 25$ DEGREES

$MACH = 1.20$

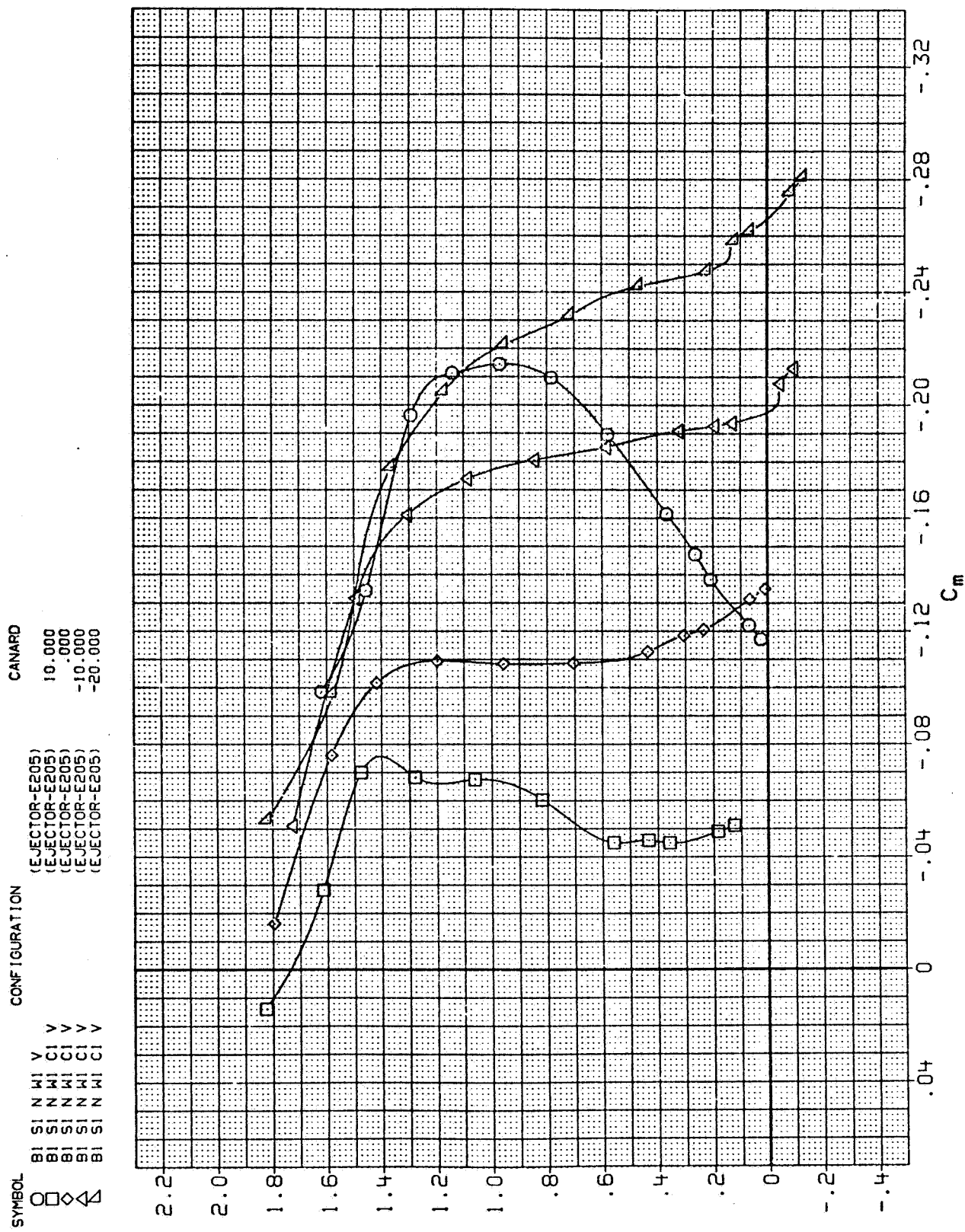


FIG. 35 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = 1.20

SYMBOL		CONFIGURATION		CANARD	
□	BI SI N WI V	(EJECTOR-E205)	10.000		
○	BI SI N WI CI V	(EJECTOR-E205)	10.000		
△	BI SI N WI CI V	(EJECTOR-E205)	-10.000		
▽	BI SI N WI CI V	(EJECTOR-E205)	-20.000		

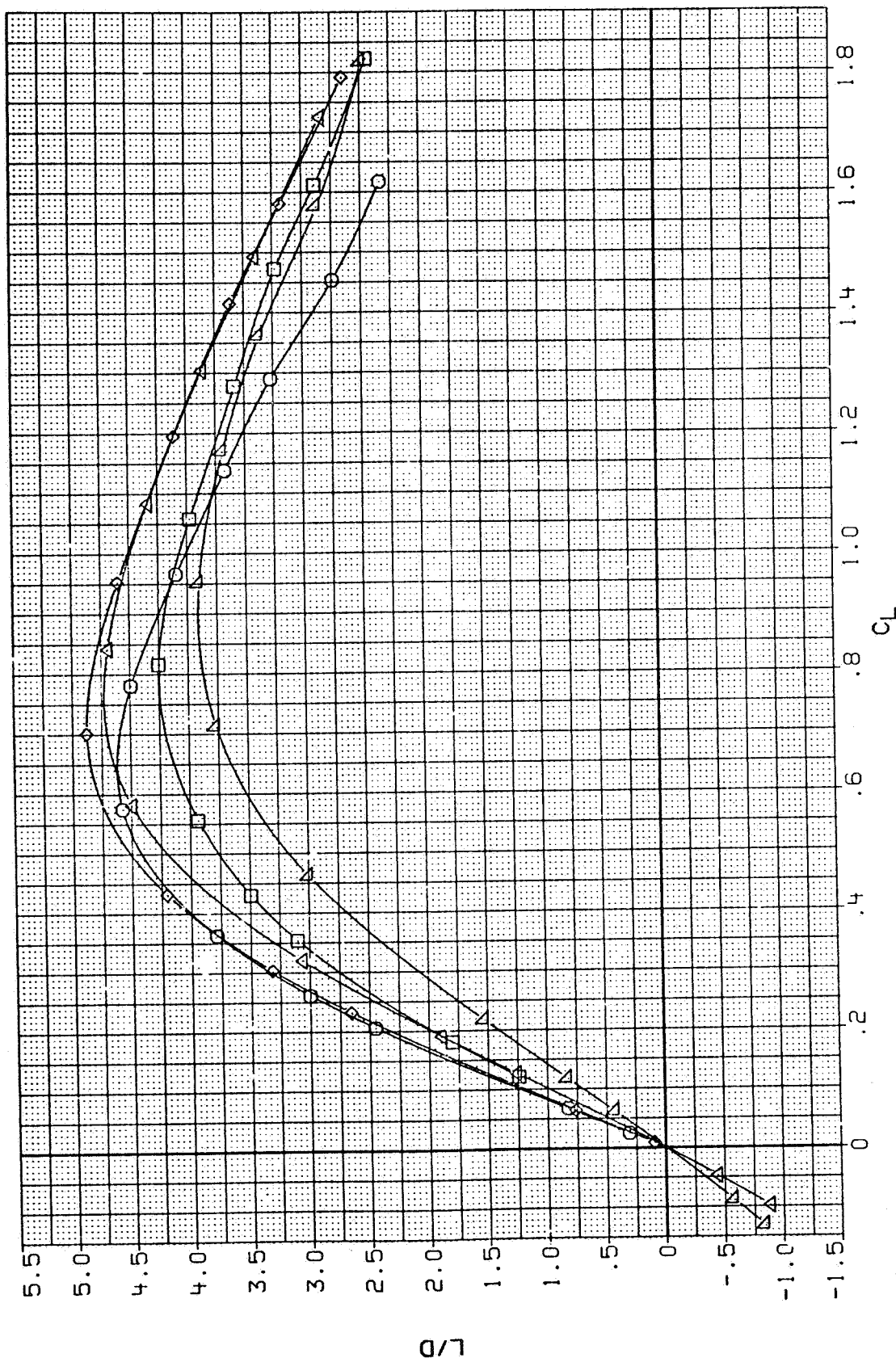


FIG. 35 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = 1.20

SYMBOL CONFIGURATION TE-W
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

BI SI N WI CI V
 BI SI N WI CI V
 BI SI N WI CI V

□ ○ ◇

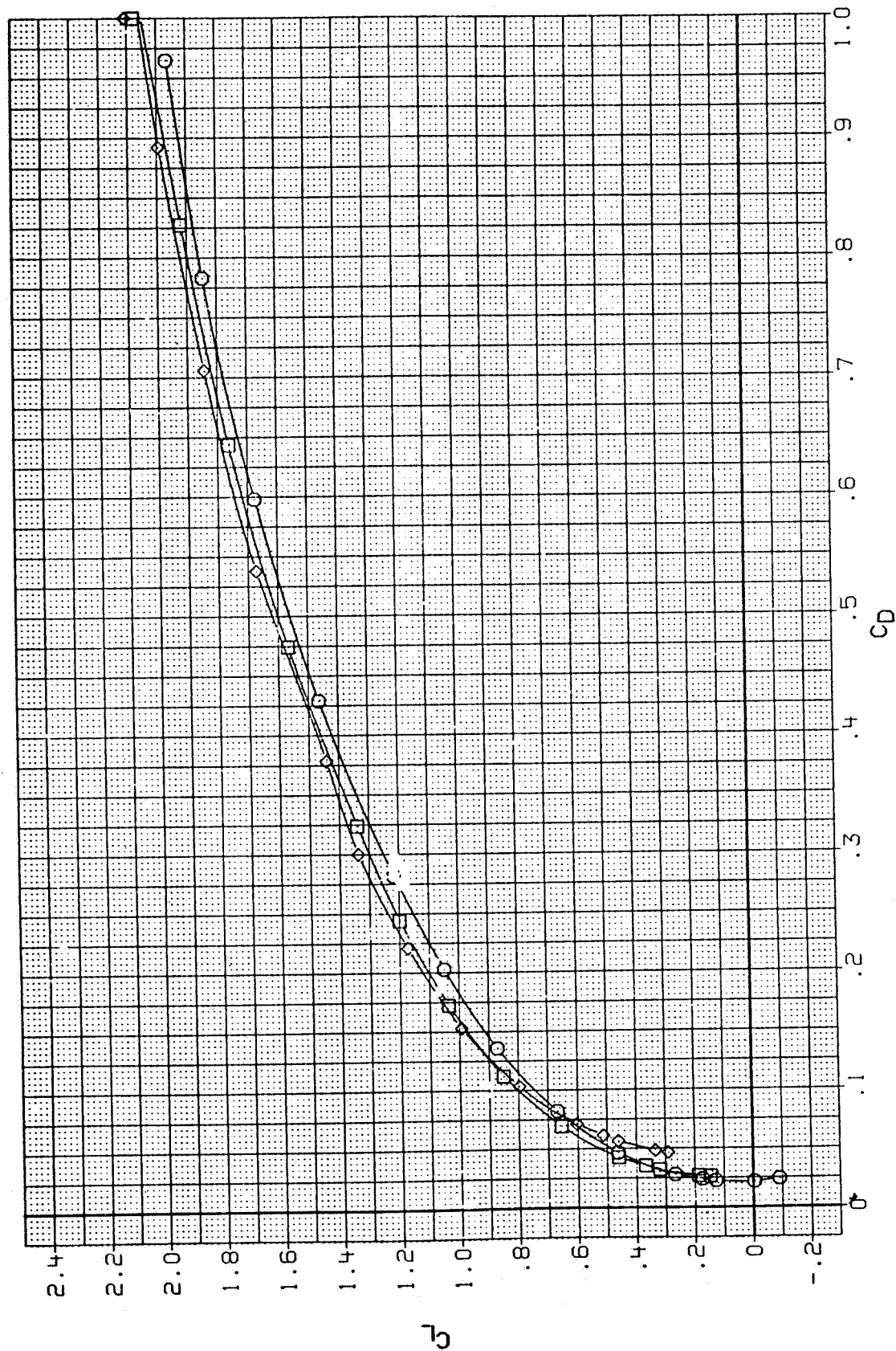


FIG. 36 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .60

SYMBOL CONFIGURATION TE-W
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

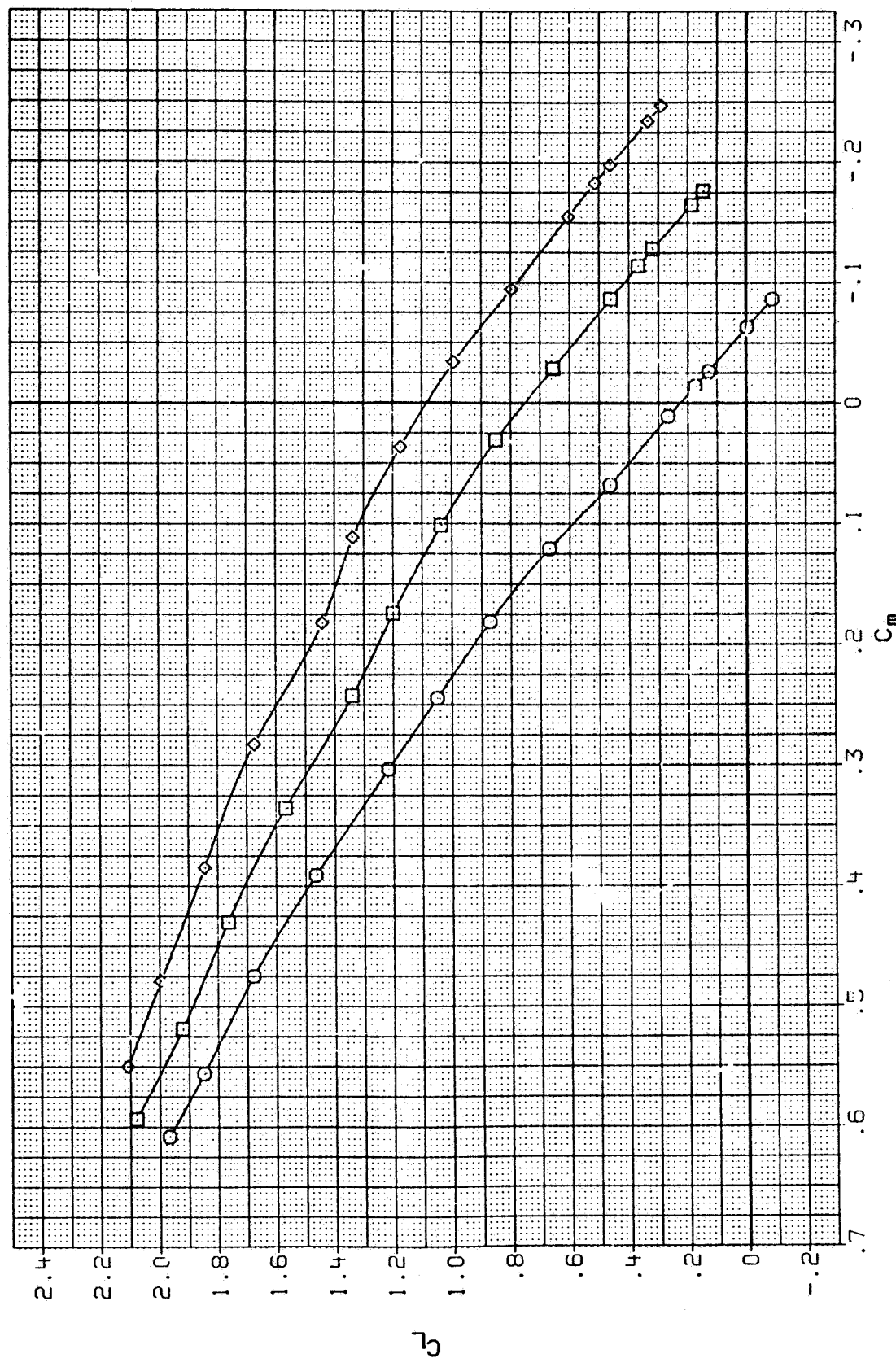


FIG. 36 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .60

SYMBOL	CONFIGURATION	TE-W
○	(EJECTOR-E205)	.000
□	(EJECTOR-E205)	10.000
◇	(EJECTOR-E205)	25.000

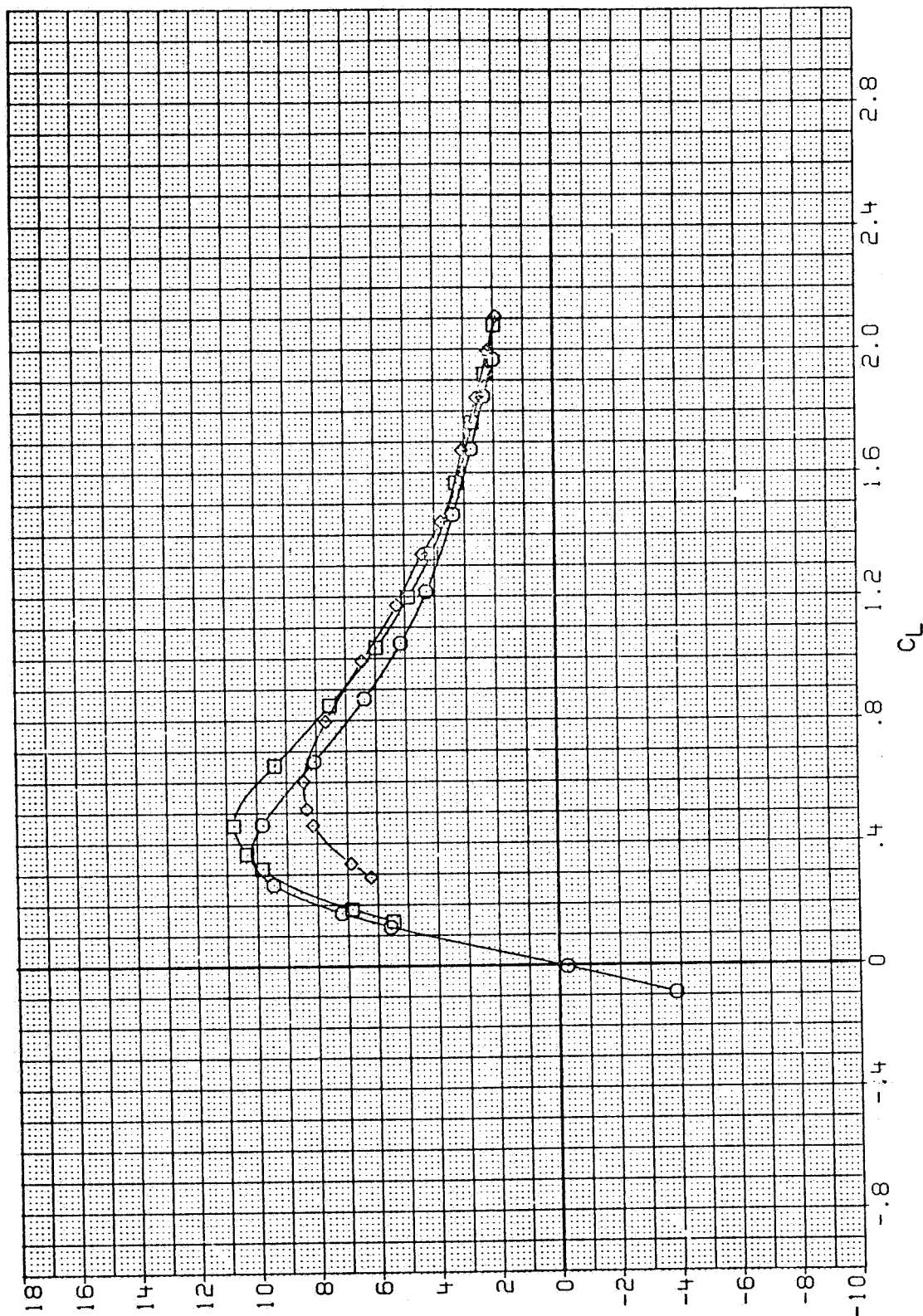


FIG. 36 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .60

L/D

SYMBOL CONFIGURATION TE-W
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

.000
 10.000
 25.000

BI SI N MI CI V
 BI SI N MI CI V
 BI SI N MI CI V

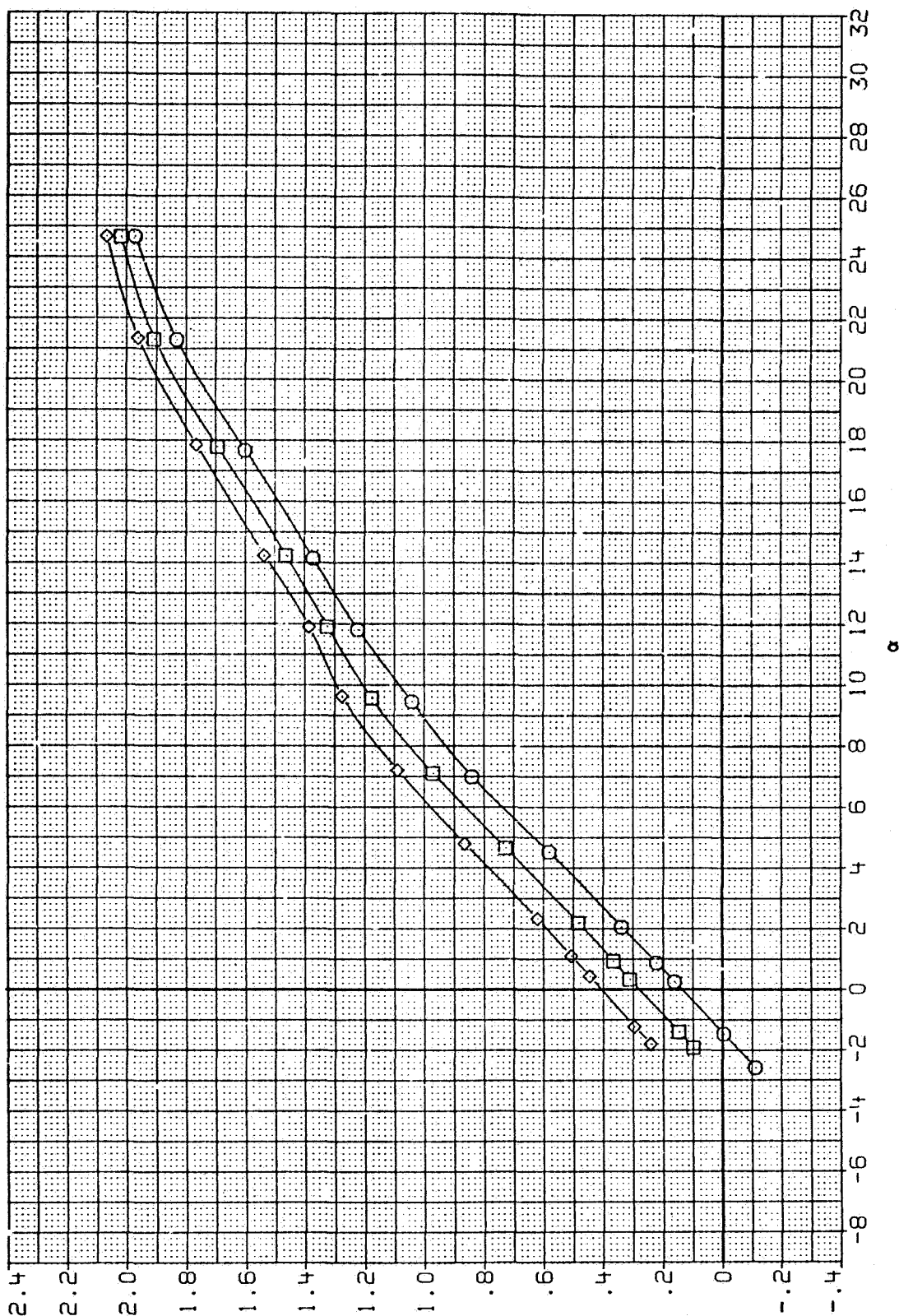


FIG. 37 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .90

SYMBOL CONFIGURATION TE-M
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

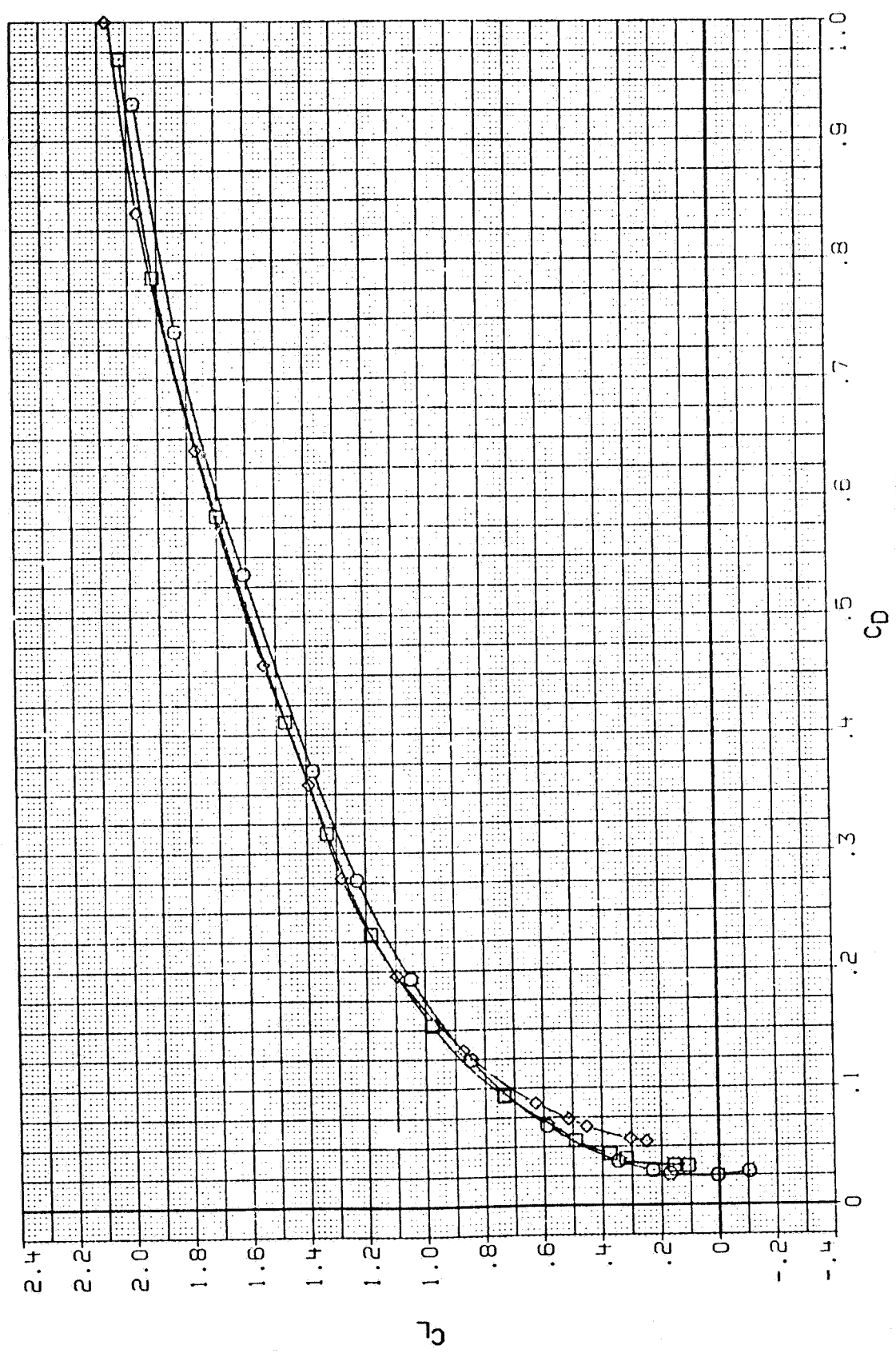


FIG. 37 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .90

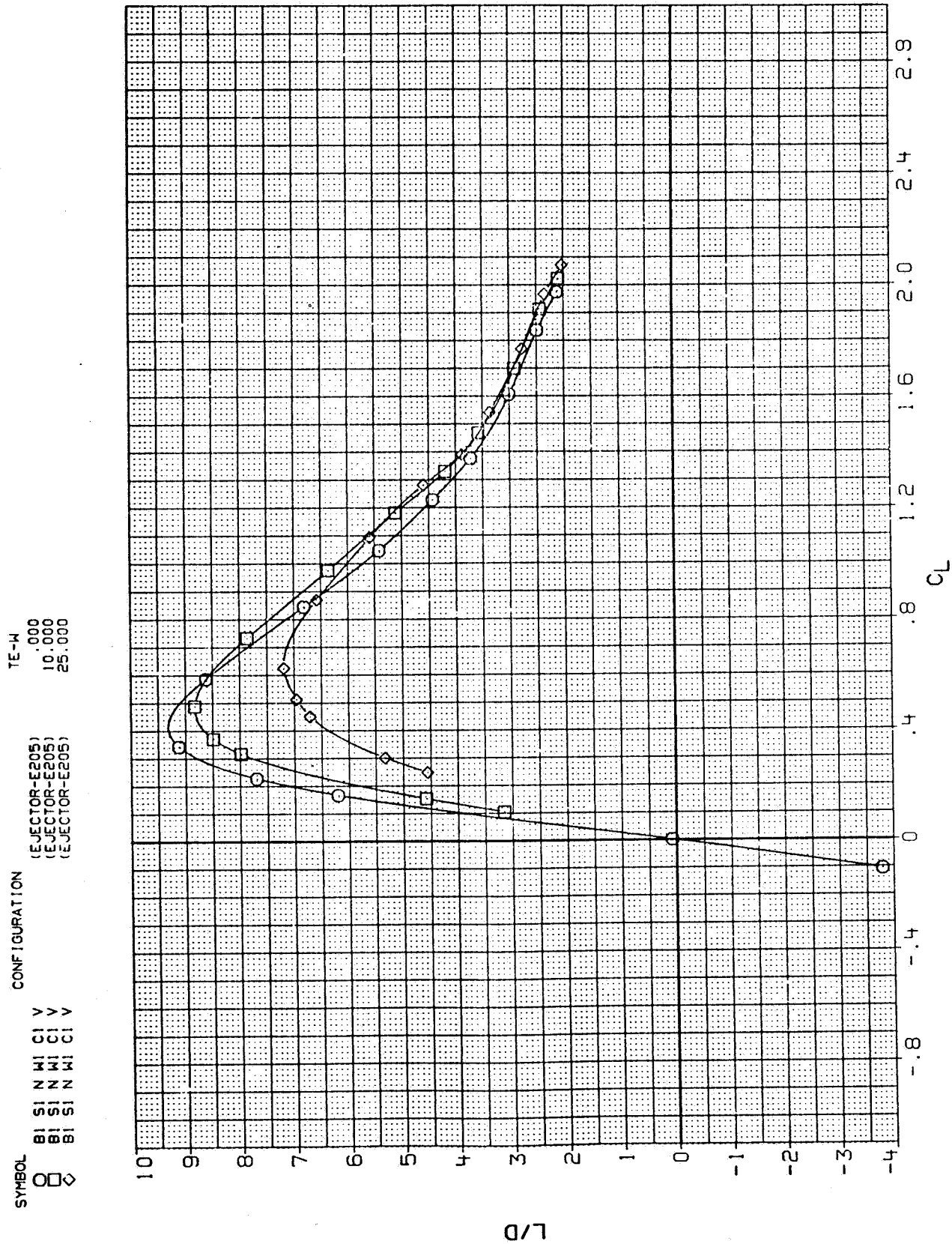


FIG. 37 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .90

SYMBOL CONFIGURATION TE-W
 (EJECTOR-E205) .000
 (EJECTOR-E205) 10.000
 (EJECTOR-E205) 25.000

BI SI N WI CI V
 BI SI N WI CI V
 BI SI N WI CI V

.000
 10.000
 25.000

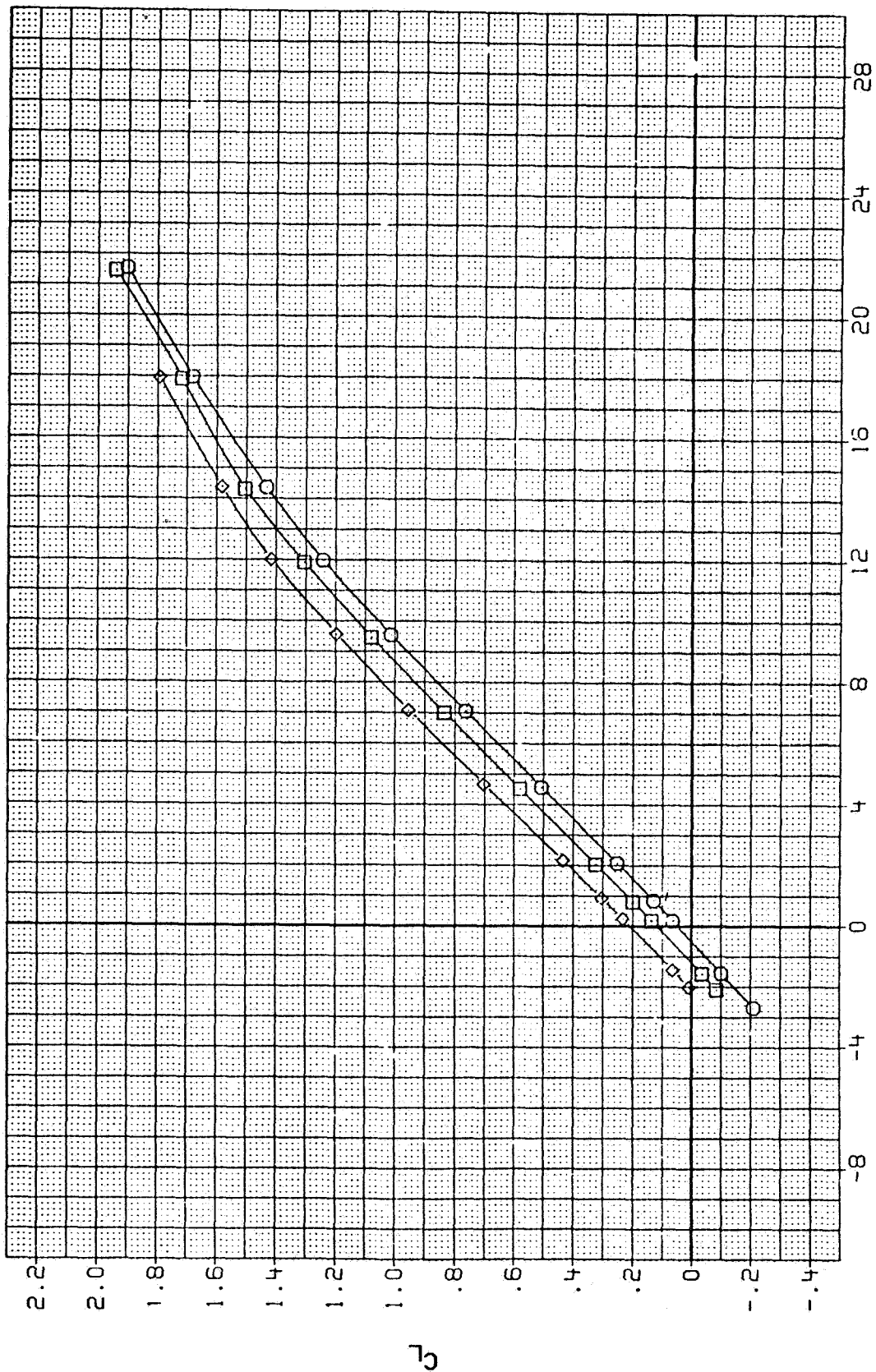
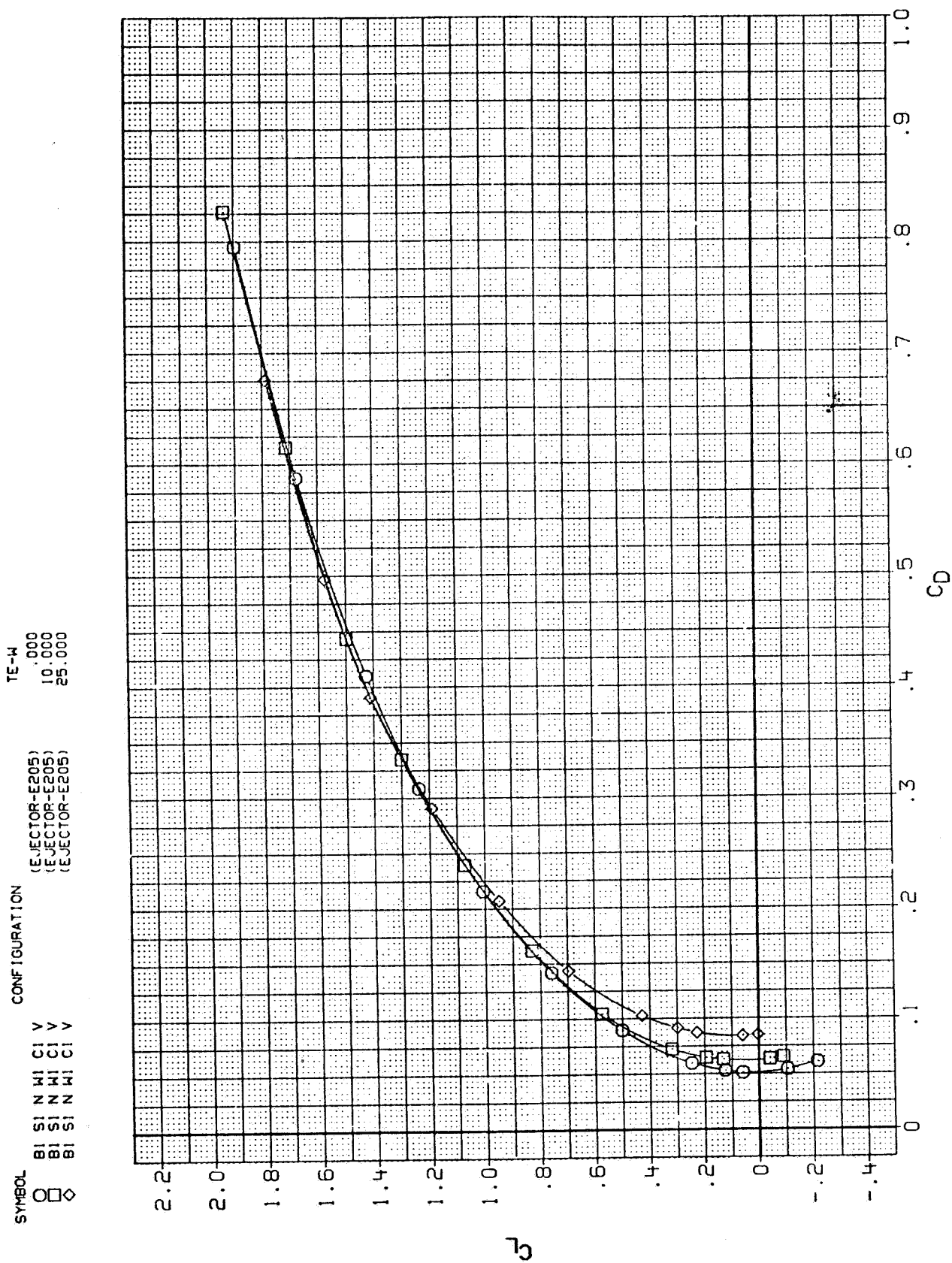
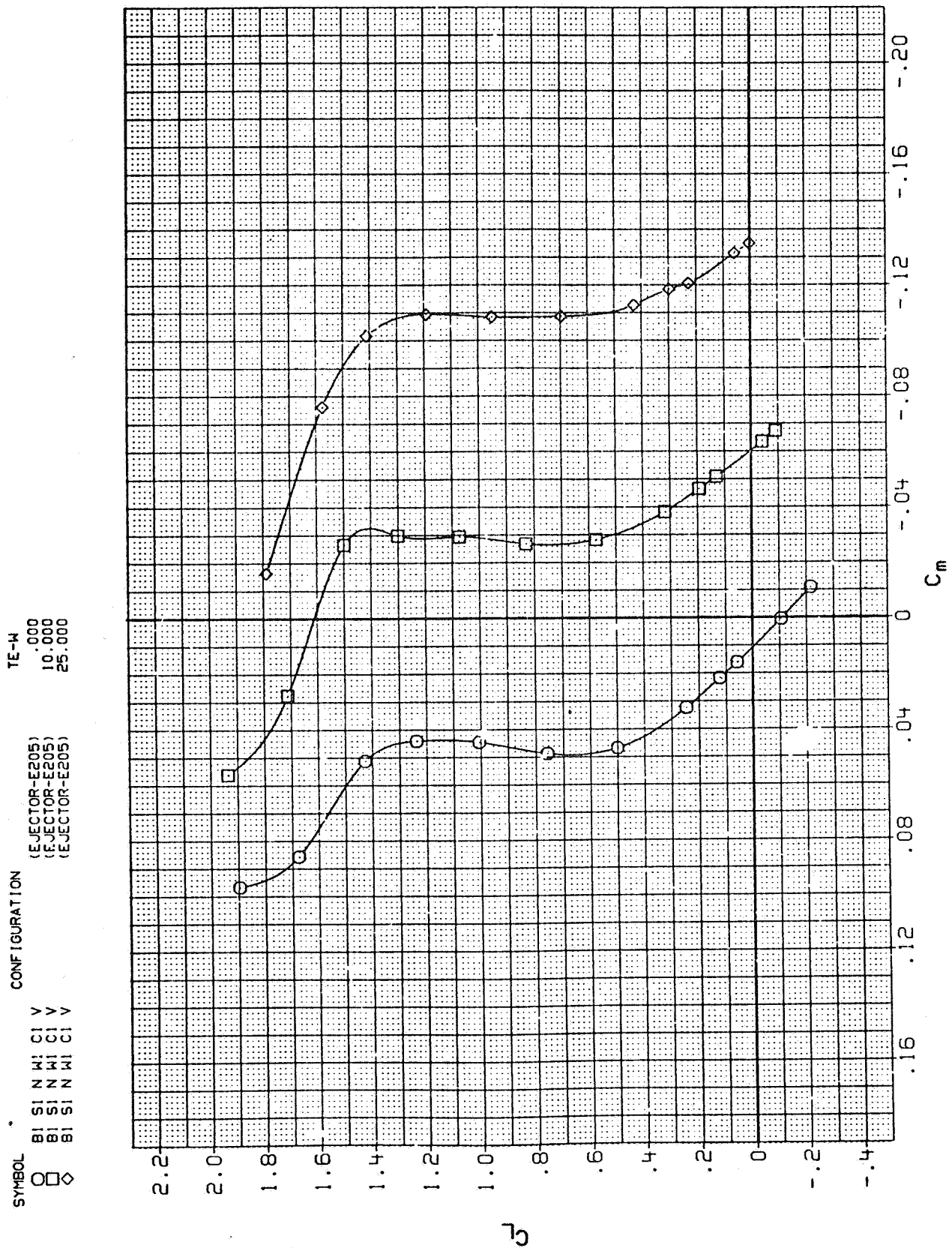


FIG. 38 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = 1.20





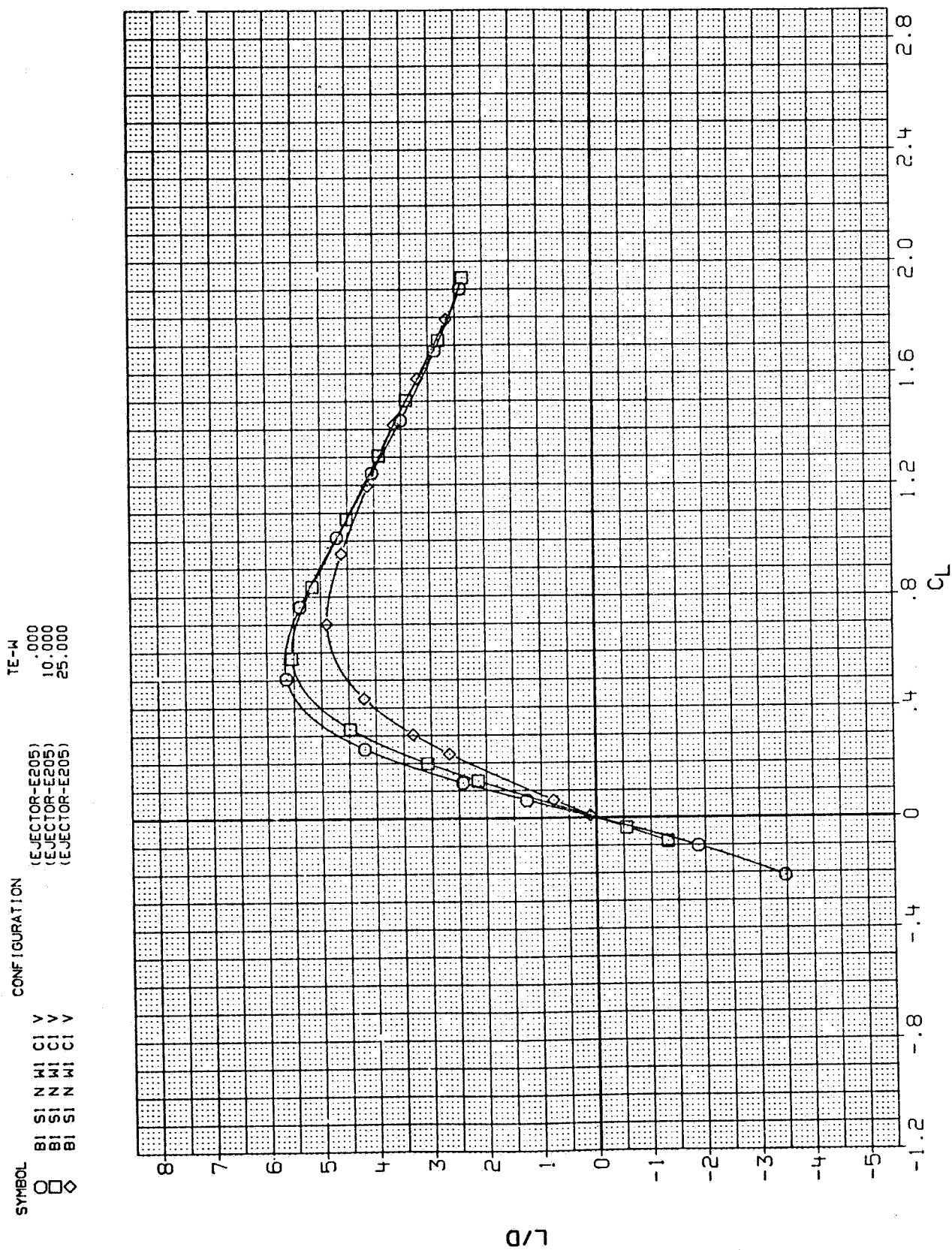


FIG. 38 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = 1.20

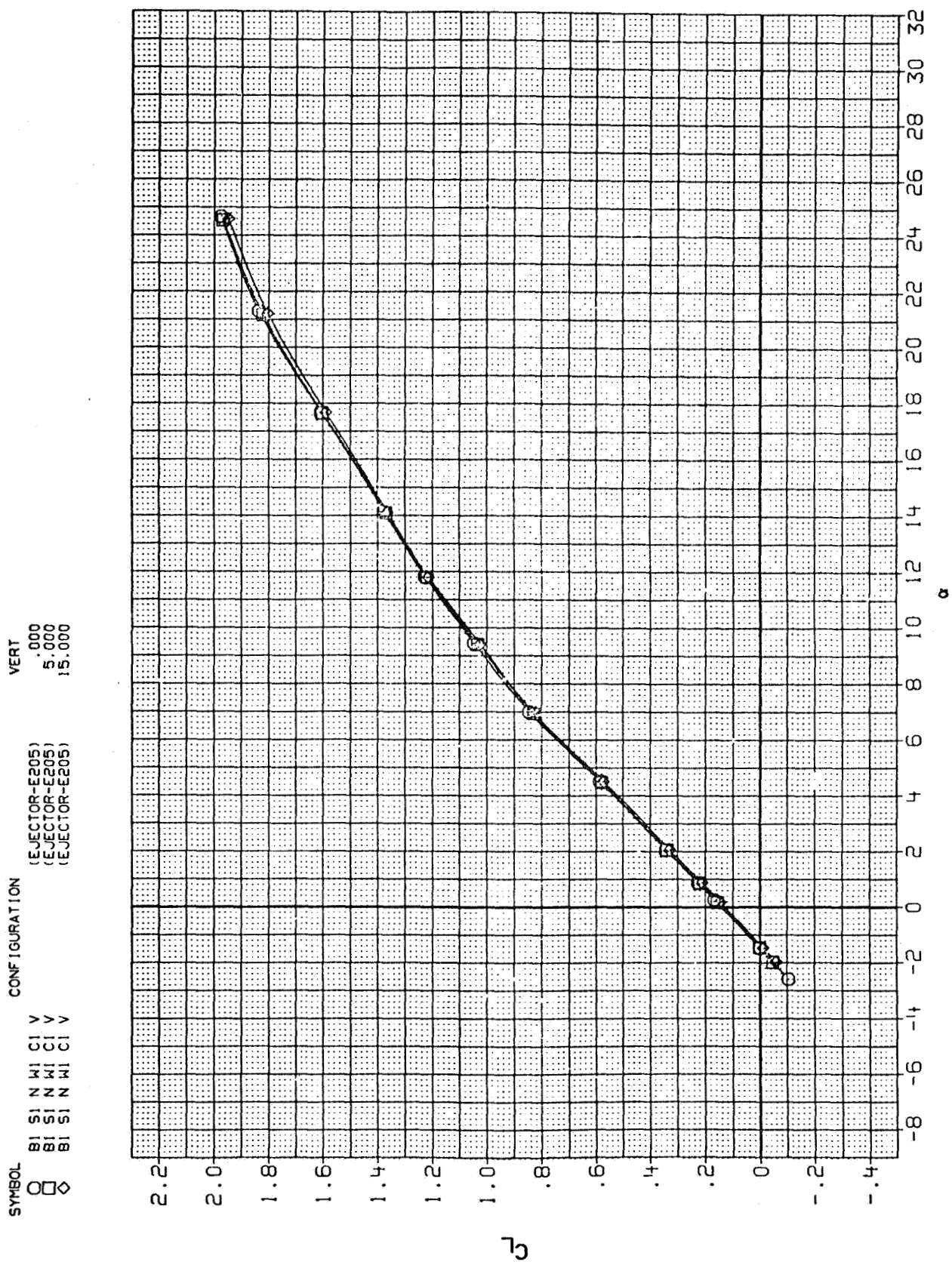


FIG. 39 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .90

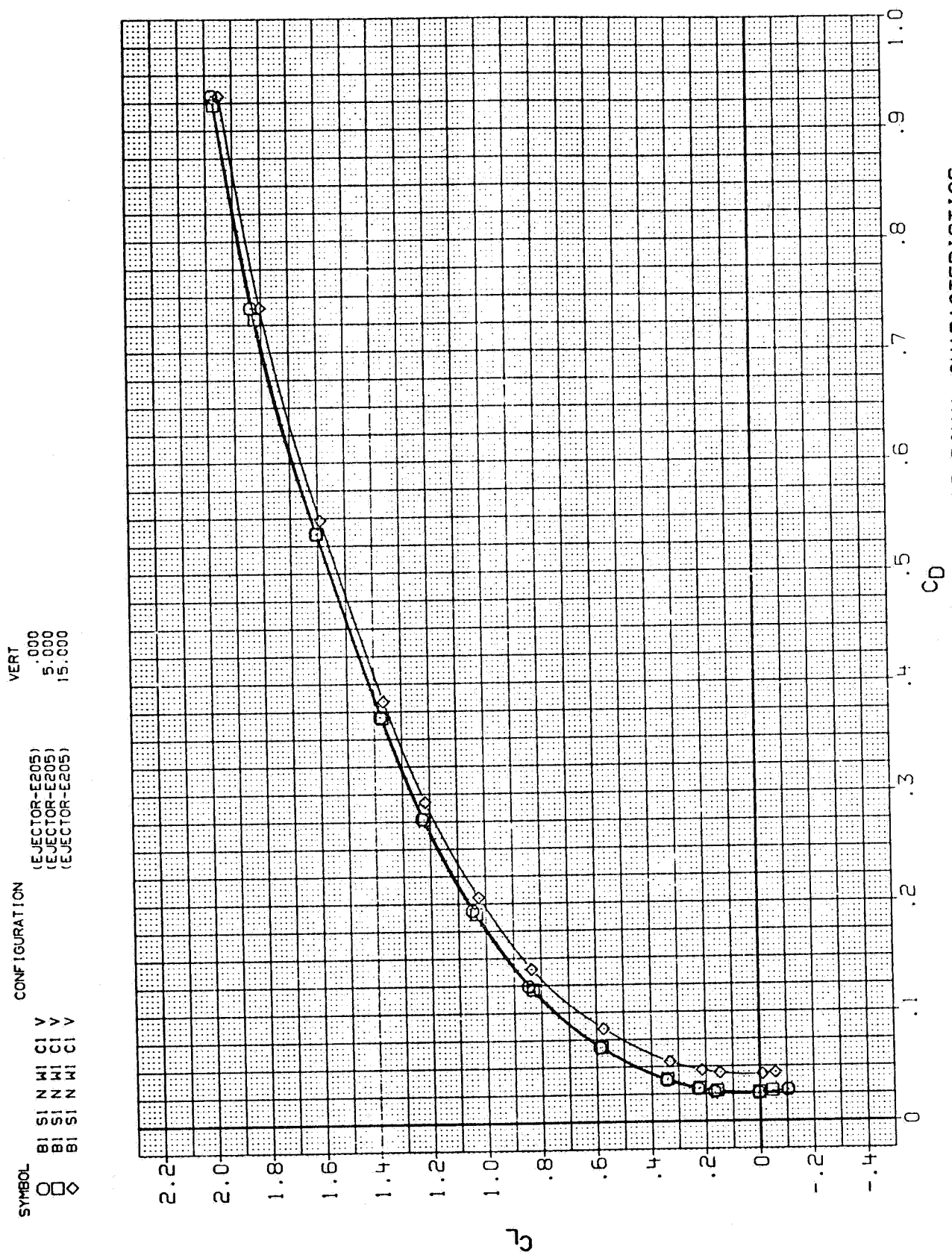


FIG. 39 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL	CONFIGURATION	VERT
○	BI SI N WI CI V (EJECTOR-E205)	.000
□	BI SI N WI CI V (EJECTOR-E205)	5.000
◇	BI SI N WI CI V (EJECTOR-E205)	15.000

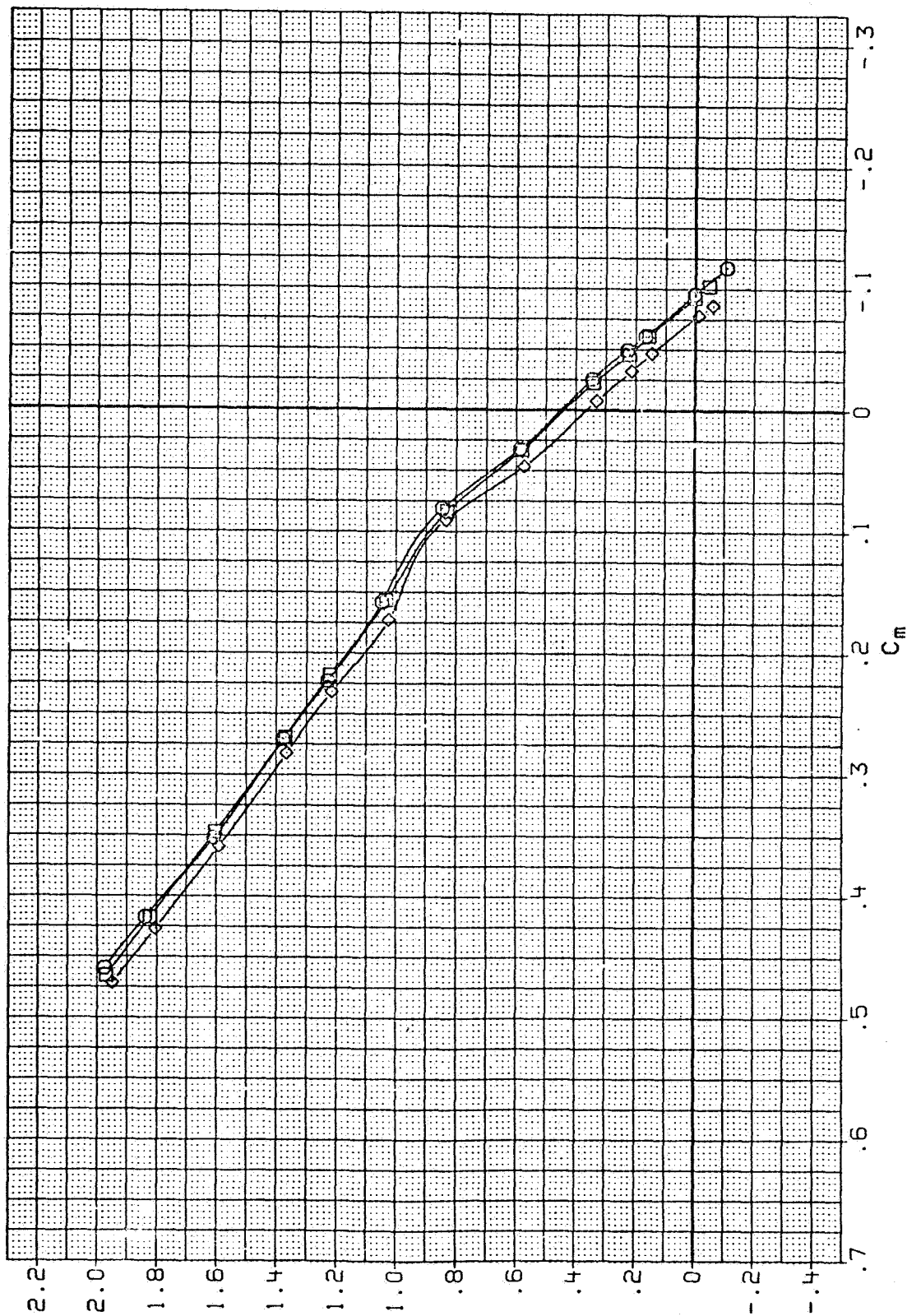


FIG. 39 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .90

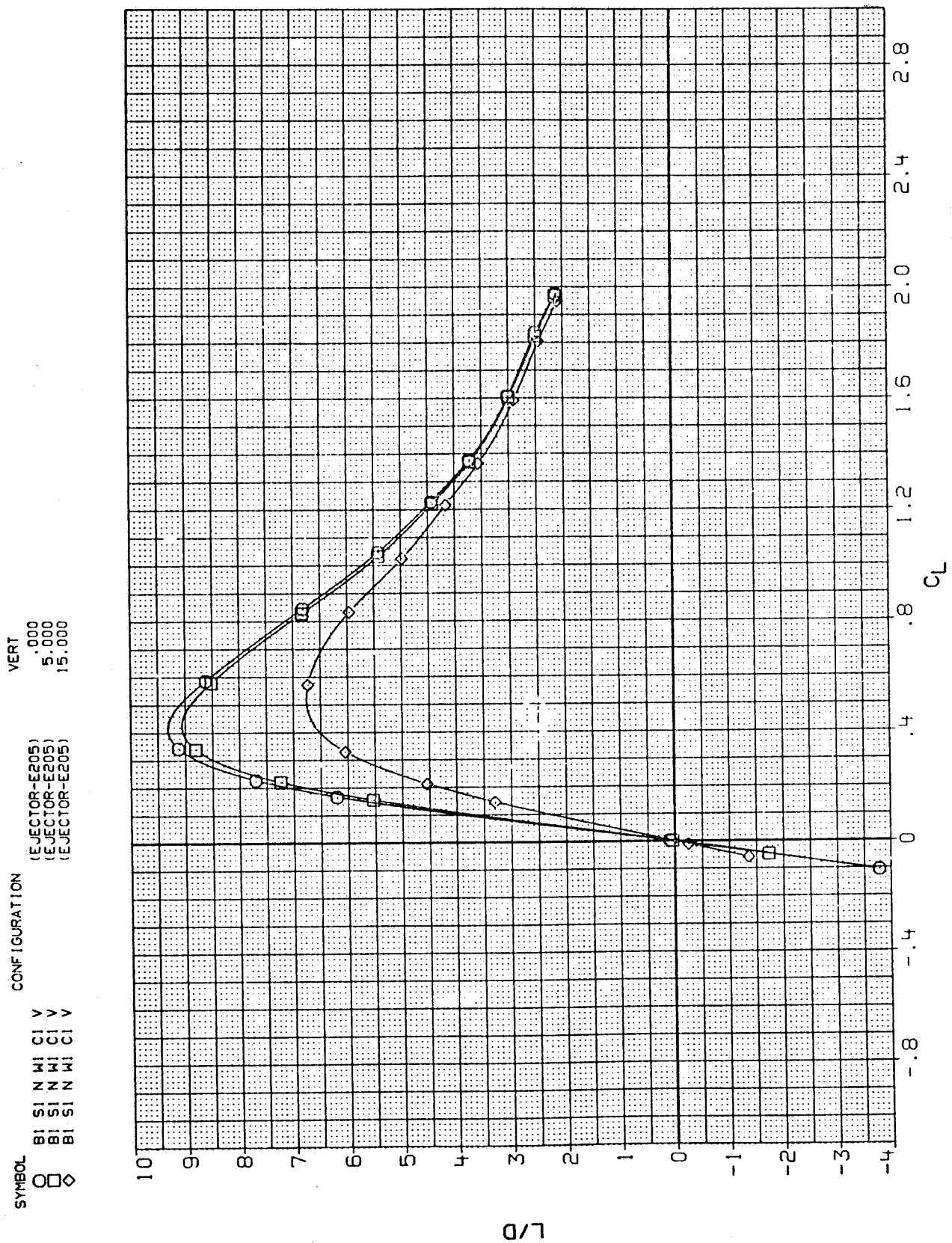


FIG. 39 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL CONFIGURATION VERT
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

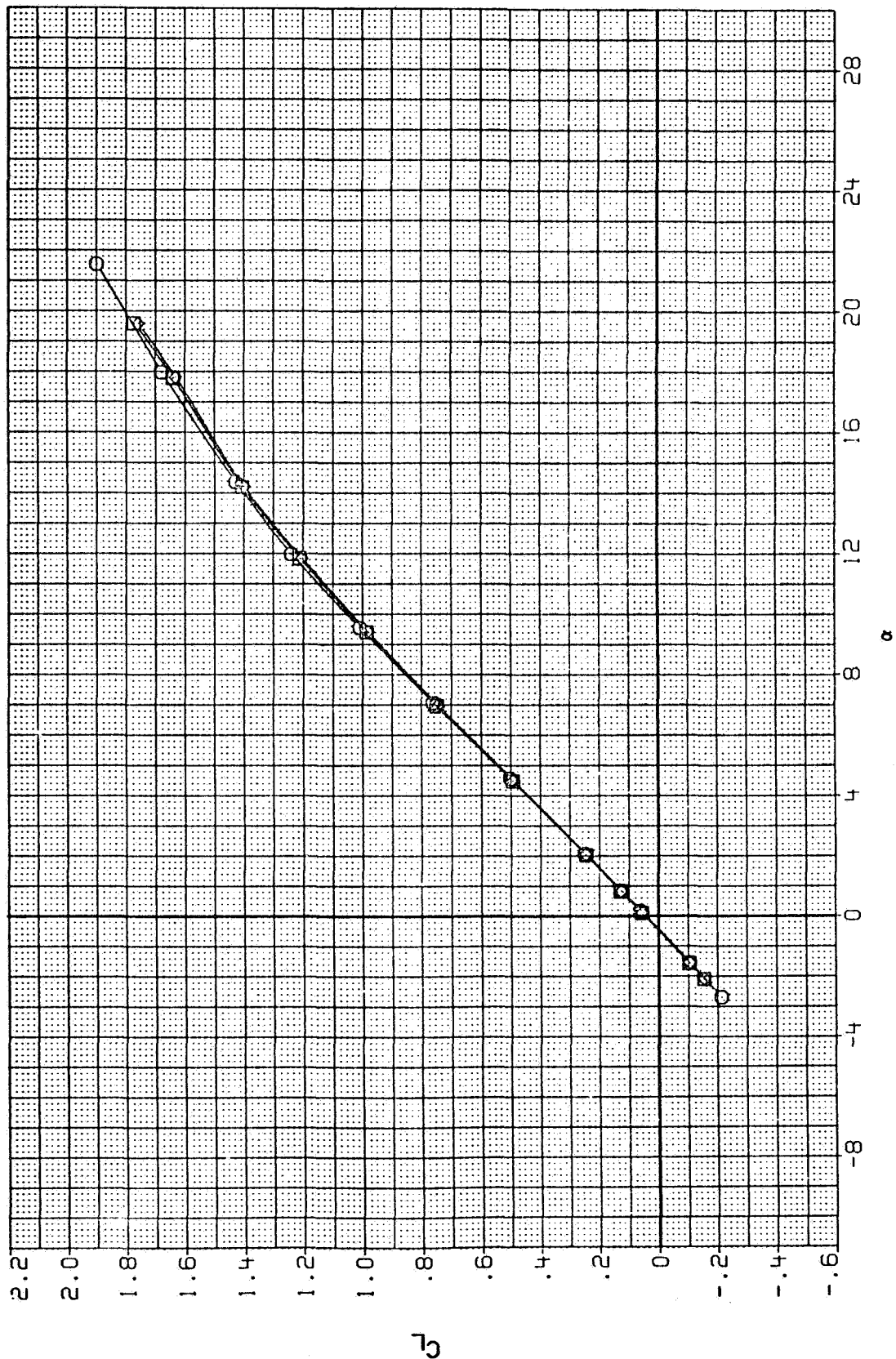


FIG. 40 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

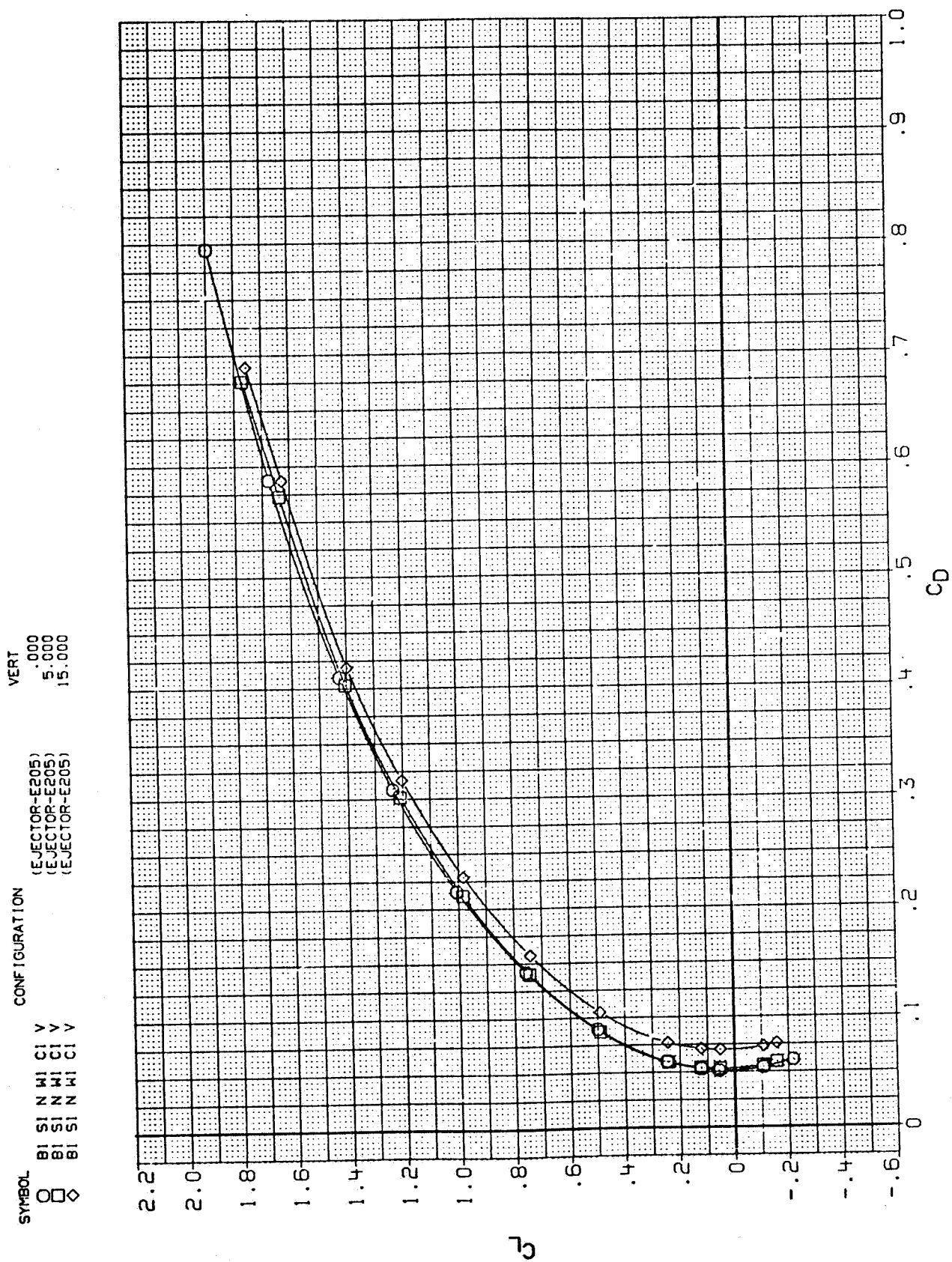


FIG. 40 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL	CONFIGURATION	VERT
○	(EJECTOR-E205)	.000
□	(EJECTOR-E205)	5.000
◇	(EJECTOR-E205)	15.000

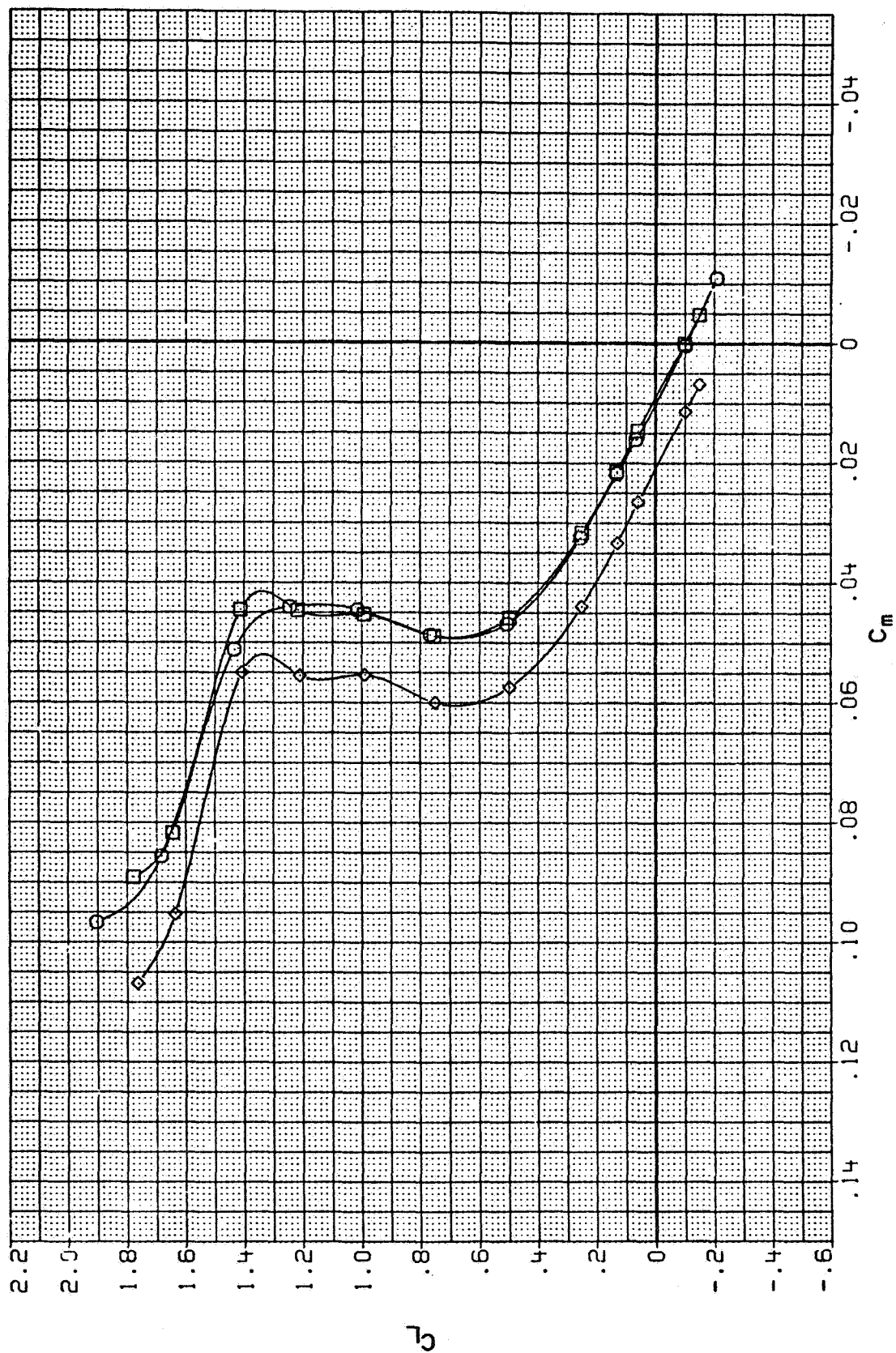


FIG. 40 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL	CONFIGURATION	VERT
BI SI N HI CI V	(EJECTOR-E205)	.000
BI SI N HI CI V	(EJECTOR-E205)	5.000
BI SI N HI CI V	(EJECTOR-E205)	15.000

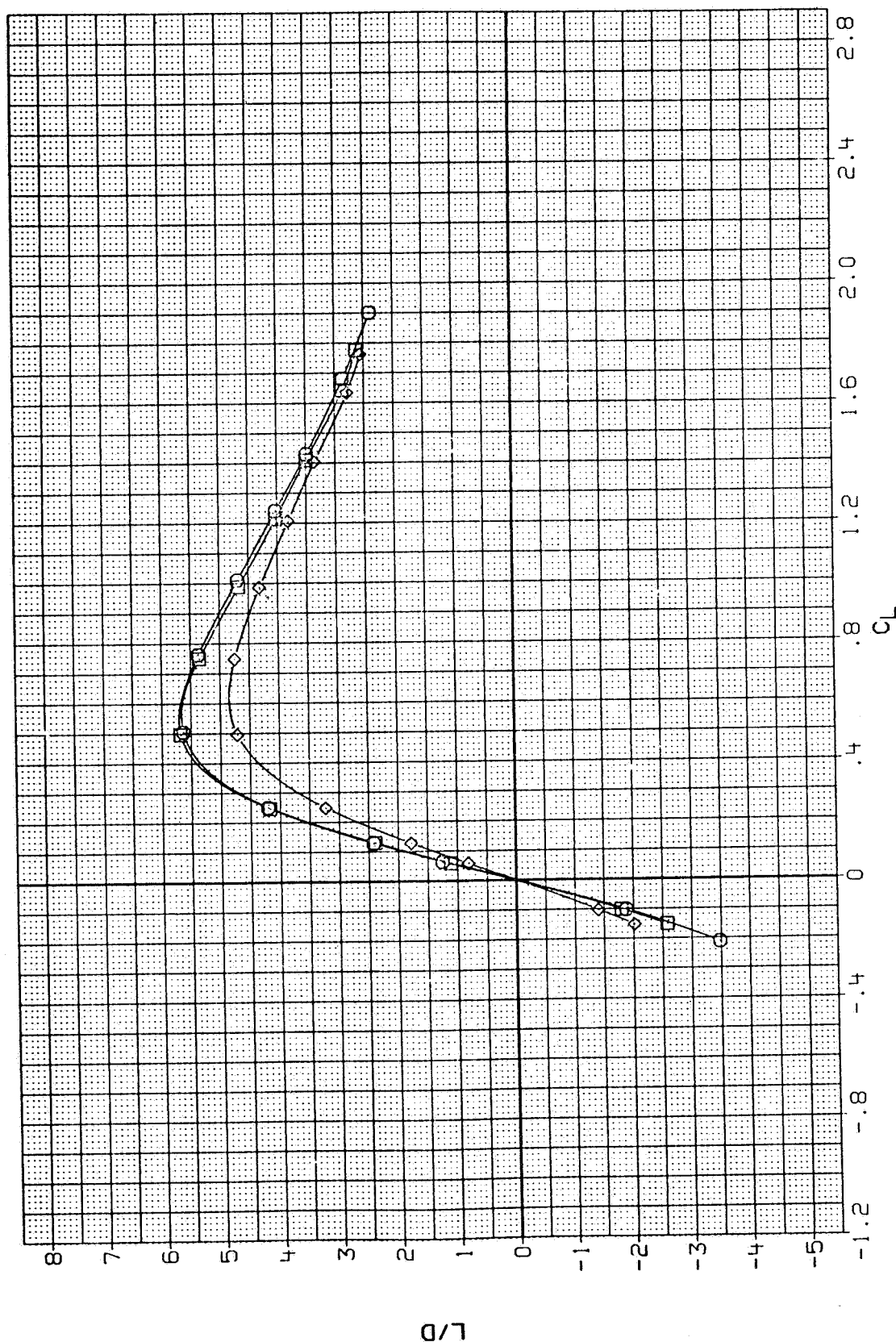


FIG. 40 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

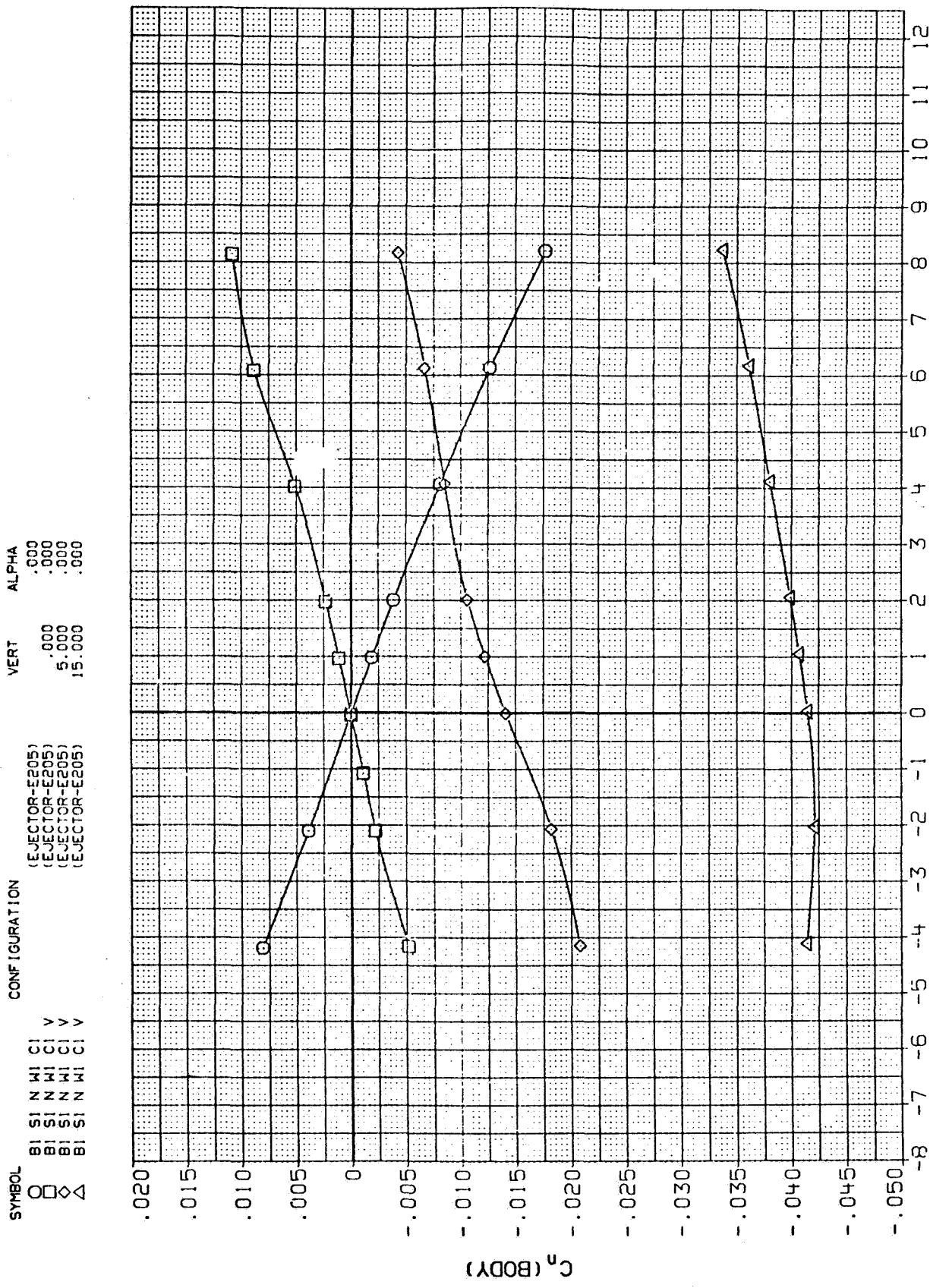


FIG. 41 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES
 MACH = .90

SYMBOL CONFIGURATION VERT ALPHA:
 ○ (EJECTOR-E205) .000 .000
 ◇ (EJECTOR-E205) .000 .000
 △ (EJECTOR-E205) .000 .000
 △ (EJECTOR-E205) 5.000 .000
 △ (EJECTOR-E205) 15.000 .000

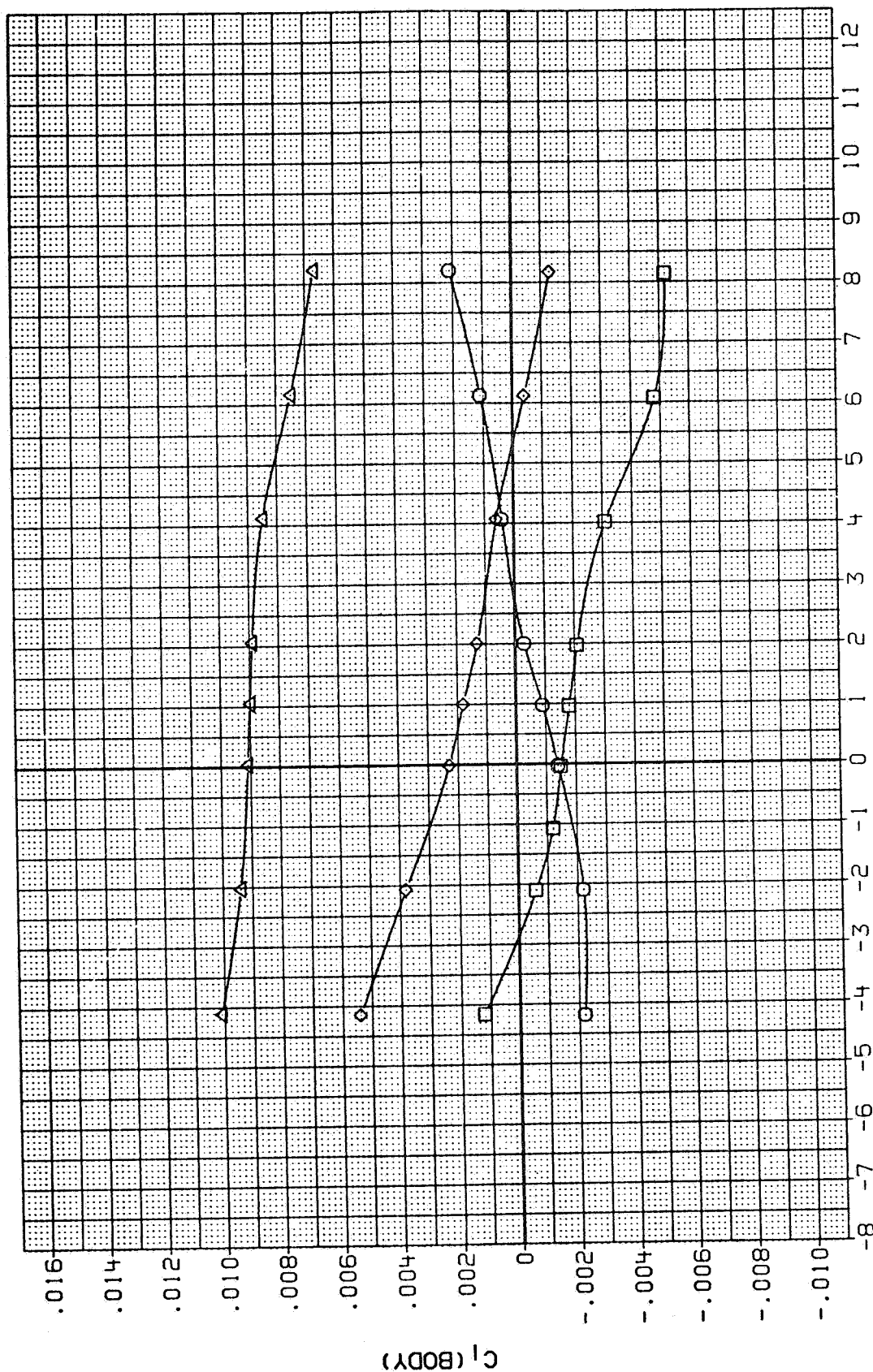
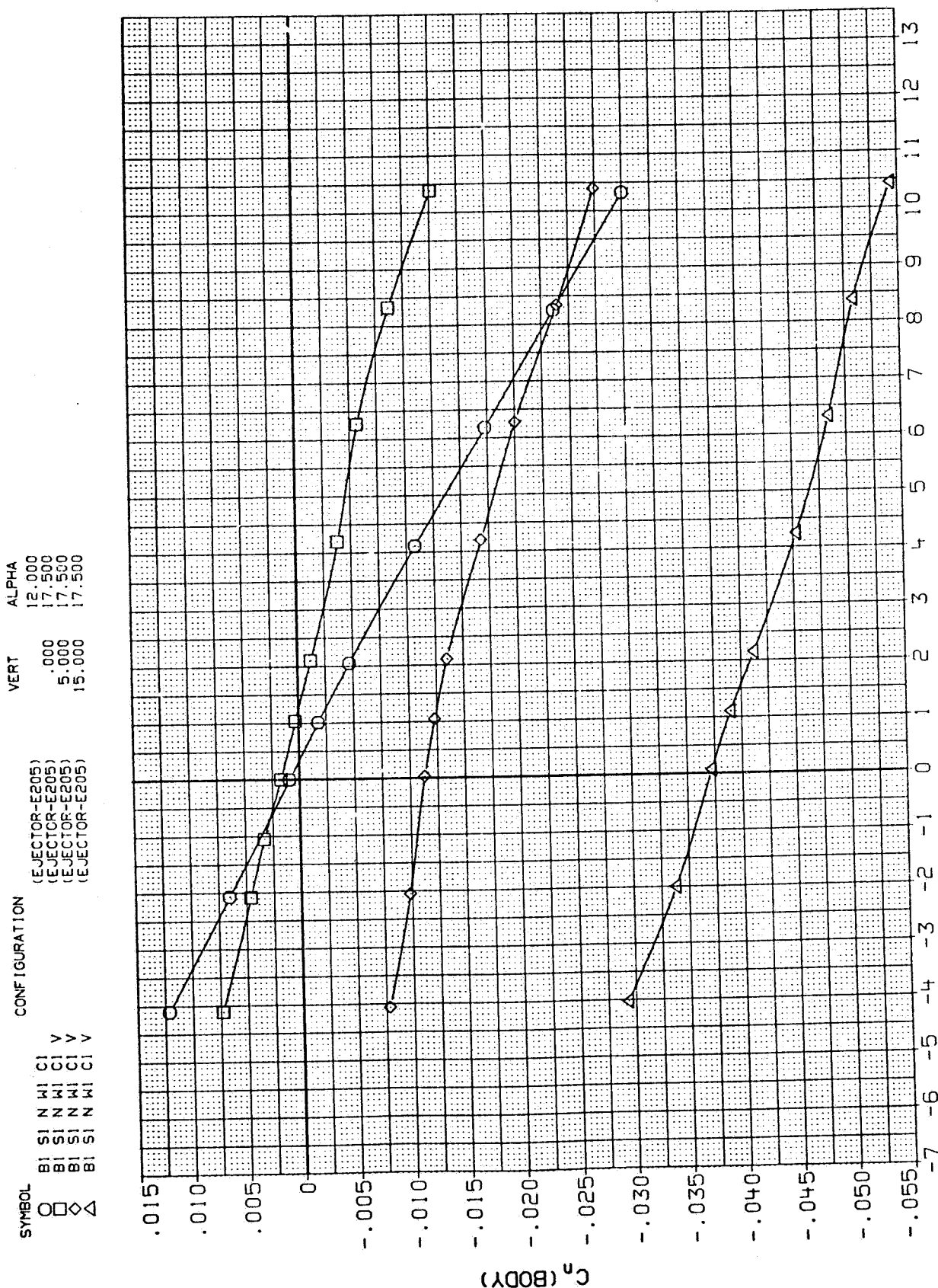


FIG. 41 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES
 MACH = .90



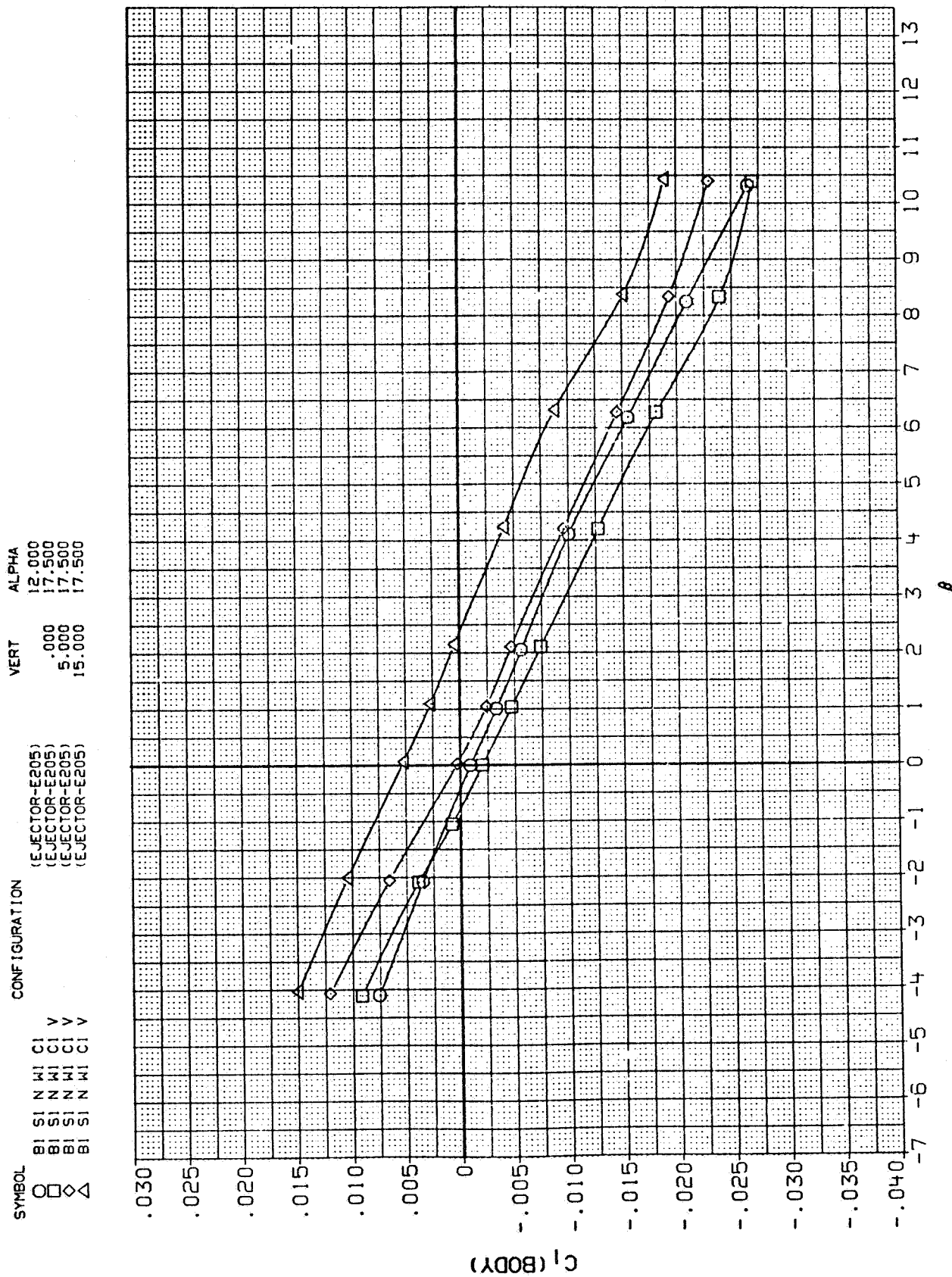


FIG. 41 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES
 MACH = .90

SYMBOL	CONFIGURATION	VERT	ALPHA
○	BI SI N MI CI V	.000	12.000
□	BI SI N MI CI V	5.000	17.500
△	BI SI N MI CI V	15.000	17.500

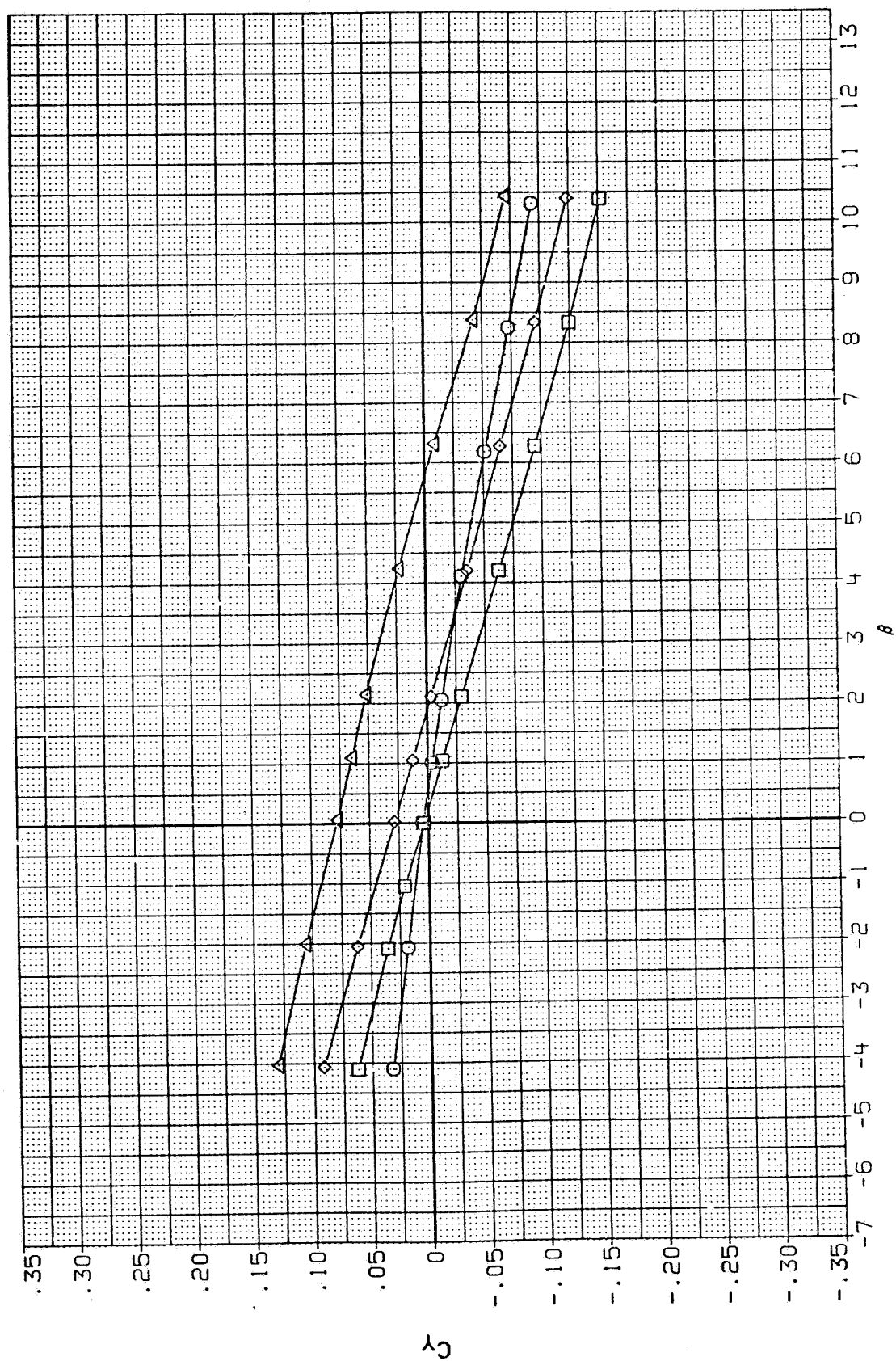


FIG. 41 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES
 MACH = .90

SYMBOL	CONFIGURATION				VERT	ALPHA
	BI	SI	N	WI		
□	SI	N	WI	CI	.000	.000
○	SI	N	WI	CI	.000	.000
◇	SI	N	WI	CI	.000	.000
△	SI	N	WI	CI	.000	.000

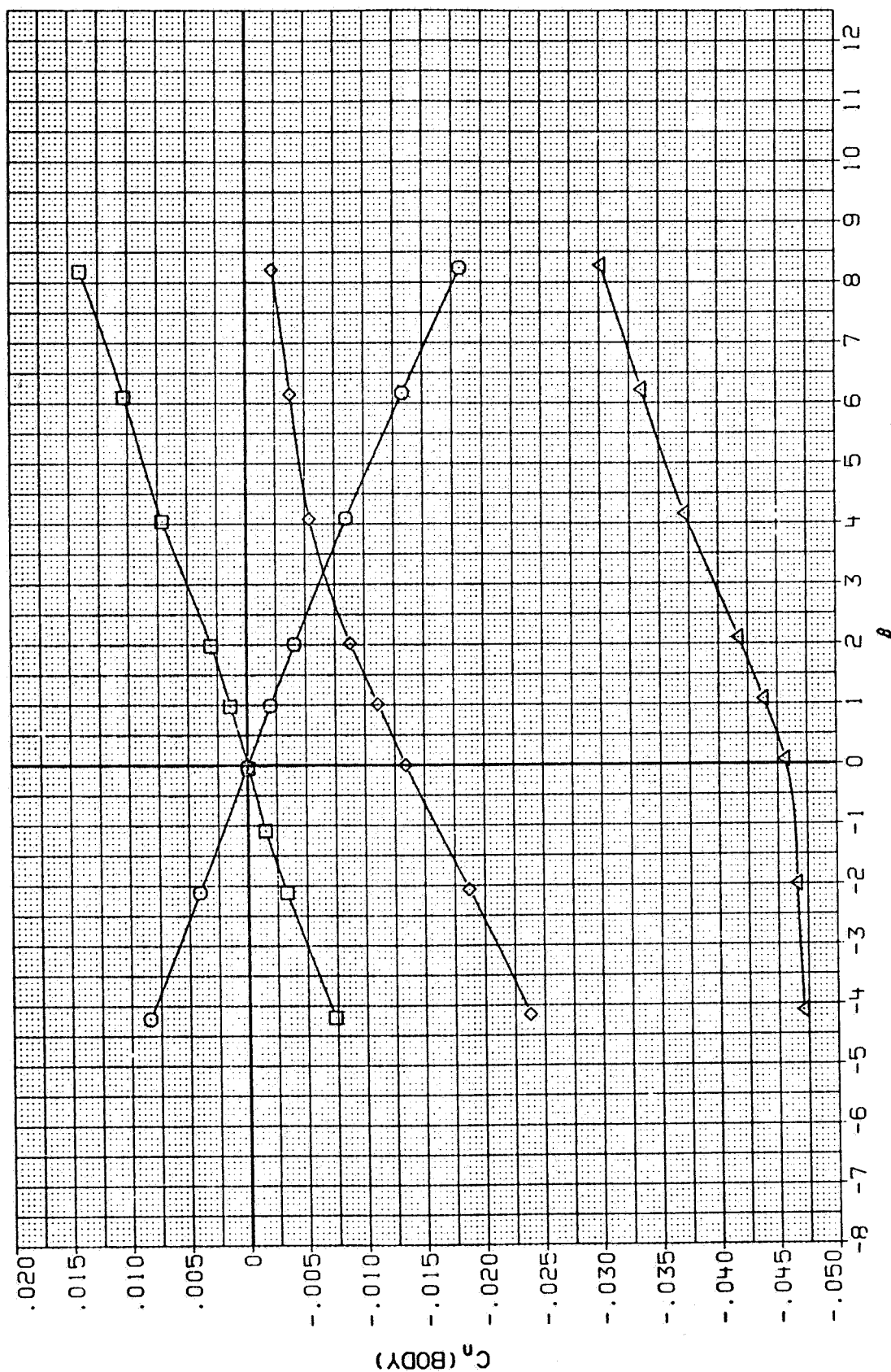


FIG. 42 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES
 MACH = 1.20

SYMBOL	CONFIGURATION	VERT	ALPHA
□	B1 S1 N W1 C1 V	.000	.000
○	B1 S1 N W1 C1 V	.000	.000
◇	B1 S1 N W1 C1 V	5.000	.000
△	B1 S1 N W1 C1 V	15.000	.000

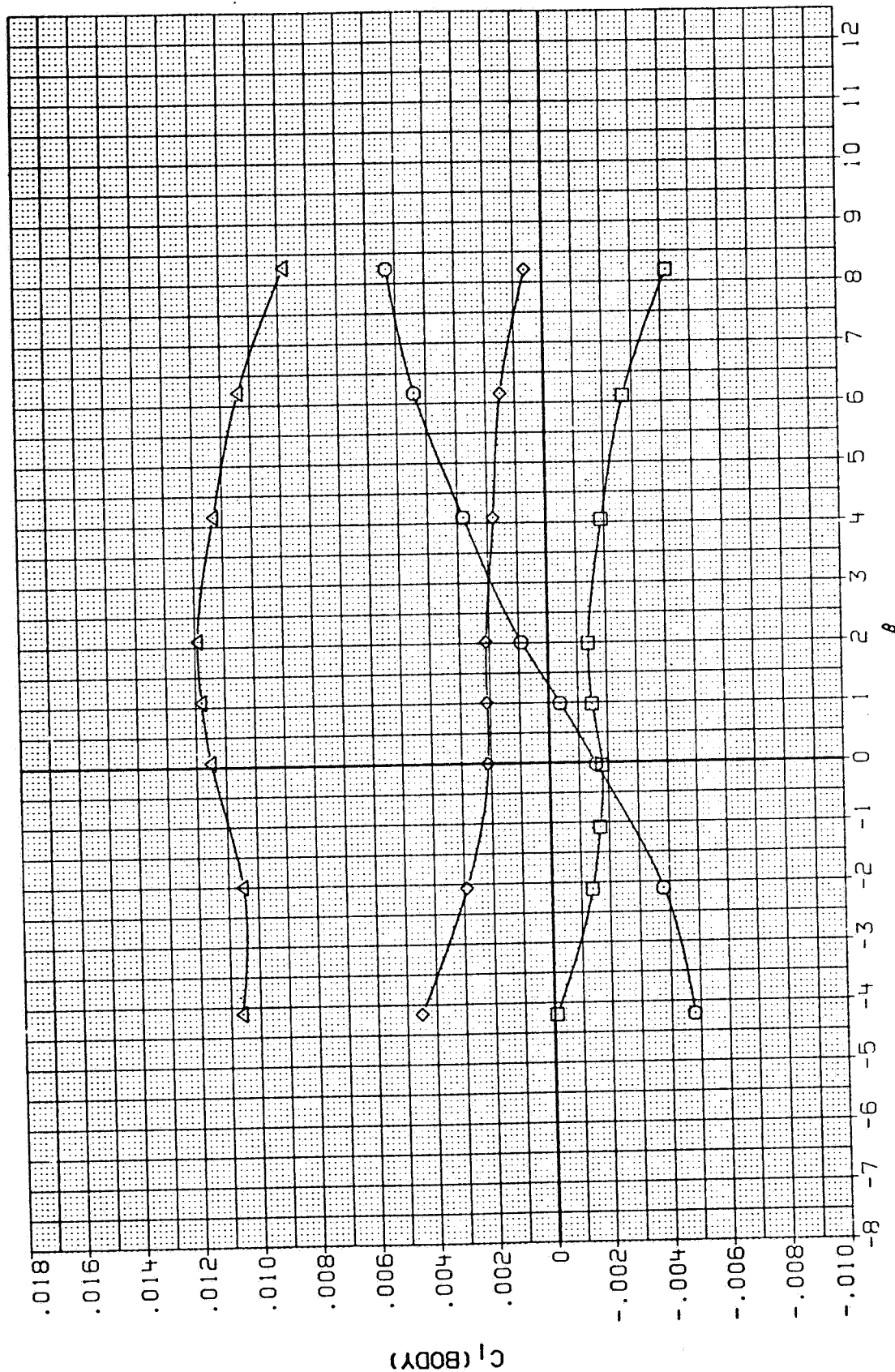


FIG. 42 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES
 MACH = 1.20

SYMBOL	CONFIGURATION	VERT	ALPHA
○	(EJECTOR-E205)	.000	.000
◇	(EJECTOR-E205)	.000	.000
△	(EJECTOR-E205)	.000	.000
	(EJECTOR-E205)	5.000	.000
	(EJECTOR-E205)	15.000	.000

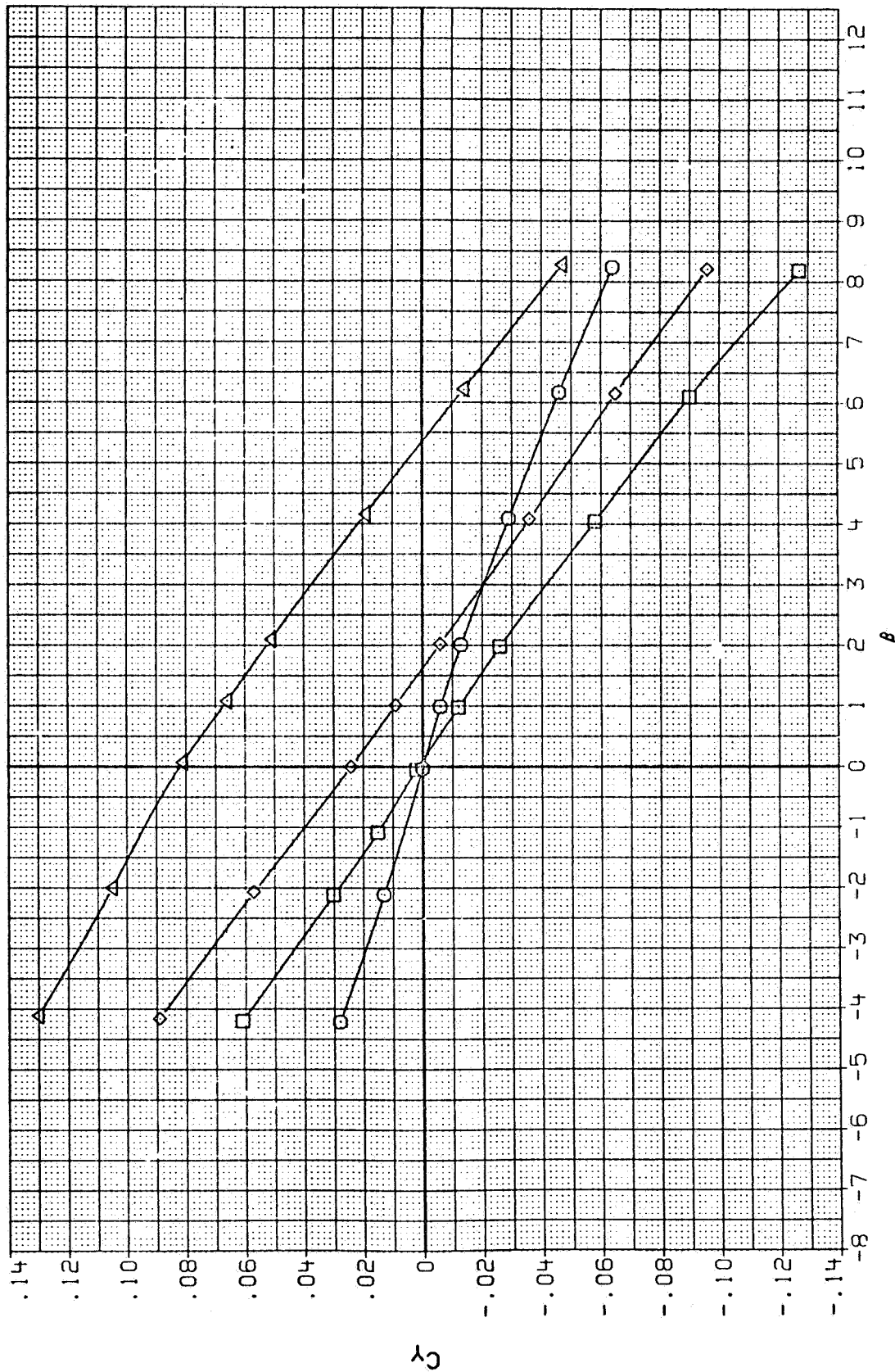


FIG. 42 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES
 MACH = 1.20

SYMBOL	CONFIGURATION	VERT	ALPHA
□	(EJECTOR-E205)	12.000	12.000
◇	(EJECTOR-E205)	.000	15.000
△	(EJECTOR-E205)	5.000	12.000
	(EJECTOR-E205)	15.000	12.000

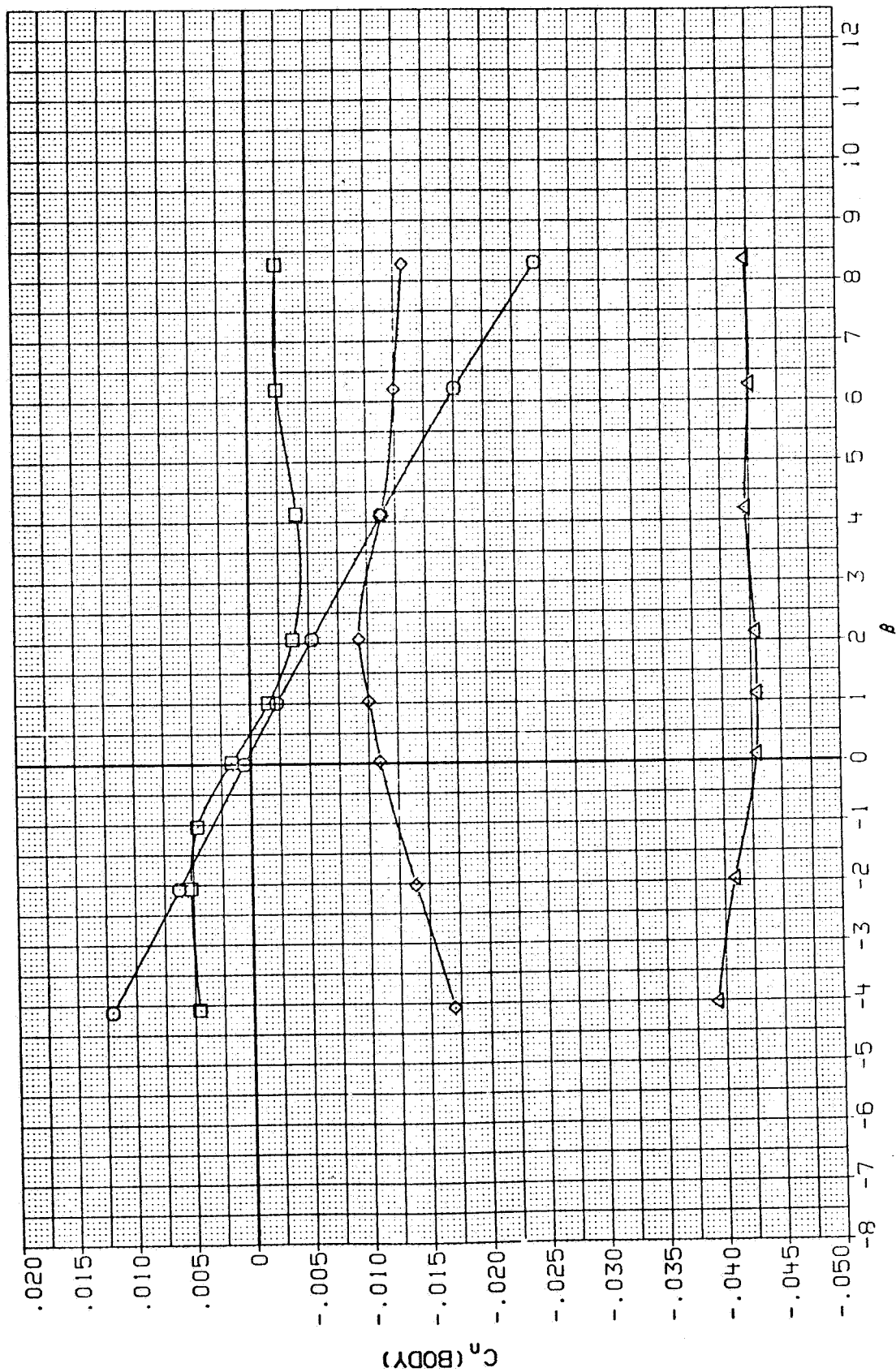


FIG. 42 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 10 DEGREES

MACH = 1.20

SYMBOL	CONFIGURATION	VERT	ALPHA
○	(EJECTOR-E205)	12.000	12.000
□	(EJECTOR-E205)	.000	15.000
◇	(EJECTOR-E205)	5.000	12.000
△	(EJECTOR-E205)	15.000	12.000

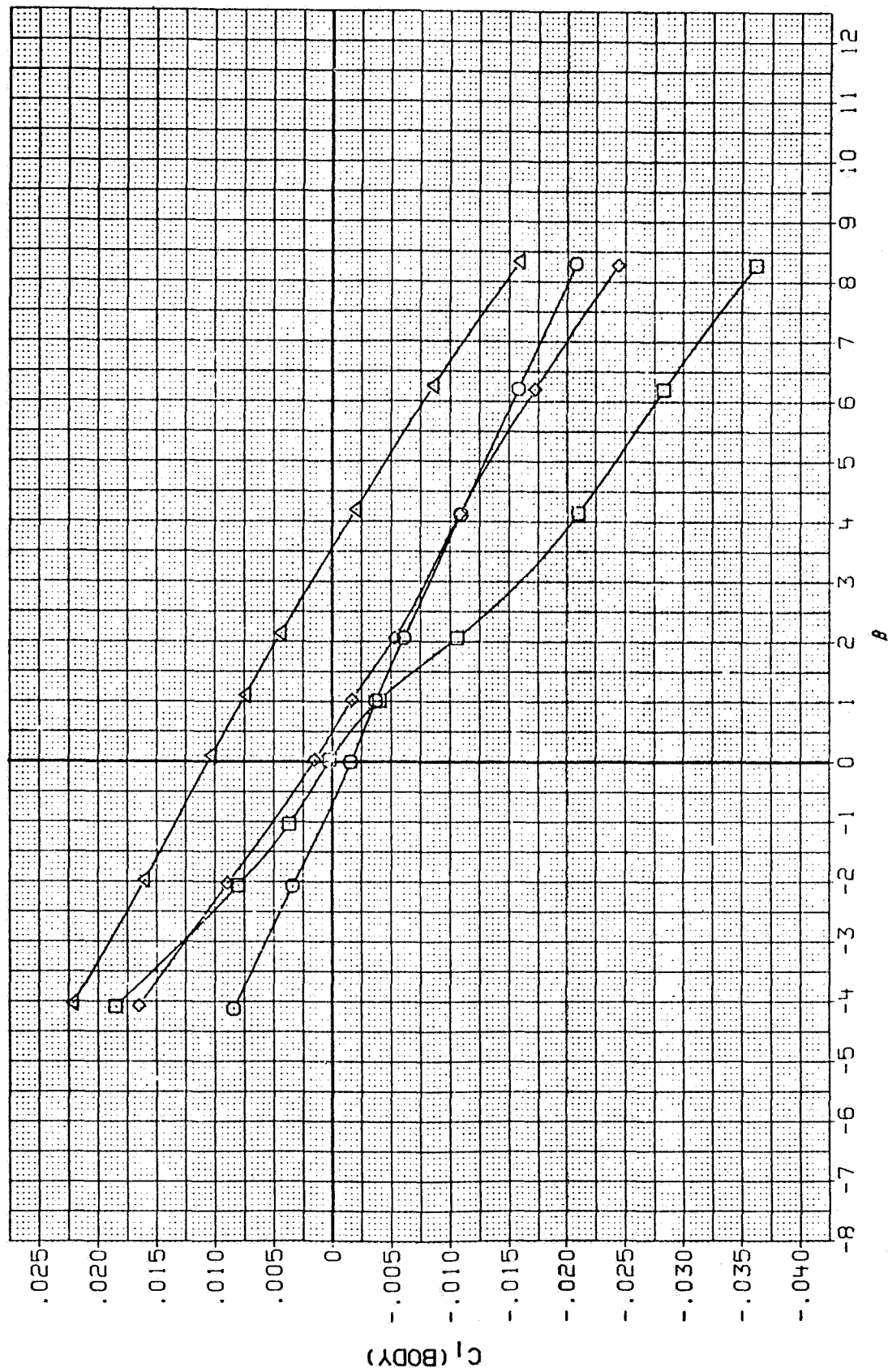


FIG. 42 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 $\alpha = 10^\circ$
MACH = 1.20

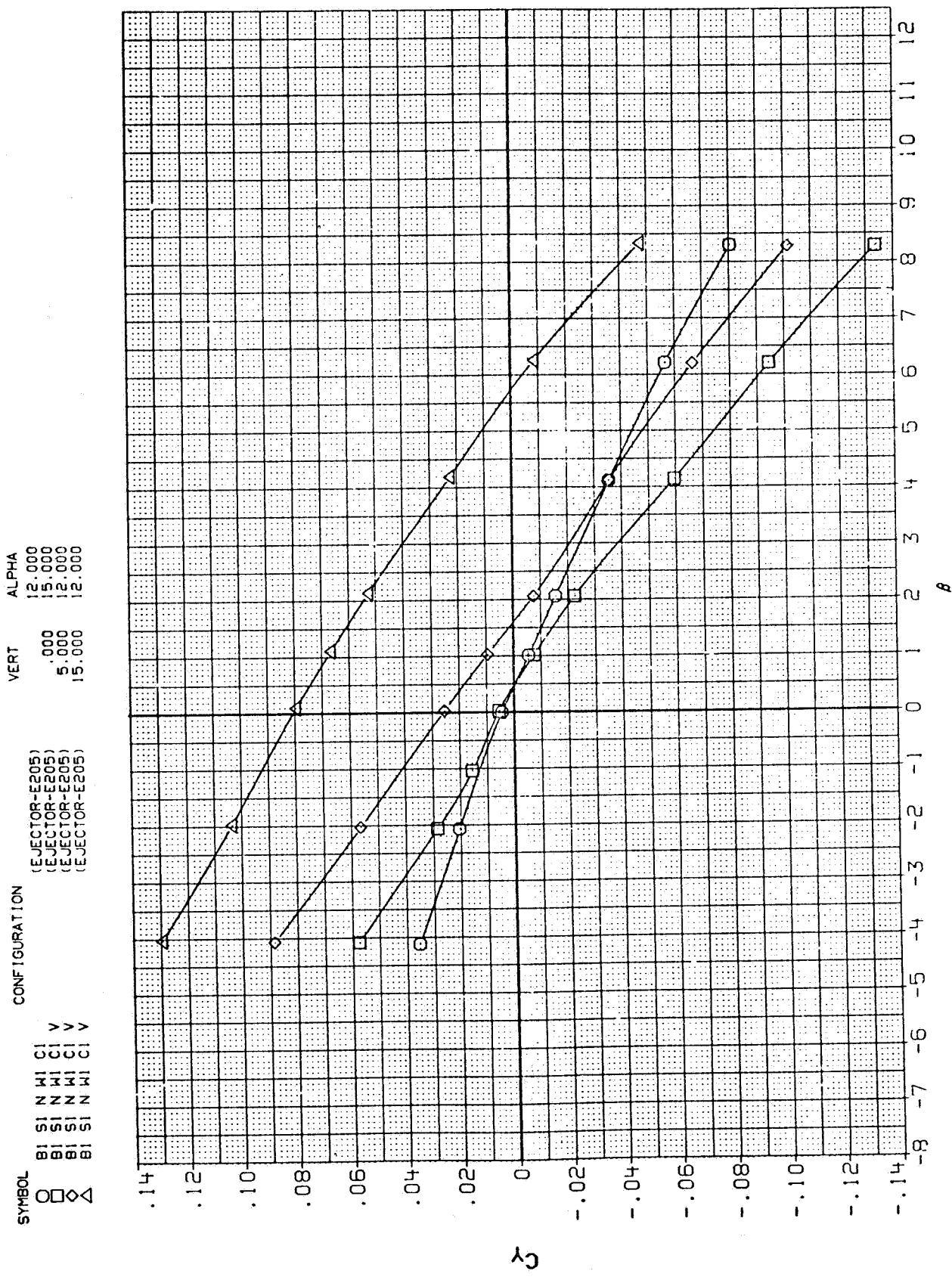


FIG. 42 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES
 MACH = 1.20

SYMBOL CONFIGURATION

○ B) SI N W1 C1 V (EJECTOR-E205)

□ B) SI N W1 C2 V (EJECTOR-E205)

◇ B) SI N W1 C3 V (EJECTOR-E205)

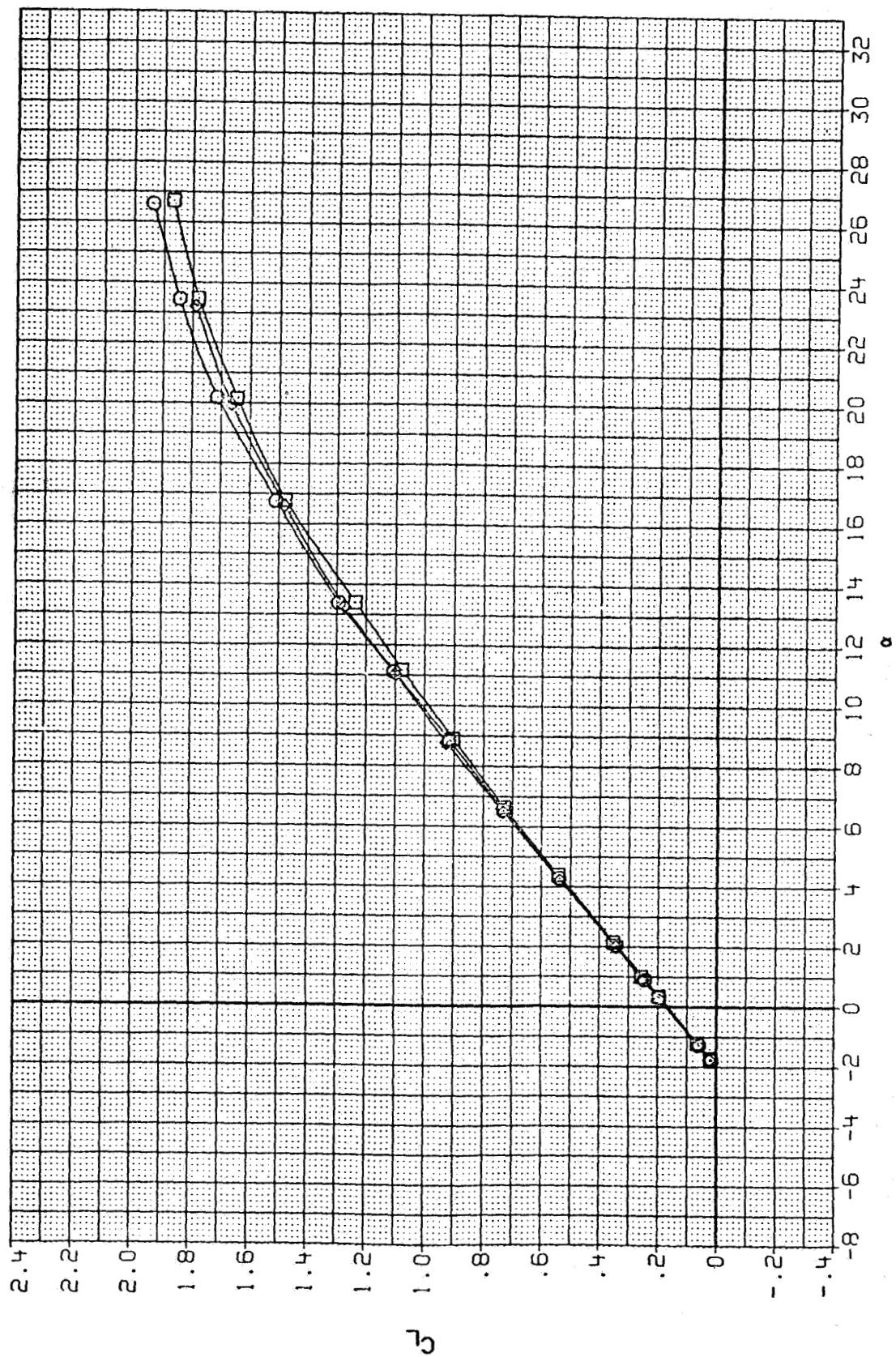


FIG. 43 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE SI
MACH = .60

SYMBOL CONFIGURATION
 ○ BI SI N WI C1 V (EJECTOR-E205)
 □ BI SI N WI C2 V (EJECTOR-E205)
 ◇ BI SI N WI C3 V (EJECTOR-E205)

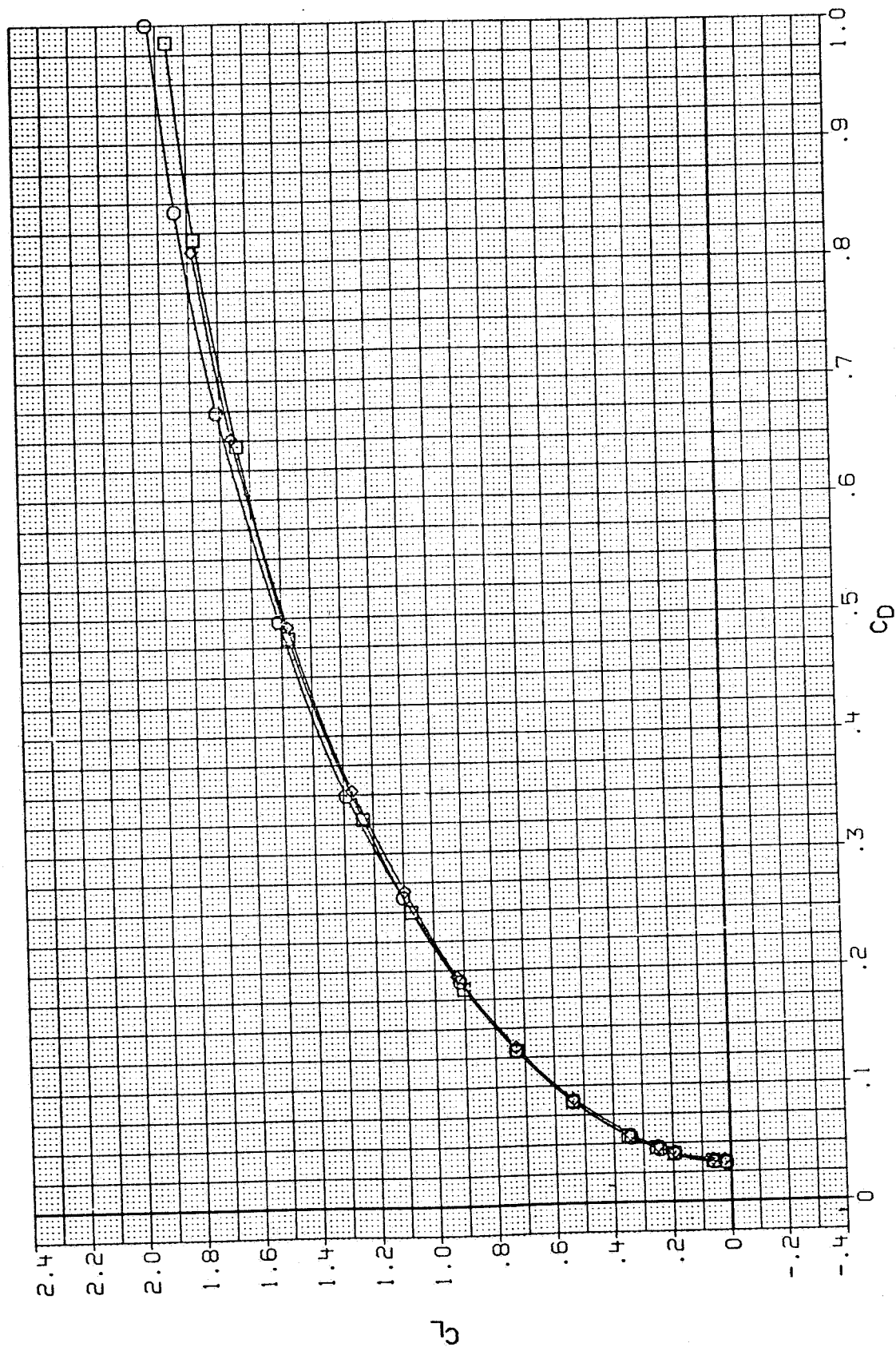


FIG. 43 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S1
 MACH = .60

SYMBOL CONFIGURATION
 ○ BI SI N WI C1 V (EJECTOR-E205)
 □ BI SI N WI C2 V (EJECTOR-E205)
 ◇ BI SI N WI C3 V (EJECTOR-E205)

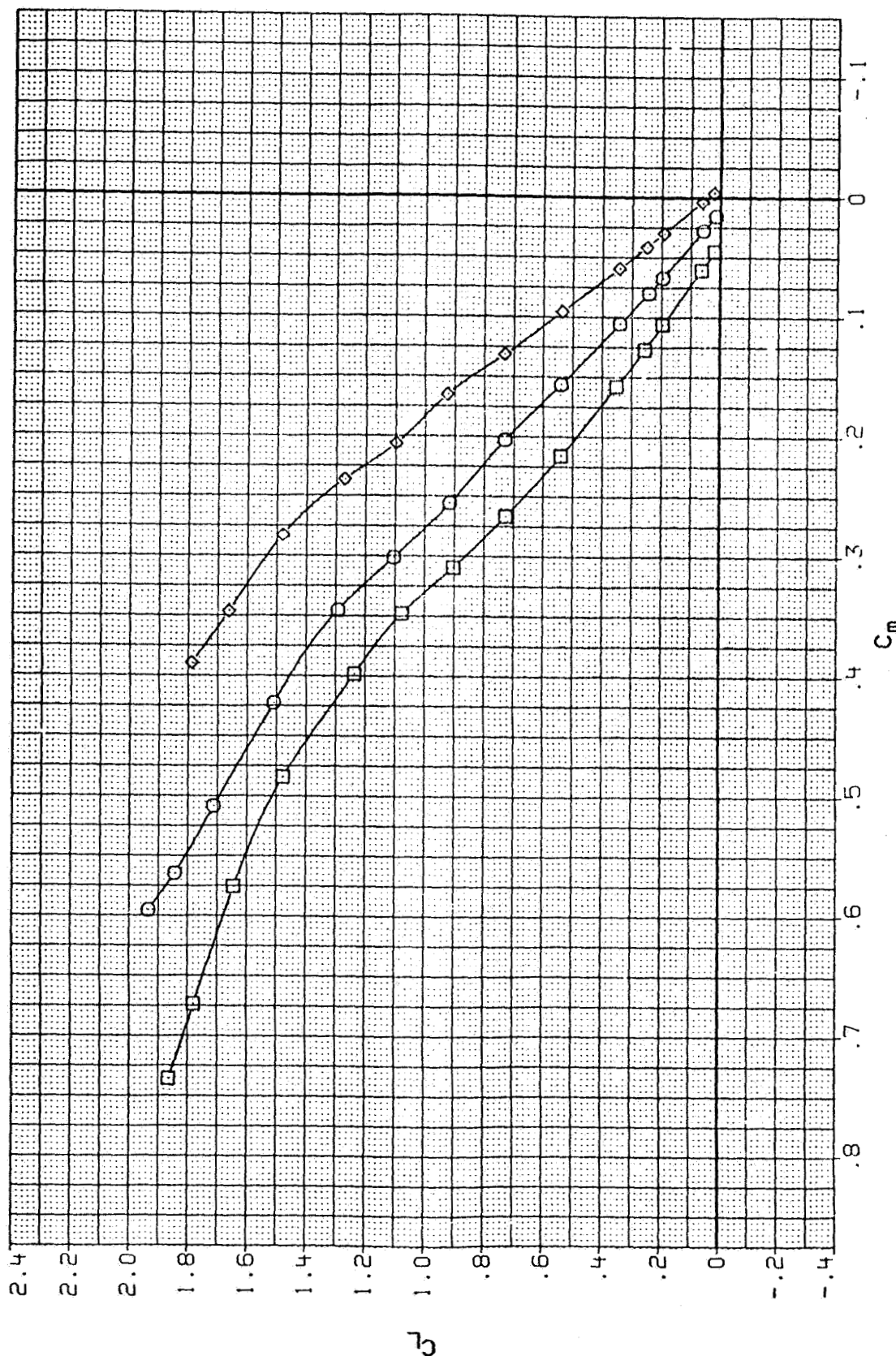


FIG. 43 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S1
 MACH = .60

SYMBOL CONFIGURATION
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

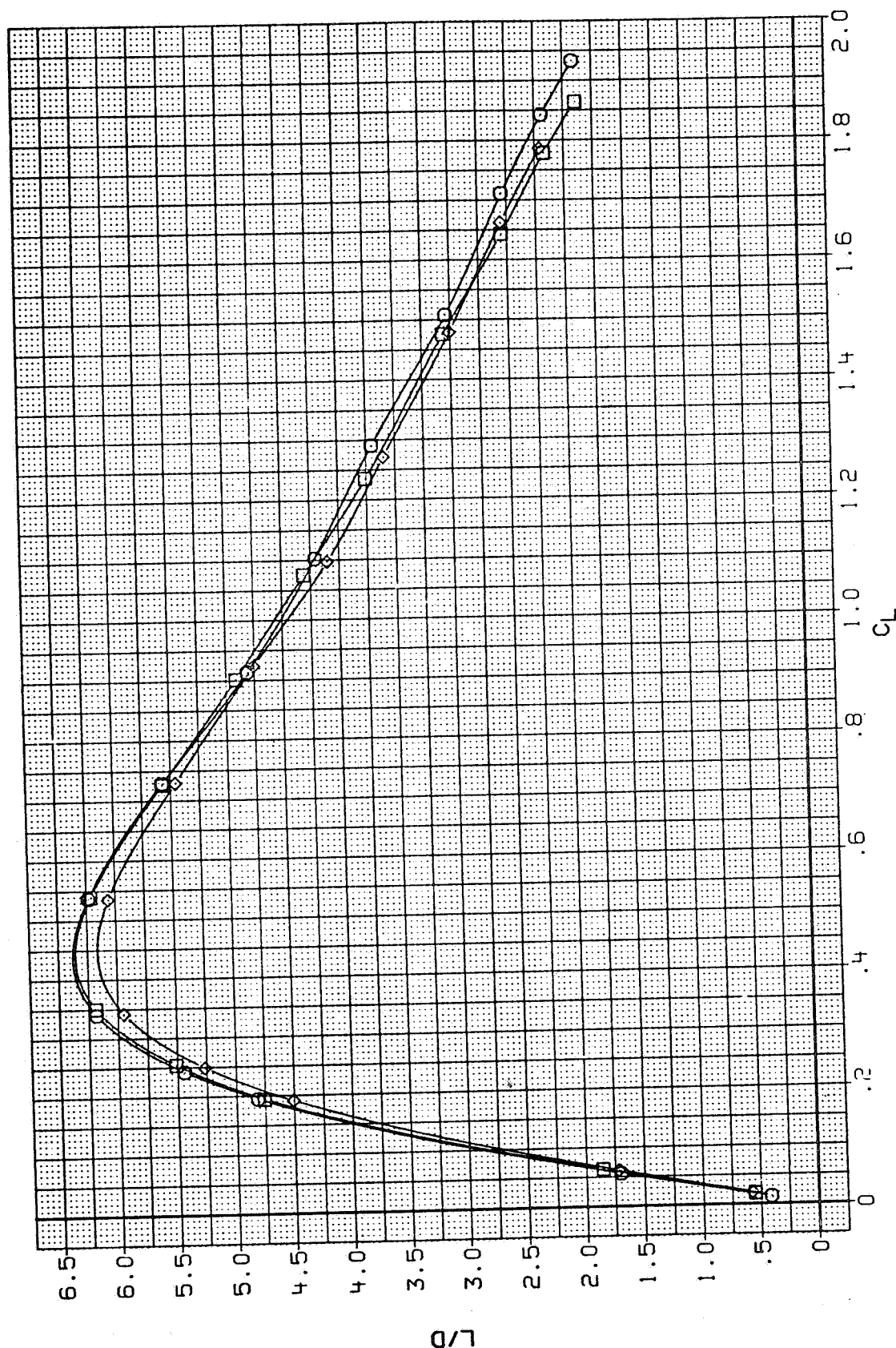


FIG. 43 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S1

SYMBOL CONFIGURATION
 ○ B1 S1 N W1 C1 V (EJECTOR-E205)
 □ B1 S1 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S1 N W1 C3 V (EJECTOR-E205)

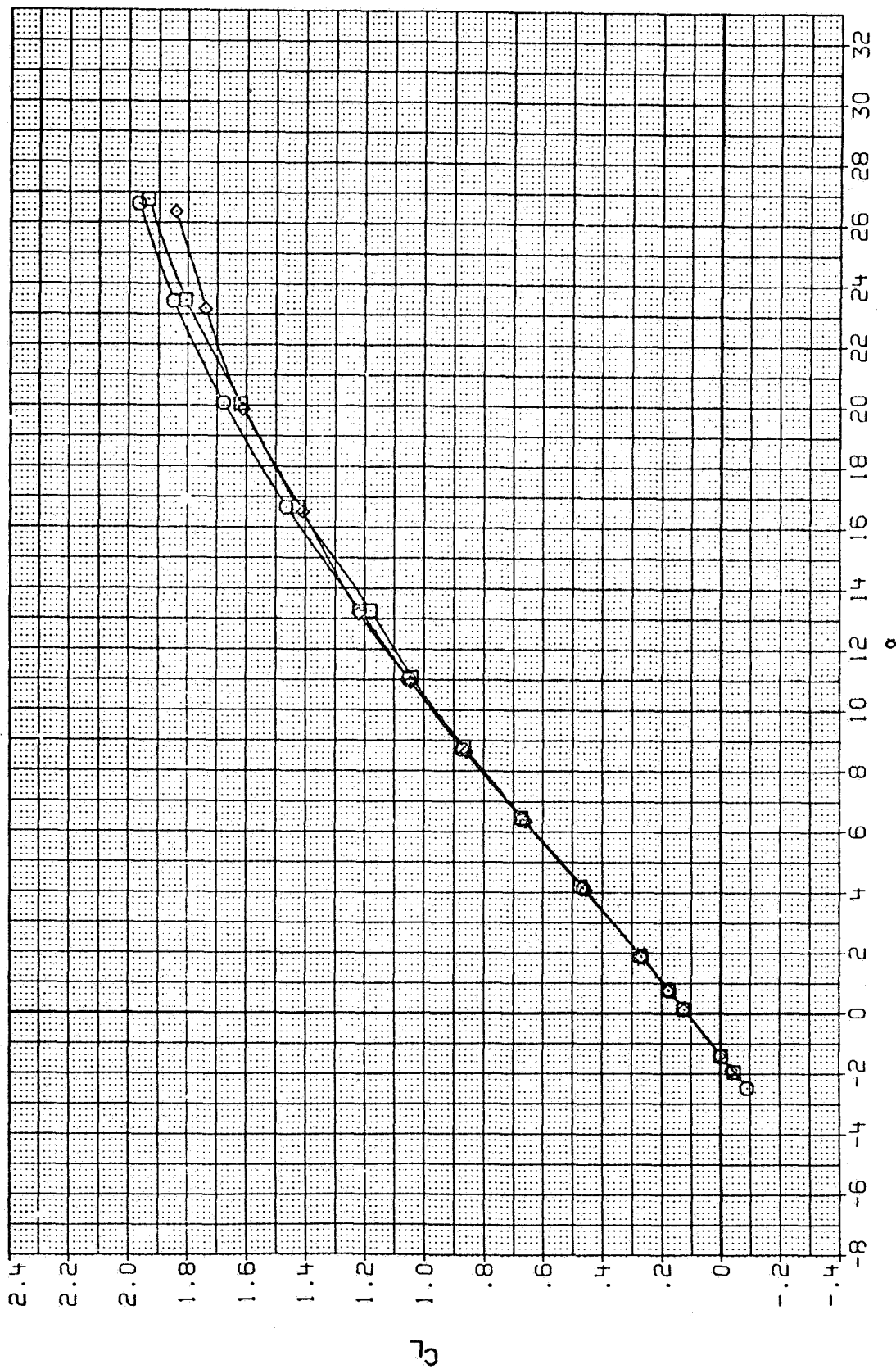


FIG. 44 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S1
 MACH = .60

SYMBOL CONFIGURATION

○ B1 S1 N W1 C1 V
 □ B1 S1 N W1 C2 V
 ◇ B1 S1 N W1 C3 V

(EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

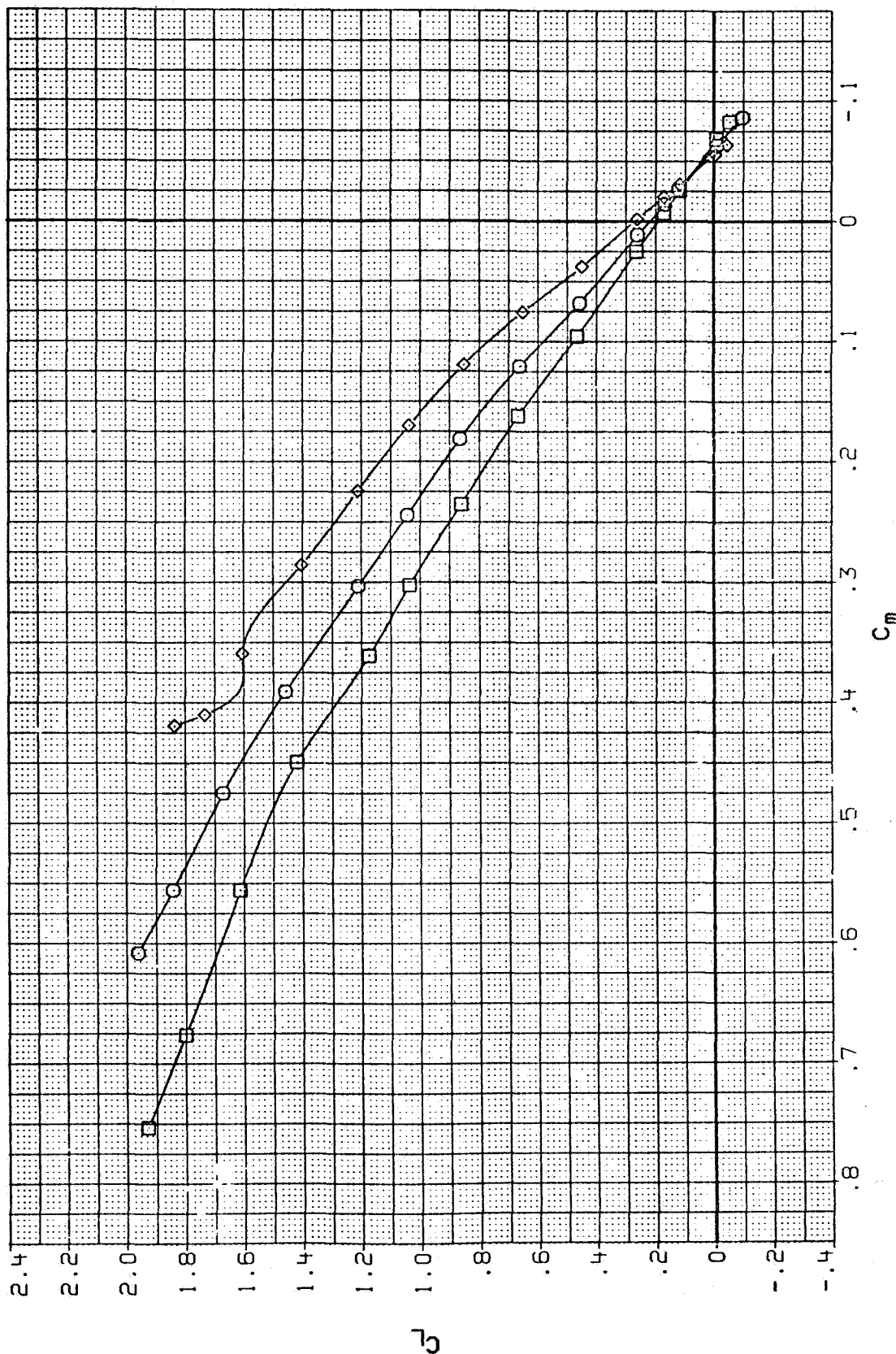


FIG. 44 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S1
 MACH = .60

SYMBOL CONFIGURATION

○ BI SI N WI C1 V (EJECTOR-E205)
 □ BI SI N WI C2 V (EJECTOR-E205)
 ◇ BI SI N WI C3 V (EJECTOR-E205)

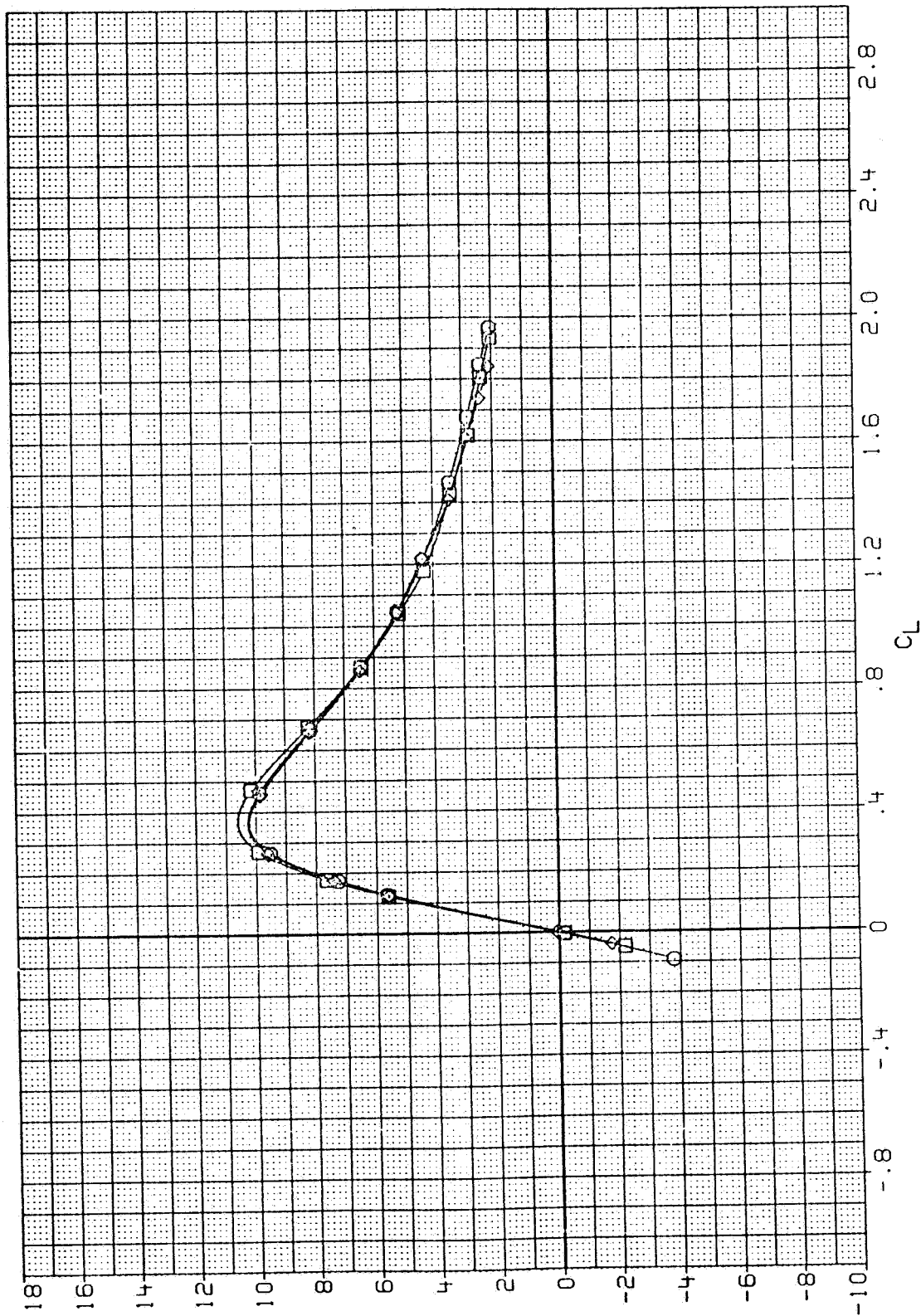


FIG. 44 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S1
 MACH = .60

SYMBOL CONFIGURATION

○ BI SI N WI C1 V (EJECTOR-E205)

□ BI SI N WI C2 V (EJECTOR-E205)

◇ BI SI N WI C3 V (EJECTOR-E205)

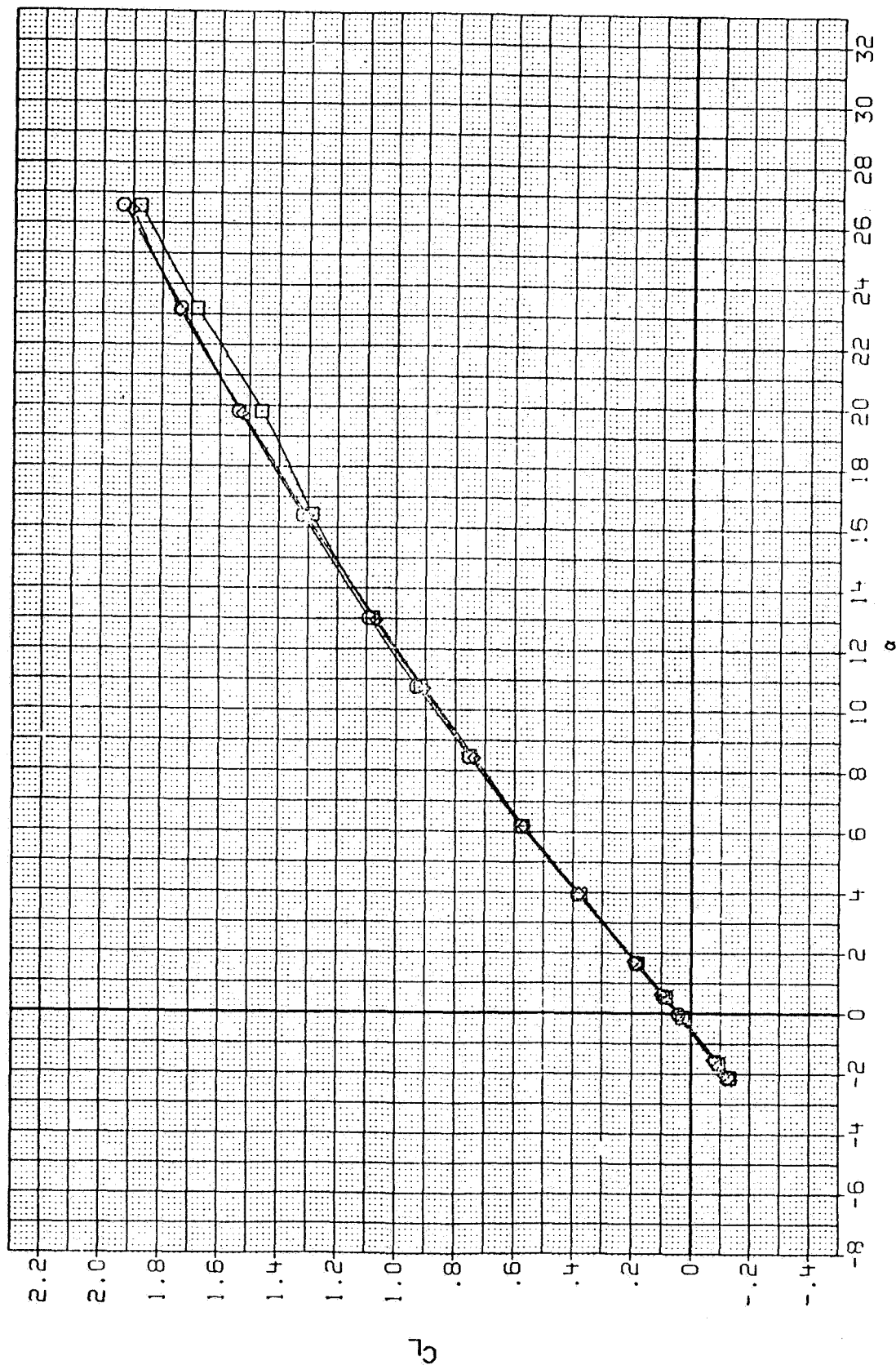


FIG. 45 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = -10 DEGREES, STRAKE S1
MACH = .60

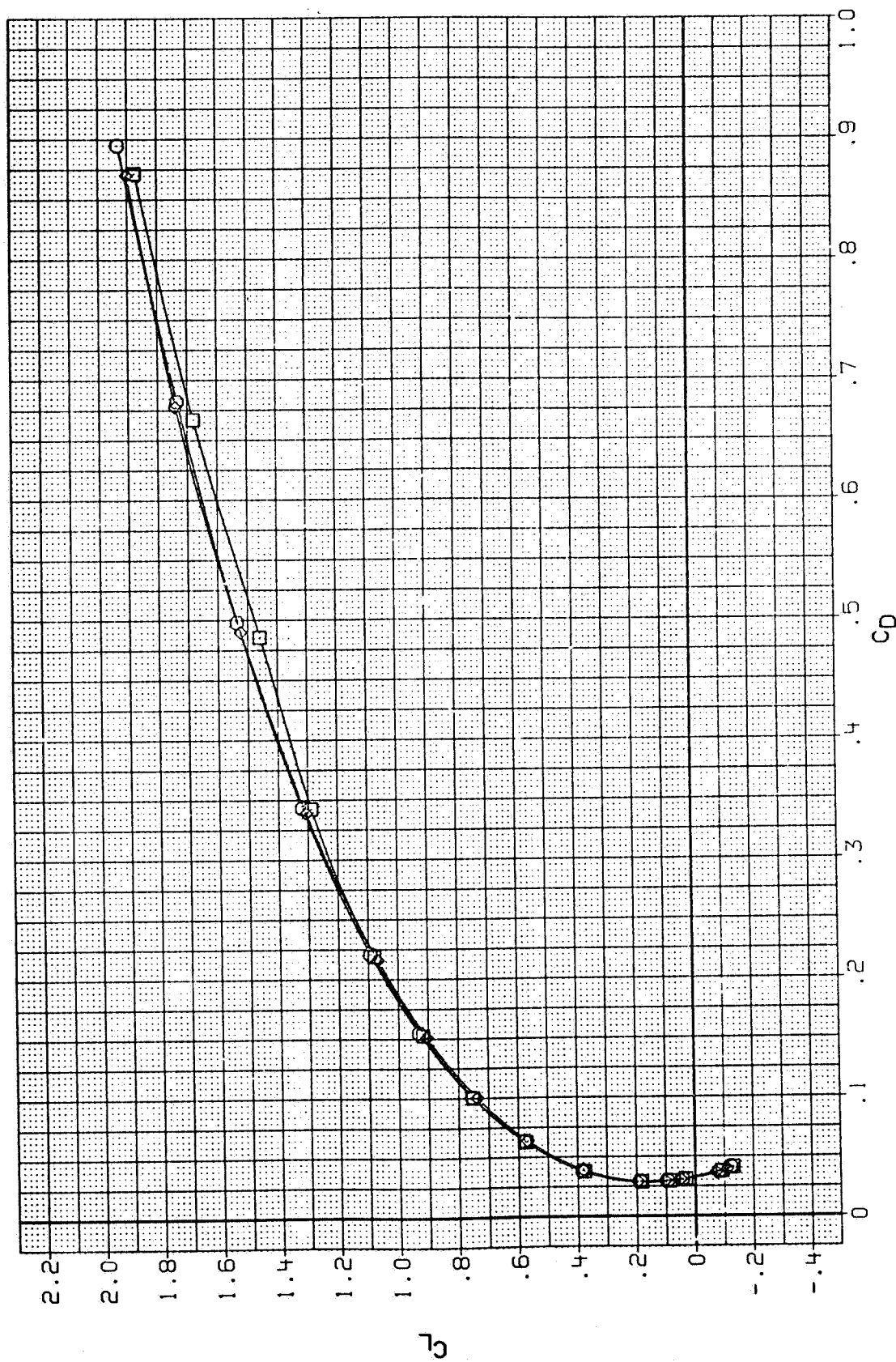


FIG. 45 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = -10 DEGREES, STRAKE S1
MACH = .60

SYMBOL CONFIGURATION
 ○ B1 S1 N W1 C1 V (EJECTOR-E205)
 □ B1 S1 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S1 N W1 C3 V (EJECTOR-E205)

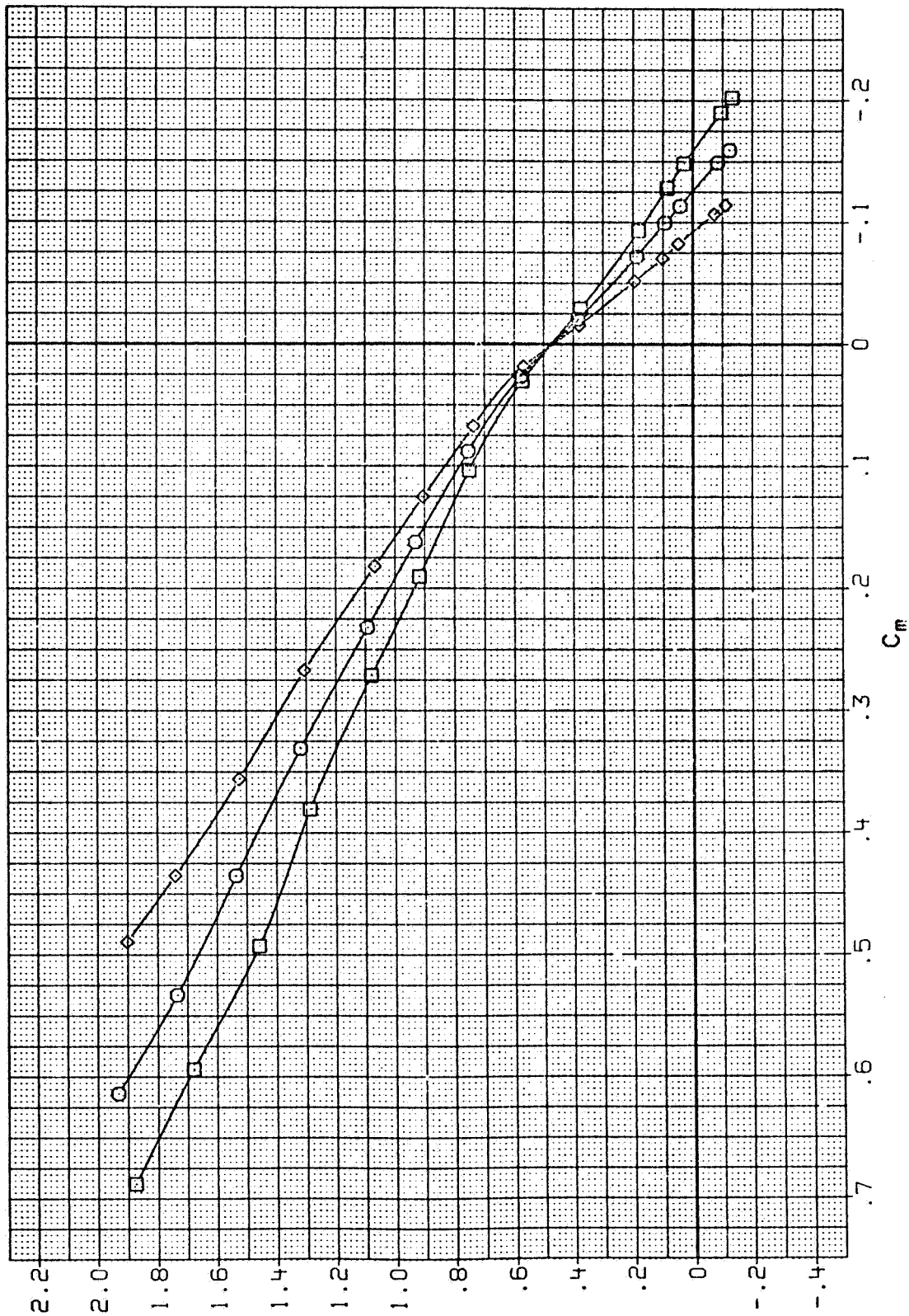


FIG. 45 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S1
 MACH = .60

SYMBOL CONFIGURATION
 ○ BI SI N WI C1 V (EJECTOR-E205)
 □ BI SI N WI C2 V (EJECTOR-E205)
 ◇ BI SI N WI C3 V (EJECTOR-E205)

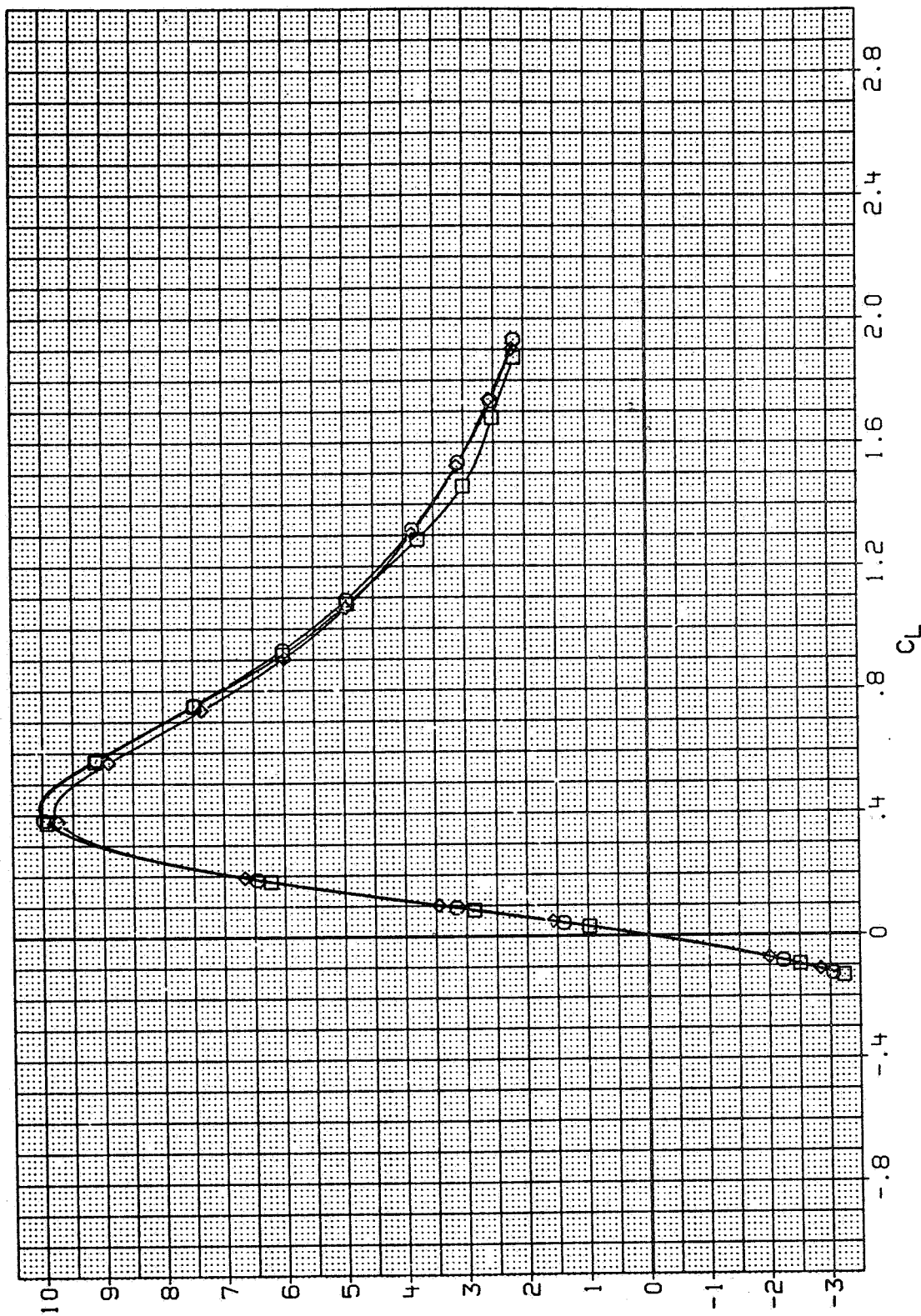


FIG. 45 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S1
 MACH = .60

SYMBOL CONFIGURATION

BI SI N WI C1 V (EJECTOR-E205)
 BI SI N WI C2 V (EJECTOR-E205)
 BI SI N WI C3 V (EJECTOR-E205)

○ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

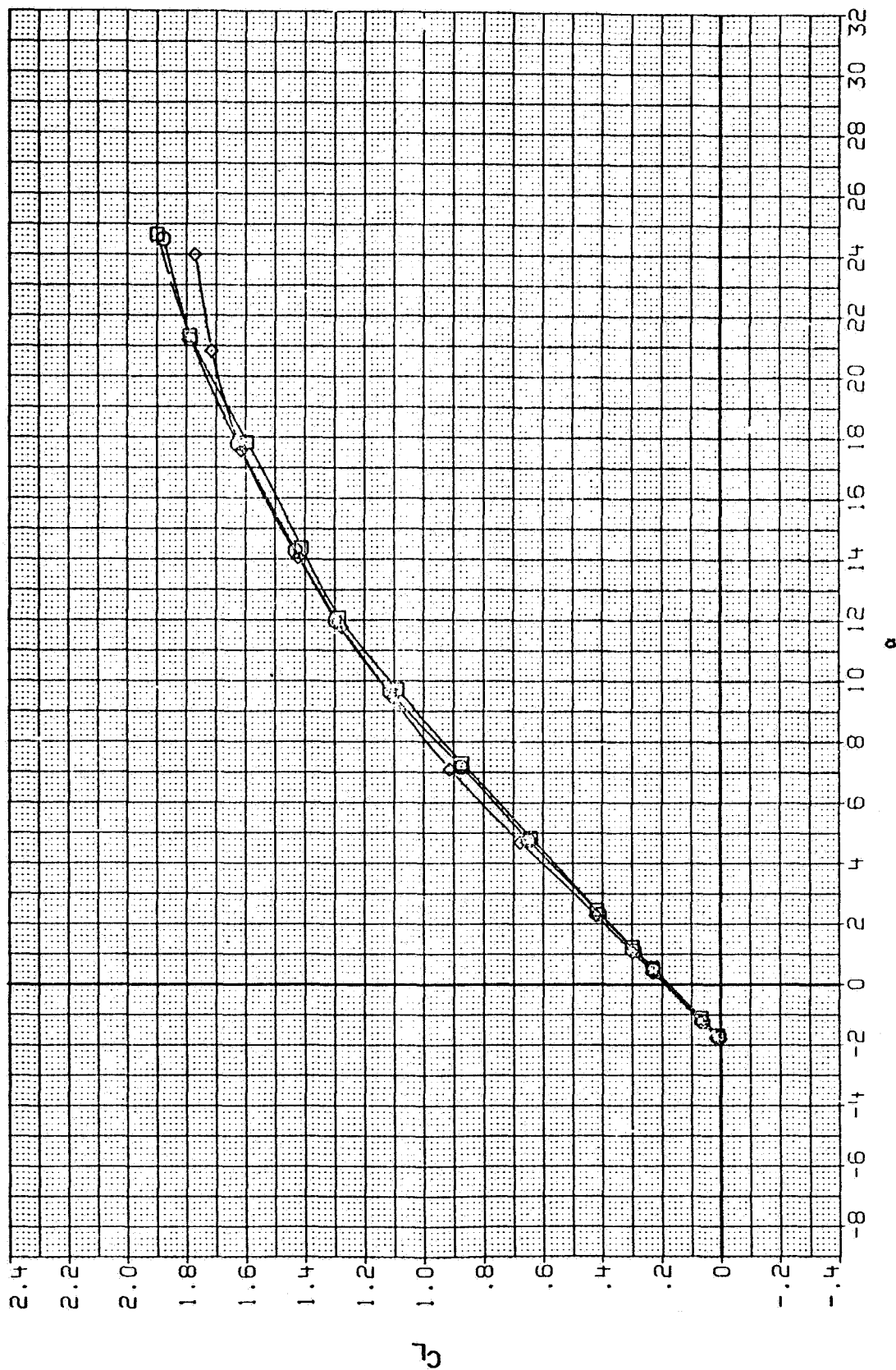


FIG. 46 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S1
MACH = .90

SYMBOL CONFIGURATION

BI SI N WI C1 V (EJECTOR-E205)
 BI SI N WI C2 V (EJECTOR-E205)
 BI SI N WI C3 V (EJECTOR-E205)

□ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

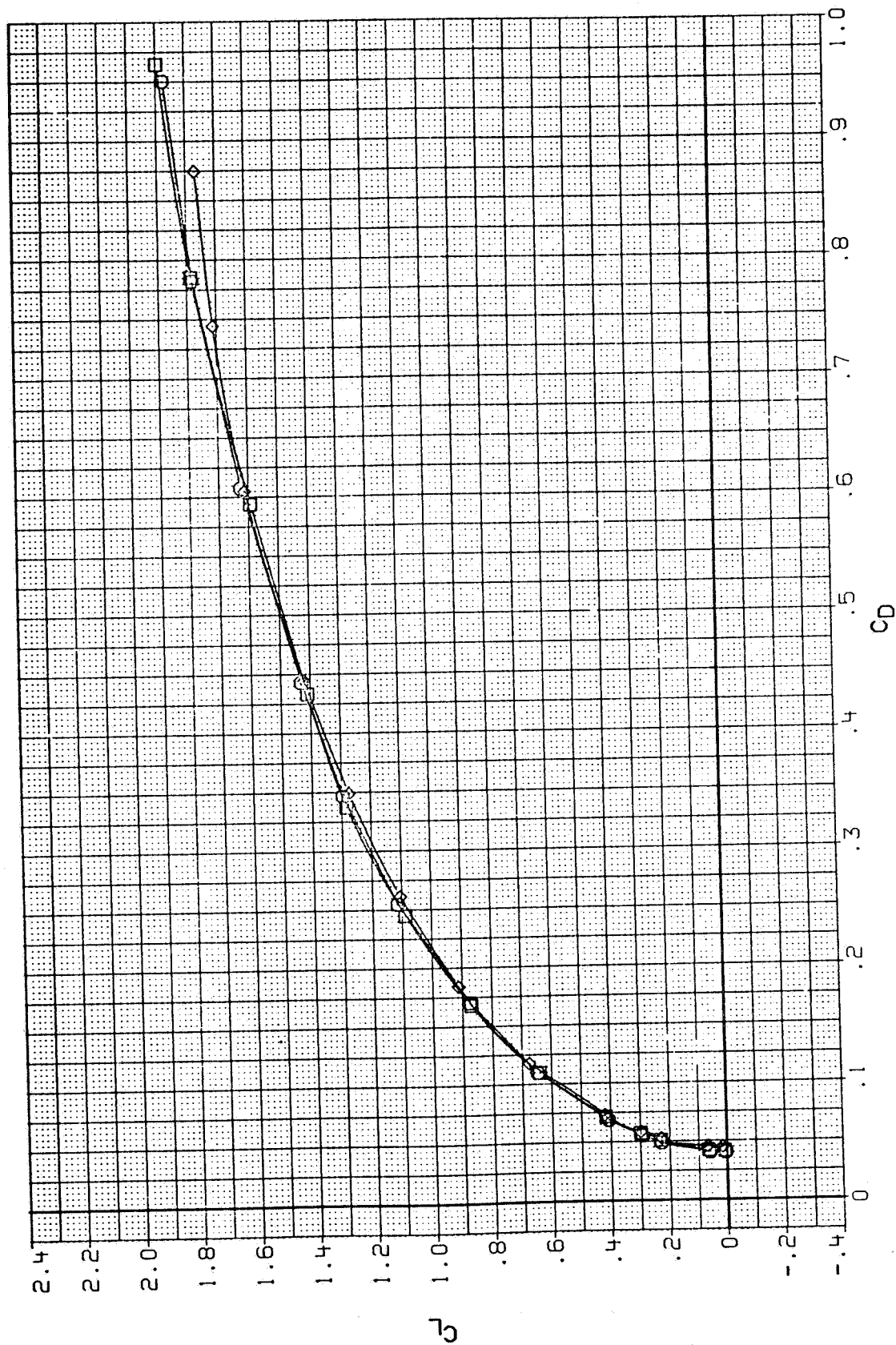


FIG. 46 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S1
MACH = .90

SYMBOL CONFIGURATION
 ○ BI SI N WI C1 V (EJECTOR-E205)
 □ BI SI N WI C2 V (EJECTOR-E205)
 ◇ BI SI N WI C3 V (EJECTOR-E205)

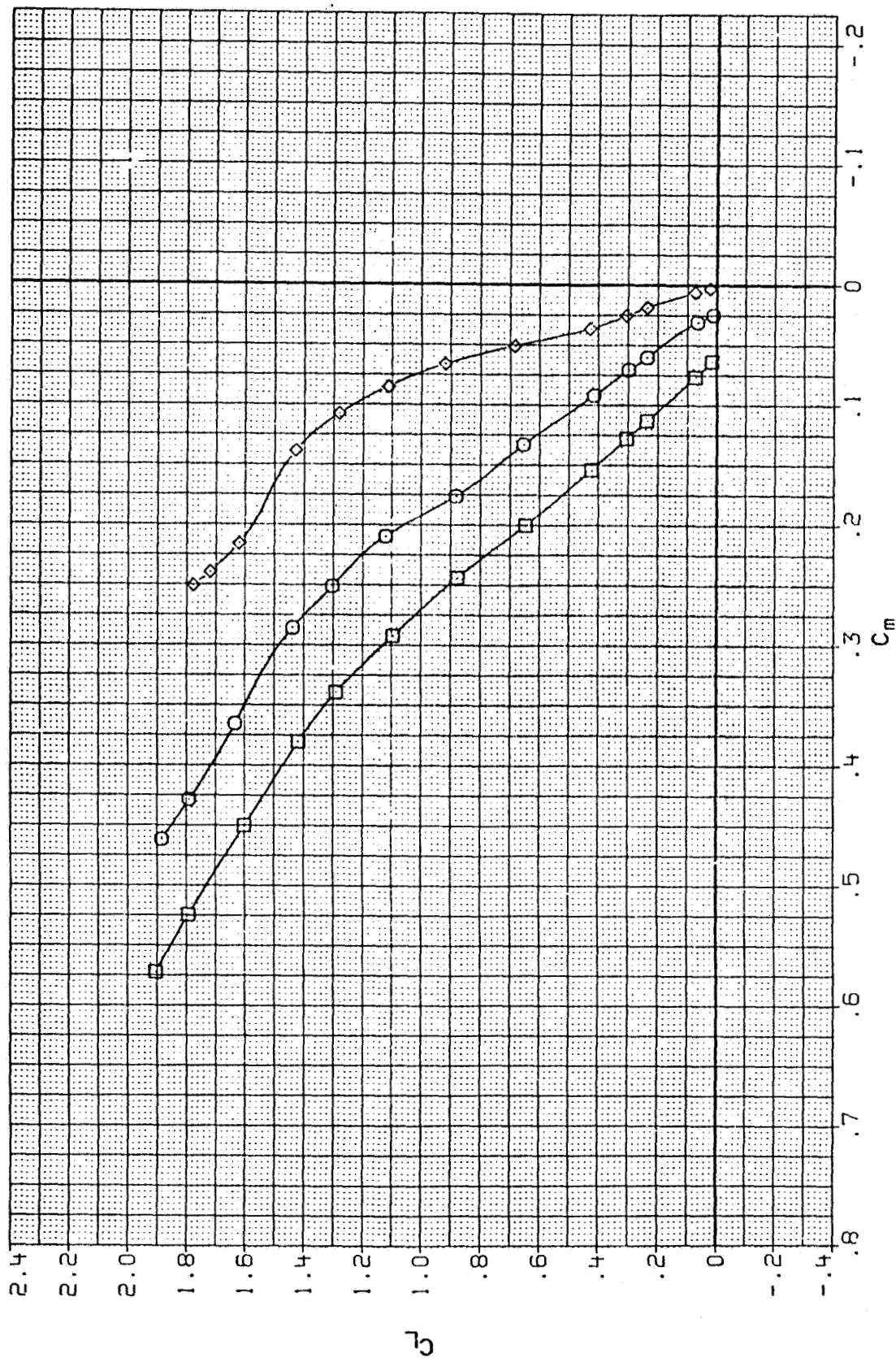


FIG. 46 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE SI
 MACH = .90

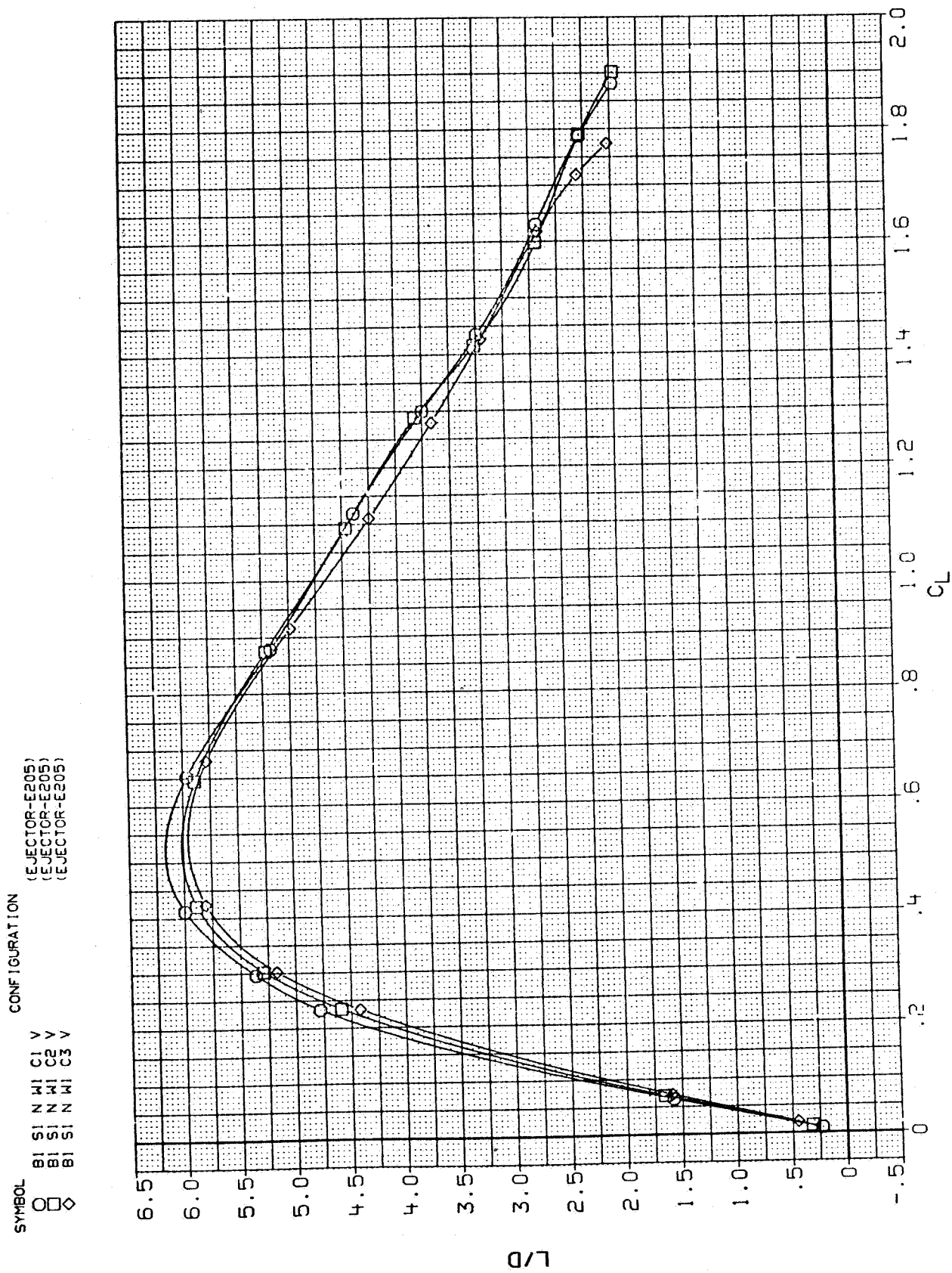


FIG. 46 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S1

MACH = .90

SYMBOL CONFIGURATION
 ○ BI SI N MI C1 V (EJECTOR-E205)
 □ BI SI N MI C2 V (EJECTOR-E205)
 ◇ BI SI N MI C3 V (EJECTOR-E205)

