

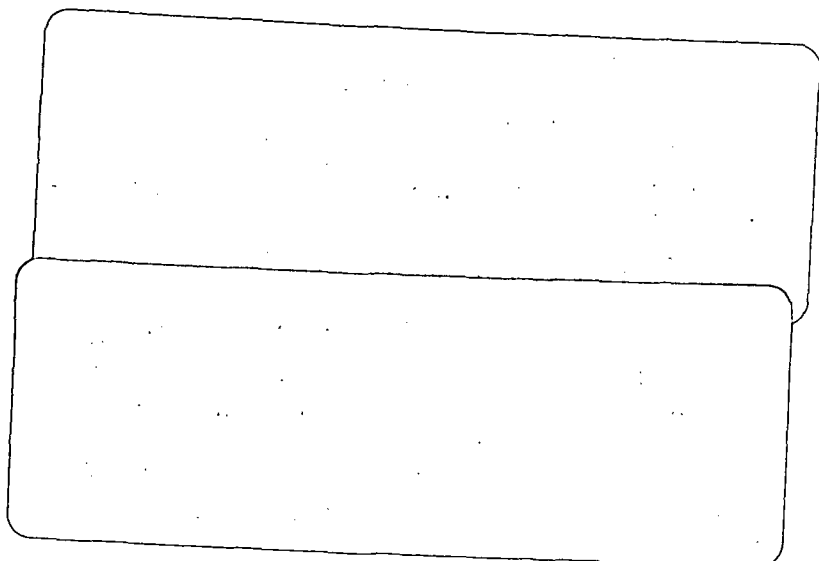
NASA Contractor Report 3122

Computer Programs for Calculating
Pressure Distributions Including
Vortex Effects on Supersonic
Monoplane or Cruciform Wing-
Body-Tail Combinations With
Round or Elliptical Bodies

Marnix F. E. Dillenius and Jack N. Nielsen

CONTRACT NAS1-14495
APRIL 1979

NASA



NASA Contractor Report 3122

**Computer Programs for Calculating
Pressure Distributions Including
Vortex Effects on Supersonic
Monoplane or Cruciform Wing-
Body-Tail Combinations With
Round or Elliptical Bodies**

Marnix F. E. Dillenius and Jack N. Nielsen
Nielsen Engineering & Research, Inc.
Mountain View, California

Prepared for
Langley Research Center
under Contract NAS1-14495

NASA

National Aeronautics
and Space Administration

**Scientific and Technical
Information Office**

1979

TABLE OF CONTENTS

<u>Section</u>	<u>Page No.</u>
SUMMARY	1
1. INTRODUCTION	3
SYMBOLS EXCLUSIVE OF APPENDICES	5
2. GENERAL APPROACH	11
2.1 Body of Revolution with Cruciform Fins	11
2.2 Elliptical Body with Monoplane Wing and Interdigitated Fins	12
3. DETAILED APPROACH FOR BODIES OF REVOLUTION WITH CRUCIFORM FINS	13
3.1 Modeling of Fins by Constant u-velocity Panels	13
3.2 Modeling of Body of Revolution Alone	13
3.3 Body Interference Shell for Fin-Body Interference	14
3.4 Wing-Body Interference Solution	15
3.5 Nose Vortex Characteristics	18
3.6 Pressure Distribution Calculations	20
4. DETAILED APPROACH FOR ELLIPTICAL BODY WITH MONOPLANE WING AND INTERDIGITATED CRUCIFORM TAIL	21
4.1 Modeling of Monoplane Wing, Interdigitated Tails and Elliptical Body by Body Source Panels	21
4.2 Pressures, Forces, and Moments on Body with Elliptical Cross Section	24
4.3 Wing-Body and Tail-Body Interference	28
5. PROCEDURE FOR APPLICATION OF PROGRAMS TO COMPLETE CONFIGURATIONS	29
5.1 Circular Body with Cruciform Canard and Tail Fins	29
5.1.1 Sequential use of programs	29
5.1.2 Assembly of pressure, force and moment data	33
5.2 Elliptic Cross Section Body-Monoplane Wing-Interdigitated Tail Fins	35
5.2.1 Sequential use of program	35
5.2.2 Assembly of pressure, force and moment data	39
6. CALCULATIVE EXAMPLES	41
6.1 Sample Case 1: Axisymmetric Body-Cruciform Canard- Cruciform Tail Fins	41

SUMMARY

Computer programs have been developed capable of calculating detailed aerodynamic loadings and pressure distributions acting on pitched and rolled supersonic missile configurations which utilize bodies of circular or elliptical cross section. The applicable range in angle of attack is up to 20° . Mach number may range from 1.3 to about 3.0.

The theoretical approach described in this report is based on representing the components by three-dimensional singularities associated with supersonic, linear flow theory. The body with circular cross section is modeled by a distribution along the centerline of supersonic line sources or sinks to account for volume effects and supersonic line doublets to account for effects of angle of attack. If the body cross section is elliptical, supersonic body source panels are placed on the body surface accounting for both volume and angle of attack effects. Constant u-velocity panels are distributed over the lifting fins or wings to account for lift. Fin thickness is modeled by planar source panels. The fins may be arbitrarily deflected. In order to account for fin-body interference, a shell with constant cross section is placed around the body over a length equal to the fin rootchord. Constant u-velocity panels are distributed on this interference shell to account for lift carryover onto the body. Behind the trailing edges, fin-body interference is accounted for by the inclusion of the effects of fin trailing vorticity, determined from slender-body theory, in the calculation of body pressures. Body nose vortex shedding is modeled by potential flow vortices whose strengths and positions in the cross flow plane are determined from an analytical-empirical approach. If the body cross section is circular, the body nose shedding vortex data is built into the main program. For bodies with elliptical cross section, this data is input to the body flow modeling program and must be determined from other means. Body nose and canard fin vortex paths along the configuration are calculated by the

vortex chasing program based on slender-body theory including effects of fin deflection.

Over the body nose section, the calculated pressure distribution can include effects of vorticity shed from the body nose. Through the canard or monoplane wing section, the pressures acting on the body and lifting surfaces can be influenced by the body vortices as they travel along the body. From the canard to the tail section, the body pressures can be affected by body and canard fin vortices. The effects of the vortices may also be included in the calculation of the loads on the tail fins.

A description is given for the procedure required to calculate, in a series of steps, pressure distributions and loadings acting on complete configurations. Two calculative examples are shown. The first case involves a cruciform canard-body with circular cross section-cruciform tail. The second case is concerned with a monoplane wing-elliptical cross section body-interdigitated tail configuration. The computer programs are described and documented in the appendices of this report.

1. INTRODUCTION

Methods for computing the supersonic pressure distributions on missiles having monoplane or cruciform fins or missiles with bodies of elliptical cross section are not well developed, and much work is required to produce programs that can be used for design purposes. It is the purpose of the work reported here to extend an existing three-dimensional, supersonic, lifting-surface computer program to include various options required for missiles of the above types. The work was jointly supported by Langley Research Center and the Air Force Flight Dynamics Laboratories. Langley technical directors were Wallace C. Sawyer, Raymond L. Barger, and Jerry M. Allen; Air Force technical director was Calvin L. Dyer.

Before describing the extensions to the preexisting program, a brief description of it will be given. The program was developed under ONR sponsorship and is described in references 1 and 2. In reference 1 supersonic planar or cruciform wing-body combinations with round bodies were treated, and fin loadings were determined using panel methods and linear theory. No vortices were included, and a tandem set of lifting surfaces was not covered. In reference 2 the full Bernoulli pressure equation was used in determining fin loadings. The paths of vortices behind cruciform fins were studied for a cylindrical afterbody using both slender-body theory and the full wave equation. It was decided that slender-body results were sufficiently accurate. Provision to account for specified nose vortices on the fin loading was included. Preliminary leading- and side-edge suction calculations were implemented for the purpose of modeling separation vortices from the leading- and side-edges of the fins using the Polhamus vortex lift analogy described in reference 3. Furthermore, the effects of body nose and canard vortices on the cruciform tail were determined. The applicable range of included angle of attack was increased to about 20° .

The additional scope of the present report covers extensions to the computer program of reference 2 to two missile types, cruciform wing-body combinations with an axisymmetric body and a combination with elliptic body cross sections, monoplane wing and cruciform interdigitated tails. With regard to the first configuration the following items have been added to the computer program:

(1) Add option for determining body nose vortex characteristics explicitly.

(2) Calculate body pressure coefficients for entire missile.

(3) Explicitly determine the positions of all vortices at the canard trailing edge including nose vortices and vortices from canard fin leading edges, side edges, and trailing edges.

(4) Add an option to calculate the trajectories of all vortices over the entire length of the missile.

(5) Include effects of canard and tail fins deflection on vortex paths and fin loadings.

(6) Add option to include effects of canard fin thickness.

With regard to the missile with a body of elliptical cross section, the following tasks are addressed herein:

(1) The three dimensional, supersonic, lifting-surface computer program is to be extended to monoplane wing - combinations for elliptical cross-section missile bodies with cylindrical and boat-tailed aft ends having various conventional wing planform shapes. Pressure distributions shall be calculated including thickness and vortex effects. The resulting forces and moments are to be determined.

(2) The program is to be extended to include provisions for handling a cruciform interdigitated tail that can be located at various cant angles to the body surface. The loads on the tail fins are to be calculated including tail fin-body interference effects together with wing vortex effects. No thickness need be included for the tail fins. The fin contributions to the overall forces and moments are to be determined.

In this report the general approaches are described first for determining the pressure distributions on the two configurational types under consideration. Then a more detailed description of the approach is given with the bulk of the analytical material given in a series of appendices. Next, detailed procedures are given for applying the component computer programs to complete configurations, followed by two calculative examples. Some comparisons between predictions and experiment are then given. Complete descriptions of the component computer programs are given in appendices together with input and output format.

SYMBOLS EXCLUSIVE OF APPENDICES

a		local body radius
c		chord of a fin panel through its centroid
c_2		chord of fin panels at fin side edge
C_m	body axis	component moments per unit dynamic pressure along $y_B, z_B,$ and x_B due to net effect of C_N panels summed over all body panels
C_n	body axis	
C_ℓ	body axis	
C_m	panel	pitching moment, yawing moment, and rolling moment for unit dynamic pressure of single body source panel in x_B, y_B, z_B coordinates
C_n	panel	
C_ℓ	panel	
C_m	wind axis	component moments for unit dynamic pressure along \bar{y}, \bar{z} axes due to net effect of C_N panels summed over all body panels
C_n	wind axis	
C_D	C_x	wind axis
C_L	C_N	wind axis
$C_{x_B}, C_{y_B}, C_{z_B}$		components in x_B, y_B, z_B coordinates of C_N panel summed over all body panels
C_{x_B}	panel	components of C_N panel along $x_B, y_B,$ and $z_B,$ respectively
C_{y_B}	panel	
C_{z_B}	panel	
C_N	panel	force normal to body panel for unit dynamic pressure, $(C_p) \cdot (\text{panel area})$

SYMBOLS EXCLUSIVE OF APPENDICES (Continued)

C_x wind axis	components in \bar{x} , \bar{y} , \bar{z} coordinates of C_N panels summed over all body panels
C_z wind axis	
C_z wind axis	
$C_{N_{LE}}$	fin normal-force coefficient due to leading-edge suction
$C_{N_{SE}}$	fin normal-force coefficient due to side-edge suction
C_S	suction coefficient, suction force divided by qS_R
C_P	pressure coefficient, $(p-p_\infty)/q$
$C_{P_{min}}$	pressure coefficient for vacuum
ΔF_X	force in $-x_W$ direction acting on lifting vortex element of fin panel
ΔF_{Y_1}	force in y_W direction acting on lifting vortex element of fin panel
ΔF_{Y_2}	force in y_W direction acting on trailing vortices along side edge of a panel for a distance " c_2 " between successive trailing vortex element intersections with the edge
GAMT	nondimensional body vortex strength, equation (7)
$K_{LE}, K_{V,LE}$	$C_{N_{LE}}/C_{S_{LE}}$
$K_{SE}, K_{V,SE}$	$C_{N_{SE}}/C_{S_{SE}}$
M_∞	free-stream Mach number

SYMBOLS EXCLUSIVE OF APPENDICES (Continued)

n	summation index for all constant u-velocity panels
NCW	number of fin panels along the chord
NHP	number of constant u-velocity panels on both horizontal fins
NPANLS	sum of panels on horizontal and vertical fins
NRP	number of panels on right horizontal fin
NWBP	total number of panels on cruciform fins and body interference shell
N3P	number of constant u-velocity panels on upper vertical fin and horizontal fins
p	load static pressure
p_{∞}	free-stream static pressure
q, q_{∞}	free-stream dynamic pressure
r_b	body radius at start of cylindrical section
S_R	missile reference area
SUMFT2	see quation (24)
SUMFX	sum of all forces acting upstream on vortex elements of fin in vortex lattice structure nondimensionalized by qS_R
SUMFY1	see equation (22)
SUMFY2	see equation (23)

SYMBOLS EXCLUSIVE OF APPENDICES (Continued)

u, v, w	components of the flow velocity along axes $x_B, y_B,$ and $z_B,$ respectively
u^+	axial velocity on outward surface of constant u-velocity panel
$\bar{u}, \bar{v}, \bar{w}$	components of velocity V_R along wind axes corresponding to $x_B, y_B,$ and z_B for $\alpha_c = 0$ and $\phi = 0$
v_N	velocity normal to body interference panel due to constant u-velocity panels of fins and interference shell
v_{N_t}	velocity normal to body interference panel due to fin thickness source panels
V_R	total resultant velocity at point on the body surface
v_W	velocity induced normal to vertical fin by all constant u-velocity panels of fins and interference shell
v_{W_i}	velocity induced normal to vertical fin by body axis singularities and external vortices
V_∞	free-stream velocity
w_N	velocity normal to body source panel with orientation angles θ and δ
w_W	velocity induced normal to horizontal fin by all constant u-velocity panels of fins and interference shell
w_{W_i}	velocity induced normal to horizontal fin by body axis singularities and external vortices

SYMBOLS EXCLUSIVE OF APPENDICES (Continued)

α	angle of pitch, equation (12)
α_c	included angle of attack, angle between free-stream velocity vector and body longitudinal axis
β	angle of sideslip, equation (12)
γ	ratio of specific heats of air
Γ_B	strength of right body nose vortex
δ	pitch of panel about y' axis positive in direction $x' \rightarrow z'$
$\delta_{H,L}$	deflection of left horizontal fin, positive trailing edge down
$\delta_{H,R}$	deflection of right horizontal fin, positive trailing edge down
$\delta_{V,D}$	deflection of lower vertical fin, positive trailing edge right
$\delta_{V,U}$	deflection of upper vertical fin, positive trailing edge right
θ	polar angle in y_B, z_B plane
θ_s	streamwise slope of bevelled leading edge of fin
$\theta_{2,BIP}$	angle between trailing edge of body panel and y_B or y_w axis
ν	index of all control points on cruciform fin and body interference shell
ϕ	roll angle of missile, positive for clockwise rotation looking toward the nose

SYMBOLS EXCLUSIVE OF APPENDICES (Continued)

x_B, y_B, z_B	Cartesian coordinates fixed to missile with the origin at the body nose tip; x_B is positive rearward, y_B is positive to right looking forward, and z_B is positive upward.
$\bar{x}, \bar{y}, \bar{z}$	wind axes corresponding to x_B, y_B, z_B when $\alpha_c = 0, \phi = 0$
x', y', z'	set of axes obtained by first rotating y_B and z_B about x_B by angle θ in positive sense followed by rotating angle δ about new y_B ($=y'$) axis
$x_{B,V}, y_{B,V}, z_{B,V}$	coordinates of body vortex in x_B, y_B, z_B coordinates
x_B	axial distance behind body nose
$x_{B,s}$	distance from body nose to body separation location
$x_{B,TLE}$	value of x_B at leading edge of tail fin root chord
$x_{B,TTE}$	value of x_B at trailing edge of tail fin root chord
$x_{B,WLE}$	value of x_B at leading edge of wing root chord
$x_{B,WTE}$	value of x_B at trailing edge of wing root chord
XST	axial distance parameter, equation (6)
x_M, y_M, z_M	coordinates of moment center in x_B, y_B, z_B coordinates; $y_M = 0$
y_V, z_V	coordinates of right body vortex with y_V measured positive to right of plane of α_c and z_V measured in α_c plane normal to flow direction

2. GENERAL APPROACH

2.1 Body of Revolution with Cruciform Fins

The basic methods employed to represent an axisymmetric body with cruciform fins have been described in reference 1. The computer program of that reference is based on the wave equation associated with supersonic, linear flow theory. The program models axisymmetric bodies and the fins accounting for mutual interference by the inclusion of an interference panel shell around the body where fins are attached. This program served as the starting point for the determination of the aerodynamic characteristics at higher angles of attack by the inclusion of nonlinear features in the methods initially developed in reference 2. They include the full Bernoulli relationship for the pressure coefficient and the capability to account for specified or hand calculated vorticity shed from the body nose and the fins. In the computer program of reference 2, the body nose vortex strengths and positions for the case at hand were extracted from the experimental data presented in reference 4 and added to the program input.

The present wing-body program, designated DEMON2, incorporates the data for body nose vorticity as a function of axial distance from the nose if the body is circular in cross section. These data, used if the included angle of attack exceeds 4° , are tabulated in this report. The calculation of the vorticity shed from the edges of the fins is now performed by program DEMON2, as described in Appendices B and C. Results include the distribution of vorticity along the leading and side edges, which contribute to one or more concentrated vortices at the trailing edge on each side. A program designated VPATH2, based on slender-body theory, is used to track body nose vortices past the canard section, and to track body nose vortices and canard vortices past the afterbody and tail section for the case involving an axisymmetric body. The fins can have arbitrary deflection. This program serves as a companion to program DEMON2. The crossflow plane solutions are given in Appendix I. For cases involving axisymmetric bodies, program DEMON2 then computes, in a series of steps, the pressures acting on the body surface, fins and the part of the body covered by the interference shell including the effects of body and fin vortices where applicable. A detailed description of the procedure is given subsequently in section 5.1.

2.2 Elliptical Body with Monoplane Wing and Interdigitated Fins

For the purpose of handling a body with elliptical cross section, a separate program designated WDYBDY has been developed. This program serves as a companion to program DEMON2 and performs the body-alone modeling when the cross section of the body is elliptical. The method makes use of supersonic body source panels distributed on the surface of the body to account simultaneously for volume and angle of-attack effects. In addition, program DEMON2 has been generalized to treat an interference panel shell with elliptical cross section to which either a monoplane wing or interdigitated tail fins can be attached. The required geometrical transformations and extended flow tangency condition are described in Appendix E. For a body with elliptical cross section, the body nose vorticity characteristics are read in to program WDYBDY and are determined from a separate method since no data base is available as yet. A combined theoretical-empirical computer program for this purpose was developed for the spin-entry studies described in reference 5. This program was specialized to determine the strengths and positions of vortices shed from noses with elliptical cross section at supersonic conditions. For the sake of illustrating the use of the programs, an application of it is included in the second calculative example described later. The vortices are tracked by program VPATHL, based on slender-body theory, past the monoplane wing section and along the body with elliptical cross section up to the tail section if the length of the body is long enough.

For configurations involving bodies with elliptical cross section, program WDYBDY computes the pressures on the body surface up to the forward lifting surfaces (monoplane wing) and between the forward surfaces and tail surfaces (interdigitated tails) including effects of body and wing vortices where applicable. In the monoplane wing and interdigitated tail regions, program DEMON2 determines the pressures on the lifting surfaces and the part of the body covered by the interference panel shell including the effects of vortices where applicable.

By using the above mentioned programs in sequence it is possible to compute the pressure distributions and fin loadings acting on complete configurations by treating first the nose section, then the forward lifting surface section, followed by the afterbody and the tail section.

3. DETAILED APPROACH FOR BODIES OF REVOLUTION WITH CRUCIFORM FINS

In this section, the paneling method used to model lifting surfaces and the line singularity distributions used to model axisymmetric bodies will first be summarized. The method used to account for body-fin mutual interference is described. Features added to the boundary condition, to be shown below, include an account for fin thickness and arbitrary fin deflection. The separation vorticity data associated with axisymmetric body noses is tabulated and the pressure calculation method is described.

3.1 Modeling of Fins by Constant u-velocity Panels

Each fin of a cruciform fin-axisymmetric body combination is divided into trapezoidal area panels. The geometrical layout is accomplished by subroutine LAYOUT of program DEMON2. These panels are called constant u-velocity panels for supersonic flow and are located in the chordal planes of the lifting surfaces. When the full Bernoulli equation is used to calculate pressure, these panels are no longer constant pressure panels as referred to by Woodward et al. in reference 6. The solution for a given panel is generated by a superposition of the basic solutions for semi-infinite triangles with their apexes at the panel corners. The basic solution and superposition schemes, as implemented in subroutines VELO and VELNOR of program DEMON2, are described in great detail in sections 3.3.2 through 3.3.6 and Appendix II of reference 7. In addition, the effects of fin thickness are accounted for by the use of constant strength source panels located in the chordal planes of the fins. Their solutions are also obtained by a superposition scheme of semi-infinite triangles as described in section 3.3.4 and Appendix II of reference 7. In program DEMON2, the basic solution and superposition schemes associated with the constant strength source panels for fin thickness are programmed in subroutines VELOTH and THKVEL, respectively.

3.2 Modeling of Body of Revolution Alone

The potential flow model used to represent an axisymmetric body in supersonic flow is described in detail in section 3.2 and Appendix I of reference 7. Such a body can be represented by a distribution of line sources/sinks and line doublets along the body centerline to account for

volume and angle of attack effects, respectively. The strengths of these singularities are determined from the flow tangency condition applied at points on the body surface using a marching procedure from the nose tip to body base. Subroutine BDYGEN of program DEMON2 is concerned with the layout and strength determination of the line singularities. It is possible that a portion of the body nose contour lies outside the Mach cone from its apex at the nose tip. This can occur for high Mach numbers. In this case, the present version of subroutine BDYGEN has been programmed to move the origins of the line singularities up towards the body nose. The result is to minimize the inherent error in the solution near the nose if the Mach cone from the nose tip intersects the body contour. The part of the nose contour outside the Mach cone is then replaced by a cone. This constitutes a limitation to the method. An illustration of this scheme will be discussed later in connection with the pressure distribution on an ogive-cylinder using the Bernoulli pressure expression.

3.3 Body Interference Shell for Fin-Body Interference

An interference shell is positioned around the body over the length covered by the fins to account for fin-body interference. Constant u-velocity panels are distributed on this shell by subroutine LAYOUT in addition to those on the fins. The panels on the interference shell and fins contain one control point each, which is located at the 95 percent chord containing the panel centroid. A typical distribution of constant u-velocity panels is shown in figure 1. The body and wing coordinate system, (x_B, y_B, z_B) and (x_W, y_W, z_W) , respectively, are also shown. The axial location on the centerline of the origin of the latter is at the axial location of the leading edge of the fin root chords. Both coordinate systems can be the reference coordinate system. Fins in the $z_W = 0$ or $z_B = 0$ plane are called horizontal fins. Fins in the $y_W = 0$ or $y_B = 0$ plane are called vertical fins. Angle of pitch, α , and sideslip, β , are determined from the included angle of attack, α_c , and roll angle ϕ .*

* See equation (12)

3.4 Wing-Body Interference Solution

For the cruciform fin-axisymmetric body combination shown in figure 1, the strengths of the line singularities representing the body itself are solved for by subroutine BDYGEN in program DEMON2. Body on fin interference is accounted for as follows. The velocities normal to the fins at the control points induced by the body line singularities are computed by subroutine VELCAL in program DEMON2. On the horizontal fins these velocities are added to the free-stream component normal to the fin surface including the effect of fin deflection. On the vertical fins, the body induced normal velocity is added to the free-stream component normal to the vertical fin surface. These additions are performed in routine CRFWBD of program DEMON2. If external vortices are present, their effects are determined separately by program VPATH2 and added to the body induced velocities by an exchange of data sets between VPATH2 and DEMON2. The flow tangency condition applied to the control points on the horizontal fins is built up in routine CRFWBD of program DEMON2 as follows. Let the number of panels laid out over the cruciform fins and interference shell be NWBP and let NRP be the number of panels on the right horizontal fin only. Then, with v as index for all the control points and n the summation index for all the constant u -velocity panels, the flow tangency condition for the right horizontal fin is given by

$$\sum_{n=1}^{NWBP} w_{W_{v,n}} = -\sin(\alpha + \delta_{H,R}) - w_{W_{i,v}}, \quad v = 1, 2, \dots, NRP \quad (1)$$

where α is the angle of pitch and $\delta_{H,R}$ is the deflection of the right horizontal fin. The term on the left-hand side represents the summed velocity component (for unit V_∞) normal to the horizontal fin induced by all constant u -velocity panels on the fins and interference shell of the finned section under consideration. The method for calculating the terms on the left-hand side of equations (1) through (5) is given on page 6 of reference 1 or section 3.3.4 of reference 7. The first term on the right-hand side is due to the free-stream velocity, and the second term $w_{W_{i,v}}$ is induced by the body singularities and external vortices if present. Setting NHP equal to the number of constant u -velocity panels on both horizontal fins, the flow tangency on the left horizontal fin is expressed as

$$\sum_{n=1}^{NWBP} w_{W_{v,n}} = -\sin(\alpha + \delta_{H,L}) - w_{W_{i,v}}, \quad v = NRP+1, \dots, NHP \quad (2)$$

where $\delta_{H,L}$ is the deflection of the left horizontal fin. Let N3P be equal to the number of constant u-velocity panels on the upper vertical fin plus the number on the horizontal fins. The flow tangency condition applied at the control points of the upper vertical fin is written as follows:

$$\sum_{n=1}^{NWBP} v_{W_{v,n}} = \sin(\beta + \delta_{V,U}) - v_{W_{i,v}}, \quad v = NHP+1, \dots, N3P \quad (3)$$

Angle β is angle of sideslip and $\delta_{V,U}$ is the deflection of the upper vertical fin. The term on the left-hand side represents the summed velocity normal to the upper vertical fin induced by all constant u-velocity panels on the fins and interference shell. The first term on the right-hand side is due to the free-stream velocity, and the second term $v_{W_{i,v}}$ is induced by the body singularities and external vortices if present. The flow tangency applied at the control points of the lower vertical fin is

$$\sum_{n=1}^{NWBP} v_{W_{v,n}} = \sin(\beta + \delta_{V,D}) - v_{W_{i,v}}, \quad v = N3P+1, \dots, NPANLS \quad (4)$$

Here $\delta_{V,D}$ is the deflection of the lower vertical fin and NPANLS is the sum of the panels on the horizontal and vertical fins.

For cruciform fin-axisymmetric body combination the fins lie in mutually perpendicular planes of symmetry of the cylindrical body (at least for the fins at zero cant angle). Consequently, thickness effects of one fin cannot influence the loading on other fins but they can affect the panels on the interference shell. Therefore, if fin thickness is to be accounted for, the flow tangency condition applied at a control point on the interference shell is now stated as follows:

$$\sum_{n=1}^{NWBP} v_{N_{v,n}} = -v_{N_{t,v}}, \quad v = NPANLS+1, \dots, NWBP \quad (5)$$

In this instance, the term on the left-hand side is the summed velocity normal to the body interference panel with index v induced by the constant u-velocity panels on the fins and the shell itself. The term on the right-hand side is the velocity normal to the v^{th} body interference

panel induced by all the source panels laid out over the fins to model thickness effects. In this way, fin on body interference is accounted for. Note that vortex induced velocity components are not included in the boundary condition associated with the interference shell, equation (5). The two-dimensional approach used to track vortices past bodies and body-fin combinations already insures that there is no flow through the body surface and fins due to the presence of external vortices. However, to satisfy the fin boundary condition in a three-dimensional sense, the loading on the fins due to the vortices is accounted for on the basis of the panel method from the known vortex paths. Thus, the vortex paths from the leading edge of the cruciform canard on to the tail are first calculated by program VPATH2 on the basis of slender-body theory accounting for the geometry of the configuration. Then, for the axial location of each control point on the fins, subroutine VVELS of program VPATH2 also calculates the velocities at the fin control points induced by the external vortices and their images for the body alone. In this approach, the reaction of the fins to the effect of external velocities comes from two sources. First, the strengths of constant u-velocity are affected by the vortex induced effects in the boundary condition. Second, the pressures calculated subsequently by subroutine SPECPR of program DEMON2 at points on the fins contain all induced velocity components from the external vortices. Further discussion of fin pressures can be found at the end of this description. Pressures as calculated by subroutine BDYPR at the control points of the constant u-velocity panels on the body interference shell also include contributions from the external vortices and their images for the body alone as calculated by program VPATH2.

Equations (1) through (5) form a set of simultaneous equations from which the unknown constant u-velocity panel strengths can be solved. The number of unknown in the set of simultaneous equations is given by NWBP. The matrix solution is performed by subroutines LINEQS and SOLVE in program DEMON2. Constant u-velocity panel strengths are expressed in terms of the axial perturbation velocity component $\frac{1}{\pi} \frac{u^+}{V_\infty}$. It has a constant value for all points in the constant u-velocity panel.

3.5 Nose Vortex Characteristics

For configurations involving body noses with circular cross section, program DEMON2 is now equipped to determine body nose vortex characteristics up to the cruciform canard section from a data base built into subroutine BDYVTX. The data base is extracted from the compiled experimental data displayed in figure 5 of reference 4. The shed vorticity is represented by two concentrated symmetrical vortices whose strengths and positions in the cross flow plane are given as a function of axial distance from the nose. The separation distance, $x_{B,s}$, measured from the nose is obtained from either equation (5), reference 4, for sharp noses or equation (6), reference 4, for noses with cone semi-apex angles in excess of 30° .

The vorticity characteristics are to be determined at some axial distance from the nose, x_B . The axial location aft of the separation point is nondimensionalized by the body radius at the base of the nose designated RB in subroutine BDYPR. This subroutine calls subroutine BDYVTX and computes the pressure distributions on the body nose (and the portion of the body between the canard and tail fin regions). In subroutine BDYVTX, the nondimensionalized axial distance is multiplied by $\sin \alpha_c$, where α_c is the included angle of attack, and the result is named XPAR. This subroutine then proceeds to interpolate in a table containing a finite set of values for the axial distance parameter called XST.

$$XST = \frac{x_B - x_{B,s}}{r_b} \sin \alpha_c \quad (6)$$

Vortex strengths are designated GAMT and are nondimensionalized by the free-stream velocity V_∞ and the local body radius, a , which is a function of axial distance. As a function of the axial parameter XST, the table contains values for GAMT taken off the lower curve of figure 5(a) in reference 4.

$$GAMT = \frac{\Gamma_B}{2\pi a(x_B) V_\infty \sin \alpha_c} \quad (7)$$

This curve contains data for both supersonic and subsonic speeds. The coordinates in the cross flow plane are also divided by the local body radius with z_V aligned with the component of the free stream in the

cross flow plane and y_V normal to it, positive to the right. The tables in subroutine BDYVTX contain y_V coordinates for both subsonic and supersonic flow conditions denoted YA1 and YA2, respectively. The latter is used here. Only one set is given for the z_V coordinate designated ZA1.

$$\left. \begin{aligned} \text{YA2} &= \frac{y_V}{a(x_B)} \Big|_{\text{supersonic}} \\ \text{ZA1} &= \frac{z_V}{a(x_B)} \end{aligned} \right\} \quad (8)$$

Thus, for a given axial distance from the nose, x_B , ahead of the forward lifting surface region, the vortex strengths and positions are determined by interpolation from the table shown below.

XST	GAMT	YA2	ZA1
0	0.3	0.63	1.14
1.0	0.32	0.64	1.26
2.0	0.34	0.663	1.38
3.0	0.40	0.665	1.5
4.0	0.48	0.678	1.615
5.0	0.62	0.69	1.73
6.0	0.77	0.70	1.84
7.0	0.90	0.715	1.95
8.0	1.0	0.725	2.05
9.0	1.08	0.735	2.14
10.0	1.15	0.74	2.20

The coordinates y_V/a and z_V/a obtained from the above table by interpolation for given x_B are transformed into the body fixed coordinate system by a rotation through angle of roll ϕ . This process is performed in subroutine BDYPR and it is followed by a call to subroutine VRTVEL to calculate all velocity components induced by the separation vortices at points on the axisymmetric body at axial location x_B . These velocity components are then combined with the velocity components induced by the line sources/sinks and line doublets of the body of revolution itself for the purpose of determining the pressure distribution, as described below.

3.6 Pressure Distribution Calculations

The resultant velocity at a point on the body surface, including effects of free stream, is given by

$$\frac{V_R}{V_\infty} = 1 + \frac{2u}{V_\infty} \cos \alpha_c - \frac{2v}{V_\infty} \sin \alpha_c \sin \phi + \frac{2w}{V_\infty} \sin \alpha_c \cos \phi + \frac{u^2 + v^2 + w^2}{V_\infty^2} \quad (9)$$

where flow angle α_c is the included angle of attack and ϕ is the angle of roll. This result is obtained by applying the pitch-roll transformation shown in table 1-2 of reference 8 to the velocity components (u, v, w) aligned with the body coordinate system (x_B, y_B, z_B). The resultant velocity calculated in subroutine BDYPR using equation (9) is then substituted into the Bernoulli pressure-velocity relationship repeated here for convenience.

$$C_P = \frac{p - p_\infty}{q_\infty} = \frac{2}{\gamma M_\infty^2} \left\{ \left[1 + \frac{\gamma-1}{2} M_\infty^2 \left(1 - \frac{V_R^2}{V_\infty^2} \right) \right]^{\frac{\gamma}{\gamma-1}} - 1 \right\} \quad (10)$$

The pressure coefficient has the limiting value corresponding to vacuum pressure ($p = 0$) so that it is equal to

$$C_{P_{\min}} = \frac{-2}{\gamma M_\infty^2} \quad (11)$$

The above pressure calculations at points on the surface of an axisymmetric body are performed by subroutine BDYPR of program DEMON2. For the parts of the body covered by the interference shell, the pressures are calculated by program BDYPR also in the same manner using ENTRY BDYAFT. The resultant velocity calculated by means of equation (9) then includes contributions from the constant u -velocity panels on the fins and interference shell in addition to the contributions from the body line singularities and external vortices when applicable. Pressures on the fin are also computed with the Bernoulli pressure equation (10). The velocity component contains contributions from the constant u -velocity panels distributed over the fins and interference shell, contributions from the body singularities and external vortices where applicable. Special care

must be taken in the calculation of the discontinuous velocity components immediately above and below the control points of the constant u-velocity panels on the fins. In subroutine SPECPR of program DEMON2, they are related directly to the strength of the panel under consideration.

Some comparisons with measurements are given in the results comparisons, section 7, for the case of an ogive cylindrical body without body nose vorticity. These comparisons serve to test the body modeling method and the pressure expression used.

In determining the effect of the canard vortices on the pressure distribution, it is first necessary to establish the strength and position at the canard fin trailing edges. This is accomplished as described in Appendices B and C. The vortices are tracked back to the empennage using a vortex tracking program based on slender-body theory. The velocities included in this calculation are described in Appendix I.

4. DETAILED APPROACH FOR ELLIPTICAL BODY WITH MONOPLANE WING AND INTERDIGITATED CRUCIFORM TAIL

This section of the report gives a short description of the method using body source panels to represent a body with elliptical cross sections at combined angle of pitch and sideslip. Extensions to the flow tangency conditions are pointed out. The method used to include effects of specified body nose vorticity is described. The flow angles and the velocity components used in the pressure expression are given. Figure 2 shows a body source panel layout for a body with elliptical cross sections.

4.1 Modeling of Monoplane Wing, Interdigitated Tails and Elliptical Body by Body Source Panels

Basically, the layout of constant u-velocity panels on the monoplane wing or interdigitated tails is performed in the same way as for cruciform fins by subroutine LAYOUT of program DEMON2. For interdigitated tails, additional geometric transformations are required to express panel corner coordinates and induced velocities in the reference coordinate system which can be either the body (x_B, y_B, z_B) or wing (x_W, y_W, z_W) coordinate system shown in figure 1. These transformations are discussed in Appendix D. At the present time thickness effects are included only for the monoplane wing using planar source panels mentioned earlier in connection with cruciform fins. Program DEMON2 has been extended to allow for an interference shell with elliptical cross section. The

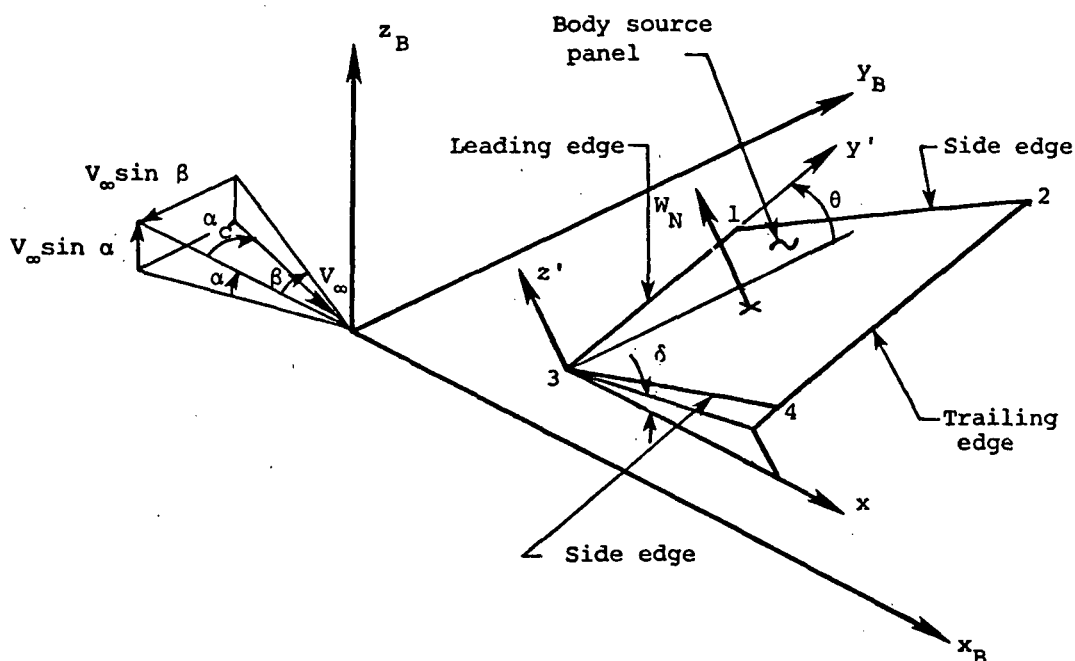
additional analysis required with regard to the load calculation is given in Appendix G concerned with body interference panels on a shell with elliptical cross section. As far as the attitude of a given body interference panel is concerned, the angle between the panel trailing edge and the y_B or y_W axis is now calculated in accordance with the expressions for $\theta_{2,BIP}$ shown in figure 3. This angle is used in the transformation from the body interference panel coordinate system to the wing or body reference coordinate system (and vice versa) as performed by subroutine TRBIPW of program DEMON2.

The body itself with elliptical cross section is modeled by program WDYBDY using supersonic body source panels which can be inclined to the flow. A typical layout of body source panels on a body with elliptical cross section is shown in figure 2. The angle of inclination between a body source panel and the body centerline is limited to the semi-apex angle of the Mach cone associated with the free-stream Mach number. Thus, there is a limit to which body noses can be modeled by the body source panel method. The solution for such a panel is based on supersonic, linear theory as described in reference 9. As is the case for constant u-velocity panels, the influence of one body source panel (not to be mistaken for the planar source panel used to model fin thickness) is also obtained by summing the influences of the four panel corners. The basic expressions for perturbation velocity components are given on page 35 of the cited reference. Program WDYBDY consists of body modeling subroutines extracted from the computer program described in reference 10 and modified to account for combined angles of pitch and sideslip. The subroutines affected by this modification are SOLVE, PRESS, and FORMOM in program WDYBDY. The specific modifications will now be described.

Angle of pitch, α , and angle of sideslip, β , are related to the included angle of attack, α_c , and angle of roll, ϕ (positive right fin or wing down), in accordance with the pitch-roll sequence described in reference 8, Table 1-2. As a result, the pitch and sideslip angles are determined from the following expressions.

$$\left. \begin{aligned} \sin \alpha &= \sin \alpha_c \cos \phi \\ \sin \beta &= \sin \alpha_c \sin \phi \end{aligned} \right\} \quad (12)$$

The orientation angles, δ and θ , associated with an inclined body source panel and the flow angles, α and β , are shown in the sketch below. Also indicated are the local coordinate systems x', y', z' associated with the source panel and the reference coordinate system x_B, y_B, z_B . The orientation angles δ and θ are shown in their positive sense if the panel corner numbering sequence is as indicated in the sketch. Axis x' is aligned with x_B .



In subroutine SOLVE of program WDYBDY, the contribution from the free stream to the flow tangency condition has been modified to include components due to pitch and sideslip. The component from the free stream normal to the body source panel inclined at angle δ to the x', y' plane and inclined to the $z_B = 0$ plane at angle θ is expressed below. This quantity is designated W_N/V_∞ and is programmed as NB(I) in subroutine SOLVE.

$$\frac{W_N}{V_\infty} = \sin \alpha \cos \theta \cos \delta + \sin \beta \sin \theta \cos \delta - \cos \alpha_c \sin \delta \quad (13)$$

With the contribution from the free stream given by the above equation, the flow tangency condition is applied at the control points (centroids) of the body source panels. The result is a set of simultaneous equations from which the panel strengths are obtained. The matrix solution is an iterative one if the number of source panels is in excess of 60.

4.2 Pressures, Forces, and Moments on Body with Elliptical Cross Section

The pressure coefficient is computed at the body source panel control points by subroutine PRESS in program WDYBDY using the Bernoulli pressure-velocity relationship, equation (10). In subroutine PRESS the resultant velocity V_R was originally determined from the velocity components in the wind-axis system for the unrolled case. Using the transformations indicated in Table 1-2 of reference 8 for the combined pitch and roll case, the components in the wind-axis system $(\bar{u}, \bar{v}, \bar{w})$ are related to the components (u, v, w) aligned with the body axis system (x_B, y_B, z_B) as follows.

$$\left. \begin{aligned} \frac{\bar{u}}{V_\infty} &= \frac{u}{V_\infty} \cos \alpha_c - \frac{v}{V_\infty} \sin \beta + \frac{w}{V_\infty} \sin \alpha \\ \frac{\bar{v}}{V_\infty} &= \frac{v}{V_\infty} \cos \phi + \frac{w}{V_\infty} \sin \phi \\ \frac{\bar{w}}{V_\infty} &= -\frac{u}{V_\infty} \sin \alpha_c - \frac{v}{V_\infty} \cos \alpha_c \sin \phi + \frac{w}{V_\infty} \cos \alpha_c \cos \phi \\ \frac{V_R^2}{V_\infty^2} &= \left(\frac{\bar{u}}{V_\infty}\right)^2 + \left(\frac{\bar{v}}{V_\infty}\right)^2 + \left(\frac{\bar{w}}{V_\infty}\right)^2 \end{aligned} \right\} \quad (14)$$

The last quantity is denoted Q2 in subroutine PRESS of program WDYBDY. The angles associated with the trigonometric functions are described in connection with equation (12).

In order to add the capability of including effects from specified body nose vorticity in the body pressure calculation, program WDYBDY is equipped with additional subroutines. Subroutine READVX reads in an array of axial locations measured from the body nose, ELBDVT reads arrays containing the lateral coordinates and strengths of the vortices. For the axial location of a given control point in a body source panel, these subroutines interpolate for the coordinates in the cross flow plane and strengths of the vortices. Subroutine VVELS then proceeds to compute the velocity components induced by the set of external vortices and their images inside of an elliptical cross section at the control point. This application of slender-body theory is a degenerate form of one of the

crossflow plane solutions described in Appendix I in connection with vortex path calculations. The flow tangency condition at the body surface is therefore satisfied and the body source panel strengths are not affected. The vortex induced velocities are calculated in the body reference coordinate system and added to the v and w velocity components in equation (14). In connection with the application of slender-body theory to elliptical cross sections, a special procedure is followed to avoid numerical problems leading to unrealistic values for the velocity components at the body source panel control points. Essentially, the control points are moved just outside the actual body circumference as described in detail in Appendix H.

Once the pressures on the body are known, subroutine FORMOM, as applied to the body modeling program WDYBDY, computes the overall forces and moments acting on a body with elliptical cross section. This subroutine was extended to include calculating the side force and yawing moment for the pitched and rolled case. First, a normal-force "coefficient" is defined* for one body source panel as follows.

$$C_N \Big|_{\text{panel}} = - C_P \text{ Area} \Big|_{\text{panel}} \quad (15)$$

By first resolving through the panel inclination angle δ and then through the azimuthal orientation angle θ , the forces on the panel expressed in the body coordinate system (x_B, y_B, z_B) indicated in figures 1 and 2 are given by

$$\left. \begin{aligned} C_{x_B} \Big|_{\text{panel}} &= - C_N \Big|_{\text{panel}} \sin \delta \\ C_{y_B} \Big|_{\text{panel}} &= - C_N \Big|_{\text{panel}} \cos \delta \sin \theta \\ C_{z_B} \Big|_{\text{panel}} &= C_N \Big|_{\text{panel}} \cos \delta \cos \theta \end{aligned} \right\} \quad (16)$$

Angles δ and θ are shown in the sketch discussed above.

The contributions from one body source panel to the moments are determined as follows. The pitching and yawing moments are first calculated in terms of the body coordinate system. In this way, the pitching-moment vector is normal to the $y_B = 0$ plane and the yawing-moment vector

* Normal force per unit dynamic pressure.

is normal to the $z_B = 0$ plane. Rolling-moment vector lies along the x_B axis. For one body source panel, the contribution to the pitching-moment coefficient in the body coordinate system is stated below.

$$C_m \Big|_{\text{panel}} = - C_{z_B} \Big|_{\text{panel}} (x_{C,B} - XM) + C_{x_B} \Big|_{\text{panel}} (z_{C,B} - ZM) \quad (17a)$$

nose up positive

The contribution to yawing moment in the body coordinate system is given by

$$C_n \Big|_{\text{panel}} = - C_{y_B} \Big|_{\text{panel}} (x_{C,B} - XM) + C_{x_B} \Big|_{\text{panel}} y_{C,B} \quad (17b)$$

nose to right positive

and the contribution to rolling moment in the body coordinate system is written as

$$C_l \Big|_{\text{panel}} = - C_{z_B} \Big|_{\text{panel}} y_{C,B} + C_{y_B} \Big|_{\text{panel}} (z_{C,B} - ZM) \quad (17c)$$

right fin down positive

In the above equations, $(x_{C,B}, y_{C,B}, z_{C,B})$ are the coordinates of the centroid or control point of the body source panel. The moment center is given by $(XM, 0, ZM)$ in the body coordinate system. In subroutine FORMOM, the quantities defined by equations (16) and (17) are designated DCXB, DCYB, DCZB and DCMB, DCNYAW, DCLROL, respectively. The contributions to the forces from all the panels are then added and divided by a reference area designated REFA. The contributions to the moments are also added and divided by reference area REFA and reference length REFD.

For the pitched and rolled case, an additional transformation is performed in subroutine FORMOM to finally determine the forces and moments in the wind-axis system. Thus, let $C_z \Big|_{\text{wind axis}}$ be in the plane formed by the body centerline and the free-stream velocity vector and lie

in the direction normal to that vector. This quality is in fact the lift in coefficient form acting on the body and it is obtained by applying the body to wind axis transformation indicated on page 12 of reference 8.

$$C_L = C_z \Big|_{\text{wind axis}} = -C_{x_B} \sin \alpha_c - C_{y_B} \cos \alpha_c \sin \phi + C_{z_B} \cos \alpha_c \cos \phi \quad (18a)$$

Let $C_y \Big|_{\text{wind axis}}$ be the force normal to the plane formed by the body centerline and the free-stream vector, positive to the right.

$$C_y \Big|_{\text{wind axis}} = C_{z_B} \sin \phi + C_{y_B} \cos \phi \quad (18b)$$

The axial force in the wind axis system, $C_x \Big|_{\text{wind axis}}$, lies along the free-stream vector. It equals the drag-force coefficient C_D .

$$C_D = C_x \Big|_{\text{wind axis}} = C_{x_B} \cos \alpha_c - C_{y_B} \sin \alpha_c \sin \phi + C_{z_B} \sin \alpha_c \cos \phi \quad (18c)$$

In the wind axis system, the pitching-moment vector is normal to the plane formed by the free-stream vector and the body centerline, positive nose up. The pitch-roll transformation is applied again to the moments in the body axis system.

$$C_m \Big|_{\text{wind axis}} = C_m \Big|_{\text{body axis}} \cos \phi - C_n \Big|_{\text{body axis}} \sin \phi \quad (19a)$$

The yawing-moment vector in the wind axis system lies in the direction of the lift force, positive nose right.

$$C_n \Big|_{\text{wind axis}} = -C_\ell \sin \alpha_c + C_m \Big|_{\text{body axis}} \cos \alpha_c \sin \phi + C_n \Big|_{\text{body axis}} \cos \alpha_c \cos \phi \quad (19b)$$

In equations (18) and (19), angles α_c , ϕ , α and β are discussed above in connection with equation (12). They are designated ALPHAC, PHIR, ALPHA and BETA, respectively, in subroutines FORMOM, SOLVE and PRESS of program WDYBDY.

4.3 Wing-Body and Tail-Body Interference

Once the body with elliptical cross section is modeled by program WDYBDY for given included angle of attack, α_c , angle of roll, ϕ , and Mach number, the velocity components induced by the body source panels with known strengths are computed at the control points on the monoplane wing or interdigitated tail fins by an added subroutine BDYVEL of program WDYBDY. In this way, body to wing or fin interference is accounted for. This is accomplished by interchanging data sets between programs WDYBDY and DEMON2. Note that for axisymmetric bodies, program DEMON2 performs both the body modeling and fin modeling and no such data set exchange is required.

For the monoplane wing attached to the interference shell, the flow tangency condition for the right wing is given by equation (1). If the configuration is rolled in addition to pitched, the flow tangency condition must also be set up for the left wing, equation (2). The flow tangency condition applied at the control points of the constant u-velocity panels in the interference shell with elliptical cross section is given by equation (5). This boundary condition accounts for wing or fin on body interference. The strengths of the constant u-velocity panels distributed over the monoplane wing and the interference shell with elliptical cross section are then solved from the set of simultaneous equations generated by the flow tangency condition. Effects of external vorticity can be included in the wing boundary condition by exchanging data sets between programs DEMON2 and VPATHL. The latter program determines the paths of the body nose vortices as they pass through the monoplane wing section up to the tail section. It also computes velocity components induced at the control points of the constant u-velocity panels on the monoplane wing by the external (body nose) vortices in the presence of the body only. In this way the monoplane wing is influenced by the external vorticity in the boundary condition and in the calculation of pressures acting on the wing as performed by subroutine SPECPR in program DEMON2. The reason for this procedure is increased accuracy as mentioned in the previous section 3.4 concerned with cruciform fins on an axisymmetric body.

5. PROCEDURE FOR APPLICATION OF PROGRAMS TO COMPLETE CONFIGURATIONS

5.1 Circular Body with Cruciform Canard and Tail Fins

The following is a description of the step-wise use of programs DEMON2 and VPATH2 for handling a complete configuration with a body of circular cross section. The manner in which the programs are used sequentially and the exchange of data sets are indicated. The first three steps are concerned with the part of the configuration from the body nose to the trailing edge of the canard section. The remaining steps deal with the body aft of the canard and with the cruciform tail-fins. Finally, the procedure required to assemble pressure distributions acting on the entire configuration is given. The steps at which fin forces and moments are calculated are also indicated.

5.1.1 Sequential use of programs

- Step 1(a). Run lifting-surface program DEMON2, with index NCPOUT set equal to 2 in namelist INPUT. This step generates the coordinates of the control points associated with the constant u-velocity panels distributed on the fins of the cruciform-canard and the body-interference shell. The number of control points and the sets of coordinates are stored in a data set designated TAPE4 = CPTS1. There are NWBP sets of coordinates where NWBP is the number of control points on the canard fins and the interference shell. This shell has constant circular cross-sectional area and covers the body from the leading-edge to the trailing-edge of the canard section. This step can be combined with step 1(b) discussed next by setting NCPOUT equal to 1 instead of 2.
- Step 1(b). Consider the canard fins mounted on the body. The body is modeled from its nose to the trailing edge of the canard fin as a minimum. Run lifting-surface program DEMON2 with index NCPOUT set equal to zero in namelist INPUT. This step can be combined with step 1(a) by setting NCPOUT = 1. If the latter value is used, the program not only generates the data set containing the control point characteristics, CPTS1, but will also proceed to compute the pressure distributions on the

body nose up to the canard section. If the included angle of attack is sufficiently high, the effects of body nose vorticity will be accounted for in the body pressures. In addition, the strengths of the constant u-velocity panels and subsequently the pressure distributions and loadings acting on the canard fins and interference shell are calculated without the effects of body nose vorticity. The output includes information concerning fin leading- and side-edge separation vorticity.

Step 2. Vortex path program VPATH2 is now employed to track the body nose vortices over the canard section. Input includes the data set designated CPTS1 containing the number and sets of coordinates of the control points on the cruciform canard fins and interference shell. This data set was generated in either step 1(a) or 1(b). In the input to program VPATH2, indices NCPIN and NVLOUT are set equal to 1 for this run. The former causes data set CPTS1 to be read in and the latter generates a data set designated VELOS1. The input to this program also includes the strengths and coordinates in the crossflow plane of the body nose vortices at the axial station corresponding to the start or leading edge of the canard section. These vortices are tracked back to the end or trailing edge of the canard section. Effects of fin edge vorticity (kept stationary) can be included in the determination of the paths of the body nose vortices. Fin leading- and side-edge vortex strengths (if comparable in magnitude to the body nose vortices) and locations are read-in by the program separately from the input associated with the vortices whose paths and effects are to be calculated.

After the vortex paths have been calculated, program VPATH2 calculates the perturbation velocities induced by the body nose vortices at the control points of the canard fins and interference shell. The velocity components are stored in data set TAPE7 = VELOS1 mentioned earlier. In this velocity calculation, the effects of the vortices are calculated in the presence of the body only, or in other words as if the canard fins are not present.

Step 3. Program DEMON2 is run again with NVLIN = 1 and NCPOUT = 0 in namelist INPUT. The value of the first index tells the program to read in velocity components induced by the body nose vortices at the control points on the canard fins and the interference shell as the vortices pass by the canard section. This information was generated in step 2 by program VPATH2 and stored in data set TAPE7 = VELOS1. The strengths of the constant u-velocity panels are then recalculated including the effects of the external body nose vortices. As a result of this calculation, the pressure distributions, forces and moments on the canard fins and pressures on the body aft of the leading edge of the canard root chord include effects induced by the body nose vortices.

At this stage, the output also contains specifications for the concentrated vortices associated with the fin trailing edges. Specifications calculated on the basis of Bernoulli-type loading pressures will be used in a later step. Furthermore, the distributions of fin leading- and side-edge vorticity calculated on the basis of linear (u/V_∞ type loading pressure) theory will be considered in the calculations that follow.

Step 4. Program DEMON2 is applied to treat the tail fin section mounted on the body. The body is modeled from the nose to its base. In this step, effects of external vortices are not accounted for. Index NCPOUT = 1, NVLIN = 0 and ITAIL = 1 in namelist INPUT for this run. In addition, quantity XSTART must be set equal to the axial location of the trailing edge of the canard section.

The first index causes the program to generate a data set designated CPTS2 which contains the number and sets of coordinates associated with control points on the tail fins and interference shell. Additionally, this data set contains the sets of coordinates specifying points on the body surface between the canard and tail section at which pressures will be calculated. At this stage, the calculated pressures on the body do not include effects of external vorticity. The tail fin loadings do not include effects of body nose and canard fin vorticity so far.

Step 5.

The vortex path program VPATH2 is now used to chase external vortices from the canard section, along the aft body, past the tail section, to the body base. Index NCPIN = 1 and NVLOUT = 1 for this run. The value given to the first index causes the program to read in data set CPTS2 containing control and body pressure points. Velocity components induced by the external vortices are calculated at the points whose coordinates are in data set CPTS2. The value given to the second index results in the generation of data set TAPE7 = VELOS2 which contains the induced velocity components. The strengths and positions of the vortices at the trailing edge of the canard section as required by the input to program VPATH2 for this run include the following:

1. Body nose vortices whose characteristics are available at the trailing edge of the canard section as a result of step 2 calculated by program VPATH2.
2. Concentrated vortices emanating from the trailing edges of the canard fins. Strengths and locations of these vortices are available from the results (based on Bernoulli pressures) generated by program DEMON2 at the end of step 3.
3. Fin leading- and side-edge separation vortices, if their strengths are comparable to the strengths of the vortices of 1 and 2. Their strengths and spanwise positions (based on linear pressures) at the fin trailing edge are also calculated by and appear in the output of program DEMON2. The user may input a distance off the fin plane equal to the product of the root chord and the tangent of half the angle of attack seen by the fin in question.

After the paths of the above vortices are calculated, program VPATH2 proceeds to compute their effects at points on the aft body and on the tail section as mentioned above. In this process, the velocity components induced by the external vortices are calculated in the presence of the body only, or in other words as if the tail fins are not present.

Step 6. Finally, program DEMON2 is applied again to the tail fins on the body. Index NCPOUT = 0, NVLIN = 1 and ITAIL = 1. The program reads in data set TAPE7 = VELOS2 which contains vortex effects calculated in the previous step at points on the aft body and the tail section including the fins.

The strengths of the constant u-velocity panels are recalculated including the effects of body- and canard-fin vortices. As a result of this calculation, the pressure distributions, forces and moments acting on the tail fins and the pressure distributions on the body from the canard section to the body base are affected by the body and canard fin vortices.

5.1.2 Assembly of pressure, force and moment data

The results obtained in the stepwise manner described above allow for the determination of the pressure distributions on the body and forces and moments acting on the fins as follows.

Nose section: $0 < x_B < x_{B,WLE}$

At the end of step 1, the output of program DEMON2 includes circumferential pressure distributions at a finite number of axial stations from the nose tip to the leading edge of the canard section. From this information, meridional pressure distributions can also be obtained. Effects of body nose vorticity are accounted for in the velocity components used to compute Bernoulli pressures.

Canard section: $x_{B,WLE} < x_B < x_{B,WTE}$

Pressure distributions on the body aft of the leading edge of the fin root chords (up to the trailing edge) and on the fins are calculated by program DEMON2 in step 3. The results include effects of body nose vorticity. Normal forces and moments acting on the fins including the influence of body nose vorticity are also calculated and output by the program (refer to quantities under Bernoulli-type loading pressures). Any augmentation to the fin normal force due to fin leading- and side-edge separation can be determined from the following hand calculation

using the quantities printed under the U/VINF (linear) type loading pressure. Consider the right horizontal fin (the other fins are treated the same way).

$$C_N|_{LE} + C_N|_{SE} = K_{LE} C_S|_{LE} + K_{SE} C_S|_{SE} \quad (\text{Polhamus' Analogy})$$

If K_{LE} and K_{SE} are not input, then the following values are used in obtaining vortex strengths:

$$K_{LE} \cong 0.5; K_{SE} \cong 0.5 \quad (\text{default value})$$

$$C_S|_{LE} = [(\text{SUMFX})^2 + (\text{SUMFY1} + \text{SUMFY2})^2]^{\frac{1}{2}}$$

$$C_S|_{SE} = \text{SUMFT2}$$
(20)

In the above SUMFX is the sum of all the forces acting upstream in the plane of the fin. For example, if NRP equals the number of constant u-velocity panels on the right horizontal fin

$$\text{SUMFX}|_{\text{Right hor. fin}} = \sum_{n=1}^{\text{NRP}} \frac{\Delta F_{x,n}}{q} \quad (21)$$

The axial in-plane force ΔF_x for one panel is shown in the second sketch of Appendix C. In-plane side force ΔF_{y1} is also indicated and

$$\text{SUMFY1} = \sum_{n=1}^{\text{NRP}} \frac{\Delta F_{y1,n}}{q} \quad (22)$$

The in-plane side force ΔF_{y2} acting at the outboard aft corner is also shown in the second sketch of Appendix C. For all the panels on the fin except those at the tip chord

$$\text{SUMFY2} = \sum_{n=1}^{\text{NRP}-\text{NCW}} \frac{\Delta F_{y2,n}}{q} \quad (23)$$

where NCW is the number of panels along the chord. Then by adding the contributions from the panels at the tip

$$\text{SUMFT2} = \sum_{n=\text{NRP}-\text{NCW}+1}^{\text{NRP}} \frac{\Delta F_{y_2,n}}{q} \quad (24)$$

Section behind canard section: $x_{B,WTE} < x_B < x_{B,TTE}$

Pressure distributions on the aft body from the canard section up to the tail section are calculated in step 6 using program DEMON2. From the leading edge of the tail section to the trailing edge (assumed to be at the same axial location as the body base), the pressure distributions on the body appear under the heading AFT OF LEADING EDGE OF FIN ROOT CHORDS . Normal forces and moments acting on the tail fins including influence of body nose and canard vorticity are also calculated and printed by the program (refer to quantities under Bernoulli-type loading pressure). Any augmentation to the fin normal force due to fin leading- and side-edge separation can be determined from the hand calculation discussed earlier in connection with the canard fins, equations (20) through (24).

5.2 Elliptic Cross Section Body-Monoplane Wing-Interdigitated Tail Fins

The following is a description of the stepwise use of programs DEMON2, WDYBDY and VPATHL for handling a complete configuration with a body of elliptical cross section. The manner in which the programs are used sequentially and the exchange of data sets are indicated. The first five steps are concerned with the part of the configuration from the body nose to the trailing edge of the monoplane wing. The remaining steps deal with the body aft of the monoplane wing section and with the tail fins. Finally, the procedure required to assemble pressure distributions and overall forces and moments acting on the entire configuration is indicated.

5.2.1 Sequential use of program

Step 1. Run lifting-surface program DEMON2 with index NCPOUT = 2 in namelist INPUT. This run generates the coordinates of the control points associated with the constant u-velocity panels

distributed on the monoplane-wing and the body-interference shell. The number of control points and the sets of coordinates are stored in a data-set designated TAPE4 = WCPTS. There are NWBP coordinates where NWBP equals the number of control points on the monoplane wing and the interference shell. This shell has constant elliptical cross section and covers the body from the leading edge to the trailing edge of the monoplane wing.

- Step 2. Run body source panel program WDYBDY for the elliptical body alone with index NCWPT = NWBP in the input. This causes the data set containing control point coordinates designated TAPE4 = WCPTS to be read in. The body length should extend at least up to the trailing edge of the monoplane wing if the trailing edge is supersonic. If this edge is subsonic, the body length should extend past the monoplane wing section in order to account fully for body-wing interference. This program can also read in forebody separation vorticity characteristics calculated by a separate program mentioned in section 2 entitled GENERAL APPROACH. Results of this run include pressure distributions along body meridians up to the wing section including effects of body nose vorticity if applicable. In addition, perturbation velocities induced by body source panels alone at the specified control points are calculated. These velocities are stored in another data set designated TAPE4 = WVELS and passed to program DEMON2.
- Step 3. Program DEMON2 is run again for the monoplane wing/elliptical interference shell with NCPOUT = 0 and NVLIN = 0 in the name-list INPUT. The program proceeds to calculate the constant u-velocity panel strengths including the effects induced by the body source panels. Output includes the strength and lateral positions of the leading- and side-edge vorticity associated with the monoplane wing as a function of axial location. So far, effects of body nose vortices have not been included.
- Step 4. Run program VPATHL with indices NVLOUT = 1 and NCPIN = 1 in the input. It is applied to the monoplane wing/elliptical cross section body. The axial starting point is at the leading edge of the monoplane wing rootchord. Vortices to be

tracked to the trailing edge are the body nose vortices whose strengths and positions are known at the leading edge of the monoplane wing root chord from results obtained with a separate program. The effects of wing leading- and side-edge vorticity (kept stationary) can be included in the calculation of the paths of the body nose vortices. The values given to the indices NCP and NCPIN causes program VPATHL to read in data set TAPE4 = WCPTS containing coordinates of the control points distributed on the monoplane wing and interference shell. After the body nose vortex paths have been calculated, perturbation velocities induced by the body nose vortices at the control points are computed and stored in data set TAPE7 = VRTVEL. In this velocity calculation, the effects of the vortices are calculated in the presence of the elliptical body only.

Step 5. Use program DEMON2 again with indices NVLIN = 1 and NCPOUT = 0 in the namelist INPUT. The value of the first index tells the program to read in velocities induced by the body nose vortices at the control points on the wing and interference shell as the vortices pass by the wing section. This information is stored in data set TAPE7 = VRTVEL. The strengths of the constant u-velocity panels are then recalculated including the effects of the external body nose vortices, and the body itself. The output includes pressure distributions on the monoplane wing and the length of body spanned by the wing section accounting for all vortices. In addition, strengths and positions of the trailing-edge vorticity of the monoplane wing are calculated from the spanwise load distributions. At this stage, the configuration has been treated from the body nose up to the trailing edge of the monoplane wing section. Strengths and locations of the body nose vortices, wing leading- and side-edge vortices and wing trailing-edge vortices are now known at the end of the wing section.

Step 6. If the tail section is located aft of the wing section by some length of body, this and the following step must be taken in order to track body nose and monoplane wing vorticity along the body up to the tail fin section. Program WDYBDY is run for the elliptic body only to generate

coordinates of control points associated with the source panels laid out from the wing section to the tail section. These coordinates are stored in another data set designated TAPE4 = BCPTS, which is passed to program VPATHL.

- Step 7. Program VPATHL is applied again to the elliptical body alone from the wing section to the tail section. If there is no body length between the wing rootchord trailing-edge and the tail fin rootchord leading-edge, this step is omitted. Vortices to be tracked over this length along the body include the body vortices, wing leading- and side-edge vortices and the wing trailing-edge vortices. Strengths and positions of these vortices are known at the monoplane wing trailing-edge location (see steps 4 and 5). Once the vortex paths have been determined, program VPATHL calculates the velocities induced by the vortices at the control points on the body passed through by means of data set TAPE4 = BCPTS generated by step 6. These velocities are to be passed back to program WDYBDY using data set designated TAPE7 = VRTVEB (step 9).
- Step 8. Program DEMON2 is applied to the interdigitated tails to generate the coordinates of the NWBP control points distributed on the fins and the interference shell. Index NCPOUT is set equal to 2 in namelist INPUT and the coordinates are stored in a data set designated TAPE4 = TCPTS. This step is essentially a repeat of step 1 applied to the tail fin in this instance.
- Step 9. The body program WDYBDY is applied to the entire body length of the configuration. Index NCWPT is set equal to NWBP, the number of control points on the tail fin and interference shell. As in step 2, a data set designated TAPE4 = TCPTS containing control points is read in. Velocities induced by the body source panels at the control points are calculated by program WDYBDY. They are stored in a data set designated TAPE4 = TVELS to be passed back to program DEMON2. In addition, by setting index NVLIN = 1 in the input to program WDYBDY, data set TAPE4 = VRTVEB generated in step 7 is read in. It contains velocities induced by external body and wing

vortices. Their effects are included in the calculation of pressure distributions on the body from the wing section trailing edge to the leading edge of the tail fins. If there is no body length between these two stations, no such pressure distributions are calculated.

Step 10. In this final step, program DEMON2 is applied to the interdigitated tail fins with NCPOUT set equal to zero. This index signals the program to read in the body source panel induced velocities stored on data set TAPE4 = TVELS. For any case involving interdigitated fins, set NDRAG equal to zero. Strengths and positions of forebody vorticity, wing leading-, side- and trailing-edge vorticity are known at the leading edge of the tail section as a result of step 7, or 5 if there is no body length separating the wing and tail sections. Their influences are calculated at the tail fin control points assuming that the vortex paths are not disturbed by the presence of the fin surfaces. Pressure distributions are calculated on the fins and the part of the body spanned by the tailfin section. In addition, forces and moments acting on the fins are computed.

5.2.2 Assembly of pressure, force and moment data

The results obtained in the stepwise manner described above allow for the determination of the pressure distributions and overall forces and moments acting on the entire configuration by adding those calculated for the separate sections as follows.

Nose section: $0 < x_B < x_{B,WLE}$

Pressure distributions along body meridians, normal- and side-force, pitching- and yawing-moment contributions are calculated by program WDYBDY up to the leading-edge of the monoplane wing root chord. This is accomplished by step 2. Forces and moments are referred to the body-axis system with x_B directed back along the centerline, y_B to the right along the horizontal semi-axis viewing forward and z_B upwards along the vertical semi-axis for an elliptical body. In this way, the normal force C_z points along the positive z_B direction and side force C_y

in the positive y_B direction. Pitching moment is measured in the $y_B = 0$ plane. If the pitching moment acts to bring the nose up in this plane, the sense of this moment is positive. Yawing moment is measured in the $z_B = 0$ plane. If this moment acts to move the nose into the positive y_B direction, the sense of this moment is positive.

Canard section: $x_{B,WLE} < x_B < x_{B,WTE}$

Pressure distributions along body meridians are calculated by program DEMON2 over this body section in step 5. Normal- and side-force, pitching- and yawing-moment contributions from this body section* and the monoplane wing are also computed as a result of step 5.

Section behind canard section up to tail fins (if applicable):

$x_{B,WTE} < x_B < x_{B,TLE}$

Over this length of body, the pressure distributions along body meridians are calculated by program WDYBDY as part of step 9. Normal- and side-force, pitching- and yawing-moment contributions are also computed. If there is no body length, $x_{B,WTE} - x_{B,TLE} \leq 0$, this part of the procedure is not applicable.

Tail section: $x_{B,TLE} < x_B < x_{B,TTE}$

Over this last body section, pressure distributions along body meridians are calculated by program DEMON2 in step 10. In addition, contributions to the normal- and side-force, pitching- and yawing-moment from this body section* and the tail fins are also calculated as part of step 10.

In general it is advantageous to let the number of source panels on the body circumference read into program WDYBDY match the number of circumferential constant u-velocity specified in namelist \$INPUT of program DEMON1. In this way, the meridians on which pressures are computed are essentially the same. Reference areas and lengths must be the same in the inputs to programs WDYBDY and DEMON2. Force and moment coefficients calculated for the individual sections of the entire configuration can then be added to obtain overall forces and moments.

* Note that force and moment coefficients associated with the interference shell as calculated by program DEMON2 are only representative of lift carryover from the lifting surfaces to the body; refer to Appendix J.

6. CALCULATIVE EXAMPLES

In this section, two sample cases will be described. The first concerns a configuration designated $B_1W_4T_4$ associated with UPWT Project 1126, for which unpublished data was made available by NASA/Langley. This model consists of a cruciform canard and a cruciform tail attached to a body with circular cross section. The second case involves a wind tunnel model consisting of a monoplane wing and interdigitated tail section mounted on a body with elliptical cross section described in reference 11. These models are used in the sample cases to illustrate the use of the computer program described in this report.

For both cases, first the procedures used to determine the effects of body nose vorticity on the forebody pressures are indicated. Second, canard or monoplane loadings are determined including effects of the body nose vorticity. Third, the calculated canard edge vortices and the body nose vortices are tracked back through the tail section for the first sample case. Finally, the tail fin loadings are calculated including effects of all vortices. Special care must be taken in the positioning of the interference shell around a body with elliptical cross section as will be discussed below.

References will be made to the steps listed earlier in section 5. The method used to hand calculate the augmentation to normal force due to wing edge vorticity is indicated in section 6.2.3.

6.1 Sample Case 1: Axisymmetric Body-Cruciform Canard-Cruciform Tail Fins

The configuration of a model including a body with circular cross section and an ogive nose is shown in figure 4. The cruciform canard and tail fins are identical and details of the bevelled sections are indicated. Programs DEMON2 and VPATH2 are used to treat this configuration rolled 45° and at included angle of attack of 14.216° . Under these conditions the angle of pitch and sideslip are both equal to 10° . The Mach number is 1.70. Note that there will be no symmetry with respect to the wing-axis system x_W, y_W, z_W in terms of aerodynamic loading. Thus, all fins must be modeled. However, there will be symmetry in loading with respect to the direction of the free-stream component in the cross-flow plane. In other words, the configuration is in the X-position

relative to that direction. This condition serves as a check on the programs. For example, the loads on the upper vertical and left horizontal fins, indicated in figure 4, must be equal. Likewise, the vortex paths must be symmetrically positioned relative to the free-stream velocity component in the crossflow plane.

6.1.1 Geometry and singularity layout

The following geometrical specifications and singularity distributions will be used for the axisymmetric body and fins. The specified numbers of singularities along the body centerline and on the fins may not be sufficient for precise calculated results but serve to generate this sample case. Refer to figure 4 for geometrical details.

Namelist \$BODY in subroutine BDYGEN of program DEMON2 includes specifications for the body:

number of line sources/sinks and line doublets, NXBODY = 39
nose length, LNOSE = 7.8
body length, LBODY = 39.0

The body radius for the cylindrical section, RB, is specified in the following.

Namelist \$INPUT in main routine CRFWBD of program DEMON2 includes specifications for either the canard or the tail fins and the corresponding body interference shell.

rootchord, CRP = CRPV = 3.6
exposed semi-span, B2 = B2V = 2.34
leading-edge sweep, SWLEP = SWLEV = 30.0°
trailing-edge sweep, SWTEP = SWTEV = 0.0°
number of constant u-velocity panels along a chord, NCW = 3
number of planar source panels along a chord, NCWT = 8
number of constant u-velocity panels along the span, MSWR = 5
(right horizontal fin)
MSWL = 5
(left horizontal fin)
MSWU = 5
(upper vertical fin)
MSWD = 5
(lower vertical fin)

number of planar source panels along the span is specified in
 subroutine THKIN of program DEMON2, MSWT = 5 for all fins
 length of body interference shell, BIL = 3.6
 radius of body interference shell, RB = 1.3
 number of body interference panels on the circumference
 (ring), NBDCR = 16
 number of body interference panel rings, NCWB = 3
 distance from body nose to leading edge of lifting surface
 section, XWLE = 19.8 for canard, XWLE = 35.4 for tail

The thickness slopes are read in by subroutine THETIN of program DEMON2
 and are determined as follows. The layout specified above for the planar
 source panels is shown by the thin lines superimposed on the fin planform
 in figure 4. At the centroid of each panel, the streamwise slope is to
 be specified. If the centroid lies on a bevelled portion of the fin, the
 streamwise slope equals the slope of the fin surface measured parallel to
 the fin rootchord. For centroids on the bevelled portion near the
 leading edge, the streamwise slope is given by

$$\text{THET} = \tan \theta_s = \frac{0.075}{0.6145} = 0.122 \quad (25)$$

On the unbevelled portion, the slope equals zero. Near the trailing
 edge, the streamwise slope equals

$$\text{THET} = \tan \theta_s = -\frac{0.075}{0.532} = -0.141 \quad (26)$$

Near the side edge, the streamwise slopes are chosen on the basis of the
 location of the source panel centroid on the fin. The above input
 parameters will be used in all runs with program DEMON2 described in the
 procedure for an axisymmetric body configuration, section 5.1.

6.1.2 Body nose vortices, pressure distributions on forebody

In accordance with step 1b described in section 5.1.1, program
 DEMON2 is run using the input data shown in figure 5. These data include
 the geometrical specifications and numbers of singularities laid out to
 represent the body-canard section of the complete configuration. The
 input data required by program DEMON2 is described in detail in Appendix
 J. Note that control index NCPOUT must be set equal to 1. The output of
 this run is shown in figure 6. It includes a printout of the data set,

designated CPTS1, containing the 108 sets of coordinates of the control points distributed over the canard fins and the interference shell. This data set will be used later. The output also includes pressure coefficients as a function of polar angle for 10 axial locations from the body nose. The polar angle is named THETA and is measured positive counter-clockwise from the positive y_B or y_W axis. The number of axial stations on the forebody at which the pressures are calculated is equal to one half of the body line singularities up to the canard section. Subroutine BDYVTX of program DEMON2 calculates the separation point to be at $x_B = 17.2$ inches or at about the fifth axial station. From that location on to the canard section, the shed vorticity is represented by two concentrated vortices growing in strength and moving in the crossflow plane in accordance with the data base built into subroutine BDYVTX.

The pressures acting on the forebody are calculated in subroutine BDYPR using the Bernoulli pressure expression, equation (10) in coefficient form. In terms of p/p_∞ , where p_∞ is the free-stream static pressure, the pressures are plotted in figures 7(a) and 7(b) as a function of axial distance x_B from the body nose for several polar angles. The solid line represents pressures including body vortex effects. Pressures computed without effects of body vorticity are indicated by the crosses. From the onset of the body vortex shedding modeled by two discrete vortices, the Bernoulli pressures include effects induced by the external vortices and their images inside the body. Along the symmetrically located meridians, at $\theta = 45^\circ$ and 225° on figure 7(a), the effect of the body vortices is to increase the pressures slightly. Note that the pressure distributions along these meridians are identical due to flow symmetry. However, the meridians at $\theta = 135^\circ$ and 315° , figure 7(b) show no effect from the body vortices. On account of flow symmetry, the vortices and their images inside the body induce zero lateral velocity components along these meridians. Thus, the pressures are not affected by the body nose vortices along these meridians.

At the leading edge of the canard section, the body nose vortices are fully developed. The paths of the vortices as they pass through the canard section will now be determined and the canard fin loadings calculated.

6.1.3 Pressures and loads acting on the cruciform canard-body section

The pressures, forces and moments acting on the fins and body covered by the interference shell excluding body nose vortex effects are available in the output of the run performed with program DEMON2 just described. To account for the body vortices requires knowledge of their lateral coordinates as a function of axial distance through the canard region. In accordance with step 2 of the procedure, section 5.1.1, vortex tracking program VPATH2 is now employed to accomplish that task.

In order to improve accuracy, the strengths and positions of the body nose vorticity at the leading edge of the canard section are obtained from figure 5, reference 4, instead of the body pressure output mentioned above. For the last axial station, $x_B = 18.98$, at which body pressures are calculated as a result of the previous step, the body vortex strength, Γ/V_∞ , equals 0.71. The canard leading edge is at $x_B = 19.8$ and the value for the body vortex strength equals 0.8024 in accordance with the cited figure. The lateral positions of the vortices are also determined at the canard leading-edge location. Body nose vortex strengths and lateral coordinates, in the body reference coordinate system, to be read in to program VPATH2 are given in the following table.

Γ/V_∞	$y_{B,V}$	$z_{B,V}$	$x_{B,V}$
0.8024	-0.64337	1.8382	19.8
-0.8024	-1.8382	0.64337	19.8

For this run with program VPATH2, indices NCPIN and NVLOUT are set equal to 1. After the vortex paths are calculated, the vortex induced velocities are determined at the control points on the canard fins and the interference shell. In this process, the vortices are in the presence of the body only. The purpose for this approach is described in section 3.4.

The input for program VPATH2 for this run is shown in figure 8. The output is shown in figure 9. It includes the lateral positions, in the body reference coordinate system, of the body nose vortices at the trailing edge of the canard section. They are given in the following table.

Γ/V_∞	$Y_{B,V}$	$Z_{B,V}$	$x_{B,V}$
0.8024	-0.68451	1.9192	23.4
-0.8024	-1.9192	0.68451	23.4

Comparison with the previous table indicates a small amount of lateral movement of the body vortices as they travel through the canard section. The vortices are located symmetrically with respect to the free-stream component in the crossflow plane. The output also shows the vortex induced velocities at the 108 control points associated with the canard fins and interference shell. Control point coordinates and vortex induced velocities are stored in a data set designated VELOS1.

In order to determine the effects of the body nose vortices on the canard section, program DEMON2 is run again in accordance with step 3 of section 5.1.1. The input for this run is the same as shown in figure 5 except for index NVLIN now set equal to 1 and index NCPOUT set equal to its default value 0. The forebody pressures appear unchanged in the output shown in figure 10. Vortex induced velocity components designated VVEL and WVEL are printed out under the heading POINT COORDINATES AND PERTURBATION VELOCITIES CALCULATED BY PROGRAM VPATH2 or VPATHL. These velocity components are included in the boundary conditions, equations (1) through (4), and the strengths of the constant u-velocity panels are recalculated. The pressures calculated at the control points on the fins and interference shell are changed because of the recalculated panel strengths and the inclusion of vortex induced velocities in the Bernoulli pressure determination.

Figures 11(a) and 11(b) show the pressure distributions on the forebody and over the length of the canard section. The latter are taken from program DEMON2 output under the heading AFT OF LEADING EDGE OF FIN ROOTCHORDS. As before, the solid line represents pressures calculated including the body nose vorticity; the crosses are pressures without body vorticity. For the symmetrically located meridians at $\theta = 56.25^\circ$ and $\theta = 213.75^\circ$, the effects of body nose vorticity are negligible over the canard section. Along the symmetrically located meridians at $\theta = 101.25^\circ$ and $\theta = 168.75^\circ$, the effects of the body vorticity are to increase the pressures. The output shown in figure 10 includes loadings for all fins based on linear pressure and Bernoulli pressure. In both cases, due to flow symmetry the loadings on the right horizontal and lower vertical

fins are identical as are the loadings on the upper vertical and left horizontal fins. On the right horizontal fins, figure 12 shows slight effect of the body nose vorticity on the span loading. Due to the closer proximity of the upper vertical fin to the vorticity, the span loading is reduced significantly in the inboard region. In figure 13 the dashed curve (with vortices) exhibits a maximum and drops off in magnitude towards the fin root. In accordance with the analysis in Appendix B, this type of span load distribution gives rise to an inboard and outboard concentrated vortex at the trailing edge of this canard fin. The right horizontal fin does not show any extrema off the root and only one concentrated vortex results at the trailing edge. The leading edges of the fins are supersonic for the Mach number at hand so there is no leading-edge separation vortex in accordance with the analysis in Appendix C. The side edges of the fins give rise to a separation vortex with negligible strength as shown below. Thus, at the trailing edge of the canard section, the strengths and locations of body and canard vortices are assembled for the purpose of determining their paths to the base of the body. Their characteristics are taken from the output of program DEMON2 as a result of step 3, section 5.1.1. The body nose vortex specifications are taken from the output of program VPATH2 as a result of step 2:

Γ/V_∞	$y_{B,V}$	$z_{B,V}$	$x_{B,V}$	
0.8024	-0.68451	1.9192	23.4	} body nose vortices
-0.8024	-1.9192	0.68451	↓	
0.94911	3.15424	0.0	23.4	right hor. fin T.E. vortex
0.05844	-2.09688	0.0	↓	inboard } left hor. fin
-0.59187	-3.46609	0.0		outboard } T.E. vortices
-0.05844	0.0	2.09688	↓	inboard } upper vert. fin
0.59187	0.0	3.46609		outboard } T.E. vortices
-0.94911	0.0	-3.15424	↓	lower vert. fin T.E. vortex
0.01491	3.64	~0.0	23.4	right hor. fin S.E. vortex
-0.01797	-3.64	~0.0	↓	left hor. fin S.E. vortex
0.01797	~0.0	3.64		upper vert. fin S.E. vortex
-0.01491	~0.0	-3.64	↓	lower vert. fin S.E. vortex

In this table, the trailing-edge vortex characteristics, $\text{GAMMA}/\text{VIN F}$ and Y.C.G. or Z.C.G., are obtained from the loading output under the heading BERNOULLI TYPE LOADING PRESSURE. The side-edge vortex characteristics, $\text{GAMMA}, \text{SE}/\text{VIN F}$ and YBAR or ZBAR , are obtained from the loading output under the heading $\text{U}/\text{VIN F}$ LOADING PRESSURE. The strengths of the side edge vortices are negligible compared to the strengths of the body nose and trailing edge vortices and will not be included in further analysis.

At the top of figure 14, all the vortices excepting the side-edge vortices listed in the above table are shown in position at the canard trailing edge, $x_B = 23.4$. They will eventually be tracked down the body through the tail section. However, before determining the vortex paths over the aft body, the body tail section must be dealt with in accordance with step 4 of section 5.1.1. Program DEMON2 is used again to model the body and the cruciform tail fins without accounting for the presence of body nose and canard fin vortices. The input for this run is the same as shown in figure 5 except that the distance from the nose to the tail section, XWLE , is now set equal to 35.4. Also, indices $\text{NCPOUT} = 1$, $\text{NVLIN} = 0$ and $\text{ITAIL} = 1$ in namelist \$INPUT. Quantity XSTART is set equal to the trailing-edge location of the canard section, $\text{XSTART} = 23.4$. With these specifications, the program generates a data set, designated CPTS2, containing 268 sets of coordinates. Of this set, the first 108 sets pertain to the control points on the tail fins and interference shell. The remaining 160 are associated with points on the body aft of the canard section up to the tail section at which pressures will be calculated. The output for this run is not shown. The calculated pressures on the body meridians and the tail fin loadings do not include effects of body nose and canard vortices so far.

6.1.4 Vortex positions at body base, pressure distributions on aft body, tail fin loadings

Using program VPATH2, the vortices shown in the upper part of figure 14 are chased from the trailing edge of the canard section, past the aft body, through the tail section to the body base. In accordance with step 5 in section 5.1.1, the input to program VPATH2 for this run includes index $\text{NCPIN} = 1$ and index $\text{NVLOUT} = 1$. The input for this run is shown in figure 15. Under the influence of the free stream, the mutual interaction between the vortices and the effects of the presence

of the body and tail section, the vortices move as a function of axial distance.

After the vortex paths have been determined, the vortex induced velocity components will be calculated at the 268 sets of coordinates associated with points on the aft body, tail fins and interference shell. Again, in this process the vortices are in the presence of the body only. The output of program VPATH2 is shown in figure 16. The bottom half of figure 14 shows the vortices at the base of the body as taken from the output at the $x_B = 39.0$ station (x-station no. 26). Comparison with the upper half shows that the body nose vortices did not move nearly as much as the vortices associated with the fins. The output also includes the velocity components induced by the vortices at the set of 268 points read in to the program. The control point coordinates and the induced velocity components are stored in a data set called VELOS2.

As described in the last step 6 of section 5.1.1, program DEMON2 is applied one more time to the tail fins and body. However, in this instance the input to program DEMON2 includes index NVLIN = 1 and ITAIL = 1. The input is shown in figure 17. Vortex induced velocity components are now included in the flow tangency condition applied at the control points distributed over the fins, equations (1) through (14). They are also included in the Bernoulli pressures calculated by subroutine BDYPR over the aft body and the part of the body covered by the interference shell associated with the tail fins. The output of this run is shown in figure 18. The pressure distributions and forces and moments acting on the tail fins now include effects induced by the body and canard fin vortices.

The pressures calculated along meridians at $\theta = 11.25^\circ$, 56.25° and 101.25° are shown in figure 19. The solid lines are the pressure distributions calculated including vortex effects and the crosses are calculated with vortices absent. The 11.25° and 101.25° meridians are on the suction sides of the right horizontal and upper vertical fins, respectively. Therefore, through the tail section, the pressures on these meridians are lower than the pressures on the 56.25° meridian. In general, over the aft body and through the tail section, the calculated effect of the body nose and canard vortices is to increase the pressures along the meridians shown.

The effect of the presence of vortices on the span loadings acting on the right horizontal and upper vertical fins are shown in figures 20 and 21. The tail fins are identical in geometry to the canard fins. Without vortices, the solid lines indicate that the span loading on the right horizontal and upper vertical fins are practically identical to those on the corresponding canard fins; see figures 12 and 13. However, in the tail region the body nose and canard vortices have larger influence in reducing the loadings on the two fins as shown in the figures by the dashed lines. On account of symmetry about the component of free stream in the crossflow plane, the loadings on the left horizontal fin are reduced to the same extent shown for the upper vertical fin in figure 21. Likewise, the loading on the lower vertical fin is reduced to the same extent indicated in figure 20.

6.2 Sample Case 2: Elliptic Cross Section Body-Monoplane Wing-Interdigitated Tails

The configuration of a model including a body with elliptical cross section is shown in figure 22. The body has an ellipticity ratio of 3. A monoplane wing and interdigitated tail fins with bevelled streamwise sections are attached to the body. Programs WDYBDY, DEMON2 and VPATHL are used to analyze this configuration at angle of attack of 10° and zero roll angle. The Mach number is 1.70. Under these conditions, there will be a symmetry plane at $y_B = 0$ in terms of the aerodynamic loading. Thus, only the right monoplane wing and the right upper and right lower interdigitated tail fins need to be modeled by program DEMON2. For the same reason, only the right half of the body needs to be modeled by source panels by means of program WDYBDY. Any vortices analyzed by program VPATHL will also be symmetrically positioned with respect to the $y_B = 0$ plane.

6.2.1 Geometry and singularity layout

The following geometrical specifications and singularity distributions will be used for the elliptical cross section body with monoplane wing and interdigitated tail fins. The specified numbers of body source panels to model the body and the numbers of chordwise and spanwise constant u-velocity panels to model the wing and tail fins give rise to a sparse layout. As such they may not be sufficient for precise

calculated results but serve to generate this sample case. Refer to figures 22 in connection with input to program WDYBDY and figure 23 in connection with input to program DEMON2 for geometrical details.

The input to program WDYBDY includes the following specifications for the body with elliptic cross section. There will be two sets, depending on which lifting-surface section the effects of the body are to be determined.

Set #1.- Monoplane Wing Section

Body length to be modeled = 25.6 (covers the monoplane wing section)

Number of body source panels on the half circumference or half ring + 1 = KRAD, KRAD = 9 (8 panels/half ring)

Number of body source panels in the axial direction or number of rings + 1 = KFORX, KFORX = 11 (10 panels axially)

Body length over which pressures and loads are to be computed by program WDYBDY, XWLE = 18 (Program DEMON2 covers the winged section).

Set #2 - Interdigitated Tail Section

Body length to be modeled = 28.0 (covers the interdigitated tail section)

Number of body source panels on the half circumference or half ring + 1 = KRAD, KRAD = 9 (8 panels/half ring)

Number of body source panels in the axial direction or number of rings + 1 = KFORX, KFORX = 12 (11 panels axially)

The step for which this data is the partial input, no pressures and loads are computed

The first set will be used for the run with program WDYBDY in accordance with step 2, section 5.2.1, and the second set will be used for the run in accordance with step 9, section 5.2.1. The body source paneling layout associated with both sets is shown in figures 24(a), 24(b) and 24(c) in planview, sideview and cross section, respectively. Note that only the right half of the body will be modeled.

Namelist \$INPUT in main routine CRFWBD of program DEMON2 includes specifications for the lifting surfaces and their associated interference shells. If the body is modeled by means of body source panels, as is the case here, it is important that the entire interference shell be exterior

to the body source panels. If the shell were made to lie partially on the inside of the body outline, some of the control points distributed on the interference shell may lie on the interior side of one or more body source panels. In this case, the velocity components induced by the source panels at those points would be invalid.* As a consequence, the interference shells are laid out and the monoplane wing is idealized as shown in figure 23. For the monoplane wing attached to its interference shell with elliptic cross section, the input includes the following (refer to figure 23):

rootchord, CRP = 7.55
exposed semispan, B2 = 1.0935
leading edge sweep, SWLEP = 75.0°
trailing edge sweep, SWTEP = 30.016°
number of constant u-velocity panels along a chord, NCW = 2
number of planar source panels along a chord, NCWT = 4
number of constant u-velocity panels along the span, MSWR = 3
number of planar source panels along the span is specified in
subroutine THKIN of program DEMON2, MSWT = 3
length of body interference shell, BIL = 7.55
horizontal semi-axis of elliptical interference shell, RB =
3.4641
vertical semi-axis of elliptical interference shell, RA =
1.155
Note: the ellipticity ratio, RB/RA = 3.0
number of body interference panels on the circumference (ring),
NBDCR = 16
number of body interference rings, NCWB = 2
distance from body nose to monoplane wing section, XWLE = 18.0

The thickness slopes are read in by subroutine THETIN of program DEMON2. They are determined in the manner described for the first sample case, section 6.1.1. Using the detailed streamwise sections available from reference 11, the following streamwise slopes are used. For centroids of planar source panels near the leading edge, the streamwise slope is given by

* The solution associated with body source panels, reference 9, is valid only in the plane of the panel and along the outward normal.

$$\text{THET} = \tan \theta_s = \frac{0.125}{2.516} = 0.049692 \quad (27)$$

On the unbevelled portion, the slope equals zero. Near the trailing edge, the streamwise slope equals

$$\text{THET} = \tan \theta_s = -\frac{0.125}{1.5845} = -0.07889 \quad (28)$$

For the upper right and lower right interdigitated tail fins attached to its interference shell, the input includes the following (refer to figure 23). Thickness is not accounted for.

rootchord, CRP = CRPV = 3.6
 exposed semispan, B2 = B2V = 3.6

upper right fin { leading-edge sweep (varies with distance along the span),
 VSWLER = 45.0° up to YRT = 2.0
 VSWLER = 14.04° up to YRT = 3.6
 Note: since leading-edge sweep varies, the trailing edge must also be specified as if it varies with distance along the span
 trailing-edge sweep, VSWTER = 0.0 for all YRT

lower right fin { leading-edge sweep (varies with distance along the span),
 VSWLEU = 45.0° up to ZUT = 2.0
 VSWLEU = 14.04° up to ZUT = 3.6
 see note above
 trailing-edge sweep, VSWTEU = 0.0 for all ZUT

number of constant u-velocity panels along a chord, NCW = 2
 number of constant u-velocity panels along the span, MSWR = 4
 (upper right fin)
 MSWU = 4
 (lower right fin)

length of body interference shell, BIL = 3.6
 horizontal semi-axis of elliptical interference shell,
 RB = 3.129

vertical semi-axis of elliptical interference shell,
 RA = 1.043

Note: the ellipticity ratio, RB/RA = 3.0

number of body interference panels on the circumference (ring),
 NBDCR = 16

number of body interference panel rings, NCWB = 2

distance from body nose to tail section, $XWLE = 24.4$
angle of the location of the fins on the interference shell
measured from positive y_w -axis, $THETIT = 22.545^\circ$
dihedral angle of the fins, $PHIDIH = 30^\circ$

Angles $THETIT$ and $PHIDIH$ are also indicated in figure 3. The above sets of input parameters will be used in the runs with programs $WDYBDY$ and $DEMON2$ described in the procedure for a body with elliptical cross section, section 5.2.

6.2.2 Body nose vorticity, pressure distributions on forebody

After running program $DEMON2$ in accordance with step 1, section 5.2.1, to generate data set $WCPTS$, program $WDYBDY$ is then run to model the body with elliptical cross section. The input to program $WDYBDY$ includes the parameters in the first set described above and index $NCWPT$ which must be set equal to the sum of all constant u -velocity panels on the monoplane wing and the interference shell. The length of body, to be modeled for this run, is taken to the trailing edge of the interference shell associated with the monoplane wing. The input for this run is shown in figure 25. For this case, the geometry of the body with elliptical cross section is given in terms of the horizontal semi-axis, $FUSBY$, and the vertical semi-axis, $FUSAZ$, as a function of axial location $XFUS$. Also included are the body nose vorticity characteristics, if indices $NVTX$ and $NXVTX$ are nonzero, provided by a separate program; see section 2.2. The axial stations at which this data is to be specified are read in from subroutine $READVX$ and the lateral locations and strengths of the vortices are read in by subroutine $ELBDVT$. The output of this run is given in figure 26. Included in the output are the pressure coefficients designated CP and printed on the page identified with $**FORMOM**$. They are plotted in figures 27(a) and 27(b) from the body nose up to the leading edge of the monoplane wing section.

Figure 27(a) shows pressure distributions on the upper half of the body. The open symbols include effects of body nose vorticity. Pressure distributions without vortex effects are also shown by the solid symbols. In the legend, the first column of symbols are for meridians on which pressures are calculated over the forebody, the second column are for the monoplane wing section and the third for the tail section. For the moment, the forebody only is considered. The pressures shown in

figure 27(a) are below free-stream static pressure. The effects of the specified body nose vortices are to increase the pressures along the $\theta = 9.07^\circ$ meridian and to decrease the pressures along the $\theta = 31.41^\circ$ meridian. On the lower half of the body, figure 27(b) shows that the effects of the body vortices are much less. Only one result is shown without vortex effects and there is little difference between the dark and light triangles. The output also includes the contributions from the forebody to the overall forces and moments under the heading TOTAL COEFFICIENTS ON THE BODY FROM XSTART = 0.0 to XWLE = 18.0. In order to improve the accuracy of these contributions, especially with vortex effects, the number of source panels should be larger than used here in this sample case.

Program WDYBDY also computes velocity components, induced by the body source panels only, at the control points distributed over the monoplane wing and interference shell read in by means of data set WCPTS. These velocity components are stored in a data set designated WVELS for later use by program DEMON2.

6.2.3 Pressures and loads acting on the monoplane wing-body section

After completing the calculations of pressures and loads acting on the forebody, program DEMON2 is applied to the monoplane wing-body section in accordance with step 3 of section 5.2.1. As a result of this run, the loadings acting on the monoplane wing section are calculated excluding effects of body nose vorticity. The output also includes the strength, $\Gamma/V_\infty|_{\text{edge}}$, and lateral position, \bar{y}_W , of the leading- and side-edge vorticity as a function of axial coordinate x_W . Values for these characteristics are taken from the loading output under the heading U/VINF TYPE LOADING PRESSURE. Leading-edge vorticity is designated GAMMA,LE/VINF, side-edge vorticity is GAMMA,SE/VINF, and the lateral location appears as YBAR. Along the leading-edge, the axial coordinate is XLE, along the side-edge it is XSE, both are in the wing coordinate system. The values shown in the following table are taken from the output of program DEMON2 for the right monoplane wing half. They are calculated with $K_{V,LE} = K_{V,SE} = 0.5$ (refer to Appendix C, equation C11, etc.). Note that x_W is the axial coordinate in the wing coordinate system.

x_W	\bar{y}_W	$\frac{\Gamma}{V_\infty}$ edge	
0.66148	3.64135	0.27984	} along leading edge
2.01812	3.82511	0.27786	
3.37295	4.03457	0.28634	
4.081	4.34073	0.44937	} along side edge
6.13099	4.40075	0.58150	

Following step 4 of section 5.2.1, the vortex chasing program VPATHL is then employed to determine the paths of the two body nose vortices from the leading edge to the trailing edge of the monoplane wing section. The input for this run is shown in figure 28. Characteristics of the two symmetric body nose vortices at the start of the wing section are specified on the 9th line. Note that these two sets of characteristics are also shown in the input to program WDYBDY indicated in figure 25 at the last axial station associated with the forebody, $XV = 18.0$, on the cards marked YVRTX1, ZVRTX1, GAM1, and YVRTX2, ZVRTX2, GAM2, respectively. Also, the characteristics of the symmetric vortices on the opposite side of the plane of symmetry, $y_B = 0$ plane, must also be input to VPATHL. The starting values of the symmetric body nose vortex strengths and lateral positions are given in the following table with x_B , y_B and z_B in the body coordinate system.

x_B	y_B	z_B	$\frac{\Gamma}{V_\infty}$ Body nose
18	2.35	1.673	1.52
18	-2.35	1.673	-1.52

The body nose vortex characteristics as a function of distance from the nose were determined by an adapted version of the program associated with reference 5 as mentioned earlier in section 2.2. Although the magnitude of the body nose vortex strength is at least 2.5 times the magnitude of the edge vorticity strength, for illustrative purposes the edge vorticity will be included in the determination of the body nose vortex paths. Thus, the input to program VPATHL shown in figure 28 also includes the edge vorticity specifications listed in the first table above. At this stage, the edge vorticity characteristics are only approximate in that the body nose vortex effects have not been included in the wing loading nor the edge vorticity distribution as calculated in step 3.

After the body nose vortex paths are known and the wing loading recalculated in step 5, described later, the updated edge vorticity distribution should be compared with the one given in the first table. If differences are sufficiently large, the calculations performed by steps 4 and 5 should be repeated until the edge vorticity distribution is converged.

Figure 29 shows the output of program VPATHL. The geometry of the monoplane plane wing in planform appears under the heading FIN GEOMETRY. The specified strengths and lateral coordinates of the leading- and side-edge vorticity as a function of axial distance measured from the body nose also appears on the first page of the output. The horizontal and vertical semi-axes of the body are held constant over the monoplane wing section. In fact, the body nose vortices pass over the idealized monoplane wing attached to the interference shell as indicated in figure 23. At the location corresponding to the trailing edge of the monoplane wing section, $x_B = 25.5$, the coordinates in the crossflow plane of the body nose vortices are given below.

x_B	y_B	z_B	$\frac{\Gamma}{V_\infty}$ Body nose
25.5	2.4609	1.8792	1.52
25.5	-2.4609	1.8792	-1.52

Comparison with the preceding table shows that the body nose vortices move upward and outboard by a small amount. If the monoplane edge vorticity is neglected in the calculation of the body nose vortex paths, the results shown in the table below would be generated by program VPATHL. It is seen that for this illustrative example, the body nose vortices move higher but do not move as much outboard when the effects of edge

x_B	y_B	z_B	$\frac{\Gamma}{V_\infty}$ Body nose
25.5	2.4276	1.9509	1.52
25.5	-2.4276	1.9509	-1.52

vorticity are not included. In an actual calculation, the characteristics of the leading- and side-edge vorticity must be determined with a larger number of panels than is used in step 3. The last part of the output generated by program VPATHL contains the velocity components induced by

the body nose vortices at the control points of the monoplane wing. These data are stored in data set VRTVEL.

In accordance with step 5 of section 5.2.1, program DEMON2 is run again to obtain the pressures acting on the monoplane wing-body section including effects of body nose vortices. In this run index NVLIN is set equal to 1 thereby causing data set VRTVEL to be read in. The input of program DEMON2 is shown in figure 30 for this run. Output generated by program DEMON2 is shown in figure 31. The last part contains the pressures acting along meridians on the interference shell under the heading AFT OF LEADING EDGE OF FIN ROOTCHORDS. Figures 27(a) and 27(b) include calculated pressures along 4 meridians on the interference shell. They are indicated by the second column of symbols and correspond to axial locations $x_B = 21.58$ and $x_B = 25.36$. These meridians are essentially the same* as the meridians for which pressures are plotted on the forebody. Over the upper half of the body, figure 27(a), the pressures through the monoplane wing section continue below free stream. Open symbols include effects of body nose vortex effects and the solid symbols are calculated excluding the body nose vortex effects. Along the $\theta_p = 11.25^\circ$ meridian the effects of the vorticity is to increase the pressure appreciably and along the $\theta_p = 33.75^\circ$ meridian the pressure is decreased. On the lower half of the body, the results shown on figure 27(b) show little effects from the body nose vorticity including the axial locations at $x_B = 21.58$ and 25.36.

The span-load distribution associated with the monoplane wing is shown in figure 32. The calculated results include body nose vortex effects. The solid line represents the potential span-load distribution which does not exhibit a maximum off the wing rootchord in contradistinction with the results computed for the cruciform canard of Sample Case 1 shown in figure 13 and discussed in section 6.1. For the indicated Mach number, the leading edge of the monoplane wing lies aft of the Mach cone with its vertex at the leading edge of the rootchord. Therefore, the leading edge is subsonic and the program calculates the suction distribution along that edge. Using the Polhamus vortex-lift analogy with the proportion of the leading edge suction converted to normal force equal

* Slight differences in polar angle are due to differences between geometry of body source panel layout and body interference panel layouts.

to 0.5 (refer to Appendix C), the dashed line represents the augmented span loading up to the side edge. The increments added to the potential span loading are obtained from the spanwise distribution $CS \cdot C / (2 \cdot B)$ for the right wing. They are calculated on the basis of linear pressure loading under the heading U/VINF TYPE LOADING PRESSURE, and must be multiplied by 0.5. The side edge also contributes to the calculated additional normal-force distribution which would be concentrated near the tip but is not shown in figure 32.

The augmentation to the normal-force coefficient for one wing half can be determined by multiplying the suction coefficient $C_S|_{LE}$ for the leading edge by the appropriate factor $K_{V,LE}$ and adding it to the suction coefficient for the side edge $C_S|_{SE}$ multiplied by the appropriate factor $K_{V,SE}$. The suction coefficient for the leading edge is proportional to the accumulated quantity CSINT(I) with index I equal to the number of panels in the spanwise direction. This number is equal to the quantity MSWR, specified in the input for program DEMON2, for the right wing half. In other words, the last value under the heading CSINT is taken from the spanwise distributions calculated on the basis of linear pressure loading of the lifting surface under consideration. This value must be multiplied by $2b$ where b is twice the exposed semispan, $b/2$, specified in the input of program DEMON2 and divided by the reference area S_{REF} . The suction for the side edge can be obtained from a numerical integration of the quantity SUCTION FORCE PER UNIT LENGTH / (Q * TIPCHORD) which appears under the heading SIDE EDGE DISTRIBUTION in the loading output calculated with linear pressure loading. Setting this quantity equal to $c_{S,JSE}$, the suction coefficient associated with the side edge is given by

$$C_S|_{\text{side edge}} = \frac{(c_{TIP})^2}{S_{REF}} \sum_{JSE=1}^{NCW} c_{S,JSE} \cdot \frac{C_{TIP,JSE}}{C_{TIP}} \quad (27)$$

In the above expression, c_{TIP} is the chord of the side edge or wing tip, S_{REF} is the reference area and NCW is the number of constant u-velocity panels in the chordwise direction. Thus for one wing half, the augmentation to the normal-force coefficient due to leading- and side-edge vorticity can be computed as follows.

$$C_N|_{\substack{LE+SE \\ \text{vorticity}}} = K_{V,LE} C_S|_{LE} + K_{V,SE} C_S|_{SE} \quad (28)$$

The vortex lift factors $K_{V,LE}$ and $K_{V,SE}$ are discussed in Appendix C.

The above process for the calculation of the augmentation to normal force due to leading- and side-edge vorticity must be repeated for each wing half. Since the flow conditions (including the presence of body nose vorticity) and configuration geometry are symmetric with respect to the $y_B = 0$ plane, the resulting loading on the body and lifting surfaces are also symmetric. Thus, the augmentation given by equation (28) must be doubled.

Finally, the updated characteristics of the monoplane wing leading- and side-edge vorticity also appear in the loading output under the heading U/VINF TYPE LOADING PRESSURE. They are listed below and at this stage (step 5) include effects of body nose vorticity. Comparison with the results excluding body nose vorticity shown in the first table of this section indicates an appreciable drop in strength and a slight out-board movement. On the basis of the difference in vorticity strength, an

x_W	\bar{y}_W	$\frac{\Gamma}{V_\infty}$ edge	
0.66148	3.64135	0.19406	} along leading edge
2.01812	3.83365	0.19763	
3.37295	4.05562	0.21123	
4.081	4.36126	0.35606	} along side edge
6.13099	4.41828	0.47179	

iteration would be recommended for an actual calculation. Note that a drop in edge vorticity strength would result in less influence in the body nose vortex path calculation. This should speed up the convergence mentioned earlier in this section.

6.2.4 Pressures and loads acting on the interdigitated tail-body section

According to figure 23, the monoplane wing-body section actually overlaps the interdigitated tail-body section. Thus, there is no after-body separating the former from the latter. Consequently, steps 6 and 7 described in section 5.2.1 are omitted.

In dealing with the overlap situation, the following approximate procedure is adopted. The strengths and positions of the body nose vortices and the monoplane wing vortices are calculated by the preceding steps 4 and 5. The axial locations at which these characteristics are now known vary a little. The body nose vortices are known at $x_B = 25.5$.

The monoplane wing vortices are calculated somewhat aft of this location on or slightly above the trailing edge at different spanwise locations. For the purpose of determining the effects on the interdigitated tails, the vortices are assumed to pass through the tail section in a direction parallel to the body centerline. Their lateral positions are taken from the results obtained earlier. The following table contains the coordinates in the crossflow plane and the strengths of the external vortices influencing the pressures and loads acting on the interdigitated tails and body section. They will be part of the input to program DEMON2 applied

y_B	z_B	$\frac{\Gamma}{V_\infty}$	
2.4609	1.8792	1.52	} body nose vortices
-2.4609	1.8792	-1.52	
4.41828	0.661	0.47179	} combined LE and SE vorticity at TE of monoplane wing
-4.41828	0.661	-0.47179	
4.38465	0.0	0.59704	} TE vortices on TE of mono- plane wing
-4.38465	0.0	-0.59704	

to the tail section. Note that the strengths and positions of the symmetry vortices must also be specified. The body nose vortex characteristics appear in the output of program VPATHL for the last axial station at $x_B = 25.5$ as a result of step 4. The combined leading- and side-edge vorticity characteristics at the wing trailing edge are obtained from the output of program DEMON2 as a result of step 5. They are taken from the distribution of vorticity along the side edge under the heading U/VINF TYPE LOADING PRESSURE. The accumulated value of the side-edge vorticity added to the leading-edge vorticity is taken at the wing trailing edge. In other words, the last values in the columns headed YBAR and GAMMA,SE/VINF are listed above. The vertical displacement is determined on the basis of the leading- and side-edge vorticity leaving the monoplane wing surface at an angle equal to half the angle of attack seen by the wing. With a rootchord equal to 7.55, refer to figure 23, the vertical displacement at the trailing edge is given by

$$z_B = (7.55) \tan 5^\circ = 0.661 \quad (29)$$

The trailing-edge vortex characteristics are taken from the loading information output generated by program DEMON2 as a consequence of step 5

described in section 5.2.1. Trailing-edge vortex strength(s) and position(s) are taken from the results calculated on the basis of Bernoulli type loading pressures. They appear under the heading T. E. FIN VORTEX INFO.