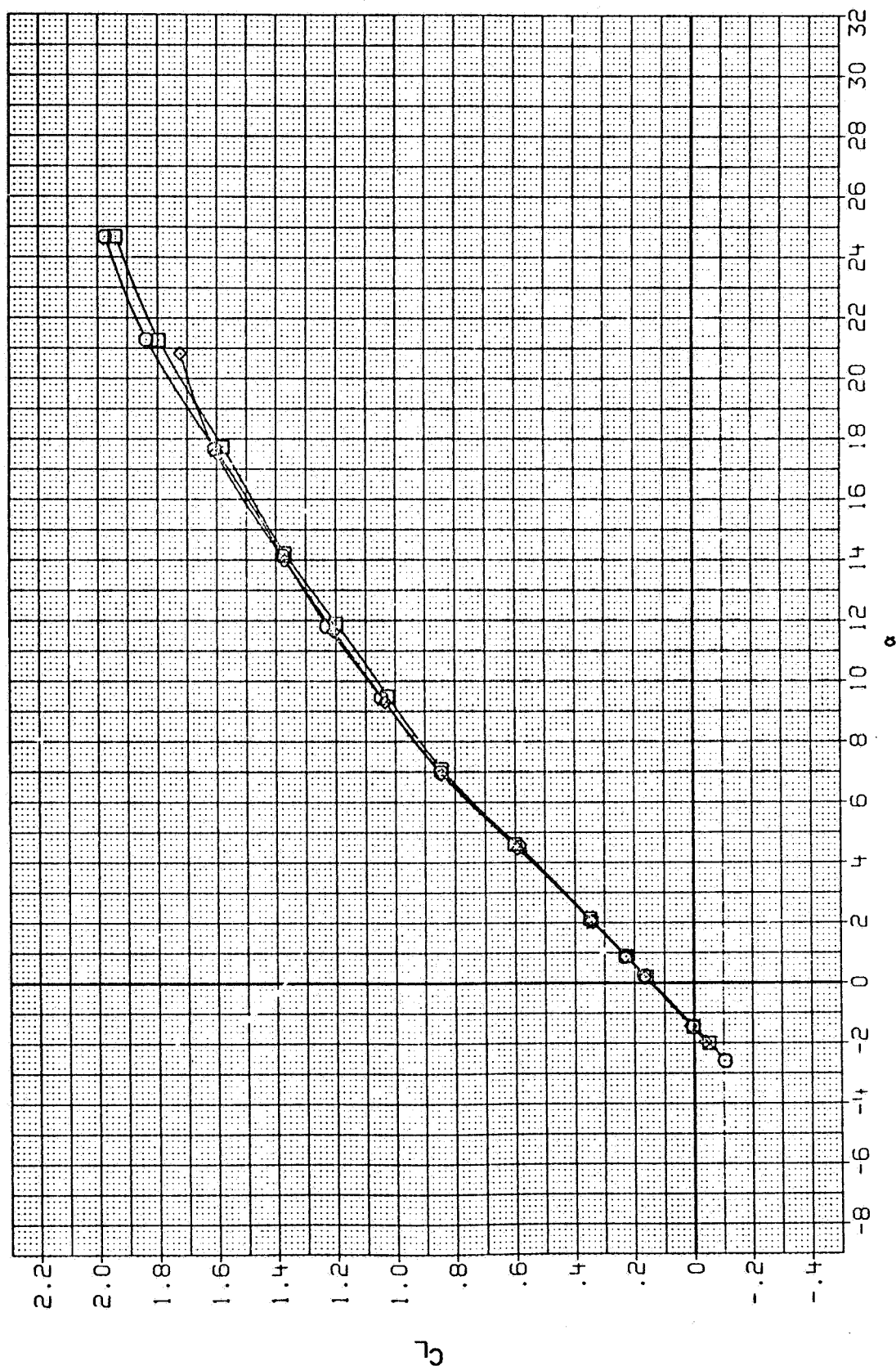


FIG. 47 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE SI
 MACH = .90

SYMBOL	CONFIGURATION
BI SI N WI C1 V	(EJECTOR-E205)
BI SI N WI C2 V	(EJECTOR-E205)
BI SI N WI C3 V	(EJECTOR-E205)
○	
◇	

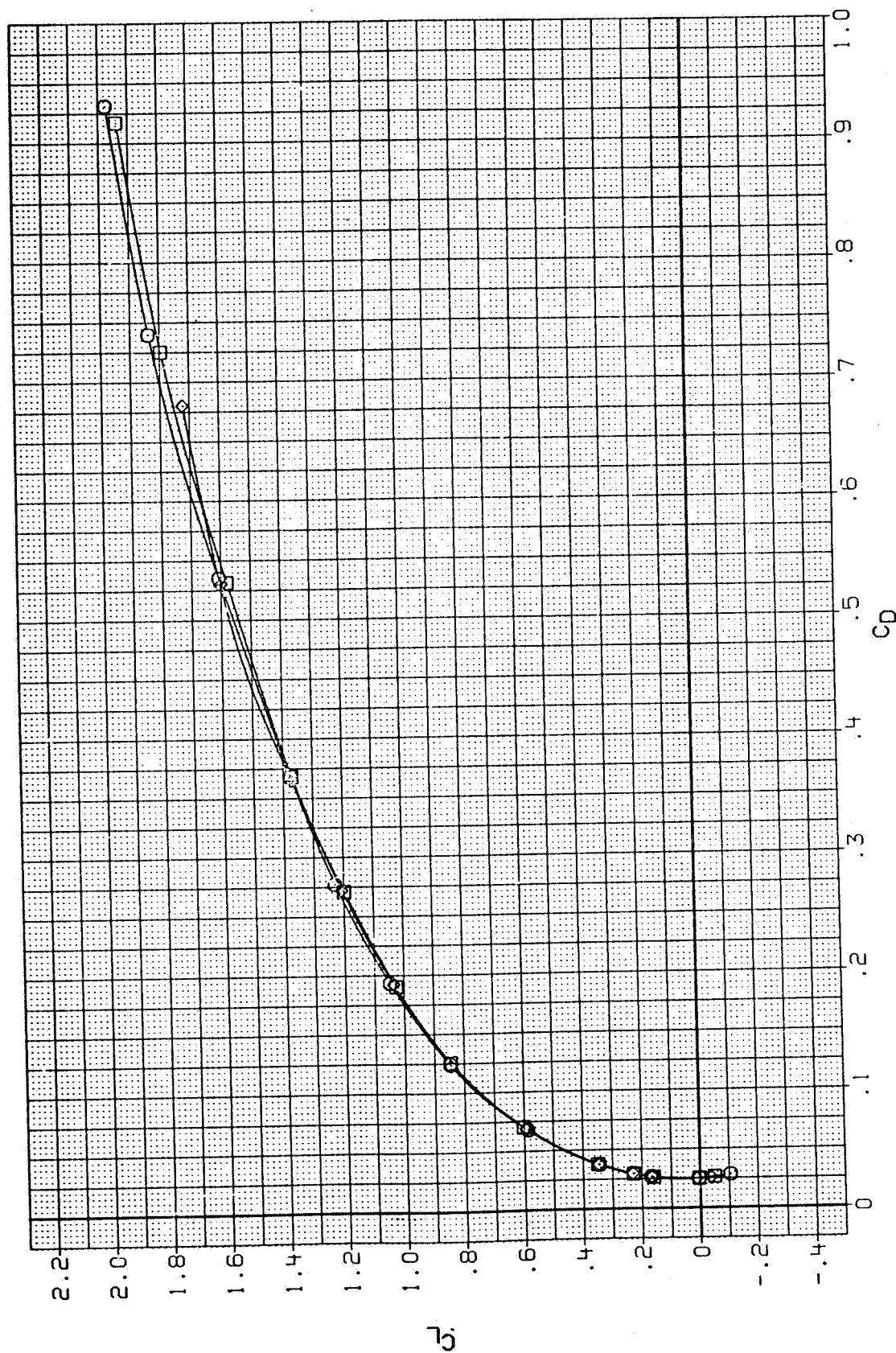


FIG. 47 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 0 DEGREES, STROKE S1

MACH = .90

SYMBOL CONFIGURATION

○ (EJECTOR-E205)
 □ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

BI SI N WI C1 V
 BI SI N WI C2 V
 BI SI N WI C3 V

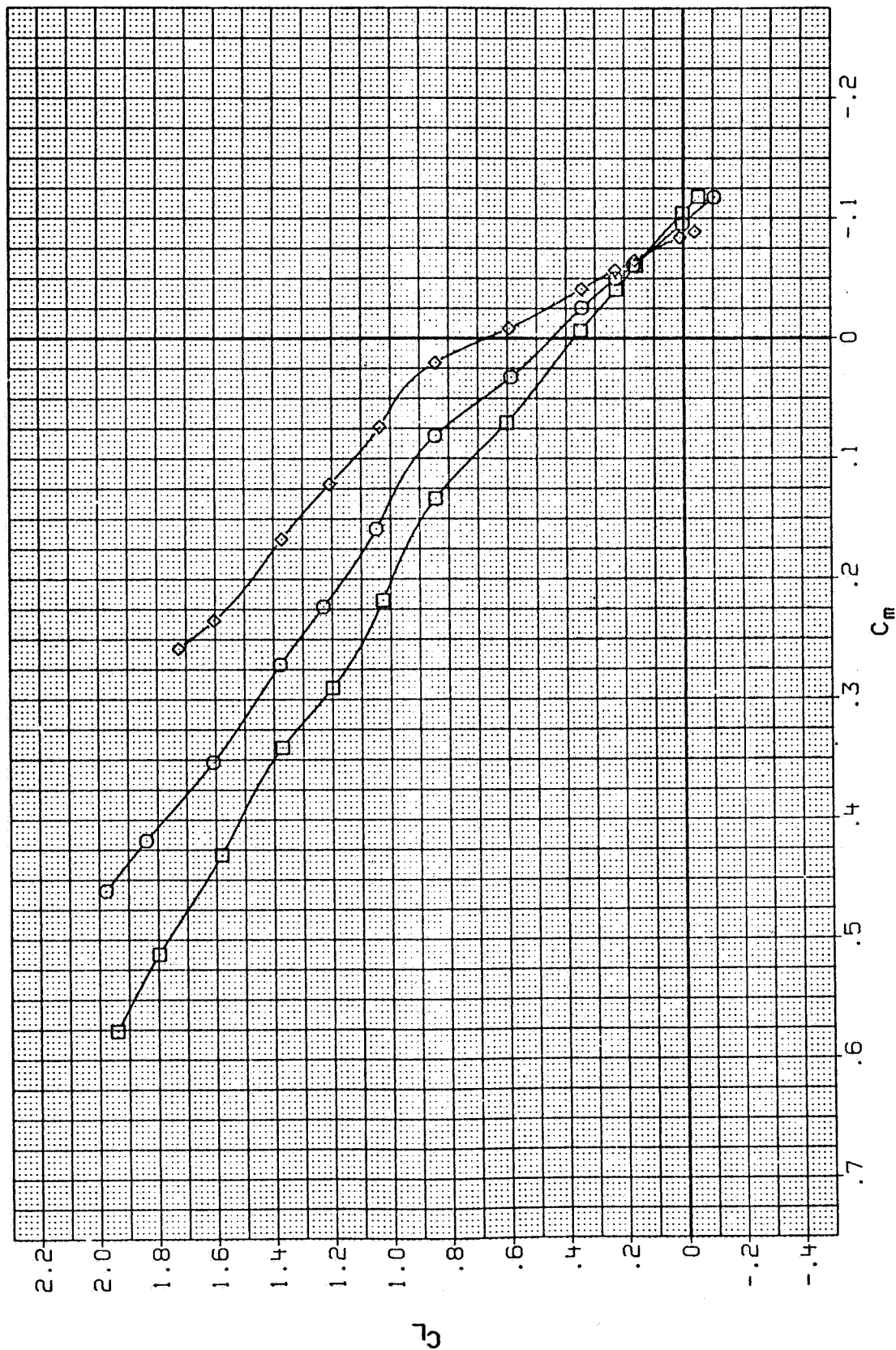


FIG. 47 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 0 DEGREES, STRAKE S1

MACH = .90

SYMBOL CONFIGURATION

BI SI N WI C1 V (EJECTOR-E205)
 BI SI N WI C2 V (EJECTOR-E205)
 BI SI N WI C3 V (EJECTOR-E205)

○ □ ◇
 ○ □ ◇

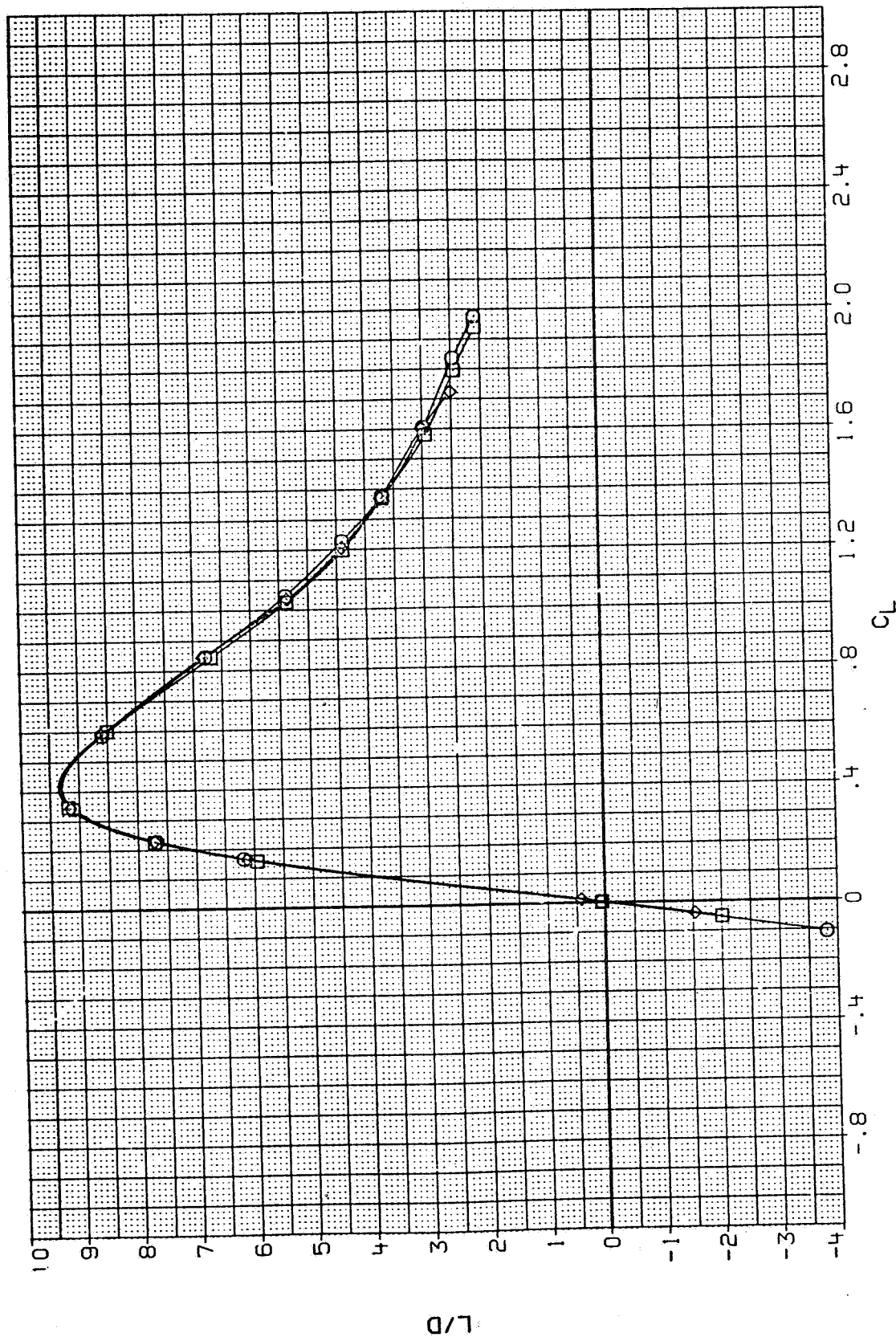


FIG. 47 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 0 DEGREES, STRAKE S1

MACH = .90

L/D

SYMBOL CONFIGURATION

○ BI SI N WI C1 V (EJECTOR-E205)
 □ BI SI N WI C2 V (EJECTOR-E205)
 ◇ BI SI N WI C3 V (EJECTOR-E205)

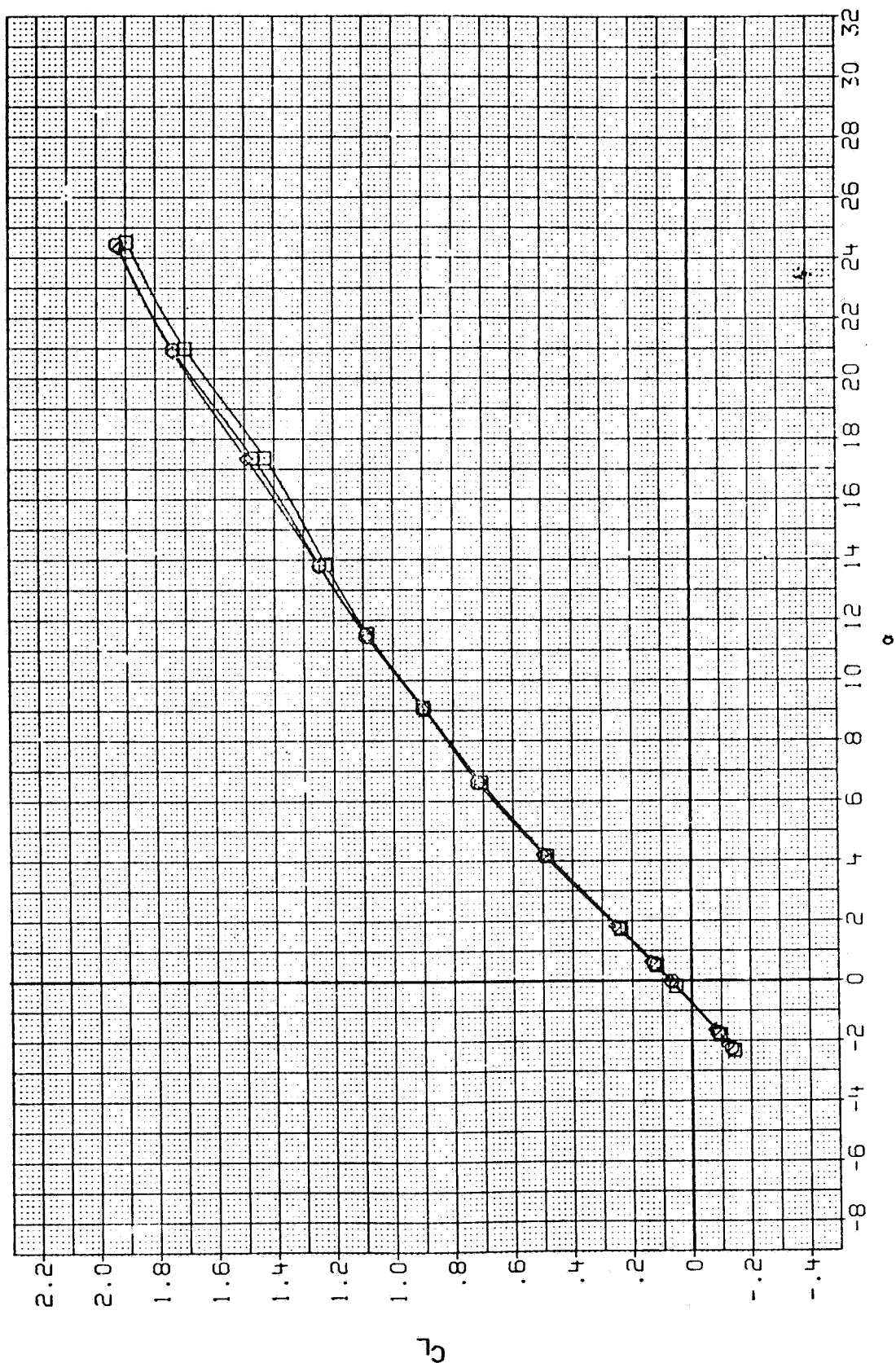


FIG. 48 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE SI
 MACH = .90

SYMBOL CONFIGURATION
 □ BI SI N WI C1 V
 BI SI N WI C2 V
 ◇ BI SI N WI C3 V
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

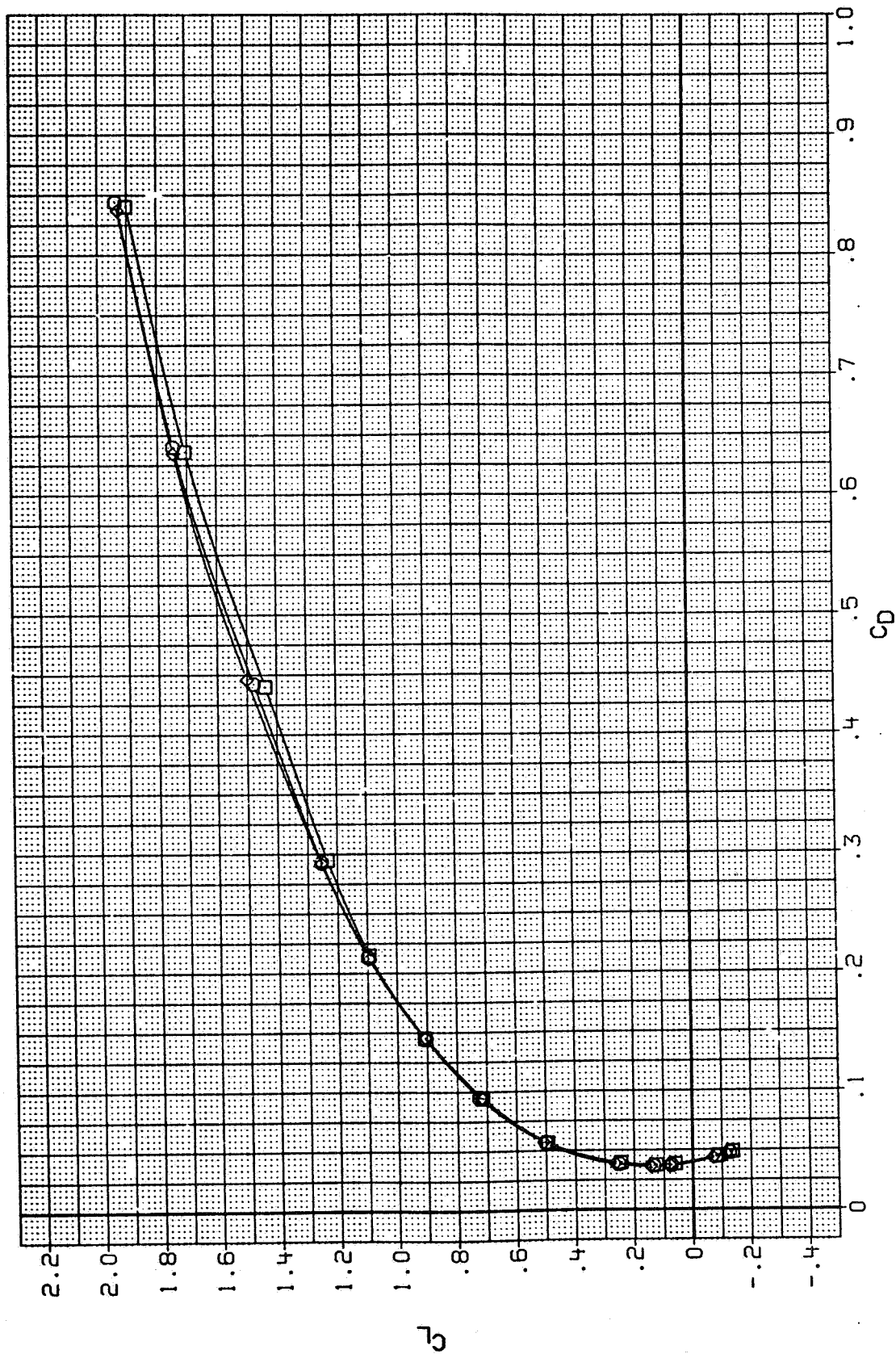


FIG. 48 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S1
 MACH = .90

SYMBOL CONFIGURATION

BI SI N WI C1 V (EJECTOR-E205)
 BI SI N WI C2 V (EJECTOR-E205)
 BI SI N WI C3 V (EJECTOR-E205)

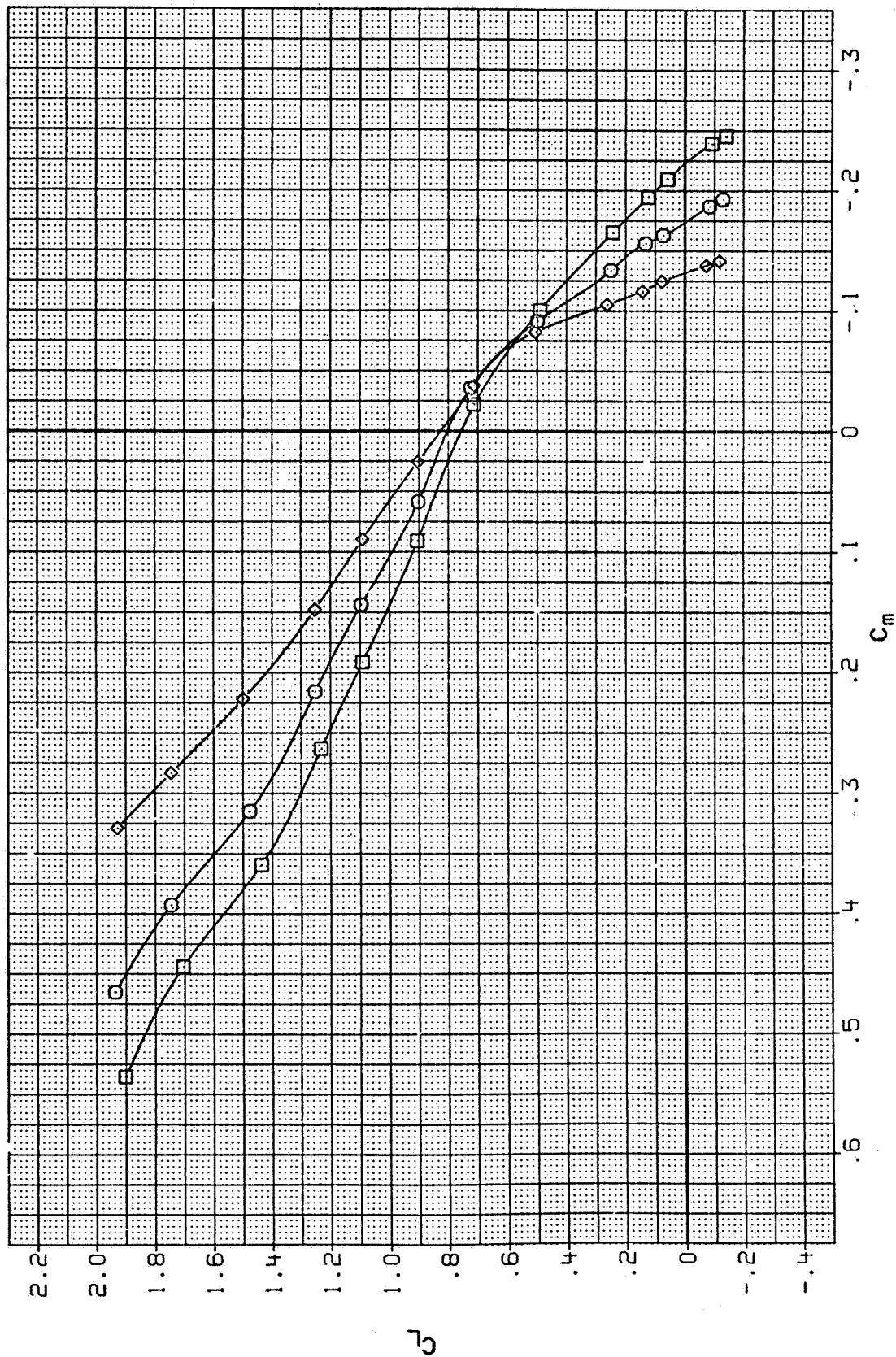


FIG. 48 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = -10 DEGREES, STRAKE S1

MACH = .90

SYMBOL CONFIGURATION
 BI SI N WI C1 V (EJECTOR-E205)
 BI SI N WI C2 V (EJECTOR-E205)
 BI SI N WI C3 V (EJECTOR-E205)

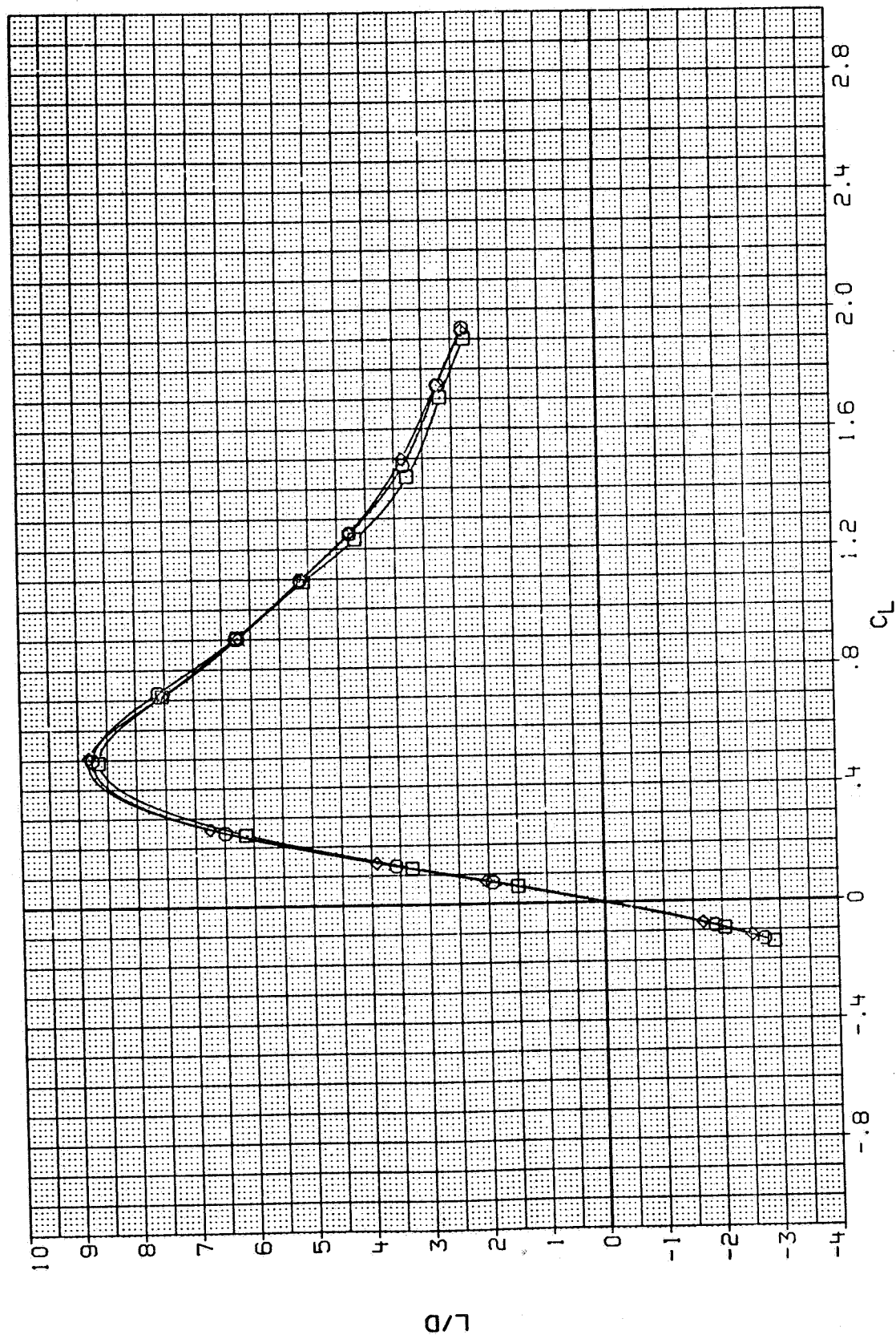


FIG. 48 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S1
 MACH = .90

L/D

SYMBOL CONFIGURATION

○ (EJECTOR-E205)
 □ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

B1 S1 N W1 C1 V
 B1 S1 N W1 C2 V
 B1 S1 N W1 C3 V

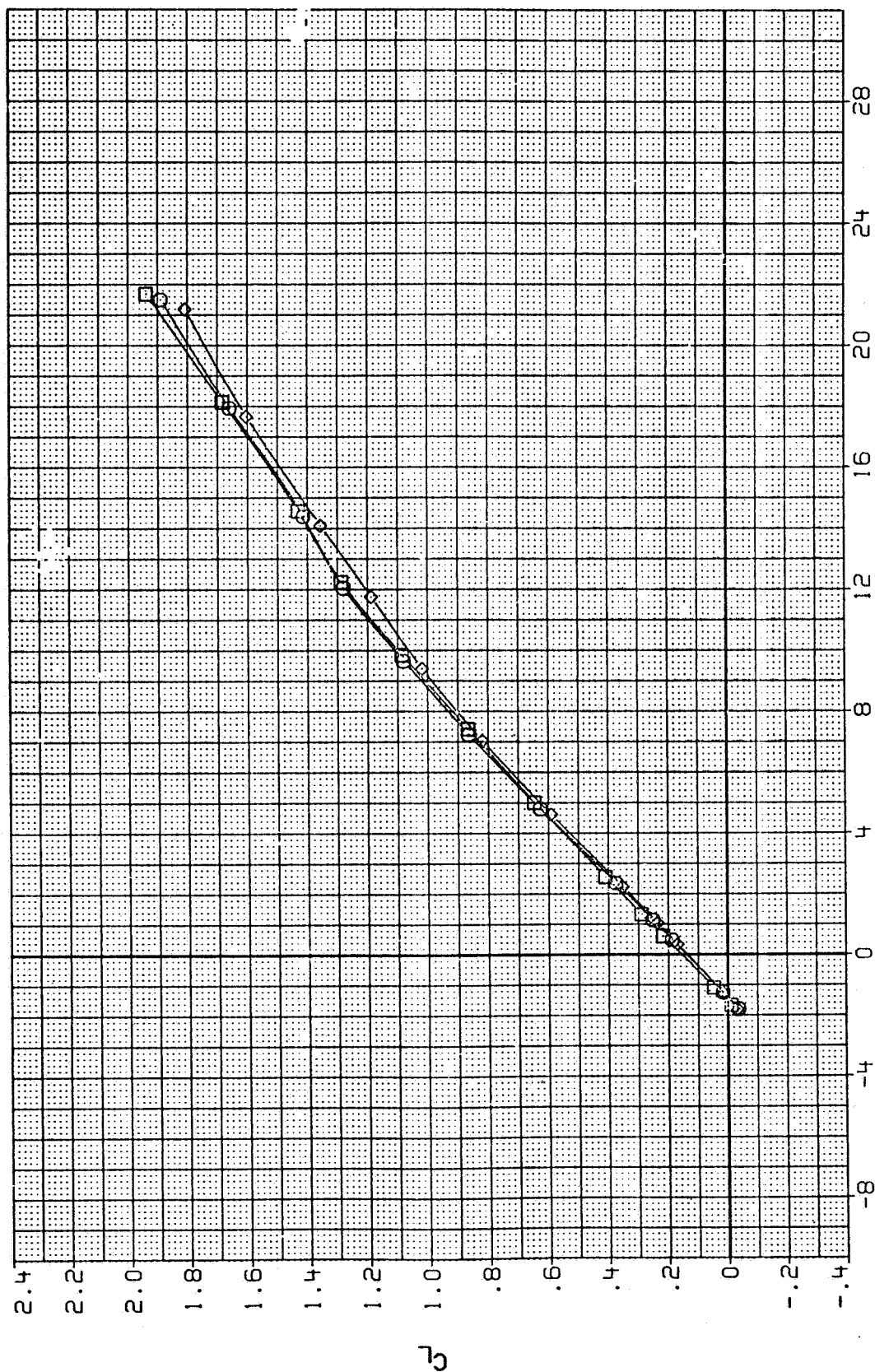


FIG. 49 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S1
 MACH = 1.20

SYMBOL CONFIGURATION

○ (EJECTOR-E205)
 □ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

B1 S1 N W1 C1 V
 B1 S1 N W1 C2 V
 B1 S1 N W1 C3 V

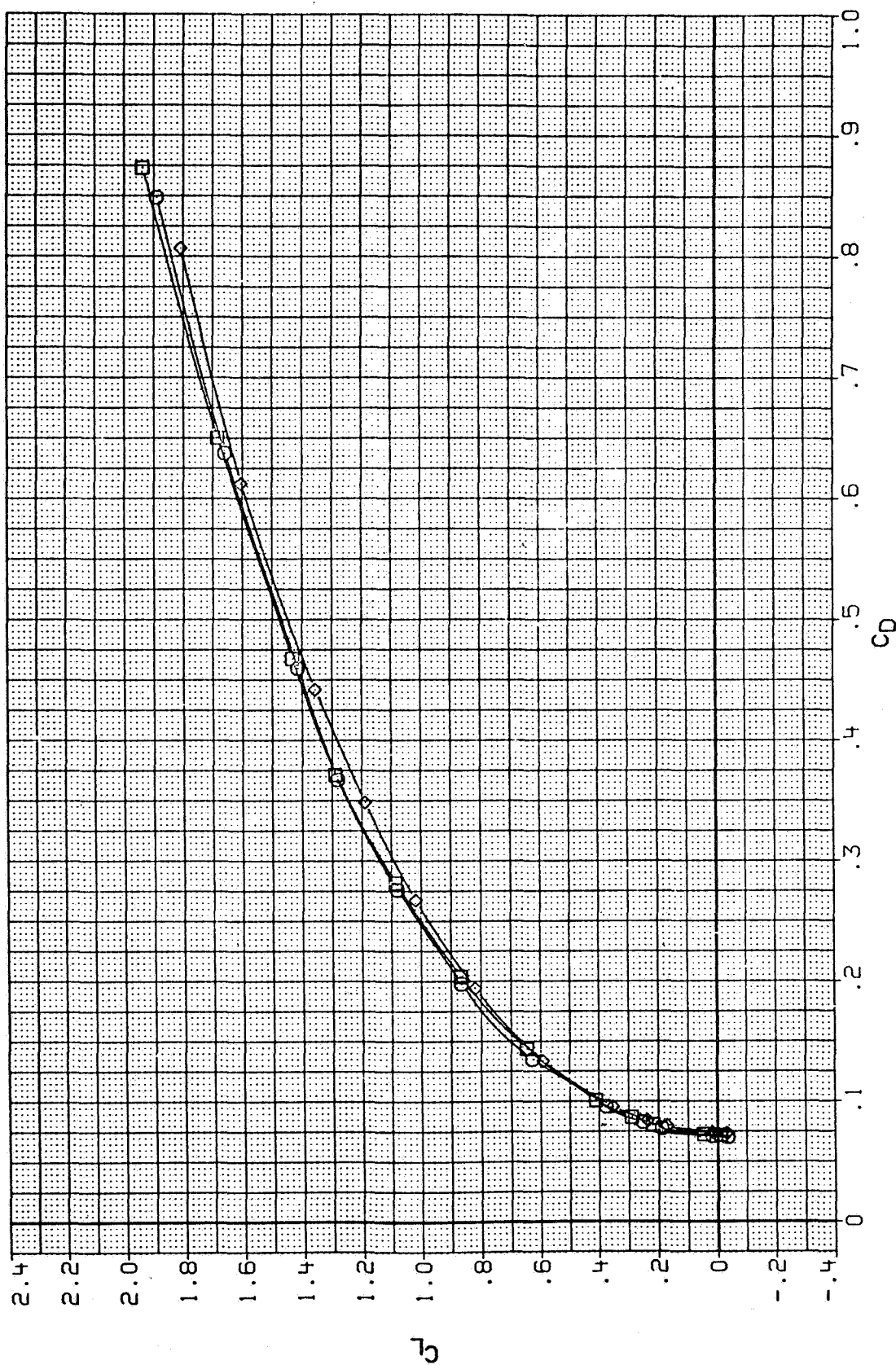


FIG. 49 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S1
 MACH = 1.20

SYMBOL CONFIGURATION

○ BI SI N WI C1 V (EJECTOR-E205)
 □ BI SI N WI C2 V (EJECTOR-E205)
 ◇ BI SI N WI C3 V (EJECTOR-E205)

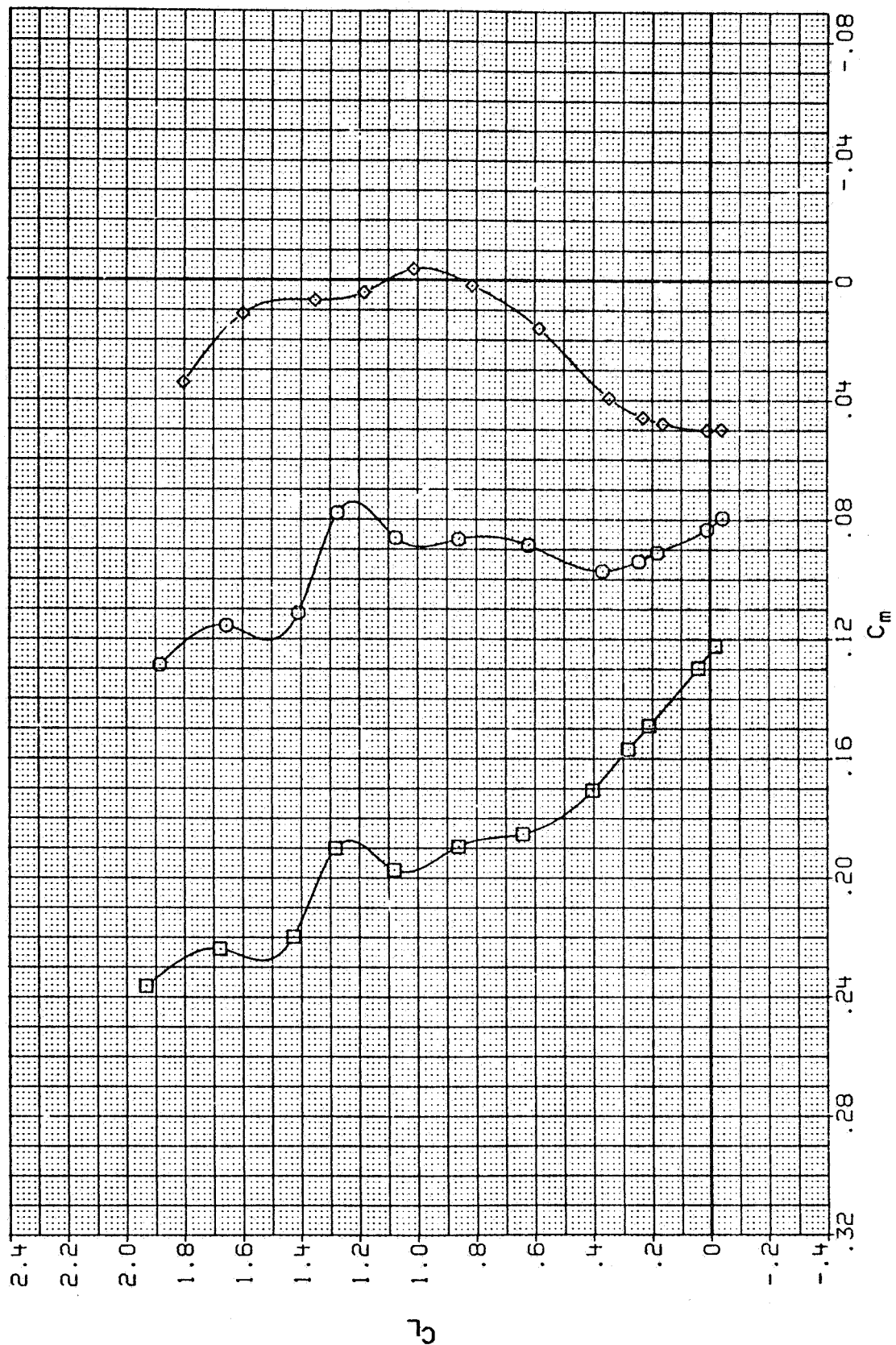


FIG. 49 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S1
MACH = 1.20

SYMBOL CONFIGURATION
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

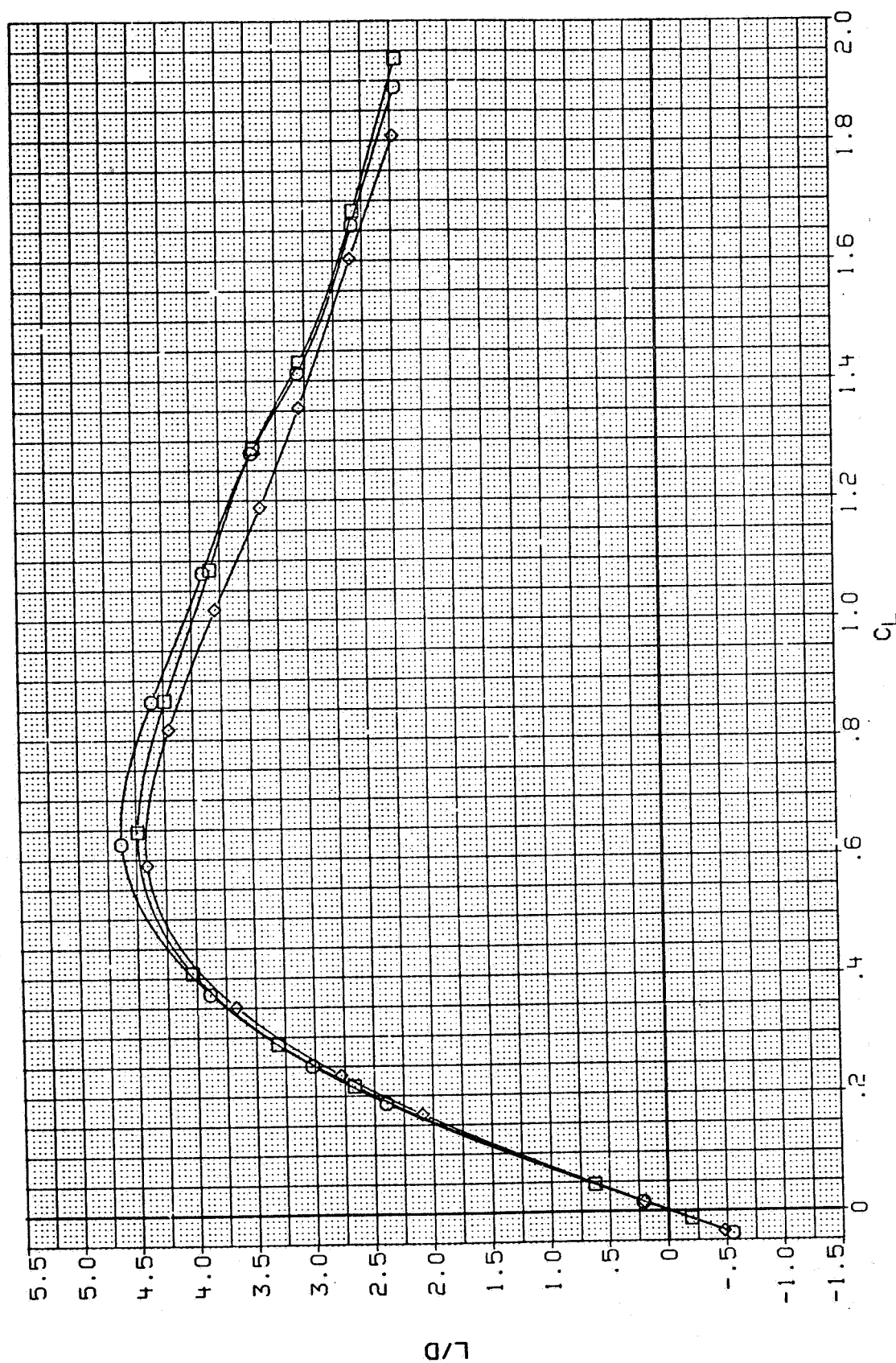


FIG. 49 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE SI
 MACH = 1.20

SYMBOL CONFIGURATION
 ○ BI SI N WI C1 V
 □ BI SI N WI C2 V
 ◇ BI SI N WI C3 V
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

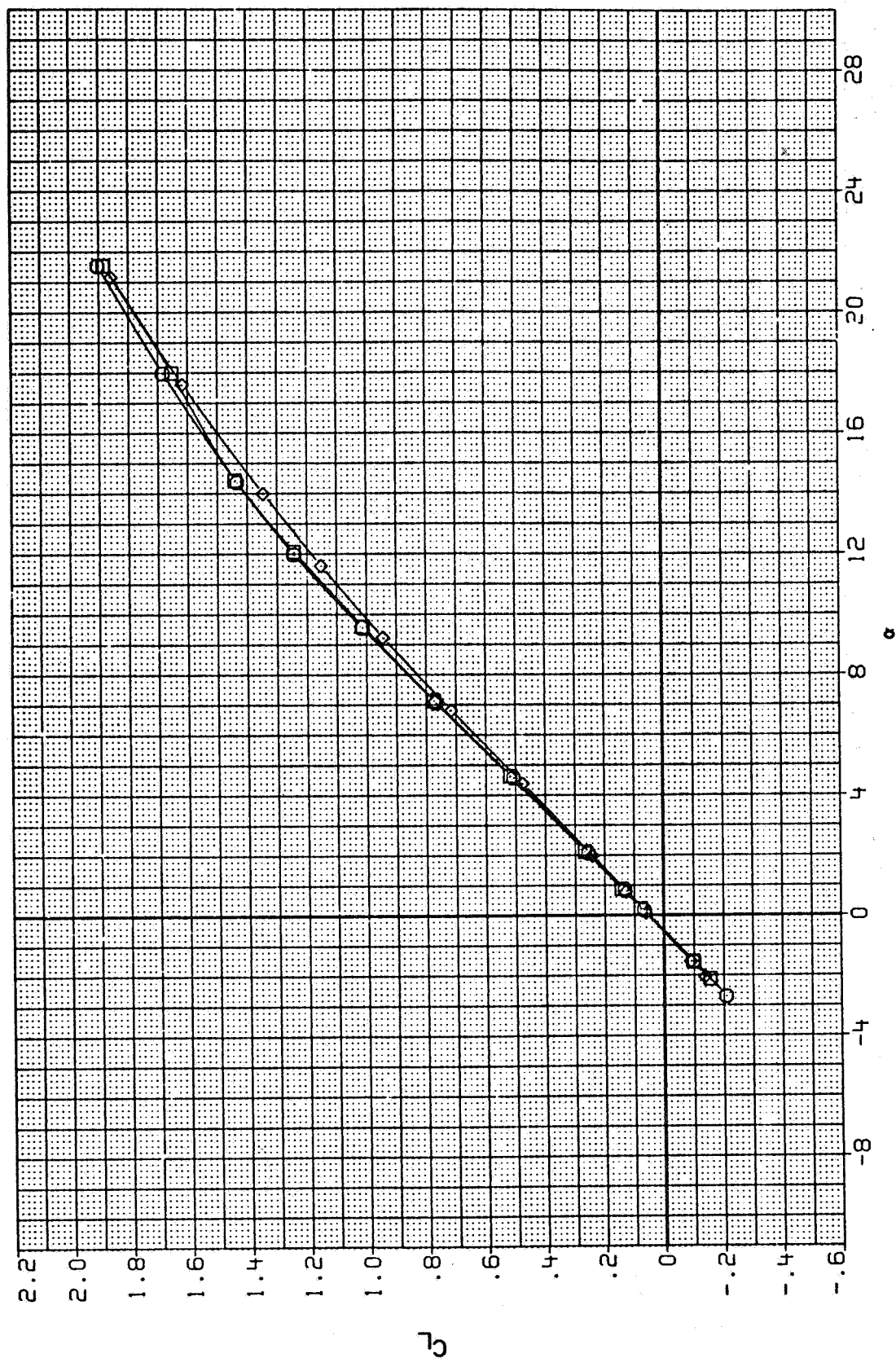


FIG. 50 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S1
 MACH = 1.20

SYMBOL CONFIGURATION

□	BI SI N WI C1 V	(EJECTOR-E205)
○	BI SI N WI C2 V	(EJECTOR-E205)
◇	BI SI N WI C3 V	(EJECTOR-E205)

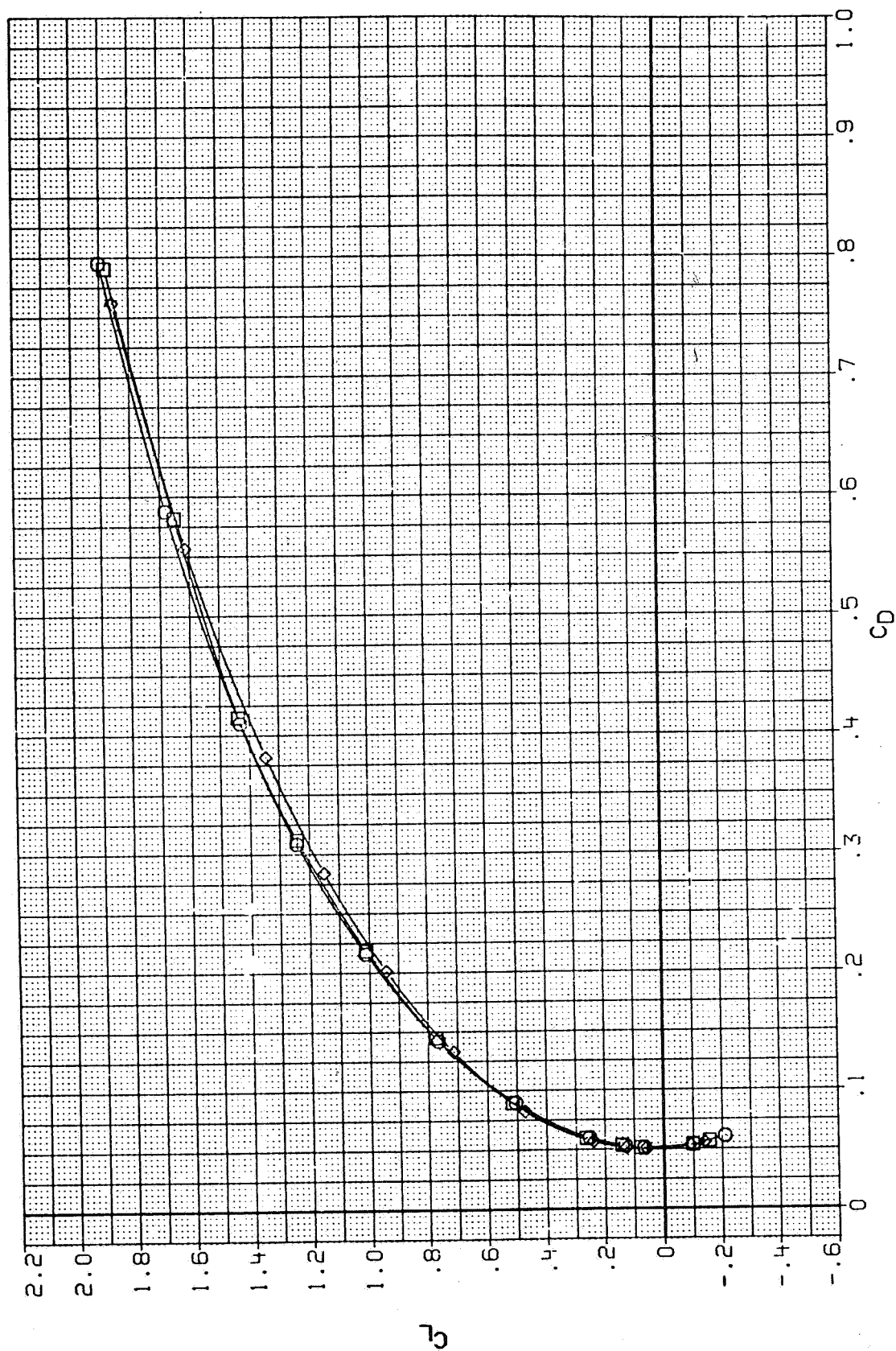


FIG. 50 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S1
 MACH = 1.20

SYMBOL CONFIGURATION
 ○ B1 S1 N W1 C1 V (EJECTOR-E205)
 □ B1 S1 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S1 N W1 C3 V (EJECTOR-E205)

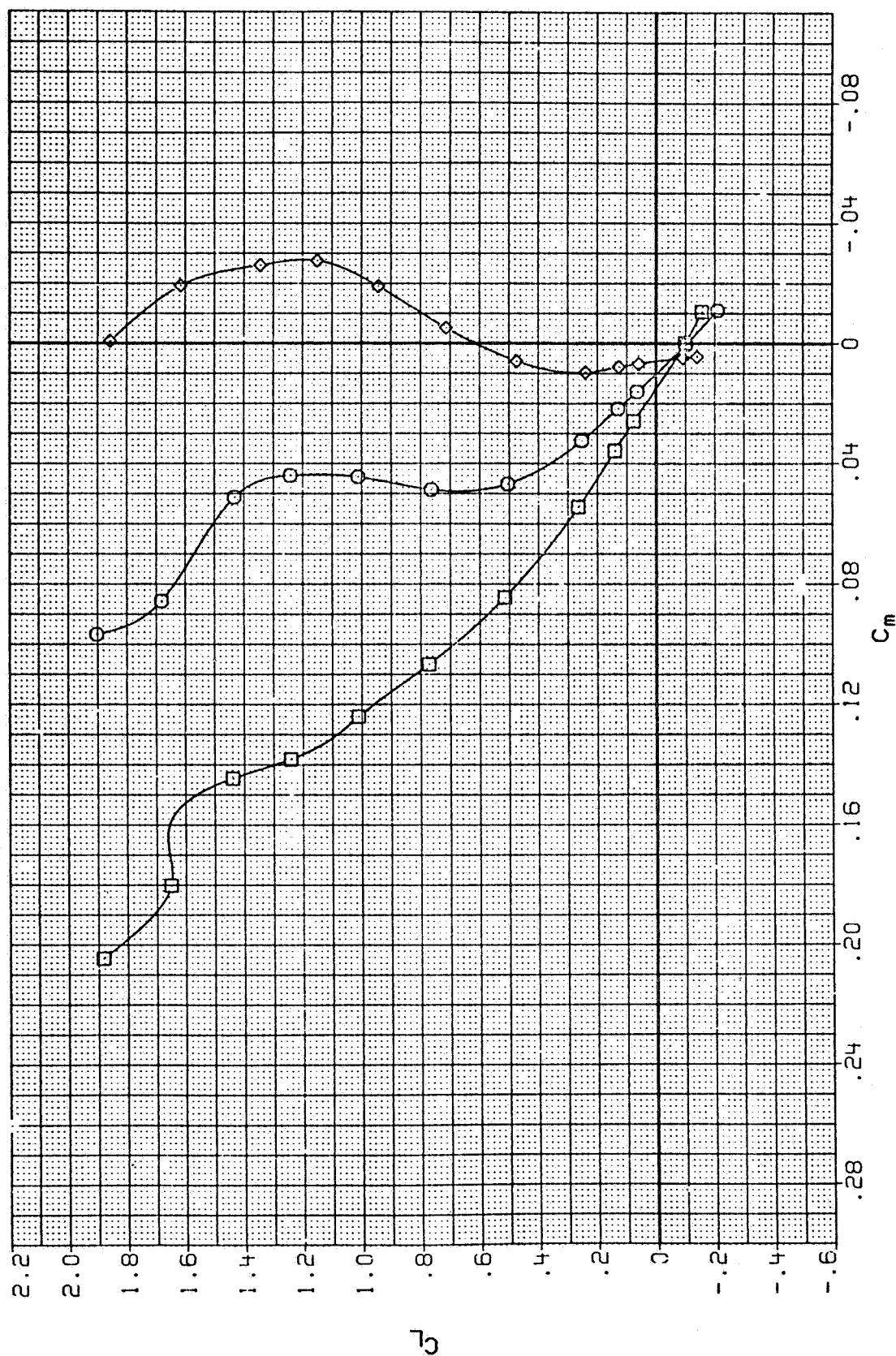


FIG. 50 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S1
 MACH = 1.20

SYMBOL CONFIGURATION
 ○ BI SI N WI C1 V
 □ BI SI N WI C2 V
 ◇ BI SI N WI C3 V
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

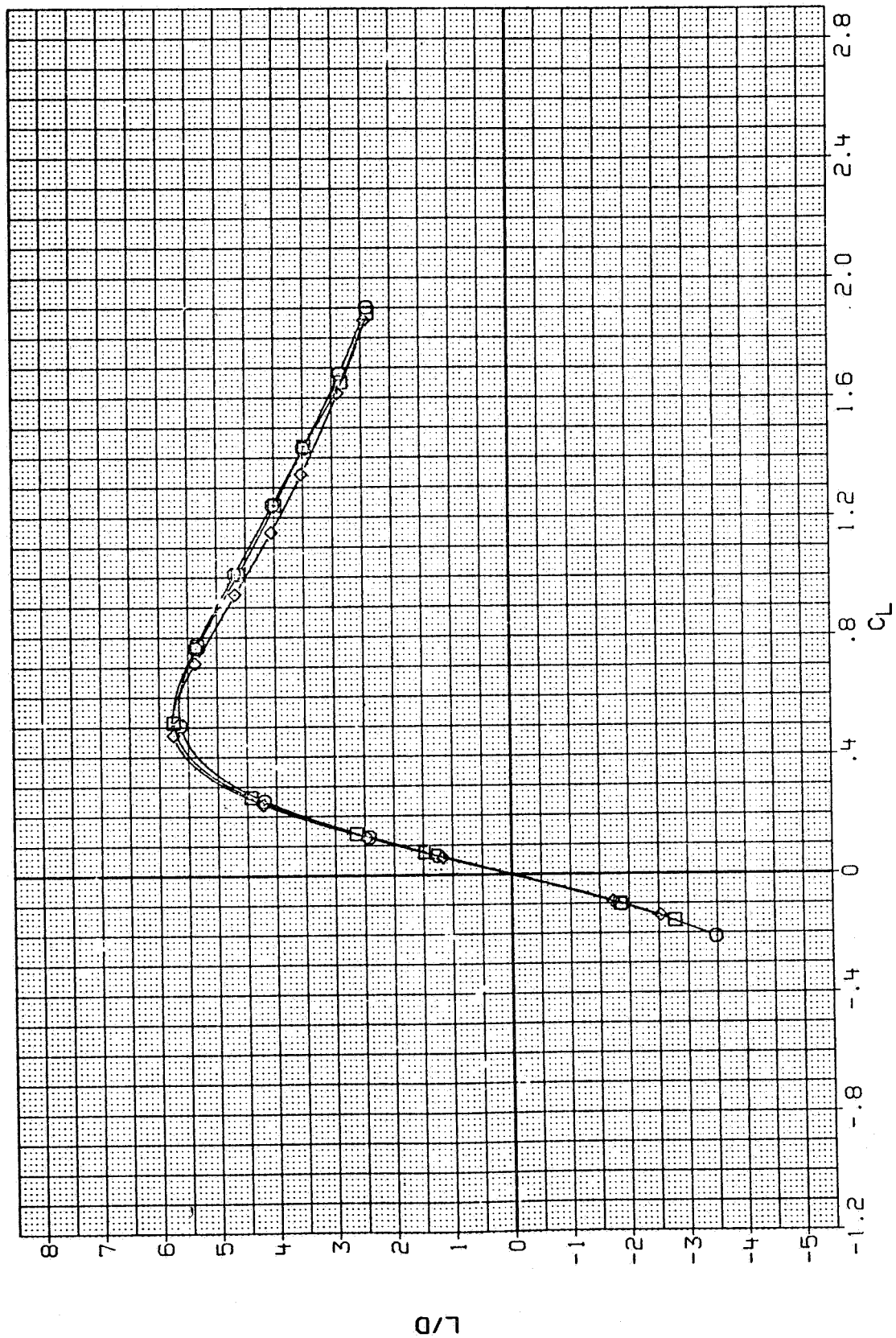


FIG. 50 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S1

MACH = 1.20

SYMBOL CONFIGURATION
 ○ BI SI N WI C1 V (EJECTOR-E205)
 □ BI SI N WI C2 V (EJECTOR-E205)
 ◇ BI SI N WI C3 V (EJECTOR-E205)

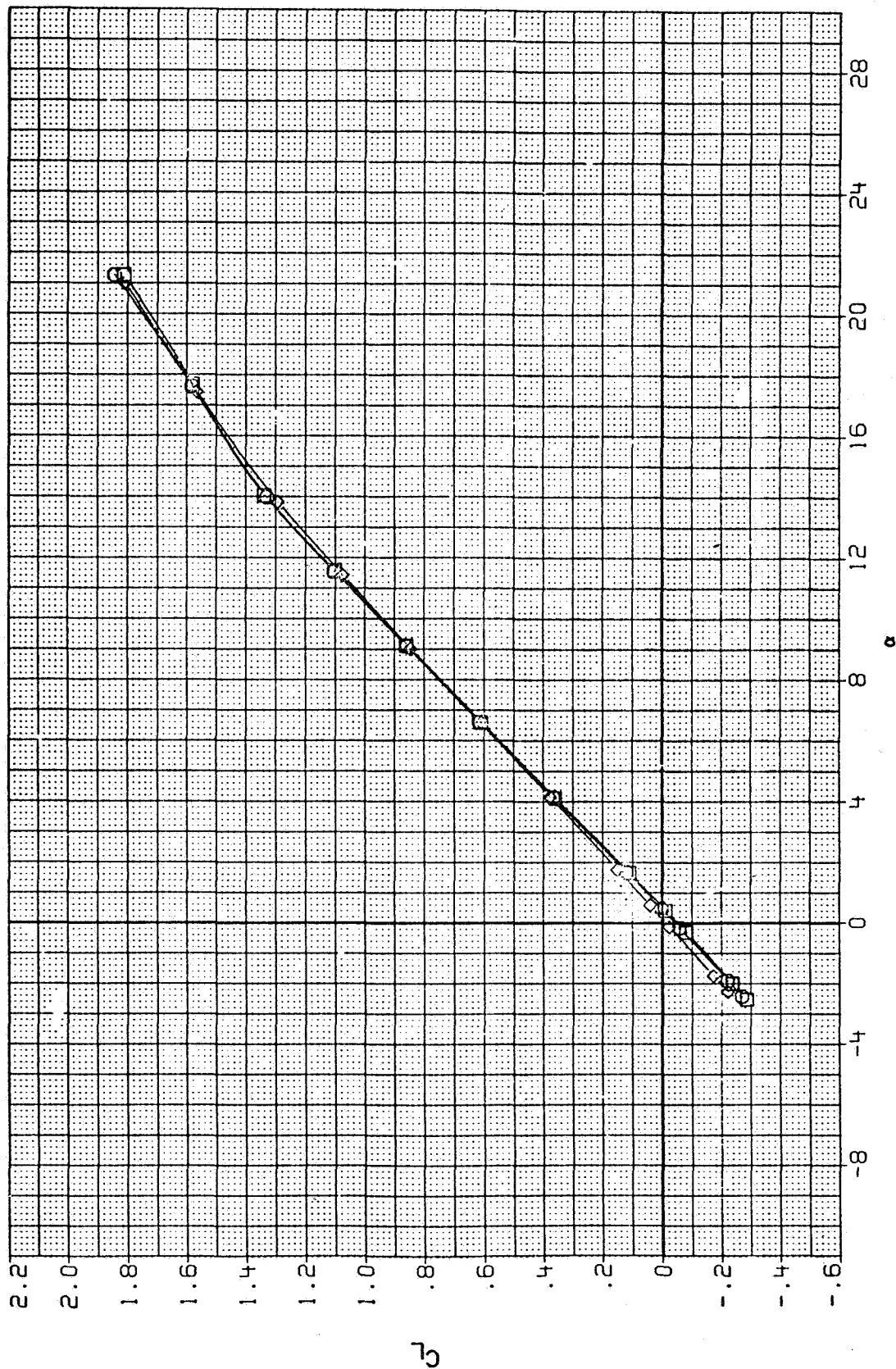


FIG. 51 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S1
 MACH = 1.20

SYMBOL CONFIGURATION

○ BI SI N WI C1 V (EJECTOR-E205)

□ BI SI N WI C2 V (EJECTOR-E205)

◇ BI SI N WI C3 V (EJECTOR-E205)

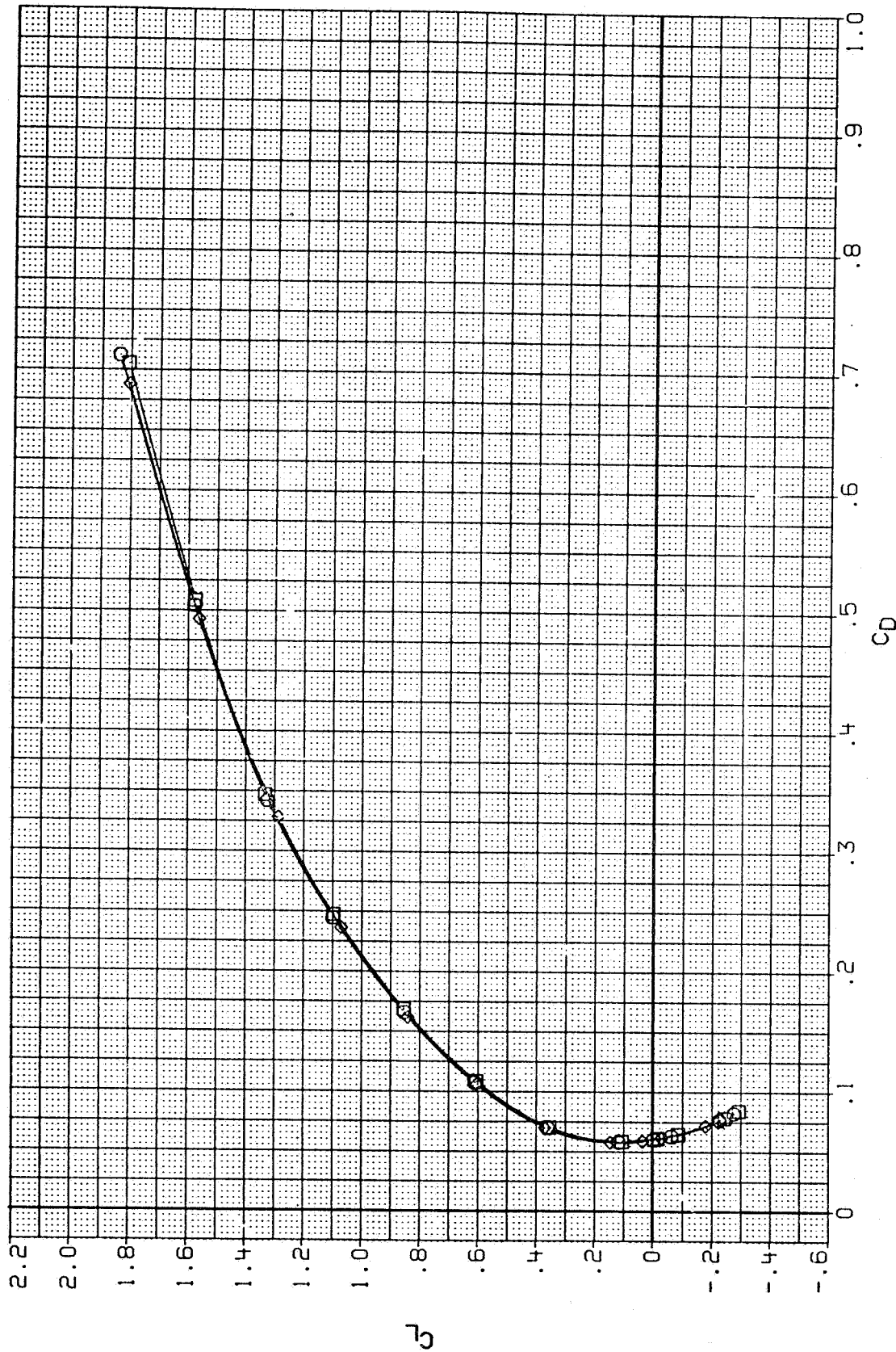


FIG. 51 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = -10 DEGREES, STRAKE S1
MACH = 1.20

SYMBOL CONFIGURATION
 ○ BI SI N WI C1 V (EJECTOR-E205)
 □ BI SI N WI C2 V (EJECTOR-E205)
 ◇ BI SI N WI C3 V (EJECTOR-E205)

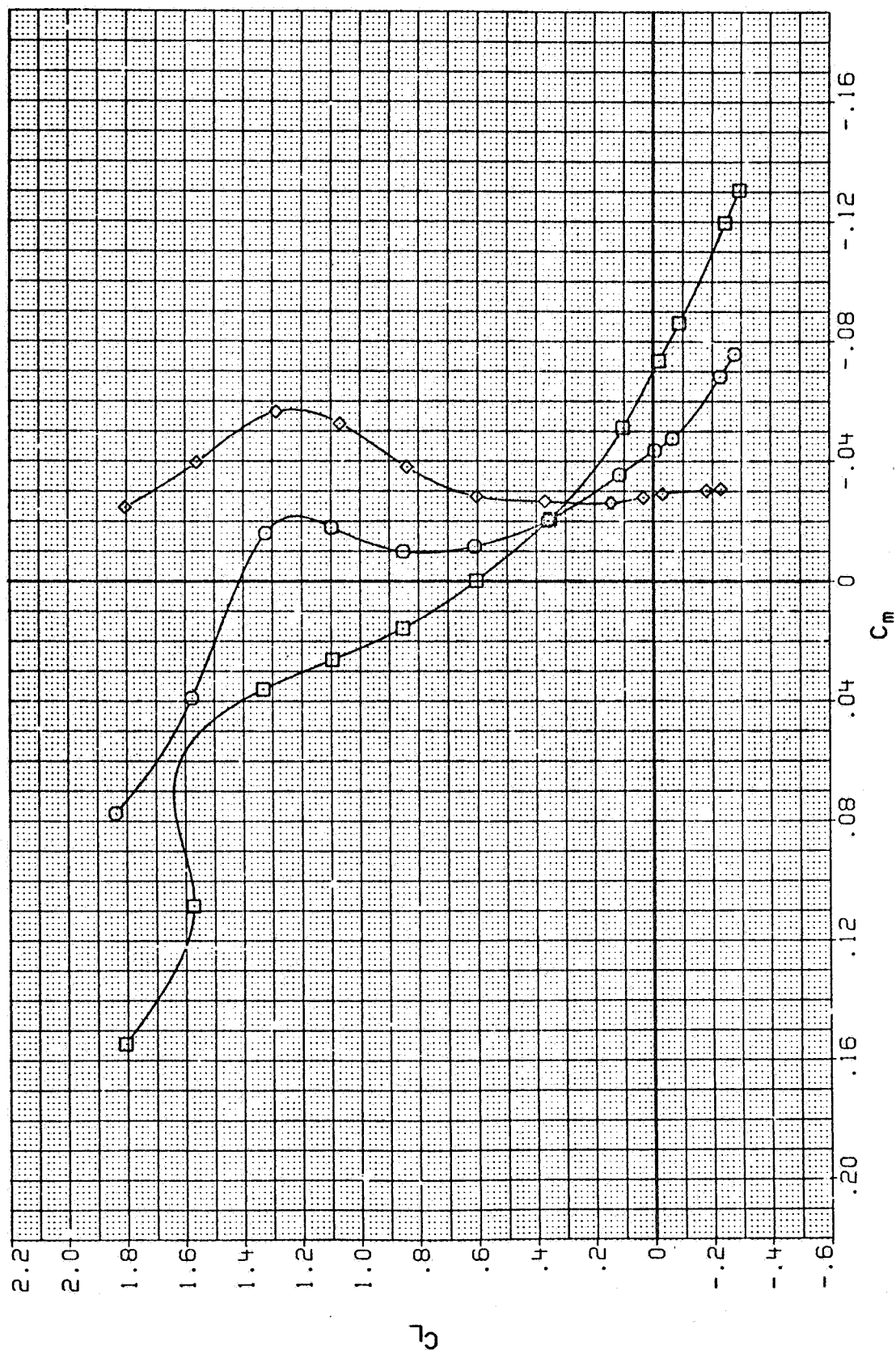


FIG. 51 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S1
 MACH = 1.20

SYMBOL		CONFIGURATION	
□	BI SI N WI C1 V	(EJECTOR-E205)	
□	BI SI N WI C2 V	(EJECTOR-E205)	
◇	BI SI N WI C3 V	(EJECTOR-E205)	

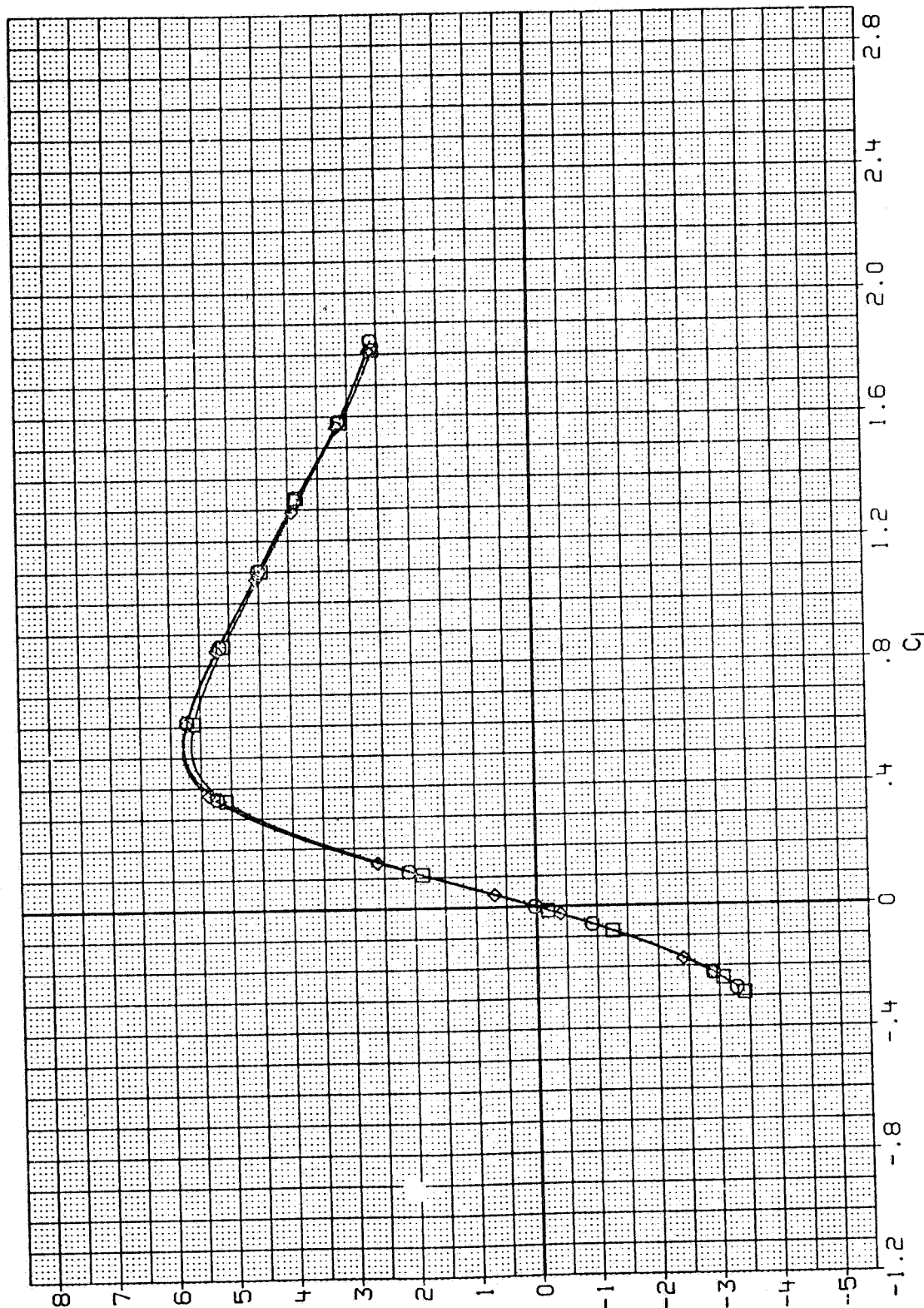


FIG. 51 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = -10 DEGREES, STRAKE SI
MACH = 1.20

SYMBOL CONFIGURATION
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

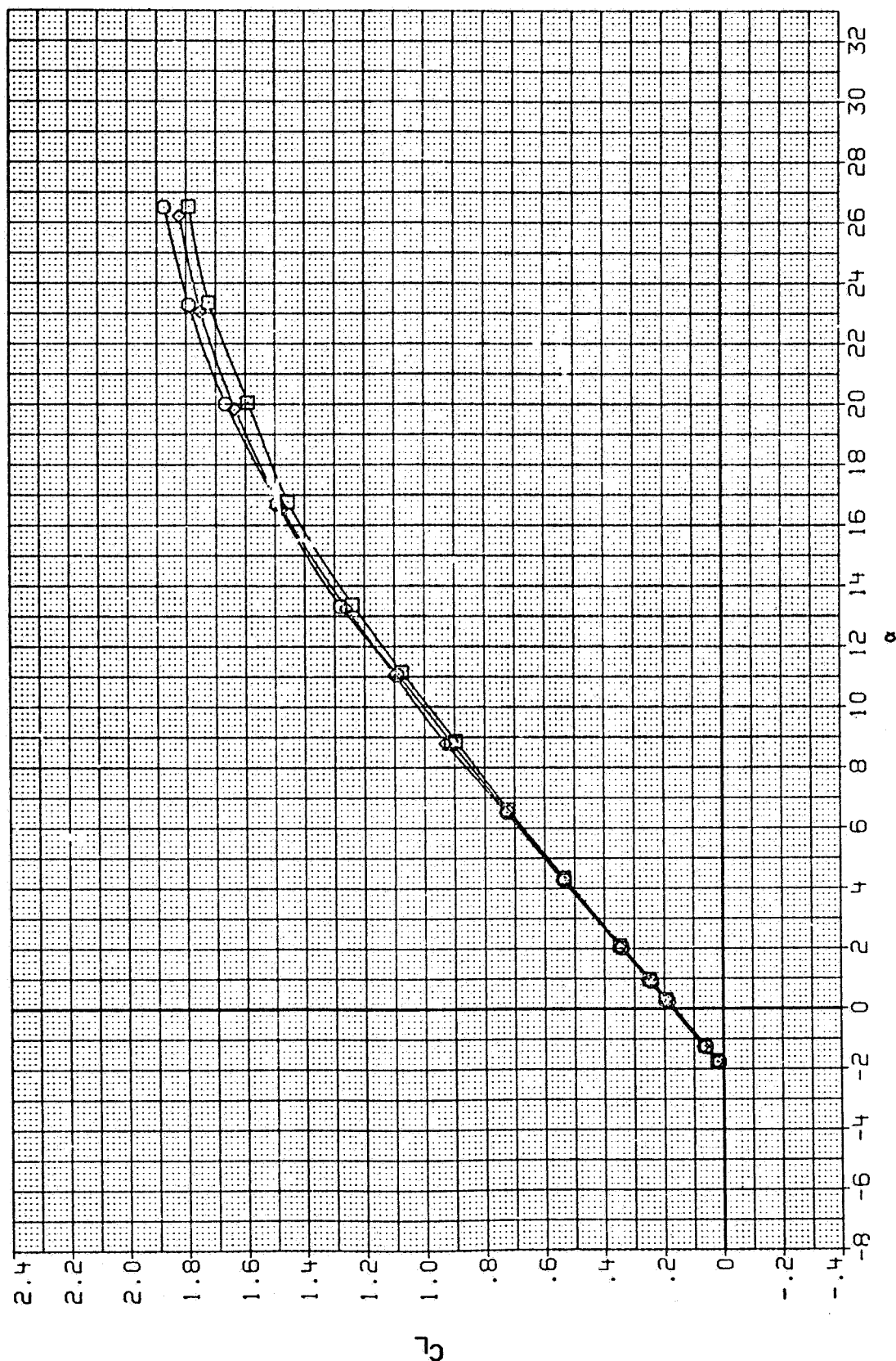


FIG. 52 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S2
 MACH = .60

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

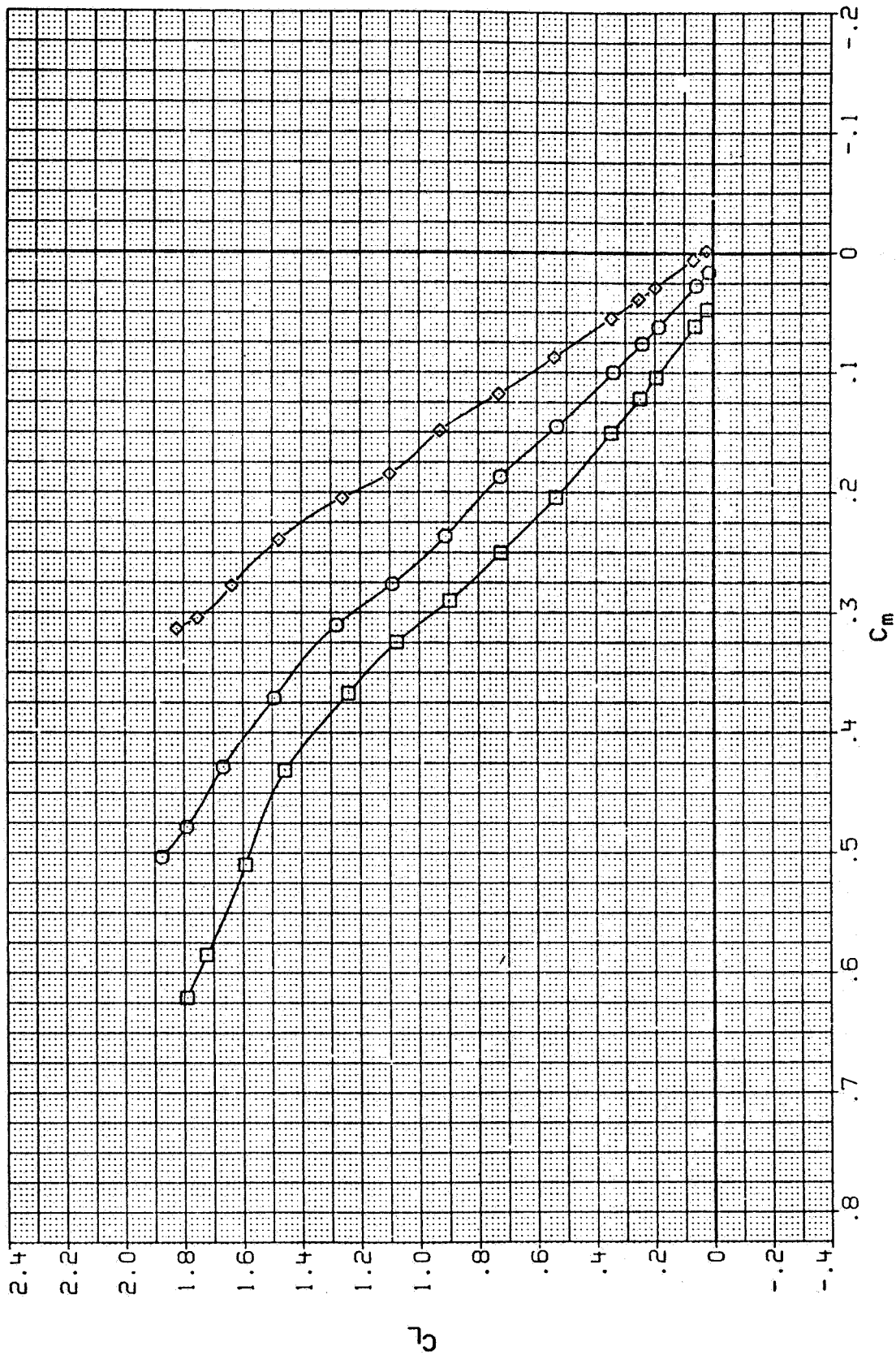


FIG. 52 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S2
 MACH = .60

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

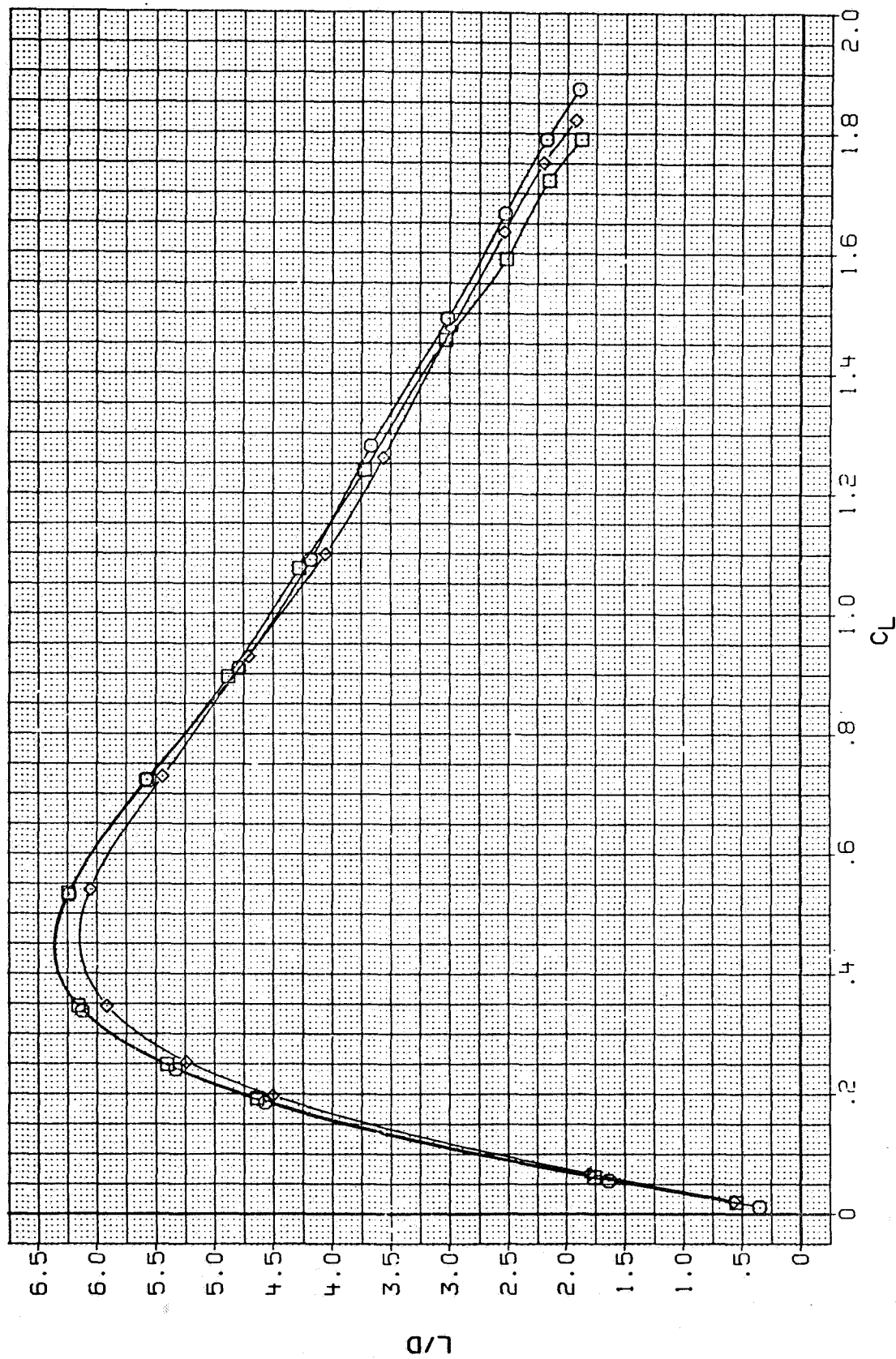


FIG. 52 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S2
 MACH = .60

SYMBOL CONFIGURATION

○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

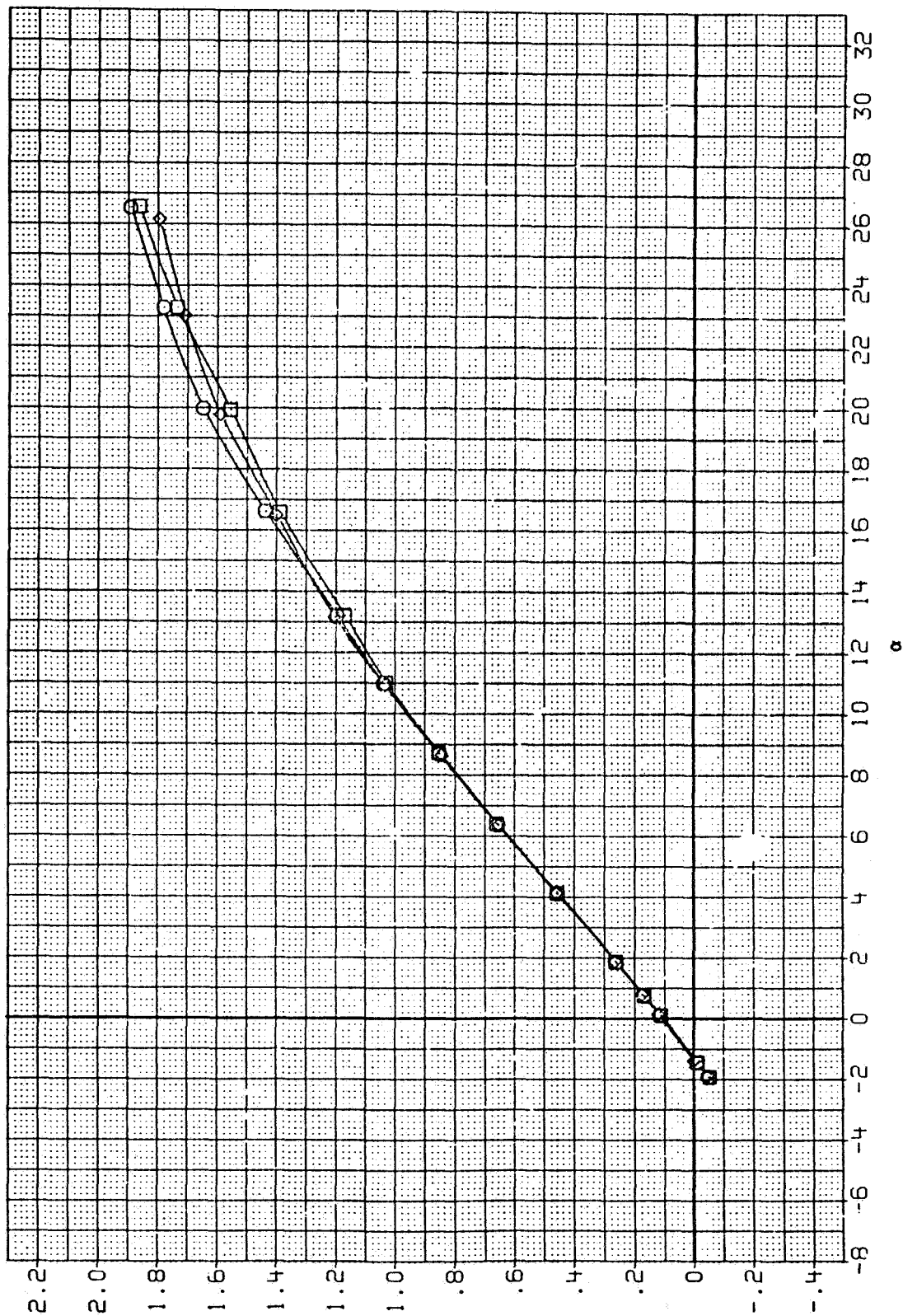


FIG. 53 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = .60

SYMBOL CONFIGURATION

○ B1 S2 N W1 C1 V
 □ B1 S2 N W1 C2 V
 ◇ B1 S2 N W1 C3 V

(EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

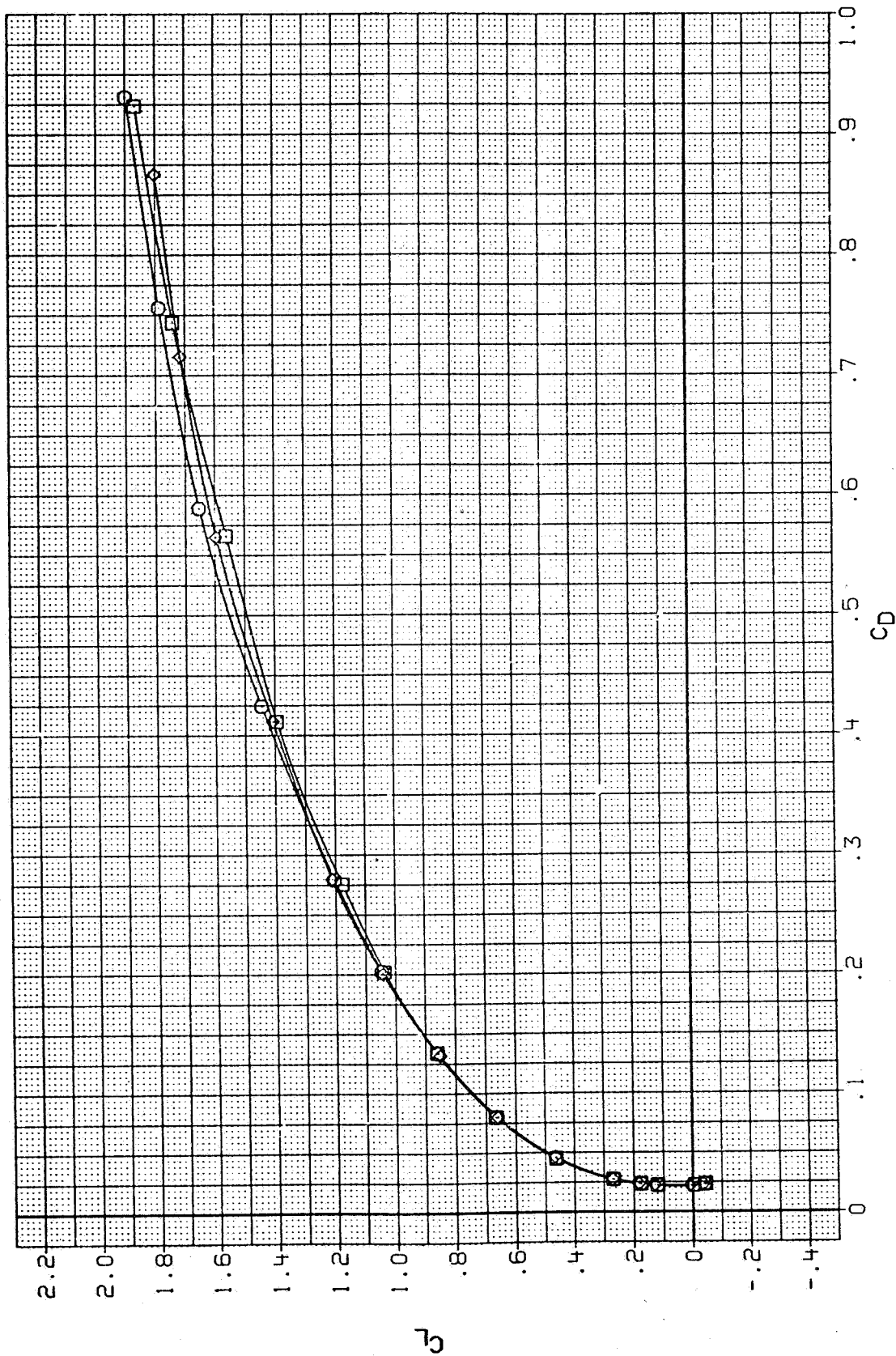


FIG. 53 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = .60

SYMBOL	CONFIGURATION
○	B1 S2 N W1 C1 V (EJECTOR-E205)
□	B1 S2 N W1 C2 V (EJECTOR-E205)
◇	B1 S2 N W1 C3 V (EJECTOR-E205)

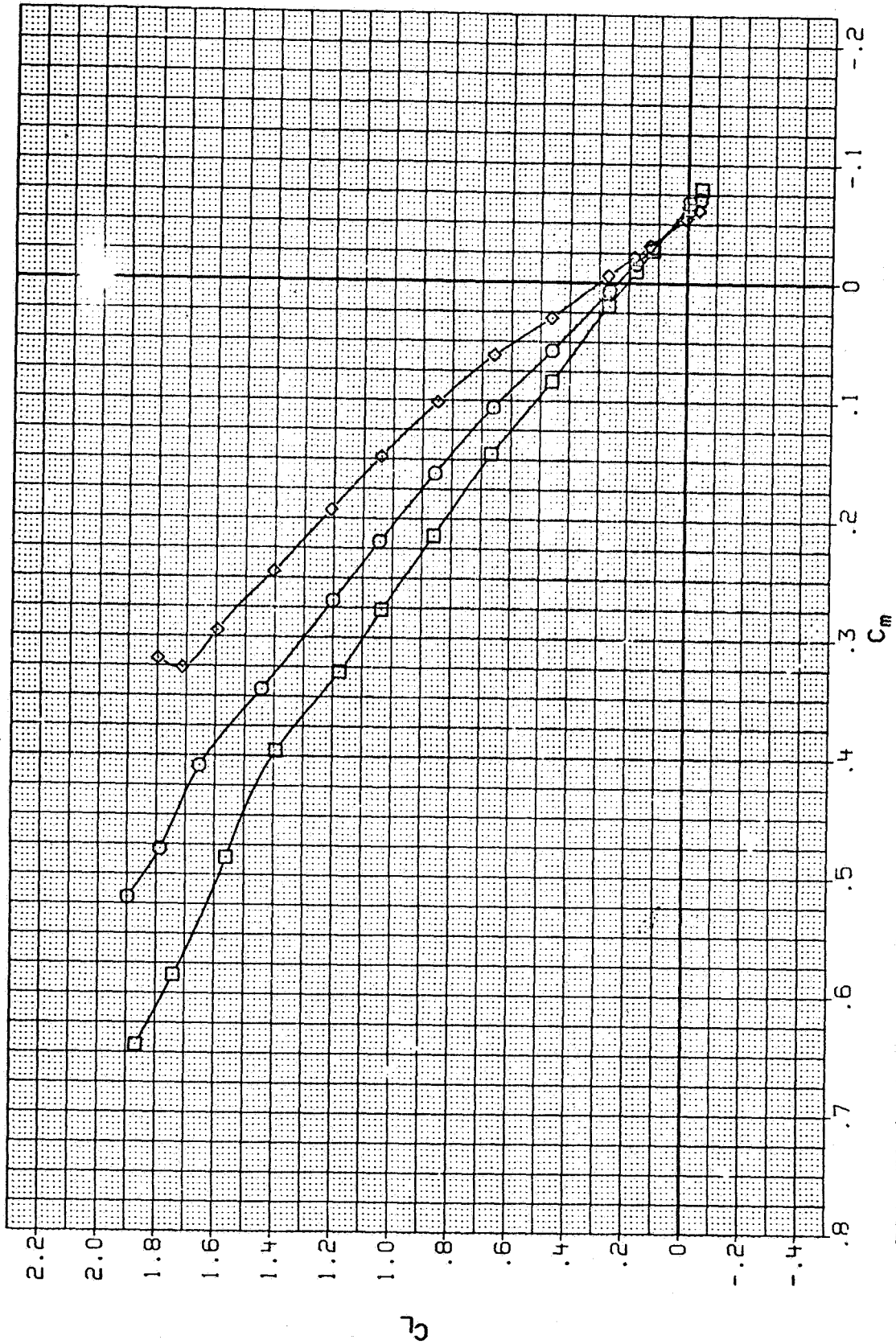


FIG. 53 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = .60

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

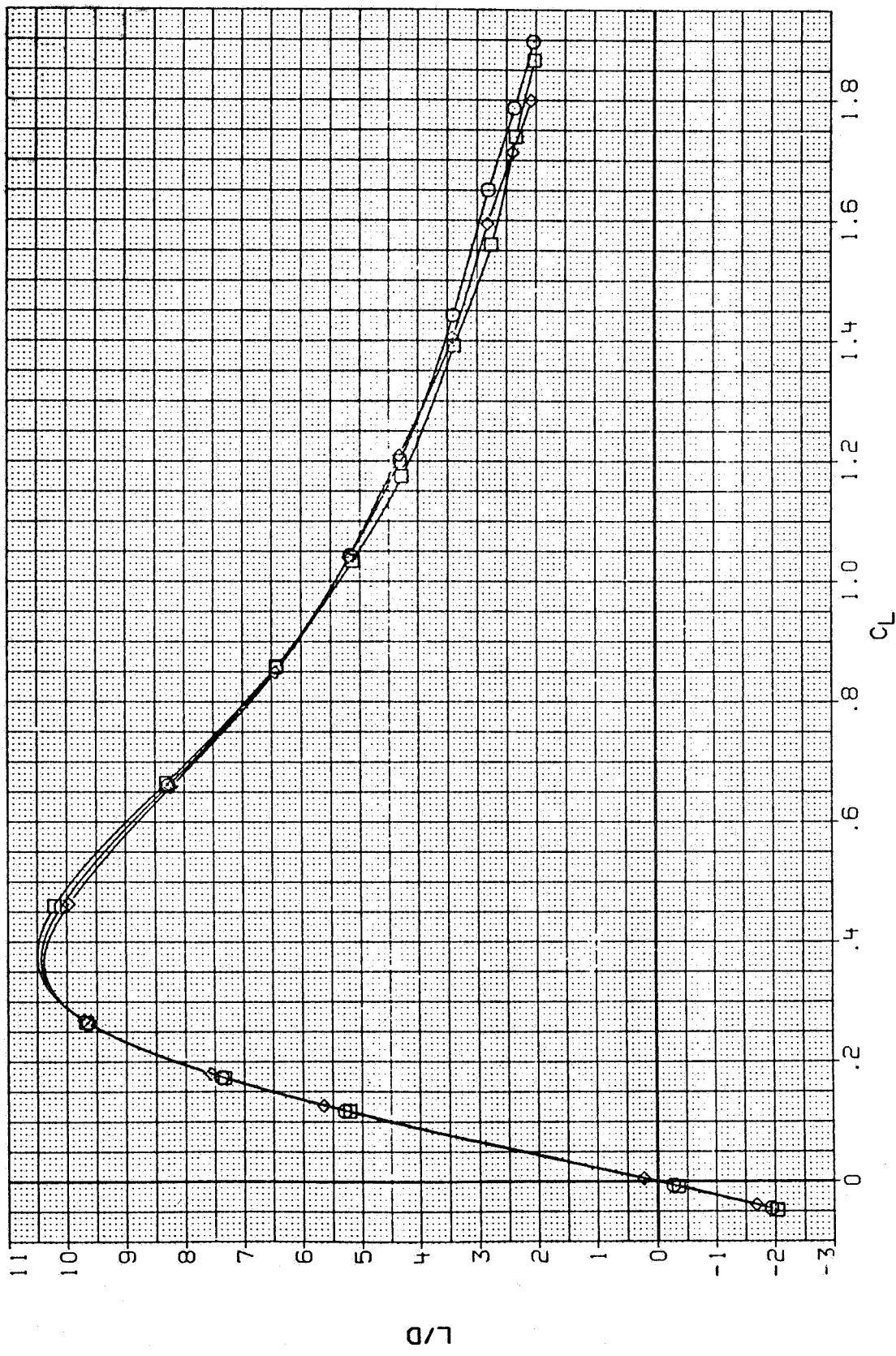


FIG. 53 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = .60

SYMBOL CONFIGURATION
 ○ (EJECTOR-E205)
 □ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

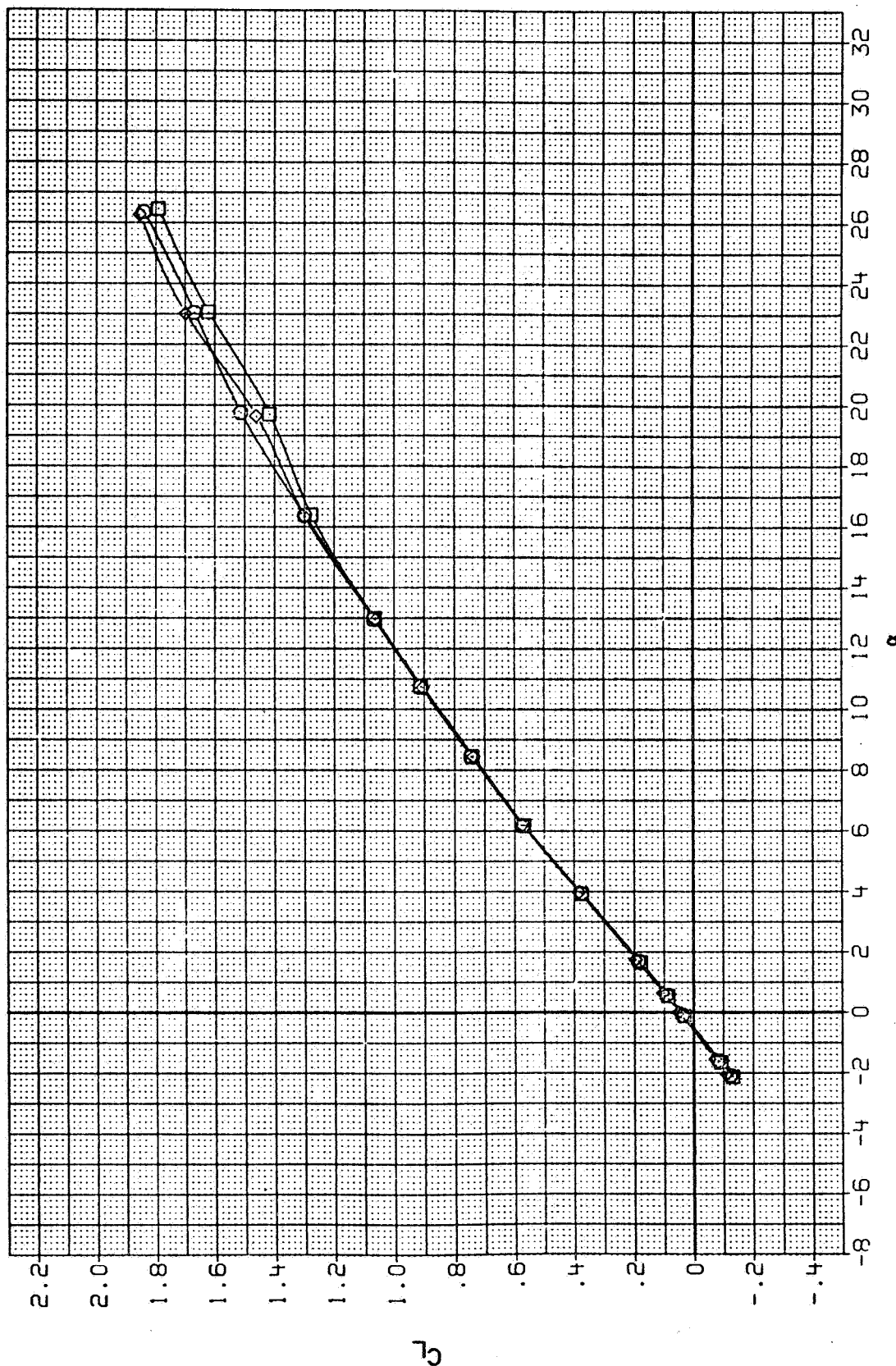


FIG. 54 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = .60

SYMBOL CONFIGURATION
 □ B1 S2 N W1 C1 V
 B1 S2 N W1 C2 V
 ◇ B1 S2 N W1 C3 V
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

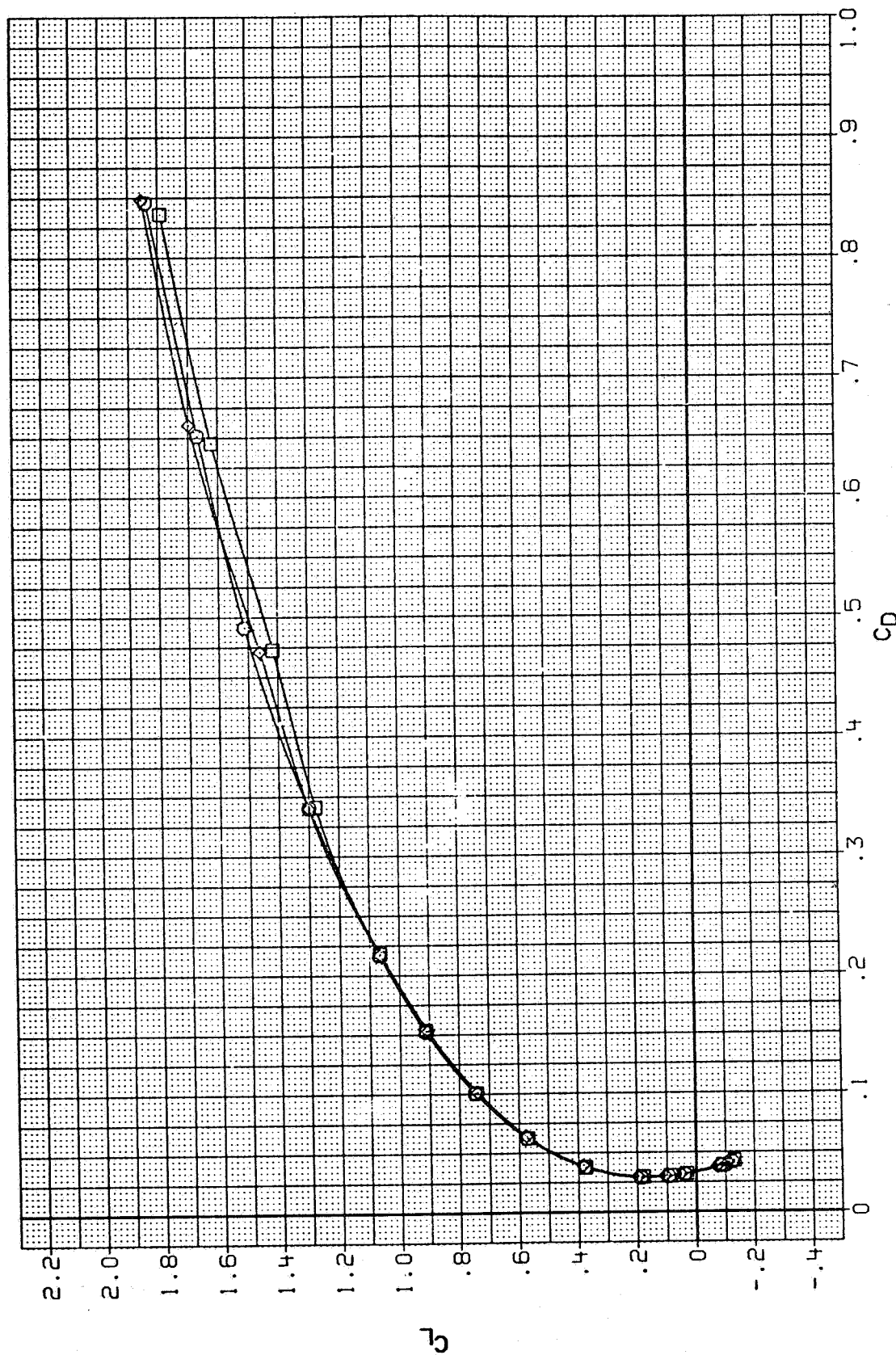


FIG. 54 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = .60

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

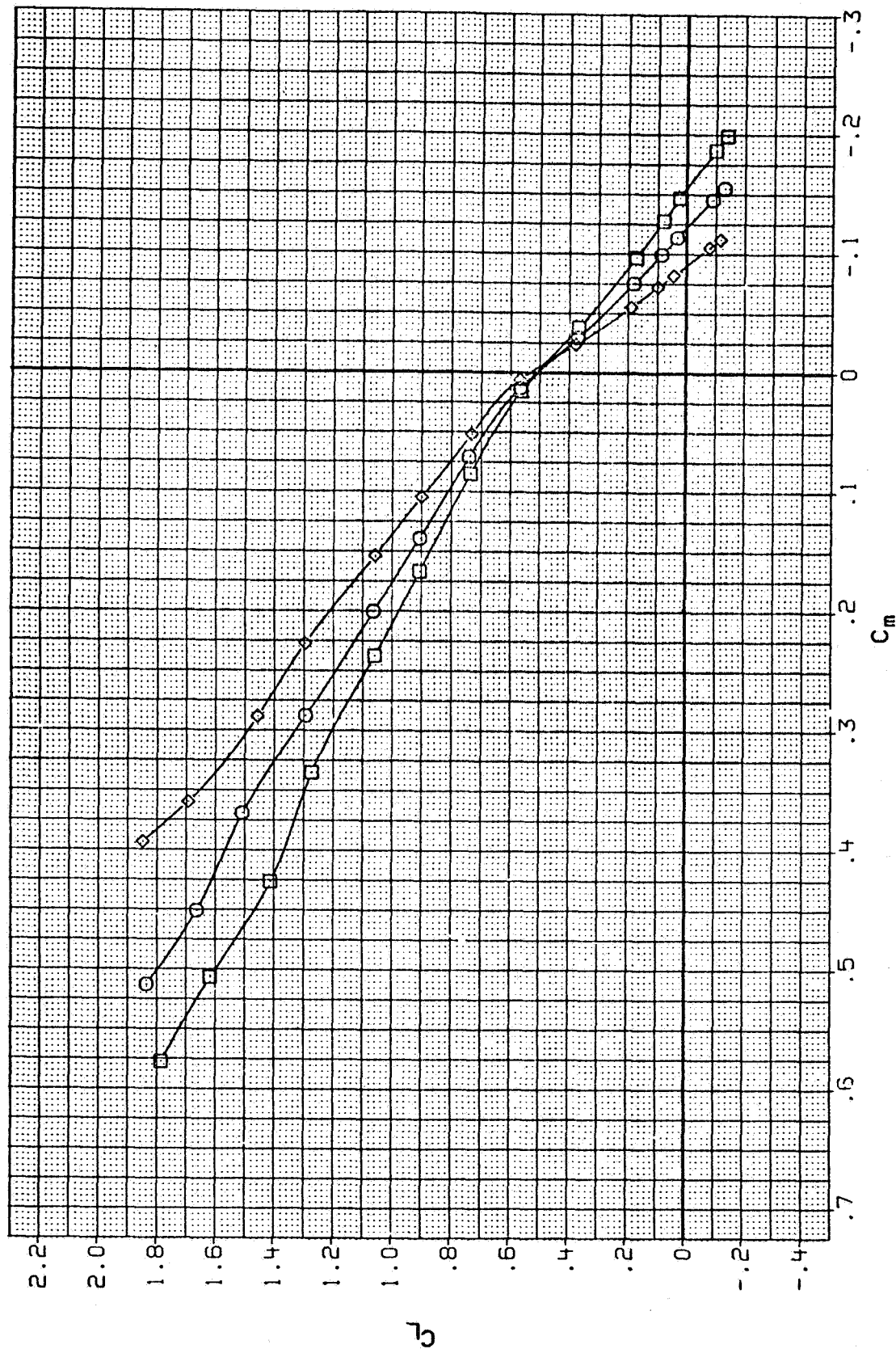


FIG. 54 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = .60

SYMBOL	CONFIGURATION
○	B1 S2 N W1 C1 V (EJECTOR-E205)
□	B1 S2 N W1 C2 V (EJECTOR-E205)
◇	B1 S2 N W1 C3 V (EJECTOR-E205)

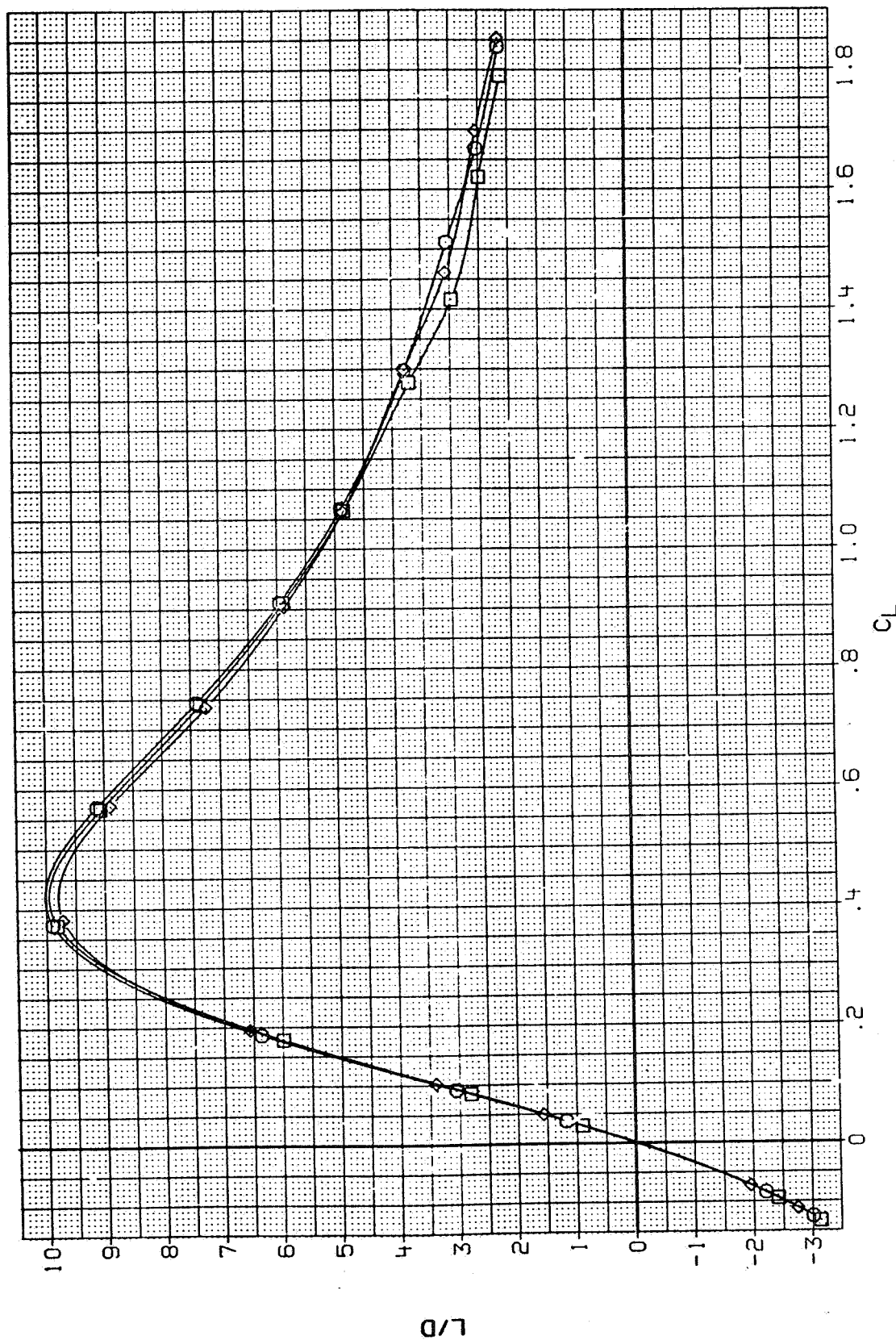


FIG. 54 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = .60

SYMBOL CONFIGURATION

○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

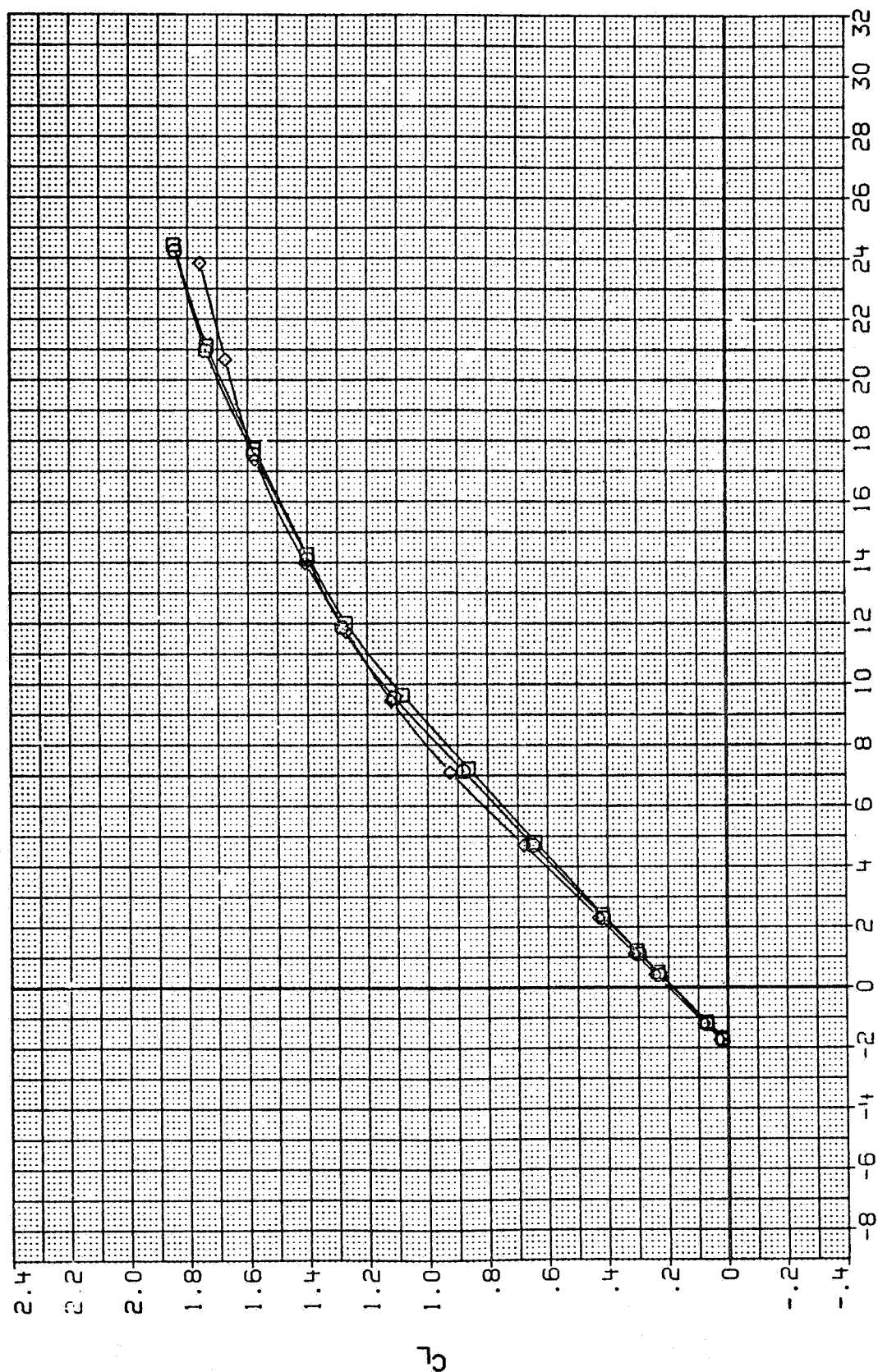


FIG. 55 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S2

MACH = .90

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V
 □ B1 S2 N W1 C2 V
 ◇ B1 S2 N W1 C3 V
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

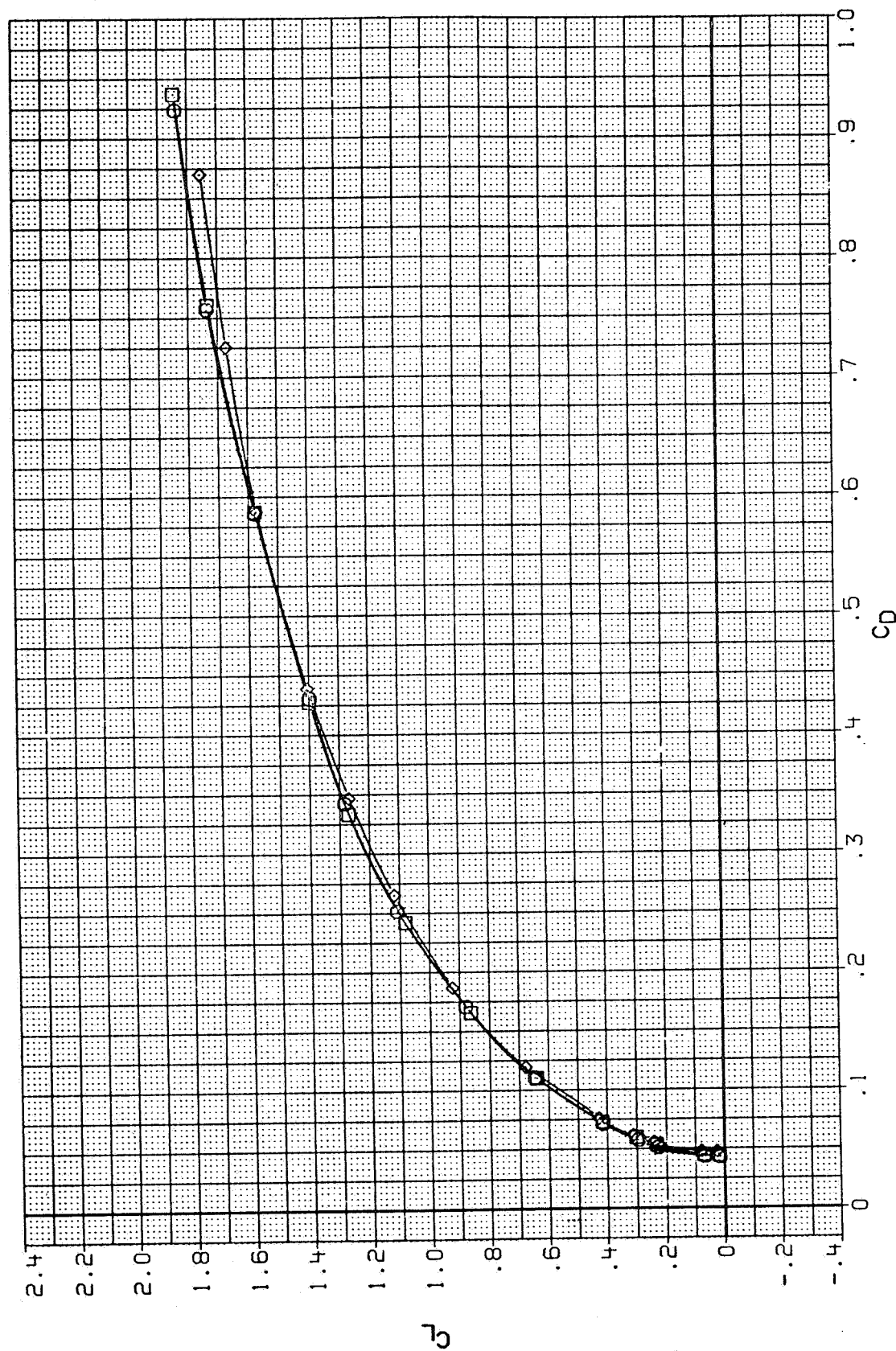


FIG. 55 CANARD LOCATION EFFECTS; LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S2
 MACH = .90

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V
 (EJECTOR-E205)
 ◇ B1 S2 N W1 C2 V
 (EJECTOR-E205)
 □ B1 S2 N W1 C3 V
 (EJECTOR-E205)

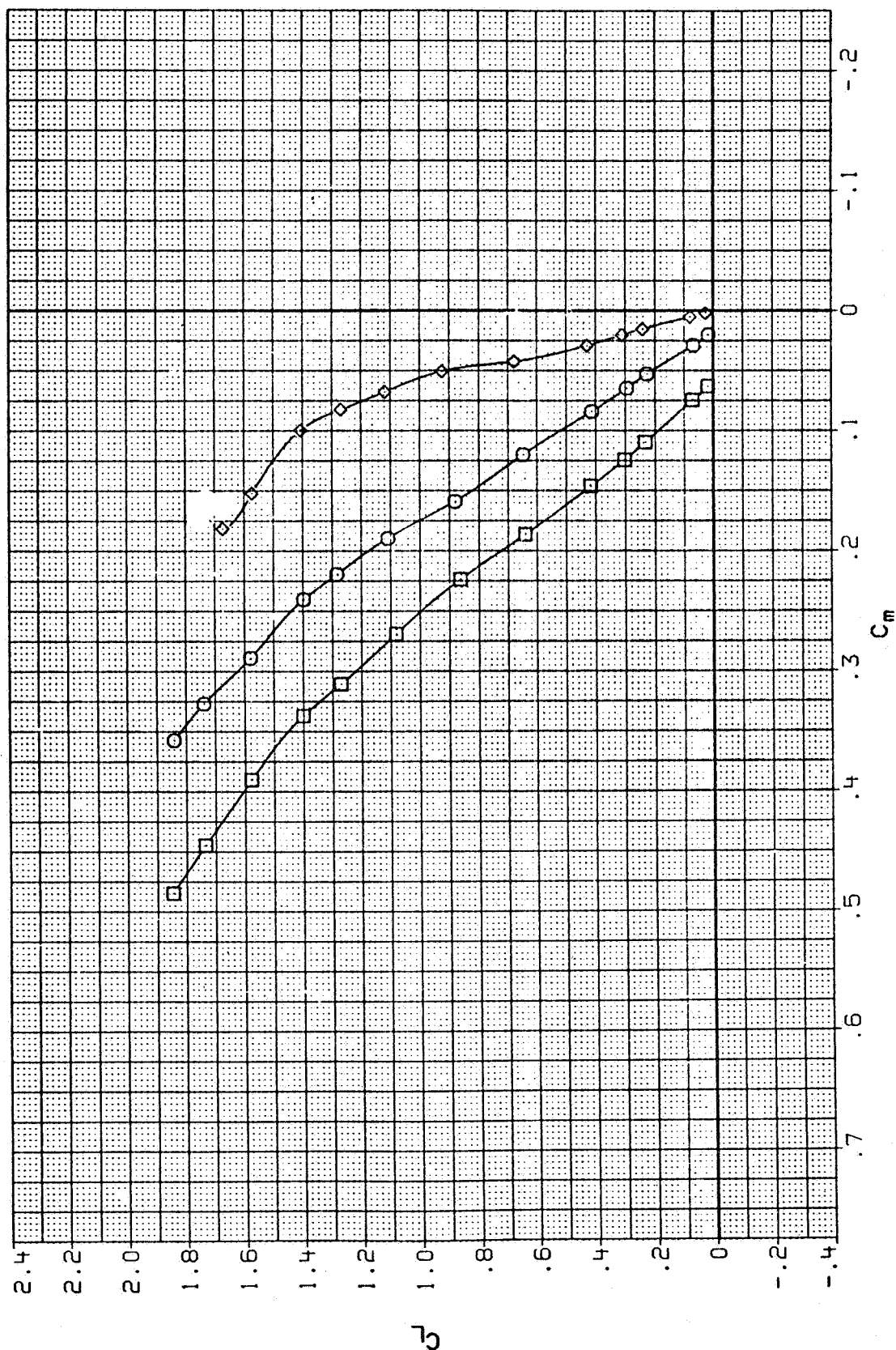


FIG. 55 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S2
 MACH = .90

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V
 □ B1 S2 N W1 C2 V
 ◇ B1 S2 N W1 C3 V
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

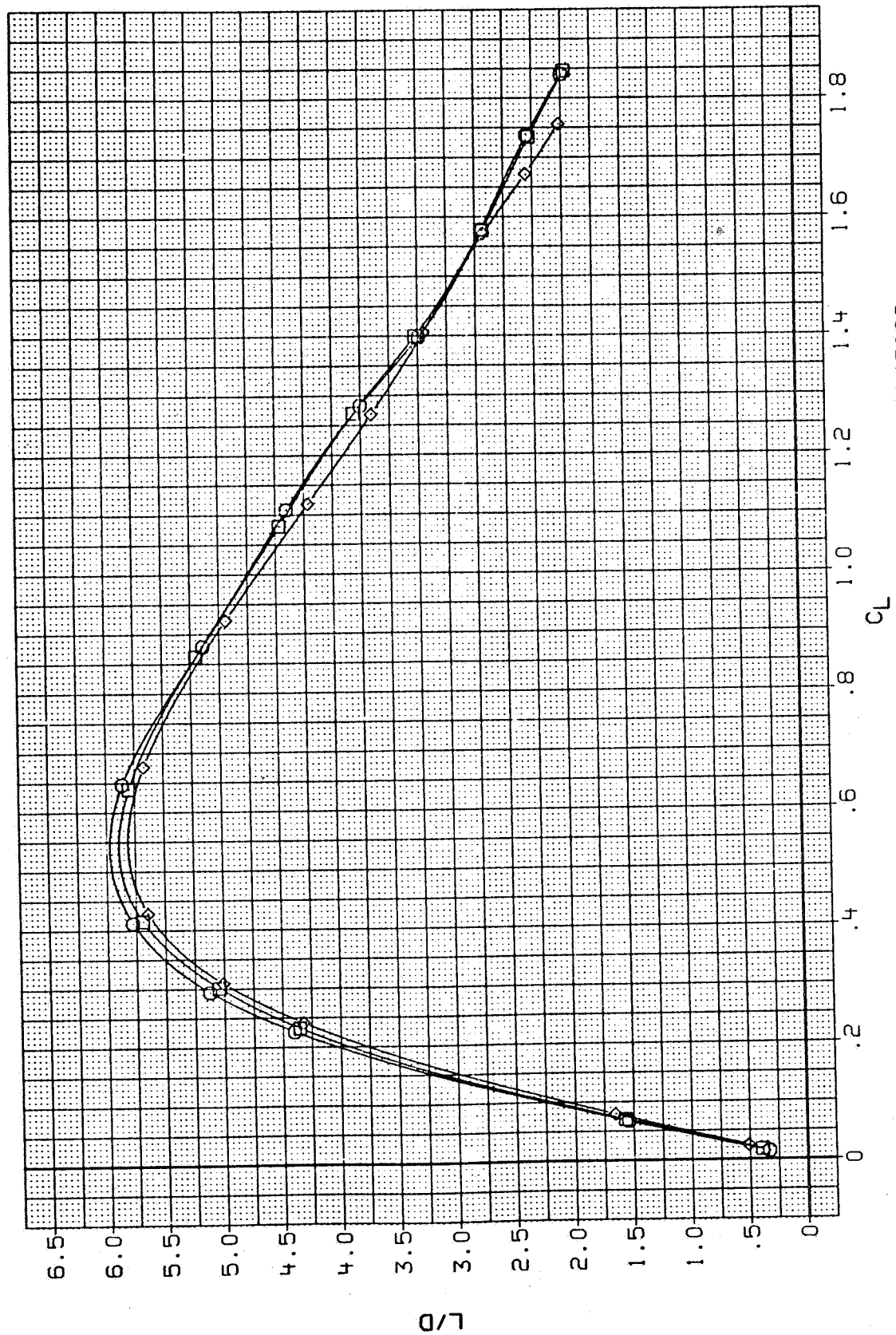


FIG. 55 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S2

MACH = .90

O/L

SYMBOL CONFIGURATION

○ (EJECTOR-E205)
 □ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

B1 S2 N W1 C1 V
 B1 S2 N W1 C2 V
 B1 S2 N W1 C3 V

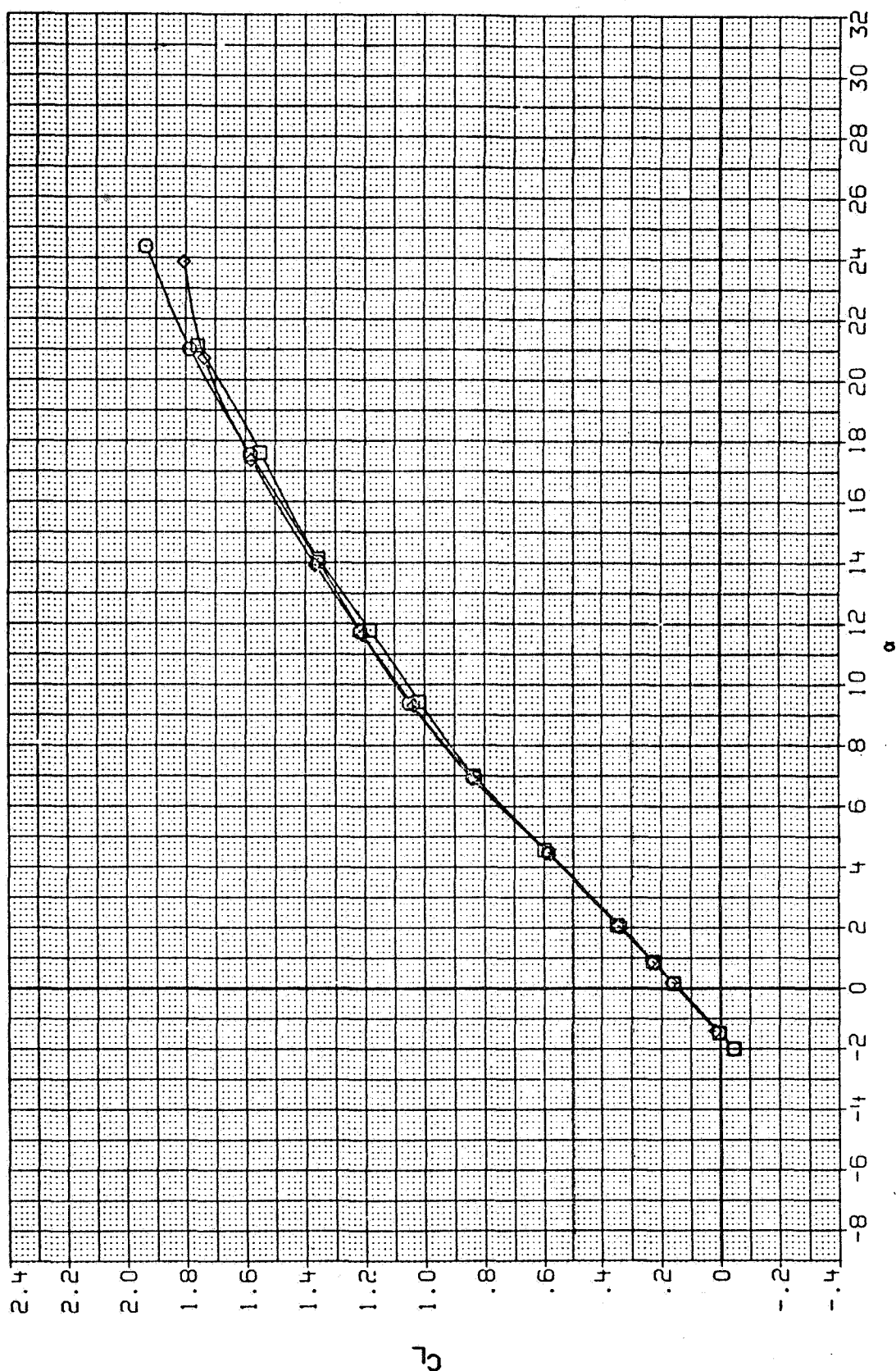


FIG. 56 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = .90

SYMBOL CONFIGURATION

○ B1 S2 N W1 C1 V (EJECTOR-E205)

◇ B1 S2 N W1 C2 V (EJECTOR-E205)

◇ B1 S2 N W1 C3 V (EJECTOR-E205)

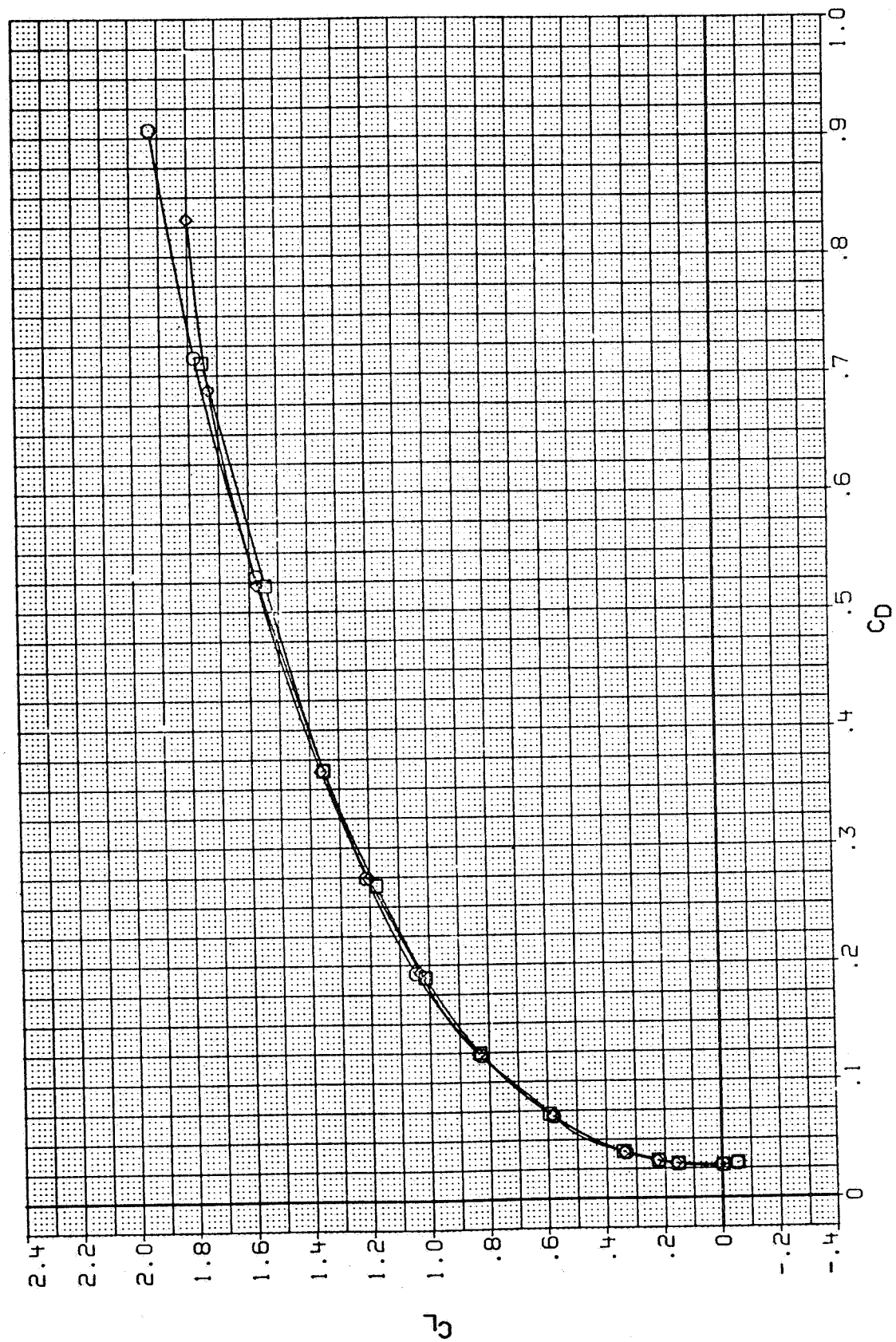


FIG. 56 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 0 DEGREES, STRAKE S2

MACH = .90

SYMBOL CONFIGURATION

○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

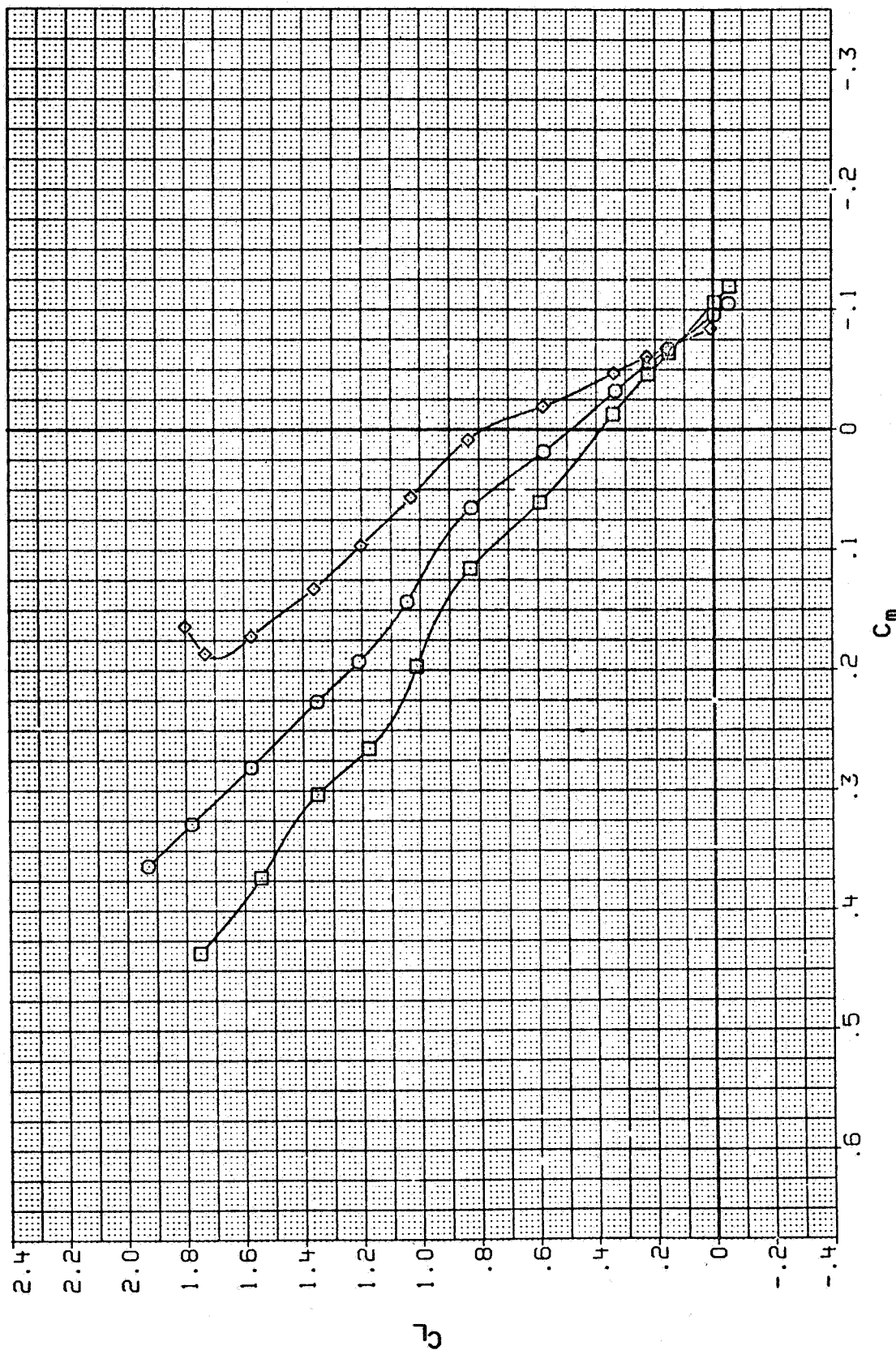


FIG. 56 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = .90

SYMBOL CONFIGURATION
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)
 B1 S2 N W1 C1 V
 B1 S2 N W1 C2 V
 B1 S2 N W1 C3 V

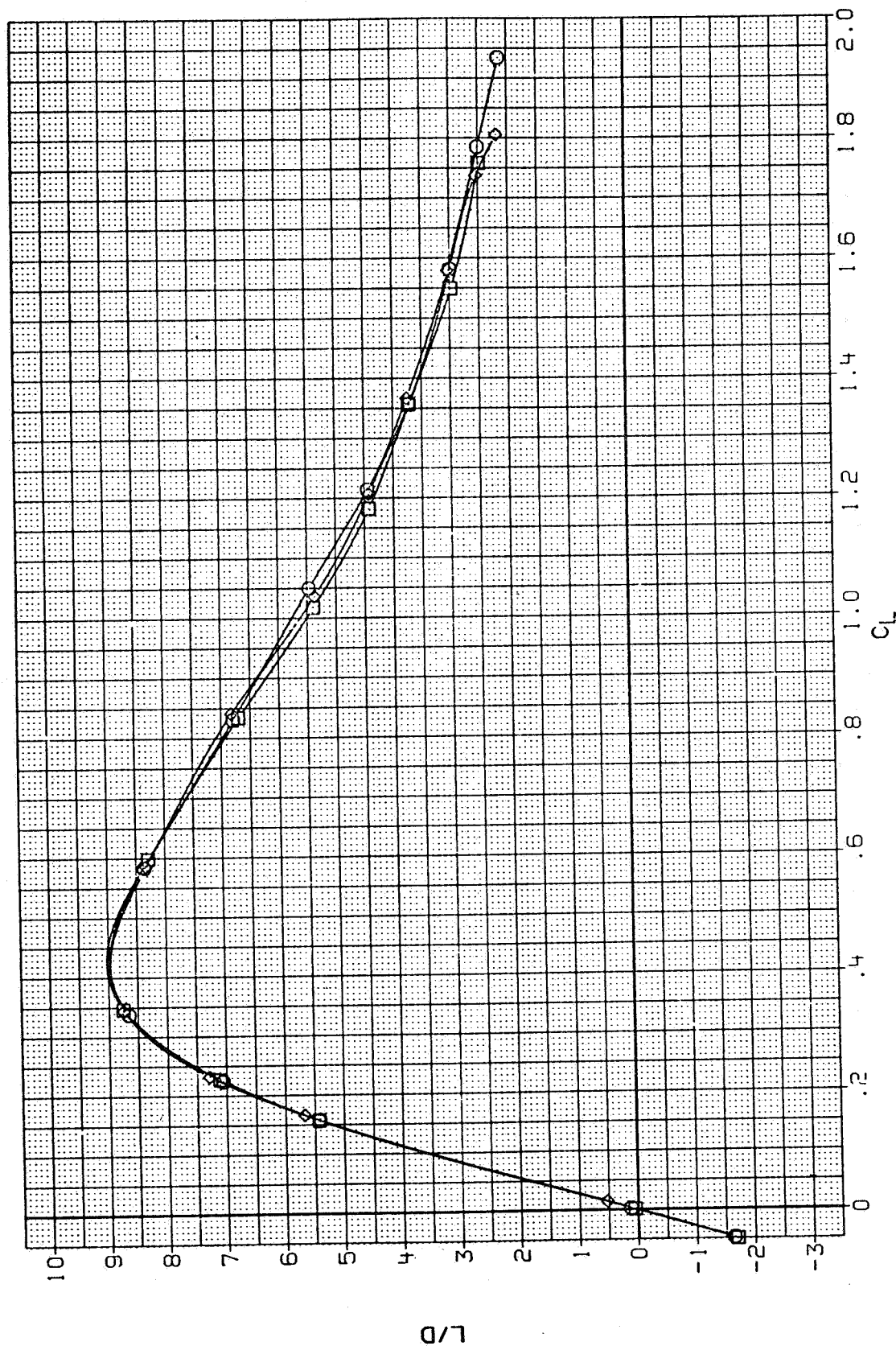


FIG. 56 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = .90

SYMBOL CONFIGURATION

○ (EJECTOR-E205)
 □ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

B1 S2 N W1 C1 V
 B1 S2 N W1 C2 V
 B1 S2 N W1 C3 V

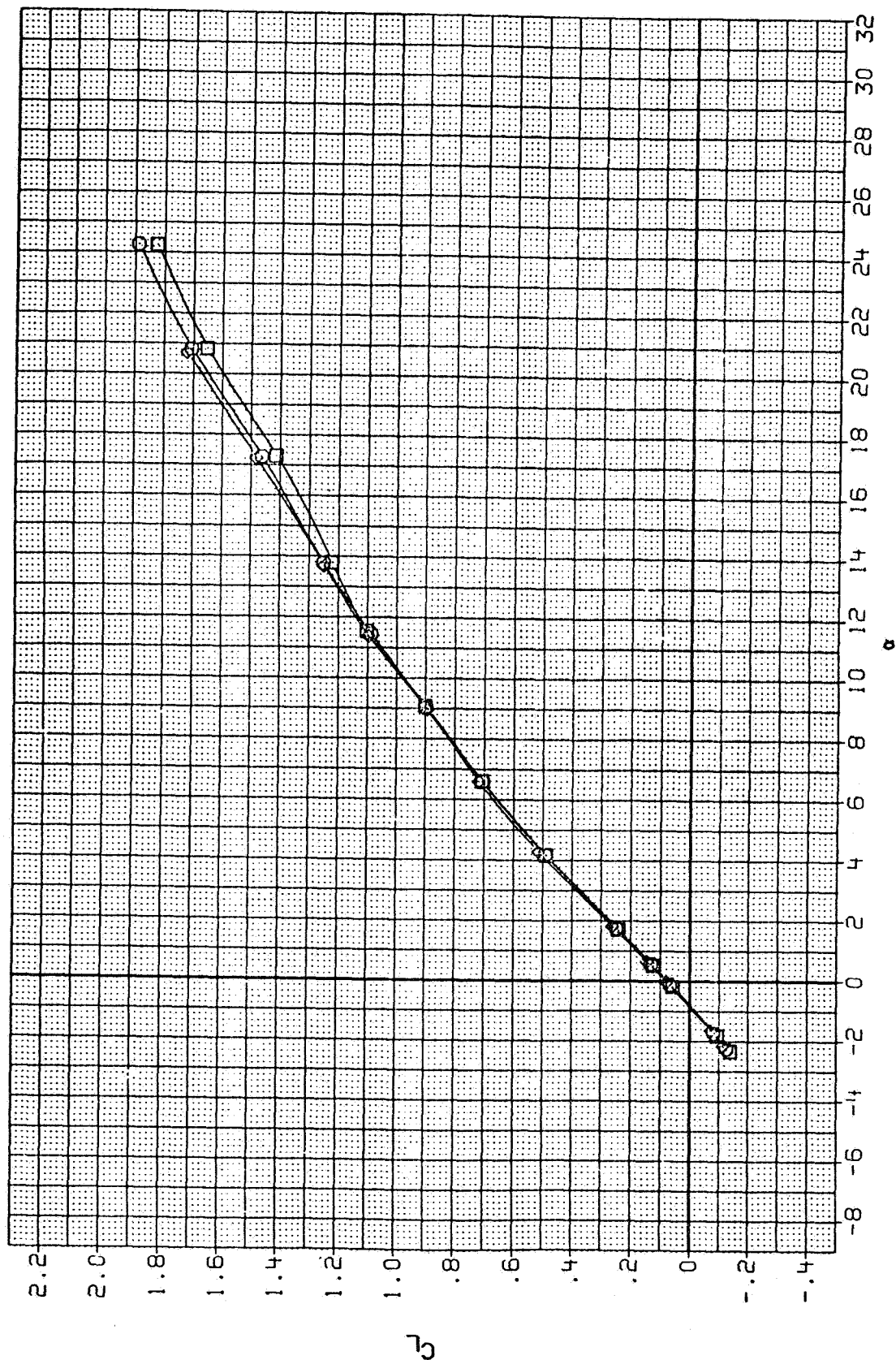


FIG. 57 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = .90

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V
 □ B1 S2 N W1 C2 V
 ◇ B1 S2 N W1 C3 V

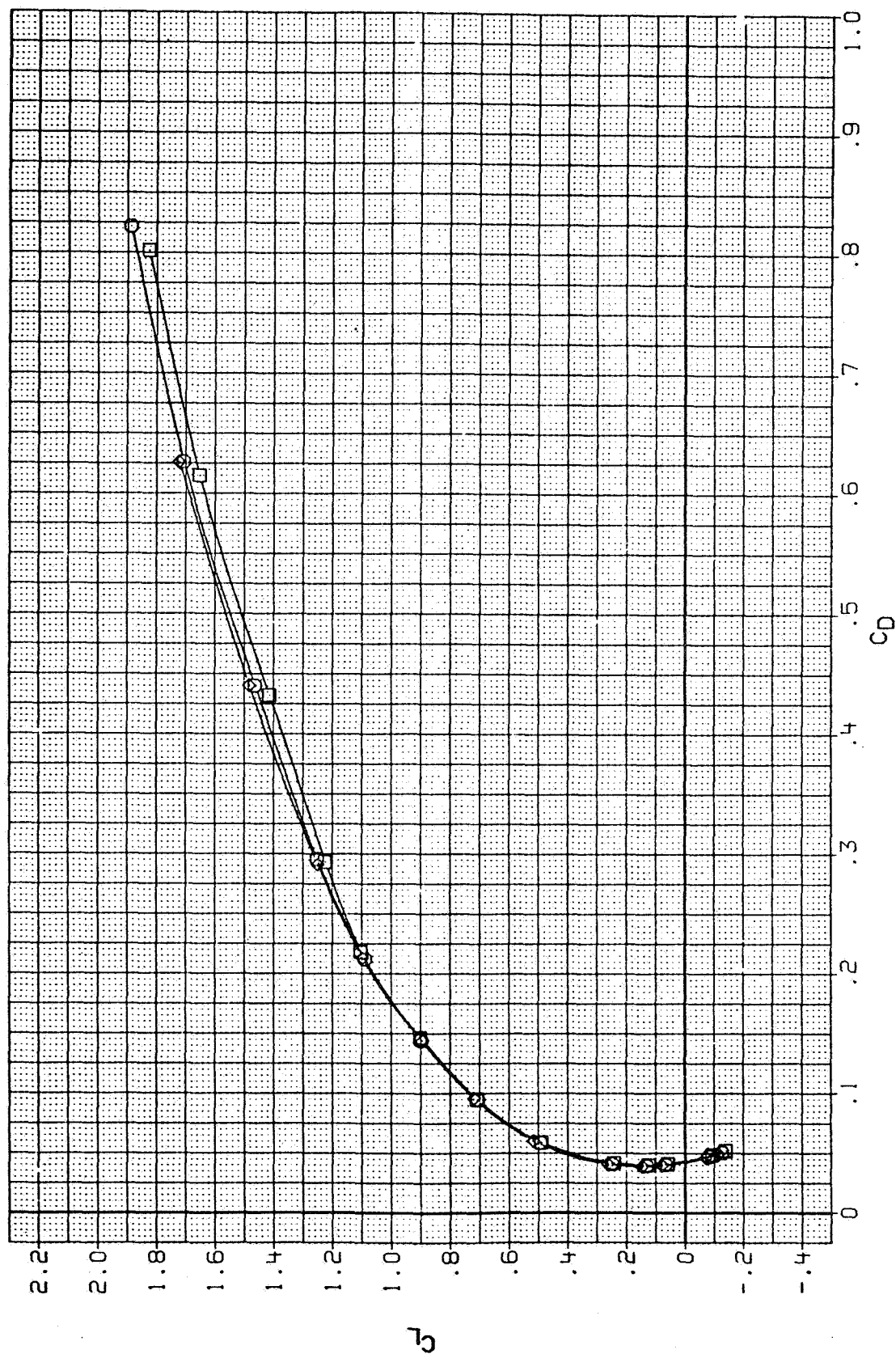


FIG. 57 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = .90

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

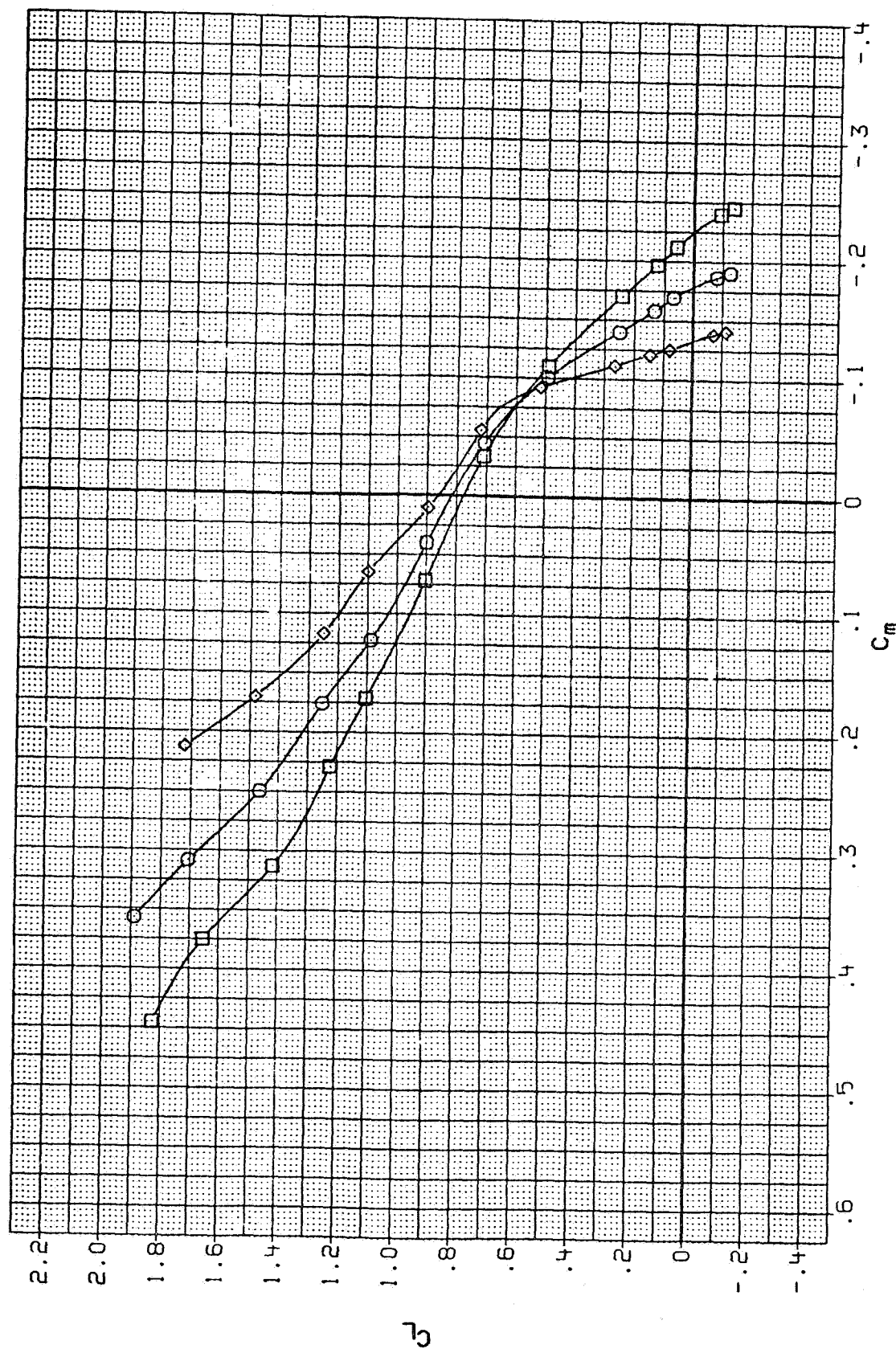


FIG. 57 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = .90

SYMBOL CONFIGURATION
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

B1 S2 N W1 C1 V
 B1 S2 N W1 C2 V
 B1 S2 N W1 C3 V

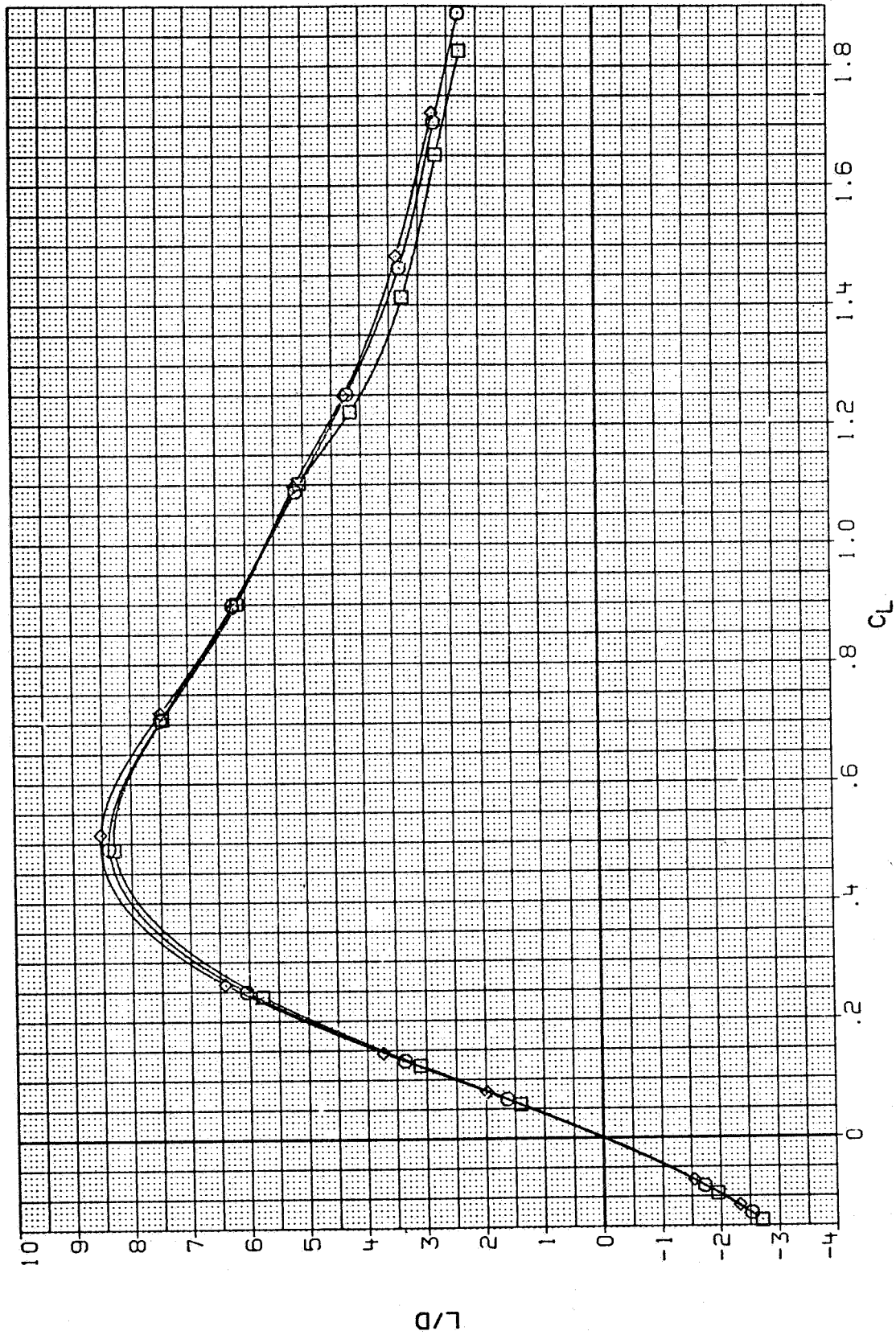


FIG. 57 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = .90

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SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

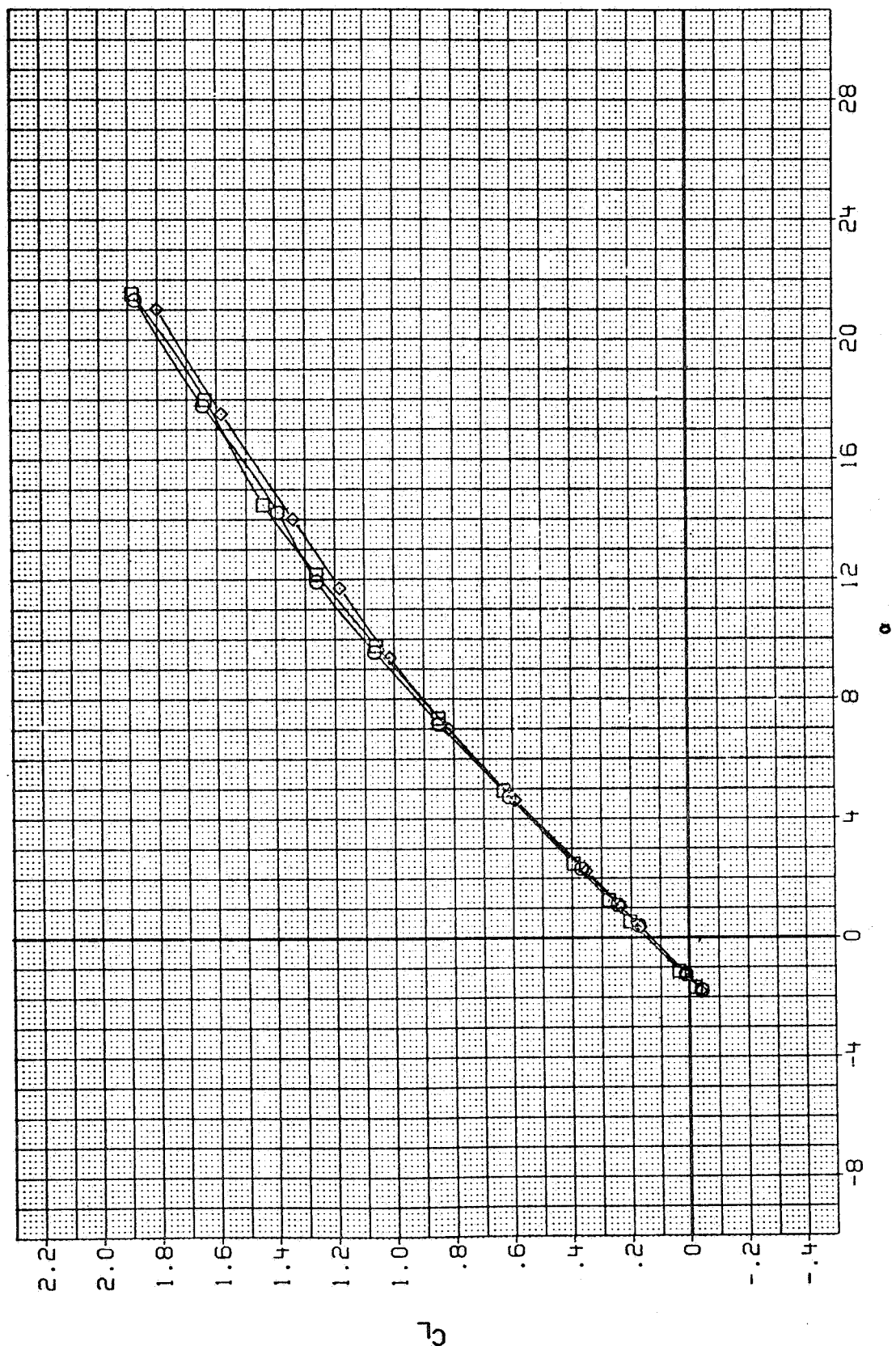
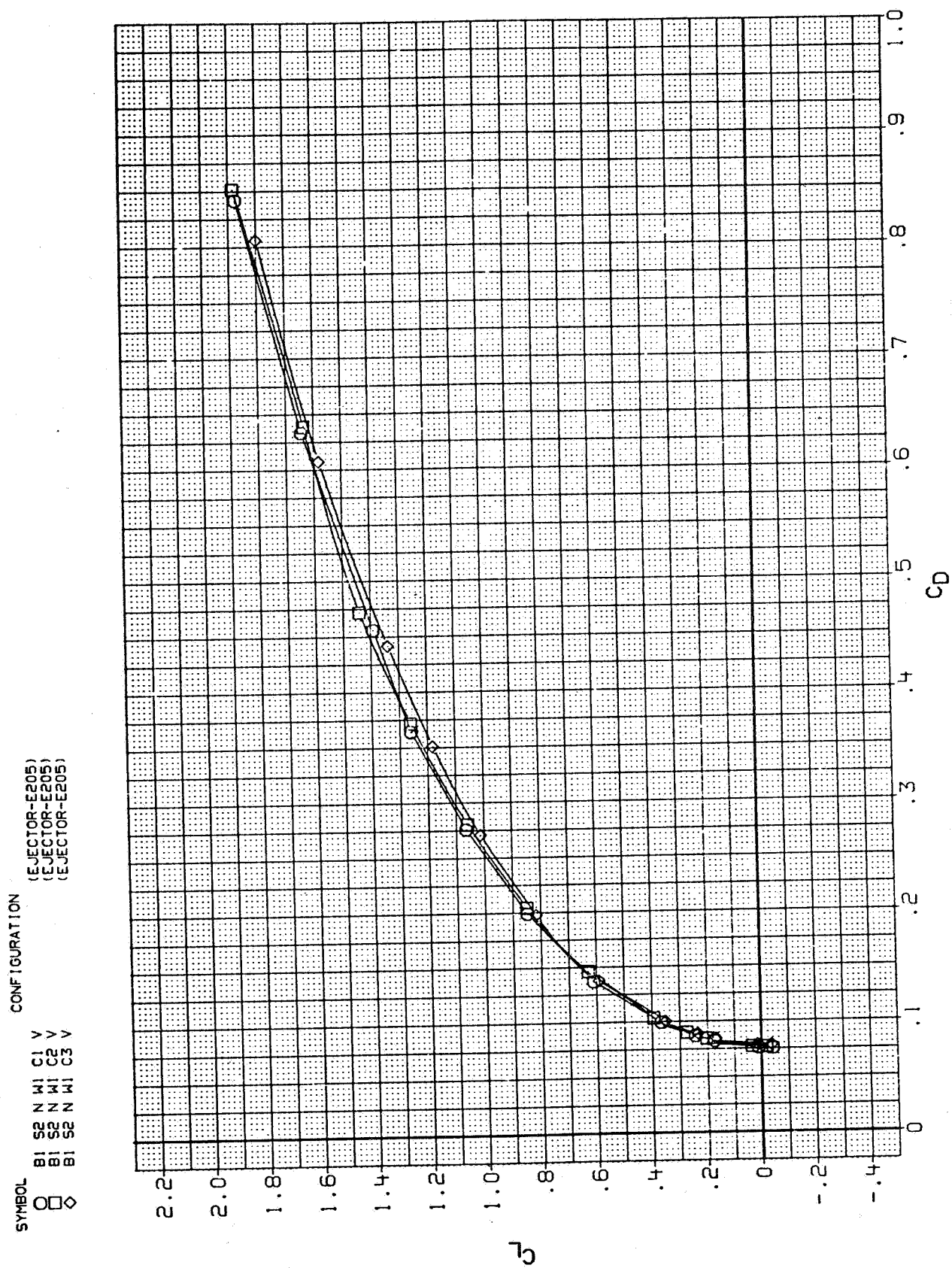


FIG. 58 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S2
 MACH = 1.20



SYMBOL CONFIGURATION

○ B1 S2 N W1 C1 V
 □ B1 S2 N W1 C2 V
 ◇ B1 S2 N W1 C3 V

(EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

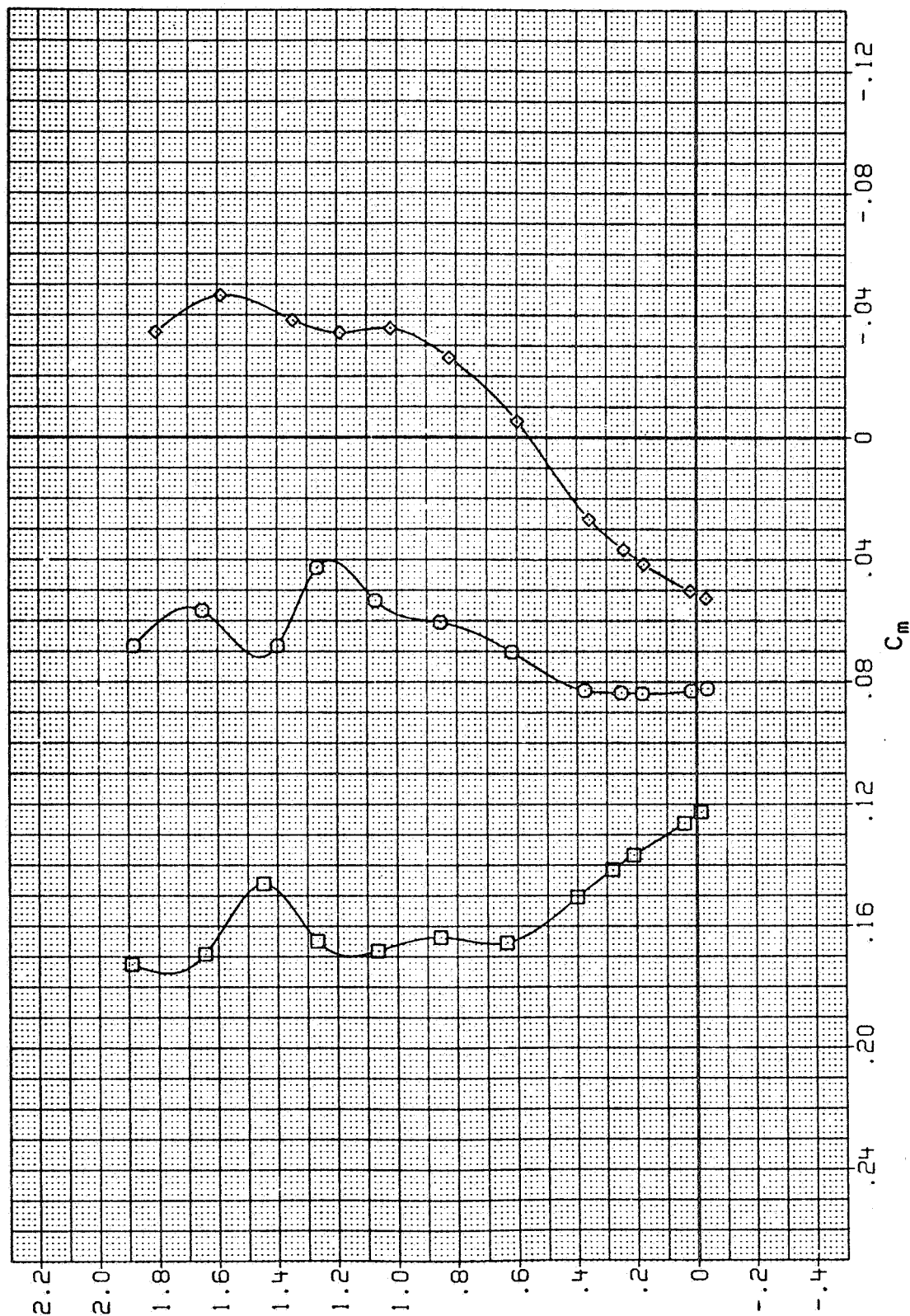


FIG. 58 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S2
MACH = 1.20

SYMBOL CONFIGURATION

B1 S2 N W1 C1 V (EJECTOR-E205)
 B1 S2 N W1 C2 V (EJECTOR-E205)
 B1 S2 N W1 C3 V (EJECTOR-E205)

○
 □
 ◇

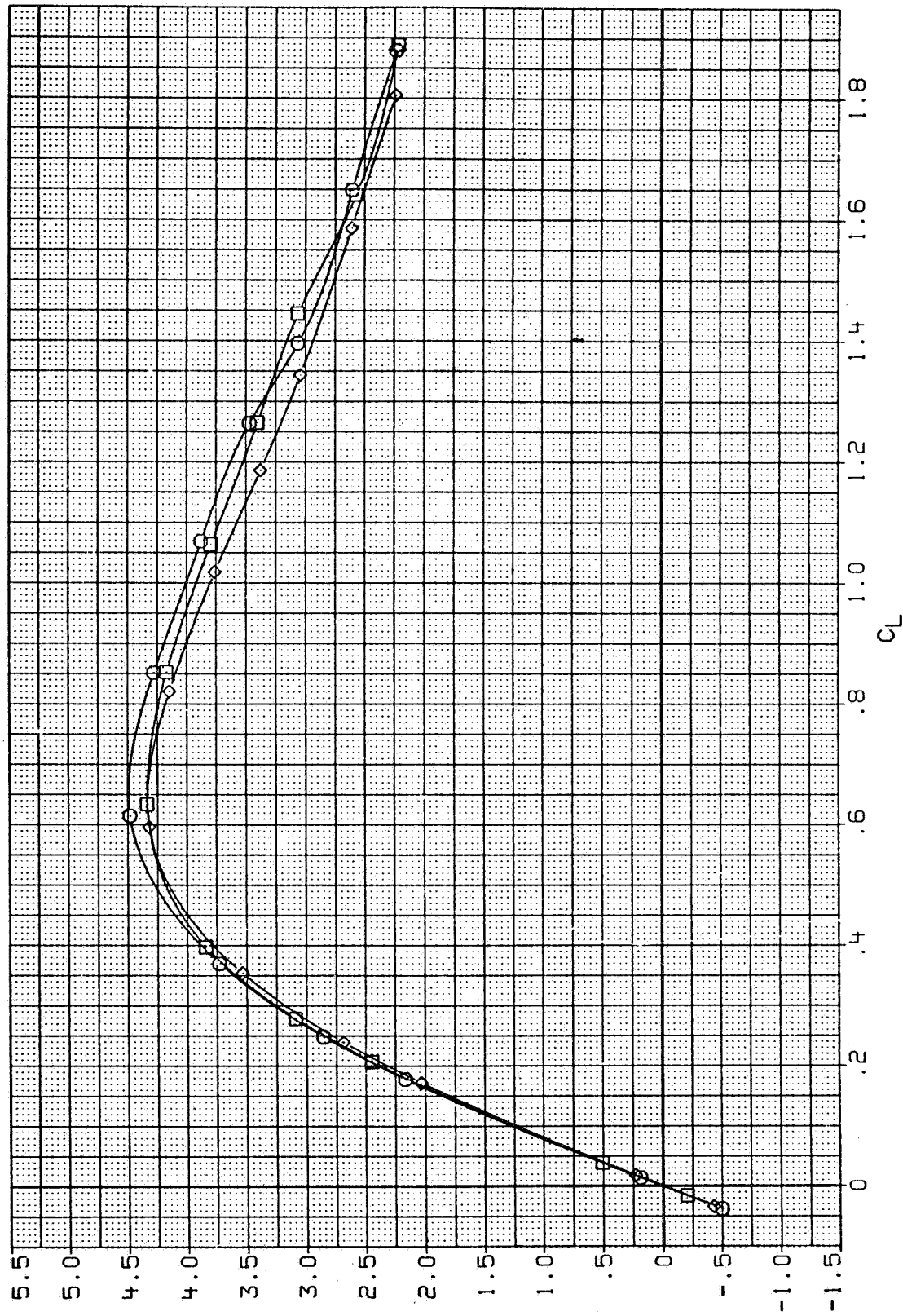


FIG. 58 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S2
 MACH = 1.20

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V
 □ B1 S2 N W1 C2 V
 ◇ B1 S2 N W1 C3 V

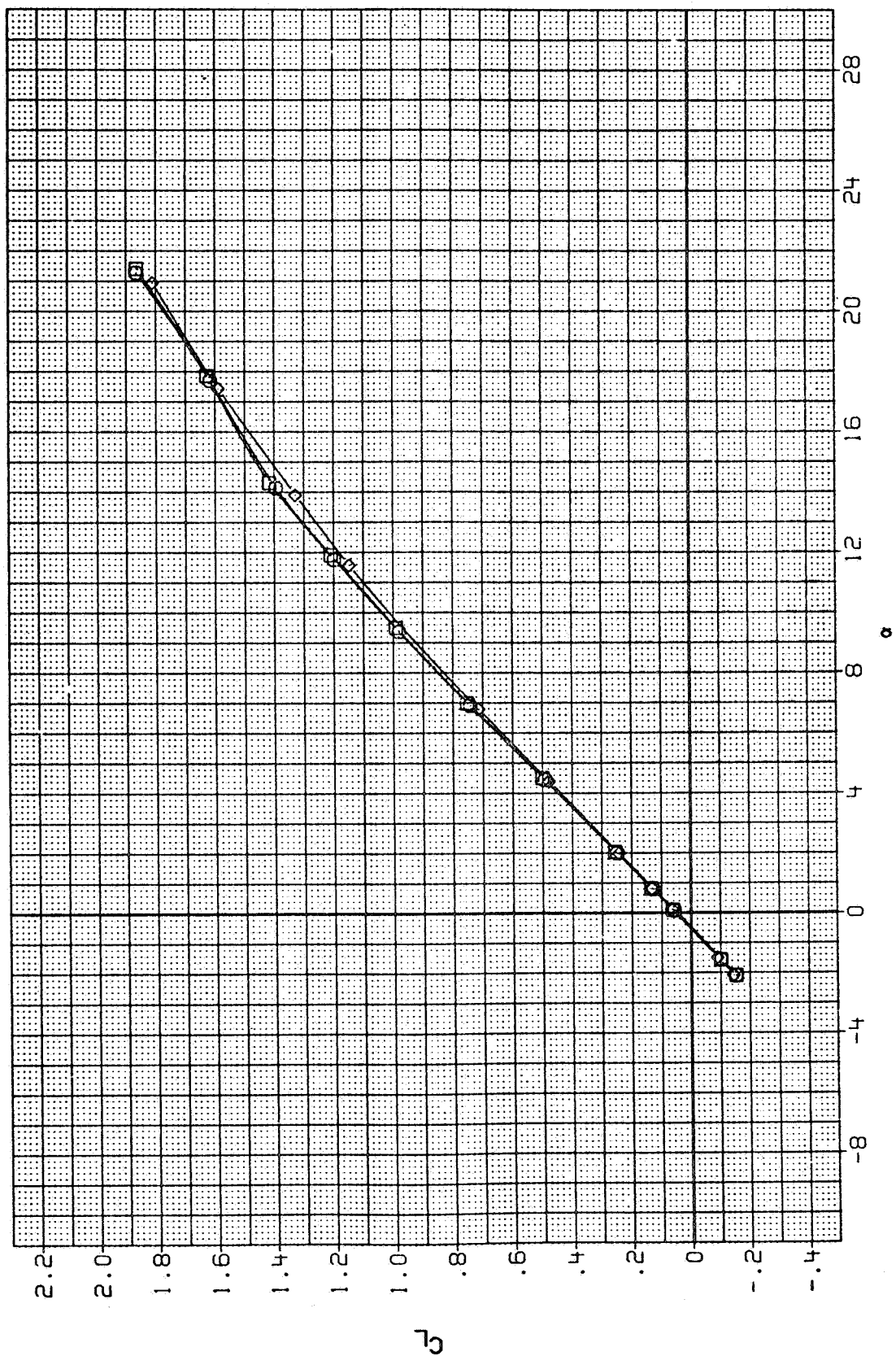


FIG. 59 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = 1.20

SYMBOL CONFIGURATION
 □ B1 S2 N W1 C1 V
 ○ B1 S2 N W1 C2 V
 ◇ B1 S2 N W1 C3 V
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

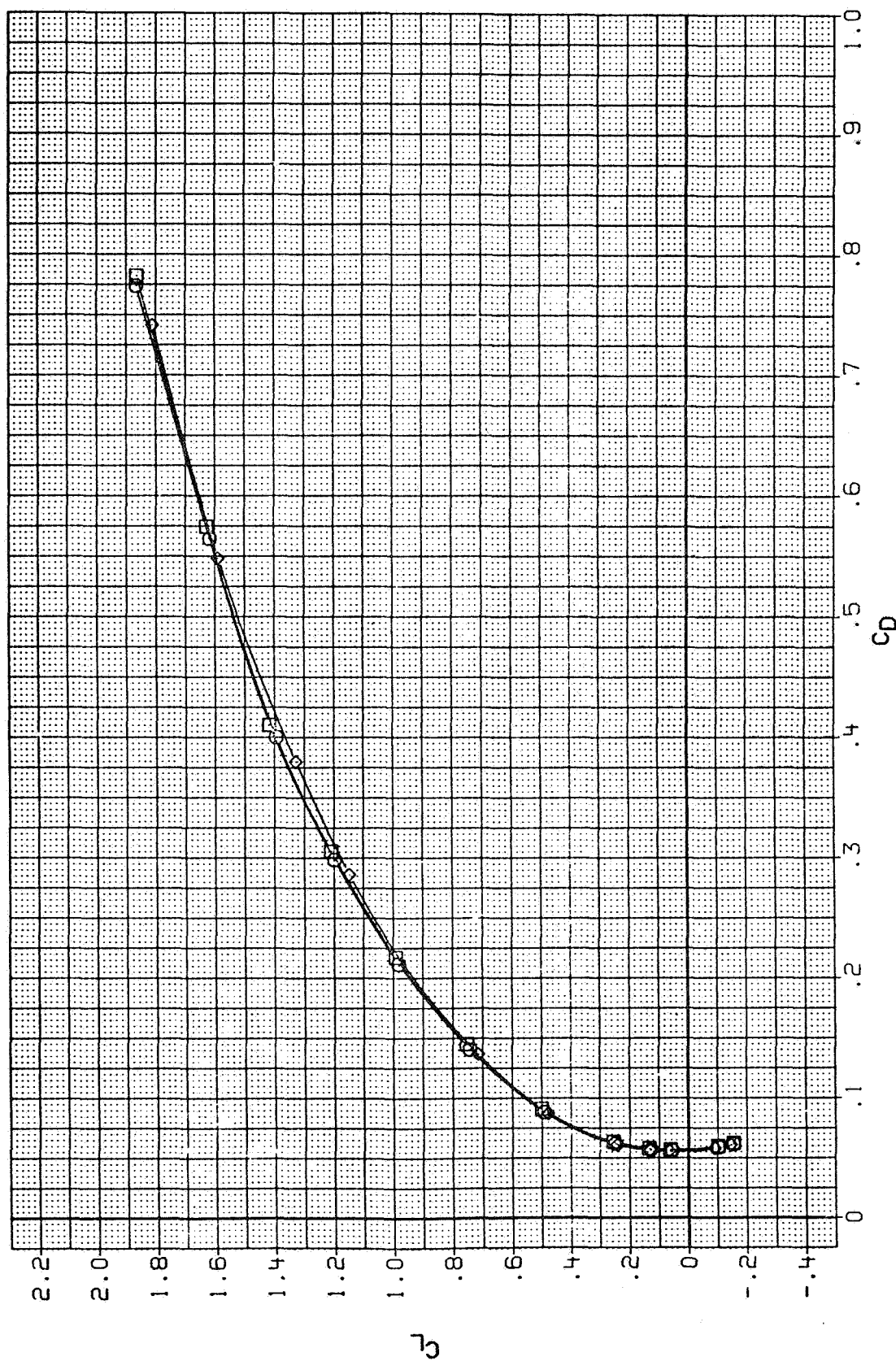


FIG. 59 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = 1.20

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

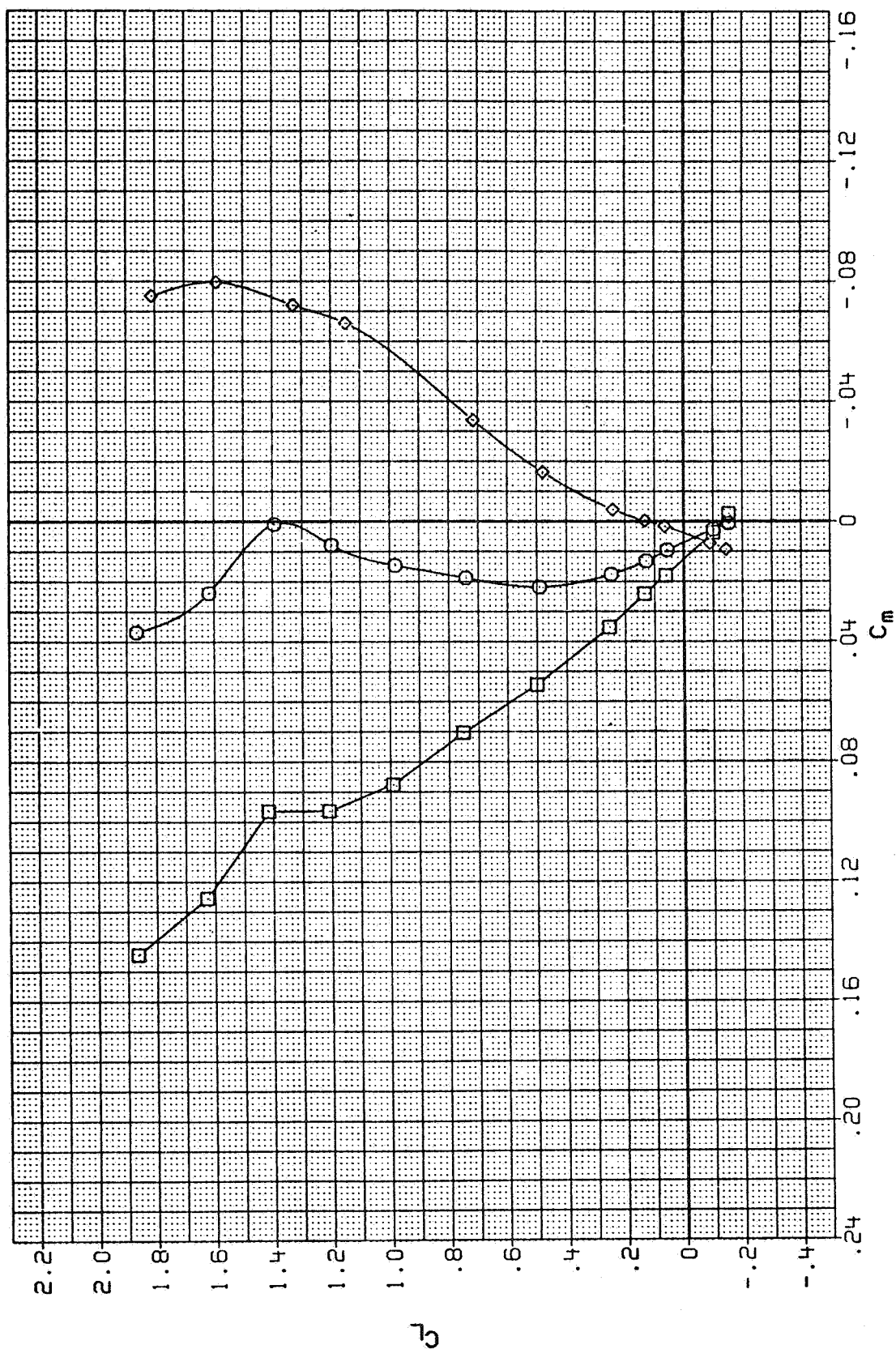


FIG. 59 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = 1.20

SYMBOL CONFIGURATION

○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

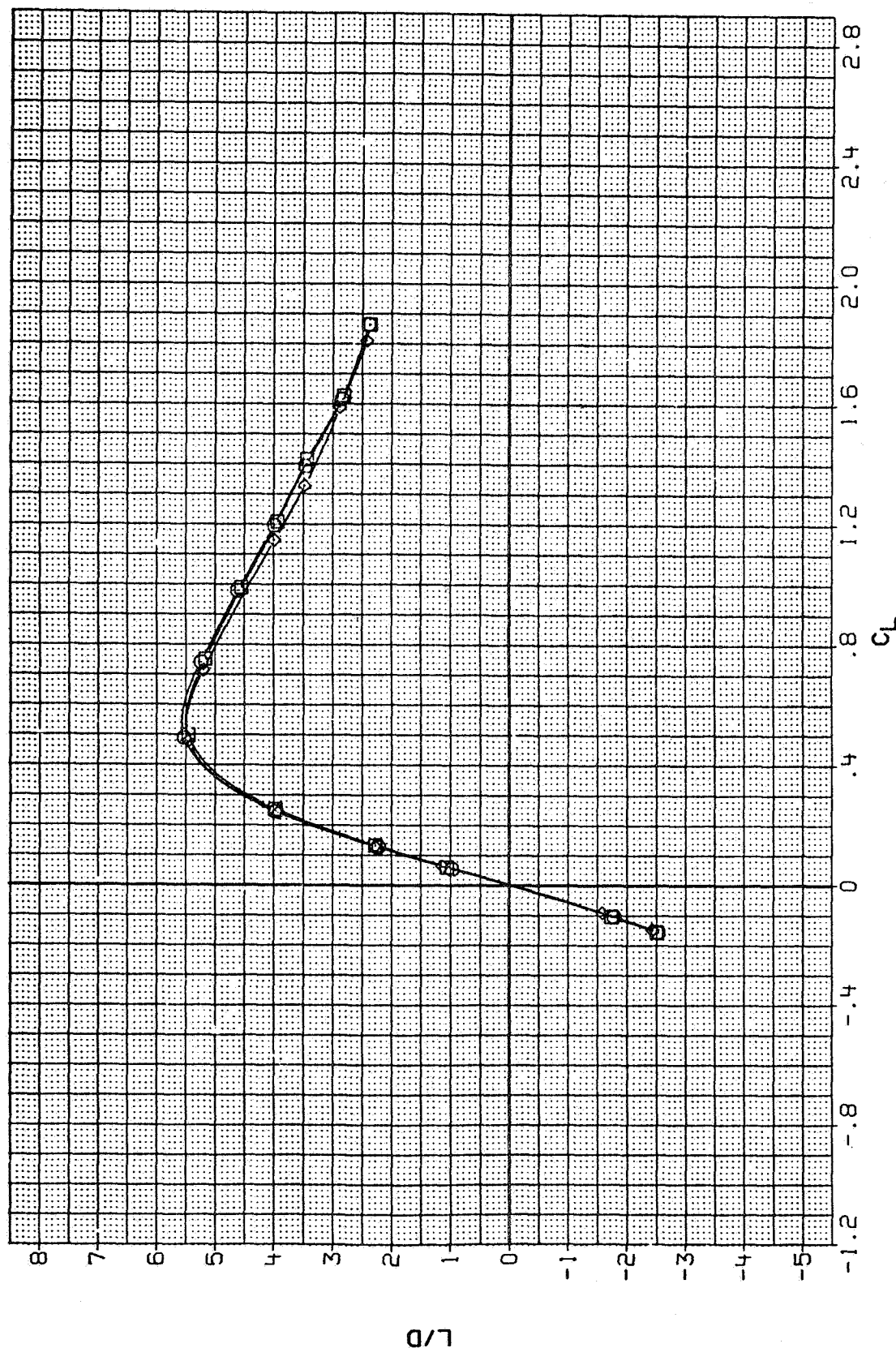


FIG. 59 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S2
 MACH = 1.20

SYMBOL CONFIGURATION

□ B1 S2 N W1 C1 V
 (EJECTOR-E205)

◇ B1 S2 N W1 C2 V
 (EJECTOR-E205)

◇ B1 S2 N W1 C3 V
 (EJECTOR-E205)

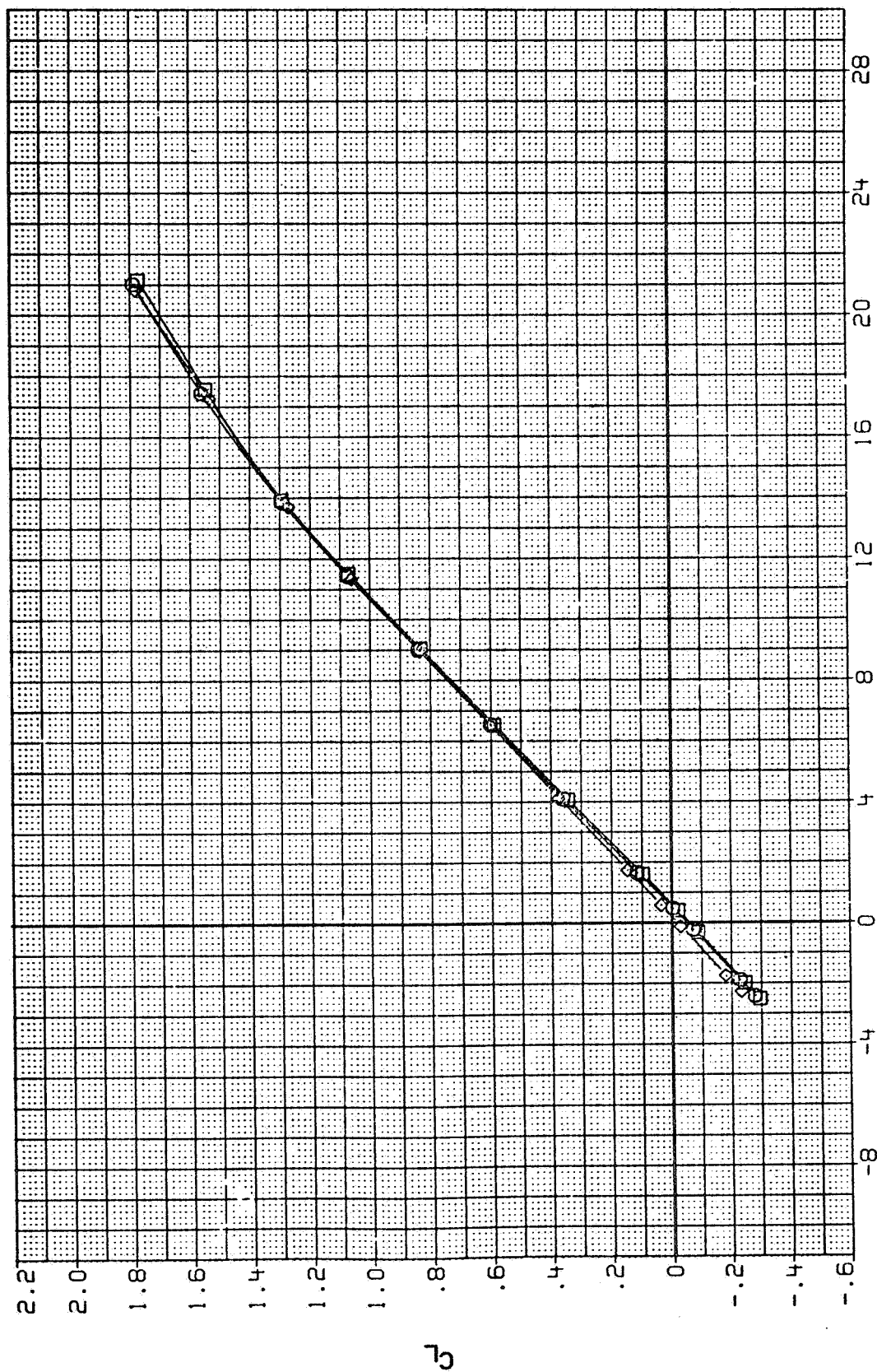


FIG. 60 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = 1.20

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V (EJECTOR-E205)
 □ B1 S2 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C3 V (EJECTOR-E205)

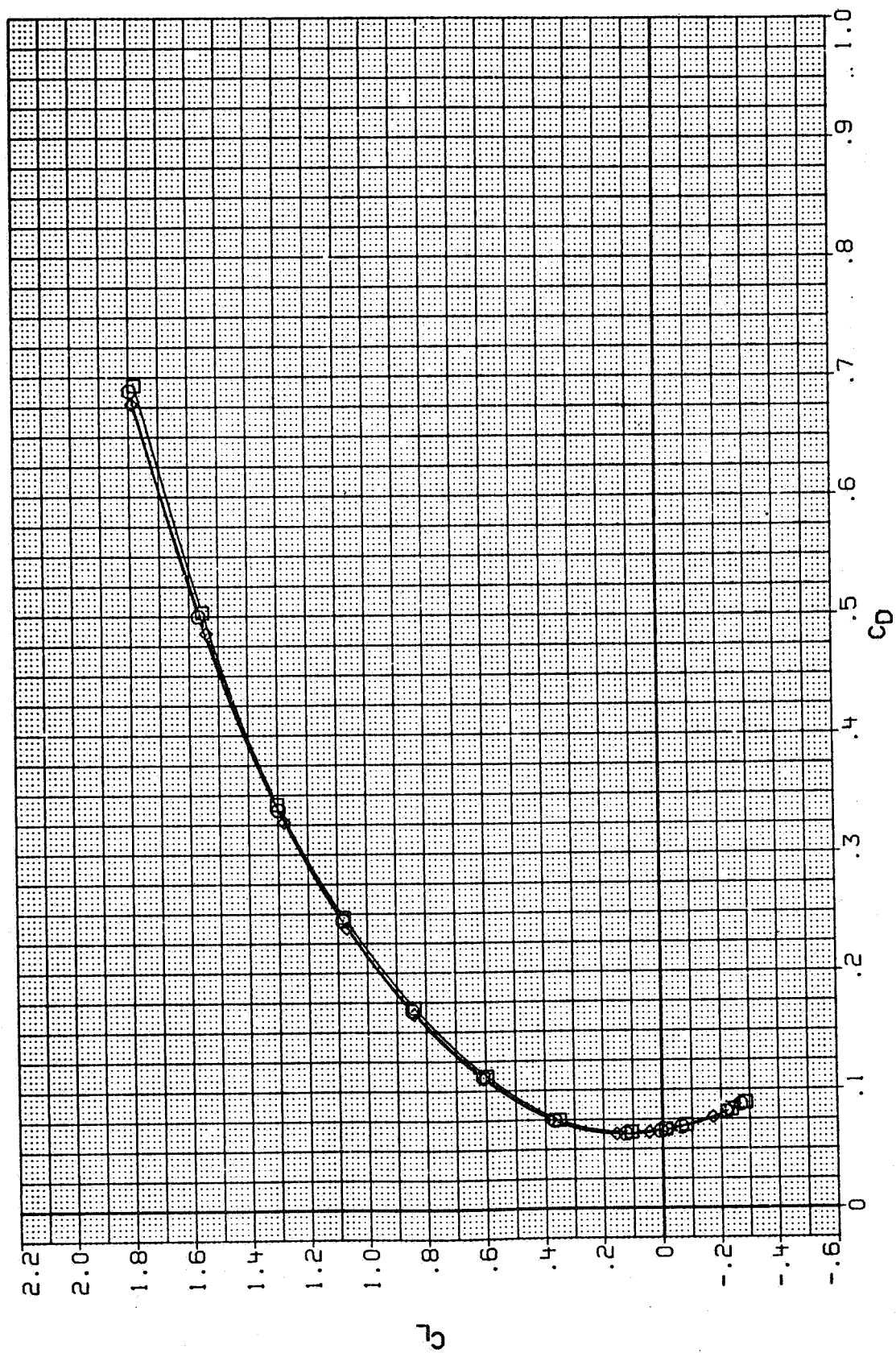


FIG. 60 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = 1.20

SYMBOL CONFIGURATION
 ○ B1 S2 N W1 C1 V (EJECTOR-E205)
 ◇ B1 S2 N W1 C2 V (EJECTOR-E205)
 □ B1 S2 N W1 C3 V (EJECTOR-E205)

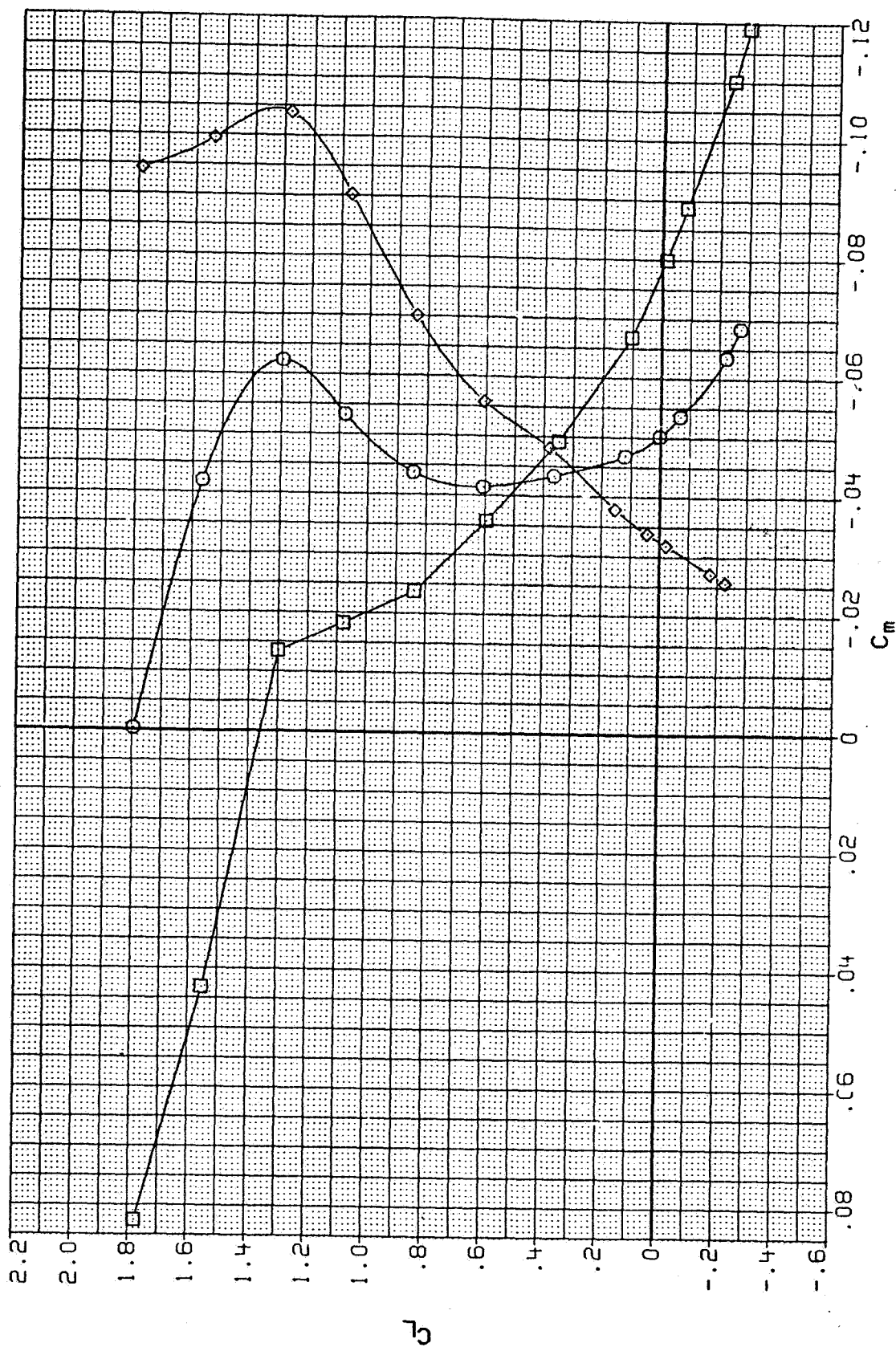


FIG. 60 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = 1.20

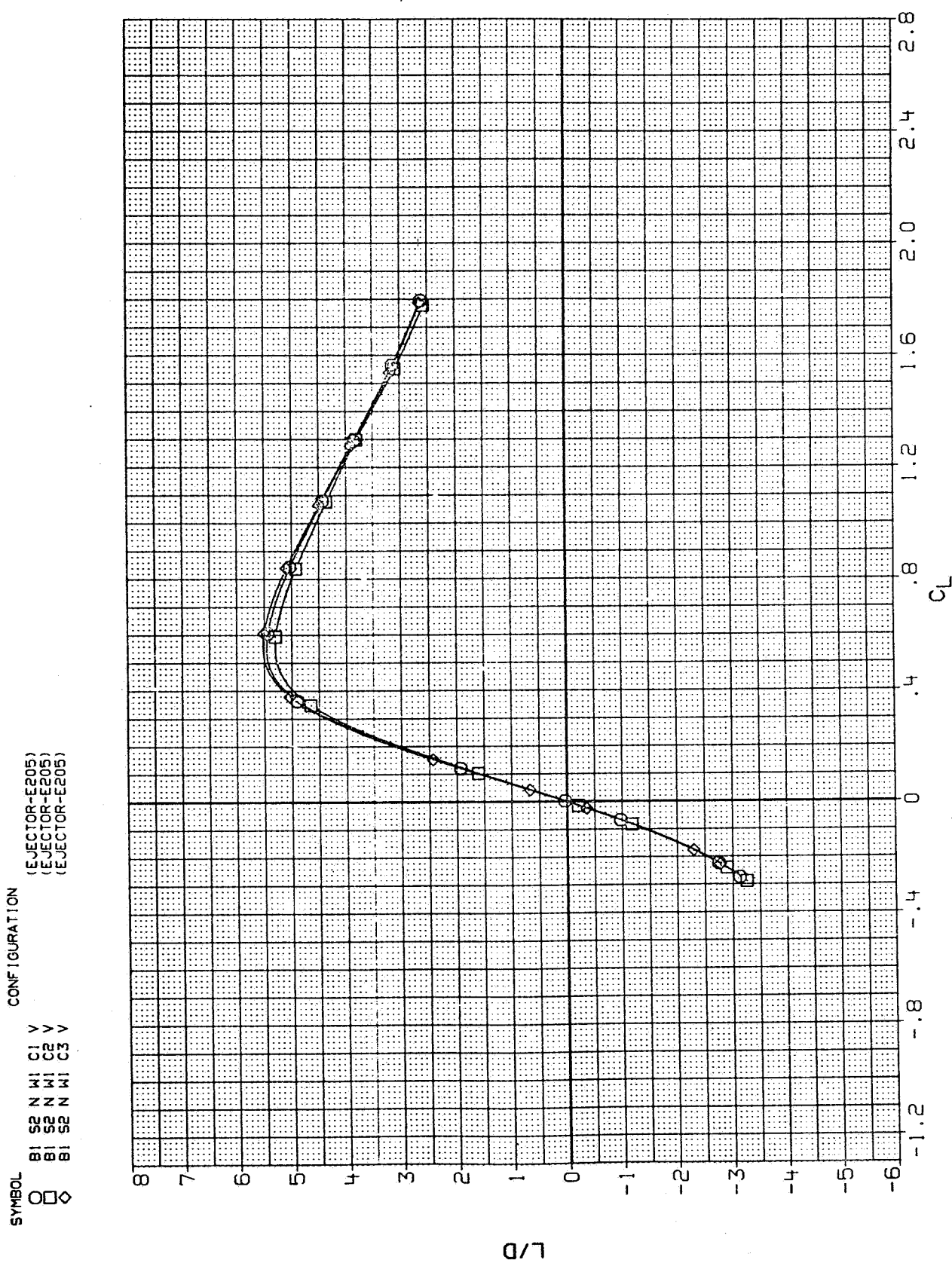


FIG. 60 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S2
 MACH = 1.20

SYMBOL CONFIGURATION

○	B1 S3	N	W1	C1	V	(EJECTOR-E205)
□	B1 S3	N	W1	C2	V	(EJECTOR-E205)
◇	B1 S3	N	W1	C3	V	(EJECTOR-E205)

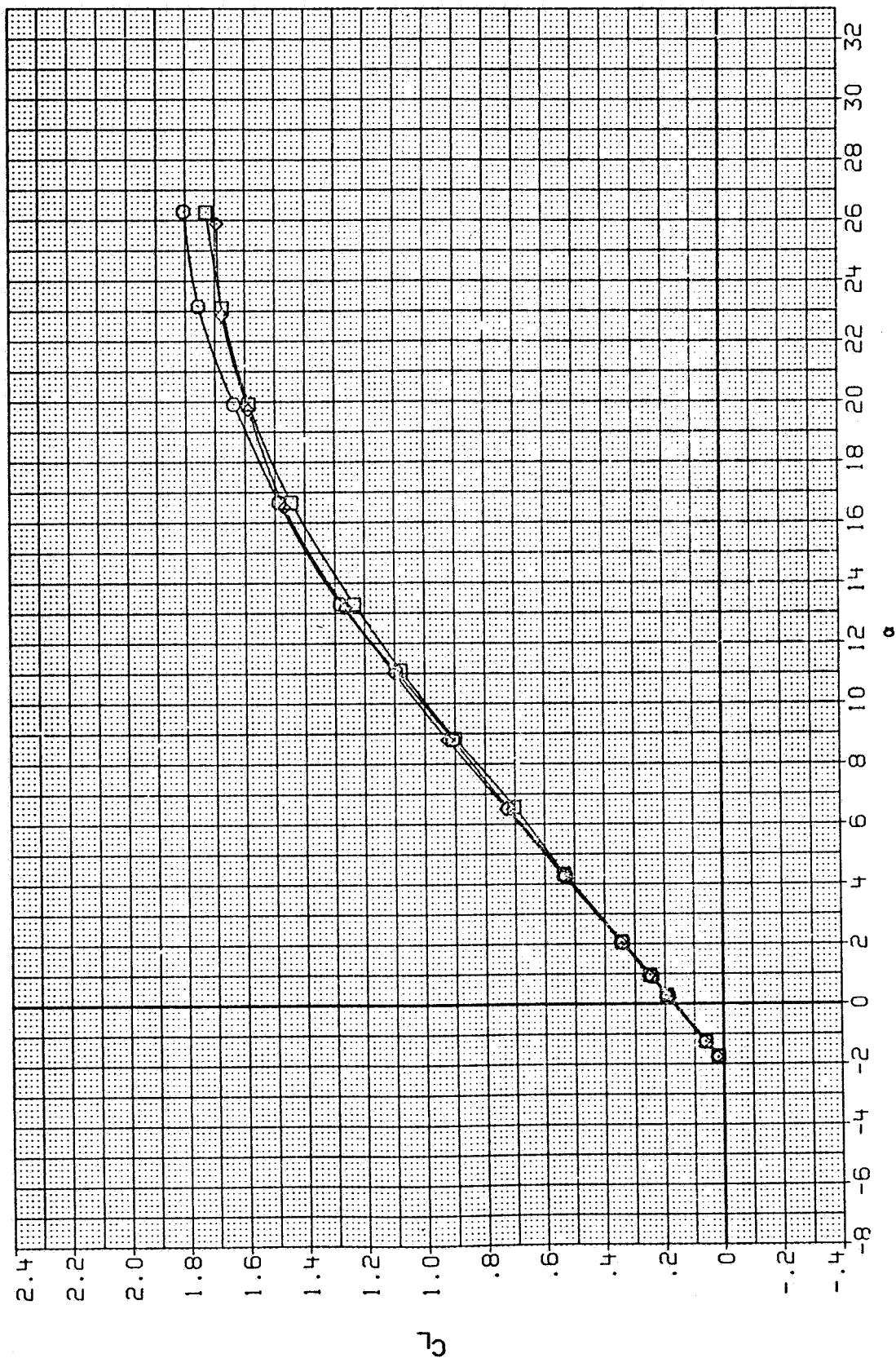


FIG. 61 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S3

MACH = .60

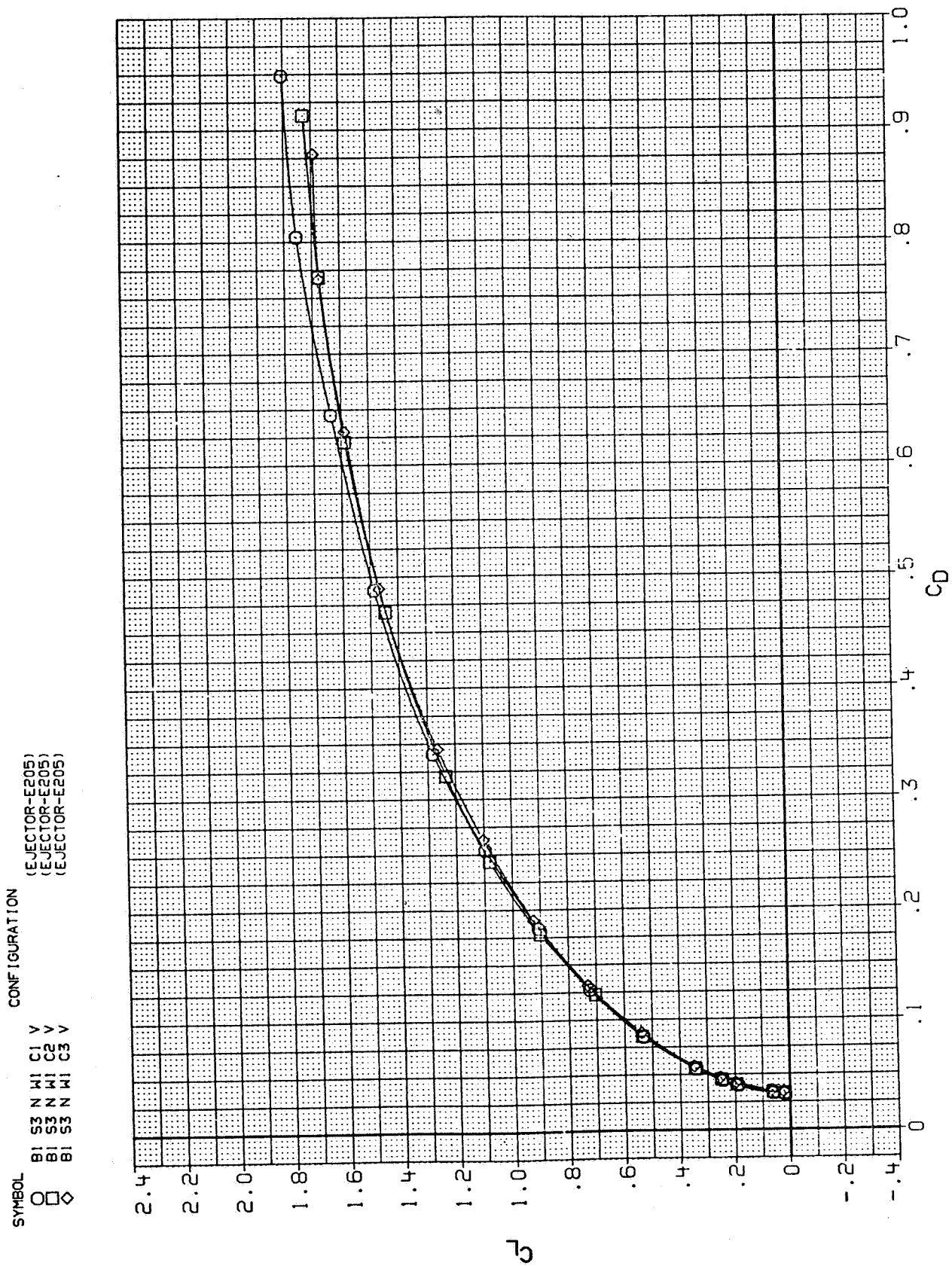


FIG. 61 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S3
MACH = .60

SYMBOL CONFIGURATION
 ○ B1 S3 N W1 C1 V (EJECTOR-E205)
 ◇ B1 S3 N W1 C2 V (EJECTOR-E205)
 □ B1 S3 N W1 C3 V (EJECTOR-E205)

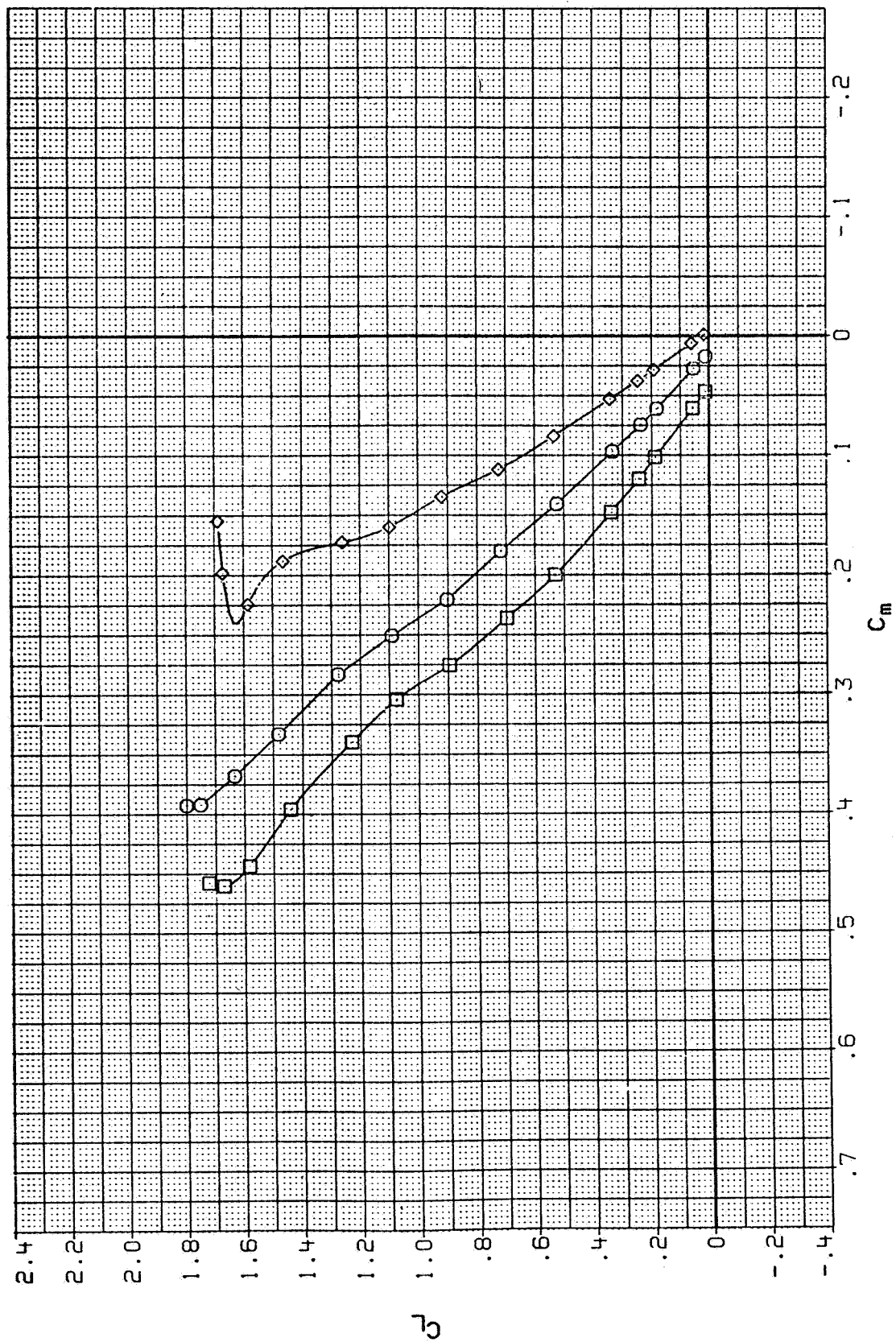


FIG. 61 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S3
 MACH = .60

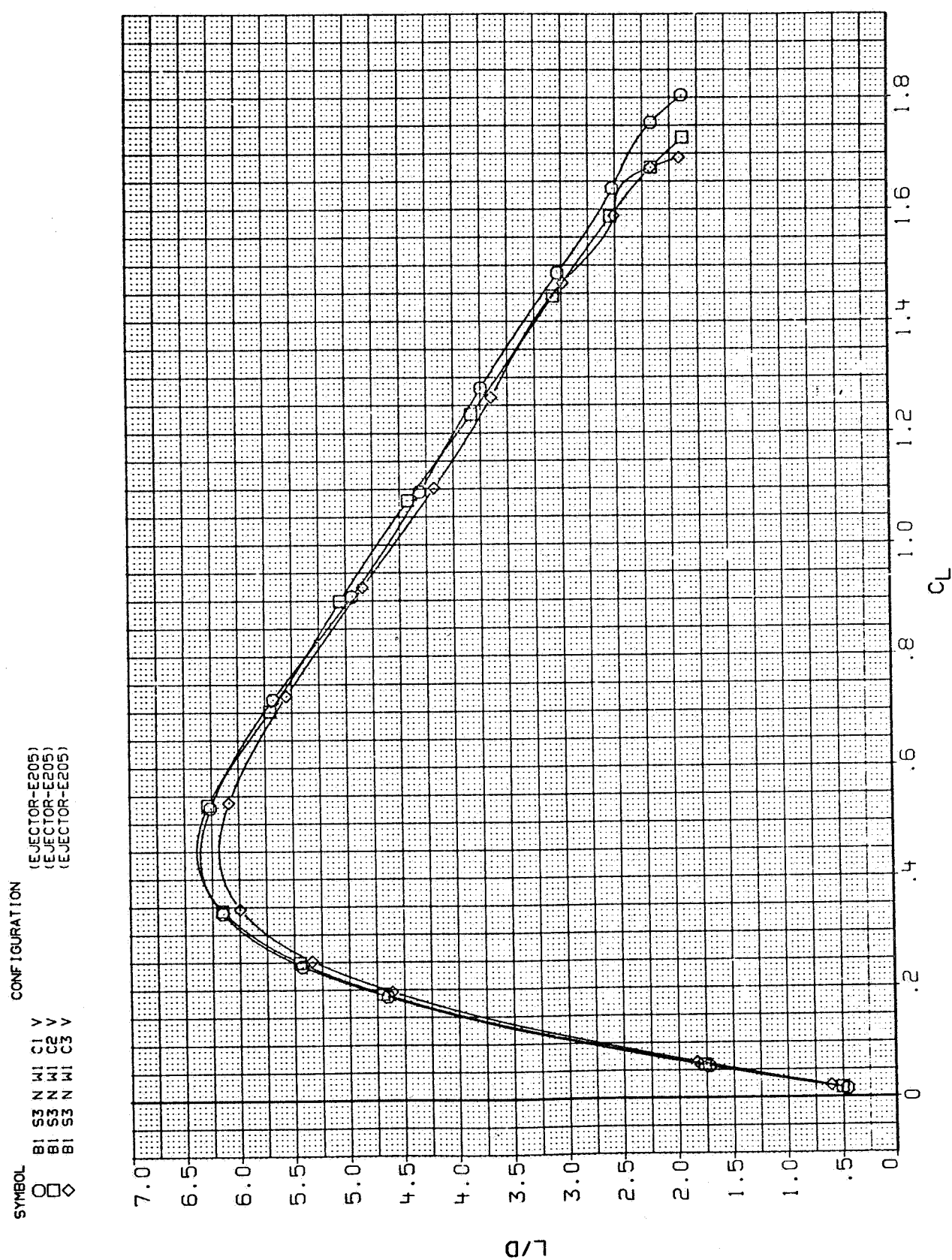


FIG. 61 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S3

SYMBOL CONFIGURATION
 ○ BI S3 N MI C1 V
 □ BI S3 N MI C2 V
 ◇ BI S3 N MI C3 V
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

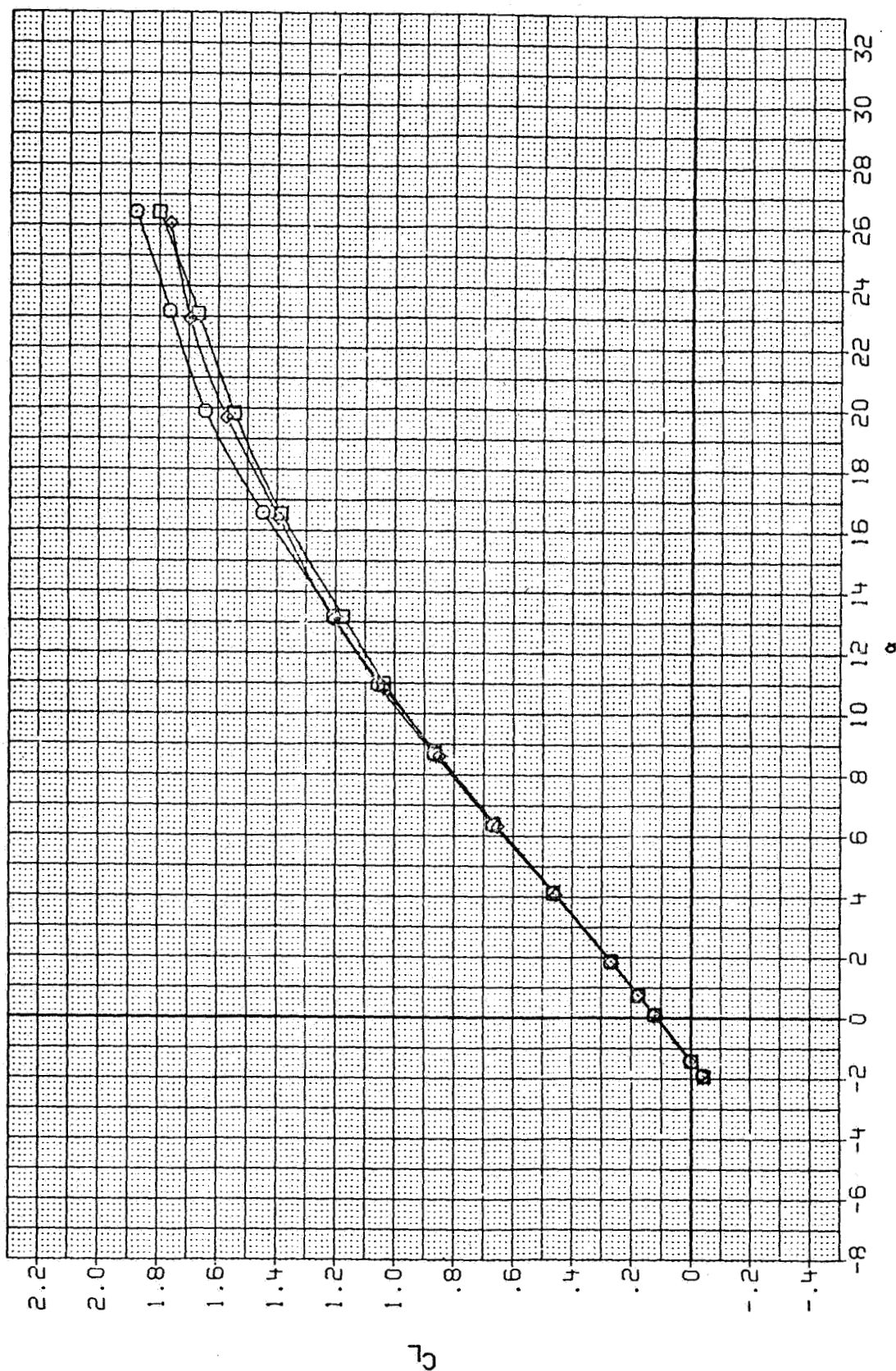


FIG. 62 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S3
 MACH = .60

SYMBOL CONFIGURATION
 ○ B1 S3 N W1 C1 V (EJECTOR-E205)
 □ B1 S3 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S3 N W1 C3 V (EJECTOR-E205)

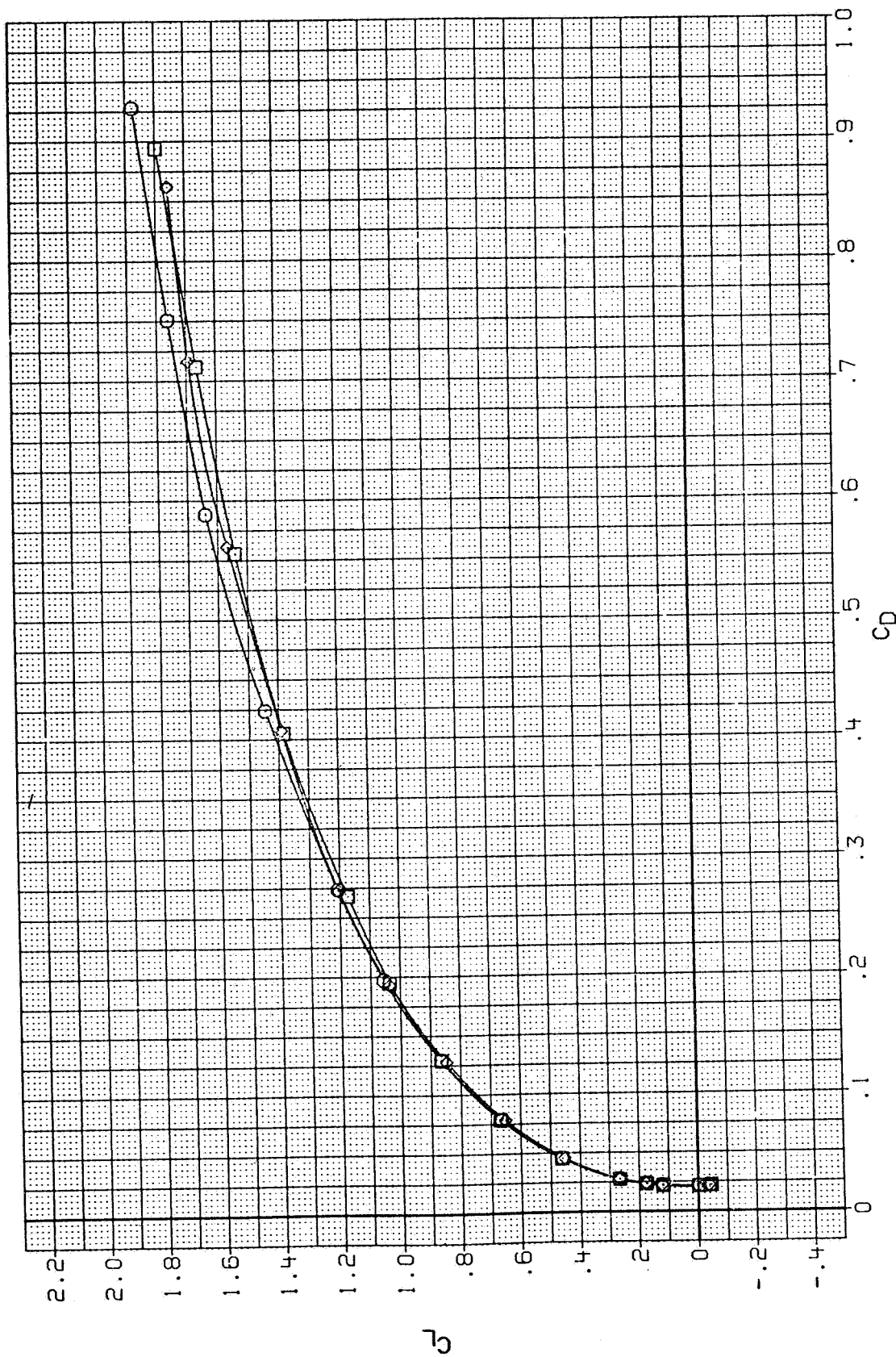


FIG. 62 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S₂

MACH = .60

SYMBOL CONFIGURATION
 ○ (EJECTOR-E205)
 □ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

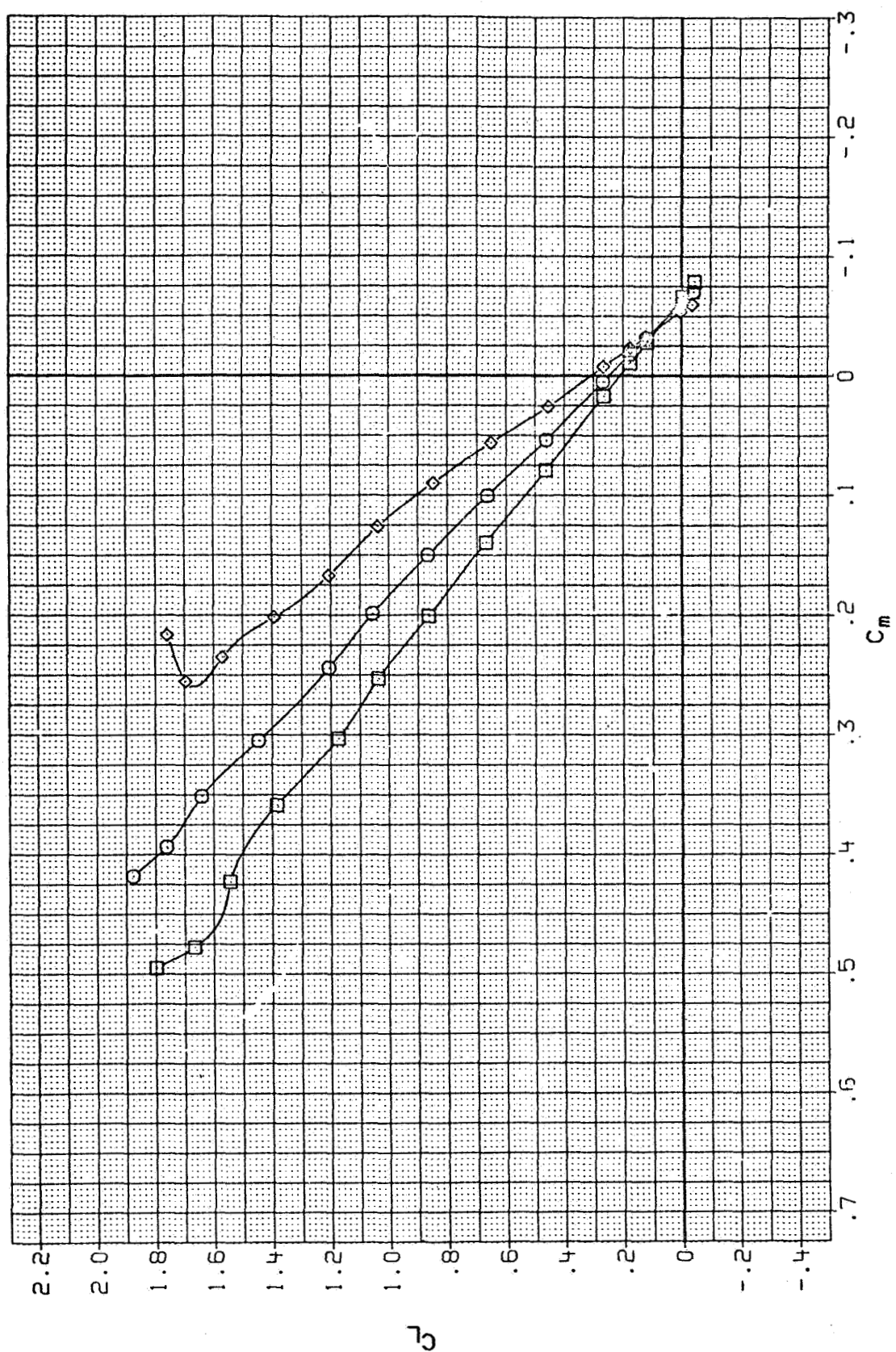


FIG. 62 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S3
 MACH = .60

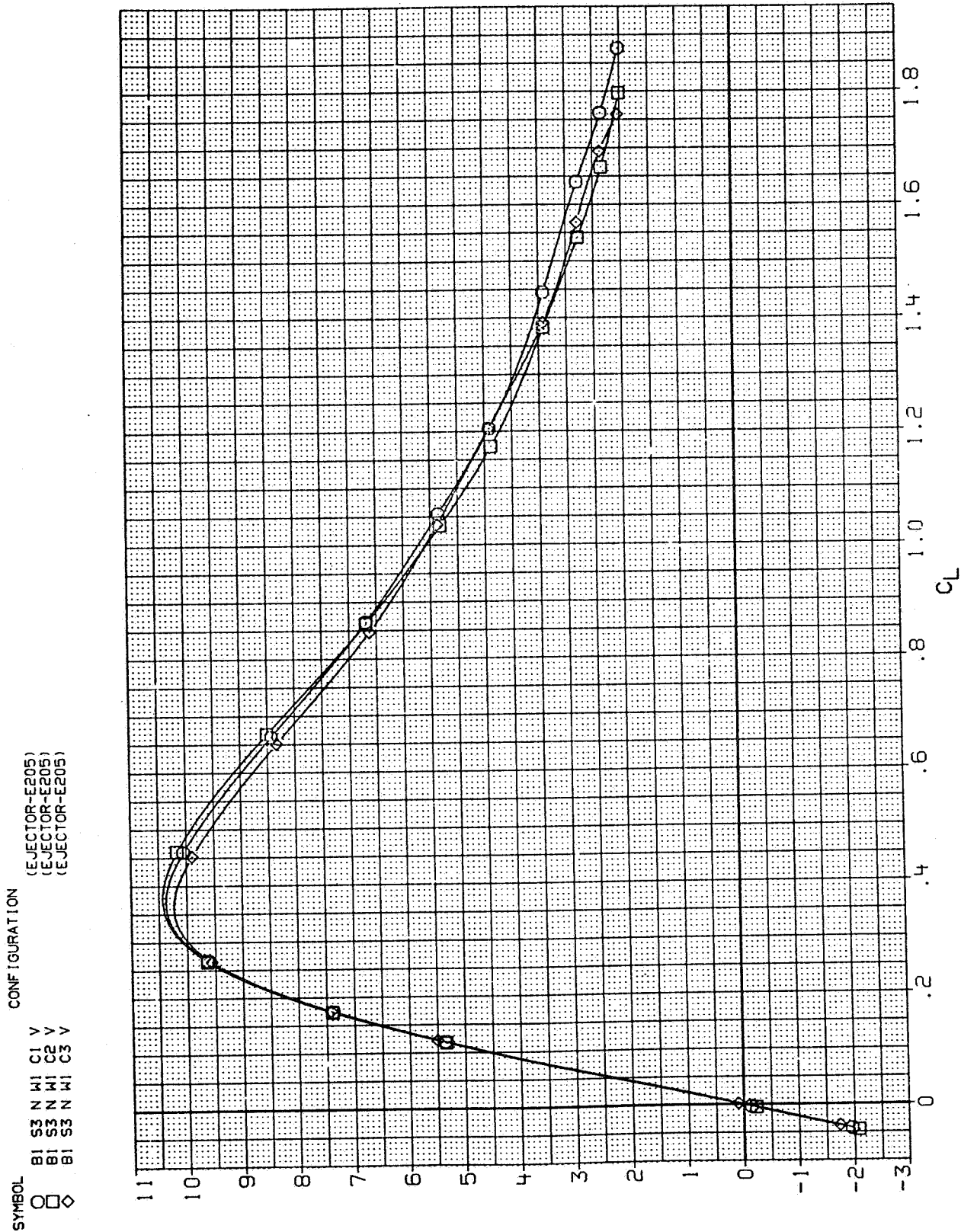


FIG. 62 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 0 DEGREES, STRAKE S3
MACH = .60

L/D

SYMBOL CONFIGURATION
 ○ BI S3 N W1 C1 V (EJECTOR-E205)
 □ BI S3 N W1 C2 V (EJECTOR-E205)
 ◇ BI S3 N W1 C3 V (EJECTOR-E205)

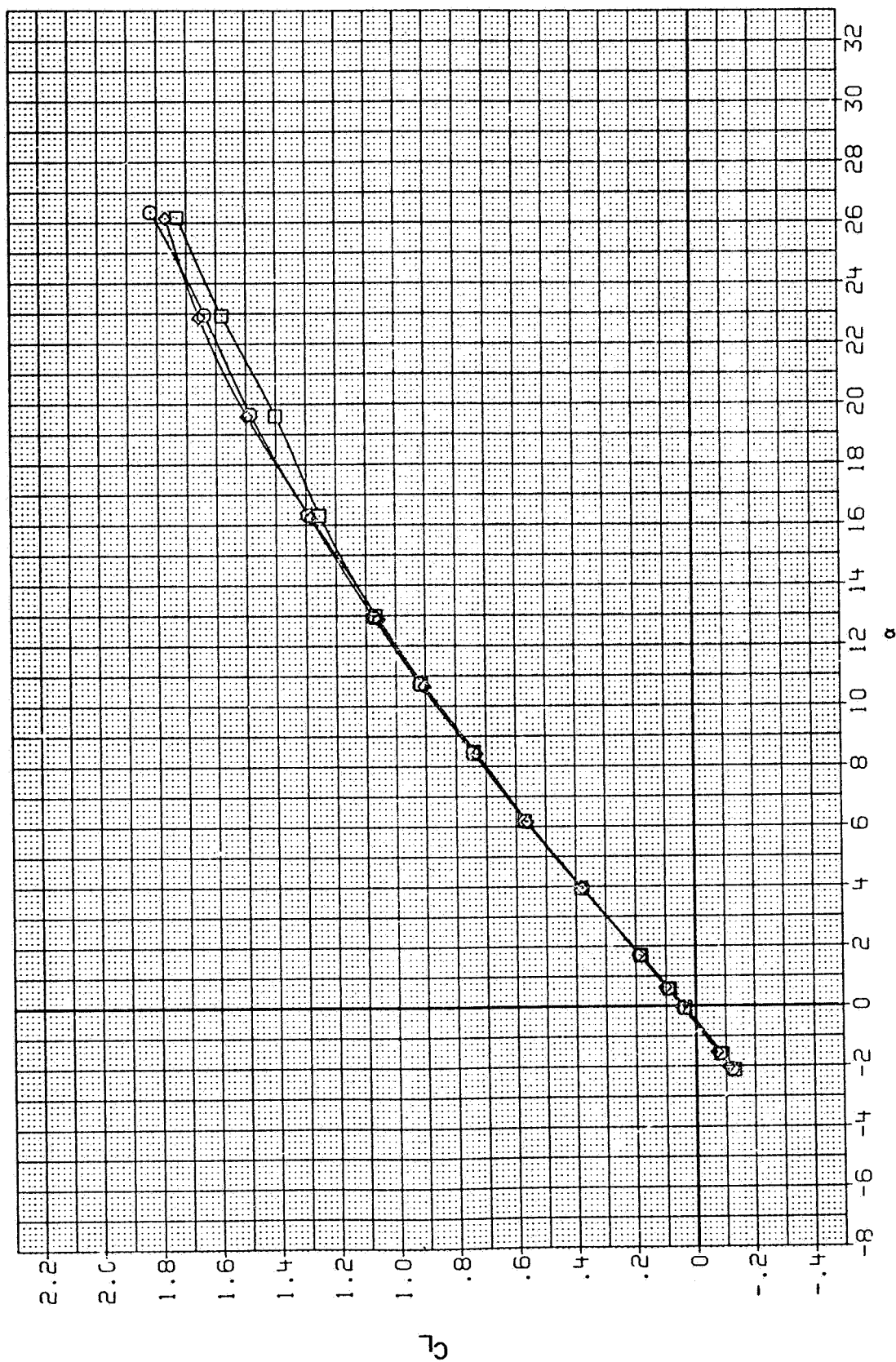


FIG. 63 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S3
 MACH = .60

SYMBOL CONFIGURATION
 ○ BI S3 N W1 C1 V (EJECTOR-E205)
 □ BI S3 N W1 C2 V (EJECTOR-E205)
 ◇ BI S3 N W1 C3 V (EJECTOR-E205)

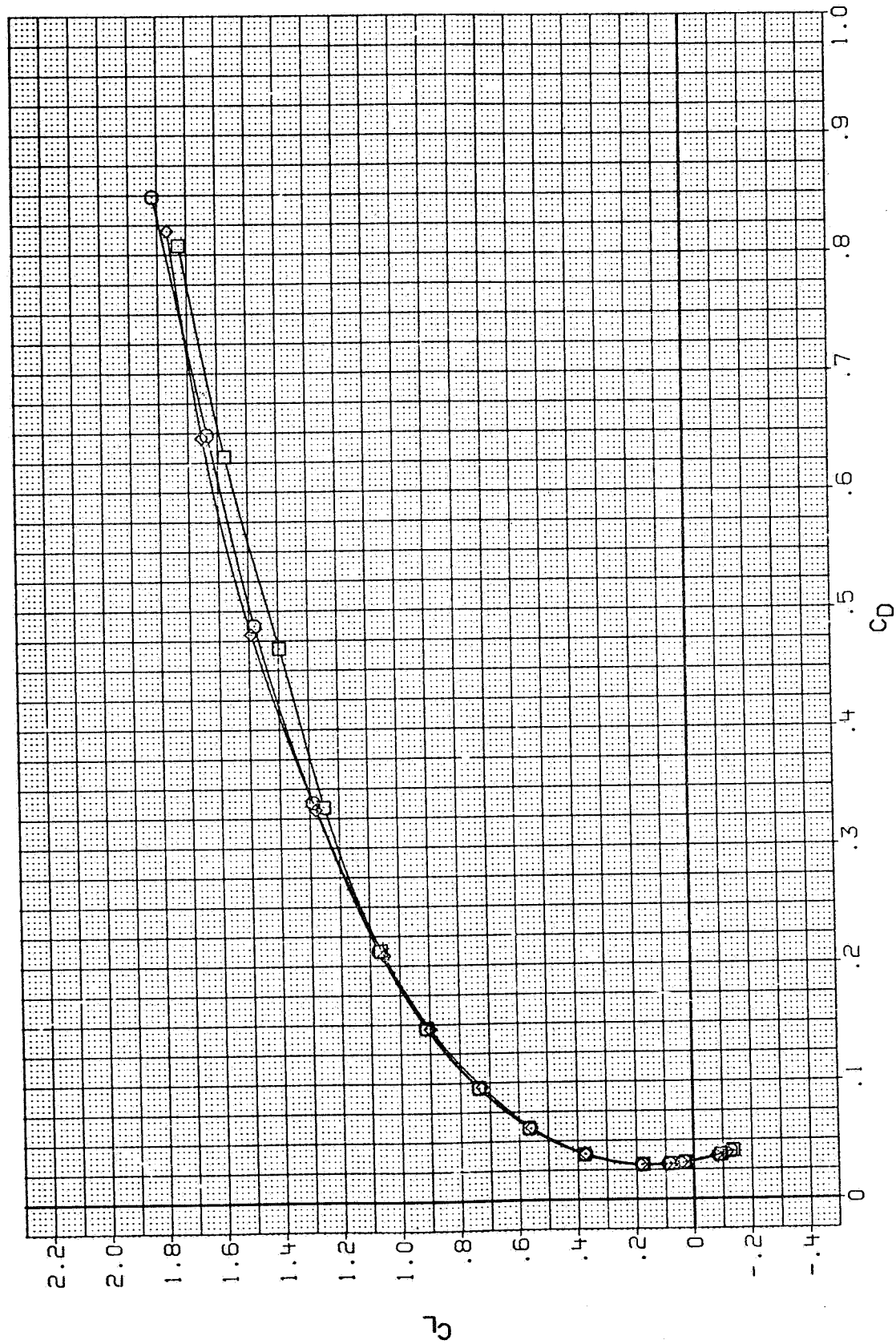


FIG. 63 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S3
 MACH = .60

SYMBOL CONFIGURATION

○ B1 S3 N W1 C1 V (EJECTOR-E205)
 □ B1 S3 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S3 N W1 C3 V (EJECTOR-E205)

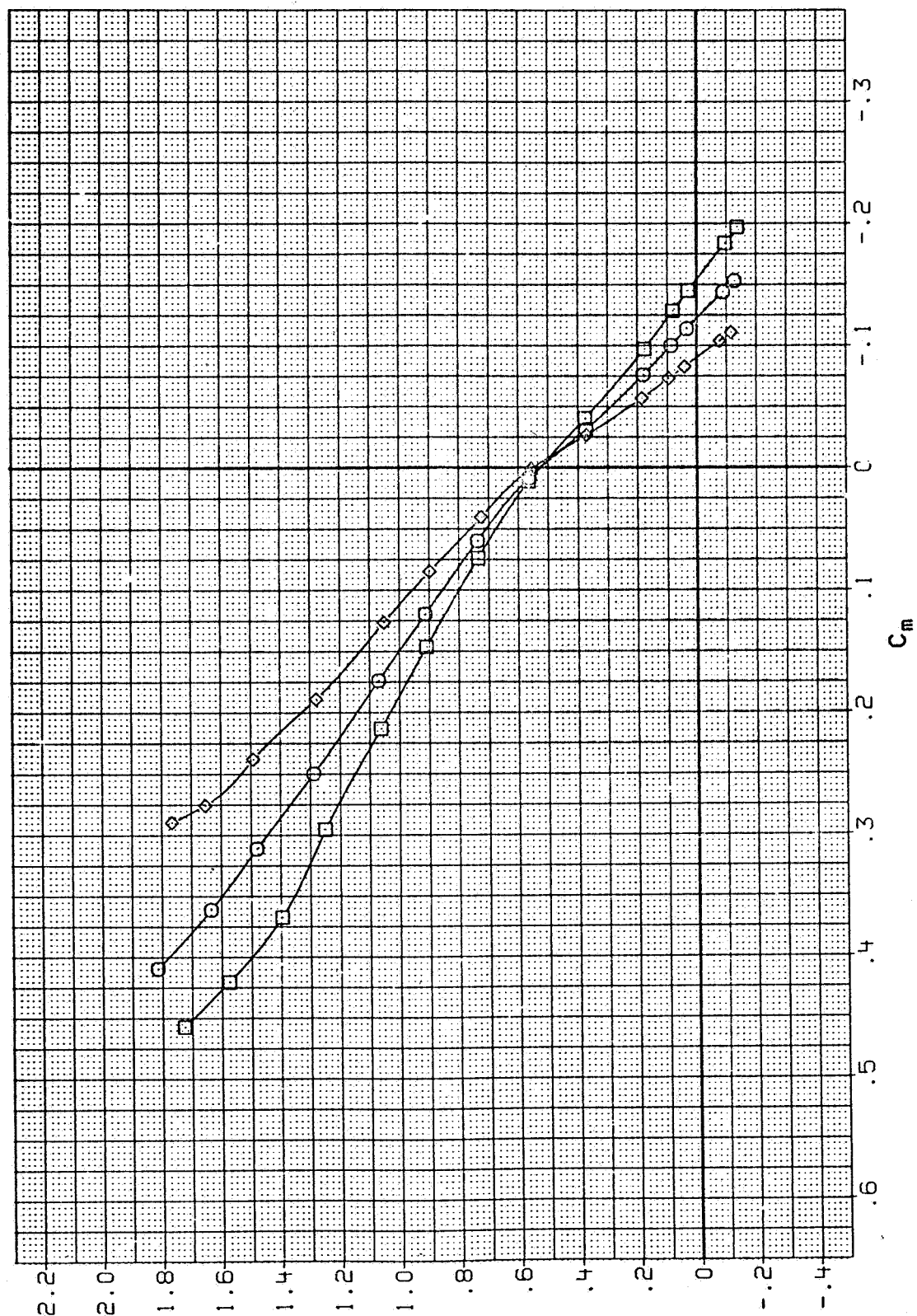


FIG. 63 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S3
 MACH = .60

SYMBOL CONFIGURATION

○ B1 S3 N W1 C1 V (EJECTOR-E205)
 □ B1 S3 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S3 N W1 C3 V (EJECTOR-E205)

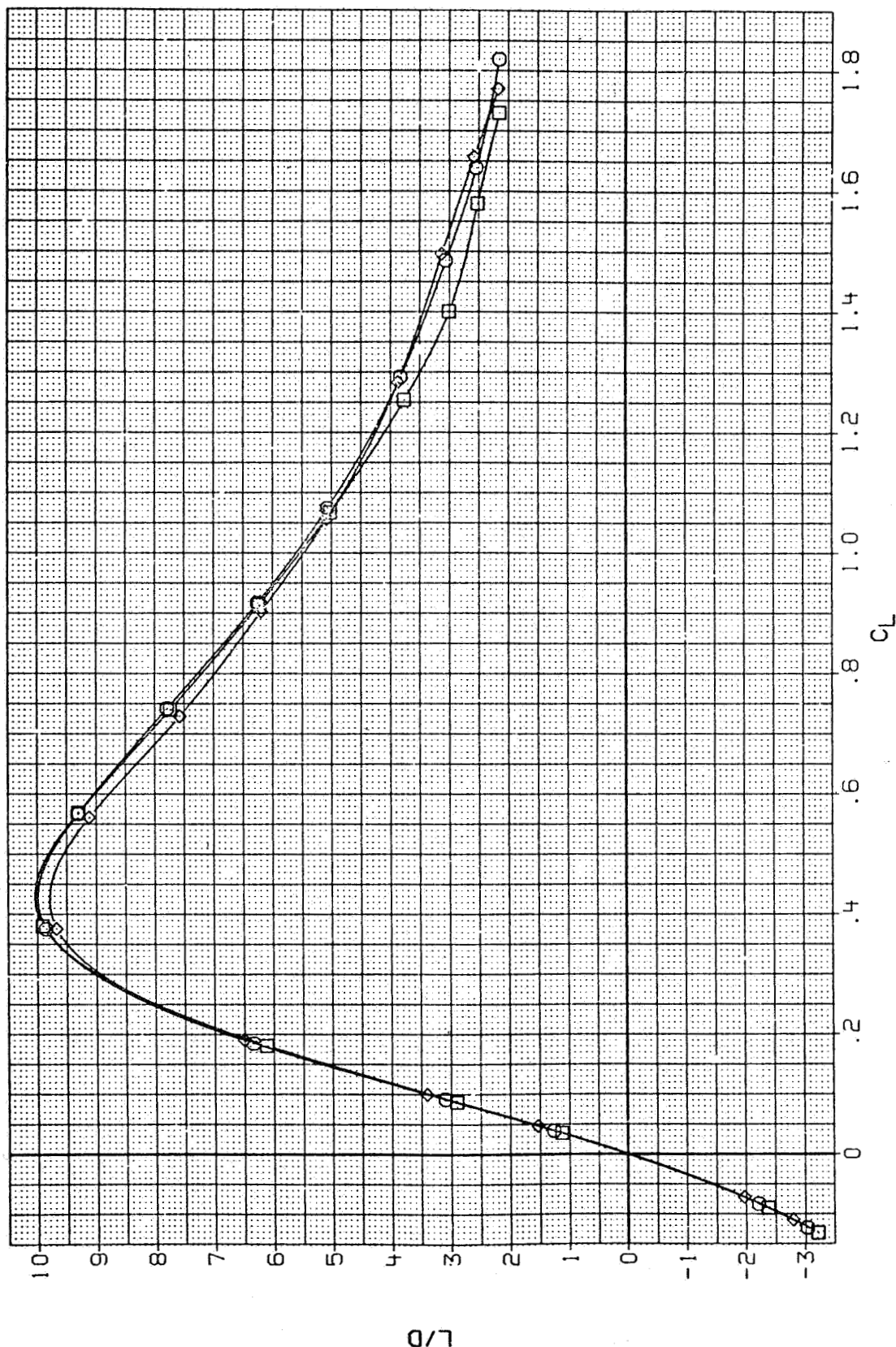


FIG. 63 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = -10 DEGREES, STRAKE S3
MACH = .60

L/D

SYMBOL CONFIGURATION

○ BI S3 N WI C1 V
 □ BI S3 N WI C2 V
 ◇ BI S3 N WI C3 V

(EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

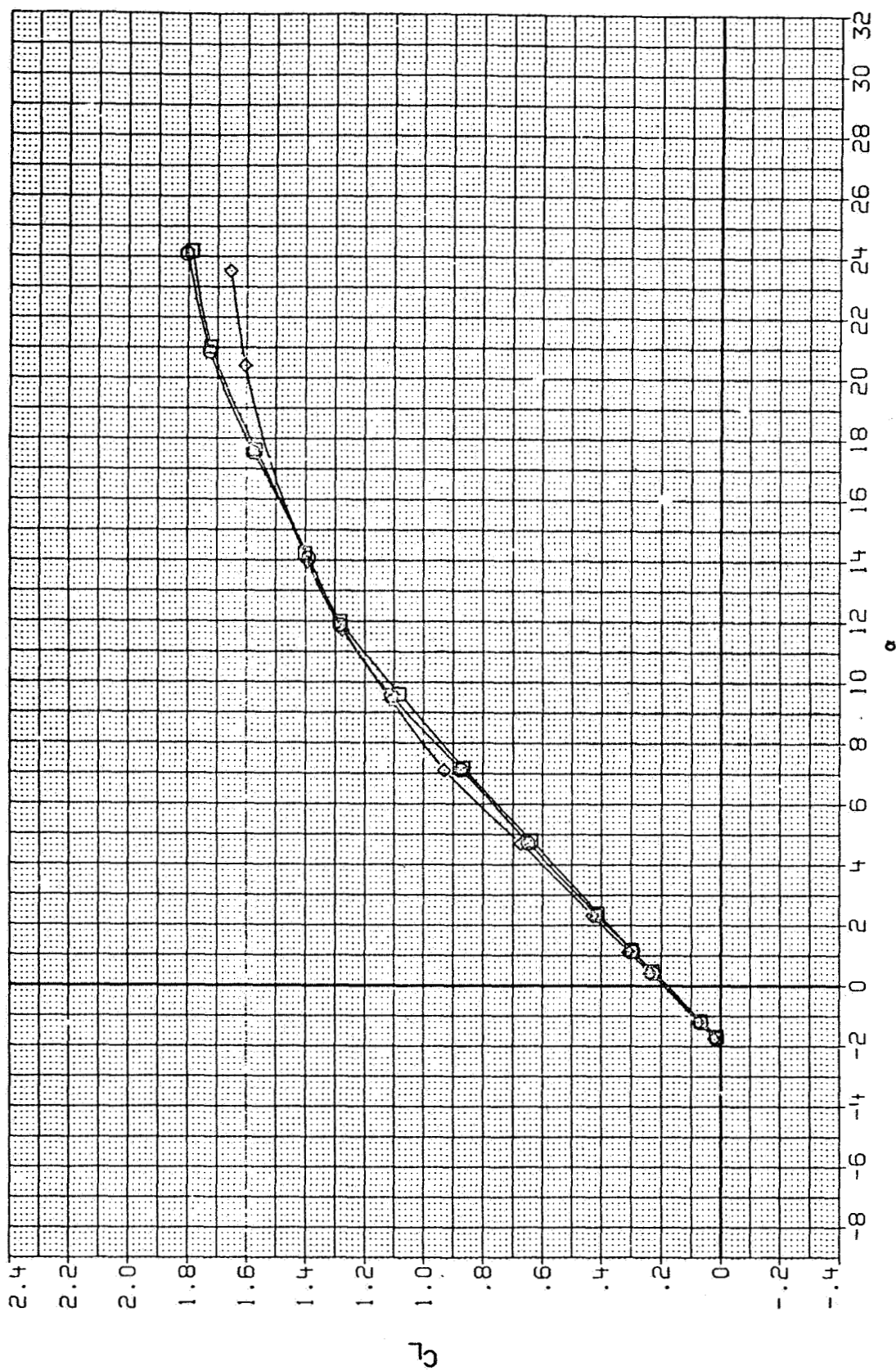


FIG. 64 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S3
 MACH = .90

SYMBOL CONFIGURATION
 ○ B1 S3 N W1 C1 V (EJECTOR-E205)
 □ B1 S3 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S3 N W1 C3 V (EJECTOR-E205)

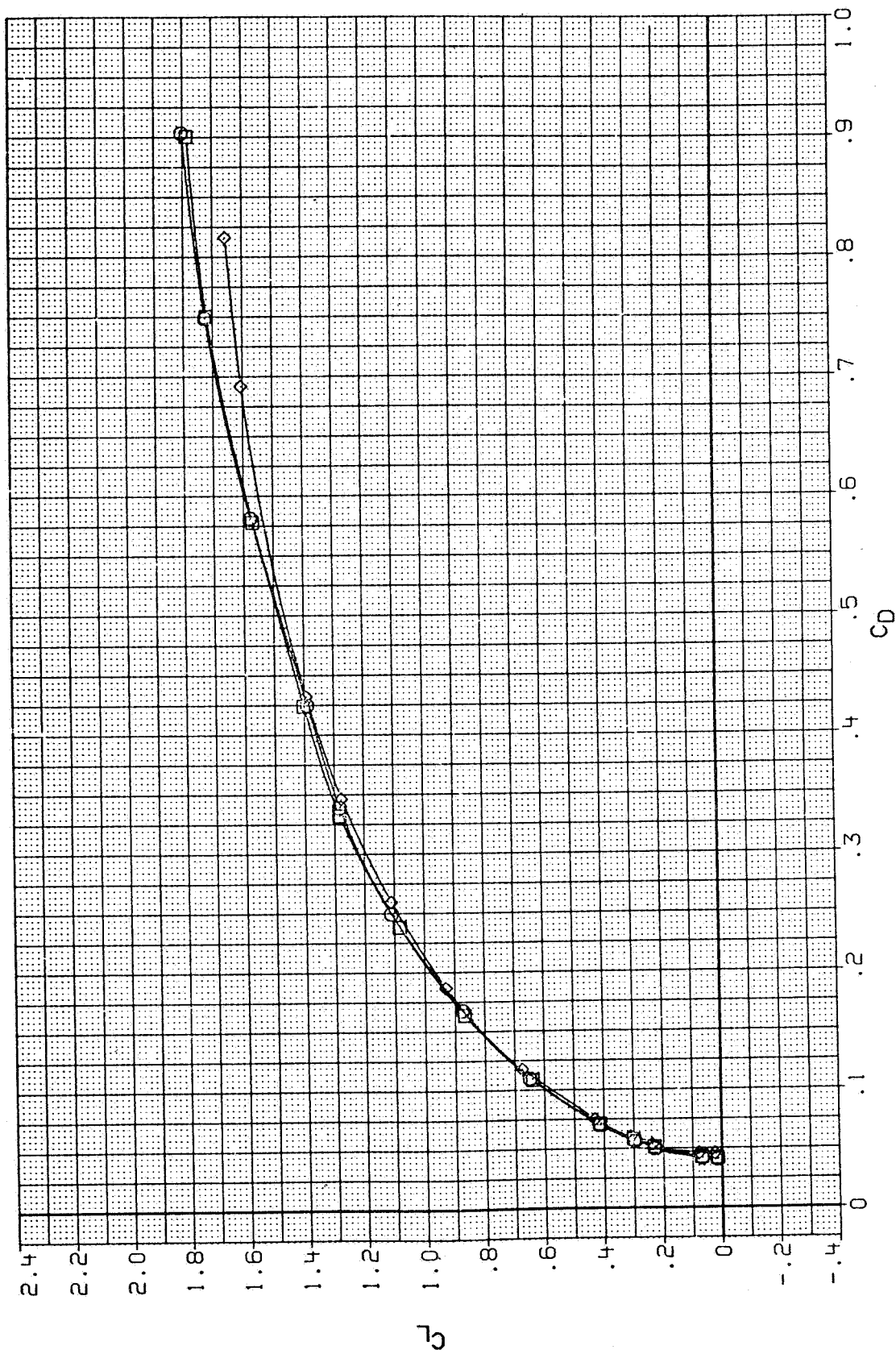


FIG. 64 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S3
 MACH = .90

SYMBOL CONFIGURATION

○ BI S3 N WI C1 V
 □ BI S3 N WI C2 V
 ◇ BI S3 N WI C3 V
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

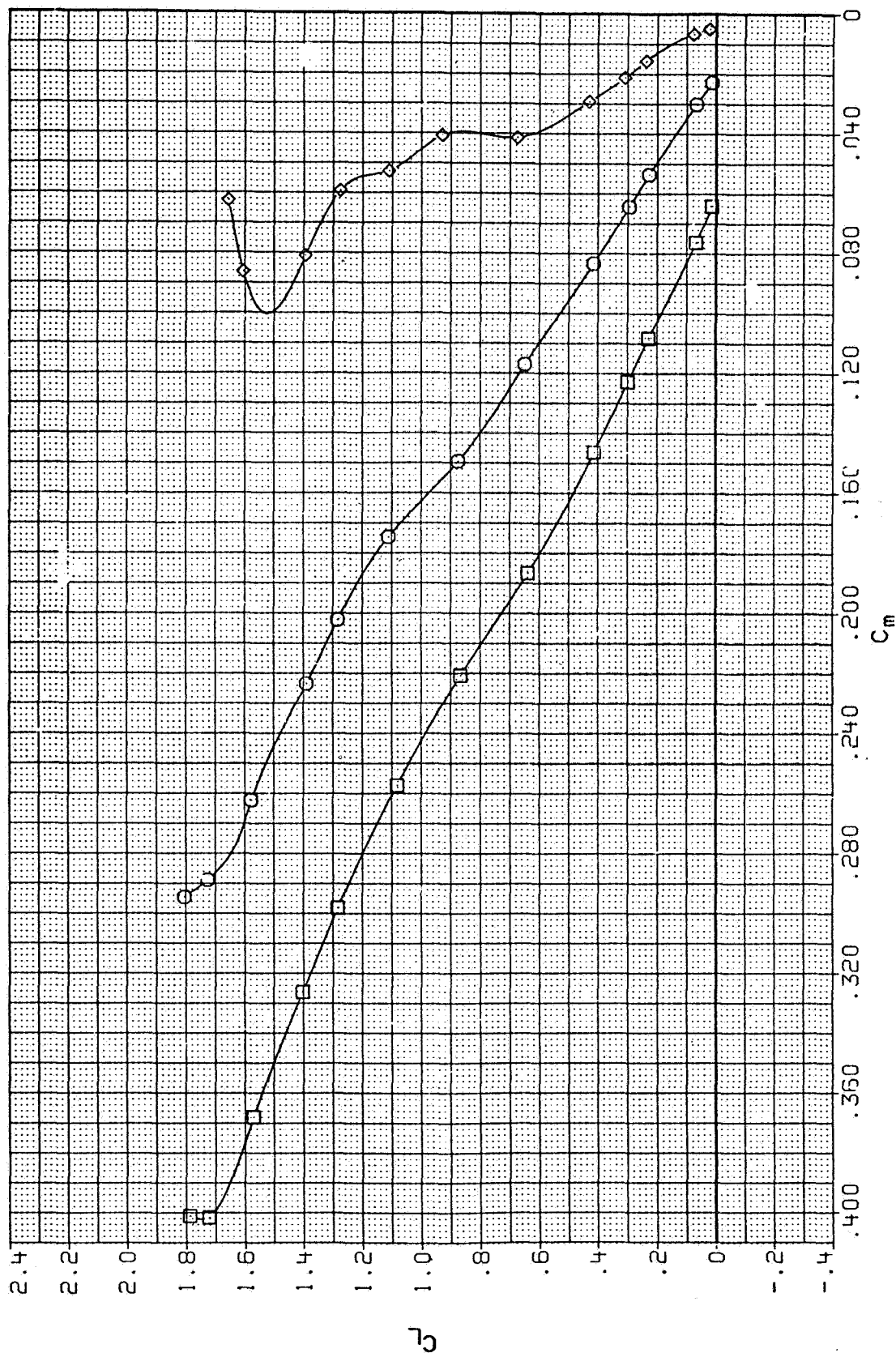


FIG. 64 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S3
MACH = .90

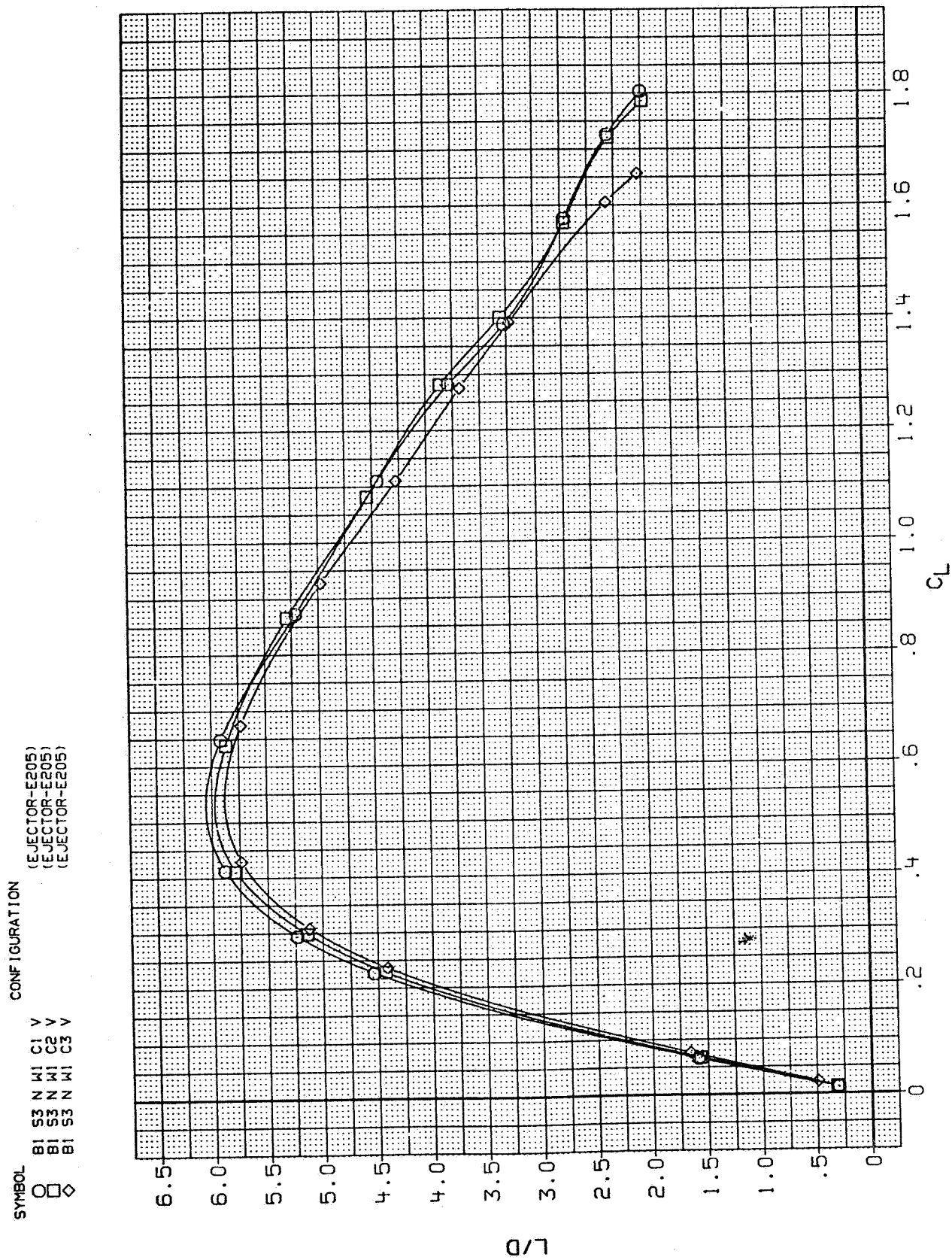


FIG. 64 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S3

MACH = .90

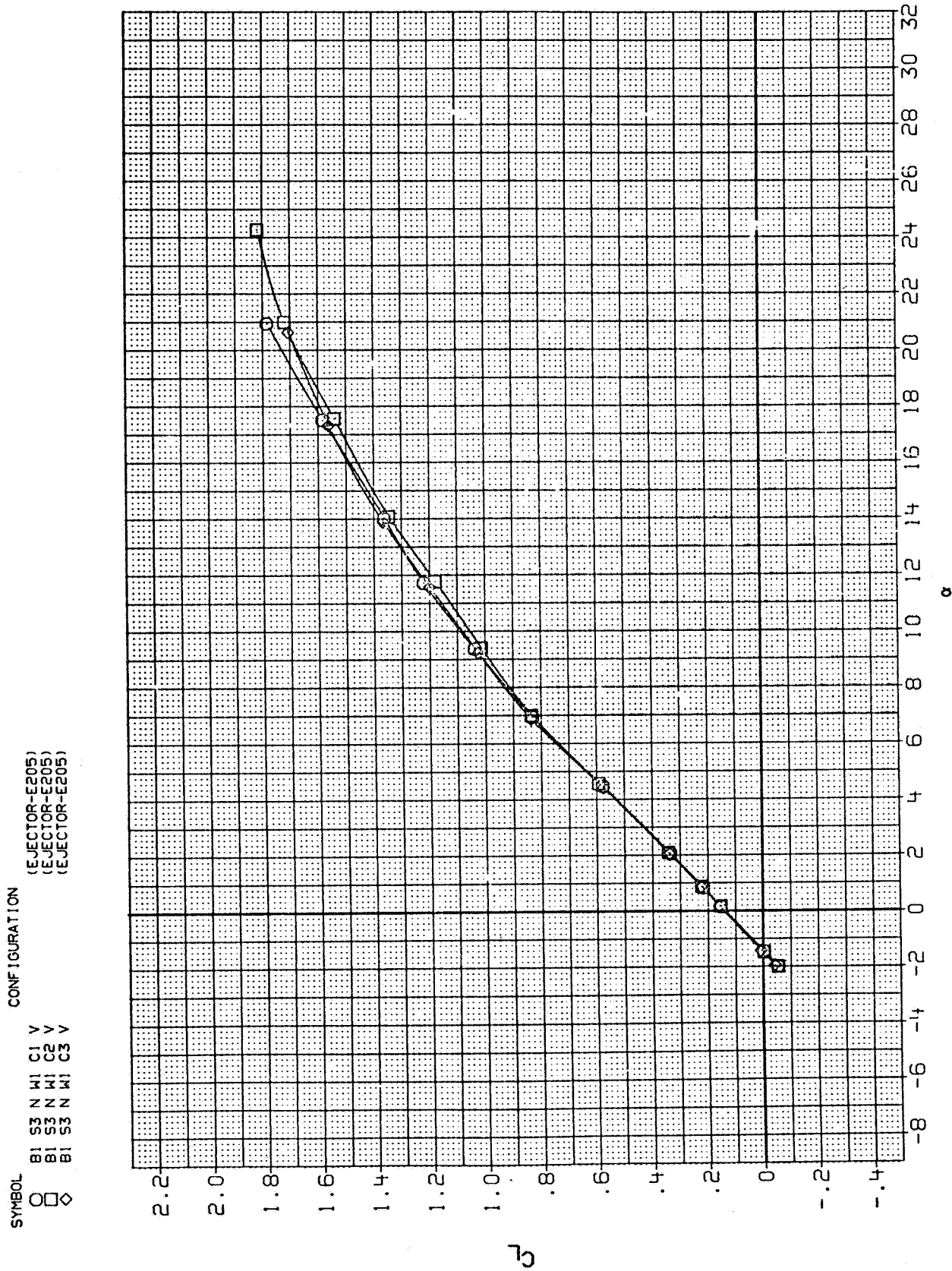


FIG. 65 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S3

MACH = .90

SYMBOL CONFIGURATION

$\square$ B1 S3 N W1 C1 V (EJECTOR-E205)
 $\circ$ B1 S3 N W1 C2 V (EJECTOR-E205)
 $\diamond$ B1 S3 N W1 C3 V (EJECTOR-E205)

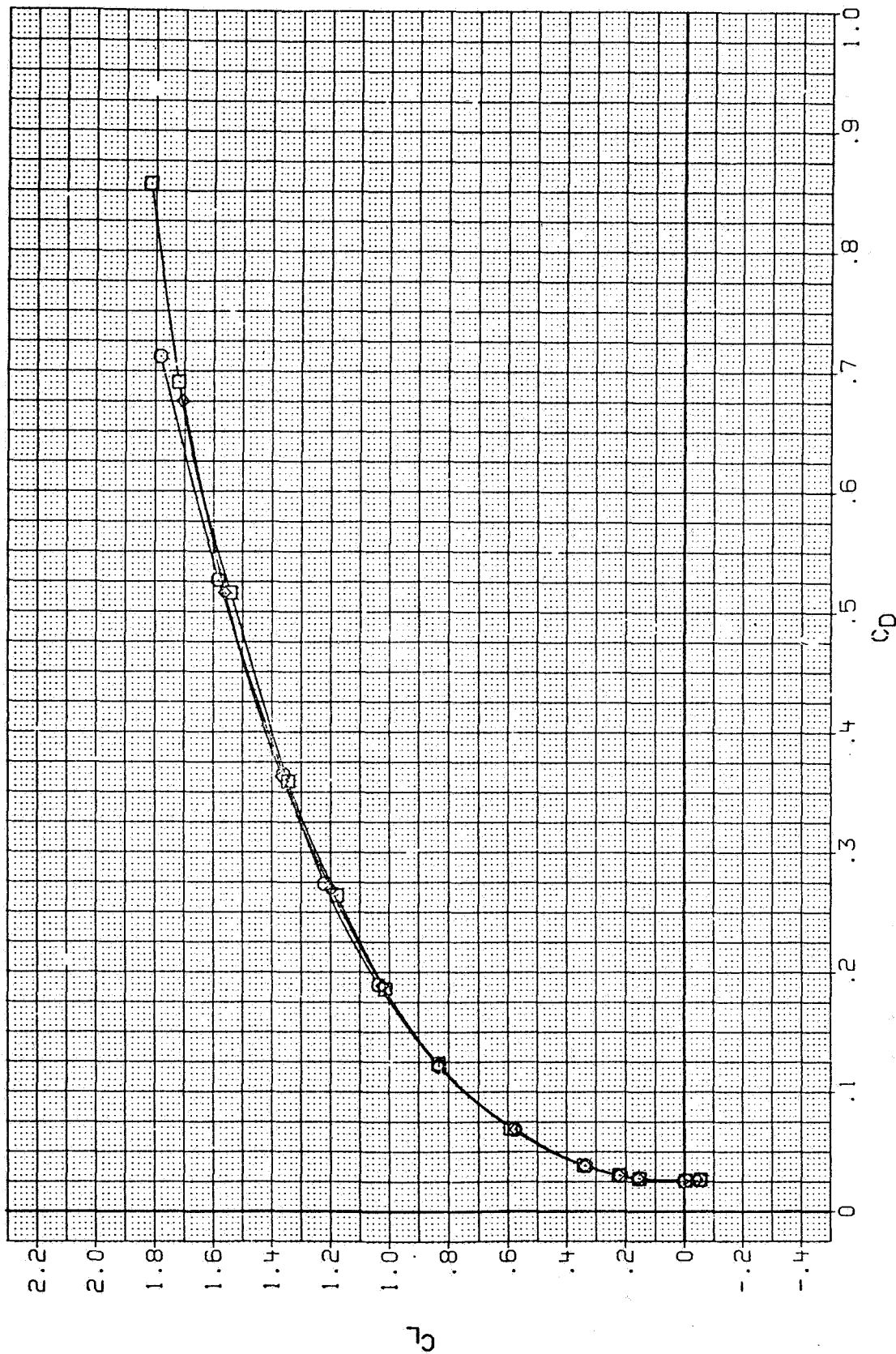


FIG. 65 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S3
 MACH = .90

SYMBOL CONFIGURATION

○ E1 S3 N W1 C1 V (EJECTOR-E205)
 □ B1 S3 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S3 N W1 C3 V (EJECTOR-E205)

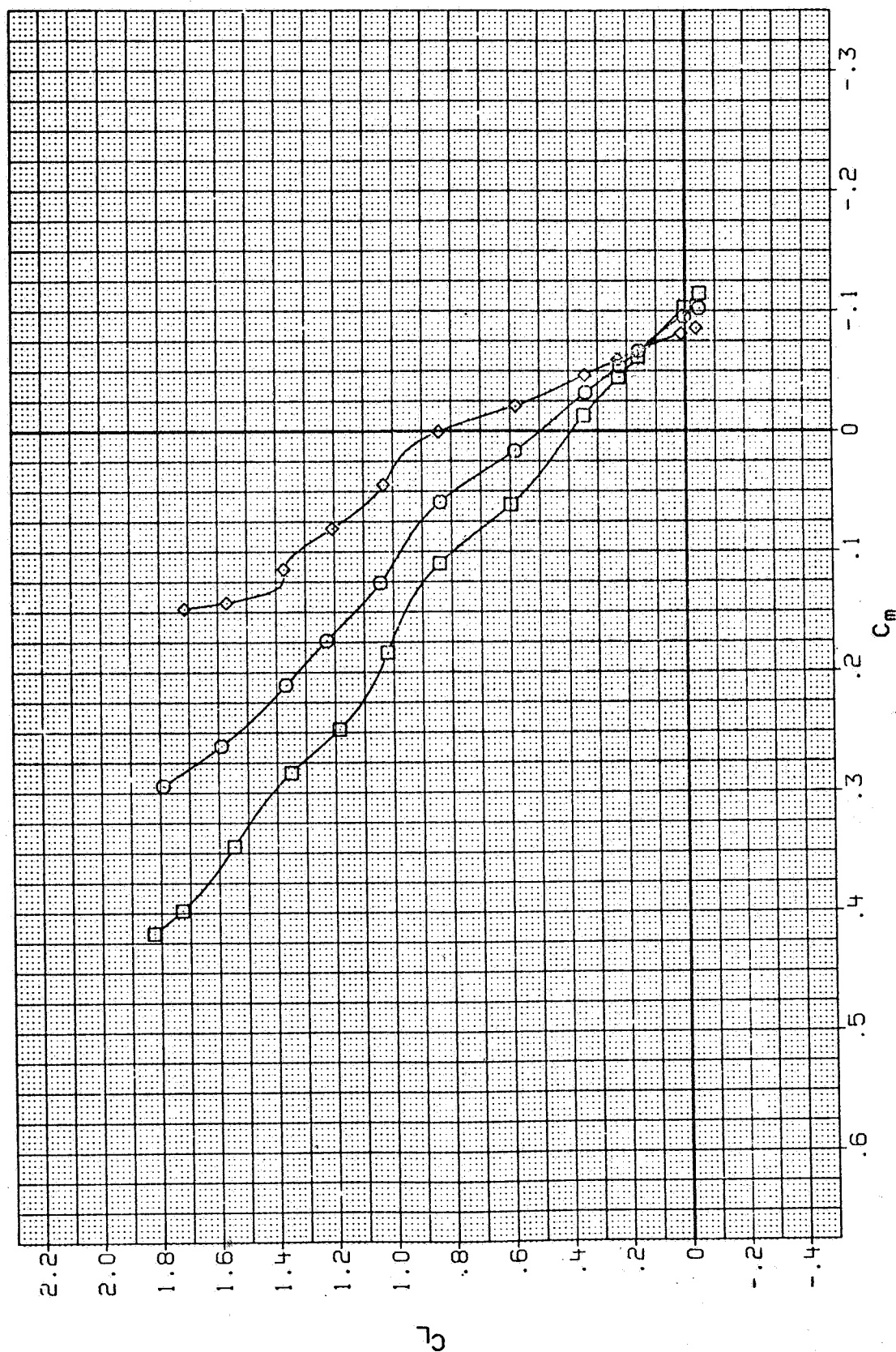


FIG. 65 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S3
 MACH = .90

SYMBOL CONFIGURATION
 B1 S3 N W1 C1 V (EJECTOR-E205)
 B1 S3 N W1 C2 V (EJECTOR-E205)
 B1 S3 N W1 C3 V (EJECTOR-E205)

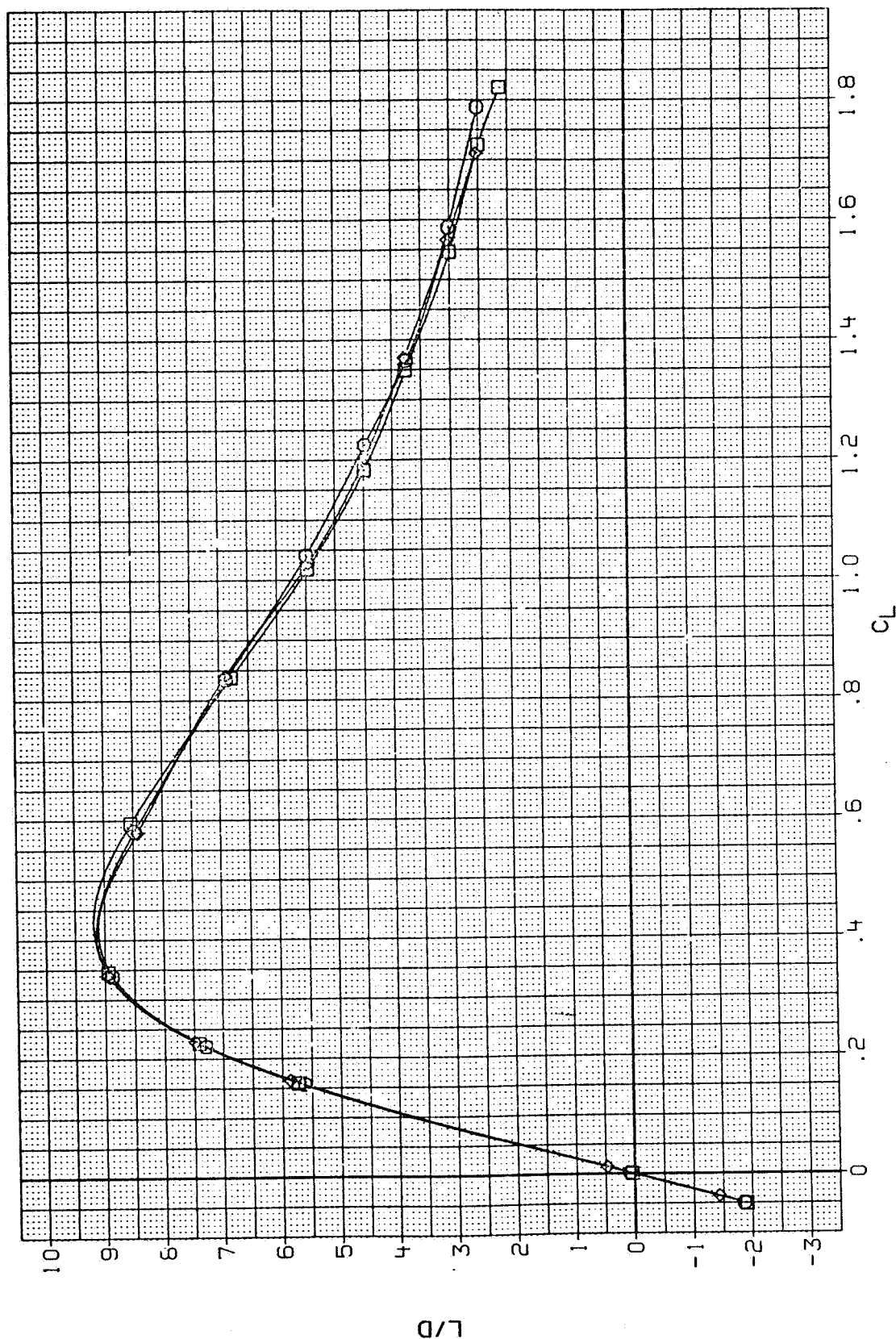


FIG. 65 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S3
 MACH = .90

SYMBOL CONFIGURATION

○ B1 S3 N W1 C1 V
 (EJECTOR-E205)
 □ B1 S3 N W1 C2 V
 (EJECTOR-E205)
 ◇ B1 S3 N W1 C3 V
 (EJECTOR-E205)

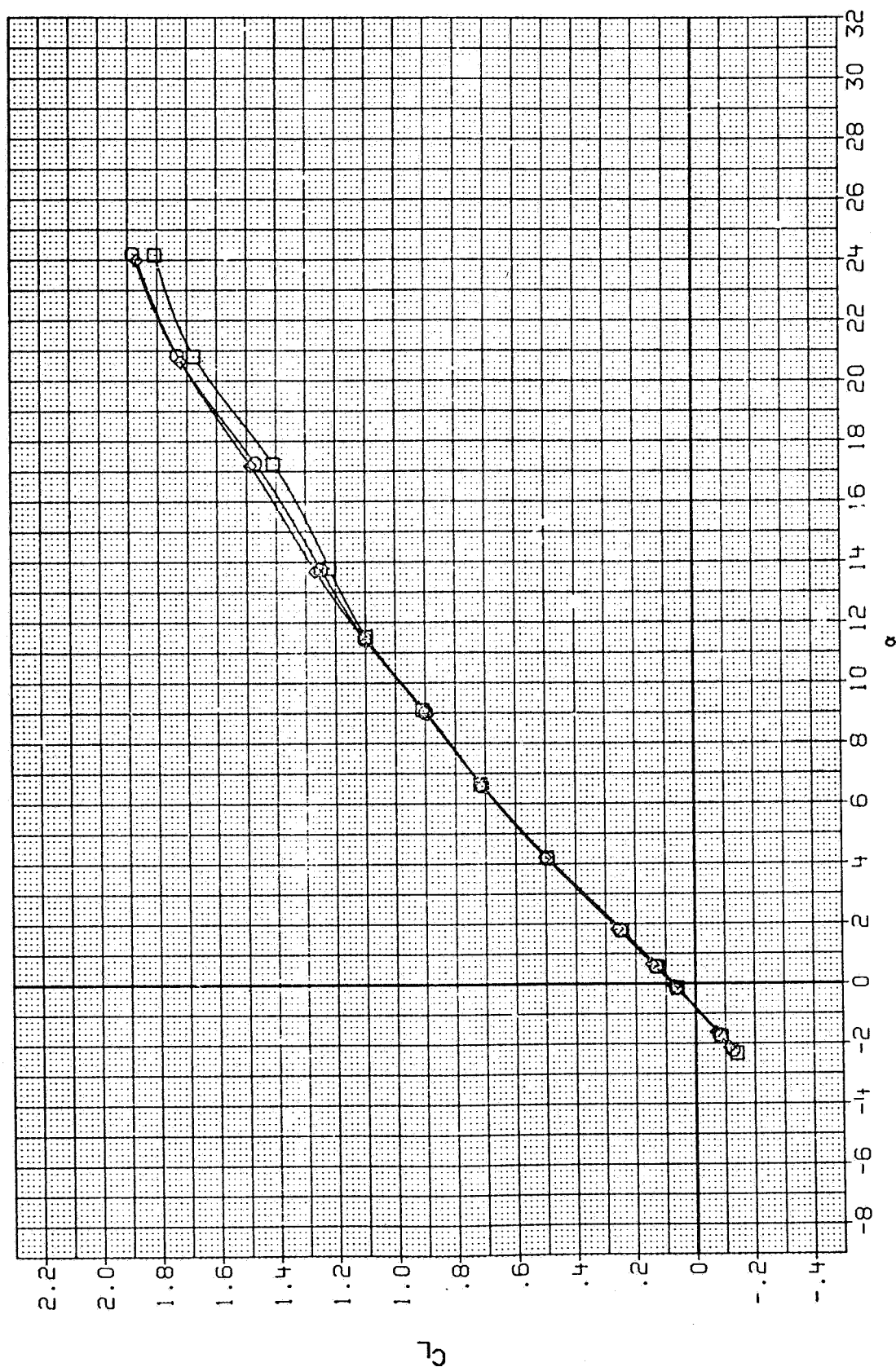


FIG. 66 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S3
 MACH = .90

SYMBOL CONFIGURATION
 ○ B1 S3 N W1 C1 V (EJECTOR-E205)
 □ B1 S3 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S3 N W1 C3 V (EJECTOR-E205)

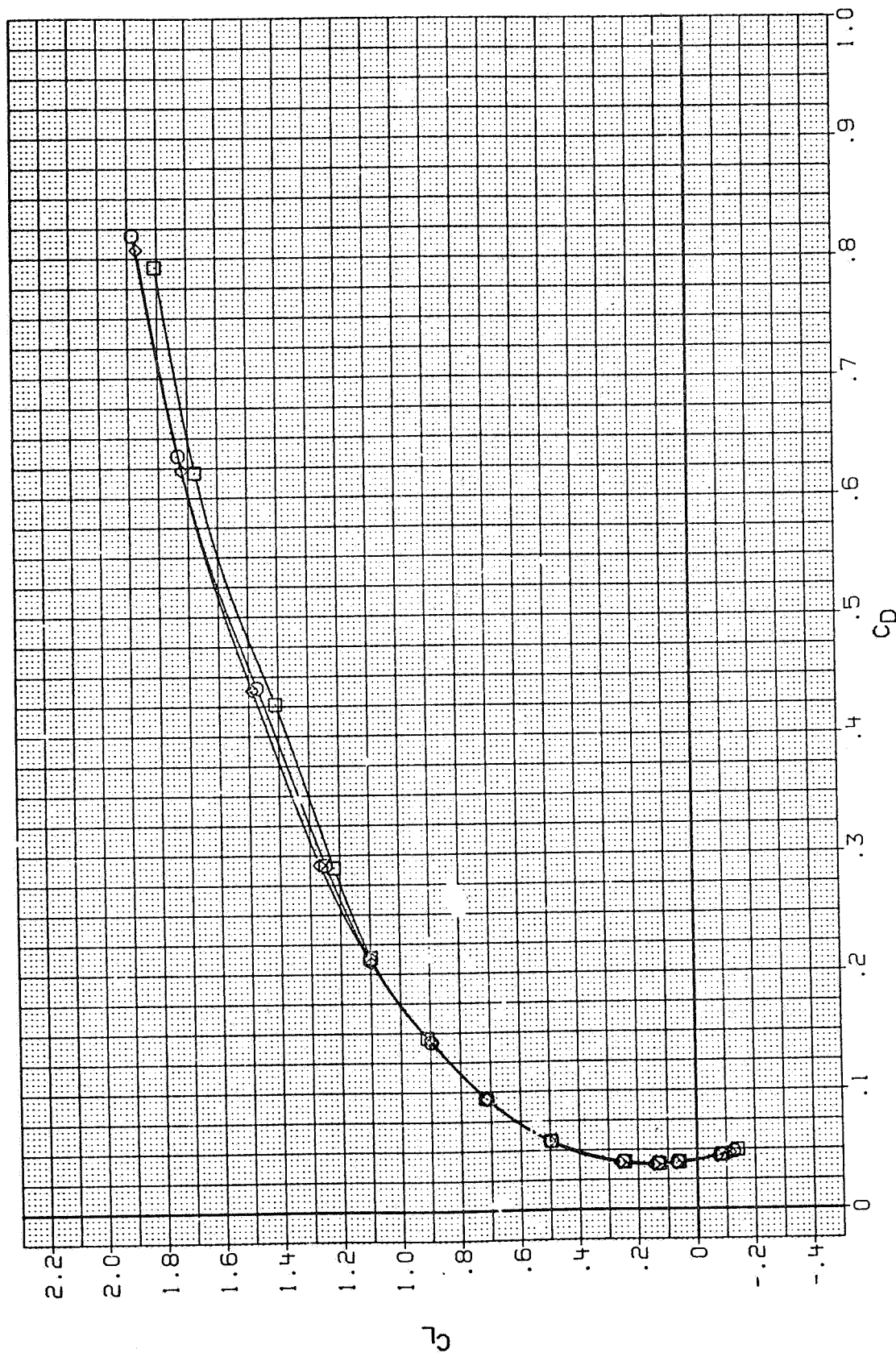


FIG. 66 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S3
 MACH = .90

SYMBOL CONFIGURATION
 ○ B1 S3 N W1 C1 V
 □ B1 S3 N W1 C2 V
 ◇ B1 S3 N W1 C3 V
 (EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

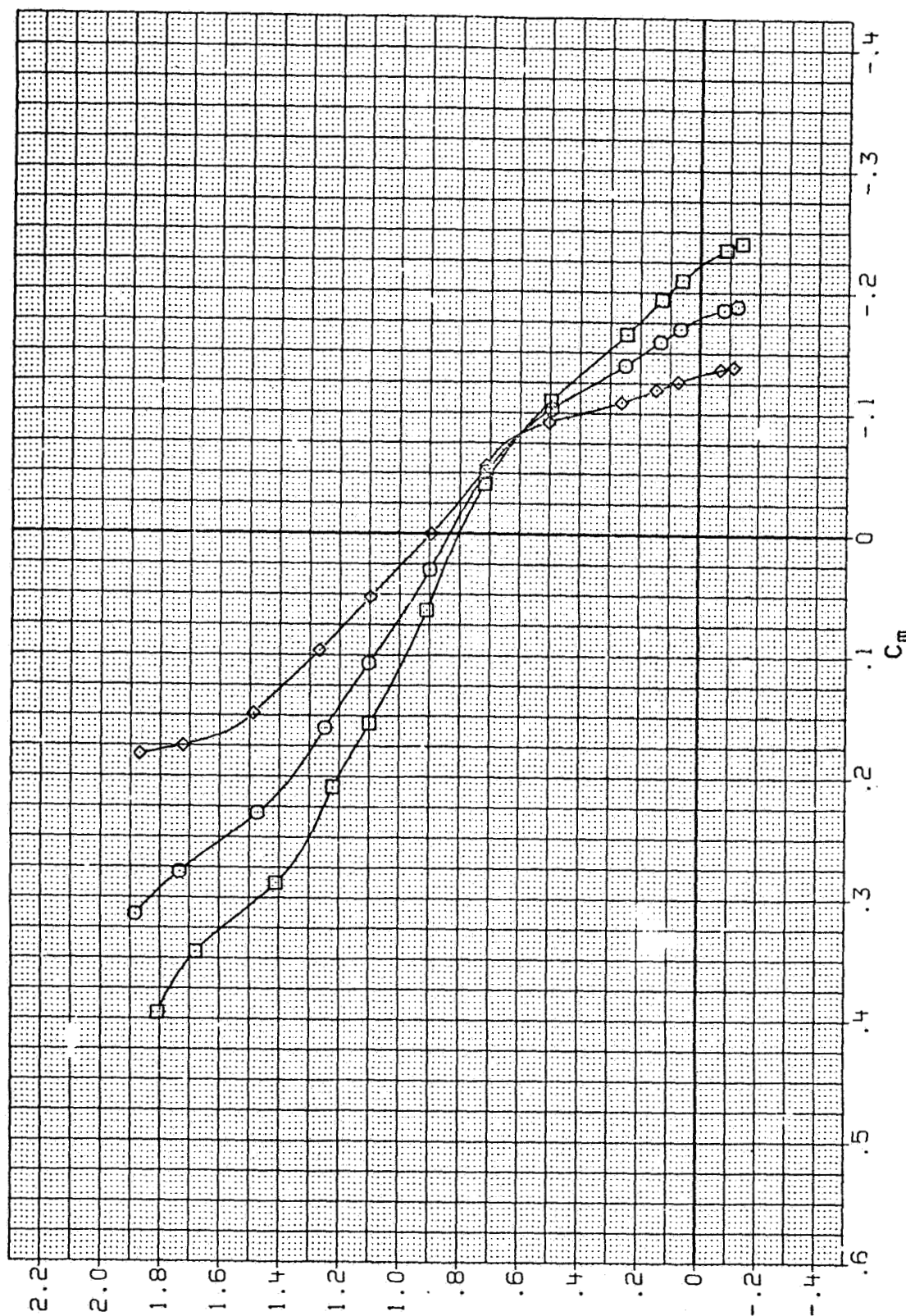


FIG. 66 CANARD LOCATION EFFECTS; LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S3
 MACH = .90

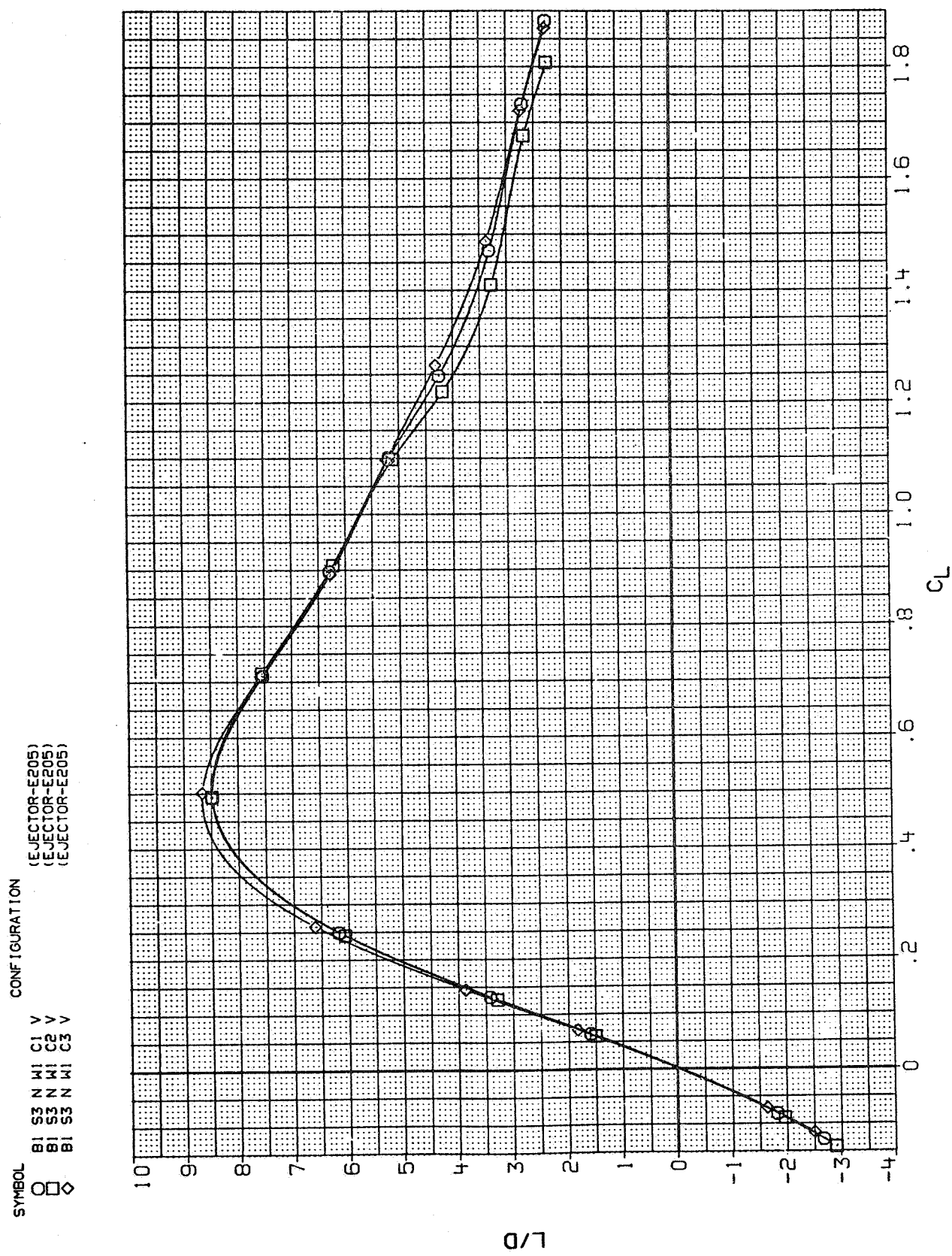


FIG. 66 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = -10 DEGREES, STRAKE S3
MACH = .90

SYMBOL CONFIGURATION
 BI S3 N WI C1 V (EJECTOR-E205)
 BI S3 N WI C2 V (EJECTOR-E205)
 BI S3 N WI C3 V (EJECTOR-E205)

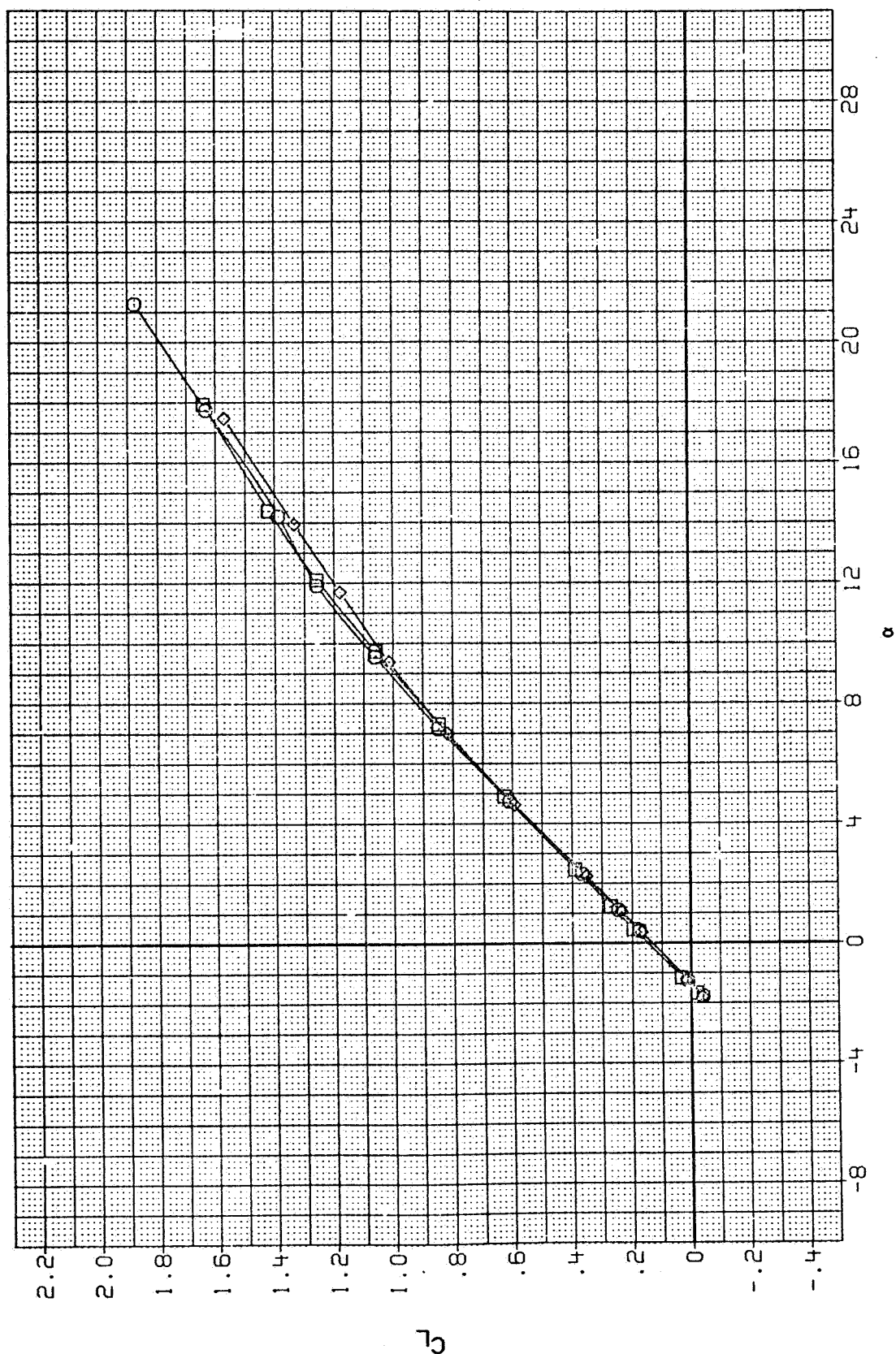


FIG. 67 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S3
 MACH = 1.20

SYMBOL		CONFIGURATION	
□	BI S3 N W1 C1 V	(EJECTOR-E205)	
□	BI S3 N W1 C2 V	(EJECTOR-E205)	
◇	BI S3 N W1 C3 V	(EJECTOR-E205)	

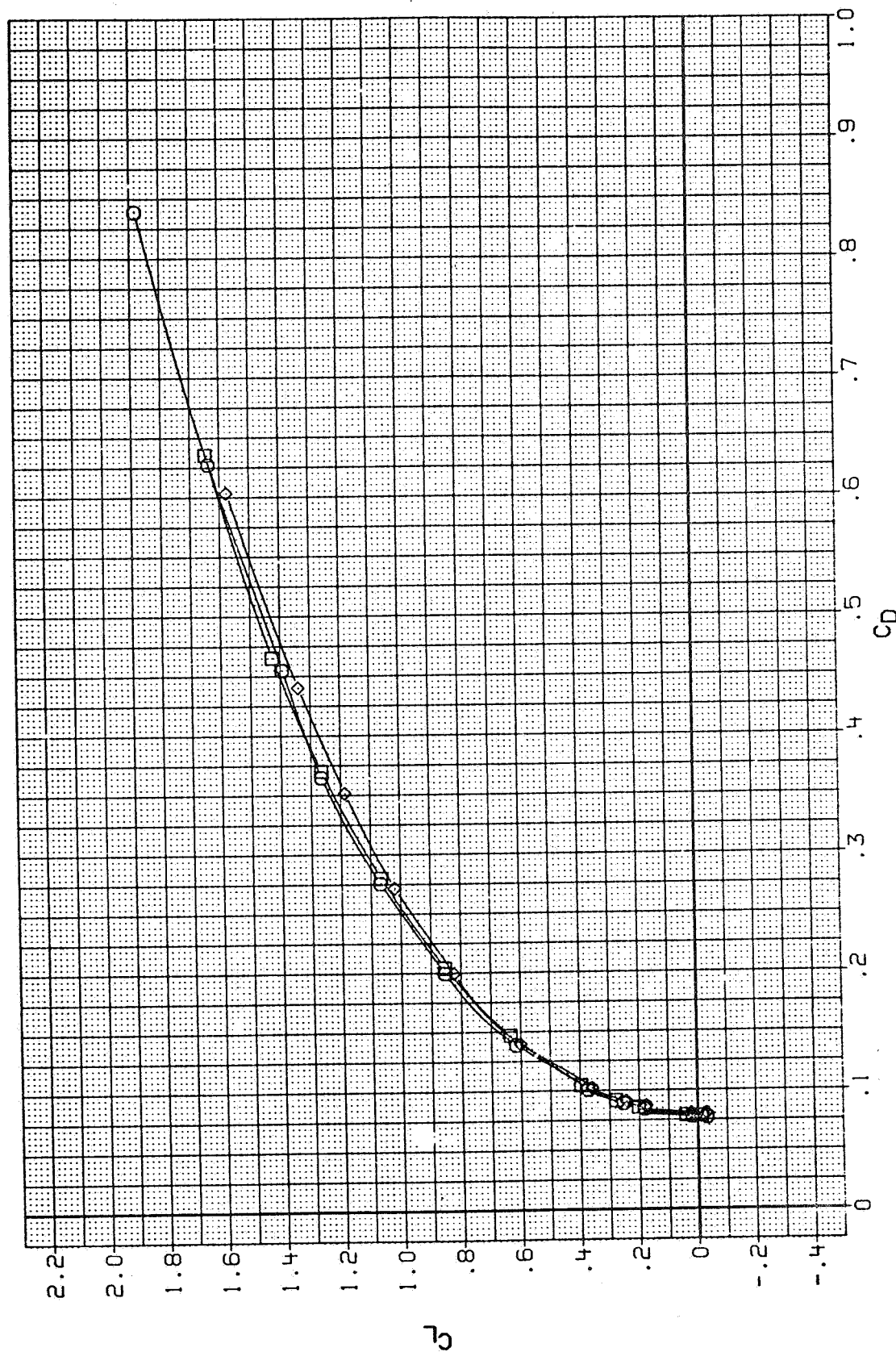


FIG. 67 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 10 DEGREES, STRAKE S3
MACH = 1.20

SYMBOL CONFIGURATION

□ BI S3 N WI C1 V
 ○ BI S3 N WI C2 V
 ◇ BI S3 N WI C3 V

(EJECTOR-E205)
 (EJECTOR-E205)
 (EJECTOR-E205)

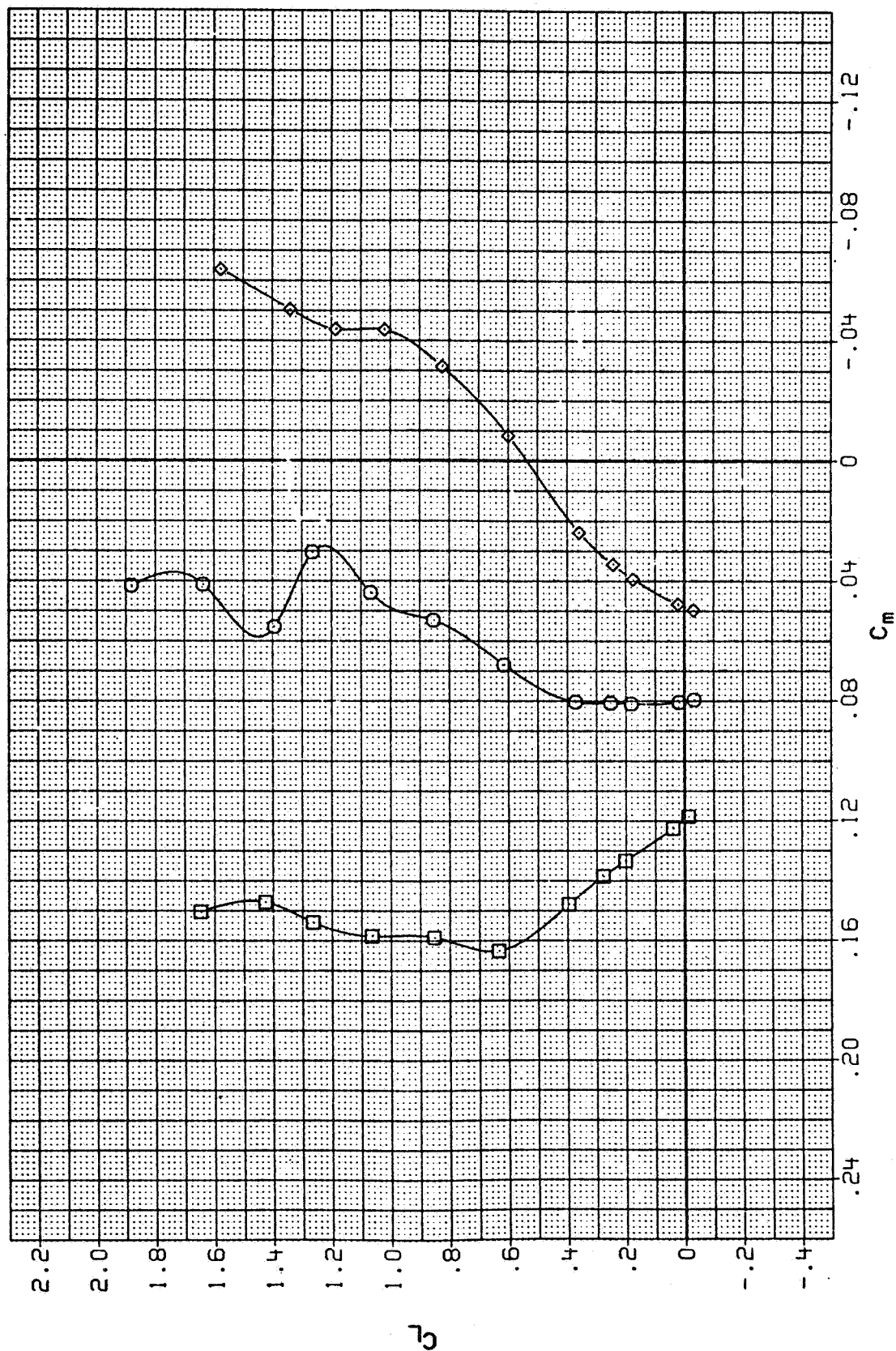


FIG. 67 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S3
 MACH = 1.20

SYMBOL		CONFIGURATION		
○	BI S3 N W1 C1 V	(EJECTOR-E205)		
□	BI S3 N W1 C2 V	(EJECTOR-E205)		
◇	BI S3 N W1 C3 V	(EJECTOR-E205)		

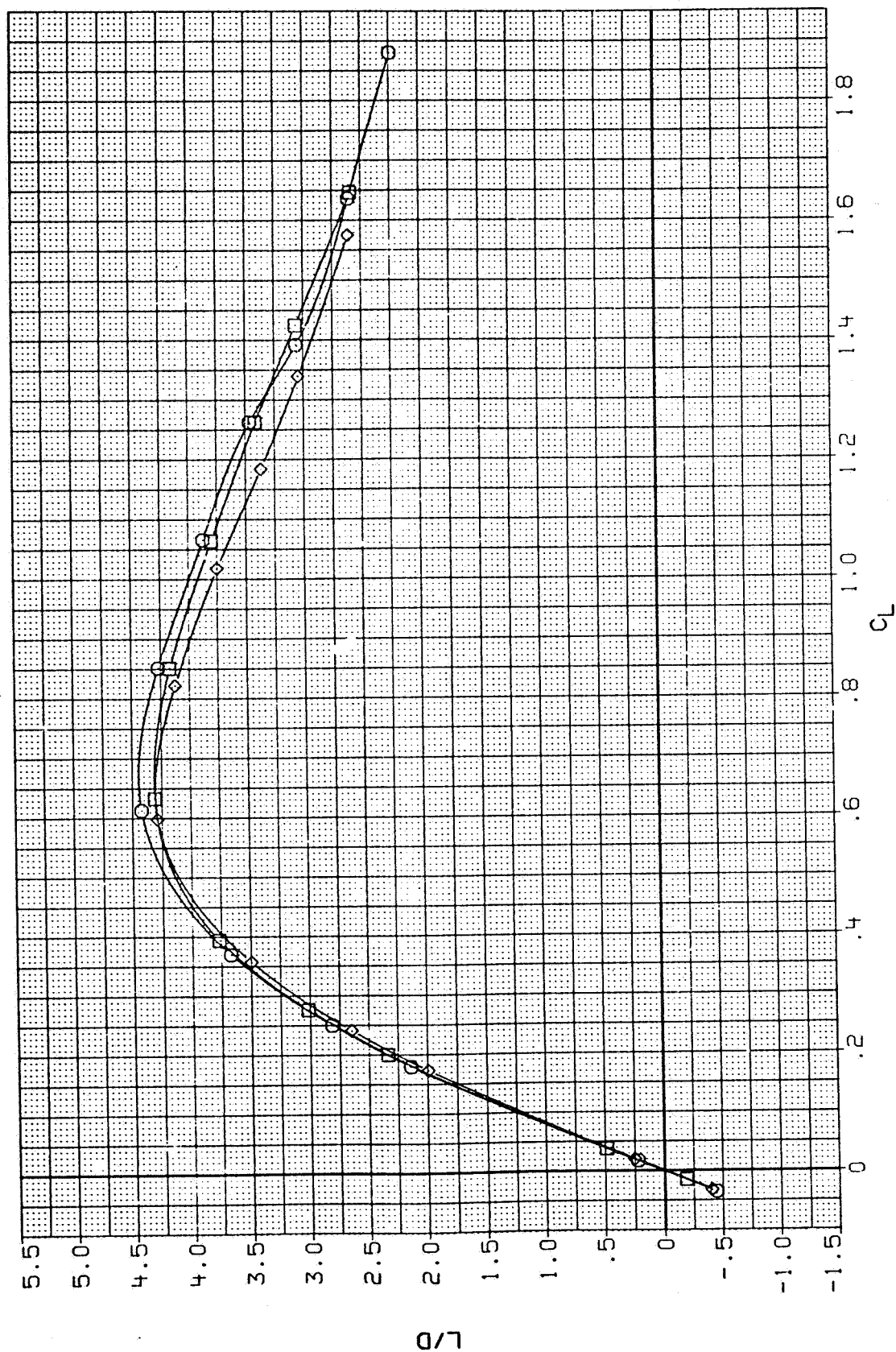


FIG. 67 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 10 DEGREES, STRAKE S3
 MACH = 1.20

SYMBOL CONFIGURATION

○ B1 S3 N W1 C1 V (EJECTOR-E205)

□ B1 S3 N W1 C2 V (EJECTOR-E205)

◇ B1 S3 N W1 C3 V (EJECTOR-E205)

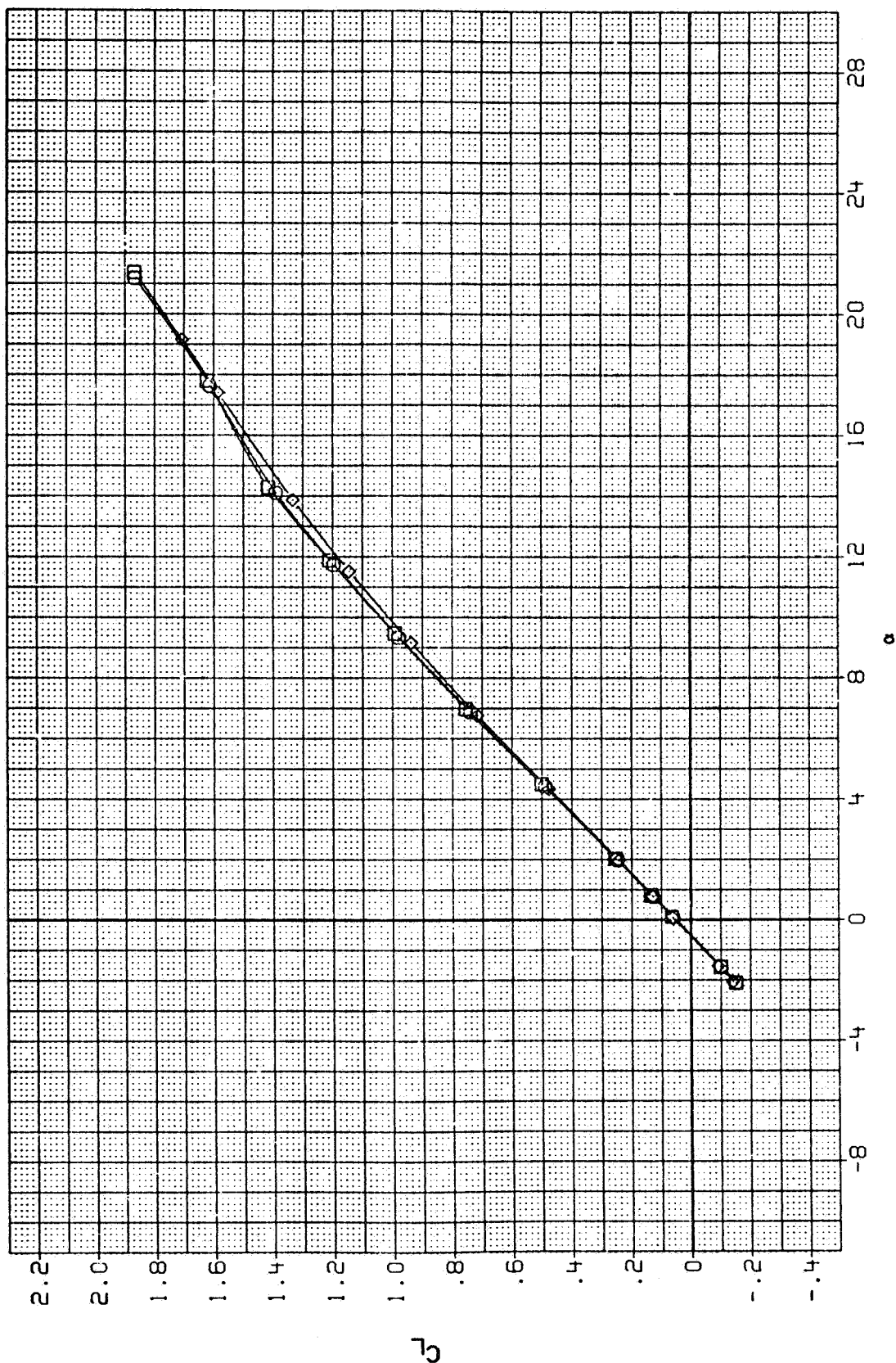


FIG. 68 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = 0 DEGREES, STRAKE S3
MACH = 1.20

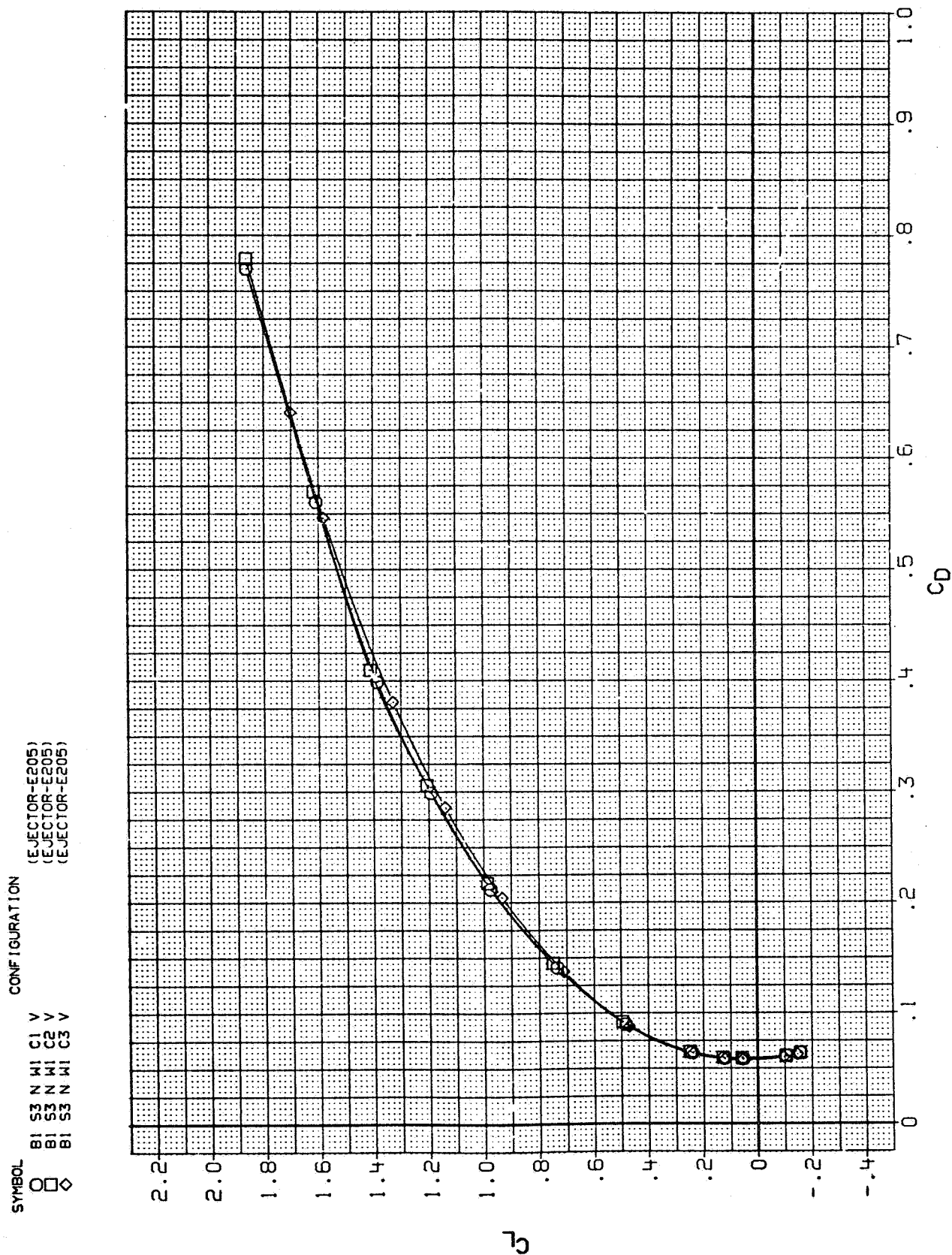


FIG. 68 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S3

MACH = 1.20

SYMBOL CONFIGURATION
 BI S3 N W1 C1 V (EJECTOR-E205)
 BI S3 N W1 C2 V (EJECTOR-E205)
 BI S3 N W1 C3 V (EJECTOR-E205)

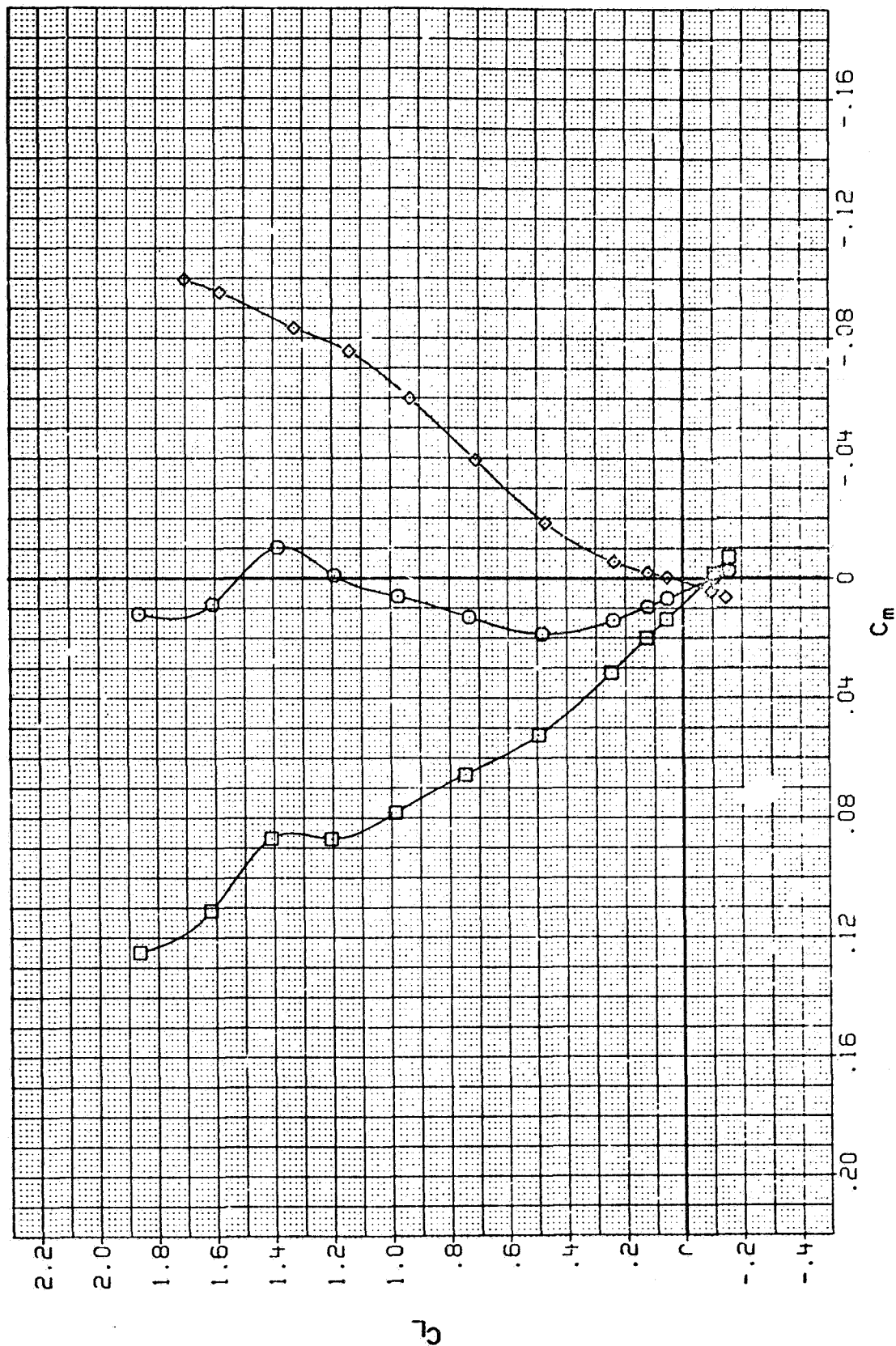


FIG. 68 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, SIRAKE S3
 MACH = 1.20

SYMBOL CONFIGURATION

BI S3 N WI C1 V (EJECTOR-E205)
 BI S3 N WI C2 V (EJECTOR-E205)
 BI S3 N WI C3 V (EJECTOR-E205)

○
 □
 ◇

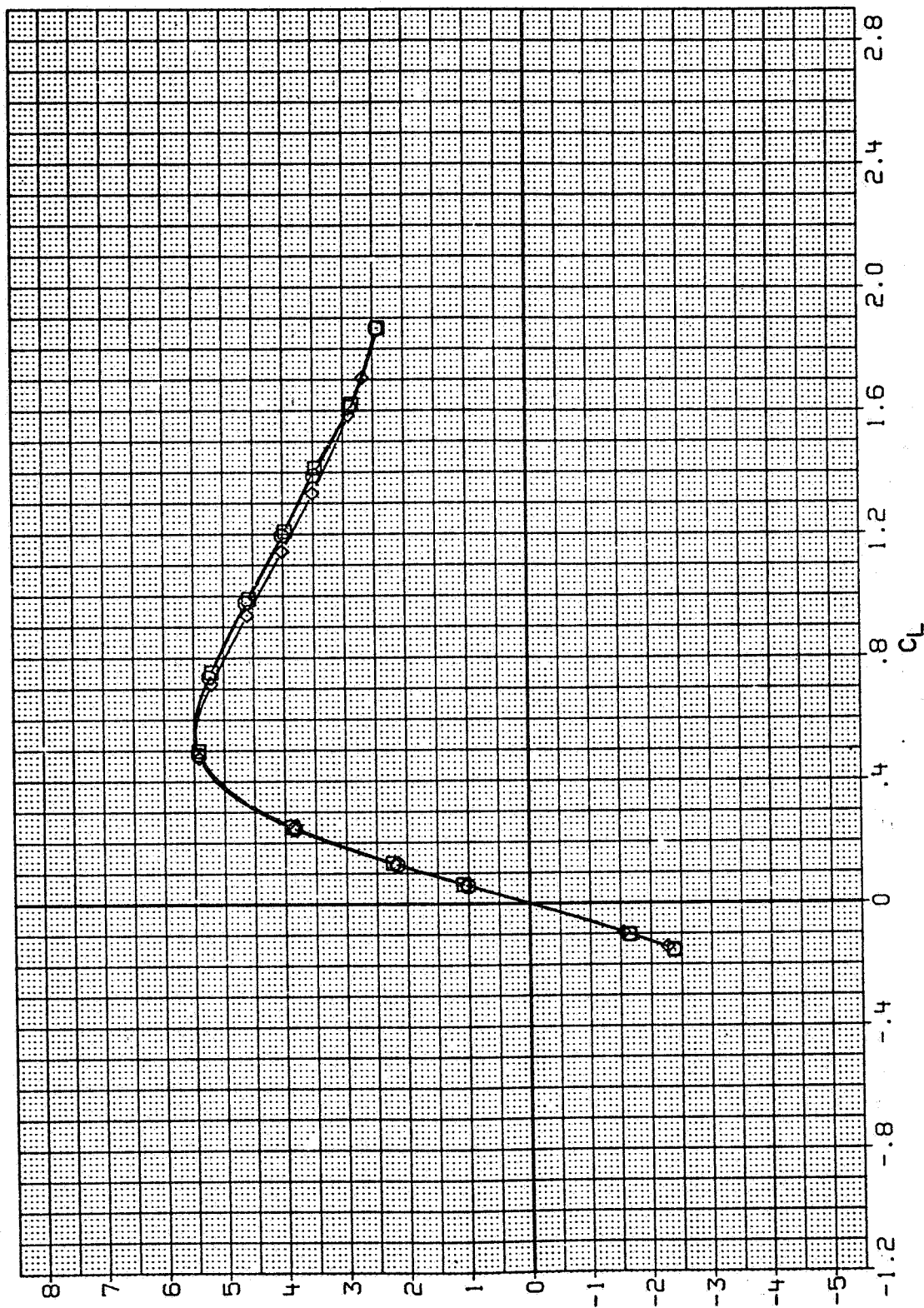


FIG. 68 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = 0 DEGREES, STRAKE S3
 MACH = 1.20

SYMBOL CONFIGURATION

○ (EJECTOR-E205)
 □ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

B1 S3 N W1 C1 V
 B1 S3 N W1 C2 V
 B1 S3 N W1 C3 V

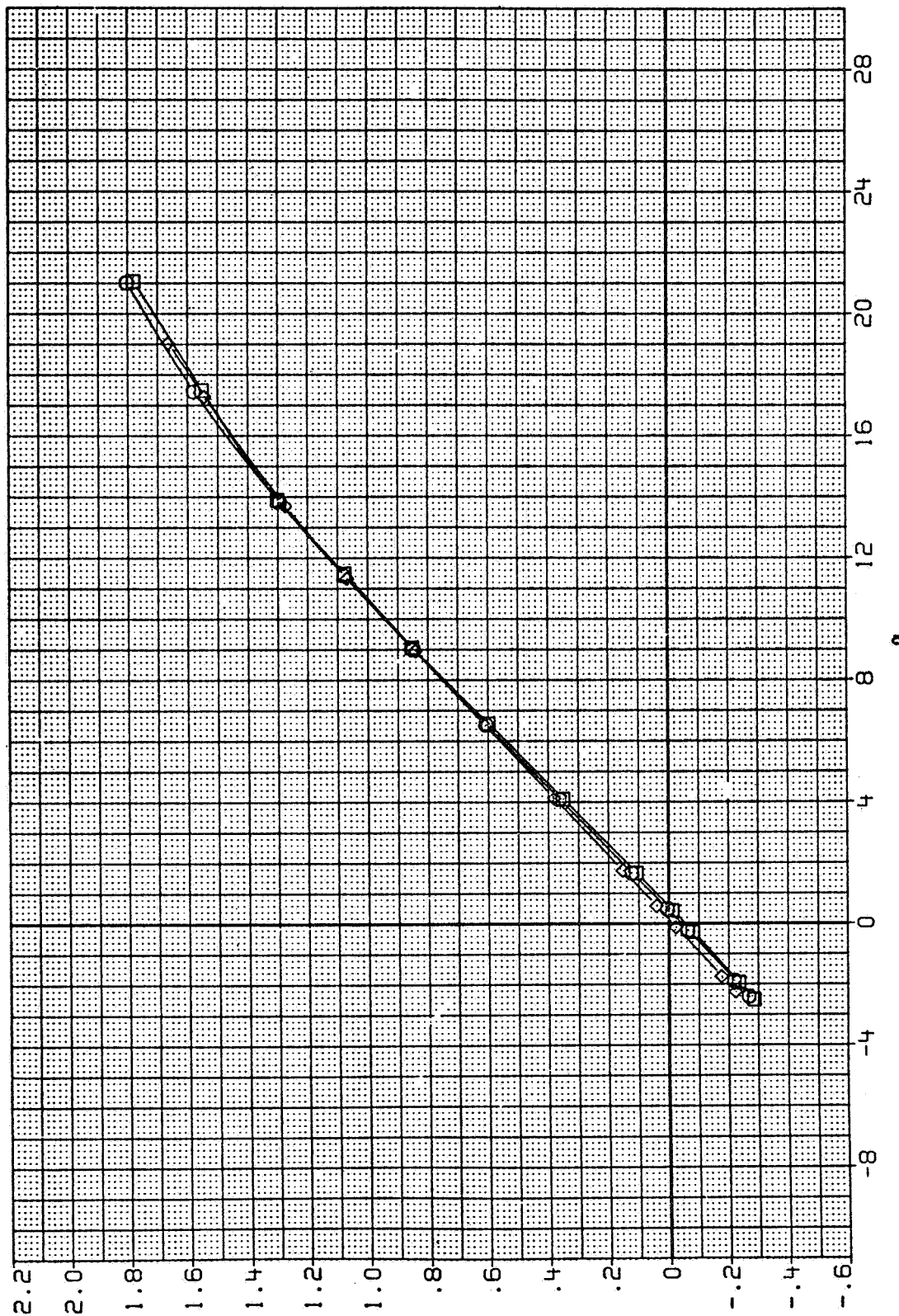


FIG. 69 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S3
 MACH = 1.20

SYMBOL CONFIGURATION

○	B1 S3 N W1 C1 V	(EJECTOR-E205)
□	B1 S3 N W1 C2 V	(EJECTOR-E205)
◇	B1 S3 N W1 C3 V	(EJECTOR-E205)

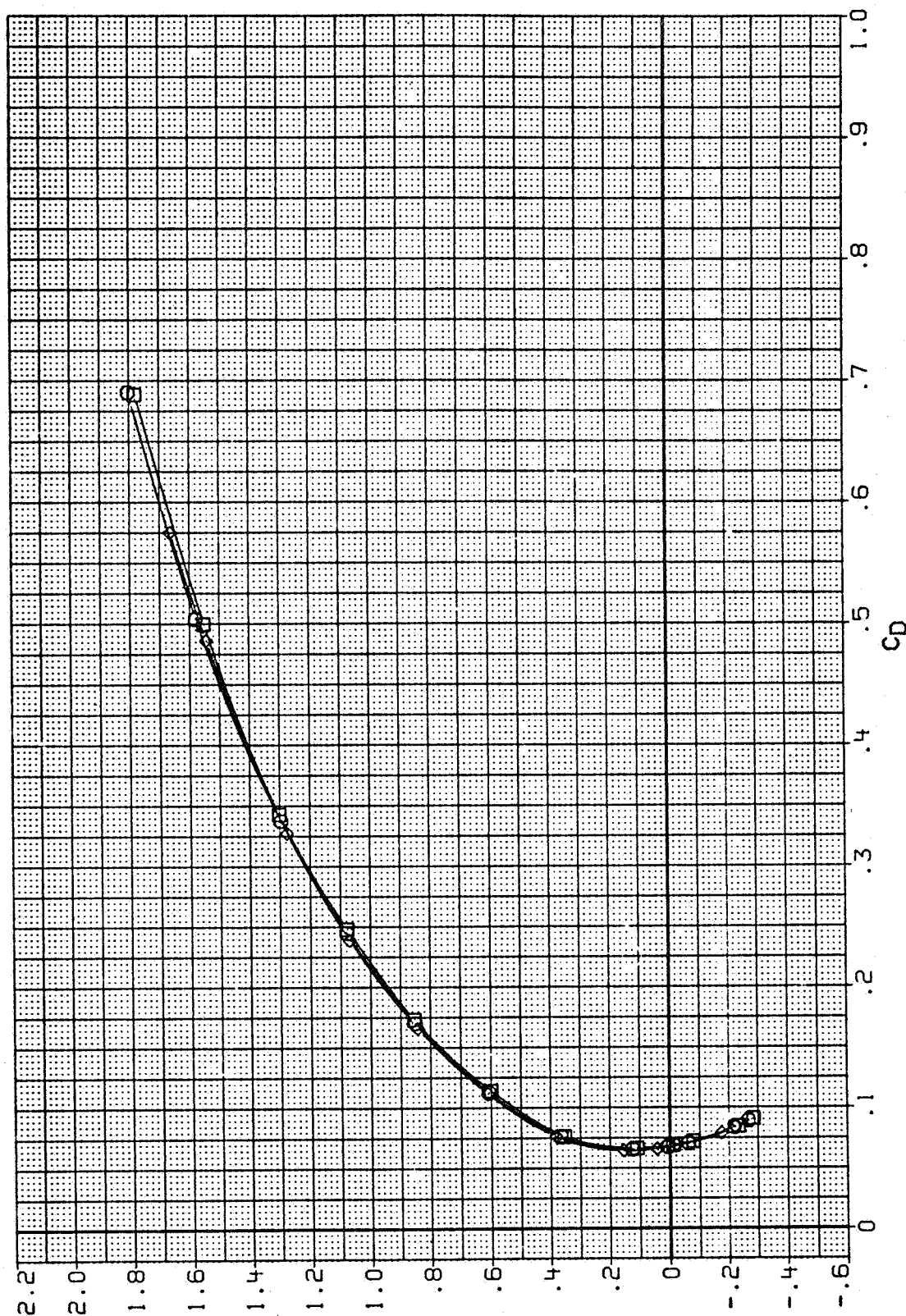


FIG. 69 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
CANARD = -10 DEGREES, STRAKE S3
MACH = 1.20

SYMBOL CONFIGURATION
 ○ B1 S3 N W1 C1 V (EJECTOR-E205)
 □ B1 S3 N W1 C2 V (EJECTOR-E205)
 ◇ B1 S3 N W1 C3 V (EJECTOR-E205)

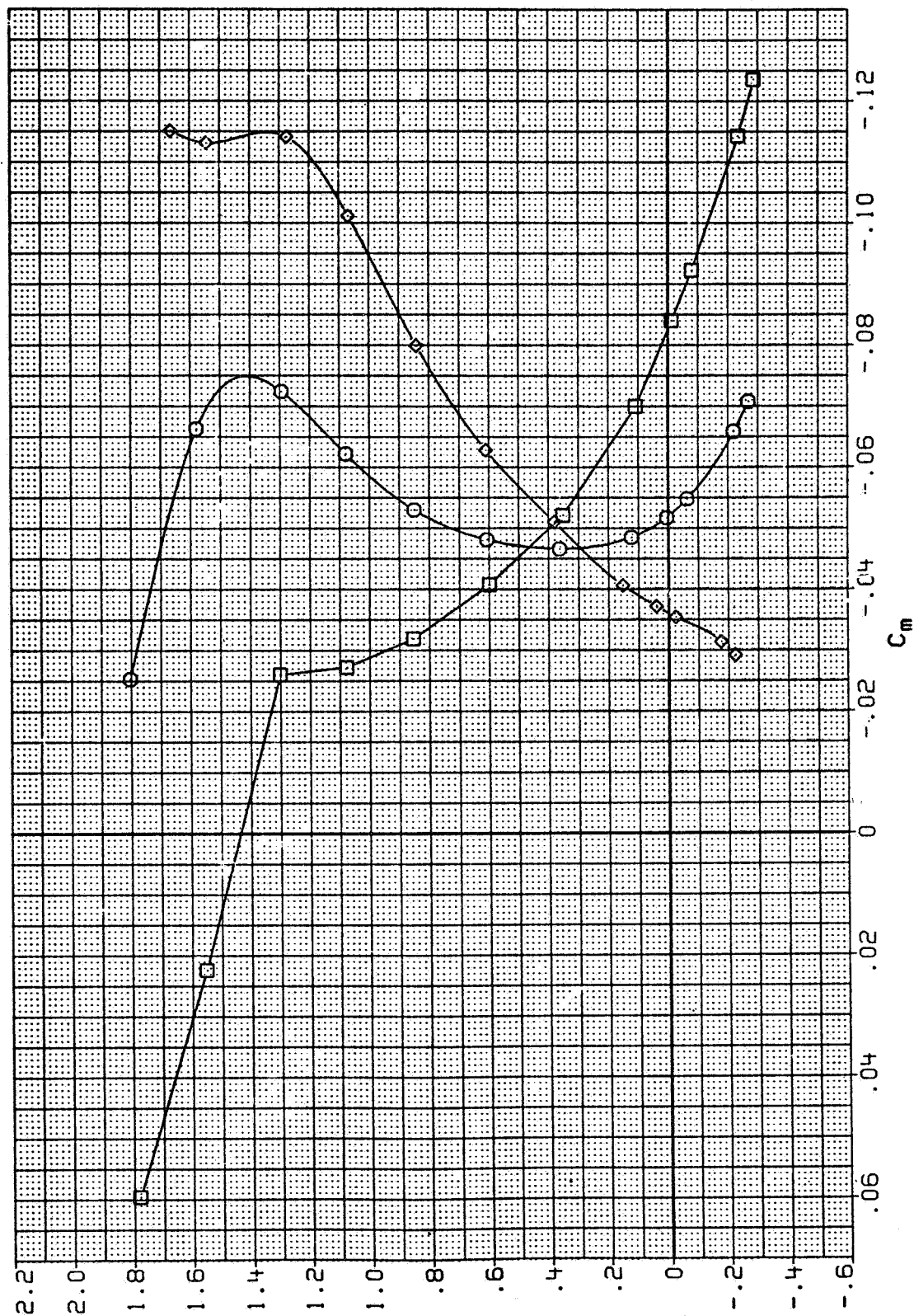


FIG. 69 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S3
 MACH = 1.20

SYMBOL CONFIGURATION

○ (EJECTOR-E205)
 □ (EJECTOR-E205)
 ◇ (EJECTOR-E205)

BI S3 N HI C1 V
 BI S3 N HI C2 V
 BI S3 N HI C3 V

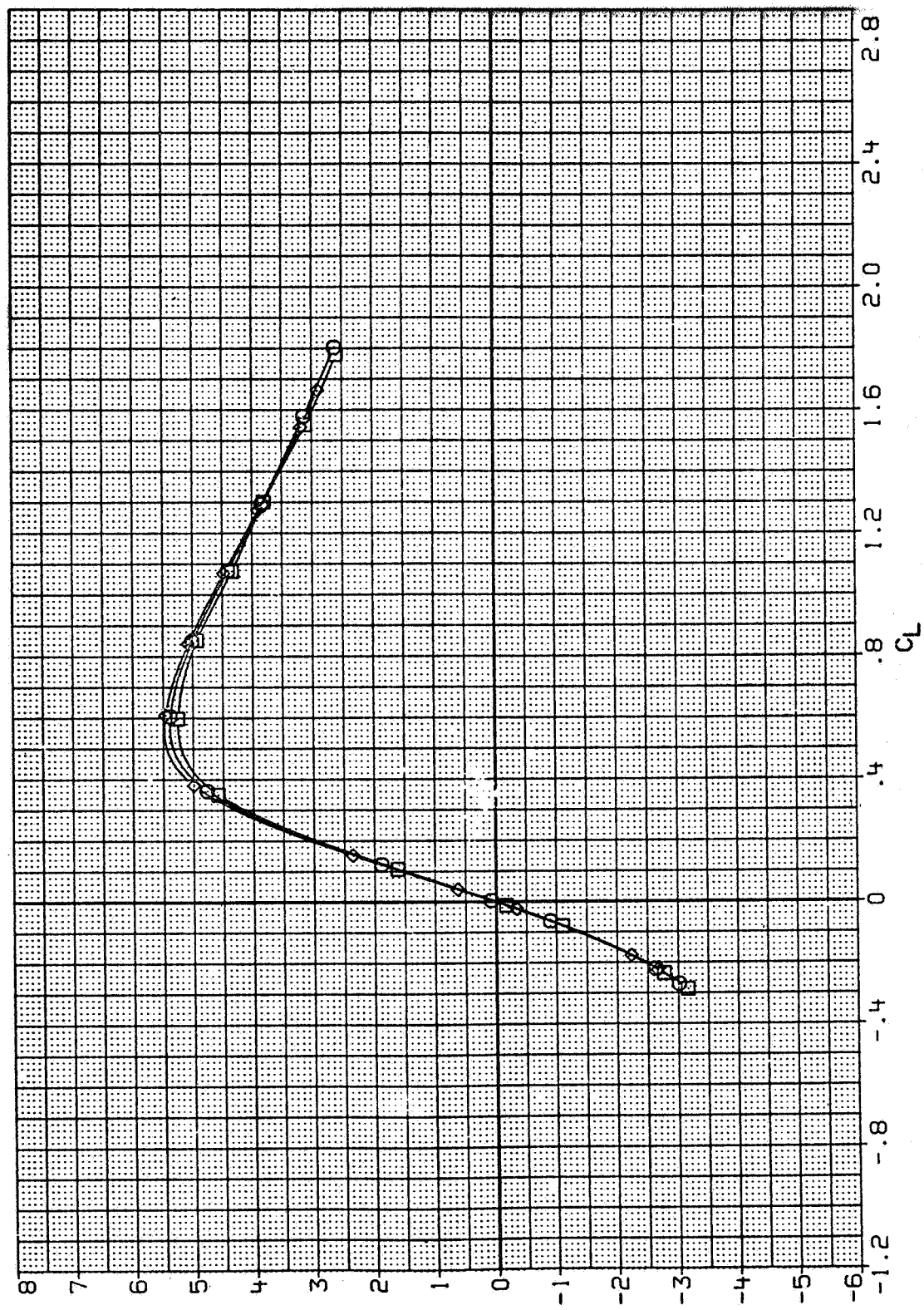


FIG. 69 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS
 CANARD = -10 DEGREES, STRAKE S3
 MACH = 1.20