Before the loads on the interdigitated tail section can be determined, program DEMON2 must first be run in accordance with step 8 of section 5.2.1 for the purpose of generating the data set TCPTS containing the coordinates of the control points distributed over the tail fins and the interference shell. Index NCPOUT must be set equal to 2 for this fin. The input is otherwise the same as the input to be discussed in connection with step 10. Once data set TCPTS has been generated, step 9 involves the application of program WDYBDY to the entire body length (i.e. up to the base of the tail section). The primary function of this run is to calculate the store in data set TVELS the velocity components induced by the body source panels at the control points on the tail fins and body interference shell. This last data set will be passed back to program DEMON2 in accordance with step 10.

The loads acting on the interdigitated tail-body section are calculated by program DEMON2 as per step 10 of section 5.2.1. Effects of the body nose and monoplane wing vortices will be included. The strengths and positions in the crossflow plane of these external vortices are listed in the discussion above. The input is shown in figure 33 and includes the break in sweep of the tail fins as described in section 6.2.1. For this run involving interdigitated tails, control index NDRAG must equal its default value 0. With this control, the program will not compute in plane forces used in the determination of edge suction. Note that with the Mach number at hand (1.7), the leading edge of the tail fin is supersonic for both sweep angles. Thus, the leading edge would have zero suction in this case. At the present time, program DEMON2 cannot compute in plane forces nor span loadings if the lifting surfaces under consideration involve interdigitated fins.

The input in figure 33 also includes the 6 external vortices listed in the table above. Index NVRTX=6 in namelist \$INPUT causes the program to read in the strengths and lateral coordinates of the 6 body nose and monoplane wing vortices. In figure 33, the vortex specifications start on the 9th line from the end of the input. The listed z_B (or z_W) coordinates of the two body nose vortices are slightly in error. The number

1.8809 should have been 1.8792. The output generated by program DEMON2 using the latter value appears in figure 34. As mentioned earlier, the influences of the external vortices are accounted for in the loading calculations on the basis of their paths being aligned with the body centerline.

Pressure distributions along the meridians of the interference shell indicated in figure 23 appear under the heading AFT OF LEADING EDGE OF FIN ROOTCHORDS. The outline of the interference shell is the idealization of the actual body contour. Figure 27(a) contains calculated pressure coefficients for two meridians, at $\theta_p = 5.64^\circ$ and $\theta_p = 16.91^\circ$, respectively, on the upper half of the body. Both correspond to locations on the body contour below the right upper tail fin; in fact they lie on the impact side of that fin at axial stations $x_B = 26.11$ and 27.91 . The pressures in this region rise rapidly from the leading edge of the tail section to the trailing edge. On the lower half of the body, figure 27(b), pressure coefficients are shown for the $\theta_p = 298.09^\circ$ and $\theta_p = 354.36^\circ$ meridians through the tail section. These two meridians lie on opposite sides of the right lower fin. Consequently, the pressure on the body below the fin ($\theta_p = 298.09^\circ$) is higher than the pressure above the fin ($\theta_p = 354.36^\circ$).

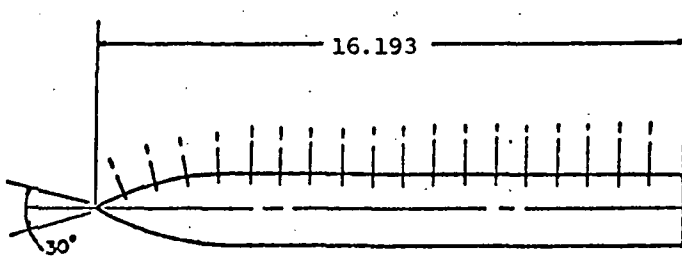
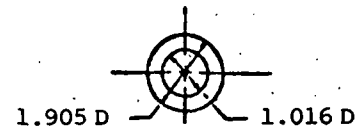
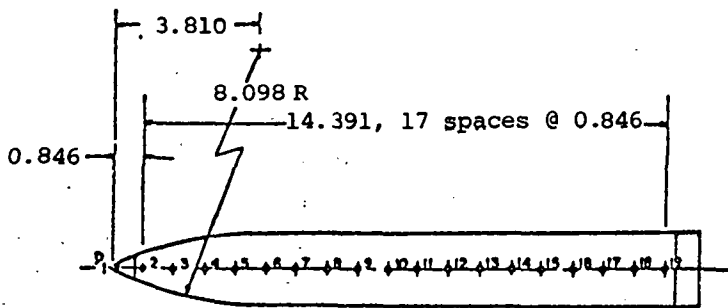
The pressure loading distributions for the upper and lower right fins appear under the heading PRESSURE LOADING AT CONTROL POINTS. Results are available on the basis of linear pressures under the heading DELTP,LIN., and on the basis of Bernoulli pressures under the heading DELTP,BERN. Forces acting on the fins in coefficient form are shown in the loading information output also for both types of loading pressures. If the effects of the body nose vortices are omitted, the loadings on the upper fins of the interdigitated tail section would be increased.

7. COMPARISON WITH EXPERIMENTAL DATA

During the development of the axisymmetric body modeling and pressure calculation methods described in section 3, some comparisons were made with experimental data. The ogive cylinder model shown at the top of figures 35, 36 and 37 is in fact the pressure distribution model used in connection with the store separation work associated with references 12, 13, and 14. This model is equipped with 19 pressure taps and the dimensions in inches are shown below. At the angle of attack under consideration

(5°), very little if any body vorticity will be generated. Thus, calculations were performed using program DEMON2.

The ogive cylindrical body is modeled with 30 line sources/sinks to account for volume effects and 30 line doublets to account for angle of attack. The calculated results are computed by subroutine BDYPR in conjunction with subroutine BDYGEN of program DEMON2. They are represented by a solid line in figure 35 for $M_\infty = 1.5$, in figure 36 for $M_\infty = 2.0$ and in figure 37 for $M_\infty = 2.5$. Program DEMON2 is not capable of modeling a body alone in its present state. Thus, near the body base a set of fins are attached as far as that program is concerned. The solid line is terminated at the leading edge of this imaginary fin section.



All dimensions in cm.

In general, the calculated results match the data well for all three Mach numbers. Near the body nose, some differences are evident for the two lower Mach numbers, figures 35 and 36. It is interesting to note that if the linear pressure relationship is used instead of the Bernoulli expression, the results near the nose tip are improved. However, at other locations, the agreement is then diminished. At the highest Mach number, $M_\infty = 2.5$, the Mach cone at the nose tip intersects the body. The part

of the body nose outside of the Mach cone is then idealized by a conical surface, in fact by the Mach cone itself. In addition, as described in section 3, subroutine BDYGEN moves the line singularities up towards the nose in an effort to minimize the errors attendant to this approximation and the method of body modeling employed. Even so, if the pressure were calculated on the body between the nose tip and the location where the Mach cone emerges, the body singularities would have no effects. Thus, this constitutes a limit to the applicability of the body modeling method. Note that in figure 37 the most forward static pressure tap lies behind the intersection of the Mach cone and the body so that this location is affected by the forward line singularities.

8. CONCLUDING REMARKS

Existing cruciform wing-body computer programs have been extended and additional programs developed to compute, in a stepwise manner, pressure distributions acting on complete missile configurations. The applicable flow regime is supersonic and the configuration can be at combined angle of pitch and sideslip. The body can be circular or elliptic in cross section. The lifting surfaces can be a cruciform canard and/or cruciform tail or a monoplane wing and interdigitated tail fins. Effects of body nose- and canard- or monoplane wing-vortices, tracked along the configuration, can be accounted for in the body pressures and tail fin loadings. For cases involving axisymmetric bodies, the body nose shed vortex characteristics are built into the program. Two calculative examples are given: the first concerns a cruciform canard-axisymmetric body-cruciform tail configuration and the second involves a monoplane wing-elliptic cross section body-interdigitated tail configuration. Limited comparisons between calculated and measured pressures are shown for an ogive cylinder at 5° angle of attack. Fin loads comparisons are described in earlier work. Fin edge vorticity characteristics are calculated by the program from the suction distributions using Polhamus' vortex lift analogy. Some comparisons with other theories are shown for leading- and side-edge suction forces in an appendix.

Some of the limitations of the program in their range of applicability are pointed out in this report. The limitations discussed herein are consequences of the basic linear methods used to model the components

or to account for effects of vortices on the components. The limitation in applicability with regard to flow conditions is estimated to be about 20° in included angle of attack and supersonic velocities up to Mach number 3. A better estimate of the limitations of the program must await detailed pressure distribution data not now available.

The precision of the calculative method is associated with the number of body source panels used to model bodies with elliptical cross section, the number of discrete vortices used to represent body nose vortex shedding, and the number of constant u-velocity panels used to model the lifting surfaces.

The behavior of a vortex in the close proximity of a lifting surface can be a limiting factor in accuracy of prediction. It is possible to include a core in the model for the purpose of reducing the effect of the singularity in tangential velocity associated with the potential vortex model. To the best of our knowledge, there are no data available as yet for the vortex-shedding characteristics associated with bodies with elliptical cross section. A predictive program is available, as discussed herein, but must be thoroughly tested against experimental data not yet available.

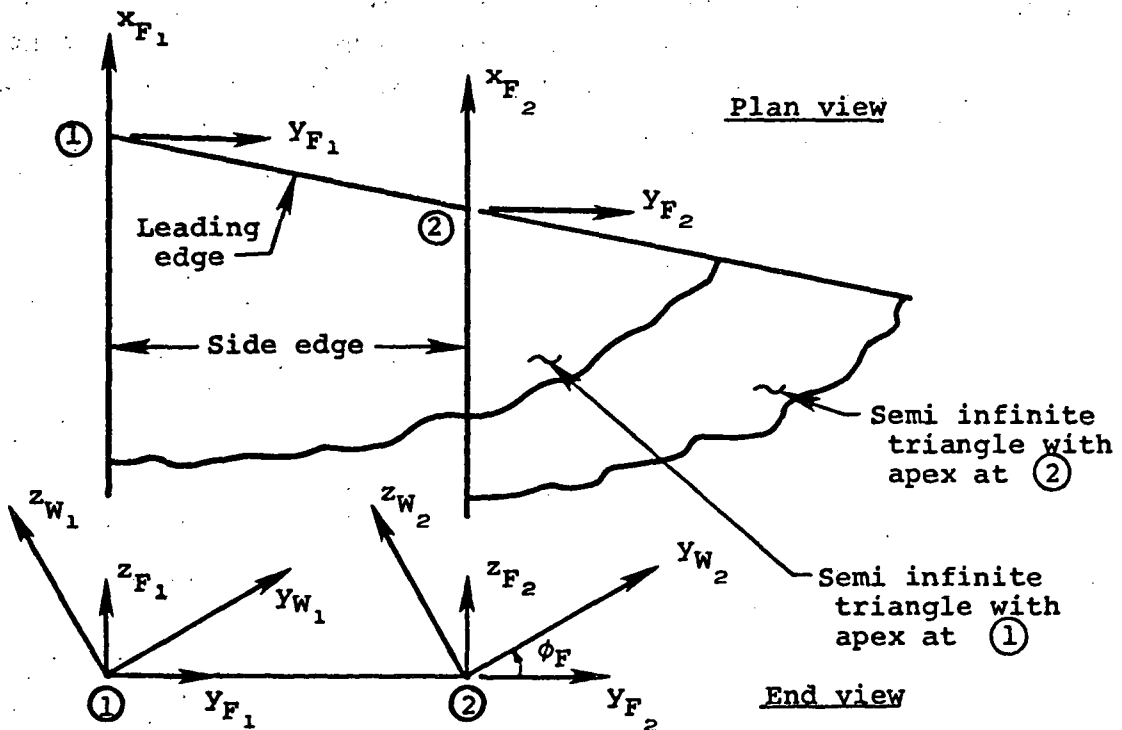
At the present time, the programs are used in a sequential manner without the benefit of an executive program. Running time is a function of the number of panels used. Some decrease in running time is possible by further refining the program.

APPENDIX A

SUPERPOSITION OF CORNER SOLUTIONS FOR A CONSTANT u-VELOCITY PANEL AT ARBITRARY DIHEDRAL ANGLE

In representing fin configurations by a distribution of constant u-velocity panels, questions arise concerning the coordinate system used in the panel corner superposition scheme. The superposition scheme is described in references 1 and 7. Furthermore, if the configuration geometry and flow conditions dictate symmetry in the flow field around the configuration, the aerodynamic influence coefficient matrix must reflect that condition. This appendix addresses these two topics in relation to the wing-body program DEMON2 only.

For simplicity consider only the corners on the leading edge of a constant u-velocity panel. Corners on the trailing edge are treated in the same manner. The following sketch shows the plan view and end view of the leading- and side-edges. Also indicated are the local panel coordinate systems with origins at panel corners 1 and 2. Axes x_{F1} , y_{F1} and axes x_{F2} , y_{F2} lie in the plane of the panel ($z_{F1} = 0$, $z_{F2} = 0$).



APPENDIX A

The end view shows the local lateral coordinates (y_{W_1}, z_{W_1}) and (y_{W_2}, z_{W_2}) with origins at corners 1 and 2, respectively. They are parallel to the reference wing coordinate system (x_W, y_W, z_W) , and we will need velocity components in this system. Coordinate systems $(x_{F_1}, y_{F_1}, z_{F_1})$ and $(x_{W_1}, y_{W_1}, z_{W_1})$ are different by a rotation about the x_{F_1} or x_{W_1} axis through fin dihedral angle ϕ_F . The same is true for the two systems at corner 2. The leading edge shown above has positive sweep. The superposition principle states that the solution for this infinitely long panel is given by the solution associated with the semi-infinite triangle with its apex at corner 1 minus the solution associated with the semi-infinite triangle with its apex at corner 2. Thus, in terms of flow velocity components, the superposition scheme specifies the velocity components in the x_F, y_F, z_F directions as follows for the semi-infinite panel.

$$\left. \begin{aligned} u_{F,TOT} &= u_{F_1} - u_{F_2} \\ v_{F,TOT} &= v_{F_1} - v_{F_2} \\ w_{F,TOT} &= w_{F_1} - w_{F_2} \end{aligned} \right\} \quad (A1)$$

The corresponding velocities in the wing coordinate system are obtained from those given by equation (A1) by means of a rotational coordinate transformation.

$$\left. \begin{aligned} v_{W,TOT} &= v_{F,TOT} \cos \phi + w_{F,TOT} \sin \phi \\ w_{W,TOT} &= w_{F,TOT} \cos \phi - v_{F,TOT} \sin \phi \end{aligned} \right\} \quad (A2)$$

In equation (A1), the superposition principle is applied to the velocities expressed in the panel coordinate system (x_F, y_F, z_F) . These velocities are then transformed to the wing coordinate system (x_W, y_W, z_W) as indicated in equation (A2).

Alternately, velocities v_{F_1}, w_{F_1} , and v_{F_2}, w_{F_2} can first be transformed into the wing coordinate system and the superposition applied to

the result. The lateral velocity components in the wing coordinate system are obtained from the ones in the panel coordinate system as follows.

$$\left. \begin{aligned} v_{W_1} &= v_{F_1} \cos \phi + w_{F_1} \sin \phi \\ w_{W_1} &= w_{F_1} \cos \phi - v_{F_1} \sin \phi \\ v_{W_2} &= v_{F_2} \cos \phi + w_{F_2} \sin \phi \\ w_{W_2} &= w_{F_2} \cos \phi - v_{F_2} \sin \phi \end{aligned} \right\} \quad (A3)$$

Applying the superposition scheme to the velocities in the wing system and substituting from equations (A3) has the result

$$v_{W,TOT} = v_{W_1} - v_{W_2} = (v_{F_1} - v_{F_2}) \cos \phi + (w_{F_1} - w_{F_2}) \sin \phi$$

$$w_{W,TOT} = w_{W_1} - w_{W_2} = (w_{F_2} - w_{F_1}) \cos \phi - (v_{F_1} - v_{F_2}) \sin \phi$$

Or rewriting in terms of the quantities shown in equation (A1) then gives

$$\left. \begin{aligned} v_{W,TOT} &= v_{F,TOT} \cos \phi + w_{F,TOT} \sin \phi \\ w_{W,TOT} &= w_{F,TOT} \cos \phi - v_{F,TOT} \sin \phi \end{aligned} \right\} \quad (A4)$$

This result is the same as the expressions shown in equation (A2). The conclusion is that the superposition scheme and the coordinate rotation can be interchanged. However, in program DEMON2, the actual procedure employed is as follows: In subroutine VELNOR, the coordinates of a given field point are first calculated relative to corner 1 in the wing reference coordinate system (x_W, y_W, z_W) . These relative coordinates are then transformed to the local panel coordinate system (x_F, y_F, z_F) and the

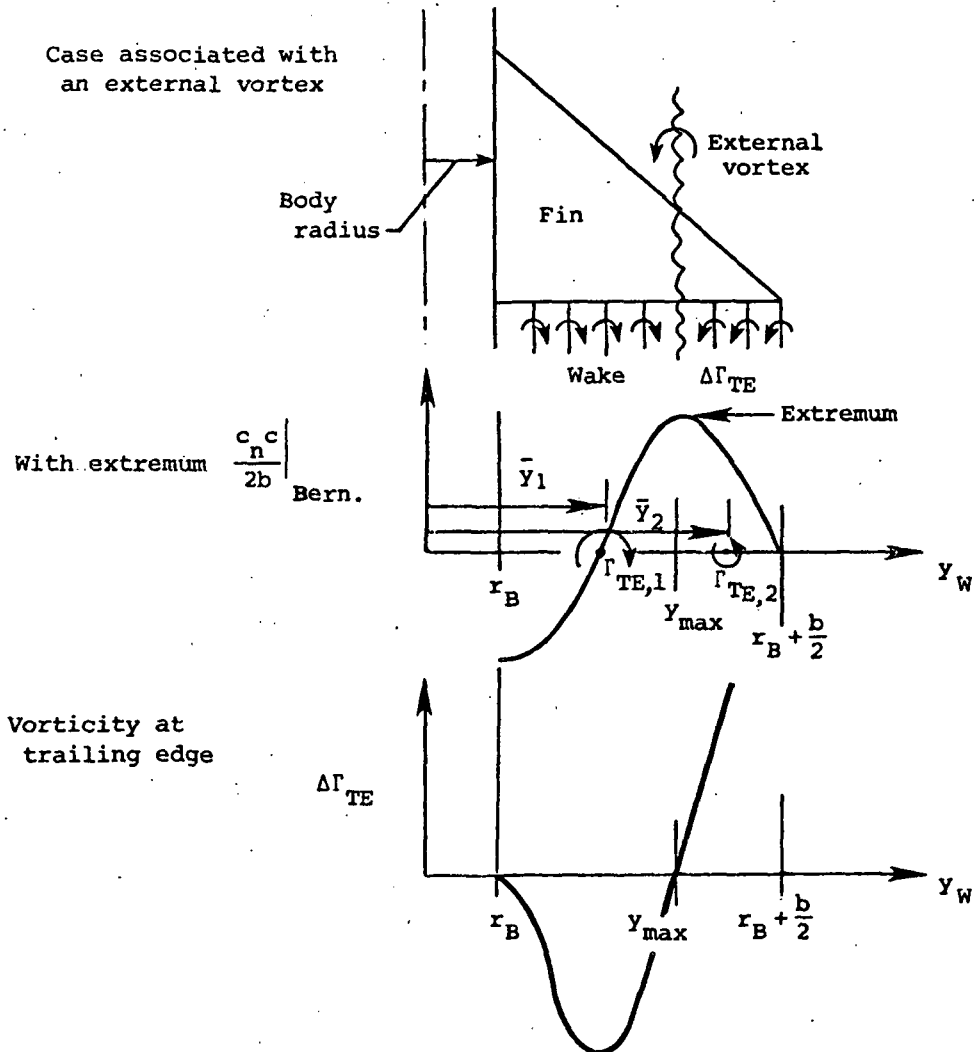
APPENDIX A

influence of the semi-infinite triangle with apex at corner 1 is calculated at the field point by a call to subroutine VELO. The induced velocities are returned in the local coordinate system and transformed back to the wing reference system. Before proceeding to corner 2, however, subroutine VELNOR checks on the possibility of symmetry, that is, for the case of zero sideslip or symmetry in the external vortices if present. If affirmative, the effect of the image corner on the opposite side of the body must be taken into account. To accomplish this, the field point instead is moved to its image point on the other side of the fuselage. The effect of the actual corner 1 is computed there in the wing coordinate system. The velocity components calculated in this way are then transferred to the actual field point with a change in sign on the side wash, v , aligned with the y_w -axis, if corner 1 belongs to a panel on the right horizontal fin. Thus, the procedure used to account for flow symmetry depends on expressing the velocity components in the wing reference coordinate system. The same procedure applies to all corners of panels at any dihedral angle. Thus, these panels include the constant u -velocity panels on cruciform fins, interdigitated fins, monoplane wings and the interference shell.

APPENDIX B

DETERMINATION OF STRENGTHS AND POSITIONS OF CONCENTRATED VORTICES AT THE FIN TRAILING EDGE

Consider a fin or a wing attached to a body as shown in the following sketch. An external vortex passes over the fin. The resulting span load distribution is indicated. The distribution at the trailing edge of the trailing-edge vorticity is also shown. It is desired to determine the strength(s) and location(s) of the concentrated vortex (vortices) representing the wake.



APPENDIX B

In order to represent the distributed trailing-edge vorticity by concentrated vortices, the spanwise load distribution based on the Bernoulli pressure expressions must be calculated first. For the case when this distribution exhibits extrema in between the end points, the number of concentrated vortices is given by the number of extrema plus 1. The trailing-edge vortex strength and position for the inboard portion of the normal-force distribution are then given by

$$\frac{\Gamma_{TE,1}}{V_\infty} = -\frac{1}{2} \int_{r_B}^{y_{max}} \frac{\partial}{\partial y}(cc_n) dy = -\frac{1}{2} \int_{r_B}^{y_{max}} d(cc_n) \quad (B1)$$

$$\bar{y}_1 = \frac{-\frac{1}{2} \int_{r_B}^{y_{max}} y \frac{\partial}{\partial y}(cc_n) dy}{-\frac{1}{2} \int_{r_B}^{y_{max}} \frac{\partial}{\partial y}(cc_n) dy} \quad (B2)$$

The basic relationship between the trailing-edge vorticity and the span-loading used here is described in detail in section 9.1 of reference 15. Fundamentally, it is shown that the rate of change in trailing-edge vorticity with spanwise distance equals the negative of the rate of change of the difference in potential between the upper and lower surfaces of the wing or fin. This is obtained by performing a contour integration parallel to the fin plane just behind the trailing edge. With simplifying assumptions, the potential difference (jump) at the trailing edge can be related to the span load distribution. The combination of these results leads to equation (B1). Integrating equation (B1) yields

$$\frac{\Gamma_{TE,1}}{V_\infty} = -\frac{1}{2} \left[cc_n \Big|_{y_{max}} - cc_n \Big|_{r_B} \right] \quad (B3)$$

and integration of equation (B2) by parts results in

$$\bar{y}_1 = \frac{-\frac{1}{2} \left[y(cc_n) \Big|_{r_B}^{y_{\max}} - \int_{r_B}^{y_{\max}} (cc_n) dy \right]}{-\frac{1}{2} \int_{r_B}^{y_{\max}} d(cc_n)}$$

$$\bar{y}_1 = \frac{y_{\max} cc_n \Big|_{y_{\max}} - r_B cc_n \Big|_{r_B} - \int_{r_B}^{y_{\max}} (cc_n) dy}{cc_n \Big|_{y_{\max}} - cc_n \Big|_{r_B}} \quad (B4)$$

After splitting up the terms, the spanwise location of the inboard vortex is

$$\bar{y}_1 = \frac{y_{\max} cc_n \Big|_{y_{\max}} - r_B cc_n \Big|_{r_B} - \int_{r_B}^{y_{\max}} (cc_n) dy}{cc_n \Big|_{y_{\max}} - cc_n \Big|_{r_B}} \quad (B5)$$

The strength and position of the outboard vortex is obtained in the same fashion by changing the limits of integration.

$$\frac{\Gamma_{TE,2}}{V_{\infty}} = -\frac{1}{2} \int_{y_{\max}}^{r_B + \frac{b}{2}} d(cc_n)$$

$$= -\frac{1}{2} \left[cc_n \Big|_{r_B + \frac{b}{2}} - cc_n \Big|_{y_{\max}} \right] \quad (B6)$$

APPENDIX B

Since the spanwise loading is zero at the side edge, equation (B6) simplifies to

$$\frac{\Gamma_{TE,2}}{V_\infty} = \frac{1}{2} cc_n \Big|_{y_{max}} \quad (B7)$$

The spanwise location at the trailing edge is given by equation (B2) with the proper limits of integration

$$\bar{y}_2 = \frac{-\frac{1}{2} \int_{y_{max}}^{r_B + \frac{b}{2}} y \frac{\partial}{\partial y} (cc_n) dy}{-\frac{1}{2} \int_{y_{max}}^{r_B + \frac{b}{2}} d(cc_n)} \quad (B8)$$

After integration by parts, the result is

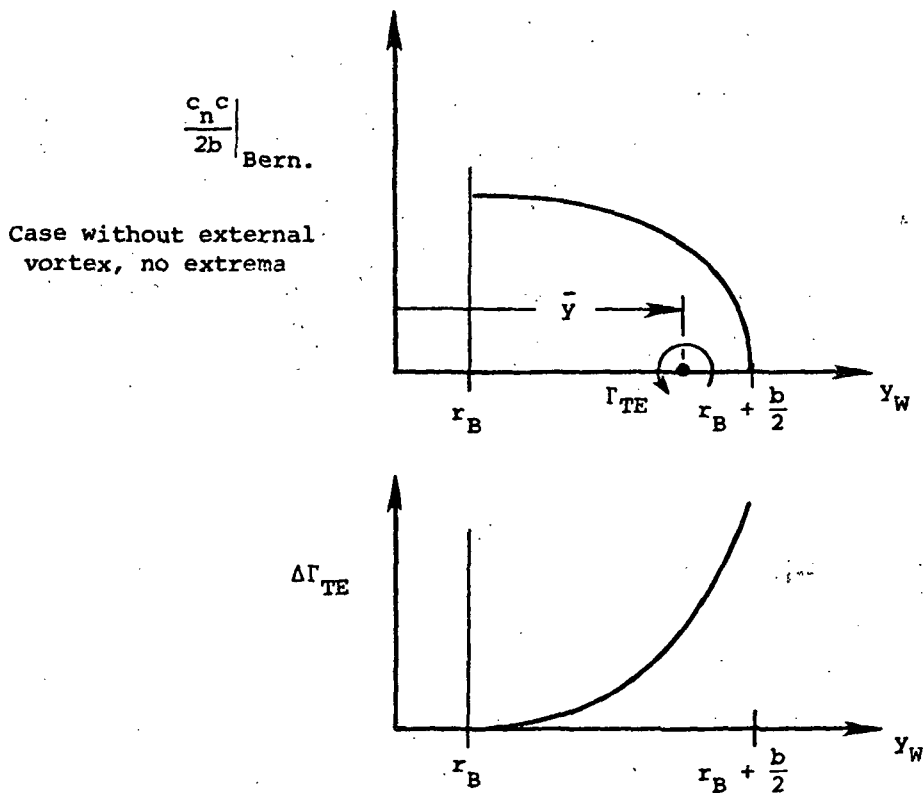
$$\begin{aligned} \bar{y}_2 &= \frac{\begin{array}{c} \nearrow \\ (r_B + \frac{b}{2}) cc_n \Big|_{r_B + \frac{b}{2}} \end{array} - y_{max} cc_n \Big|_{y_{max}} - \frac{\int_{y_{max}}^{r_B + \frac{b}{2}} (cc_n) dy}{\begin{array}{c} \nearrow \\ cc_n \Big|_{r_0 + \frac{b}{2}} \end{array} - cc_n \Big|_{y_{max}} - \frac{cc_n \Big|_{r_\Delta + \frac{b}{2}} - cc_n \Big|_{y_{max}}}{\begin{array}{c} \nearrow \\ -y_{max} cc_n \Big|_{y_{max}} \end{array} - \frac{\int_{y_{max}}^{r_B + \frac{b}{2}} (cc_n) dy}{\begin{array}{c} \nearrow \\ -cc_n \Big|_{y_{max}} \end{array}}} \end{aligned}$$

and finally

$$\bar{y}_2 = y_{\max} + \frac{\int_{y_{\max}}^{r_B + \frac{b}{2}} (cc_n) dy}{cc_n|_{y_{\max}}} \quad (B9)$$

If the span-load distribution exhibits additional extrema, equations (B3) and (B5) must be applied again with the appropriate limits of integration $y_{\max,1}$ to $y_{\max,2}$. For the outboard vortex, equations (B7) and (B9) hold.

For the sake of completeness, expressions for the strength and spanwise location of the trailing-edge vorticity will be given for the case of spanwise load distributions such as the one shown below. Only one concentrated vortex is associated with this type of distribution.



APPENDIX B

Equations (B1) and (B2) are applied again with the upper limit of integration changed to $r_B + \frac{b}{2}$. The results are

$$\frac{\Gamma_{TE}}{V_\infty} = -\frac{1}{2} \int_{r_B}^{r_B + \frac{b}{2}} \frac{\partial}{\partial y} (cc_n) dy \quad (B10)$$

$$\bar{y} = \frac{-\frac{1}{2} \int_{r_B}^{r_B + \frac{b}{2}} y \frac{\partial}{\partial y} (cc_n) dy}{-\frac{1}{2} \int_{r_B}^{r_B + \frac{b}{2}} \frac{\partial}{\partial y} (cc_n) dy} \quad (B11)$$

Integrating equation (B10) gives

$$\frac{\Gamma_{TE}}{V_\infty} = -\frac{1}{2} \left[cc_n \Big|_{r_B + \frac{b}{2}} - cc_n \Big|_{r_B} \right]$$

and since the wing loading vanishes at the side edges, there results

$$\frac{\Gamma_{TE}}{V_\infty} = \frac{1}{2} cc_n \Big|_{r_B} \quad (B12)$$

After integration by parts, equation (B11) becomes

$$\bar{y} = \frac{-\frac{1}{2} \left[y(cc_n) \Big|_{r_B}^{r_B + \frac{b}{2}} - \int_{r_B}^{r_B + \frac{b}{2}} (cc_n) dy \right]}{-\frac{1}{2} (cc_n) \Big|_{r_B}^{r_B + \frac{b}{2}}}$$

Making use again of the fact that the wing load is zero on the side edge simplifies the above equation to

$$\bar{y} = \frac{-r_B(cc_n) \Big|_{r_B} - \int_{r_B}^{r_B + \frac{b}{2}} (cc_n) dy}{-cc_n \Big|_{r_B}}$$

or

$$\bar{y} = r_B + \frac{\int_{r_B}^{r_B + \frac{b}{2}} (cc_n) dy}{cc_n \Big|_{r_B}} \quad (B13)$$

Subroutine SPNLD in program DEMON2 generates discrete values for the spanwise loading $c_n c / 2b$ at specific y locations. The extrema are searched for. The integrals appearing in equations (B5) and (B9) can then be represented by finite summations. For example, if for a fin the number of y stations up to y_{\max} is MSW_{\max} and the total number of y stations is $MSWR$ then the integrals are rewritten as follows.

$$\int_{r_B}^{y_{\max}} (cc_n) dy = 2b \sum_{i=1}^{MSW_{\max}} \frac{c_n c}{2b} \Big|_i \Delta y_i \quad (B14)$$

and

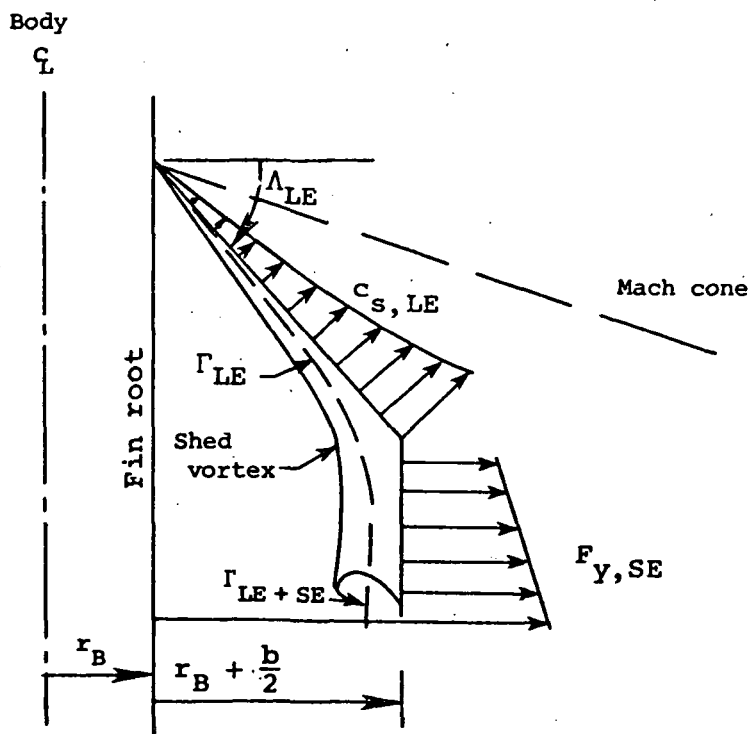
$$\int_{y_{\max}}^{r_B + \frac{b}{2}} (cc_n) dy = 2b \sum_{i=MSW_{\max}}^{MSWR} \frac{c_n c}{2b} \Big|_i \Delta y_i \quad (B15)$$

Subroutine SPNLD then proceeds to compute Γ_{TE}/V_{∞} designated as GAMMA and \bar{y} as YCG in accordance with equations (B5) and (B9). Note again that in all of the above the span loading is based on the Bernoulli pressure calculation.

APPENDIX C

CALCULATION OF LEADING- AND SIDE-EDGE VORTICITY DISTRIBUTIONS

This appendix contains a description of the improved method used to calculate leading- and side-edge vorticity characteristics associated with cruciform fins on bodies in supersonic flow. First the distributions of suction force acting on these edges must be determined. Then Polhamus' leading-edge suction analogy, reference 3, is used and applied also to the side edges. As a consequence of this analogy, the normal force acting on a lifting surface in supersonic flow is augmented by an amount proportional to the suction force acting on the leading- and side-edges for sharp edges. Consider the following sketch. It shows a general planform of a fin attached to a body. A schematic distribution of the suction force along the leading- and side-edge is also indicated. The objective is to determine the position and strength of the shed vortex from knowledge of the suction distribution. Note that if the leading edge is supersonic (this occurs when the Mach cone lies between the leading edge and the fin root chord), the suction force acting on that edge equals zero.



APPENDIX C

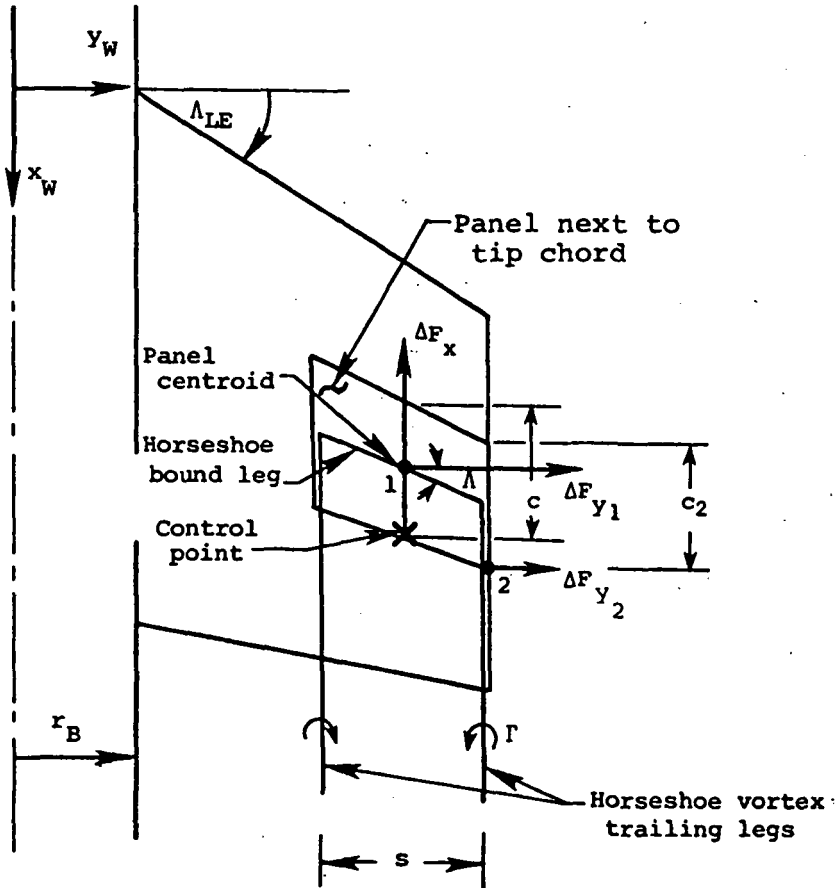
The method used to calculate the suction forces is described below in some detail. The subroutines in program DEMON2 concerned with the suction calculations are identified. The new procedure used for the side-edge suction calculation is pointed out. Calculated leading-edge thrust and suction-force distributions are compared with conical theory for the case of a slender delta wing. The predicted variation of side force along the side edge of a cropped delta wing is compared with two other theories. The side-edge suction factor, obtained using results computed by program DEMON2, is compared with conical theory for a case involving a rectangular wing.

After the suction distribution along the leading- and side-edges is described, the method used to convert the suction to edge vorticity is indicated.

Calculation of Suction Distribution

The present method used to calculate forces acting in the plane of a fin or wing in supersonic flow was first described in reference 1. For the sake of completeness, the important features and improvements to the method will be described here in the application to the determination of the suction forces acting on the leading edge and side edge of a fin.

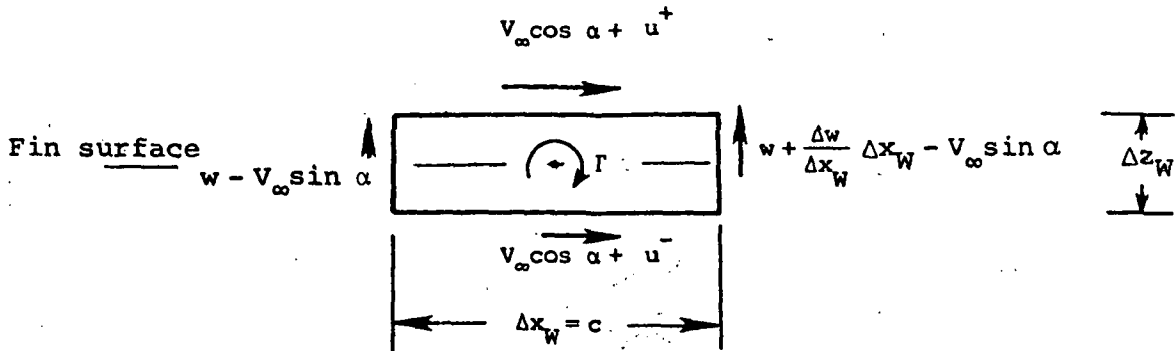
First, the constant u-velocity panel strengths are recast in vorticity strengths. In fact, an equivalent vortex lattice is constructed using the same geometric paneling layout. The bound portion of each horseshoe vortex passes through the centroid of each constant u-velocity panel while the trailing legs extend in the streamwise direction as shown in the following sketch for a horizontal fin attached to a body.



A vertical fin attached to a body is treated in a similar manner. The above sketch also shows the in-plane force ΔF_x (acting in the negative x_w -direction) and side forces ΔF_{y1} and ΔF_{y2} . The quantity ΔF_{y2} is the side force acting on the side edge for a distance $c_2/2$ forward of point 2 and a distance $c_2/2$ downstream of the point. It should be noted that the resultant in-plane forces must appear at the edges of the fin. The trailing edge has no such forces by virtue of the Kutta condition if subsonic, and in no event if supersonic. Thus, the elemental forces ΔF_x , ΔF_{y1} , and ΔF_{y2} summed over all the panels and vectorially added on a given fin appear either as leading- or side-edge suction forces.

The strength of the constant u-velocity panel is taken as the u-velocity in and immediately above its plane and is denoted u^+ . The perturbation velocity immediately below, u^- , equals $-u^+$. The equivalent circulation can then be determined from the closed path (clockwise) integral of the product of the total velocity tangential to the path and the path length shown in the following sketch. Neglecting terms of higher

APPENDIX C



order in Δx , the equivalent circulation strength Γ is then given by

$$\frac{\Gamma}{V_\infty} = 2 c \frac{u^+}{V_\infty} \quad (C1)$$

In subroutine LOADS of program DEMON2, the linear loading pressure acting on a panel is used instead of the panel strength u^+ in the determination of the equivalent circulation strengths. The linear loading pressure is related to the constant u-velocity panel strength as follows.

$$\left. \frac{\Delta p}{q} \right|_{\text{linear}} = 4 \frac{u^+}{V_\infty} \quad (C2)$$

The circulation strengths are calculated using equations (C1) and (C2). The velocity normal to the panels induced by the constant u-velocity panels distributed on all fins and the body interference shell are then calculated and added to the contribution to the velocity normal to the fin induced by the singularities modeling the body. The in-plane forces can be calculated using the Kutta-Joukowski law for lift acting on a vortex filament. The forces acting on the bound vortex with sweep angle Λ and the side force acting on the outboard trailing leg of one panel are given by the following expressions. Angle α is the sum of the angle of pitch added to the fin deflection angle if applicable.

$$\frac{\Delta F_x}{q} = 2 s \frac{\Gamma}{V_\infty} \left(\sin \alpha + \frac{w_1}{V_\infty} \right) \quad (C3)$$

$$\frac{\Delta F_{y_1}}{q} = \frac{\Delta F_x}{q} \tan \Lambda \quad (C4)$$

$$\frac{\Delta F_{y_2}}{q} = 2 c_2 \frac{\Delta \Gamma}{V_\infty} \left(\sin \alpha + \frac{w_2}{V_\infty} \right) \quad (C5)$$

In equation (C5) $\Delta \Gamma$ is the sum of all the trailing vorticity along the panel side edge for all panels in the chordwise row ahead of the outboard aft corner. For the last panel c_2 is replaced by $c_2/2$. The above panel forces apply to panels on a horizontal fin. For panels on the vertical fin, y_1 and y_2 are replaced by z_1 and z_2 , w_1 and w_2 are replaced by v_1 and v_2 , $\sin \alpha$ is replaced by $\sin \beta$ and the sign inside the brackets is changed to negative. Perturbation upwash velocity w_1 is computed at the centroid of the panel and w_2 is computed at the aft outboard corner. The forces at the centroid, F_x and F_{y_1} divided by the dynamic pressure are computed in subroutine LOADS. The side force on the outboard leg is calculated in subroutine SPNLD of program DEMON2.

The forces calculated for every panel in accordance with equations (C3) through (C5) can be summed to obtain the net in-plane forces acting on a column (strip in chordwise direction) of panels and on the entire fin. If the number of panels in a given column is large, the vector sum of forces ΔF_x and $(\Delta F_{y_1} + \Delta F_{y_2})$ equals the suction force for that column acting in the direction normal to the leading edge. In order to obtain good results for the leading edge without having to resort to a large number of panels it was found advantageous to calculate the suction force from the sum of the F_x forces and the leading-edge sweep of the fin under consideration. The section coefficient for suction, c_s , is the suction force per unit span divided by qc , where c is the local chord. This section coefficient is calculated in nondimensional form in

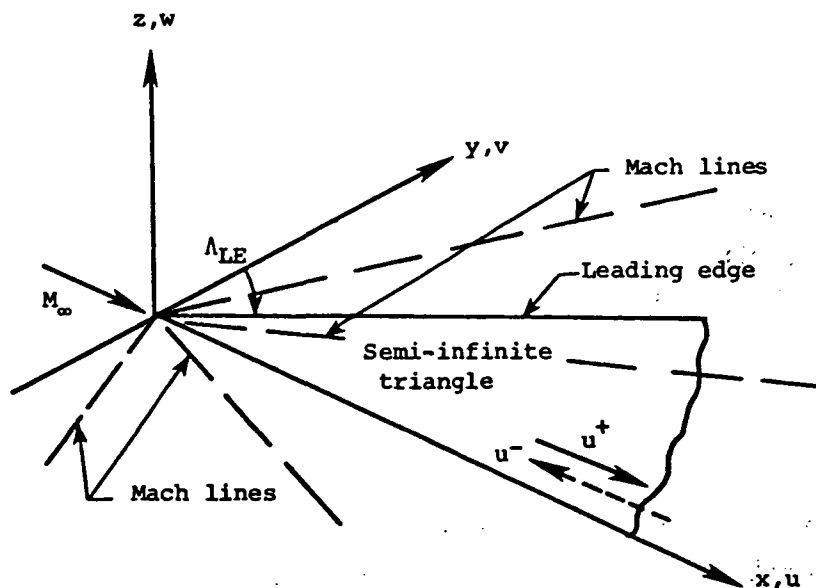
APPENDIX C

accordance with

$$\frac{c_s c}{2b} = \frac{\sum_{i=1}^{NCW} \frac{\Delta F_x}{q} |i}{s (2b) \cos \lambda_{LE}} \quad (C6)$$

by subroutine SPNLD of program DEMON2. The index NCW is the number of panels in the chordwise direction. Panel width s is constant for a column of panels but can vary from one column to the next. By adding the contributions from all constant u -velocity panels distributed on a fin, excluding the outboard leg side forces of the panels at the tipchord, the summed in-plane forces F_x , F_{y_1} and F_{y_2} for the leading edge are computed in subroutine SPNLD. When divided by q_∞ , they are designated SUMFX, SUMFY1 and SUMFY2, respectively, for horizontal fins (a horizontal fin lies in the $z_B = 0$ plane; see figure 1). Total forces F_x , F_{z_1} and F_{z_2} are designated SUMFX, SUMFZ1 and SUMFZ2, respectively, for the vertical fins (a vertical fin lies in the $y_B = 0$ plane). The forces acting on the outboard legs of panels at the fin tipchords are added separately and designated SUMFT2 in subroutine SPNLD. The sum represents the suction force on the side edge of the fin. Velocity components w_2/V_∞ (for horizontal fins) and v_2/V_∞ (for vertical fins) calculated at points on the side edge of fins with subsonic leading edges are calculated in accordance with the special procedure described next.

Consider a basic semi-infinite triangle with its apex at one of the corners of a constant u -velocity panel. The sketch below shows one semi-infinite triangle with two Mach lines corresponding to two free-stream Mach numbers. When the leading edge of the triangle lies inside the Mach cone, it is a subsonic leading edge. If it lies outside the Mach cone, the edge is supersonic. The outboard aft corner points of panels at the side edge, marked 2 on the second sketch of this appendix, lie on the extended leading and extended trailing edges of many panels inboard of the side edge panels. In particular, the point lies on the trailing edge of the panel shown in the sketch. If the edges are subsonic, the



contributions to the upwash from the semi-infinite triangles on whose leading edge the point lies are in fact singular as shown in figure II-1(a) in reference 7. To avoid numerical difficulties, subroutine VELO in program DEMON2 sets the downwash equal to zero. As a consequence, the points on the side edge of a fin with subsonic leading and trailing edges only receive upwash contributions from those basic semi-infinite triangles whose leading edges do not pass through the points. It was found that the side force calculated on the side edge of a cropped delta wing using the upwash, w_2 , calculated this way was underestimated. By moving the points on the side edge off the fin a distance equal to the width of the nearest panel width, the values of the upwash are increased and more reasonable values for the side edge forces are obtained. For a cropped delta wing with supersonic leading and trailing edges the above problem does not exist. The upwash at the leading edge is discontinuous in this case; refer to figure II-1(c) in reference 7. The mean value is used.

A few examples will now be discussed. Consider figure C-1 first. It shows the distribution of thrust and suction along the leading edge of a delta wing with aspect ratio equal to 1. The Mach number is $\sqrt{2}$. The conical theory results for the linear thrust distribution shown by the lower dashed line, is based on the thrust coefficient calculated from the lift and drag coefficient for small angle of attack as follows.

APPENDIX C

$$C_T = \alpha C_L - \left(\frac{C_{D_i}}{C_L^2} \right) C_L = \frac{T}{q c_r (b/2)} \quad (C7)$$

For a delta wing, page 292 in reference 8 contains expressions for lift and drag. The slope of the spanwise thrust distribution $c c_t/2b$ for the half wing is then related to the thrust coefficient by

$$k_T = \frac{\frac{C_T}{2} c_r}{2b} \quad (C8)$$

where c_r is the rootchord. The suction coefficient of one wing half is related to the thrust through the leading edge sweep Λ of the leading edge.

$$C_S \Big|_{\text{half wing}} = \frac{\frac{C_T}{2}}{\cos \Lambda} = \frac{S}{c_r (b/2) q} \quad (C9)$$

Therefore, the linear slope of the spanwise suction distribution is given by

$$k_S = \frac{C_S c_r}{2b} = \frac{k_T}{\cos \Lambda} \quad (C10)$$

The results calculated by subroutine SPNLD in program DEMON2 with a layout of five chordwise and 20 spanwise panels agree well with the linear thrust distribution from conical theory. The suction coefficient is actually calculated on the basis of vectorially adding the forward and side forces acting on all the constant u-velocity panels. The results calculated from the program are higher than the conical result from the 70 percent spanwise station on although the curve tends to return to the conical value near the tip. Nevertheless, the resultant suction force calculated this way was almost exactly normal to the leading edge. If the values of $(c_t c)/2b$ are simply divided by $\cos \Lambda$, the resulting $(c_s c)/2b$ values, as indicated by the crosses, are very close to the conical results. However, the suction as calculated in the program is away from the normal to the leading edge by a few degrees.

The distribution of the suction force along the side edge of a cropped delta wing is shown in figure C-2. Results calculated by subroutine SPNLD of program DEMON2 are indicated by the solid circles. The solid line is a distribution calculated on the basis of conical theory and given by an adapted version of equation 10 on page 8 of reference 16. Certain restrictions are imposed on the application of the expression shown in figure C-2. For example, the Mach lines from the leading edges of the tip chords must not intersect the opposite wing tip. The dashed line represents an exact linear theory result obtained by J. N. Nielsen using some of the results derived in reference 17 and the lift-cancellation method. Other than close to the leading and trailing edges of the tip chord, the program results match the exact theory well. Overall suction force along the side edge calculated by the program is slightly below that calculated by the linear theory. For this case, the leading edges and trailing edges of the panels along the side edge are subsonic near the leading edge of the side edge and supersonic near the trailing edge. This is a mixed case and the offset scheme described above may not apply to all of the points on the side edge.

The last example of suction force calculation is shown in figure C-3 for the case of a rectangular wing. The result shown by the dashed line is based on conical theory and can be obtained by the methods employed by Lamar in reference 18 for rectangular wings. The solid line is the result calculated by the program using the following definition of $K_{V,SE}$, the side-edge suction coefficient.

$$K_{V,SE} = \frac{2(F_{Y_2} + F_{T_2})}{qS_{Ref}\sin^2\alpha} \quad (C11)$$

Quantity F_{Y_2}/q (SUMFY2 in subroutine SPNLD) is the sum of the in-plane forces, divided by the dynamic pressure, in the y_w -direction acting at the outboard aft corner of all the panels except those next to the side edge. Quantity F_{T_2}/q (SUMFT2 in subroutine SPNLD) is the sum of the forces, divided by the dynamic pressure, in the y_w -direction acting on the outboard aft corners of the panels at the side edge. Results were calculated for five panels in the chordwise direction as a function of

APPENDIX C

the number of panels in the spanwise direction. The solid line approaches the conical theory result as the number of spanwise panels is increased. Increasing the number of chordwise panels also improves the agreement. With 10 along the chord and 15 along the span, the point marked by the cross corresponds to $K_{V,SE} = 1.099$.

Conversion of Suction to Edge Vorticity

With the distribution of suction along the leading and side edges of a given lifting surface calculated by the methods described above, the Polhamus analogy is used to convert the suction to additional normal force and accompanying edge vorticity. The analogy is described in reference 3 and states that at high angles of attack the normal force acting on a delta type wing is augmented by an amount proportional to the suction force acting on the leading edge. The additional lift is associated with flow separation along swept leading edges. This analogy is extended to the side edges of a wing or fin of general planform.

Section 6.2.3 contains a description of the procedure used to compute the increment in normal force due to edge vorticity from the suction force coefficients calculatable from quantities in the output of program DEMON2. In the following, the method for relating the distribution along the leading and side edges of suction force to the distribution of augmented normal force is indicated. Then, a discussion follows concerning the analysis required to relate the distribution of edge vorticity to the distribution of augmented normal force.

For the leading edge, the spanwise distribution of suction is given by equation (C6). Define $K_{V,LE}$, assumed constant, as the proportion of the suction converted to normal force

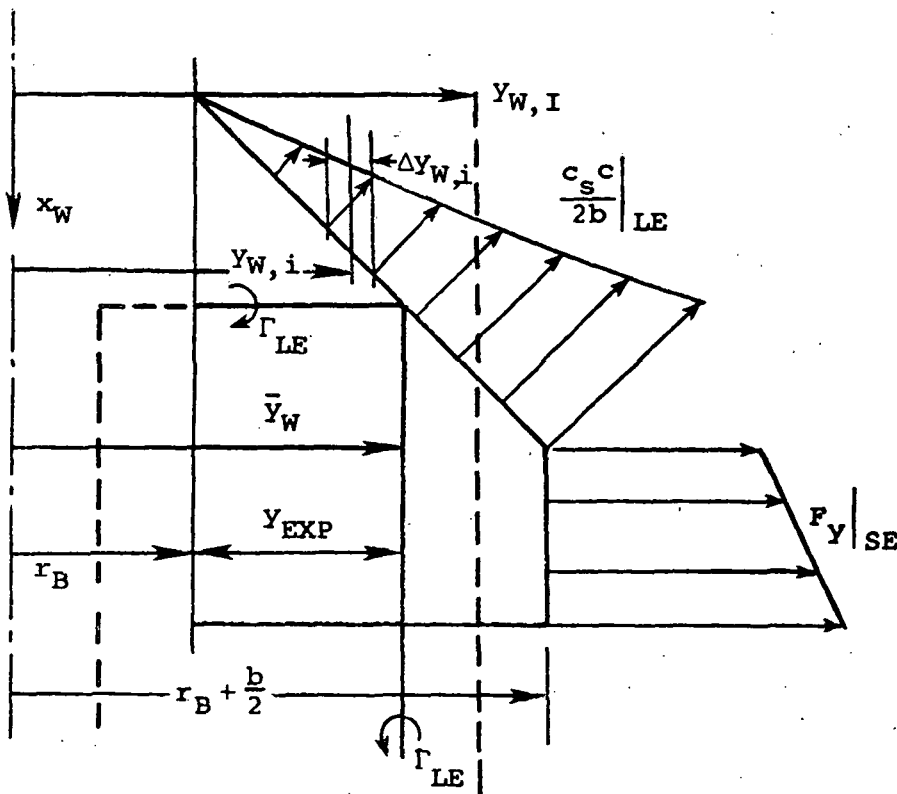
$$K_{V,LE} = \frac{\frac{\Delta c_n c}{2b}}{\frac{c_s c}{2b}} \quad (C12)$$

This factor is called the vortex lift vector for the leading edge. It is a function of leading edge sweep, Mach number and leading-edge geometry. For sharp edges, figure 9(a) in reference 4 contains graphs from which estimates can be obtained for $K_{V,LE}$ values as a function of aspect

ratio and Mach number. In accordance with equation (30), the vortex lift factor $K_{V,LE}$ is also applicable to the suction coefficient associated with the entire leading edge to give the increment in normal force due to leading-edge vorticity (for one wing half)

$$K_{V,LE} = \frac{C_N|_{L.E. \text{ vorticity}}}{C_S|_{L.E.}} \quad (C13)$$

Refer now to the sketch below. Schematic distributions of suction



are shown for the leading and side edge of the wing or fin attached to a body. Up to given spanwise position $y_{W,I}$ subroutine SPNLD of program DEMON2 integrates the spanwise suction distribution. The integrated quantity is named CSINT. It is equal to the suction force divided by $2b$ ($b/2$ is the exposed semispan of the fin) accumulated up to spanwise location $y_{W,I}$.

$$CSINT = \sum_{i=1}^I \frac{c_s c}{2b} |_{i} \Delta y_{W,i} \quad (C14)$$

APPENDIX C

The moment of the suction force divided by factor $2b$ is formed as follows.

$$CSMOM = \sum_{i=1}^I y_{W,i} \left. \frac{c_s c}{2b} \right|_i \Delta y_{W,i} \quad (C15)$$

The spanwise location of the "center of gravity" of the suction distribution along the leading edge up to $y_{W,I}$ is given by the ratio of the moment over the force.

$$\left. \begin{aligned} \bar{y}_W &= \frac{CSMOM}{CSINT} \\ y_{EXP} &= \bar{y}_W - r_b \end{aligned} \right\} \quad (C16)$$

A horseshoe vortex is laid-out on the wing or fin attached to the body. The outboard trailing filament is at spanwise position \bar{y}_W . The lift acting on the bound or spanwise leg is made equal to the increment in normal force due to leading-edge vorticity. Up to spanwise location $y_{W,I}$, the increment in normal force in coefficient form is given by equation (C13) in conjunction with equation (C14).

$$C_N \Big|_{L.E. \text{ vorticity}} = K_{V,LE} (CSINT) 2b \quad (C17)$$

Taking the component in the direction of the lift force results in

$$C_L \Big|_{L.E. \text{ vorticity}} = K_{V,LE} (CSINT) 2b \cos \alpha \quad (C18)$$

where α is the angle of attack seen by the lifting surface in question. Then, with the Kutta-Joukowski law for lift on a vortex filament, the vortex strength Γ_{LE} associated with the added lift can be obtained from the following approximate relation.

$$\frac{\Gamma_{LE}}{V_\infty} = \frac{K_{V,LE} (CSINT) 2b \cos \alpha}{2y_{EXP}} \quad (C19)$$

This relation is correct for a wing alone ($r_b = 0$) for which the span of the horseshoe vortex would be equal to $2\bar{y}_W$ or $2y_{EXP}$. However, for a wing or fin attached to a body as shown in the sketch above, the span or

width of the horseshoe vortex is the difference between \bar{y}_W and the distance from the body centerline to the image (shown dashed) of the outboard trailing filament, r_b^2/\bar{y}_W . At the present time, equation (C19) is programmed in subroutine SPNLD of program DEMON2. In any event, equation (C19) provides the spanwise distribution of Γ_{LE} and its location \bar{y}_W is given by equation (C16).

A similar procedure is followed for determining the strength and spanwise location of vorticity along the side edge. The summing process indicated in equation (C14) to calculate quantity CSINT is continued along the side edge using the side force designated $FT_2(J_{TIP})$ and computed in accordance with equation (C5). The vorticity associated with the added normal force is also determined by expressions (C18) and (C19) replacing $K_{V,LE}$ with $K_{V,SE}$. The same remarks made above in connection with the spanwise width apply. In addition, it is recommended to set $K_{V,SE} = K_{V,LE}$ for use in the program as written at the present time. Note that these vortex lift factors have the default value 0.5 in main routine CRFWBD of program DEMON2.

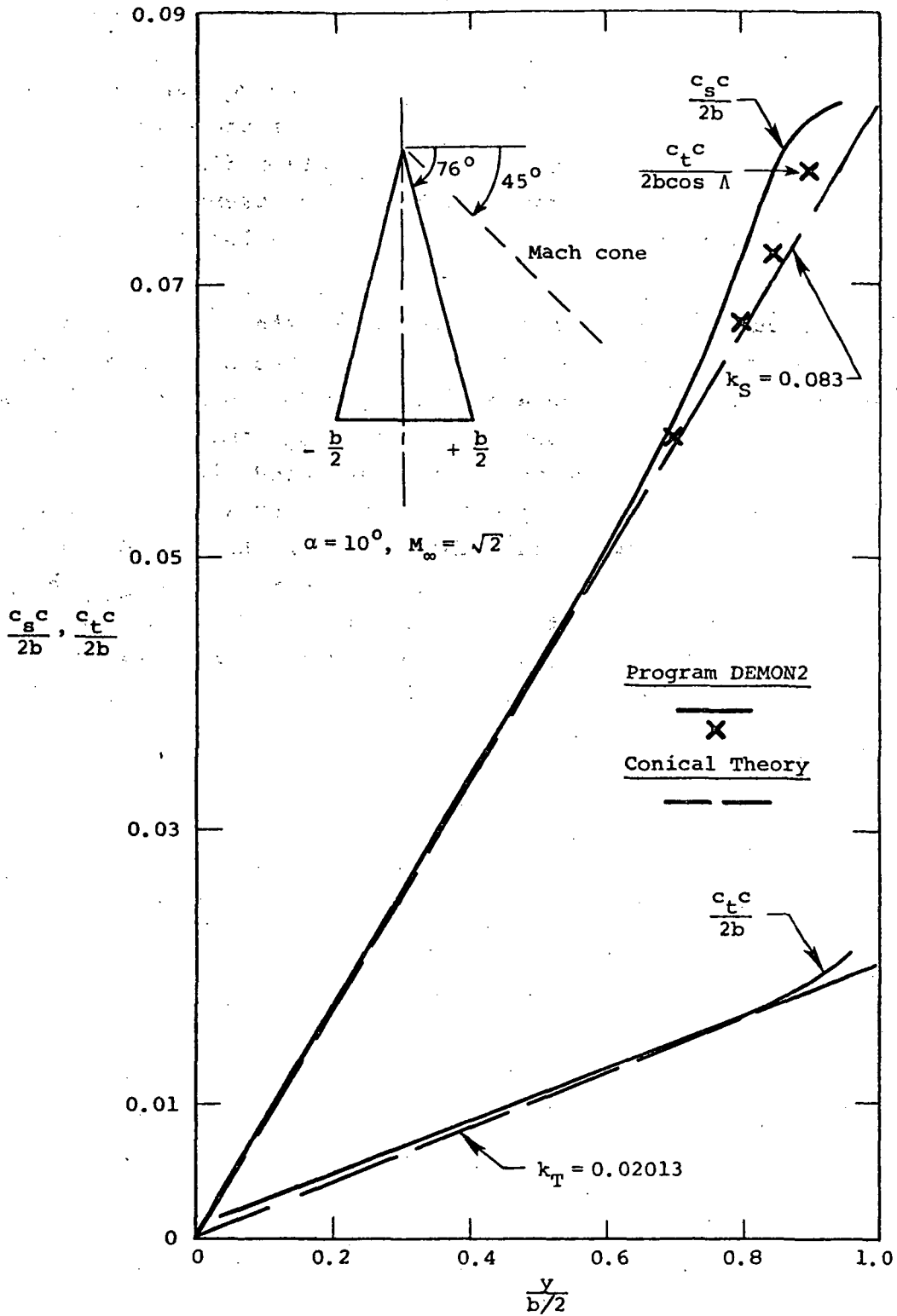
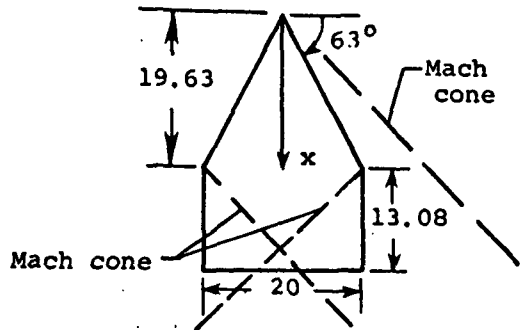


Figure C-1.- Spanload distribution of suction and thrust for a delta wing with aspect ratio 1.



$R = 0.87$
 $M_\infty = 1.5$
 $\alpha = 10^\circ$

Number of Chordwise Panels	Number of Spanwise Panels
Program DEMON2	
5	● 10

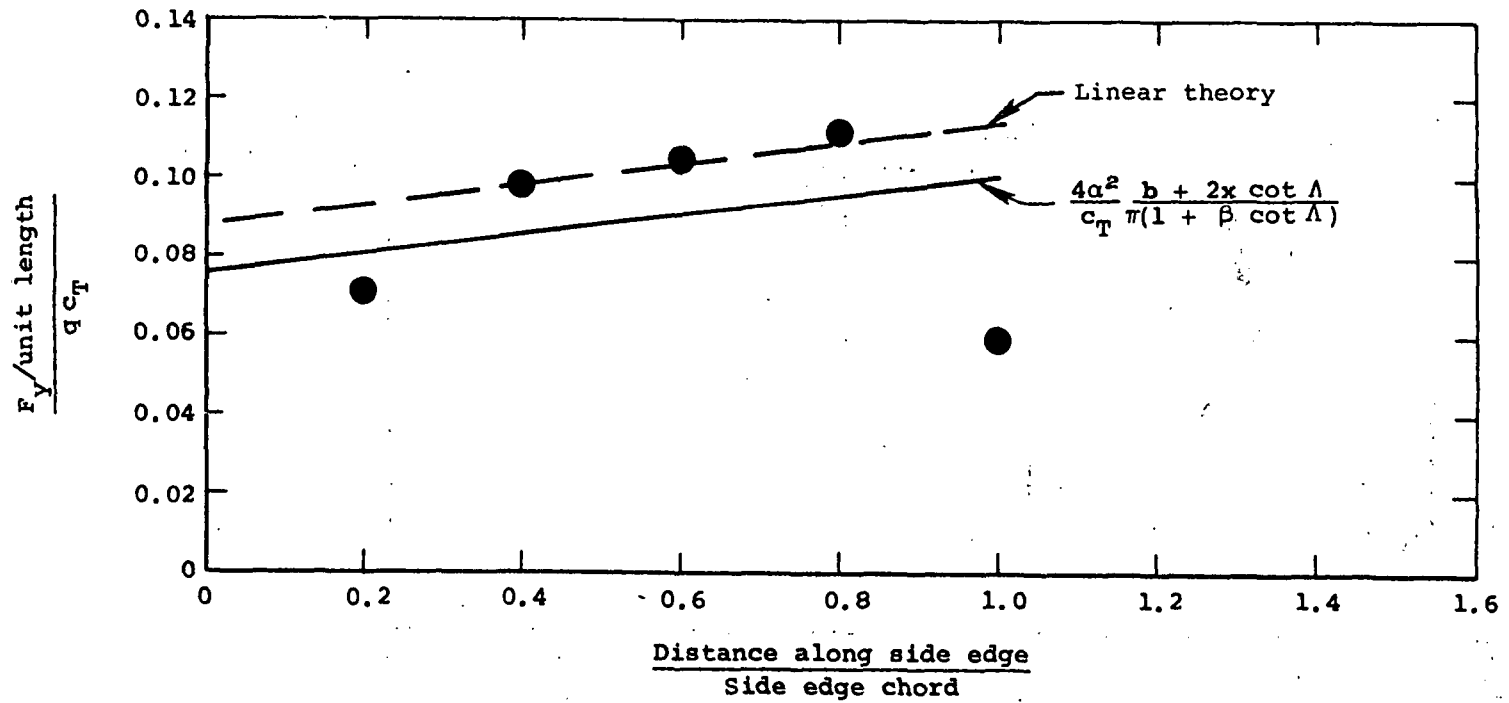


Figure C-2.- Distribution of suction force along side edge of a cropped delta wing; $b = 20$, $c_T = 13.08$, $\Lambda = 63^\circ$.

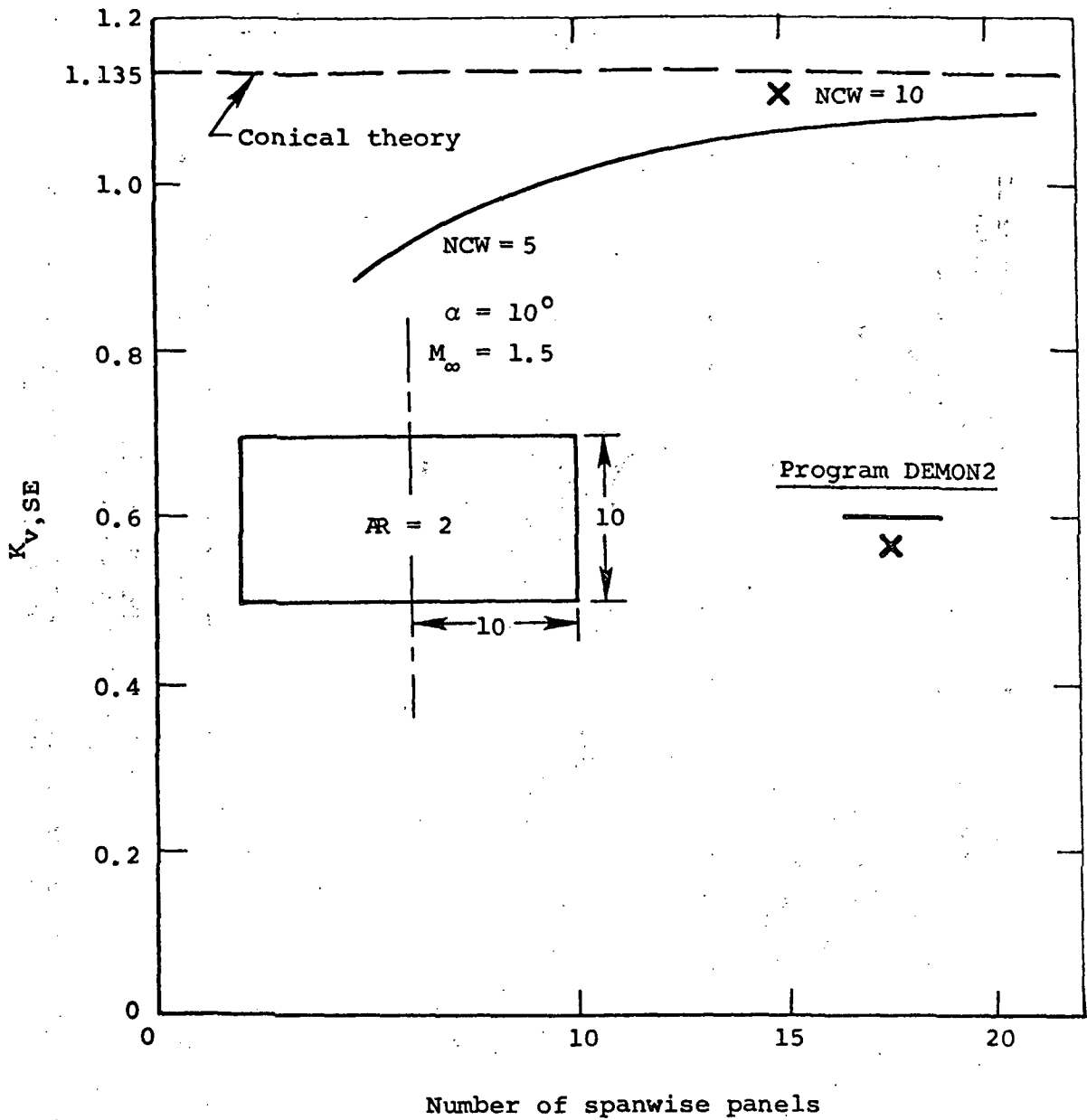
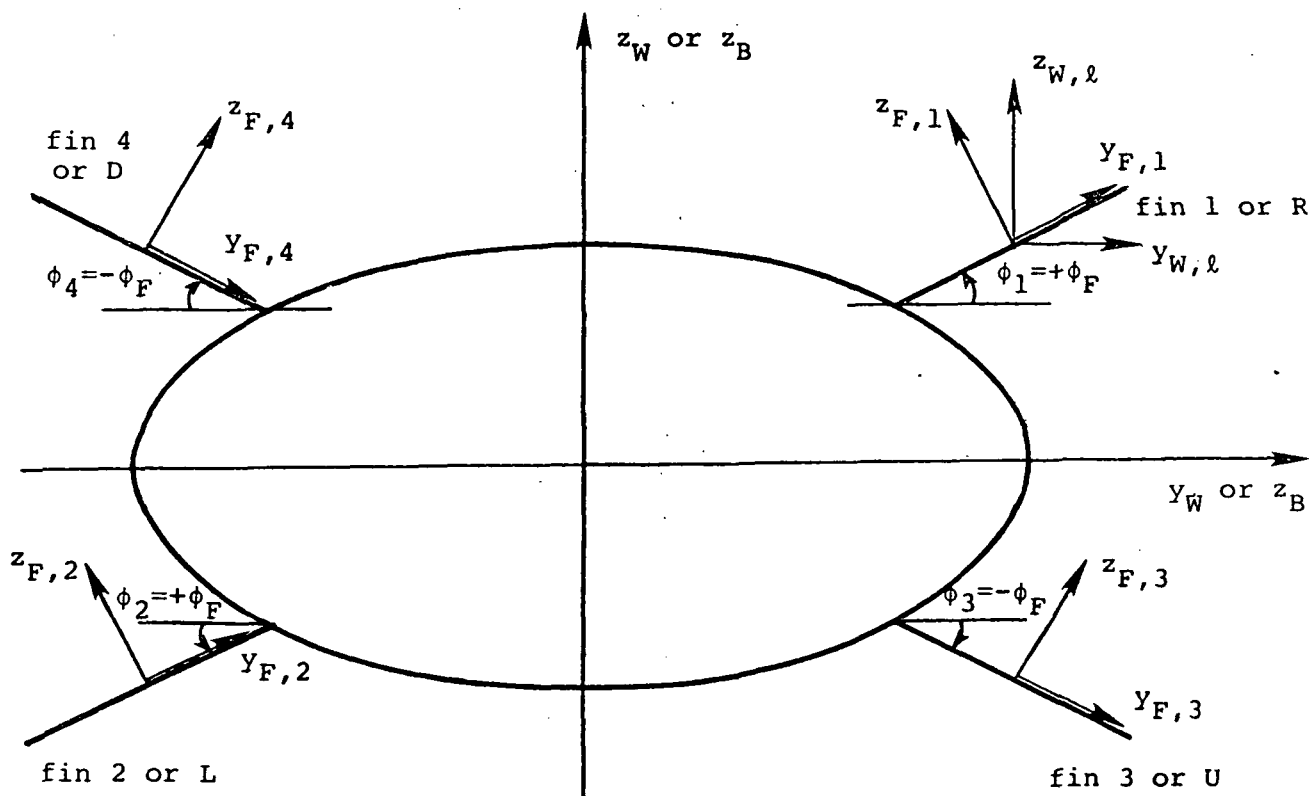


Figure C-3.- Side-edge suction factor $K_{V,SE}$ for a rectangular wing.

APPENDIX D

TRANSFORMATION FROM FIN COORDINATES TO WING OR BODY REFERENCE COORDINATE SYSTEM AND VICE VERSA

In the calculation of the influence of one constant u-velocity panel at the control point of another or at a given field point, the following procedure is used. The coordinates of the four corners of all the constant u-velocity panels are calculated by subroutine LAYOUT in program DEMON2 in the wing coordinate system (x_W, y_W, z_W) . The coordinates of the control points (or field points) are also determined by subroutine LAYOUT (or specified) in the wing coordinate system. The first step is to calculate the coordinates of the point relative to the corners of the influencing panel under consideration. Then these local coordinates $(x_{W,\ell}, y_{W,\ell}, z_{W,\ell})$, which are parallel to the wing coordinate system, are transformed to a panel coordinate system with the y_F and x_F axes in the plane of the fin. In this process the origin at one corner of the constant u-velocity panel remains fixed. Thus, the transformation is a simple rotation through the applicable fin dihedral angle. Only one local coordinate system is shown on each fin in the sketch below.



APPENDIX D

For the right upper and left lower fins, fin 1 or fin R and fin 2 or fin L, the local wing to local fin coordinate transformation is stated as follows.

$$\left. \begin{aligned} Y_{F,1 \text{ or } 2} &= Y_{W,\ell} \cos \phi_{1 \text{ or } 2} + z_{W,\ell} \sin \phi_{1 \text{ or } 2} \\ z_{F,1 \text{ or } 2} &= z_{W,\ell} \cos \phi_{1 \text{ or } 2} - Y_{W,\ell} \sin \phi_{1 \text{ or } 2} \end{aligned} \right\} \quad (D1)$$

Fin dihedral angles ϕ_1 and ϕ_2 are taken equal to the specified fin dihedral angle, $+\phi_F$, also shown in figure 3. The coordinate system rotation for the left upper and right lower fins, fin 4 or fin D and fin 3 or fin U is given by

$$\left. \begin{aligned} Y_{F,3 \text{ or } 4} &= Y_{W,\ell} \cos \phi_{3 \text{ or } 4} - z_{W,\ell} \sin \phi_{3 \text{ or } 4} \\ z_{F,3 \text{ or } 4} &= z_{W,\ell} \cos \phi_{3 \text{ or } 4} + Y_{W,\ell} \sin \phi_{3 \text{ or } 4} \end{aligned} \right\} \quad (D2)$$

Fin dihedral angles ϕ_3 and ϕ_4 are taken equal to negative specified fin dihedral angle, $-\phi_F$. Thus, the transformation given by equations (D1) and (D2) are in fact the same provided the negative dihedral angle, $-\phi_F$, associated with fins 3 and 4 is substituted in equation (D1). The local fin to local wing coordinate transformation is given by the following expression. For the right upper and left lower fins, fin 1 or fin R and fin 2 or fin L, the transformation is

$$\left. \begin{aligned} Y_{W,\ell} &= Y_{F,1 \text{ or } 2} \cos \phi_{1 \text{ or } 2} - z_{F,1 \text{ or } 2} \sin \phi_{1 \text{ or } 2} \\ z_{W,\ell} &= z_{F,1 \text{ or } 2} \cos \phi_{1 \text{ or } 2} + Y_{F,1 \text{ or } 2} \sin \phi_{1 \text{ or } 2} \end{aligned} \right\} \quad (D3)$$

Fin dihedral angles ϕ_1 and ϕ_2 are equal to positive fin dihedral angle, $+\phi_F$. The local fin to local wing coordinate transformation for the left upper and right lower fins, fin 4 or fin D and fin 3 or U can be expressed as

$$\left. \begin{aligned} Y_{W,\ell} &= Y_{F,3 \text{ or } 4} \cos \phi_{3 \text{ or } 4} + z_{F,3 \text{ or } 4} \sin \phi_{3 \text{ or } 4} \\ z_{W,\ell} &= z_{F,3 \text{ or } 4} \cos \phi_{3 \text{ or } 4} - Y_{F,3 \text{ or } 4} \sin \phi_{3 \text{ or } 4} \end{aligned} \right\} \quad (D4)$$

Fin dihedral angles ϕ_3 and ϕ_4 are equal to negative specified fin dihedral angle, $-\phi_F$. Again, equation (D4) can be obtained from equation (D3) by accounting for the negative dihedral angle, $-\phi_F$, associated with fins 3 and 4.

The transformations indicated by equations (D1) and (D3) are programmed in subroutine ROTATE of program DEMON2. The former is accomplished through entry point ROTWF and the latter through entry point ROTFW in subroutine ROTATE.

The transformation given by equation (D1) also applies to the flow velocity components in the wing coordinate system v_W, w_W aligned with the y_W and z_W axes. After calculating the components v_W and w_W , the velocity components v_F and w_F in the local panel or fin coordinate system can be determined. Conversely, equation (D3) is used to transform velocities in the local panel or fin coordinate system to the local wing coordinate system which is aligned with the reference wing coordinate system (x_W, y_W, z_W). The following appendix concerned with the flow boundary condition makes use of the above equations.

APPENDIX E

INTERDIGITATED FINS, BOUNDARY CONDITIONS

The flow tangency condition states that the net flow velocity normal to the fin must equal zero. Besides the free-stream component, there are external contributions from the body source panels calculated by program WDYBDY and effects induced by vortices associated with the body nose and the monoplane wing calculated by subroutine VVELS in program DEMON2. For all of these external contributions, the coordinate system in which they are expressed is the body or wing reference coordinate system. Body and wing coordinate systems are parallel to one another; see figure 1. The former has its origin at the body nose while the latter has its origin on the body centerline at the axial location of the wing or fin rootchord leading edge. Thus, in order to determine the external contribution to the flow velocity normal to the fin, the components must be resolved and added as follows.

Referring to figure 1, the sidewash, v_W or v_B is aligned with the y_W or y_B axis. Upwash w_W or w_B is in the z_W or z_B direction. The component of the flow normal to the fin surface at the j 'th control point ($x_{CPT,j}$, $y_{CPT,j}$, $z_{CPT,j}$) can be determined from the transformations discussed in Appendix D. For example, the normal velocity components on the right upper fin, fin 1 or fin R are obtained from

$$v_{N,j} = w_{W,j} \cos \phi_1 - v_{W,j} \sin \phi_1 \quad (E1)$$

In this instance the fin dihedral angle ϕ_1 equals the specified fin dihedral angle ϕ_F listed as PHIDIH in namelist \$INPUT of routine CRFWBD in program DEMON2. Angle ϕ_F is also indicated in figure 3. The velocity normal to the left lower fin, fin 2 or fin L is also given by equation (E1) with fin dihedral angle ϕ_2 taken equal to dihedral angle ϕ_F . For the right lower fin, fin 3 or fin U, the velocity normal to the fin surface at the j 'th control point is obtained from the velocity components expressed in the wing coordinate system as follows.

$$v_{N,j} = w_{W,j} \cos \phi_3 + v_{W,j} \sin \phi_3 \quad (E2)$$

APPENDIX E

In this equation, angle ϕ_3 is taken equal to negative specified fin dihedral angle, $-\phi_F$. The velocity normal to the left upper fin is also given by equation (E2) substituting angle ϕ_4 for angle ϕ_3 . Angle ϕ_4 equals negative fin dihedral angle, $-\phi_F$.

Expressions (E1) and (E2) cause the normal velocity component to be aligned with the direction of the normal load C_N shown in figure 3 for each fin. The contribution from the free stream can be expressed in components directed along the wing or body coordinate system.

$$\left. \begin{aligned} W_W &= V_\infty \sin \alpha \\ V_W &= -V_\infty \sin \beta \end{aligned} \right\} \quad (E3)$$

where α is angle of pitch and β is angle of sideslip. These angles are calculated from the combined angle of attack, α_c , and the angle of roll, ϕ , in accordance with the pitch-roll sequence described in the section entitled GENERAL APPROACH, equation (12).

All external contributions to the normal velocity component are added and substituted directly into equations (E1) and (E2). The sum of all the external contributions to the normal velocity at a control point on a fin must be offset by the sum of the normal velocity components induced by all constant u-velocity panels on the fins and the body interference shell. In computer program DEMON2, the contributions from the constant u-velocity panels on the fins or interference shell are determined in a coordinate system associated with the plane of the panel in question and then transformed to the wing or body coordinate system. Equations (E1) and (E2) together with the transformations discussed in Appendix D are subsequently employed to determine the normal component induced by one panel at the control point of another. The result is a set of simultaneous equations from which the unknown panel strengths can be calculated. Thickness effects from the interdigitated tail fin are not accounted for. For the case of cruciform fins, thickness effects can be accounted for and detailed expressions for the boundary condition are given in section 2 entitled GENERAL APPROACH.

APPENDIX F

INTERDIGITATED FINS, FORCE AND MOMENT CALCULATIONS

The following force- and moment-coefficient calculations are programmed in subroutine LOADS of program DEMON2. Each fin of an interdigitated fin configuration is dealt with separately.

Right upper fin:

Let $C_{N,j}$ be equal to the normal-force coefficient for one constant u-velocity panel with control point coordinates $x_{CPT,j}$, $y_{CPT,j}$ and $z_{CPT,j}$ specified in the wing coordinate system (x_W, y_W, z_W). The positive sense of the normal force is shown in figure 3. Then the components in the positive z_W and y_W or z_B and y_B directions are given by

$$\left. \begin{aligned} C_{z,j} &= C_{N,j} \cos \phi_F \\ C_{y,j} &= -C_{N,j} \sin \phi_F \end{aligned} \right\} \quad (F1)$$

in accordance with the rotational coordinate transformation discussed in Appendix D. The pitching moment in the body coordinate system about a specified moment center ($X_M, 0, Z_M$) is defined as a moment with its axis normal to the $y_B = 0$ or $y_W = 0$ plane. Clockwise rotation about the y_B or y_W axis when viewing along its positive direction corresponds to positive pitching moment (positive pitching moment causes nose up). For one panel, the contribution to the pitching-moment coefficient is given by

$$C_{m,j} = -C_{z,j} \frac{(x_{CPT,j} - X_M)}{l_{ref}} \quad (F2)$$

The yawing moment in the body coordinate system about a specified moment center ($X_M, 0, Z_M$) is defined as a moment with its axis normal to the $z_B = 0$ or $z_W = 0$ plane. Clockwise rotation about the z_B or z_W axis when viewing along its negative direction corresponds to positive yawing moment (nose to right is positive yawing). The contribution from one panel equals

APPENDIX F

$$C_{n,j} = -C_{y,j} \frac{(x_{CPT,j} - XM)}{l_{ref}} \quad (F3)$$

Rolling moment measured about the body centerline is positive if the right fin(s) move in the clockwise direction viewing upstream. Both components $C_{z,j}$ and $C_{y,j}$ contribute to the rolling-moment coefficient. Thus, the contribution from one panel is

$$C_{\ell,j} = \frac{-C_{z,j} y_{CPT,j} + C_{y,j} z_{CPT,j}}{l_{ref}} \quad (F4)$$

By adding all contributions from the constant u-velocity panels on the right upper fin, the total force and moment coefficients acting on that fin can be determined. Thus for the upper right fin designated Fin 1 or Fin R, the forces acting on it in the z_W and y_W directions, respectively, are given in coefficient form as

$$\left. \begin{aligned} C_{z,1} \text{ or } C_{z,R} &= \sum_{j=1}^{NRP} C_{N,j} \cos \phi_F \\ C_{y,1} \text{ or } C_{y,R} &= -\sum_{j=1}^{NRP} C_{N,j} \sin \phi_F \end{aligned} \right\} \quad (F5)$$

Here NRP is the number of constant u-velocity panels on the right upper fin. The pitching-, yawing- and rolling-moment coefficients are obtained from the following expressions, respectively.

$$\left. \begin{aligned} C_{m,1} \text{ or } C_{m,R} &= -\sum_{j=1}^{NRP} C_{N,j} \cos \phi_F \frac{(x_{CPT,j} - XM)}{l_{ref}} \\ C_{n,1} \text{ or } C_{n,R} &= \sum_{j=1}^{NRP} C_{N,j} \sin \phi_F \frac{(x_{CPT,j} - XM)}{l_{ref}} \\ C_{\ell,1} \text{ or } C_{\ell,R} &= -\sum_{j=1}^{NRP} \frac{(C_{N,j} \cos \phi_F y_{CPT,j} - C_{N,j} \sin \phi_F (z_{CPT,j} - ZM))}{l_{ref}} \end{aligned} \right\} \quad (F6)$$

The reference length ℓ_{ref} as well as the reference area S_{ref} are specified in namelist INPUT of routine CRFWBD in program DEMON2 as REFL and SREF, respectively. Fin dihedral angle, ϕ_1 or ϕ_R , is defined as shown in figure 3 and equals positive angle ϕ_F . Angles ϕ_F and θ are specified in namelist \$INPUT in the main program CRFWBD of program DEMON2 as PHIDIH and THETIT, respectively.

Left lower fin:

All expressions shown and discussed above for the right upper fin apply except for equation (E5) which gives the forces acting on the left lower fin. They are changed to

$$\left. \begin{aligned} C_{z,2} \text{ or } C_{z,L} &= \sum_{j=NRP+1}^{NHP} C_{N,j} \cos \phi_F \\ C_{y,2} \text{ or } C_{y,L} &= \sum_{j=NRP+1}^{NHP} C_{N,j} \sin \phi_F \end{aligned} \right\} \quad (F7)$$

where NHP is the number of constant u-velocity panels on the right upper fin plus the number of panels on the lower left fin. Likewise, the expressions (F6) for moments become

$$\left. \begin{aligned} C_{m,2} \text{ or } C_{m,L} &= \sum_{j=NRP+1}^{NHP} C_{N,j} \cos \phi_F \frac{(x_{CPT,j} - XM)}{\ell_{ref}} \\ C_{n,2} \text{ or } C_{n,L} &= \sum_{j=NRP+1}^{NHP} C_{N,j} \sin \phi_F \frac{(x_{CPT,j} - XM)}{\ell_{ref}} \\ C_{\ell,2} \text{ or } C_{\ell,L} &= \sum_{j=NRP+1}^{NHP} \frac{(C_{N,j} \cos \phi_F y_{CPT,j} - C_{N,j} \sin \phi_F (z_{CPT,j} - ZM))}{\ell_{ref}} \end{aligned} \right\} \quad (F8)$$

Note that in accordance with the convention indicated in figure 3, the dihedral angle, ϕ_2 or ϕ_L , associated with this fin equals positive angle ϕ_F . Fin location angle, θ_2 or L , is defined as shown and equals positive angle θ .

APPENDIX F

Right lower fin:

Referring again to figure 3, the dihedral angle of this fin, ϕ_3 or ϕ_U , equals the negative angle, $-\phi_F$. The positive sense of C_N is also indicated. For this fin, the fin location angle, θ_3 or θ_U , equals the negative angle, $-\theta$. All expressions shown and discussed above for the right upper fin apply except equations (F5) and (F6) for which the index of the summations is changed and also accounting for the change in sign on terms involving dihedral angle ϕ_F .

$$\left. \begin{aligned} C_{Z,3} \text{ or } C_{Z,U} &= \sum_{j=\text{NHP}+1}^{\text{N3P}} C_{N,j} \cos \phi_F \\ C_{Y,3} \text{ or } C_{Y,U} &= \sum_{j=\text{NHP}+1}^{\text{N3P}} C_{N,j} \sin \phi_F \end{aligned} \right\} \quad (\text{F9})$$

where N3P equals the number of constant u-velocity panels on the right upper fin added to the number on the left lower fin added to the number on the lower right fin. The pitching-, yawing- and rolling-moment coefficients are

$$\left. \begin{aligned} C_{m,3} \text{ or } C_{m,U} &= \sum_{j=\text{NHP}+1}^{\text{N3P}} C_{N,j} \cos \phi_F \frac{(x_{\text{CPT},j} - X_M)}{l_{\text{ref}}} \\ C_{n,3} \text{ or } C_{n,U} &= \sum_{j=\text{NHP}+1}^{\text{N3P}} C_{N,j} \sin \phi_F \frac{(x_{\text{CPT},j} - X_M)}{l_{\text{ref}}} \\ C_{l,3} \text{ or } C_{l,U} &= \sum_{j=\text{NHP}+1}^{\text{N3P}} \frac{(C_{N,j} \cos \phi_F Y_{\text{CPT},j} - C_{N,j} \sin \phi_F (z_{\text{CPT},j} - Z_M))}{l_{\text{ref}}} \end{aligned} \right\} \quad (\text{F10})$$

Left upper fin:

The dihedral angle for this fin, ϕ_4 or ϕ_D , and its location angle, θ_4 or θ_D , have the same sense as those for the right lower fin. Thus, ϕ_4 equals negative angle, $-\phi_F$, and θ_4 equals negative angle, $-\theta$. The expressions for the forces and moments acting on this fin are the same as equations (E5) and (E6) except for a change in the index and accounting for the change in sign for terms involving ϕ_F .

$$\left. \begin{aligned} C_{Z,4} \text{ or } C_{Z,D} &= \sum_{j=N3P+1}^{NPANLS} C_{N,j} \cos \phi_F \\ C_{Y,4} \text{ or } C_{Y,D} &= \sum_{j=N3P+1}^{NPANLS} C_{N,j} \sin \phi_F \end{aligned} \right\} \quad (F11)$$

Here, NPANLS equals the sum of the number of constant u-velocity panels on all four fins. The pitching-, yawing- and rolling-moment coefficients are given by

$$\left. \begin{aligned} C_{m,4} \text{ or } C_{m,D} &= \sum_{j=NHP+1}^{NPANLS} C_{N,j} \cos \phi_F \frac{(x_{CPT,j} - XM)}{\ell_{ref}} \\ C_{n,4} \text{ or } C_{n,D} &= \sum_{j=NHP+1}^{NPANLS} C_{N,j} \sin \phi_F \frac{(x_{CPT,j} - XM)}{\ell_{ref}} \\ C_{\ell,4} \text{ or } C_{\ell,D} &= \sum_{j=NHP+1}^{NPANLS} \frac{(C_{N,j} \cos \phi_F y_{CPT,j} - C_{N,j} \sin \phi_F (z_{CPT,j} - ZM))}{\ell_{ref}} \end{aligned} \right\} \quad (F12)$$

If the aerodynamic loading is symmetric about the vertical or $y_B = 0$ plane as is the case for an unrolled configuration with symmetric body nose vorticity, only the right upper and lower fins are considered and the overall sideforce, C_Y , and yawing moment, C_n , are zero.

APPENDIX G

BODY INTERFERENCE PANELS IN SHELL OF ELLIPTICAL CROSS SECTION,
FORCE AND MOMENT CALCULATIONS

The following force and moment coefficients are computed in sub-routine LOADS of program DEMON2. Let $C_{N,k}$ be equal to the normal-force coefficient for one body interference panel (a constant u-velocity panel) with control point coordinates $x_{CPT,k}$, $y_{CPT,k}$, $z_{CPT,k}$ specified in the wing coordinate system (x_W , y_W , z_W). The positive sense of the normal force corresponds to a force pointing outward from the body as shown in figure 3. The components in the z_W and y_W or z_B and y_B direction are given by

$$\left. \begin{aligned} C_{z,k} &= C_{N,k} \cos \theta_{2k} \\ C_{y,k} &= C_{N,k} \sin \theta_{2k} \end{aligned} \right\} \quad (G1)$$

when θ_2 is the angle between the panel trailing edge and the y_W axis. It is calculated in accordance with

$$\left. \begin{aligned} \sin \theta_{2k} &= \frac{z_{W,k,i} - z_{W,k,i-1}}{\left[\left(z_{W,k,i} - z_{W,k,i-1} \right)^2 + \left(y_{W,k,i} - y_{W,k,i-1} \right)^2 \right]^{\frac{1}{2}}} \\ \cos \theta_{2k} &= - \frac{y_{W,k,i} - y_{W,k,i-1}}{\left[\left(z_{W,k,i} - z_{W,k,i-1} \right)^2 + \left(y_{W,k,i} - y_{W,k,i-1} \right)^2 \right]^{\frac{1}{2}}} \end{aligned} \right\} \quad (G2)$$

Subscript i and $i-1$ refer to the two parallel panel side edges as shown in figure 3. Note that panel location angle θ_{BIP} positions the side edge designated i on the body circumference (BIP stands for body interference panel).

For the k 'th body interference panel, the contribution to the pitching-moment coefficient is taken about moment center (x_M , 0 , z_M) and is given by

APPENDIX G

$$C_{m,k} = -C_{z,k} \frac{x_{CPT,k}^{-XM}}{l_{ref}} \quad (G3)$$

where as discussed earlier in connection with the right upper fin, positive pitching corresponds to nose-up motion. The contribution to the yawing-moment coefficient from the k'th body interference panel equals

$$C_{n,k} = -C_{y,k} \frac{x_{CPT,k}^{-XM}}{l_{ref}} \quad (G4)$$

where positive yawing corresponds to nose to right motion. As is the case for the interdigitated fins, both components of the normal-force coefficient contribute to the rolling-moment coefficient.

$$C_{l,k} = \frac{-C_{z,k} y_{CPT,k} + C_{y,k} (z_{CPT,k}^{-ZM})}{l_{ref}} \quad (G5)$$

By adding all contributions from all the constant u-velocity panels laid out on the interference shell, the total force and moment coefficients acting on the part of the body covered by the interference shell can be calculated. Thus, the contributions to the overall forces acting in the z_W and y_W directions are given in coefficient form as

$$\left. \begin{aligned} C_{z,BIP} &= \sum_{k=1}^{NBIP} C_{N,k} \cos \theta_{2k} \\ C_{y,BIP} &= \sum_{k=1}^{NBIP} C_{N,k} \sin \theta_{2k} \end{aligned} \right\} \quad (G6)$$

Here, the number of constant u-velocity panels in the interference shell is given by NBIP. The contributions to the overall pitching-, yawing- and rolling-moment coefficients are specified as follows, respectively.

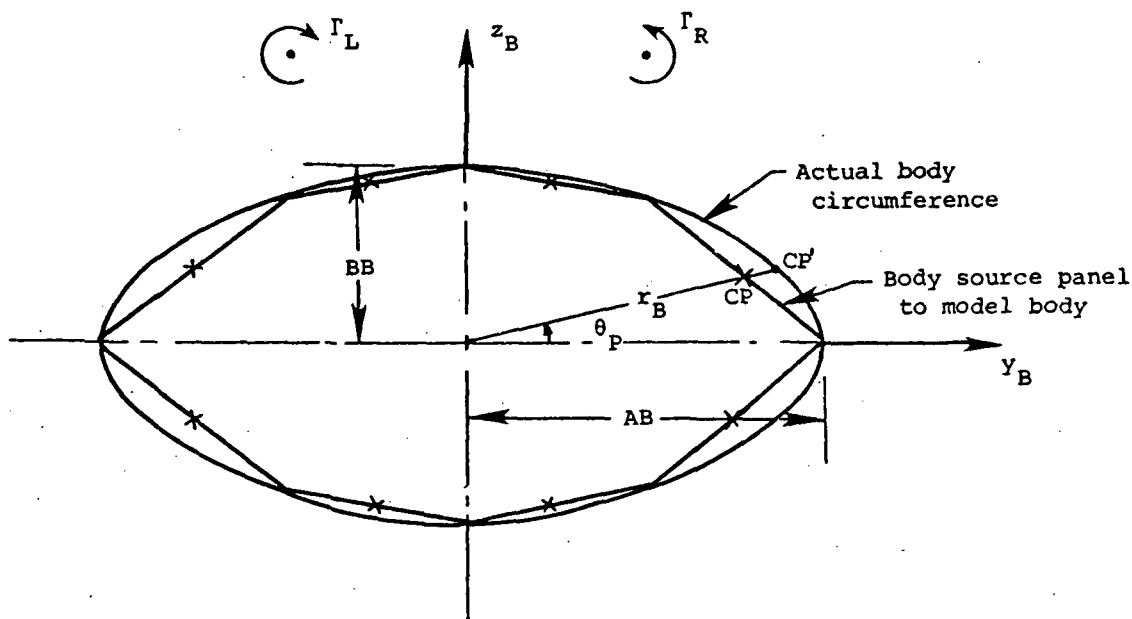
$$\left. \begin{aligned}
 C_{m,BIP} &= \sum_{k=1}^{NBIP} C_{N,k} \cos \theta_{2k} \frac{x_{CPT,k}^{-XM}}{\ell_{ref}} \\
 C_{n,BIP} &= \sum_{k=1}^{NBIP} C_{N,k} \sin \theta_{2k} \frac{x_{CPT,k}^{-XM}}{\ell_{ref}} \\
 C_{\ell,BIP} &= \sum_{k=1}^{NBIP} \frac{C_{N,k} \cos \theta_{2k} y_{CPT,k} - C_{N,k} \sin \theta_{2k} (z_{CPT,k}^{-ZM})}{\ell_{ref}}
 \end{aligned} \right\} (G7)$$

As mentioned earlier, the reference length ℓ_{ref} and the reference area S_{ref} are specified in namelist \$INPUT of routine CRFWBD in program DEMON2 as REFL and SREF, respectively.

APPENDIX H

EFFECTS OF EXTERNAL VORTICITY ON BODY WITH ELLIPTICAL CROSS SECTION

The sketch below shows the circumference of an elliptical body. Also indicated are eight panels in end view as an example of a sparse body paneling layout. The panels can be source panels as employed in program WDYBDY to account for body volume, angle of pitch and angle of sideslip. However, in program DEMON2, these panels are constant u-velocity panels to account for wing-body or tail fin-body interference. In either case, the panel control points designated CP in the sketch lie inside the actual body circumference. In the calculation of pressure distribution on the body, it is desired to account for external vortices at the control points. Let Γ_R and Γ_L be body nose vorticity idealized to two potential flow vortices.



The solution for the flow field around a body with elliptical cross section in the presence of specified external vortices is given in Appendix I. This solution is programmed in subroutine VVELS in both programs WDYBDY and DEMON2 and provides valid flow field velocities at points on and outside the body circumference. However, the control points, CP, are inside the body by virtue of the method resulting in a layout of inscribed panels. For the purpose of accounting for the

APPENDIX H

presence of the vortices, their induced velocities are calculated at points CP' instead. They lie on the intersection of the body radius which contains control point CP and the body circumference. In actuality, points CP' are displaced further out a distance equal to one percent of the body radius r_B in the programs using subroutine VVELS. This is done to prevent numerical problems encountered when computing velocities on the body surface if the coordinates of the body points are calculated and specified to subroutine VVELS. To accomplish this, the polar angle θ_p designated THETP in the computer program is calculated first as follows.

$$\theta_p = \tan^{-1} \frac{z_{CPT}}{y_{CPT}} \quad (H1)$$

The coordinates of a given control point CP are x_{CPT} , y_{CPT} and z_{CPT} in either the body or wing reference coordinate system. Then to determine the body radius r_B at angle θ_p , the equation for the ellipse is used.

$$r_B^2 = \frac{1}{\frac{\cos^2 \theta_p}{AB^2} + \frac{\sin^2 \theta_p}{BB^2}} \quad (H2)$$

Here AB is the horizontal semi-axis and BB is the vertical semi-axis of the elliptical cross section for given axial body station. The coordinates of the corresponding body surface point CP' displaced one percent of the radius r_B outside the actual body circumference are

$$\begin{aligned} y_{CPB} &= 1.01r_B \cos \theta_p \\ z_{CPB} &= 1.01r_B \sin \theta_p \end{aligned} \quad (H3)$$

Thus, subroutine VVELS computes the vortex induced velocities at points CP'. These velocities are added to all other velocity component contributions calculated at the panel control points, CP. The pressure is then calculated at points CP in accordance with the Bernoulli relation, equation (10).

APPENDIX I

VELOCITY COMPONENTS IN CROSSFLOW PLANE REQUIRED TO CALCULATE VORTEX TRAJECTORIES

In order to calculate vortex trajectories using slender-body methods, it is necessary to know the two velocity components in the crossflow plane at the vortices. The lateral movement between two axial stations a distance Δx apart can be calculated from these quantities. Since a number of different cross sectional shapes in the crossflow planes are of interest in the present computer program, a number of different solutions are needed. Specifically the following eight velocity fields are used.

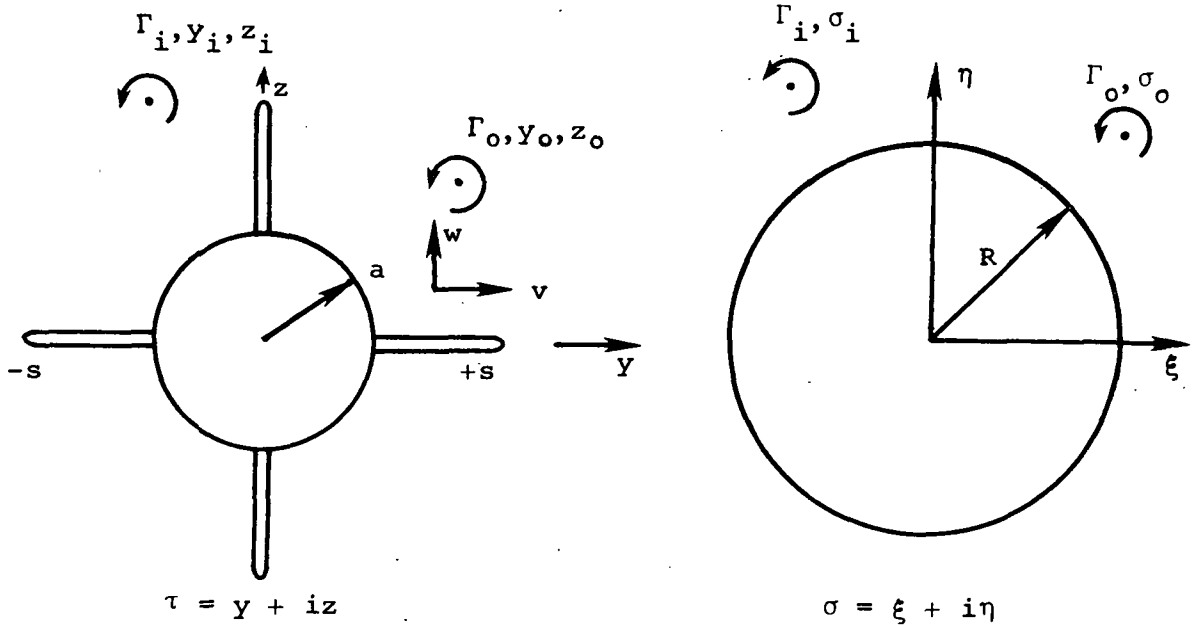
1. Velocity field induced in crossflow plane by a set of vortices in the presence of a cruciform wing-body combination on one member of the set.
2. Velocity components in crossflow plane due to pitch and bank of a cruciform wing-body combination including volume effects.
3. Flow field in crossflow plane due to symmetrical deflection of two panels of a planar wing-body combination.
4. Flow field in crossflow plane due to deflection of a single panel on a cruciform wing-body combination.
5. Velocities on a vortex due to other vortices in the crossflow plane in the presence of a monoplane midwing mounted on a body of elliptical cross-section.
6. Velocity components in crossflow plane due to pitch and bank of a monoplane midwing mounted on a body of elliptical cross-section.
7. Velocities on a vortex due to other vortices in the presence of a monoplane midwing mounted on a body of elliptical cross-section including effects of angles of pitch and sideslip.
8. Velocity components in the crossflow plane due to expansion of a body with elliptical cross sections.

The expressions for all these velocity fields are given in this Appendix. Although some of the expressions have been published elsewhere, they are all being presented here for completeness and to collect the results in one place.

APPENDIX I

1.- Velocity Field Induced in Crossflow Plane by a Set of Vortices in the Presence of a Cruciform Wing-Body Combination on One Member of the Set

This solution is required to determine the trajectory of a vortex in the presence of a cruciform wing-body combination. The solution for v and w will be determined using slender-body theory. The following transformation of a cruciform wing-body into a circle of radius R is used.



$$\tau^2 + \frac{a^4}{\tau^2} = \sigma^2 + \frac{R^4}{\sigma^2} \qquad 2R^2 = s^2 + \frac{a^4}{s^2} \qquad (I1)$$

$$\sigma = \frac{1}{2} \left[\sqrt{\left(\tau^2 + \frac{a^4}{\tau^2} \right)^2 - 2R^2} + \sqrt{\left(\tau^2 + \frac{R^4}{\tau^2} \right) + 2R^2} \right] \qquad (I2)$$

$$\tau = \frac{1}{2} \left[\sqrt{\left(\sigma^2 + \frac{R^4}{\sigma^2} \right)^2 - 2a^2} + \sqrt{\left(\sigma^2 + \frac{R^4}{2} \right) + 2R^2} \right] \qquad (I3)$$

The potential for one vortex in the presence of the circle in the σ plane is

$$W_1(\sigma) = \frac{-i\Gamma_o}{2\pi} \ln(\sigma - \sigma_o) + \frac{i\Gamma_o}{2\pi} \ln \left(\sigma - \frac{R^2}{\sigma_o} \right) \qquad (I4)$$

We omit center vortices to keep the solution regular for large σ . The complex potential for the set of vortices is

$$W_t(\sigma) = \frac{-i\Gamma_0}{2\pi} \ln(\sigma - \sigma_0) + \frac{i\Gamma_0}{2\pi} \ln\left(\sigma - \frac{R^2}{\sigma_0}\right) - \frac{i}{2\pi} \sum_{i=1}^N \Gamma_i \ln\left[\frac{\sigma - \sigma_i}{\left(\sigma - \frac{R^2}{\sigma_i}\right)}\right] \quad (I5)$$

The complex potential in the τ plane is given by equation (I5) with the substitution $\sigma = \sigma(\tau)$.