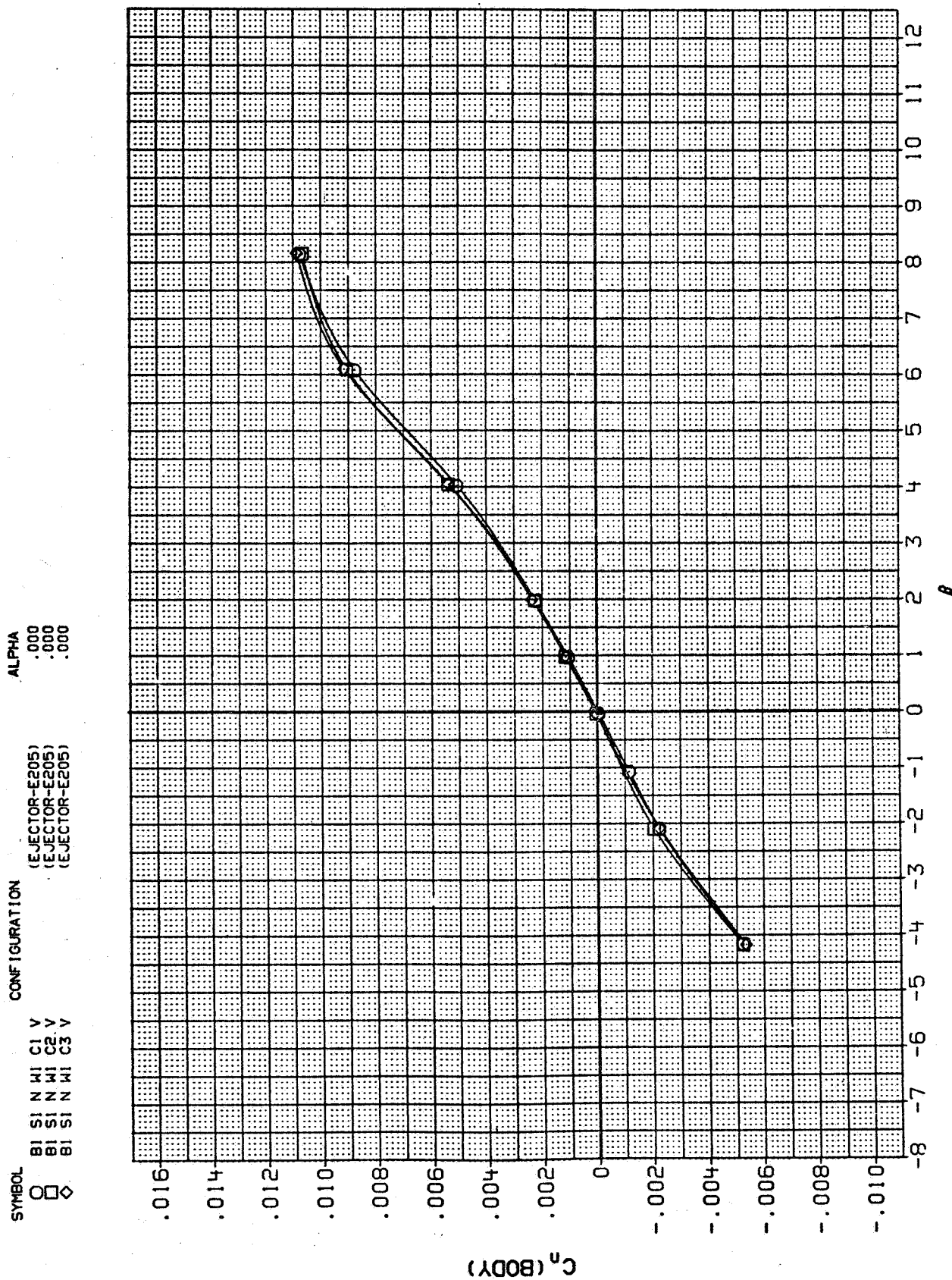


FIG. 70 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 $\alpha = 0$ DEGREES, VERTICAL TAIL ON

MACH = .90

SYMBOL CONFIGURATION ALPHA

○ (EJECTOR-E205) .000
 □ (EJECTOR-E205) .000
 ◇ (EJECTOR-E205) .000

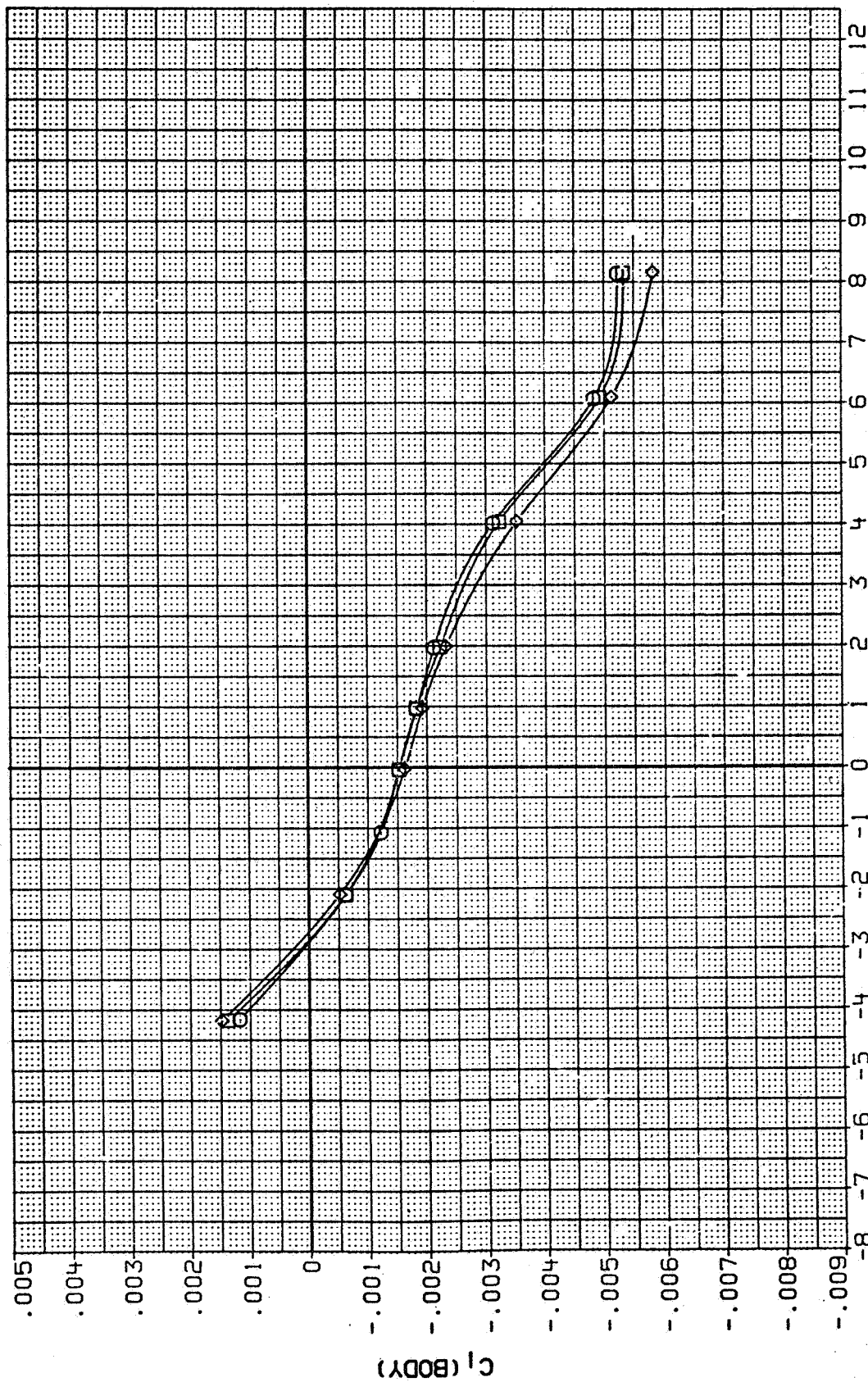


FIG. 70 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 0 DEGREES, VERTICAL TAIL ON

MACH = .90

SYMBOL CONFIGURATION ALPHA

○ (EJECTOR-E205) .000
 ◇ (EJECTOR-E205) .000

BI SI N WI C1 V
 BI SI N WI C2 V
 BI SI N WI C3 V

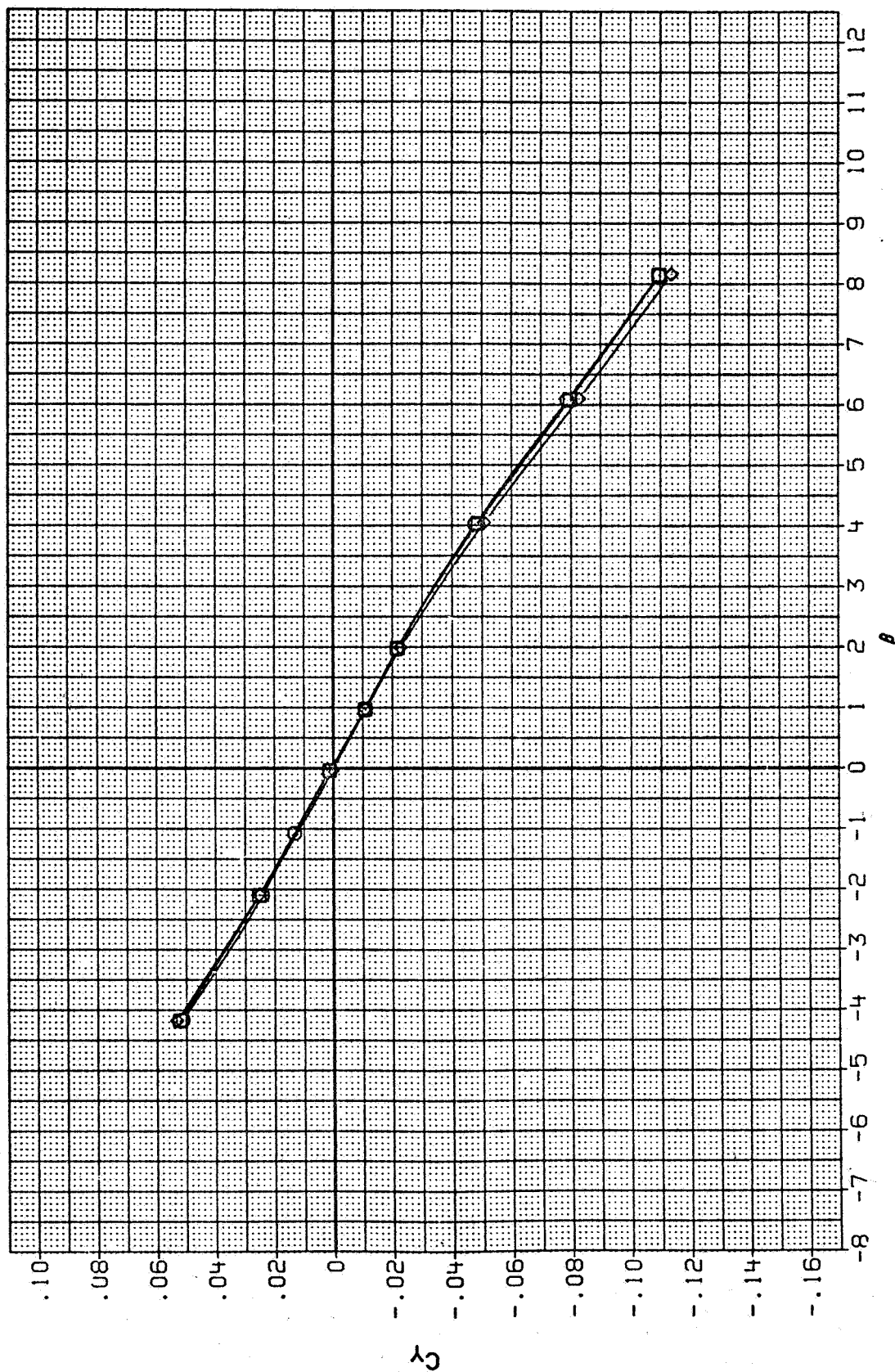


FIG. 70 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = .90

SYMBOL CONFIGURATION ALPHA
 □ (EJECTOR-E205) 17.500
 ○ (EJECTOR-E605) 17.500
 ◇ (EJECTOR-E205) 17.500

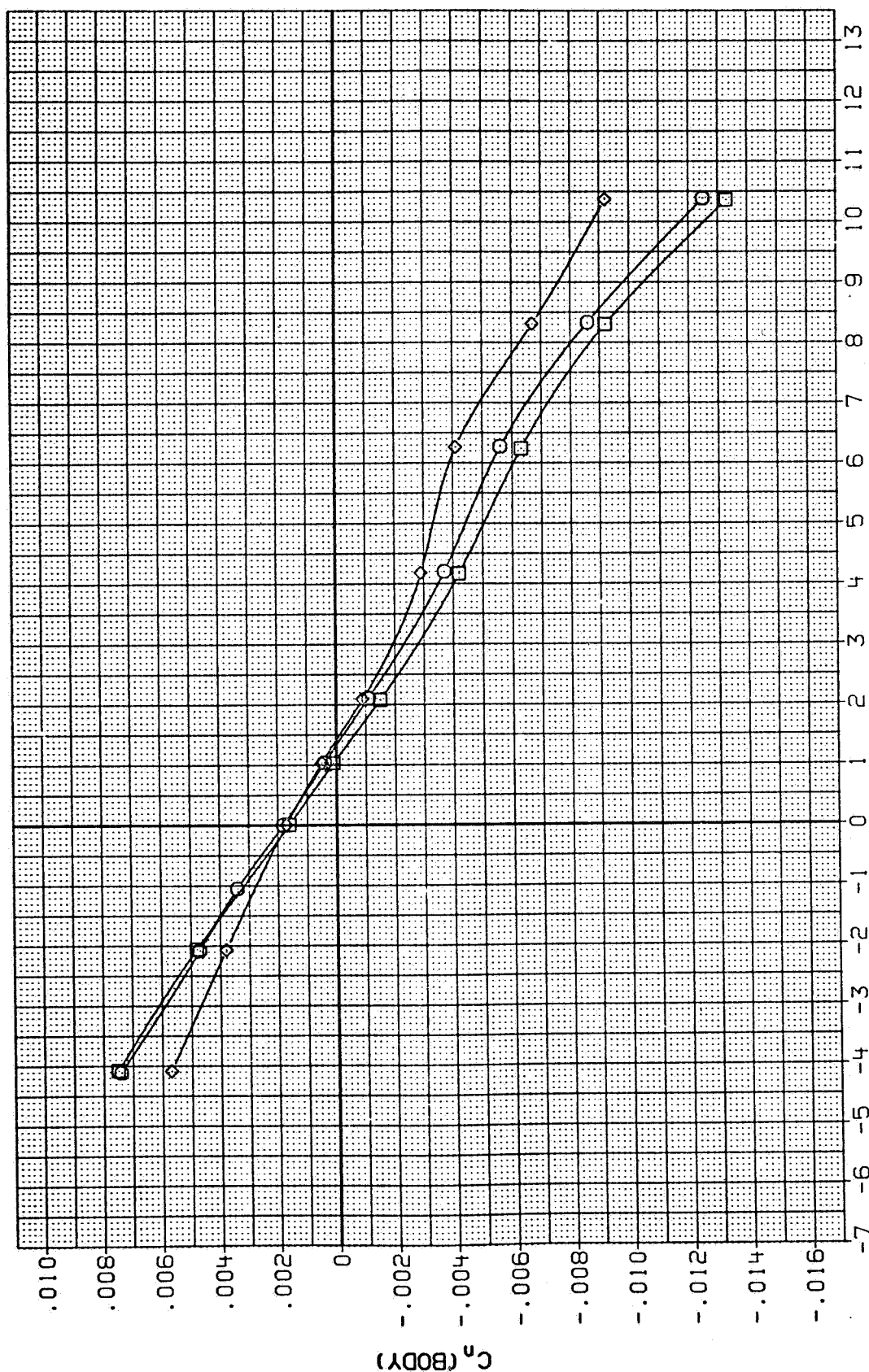


FIG. 70 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL ON

MACH = 0.90

SYMBOL	BI SI N WI C1 V BI SI N WI C2 V BI SI N WI C3 V	CONFIGURATION	(EJECTOR-E205) (EJECTOR-E205) (EJECTOR-E205)	ALPHA
				17.500
				17.500
				17.500

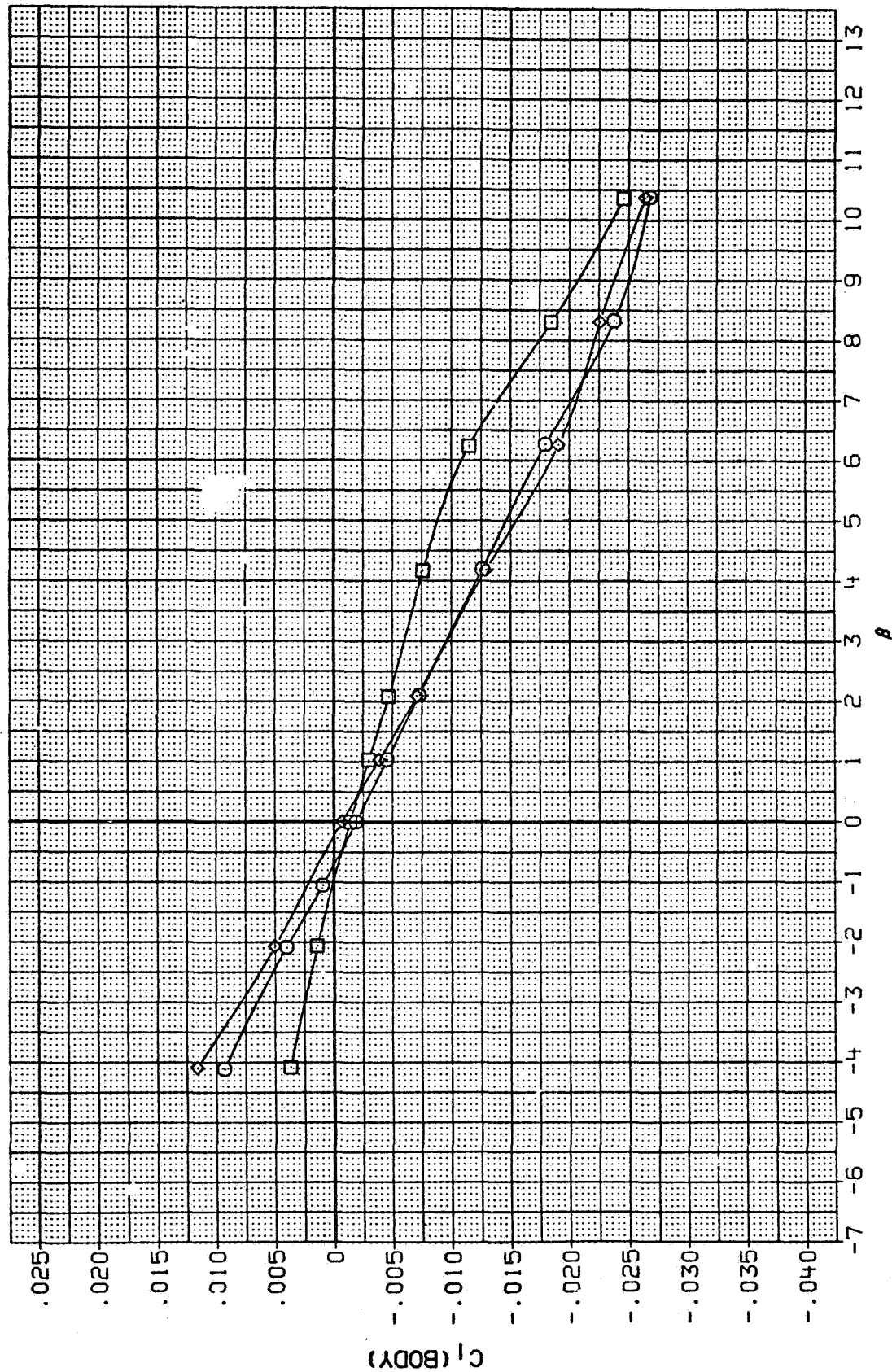


FIG. 70 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL ON
 MACH = .90

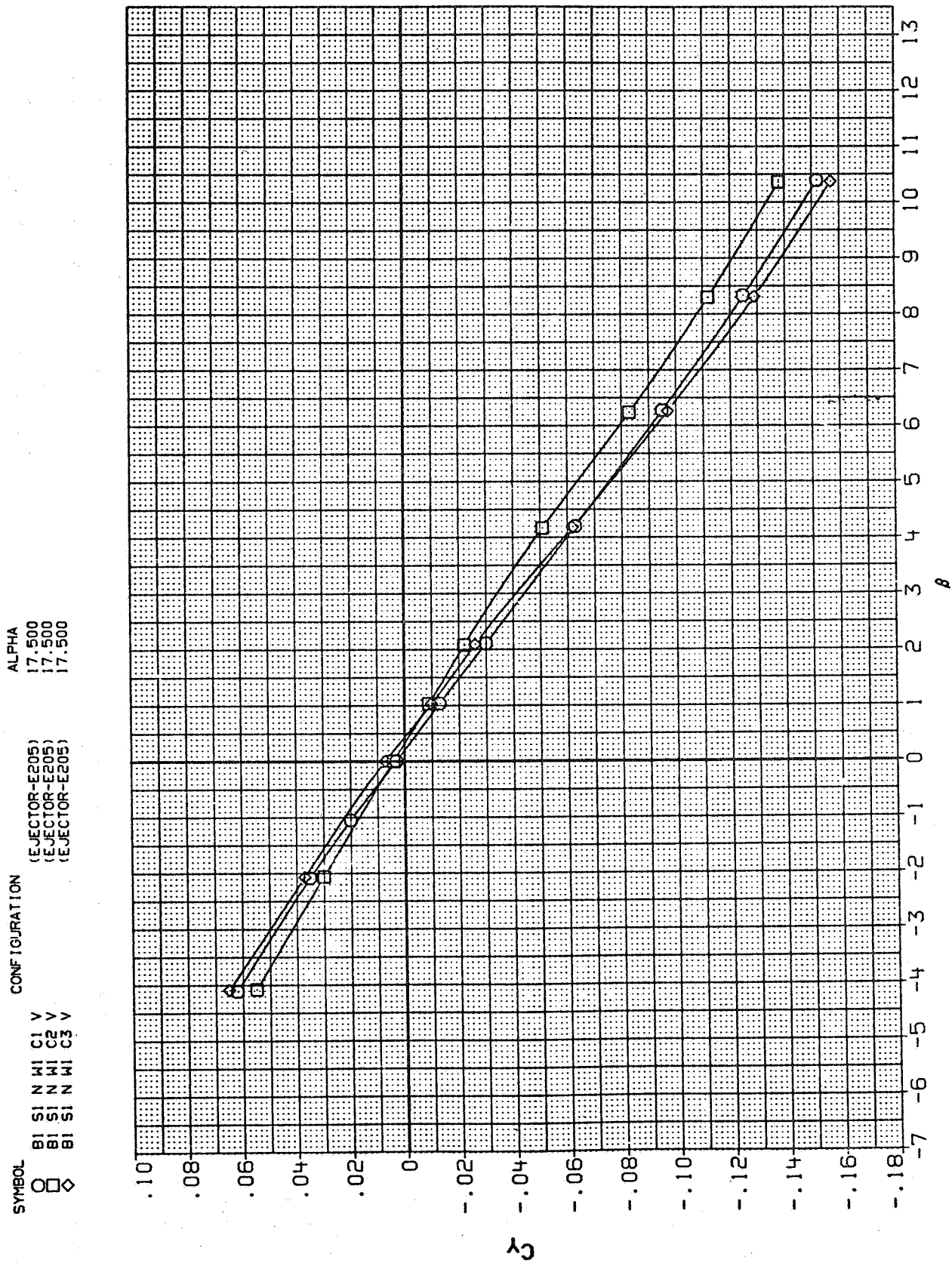


FIG. 70 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL ON
 MACH = .90

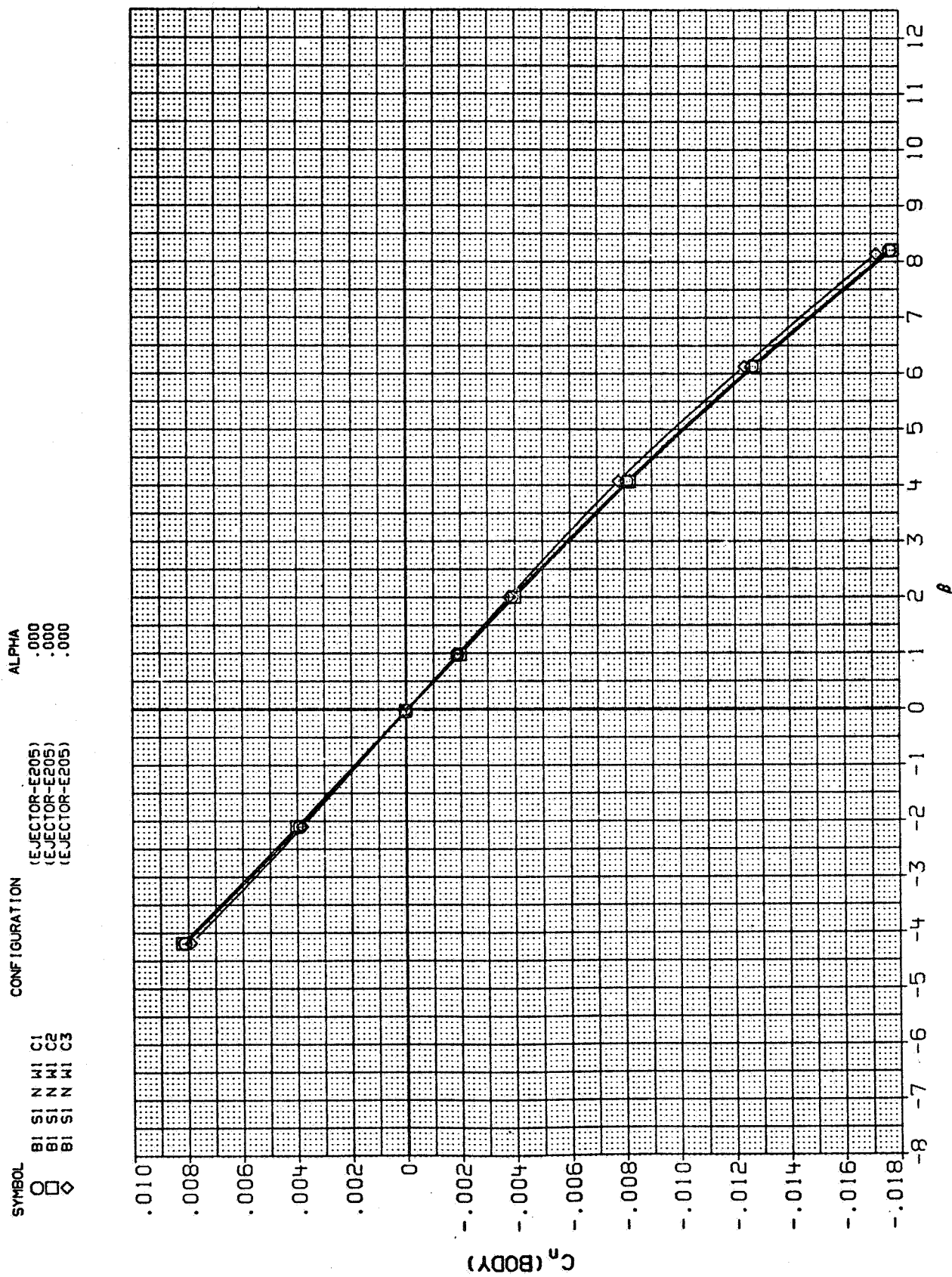


FIG. 71 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF

MACH = .90

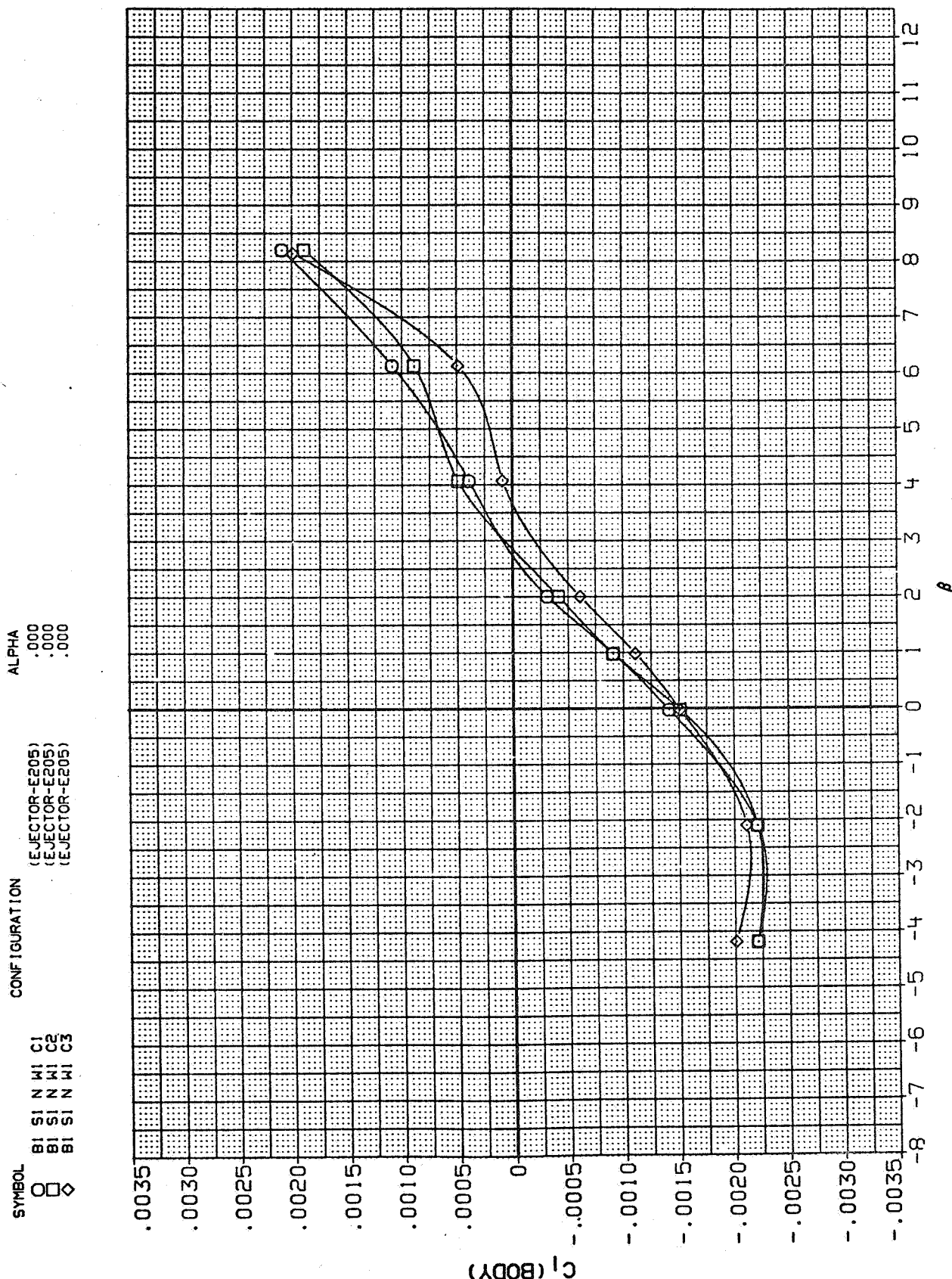


FIG. 71 CANARD LOCATION EFFECTS; LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF
 MACH = .90

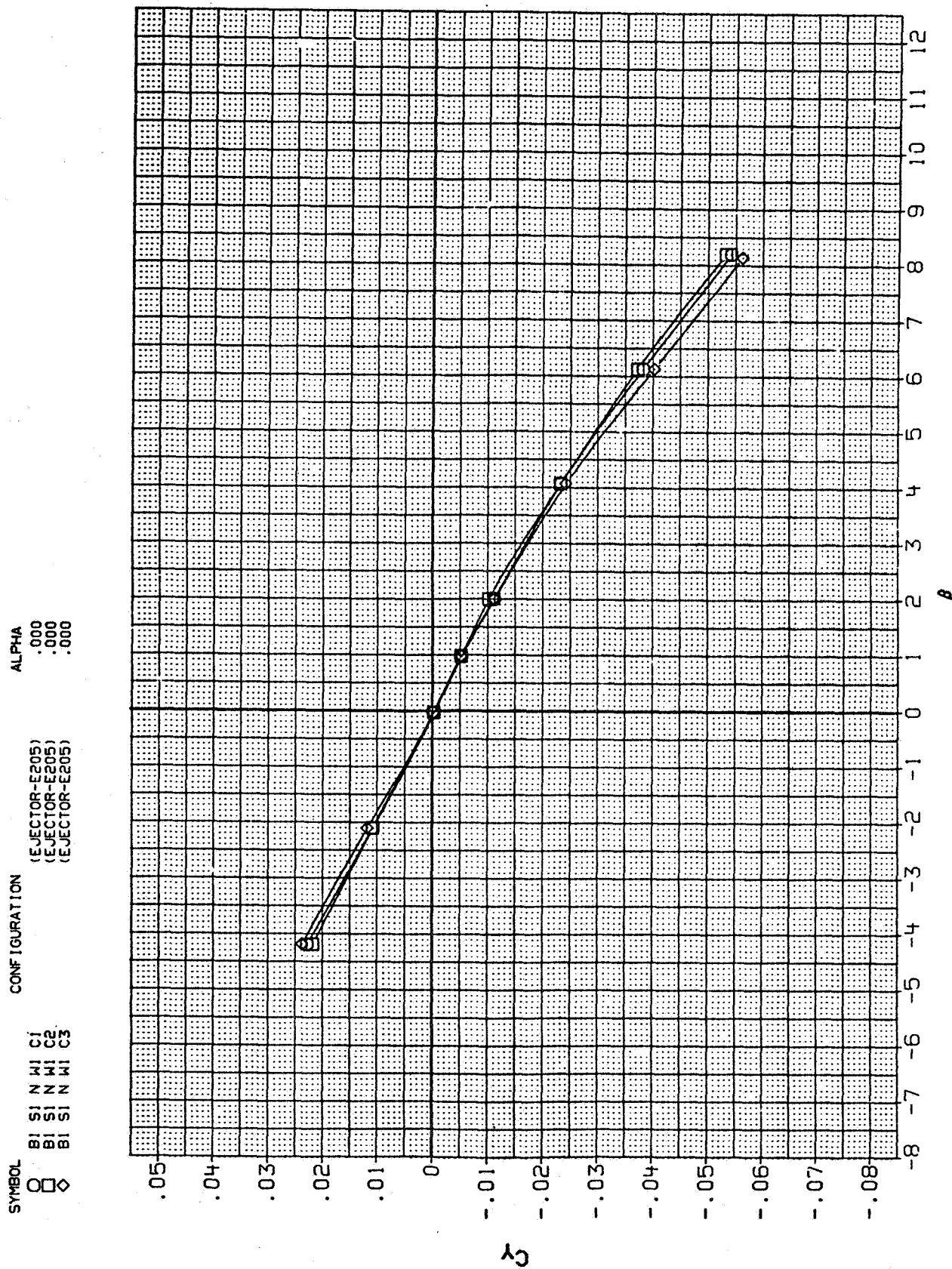


FIG. 71 CANARD LOCATION EFFECTS; LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF
 MACH = .90

SYMBOL	CONFIGURATION	ALPHA
□	(EJECTOR-E205)	12.000
◇	(EJECTOR-E205)	12.000
◇	(EJECTOR-E205)	17.500

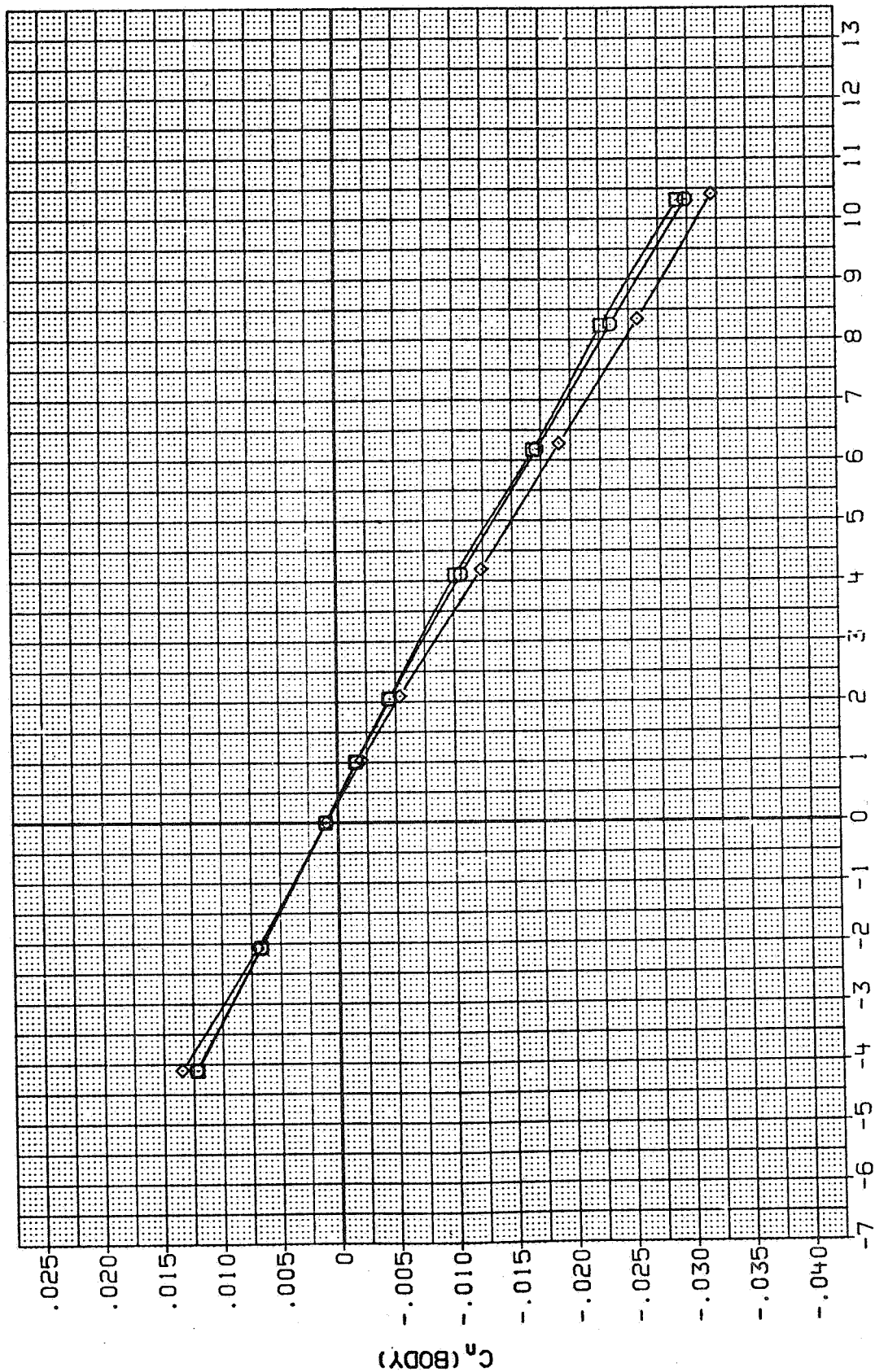


FIG. 71 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 $\alpha = 15$ DEGREES, VERTICAL TAIL OFF
 $MACH = 0.90$

SYMBOL CONFIGURATION ALPHA
 □ (EJECTOR-E205) 12.000
 ◇ (EJECTOR-E205) 12.000
 (EJECTOR-E205) 17.500

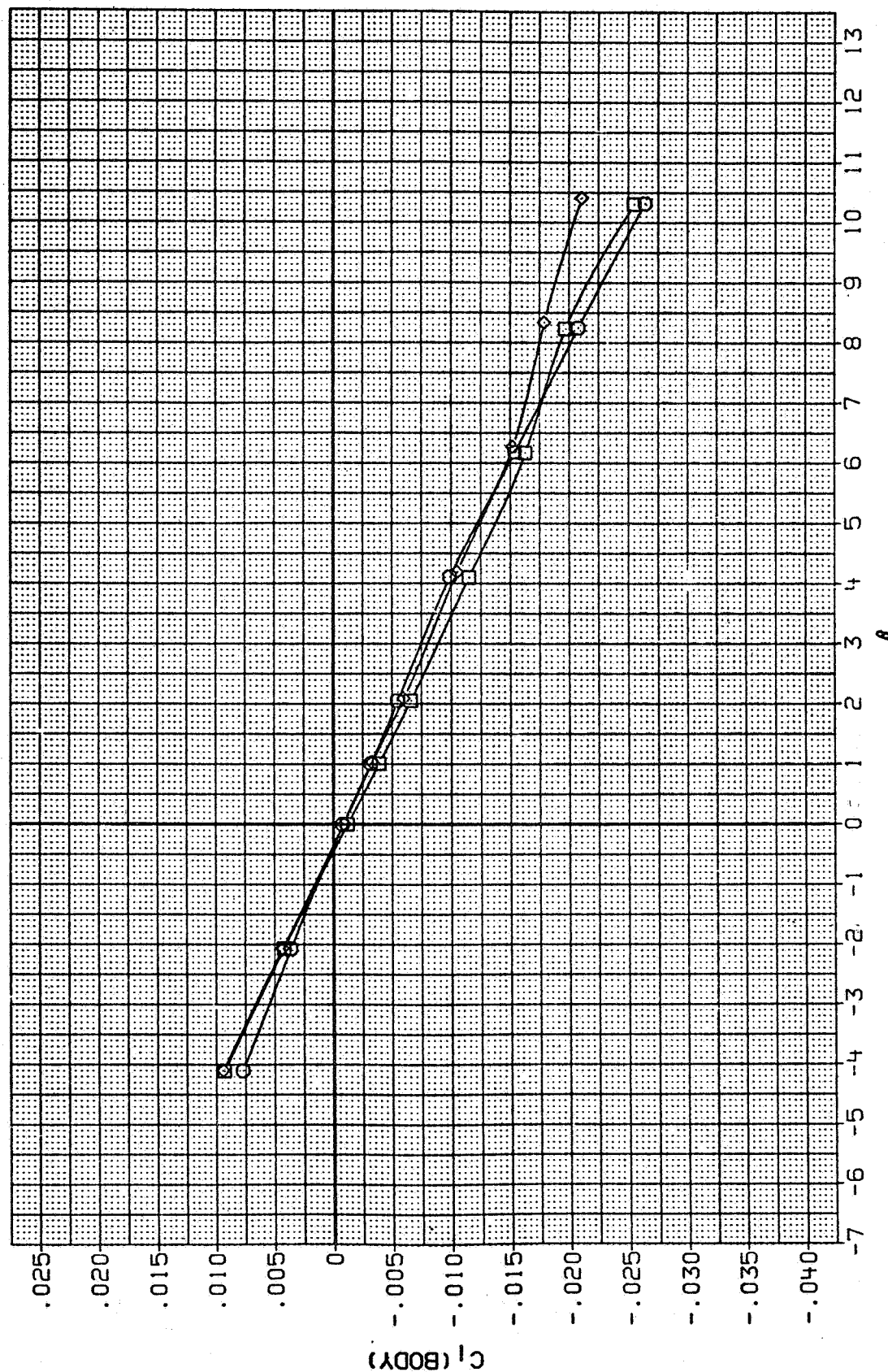


FIG. 71 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL OFF
 MACH = .90

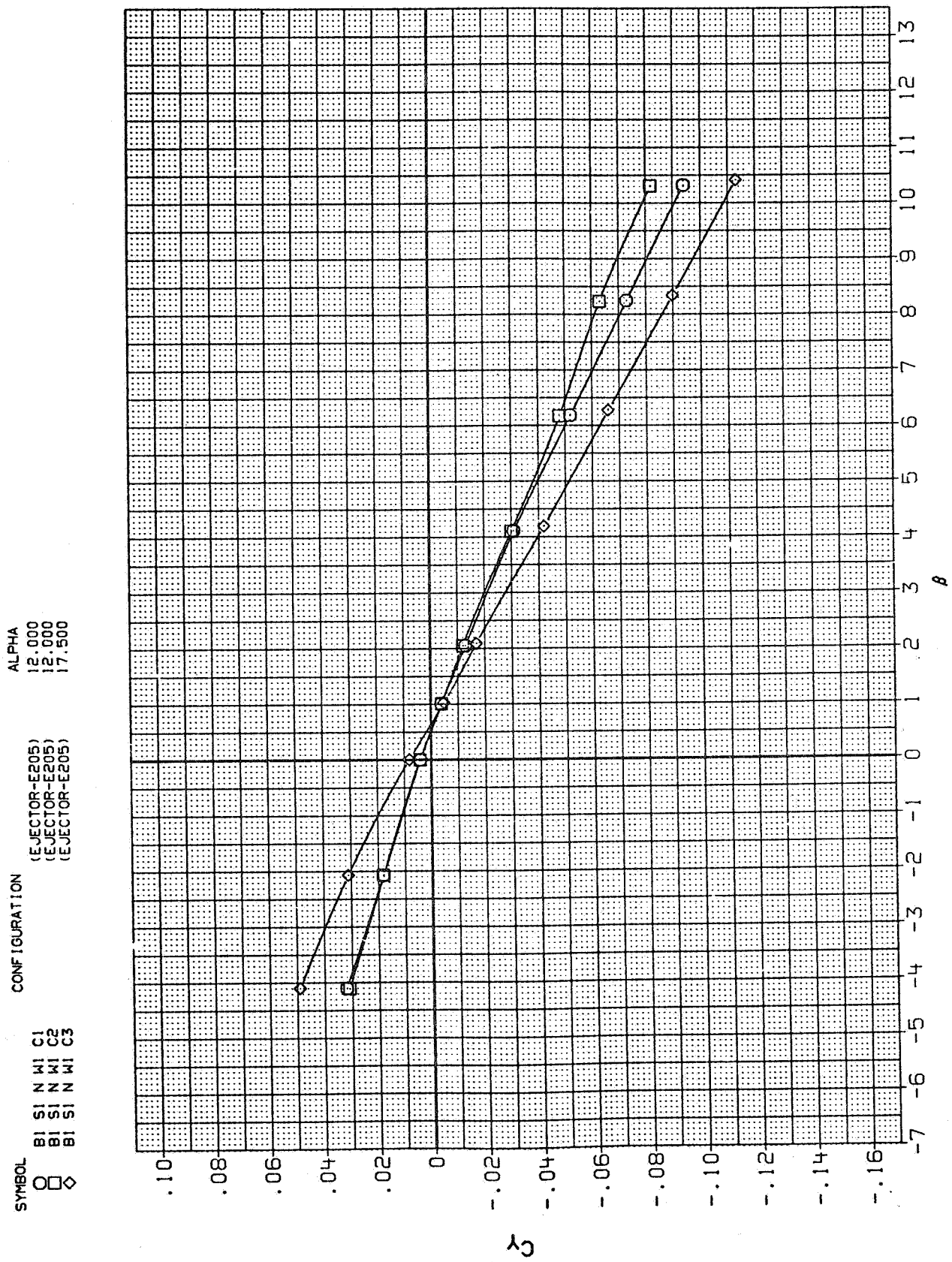


FIG. 71 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL OFF
 MACH = .90

SYMBOL CONFIGURATION ALPHA
 ○ (EJECTOR-E205) .000
 □ (EJECTOR-E205) .000
 ◇ (EJECTOR-E205) .000

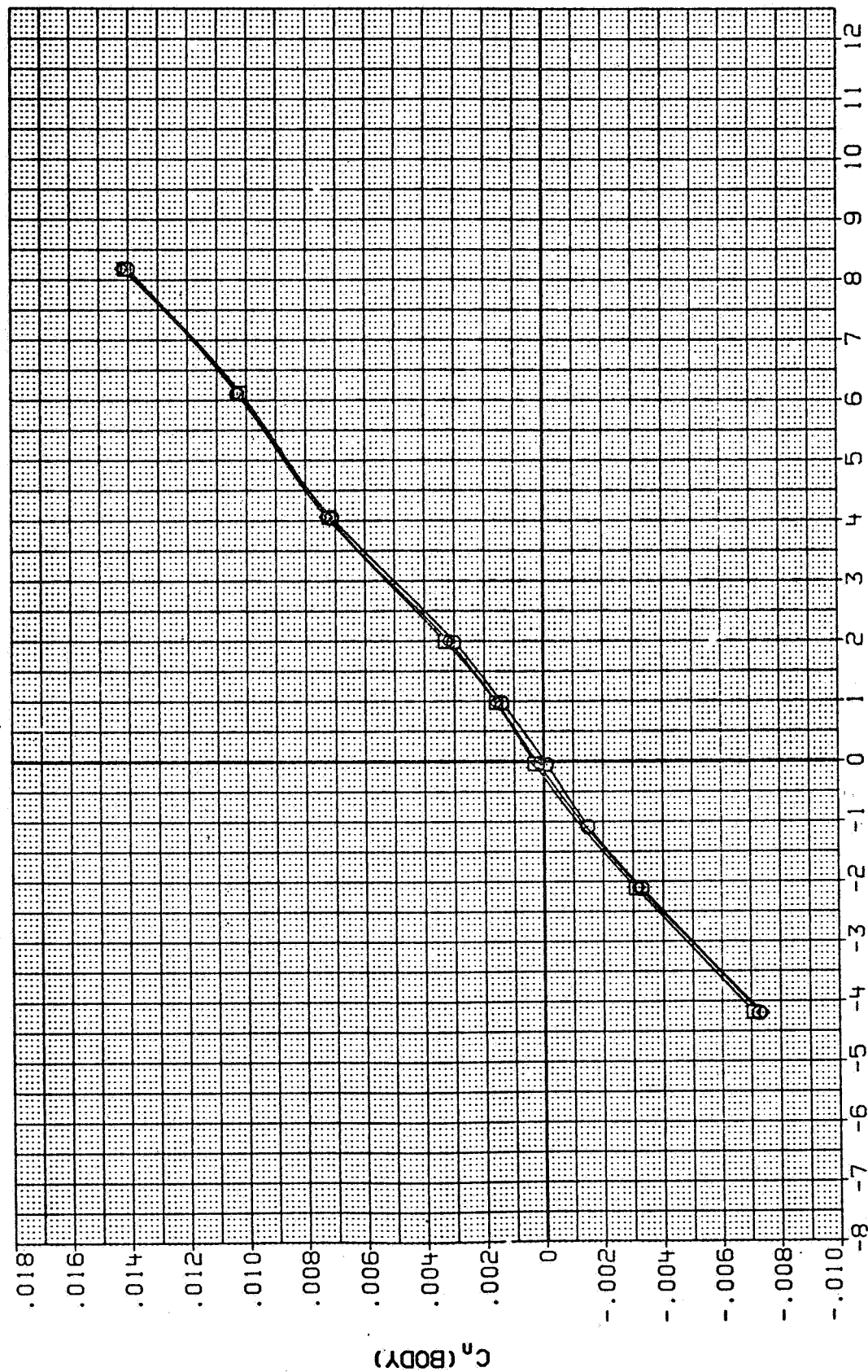


FIG. 72 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

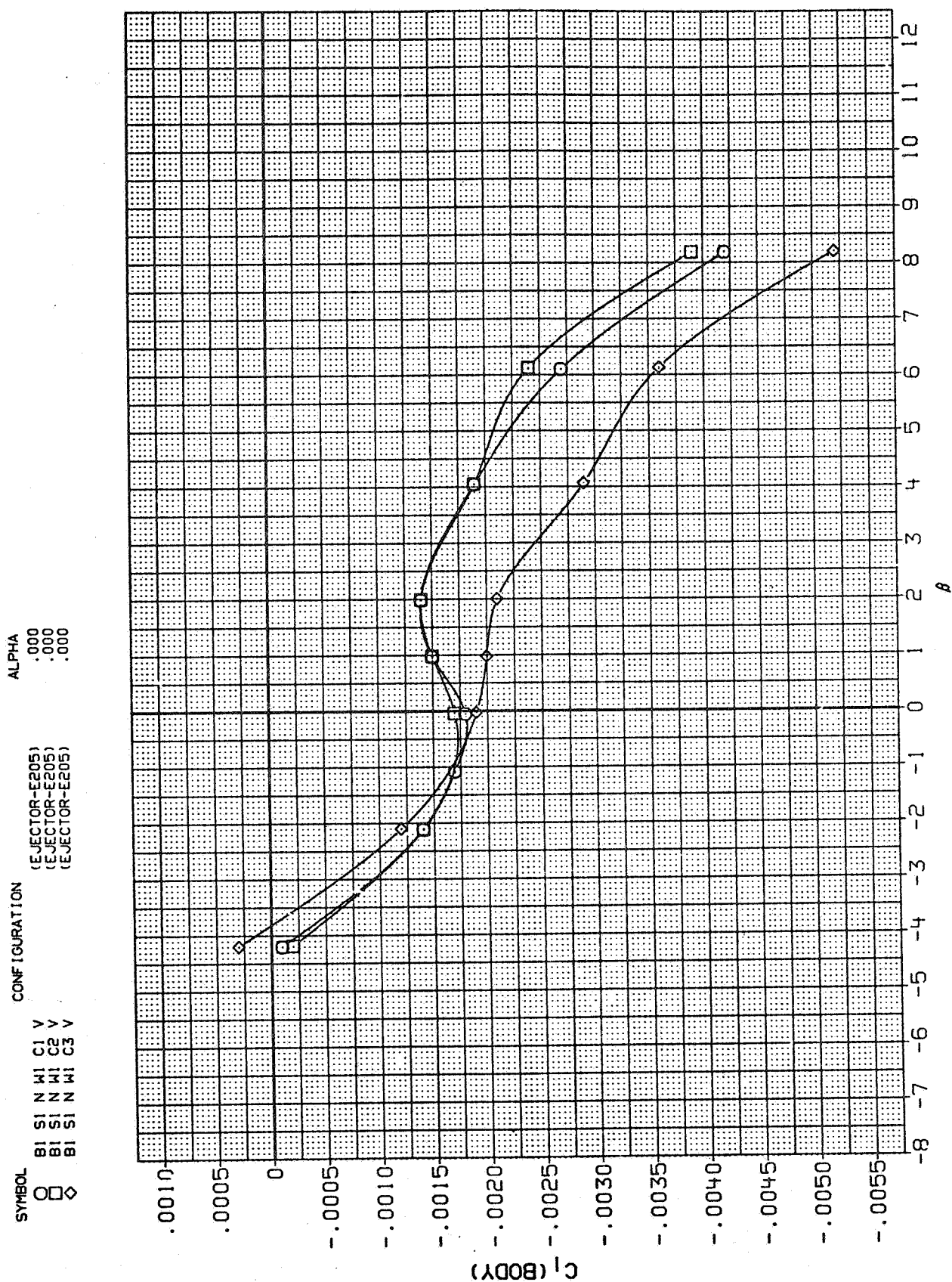


FIG. 72 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

SYMBOL CONFIGURATION ALPHA

○ (EJECTOR-E205) .000

◇ (EJECTOR-E205) .000

◇ (EJECTOR-E205) .000

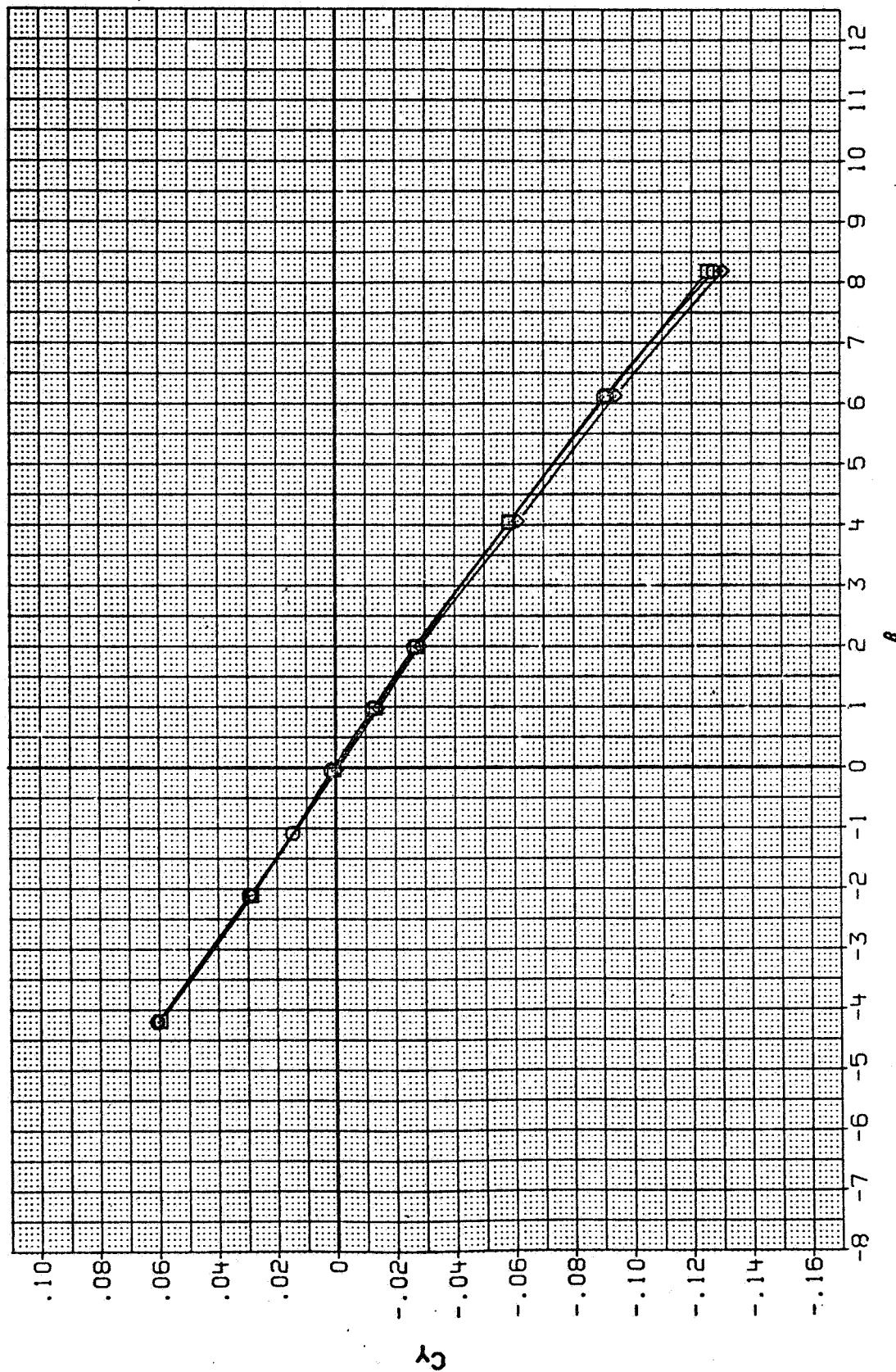


FIG. 72 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

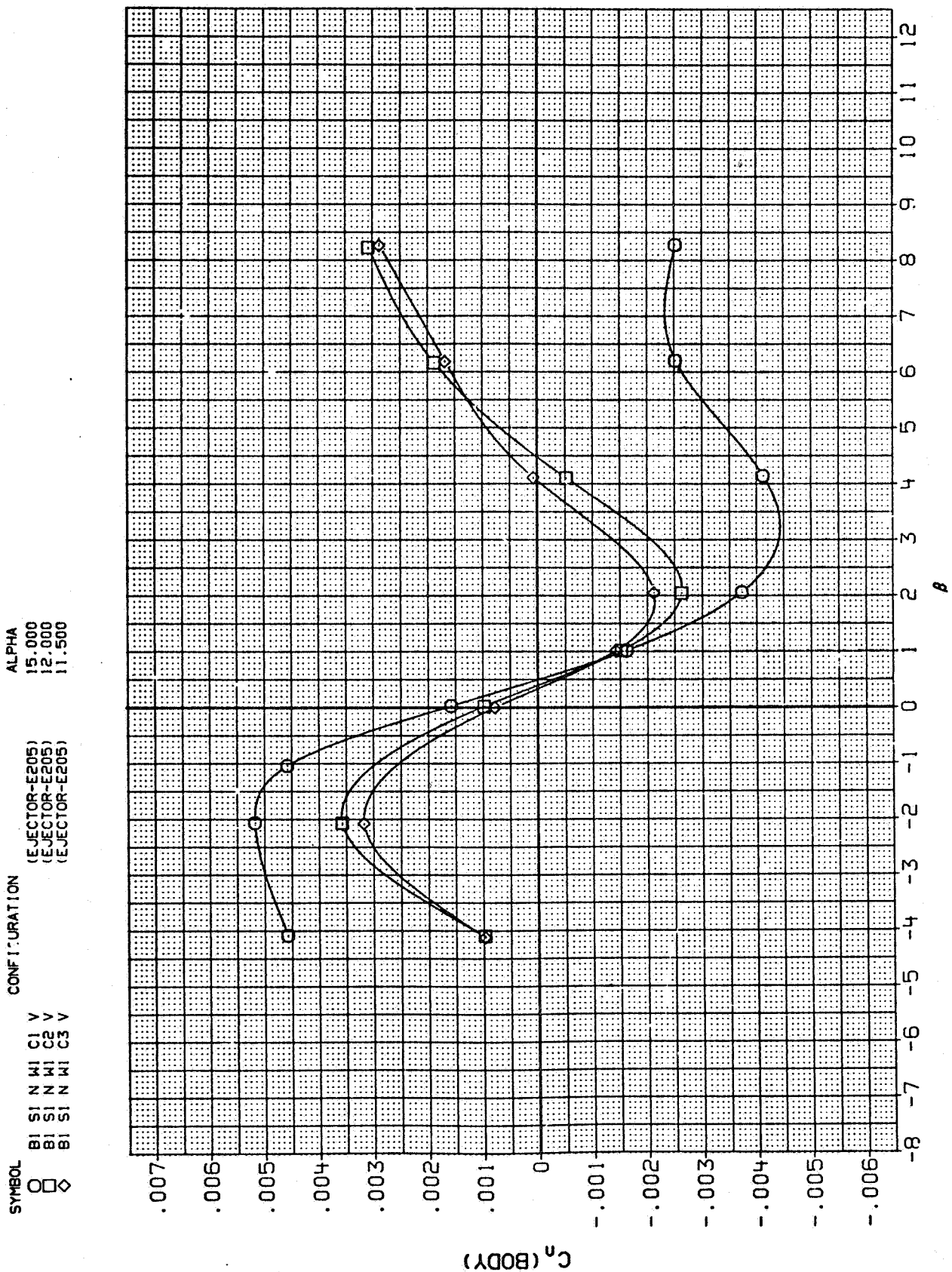


FIG. 72 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
○	(EJECTOR-E205)	15.000
□	(EJECTOR-E205)	12.000
◇	(EJECTOR-E205)	11.500

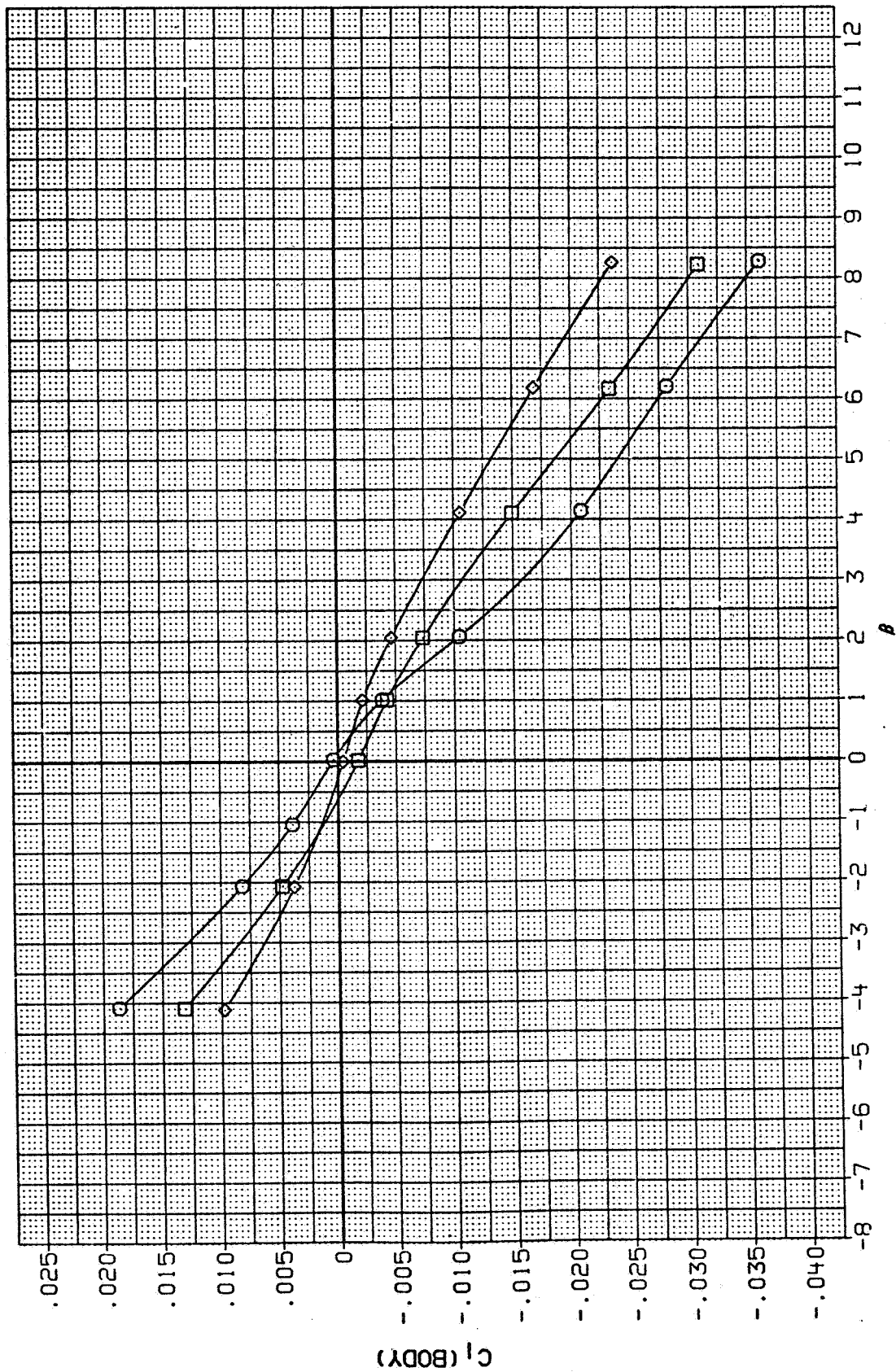


FIG. 72 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 $\alpha = 10$ DEGREES, VERTICAL TAIL ON
 $MACH = 1.20$

SYMBOL	CONFIGURATION	ALPHA
BI SI N WI C1 V	(EJECTOR-E205)	15.000
BI SI N WI C2 V	(EJECTOR-E205)	12.000
BI SI N WI C3 V	(EJECTOR-E205)	11.500

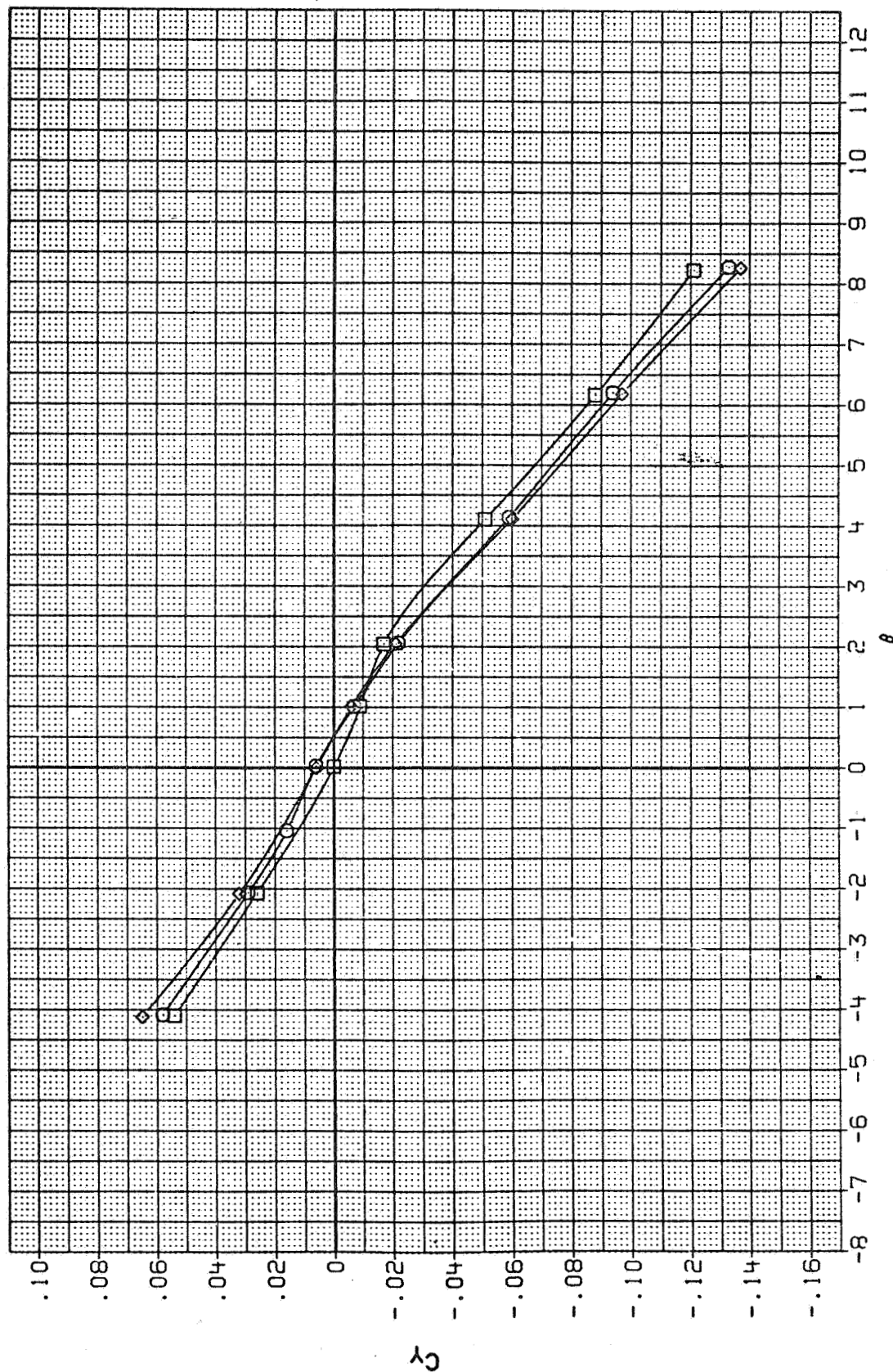


FIG. 72 CANARD LOCATION EFFECTS; LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
□	(EJECTOR-E205)	.000
○	(EJECTOR-E205)	.000
◇	(EJECTOR-E205)	.000

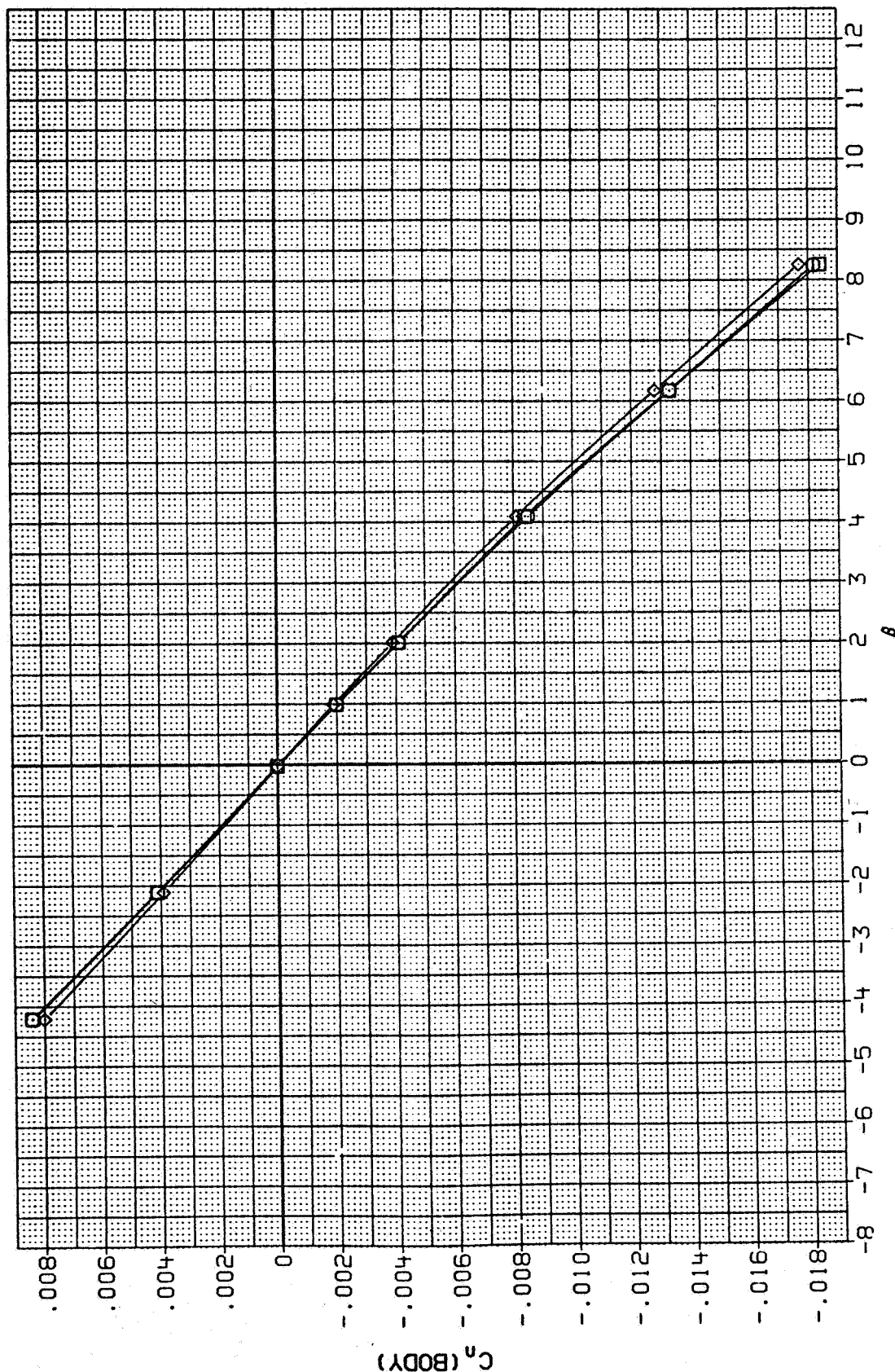


FIG. 73 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 $ALPHA = 0$ DEGREES, VERTICAL TAIL OFF
 $MACH = 1.20$

SYMBOL CONFIGURATION ALPHA
 BI SI N WI C1 (EJECTOR-E205) .000
 BI SI N WI C2 (EJECTOR-E205) .000
 BI SI N WI C3 (EJECTOR-E205) .000

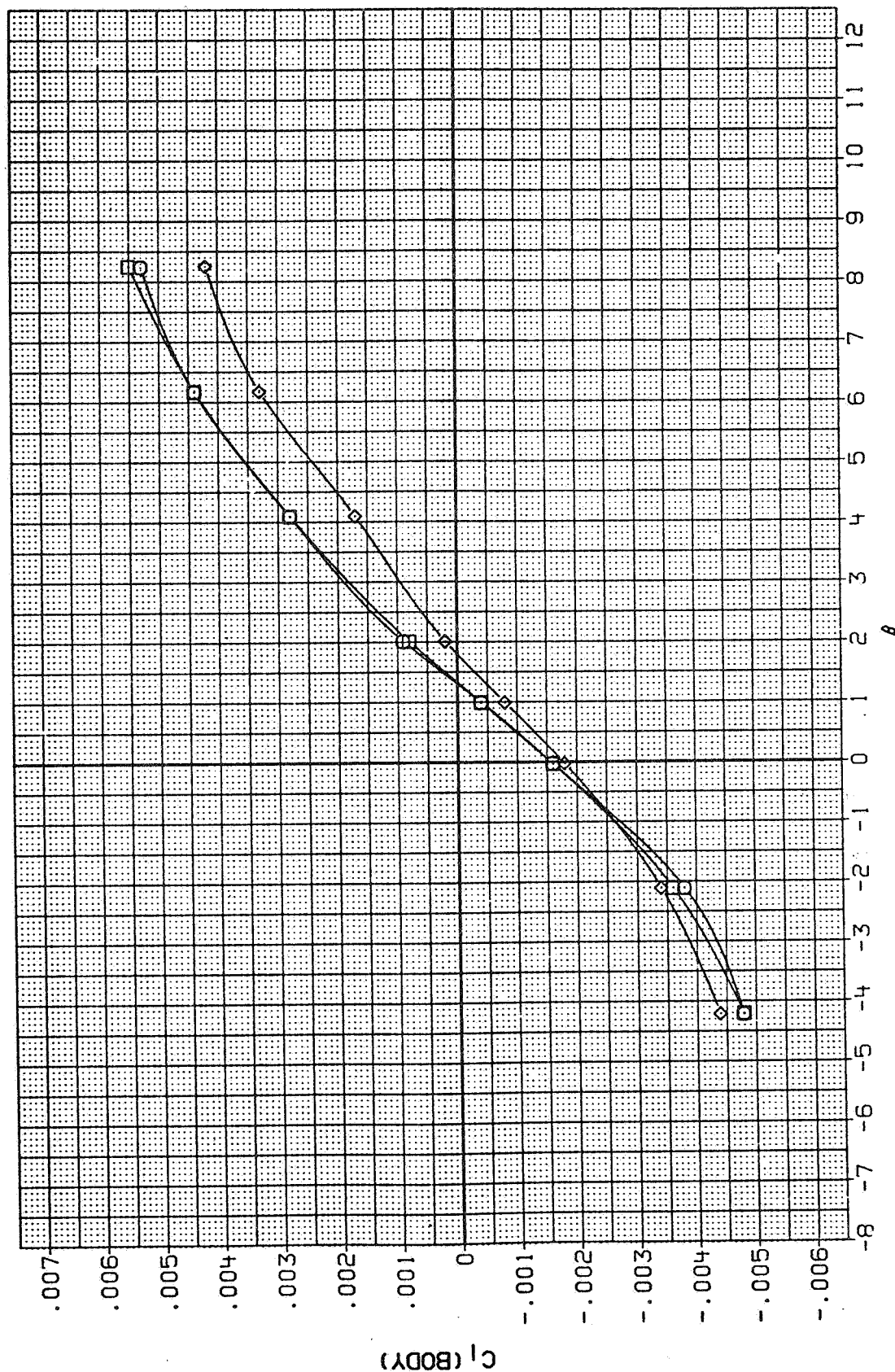


FIG. 73 CANARD LOCATION EFFECTS; LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF
 MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
○	(EJECTOR-E205)	.000
□	(EJECTOR-E205)	.000
◇	(EJECTOR-E205)	.000

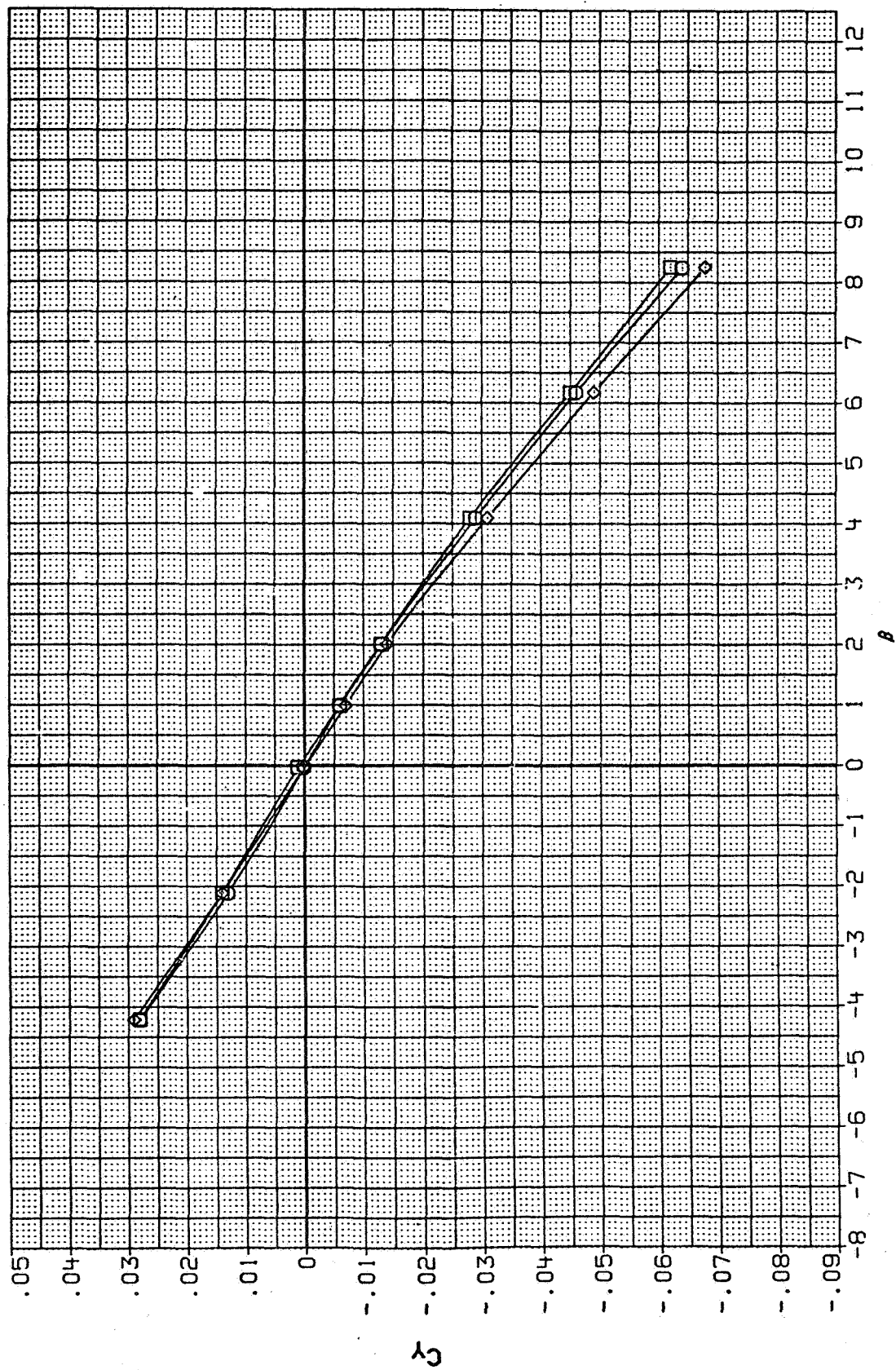


FIG. 73 CANARD LOCATION EFFECTS; LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF
 MACH = 1.20

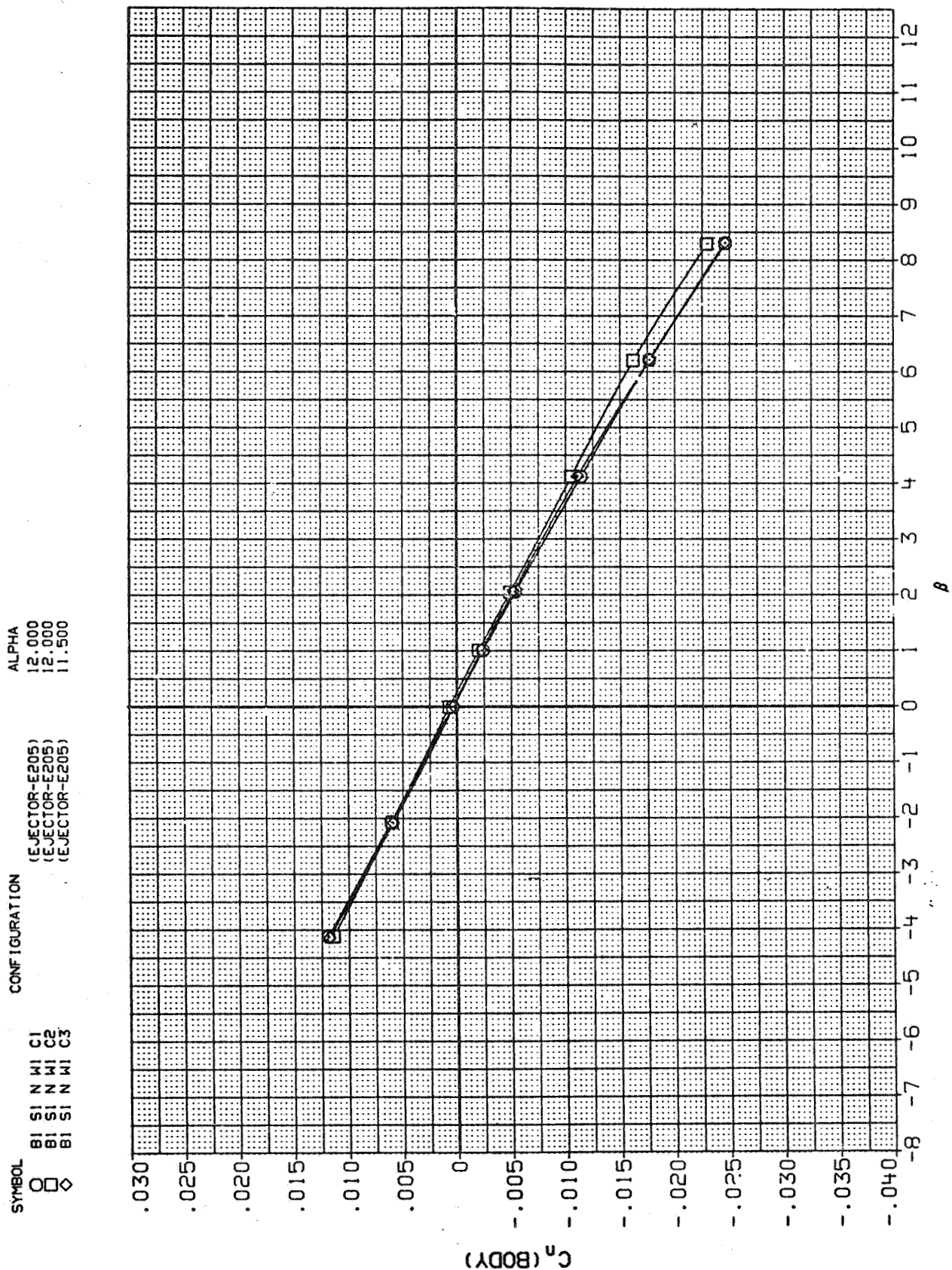


FIG. 73 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL OFF
 MACH = 1.20

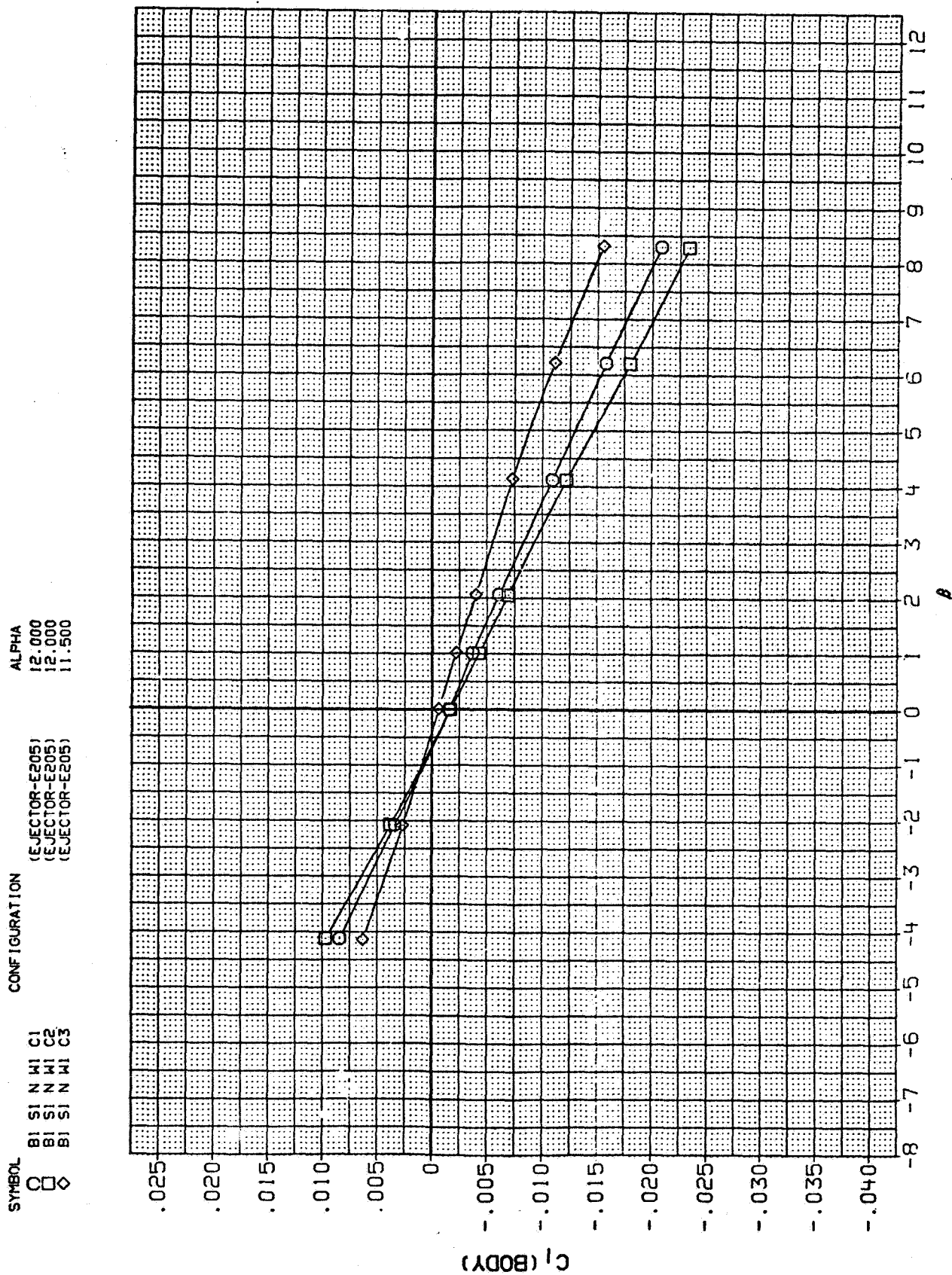


FIG. 73 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL OFF
 MACH = 1.20

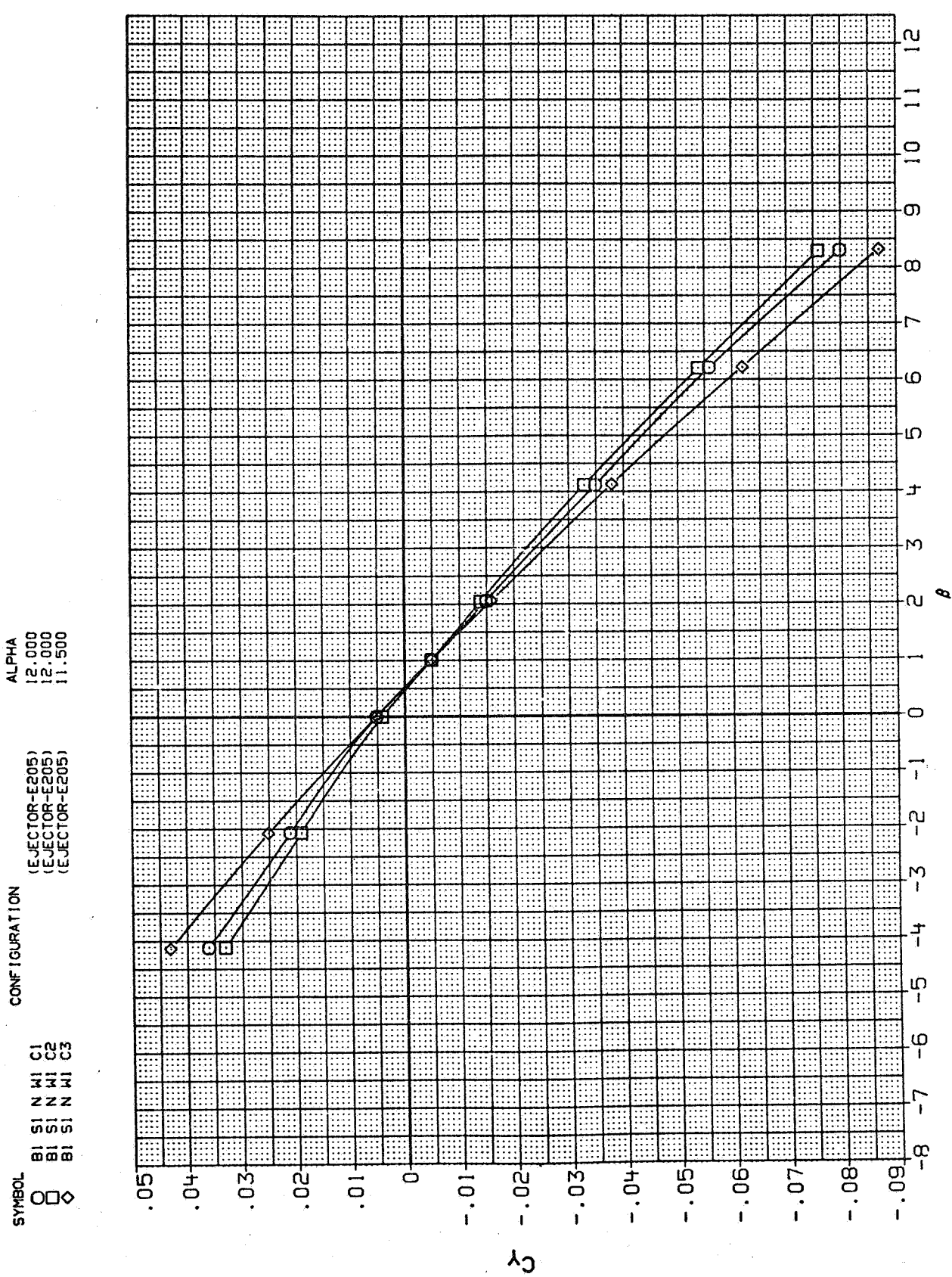


FIG. 73 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 10 DEGREES, VERTICAL TAIL OFF
MACH = 1.20

SYMBOL	CONFIGURATION	CANARD
○	(EJECTOR-E205)	.000
□	(EJECTOR-E205)	.000
◇	(EJECTOR-E205)	.000

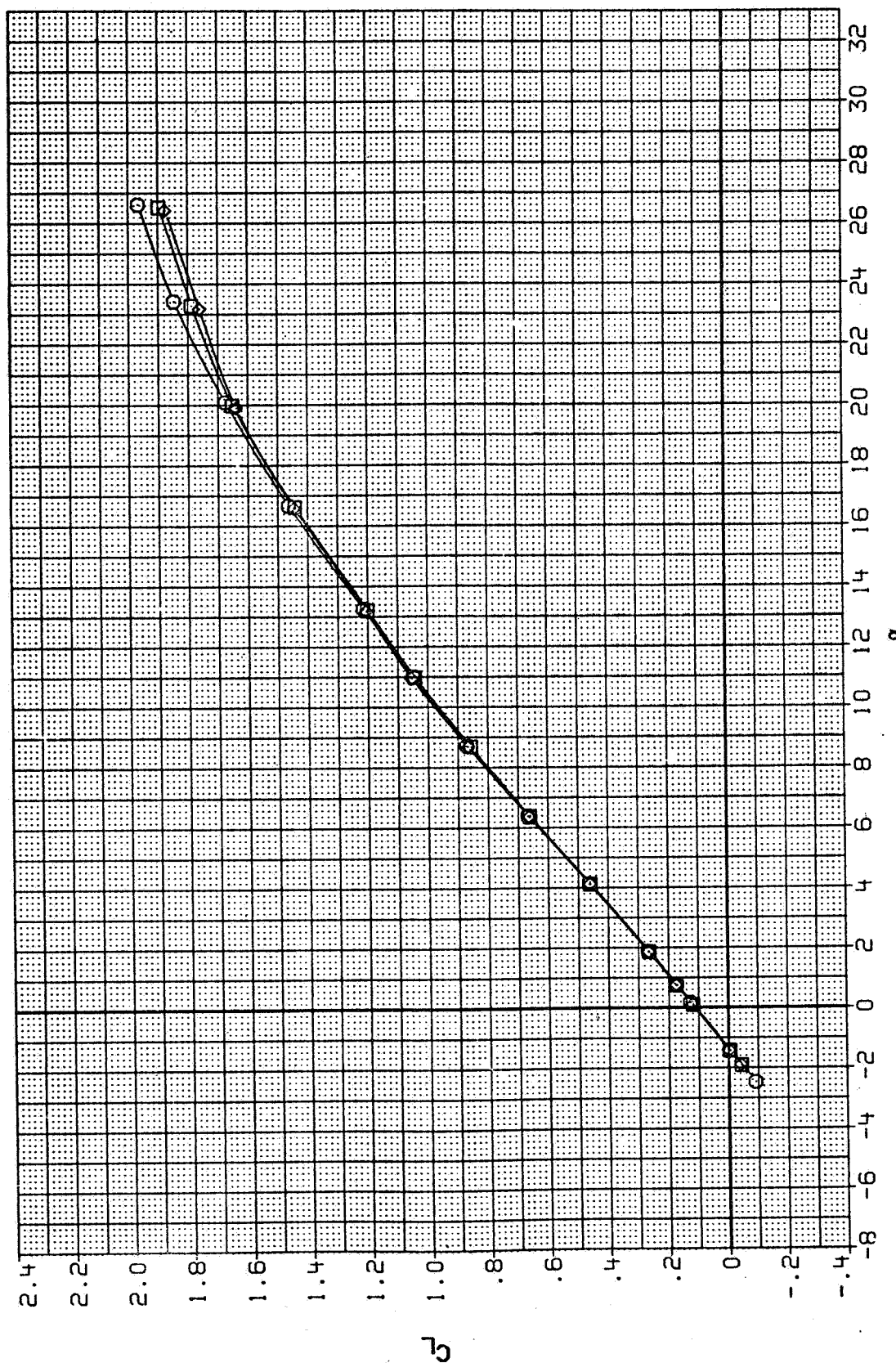


FIG. 74 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = .60

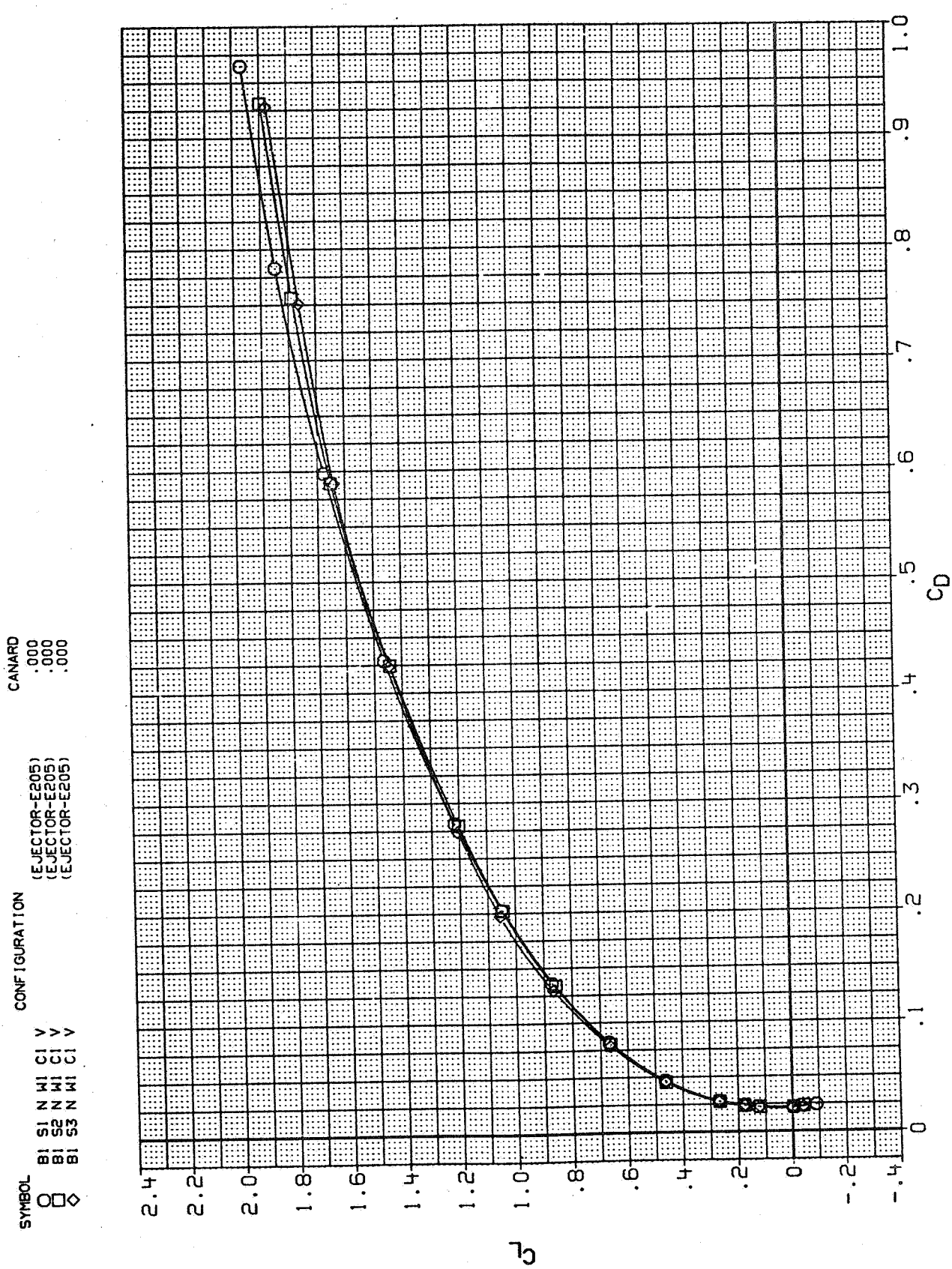


FIG. 74 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL	CONFIGURATION	CANARD
□	B1 S1 N W1 C1 V	.000
○	B1 S2 N W1 C1 V	.000
◇	B1 S3 N W1 C1 V	.000

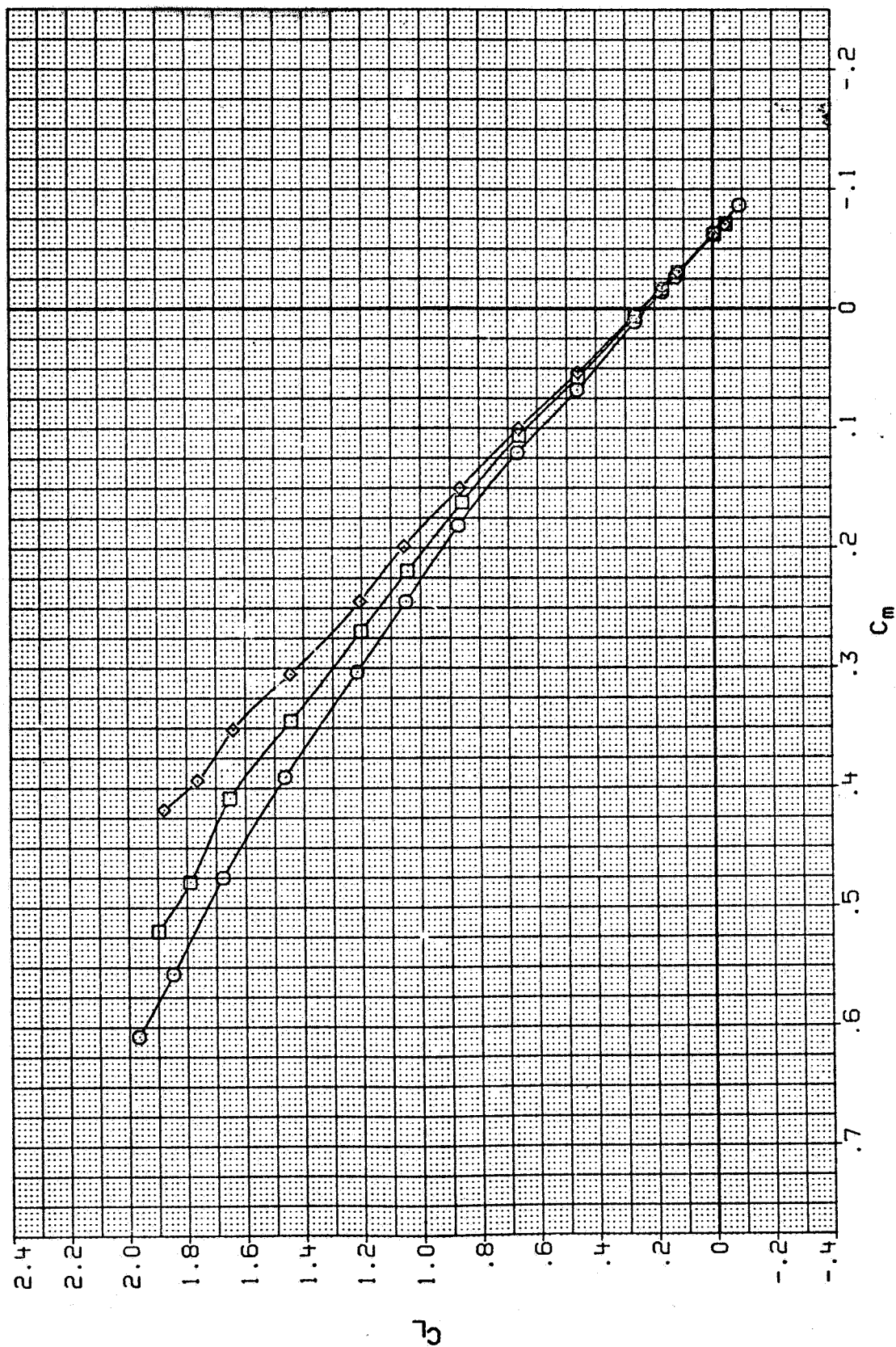


FIG. 74 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL	CONFIGURATION	CANARD
□	(EJECTOR-E205)	.000
◇	(EJECTOR-E205)	.000
	(EJECTOR-E205)	.000

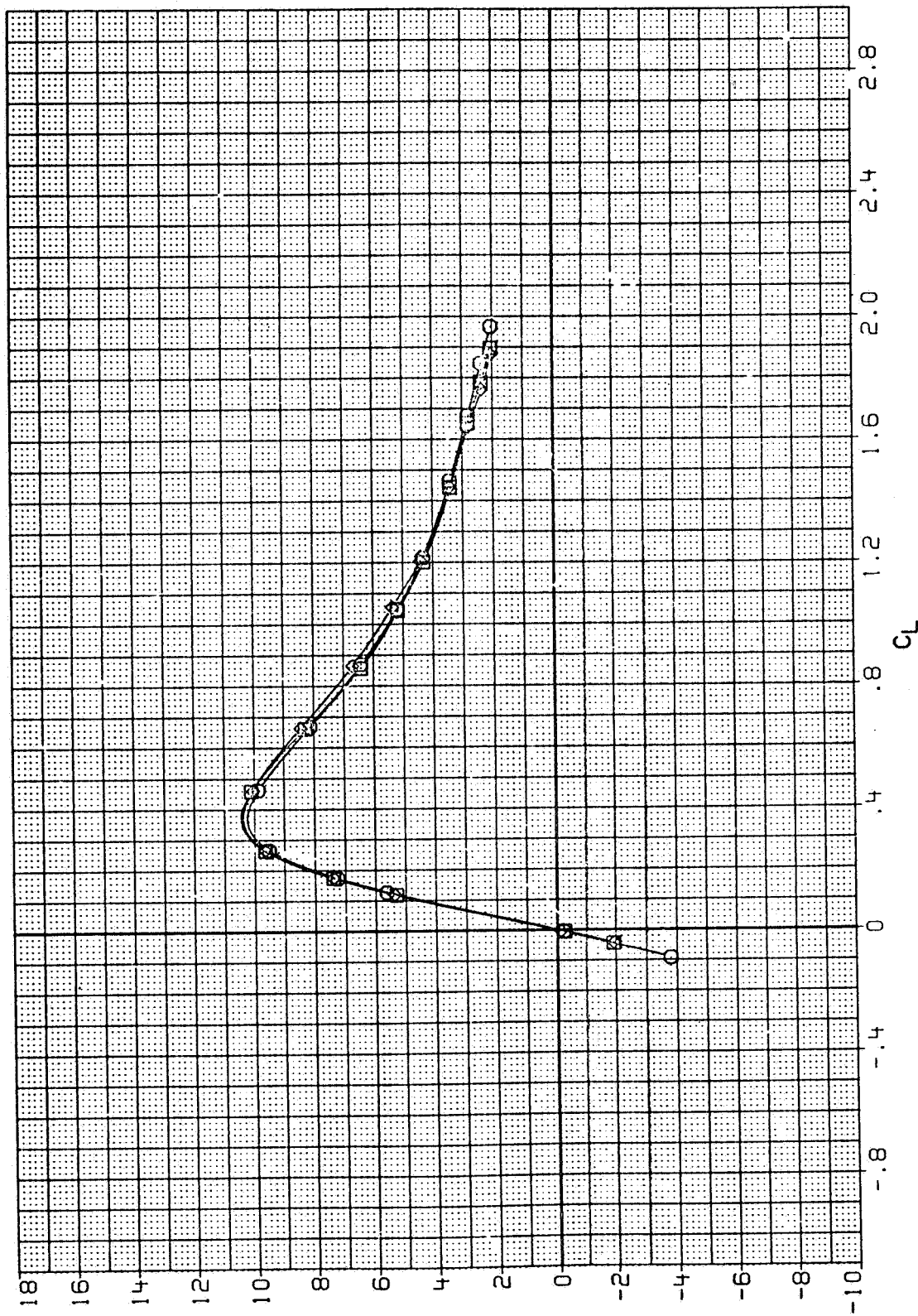


FIG. 74 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL		CONFIGURATION		CANARD	
○	BI S1	N	WI CI V		.000
□	BI S2	N	WI CI V	(EJECTOR-E205)	.000
◇	BI S3	N	WI CI V	(EJECTOR-E205)	.000

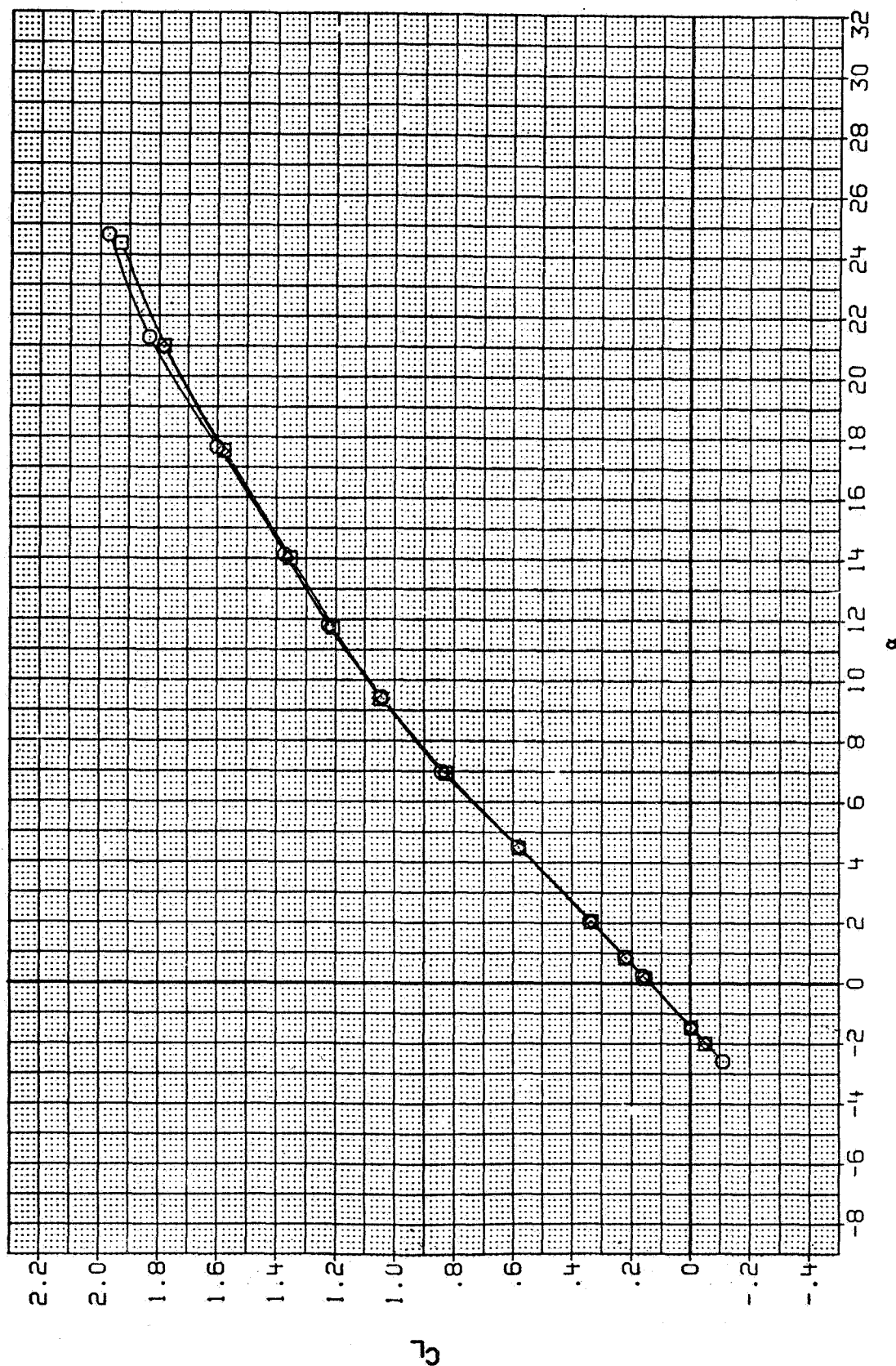


FIG. 75 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL CONFIGURATION CANARD

○ BI S1 N W1 C1 V .000
 □ BI S2 N W1 C1 V .000
 ◇ BI S3 N W1 C1 V .000

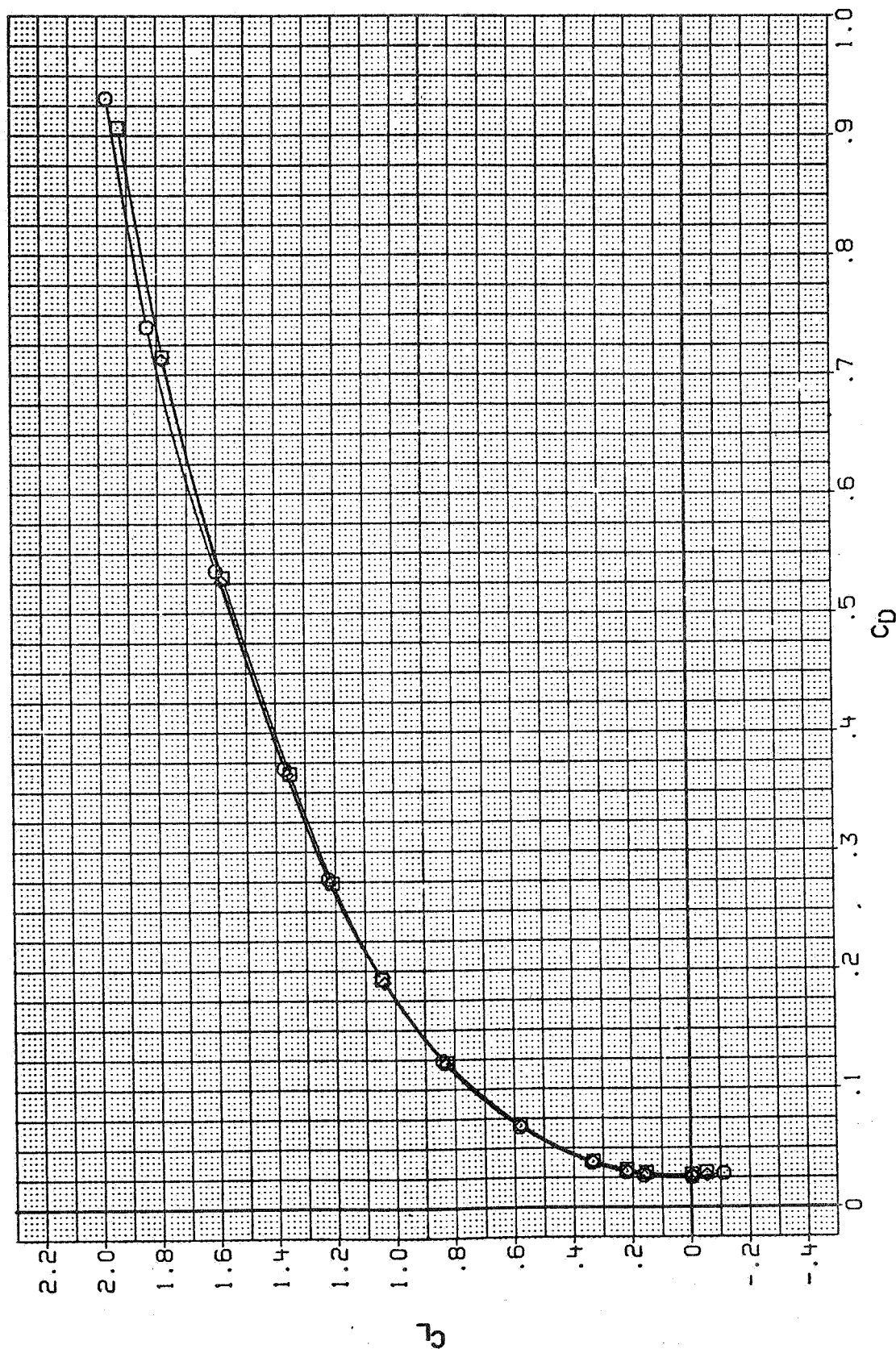


FIG. 75 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL	CONFIGURATION	CANARD
○	BI S1 N W1 C1 V	.000
□	BI S2 N W1 C1 V	.000
◇	BI S3 N W1 C1 V	.000
	(EJECTOR-E205)	
	(EJECTOR-E205)	
	(EJECTOR-E205)	

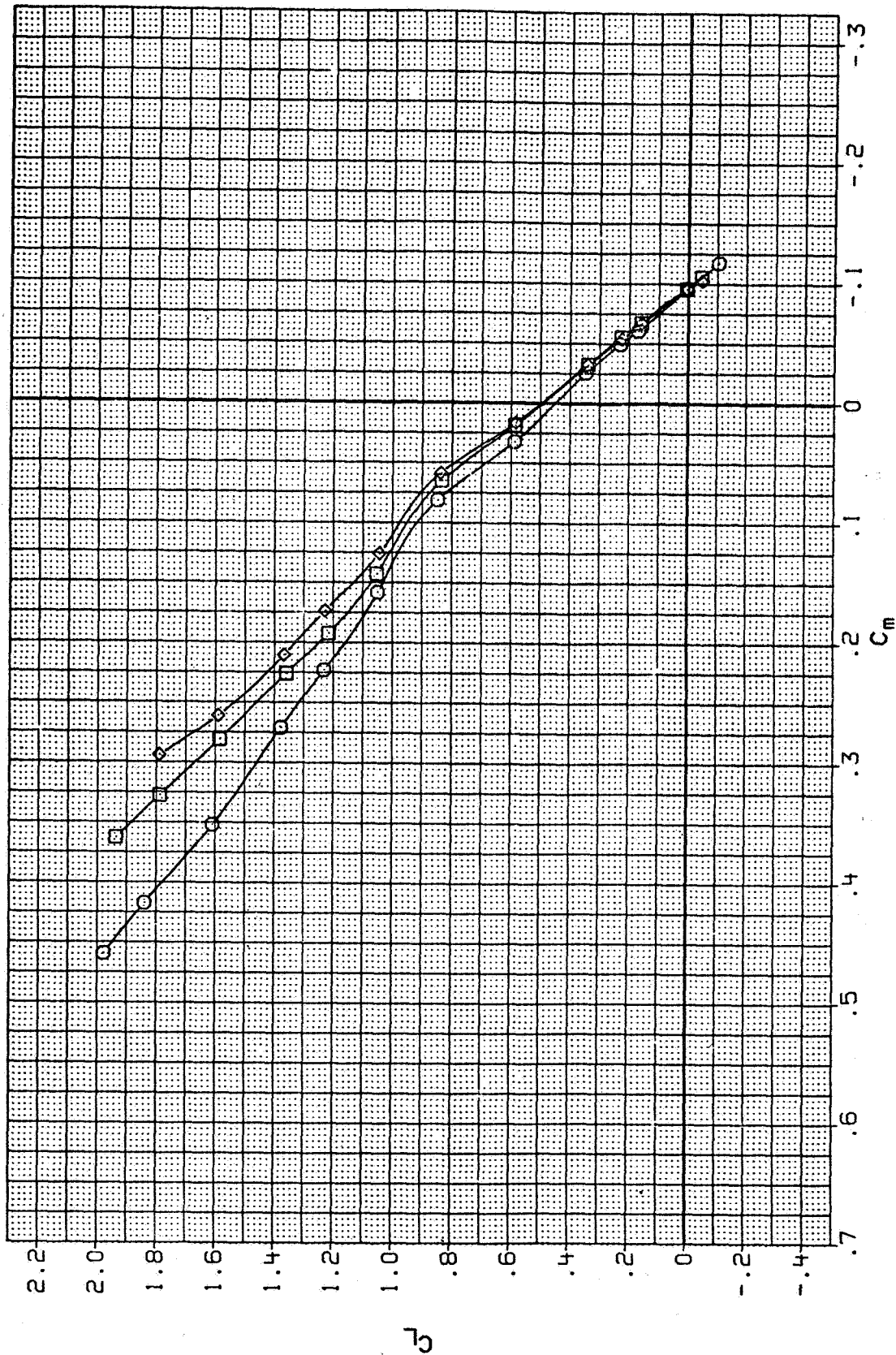


FIG. 75 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL CONFIGURATION CANARD
 ○ BI S1 N W1 C1 V .000
 □ BI S2 N W1 C1 V .000
 ◇ BI S3 N W1 C1 V .000

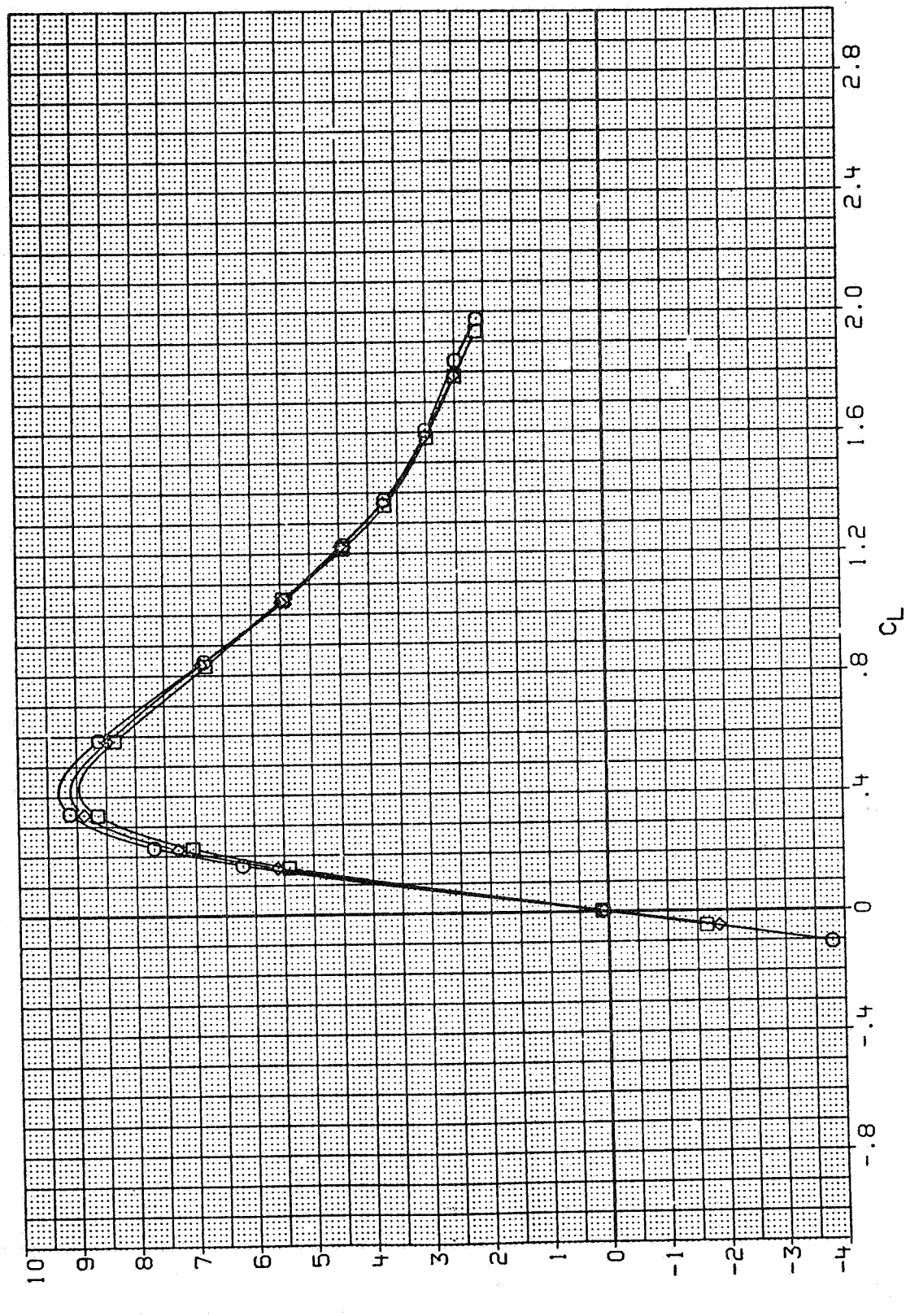


FIG. 75 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL CONFIGURATION CANARD
 ○ BI S1 N W1 C1 V .000
 □ BI S2 N W1 C1 V .000
 ◇ BI S3 N W1 C1 V .000

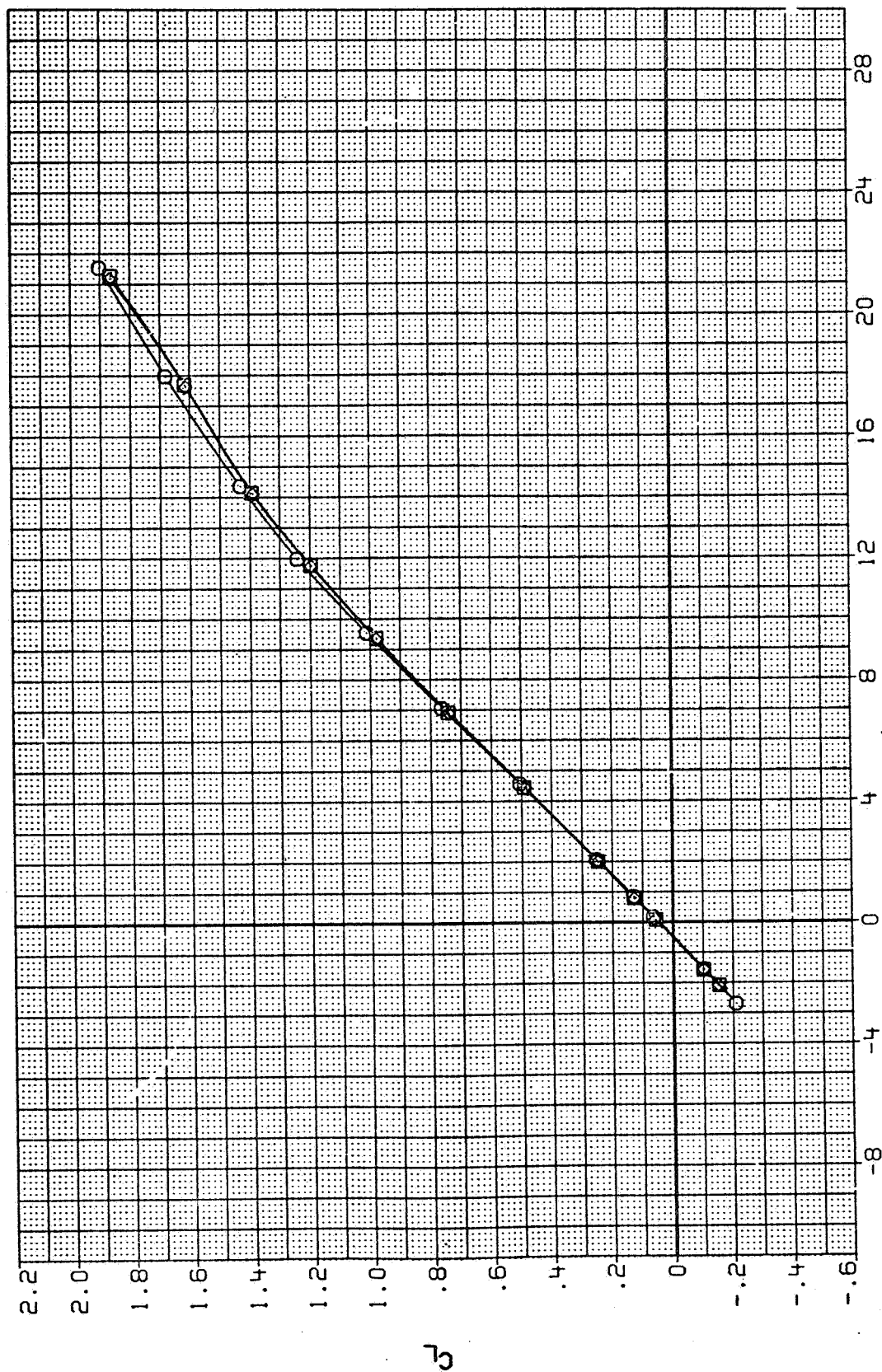


FIG. 76 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL CONFIGURATION CANARD
 ○ (EJECTOR-E205) .000
 □ (EJECTOR-E205) .000
 ◇ (EJECTOR-E205) .000

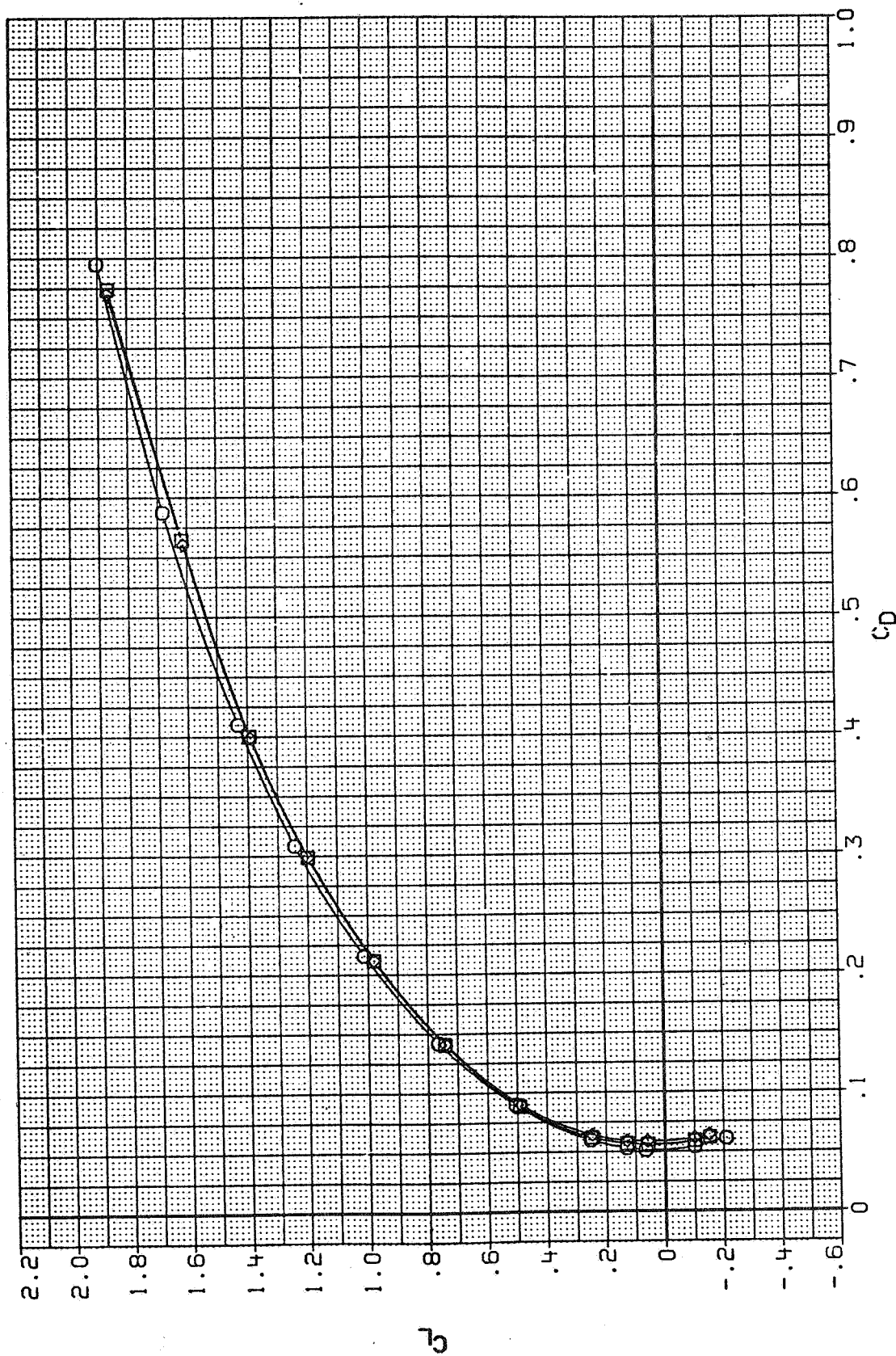


FIG. 76 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL	CONFIGURATION	CANARD
○	B1 S1 N W1 C1 V	.000
□	B1 S2 N W1 C1 V	.000
◇	B1 S3 N W1 C1 V	.000

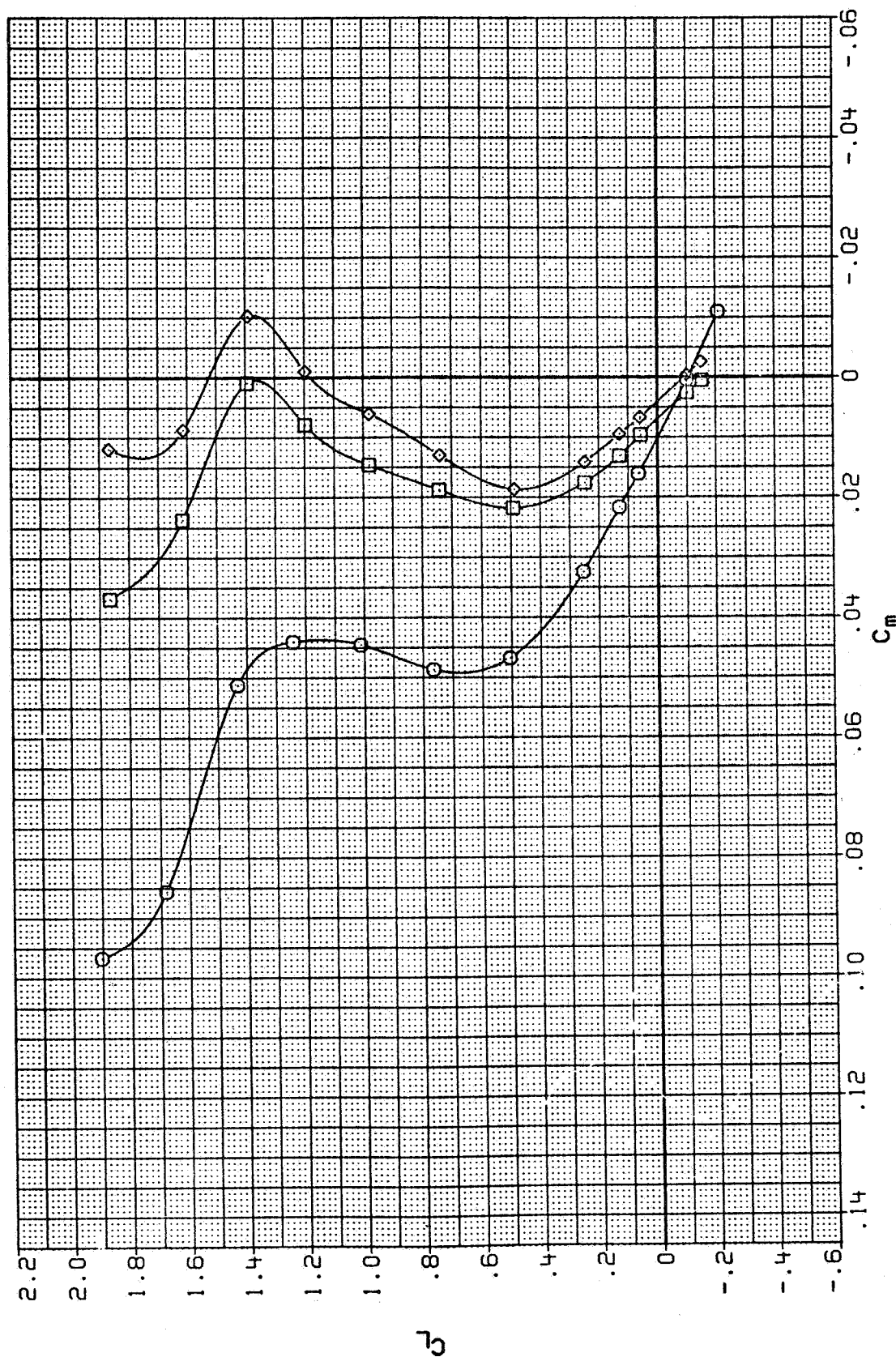


FIG. 76 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL	BI S1 N MI CI V BI S2 N MI CI V BI S3 N MI CI V	CONFIGURATION	(EJECTOR-E205) (EJECTOR-E205) (EJECTOR-E205)	CANARD	.000 .000 .000

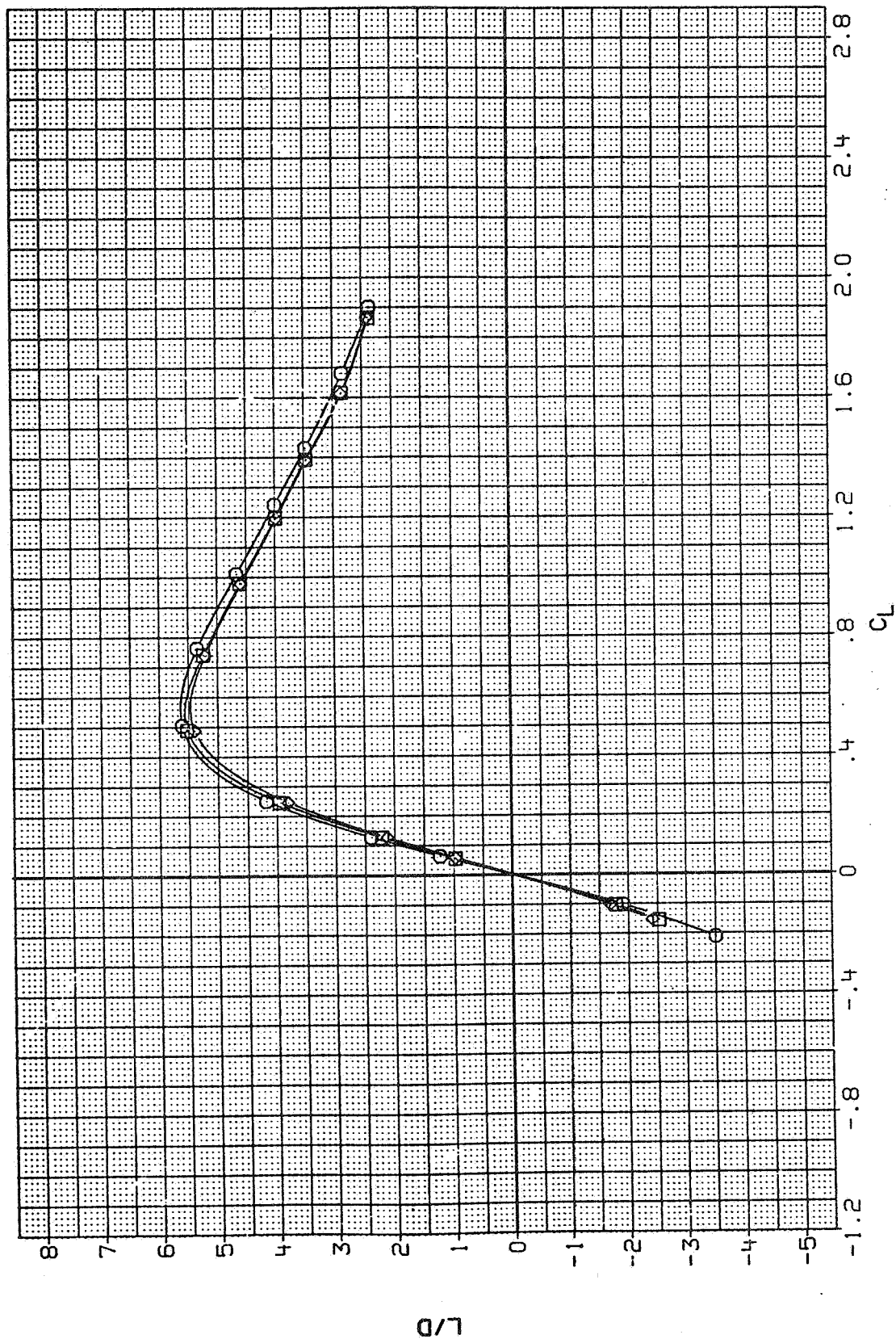


FIG. 76 STRAKE VARIATIONS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

L/D

325

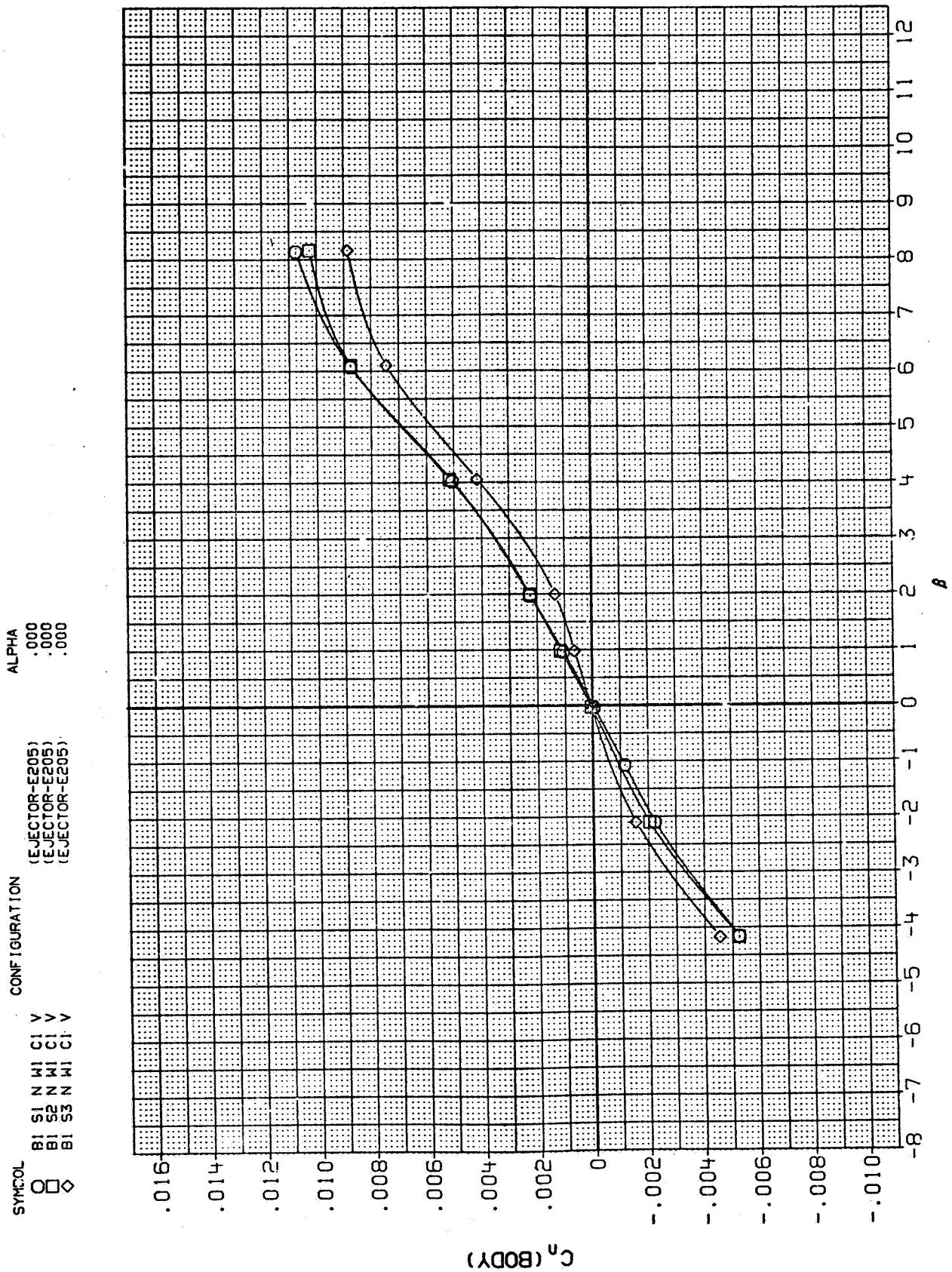


FIG. 77 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = .90

SYMBOL CONFIGURATION ALPHA
 ○ (EJECTOR-E205) .000
 □ (EJECTOR-E205) .000
 ◇ (EJECTOR-E205) .000

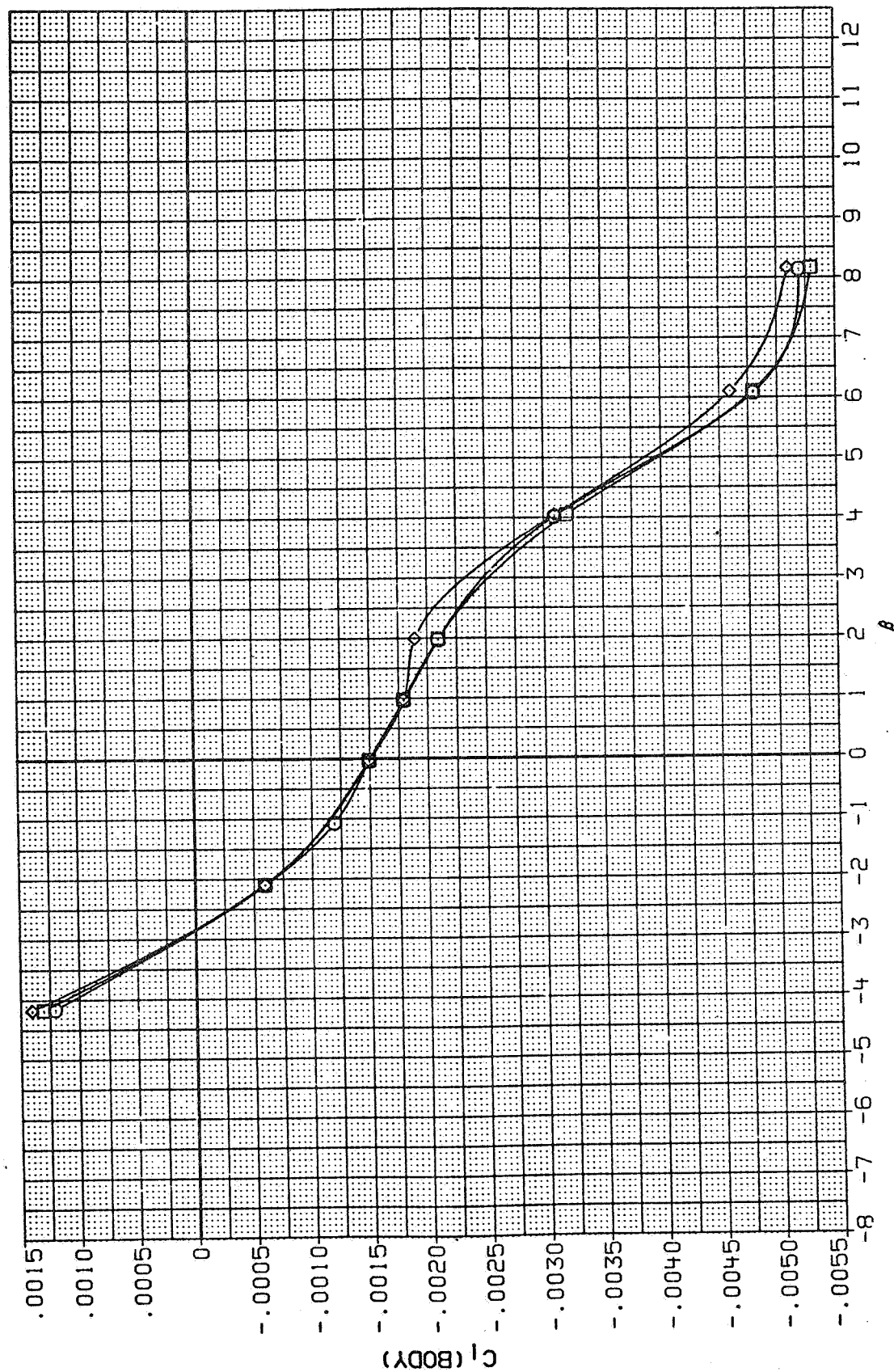


FIG. 77 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES; VERTICAL TAIL ON
 MACH = .90

SYMBOL	CONFIGURATION	ALPHA
○	B1 S1 N W1 C1 V	.000
□	B1 S2 N W1 C1 V	.000
◇	B1 S3 N W1 C1 V	.000

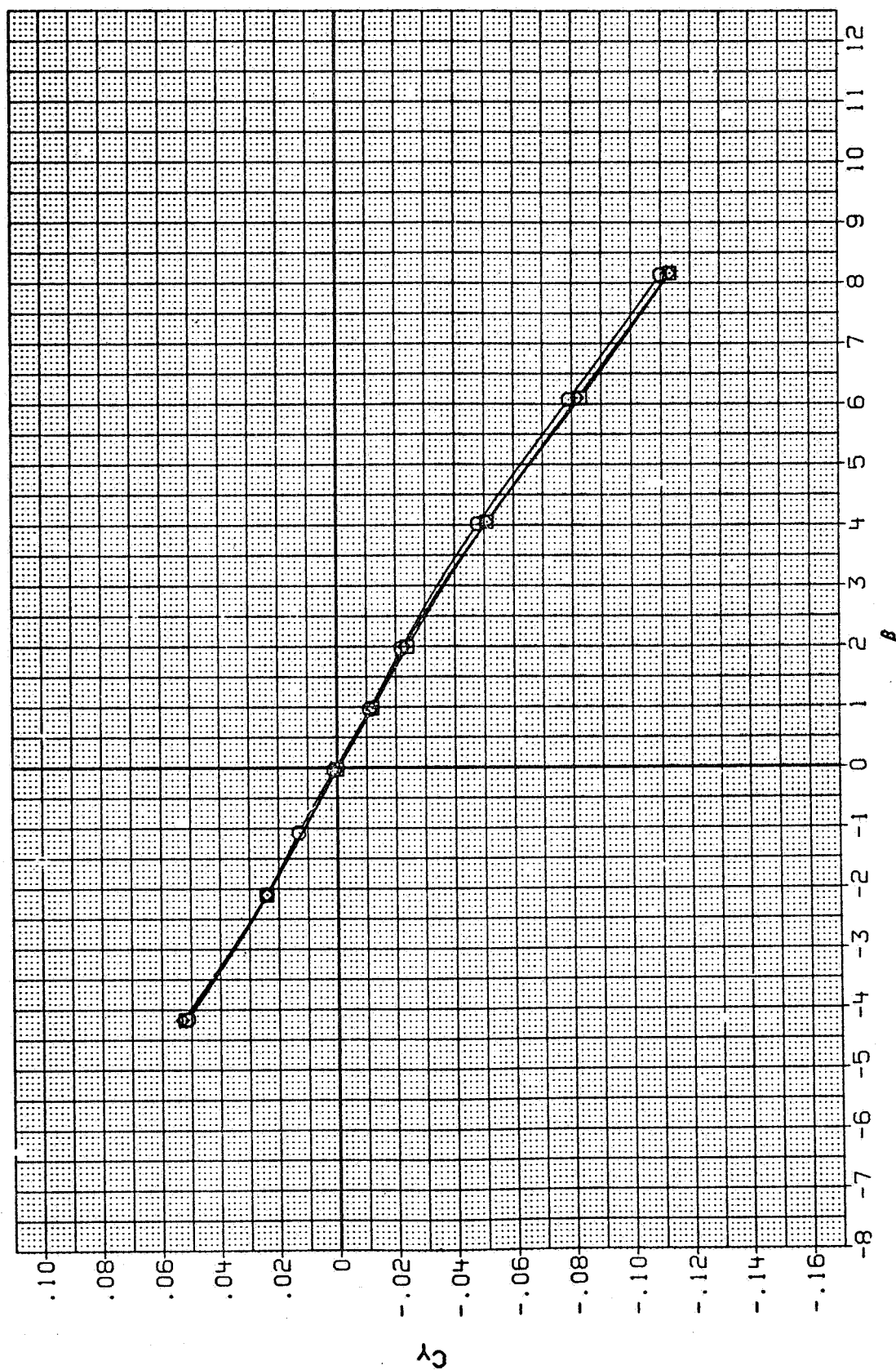


FIG. 77 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = .90

SYMBOL	CONFIGURATION	ALPHA
□	(EJECTOR-E205)	17.500
◇	(EJECTOR-E205)	17.500
◇	(EJECTOR-E205)	17.500

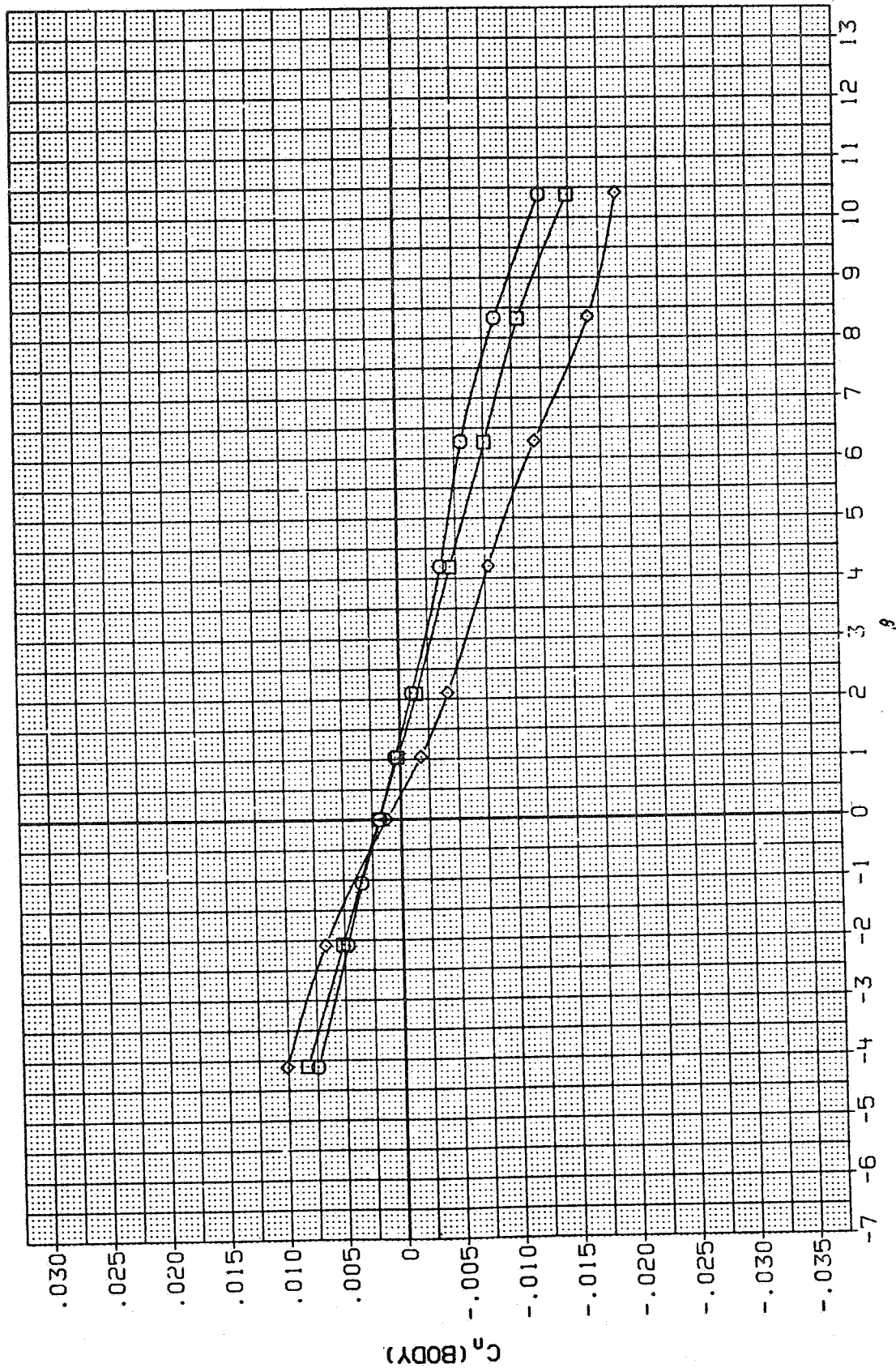


FIG. 77 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL ON
 MACH = .90

SYMBOL	CONFIGURATION	ALPHA
○	BI S1 N WI C1 V	17.500
□	BI S2 N WI C1 V	17.500
◇	BI S3 N WI C1 V	17.500

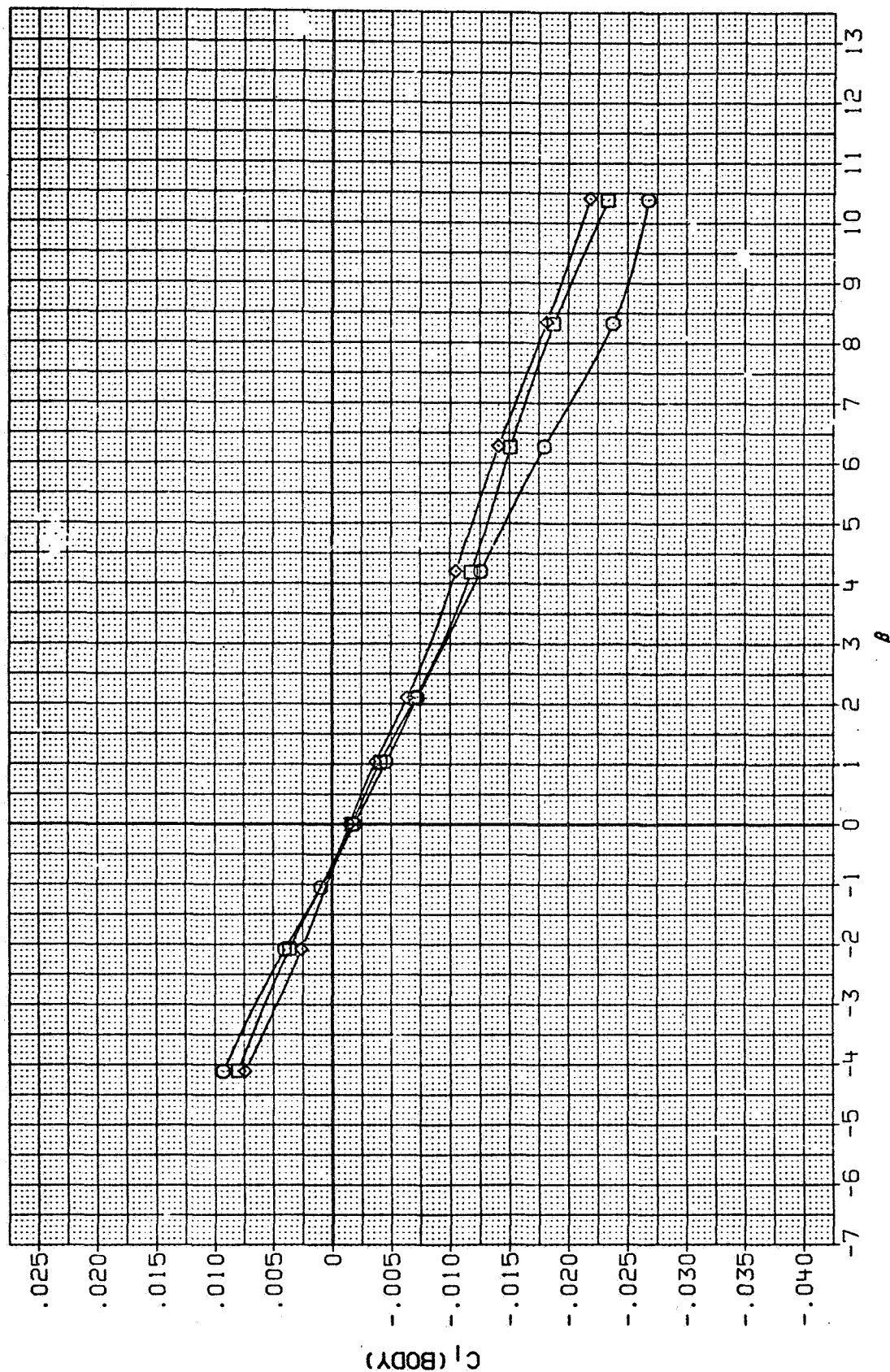


FIG. 77 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 $\alpha = 15^\circ$
 $M = 0.90$

SYMBOL CONFIGURATION ALPHA
 □ B1 S1 N W1 C1 V 17,500
 □ B1 S2 N W1 C1 V 17,500
 ◇ B1 S3 N W1 C1 V 17,500

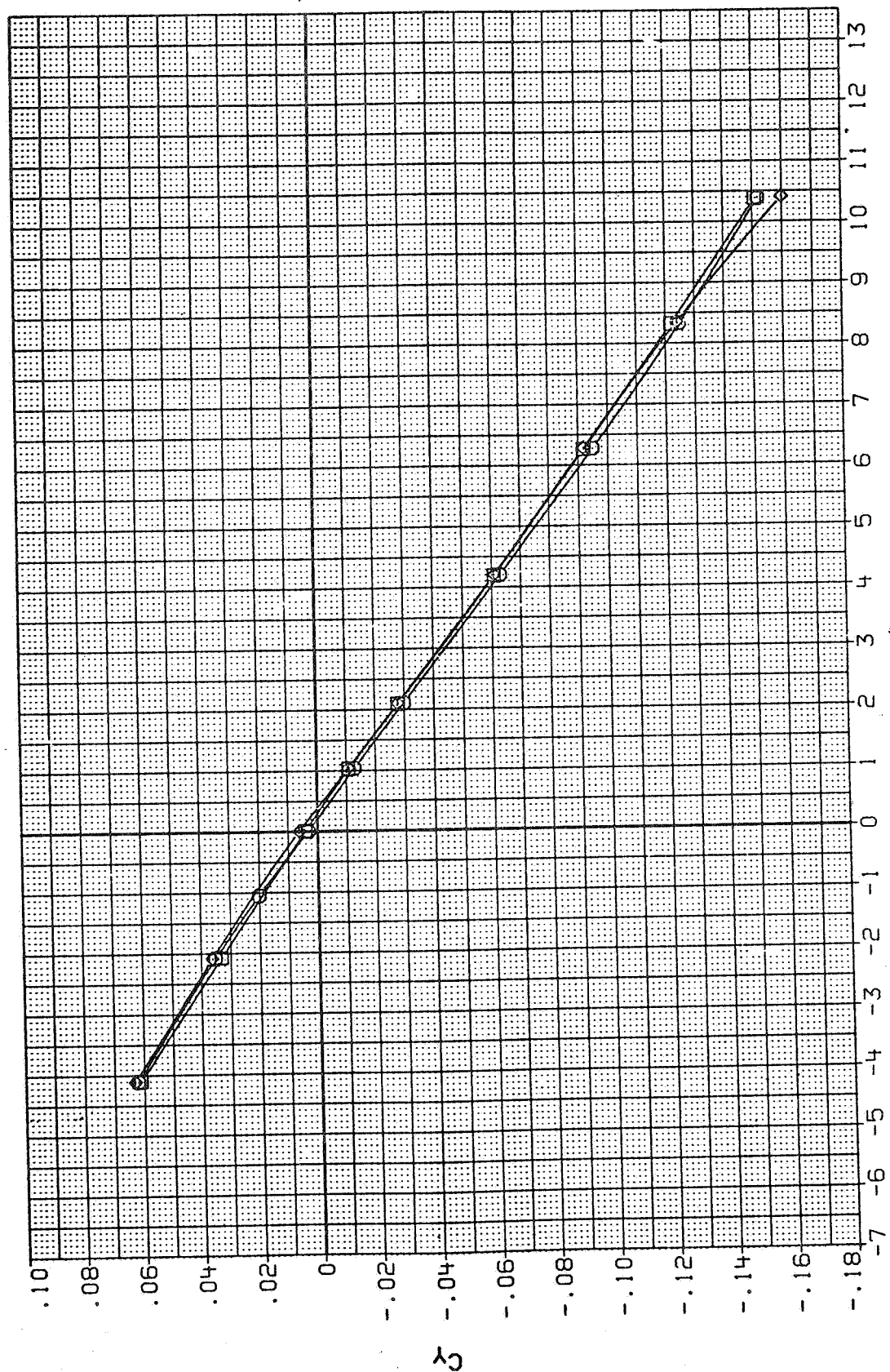


FIG. 77 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL ON
 MACH = .90

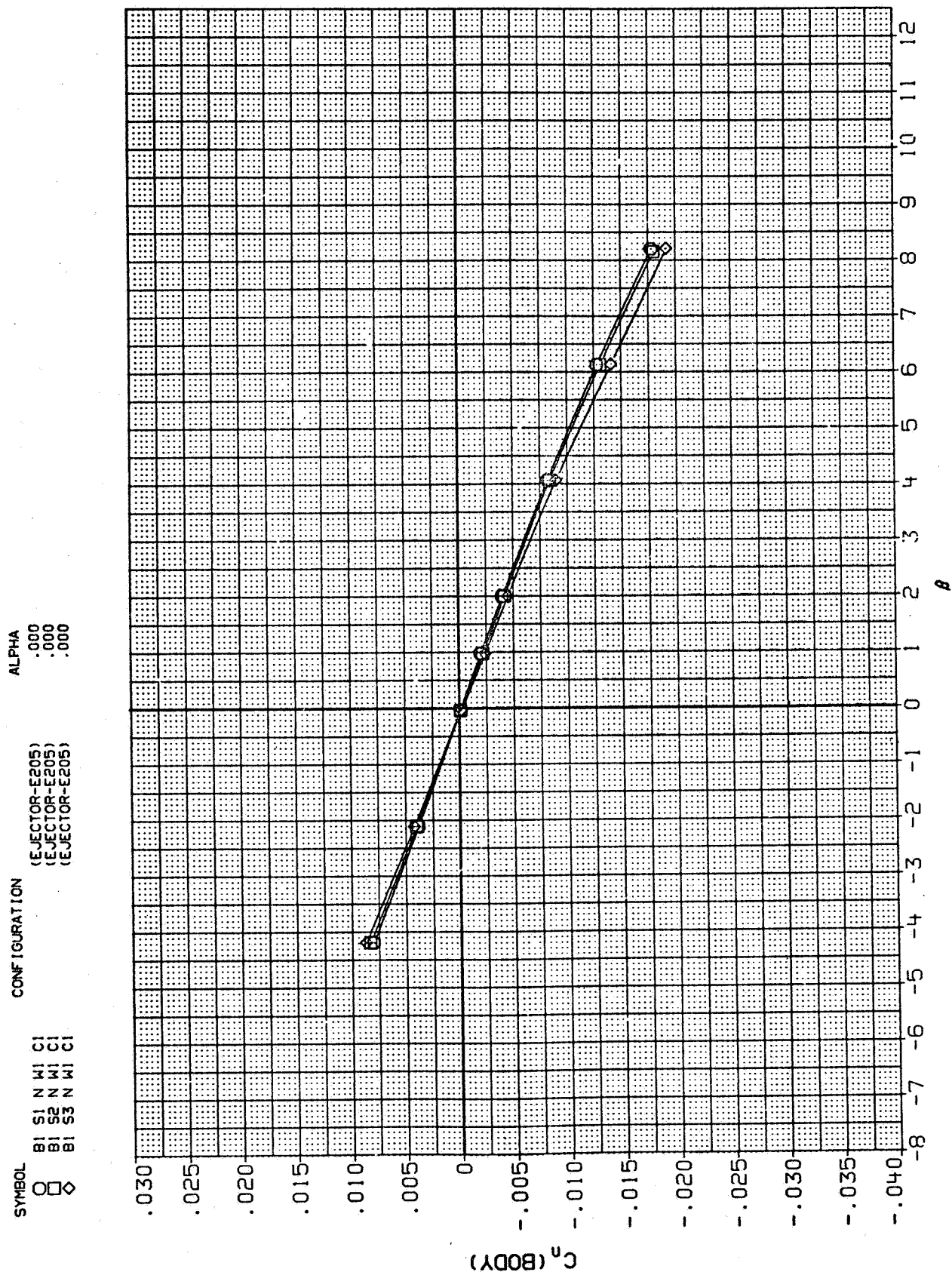


FIG. 78 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF
 MACH = .90

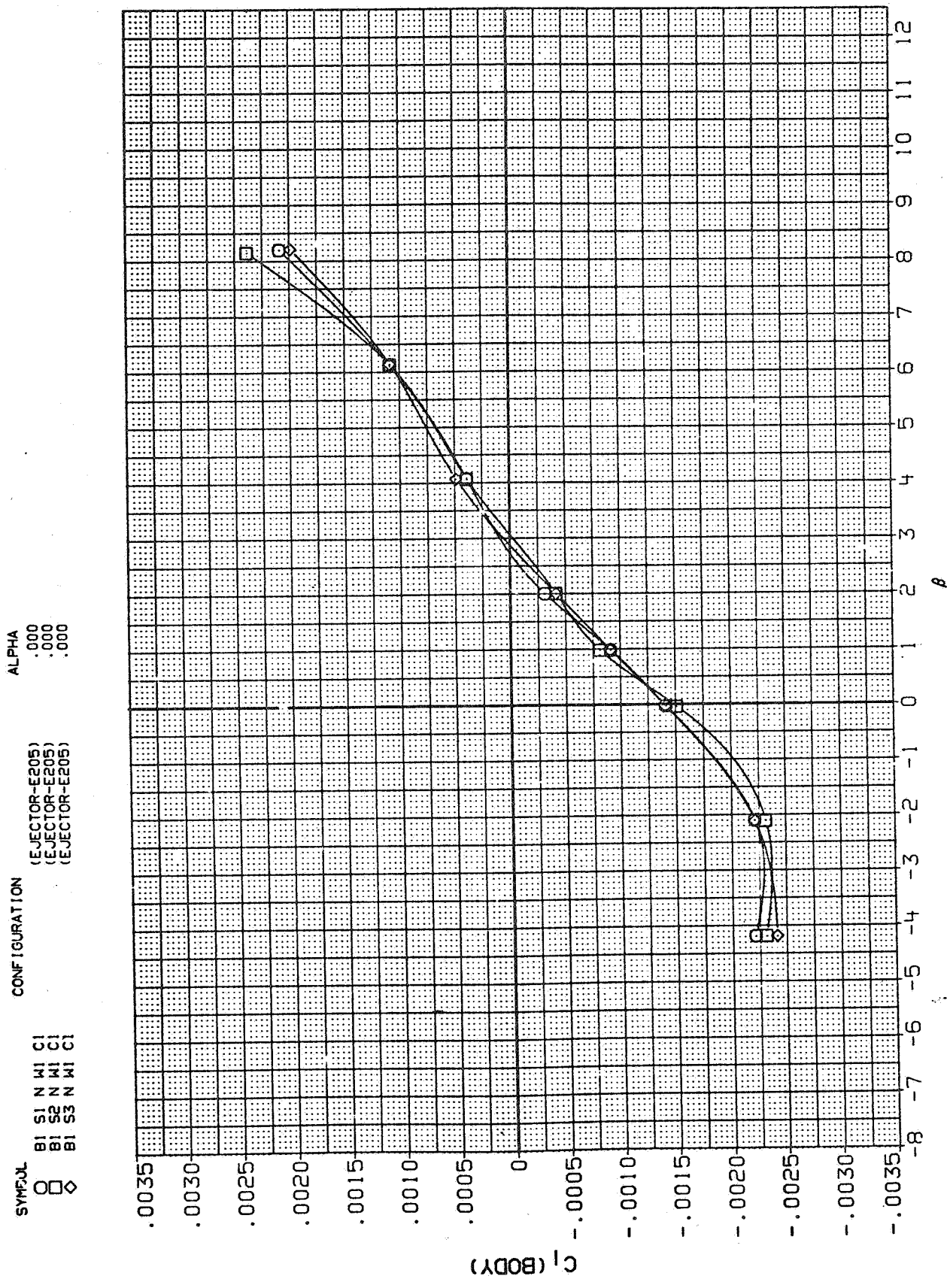


FIG. 78 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES; VERTICAL TAIL OFF
 MACH = .90

SYMBOL	CONFIGURATION	ALPHA
□	B1 S1 N W1 C1	.000
◇	B1 S2 N W1 C1	.000
◇	B1 S3 N W1 C1	.000

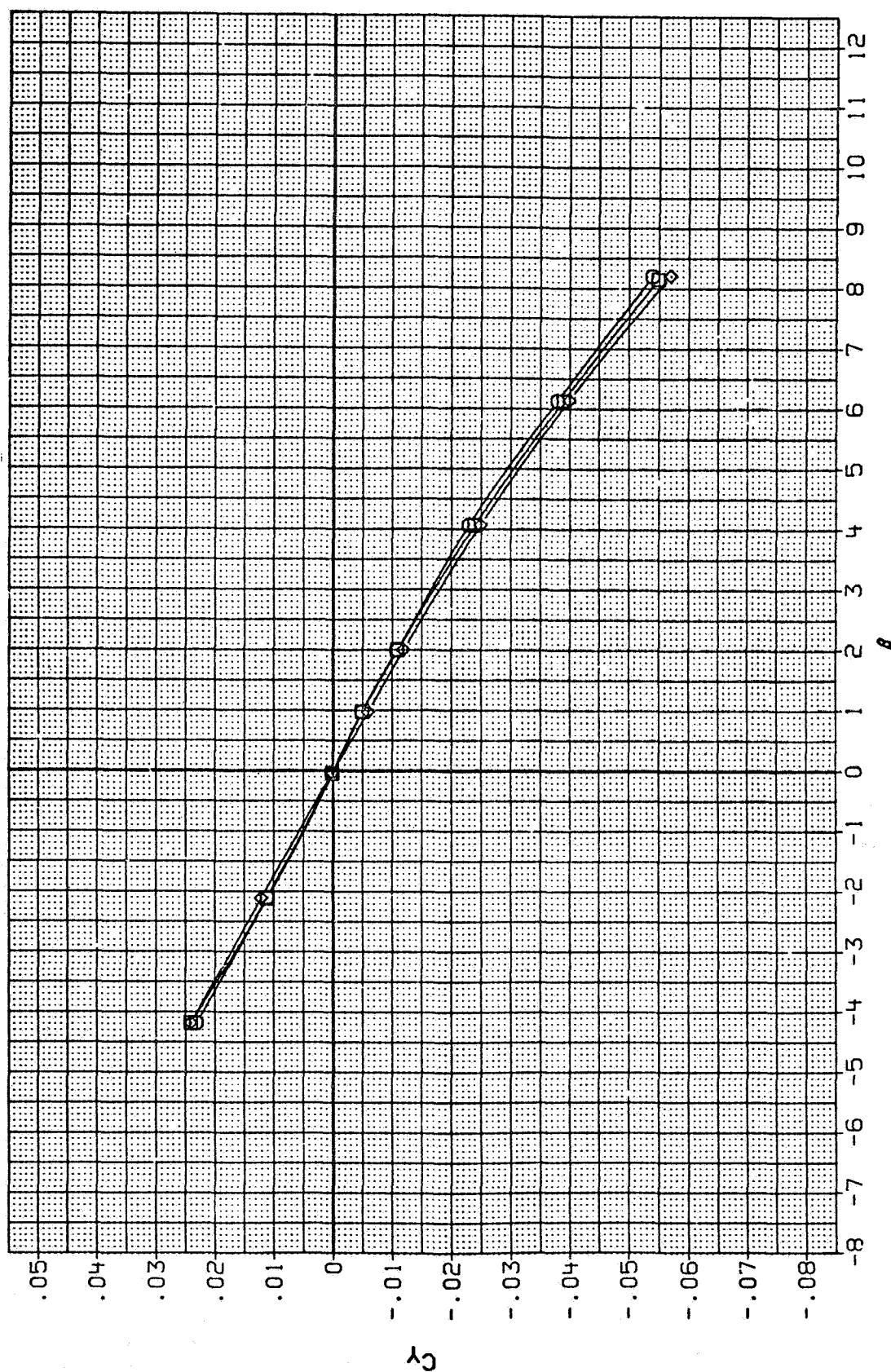


FIG. 78 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF

MACH = .90

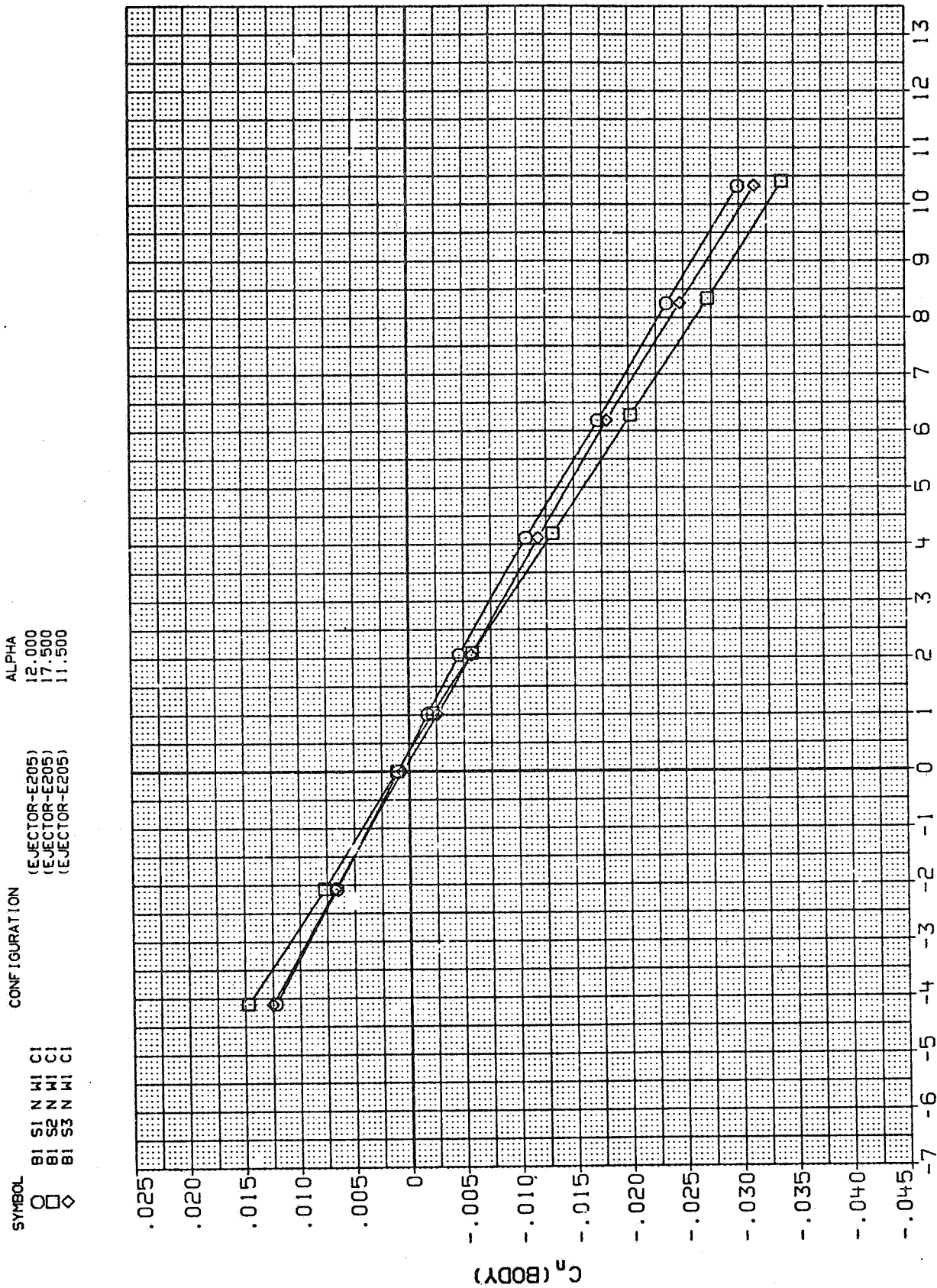


FIG. 78 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL OFF
 MACH = .90

SYMBOL	CONFIGURATION	ALPHA
○	(EJECTOR-E205)	12.000
□	(EJECTOR-E205)	17.500
◇	(EJECTOR-E205)	11.500

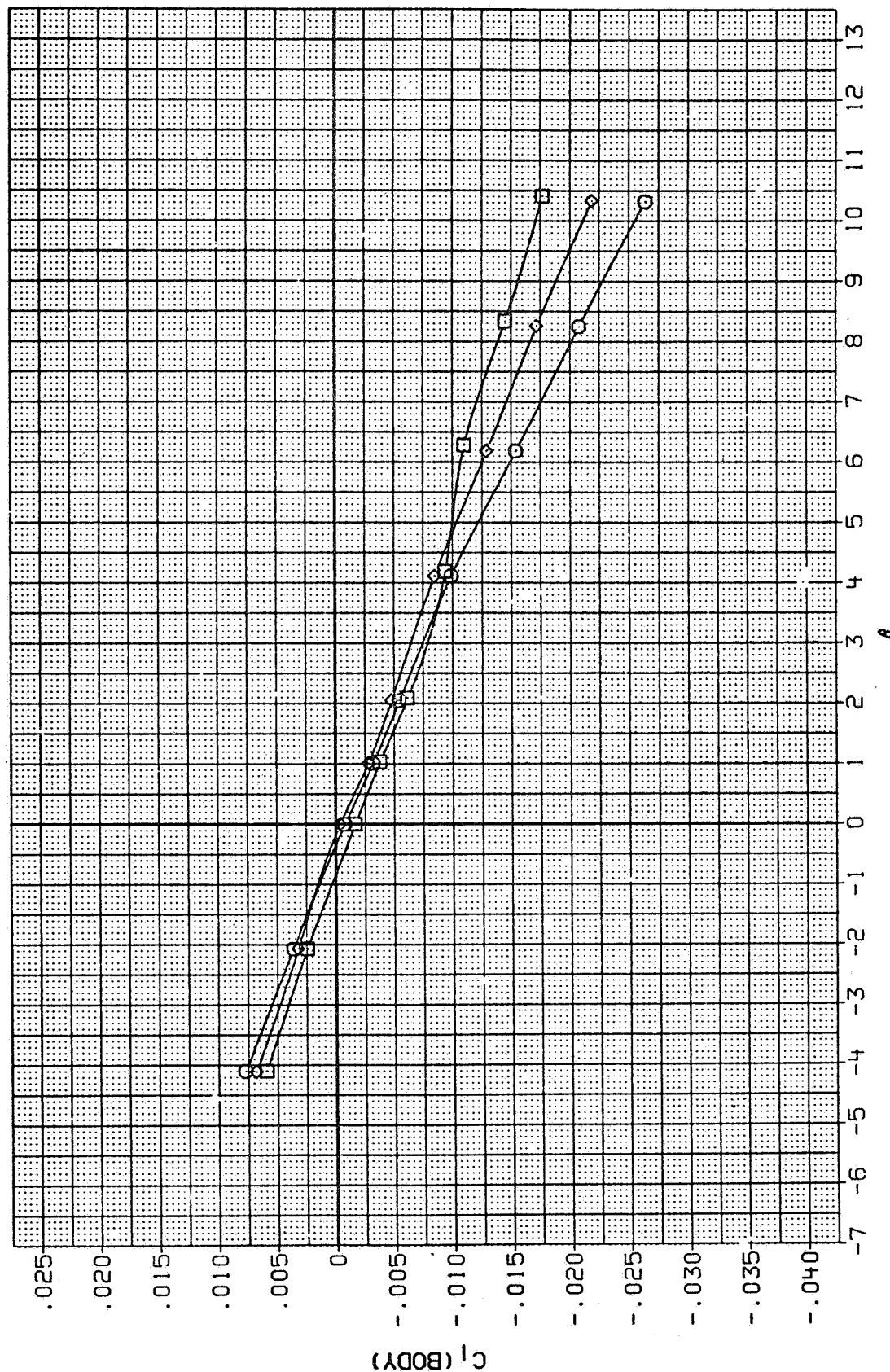


FIG. 78 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL OFF
 MACH = .90

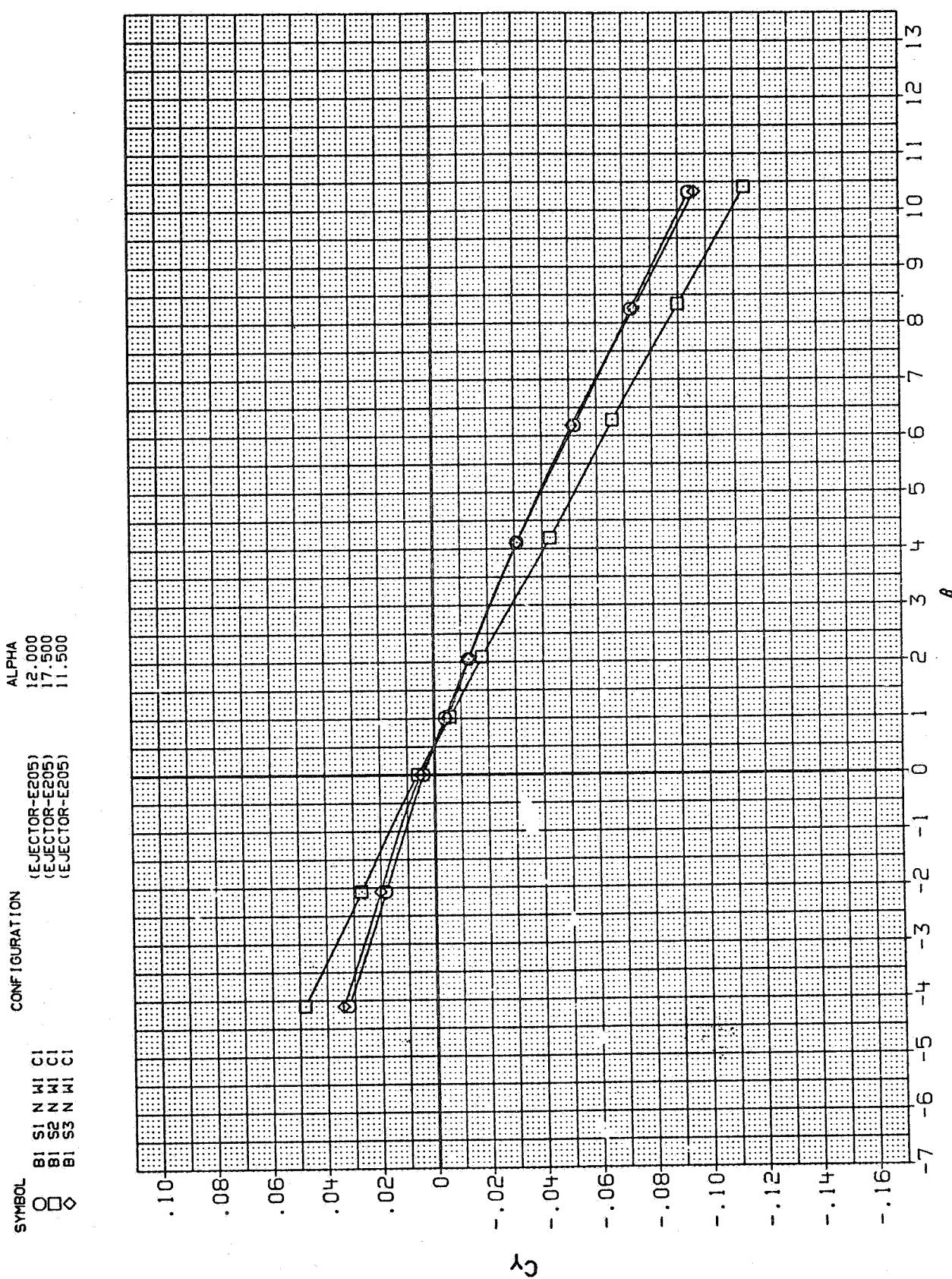


FIG. 78 STRAKE VARIATIONS; LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL OFF
 MACH = .90

SYMBOL CONFIGURATION ALPHA
 ○ (EJECTOR-E205) .000
 □ (EJECTOR-E205) .000
 ◇ (EJECTOR-E205) .000

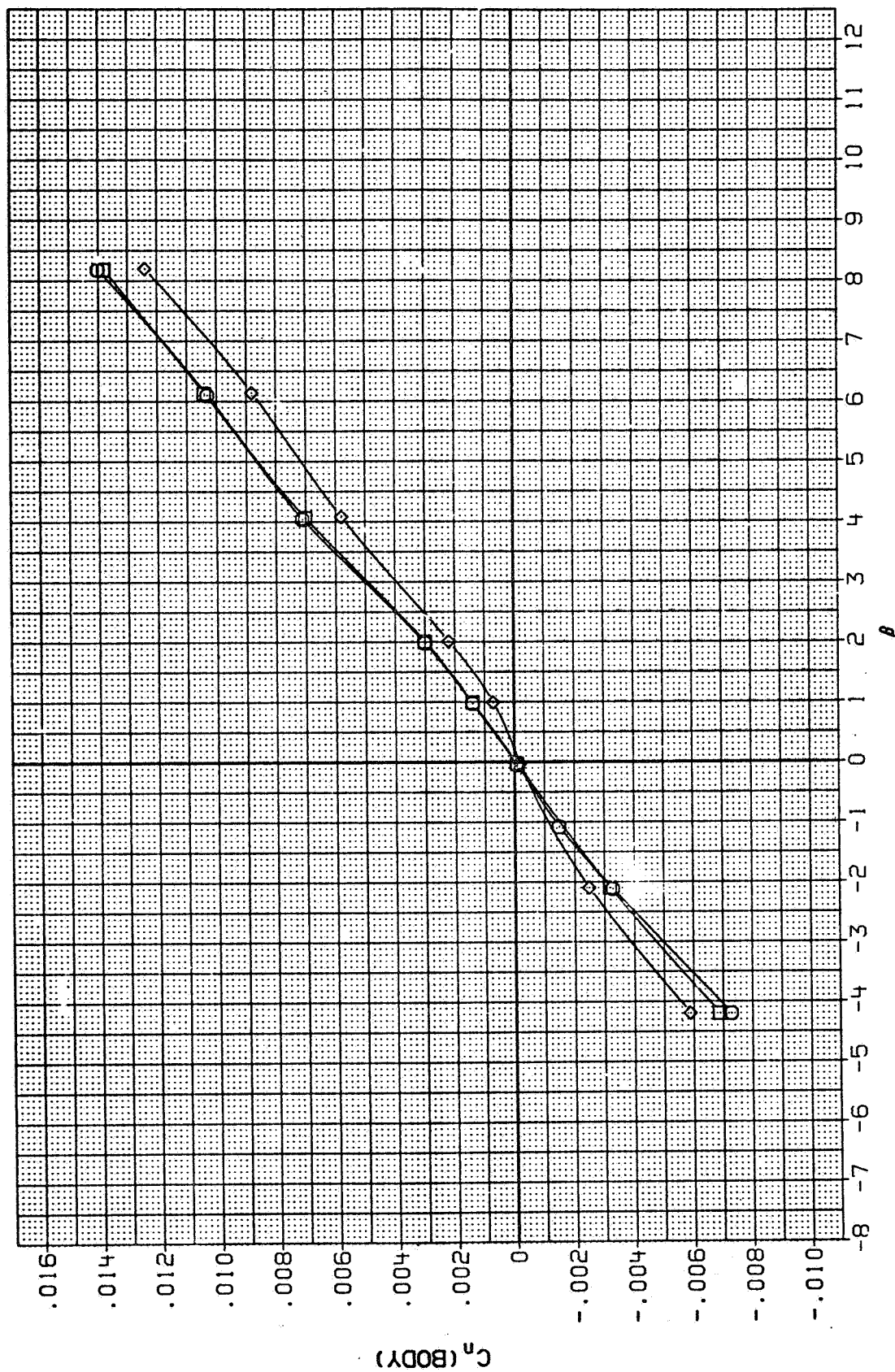


FIG. 79 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

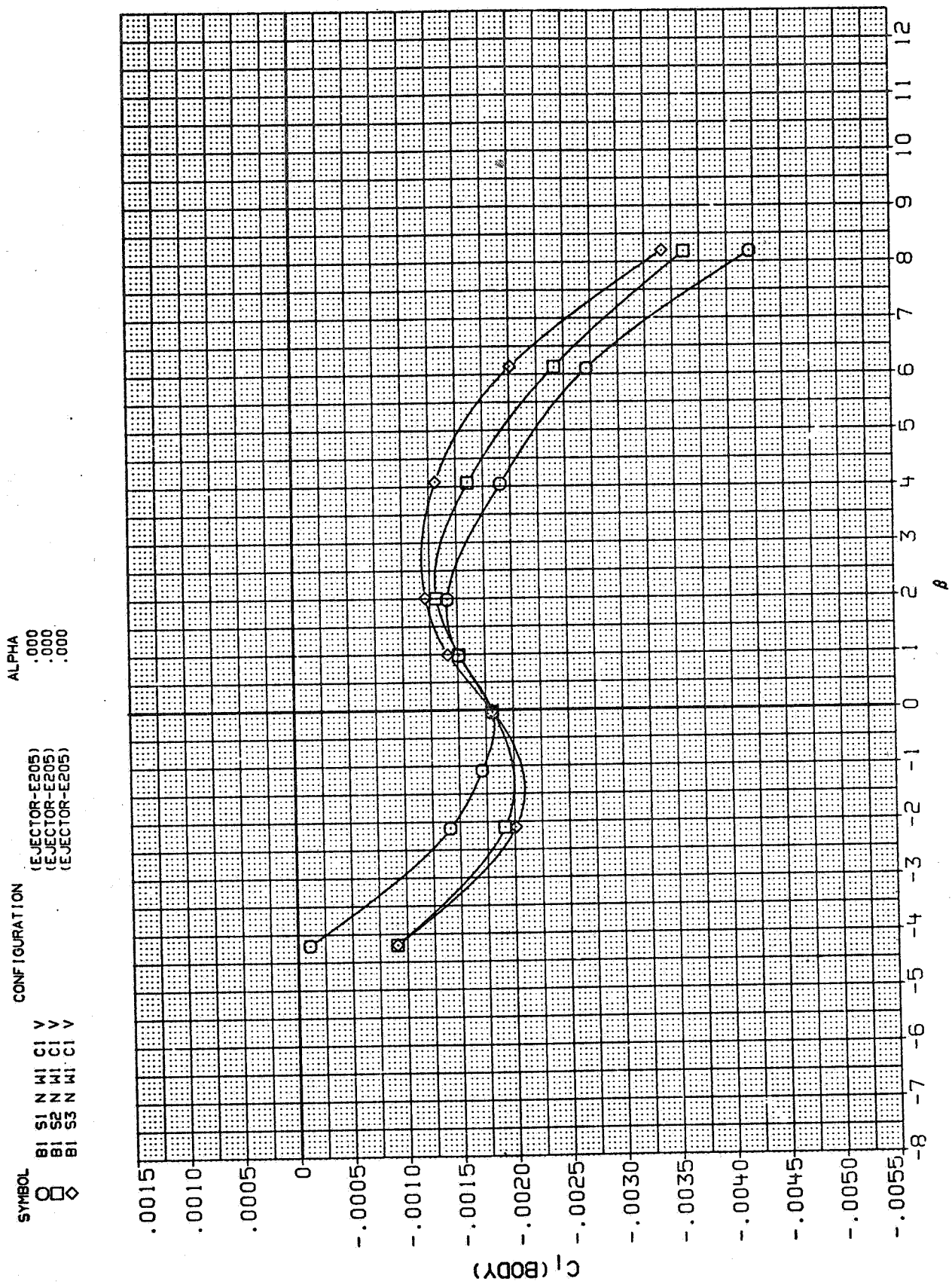


FIG. 79 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

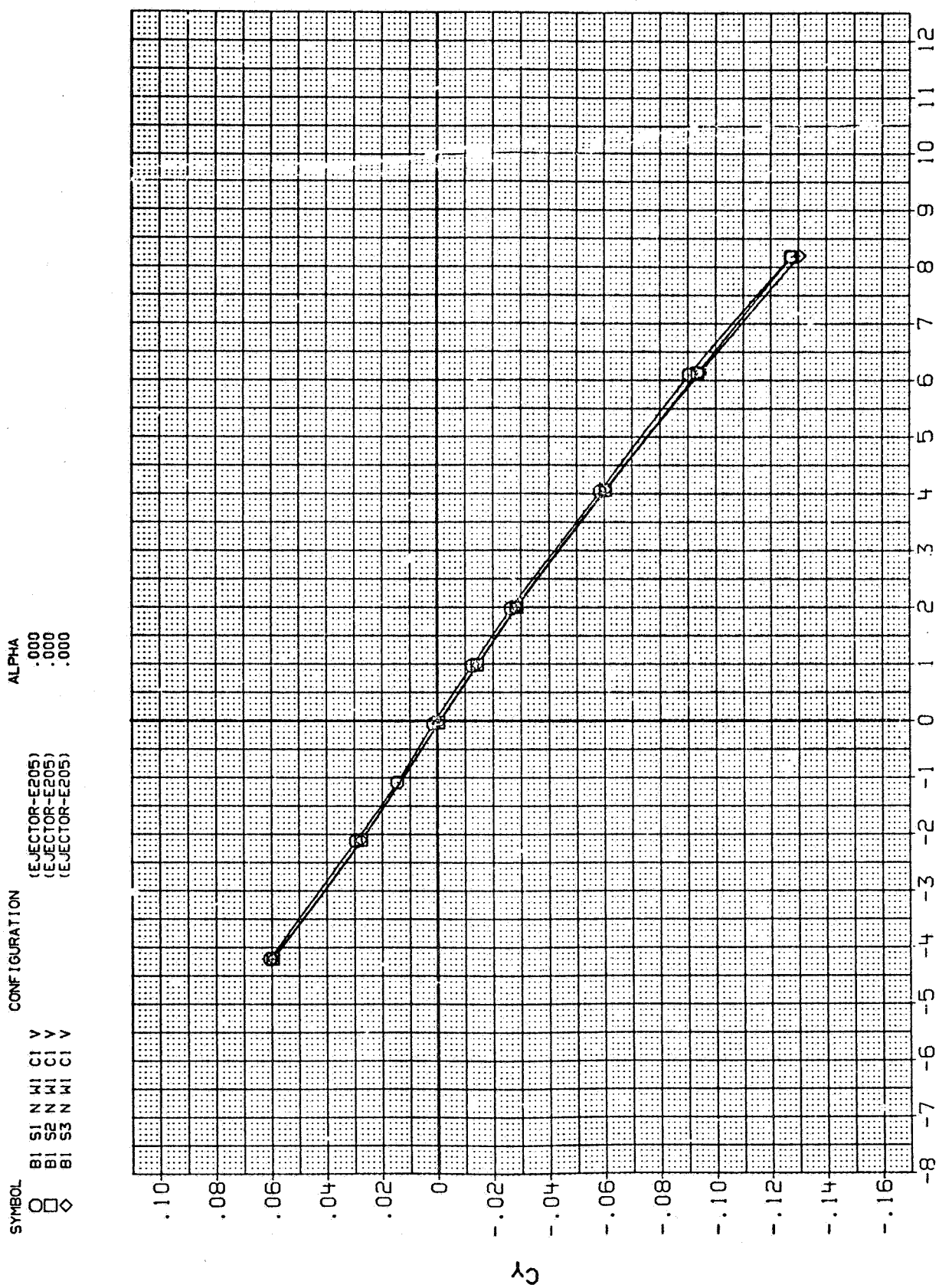


FIG. 79 STRAKE VARIATIONS; LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES; VERTICAL TAIL ON

MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
○	BI S1 N MI CI V	15.000
◇	BI S2 N MI CI V	12.000
□	BI S3 N MI CI V	11.500

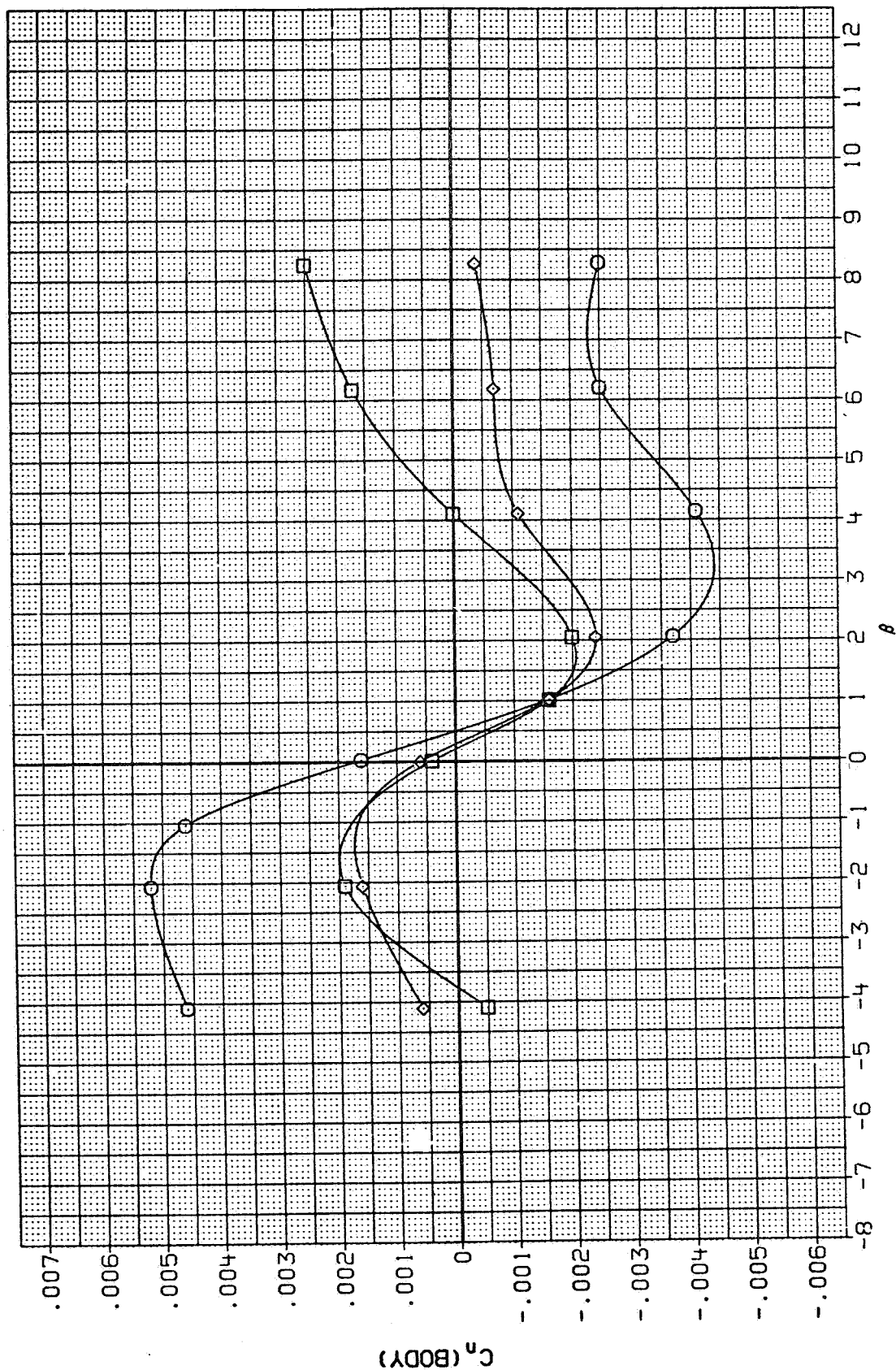


FIG. 79 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

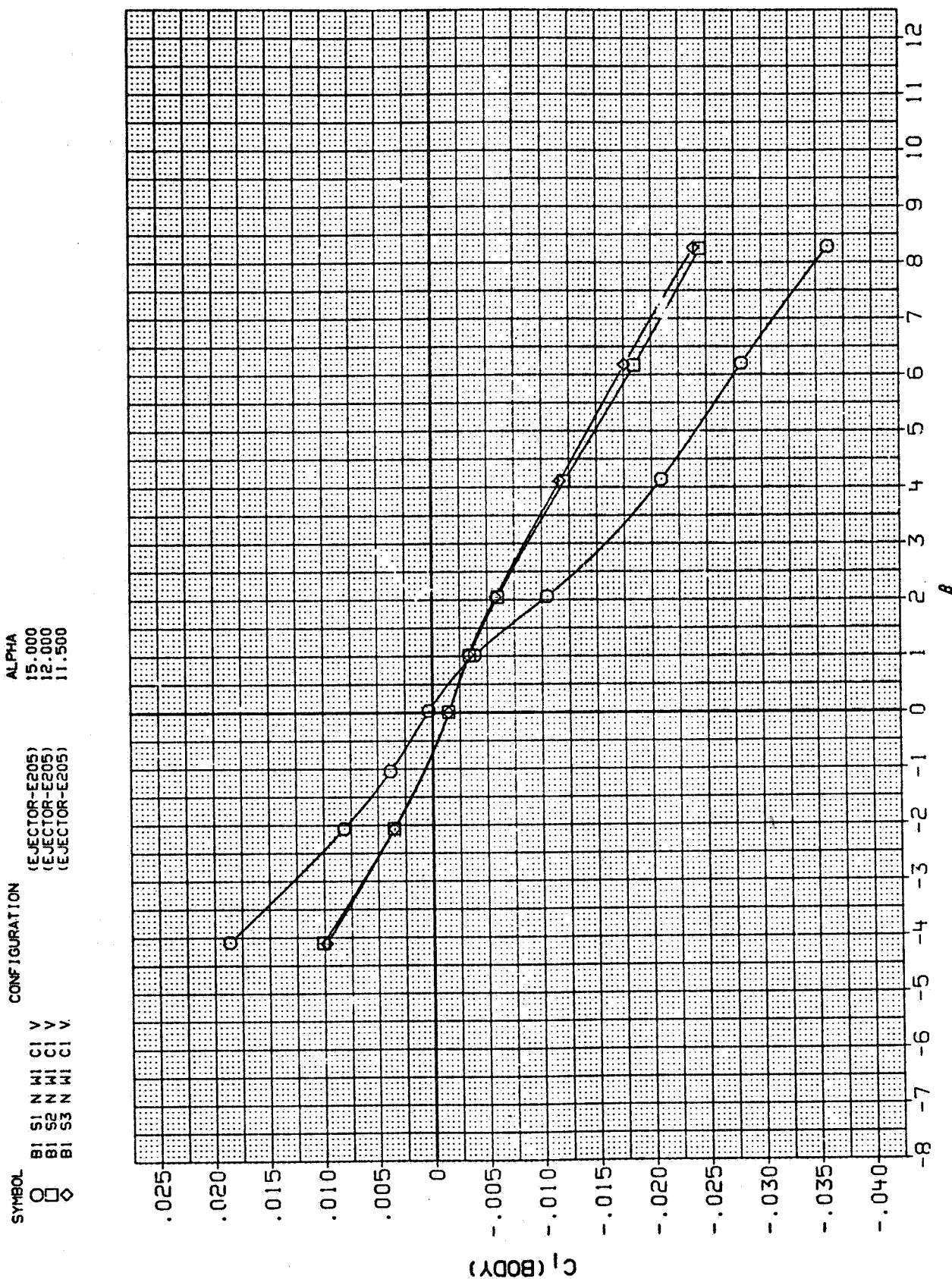


FIG. 79 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
□	B1 S1 N W1 C1 V	15.000
◇	(EJECTOR-E205)	12.000
◇	B1 S2 N W1 C1 V	11.500
◇	(EJECTOR-E205)	
◇	B1 S3 N W1 C1 V	
◇	(EJECTOR-E205)	

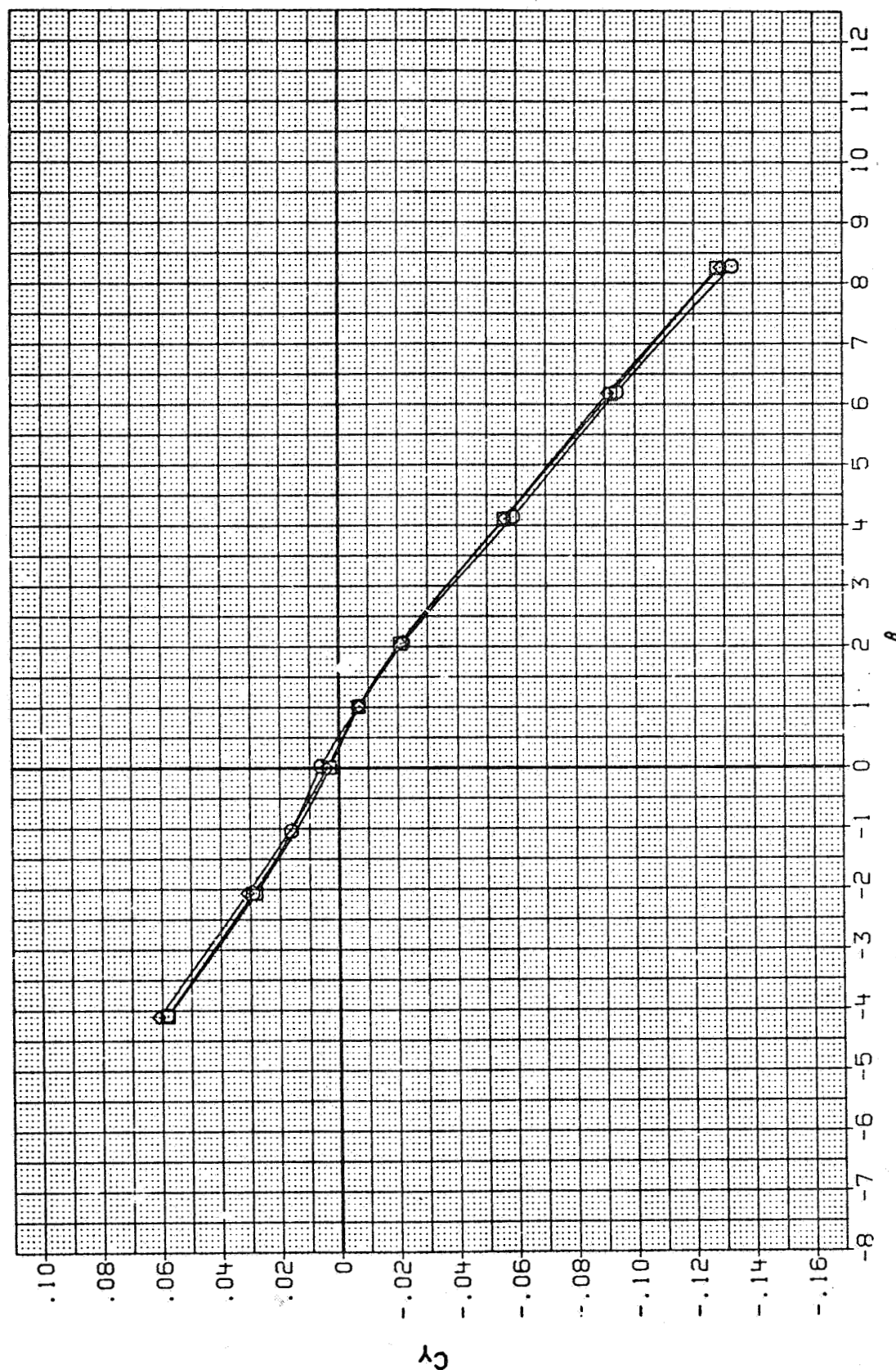


FIG. 79 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

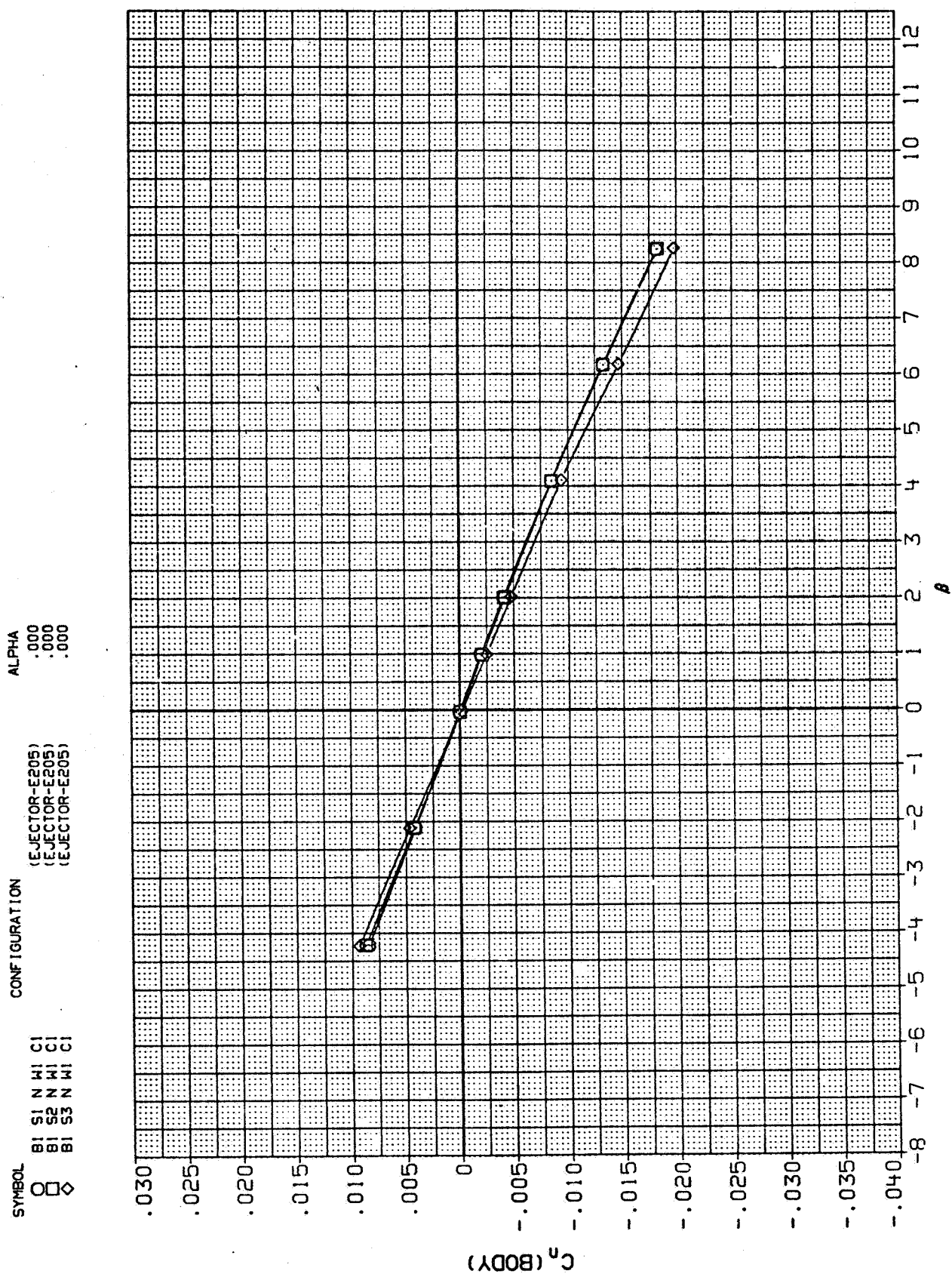


FIG. 80 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF
 MACH = 1.20

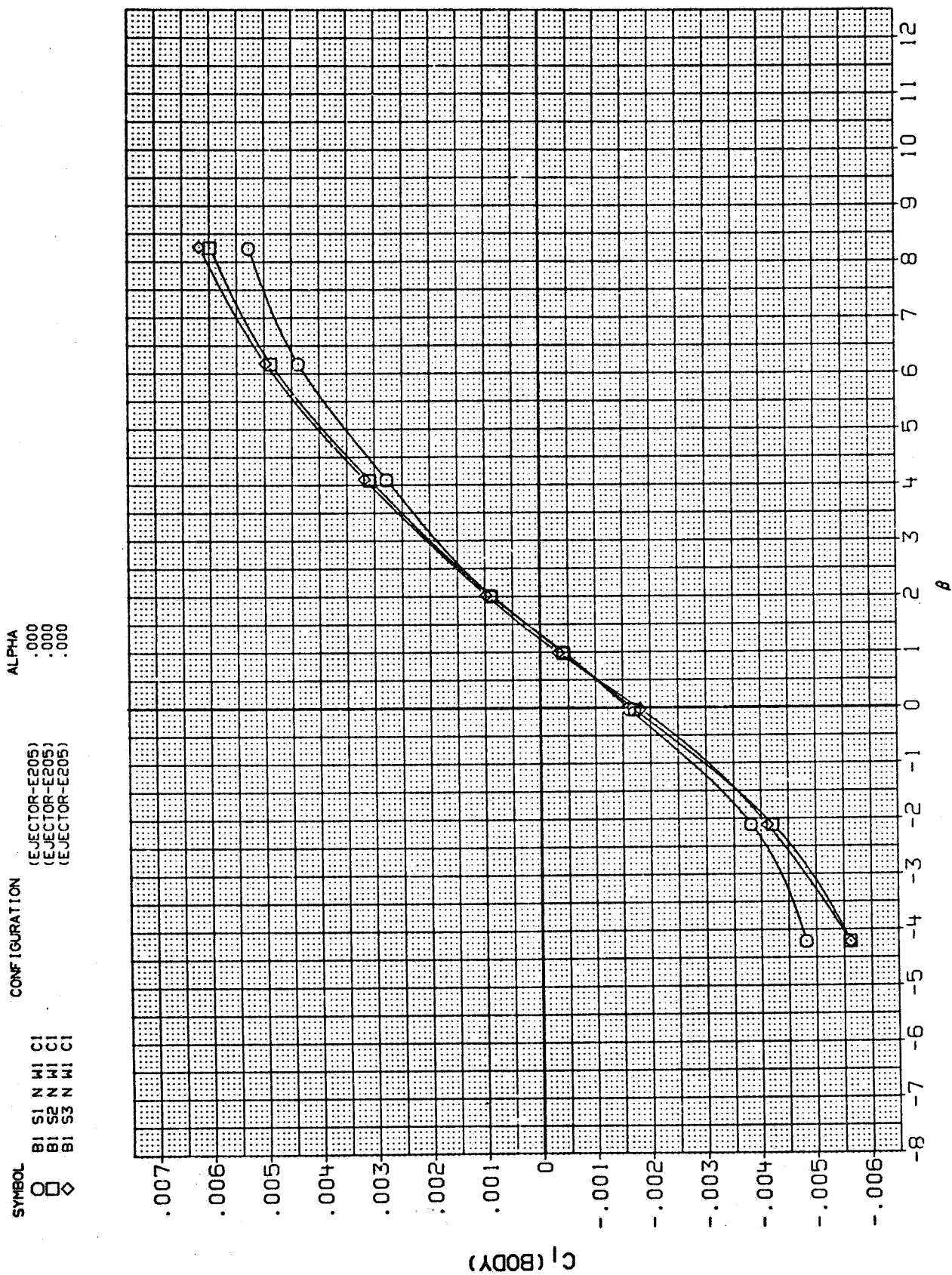


FIG. 80 STRAKE VARIATIONS; LATERAL/DIRECTIONAL CHARACTERISTICS
 $\alpha = 0$ DEGREES; VERTICAL TAIL OFF

MACH = 1.20

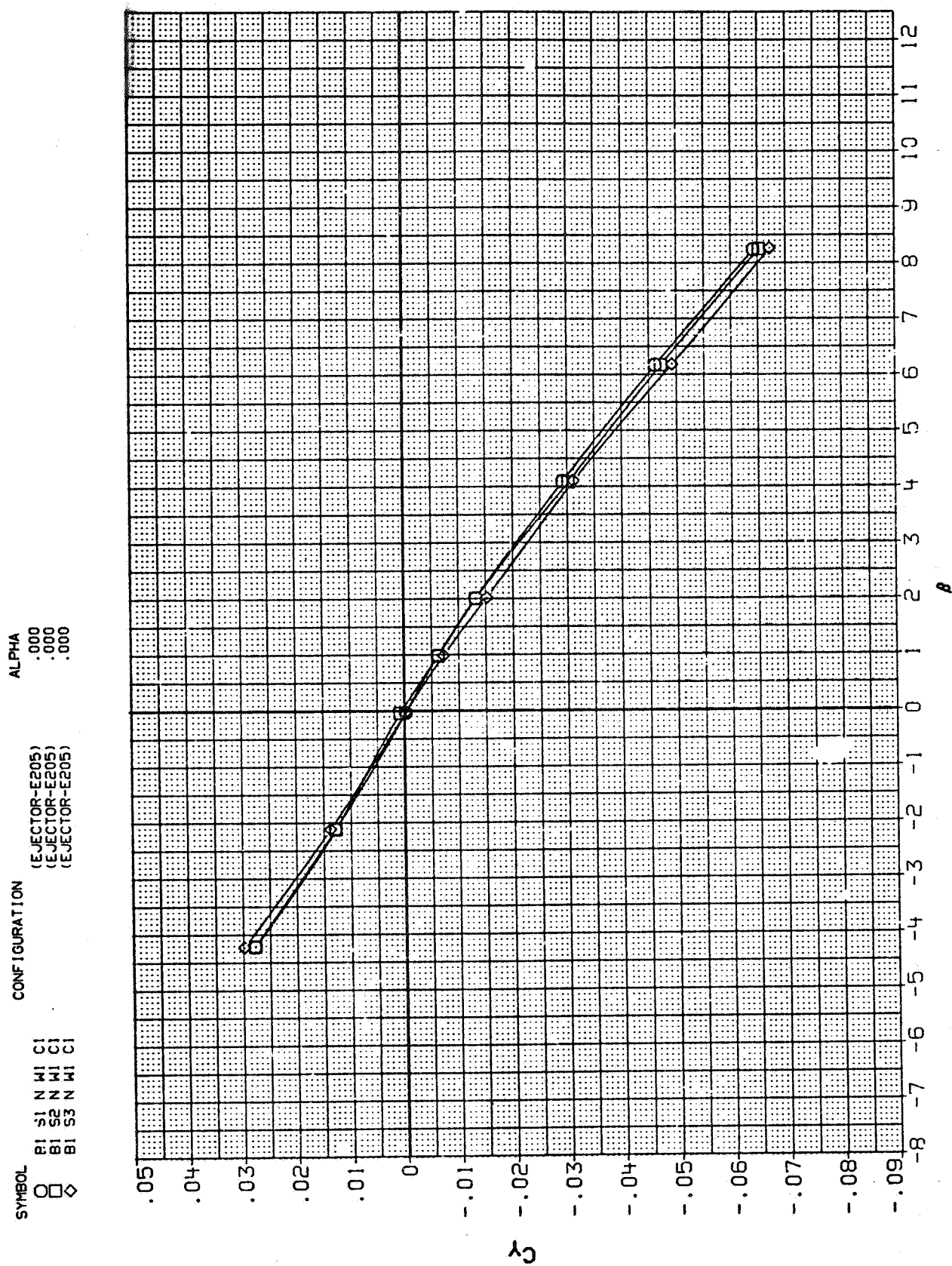


FIG. 80 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF

MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
□	BI S1 N WI CI (EJECTOR-E205)	12.000
◇	BI S2 N WI CI (EJECTOR-E205)	12.000
◇	BI S3 N WI CI (EJECTOR-E205)	11.500

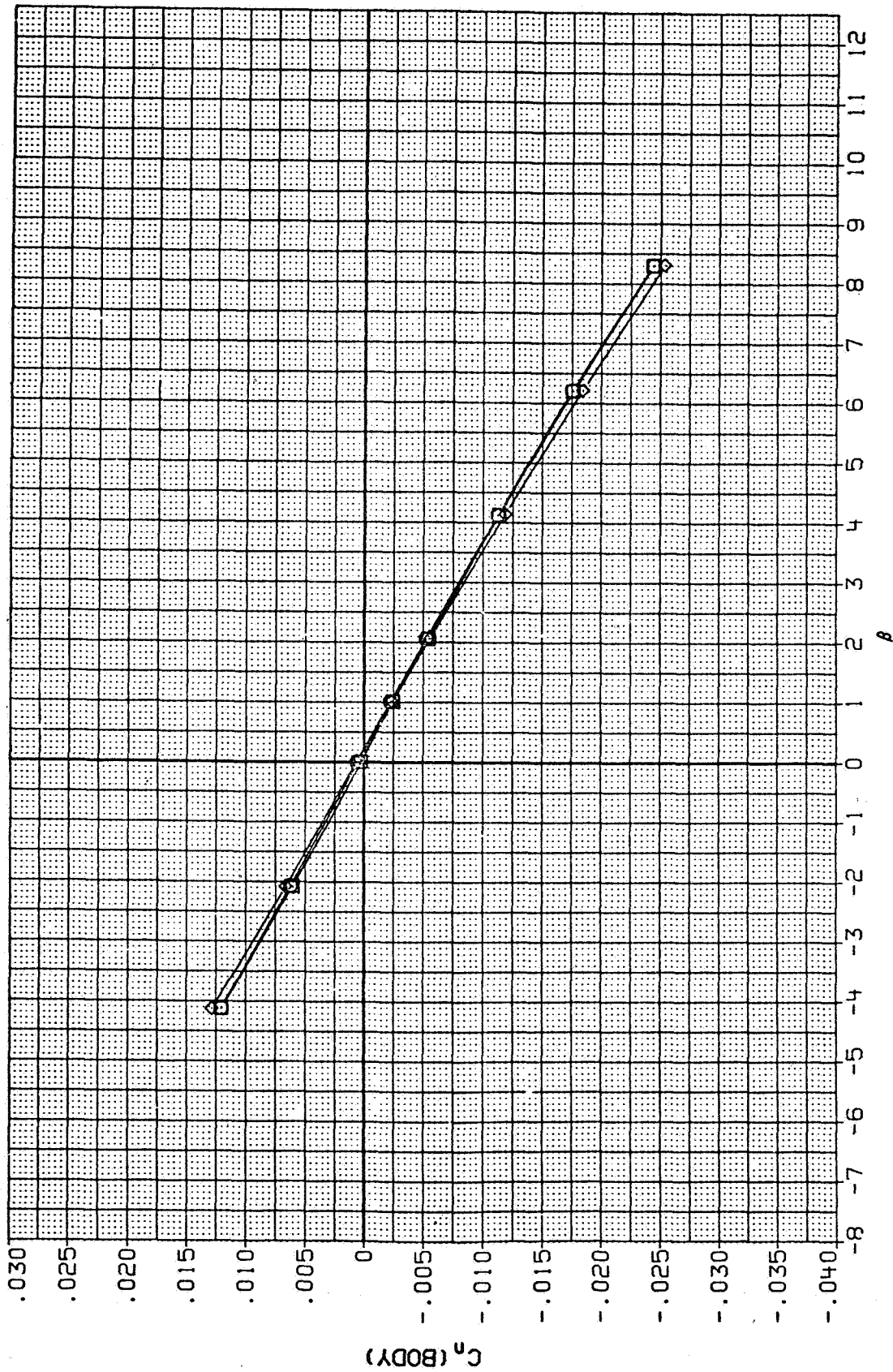


FIG. 80 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL OFF
 MACH = 1.20

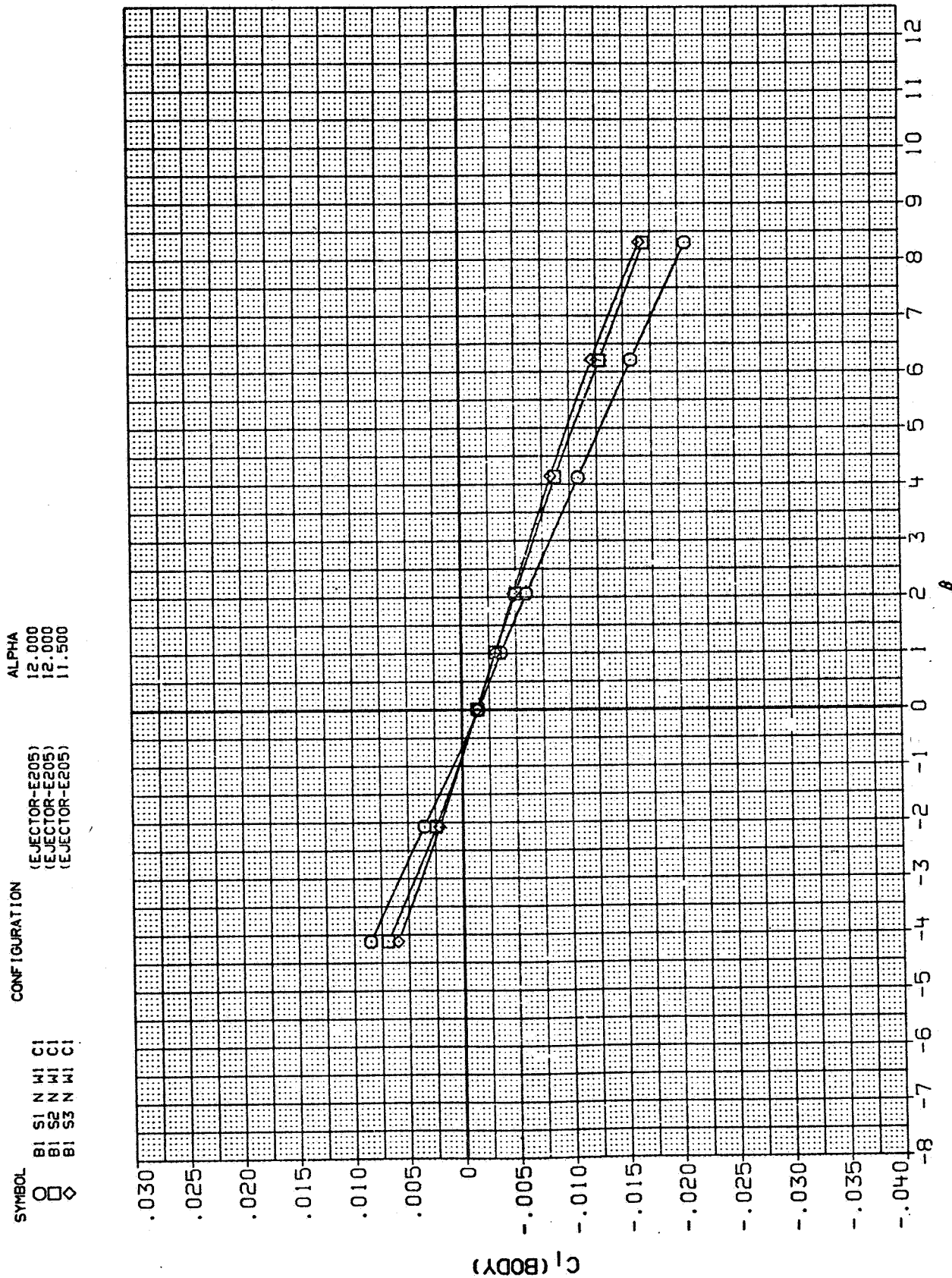


FIG. 80 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL OFF
 MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
□	(EJECTOR-E205)	12.000
◇	(EJECTOR-E205)	12.000
◇	(EJECTOR-E205)	11.500

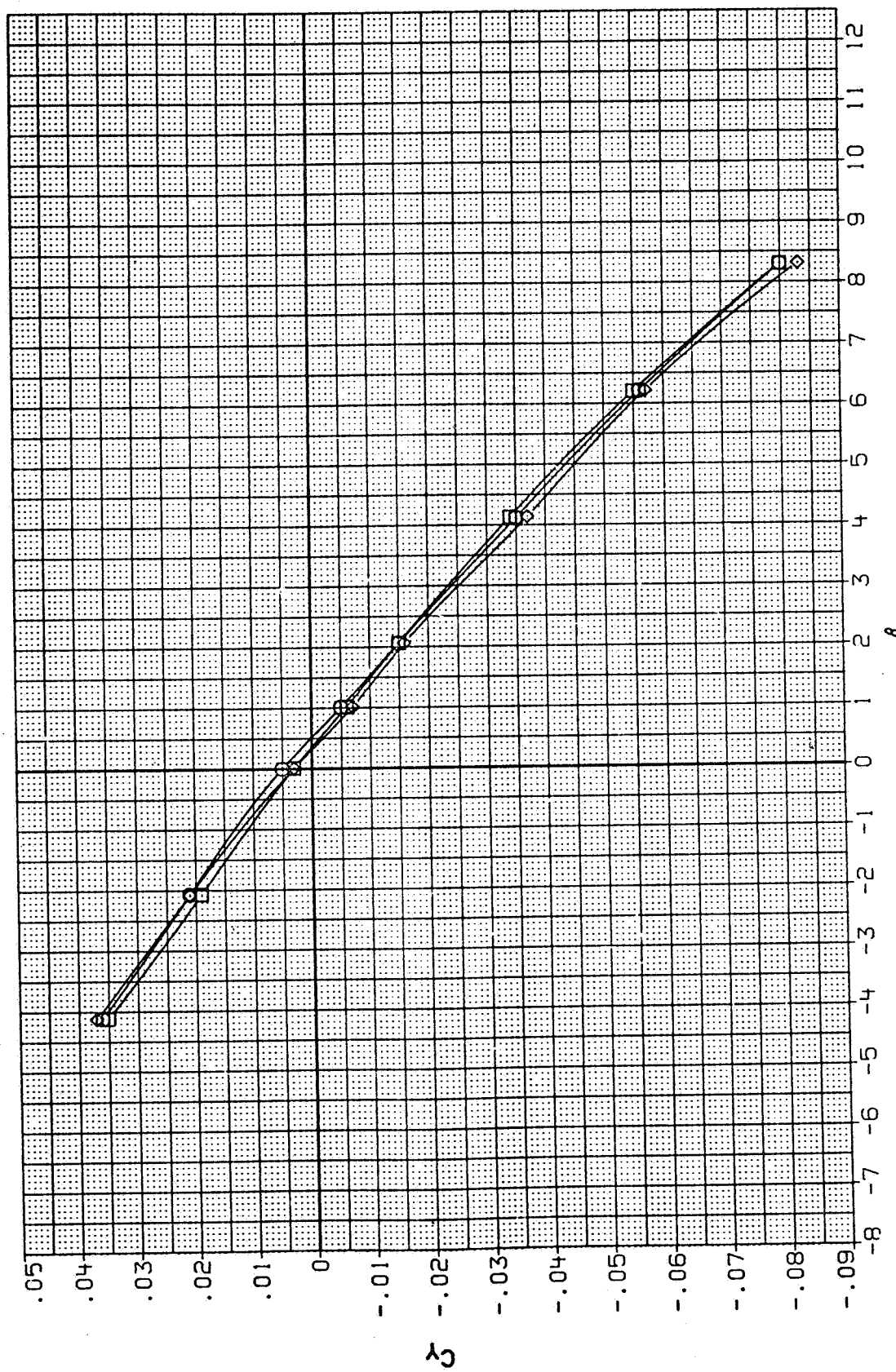


FIG. 80 STRAKE VARIATIONS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL OFF
 MACH = 1.20

(RALS-R104)

SYMBOL	CONFIGURATION	B2	N	M2	C1	V	PARAMETRIC VALUES
	MACH	BETA	RN/L	LE-C	TE-C	VERT	
○	.400	.000	.000	.000	.000	.000	
□	.598	.000	9.843	.000	.000	.000	
△	.799	.000	.000	.000	.000	.000	
	.901	.000	.000	.000	.000	.000	CANARD

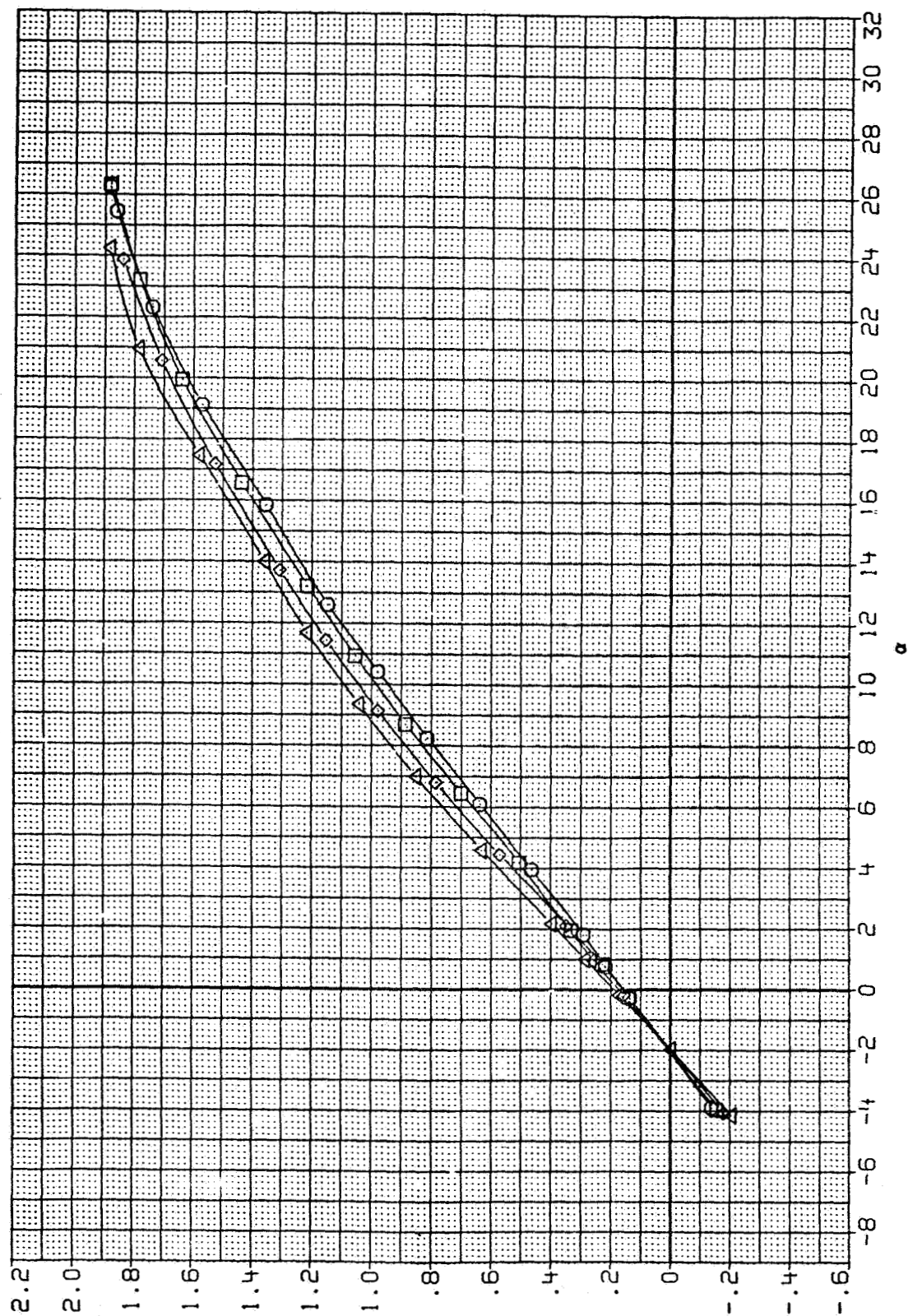


FIG. 81 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(RALS-R104)

CONFIGURATION B2 N W2 C1 V
MACH .946
1.094
1.198
1.396

BETA .000
RN/L 9.843
LE-W .000
TE-W .000
CANARD .000

PARAMETRIC VALUES
LE-C
TE-C
VERT

SYMBOL
□
◇
△

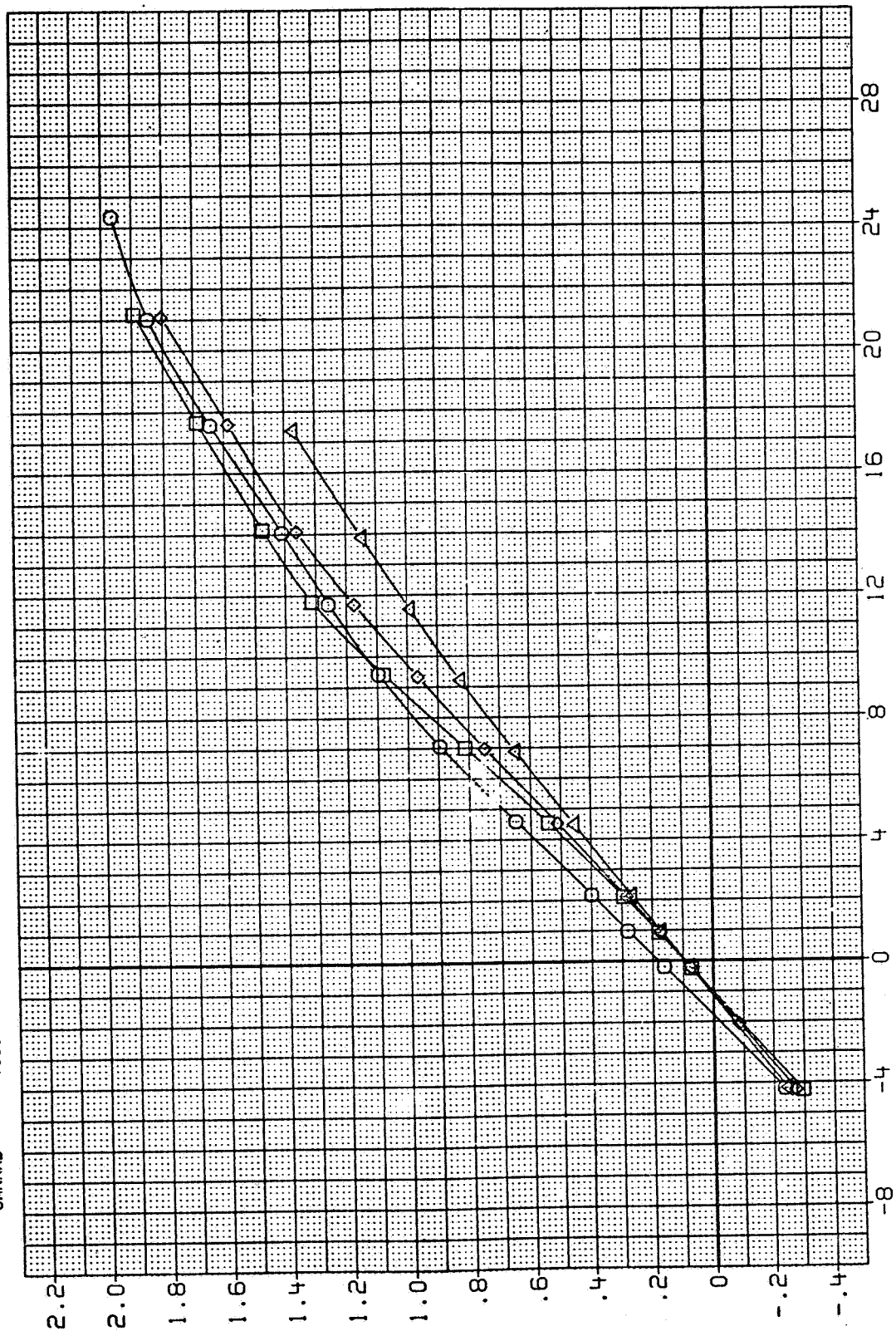


FIG. 81 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(RALS-R104)

CONFIGURATION B2 N W2 C1 V

MACH	BETA	RN/L	LE-H	TE-W	CANARD
.400	.000	.000	.000	.000	.000
.598	.000	9.843	.000	.000	.000
.799	.000	.000	.000	.000	.000
.901	.000	.000	.000	.000	.000

SYMBOL
□ ◇ △

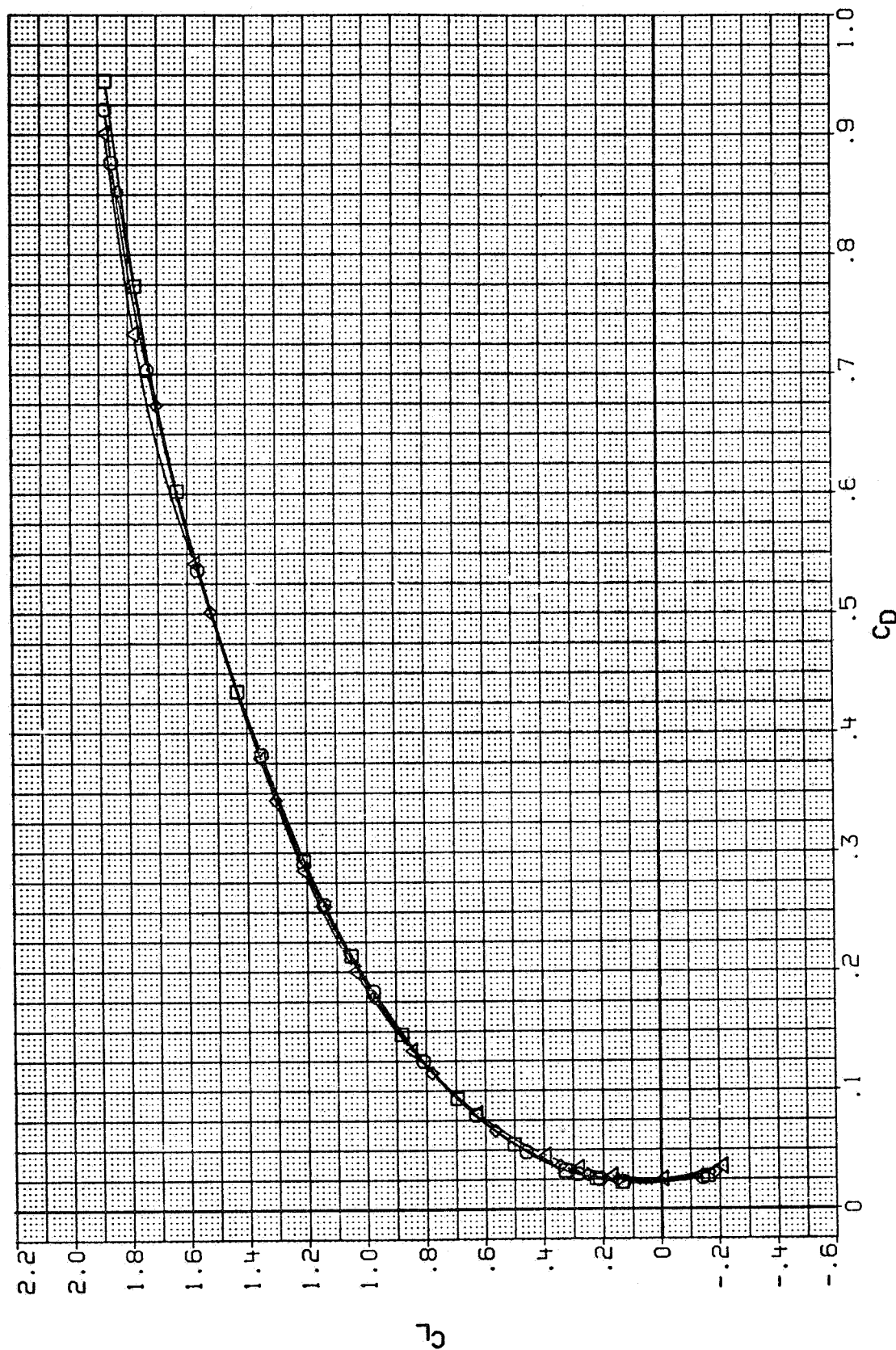


FIG. 81 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(RALS-R104)

CONFIGURATION B2 N W2 C1 V	
MACH	PARAMETRIC VALUES
.946	BETA .000 LE-C
1.094	RN/L 9.843 TE-C
1.198	LE-W .000 VERT
1.396	TE-W .000
	CANARD .000

SYMBOL
□ ◇ △

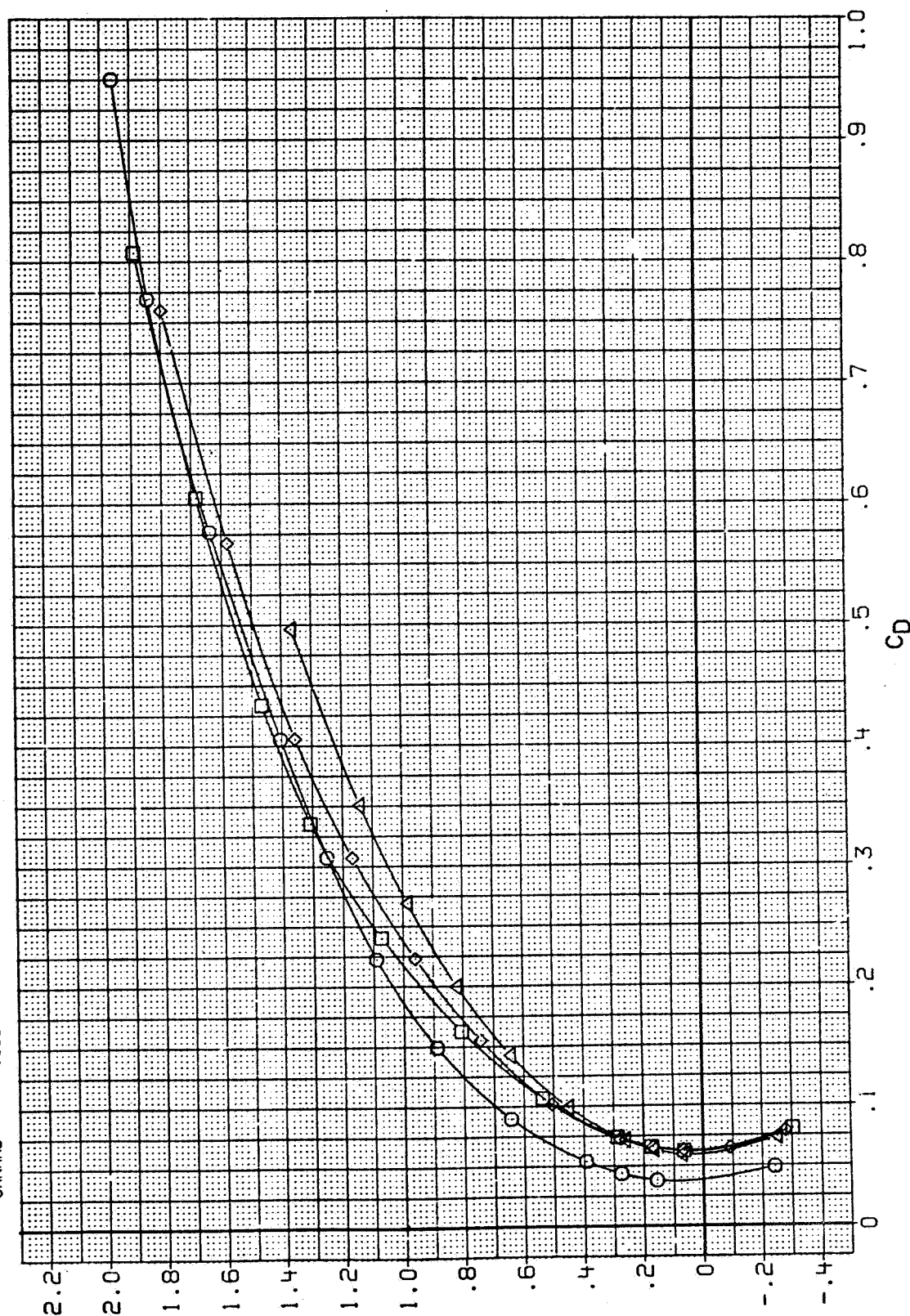


FIG. 81 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(RALS-R104)

CONFIGURATION B2 N W2 C1 V

PARAMETRIC VALUES

MACH	BETA	RN/L	LE-W	TE-W	CANARD	LE-C	TE-C	VERT
.400	.000	.000	.000	.000	.000	.000	.000	.000
.598	.000	.000	.000	.000	.000	.000	.000	.000
.799	.000	.000	.000	.000	.000	.000	.000	.000
.901	.000	.000	.000	.000	.000	.000	.000	.000

SYMBOL

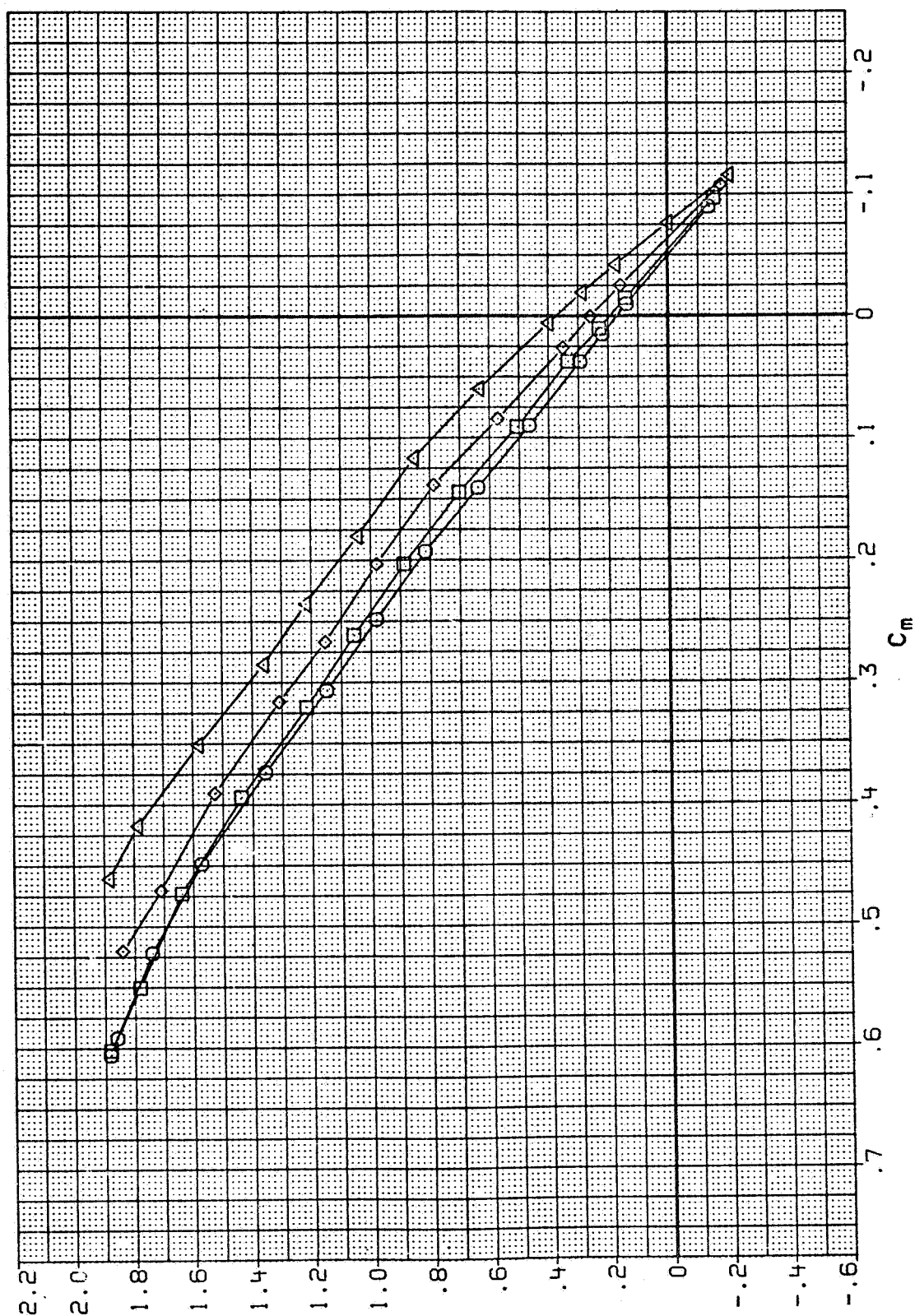



FIG. 81 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(RALS-R104)

CONFIGURATION B2 N W2 C1 V
MACH .946
BETA .000
RN/L 9.843
LE-W .000
TE-W .000
CANARD .000

SYMBOL
○ □ ◇ △

PARAMETRIC VALUES
LE-C
TE-C
VERT

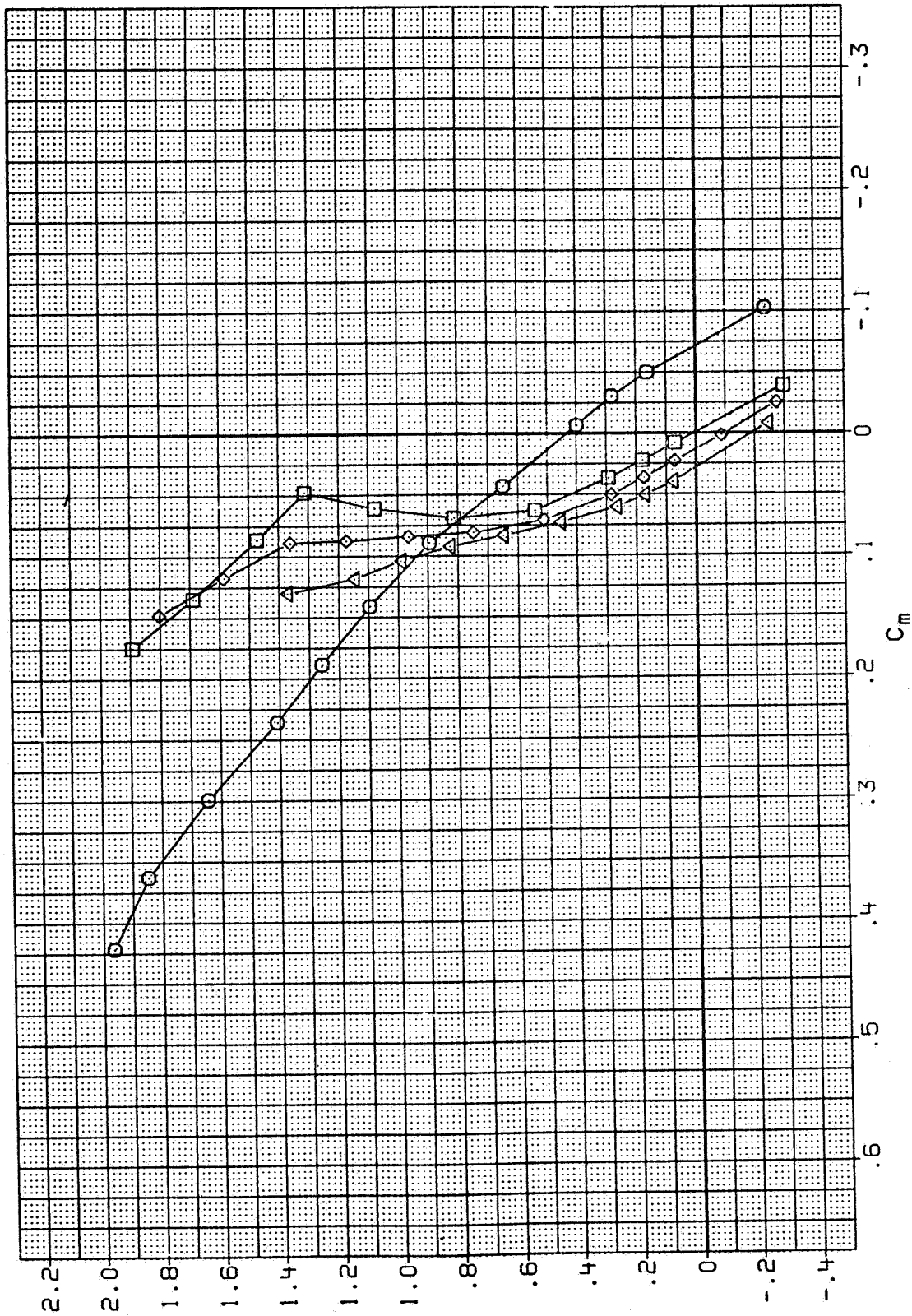


FIG. 81 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(RALS-R104)

CONFIGURATION B2 N W2 C1 V
MACH
SYMBOL
BETA .000
RN/L 9.843
LE-W .000
TE-W .000
CANARD .000
PARAMETRIC VALUES
LE-C
TE-C
VERT

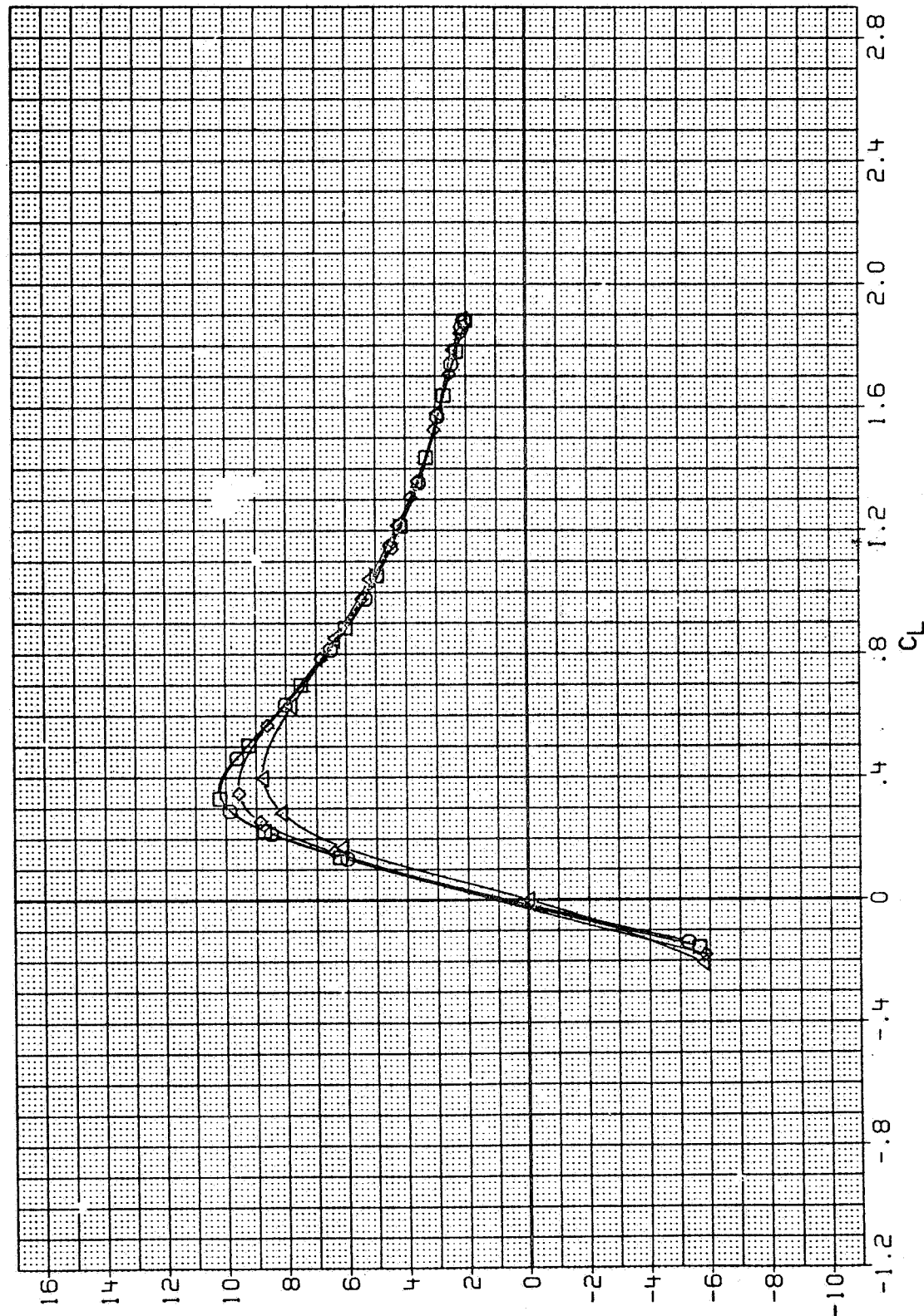


FIG. 81 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

L/D

(RALS-R104)

CONFIGURATION B2 N W2 C1 V

MACH BETA RN/L LE-C TE-C VERT

1.094 .000 9.843 .000 .000 .000

1.198 .000 .000 .000 .000 .000

1.396 .000 .000 .000 .000 .000

CANARD

SYMBOL

○ □ ◇ △

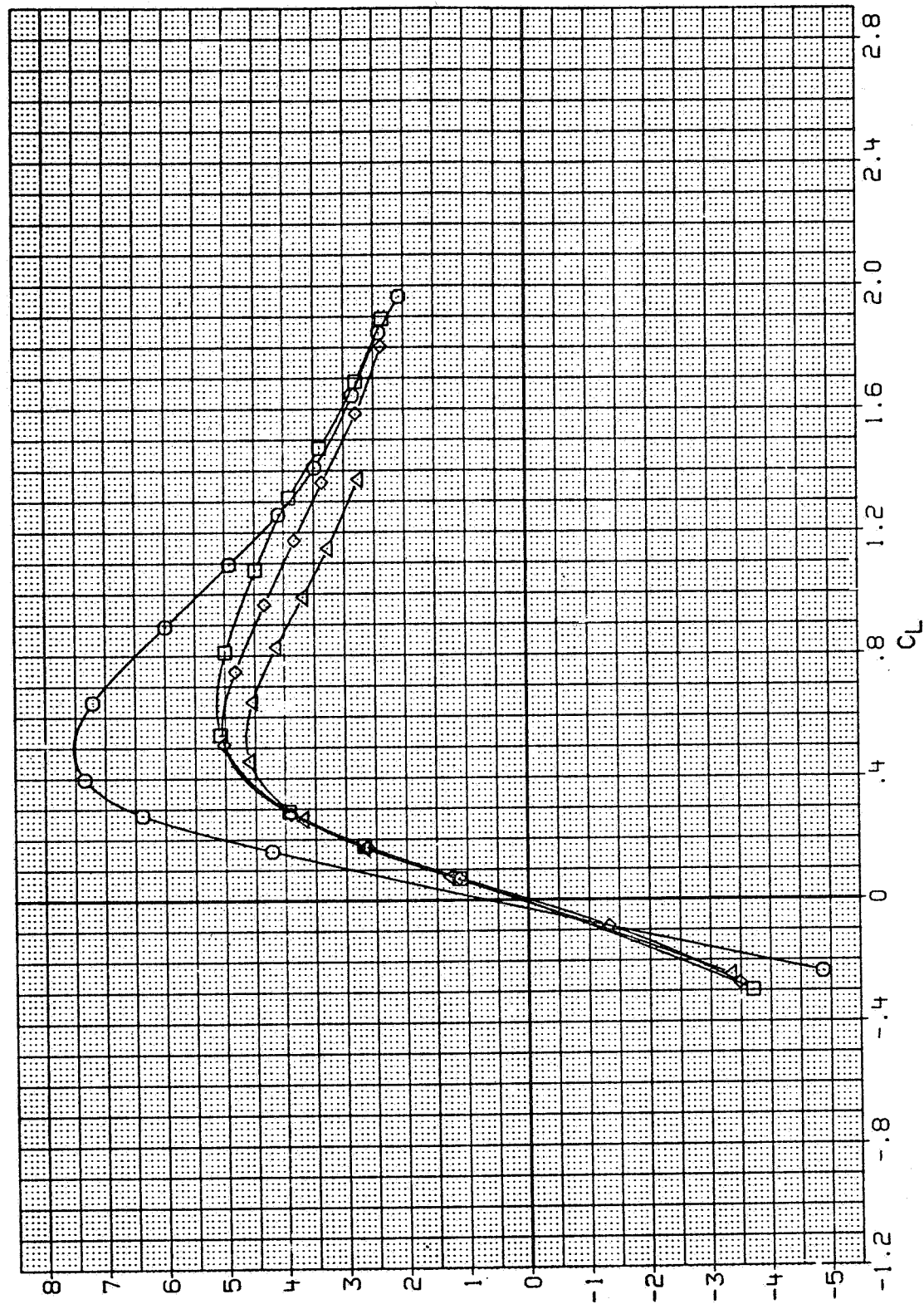


FIG. 81 BASIC LONGITUDINAL CHARACTERISTICS FOR VARIOUS MACH NUMBERS

(RALS-R104)

CONFIGURATION B2 N W2 C1 V
PARAMETRIC VALUES

BETA	.000	LE-C	.000
RN/L	9.843	TE-C	.000
LE-W	.000	VERT	.000
TE-W	.000		
CANARD	.000		

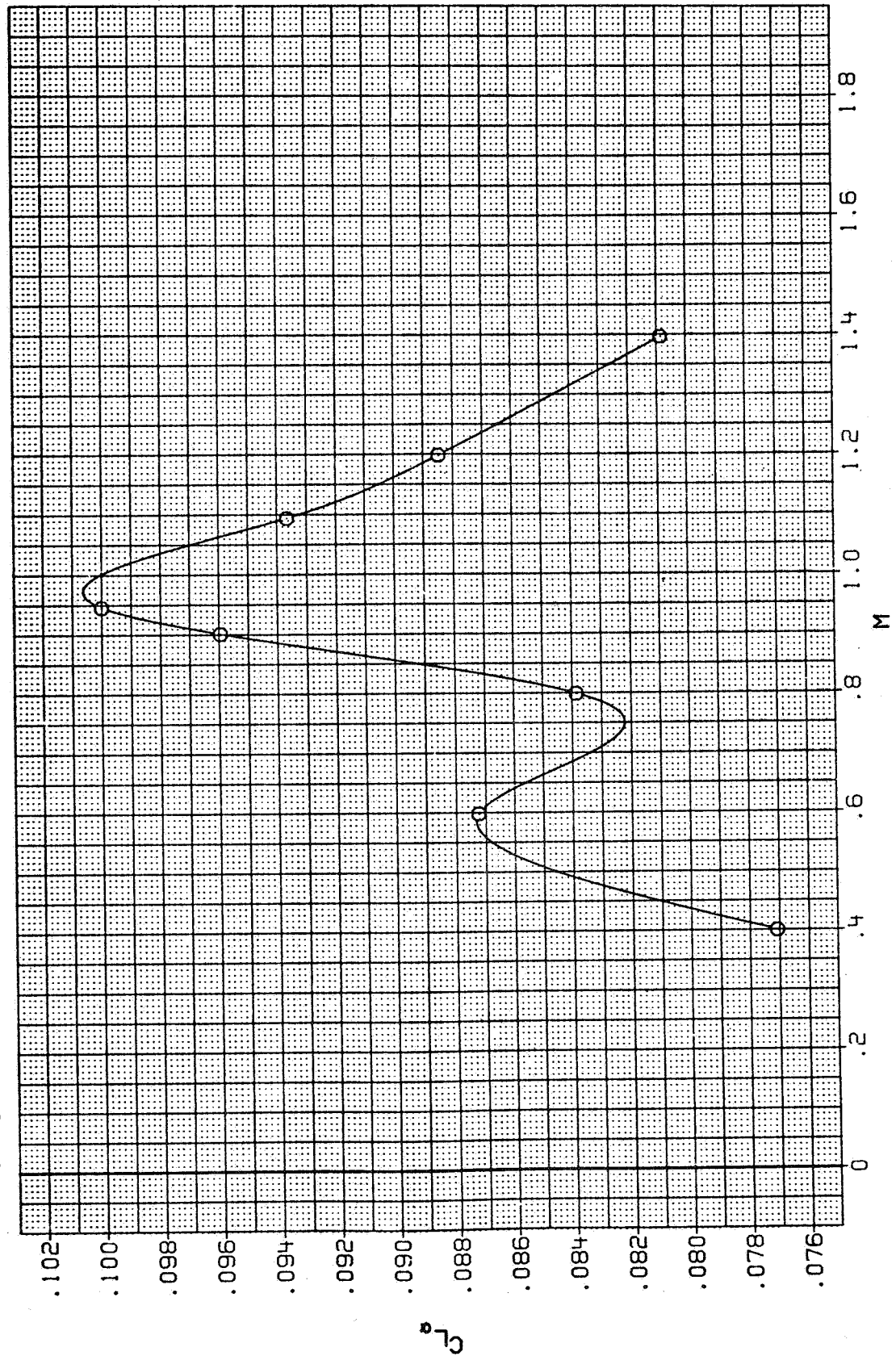


FIG. 82 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

358

(RALS-R104)

CONFIGURATION B2 N W2 C1 V

PARAMETRIC VALUES

BETA	.000	LE-C	.000
RN/L	9.843	TE-C	.000
LE-W	.000	VERT	.000
TE-W	.000		
CANARD	.000		

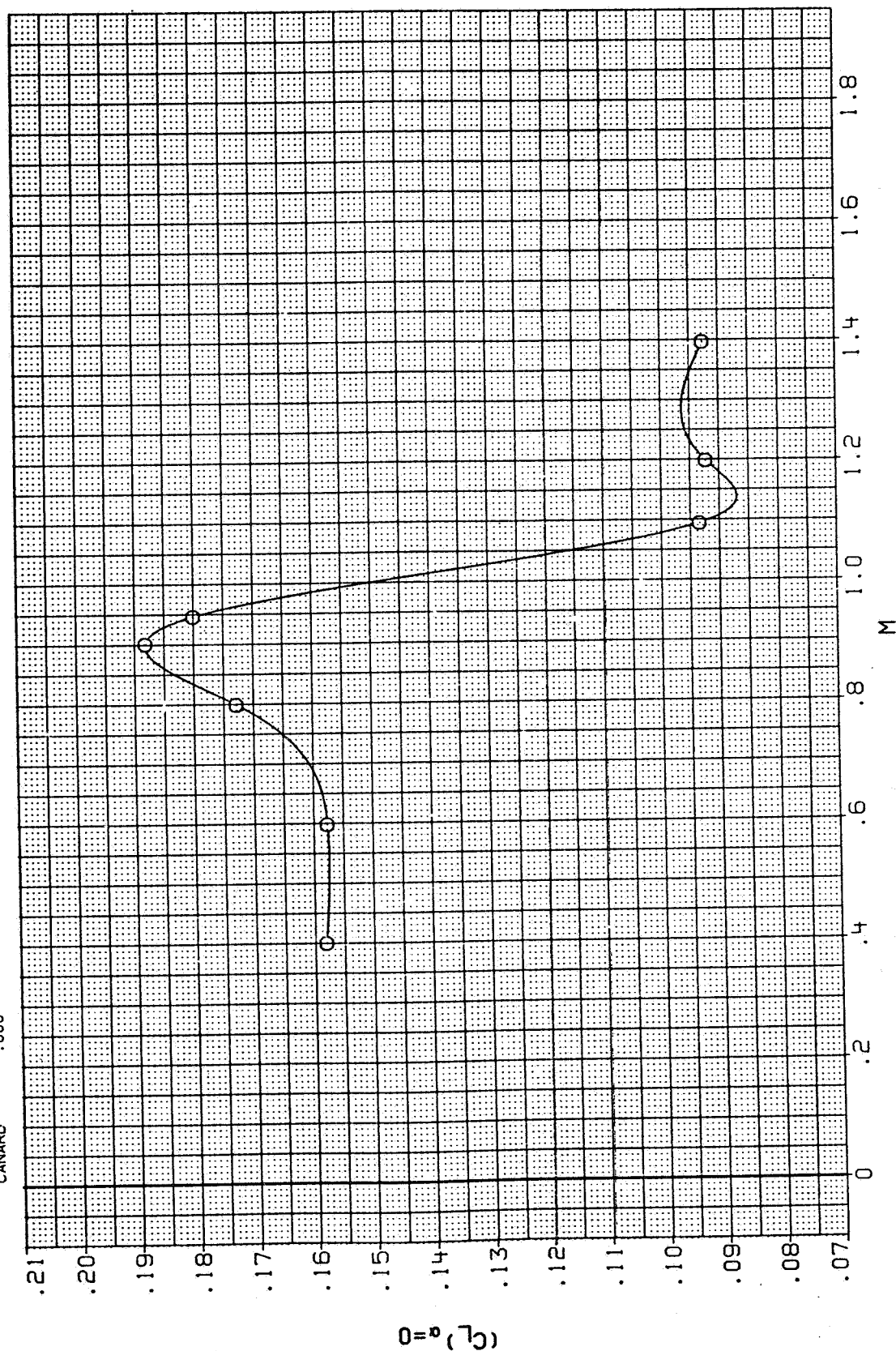


FIG. 82 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

(RALS-R104)

CONFIGURATION B2 N W2 C1 V
PARAMETRIC VALUES

BETA .000
RN/L 9.843
LE-W .000
TE-W .000
CANARO .000

LE-C .000
TE-C .000
VERT .000

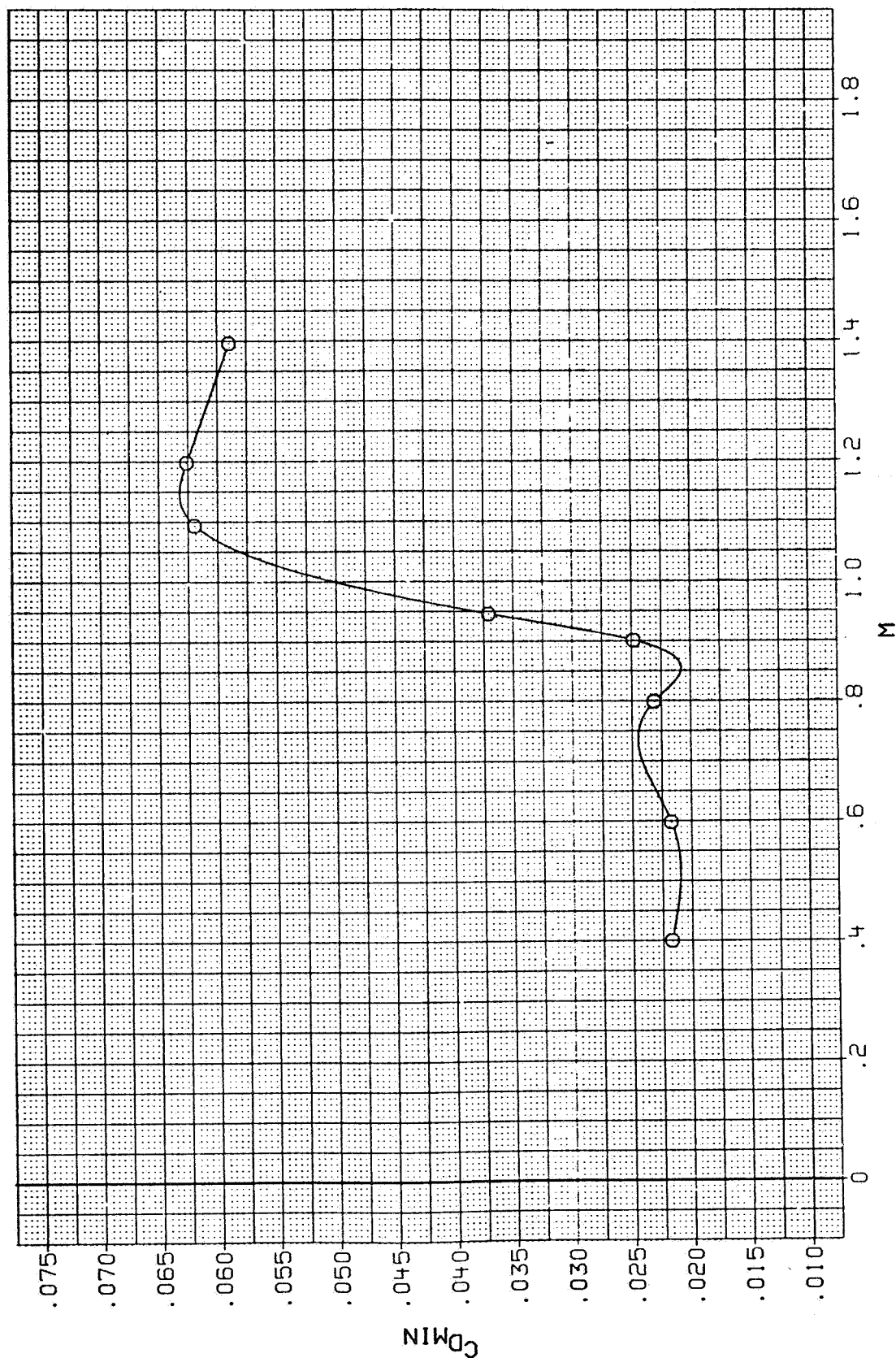


FIG. 82 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

(RALS-R104)

CONFIGURATION B2 N W2 C1 V

PARAMETRIC VALUES

BETA	.000	LE-C	.000
RN/L	9.843	TE-C	.000
LE-W	.000	VERT	.000
TE-W	.000		
CANARD	.000		

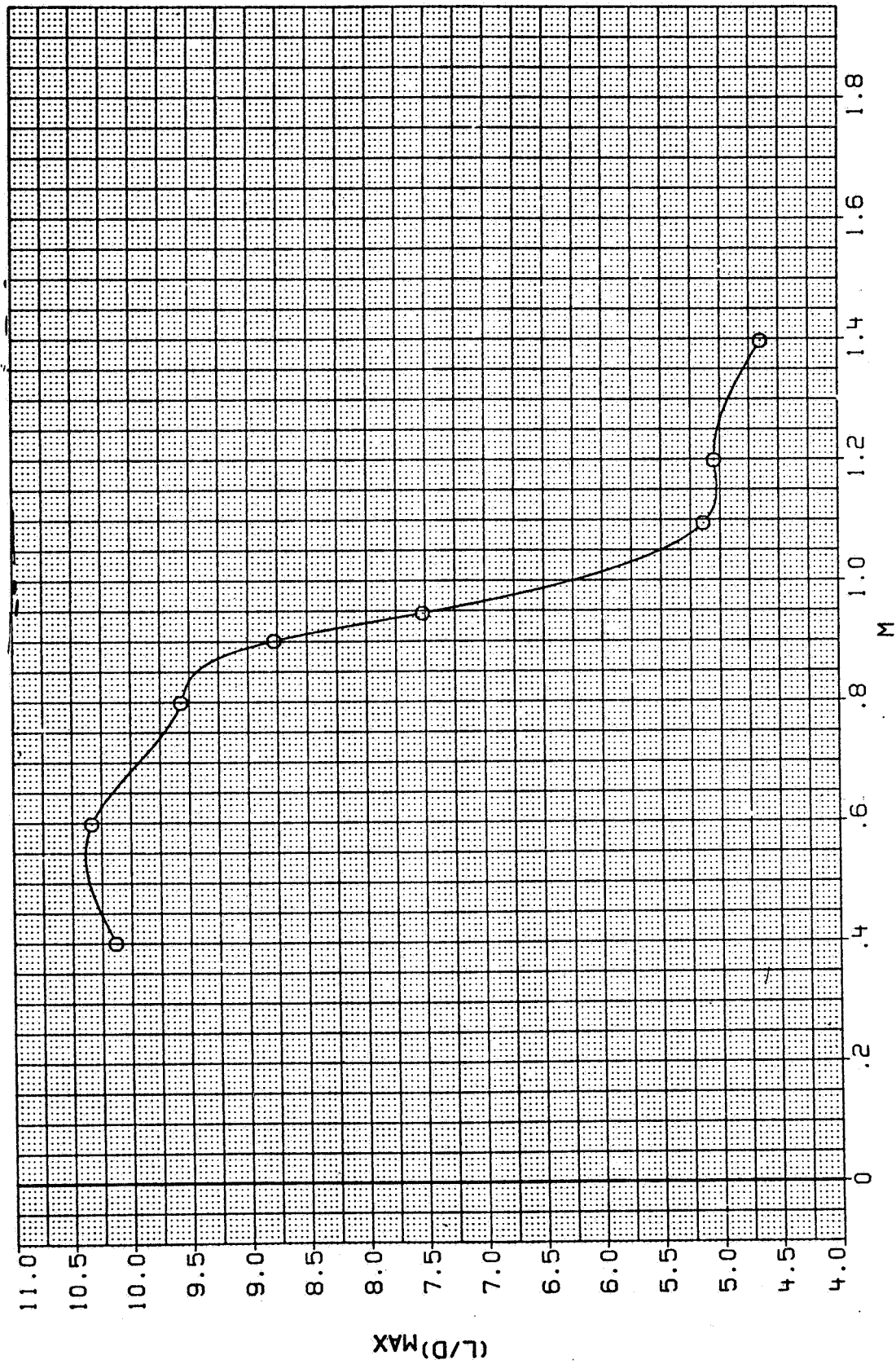


FIG. 82 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

(RALS-R104)

CONFIGURATION B2 N W2 C1 V
PARAMETRIC VALUES

BETA	.000	LE-C	.000
RN/L	9.843	TE-C	.000
LE-W	.000	VERT	.000
TE-W	.000		
CANARD	.000		

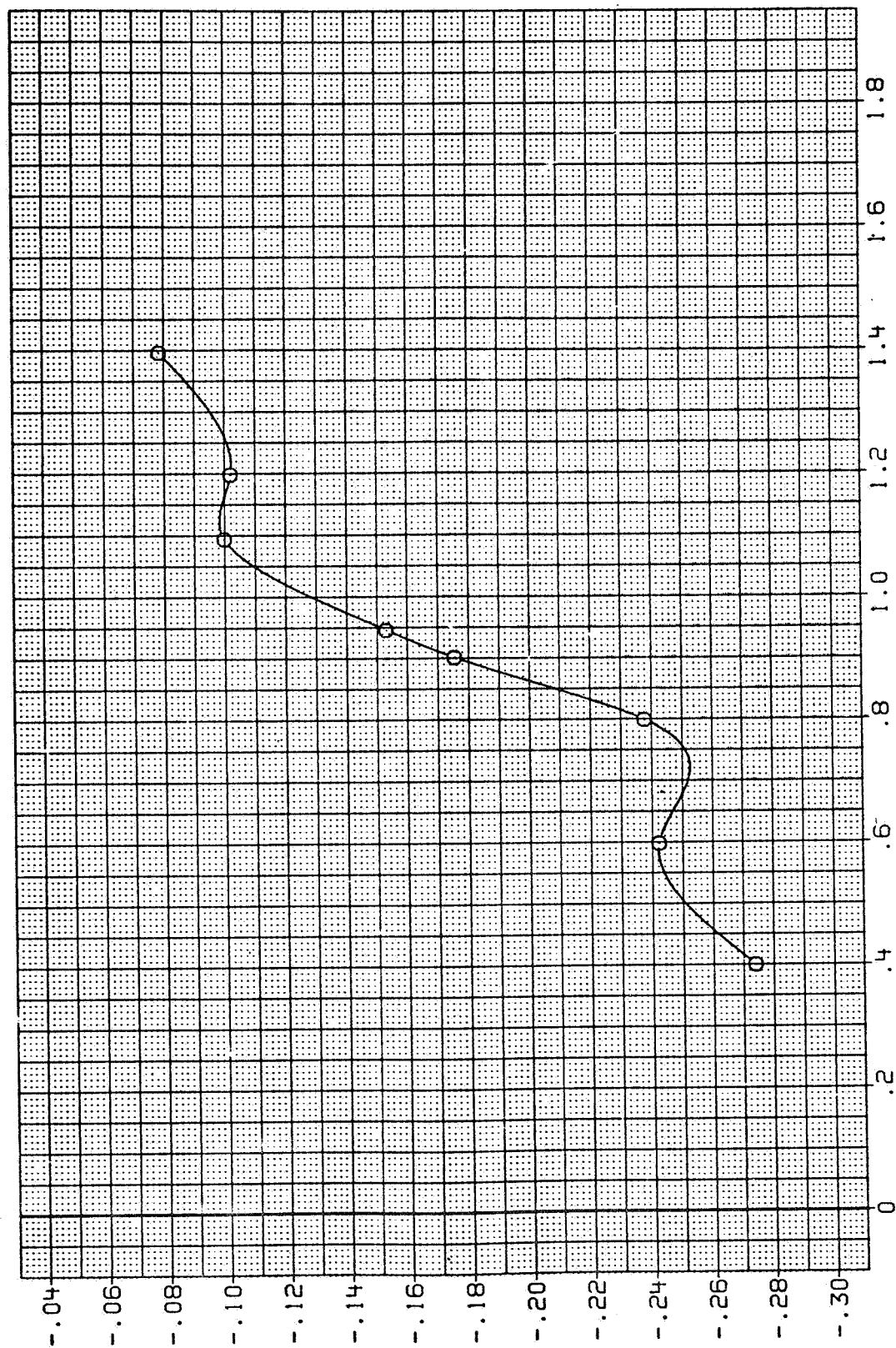


FIG. 82 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

(RALS-R104)

CONFIGURATION B2 N W2 C1 V

PARAMETRIC VALUES

BETA	.000	LE-C	.000
RN/L	9.843	TE-C	.000
LE-H	.000	VERT	.000
TE-H	.000		
CANARD	.000		

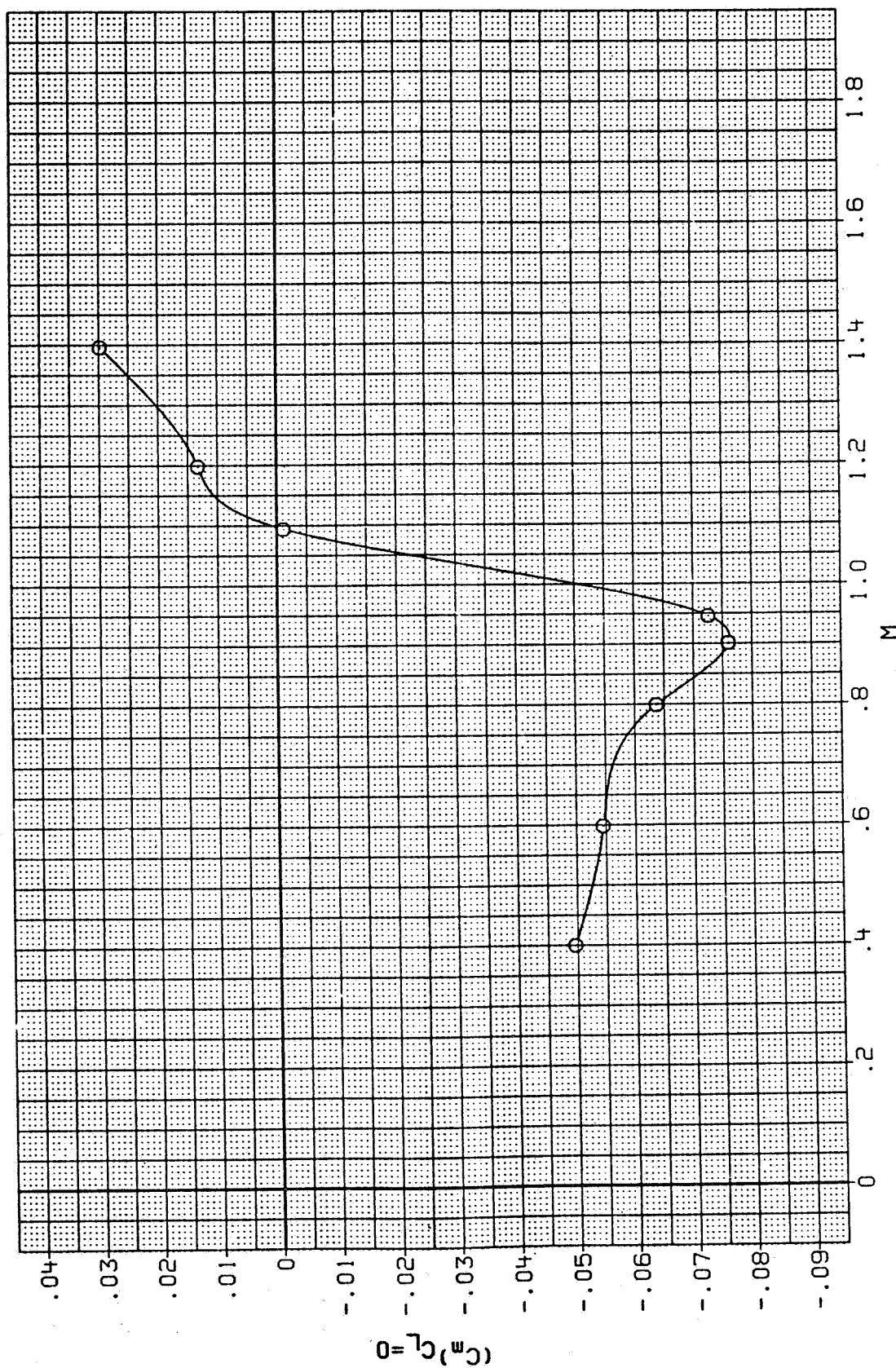


FIG. 82 SUMMARY OF BASIC LONGITUDINAL CHARACTERISTICS WITH MACH NUMBER

SYMBOL CONFIGURATION
 □ B2 N V
 ◇ B2 N M2 V
 △ B2 N C1 V
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

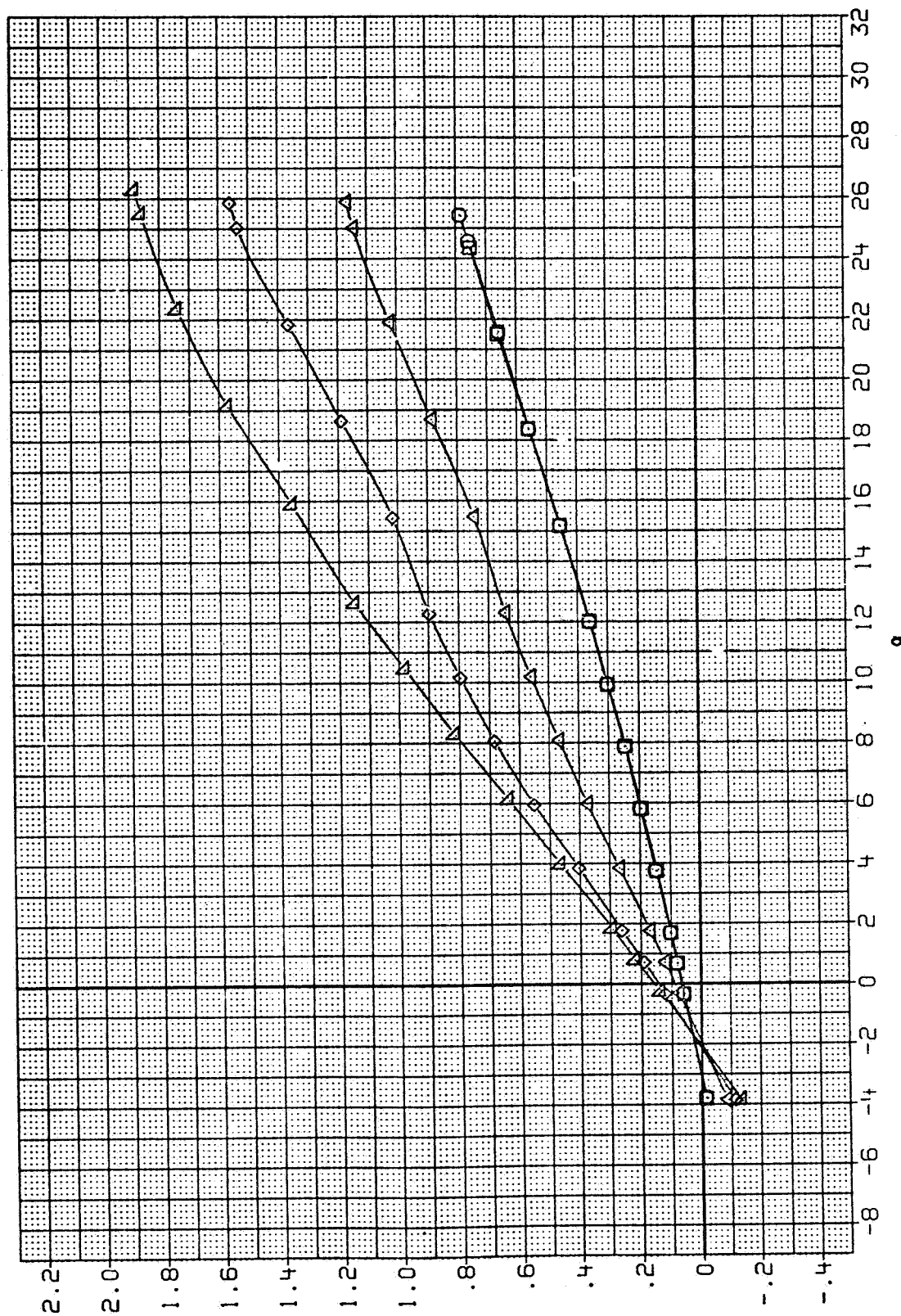


FIG. 83 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .40

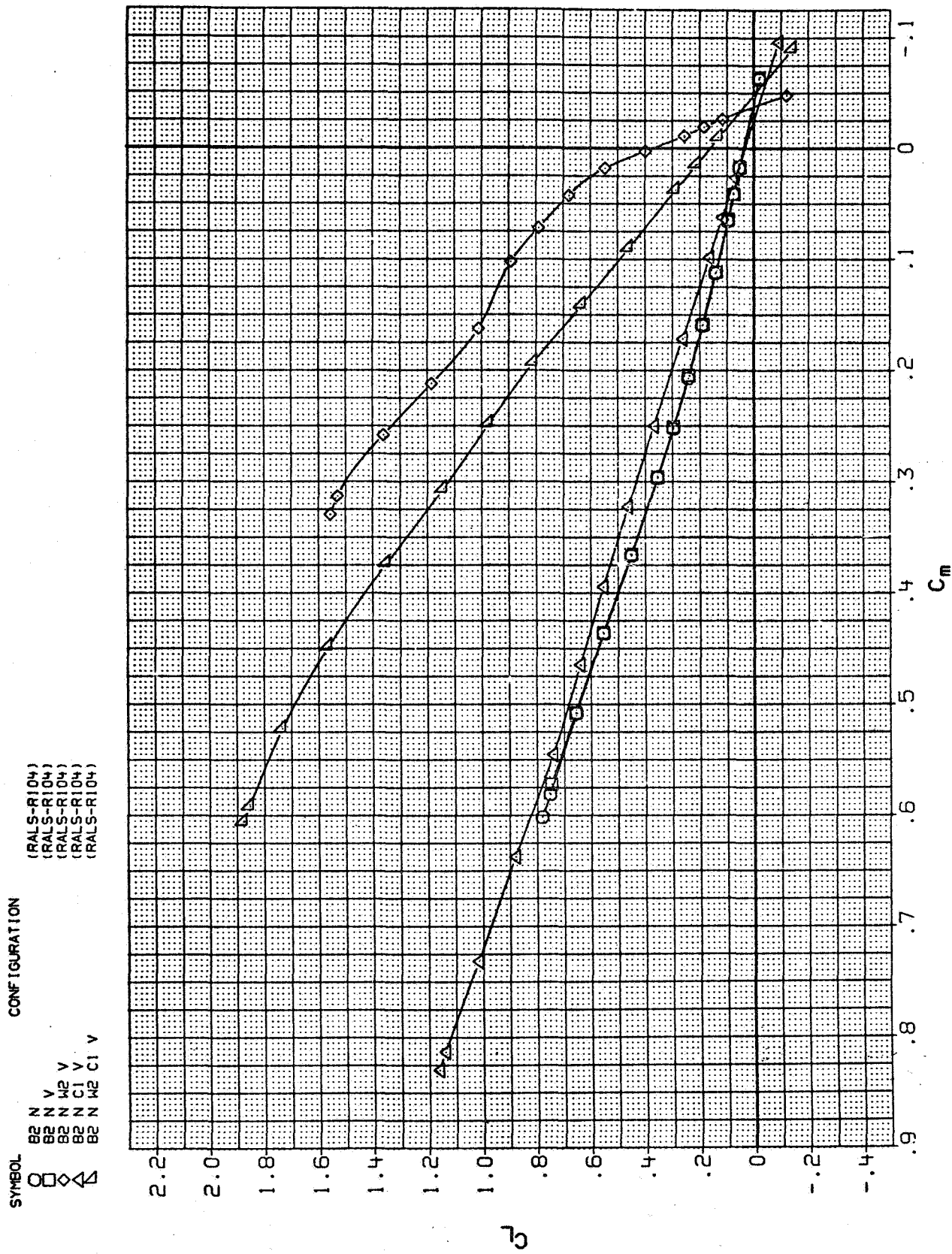


FIG. 83 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .40

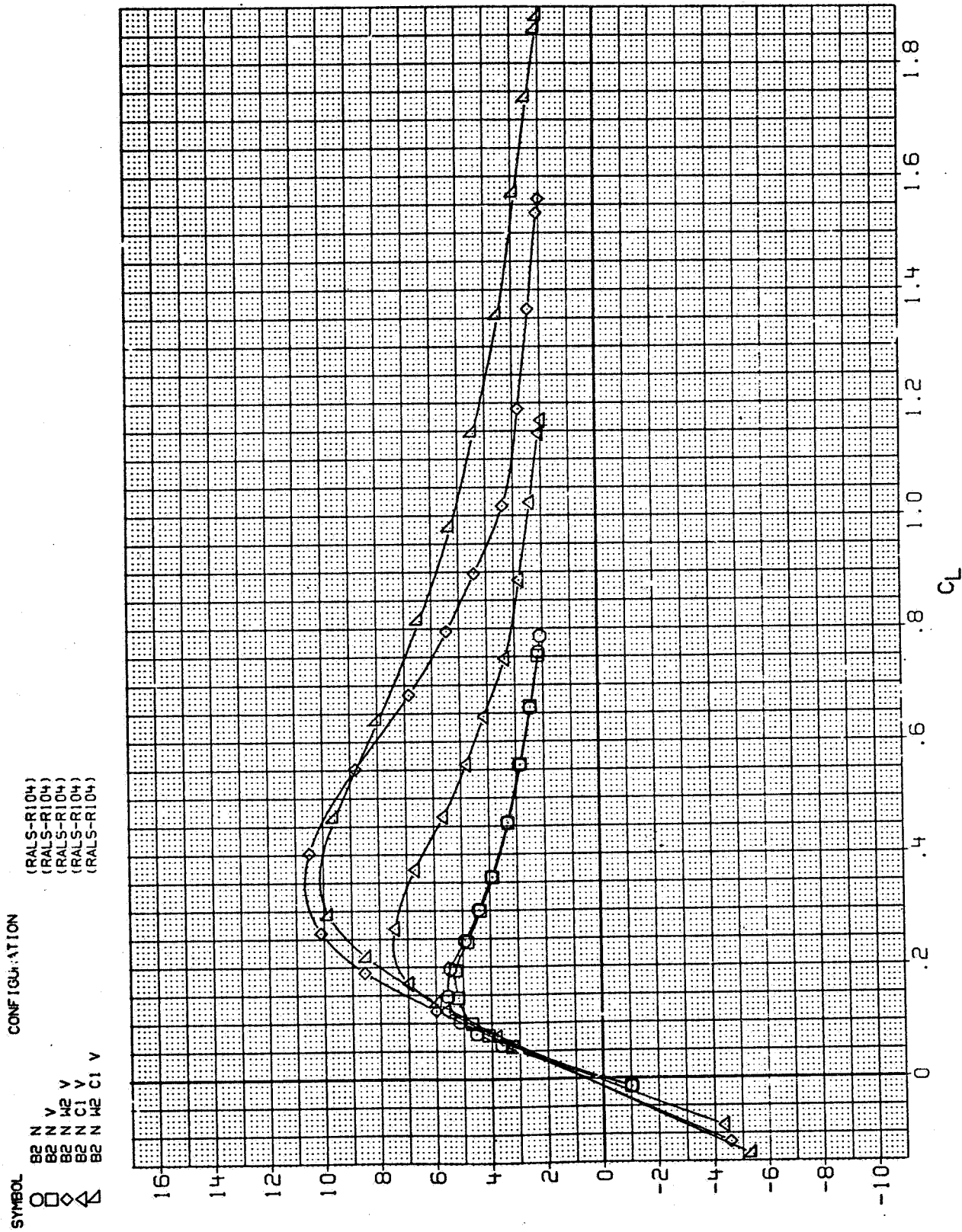


FIG. 83 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .40

0/1

SYMBOL	CONFIGURATION
□	B2 N V
◇	B2 N W2 V
△	B2 N C1 V
▽	B2 N W2 C1 V
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)

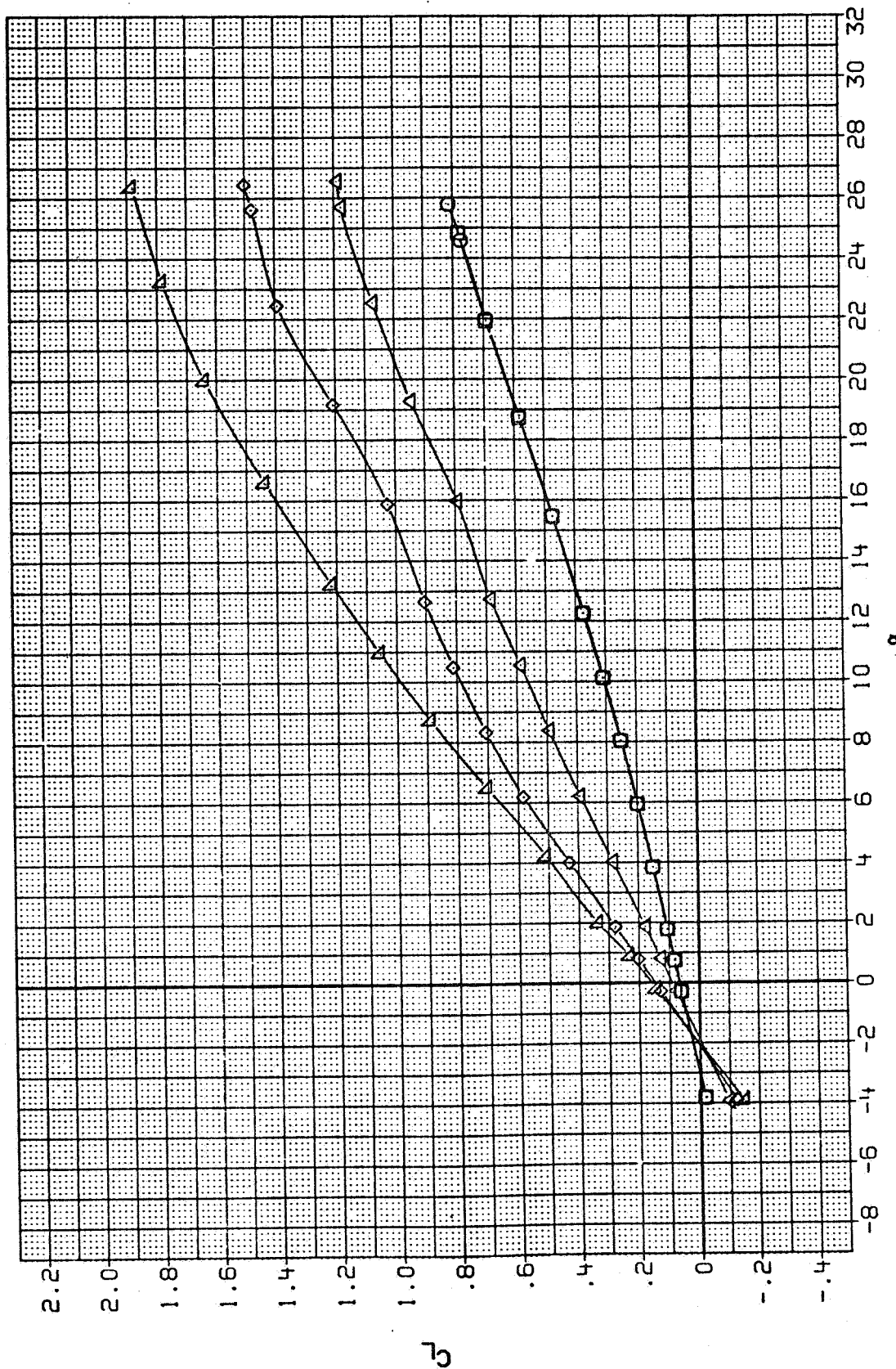


FIG. 84 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL CONFIGURATION
 □ B2 N V
 ◇ B2 N M2 V
 △ B2 N C1 V
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

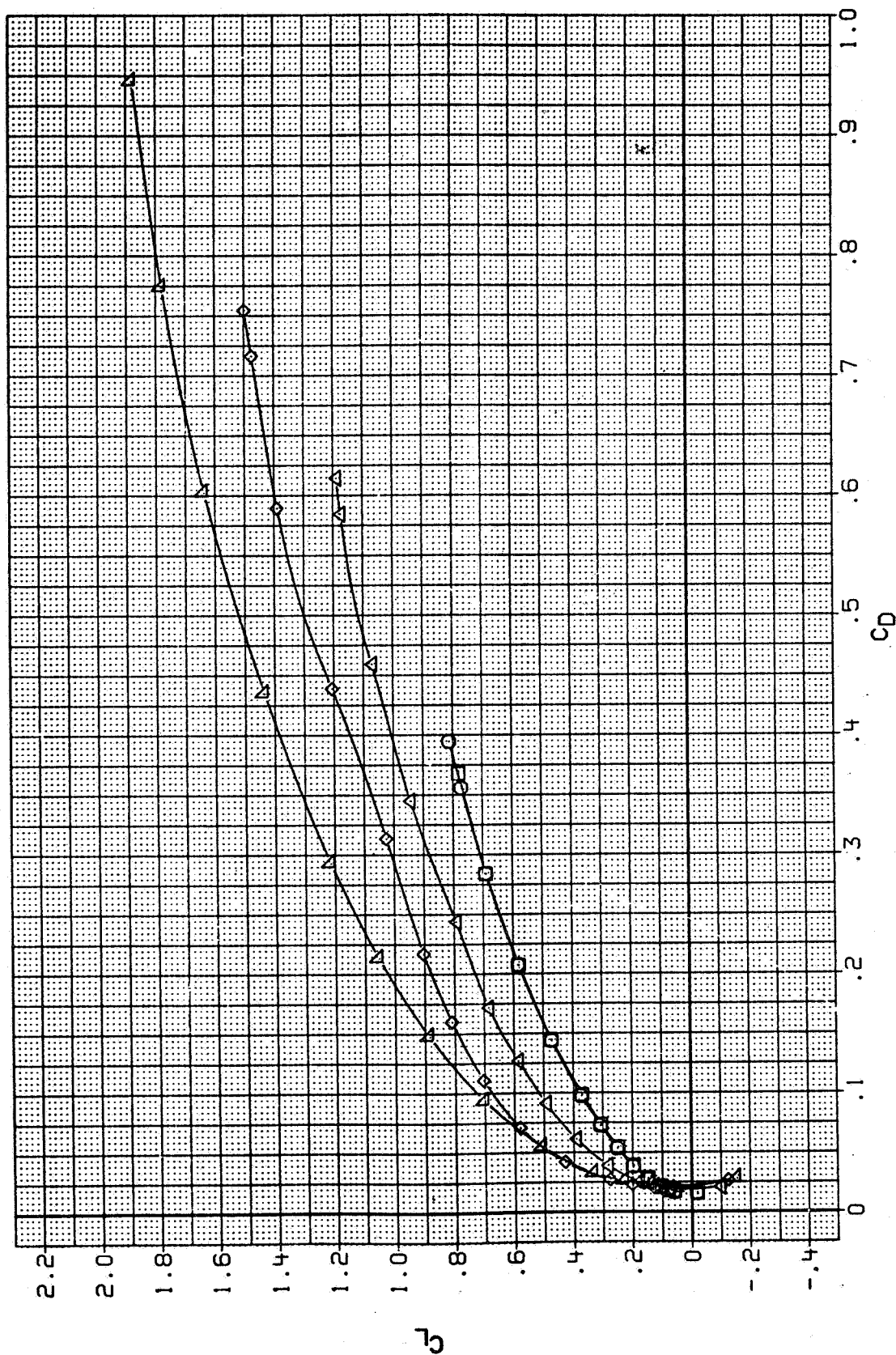


FIG. 84 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .60

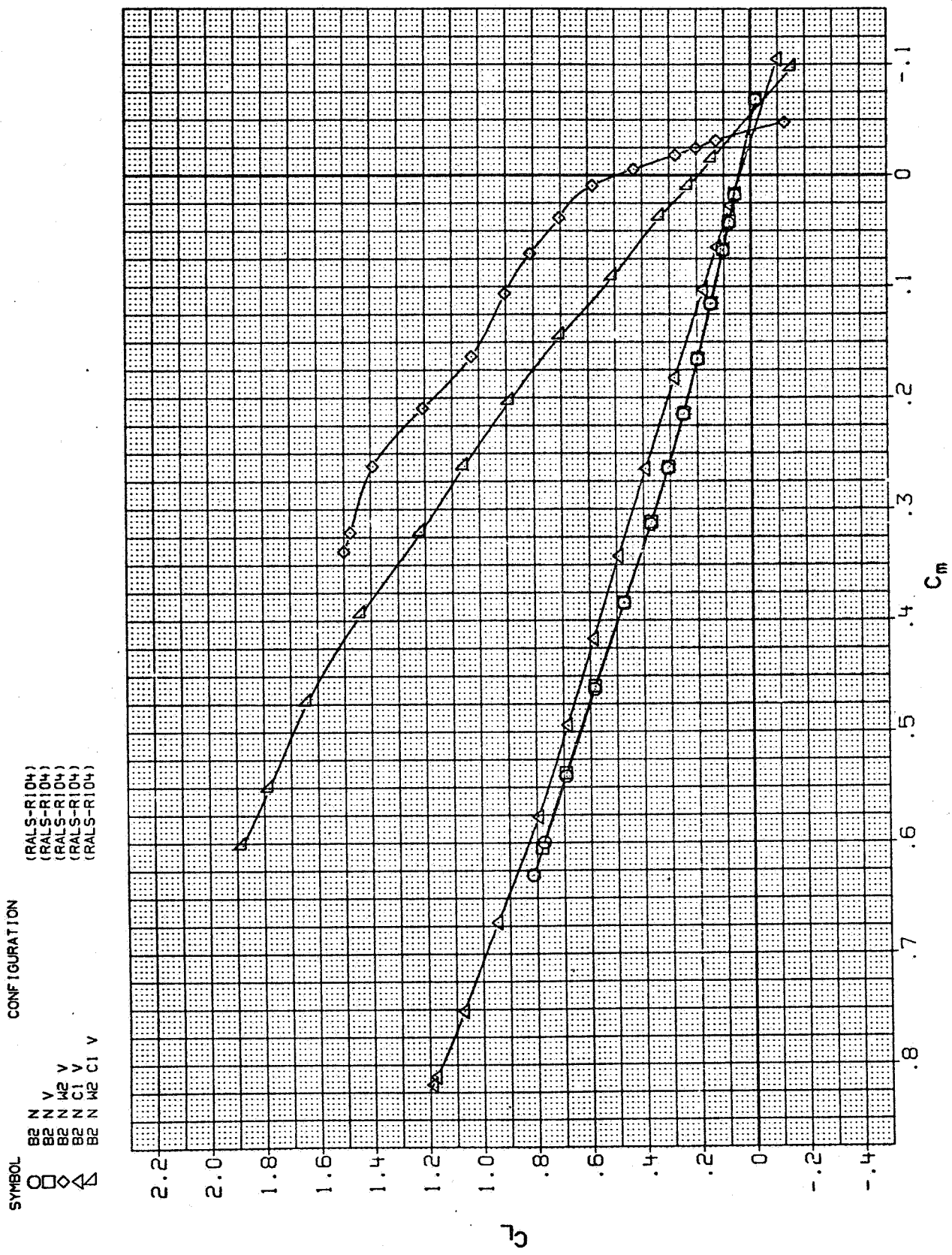


FIG. 84 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL	CONFIGURATION
□	B2 N V
◇	B2 N W2 V
△	B2 N C1 V
	B2 N W2 C1 V
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)

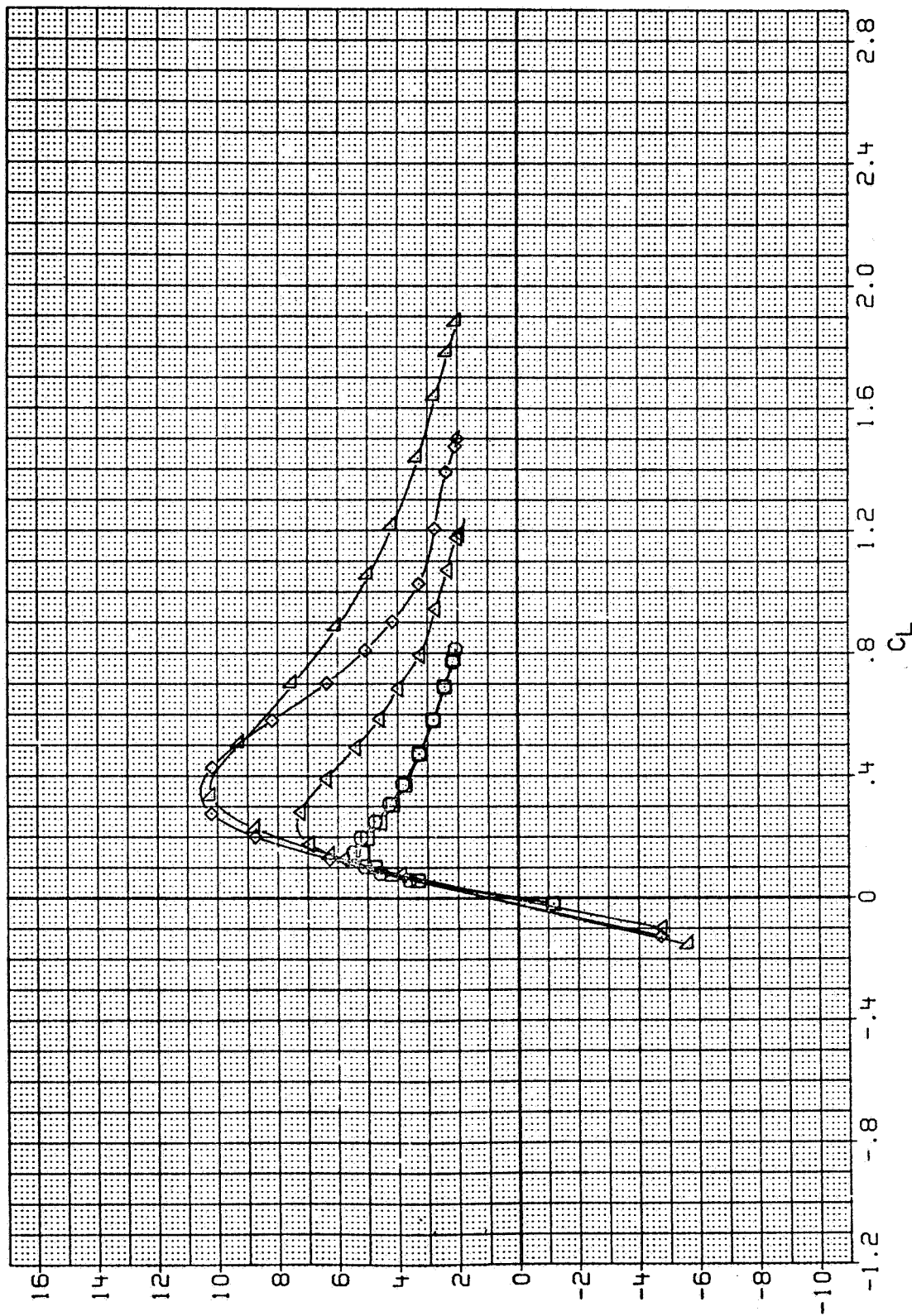


FIG. 84 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .60

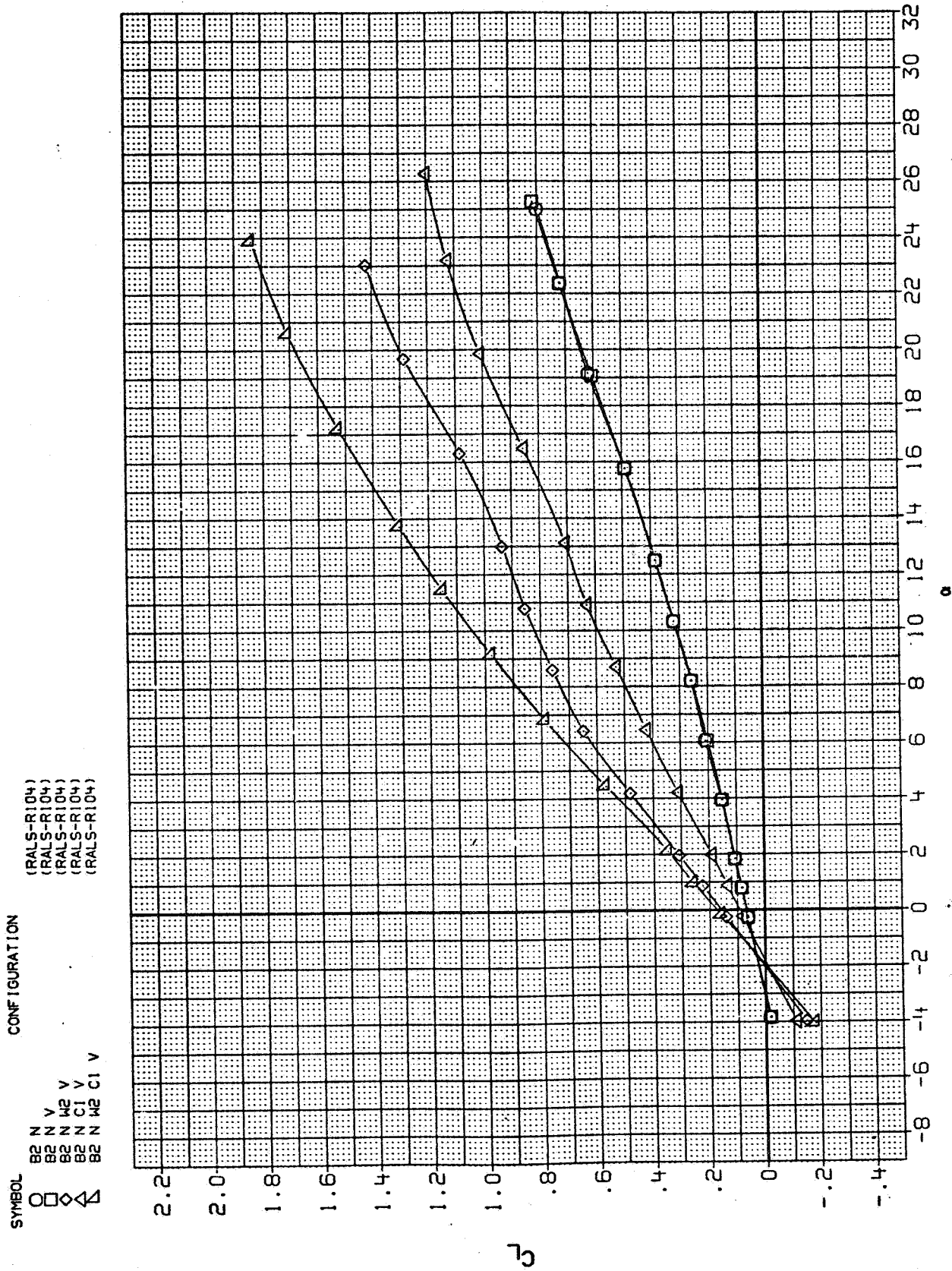


FIG. 85 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .80

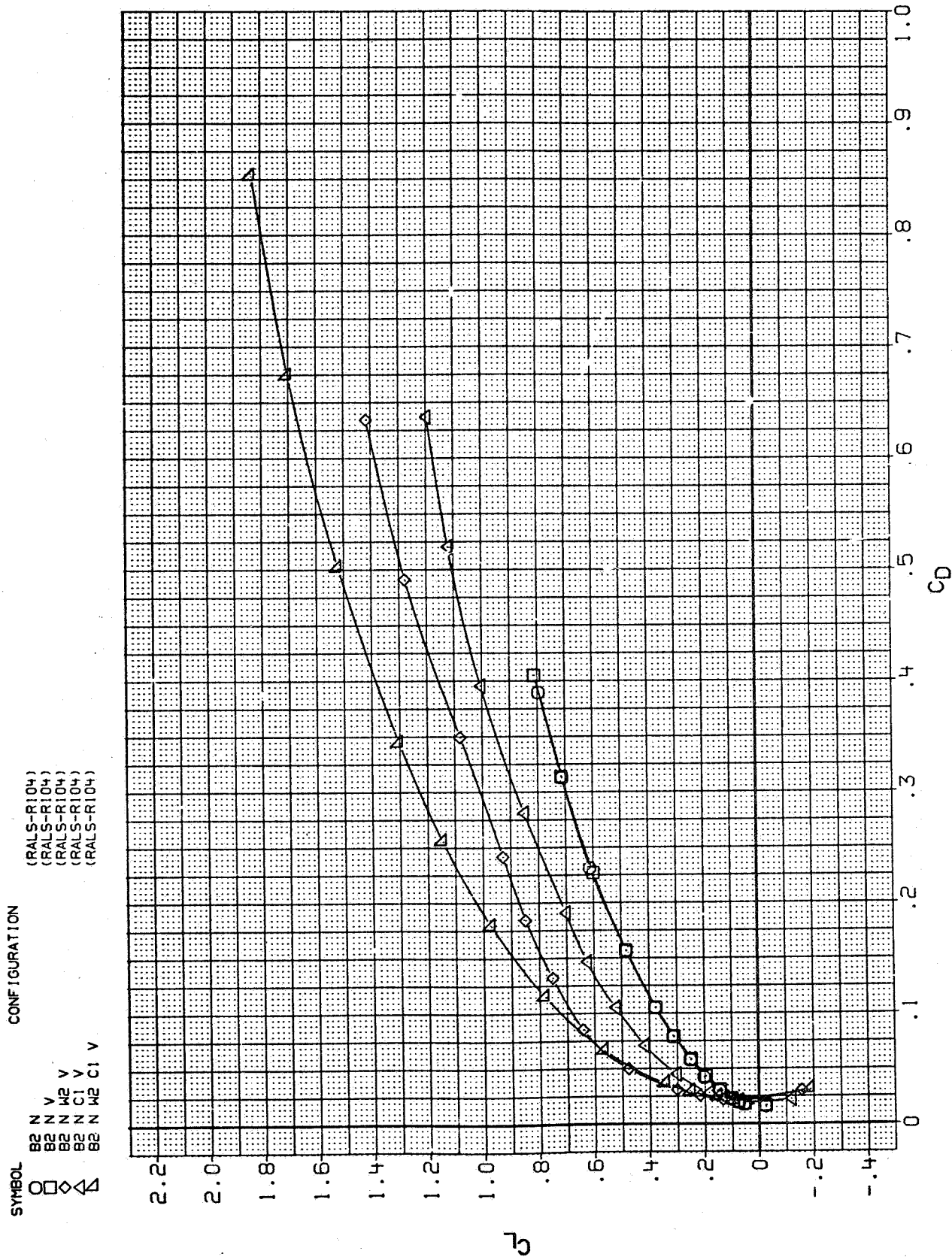


FIG. 85 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .80

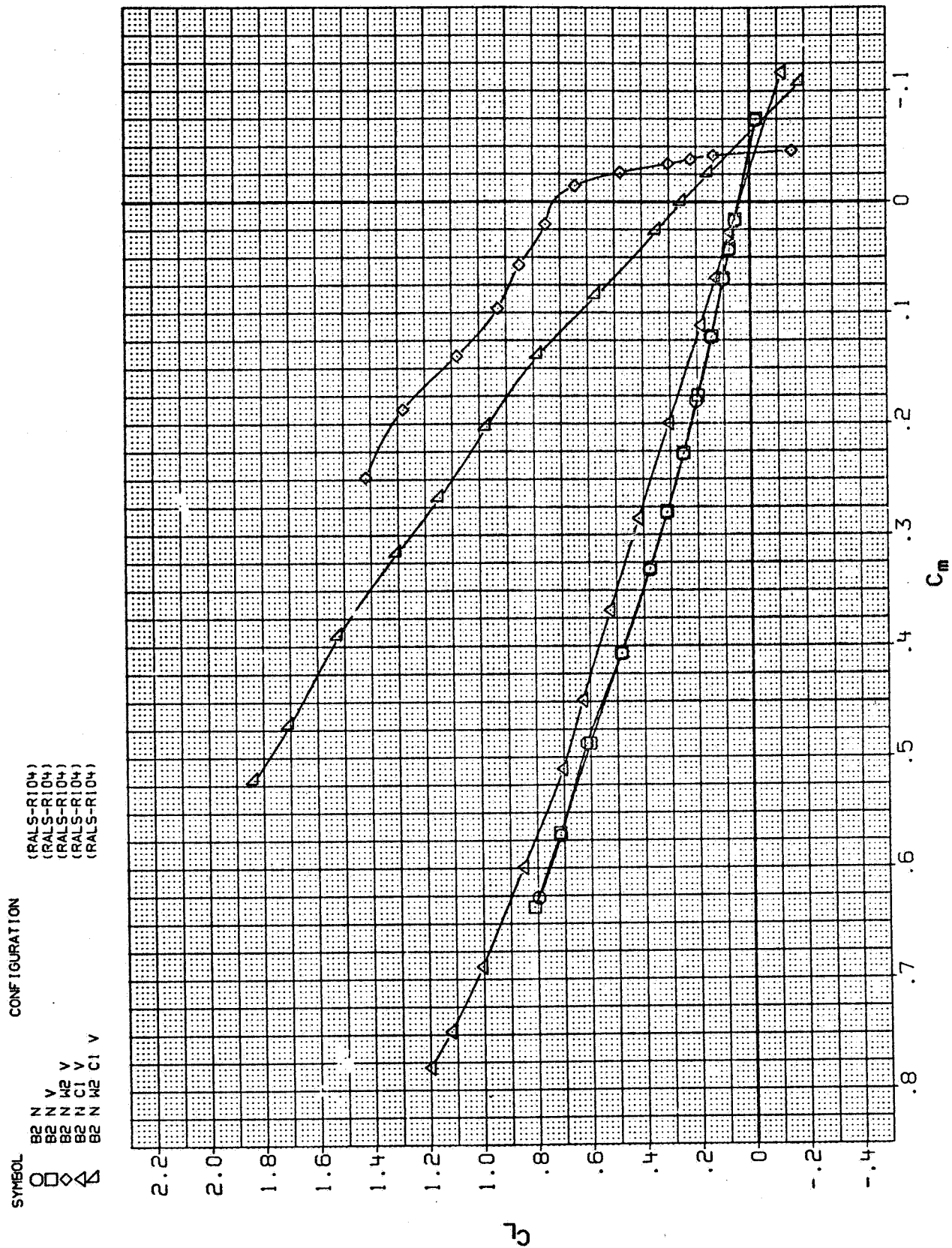


FIG. 85 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .80

SYMBOL CONFIGURATION
 ○ B2 N V
 □ B2 N M2 V
 ◇ B2 N C1 V
 △ B2 N M2 C1 V
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

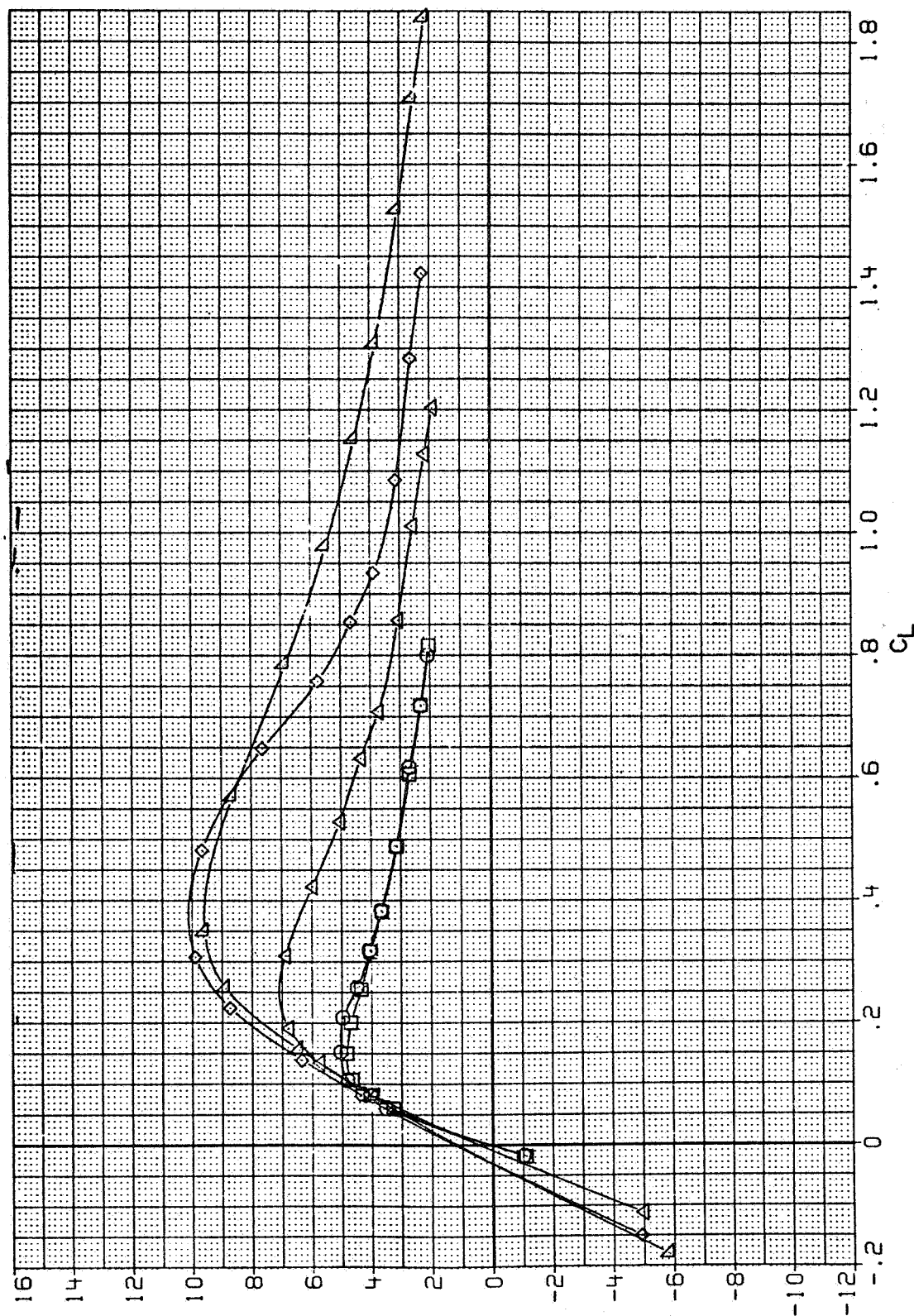


FIG. 85 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .80

SYMBOL CONFIGURATION
 ○ B2 N V
 ◇ B2 N W2 V
 △ B2 N C1 V
 B2 N W2 C1 V
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

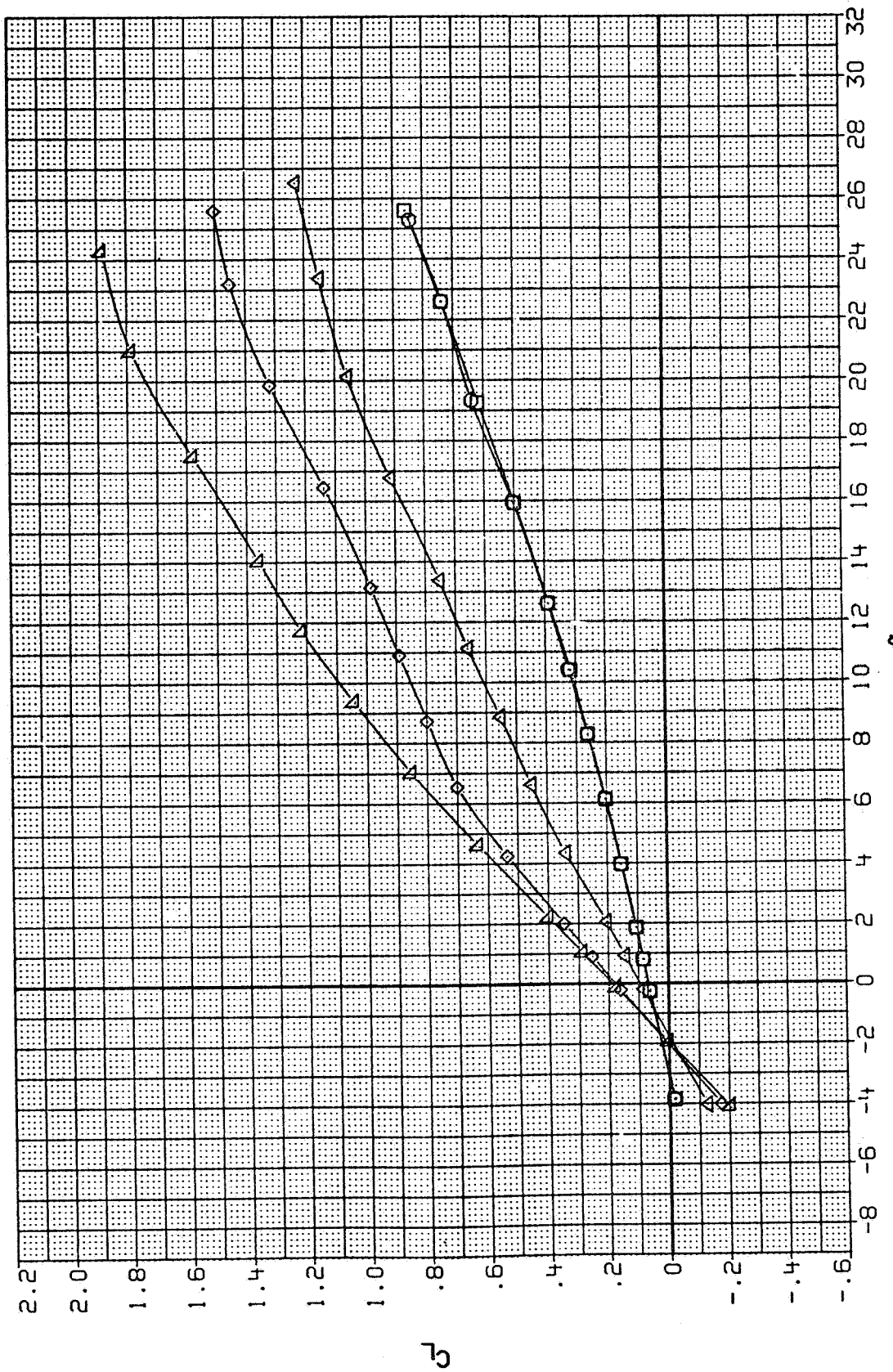


FIG. 86 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL CONFIGURATION

B2 N V (RALS-R104)
 B2 N W2 V (RALS-R104)
 B2 N C1 V (RALS-R104)
 B2 N W2 C1 V (RALS-R104)

□
 ◇
 △

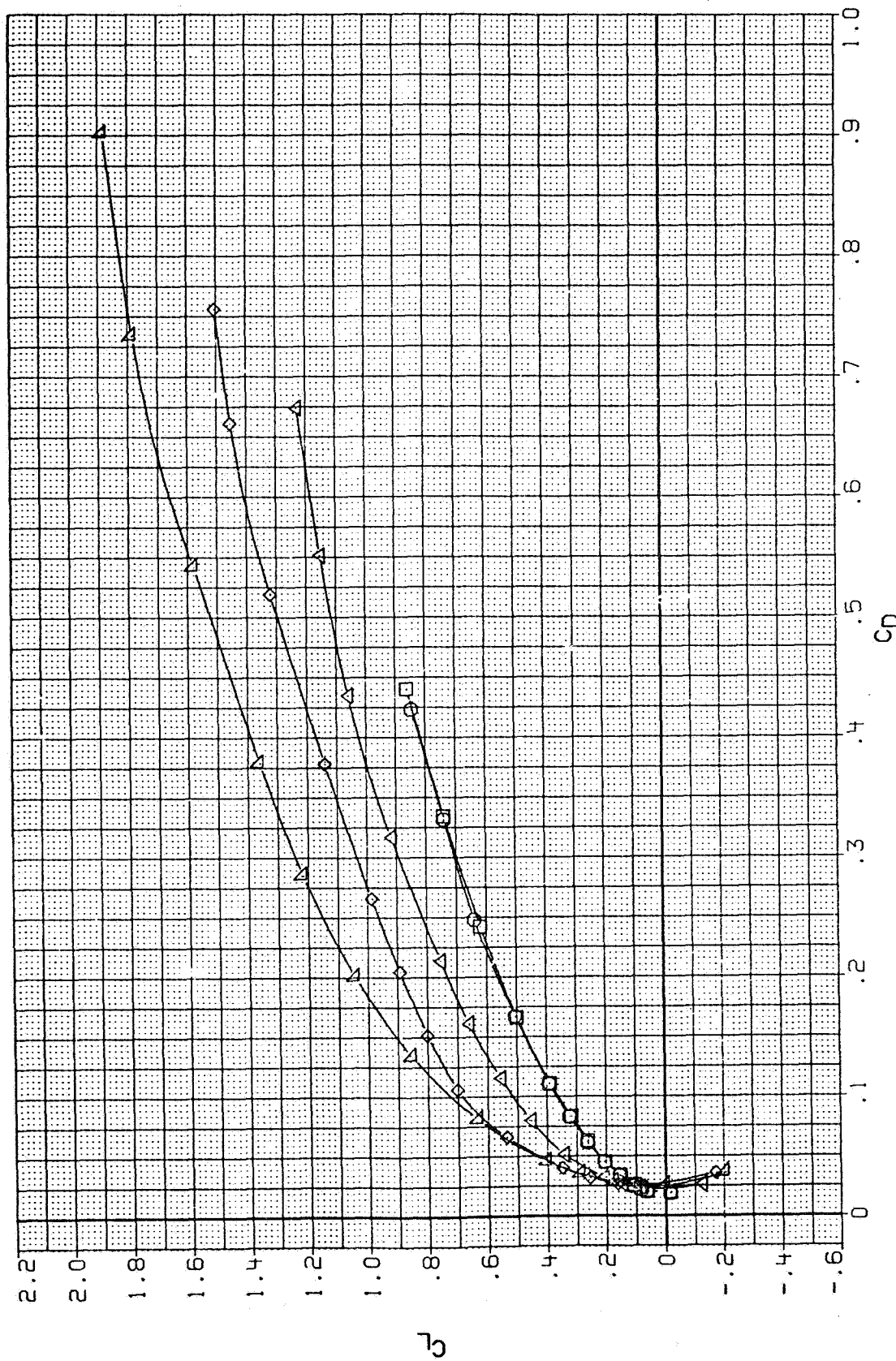


FIG. 86 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL	CONFIGURATION
□	B2 N (RALS-R104)
◇	B2 N V (RALS-R104)
△	B2 N M2 V (RALS-R104)
▽	B2 N C1 V (RALS-R104)
◻	B2 N M2 C1 V (RALS-R104)

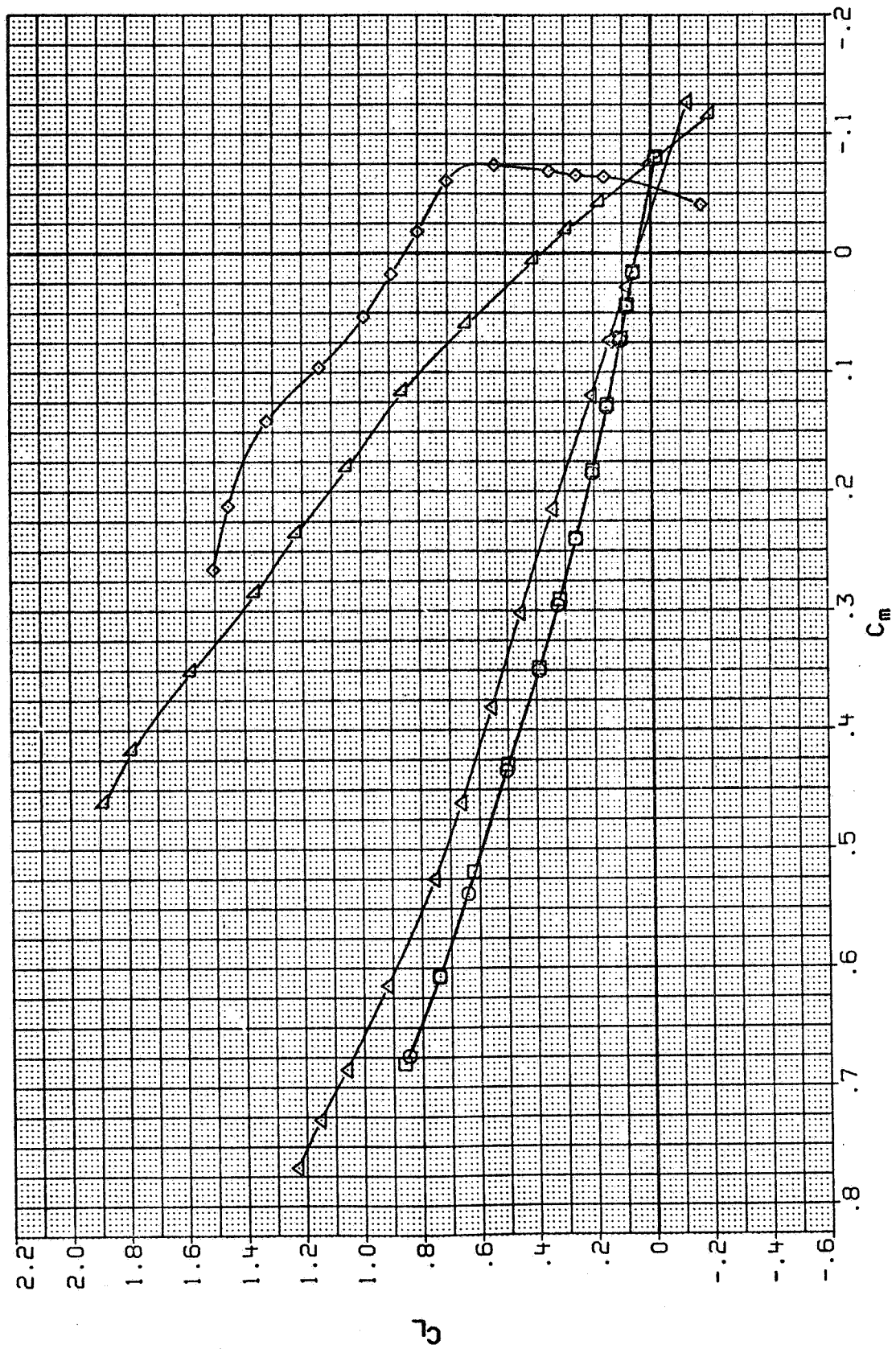


FIG. 86 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 0.90

SYMBOL	CONFIGURATION
□	B2 N V (RALS-R104)
◇	B2 N W2 V (RALS-R104)
△	B2 N C1 V (RALS-R104)
△	B2 N W2 C1 V (RALS-R104)

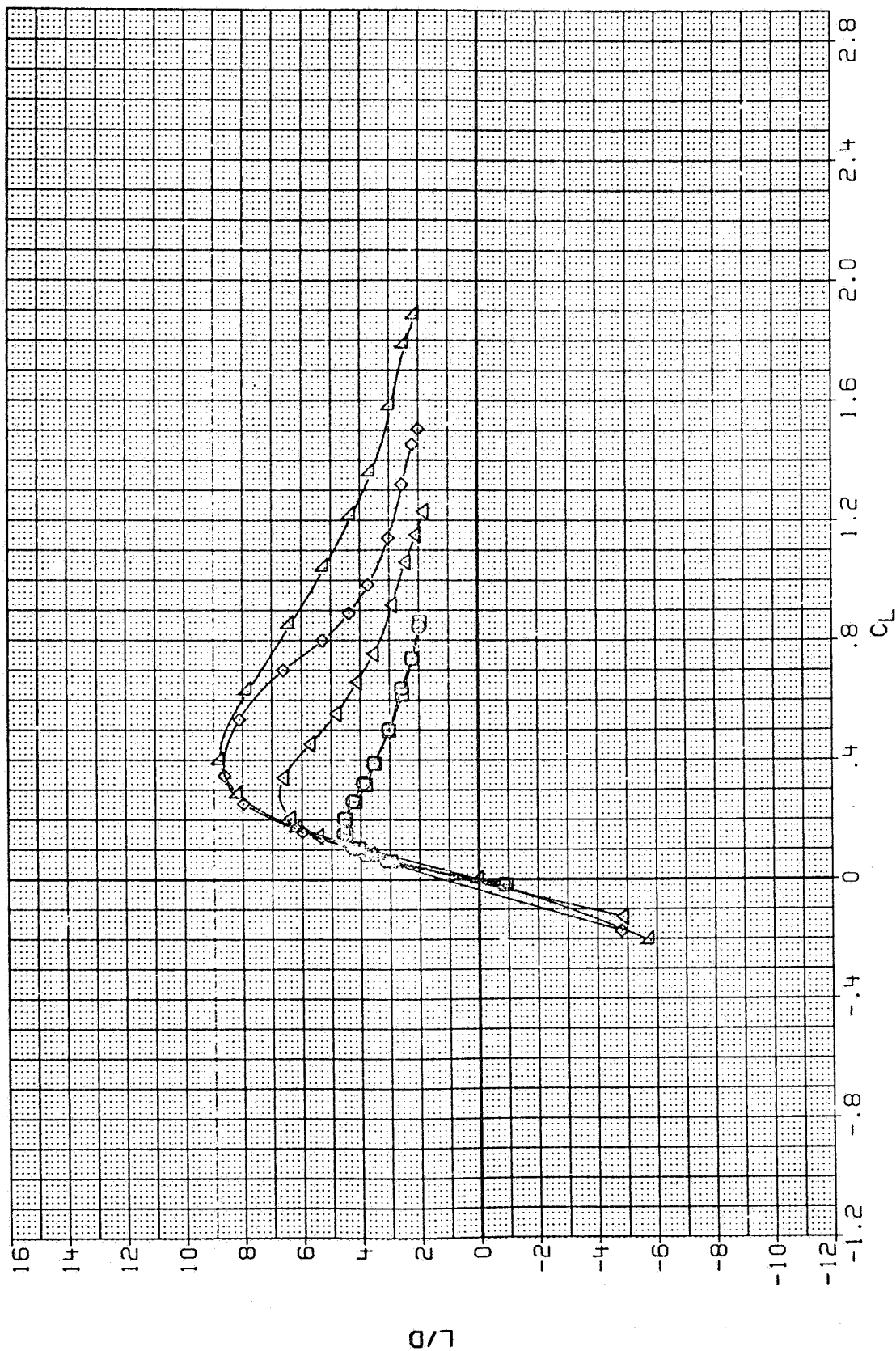


FIG. 86 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .90

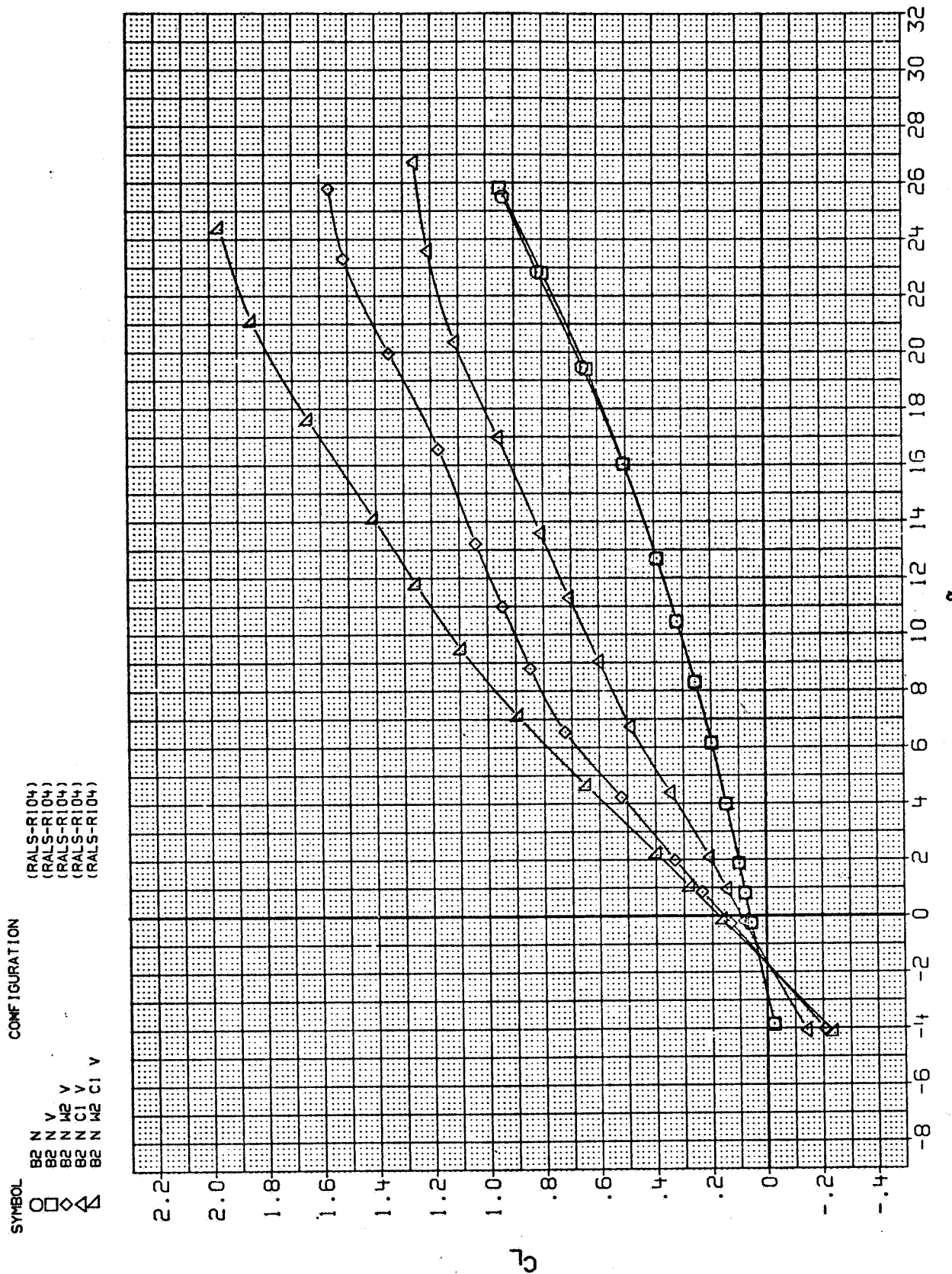


FIG. 87 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .95

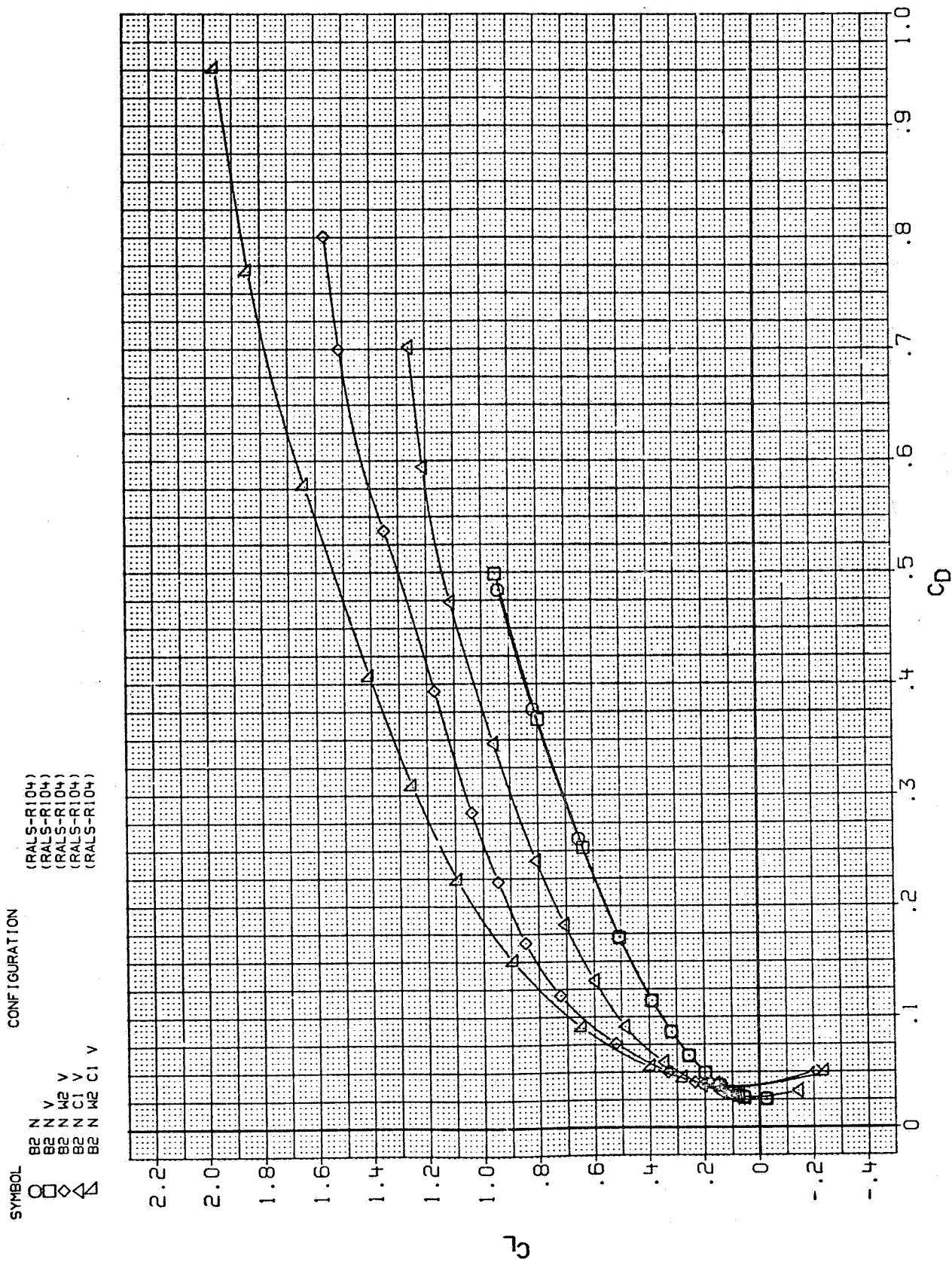


FIG. 87 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .95

SYMBOL	CONFIGURATION
□	B2 N V
◇	B2 N W2 V
△	B2 N C1 V
	B2 N W2 C1 V
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)

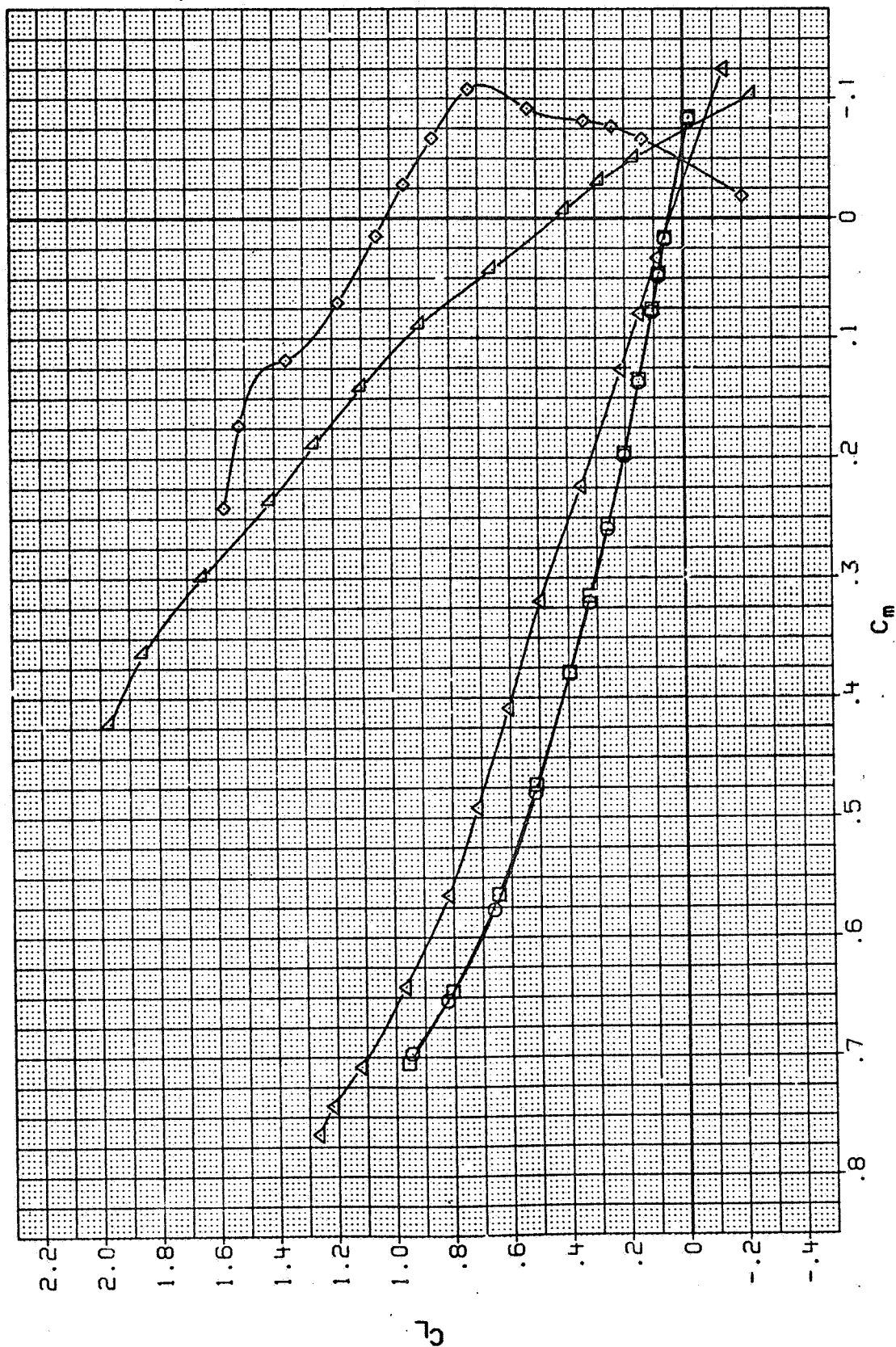


FIG. 87 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .95

SYMBOL CONFIGURATION
 □ B2 N V
 ◇ B2 N W2 V
 △ B2 N C1 V
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