Consider now the complex potential for the motion of vortex Γ_0 in the τ plane.

$$W_{\Gamma_0}(\tau) = W_t(\sigma(\tau)) + \frac{i\Gamma_0}{2\pi} \ln(\tau - \tau_0) \quad (I6)$$

The velocity components of Γ_0 in the τ plane are

$$v_0 - iw_0 = \frac{d}{d\tau} W_{\Gamma_0}(\tau) \Big|_{\tau=\tau_0} \quad (I7)$$

$$\begin{aligned} \frac{d}{d\tau} W_{\Gamma_0}(\tau) &= \frac{d}{d\tau} \left[\frac{-i\Gamma_0}{2\pi} \ln\left(\frac{\sigma - \sigma_0}{\tau - \tau_0}\right) \right] + \frac{d}{d\tau} \left[\frac{i\Gamma_0}{2\pi} \ln\left(\sigma - \frac{R^2}{\sigma_0}\right) \right] \\ &\quad - \frac{i}{2\pi} \frac{d}{d\tau} \sum \Gamma_i \ln\left[\frac{\sigma - \sigma_i}{\sigma - \frac{R^2}{\sigma_i}}\right] \end{aligned} \quad (I8)$$

It is shown (ref. 4) that

$$\begin{aligned} \frac{d}{d\tau} \ln\left(\frac{\tau - \tau_0}{\sigma - \sigma_0}\right) \Big|_{\tau \rightarrow \tau_0} &= \lim_{\tau \rightarrow \tau_0} \left[\frac{1}{\tau - \tau_0} - \frac{1}{(\sigma - \sigma_0)} \frac{d\sigma}{d\tau} \right] \\ \sigma - \sigma_0 &= (\tau - \tau_0) \left(\frac{d\sigma}{d\tau} \right)_{\tau_0} + \frac{1}{2} (\tau - \tau_0)^2 \frac{d^2\sigma}{d\tau^2} \Big|_{\tau_0} \\ \frac{d\sigma}{d\tau} &= \left(\frac{d\sigma}{d\tau} \right)_{\tau_0} + (\tau - \tau_0) \frac{d^2\sigma}{d\tau^2} \Big|_{\tau_0} \end{aligned} \quad (I9)$$

APPENDIX I

$$\begin{aligned}
 \frac{1}{\tau - \tau_0} - \frac{1}{(\sigma - \sigma_0)} \frac{d\sigma}{d\tau} &= \frac{1}{\sigma - \sigma_0} \left(\frac{\sigma - \sigma_0}{\tau - \tau_0} - \frac{d\sigma}{d\tau} \right) \\
 &= \frac{1}{\sigma - \sigma_0} \left[\left(\frac{d\sigma}{d\tau} \right)_{\tau_0} + \frac{1}{2} (\tau - \tau_0) \frac{d^2\sigma}{d\tau^2} \Big|_{\tau_0} \right. \\
 &\quad \left. - \frac{d\sigma}{d\tau} \Big|_{\tau_0} - (\tau - \tau_0) \frac{d^2\sigma}{d\tau^2} \Big|_{\tau_0} \dots \right] \\
 &= -\frac{1}{2} \left(\frac{\tau - \tau_0}{\sigma - \sigma_0} \right) \frac{d^2\sigma}{d\tau^2} \Big|_{\tau_0}
 \end{aligned} \tag{I10}$$

$$\lim_{\tau \rightarrow \tau_0} \left(\frac{d}{d\tau} \right) \left[\ln \left(\frac{\tau - \tau_0}{\sigma - \sigma_0} \right) \right] = -\frac{1}{2} \left(\frac{d\tau}{d\sigma} \right)_{\tau_0} \left(\frac{d^2\sigma}{d\tau^2} \right)_{\tau_0} \tag{I11}$$

$$\begin{aligned}
 v_0 - iw_0 &= \frac{i\Gamma_0}{2\pi} \left[-\frac{1}{2} \left(\frac{d\tau}{d\sigma} \right) \frac{d^2\sigma}{d\tau^2} \right]_{\tau_0} + \frac{i\Gamma_0}{2\pi} \frac{\bar{\sigma}_0}{\sigma_0 \bar{\sigma}_0 - R^2} \left(\frac{d\sigma}{d\tau} \right)_{\tau_0} \\
 &\quad - \frac{i}{2\pi} \sum_{i=1}^N \Gamma_i \left(\frac{1}{\sigma_0 - \sigma_i} - \frac{\bar{\sigma}_i}{\sigma_0 \bar{\sigma}_i - R^2} \right) \left(\frac{d\sigma}{d\tau} \right)_{\tau_0}
 \end{aligned} \tag{I12}$$

$$\frac{d\sigma}{d\tau} = \frac{\frac{1}{2} \left(\tau^3 - \frac{a^4}{\tau} \right) \left[\sqrt{\left(\tau^2 + \frac{a^4}{\tau^2} \right) + 2R^2} + \sqrt{\left(\tau^2 + \frac{a^4}{\tau^2} \right) - 2R^2} \right]}{\sqrt{\left(\tau^2 + \frac{a^4}{\tau^2} \right)^2 - 4R^4}} \tag{I13}$$

Equations (I1), (I2) and (I3) yield the following relationships.

$$\frac{d\sigma}{d\tau} = \frac{(\tau^4 - a^4)\sigma^3}{\tau^3(\sigma^4 - R^4)} \tag{I14}$$

$$\frac{d^2\sigma}{d\tau^2} = \frac{\sigma^3(\tau^4 + 3a^4)}{(\sigma^4 - R^4)\tau^4} - \frac{\sigma^5(\tau^4 - a^4)^2(\sigma^4 + 3R^4)}{\tau^6(\sigma^4 - R^4)^3} \tag{I15}$$

$$\frac{d\tau}{d\sigma} \frac{d^2\sigma}{d\tau^2} = \frac{\tau^2(\sigma^4 - R^4)^2(\tau^4 + 3a^4) - \sigma^2(\tau^4 - a^4)^2(\sigma^4 + 3R^4)}{\tau^3(\sigma^4 - R^4)^2(\tau^4 - a^4)} \tag{I16}$$

With these results, we find the desired velocity

$$\begin{aligned}
 v_o - iw_o &= \frac{-i\Gamma_o}{4\pi} \frac{\left[\tau_o^2 (\sigma_o^4 - R_o^4)^2 (\tau_o^4 + 3a^4) - \sigma_o^2 (\tau_o^4 - a^4)^2 (\sigma_o^4 + 3R_o^4) \right]}{\tau_o^3 (\sigma_o^4 - R_o^4)^2 (\tau_o^4 - a^4)} \\
 &+ \frac{i\Gamma_o}{2\pi} \frac{\bar{\sigma}_o}{(\sigma_o \bar{\sigma}_o - R^2)} \frac{(\tau_o^4 - a^4) \sigma_o^3}{\tau_o^3 (\sigma_o^4 - R^4)} \\
 &- \frac{i}{2\pi} \frac{(\tau_o^4 - a^4) (\sigma_o^3)}{\tau_o^3 (\sigma_o^4 - R^4)} \sum_{i=1}^N \Gamma_i \left[\frac{1}{\sigma_o - \sigma_i} - \frac{\bar{\sigma}_i}{\sigma_o \bar{\sigma}_i - R^2} \right] \tag{I17}
 \end{aligned}$$

where

Γ_o = strength of vortex, the velocity components of which are being calculated

v_o, w_o = velocity component of vortex Γ_o

Γ_i = strength of any vortex except Γ_o ; $i=1, 2, \dots, N$

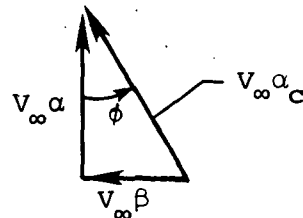
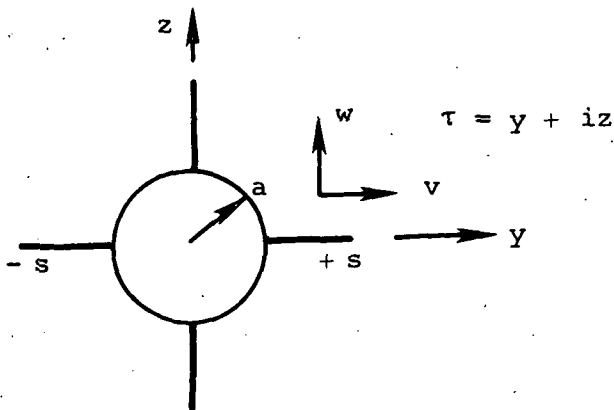
τ_o = position of Γ_o in τ plane

σ_o = position of Γ_o in σ plane

σ_i = position of Γ_i in σ plane

2.- Velocity Components in Crossflow Plane Due to Pitch and Bank of a Cruciform Wing-Body Combination Including Volume Effects

For a pitched and banked cruciform missile the induced flow field can be obtained by superimposing two planar missile flow fields at right angles



APPENDIX I

The flow field about a planar wing-body with horizontal wings is described by complex potential W_α corresponding to $V_\infty \cos \phi \sin \alpha_c$ along the positive axis of z . The complex potential W_β is associated with velocity $-V_\infty \sin \phi \sin \alpha_c$ along the negative axis of y . The total potential is then

$$\frac{W(\tau)}{V_\infty} = b_0(x) + a \left(\frac{da}{dx} \right) \ln \tau + W_\alpha(\tau) + W_\beta(\tau) \quad (I18)$$

If $\phi = 0$, the perturbation complex potential is given in equation 5.3 of reference 8. Using the small angle approximation:

$$\frac{W(\tau)}{V_\infty} = b_0(x) + a \left(\frac{da}{dx} \right) \ln \tau - i\alpha \left\{ \left[\left(\tau + \frac{a^2}{\tau} \right)^2 - \left(s + \frac{a^2}{s} \right)^2 \right]^{\frac{1}{2}} - \tau \right\} \quad (I19)$$

The velocity $v-iw$ for $\phi = 0$ is then

$$\frac{v-iw}{V_\infty} = \frac{1}{V_\infty} \frac{dW}{d\tau} = a \left(\frac{da}{dx} \right) \frac{1}{\tau} + i\alpha \frac{-i\alpha (\tau^4 - a^4)s}{\tau^2 \sqrt{(\tau^2 - s^2)(\tau^2 s^2 - a^4)}}; \phi = 0 \quad (I20)$$

and

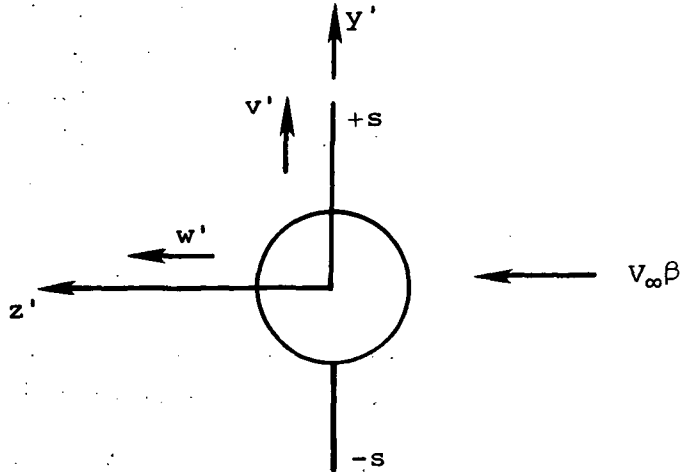
$$v-iw \rightarrow 0 \quad \text{as} \quad \tau \rightarrow \infty$$

The perturbation velocity $v_\alpha - iw_\alpha$ associated with the velocity component $V_\infty \alpha$ is

$$\frac{v_\alpha - iw_\alpha}{V_\infty} = \frac{-i\alpha (\tau^4 - a^4)s}{\tau^2 \sqrt{(\tau^2 - s^2)(\tau^2 s^2 - a^4)}} + i\alpha \quad (I21)$$

From this expression we can determine the perturbation velocity $v_\beta - iw_\beta$ associated with the velocity $V_\infty \beta$ along the negative axis of y .

Consider a set of coordinates y' and z' as shown with velocity components v' and w' with $\tau' = -i\tau$.



The perturbation velocity $v' - iw'$ is given analogous to equation (I21) as

$$\begin{aligned} \frac{v' - iw'}{V_\infty} &= \frac{-i\beta (\tau'^4 - a^4)s}{\tau'^2 \sqrt{(\tau'^2 - s^2)(\tau'^2 s^2 - a^4)}} + i\beta \\ &= \frac{-i\beta (\tau^4 - a^4)s}{\tau^2 \sqrt{(\tau^2 + s^2)(\tau^2 s^2 + a^4)}} + i\beta \end{aligned} \quad (\text{I22})$$

$$-i(v' - iw') = v_\beta - iw_\beta = \frac{-\beta (\tau^4 - a^4)s}{\tau^2 \sqrt{(\tau^2 + s^2)(\tau^2 s^2 + a^4)}} + \beta \quad (\text{I23})$$

It is possible to add $v_\beta - iw_\beta$ to the results of equation (I20) for $\phi = 0$ to obtain the total complex potential for the cruciform wing-body combination since the sum satisfies the boundary condition. Accordingly we have the final result

$$\begin{aligned} v - iw &= a \left(\frac{da}{dx} \right) \left(\frac{1}{\tau} \right) + i\alpha + \beta - \frac{i\alpha (\tau^4 - a^4)s}{\tau^2 \sqrt{(\tau^2 - s^2)(\tau^2 s^2 - a^4)}} \\ &\quad - \frac{\beta (\tau^4 - a^4)s}{\tau^2 \sqrt{(\tau^2 + s^2)(\tau^2 s^2 + a^4)}} \end{aligned} \quad (\text{I24})$$

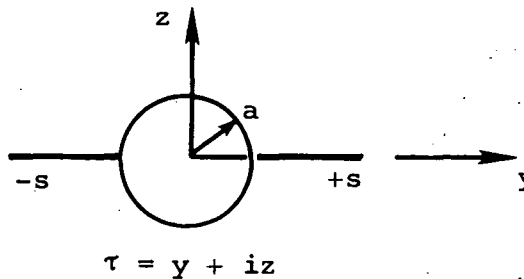
3.- Flow Field in Crossflow Plane Due to Symmetrical Deflection of Two Panels of a Planar Wing-Body Combination

3.1 Introduction

In determining the perturbation velocity components in the flow field of a cruciform wing-body combination, we must have flow field solutions (1) for no fin deflection at $\alpha \neq 0$, (2) for symmetrical fin deflection of opposing panels at $\alpha = 0$, and (3) for the deflection of a single fin of a cruciform configuration at $\alpha = 0$. The first two flow fields for a cruciform wing-body can be formed by superimposing solutions for a planar wing-body combination at right angles to each other. The first solution is given in the preceding sections; the second solution is the subject of this section, and the third solution is the subject of the next section.

3.2 Boundary Value Problem

Consider a planar wing-body combination with a circular body of radius a and a fin of total semispan s .



The left and right fins are deflected trailing edge down by an angular deflection δ such that the normal velocity on the fins due to the free stream is $V_\infty \delta$. The complex velocity in the crossflow plane is $v + iw$. We have to find perturbation velocity components u, v, w at a point x, y, z in the crossflow plane. The complex variable in the crossflow plane is $\tau = y + iz$.

3.3. Method of Solution

Let $W(\tau)$ be the complex potential for crossflow about the wing-body combination in the crossflow plane at $x = \text{constant}$. Let the missile cross section in the τ plane be transformed to a circle of radius R_0 in the σ plane. We will find a complex potential $W(\sigma)$ which when transformed back to the τ plane satisfies the boundary condition in this plane. If

$$\frac{dW}{d\sigma} = v - iw \quad (I25)$$

$$\frac{dW}{d\tau} = v - iw = (V - iW) \left(\frac{d\sigma}{d\tau} \right)$$

The transformation taking the missile cross section into the circle of radius R_0 is

$$\tau + \frac{a^2}{\tau} = \sigma + \frac{R_0^2}{\sigma} \quad (I26)$$

with

$$2R_0 = s + \frac{a^2}{s} \quad (I27)$$

where a is the body radius and s the fin semispan. In this transformation the field far from the cross section is undistorted. The reciprocal relationships between corresponding points in the σ and τ planes are obtained from the equations for the upper half plane

$$\sigma = \frac{1}{2} \left(\tau + \frac{a^2}{\tau} \right) + \frac{1}{2} \sqrt{\left(\tau + \frac{a^2}{\tau} \right)^2 - 4R_0^2} \quad (I28)$$

$$\tau = \frac{1}{2} \left(\sigma + \frac{R_0^2}{\sigma} \right) + \frac{1}{2} \sqrt{\left(\sigma + \frac{R_0^2}{\sigma} \right)^2 - 4a^2} \quad (I29)$$

On the circle $\sigma = R_0 e^{i\theta}$, we have

$$\tau = R_0 \cos \theta + R_0 \sqrt{\cos^2 \theta - \frac{a^2}{R_0^2}} \quad (I30)$$

If $\theta = 0^\circ$

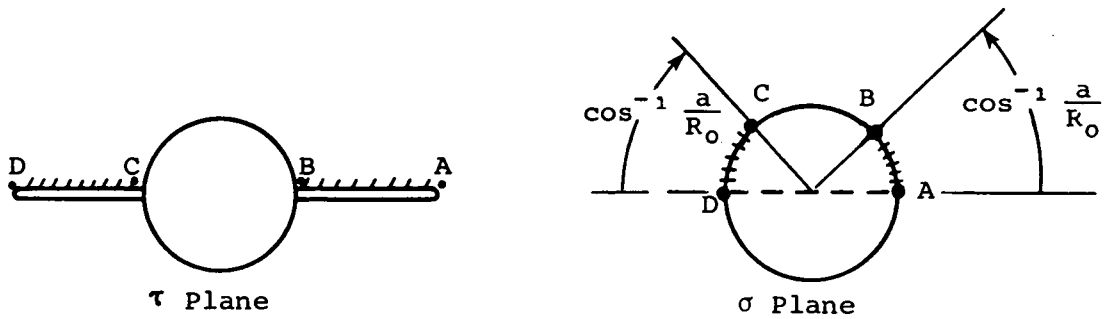
$$\tau = s \quad (I31)$$

If $\cos \theta = a/R_0$, then

$$\tau = a \quad (I32)$$

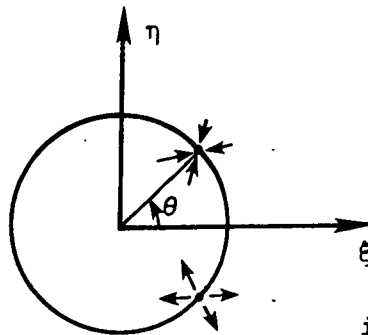
APPENDIX I

These points are shown in the following sketch



3.4 Complex Potential

To obtain the complex potential, we follow a variation of the method of Adams and Dugan (ref. 21). Consider points on the upper and lower surfaces of the right wing at the same y location between $y = a$ and $y = s$.



Let the corresponding points in the σ plane be $R_0 e^{i\theta_0}$ and $R_0 e^{-i\theta_0}$.

Let a sink of strength dm exist at the point $R_0 e^{i\theta_0}$ and a source of opposite strength exist at $R_0 e^{-i\theta_0}$. The complex potential due to the sum of these two singularities is

$$dW_R = - \frac{dm}{2\pi} \ln \left(\frac{\sigma - R_0 e^{i\theta_0}}{\sigma - R_0 e^{-i\theta_0}} \right) \tag{I33}$$

The circle $R_0 e^{i\theta}$ is a streamline of the flow except at the singular points. In the τ plane an amount of fluid $dm/2$ enters the fin from above and an amount of fluid $dm/2$ goes out beneath the fin. Since the upwash through the fin δV_∞ must be countered by the source-sink combination, we have

$$dm = 2\delta V_\infty dy \quad (I34)$$

Accordingly the complex potential due to the right fin is

$$W_R = -\frac{\delta V_\infty}{\pi} \int_a^s \ln \left(\frac{\frac{\sigma}{R_0} - e^{i\theta_0}}{\frac{\sigma}{R_0} - e^{-i\theta_0}} \right) dy \quad (I35)$$

For the left fin, we have by analogy

$$\begin{aligned} dW_L &= -\frac{dm}{\pi} \ln \left(\frac{\sigma - R_0 e^{i(\pi-\theta_0)}}{\sigma - R_0 e^{i(\pi+\theta_0)}} \right) \\ &= -\frac{dm}{2\pi} \ln \left(\frac{\sigma - R_0 e^{-i\theta_0}}{\sigma + R_0 e^{i\theta_0}} \right) \\ W_L &= -\frac{\delta V_\infty}{\pi} \int_{-s}^{-a} \ln \left(\frac{\sigma + R_0 e^{-i\theta_0}}{\sigma + R_0 e^{i\theta_0}} \right) dy \end{aligned} \quad (I36)$$

$$\begin{aligned} W_R + W_L &= -\frac{\delta V_\infty}{\pi} \int_a^s \ln \frac{\left(\frac{\sigma}{R_0} - e^{i\theta_0} \right) \left(\frac{\sigma}{R_0} + e^{-i\theta_0} \right)}{\left(\frac{\sigma}{R_0} - e^{-i\theta_0} \right) \left(\frac{\sigma}{R_0} + e^{i\theta_0} \right)} dy \\ W &= -\frac{\delta V_\infty}{\pi} \int_a^s \ln \left(\frac{\sigma^2 - R_0^2 - 2iR_0\sigma \sin \theta_0}{\sigma^2 - R_0^2 + 2iR_0\sigma \sin \theta_0} \right) dy \end{aligned} \quad (I37)$$

To solve equation (I37) for $W(\sigma)$, we first assume that σ is real, and integrate equation (I37) on this basis. We then invoke the principle of analytic continuation, and assume the result is valid for σ complex. The complex velocity in the τ plane is determined by

APPENDIX I

$$v - iw = \frac{dW}{d\sigma} \frac{d\sigma}{d\tau} \quad (I38)$$

and it can be examined to make sure it satisfies the boundary conditions.

Setting

$$\frac{\sigma^2 - R_o^2}{2R_o\sigma} = \lambda \quad (I39)$$

$$W = - \frac{\delta V_\infty}{\pi} \int_a^s \ln \left(\frac{\lambda - i \sin \theta_o}{\lambda + i \sin \theta_o} \right) dy \quad (I40)$$

Integrating by parts

$$W = - \frac{\delta V_\infty}{\pi} \left[-a \ln \left(\frac{\lambda - i \sqrt{1 - \frac{a^2}{R_o^2}}}{\lambda + i \sqrt{1 - \frac{a^2}{R_o^2}}} \right) + i \int_a^s \frac{y d(\sin \theta_o)}{\lambda - i \sin \theta_o} + i \int_a^s \frac{y d(\sin \theta_o)}{\lambda + i \sin \theta_o} \right] \quad (I41)$$

Let

$$I_1 = \int_a^s \frac{y d(\sin \theta_o)}{\lambda - i \sin \theta_o}$$

$$I_2 = \int_a^s \frac{y d(\sin \theta_o)}{\lambda + i \sin \theta_o}$$

With the help of subsequent results in section 3.6 for $I_1 + I_2$, we obtain

$$W(\sigma, a, R_o) = - \frac{\delta V_\infty}{\pi} \left\{ -a \ln \left(\frac{\lambda - i \sqrt{1 - \frac{a^2}{R_o^2}}}{\lambda + i \sqrt{1 + \frac{a^2}{R_o^2}}} \right) \right.$$

(equation continued on next page)

$$\left. \begin{aligned}
 & -2iR_o \sqrt{\lambda^2 + 1} \tan^{-1} \left\{ \frac{\sqrt{\lambda^2 + 1}}{\lambda} \frac{\sqrt{1 - \frac{a^2}{R_o^2}}}{\frac{a}{R_o}} \right\} \\
 & - iR_o \pi \sqrt{\lambda^2 + 1 - \frac{a^2}{R_o^2}} + 2\lambda R_o i \left[\frac{\pi}{2} + \cos^{-1} \left(\frac{a}{R_o} \right) \right]
 \end{aligned} \right\} \quad (I42)$$

3.5 Crossflow Velocity Components

Having the complex potential, we may now obtain the velocity components in the σ plane and the τ plane.

$$v - iw = \frac{dW}{d\lambda} \left(\frac{d\lambda}{d\sigma} \right) \quad (I43)$$

We will carry out the differentiation

$$\ln \left(\frac{\lambda - i\sqrt{1 - \frac{a^2}{R_o^2}}}{\lambda + i\sqrt{1 - \frac{a^2}{R_o^2}}} \right) = \left(-2i \tan^{-1} \frac{\sqrt{1 - \frac{a^2}{R_o^2}}}{\lambda} \right) \quad (I44)$$

$$\frac{d}{d\lambda} \ln \left(\frac{\lambda - i\sqrt{1 - \frac{a^2}{R_o^2}}}{\lambda + i\sqrt{1 - \frac{a^2}{R_o^2}}} \right) = \frac{+ 2i\sqrt{1 - \frac{a^2}{R_o^2}}}{\lambda^2 + 1 - \frac{a^2}{R_o^2}} \quad (I45)$$

$$\frac{d\lambda}{d\sigma} = \frac{\sigma^2 + R_o^2}{2R_o\sigma^2} \quad \lambda = \frac{\sigma^2 - R_o^2}{2R_o\sigma} \quad (I46)$$

Thus

APPENDIX I

$$\frac{d}{d\sigma} \ln \left[\frac{\lambda - i\sqrt{1 - \frac{a^2}{R_0^2}}}{\lambda + i\sqrt{1 - \frac{a^2}{R_0^2}}} \right] = \frac{4iR_0(\sigma^2 + R_0^2)\sqrt{1 - \frac{a^2}{R_0^2}}}{(\sigma^2 + R_0^2)^2 - 4a^2\sigma^2} \quad (I47)$$

The other differentiation yields

$$\begin{aligned} \frac{d}{d\sigma} \left[\sqrt{\lambda^2 + 1} \tan^{-1} \left[\frac{\sqrt{\lambda^2 + 1}}{\lambda} \frac{\sqrt{1 - \frac{a^2}{R_0^2}}}{\frac{a}{R_0}} \right] \right] &= \frac{2(\sigma^2 + R_0^2)a\sqrt{1 - \frac{a^2}{R_0^2}}}{(\sigma^2 + R_0^2)^2 - 4a^2\sigma^2} \\ &+ \frac{(\sigma^2 - R_0^2)}{2R_0\sigma^2} \tan^{-1} \left[\left[\frac{\sigma + R_0^2}{\sigma^2 - R_0^2} \right] \left[\frac{\sqrt{1 - \frac{a^2}{R_0^2}}}{\frac{a}{R_0}} \right] \right] \end{aligned} \quad (I48)$$

$$\frac{d}{d\sigma} \sqrt{\lambda^2 + 1 - \frac{a^2}{R_0^2}} = \frac{\sigma^4 - R_0^4}{2R_0\sigma^2} \frac{1}{\sqrt{(\sigma^2 + R_0^2)^2 - 4a^2\sigma^2}}$$

The expression in complex form for $V - iW$ is

$$\begin{aligned} V - iW &= -\frac{\delta V_\infty}{\pi} \left\{ -\frac{4iaR_0(\sigma^2 + R_0^2)\sqrt{1 - \frac{a^2}{R_0^2}}}{(\sigma^2 + R_0^2)^2 - 4a^2\sigma^2} - \frac{4iaR_0(\sigma^2 + R_0^2)\sqrt{1 - \frac{a^2}{R_0^2}}}{(\sigma^2 + R_0^2)^2 - 4a^2\sigma^2} \right. \\ &\quad \left. - \frac{i(\sigma^2 - R_0^2)}{\sigma^2} \tan^{-1} \left[\left[\frac{\sigma^2 + R_0^2}{\sigma^2 - R_0^2} \right] \left[\frac{\sqrt{1 - \frac{a^2}{R_0^2}}}{\frac{a}{R_0}} \right] \right] \right\} \end{aligned}$$

(equation continued on next page)

$$- \frac{i\pi}{2\sigma^2} \frac{(\sigma^4 - R_0^4)}{\sqrt{(\sigma^2 + R_0^2)^2 - 4a^2\sigma^2}} + \frac{i(\sigma^2 + R_0^2)}{\sigma^2} \left[\frac{\pi}{2} + \cos^{-1} \left(\frac{a}{R_0} \right) \right] \quad (I49)$$

We now determine $v - iw$ in the τ plane

$$v - iw = (V - iW) \frac{d\sigma}{d\tau} \quad (I50)$$

From the transformation we find the following relationships

$$\left. \begin{aligned} \frac{d\sigma}{d\tau} &= \frac{\sigma^2}{(\sigma^2 - R_0^2)} \frac{(\tau^2 - a^2)}{\tau^2} \\ \frac{\sigma^2 + R_0^2}{\sigma} &= \tau + \frac{a^2}{\tau} \\ \frac{\sigma^2 - R_0^2}{\sigma} &= \sqrt{\left(\tau + \frac{a^2}{\tau}\right)^2 - 4R_0^2} \end{aligned} \right\} \quad (I51)$$

The following results are needed to accomplish the transformation of the results to the τ plane

$$\begin{aligned} \frac{\sigma^2 + R_0^2}{(\sigma^2 + R_0^2)^2 - 4a^2\sigma^2} \left(\frac{d\sigma}{d\tau} \right) &= \frac{\frac{\sigma^2 + R_0^2}{\sigma}}{\left[\frac{\sigma^2 + R_0^2}{\sigma} \right]^2 - 4a^2} \frac{\sigma}{(\sigma^2 - R_0^2)} \left(\frac{\tau^2 - a^2}{\tau^2} \right) \\ &= \frac{\left(\tau + \frac{a^2}{\tau} \right)}{\left[\left(\tau + \frac{a^2}{\tau} \right)^2 - 4a^2 \right] \sqrt{\left(\tau + \frac{a^2}{\tau} \right)^2 - 4R_0^2}} \frac{1}{\left(\frac{\tau^2 - a^2}{\tau^2} \right)} \\ &= \frac{(\tau^2 + a^2)}{(\tau^2 - a^2) \sqrt{(\tau^2 + a^2)^2 - 4R_0^2\tau^2}} \quad (I52) \end{aligned}$$

APPENDIX I

Since

$$\frac{\sigma^2 - R_o^2}{\sigma^2} \frac{d\sigma}{d\tau} = \left(\frac{\tau^2 - a^2}{\tau^2} \right) \quad (I53)$$

we find

$$\left(\frac{d\sigma}{d\tau} \right) \left(\frac{\sigma^2 - R_o^2}{\sigma^2} \right) \tan^{-1} \left[\left(\frac{\sigma^2 + R_o^2}{\sigma^2 - R_o^2} \right) \frac{\sqrt{1 - \frac{a^2}{R_o^2}}}{\frac{a}{R_o}} \right] = \left(\frac{\tau^2 - a^2}{\tau^2} \right) \tan^{-1} \left[\frac{(\tau^2 + a^2) \sqrt{1 - \frac{a^2}{R_o^2}}}{\left(\frac{a}{R_o} \right) \sqrt{(\tau^2 + a^2)^2 - 4R_o^2 \tau^2}} \right] \quad (I54)$$

$$\frac{\sigma^4 - R_o^4}{\sigma^2 \sqrt{(\sigma^2 + R_o^2)^2 - 4a^2 \sigma^2}} \left(\frac{d\sigma}{d\tau} \right) = \frac{(\tau^2 + a^2)}{\tau^2} \quad (I55)$$

$$\frac{\sigma^2 + R_o^2}{\sigma^2} \frac{d\sigma}{d\tau} = \frac{\tau^4 - a^4}{\tau^2 \sqrt{(\tau^2 + a^2)^2 - 4R_o^2 \tau^2}} \quad (I56)$$

These results yield the complex velocity in the τ plane.

$$(v - iw) = \frac{\delta V_\infty}{\pi} \left\{ i \left(\frac{\tau^2 - a^2}{\tau^2} \right) \tan^{-1} \left[\frac{(\tau^2 + a^2) \sqrt{1 - \frac{a^2}{R_o^2}}}{\left(\frac{a}{R_o} \right) \sqrt{(\tau^2 + a^2)^2 - 4R_o^2 \tau^2}} \right] \right\}$$

(equation continued on next page)

$$+ i \left(\frac{\pi}{2} \frac{\tau^2 + a^2}{\tau^2} - \frac{i}{\sqrt{(\tau^2 + a^2)^2 - 4R_0^2 \tau^2}} \left(\frac{\tau^4 - a^4}{\tau^2} \right) \right) \left[\frac{\pi}{2} + \cos^{-1} \left(\frac{a}{R_0} \right) \right] \quad (I57)$$

The expression can be broken down into real and imaginary parts to obtain v and w, but is probably more convenient to obtain v - iw on the computer using complex calculations.

3.6 Evaluation of Certain Definite Integrals

The following integrals are to be evaluated

$$I_1 = \int_0^{\pi/2} \frac{y \, d(\sin \theta)}{\sqrt{1 - a^2/R_0^2} \lambda - i \sin \theta} \quad (I58)$$

$$I_2 = \int_0^{\pi/2} \frac{y \, d(\sin \theta)}{\sqrt{1 - a^2/R_0^2} \lambda + i \sin \theta} \quad (I59)$$

where

$$y = R_0 \left[\cos \theta + \sqrt{1 - \frac{a^2}{R_0^2} - \sin^2 \theta} \right] \quad (I60)$$

We want the sum $I_1 + I_2$ in particular

$$I_1 + I_2 = 2\lambda R_0 \int_0^{\pi/2} \frac{1}{\sqrt{1 - a^2/R_0^2} \lambda^2 + \sin^2 \theta} \left(\cos \theta + \sqrt{1 - \frac{a^2}{R_0^2} - \sin^2 \theta} \right) d(\sin \theta) \quad (I61)$$

$$= 2\lambda R_0 \left[(1 + \lambda^2) \int_{\cos^{-1} a/R_0}^{\pi/2} \frac{d\theta}{(\lambda^2 + \sin^2 \theta)} - \int_{\cos^{-1} a/R_0}^{\pi/2} d\theta \right]$$

(equation continued on next page)

APPENDIX I

$$\begin{aligned}
 & + \left(1 - \frac{a^2}{R_0^2} + \lambda^2 \right) \int_0^\circ \frac{d(\sin \theta)}{\sqrt{1 - a^2/R_0^2} (\lambda^2 + \sin^2 \theta) \sqrt{1 - \frac{a^2}{R_0^2} - \sin^2 \theta}} \\
 & - \int_0^\circ \frac{d(\sin \theta)}{\sqrt{1 - a^2/R_0^2} \sqrt{1 - \frac{a^2}{R_0^2} - \sin^2 \theta}} \quad \left. \vphantom{\int_0^\circ} \right] \quad \text{(I62)} \\
 & \hspace{20em} \text{(Concluded)}
 \end{aligned}$$

We now integrate each of the four separate integrals. From pg. 323 in reference 19.

$$\begin{aligned}
 \int_{\cos^{-1}(a/R_0)}^\circ \frac{d\theta}{(\lambda^2 + \sin^2 \theta)} &= \frac{1}{\sqrt{\lambda^2(\lambda^2 + 1)}} \tan^{-1} \left[\frac{\sqrt{\lambda^2(\lambda^2 + 1)} \tan \theta}{\lambda^2} \right] \Big|_{\cos^{-1}(a/R_0)}^\circ \\
 &= - \frac{1}{\lambda \sqrt{\lambda^2 + 1}} \tan^{-1} \left[\frac{\sqrt{\lambda^2 + 1}}{\lambda} \frac{\sqrt{1 - \frac{a^2}{R_0^2}}}{\left(\frac{a}{R_0}\right)} \right] \quad \text{(I63)}
 \end{aligned}$$

$$\int_{\cos^{-1}(a/R_0)}^\circ d\theta = - \cos^{-1} \left(\frac{a}{R_0} \right) \quad \text{(I64)}$$

The third integral can be evaluated with the help of the following result from page 55 in reference 20.

$$\int \frac{dx}{(\lambda^2 + x^2) \sqrt{v^2 - x^2}} = \frac{1}{\lambda \sqrt{\lambda^2 + v^2}} \tan^{-1} \frac{x \sqrt{\lambda^2 + v^2}}{\lambda \sqrt{v^2 - x^2}} + C \quad \text{(I65)}$$

$$\int_0^\circ \frac{d(\sin \theta)}{\sqrt{1 - a^2/R_0^2} (\lambda^2 + \sin^2 \theta) \sqrt{1 - \frac{a^2}{R_0^2} - \sin^2 \theta}} = \frac{1}{\lambda \sqrt{\lambda^2 + 1 - \frac{a^2}{R_0^2}}}$$

$$\tan^{-1} \left[\frac{\sqrt{\lambda^2 + 1 - \frac{a^2}{R_0^2}} \sin \theta}{\lambda \sqrt{1 - \frac{a^2}{R_0^2} - \sin^2 \theta}} \right] \Big|_0^{\circ} = - \left(\frac{\pi}{2} \right) \frac{1}{\lambda \sqrt{\lambda^2 + 1 - \frac{a^2}{R_0^2}}} \quad (\text{I66})$$

The fourth integral is

$$\int_0^{\circ} \frac{d(\sin \theta)}{\sqrt{1 - \frac{a^2}{R_0^2} - \sin^2 \theta}} = \sin^{-1} \left[\frac{\sin \theta}{\sqrt{1 - \frac{a^2}{R_0^2}}} \right] \Big|_0^{\circ} = - \frac{\pi}{2} \quad (\text{I67})$$

Finally we have

$$I_1 + I_2 = 2\lambda R_0 \left\{ - \frac{\sqrt{\lambda^2 + 1}}{\lambda} \tan^{-1} \left[\frac{\sqrt{\lambda^2 + 1}}{\lambda} \frac{\sqrt{1 - \frac{a^2}{R_0^2}}}{\frac{a}{R_0}} \right] + \cos^{-1} \left[\frac{a}{R_0} \right] - \frac{\pi}{2} \left[\frac{\sqrt{\lambda^2 + 1 - \frac{a^2}{R_0^2}}}{\lambda} \right] + \frac{\pi}{2} \right\} \quad (\text{I68})$$

4.- Flow Field in Crossflow Plane Due to Deflection of a Single Panel on a Cruciform Wing-Body Combination

4.1 Introduction

For a cruciform wing-body with no panel deflection, the flow field based on slender-body theory is given in section 2. However, the general flow field due to panel deflection is not known. From the results for single panel deflection, the effect of arbitrary deflections of all four panels can be obtained by superposition. This result will now be derived.

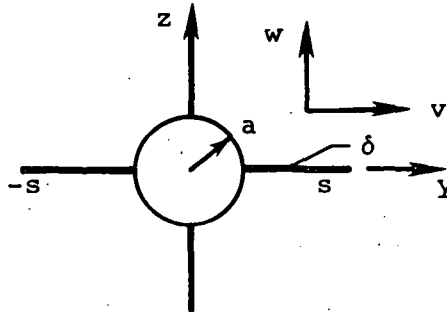
4.2 Boundary Value Problem

Consider the cross section of a cruciform wing-body combination at zero roll angle and zero angle of attack but with the right fin deflected

APPENDIX I

by angle, δ , positive trailing edge down. The crossflow plane is designated by the complex variable

$$\tau = y + iz$$



The body radius is "a" and the fin semispan is "s". The vector velocity in the crossflow plane is $v + iw$, and the axial component of velocity is "u". Let the right panel be deflected by the angle δ so that free-stream velocity V_∞ causes an uniform upwash $V_\infty \sin \delta$ through the fin. We must find a potential ϕ which produces equal and opposite downwash on the right fin and at the same time causes no flow normal to the other fins or the body. We then are to find the flow velocity components u and w at points x, y, z in the field due to this potential. The quantities a and s can be functions of x .

4.3 Method of Solution

The method of solution is to find the complex potential W which produces unit velocity at a given point on the deflected wing in the range $a \leq y \leq s$ and zero at all other points. Then the effect of all such fundamental solutions over the range is summed by integration. The fundamental solution is that given by Adams and Dugan in reference 21. The velocity components are found by differentiation of W .

In obtaining the solution, recourse will be had to the theory of conformal transformation. In this connection let the cross-section of the cruciform wing-body combination in the τ plane be transformed into a circle of radius R in the σ plane with

$$\sigma = \xi + i\eta \tag{I69}$$

Such a transformation is given as

$$\tau^2 + \frac{a^4}{\tau^2} = \sigma^2 + \frac{R^4}{\sigma^2} \quad (\text{I70})$$

with

$$2R^2 = s^2 + \frac{a^4}{s^2} \quad (\text{I71})$$

The reciprocal relationships between points in the τ and σ planes are

$$\left. \begin{aligned} \sigma &= \frac{1}{2} \left[\sqrt{\left(\tau^2 + \frac{a^4}{\tau^2}\right) - 2R^2} + \sqrt{\left(\tau^2 + \frac{a^4}{\tau^2}\right) + 2R^2} \right] \\ \tau &= \frac{1}{2} \left[\sqrt{\left(\sigma^2 + \frac{R^4}{\sigma^2}\right) - 2a^2} + \sqrt{\left(\sigma^2 + \frac{R^4}{\sigma^2}\right) + 2a^2} \right] \end{aligned} \right\} \quad (\text{I72})$$

In these relationships we confine our attention to the upper half plane. In equation (I70) we have put the fields at ∞ into the identity relationship

$$\sigma \rightarrow \tau \text{ as } \tau \rightarrow \infty \quad (\text{I73})$$

A point $Re^{i\theta_0}$ on the circle $Re^{i\theta}$ corresponds to y_0 in the physical plane. From equation (I70)

$$2R^2 \left(\frac{e^{2i\theta_0} + e^{-2i\theta_0}}{2} \right) = y_0^2 + \frac{a^4}{y_0^2} \quad (\text{I74})$$

so that

$$\frac{y_0^2}{R^2} = \cos 2\theta_0 + \sqrt{\left(\cos 2\theta_0 - \frac{a^2}{R^2}\right) \left(\cos 2\theta_0 + \frac{a^2}{R^2}\right)} \quad (\text{I75})$$

and

$$\frac{y_0}{R} = \frac{1}{\sqrt{2}} \left[\sqrt{\cos 2\theta_0 - \frac{a^2}{R^2}} + \sqrt{\cos 2\theta_0 + \frac{a^2}{R^2}} \right] \quad (\text{I76})$$

If $y_0 = s$, then from equation (I74) and (I71)

$$2R^2 \cos 2\theta_0 = 2R^2$$

APPENDIX I

or

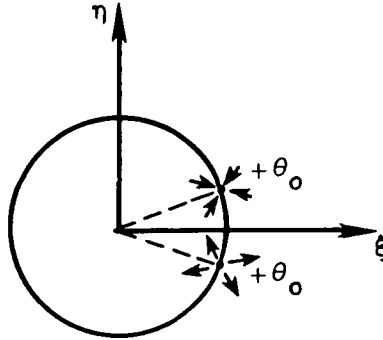
$$\theta_0 = 0; \quad y = s \quad (I77)$$

Let the point $Re^{i\gamma}$ correspond in the σ plane to $y = a$ in the τ plane. Then from equation (I74)

$$\cos 2\gamma = \frac{a^2}{R^2} \quad (I78)$$

4.4 Complex Potential

To obtain the complex potential for the fundamental solution, we follow the method of Adams and Dugan. Consider points on the upper and lower surfaces of the wing at $y = y_0$ and consider a sink of strength dm at $Re^{i\theta_0}$ and a source at point $Re^{-i\theta_0}$ in the σ plane, corresponding to the two points at $y=y_0$ in the τ plane.



The complex potential for the sink is (assuming dm is positive)

$$dW_1 = -\frac{dm}{2\pi} \ln(\sigma - Re^{i\theta_0})$$

and for the pair, we have

$$dW = \frac{-dm}{2\pi} \ln \left(\frac{\sigma - Re^{i\theta_0}}{\sigma - Re^{-i\theta_0}} \right) \quad (I79)$$

It can be shown that the circle

$$\sigma = Re^{i\theta}$$

is a streamline of the complex potential given by equation (I79) although the points $Re^{i\theta_0}$ and $Re^{-i\theta_0}$ are singular points since many streamlines converge at these points, with a net mass flow through the circle at these points. Since ϕ and ψ are equal at corresponding points in the τ and σ planes in the conformal transformation of the flow, we can evaluate ψ on the wing panel in the τ plane. Let the velocity components in the

τ plane be v and w . Then on the wing panel

$$\frac{d\psi_o}{dy_o} = -w = + \delta V_\infty; \quad a \leq y_o \leq s \quad (I80)$$

Now since only half the source or sink flow passes through the fin

$$\frac{dm}{2} = \delta V_\infty dy \quad (I81)$$

and we have

$$dm = 2d\psi_o = 2\delta V_\infty dy_o \quad (I82)$$

Now summing all sources and sinks along both sides of the right panel between $a \leq y_o \leq s$, we have

$$W = -\frac{1}{\pi} \int_{\psi(a)}^{\psi(s)} \ln \left(\frac{\sigma - Re^{i\theta_o}}{\sigma - Re^{-i\theta_o}} \right) d\psi_o \quad (I83)$$

Integrating by parts, yields

$$W(\sigma) = \frac{\psi(\gamma)}{\pi} \ln \left(\frac{\sigma - Re^{i\gamma}}{\sigma - Re^{-i\gamma}} \right) - \frac{1}{\pi} \int_0^\gamma \psi(\theta_o) \frac{d}{d\theta_o} \left[\ln \left(\frac{\sigma - Re^{+i\theta_o}}{\sigma - Re^{-i\theta_o}} \right) \right] d\theta_o$$

$$W(\sigma) = \frac{\psi(\gamma)}{\pi} \ln \left(\frac{\sigma - Re^{+i\gamma}}{\sigma - Re^{-i\gamma}} \right) - \frac{2iR}{\pi} \int_0^\gamma \frac{(\sigma \cos \theta_o - R) \psi(\theta_o) d\theta_o}{\sigma^2 - 2\sigma R \cos \theta_o + R^2} \quad (I84)$$

We now evaluate ψ_o by integrating equation (I80)

$$\psi_o = \delta V_\infty y_o + k \quad (I85)$$

where k is an arbitrary constant which we will set equal to zero. We thus find the complex potential

$$W(\sigma) = \frac{\delta V_\infty}{\pi} \left\{ a \ln \left(\frac{\sigma - Re^{i\gamma}}{\sigma - Re^{-i\gamma}} \right) - i\sqrt{2} R^2 \int_0^\gamma \frac{(\sigma \cos \theta_o - R) \left[\sqrt{\cos 2\theta_o - \frac{a^2}{R^2}} + \sqrt{\cos 2\theta_o + \frac{a^2}{R^2}} \right]}{(\sigma^2 - 2\sigma R \cos \theta_o + R^2)} d\theta_o \right\} \quad (I86)$$

APPENDIX I

The expression of equation (I86) is the one which will be used to determine u , v and w . Several approaches are possible. First we might consider σ as a real quantity, and integrate equation (I86) to obtain $W(\sigma)$. Then invoking the principle of analytical continuation, we would assume σ was complex again, and separate $W(\sigma)$ into ϕ and ψ . Differentiation of ϕ then leads to u , v , and w . This approach was tried and the part of the second integral involving $\sqrt{\cos 2\theta_o - a^2/R^2}$ yields complete elliptical integrals of the third kind. The second part involving $\sqrt{\cos 2\theta_o + a^2/R^2}$ yields incomplete elliptic integrals of the third kind. To separate such an incomplete elliptic integral into real and imaginary parts was considered too formidable a task so that an alternate approach was decided. In this approach $W(\sigma)$ is differentiated, and an expression for $V - iW$ is obtained. Complex integration then yields V and W , the velocity components in the σ plane.

4.5 Determination of V and W

We will determine V , and W by carrying out the operation

$$V - iW = \frac{dW}{d\sigma} \quad (\text{I87})$$

on equation (I86) and evaluating the complex integral. Carrying out the operations yields

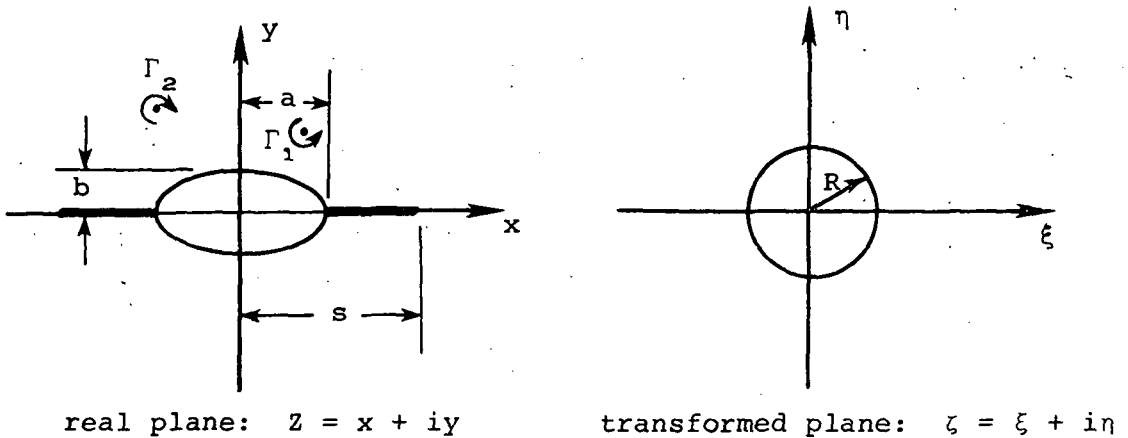
$$\begin{aligned} \frac{V - iW}{\delta V_\infty / \pi} &= \frac{a}{\sigma - R e^{i\gamma}} - \frac{a}{\sigma - R e^{-i\gamma}} \\ &+ i\sqrt{2} R^2 \int_0^\gamma \frac{[(\sigma^2 + R^2) \cos \theta_o - 2R\sigma] [\sqrt{\cos 2\theta_o + a^2/R^2} + \sqrt{\cos 2\theta_o - a^2/R^2}] d\theta_o}{(\sigma^2 - 2\sigma R \cos \theta_o + R^2)^2} \end{aligned} \quad (\text{I88})$$

Equation (I88) is solved numerically.

5.- Velocities on a Vortex Due to Other Vortices in the Crossflow Plane in the Presence of a Monoplane Midwing Mounted on a Body of Elliptic Cross-Section

5.1 Conformal Mapping

As the first step in the analysis, we transform the elliptical configuration into a circle of radius R.

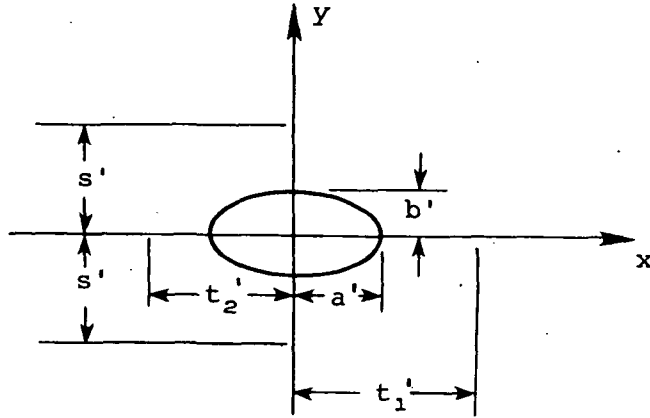


Bryson (ref. 22) has presented the desired conformal mapping for an elliptical body with wings and vertical tail. Bryson's configuration is rotated 90° from the present one. The conformal mapping for the configuration shown below is:

$$z = w + \frac{a'^2 - b'^2}{4w} \tag{I89}$$

$$\left[w + \frac{(a' + b')^2}{4w} \right]^2 = \left[\frac{h-f}{2} + \zeta + \frac{(h+f)^2}{16\zeta} \right]^2 - k^2 \tag{I90}$$

APPENDIX I



where

$$k = \sigma - \left[\frac{(a' + b')^2}{4\sigma} \right] \quad (I91)$$

$$h^2 = k^2 + \left[\tau_1 + \frac{(a' + b')^2}{4\tau_1} \right]^2 \quad (I92)$$

$$f^2 = k^2 + \left[\tau_2 + \frac{(a' + b')^2}{4\tau_2} \right]^2 \quad (I93)$$

and

$$\sigma = \frac{1}{2} \left(s' + \sqrt{s'^2 + a'^2 - b'^2} \right) \quad (I94)$$

$$\tau_1 = \frac{1}{2} \left(t_1' + \sqrt{t_1'^2 - a'^2 + b'^2} \right) \quad (I95)$$

$$\tau_2 = \frac{1}{2} \left(t_2' + \sqrt{t_2'^2 - a'^2 + b'^2} \right) \quad (I96)$$

For a configuration consisting of a monoplane midwing attached to the body with elliptical cross section (i.e. no vertical surfaces), we get the following special results.

$$t_1' = t_2' = s \quad (I97)$$

$$a' = a \quad (I98)$$

$$b' = b \quad (I99)$$

$$s' = b' = b \quad (I100)$$

In addition, we obtain

$$\begin{aligned} \tau_1 = \tau_2 &= \frac{1}{2} \left[s + \sqrt{s^2 - a^2 + b^2} \right] & (I101) \\ &= \tau \end{aligned}$$

$$\sigma = \frac{1}{2} (b + a) \quad (I102)$$

$$k = \frac{1}{2} (a + b) - \frac{(a + b)^2}{2(a + b)} = 0 \quad (I103)$$

$$h = f = \tau + \frac{\sigma^2}{\tau} \quad (I104)$$

The required conformal mapping without the tail fins is

$$z = w + \frac{a^2 - b^2}{4w} \quad (I105)$$

with

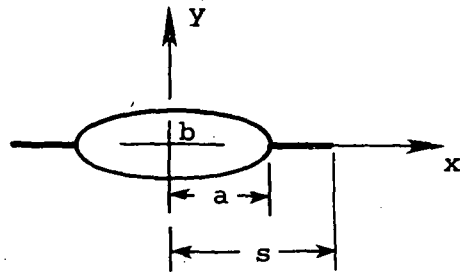
$$w + \frac{\sigma^2}{w} = \zeta + \frac{(h/2)^2}{\zeta} \quad (I106)$$

where

$$\sigma = \frac{1}{2} (a + b) \quad (I107)$$

$$h = \tau + \frac{\sigma^2}{\tau} \quad (I108)$$

$$\tau = \frac{1}{2} \left[s + \sqrt{s^2 - a^2 + b^2} \right] \quad (I109)$$



The radius of the circle in the transformed plane is

$$R = \frac{h}{2} = \frac{1}{4} \left[s + \sqrt{s^2 - a^2 + b^2} + \frac{(a + b)^2}{s + \sqrt{s^2 - a^2 + b^2}} \right] \quad (I110)$$

From equation (I106)

$$w = \frac{1}{2} \left\{ \zeta + \frac{(h/2)^2}{\zeta} \pm \sqrt{\left[\zeta + \frac{(h/2)^2}{\zeta} \right]^2 - (a + b)^2} \right\} \quad (I111)$$

also, from equation (I105)

APPENDIX I

$$w = \frac{1}{2} \left(z + \sqrt{z^2 - a^2 + b^2} \right) \quad (I112)^*$$

and, from equation (I106)

$$\zeta = \frac{1}{2} \left[w + \frac{\sigma^2}{w} \pm \sqrt{\left(w + \frac{\sigma^2}{w} \right)^2 - h^2} \right] \quad (I113)^*$$

The choice of signs in equations (I111) and (I113) will now be addressed. When evaluating these equations, use of the positive (+) sign will produce the correct result if the square root function is evaluated properly. The rule to follow in evaluating the square roots, is that the result should be a complex quantity in the same quadrant as the complex quantity appearing in the argument. This is particularly important if the original quantity is a negative real number. Thus, if:

$$\zeta + \frac{(h/2)^2}{\zeta} = -A$$

Then,

$$\left[\zeta + \frac{(h/2)^2}{\zeta} \right]^2 - (a+b)^2 = A^2 - (a+b)^2$$

Assuming $A^2 \gg (a+b)^2$, the square root of this is positive, and $\approx \pm A$. Then, for equation (I111)

$$w \approx \frac{1}{2} [-A \pm A] = 0$$

This does not follow from equation (I106) which suggests that if $\zeta + \frac{(h/2)^2}{\zeta}$ is large, then w should also be large. Thus, the proper solution of the square root would use the negative sign. In complex notation:

$$\zeta + \frac{(h/2)^2}{\zeta} = Ae^{i\pi}$$

Therefore,

* For body with elliptical cross section it can be shown that $w = \zeta$. Set $s = a$ in equation (I110), then compare equations (I111) and (I113).

$$\begin{aligned} \left[\zeta + \frac{(h/2)^2}{\zeta} \right]^2 - (a+b)^2 &= A^2 e^{i2\pi} - (a+b)^2 \\ &= \left[A^2 - (a+b)^2 \right] e^{i2\pi} \end{aligned}$$

so that

$$\begin{aligned} \left[\zeta + \frac{(h/2)^2}{\zeta} \right]^2 - (a+b)^2 &= \sqrt{A^2 - (a+b)^2} e^{i\pi} \\ &= -\sqrt{A^2 - (a+b)^2} \end{aligned}$$

5.2 Velocity of Vortex in Plane of Elliptical Wing-Body

In the circle plane, the complex potential for a set of vortices in the presence of the circle of radius R is given by equation (I5) as follows

$$\begin{aligned} W_1(\zeta) &= -\frac{i}{2\pi} \Gamma_0 \ln(\zeta - \zeta_0) + \frac{i}{2\pi} \Gamma_0 \ln \left[\zeta - \frac{R^2}{\zeta_0} \right] \\ &\quad - \frac{i}{2\pi} \sum_{j=1}^N \Gamma_j \ln \left[\frac{\zeta - \zeta_j}{\zeta - \frac{R^2}{\zeta_j}} \right] \end{aligned} \quad (\text{I114})$$

To find the motion of vortex Γ_0 in the Z plane the proper complex potential must take account of the fact that Γ_0 induces no velocity on itself

$$W_{\Gamma_0}(Z) = W_1\left[\zeta(Z)\right] + \frac{i\Gamma_0}{2\pi} \ln(Z - Z_0) \quad (\text{I115})$$

The velocity of the vortex at Z_0 is then:

$$v_0 - iw_0 = \lim_{Z \rightarrow Z_0} \left\{ \frac{d}{dZ} \left[W_{\Gamma_0}(Z) \right] \right\} \quad (\text{I116})$$

Equation (I116) yields

APPENDIX I

$$\begin{aligned} \frac{d}{dz} \left[W_{\Gamma_0}(z) \right] &= \frac{d}{dz} \left[-\frac{i}{2\pi} \Gamma_0 \ln \left(\frac{z - z_0}{z - z_0} \right) \right] + \frac{d}{dz} \left[\frac{i\Gamma_0}{2\pi} \ln \left(z - \frac{R^2}{z_0} \right) \right] \\ &\quad - \frac{i}{2\pi} \frac{d}{dz} \sum_{j=1}^N \Gamma_j \ln \left(\frac{z - z_j}{z - \frac{R^2}{z_j}} \right) \end{aligned} \quad (I117)$$

The first term presents a problem which must be resolved by the following limiting process

$$\begin{aligned} -\frac{i\Gamma_0}{2\pi} \frac{d}{dz} \left[\ln \left(\frac{z - z_0}{z - z_0} \right) \right] &= -\frac{i\Gamma_0}{2\pi} \left[\frac{z - z_0}{z - z_0} \right] \left[\frac{1}{z - z_0} \frac{dz}{dz} - \frac{z - z_0}{(z - z_0)^2} \right] \\ &= \frac{i\Gamma_0}{2\pi} \left[\frac{1}{z - z_0} - \frac{1}{z - z_0} \frac{dz}{dz} \right] \end{aligned} \quad (I118)$$

Expand ζ in a Taylor series about z_0 .

$$\begin{aligned} \zeta &= \zeta(z) \\ \zeta - \zeta_0 &= (z - z_0) \left. \frac{d\zeta}{dz} \right|_{z_0} + \frac{1}{2} (z - z_0)^2 \left. \frac{d^2\zeta}{dz^2} \right|_{z_0} \\ &\quad + \frac{1}{6} (z - z_0)^3 \left. \frac{d^3\zeta}{dz^3} \right|_{z_0} + o(z - z_0)^4 \\ \frac{d\zeta}{dz} - \left. \frac{d\zeta}{dz} \right|_{z_0} &= (z - z_0) \left. \frac{d^2\zeta}{dz^2} \right|_{z_0} + \dots \end{aligned} \quad (I119)$$

Then

$$\begin{aligned} \frac{\zeta - \zeta_0}{z - z_0} &= \left. \frac{d\zeta}{dz} \right|_{z_0} + \frac{1}{2} (z - z_0) \left. \frac{d^2\zeta}{dz^2} \right|_{z_0} + \frac{1}{6} (z - z_0)^2 \left. \frac{d^3\zeta}{dz^3} \right|_{z_0} \\ &\quad + o(z - z_0)^3 \end{aligned} \quad (I120)$$

Applying the limiting process to equation (I118), the result is

$$\begin{aligned} \lim_{z \rightarrow z_0} \left\{ -\frac{i\Gamma_0}{2\pi} \frac{d}{dz} \left[\ln \frac{\zeta - \zeta_0}{z - z_0} \right] \right\} &= \frac{i\Gamma_0}{2\pi} \lim_{z \rightarrow z_0} \frac{1}{(\zeta - \zeta_0)} \left[\frac{(\zeta - \zeta_0)}{z - z_0} - \frac{d\zeta}{dz} \right] \\ &= \frac{i\Gamma_0}{2\pi} \lim_{z \rightarrow z_0} \frac{1}{\zeta - \zeta_0} \left[\frac{1}{2}(z - z_0) \frac{d^2\zeta}{dz^2} \Big|_{z_0} + \frac{1}{6}(z - z_0)^2 \frac{d^3\zeta}{dz^3} \Big|_{z_0} + \dots \right. \\ &\quad \left. - (z - z_0) \frac{d^2\zeta}{dz^2} \Big|_{z_0} - \dots \right] \end{aligned} \quad (I121)$$

by substitution from equation (I119) and (I120). Since

$$\lim_{z \rightarrow z_0} \frac{z - z_0}{\zeta - \zeta_0} = \frac{dz}{d\zeta} \Big|_{z_0} \quad (I122)$$

we finally obtain for the first term

$$\lim_{z \rightarrow z_0} \left\{ -\frac{i\Gamma_0}{2\pi} \frac{d}{dz} \left[\ln \left(\frac{\zeta - \zeta_0}{z - z_0} \right) \right] \right\} = -\frac{i\Gamma_0}{2\pi} \frac{dz}{d\zeta} \Big|_{z_0} \frac{d^2\zeta}{dz^2} \Big|_{z_0} \quad (I123)$$

Carrying out the remaining differentiation yields an expression for the velocity at vortex Γ_0 due to the other vortices

$$\begin{aligned} v_0 - iw_0 &= -\frac{i\Gamma_0}{4\pi} \frac{dz}{d\zeta} \Big|_{z_0} \frac{d^2\zeta}{dz^2} \Big|_{z_0} + \frac{i\Gamma_0}{2\pi} \frac{\bar{\zeta}_0}{\zeta_0 \bar{\zeta}_0 - R^2} \frac{d\zeta}{dz} \Big|_{z_0} \\ &\quad - \frac{i}{2\pi} \sum_{j=1}^N \Gamma_j \left[\frac{1}{\zeta_0 - \zeta_j} - \frac{\bar{\zeta}_j}{\zeta_0 \bar{\zeta}_j - R^2} \right] \frac{d\zeta}{dz} \Big|_{z_0} \end{aligned} \quad (I124)$$

5.3 Evaluation of Certain Derivatives

We now evaluate the derivatives $\frac{dz}{d\zeta}$ and $\frac{d^2\zeta}{dz^2}$ required in equation (I124). From equations (I105) and (I111)

APPENDIX I

$$\frac{dz}{d\zeta} = \frac{dz}{dw} \frac{dw}{d\zeta} = \frac{1}{2} \left[1 - \frac{a^2 - b^2}{4w^2} \right] \left[1 - \frac{R^2}{\zeta} \right] \left[1 + \frac{\zeta + \frac{R^2}{\zeta}}{\sqrt{\left(\zeta + \frac{R^2}{\zeta}\right)^2 - (a+b)^2}} \right] \quad (I125)$$

From equations (I112) and (I113)

$$\frac{d\zeta}{dz} = \frac{d\zeta}{dw} \frac{dw}{dz} = \frac{1}{2} \left[1 - \frac{\sigma^2}{w^2} \right] \left[1 + \frac{w + \frac{\sigma^2}{w}}{\sqrt{\left(w + \frac{\sigma^2}{w}\right)^2 - h^2}} \right] \frac{dw}{dz} \quad (I126)$$

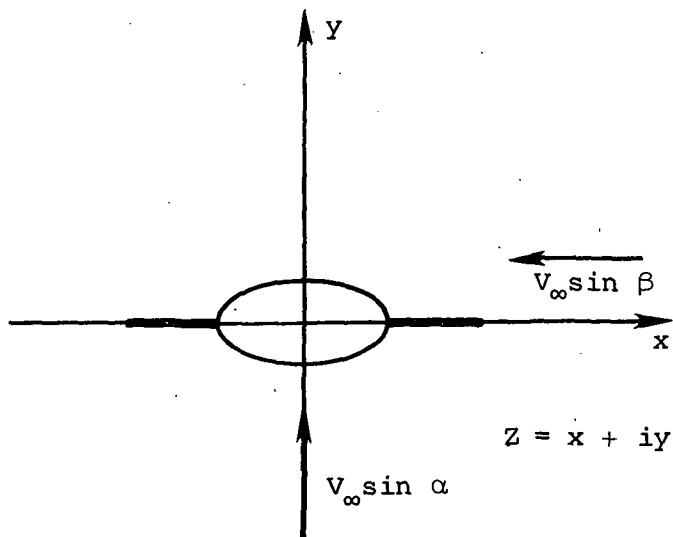
$$\frac{dw}{dz} = \frac{1}{2} \left[1 + \frac{z}{\sqrt{z^2 - a^2 + b^2}} \right] \quad (I127)$$

For the second derivative, we thus find

$$\begin{aligned} \frac{d^2\zeta}{dz^2} &= \frac{d}{dz} \left[\frac{d\zeta}{dz} \right] = \frac{dw}{dz} \frac{d}{dw} \left[\frac{d\zeta}{dz} \right] \\ &= \left(\frac{dw}{dz} \right)^2 \frac{d}{dw} \left[\frac{1}{2} \left(1 - \frac{\sigma^2}{w^2} \right) \left(1 + \frac{w + \frac{\sigma^2}{w}}{\sqrt{\left(w + \frac{\sigma^2}{w}\right)^2 - h^2}} \right) \right] \\ &= \left(\frac{dw}{dz} \right)^2 \left[\frac{\sigma^2}{w^3} \left(1 + \frac{w + \frac{\sigma^2}{w}}{\sqrt{\left(w + \frac{\sigma^2}{w}\right)^2 - h^2}} \right) \right. \\ &\quad \left. - \frac{1}{2} \left(1 - \frac{\sigma^2}{w^2} \right)^2 \frac{1}{\sqrt{\left(w + \frac{\sigma^2}{w}\right)^2 - h^2}} \left(\frac{h^2}{\left(w + \frac{\sigma^2}{w}\right)^2 - h^2} \right) \right] \end{aligned} \quad (I128)$$

6.- Velocity Components in the Crossflow Plane Due to Pitch
and Bank of a Monoplane Midwing Mounted on a
Body of Elliptical Cross Section

The sketch below shows a monoplane wing mounted on a body with elliptical cross section. The upwash is $V_\infty \sin \alpha$ and the sidewash is $V_\infty \sin \beta$ in the negative x-direction.



Consider the transformation of the wing-body combination into a circle of radius R in the ζ plane as described in section 5.1. For the pitch flow, the complex potential in the ζ plane is:

$$W_\alpha(\zeta) = -i V_\infty \sin \alpha \left(\zeta - \frac{R^2}{\zeta} \right) \quad (1129)$$

The velocity in the Z plane is then

$$v_\alpha - iw_\alpha = \frac{dw}{dZ} = \frac{dw_\alpha}{d\zeta} \frac{d\zeta}{dZ}$$

or

$$v_\alpha - iw_\alpha = i V_\infty \sin \alpha \left(1 + \frac{R^2}{\zeta^2} \right) \frac{d\zeta}{dZ} \quad (1130)$$

For the sideslip flow the complex potential in the ζ plane is

APPENDIX I

$$\begin{aligned}
 W_{\beta}(\zeta) &= -i V_{\infty} \sin \beta e^{-i\frac{\pi}{2}} \left(\zeta - \frac{R^2 e^{i\pi}}{\zeta} \right) \\
 &= -V_{\infty} \sin \beta \left(\zeta + \frac{R^2}{\zeta} \right)
 \end{aligned}
 \tag{I131}$$

The associated velocity components in the Z plane are given by

$$v_{\beta} - iw_{\beta} = -V_{\infty} \sin \beta \left(1 - \frac{R^2}{\zeta^2} \right) \frac{d\zeta}{dZ}
 \tag{I132}$$

7.- Velocities on a Vortex Due to Other Vortices in the Presence of a Monoplane Midwing Mounted on a Body of Elliptical Cross-Section Including Effects of Angles of Pitch and Sideslip

We follow the same conformal transformation described in section 5.1. The complete potential for the flow in the ζ plane is

$$\begin{aligned}
 W[\zeta(Z)] &= -i V_{\infty} \sin \alpha \left(\zeta - \frac{R^2}{\zeta} \right) + V_{\infty} \sin \beta \left(\zeta + \frac{R^2}{\zeta} \right) \\
 &\quad - \frac{i}{2\pi} \Gamma_0 \ln \left(\frac{\zeta - \zeta_0}{Z - Z_0} \right) + \frac{i}{2\pi} \Gamma_0 \ln \left(\zeta - \frac{R^2}{\bar{\zeta}_0} \right) \\
 &\quad - \frac{i}{2\pi} \sum_{j=1}^N \Gamma_j \ln \left(\frac{\zeta - \zeta_j}{\zeta - \frac{R^2}{\bar{\zeta}_j}} \right)
 \end{aligned}
 \tag{I133}$$

and the velocity at Z_0 is:

$$\begin{aligned}
 v_0 - iw_0 &= -i V_{\infty} \sin \alpha \left(1 + \frac{R^2}{\zeta_0^2} \right) \frac{d\zeta}{dZ} \Big|_{Z_0} + V_{\infty} \sin \beta \left(1 - \frac{R^2}{\zeta_0^2} \right) \frac{d\zeta}{dZ} \Big|_{Z_0} \\
 &\quad - \frac{i\Gamma_0}{4\pi} \frac{dZ}{d\zeta} \Big|_{Z_0} \frac{d^2\zeta}{dZ^2} \Big|_{Z_0} + \frac{i\Gamma_0}{2\pi} \frac{\bar{\zeta}_0}{\zeta_0 \bar{\zeta}_0 - R^2} \frac{d\zeta}{dZ} \Big|_{Z_0}
 \end{aligned}$$

(equation continued on next page)

$$- \frac{i}{2\pi} \sum_{j=1}^N \Gamma_j \left[\frac{1}{\zeta_0 - \zeta_j} - \frac{\bar{\zeta}_j}{\zeta_0 \bar{\zeta}_j - R^2} \right] \frac{d\zeta}{dZ} \Big|_{z_0} \quad (I134)$$

The derivatives $\frac{dZ}{d\zeta}$ and $\frac{d^2\zeta}{dZ^2}$ are given in section 5.3.

8.- Velocity Components in the Crossflow Plane Due to Expansion of a Body With Elliptical Cross Sections

Assume that the expansion occurs with constant a/b ratio. Equation (4-30) of reference 8 gives the desired complex potential

$$W_1(z) = \frac{S'}{2\pi} \ln \frac{z + \sqrt{z^2 - a^2 + b^2}}{2} \quad (I135)$$

$$S = \pi ab$$

$$a = a(x)$$

$$b = b(x)$$

If $\frac{a}{b} = 1/k$ then $S = \pi ka^2$ and $S' = 2\pi kaa' = 2\pi ka \frac{da}{dx}$.

Carrying out the differentiation yields the velocity components.

$$\begin{aligned} v - iw &= \frac{dw}{dZ} = \frac{S'}{2\pi} \frac{2}{z + \sqrt{z^2 - a^2 + b^2}} \left(\frac{1}{2} + \frac{2z}{2(2)\sqrt{z^2 - a^2 + b^2}} \right) \\ &= \frac{S'}{2\pi} \frac{1}{z + \sqrt{z^2 - a^2 + b^2}} \left(\frac{\sqrt{z^2 - a^2 + b^2} + z}{\sqrt{z^2 - a^2 + b^2}} \right) \\ &= \frac{S'}{2\pi} \frac{1}{\sqrt{z^2 - a^2 + b^2}} \end{aligned} \quad (I136)$$

APPENDIX J

DESCRIPTION OF PROGRAM DEMON2

The purpose of this appendix is to describe the supersonic lifting surface-body computer program in sufficient detail to permit understanding and use of the program. The present program is an extended and improved version of a pre-existing wing-body program as described in section 1 of this report.

Program DEMON2 computes pressure distributions on lifting surfaces and along the meridians of the body if it is circular in cross section. In this case, the program is equipped with body nose shed vorticity data modeled by two symmetric, discrete potential flow vortices. The effects of this vorticity are accounted for in the calculation of pressures on the body and lifting surfaces. If the body is elliptical in cross section, program WDYBDY described in Appendix K is employed to model the body and to compute pressures acting on it. Program WDYBDY also serves as a companion to DEMON2 for the purpose of calculating body induced velocities at the control points on the lifting surfaces through an exchange of data sets. The lifting surfaces can be cruciform canard fins or cruciform tail fins, a monoplane wing or interdigitated tail fins. For all but the last case, edge vorticity characteristics are calculated by the program.

By repeated application, program DEMON2 in conjunction with other programs can be employed to handle complete configurations including forward and tail lifting surfaces mounted on bodies with circular or elliptical cross section. Detailed descriptions of the required procedures are given in section 5.

The theoretical basis of program DEMON2 and its usage will first be summarized. Configuration parameters taken into consideration are listed. The general calculation procedure is given and it is followed by a description of the program operation. Program limitations and precautions are pointed out. The input required and the output generated by the program are described. Program listings appear at the end of this appendix.

Program Description

Fundamentally, the program is based on representing the lifting surfaces by constant u-velocity panels and the body with circular cross section by a distribution of line sources/sinks and doublets along its

centerline. Fin or wing thickness effects are modeled by planar source panels. The body source/sink and doublet strengths are determined explicitly from the flow tangency condition at points on the body surface. The body singularities and body nose vorticity, if applicable, induce velocity components at points on the lifting surfaces. The strengths of the constant u-velocity panels associated with the lifting surfaces and those laid out in a shell around the body to account for interference are obtained from a set of simultaneous equations which result from applying the flow tangency condition at a finite set of control points distributed over the lifting surfaces and interference shell. Thus, mutual interference between one lifting surface and another and between the lifting surfaces and the body are fully accounted for. Further details are given in section 2 and 3 of this report.

If the body is elliptical in cross section, a companion program designated WDYBDY, described in Appendix K, models the body using body source panels. In the main routine CRFWBD of program DEMON2, the effects induced by the body source panels and body nose vorticity, if applicable, are included in the flow tangency condition applied at points on the lifting surfaces. The program has been arranged to allow for an interference shell with elliptical cross section. The lifting surfaces attached to this shell can be a monoplane wing or a set of interdigitated tail fins. Mutual interference is accounted for in the manner described above. Refer to section 4 for more detail.

In the case involving an axisymmetric body, the program first treats the forebody and the forward or canard-body section. Effects of body nose vortices can be included in the calculation of pressures on the body and fins. The afterbody and tail fins are treated by another application of this program. Effects of body nose vortices and the canard edge vortices can be included in the calculated pressures acting on the aft body and loads on the tail fins. A separate program VPATH2, based on slender-body theory and described in Appendix L, is employed to determine the vortex paths along the complete configuration from the leading edge of the canard section back to the body base. The required procedure is described in section 5.1.

When the body is elliptical in cross section, the program first treats the forward or monoplane wing-body section. The forebody is

APPENDIX J

handled by program WDYBDY. Effects of body nose vortices can be accounted for in the calculation of pressures on the body and the monoplane wing. The part of the body between the monoplane wing and tail section is handled also by program WDYBDY. The interdigitated tail-body section is treated by another application of program DEMON2. Effects of body nose and monoplane wing edge vortices can be included in the calculated pressures acting on the afterbody and on the interdigitated tail fin-body section. A separate program VPATHL, based on slender-body theory and described in Appendix L, is used to track vortices from the leading edge of the monoplane wing section to the leading edge of the interdigitated tail section. Section 5.2 describes the required procedure in detail.

As far as the lifting surface sections are concerned, program DEMON2 computes pressure distributions, forces and moments including effects of external vortices, if applicable. The pressures on the fins or wing are calculated on the basis of linear and Bernoulli pressure relationships. For all cases except those including interdigitated tails, leading- and side-edge suction distributions are calculated for the purpose of modeling separation vorticity characteristics at these edges using Polhamus' analogy as described in Appendix C. At the trailing edges, one or more concentrated vortices are computed from the span load distribution using the method described in Appendix B.

Two calculative examples are described in section 6. It should be noted here that the program can also treat wings or fins alone. However, axisymmetric bodies alone cannot be handled. In the latter case, the program can still be used to obtain forebody pressures by including a set of artificial lifting surfaces at the base of the body of interest. Note that the program WDYBDY treats bodies alone. However, in the application of WDYBDY to axisymmetric bodies, computation time far exceeds the time required by program DEMON2 on account of the different type and number of singularities used to represent the body.

Geometrical Characteristics

Program DEMON2 contains the subroutines required to flow model bodies with circular cross section. The body is composed of a nose section followed by a cylindrical section. The nose section may have the following shapes (the choice is set by control index BCODE in namelist \$BODY

read in by subroutine BDYGEN):

	<u>Forebody Shape</u>
BCODE = 0	Parabolic
= 1	Sears-Haack*
= 2	Tangent-ogive
= 3	Ellipsoidal
= 4	Conical

The geometrical characteristics of the lifting surfaces that can be accounted for include the following:

Leading-edge shape:	Straight line which may be swept or it can be composed of straight line elements with different sweeps.
Trailing-edge shape:	Straight line which may be swept or it can be composed of straight line elements with different sweeps.
Thickness:	Accounted for by specifying streamwise slopes (not applicable to interdigitated tails).
Taper:	Uniform or broken.
Mean camber surface:	Planar.
Side edges:	Streamwise (not essential).
Dihedral:	Arbitrary, set by angle PHIDIR (see figure 3).
Location of interference shell:	Arbitrary, set by angle THETIT (see figure 3).

The lifting surfaces can be cruciform canard fins, cruciform tail fins, a monoplane wing or a set of interdigitated tails. In all instances, there must be a vertical plane of symmetry ($y_B = 0$ plane) as far as the geometry is concerned.

* Ashley, H. and Landahl, M.: Aerodynamics of Wings and Bodies, Addison-Wesley Publishing Co., Inc., 1965, pp. 180-181.

APPENDIX J

Calculation Procedure

Program DEMON2 proceeds through various stages as follows. After reading in the run identification, namelist \$INPUT is read in by main routine CRFWBD. Basically, this list contains wing or fin geometry data, flow conditions, geometry specifications for the interference shell and specifications for the distribution of constant u-velocity panels on the fin and the shell. In addition, moment-center coordinates and the vortex lift factors are specified. The wing- and body-coordinate systems are shown in figures 1 and 2.

The wings or fins of any fin-body combination are covered with a constant u-velocity panel layout with the panel side edges parallel to the fin root chords which, in turn, are made to be parallel to the body centerline. An optional input allows for unequal spanwise spacing of the side edges and breaks in sweep. The actual construction of the panel sweeps, centroid and control point coordinates is performed in subroutine LAYOUT. All coordinates are expressed in the x_w , y_w , z_w or wing coordinate system. Coordinate transformations relating a fin coordinate system with origin on the fin rootchord to the wing coordinate system are implemented in subroutine LAYOUT by means of function statements FYROT and FZROT. Subroutine LAYOUT also computes the geometrical characteristics of the body interference panels. Note that the leading and trailing edges of the interference panels are unswept, see figure 1.

As an option, the above process is repeated in subroutine THKLYT for the layout of planar source panels. They are used to account for thickness associated with the wings or fins of a cruciform, planar but not an interdigitated configuration such as the combination shown in figure 3. Streamwise thickness slopes are read in by subroutine THKIN. Depending on the procedural steps described in section 5, main routine CRFWBD can write a data set containing the coordinates, in the wing coordinate system, of the control points associated with the wings or fins and the interference shell. If control index NCPOUT is set equal to 2 in namelist \$INPUT, the run is stopped at this stage. Otherwise, the program continues as follows.

If the body is circular in cross section, main routine CRFWBD calls subroutine BDYGEN. This subroutine proceeds to read in namelist \$BODY

which contains body nose length and length of body to be modeled as well as control indices governing the number of line singularities distributed along the body centerline and the shape of the body nose. The layout and strengths of the line sources/sinks and line doublets employed to flow model the body are then computed for the flow conditions read in by name-list \$INPUT. Main routine CRFWBD then calls subroutine BDYPR which computes pressure distributions at points along the meridians on the body with circular cross section. The Bernoulli pressure, equation (10), is used for this purpose on this process, effects of body nose vorticity and body line singularities are accounted in the pressures calculated on the forebody. Over the length of body covered by the lifting surfaces, the pressures are computed at the control points of the body interference panels in the interference shell. This is performed following entry point BDYAFT after the panel strengths are calculated. The velocity components used in the pressure calculation include contributions from the body line singularities, external vortices and constant u-velocity and source panels distributed over the fins or wings. The effects of external vortices (such as body nose vortices) can be accounted for on the basis of the vortices moving parallel to the body centerline (subroutine VRTVEL) or the vortices moving in the crossflow plane (program VPATH2 or VPATHL). Subroutine BDYPR also calculates the pressures on the length of body between the forward and aft lifting surface sections.

Velocity components induced by line singularities associated with the axisymmetric body at the control points on the lifting surfaces and interference shell are calculated by subroutine VELCAL. These components will be used in the flow tangency condition applied at points on the lifting surfaces and in the calculation of pressures at points on the lifting surfaces and the interference shell.

For cases involving bodies with elliptical cross sections, main routine CRFWBD calls subroutine BDYRD which reads in velocity components induced by the body source panels at the control points distributed over the lifting surfaces and interference shell. These velocities will be used in the flow tangency condition applied at the control points on the lifting surfaces and the calculation of pressures at points on the lifting surfaces and the interference shell.

Routine CRFWBD continues with the construction of the influence coefficient matrix associated with the constant u-velocity panels laid out on the lifting surfaces and the interference shell. In this process, subroutine VELNOR performs the superposition of 4 corner solutions associated with a trapezoidal, constant u-velocity panel. For each corner subroutine VELO computes the influence of a semi infinite triangle. If the flow conditions dictate symmetry in loading (w.r.t. the y_B (or y_W) = 0 plane), subroutine VELNOR also accounts for the influence of the constant u-velocity panels on the opposite side of the plane of symmetry. Appendix A contains a discussion concerning the superposition scheme and the symmetry account.

The aerodynamic influence matrix, designated FVN, consists of the left-hand sides of equations (1) through (5) in section 3.4 and is triangularised by subroutine LINEQS. The right-hand sides of these equations are formed as a single column matrix designated RHS. For the control points on the lifting surfaces, the latter contains contributions from the free stream (including effect of deflection angle), body singularities (line singularities or source panels) and external vortices if applicable. For the control points on the interference shell, the right-hand side only contains contributions from the planar source panels modeling thickness of the lifting surfaces. These contributions are calculated by a call to subroutine THKVEL. Note that thickness effects are not accounted for if the lifting surfaces are interdigitated tails.

In the determination of velocity components normal to the panels on the lifting surfaces, transformations from the reference or wing coordinate system to the fin coordinate system are required. Subroutine ROTATE with entry points ROTWF and ROTFW contains the rotational coordinate transformation described in Appendix D. These transformations are used in the determination of normal velocity components as indicated in Appendix E and apply to cruciform, monoplane and interdigitated lifting surface configurations. Likewise, velocity transformations are performed from the reference or wing coordinate system to the local body interference panel coordinate system. These transformations are performed in subroutine TRBIPW with entry points TRWBIP (for coordinates), ROTBW and ROTWB (for velocities). The angles associated with the transformations

are indicated in figure 3. The velocity transformations apply to both the left- and right-hand sides of equations (1) through (5).

Main routine CRFWBD then calls subroutine SOLVE which takes the triangulated aerodynamic influence coefficient matrix, FVN, generated by LINEQS and the single column matrix, RHS, and proceeds to solve for the unknown strengths of the constant u-velocity panels.

Subroutine LOADS is then called to compute forces and moments acting on the lifting surfaces and the interference shell. Transformations from the local fin or body interference panel coordinate system to the reference or wing coordinate system are performed for the force and moment coefficients. For example, the force acting normal to the fins must be resolved into the y_W or y_B and z_W or z_B directions associated with the wing or body coordinate systems. The procedure is described in Appendix F. Note that the force and moment transformations also apply to monoplane or cruciform lifting surface configurations. The forces and moments are calculated in the body coordinate system and then transformed into the wind axis coordinate system in accordance with equations (18) and (19). These equations appear in section 4.2 in connection with calculations performed in program WDYBDY and apply to subroutine LOADS of program DEMON2 as well.

The loads acting on the interference shell calculated by subroutine LOADS represent only the lift carryover from the lifting surfaces to the body and may include interference due to fin or wing thickness. The pressures acting on the interference shell calculated by subroutine BDYPR (through entry point BDYAFT) include effects not only from the lifting surfaces but also include contributions from body singularities and external vortices if applicable. As such the pressures are indicative of the total load acting on the body over the length covered by the lifting surfaces.

Subroutine LOADS calculates the fin and interference shell loads first on the basis of linear pressure. This is followed by a call to subroutine SPECPR from subroutine LOADS to compute pressures acting on the lifting surfaces using the Bernoulli pressure equation (10). The loads acting on the lifting surfaces are then recalculated on the basis of the Bernoulli pressures.

APPENDIX J

If the lifting surfaces do not form an interdigitated fin configuration, subroutine LOADS calls subroutine SPNLD for the purpose of calculating spanload distributions, leading- and side-edge suction distributions. Using the span loading information, the strength and spanwise location of the concentrated trailing-edge vortices are calculated in accordance with Appendix B. The vorticity characteristics associated with the leading and side edges are determined from the suction distributions as described in Appendix C.

Program Operation

The cruciform wing-body computer program is written in the FORTRAN IV language (029 punch) and has been run on the CDC 6600 machine belonging to Boeing Computer Services, Inc. The main program is arranged so that a total of 250 constant u-velocity panels is available to cover the wing surfaces and to be used as body interference panels. A total of 100 sources and 100 doublets can be used to model the body. If the program is to be run on a different computer with smaller core memory, dimension statements need to be changed to permit operation on that machine.

In addition to the standard input and output tapes (TAPE5=INPUT, TAPE6=OUTPUT), the program may require additional devices such as disc files or tapes for storing data sets generated when certain options are used. One data set would consist of a set of control point coordinates and the other would contain a set of perturbation velocities. Devices used for these purposes are TAPE4 and TAPE7. The program employs a system-supplied subroutine REQFL which computes the actual dimension requirement for the aerodynamic coefficient matrix FVN. This subroutine makes use of special machine-dependent parameters. Certain other systems may have a similar subroutine available. If no such subroutine is available, the dimension of array FVN should be set to 62,500 and the four calls to REQFL marked in the main program removed.

Additional system-supplied devices used by the main program are the BUFFER OUT and BUFFER IN options. They are used as an option to save the triangulated aerodynamic influence matrix FVN associated with the fins and body interference shell. TAPE3 is used for this purpose. This procedure saves time when calculations are done for a given configuration at some Mach number but with different included angles of attack or roll.

However, the pertinent calls should be removed from the main program if other systems do not offer such devices.

Program DEMON2 treats one set of lifting surfaces on a body. In order to handle complete configurations involving forward and tail lifting surfaces, the program must be used in a stepwise manner in conjunction with other programs described in this report. A detailed description of the required procedure is given in section 5.

Running time required by program DEMON2 is governed by the number of constant u-velocity panels laid out on the lifting surfaces. For a pitched and rolled cruciform wing-body combination employing 192 constant u-velocity panels and 22 sources/sinks and doublets, the running time on the CDC 6600 is about 60 seconds for one set of flow conditions.

Program Limitations and Precautions

There are some problems that could arise in the use of the cruciform wing-body program. It should be noted that subroutines LOADS, BDYPR, VRTVEL, ROTATE and TRBIPW contain entry points. The first does not employ an argument list and should not cause any problems. However, the entry points in the second, third, fourth and fifth may need to have the appropriate subroutine argument list attached to them if other computer machines are used.

A warning is concerned with the use of system subroutine REQFL and the BUFFER devices already mentioned above under program operation. If the subroutine is not available, an equivalent subroutine can be called or the calls to REQFL can be removed and the dimension on FVN set to 62,500. Similarly, if the BUFFER devices are not system supplied, calls to them in the main program should be removed.

In the specification of the number of constant u-velocity panels to be distributed on the fins and body in namelist \$INPUT, the following limits must be kept in mind. For the fins, a maximum of 150 panels are available. In the spanwise direction, the maximum number of panels is 19. The number of body interference panels must not exceed 100. Finally, the total number of panels on the fins and interference shell cannot exceed 250. In namelist \$BODY, the number of sources/sinks and the number of doublets (both specified by NXBODY) cannot exceed 100.

APPENDIX J

Care must be taken with the use of control indices NOUT and NPR. A very large amount of additional output is generated when these indices are set equal to one. This output should only be used for debugging purposes employing a minimum number of constant u-velocity panels such as two per fin and four on the circumference of the body interference shell with two in the lengthwise direction.

A maximum magnitude is set by the program for the perturbation velocities induced by external vortices at the control points in the flow tangency condition. Since these velocities are based on potential vortex theory, their values could assume large magnitudes if the vortices run close to the fins and cause undue influence. Consequently, their magnitude is limited to 0.35. This value can be overridden by setting variable VRTMAX in namelist \$INPUT equal to the desired value.

At the present time, program DEMON2 computes pressure distributions on the body surface and lifting surfaces of complete configurations in conjunction with other programs as described in section 5. The program also determines the force and moment coefficients associated with the lifting surfaces but it does not compute the forces and moments acting on the body if it is circular in cross section. The latter quantities can be determined by an integration of the program calculated pressure distributions. In this connection, the program calculated forces and moments associated with the interference shell only represent the effects of lift carryover from the lifting surfaces to the body although effects of thickness may be included. The actual loads acting on the part of the body in the lifting surface section can also be determined from the pressure distributions.

Span load and suction distributions and the associated edge vorticity characteristics are not calculated for interdigitated fins at this time. Thickness effects are also not accounted for this type of lifting surface configuration.

Description of Input

This section describes the input for program DEMON2 for treating one set of lifting surfaces on a body. In the following discussion, the content of all input cards is summarized. All possible input variables

are listed at the end of this section in the order of appearance in the input deck, except for the first four variables which do not appear in the input deck but are needed for program input preparation. Sample inputs are discussed in section 6 concerned with the calculative examples. Note that the correspondence in designation between interdigitated fins and cruciform fins is indicated in figure 3 and also referred to in item 2 below.

Item 1

The first card serves as identification and may contain any alphanumeric information desired. This information is printed on the first page of the output.

Item 2

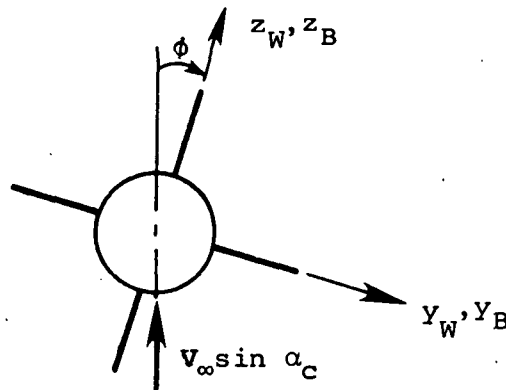
The second and following cards form the namelist \$INPUT which specifies the geometrical parameters of the wing surfaces and interference shell. These parameters are the leading-edge and trailing-edge sweeps, semispan and rootchord. For a planar wing or cruciform wing alone, the rootchord is the wing centerline or the cruciform wing junction. In the case of a wing-body combination, the rootchord is the line formed by the junction of the lifting surface and the body. The semispan is measured from the rootchord in any case.

This namelist also contains the deflection angles and the number of chordwise and spanwise constant u-velocity panels for each lifting surface. The spanwise number may differ from one fin to another but the chordwise number NCW is the same for all. Similar information is specified for the layout of planar source panels. The number of body interference panels, NBD CR, on the circumference are also included in this namelist. The specification of the latter also determines whether or not a body is present. The number of body interference panels in the axial direction is specified by NCWB. The body can be cylindrical or elliptical in cross section over the interference length, BIL, spanned by the lifting surfaces. If the interference shell is elliptical, the horizontal semi-axis RB and vertical semi-axis RA must be specified. The ratio RB/RA must equal ERATIO. If the interference shell is circular, set RB equals RA and ERATIO equals 1. If the lifting surfaces are delta wings (unswept trailing edges), length BIL equals the rootchord CRP. If the trailing edges are

APPENDIX J

swept back, the length BIL should be extended to include the trailing edge of the tip chord to account properly for the interference of the lifting surfaces on the body.

The included angle of attack, ALFAC, is the angle between the free stream and the body/wing centerline (x_B -axis in figure 1). Angle of roll, PHI, is indicated by ϕ in the sketch below. The program computes pitch and sideslip angles in accordance with the pitch-roll transformation mentioned in section 4 of this report.



Setting control index NDRAG equal to 1 results in the calculation of in-plane forces (Appendix C) acting on the lifting surfaces. At the present time, this is not possible when the lifting surfaces form an interdigitated configuration and NDRAG should be set equal to 0 (the default value) for this case.

In addition, more control indices, free-stream Mach number, and reference quantities SREF and REFL are read in. Breaks in leading-edge and/or trailing-edge sweeps are also allowed if the configuration is a wing or cruciform wing alone at zero sideslip or if the configuration consists of a monoplane or cruciform or interdigitated wing-body. This option is governed by control index LVSWP. Angles SWLEP, SWTEP, SWLEV, and SWTEV need not be specified if LVSWP \neq 0.

Indices NCPOUT, NVLIN, ITAIL, JCPT play an important part in the procedural use of program DEMON2 as described in section 5 in this report. Quantities FKLE and FKSE are the vortex lift factors discussed in Appendix C. The axial location of the moment center, XM, must be specified in the body coordinate system with origin at the nose.

Angles PHIDIH and THETIT are indicated on figure 3 and apply to monoplane and interdigitated lifting surface configurations. Note that the correspondence in designation between interdigitated fins and cruciform fins is indicated in figure 3. It is also referred to in connection with the fin deflection angles listed under item 2.

Item 3

This optional input is required when there are breaks in the wing sweep or if the constant u-velocity panel side edges are to be laid out with user-determined unequal spanwise spacings. This input pertains only to a wing or cruciform wing alone at zero sideslip. Variable YR is the distance from the rootchord to the outboard panel side edges. Therefore, the first value for YR is zero. The last value for YR must equal wing semispan, B2, specified in the namelist \$INPUT. In effect, this specification positions the panel outboard side edges on the right wing. The sweep angles are positive for wings with sweptback leading and trailing edges.

Item 4

The optional input of this item is associated with a wing-body combination with breaks in leading-edge and/or trailing-edge sweeps. Also, this input should be used for this configuration if the constant u-velocity panel side edges are to be laid out with user-determined unequal spacings. Variable YRT is the distance from the wing rootchord to the outboard constant u-velocity panel edges on the right wing or fin. The first value should equal 0.0 and the last value for YRT equals the semispan, B2; the latter is specified in the namelist \$INPUT. The sweep angles are positive for right wings or fins with sweptback leading and trailing edges.

Item 5

This optional input accompanies Item 4 and is associated with the left wing or fin. Variable YLT is the distance from the wing rootchord to the outboard constant u-velocity panel edges on the left wing or fin. The first value should equal 0.0 and the last value for YLT equals the negative semispan, -B2. The sweep angles are negative for left wings or fins with sweptback leading and trailing edges.

APPENDIX J

Item 6

The information in this optional item accompanies Items 4 and 5 if the configuration is a cruciform or interdigitated wing-body combination. Again, this input should only be used if there are breaks in the wing or fin sweeps or if the panel side edges are to be laid out with user-determined unequal spacings. Variable ZUT is the distance from the wing rootchord to the outboard constant u-velocity panel edges on the upper wing or fin. The first value should equal 0.0 and the last equals the semispan, B2V. The latter is specified in namelist \$INPUT. The sweep angles are positive for upper wings or fins with sweptback leading and trailing edges.

Item 7

This optional information is the last of four inputs associated with a cruciform or interdigitated wing-body combination if there are breaks in sweep or if the constant u-velocity panel side edges are to be laid out with user determined spacings; see Items 4 through 6. Variable ZDT is the distance from the wing rootchord to the outboard constant u-velocity panel edges on the lower wing or fin. The first value should equal 0.0 and the last value for ZDT must equal -B2V. The sweep angles are negative for lower wings or fins with sweptback leading and trailing edges.

Item 8

This item is concerned with the specification of the layout and strengths of the planar source panels employed to model thickness of the lifting surfaces. If the case at hand involves interdigitated lifting surfaces, this item must be omitted in the input (NTDAT=0). Basically, the planar source panels are laid out in the same manner used to layout the constant u-velocity panels. However, in this case the distance out to the outboard panel edge is now measured from the body centerline not the rootchord of the lifting surface under consideration. Breaks in sweep are handled by control index LVSWT in the same way control index LVSWP handled breaks in sweep in the layout of constant u-velocity panels.

The strengths of the planar source panels are related directly to the streamwise slopes and must be specified a priori. An example of such

a specification is shown in section 6.2.. Note that quantity THET is in fact the tangent of the thickness envelope angle, $\tan \theta_s$.

Item 9

The input cards for this item form the namelist \$BODY which is required only when a body with circular cross section is part of the configuration under consideration. If the integer NBDCR in namelist \$INPUT under Item 2 is specified to be nonzero, and RB equals RA, a body with circular cross section is present. The information in this input includes specification of body geometry parameters and is read in by subroutine BDYGEN. The length of the nose, LNOSE, determines the body length over which the radius is changing as a function of the body axial coordinate. The actual nose configuration is governed by control index, BCODE, which selects preprogrammed forebody shapes described above in this appendix.

Normally, the body length, LBODY, should at least equal the axial distance from the body nose to the trailing edges of the lifting surfaces under consideration. If the trailing edges are sweptback, length LBODY should be taken to include the trailing edge of the tip chords or side edges of the lifting surfaces at hand.

The minimum number of body modeling singularities NXBODY should be determined as follows. Let the density (sources and doublets/unit body length) be determined by the number of constant u-velocity panels in the chordwise direction on the wing divided by the rootchord (or length of wing-body junction). Then, number NXBODY equals the density times body length.

Item 10(a)

This input is required only when variable NVRTX specified in namelist \$INPUT, Item 2, is nonzero and if the body is circular in cross section. In fact, NVRTX is the number of external, two-dimensional vortices whose influences are to be included in the pressure and loading calculations. Each vortex is assumed to be infinite in length and to be parallel to the body centerline. Therefore, with each vortex there is associated a non-dimensional strength, GAMMA, and nondimensional crossflow plane coordinate, YVRTX, ZVRTX, given in the body or wing coordinate system shown in figure 1. These quantities are input in subroutine VRTVEL.

APPENDIX J

Item 10(b)

This input is required only when variable NVRTX specified in namelist \$INPUT, Item 2, is nonzero and if the body is elliptical in cross section. As in item 10, each vortex is assumed infinite in length and to be parallel to the body centerline. In this case, the strength GAMMA is Γ/V_∞ , and YVRTX and ZVRTX are the coordinates expressed in the wing coordinate system for each vortex. This information is read in by main routine CRFWBD.

Items 11, 12, 13, 14

The information specified in these items pertain to leading- and side-edge vorticity characteristics. If specified in the input, their influence would influence the pressures and loads on the lifting surfaces and the interference shell under consideration. Presently, it is not recommended to include edge vorticity effects associated with a lifting surface in the calculation of the loading acting on the same lifting surface. Thus, a blank card can be inserted for items 11 and 13.

Item 15

This card ends the process of reading in data for program DEMON2. It should only be put at the end of all data cards for the case(s) to be run. The computer program stops the search for more data and the run is finished.

INPUT VARIABLES, PROGRAM DEMON2

The terms "right and "left" refer to an observer looking forward.

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
MSWRP	Definitions of terms used below	(Number of chordwise rows on right wing) + 1; MSWRP = MSWR + 1.
MSWLP		(Number of chordwise rows on left wing) + 1; MSWLP = MSWL + 1.
MSWUP		(Number of chordwise rows on upper wing) + 1; MSWUP = MSWU + 1.
MSWDP		(Number of chordwise rows on lower wing) + 1; MSWDP = MSWD + 1.

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
<u>Item 1</u>	(20A4)	Any alphanumeric information may be put on this card for identification of the calculation.
<u>Item 2</u>		Namelist \$INPUT.
CRP	$c_{r,H}$	Horizontal wing rootchord, dimensional.
SWLEP	$\Lambda_{LE,H}$	Horizontal wing leading-edge sweep angle measured in wing planform, positive for sweep back, degrees.
SWTEP	$\Lambda_{TE,H}$	Horizontal wing trailing-edge sweep angle measured in wing planform, positive for sweep back, degrees.
NCW		Number of chordwise constant u-velocity panels on the wing.
MSWR		Number of spanwise constant u-velocity panels on right wing; $1 \leq MSWR \leq 19$.
MSWL		Number of spanwise constant u-velocity panels on left wing; $1 \leq MSWL \leq 19$, default is 0.
MSWU		Number of spanwise constant u-velocity panels on the upper wing; $1 \leq MSWU \leq 19$, default is 0.
MSWD		Number of spanwise constant u-velocity panels on the lower wing; $1 \leq MSWD \leq 19$, default is 0. <u>Note:</u> When running symmetric case <u>do not</u> include vertical surfaces. Set NCRX = 0 MSWL = 0 MSWU = 0 MSWD = 0
SWLEV	$\Lambda_{LE,V}$	Vertical wing leading-edge sweep angle measured in wing planform positive for sweep back, degrees, default is 0.0.
SWTEV	$\Lambda_{TE,V}$	Vertical wing trailing-edge sweep angle measured in wing planform, positive for sweep back, degrees, default is 0.0.
CRPV	$c_{r,V}$	Vertical wing rootchord, dimensional, default is 0.

APPENDIX J

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
B2	$b_H/2$	Exposed horizontal wing semispan, dimensional.
B2V	$b_V/2$	Exposed vertical wing semispan, dimensional, default is 0.0.
RA	b	Vertical semi-axis for body with elliptical cross section.
RB	a	Horizontal semi-axis for body with elliptical cross section.
ERATIO	a/b	Ratio of RB over RA <u>Note:</u> If body has circular cross section set RA = RB and ERATIO = 1.0.
BIL		Length of body influenced by fins to account for interference. For fins with delta planform and for wing-alone cases, BIL = CRP.
NFVNPR		NFVNPR \neq 0 Print influence coefficient matrix FVN for debugging, default is 0.0.
NOLINP		NOLINP = 0 Loadings calculated on the basis of linear pressures only, default value. NOLINP = 1 Loadings calculated on the basis of linear and Bernoulli pressures.
NOUT		NOUT \neq 0 Print large amount of output for debugging, default is 0.0.
NPR		Same as NOUT, default is 0.0.
NDRAG		NDRAG = 0 Omit calculation of in-plane forces, default value. NDRAG = 1 Include calculation of in-plane forces. Use default value when treating interdigitated tails.
FAC		FAC = 0.95 Fraction of the constant pressure panel chord (which contains the centroid) where the control point is located.
TOLFAC		TOLFAC = 1 Multiplication factor used in the evaluation of the tolerance, TLRNC, used in subroutine VELO.

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
NPRESS		NPRESS = 0 This value insures that loadings are also computed on the basis of the linear pressure relationship in addition to the Bernoulli pressure relationship.
VRTMAX		Maximum magnitude of vortex induced velocities included in flow tangency condition, default is 0.35.
NVRTPL		NVRTPL = 0 Component of velocity parallel to fin induced by vortices not included in Bernoulli loading pressure, default value. NVRTPL = 1 Loading pressure calculated including parallel component of vortex induced velocity.
NAGAIN		NAGAIN = 0 No use made of buffer to save aerodynamic influence matrix, FVN, after triangulation, default value = 0. NAGAIN = 1 Buffer out FVN array. For succeeding runs, keep NAGAIN = 1.
DELR	$\delta_{H,R}$	Deflection angle of horizontal right wing. Positive: trailing edge down, degrees, default is zero.
DELL	$\delta_{H,L}$	Deflection angle of horizontal left wing, Positive: trailing edge down, degrees, default is 0.0.
DELU	$\delta_{V,U}$	Deflection angle of vertical upper wing, Positive: trailing edge to right, degrees, default is 0.0.
DELD	$\delta_{V,D}$	Deflection angle of vertical lower wing, Positive: trailing edge to right, degrees, default is 0.0. If case involves <u>interdigitated fins</u> : $\delta_{H,R}$ applies to right upper fin, trailing edge down is positive. $\delta_{H,L}$ applies to left lower fin, trailing edge down is positive. $\delta_{V,U}$ applies to right lower fin, trailing edge down is positive. $\delta_{V,D}$ applies to left upper fin, trailing edge down is positive.
ALFAC	α_c	Included angle of attack, measured between free-stream velocity vector and body/wing centerline.

APPENDIX J

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
PHI	ϕ	Angle of roll, measured from the plane containing the free-stream velocity vector and the body/wing centerline to the upper wing, positive clockwise looking forward, default is 0.0.
FMACH	M_{∞}	Free-stream Mach number.
LVSWP		LVSWP = 0 No breaks in wing leading or trailing edges, or equal spanwise spacings of panel side edges, default value. LVSWP \neq 0 Up to 19 breaks in wing leading or trailing edges or up to 19 unequal spanwise spacings.
NVRTX		Number of external vortices present, NVRTX \leq 10 (see Item 10(a)).
NCRX		NCRX = 0 Horizontal wing only present, default value. NCRX = 1 Vertical wing surfaces in addition to horizontal wing surfaces present.
NBDCR		Number of constant u-velocity panels on the circumference of the body. NBDCR = 0 No body present, default value. NBDCR > 0 Body present (see Item 8).
NCWB		Number of constant u-velocity panels in the longitudinal direction on the surface of the body over the body interference length BIL, default is 0.0.
SREF	S_{ref}	Reference area used in load calculations, default is 1.
REFL	l_{ref}	Reference length used in rolling-moment calculations, default is 1.
ITAIL		ITAIL = 1 Tail fins to be considered, default is 0. If case involves interdigitated fins mounted on body with elliptic cross section set ITAIL = 0.
NBDYPR		NBDYPR = 1 Pressures to be calculated along body meridians, default is 0.

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
NTPR		NTPR = 1 Print debug output from subroutine THKVLE, default is 0.
NTDAT		Number of sets of thickness data to be input. Set NTDAT=0 for cases involving interdigitated fins. NTDAT = 0 No thickness input data, default value. NTDAT = 1 For horizontal wing, symmetric layout <u>or</u> for cruciform wing, symmetric layout with layout on vertical wings same as on horizontal wings. NTDAT = 2 For cruciform wing, symmetric layout. Vertical wing layout different from horizontal <u>or</u> for horizontal wing alone (delta wing) with asymmetric layout. NTDAT = 4 For cruciform wing alone (delta wing), asymmetric layout.
NCWT		Number of source panels in a chordwise row, default is 0.
NCPOUT		NCPOUT = 0 No control point coordinates written, default value. NCPOUT = 1 Write coordinates (in wing coordinate system) of control points on fin and body interference shell in data set (TAPE4), and continue the run. NCPOUT = 2 Write coordinates (in wing coordinate system) of control points on fin and body interference shell in data set (TAPE4) and stop the run (STOP77).
NVLIN		NVLIN = 0 Do not read in velocity components induced by moving vortices. NVLIN = 1 Read in velocities induced by moving vortices (calculated by program VPATH2 or VPATHL) from a data set (TAPE7), default is 0.
XSTART		Axial station aft of which body pressures are to be calculated. If case involves interdigitated tails on body with elliptic cross section, set XSTART = 0.0, default is 0.0.

APPENDIX J

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
JCPT		Number of control points and body pressure points calculated by subroutine BDYPR and printed in output. This number is required when NVLIN = 1 and ITAIL = 1, default is 0.
FKLE		Fraction of leading-edge suction converted into normal force, default is 0.5.
FKSE		Fraction of side-edge suction converted into normal force, default is 0.5.
XM		x-coordinate of moment center in body coordinate system, default is 0.0.
ZM		z-coordinate of moment center in body coordinate system, default is 0.0.
PHIDIH	ϕ_F	Dihedral angle associated with interdigitated fin, default is 0.0, $0 \leq \phi_F < 90^\circ$.
THETIT	θ	Location angle associated with interdigitated fin, default is 0.0, $0 \leq \theta < 90^\circ$.
XWLE		Axial location of wing rootchord leading edge measured from body nose, default is 0.0.
<u>Item 3</u>	(3F10.5)	Optional input for planar or cruciform wing alone at zero sideslip.
YR(KJ)	$Y_{W,R}$ (KJ)	Distance from wing rootchord to the constant pressure panel outboard side edge on right wing, $1 \leq KJ \leq MSWRP$, ($MSWRP \leq 30$), $YR(1) = 0.0$, $YR(MSWRP) = B2$.
VSWLER(KJ)	$\Lambda_{LE,R}$ (KJ)	Leading-edge sweep of wing between YR(KJ-1) and YR(KJ), positive for sweep back, degrees, $1 \leq KJ \leq MSWRP$, ($MSWRP \leq 20$), $VSWLER(1) = 0.0$.
VSWTER(KJ)	$\Lambda_{TE,R}$ (KJ)	Trailing-edge sweep of wing between YR(KJ-1) and YR(KJ), positive for sweep back, degrees. $1 \leq KJ \leq MSWRP$, ($MSWRP \leq 20$), $VSWTER(1) = 0.0$.
<u>Item 4</u>	(3F10.5)	Optional input for wing-body combination.
YRT(KJ)	Y_R (KJ)	Distance from wing rootchord to the constant u-velocity panel outboard side edge on right wing, $1 \leq KJ \leq MSWRP$, ($MSWRP \leq 20$), $YRT(1) = 0.0$, $YRT(MSWRP) = B2$.

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
VSWLER(KJ)	$\Lambda_{LE,R}^{(KJ)}$	Leading-edge sweep of wing between (YRT(KJ-1) and YRT(KJ)), positive for sweep back, degrees, $1 \leq KJ \leq MSWRP$, ($MSWRP \leq 20$), VSWLER(1) = 0.0.
VSWTER(KJ)	$\Lambda_{TE,R}^{(KJ)}$	Trailing-edge sweep of wing between (YRT(KJ-1) and YRT(KJ)), positive for sweep back, degrees, $1 \leq KJ \leq MSWRP$, ($MSWRP \leq 20$), VSWTER(1) = 0.0.
<u>Item 5</u>	(3F10.5)	Optional input for wing-body combination.
YLT(KJ)	$Y_{W,L}^{(KJ)}$	Distance from wing rootchord to the constant u-velocity panel outboard side edge on left wing, $1 \leq KJ \leq MSWLP$, ($MSWLP \leq 20$), YLT(1) = 0.0, YLT(MSWLP) = -B2.
VSWLEL(KJ)	$\Lambda_{LE,L}^{(KJ)}$	Leading-edge sweep of wing between YLT(KJ-1) and YLT(KJ), negative for sweep back, degrees, $1 \leq KJ \leq MSWLP$, ($MSWLP \leq 20$), VSWLEL(1) = 0.0.
VSWTEL(KJ)	$\Lambda_{TE,L}^{(KJ)}$	Trailing-edge sweep of wing between YLT(KJ-1) and YLT(KJ), negative for sweep back, degrees, $1 \leq KJ \leq MSWLP$, ($MSWLP \leq 20$), VSWTEL(1) = 0.0.
<u>Item 6</u>	(3F10.5)	Optional input for cruciform wing-body combination.
ZUT(KJ)	$z_{W,U}^{(KJ)}$	Distance from wing rootchord to the constant u-velocity panel outboard side edge on upper wing, $1 \leq KJ \leq MSWUP$, ($MSWUP \leq 20$), ZUT(1) = 0.0, ZUT(MSWUP) = B2V.
VSWLEU(KJ)	$\Lambda_{LE,U}^{(KJ)}$	Leading-edge sweep of wing between ZUT(KJ-1) and ZU(KJ), positive for sweep back, degrees, $1 \leq KJ \leq MSWUP$, ($MSWUP \leq 20$), VSWLEU(1) = 0.0.
VSWTEU(KJ)	$\Lambda_{TE,U}^{(KJ)}$	Trailing-edge sweep of wing between ZUT(KJ-1) and ZUT(KJ), positive for sweep back, degrees, $1 \leq KJ \leq MSWUP$, ($MSWUP \leq 20$), VSWTEU(1) = 0.0.

APPENDIX J

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
<u>Item 7</u>	(3F10.5)	Optional input for cruciform wing-body combination.
ZDT(KJ)	$z_{W,D}$ (KJ)	Distance from wing rootchord to the constant u-velocity panel outboard side edge on lower wing, $1 \leq KJ \leq MSWDP$, ($MSWDP \leq 20$), $ZDT(1) = 0.0$, $ZDT(MSWDP) = -B2V$.
VSWLED(KJ)	$\Lambda_{LE,D}$ (KJ)	Leading-edge sweep of wing between $ZDT(KJ-1)$ and $ZDT(KJ)$, negative for sweep back, degrees, $1 \leq KJ \leq MSWDP$, ($MSWDP \leq 20$), $VSWLED(1) = 0.0$.
VSWTED(KJ)	$\Lambda_{TE,D}$ (KJ)	Trailing-edge sweep of wing between $ZDT(KJ-1)$ and $ZDT(KJ)$, negative for sweep back, degrees, $1 \leq KJ \leq MSWDP$, ($MSWDP \leq 20$), $VSWTED(1) = 0.0$.
<u>Item 8</u>		Optional thickness input data when $NTDAT \neq 0$. If case involves interdigitated fins, this option is not used.
<u>Item 8(a)</u>	(3I5)	Information in items 8(a), 8(b) are read in by subroutine THKIN for the right horizontal wing.
MSWT		Number of source panels in the spanwise direction, $1 \leq 19 \leq MSWT$.
LVSWT		LVSWT = 0 No breaks in wing leading or trailing edges, or equal spanwise spacings of source panel sides, default is 0. LVSWT = 1 Up to 19 breaks in wing leading or trailing edges or up to 19 unequal spanwise spacings.
NUNIS		NUNIS = 1 Thickness distribution varies over the span. NUNIS = 0 Thickness distribution constant over the span.
<u>Item 8(b)</u>	(3F10.0)	Optional input for LVSWT = 1.
YTH(1,J)		Distance from body centerline to the source panel outboard side edge, $1 \leq J \leq MSWT+1$.

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
SWLET(J)		Leading-edge sweep of wing between YTH(1,J-1) and YTH(1,J), positive for sweep back, degrees, $1 \leq J \leq \text{MSWT}+1$.
SWTET(J)		Trailing-edge sweep of wing between YTH(1,J-1) and YTH(1,J), positive for sweep back, degrees, $1 \leq J \leq \text{MSWT}+1$.
<u>Item 8(c)</u>	(8F10.0)	Optional input specifying streamwise thickness slopes read in by subroutine THETIN.
THET(K)	$\tan \theta_s$	NUNIS = 1 K = 1, NWCT NUNIS = 0 K = 1, (NCWT*MSWT)
<u>Item 8(d)</u>		Optional input for left wing when body is not present and if geometric yaw angle is accounted for (skewed panels). All input same as for right wing above, items 8(a), 8(b), and 8(c).
<u>Item 8(e)</u>		Optional input for upper wing if NTDAT = 2 or 4 and NCRX = 1. Same input as for right wing, items 8(a), 8(b) and 8(c).
<u>Item 8(f)</u>		Optional input for lower wing if NCRX = 1 and body is not present and if geometric pitch angle is accounted for (skewed panels). All input same as for right wing, items 8(a), 8(b) and 8(c).
<u>Item 9</u>		Namelist \$BODY read in by subroutine BDYGEN. Optional input when body with circular cross section is present, NBDCR \neq 0.
NXBODY		Number of line source/sinks and line doublet singularities distributed along body centerline.
LNOSE		Length of nose part of body measured from nose tip, dimensional (real variable).
LBODY		Length of body, dimensional (real variable).

APPENDIX J

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
BCODE		Control index (integer) for specifying forebody shape. BCODE = 0 Parabolic = 1 Sears-Haack = 2 Tangent ogive = 3 Ellipsoidal = 4 Conical
<u>Item 10(a)</u>	(8F10.5)	Optional input read by subroutine VRTVEL when the effect of fixed external vortices are considered, for bodies with circular cross section only (RB = RA), $1 \leq NVRTX \leq 10$.
GAMMA(I)	$\frac{\Gamma}{2\pi V_{\infty} a}$ (I)	Nondimensional vortex strengths, a is body radius RB, $1 \leq I \leq NVRTX$.
YVRTX(I)	$\frac{y(I)}{a}$	Nondimensional y-coordinate, $1 \leq I \leq NVRTX$.
ZVRTX(I)	$\frac{z(I)}{a}$	Nondimensional z-coordinate, $1 \leq I \leq NVRTX$. There will be NVRTX sets of vortex inputs.
<u>Item 10(b)</u>	(3F10.5)	Optional input when the effect of fixed external vortices are considered, for bodies with elliptical cross section only (RB \neq RA), $1 \leq NVRTX \leq 10$.
GAMMA(I)	$\frac{\Gamma}{V_{\infty}}$ (I)	Vortex strength divided by free stream velocity, $1 \leq I \leq NVRTX$.
YVRTX(I)	$y_w(I)$	y-coordinate in wing coordinate system of I'th vortex, $1 \leq I \leq NVRTX$.
ZVRTX(I)	$z_w(I)$	z-coordinate in wing coordinate system of I'th vortex, $1 \leq I \leq NVRTX$. There will be NVRTX sets of vortex inputs.
<u>Item 11</u>	(8I10)	
MLEVR		Number of leading-edge vortex information stations for the right horizontal fin.
MLEVL		Number of leading-edge vortex information stations for the left horizontal fin.

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
MLEVU		Number of leading-edge vortex information stations for the upper vertical fin.
MLEVD		Number of leading-edge vortex information stations for the lower vertical fin.
<u>Item 12</u>	(6F10.5)	Optional input concerning leading-edge vorticity when $MLEVR+MLEVL+MLEVU+MLEVD = NLEEV \neq 0$.
XLE(IFV)	$x_{w,LE}$	Wing x-coordinate of station of fin leading edge.
CGLOC(IFV)	$\bar{y}_{LE}, \bar{z}_{LE}$	Center of gravity of the leading-edge vorticity distribution.
GAMLE(IFV)	$\frac{\Gamma_{LE}}{V_{\infty}}$	Strength of the vorticity distribution at XLE(IFV), $1 \leq IFV \leq NEDGV$.
<u>Item 13</u>	(I10)	
NSEV		Number of fin side-edge vortex information stations. Same for all fins.
<u>Item 14</u>	(6F10.5)	Optional input concerning side-edge vorticity when $4(NSEV) = NSIDGE \neq 0$.
XSE(JSE)	$x_{w,SE}$	Wing x-coordinate of station on fin side edge.
CGSELC(JSE)	$\bar{y}_{SE}, \bar{z}_{SE}$	Center of gravity of the side-edge vorticity distribution.
GAMSE(JSE)	$\frac{\Gamma_{SE}}{V_{\infty}}$	Strength of vorticity distribution at XSE(JSE), $1 \leq JSE \leq NSIDGE$.
<u>Item 15</u>	(20A4)	
ZZZZ		End of information.

Description of Output

This section gives a summarized description of the output generated by program DEMON2 for a typical case involving one set of lifting surfaces on a body. Sample outputs are shown in connection with the discussion of 2 sample cases in section 6. In the following, the important items of output are described. Note that if print control indices NOUT and NPR are not set equal to zero in namelist \$INPUT, very large output will be generated. As such, this additional output serves to aid in debugging.

The first page identifies the run. The second and possibly the third show the namelist \$INPUT. All length dimensions in the output are the same as in the input.

On the next page, the wing geometry and flow conditions are listed. The quantities ALFA and BETA correspond to angle of pitch, α , and side-slip, β , respectively, calculated by the program, using the pitch-bank convention described in section 4, from the angle of incidence ALFAC and angle of roll PHI specified in namelist \$INPUT. Information concerning the geometrical layout of the planar source panels used to model thickness of the lifting surfaces is then shown. On the next page, the specified streamwise slopes are printed. No thickness is accounted for for cases including interdigitated lifting surfaces.

If the body is circular in cross section, the next page shows namelist \$BODY which was read in by subroutine BDYGEN. It is followed by the program calculated cylindrical coordinates of the body definition points and streamwise body slopes. Together with this body geometry output, the origin of each line singularity (line sources/sinks and line doublets) are given under the heading TX. All axial coordinates are in the body coordinate system with origin at the nose, refer to figure 1. The strengths of the singularities are given by T(I) for the line sources or sinks and by TC(I) for the line doublets. On the next pages, the output shows the pressures calculated on the circumference of the body with circular cross section. This information is calculated at axial locations under the heading XB in the body coordinate system. Each circumference or ring is given a BODY RING number which is written on top of the pressure point coordinates, the velocity component involved, pressure coefficients, body slopes, and pressure ratios. The pressures are

calculated by subroutine BDYPR on the basis of the linear and Bernoulli pressure-velocity relationships. The latter is given by equation (10) in this report. If the pressures are calculated on the forebody, body nose shed vorticity characteristics can appear in the output if the included angle of attack is in excess of about 5° . The vorticity is represented by 2 concentrated vortices located symmetrically with respect to the crossflow free-stream component vector (unrolled coordinates). The vortex coordinates are also given in the body coordinate system (rolled coordinates) nondimensionalized by the local body radius. The calculated pressures include effects of the body nose vortices, if present. At the end of the print out of the pressures acting on the body, the number of control points, JCPT, is written. This number must be noted for runs involving the afterbody and tail fins, refer to sections 6.1.3 and 6.1.4.

For bodies with elliptical cross section, the horizontal and vertical semiaxes are printed immediately following the print out of local surface slope of the thickness distribution. Pressures at points on the surface of a body with elliptical cross section are calculated by program WDYBDY described in Appendix K.

The next pages of output contain the velocity components induced by external vortices, if applicable. They are calculated by program VPATH2 for axisymmetric bodies or by program VPATHL for bodies with elliptic cross section. Both programs are described in Appendix L. These programs compute the paths of the vortices and then proceed to calculate the vortex induced velocity components at the control points given under the headings XCP, YCP and ZCP.

The next page in the output lists the calculated control point coordinates (x_W, y_W, z_W) in the wing coordinate system shown in figure 1 for the constant u-velocity panels distributed on the lifting surfaces. Perturbation velocities, in the wing coordinate system, induced at these points by the body and external vortices with their paths fixed to be parallel to the body centerline are also shown. The quantities BU, BV, BW and VVRTX, WVRTX, are due to body singularities and vortices specified in Item 10(a) or 10(b) of the input. The velocity components induced by the body singularities are calculated by subroutine VELCAL if the body is axisymmetric. For bodies with elliptic cross section, they are computed by program WDYBDY, stored on a data set and read in by subroutine BDYRD.

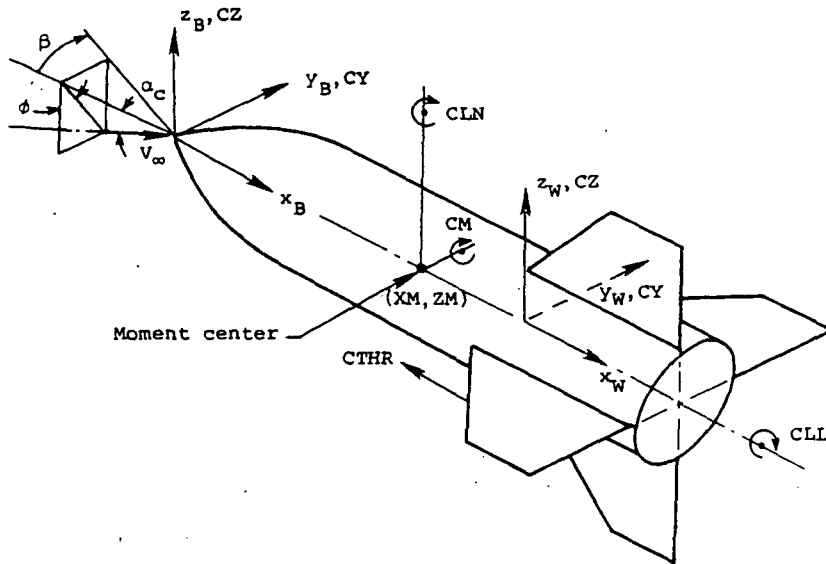
APPENDIX J

Coordinates of the control points associated with the body interference panels are given on the next page. They are expressed in the wing coordinate system. Velocity components $THU(J)$, $THV(J)$ and $THW(J)$ are induced by the planar source panels on the lifting surfaces used to model thickness.

Loading information is printed on the next pages. First, the loadings are based on linear pressure loadings. For each lifting surface the force and moment coefficients, spanwise loading and suction distributions and distributions along the side edge of suction force are given. The heading specifies flow conditions and reference quantities including the moment-center coordinates in the body system. It is followed by a list of the deflection angle, thrust coefficient, $CTHR$, acting in the negative x_B (or x_W) direction, force coefficient CZ in the z_B (or z_W) direction, force coefficient CY in the y_B (or y_W) direction, pitching moment CM (nose up positive), yawing moment CLN (nose to right positive) and rolling-moment CLL (right wing down positive) coefficients.

Force coefficients CZ , CY and moment coefficients CM , CLN and CLL are also printed for the interference shell which covers the body over the length covered by the lifting surfaces. They are only representative of the lift carryover or interference from the lifting surfaces. If actual loads acting on this section of body are to be computed, the pressure distributions mentioned at the end of this section must be integrated.

So far, the loading coefficients have been expressed in the body axis system. For convenience, the positive directions of the forces and moments in the body coordinate system are indicated in the following sketch together with the body and wing reference coordinate systems. The loading information is also specified in the wind axis system, refer to section 4.2 in this report. All force and moment coefficients are then based on a coordinate system with its longitudinal axis aligned with the free stream vector. Under the heading **SPANWISE DISTRIBUTIONS**, the quantities of interest are the span loading $CN^*C/(2*B)$, thrust distribution $CT^*C/(2*B)$, suction distribution $CS^*C/(2*B)$ and the calculated leading-edge vorticity strength $GAMMA,LE/VINF$ with its spanwise location $YBAR$. Quantity XLE is the axial coordinate, in the wing system, of the leading edge. The sums of the in-plane forces in coefficient form are then printed. Precise definitions of the terms $SUMFX$, $SUMFY1$, etc., are



given in Appendix C. Along the side edge, the distribution of suction force per unit length divided by the dynamic head times the tip chord is given together with the strength $\text{GAMMA}_{SE}/V_{\infty}$ of the side-edge vorticity and the spanwise location Y_{BAR} . Quantity Y_{BAR} lies along the y_W coordinate. Finally, for the lifting surface at hand the strength(s) and spanwise location(s) of the concentrated trailing-edge vortex (vortices) are printed under the heading T.E. FIN INFO.

After displaying the loading information and spanwise distributions for all the lifting surfaces, the output of program DEMON2 proceeds to specify pressure distributions on the lifting surfaces calculated on the basis of the Bernoulli pressure expression, equation (10). PRESSA is the pressure coefficient acting on the upper side and PRESSB is the pressure coefficient on the lower side of the horizontal lifting surface. For a planar (monoplane) and cruciform fin or wing configuration, the horizontal surfaces lie in the z_W (or z_B) = 0 plane. For interdigitated fins, the horizontal fins are the right upper and left lower fins, refer also to figure 3 and the sketch in Appendix D. Coordinates $X(J)$, $Y(J)$ and $Z(J)$ are in the wing coordinate system. The same pressure coefficient information is given for the vertical fins. For a cruciform fin configuration, the vertical surfaces lie in the y_W (or y_B) = 0 plane. For interdigitated fins, the vertical fins are the right lower and left upper fins, refer to figure 3 and the sketch in Appendix D. The loading pressures coefficients, DELTP,LIN. and DELTP,BERN., pertain to the differences in

APPENDIX J

pressures acting on the lifting surfaces based on linear and Bernoulli pressure expressions, respectively.

The loading calculation is then repeated using the Bernoulli loading pressures. The next pages of output contain the same loading information described above but all results are now based on the Bernoulli pressure equation.

The calculation of loading information based on linear pressure loadings and Bernoulli pressure loadings serves the following purposes. It should be noted first that the linear loading pressures are directly related to the constant u-velocity panel strengths in accordance with equation (C2) in Appendix C whereas the Bernoulli pressures are computed from the velocity components, included angle of attack and roll angle as indicated by equations (9) and (10). Fin forces, moments and trailing edge vorticity characteristics (related to span load distributions as shown in Appendix B) should be taken from the loading information calculated with Bernoulli pressures. At low angles of attack with zero roll and in the absence of external vorticity, the loadings based on the two pressures will be comparable. However, any loading increment due to leading- and side-edge vorticity calculated with the Polhamus analogy must be taken from the loading information based on linear pressures. This is based on the fact that the characteristics of the leading- and side-edge vorticity are related to the suction distributions which is calculated using the constant u-velocity panel strengths as described in Appendix C.

Finally, the pressures acting at the control points of the body interference shell are printed out. They are a continuation of the pressures, described at the beginning of this section, calculated at points on the body ahead of the wing-body section at hand. The same remarks apply. The pressures include effects of body singularities, external vortices, planar source panels on the lifting surfaces, and all the constant u-velocity panels on the lifting surfaces and body interference shell.

Program Listing

The wing-body program DEMON2 is written in FORTRAN IV (029 punch) computer language for the CDC 6600 machine. The program consists of a main routine, CRFWBD and 32 subroutines. Their listings are shown on pages indicated below.

PROGRAM DEMON2

<u>ROUTINE</u>	<u>ADDITIONAL ENTRIES</u>	<u>IDENTIFICATION</u> Cols. 73-76	<u>PAGE NO.</u>
1		DMN01	179
2		02	196
3	BDYAFT	03	201
4		04	207
5		05	208
6		06	209
7		07	210
8		08	211
9		09	212
10		10	212
11		11	212
12		12	216
13		13	223
14	SPECLD	14	224
15		15	235
16	ROTWF, ROTFW	16	235
17		17	236
18		18	236
19		19	237
20		20	242
21		21	253
22		22	254
23		23	255
24		24	258
25		25	260
26	TRWBIP, ROTBW, ROTWB	26	266
27		27	267
28		28	268
29		29	276
30		30	279
31	VORTEX	31	282
32		32	284
33	Z	33	285

PROGRAM DEMON2

	PROGRAM CRPWB0(INPUT,OUTPUT,TAPE3,TAPE5=INPUT,TAPE6=OUTPUT,	DM01	1
	1 TAPE4,TAPE7)	DM01	2
C		DM01	3
C	VERSIONIDEMON2.	DM01	4
C		DM01	5
C	PLANAR OR CRUCIFORM WING-BODY PROGRAM, SUPERSONIC FLOW	DM01	6
C	SET UP GEOMETRY, COORDINATES, AERODYNAMIC INFLUENCE COEFFICIENT	DM01	7
C	MATRIX, SOLVE FOR CONSTANT U-VELOCITY PANEL STRENGTHS.	DM01	8
C		DM01	9
C	DIMENSION RNS(250),YR(20),YRT(20),THU(100),THV(100),THW(100),	DM01	10
C	1VLT(20),HEAD(20),ZUT(20),ZDT(20)	DM01	11
C		DM01	12
C	LOGICAL ASYM,BODY,DELTA,TRUSYM,NOSYM,DELTAS,TAIL,ASYMT	DM01	13
C		DM01	14
C	COMMON FVN(1)	DM01	15
C	COMMON/ONE/CIRC(250),DELTP(250),FN(250),PNLC(250),SWPPE(250),	DM01	16
C	1SWPPE(250),VNOX(250),XBAR(250),ZBAR(250),XCPT(250),YCPT(250),ZCPT	DM01	17
C	2(250),XLF(250),XLH(250),XHF(250),XRB(250),YLC(250),YRC(250),ZLF(250)	DM01	18
C	30),ZRF(250),ZLB(250),ZRH(250),SNT(125),CST(125),SMT2(125),CST2(125)	DM01	19
C	4),IP(300),XFHIP(100),A,ALFA,ALFR,AN*ING,B2,R2V,BETA,BETAR,CONST,	DM01	20
C	5COSALF,COSBET,CN,DX,EM,FMACH,RCIR,SINALF,SINBET,SLOPE,TLRNC,TIPY,	DM01	21
C	6TOTLR,U,V,W,UCHK,VCHK,WCHK,WHIP,X,Y,Z,IV,IF,II,JV,MSWR,MSWL,MSWI,	DM01	22
C	7MSWD,NHIP,NCRX,NCW,NDRAG,NHP,NPR,NRP,N3P,NOCPT,NOLINP,NOUT,NPANELS,	DM01	23
C	ANPRESS,NWHP,ASYM,BODY,DELTAS,NOSYM	DM01	24
C	COMMON/THREE/ANGLR,ANGLL,ANGLU,ANGLD,DELR,DELL,DELU,DELD,SREF,REFL	DM01	25
C	COMMON/SWEEPS/VSWLER(20),VSWTER(20),VSWLEL(20),VSWTEL(20),	DM01	26
C	1 VSWLEU(20),VSWTEU(20),VSWLED(20),VSWTED(20),LVSWP,LEFT,FAC,NCWB,	DM01	27
C	2ARPHL(250),*IDTH(250)	DM01	28
C	COMMON/KVEL/BDU(150),HDV(150),BDW(150),XFLOP(150),YFLOP(150),	DM01	29
C	1 ZFLDP(150)	DM01	30
C	COMMON/SPSANG/SINALC,CUSALC,SIMPFI,COSPHI	DM01	31
C	COMMON/VRTXV/VVRTX(150),WVRTX(150),NVRTPL,NVRTX,VRTMAX	DM01	32
C	COMMON/WHTW/THTI(125),X*LE	DM01	33
C	COMMON/THKDAT/NTDAT,NCWT,NTPR,MSWT(4),NRPT,NMPT,N3PT,NTHP,ASYMT,	DM01	34
C	1 NVERT,S*LET(20,4),S*LET(20,4),YTH(20,4),THETA(400)	DM01	35
C	COMMON/THVELU/THETA,ITLRNC,THTSO	DM01	36
C	COMMON/ICVEL/UTCHK,VTCHK,*TCHK,IIT,IFT,MJ	DM01	37
C	COMMON/TSPANS/SPANR,SPANL,SPANU,SPAND,SWPLER,SWPLEL,SWPLEU,	DM01	38
C	1 SWPLED,SWPTER,SWPTEL,SWPTEU,SWPTED,PRND	DM01	39
C	COMMON/VPTVL/VVFL(500),VVEL(500),JCPT,NCPNUT,NVLIN	DM01	40
C	COMMON/VORSPC/GAMMA(10),VVRTX(10),ZVRTX(10),RLNC	DM01	41
C	COMMON/FINLE/XLE(80),CGLOC(80),GAMLE(80),FKLE,NBDGV,MLEVR,MLEVL,	DM01	42
C	1 MLEVV,MLEVH	DM01	43
C	COMMON/FINSE/XSF(80),CGSELC(80),GAMSE(80),FKSE,NSIDGE,NSEV	DM01	44
C	COMMON /ELLIPS/ RA,RB,ERATIO	DM01	45
C	COMMON /INTRDT/ PHIDIH,THETIT,YHOD,ZBOD,PHIER,PHIFU	DM01	46
C	COMMON/DAFM/XN,ZM,CZ0A,CY0A,CH0A,CL00A,CLL0A	DM01	47
C		DM01	48
C		DM01	49
C	DATA PI/3,141592653590/	DM01	50
C	DATA QUIT/4#ZZZZ/	DM01	51
C		DM01	52
C	NAMELIST /INPUT/CRP,SWLEP,SNTPE,NCW,MSWR,MSHL,ALFAC,PHI,H2,FMACH,	DM01	53
C	1 LVSWP, FAC, *NFVNR, TOLFAC,MSWD,MSHD,SWLEV,S*TEV,	DM01	54
C	1 CRPV,R2V,NCRX,RR,RA,ERATIO,NBDCR,DELR,DELL,DELU,DELD,SREF,REFL,	DM01	55
C	1 PHIDIH,THETIT,X*LE,	DM01	56
C	1 NOLINP,NOUT,NPR,NDRAG,NVRTX,NPRESS,VRTMAX ,NCWB,NAGAIN,BIL,	DM01	57
C	1 ITAIL,NVRTPL,NBDYPR,NTPW,	DM01	58
C	2NTDAT,NCWT,NCPNUT,NVLIN,XSTART,JCPT,FKLE,FKSE,XM,ZM	DM01	59
C		DM01	60
C		DM01	61
C	1 FORMAT (20A4)	DM01	62
C	2 FORMAT (1H1,20A4)	DM01	63

```

701 FORMAT(1M1,20X,15H WING GEOMETRY//
3 18X,12HTIP CHORD = ,F10.5//
4 17X,13HROOT CHORD = ,F10.5//
9 14X,16HWING SEMISPAN = ,F10.5//)
702 FORMAT (//20X,15HFLOW CONDITIONS//5X,7HMACH = ,F10.5,4X,8HALPHAC=
1 ,F10.5,4X,7HMH1 = ,F10.5,4X,7HALFA = ,F10.5,4X,7HBETA = ,F10.5//)
703 FORMAT(1M1,14X,52M PANEL CORNER COORDINATES FOR WING PART
1NELS)
704 FORMAT (1M1,10X,30HCONTROL POINT COORDINATES FOR ,12,14M CHORDWISE
1 BY ,12,32H SPANWISE PANELS ON WING 1 OR R, ,2X,12,5X,
123HSPANWISE ON WING 2 OR L, /53X,3HAND,12,31H SPANWISE PANELS ON
3WING 3 OR U,1X,12,5X, 23HSPANWISE ON WING 4 OR D, //
4 5X,1HJ,6X,4HX(J),8X,4HY(J),8X,4HZ(J),
5 7X,5HRU(J),9X,5HBV(J),9X,5HRW(J),10X,5HVVTX,10X,5HWVRTX,/)
705 FORMAT(1X,15,2X,F10.5,2X,F10.5,2X,F10.5,2X,F10.5,2X,F12.5,2X,F12.5,
1 2X,E12.5,2X,E12.5,2X,E12.5)
706 FORMAT(3X,13,3X,F9.4,1X,F9.4,1X,F9.4,1H*,F9.4,1X,F9.4,1X,F9.4,
1 1H*,F9.4,1X,F9.4,1X,F9.4,1H*,F9.4,1X,F9.4,1X,F9.4)
707 FORMAT(1M1,30X,20HINFLUENCE MATRIX FVN//)
708 FORMAT(/1X,58(1H=),13HWING 1 PANELS ,59(1H=)//)
709 FORMAT(/1X,58(1H=),13HWING 2 PANELS ,59(1H=)//)
710 FORMAT(/1X,58(1H=),13HWING 3 PANELS ,59(1H=)//)
711 FORMAT(/1X,58(1H=),13HWING 4 PANELS ,59(1H=)//)
712 FORMAT (8I10)
713 FORMAT(3F10.5)
714 FORMAT (6F10.5)
715 FORMAT(// 30X,15HPARAMETERS USED//
1 12X,7HASYM = ,L3,12X,8HTLRNC = ,E12.5/12X,7HLEFT = ,L3/
215X,7HROOTY = ,L3,12X,8HDELTA = ,L3,11X,9HTRUSSYM = ,L3,
312X,8HNSYM = ,L3//)
717 FORMAT(1M1,30X,21HSLOPES OF PANEL EDGES//6X,1HJ,5X,10HLE. SLOPE,
1 5X,10HT.E. SLOPE/)
718 FORMAT (15X,12, 8X,F10.5, 17X, F10.5, 9X, F10.5)
719 FORMAT(5X,13,5X,F10.5,5X,F10.5)
719 FORMAT( 9X,21HLEADING EDGE SWEEP = ,F10.5,2X,7HDEGREES//
2 8X,22HTRAILING EDGE SWEEP = ,F10.5,2X,7HDEGREES/)
720 FORMAT(1M1, 5X,31HCONTROL POINTS WRITTEN ON TAPE4 //
* ,4X,1HJ,4X,4HCPT,8X,4HCPT,8X,4HCPT)
721 FORMAT(9X,8HCPTV = ,F10.5//)
722 FORMAT (//10X,23HRIGHT WING PART SPAN = ,F10.5/
110X, 23H LEFT WING PART SPAN = ,F10.5)
723 FORMAT(//10X,7HCPT = ,F10.5)
724 FORMAT (1M1,10X,75H TWO DIMENSIONAL VORTEX STRENGTHS AND FIXED COORDI-
1NATES IN CROSS FLOW PLANE//
215X,5HVRTX, 6X, 10HGAMMA/VINF, 19X,
3 5HVRTX,14X,5HZVRTX//)
725 FORMAT(1M1,30X,48HCONTROL POINT COORDINATES FOR HIP+S (-ING FRAME)
1 //5X,1HJ,6X,4HX(J),8X,4HY(J),8X,4HZ(J),6X,6HTHU(J),8X,
2 6HTHV(J),8X,6HTHW(J)//)
726 FORMAT(//25X,36HTIP CORNER COORDINATES IN WING FRAME)
727 FORMAT(10X,23HUPPER WING PART SPAN = ,F10.5/
1 10X,23HLOWER WING PART SPAN = ,F10.5//)
728 FORMAT(1M1,30X,22HRIGHT HAND SIDE VECTOR//4X,1HJ,5X,6HRHS(J)//)
729 FORMAT(2X,13,2X,E12.5)
731 FORMAT(1M1,30X,19HPRESSURE ON PANEL J//4X,1HJ,4X,4MP(J)//)
7030 FORMAT (
1 1H*,12X,2HLR,15X,1H*,12X,2HHR,15X,1H*,12X,2HRH/12X,1HX,9X,1HY,
2 9X,1HZ,5X,1H*,3X,1HX,9X,1HY,9X,1HZ,5X,1H*,5X, 1HX,9X,1HY,9X,1HZ,
3 5X,1H*,3X,1HY,9X,1HZ/3HX,1H*,29X,1H*,29X,1H*/130(1H=)//
4 38X,1H*,29X,1H*,29X,1H*)
732 FORMAT (3X,69H SPECIFIED SPANWISE LOCATIONS OF OUTBOARD PANEL EDGES
1 AND SWEEP ANGLES//2X,1HX,4X,6HY ON Z,7X,10HLE. SWEEP,5X,
2 10HT.F. SWEEP/23X,5HANGLE,10X,5HANGLE//)

```

733	FORMAT (1X,I2,2X,F10.5,2(5X,F10.5))	DM01 127
734	FORMAT (1H1,4X,14H*ING 1 SURFACE //)	DM01 128
735	FORMAT (1H1,4X,14H*ING 2 SURFACE //)	DM01 129
736	FORMAT (1H1,4X,14H*ING 3 SURFACE //)	DM01 130
737	FORMAT (1H1,4X,14H*ING 4 SURFACE //)	DM01 131
744	FORMAT (1H1,4X,12H*ING SURFACE//)	DM01 132
745	FORMAT (15,3G12.5)	DM01 133
746	FORMAT (15,5E12.5)	DM01 134
747	FORMAT (1H1,10X,83HPPOINT COORDINATES AND PERTURBATION VELOCITIES	DM01 135
	CALCULATED BY PROGRAM VPATH OR VPATHL,///,	DM01 136
	2 5X,2HIC,5X,3HXCP,9X,3HYCP,9X,3HZCP,4X,8HVVEL(IC),6X,8HVEL(IC)//)	DM01 137
		DM01 138
		DM01 139
		DM01 140
999	CONTINUE	DM01 141
		DM01 142
	DEFAULT VALUES FOR NAMELIST INPUT	DM01 143
		DM01 144
	ASYME, FALSE.	DM01 145
	BILE=0.0	DM01 146
	BODY=, FALSE.	DM01 147
	BZV=0.0	DM01 148
	CRPV=0.0	DM01 149
	DELR=0.0	DM01 150
	DELL=0.0	DM01 151
	DELU=0.0	DM01 152
	DELD=0.0	DM01 153
	FRATIC=1.	DM01 154
	FAC=0.95	DM01 155
	FKLE=0.5	DM01 156
	FKSE=0.5	DM01 157
	ITAIL=0	DM01 158
	JCPT=0	DM01 159
	LVSKP=0	DM01 160
	MSWL=0	DM01 161
	MSWD=0	DM01 162
	MSWU=0	DM01 163
	NAGAIN=0	DM01 164
	NBDCR=0	DM01 165
	NBYVPR=0	DM01 166
	NCPDUT=0	DM01 167
	NCRX=0	DM01 168
	NCHR=0	DM01 169
	NCHT=0	DM01 170
	NCHAG=0	DM01 171
	NFVMPH=0	DM01 172
	NGLIN=0	DM01 173
	NHNT=0	DM01 174
	NPR=0	DM01 175
	NPRESS=0	DM01 176
	NIDATE=0	DM01 177
	NTPR=0	DM01 178
	NVLIN=0	DM01 179
	NVRTPL=0	DM01 180
	NVRTX=0	DM01 181
	PHI=0.0	DM01 182
	RA=0.	DM01 183
	RB=0.0	DM01 184
	RFFL=1.0	DM01 185
	SREF=1.0	DM01 186
	SKLEP=0.0	DM01 187
	SKLEV=0.0	DM01 188
	SKTEP=0.0	DM01 189

	S*TFV=0.0	DM01 190
	TOLFAC=1.0	DM01 191
	VRTMAX=0.35	DM01 192
	X=0.0	DM01 193
	XSTART=0.0	DM01 194
	X*LE=0.0	DM01 195
	Z=0.0	DM01 196
C		DM01 197
C	THE FOLLOWING FIN ORIENTATION ANGLES AND TRIG. FUNCTIONS ARE	DM01 198
C	THE DEFAULT VALUES FOR CRUCIFORM FIN CASE.	DM01 199
C		DM01 200
	PHIFR=0.0	DM01 201
	PHIFL=0.0	DM01 202
	PHIFUR=0.0	DM01 203
	PHIFD=90.0	DM01 204
	THETR=0.0	DM01 205
	THETL=0.0	DM01 206
	THETU=90.0	DM01 207
	THETD=90.0	DM01 208
	PHIDT=0.0	DM01 209
	THETI=0.0	DM01 210
C		DM01 211
C		DM01 212
C		DM01 213
C	*****	DM01 214
C	SET CORE REQUIREMENT BASED ON FVN(I)	DM01 215
	LFL=0	DM01 216
	CALL HEQFL(LFL)	DM01 217
C		DM01 218
C	*****	DM01 219
C		DM01 220
C	WING GEOMETRY SPECIFIED IN PLANFORM,	DM01 221
C	GEOMETRICALLY SYMMETRIC WINGS ONLY	DM01 222
C		DM01 223
C		DM01 224
C	READ HEADER CARD	DM01 225
C		DM01 226
	READ(5,1) HEAD	DM01 227
	IF(HEAD(1).EQ.QUIT) STOP	DM01 228
C		DM01 229
C	READ NAMELIST INPUT	DM01 230
C		DM01 231
	READ (5,INPUT)	DM01 232
C		DM01 233
C		DM01 234
C		DM01 235
C	ANGLE OF ATTACK AND SIDESLIP ARE CALCULATED IN ACCORDANCE WITH	DM01 236
C	PITCH-ROLL TRANSFORMATION, SEE NIELSEN PAGE 5.	DM01 237
C		DM01 238
	DTOP=PI/180.0	DM01 239
	ALFACR=ALFAC*DTOR	DM01 240
	SINALC=STN(ALFACR)	DM01 241
	COSALC=COS(ALFACR)	DM01 242
	PHIR=PHI*DTOR	DM01 243
	SINPHI=SIN(PHIR)	DM01 244
	COSPHI=COS(PHIR)	DM01 245
	SINALF=SINALC*COSPHI	DM01 246
	ALFR=ASTN(SINALF)	DM01 247
	COSALF=COS(ALFR)	DM01 248
	SINBET=SINALC*SINPHI	DM01 249
	BETA=ASTN(SINBET)	DM01 250
	COSBET=COS(BETA)	DM01 251
	BETAY=BETA*DTOR	DM01 252
	ALFA=ALFR*DTOR	

C		DH01 253
C	FIN ANGLE PROPERTIES	DH01 254
C		DH01 255
C	SLPWLE=TAN(S*LEP*DTOR)	DH01 256
C	SLPWE=TAN(S*WEP*DTOR)	DH01 257
C	SLPVLE=TAN(S*LEV*DTOR)	DH01 258
C	SLPVE=TAN(S*TEV*DTOR)	DH01 259
C		DH01 260
C	CHECK FOR INTERDIGITATED TAIL DIBEDRAL ANGLES	DH01 261
C		DH01 262
C	NOTE: IF INTERDIGITATED FINS ARE UNDER CONSIDERATION, THE FOLLOWING	DH01 263
C	CORRELATION HOLDS.	DH01 264
C		DH01 265
C	RIGHT UPPER FIN.....RIGHT OR 1	DH01 266
C	LEFT LOWER FIN.....LEFT OR 2	DH01 267
C	RIGHT LOWER FIN.....UPPER OR 3	DH01 268
C	LEFT UPPER FIN.....LOWER OR DOWN OR 4	DH01 269
C	THIS DESIGNATION ESTABLISHES CORRESPONDENCE BETWEEN CRUCIFORM AND	DH01 270
C	INTERDIGITATED FINS.	DH01 271
C	NOTE: THE DIBEDRAL ANGLE DEFINED AS THE CANT ANGLE WERE.	DH01 272
C		DH01 273
C	IF (THETIT.LE.0.0 .OR. THETIT.GE.90.) GO TO 22	DH01 274
C		DH01 275
C	PHIFR = UPPER RIGHT CANT ANGLE, PHIFL = LOWER LEFT CANT ANGLE	DH01 276
C	PHIFU = LOWER RIGHT CANT ANGLE, PHIFO = UPPER LEFT CANT ANGLE	DH01 277
C		DH01 278
C	PHIFR=PHIDIH	DH01 279
C	PHIFL=PHIDIH	DH01 280
C	PHIFU=PHIDIH	DH01 281
C	PHIFO=PHIDIH	DH01 282
C		DH01 283
C		DH01 284
C	THETR,THETO DEFINE LOCATIONS OF RHS FINS ON BODY CIRCUMFERENCE	DH01 285
C	MEASURED POS. FROM +Y*AXIS COUNTERCLOCKWISE.	DH01 286
C	THETL,THETO DEFINE LOCATIONS OF LHS FINS ON BODY CIRCUMFERENCE	DH01 287
C	MEASURED POS. FROM -Y*AXIS COUNTERCLOCKWISE.	DH01 288
C		DH01 289
C		DH01 290
C	THETR=THETIT	DH01 291
C	THETL=THETIT	DH01 292
C	THETR=THETIT	DH01 293
C	THETO=THETIT	DH01 294
C	22 CONTINUE	DH01 295
C		DH01 296
C	ELLIPSE PROPERTIES	DH01 297
C	RB...HORIZONTAL SEMI-AXIS	DH01 298
C	RA...VERTICAL SEMI-AXIS	DH01 299
C		DH01 300
C	IF (RA.EQ.0. .AND .RH.EQ.0.) GO TO 23.	DH01 301
C	IF (RA.EQ.0.) RA=RB/EPATIO	DH01 302
C	IF (RH.EQ.0.) RB=RA*EPATIO	DH01 303
C	EPATIO=RB/RA	DH01 304
C	23 CONTINUE	DH01 305
C	RCIR=SQRT(RA*RB)	DH01 306
C	RHOD=RB	DH01 307
C		DH01 308
C		DH01 309
C	LOGICAL VARIABLE ASYM GOVERNS LAYOUT OF SKEWED PANELS WHICH	DH01 310
C	ONLY CAN BE DONE WHEN THERE IS NO BODY PRESENT.	DH01 311
C	PRESENTLY, PLANAR DELTA WINGS ONLY.	DH01 312
C		DH01 313
C	LOGICAL VARIABLE TRUSYM MAKES USE OF GEOMETRIC AND LOADING	DH01 314
C	SYMMETRY PROPERTIES	DH01 315
C		DH01 315

```

ASYM=(BETAY,NE,0,0),AND,(NBDCR,EQ,0)                                DM01 316
BODY=NBDCR,NE,0                                                    DM01 317
DELTA=DELR,NE,0,,OR,DELL,NE,0,,OR,DELU,NE,0,,OR,DELD,NE,0,      DM01 318
DELTAS=DELR,NE,DELL,OR,DELU,NE,0,,OR,DELD,NE,0,                  DM01 319
TRUSYM=BETAY,EQ,0,0,AND,,NOT,DELTAS                                DM01 320
NOSYM=,NOT,TRUSYM                                                  DM01 321
TAIL=ITAIL,NE,0                                                    DM01 322
C                                                                      DM01 323
TIPY=BZ                                                              DM01 324
NRP=NC**MSWR                                                        DM01 325
NRP1=NRP+1                                                           DM01 326
NHP=NC**MSWL                                                        DM01 327
NHP1=NHP+1                                                           DM01 328
N3P=NC**MSWL+MSWR+MSWL                                            DM01 329
N3P1=N3P+1                                                           DM01 330
NPNALS=NC**MSWR+MSWL+MSWL+MSWL+MSWL                              DM01 331
IF (TRUSYM) NPNALS=NRP                                             DM01 332
IF (TRUSYM,AND,THETIT,GT,0,) NPNALS=NC**MSWR+MSWL              DM01 333
NPNALP=NPNALS+1                                                    DM01 334
NRIP=NC**NBDCR                                                      DM01 335
IF (TRUSYM,AND,BODY) NRIP=NRIP/2                                   DM01 336
NWRP=NPNALS+NRIP                                                    DM01 337
IF (NWRP,GT,8) NPR=0                                               DM01 338
C                                                                      DM01 339
WRITE (6,2) HEAD                                                    DM01 340
C                                                                      DM01 341
C                                                                      DM01 342
C ANGLS ANGLR,ANGLL,ANGLU,ANGLO GOOD ONLY FOR CRUCIFORM FINS OR  DM01 343
C MONO-PLANE WING.                                                 DM01 344
C                                                                      DM01 345
RDELR=DELR*DTOR                                                    DM01 346
ANGLR=RDELR + ALFR                                                 DM01 347
RDELL=DELL*DTOR                                                    DM01 348
ANGLL=ALFR+RDELL                                                  DM01 349
RDELU=DELU*DTOR                                                    DM01 350
ANGLU=BETAY+RDELU                                                 DM01 351
RDELD=DELD*DTOR                                                    DM01 352
ANGLD=BETAY+RDELD                                                 DM01 353
BETA=SQRT(AHS(FMACH**FMACH-1.))                                     DM01 354
TLRNC=(H2+15,E-5)**2*TOLFAC                                       DM01 355
TOTLR=2.0*TLRNC                                                    DM01 356
CONST=4.0*PI                                                        DM01 357
TBETA=BETA                                                         DM01 358
TBTSC=BETA*BETA                                                    DM01 359
TTLRNC=TLRNC                                                       DM01 360
NVERT=NCRX                                                         DM01 361
ASYM=ASYM                                                           DM01 362
C                                                                      DM01 363
C                                                                      DM01 364
WRITE(6,INPUT)                                                       DM01 365
IF (NAGAIN,GT,1) GO TO 53                                           DM01 366
C                                                                      DM01 367
C                                                                      DM01 368
C*****DM01 369
C UP TO STATEMENT 69 IS FOR WING ALONE CASE                          DM01 370
C*****DM01 371
C NOTE: IF NDRAG=1, USE A MAXIMUM OF 150 PANELS                      DM01 372
C                                                                      DM01 373
IF(ASYM,OR,BODY,OR,NCRX,NE,0) GO TO 69                             DM01 374
MSWRP=MSWR+1                                                        DM01 375
IF(LVSWP,EQ,0) GO TO 25                                             DM01 376
C                                                                      DM01 377
C FOR THIS CASE YH(KJ) MEASURED FROM WING CENTERLINE.             DM01 378

```

```

C                                     D*01 379
READ(5,713) (YR(KJ),VS=LER(KJ),VS=TER(KJ),K.I=1,MS=RP) D*01 380
S*PLER=VS=LER(MS=RP) D*01 381
S*PTER=VS=TER(MS=RP) D*01 382
GO TO 26 D*01 383
C                                     D*01 384
C LAY OUT THE SPANWISE LOCATION OF PANEL NOS. YR(I) IN THE PLANFORM D*01 385
C PLANE D*01 386
C IF THEY WERE NOT READ IN ALREADY D*01 387
C                                     D*01 388
25 YR(1)=0.0 D*01 389
YR(MS=RP)=H2 D*01 390
DY=H2/MS=RP D*01 391
DO 110 I=2,MS=RP D*01 392
AI=I-1 D*01 393
110 YR(I)=YR(1)+DY*AI D*01 394
S*PLER=S*LEP D*01 395
S*PTER=S*TER D*01 396
26 SPAN=H2 D*01 397
CRPT=CRP D*01 398
GO TO 68 D*01 399
C                                     D*01 400
C IF WITH STRIP AND WITHOUT BODY. D*01 401
C YAWED WING GEOMETRY LAY OUT RELATIVE TO LINE FORMED BY D*01 402
C INTERSECTION OF STREAMWISE PLANE THROUGH WING ROOT CHORD LE AND D*01 403
C WING PLANFORM PLANE (A STREAMWISE LINE) D*01 404
C THIS PROGRAM OPTION CAN ONLY BE USED FOR DELTA WING D*01 405
C WITHOUT BODY. D*01 406
C                                     D*01 407
69 CONTINUE D*01 408
MS=RP=MS=RP+1 D*01 409
S*LEP=S*LEP+1 D*01 410
MS=UP=MS=UP+1 D*01 411
MS=DP=MS=DP+1 D*01 412
IF (BODY) GO TO 74 D*01 413
IF (.NOT.ASYM) GO TO 74 D*01 414
IF (CVS=0,NE.0) GO TO 50 D*01 415
S*PLER=S*LEP+RETAY D*01 416
S*PTER=S*TER+RETAY D*01 417
S*PLEL=S*LEP+RETAY D*01 418
S*PTEL=S*TER+RETAY D*01 419
CTP=CRP-H2*(SLP=LE=BLP=TE) D*01 420
CPT=CPR*(COSHET+SINHET*TAN(S*PTEL*DTOR)) D*01 421
SPANL=(H2/COS(S*LEP*DTOR))*COS(S*PLEL*DTOR) D*01 422
SPANR=(H2/COS(S*LEP*DTOR))*COS(S*PLER*DTOR)+CTP*SINHET D*01 423
GO TO 76 D*01 424
C                                     D*01 425
C SET UP GEOMETRICALLY SYMMETRIC LAY-OUT. D*01 426
C                                     D*01 427
C                                     D*01 428
73 S*PLER=S*LEP D*01 429
S*PTER=S*TER D*01 430
S*PLEL=S*LEP D*01 431
S*PTEL=S*TER D*01 432
CRPT=CRP D*01 433
SPANL=H2 D*01 434
SPANR=H2 D*01 435
74 CONTINUE D*01 436
IF (BODY,LE.0) GO TO 77 D*01 437
C                                     D*01 438
C CASE FOR VERTICAL WING PANELS D*01 439
C                                     D*01 440
C IF (BODY) GO TO 75 D*01 441

```


	IF (.NOT.ASYM) GO TO 75	
	S*PLEU=S*LEV+ALFA	DM01 442
	S*PTEU=S*TEV+ALFA	DM01 443
	S*PLED=S*LEV+ALFA	DM01 444
	S*PTED=S*TEV+ALFA	DM01 445
	CTPV=CRPV+H2V*(SLPVLE+SLPVTE)	DM01 446
	CRPTV=CRPV*(COSALF+SINALF*TAN(S*PTEU*DTOR))	DM01 447
	SPANU=(R2V/COS(S*LEV*DTOR))*COS(S*PLEU*DTOR)	DM01 448
	SPAND=(R2V/COS(S*LEV*DTOR))*COS(S*PLED*DTOR)+CTPV*SINALF	DM01 449
	GO TO 77	DM01 450
	75 S*PLEU=S*LEV	DM01 451
	S*PTEU=S*TEV	DM01 452
	S*PLED=S*LEV	DM01 453
	S*PTED=S*TEV	DM01 454
	CRPTV=CRPV	DM01 455
	SPANU=H2V	DM01 456
	SPAND=H2V	DM01 457
	77 CONTINUE	DM01 458
C		DM01 459
C		DM01 460
	SLPWLR= TAN(S*PLER*DTOR)	DM01 461
	SLPWTR= TAN(S*PTER*DTOR)	DM01 462
	SLPWLLE= TAN(S*PLEL*DTOR)	DM01 463
	SLPWTE= TAN(S*PTEL*DTOR)	DM01 464
	IF (NCRX.EQ.0) GO TO 64	DM01 465
	SLPWLU= TAN(S*PLEU*DTOR)	DM01 466
	SLPWLLE= TAN(S*PLED*DTOR)	DM01 467
	SLPWTEU= TAN(S*PTEU*DTOR)	DM01 468
	SLPWTE= TAN(S*PTED*DTOR)	DM01 469
	64 IF (LVSAP.EQ.0) GO TO 65	DM01 470
C		DM01 471
C	READ IN NON UNIFORM DISTANCES TO PANEL OUTBOARD EDGES.	DM01 472
C	IF WITH A BODY, MEASURE FROM FIN ROOT CHORD.	DM01 473
C		DM01 474
	60 READ (5,713) (VRT(KJ),VSWLER(KJ),VSWTER(KJ),KJ=1,MSWRP)	DM01 475
	S*PLER=VSWLER(MSWRP)	DM01 476
	S*PTER=VSWTER(MSWRP)	DM01 477
	S*PLEU=S*PLER	DM01 478
	S*PTEU=S*PTER	DM01 479
	SPANR=VRT(MSWRP)-VRT(1)	DM01 480
	SPANL=SPANR	DM01 481
	SPANU=SPANR	DM01 482
	IF (TRUSYM.AND. THETIT.LE.0.) GO TO 68	DM01 483
	IF (TRUSYM) GO TO 61	DM01 484
	READ (5,713) (VLT(KJ),VSWLEL(KJ),VSWTEL(KJ),KJ=1,MSWLP)	DM01 485
	S*PLEL=VSWLEL(MSWLP)	DM01 486
	S*PTEL=VSWTEL(MSWLP)	DM01 487
	SPANL=(VLT(MSWLP)-VLT(1))	DM01 488
	IF (NCRX.EQ.0) GO TO 68	DM01 489
C		DM01 490
C	IF TRUSYM IS TRUE AND INTERDIGITATED TAIL IS TREATED,	DM01 491
C	DATA IS EXPECTED FOR THE RIGHT UPPER AND LOWER FINS	DM01 492
C		DM01 493
	61 READ(5,713) (ZUT(KJ),VSWLEU(KJ),VSWTEU(KJ),KJ=1,MSWUP)	DM01 494
	S*PLEU=VSWLEU(MSWUP)	DM01 495
	S*PTEU=VSWTEU(MSWUP)	DM01 496
	SPANU=ZUT(MSWUP)-ZUT(1)	DM01 497
	IF (TRUSYM) GO TO 68	DM01 498
	READ(5,713) (ZDT(KJ),VSWLED(KJ),VSWTED(KJ),KJ=1,MSWDP)	DM01 499
	S*PLED=VSWLED(MSWDP)	DM01 500
	S*PTED=VSWTED(MSWDP)	DM01 501
	SPAND=(ZDT(MSWDP)-ZDT(1))	DM01 502
	GO TO 68	DM01 503
	65 CONTINUE	DM01 504

C		DM01 505
C	EQUAL SPANWISE WIDTHS, CONSTANT SWEEPS	DM01 506
C	PANELS IN HORIZONTAL WING SURFACES	DM01 507
C		DM01 508
	YRT(1)=0.0	DM01 509
	YRT(MSWRP)=SPANR+YRT(1)	DM01 510
	OYR=SPANR/MSWR	DM01 511
	DO 51 I=2,MSWR	DM01 512
	AI=I-1	DM01 513
51	YRT(I)=OYR*AI+YRT(1)	DM01 514
	IF (TRUSYM .AND. THETIT.EQ.0.0) GO TO 68	DM01 515
C		DM01 516
	IF (TRUSYM) GO TO 57	DM01 517
	YLT(1)=0.0	DM01 518
	YLT(MSWLP)=SPANL+YLT(1)	DM01 519
	OYL=SPANL/MSWL	DM01 520
	DO 52 I=2,MSWL	DM01 521
	AI=I-1	DM01 522
52	YLT(I)=OYL*AI+YLT(1)	DM01 523
	IF (NCRX.EQ.0) GO TO 68	DM01 524
C		DM01 525
C	PANELS IN VERTICAL PLANE	DM01 526
C		DM01 527
57	ZUT(1)=0.0	DM01 528
	ZUT(MSWUP)=SPANU+ZUT(1)	DM01 529
	DZU=SPANU/MSWU	DM01 530
	DO 54 I=2,MSWU	DM01 531
	AI=I-1	DM01 532
54	ZUT(I)=DZU*AI+ZUT(1)	DM01 533
C		DM01 534
	IF (TRUSYM) GO TO 68	DM01 535
	ZDT(1)=0.0	DM01 536
	ZDT(MSWDP)=SPAND+ZDT(1)	DM01 537
	DZD=SPAND/MSWD	DM01 538
	DO 55 I=2,MSWD	DM01 539
	AI=I-1	DM01 540
55	ZDT(I)=DZD*AI+ZDT(1)	DM01 541
68	CONTINUE	DM01 542
C		DM01 543
	IF (LVSWP.EQ.0) GO TO 79	DM01 544
	IF (ASYM.OR.BODY.OR.NCRX.NE.0) GO TO 28	DM01 545
	*WRITE (6,744)	DM01 546
	WRITE (6,732)	DM01 547
	DO 29 K=1,MSWRP	DM01 548
29	WRITE (6,733) K,YR(K),VSWLER(K),VSWTER(K)	DM01 549
	GO TO 79	DM01 550
2A	WRITE (6,734)	DM01 551
	WRITE (6,732)	DM01 552
	DO 80 K=1,MSWRP	DM01 553
80	WRITE (6,733) K,YRT(K),VSWLER(K),VSWTER(K)	DM01 554
	IF (TRUSYM .AND. THETIT.LE.0.) GO TO 79	DM01 555
	IF (TRUSYM) GO TO 84	DM01 556
	WRITE (6,735)	DM01 557
	DO 81 K=1,MSWLP	DM01 558
81	WRITE (6,735) K,YLT(K),VSWLER(K),VSWTER(K)	DM01 559
	IF (NCRX.EQ.0) GO TO 79	DM01 560
84	WRITE (6,736)	DM01 561
	DO 82 K=1,MSWUP	DM01 562
82	WRITE (6,735) K,ZUT(K),VSWLER(K),VSWTER(K)	DM01 563
	IF (TRUSYM) GO TO 79	DM01 564
	WRITE (6,737)	DM01 565
	DO 83 K=1,MSWDP	DM01 566
83	WRITE(6,735) K,ZDT(K),VSWLER(K),VSWTER(K)	DM01 567

	70 CONTINUE	DM01 543
C		DM01 549
C		DM01 570
C	LAY-OUT ELEMENTAL PANELS ON WING ALONE.	DM01 571
C		DM01 572
	IF (ASYM,OR,BODY,OR,NCRX,NE,0) GO TO 50	DM01 573
	CALL LAYOUT(SLPWLE,SLPWTE,YR,MSWRP,CRP,1,CTP,PHIFR,THETR)	DM01 574
	IF (NOUT,EQ,1) WRITE (6,715) ASYM,TLRNC,LEFT,BODY,DELTA,TRUSYM,	DM01 575
	INOSYM	DM01 576
	GO TO 53	DM01 577
C		DM01 578
C		DM01 579
C	LAY-OUT ELEMENTAL PANELS ON THE FINS.	DM01 580
C		DM01 581
C	NOTE: DISTANCES YRT, YLT, ZUT, ZDT ARE MEASURED FROM THE FIN ROOT	DM01 582
C	CORDS IF BODY IS PRESENT	DM01 583
C		DM01 584
C		DM01 585
	50 CALL LAYOUT(SLPWLP,SLPWTR,YRT,MSWRP,CRPT,1,CTP,PHIFR,THETR)	DM01 586
	IF (NOUT,EQ,1) WRITE (6,715) ASYM,TLRNC,LEFT,BODY,DELTA,TRUSYM,	DM01 587
	INOSYM	DM01 588
	IF (NCRX,NE,0) CTPV=CTP	DM01 589
	IF (TRUSYM,AND,THETIT,LE,0.0) GO TO 62	DM01 590
C		DM01 591
	IF (TRUSYM) GO TO 63	DM01 592
	CALL LAYOUT(SLPWLL,SLPWTL,YLT,MSWLP,CRPT,2,CTPL,PHIFL,THETL)	DM01 593
	IF (NOUT,EQ,1) WRITE (6,715) ASYM,TLRNC,LEFT,BODY,DELTA,TRUSYM,	DM01 594
	INOSYM	DM01 595
	IF (NCRX,EQ,0) GO TO 62	DM01 596
C		DM01 597
	63 CALL LAYOUT(SLPWLU,SLPWTH,ZUT,MSWUP,CRPTV,3,CTPV,PHIFU,THETU)	DM01 598
	IF (NOUT,EQ,1) WRITE (6,715) ASYM,TLRNC,LEFT,BODY,DELTA,TRUSYM,	DM01 599
	INOSYM	DM01 600
C		DM01 601
	IF (TRUSYM) GO TO 62	DM01 602
	CALL LAYOUT(SLPWLD,SLPWTD,ZDT,MSWUP,CRPTV,4,CTPVD,PHIFD,THETD)	DM01 603
	IF (NOUT,EQ,1) WRITE (6,715) ASYM,TLRNC,LEFT,BODY,DELTA,TRUSYM,	DM01 604
	INOSYM	DM01 605
C		DM01 606
C	LAY-OUT BODY INTERFERENCE PANELS	DM01 607
C		DM01 608
	62 IF (NBDCR,EQ,0) GO TO 53	DM01 609
	CALL LAYOUT(SLPWLE,SLPWTE,0.0,NBDCR,HIL,5,0.,0.,0.)	DM01 610
	IF (NOUT,EQ,1) WRITE (6,715) ASYM,TLRNC,LEFT,BODY,DELTA,TRUSYM,	DM01 611
	INOSYM	DM01 612
	53 CONTINUE	DM01 613
C		DM01 614
C		DM01 615
	WRITE(6,701) CTP,CRP,H2	DM01 616
	IF (LVSWP,EQ,0) WRITE(6,719) SWLEP,SWTEP	DM01 617
	WRITE (6,702) FMACH,ALFAC,PHI,ALFA,RETA	DM01 618
	IF (.NOT,ASYM) GO TO 56	DM01 619
	WRITE(6,722) SPANP,SPANL	DM01 620
	IF(NCRX,NE,0)WRITE(6,727) SPANU,SPAND	DM01 621
	56 CONTINUE	DM01 622
	WRITE(6,723) CRPT	DM01 623
	IF(NCRX,NE,0) WRITE(6,721) CRPTV	DM01 624
	IF (NOUT,NE,1) GO TO 7813	DM01 625
	WRITE(6,703)	DM01 626
	WRITE(6,7030)	DM01 627
	WRITE(6,708)	DM01 628
	WRITE(6,706) (J,XLF(J),YLC(J),ZLF(J),XLR(J),YLC(J),ZLR(J),XRF(J),	DM01 629
	1 YRC(J),ZRF(J),XPH(J),YPC(J),ZRH(J),J=1,NRP)	DM01 630

	IF (TRUSYM .AND. THEIT.LE.0.) GO TO 71	DM01 631
C	IF (TRUSYM) GO TO 75	DM01 632
	WRITE(6,709)	DM01 633
	WRITE(6,706) (J,XLF(J),YLC(J),ZLF(J),XLB(J),YLC(J),ZLB(J),XRF(J),	DM01 634
	1 YRC(J),ZRF(J),XRB(J),YRC(J),ZRB(J),J=NRP1,NRP)	DM01 635
	IF(NCRX.EQ.0) GO TO 71	DM01 636
		DM01 637
C	73 WRITE(6,710)	DM01 638
	WRITE(6,706) (J,XLF(J),YLC(J),ZLF(J),XLB(J),YLC(J),ZLB(J),XRF(J),	DM01 639
	1 YRC(J),ZRF(J),XRB(J),YRC(J),ZRB(J),J=NRP1,NRP)	DM01 640
	IF (TRUSYM) GO TO 71	DM01 641
		DM01 642
C	WRITE(6,711)	DM01 643
	WRITE(6,706) (J,XLF(J),YLC(J),ZLF(J),XLB(J),YLC(J),ZLB(J),XRF(J),	DM01 644
	1 YRC(J),ZRF(J),XRB(J),YRC(J),ZRB(J),J=N3P1,NPANLS)	DM01 645
		DM01 646
C	71 IF(NHDCR.EQ.0) GO TO 72	DM01 647
	WRITE(6,726)	DM01 648
	WRITE(6,7030)	DM01 649
	WRITE (6,706) (J,XLF(J),YLC(J),ZLF(J),XLB(J),YLC(J),ZLB(J),XRF(J),	DM01 650
	1YRC(J),ZRF(J),XRB(J),YRC(J),ZRB(J),J=NPANLP,NWBP)	DM01 651
	WRITE (6,717)	DM01 652
	WRITE (6,718) (J,SWPPLE(J),SWPPE(J),J=1,NWRP)	DM01 653
	GO TO 7813	DM01 654
	72 WRITE(6,717)	DM01 655
	WRITE(6,718) (J,SWPPLE(J),SWPPE(J),J=1,NPANLS)	DM01 656
	7813 CONTINUE	DM01 657
		DM01 658
C		DM01 659
C		DM01 660
C	INPUT THICKNESS DATA, PRINT INPUT VALUES, AND LAY	DM01 661
C	OUT SOURCE PANELS ON FINS.	DM01 662
C	SUBROUTINE THKIN READS IN STREAMWISE THICKNESS SLOPES.	DM01 663
C		DM01 664
	IF(NTDAT.EQ.0) GO TO 88	DM01 665
	CALL THKIN	DM01 666
	CALL THKOUT	DM01 667
	CALL THKLYT(CRPT,0)	DM01 668
	IF(ASYM) CALL THKLYT(CRPT,1)	DM01 669
		DM01 670
C	IF(NCRX.EQ.0) GO TO 88	DM01 671
	CALL THKLYT(CRPTV,2)	DM01 672
	IF(ASYM) CALL THKLYT(CRPTV,3)	DM01 673
	88 CONTINUE	DM01 674
		DM01 675
C	INITIALIZE BODY INDUCED VELOCITIES AND VORTEX INDUCED VELOCITIES	DM01 676
C		DM01 677
C	DO 10 KM=1,150	DM01 678
	VVRTX(KM)=0.0	DM01 679
	AVVRTX(KM)=0.0	DM01 680
	HOU(KM)=0.0	DM01 681
	HOU(KM)=0.0	DM01 682
	10 HOU(KM)=0.0	DM01 683
		DM01 684
C	DO 11 IC=1,500	DM01 685
	VVEL(IC)=0.0	DM01 686
	11 VVEL(IC)=0.0	DM01 687
		DM01 688
C		DM01 689
C		DM01 690
C	WHEN NCPOUT NOT ZERO,	DM01 691
C	PUT WING OR FIN CONTROL POINTS AND BODY INTERFERENCE PANEL	DM01 692
C	CONTROL POINTS IN DATA SET ON TAPE 4.	DM01 693

Page Intentionally Left Blank

Page Intentionally Left Blank

```

C                                                    *DM01 821
C SPECIAL PURPOSE CORE MEMORY ECONOMY SECTION FOR HCS 8600 *DM01 822
C SET CORE REQUIREMENT BASED ON LFL PLUS FVN(NWHP,NWHP) *DM01 823
C NOTE: ALREADY SET FVN(1). DM01 824
C                                                    *DM01 825
C MFLTOT=LFL*NWHP*NWHP-1 DM01 826
C CALL REQFL(MFLTOT) DM01 827
C                                                    *DM01 828
C***** DM01 829
C DM01 830
C SET UP INFLUENCE COEFFICIENT MATRIX DM01 831
C IT IS THE LHS OF THE FLOW TANGENCY CONDITION. DM01 832
C NOTE: THE R.C. STATES THAT VELOCITY NORMAL TO THE PANELS MUST DM01 833
C BE ZERO. DM01 834
C THEREFORE ALL VELOCITIES MUST BE TRANSFORMED INTO INDIVIDUAL DM01 835
C FLAP COORDINATE SYSTEM. DM01 836
C DM01 837
C DM01 838
C CALCULATE THE INFLUENCE OF EACH PANEL ON EACH CONTROL POINT DM01 839
C II AND IF ARE THE LIMITS FOR SUMMATION OF THE INFLUENCE FUNCTION DM01 840
C IN SUBROUTINE VELNOR DM01 841
C IF II = IF, THE INFLUENCE OF A SINGLE PANEL AT A POINT RESULTS DM01 842
C AS IN THE COMPUTATION OF THE ARRAY FVN. IF II=1 AND IF=NWHP, DM01 843
C THE INFLUENCES ARE SUMMED OVER ALL PANELS, AS IN THE COMPUTATION DM01 844
C RESULTANT VELOCITIES BELOW.... DM01 845
C DM01 846
C --- I IS THE INDEX OF THE INFLUENCING PANEL DM01 847
C DM01 848
C DM01 849
C JJ=0 DM01 850
C NUCPT=0 DM01 851
C DO 450 I=1,NWHP DM01 852
C II=I DM01 853
C IF=I DM01 854
C DM01 855
C J IS THE INDEX OF THE INFLUENCED PANEL, I.E. ITS CONTROL POINT. DM01 856
C DM01 857
C DO 425 J=1,NWHP DM01 858
C JB=J-NPANELS DM01 859
C CALL VELNOR(XCPT(J),YCPT(J),ZCPT(J)) DM01 860
C JJ=JJ+1 DM01 861
C IF(J.LE.NPANELS) GO TO 417 DM01 862
C DM01 863
C INFLUENCED PANEL IS ON THE BODY INTERFERENCE SHELL. DM01 864
C DM01 865
C CALL ROTAB (VCHK,WCHK,VV,WW,JB) DM01 866
C GO TO 418 DM01 867
C DM01 868
C INFLUENCED PANEL IS ON A FIN. DM01 869
C DM01 870
C 417 IF (J.LE.NWHP) PHIF=PHIFR*DTOR DM01 871
C IF (J.GT.NWHP.AND.J.LE.NPANELS) PHIF=PHIFU*DTOR DM01 872
C CALL ROTAB(VCHK,WCHK,VV,WW,PHIF) DM01 873
C 418 FVN(JJ)=WW DM01 874
C 425 CONTINUE DM01 875
C 450 CONTINUE DM01 876
C DM01 877
C DEBUG DUMP OF THE FVN ARRAY DM01 878
C DM01 879
C IF(NFVNPR.EQ.0) GO TO 618 DM01 880
C WRITE (6,707) DM01 881
C CALL OUT(FVN,NWHP) DM01 882
C 618 CONTINUE DM01 883

```

CALL LINEQS(NWBP,FVN)	DM01 884
IF (NAGAIN,NE,1) GO TO 9000	DM01 885
JMAX=NWRP**2	DM01 886
REWIND 5	DM01 887
HUFFER OUT (3,1) (FVN(1),FVN(JMAX))	DM01 888
NAGAIN=NAGAIN+1	DM01 889
IF (UNIT(3)) 27,27,27	DM01 890
27 CONTINUE	DM01 891
GO TO 9000	DM01 892
C*****	DM01 893
C	*DM01 894
C CASE FOR NAGAIN G.T. 1, SET REQUIRED FIELD LENGTH.	DM01 895
C	DM01 896
8889 JMAX=NWRP**2	DM01 897
MFLTOT=LPL+NWRP*NWRP-1	DM01 898
CALL REGL(MFLTOT)	DM01 899
C	*DM01 900
C*****	DM01 901
C	DM01 902
REWIND 3	DM01 903
BUFFER IN (3,1) (FVN(1),FVN(JMAX))	DM01 904
IF (UNIT(5)) 30,30,30	DM01 905
30 CONTINUE	DM01 906
9000 CONTINUE	DM01 907
C	DM01 908
C SET UP SINGLE COLUMN MATRIX RHS FOR RIGHT HAND SIDE	DM01 909
C IT REPRESENTS THE EXTERNALLY INDUCED VELOCITIES AND ANGLE OF	DM01 910
C PITCH AND SIDESLIP EFFECTS AS WELL AS FIN THICKNESS.	DM01 911
C NOTES: NO THICKNESS EFFECTS ACCOUNTED FOR IF INTERDIGITATED FINS	DM01 912
C ARE CONSIDERED.	DM01 913
C	DM01 914
C	DM01 915
IF (NVLIN,EQ,0,OR,ITAIL,EQ,1) GO TO 607	DM01 916
REWIND 7	DM01 917
WRITE (6,747)	DM01 918
607 CONTINUE	DM01 919
C	DM01 920
C CASE FOR WING OR FIN ALL AT SAME ANGLE AS BODY	DM01 921
C	DM01 922
C READ IN VELOCITIES INDUCED BY MOVING VORTICES (CALCULATED BY	DM01 923
C PROGRAM VPATH) AT ALL CONSTANT U-VELOCITY PANEL CONTROL POINTS.	DM01 924
C	DM01 925
C	DM01 926
IF (DELTA) GO TO 627	DM01 927
DO 620 I=1,NWRP	DM01 928
IC=I	DM01 929
IF (NVLIN,EQ,0,OR,ITAIL,EQ,1) GO TO 605	DM01 930
READ (7,746) IC,XCP,YCP,ZCP,VVEL(IC),WVEL(IC)	DM01 931
WRITE (6,705) IC,XCP,YCP,ZCP,VVEL(IC),WVEL(IC)	DM01 932
605 CONTINUE	DM01 933
WEXT=SINALF+BDW(I)+WVRTX(I)+WVEL(IC)	DM01 934
VEXT=-SINRET+BDV(I)+VVRTX(I)+VVEL(IC)	DM01 935
IF (I,GT,NPANELS) GO TO 601	DM01 936
IF (I,LE,NHP) GO TO 602	DM01 937
IF (I,LE,NPANELS) GO TO 604	DM01 938
601 RHS(I)=0.0	DM01 939
GO TO 620	DM01 940
602 PHIF=PHIFR+UTDR	DM01 941
CALL ROTWF(VEXT,WEXT,VV,WW,PHIF)	DM01 942
RHS(I)=WW	DM01 943
GO TO 620	DM01 944
604 PHIF=PHIFR+DTDR	DM01 945
CALL ROTWF(VEXT,WEXT,VV,WW,PHIF)	DM01 946

	RHS(I)=WWW	
620	CONTINUE	DM01 947
	GO TO 646	DM01 948
C		DM01 949
C	RIGHT HAND SIDE FOR WINGS OR FINS TILTED WITH RESPECT TO BODY	DM01 950
C		DM01 951
627	CONTINUE	DM01 952
	DO 645 K=1,N=NB	DM01 953
	IC=K	DM01 954
	IF (NVLIN.EQ.0.OR.ITAIL.EQ.1) GO TO 606	DM01 955
	READ (7,746) IC,XCP,YCP,ZCP,VVEL(IC),WVEL(IC)	DM01 956
	WRITE (6,705) IC,XCP,YCP,ZCP,VVEL(IC),WVEL(IC)	DM01 957
606	CONTINUE	DM01 958
	VEXT=-SINHET*HDV(K)+VVRTX(K)+VVVEL(IC)	DM01 959
	WEXT=STINALF*HDW(K)+WVRTX(K)+WVEL(IC)	DM01 960
	IF (K.GT.NPANELS) GO TO 603	DM01 961
	IF (K.LE.NRP) GO TO 641	DM01 962
	IF (K.LE.NHP) GO TO 642	DM01 963
	IF (K.LE.N3P) GO TO 643	DM01 964
	IF (K.LE.NPANELS) GO TO 644	DM01 965
603	RHS(K)=0.0	DM01 966
	GO TO 645	DM01 967
641	PHIF=PHIFR*DTOR	DM01 968
	CALL ROTXF(VEXT,WEXT,VV,WW,PHIF)	DM01 969
	RHS(K)=WWW*SIN(RDELX)	DM01 970
	GO TO 645	DM01 971
642	PHIF=PHIFL*DTOR	DM01 972
	CALL ROTXF(VEXT,WEXT,VV,WW,PHIF)	DM01 973
	RHS(K)=WWW*SIN(RDELL)	DM01 974
	GO TO 645	DM01 975
643	PHIF=PHIFU*DTOR	DM01 976
	CALL ROTXF(VEXT,WEXT,VV,WW,PHIF)	DM01 977
	RHS(K)=WWW*SIN(RDELU)	DM01 978
	GO TO 645	DM01 979
644	PHIF=PHIFD*DTOR	DM01 980
	CALL ROTXF(VEXT,WEXT,VV,WW,PHIF)	DM01 981
	RHS(K)=WWW*SIN(RDELD)	DM01 982
645	CONTINUE	DM01 983
646	CONTINUE	DM01 984
C		DM01 985
C	ADD IN PERTURBATION VELOCITY COMPONENTS INDUCED BY FIN	DM01 986
C	SOURCE PANELS AT THE BODY INTERFERENCE PANEL CONTROL POINTS.	DM01 987
C		DM01 988
	IF (NTOAT.EQ.0.OR..NOT.BODY) GO TO 91	DM01 989
	IIT=1	DM01 990
	IFT=NTHP	DM01 991
	DO 90 K=NPANLP,N=NB	DM01 992
	MJ=K	DM01 993
	CALL THXVEL(XCPT(K),YCPT(K),ZCPT(K))	DM01 994
	KB=K-NPANELS	DM01 995
	THU(KB)=UTCHK	DM01 996
	THV(KB)=VTCHK	DM01 997
	THW(KB)=WTCHK	DM01 998
C		DM01 999
C	INFLUENCED PANEL IS A BIP. RESOLVE WING-FRAME	DM011000
C	VELOCITIES INTO BIP FRAME.	DM011001
C		DM011002
	CALL ROTAR(VTCHK,WTCHK,VT,WT,KB)	DM011003
	RHS(K)=RHS(K)+WT	DM011004
90	CONTINUE	DM011005
	GO TO 92	DM011006
91	DO 93 K=NPANLP,N=NB	DM011007
	KB=K-NPANELS	DM011008
	THU(KB)=0.0	DM011009
	THV(KB)=0.0	DM011010

```

93 TH*(KH)=0.0
92 CONTINUE
C
  IF (NOUT.NE.0) WRITE (6,728)
  IF (NOUT.EQ.0) GO TO 648
  WRITE(6,729) (K,RHS(K),K=1,NWBP)
648 CONTINUE
  CALL SOLVE(RHS,FVN,NWRP)
  IF (NOUT.NE.0) WRITE(6,731)
  DO 630 I=1,NWBP
    DEMONP=RHS(I)*CONST
    DELTP(I)=DEMONP
    IF (ABS(DELTP(I)).LT.1.0E-10) DELTP(I)=0.0
    IF (NOUT.EQ.0) GO TO 630
    WRITE(6,729) I,DELTP(I)
630 CONTINUE
C*****
C REDUCE REQUIRED CORE ALLOCATION BACK TO LFL SIZE
C
C CALL REGFL(LFL)
C*****
C
C PRINT CONTROL POINT COORDINATES OF THE CONSTANT U-VELOCITY PANELS
C ON THE WING OR FIN SURFACES AND THE EXTERNALLY INDUCED
C VELOCITIES AT THE CONTROL POINTS.
C
C WRITE(6,704) NCW,MSWR,MSWL,MSWU,MSWD
C WRITE(6,705) (J,XCPT(J),YCPT(J),ZCPT(J),BDU(J),BDV(J),BDW(J),
C IVRTX(J),WVRTX(J),J=1,NPANLS)
C IF (.NOT.BODY) GO TO 655
C WRITE(6,725)
C DO 650 K=NPANLP,NWBP
650 WRITE(6,705) K,XCPT(K),YCPT(K),ZCPT(K),THU(K=NPANLS),
C THV(K=NPANLS),THW(K=NPANLS)
655 CONTINUE
C
C
C
C CALCULATE LOADINGS ON THE WINGS OR FINS WITH LINEAR PRESSURE
C LOADINGS
C
C IF (NPRESS.EQ.0) CALL LOADS
C
C
C NON LINEAR PRESSURE LOADING CALCULATION
C NVRTPL=0 MEANS EXCLUDE VORTEX INDUCED VELOCITIES PARALLEL TO WING
C SURFACES
C
C
C IF (NOLINP.NE.0) CALL SPECPR
C
C CONTINUE CALCULATION OF PRESSURES ON THE BODY MERIDIANS IN THE
C REGION AFT OF LEADING EDGES OF FIN-BODY JUNCTIONS.
C BODYAFT IS ENTRY POINT IN SUBROUTINE BODYPR
C
C IF (BODY.AND.NBODYPR.NE.0) CALL BODYAFT(ITAIL,XSTART)
C
C GO TO 999
C END

```

```

DM011011
DM011012
DM011013
DM011014
DM011015
DM011016
DM011017
DM011018
DM011019
DM011020
DM011021
DM011022
DM011023
DM011024
DM011025
DM011026
DM011027
DM011028
DM011029
DM011030
DM011031
DM011032
DM011033
DM011034
DM011035
DM011036
DM011037
DM011038
DM011039
DM011040
DM011041
DM011042
DM011043
DM011044
DM011045
DM011046
DM011047
DM011048
DM011049
DM011050
DM011051
DM011052
DM011053
DM011054
DM011055
DM011056
DM011057
DM011058
DM011059
DM011060
DM011061
DM011062
DM011063
DM011064
DM011065
DM011066
DM011067
DM011068
DM011069
DM011070
DM011071
DM011072
DM011073

```

```

SUBROUTINE HOYGEN                                DM02  1
C                                                    DM02  2
C   VERSION: DEMON2.                              DM02  3
C                                                    DM02  4
C   THIS SUBROUTINE DETERMINES STRENGTHS OF SUPERSONIC LINEARLY DM02  5
C   VARYING LINE SOURCES/SINKS AND LINE DOUBLETS TO MODEL A BODY OF DM02  6
C   REVOLUTION AT GIVEN INCLUDED ANGLE OF ATTACK AND MACH NUMBER. DM02  7
C                                                    DM02  8
C   DIMENSION A(100)                              DM02  9
C                                                    DM02 10
C   LOGICAL ASYM,DUMBODY,DELTA,NOSYM              DM02 11
C                                                    DM02 12
C   COMMON/ONE/DUM1(6402),ALFR,ARWING,B2,DUM2(9),FMACH,FR,DUM3(3), DM02 13
C   1 TLRNC,TIPY,INTLR,DUM4(18) ,                DM02 14
C   2 NRIP,DUM5(2),NDRAG,DUM6(4),NOCPT,NOLINE,NOUT,NPANELS,NPRESS,NWBP, DM02 15
C   2ASYM,DUMBODY,DELTA,NOSYM                    DM02 16
C   COMMON/TWO/TX(101),UBO(101),UBS(101),VBO(101),VBS(101),VTBO(101), DM02 17
C   1XBODY(101),RBBODY(101),RPHBODY(101),DRDY(100),T(100),TC(100),COEFF DM02 18
C   2(S),BCODE,RETASQ,HSQ,RADIUS,RFIELD,DUM7 ,U,V,VT,LNUSE,MACH,MACHSQ, DM02 19
C   3BETA,XFIELD,X2,LBODY,NXBODY                DM02 20
C   COMMON/THREE/THTI(125),X*LE                  DM02 21
C   COMMON/SPSANG/SINALC,COSALC,SINPHI,COSPHI    DM02 22
C   COMMON/FOUR/XF(100),RF(100)                  DM02 23
C                                                    DM02 24
C   REAL MACH,MACHSQ,LNUSE,LBODY,LBODYR          DM02 25
C                                                    DM02 26
C   INTEGER BCODE                                DM02 27
C                                                    DM02 28
C                                                    DM02 29
C   NAMELIST/BODY/NXBODY,LNUSE,LBODY,BCODE       DM02 30
C                                                    DM02 31
C                                                    DM02 32
C                                                    DM02 33
C                                                    DM02 34
C   6 FORMAT(I4,F9.4,10G11.4)                    DM02 35
C   227 FORMAT(1H0,53HVELOCITIES INDUCED ON BODY BY BODY LINE SINGULARITIES DM02 36
C   19 FOR MACH=,F7.4,5X,6HALFAC=,F7.4//20X,12HBODY SOURCES,25X,13HBODY DM02 37
C   2 DOUBLES,//9X,1HX,5X,1HU,10X,1HV,10X,2HVN,9X,1HU,9X,1HV,10X, DM02 38
C   3 2HVT, 9X,2HVN/)                             DM02 39
C   700 FORMAT(1X,4(1H=),22HBODY DEFINITION POINTS,7(1H=),3X,10(1H=), DM02 40
C   1 14HCONTROL POINTS,9(1H=)/3X,1HI,6X,5HNXBODY,6X,5HRRBODY,5X, DM02 41
C   2 6HRRBODY,12X,2HXF,9X,2HRF,6X,5HDR/DX//) DM02 42
C   701 FORMAT(1X,13,1X,F10.4,1X,F10.4,1X,F10.4,4X,F10.4, 1X,F10.4,1X, DM02 43
C   1 F10.4) DM02 44
C   702 FORMAT(20X,20H***REVISED LAYOUT***) DM02 45
C   703 FORMAT(1H1) DM02 46
C   704 FORMAT (//,9X,54HBODY MERIDIAN-BODY NOSE MACH CONE INTERSECTION AT DM02 47
C   1 X|= ,F10.5/) DM02 48
C   799 FORMAT(1H1,89HPHYSICAL DIMENSIONS OF BODY AND LINE SINGULARITY STR DM02 49
C   1NGTHS REPRESENTING THE BODY AT MACH=,F7.4,5X,7HALFAC= ,F7.4/ DM02 50
C   2 9X,1HX,12X,1HR,11X,5HDR/DX,12X,2HTX,10X,4HT(I),10X,5HTC(I)) DM02 51
C   801 FORMAT(I4,F9.4, 5G15.5) DM02 52
C   802 FORMAT (1H1,48HBODY RADIUS TOO LARGE IN RELATION TO BODY LENGTH//) DM02 53
C   803 FORMAT(///5X,63HMACH CONE-BODY MERIDIAN INTERSECTION NOT FOUND AFT DM02 54
C   1ER 100 TRIALS//) DM02 55
C                                                    DM02 56
C   MACH=FMACH DM02 57
C   RADIUS=FR DM02 58
C                                                    DM02 59
C   READ NAMELIST BODY DM02 60
C                                                    DM02 61
C                                                    DM02 62

```

C	READ(5,BODY)	DM02 63
C		DM02 64
C	WRITE(6,BODY)	DM02 65
	IF(NXBODY.LE.0.OR.NXBODY.GT.101)NXBODY=51	DM02 66
		DM02 67
C		DM02 68
C	INITIALIZE DOUBLET STRENGTHS	DM02 69
C		DM02 70
C	DO 103 I=1,NXBODY	DM02 71
	103 TC(I)=0.0	DM02 72
C		DM02 73
C	CALCULATION OF AERODYNAMIC DATA	DM02 74
C		DM02 75
	MACHSQ=MACH*MACH	DM02 76
	BETASQ=MACHSQ-1.0	DM02 77
	BETA=SQRT(BETASQ)	DM02 78
	ALPHA=ASIN(SINALC)	DM02 79
	ALFAC=ALPHA*57.2957795	DM02 80
	N=NXBODY-1	DM02 81
	XBODY(1)=0.0	DM02 82
	XBODY(NXBODY)=LBODY	DM02 83
C		DM02 84
C		DM02 85
C	HAIL OUT IF MACH CONE FROM NOSE TIP LIES INSIDE THE ENTIRE LENGTH	DM02 86
C	OF THE BODY	DM02 87
C		DM02 88
C	IF (BETA*RADIUS.GE.LBODY) GO TO 200	DM02 89
	GO TO 204	DM02 90
	200 WRITE (6,802)	DM02 91
	STOP	DM02 92
	204 CONTINUE	DM02 93
C		DM02 94
C	SETUP OF POINTS ON BODY AXIS BY DIVIDING BODY LENGTH INTO N EQUAL	DM02 95
C	SEGMENTS	DM02 96
C		DM02 97
	DEL=LBODY/N	DM02 98
	DO 33 I=2,N	DM02 99
	33 XBODY(I)=XBODY(I-1)+DEL	DM02 100
C		DM02 101
C		DM02 102
C		DM02 103
C	CALCULATION OF BODY RADII AND STREAM WISE SLOPES AT THE X-STATIONS	DM02 104
C	OF THE AXIS POINTS.	DM02 105
C	THEY ARE THE COORDINATES AND SLOPE AT THE BODY DEFINITION POINTS	DM02 106
C		DM02 107
	DO 35 I=1,NXBODY	DM02 108
	35 CALL BODYR(XBODY(I),RBODY(I),RPBODY(I))	DM02 109
C		DM02 110
C	NOW DETERMINE SLOPES DR/DX AT THE CONTROL POINTS TAKEN MID-WAY	DM02 111
C	BETWEEN THE BODY DEFINITION POINTS	DM02 112
C		DM02 113
	DO 36 I=1,N	DM02 114
	XF(I)=.5*(XBODY(I+1)+XBODY(I))	DM02 115
	CALL BODYR(XF(I),RF(I),DRDX(I))	DM02 116
	36 CONTINUE	DM02 117
	IF(NOUT.NE.1) GO TO 9	DM02 118
	WRITE(6,703)	DM02 119
	WRITE(6,700)	DM02 120
	*WRITE(6,701) (I,XBODY(I),RBODY(I),RPBODY(I),XF(I),RF(I),	DM02 121
	DRDX(I),I=1,N)	DM02 122
	WRITE(6,701) NXBODY,XBODY(NXBODY),RBODY(NXBODY),RPBODY(NXBODY)	DM02 123
	9 CONTINUE	DM02 124
C		DM02 125

C	NEXT LOOP DETERMINES THE LOCATIONS OF THE ORIGINS OF THE LINEARLY	DM02 126
C	VARYING LINE SOURCES/SINKS AND DOUBLETS.	DM02 127
C	THEIR STARTING POINTS ARE GIVEN BY TX(I)	DM02 128
C		DM02 129
	DO 10 I=1,NXBODY	DM02 130
	10 TX(I)=XBODY(I)-BETA*WBODY(I)	DM02 131
C		DM02 132
C	IF CONTROL POINTS LIE OUTSIDE THE MACH CONE WITH ITS ORIGIN AT THE	DM02 133
C	BODY NOSE, REVISE LAY-OUT OF BODY DEFINITION POINTS ETC.	DM02 134
C		DM02 135
	IF(BETA*RF(1),LT,XF(1))GO TO 199	DM02 136
C		DM02 137
C	DETERMINE X-STATION OF INTERSECTION OF BODY NOSE MACH CONE	DM02 138
C	WITH BODY	DM02 139
C		DM02 140
	DO 37 I=2,N	DM02 141
	IF((BETA*RF(1)-XF(I)),LT,0.0) GO TO 38	DM02 142
	37 CONTINUE	DM02 143
	38 IAFT=I	DM02 144
	IBFR=I-1	DM02 145
	DELTX=(XF(IAFT)-XF(IBFR))+0.1	DM02 146
	ITRY=0	DM02 147
	XTRY=XF(IAFT)	DM02 148
	40 RMCNE=XTRY/BETA	DM02 149
	CALL BODYR(XTRY,RI,SLPE)	DM02 150
	ITRY=ITRY+1	DM02 151
	ERR=RI-RMCNE	DM02 152
	IF(ITRY,GE,100) GO TO 42	DM02 153
	IF(ERR,LT,0.0) GO TO 39	DM02 154
	XTRY=XTRY+DELTX	DM02 155
	GO TO 40	DM02 156
	42 WRITE(6,803)	DM02 157
	STOP	DM02 158
	39 IF(ABS(ERR),LT,(.01*RI)) GO TO 41	DM02 159
	YTRY=XTRY-DELTX	DM02 160
	DELTX=0.1*DELTX	DM02 161
	GO TO 40	DM02 162
	41 XI=XTRY	DM02 163
C		DM02 164
C	REVISE LAYOUT OF BODY DEFINITION POINTS, CONTROL POINTS, AND	DM02 165
C	ORIGINS OF LINE SINGULARITIES	DM02 166
C		DM02 167
	LWBODY=LBODY-XI	DM02 168
	DEL=LWBODY/R	DM02 169
	WBODY(2)=XI+DEL	DM02 170
	DO 43 I=3,N	DM02 171
	43 WBODY(I)=WBODY(I-1)+DEL	DM02 172
C		DM02 173
	DO 44 I=1,NXBODY	DM02 174
	44 CALL BODYR(WBODY(I),WBODY(I),WBODY(I))	DM02 175
C		DM02 176
	XF(1)=0.5*(XI+WBODY(2))	DM02 177
	CALL BODYR(XF(1),RF(1),OROX(1))	DM02 178
	DO 45 I=2,N	DM02 179
	XF(I)=0.5*(WBODY(I)+WBODY(I+1))	DM02 180
	CALL BODYR(XF(I),RF(I),OROX(I))	DM02 181
	45 CONTINUE	DM02 182
	IF(MOUT,NE,1) GO TO 455	DM02 183
	WRITE(6,703)	DM02 184
	WRITE(6,702)	DM02 185
	WRITE(6,704) XI	DM02 186
	WRITE(6,700)	DM02 187

```

WRITE(6,701) (I,XBODY(I),RBODY(I),RPRBODY(I),XF(I),RF(I),      DM02 188
1 DPROX(I),I=1,N)      DM02 189
WRITE(6,701) NXBODY, XBODY(NXBODY), RBODY(NXBODY), RPRBODY(NXBODY) DM02 190
455 CONTINUE      DM02 191
TX(1)=0.0      DM02 192
DO 46 I=2,NXBODY      DM02 193
46 TX(I)=XBODY(I)-BETA*PRBODY(I)      DM02 194
199 CONTINUE      DM02 195
C      DM02 196
C DETERMINATION OF SOURCE STRENGTHS AT CONTROL POINTS MIDWAY BETWEEN DM02 197
C BODY DEFINITION POINTS.      DM02 198
C      DM02 199
C CALCULATION OF THE FIRST SOURCE STRENGTH.      DM02 200
C      DM02 201
XFIELD=XF(1)      DM02 202
RFIELD=RF(1)      DM02 203
SLOPE=DPROX(1)      DM02 204
RSQ=BETASQ+RFIELD*RFIELD      DM02 205
X2=XFIELD-LBODY      DM02 206
CALL SOURCE(1)      DM02 207
A(1)=V*SLOPE*U      DM02 208
T(1)=DPROX(1)/A(1)      DM02 209
C      DM02 210
C CALCULATION OF THE REST OF SOURCE STRENGTHS.      DM02 211
C      DM02 212
DO 210 I=2,N      DM02 213
XFIELD=XF(I)      DM02 214
RFIELD=RF(I)      DM02 215
SLOPE=DPROX(I)      DM02 216
RSQ=BETASQ+RFIELD*RFIELD      DM02 217
X2=XFIELD-LBODY      DM02 218
DO 205 J=1,I      DM02 219
CALL SOURCE(J)      DM02 220
205 A(J)=V*SLOPE*U      DM02 221
SUM=0.      DM02 222
I*1=I-1      DM02 223
DO 201 J=1,I*1      DM02 224
201 SUM=T(I)+A( J)+SUM      DM02 225
210 T(I)=(DPROX(I)-SUM)/A(I)      DM02 226
T(NXBODY)=0.0      DM02 227
C      DM02 228
C DETERMINATION OF DOUBLET STRENGTHS AT CONTROL POINTS MIDWAY      DM02 229
C BETWEEN BODY DEFINITION POINTS      DM02 230
C      DM02 231
C CALCULATION OF THE FIRST DOUBLET STRENGTH.      DM02 232
C      DM02 233
IF (ABS(ALPHA).LT.1.0E-10,OR,RB.LT.(0.1+H2)) GO TO 798      DM02 234
XFIELD=XF(1)      DM02 235
RFIELD=RF(1)      DM02 236
SLOPE=DPROX(1)      DM02 237
RSQ=BETASQ+RFIELD*RFIELD      DM02 238
X2=XFIELD-LBODY      DM02 239
CALL DOUBLET(1)      DM02 240
A(1)=SLOPE*U-V      DM02 241
TC(1)=ALPHA/A(1)      DM02 242
C      DM02 243
C CALCULATION OF THE REST OF THE DOUBLET STRENGTHS.      DM02 244
C      DM02 245
DO 215 I=2,N      DM02 246
XFIELD=XF(I)      DM02 247
RFIELD=RF(I)      DM02 248
SLOPE=DPROX(I)      DM02 249
RSQ=BETASQ+RFIELD*RFIELD      DM02 250

```

X2=XFIELD=LBODY	DM02 251
DO 212 J=1,I	DM02 252
CALL DOUBLET(J)	DM02 253
212 A(J)=SLOPE*U*V	DM02 254
SUM=0.	DM02 255
IM1=I-1	DM02 256
DO 203 J=1,IM1	DM02 257
203 SUM=TC(J)*A(J)+SUM	DM02 258
215 TC(I)=(ALPHA-SUM)/A(I)	DM02 259
TC(NXBODY)=0.0	DM02 260
798 CONTINUE	DM02 261
C	DM02 262
C PRINT OUT OF BODY CHARACTERISTICS	DM02 263
C	DM02 264
WRITE(6,799)MACH,ALFAC	DM02 265
DO 800 I=1,NXBODY	DM02 266
800 WRITE(6,801) I,XBODY(I),RBODY(I),RPHODY(I),TX(I),T(I),TC(I)	DM02 267
C	DM02 268
C COMPUTATION OF VELOCITIES INDUCED ON BODY BY BODY SOURCES AND	DM02 269
C DOUBLETS AT BODY DEFINITION POINTS, THETA DEGR. MEANS LEFWARD SIDE	DM02 270
C	DM02 271
IF(NOUT.EQ.0) RETURN	DM02 272
WRITE(6,227)MACH,ALFAC	DM02 273
C	DM02 274
C COSTH,SINTH ARE COSINE AND SINE,RESPECTIVELY, OF THE STREAMWISE	DM02 275
C BODY SLOPE ANGLE.	DM02 276
C	DM02 277
DO 225 I=1,NXBODY	DM02 278
COSTH=SQRT(1./(RPHODY(I)**2+1.))	DM02 279
SINTH=SQRT(1.-COSTH*COSTH)	DM02 280
XFIELD=XBODY(I)	DM02 281
RFIELD=RBODY(I)	DM02 282
IF(RFIELD.GT.0.)GO TO 214	DM02 283
C	DM02 284
C IF THE FIELD POINT IS ON THE AXIS, THEN WE SHIFT OUT TO AVOID THE	DM02 285
C SINGULARITY IN THE VELOCITY FUNCTION ON THE AXIS.	DM02 286
C	DM02 287
IF(I.EQ.NXBODY)GO TO 221	DM02 288
RFIELD=RBODY(I+1)/10.	DM02 289
XFIELD=XFIELD+(XBODY(I+1)-XBODY(I))/10.	DM02 290
GO TO 214	DM02 291
221 RFIELD=RBODY(I-1)/10.	DM02 292
XFIELD=XFIELD-(XBODY(I)-XBODY(I-1))/10.	DM02 293
214 RSQ=RETASQ+RFIELD*RFIELD	DM02 294
X2=XFIELD-LBODY	DM02 295
C	DM02 296
C VELOCITIES UD,VD ARE CALCULATED ON THE BODY OPPOSITE THE CROSS	DM02 297
C FLOW STREAM VECTOR (LEFWARD SIDE)	DM02 298
C VELOCITY VTD IS CALCULATED AT 90 DEGREES FROM THE CROSS FLOW	DM02 299
C STREAM DIRECTION	DM02 300
C	DM02 301
US=0.	DM02 302
VS=0.	DM02 303
UD=0.	DM02 304
VD=0.	DM02 305
VTD=0.	DM02 306
DO 218 J=1,I	DM02 307
CALL SOURCE(J)	DM02 308
US=US+T(J)*U	DM02 309
VS=VS+T(J)*V	DM02 310
CALL DOUBLET(J)	DM02 311
UD=UD+U*TC(J)	DM02 312
VD=VD+V*TC(J)	DM02 313

```

C
C VNS,VND ARE INDICATORS OF LEAKAGE THROUGH THE BODY SURFACE
C AT THE BODY DEFINITION POINTS.
C NOTE: THE BOUNDARY CONDITION IS SATISFIED AT THE CONTROL POINTS IN
C BETWEEN THE BODY DEFINITION POINTS.
C
218 VTD=VTD+VT*TC(J)
IF(RPHODY(I).LT.0.)GO TO 220
VNS=VS*COSTH=(1.+US)*SINTH
VND=(VD+ALPHA)*COSTH=UD*SINTH
GO TO 222
220 VNS=VS*COSTH+(1.+US)*SINTH
VND=(VD+ALPHA)*COSTH+US*SINTH
222 UBS(I)=US
VBS(I)=VS
UBD(I)=UD
VBD(I)=VD
VTHD(I)=VTD
225 WRITE(6,6) I,XBODY(I),US,VS,VNS,UD,VD,VTD,VND
RETURN
END

```

```

DM02 314
DM02 315
DM02 316
DM02 317
DM02 318
DM02 319
DM02 320
DM02 321
DM02 322
DM02 323
DM02 324
DM02 325
DM02 326
DM02 327
DM02 328
DM02 329
DM02 330
DM02 331
DM02 332
DM02 333
DM02 334

```

```

SUBROUTINE BODYPR(ITAIL,XSTART)
VERSION:DEMON2.
THIS SUBROUTINE COMPUTES LINEAR AND BERNOULLI PRESSURES AT POINTS
ON THE BODY SURFACE.
THE POINTS LIE ON BODY MERIDIANS. THEIR X-COORDINATES ARE A SUBSET
OF THE X-COORDINATES OF THE BODY CONTROL POINTS (XF(I),XF(I))
DETERMINED IN SUBROUTINE BODYGEN.
THE DENSITY OF THE POINTS IS TAKEN AS HALF THE DENSITY OF
THE BODY SINGULARITIES.
WHERE THE BODY
IS COVERED WITH INTERFERENCE PANELS, THE POINTS COINCIDE WITH
THE PANEL CONTROL POINTS. THE BODY MERIDIANS ON WHICH THE
POINTS LIE PASS THROUGH THE CONTROL POINTS OF THE BODY
INTERFERENCE PANELS. THE NUMBER OF BODY MERIDIANS IS EQUAL TO
NBDCR. THAT IS, THE NUMBER OF BODY INTERFERENCE PANELS ON THE
BODY CIRCUMFERENCE.
DIMENSION THETA(100)
LOGICAL BODY,NOSYM
COMMON/ONE/CIRC(250),DELTP(250),FN(250),PNLC(250),SWPPLF(250),
18WPPTE(250),VNDR(250),XBAR(250),ZBAR(250),XCPT(250),YCPT(250),ZCPT(250),
2(250),XLF(250),XLH(250),XHF(250),XRR(250),YLC(250),YRC(250),ZLF(250),
30),ZHF(250),ZLH(250),ZRH(250),SNT(125),CST(125),SNT2(125),CST2(125),
4),TP(300),XFBIP(100),A,ALFA,ALFR,AKWING,H2,H2V,HETA,HETAR,CGNST,
5COSALF,COSHET,CN,UX,EM,FMACH,RCIR,SINALF,SINHET,SLOPE,TLRNC,TIPY,
6TOTLR,U,V,W,UCHK,VCHK,WCHK,XHIP,X,Y,Z,I,IF,IT,J,MSWR,MSWL,MSWU,
7MSWD,NRIP,NCRX,NCW,NDRAG,NHP,NPR,NRP,N3P,NOCPT,HOLINP,NOIT,NPANELS,
8NDRESS,NARP,ASYM,BODY,DELTAS,NOSYM
COMMON/SWEEPS/VSWLER(20),VSWTER(20),VSWLEL(20),VSWTEL(20),
1 VSWLEH(20),VSWTEU(20),VSWLED(20),VSWTEF(20),LVSWP,LEFT,FAC,NCWB,

```

```

DM03 1
DM03 2
DM03 3
DM03 4
DM03 5
DM03 6
DM03 7
DM03 8
DM03 9
DM03 10
DM03 11
DM03 12
DM03 13
DM03 14
DM03 15
DM03 16
DM03 17
DM03 18
DM03 19
DM03 20
DM03 21
DM03 22
DM03 23
DM03 24
DM03 25
DM03 26
DM03 27
DM03 28
DM03 29
DM03 30
DM03 31
DM03 32
DM03 33
DM03 34
DM03 35
DM03 36
DM03 37
DM03 38

```



```

2ARPAL(250),*IDTH(250)                                DM03 39
COMMON/RVEL/RDUI(150),ROV(150),ROR(150),XFLOP(150),YFLOP(150), DM03 40
1 ZFLOP(150)                                           DM03 41
COMMON/SPSANG/SINALC,COSALC,SINPHI,COSPHI            DM03 42
COMMON/*HTR/HTI(125),X*LE                             DM03 43
COMMON/TW/TX(101),UBD(101),UHS(101),VAD(101),VHS(101),VTMD(101), DM03 44
1XBODY(101),RBODY(101),RBBODY(101),URDY(100),T(100),TC(100),COEFF DM03 45
2(S),ACODE,HETASO,BSO,RADIUS,WFIELD,RNOSE,DUMVEL(S),LNOSE,MACH, DM03 46
3MACHSQ,DMBETA,XFIELD,Y2,LBODY,NXBODY                DM03 47
COMMON/*WTR1/XF(100),WF(100)                          DM03 48
COMMON/VRTXV/VVRTX(150),*VRTX(150),VVRTPL,NVRTX,VRTMAX DM03 49
COMMON/TNKDAT/NTDAT,NCWT,NIPR,MSAT(4),NRPT,NHPT,N3PT,NTHP,ASYMT, DM03 50
1 NVERT,S*LET(20,4),S*LET(20,4),YTH(20,4),THETA(400) DM03 51
COMMON/ICVEL/UTCHK,VTCHK,WCHK,IIT,IFT,MJ              DM03 52
COMMON/VPTHVL/VVEL(500),*VEL(500),JCPT,NCPOUT,NVLIH DM03 53
COMMON/VORSPC/GAMMA(10),YVRTX(10),ZVRTX(10),RLNC DM03 54
COMMON/ELLIPS/RA,RB,EPATIO                             DM03 55
C                                                       DM03 56
C                                                       DM03 57
REAL LBODY                                             DM03 58
C                                                       DM03 59
C                                                       DM03 60
DATA RADTOD/57.2457795/                               DM03 61
C                                                       DM03 62
C                                                       DM03 63
C                                                       DM03 64
700 FORMAT(1H1,25X,49HPRESSURE COEFFICIENTS AT POINTS ON BODY MERIDIAN DM03 65
13//)
701 FORMAT (//45X,10HBODY RING#,1X,I3/)                DM03 67
702 FORMAT(1X,I3,12F10.5)                              DM03 68
703 FORMAT (2X,1HJ,4X,6HMETA,,5X,2HX9,6X,2HVA,8X,2HZB,8X,4HTUT,6X, DM03 69
1 4HVTIT,6X,4HTUT,4X,7HCP,LIN,,3X,8HCP,BERN,,3X,5HDP/0X,5X, DM03 70
2 7HP/PINF,,3X,7HP/PINF,/8X,4HDEG,,97X,5HBERN,,5X,4HLIN,/) DM03 71
704 FORMAT (1H1,106(1H*)/1X,37HAF OF LEADING EDGE OF FIN ROOTCORDS) DM03 72
705 FORMAT (1X,I5,3(2X,F10.5),2(2X,E12.5))            DM03 73
706 FORMAT (/40X,46HRIGHT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINFL)= , DM03 74
1 F10.5/
2 40X,46HRIGHT VORTEX Y(ROLLED COORDS.)/RLOC = , DM03 76
3 F10.5/
4 40X,46HRIGHT VORTEX Z(ROLLED COORDS.)/RLOC = , DM03 78
5 F10.5/
6 40X,46HLEFT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINFL) = , DM03 80
7 F10.5/
8 40X,46HLEFT VORTEX Y(ROLLED COORDS.)/RLOC = , DM03 82
9 F10.5/
1 40X,46HLEFT VORTEX Z(ROLLED COORDS.)/RLOC = , DM03 84
2 F10.5/)
745 FORMAT (I5,5E12.5)                                  DM03 86
746 FORMAT (I5,5E12.5)                                  DM03 87
747 FORMAT (///10X,38HTOTAL NUMBER OF PRESSURE POINTS,JCPT#,14) DM03 88
748 FORMAT (1H1,10X,73HPPOINT COORDINATES AND PERTURBATION VELOCITIES COM03 89
1ALCULATED BY PROGRAM VPATH//,
2 5X,2HIC,5X,3HXCP,9X,3HYCP,9X,3HZCP,8X,8HVVEL(IC),6X,8HWVEL(IC)) DM03 91
C                                                       DM03 92
C                                                       DM03 93
C                                                       DM03 94
IF (.NOT.RBODY) RETURN                                  DM03 95
FACTR1=1.428571429/(FMACH*FMACH)                       DM03 96
FACTR2=0.2*FMACH*FMACH                                  DM03 97
DEGTOR=1.0/RADTOD                                       DM03 98
ALFAC=ASIN(SINALC)*RADTOD                               DM03 99
THETA=ATAN(RBODY(1))*RADTOD                             DM03 100
FINF=X*LE/(2.0*RB)                                      DM03 101
XA=X*LF/RB                                              DM03 102