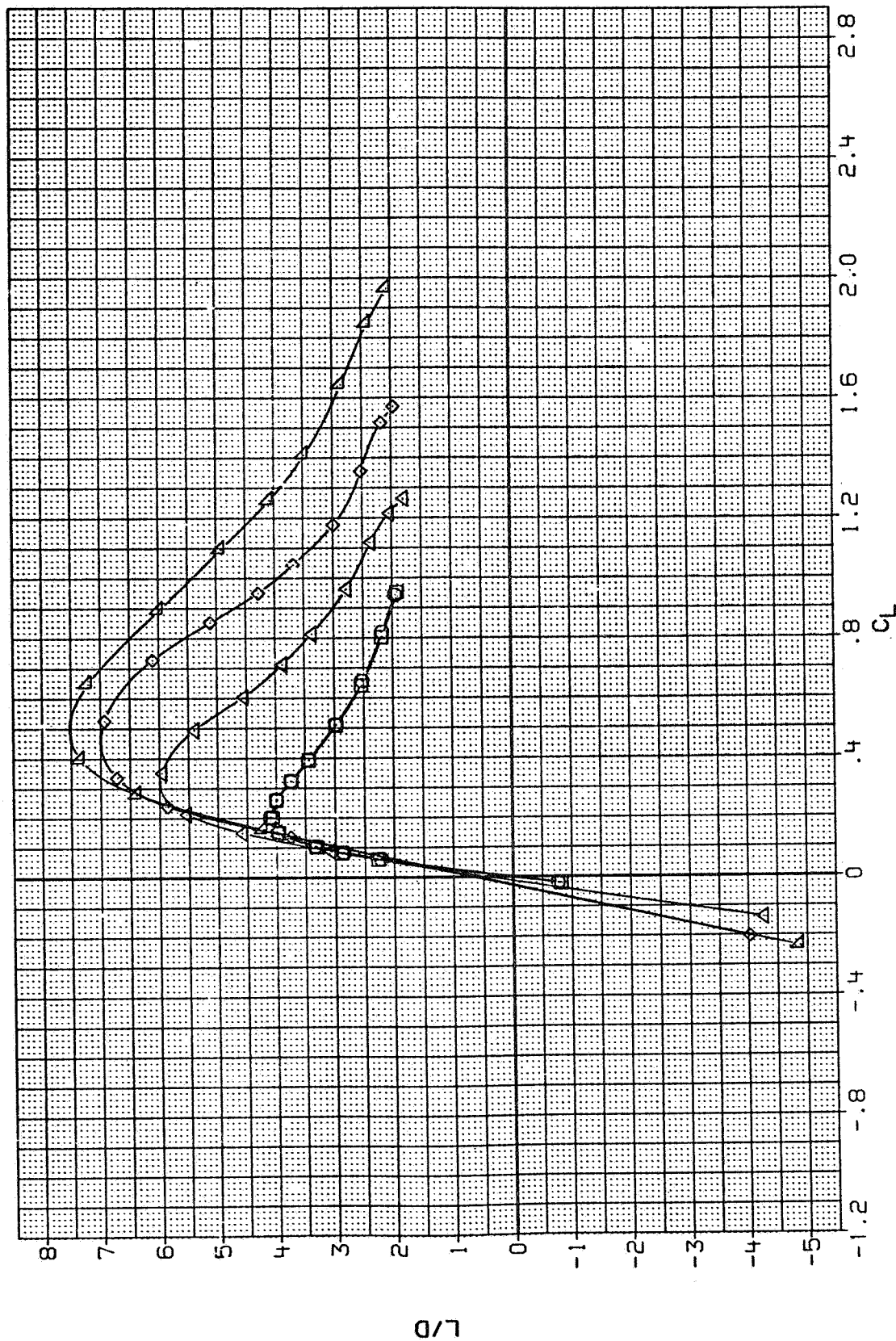


FIG. 87 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = .95

SYMBOL CONFIGURATION
 □ B2 N V
 ◇ B2 N W2 V
 △ B2 N C1 V
 (RA-S-R104)
 (RA-S-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

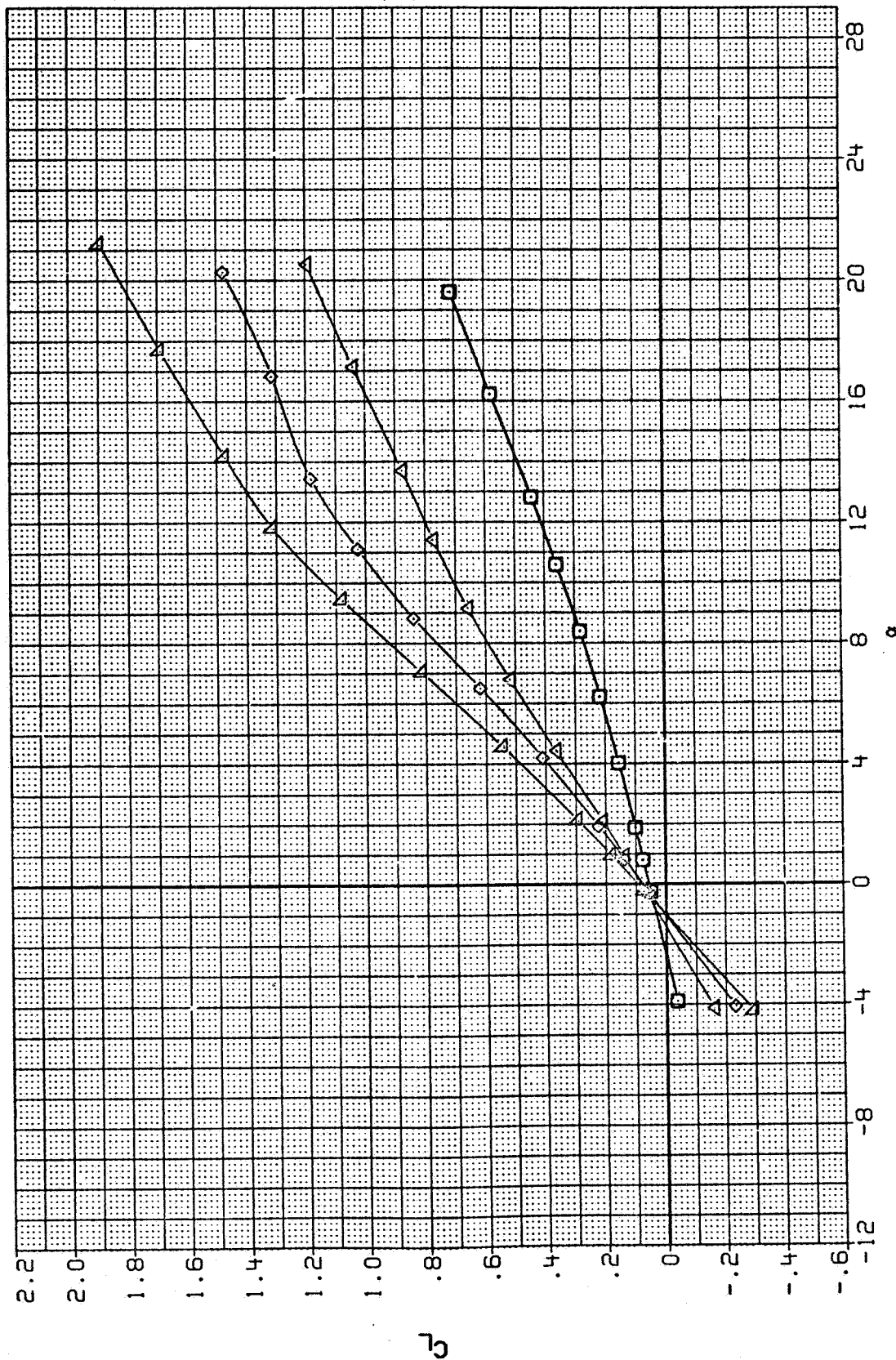


FIG. 88 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.10

SYMBOL	CONFIGURATION
B2 N	(RALS-R104)
B2 N V	(RALS-R104)
B2 N W2 V	(RALS-R104)
B2 N C1 V	(RALS-R104)
B2 N W2 C1 V	(RALS-R104)

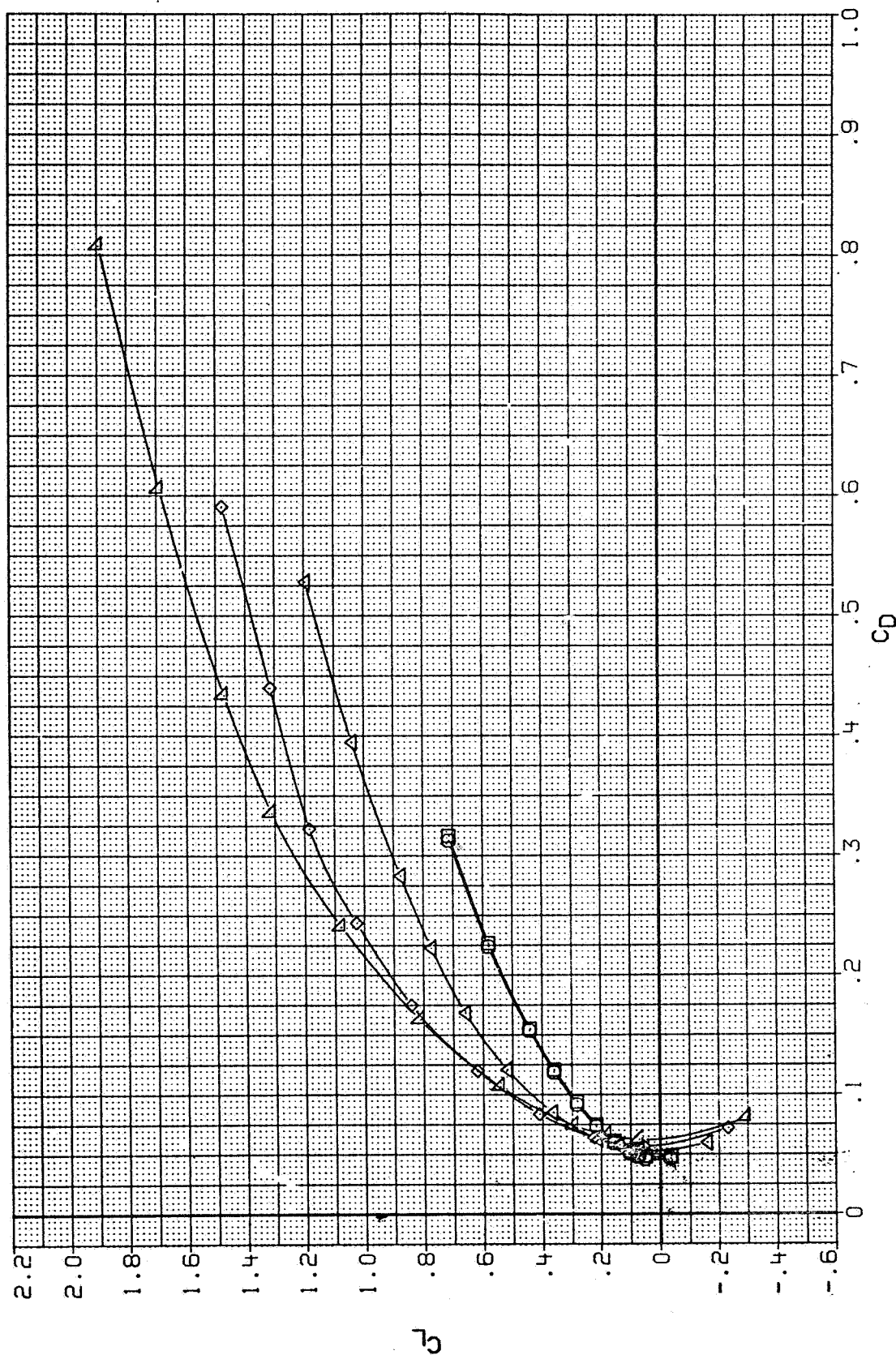


FIG. 88 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.10

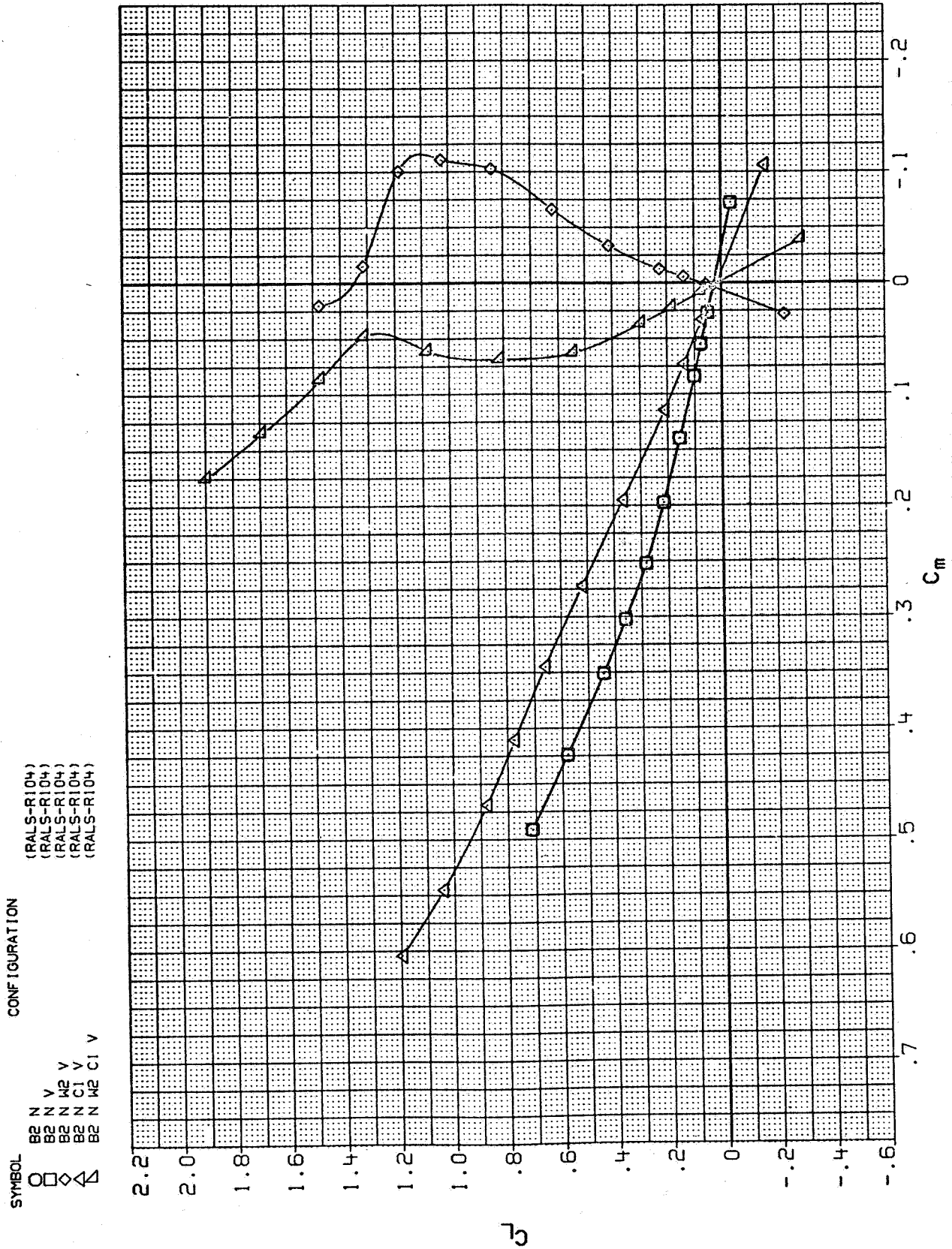


FIG. 88 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.10

SYMBOL CONFIGURATION
 B2 N V (RALS-R104)
 B2 N W2 V (RALS-R104)
 B2 N C1 V (RALS-R104)
 B2 N W2 C1 V (RALS-R104)

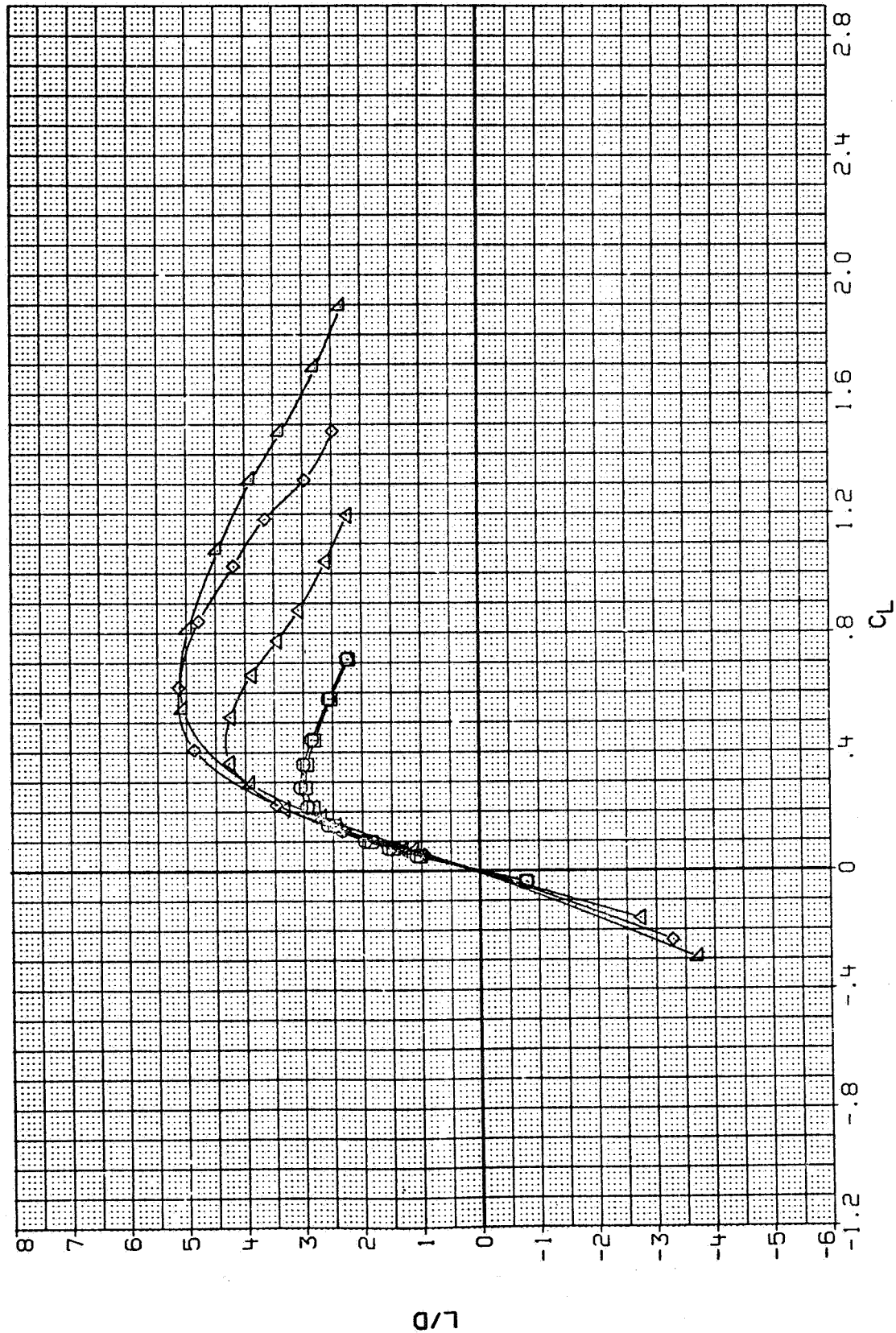


FIG. 88 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.10

SYMBOL	CONFIGURATION
$\square$	B2 N V (RALS-R104)
$\diamond$	B2 N W2 V (RALS-R104)
$\triangle$	B2 N C1 V (RALS-R104)
∇	B2 N W2 C1 V (RALS-R104)

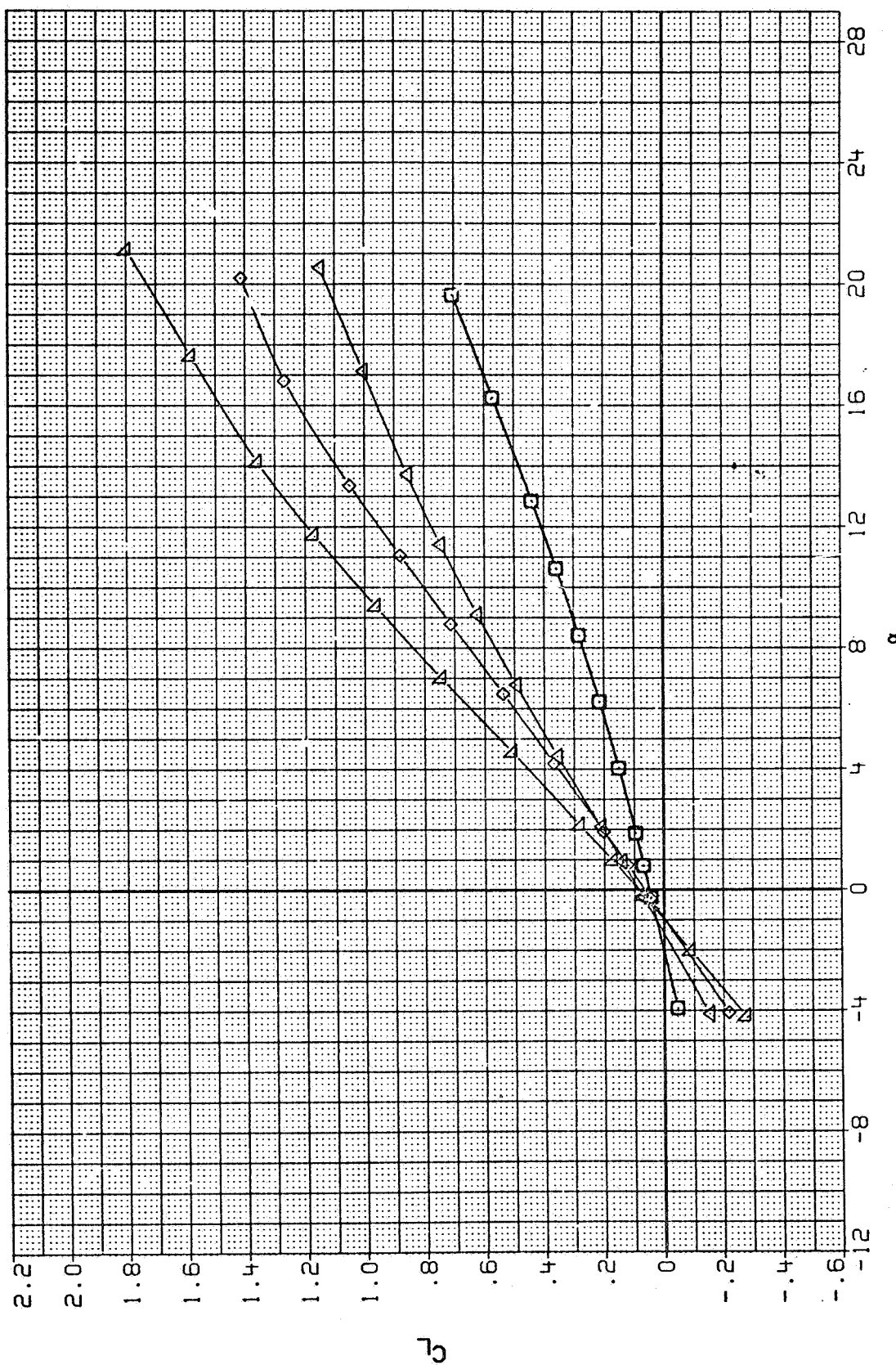


FIG. 89 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL CONFIGURATION

○ B2 N V
 □ B2 N W2 V
 ◇ B2 N C1 V
 △ B2 N W2 C1 V

(RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

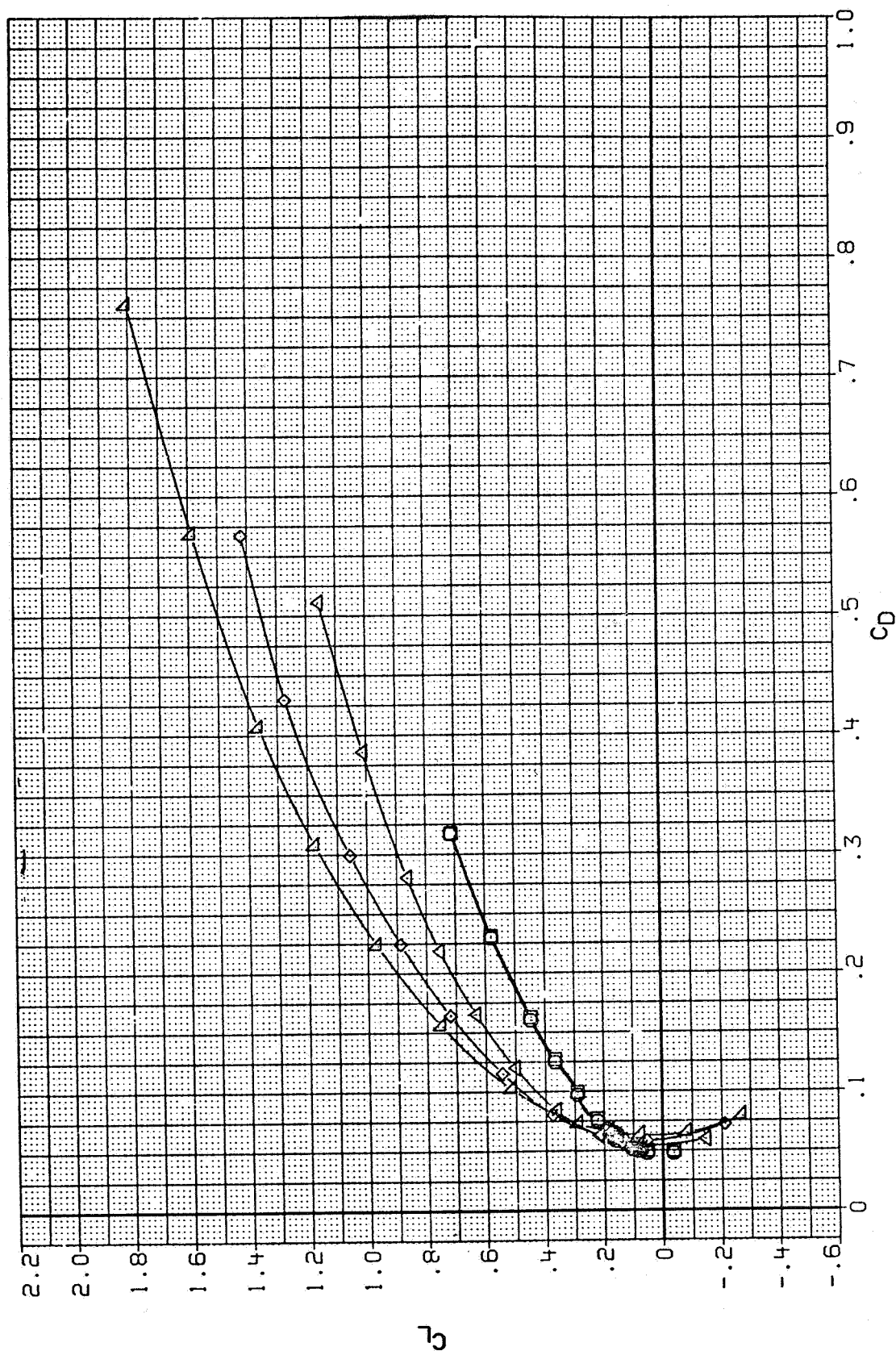


FIG. 89 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL	CONFIGURATION
□	B2 N (RALS-R104)
◇	B2 N V (RALS-R104)
△	B2 N M2 V (RALS-R104)
▽	B2 N C1 V (RALS-R104)

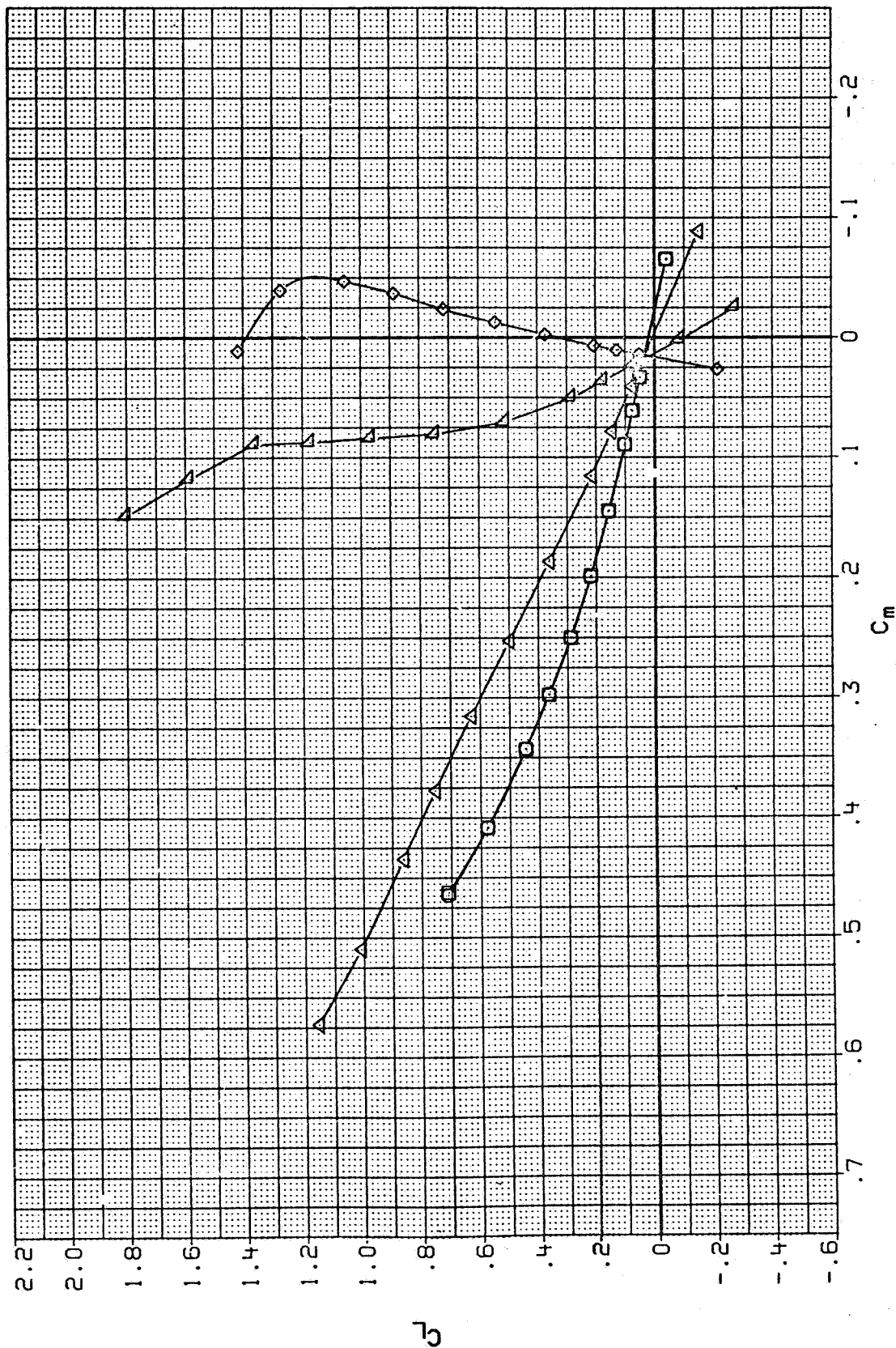


FIG. 89 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL	CONFIGURATION
□	B2 N V (RALS-R104)
◇	B2 N W2 V (RALS-R104)
△	B2 N C1 V (RALS-R104)
▽	B2 N W2 C1 V (RALS-R104)

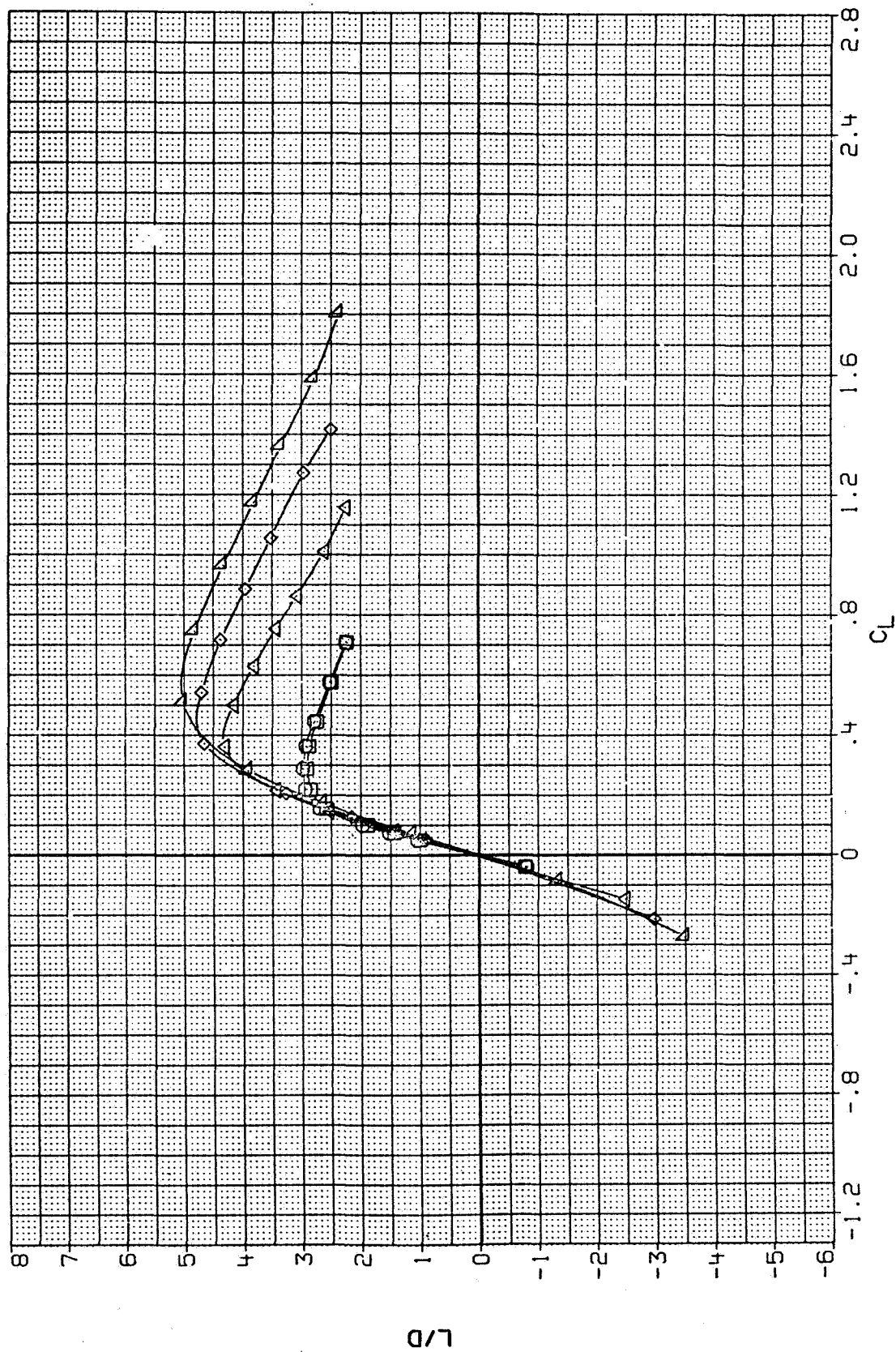


FIG. 89 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL	CONFIGURATION
□	B2 N (RALS-R104)
◇	B2 N V (RALS-R104)
△	B2 N W2 V (RALS-R104)
▽	B2 N C1 V (RALS-R104)
▽	B2 N W2 C1 V (RALS-R104)

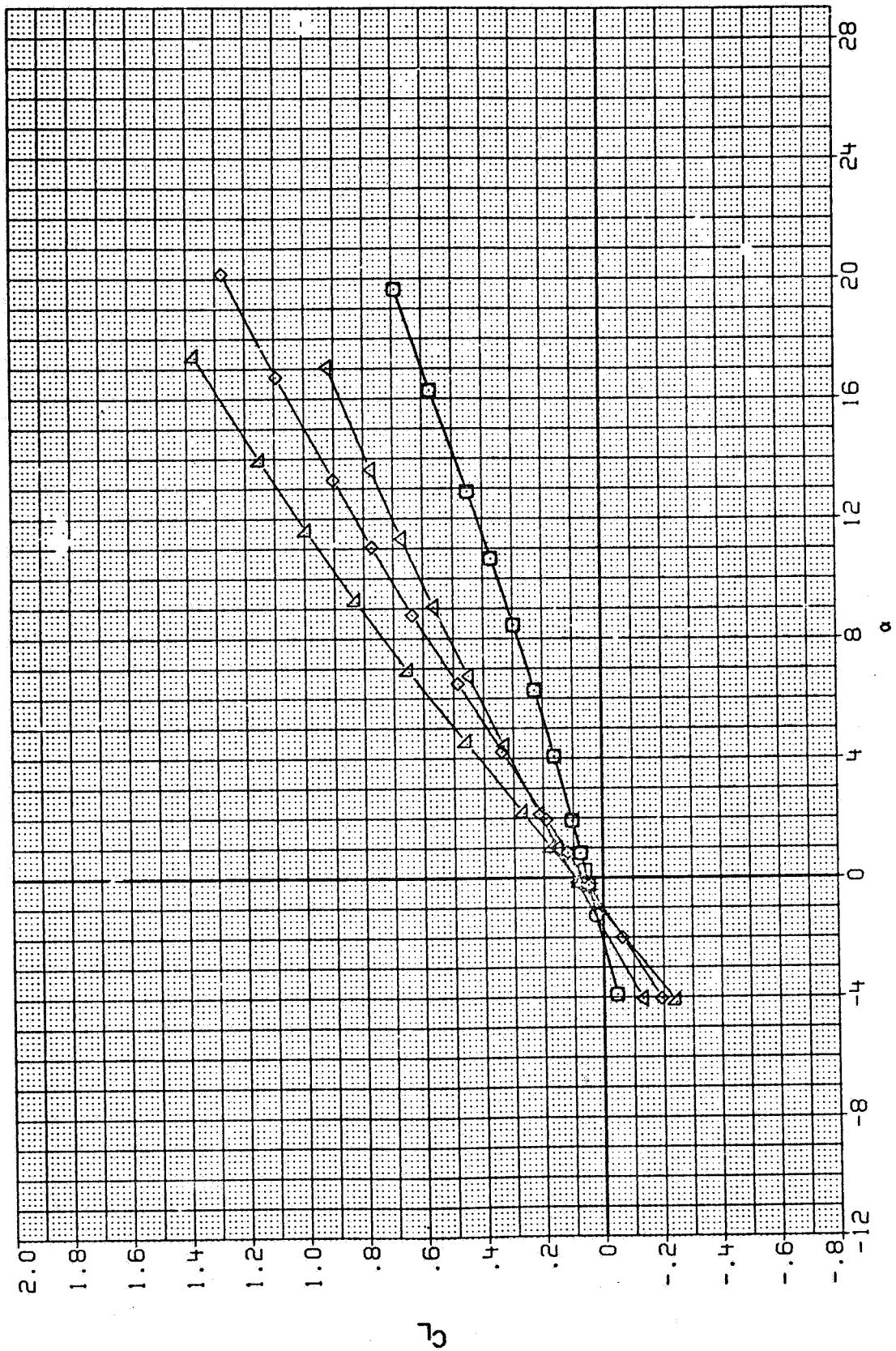


FIG. 90 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.40

SYMBOL	CONFIGURATION
○	B2 N V
◇	B2 N W2 V
△	B2 N C1 V
	B2 N W2 C1 V
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)

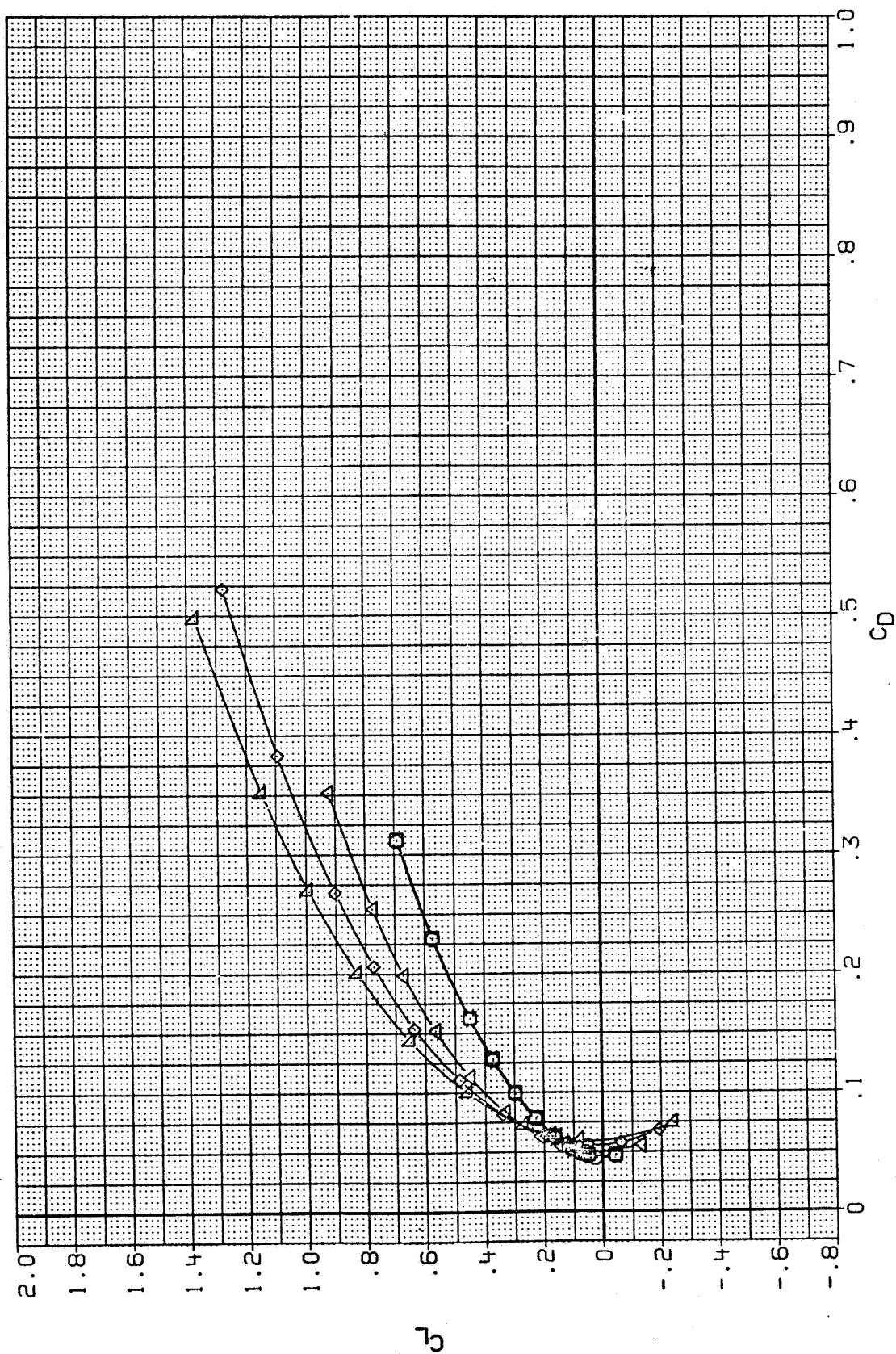


FIG. 90 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.40

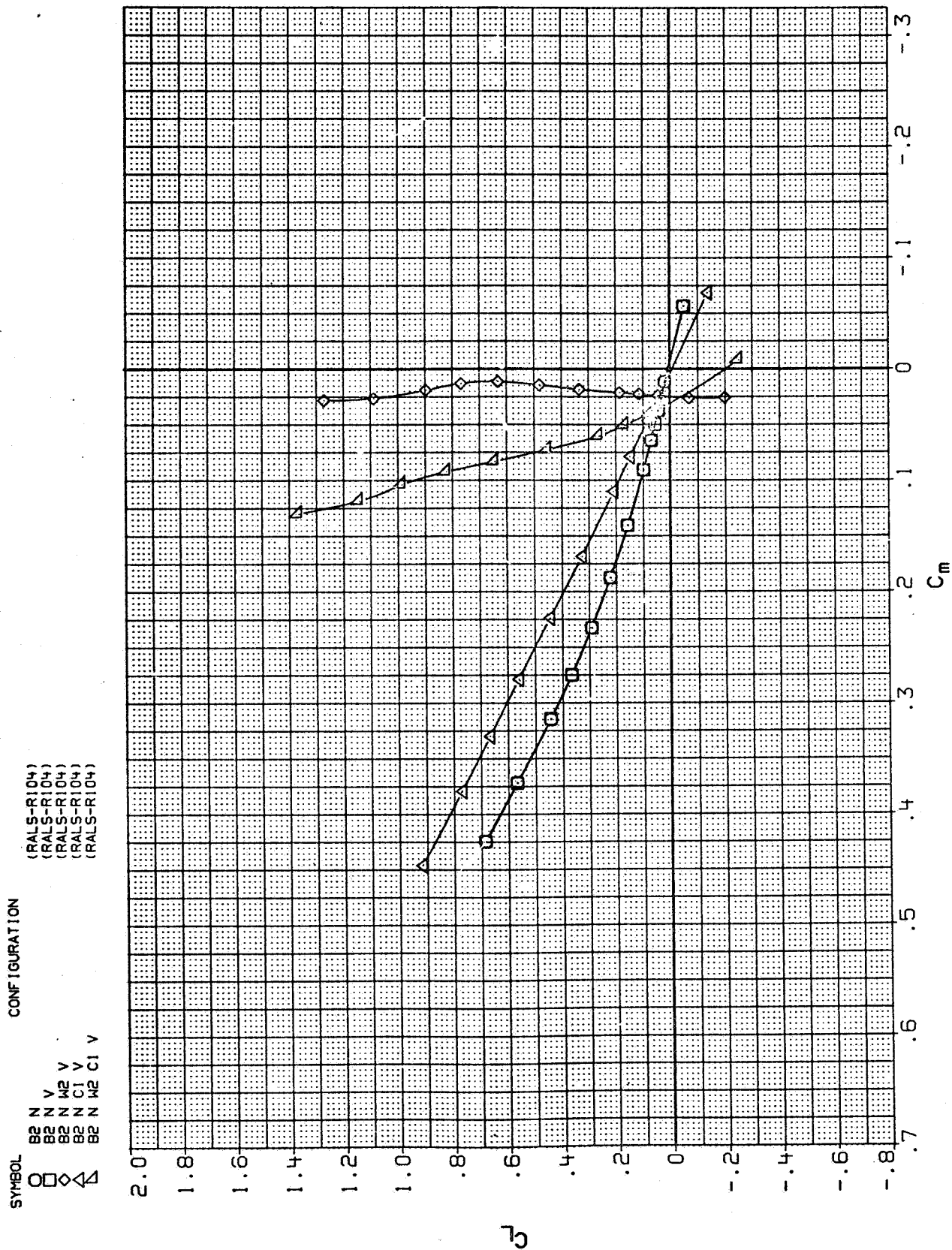


FIG. 90 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.40

SYMBOL	CONFIGURATION
□	B2 N V
◇	B2 N W2 V
△	B2 N C1 V
▽	B2 N W2 C1 V
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)

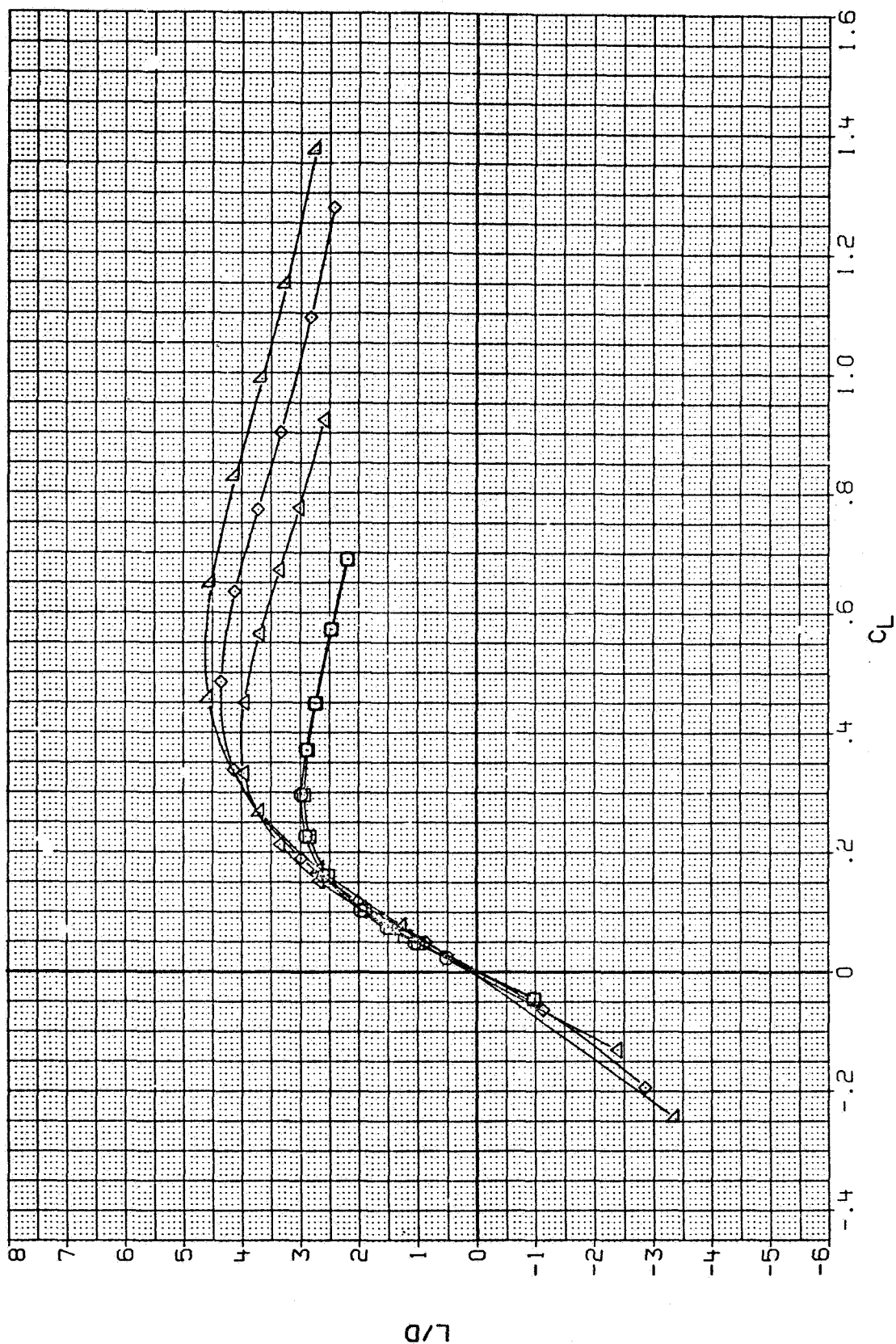


FIG. 90 COMPONENT BUILDUP, LONGITUDINAL CHARACTERISTICS

MACH = 1.40

SYMBOL	CONFIGURATION
□	B2 N V
◇	B2 N W2 V
△	B2 N C1 V
	B2 N W2 C1 V
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)
	(RALS-R104)

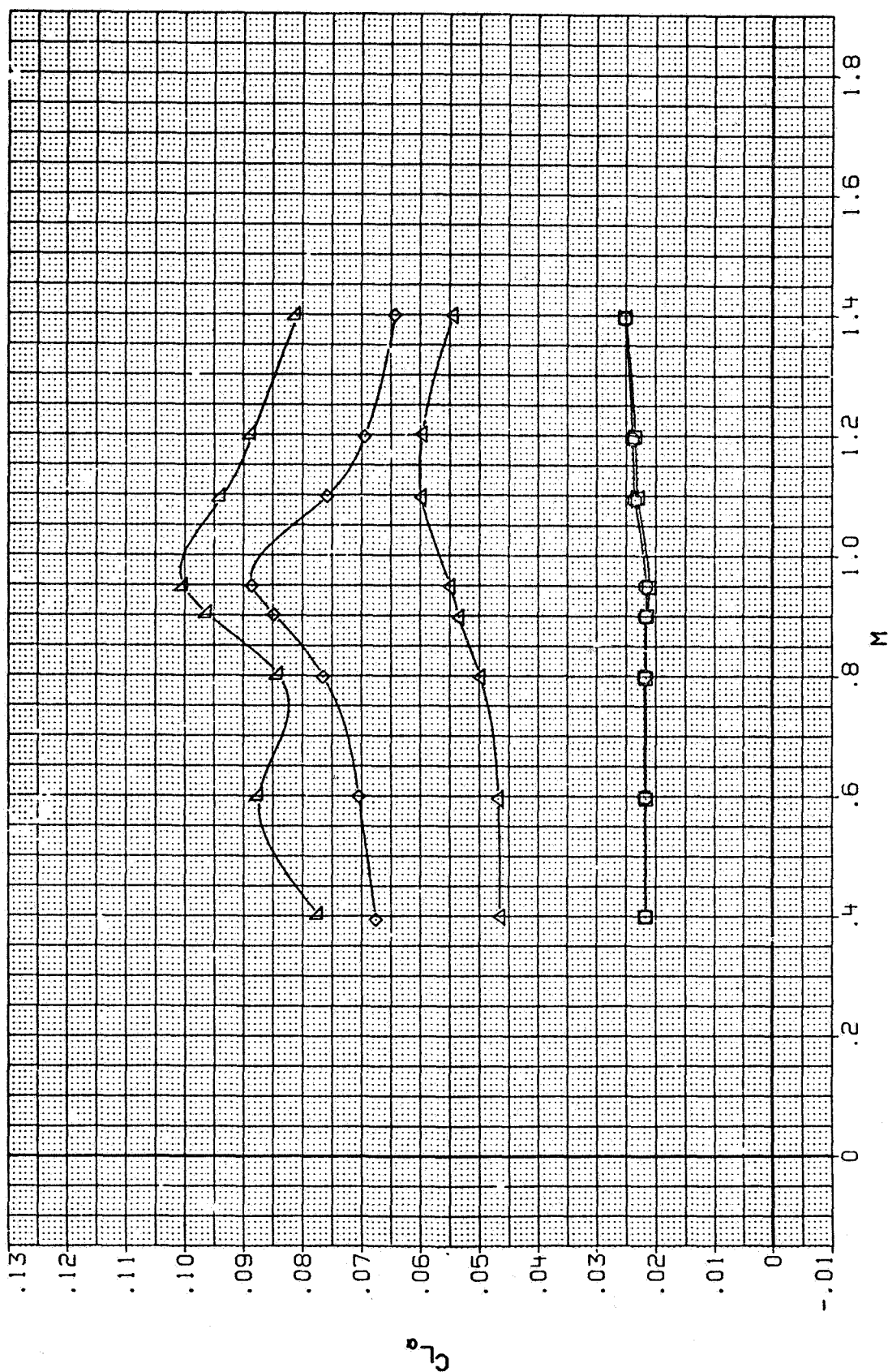


FIG. 91 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

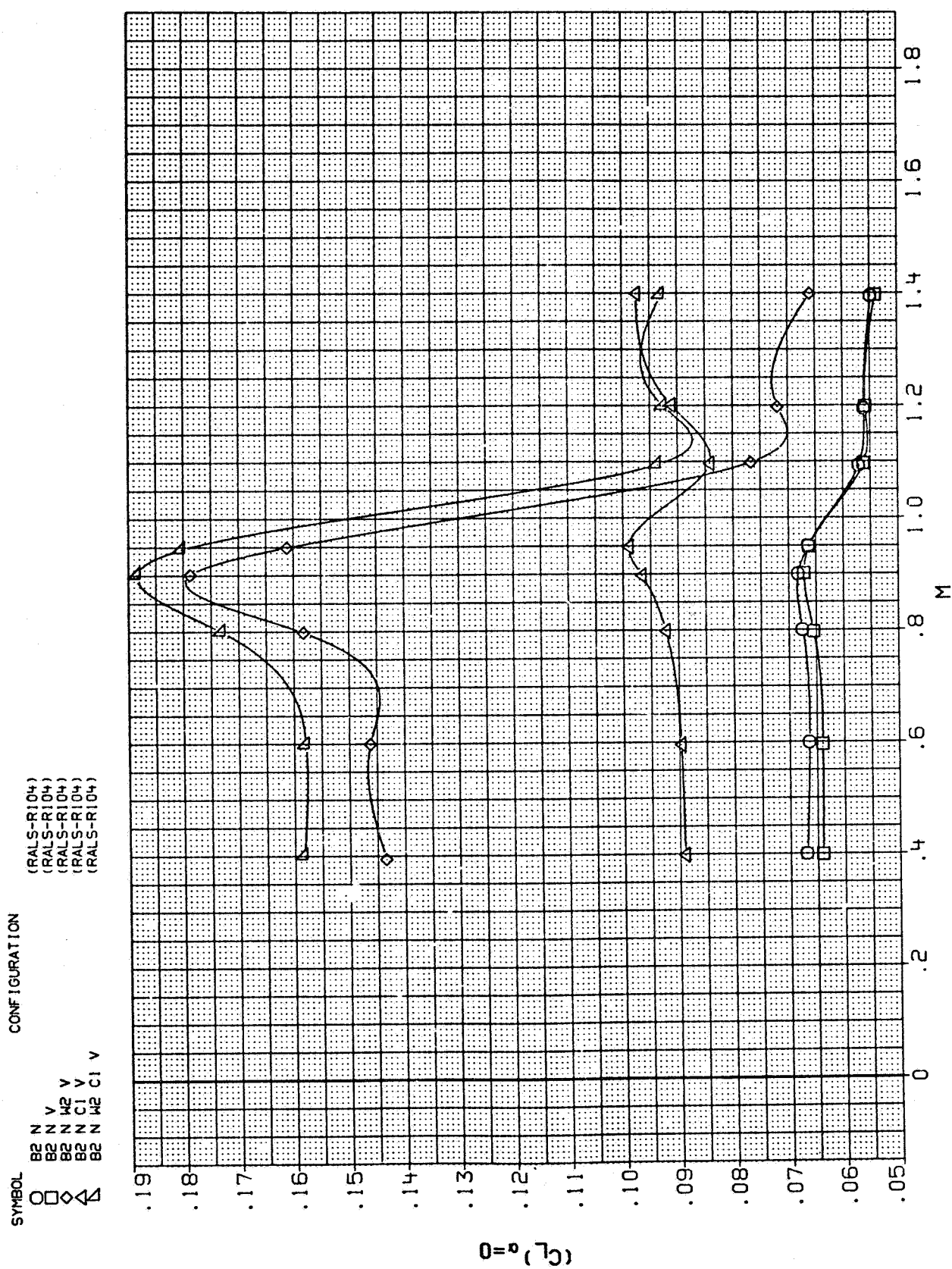


FIG. 91 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

SYMBOL		CONFIGURATION	
○	B2 N	(RALS-R104)	
◇	B2 N V	(RALS-R104)	
◊	B2 N M2 V	(RALS-R104)	
△	B2 N C1 V	(RALS-R104)	
▽	B2 N M2 C1 V	(RALS-R104)	

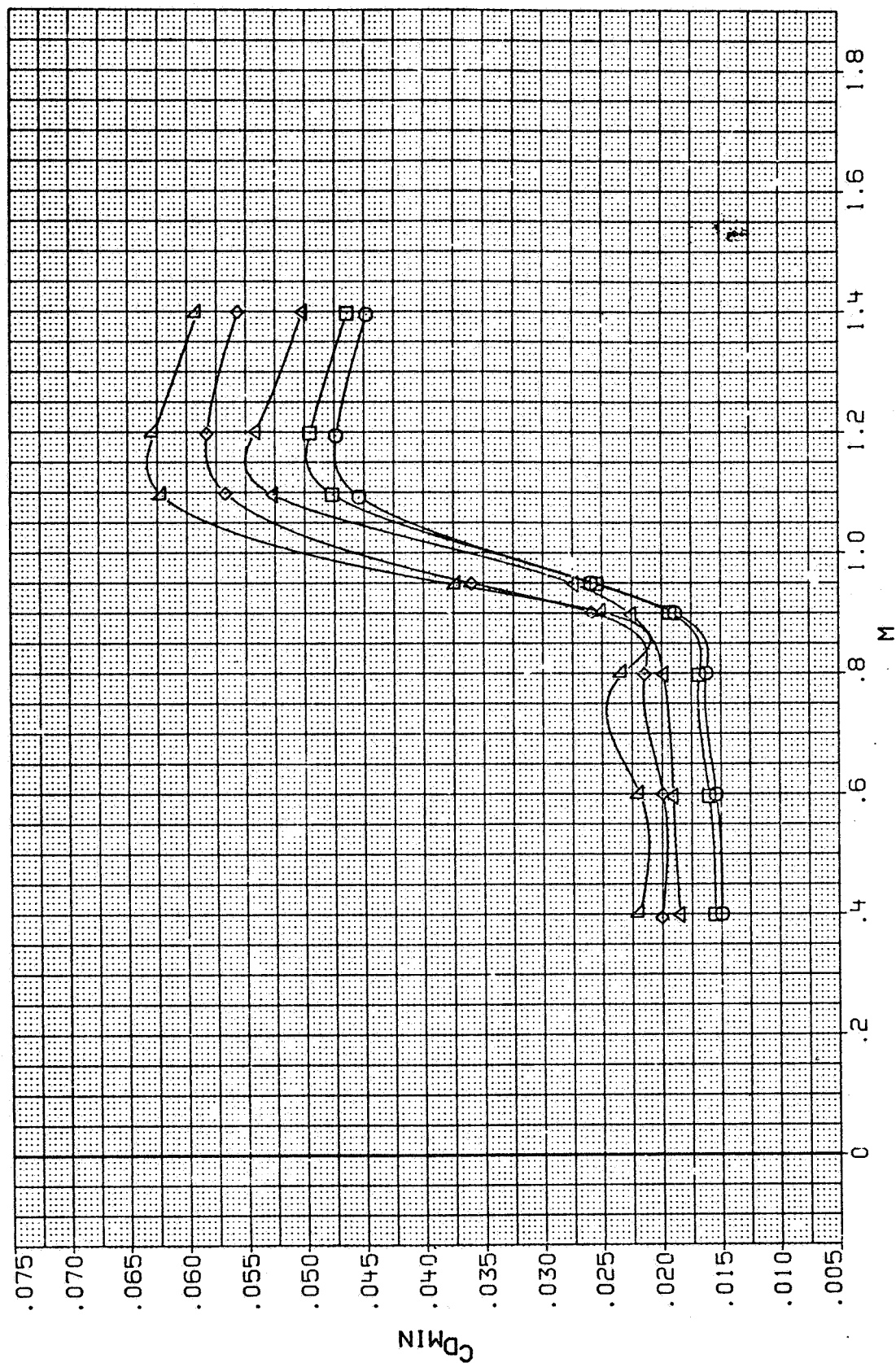


FIG. 91 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

SYMBOL CONFIGURATION
 □ B2 N V
 ◇ B2 N M2 V
 △ B2 N C1 V
 B2 N M2 C1 V
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

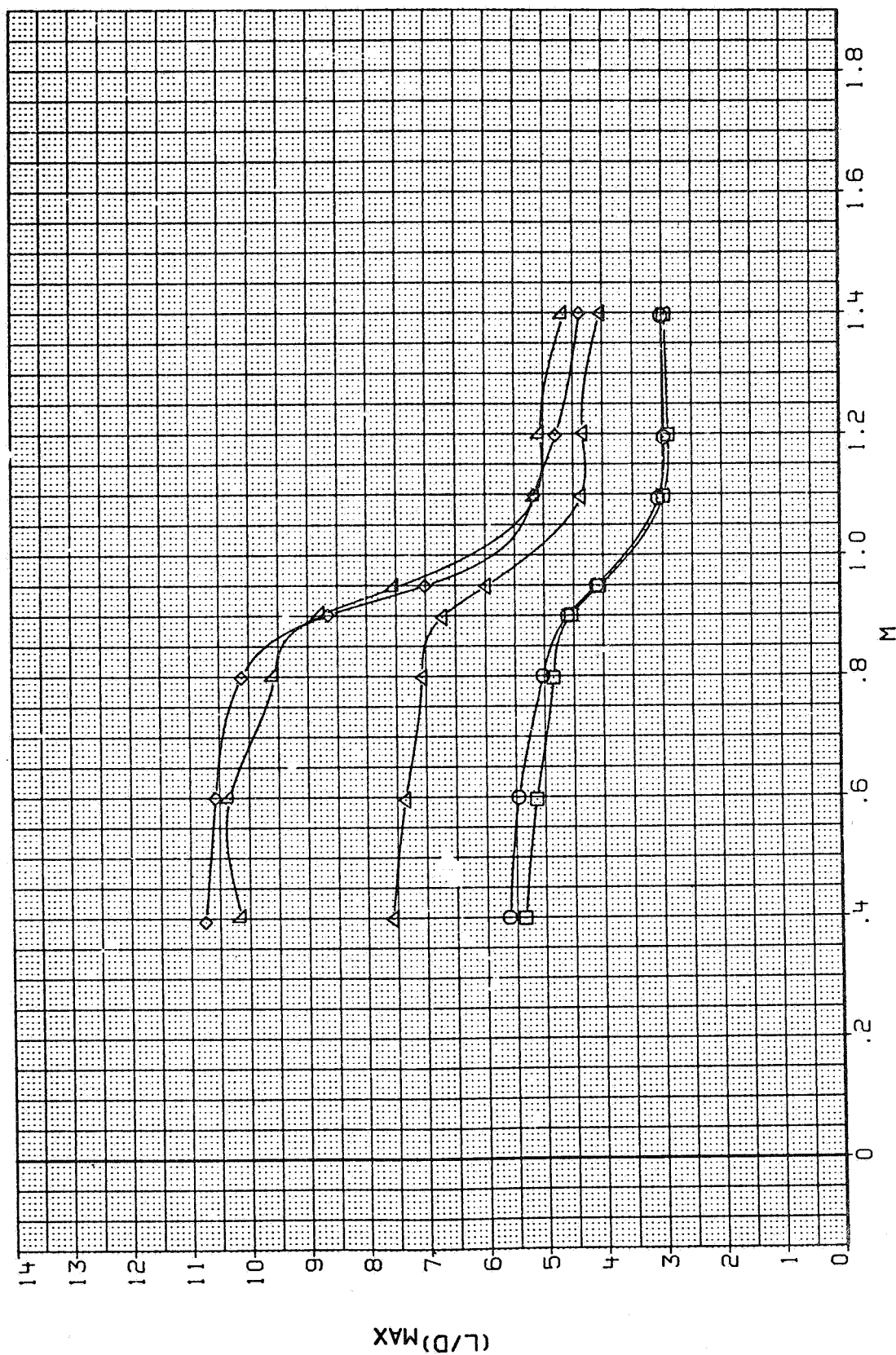


FIG. 91 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

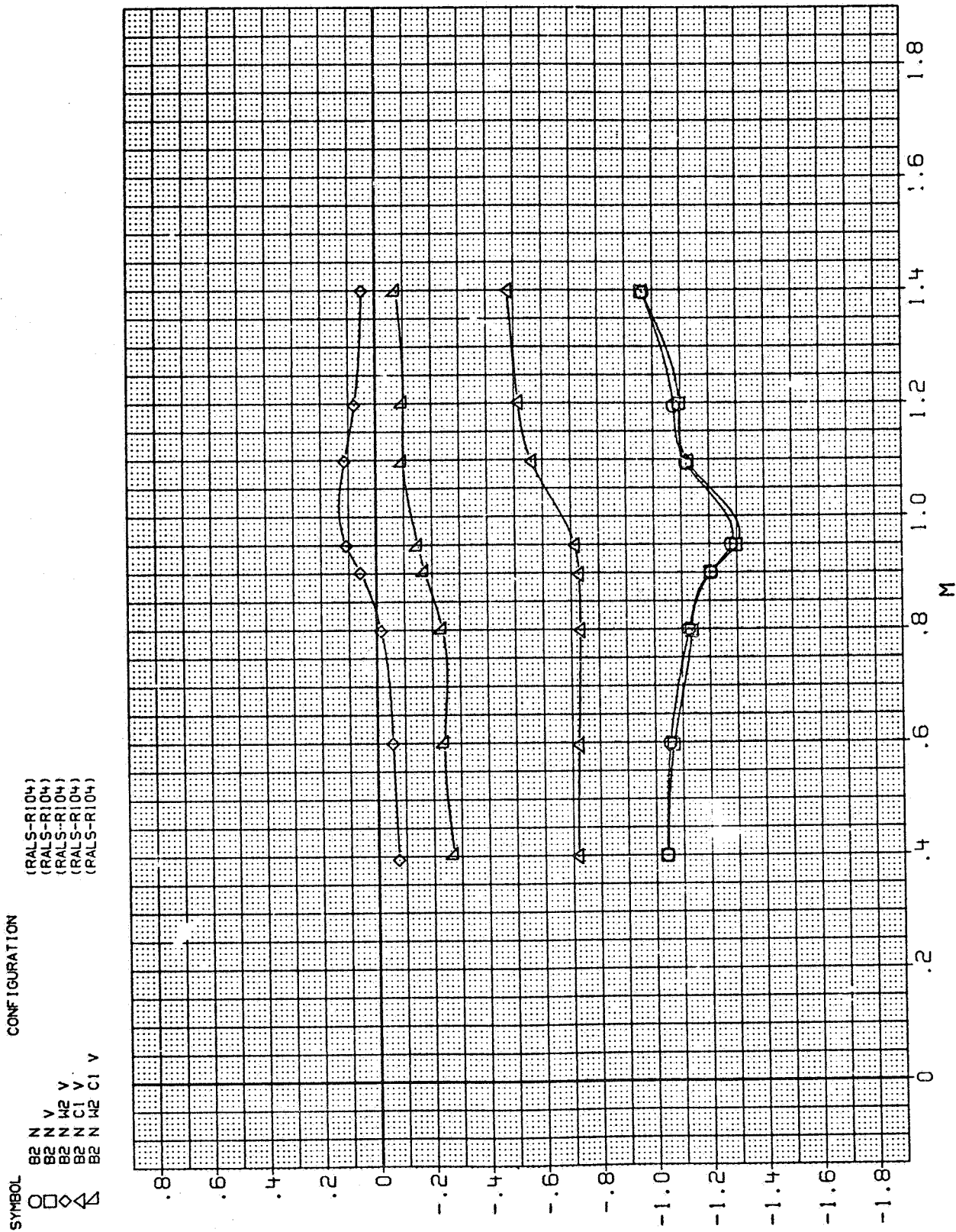


FIG. 91 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

SYMBOL CONFIGURATION
 B2 N V (RALS-R104)
 B2 N W2 V (RALS-R104)
 B2 N C1 V (RALS-R104)
 B2 N W2 C1 V (RALS-R104)

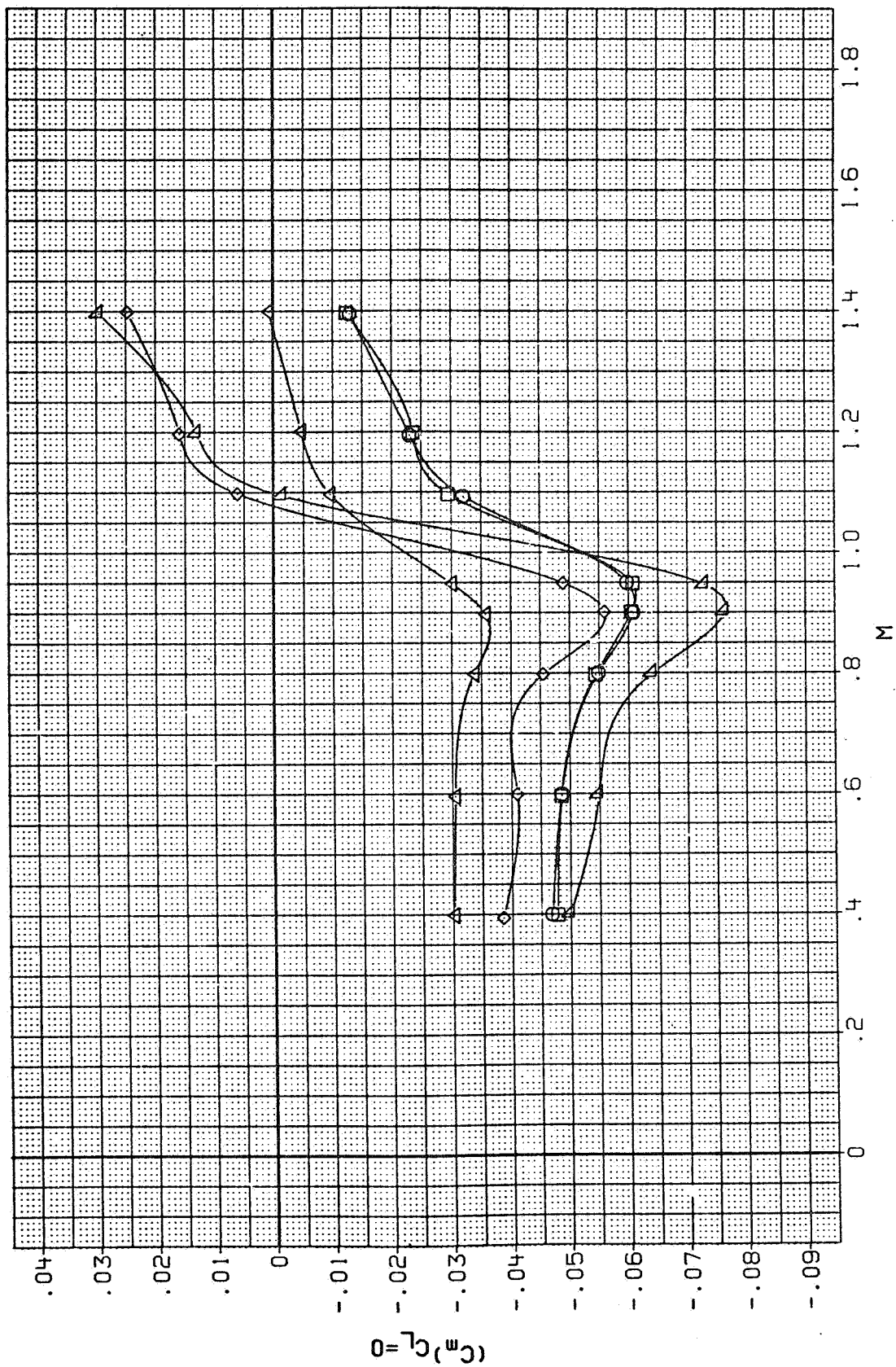


FIG. 91 SUMMARY OF COMPONENT BUILDUP WITH MACH NUMBER

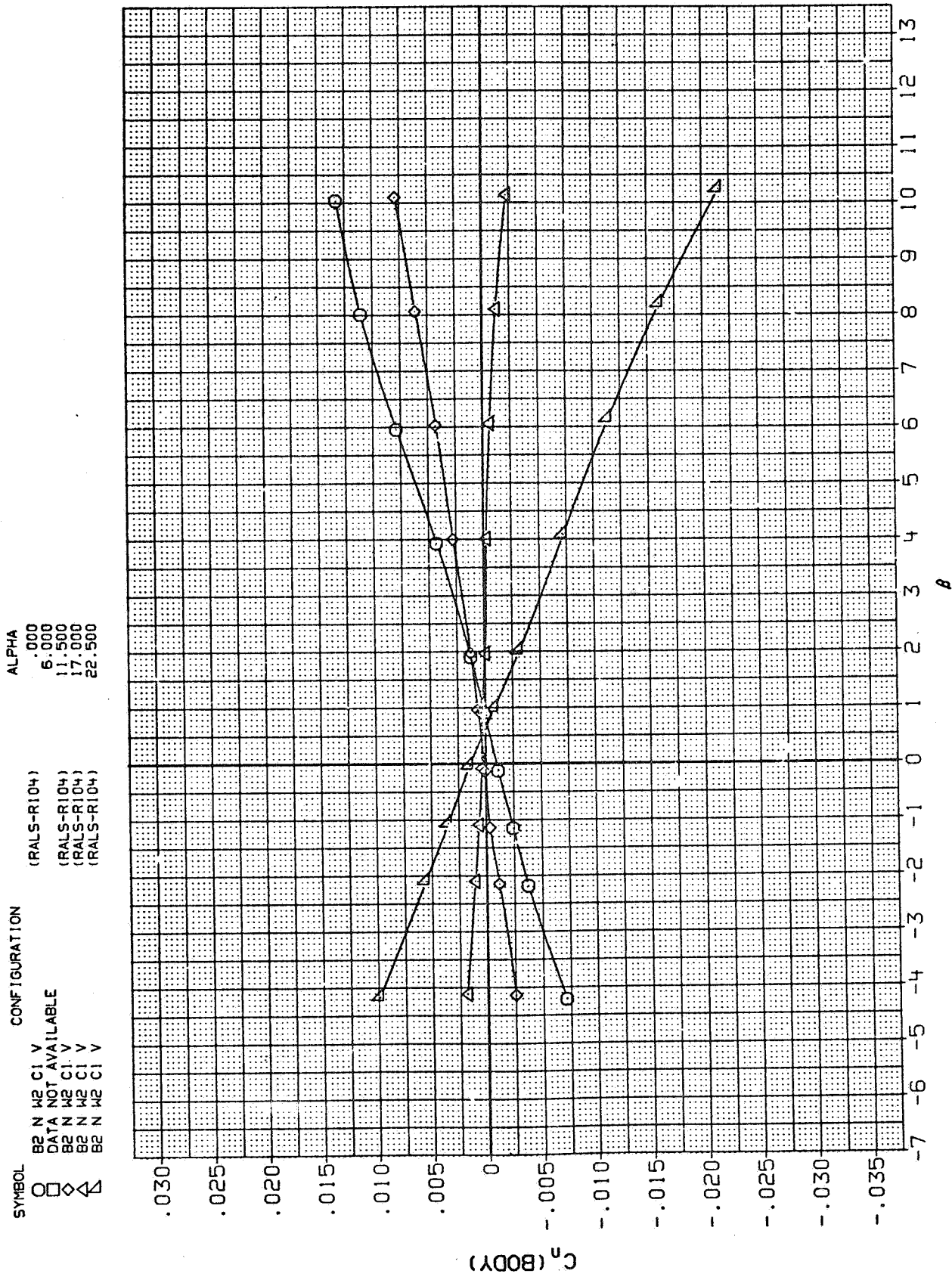


FIG. 92 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .60

SYMBOL CONFIGURATION ALPHA
 ○ B2 N W2 C1 V .000
 DATA NOT AVAILABLE 6.000
 B2 N W2 C1 V 11.500
 B2 N W2 C1 V 17.000
 B2 N W2 C1 V 22.500

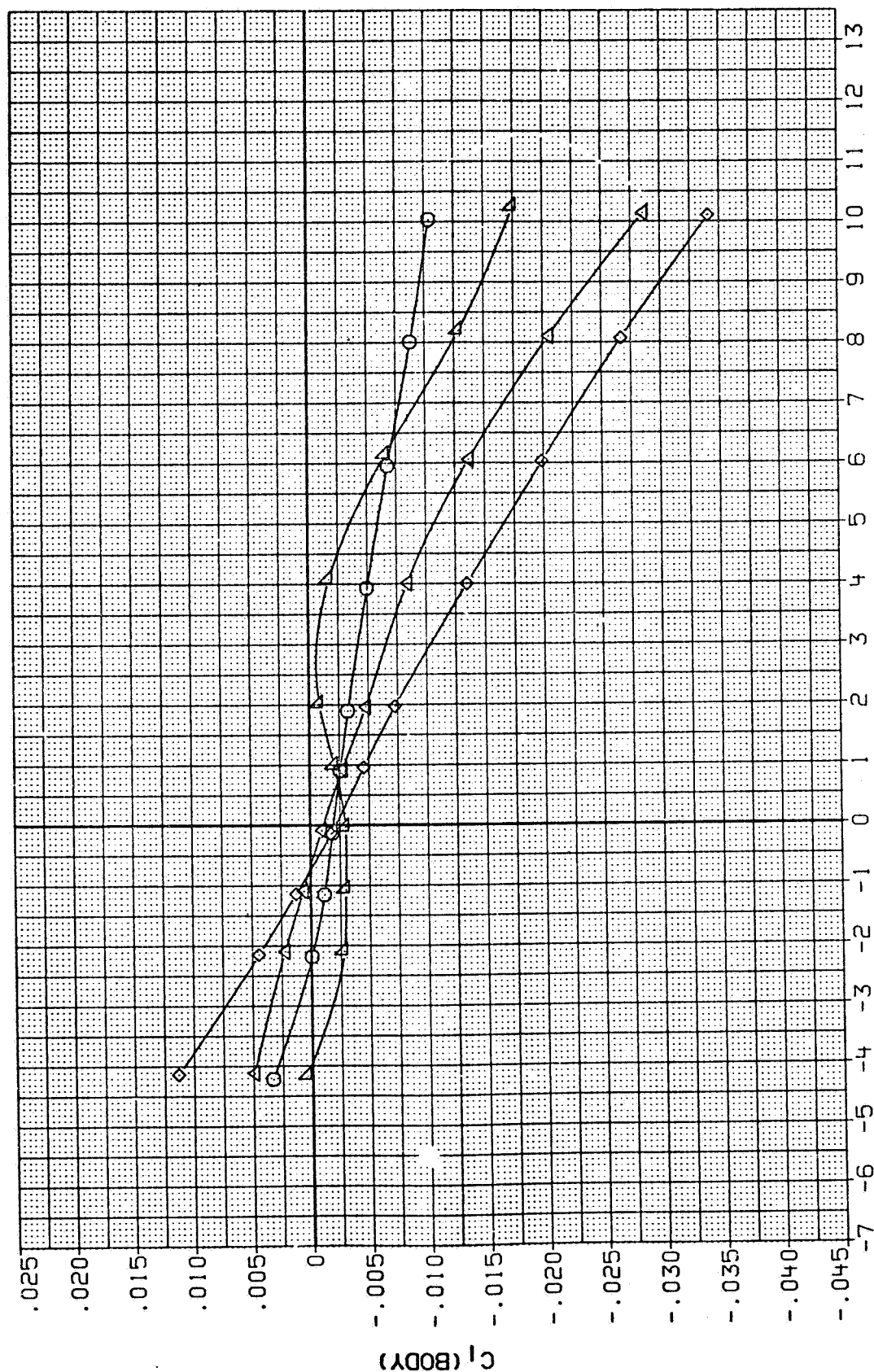


FIG. 92 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .60

SYMBOL	CONFIGURATION	ALPHA
B2 N W2 C1 V	(RALS-R104)	.000
DATA NOT AVAILABLE	(RALS-R104)	6.000
B2 N W2 C1 V	(RALS-R104)	11.500
B2 N W2 C1 V	(RALS-R104)	17.000
B2 N W2 C1 V	(RALS-R104)	22.500

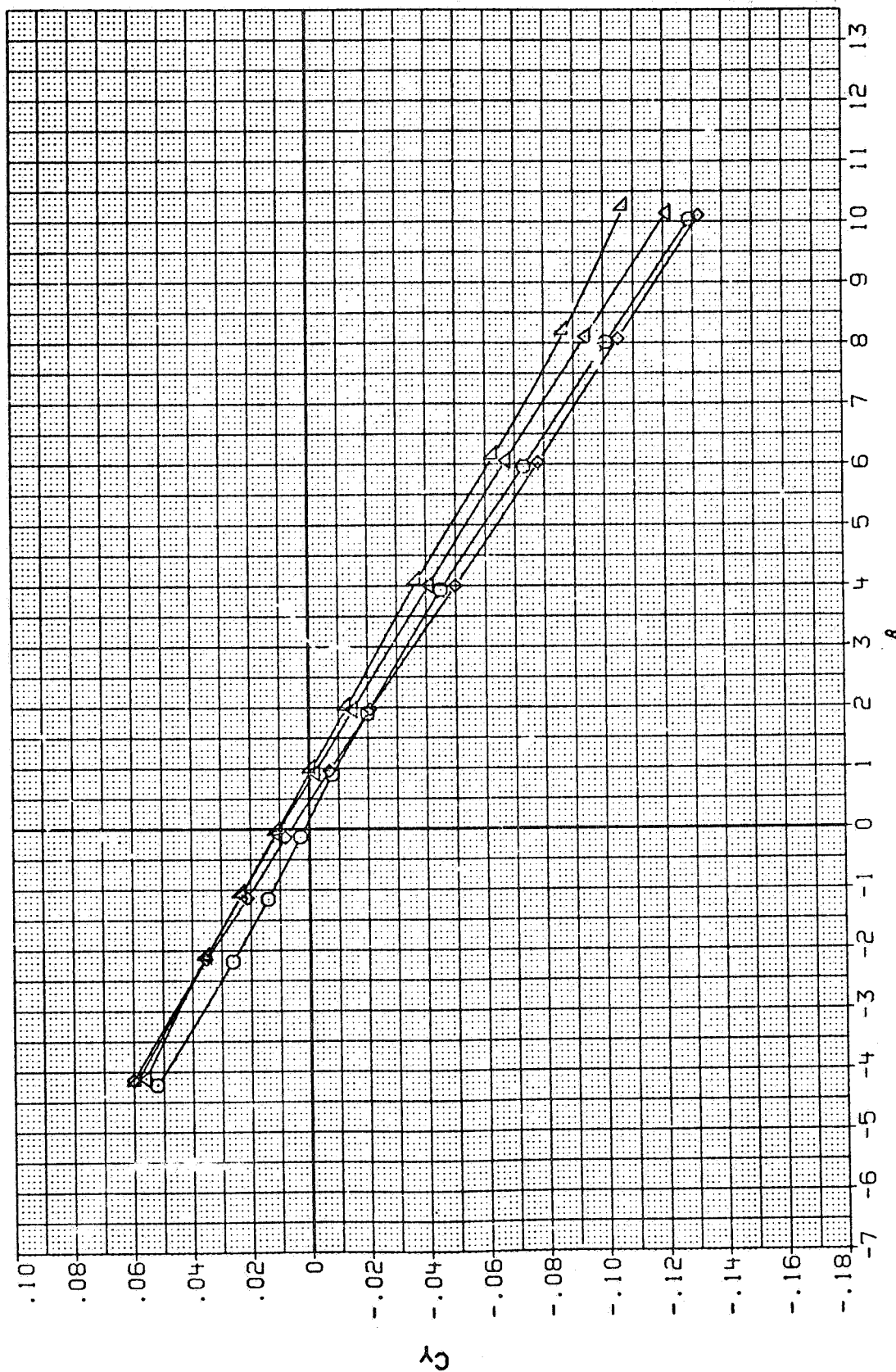


FIG. 92 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .60

SYMBOL CONFIGURATION ALPHA

○ B2 N W2 C1 V
 DATA NOT AVAILABLE
 □ B2 N W2 C1 V
 △ B2 N W2 C1 V
 ▲ B2 N W2 C1 V

(RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

.000
 6.000
 11.500
 17.000
 22.500

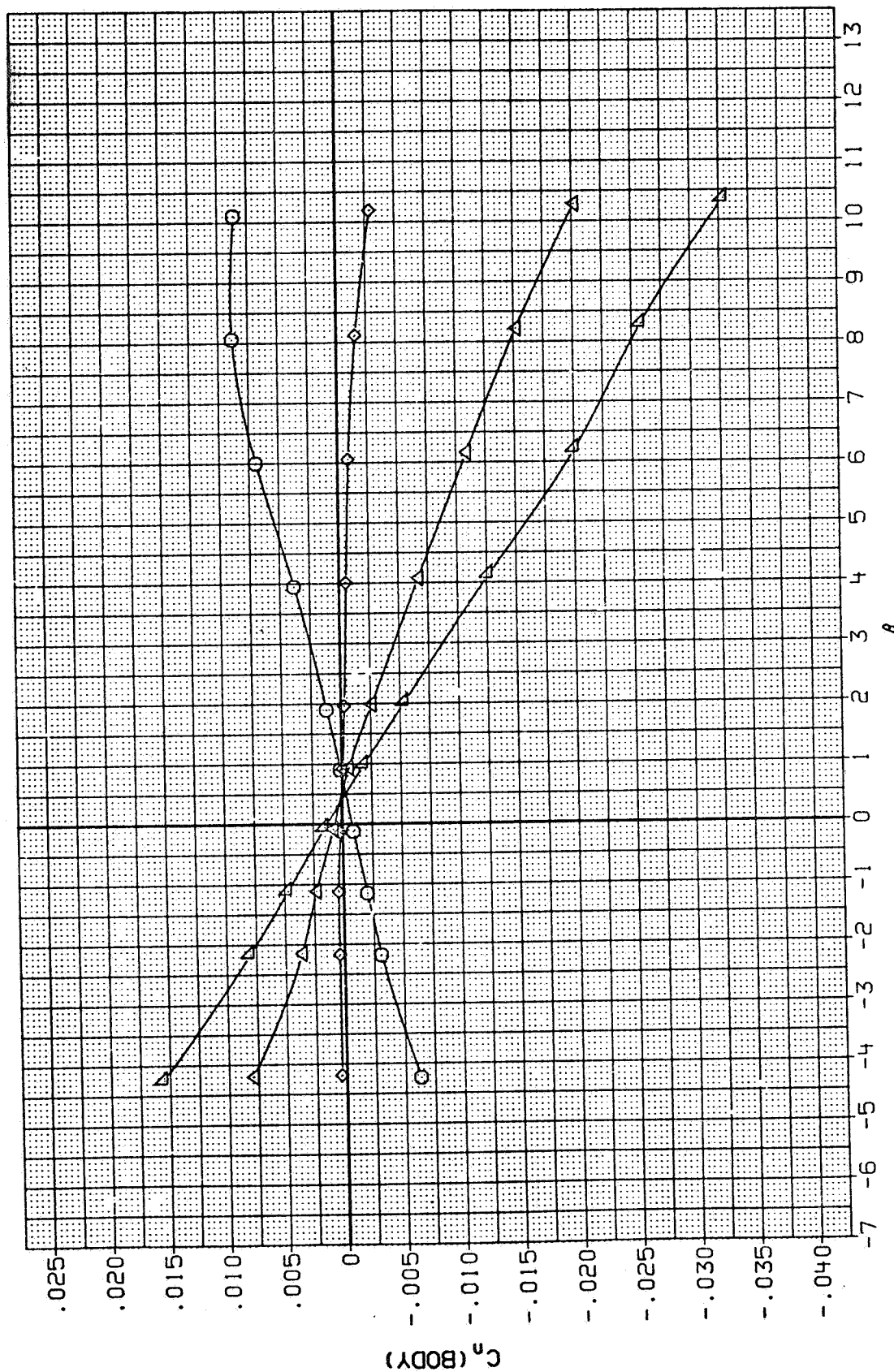


FIG. 93 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .90

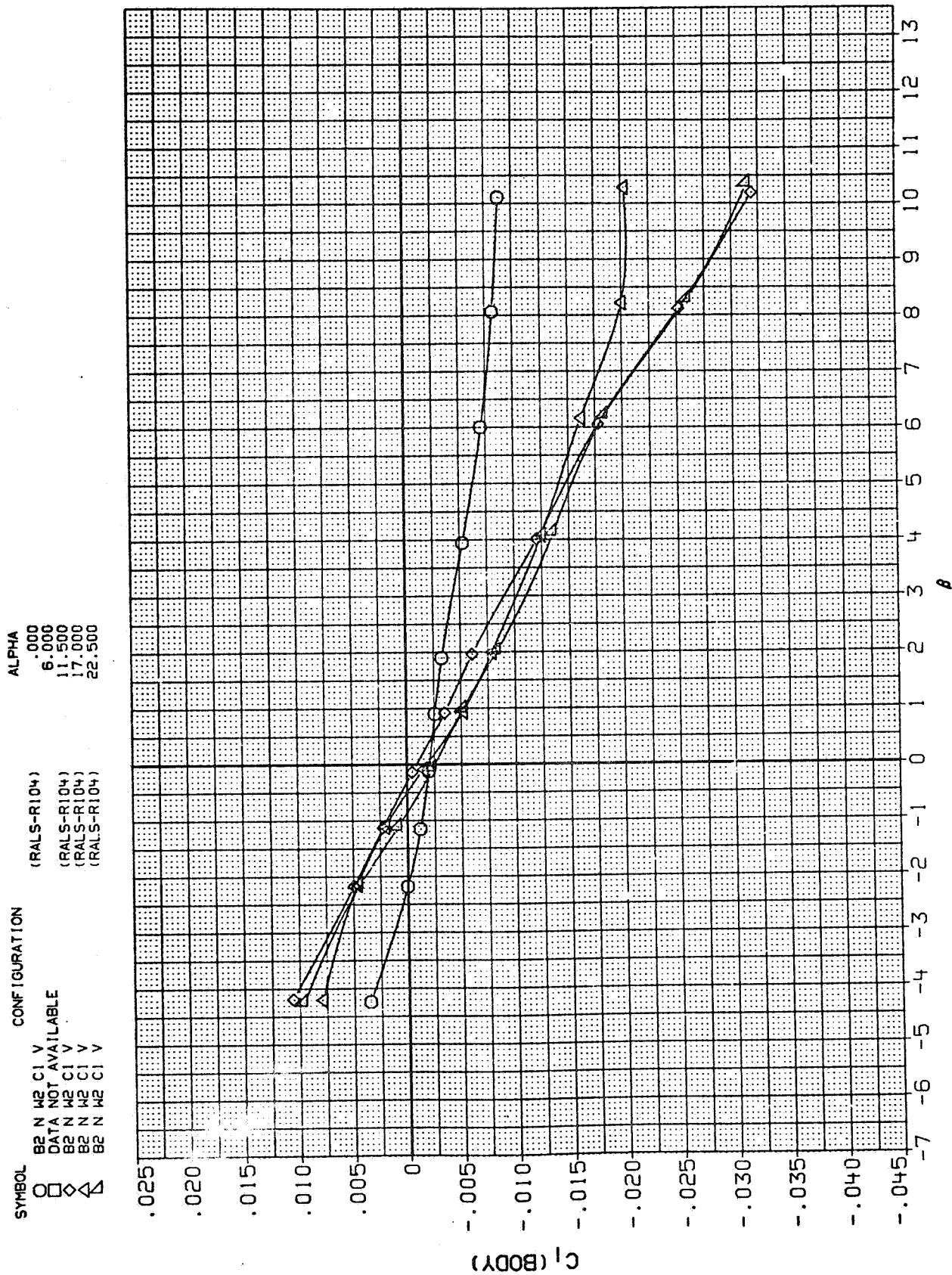


FIG. 93 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

SYMBOL	CONFIGURATION	ALPHA
□	B2 N W2 C1 V	.000
◇	DATA NOT AVAILABLE	6.000
△	B2 N W2 C1 V	11.500
	B2 N W2 C1 V	17.000
	B2 N W2 C1 V	22.500
	(RALS-R104)	
	(RALS-R104)	
	(RALS-R104)	

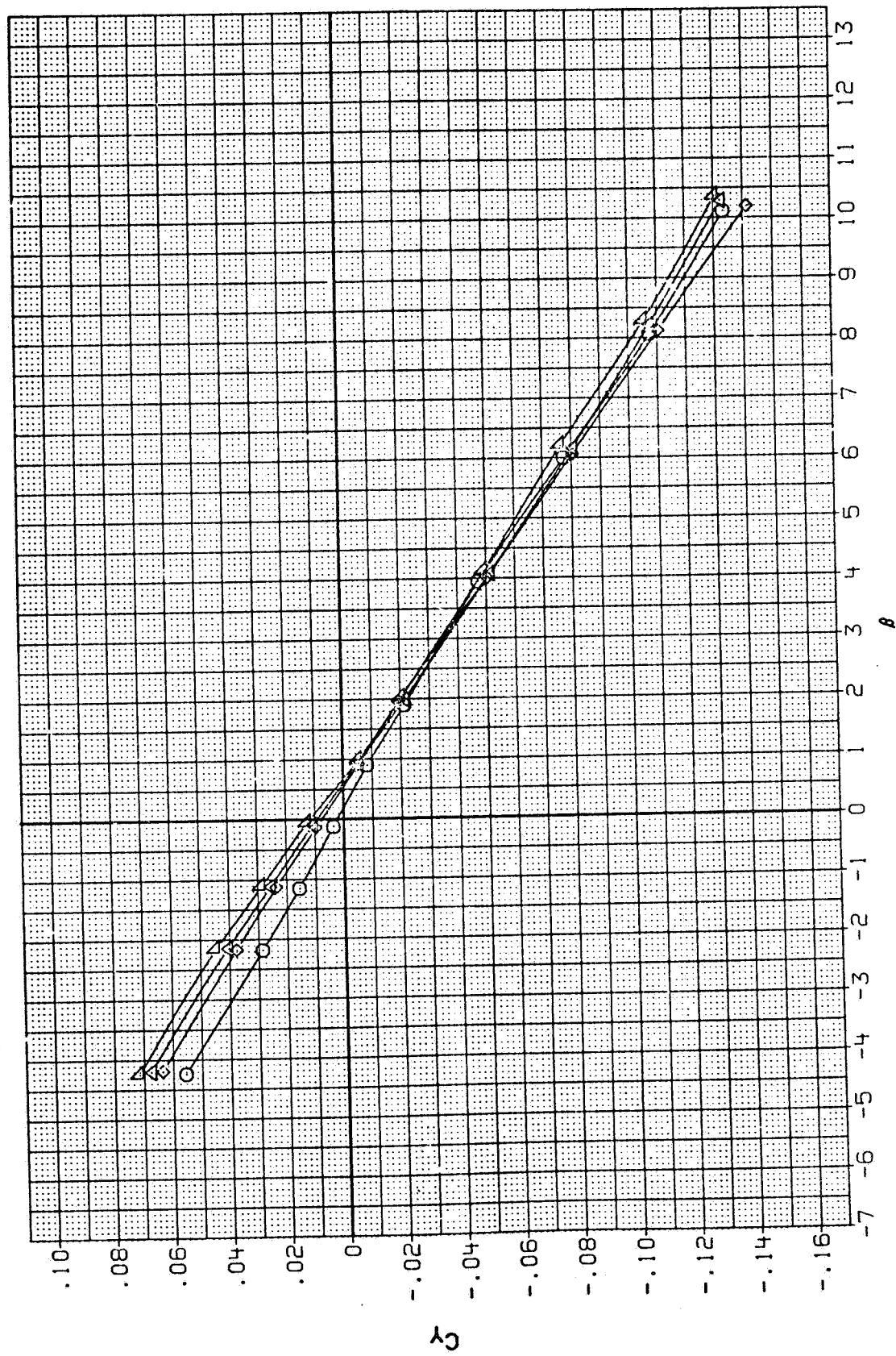


FIG. 93 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = .90

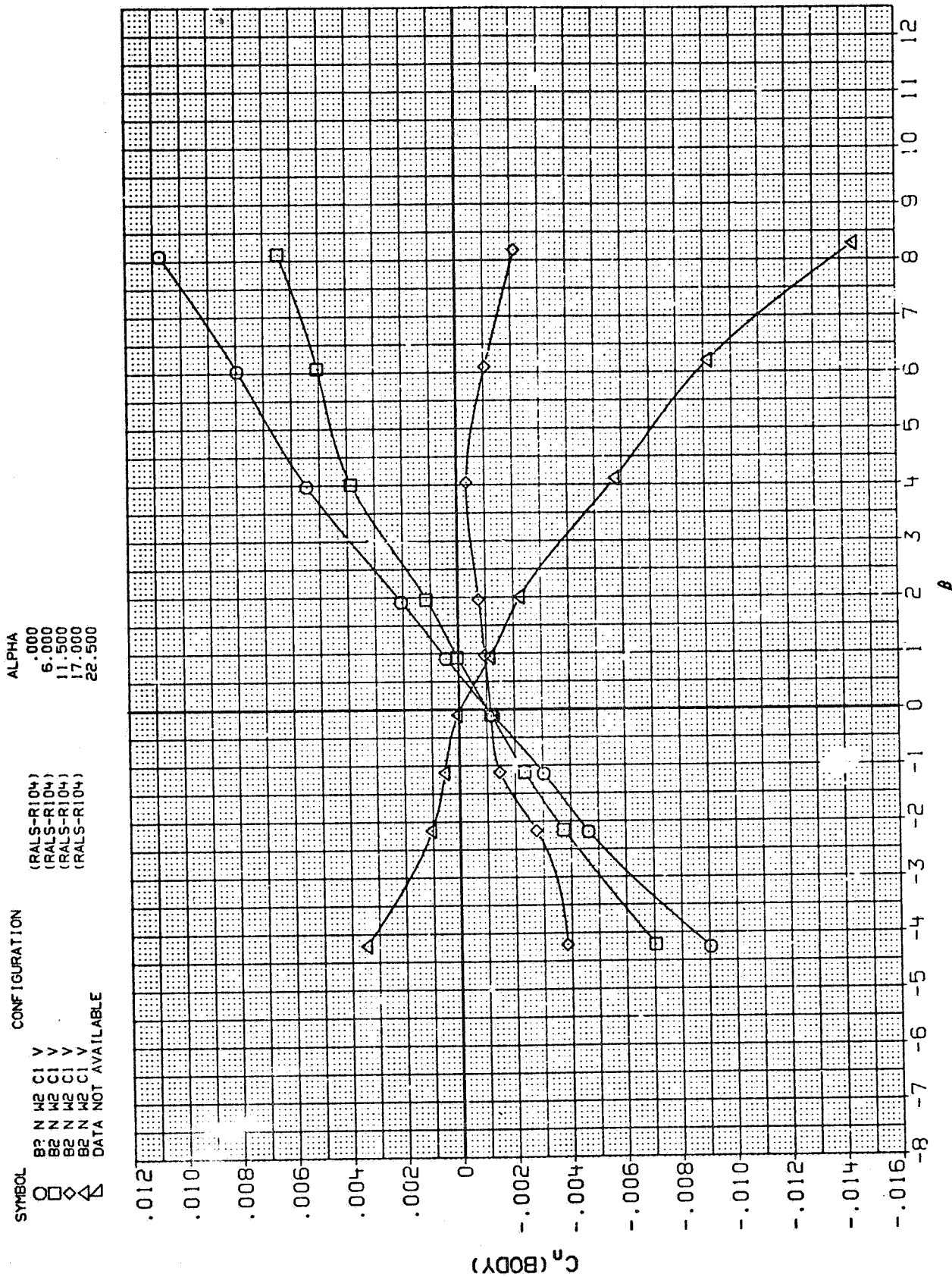


FIG. 94 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = 1.20

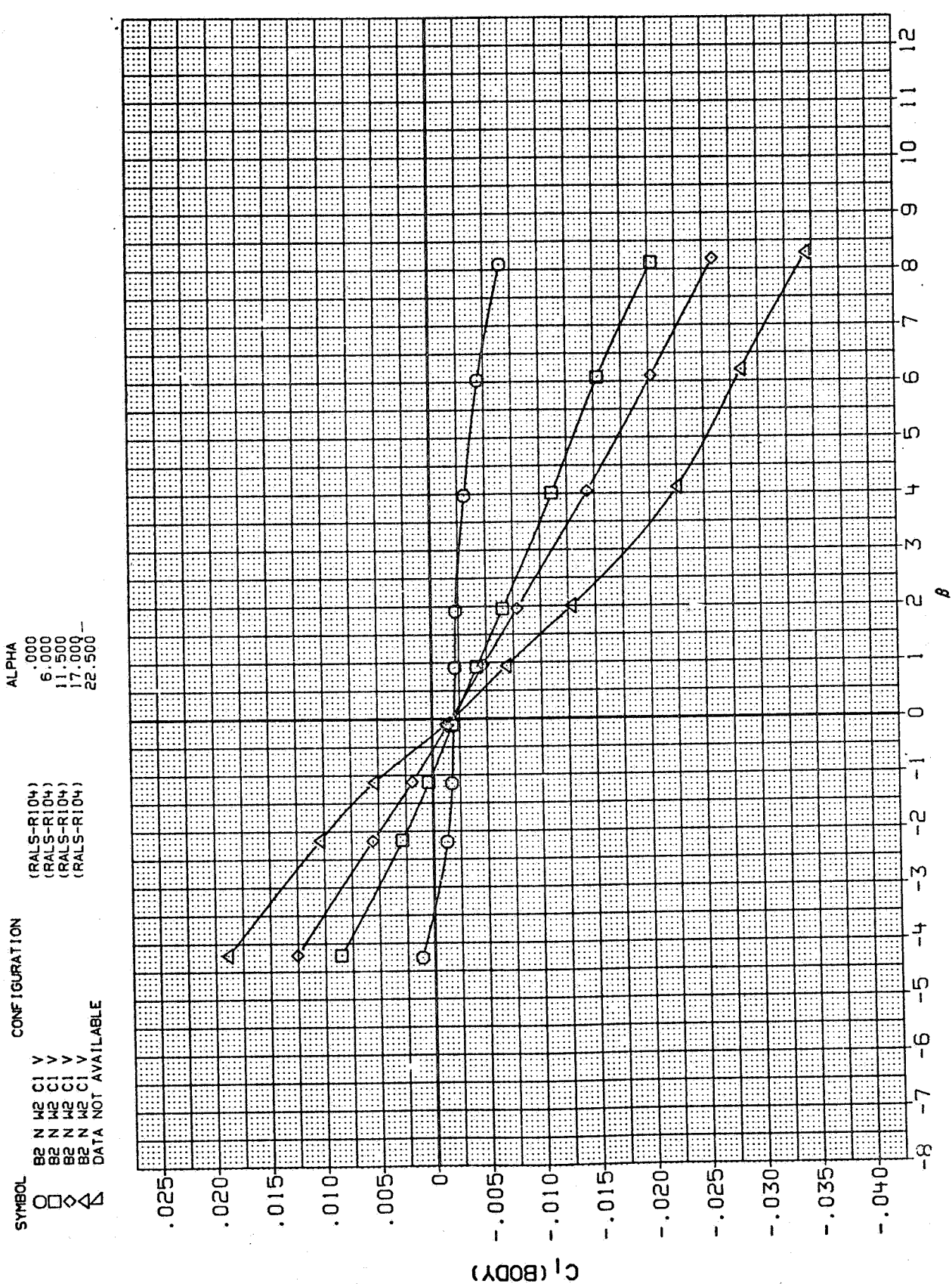


FIG. 94 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
□	B2 N W2 C1 V	.000
◇	B2 N W2 C1 V	6.000
△	B2 N W2 C1 V	11.500
△	B2 N W2 C1 V	17.000
△	B2 N W2 C1 V	22.500
△	DATA NOT AVAILABLE	

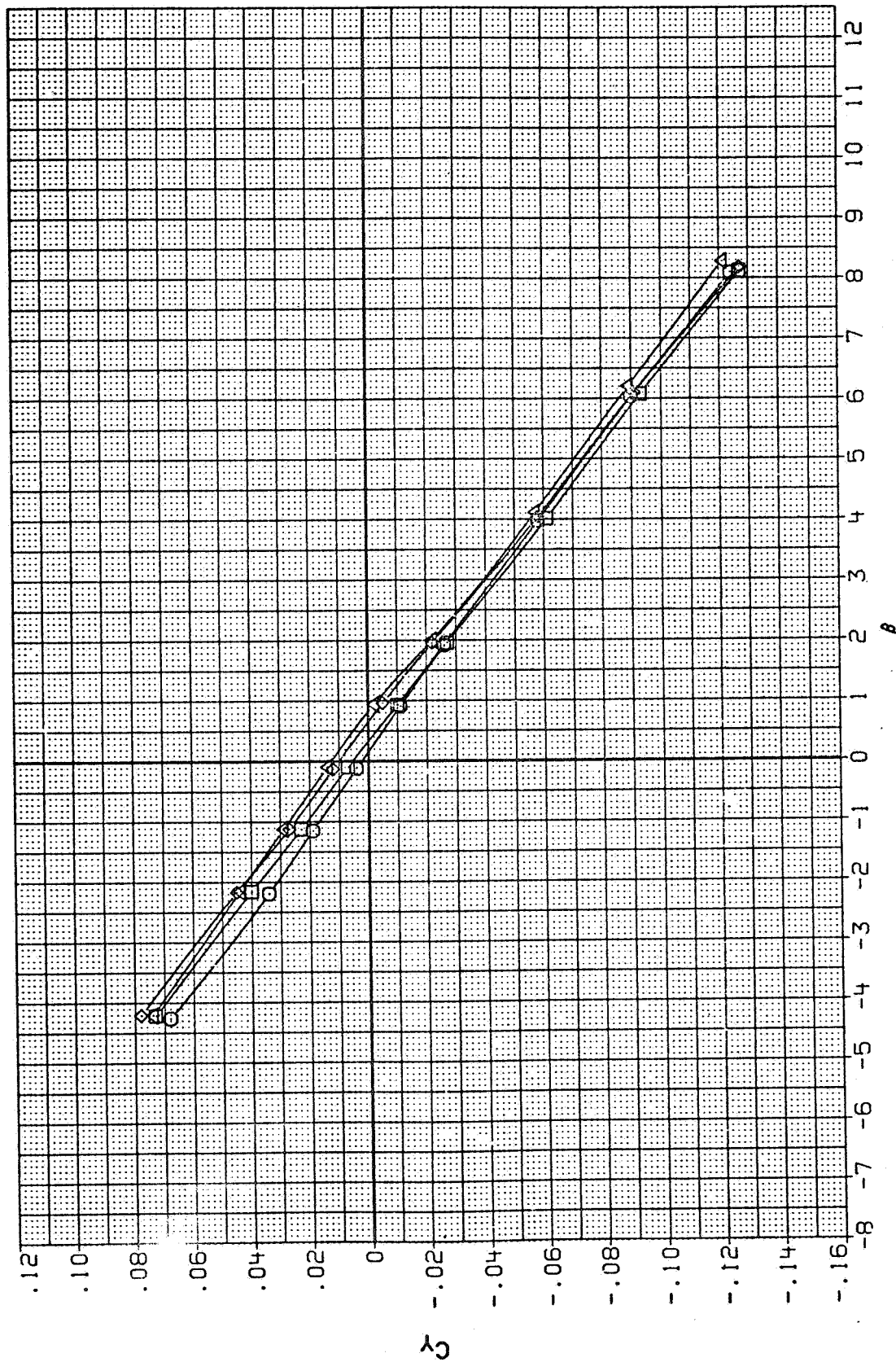


FIG. 94 BASIC LATERAL/DIRECTIONAL CHARACTERISTICS FOR VARIOUS ALPHA

MACH = 1.20

(RALS-R104)

CONFIGURATION B2 N W2 C1 V
MACH .598
RN/L .901
LE-W .000
TE-W .000
CANARD LE-C .000
PARAMETRIC VALUES
TE-C VERT .000

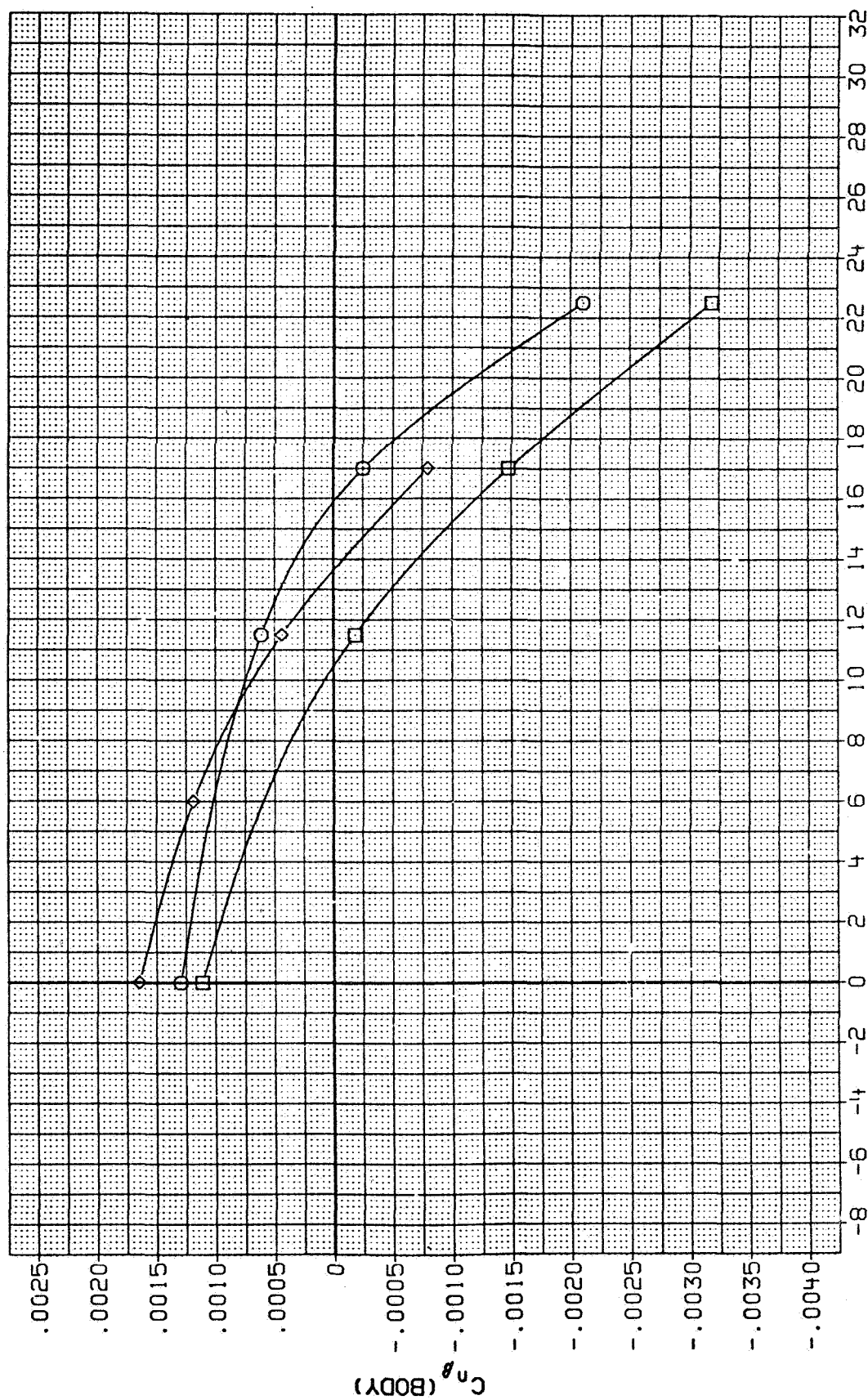


FIG. 95 SUMMARY OF BASIC LATERAL/DIRECTIONAL CHARACTERISTICS WITH ALPHA

(RALS-R104)

CONFIGURATION B2 N W2 C1 V
MACH .598
RN/L 9.843
LE-W .000
TE-W .000
CANARD .000
LE-C .000
PARAMETRIC VALUES
TE-C
VERT

SYMBOL
□
◇

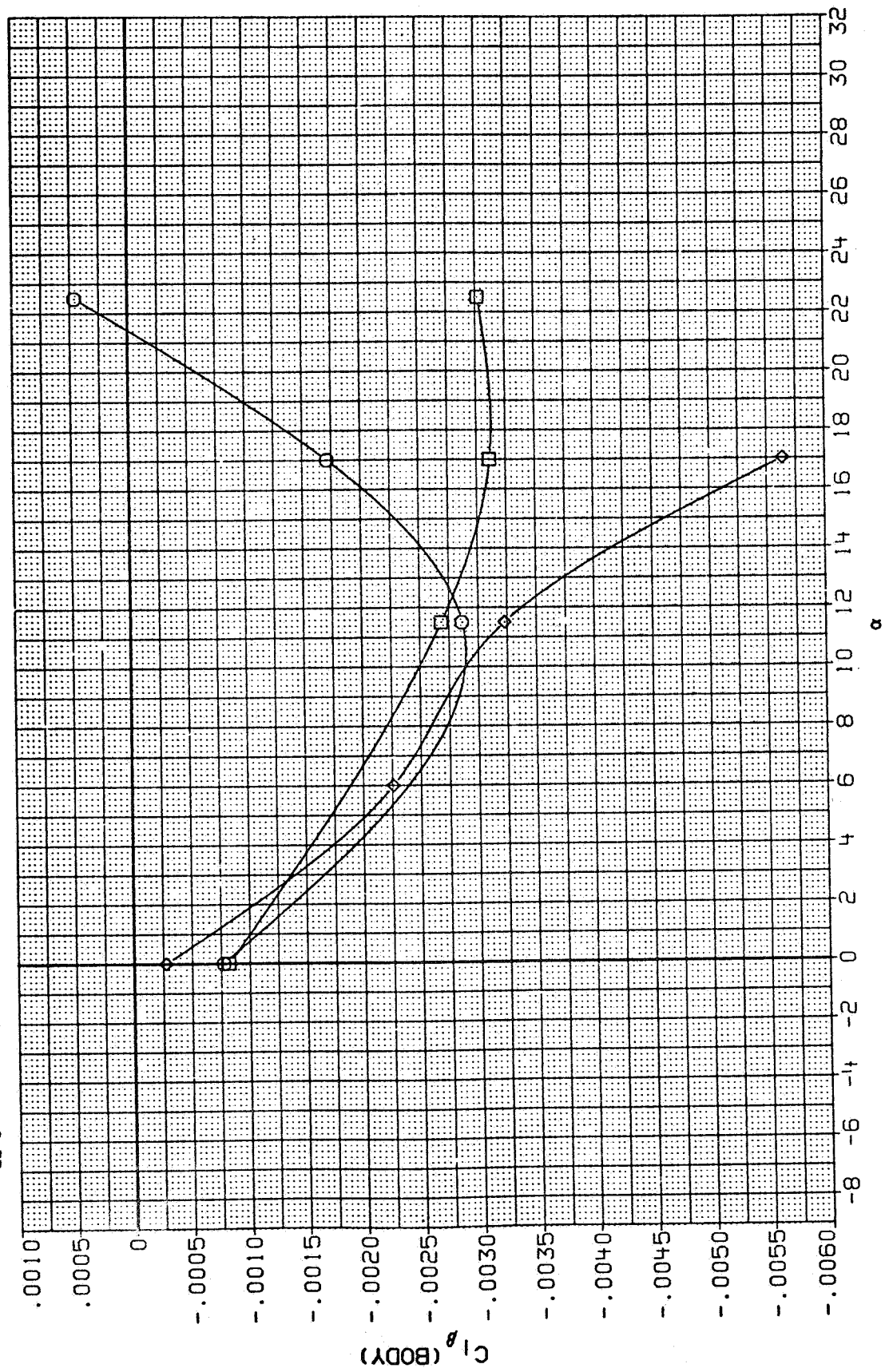


FIG. 95 SUMMARY OF BASIC LATERAL/DIRECTIONAL CHARACTERISTICS WITH ALPHA

(RALS-R104)

CONFIGURATION B2 N W2 C1 V
MACH .598
RN/L 9.843
LE-W .000
TE-W .000
CANARD .000
LE-C .000
PARAMETRIC VALUES
TE-C
VERT

SYMBOL
□
◇

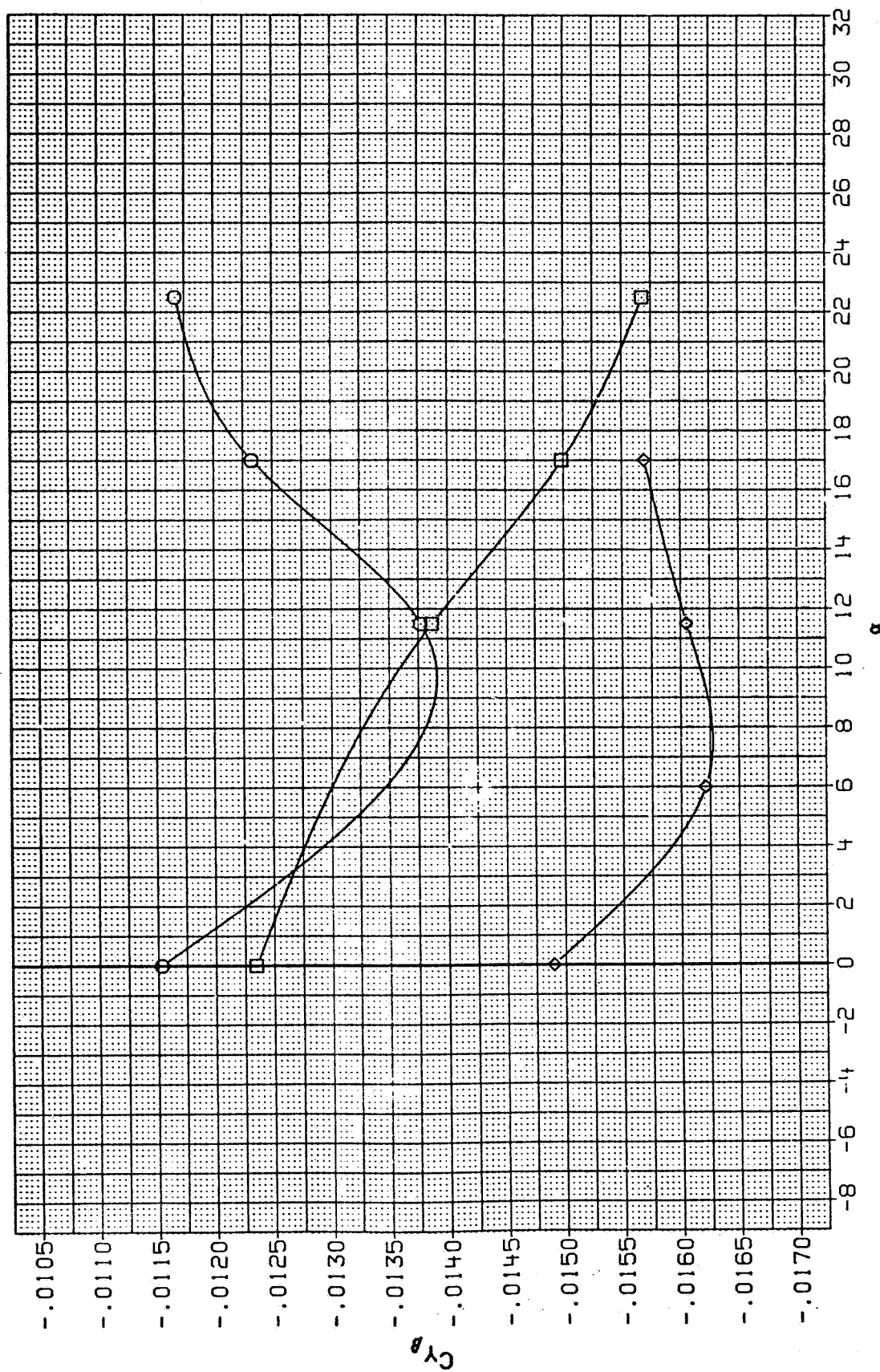


FIG. 95 SUMMARY OF BASIC LATERAL/DIRECTIONAL CHARACTERISTICS WITH ALPHA

SYMBOL	CONFIGURATION	ALPHA
○	B2 N W2 C1 V	.000
□	B2 N W2 C1 V	17.000
◇	B2 N W2 V	.000
△	B2 N W2 V	16.500

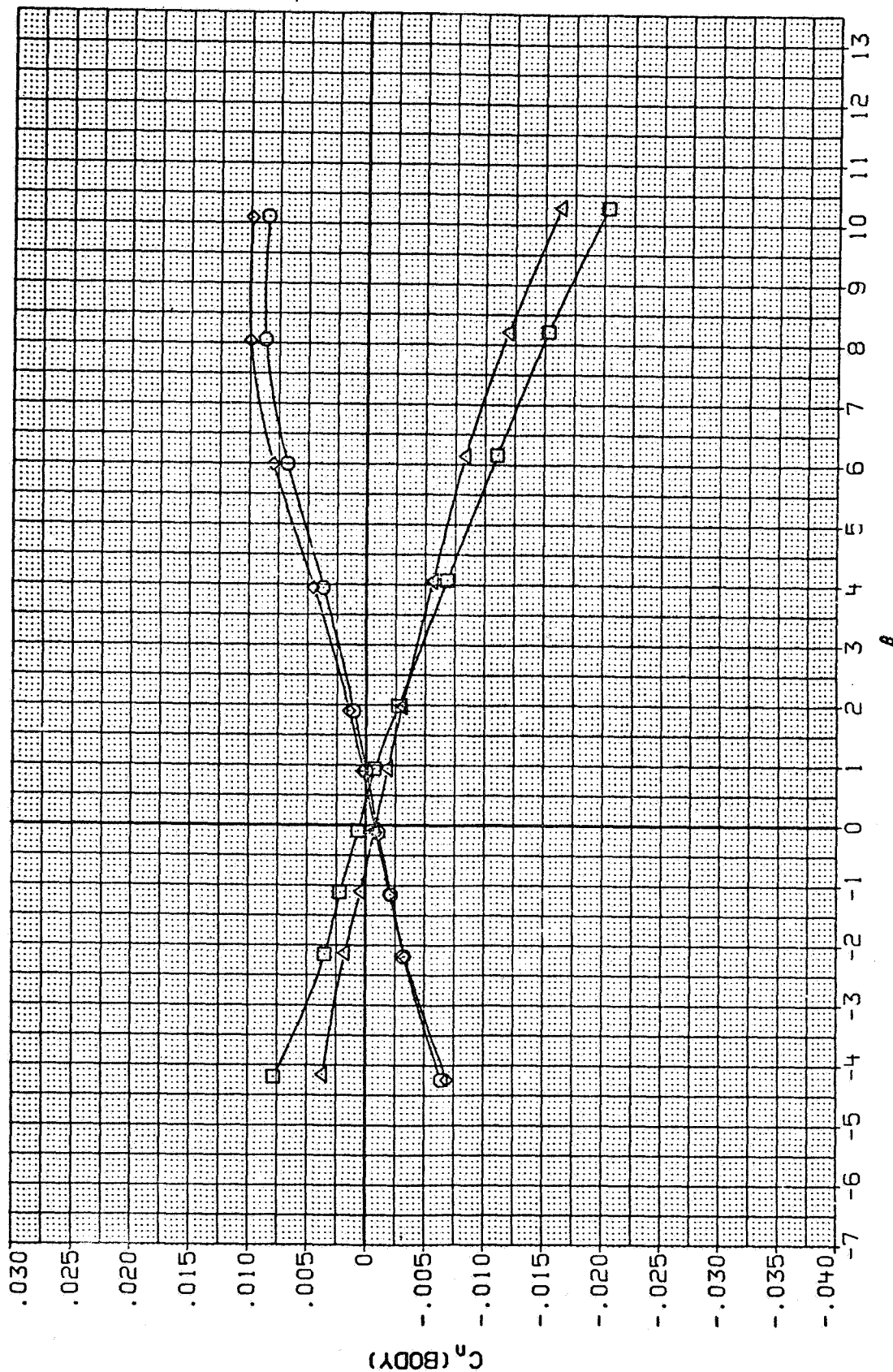


FIG. 96 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = .90

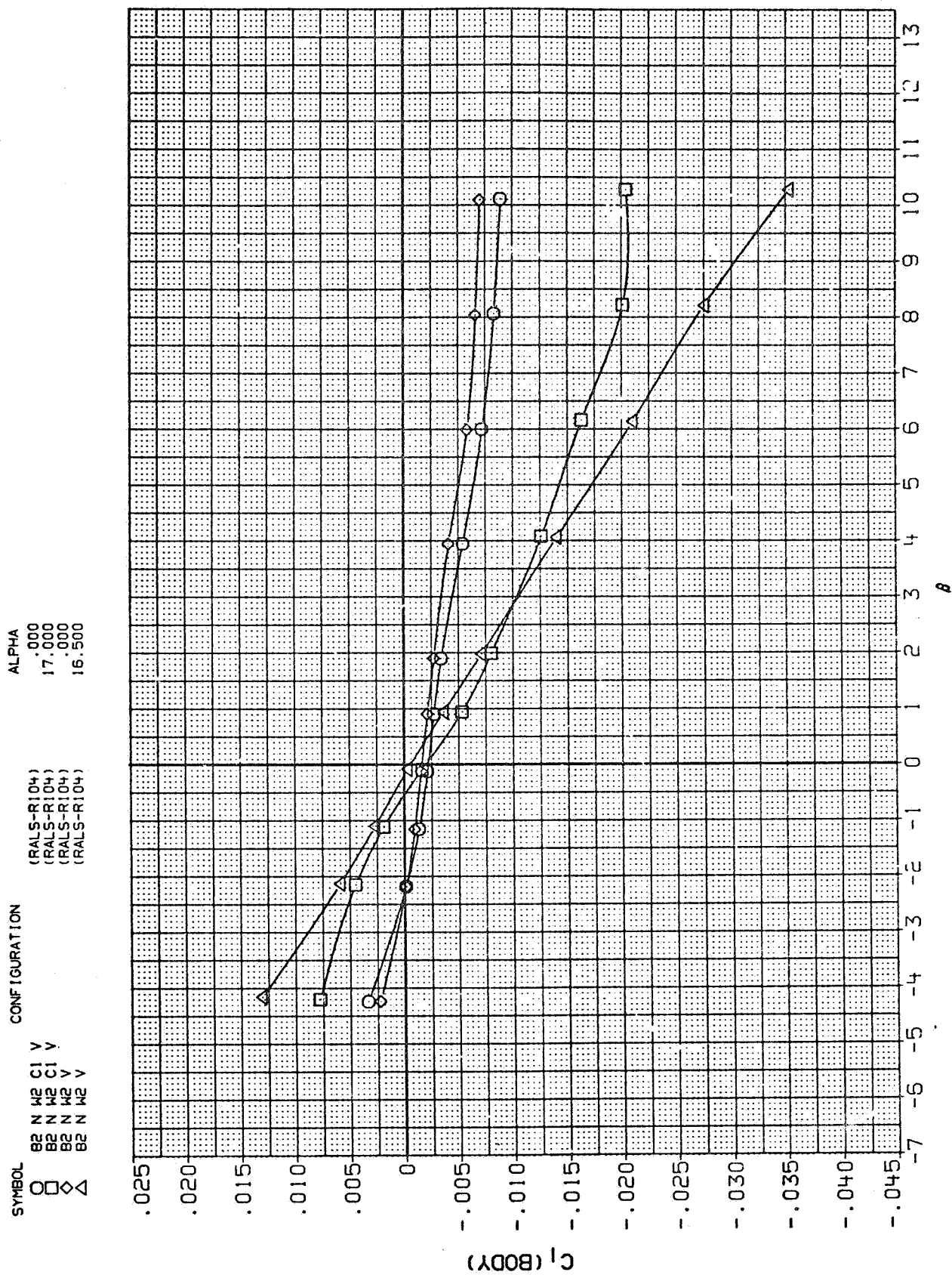


FIG. 96 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = .90

SYMBOL	CONFIGURATION	ALPHA
○	B2 N W2 C1 V	.000
□	B2 N W2 C1 V	17.000
◇	B2 N W2 V	.000
△	B2 N W2 V	16.500

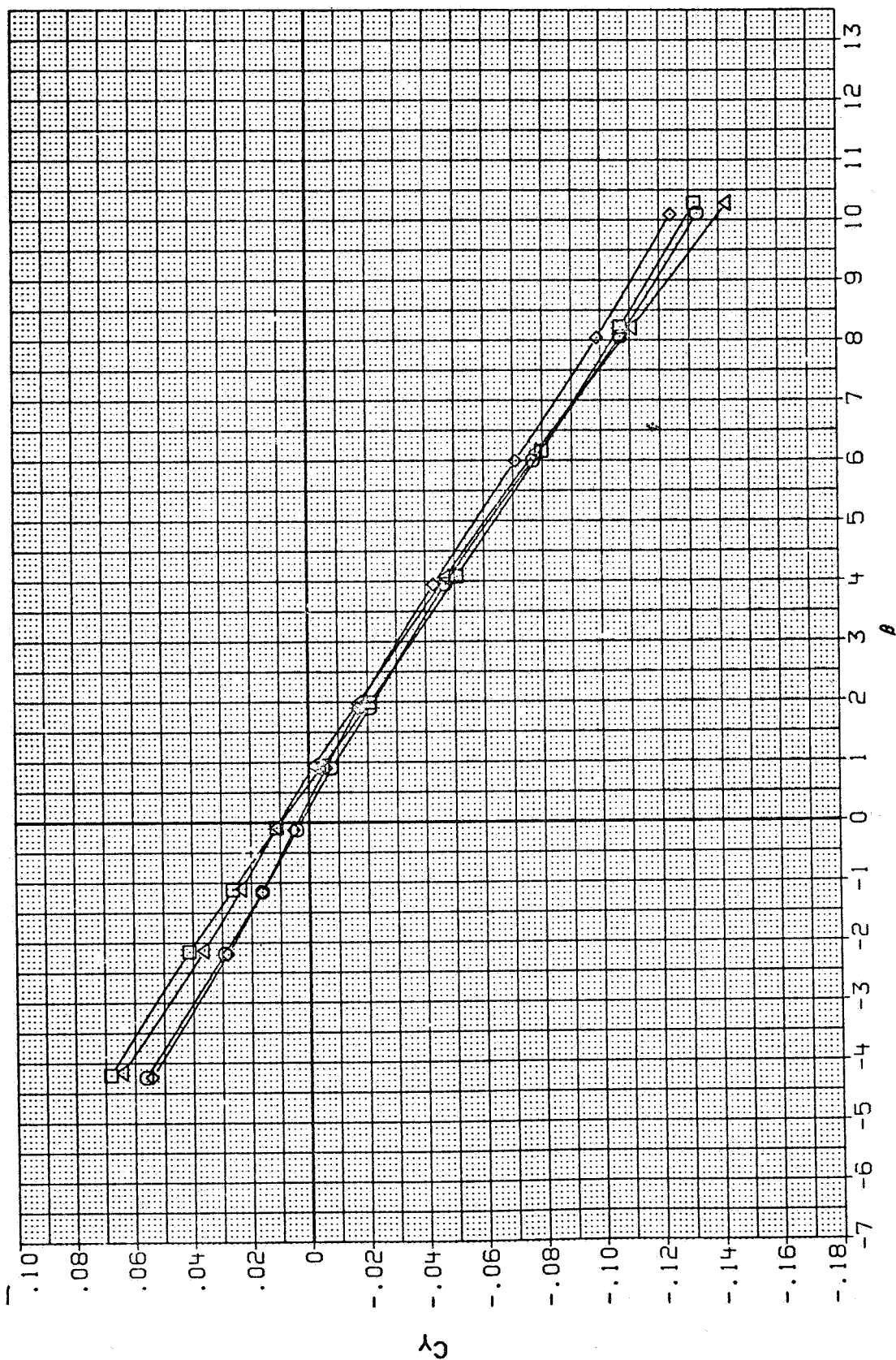


FIG. 96 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = .90

SYMBOL	CONFIGURATION	ALPHA
○	B2 N W2 C1 V	.000
□	B2 N W2 C1 V	11.500
△	B2 N W2 V	.000
△	B2 N W2 V	11.500

(RALS-R104)
(RALS-R104)
(RALS-R104)
(RALS-R104)

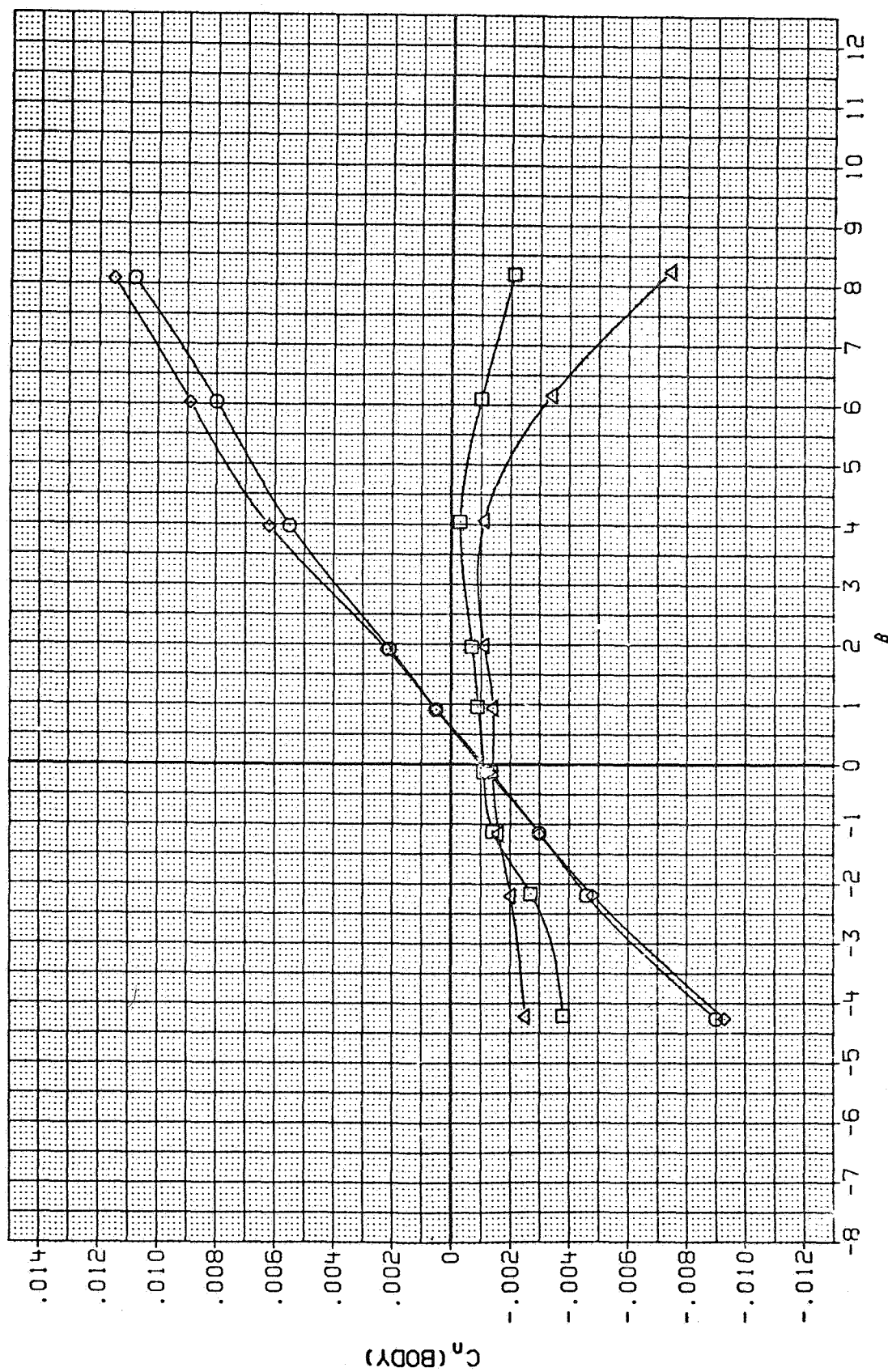


FIG. 97 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
□	(RALS-R104)	.000
○	(RALS-R104)	11.500
△	(RALS-R104)	.000
◇	(RALS-R104)	11.500

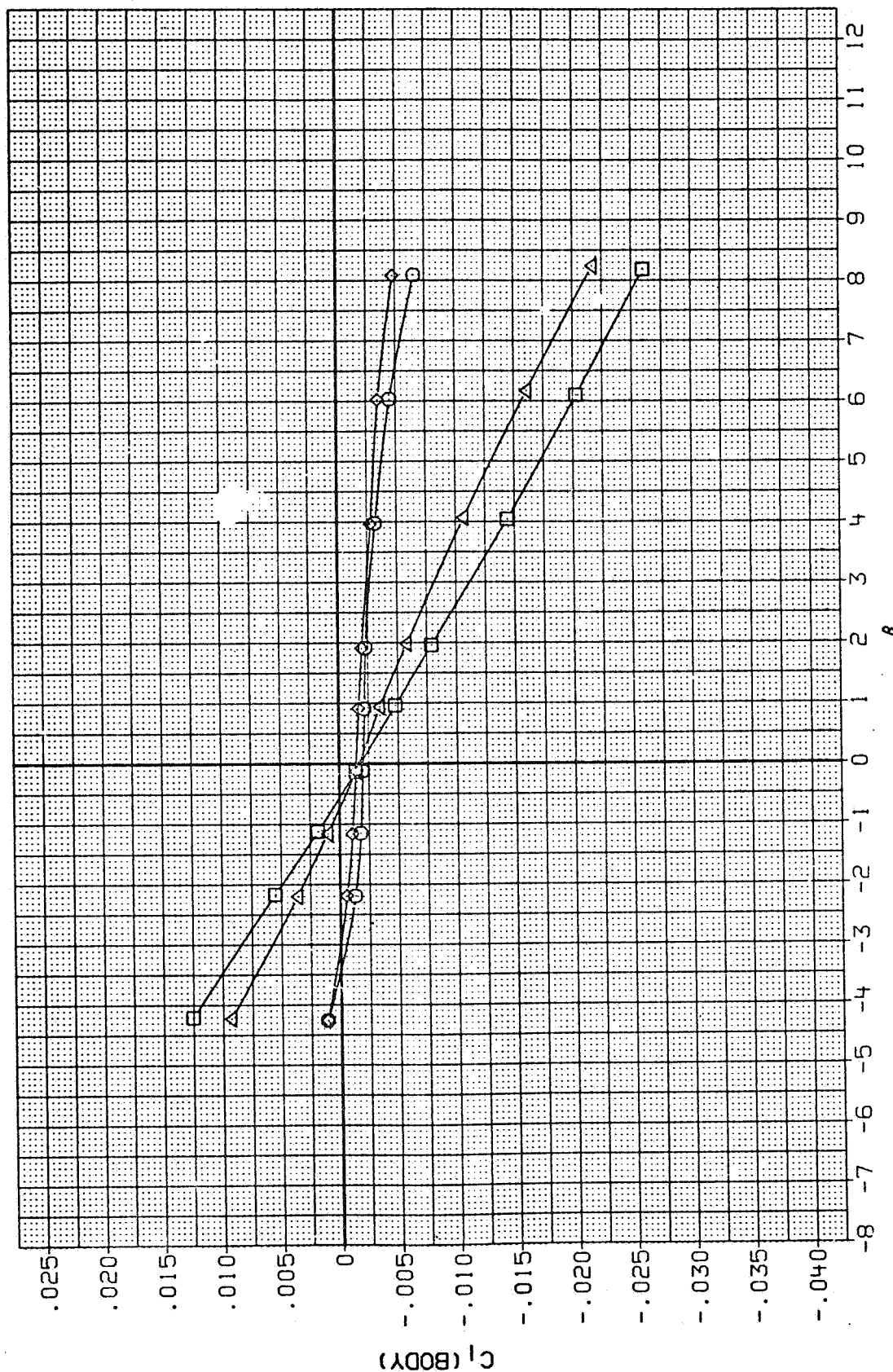


FIG. 97 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = 1.20

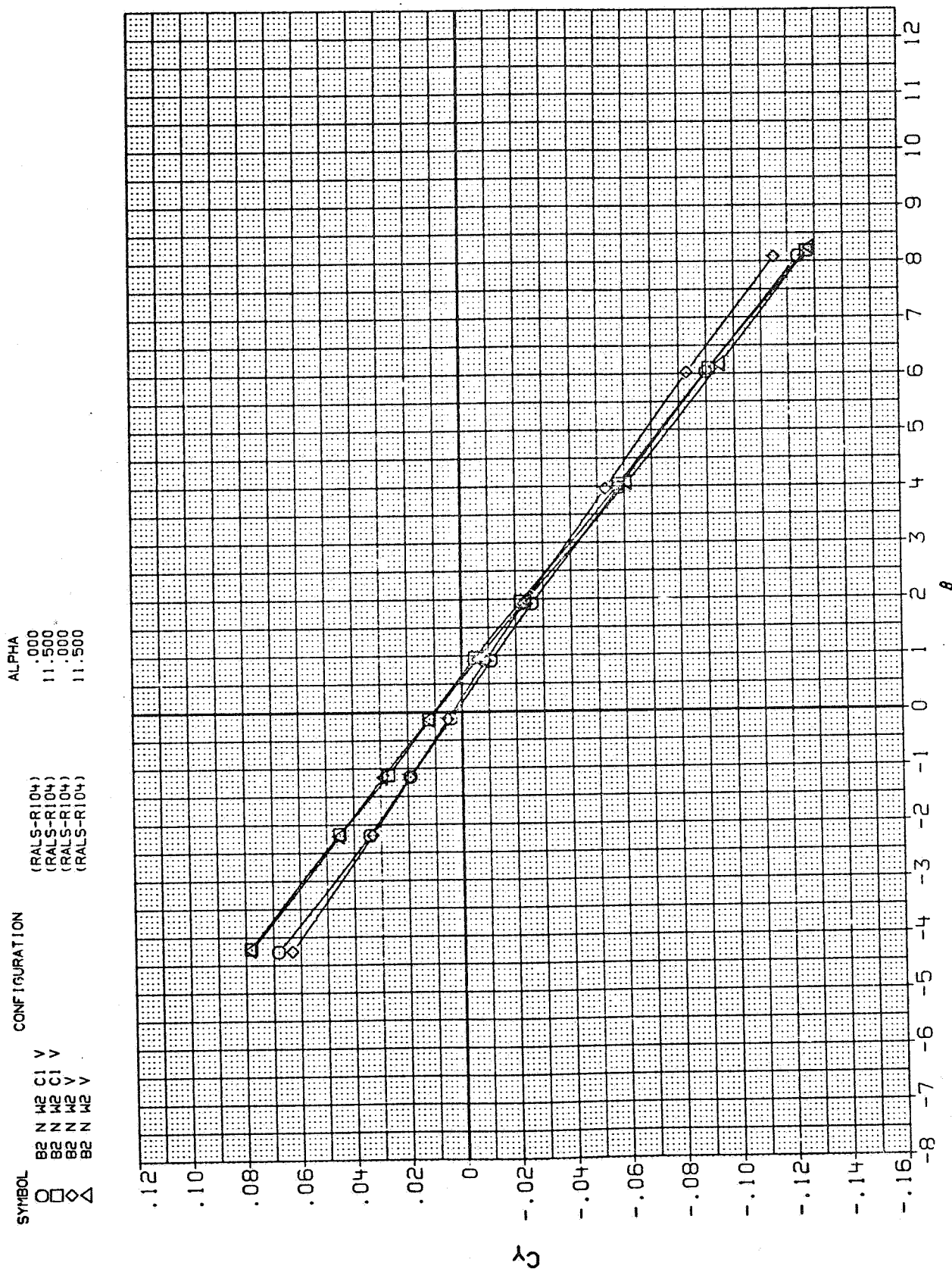


FIG. 97 LATERAL/DIRECTIONAL CHARACTERISTICS, CANARD ON/OFF

MACH = 1.20

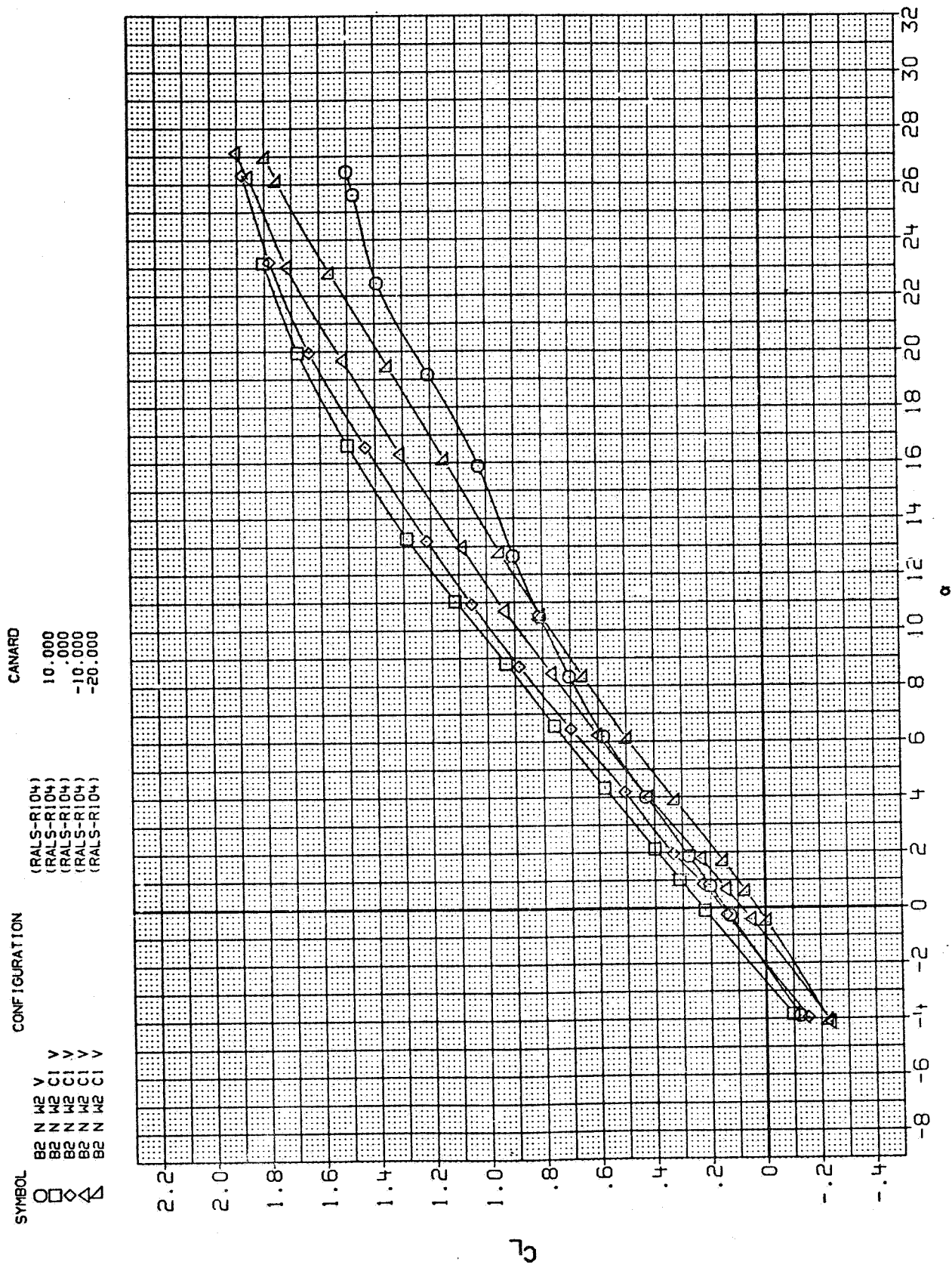


FIG. 98 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .60

SYMBOL	CONFIGURATION	CANARD
○	B2 N W2 V	10.000
◇	B2 N W2 C1 V	.000
△	B2 N W2 C1 V	-10.000
	B2 N W2 C1 V	-20.000

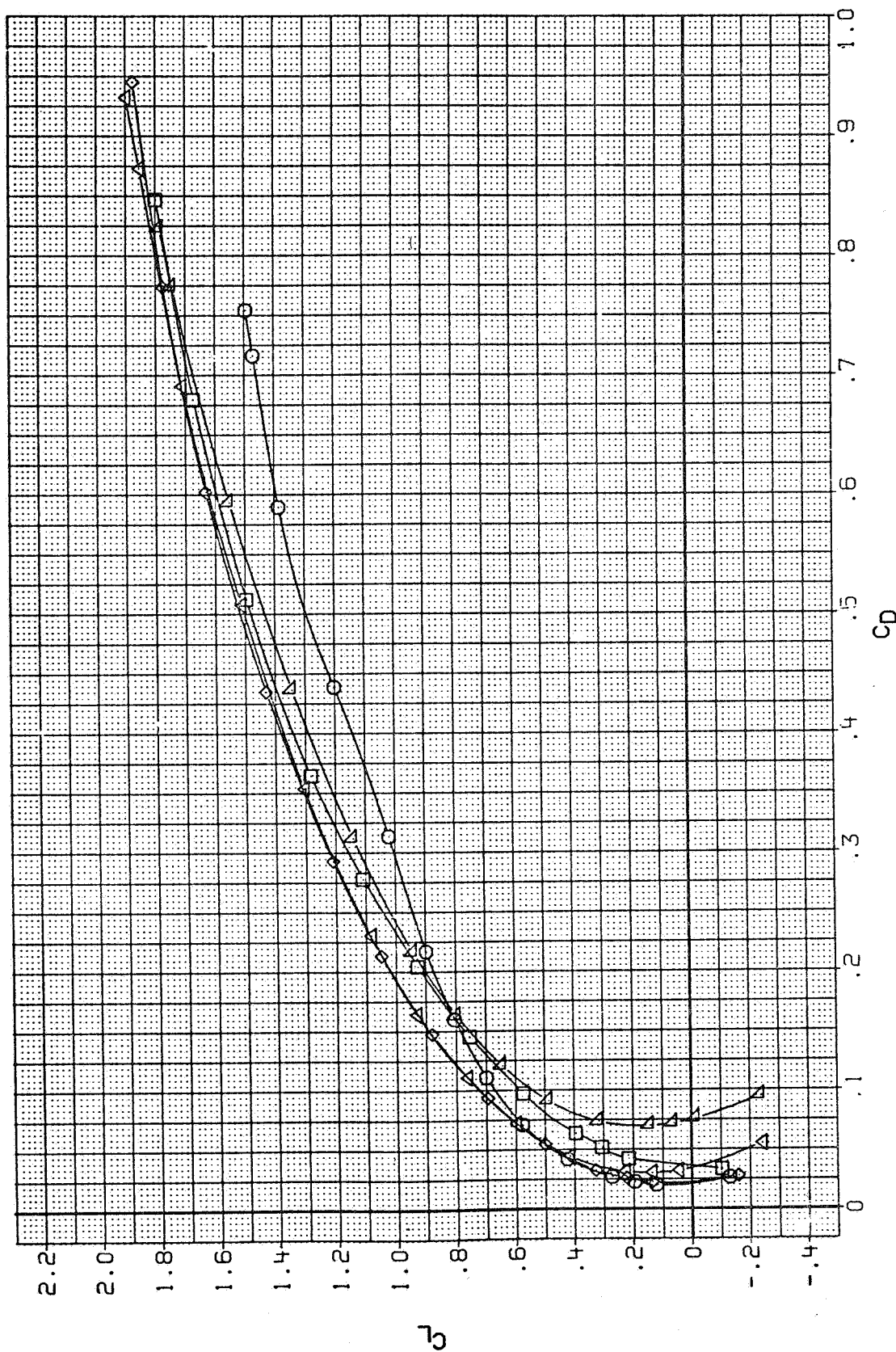


FIG. 98 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .60

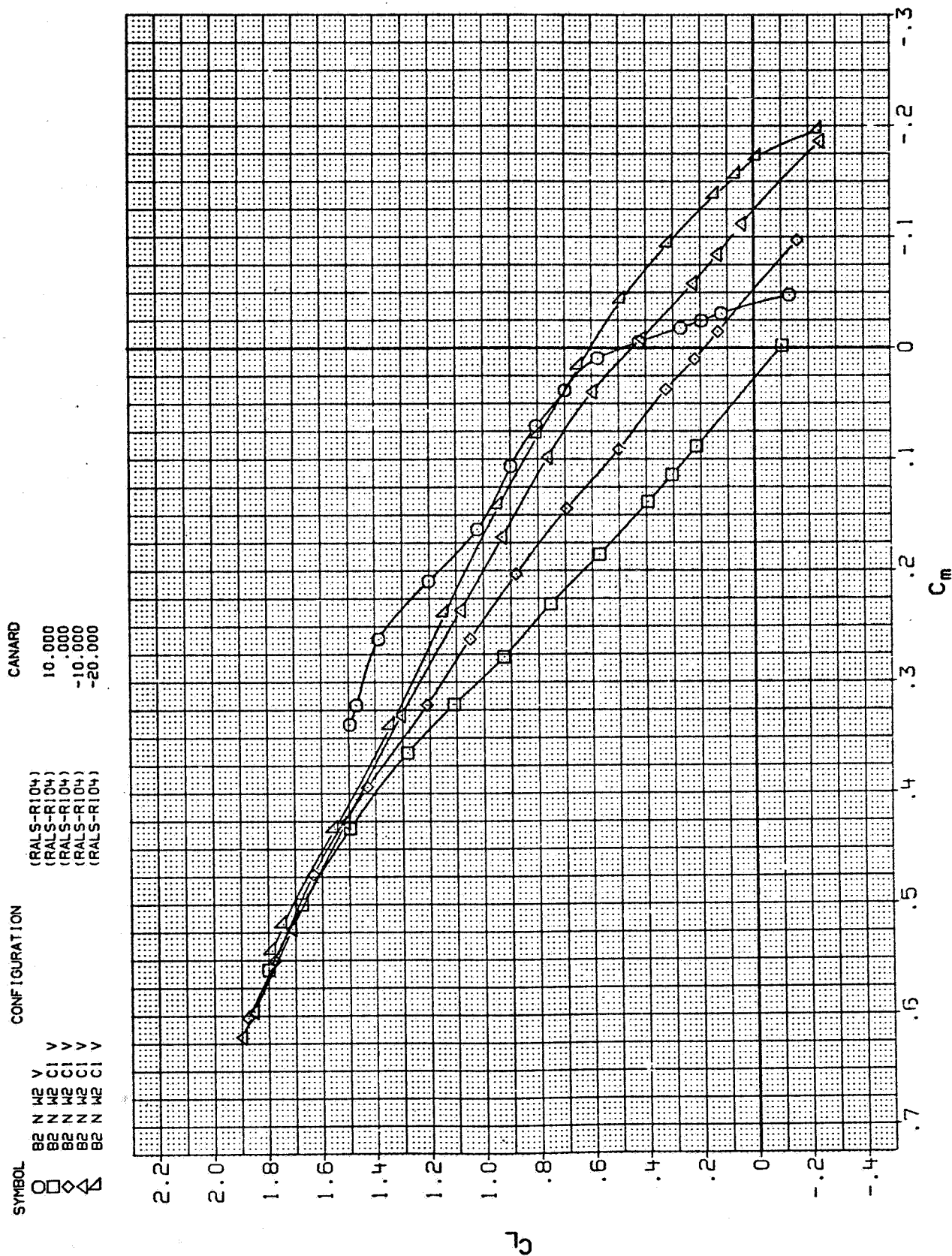


FIG. 98 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .60

CANARD

10.000
 .000
 -10.000
 -20.000

(RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

CONFIGURATION

B2 N W2 V
 B2 N W2 C1 V
 B2 N W2 C1 V
 B2 N W2 C1 V
 B2 N W2 C1 V

SYMBOL
 ○ □ △ ▽

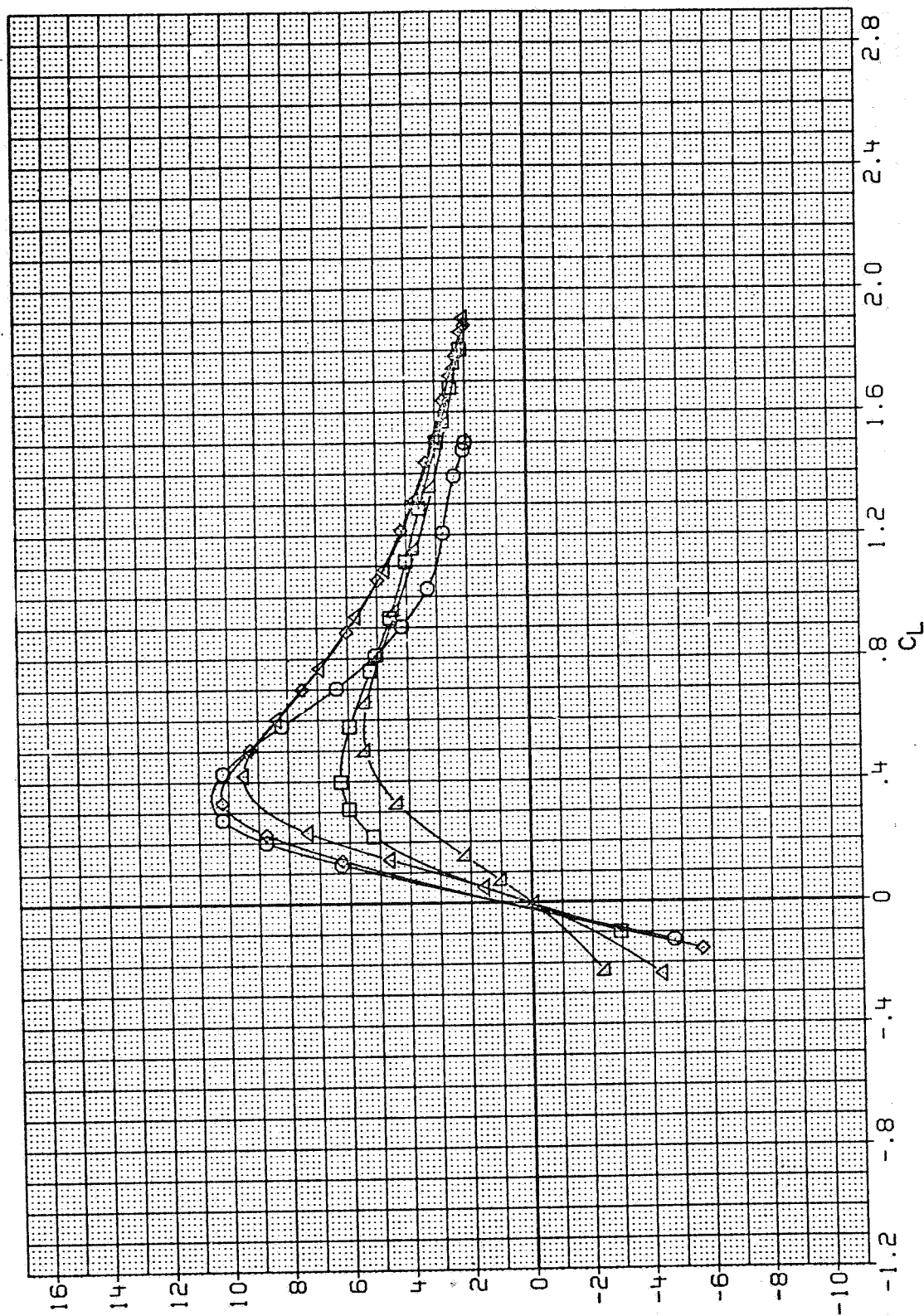


FIG. 98 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .60

SYMBOL	CONFIGURATION	CANARD
○	B2 N W2 V (RALS-R104)	10.000
□	B2 N W2 C1 V (RALS-R104)	.000
◇	B2 N W2 C1 V (RALS-R104)	-10.000
△	B2 N W2 C1 V (RALS-R104)	-20.000

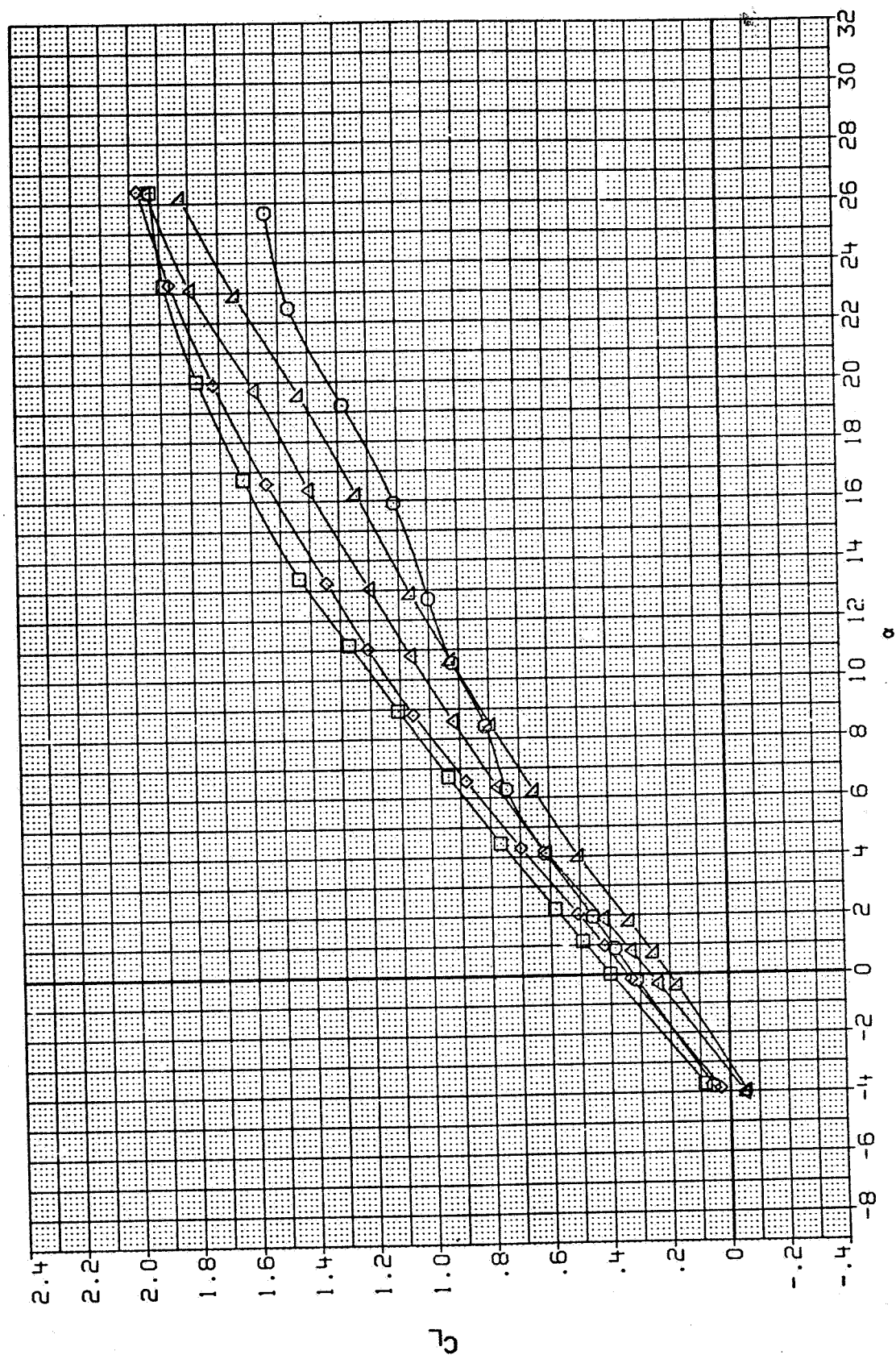


FIG. 99 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .60

SYMBOL	CONFIGURATION	CANARD
□	B2 N W2 V	10.000
◇	B2 N W2 C1 V	.000
△	B2 N W2 C1 V	-10.000
▽	B2 N W2 C1 V	-20.000

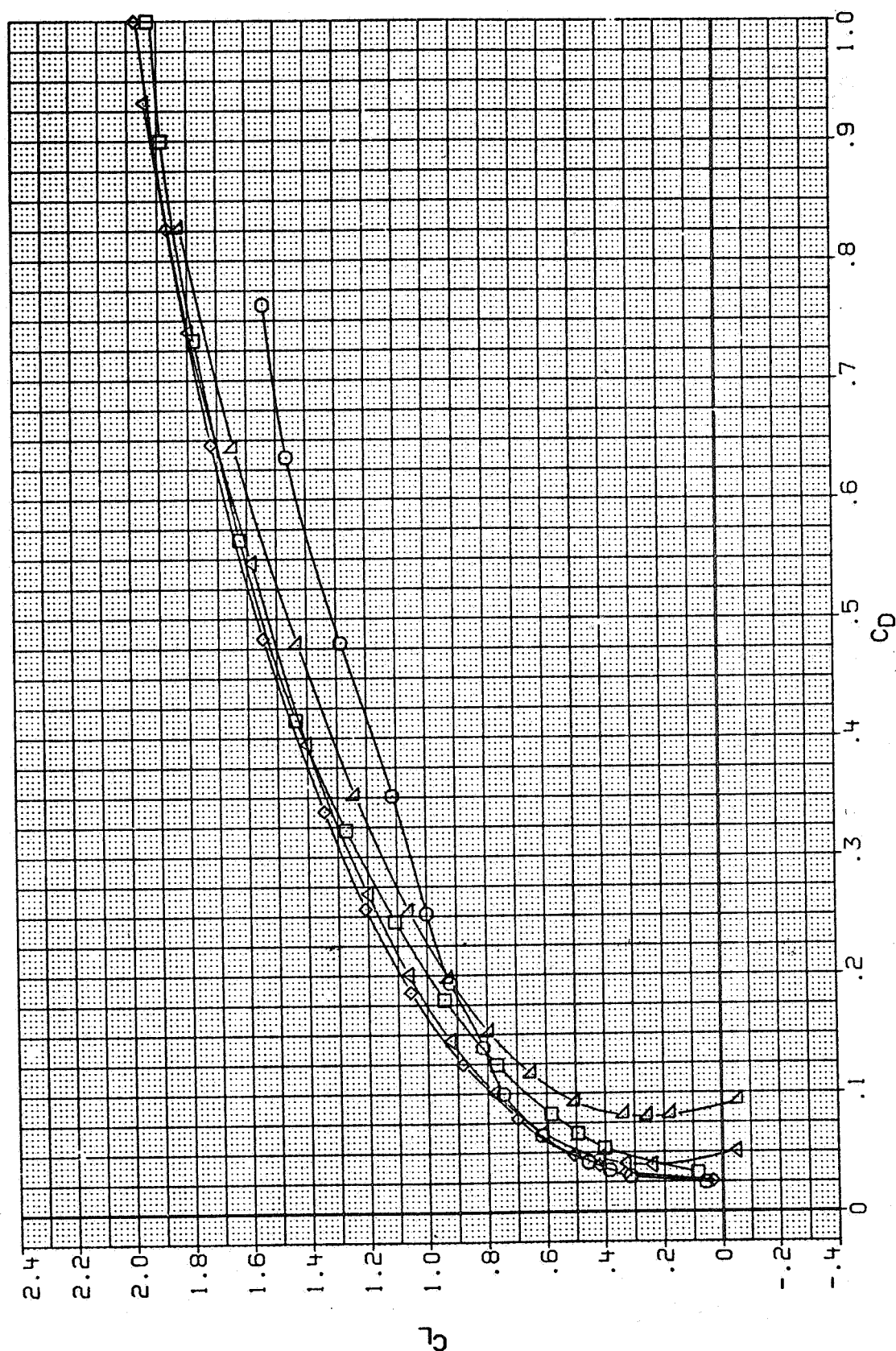


FIG. 99 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .60

SYMBOL	CONFIGURATION	CANARD
○	B2 N W2 V	10.000
□	B2 N W2 C1 V	.000
◇	B2 N W2 C1 V	-10.000
△	B2 N W2 C1 V	-20.000

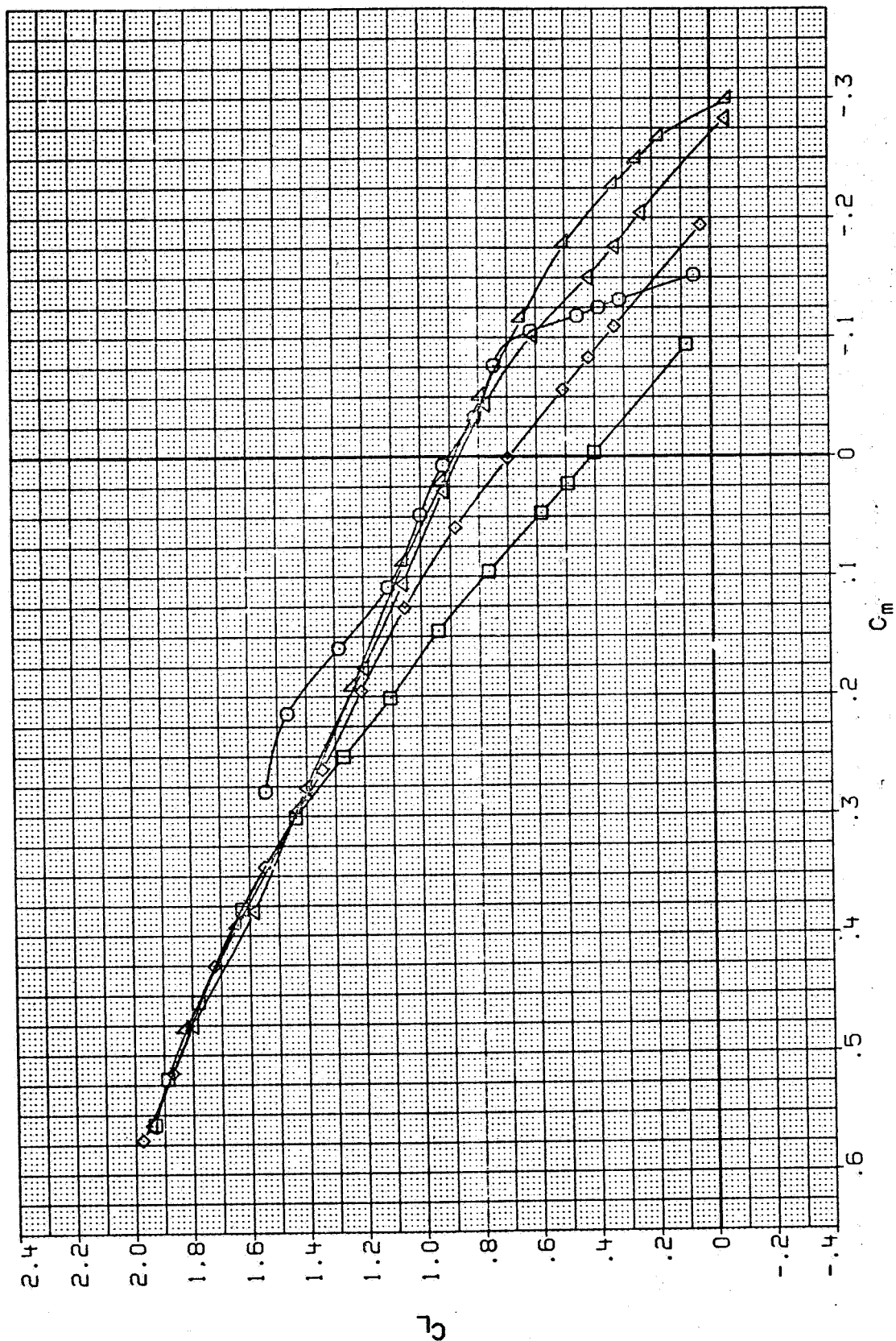


FIG. 99 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .60

SYMBOL	CONFIGURATION	CANARD
□	B2 N W2 V	10.000
◇	B2 N W2 C1 V	.000
△	B2 N W2 C1 V	-10.000
	B2 N W2 C1 V	-20.000

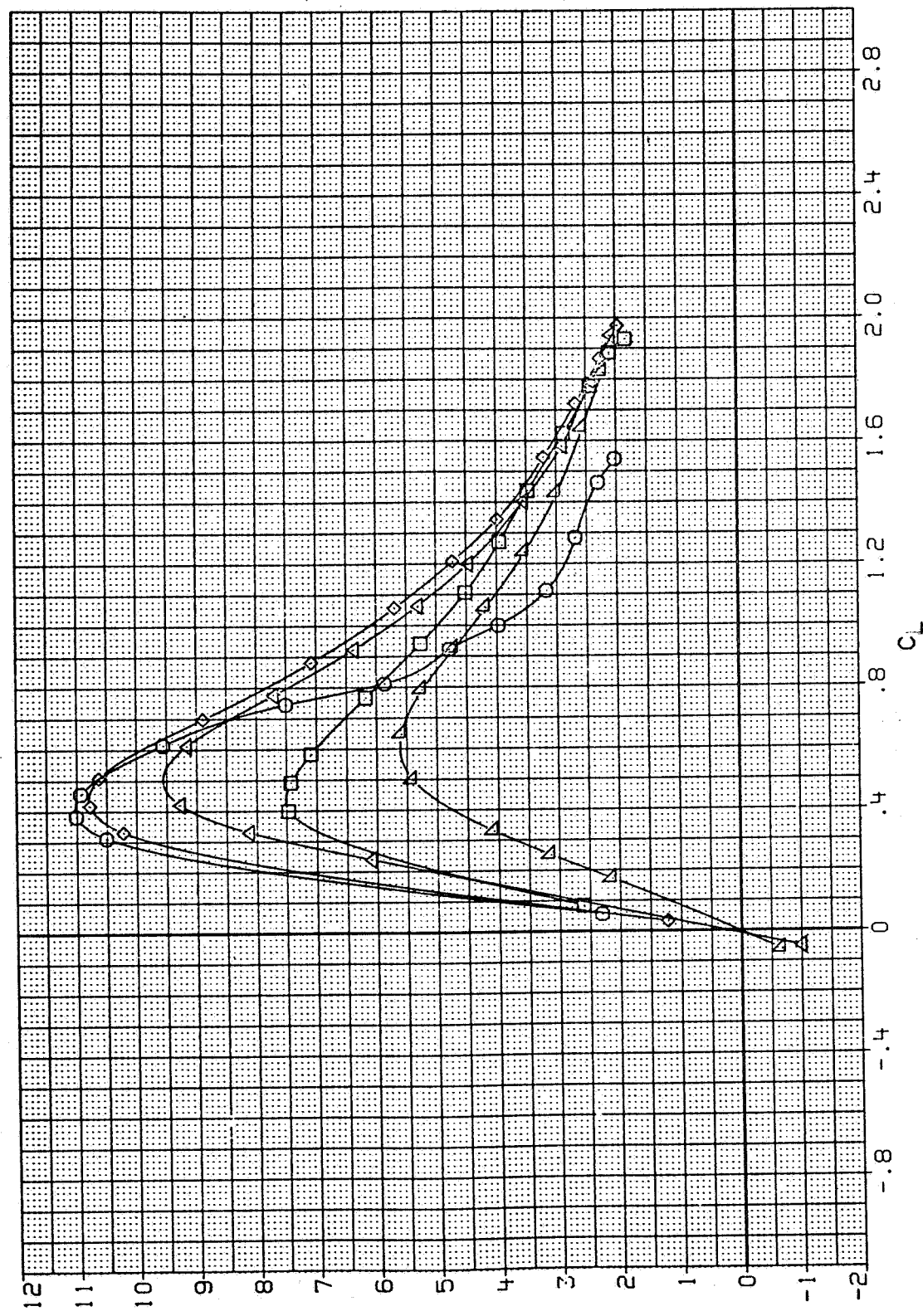


FIG. 99 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .60

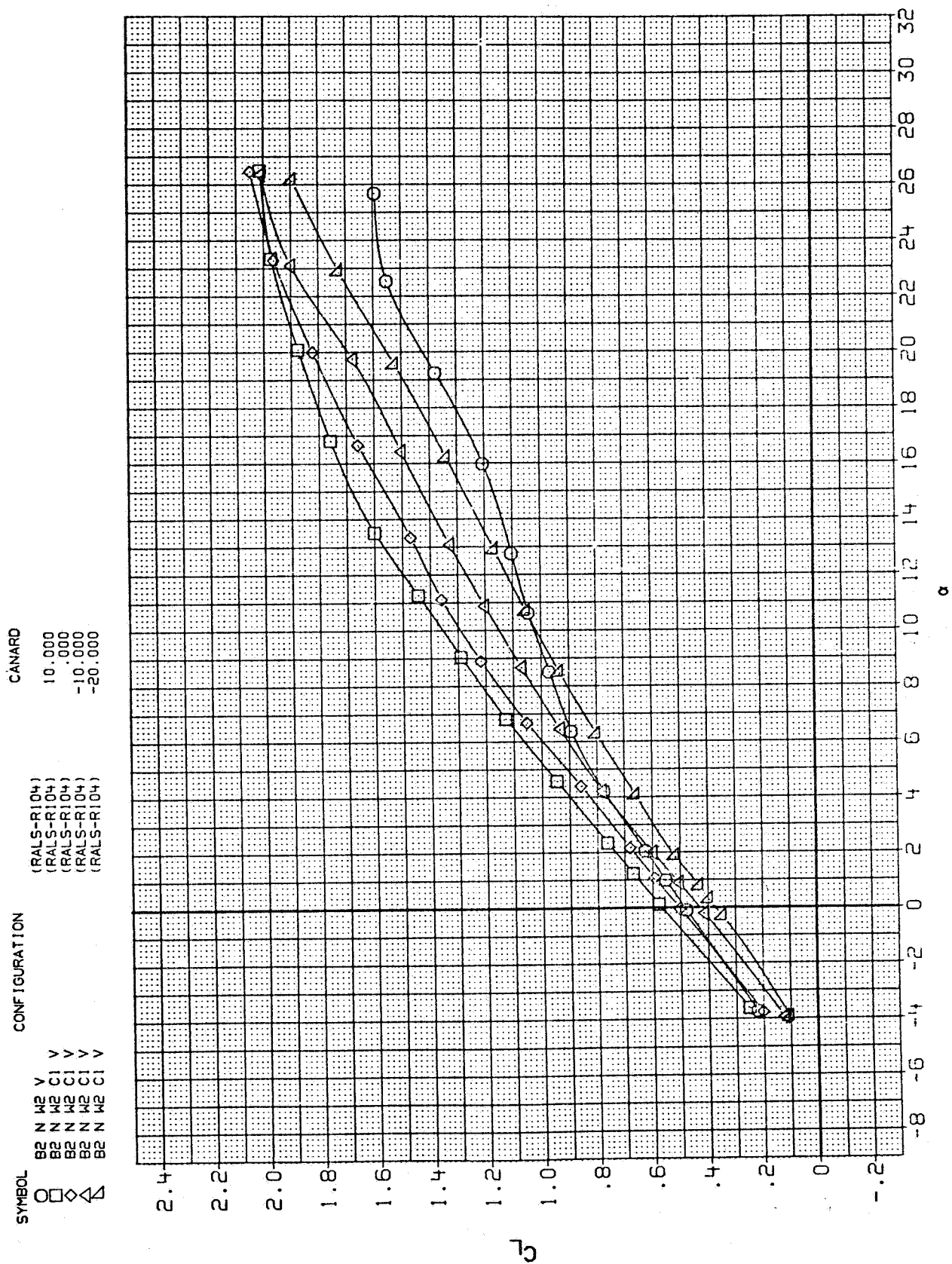


FIG. 100 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .60

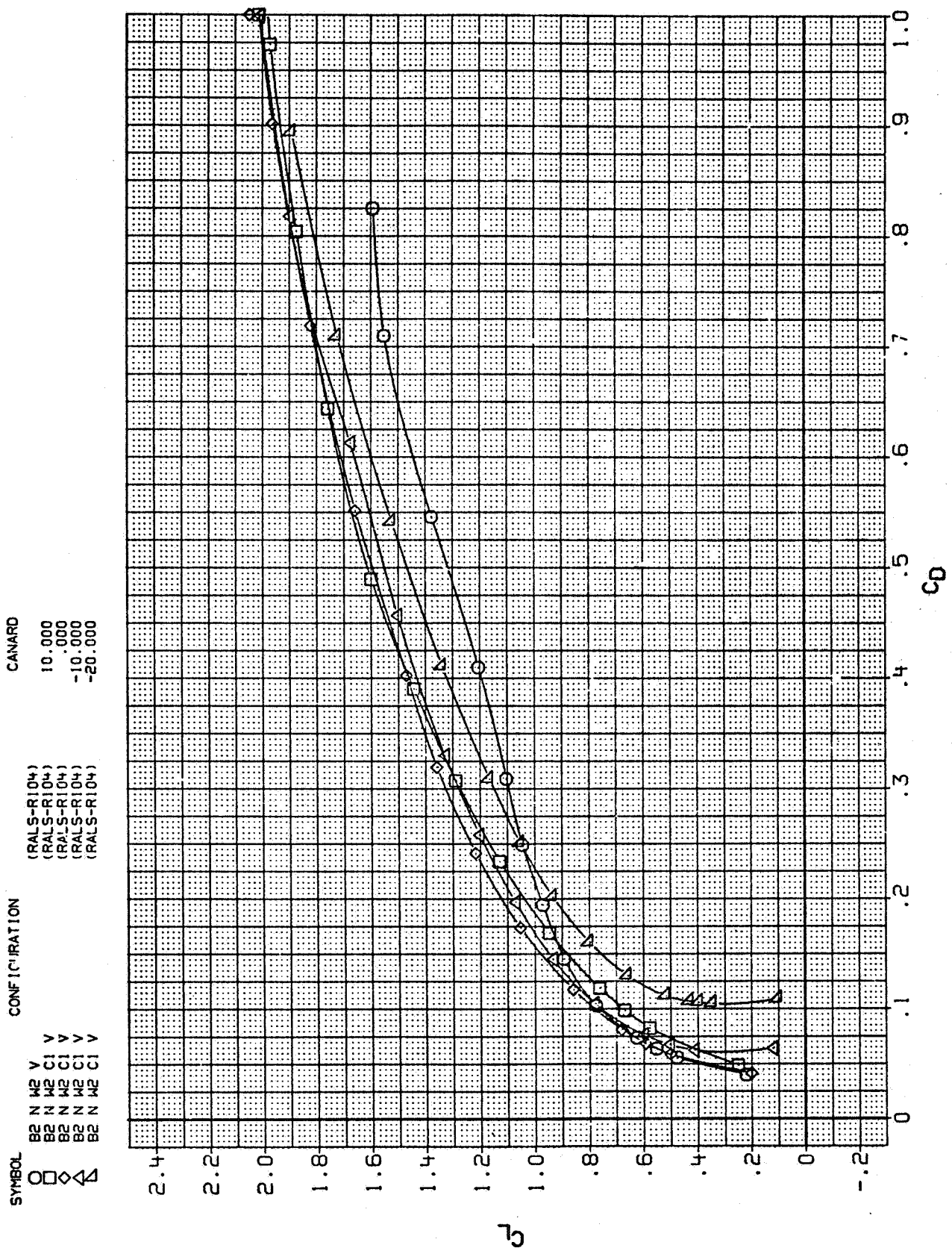


FIG. 100 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES
MACH = .60

SYMBOL	CONFIGURATION	CANARD
B2 N W2 V	(RALS-R104)	10.000
B2 N W2 C1 V	(RALS-R104)	.000
B2 N W2 C1 V	(RALS-R104)	-10.000
B2 N W2 C1 V	(RALS-R104)	-20.000