```

	NUMPTS1	DM03 103
C		DM03 104
C		DM03 105
C	NOTE: UP TO ENTRY HOYAPT, FOLLOWING APPLIES TO CIRCULAR CROSS SECTION	DM03 106
C	BODIES ONLY.	DM03 107
C	SET UP ARRAY OF COORDINATES IN WING COORDINATE SYSTEM FOR	DM03 108
C	THE PRESSURE POINTS AHEAD OF THE WING OR FIN-BODY JUNCTION.	DM03 109
C	CALCULATE VELOCITY COMPONENTS IN BODY COORDINATE SYSTEM.	DM03 110
C	THEN CALCULATE PRESSURE COEFFICIENTS.	DM03 111
C		DM03 112
C	READ IN PERTURBATION VELOCITIES CALCULATED BY PROGRAM VPATH2	DM03 113
C	IF NVLIN IS NOT ZERO.	DM03 114
C	ONLY APPLICABLE WHEN TAIL IS UNDER CONSIDERATION.	DM03 115
C		DM03 116
C	IF (NVLIN.EQ.0.OR ,ITAIL.EQ.0) GO TO 8	DM03 117
C	REWIND 7	DM03 118
C	WRITE (6,748)	DM03 119
C	DO 9 I=1,JCPT	DM03 120
C	READ (7,746) IC,XCP,YCP,ZCP,VVEL(IC),WVEL(IC)	DM03 121
C	9 WRITE (6,705) IC,XCP,YCP,ZCP,VVEL(IC),WVEL(IC)	DM03 122
C	8 CONTINUE	DM03 123
C		DM03 124
C	WRITE(6,700)	DM03 125
C	WRITE (6,703)	DM03 126
C	NRING=NRIP/NCWB	DM03 127
C	NRINGD=2*NRING	DM03 128
C	IF (.NOT.NOSYM) NRINGD=NRINGD+1	DM03 129
C	NHALF=NXBODY/2	DM03 130
C	DTHEA=THI(1)/2,0	DM03 131
C	ANBODY=NXBODY	DM03 132
C	DELX=LBODY/(ANBODY-1,0)	DM03 133
C	IF (ITAIL.EQ.1) GO TO 5	DM03 134
C	JCPT=0	DM03 135
C	ISTART=1	DM03 136
C	IL=0	DM03 137
C	GO TO 6	DM03 138
C	5 JCPT=NWRP	DM03 139
C	ISTART=(XSTANT/(DELX*2,0))+2	DM03 140
C	6 CONTINUE	DM03 141
C		DM03 142
C		DM03 143
C		DM03 144
C	WRITE DATA-SET CONTAINING CONTROL POINTS.	DM03 145
C		DM03 146
C		DM03 147
C	IF (ITAIL.EQ.0.AND,NCPOUT.EQ.0) GO TO 7	DM03 148
C	DO 21 IXSTAT=ISTART,NHALF	DM03 149
C	ICPT=(IXSTAT-1)*2+1	DM03 150
C	XPT=XF(ICPT)-XWLE	DM03 151
C	IF (XPT.GE.0.01) GO TO 22	DM03 152
C	DO 23 J=1,NRINGD	DM03 153
C	23 JCPT=JCPT+1	DM03 154
C	21 CONTINUE	DM03 155
C	22 CONTINUE	DM03 156
C	WRITE(6,747) JCPT	DM03 157
C	REWIND 4	DM03 158
C	WRITE(4,745) JCPT	DM03 159
C	WRITE(4,745) (J,XCPT(J),YCPT(J),ZCPT(J),J=1,NWRP)	DM03 160
C	JCPT=NWRP	DM03 161
C	7 CONTINUE	DM03 162
C		DM03 163
C		DM03 164
C		DM03 165
C		DM03 166
C	DO 10 IXSTAT=ISTART,NHALF	
C	ICPT=(IXSTAT-1)*2+1	
C	XPT=XF(ICPT)-XWLE	

	IF(XPT,GE,0.0) GO TO 13	DM03 167
	WRITE(6,701) IXSTAT	DM03 168
	DO 11 JPOLAR=1,NRING	DM03 169
	JOBLE=JPOLAR*2	DM03 170
	JOM1=JOBLE-1	DM03 171
	THETO(JOM1)=THTI(JPOLAR)-0THETA	DM03 172
	THETO(JOBLE)=THTI(JPOLAR)	DM03 173
	THETEY=THETO(JOBLE)*DEGTOR	DM03 174
	THETOD=THETO(JOM1)*DEGTOR	DM03 175
	YPTEV=RF(ICPT)*COS(THETEY)	DM03 176
	YPTOD=RF(ICPT)*COS(THETOD)	DM03 177
	ZPTEV=RF(ICPT)*SIN(THETEY)	DM03 178
	ZPTOD=RF(ICPT)*SIN(THETOD)	DM03 179
C		DM03 180
C	NOTE1 XFLOP,YFLOP,ZFLOP ARE IN THE WING COORDINATE SYSTEM.	DM03 181
C		DM03 182
	XFLOP(JOM1)=XPT	DM03 183
	XFLOP(JOBLE)=XPT	DM03 184
	YFLOP(JOM1)=YPTOD	DM03 185
	YFLOP(JOBLE)=YPTEV	DM03 186
	ZFLOP(JOM1)=ZPTOD	DM03 187
	11 ZFLOP(JOBLE)=ZPTEV	DM03 188
C		DM03 189
C	IF TRUSYM IS TRUE, ADD FIELDPOINT AT 270 DEGREES	DM03 190
C	TO COORDINATE ARRAYS.	DM03 191
C		DM03 192
	IF(NOSYM) GO TO 25	DM03 193
	DO 20 J=1,NRING	DM03 194
	JJ=NRINGD-J	DM03 195
	XFLOP(JJ+1)=XFLOP(JJ)	DM03 196
	YFLOP(JJ+1)=YFLOP(JJ)	DM03 197
	ZFLOP(JJ+1)=ZFLOP(JJ)	DM03 198
	THETO(JJ+1)=THETO(JJ)	DM03 199
	20 CONTINUE	DM03 200
	XFLOP(NRING+1)=XPT	DM03 201
	YFLOP(NRING+1)=0.0	DM03 202
	ZFLOP(NRING+1)=-RF(ICPT)	DM03 203
	THETO(NRING+1)=270.0	DM03 204
	25 CONTINUE	DM03 205
C		DM03 206
C	COMPUTE CONTRIBUTION TO VELOCITIES FROM BODY SINGULARITIES.	DM03 207
C	BDU, BDV, BDW.	DM03 208
C		DM03 209
	CALL VELCAL (NRINGD,ALFR,RETAR,1)	DM03 210
C		DM03 211
C	NOTE2 AHEAD OF THE FIN-BODY JUNCTION,NO INFLUENCE FROM CONSTANT	DM03 212
C	U-VELOCITY OR SOURCE PANELS.	DM03 213
C		DM03 214
C		DM03 215
C	ADD CONTRIBUTION FROM NOSE VORTICES IF APPLICABLE.	DM03 216
C	THEIR INFLUENCE IS LIMITED TO THE DISTANCE ALONG THE BODY UP TO	DM03 217
C	THE ROOTCHORD LE OF THE CANARDS.	DM03 218
C		DM03 219
	IF (ITAIL,EO,1) GO TO 19	DM03 220
	IF (ABS(ALFAC),LE,4,0) GO TO 19	DM03 221
	XGAMN=XF(ICPT)/RB	DM03 222
	PLOC=RF(ICPT)	DM03 223
	CALL BODYVTX (ALFAC,THETA,FINE,XA,FMACH,GAMN,1,XGAMN,YGAMN,	DM03 224
	1 ZGAMN,XSA,IL)	DM03 225
	IF (GAMN,FG,0,0) GO TO 19	DM03 226
	NVRT=NVRTX	DM03 227
	NVRTX=2	DM03 228
	GAMMA(1)=GAMN	DM03 229
	GAMMA(2)=-GAMN	DM03 230

	YVRTX(1)=-ZGAMN*SINPHI+YGAMN*COSPHI	DM03 231
	YVRTX(2)=-ZGAMN*SINPHI-YGAMN*COSPHI	DM03 232
	ZVRTX(1)=ZGAMN*CUSPHI+YGAMN*SINPHI	DM03 233
	ZVRTX(2)=ZGAMN*CUSPHI-YGAMN*SINPHI	DM03 234
	WRITE (6,706) GAMMA(1),YVRTX(1),ZVRTX(1),	DM03 235
	1 GAMMA(2),YVRTX(2),ZVRTX(2)	DM03 236
	NCPT=1	DM03 237
	CALL VORTEX (1,NRINGD)	DM03 238
	NVRTX=NVRT	DM03 239
	19 CONTINUE	DM03 240
C		DM03 241
C	PRESSL=LINEAR PRESSURE COEFFICIENT	DM03 242
C	PRESSB=BERNOULLI PRESSURE COEFFICIENT	DM03 243
C		DM03 244
	DO 12 J=1,NRINGD	DM03 245
	JCPT=JCPT+1	DM03 246
	IC=JCPT	DM03 247
	XBDY=XFLDP(J)+XWLE	DM03 248
	IF (NOUT.NE.0)	DM03 249
	1WRITE (6,702) J,THEID(J),XBDY,YFLDP(J),ZFLDP(J),BDU(J),BDV(J),	DM03 250
	1 BDW(J)	DM03 251
	UTOT=BDU(J)	DM03 252
	VTOT=BDV(J)+VVRTX(J)	DM03 253
	WTOT=BDW(J)+WVRTX(J)	DM03 254
	IF (NOUT.NE.0)	DM03 255
	1WRITE (6,702) J,THEID(J),XBDY,YFLDP(J),ZFLDP(J),UTOT,VTOT,*TOT	DM03 256
	VTOT=VTOT+VVEL(IC)	DM03 257
	WTOT=WTOT+WVEL(IC)	DM03 258
	IF (NOUT.NE.0)	DM03 259
	1WRITE (6,702) J,THEID(J),XBDY,YFLDP(J),ZFLDP(J),UTOT,VTOT,WTOT	DM03 260
	PRESSL=-2.0*UTOT	DM03 261
	BDUSQ=UTOT*UTOT	DM03 262
	BDVSO=VTOT*VTOT	DM03 263
	BDWSQ=WTOT*WTOT	DM03 264
	URAR=UTOT*COSALC-VTOT*SINBET+WTOT*SINALF	DM03 265
	ARG=1.0-FACTR2*(2.0*URAR+BDUSQ+BDVSO+BDWSQ)	DM03 266
	PRESSB=FACTR1	DM03 267
	IF (ARG.GE.TOTLR) PRESSB=FACTR1*(ARG**3.5-1.0)	DM03 268
	POPINF=PRESSB/FACTR1+1.0	DM03 269
	PLINOP=PRESSL/FACTR1+1.0	DM03 270
	1WRITE (6,702) J,THEID(J),XBDY,YFLDP(J),ZFLDP(J),UTOT,VTOT,WTOT,	DM03 271
	PRESSL,PRESSB,DRDX(ICPT),POPINF ,PLINOP	DM03 272
C		DM03 273
C		DM03 274
C	FINISH WRITING DATA-SET WITH BODY PRESSURE POINTS.	DM03 275
C	APPLICABLE ONLY WHEN ITAIL=1 AND NCPOUT.NE.0.	DM03 276
C		DM03 277
C	NOTE: THEY ARE SPECIFIED IN THE WING COORDINATE SYSTEM.	DM03 278
C		DM03 279
	IF (ITAIL.EQ.1.AND.NCPOUT.NE.0)	DM03 280
	1 WRITE (4,745) JCPT,XFLDP(J),YFLDP(J),ZFLDP(J)	DM03 281
C		DM03 282
	VVRTX(J)=0.0	DM03 283
	WVRTX(J)=0.0	DM03 284
	12 CONTINUE	DM03 285
	10 CONTINUE	DM03 286
	13 CONTINUE	DM03 287
	WRITE (6,747) JCPT	DM03 288
	RETURN	DM03 289
C		DM03 290
C	CALCULATE PRESSURE COEFFICIENTS AFT OF LEADING EDGE OF FIN=BODY	DM03 291
C	JUNCTION AT CONTROL POINTS OF BODY INTERFERENCE PANELS.	DM03 292
C	CONTROL POINT COORDINATES ARE IN WING SYSTEM.	DM03 293

C		DM03 294
	ENTRY BODYAFT	DM03 295
C		DM03 296
	WRITE (6,704)	DM03 297
	WRITE (6,700)	DM03 298
	WRITE (6,703)	DM03 299
	DO 14 IHD=1, NRIP	DM03 300
	JHD=IHD+NPANLS	DM03 301
	XFLOP(IHD)=XCPT(JHD)	DM03 302
	YFLOP(IHD)=YCPT(JHD)	DM03 303
	14 ZFLOP(IHD)=ZCPT(JHD)	DM03 304
C		DM03 305
C	COMPUTE CONTRIBUTION TO VELOCITIES FROM BODY SINGULARITIES, HDU,	DM03 306
C	HDV, HDW.	DM03 307
C	IF BODY HAS ELLIPTICAL CROSS SECTION, HDU, HDV, HDW ARE ALREADY READ	DM03 308
C	IN BY ROUTINE CREWRD FROM A DATA SET. (SEE SUBROUTINE BODYR)	DM03 309
C		DM03 310
	IF (RA, EQ, RB) CALL VELCAL (NBIP, ALFR, RETAR, 1)	DM03 311
C		DM03 312
C		DM03 313
C	ADD EFFECTS OF 2-D TYPE VORTICES IF APPLICABLE	DM03 314
C	THEY HAVE BEEN CALCULATED ALREADY IN CREWRD.	DM03 315
C	(BY MEANS OF SUBROUTINE VRTVEL OR VVELS).	DM03 316
C		DM03 317
	DO 18 K=1, NBIP	DM03 318
	KK=K+NPANLS	DM03 319
	IF (RA, EQ, RB) GO TO 16	DM03 320
	HDU(K)=HDU(KK)	DM03 321
	HDV(K)=HDV(KK)	DM03 322
	HDW(K)=HDW(KK)	DM03 323
	16 HDV(K)=HDV(K)+VVRTX(KK)	DM03 324
	18 HDW(K)=HDW(K)+WVRTX(KK)	DM03 325
C		DM03 326
C	ADD CONTRIBUTION FROM SOURCE PANELS ON WINGS	DM03 327
C		DM03 328
	IF (NTOAT, EQ, 0) GO TO 35	DM03 329
	IIT=1	DM03 330
	IFT=NRIP	DM03 331
	DO 30 K=1, NBIP	DM03 332
	KJ=K	DM03 333
	CALL THKVEL(XFLOP(K), YFLOP(K), ZFLOP(K))	DM03 334
	HDU(K)=HDU(K)+UTCHK	DM03 335
	HDV(K)=HDV(K)+VTCHK	DM03 336
	HDW(K)=HDW(K)+WTCHK	DM03 337
	30 CONTINUE	DM03 338
	35 CONTINUE	DM03 339
C		DM03 340
C	CALCULATE CONTRIBUTION FROM CONSTANT U-VELOCITY PANELS ON BODY	DM03 341
C	INTERFERENCE SHELL AND WINGS OR FINS.	DM03 342
C	ADD IN VELOCITIES INDUCED BY MOVING VORTICES (IF APPLICABLE).	DM03 343
C		DM03 344
C		DM03 345
	IHD=0	DM03 346
	JI=1	DM03 347
	IF=NRIP	DM03 348
	NRING=NRIP/NCWR	DM03 349
	DTHETA=THTI(1)/2.0	DM03 350
	FACTR1=1.428571429/(FMACH*FMACH)	DM03 351
	FACTR2=0.2*FMACH*FMACH	DM03 352
	DO 15 IL=1, NCWB	DM03 353
	WRITE (6,701) IL	DM03 354
	DO 17 JL=1, NRING	DM03 355
	IHD=IHD+1	DM03 356

IC=NPANLS+IRD	DM03 357
THTSD=THTI(JL)=DTMET.	DM03 358
XBDY=XFLDP(IRD)+XWLE	DM03 359
IF (NDUT,NE,0)	DM03 360
1WRITE (6,702) JL,THTSD,XBDY,YFLDP(IRD),ZFLDP(IRD),BDU(IRD),	DM03 361
1BDV(IRD),BD*(IRD)	DM03 362
CALL VFLNDR (XFLDP(IRD),YFLDP(IRD),ZFLDP(IRD))	DM03 363
UTOT=UCHK+BDU(IRD)	DM03 364
VTOT=VCHK+BDV(IRD)+VVEL(IC)	DM03 365
WTOT=WCHK+BD*(IRD)+WVEL(IC)	DM03 366
IF (NDUT,NE,0)	DM03 367
1WRITE (6,702) JL,THTSD,XBDY,YFLDP(IRD),ZFLDP(IRD),UTOT,VTOT,	DM03 368
1WTOT	DM03 369
PRESSL=-2.0*UTOT	DM03 370
HOUSSQ=UTOT*UTOT	DM03 371
BDVSSQ=VTOT*VTOT	DM03 372
BDWSSQ=WTOT*WTOT	DM03 373
UBAR=UTOT*COSALC=VTOT*SINBET+WTOT*SINALF	DM03 374
ARG=1.0-FACTR2*(2.0+UBAR+HOUSSQ+BDVSSQ+BDWSSQ)	DM03 375
PRESSB=-FACTR1	DM03 376
IF (ARG,GE,TOTLR) PRESSB=FACTR1*(ARG**3.5-1.0)	DM03 377
POPINF=PRESSB/FACTR1+1.0	DM03 378
PLINDP=PRESSL/FACTR1+1.0	DM03 379
SLP=0.0	DM03 380
WRITE (6,702) JL,THTSD,XBDY, YFLDP(IRD),ZFLDP(IRD),UTOT	DM03 381
1,VTOT,WTOT,PRESSL,PRESSB,SLP,POPINF,PLINDP	DM03 382
17 CONTINUE	DM03 383
15 CONTINUE	DM03 384
RETURN	DM03 385
END	DM03 386

SUBROUTINE BODYRD(BDU,BDV,BDW,NWBP,NPANLS,NAGAIN)	DM04 1
C	DM04 2
C VERSION: DEMON2	DM04 3
C	DM04 4
C ROUTINE TO READ ELLIPTICAL CROSS SECTION BODY INDUCED VELOCITIES	DM04 5
C AT WING AND BODY INTERFERENCE SHELL.	DM04 6
C THEY ARE READ IN FROM TAPE4.	DM04 7
C	DM04 8
C DIMENSION BDU(NWBP),BDV(NWBP),BDW(NWBP)	DM04 9
C	DM04 10
C COMMON/ELLIPS/RA,RE,RATIO	DM04 11
C	DM04 12
700 FORMAT (////,5X,54HBODY UNDER CONSIDERATION HAS ELLIPTICAL CROSS SECTION./	DM04 13
1SECTION./	DM04 14
2 5X,40HINTERFERENCE SHELL HAS FOLLOWING PROPERTIES://	DM04 15
3 5X,23HHORIZONTAL SEMI-AXIS = ,F10.5//	DM04 16
4 5X,23HVERTICAL SEMI-AXIS = ,F10.5/////	DM04 17
745 FORMAT(15,3E12,5)	DM04 18
750 FORMAT(////,10X,24HWARNING = NWCPT,NE,NWBP,76X,12H** BODYRD ** //,	DM04 19
* 7H NWCPT=,15,7H XMACH=,F10.4,7H ALPHA=,F10.4)	DM04 20
C	DM04 21
C READ PAST CONTROL POINT COORDINATES.	DM04 22
C	DM04 23
C	DM04 24
IF (NAGAIN,LE,0) REWIND 4	DM04 25
IF (NAGAIN,LE,0) READ (4,745) NDUM	DM04 26
IF (NAGAIN,LE,0) READ(4,745) (I,XPTJ,YPTJ,ZPTJ,J=1,NWBP)	DM04 27
WRITE (6,700) RB,RA	DM04 28
C	DM04 29
C	DM04 29

C	READ VELOCITY COMPONENTS	DM04	30
C		DM04	31
	READ(4,745) NWCPT,XMACH,XALPHA	DM04	32
	IF (NWCPT,NE,NWHP) WRITE(6,750) NWCPT,XMACH,XALPHA	DM04	33
	READ(4,745) (I,RDU(J),RDV(J),RDW(J),J=1,NWCPT)	DM04	34
	RETURN	DM04	35
	END	DM04	36
	SUBROUTINE RDVVTX (ALPHA,THETA,FINE,XA,EMACH,GAMN,NG, 1 XGAMN,YGAMN,ZGAMN,XSA,IL)	DM05	1
C		DM05	2
C	VERSION: DEMON2	DM05	3
C		DM05	4
C	FOR BODIES WITH CIRCULAR CROSS SECTION ONLY	DM05	5
C	THIS SUBROUTINE COMPUTES STRENGTH AND POSITION IN THE CROSS FLOW	DM05	6
C	PLANE OF THE BODY WISE VORTICES AS A FUNCTION OF AXIAL DISTANCE.	DM05	7
C	THE METHOD USED IS BASED ON EXPERIMENTAL DATA.	DM05	8
C	REFERENCE IS NASA CR-2473,1975.	DM05	9
C		DM05	10
C	DIMENSION XST(11),ZA1(11),YA1(11),YA2(11),GAMT(11)	DM05	11
C		DM05	12
C	DATA XST/0,0,1,0,2,0,3,0,4,0,5,0,6,0,7,0,8,0,9,0,10,0/	DM05	13
C	DATA GAMT/0,3,0,32,0,34,0,40,0,48,0,62,0,77,0,90,1,0,1,08,1,15/	DM05	14
C	DATA YA1/.45,.463,.477,.492,.505,0,52,.534,0,55,0,565,0,575,0,585/DM05	DM05	15
C	DATA YA2/.63,.64,.653,.665,.678,.69,.7,.715,.725,.735,.74/	DM05	16
C	DATA ZA1/1,14,1,26,1,38,1,5,1,615,1,75,1,84,1,95,2,05,2,14,2,20/	DM05	17
C		DM05	18
C		DM05	19
	701 FORMAT (//IX5H*****,3X62HASYMMETRIC OR UNSTEADY BODY VORTEX SEPARATION POSSIBLE *****/)	DM05	20
	702 FORMAT (40X,41HBODY NOSE SEPARATION AT XB/RB = ,F10,5/	DM05	21
	1 40X, 41HVORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = ,F10,5/	DM05	22
	2 40X,41HVORTEX Y/RLOC (UNROLLED COORDS) = ,F10,5/	DM05	23
	3 40X,41HVORTEX Z/RLOC (UNROLLED COORDS) = ,F10,5/)	DM05	24
C		DM05	25
C		DM05	26
	IF (IL,GE,1) GO TO 16	DM05	27
	BDVVRT=1,0	DM05	28
	NTABLE=11	DM05	29
	DELTA=0,0	DM05	30
	F=1,0	DM05	31
	IF (ALPHA,LT,0,0) F=-1,0	DM05	32
	ALPHA=F*ALPHA	DM05	33
C		DM05	34
C	XSA=XSEPARATION/RB	DM05	35
C		DM05	36
	IF (THETA,LE,30,0) GO TO 10	DM05	37
	XSA=10,/(ALPHA =4,0) + 2,0	DM05	38
	GO TO 15	DM05	39
	10 XSA=32,0 - SQRT(1024,0*(ALPHA =4,0)/(THETA=4,0))	DM05	40
	13 IF (XSA,LT,0,0) XSA=0,0	DM05	41
	IL=IL+1	DM05	42
	IF(XSA,GE,XA) BDVVRT=0,0	DM05	43
	IF(RDVVRT,EQ,0,0) GO TO 31	DM05	44
	IF (XSA,GE,YA) GO TO 31	DM05	45
C		DM05	46
C	COMPUTE UPPER LIMIT FOR SYMMETRIC VORTEX SEPARATION	DM05	47
C		DM05	48
	ALMT=((FINE=12,0)**2)/3,57 + 12,0	DM05	49
	IF (ALPHA ,GT,ALMT) WRITE (6,701)	DM05	50
	SNALP=SIN(ALPHA0/57,2957795)*F	DM05	51
	16 CONTINUE	DM05	52
	IF(BDVVRT,EQ,0,0) GO TO 31	DM05	53

	XPAR=(XGAMN-XSA)*SNALP	DM05	54
	IF (XPAR .GT. 0.0) GO TO 31	DM05	55
C		DM05	56
C	INTERPOLATE IN DATA TABLES FOR THE X-STATION XGAMNBY/RR.	DM05	57
C	GAMT=GAMMA/(2*PI*RLNC*VINP*SIN(ALFA))	DM05	58
C	YA1,YA2,ZA1 ARE DIVIDED BY RLNC.	DM05	59
		DM05	60
	DO 20 J=1,NTABLE	DM05	61
	K=J	DM05	62
	IF (XPAR-XST(J)) 22,23,20	DM05	63
20	CONTINUE	DM05	64
23	GAMN =GAMT(K)*SNALP	DM05	65
	ZGAMN =ZA1(K)	DM05	66
	Y1=YA1(K)	DM05	67
	Y2=YA2(K)	DM05	68
	GO TO 30	DM05	69
22	DELTA=(XPAR-XST(K-1))/(XST(K)-XST(K-1))	DM05	70
	GAMN =GAMT(K-1) + DELTA*(GAMT(K)-GAMT(K-1))	DM05	71
	GAMN=GAMN*SNALP	DM05	72
	ZGAMN =ZA1(K-1) + DELTA*(ZA1(K)-ZA1(K-1))	DM05	73
	Y1=YA1(K-1) + DELTA*(YA1(K)-YA1(K-1))	DM05	74
	Y2=YA2(K-1) + DELTA*(YA2(K)-YA2(K-1))	DM05	75
30	YGAMN =Y1	DM05	76
	IF (EMACH .GT. 1.0) YGAMN =Y2	DM05	77
	GAMN=GAMN*F	DM05	78
	ZGAMN=ZGAMN*F	DM05	79
	GO TO 32	DM05	80
31	GAMN=0.0	DM05	81
32	CONTINUE	DM05	82
	IF (GAMN.NE.0.0) WRITE (6,702) XSA,GAMN,YGAMN,ZGAMN	DM05	83
	RETURN	DM05	84
	END	DM05	85

	SUBROUTINE BODYR(X,R,PPRIME)	DM06	1
C		DM06	2
C	VERSION: DEMON1	DM06	3
C		DM06	4
C	SUBROUTINE FOR THE CALCULATION OF BODY RADII AND SLOPE. THE INTEGER	DM06	5
C	VARIABLE HCODE CONTROLS THE TYPE OF NOSE DEFINITION	DM06	6
C	HCODE=0 PARABOLIC BODY	DM06	7
C	HCODE=1 SEARS-HAACK-ADAMS BODY	DM06	8
C	HCODE=2 TANGENT OGIVE	DM06	9
C	HCODE=3 ELLIPSOIDAL BODY	DM06	10
C	HCODE=4 CONICAL BODY	DM06	11
C		DM06	12
	COMMON/T=0/DUM(1214),HCODE,BETASQ,BSQ,RADIUS,PFIELD,DUM3 ,U,V,VT,	DM06	13
	LNNOSE,DUM2(5),LBODY,NXBODY	DM06	14
		DM06	15
C	REAL LNNOSE,LMBODY	DM06	16
	INTEGER HCODE	DM06	17
		DM06	18
C	IF(X.LE.LNNOSE) GO TO 20	DM06	19
		DM06	20
C	CYLINDRICAL SECTION OF BODY	DM06	21
C		DM06	22
	R=RADIUS	DM06	23
	PPRIME=0.	DM06	24
	RETURN	DM06	25
C		DM06	26
C	NOSE SECTION	DM06	27

C		D406	24
	20	D406	29
	XX=(LN0SE-X)/LN0SE	D406	30
	RR=RADIUS	D406	31
	IF(HCODE.GT.0)GO TO 22	D406	32
C		D406	33
C	PARABOLIC NOSE	D406	34
C		D406	35
	R= RR*(1.-XX*XX)	D406	36
	RPRIME=RR/LN0SE*2.*XX	D406	37
	RETURN	D406	38
	22 GO TO(23,24,25,26),HCODE	D406	39
C		D406	40
C	SEARS-MAACK-ADAMS FOREBODY	D406	41
C		D406	42
	23 IF(XX.GT.9.999E-1) GO TO 223	D406	43
	XY=1.-XX*XX	D406	44
	PHI=XY**0.75	D406	45
	R= RR*PHI	D406	46
	RPRIME=RR/LN0SE*1.5*XX*PHI/XY	D406	47
	RETURN	D406	48
	223 R=0.0	D406	49
	RPRIME=1.59	D406	50
	RETURN	D406	51
C		D406	52
C	TANGENT OGIVE NOSE	D406	53
C		D406	54
	24 RL=RR/LN0SE	D406	55
	RDL=.5*(1.+RL*RL)/RL	D406	56
	XY=SQRT(RDL*RDL-XX*XX)	D406	57
	R=RADIUS=LN0SE*(RDL-XY)	D406	58
	RPRIME=XY/XY	D406	59
	RETURN	D406	60
C		D406	61
C	ELLIPSOID FOREBODY	D406	62
C		D406	63
	25 IF(XX.GT.9.999E-1) GO TO 223	D406	64
	PHI=SQRT(1.-XX*XX)	D406	65
	R= RR*PHI	D406	66
	RPRIME=RR/LN0SE*XX/PHI	D406	67
	RETURN	D406	68
C		D406	69
C	CONE FOREBODY	D406	70
C		D406	71
	26 R= RR*(1.-XX)	D406	72
	RPRIME=RR/LN0SE	D406	73
	RETURN	D406	74
	END	D406	74
	COMPLEX FUNCTION DBLU(Z)	D407	1
C		D407	2
C	VERSION: DEMON1	D407	3
C		D407	4
C	THIS FUNCTION SUBROUTINE CALCULATES THE INTERMEDIATE TRANSFORM	D407	5
C	VARIABLE W FOR THE CONFORMAL TRANSFORMATION OF AN ELLIPTICAL	D407	6
C	BODY WITH WINGS	D407	7
C		D407	8
C	COMMON/COM1/A2,R2,R2	D407	9
	COMMON/COM3/ZR,ZI	D407	10
	COMMON/COM5/CNDZ	D407	11
	COMMON/COM6/A2,A	D407	12

C	COMPLEX Z,ZZ,D*ZZ,W,W2,WW	DM07	13
		DM07	14
C	ZZ=Z*Z	DM07	15
	ZR=REAL(Z)	DM07	16
	ZI=AIMAG(Z)	DM07	17
	IF(ZR.NE.0.0) ZR=ZR/ABS(ZR)	DM07	18
	IF(ZI.NE.0.0) ZI=ZI/ABS(ZI)	DM07	19
	ZZ=ZZ+AZ*H2	DM07	20
	Y=AIMAG(ZZ)	DM07	21
	AY=1.0	DM07	22
	IF(Y.LT.0.0) AY=-1.0	DM07	23
	AYZ=1.0	DM07	24
	IF(ZI.LT.0.0) AYZ=-1.0	DM07	25
	ZZ=CSGPT(ZZ)*AY*AYZ	DM07	26
	IF((ABS(ZI).LE.0.0).AND.(REAL(Z).LT.0.0)) ZZ=CMPLX(-REAL(ZZ),	DM07	27
	AIMAG(ZZ))	DM07	28
	D*ZZ=0.5*(1.0+Z/ZZ)	DM07	29
	W=0.5*(Z+ZZ)	DM07	30
	W2=1.0/W*W	DM07	31
	DBLU=WW	DM07	32
	RETURN	DM07	33
	END	DM07	34
		DM07	35

	SUBROUTINE DOUHLT(J)	DM08	1
C		DM08	2
C	VERSION 1 DEMONI	DM08	3
C		DM08	4
C	SUBROUTINE TO CALCULATE THE VELOCITIES DUE TO A LINEAR LINE DOUBLET OF	DM08	5
C	UNIT STRENGTH WITH ORIGIN AT TX(J).	DM08	6
C		DM08	7
	INTEGER MCODE	DM08	8
	COMMON/T*0/TX(101),DUM1(505),ZZ(403),T(100),TC(100),COEFF(5),	DM08	9
	IRCODE,BETASQ,BSSQ,RADIUS,RFIELD,RNUSE,U,V,VT,VA,VC,XD,BETA,XFIELD,	DM08	10
	ZX2,XH,NXBODY	DM08	11
C		DM08	12
	100 FORMAT(140,59HFIELD POINT IS WITHIN TAIL MACH CONE. U AND V SET TO	DM08	13
	10 ZERO.)	DM08	14
C		DM08	15
C		DM08	16
C		DM08	17
C	IN THE FOLLOWING, U AND V SHOULD HAVE FACTOR COS(THPLPH) FACTOR IN	DM08	18
C	FRONT.	DM08	19
C	VT SHOULD HAVE FACTOR SIN(THPLPH) FACTOR IN FRONT.	DM08	20
C	ANGLE THPLPH IS MEASURED CLOCKWISE FROM THE LEeward DIRECTION WHEN	DM08	21
C	VIEWED FROM THE REAR.	DM08	22
C	THE ANGULAR DEPENDENCE ON ANGLE THPLPH IS ACCOUNTED FOR IN	DM08	23
C	SUBROUTINE VELCAL.	DM08	24
	XI=XFIELD-TX(J)	DM08	25
	HR=BETA*RFIELD	DM08	26
	IF(XI.LE.HR) GO TO 10	DM08	27
	IF(X2.LE.HR) GO TO 21	DM08	28
	WRITE(6,100)	DM08	29
	GO TO 10	DM08	30
21	XHR=XI/HR	DM08	31
	XX=SQRT(XHR*XHR-1.)	DM08	32
	U=BETA*XX	DM08	33
	ACOSM=ALOG(XHR+XX)	DM08	34
	V=XHR*XX	DM08	35

	V= .5*HETASQ*(ACOSH+XX)	DM08	36
	VT= .5*HETASQ*(ACOSH+YY)	DM08	37
	RETURN	DM08	38
C		DM08	39
C	FIELD POINT IS AHEAD OF MACH. CONE FROM DOUBLET ORIGIN.	DM08	40
C		DM08	41
	10 U=0.	DM08	42
	V=0.	DM08	43
	VT=0.	DM08	44
	RETURN	DM08	45
	END	DM08	46
	COMPLEX FUNCTION DSDZ(S)	DM09	1
C		DM09	2
C	VERSION: DEMON1	DM09	3
C		DM09	4
	COMMON/COM2/SIG2,M2	DM09	5
	COMMON/COM5/DWDZ	DM09	6
	COMMON/COM4/G2,G1	DM09	7
	COMMON/COM6/*2,K	DM09	8
	COMPLEX W,*2,DWDZ,G1,G2	DM09	9
	DSDZ=0.5*(1.0-SIG2*M2)*(1.0+G1/G2)*DWDZ	DM09	10
	RETURN	DM09	11
	END	DM09	12
	SUBROUTINE EDGES(MS*P,SPAN,RBOD,ANGLE,ANGTE,Y,SWLE,SWTE)	DM10	1
C		DM10	2
C	VERSION: DEMON1	DM10	3
C		DM10	4
C	THIS ROUTINE CALCULATES EQUALLY SPACED SIDE-EDGES.	DM10	5
C	SWEEP ANGLE ARRAYS ARE SET EQUAL TO CONSTANT	DM10	6
C	LEADING EDGE AND TRAILING EDGE VALUES.	DM10	7
C		DM10	8
	DIMENSION Y(1),SWLE(1),SWTE(1)	DM10	9
C		DM10	10
	DYR=SPAN/(MS*P-1)	DM10	11
	DO 50 I=1,MS*P	DM10	12
	AI=I-1	DM10	13
	SWLE(I)=ANGLE	DM10	14
	SWTE(I)=ANGTE	DM10	15
	Y(I)=DYR*AI+RBOD	DM10	16
50	CONTINUE	DM10	17
	SWLE(1)=0.0	DM10	18
	SWTE(1)=0.0	DM10	19
C		DM10	20
	RETURN	DM10	21
	END	DM10	22
	SUBROUTINE EDGVOR	DM11	1
C		DM11	2
C	VERSION: DEMON1	DM11	3
C		DM11	4
C	COMPUTE EFFECTS AT CONTROL POINTS ON FINS AND BODY INTERFERENCE	DM11	5
C	SHELL OF FIN LEADING AND SIDE EDGE VORTICITY.	DM11	6

C		DM11	7
	LOGICAL BODY	DM11	8
C		DM11	9
	COMMON/ONE/CIRC(250),DELTP(250),FN(250),PNLC(250),SWPPLE(250),	DM11	10
	1S+POTE(250),VNDIR(250),XBAR(250),ZBAR(250),XCPT(250),YCPT(250),ZCPTD	DM11	11
	2(250),XLF(250),XLH(250),XRF(250),XRH(250),YLC(250),YHC(250),ZLF(250)	DM11	12
	30),ZRF(250),ZLB(250),ZRB(250),SHT(125),CST(125),SHT2(125),CST2(125)	DM11	13
	4),IP(300),XFHIP(100),A,ALFA,ALFA,ARHING,R2,R2V,BETA,BETAR,CONST,	DM11	14
	5COSALF,COSBET,CM,DX,EY,FMACH,RCIR,SINALF,SINBET,SLOPE,TLRAC,TIPY,	DM11	15
	6TDLR,U,V,W,UCHK,VCHK,WCHK,WBIP,X,Y,Z,I,TF,II,J,MSWR,MSWL,MSWII,	DM11	16
	7MSWD,ARIP,ACRX,NCW,NDRAG,NHP,NRP,NRP,N3P,NDCPT,NOLINP,NOUT,NPANELS,	DM11	17
	8NPRESS,NWBP,ASYM,BODY,DELTAS,NOSYM	DM11	18
	COMMON/VRTXV/VVRTX(150),WVRTX(150),NVRTPI,NVRTX,VPTMAX	DM11	19
	COMMON/HVEL/HDU(150),RDV(150),RDW(150),XFLOP(150),YFLOP(150),	DM11	20
	1 ZFLOP(150)	DM11	21
	COMMON/FINLE/XLE(80),CGLOC(80),GAMLE(80),FKLE,NEDGV,MLEVR,MLEVL,	DM11	22
	1 MLEVV,MLEVD	DM11	23
	COMMON/FINSE/XSE(80),CGSELC(80),GAMSE(80),FKSE,NSIDGE,NSEV	DM11	24
	COMMON/VGRSPC/GAMMA(10),YVRTX(10),ZVRTX(10),PLOC	DM11	25
	COMMON/ELLIPS/RA,RB,ERATIO	DM11	26
C		DM11	27
	DATA PI/3,141592653589/	DM11	28
C		DM11	29
	716 FORMAT (1H1,15X,43HFIN L.E. AND S.E. EFFECTS AT CONTROL POINTS//	DM11	30
	1 2X,1HK,5X,4HX,CP,7X,4HY,CP,7X,4HZ,CP,6X,4HGAMMA//,6X,7HY,VRTX//,4X,	DM11	31
	2 7HZ,VRTX//,3X,6HV,VRTX,5X,6HW,VRTX/34X,11H2PI*RR*VINF,2X,2HRB,9X,	DM11	32
	3 2HRH//)	DM11	33
	717 FORMAT (1X,I3,8(1X,F10,5))	DM11	34
C		DM11	35
C		DM11	36
C	EFFECT OF FIN L.E. VORTICITY AT THE FIN CONTROL POINTS AND THE	DM11	37
C	BODY INTERFERENCE PANEL CONTROL POINTS.	DM11	38
C		DM11	39
	NDCPT=1	DM11	40
	NVRT=NVRTX	DM11	41
	IF (NOUT.EQ.0) WRITE (6,716)	DM11	42
	JTIPLE=NRP+NCN+1	DM11	43
	XTIPLE=XRF(JTIPLE)	DM11	44
	DENOM=2.0*PI*RH	DM11	45
	JTIPT=NRP	DM11	46
	XTIPTY=XRH(JTIPT)	DM11	47
	DO 33 K=1,NWBP	DM11	48
	XFLOP(K)=XCPT(K)	DM11	49
	YFLOP(K)=YCPT(K)	DM11	50
	ZFLOP(K)=ZCPT(K)	DM11	51
	IF (NEDGV.EQ.0) GO TO 34	DM11	52
	IFIN=1	DM11	53
	KSTART=1	DM11	54
	KUL=MLEVR	DM11	55
35	CONTINUE	DM11	56
	IF (IFIN.EQ.5) GO TO 34	DM11	57
	IF (IFIN.EQ.2) KSTART=MLEVR+1	DM11	58
	IF (IFIN.EQ.3) KSTART=MLEVR+MLEVL+1	DM11	59
	IF (IFIN.EQ.4) KSTART=MLEVR+MLEVL+MLEVV+1	DM11	60
	DO 36 IFV=KSTART,KUL	DM11	61
	IF (XCPT(K).LT.XLE(KSTART)) GO TO 34	DM11	62
	JV=IFV-1	DM11	63
	IF (IFV.EQ.1) JV=1	DM11	64
	IF (XCPT(K).LE.XLE(IFV)) GO TO 37	DM11	65
36	CONTINUE	DM11	66
	IF (XCPT(K).LE.XTIPLE) GO TO 38	DM11	67
	GO TO 34	DM11	68
37	KV=JV+1	DM11	69

x1=x1E(JV)	DM11	70
x2=x1E(KV)	DM11	71
DIFF=x2-x1	DM11	72
wT1=(x2-xcPT(K))/DIFF	DM11	73
wT2=(xcPT(K)-x1)/DIFF	DM11	74
IF (IFIN.EQ.3,OR,IFIN.EQ.4) GO TO 39	DM11	75
YVINT=wT1*CGLUC(JV)+wT2*CGLUC(KV)	DM11	76
ZVBAR=xcPT(K)*TAN(ALFR/2,0)	DM11	77
GAMINT=wT1*GAMLE(JV)+wT2*GAMLE(KV)	DM11	78
YVRTX(1)=YVINT/RB	DM11	79
ZVRTX(1)=ZVBAR/RB	DM11	80
GAMMA(1)=GAMINT/DENOM	DM11	81
GO TO 31	DM11	82
38 GAMMA(1)=GAMLE(KUL)/DENOM	DM11	83
GAMINT=GAMLE(KUL)	DM11	84
IF (IFIN.EQ.3,OR,IFIN.EQ.4) GO TO 32	DM11	85
YVRTX(1)=CGLUC(KUL)/RB	DM11	86
ZVRTX(1)=xcPT(K)*TAN(ALFR/2,0)/RB	DM11	87
YVINT=CGLUC(KUL)	DM11	88
ZVBAR=ZVRTX(1)*RB	DM11	89
GO TO 31	DM11	90
32 YVRTX(1)=xcPT(K)*TAN(BETAR)/RB	DM11	91
ZVRTX(1)=CGLUC(KUL)/RB	DM11	92
YVINT=YVRTX(1)*RB	DM11	93
ZVBAR=CGLUC(KUL)	DM11	94
31 RLOC=RB	DM11	95
NVRTX=1	DM11	96
IF (HDDY,AND,RA,EQ,RB) CALL VORTEX (K,K)	DM11	97
YCP=YFLDP(K)	DM11	98
ZCP=ZFLDP(K)	DM11	99
THETP=ATAN2(ZCP,YCP)	DM11	100
SINTH=SIN(THETP)	DM11	101
COSTH=COS(THETP)	DM11	102
RCPT=SQRT(YCP*YCP+ZCP*ZCP)	DM11	103
RBODY=SQRT(1,0/((SINTH/RA)**2+(COSTH/RB)**2))	DM11	104
IF (RCPT.LE,RBODY) GO TO 20	DM11	105
GO TO 21	DM11	106
20 YCP=1,01*RBODY*COSTH	DM11	107
ZCP=1,01*RBODY*SINTH	DM11	108
21 CONTINUE	DM11	109
IF (HDDY,AND,RA,NE,RB) CALL VVELS(1,YCP ,ZCP ,YVINT,ZVBAR,	DM11	110
1 GAMINT,RB,RA,VVRTX(K),NVRTX(K),VRTMAX)	DM11	111
IF (NOUT,NE,0) WRITE (6,717) K,YFLDP(K),YFLDP(K),ZFLDP(K),	DM11	112
1 GAMMA(1),YVRTX(1),ZVRTX(1),NVRTX(K),VVRTX(K)	DM11	113
GO TO 40	DM11	114
39 ZVINT=wT1*CGLUC(JV)+wT2*CGLUC(KV)	DM11	115
YVBAR=xcPT(K)*TAN(BETAR/2,0)	DM11	116
GAMINT=wT1*GAMLE(JV)+wT2*GAMLE(KV)	DM11	117
YVRTX(1)=YVBAR/RB	DM11	118
ZVRTX(1)=ZVINT/RB	DM11	119
GAMMA(1)=GAMINT/DENOM	DM11	120
RLOC=RB	DM11	121
NVRTX=1	DM11	122
IF (HDDY,AND,RA,EQ,RB) CALL VORTEX (K,K)	DM11	123
YCP=YFLDP(K)	DM11	124
ZCP=ZFLDP(K)	DM11	125
THETP=ATAN2(ZCP,YCP)	DM11	126
SINTH=SIN(THETP)	DM11	127
COSTH=COS(THETP)	DM11	128
RCPT=SQRT(YCP*YCP+ZCP*ZCP)	DM11	129
RBODY=SQRT(1,0/((SINTH/RA)**2+(COSTH/RB)**2))	DM11	130
IF (RCPT.LE,RBODY) GO TO 22	DM11	131
GO TO 23	DM11	132

22	YCP=1.01*RHODY*COSTH	DM11 133
	ZCP=1.01*RHODY*SINTH	DM11 134
23	CONTINUE	DM11 135
	IF (BODY,AND,RA,NE,RBY) CALL VVELS(1,YCP ,ZCP ,YVHAR,ZVINT,	DM11 136
	1 GAMINT,RR,RA,VVRTX(K),VVRTX(K),VRTMAX)	DM11 137
	IF (NOUT,NE,0) WRITE (6,717) K,XFLDP(K),YFLDP(K),ZFLDP(K),	DM11 138
	1 GAMMA(1),VVRTX(1),ZVRTX(1),VVRTX(K),VVRTX(K)	DM11 139
40	CONTINUE	DM11 140
	IFIN=IFIN+1	DM11 141
	IF (IFIN,EQ,2) KUL=MLEVR+MLEVL	DM11 142
	IF (IFIN,EQ,3) KUL=MLEVR+MLEVL+MLEVU	DM11 143
	IF (NCPX,EQ,0) GO TO 34	DM11 144
	IF (IFIN,EQ,4) KUL=MLEVR+MLEVL+MLEVU+MLEVD	DM11 145
	GO TO 35	DM11 146
34	CONTINUE	DM11 147
C		DM11 148
C	EFFECTS OF FIN S.E. VORTICITY AT FIN CONTROL PRINTS AND BODY	DM11 149
C	INTERFERENCE PANELS.	DM11 150
C		DM11 151
	IF (NSIDG,EQ,0) GO TO 48	DM11 152
	IFIN=1	DM11 153
	KSTART=1	DM11 154
	KULNSEV	DM11 155
47	CONTINUE	DM11 156
	IF (IFIN,EQ,5) GO TO 48	DM11 157
	IF (IFIN,EQ,2) KSTART=NSSEV+1	DM11 158
	IF (IFIN,EQ,3) KSTART=2*NSSEV+1	DM11 159
	IF (IFIN,EQ,4) KSTART=3*NSSEV+1	DM11 160
	DO 49 JSE=KSTART,KUL	DM11 161
	IF (XCPT(K),LT,XSE(KSTART)) GO TO 48	DM11 162
	JVSE=JSE-1	DM11 163
	IF (JSE,EQ,1) JVSE=1	DM11 164
	IF (XCPT(K),LE,XSE(JVSE)) GO TO 46	DM11 165
49	CONTINUE	DM11 166
	IF (XCPT(K),LE,XTIPT) GO TO 41	DM11 167
	GO TO 48	DM11 168
46	CONTINUE	DM11 169
	KVSE=JVSE+1	DM11 170
	X1=XSE(JVSE)	DM11 171
	X2=XSE(KVSE)	DM11 172
	DIFF=X2-X1	DM11 173
	WT1=(X2-XCPT(K))/DIFF	DM11 174
	WT2=(XCPT(K)-X1)/DIFF	DM11 175
	IF (IFIN,EQ,3,OR,IFIN,EQ,4) GO TO 45	DM11 176
	YVINT=WT1*CGSEL(C(JVSE))+WT2*CGSEL(C(KVSE))	DM11 177
	ZVHAR=XCPT(K)*TAN(ALFR/2,0)	DM11 178
	GAMINT=WT1*GAMSE(JVSE)+WT2*GAMSE(KVSE)	DM11 179
	VVRTX(1)=YVINT/RB	DM11 180
	ZVRTX(1)=ZVHAR/RB	DM11 181
	GAMMA(1)=GAMINT/OPENUM	DM11 182
	GO TO 42	DM11 183
41	GAMMA(1)=GAMSE(KUL)/OPENUM	DM11 184
	GAMINT=GAMSE(KUL)	DM11 185
	IF (IFIN,EQ,3,OR,IFIN,EQ,4) GO TO 43	DM11 186
	VVRTX(1)=CGSEL(C(KUL))/RB	DM11 187
	ZVRTX(1)=XCPT(K)*TAN(ALFR/2,0)/RB	DM11 188
	YVINT=CGSEL(C(KUL))	DM11 189
	ZVHAR=ZVRTX(1)*RB	DM11 190
	GO TO 42	DM11 191
43	VVRTX(1)=(XCPT(K)*TAN(HEFR/2,0))/RB	DM11 192
	ZVRTX(1)=CGSEL(C(KUL))/RB	DM11 193
	YVINT=YVRTX(1)*RB	DM11 194
	ZVHAR=CGSEL(C(KUL))	DM11 195

42	RLOC=RR	DM11	196
	NVRTX=1	DM11	197
	IF (BODY,AND,RA,EQ,RR) CALL VORTEX (K,K)	DM11	198
	IF (BODY,AND,RA,NE,RR) CALL VVELS(1,YFLDP(K),ZFLDP(K),YVINT,ZVBAR,DM11	199	
	1 GAMINT,RR,RA,VVRTX(K),*VRTX(K),VRTMAX)	DM11	200
	IF (NOUT,NE,0) WRITE (6,717) K,XFLDP(K),YFLDP(K),ZFLDP(K),	DM11	201
	1 GAMMA(1),YVRTX(1),ZVRTX(1),VVRTX(K),*VRTX(K)	DM11	202
	GO TO 44	DM11	203
45	ZVINT=WT1*CGSELC(JVSE)+WT2*CGSELC(KVSE)	DM11	204
	YVBAR=XOPT(K)*TAN(HEPAR/2,0)	DM11	205
	GAMINT=WT1*GAMSE(JVSE)+WT2*GAMSE(KVSE)	DM11	206
	YVRTX(1)=YVBAR/RR	DM11	207
	ZVRTX(1)=ZVINT/RR	DM11	208
	GAMMA(1)=GAMINT/DENUM	DM11	209
	RLOC=RR	DM11	210
	NVRTX=1	DM11	211
	IF (BODY,AND,RA,EQ,RR) CALL VORTEX (K,K)	DM11	212
	IF (BODY,AND,RA,NE,RR) CALL VVELS(1,YFLDP(K),ZFLDP(K),YVBAR,ZVINT,DM11	213	
	1 GAMINT,RR,RA,VVRTX(K),*VRTX(K),VRTMAX)	DM11	214
	IF (NOUT,NE,0) WRITE (6,717) K,XFLDP(K),YFLDP(K),ZFLDP(K),	DM11	215
	1 GAMMA(1),YVRTX(1),ZVRTX(1),VVRTX(K),*VRTX(K)	DM11	216
44	CONTINUE	DM11	217
	IFIN=IFIN+1	DM11	218
	IF (IFIN,EQ,2) KUL=2*NSEV	DM11	219
	IF (IFIN,EQ,3) KUL=3*NSEV	DM11	220
	IF (NCRX,EQ,0) GO TO 48	DM11	221
	IF (IFIN,EG,4) KUL=4*NSEV	DM11	222
	GO TO 47	DM11	223
48	CONTINUE	DM11	224
33	CONTINUE	DM11	225
	NVRTX=NVRT	DM11	226
	RETURN	DM11	227
	END	DM11	228

	SUBROUTINE LAYOUT (3LPWLE,SLPWTE,Y,*SWP,CRP,NS,CTP,PHI,THET)	DM12	1
C		DM12	2
C	VERSION: DEMON2	DM12	3
C		DM12	4
C	THIS SUBROUTINE LAYS OUT AND DETERMINES GEOMETRICAL PROPERTIES	DM12	5
C	OF THE CONSTANT U-VELOCITY PANELS ON THE WING OR FIN SURFACES	DM12	6
C	AND ON THE BODY OR FUSELAGE WHERE MUTUAL WING-BODY INTERFERENCE	DM12	7
C	OCCURS.	DM12	8
C		DM12	9
C	DIMENSION CSIDE(20),NPD(3),Y(1)	DM12	10
C		DM12	11
C	LOGICAL LEFT,ASYM,BODY,DELTA,TRUSYM,NOSYM	DM12	12
C		DM12	13
C	COMMON/ONE/CIRC(250),DELTP(250),FN(250),PNLC(250),SWPPLE(250),	DM12	14
	1SWPPTE(250),VNDK(250),XBAR(250),ZBAR(250),XOPT(250),YOPT(250),ZOPT	DM12	15
	2(250),XLF(250),XLH(250),XRF(250),XRR(250),VIC(250),YRC(250),ZLF(250)	DM12	16
	30),ZRF(250),ZLH(250),ZRR(250),SNT(125),CST(125),SNT2(125),CST2(125)	DM12	17
	4),IP(300),XFRIP(100),A,ALFA,ALFR,AWING,RZ,RZV,RETA,REYAP,CONST,	DM12	18
	SCISALF,COSRET,CY,DX,EM,FMACH,RCIR,SINALF,SINBET,SLOPE,TLRNC,TTPY,	DM12	19
	6TUTLR,U,V,*,UCHK,VCHK,WCHK,WBIP,X,DDMY,Z,IV,TF,II,JV,MSWR,MSWL,	DM12	20
	7MSWU,MSWD,NEIP,NCRX,NCK,NDRAG,NRP,NRH,NRP,NSP,NOCPT,NOLINP,NOUT,	DM12	21
	8NPANLS,NPRESS,NWBP,ASYM,BODY,DELTA,NOSYM	DM12	22
	COMMON/SWEEPS/VSWLER(20),VSWFER(20),VSWLEL(20),VSWTEL(20),	DM12	23
	1 VSWLEU(20),VSWTEU(20),VSWLED(20),VSWTED(20),LVS*P,LEFT,FAC,NCNB	DM12	24
	2,ARPVL(250),*IDTM(250)	DM12	25

	COMMON/VRTXV/DIMMY(301),NVRTX,VRTMAX	DM12 26
	COMMON/WBTR/THI(125),X*LE	DM12 27
	COMMON /ELLIPS/ RA,RA,ERATIO	DM12 28
	COMMON /INTROT/ PHIDIN,THETI,YHOD,ZHOD,PHIFR,PHIFU	DM12 29
C		DM12 30
C		DM12 31
C	DATA PI/3,1415926535897/	DM12 32
C		DM12 33
C	FUNCTION DEFINING THE RADIUS OF AN ELLIPSE IN TERMS OF TH	DM12 34
C		DM12 35
	FRAID(SN,CS)=1.0/SQRT((CS/RA)**2+(SN/RA)**2)	DM12 36
	FYROT(YP) = COSINE*YP+YHOD	DM12 37
	FZROT(YP) = SINE *YP+ZHOD	DM12 38
C		DM12 39
	TRUSYM=BETAR.EQ.0.0.AND..NOT.DELTA	DM12 40
	DTOR = PI/180.	DM12 41
C		DM12 42
C	NS(=IL+1) IS WING QUADRANT INDICATOR	DM12 43
C	NS=1, RIGHT FIN# =2, LEFT FIN# =3, UPPER FIN# =4, LOWER FIN	DM12 44
C	NS=5, BODY	DM12 45
C	REFER TO MAIN PROGRAM CRFWBD FOR CORRESPONDENCE BETWEEN FINS ON	DM12 46
C	CRUCIFORM AND INTERDIGITATED CONFIGURATIONS.	DM12 47
C		DM12 48
	IF (NS.EQ.5) GO TO 200	DM12 49
	LEFT = NS.EQ.2 .OR. NS.EQ.4	DM12 50
	ANCW=NCW	DM12 51
	SLPCIF= SLP*LE=SLP*TE	DM12 52
	CSIDE(1)=CRP	DM12 53
	MPD(1)=MPP	DM12 54
	MPD(2)=MNP	DM12 55
	MPD(3)=M3P	DM12 56
C		DM12 57
C	VERTICAL WING TREATED IN THE SAME WAY AS HORIZONTAL WING	DM12 58
C	Y AND Z COORDINATES ARE INTERCHANGED FOR VERTICAL WING	DM12 59
C		DM12 60
C	LEFT STANDS FOR EITHER LEFT HORIZONTAL WING OR FOR LOWER	DM12 61
C	VERTICAL WING	DM12 62
C		DM12 63
C		DM12 64
C	LOCATE (Y,Z) OF WING BODY JUNCTION	DM12 65
C		DM12 66
	IF (THET.EQ.90.0) GO TO 100	DM12 67
	GO TO 101	DM12 68
100	CS=0.0	DM12 69
	SN=1.0	DM12 70
	GO TO 104	DM12 71
101	CONTINUE	DM12 72
	CS = COS(THET*DTOR)	DM12 73
	SN = SIN(THET*DTOR)	DM12 74
104	CONTINUE	DM12 75
	RAD = FRAID(SN,CS)	DM12 76
	IF (LEFT) RAD=-RAD	DM12 77
	YHOD = RAD*CS	DM12 78
	ZHOD = RAD*SN	DM12 79
C		DM12 80
C	DEFINE DIHEDRAL ANGLES OF FINS	DM12 81
C		DM12 82
	IF (PHI.EQ.90.0) GO TO 102	DM12 83
	GO TO 103	DM12 84
102	COSINE=0.0	DM12 85
	SINE=1.0	DM12 86
	GO TO 105	DM12 87
103	CONTINUE	DM12 88

	COSINE = COS(PHI*DTOR)	DM12 89
	SINE = SIN(PHI*DTOR)	DM12 90
105	CONTINUE	DM12 91
C		DM12 92
C	INDEX I RUNS SPANWISE, X CHORDWISE ALONG WING	DM12 93
C	CALCULATE LENGTHS OF OUTBOARD PANEL SIDE, CSIDE	DM12 94
C	J IS THE PANEL NUMBER	DM12 95
C		DM12 96
	WLEX=0.0	DM12 97
	DO 140 I=2, NSWP	DM12 98
	IM=I-1	DM12 99
C		DM12 100
C	LVSWP, VARIABLE WING SWEEP OPTION	DM12 101
C	LVSWP=0, GENERATE Y INTERNALLY IN CREWDR	DM12 102
C	LVSWP=1, READ IN Y+S,	DM12 103
C		DM12 104
	IF (LVSWP,EO,0) GO TO 40	DM12 105
	GO TO (42,41,30,31),NS	DM12 106
C		DM12 107
C	CASE FOR YAWED WING, STREAMWISE PLANE PASSING THROUGH ROOTCHORD	DM12 108
C	LE INTERSECTS WING TE	DM12 109
C	TE SWEEPS MAY VARY AS A CONSEQUENCE	DM12 110
C		DM12 111
C	PANELS ON RIGHT HAND WING	DM12 112
C		DM12 113
	42 SLPWLE=TAN(VSWLER(I)*DTOR)	DM12 114
	SLPWTE=TAN(VSWTER(I)*DTOR)	DM12 115
	GO TO 44	DM12 116
C		DM12 117
C	PANELS ON LEFT HAND WING	DM12 118
C		DM12 119
	41 SLPWLE=TAN(=VSWLEL(I)*DTOR)	DM12 120
	SLPWTE=TAN(=VSWTEL(I)*DTOR)	DM12 121
	GO TO 44	DM12 122
C		DM12 123
C	PANELS ON UPPER WING	DM12 124
C		DM12 125
	30 SLPWLE=TAN(VSWLEU(I)*DTOR)	DM12 126
	SLPWTE=TAN(VSWTEU(I)*DTOR)	DM12 127
	GO TO 44	DM12 128
C		DM12 129
C	PANELS ON LOWER WING	DM12 130
C		DM12 131
	31 SLPWLE=TAN(=VSWLED(I)*DTOR)	DM12 132
	SLPWTE=TAN(=VSWTED(I)*DTOR)	DM12 133
C		DM12 134
C		DM12 135
	44 SLPDIF=SLPWLE-SLPWTE	DM12 136
	CSIDE(I)=CSIDE(IM)-(Y(I)-Y(IM))*SLPDIF	DM12 137
	IF (LEFT) CSIDE(I)=CSIDE(IM)+(Y(I)-Y(IM))*SLPDIF	DM12 138
	GO TO 43	DM12 139
C		DM12 140
C	NONVARYING L,E, AND T,E, SWEEPS CONSTANT VALUES USED	DM12 141
C		DM12 142
	40 CSIDE(I)=CRP+(Y(I)-Y(1))*SLPDIF	DM12 143
	IF (LEFT) CSIDE(I)=CRP+(Y(I)-Y(1))*SLPDIF	DM12 144
	43 CONTINUE	DM12 145
C		DM12 146
C	SWPPLE AND SWPTE ARE PANEL L,E, AND T,E, SWEEPS	DM12 147
C	CALCULATE PANEL CORNER POINT COORDINATES	DM12 148
C		DM12 149
	IF (I,EO,2) GO TO 45	DM12 150
	JLE=(I-3)*NC+1	DM12 151

	IF (NS.GT.1) JLE=JLE+NPD(NS=1)	DM12 152
	WLEX=XRF(JLE)	DM12 153
	IF (LEFT) WLEX=XLF(JLE)	DM12 154
C	45 CONTINUE	DM12 155
	DO 130 K=1,NCW	DM12 156
	J=(I-2)*NC+K	DM12 157
	IF (NS.GT.1) J=J+NPD(NS=1)	DM12 158
	AKM=K-1	DM12 159
	AK=K	DM12 160
	S*PPLF(J)=SLP*WLE=AKM*SLPDIF/ANCW	DM12 161
	S*PPTE(J)=SLP*WLE=AK*SLPDIF/ANCW	DM12 162
	IF (ABS(S*PPLF(J)).LE.0.001) S*PPLF(J)=0.0	DM12 163
	IF (ABS(S*PPTE(J)).LE.0.001) S*PPTE(J)=0.0	DM12 164
	IF (LEFT) GO TO 50	DM12 165
C		DM12 166
C	PANEL LAY OUT FOR RIGHT RIGHT HAND WING CORNER POINTS.	DM12 167
C	THEY APPLY TO RIGHT AND UPPER FINS.	DM12 168
C		DM12 169
	XLF(J)=AKM*CSIDE(IM)/ANCW+WLEX	DM12 170
	XLB(J)=XLF(J)+CSIDE(IM)/ANCW	DM12 171
	XRF(J)=AKM*CSIDE(I)/ANCW+(Y(I)-Y(IM))*SLP*WLE+WLEX	DM12 172
	XRB(J)=XRF(J)+CSIDE(I)/ANCW	DM12 173
	YLC(J)=Y(IM)	DM12 174
	YRC(J)=Y(I)	DM12 175
	GO TO 51	DM12 176
C		DM12 177
C	PANEL LAY OUT FOR LEFT HAND WING CORNER POINTS.	DM12 178
C	THEY APPLY TO LEFT AND LOWER FINS.	DM12 179
C		DM12 180
	50 CONTINUE	DM12 181
	XLF(J)=AKM*CSIDE(I)/ANCW+(Y(I)-Y(IM))*SLP*WLE+WLEX	DM12 182
	XRF(J)=AKM*CSIDE(IM)/ANCW+WLEX	DM12 183
	XRB(J)=XRF(J)+CSIDE(IM)/ANCW	DM12 184
	XLB(J)=XLF(J)+CSIDE(I)/ANCW	DM12 185
	YLC(J)=Y(I)	DM12 186
	YRC(J)=Y(IM)	DM12 187
	51 CONTINUE	DM12 188
	ZLF(J)=0.0	DM12 189
	ZRF(J)=0.0	DM12 190
	ZLB(J)=0.0	DM12 191
	ZRB(J)=0.0	DM12 192
C		DM12 193
C	FIND Y-COORDINATE OF CONTROL POINT AND PANEL CENTROID	DM12 194
C		DM12 195
	A1=XRB(J)-XRF(J)	DM12 196
	A2=XLB(J)-XLF(J)	DM12 197
	H=Y(I)-Y(IM)	DM12 198
	YBAR=(2.0*A1+A2)*H/(3.0*(A1+A2))	DM12 199
	YCPT(J)=Y(IM)+YBAR	DM12 200
	IF (LEFT) YBAR=(2.0*A2+A1)*H/(3.0*(A1+A2))	DM12 201
	IF (LEFT) YCPT(J)=Y(IM)-YBAR	DM12 202
		DM12 203
C		DM12 204
C	FIND X-COORDINATE OF CONTROL POINT AND PANEL CENTROID	DM12 205
C		DM12 206
	XPCLE=XLF(J)+YBAR*S*PPLF(J)	DM12 207
	XPCTE=XLB(J)+YBAR*S*PPTE(J)	DM12 208
	IF (LEFT) XPCLE=XRF(J)+YBAR*S*PPLF(J)	DM12 209
	IF (LEFT) XPCTE=XRB(J)+YBAR*S*PPTE(J)	DM12 210
	P*LC(J)=XPCTE-XPCLE	DM12 211
	XCP(J)=XPCLE+FAC*P*LC(J)	DM12 212
	XHAP(J)=(XPCTE+XPCLE)/2.0	DM12 213
C		DM12 214

C	ZCPT(J)=0.0	DM12 215
	ZHAR(J)=0.0	DM12 216
	IF (.NOT.LEFT) GO TO 120	DM12 217
	IF (SWPPLE(J),FR,0.0) SWPPLE(J)=TLRNC	DM12 218
	IF (SWPPE(J),FR,0.0) SWPPE(J)=TLRNC	DM12 219
	SWPPLE(J)=-SWPPLE(J)	DM12 220
	SWPPE(J)=-SWPPE(J)	DM12 221
	120 CONTINUE	DM12 222
C		DM12 223
C	AREA AND WIDTH OF PANEL IN LOCAL COORDINATES	DM12 224
C		DM12 225
C	121 ARPML(J)=0.5*(YRC(J)+YLC(J))*(XLB(J)+XLF(J)+XRB(J)+XRF(J))	DM12 226
	WIDTH(J)=YRC(J)-YLC(J)	DM12 227
C		DM12 228
C	TRANSFORM FROM FIN COORDINATES TO THE WING REFERENCE COORDINATE	DM12 229
C	SYSTEM XW,YW,ZW.	DM12 230
C		DM12 231
	ZLF(J) = FZROT(YLC(J)-Y(1))	DM12 232
	ZLH(J) = ZLF(J)	DM12 233
	YLC(J) = FYROT(YLC(J)-Y(1))	DM12 234
	ZPF(J) = FZROT(YRC(J)-Y(1))	DM12 235
	ZPH(J) = ZRF(J)	DM12 236
	YRC(J) = FYROT(YRC(J)-Y(1))	DM12 237
	ZBAR(J) = FZROT(YCPT(J)-Y(1))	DM12 238
	ZCPT(J) = ZBAR(J)	DM12 239
	YCPT(J) = FYROT(YCPT(J)-Y(1))	DM12 240
	130 CONTINUE	DM12 241
	140 CONTINUE	DM12 242
	CTP=CSIDE(MSWP)	DM12 243
	RETURN	DM12 244
C		DM12 245
C	***** LAY OUT BODY INTERFERENCE PANELS *****	DM12 246
C		DM12 247
C	200 DX=CRP/MCWB	DM12 248
		DM12 249
C		DM12 250
C		DM12 251
C	NOTE: MSWP IS ACTUALLY MDCR	DM12 252
C		DM12 253
	MSWP = 4*(MSWP/4)	DM12 254
	MS90 = MSWP/4	DM12 255
	MS180 = 2*MS90	DM12 256
	MS270 = 3*MS90	DM12 257
	MMSWP = MSWP	DM12 258
	IF (TRUSV) MMSWP=MMSWP/2	DM12 259
	DTHTOG = 90./FLOAT(MS90)	DM12 260
	DTHTS = DTHTOG	DM12 261
	DTHTU = DTHTOG	DM12 262
C		DM12 263
C	IT1,IT2,IT3,IT4,...,INDEX OF INTERFERENCE PANEL IMMEDIATELY	DM12 264
C	PRECEDING FIN LOCATIONS ON BODY CIRCUMFERENCE.	DM12 265
C		DM12 266
C	INITIALIZE	DM12 267
	IT1 = 0	DM12 268
	IT2 = 0	DM12 269
	IT3 = 0	DM12 270
	IT4 = 0	DM12 271
	IF (THEIT,GE,90. .OR. THEIT,LE,0.) GO TO 210	DM12 272
C		DM12 273
C	INTERDIGITATED TAIL EXISTS	DM12 274
C		DM12 275
C		DM12 276
C	RECALCULATE RADIUS AT AND VR,ZH COORDINATES OF FIN LOCATION	DM12 277

```

C      ON THE BODY CIRCUMFERENCE FOR THE RIGHT UPPER FIN ONLY.          0412 274
C                                                                              0412 279
C      CS=COS(THETIT*DTOR)                                               0412 280
C      SN=SIN(THETIT*DTOR)                                               0412 281
C      RAD=FRAD(SN,CS)                                                    0412 282
C      YBOD=RAD*CS                                                         0412 283
C      ZBOD=RAD*SN                                                         0412 284
C                                                                              0412 285
C      CHECK RATIO OF APPROXIMATE ARC LENGTH ON EITHER SIDE OF THETIT.  0412 286
C                                                                              0412 287
C                                                                              0412 288
C      ARCUS=SQRT(YBOD**2+(ZBOD-RA)**2)                                    0412 289
C      ARCS=SQRT((RB-YBOD)**2+ZBOD**2)                                    0412 290
C      DARC=(ARCUS+ARCS)/FLUAT(MS90)                                       0412 291
C                                                                              0412 292
C      DETERMINE NUMBER OF PANELS BETWEEN Y-AXIS AND FIN LOCATION ON THE 0412 293
C      BODY CIRCUMFERENCE.                                                0412 294
C                                                                              0412 295
C      IT1= IFIX((ARCS/DARC)+0.5)                                         0412 296
C      IT1= MAX0(IT1,1)                                                   0412 297
C      IT1= MIN0(IT1,MS90-1)                                             0412 298
C                                                                              0412 299
C      DTHTS IS INCREMENT BETWEEN PANELS ON RIGHT AND LEFT (0=THETIT)  0412 300
C      DTHTU IS INCREMENT BETWEEN PANELS ON TOP AND BOTTOM (THETIT=90)  0412 301
C                                                                              0412 302
C      DTHTS = THETIT/IT1                                                 0412 303
C      DTHTU = (90.-THETIT)/(MS90-IT1)                                    0412 304
C      IT2 = MS180-IT1                                                    0412 305
C      IT3 = MS180+IT1                                                    0412 306
C      IT4 = MSWP-IT1                                                     0412 307
C      CONTINUE                                                            0412 308
C                                                                              0412 309
C      HERE K HAS ONE VALUE FOR EACH RING OF HIP*S                       0412 310
C      FOR EACH CIRCUMFERENTIAL RING, THE X FRONT POSITION, XFBIP(L)     0412 311
C      IS A CONSTANT ==                                                  0412 312
C      XFBIP(L) IS THE X-STATON OF THE BODY RING IN WING COORDINATES    0412 313
C                                                                              0412 314
C      201 KX=0                                                            0412 315
C      DO 230 K=1,MBIP,MMSWP                                             0412 316
C      XS=KX*DX                                                            0412 317
C      KP=K+MMSWP=1                                                       0412 318
C                                                                              0412 319
C      L IS BODY PANEL INDEX                                             0412 320
C                                                                              0412 321
C      DO 220 L=K,KP                                                       0412 322
C      XFBIP(L)=XS                                                         0412 323
C      CONTINUE                                                            0412 324
C      KX=KX+1                                                            0412 325
C      CONTINUE                                                            0412 326
C                                                                              0412 327
C      CALCULATE THE TRIG FUNCTIONS OF THE ANGLES ASSOCIATED WITH EACH  0412 328
C      HIP. THIS LOOP EXECUTES ONCE FOR EACH DIFFERENT HIP ORIENTATION, 0412 329
C      SETS THE FUNCTIONS FOR ALL HIP*S THAT ARE AT THE SAME ANGLE.     0412 330
C                                                                              0412 331
C      ANG IS THE ANGLE OF ROTATION OF THE HIP WITH RESPECT TO THE WING  0412 332
C      COORDINATE SYSTEM.                                                0412 333
C      THY IS THE PULAR ANGLE OF THE HIP WITH RESPECT TO THE WING Y-AXIS. 0412 334
C                                                                              0412 335
C                                                                              0412 336
C      BODY PANEL NUMBERING BEGINS AT Z=0, Y=RB AND PROCEEDS           0412 337
C      COUNTERCLOCKWISE IN ANGLE , THEN INCREMENTED IN X.              0412 338
C                                                                              0412 339
C      IK = 0                                                              0412 340

```

	THTIDG = 0.0	DM12 341
	YIM1 = RH	DM12 342
	ZIM1 = 0.0	DM12 343
C		DM12 344
C	I IS THE RUNNING INDEX ON THE BODY CIRCUMFERENCE.	DM12 345
	DO 260 I=1,MSWP	DM12 346
C		DM12 347
C	GENERATE ANGLE TO BE INCREMENTED BETWEEN TAIL SEGMENTS	DM12 348
C		DM12 349
C	DTHT = DTHTS	DM12 350
C		DM12 351
C	TEST FOR UPPER OR LOWER BODY PANEL WIDTH	DM12 352
C		DM12 353
	IF (I.GT.IT1 .AND. I.LE.IT2) DTHT=DTHTU	DM12 354
	IF (I.GT.IT3 .AND. I.LE.IT4) DTHT=DTHTU	DM12 355
	THTIDG = THTIDG+DTHT	DM12 356
	IF (I.EQ.MS90) THTIDG=90.	DM12 357
	IF (I.EQ.MS180) THTIDG=180.	DM12 358
	IF (I.EQ.MS270) THTIDG=270.	DM12 359
	IF (I.EQ.MSWP) THTIDG=360.	DM12 360
C		DM12 361
C	COMPUTE GEOMETRY OF ELLIPTIC BODY AND PRESCRIBED ANGLE.	DM12 362
C		DM12 363
	THT=THTIDG+DTOR	DM12 364
C		DM12 365
C	COMPUTE PROPERTIES OF ELLIPTIC BODY	DM12 366
C	RAD IS THE LOCAL BODY RADIUS AS A FUNCTION OF THT	DM12 367
C	THT IS THE MERIDIAN ANGLE FOR THE PANEL MEASURED COUNTERCLOCKWISE	DM12 368
C	FROM THE Y(*ANG) AXIS	DM12 369
C		DM12 370
	SN=SN(THT)	DM12 371
	CS=CS(THT)	DM12 372
	YI=FRAD(SN,CS)*CS	DM12 373
	ZI=FRAD(SN,CS)*SN	DM12 374
C		DM12 375
C	CHECK FOR BODY SYMMETRY	DM12 376
C		DM12 377
	IF (I.GT.MS90 .AND. I.LE.MS270 .AND. TRUSYM) GO TO 250	DM12 378
	IK = IK+1	DM12 379
	DY=YI-YIM1	DM12 380
	DZ=ZI-ZIM1	DM12 381
	WHIP=SQRT(DZ*DZ+DY*DY)	DM12 382
	SN2= DZ/WHIP	DM12 383
	CS2=-DY/WHIP	DM12 384
	AREA=WB*IP*DX	DM12 385
C		DM12 386
C	J IS THE PANEL INDEX OF RIPS	DM12 387
C	K IS THE PANEL INDEX OF KING AND BODY PANELS	DM12 388
C		DM12 389
	DO 240 J=IK,NHIP,MMSWP	DM12 390
	K=J+NPANLS	DM12 391
	THTI(J)=THTIDG	DM12 392
	SNT(J)=SN	DM12 393
	CST(J)=CS	DM12 394
	SNT2(J)=SN2	DM12 395
	CST2(J)=CS2	DM12 396
C		DM12 397
C		DM12 398
	YCPT(K)=0.5*(YI+YIM1)	DM12 399
	ZCPT(K)=0.5*(ZI+ZIM1)	DM12 400
C		DM12 401
	SWPPL(K)=0.0	DM12 402
	S*PRTE(K)=0.0	DM12 403

	ARPNL(K)=AREAP	DM12 404
C		DM12 405
C	NOTE == IN THE **HIP** SYSTEM, YLC=0 AND YRC=HIP	DM12 406
C		DM12 407
C	DEFINE HIP PANEL CORNER POINTS IN WING COORDINATE SYSTEM	DM12 408
C		DM12 409
	YLC(K)=YI	DM12 410
	YRC(K)=YIM1	DM12 411
	ZLF(K)=ZI	DM12 412
	ZLB(K)=ZI	DM12 413
	ZRF(K)=ZIM1	DM12 414
	ZRB(K)=ZIM1	DM12 415
	XLF(K)=XFHIP(J)	DM12 416
	YRF(K)=XLF(K)	DM12 417
	XLR(K)=XLF(K)+DX	DM12 418
	YRB(K)=XLR(K)	DM12 419
C		DM12 420
C	CONTROL POINT X COORDINATE IN WING SYSTEM	DM12 421
C		DM12 422
240	YCPT(K)=XFHIP(J)+FAC*DX	DM12 423
250	CONTINUE	DM12 424
	YIM1=YI	DM12 425
	ZIM1=ZI	DM12 426
260	CONTINUE	DM12 427
	RETURN	DM12 428
	END	DM12 429

	SUBROUTINE LINEQS(N,A)	DM13 1
C		DM13 2
C	VERSION: DEMONI	DM13 3
C		DM13 4
C	THIS SUBROUTINE TAKES IN SINGLE COLUMN MATRIX A(N*N), CONVERTS IT	DM13 5
C	TO SQUARE MATRIX A(N*N) AND	DM13 6
C	IP(300) REMEMBERS WHAT WAS DONE TO TRIANGULATE MATRIX A	DM13 7
C	IT IS USED IN SOLVE TO DO SAME THING TO B	DM13 8
C		DM13 9
C	DIMENSION A(N,N)	DM13 10
C		DM13 11
C	LOGICAL ASYM,BODY,DELTA,NOSYM	DM13 12
C		DM13 13
C	COMMON/ONE/DUM1(6000),IP(300),DUM2(100),DUM3(54),ASYM,BODY,DELTA,	DM13 14
C	INOSYM	DM13 15
C		DM13 16
	IP(N)=1	DM13 17
	DO 6 K=1,N	DM13 18
	IF(K.EQ.N)GO TO 5	DM13 19
	KP1=K+1	DM13 20
	M=K	DM13 21
	IP(K)=M	DM13 22
	IF(M.NE.K)IP(N)=-IP(N)	DM13 23
	T=A(M,K)	DM13 24
	A(N,K)=A(K,K)	DM13 25
	A(K,K)=T	DM13 26
	IF(T.EQ.0.)GO TO 5	DM13 27
	DO 2 I=KP1,N	DM13 28
	2 A(I,K)=-A(I,K)/T	DM13 29
	DO 4 J=KP1,N	DM13 30
	T=A(M,J)	DM13 31
	A(M,J)=A(K,J)	DM13 32
	A(K,J)=T	DM13 33
	IF(T.EQ.0.)GO TO 4	DM13 34
	DO 3 I=KP1,N	DM13 35
3	A(I,J)=A(I,J)+A(I,K)*T	DM13 36

	4 CONTINUE	DM13	37
	5 IF(A(K,K),EQ,0.)IP(N)=0	DM13	38
	6 CONTINUE	DM13	39
	RETURN	DM13	40
	END	DM13	41
	 SUBROUTINE LOADS	DM14	1
C		DM14	2
C	VERSION:DEMON2.	DM14	3
C		DM14	4
C	THIS SUBROUTINE CALCULATES FORCES AND MOMENTS ACTING ON THE	DM14	5
C	WINGS OR FINS AND THE INTERFERENCE SHELL.	DM14	6
C	THEY ARE FIRST CALCULATED IN THE WING REFERENCE COORDINATE SYSTEM	DM14	7
C	AND THEN TRANSFORMED TO WING-AXIS SYSTEM.	DM14	8
C		DM14	9
C	IN-PLANE FORCES FX AND FY1 OR FZ1 ARE ALSO COMPUTED. HERE,FX	DM14	10
C	IS POSITIVE FORWARD PARALLEL TO BODY CENTERLINE.	DM14	11
C	IN-PLANE FORCE FY2 IS CALCULATED IN SUBROUTINE SPMLD.	DM14	12
C		DM14	13
	DIMENSION BFY(100),BFZ(100)	DM14	14
	DIMENSION XB(150),YC(150),ZB(150)	DM14	15
C		DM14	16
	LOGICAL ASYM,NOSYM,BODY,DELTA,ANY,ANYHD	DM14	17
C		DM14	18
	COMMON/ONE/CIRC(250),DELTP(250),FN(250),PNLC(250),SWPPE(250),	DM14	19
	1SWPPE(250),VNOR(250),XBAR(250),ZBAR(250),XCPT(250),YCPT(250),ZCPT(250),	DM14	20
	2(250),XLF(250),XLB(250),XRF(250),XRB(250),YLC(250),YRC(250),ZLF(250),	DM14	21
	30),ZRF(250),ZLH(250),ZRH(250),SNT(125),CST(125),SNT2(125),CST2(125),	DM14	22
	4),IP(300),XFBIP(100),A,ALFA,ALFR,ARWING,R2,P2V,BETA,BETAR,CONST,	DM14	23
	5COSALF,COSBET,CN,DX,EM,FMACH,RC1R,SINALF,SINBET,SLOPE,TLRNC,TIPY,	DM14	24
	6TOTLR,U,V,W,UCHK,VCHK,WCHK,WRIP,X,Y,Z,IV,IF,II,JV,MSWR,MSXL,MSXU,	DM14	25
	7MSWD,NRIP,NCRX,NCW,NDRAG,NMP,NRP,NRP,N3P,NOCPT,NOLINP,NOUT,PANLS,	DM14	26
	8NPRESS,NWRP,ASYM,BODY,DELTA,NOSYM	DM14	27
	COMMON/THREE/ANGLR,ANGLL,ANGLU,ANGLD,DELR,DELL,DELU,DELD,SHEF,REFL	DM14	28
	COMMON/SWEEPS/VSWLER(20),VSWTER(20),VSWLEL(20),VSWTEL(20),	DM14	29
	1 VSWLEU(20),VSWTEU(20),VSWLED(20),VSWTED(20),LVSWP,LEFT,FAC,NCWB	DM14	30
	2,ANPNL(250),WIDTH(250)	DM14	31
	COMMON/BVEL/BDU(150),BDV(150),BDW(150),XFLOP(150),YFLOP(150),	DM14	32
	1 ZFLOP(150)	DM14	33
	COMMON/SPCPRS/DLTP(150)	DM14	34
	COMMON/VRTX/VVPTX(150),WVRTX(150),WVRTPL,WVRTX,VRTMAX	DM14	35
	COMMON/WBTK/THTI(125),X*LE	DM14	36
	COMMON/FRCFIS/VNOROS(150),FX(150),FY(150),FZ(150),DLTPG(150),ANYHD	DM14	37
	COMMON/VPTHVL/VVEL(500),WVEL(500),JCPT,NCPQUT,NVLIN	DM14	38
	COMMON/SPSANG/SINALC,COSALC,SINPHI,COSPHI	DM14	39
	COMMON/ELLIPS/RA,RB,ERATIO	DM14	40
	COMMON/INTRPT/PHIDTH,THETIT,YROD,ZROD,PHIFR,PHIFU	DM14	41
	COMMON/DAFM/X4,ZM,CZ0A,CY0A,CM0A,CLN0A,CLL0A	DM14	42
C		DM14	43
	DATA PI/3.141592653590/	DM14	44
C		DM14	45
C		DM14	46
	701 FORMAT(1H1,25X,21HWING PANEL PROPERTIES,///,2X,1HJ,5X,7HYCPT(J),3X,	DM14	47
	1 10HCHORD THRU,4X,5HPANEL,3X,8HMIDCHORD,9X,6HDELTA=,5X,5HFN(J),/	DM14	48
	2 18X,8HCENTROID,6X,4HSPAN,4X,10HSEEP,DEG,,7X,2HCP,///)	DM14	49
	702 FORMAT(///,25X,21HWING PANEL PROPERTIES,///,2X,1HJ,5X,7HZCPT(J),3X,	DM14	50
	1 10HCHORD THRU,4X,5HPANEL,3X,8HMIDCHORD,9X,6HDELTA=,5X,5HFN(J),/	DM14	51
	2 18X,8HCENTROID,6X,4HSPAN,4X,10HSEEP,DEG,7X,2HCP,///)	DM14	52
	705 FORMAT(8X,13,7X,F10.5,2X,F10.5,2X,F10.5,2X,F10.5,2X,F10.5,	DM14	53
	12X,F10.5,2X,F10.5)	DM14	54
	706 FORMAT(1X,13,2(1X,F10.5),5(2X,F10.5))	DM14	55

```

707 FORMAT(1H1,20X,31HBODY INFLUENCE PANEL PROPERTIES//2X,1HJ,6X,      DM14 56
  1 7HYCPT(J),4X,6HLENGTH,6X,5H>IDTH,6X,8H|THETA(J),2X,5HVFY(J),5X,      DM14 57
  2 5HVFZ(J),5X,5HFN(J),5X,8H|DELTA=CP,3X,7HGAMMA/V//)      DM14 58
710 FORMAT(1X,I3,9(1X,F10.5))      DM14 59
714 FORMAT(1H1,25X,35HVELOCITIES AT PANEL CENTROID POINTS//      DM14 60
  1 10X,1HJ,11X,7H|XBAR(J),5X,7HYBAR(J),5X,7HZBAR(J),9X,1HU,11X,      DM14 61
  2 1HV,11X,1HW,8X,4HVNOR//)      DM14 62
717 FORMAT(1H1,40X,19HLOADING INFORMATION//      DM14 63
  X 11X,14HMACH NUMBER = ,E12.5/      DM14 64
  1 7X,18HANGLE OF ATTACK = ,F8.3,1X,7HDEGREES/      DM14 65
  27X,18H|SIDE SLIP ANGLE = ,F8.3,1X,7HDEGREES/      DM14 66
  3 13X,12H|ING AREA = ,F10.5/      DM14 67
  4 8X,17HREFERENCE AREA = ,F10.5/      DM14 68
  5 6X,19HREFERENCE LENGTH = ,F10.5/      DM14 69
  6 3X,22H|POSED WING SPAN B = ,F10.5/      DM14 70
  7 3X,22H|MENT CENTER X = ,F10.5/      DM14 71
  8 20X,5H|ZK = ,F10.5//)      DM14 72
71A FORMAT(20X,5HTOTAL,12X,10HFIN 1 OR R,8X,10HFIN 2 OR L,7X,      DM14 73
  1 10HFIN 3 OR U,8X,10HFIN 4 OR D,5X,13HINTERF. SHELL,/      DM14 74
  2 6X,19H|EFL. ANGLE DEG. = ,12X,4(6X,F12.5)//      DM14 75
  * 18X,7H|CTR = ,E12.5,4(6X,F12.5)//      DM14 76
  3 20X,5H|CZ = ,E12.5,5(6X,E12.5)//      DM14 77
  4 20X,5H|CY = ,E12.5,5(6X,E12.5)//      DM14 78
  5 20X,5H|CX = ,E12.5,5(6X,E12.5)//      DM14 79
  6 19X,6H|CLN = ,E12.5,5(6X,E12.5)//      DM14 80
  7 19X,6H|CLL = ,E12.5,5(6X,E12.5)//      DM14 81
  * //,20X,33H|FOLLOWING ARE IN WIND-AXIS SYSTEM//      DM14 82
  8 20X,5H|CL = ,E12.5,5(6X,E12.5)//      DM14 83
  * 16X,9H|CYWIND = ,E12.5,5(6X,E12.5)//      DM14 84
  9 19X,6H|C| = ,E12.5,5(6X,E12.5)//      DM14 85
  1 14X,12H|C|/CL**2 = ,E12.5/      DM14 86
  * 16X,9H|CXWIND = ,E12.5,5(6X,E12.5)//      DM14 87
  * 15X,10H|CLNWIND = ,E12.5,5(6X,E12.5)////)      DM14 88
725 FORMAT (//1X,26HU/VINE TYPE LOADING PRESSURE//)      DM14 89
726 FORMAT (//1X,32HBERNOULLI TYPE LOADING PRESSURE//)      DM14 90
727 FORMAT(1H1,27X,40HVELOCITIES AT PANEL OUTBOARD AFT CORNERS//)      DM14 91
728 FORMAT(1H0,9X,1HJ,11X,6HXRB(J),6X,6HYRC(J),6X,6HZRB(J),10X,1HU,      DM14 92
  1 11X,1HV,11X,1HW,8X,4HVNOR//)      DM14 93
729 FORMAT(1H0,9X,1HJ,11X,6HXLB(J),6X,6HYLC(J),6X,6HZLB(J),10X,1HU,      DM14 94
  1 11X,1HV,11X,1HW,8X,4HVNOR//)      DM14 95
730 FORMAT (///10X,61HNOTE: L.E. OF LEAD PANEL IN FIRST CHORDWISE ROW      DM14 96
  ITS SUPERSONIC//)      DM14 97
      DM14 98
      DM14 99
      DM14 100
      DM14 101
      DM14 102
      DM14 103
      DM14 104
      DM14 105
      DM14 106
      DM14 107
      DM14 108
      DM14 109
      DM14 110
      DM14 111
      DM14 112
      DM14 113
      DM14 114
      DM14 115
      DM14 116
      DM14 117
      DM14 118

```

C
C
C
C
C
C
C
C
C
C
C

508	ZFLDP(J)=ZCPT(J)	DM14 119
	NSTART=1	DM14 120
	IF (BODY,AND,RA,EQ,RB) CALL VELCAL(NPANLS,ALFR,HETAR,NSTART)	DM14 121
	DO 510 J=1,NPANLS	DM14 122
	CALL VELNDR(XBAR(J),YCPT(J),ZBAR(J))	DM14 123
	UCT=UCHK	DM14 124
	VCT=VCHK	DM14 125
	WCT=WCHK	DM14 126
	IF(J,GT,NMP) GO TO 509	DM14 127
	VNDR(J)=VCHK+BDV(J)+VVEL(J)+VVRTX(J)	DM14 128
	GO TO 512	DM14 129
509	VNDR(J)=VCHK+BDV(J)+VVEL(J)+VVRTX(J)	DM14 130
512	CONTINUE	DM14 131
	IF (NOUT,NE,1) GO TO 510	DM14 132
	WRITE (6,705) J,XBAR(J),YCPT(J),ZBAR(J),UCT,VCT,WCT,VNDR(J)	DM14 133
510	CONTINUE	DM14 134
	HERE N=1.....RIGHT HOR. FIN	DM14 135
	N=2.....LEFT HOR. FIN	DM14 137
	N=3.....UPPER VERT. FIN	DM14 138
	N=4.....LOWER VERT. FIN	DM14 139
		DM14 140
	IF(NOUT,EO,1) WRITE (6,727)	DM14 141
	N=0	DM14 142
	JSTART=1	DM14 143
	JTIP=NRP,NCW+1	DM14 144
	TIPCHD=XPR(NRP)-XRF(JTIP)	DM14 145
	JEND=NRP	DM14 146
607	N=N+1	DM14 147
	IF (NOUT,EO,1,AND,(N,EO,1,OR,N,EO,3)) GO TO 911	DM14 148
	IF (NOUT,EO,1) WRITE (6,729)	DM14 149
	GO TO 912	DM14 150
911	WRITE (6,728)	DM14 151
912	DO 608 J=JSTART,JEND	DM14 152
	IF(N,EO,2,OR,N,EO,4) GO TO 908	DM14 153
	XFLDP(J)=XRB(J)	DM14 154
	YFLDP(J)=YRC(J)	DM14 155
	ZFLDP(J)=ZRB(J)	DM14 156
	XR(J)=XRB(J)	DM14 157
	YC(J)=YRC(J)	DM14 158
	ZB(J)=ZRB(J)	DM14 159
		DM14 160
	FOR WINGS WITH SIDE EDGES:	DM14 161
	IF L.E. SWEEP OF COUNTERWISE ROR NEAREST THE TIP IS SUBSONIC,	DM14 162
	MOVE THE OUTBOARD CORNER OUT ONE PANEL WIDTH	DM14 163
		DM14 164
	IF (TIPCHD,LT,100,0+TLRNC) GO TO 608	DM14 165
	IF (N,EO,1,AND,J,GE,JTIP,AND,SWPPLE(JTIP),GT,BETA) GO TO 909	DM14 166
	IF (N,EO,3,AND,J,GE,JTIP,AND,SWPPLE(JTIP),GT,BETA) GO TO 925	DM14 167
	GO TO 608	DM14 168
909	YC(J)=YRC(J)+1,0+WIDTH(J)	DM14 169
	GO TO 608	DM14 170
925	ZB(J)=ZRB(J)+1,0+WIDTH(J)	DM14 171
	GO TO 608	DM14 172
908	XFLDP(J)=XLR(J)	DM14 173
	YFLDP(J)=YLC(J)	DM14 174
	ZFLDP(J)=ZLH(J)	DM14 175
	XB(J)=XLR(J)	DM14 176
	YC(J)=YLC(J)	DM14 177
	ZB(J)=ZLH(J)	DM14 178
		DM14 179
	IF (TIPCHD,LT,100,0+TLRNC) GO TO 608	DM14 180
	IF (N,EO,2,AND,J,GE,JTIP,AND,ABS(SWPPLE(JTIP)),GT,BETA) GO TO 924	DM14 180
	IF (N,EO,4,AND,J,GE,JTIP,AND,ABS(SWPPLE(JTIP)),GT,BETA) GO TO 926	DM14 181

	GO TO 608	0414 187
924	YC(J)=YIC(J)=1.0*[DTH(J)	0414 188
	GO TO 608	0414 189
926	ZB(J)=ZRH(J)=1.0*[DTH(J)	0414 185
608	CONTINUE	0414 186
	IF (BDIV,AND,NA,EO,PR) CALL VELCAL(JEND,ALFR,PETAP,JSTART)	0414 187
	DO 610 J=JSTART,JEND	0414 188
	CALL VELNDR(XR(J),YC(J),ZB(J))	0414 189
	UCT=UCHK	0414 190
	VCT=VCHK	0414 191
	*CT=WCHK	0414 192
	IF (J,GT,NHP) GO TO 915	0414 193
	VNDROS(J)=WCHK+BDV(J)+WVEL(J)+WVRTX(J)	0414 194
	GO TO 913	0414 195
915	VNDROS(J)=VCHK+NOV(J)+VVEL(J)+VVRTX(J)	0414 196
913	IF (NOUT,NE,1) GO TO 610	0414 197
	WRITE (6,705) J,XB(J),YC(J),ZB(J),UCT,VCT,*CT,VNDROS(J)	0414 198
610	CONTINUE	0414 199
	IF (.NOT.NOSYM) GO TO 513	0414 200
	IF (N,NE,1) GO TO 611	0414 201
	JSTART=NRP+1	0414 202
	JEND=NHP	0414 203
	JTIP=NHP-NC+1	0414 204
	TIPCHD=XLH(NHP)-XLF(JTIP)	0414 205
	GO TO 607	0414 206
611	IF (N,NE,2,OR,NHP,EO,NPALS) GO TO 612	0414 207
	JSTART=NRP+1	0414 208
	JEND=NHP	0414 209
	JTIP=NHP-NC+1	0414 210
	TIPCHD=XRH(NHP)-XRF(JTIP)	0414 211
	GO TO 607	0414 212
612	IF (N,NE,3) GO TO 513	0414 213
	JSTART=NRP+1	0414 214
	JEND=NPALS	0414 215
	JTIP=NPALS-NC+1	0414 216
	TIPCHD=XLH(NPALS)-XLF(JTIP)	0414 217
	GO TO 607	0414 218
513	CONTINUE	0414 219
C		0414 220
C		0414 221
C		0414 222
C	INITIALIZE VARIABLES	0414 223
		0414 224
	CNR=0.	0414 225
	CYR=0.	0414 226
	CZBIP=0.0	0414 227
	CYHIP=0.0	0414 228
	CMHIP=0.0	0414 229
	CLNHP=0.0	0414 230
	CLLHP=0.0	0414 231
	CLRHP=0.0	0414 232
	CCIRP=0.0	0414 233
	CYHRP=0.0	0414 234
	CMHRP=0.0	0414 235
	CLNRP=0.0	0414 236
		0414 237
C		0414 238
C	ENTER HERE FOR NONLINEAR PRESSURE LOADINGS	0414 239
C		0414 240
C	ENTRY SPECLO	0414 241
		0414 242
	DTOR=PI/180.0	0414 243
	AREA=0.0	0414 244
	CZ(A)=0.0	0414 244

	CYDA=0.0	DM14 245
	CMDA=0.0	DM14 246
	CLNDA=0.0	DM14 247
	CLLDA=0.0	DM14 248
	CZFINU=0.0	DM14 249
	CZFIND=0.0	DM14 250
	CYFINU=0.0	DM14 251
	CYFIND=0.0	DM14 252
	CMFINU=0.0	DM14 253
	CMFIND=0.0	DM14 254
	CLNFU=0.0	DM14 255
	CLNFD=0.0	DM14 256
	CLLFU=0.0	DM14 257
	CLLFD=0.0	DM14 258
	CYU=0.	DM14 259
	CYD=0.	DM14 260
	CTHRU=0.	DM14 261
	CTHRD=0.	DM14 262
	CTHRR=0.0	DM14 263
	CTHRL=0.0	DM14 264
	CLR=0.0	DM14 265
	CLL=0.0	DM14 266
	CLU=0.0	DM14 267
	CLD=0.0	DM14 268
	CDIR=0.0	DM14 269
	CDIL=0.0	DM14 270
	CDIU=0.	DM14 271
	CDID=0.	DM14 272
	COCLS=0.0	DM14 273
	CYWR=0.0	DM14 274
	CYWL=0.0	DM14 275
	CYWU=0.0	DM14 276
	CYWD=0.0	DM14 277
	CYFR=0.	DM14 278
	CMFL=0.	DM14 279
	CMFU=0.	DM14 280
	CMFD=0.	DM14 281
	CLNFR=0.0	DM14 282
	CLNFL=0.0	DM14 283
	CLNFU=0.0	DM14 284
	CLNFD=0.0	DM14 285
	CNADRV=0.0	DM14 286
	CYADRM=0.0	DM14 287
		DM14 288
C	BETAY= BETAR/DTOR	DM14 289
	ANYEN(ASYM	DM14 290
	ANYMO=,NOT,ASYM	DM14 291
C		DM14 292
C	PUT MOMENT CENTER IN WING COORDINATE SYSTEM.	DM14 293
C		DM14 294
	X*BXH=XWLE	DM14 295
C		DM14 296
C		DM14 297
C	NOTE: DLTPG IS DELTA-LOADING PRESSURE/O OR DELTA-CP	DM14 298
C		DM14 299
	DO 902 I=1,NPANELS	DM14 300
	IF (NPRESS.EQ.0) DLTPG(I)=DELTP(I)	DM14 301
	IF (NPRESS.EQ.1) DLTPG(I)=DLTP(I)	DM14 302
	902 CONTINUE	DM14 303
C		DM14 304
C		DM14 305
C		DM14 306
C	WRITE OUT BIP PANEL PROPERTIES	DM14 307

C	CONTRIBUTION FROM BODY INTERFERENCE PANELS TO CZ...CNR	DM14 308
C	CONTRIBUTION FROM BODY INTERFERENCE PANELS TO CY...CYB	DM14 309
C		DM14 310
	IF (NBIP.EQ.0) GO TO 140	DM14 311
	IF (NPRESS.NE.0) GO TO 161	DM14 312
	IF (NOUT.NE.0) *WRITE (6,707)	DM14 313
	DO 140 K=1,NBIP	DM14 314
	Y=X+NPANLS	DM14 315
	F=DELTP(I)*ARPNL(I)	DM14 316
	FN(I)=F	DM14 317
	CALL ROTBW(0.,F,BFY(K),BFZ(K),K)	DM14 318
	CYB=CNR+BFZ(K)	DM14 319
	L=I	DM14 320
	CYB=CYB+BFY(K)	DM14 321
	CIRC(L)=0.5*DELTP(I)*DX	DM14 322
	ARM=XCPT(I)-XM*	DM14 323
	BFZM=BFZ(K)*ARM	DM14 324
	CMBIP=CMBIP+BFZM	DM14 325
	BFYM=BFY(K)*ARM	DM14 326
	CLNBIP=CLNBIP+BFYM	DM14 327
	BIPRM=BFZ(K)*YCPT(L)+BFY(K)*(ZCPT(L)-ZM)	DM14 328
	CLLRIP=CLLRIP+BIPRM	DM14 329
	IF (NOUT.NE.0)	DM14 330
	*WRITE(6,710) L,YCPT(L),DX,NBIP,THTI(K),BFY(K),BFZ(K),FN(L),	DM14 331
	*DELTP(L),CIRC(L)	DM14 332
140	CONTINUE	DM14 333
	CZBIP=CNR/SREF	DM14 334
	CYBIP=CYB/SREF	DM14 335
	CMBIP=CMBIP/(3REF*REFL)	DM14 336
	CLNBIP=CLNBIP/(SREF*REFL)	DM14 337
	CLLRIP=CLLRIP/(SREF*REFL)	DM14 338
	IF (ANY) GO TO 161	DM14 339
	CZBIP=2.0*CZBIP	DM14 340
	CYBIP=0.0	DM14 341
	CMBIP=2.0*CMBIP	DM14 342
	CLNBIP=0.0	DM14 343
	CLLRIP=0.0	DM14 344
161	CONTINUE	DM14 345
140	CONTINUE	DM14 346
C		DM14 347
C		DM14 348
C		DM14 349
C	CALCULATE FORCES,CZFIN,CYFIN, ACTING ON THE FINS,	DM14 350
C	PITCHING MOMENT,CMFIN,YAWING MOMENT,CLNF,ROLLIN MOMENT,CLLF,	DM14 351
C	CTHR IS THRUST FORCE, LAST LETTER DESIGNATES FIN AS FOLLOWS,	DM14 352
C	R.....HOR. RIGHT FIN	DM14 353
C	L.....HOR. LEFT FIN	DM14 354
C	U.....VERT. UPPER FIN	DM14 355
C	D.....VERT. LOWER FIN	DM14 356
C	HIP,.....INTERFERENCE SHELL.	DM14 357
C		DM14 358
C	ALSO:	DM14 359
C	IN WING OR BODY COORDINATE SYSTEM,	DM14 360
C	FX.....THRUST FORCE IN NEG. X-DIR. IN PLANE OF WING/D	DM14 361
C	FY.....SIDE FORCE IN Y-DIRECTION IN PLANE OF WING/D	DM14 362
C	FZ.....UPWARDS FORCE IN Z-DIR. IN PLANE OF VERTICAL WING	DM14 363
C	NOTE: ADDITIONAL CONTRIBUTIONS TO IN PLANE FORCES ARE CALCULATED	DM14 364
C	IN SUBROUTINE SPNLD.	DM14 365
C	PRESENTLY, IN-PLANE FORCES SUITABLE FOR CRUCIFORM OR PLANAR	DM14 366
C	FINS OR WINGS ONLY.	DM14 367
C		DM14 368
C	THE 300 LOOP IS USED FOR THE RIGHT AND LEFT HORIZONTAL PANELS	DM14 369
C		DM14 370

	IF (NDUT,NE,0) WRITE (6,701)	DM14 371
	JL=1	DM14 372
	JUB=NRP	DM14 373
	IL=0	DM14 374
	ANGL=ANGLR	DM14 375
	SINANG=SIN(ANGL)	DM14 376
	PHIF=PHIFR*DTOR	DM14 377
302	CONTINUE	DM14 378
	CZFIN=0,0	DM14 379
	CYFIN=0,0	DM14 380
	CMFIN=0,0	DM14 381
	CLNFIN=0,0	DM14 382
	CLLFIN=0,0	DM14 383
	CNN=0,0	DM14 384
	CTHR=0,0	DM14 385
	GO 301 J=JL,JU	DM14 386
	AREA=AREA+ARPNL(J)	DM14 387
	I=J	DM14 388
	F= ARPNL(J)*DLTPG(I)	DM14 389
	FN(I)=F	DM14 390
	YCHK= YCPT(I)+C/SBET=XBAR(I)*SINBET	DM14 391
	IF (ANYMR) YCHK=YCPT(I)	DM14 392
	ARM=YCPT(J)*XMR	DM14 393
	CALL ROTF(0,0,F,CYP,CZP,PHIF)	DM14 394
	CMP=CZP+ARM	DM14 395
	CLNPR=CYP+ARM	DM14 396
	PRM=CZP+YCPT(J)+CYP*(ZCPT(J)+Z)	DM14 397
	CZFIN=CZFIN+CZP	DM14 398
	CYFIN=CYFIN+CYP	DM14 399
	CMFIN=CMFIN+CMP	DM14 400
	CLNFIN=CLNFIN+CLNPR	DM14 401
	CLLFIN=CLLFIN+PRM	DM14 402
	CNN=CNN+F	DM14 403
C		DM14 404
C	CIRC IS GAMMA/V (FT),BASED ON LINEAR PRESSURE.	DM14 405
C		DM14 406
	CIRC(J)=0,5*DLTPG(J)*PNLC(J)	DM14 407
	SLPMC=0,5*(SWPPLE(J)+SWPPE(J))	DM14 408
	SWPMC=ATAN(SLPMC)*57,2957795	DM14 409
	IF (NDRAG,EN,0) GO TO 299	DM14 410
	FX(J)=2,0*WIDTH(J)+CIRC(J)*(SINANG+VNDR(J))	DM14 411
	FY(J)=FX(J)*SLPMC	DM14 412
	CYADDH=CYADDH+FY(J)	DM14 413
	CTHR=CTHR+FX(J)	DM14 414
299	IF (NDUT,NE,0)	DM14 415
	WRITE (6,704) J,YCPT(J),PNLC(J),WIDTH(J),SWPMC,DLTPG(J),FN(J)	DM14 416
	300 CONTINUE	DM14 417
C		DM14 418
	IF (IL,EO,1) GO TO 310	DM14 419
	CNR=CNN/SREF	DM14 420
	CZFINR=CZFIN/SREF	DM14 421
	CYFINR=CYFIN/SREF	DM14 422
	CMFINR=CMFIN/(SREF*REFL)	DM14 423
	CLNFR=CLNFIN/(SREF*REFL)	DM14 424
	CLLFR=CLLFIN/(SREF*REFL)	DM14 425
	CTHRR=CTHR/SREF	DM14 426
C		DM14 427
C	NOTE: SYMMETRY CONSIDERATIONS ARE USED IN DIFFERENT MANNER FOR	DM14 428
C	THE CASE OF INTERDIGITATED TAIL FINS (THEFIT,NE,0).	DM14 429
C	REFER TO MAIN PROGRAM CRF=BD FOR DESIGNATIONS OF INTERDIGITATED	DM14 430
C	FINS.	DM14 431
C		DM14 432
	IF (ANY) GO TO 301	DM14 433