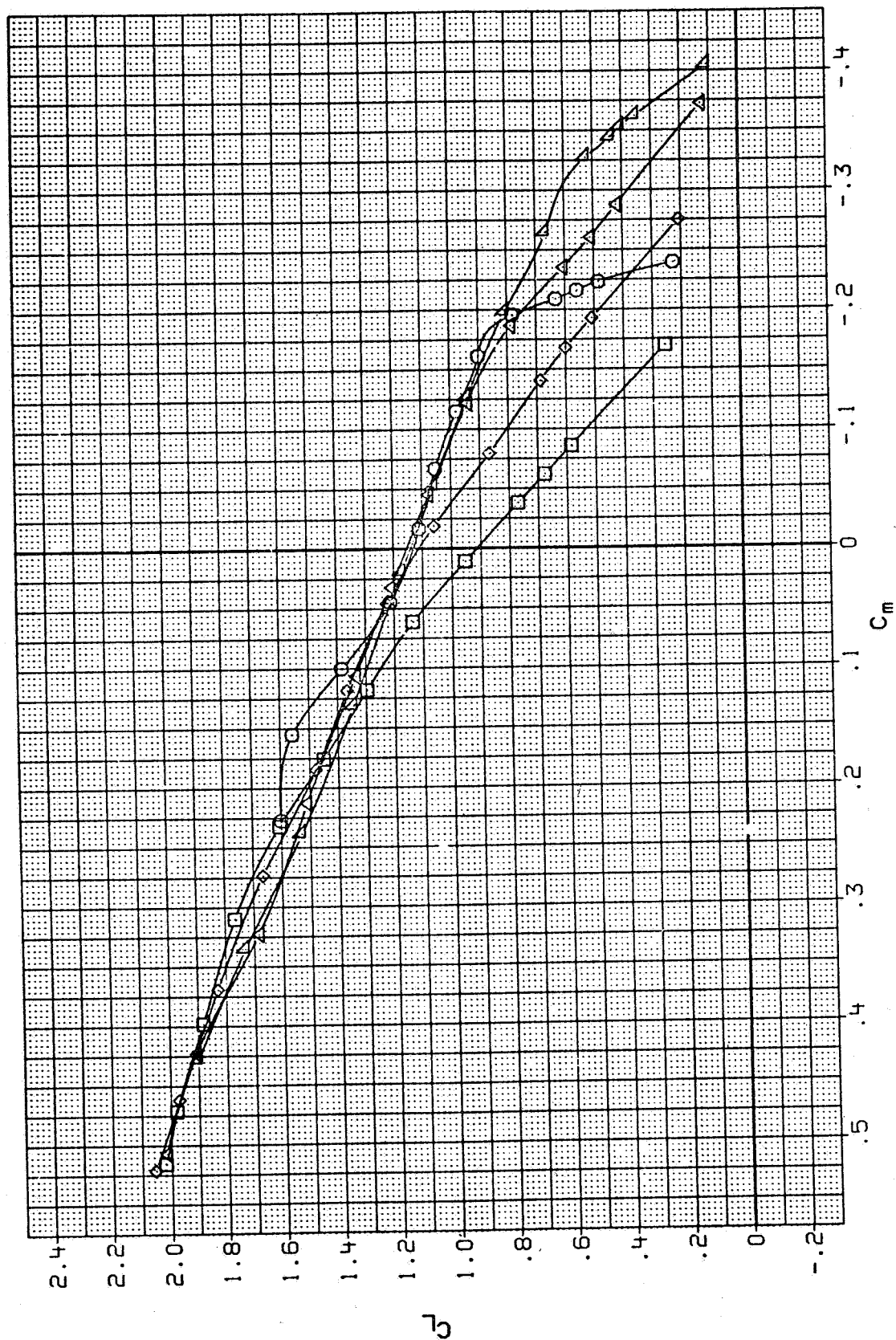


FIG. 100 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .60

SYMBOL	CONFIGURATION	CANARD
○	B2 N W2 V	10.000
□	B2 N W2 C1 V	10.000
△	B2 N W2 C1 V	-10.000
	B2 N W2 C1 V	-20.000
	(RALS-R104)	
	(RALS-R104)	
	(RALS-R104)	
	(RALS-R104)	

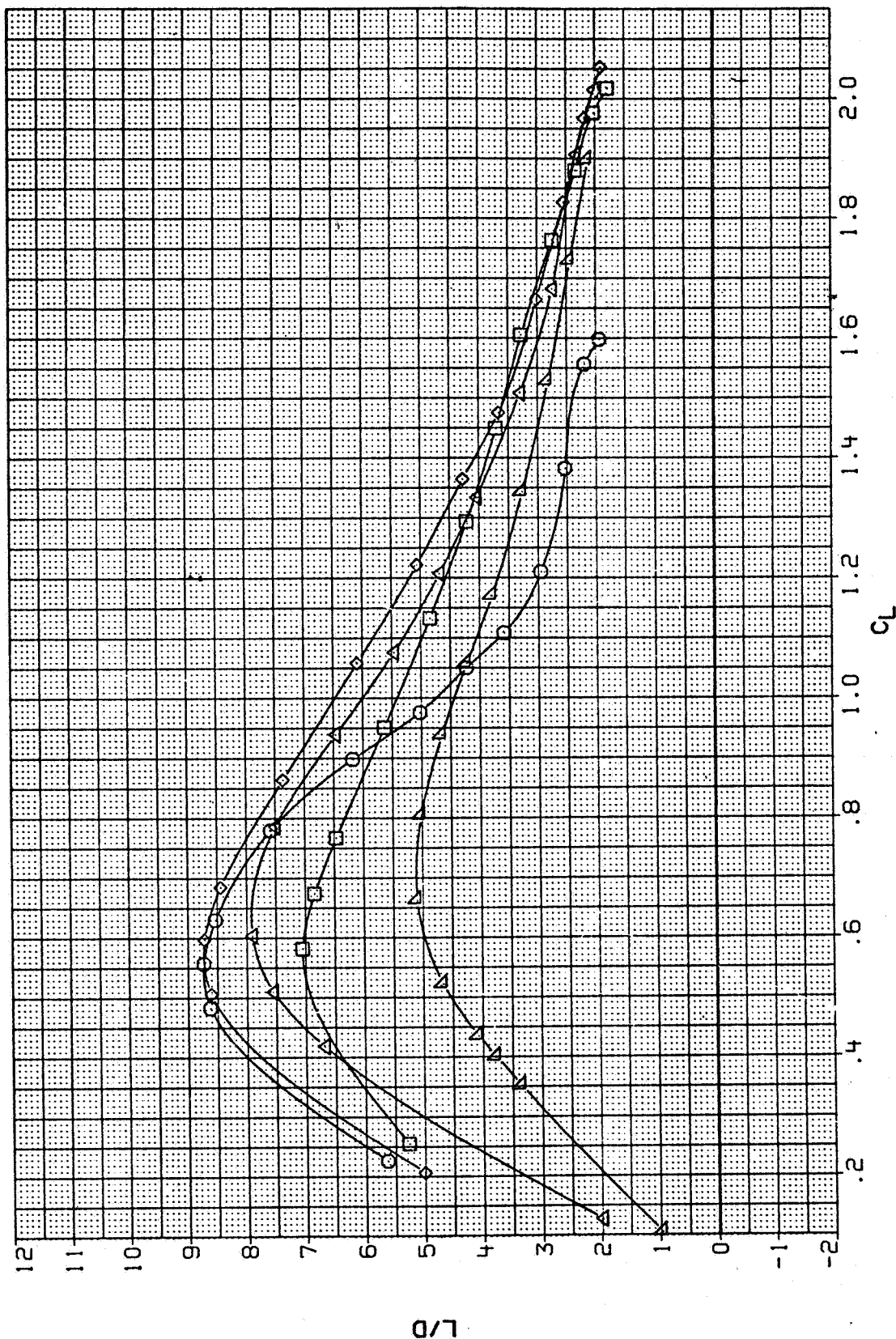
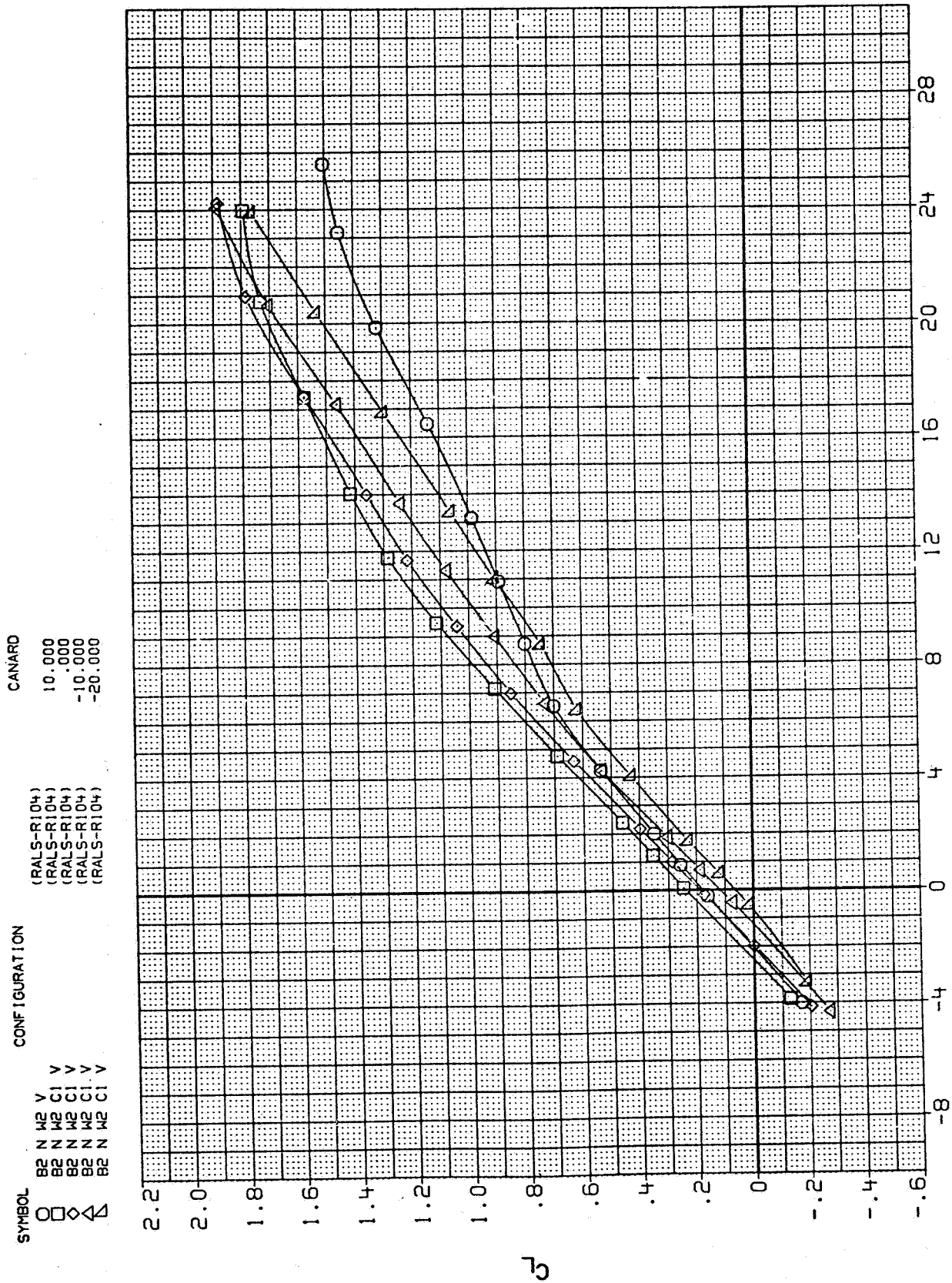


FIG. 100 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .60



SYMBOL	CONFIGURATION	CANARD
○	B2 N W2 V	10.000
□	B2 N W2 C1 V	.000
◇	B2 N W2 C1 V	-10.000
△	B2 N W2 C1 V	-20.000

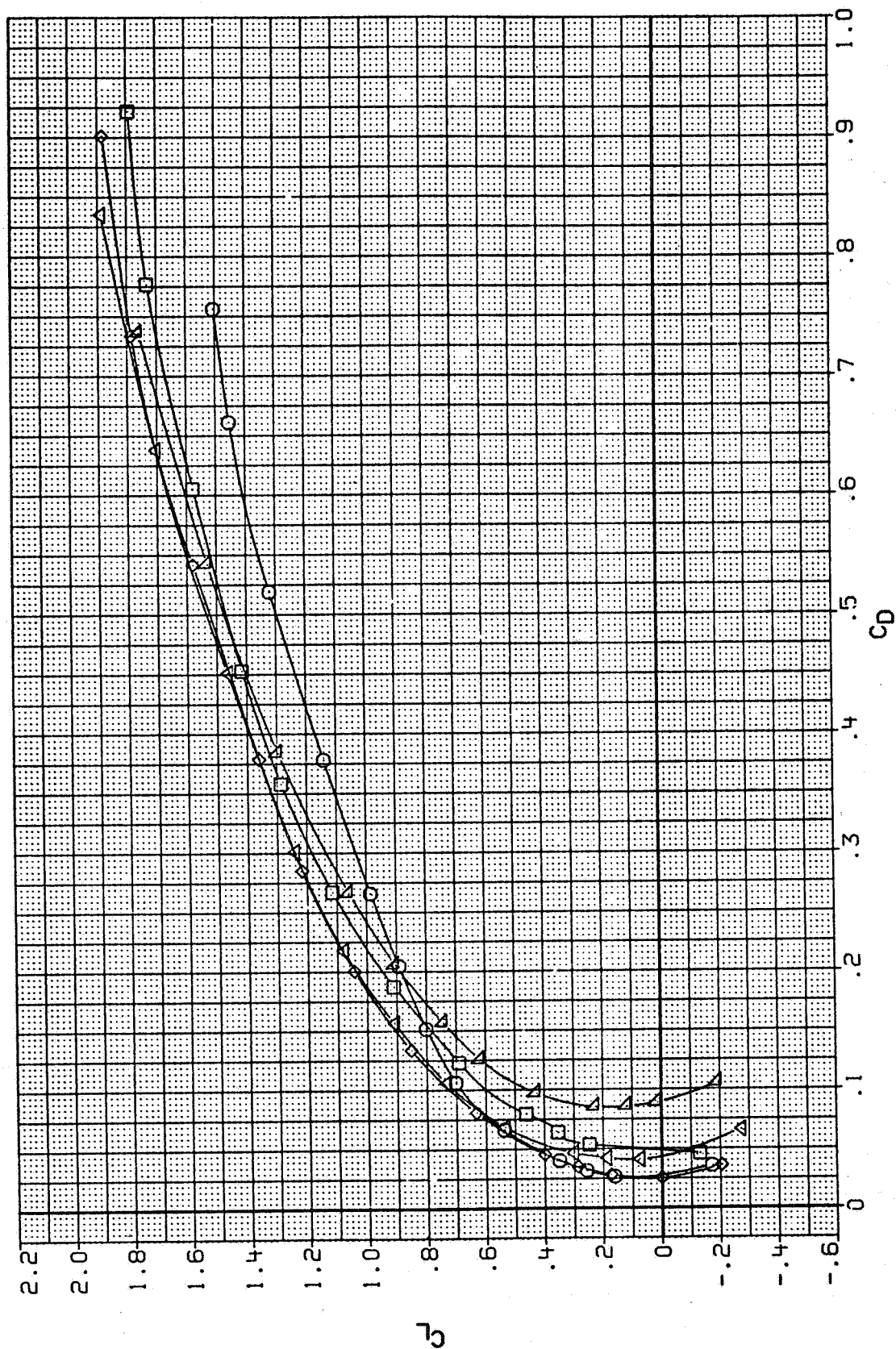


FIG. 101 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .90

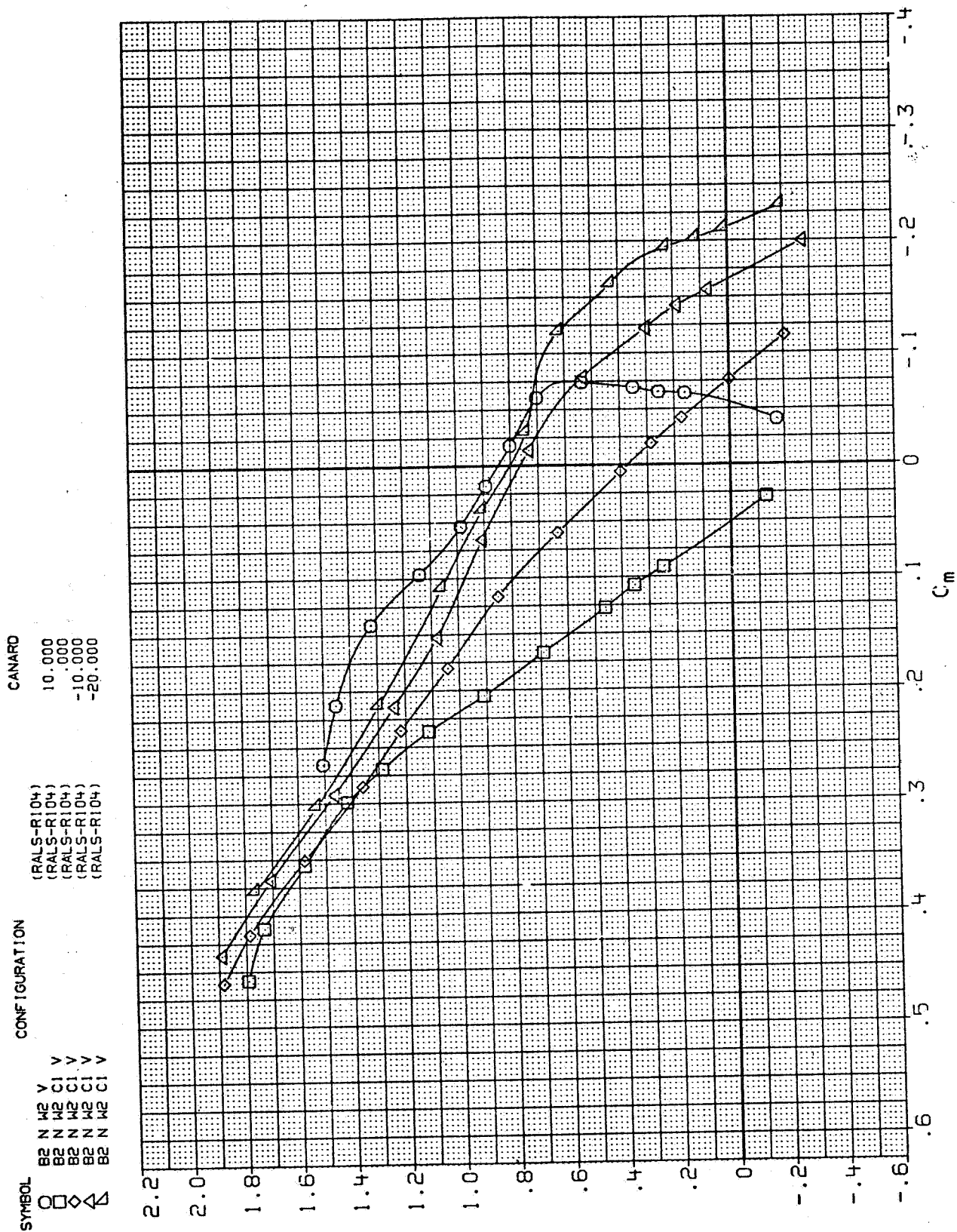


FIG. 101 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .90

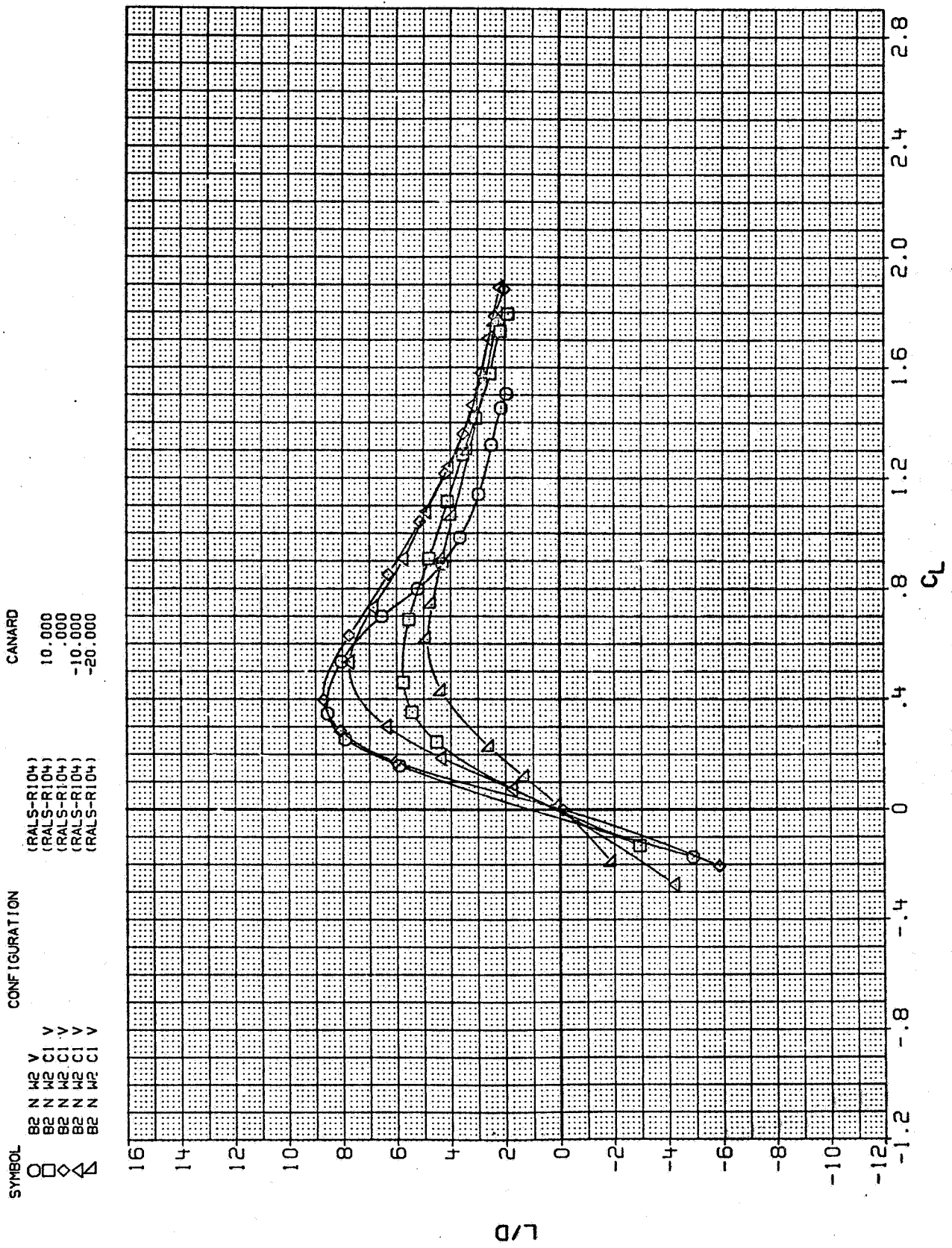


FIG. 101 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = .90

SYMBOL		CONFIGURATION		CANARD	
□	B2 N W2 V	(RALS-R104)	10.000		
◇	B2 N W2 C1 V	(RALS-R104)	-10.000		
△	B2 N W2 C1 V	(RALS-R104)	-20.000		

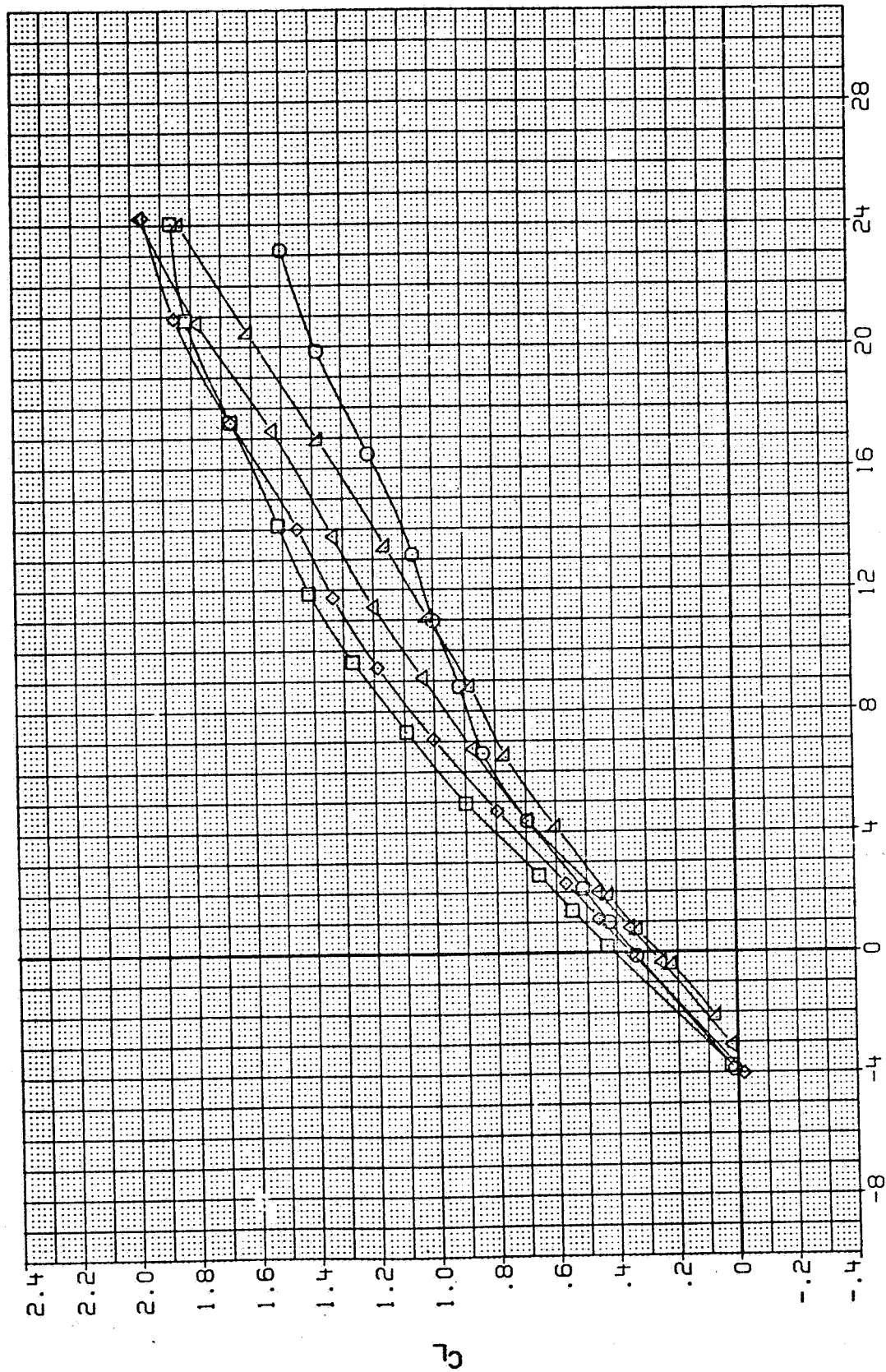


FIG. 102 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .90

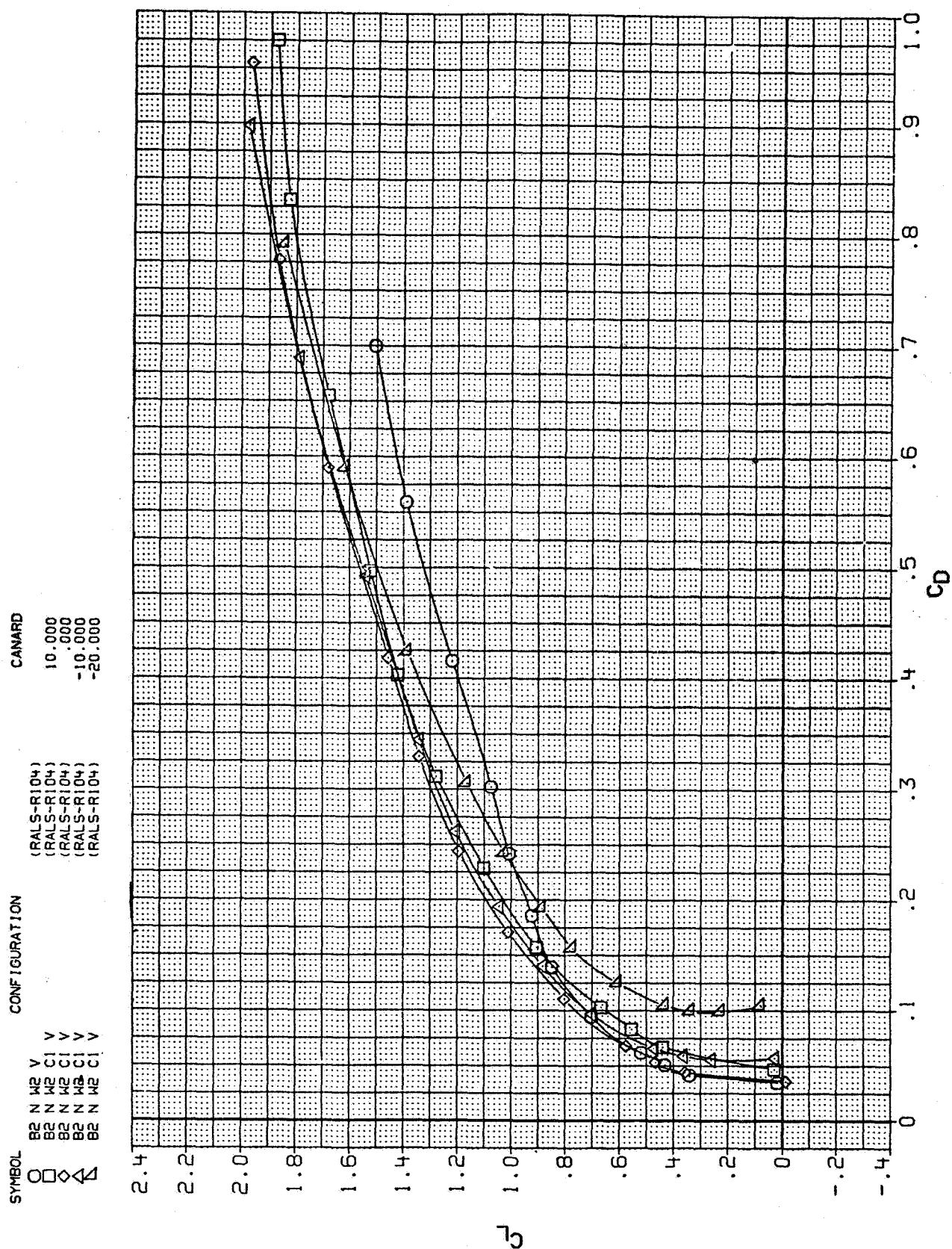


FIG. 102 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .90

SYMBOL	  	CONFIGURATION		CANARD	
		B2 N W2 V	(RALS-R104)	10.000	
		B2 N W2 C1 V	(RALS-R104)	.000	
		B2 N W2 C1 V	(RALS-R104)	-10.000	
		B2 N W2 C1 V	(RALS-R104)	-20.000	

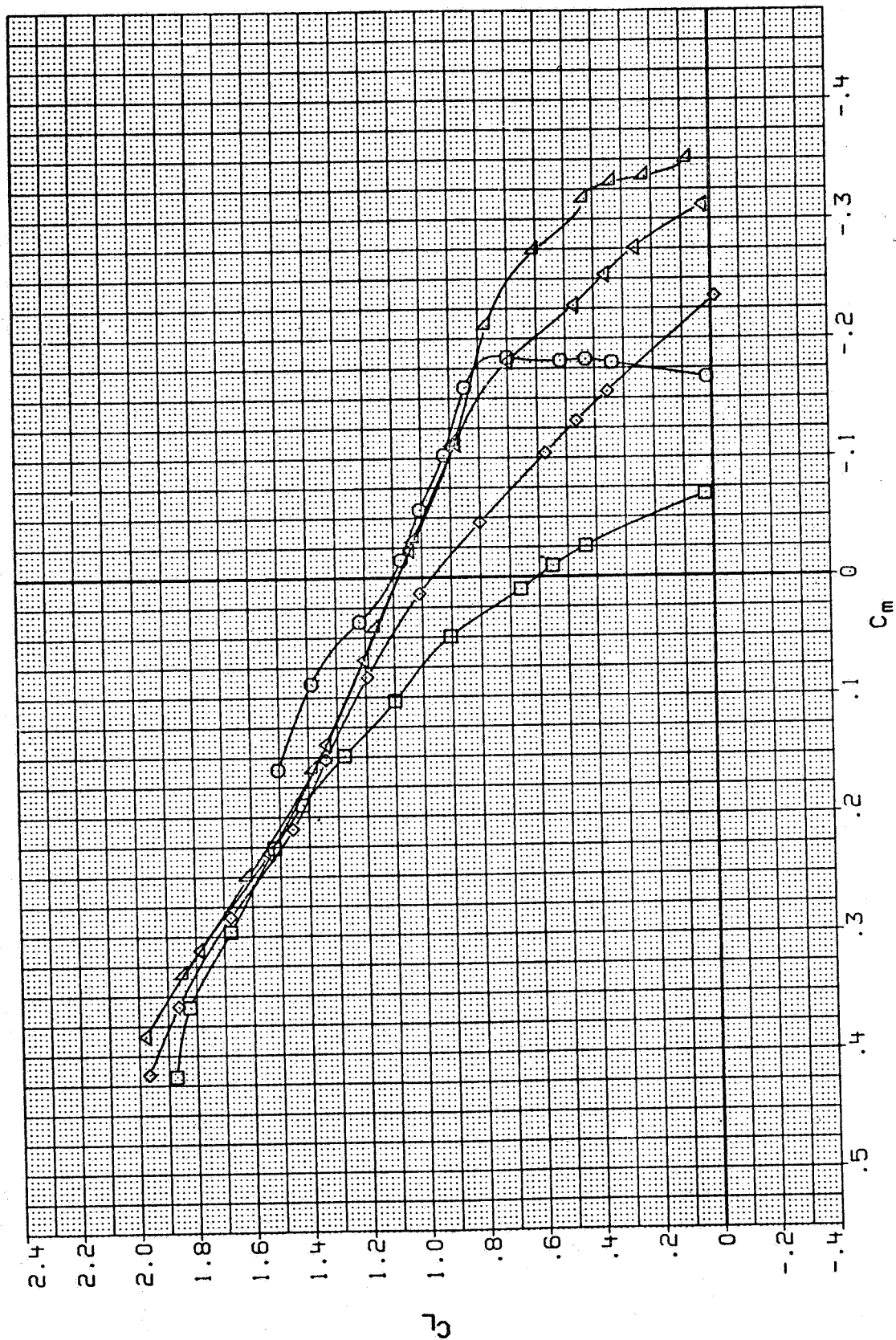


FIG. 102 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .90

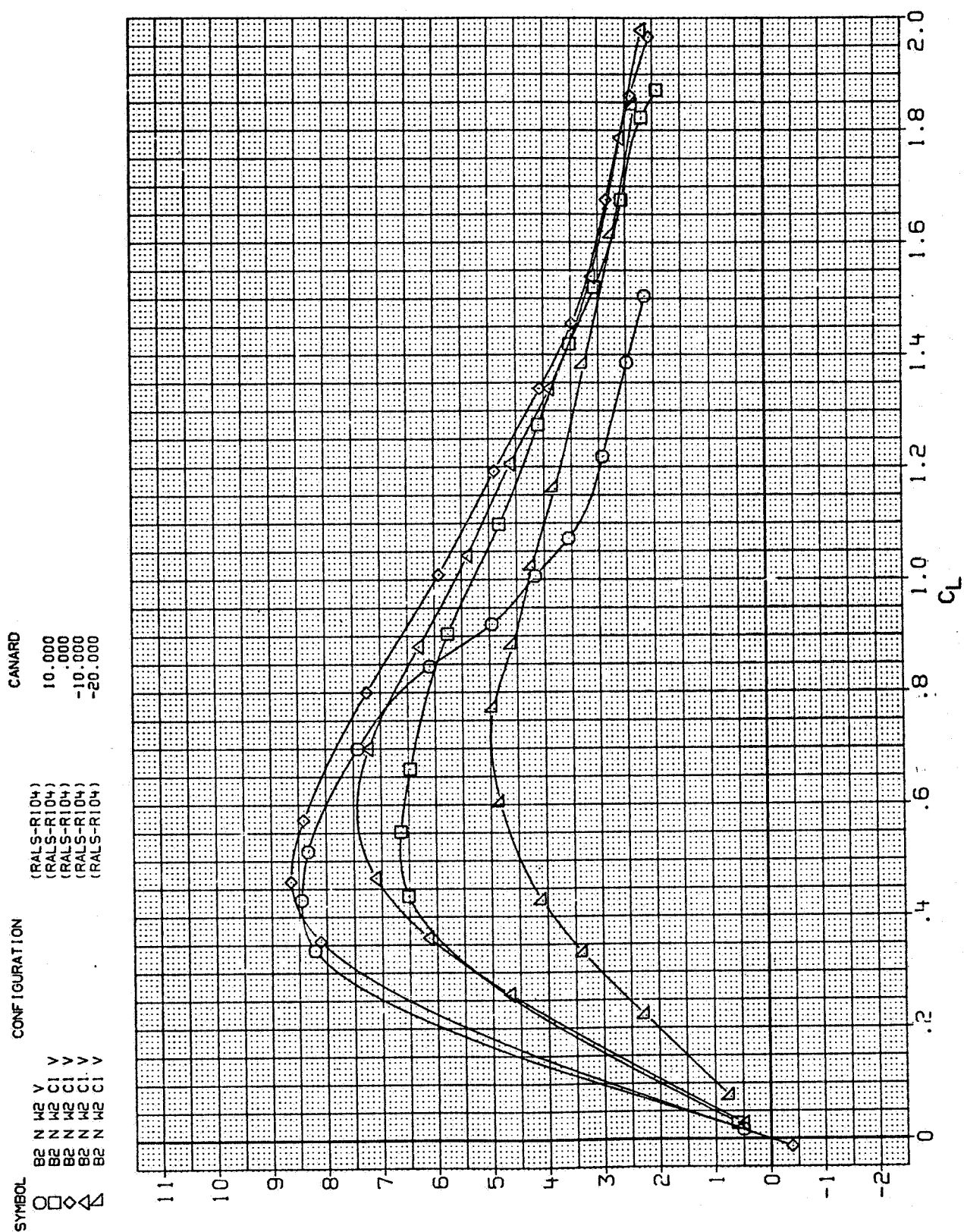


FIG. 102 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = .90

SYMBOL		CONFIGURATION		CANARD	
○	B2 N W2 V	(RALS-R104)	10.000		
◇	B2 N W2 C1 V	(RALS-R104)	.000		
△	B2 N W2 C1 V	(RALS-R104)	-10.000		
□	B2 N W2 C1 V	(RALS-R104)	-20.000		

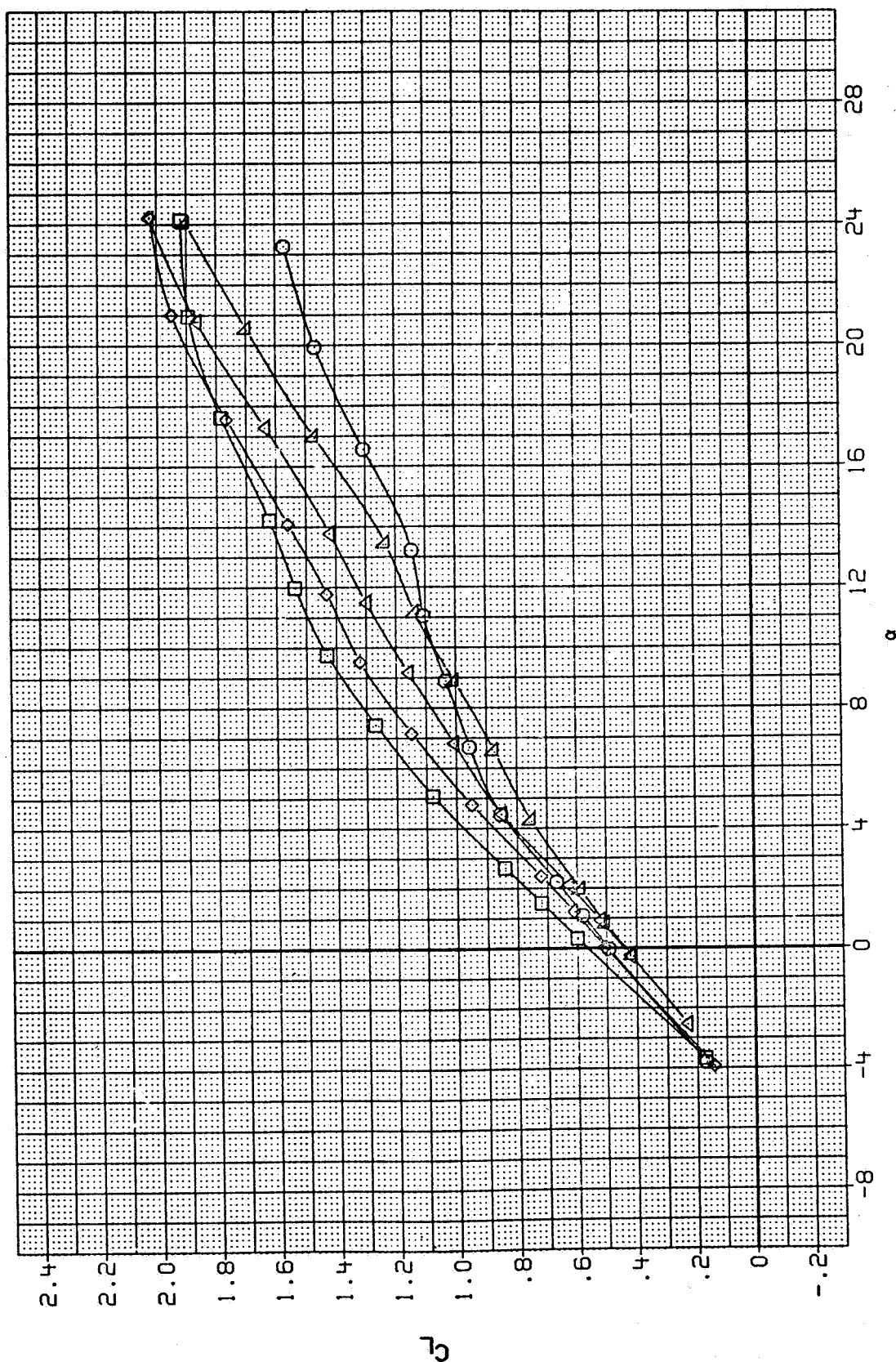


FIG. 103 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .90

SYMBOL	CONFIGURATION	CANARD
○	B2 N W2 V	10.000
◇	B2 N W2 C1 V	.000
△	B2 N W2 C1 V	-10.000
▽	B2 N W2 C1 V	-20.000

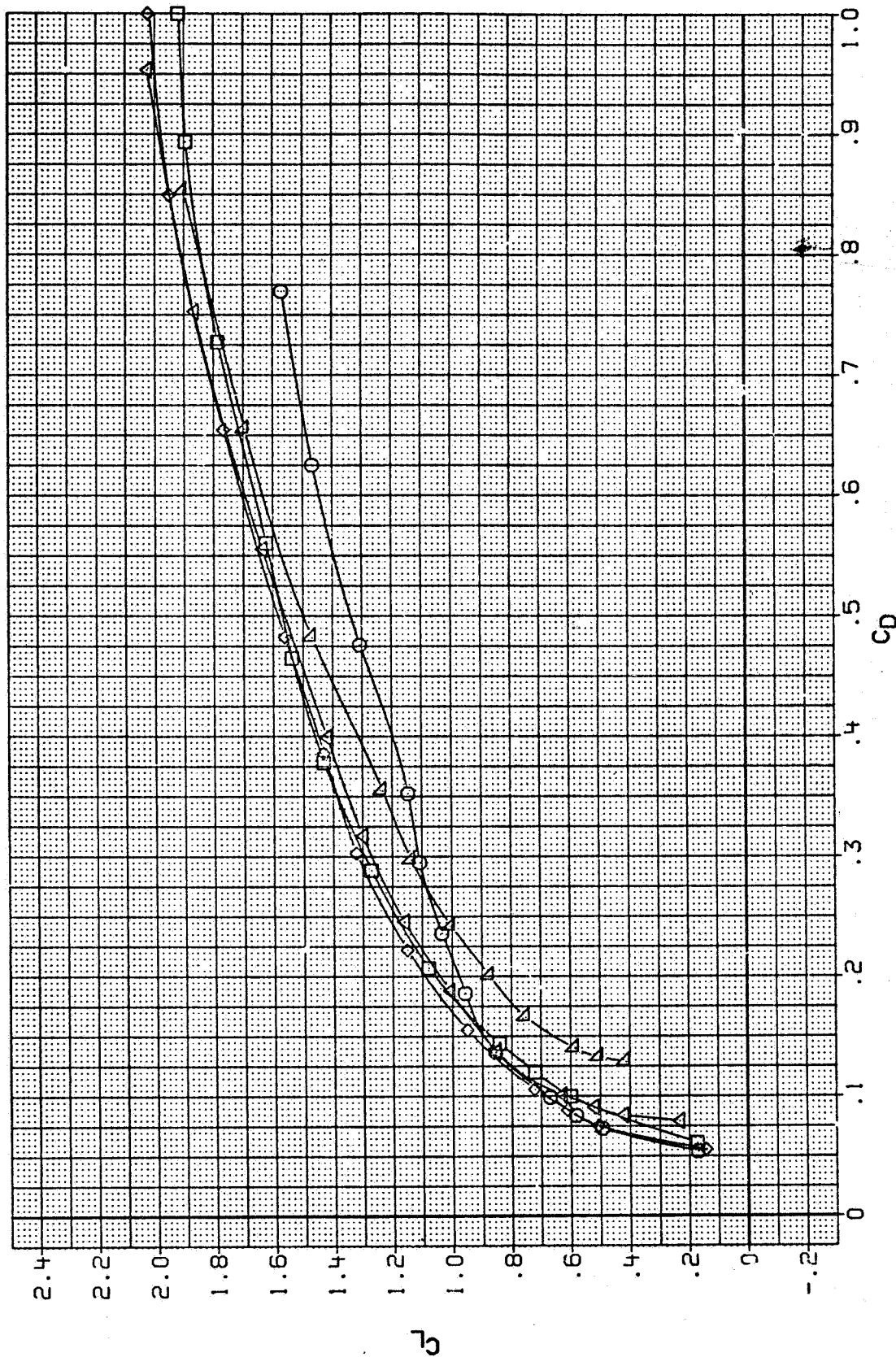


FIG. 103 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .90

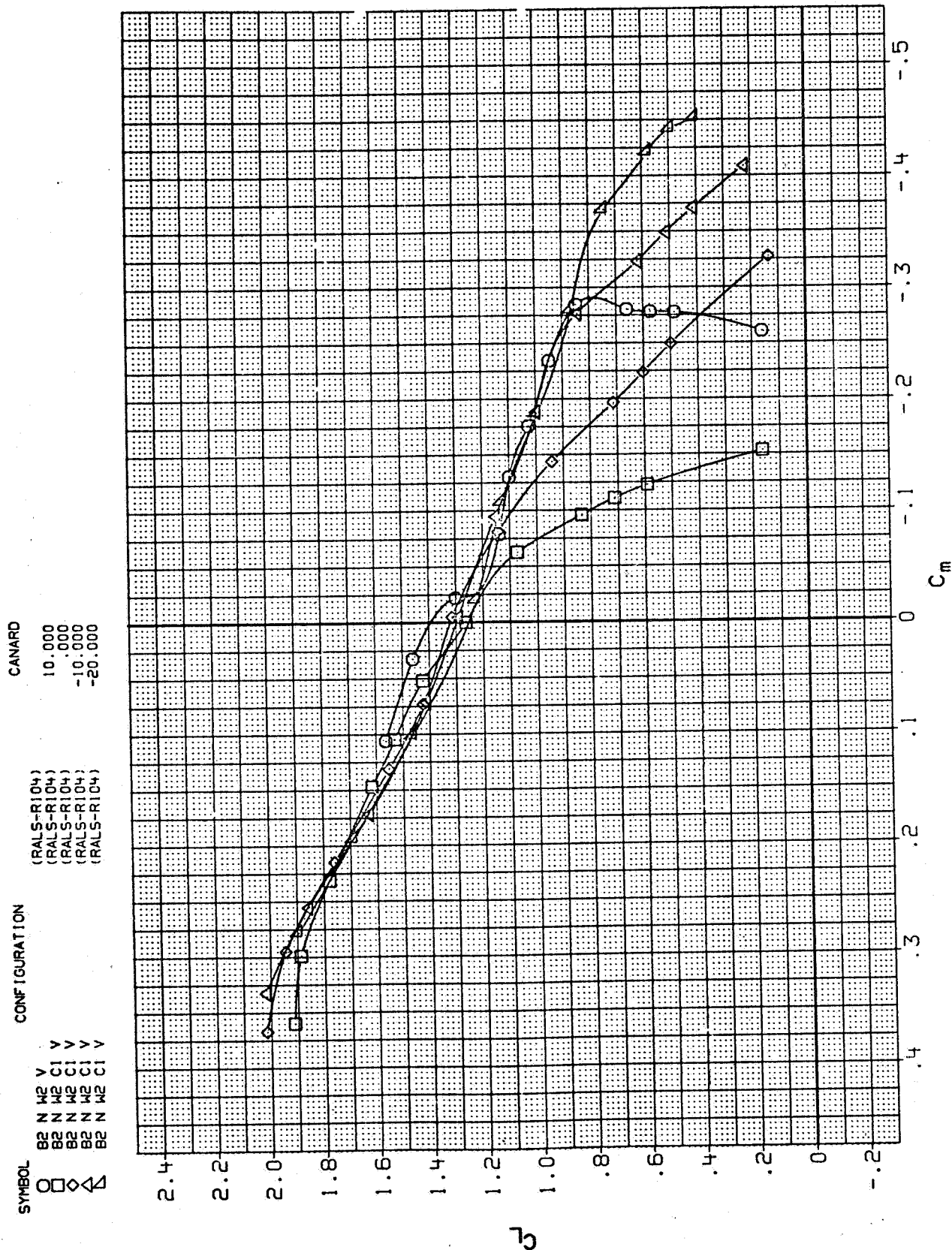
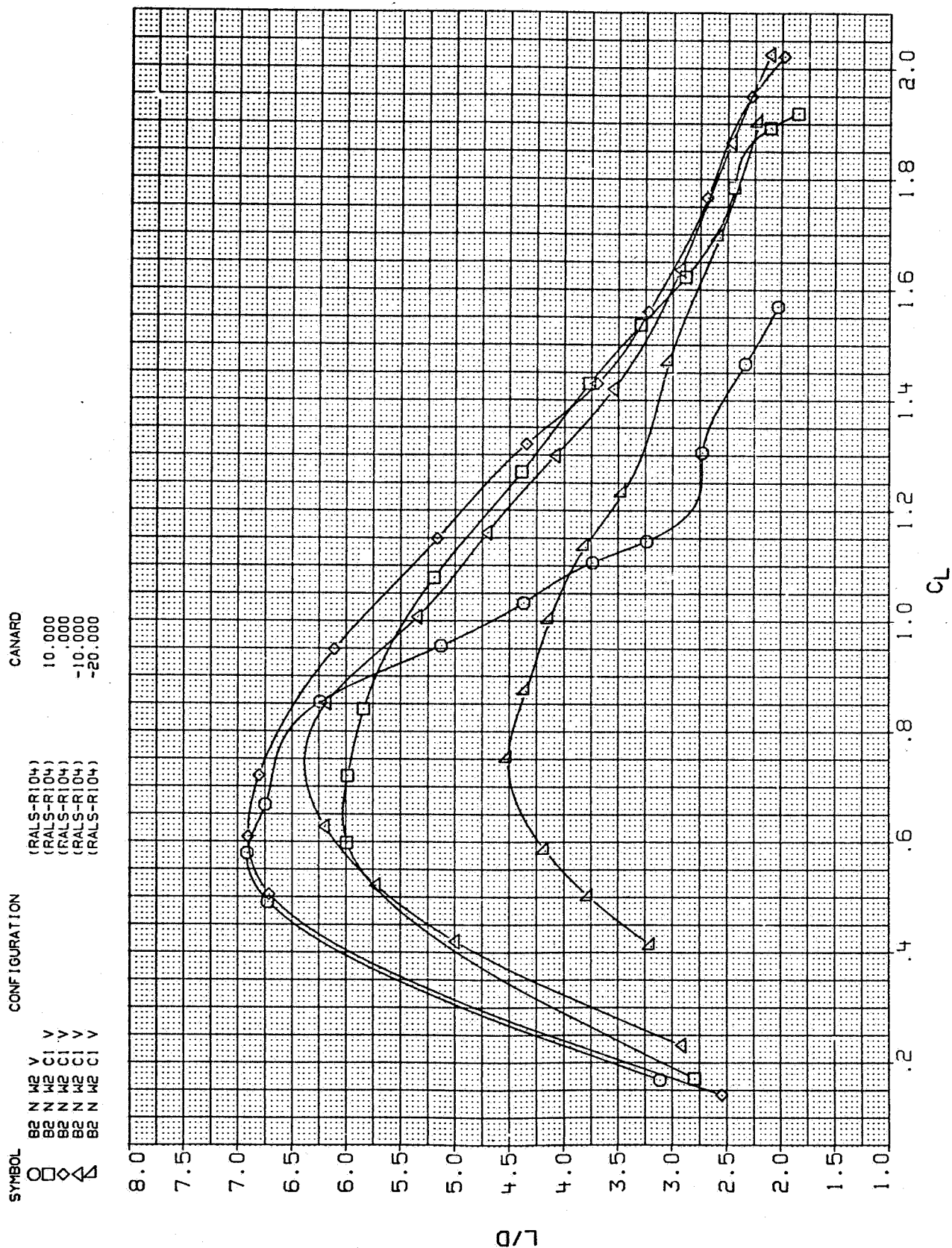


FIG. 103 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = .90



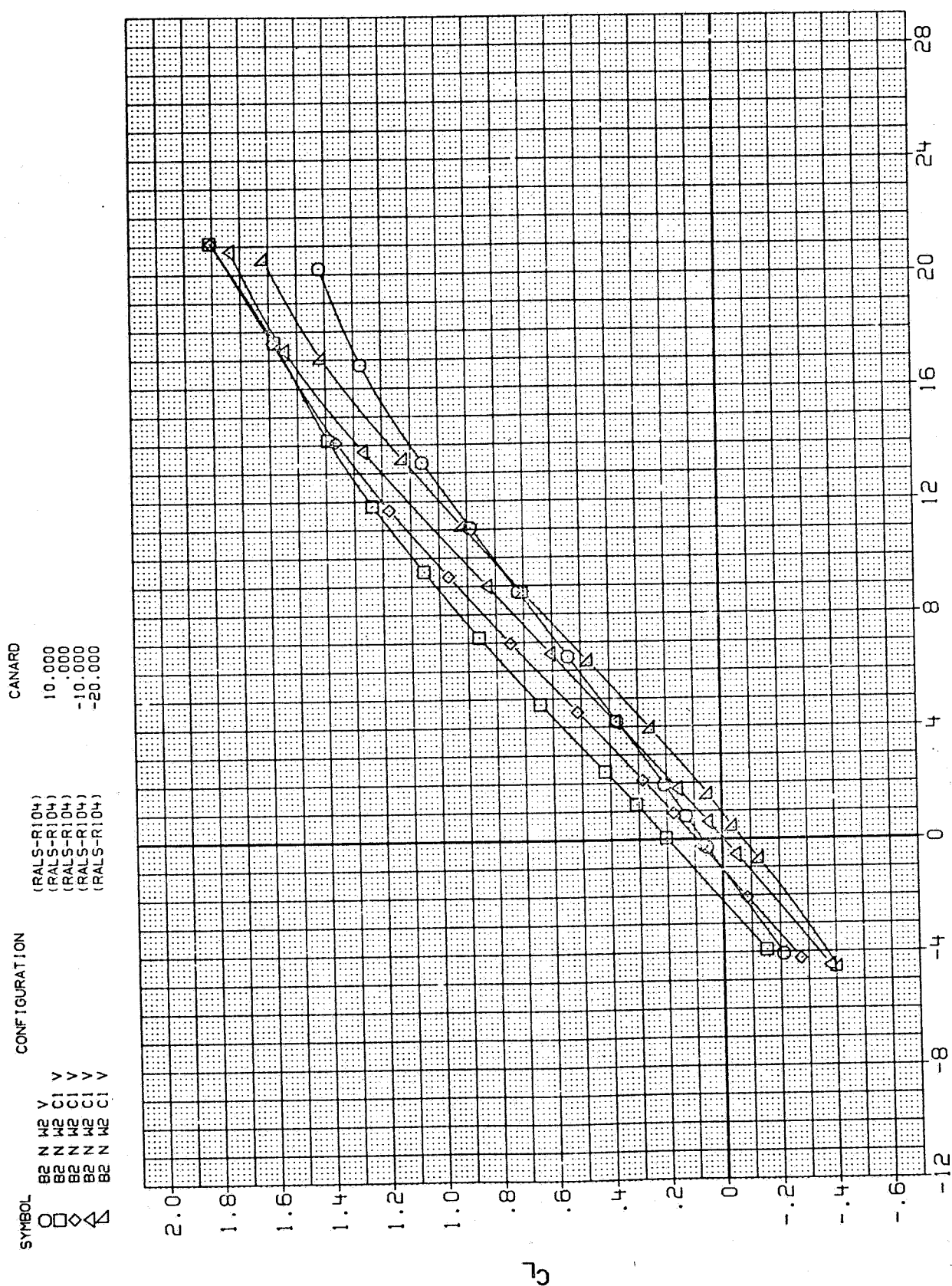


FIG. 104 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = 1.20

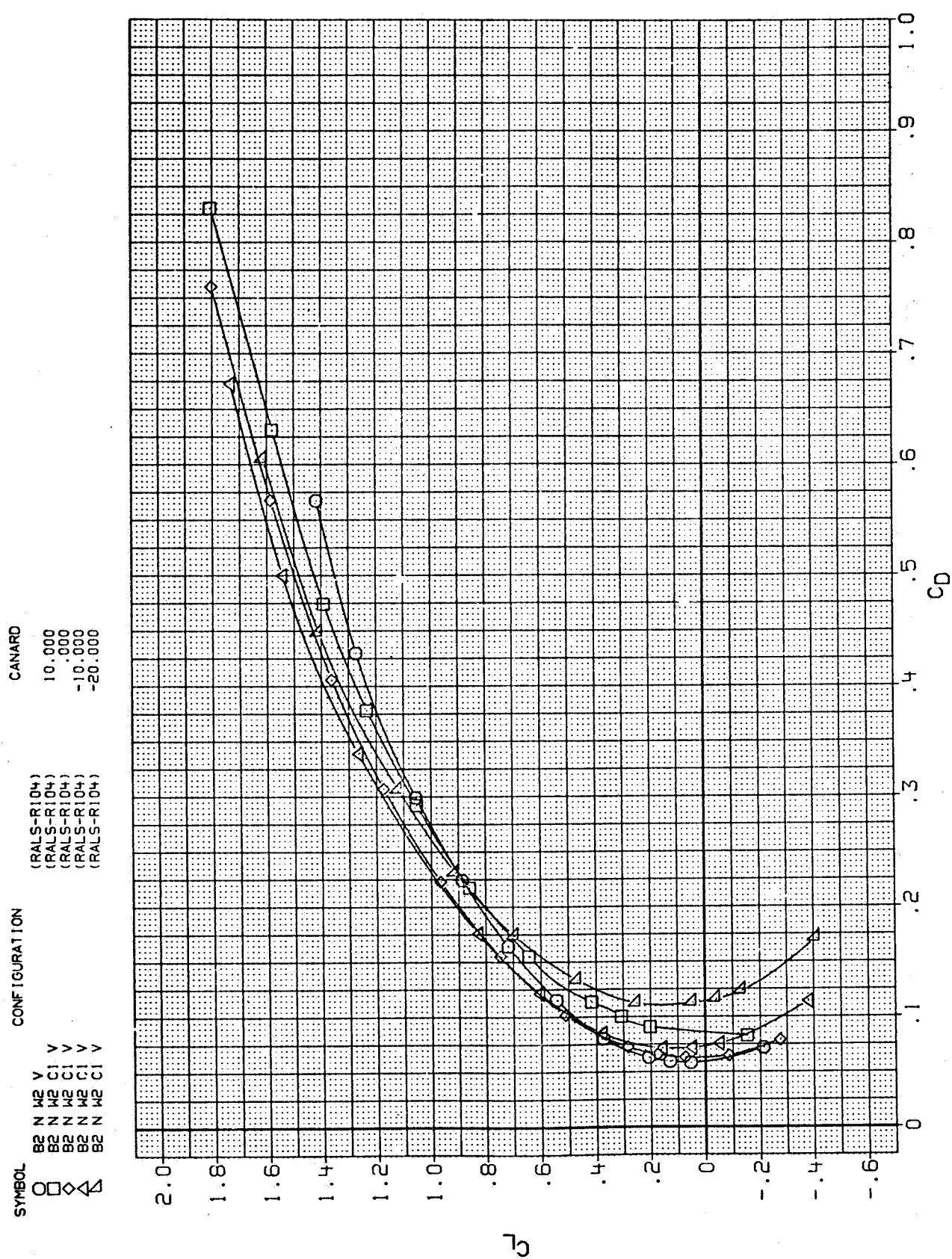


FIG. 104 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = 1.20

SYMBOL	CONFIGURATION	CANARD
B2 N W2 V	(RALS-R104)	10.000
B2 N W2 C1 V	(RALS-R104)	.000
B2 N W2 C1 V	(RALS-R104)	-10.000
B2 N W2 C1 V	(RALS-R104)	-20.000

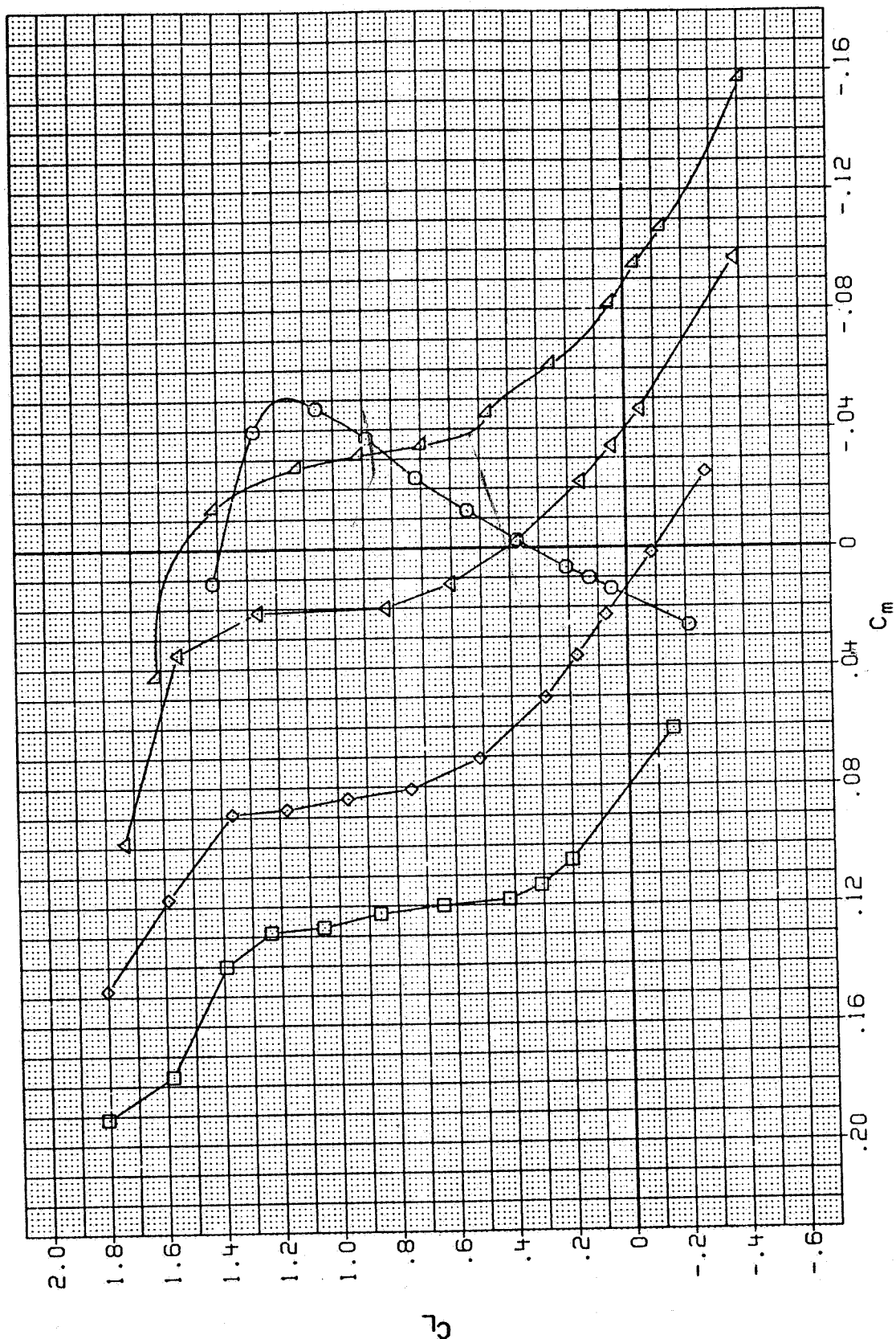


FIG. 104 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = 1.20

SYMBOL	CONFIGURATION	CANARD
□	B2 N W2 V	10.000
◇	B2 N W2 C1 V	.000
△	B2 N W2 C1 V	-10.000
▽	B2 N W2 C1 V	-20.000

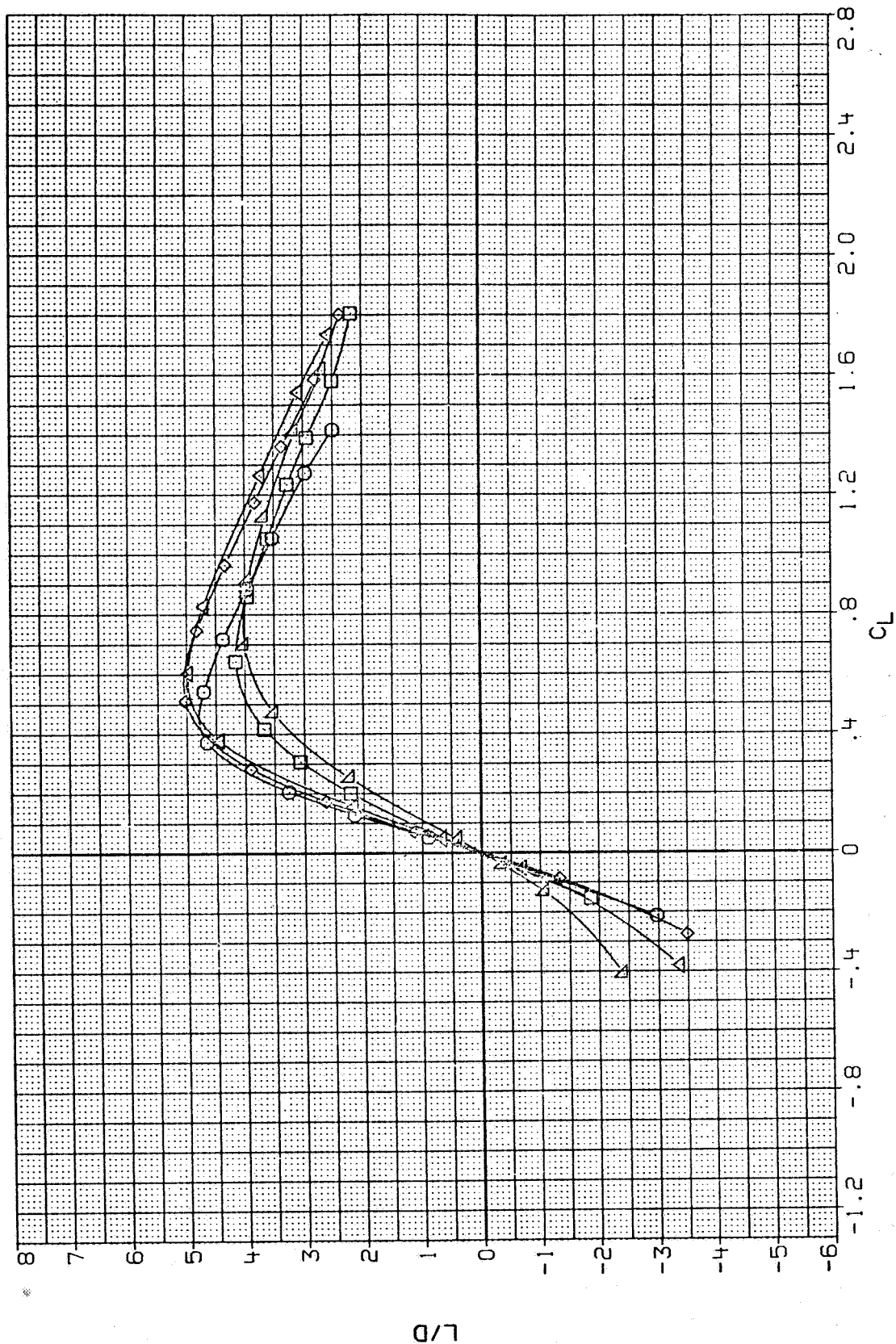


FIG. 104 CANARD INCIDENCE EFFECTS, TE-W = 0 DEGREES

MACH = 1.20

0/1

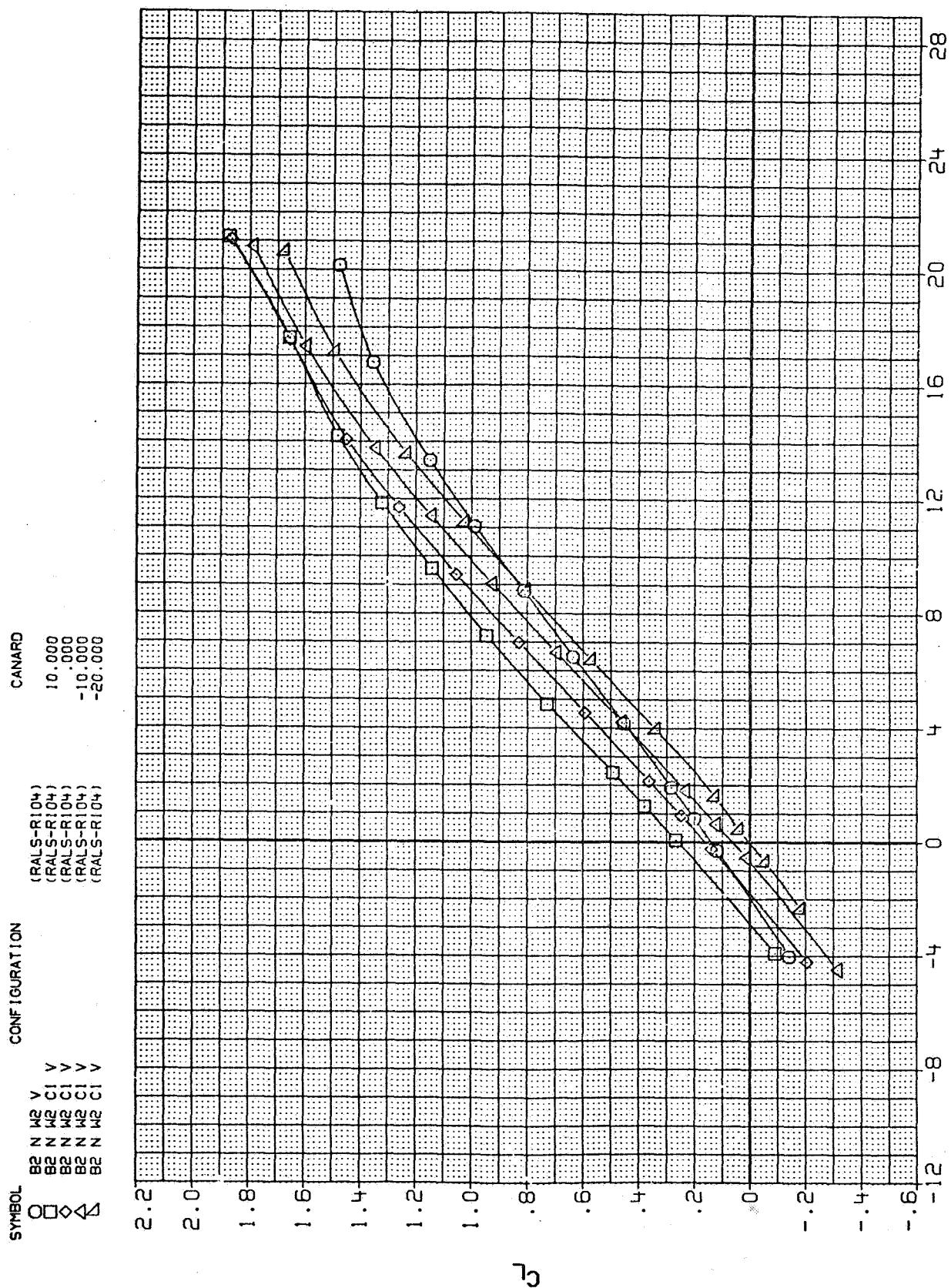
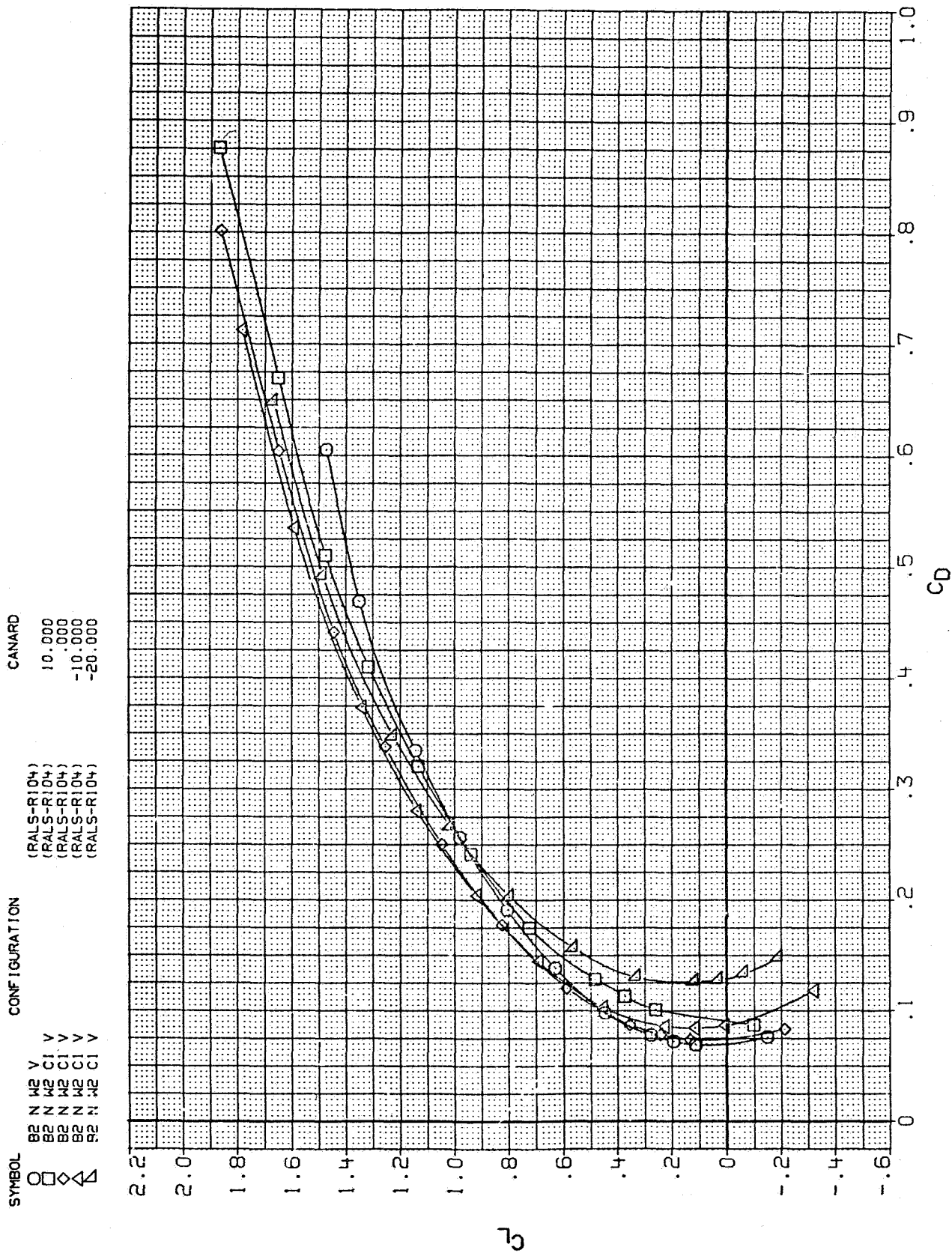


FIG. 105 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = 1.20



SYMBOL	CONFIGURATION	CANARD
B2 N W2 V	(RALS-R104)	10.000
B2 N W2 C1 V	(RALS-R104)	.000
B2 N W2 C1 V	(RALS-R104)	-10.000
B2 N W2 C1 V	(RALS-R104)	-20.000

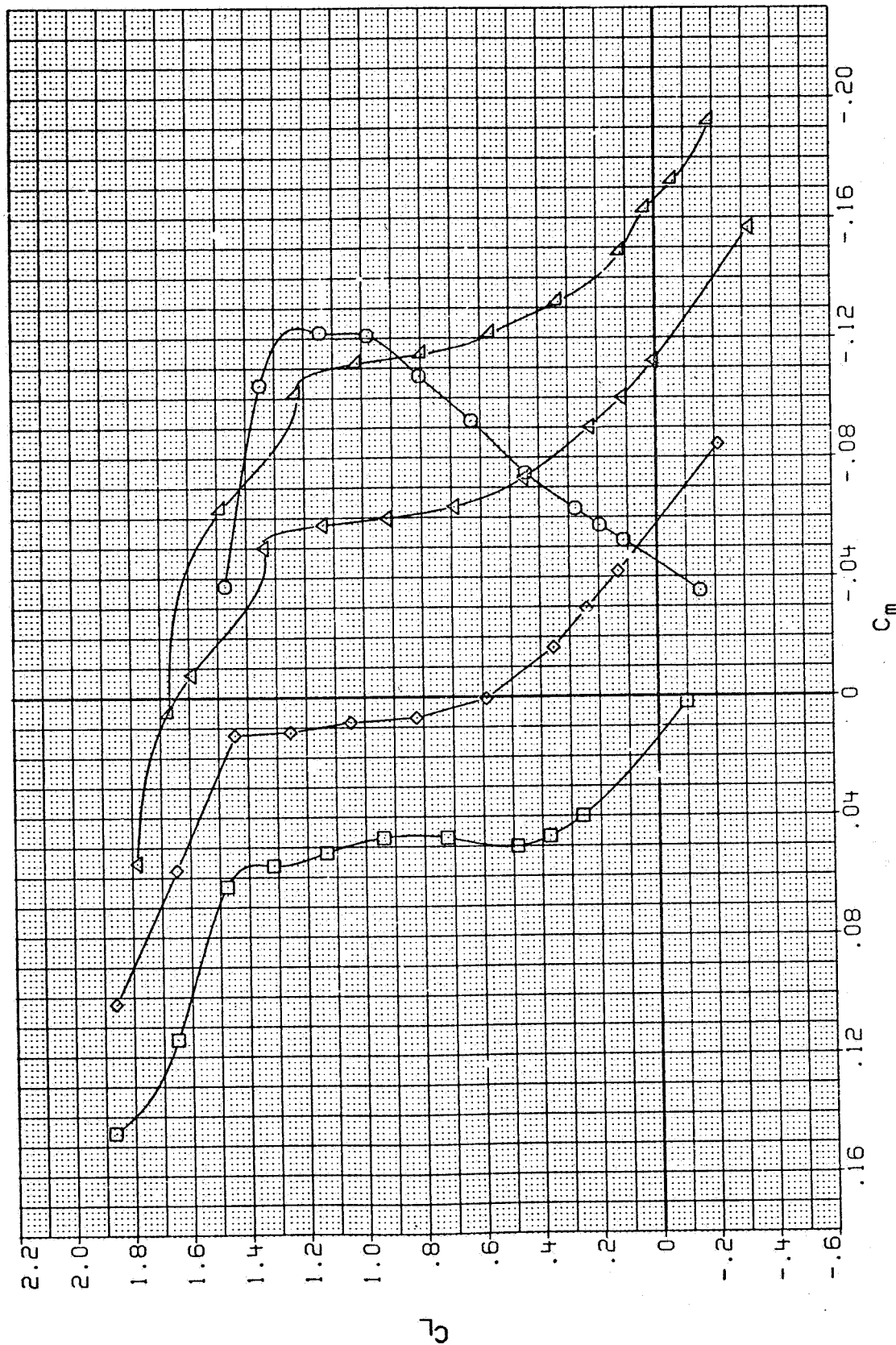


FIG. 105 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = 1.20

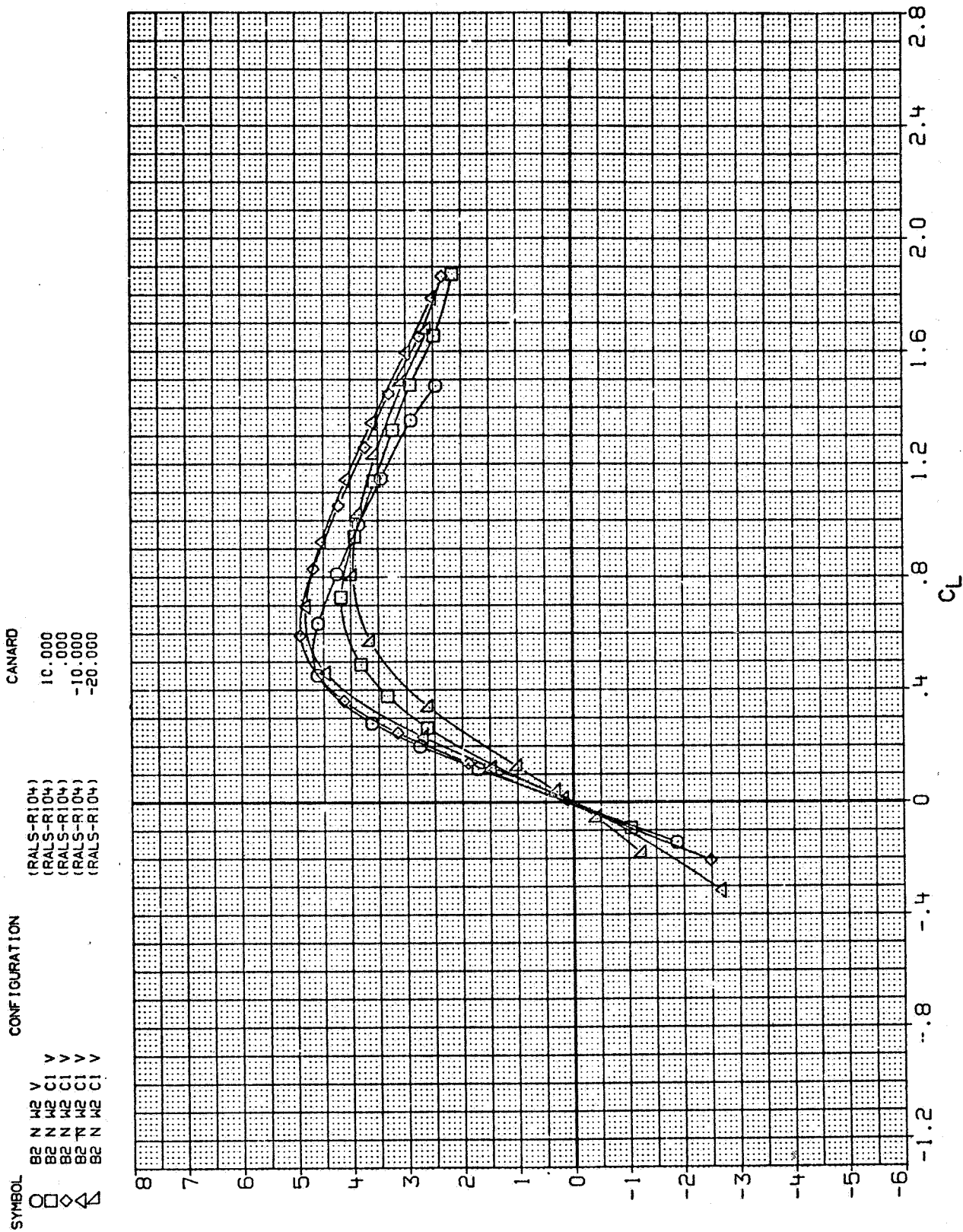


FIG. 105 CANARD INCIDENCE EFFECTS, TE-W = 10 DEGREES

MACH = 1.20

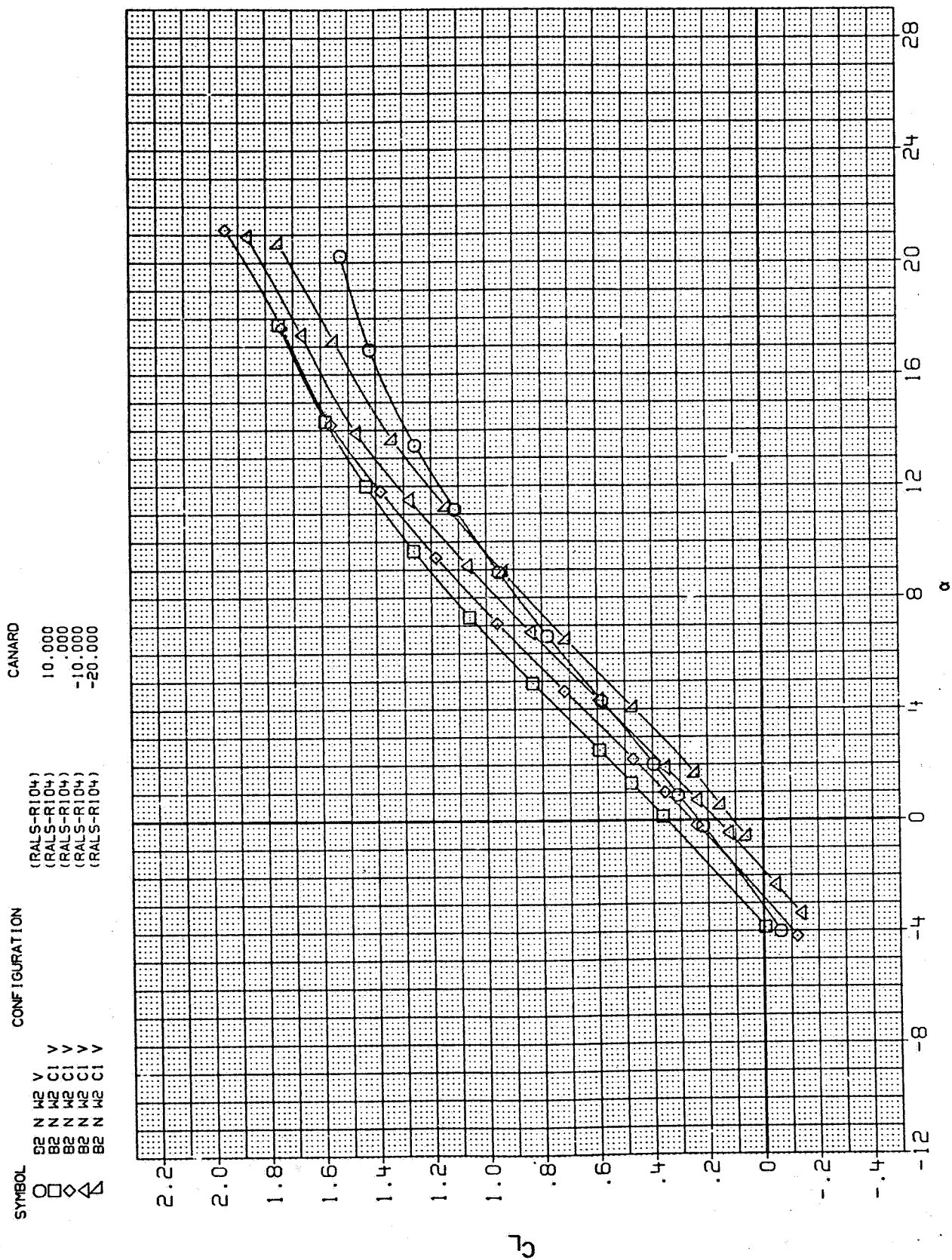


FIG. 106 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = 1.20

SYMBOL	CONFIGURATION	CANARD
□	B2 N W2 V	10.000
◇	B2 N W2 C1 V	.000
△	B2 N W2 C1 V	-10.000
	B2 N W2 C1 V	-20.000

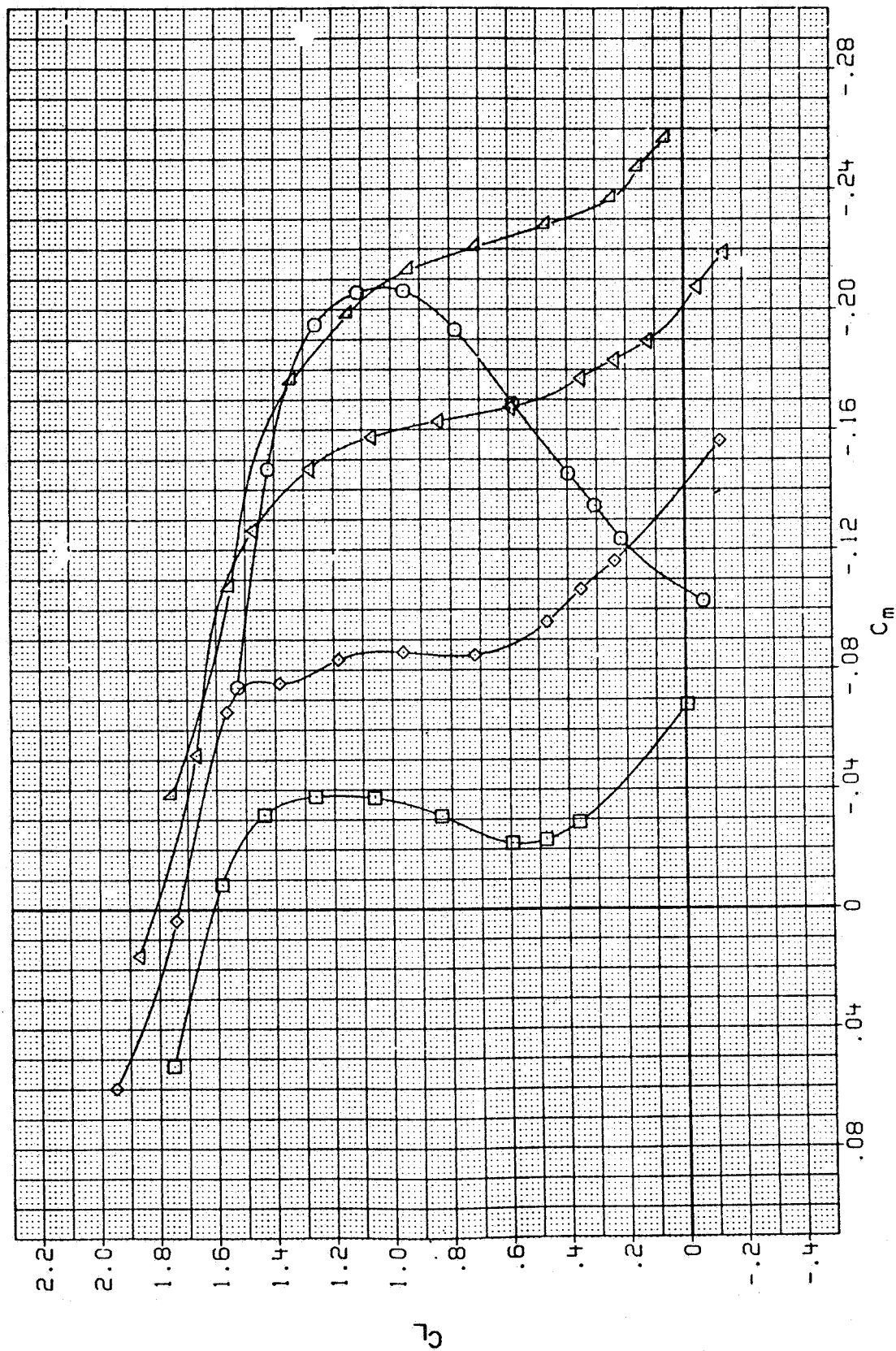


FIG. 106 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = 1.20

SYMBOL	CONFIGURATION	CANARD
○	B2 N W2 V	10.000
□	B2 N W2 C1 V	.000
△	B2 N W2 C1 V	-10.000
◇	B2 N W2 C1 V	-20.000

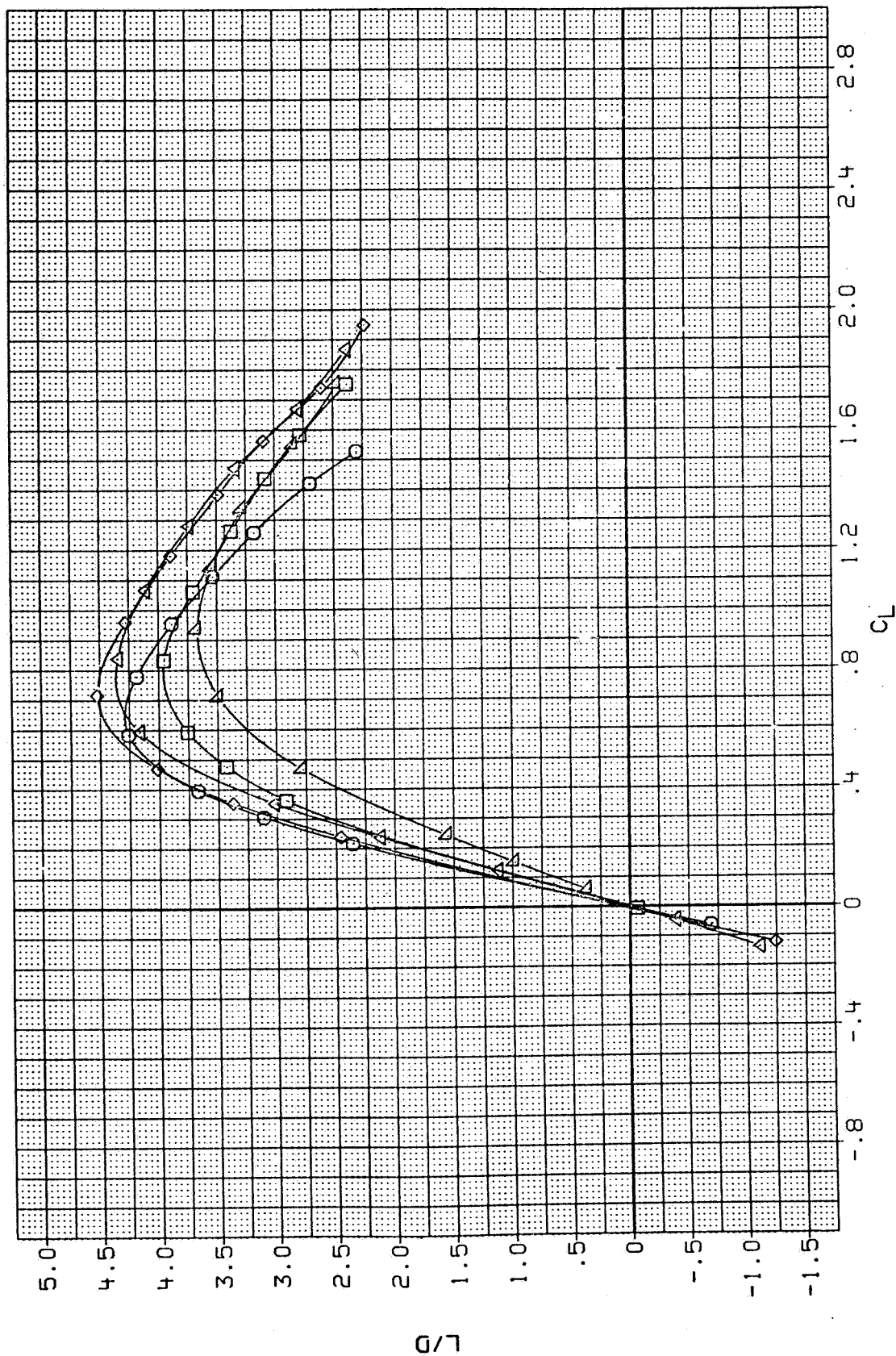


FIG. 106 CANARD INCIDENCE EFFECTS, TE-W = 25 DEGREES

MACH = 1.20

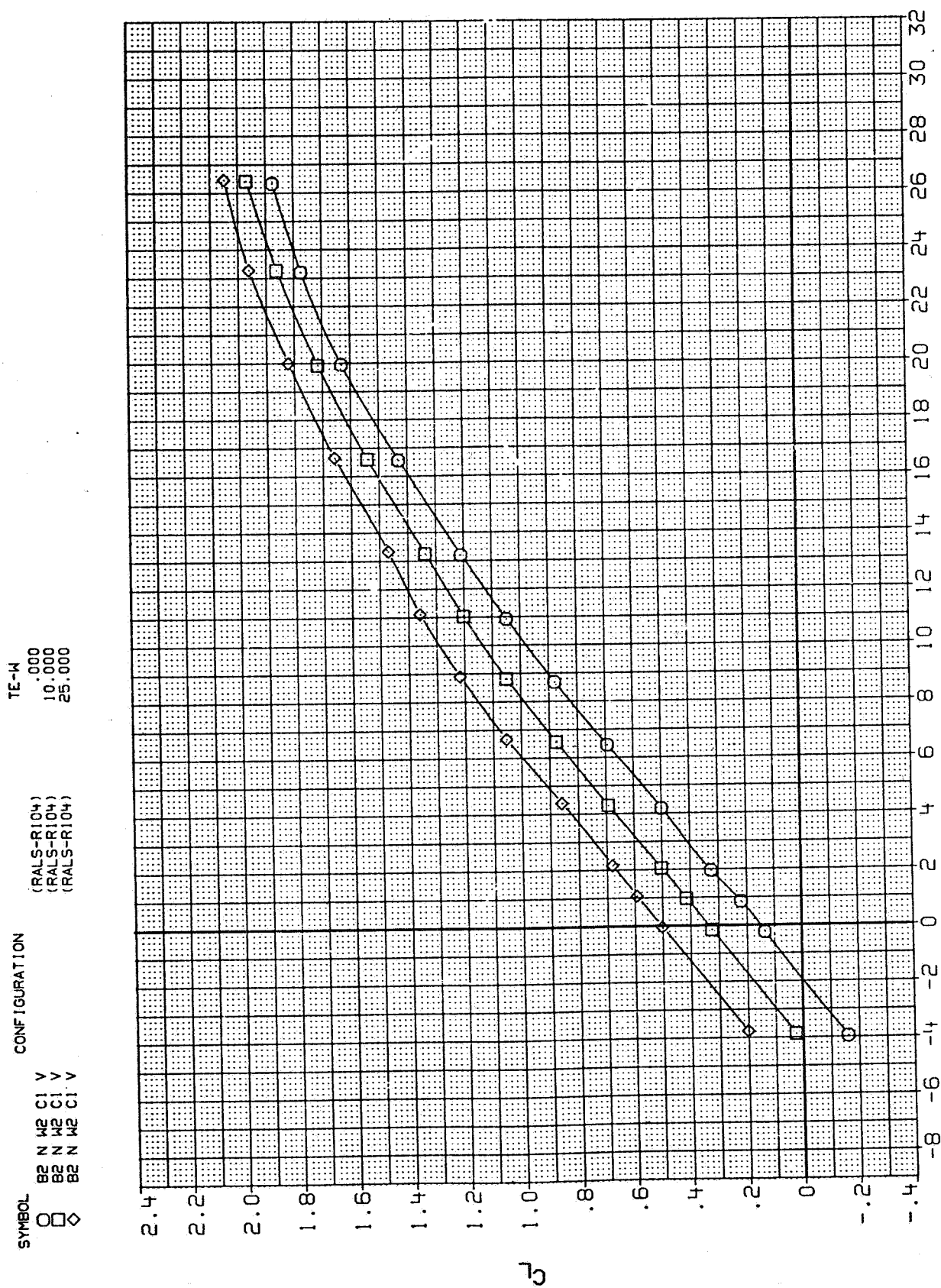


FIG. 107 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .60

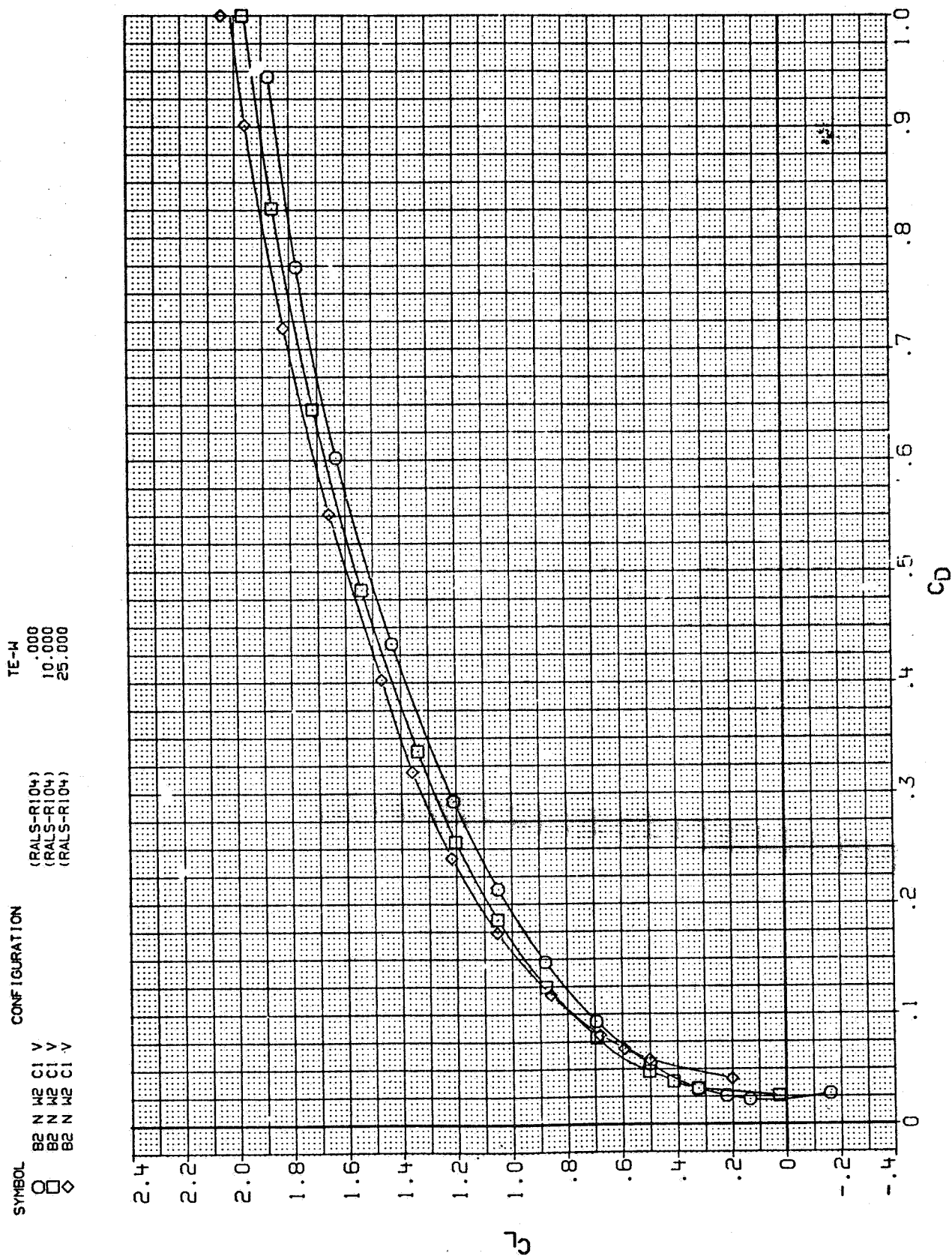


FIG. 107 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .60

TE-W
.000
10.000
25.000

(RALS-R104)
(RALS-R104)
(RALS-R104)

CONFIGURATION

B2 N W2 C1 V
B2 N W2 C1 V
B2 N W2 C1 V

SYMBOL
□
◇

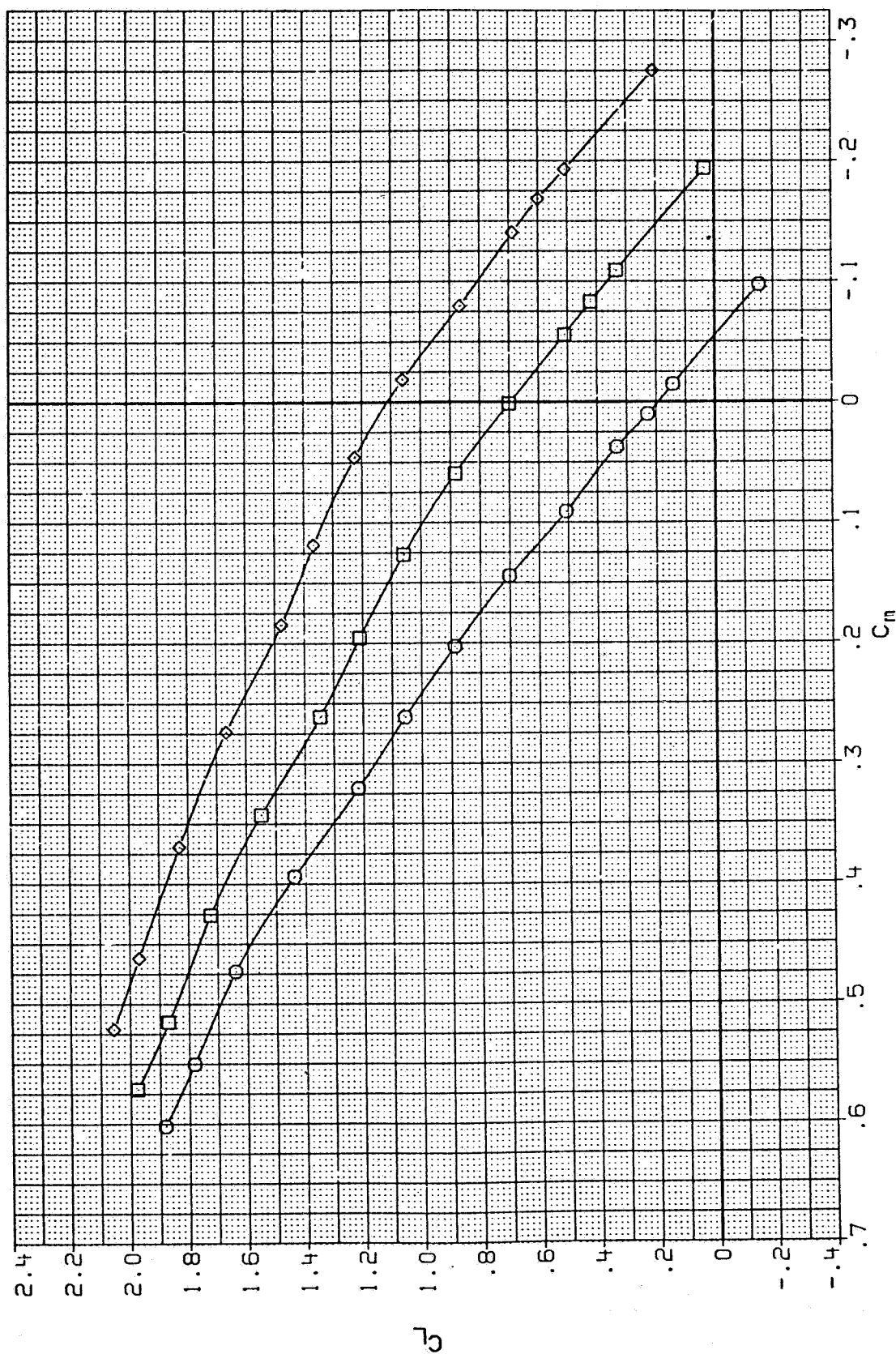


FIG. 107 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .60

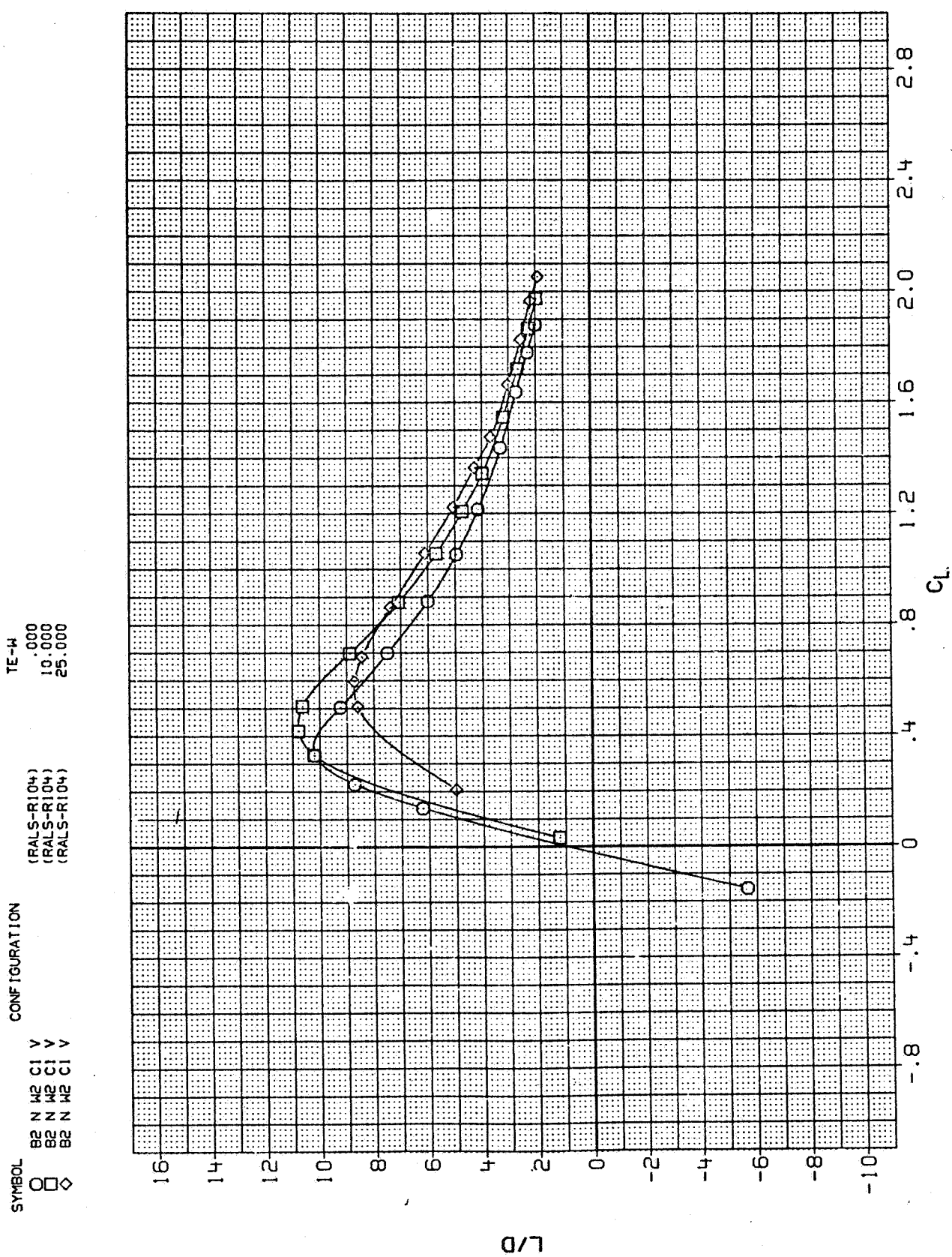


FIG. 107 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .60

TE-H
.000
10.000
25.000

CONFIGURATION

(RALS-R104)
(RALS-R104)
(RALS-R104)

SYMBOL
B2 N W2 C1 V
B2 N W2 C1 V
B2 N W2 C1 V

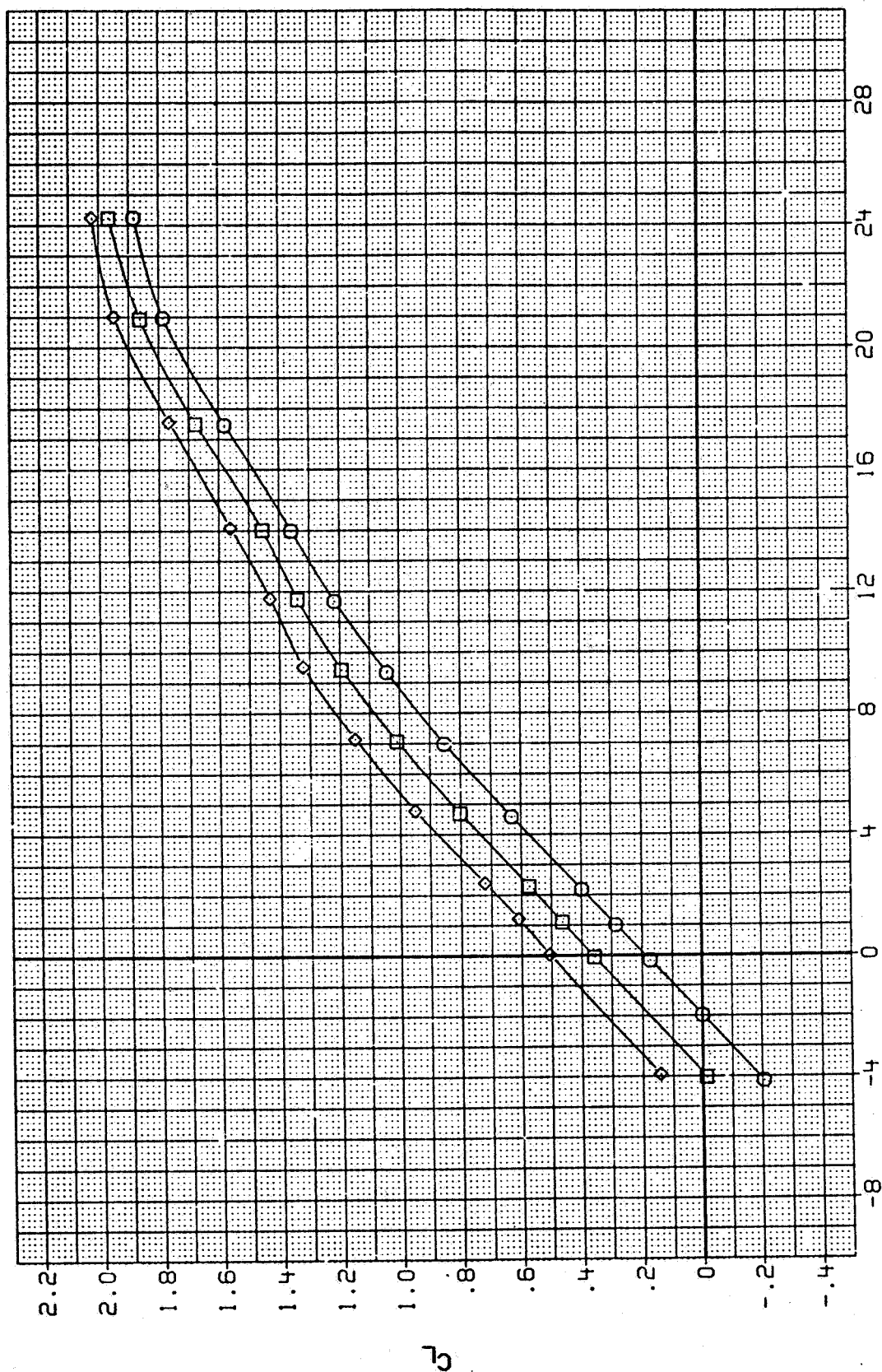


FIG. 108 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .90

SYMBOL	CONFIGURATION		TE-W
	B2 N W2 C1 V	(RALS-R104)	
○	B2 N W2 C1 V	(RALS-R104)	.000
□	B2 N W2 C1 V	(RALS-R104)	10.000
◇	B2 N W2 C1 V	(RALS-R104)	25.000

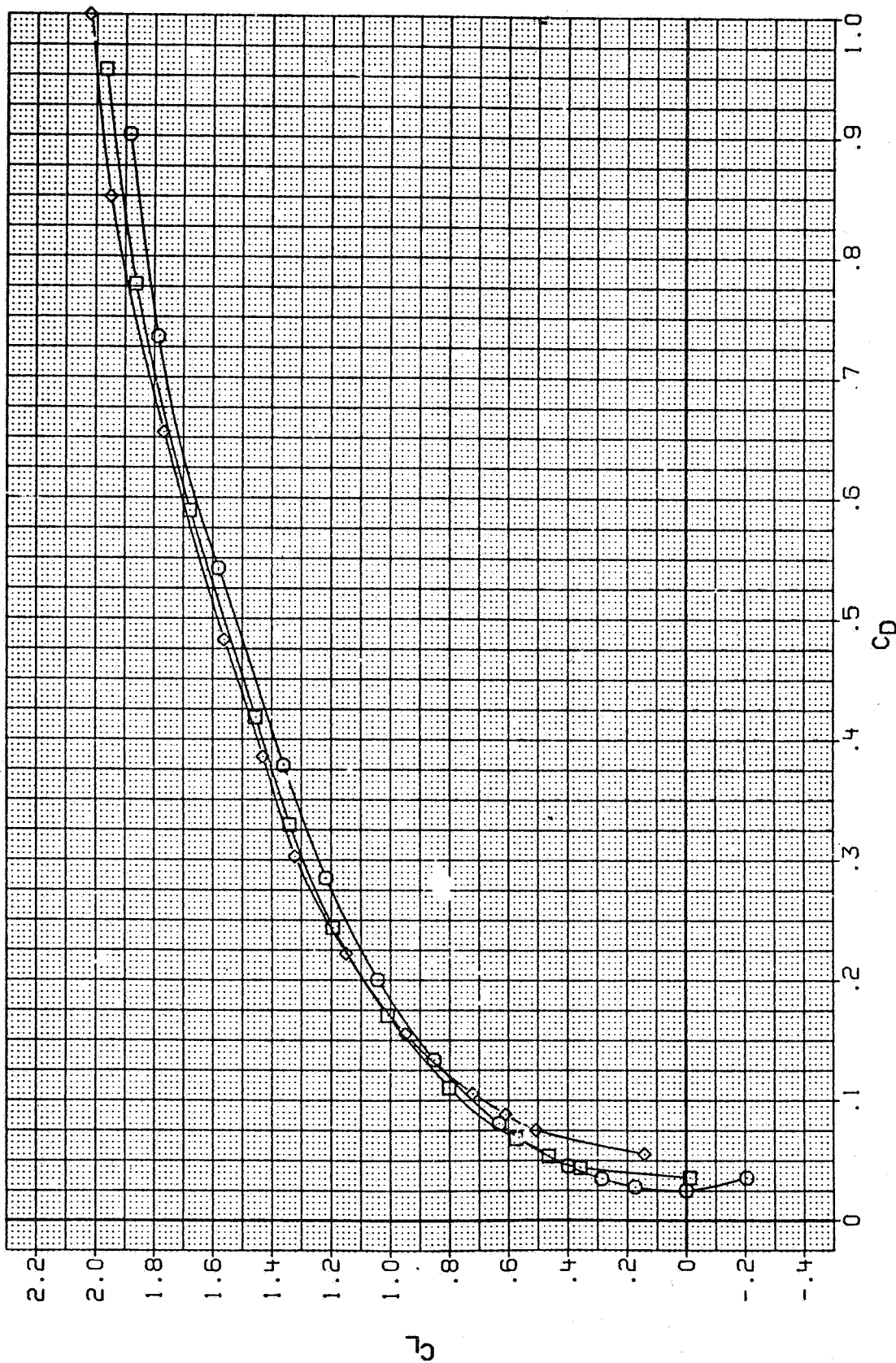


FIG. 108 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .90

SYMBOL CONFIGURATION TE-W
 ○ 82 N W2 C1 V .000
 □ 82 N W2 C1 V 10.000
 ◇ 82 N W2 C1 V 25.000

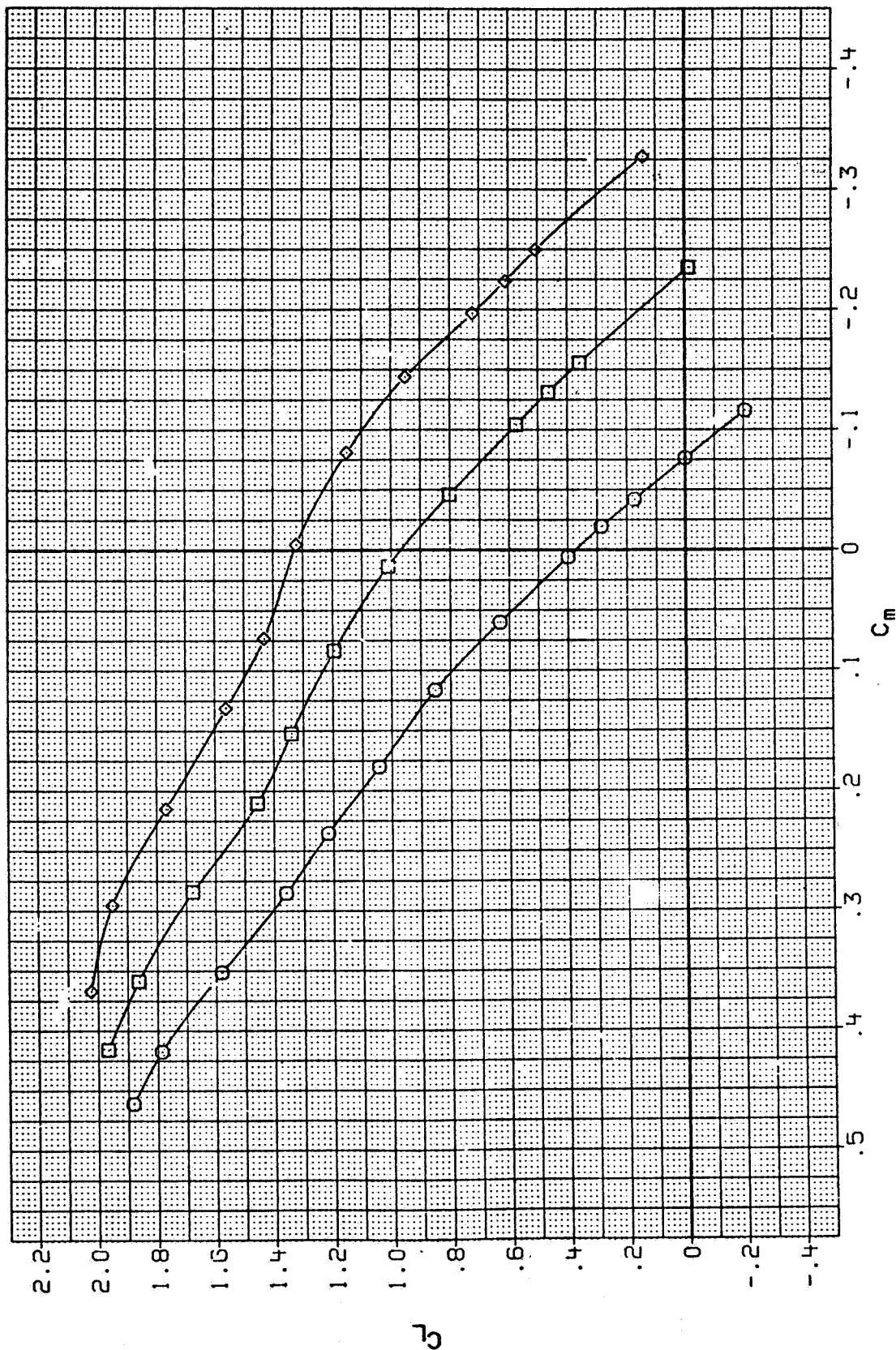


FIG. 108 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .90

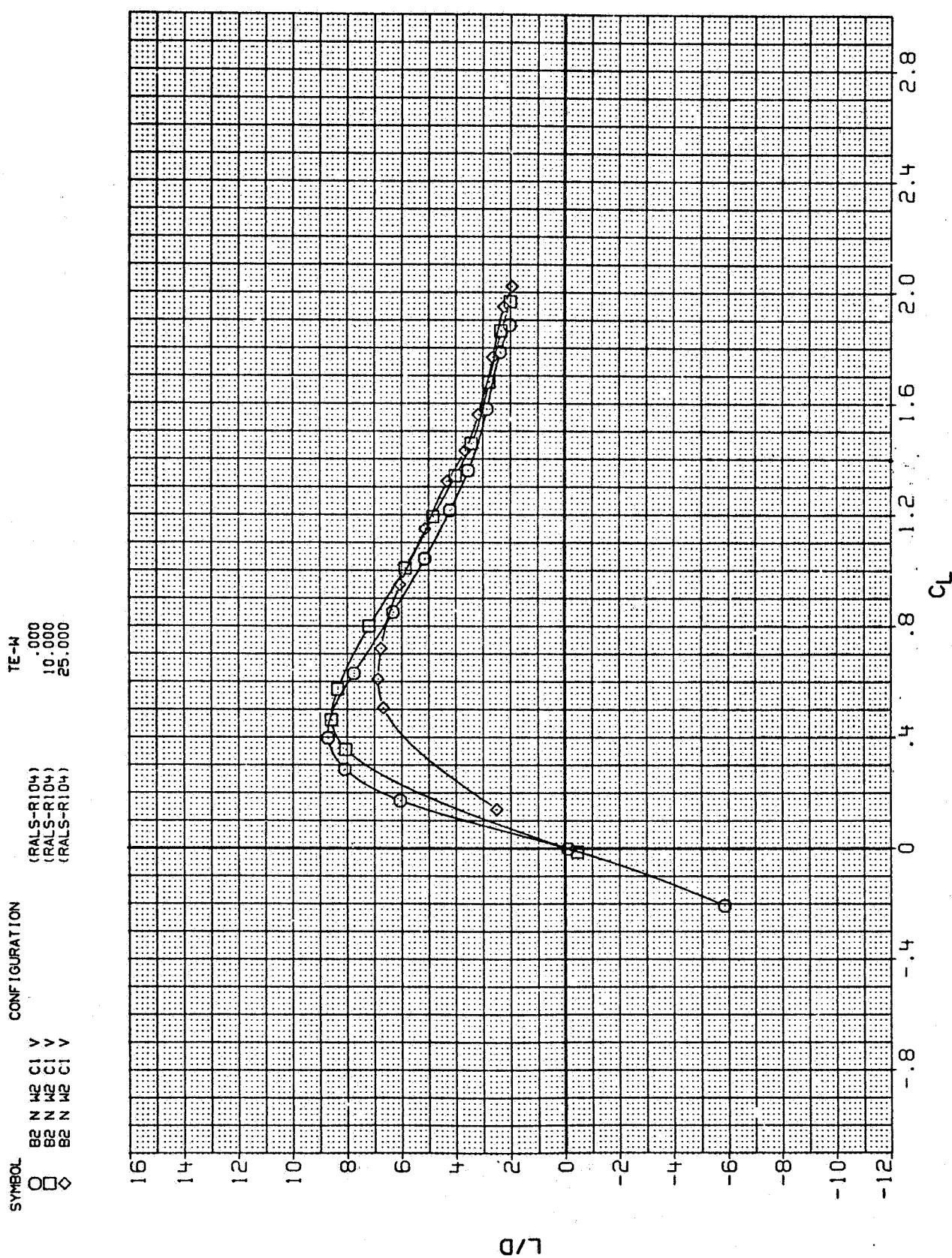


FIG. 108 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = .90

SYMBOL CONFIGURATION TE-W
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

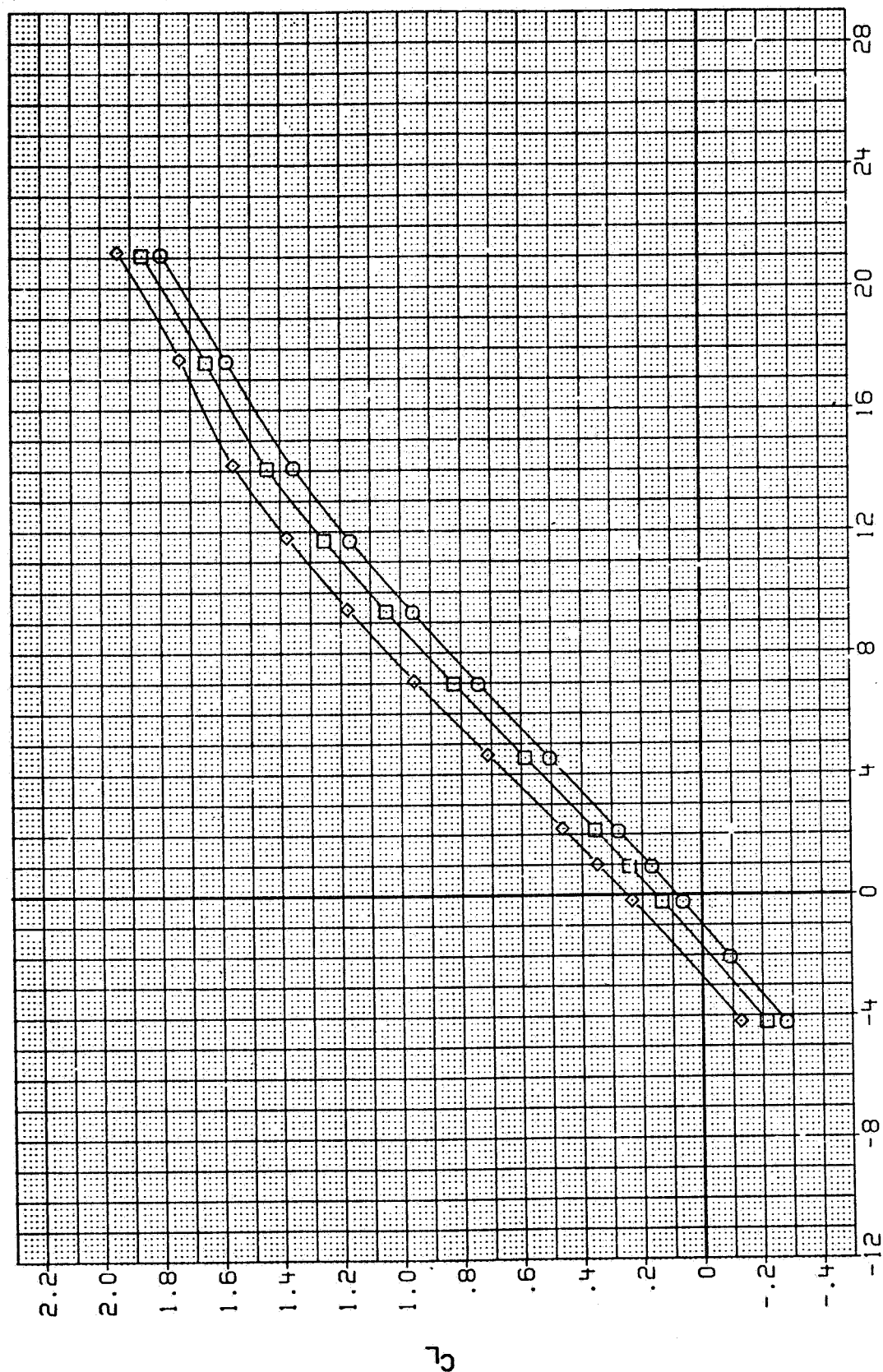


FIG. 109 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = 1.20

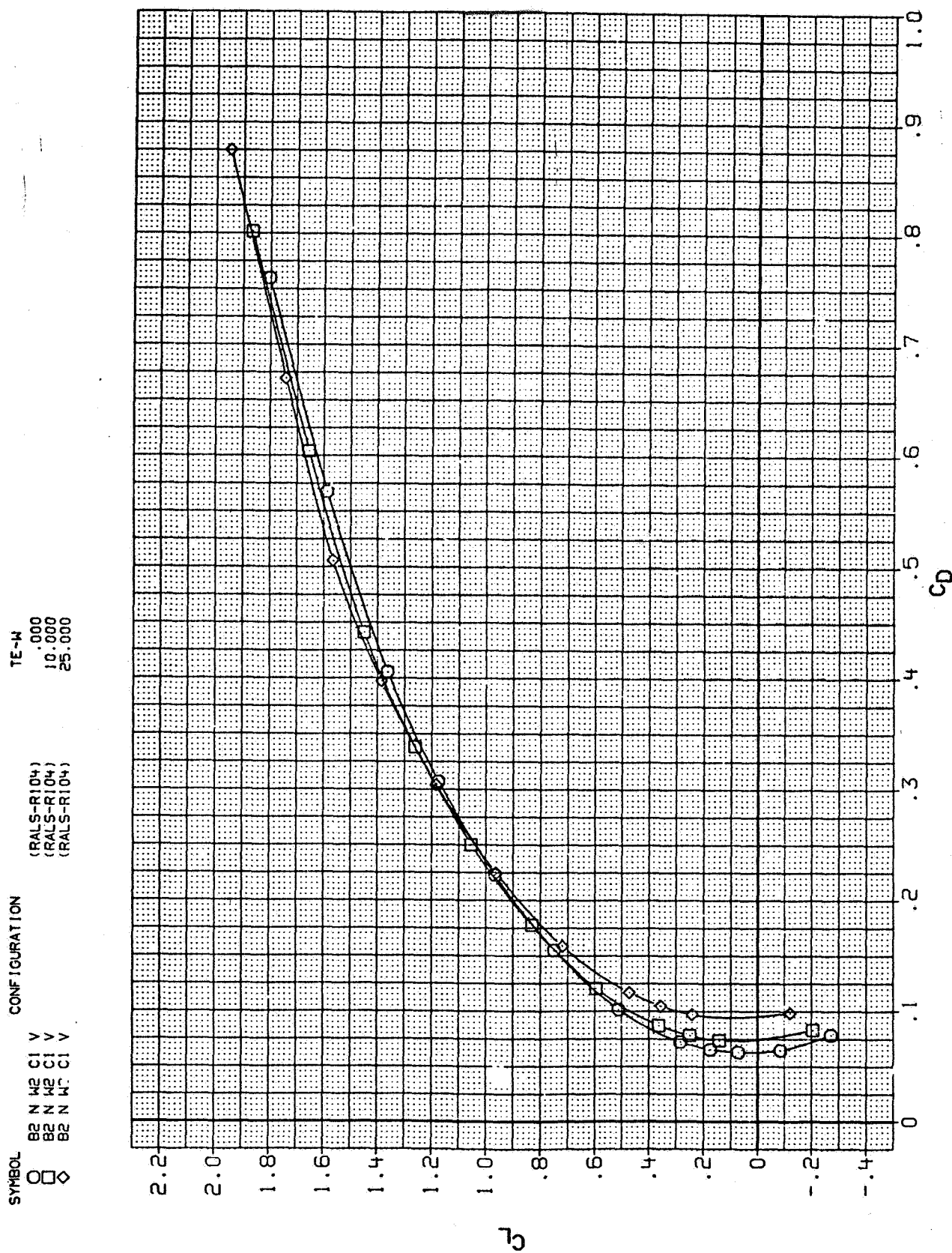


FIG. 109 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = 1.20

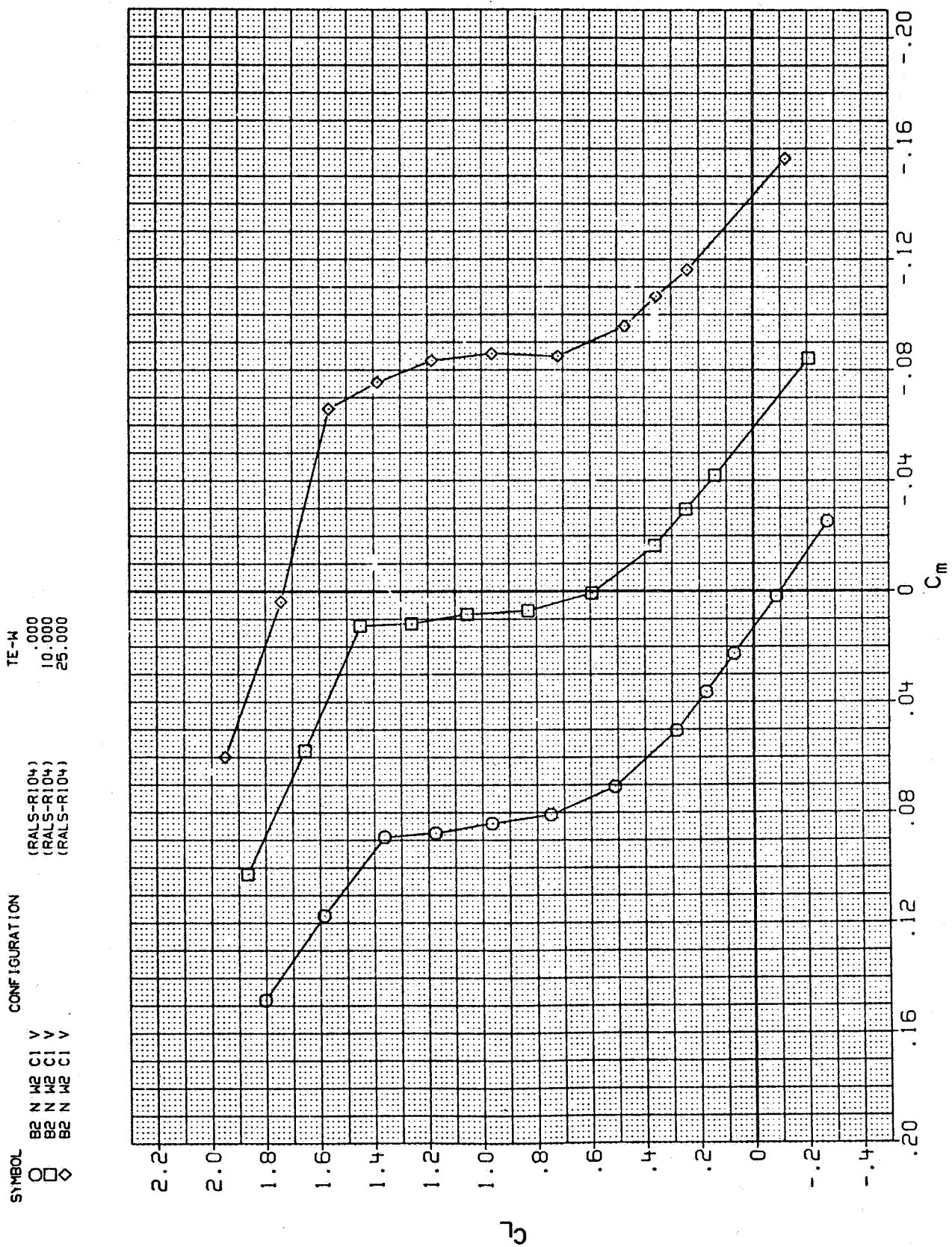


FIG. 109 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = 1.20

TE-W
.000
10.000
25.000

CONFIGURATION

(RALS-R104)
(RALS-R104)
(RALS-R104)

SYMBOL

B2 N W2 C1 V
B2 N W2 C1 V
B2 N W2 C1 V

○ □ ◇

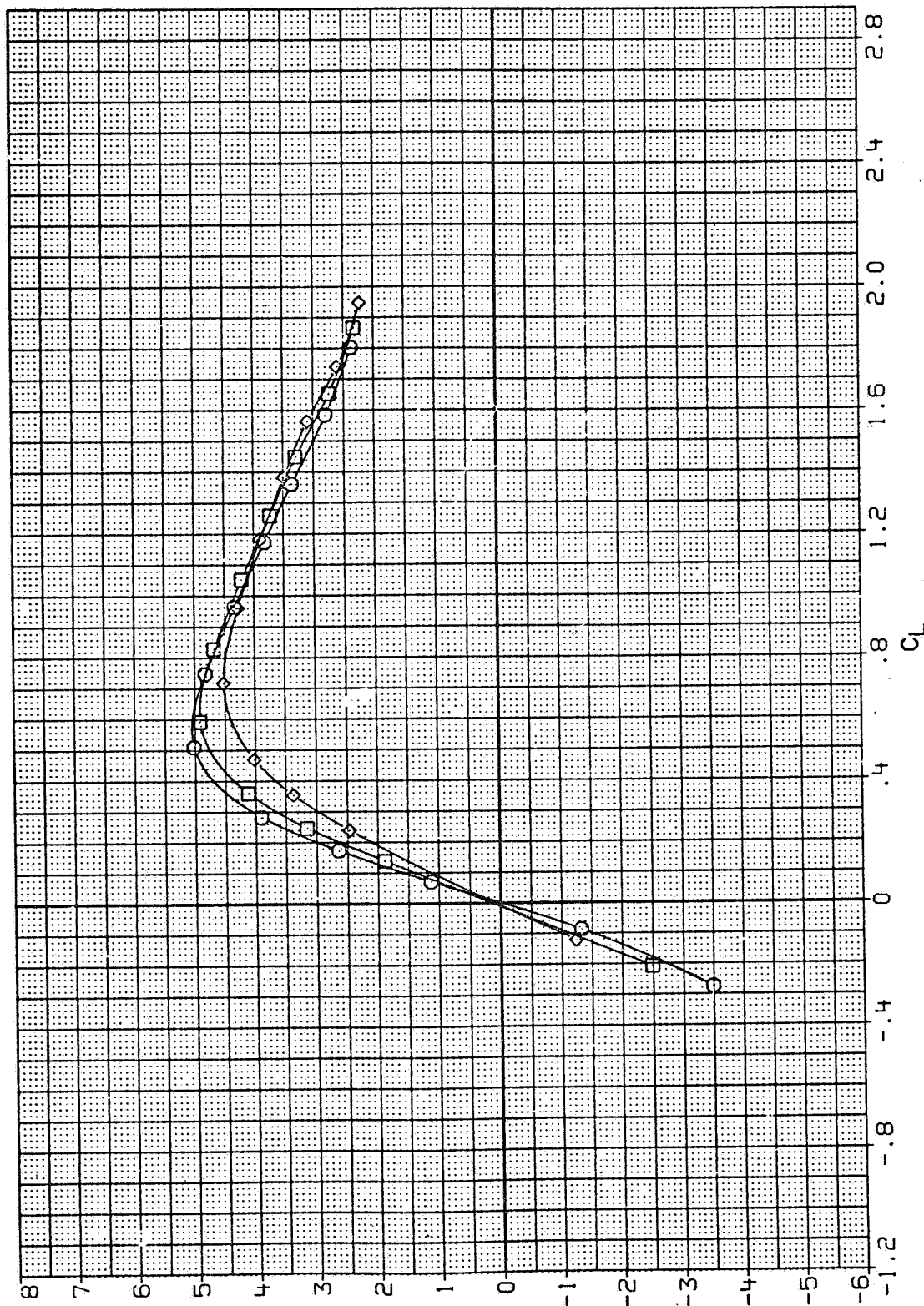


FIG. 109 FLAP DEFLECTION EFFECTS, CANARD = 0 DEGREES

MACH = 1.20

SYMBOL CONFIGURATION VERT
 ○ B2 N W2 C1 V .000
 □ B2 N W2 C1 V 5.000
 ◇ B2 N W2 C1 V 15.000

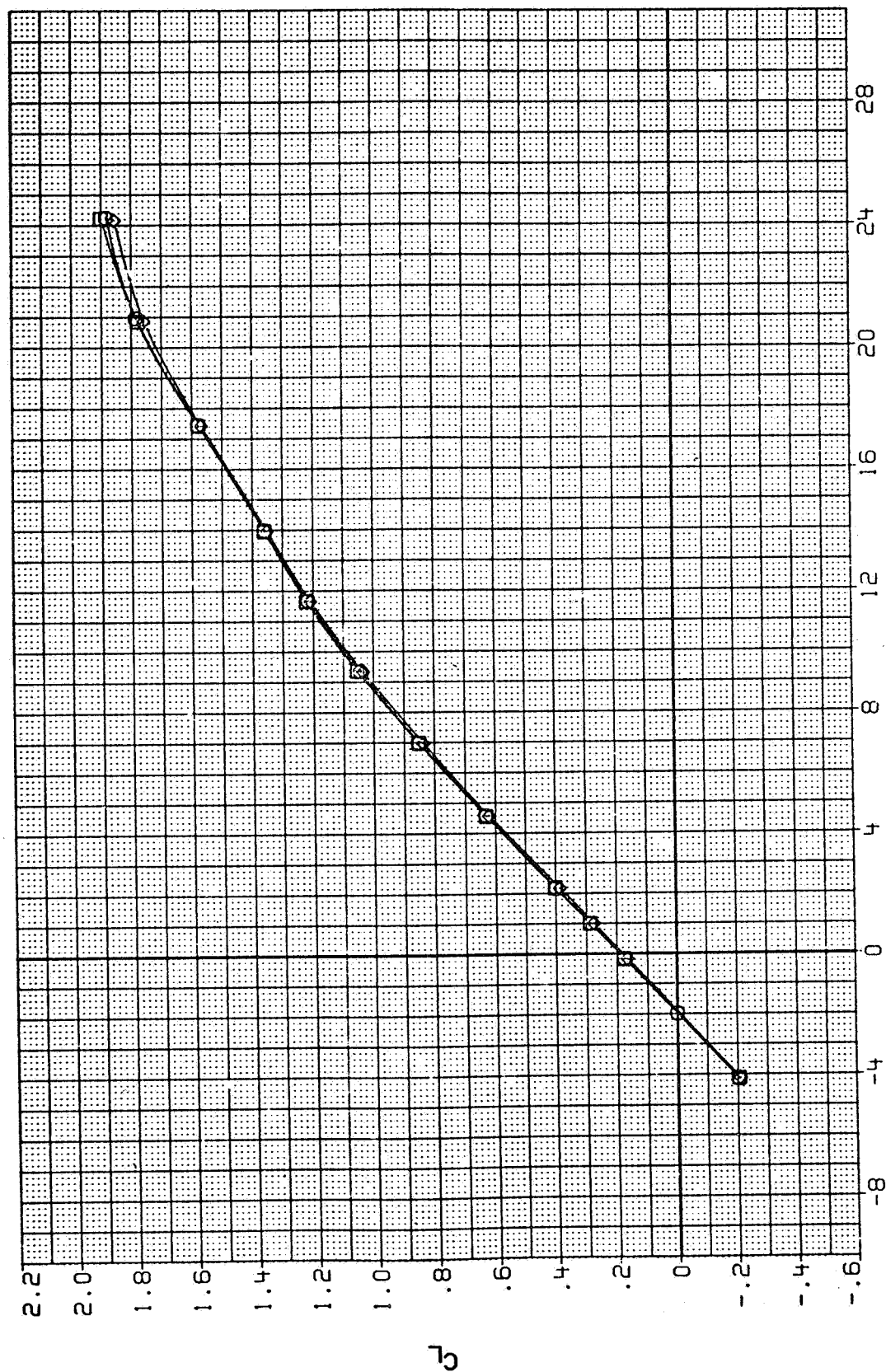


FIG. 110 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .90

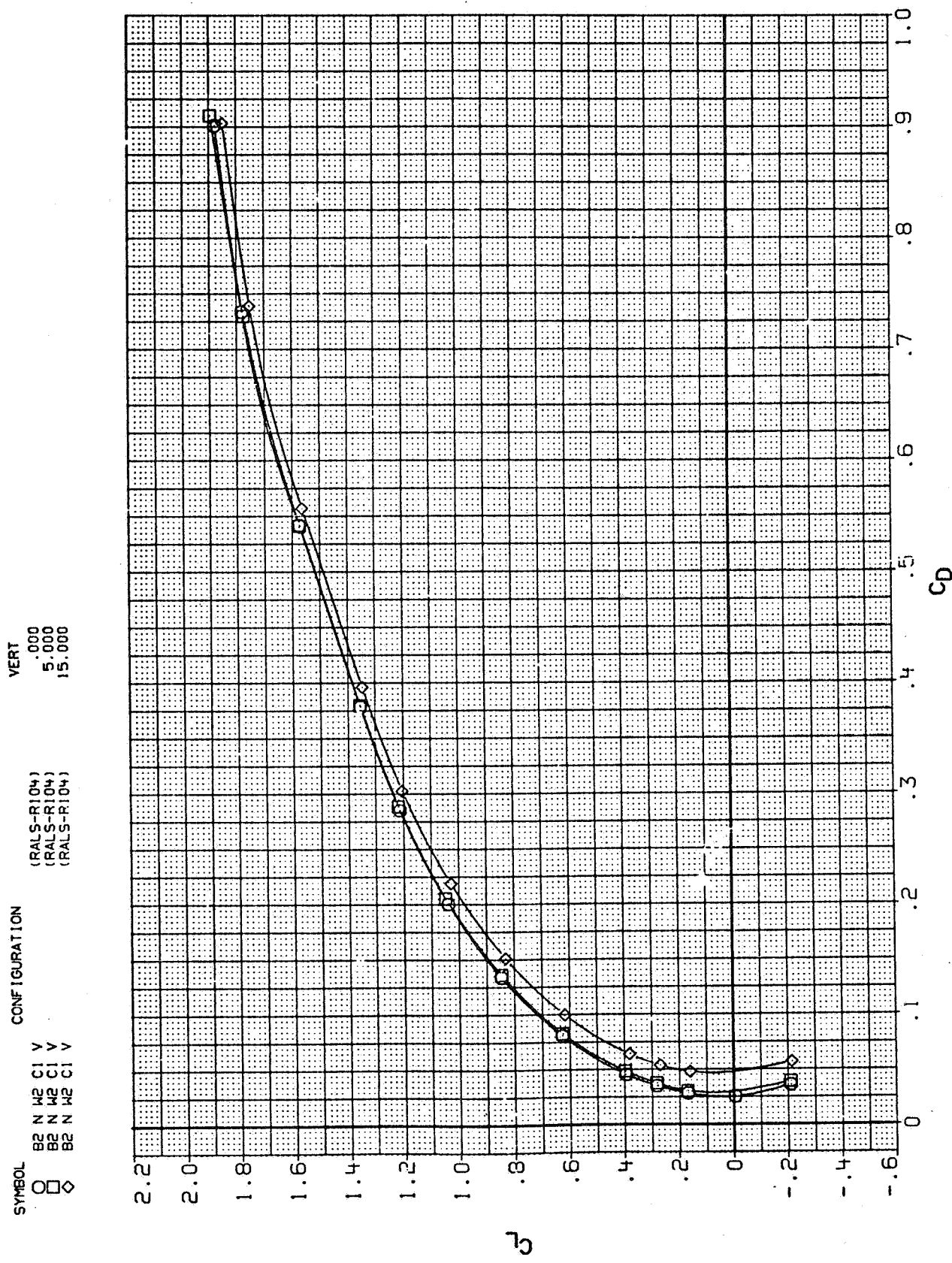


FIG. 110 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL	CONFIGURATION	VERT
○	B2 N W2 C1 V	.000
□	B2 N W2 C1 V	5.000
◇	B2 N W2 C1 V	15.000

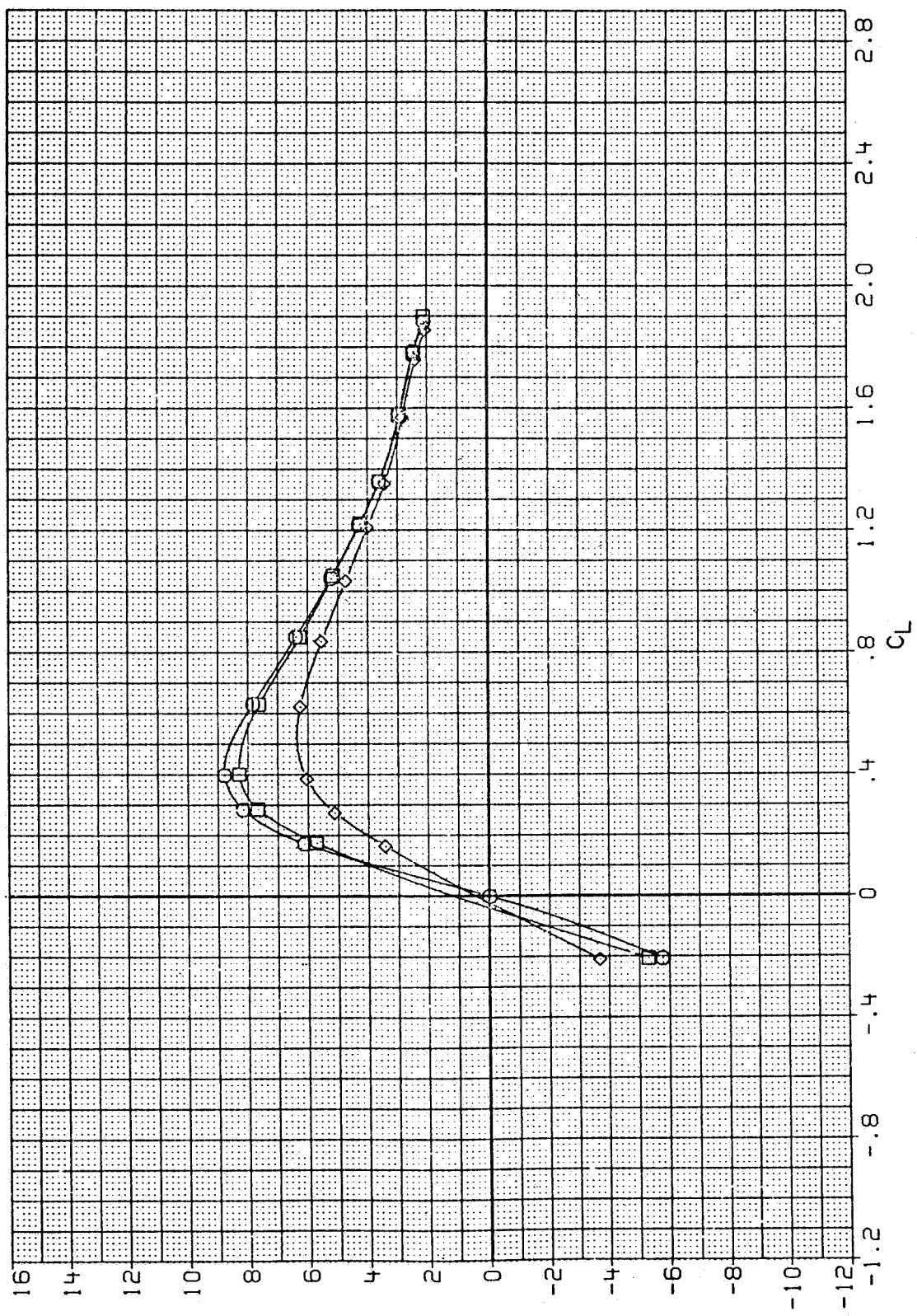


FIG. 110 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .90

VERT
.000
5.000
15.000

(RALS-R104)
(RALS-R104)
(RALS-R104)

CONF IGURATION

B2 N W2 C1 V
B2 N W2 C1 V
B2 N W2 C1 V

SYMBOL
□
◇

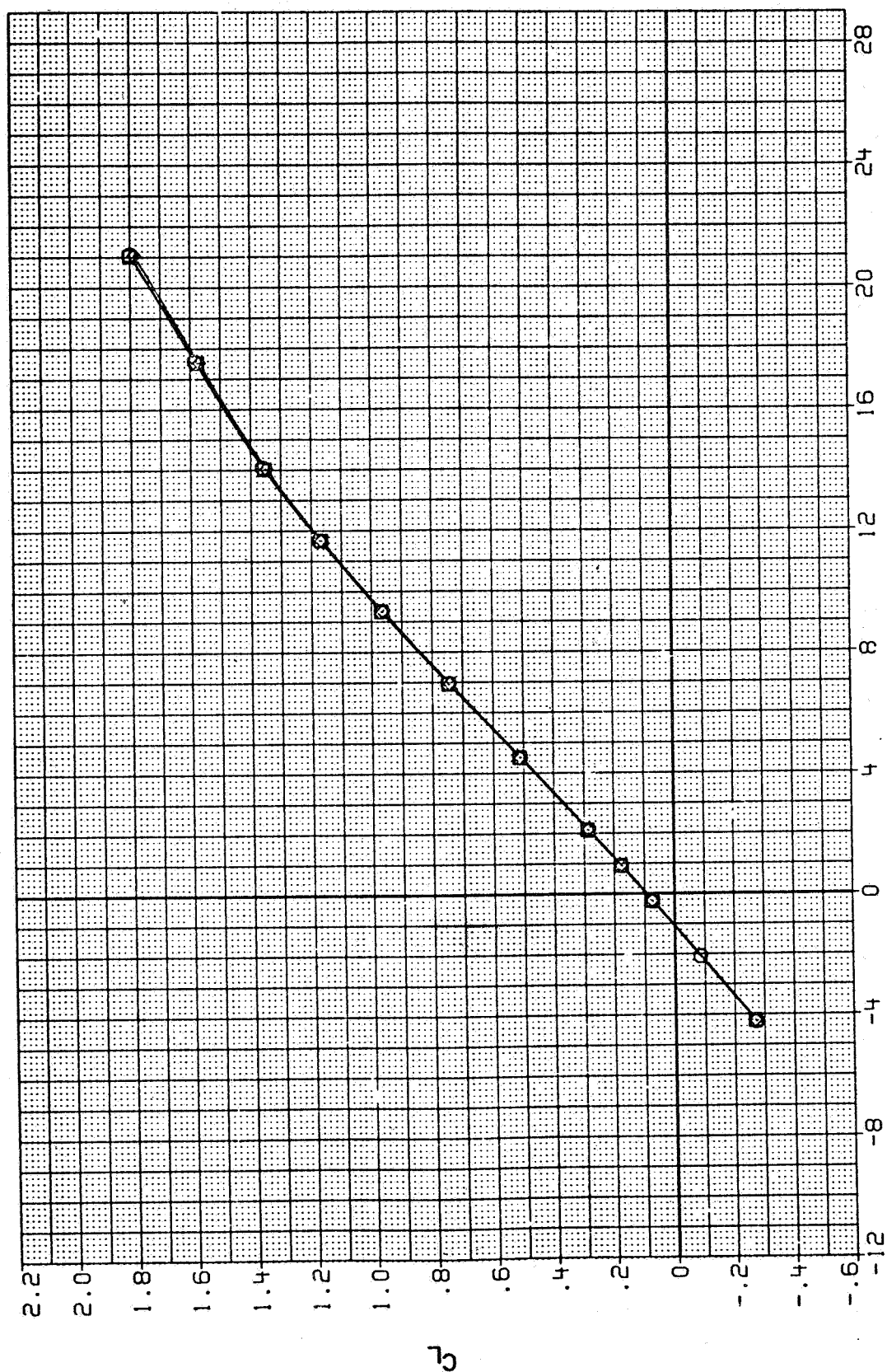


FIG. 111 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL CONF IGURATION VERT
 B2 N W2 C1 V (RALS-R104)
 B2 N W2 C1 V (RALS-R104)
 B2 N W2 C1 V (RALS-R104)

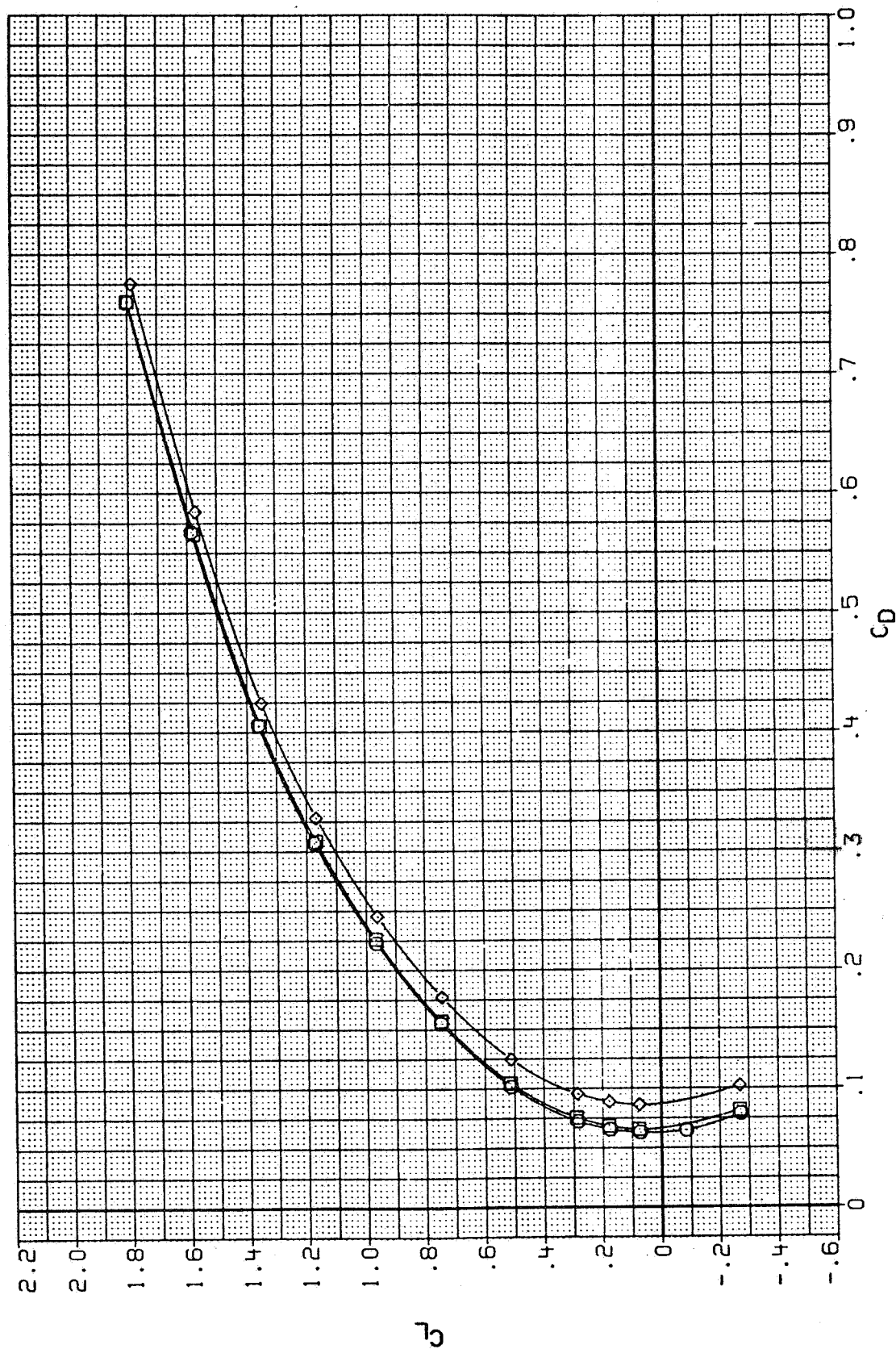


FIG. 111 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

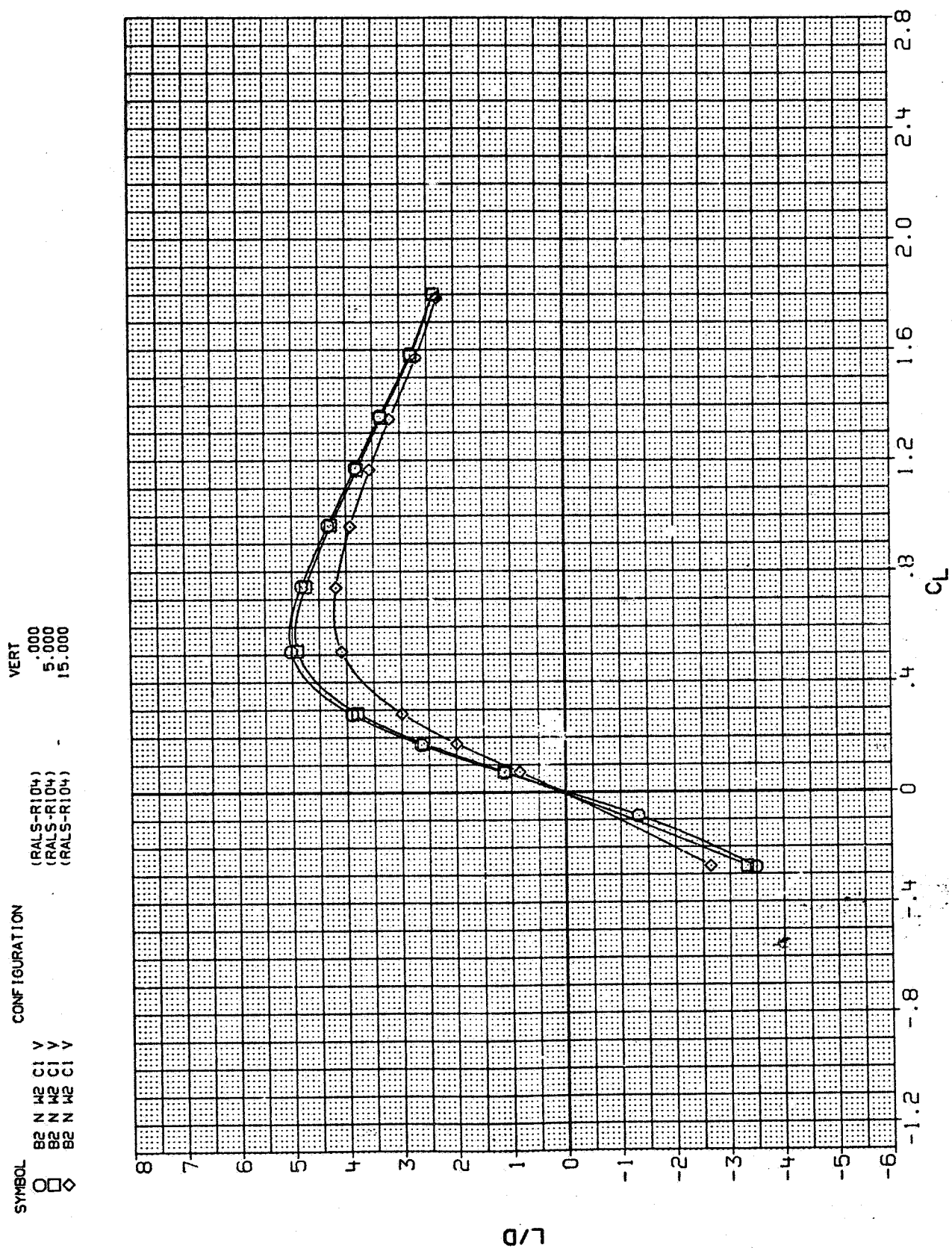


FIG. 111 VERTICAL TAIL DEFLECTION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

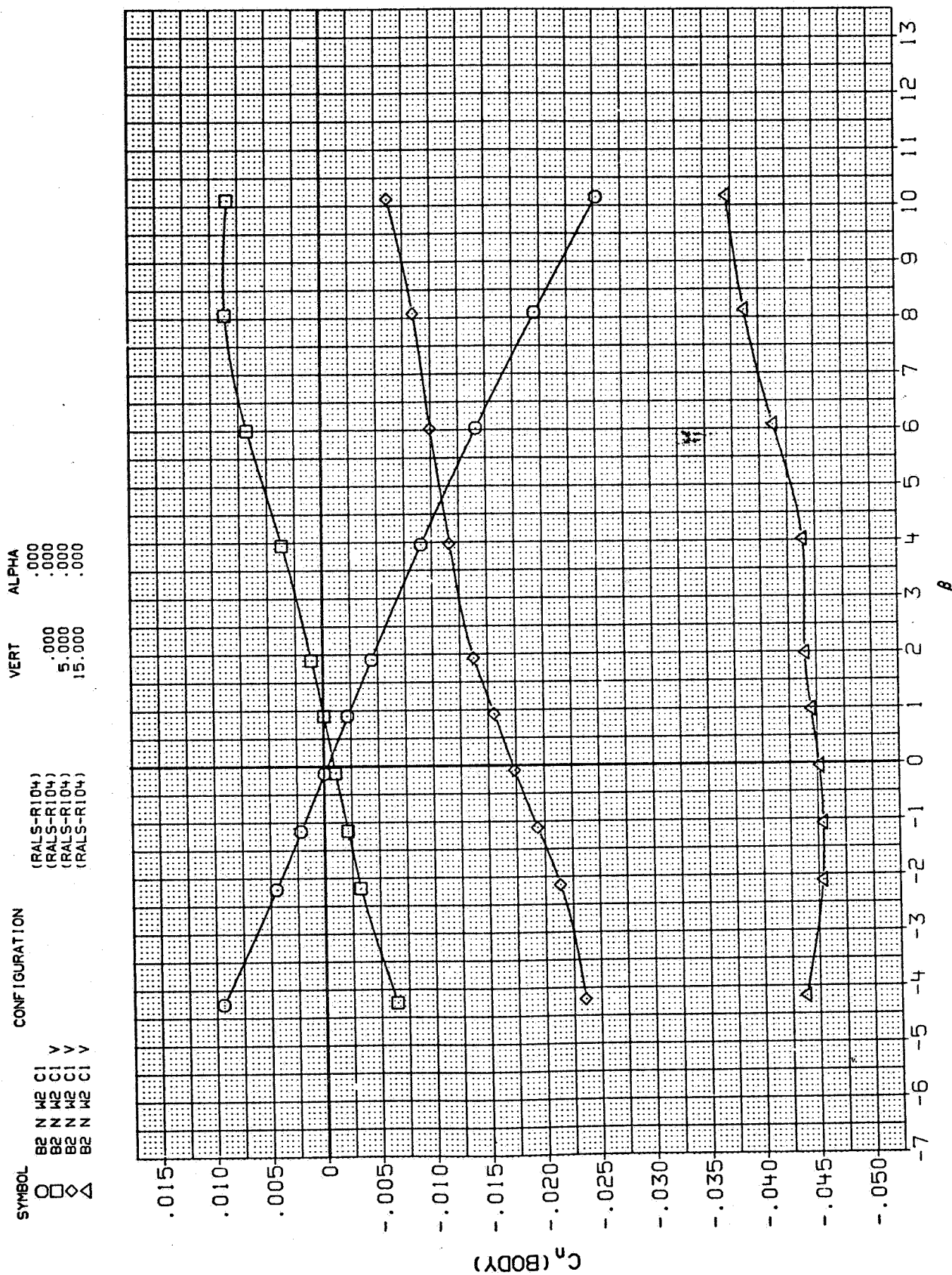


FIG. 112 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 0 DEGREES

MACH = .90

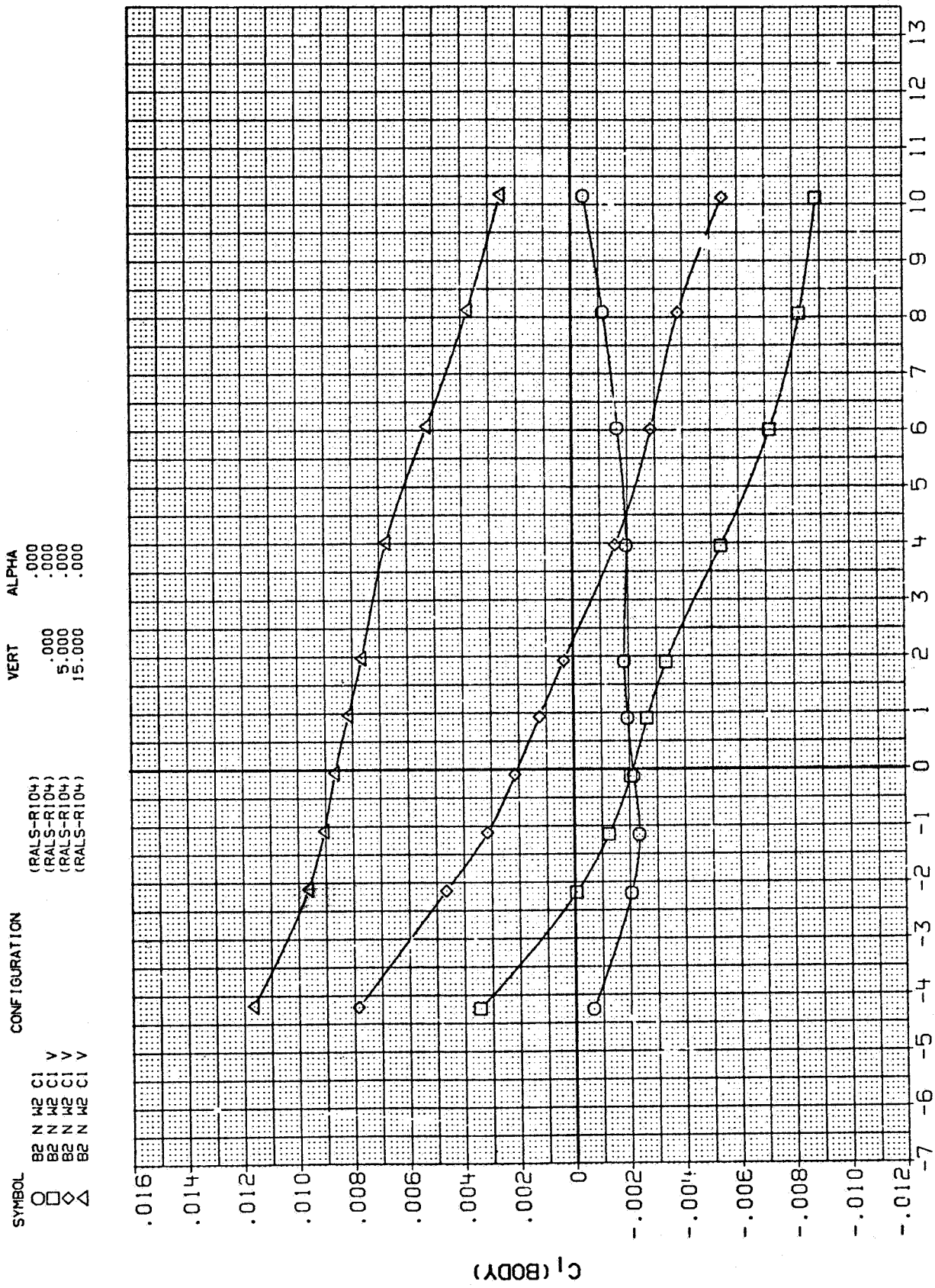


FIG. 112 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES
 MACH = .90

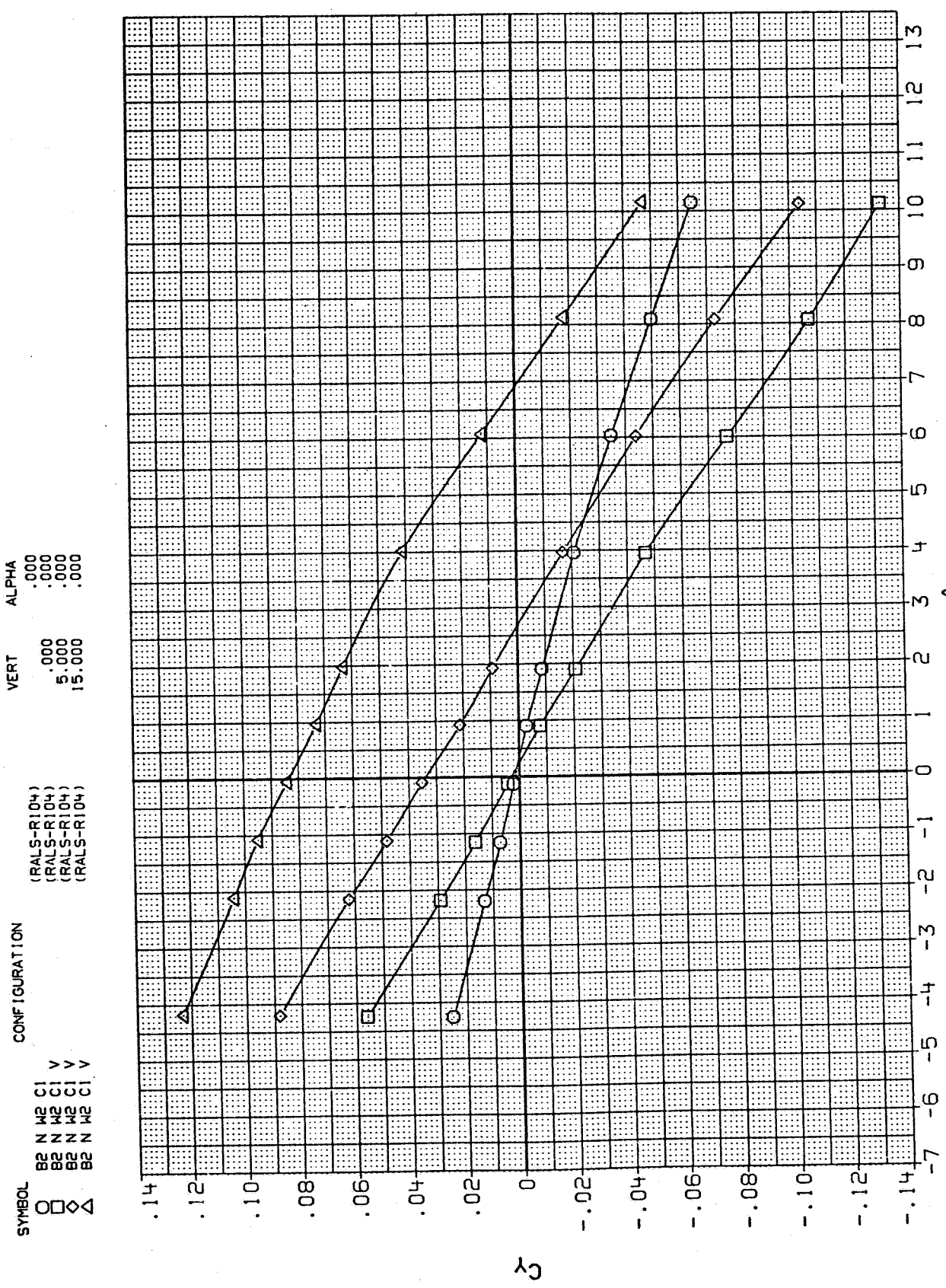


FIG. 112 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES
 MACH = .90

SYMBOL	CONFIGURATION	VERT	ALPHA
○	B2 N W2 C1	17.500	17.500
□	B2 N W2 C1 V	17.000	17.000
◇	B2 N W2 C1 V	5.000	17.500
△	B2 N W2 C1 V	15.000	11.500