	AREA=2.0*AREA	DM14 434
	IF (THEIT,NE,0.0) GO TO 303	DM14 435
	GO TO 304	DM14 436
303	CZFIN=CZFINR	DM14 437
	CYFIN=CYFINR	DM14 438
	CMFIN=CMFINR	DM14 439
	CLNFR=CLNFR	DM14 440
	CLLFR=CLLFR	DM14 441
	CTHR=CTHRR	DM14 442
	CY=CNR	DM14 443
	GO TO 311	DM14 444
304	CZFINL=CZFINR	DM14 445
	CYFINL=CYFINR	DM14 446
	CMFINL=CMFINR	DM14 447
	CLNFL=CLNFR	DM14 448
	CLLFL=CLLFR	DM14 449
	CTHRL=CTHRR	DM14 450
	CAL = CNR	DM14 451
	CYADDH=0.0	DM14 452
	GO TO 311	DM14 453
301	CONTINUE	DM14 454
C		DM14 455
C	REENTER ABOVE LOOP FOR LEFT HORIZONTAL PANEL	DM14 456
C		DM14 457
	IL=1	DM14 458
	JL=JU+1	DM14 459
	JU=NHP	DM14 460
	ANGL=ANGLL	DM14 461
	SINANG=SIN(ANGL)	DM14 462
	GO TO 302	DM14 463
310	CZFINL=CZFIN/SREF	DM14 464
	CYFINL=CYFIN/SREF	DM14 465
	CMFINL=CMFIN/(SREF*REFL)	DM14 466
	CLNFL=CLNFIN/(SREF*REFL)	DM14 467
	CLLFL=CLLFIN/(SREF*REFL)	DM14 468
	CTHRL=CTHR/SREF	DM14 469
	CAL=CNH/SREF	DM14 470
311	CONTINUE	DM14 471
	IF (NHP,EN,NPANELS) GO TO 350	DM14 472
C		DM14 473
C	THE 320 LOOP IS USED FOR THE UPPER AND LOWER VERTICAL PANELS	DM14 474
C		DM14 475
	IF (NOUT,NE,0) *WHITE (6,702)	DM14 476
	JL=NHP+1	DM14 477
	JU=N3P	DM14 478
	IL=0	DM14 479
	ANGL=ANGLU	DM14 480
	SINANG=SIN(ANGL)	DM14 481
	PHIF=PHIFU*DTOR	DM14 482
325	CONTINUE	DM14 483
	CZFIN=0.0	DM14 484
	CYFIN=0.0	DM14 485
	CMFIN=0.0	DM14 486
	CLNFIN=0.0	DM14 487
	CLLFIN=0.0	DM14 488
	CY=0.0	DM14 489
	CTHR=0.0	DM14 490
	DO 320 J=JL,JU	DM14 491
	I=J	DM14 492
	F= ARP*(J)*DLTPG(I)	DM14 493
	F*(I)=F	DM14 494
	ZCHK= ZCPT(I)*COSALF+XBAR(I)*SINALF	DM14 495
	IF (ANYMO) ZCHK=ZCPT(I)	DM14 496

	ARM=XCPT(J)=X*W	DM14 497
	CALL ROTFN(0.0,F,CYP,CZP,PHIF)	DM14 498
	CMP=CZP*ARM	DM14 499
	CLNP=CYP*ARM	DM14 500
	PRM=CZP*YCPT(J)+CYP*(ZCPT(J)-ZM)	DM14 501
	CZFIN=CZFIN+CZP	DM14 502
	CYFIN=CYFIN+CYP	DM14 503
	CMFIN=CMFIN+CMF	DM14 504
	CLNFIN=CLNFIN+CLNP	DM14 505
	CLLFIN=CLLFIN+PRM	DM14 506
	CYY=CYY+F	DM14 507
	CIRC(J)=0.5*DLTPG(J)*PNLC(J)	DM14 508
	SLPMC=0.5*(S*PPLC(J)+S*PPTC(J))	DM14 509
	S*PMC=ATAN(SLPMC)*57.2957795	DM14 510
	IF (NDRAG.EQ.0) GO TO 319	DM14 511
	FX(J)=2.*IDTH(J)*CIRC(J)*(SINANG-VNOR(J))	DM14 512
	FZ(J)=FX(J)*SLPMC	DM14 513
	CNADDV=CNADDV+FZ(J)	DM14 514
	CTHR=CTHR+FX(J)	DM14 515
310	IF (NDUT.NE.0)	DM14 516
	WRITE (6,706) J,ZCPT(J),PNLC(J),IDTH(J),S*PMC,DLTPG(J),FN(J)	DM14 517
320	CONTINUE	DM14 518
	IF (IL.EQ.1) GO TO 330	DM14 519
	CZFINU=CZFIN/SREF	DM14 520
	CYFINU=CYFIN/SREF	DM14 521
	CMFINU=CMFIN/(SREF*REFL)	DM14 522
	CLNFINU=CLNFIN/(SREF*REFL)	DM14 523
	CLLFINU=CLLFIN/(SREF*REFL)	DM14 524
	CTHRU=CTHR/SREF	DM14 525
	CYU=CYY/SREF	DM14 526
	IF (ANY) GO TO 321	DM14 527
	IF (THEIT.NE.0.0) GO TO 322	DM14 528
	GO TO 350	DM14 529
322	CZFINL=CZFINU	DM14 530
	CYFINL=CYFINU	DM14 531
	CMFINL=CMFINU	DM14 532
	CLNFINL=CLNFINU	DM14 533
	CLLFINL=CLLFINU	DM14 534
	CTHRL=CTHRU	DM14 535
	CNL=CYU	DM14 536
	GO TO 350	DM14 537
321	CONTINUE	DM14 538
C		DM14 539
C	REENTER ABOVE LOOP FOR LOWER VERTICAL PANEL	DM14 540
C		DM14 541
	IL=1	DM14 542
	JL=JU+1	DM14 543
	JU=NPANLS	DM14 544
	ANGLE=ANGLD	DM14 545
	SINANG=SN(ANGL)	DM14 546
	GO TO 325	DM14 547
330	CZFIND=CZFIN/SREF	DM14 548
	CYFIND=CYFIN/SREF	DM14 549
	CMFIND=CMFIN/(SREF*REFL)	DM14 550
	CLNFD=CLNFIN/(SREF*REFL)	DM14 551
	CLLFD=CLLFIN/(SREF*REFL)	DM14 552
	CTHRD=CTHR/SREF	DM14 553
	CYD=CYY/SREF	DM14 554
350	CONTINUE	DM14 555
C		DM14 556
C		DM14 557
C		DM14 558
C		DM14 559

C		DM14 560
C	OVERALL FORCE AND MOMENT COEFFICIENTS FOR FINS AND INTERFERENCE	DM14 561
C	SHELL IN WING OR BODY REFERENCE SYSTEM.	DM14 562
C		DM14 563
C	CTHROA.....ACTS ALONG NEGATIVE X-AXIS	DM14 564
C	CYIOA.....ACTS ALONG POSITIVE Y-AXIS	DM14 565
C	CZIOA.....ACTS ALONG POSITIVE Z-AXIS	DM14 566
C	CMQA.....VECTOR ALONG NEGATIVE Y-AXIS, NOSE UP POS.	DM14 567
C	CLNOA.....VECTOR ALONG POSITIVE Z-AXIS, NOSE TO RIGHT POS.	DM14 568
C	CLLNOA.....VECTOR ALONG POSITIVE X-AXIS, RIGHT WING DOWN POS.	DM14 569
C		DM14 570
C	CNADDV,CYADDH,..ADDITIONS TO CZOA,CYOA DUE TO IN PLANE FORCES, NOT	DM14 571
C	SUCTION CONVERSION TO NORMAL FORCE.	DM14 572
C		DM14 573
C	FORCE COEFFICIENTS IN X,Y,Z DIRECTIONS.	DM14 574
C		DM14 575
C	CTHROA=CTHRR+CTHRL+CTHRU+CTHRD	DM14 576
C	CZOA=CZFNR+CZFNL+CZFNU+CZFND+CZRIP	DM14 577
C	CYOA=CYFNR+CYFNL+CYFNU+CYFND+CYBIP	DM14 578
C	CNADDV=CNADDV/SREF	DM14 579
C	CYADDH=CYADDH/SREF	DM14 580
C		DM14 581
C	PITCHING, YAWING, ROLLING MOMENTS COEFFICIENTS.	DM14 582
C		DM14 583
C	CMQA=CMFNR+CMFNL+CMFNU+CMFND+CMBIP	DM14 584
C	CLNOA=CLNFR+CLNFL+CLNFU+CLNFD+CLNBIP	DM14 585
C	CLLOA=CLLFR+CLLFL+CLLFU+CLLFD+CLLBIP	DM14 586
C		DM14 587
C		DM14 588
C	OVERALL FORCE AND MOMENT COEFFICIENTS IN WIND-AXIS SYSTEM (EXCEPT	DM14 589
C	ROLLING MOMENT)	DM14 590
C		DM14 591
C	CDI.....ACTS BACK ALONG FREE STREAM DIRECTION, X=WIND-AXIS	DM14 592
C	CYW.....ACTS TO THE RIGHT NORMAL TO FREE STREAM VECTOR=BODY	DM14 593
C	CENTER LINE PLANE, Y=WIND-AXIS	DM14 594
C	CL.....ACTS UPWARDS IN FREE STREAM VECTOR=BODY CENTERLINE	DM14 595
C	PLANE NORMAL TO FREE STREAM VECTOR, Z=WIND-AXIS	DM14 596
C	CMQAW...VECTOR ALONG NEGATIVE YWIND-AXIS, NOSE UP POS.	DM14 597
C	CLNOAW...VECTOR ALONG POSITIVE ZWIND-AXIS, NOSE TO RIGHT, POS.	DM14 598
C		DM14 599
C	DRAG, LATERAL, LIFT FORCE COEFFICIENTS	DM14 600
C		DM14 601
C	CDIR=-CTHRR*COSALC-CYFNR*SINALC*SINPHI+CZFNR*SINALC*COSPHI	DM14 602
C	CDIL=-CTHRL*COSALC-CYFNL*SINALC*SINPHI+CZFNL*SINALC*COSPHI	DM14 603
C	CDIU=-CTHRU*COSALC-CYFNU*SINALC*SINPHI+CZFNU*SINALC*COSPHI	DM14 604
C	CDID=-CTHRD*COSALC-CYFND*SINALC*SINPHI+CZFND*SINALC*COSPHI	DM14 605
C	CDIRIP=	DM14 606
C	=CYRIP*SINALC*SINPHI+CZRIP*SINALC*COSPHI	DM14 607
C	CDI=CDIR+CDIL+CDIU+CDID+CDIRIP	DM14 608
C		DM14 609
C	CYWR=CZFNR*SINPHI+CYFNR*COSPHI	DM14 610
C	CYWL=CZFNL*SINPHI+CYFNL*COSPHI	DM14 611
C	CYWU=CZFNU*SINPHI+CYFNU*COSPHI	DM14 612
C	CYWD=CZFND*SINPHI+CYFND*COSPHI	DM14 613
C	CYWRIP=CZRIP*SINPHI+CYBIP*COSPHI	DM14 614
C	CYW=CYWR+CYWL+CYWU+CYWD+CYWRIP	DM14 615
C		DM14 616
C		DM14 617
C	CLR=CTHRR*SINALC-CYFNR*COSALC*SINPHI+CZFNR*COSALC*COSPHI	DM14 618
C	CLL=CTHRL*SINALC-CYFNL*COSALC*SINPHI+CZFNL*COSALC*COSPHI	DM14 619

	CLU=CTHRU*SINALC-CYFINU*COSALC+SINPHI+CZFINU*COSALC+COSPHI	DM14 620
	CLD=CTHRD*SINALC-CYFIND*COSALC+SINPHI+CZFIND*COSALC+COSPHI	DM14 621
	CLBIP=-CYBIP*COSALC+SINPHI+CZBIP*COSALC+COSPHI	DM14 622
	CL=CLR+CLL+CLU+CLD+CLBIP	DM14 623
	CDCLS=CDT/(CL*CL)	DM14 624
C		DM14 625
C	PITCHING, YAWING MOMENTS	DM14 626
C		DM14 627
	CMFR*=CMFINR*COSPHI-CLNFR*SINPHI	DM14 628
	CMFL*=CMFINL*COSPHI-CLNFL*SINPHI	DM14 629
	CMFU*=CMFINU*COSPHI-CLNFU*SINPHI	DM14 630
	CMFD*=CMFIND*COSPHI-CLNFD*SINPHI	DM14 631
	CMBIP*=CMBIP*COSPHI-CLNBIP*SINPHI	DM14 632
	CMQAW*=CMFR*+CMFL*+CMFU*+CMFD*+CMBIP*	DM14 633
C		DM14 634
C		DM14 635
	CLNFR*=-CLLFR*SINALC+CMFINR*COSALC+SINPHI+CLNFR*COSALC+COSPHI	DM14 636
	CLNFL*=-CLLFL*SINALC+CMFINL*COSALC+SINPHI+CLNFL*COSALC+COSPHI	DM14 637
	CLNFU*=-CLLFU*SINALC+CMFINU*COSALC+SINPHI+CLNFU*COSALC+COSPHI	DM14 638
	CLNFD*=-CLLFD*SINALC+CMFIND*COSALC+SINPHI+CLNFD*COSALC+COSPHI	DM14 639
	CLNBIP*=-CLLBIP*SINALC+CMBIP*COSALC+SINPHI+CLNBIP*COSALC+COSPHI	DM14 640
	CLNDAW*=CLNFR*+CLNFL*+CLNFU*+CLNFD*+CLNBIP*	DM14 641
		DM14 642
C		DM14 643
C	WRITE ALL LOADING RESULTS.	DM14 644
C		DM14 645
	SPAN=2.0*H2	DM14 646
	WRITE(6,717) FMACH,ALFA,BETAY,AREA,SREF,REFL,SPAN,XM,ZM	DM14 647
	IF (NPRESS.EQ.0) WRITE(6,725)	DM14 648
	IF (NPRESS.EQ.1) WRITE(6,726)	DM14 649
	WRITE(6,718) DELR,DELL,DELU,DELD,	DM14 650
	1 CTHDA,CTHR,CTHRL,CTHRU,CTHRD,	DM14 651
	2 CZDA,CZFIR,CZFIL,CZFINU,CZFIND,CZBIP,	DM14 652
	3 CYDA,CYFIR,CYFIL,CYFINU,CYFIND,CYBIP,	DM14 653
	4 CMOA,CMFIR,CMFIL,CMFINU,CMFIND,CMBIP,	DM14 654
	5 CLNDA,CLNFR,CLNFL,CLNFU,CLNFD,CLNBIP,	DM14 655
	6 CLLDA,CLLFR,CLLFL,CLLFU,CLLFD,CLLBIP,	DM14 656
	7 CL,CLR,CLL,CLU,CLD,CLBIP,	DM14 657
	* CYN,CYP,CYL,CYU,CYD,CYBIP,	DM14 658
	8 CDI,CDR,CDIL,CDIU,CDID,CDIBIP,	DM14 659
	9 CDCLS,	DM14 660
	CMQAW,CMFR,CMFL*,CMFU*,CMFD*,CMBIP*,	DM14 661
	CLNDAW,CLNFR,CLNFL*,CLNFU*,CLNFD*,CLNBIP*	DM14 662
		DM14 663
C	CHECK ON SUPERSONIC L.E. BASED ON L.E. SWEEP OF INBOARD	DM14 664
C	CHORDWISE NOW	DM14 665
C		DM14 666
	ARGTAN=1.0/BETA	DM14 667
	ANGMCH=(ATAN(ARGTAN))*57.2957795	DM14 668
	PSIMCH=90.0+ANGMCH	DM14 669
	PSIPLE=(ATAN(SWPPLE(1)))*57.2957795	DM14 670
	IF (PSIMCH.GT.PSIPLE) WRITE(6,730)	DM14 671
		DM14 672
C		DM14 673
C		DM14 674
C		DM14 675
	IF (THFIT.NE.0.0) RETURN	DM14 676
	CALL SPNU	DM14 677
	RETURN	DM14 678
	END	DM14 679

C	SUBROUTINE OUT(A,N)	DM15	1
C	VERSION: DEMON1	DM15	2
C	DIMENSION A(N,N)	DM15	3
	1 FORMAT(10(1X,E11.4))	DM15	4
	2 FORMAT(1H)	DM15	5
	DD 100 I=1,N	DM15	6
	*WRITE (6,1) (A(I,J),J=1,N)	DM15	7
100	WRITE(6,2)	DM15	8
	RETURN	DM15	9
	END	DM15	10
		DM15	11
		DM15	12
C	SUBROUTINE ROTATE(YIN,ZIN,YOUT,ZOUT,PHIF)	DM16	1
C	VERSION: DEMON2.	DM16	2
C	THIS SUBROUTINE ROTATES LOCAL COORDINATES RELATIVE TO CONSTANT	DM16	3
C	U-VELOCITY PANEL CORNERS AND PARALLEL TO WING COORDINATE	DM16	4
C	SYSTEM TO LOCAL COORDINATES IN THE PLANE OF THE PANEL ITSELF AND	DM16	5
C	VICE VERSA.	DM16	6
C	COMMON/DNE/DUM1(6400),A,DUM2(5),BETA,DUM3(6),EM,DUM4(4),SLOPE,	DM16	7
	1TLRNC,TIPY,TOTLR,U,V,N,DUM5(4),X,Y8,Z8,M1,DUM6(2),MJ,DUM7(8),NHP,	DM16	8
	ZNPR,DUM8(2),NOCP,NULINP,NOUT,NPANLS,DUM9(2),ASYM,BODY,DELTA,NOSYMDM16	DM16	9
	COMMON/INTROT/PHIOIN,THEIT,YROD,ZROD,PHIFR,PHIFU	DM16	10
C	DATA PI02/1,570796326795/	DM16	11
C		DM16	12
C		DM16	13
C	WING TO FIN	DM16	14
C	ENTRY ROTWF	DM16	15
	IF (ABS(PHIF-PI02),LT,TLRNC) GO TO 100	DM16	16
	GO TO 101	DM16	17
100	COSPHI=0.0	DM16	18
	SINPHI=1.0	DM16	19
	GO TO 104	DM16	20
101	CONTINUE	DM16	21
	COSPHI=COS(PHIF)	DM16	22
	SINPHI=SIN(PHIF)	DM16	23
104	CONTINUE	DM16	24
	YOUT=YIN*COSPHI+ZIN*SINPHI	DM16	25
	ZOUT=ZIN*COSPHI-YIN*SINPHI	DM16	26
	RETURN	DM16	27
C		DM16	28
C	FIN TO WING	DM16	29
C	ENTRY ROTFW	DM16	30
	IF (ABS(PHIF-PI02),LT,TLRNC) GO TO 102	DM16	31
	GO TO 103	DM16	32
102	COSPHI=0.0	DM16	33
	SINPHI=1.0	DM16	34
	GO TO 105	DM16	35
103	CONTINUE	DM16	36
	COSPHI=COS(PHIF)	DM16	37
	SINPHI=SIN(PHIF)	DM16	38
105	CONTINUE	DM16	39
	YOUT=YIN*COSPHI-ZIN*SINPHI	DM16	40
	ZOUT=ZIN*COSPHI+YIN*SINPHI	DM16	41
	RETURN	DM16	42
	END	DM16	43
		DM16	44
		DM16	45
		DM16	46
		DM16	47
		DM16	48
		DM16	49

	SUBROUTINE SOLVE (B,A,N)	DM17	1
C		DM17	2
C	VERSION: DEMON1	DM17	3
C		DM17	4
C		DM17	5
C	THIS SUBROUTINE TAKES IN THE TRIANGULATED MATRIX A, RIGHT HAND	DM17	6
C	SIDE VECTOR B, IT IS OPERATED ON BY IP(300)	DM17	7
C	SOLUTION THEN PROCEEDS, ANSWER IS IN VECTOR B AGAIN	DM17	8
C		DM17	9
C	DIMENSION B(1)	DM17	10
C	DIMENSION A(N,N)	DM17	11
C		DM17	12
C	LOGICAL ASYM,BODY,DELTA,NOSYM	DM17	13
C		DM17	14
C	COMMON/ONE/DUM1(6000),IP(300),DUM2(102),ALFR,DUM3(18),TOTLX,	DM17	15
C	1DUM4(21),NDRAG,DUM5(4),NOCPY,NOLIN,NOUT,NPANELS,NPRESS,N=BP,ASYM,	DM17	16
C	2BODY,DELTA,NOSYM	DM17	17
C		DM17	18
C		DM17	19
C	IF(N.EQ.1)GO TO 9	DM17	20
C	NM1=N-1	DM17	21
C	DO 7 K=1,NM1	DM17	22
C	KP1=K+1	DM17	23
C	M=IP(K)	DM17	24
C	T=B(M)	DM17	25
C	R(M)=B(K)	DM17	26
C	R(K)=T	DM17	27
C	DO 7 I=KP1,N	DM17	28
C	7. R(I)=B(I)+A(I,K)*T	DM17	29
C		DM17	30
C		DM17	31
C	DO 8 KR=1,NM1	DM17	32
C	KM1=N-KR	DM17	33
C	K=KM1+1	DM17	34
C	R(K)=R(K)/A(K,K)	DM17	35
C	T=R(K)	DM17	36
C	IF (T.EQ.0.0) GO TO 9	DM17	37
C	DO 8 I=1,KM1	DM17	38
C	8. R(I)=B(I)+A(I,K)*T	DM17	39
C	9. R(1)=B(1)/A(1,1)	DM17	40
C	RETURN	DM17	41
C	END	DM17	42
	SUBROUTINE SOURCE(J)	DM18	1
C	VERSION: DEMON	DM18	2
C		DM18	3
C	VERSION: DEMON1	DM18	4
C		DM18	5
C	SUBROUTINE TO CALCULATE THE VELOCITIES DUE TO A LINEAR LINE SOURCE OF	DM18	6
C	UNIT SLOPE WITH ORIGIN AT TX(J).	DM18	7
C	SOLUTIONS GIVEN BY WOODWARD AND LARSEN (HOING REPT. D6-10741), EQUATION	DM18	8
C	(53) OR ANTONIO FERRI, "ELEMENTS OF AERODYNAMICS OF SUPERSONIC FLOWS,"	DM18	9
C	EQUATION (374).	DM18	10
C		DM18	11
C	INTEGER RCODE	DM18	12
C	COMMON/TWO/TX(101),DUM1(1113),RCODE,BETASO,RSO,RADIUS,XFIELD,RNOSD	DM18	13
C	1,U,V,VY,XA,XC,XD,BETA,XFIELD,X2,XB,NXBODY	DM18	14
C		DM18	15
C		DM18	16
C	100 FORMAT(1H0,59HFIELD POINT IS WITHIN TAIL MACH CONE. U AND V SET TO	DM18	17

	10 ZERO,)	DM18	18
C		DM18	19
	X1=XFIELD-TX(J)	DM18	20
	NR=BETA*XFIELD	DM18	21
	IF(X1,LF,BW) GO TO 10	DM18	22
	IF(X2,LE,BR)GO TO 11	DM18	23
	WRITE(6,100)	DM18	24
	GO TO 10	DM18	25
	11 XL=X1/BR.	DM18	26
	D23= SQRT(XL*XL+1.)	DM18	27
	U=-ALOG(XL+D23)	DM18	28
	V=BETA*D23	DM18	29
	RETURN	DM18	30
C		DM18	31
C	FIELD POINT IS AHEAD OF MACH CONE FROM SOURCE ORIGIN.	DM18	32
C		DM18	33
	10 U=0.	DM18	34
	V=0.	DM18	35
	RETURN	DM18	36
	END	DM18	37
	SUBROUTINE SPECPR	DM19	1
C		DM19	2
C	VERSION: DEMON1	DM19	3
C		DM19	4
C	THIS SUBROUTINE COMPUTES BERNOULLI PRESSURES AT CONTROL POINTS	DM19	5
C	OF THE CONSTANT U-VELOCITY PANELS	DM19	6
C	ON THE WING OR FIN SURFACES	DM19	7
C		DM19	8
C		DM19	9
C		DM19	10
C	DIMENSION PRESSA(150),PRESSB(150),PRESSR(150),PRESSL(150)	DM19	11
C		DM19	12
C	LOGICAL BODY,ASYM,DELTA,NOSYM	DM19	13
C		DM19	14
C	COMMON/DNE/DUM1(250),DELTP(250),DUM2(1750),XCPT(250),YCPT(250),	DM19	15
	ZCPT(250),DUM3(3402),ALFR,ARWING,DUM4(2),BETA,BETAN,CONST,COSALF,	DM19	16
	2COSBET,CN,DX,EM,FMACH,RCIR,	DM19	17
	2 SINALF,SINBET,DUM5(3),TOTLR,DUM6(3),UCHK,	DM19	18
	3VCHK,WCHK,DUM7(4),J,IF,II,K,DUM8(4),NRIP,NCPX,NCW,NDRAG,NRP,NPR,	DM19	19
	4NRP,N3P,NOCPT,NOLINP,NOUT,NPANELS,NPRESS,NWRP,ASYM,BODY,DELTA,NOSYM	DM19	20
	COMMON/WVEL/BDU(150),BDV(150),BDW(150),XFLDP(150),YFLDP(150),	DM19	21
	1 ZFLDP(150)	DM19	22
	COMMON/SPCPRS/DLTP(150)	DM19	23
	COMMON/SPSANG/SINALC,COSALC,SINPHI,COSPHI	DM19	24
	COMMON/VRTXV/VVRTX(150),NVRTX(150),NVRTPL,NVRTX,VRTMAX	DM19	25
	COMMON/THKDAT/NTDAT,NCWT,NTPR,MSWT(4),NRPT,NHPT,N3PT,NTHP,ASYMT,	DM19	26
	1 NVERT,SWLET(20,4),SWTET(20,4),YTH(20,4),THETA(400)	DM19	27
	COMMON/ICVEL/UTCHK,VTCHK,ATCHK,IIT,IFT,MJ	DM19	28
	COMMON/VPTHVL/VVEL(500),WVEL(500),JCPT,NCPDUT,NVLIN	DM19	29
	COMMON /ELLIPS/ RA,WB,ERATIO	DM19	30
C		DM19	31
C		DM19	32
C		DM19	33
	720 FORMAT(1X,I3,11F11.6)	DM19	34
	721 FORMAT(1X,I3,6F11.6,11X,3F11.6)	DM19	35
	732 FORMAT(///10X,104HVELOCITIES AND BERNOULLI PRESSURES AT CONTROL	DM19	36
	POINTS IMMEDIATELY ABOVE AND BELOW HORIZONTAL WING SURFACE//	DM19	37
	22X,1HJ,6X,4HX(J),7X,4HY(J),7X,4HZ(J),5X,5HJOTA,6X,5HVTOTA,	DM19	38
	36X,5HWTOTA,6X,6HPRESSA,5X,5HWTOTB,6X,5HVTOTB,6X,5HWTOTB,	DM19	39
	46X,6HPRESSB//)	DM19	40

```

754 FORMAT(////10X,107HVELOCITIES AND BERNOULLI PRESSURES AT CONTROL PDM19 41
POINTS IMMEDIATELY TO RIGHT AND LEFT OF VERTICAL WING SURFACE// DM19 42
22X,1HJ,6X,4HX(J),7X,4HY(J),7X,4HZ(J),5X,5HVTOTR,6X,5HVTOTL, DM19 43
36X,5HWTOTR,6X,6HPPRESSR,5X,5HWTOTL,6X,5HVTOTL,6X,5HWTOTL,6X, DM19 44
46HPPRESSL/) DM19 45
736 FORMAT(////3X,35HPPRESSURE LOADINGS AT CONTROL POINTS// DM19 46
1 2X,1HJ,7X,4HX(J),7X,4HY(J),7X,4HZ(J),4X,10HDELTP,LIN.,1X, DM19 47
2 11HDELTP,HERN,/) DM19 48
737 FORMAT(1H1,77HPPRESSURE LOADINGS EXCLUDE VORTEX INDUCED COMPONENTS DM19 49
1 PARALLEL TO WING SURFACES//) DM19 50
738 FORMAT(1H1,77HPPRESSURE LOADINGS INCLUDE VORTEX INDUCED COMPONENTS DM19 51
1 PARALLEL TO WING SURFACES//) DM19 52
C DM19 53
C DM19 54
C DM19 55
C DM19 56
C DM19 57
C DM19 58
C DM19 59
C DM19 60
C DM19 61
C DM19 62
C DM19 63
C DM19 64
C DM19 65
C DM19 66
C DM19 67
C DM19 68
C DM19 69
C DM19 70
C DM19 71
C DM19 72
C DM19 73
C DM19 74
C DM19 75
C DM19 76
C DM19 77
C DM19 78
C DM19 79
C DM19 80
C DM19 81
C DM19 82
C DM19 83
C DM19 84
C DM19 85
C DM19 86
C DM19 87
C DM19 88
C DM19 89
C DM19 90
C DM19 91
C DM19 92
C DM19 93
C DM19 94
C DM19 95
C DM19 96
C DM19 97
C DM19 98
C DM19 99
C DM19 100
C DM19 101
C DM19 102
C DM19 103

```

	I VTOTA, WTOTA	DM19 104
C	CONTINUOUS CONTRIBUTION FROM HORIZONTAL FINS	DM19 105
C		DM19 106
C		DM19 107
	II=1	DM19 108
	IF=NHMP	DM19 109
	CALL VELNDR(XCPT(K),YCPT(K),ZCPT(K))	DM19 110
	VTOTA=VTOTA+VCHK	DM19 111
	WTOTA=WTOTA+WCHK	DM19 112
	IF (NOUT.NE.0)	DM19 113
	WRITE (6,721) K, XCPT(K), YCPT(K), ZCPT(K), UTOTA, VTOTA, WTOTA, UTOTB,	DM19 114
	I VTOTB, WTOTB	DM19 115
	IF (NHMP.EQ.NHBP) GO TO 801	DM19 116
C		DM19 117
C	CONTRIBUTION FROM VERTICAL FINS AND BODY INTERFERENCE PANELS.	DM19 118
C		DM19 119
	II=NHMP	DM19 120
	IF=NHBP	DM19 121
	CALL VELNDR(XCPT(K),YCPT(K),ZCPT(K))	DM19 122
	UTOTA=UTOTA+UCHK	DM19 123
	VTOTA=VTOTA+VCHK	DM19 124
	WTOTA=WTOTA+WCHK	DM19 125
C		DM19 126
	UTOTB=UTOTB+UCHK	DM19 127
	VTOTB=VTOTB+VCHK	DM19 128
	WTOTB=WTOTB+WCHK	DM19 129
	IF (NOUT.NE.0)	DM19 130
	WRITE (6,721) K, XCPT(K), YCPT(K), ZCPT(K), UTOTA, VTOTA, WTOTA, UTOTB,	DM19 131
	I VTOTB, WTOTB	DM19 132
	801 CONTINUE	DM19 133
C		DM19 134
C	SOURCE PANEL CONTRIBUTION	DM19 135
C		DM19 136
	IF (NTOAT.EQ.0) GO TO 830	DM19 137
	III=1	DM19 138
	IFT=NHMP	DM19 139
	M=JK	DM19 140
	CALL THKVEL(XCPT(K),YCPT(K),ZCPT(K))	DM19 141
	UTOTA=UTOTA+UTCHK	DM19 142
	VTOTA=VTOTA+VTCHK	DM19 143
	WTOTA=WTOTA+WTCHK	DM19 144
	UTOTB=UTOTB+UTCHK	DM19 145
	VTOTB=VTOTB+VTCHK	DM19 146
	WTOTB=WTOTB+WTCHK	DM19 147
	IF (NOUT.NE.0)	DM19 148
	WRITE (6,721) K, XCPT(K), YCPT(K), ZCPT(K), UTOTA, VTOTA, WTOTA, UTOTB,	DM19 149
	I VTOTB, WTOTB	DM19 150
	830 CONTINUE	DM19 151
C		DM19 152
	HDUSQ=UTOTA*UTOTA	DM19 153
	HDSQ=VTOTA*VTOTA	DM19 154
	HDSQ=WTOTA*WTOTA	DM19 155
	UHAR=UTOTA*COSALC=VTOTA*SINHET+WTOTA*SINALF	DM19 156
	ARG=1, 0=FACTR2*(2, 0+UHAR+HDUSQ+HDSQ+HDSQ)	DM19 157
	PRESSA(K)=FACTH1	DM19 158
	IF (ARG.GE.1) PRESSA(K)=FACTH1*(ARG+3,5=1,0)	DM19 159
	HDUSQ=UTOTB*UTOTB	DM19 160
	HDSQ=VTOTB*VTOTB	DM19 161
	HDSQ=WTOTB*WTOTB	DM19 162
	UHAR=UTOTB*COSALC=VTOTB*SINHET+WTOTB*SINALF	DM19 163
	ARG=1, 0=FACTR2*(2, 0+UHAR+HDUSQ+HDSQ+HDSQ)	DM19 164
	PRESSA(K)=FACTH1	DM19 165
	IF (ARG.GE.1) PRESSA(K)=FACTH1*(ARG+3,5=1,0)	DM19 166

```

      WRITE (6,720) K, XCPT(K), YCPT(K), ZCPT(K), UTOTA, VTOTA, WTOTA,
1      PRESSA(K), UTOTh, VTOTH, WTOTh, PRESSB(K)
      807 CONTINUE
C
C   POINTS IMMEDIATELY TO THE RIGHT AND THE LEFT OF VERTICAL
C   WING SURFACE TREATED SEPARATELY DUE TO DISCONTINUITY IN
C   INFLUENCE FUNCTIONS WHEN Y EQUALS ZERO.
C   ADD IN CONTRIBUTIONS FROM EXTERNAL VORTICES.
C
C
C   IF (NCRX.EQ.0) GO TO 841
      WRITE (6,734)
C
C
      DO 808 J=NHPI, NPNLS
      XFLOP(J)=XCPT(J)
      YFLOP(J)=YCPT(J)
      808 ZFLOP(J)=ZCPT(J)
      NSTART=NHPI
C
      IF (HODY.AND.RA.EQ.NH) CALL VELCAL(NPNLS,ALFR,HETAR,NSTART)
      DO 813 K=NHPI, NPNLS
      WADVRT=VVRTX(K)
      IF (NVRTX.NE.0.AND.NVRTPL.EQ.0) WADVRT=0.0
C
      II=K
      IF=K
      CALL VELCOR(XCPT(K),YCPT(K),ZCPT(K))
      UTOTR=UCHK+BDU(K)
      VTOTR=BDV(K)+VVRTX(K)+VVEL(K)
      WTOTR=CHK+BDW(K)+WADVRT+WVEL(K)
      UTOTL=UCHK+BDU(K)
      VTOTL=BDV(K)+VVRTX(K)+VVEL(K)
      WTOTL=CHK+BDW(K)+WADVRT+WVEL(K)
      IF (NOUT.NE.0)
1      WRITE (6,721) K, XCPT(K), YCPT(K), ZCPT(K), UTOTR, VTOTR, WTOTR, UTOTL,
1      VTOTL, WTOTL
C
      II=NHPI
      IF=NPNLS
      CALL VELCOR(XCPT(K),YCPT(K),ZCPT(K))
      VTOTR=VTOTR+VCHK
      VTOTL=VTOTL+VCHK
      IF (NOUT.NE.0)
1      WRITE (6,721) K, XCPT(K), YCPT(K), ZCPT(K), UTOTR, VTOTR, WTOTR, UTOTL,
1      VTOTL, WTOTL
C
      II=1
      IF=NHPI
      CALL VELCOR(XCPT(K),YCPT(K),ZCPT(K))
      UTOTR=UTOTR+UCHK
      VTOTR=VTOTR+VCHK
      WTOTR=WTOTR+CHK
      UTOTL=UTOTL+UCHK
      VTOTL=VTOTL+VCHK
      WTOTL=WTOTL+CHK
      IF (NOUT.NE.0)
1      WRITE (6,721) K, XCPT(K), YCPT(K), ZCPT(K), UTOTR, VTOTR, WTOTR, UTOTL,
1      VTOTL, WTOTL
C
      IF (NPNLS.EQ.NHPI) GO TO 803
      II=NPNLS1
      IF=NHPI
      CALL VELCOR(XCPT(K),YCPT(K),ZCPT(K))

```

```

DM19 167
DM19 168
DM19 169
DM19 170
DM19 171
DM19 172
DM19 173
DM19 174
DM19 175
DM19 176
DM19 177
DM19 178
DM19 179
DM19 180
DM19 181
DM19 182
DM19 183
DM19 184
DM19 185
DM19 186
DM19 187
DM19 188
DM19 189
DM19 190
DM19 191
DM19 192
DM19 193
DM19 194
DM19 195
DM19 196
DM19 197
DM19 198
DM19 199
DM19 200
DM19 201
DM19 202
DM19 203
DM19 204
DM19 205
DM19 206
DM19 207
DM19 208
DM19 209
DM19 210
DM19 211
DM19 212
DM19 213
DM19 214
DM19 215
DM19 216
DM19 217
DM19 218
DM19 219
DM19 220
DM19 221
DM19 222
DM19 223
DM19 224
DM19 225
DM19 226
DM19 227
DM19 228
DM19 229
DM19 230

```

```

      UTOTR=UTOTR+UCHK
      VTOTR=VTOTR+VCHK
      WTOTR=WTOTR+WCHK
      UTOTL=UTOTL+UCHK
      VTOTL=VTOTL+VCHK
      WTOTL=WTOTL+WCHK
C
      IF (NOUT.NE.0)
      IWRITE (6,721) K,XCPT(K),YCPT(K),ZCPT(K),UTOTR,VTOTR,WTOTR,UTOTL,
      I VTOTL,WTOTL
      805 CONTINUE
C
      SOURCE PANEL CONTRIBUTION
C
      IF (NTOAT.EQ.0) GO TO 835
      NJ=K
      CALL THKVEL(XCPT(K),YCPT(K),ZCPT(K))
      UTOTR=UTOTR+UTCHK
      VTOTR=VTOTR+VTCHK
      WTOTR=WTOTR+WTCHK
      UTOTL=UTOTL+UTCHK
      VTOTL=VTOTL+VTCHK
      WTOTL=WTOTL+WTCHK
      IF (NOUT.NE.0)
      IWRITE (6,721) K,XCPT(K),YCPT(K),ZCPT(K),UTOTR,VTOTR,WTOTR,UTOTL,
      I VTOTL,WTOTL
      835 CONTINUE
C
      HDUSQ=UTOTR*UTOTR
      HDVSO=VTOTR*VTOTR
      HDWSQ=WTOTR*WTOTR
      USAR=UTOTR*COSALC=VTOTR*SINNET+WTOTR*SINALF
      ARG1,0=FACTR2*(2,0*(UHAR+HDUSQ+HDVSO)+HDWSQ)
      PRESSR(K)=FACTR1
      IF (ARG.GE,10TLR)PRESSR(K)=FACTR1*(ARG**3,5=1,0)
      HDVSO=UTOTL*UTOTL
      HDVSO=VTOTL*VTOTL
      HDWSQ=WTOTL*WTOTL
      UHAR=UTOTL*COSALC=VTOTL*SINNET+WTOTL*SINALF
      ARG1,0=FACTR2*(2,0*(UHAR+HDUSQ+HDVSO)+HDWSQ)
      PRESSL(K)=FACTR1
      IF (ARG.GE,10TLR)PRESSL(K)=FACTR1*(ARG**3,5=1,0)
      IWRITE (6,720) K,XCPT(K),YCPT(K),ZCPT(K),UTOTR,VTOTR,WTOTR,
      I PRESSR(K),UTOTL,VTOTL,WTOTL,PRESSL(K)
      815 CONTINUE
C
      CALCULATE PRESSURE DIFFERENCES AT CONTROL POINTS
C
      801 CONTINUE
      WRITE (6,736)
      DO A21 K=1,NPANELS
      IF (K.LE,NMP) GO TO 822
      GO TO 823
      822 DLTP(K)=PRESSR(K)-PRESSA(K)
      GO TO 824
      823 DLTP(K)=PRESSL(K)-PRESSL(K)
      824 CONTINUE
      821 IWRITE (6,720) K,XCPT(K),YCPT(K),ZCPT(K),DLTP(K),DLTP(K)
C
      CALCULATE WING LOADINGS DUE TO BERNOULLI LOADING PRESSURES
      WPRESS=1

```

```

DM19 231
DM19 232
DM19 233
DM19 234
DM19 235
DM19 236
DM19 237
DM19 238
DM19 239
DM19 240
DM19 241
DM19 242
DM19 243
DM19 244
DM19 245
DM19 246
DM19 247
DM19 248
DM19 249
DM19 250
DM19 251
DM19 252
DM19 253
DM19 254
DM19 255
DM19 256
DM19 257
DM19 258
DM19 259
DM19 260
DM19 261
DM19 262
DM19 263
DM19 264
DM19 265
DM19 266
DM19 267
DM19 268
DM19 269
DM19 270
DM19 271
DM19 272
DM19 273
DM19 274
DM19 275
DM19 276
DM19 277
DM19 278
DM19 279
DM19 280
DM19 281
DM19 282
DM19 283
DM19 284
DM19 285
DM19 286
DM19 287
DM19 288
DM19 289
DM19 290
DM19 291
DM19 292
DM19 293

```


C	CALL SPECLO	DM19 294
C		DM19 295
	RETURN	DM19 296
	END	DM19 297
		DM19 298
C	SUBROUTINE SPNLD	DM20 1
C		DM20 2
C	VERSION: DEMON1	DM20 3
C		DM20 4
C	THIS SUBROUTINE COMPUTES SPAN LOAD DISTRIBUTIONS	DM20 5
C	THIS SUBROUTINE COMPUTES SPAN LOAD DISTRIBUTIONS FOR MONOPLANE	DM20 6
C	OR CRUCIFORM WING OR FIN CONFIGURATIONS ONLY.	DM20 7
C	NOTE: INTERDIGITATED FINS PRESENTLY EXCLUDED.	DM20 8
C	ALSO ADDITIONAL IN-PLANE FORCES, FY2, FZ2,	DM20 9
C	AND SUCTION DISTRIBUTIONS ALONG THE LEADING EDGE AND SIDE EDGE.	DM20 10
C	USING THIS INFORMATION, FIN LEADING AND SIDE EDGE VORTICITY	DM20 11
C	DISTRIBUTIONS ARE CALCULATED.	DM20 12
C	IN ADDITION, FIN TRAILING EDGE VORTEX STRENGTH AND SPANWISE	DM20 13
C	LOCATION ARE DETERMINED FROM THE LOAD DISTRIBUTIONS.	DM20 14
C		DM20 15
	DIMENSION SLOAD (20), CHORDS(150), FY2(150), FZ2(150), FT2(20),	DM20 16
	1 YCG(20), ZCG(20), VALMAX(5), YMAX(5), VALNUM(5), ZMAX(5), SLP(20),	DM20 17
	2 CIRNET(80), GAMMA(20)	DM20 18
C		DM20 19
C	LOGICAL ASYM, ANYMO, SSLE	DM20 20
		DM20 21
	COMMON/ONE/CIRC(250), DELTP(250), FN(250), PNLC(250), SWPPLE(250),	DM20 22
	19*PPTF(250), VNOR(250), XHAR(250), ZHAR(250), XCPT(250), YCPT(250), ZCPT(250)	DM20 23
	2(250), XLF(250), XLH(250), XRF(250), XHH(250), VIC(250), YRC(250), ZLF(250)	DM20 24
	30), ZRF(250), ZLH(250), ZRH(250), SYT(125), CST(125), SYT2(125), CST2(125)	DM20 25
	4), IP(300), XFHIP(100), A, ALFA, ALFR, ANGLE, B2, P2V, BETA, BETAR, CONST,	DM20 26
	5COSALF, COSBET, CN, CX, CY, FMACH, RCIR, SINALF, SINBET, SLOPF, TIRNC, TIPY,	DM20 27
	6TTLR, U, V, W, UCHK, VCHK, WCHK, XHIP, X, Y, Z, I, IF, II, III, VSAR, SWL, SWU,	DM20 28
	7HSD, NRIP, NCRX, NCW, NDRA, NHP, NRP, NRP, NRP, NRP, NRP, NRP, NRP, NRP,	DM20 29
	8NPPSS, NRRP, ASYM, MODY, DELTA, NDSYM	DM20 30
	COMMON/THREE/ANGLR, ANGLL, ANGLU, ANGLD, DELR, DELL, DELU, DELD, SHEF, REFL	DM20 31
	COMMON/SIX/FEPS/VSLEL(20), VSWTER(20), VSLEL(20), VSWTEL(20),	DM20 32
	1 VSWLEU(20), VSWTEU(20), VSWLED(20), VSWTED(20), LVSWP, LEFT, FAC, NCWH	DM20 33
	2, ARPNL(250), WIDTH(250)	DM20 34
	COMMON/FRCDIS/VNOR03(150), FX(150), FY(150), FZ(150), DLTPO(150), ANYMO	DM20 35
	COMMON/VRTX/VVRTX(150), WVTX(150), NVRTPL, NVRTX, VRTMAX	DM20 36
	COMMON/VPTHVL/VVEL(500), WVEL(500), JCPT, VCPOUT, NVLIN	DM20 37
	COMMON/FINLE/XLE(80), CGLOC(80), GAMLE(80), FK(8), NEOGV, MLEVU, MLEVL,	DM20 38
	1 MLEVU, MLEVD	DM20 39
	COMMON/FINSE/XSE(80), CGSELC(80), GAMSE(80), FXSE, NSIDGE, NSEV	DM20 40
	COMMON/ELLIPSWA, PB, EQATIO	DM20 41
		DM20 42
C		DM20 43
C	702 FORMAT(////1X, 22HSPANWISE DISTRIBUTIONS//)	DM20 44
	703 FORMAT (2X, I2, 2X, 8(F10.5, 2X), F10.5, 1X, 2(F10.5)	DM20 45
	704 FORMAT (2X, I2, 2X, F10.5, 2X, F10.5, 74X, F10.5)	DM20 46
	706 FORMAT (1X, I3, 2(1X, F10.5), 5(2X, F10.5))	DM20 47
	707 FORMAT (////10X, 22HSIDE EDGE DISTRIBUTION//2X, 4HJTIP, 2X,	DM20 48
	1 3HJSE, 2X, 8HDISTANCE, 7X, 13HSUCTION FORCE, 7X, 8HGAMMA, SE, 6X,	DM20 49
	2 4HZHAR, 7X, 3HJSE/13X, 7HFROM LE, 8X, 15HPPR UNIT LENGTH, 5X,	DM20 50
	3 5H/VIN/13X, 9H/TIPCHORD, 6X, 13H/(J*IPCHORD))	DM20 51
	708 FORMAT (////10X, 22HSIDE EDGE DISTRIBUTION//2X, 4HJTIP, 2X,	DM20 52
	1 3HJSE, 2X, 8HDISTANCE, 7X, 13HSUCTION FORCE, 7X, 8HGAMMA, SF, 6X,	DM20 53
	2 4HYZHAR, 7X, 3HJSE/13X, 7HFROM LE, 8X, 15HPPR UNIT LENGTH, 5X,	DM20 54

```

3 5H/VINF/13X,9H/TIPCHORD,6X,13H/(Q*TIPOHORD1/)           D*20 55
700 FORMAT (3X,I2,4X,I2,1X,F10.5,6X,F10.5,6X,F10.5,4X,F10.5,1X,F10.5) D*20 56
710 FORMAT (1X,I5,9(1X,F10.5))                               D*20 57
712 FORMAT (////)                                           D*20 58
1 10X,9HSUMFX = ,E12.5,/10X,9HSUMFY1 = ,E12.5,/10X,9HSUMFY2 = , D*20 59
1E12.5,/10X,9HSUMFZ2 = ,E12.5)                             D*20 60
721 FORMAT(14I,20(1H=),410,2(1H=))                          D*20 61
723 FORMAT( 3X,14I,5X,7HZ/(H/2),2X,10HCN*C/(2*B),2X,10HCT*C/(2*B), D*20 62
1 1X,11HCZ1*C/(2*B),1X,13HCZTOT*C/(2*B),1X,10HCS*C/(2*B),5X, D*20 63
2 5HCSINT,5X,4HCHAR,7X,9HGAMMET(I),2X,13HGAMMA,LE/VINF,2X,3HXLE/) D*20 64
724 FORMAT( 3X,14I,5X,7HY/(H/2),2X,10HCN*C/(2*B),2X,10HCT*C/(2*B), D*20 65
1 1X,11HCY1*C/(2*B),1X,13HCYTOT*C/(2*B) ,1X,10HCS*C/(2*B),5X, D*20 66
2 5HCSINT,5X,4HYHAR,7X,9HGAMMET(I),2X,13HGAMMA,LE/VINF,2X,3HXLE/) D*20 67
731 FORMAT (////10X,9HSUMFX = ,E12.5/10X,9HSUMFZ1 = ,E12.5/10X, D*20 68
1 9HSUMFZ2 = ,E12.5/10X,9HSUMFZ2 = ,E12.5/) D*20 69
733 FORMAT (////,25X,17H*ING PANEL FORCES//2X,14J,5X,7HZCPT(J),3X, D*20 70
1 8HDELTA=CP,6X,6HGAMMA/,6X,2HFX,10X,3HFY1, 9X,3HFY2/ D*20 71
2 32X,4HVINF,/) D*20 72
734 FORMAT (//8X,14I,3X,3HDLT,6X,3HSLP,4X,4HISFO,3X,4HZCHK,5X, D*20 73
1 6HVALINT,1X,4HNUM=,3X,6HVALMAX,3X,6HVALNUM,5X,4HZMAX/51X,3HEXT) D*20 74
735 FORMAT (/7X,I2,2(1X,FR,4),2X,I2,1X,2(1X,FR,4),2X,I2,1X, D*20 75
1 3(1X,FR,4)/) D*20 76
736 FORMAT (////30H*****T,E, FIN VORTEX INFO*****/) D*20 77
738 FORMAT (1X,4HIVRT,1X,10HGAMMA/VINF,3X,6HY,C.G./) D*20 78
739 FORMAT (////25X,17H*ING PANEL FORCES//2X,14J,5X,7HZCPT(J),,3X, D*20 79
1 8HDELTA=CP,6X,6HGAMMA/,5X,2HFX,10X,3HFZ1,10X,3HFZ2,/ D*20 80
2 18X,4HIVIN,10X,4HVINF,/) D*20 81
742 FORMAT (1X,4HIVRT,1X,10HGAMMA/VINF,5X,6HZ,C.G./) D*20 82
743 FORMAT (//8X,14I,3X,3HDLT,6X,3HSLP,4X,4HISFO,3X,4HZCHK,5X, D*20 83
1 6HVALINT,1X,4HNUM=,3X,6HVALMAX,3X,6HVALNUM,5X,4HZMAX/51X,3HEXT) D*20 84
C DATA ARW/10HRIGHT WING/,ALW/10H LEFT WING/,ALUW/10HUPPER WING/, D*20 85
C 1 ADW/10HLOWER WING/ D*20 86
C INITIALIZE D*20 87
C D*20 88
C D*20 89
C DQ 905 I=1,40 D*20 90
C 903 CIRNET(I)=0.0 D*20 91
C D*20 92
C D*20 93
C D*20 94
C CALCULATE SPANWISE LOAD DISTRIBUTIONS D*20 95
C D*20 96
C MSWRP=MSWR+1 D*20 97
C MSWLP=MSWL+1 D*20 98
C MSWUP=MSWU+1 D*20 99
C MSWOP=MSWO+1 D*20 100
C CFC=1.0/(4.0*B2) D*20 101
C T*OB=4.0*B2 D*20 102
C ARG TAN=1.0/BETA D*20 103
C ANGMCH=(ATAN(ARGTAN))*57.2957795 D*20 104
C PSIMCH=90.0-ANGMCH D*20 105
C D*20 106
C LOOP 542 IS FOR RIGHT AND LEFT HORIZONTAL FINS D*20 107
C D*20 108
C HT=1.0/HZ D*20 109
C WRITE(6,721) ARW D*20 110
C WRITE(6,702) D*20 111
C WRITE(6,724) D*20 112
C J=1 D*20 113
C TL=0 D*20 114
C ANGL=ANGLR D*20 115
C SINANG=9*(N(ANGL) D*20 116
C COSANG=COS(ANGL) D*20 117

```

	NSPANP=MSWRP	DM20 119
	SIGN=+1.0	DM20 119
	KUL=MSWRP	DM20 120
	.ISTART=1	DM20 121
	JEND=NRP	DM20 122
	JTIP=NRP-N(C+1	DM20 123
	TIPCH=XRHB(NRP)-XRF(JTIP)	DM20 124
	IVRT=0	DM20 125
	IFV=0	DM20 126
540	CONTINUE	DM20 127
	CIRNET(NSPANP)=0.0	DM20 128
	I=0	DM20 129
C		DM20 130
C		DM20 131
	SUMFX=0.0	DM20 132
	SUMFY1=0.0	DM20 133
	SUMFY2=0.0	DM20 134
	SUMFT2=0.0	DM20 135
C		DM20 136
C		DM20 137
	SLP(1)=0.0	DM20 138
	DLT=0.	DM20 139
	VALINT=0.0	DM20 140
	CSINT=0.0	DM20 141
	CSMOM=0.0	DM20 142
	NUMEXT=0	DM20 143
	ISEQ=0	DM20 144
	NDEXT=0	DM20 145
C		DM20 146
C	ALL CIRNET ARE POSITIVE IN THE COUNTER CLOCKWISE DIRECTION LOOKING	DM20 147
C	FORWARD	DM20 148
C	NOTE: IN PLANE FORCE FY2 ACTS ON OUTBOARD AFT CORNER OF EACH PANEL.	DM20 149
C	HERE: IL=0.....RIGHT FIN	DM20 150
C	IL=1.....LEFT FIN	DM20 151
C		DM20 152
	DD 542 K=2,KUL	DM20 153
	I=I+1	DM20 154
	IFV=IFV+1	DM20 155
	SCSMX=0.0	DM20 156
	SCSMY1=0.0	DM20 157
	SCSMY2=0.0	DM20 158
	SWPANG=ABS(ATAN(SWPPL(E(J))))	DM20 159
	COSSWP=COS(SWPANG)	DM20 160
	PSIPLE=SWPANG*57.2957795	DM20 161
	SSLE=PSIPCH.GT.PSIPLE	DM20 162
	SUM1=0.0	DM20 163
	YCHK=YCPT(J)+COSMET-XHAR(J)*SINBET	DM20 164
	IF (ANYMO) YCHK#YCPT(I)	DM20 165
	YLOC=YCHK*HTW	DM20 166
	IP1=I+1	DM20 167
	IF (TL.EQ.1) GO TO 460	DM20 168
	NFRST=1	DM20 169
	ISPN=IP1	DM20 170
	IC=I	DM20 171
	XLE(IFV)=XLF(J)+(YCPT(J)-YLC(J))*SWPPL(E(J))	DM20 172
	GO TO 461	DM20 173
460	NFRST=MSWRP+1	DM20 174
	ISPN=IP1+MSWRP	DM20 175
	IC=I+MSWRP	DM20 176
	XLE(IFV)=XHF(J)+(YCPT(J)-YHC(J))*SWPPL(E(J))	DM20 177
461	CONTINUE	DM20 178
	CIRNET(ISPN)=0.0	DM20 179
	DD 541 L=1,MC	DM20 180

	SUM1=SUM1+FN(J)	DM20 181
	*IDI=1./WIDTH(J)	DM20 182
	IF (I.NE.1) GO TO 812	DM20 183
	CIRNET(NFRST)=CIRNET(NFRST)-CIRC(J)*SIGN	DM20 184
812	JADJ=J+NC*	DM20 185
	IF (K.EQ.KUL) GO TO 916	DM20 186
	GO TO 917	DM20 187
916	CIRNET(NSPANP)=CIRNET(NSPANP)+CIRC(J)*SIGN	DM20 188
	GO TO 813	DM20 189
917	CIRNET(ISPN)=CIRNET(ISPN)+(CIRC(J)-CIRC(JADJ))*SIGN	DM20 190
813	CONTINUE	DM20 191
	IF (NDRAG.EQ.0) GO TO 815	DM20 192
	IF (IL.EQ.1) GO TO 440	DM20 193
	CHORDS(J)=XRB(J)-XRF(J)	DM20 194
	GO TO 441	DM20 195
440	CHORDS(J)=XLB(J)-XLF(J)	DM20 196
441	CONTINUE	DM20 197
	IF (L.EQ.NC*) CHORDS(J)=0.5*CHORDS(J)	DM20 198
	FY2(J)=2.0*CHORDS(J)*CIRNET(ISPN)*(SINANG+VNDROS(J))	DM20 199
	IF (FX(J).LT.0.0.(R.SSLE)) GO TO 818	DM20 200
	SCSMX=SCSMX+FX(J)	DM20 201
	SCSMY1=SCSMY1+FY(J)	DM20 202
818	CONTINUE	DM20 203
	IF (K.EQ.KUL) GO TO 816	DM20 204
	SCSMY2=SCSMY2+FY2(J)	DM20 205
	GO TO 815	DM20 206
816	FT2(L)=FY2(J)	DM20 207
	SUMFT2=SUMFT2+FT2(L)	DM20 208
815	CONTINUE	DM20 209
C		DM20 210
C	WIDTH(J) IS PANEL SPANWISE DIMENSION, ALWAYS POSITIVE.	DM20 211
C	IT IS CALCULATED IN SUBROUTINE LAYOUT.	DM20 212
C		DM20 213
501	J=J+1	DM20 214
	DELY=WIDTH(J-1)	DM20 215
	SUMFX=SUMFX+SCSMX	DM20 216
	SUMFY1=SUMFY1+SCSMY1	DM20 217
	SUMFY2=SUMFY2+SCSMY2	DM20 218
	FACTOR=*IDI*CFC	DM20 219
C		DM20 220
C	SLOAD,...,CNC/2R,SECFXX,...,CIC/1H,SECFY,...,CYC/2R,SECFY2,...,CY(TOT)	DM20 221
C	/2R,SECSUC,...,CSC/2R	DM20 222
C	VALINT.....ACCUMULATED VALUE OF THE INTEGRAL (CNC/2R)*DELY OVER	DM20 223
C	THE SPANWISE DIRECTION.	DM20 224
C	CSINT.....ACCUMULATED VALUE OF THE INTEGRAL (CSC/2R)*DELY OVER	DM20 225
C	THE SPANWISE DIRECTION.	DM20 226
C		DM20 227
	SLOAD(I)=SUM1*WIDI*CFC	DM20 228
	VALINT=VALINT+(SLOAD(I)*DELY)	DM20 229
	IF (NDRAG.NE.0) GO TO 562	DM20 230
	WRITE (6,703) IC,YLOC,SLOAD(I),CIRNET(IC)	DM20 231
	IF (K.NE.KUL) GO TO 542	DM20 232
	YLOC=((H2+RH)/B2)*SIGN	DM20 233
	SLOTIP=0.0	DM20 234
	WRITE (6,704) NSPANP,YLOC,SLOTIP,CIRNET(NSPANP)	DM20 235
	GO TO 542	DM20 236
562	CONTINUE	DM20 237
	IF (SSLE) GO TO 551	DM20 238
	SECFXX=SCSMX*FACTOR	DM20 239
	SECFY=SCSMY1*FACTOR	DM20 240
	SECFY2=(SCSMY2+SCSMY1)*FACTOR	DM20 241
	SECSUC=SECFXX/COSSAP	DM20 242
	CSINT=CSINT+(SECSUC*DELY)	DM20 243

	CNSOM=CNSOM+ABS(YCHK*SECSUC*DELY)	DM20 244
	CGLOC(IFV)=(CNSOM/CSINT)*SIGN	DM20 245
	YEXP=CGLOC(IFV)=(RH*SIGN)	DM20 246
	GAMLE(IFV)=FALE*((CSINT+T*OH)/(2.0*YEXP))*COSANG	DM20 247
	GO TO 552	DM20 248
551	SECFXX=0.0	DM20 249
	SECFY=0.0	DM20 250
	SECFY2=SCSMY2*FACTOR	DM20 251
	SECSUC=0.0	DM20 252
	CGLOC(IFV)=0.0	DM20 253
	GAMLE(IFV)=0.0	DM20 254
552	CONTINUE	DM20 255
	WRITE (6,703) IC,YLOC,SLOAD(I),SECFXX,SECFY,SECFY2,SECSUC,CSINT,	DM20 256
	CGLOC(IFV),CIRNET(IC),GAMLE(IFV),XLE(IFV)	DM20 257
	IF (K,NE,KUL) GO TO 525	DM20 258
	YLOC=(R2+R3)/R2)*SIGN	DM20 259
	SLOTIP=0.0	DM20 260
	WRITE (6,704) NSPANP,YLOC,SLOTIP,CIRNET(NSPANP)	DM20 261
525	CONTINUE	DM20 262
	IF (I.EQ.1) GO TO 645	DM20 263
	IM1=I-1	DM20 264
	DLT=ABS(YCHK-YCHKBF)	DM20 265
	SLP(I)=(SLOAD(I)-SLOAD(IM1))/DLT	DM20 266
	REFSLP=ABS(SLOAD(I)/(10.0*R2))	DM20 267
	IF (ABS(SLP(I)),LE,REFSLP) SLP(I)=0.0	DM20 268
	IF (I.EQ.2) GO TO 646	DM20 269
	IF (K,EQ,KUL) GO TO 521	DM20 270
	GO TO 522	DM20 271
521	SLP(NSPANP)=SLOAD(I)/(DLT/2.0)	DM20 272
	IF (ABS(SLP(NSPANP)),LE,REFSLP) GO TO 646	DM20 273
	SLPCHK=SLP(I)	DM20 274
	IF (SLPCHK,EQ,0.0) SLPCHK=SLP(I-1)	DM20 275
	IF (SLPCHK,GT,0.0,AND,SLP(NSPANP),LT,0.0) GO TO 645	DM20 276
	IF (SLPCHK,LT,0.0,AND,SLP(NSPANP),GT,0.0) GO TO 643	DM20 277
522	CONTINUE	DM20 278
	IF (SLP(I),EQ,0.0) GO TO 646	DM20 279
	IF (SLPHF,EQ,0.0,AND,I,GE,4) SLPHF=SLP(I-2)	DM20 280
	IF (SLPHF,GT,0.0,AND,SLP(I),LT,0.0) GO TO 643	DM20 281
	IF (SLPHF,LT,0.0,AND,SLP(I),GT,0.0) GO TO 643	DM20 282
	GO TO 646	DM20 283
C		DM20 284
C	VALMAX IS THE EXTREME VALUE OF CNC/2R	DM20 285
C	ITS VALUE IS TAKEN EQUAL TO THE (I-1)TH VALUE OF CNC/2B	DM20 286
C	LIKE=ISE YMAX	DM20 287
C	VALMAX(1) IS THE VALUE OF CNC/2R NEAREST THE ROOT	DM20 288
C		DM20 289
643	NUMEXT=NUMEXT+1	DM20 290
	ISEQ=NUMEXT+1	DM20 291
	VALMAX(1)=SLOAD(I)	DM20 292
	YMAX(1)=RH*SIGN	DM20 293
	VALMAX(ISEQ)=SLOAD(IM1)	DM20 294
	YMAX(ISEQ)=YCHKBF	DM20 295
	IF (IL,EQ,0) YOUTSD=YRC(J=1-NCH)	DM20 296
	IF (IL,EQ,1) YOUTSD=YLC(J=1-NCH)	DM20 297
	RSINT=SLOAD(IM1)+(YOUTSD-YMAX(ISEQ))*SIGN	DM20 298
	VALINT=RSINT+(SLOAD(I)*DELY)	DM20 299
	VALNUM(ISEQ)=VLINBF=RSINT	DM20 300
644	SLPHF=SLP(I)	DM20 301
645	YCHKBF=YCHK	DM20 302
	VLINBF=VALINT	DM20 303
	IF (K,EQ,KUL,AND,NUMEXT,EQ,0) GO TO 526	DM20 304
	GO TO 527	DM20 305
526	VALMAX(1)=SLOAD(I)	DM20 306

	YMAX(1)=YCHK	DM20 307
	VALNUM(1)=VALINT	DM20 308
	NOEXT=1	DM20 309
527	CONTINUE	DM20 310
	IF (I.EQ.1.AND.NOOUT.NE.0) WRITE (6,734)	DM20 311
	IF (NOOUT.NE.0) WRITE (6,735) I,DLT,SLP(I),ISEQ,YCHK,VALINT,NUMEXT,	DM20 312
	1 VALMAX(ISEQ),VALNUM(ISEQ),YMAX(ISEQ)	DM20 313
	IF (NOOUT.NE.0.AND.K.EQ.KUL) WRITE (6,735) IP1, DLT,SLP(*SPANP),	DM20 314
	1 ISEQ,YCHK,VALINT,NUMEXT,VALMAX(ISEQ),VALNUM(ISEQ),YMAX(ISEQ)	DM20 315
542	CONTINUE	DM20 316
C		DM20 317
	SUMFX=SUMFX/SREF	DM20 318
	SUMFY1=SUMFY1/SREF	DM20 319
	SUMFY2=SUMFY2/SREF	DM20 320
	SUMFT2=SUMFT2/SREF	DM20 321
	WRITE (6,712) SUMFX,SUMFY1,SUMFY2,SUMFT2	DM20 322
C		DM20 323
C	SIDE FORCE PER UNIT TIPCHORD/(Q*AC)	DM20 324
C		DM20 325
	IF (NDPAG.EQ.0) GO TO 600	DM20 326
	IF (TIPCHD.LT.100.0*TLRNC) GO TO 600	DM20 327
	TIPPEL=TIPCHD/NCW	DM20 328
	DENOM=TIPCHD+TIPPEL	DM20 329
	WRITE (6,708)	DM20 330
	JSE=0	DM20 331
	FACTRK=1.0/(FKLE*TWOB)	DM20 332
	FACTRI=1.0/FACTRK	DM20 333
	DO 914 JTIP=1,NCW	DM20 334
	AJTIP=JTIP	DM20 335
	XLOC=AJTIP*TIPPEL	DM20 336
	XLOCOC=XLOC/TIPCHD	DM20 337
	FT=FT2(JTIP)/DENOM	DM20 338
	JSE=JSE+1	DM20 339
	IF (TL.EQ.1) GO TO 918	DM20 340
	J=NRP+NCW+JTIP	DM20 341
	XSE(JSE)=XRF(J)	DM20 342
	GO TO 919	DM20 343
918	J=NRP+NCW+JTIP	DM20 344
	XSE(JSE)=XLF(J)	DM20 345
919	CSMDM=CSMDM+ABS((RB+R2)*FACTRK*FT2(JTIP)*FKSE)	DM20 346
	CSINT=CSINT+ABS(FACTRK*FT2(JTIP)*FKSE)	DM20 347
	CGSELC(JSE)=(CSMDM/CSINT)*SIGN	DM20 348
	YEXP=CGSELC(JSE)*(RB*SIGN)	DM20 349
	GAMSE(JSE)=((CSINT*FACTRI)/(2.0*YEXP))*COSANG	DM20 350
914	WRITE (6,709) JTIP,JSE,XLOCOC,FT,GAMSE(JSE),CGSELC(JSE),XSE(JSE)	DM20 351
600	CONTINUE	DM20 352
C		DM20 353
C		DM20 354
C	PRINT INDIVIDUAL PANEL FORCES	DM20 355
C		DM20 356
	IF (NOOUT.NE.1) GO TO 548	DM20 357
	WRITE (6,733)	DM20 358
	DO 550 J=JSTART,JEND	DM20 359
550	WRITE (6,706) J,YCPT(J),DLTPG(J),CIRC(J),FX(J),FY(J),FY2(J)	DM20 360
548	CONTINUE	DM20 361
C		DM20 362
C		DM20 363
C		DM20 364
C		DM20 365
C	FIN TRAILING EDGE VORTICES CALCULATED NEXT.	DM20 366
C	GAMMA.....GAMMA/VINF, POSITIVE COUNTERCLOCKWISE.	DM20 367
C	YCG.....YHAR, MEASURED FROM BODY CENTERLINE.	DM20 368
C		DM20 369

	IF (NDWAG, EQ, 0) GO TO 531	0420 370
	WRITE (6, 736)	0420 371
	WRITE (6, 738)	0420 372
	IF (NDFXT, EQ, 0) GO TO 528	0420 373
	IVRT=IVRT+1	0420 374
	GAMMA(IVRT)=(SLOAD(1)*T*OB/2, 0)*SIGN	0420 375
	YCG(IVRT)=(WB+(VALNUM(1)/SLOAD(1)))*SIGN	0420 376
	WRITE (6, 710) IVRT, GAMMA(IVRT), YCG(IVRT)	0420 377
	GO TO 531	0420 378
528	CONTINUE	0420 379
	NLST=NUMFXT+1	0420 380
	DO 650 ISFQ=1, NLST	0420 381
	IVRT=IVRT+1	0420 382
	ISFQI=ISEQ+1	0420 383
	IF (ISEQ, EQ, NLST) GO TO 534	0420 384
	DIFMAX=VALMAX(ISEQI)-VALMAX(ISEQ)	0420 385
	GAMMA(IVRT)=(T*OB/2, 0)*DIFMAX*SIGN	0420 386
	YCG(IVRT)=((YMAX(ISEQI)*VALMAX(ISEQI)-YMAX(ISEQ)*VALMAX(ISEQ))	0420 387
	1 /DIFMAX)=(VALNUM(ISEQI)/DIFMAX)*SIGN	0420 388
	GO TO 533	0420 389
534	GAMMA(IVRT)=(T*OB/2, 0)*VALMAX(ISEQ)*SIGN	0420 390
	YCG(IVRT)=YMAX(ISEQ)+(VALINT/VALMAX(ISEQ))*SIGN	0420 391
533	CONTINUE	0420 392
	WRITE (6, 710) IVRT, GAMMA(IVRT), YCG(IVRT)	0420 393
650	CONTINUE	0420 394
531	CONTINUE	0420 395
C		0420 396
C		0420 397
	IF (MSWL, EQ, 0) GO TO 549	0420 398
	IF (IL, NE, 0) GO TO 543	0420 399
C		0420 400
C	RE-ENTER ABOVE LOOP FOR LEFT HORIZONTAL WING	0420 401
C		0420 402
	IL=1	0420 403
	KUL=MSWLP	0420 404
	JSTART=NMP+1	0420 405
	JEND=NMP	0420 406
	JTIP=NMP-NC+1	0420 407
	TIPCHD=XI, B(NMP)=XLF(JTIP)	0420 408
	WRITE (6, 721) ALN	0420 409
	WRITE (6, 702)	0420 410
	WRITE (6, 720)	0420 411
	ANGL=ANGLL	0420 412
	SINANG=SIN(ANGL)	0420 413
	COSANG=COS(ANGL)	0420 414
	NSPAN=NSPANP+MSWLP	0420 415
	SIGN=1.0	0420 416
	J=NMP+1	0420 417
	GO TO 540	0420 418
543	IF (MSWU, EQ, 0) GO TO 549	0420 419
C		0420 420
C	LOOP 546 IS FOR UPPER AND LOWER FINS	0420 421
C	HERE IL=0....UPPER FIN	0420 422
C	IL=1....LOWER FIN	0420 423
C		0420 424
C		0420 425
	BTW=1, 0/R2V	0420 426
	T*OB=4, 0+R2V	0420 427
	WRITE (6, 721) ALN	0420 428
	WRITE (6, 702)	0420 429
	WRITE (6, 723)	0420 430
	KUBMSWUP	0420 431
	IL=0	0420 432

ANGL=ANGLU	DM20 433
SINANG=SIGN(ANGL)	DM20 434
COSANG=COS(ANGL)	DM20 435
NSPANP=MSWUP+NSPANP	DM20 436
SIGN=+1.0	DM20 437
J=NHMP+1	DM20 438
JSTART=NHMP+1	DM20 439
JEND=NSP	DM20 440
JTIP=NSP-NCW+1	DM20 441
TIPCHO=XRB(NSP)-XRF(JTIP)	DM20 442
540 CONTINUE	DM20 443
CIRNET(NSPANP)=0.0	DM20 444
I=0	DM20 445
SUMFX=0.0	DM20 446
SUMFZ1=0.0	DM20 447
SUMFZ2=0.0	DM20 448
SUMFT2=0.0	DM20 449
SLP(1)=0.0	DM20 450
DLT=0.0	DM20 451
VALINT=0.0	DM20 452
CSINT=0.0	DM20 453
CSMOM=0.0	DM20 454
NUMEXT=0	DM20 455
ISFO=0	DM20 456
NDEXT=0	DM20 457
DO 546 K=2,KU	DM20 458
I=I+1	DM20 459
IFV=IFV+1	DM20 460
SCSMX=0.0	DM20 461
SCSMZ1=0.0	DM20 462
SCSMZ2=0.0	DM20 463
SUM1=0.0	DM20 464
SWPANG=ABS(ATAN(SWPPLE(J)))	DM20 465
COSSWP=COS(SWPANG)	DM20 466
PSIPLE=SWPANG*57.2957795	DM20 467
SSLE=PSIMCH.GT.PSIPLE	DM20 468
ZCHK=ZCPT(J)*COSALF+XHAR(J)*SINALF	DM20 469
IF (ANYMO) ZCHK=ZCPT(J)	DM20 470
ZLOC=ZCHK*BTW	DM20 471
IP1=I+1	DM20 472
IF (IL.EQ.1) GO TO 560	DM20 473
NFRST=MSWRP+MSWLP+1	DM20 474
ISPN=IP1+MSWRP+MSWLP	DM20 475
IC=I+MSWRP+MSWLP	DM20 476
XLE(IFV)=XLF(J)+(ZCPT(J)-ZLF(J))*SWPPLE(J)	DM20 477
GO TO 561	DM20 478
560 NFRST=MSWRP+MSWLP+MSWUP+1	DM20 479
ISPN=IP1+MSWRP+MSWLP+MSWUP	DM20 480
IC=I+MSWRP+MSWLP+MSWUP	DM20 481
XLE(IFV)=XRF(J)+(ZCPT(J)-ZRF(J))*SWPPLE(J)	DM20 482
561 CONTINUE	DM20 483
CIRNET(ISPN)=0.0	DM20 484
C	DM20 485
C	DM20 486
C	DM20 487
C	DM20 488
C	DM20 489
C	DM20 490
DO 545 L=1,NCW	DM20 491
SUM1=SUM1+FN(J)	DM20 492
VDI=1./VDTH(J)	DM20 493
IF (I.NE.1) GO TO 212	DM20 494
CIRNET(NFRST)=CIRNET(NFRST)-CIRC(J)*STGN	DM20 495

212	JADJ=J+NCW	0420	496
	IF (K, EQ, KU) GO TO 216	0420	497
	GO TO 217	0420	498
216	CIRNET(NSPANP)=CIRNET(NSPANP)+CIRC(J)*SIGN	0420	499
	GO TO 213	0420	500
217	CIRNET(ISPN)=CIRNET(ISPN)+(CIRC(J)-CIRC(JADJ))*SIGN	0420	501
213	CONTINUE	0420	502
	IF (NDWAG, EQ, 0) GO TO 317	0420	503
	IF (IL, EQ, 1) GO TO 340	0420	504
	CHORDS(J)=XRB(J)-XRF(J)	0420	505
	GO TO 341	0420	506
340	CHORDS(J)=XLB(J)-XLF(J)	0420	507
341	CONTINUE	0420	508
	IF (L, EQ, NCW) CHORDS(J)=0.5*CHORDS(J),	0420	509
	FZ2(J)=2.0*CHORDS(J)*CIRNET(ISPN)*(SINANG=VNDORS(J))	0420	510
	IF (FX(J), LT, 0.0, OR, SSLE) GO TO 342	0420	511
	SCSMX=SCSMX+FX(J)	0420	512
	SCSMZ1=SCSMZ1+PZ(J)	0420	513
342	CONTINUE	0420	514
	IF (K, EQ, KUL) GO TO 316	0420	515
	SCSMZ2=SCSMZ2+FZ2(J)	0420	516
	GO TO 317	0420	517
316	FT2(L)=FZ2(J)	0420	518
	SUMFT2=SUMFT2+FT2(L)	0420	519
317	CONTINUE	0420	520
545	J=J+1	0420	521
	DELZ=WIDTH(J-1)	0420	522
	SUMFX=SUMFX+SCSMX	0420	523
	SUMFZ1=SUMFZ1+SCSMZ1	0420	524
	SUMFZ2=SUMFZ2+SCSMZ2	0420	525
		0420	526
		0420	527
		0420	528
		0420	529
		0420	530
		0420	531
		0420	532
		0420	533
		0420	534
		0420	535
		0420	536
		0420	537
		0420	538
		0420	539
		0420	540
		0420	541
		0420	542
		0420	543
		0420	544
		0420	545
		0420	546
		0420	547
		0420	548
		0420	549
851	SECFXX=0.0	0420	550
	SECFZ=0.0	0420	551
	SECFZ2=SCSMZ2*FACTOR	0420	552
	SECSUC=0.0	0420	553
	CGLOC(IFV)=0.0	0420	554
	GAMLE(IFV)=0.0	0420	555
852	CONTINUE	0420	556
	WRITE (6, 703) IC, ZLOC, SLOAD(I), SECFXX, SECFZ, SECFZ2, SECSUC, CSINT,	0420	557
	CGLOC(IFV), CIRNET(IC), GAMLE(IFV), XLE(IFV)	0420	558
	IF (K, NE, KUL) GO TO 544	0420	559

ZLOC=((R2V+RA)/P2)*SIGN	DM20 550
SLOTIP=0.0	DM20 560
*WRITE (6,704) NSPANP,ZLOC,SLOTIP,CIRNET(NSPANP)	DM20 561
560 CONTINUE	DM20 562
IF (I.EQ.1) GO TO 845	DM20 563
IM1=I-1	DM20 564
DLT=ARS(ZCHK-ZCHKBF)	DM20 565
SLP(I)=(SLOAD(I)-SLOAD(IM1))/DLT	DM20 566
REFSLP=ARS(SLOAD(I)/(10.0*R2V))	DM20 567
IF (ARS(SLP(I)),LE,REFSLP) SLP(I)=0.0	DM20 568
IF (I.EQ.2) GO TO 846	DM20 569
IF (K.EQ.KU) GO TO 821	DM20 570
GO TO 822	DM20 571
821 SLP(NSPANP)=-SLOAD(I)/(DLT/2.0)	DM20 572
IF (ARS(SLP(NSPANP))GE,REFSLP) GO TO 846	DM20 573
SLPCHK=SLP(I)	DM20 574
IF (SLPCHK.EQ.0.0) SLPCHK=SLP(I-1)	DM20 575
IF (SLPCHK.GT.0.0.AND,SLP(NSPANP).LT.0.0) GO TO 843	DM20 576
IF (SLPCHK.LT.0.0.AND,SLP(NSPANP).GT.0.0) GO TO 843	DM20 577
822 CONTINUE	DM20 578
IF (SLP(I).EQ.0.0) GO TO 846	DM20 579
IF (SLPHF.EQ.0.0.AND,I.GE.4) SLPHF=SLP(I-2)	DM20 580
IF (SLPHF.GT.0.0.AND,SLP(I).LT.0.0) GO TO 843	DM20 581
IF (SLPHF.LT.0.0.AND,SLP(I).GT.0.0) GO TO 843	DM20 582
GO TO 846	DM20 583
843 NUMEXT=NUMEXT+1	DM20 584
ISEQ=NUMEXT+1	DM20 585
VALMAX(1)=SLOAD(1)	DM20 586
ZMAX(1)=RA*SIGN	DM20 587
VALMAX(ISEQ)=SLOAD(IM1)	DM20 588
ZMAX(ISEQ)=ZCHKBF	DM20 589
IF (IL.EQ.0) ZOUTSD=ZRB(J-1-NCW)	DM20 590
IF (IL.EQ.1) ZOUTSD=ZLB(J-1-NCW)	DM20 591
RSINT=SLOAD(IM1)+(ZOUTSD-ZMAX(ISEQ))*SIGN	DM20 592
VALINT=RSINT+(SLOAD(I)*DELZ)	DM20 593
VALNUM(ISEQ)=VLINBF-RSINT	DM20 594
844 SLPHF=SLP(I)	DM20 595
845 ZCHKBF=ZCHK	DM20 596
VLINBF=VALINT	DM20 597
IF (K.EQ.KU.AND,NUMEXT.EQ.0) GO TO 826	DM20 598
GO TO 827	DM20 599
826 VALMAX(1)=SLOAD(1)	DM20 600
ZMAX(1)=ZCHK	DM20 601
VALNUM(1)=VALINT	DM20 602
NDEXT=1	DM20 603
827 CONTINUE	DM20 604
IF (T.EQ.1.AND,NDUT.NE.0) *WRITE (6,743)	DM20 605
IF (NDUT.NE.0) *WRITE (6,735) I,DLT,SLP(I),ISEQ,ZCHK,VALINT,NUMEXT,	DM20 606
1 VALMAX(ISEQ),VALNUM(ISEQ),ZMAX(ISEQ)	DM20 607
IF (NDUT.NE.0.AND,K.EQ.KU) *WRITE (6,735) IP1, DLT,SLP(NSPANP),	DM20 608
1 ISEQ,ZCHK,VALINT,NUMEXT,VALMAX(ISEQ),VALNUM(ISEQ),ZMAX(ISEQ)	DM20 609
546 CONTINUE	DM20 610
C	DM20 611
SUMFX=SUMFX/SREF	DM20 612
SUMFZ1=SUMFZ1/SREF	DM20 613
SUMFZ2=SUMFZ2/SREF	DM20 614
SUMFT2=SUMFT2/SREF	DM20 615
WRITE (6,731) SUMFX,SUMFZ1,SUMFZ2,SUMFT2	DM20 616
C	DM20 617
C	DM20 618
C	DM20 619
C	DM20 620
IF (NDRAG.EQ.0) GO TO 400	DM20 621

```

IF (TIPCHD,LT,100.0+TLWAC) GO TO 400
TIPEPL=TIPEPL/NCW
DENOM=TIPEPL*TIPEPL
WRITE (6,707)
FACTRK=1.0/(FKLE+THOB)
FACTRI=1.0/FACTRK
DO 414 JTIP=1,NCW
AJTIP=JTIP
XLQC=AJTIP*TIPEPL
XLQCC=XLQC/TIPCHD
FT=FT2(JTIP)/DENOM
JSE=JSE+1
IF (IL,EQ,1) GO TO 920
J=N3P-NCW+JTIP
XSE(JSE)=XRF(J)
GO TO 921
920 J=NPANLS-NCW+JTIP
XSE(JSE)=XLF(J)
921 CSMOM=CSMOM+ABS((WA+BP)*FACTRK*FT2(JTIP)*FKSE)
CSINT=CSINT+ABS(FACTRK*FT2(JTIP)*FKSE)
CGSELC(JSE)=(CSMOM/CSINT)*SIGN
ZEXP=CGSELC(JSE)*(RA*SIGN)
GAMSE(JSE)=((CSINT*FACTRI)/(2.0*ZEXP))*COSANG
414 WRITE (6,709) JTIP,JSE,XLQCC,FT,GAMSE(JSE),CGSELC(JSE),XSE(JSE)
400 CONTINUE
C
C PRINT INDIVIDUAL PANEL FORCES
C
IF (NOUT,EQ,0) GO TO 448
WRITE (6,739)
DO 450 J=JSTART,JEND
450 WRITE (6,706) J,ZCPT(1),DLTPG(J),CIRC(J),FX(J),FZ(J),FZ2(J)
448 CONTINUE
C
C FIN TRAILING EDGE VORTICES CALCULATED NEXT.
C GAMMA,....,GAMMA/VINF, POSITIVE COUNTERCLOCKWISE.
C ZCG,.....,ZBAR, MEASURED FROM BODY CENTERLINE.
C
IF (NDRAG,EQ,0) GO TO 631
WRITE (6,735)
WRITE (6,742)
IF (NDEXT,EQ,0) GO TO 628
IVRT=IVRT+1
GAMMA(IVRT)=(SLOAD(1)*THOB/2.0)*SIGN
ZCG(IVRT)=(WA+(VALNUM(1)/SLOAD(1)))*SIGN
WRITE (6,710) IVRT,GAMMA(IVRT),ZCG(IVRT)
GO TO 631
628 CONTINUE
NLST=NUMEXT+1
DO 651 ISEQ=1,NLST
IVRT=IVRT+1
ISEQP1=ISEQ+1
IF (ISEQ,EQ,NLST) GO TO 634
DIFMAX=VALMAX(ISEQP1)-VALMAX(ISEQ)
GAMMA(IVRT)=-((THOB/2.0)*DIFMAX)*SIGN
ZCG(IVRT)=-((ZMAX(ISEQP1)*VALMAX(ISEQP1)-ZMAX(ISEQ)*VALMAX(ISEQ))
1/DIFMAX)-(VALNUM(ISEQP1)/DIFMAX)*SIGN
GO TO 633
634 GAMMA(IVRT)=(THOB/2.0)*VALMAX(ISEQ)*SIGN
ZCG(IVRT)=ZMAX(ISEQ)+(ABS(VALINT/VALMAX(ISEQ)))*SIGN
633 CONTINUE
WRITE (6,710) IVRT,GAMMA(IVRT),ZCG(IVRT)
651 CONTINUE

```

```

0420 622
0420 623
0420 624
0420 625
0420 626
0420 627
0420 628
0420 629
0420 630
0420 631
0420 632
0420 633
0420 634
0420 635
0420 636
0420 637
0420 638
0420 639
0420 640
0420 641
0420 642
0420 643
0420 644
0420 645
0420 646
0420 647
0420 648
0420 649
0420 650
0420 651
0420 652
0420 653
0420 654
0420 655
0420 656
0420 657
0420 658
0420 659
0420 660
0420 661
0420 662
0420 663
0420 664
0420 665
0420 666
0420 667
0420 668
0420 669
0420 670
0420 671
0420 672
0420 673
0420 674
0420 675
0420 676
0420 677
0420 678
0420 679
0420 680
0420 681
0420 682
0420 683
0420 684

```

631 CONTINUE	DM20 685
C	DM20 686
C	DM20 687
C RE=ENTER ABOVE LOOP FOR LOWER WING	DM20 688
C	DM20 689
IF(IL,NE,0) GO TO 549	DM20 690
WRITE(6,721) ADM	DM20 691
WRITE(6,702)	DM20 692
WRITE(6,723)	DM20 693
IL=1	DM20 694
KUBMSWD+1	DM20 695
JSTART=N3P+1	DM20 696
JEND=NPANLS	DM20 697
ANGL=ANGLD	DM20 698
SINANG=SIN(ANGL)	DM20 699
NSPANP=NSPANP+MSWDP	DM20 700
SIGN=-1.0	DM20 701
J=N3P+1	DM20 702
JTIP=NPANLS=NCW+1	DM20 703
TIPCHO=XL(R(NPANLS)=XLF(JTIP)	DM20 704
GO TO 544	DM20 705
540 CONTINUE	DM20 706
C	DM20 707
C	DM20 708
RETURN	DM20 709
END	DM20 710

SUBROUTINE THETIN(MSW,MT)	DM21 1
C	DM21 2
C VERSION: DEMON1	DM21 3
C	DM21 4
C THIS ROUTINE READS THICKNESS SLOPES FOR AN ARBITRARY WING.	DM21 5
C	DM21 6
COMMON/THKDAT/NTOAT,NCWT,NTPR,MSWT(4),NRPT,NHPT,N3PT,NTHP,ASYMT,	DM21 7
1 NVERT,SWLET(20,4),SWIET(20,4),YTH(20,4),THETA(400)	DM21 8
COMMON/THIAS/NUNIS,THET(400)	DM21 9
C	DM21 10
500 FORMAT(8F10,0)	DM21 11
C	DM21 12
MT=NCWT*MSW	DM21 13
IF(NUNIS,NE,0) GO TO 5	DM21 14
MN=0	DM21 15
DO 1 JN=1,MT,NCWT	DM21 16
MN=MN+NCWT	DM21 17
1 READ(5,500) (THET(J),J=JN,MN)	DM21 18
RETURN	DM21 19
5 READ(5,500) (THET(J),J=1,NCWT)	DM21 20
DO 6 J=2,MSW	DM21 21
JJ=(J-1)*NCWT	DM21 22
DO 6 K=1,NCWT	DM21 23
KK=JJ+K	DM21 24
6 THET(KK)=THET(K)	DM21 25
RETURN	DM21 26
END	DM21 27

	SUBROUTINE THKIN	0422	1
C		0422	2
C	VERSION: DEMON1	0422	3
C		0422	4
C	SUBROUTINE TO INPUT THICKNESS DATA.	0422	5
C		0422	6
	LOGICAL ASYMT	0422	7
	COMMON/THKDAT/NTDAT,NCWT,NTPT,MSWT(4),NRPT,MRPT,MSPT,NTHP,ASYMT,	0422	8
1	NVERT,SWLET(20,4),SWTET(20,4),YTH(20,4),THETA(400)	0422	9
	COMMON/SPANS/SPANR,SPANL,SPANU,SPAND,SWPLER,SWPLEL,SWPLEU,	0422	10
1	SWPLED,SWPTER,SWPTEL,SWPTEU,SWPTED,RR00	0422	11
	COMMON/THAS/NUMIS,THET(400)	0422	12
C		0422	13
	500 FORMAT(10I5)	0422	14
	510 FORMAT(3F10,0)	0422	15
C		0422	16
C		0422	17
C	INITIALIZE INDICES	0422	18
C		0422	19
	NLP=0	0422	20
	NUP=0	0422	21
	NDP=0	0422	22
C		0422	23
C	INPUT RIGHT WING DATA.	0422	24
C		0422	25
	READ(5,500) MSWT(1),LVSWT,NUMIS	0422	26
	MSWP=MSWT(1)+1	0422	27
C		0422	28
C	IF SIDESLIP IS NON-ZERO OR IF LVSWT=0, SPANWISE SPACINGS	0422	29
C	ARE NOT READ IN. THEY MUST BE CALCULATED AND EQUALLY	0422	30
C	SPACED. NO BREAKS IN SWEEP ARE ALLOWED.	0422	31
C		0422	32
	IF(ASYMT.OR.LVSWT.EQ.0) GO TO 5	0422	33
	READ(5,510) (YTH(I,1),SWLET(I,1),SWTET(I,1),I=1,MSWP)	0422	34
	GO TO 10	0422	35
	5 CALL EDGES(MSWP,SPANR,RR00,SWPLER,SWPTER,YTH(1,1),SWLET(1,1),	0422	36
	1 SWTET(1,1))	0422	37
	10 CONTINUE	0422	38
C		0422	39
C	SUBROUTINE THETIN READS THICKNESS SLOPES.	0422	40
C		0422	41
	CALL THETIN(MSWT(1),NRPT)	0422	42
	00 15 I=1,NRPT	0422	43
15	THETA(I)=THET(I)	0422	44
	IF(NTDAT.EQ.1) GO TO 40	0422	45
C		0422	46
C	INPUT LEFT WING DATA IF SIDESLIP IS NON-ZERO, WING ALONE.	0422	47
C		0422	48
	IF(.NOT.ASYMT) GO TO 25	0422	49
	READ(5,500) MSWT(2),LVSWT,NUMIS	0422	50
	MSWP=MSWT(2)+1	0422	51
	CALL EDGES(MSWP,-SPANL,-RR00,-SWPLEL,-SWPTEL,YTH(1,2),	0422	52
1	SWLET(1,2),SWTET(1,2))	0422	53
	CALL THETIN(MSWT(2),NLP)	0422	54
	00 20 I=1,NLP	0422	55
20	THETA(I+NRPT)=THET(I)	0422	56
C		0422	57
C	INPUT UPPER WING DATA IF VERTICAL WINGS ARE PRESENT	0422	58
C	AND THEIR GEOMETRY IS DIFFERENT FROM HORIZONTAL WINGS.	0422	59
C	NOTE THAT NTDAT IS NOW NE 1.	0422	60
C		0422	61
	25 CONTINUE	0422	62
	IF(NVERT.EQ.0) GO TO 50	0422	63
	READ(5,500) MSWT(3),LVSWT,NUMIS	0422	64

	MSWP=MSWT(3)+1	DM22 65
	IF(ASYMT,OR,LVSWT,EQ,0) GO TO 27	DM22 66
	READ(5,510) (YTH(I,3),SWLET(I,3),SWTET(I,3),I=1,MSWP)	DM22 67
	GO TO 28	DM22 68
	27 CALL EDGES(MSWP,SPANU,HHOD,SWPLEU,SWPTEU,YTH(I,3),SWLET(I,3),	DM22 69
	1 SWTET(I,3))	DM22 70
	28 CONTINUE	DM22 71
	CALL THETIN(MSWT(3),NUP)	DM22 72
	DO 30 I=1,NUP	DM22 73
	30 THETA(NRPT+NLP+I)=THET(I)	DM22 74
C		DM22 75
C	INPUT LOWER WING DATA IF SIDESLIP IS NON-ZERO, WING ALONE.	DM22 76
C		DM22 77
	IF(.NOT,ASYMT) GO TO 50	DM22 78
	READ(5,500) MSWT(4),LVSWT,NUNIS	DM22 79
	MSWP=MSWT(4)+1	DM22 80
	CALL EDGES(MSWP,=SPANU,=HHOD,=SWPLEU,=SWPTEU,YTH(I,4),SWLET(I,4),	DM22 81
	1 SWTET(I,4))	DM22 82
	CALL THETIN(MSWT(4),NUP)	DM22 83
	DO 35 I=1,NUP	DM22 84
	35 THETA(NRPT+NLP+NUP+I)=THET(I)	DM22 85
	GO TO 50	DM22 86
C		DM22 87
C	ALL DATA INPUT AT THIS POINT.	DM22 88
C		DM22 89
C	SET UPPER WING EQUAL TO RIGHT WING IN SYMMETRIC	DM22 90
C	CASE (NTOAT=1 AND NVERT NE 0)	DM22 91
C		DM22 92
	40 CONTINUE	DM22 93
	IF(NVERT,EQ,0) GO TO 50	DM22 94
	MSWT(3)=MSWT(1)	DM22 95
	MSWP=MSWT(1)+1	DM22 96
	DO 45 I=1,MSWP	DM22 97
	YTH(I,3)=YTH(I,1)	DM22 98
	SWLET(I,3)=SWLET(I,1)	DM22 99
	45 SWTET(I,3)=SWTET(I,1)	DM22 100
	NUP=NRPT	DM22 101
	DO 46 I=1,NRPT	DM22 102
	46 THETA(NRPT+I)=THETA(I)	DM22 103
C		DM22 104
C	CALCULATE INDICES.	DM22 105
C		DM22 106
	50 CONTINUE	DM22 107
	NRPT=NRPT+NLP	DM22 108
	N3PT=NRPT+NUP	DM22 109
	NTHP=N3PT+NUP	DM22 110
C		DM22 111
	RETURN	DM22 112
	END	DM22 113
	SUBROUTINE THKLYT(CRP,IL)	DM23 1
C		DM23 2
C	VERSION: DEMUNI	DM23 3
C		DM23 4
C	THIS ROUTINE LAYS OUT SOURCE PANELS ON A SINGLE WING SURFACE.	DM23 5
C		DM23 6
	DIMENSION NDP(3)	DM23 7
C		DM23 8
	COMMON/DNE/CIRC(250),DELTP(250),FN(250),PNLC(250),SWPPL(250),	DM23 9
	IS+PPT(250),VNOR(250),XBAR(250),ZBAR(250),XCPT(250),YCPT(250),ZCPT	DM23 10

```

2(250),XLF(250),XLH(250),XRF(250),XHB(250),YLC(250),YRC(250),ZLF(250)DM23 11
30),ZRF(250),ZLB(250),ZRH(250),SNT(125),CST(125),SNT2(125),CST2(125)DM23 12
4),IP(300),XFHIP(100),A,ALFA,ALFA,ARWING,H2,P2V,BETA,RTAN,CONST, DM23 13
5CUSALF,CONSBET,CN,OX,EM,FMAC,RR,SINALF,SINREF,SLOPE,TLRNC,TIPY, DM23 14
6TOTLR,U,V,*,UCHK,VCHK,WCHK,WHIP,X,DUMY,Z,I,IF,II,J,MSWP,MSWL,MSWU,DM23 15
7MSWD,NBIP,NCRX,NCH,DRAG,NHP,NRP,NRP,N3P,NOCPT,NOLINP,NOUT,NPANELS,DM23 16
8NPRESS,NRWP,ASYM,BODY,DELTA,NOSYM DM23 17
COMMON/THKDAT/NTDAT,NCWT,NTPR,N3WT(4),NRPT,NHPT,N3PT,NTHP,ASYMT, DM23 18
1 NVFRT,SWLET(20,4),SWTET(20,4),YTH(20,4),THETA(400) DM23 19
COMMON/THKSPAN/XRFT(400),XLFT(400),XFRT(400),XLBT(400), DM23 20
1 YRFT(400),YLCT(400),ZRFT(400),ZLFT(400),ZRB(400), DM23 21
2 ZLRT(400),SLLET(400),SLTET(400) DM23 22
LOGICAL LEFT DM23 23
DATA OTOR/,0174532925/ DM23 24
C
C FORMAT STATEMENTS DM23 25
C
C 700 FORMAT(1H,50X,40HPANEL CORNER COORDINATES FOR WING PANELS) DM23 26
705 FORMAT(/5X,1HJ,15X,2HLF,15X,1H*,12X,2HLB,15X,1H*,12X,2HRF,15X, DM23 27
1 1H*,12X,2HRB/12X,1HX,9X,1HY,9X,1HZ,5X,1H*,3X,1HX,9X,1HY, DM23 28
2 9X,1HZ,5X,1H*,3X,1HX,9X,1HY,9X,1HZ,5X,1H*,3X,1HX,9X,1HY, DM23 29
3 9X,1HZ,/38X,1H*,29X,1H*,29X,1H*/130(1H*)/ DM23 30
4 38X,1H*,29X,1H*,29X,1H*) DM23 31
710 FORMAT(/1X,56(1H=),17HRIGHT WING PANELS,57(1H=)/) DM23 32
711 FORMAT(/1X,57(1H=),16HLEFT WING PANELS,57(1H=)/) DM23 33
712 FORMAT(/1X,56(1H=),17HUPPER WING PANELS,57(1H=)/) DM23 34
713 FORMAT(/1X,56(1H=),17HLOWER WING PANELS,57(1H=)/) DM23 35
720 FORMAT(3X,15,3X,F9.4,1X,F9.4,1X,F9.4,1H*,F9.4,1X,F9.4,1X,F9.4, DM23 36
1 1H*,F9.4,1X,F9.4,1X,F9.4,1H*,F9.4,1X,F9.4,1X,F9.4) DM23 37
C
C VERTICAL WING COORDINATES ARE CALCULATED IN THE SAME WAY DM23 38
C AS HORIZONTAL COORDINATES, Y AND Z COORDINATES ARE DM23 39
C THEN INTERCHANGED FOR VERTICAL WING. DM23 40
C LEFT STANDS FOR EITHER LEFT HORIZONTAL WING DM23 41
C OR LOWER VERTICAL WING. DM23 42
C
C LEFT=IL,EQ,1,OR,IL,EQ,3 DM23 43
C NS=IL+1 DM23 44
C NRPT(1)=NRPT DM23 45
C NRPT(2)=NHPT DM23 46
C NRPT(3)=N3PT DM23 47
C MSWP=MSWT(NS)+1 DM23 48
C
C SET CONSTANT SWEEP INDICATOR. DM23 49
C
C LVSWT=0 DM23 50
C IF(MSWP,EQ,2) GO TO 15 DM23 51
C DO 10 I=3,MSWP DM23 52
C IM=I-1 DM23 53
C 10 IF(SWLET(I,NS),NE,SWLET(IM,NS),OR,SWTET(I,NS),NE,SWTET(IM,NS)) DM23 54
C 1 LVSWT=1 DM23 55
C 15 SLPWLE=TAN(SWLET(MSWP,NS)*OTOR) DM23 56
C SLPWTE=TAN(SWTET(MSWP,NS)*OTOR) DM23 57
C CSIDEP=CRP DM23 58
C ANCH=NCWT DM23 59
C *LEX=0,0 DM23 60
C
C LAY OUT PANELS, INDEX I RUNS SPANWISE, K CHORDWISE. DM23 61
C
C CALCULATE OUTWARD SIDE EDGE FOR A CHORDWISE ROW. DM23 62
C
C DO 60 I=2,MSWP DM23 63
C IM=I-1 DM23 64
C *F(LVSWT,EQ,0) GO TO 20 DM23 65

```

	SLP=LE*TAN(SWLFT(I,NS)*DTOR)	DM23	75
	SLPWTE=TAN(SWTET(I,NS)*DTOR)	DM23	76
20	SLPDIF=SLP*LE-SLPWTE	DM23	77
	CSIDE=CSIDEP-(YTH(I,NS)-YTH(IM,NS))*SLPDIF	DM23	78
	IF(I,EQ,2) GO TO 30	DM23	79
	JLE=(I-3)*NCWT+1	DM23	80
	IF(NS,GT,1) JLE=JLE+NDP(NS-1)	DM23	81
	WLEX=XRFT(JLE)	DM23	82
	IF(LEFT) WLEX=XLFT(JLE)	DM23	83
30	CONTINUE	DM23	84
C		DM23	85
C	CALCULATE PANEL LEADING AND TRAILING EDGE	DM23	86
C	SLOPES AND CORNER COORDINATES.	DM23	87
C		DM23	88
	DO 50 K=1,NCWT	DM23	89
	J=(I-2)*NCWT+K	DM23	90
	IF(NS,GT,1) J=J+NDP(NS-1)	DM23	91
	AKM=K-1	DM23	92
	AK=K	DM23	93
	SLEET(J)=SLPWLE-AKM*SLPDIF/ANCW	DM23	94
	SLTET(J)=SLPWLE-AK*SLPDIF/ANCW	DM23	95
	IF (ABS(SLEET(J)),LE,0.001) SLEET(J)=0.0	DM23	96
	IF (ABS(SLTET(J)),LE,0.001) SLTET(J)=0.0	DM23	97
	XLFT(J)=AKM*CSIDEP/ANCW+WLEX	DM23	98
	XLBT(J)=XLFT(J)+CSIDEP/ANCW	DM23	99
	XRFT(J)=AKM*CSIDE/ANCW+(YTH(I,NS)-YTH(IM,NS))*SLPWLE+WLEX	DM23	100
	XRBT(J)=XRFT(J)+CSIDE/ANCW	DM23	101
	YLCT(J)=YTH(IM,NS)	DM23	102
	YRCT(J)=YTH(I,NS)	DM23	103
	IF(.NOT,LEFT) GO TO 40	DM23	104
C		DM23	105
C	INTERCHANGE LEFT AND RIGHT COORDINATES FOR LEFT WING.	DM23	106
C		DM23	107
	TEMP=XLFT(J)	DM23	108
	XLFT(J)=XRFT(J)	DM23	109
	XRFT(J)=TEMP	DM23	110
	TEMP=XLBT(J)	DM23	111
	XLBT(J)=XRBT(J)	DM23	112
	XRBT(J)=TEMP	DM23	113
	TEMP=YLCT(J)	DM23	114
	YLCT(J)=YRCT(J)	DM23	115
	YRCT(J)=TEMP	DM23	116
	IF (SLEET(J),EQ,0.0) SLEET(J)=-TLRNC	DM23	117
	IF (SLTET(J),EQ,0.0) SLTET(J)=-TLRNC	DM23	118
C		DM23	119
40	CONTINUE	DM23	120
	ZLFT(J)=0.0	DM23	121
	ZRFT(J)=0.0	DM23	122
	ZLBT(J)=0.0	DM23	123
	ZRBT(J)=0.0	DM23	124
C		DM23	125
C	INTERCHANGE Y AND Z COORDINATES FOR VERTICAL PANELS.	DM23	126
C		DM23	127
	IF(NS,LE,2) GO TO 50	DM23	128
	ZLFT(J)=YLCT(J)	DM23	129
	ZLBT(J)=YLCT(J)	DM23	130
	YLCT(J)=0.0	DM23	131
	ZRFT(J)=YRCT(J)	DM23	132
	ZRBT(J)=YRCT(J)	DM23	133
	YRCT(J)=0.0	DM23	134
C		DM23	135
50	CONTINUE	DM23	136
	CSIDEP=CSIDE	DM23	137

	60 CONTINUE		
C			DM23 138
C	DEBUG PRINT OF PANEL CORNER COORDINATES.		DM23 139
C			DM23 140
	IF(NTPR,EO,0) RETURN		DM23 141
	IF(IL,GT,0) GO TO 70		DM23 142
	WRITE(6,700)		DM23 143
	WRITE(6,705)		DM23 144
	WRITE(6,710)		DM23 145
	NI=1		DM23 146
	NF=NRPT		DM23 147
	GO TO 90		DM23 148
	70 IF(IL,GT,1) GO TO 75		DM23 149
	WRITE(6,711)		DM23 150
	NI=NI+1		DM23 151
	NF=NHPT		DM23 152
	GO TO 90		DM23 153
	75 IF(IL,EG,3) GO TO 80		DM23 154
	WRITE(6,712)		DM23 155
	NI=NI+1		DM23 156
	NF=N3PT		DM23 157
	GO TO 90		DM23 158
	80 WRITE(6,713)		DM23 159
	NI=N3PT+1		DM23 160
	NF=NTHP		DM23 161
	90 WRITE(6,720) (J,XLEFT(J),YLEFT(J),ZLEFT(J),XLBT(J),YLCT(J),ZLBT(J),		DM23 162
	1 XRT(J),YRCT(J),ZRT(J),XRBT(J),YRCT(J),ZRBT(J),J=NI,NF)		DM23 163
C			DM23 164
	RETURN		DM23 165
	END		DM23 166
			DM23 167

	SUBROUTINE THKOUT		DM24 1
C			DM24 2
C	VERSION: DEMON1		DM24 3
C			DM24 4
C	THIS ROUTINE PRINTS OUT THICKNESS DATA. AFTER THE		DM24 5
C	THICKNESS SLOPES ARE PRINTED, THEY ARE DIVIDED BY PI.		DM24 6
C			DM24 7
	LOGICAL ASYMT		DM24 8
	COMMON/THKDAT/NTDAT,NCMT,NTPR,MSWT(4),NRPT,NHPT,N3PT,NTHP,ASYMT,		DM24 9
	1 NVFRT,SLEFT(20,4),SWTET(20,4),YTH(20,4),THETAL(400)		DM24 10
	DATA PI/3.141592654/		DM24 11
C			DM24 12
	600 FORMAT(1H1,30X,56HINPUT VALUES OF THE LOCAL SURFACE SLOPE OF THE		DM24 13
	THICKNESS/32X,52H DISTRIBUTION, FOR EACH CHORDWISE ROW THE FIRST VAL		DM24 14
	2UE/37X,41HIS FOR THE PANEL NEAREST THE LEADING EDGE)		DM24 15
	610 FORMAT(//5X,18HRIGHT WING SURFACE/)		DM24 16
	620 FORMAT(//5X,17HLEFT WING SURFACE/)		DM24 17
	630 FORMAT(//5X,18HUPPER WING SURFACE/)		DM24 18
	640 FORMAT(//5X,18HLOWER WING SURFACE/)		DM24 19
	650 FORMAT(11X,3HRINW,30X,6HSLOPES)		DM24 20
	660 FORMAT(8X,15,4X,(//1H+,27X,8F10,5))		DM24 21
	670 FORMAT(1H1,26H WING THICKNESS INPUT DATA//15X,		DM24 22
	1 55HSPANWISE LOCATIONS OF PANEL SIDE EDGES AND SWEEP ANGLES/		DM24 23
	2 20X,27HOF WING SECTION TO THE LEFT, //26X,		DM24 24
	3 29HSPANWISE LE SWEEP TO SWEEP/20X,1HT,5X,8HLOCATION/		DM24 25
	4 28X,4HFET,5X,7HDEGREES,3X,7HDEGREES)		DM24 26
	675 FORMAT(18X,15,4X,3F10,5)		DM24 27
	680 FORMAT(//16X,13,36H THICKNESS PANELS ARE TO BE LAID OUT//16X,13,		DM24 28
	1 20H CHORDWISE ROWS WITH,13,12H IN EACH ROW)		DM24 29

```

C
C
C
C
C
C
----- OUTPUT THICKNESS PANEL GEOMETRY -----
HEADING AND RIGHT WING DATA
WRITE(6,670)
WRITE(6,610)
NSP=MSWT(1)+1
WRITE(6,675) (I,YTH(I,1),SWLET(I,1),SWTET(I,1),I=1,NSP)
WRITE(6,680) NRPT,MSWT(1),NCWT
LEFT WING DATA IF NON-ZERO SIDESLIP AND WING ALONE.
IF(.NOT.ASYM1) GO TO 2
WRITE(6,620)
NSP=MSWT(2)+1
WRITE(6,675) (I,YTH(I,2),SWLET(I,2),SWTET(I,2),I=1,NSP)
NLFT=NHPT=NRPT
WRITE(6,680) NLFT,MSWT(2),NCWT
UPPER WING DATA IF VERTICAL WINGS PRESENT
2 CONTINUE
IF(NVERT.EQ.0) GO TO 4
WRITE(6,630)
NSP=MSWT(3)+1
WRITE(6,675) (I,YTH(I,3),SWLET(I,3),SWTET(I,3),I=1,NSP)
NUPP=NJPT=NHPT
WRITE(6,680) NUPP,MSWT(3),NCWT
LOWER WING DATA IF NON-ZERO SIDESLIP AND WING ALONE.
IF(.NOT.ASYM1) GO TO 4
WRITE(6,640)
NSP=MSWT(4)+1
WRITE(6,675) (I,YTH(I,4),SWLET(I,4),SWTET(I,4),I=1,NSP)
NDP=NHPT=NJPT
WRITE(6,680) NDP,MSWT(4),NCWT
----- OUTPUT THICKNESS SLOPES -----
4 CONTINUE
HEADING AND RIGHT WING DATA
WRITE(6,600)
WRITE(6,610)
WRITE(6,650)
MNE0
T=0
DO 5 JNW=1,NHPT,NCWT
MNE=MN+NCWT
I=I+1
WRITE(6,650) I,(THETA(J),J=JNW,MN)
5 CONTINUE
LEFT WING DATA IF NON-ZERO SIDESLIP AND WING ALONE
IF(.NOT.ASYM1) GO TO 20
WRITE(6,620)
WRITE(6,650)
IB0
NPP0=NRPT+1