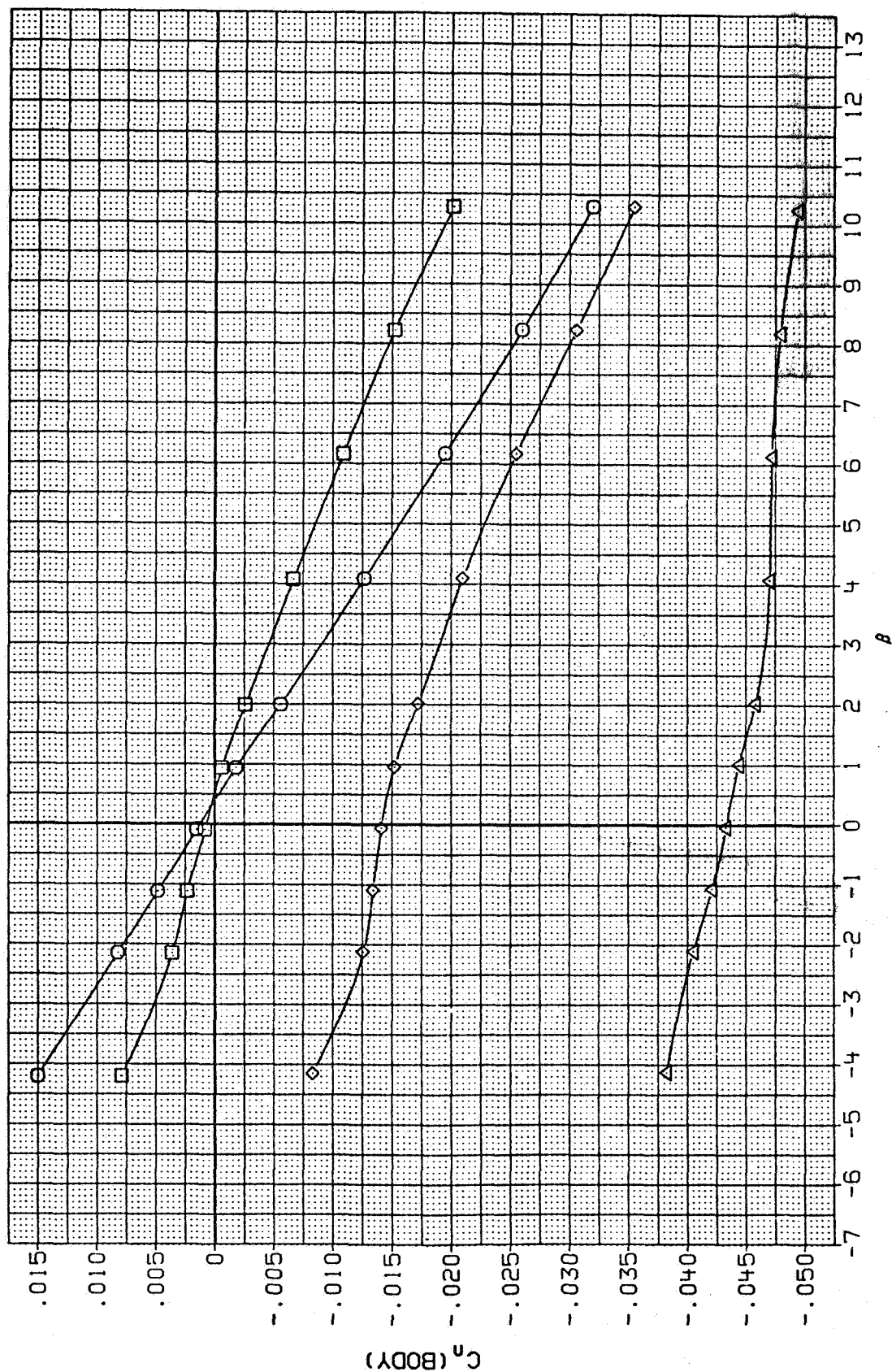


FIG. 112 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES
 MACH = .90

SYMBOL	CONFIGURATION	VERT	ALPHA
□	B2 N W2 C1 V	.000	17.500
◇	B2 N W2 C1 V	5.000	17.000
△	B2 N W2 C1 V	15.000	17.500
	(RALS-R104)		17.500
	(RALS-R104)		17.000
	(RALS-R104)		17.500

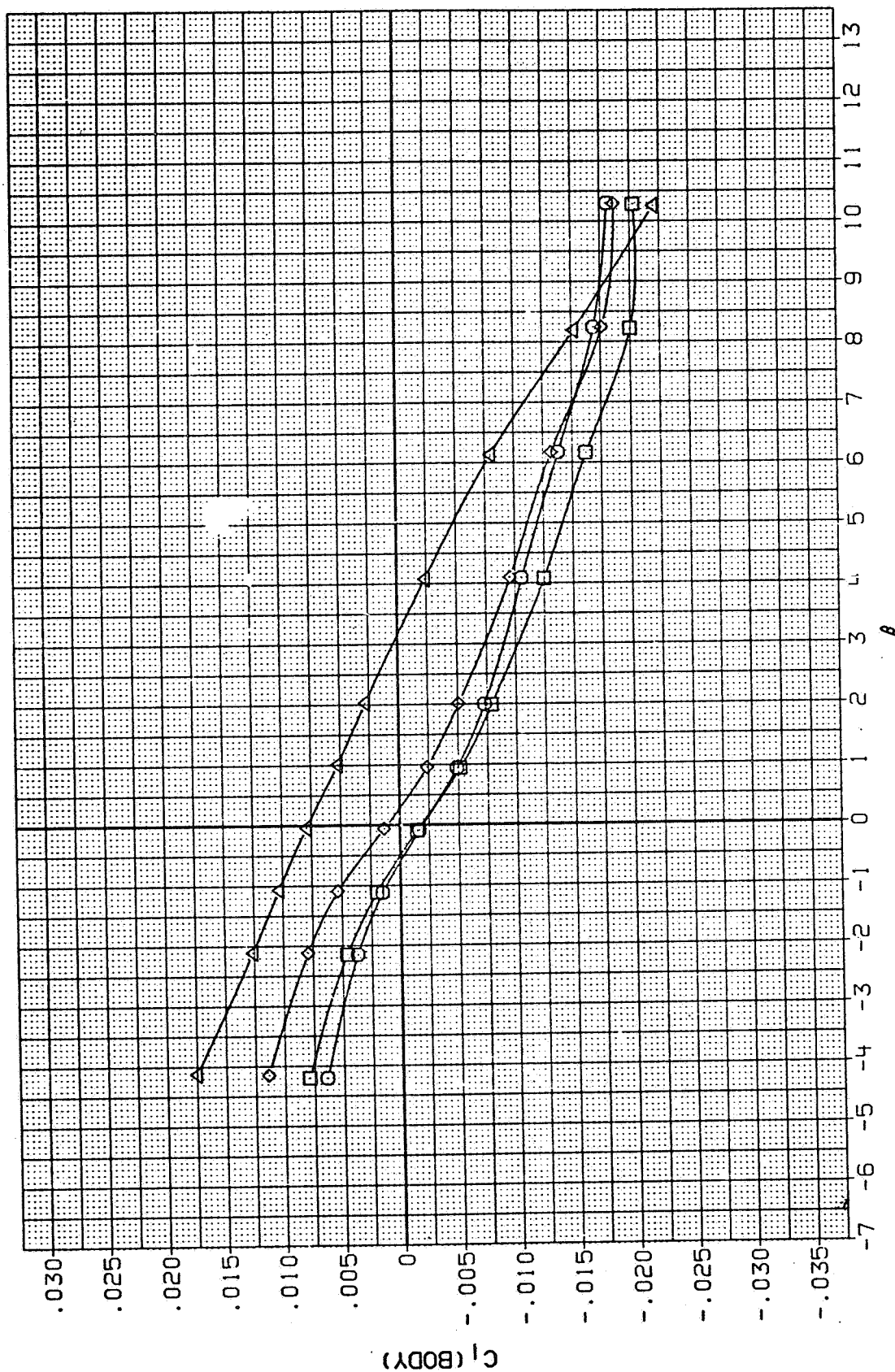


FIG. 112 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 15 DEGREES

MACH = .90

SYMBOL

B2 N W2 C1 V
B2 N W2 C1 V
B2 N W2 C1 V
B2 N W2 C1 V

CONFIGURATION

(RALS-R104)
(RALS-R104)
(RALS-R104)
(RALS-R104)

VERT

ALPHA
17.500
17.000
17.500
11.500

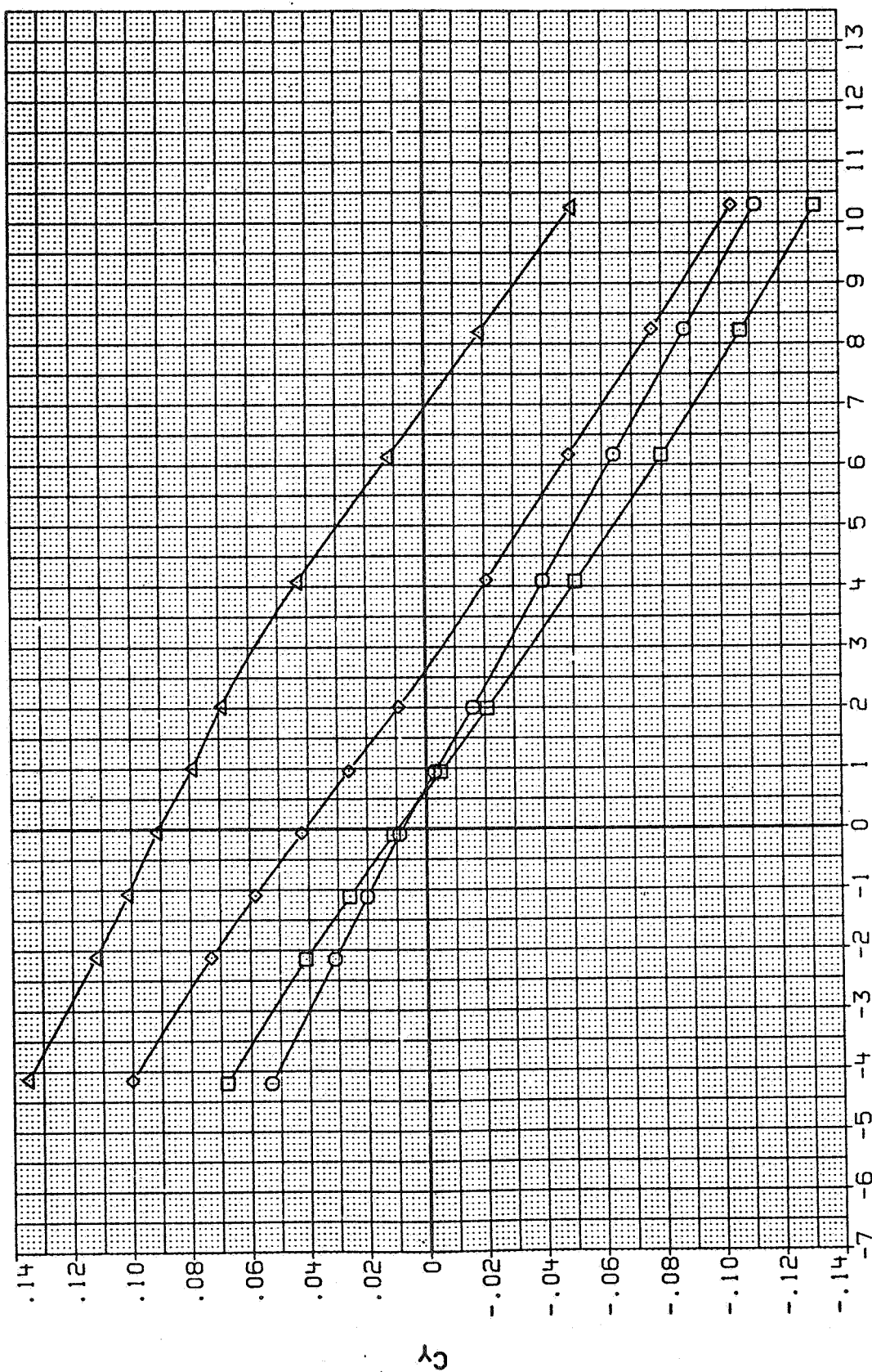


FIG. 112 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 15 DEGREES

MACH = .90

SYMBOL	CONFIGURATION	VERT	ALPHA
○	B2 N W2 C1 V	.000	.000
◇	B2 N W2 C1 V	.000	.000
△	B2 N W2 C1 V	.000	.000
	(RALS-R104)	5.000	.000
	(RALS-R104)	15.000	.000

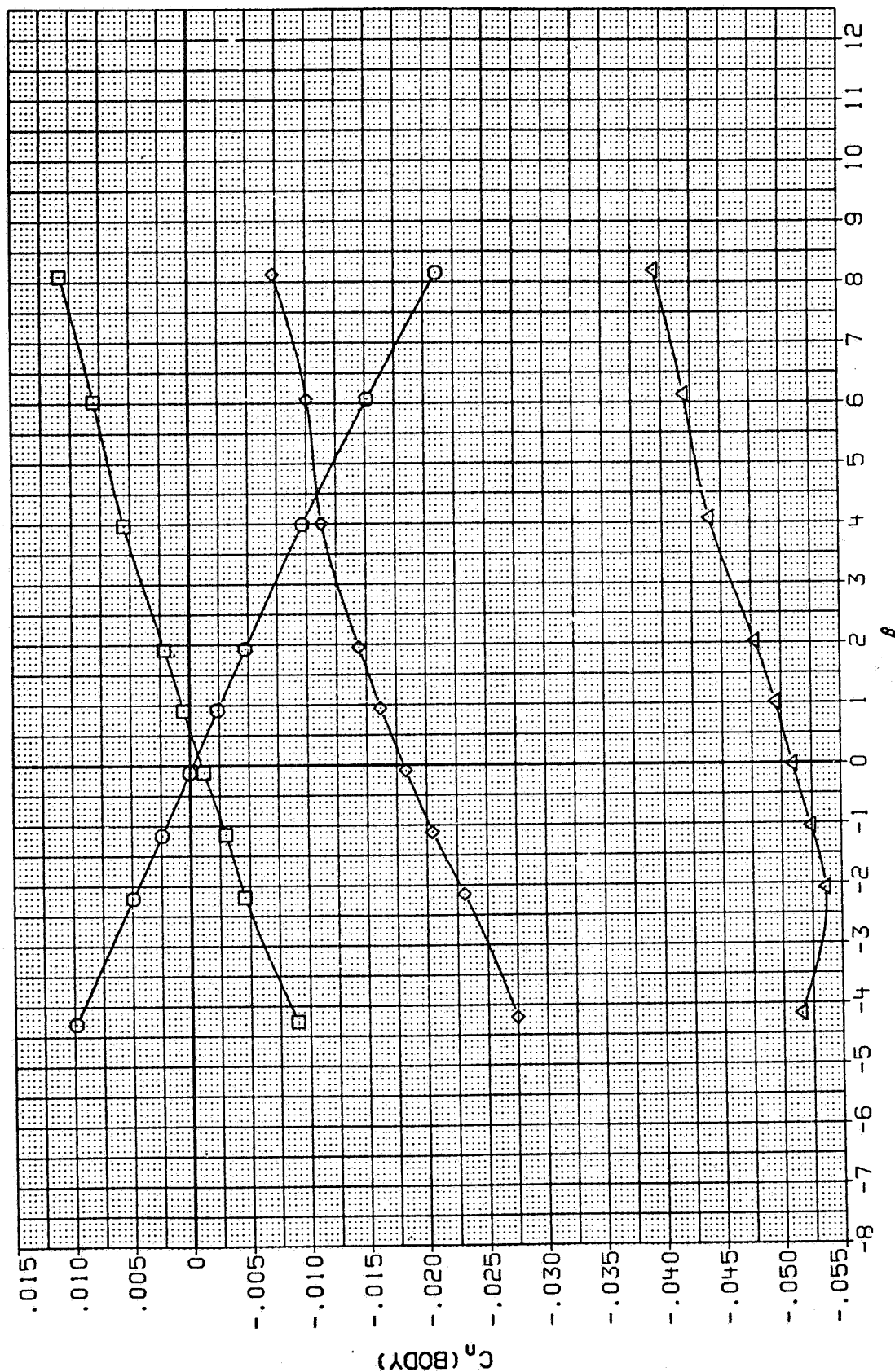


FIG. 113 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 0 DEGREES

MACH = 1.20

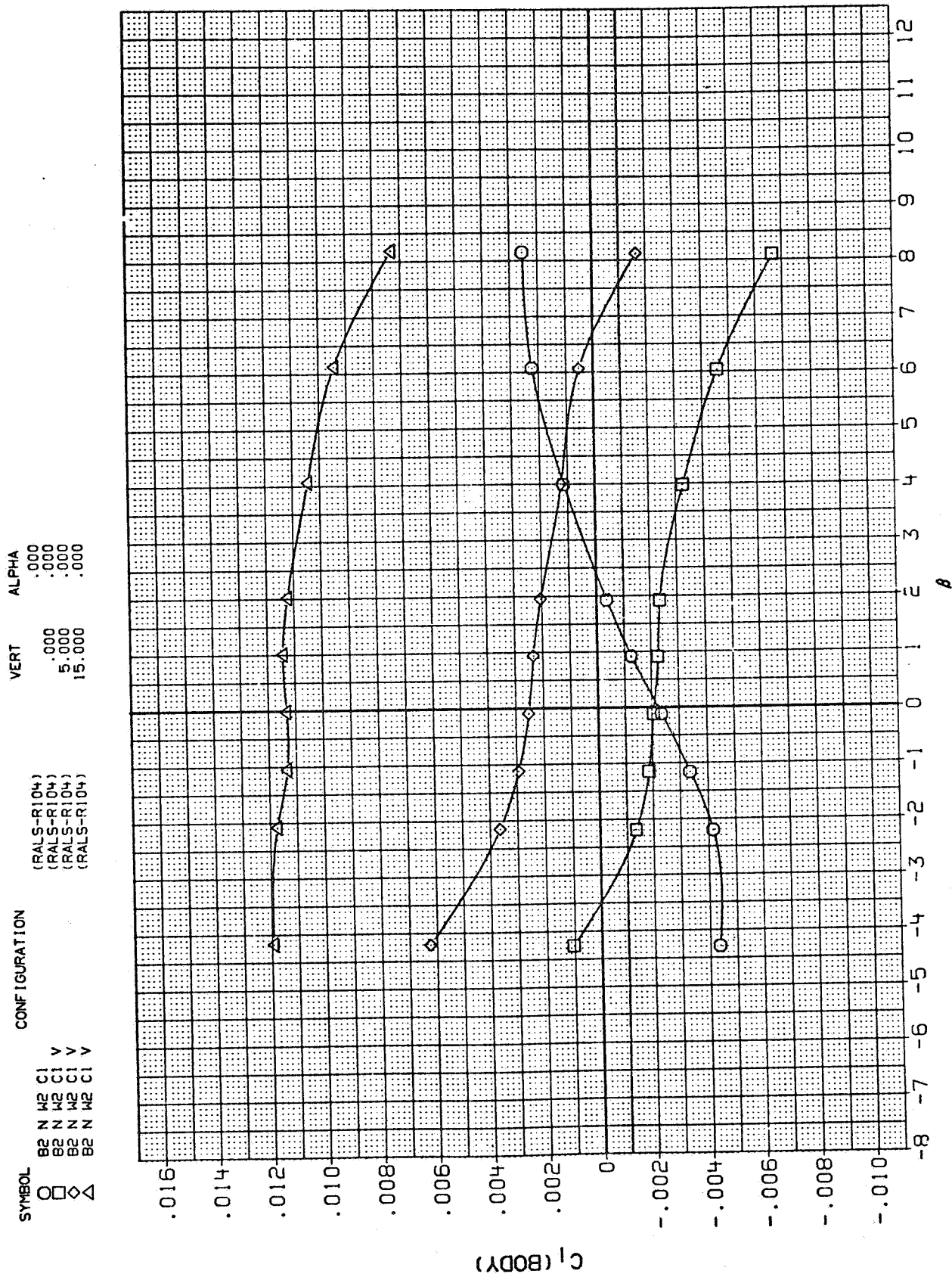


FIG. 113 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES
 MACH = 1.20

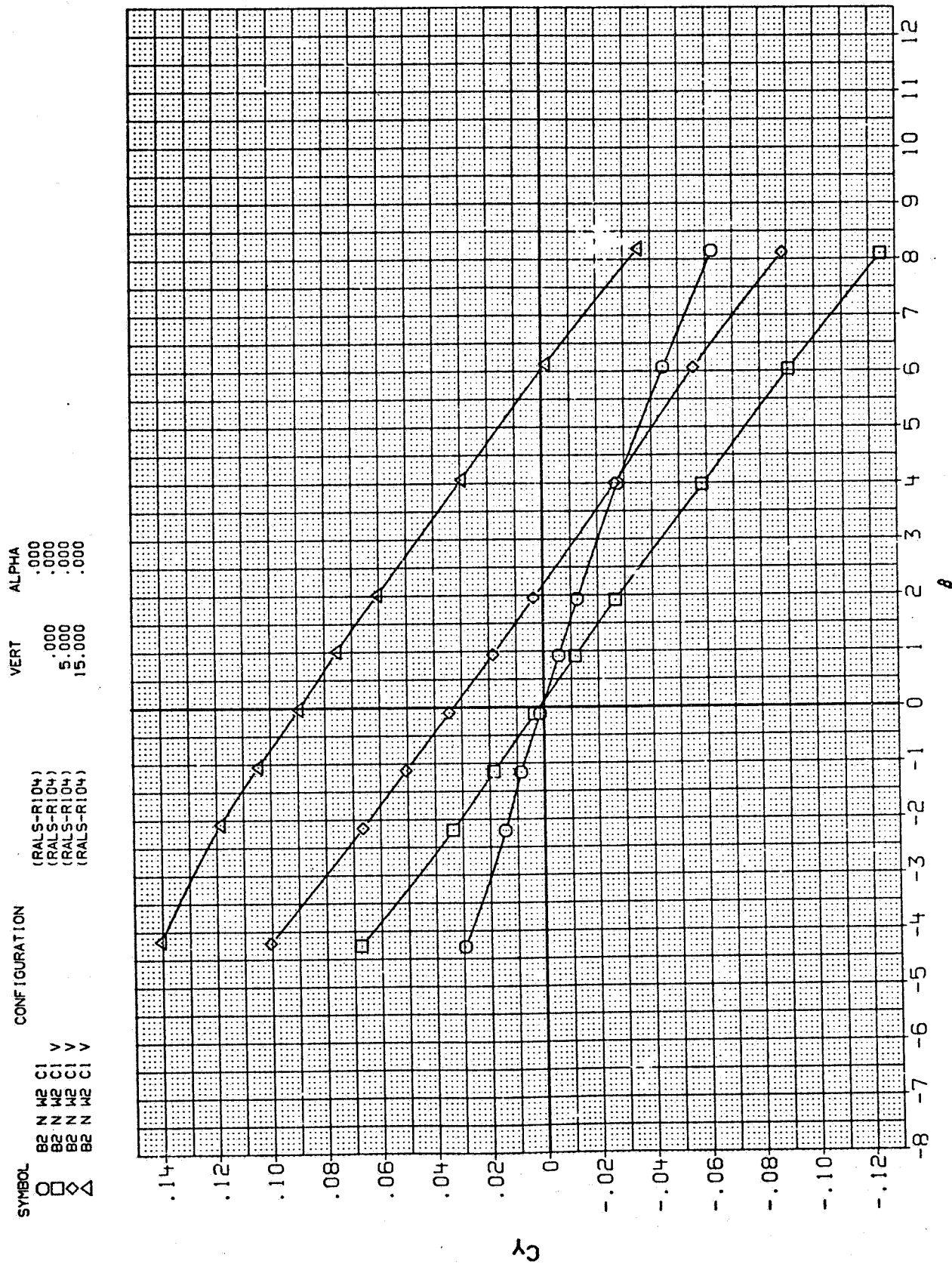


FIG. 113 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 $\alpha = 0$ DEGREES

MACH = 1.20

SYMBOL	CONFIGURATION	VERT	ALPHA
○	B2 N W2 C1 V	.000	11.500
□	B2 N W2 C1 V	5.000	11.500
◇	B2 N W2 C1 V	15.000	11.500
△	B2 N W2 C1 V	15.000	11.500

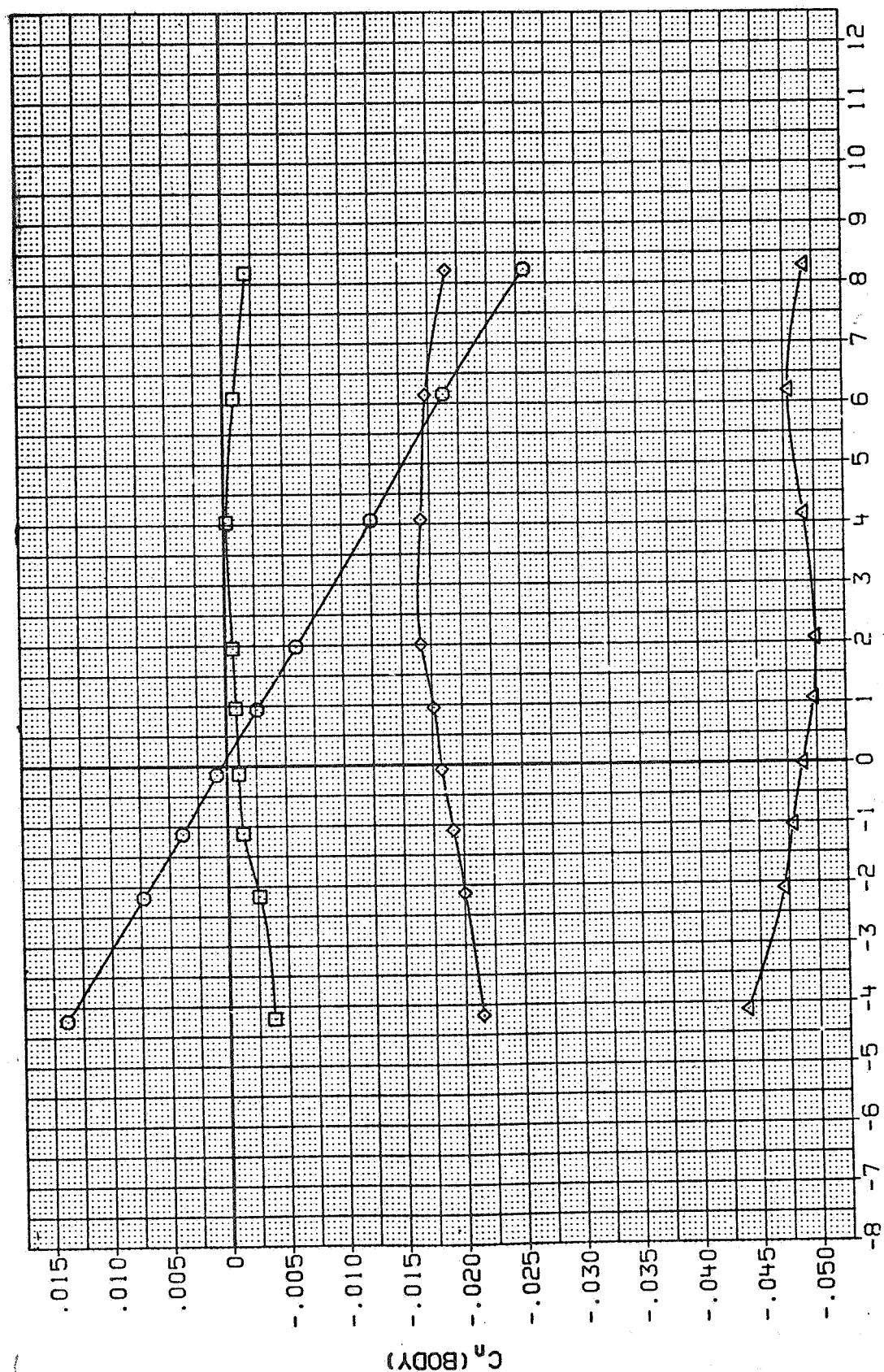


FIG. 113 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 10 DEGREES

MACH = 1.20

SYMBOL CONFIGURATION VERT ALPHA
 ○ B2 N W2 C1 V .000 11.500
 □ B2 N W2 C1 V 5.000 11.500
 △ B2 N W2 C1 V 15.000 11.500
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

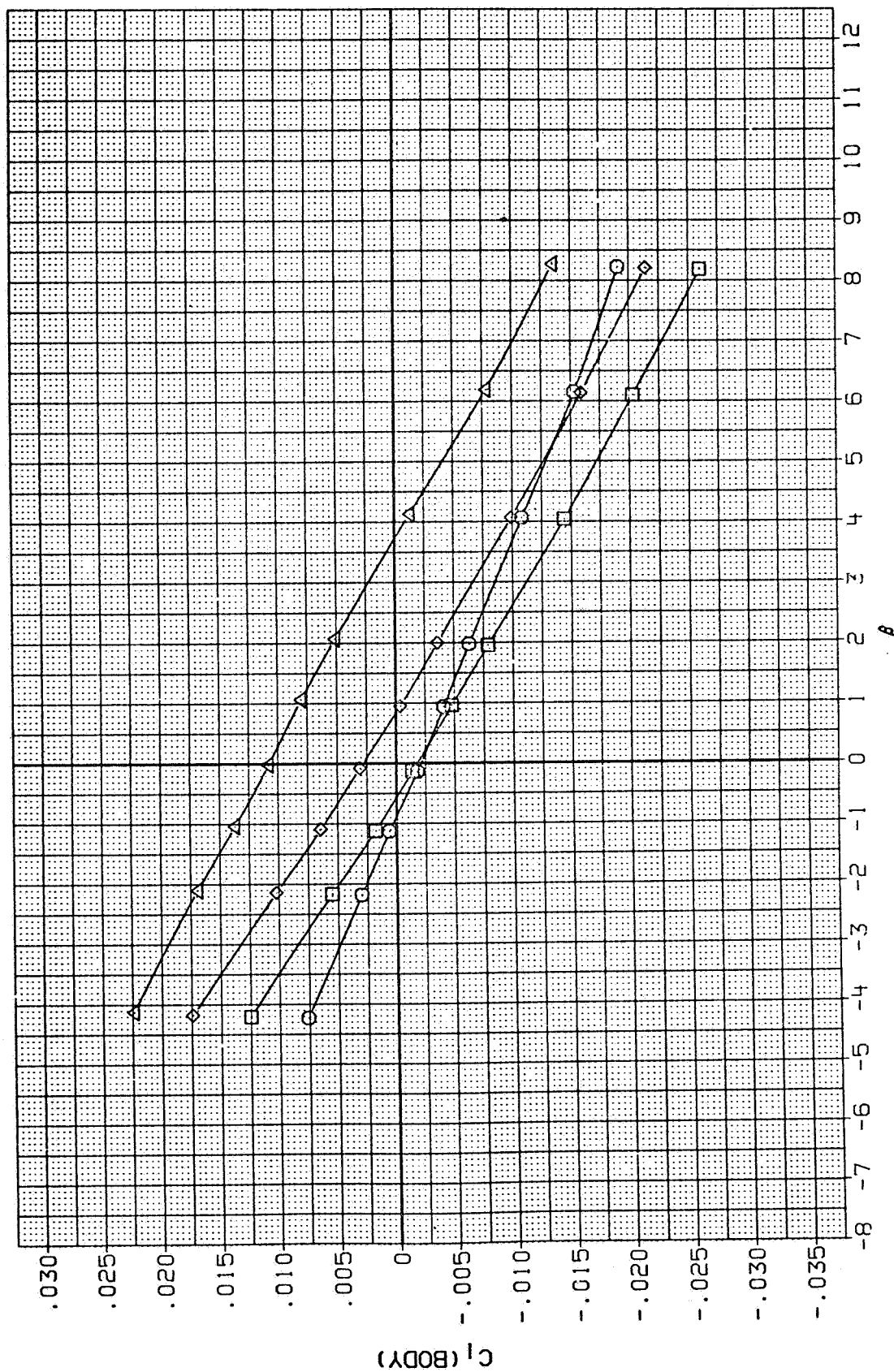


FIG. 113 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES
 MACH = 1.20

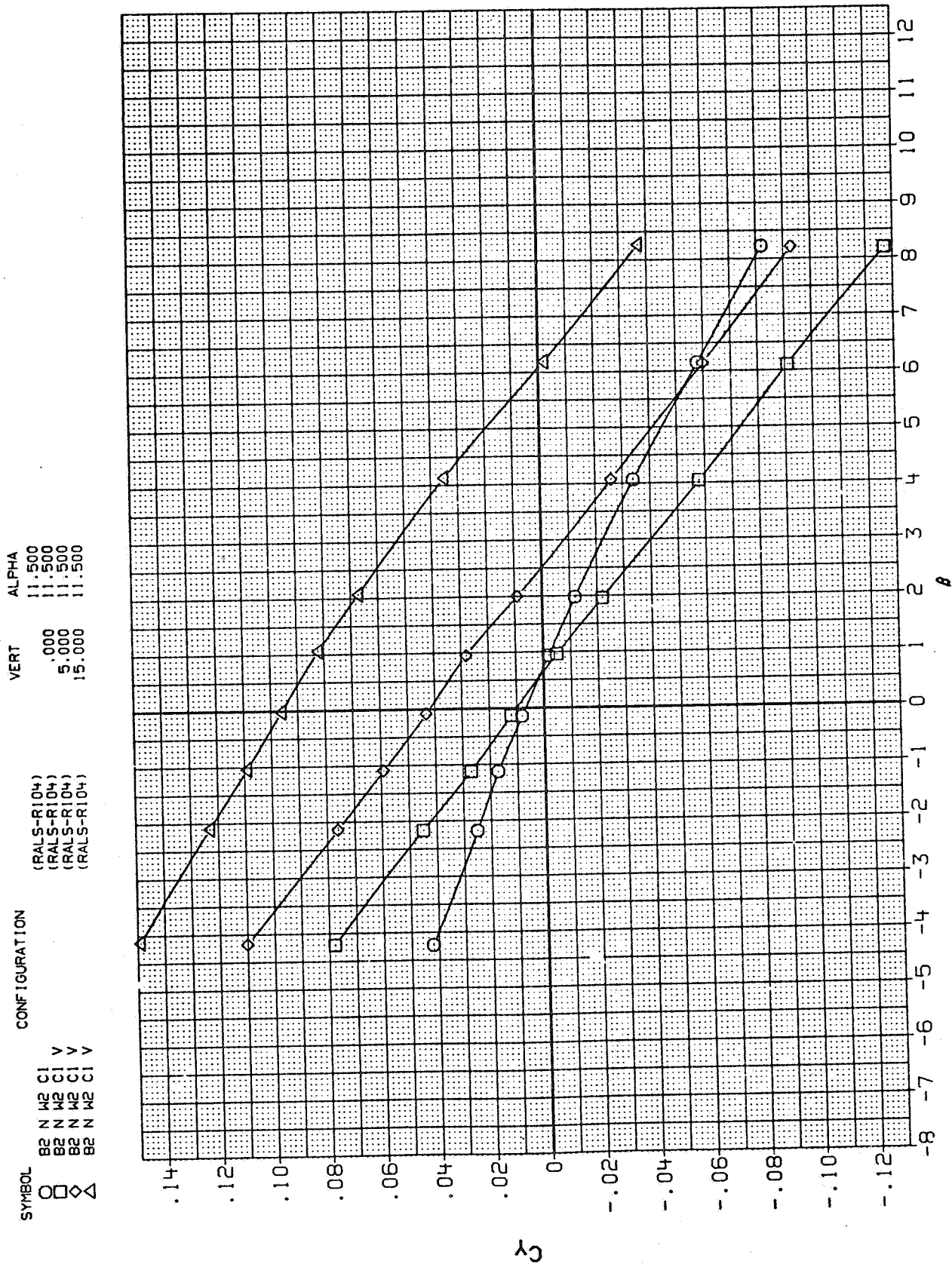


FIG. 113 VERTICAL TAIL DEFLECTION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES
 MACH = 1.20

SYMBOL		CONFIGURATION	
○	B2 N W2 C1 V	(RALS-R104)	
◇	B2 N W2 C2 V	(RALS-R104)	
◇	B2 N W2 C3 V	(RALS-R104)	

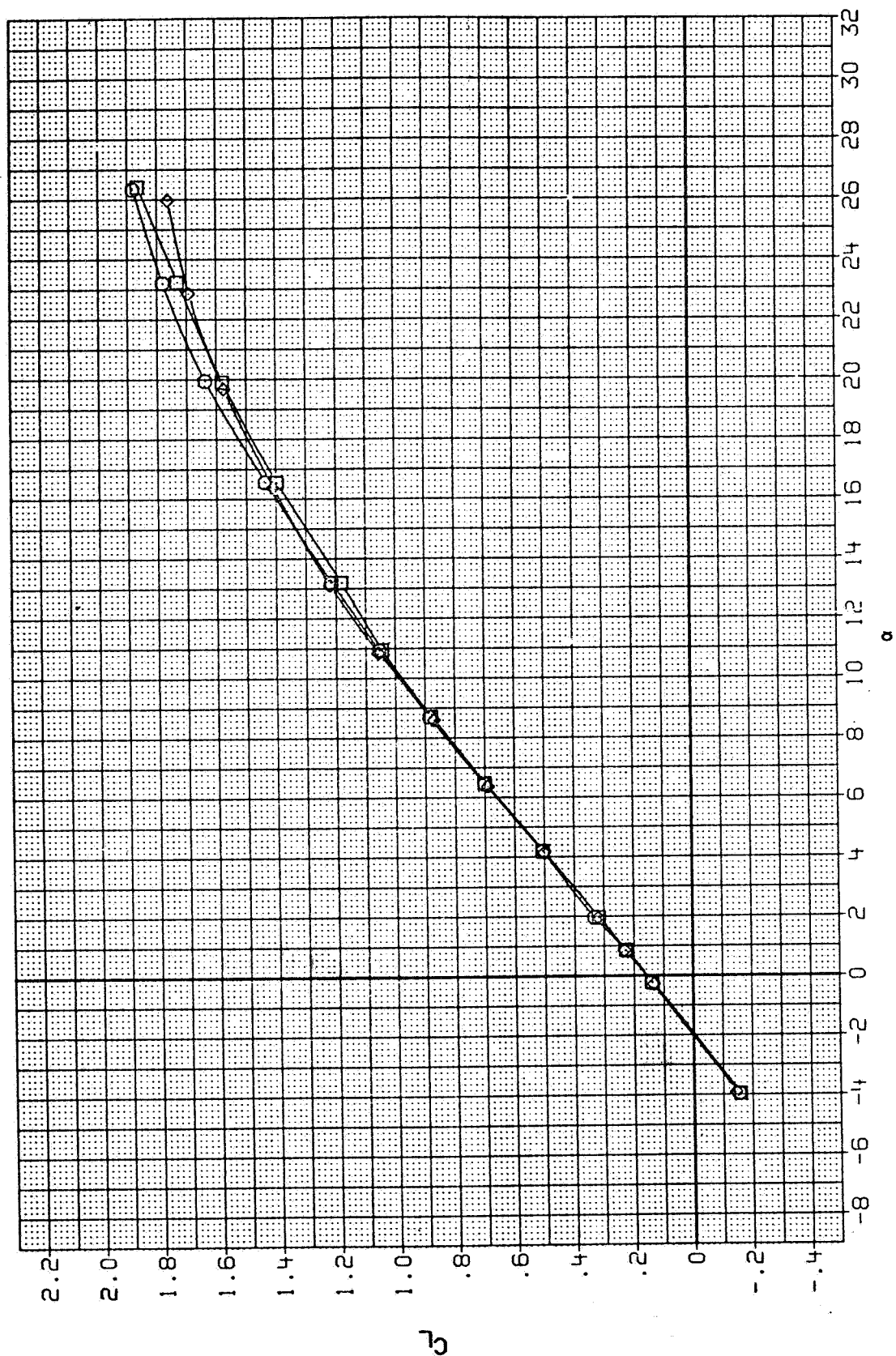


FIG. 114 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL CONFIGURATION
 ○ B2 N W2 C1 V (RALS-R104)
 □ B2 N W2 C2 V (RALS-R104)
 ◇ B2 N W2 C3 V (RALS-R104)

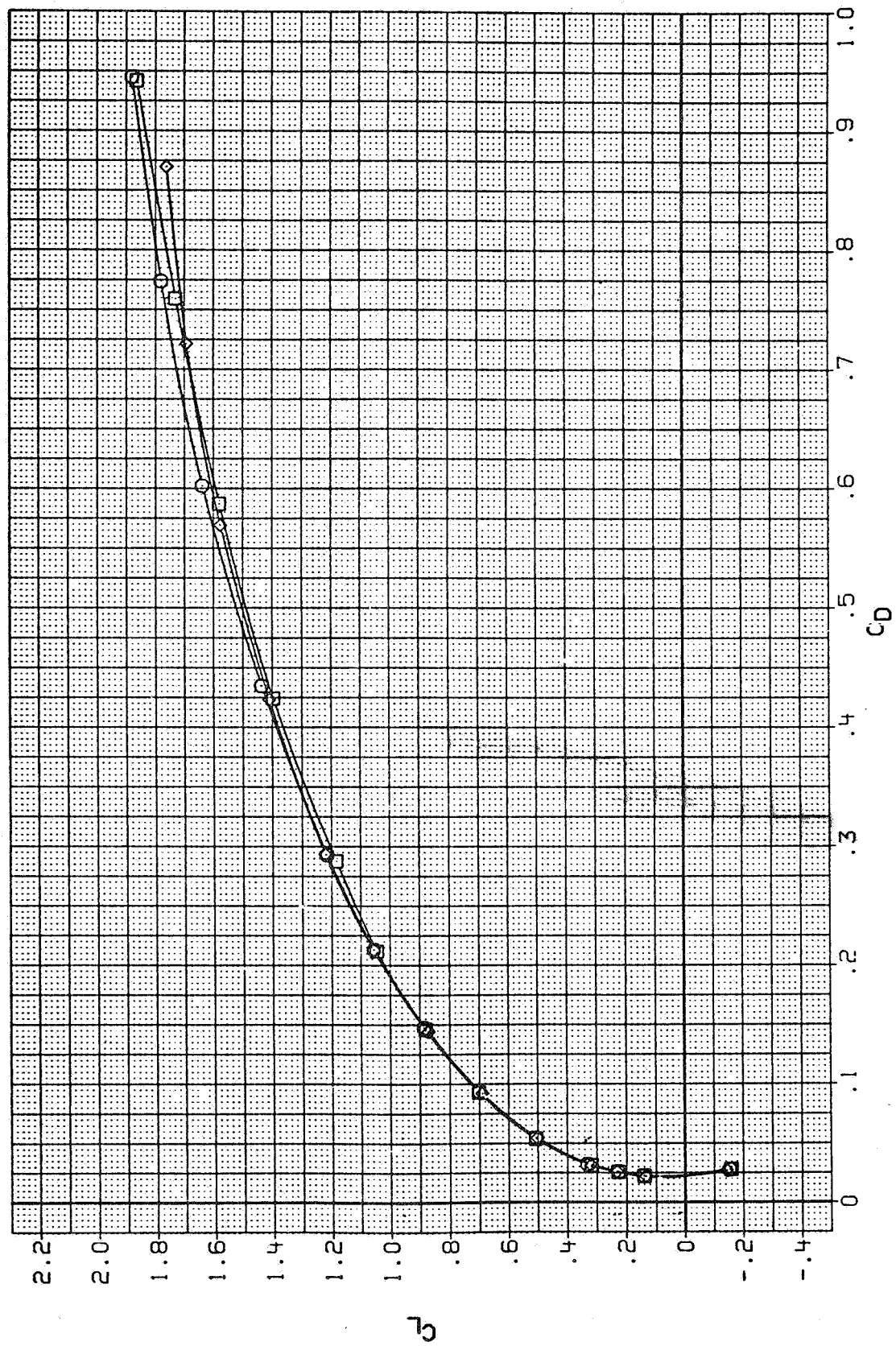


FIG. 114 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .60

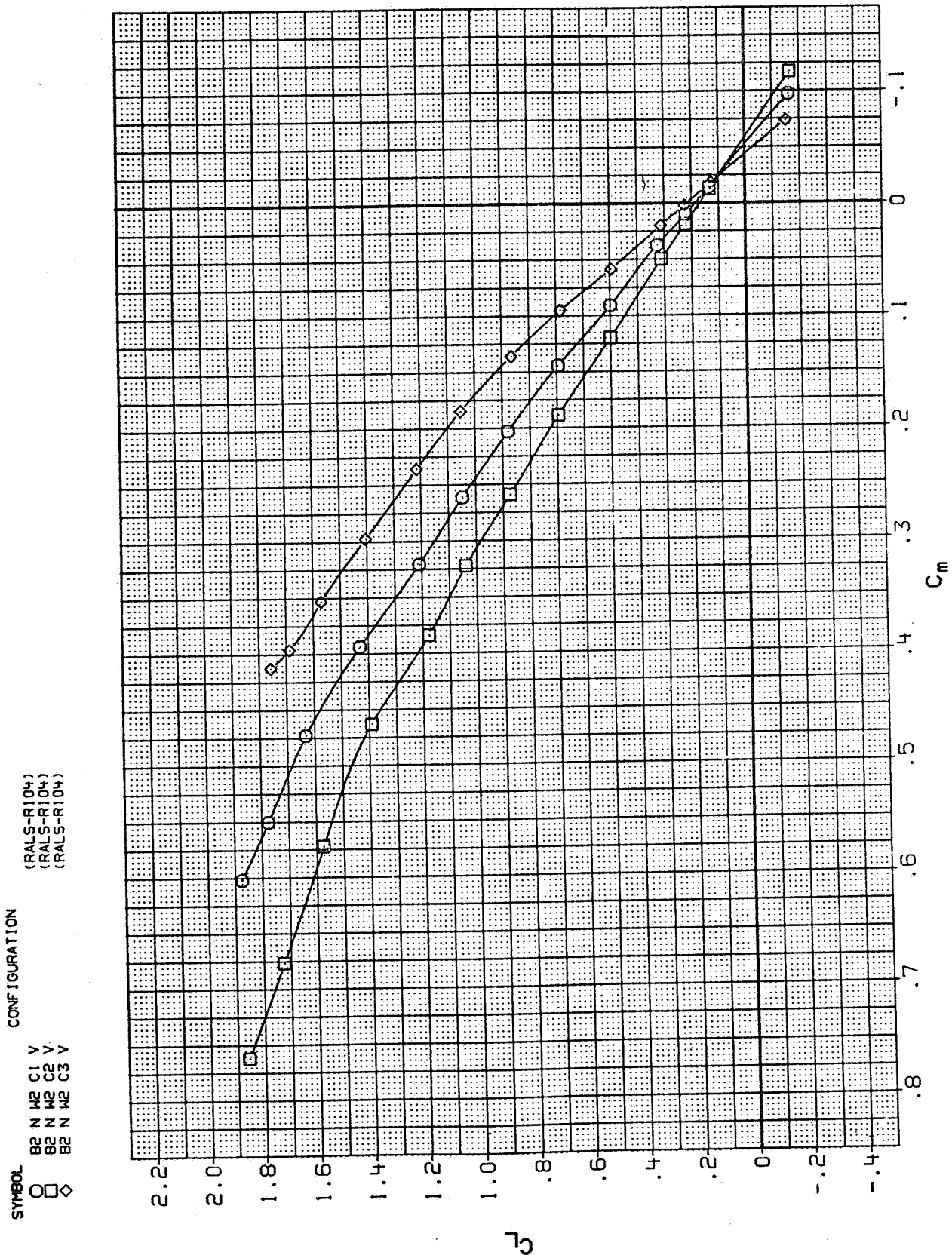


FIG. 114 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .60

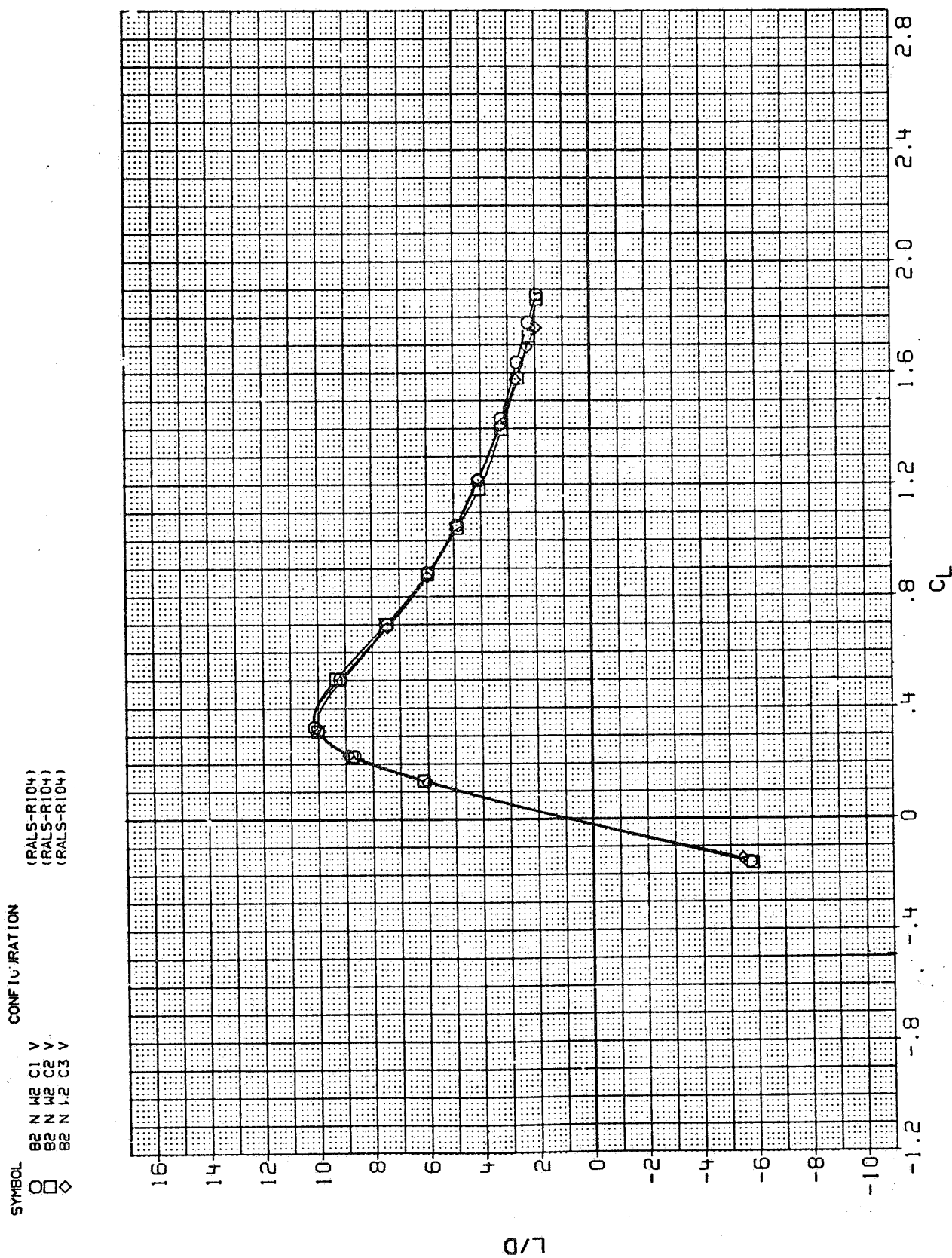


FIG. 114 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .60

SYMBOL CONFIGURATION
 ○ B2 N W2 C1 V (RALS-R104)
 □ B2 N W2 C2 V (RALS-R104)
 ◇ B2 N W2 C3 V (RALS-R104)

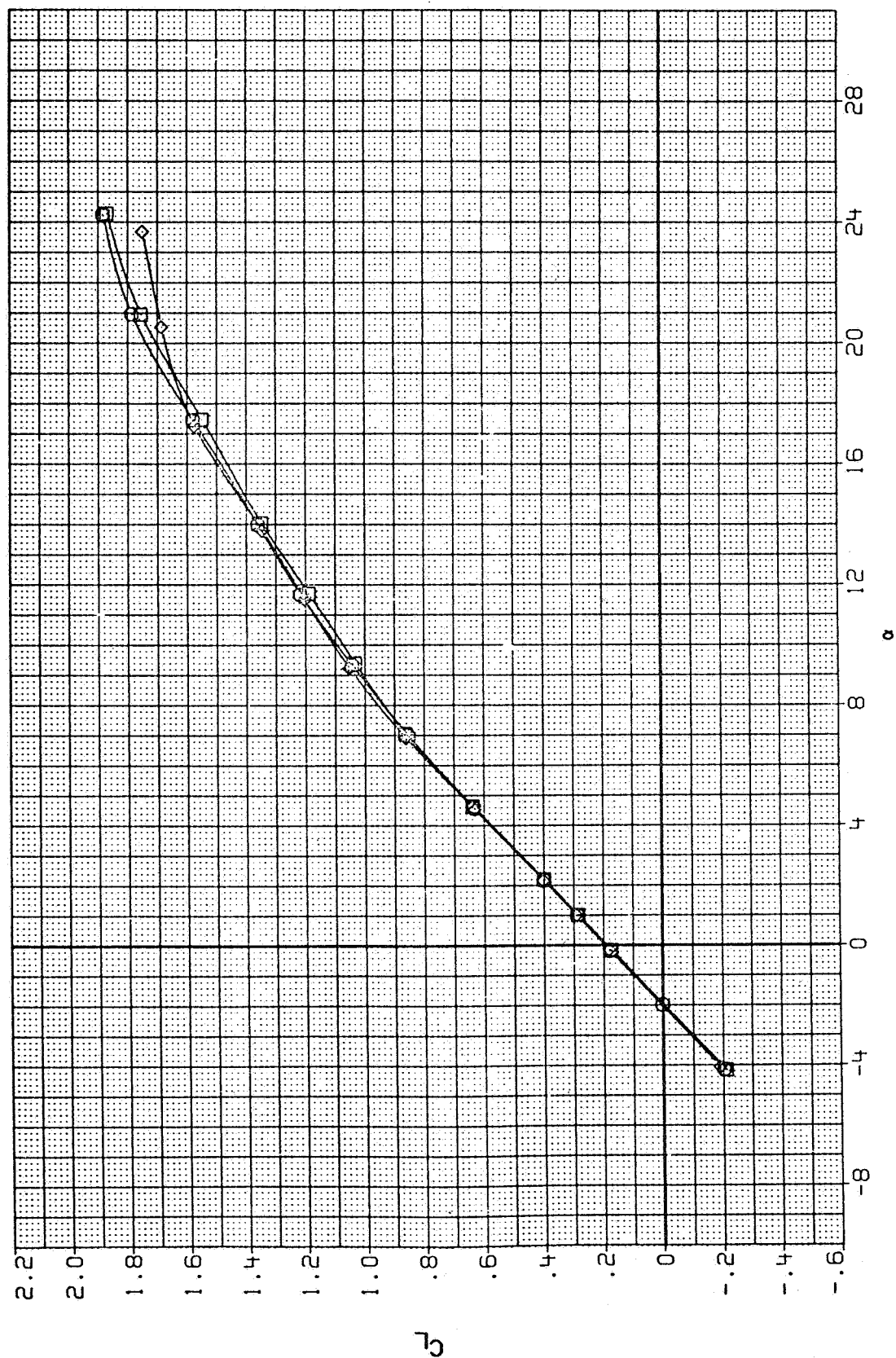


FIG. 115 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL		CONFIGURATION	
□	B2 N W2 C1 V	(RALS-R104)	
□	B2 N W2 C2 V	(RALS-R104)	
◇	B2 N W2 C3 V	(RALS-R104)	

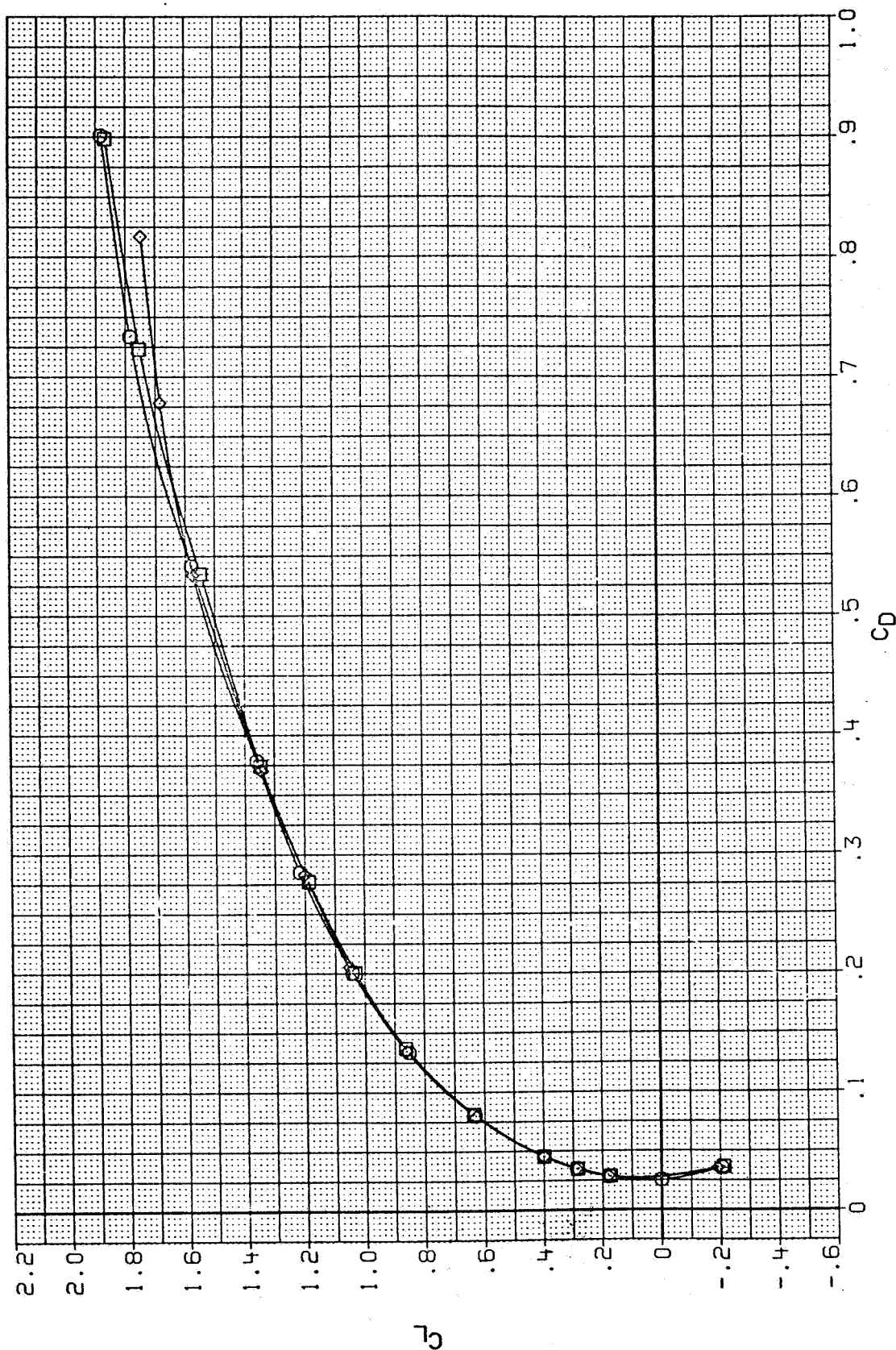


FIG. 115 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL CONFIGURATION

○ B2 N W2 C1 V
 □ B2 N W2 C2 V
 ◇ B2 N W2 C3 V

(RALS-R104)
 (RALS-R104)
 (RALS-R104)

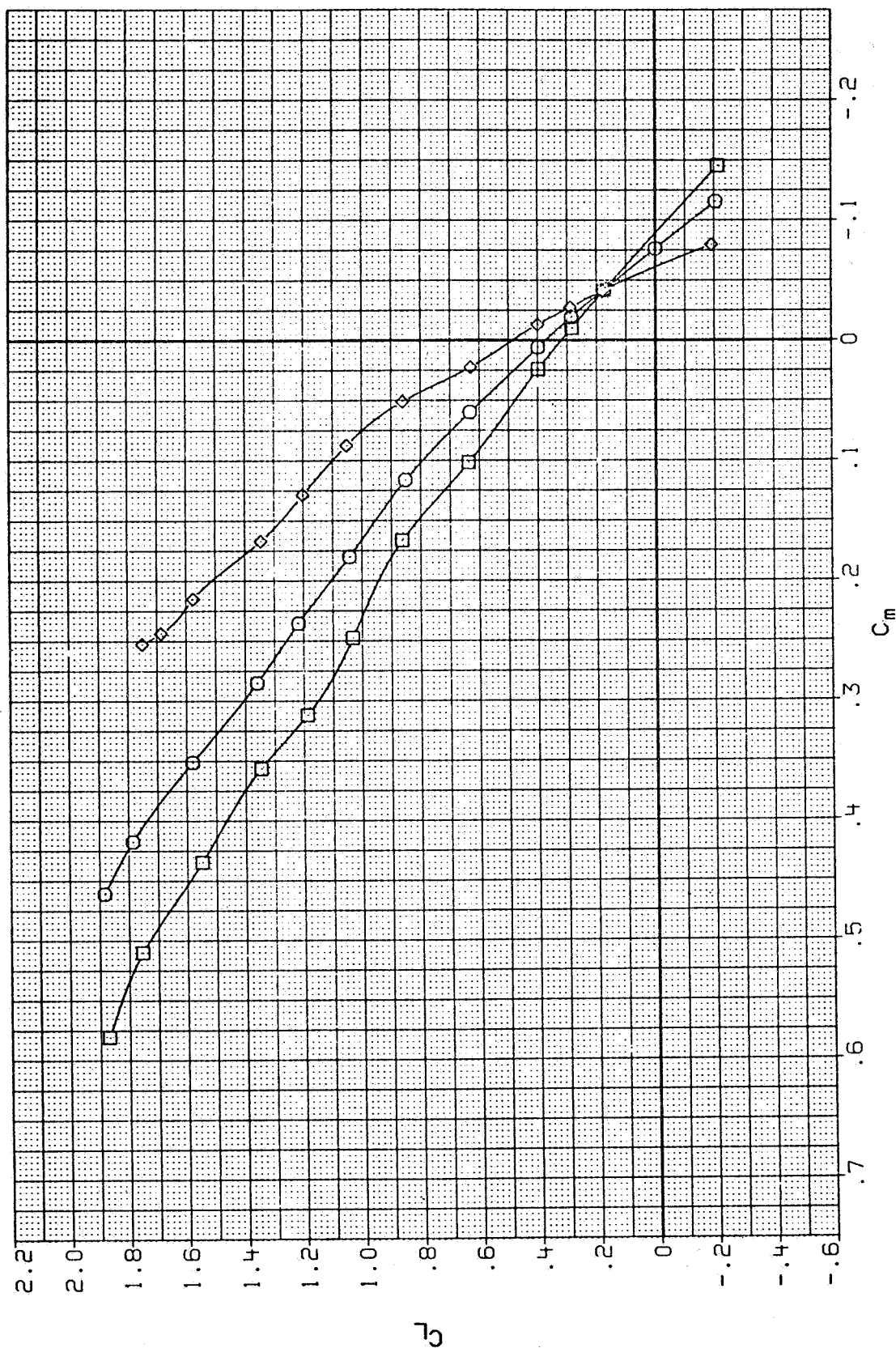


FIG. 115 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 0.90

SYMBOL CONFIGURATION
 ○ B2 N W2 C1 V (RALS-R104)
 □ B2 N W2 C2 V (RALS-R104)
 ◇ B2 N W2 C3 V (RALS-R104)

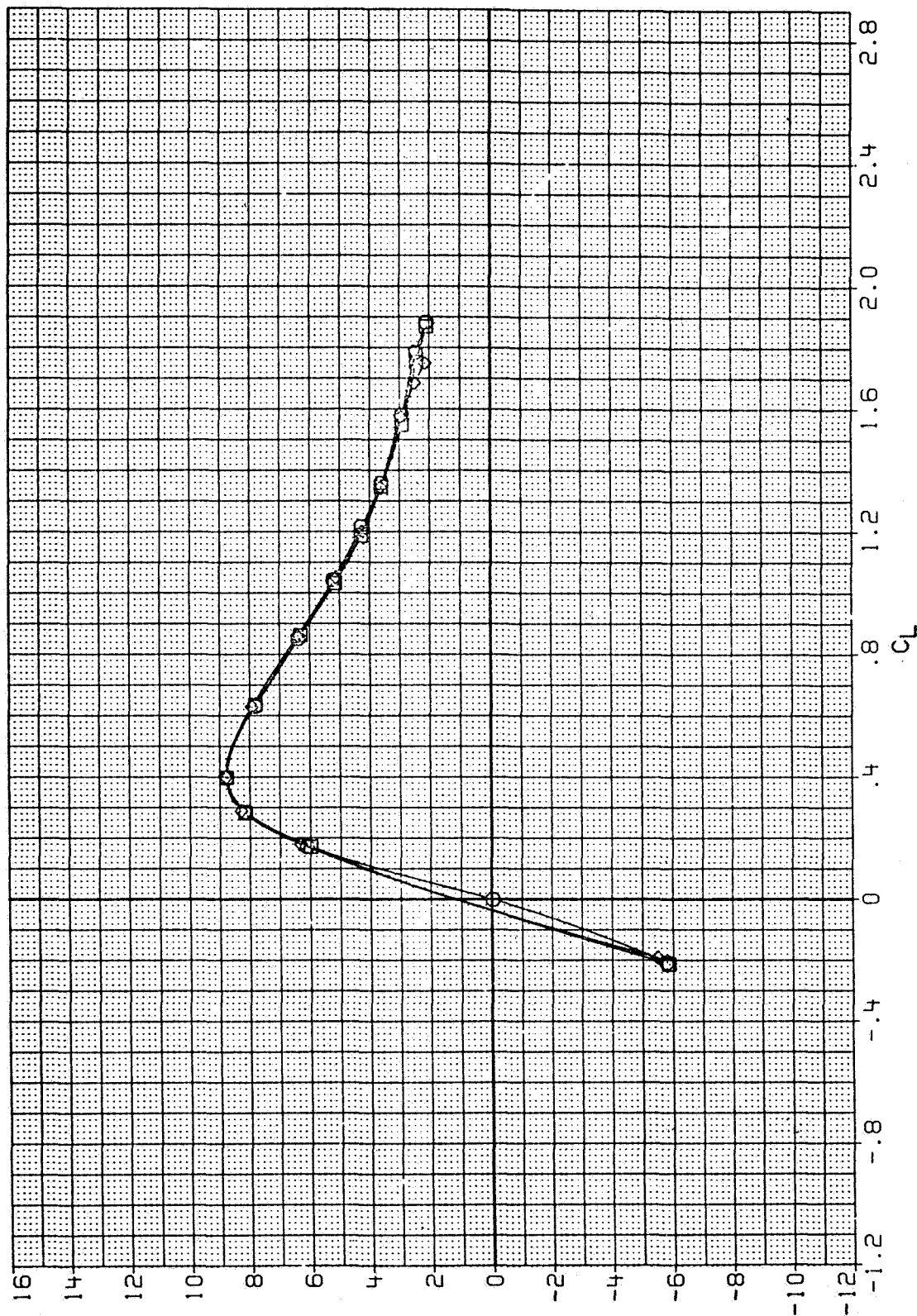


FIG. 115 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = .90

SYMBOL CONFIGURATION
 ○ B2 N W2 C1 V
 ◇ B2 N W2 C2 V
 ◇ B2 N W2 C3 V
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

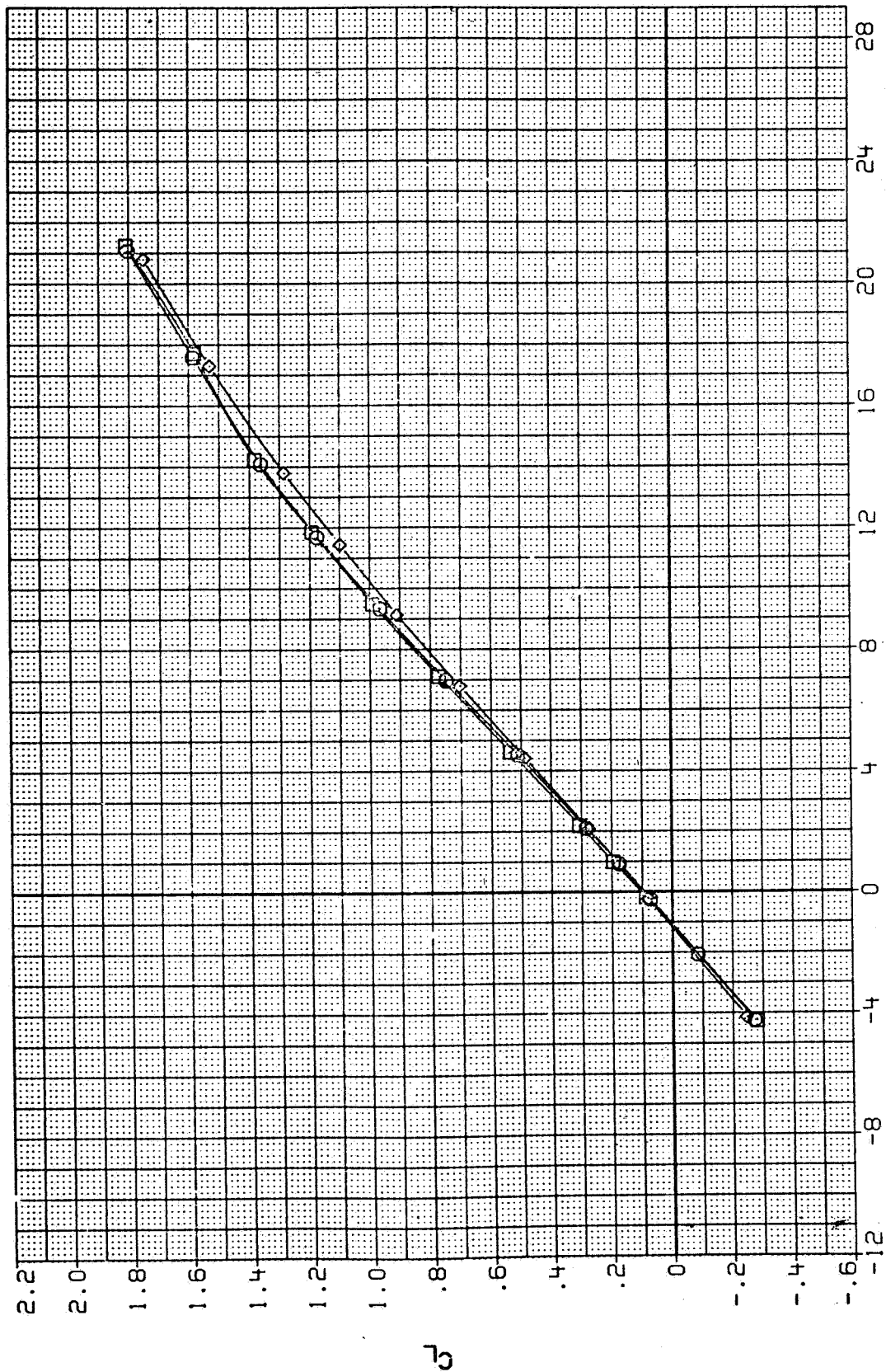


FIG. 116 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL CONFIGURATION
 ○ B2 N M2 C1 V (RALS-R104)
 ◇ B2 N M2 C2 V (RALS-R104)
 ◇ B2 N M2 C3 V (RALS-R104)

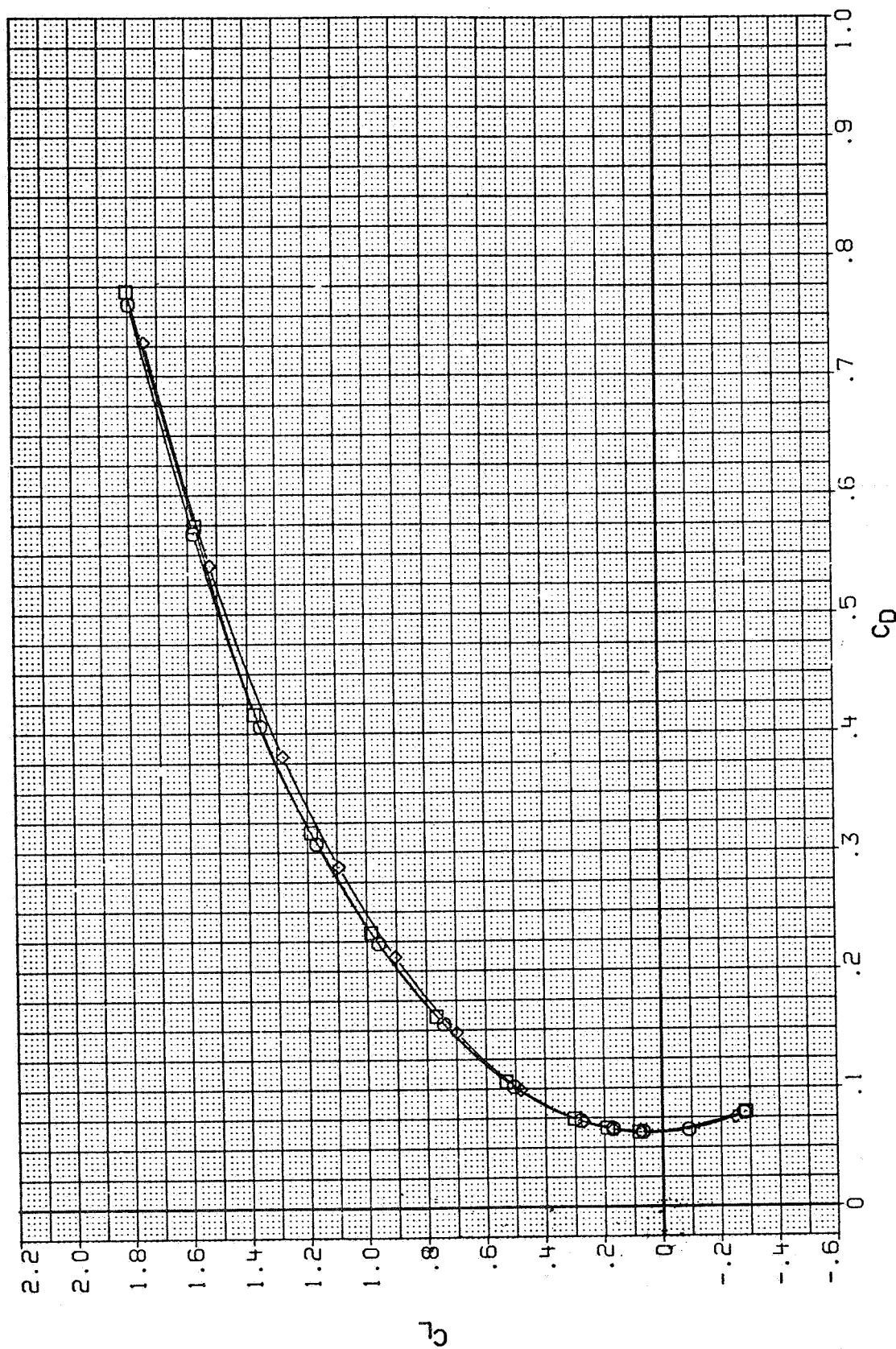


FIG. 116 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL CONFIGURATION

B2 N W2 C1 V (RALS-R104)
 B2 N W2 C2 V (RALS-R104)
 B2 N W2 C3 V (RALS-R104)

○ (RALS-R104)
 □ (RALS-R104)
 ◇ (RALS-R104)

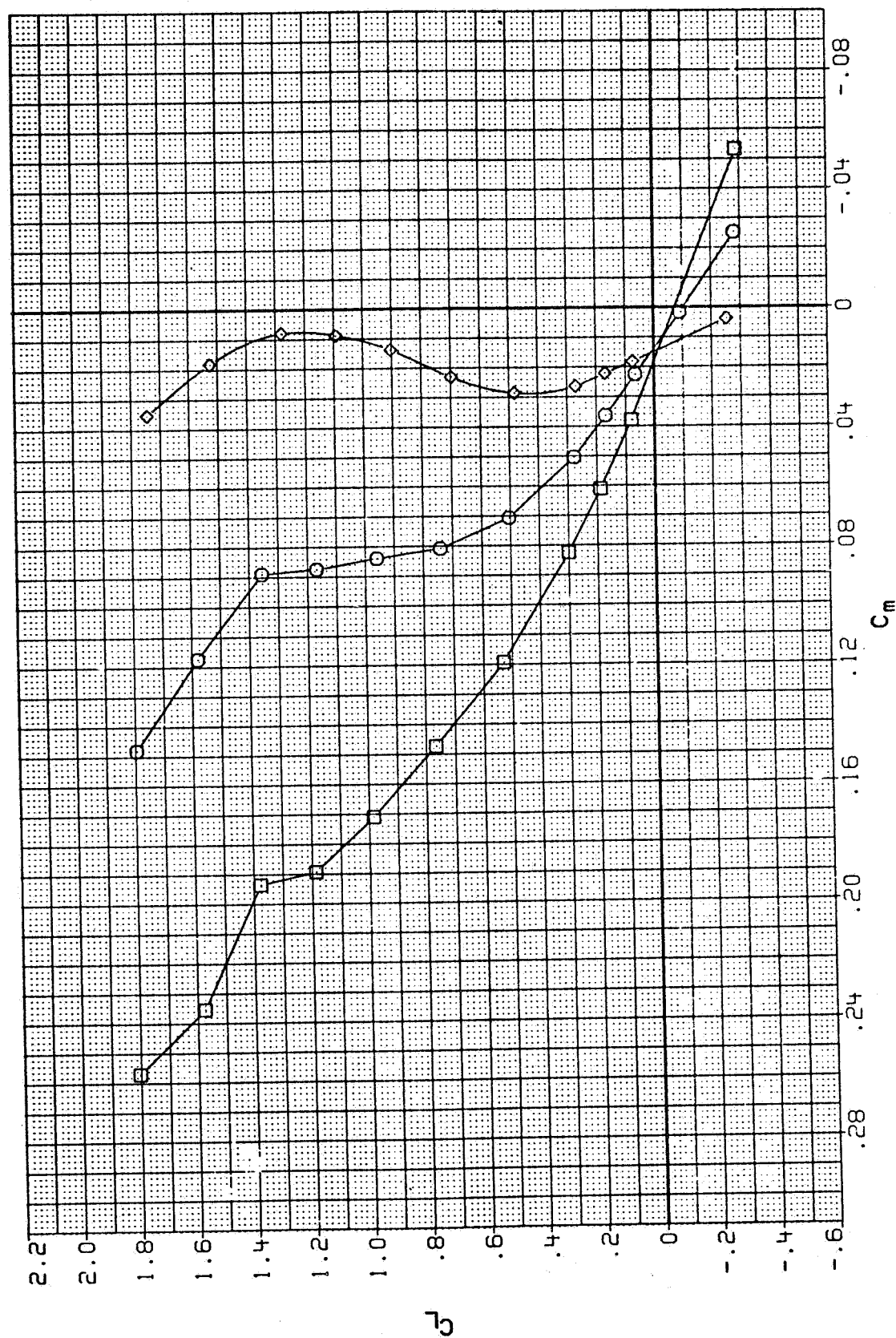


FIG. 116 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

SYMBOL CONFIGURATION
 □ B2 N W2 C1 V
 ◇ B2 N W2 C2 V
 ◇ B2 N W2 C3 V
 (RALS-R104)
 (RALS-R104)
 (RALS-R104)

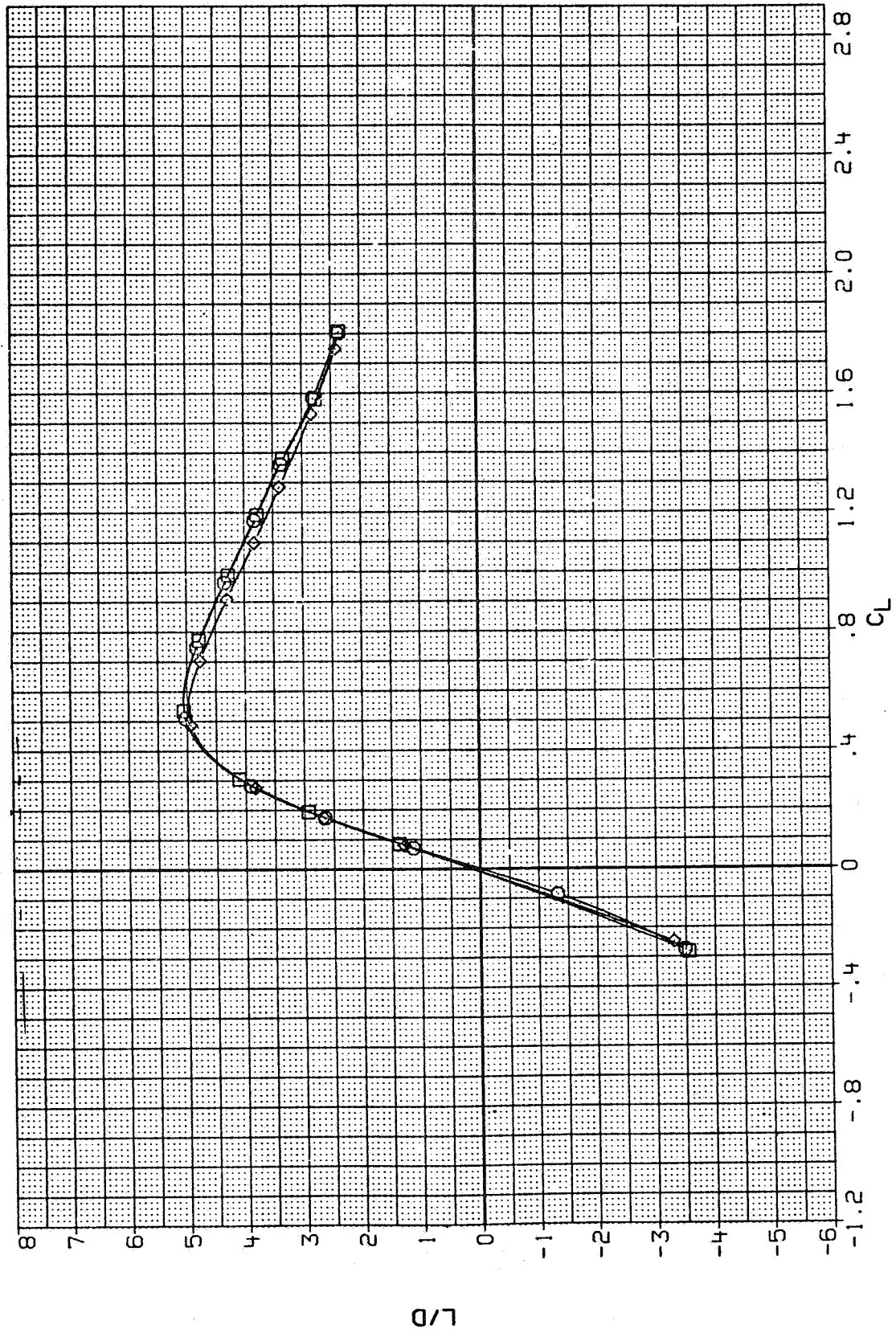


FIG. 116 CANARD LOCATION EFFECTS, LONGITUDINAL CHARACTERISTICS

MACH = 1.20

0/1

SYMBOL	CONFIGURATION	ALPHA
○	B2 N W2 C1 V	.000
□	B2 N W2 C2 V	.000
◇	B2 N W2 C3 V	.000
	(RALS-R104)	
	(RALS-R104)	
	(RALS-R104)	

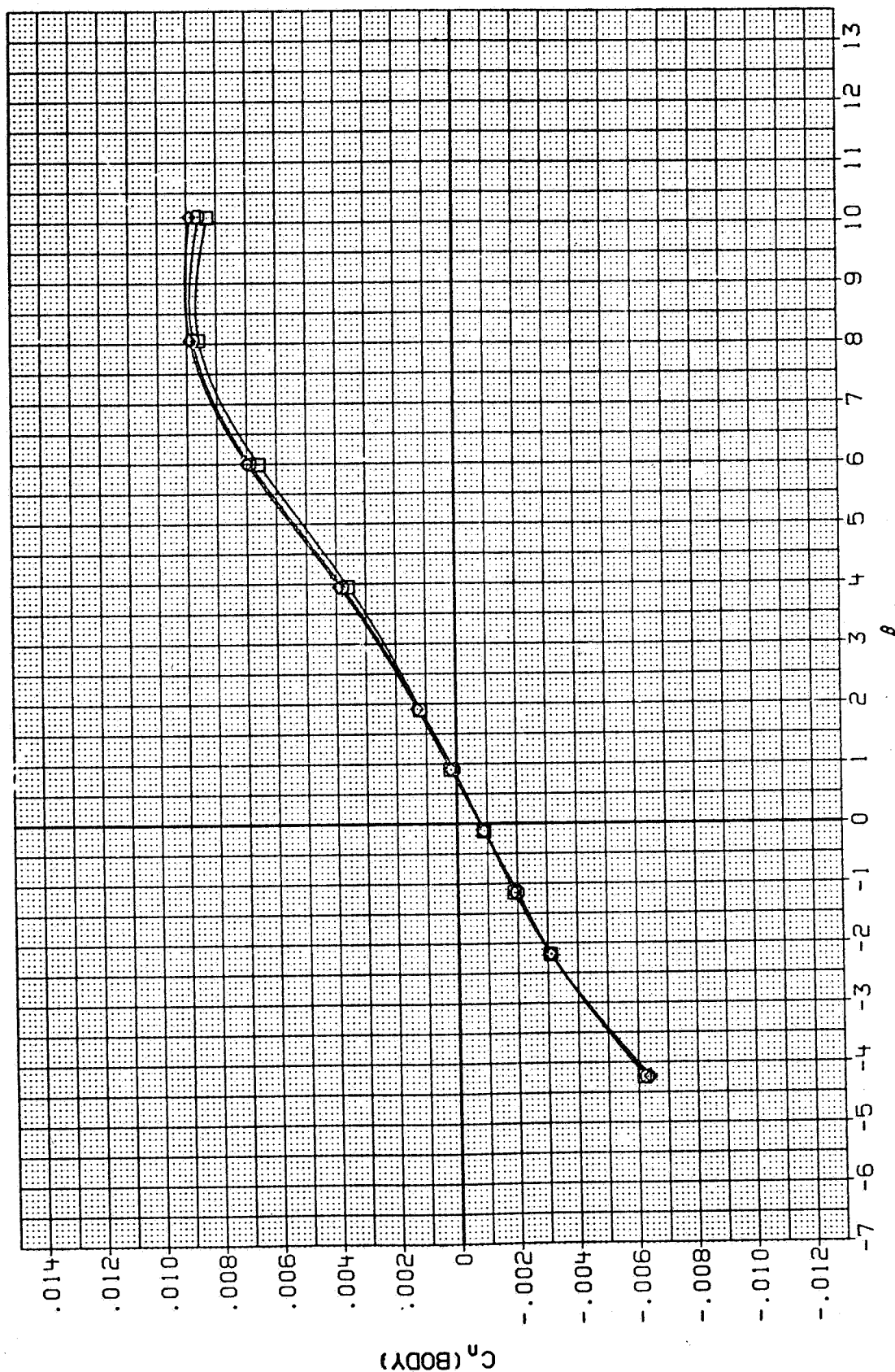


FIG. 117 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = .90

SYMBOL CONFIGURATION ALPHA
 ○ (RALS-R104) .000
 □ (RALS-R104) .000
 ◇ (RALS-R104) .000

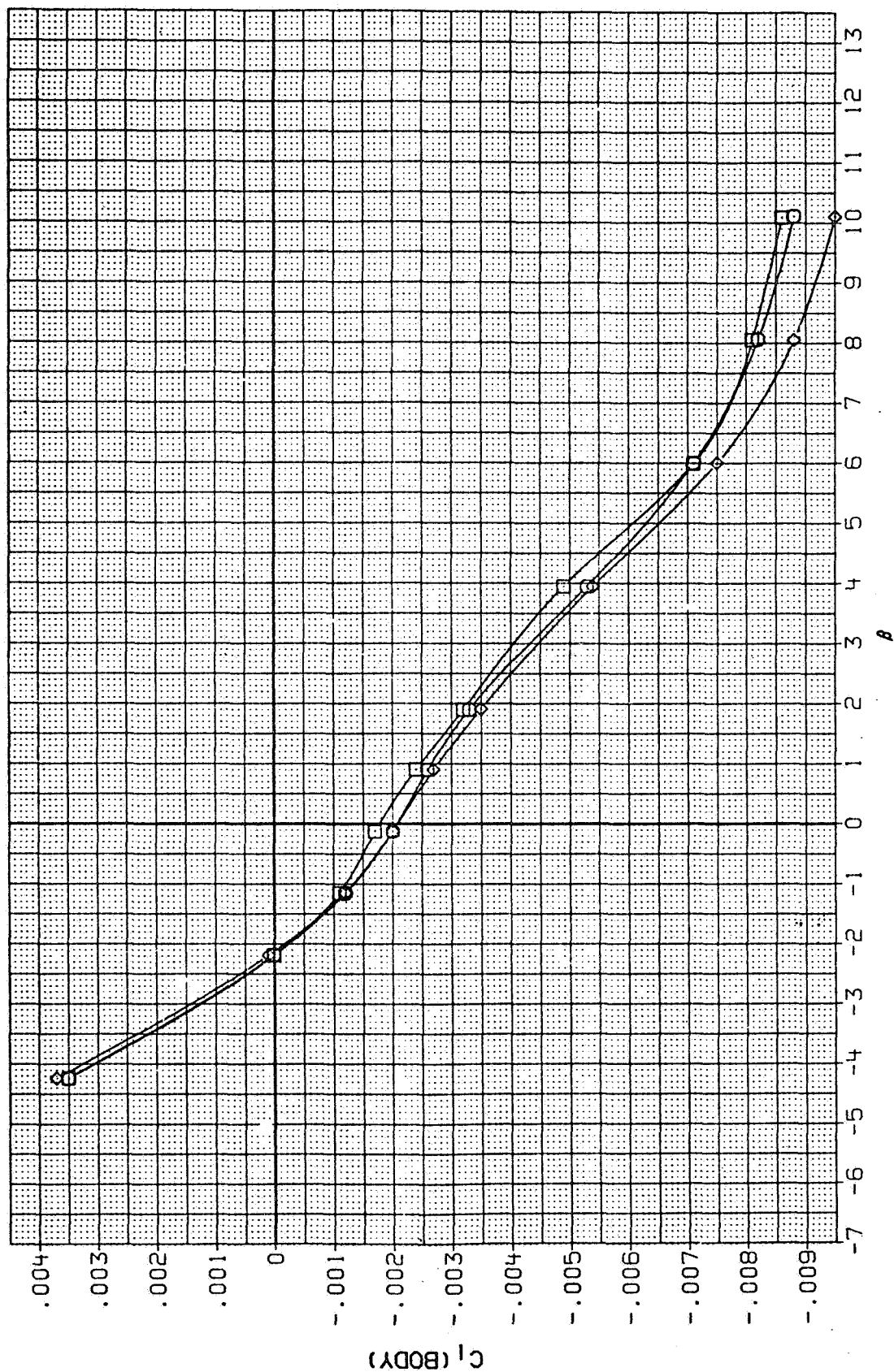


FIG. 117 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = .90

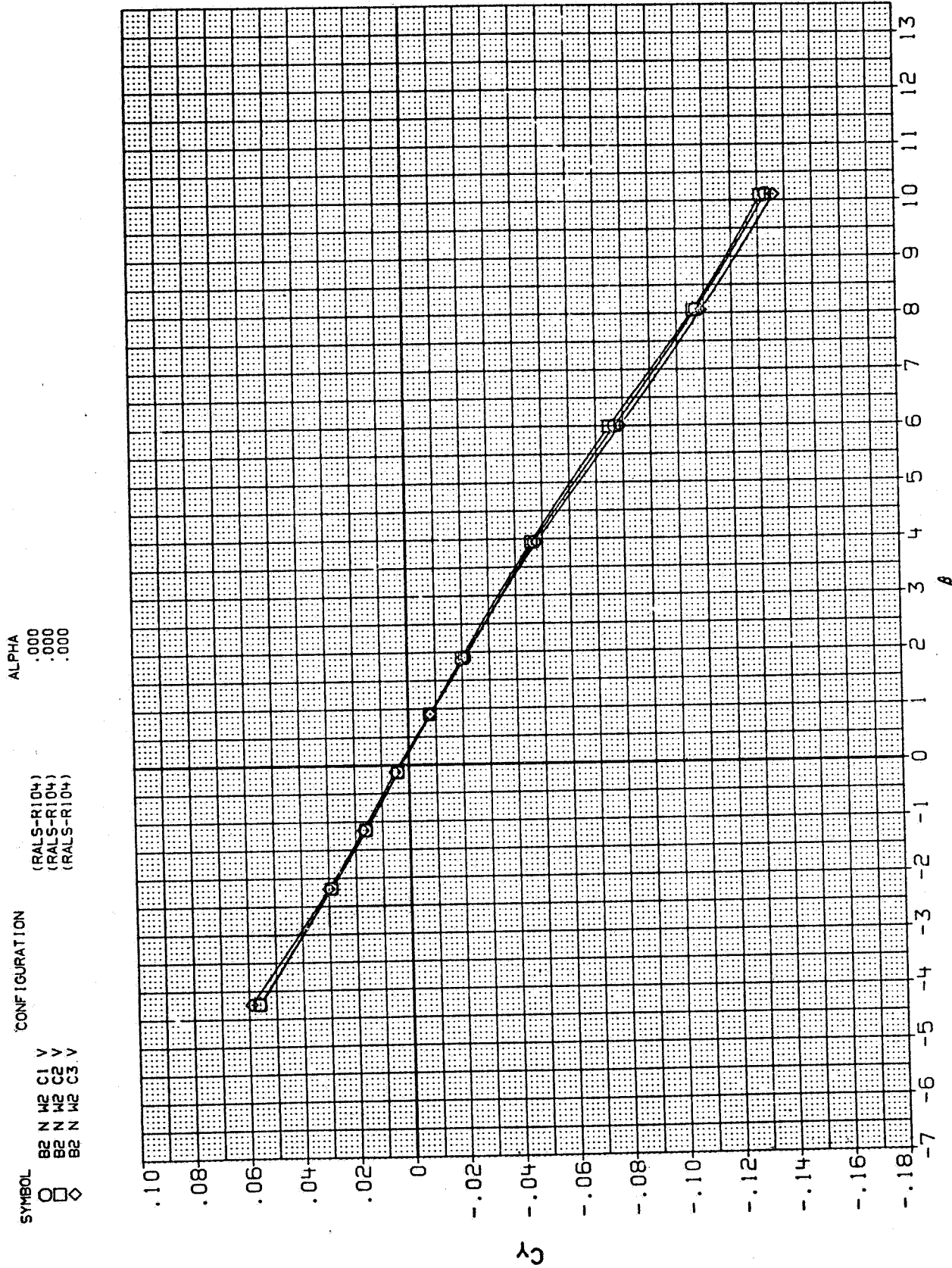


FIG. 117 CANARD LOCATION EFFECTS; LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON

MACH = .90

SYMBOL CONFIGURATION ALPHA
 □ B2 N W2 C1 V 17.000
 □ B2 N W2 C2 V 12.000
 ◇ B2 N W2 C3 V 17.000

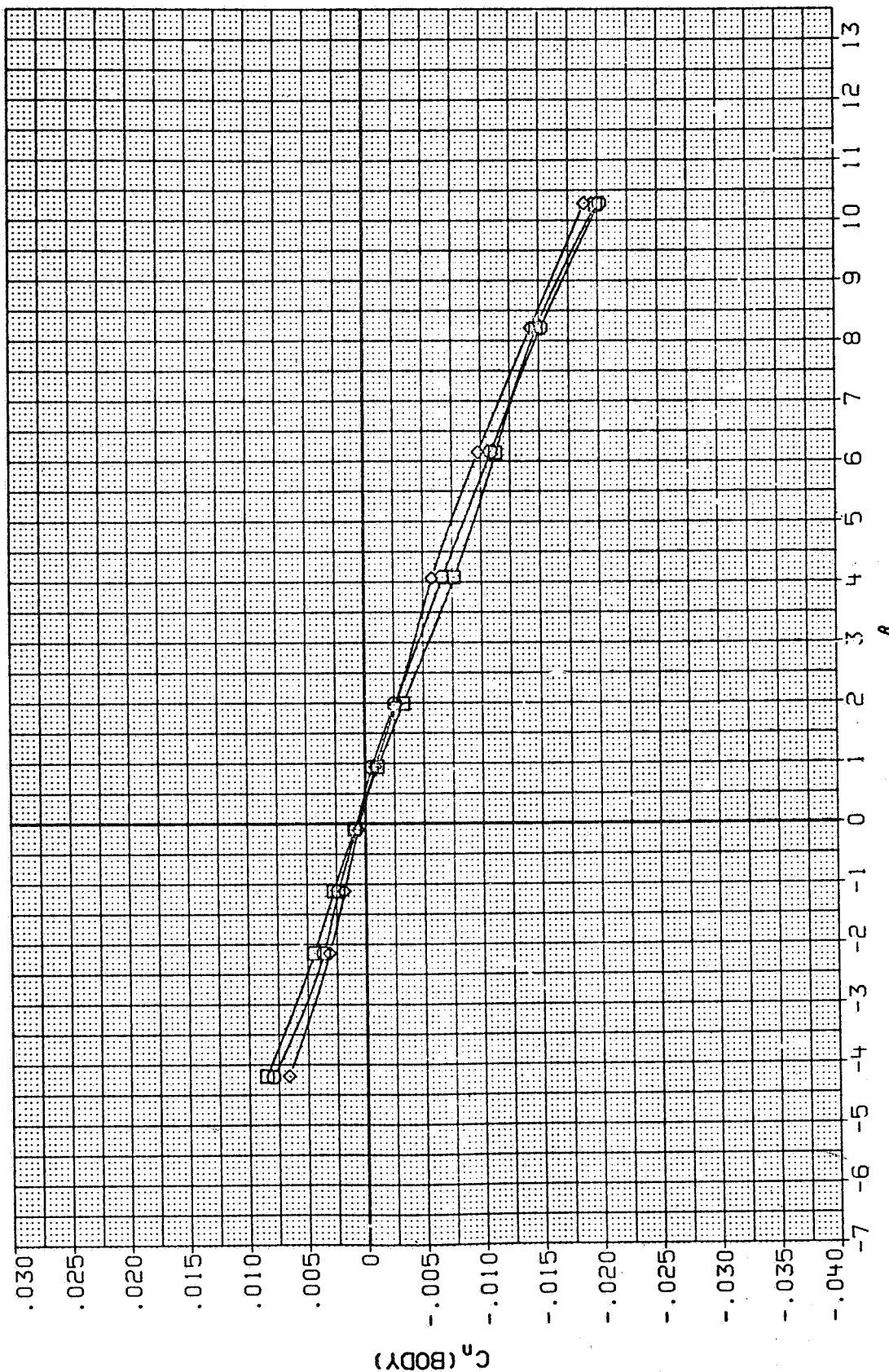


FIG. 117 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL ON
 MACH = .90

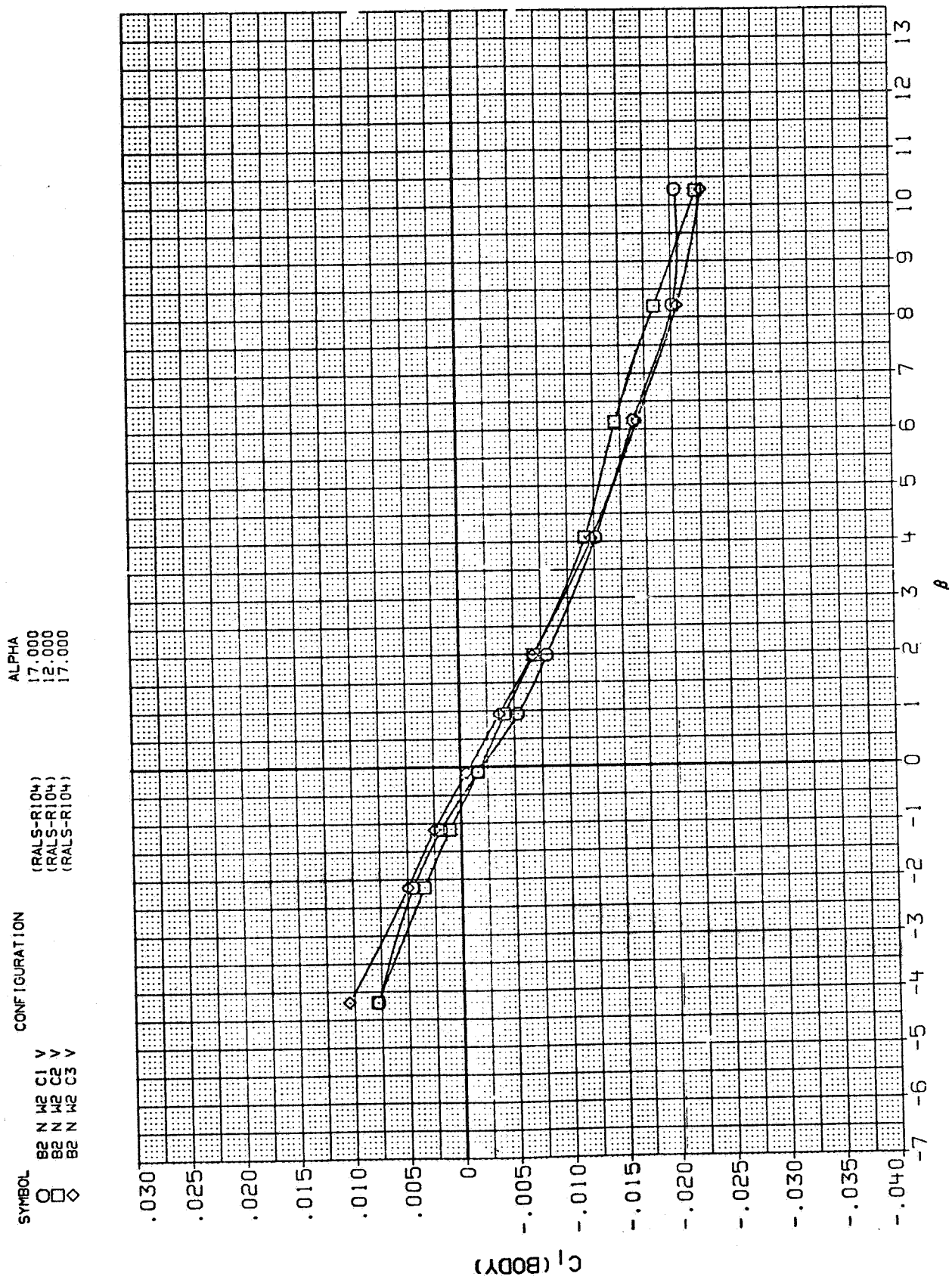


FIG. 117 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 15 DEGREES, VERTICAL TAIL ON

MACH = 0.90

SYMBOL

B2 N W2 C1 V
B2 N W2 C2 V
B2 N W2 C3 V

CONFIGURATION

(RALS-R104)
(RALS-R104)
(RALS-R104)

ALPHA
17.000
12.000
17.000

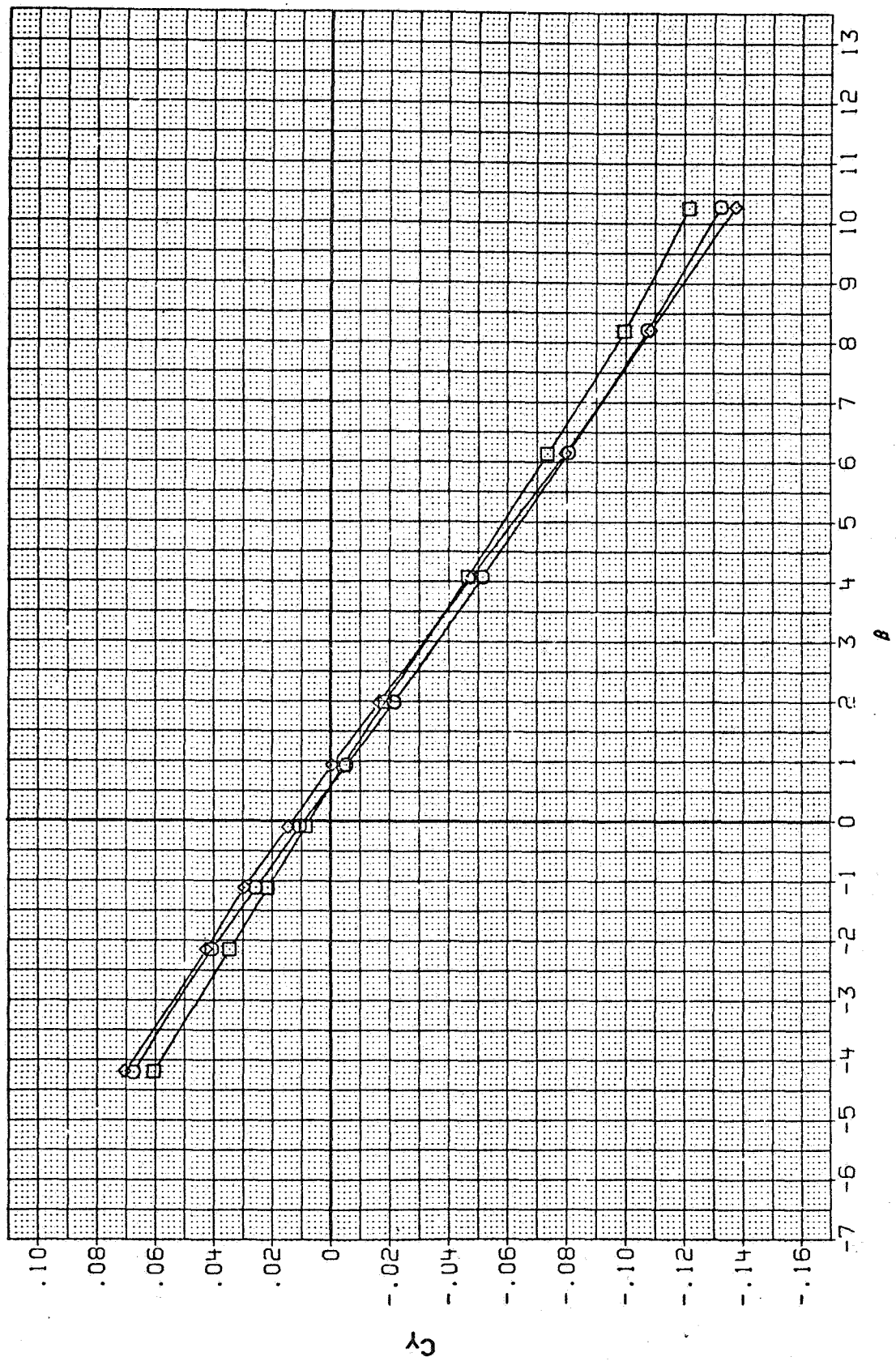


FIG. 117 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 15 DEGREES, VERTICAL TAIL ON

MACH = .90

SYMBOL CONFIGURATION ALPHA
 B2 N W2 C1 (RALS-R104) .000
 B2 N W2 C2 (RALS-R104) .000
 B2 N W2 C3 (RALS-R104) .000

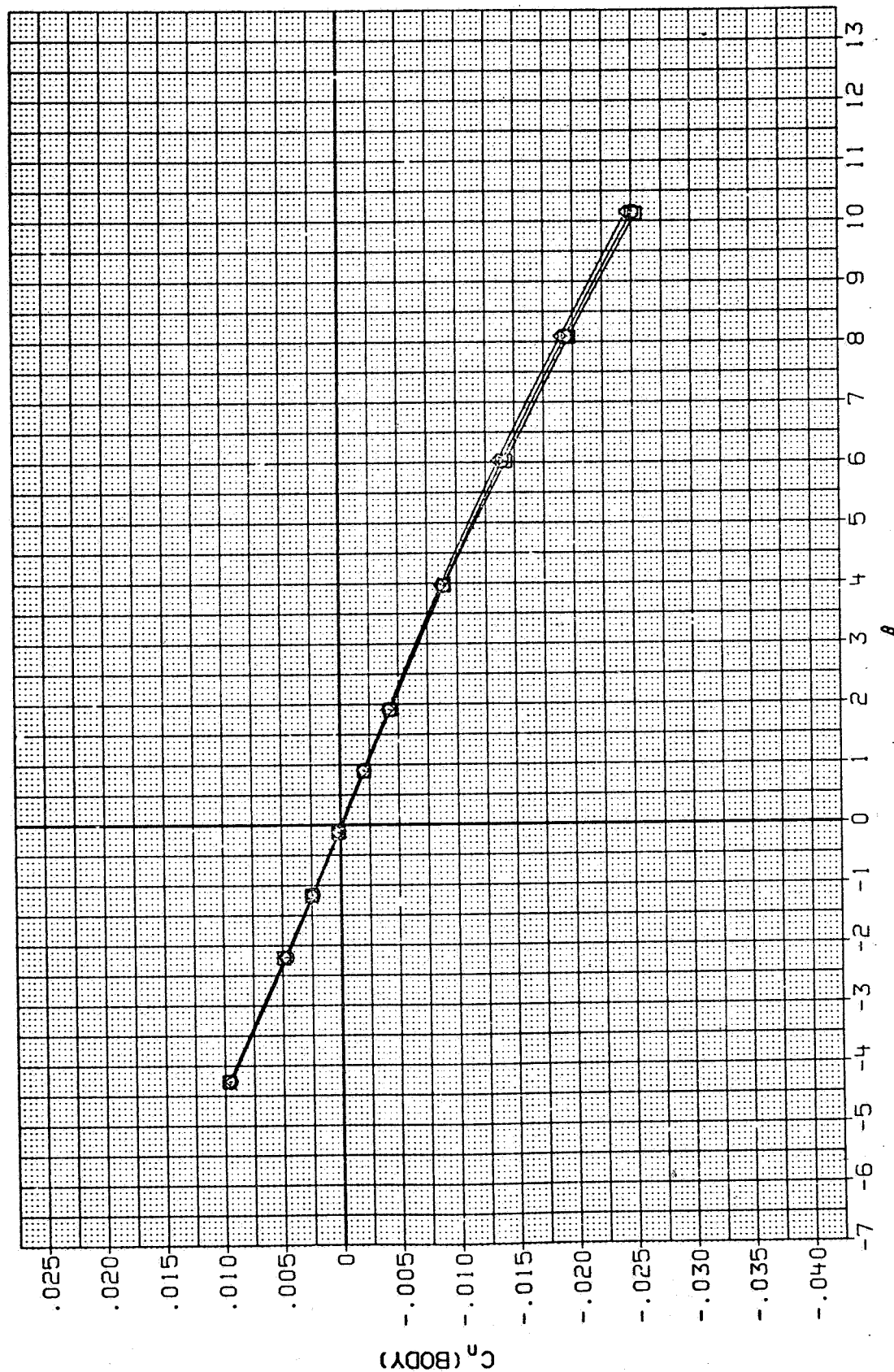


FIG. 118 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF

MACH = .90

SYMBOL CONFIGURATION ALPHA
 ○ (RALS-R104) .000
 □ (RALS-R104) .000
 ◇ (RALS-R104) .000

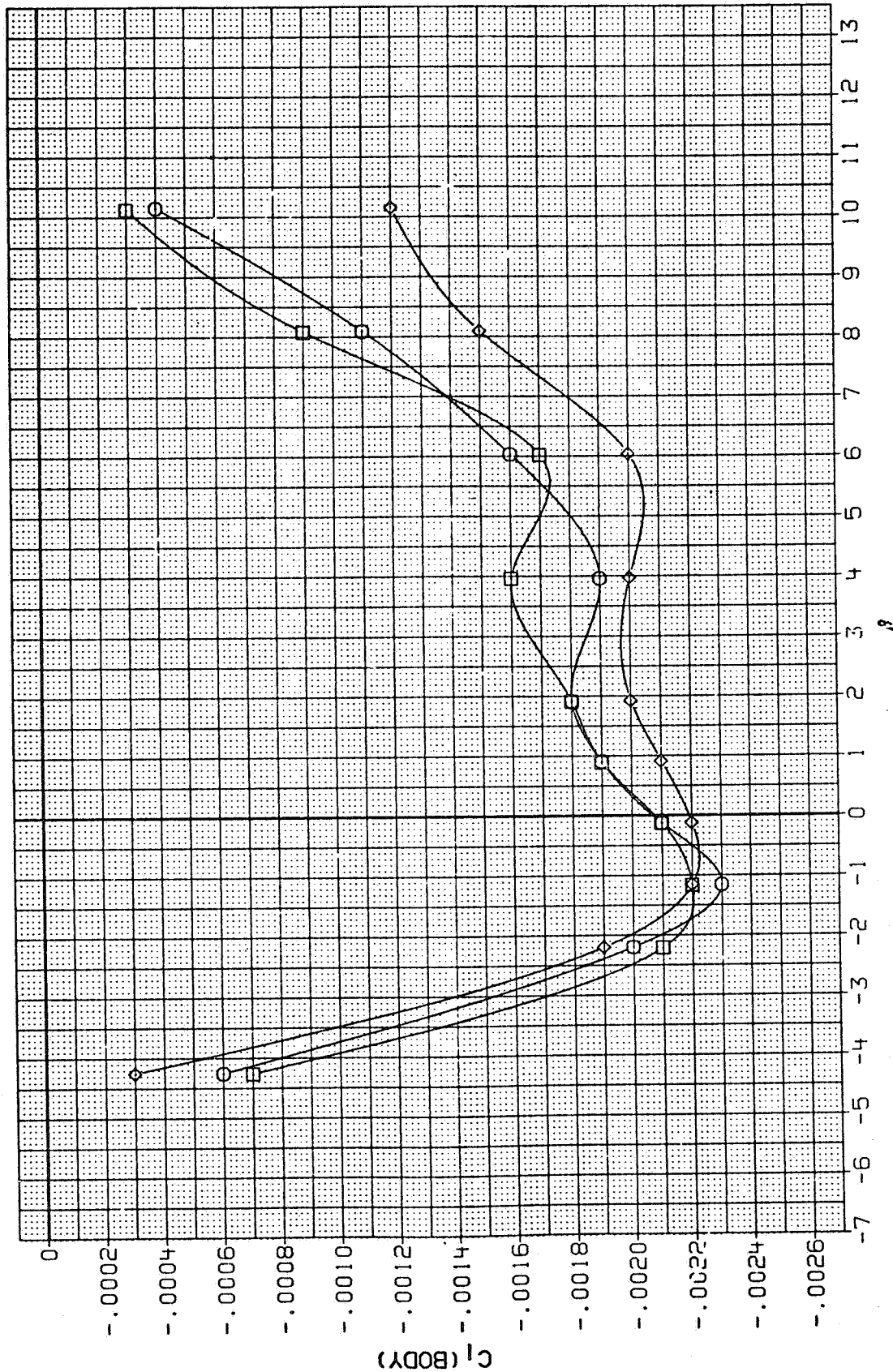


FIG. 118 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF
 MACH = .90

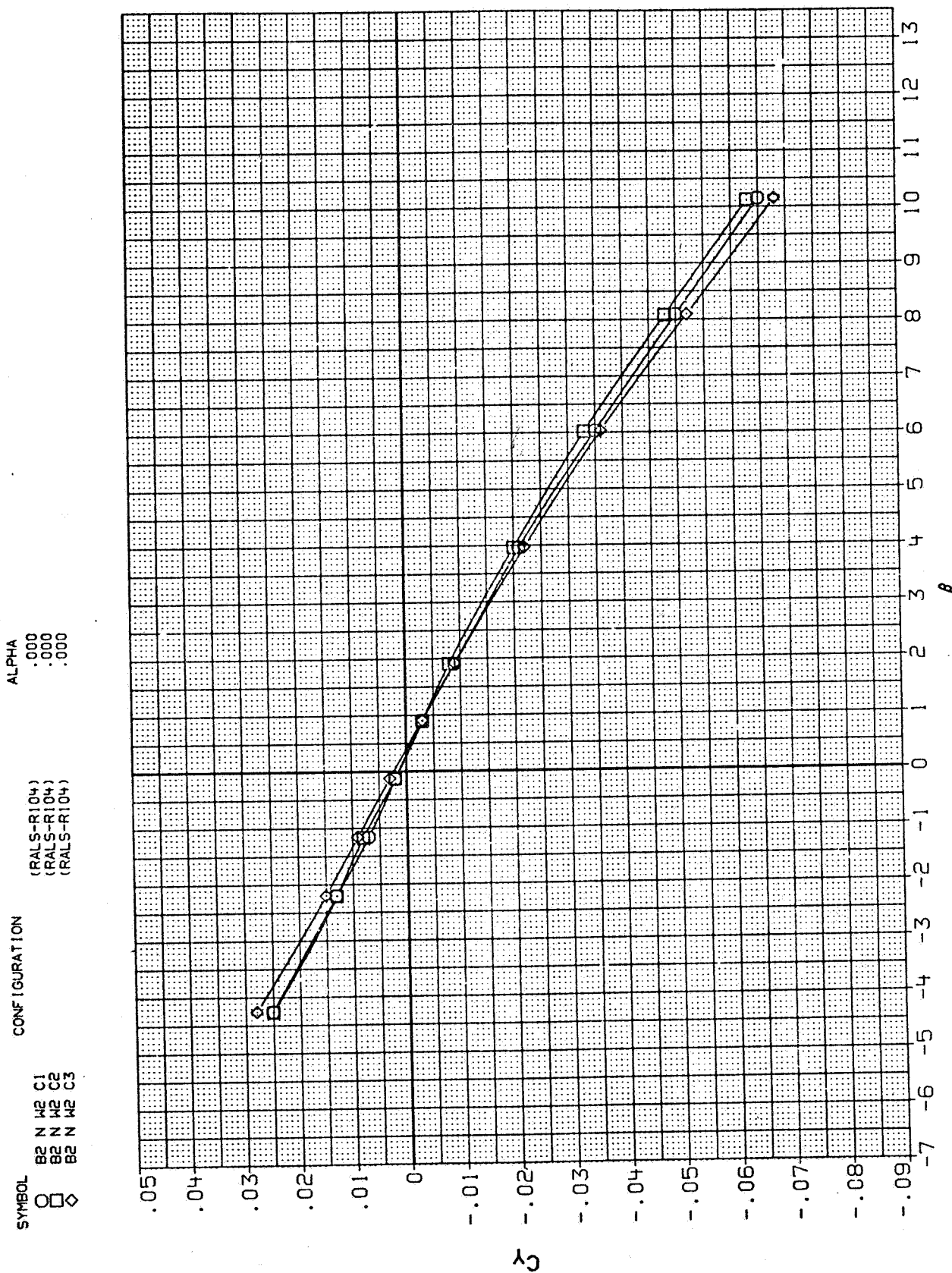


FIG. 118 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF

MACH = .90

SYMBOL CONFIGURATION ALPHA

$\square$ (RALS-R104) 17.500
 $\diamond$ (RALS-R104) 12.000
 $\diamond$ (RALS-R104) 17.000

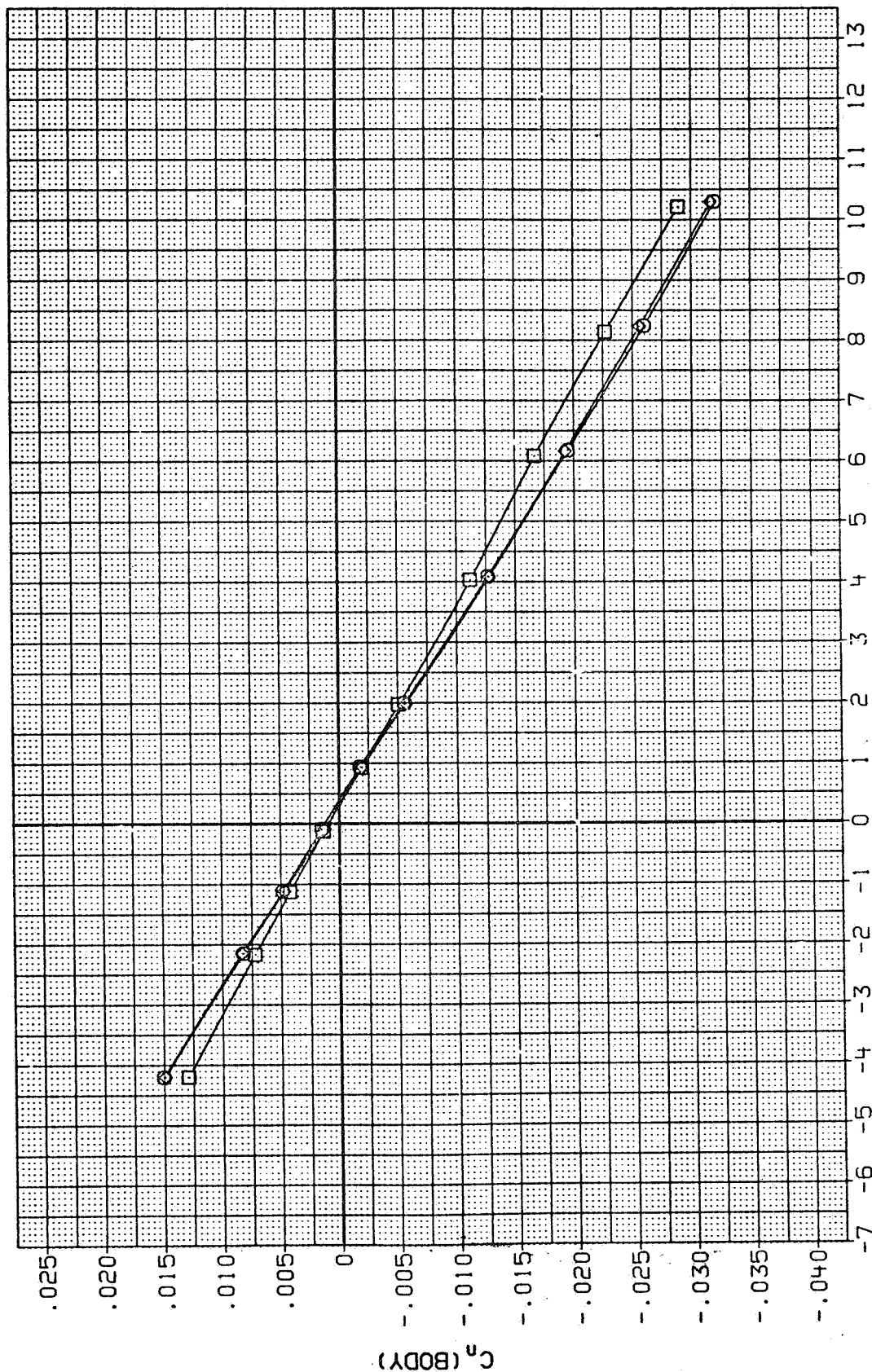


FIG. 118 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL OFF

MACH = .90

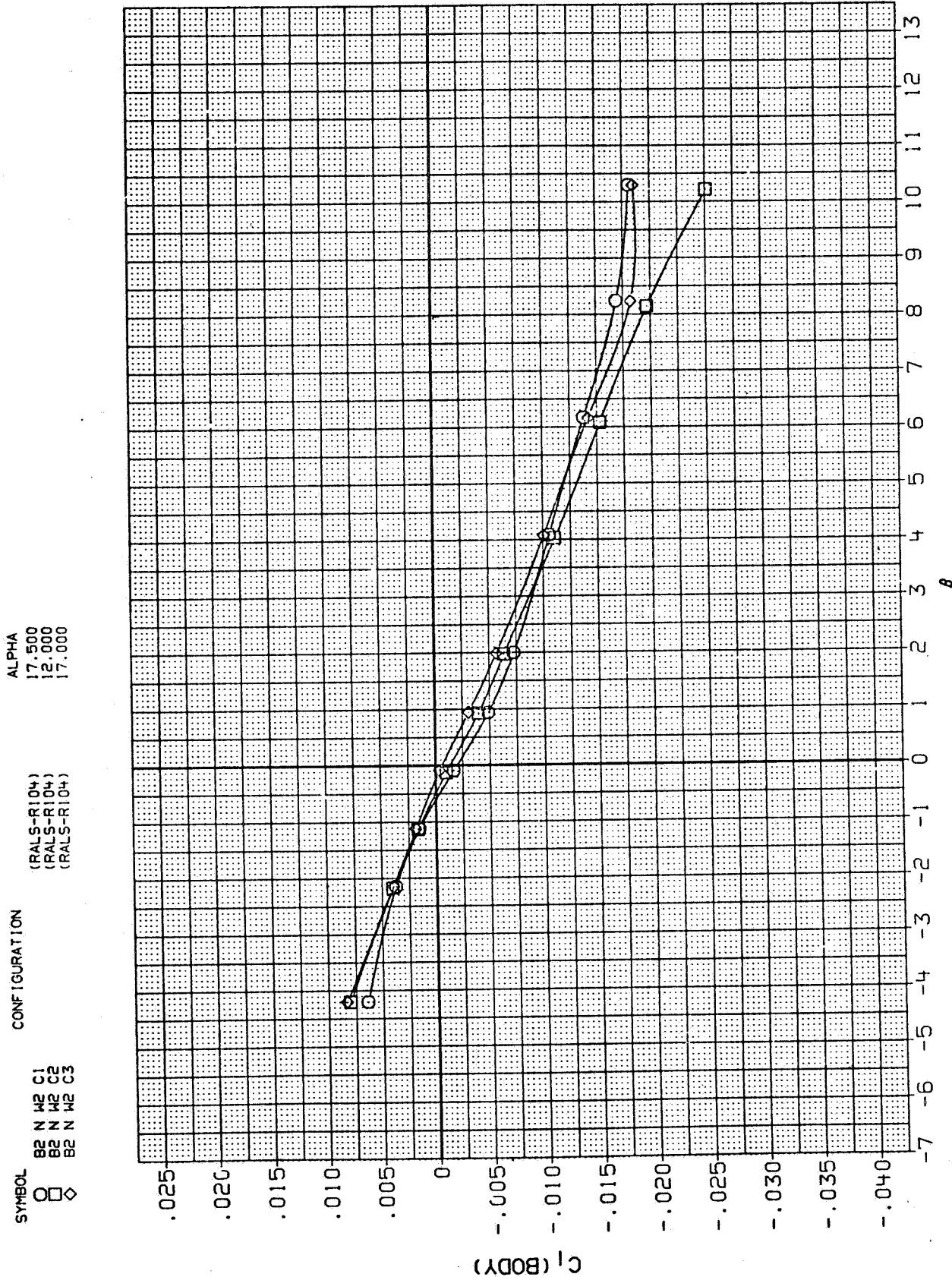


FIG. 118 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 15 DEGREES, VERTICAL TAIL OFF

MACH = .90

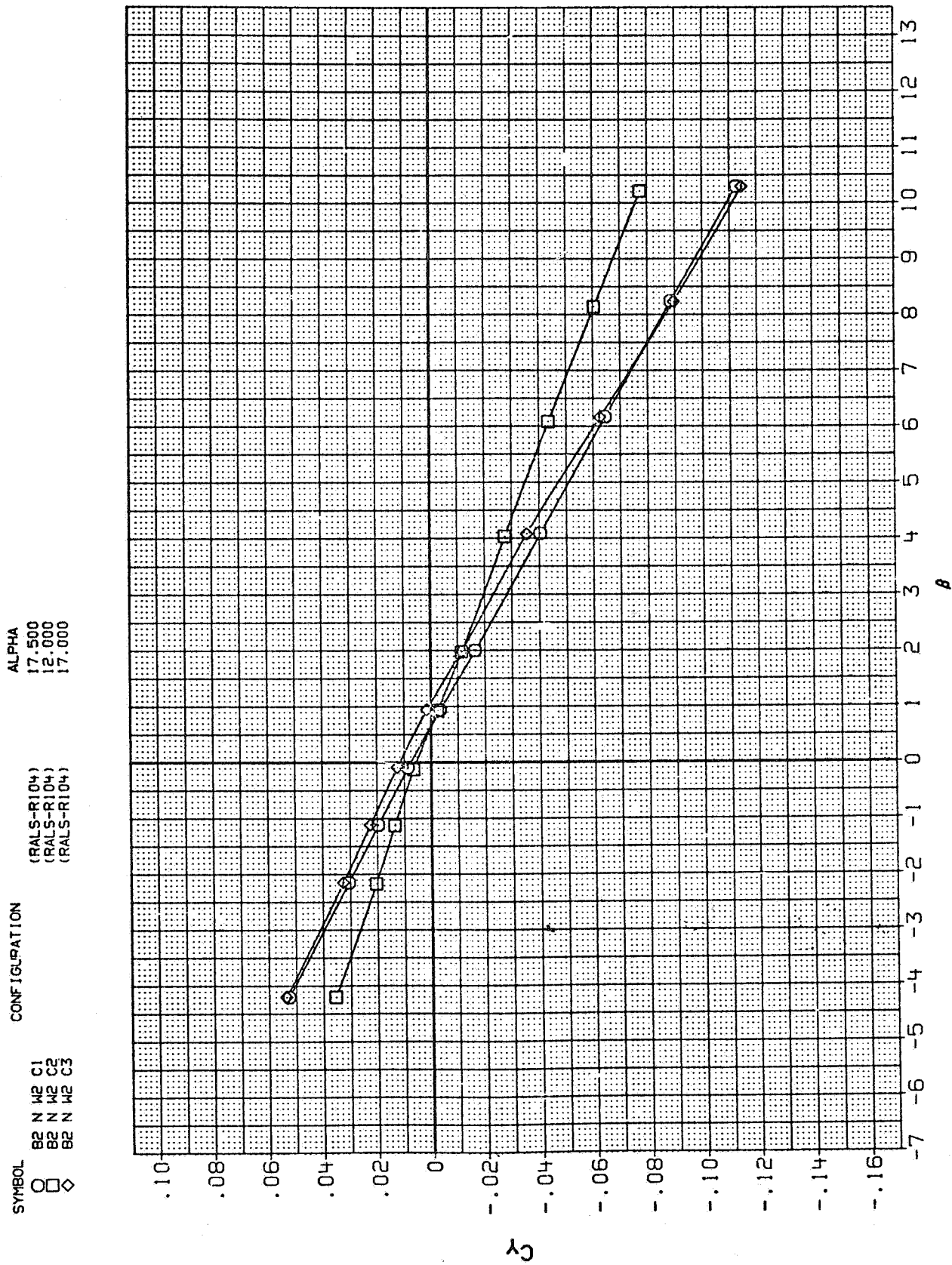


FIG. 118 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 15 DEGREES, VERTICAL TAIL OFF

MACH = .90

SYMBOL CONFIGURATION ALPHA
 □ B2 N W2 C1 V .000
 ◇ B2 N W2 C2 V .000
 B2 N W2 C3 V .000

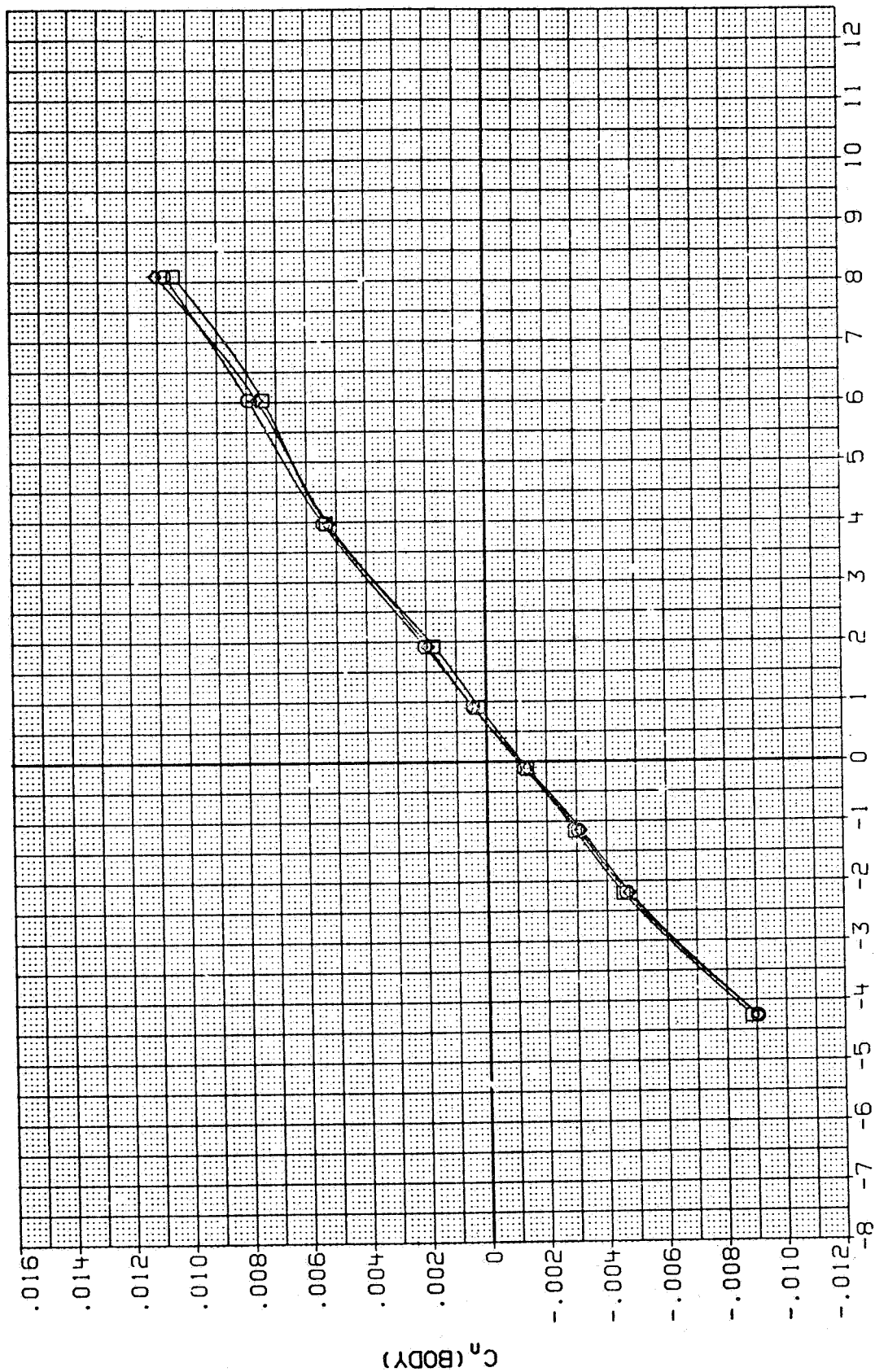


FIG. 119 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

SYMBOL CONFIGURATION ALPHA

$\square$ B2 N W2 C1 V .000
 $\diamond$ B2 N W2 C2 V .000
 $\square$ B2 N W2 C3 V .000

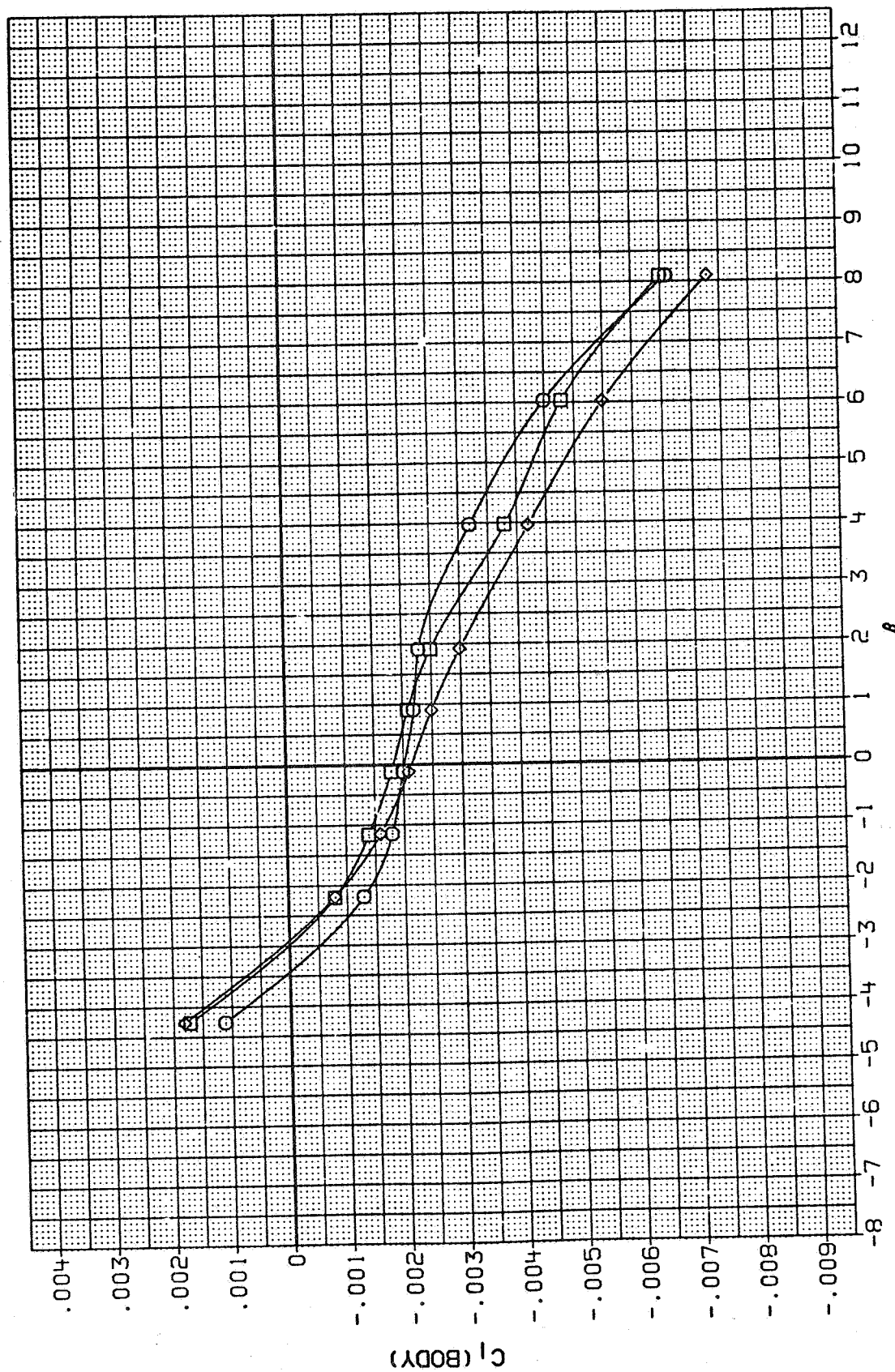


FIG. 119 CANARD LOCATION EFFECTS; LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON

MACH = 1.20

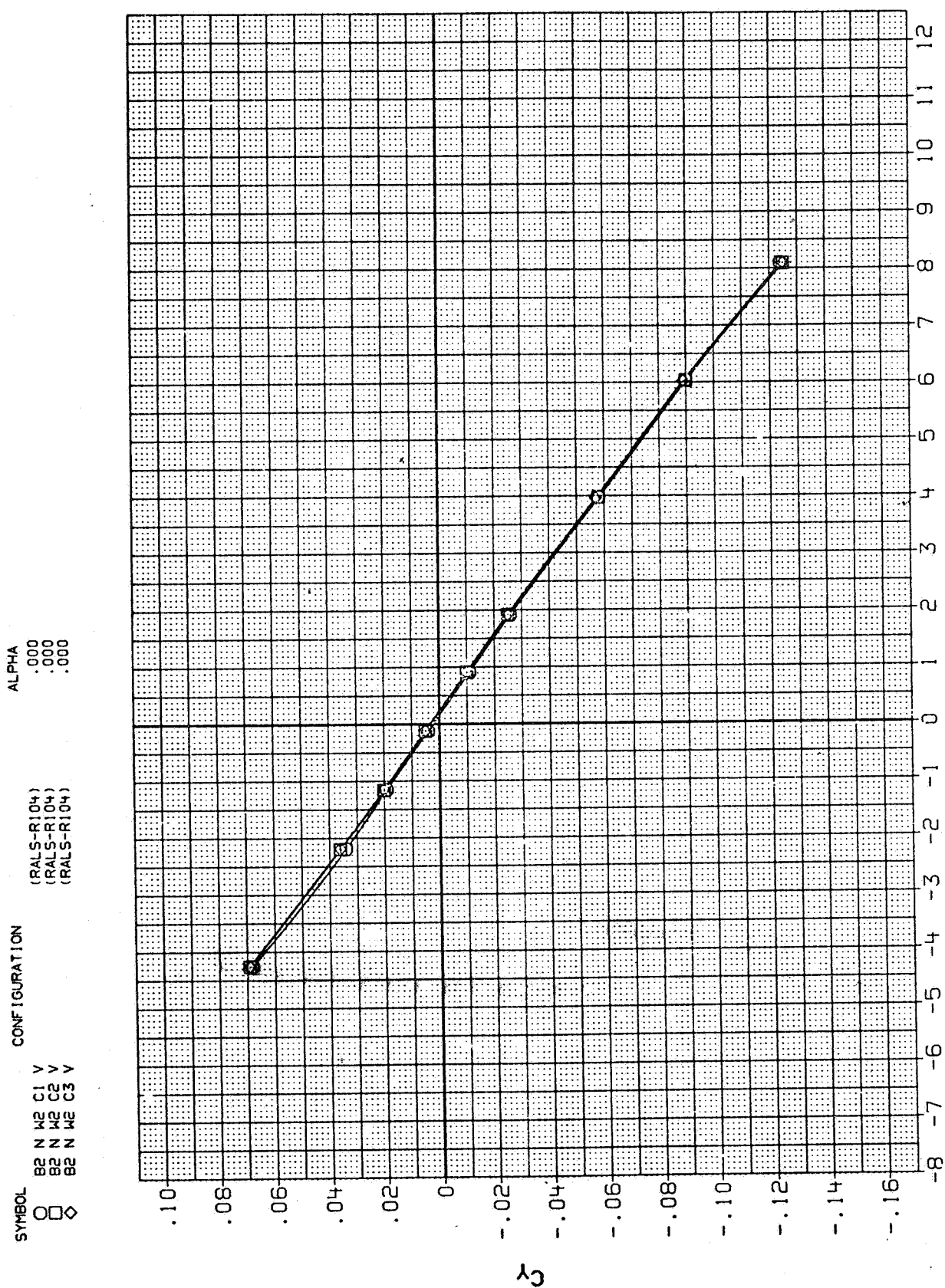


FIG. 119 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL ON

MACH = 1.20

SYMBOL CONFIGURATION ALPHA
 □ B2 N W2 C1 V 11.500
 ○ B2 N W2 C2 V 12.000
 ◇ B2 N W2 C3 V 11.500

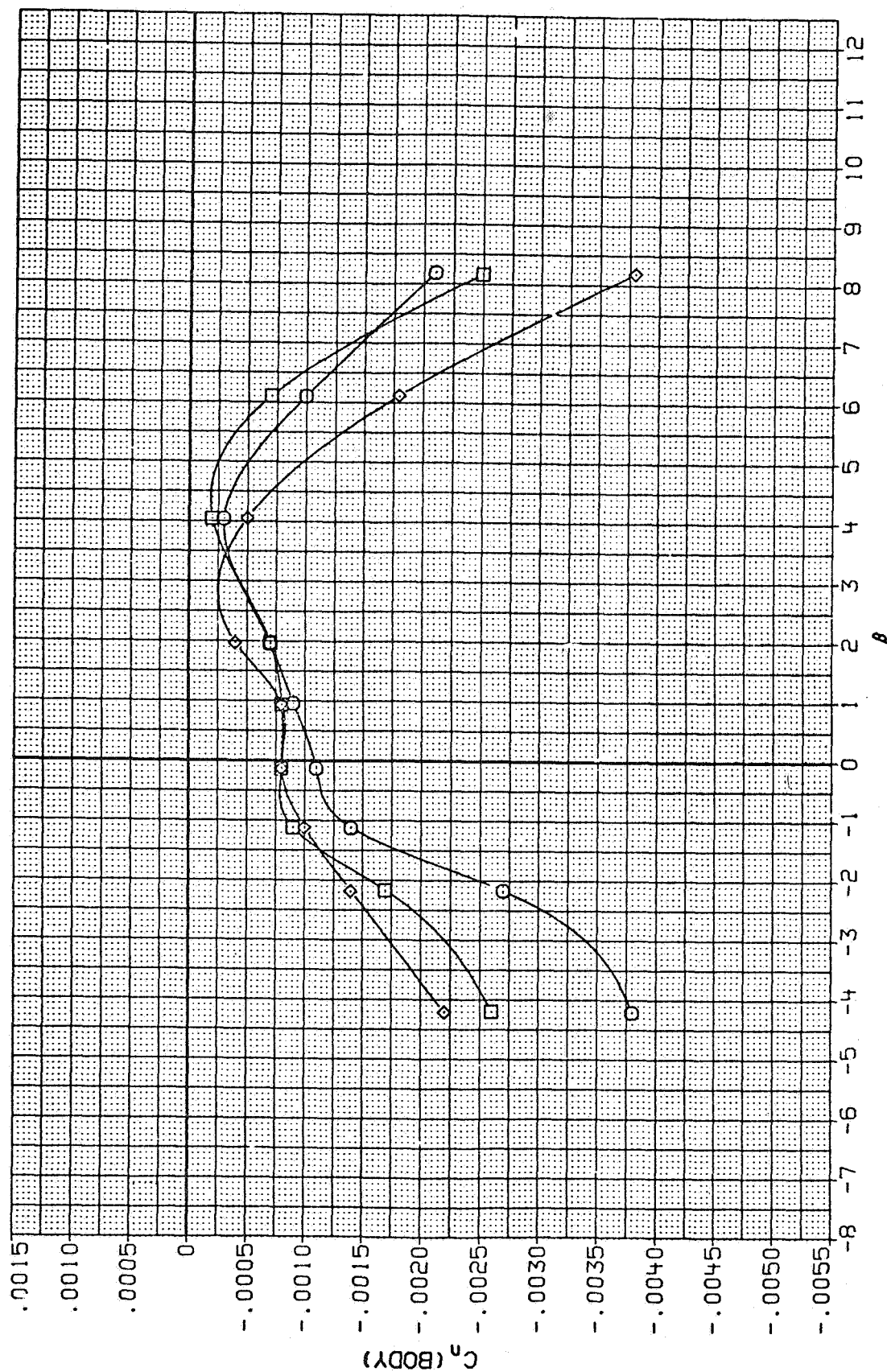


FIG. 119 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

SYMBOL CONFIGURATION ALPHA
 □ 82 N W2 C1 V 11.500
 ○ 82 N W2 C2 V 12.000
 ◇ 82 N W2 C3 V 11.500

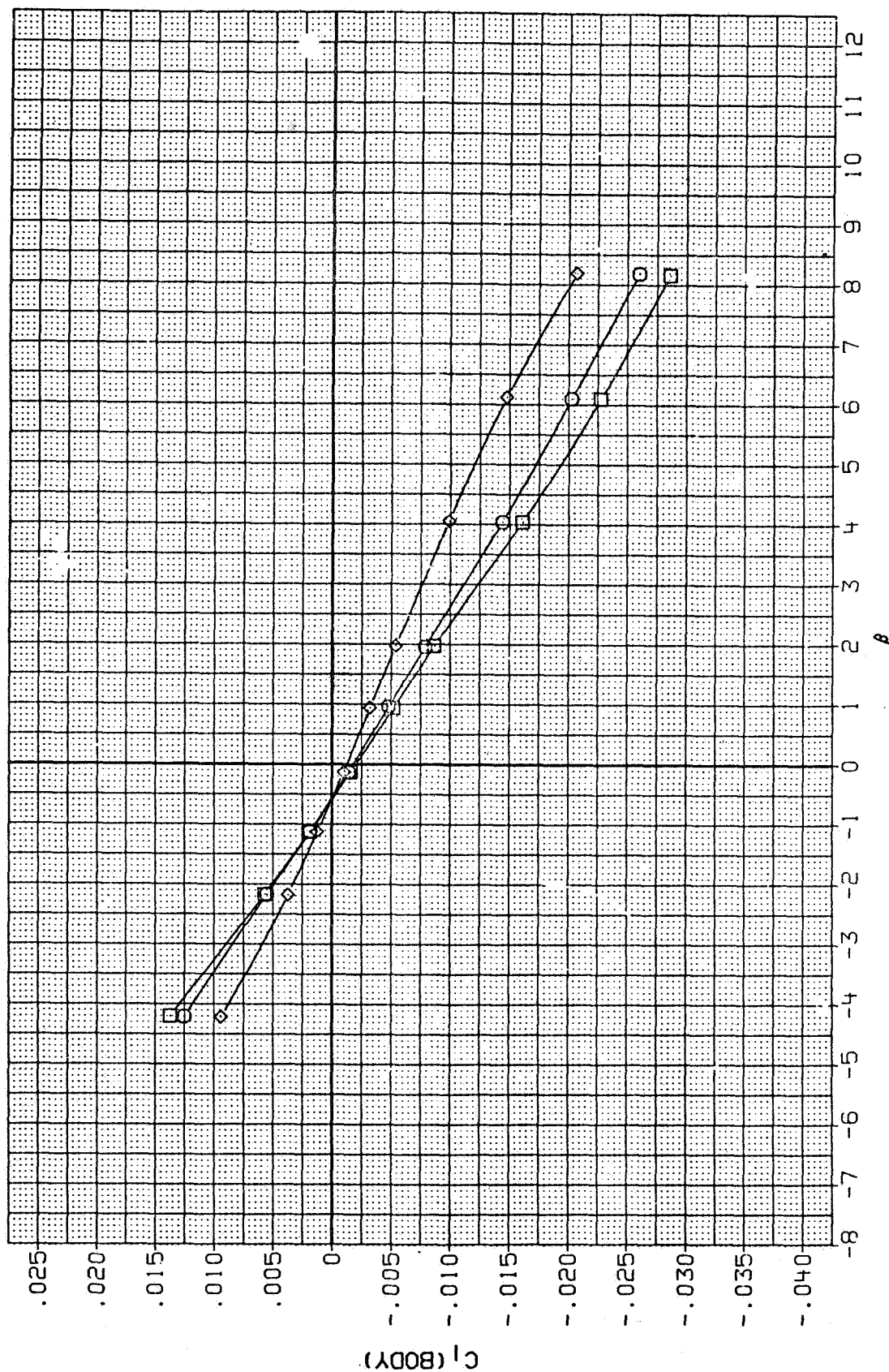


FIG. 119 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL ON
 MACH = 1.20

SYMBOL		CONFIGURATION		ALPHA	
○	B2 N W2 C1 V	(RALS-R104)	11.500		
□	B2 N W2 C2 V	(RALS-R104)	12.000		
◇	B2 N W2 C3 V	(RALS-R104)	11.500		

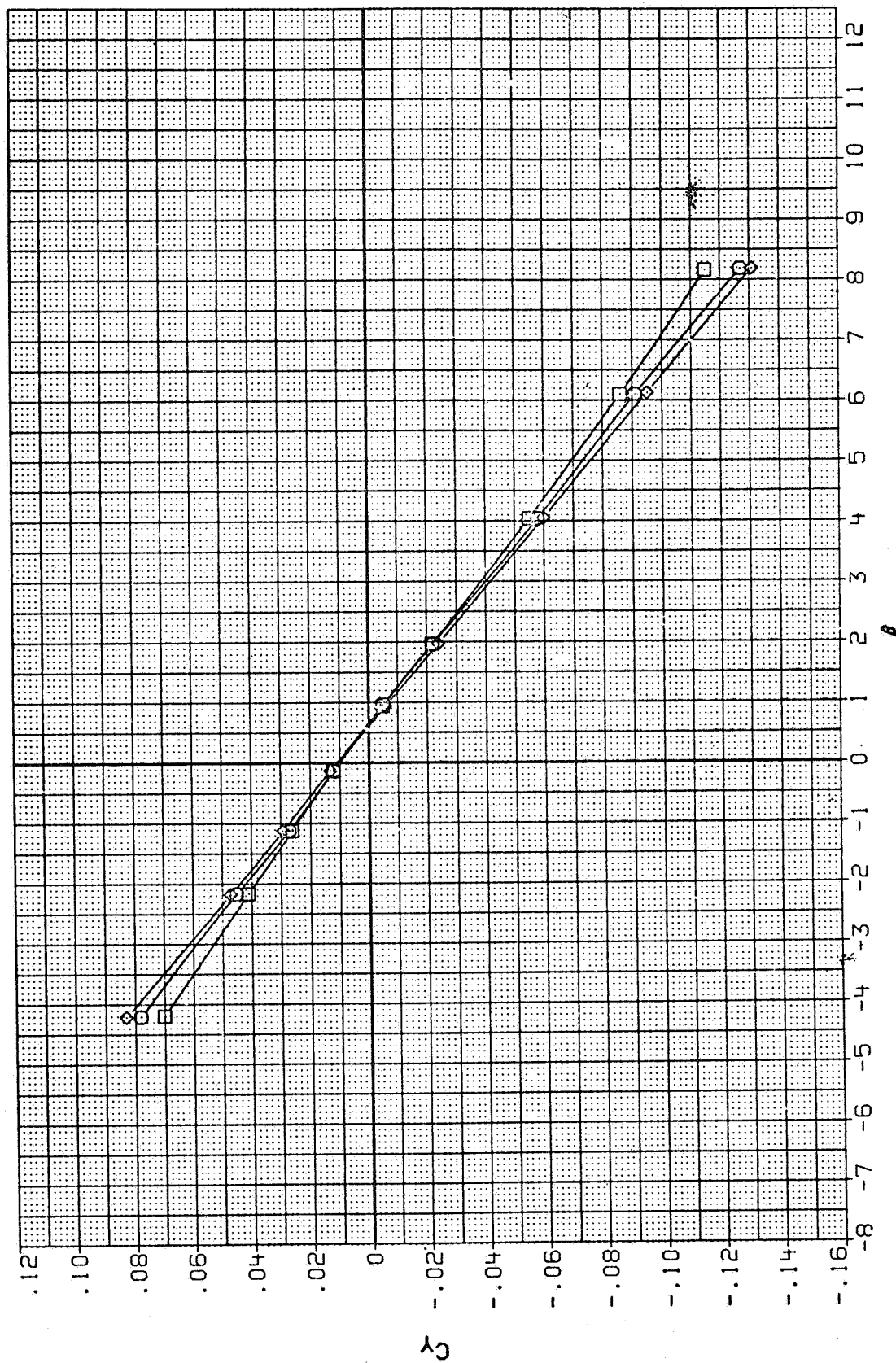


FIG. 119 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
ALPHA = 10 DEGREES, VERTICAL TAIL ON

MACH = 1.20

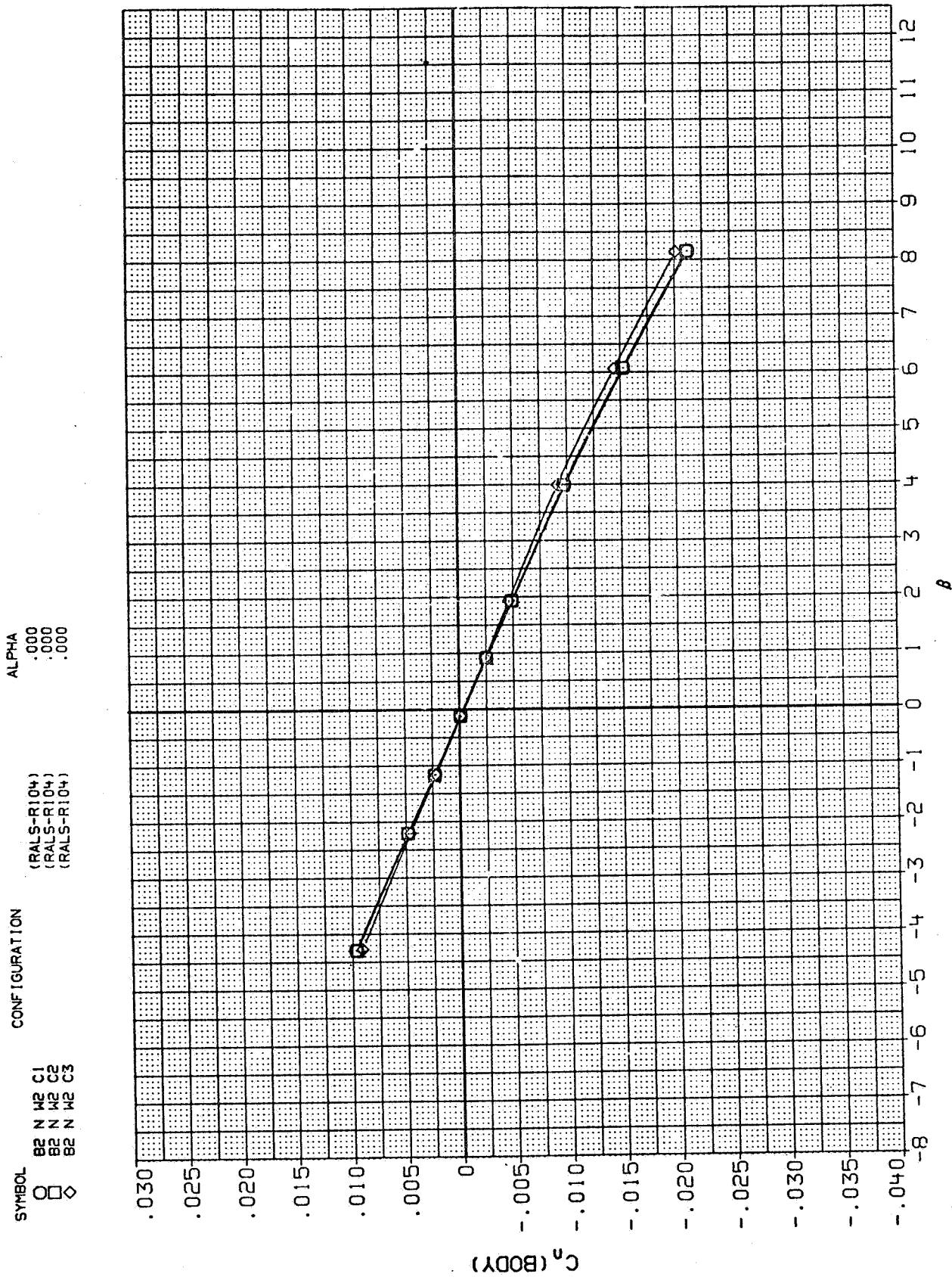


FIG. 120 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF

MACH = 1.20

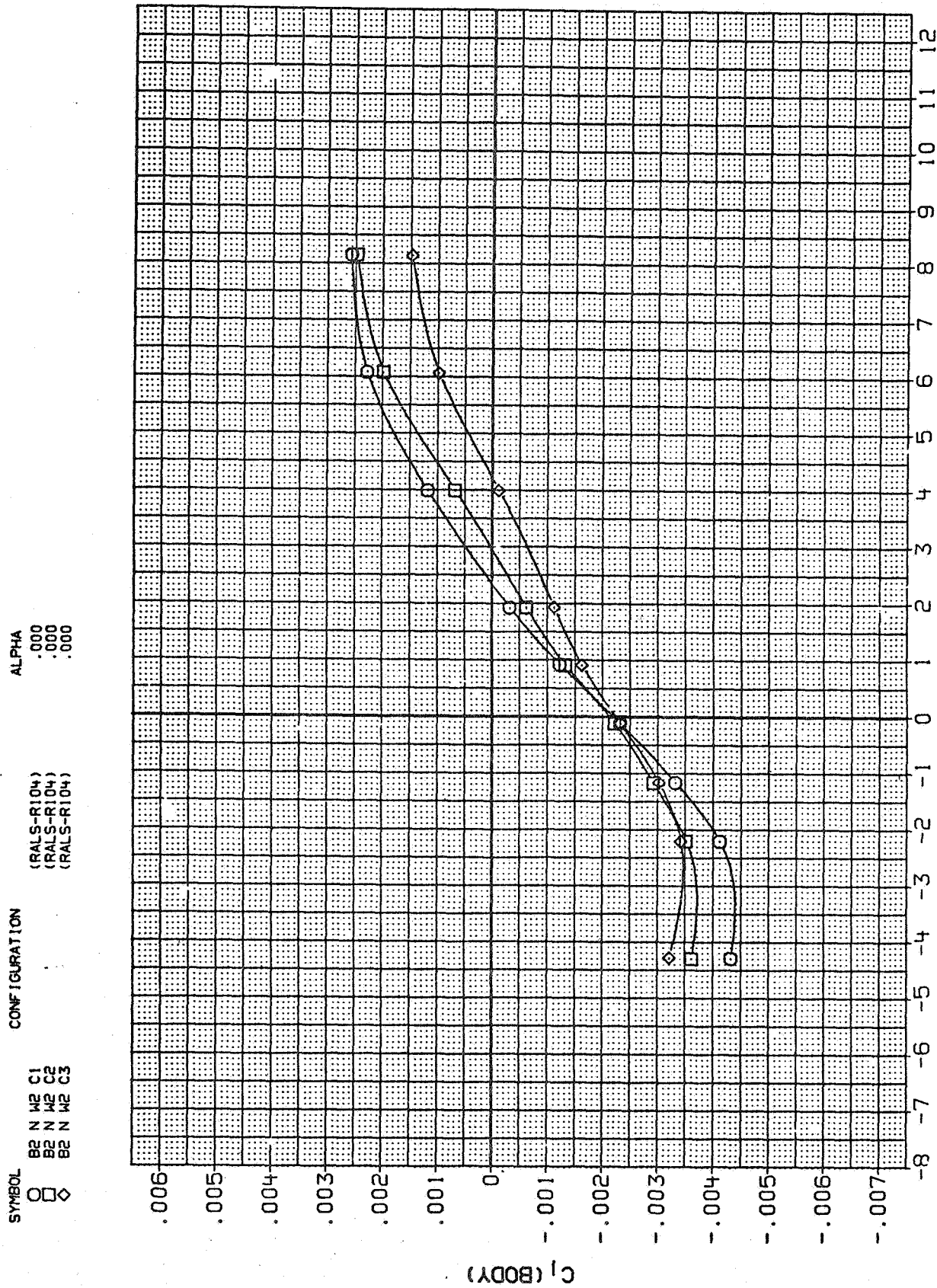


FIG. 120 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF
 MACH = 1.20

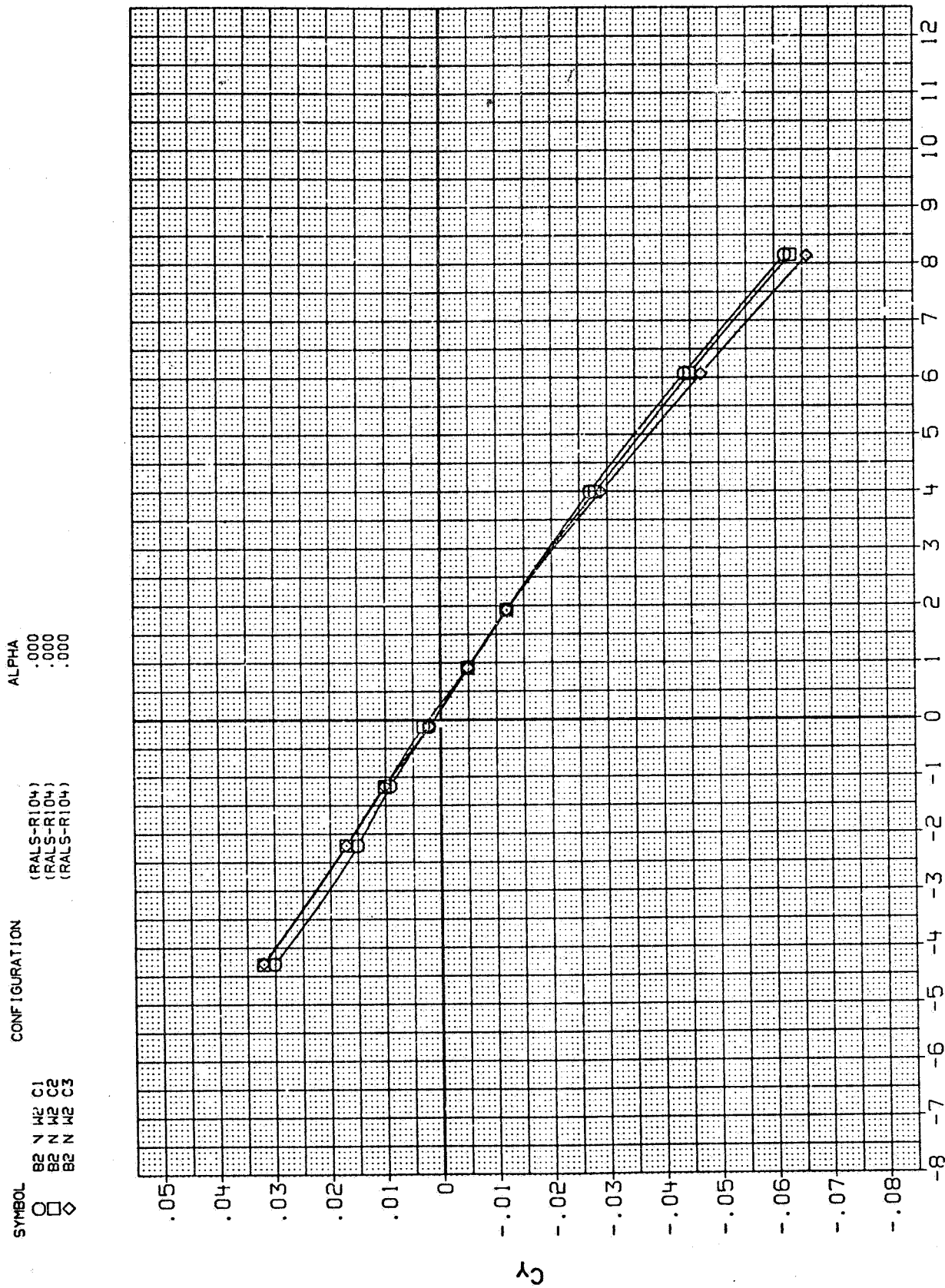


FIG. 120 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 0 DEGREES, VERTICAL TAIL OFF

MACH = 1.20

SYMBOL	CONFIGURATION	ALPHA
□	(RALS-R104)	11.500
◇	(RALS-R104)	12.000

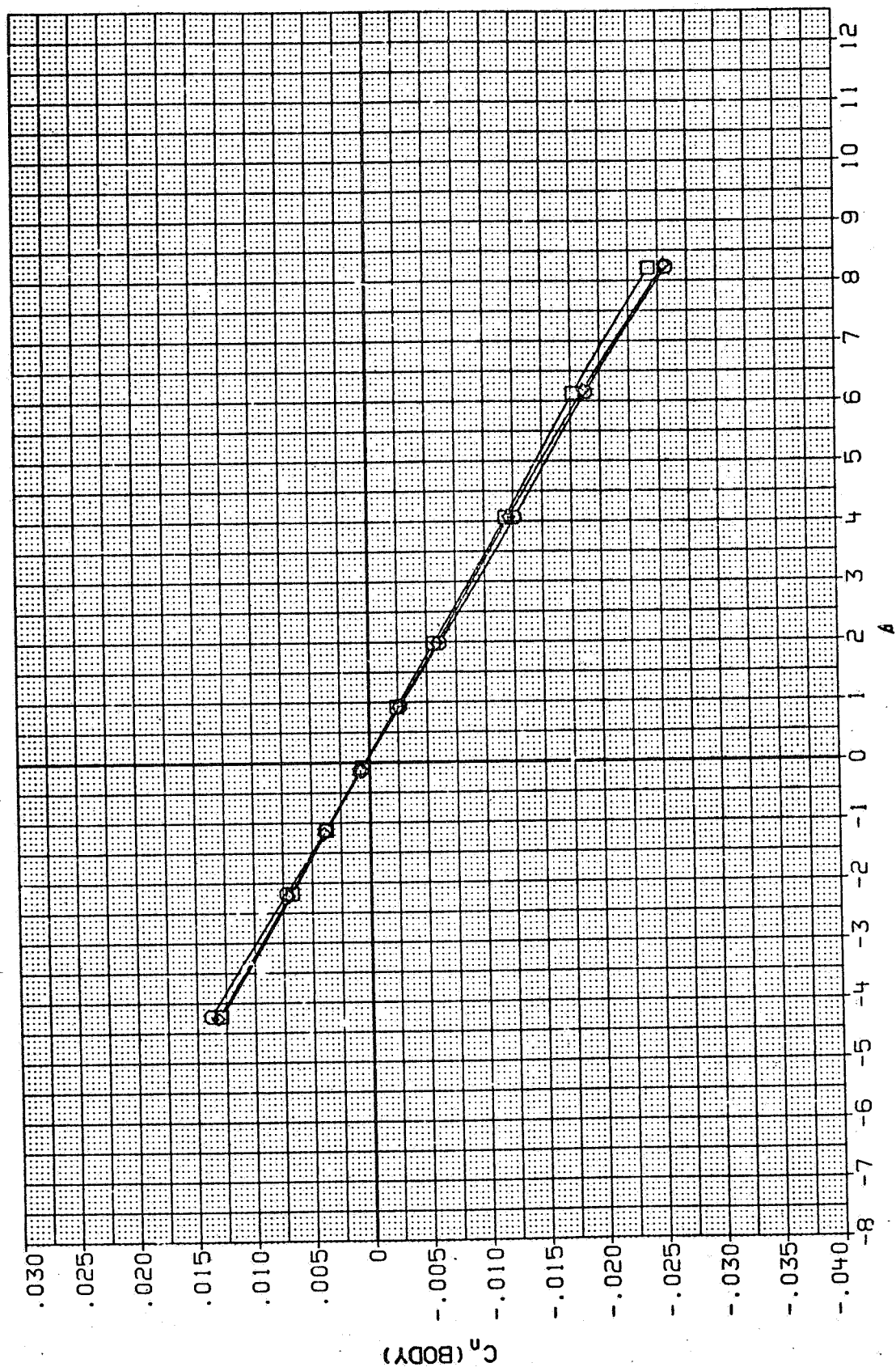


FIG. 120 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL OFF
 MACH = 1.20

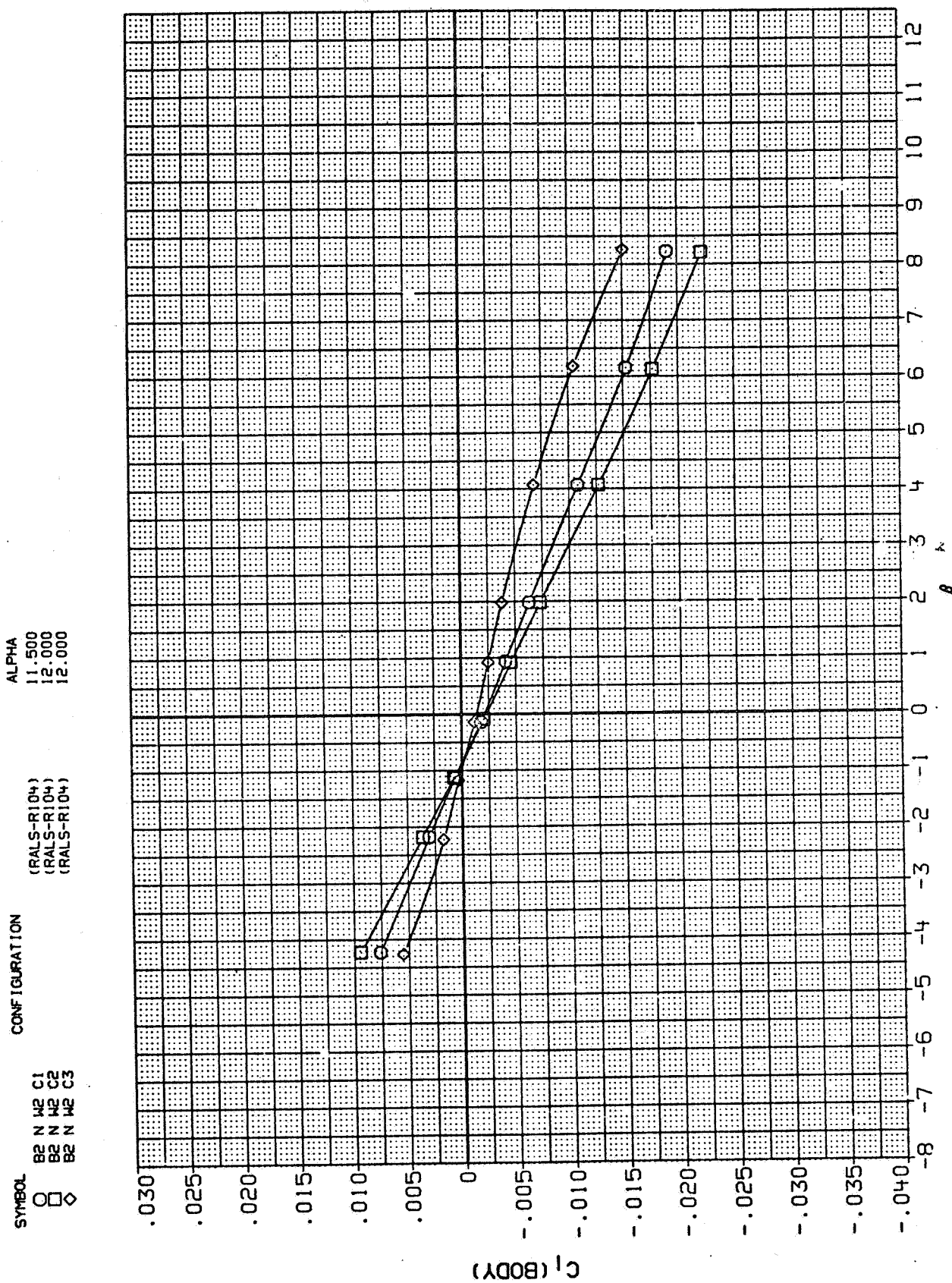


FIG. 120 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL OFF

MACH = 1.20

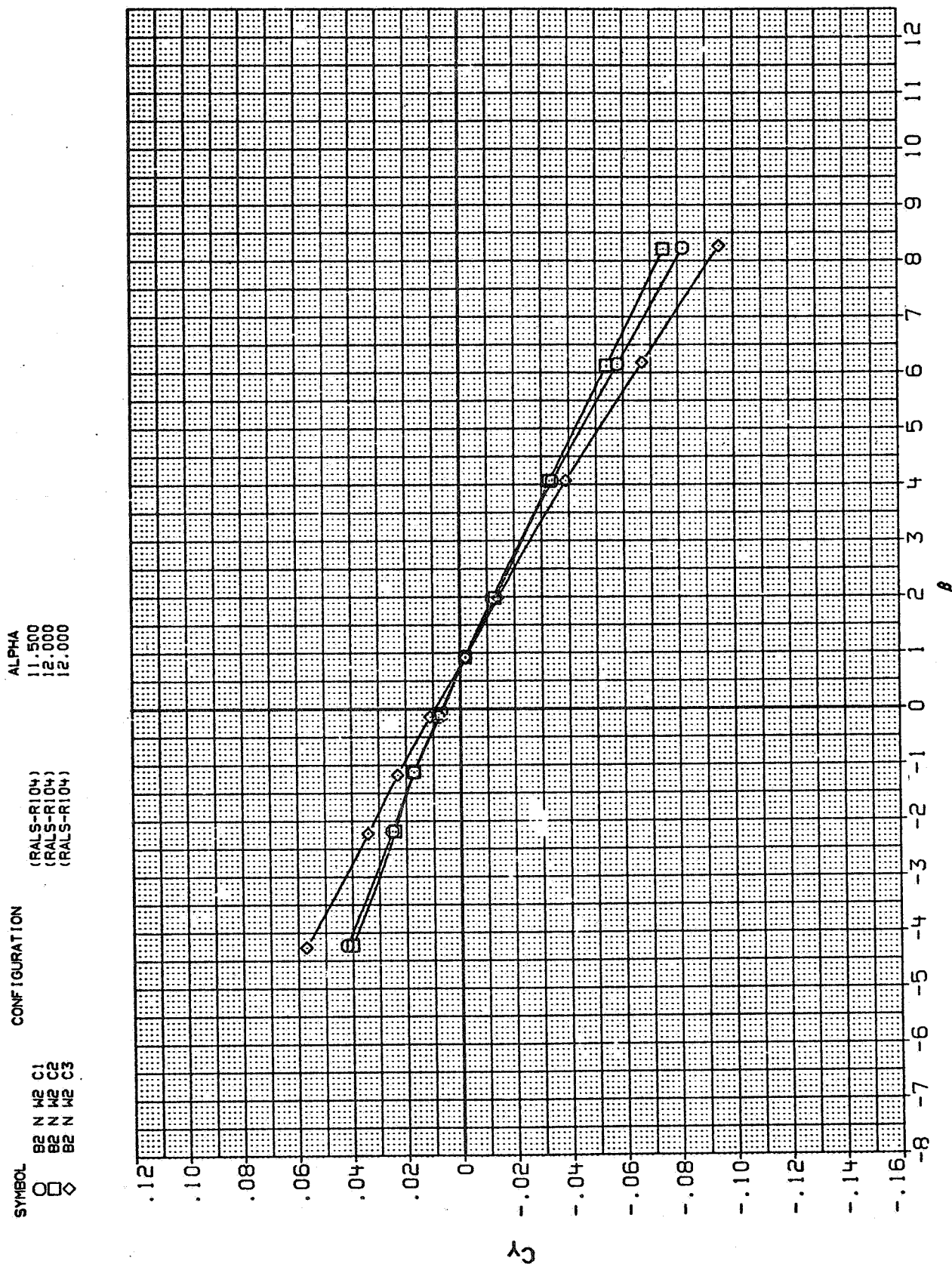


FIG. 120 CANARD LOCATION EFFECTS, LATERAL/DIRECTIONAL CHARACTERISTICS
 ALPHA = 10 DEGREES, VERTICAL TAIL OFF

MACH = 1.20

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15. Supplementary Notes					
16. Abstract A wind-tunnel test was conducted at Ames Research Center (ARC) to measure the aerodynamic characteristics of two horizontal-attitude takeoff and landing V/STOL fighter/attack aircraft concepts. The concepts were developed by the General Dynamics Corporation, Fort Worth Division, in a contract study for Ames Research Center and the David Taylor Naval Ship Research and Development Center (DTNSRDC). In one concept, a jet diffuser ejector was used for the vertical lift system; the other used a remote augmentation lift system (RALS). Wind-tunnel tests to investigate the aerodynamic uncertainties and to establish a data base for these types of concepts have been conducted at ARC over a Mach number range from 0.2 to 2.0. The present report covers tests, conducted in the Ames 11-Foot Transonic Wind Tunnel, for Mach numbers from 0.4 to 1.4. Detailed effects of varying the angle of attack (up to 27°), angle of sideslip (-4° to +8°), Mach number, Reynolds number, and configuration buildup were investigated. In addition, the effects of wing trailing-edge flap deflections, canard incidence, and vertical tail deflections were explored. Variable canard longitudinal location and different shapes of the inboard nacelle-body strakes were also investigated.					
17. Key Words (Suggested by Author(s)) Fighter/attack aircraft Aerodynamic technology Vectored-engine-over-wing (VEO-wing) Remote augmentation lift system (RALS) Propulsive lift VSTOL; Ejector				18. Distribution Statement Unlimited STAR Category - 02	
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