```

```

DM24 30
DM24 31
DM24 32
DM24 33
DM24 34
DM24 35
DM24 36
DM24 37
DM24 38
DM24 39
DM24 40
DM24 41
DM24 42
DM24 43
DM24 44
DM24 45
DM24 46
DM24 47
DM24 48
DM24 49
DM24 50
DM24 51
DM24 52
DM24 53
DM24 54
DM24 55
DM24 56
DM24 57
DM24 58
DM24 59
DM24 60
DM24 61
DM24 62
DM24 63
DM24 64
DM24 65
DM24 66
DM24 67
DM24 68
DM24 69
DM24 70
DM24 71
DM24 72
DM24 73
DM24 74
DM24 75
DM24 76
DM24 77
DM24 78
DM24 79
DM24 80
DM24 81
DM24 82
DM24 83
DM24 84
DM24 85
DM24 86
DM24 87
DM24 88
DM24 89
DM24 90
DM24 91
DM24 92

```

	DO 10 JN=NRPP,NHPT,NCWT	DM24	93
	MN=MN+NCWT	DM24	94
	I=I+1	DM24	95
	WRITE(6,660) I,(THETA(J),J=JNW,MN)	DM24	96
	10 CONTINUE	DM24	97
C		DM24	98
C	UPPER WING DATA IF VERTICAL WINGS PRESENT	DM24	99
C		DM24	100
	20 CONTINUE	DM24	101
	IF(NVERT.EQ.0) GO TO 40	DM24	102
	WRITE(6,630)	DM24	103
	WRITE(6,650)	DM24	104
	I=0	DM24	105
	NHPP=NHPT+1	DM24	106
	DO 25 JN=NHPP,N3PT,NCWT	DM24	107
	MN=MN+NCWT	DM24	108
	I=I+1	DM24	109
	WRITE(6,660) I,(THETA(J),J=JNW,MN)	DM24	110
	25 CONTINUE	DM24	111
C		DM24	112
C	LOWER WING DATA IF NON=ZERO SIDESLIP AND WING ALONE.	DM24	113
C		DM24	114
	IF(.NOT. ASYMT) GO TO 40	DM24	115
	WRITE(6,640)	DM24	116
	WRITE(6,650)	DM24	117
	I=0	DM24	118
	N3PP=N3PT+1	DM24	119
	DO 30 JN=N3PP,NTHP,NCWT	DM24	120
	MN=MN+NCWT	DM24	121
	I=I+1	DM24	122
	WRITE(6,660) I,(THETA(J),J=JNW,MN)	DM24	123
	30 CONTINUE	DM24	124
C		DM24	125
C	DIVIDE INPUT SLOPES BY PI	DM24	126
C		DM24	127
	40 CONTINUE	DM24	128
	DO 45 J=1,NTHP	DM24	129
	45 THETA(J)=THETA(J)/PI	DM24	130
C		DM24	131
	RETURN	DM24	132
	END	DM24	133
	SUBROUTINE THKVEL(XX,YY,ZZ)	DM25	1
C		DM25	2
C		DM25	3
C	VERSION: DEMON1	DM25	4
C		DM25	5
C	THIS SUBROUTINE CALCULATES PERTURBATION VELOCITIES INDUCED BY	DM25	6
C	THE WING THICKNESS PANELS.	DM25	7
C	SUPERPOSITION OF 4 CORNER SOLUTIONS IS USED.	DM25	8
C	THKVEL RETURNS VELOCITIES UTH,VTH,WTH IN WING	DM25	9
C	REFERENCE FRAME.	DM25	10
C		DM25	11
C	LOGICAL NUPR,SDSLIP,VERPNL	DM25	12
C		DM25	13
	COMMON/THKDAT/HTDAT,NCWT,NTPR,MSWT(4),NRPT,NHPT,N3PT,NTHP,SDSLIP,	DM25	14
1	NVERT,SLLET(20,4),SLTET(20,4),YTH(20,4),THETA(400)	DM25	15
	COMMON/THKPAN/XRFT(400),XLFT(400),XRRT(400),XLRT(400),	DM25	16
1	YRCT(400),YLCT(400),ZRFT(400),ZLFT(400),ZRRT(400),	DM25	17
2	ZLRT(400),SLLET(400),SLTET(400)	DM25	18

```

COMMON/ICVEL/UPT,VPT,WPT,IIT,IFT,MJ
COMMON/THVARG/X,Y,Z,U,V,W,EM,VERPNL,NOPR
C
1 FORMAT(5X,5HPANEL,14,4X,6HCORNER,12,
1
1 ,3X,4HZ = E12.5/6X,4HU = ,E12.5,6X,4HV = ,E12.5,6X,4HW = ,E12.5/
2 5X,5HTU = ,E12.5,5X,5HTV = ,E12.5,5X,5HTW = ,E12.5)
2 FORMAT(//6H UPT =,E12.5,5X,5HVTU =,E12.5,5X,5HHTU =,E12.5)
C
NOPR=NTPR,NE,0
C
UPT=0.0
VPT=0.0
WPT=0.0
XI=XX
VI=YY
ZI=ZZ
C
I IS INDEX OF INFLUENCING PANEL
C
DO 100 I=IIT,IFT
VERPNL=I,GT,NHPT
MI=I
TI=0.
TV=0.
TW=0.
EM1=SLLET(I)
EM2=SLTET(I)
C
***** CORNER 1 *****
C
IF(EM1,LT,0.0) GO TO 15
EM=EM1
X=XI-XLFT(I)
Y=YI-YLCT(I)
Z=ZI-ZLFT(I)
CALL VELOTH
TU=TU+U
TV=TV+V
TW=TW+W
ICNR=1
MNJ=MJ
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW
IF(SOSLIP) GO TO 10
IF (VERPNL) GO TO 31
YB=(YI+YLCT(I))
CALL VELOTH
TU=TU+U
TV=TV+V
TW=TW+W
GO TO 32
31 ZB=(ZI+ZLFT(I))
CALL VELOTH
TU=TI+U
TV=TV+V
TW=TW+W
32 CONTINUE
MNJE=MJ
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW
GO TO 10
C
CORNER 1 FOR M .LT.0.0

```

C		DM25 82
	15 CONTINUE	DM25 83
	EM=EM1	DM25 84
	X=XI-XLFT(I)	DM25 85
	Y=YLCT(I)-YI	DM25 86
	Z=ZI-ZLFT(I)	DM25 87
	IF(VERPNL) GO TO 51	DM25 88
	CALL VELOTH	DM25 89
	TU=TI-U	DM25 90
	TV=TV+V	DM25 91
	TW=TW+W	DM25 92
	GO TO 52	DM25 93
	51 Y=-Y	DM25 94
	Z=-Z	DM25 95
	CALL VELOTH	DM25 96
	TU=TI-U	DM25 97
	TV=TV-V	DM25 98
	TW=TW+W	DM25 99
	52 CONTINUE	DM25 100
	ICNR=1	DM25 101
	MNJ=MJ	DM25 102
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM25 103
	IF(SDSLIP) GO TO 17	DM25 104
	IF(VERPNL) GO TO 41	DM25 105
	Y=YLCT(I)+YI	DM25 106
	CALL VELOTH	DM25 107
	TU=TI-U	DM25 108
	TV=TV+V	DM25 109
	TW=TW+W	DM25 110
	GO TO 42	DM25 111
C		DM25 112
	41 Z=ZLFT(I)+ZI	DM25 113
	CALL VELOTH	DM25 114
	TU=TI-U	DM25 115
	TV=TV-V	DM25 116
	TW=TW+W	DM25 117
	42 CONTINUE	DM25 118
	MNJ=MJ	DM25 119
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM25 120
	GO TO 17	DM25 121
	10 CONTINUE	DM25 122
C		DM25 123
C	***** CORNER 2 *****	DM25 124
C		DM25 125
	X=XI-XRFT(I)	DM25 126
	Y=YI-YRCT(I)	DM25 127
	Z=ZI-ZRFT(I)	DM25 128
	CALL VELOTH	DM25 129
	TU=TI-U	DM25 130
	TV=TV+V	DM25 131
	TW=TW+W	DM25 132
	ICNR=2	DM25 133
	MNJ=MJ	DM25 134
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM25 135
	IF(SDSLIP) GO TO 20	DM25 136
	IF(VERPNL) GO TO 33	DM25 137
	Y=(YI+YRCT(I))	DM25 138
	CALL VELOTH	DM25 139
	TU=TI-U	DM25 140
	TV=TV+V	DM25 141
	TW=TW+W	DM25 142
	GO TO 34	DM25 143
	33 Z=(ZI+ZRFT(I))	DM25 144
	CALL VELOTH	DM25 145

	TU=U	0425 146
	TV=V	0425 147
	TW=W	0425 148
34	CONTINUE	0425 149
	MNJ=MJ	0425 150
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	0425 151
	GO TO 20	0425 152
C		0425 153
C	CORNER 2 FOR M.LT. 0	0425 154
C		0425 155
17	CONTINUE	0425 156
	X=XI-XRFT(I)	0425 157
	Y=YRFT(I)-YI	0425 158
	Z=ZI-ZRFT(I)	0425 159
	IF(VERPML) GO TO 53	0425 160
	CALL VELOTH	0425 161
	TU=U	0425 162
	TV=V	0425 163
	TW=W	0425 164
	GO TO 54	0425 165
53	Y=Y	0425 166
	Z=Z	0425 167
	CALL VELOTH	0425 168
	TU=U	0425 169
	TV=V	0425 170
	TW=W	0425 171
54	CONTINUE	0425 172
	ICNR=2	0425 173
	MNJ=MJ	0425 174
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	0425 175
	IF(SDSLIP) GO TO 20	0425 176
	IF(VERPML) GO TO 43	0425 177
	Y=YRFT(I)+YI	0425 178
	CALL VELOTH	0425 179
	TU=U	0425 180
	TV=V	0425 181
	TW=W	0425 182
	GO TO 44	0425 183
43	Z=ZRFT(I)+ZI	0425 184
	CALL VELOTH	0425 185
	TU=U	0425 186
	TV=V	0425 187
	TW=W	0425 188
44	CONTINUE	0425 189
	MNJ=MJ	0425 190
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	0425 191
20	CONTINUE	0425 192
C		0425 193
C	***** CORNER 3 *****	0425 194
C		0425 195
	IF(EM2.LT.0.0) GO TO 19	0425 196
	EM=EM2	0425 197
	X=XI-XLRT(I)	0425 198
	Y=YI-YLCT(I)	0425 199
	Z=ZI-ZLRT(I)	0425 200
	CALL VELOTH	0425 201
	TU=U	0425 202
	TV=V	0425 203
	TW=W	0425 204
	ICNR=3	0425 205
	MNJ=MJ	0425 206
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	0425 207
	IF(SDSLIP) GO TO 30	0425 208

IF (VERPNL) GO TO 35	DM25 209
Y=YI+YLCI(I)	DM25 210
CALL VELOTH	DM25 211
TU=TU+U	DM25 212
TV=TV+V	DM25 213
TW=TW+W	DM25 214
GO TO 36	DM25 215
35 Z=ZI+ZLCI(I)	DM25 216
CALL VELOTH	DM25 217
TU=TU+U	DM25 218
TV=TV+V	DM25 219
TW=TW+W	DM25 220
36 CONTINUE	DM25 221
MNJ=MJ	DM25 222
IF(NOPR) WRITE(6,1) MI, ICNR, MNJ, X, Y, Z, U, V, W, TU, TV, TW	DM25 223
GO TO 30	DM25 224
C	DM25 225
C	DM25 226
C	DM25 227
19 CORNER 3 FOR M .LT. 0	DM25 228
19 CONTINUE	DM25 229
EM=EM2	DM25 230
X=XI-XLCI(I)	DM25 231
Y=YLCI(I)-YI	DM25 232
Z=ZI-ZLCI(I)	DM25 233
IF (VERPNL) GO TO 55	DM25 234
CALL VELOTH	DM25 235
TU=TU+U	DM25 236
TV=TV+V	DM25 237
TW=TW+W	DM25 238
GO TO 56	DM25 239
55 Y=Y	DM25 240
Z=Z	DM25 241
CALL VELOTH	DM25 242
TU=TU+U	DM25 243
TV=TV+V	DM25 244
TW=TW+W	DM25 245
56 CONTINUE	DM25 246
ICNR=3	DM25 247
MNJ=MJ	DM25 248
IF(NOPR) WRITE(6,1) MI, ICNR, MNJ, X, Y, Z, U, V, W, TU, TV, TW	DM25 249
IF(SDSLIP) GO TO 21	DM25 250
IF(VERPNL) GO TO 45	DM25 251
Y=YLCI(I)+YI	DM25 252
CALL VELOTH	DM25 253
TU=TU+U	DM25 254
TV=TV+V	DM25 255
TW=TW+W	DM25 256
GO TO 46	DM25 257
45 Z=ZLCI(I)+ZI	DM25 258
CALL VELOTH	DM25 259
TU=TU+U	DM25 260
TV=TV+V	DM25 261
TW=TW+W	DM25 262
46 CONTINUE	DM25 263
MNJ=MJ	DM25 264
IF(NOPR) WRITE(6,1) MI, ICNR, MNJ, X, Y, Z, U, V, W, TU, TV, TW	DM25 265
GO TO 21	DM25 266
30 CONTINUE	DM25 267
C	DM25 268
C ***** CORNER 4 *****	DM25 269
C	DM25 270
Y=YI-YRCI(I)	DM25 271
V=YI-YRCI(I)	DM25 272
Z=ZI-ZRCI(I)	DM25 273

CALL VELOTH	0425 273
TU=TV+U	0425 274
TV=TV+V	0425 275
T=TW+W	0425 276
ICNR=4	0425 277
MNJ=MJ	0425 278
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	0425 279
IF(SDSLIP) GO TO 40	0425 280
IF(VERPNL) GO TO 37	0425 281
Y=VI+YRCT(I)	0425 282
CALL VELOTH	0425 283
TU=TV+U	0425 284
TV=TV+V	0425 285
T=TW+W	0425 286
GO TO 38	0425 287
37 Z=ZI+ZRRT(I)	0425 288
CALL VELOTH	0425 289
TU=TV+U	0425 290
TV=TV+V	0425 291
T=TW+W	0425 292
38 CONTINUE	0425 293
MNJ=MJ	0425 294
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	0425 295
GO TO 40	0425 296
C	0425 297
C	0425 298
C	0425 299
21 CONTINUE	0425 300
X=XI-XRRT(I)	0425 301
Y=YRCT(I)-YI	0425 302
Z=ZI-ZRRT(I)	0425 303
IF(VERPNL) GO TO 57	0425 304
CALL VELOTH	0425 305
TU=TV+U	0425 306
TV=TV+V	0425 307
T=TW+W	0425 308
GO TO 58	0425 309
57 Y=V	0425 310
Z=Z	0425 311
CALL VELOTH	0425 312
TU=TV+U	0425 313
TV=TV+V	0425 314
T=TW+W	0425 315
58 CONTINUE	0425 316
ICNR=4	0425 317
MNJ=MJ	0425 318
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	0425 319
IF(SDSLIP) GO TO 40	0425 320
IF(VERPNL) GO TO 47	0425 321
V=YI+YRCT(I)	0425 322
CALL VELOTH	0425 323
TU=TV+U	0425 324
TV=TV+V	0425 325
T=TW+W	0425 326
GO TO 48	0425 327
47 Z=ZRRT(I)+ZI	0425 328
CALL VELOTH	0425 329
TU=TV+U	0425 330
TV=TV+V	0425 331
T=TW+W	0425 332

4A	CONTINUE	DM25	333
	MNJ=-MJ	DM25	334
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TK	DM25	335
4B	CONTINUE	DM25	336
C		DM25	337
	UPT=UPT+TU*THEAL(I)	DM25	338
	VPT=VPT+TV*THEAL(I)	DM25	339
	WPT=WPT+TW*THEAL(I)	DM25	340
100	CONTINUE	DM25	341
C		DM25	342
	IF(NOPR) WRITE(6,2) UPT,VPT,WPT	DM25	343
C		DM25	344
	RETURN	DM25	345
	END	DM25	346
	SUBROUTINE TRHIP=(YI,ZI,YO,ZO,I)	DM26	1
C		DM26	2
C	VERSION: DEMON1	DM26	3
C		DM26	4
C	THIS SUBROUTINE TRANSFORMS COORDINATES AND VELOCITIES FROM WING	DM26	5
C	COORDINATE SYSTEM TO INTERFERENCE PANEL COORDINATE SYSTEM AND	DM26	6
C	VICE VERSA.	DM26	7
C		DM26	8
	LOGICAL ASYM,BODY,DELTA,NOSYM	DM26	9
C		DM26	10
	COMMON/ONE/DUM1(5500),SNT(125),CST(125),SNT2(125),CST2(125),	DM26	11
	IIP(300),YFBIP(100),DUM2(12),DX,DUM3(2),RB,DUM4(12),WHIP,DUM5(11),	DM26	12
	ZHBIP,DUM6(10),NPANLS,NPRESS,NWHP,ASYM,BODY,DELTA,NOSYM	DM26	13
C		DM26	14
	DIMENSION YLC(250),ZLF(250)	DM26	15
	EQUIVALENCE (YLC(1),DUM1(4001)), (ZLF(1),DUM1(4501))	DM26	16
C		DM26	17
C	TRANSFORM FROM HIP TO WING COORDINATES	DM26	18
C		DM26	19
	INP=I+NPANLS	DM26	20
	YO=YI*CST2(I) + ZI*SNT2(I) + YLC(INP)	DM26	21
	ZO=ZI*CST2(I) - YI*SNT2(I) + ZLF(INP)	DM26	22
	RETURN	DM26	23
C		DM26	24
C	TRANSFORM FROM WING TO HIP COORDINATES	DM26	25
C		DM26	26
	ENTRY TRWHIP	DM26	27
	INP=I+NPANLS	DM26	28
	ZC=ZI-ZLF(INP)	DM26	29
	YC=YI-YLC(INP)	DM26	30
10	YO=YC*CST2(I) + ZC*SNT2(I)	DM26	31
	ZO=ZC*CST2(I) + YC*SNT2(I)	DM26	32
	RETURN	DM26	33
C		DM26	34
C	VELOCITY TRANSFORM == HIP TO WING	DM26	35
C		DM26	36
	ENTRY ROTW	DM26	37
	YO=YI*CST2(I) + ZI*SNT2(I)	DM26	38
	ZO=ZI*CST2(I) - YI*SNT2(I)	DM26	39
	RETURN	DM26	40
C		DM26	41
C	WING TO HIP VELOCITY TRANSFORM	DM26	42
C		DM26	43
	ENTRY ROTWH	DM26	44
	ZC=ZI	DM26	45
	YC=YI	DM26	46

	GO TO 10	0426	47
	END	0426	48
	SUBROUTINE VELCAL(NDIM,ALPHA,BETA,NSTART)	0427	1
C	VERSION: DEMON1	0427	2
C	SUBROUTINE TO CALCULATE THE VELOCITIES FOR THE FIELD POINTS X,Y,Z DUE	0427	3
C	TO THE BODY SINGULARITIES.	0427	4
C		0427	5
C	DIMENSION X(150),YY(150),ZZ(150)	0427	6
C		0427	7
C	LOGICAL ASYM,BODY,DELTA,NOSYM	0427	8
C		0427	9
C	COMMON/ONE/CIRC(250),DUM1(500),PNLC(250),DUM2(500),VWNR(250),	0427	10
C	1XPR(250),ZHR(250),DUMR(750),	0427	11
C	DUM3(2500),DUM4(904),	0427	12
C	ZHP,H2V,DUM5(5),CN,DUMA(24),MSWR,MSWL,MSWD,MSWD,DUM7(2),NCL,NDRAG,	0427	13
C	3MRP,NRP,NRP,N3P,DUM8(6),ASYM,BODY,DELTA,NOSYM	0427	14
C	COMMON/TAO/TX(101),DUM9(505),DUMZZ(403),T(100),TC(100),COEFF(5),	0427	15
C	IRCODE,BETASQ,BSD,RADIUS,RFIELD,RNOSE,U,V,VT,XA,XB,XC,XD,XFIELD,X2,	0427	16
C	ZLBODY,NXRBDY	0427	17
C	COMMON/RVEL/RI(150),VI(150),WI(150),XFLOP(150),YFLOP(150),	0427	18
C	ZFLOP(150)	0427	19
C	COMMON/WTR/THTI(125),X*LE	0427	20
C		0427	21
C	REAL LBODY	0427	22
C	INTEGER BCODE	0427	23
C		0427	24
C		0427	25
C		0427	26
C		0427	27
C		0427	28
C		0427	29
C		0427	30
C		0427	31
C		0427	32
C		0427	33
C		0427	34
C		0427	35
C		0427	36
C		0427	37
C		0427	38
C		0427	39
C		0427	40
C		0427	41
C		0427	42
C		0427	43
C		0427	44
C		0427	45
C		0427	46
C		0427	47
C		0427	48
C		0427	49
C		0427	50
C		0427	51
C		0427	52
C		0427	53
C		0427	54
C		0427	55
C		0427	56
C		0427	57
C		0427	58

	NSQ=METASQ+RFIELD*RFIELD	DM27	59
	XZ=XFIELD*LBODY	DM27	60
C		DM27	61
	US=0.	DM27	62
	VS=0.	DM27	63
	UD=0.	DM27	64
	VD=0.	DM27	65
	VTD=0.	DM27	66
	DO 110 J=1,N	DM27	67
	CALL SOURCE(J)	DM27	68
	US=US+T(J)*U	DM27	69
	VS=VS+T(J)*V	DM27	70
	CALL ORUET(J)	DM27	71
	UD=UD+U*TC(J)	DM27	72
	VD=VD+V*TC(J)	DM27	73
	110 VTD=VTD+VT*TC(J)	DM27	74
C		DM27	75
C	TRANSFORMATION OF VELOCITIES INTO BODY COORDINATE SYSTEM.	DM27	76
C	U,V,W, RATHER THAN U,VR,VTHETA.	DM27	77
C		DM27	78
	COSTH=COS(THPLPH)	DM27	79
	U1(I)=US+UD*COSTH	DM27	80
	VR=VD*COSTH+VS	DM27	81
	VTD=VTD*SIN(THPLPH)	DM27	82
	SINTH=SIN(THETA)	DM27	83
C		DM27	84
C	AT THIS STAGE U1,VR,VTD ARE THE LONGITUDINAL,RADIAL AND TANGENTIAL	DM27	85
C	VELOCITY COMPONENTS IN THE BODY CYLINDRICAL COORDINATE SYSTEM.	DM27	86
C	NEXT,TRANSFORM INTO RECTANGULAR BODY COORDINATE SYSTEM.	DM27	87
C		DM27	88
	COSTH=COS(THETA)	DM27	89
	V1(I)=VR*SINTH+VTD*COSTH	DM27	90
	W1(I)=VR*COSTH+VTD*SINTH	DM27	91
	IF (ABS(U1(I)).LT.1.0E-06) U1(I)=0.0	DM27	92
	IF (ABS(V1(I)).LT.1.0E-06) V1(I)=0.0	DM27	93
	IF (ABS(W1(I)).LT.1.0E-06) W1(I)=0.0	DM27	94
	100 CONTINUE	DM27	95
	RETURN	DM27	96
	END	DM27	97
	SUBROUTINE VELNOR(XX,YY,ZZ)	DM28	1
C		DM28	2
C	VERSION: DEMUNI	DM28	3
C		DM28	4
C	THIS SUBROUTINE CALCULATES PERTURBATION VELOCITIES INDUCED BY	DM28	5
C	THE WING AND BODY INTERFERENCE PANELS USING SUPERPOSITION SCHEME	DM28	6
C	SUPERPOSITION OF 4 CORNER SOLUTIONS IS USED	DM28	7
C	VELNOR RETURNS VELOCITIES UP,VP,WP IN WING REFERENCE FRAME...	DM28	8
C		DM28	9
C	LOGICAL ASYM,ASYMI,DELTA,BODY,NOSYM,IGTNP,NOPR	DM28	10
C		DM28	11
	COMMON/DNE/CIRC(250),DELTP(250),FN(250),PNLC(250),SWPPLE(250),	DM28	12
	13*PPT(250),DUM1(1000),YCPT(250),ZCPT(250),YLF(250),XLR(250),	DM28	13
	2XRF(250),XWB(250),YLC(250),YRC(250),ZLF(250),ZRF(250),ZLR(250),	DM28	14
	3ZRR(250),ANT(125),CST(125),DUM2(550),	DM28	15
	3 XFRIP(100),A,ALFA,ALFR,AWING,H2,B2V,HETA,	DM28	16
	4HETA,CONST,COSALF,COSBET,CN,DX,EM,FMACH,WR,SINALF,SINBET,SLOPE,	DM28	17
	5TLRNC,TIPY,TOTLR,U,V,W,UP,VP,WP,WIP,X,Y,Z,XT,IF,II,MJ,MSWK,MSWL,	DM28	18
	6MSWU,MSWD,MSIP,MSRX,MSY,MSWAG,MSWP,MSRP,MSIP,MSOCT,MSLINP,MSOUT,	DM28	19
	7NPANLS,NPRESS,NWPP,ASYMI,BODY,DELTA,NOSYM	DM28	20
C		DM28	21

COMMON/WHTR/THTI(125),X*LE	DM28	22
COMMON /INTRDT/ PHIDIH,THETIT,YH00,ZB00,PHIFR,PHIFU	DM28	23
C	DM28	24
DATA PI/3,141592653590/	DM28	25
C	DM28	26
1 FORMAT(5X,5HPANEL,I4,6X,6HCORNER,I2,	DM28	27
1 6X,4MC,P,,15,3X,4HY = ,E12,5,3X,4HY = ,E12,5	DM28	28
1 3X,4HZ = E12,5/6X,4HU = ,E12,5,6X,4HV = ,E12,5,6X,4HW = ,E12,5/	DM28	29
2 5X,5HTU = ,E12,5,5X,5HTV = ,E12,5,5X,5HTW = ,E12,5)	DM28	30
2 FORMAT(1X,7HASYM = ,L3)	DM28	31
C	DM28	32
ASYM= N0SYM	DM28	33
N0PR= (NPR,NE,0)	DM28	34
DTOR=PI/180,0	DM28	35
C	DM28	36
UP=0.	DM28	37
VP=0.	DM28	38
WP=0.	DM28	39
XI=XX	DM28	40
YI=YY	DM28	41
ZI=ZZ	DM28	42
C	DM28	43
I IS INDEX OF INFLUENCING PANEL	DM28	44
C	DM28	45
DD 100 I=II,IF	DM28	46
IGTNP= I,GT,NPANLS	DM28	47
K=I-NPANLS	DM28	48
MI=I	DM28	49
TU=0.	DM28	50
TV=0.	DM28	51
TW=0.	DM28	52
EM1=SWPPLE(I)	DM28	53
EM2=SWPPTE(I)	DM28	54
C	DM28	55
C***** CORNER 1 *****	DM28	56
C	DM28	57
C	DM28	58
C	DM28	59
C IF INFLUENCER IS A BODY INTERFERENCE PANEL,SUPERPOSITION IS	DM28	60
C PERFORMED IN THE WING SYSTEM , SAME FOR INTERDIGITATED FINS.	DM28	61
C NOTE: BODY INTERFERENCE PANELS IN 2ND, AND 4TH, QUARTERS ACT LIKE	DM28	62
C WING PANELS WITH NEGATIVE SWEEP	DM28	63
C	DM28	64
IF (I,LE,NPANLS) GO TO 60	DM28	65
IF ((THTI(K),GT,90,0,AND,THTI(K),LE,180,0),OR,	DM28	66
1(THTI(K),GT,270,0,AND,THTI(K),LE,360,0)) GO TO 15	DM28	67
60 CONTINUE	DM28	68
IF (I,LE,NHP) PHIF=PHIFR*DTOR	DM28	69
IF (I,GT,NHP,AND,I,LE,NPANLS) PHIF=PHIFH*DTOR	DM28	70
IF (EM1,LT,0,0) GO TO 15	DM28	71
SLOPE=PMI	DM28	72
EM=EM1	DM28	73
X=XI-XLF(I)	DM28	74
Y=YI-YLC(I)	DM28	75
Z=ZI-ZLF(I)	DM28	76
IF (ARS(X),LE,TLRNC) X=0,0	DM28	77
IF (ARS(YT),LE,TLRNC) YT=0,0	DM28	78
IF (ARS(ZT),LE,TLRNC) ZT=0,0	DM28	79
Y=YT	DM28	80
Z=ZT	DM28	81
IF (,NOT,IGTNP) CALL ROTWF(YT,ZT,Y,Z,PHIF)	DM28	82
C	DM28	83
C FOR PANELS WITH POSITIVE SWEEP,SUPERPOSITION IS CORNER 1=2+3+4.	DM28	84

C		DM2A	85
C	IF INFLUENCER IS A BODY INFLUENCING PANEL, TRANSFORM KING Y,Z	DM2A	86
C	COORDINATES INTO BIP COORDINATE SYSTEM, ONLY NEED TO ROTATE SINCE	DM2A	87
C	ORIGIN IS ALREADY AT BIP CORNER	DM2A	88
C	THEN TRANSFORM VELOCITIES FROM BIP FRAME BACK TO KING, SAME FOR	DM2A	89
C	INTERDIGITATED FINS.	DM2A	90
C		DM2A	91
	IF (IGTNP) CALL ROTNH(Y*,Z*,Y,Z,K)	DM2A	92
	CALL VELO	DM2A	93
	VB=V	DM2A	94
	WB=W	DM2A	95
	VT=V	DM2A	96
	WT=W	DM2A	97
	IF (.NOT.IGTNP) CALL ROTF=(VT,WT,V,W,PHIF)	DM2A	98
	IF (IGTNP) CALL ROTNH(VB,WB,V,W,K)	DM2A	99
	TU=TU+U	DM2A	100
	TV=TV+V	DM2A	101
	TW=TW+W	DM2A	102
	ICNR=I	DM2A	103
	MNJ=MJ	DM2A	104
	IF (NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM2A	105
	IF (NOPR) WRITE(6,2) ASYM	DM2A	106
	IF (ASYM) GO TO 10	DM2A	107
	YT=(YI+YLC(I))	DM2A	108
	Y=BYT	DM2A	109
	IF (.NOT.IGTNP) CALL ROTMF(YT,ZT,Y,Z,PHIF)	DM2A	110
	IF (IGTNP) CALL ROTNH(Y*,Z*,Y,Z,K)	DM2A	111
	CALL VELO	DM2A	112
	VB=V	DM2A	113
	WB=W	DM2A	114
	VT=V	DM2A	115
	WT=W	DM2A	116
	IF (.NOT.IGTNP) CALL ROTF=(VT,WT,V,W,PHIF)	DM2A	117
	IF (IGTNP) CALL ROTNH(VB,WB,V,W,K)	DM2A	118
	TU=TU+U	DM2A	119
	TV=TV+V	DM2A	120
	TW=TW+W	DM2A	121
	MNJ=MJ	DM2A	122
	IF (NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM2A	123
	GO TO 10	DM2A	124
		DM2A	125
		DM2A	126
	FOR PANELS WITH NEGATIVE SWEEP, SUPERPOSITION IS CORNER -1+2+3=4	DM2A	127
		DM2A	128
	CORNER 1 FOR M .LT. 0.0	DM2A	129
		DM2A	130
	15 CONTINUE	DM2A	131
	SLOPE=EM1	DM2A	132
	F=FM1	DM2A	133
	X=XI-XLF(I)	DM2A	134
	Y=YI+YLC(I)	DM2A	135
	Z=ZI-ZLF(I)	DM2A	136
	IF (ABS(X).LE.TLRNC) X=0.0	DM2A	137
	IF (ABS(YT).LE.TLRNC) YT=0.0	DM2A	138
	IF (ABS(ZT).LE.TLRNC) ZT=0.0	DM2A	139
	Y=BYT	DM2A	140
	Z=BYZT	DM2A	141
	IF (.NOT.IGTNP) CALL ROTMF(YT,ZT,Y,Z,PHIF)	DM2A	142
	IF (IGTNP) CALL ROTNH(Y*,Z*,Y,Z,K)	DM2A	143
	Y=BY	DM2A	144
	CALL VELO	DM2A	145
	VT=V	DM2A	146
	WT=W	DM2A	147

VR=V	DM2A 148
WR=W	DM2A 149
IF (.NOT.IGTNP) CALL ROTF*(VT,WT,V,W,PHIF)	DM2A 150
IF (IGTNP) CALL ROTB*(VH,WH,V,W,K)	DM2A 151
TU=TU-U	DM2A 152
TV=TV-V	DM2A 153
TW=TW-W	DM2A 154
ICNR=1	DM2A 155
MNJ=MJ	DM2A 156
IF (NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM2A 157
IF (ASYM) GO TO 17	DM2A 158
YT=(YI+YLC(I))	DM2A 159
Y=YT	DM2A 160
IF (.NOT.IGTNP) CALL ROTWF*(YT,ZT,Y,Z,PHIF)	DM2A 161
IF (IGTNP) CALL ROTWH*(YH,ZH,Y,Z,K)	DM2A 162
VS=V	DM2A 163
CALL VELO	DM2A 164
VT=V	DM2A 165
WT=W	DM2A 166
VB=V	DM2A 167
WB=W	DM2A 168
IF (.NOT.IGTNP) CALL ROTFX*(VT,WT,V,W,PHIF)	DM2A 169
IF (IGTNP) CALL ROTB*(VH,WH,V,W,K)	DM2A 170
TU=TU-U	DM2A 171
TV=TV-V	DM2A 172
TW=TW-W	DM2A 173
MNJ=MJ	DM2A 174
IF (NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM2A 175
GO TO 17	DM2A 176
10 CONTINUE	DM2A 177
C	DM2A 178
C ***** CORNER 2 *****	DM2A 179
C	DM2A 180
X=XI-XRF(I)	DM2A 181
Y=YI-YRC(I)	DM2A 182
Z=ZI-ZRF(I)	DM2A 183
IF (ABS(X),LE,TLRNC) X=0.0	DM2A 184
IF (ABS(Y),LE,TLRNC) Y=0.0	DM2A 185
IF (ABS(Z),LE,TLRNC) Z=0.0	DM2A 186
Y=YT	DM2A 187
Z=ZT	DM2A 188
IF (.NOT.IGTNP) CALL ROTWF*(YT,ZT,Y,Z,PHIF)	DM2A 189
IF (IGTNP) CALL ROTWH*(YH,ZH,Y,Z,K)	DM2A 190
CALL VELO	DM2A 191
VS=V	DM2A 192
WB=W	DM2A 193
VT=V	DM2A 194
WT=W	DM2A 195
IF (.NOT.IGTNP) CALL ROTFX*(VT,WT,V,W,PHIF)	DM2A 196
IF (IGTNP) CALL ROTB*(VH,WH,V,W,K)	DM2A 197
TU=TU-U	DM2A 198
TV=TV-V	DM2A 199
TW=TW-W	DM2A 200
ICNR=2	DM2A 201
MNJ=MJ	DM2A 202
IF (NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM2A 203
IF (ASYM) GO TO 20	DM2A 204
YT=(YI+YRC(I))	DM2A 205
Y=YT	DM2A 206
IF (.NOT.IGTNP) CALL ROTWF*(YT,ZT,Y,Z,PHIF)	DM2A 207
IF (IGTNP) CALL ROTWH*(YH,ZH,Y,Z,K)	DM2A 208
CALL VELO	DM2A 209
VH=V	DM2A 210

	WRBW	0428 211
	VTBV	0428 212
	WTBW	0428 213
	IF (,NOT,IGTNP) CALL ROTF*(VT,WT,V,W,PHIF)	0428 214
	IF (IGTNP) CALL ROTH*(VH,*B,V,W,K)	0428 215
	TU=U+U	0428 216
	TV=TV+V	0428 217
	TW=TW+W	0428 218
	MNJ=M+J	0428 219
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	0428 220
	GO TO 20	0428 221
C		0428 222
C	CORNER 2 FOR M .LT. 0	0428 223
C		0428 224
	17 CONTINUE	0428 225
	X=XI-XRF(I)	0428 226
	Y=YI-YRC(I)	0428 227
	Z=ZI-ZRF(I)	0428 228
	IF (ABS(X),LE,TLRNC) X=0.0	0428 229
	IF (ABS(Y),LE,TLRNC) Y=0.0	0428 230
	IF (ABS(Z),LE,TLRNC) Z=0.0	0428 231
	Y=BYT	0428 232
	Z=ZT	0428 233
	IF (,NOT,IGTNP) CALL ROTF*(YT,ZT,Y,Z,PHIF)	0428 234
	IF (IGTNP) CALL ROTH*(YW,ZW,Y,Z,K)	0428 235
	Y=Y	0428 236
	CALL VELO	0428 237
	VT=V	0428 238
	WT=W	0428 239
	VR=V	0428 240
	WR=W	0428 241
	IF (,NOT,IGTNP) CALL ROTF*(VT,WT,V,W,PHIF)	0428 242
	IF (IGTNP) CALL ROTH*(VH,*B,V,W,K)	0428 243
	TU=U+U	0428 244
	TV=TV+V	0428 245
	TW=TW+W	0428 246
	ICNR=2	0428 247
	MNJ=M+J	0428 248
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	0428 249
	IF(ASYM) GO TO 20	0428 250
	YI=(YI+YRC(I))	0428 251
	Y=BYT	0428 252
	IF (,NOT,IGTNP) CALL ROTF*(YT,ZI,Y,Z,PHIF)	0428 253
	IF (IGTNP) CALL ROTH*(YH,*B,Y,Z,K)	0428 254
	Y=Y	0428 255
	CALL VELO	0428 256
	VT=V	0428 257
	WT=W	0428 258
	VR=V	0428 259
	WR=W	0428 260
	IF (,NOT,IGTNP) CALL ROTF*(VT,WT,V,W,PHIF)	0428 261
	IF (IGTNP) CALL ROTH*(VH,*B,V,W,K)	0428 262
	TU=U+U	0428 263
	TV=TV+V	0428 264
	TW=TW+W	0428 265
	MNJ=M+J	0428 266
	IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	0428 267
	20 CONTINUE	0428 268
C		0428 269
C	***** CORNER 3 *****	0428 270
C		0428 271
	IF (I,LE,NPANLS) GO TO 61	0428 272
	IF ((TMTI(K),GT,90.0,AND,TMTI(K),LE,180.0),OR,	0428 273

```

1(TMTI(K),GT,270,0,AND,TMTI(K),LE,360,0)) GO TO 19
61 IF (EM2,LT,0.0) GO TO 19
EM=EM2
SLOPE=EM2
X=XI-XLH(I)
Y=YI-YLC(I)
Z=ZI-ZLB(I)
Y=YI
IF (ABS(X),LE,TLRNC) X=0,0
IF (ABS(Y),LE,TLRNC) Y=0,0
IF (ABS(Z),LE,TLRNC) Z=0,0
Z=ZT
IF (.NOT,IGTNP) CALL ROTWF(YT,ZT,Y,Z,PHIF)
IF (IGTNP) CALL ROTWB(YW,ZW,Y,Z,K)
CALL VELO
VB=V
WB=W
VT=V
WT=W
IF (.NOT,IGTNP) CALL ROTWF(VT,WT,V,W,PHIF)
IF (IGTNP) CALL ROTWB(VB,WB,V,W,K)
TU=U
TV=TV+V
TW=TW+W
ICNR=3
MNJ=MJ
IF (NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW
IF (ASYM) GO TO 30
YI=YI+YLC(I)
Y=YI
IF (.NOT,IGTNP) CALL ROTWF(YT,ZT,Y,Z,PHIF)
IF (IGTNP) CALL ROTWB(YW,ZW,Y,Z,K)
CALL VELO
VB=V
WB=W
VT=V
WT=W
IF (.NOT,IGTNP) CALL ROTWF(VT,WT,V,W,PHIF)
IF (IGTNP) CALL ROTWB(VB,WB,V,W,K)
TU=U
TV=TV+V
TW=TW+W
MNJ=MJ
IF (NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW
GO TO 30
C
C CORNER 3 FOR M .LT. 0
C
19 CONTINUE
SLOPE=EM2
EM=EM2
X=XI-XLH(I)
Y=YI-YLC(I)
Z=ZI-ZLB(I)
IF (ABS(X),LE,TLRNC) X=0,0
IF (ABS(Y),LE,TLRNC) Y=0,0
IF (ABS(Z),LE,TLRNC) Z=0,0
Y=YI
Z=ZT
IF (.NOT,IGTNP) CALL ROTWF(YT,ZT,Y,Z,PHIF)
IF (IGTNP) CALL ROTWB(YW,ZW,Y,Z,K)
Y=V
CALL VELO

```

```

0428 274
0428 275
0428 276
0428 277
0428 278
0428 279
0428 280
0428 281
0428 282
0428 283
0428 284
0428 285
0428 286
0428 287
0428 288
0428 289
0428 290
0428 291
0428 292
0428 293
0428 294
0428 295
0428 296
0428 297
0428 298
0428 299
0428 300
0428 301
0428 302
0428 303
0428 304
0428 305
0428 306
0428 307
0428 308
0428 309
0428 310
0428 311
0428 312
0428 313
0428 314
0428 315
0428 316
0428 317
0428 318
0428 319
0428 320
0428 321
0428 322
0428 323
0428 324
0428 325
0428 326
0428 327
0428 328
0428 329
0428 330
0428 331
0428 332
0428 333
0428 334
0428 335
0428 336

```


VT=V	DM2A 337
WT=W	DM2A 338
VH=V	DM2A 339
WH=W	DM2A 340
IF (.NOT.IGTNP) CALL ROTFX(VT,WT,V,W,PHIF)	DM2A 341
IF (IGTNP) CALL ROTHW(VB,WB,V,W,K)	DM2B 342
TU=TU+U	DM2B 343
TV=TV+V	DM2B 344
TW=TW+W	DM2A 345
ICNR=3	DM2A 346
MNJ=MJ	DM2A 347
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM2B 348
IF(ASYM) GO TO 21	DM2A 349
YT=(YI+YLC(I))	DM2A 350
Y=YT	DM2A 351
IF (.NOT.IGTNP) CALL ROTWF(YT,ZT,Y,Z,PHIF)	DM2A 352
IF (IGTNP) CALL ROTWB(YW,ZW,Y,Z,K)	DM2A 353
Y=Y	DM2A 354
CALL VELO	DM2A 355
VB=V	DM2B 356
WB=W	DM2A 357
VT=V	DM2B 358
WT=W	DM2B 359
IF (.NOT.IGTNP) CALL ROTFX(VT,WT,V,W,PHIF)	DM2A 360
IF (IGTNP) CALL ROTHW(VB,WB,V,W,K)	DM2B 361
TU=TU+U	DM2A 362
TV=TV+V	DM2B 363
TW=TW+W	DM2A 364
MNJ=MJ	DM2B 365
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM2A 366
GO TO 21	DM2B 367
30 CONTINUE	DM2A 368
C	DM2B 369
C***** CORNER 4 *****	DM2B 370
C	DM2A 371
X=XI-XRB(I)	DM2B 372
YT=YI-YRC(I)	DM2B 373
ZT=ZI-ZRB(I)	DM2B 374
IF (ABS(X),LE,TLRNC) X=0.0	DM2B 375
IF (ABS(YT),LE,TLRNC) YT=0.0	DM2A 376
IF (ABS(ZT),LE,TLRNC) ZT=0.0	DM2B 377
Y=YT	DM2B 378
Z=ZT	DM2A 379
IF (.NOT.IGTNP) CALL ROTWF(YT,ZT,Y,Z,PHIF)	DM2B 380
IF (IGTNP) CALL ROTWB(YW,ZW,Y,Z,K)	DM2A 381
CALL VELO	DM2B 382
VB=V	DM2B 383
WB=W	DM2B 384
VT=V	DM2B 385
WT=W	DM2A 386
IF (.NOT.IGTNP) CALL ROTFX(VT,WT,V,W,PHIF)	DM2B 387
IF (IGTNP) CALL ROTHW(VB,WB,V,W,K)	DM2A 388
TU=TU+U	DM2B 389
TV=TV+V	DM2B 390
TW=TW+W	DM2A 391
ICNR=4	DM2B 392
MNJ=MJ	DM2B 393
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW	DM2A 394
IF(ASYM) GO TO 40	DM2B 395
YT=(YI+YRC(I))	DM2B 396
Y=YT	DM2A 397
IF (.NOT.IGTNP) CALL ROTWF(YT,ZT,Y,Z,PHIF)	DM2B 398
IF (IGTNP) CALL ROTWB(YW,ZW,Y,Z,K)	DM2B 399
CALL VELO	DM2B 400

VT=V		DM28	401
*TW		DM28	402
IF (.NOT.IGTNP) CALL ROTFW(VT,WT,V,W,PHIF)		DM28	403
IF (IGTNP) CALL ROTHW(VB,WB,V,W,K)		DM28	404
TU=U+U		DM28	405
TV=TV+V		DM28	406
T=TW+W		DM28	407
MNJ=MJ		DM28	408
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW		DM28	409
GO TO 40		DM28	410
C		DM28	411
C		DM28	412
C		DM28	413
21 CONTINUE		DM28	414
X=XI-XRR(I)		DM28	415
YI=YI-YRC(I)		DM28	416
ZI=ZI-ZRH(I)		DM28	417
IF (ABS(X).LE.TLRNC) X=0.0		DM28	418
IF (ABS(YI).LE.TLRNC) YI=0.0		DM28	419
IF (ABS(ZI).LE.TLRNC) ZI=0.0		DM28	420
Y=YT		DM28	421
Z=ZI		DM28	422
IF (.NOT.IGTNP) CALL ROTWF(YT,ZT,Y,Z,PHIF)		DM28	423
IF (IGTNP) CALL ROTWR(YW,ZW,Y,Z,K)		DM28	424
Y=YT		DM28	425
CALL VELO		DM28	426
VT=V		DM28	427
*TW		DM28	428
VH=V		DM28	429
WB=W		DM28	430
IF (.NOT.IGTNP) CALL ROTFW(VT,WT,V,W,PHIF)		DM28	431
IF (IGTNP) CALL ROTHW(VB,WB,V,W,K)		DM28	432
TU=U+U		DM28	433
TV=TV+V		DM28	434
T=TW+W		DM28	435
ICNR=4		DM28	436
MNJ=MJ		DM28	437
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW		DM28	438
IF(ASYM) GO TO 40		DM28	439
YI=(YI+YRC(I))		DM28	440
Y=YT		DM28	441
IF (.NOT.IGTNP) CALL ROTWF(YT,ZT,Y,Z,PHIF)		DM28	442
IF (IGTNP) CALL ROTWR(YW,ZW,Y,Z,K)		DM28	443
Y=YT		DM28	444
CALL VELO		DM28	445
VH=V		DM28	446
WB=W		DM28	447
VT=V		DM28	448
*TW		DM28	449
IF (.NOT.IGTNP) CALL ROTFW(VT,WT,V,W,PHIF)		DM28	450
IF (IGTNP) CALL ROTHW(VB,WB,V,W,K)		DM28	451
TU=U+U		DM28	452
TV=TV+V		DM28	453
T=TW+W		DM28	454
MNJ=MJ		DM28	455
IF(NOPR) WRITE(6,1) MI,ICNR,MNJ,X,Y,Z,U,V,W,TU,TV,TW		DM28	456
40 CONTINUE		DM28	457
C		DM28	458
IF(II.EQ.IF.AND.NOCPT.EQ.0) GO TO 101		DM28	459
UP=UP+TU*DELTP(I)		DM28	460
VP=VP+TV*DELTP(I)		DM28	461
WP=WP+TW*DELTP(I)		DM28	462
100 CONTINUE		DM28	463

```

UP=UP/CONST                                0M28 464
VP=VP/CONST                                0M28 465
WP=WP/CONST                                0M28 466
RETURN                                      0M28 467
C                                            0M28 46A
C      UP,VP,WP BELOW ARE FOR SETTING UP INFLUENCE FUNCTIONS FOR USE IN
C      THE INFLUENCE MATRIX                 0M28 469
C                                            0M28 470
C                                            0M28 471
101 UP=U                                     0M28 472
    VP=V                                     0M28 473
    WP=W                                     0M28 474
    RETURN                                    0M28 475
    END                                       0M28 476

SUBROUTINE VELO                             0M29 1
C                                            0M29 2
C      VERSION:DEMON2.                      0M29 3
C                                            0M29 4
C      THIS SUBROUTINE CALCULATES THE INFLUENCE OF THE BASIC
C      SEMI-INFINITE TRIANGLES WHICH ARE UNDER CONSTANT LOADING.
C      MORE CORRECTLY, THEY ARE UNDER CONSTANT U DIFFERENCE
C      THE COORDINATE SYSTEM USED HERE IS THE COORDINATE SYSTEM ASSUMED
C      WITH THE TRIANGLE UNDER CONSIDERATION.
C                                            0M29 9
C      LOGICAL ASYM,BODY,DELTA,NOSYM        0M29 10
C                                            0M29 11
C      COMMON/ONE/DUM1(6400),A,DUM2(5),BETA,DUM3(6),EM,DUM4(4),SLOPE,
C      TLRNC,TIPY,TOTLW,U,V,W,DUM5(4),X,YS,ZS,M1,DUM6(2),MJ,DUM7(8),NHP,
C      ZNPR,DUM8(2),NOOPT,NOLINP,NOOUT,NPANLS,DUM9(2),ASYM,BODY,DELTA,NOSYM
C                                            0M29 15
C      NAMELIST /DEBUG/X,Y,Z,F1,F2, F4,F5, F7,ARG, EML,BETA,U,V,W
C      I,TOP,BOT,ARGY, TLRNC,YEDGE
C                                            0M29 17
C      DATA PI/3,141592653590/
C                                            0M29 20
C                                            0M29 21
C      STATEMENT FUNCTIONS.
C      PLANAR FORMULATION
C                                            0M29 25
FF1(X,Y,Z) = Z*SQRT(XSQ-BTSQ*(YSQ+ZSQ))
FF2(X,Y,Z) = Y*(EML*Y-X)+EML*ZSQ
FF3(X,Y,Z) = EML*ALOG((X+EML-BTSQ*Y
1 + SQRT((X+EML-BTSQ*Y)*(X+EML-BTSQ*Y)
2 + BTSQ*((Y+EML-X)*(Y+EML-X)+ EMLSQ*ZSQ-BTSQ*ZSQ)))
4 / (BETA*SQRT((Y+EML-X)*(Y+EML-X) + EMLSQ*ZSQ-BTSQ*ZSQ)))
6 / SQRT(ABS(EMLSQ-BTSQ))
FF4(X,Y,Z) = (Y/(YSQ+ZSQ))*SQRT(XSQ-BTSQ*(YSQ+ZSQ))
FF5(X,Y,Z) = ALOG((X+SQRT(XSQ-BTSQ*(YSQ+ZSQ)))
1 / (BETA*SQRT(YSQ+ZSQ)))
FF7(X,Y,Z) = (Z/(YSQ+ZSQ))*SQRT(XSQ-BTSQ*(YSQ+ZSQ))
FFSQN(X,Y,Z) = (SQRT(XSQ-BTSQ*(YSQ+ZSQ)))/(X-BETA*Y)
FFSS(X,Y,Z) = EML*ATAN2(SQRT((BTSQ-EMLSQ)*(XSQ-BTSQ*(YSQ+ZSQ))),
1 X+EML-BTSQ*Y) / SQRT(ABS(EMLSQ-BTSQ))
C                                            0M29 39
C                                            0M29 40
C                                            0M29 41
C      Y=YS
C                                            0M29 42
C      Z=ZS
C                                            0M29 43
C      TOP=0.0
C                                            0M29 44
C      BOT=0.0
C                                            0M29 45
C                                            0M29 46

```

	EML=EM	DM29 47
	XSQ=X*Y	DM29 48
	YSQ=Y*Y	DM29 49
	ZSQ=Z*Z	DM29 50
	HTSQ=BETA*BETA	DM29 51
	EMLSQ=EML*EML	DM29 52
C		DM29 53
C	CHECK FOR SUBSONIC, SONIC OR SUPERSONIC LEADING EDGE	DM29 54
C		DM29 55
	IF (X.LT.0.0) GO TO 50	DM29 56
	IF (X.EQ.0.0.AND.Y.EQ.0.0.AND.Z.EQ.0.0) GO TO 50	DM29 57
	IF (ABS(FML).LT.(100.0+TLRNC)) GO TO 120	DM29 58
	YEDGE=X/EML	DM29 59
	GO TO 121	DM29 60
120	YEDGE=10.0E+07	DM29 61
	GO TO 20	DM29 62
C		DM29 63
C	CHECK FOR SUBSONIC, SONIC, OR SUPERSONIC LEADING EDGE	DM29 64
C		DM29 65
121	ARG=HTSQ*(1./EMLSQ)	DM29 66
	IF (ABS(ARG)-1.0).LT.TLRNC GO TO 25	DM29 67
	IF (ARG.LT.1.0) GO TO 10	DM29 68
	RBT=SQRT(YSQ+ZSQ)*BETA	DM29 69
	IF (X.GT.RBT) GO TO 63	DM29 70
	GO TO 21	DM29 71
50	U=0.	DM29 72
	V=0.	DM29 73
	W=0.	DM29 74
	RETURN	DM29 75
C		DM29 76
C	SUPERSONIC LEADING EDGE CASE --	DM29 77
C		DM29 78
20	CONTINUE	DM29 79
C		DM29 80
C	CHECK IF POINT (X,Y,Z) LIES INSIDE, ON, OR OUTSIDE MACH CONE	DM29 81
C	FROM ORIGIN	DM29 82
C		DM29 83
	RRT=SQRT(YSQ+ZSQ)*BETA	DM29 84
	IF (X.GT.RRT) GO TO 24	DM29 85
21	IF (Y.LT.0.0.OR.Y.GE.YEDGE) GO TO 50	DM29 86
C		DM29 87
C	POINT LIES OUTSIDE MACH CONE FROM ORIGIN BUT THE POINT LIES	DM29 88
C	INSIDE MACH CONE FROM LEADING EDGE AT SAME Y AS P(X,Y,Z)	DM29 89
C		DM29 90
	YC=X*EML/RTSQ	DM29 91
	IF (Y.LT.YC) GO TO 50	DM29 92
	XLE=Y+RLOPE	DM29 93
	XTRNSF=X-XLE	DM29 94
	IF (ABS(XTRNSF).LE.(100.0+TLRNC)) XTRNSF=0.0	DM29 95
	ZCONE=XTRNSF/(SQRT(HTSQ-EMLSQ))	DM29 96
	IF (ABS(Z).GT.ZCONE) GO TO 50	DM29 97
	IF (ABS(Z) .LT.TLRNC.OR.(Z) .GT.0.) GO TO 70	DM29 98
	GO TO 71	DM29 99
70	F1=PI	DM29 100
	GO TO 74	DM29 101
71	F1=PI	DM29 102
74	F2=(EML*PI)/SQRT(ABS(HTSQ-EMLSQ))	DM29 103
	IF (ABS(FML).LT.(100.0+TLRNC)) F2=BETA*PI	DM29 104
	IF (XTRNSF.EQ.0.0.AND.Z.EQ.0.0) F2=F2/2.0	DM29 105
	F4=0.0	DM29 106
	F5=0.	DM29 107
	F7=0.0	DM29 108
	GO TO 47	DM29 109
C		DM29 109

```

C      POINT LIES INSIDE MACH CONE FROM ORIGIN                                0429 110
C                                                                                   0429 111
24 CONTINUE                                                                    0429 112
   F2=BETA*ATAN2(SQRT(X*X-BTSQ*(YSQ+ZSQ)),-BETA*Y)                             0429 113
   GO TO 22                                                                      0429 114
63 F2=FFS(X,Y,Z)                                                                0429 115
   GO TO 22                                                                      0429 116
C                                                                                   0429 117
C      SONIC LEADING EDGE CASE==                                             0429 118
C                                                                                   0429 119
25 CONTINUE                                                                    0429 120
C                                                                                   0429 121
C      CHECK IF POINT(X,Y,Z) LIES ON OR OUTSIDE MACH CONE FROM ORIGIN       0429 122
C      IF TRUE SET PERTURBATION VELOCITIES EQUAL TO ZERO                    0429 123
C                                                                                   0429 124
      RBT=SQRT(YSQ+ZSQ)*BETA                                                    0429 125
      IF (X,LE,RBT) GO TO 50                                                    0429 126
      F2=FFS(X,Y,Z)                                                            0429 127
      XTRNSF=X-XLE                                                             0429 128
      IF (XTRNSF,EQ,0.0,AND,Z,EQ,0.0) F2=F2/2.0                             0429 129
      GO TO 22                                                                  0429 130
C                                                                                   0429 131
C      SUBSONIC LEADING EDGE CASE==                                         0429 132
C                                                                                   0429 133
10 CONTINUE                                                                    0429 134
C                                                                                   0429 135
C      CHECK IF POINT (X,Y,Z) LIES ON OR OUTSIDE MACH CONE                 0429 136
C      IF TRUE SET PERTURBATION VELOCITIES TO ZERO                          0429 137
C                                                                                   0429 138
      RBT=SQRT(YSQ+ZSQ)*BETA                                                    0429 139
      IF (X,LE,RBT) GO TO 50 -                                                 0429 140
      ARG2=BETA*SQRT((Y+EML-X)*(Y+EML-X)+EMLSQ+ZSQ-BTSQ+ZSQ)                 0429 141
      IF (ABS(ARG2),LT,TLRNC) GO TO 26                                         0429 142
      F2=FF2(X,Y,Z)                                                            0429 143
      GO TO 22                                                                  0429 144
26 F2=0.0                                                                        0429 145
22 CONTINUE                                                                    0429 146
   IF (Y,EQ,0.0,AND,Z,EQ,0.0) GO TO 50                                        0429 147
   ARGY=Y-YEDGE                                                                0429 148
   IF (ABS(ARGY),LT,(100.0*TLRNC),AND,ABS(Z),LT,TLRNC) GO TO 50             0429 149
   TOP=FIT(X,Y,Z)                                                             0429 150
   ROT=FIT(X,Y,Z)                                                             0429 151
   IF (ABS(TOP),GE,TLRNC) GO TO 43                                             0429 152
   IF (Y,GT,0.0,AND,Y,LT,YEDGE,AND,ABS(Z) .LT,TLRNC) GO TO 48             0429 153
   GO TO 44                                                                    0429 154
48 F1=PI                                                                        0429 155
   GO TO 46                                                                    0429 156
43 F1=ATAN2(TOP,ROT)                                                           0429 157
   IF (ABS(F1),LT,TLRNC) F1=0.                                                0429 158
   GO TO 46                                                                    0429 159
44 F1=0.0                                                                        0429 160
46 CONTINUE                                                                    0429 161
   F4=FF4(X,Y,Z)                                                              0429 162
   F5=FF5(X,Y,Z)                                                              0429 163
   F7=FF7(X,Y,Z)                                                              0429 164
C                                                                                   0429 165
C      CALCULATE PERTURBATION VELOCITIES U/V,V/V,W/V                       0429 165
C                                                                                   0429 167
47 U=F1                                                                        0429 168
   IF (ABS(EML),LT,(100.0*TLRNC)) GO TO 101                                   0429 169
   V=EML*F1+F7                                                                0429 170
   W= (EML*(ABS(1.0-BTSQ/EMLSQ)*F2-F5)-F4)                                    0429 171
   GO TO 102                                                                    0429 172

```

101	CONTINUE	DM29	173
	V=F7	DM29	174
	W=F4+F2	DM29	175
102	CONTINUE	DM29	176
C		DM29	177
	IF (NPR,ME,0) WRITE (6,DEBUG)	DM29	178
C		DM29	179
	RETURN	DM29	180
	END	DM29	181
	SUBROUTINE VELOTH	DM30	1
C		DM30	2
C	VERSION: DEMON1	DM30	3
C		DM30	4
C	THIS SUBROUTINE CALCULATES THE INFLUENCE OF A SEMI-INFINITE	DM30	5
C	TRIANGLE WITH CONSTANT SOURCE STRENGTH.	DM30	6
C		DM30	7
	LOGICAL VERPNL,INSIDE,NOPR	DM30	8
C		DM30	9
	COMMON/THVARG/XTH,YTH,ZTH,UTH,VTH,WTH,EML,VERPNL,NOPR	DM30	10
C	COMMON/THVFLO/BETA,TLRNC,BTSQ	DM30	11
C		DM30	12
	NAMELIST/DEBUG/X,Y,Z,EML,INSIDE,ARG1,BETA,F1,F2,F5,	DM30	13
C	UTH,VTH,WTH,YEDGE,ARGY	DM30	14
C	DATA PI/3,14159265/	DM30	15
C		DM30	16
C	SET VELOCITIES TO ZERO FOR WHATEVER REASON	DM30	17
C		DM30	18
	IF(XTH.GE.TLRNC) GO TO 3	DM30	19
C	1 UTH=0.0	DM30	20
	VTH=0.0	DM30	21
	WTH=0.0	DM30	22
	RETURN	DM30	23
C		DM30	24
C	CHECK IF THE INFLUENCING PANEL IS A VERTICAL PANEL.	DM30	25
C	IF SQ, Y=ZTH AND Z=YTH	DM30	26
C	THI TRANSFORMATION ROTATES SEMI INFINITE TRIANGLE 90 DEG. IN	DM30	27
C	COUNTERCLOCKWISE DIRECTION.	DM30	28
C		DM30	29
	3 CONTINUE	DM30	30
	X=XTH	DM30	31
	IF(VERPNL) GO TO 4	DM30	32
	Y=YTH	DM30	33
	Z=ZTH	DM30	34
	GO TO 5	DM30	35
	4 Y=ZTH	DM30	36
	Z=YTH	DM30	37
	5 YSQ=Y*Y	DM30	38
	ZSQ=Z*Z	DM30	39
	EMLSQ=EML*EML	DM30	40
	ARG1=X*X-BTSQ*(YSQ+ZSQ)	DM30	41
	INSIDE=ARG1.GT.TLRNC	DM30	42
C		DM30	43
C	CHECK FOR SPECIAL CASE OF UNSWEPT LEADING EDGE	DM30	44
C		DM30	45
	IF(ABS(EML).LT.(100.0+TLRNC)) GO TO 70	DM30	46
	YEDGE=X/EML	DM30	47
	ARGY=Y-YEDGE	DM30	48
C		DM30	49
C	CHECK WHETHER LEADING EDGE IS SUBSONIC, SONIC, OR SUPERSONIC	DM30	50

C		0M30	51
	STEST=BTSQ=EMLSQ	0M30	52
	IF(ABS(STEST),LT,TLRNC) GO TO 20	0M30	53
	IF(STEST,GT,0.0) GO TO 30	0M30	54
C	***** SUBSONIC LEADING EDGE *****	0M30	55
C		0M30	56
C	DETERMINE IF POINT LIES INSIDE OR OUTSIDE MACH CONE FROM ORIGIN	0M30	57
C	IF IT LIES OUTSIDE, SET PERTURBATION VELOCITIES TO ZERO	0M30	58
C		0M30	59
C	IF(,NOT,INSIDE) GO TO 1	0M30	60
C		0M30	61
C	POINT LIES INSIDE MACH CONE FROM ORIGIN	0M30	62
C		0M30	63
C	RAD=SQRT(ARG1)	0M30	64
	T1=X*EML-RTSQ*Y	0M30	65
	T2=BETA*SQRT((Y+EML-X)*(Y+EML-X)+ZSQ*(EMLSQ-BTSQ))	0M30	66
C		0M30	67
C	TEST FOR POSSIBLE SINGULARITY IN F1 OR F2	0M30	68
C		0M30	69
C	IF(ABS(ARGY),LT,(100.0*TLRNC),AND,ABS(Z),LT,TLRNC) GO TO 1	0M30	70
	F2=(EML/SQRT(EMLSQ-BTSQ))*ALOG((T1+SQRT(T1+T1-T2*T2))/T2)	0M30	71
	IF(ABS(Y),LT,TLRNC,AND,ABS(Z),LT,TLRNC) GO TO 13	0M30	72
	F1=ATAN2(Z*RAD,EML*(YSQ+ZSQ)-Y*X)	0M30	73
	F5=ALOG((X+RAD)/(BETA*SQRT(YSQ+ZSQ)))	0M30	74
	GO TO 100	0M30	75
C		0M30	76
C	CASE FOR Y AND Z BOTH SMALL	0M30	77
C		0M30	78
C		0M30	79
	13 F1=0.0	0M30	80
	VTH=0.0	0M30	81
	GO TO 101	0M30	82
C		0M30	83
C	***** SONIC LEADING EDGE *****	0M30	84
C		0M30	85
	20 IF(,NOT,INSIDE) GO TO 1	0M30	86
	RAD=SQRT(ARG1)	0M30	87
	F2=RAD/(X-BETA*Y)	0M30	88
C		0M30	89
C	F1 AND F5 SAME AS IN SUBSONIC LEADING EDGE	0M30	90
C		0M30	91
C	IF(ABS(Y),LT,TLRNC,AND,ABS(Z),LT,TLRNC) GO TO 21	0M30	92
	F5=ALOG((X+RAD)/(BETA*SQRT(YSQ+ZSQ)))	0M30	93
	IF(ABS(ARGY),LT,TLRNC,AND,ABS(Z),LT,TLRNC) GO TO 22	0M30	94
	F1=ATAN2(Z*RAD,EML*(YSQ+ZSQ)-Y*X)	0M30	95
	GO TO 100	0M30	96
C		0M30	97
C	Y AND Z BOTH SMALL	0M30	98
C		0M30	99
	21 F1=0.	0M30	100
	VTH = 0.	0M30	101
	GO TO 101	0M30	102
C		0M30	103
C	Z SMALL AND Y CLOSE TO LEADING EDGE	0M30	104
C		0M30	105
	22 F1=0.	0M30	106
	GO TO 100	0M30	107
C		0M30	108
C	***** SUPERSONIC LEADING EDGE *****	0M30	109
C		0M30	110
C	DETERMINE WHETHER POINT LIES INSIDE MACH CONE FROM ORIGIN	0M30	111
C	IF OUTSIDE, THERE IS ONE MORE CHECK TO BE MADE	0M30	112
C		0M30	113

C	30 IF(INSIDE) GO TO 31	0430 114
C	POINT IS OUTSIDE MACH CONE FROM ORIGIN	0430 115
C	DETERMINE IF IT IS INSIDE MACH CONE FROM LEADING EDGE	0430 116
C	IF OUTSIDE, SET PERTURBATION VELOCITIES TO ZERO	0430 117
C		0430 118
C	IF(Y .LT. 0.0 .OR. Y .GE. YEDGE) GO TO 1	0430 120
C	YC=X*EML/RTSQ	0430 121
C	IF (Y.LT.YC) GO TO 1	0430 122
C	XLE=Y*FML	0430 123
C	XTRNSP=X-XLE	0430 124
C	ZCONE=XTRNSP/SQRT(STEST)	0430 125
C	IF (ABS(Z).GT.ABS(ZCONE)) GO TO 1	0430 126
C		0430 127
C	POINT IS INSIDE MACH CONE FROM LEADING EDGE	0430 128
C		0430 129
C	F2= PI*EML/SQRT(RTSQ=EMLSQ)	0430 130
C	F1=PI	0430 131
C	IF(Z.LT.0.0) F1=-PI	0430 132
C	F5=0.0	0430 133
C	GO TO 100	0430 134
C		0430 135
C	POINT IS INSIDE MACH CONE FROM ORIGIN	0430 136
C		0430 137
C	31 T3=SQRT(RTSQ=EMLSQ)	0430 138
C	PAD=SQRT(ARG1)	0430 139
C	F2=(EML/T3)*ATAN2(RAD*T3,X*EML-RTSQ*Y)	0430 140
C		0430 141
C	USE F1 AND F5 AS IN SUBSONIC LEADING EDGE CASE	0430 142
C		0430 143
C	IF (ABS(Y) .LT. TLRNC .AND. ABS(Z) .LT. TLRNC) GO TO 32	0430 144
C	F5=ALOG((X+RAD)/(BETA*SQRT(YSQ+ZSQ)))	0430 145
C	F1=ATAN2(Z*RAD,EML*(YSQ+ZSQ)-Y*X)	0430 146
C	GO TO 100	0430 147
C		0430 148
C	Y AND Z BOTH SMALL	0430 149
C		0430 150
C	32 F1=0.	0430 151
C	VTH=0.	0430 152
C	GO TO 101	0430 153
C		0430 154
C		0430 155
C	***** SPECIAL CASE FOR UNSWEPT LEADING EDGE *****	0430 156
C		0430 157
C	DETERMINE WHETHER POINT LIES INSIDE MACH CONE FROM ORIGIN	0430 158
C	IF OUTSIDE, THERE IS ONE MORE CHECK TO BE MADE	0430 159
C		0430 160
C	70 IF(INSIDE) GO TO 72	0430 161
C		0430 162
C	POINT IS OUTSIDE MACH CONE FROM ORIGIN	0430 163
C	DETERMINE IF IT IS INSIDE MACH CONE FROM LEADING EDGE	0430 164
C	IF OUTSIDE, SET PERTURBATION VELOCITIES TO ZERO	0430 165
C		0430 166
C	IF(Y .LT. 0.) GO TO 1	0430 167
C	RSTB=ABS(Z)*BETA	0430 168
C	XTEST=X-RSTB	0430 169
C	IF((RSTB .LT. TLRNC .AND. X.LE.0.) .OR. XTEST.LE.TLRNC)GO TO 1	0430 170
C		0430 171
C	POINT BETWEEN MACH CONE FROM ORIGIN AND LEADING EDGE	0430 172
C		0430 173
C	UTH=-PI/BETA	0430 174
C	F1=PI	0430 175
C	IF(Z.LT.0.0) F1=-PI	0430 176

	VTH=0.0	DM30 177
	WTH=F1	DM30 178
	GO TO 102	DM30 179
C		DM30 180
C	POINT IS INSIDE MACH CONE FROM ORIGIN	DM30 181
C		DM30 182
	72 RAD=SQRT(ARG1)	DM30 183
	UTH=-ATAN2(RAD,-BETA*Y)/BETA	DM30 184
	F2=0.0	DM30 185
	IF(ABS(Z) .LT. TLRNC .AND. ABS(Y) .LT. TLRNC)GO TO 73	DM30 186
	F1=ATAN2(Z*RAD,-Y*X)	DM30 187
	F5=ALOG((X+RAD)/(BETA*SQRT(Y ² +Z ²)))	DM30 188
	VTH=F5	DM30 189
	WTH=F1	DM30 190
	GO TO 102	DM30 191
	73 VTH=0	DM30 192
	WTH=0	DM30 193
	GO TO 102	DM30 194
C		DM30 195
C	COMPUTE PERTURBATION VELOCITIES	DM30 196
C		DM30 197
	100 VTH=F2-F5	DM30 198
	101 UTH=F2/EML	DM30 199
	WTH=F1	DM30 200
	102 IF(.NOT. VERPNL) GO TO 103	DM30 201
	TEMP=VTH	DM30 202
	VTH=-WTH	DM30 203
	WTH=TEMP	DM30 204
	103 CONTINUE	DM30 205
	IF(NOPR) WRITE(6,DEBUG)	DM30 206
	RETURN	DM30 207
	END	DM30 208
	SUBROUTINE VRTVEL(NSTART,N)	DM31 1
C		DM31 2
C	VERSION: DEMON1	DM31 3
C		DM31 4
C		DM31 5
C	SUBROUTINE FOR CALCULATION OF VELOCITIES INDUCED BY FIXED EXTERNAL	DM31 6
C	VORTICES IN THE PRESENCE OF A CIRCULAR BODY AT FIELDPOINTS	DM31 7
C	WITH COORDINATES XFLOP,YFLOP,ZFLOP.	DM31 8
C		DM31 9
C	THIS SUBROUTINE READS IN UP TO 10 VORTEX STRENGTHS AND THEIR	DM31 10
C	LOCATIONS IN THE CROSSFLOW PLANE	DM31 11
C	Y IS TO THE RIGHT WHEN VIEWING FORWARDS, Z IS UP	DM31 12
C	VORTEX INDUCED VELOCITIES ARE NAMED VVRTX,WVRTX.	DM31 13
C		DM31 14
C		DM31 15
C	LOGICAL ASYM,BODY,DELTA,NOSYM	DM31 16
C		DM31 17
C		DM31 18
	COMMON/DNE/CIRC(250),DELTP(250),FN(250),PNLC(250),SWPPLF(250),	DM31 19
	1SWPPE(250),VNOR(250),XBAR(250),ZBAR(250),XCPT(250),YCPT(250),ZCPT(250)	DM31 20
	2(250),XLF(250),XLR(250),XRF(250),XRR(250),YLC(250),YRC(250),ZLF(250)	DM31 21
	30),ZRF(250),ZLR(250),ZRR(250),SNT(125),CST(125),SNT2(125),CST2(125)	DM31 22
	4),IP(300),XFHIP(100),A,ALFA,ALFR,ARWING,B2,R2V,BETA,BETAR,COMST,	DM31 23
	5COSALF,COSBET,CN,DX,PM,FMACH,RB,SINALF,SINRFT,SLOPE,TLRNC,TIPY,	DM31 24
	6TOTLR,U,V,W,UCHK,VCHK,WCHK,WHIP,X,DUMY,Z,I,IF,II,J,MSWR,MSWL,MSWU,	DM31 25
	7MSWD,MRIP,NCRX,NCN,NDRAG,NHP,NPW,NRP,NJP,NOCPT,NOLINP,NOUT,NPANLS,	DM31 26
	8NPRESS,NWBP,ASYM,BODY,DELTA,NOSYM	DM31 27

COMMON/VVRTX/VVRTX(150),WVRTX(150),NVRTPL,NVRTX,VRTMAX	DM31	28
COMMON/VORSPC/GAMMA(10),YVRTX(10),ZVRTX(10),RLOC	DM31	29
COMMON/BVEL/DUMB(450),XFLDP(150),YFLDP(150),ZFLDP(150)	DM31	30
1 FORMAT (8F10,5)	DM31	31
2 FORMAT (1H1,10X,79H2DIM,VORTEX NON-DIMENSIONAL STRENGTHS AND FIXED	DM31	32
1 COORDINATES IN CROSS LOW PLANE	DM31	33
1 //15X,1H1,10X,6HGAMMA/,23X,2HY/,17X,	DM31	34
2PHZ/,/24X,23H(2.0*PI*BODY RAD,*VINFL),5X,11H(BODY RAD.),8X,	DM31	35
311H(BODY RAD.,)///)	DM31	36
3 FORMAT (15X,12,8X,F10,5,17X,F10,5,9X,F10,5)	DM31	37
READ IN NON-DIMENSIONALIZED VORTEX STRENGTHS,GAMMA=GAMMA/	DM31	38
(2*PI*BODY RADIUS*VINFL)	DM31	39
AND NON-DIMENSIONALIZED LOCATIONS,YVRTX/BODY RADIUS,	DM31	40
ZVRTX/BODY RADIUS	DM31	41
WRITE (6,2)	DM31	42
DO 100 I=1,NVRTX	DM31	43
READ (5,1) GAMMA(I),YVRTX(I),ZVRTX(I)	DM31	44
WRITE (6,3) I,GAMMA(I),YVRTX(I),ZVRTX(I)	DM31	45
100 CONTINUE	DM31	46
COMPUTE VORTEX INDUCED PERTURBATION VELOCITIES AT CONTROL POINTS	DM31	47
OF ALL WING SURFACES AND BODY INTERFERENCE SWELL.	DM31	48
CONTRIBUTION DUE TO EXTERNAL VORTEX....VVRTXE,WVRTXE	DM31	49
CONTRIBUTION DUE TO IMAGE VORTEX....VVRTXI,WVRTXI	DM31	50
CONTRIBUTION DUE TO CENTER VORTEX....VVRTXC,WVRTXC	DM31	51
NOTE:***CENTER VORTEX EFFECTS ARE SET ZERO	DM31	52
ENTER HERE IF VORTICES HAVE BEEN READ IN ALREADY OR CALCULATED IN	DM31	53
SUBROUTINE HDVPR.	DM31	54
ENTRY VORTEX	DM31	55
DO 101 IC=NSTART,N	DM31	56
Y=YFLDP(IC)/RLOC	DM31	57
YS=Y*Y	DM31	58
Z=ZFLDP(IC)/RLOC	DM31	59
ZS=Z*Z	DM31	60
DENOM=Y*YS+ZS	DM31	61
DO 102 JV=1,NVRTX	DM31	62
ZVSYVS=ZVRTX(JV)+ZVRTX(JV)+YVRTX(JV)+YVRTX(JV)	DM31	63
DELTYS=Y*YVRTX(JV)	DM31	64
DELTYS=DELTYS*DELTYS	DM31	65
DELTZ=Z-ZVRTX(JV)	DM31	66
DELTZS=DELTZ*DELTZ	DM31	67
DENOM1=DELTYS+DELTZS	DM31	68
IF ((DENOM1).LE.TLRNC) GO TO 105	DM31	69
VVRTXE=GAMMA(JV)*(DELTZ/DENOM1)	DM31	70
WVRTXE=GAMMA(JV)*(DELTYS/DENOM1)	DM31	71
GO TO 106	DM31	72
105 VVRTXE=0.	DM31	73
WVRTXE=0.	DM31	74
106 CONTINUE	DM31	75
DENOM2=(Y-YVRTX(JV)/ZVSYVS)**2+(Z-ZVRTX(JV)/ZVSYVS)**2	DM31	76
IF (ABS(DENOM2).LE.TLRNC) GO TO 107	DM31	77
VVRTXI=GAMMA(JV)*(Z-ZVRTX(JV)/ZVSYVS)/DENOM2	DM31	78
WVRTXI=GAMMA(JV)*(Y-YVRTX(JV)/ZVSYVS)/DENOM2	DM31	79
GO TO 108	DM31	80
107 VVRTXI=0.0	DM31	81
WVRTXI=0.0	DM31	82
108 CONTINUE	DM31	83
	DM31	84
	DM31	85
	DM31	86
	DM31	87
	DM31	88
	DM31	89
	DM31	90

	VVRTXC=0.0	DM31	91
	WVRTXC=0.0	DM31	92
	VVRTX(IC)=VVRTX(IC)+VVRTXE+VVRTXI+VVRTXC	DM31	93
	WVRTX(IC)=WVRTX(IC)+WVRTXE+WVRTXI+WVRTXC	DM31	94
C		DM31	95
C	LIMIT MAGNITUDE OF PERTURBATION VELOCITIES TO VRTMAX.	DM31	96
C		DM31	97
	IF (VVRTX(IC).GT.0.0.AND. ABS(VVRTX(IC)).GE.VRTMAX) VVRTX(IC)=	DM31	98
	1 VRTMAX	DM31	99
	IF (VVRTX(IC).LT.0.0.AND. ABS(VVRTX(IC)).GE.VRTMAX) VVRTX(IC)=	DM31	100
	1 -VRTMAX	DM31	101
	IF (WVRTX(IC).GT.0.0.AND. ABS(WVRTX(IC)).GE.VRTMAX) WVRTX(IC)=	DM31	102
	1 VRTMAX	DM31	103
	IF (-WVRTX(IC).LT.0.0.AND. ABS(WVRTX(IC)).GE.VRTMAX) WVRTX(IC)=	DM31	104
	1 -VRTMAX	DM31	105
102	CONTINUE	DM31	106
101	CONTINUE	DM31	107
C		DM31	108
	RETURN	DM31	109
	END	DM31	110

	SUBROUTINE VVELS(NV,YY,ZZ,VX,VY,G,AR,RR,V,W,VRTMAX)	DM32	1
C		DM32	2
C	VERSION: DEMON1	DM32	3
C		DM32	4
C	THIS SUBROUTINE COMPUTES PERTURBATION VELOCITY COMPONENTS DUE TO	DM32	5
C	NV EXTERNAL VORTICES AND THEIR IMAGES INSIDE A BODY WITH	DM32	6
C	ELLIPTICAL CROSS SECTION. THEY ARE ADDED TO V AND W IN THE	DM32	7
C	ARGUMENT LIST.	DM32	8
C		DM32	9
C		DM32	10
C	DIMENSION VX(1),VY(1),G(1)	DM32	11
C		DM32	12
	COMMON/COM1/A2,B2,R2	DM32	13
	COMMON/COM2/SIG2,H2	DM32	14
C		DM32	15
C	COMPLEX T0,V1,DSDT,Z,DSOZ,S1,S1B,SU,TAU,C1,VEL	DM32	16
C		DM32	17
	EXTERNAL Z,DSOZ	DM32	18
	PI=3.14159265	DM32	19
	TLC=0.001	DM32	20
	C1=CMPLX(0.0,1.0)	DM32	21
	A2=AR*AR	DM32	22
	B2=BR*BR	DM32	23
	APB=AB*RB	DM32	24
	APH2=APB*APB	DM32	25
	R=0.5*APB	DM32	26
	H2=APB2	DM32	27
	R2=R*R	DM32	28
	SIG2=R2	DM32	29
	T0=CMPLX(YY,ZZ)	DM32	30
	S0=Z(T0)	DM32	31
	V1=CMPLX(0.0,0.0)	DM32	32
	DSDT=DSOZ(S0)	DM32	33
C		DM32	34
C	LOOP OVER THE NUMBER OF VORTICES,NV	DM32	35
C		DM32	36
	DO 1 I=1,NV	DM32	37
	TAU=CMPLX(VX(I),VY(I))	DM32	38

	SI=Z(TAU)	DM32	39
	SIB=CONJG(SI)	DM32	40
	D=CABS(SI-S0)	DM32	41
	IF(D,LE,TLC) GO TO 2	DM32	42
	V1=V1-G(I)/(S0-SI)	DM32	43
2	CONTINUE	DM32	44
	D=CABS(S0-R2/SIB)	DM32	45
	IF(D,LE,TLC) GO TO 1	DM32	46
	V1=V1+G(I)/(S0-R2/SIB)	DM32	47
1	CONTINUE	DM32	48
C		DM32	49
	VEL=0.5*CI*V1*DSDT/PI	DM32	50
	V=REAL(VEL)+V	DM32	51
	W=AIMAG(VEL)+W	DM32	52
	AV=ABS(V)	DM32	53
	AW=ABS(W)	DM32	54
	IF(V.GT.0.0.AND.AV.GE.VRTMAX) V=VRTMAX	DM32	55
	IF(V.LT.0.0.AND.AV.GE.VRTMAX) V=-VRTMAX	DM32	56
	IF(W.GT.0.0.AND.AW.GE.VRTMAX) W=VRTMAX	DM32	57
	IF(W.LT.0.0.AND.AW.GE.VRTMAX) W=-VRTMAX	DM32	58
	RETURN	DM32	59
	END	DM32	60
	COMPLEX FUNCTION Z(CT)	DM33	1
C	VERSION: DEMON1	DM33	2
C		DM33	3
C	VERSION: DEMON1	DM33	4
C		DM33	5
C	THIS FUNCTION SUBROUTINE CALCULATES THE SIGMA VALUE IN THE	DM33	6
C	TRANSFORMED (CIRCLE) PLANE FOR GIVEN TAU IN THE PHYSICAL PLANE	DM33	7
C	FOR AN ELLIPTICAL BODY WITH WINGS	DM33	8
C		DM33	9
	COMMON/COM2/SIG2,H2	DM33	10
	COMMON/COM3/ZR,ZI	DM33	11
	COMMON/COM4/G2,G1	DM33	12
	COMMON/COM6/W2,*	DM33	13
C		DM33	14
C		DM33	15
C	COMPLEX W,G1,G2,CT,W2,DBLU	DM33	16
C		DM33	17
C	EXTERNAL DBLU	DM33	18
C		DM33	19
	W=DBLU(CT)	DM33	20
	G1=W+SIG2/W	DM33	21
	G2=G1+G1-H2	DM33	22
	Y=AIMAG(G2)	DM33	23
	AY=1.0	DM33	24
	IF(Y.LT.0.0) AY=-1.0	DM33	25
	YZ=AIMAG(G1)	DM33	26
	AYZ=1.0	DM33	27
	IF(YZ.LT.0.0) AYZ=-1.0	DM33	28
	GZ=CSQRT(G2)*AY*AYZ	DM33	29
	IF((ABS(YZ).LE.0.0).AND.(REAL(G1).LT.0.0)) GZ=CMPLX(-REAL(G2),	DM33	30
	AIMAG(G2))	DM33	31
	Z=0.5*(G1+G2)	DM33	32
	IF((ABS(ZI).NE.0.0).AND.(ABS(ZR).NE.0.0)) Z=CMPLX(ZR+ABS(REAL(Z)),	DM33	33
	IZI+ABS(AIMAG(Z)))	DM33	34
	RETURN	DM33	35
	END	DM33	36

APPENDIX K

DESCRIPTION OF PROGRAM WDYBDY

INTRODUCTION

The purpose of this appendix is to describe the body source paneling program. Attention is given to the program's input, its output, the added special features to account for specified body nose shed vortices, and its interplay with program DEMON2 described in Appendix J. In relation to the work described in this report, program WDYBDY is employed to handle bodies in supersonic flow when they are elliptical in cross section.

Basically, the building blocks of this body modeling program have been extracted from Woodward's improved method described in reference 9 and documented in reference 10. Existing subroutines have been modified to account for combined angle of pitch and sideslip. Subroutines have been added to include effects of specified body nose vorticity in the calculation of pressures on the body.

This program performs the following tasks when the body of the configuration of interest is elliptical in cross section. First, the pressures acting on the forebody are calculated by this program including effects of specified body nose vortices if applicable. Second, the program has been arranged to compute velocity components induced by the body source panels at the control points distributed over the forward set of lifting surfaces (monoplane wing) and the associated body interference shell. If the length of body between the forward and tail lifting surfaces is long enough to influence the overall loads, program WDYBDY should be used to compute the pressure distributions over the afterbody. Effects of body nose and monoplane wing vortices must first be determined by program VPATHL which is described in Appendix L. This program computes the vortex paths along the afterbody. By means of an exchange of data sets with program WDYBDY, vortex induced velocity components are transferred to subroutine PRESS for inclusion in the calculation of pressures at points on the afterbody. Finally, this program calculates the velocity components induced by the body source panels at the control points of the tail lifting surfaces/interdigitated tails.

Thus, program WDYBDY, together with programs DEMON2 and VPATHL, is used repeatedly in accordance with the procedure described in Section 5.2.

APPENDIX K

In this way, complete configurations involving bodies with elliptical cross section are handled.

The theoretical basis of program WDYBDY and its usage will be summarized. The calculation procedure, program operation, program limitations and termination conditions are described. Special debugging output options are discussed. Detailed descriptions of the program input and output are then given. Program listings appear at the end of this appendix.

PROGRAM DESCRIPTION

A summary of the theory associated with body source panels is given in Section 4. Body source panels are distributed over the body surface as shown in figures 2 and 24. Panel orientation angles δ and θ are indicated in the sketch of Section 4.1. These panels model the body with elliptical cross section in supersonic flow.

Program WDYBDY is an adaptation of the computer program of reference 10. It has been specialized to flow model bodies with elliptic cross section. Body geometry can be specified in terms of the horizontal and vertical semiaxes FUSBY and FUSAZ as a function of axial distance from the body nose XFUS. The configuration can be pitched and rolled giving rise to angles of pitch and sideslip. The boundary condition and pressure equations have been extended to account for angle of sideslip in addition to angle of pitch, see Section 4. The force and moment calculations have also been modified to include angle of sideslip. Normal force and side force, as well as pitching moment and yawing moment are calculated in the body- and wind-axis coordinate systems. The subroutines affected by the changes involving the inclusion of effects of combined angle of pitch and sideslip are SOLVE, PRESS and FORMOM.

In addition, subroutines READVX, ELBDVT and VVELS have been included to read in body nose separation vortex positions and strengths as a function of axial distance and to compute their contributions to the velocity components used in the Bernoulli pressure expression, equation 10. In the latter process, a slender-body theory solution is used. The solution is concerned with the calculation of velocity components induced by a set of vortices at specified points in the presence of a body with

elliptical cross section. As such, the solution is a simplified version of the general solution described in Appendix I for the case involving a monoplane wing mounted on a body with elliptical cross section. Subroutine VVELS makes use of function subroutines DBLU, DSDZ and Z. The vortex induced velocity components are computed from expressions implemented in these routines using complex quantities.

A certain amount of graphical display can be generated through the use of routines PLOTG, PLOTA2, PLOTA3, PLOTA5, PLOTA6, PLOTA8 and PLOTV2. This capability serves as an aid in checking the input parameters that govern the geometrical layout of the body source panels. It also allows for an initial look at the pressure distributions on the body.

Calculation Procedure

The program calculations are blocked into four parts, each of which depends on the completion of the previous step but which do not interact with each other. The four major partitions of the calculations are: the generation of panel geometric properties, the calculation of the aerodynamic influence coefficients, the solution for the strengths, pressures and loadings and the calculation of velocities induced at specified set of control points. All data interchanged between these blocks is either saved in common or on external files. The basic program description is contained in reference 10. A flow chart of the subroutine flow sequence is shown in figure K-1.

In the geometry block of routine GEOM, the configuration is read by CONFIG. Body paneling may be computed for a subset of the geometry used to define the configuration. NEWRAD is used to redefine the meridional lines describing the panel side edges and BODPAN both redefines the x-spacing of the panels and computes the panel corner points and inclination angles δ and θ . The geometry description is saved on TAPE 7. If vortices are to be accounted for, the x-location at which vorticity characteristics are given are read from READVX before calling NEWRAD. If the control points are to be saved for use by other programs, a table of panel control points is written on TAPE 4 at the completion of the generation of the geometry.

APPENDIX K

The generation of the aerodynamic matrix coefficients is organized in VELCMP. The velocity contributions and influences between panels are computed by BODVEL and SORPAN. The aerodynamic matrix and velocities are saved on files TAPE 8, TAPE 9, and TAPE 10.

The solution of the equations and the calculation of pressures and forces is governed by routine SOLVE. The flow tangency boundary condition is defined and the solution of the equations is computed by a combination of routines DIAGIN, PARTIN, ITRATE and INVERT. The contribution to the velocity components from external vortices is included by either interpolation in a vortex strength table or by directly reading the contributions computed by external programs such as program VPATHL described in Appendix L. The pressure coefficient on each panel and the forces and moments acting on the body are then computed in PRESS and FORMOM, respectively. If the integration of the forces and moments over the length of body between specified x-locations XSTART and XWLE is required, the force and moment calculations are repeated for that length of body.

The last calculation block is performed when the calculation of velocity components at specified control points is requested. The velocity components in the body coordinate directions are computed using the solution strengths obtained in the previous part. No contribution due to vorticity is included in this calculation. The velocities are written after the control points on TAPE 4 for transmittal to program DEMON2 described in Appendix J in accordance with the procedures given in Section 5.2.

Program Operation

The body modeling program using source panels on the surface is written in FORTRAN IV language (029 punch) and has been run on a CDC 6600 machine. The program is an adaptation of the wing-body-tail program in reference 10 simplified to body-only modeling. The program is arranged so that a total of 600 source panels are available to cover the body surface. The current version requires 122000 octal core locations to run on the CDC 6600.

The program requires seven disk files for operation. Because of the input copy feature of the program, the normal program input is read

from TAPE 5 and not the INPUT tape. The normal input file may not be re-wound. TAPE 4 may be used for either of three functions. If NWCPT is greater than one, specified control points are read from TAPE 4, velocities computed and written after the control points on TAPE 4. If NCPOUT is equal to one, the control points associated with the body source panels aft of XSTART and forward of XWLE are written on TAPE 4. If NVLIN is equal to one, the velocity components calculated by program VPATHL for control points aft of XSTART and forward of XWLE are read from TAPE 4. Files TAPE 7, TAPE 8, TAPE 9, and TAPE 10 are used to store intermediate results required for the solution of the aerodynamic matrix.

Programs Limitations

The body modeling program has several limitations due to current code dimensions and due to the limitations inherent to the linear theory. The code will handle up to 600 body source panels during solution. There is a further limitation with regard to the number of panels in a given ring and the total number of rings. The maximum number of panels on the half body for symmetric cases and on the full body for nonsymmetric cases is restricted to 20 panels on a single ring. Similarly, the maximum number of rings of panels in the axial direction is limited to thirty. The flow limitation on the code is that the angle of inclination of all panels be less than the vertex angle of the Mach cone at supersonic speeds. No provisions are incorporated in the program for the presence of detached shocks. A summary of the program termination conditions that are checked for in the code follows. When body nose vortices are present, up to ten vortices may be handled simultaneously. When the calculation of velocities are performed at external field points, a maximum of 600 field point coordinates may be read in at a time.

Program Termination Conditions

A number of labeled STOP conditions exist in the program. These may exist as a result of error conditions or end-of-data checks. They are as follows:

STOP	Routine	Description
STOP 20	GEOM	Normal program termination for end of data on TAPE 5.

APPENDIX K

STOP	Routine	Description
STOP 200	GEOM	Error - body has more than 20 columns panels around circumference.
STOP 120	NEWRAD	Error - body has more than 20 meridians.
STOP 130	NEWRAD	Error - body has more than 60 axial stations.
STOP 20	BODPAN	Error - number of rows of source panels in section exceeds 30.
STOP 30	BODPAN	Error - number of rows of source panels on body exceeds 30.
STOP 500	PRTCPT	Termination for NCPOUT equals 2.
STOP 210	SORPAN	Panel slope exceeds Mach cone angle.

Supplementary Print from CDUMP

The routine CDUMP was written to provide additional print of variables in common for debugging purposes during execution. It is called at several points within the program as specified by the print controls IPRT. The information is printed according to the value of the option as follows:

Value	Supplementary print
0	Prints only name of routine from which called.
1	Prints variables and arrays of less than 11 in length for common blocks: JOPTNS, PARAM, NEWCOM, VELCOM, and SEG.
2	Prints all of above common blocks.
3	Prints variable array BLOCK in unlabelled common.
4	Prints variables array ARRAY in common block POINT.
5	Prints common block COMPS.
6	Prints common block TRAN.
7	Prints common block BTHET
8	Prints common blocks COEF, MATCOM, and ITERAT.

Note for print control IPRINT = 0, no print is output.

Description of Configuration Geometry Input Cards

The configuration geometry input defines the external shape of the body only. The auxiliary geometry input later defines the sequence to be used in paneling the configuration by interpolation in the external geometry. The input description used here was adapted directly from reference 10 where it is used to describe an entire configuration. In all cases the original definitions have been preserved. For certain options additional meanings have been attached.

WDYBDY Program Input Data

This program was adapted from the body analysis portion of the program detailed in reference 10. Herein, the geometric variables and their definitions used to describe the body have been maintained wherever possible. Several additional cards have been added to the program to facilitate the input of new program options and the description of parameters associated with discrete vortex properties. An additional input file used to exchange control points and velocities is also required. The original description of the cards and documentation in reference 10 has been maintained for simplicity. A sample input deck is described in Section 6.2 and shown in figure 25.

The input to the program consists of four parts: the definition of program options associated with printing, plotting and vortex options; the numerical description of the configuration geometry; an auxiliary data set specifying the singularity paneling scheme and program options; and the case cards defining the Mach number, combined angle of attack and roll, and vortex locations and strengths.

The definition of the coordinate axes used in this program is defined in figure 2. The x_B , y_B and z_B axes in figure 2 correspond to the x_B , y_B , and z_B axes used in program DEMON2 and shown in figure 1. The body is considered to be viewed facing forward with the positive x_B -axis aft, the positive y_B -axis out the right and the positive z_B -axis up. In the following, the B-subscript is omitted wherever the body coordinates are mentioned.

APPENDIX K

Descriptions of Input Option Cards

The options defined here control supplementary output and online plotting not defined by IPRINT and the specification of special control point and vortex options. The latter variables control the additional input to be read in later.

Card 1 - Title card - Card 1 contains any desired identifying information in columns 1-80.

Card 2 - Option Integers - Card 2 contains 14 integers, each punched right justified in a 3-columnar field (14I3). Columns 73-80 may be used in any desired manner. It is designated the IPRT card for reference. Subroutine CDUMP referenced to in the following in connection with print control IPRT is discussed above as part of the program description. Card 2 reads the following:

<u>Column</u>	<u>Variable</u>	<u>Value</u>	<u>Description</u>
1-3	IPRT(1)	0	Do not print copy of input
		1	Print formatted copy of input data
4-6	IPRT(2)	0	No supplementary print after GEOM
		>0	Call CDUMP for special print after GEOM
7-9	IPRT(3)	0	No supplementary print of vortices
		1	Print supplementary information after calculation of vortex velocity components
10-12	IPRT(4)	0	No supplementary print after VELCMP
		>0	Call CDUMP for special print after VELCMP
13-15	IPRT(5)	0	No supplementary print after SOLVE
		>0	Call CDUMP for special print after SOLVE
16-18	IXZSYM	0	Panel only symmetric half of configuration
		1	Panel full configuration symmetrically using geometry of positive y side.
		-1	Panel full configuration by reading geometry of both sides
19-21	IPLOT(1)	0	Do not plot geometry
		1	Plot three orthographic projections and perspective of geometry of panel layout on line printer

<u>Column</u>	<u>Variable</u>	<u>Value</u>	<u>Description</u>
22-24	IPLOT(2)	0	Do not plot CP
		1	Plot CP at each control point versus x location and versus meridional angle θ
25-27	IPLOT(3)	0	Not available
28-30	IPLOT(4)	0	Not available
31-33	NWCPT	0	Do not call BDYVEL. TAPE 4 input is not required
		1-600	NWCPT values of I, XPT, YPT, ZPT control points are read from TAPE 4 and velocities induced by body source panels computed at these coordinates
		-1	NBODY values of XPT, YPT, ZPT control points are generated internally and velocities computed to test routine BDYVEL. TAPE 4 is not used. NBODY is the total number of source panels distributed over the body surface
34-36	NVTX	0	No body nose vortex strengths or Y and Z location data is read. All vortex contributions to velocities are set to zero
		1-10	Vortex Y and Z locations, YVRTX and ZVRTX, and strengths, Γ/V are read for each of NXVTX x-stations, XV. Three cards are read for each vortex
37-39	NXVTX	0	No body nose vortex x-station data is read. All vortex contributions to velocities are set to zero
		1-10	Body nose vortex x-body stations are read. These x values define the stations at which vortex Y, Z and Γ/V data will be read. One XV card is to be read. Maximum number of x-stations is 10
40-42	NCPOUT	0	No control points are output on TAPE 4
		1	X,Y,Z body control points aft of XSTART and forward of XWLE are written in (I5, 3E12.5) format on TAPE 4. Conversely, options specified by NWCPT and NVLIN will not work
		2	Same function as NCPOUT = 1 except program execution is terminated at that point
43-45	NVLIN	0	No vortex velocities are read

APPENDIX K

<u>Column</u>	<u>Variable</u>	<u>Value</u>	<u>Description</u>
		1	Body source panel control point and V and W data are read for each of the x-stations aft of XSTART and forward of XWLE from TAPE 4 as defined previously for NCPOUT = 1. XCP, YCP, ZCP, VA and WA are read in (I5, 5E12.5) for each of the x-stations. Conversely, options defined by NWCPT and NCPOUT will not work.

Card 3 - Option X-stations - Card 3 contains two real numbers punched in a 7-column field (2F7.0). Columns 73-80 may be used to identify the card. It is designated the XWLE card for reference. Card 3 reads the following:

<u>Column</u>	<u>Variable</u>	<u>Description</u>
1-7	XWLE	x-station of wing root chord leading edge. This variable has two meanings: 1) For NWCPT>0, XWLE is the reference distance from zero of the body axis coordinate system to the reference zero of the lifting surfaces whose control points are to be read from TAPE 4. It is added to the x-values read for the control points. 2) For NCPOUT = 1 or NVLIN=1, XWLE is the aft boundary of control points to be output or read in. It would correspond to the leading edge of the wing or tail surface root chord.
8-14	XSTART	x-station of start of region of additional velocity influence. For NCPOUT=1 or NVLIN=1, XSTART is the forward boundary of control points for which additional velocity components are computed or read in and control points calculated

Note: The special force calculation computes the loadings acting on the body panels with control points between x-locations XSTART and XWLE. For this calculation to be valid between these values, the user should also make the x-locations of appropriate panel leading or trailing edges correspond to the XSTART and XWLE locations as prescribed on the XFUSK card.

The geometry of the configuration may either be symmetrical or non-symmetrical about the y-0 plane (the plane of symmetry). The original configuration definition, which allowed only the description of symmetric

configurations, may be used to define only one side of the configuration or to define a paneling sequence for both sides. The input of both sides of the geometry is also allowed. The convention used in this program for definition of a symmetric configuration is to present that half of the configuration located on the positive y side of the y=0 plane. The number of input cards depends on the number of segments and the amount of detail used to describe each component. In connection with the work described in this report, disregard all references to wings, tails, and pods.

Card 4 - Control integers - Card 4 contains 24 integers, each punched right justified in a 3-column field. Columns 73-80 may be used in any desired manner. It is designated the JCARD in the data deck for reference. Card 4 contains the following:

<u>Column</u>	<u>Variable</u>	<u>Value</u>	<u>Description</u>
1-3	J0	0	No reference area
		1	Reference area to be read in
4-6	J1	0	Wing data option - not available
7-9	J2	0	No fuselage data
		1	Data for arbitrarily shaped fuselage to be read
		-1	Data for circular fuselage in form of cross sectional areas versus XFUS to be read
		-2	Data for circular fuselage in form of radii versus XFUS to be read
		-3	Data for elliptic fuselage in form of semi-axis in y-direction and semi-axis in z-direction to be read (With J6=0, fuselage will be cambered. With J6=-1, fuselage will be symmetrical with xy-plane. With J6=1, entire configuration will be symmetrical with y=0 plane.)
10-12	J3	0	Pod data option - not available
13-15	J4	0	Fin data option - not available
16-18	J5	0	Canard (horizontal tail) option - not available
19-21	J6	0	A cambered circular or arbitrary fuselage if J2 is nonzero. Read ZFUS data cards (described later under fuselage data cards)

APPENDIX K

<u>Column</u>	<u>Variable</u>	<u>Value</u>	<u>Description</u>
		1	Complete configuration is symmetrical with respect to xy-plane, which implies an uncambered circular fuselage
		-1	Uncambered circular fuselage with J2 nonzero
22-24	NWAF	0	Number of airfoil sections - not available
25-27	NWAFOR	0	Number of airfoil ordinates - not available
28-30	NFUS	1-4	Number of fuselage segments
31-33	NRADX(1)	3-30	Number of points used to represent the first fuselage segment about the circumference. If the configuration is symmetric (IXZSYM=0,1) NRADX is input for the half section. If the entire configuration is input (IXZSYM=-1) NRADX is input for the full section. If fuselage is circular, the program computes the indicated number of y- and z-ordinates
34-36	NFORX(1)	2-30	Number of x-stations for first fuselage segment
34-39	NRADX(2)	3-30	Same as NRADX(1), but for second fuselage segment
40-42	NFORX(2)	2-30	Same as NFORX(1), but for second fuselage segment
43-45	NRADX(3)	3-30	Same as NRADX(1), but for third fuselage segment
46-48	NFORX(3)	2-30	Same as NFORX(1), but for third fuselage segment
49-51	NRADX(4)	3-30	Same as NRADX(1), but for fourth fuselage segment
52-54	NFORX(4)	2-30	Same as NFORX(1), but for fourth fuselage segment
55-57	NP	0	Number of pods - not available
58-60	NPODOR	0	Number of pod stations - not available
61-63	NF	0	Number of fins - not available
64-66	NFINOR	0	Number of fin ordinates - not available
67-69	NCAN	0	Number of canards - not available
70-72	NCANOR	0	Number of canard ordinates - not available

Card 5,6,... - remaining input data cards - The remaining input data cards contain a detailed description of the body component configuration. Each card contains up to 10 values, each value punched in a 7-column field with a decimal point (10F7.0 format) and may be identified in columns 73-80. The cards are arranged in the following order as required by the above options: reference area card and fuselage data cards.

Reference area card: The reference area value is punched in columns 1-7 and may be identified as REFA in columns 73-80.

Fuselage data cards: The first card (or cards) specifies the x-values of the fuselage stations of the first segment. There will be NFORX(1) values and the cards may be identified in columns 73-80 by the symbols XFUSJ where J denotes the number of the last fuselage station given on that card. If the fuselage is cambered ($J2 < 0$, and $J6 = 0$) the z-values of the fuselage centerline are read next. There will be NFORX(1) values of z at the above x-stations.

If the fuselage is circular or elliptical, the next card (or cards) is specified according to option J2. If $J2 = -1$, the card contains NFORX(1) values of fuselage cross-sectional areas and may be identified in columns 73-80 by the symbol FUSARDJ where J denotes the number of the last fuselage stations given on that card. If $J2 = -2$, the card contains NFORX(1) values of fuselage section radii, and may be identified in columns 73-80 by the symbol FUSRADJ. If $J2 = -3$, two cards (or sets of cards) containing the elliptic body horizontal and vertical semi-axes are given. The first is the horizontal semi-axis and is designated by the symbol FUSBYJ. The second contains NFORX(1) values of the vertical semi-axis and is designated by the symbol FUSAZJ.

If the fuselage is of arbitrary shape, NRAD(1) values of the y-ordinates for a half section are given and identified in columns 73-80 as YJ where J is the station number. Following the y-ordinates are the NRADX(1) values of the corresponding z-ordinates for the half-section (or full section for IXZSYM = -1) identified in columns 73-80 as ZJ. Each station will have a set of y and z, and the convention of ordering the ordinates from bottom to top is observed. If the full section is given, the ordering continues from the top back to and including the bottom point to close the section.

APPENDIX K

For each fuselage segment a new set of cards as described must be provided. The segment descriptions should be given in the order of increasing values of x.

Description of Auxiliary Input Cards

Card 1 - Identification - Card 1 contains any desired identifying information in columns 1-80.

Card 2 - Boundary condition and control point definition - The specification of the lifting-surface boundary conditions are not applicable in the body alone version. This card also selects the output print options as originally described in reference 10. This card contains the following:

<u>Column</u>	<u>Variable</u>	<u>Value</u>	<u>Description</u>
1-3	LINBC	0	Planar boundary condition - not available
4-6	THICK	0	Thickness option - not available
7-9	IPRINT	0	Print out the pressures and the forces and moments
		1	Print out option 0 and spanwise loads on the wing, fins, and canards
		2	Print out option 1 and the velocity components and source and vortex strengths
		3	Print out option 2 and the steps in the iterative solution
		4	Print out option 3 and the axial and normal velocity matrices

A negative value of print adds the panel geometry print out to the output indicated for options 1 through 4.

LINBC, THICK, and IPRINT are punched as right justified integers.

Card 3 - Revised configuration paneling description control integers - The contents of card 2 are punched as right justified integers as follows:

<u>Column</u>	<u>Variable</u>	<u>Value</u>	<u>Description</u>
1-3	K0	0	No reference lengths
		1	Reference length data to be read

<u>Column</u>	<u>Variable</u>	<u>Value</u>	<u>Description</u>
4-6	K1	0	No wing data - not available
7-9	K2	0	No body data
		1	Body data follows
10-12	K3		Not used
13-15	K4	0	No fin (vertical tail) data - not available
16-18	K5	0	No canard (horizontal tail) data - not available
19-21	K6		Not used
22-24	KWAF	0	Number of wing sections - not available
25-27	KWAFOR	0	Number of wing ordinates - not available
28-30	KFUS		The number of fuselage segments. The program sets KFUS = NFUS
31-33	KRADX(1)	0, 3-20	Number of meridian lines used to define panel edges on first body segment. There are three options for defining the panel edges. If KRADX(1) = 0, the meridian lines are defined by NRADX(1) in the geometry input. If KRADX(1) is positive, the meridian lines are calculated at KRADX(1) equally spaced PHIKs. If KRADX(1) is negative, the meridian lines are calculated at specified values of PHIK. For symmetric configurations (IXZSYM=0,1), KRADX is the number of meridians on the half-section. For full configurations (IXZSYM=1), KRADX is the number of meridians on the full section including meridians at 0° and 360°
34-36	KFORX(1)	0, 2-30	Number of axial stations used to define leading and trailing edges of panels on first body segment. If KFORX(1) = 0, the panel edges are defined by NFORX(1) in the geometry input
37-39	KRADX(2)	0, 3-20	Same as KRADX(1), but for second body segment
40-42	KFORX(2)	0, 2-30	Same as KFORX(1), but for second body segment
43-45	KRADX(3)	0, 3-20	Same as KRADX(1), but for third body segment
46-48	KFORX(3)	0, 2-30	Same as KFORX(1), but for third body segment

APPENDIX K

<u>Column</u>	<u>Variable</u>	<u>Value</u>	<u>Description</u>
49-51	KRADX(4)	0, 3-20	Same as KRADX(1), but for fourth body segment
52-54	KFORX(4)	0, 2-30	Same as KFORX(1), but for fourth body segment

The program is restricted to 600 body singularity panels. For this program there is an additional restriction that the total number of singularity panels in the axial direction on the body (fuselage) cannot exceed 30. The arbitrary body (fuselage) capability of this program is limited to those shapes for which the radius is a single-valued function of PHIK for each cross section of the body.

Card 4,5,... - remaining input data cards - The remaining input data cards contain a detailed description of the singularity paneling of each component of the configuration. Each card contains up to 10 values, each value punched in a 7-column field with a decimal point (10F7.0 format) and may be identified in columns 73-80. The cards are arranged in the following order as required by the above options: reference lengths, vortex x-station card, and fuselage (body) data cards.

Reference length card: This card may be identified as REFL in columns 73-80 and contains the following:

<u>Column</u>	<u>Variable</u>	<u>Description</u>
1-7	REFA	Wing reference area. If REFA = 0, the reference area is defined by the value of REFA in the geometry input
8-14	REFB	Wing semispan - not used
15-21	REFC	Wing reference chord - not used
22-28	REFD	Body (fuselage) reference diameter. If REFD = 0, a value of 1.0 is used for the reference diameter. This reference length is used to non-dimensionalize all moment coefficients
29-35	REFL	Body (fuselage) reference length. If REFL = 0, a value of 1.0 is used for the reference length
36-42	REFX	x coordinate of moment center
43-49	REFZ	z coordinate of moment center

Vortex x-station card: This card is read if NXVTX is greater than zero. It is identified in columns 73-80 by the symbol XV. This card contains NXVTX values (maximum is 10) of the x-stations at which vortex strength and location will be input later, XV. These locations constitute the table in which the strength of the vortices will be obtained for each control point on the body in order to compute the cross flow solutions due to the presence of discrete vortices. The first and last x-values in this table also constitute boundaries between which vortex solutions will be computed. Outside of this range of x-stations, the contribution of the vortices will be set to zero. The values XV are punched in up to ten 7-column fields (10F7.0 format). The interpolation is currently limited by dimensions to 10 values of XV.

Fuselage (body) data cards: If KRADX(1) is negative, the first body card is the body meridian angle card. This card contains KRADX(1) values of body meridian angle expressed in degrees and may be identified in columns 73-80 as PHIKJ where J denotes the body segment number. The convention is observed that PHIK = 0, is at the bottom of the body and PHIK = 180, is at the top of the body. Repeat this card for each fuselage segment.

If KFORX(1) is non-zero, the second body card is the body axial station card. This card contains KFORX(1) values of the x-ordinate of the body axial stations and may be identified in columns 73-80 as XFUSKJ where J denotes the body segment number. Repeat this card for each fuselage segment. If forces and moments are to be integrated between values of XSTART and XWLE, the panel boundaries specified in XFUSK should correspond to one or both of these values where appropriate.

If either of these cards are omitted, the program generates the values internally from the previous configuration definition.

Description of case control cards

Card 1 - Mach number and angle of attack card - This card may be identified in columns 73-80 as MALPHA and contains the following in three 7-column fields:

APPENDIX K

<u>Column</u>	<u>Variable</u>	<u>Description</u>
1-7	MACH	The subsonic Mach number (including the value MACH = 0.) or the supersonic MACH number at which it is desired to calculate the aerodynamic data
8-14	ALPHAC	Included angle of attack at which it is desired to calculate the aerodynamic data, measured in degrees between the free-stream velocity vector and the body centerline
15-21	PHIR	Angle of roll, measured in degrees from the plane containing the free-stream velocity vector and the body centerline (the z-axis) positive clockwise

A value of MACH = -1 on this card signifies the termination of the present case. Geometry cards for a new case can follow such a terminal card.

Card 2,3,4... - Vortex strength and locations cards - If NVTX is greater than one, three cards are read for each of NVTX number of vortices. Each of the cards contains up to ten values punched in 7-column fields (10F7.0 format).

The first vortex card contains the y-location of the vortex at each of the x-stations on the XV card. There are NXVTX values on the card which is designated by the symbol YVRTXI where I is the vortex number in columns 73-80.

The second vortex card contains the z-location of the vortex at each of the x-stations on the XV card. There are NXVTX values on the card which is designated by the symbol ZVRTXI where I is the vortex number in columns 73-80.

The third vortex card contains the vortex strength divided by free stream velocity, Γ/V , of the vortex at each of the x-stations on the XV card. There are NXVTX values on the card which is designated by the symbol GAMI where I is the vortex number in columns 73-80.

A series of Mach number, angle of attack, and vortex card combinations for the same geometry may be calculated by repeating this sequence of case control cards with the desired values. If the case control sequence has been terminated by MACH = -1 on the MALPHA card an attempt

to read a new set of geometry will be made. The program will terminate if no cards exist by testing for the end of file.

Description of Output

This section describes the minimum output for the body source panel program, WDYBDY. This output occurs when IPRINT = -3 and IPRT(1)=1 in the input. All primary output items are summarized here. The outputs associated with source panel properties is described in detail in reference 10 and will only be mentioned here. A sample is given in connection with the description of the second calculative example, Section 6.2 and figure 26. For general reference the subroutine names from which the print was made is written starting in column 110 between two asterisks for the first occurrence of print within a routine. Wherever possible these identifications will be used in specifying the output to be described.

The first page of output is the list of the input cards copied directly from TAPE 5, on which it is stored, as card images. The input is rewound after copying to the output file (TAPE 6), and read again by the program as needed.

The next two (or more pages) are a copy of the input data with its mnemonic name or function as it is read from the input. The output is in the following order: the run title and option summary read in GEOM, the vehicle geometry cards as read by CONFIG, and the paneling title card and options as read by GEOM. If NXVTX>0, routine READVX prints a summary of body x-stations (XV) as read from input and the horizontal and vertical semi-axes of an elliptic section at those stations (BY and AZ). The horizontal and vertical axes are computed by interpolation in the program input geometr.

The next page is a summary of the body panel corner point coordinates as generated in BODPAN. The x,y,z coordinates of each corner point of each panel is printed. The next page is a summary of the x, y, and z coordinates of the body source panel centroids. The next page is a summary of the body panel areas and inclination angles in radian and degrees. The angle DELTA is the inclination of the source panel to the body x-axis and the angle THETA is the angle between the leading edge

APPENDIX K

of the panel and the body y-axis. These angle are indicated in the shock of Section 4.1. Additional output may be obtained for debugging purposes at the end of the geometry calculations as specified by the print options IPRT(2) and IPLOT(1).

The output from VELCMP is printed next summarizing the aerodynamic velocity matrix computations. The normal output is a summary of the numbers of panels and the CPU time required for the calculation of the velocity matrix coefficients. Output of the coefficients may be obtained from IPRINT=4. If the number of panels exceeds sixty, the solution vector is printed for intermediate iterations.

After the aerodynamic matrix has been computed a new case is begun from WDYBDY. This consists of the solution for the source strengths for a given Mach number, angle of attack, α_c , and angle of roll, ϕ . If the Mach number changes between cases, the program goes back to recompute the aerodynamic matrix.

The output from ELBDVT, concerned with body nose vorticity, is given next. A copy of the input y and z locations and the vortex strength, Γ/V , is printed first for the I'th vortex. This print is controlled by the option IPRT(1). A vortex interpolation table summarizing the strengths and locations of each of the discrete vortices to be used by VVELS in the computation of velocities induced by the nose separation vortices. The vortex trajectory is defined by XV, YVRTX, and ZVRTX for an elliptic body with horizontal and vertical semi-axes, BY and AZ. An additional debug output may be obtained for IPRT(3)=1 which summarizes the vortex properties at each of the control points as the velocities are computed.

The next page of output is printed from SOLVE summarizing the velocities on the body. For each of the panels the source strength, GB, and the axial, lateral and vertical velocity components, u, v, w, and the resultant inward normal, NB, due to only the source strength are given. In addition the velocity contributions due to discrete external vortices in the lateral and vertical directions, VA and WA, are printed. All velocity components are assumed to be positive in their respective positive coordinate directions. The sum of the contributions of the velocities due to source panels and discrete vortices is used in the calculation of pressures.

The next page of output is printed from FORMOM. It contains a summary of the forces on the panels due to the pressure acting on each of the panels. At each control point with coordinates X , Y , Z , and polar angle, $THETP$, measured positive counterclockwise from the positive y -axis, the pressure coefficient, CP , and the panel forces, CX , CY , and CZ acting along the body coordinate axes, and the moments of these forces about the reference center about each of the axes, CLL , CM , and CLN , are given. The pressure coefficient, CP , has a minimum value corresponding to zero static pressure, equation 11. The sense of the axial force, CX , is positive acting aft on the body; the force CY is positive acting to the right; and the force CZ is positive acting up. The pitching moment, CM , is positive nose up about the y -axis; the yawing moment, CLN , is positive nose right viewing downwards about the z -axis; and the rolling moment, CLL , is positive clockwise viewing forwards about the x -axis.

The total coefficients on the body are printed on the next page. These are the sum of the force components of the individual panels described above. The forces in the body coordinate system, CX , CY , and CZ are normalized by the reference area, $REFA$. The moments, CM , CLN , and CLL , have been normalized by the product of the reference area and the reference diameter, $REFD$. The moments are taken about the center, $(REFX, 0, REFZ)$. The x -location of the center of pressure, XCP , is printed as computed from the ratio, $-CM/CZ$. The force and moment coefficients are also specified in the wind axis system, see Section 4.2.

If distinct values of $XSTART$ and $XWLE$ have been specified the next two pages are a repeat of the previous two pages with the difference that only the forces and moments between $XSTART$ and $XWLE$ are computed. The total force coefficients are then the sum of the forces acting on panels between the above two variables. The program only checks on the location of control points within the x -range specified. For the integration to be valid the user must make the leading edges of the first ring of panels inside the range correspond to $XSTART$ and the trailing edges of the last ring of panels in the range must correspond to $XWLE$. This is necessary since only the integration over whole panels is within the current capability of the program.

APPENDIX K

The next page is printed when $NWCPT \neq 0$. It is a summary of the calculation of velocity components at specified field points. If $NWCPT > 0$, the field points are read from TAPE 4 as created by program DEMON2. If $NWCPT < 0$, the control points for panels generated within WDYBDY are used. In this case the velocities should reproduce the results first printed in SOLVE. The information printed by BDYVEL for each panel are the X, Y, Z of each field point at which the velocities is computed, the inclination angles, DELTA and THETA, and the velocity components, U, V, and W, in the coordinate axis directions, and the resultant outward normal velocity to the panel. The inclination angles δ and θ are defined either in the geometry definition. When the field points are read from TAPE 4 the angles are printed out as zero for the lack of better information.

This is the last page for a given case. The program will continue to read additional Mach number and α_c cases or new configurations until the end of data is reached. The output also continues to repeat as specified. The use of TAPE 4, however, is not organized to handle multiple cases at this time.

PROGRAM LISTINGS

The body modeling program is written in FORTRAN IV (029 punch) computer language for the CDC 6600 computer. The program consists of a main program, WDYBDY, and 42 subroutines. A listing of the program subroutine names in alphabetical order follows.

PROGRAM WDYBDY

<u>ROUTINE</u>	<u>IDENTIFICATION</u>	<u>PAGE NO.</u>
	col 73-76	
1. WDYBDY (main program)	WB01	312
2. BDYVEL	WB02	313
3. BODPAN	WB03	317
4. BODVEL	WB04	319
5. CDUMP	WB05	322
6. CPUTIM	WB06	324
7. COMCU	WB07	325

<u>ROUTINE</u>	<u>IDENTIFICATION</u>	<u>PAGE NO.</u>
	col 73-76	
8. CONFIG	WB08	326
9. CUBIC2	WB09	333
10. DBLU	WB10	333
11. DERIV	WB11	334
12. DERIV1	WB12	334
13. DERIV2	WB13	334
14. DIAGIN	WB14	335
15. DSDZ	WB15	336
16. DZDS	WB16	336
17. ELBDVT	WB17	336
18. FORMOM	WB18	338
19. GEOM	WB19	342
20. INVERT	WB20	345
21. ITRATE	WB21	346
22. MXOUT	WB22	349
23. NEWRAD	WB23	351
24. PANEL	WB24	353
25. PARTIN	WB25	356
26. PLOTA2	WB26	357
27. PLOTA3	WB27	360
Note: these subroutines are to be stored in LIBRARY (PLOTS) called by VPATH2, VPATHL, WDYBDY		
28. PLOTA5	WB28	363
29. PLOTA6	WB29	363
30. PLOTA7	WB30	365
31. PLOTA8	WB31	366
32. PLOTG	WB32	370
33. PLOTV2	WB33	372
34. PRESS	WB34	376
35. PRTCPT	WB35	377
36. READVX	WB36	378
37. RDVEL	WB37	379

APPENDIX K

<u>ROUTINE</u>	<u>IDENTIFICATION</u> col 73-76	<u>PAGE NO.</u>
38. SCAMP4	WB38	379
39. SOLVE	WB39	380
40. SORPAN	WB40	384
41. VELCMP	WB41	386
42. VVELS	WB42	389
43. Z	WB43	390

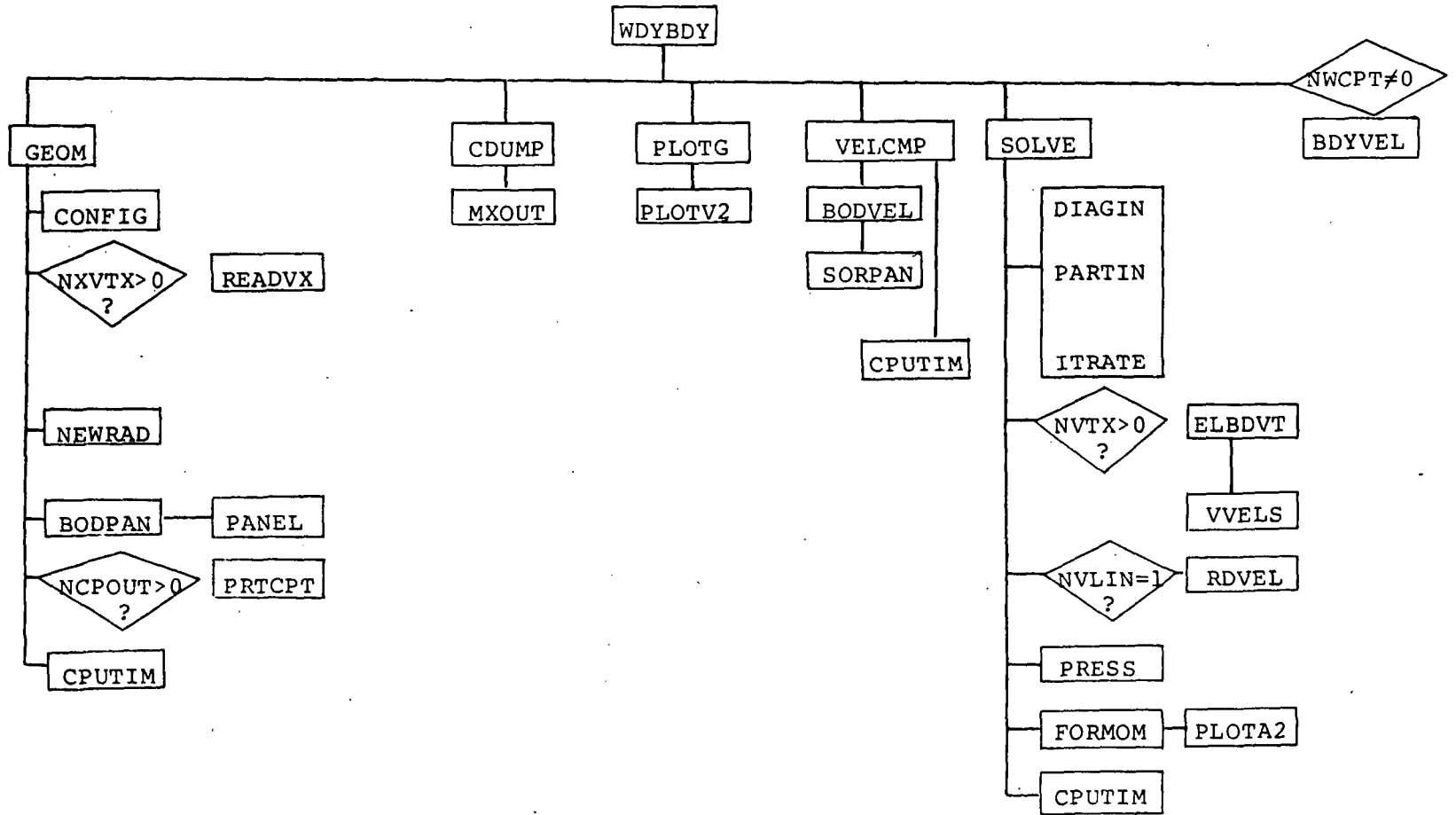


Figure K-1.- Program Subroutine Flow

PROGRAM WDYBDY

```

PROGRAM WBYHDY(OUTPUT, TAPE6=OUTPUT, TAPE4, TAPE5, TAPE7, WR01 1
1 TAPE8, TAPE9, TAPE10) WR01 2
C PROGRAM WBYHDY(INPUT, OUTPUT, TAPE5=INPUT, TAPE6=OUTPUT, TAPE7, WR01 3
CDC OVERLAY(LAB,0,0) WR01 4
C WR01 5
C ----- WR01 6
C BODY ONLY VERSION: JOE MULLEN, JUNE, 1977 WR01 7
C ----- WR01 8
C WR01 9
C PROGRAM WBYHDY COMPUTES THE SUBSONIC AND SUPERSONIC POTENTIAL WR01 10
C FLOW AERODYNAMIC CHARACTERISTICS OF BODY CONFIGURATIONS. WR01 11
C THE BODY IS REPRESENTED BY SOURCE PANELS. WR01 12
C THE THEORY IS DESCRIBED IN NASA CR-2228 (PART I) AND THE WR01 13
C COMPUTER PROGRAM IS DESCRIBED IN NASA CR-2228 (PART II). WR01 14
C WR01 15
C A CONVERGENCE CRITERIA TEST HAS BEEN INCORPORATED INTO SUBROUTINE WR01 16
C ITRATE TO CONTROL THE ITERATIVE SOLUTION PROCEDURE, THE MAXIMUM WR01 17
C NUMBER OF ITERATIONS AND THE CONVERGENCE CRITERIA TEST PARAMETER WR01 18
C HAVE BEEN ADDED TO THE PROGRAM INPUT. WR01 19
C WR01 20
C THE FOLLOWING ARE LIMITATIONS OR KNOWN PROBLEMS WR01 21
C WR01 22
C THE PROGRAM IS INTENDED TO HANDLE 600 BODY PANELS, WR01 23
C HOWEVER THE INPUT SPECIFIES CUTTING PLANES RATHER THAN WR01 24
C PANELS WHICH MAY LIMIT THE INPUT TO DEFINING LESS THAN 600 PANELS. WR01 25
C WR01 26
C THE PROGRAM WILL NOT HANDLE NACELLES. WR01 27
C WR01 28
C THE TRAILING VORTEX SHEET FROM THE WING LEAVES THE TRAILING EDGE WR01 29
C IN A PLANE PARALLEL TO THE X AXIS. WR01 30
C WR01 31
C COMMON /PARAM / NBODY, NWING, NTAIL, LHC, THK, XMACH, ALPHA, BETA, ALPHAC WR01 32
C , PHTP, REFA, REFB, REFC, REFD, REFL, REFX, REFZ WR01 33
C COMMON /VELCOM/ NPOINT, NPART, IMAX, JMAX, NMAX, EM, IPRINT, NATHK WR01 34
C , NARLEN, NARON(20), NBBLEN, NBRUN(60) WR01 35
C COMMON /JOPTS/ IZ1(60) WR01 36
C * , NCPROT, XSTART, XLEN, NWCPT, IPLOT(4), IPRT(5), IXZSYM WR01 37
C DIMENSION ICARD(8) WR01 38
C WR01 39
C CALL CPRTIM(TIME,DT,0) WR01 40
C ENB=1. WR01 41
C XMACH=1. WR01 42
C REWIND 5 WR01 43
C WRITE (6,90) WR01 44
C WRITE (6,100) WR01 45
C WR01 46
C LIST INPUT CARDS WR01 47
C WR01 48
C 10 READ (5,110) ICARD WR01 49
C IF (END(5)) 30,20,30 WR01 50
C 20 WRITE (6,120) ICARD WR01 51
C GO TO 10 WR01 52
C 30 CONTINUE WR01 53
C REWIND 5 WR01 54
C 50 WRITE (6,70) WR01 55
C WR01 56
C INPUT CONFIGURATION GEOMETRY AND COMPUTE PANELS WR01 57
C WR01 58
C CALL GEOM WR01 59
CDC CALL OVERLAY (LAB,1,0) WR01 60
C WR01 61
C GENERATE INTERMEDIATE PRINT AND PLOT GEOMETRY WR01 62
C WR01 63

```

CALL COMPP(IPRT(2),SHEND=GEOM).	WR01	64
IF (IPLOT(1),GT,0) CALL PLOTG	WR01	65
C	WR01	66
C INPUT MACH NUMBER AND COMPUTE AERODYNAMIC MATRIX	WR01	67
C A NEGATIVE MACH NUMBER IS USED TO TERMINATE MACH NUMBER AND ANGLE	WR01	68
C OF ATTACK CASES FOR A GIVEN GEOMETRY	WR01	69
C	WR01	70
60 CONTINUE	WR01	71
CALL VELCMP	WR01	72
CDC CALL OVERLAY (LMB,2,0)	WR01	73
CALL COMPP(IPRT(4),SHEND=VELC)	WR01	74
IF (XMACH,LT,0.) GO TO 50	WR01	75
WRITE (6,80)	WR01	75
C	WR01	77
C SOLVE RESULTING MATRIX EQUATIONS AND	WR01	78
C COMPUTE PRESSURES, FORCES, AND MOMENTS	WR01	79
C	WR01	80
CALL SOLVE	WR01	81
CDC CALL OVERLAY (LMB,3,0)	WR01	82
CALL COMPP(IPRT(5),SHEND=SOLV)	WR01	83
C	WR01	84
C COMPUTE ARBITRARY FIELD POINT VELOCITIES	WR01	85
C	WR01	86
IF (NDCPT,NE,0) CALL HDYVEL	WR01	87
GO TO 60	WR01	88
70 FORMAT (1H1,20X,25HBEGIN A NEW CONFIGURATION,64X,12H** WDYRDY **)	WR01	89
80 FORMAT (1H1,20X,16HBEGIN A NEW CASE,73X,12H** WDYRDY **)	WR01	90
90 FORMAT (1H1,10X,57H*****ARD*S SOURCE PANEL BODY MODELING,	WR01	91
1 SH PROGRAM,10X,16HDATED JUNE, 1977)	WR01	92
100 FORMAT (1H0,25X,19HLIST OF INPUT CARDS//)	WR01	93
110 FORMAT (A10)	WR01	94
120 FORMAT (10X,A10)	WR01	95
END	WR01	96

SUBROUTINE HDYVEL	WR02	1
C	WR02	2
C COMPUTE THE THREE COMPONENTS OF VELOCITY INDUCED AT SPECIFIED	WR02	3
C FIELD POINTS BY THE BODY PANELS. GIVEN THE STRENGTHS, GR, OF	WR02	4
C BODY SOURCE PANELS COMPUTE THE FLU VELOCITY COMPONENTS INDUCED	WR02	5
C BY BODY SOURCE PANELS AT SPECIFIED POINTS (I.E. WING MONOPLANE	WR02	6
C CENTROIDS)	WR02	7
C	WR02	8
COMMON /JOPTS/ IZ1(62),XWLE,WCPT,IPLOT(4),IPRT(5),IXZSYM	WR02	9
COMMON /PARAM / NRODY,NWING,NTAIL,LRC,THR,VMACH,ALPHA,BETA,ALPHAC	WR02	10
1 ,PHIR,REFA,REFB,REFC,REFD,REFE,REFX,REFZ	WR02	11
COMMON /VELCOM/ NPOINT,NPART,IZH(2),NMAX,EM,IPRINT,NWTHK	WR02	12
1 ,NBLK,NWRD*(20),NBLK,NHRD*(60)	WR02	13
COMMON /NECOM/K1,KAF,KAFOR,KRAX(4),KFORX(4),KFS,MAX,K4,K5	WR02	14
1 ,KF(6),KAR(6),KFINR(6),KANR(6),KOL,NCPPT,LCCPT(20),XCPT(20)	WR02	15
COMMON / / U(600),V(600),X(600),YI(600),ZI(600),	WR02	16
1 ZR(600),ART(600),YRT(600),ZRT(600),GW(600),GH(600),Z9(600)	WR02	17
COMMON /POINT / XPT(600),YPT(600),ZPT(600),THET(600),DELTA(600),	WR02	18
1 XC(30,20),YC(30,20),ZC(30,20),DELTA(600),XLE(600)	WR02	19
COMMON /BODCOM/ AMACH,TAND,CX,XCOR(4),YCOR(4),ZCOR(4)	WR02	20
1 ,XI,YI,ZI,XJ,ZJ	WR02	21
COMMON /RTHET / THETA(600)	WR02	22
C	WR02	23
DIMENSION ARRAY(6000)	WR02	24

	EQUIVALENC	(XPT(1),ARRAY(1))	WR02	25
	LOGICAL LHC		WR02	26
	DATA RADDEG/0.0174532926/		WR02	27
	DATA ICASE/0/		WR02	28
	ICASE=ICASE+1		WR02	29
C			WR02	30
	AMACH=XMACH		WR02	31
C			WR02	32
C	READ BODY GEOMETRY COORDINATES		WR02	33
C			WR02	34
	IF (NRBODY,LE,0) RETURN		WR02	35
	REWIND 7		WR02	36
	READ (7) ARRAY		WR02	37
	DO 10 I=1,NRBODY		WR02	38
	DELTA(I)=DELTA(I)		WR02	39
	THETA(I)=THETA(I)		WR02	40
	XBT(I) = XPT(I)		WR02	41
	YBT(I) = YPT(I)		WR02	42
10	ZBT(I) = ZPT(I)		WR02	43
C			WR02	44
C	READ WING CONTROL POINTS		WR02	45
C			WR02	46
	IF (NWCPT,LT,0 .OR. ICASE,GT,1) GO TO 30		WR02	47
C			WR02	48
C	IF NWCPT IS LESS THAN 0 USE BODY POINTS*		WR02	49
C	IF NWCPT IS GREATER THAN 0 READ POINTS FROM INPUT FILE ON TAPE 4		WR02	50
C			WR02	51
	REWIND 4		WR02	52
	READ (4,745) NWRP		WR02	53
	READ (4,745) (J,XPT(I),YPT(I),ZPT(I),I=1,NWCPT)		WR02	54
	DO 20 J=1,NWCPT		WR02	55
	THETA(I)=0.0		WR02	56
	DELTA(I)=0.0		WR02	57
	XPT(I)=XPT(I)+XWLE		WR02	58
20	CONTINUE		WR02	59
C			WR02	60
C	FIND END OF CONTROL POINT DATA ON TAPE 4.		WR02	61
C			WR02	62
	JPI=NWCPT+1		WR02	63
	IF (NWRP,GT,NWCPT) READ (4,745) (J,XDUM,YDUM,ZDUM,I=JPI,NWRP)		WR02	64
30	IF (NWCPT,LT,0) NWCPT=NRBODY		WR02	65
C			WR02	66
C	I IS THE INDEX OF THE FIELD POINT		WR02	67
C	J IS THE INDEX OF THE INFLUENCING PANEL		WR02	68
C			WR02	69
	WRITE(6,170)		WR02	70
C			WR02	71
C	COORDINATES OF I-TH FIELD POINT		WR02	72
C			WR02	73
	DO 110 I=1,NWCPT		WR02	74
	SINTI=SIN(THETA(I))		WR02	75
	COSTI=COS(THETA(I))		WR02	76
	YPTI=XPT(I)		WR02	77
	YPTI=YPT(I)		WR02	78
	ZPTI=ZPT(I)		WR02	79
C			WR02	80
C			WR02	81
C			WR02	82
	SIND=SIN(DELTA(I))		WR02	83
	COSD=COS(DELTA(I))		WR02	84
	SUMU = 0.		WR02	85
	SUMV = 0.		WR02	86
	SUMW = 0.		WR02	87

```

SUMN = 0.
J=0
JPN=0
I=0
DO 70 KFU=1,KFUS
NRD=KRADY(KFU)-1
NCL=KCRX(KFU)-1
DO 60 NC=1,NCL
L=L+1
JPI=1+JPN
JPN=JPI+NRD*-1
DO 50 N=1,NRD
J=J+1
TAND=TAN(DELTA(J))
COST=COS(THETA(J))
SINT=SIN(THETA(J))
XW=SINT*COSTI
XX=COST*SINTI
XY=COST*CSTI
XZ=SINT*SINTI
SINTR=X*-XX
COSTR=XY+XZ
NP1=N+1
XC1=XC(L,NP1)
YC1=YC(L,NP1)
ZC1=ZC(L,NP1)
C
C CALCULATION OF PANEL CORNER POINTS IN PANEL COORDINATE SYSTEM
C
XCOR(1)=0.
YCOR(1)=0.
ZCOR(1)=0.
XCOR(2)=XC(L+1,NP1)-XC1
YCOR(3)=0.
ZCOR(4)=ZCOR(2)
DO 40 K=2,4
LP1=L+1
NP1=N+1
IF (K,GE,3) NP1=N
IF (K,EQ,3) LP1=L
DELY=YC(LP1,NP1)-YC1
DELZ=ZC(LP1,NP1)-ZC1
YCOR(K)=DELY*COST+DELZ*SINT
ZCOR(K)=DELZ*COST-DELY*SINT
40 CONTINUE
CX=XCOR(2)
C
C CALCULATION OF FIELD POINT IN PANEL COORDINATE SYSTEM
C
XI=XPJI-XC1
YI=YPTI-YC1
ZI=ZPTI-ZC1
YI=OY*COST+OZ*SINT
ZI=OZ*COST-OY*SINT
XJ=XHT(J)-XC1
YJ=YHT(J)-YC1
ZJ=ZHT(J)-ZC1
ZJ=OZJ*COST-OYJ*SINT
C
C CALCULATE VELOCITY COMPONENTS INDUCED BY CONSTANT SOURCE
C DISTRIBUTION PANELS
C
CALL SORPAN(UR,VR,WR)

```

```

WR02 88
WR02 89
WR02 90
WR02 91
WR02 92
WR02 93
WR02 94
WR02 95
WR02 96
WR02 97
WR02 98
WR02 99
WR02 100
WR02 101
WR02 102
WR02 103
WR02 104
WR02 105
WR02 106
WR02 107
WR02 108
WR02 109
WR02 110
WR02 111
WR02 112
WR02 113
WR02 114
WR02 115
WR02 116
WR02 117
WR02 118
WR02 119
WR02 120
WR02 121
WR02 122
WR02 123
WR02 124
WR02 125
WR02 126
WR02 127
WR02 128
WR02 129
WR02 130
WR02 131
WR02 132
WR02 133
WR02 134
WR02 135
WR02 136
WR02 137
WR02 138
WR02 139
WR02 140
WR02 141
WR02 142
WR02 143
WR02 144
WR02 145
WR02 146
WR02 147
WR02 148
WR02 149
WR02 150

```

```

      UBJ=UR
      VIJ=VR+COSTR=WR*SINTR
      WIJ=VR*SINTR+WR*COSTR
      UL=0.
      VL=0.
      WL=0.
C
C CALCULATE VELOCITY COMPONENTS FROM LEFT SIDE FOR SYMMETRIC
C CONFIGURATIONS INDUCED BY CONSTANT SOURCE PANEL
C
      IF (IXZSYN.EQ.0) GO TO 45
      SINTL=XX+XX
      COSTL=XY-YZ
      OY=-YPTI-YC1
      VI=OY*COST+OZ*SINT
      ZI=OZ*COST-OY*SINT
      CALL SORPAR(UL,VL,WL)
      UBJ=UBJ+UL
      VIJ=VIJ+VL+COSTL+WL*SINTL
      WIJ=WIJ+VL*SINTL+WL*COSTL
45 CONTINUE
C
      VRJ=VIJ+COSTI-WIJ*SINTI
      WBJ=WIJ+COSTI+VIJ*SINTI
      ANJ=WIJ+COSD=URJ*SIND
      SUMU = SUMU+URJ*GB(J)
      SUMV = SUMV+VRJ*GB(J)
      SUMA = SUMA+ANJ*GB(J)
      SUMN = SUMN+ANJ*GB(J)
50 CONTINUE
60 CONTINUE
70 CONTINUE
C
C COMPUTE VELOCITY AT I-TH FIELD POINT
C
      U(I) = SUMU
      V(I) = SUMV
      W(I) = SUMA
      ALP=ALPHA*RA0DEG
      PHI=PHIR*RA0DEG
      SINAL=SIN(ALP)
      COSAL=COS(ALP)
      SINPHI=SIN(PHI)
      COSPHI=COS(PHI)
      HWI=COSAL*SIN(DELTA(I))+COS(DELTA(I))*(-SINAL+COS(THET(I)))
      * +SINAL*SIN(THET(I))
C
C
      WRITE(6,180) I,YPT(I),VPT(I),ZPT(I),THET(I),DELTA(I)
      * ,U(I),V(I),W(I),SUMN
110 CONTINUE
C
C WRITE VELOCITIES INDUCED AT FIELD POINTS AFTER CONTROL POINT DATA
C ON TAPE 4.
C
      WRITE(4,745) NWCPT,XMACH,ALPHAC,PHIR
      WRITE(4,745) (I,U(I),V(I),W(I),I=1,NWCPT)
      RETURN
C
170 FORMAT (1M1,10X,4MPERTURBATION VELOCITIES AT SPECIFIED CONTROL
* 2M POINTS BY SOURCE PANELS ,31X,12M** BODYVEL **
* ,//7X,13MCONTROL POINT,20X,12MPANEL ANGLES,10X,10MVELOCITIES,

```

```

* //AN JCPT,5X,1HA,9X,1HY,9X,1HZ,7X,4HTHET,5X,5DELTA,AX,1HU
* ,9X,1HV,9X,1HA,6X,ANNORMAL/)
130 FORMAT(15,5F10,5,5F10,5)
745 FORMAT(15,3E12,5)
END

```

```

*H02 214
*H02 215
*H02 216
*H02 217
*H02 21A

```

```

SUBROUTINE BODPAN
OVERLAY (LWB,1,5)
PROGRAM BODPAN
C
C REVISE AXIAL SPACING ON BODY (FUSELAGE) AND COMPUTE NEW PANEL
C GEOMETRY
C
COMMON /JPOINTS/ IZ1(8)
1 J1,J2,J3,J4,J5,J6,KKAF,KKAFOR,NFUS,NRADX(4),NFORX(4)
2 NP,NPOR,NF,NFINGR,NCAN,NCANOR,J2TEST,NK
3 IZ2(34),IPRT(5),IYZSYM
COMMON /PARAM / NBODY,NWING,NTAIL,LHC,THK,VMACH,ALPHA,BETA,ALPHAC
1 PHIR,REFA,REFB,REFC,REFD,REFL,REFY,REFZ
COMMON /BLOCK/ BLOCK(7500)
COMMON /POINT / ARRAY(6000)
COMMON /EACOM/ K1,KKAF,KKAFOR,KRADX(4),KFORX(4),KFUS,KAX,K4,K5
1 KF(6),KAN(6),KFINDR(6),KANOR(6),KOL,KCPT,LOCPT(20)
COMMON /VELCOM/ NPOINT,NPART,IZ4(2),NMAX,EM,IPRINT,NTHK
1 NHBLOCK,NBROW(20),NBHLOCK,NBROW(60)
COMMON /THET / THETA(600)
C
DIMENSION XR(30),YR(30,30),ZR(30,30),XJ(60),AREA(600),XPT(600),
1 YPT(600),ZPT(600),THET(600),DELTA(600),XC(30,20),YC(30,20),
2 ZC(30,20),XFUS(30,4)
C
EQUIVALENCE (BLOCK(1),XFUS(1,1)), (BLOCK(121),YS(1,1))
1 (BLOCK(5721),XZ(1,1)), (BLOCK(1921),ZB(1,1))
EQUIVALENCE (XPT(1),ARRAY(1)), (YPT(1),ARRAY(601))
* (ZPT(1),ARRAY(1201)), (THET(1),ARRAY(1801))
* (DELTA(1),ARRAY(2401)), (XC(1,1),ARRAY(3001))
* (YC(1,1),ARRAY(3601)), (ZC(1,1),ARRAY(4201))
* (AREA(1),ARRAY(4801))
C
XIN(X1,Y1,X2,Y2,Y)=X1+(X2-X1)*(Y-Y1)/(Y2-Y1)
C
RADFG=180./3.141592654
REWIND 10
IF (IPRINT,LT,0) WRITE (6,220)
C
C CALCULATE COORDINATES OF PANEL CORNERS
C JP = INDEX OF PANEL NUMBER (TOTAL=NBODY)
C JM = TOTAL NUMBER OF AXIAL STATIONS (MAX=30)
C
10 JS1
LEU
JP=0
JM=0
DO 120 NFUS=1,NFUS
KFORX=KFORX(NFUS)
NFORX=NFORX(NFUS)
KRADX=KRADX(NFUS)
KRAD=IABS(KRAD)
IF (KRAD,EG,0) KRAD=KRADX(NFUS)

```

```

*H03 1
*H03 2
*H03 3
*H03 4
*H03 5
*H03 6
*H03 7
*H03 8
*H03 9
*H03 10
*H03 11
*H03 12
*H03 13
*H03 14
*H03 15
*H03 16
*H03 17
*H03 18
*H03 19
*H03 20
*H03 21
*H03 22
*H03 23
*H03 24
*H03 25
*H03 26
*H03 27
*H03 28
*H03 29
*H03 30
*H03 31
*H03 32
*H03 33
*H03 34
*H03 35
*H03 36
*H03 37
*H03 38
*H03 39
*H03 40
*H03 41
*H03 42
*H03 43
*H03 44
*H03 45
*H03 46
*H03 47
*H03 48
*H03 49
*H03 50
*H03 51
*H03 52
*H03 53

```

	READ (10) XH,YR,ZR	WR03 54
	IF (KFUSOR,EG,0) GO TO 20	WR03 55
C		WR03 56
C	READ IN NEW AXIAL STATIONS (XJ) FOR BODY (FUSELAGE)	WR03 57
C		WR03 58
	READ (5,210) (XJ(K),K=1,KFUSOR)	WR03 59
	GO TO 50	WR03 60
20	KFUSOR=NFORX(NFU)	WR03 61
	IF (KFUSOR.LE.30) GO TO 30	WR03 62
	WRITE (6,190) NFU	WR03 63
	STOP 20	WR03 64
C		WR03 65
C	USE ORIGINAL AXIAL STATIONS XJ=XFUS	WR03 66
30	KFORX(NFU)=KFUSOR	WR03 67
	DO 40 K=1,KFUSOR	WR03 68
	XJ(K)=XFUS(K,NFU)	WR03 69
40	CONTINUE	WR03 70
50	JM=JM+KFUSOR	WR03 71
	IF (JM.LE.30) GO TO 60	WR03 72
	WRITE (6,200)	WR03 73
	STOP 50	WR03 74
C		WR03 75
C	INITIALIZE COORDINATES EQUAL TO SEGMENT LEADING EDGE	WR03 76
60	DO 70 K=1,KRAD	WR03 77
	XC(J,K)=XB(1)	WR03 78
	YC(J,K)=YB(1,K)	WR03 79
	ZC(J,K)=ZB(1,K)	WR03 80
70	CONTINUE	WR03 81
C		WR03 82
C	INTERPOLATE FOR REMAINING PANEL COORDINATES -----	WR03 83
	DO 110 JJ=2,KFUSOR	WR03 84
	JM1=J	WR03 85
	J=J+1	WR03 86
C		WR03 87
C	FIND X-STATION	WR03 88
C		WR03 89
	DO 100 M=2,NFUSOR	WR03 90
	MM1=M-1	WR03 91
	IF (XH(M),LY,XJ(JJ)) GO TO 100	WR03 92
	DO 90 K=1,KRAD	WR03 93
	XC(J,K)=XJ(JJ)	WR03 94
	YC(J,K)=XIP((YB(MM1,K),XB(MM1),YB(M,K),XH(M),XJ(JJ)))	WR03 95
	ZC(J,K)=XIP((ZB(MM1,K),XB(MM1),ZB(M,K),XH(M),XJ(JJ)))	WR03 96
	IF (K.EQ.1) GO TO 90	WR03 97
	KM1=K-1	WR03 98
	JP=JP+1	WR03 99
C		WR03 100
C	CALCULATE PANEL INCLINATION AND CENTROID	WR03 101
C		WR03 102
	CALL PANEL(O,O,J,K,L,JP,AP)	WR03 103
C		WR03 104
C	PRINT BODY PANEL COORDINATES	WR03 105
	IF (IPRINT,GE,0) GO TO 80	WR03 106
	WRITE (6,240) JP,XC(JM1,KM1),YC(JM1,KM1),ZC(JM1,KM1),XC(J,KM1),	WR03 107
	1 YC(J,KM1),ZC(J,KM1),XC(JM1,K),YC(JM1,K),ZC(JM1,K),	WR03 108
	2 XC(J,K),YC(J,K),ZC(J,K)	WR03 109
80	AREA(JP)=AP	WR03 110
90	CONTINUE	WR03 111
	GO TO 110	WR03 112
100	CONTINUE	WR03 113
110	CONTINUE	WR03 114
120	CONTINUE	WR03 115
C		WR03 116

```

NRBODY=JP
IF (NRBODY.GT.600) GO TO 170
IF (IPRINT.GE.0) GO TO 150
WRITE (6,250)
DO 130 JP=1,NRBODY
WRITE (6,270) JP,XPT(JP),YPT(JP),ZPT(JP)
130 CONTINUE
WRITE (6,280)
DO 140 JP=1,NRBODY
DDEG=DELTA(JP)*RADEG
TDEG=THET(JP)*RADEG
WRITE (6,270) JP,AREA(JP),DELTA(JP),THET(JP),DDEG,TDEG
140 CONTINUE
150 DO 160 JP=1,NRBODY
THETA(JP)=THET(JP)
160 CONTINUE
C
C STORE BODY GEOMETRY ON TAPE 7
C
WRITE (7) ARRAY
REWIND 10
RETURN
170 WRITE (6,300)
STOP
190 FORMAT (50H ERROR = NUMBER OF ROWS OF PANELS IN BODY SECTION
1 15,2X,10H EXCEEDS 30)
200 FORMAT (49H ERROR = NUMBER OF ROWS OF SINGULARITY PANELS ON
1 16H BODY EXCEEDS 30)
210 FORMAT (10F7.0)
220 FORMAT (1H1,9X,35H BODY PANEL CORNER POINT COORDINATES
* 65X,12H** 80DPAN ** ,///10X,5H1 AND
1 60H 3 INDICATE BODY PANEL LEADING-EDGE POINTS, 2 AND 4 INDICATE
2 21H TRAILING-EDGE POINTS/5X,5HPANEL,4(8X,1HX,8X,1HY,8X,1HZ)/
3 19X,3(1H1,8X),3(1H2,8X),3(1H3,8X),3(1H4,8X)/)
240 FORMAT (18,4X,12F9.5)
250 FORMAT (1H1,3PH BODY PANEL CENTROID POINT COORDINATES
1 //4X,5HPPOINT,4X,1HX,10X,1HY,10X,1HZ/15X,3(2HCP,9X)/)
270 FORMAT (18,1X,4F11.5,F11.3)
280 FORMAT (1H1,4X,39H BODY PANEL AREAS AND INCLINATION ANGLES/
1 1H0,3X,5HPANEL,2X,4HAREA,7X,5HDELTA,6X,5HTHETA,6X,5HDELTA,6X,
2 5HTHETA/24X,3HRA0,8X,3HRA0,8X,3HDEG,8X,3HDEG/)
300 FORMAT (43H ERROR = NUMBER OF BODY PANELS EXCEEDS 600)
END

```

```

WR03 117
WR03 118
WR03 119
WR03 120
WR03 121
WR03 122
WR03 123
WR03 124
WR03 125
WR03 126
WR03 127
WR03 128
WR03 129
WR03 130
WR03 131
WR03 132
WR03 133
WR03 134
WR03 135
WR03 136
WR03 137
WR03 138
WR03 139
WR03 140
WR03 141
WR03 142
WR03 143
WR03 144
WR03 145
WR03 146
WR03 147
WR03 148
WR03 149
WR03 150
WR03 151
WR03 152
WR03 153
WR03 154
WR03 155
WR03 156
WR03 157
WR03 158
WR03 159

```

```

SUBROUTINE H00VEL
C
C COMPUTE THE THREE COMPONENTS OF VELOCITY INDUCED AT SPECIFIED
C CONTROL POINTS BY THE BODY PANELS
C
COMMON /JOPTNS/ IZ1(73),IXZSY
COMMON /PARAM / NRBODY,NWING,NTAIL,LHC,THK,XMACH,ALPHA,BETA,ALPHAC
1 ,PHIR,PEFA,REFA,REFB,REFC,REFD,REFL,REFX,REFZ
COMMON /VELCOM/ NPOINT,NPART,IMAX,JMAX,NMAX,EM,IPRINT,NWTHK
1 ,NWBLK,NWROK(20),NBHLOK,NBROK(30)
COMMON /NEWCOM/K1,K-AP,K-AP0R,KRADX(4),KFORX(4),KFUS,K4,K5
1 ,KF(6),KAN(6),KFINDR(6),KANOR(6),KNL,NCPT,LOCPT(20),XCPT(20)
COMMON
1 UB(600),VB(600),WB(600),VI(600),*I(600),AN(600),
1 DN(60),ZB(240),XBT(600),YBT(600),ZHT(600),IT(600),Z9(1200)

```

```

WR04 1
WR04 2
WR04 3
WR04 4
WR04 5
WR04 6
WR04 7
WR04 8
WR04 9
WR04 10
WR04 11
WR04 12
WR04 13
WR04 14

```

	COMMON /PPOINT / XPT(600),YPT(600),ZPT(600),THET(600),DELTA(600),	WR04	15
1	XC(30,20),YC(30,20),ZC(30,20),DELTI(600),XLE(600)	WR04	16
	COMMON /BNDCOM/ AMACH,TAND,CX,XCOR(4),YCOR(4),ZCOR(4)	WR04	17
1	,XI,YI,ZI,XJ,ZJ	WR04	18
	COMMON /HTHET / THETA(600)	WR04	19
	LOGICAL LRC	WR04	20
	AMACH=XMACH	WR04	21
	JMAX=MAX	WR04	22
	II=0	WR04	23
C		WR04	24
C	I IS THE INDEX OF THE CONTROL POINT	WR04	25
C	J IS THE INDEX OF THE INFLUENCING PANEL	WR04	26
C		WR04	27
	DO 110 I=1,NPPOINT	WR04	28
	IF (LRC .AND. I.EQ.IT(I) .AND. NPART.EQ.3) GO TO 110	WR04	29
	II=II+1	WR04	30
	SINTI=SIN(THET(I))	WR04	31
	COSTI=COS(THET(I))	WR04	32
	XPTI=XPT(I)	WR04	33
	YPTI=YPT(I)	WR04	34
	ZPTI=ZPT(I)	WR04	35
	IF (NPART.EQ.3) GO TO 10	WR04	36
C	BODY PANEL INCIDENCE ANGLE	WR04	37
	SIND=SIN(DELTA(I))	WR04	38
	COSD=COS(DELTA(I))	WR04	39
	GO TO 20	WR04	40
C	WING PANEL INCIDENCE ANGLE	WR04	41
10	DELT=0.	WR04	42
CNP	IF (.NOT.LRC) DELT=DELTI(I)	WR04	43
	SIND=SIN(DELT)	WR04	44
	COSD=COS(DELT)	WR04	45
20	DO 30 J=1,NBODY	WR04	46
	UB(J)=0.	WR04	47
	VI(J)=0.	WR04	48
	WI(J)=0.	WR04	49
30	CONTINUE	WR04	50
	J=0	WR04	51
	JPN=0	WR04	52
	L=0	WR04	53
	DO 70 KFU=1,KFIS	WR04	54
	NR0=KXRAOX(KFU)-1	WR04	55
	NCOL=KFORY(KFU)-1	WR04	56
	DO 60 NC=1,NCOL	WR04	57
	L=L+1	WR04	58
	JPI=1+JPN	WR04	59
	JPN=JPI+NR0+1	WR04	60
	DO 50 NB=1,NB04	WR04	61
	J=J+1	WR04	62
	TAND=TAN(DELTA(J))	WR04	63
	COST=COS(THETA(J))	WR04	64
	SINT=SIN(THETA(J))	WR04	65
	X=XSINT*COSTI	WR04	66
	XY=COST*SINTI	WR04	67
	Y=COST*COSTI	WR04	68
	XZ=SINT*SINTI	WR04	69
	SINTREX=X-XY	WR04	70
	SINTLX=X+XY	WR04	71
	COSTREX=Y+XZ	WR04	72
	COSTLY=Y-XZ	WR04	73
	NPIS=NP+1	WR04	74
	XC1=XC(L,NP1)	WR04	75
	YC1=YC(L,NP1)	WR04	76
	ZC1=ZC(L,NP1)	WR04	77

C		4804	78
C	CALCULATION OF PANEL CORNER POINTS IN PANEL COORDINATE SYSTEM	4804	79
C		4804	80
	XCOR(1)=0.	4804	81
	YCOR(1)=0.	4804	82
	ZCOR(1)=0.	4804	83
	XCOR(2)=XC(L+1, NP1)-XC1	4804	84
	XCOR(3)=0.	4804	85
	XCOR(4)=YCOR(2)	4804	86
	DO 40 K=2,4	4804	87
	LP1=L+1	4804	88
	NP1=N+1	4804	89
	IF (K,6F,4) NP1=N	4804	90
	IF (K,6F,3) LP1=L	4804	91
	OELY=YC(LP1, NP1)-YC1	4804	92
	OELZ=ZC(LP1, NP1)-ZC1	4804	93
	YCOR(K)=OELY*COST+OELZ*SINT	4804	94
	ZCOR(K)=OELZ*COST-OELY*SINT	4804	95
40	CONTINUE	4804	96
	CX=XCOR(2)	4804	97
C		4804	98
C	CALCULATION OF CONTROL POINT IN PANEL COORDINATE SYSTEM	4804	99
C		4804	100
	YI=YPTI-YC1	4804	101
	OY=YPTI-YC1	4804	102
	OZ=ZPTI-ZC1	4804	103
	YI=OY*COST+OZ*SINT	4804	104
	ZI=OZ*COST-OY*SINT	4804	105
	XJ=XRT(J)-XC1	4804	106
	OYJ=YBT(J)-YC1	4804	107
	OZJ=ZBT(J)-ZC1	4804	108
	ZJ=OZJ*COST-OYJ*SINT	4804	109
C		4804	110
C	CALCULATE VELOCITY COMPONENTS INDUCED BY CONSTANT SOURCE	4804	111
C	DISTRIBUTION PANELS	4804	112
C		4804	113
	CALL SORPAN(UR,VR,WR)	4804	114
	UR(J)=UR	4804	115
	VI(J)=VR*COSTR+WR*SINTR	4804	116
	WI(J)=VR*SINTR+WR*COSTR	4804	117
	UL=0.	4804	118
	VL=0.	4804	119
	WL=0.	4804	120
C		4804	121
C	CALCULATE VELOCITY COMPONENTS FROM LEFT SIDE FOR SYMMETRIC	4804	122
C	CONFIGURATIONS INDUCED BY CONSTANT SOURCE PANEL	4804	123
C		4804	124
	IF (IYZSYM,NE,0) GO TO 45	4804	125
	OY=-YPTI-YC1	4804	126
	YI=OY*COST+OZ*SINT	4804	127
	ZI=OZ*COST-OY*SINT	4804	128
	CALL SORPAN(UL,VL,WL)	4804	129
	UR(J)=UR(J)+UL	4804	130
	VI(J)=VI(J)-VL*COSTL+WL*SINTL	4804	131
	WI(J)=WI(J)+VL*SINTL+WL*COSTL	4804	132
45	CONTINUE	4804	133
C		4804	134
C	CALCULATE VELOCITY COMPONENTS IN ORIGINAL COORDINATE SYSTEM	4804	135
C		4804	136
	VR(J)=VI(J)*COSTI+WI(J)*SINTI	4804	137
	WR(J)=WI(J)*COSTI+VI(J)*SINTI	4804	138
	AR(J)=AI(J)*COSD+AS(J)*SIND	4804	139
	IF (NPART,GT,1,OR,NBODY,LE,NMAX) GO TO 50	4804	140

	IF (II.LT.JP1.OR.II.GT.JPN) GO TO 50	WR04 141
	JS1=JP1	WR04 142
	JS2=JPN	WR04 143
	NS=NROW	WR04 144
50	CONTINUE	WR04 145
60	CONTINUE	WR04 146
70	CONTINUE	WR04 147
	JMAX=L	WR04 148
	IF (NBODY.LE.NMAX.OR.NPART.GT.1) GO TO 90	WR04 149
C		WR04 150
C	STORE DIAGONAL BLOCKS OF AERODYNAMIC MATRIX IN DN ARRAY	WR04 151
C		WR04 152
	DO NO J=1,NBODY	WR04 153
	IF (J.LT.JS1.OR.J.GT.JS2) GO TO 80	WR04 154
	K=J-JS1+1	WR04 155
	DN(K)=AN(J)	WR04 156
	AN(J)=0.	WR04 157
80	CONTINUE	WR04 158
	WRITE (10) (DN(J),J=1,NS)	WR04 159
90	IF (IABS(IPRNT).LT.4) GO TO 100	WR04 160
	WRITE (6,160) II	WR04 161
	WRITE (6,120) NBODY	WR04 162
	WRITE (6,150) (UB(J),J=1,NBODY)	WR04 163
	WRITE (6,130) NBODY	WR04 164
	WRITE (6,150) (AN(J),J=1,NBODY)	WR04 165
	IF (NBODY.LE.NMAX.OR.NPART.NE.1) GO TO 100	WR04 166
	WRITE (6,140) NS	WR04 167
	WRITE (6,150) (DN(J),J=1,NS)	WR04 168
100	WRITE (5) (UB(J),VR(J),WR(J),J=1,NBODY)	WR04 169
	WRITE (9) (AN(J),J=1,NBODY)	WR04 170
110	CONTINUE	WR04 171
	RETURN	WR04 172
120	FORMAT (2X,10HUB(J),J=1,,I4)	WR04 173
130	FORMAT (2X,10HAN(J),J=1,,I3)	WR04 174
140	FORMAT (2X,10HDN(J),J=1,,I3)	WR04 175
150	FORMAT (1X,10F10,5)	WR04 176
160	FORMAT (1H0,22HAERODYNAMIC MATRIX, I=,I3)	WR04 177
	END	WR04 178

	SUBROUTINE CDUMP(IPRNT,ROUTIN)	WR05 1
C		WR05 2
C	ROUTINE TO PRINT LABELED COMMON BLOCK DATA BY REQUEST.	WR05 3
C	INFORMATION TO BE PRINTED IS DETERMINED BY PRINT OPTION IPRNT.	WR05 4
C		WR05 5
C	PRINT CONTROL	WR05 6
C	IPRNT = 0 = PRINT ROUTINE NAME ONLY	WR05 7
C	= 1, PRINTS VARIABLES AND ALWAYS LESS THAN 11 IN LENGTH	WR05 8
C	FOR COMMON BLOCKS; JUPINS, PARAM, NEWCOM, VELCOM, + SEG	WR05 9
C	= 2, PRINTS ALL OF ABOVE COMMON BLOCKS	WR05 10
C	= 3, PRINT ARRAY BLOCK	WR05 11
C	= 4, PRINT VARIABLE = ARRAY	WR05 12
C	= 5, PRINTS COMMON: COMPS	WR05 13
C	= 6, PRINTS COMMON: TRAN	WR05 14
C	= 7, PRINTS COMMON: BTHET	WR05 15
C	= 8, PRINTS COMMON: COEF, MATCOM, + ITERAT	WR05 16
C	ROUTIN = HOLLERITH VARIABLE WITH NAME OF CALLING PROGRAM	WR05 17
C	SPECIFIED AS 8H-----.	WR05 18
C		WR05 19

```

C   DIMENSION ROUTIN(2)                                #R05 20
C                                                       #R05 21
COMMON /JOPTNS/ IZ1(8)                                #R05 22
1   ,J0,J1,J2,J3,J4,J5,J6,KKAF,KWAFOR,NFUS,NRADX(4),NFORX(4) #R05 23
2   ,NP,NPDDOR,NF,NFINOR,NCAN,NCANOR,J2TEST,NW,IZ2(25)   #R05 24
3   ,NVLIN,NCPDUT,XSTART,XALE,NACPT,IPLUT(4),IPRT(5),IXZSYM #R05 25
COMMON /PARAM / NHODY,NWING,NTAIL,LBC,THK,XMACH,ALPHA,BETA,ALPHAC #R05 26
1   ,PHIR,REFA,REFB,REFC,REFD,REFL,REFX,REFZ           #R05 27
COMMON /HEAD / TITLE1(2),TITLE2(2)                   #R05 28
COMMON /SEG / NSFG,NRNU(20),NCOIL(20),COSS(20),SINS(20) #R05 29
1   ,RTE(20),NWT(20),SPN(20),XLEN(20),BLE(20),ZLEN(20),ZB(60) #R05 30
COMMON /BLOCK(7500)                                    #R05 31
COMMON /PRINT / ARRAY(5000)                            #R05 32
COMMON /NEACOM/ K1,KKAF,KWAFOR,KWADY(4),KFORX(4),KFUS,MAX,K4,K5 #R05 33
1   ,KF(6),KAN(6),KFINOR(6),KANOR(6),KOL,NCPT,IICPT(20),XCPT(20) #R05 34
COMMON /VELCOM/ NPOINT,NPART,IMAX,JMAX,NMAX,EM,IPRINT,NWTHK #R05 35
1   ,NBLOK,NRNU(20),NBLOK,NHRU(60)                     #R05 36
COMMON /COMPS / TCOMPS(11)                             #R05 37
COMMON /TRAN / TTRAN(12)                                #R05 38
COMMON /THET / THET(600)                                #R05 39
COMMON /MATCHM/ MATIN                                    #R05 40
COMMON /CODEF / TCODEF(400)                             #R05 41
COMMON /ITERAT/ ITMAX,CCTEST                            #R05 42
C                                                       #R05 43
IF (IPRINT.EQ.0) RETURN                                 #R05 44
IF (IPRINT.GE.0) WRITE(A,10) ROUTIN                   #R05 45
10  FORMAT(1H1,10X,31HCCOMMON BLOCK PRINT CALLED FROM ,A) #R05 46
C                                                       #R05 47
IF (IPRINT.EQ.1 .OR. IPRINT.EQ.2)                    #R05 48
*   WRITE(6,15) J0,J1,J2,J3,J4,J5,J6,KKAF,KWAFOR      #R05 49
*   ,NFUS,NRADX,NFORX,NP,NPDDOR,NF,NFINOR,NCAN,NCANOR #R05 50
*   ,J2TEST,N,NVLIN,NCPDUT,NACPT,IPLUT,IPRT,IXZSYM   #R05 51
*   ,NHODY,NWING,NTAIL,LBC,THK,XMACH,ALPHA,BETA,ALPHAC,PHIR #R05 52
*   ,REFA,REFB,REFC,REFD,REFL,REFX,REFZ,XSTART,XALE   #R05 53
IF (IPRINT.EQ.1 .OR. IPRINT.EQ.2)                    #R05 54
*   WRITE(6,16) K1,KKAF,KWAFOR,KWADY,KFORX,KFUS,MAX,K4 #R05 55
*   ,KF,K5,KAN,KFINOR,KANOR,KOL,NCPT                  #R05 56
*   ,NPOINT,NPART,IMAX,JMAX,NMAX,IPRINT,NWTHK,NBLOK,NRBLOK #R05 57
*   ,EM,NSFG                                           #R05 58
15  FORMAT(/5X,15HCCOMMON /JOPTNS/                    #R05 59
*   ,/49H J0 J1 J2 J3 J4 J5 J6,/717                    #R05 60
*   ,/49H KKAF KWAFOR NFUS NRADX (2) (3) (4),/717     #R05 61
*   ,/49H NP NPDDOR NF (5) (4) NP NPDDOR NF,/717      #R05 62
*   ,/49H NFINOR NCAN NCANOR J2TEST NP NVLIN NCPDUT,/717 #R05 63
*   ,/49H NACPT IPLUT (2) (3) (4) IPRT (2),/717      #R05 64
*   ,/28H (5) (4) (5) IXZSYM,/417,                    #R05 65
*   ,/5X,15HCCOMMON /PARAM /                          #R05 66
*   ,/35H NHODY NWING NTAIL LBC THK,/317,2L7         #R05 67
*   ,/3X,5HXMACH,1X,5HALPHA,3X,4HRETA,6X,6HALPHAC,3X,4HPHIR,/5G12.5 #R05 68
*   ,/5X,4HREFA,3X,4HREFB,3X,4HREFC,3X,4HREFD,3X,4HREFL,/5G12.5 #R05 69
*   ,/5X,4HREFX,3X,4HREFZ,3X,6HXSTART,3X,4HXALE,/4G12.5) #R05 70
16  FORMAT(/5X,15HCCOMMON /NEACOM/                    #R05 71
*   ,/49H K1 KKAF KWAFOR KWADY (2) (3) (4),/717      #R05 72
*   ,/49H KFORX (2) (3) (4) KFUS MAX K4,/717         #R05 73
*   ,/49H KF (2) (3) (4) (5) (6) K5,/717            #R05 74
*   ,/7H KAN,/617                                       #R05 75
*   ,/7H KFINOR,/617                                    #R05 76
*   ,/7H KANOR,/617                                    #R05 77
*   ,/14H KOL NCPT,/217                                  #R05 78
*   ,/5X,15HCCOMMON /VELCOM/                          #R05 79
*   ,/49H NPOINT NPART IMAX JMAX NMAX IPRINT NWTHK,/717 #R05 80
*   ,/21H NBLOK NRNU EM,/217,612.5                    #R05 81
*   ,/5X,15HCCOMMON /SEG /                            #R05 82

```

```

* ,77H NSEG,7(17)
C
IF (IPRNT,EG,2) WRITE(6,20) IZ2
IF (IPRNT,EG,2) WRITE(6,21) NBROW,NCOL,COSS,SINS,BTE,NAT,SPNW,XLEW
* ,HLE,ZLEA
IF (IPRNT,EG,2) WRITE(6,22) LDCPT,XCPT
IF (IPRNT,EG,2) WRITE(6,23) NBROW,NBROW
20 FORMAT(/5X,6HARRAYS,7H IZ2,2(/10I5))
21 FORMAT(7H NBROW,2(/10I5))
* ,77H NCOL,2(/10I5)
* ,77H COSS,2(/10G12,5)
* ,77H SINS,2(/10G12,5)
* ,77H BTE,2(/10G12,5)
* ,77H NAT,2(/10I5)
* ,77H SPNW,2(/10G12,5)
* ,77H XLEA,2(/10G12,5)
* ,77H HLE,2(/10G12,5)
* ,77H ZLEA,2(/10G12,5)
22 FORMAT(7H LDCPT,2(/10I5))
* ,77H XCPT,2(/10G12,5))
23 FORMAT(7H NBROW,6(/10I5))
* ,77H NBROW,6(/10I5))
C
C IPRNT=3 = ARRAY BLOCK
C
IF (IPRNT,EG,3)
* CALL MEXIT(8H CDUMP ,1,,BLOCK,10,750,60,132,3,10,750)
C
C IPRNT=4, VARIABLE ARRAY
C
IF (IPRNT,EG,4)
* CALL MEXIT(8H CDUMP ,1,ARRAY,10,600,60,132,3,10,600)
C
C IPRNT=5, COMMON /COMPS/
IF (IPRNT,EG,5) WRITE(6,30) TCOMPS
30 FORMAT(/5X,15HCOMMON /COMPS /,2(/10G12,5))
C
C IPRNT=6, COMMON /TRAN /
IF (IPRNT,EG,6) WRITE(6,35) TTRAN
35 FORMAT(/5X,15HCOMMON /TRAN /,2(/10G12,5))
C
C IPRNT=7, COMMON /THET /
IF (IPRNT,EG,7) WRITE(6,40) THETI
40 FORMAT(/5X,15HCOMMON /THET /,60(/10G12,5))
C
C IPRNT=8, COMMON /COEF, /MATCOM, /ITERAT
IF (IPRNT,EG,8) WRITE(6,45) TCOEF, MATIN, ITMAX, CCTEST
45 FORMAT(/5X,15HCOMMON /COEF /,40(/10G12,5))
* ,//5X,15HCOMMON /MATCOM/,10X,7H MATIN, 15
* ,//5X,15HCOMMON /ITERAT/
* ,10X,7H ITMAX, 15,7H CCTEST,612,5)
RETURN
END

```

```

SUBROUTINE CPUTIME(T,DT,IT)
C
C ROUTINE TO COMPUTE ABSOLUTE AND RELATIVE CPUTIME DURING EXECUTION
C
C * * * * UNITS = SECONDS * * * *
C

```

```

C  USAGE:
C  (IT=0) TIME IS INITIALIZED BY FIRST CALL AS T=0, DT=0
C  CALL CPUTIM(T,DT,U)
C
C  (IT=1) COMPUTE ABSOLUTE AND INCREMENT IN CPU TIME FROM INITIAL
C  AND LAST CALL TO *CPUTIM*.
C  T = TOTAL SECONDS FROM INITIAL CALL TO *CPUTIM*
C  AS OUTPUT, T = TIME AT CURRENT CALL
C  DT = INCREMENT IN TIME (SECONDS)
C  DT = T(CUR)-T(PREV)
C
C  BY JOSEPH MULLEN, JR
C  OCTOBER, 1973
C
C  * * * * * CDC = VERSION * * * * *
C  IF (IT,LF,0) GO TO 100
C
C  COMPUTE NEW TIME AND INCREMENT
C  CALL SECOND(TIME)
C  TIME = TIME+T0
C  DT = TIME-TSAV
C  T = TIME
C  TSAV = TIME
C  RETURN
C
C  INITIALIZE CPU TIME
100 T = 0.0
C  DT = 0.0
C  TIME = 0.0
C  TSAV = 0.0
C  CALL SECOND(T0)
C  RETURN
C  END

```

```

WB06 6
WB06 7
WB06 8
WB06 9
WB06 10
WB06 11
WB06 12
WB06 13
WB06 14
WB06 15
WB06 16
WB06 17
WB06 18
WB06 19
WB06 20
WB06 21
WB06 22
WB06 23
WB06 24
WB06 25
WB06 26
WB06 27
WB06 28
WB06 29
WB06 30
WB06 31
WB06 32
WB06 33
WB06 34
WB06 35
WB06 36
WB06 37

```

```

C  SUBROUTINE COMCU(DA,DR,S,X,Y,M,N,NDA,NDR)
C
C  FIT A COMPOSITE CUBIC THROUGH N POINTS, I. E., A SEPARATE CUBIC
C  BETWEEN EACH PAIR OF ADJACENT POINTS, SUCH THAT N-1 CUBICS ARE SO
C  DETERMINED THAT EACH MATCHES ITS NEIGHBORS IN FUNCTION VALUE AND
C  IN THE FIRST AND SECOND DERIVATIVES.
C
C  COMMON/COMC/C(S0),D(S0),E(S0),Z1(250)
C  DIMENSION S(N),X(N),Y(N)
C  K=N-1
C  KUF=0
C
C  TEST FOR N LESS THAN 2
10 IF (N=2) GO TO 60
C  RETURN
C
C  TEST FOR N EQUAL TO 2
20 IF (NDA.NE.1,OR,NDR.NE.1) GO TO 50
C  S(1)=DA
C  S(2)=DR
C  M=0
C  RETURN
50 KUF=1
60 M=0
C  F(1)=0.
C  C(N)=0.
C  IF (NDA.GT.1) GO TO 80

```

```

WB07 1
WB07 2
WB07 3
WB07 4
WB07 5
WB07 6
WB07 7
WB07 8
WB07 9
WB07 10
WB07 11
WB07 12
WB07 13
WB07 14
WB07 15
WB07 16
WB07 17
WB07 18
WB07 19
WB07 20
WB07 21
WB07 22
WB07 23
WB07 24
WB07 25
WB07 26

```

	D(1)=1.	WR07	27
	C(1)=0.	WR07	28
	S(1)=0A	WR07	29
	GO TO 90	WR07	30
90	D(1)=4.	WR07	31
	C(1)=2.	WR07	32
	S(1)=6.*(Y(2)-Y(1))/(X(2)-X(1))-0A*(X(2)-X(1))	WR07	33
90	IF (X(2)-X(1),0) GO TO 120	WR07	34
	DO 110 I=2,N	WR07	35
	U=X(I)-X(I-1)	WR07	36
	V=X(I+1)-X(I)	WR07	37
	C(I)=U	WR07	38
	D(I)=2.*(U+V)	WR07	39
	F(I)=V	WR07	40
	S(I)=S(I)/(U+V)*(U+U*(Y(I+1)-Y(I))+V*V*(Y(I)-Y(I-1)))	WR07	41
110	CONTINUE	WR07	42
120	IF (NDH.GT.1) GO TO 140	WR07	43
	F(N)=0.	WR07	44
	D(N)=1.	WR07	45
	S(N)=0B	WR07	46
	GO TO 150	WR07	47
140	F(N)=2.	WR07	48
	D(N)=4.	WR07	49
	S(N)=6.*(Y(N)-Y(N-1))/(X(N)-X(N-1))+0P*(X(N)-X(N-1))	WR07	50
150	C(1)=C(1)/D(1)	WR07	51
	S(1)=S(1)/D(1)	WR07	52
	DO 160 I=2,N	WR07	53
	F=C(I)-C(I-1)*E(I)	WR07	54
	C(I)=C(I)/F	WR07	55
	S(I)=(S(I)-S(I-1)*E(I))/F	WR07	56
160	CONTINUE	WR07	57
	DO 170 J=1,K	WR07	58
	I=N-J	WR07	59
	S(I)=S(I)-S(I+1)*C(I)	WR07	60
170	CONTINUE	WR07	61
	RETURN	WR07	62
	END	WR07	63

	SUBROUTINE CONFIG	WR08	1
C		WR08	2
C	INPUT AND INITIALIZE CONFIGURATION DESCRIPTION	WR08	3
C		WR08	4
	COMMON /JOPTNS/ IZ1(8)	WR08	5
	1 , J0,J1,J2,J3,J4,J5,J6,NWAF,NWAFIR,NFUS,NRADX(4),NFORX(4)	WR08	6
	2 , NP,NPDIR,NF,NFINOR,NCAN,NCANOR,J2TEST,NW	WR08	7
	3 , IZ(34),IPRT(5),IXZSYM	WR08	8
	COMMON /PARAM / ABODY,NWING,NTAIL,LNC,THK,XMACH,ALPHA,BETA,ALPHAC	WR08	9
	1 , DWIP,REFA,REFB,REFC,REFD,REFL,REFX,REFZ	WR08	10
	COMMON BLOCK(7500)	WR08	11
C		WR08	12
C	GEOMETRY ARRAYS	WR08	13
C		WR08	14
	WING	WR08	15
	DIMENSION ABCD(8)	WR08	16
	1 , XAF(30) , XFUS(30,4) , FINORG(6,2,4) , CANORG(6,2,4)	WR08	17
	2 , WAFORG(20,4) , ZFUS(30,4) , XFIN(6,10) , XCAN(6,10)	WR08	18
	3 , WAFORD(20,3,40) , FUSAKD(30,4) , FINORD(6,2,10) , CANORD(6,2,10)	WR08	19
	4 , FZORD(20,30) , FUSAD(30,4) , FINX2(6,2,10) , CANDRI(6,2,10)	WR08	20
	5 , WAFOR(20,30) , FUS(30,30,8) , FINX3(6,2,10) , CANDRX(6,2,10)	WR08	21
	6 , FUSBY(30,4) , FINOR(6,10) , CANOR(6,10)	WR08	21

```

7 , FUSAZ(30,4) , FINCR(6,10) , CANCR(5,10) *R0A 22
C *R0A 23
C *R0A 24
C *R0A 25
EQUIVALENCE
1 ( XAF(1) ,BLOCK(1)) ( XFUS(1,1) ,BLOCK(1)) *R0A 26
2 ( XAFORG(1,1) ,BLOCK(51)) ( ZFUS(1,1) ,BLOCK(121)) *R0A 27
3 ( XAFORG(1,1,1) ,BLOCK(111)) ( FUSARG(1,1) ,BLOCK(241)) *R0A 28
4 ( TZORD(1,1) ,BLOCK(191)) ( FUSRAD(1,1) ,BLOCK(361)) *R0A 29
5 ( XAFOR(1,1) ,BLOCK(251)) ( SFUS(1,1,1) ,BLOCK(241)) *R0A 30
6 ( FUSRY(1,1) ,BLOCK(361)) *R0A 31
7 ( FUSAZ(1,1) ,BLOCK(481)) *R0A 32
C *R0A 33
EQUIVALENCE
V,FIN H,TAIL
6 ( FINORG(1,1,1) ,BLOCK(1)) ( CANORG(1,1,1) ,BLOCK(1)) *R0A 35
7 ( XFIN(1,1) ,BLOCK(49)) ( XCAN(1,1) ,BLOCK(49)) *R0A 36
8 ( FINORG(1,1,1) ,BLOCK(199)) ( CANORG(1,1,1) ,BLOCK(199)) *R0A 37
9 ( FINX2(1,1,1) ,BLOCK(229)) ( CANORI(1,1,1) ,BLOCK(229)) *R0A 38
10 ( FINX3(1,1,1) ,BLOCK(349)) ( CANORY(1,1,1) ,BLOCK(349)) *R0A 39
1 ( FINOR(1,1) ,BLOCK(469)) ( CANOR(1,1) ,BLOCK(469)) *R0A 40
2 ( FINCR(1,1) ,BLOCK(529)) ( CANCR(1,1) ,BLOCK(529)) *R0A 41
C *R0A 42
LOGICAL LPRT,HEADR,HEADR,HEADR *R0A 43
DATA PT/3,14159265/ *R0A 44
REWIND 9 *R0A 45
LPRT=IPRT(1),GT,0 *R0A 46
C *R0A 47
C REFERENCE AREA *R0A 48
C *R0A 49
REFA=1 *R0A 50
IF (J0,NE,0) READ (5,480) REFA *R0A 51
WRITE (9) REFA *R0A 52
IF (LPRT) WRITE(6,490) REFA *R0A 53
C *R0A 54
C *R0A 55
C *R0A 56
IF (J1,EQ,0) GO TO 160 *R0A 57
IF (LPRT) WRITE(6,500) *R0A 58
NBIANS(XAFOR) *R0A 59
NREC=(N+9)/10 *R0A 60
I1=9 *R0A 61
I2=0 *R0A 62
DO 20 N=1, NREC *R0A 63
I1=I1+10 *R0A 64
I2=I2+10 *R0A 65
READ (5,480) (XAF(I),I=I1,I2) *R0A 66
IF (LPRT) WRITE(6,510) N,(XAF(I),I=I1,I2) *R0A 67
CONTINUE *R0A 68
C *R0A 69
IF (LPRT) WRITE(6,520) *R0A 70
DO 30 I=1, N*AF *R0A 71
READ (5,480) (XAFORG(I,J),J=1,4) *R0A 72
IF (LPRT) WRITE(6,510) I,(XAFORG(I,J),J=1,4) *R0A 73
CONTINUE *R0A 74
30 *R0A 75
C *R0A 76
C *R0A 77
C *R0A 78
IF (J1,LT,0) GO TO 60 *R0A 79
IF (LPRT) WRITE(6,540) *R0A 79
DO 50 N=1, N*AF *R0A 80
I1=9 *R0A 81
I2=0 *R0A 82
DO 40 M=1, NREC *R0A 83
C *R0A 84

```

	I1=I1+10	WR08 85
	I2=I2+10	WR08 86
	READ (5,480) (TZORD(NN,I),I=I1,I2)	WR08 87
	DO 40 I=I1,I2	WR08 88
	IF (N*AFORG(NN,4).EQ.0.) GO TO 40	WR08 89
	TZORD(NN,I)=TZORD(NN,I)+100./N*AFORG(NN,4)	WR08 90
40	CONTINUE	WR08 91
	IF (LPRT) WRITE(6,510) NN,(TZORD(NN,I),I=I1,I2)	WR08 92
50	CONTINUE	WR08 93
	GO TO 80	WR08 94
60	DO 70 I=1,N*AF	WR08 95
	DO 70 K=1,I	WR08 96
	TZORD(I,K)=0.	WR08 97
70	CONTINUE	WR08 98
80	L=1	WR08 99
C		WR08 100
C	N*AFOR POSITIVE INDICATES SYMMETRICAL ORDINATES	WR08 101
C	NEGATIVE INDICATES UPPER AND LOWER ORDINATES GIVEN	WR08 102
	IF (N*AFOR.LT.0) L=2	WR08 103
	IF (LPRT) WRITE(6,550)	WR08 104
	DO 100 NN=1,N*AF	WR08 105
	DO 100 K=1,L	WR08 106
	I1=-9	WR08 107
	I2=0	WR08 108
	DO 90 N1=1,N*REC	WR08 109
	I1=I1+10	WR08 110
	I2=I2+10	WR08 111
	READ (5,480) (N*AFORD(NN,K,I),I=I1,I2)	WR08 112
	IF (LPRT) WRITE(6,510) NN,(N*AFORD(NN,K,I),I=I1,I2)	WR08 113
90	CONTINUE	WR08 114
100	CONTINUE	WR08 115
	DO 110 NN=1,N*AF	WR08 116
	DO 110 K=1,N	WR08 117
	N*AFOR(NN,K)=N*AFORD(NN,1,K)	WR08 118
	IF (L.EQ.1) GO TO 110	WR08 119
	N*AFOR(NN,K)=(N*AFORD(NN,1,K)+N*AFORD(NN,2,K))/2.	WR08 120
	TZORD(NN,K)=(N*AFORD(NN,1,K)-N*AFORD(NN,2,K))/2.+TZORD(NN,K)	WR08 121
110	CONTINUE	WR08 122
	IF (N*AFOR.LT.0) GO TO 130	WR08 123
	DO 120 NN=1,N*AF	WR08 124
	DO 120 K=1,N	WR08 125
	N*AFOR(NN,2,K)=N*AFORD(NN,1,K)	WR08 126
120	CONTINUE	WR08 127
130	N*AFOR=IABS(N*AFOR)	WR08 128
	NN=N*AFOR	WR08 129
	J1=IABS(J1)	WR08 130
C		WR08 131
C	CHANGE WING TO ACTUAL UNITS	WR08 132
C		WR08 133
	DO 150 I=1,N*AF	WR08 134
	E=0.01*N*AFORG(I,4)	WR08 135
	E3=N*AFORG(I,3)	WR08 136
	DO 140 J=1,N*AFOR	WR08 137
	N*AFORD(I,1,J)=E+N*AFORD(I,1,J)+E3+TZORD(I,J)*E	WR08 138
	N*AFORD(I,2,J)=-E+N*AFORD(I,2,J)+E3+TZORD(I,J)*E	WR08 139
	N*AFORD(I,3,J)=N*AFORG(I,1)+L*N*AF(J)	WR08 140
140	CONTINUE	WR08 141
150	CONTINUE	WR08 142
C	WRITE (9) BLUCK	WR08 143
150	CONTINUE	WR08 144
	N=IABS(N*AFOR)	WR08 145
C		WR08 146
C	FUSELAGE (BODY) -----	WR08 147

```

C
IF (J2.EQ.0) GO TO 290
J2TEST=3
C
C J2 < 0 AND J6 = -1 INDICATE CIRCULAR/ELLIPTIC FUSELAGE SYMMETRICAL
C WITH THE XY-PLANE
C
C J2 < 0 AND J6 = 0 INDICATE CIRCULAR/ELLIPTIC CAMBERED FUSELAGE
C
C J6 = 1 INDICATES COMPLETE CONFIGURATION SYMMETRICAL WITH THE
C XY-PLANE
C
C J2 = -1, READ FUSELAGE CROSS SECTIONAL AREAS VS XFUS ON INPUT
C
C J2 = -2, READ FUSELAGE RADII VS XFUS ON INPUT
C
C J2 = -3, READ ELLIPTIC FUSELAGE SEMI-MAJOR AXES VS XFUS
C
IF (J2.LE.-1.AND.J6.EQ.-1) J2TEST=1
IF (J2.LE.-1.AND.J6.EQ.0) J2TEST=2
IF (J6.EQ.1) J2TEST=1
READA=J2.EQ.-1
READR=J2.EQ.-2
READS=J2.EQ.-3
J2=1
C
C READ XFUS
C
IF (LPRT) WRITE(6,570)
DO 290 N=1,NFUS
NRAD=NRAD*(NFU)
NFUSOR=NFOR*(NFU)
N=NFUSOR
NREC=(N+9)/10
I1=-9
I2=0
DO 170 M=1,NREC
I1=I1+10
I2=I2+10
READ (5,480) (XFUS(I,NFU),I=I1,I2)
IF (LPRT) WRITE(6,510) NFU,(XFUS(I,NFU),I=I1,I2)
170 CONTINUE
C
C J2TEST = 2 INDICATES CIRCULAR/ELLIPTIC CAMBERED FUSELAGE
C
IF (J2TEST.EQ.2) GO TO 190
I1=-9
I2=0
IF (LPRT) WRITE(6,580)
DO 180 M=1,NREC
I1=I1+10
I2=I2+10
READ (5,480) (ZFUS(I,NFU),I=I1,I2)
IF (LPRT) WRITE(6,510) NFU,(ZFUS(I,NFU),I=I1,I2)
180 CONTINUE
GO TO 210
190 DO 200 I=1,NFUSOR
ZFUS(I,NFU)=0.
200 CONTINUE
C
C J2TEST = 3 INDICATES ARBITRARY FUSELAGE - READ YJ + ZJ OF SECTION
C
210 IF (J2TEST.EQ.3) GO TO 250
NCRD=(NCRD+9)/10
DO 240 K=1,NFUSOR
DO 230 K=1,2
IF (LPRT.AND.K.EQ.1) WRITE(6,590)
IF (LPRT.AND.K.EQ.2) WRITE(6,600)
KK=K+(NFU-1)*2

```


	I1=10	*R08 211
	I1=-9	*R08 212
	I2=0	*R08 213
	DO 220 NN=1,NCARD	*R08 214
	IF (NN.EQ.NCARD) I1=MOD(NRAD,10)	*R08 215
	IF (I1.EQ.0) I1=10	*R08 216
	I1=I1+10	*R08 217
	I2=I2+I1	*R08 218
	HEAD (5,480) (SFUS(I,JX,KK),I=11,I2)	*R08 219
	IF (LPRT) WRITE(6,510) JX,(SFUS(I,JX,KK),I=11,I2)	*R08 220
220	CONTINUE	*R08 221
230	CONTINUE	*R08 222
240	CONTINUE	*R08 223
	GO TO 280	*R08 224
C		*R08 225
C	CIRCULAR/ELLIPTIC FUSELAGE - READ CROSS SECTIONAL AREAS/RADII	*R08 226
C		*R08 227
250	CONTINUE	*R08 228
	IF (LPRT.AND.HEADA) WRITE(6,610)	*R08 229
	IF (LPRT.AND.HEADR) WRITE(6,615)	*R08 230
	IF (LPRT.AND.HEADL) WRITE(6,680)	*R08 231
	DO 255 I=1,NFUSOR	*R08 232
255	FUSAZ(I,NFU)=0.0	*R08 233
	I1=-9	*R08 234
	I2=0	*R08 235
	DO 260 NI=1,NREC	*R08 236
	I1=I1+10	*R08 237
	I2=I2+10	*R08 238
	IF (READA) READ (5,480) (FUSARD(I,NFU),I=11,I2)	*R08 239
	IF (READR) READ (5,480) (FUSRAD(I,NFU),I=11,I2)	*R08 240
	IF (READL) READ (5,480) (FUSBY(I,NFU),I=11,I2)	*R08 241
	IF (LPRT.AND.READA) WRITE(6,510) NFU,(FUSARD(I,NFU),I=11,I2)	*R08 242
	IF (LPRT.AND.READR) WRITE(6,510) NFU,(FUSRAD(I,NFU),I=11,I2)	*R08 243
	IF (LPRT.AND.READL) WRITE(6,510) NFU,(FUSBY(I,NFU),I=11,I2)	*R08 244
260	CONTINUE	*R08 245
C		*R08 246
	IF (.NOT.READL) GO TO 268	*R08 247
	WRITE(6,690)	*R08 248
	DO 264 I1=1,NFUSOR,10	*R08 249
	I2=I1+9	*R08 250
	READ(5,480) (FUSAZ(I,NFU),I=11,I2)	*R08 251
	IF (LPRT) WRITE(6,510) NFU,(FUSAZ(I,NFU),I=11,I2)	*R08 252
264	CONTINUE	*R08 253
268	CONTINUE	*R08 254
	DO 270 I=1,NFUSOR	*R08 255
	IF (READA) FUSRAD(I,NFU)=SQRT(FUSARD(I,NFU)/PI)	*R08 256
	IF (READR) FUSARD(I,NFU)=PI*FUSRAD(I,NFU)**2	*R08 257
	IF (FUSAZ(I,NFU).LE.0.) FUSAZ(I,NFU)=FUSBY(I,NFU)	*R08 258
270	CONTINUE	*R08 259
280	CONTINUE	*R08 260
CR	WRITE (9) PLOCK	*R08 261
290	CONTINUE	*R08 262
C		*R08 263
C	POD GEOMETRY JUMPY READ STATEMENTS -----	*R08 264
C		*R08 265
	IF (J3.EQ.0) GO TO 330	*R08 266
	NONPODOR	*R08 267
	NREC=(N+9)/10	*R08 268
	DO 320 NN=1,NP	*R08 269
	READ (5,470) ARCD	*R08 270
	DO 300 NI=1,NREC	*R08 271
	READ (5,470) ARCD	*R08 272
300	CONTINUE	*R08 273

	DO 310 M=1,NREC	WR08 274
	READ (5,470) ABCD	WR08 275
310	CONTINUE	WR08 276
320	CONTINUE	WR08 277
C		WR08 278
C	FINS (VERTICAL TAILS) -----	WR08 279
C		WR08 280
330	IF (J4.EQ.0) GO TO 380	WR08 281
	N=FINOR	WR08 282
	DO 350 NN=1,NF	WR08 283
	READ (5,480) ((FINORG(NN,I,J),J=1,4),I=1,2)	WR08 284
	IF (LPRT) WRITE(6,620) NN,((FINORG(NN,I,J),J=1,4),I=1,2)	WR08 285
	READ (5,480) (XFIN(NN,I),I=1,N)	WR08 286
	IF (LPRT) WRITE(6,630) (XFIN(NN,I),I=1,N)	WR08 287
	READ (5,480) (FINORD(NN,1,J),J=1,N)	WR08 288
	IF (LPRT) WRITE(6,640) (FINORD(NN,1,J),J=1,N)	WR08 289
	DO 340 J=1,N	WR08 290
	FINC(R(NN,J))=0.	WR08 291
	FINDR(NN,J)=FINORD(NN,1,J)	WR08 292
340	CONTINUE	WR08 293
350	CONTINUE	WR08 294
C		WR08 295
C	CHANGE FINS TO ACTUAL UNITS	WR08 296
C		WR08 297
	DO 370 LQ=1,NF	WR08 298
	DO 370 I=1,2	WR08 299
	J=3-I	WR08 300
	E=01*FINORG(LQ,J,4)	WR08 301
	E2=FINORG(LQ,J,2)	WR08 302
	DO 360 K=1,NFINOR	WR08 303
	EE=FINORD(LQ,1,K)*E	WR08 304
	FINDR(LQ,J,K)=E2+EE	WR08 305
	FINDX2(LQ,J,K)=E2-EE	WR08 306
	FINDX3(LQ,J,K)=FINORG(LQ,J,1)+E*XFIN(LQ,K)	WR08 307
360	CONTINUE	WR08 308
370	CONTINUE	WR08 309
CR	WRITE (9) BLOCK	WR08 310
380	CONTINUE	WR08 311
C		WR08 312
C	CANARDS (HORIZONTAL TAILS) -----	WR08 313
C		WR08 314
	IF (J5.EQ.0) GO TO 460	WR08 315
	N=CANR	WR08 316
	DO 420 NN=1,NCAN	WR08 317
	READ (5,480) ((CANORG(NN,I,J),J=1,4),I=1,2)	WR08 318
	IF (LPRT) WRITE(6,510) NN,((CANORG(NN,I,J),J=1,4),I=1,2)	WR08 319
	READ (5,480) (XCAN(NN,I),I=1,N)	WR08 320
	IF (LPRT) WRITE(6,650) (XCAN(NN,I),I=1,N)	WR08 321
	READ (5,480) (CANORD(NN,1,J),J=1,N)	WR08 322
	IF (LPRT) WRITE(6,670) (CANORD(NN,1,J),J=1,N)	WR08 323
C		WR08 324
C	CANOR POSITIVE INDICATES SYMMETRICAL ORDINATES	WR08 325
C	CANOR NEGATIVE INDICATES UPPER AND LOWER ORDINATES ARE GIVEN	WR08 326
C		WR08 327
	IF (NCANR,LT,0) GO TO 400	WR08 328
	DO 390 J=1,N	WR08 329
	CANR(NN,J)=0.	WR08 330
	CANOR(NN,J)=CANORD(NN,1,J)	WR08 331
	CANOR1(NN,1,J)=CANORD(NN,1,J)	WR08 332
390	CONTINUE	WR08 333
	GO TO 420	WR08 334
400	CONTINUE	WR08 335
	READ (5,480) (CANOR1(NN,1,J),J=1,N)	WR08 336

```

IF (LPRT) WRITE(6,670) (CANORD(NN,1,J),J=1,N)
DO 410 J=1,N
CANOR(NN,J)=(CANORD(NN,1,J)+CANORI(NN,1,J))/2.
CANCR(NN,J)=(CANORD(NN,1,J)-CANORI(NN,1,J))/2.
410 CONTINUE
420 CONTINUE
C
C CHANGE CANARD TO ACTUAL UNITS
C
DO 450 NN=1,NCAN
DO 440 K=1,2
I=3-K
E=.01*CANDRG(NN,I,4)
E3=CANDRG(NN,I,5)
DO 430 J=1,N
CANORD(NN,I,J)=E*CANDRD(NN,1,J)+E3
CANORI(NN,I,J)=-E*CANDRI(NN,1,J)+E3
CANORX(NN,I,J)=CANORG(NN,I,1)+E*XCAN(NN,J)
430 CONTINUE
440 CONTINUE
450 CONTINUE
CH WRITE(9) BLOCK
460 CONTINUE
REWIND 9
RETURN
C
470 FORMAT(8A10)
480 FORMAT(10F7.0)
490 FORMAT(///10X,26HVEHICLE GEOMETRY DEFINITION,74X,12H** CONFIG **
* /5X,53HREFERENCE AREA (J0,GT,0) REFA=.613,6)
500 FORMAT(/5X,45H XAF = WING ORDINATES FOR AIRFOIL (: CHORD)
* /10X(J1,NE,0))
510 FORMAT(15,10F10.4)
520 FORMAT(/5X,42HWAFORG = WING AIRFOIL LEADING EDGE + CHORD
* /4X,1H1,7X,1HX,9X,1HY,9X,1HZ,5X,5HCHORD)
540 FORMAT(/5X,30H TZORD = WING CAMBER, Z VS XAF)
550 FORMAT(/5X,45HWAFORD = WING AIRFOIL ORDINATE (+SYM,=UP/LOW)
* /9H NKAFOR=,15)
570 FORMAT(/5H NFU,5X,26HXFUS = FUSELAGE X-STATIONS)
580 FORMAT(/5H NFU,5X,37HZFUS = FUSELAGE Z-CAMBER VS XFUS FOR
* /16HCIRCULAR SECTION)
590 FORMAT(/5H JX,5X,42HY = COORDINATE ARBITRARY FUSELAGE SECTION
1 /6H(SFUS))
600 FORMAT(/5H JX,5X,42HZ = COORDINATE ARBITRARY FUSELAGE SECTION
1 /6H(SFUS))
610 FORMAT(/5X,45HFUSAR0 = CIRCULAR FUSELAGE CROSS SECTION AREA)
615 FORMAT(/5X,42HFUSRAD = CIRCULAR FUSELAGE RADIUS)
620 FORMAT(/5X,38HFINDRG = VERTICAL FIN AIRFOIL ORIGIN#
* /5X,4HFIN SEG=,13,/10X,1HX,9X,1HY,9X,1HZ,5X,5HCHORD
* /5H IN /4F10.3,5H OUT,4F10.3)
630 FORMAT(/5X,40H XFIN = X-STATION FIN AIRFOIL (: CHORD),/10F10.4)
640 FORMAT(/5X,40HFINDRD = AIRFOIL ORDINATES VS XFIN (SYM),/10F10.4)
650 FORMAT(/5X,41HCANORG = HORIZONTAL TAIL AIRFOIL ORIGIN#
* /5X,9HTAIL SEG=,13,/10X,1HX,9X,1HY,9X,1HZ,5X,5HCHORD
* /5H IN /4F10.3,5H OUT,4F10.3)
650 FORMAT(/5X,41H XCAN = X-STATION TAIL AIRFOIL (: CHORD),/10F10.4)
670 FORMAT(/5X,41HCANDRD = AIRFOIL ORDINATES VS XCAN (SYM),/10F10.4)
680 FORMAT(/5H NFU,5X,41HFUSRY = ELLIPTIC FUSELAGE SEMI-MAJOR AXES)
690 FORMAT(/5H NFU,5X,41HFUSAZ = ELLIPTIC FUSELAGE SEMI-MINOR AXES)
END

```

```

WR08 337
WR08 338
WR08 339
WR08 340
WR08 341
WR08 342
WR08 343
WR08 344
WR08 345
WR08 346
WR08 347
WR08 348
WR08 349
WR08 350
WR08 351
WR08 352
WR08 353
WR08 354
WR08 355
WR08 356
WR08 357
WR08 358
WR08 359
WR08 360
WR08 361
WR08 362
WR08 363
WR08 364
WR08 365
WR08 366
WR08 367
WR08 368
WR08 369
WR08 370
WR08 371
WR08 372
WR08 373
WR08 374
WR08 375
WR08 376
WR08 377
WR08 378
WR08 379
WR08 380
WR08 381
WR08 382
WR08 383
WR08 384
WR08 385
WR08 386
WR08 387
WR08 388
WR08 389
WR08 390
WR08 391
WR08 392
WR08 393
WR08 394
WR08 395
WR08 396

```

	SUBROUTINE CUBIC2(X,Y,D,C,J)	WR09	1
C		WR09	2
C	FIT A CURIC TO TWO POINTS GIVEN THE SLOPE AT EACH POINT	WR09	3
C		WR09	4
	DIMENSION X(2),Y(2),D(2),C(4)	WR09	5
	X2=X(2)	WR09	6
	H=X(1)-X2	WR09	7
	IF (H.NE.,0.) GO TO 20	WR09	8
10	J=3	WR09	9
	RETURN	WR09	10
20	A=(Y(1)-Y(2))/H	WR09	11
	E=X(1)+X2	WR09	12
	C(4)=(D(1)+D(2)-A-A)/H/B	WR09	13
	C(3)=(A-D(2))/H-C(4)*(E+X2)	WR09	14
	C(2)=A-E+C(3)-C(4)*(E*X2+X(1)**2)	WR09	15
	C(1)=Y(2)-X2*(C(2)+X2*(C(3)+X2*C(4)))	WR09	16
	J=1	WR09	17
	RETURN	WR09	18
	END	WR09	19

	COMPLEX FUNCTION DBLU(Z)	WR10	1
C		WR10	2
C	THIS FUNCTION SUBROUTINE CALCULATES THE INTERMEDIATE TRANSFORM	WR10	3
C	VARIABLE W FOR THE CONFORMAL TRANSFORMATION OF AN ELLIPTICAL	WR10	4
C	BODY WITH WINGS	WR10	5
C		WR10	6
	COMMON/COM1/A2,B2,R2	WR10	7
	COMMON/COM2/ZR,ZI	WR10	8
	COMMON/COM3/D*DLZ	WR10	9
	COMMON/COM4/W2,W	WR10	10
C		WR10	11
C	COMPLEX Z,Z2,D*DLZ,W,W2,W	WR10	12
		WR10	13
	Z2=Z*Z	WR10	14
	ZR=REAL(Z)	WR10	15
	ZI=AIMAG(Z)	WR10	16
	IF (ZR.NE.,0.) ZR=ZR/ABS(ZR)	WR10	17
	IF (ZI.NE.,0.) ZI=ZI/ABS(ZI)	WR10	18
	Z2=Z2-A2+R2	WR10	19
	W=AIMAG(Z2)	WR10	20
	AY=1.0	WR10	21
	IF (Y.LT.,0.) AY=-1.0	WR10	22
	AYZ=1.0	WR10	23
	IF (ZI.LT.,0.) AYZ=-1.0	WR10	24
	Z2=CSQRT(Z2)*AY*AYZ	WR10	25
	IF ((ABS(ZI).LE.,0.) .AND. (REAL(Z).LT.,0.)) Z2=CMPLX(-REAL(Z2),	WR10	26
1	AIMAG(Z2))	WR10	27
	D*DLZ=0.5*(1.0+Z/Z2)	WR10	28
	W=0.5*(Z+Z2)	WR10	29
	W2=1.0/W/W	WR10	30
	DBLU=W	WR10	31
	RETURN	WR10	32
	END	WR10	33

	SUBROUTINE DERIV(X,Y,N,NDA,DA,FD)	WB11	1
C		WB11	2
C	FIT A CHAIN OF CUBIC CURVES THROUGH A SET OF N POINTS HAVING	WB11	3
C	CONTINUOUS FIRST AND SECOND DERIVATIVES AT THE INTERMEDIATE POINTS	WB11	4
C	AND SPECIFIED FIRST OR SECOND DERIVATIVE AT THE END POINTS	WB11	5
C		WB11	6
	COMMON/COEFF/C(4,50),Z1(200)	WB11	7
	DIMENSION X(1),Y(1),FD(1)	WB11	8
	CALL SCAMP4(X,Y,N,NDA,-1,DA,0.,C,FD,0)	WB11	9
	RETURN	WB11	10
	END	WB11	11

	FUNCTION DERIV1(X1,Y1,N)	WB12	1
C		WB12	2
C	FIND THE FIRST DERIVATIVE OF THE QUADRATIC THROUGH THREE GIVEN	WB12	3
C	POINTS AT A SPECIFIED ONE OF THESE POINTS. THIS PROVIDES A GOOD	WB12	4
C	APPROXIMATION TO THE SLOPE OF A FUNCTION AT A POINT, PARTICULARLY	WB12	5
C	IF THE OTHER TWO POINTS USED ARE NEARBY.	WB12	6
C		WB12	7
	DIMENSION X(3),Y(3),X1(3),Y1(3)	WB12	8
	EQUIVALENCE (S,K)	WB12	9
	DO 10 J=1,3	WB12	10
	X(J)=X1(J)	WB12	11
	Y(J)=Y1(J)	WB12	12
10	CONTINUE	WB12	13
	K=N	WB12	14
	E=Y(1)-Y(2)	WB12	15
	H=Y(1)-Y(3)	WB12	16
	A=X(1)-X(2)	WB12	17
	B=X(1)-X(3)	WB12	18
	C=A*(X(1)+X(2))	WB12	19
	DT=B*(X(1)+X(3))	WB12	20
	C3=(H+E-A*B)/(H+C-A*DT)	WB12	21
	C2=(E-C3*A)/A	WB12	22
	K1=IABS(K)	WB12	23
	DO 20 I=1,3	WB12	24
	IF (K1,EQ,1) GO TO 30	WB12	25
20	CONTINUE	WB12	26
	GO TO 40	WB12	27
30	S=X(K1)	WB12	28
40	DERIV1=C2+2.*C3*S	WB12	29
	RETURN	WB12	30
	END	WB12	31

	FUNCTION DERIV2(X,Y,XX)	WB13	1
C		WB13	2
C	FIND THE SECOND DERIVATIVE OF THE CUBIC THROUGH FOUR GIVEN POINTS	WB13	3
C	AT AN ARBITRARY POINT WHOSE X COORDINATE IS SPECIFIED	WB13	4
C		WB13	5
	DIMENSION X(4),Y(4)	WB13	6
	DERIV2=0.	WB13	7
	IF (X(4),EQ,X(1)) RETURN	WB13	8
	IF (X(4),EQ,X(2)) RETURN	WB13	9
	IF (X(4),EQ,X(3)) RETURN	WB13	10
	IF (X(3),EQ,X(2)) RETURN	WB13	11

IF (X(3).EQ.X(1)) RETURN	*B13	12
IF (X(2).EQ.X(1)) RETURN	*B13	13
Q41=(Y(4)-Y(1))/(X(4)-X(1))	*B13	14
Q31=(Y(3)-Y(1))/(X(3)-X(1))	*B13	15
Q21=(Y(2)-Y(1))/(X(2)-X(1))	*B13	16
F=(Q31-Q21)/(X(3)-X(2))	*B13	17
D=((Q41-Q21)/(X(4)-X(2))-F)/(X(4)-X(3))	*B13	18
C=E-D*(X(3)+X(2)+X(1))	*B13	19
DERIV2=2.*(C+3.*D**X)	*B13	20
RETURN	*B13	21
END	*B13	22
	*B14	1
	*B14	2
C INVERT THE DIAGONAL BLOCKS OF THE MATRIX	*B14	3
C FOR MATRIX PARTITIONS X 50X60 INVERTED DIAGONALS ARE ON TAPE10.	*B14	4
C	*B14	5
COMMON /PARAM / NBODY, NRING, NTAIL, LHC, THK, XNACH, ALPHA, BETA, ALPHAC	*B14	6
1 , PHIR, REFA, REFB, REFC, REFD, REFL, REFX, REF7	*B14	7
COMMON /VELCOM/ NPOINT, NPART, IMAX, JMAX, NMAX, EM, IPRINT, NTHK	*B14	8
1 , NNBLOK, NNR0W(20), NBBLOK, NBR0W(60)	*B14	9
COMMON /POINT / O(60,60), Z4(2400)	*B14	10
C	*B14	11
CALL CPRTIM(TIME,DT,1)	*B14	12
REWIND 9	*B14	13
REWIND 10	*B14	14
NDIM=60	*B14	15
IF (NBODY.EQ.0) GO TO 50	*B14	16
C	*B14	17
C READ MATRICES AND INVERT DIAGONAL BLOCKS	*B14	18
C	*B14	19
DO 40 NH=1,NBBLOK	*B14	20
NR0W=NBROW(NH)	*B14	21
NCOL=NR0W	*B14	22
IF (NBODY.GT.NMAX) GO TO 20	*B14	23
C	*B14	24
IF (NBODY)61, USE ENTIRE MATRIX ON TAPE9	*B14	24
DO 10 J=1,NBODY	*B14	25
READ (9) (D(I,J),J=1,NBODY)	*B14	26
10	*B14	27
CONTINUE	*B14	27
GO TO 30	*B14	28
C	*B14	29
IF (NBODY)60, USE DIAGONAL BLOCKS ON TAPE7	*B14	29
20	*B14	30
READ (7) D	*B14	30
30	*B14	31
CALL INVERT(D,ACOL,NOTM)	*B14	31
WRITE (10) D	*B14	32
40	*B14	33
CONTINUE	*B14	33
C	*B14	34
C READ WING MATRICES AND INVERT DIAGONAL BLOCKS -----	*B14	35
C	*B14	36
50	*B14	37
CONTINUE	*B14	37
C4	*B14	38
IF (NRING.EQ.0) GO TO 140	*B14	38
C	*B14	39
IF (NRING)61, READ PAST WING/BODY MATRICES AND USE ENTIRE MATRIX	*B14	39
C4130	*B14	40
CONTINUE	*B14	40
140	*B14	41
REWIND 10	*B14	41
REWIND 9	*B14	42
REWIND 7	*B14	43
CALL CPRTIM(TIME,DT,1)	*B14	44
WRITE (6,150) TIME,DT	*B14	45
150	*B14	46
FORMAT(/10X,14#END DIAGIN, TIME=F10.4,5X,3#DT=F10.4)	*B14	46
RETURN	*B14	47
END	*B14	48

COMPLEX FUNCTION OSDZ(S)	WB15	1
COMMON/COM2/SIG2,H2	WB15	2
COMMON/COM5/O*OZ	WB15	3
COMMON/COM4/G2,G1	WB15	4
COMMON/COM6/W2,W	WB15	5
COMPLEX W,S,W2,G1,G2	WB15	6
OSDZ=0.5*(1.0-SIG2*W2)*(1.0+G1/G2)*O*OZ	WB15	7
RETURN	WB15	8
END	WB15	9

COMPLEX FUNCTION OZOS(S)	WB16	1
COMMON/COM1/A2,H2,R2	WB16	2
COMMON/COM2/SIG2,H2	WB16	3
COMMON/COM5/W2,W	WB16	4
COMPLEX W,S,W2,G1,S2,Z,Z2	WB16	5
S2=S*S	WB16	6
G1=0.5*(1.0+0.25*(A2-H2)**2)*(1.0+R2/S2)	WB16	7
Z=S+R2/S	WB16	8
Z2=Z*Z-4.0*SIG2	WB16	9
Y=AIMAG(Z)	WB16	10
YZ=AIMAG(Z2)	WB16	11
AY=1.0	WB16	12
AYZ=1.0	WB16	13
IF(Y.LT.0.0) AY=-1.0	WB16	14
IF(YZ.LT.0.0) AYZ=-1.0	WB16	15
Z2=CSQRT(Z2)*AY*AYZ	WB16	16
IF((ABS(Y).LE.0.0).AND.(REAL(Z).LT.0.0)) Z2=CMPLX(-REAL(Z2),	WB16	17
1 AIMAG(Z2))	WB16	18
OZOS=G1*(1.0+Z/Z2)	WB16	19
RETURN	WB16	20
END	WB16	21

SUBROUTINE ELHDVT (VA,WA,XPT,YPT,ZPT,NBODY)	WB17	1
C	WB17	2
C ROUTINE ELHDVT = ELLIPTICAL BODY NOSE SEPARATION VORTEX CALCULATION	WB17	3
C	WB17	4
C THIS ROUTINE INTERPOLATES IN TABLES OF VORTEX STRENGTH AND LOCATION	WB17	5
C VERSUS X-STATION TO COMPUTE THE VORTEX VELOCITIES AT BODY CONTROL	WB17	6
C POINTS	WB17	7
C	WB17	8
DIMENSION VA(1),WA(1),XPT(1),YPT(1),ZPT(1)	WB17	9
DIMENSION G(10),VX(10),VY(10)	WB17	10
DIMENSION YVPTX(10,10),ZVPTX(10,10),GX(10,10)	WB17	11
COMMON /BVPTX / NVTX,NXVTX,AV(10),AV(10),HV(10)	WB17	12
COMMON /JPTXS/ IZ1(60),IPRT(5),IXZSYM	WB17	13
LOGICAL LPRT,LPRT3	WB17	14
IF (NVTX.LE.0) RETURN	WB17	15
IF (NXVTX.LE.0) RETURN	WB17	16
LPRT = IPRT(1).GT.0	WB17	17
LPRT3 = IPRT(3).GT.0	WB17	18
C	WB17	19
C ----- VORTEX LOCATION AND STRENGTHS -----	WB17	20
C FIRST SUBSCRIPT = VORTEX NO. SECOND SUBSCRIPT = X-STATION	WB17	21
C	WB17	22
C READ VORTEX (Y,Z) LOCATIONS AT EACH STATION BY VORTEX	WB17	23
C	WB17	24

```

IF (LPRT) WRITE(6,190)
DO 130 I=1,NVIX
  READ(5,180) (YVRTX(I,J),J=1,NXVTX)
  IF (LPRT) WRITE(6,220) I,(YVRTX(I,J),J=1,NXVTX)
  READ(5,180) (ZVRTX(I,J),J=1,NXVTX)
  IF (LPRT) WRITE(6,230) I,(ZVRTX(I,J),J=1,NXVTX)
  READ(5,180) (GX(I,J),J=1,NXVTX)
  IF (LPRT) WRITE(6,210) I,(GX(I,J),J=1,NXVTX)
130 CONTINUE
C
C VORTEX INTERPOLATION SUMMARY TABLE
C
  WRITE(6,230)
  DO 135 I=1,NVIX
    WRITE(6,240) I
    WRITE(6,250) (J,XV(J),YVRTX(I,J),ZVRTX(I,J),AV(J),BV(J),GX(I,J)
    * ,J=1,NXVTX)
135 CONTINUE
C
C ----- LOOP ON BODY CONTROL POINTS -----
C
  IF (LPRT3) WRITE(6,270)
  DO 170 I=1,NBODY
    VA(I) = 0.0
    VB(I) = 0.0
    IF (XPT(I),LT,XV(1)) GO TO 170
    IF (XPT(I),GT,XV(NXVTX)) GO TO 170
C
C LOCATE X-CONTROL POINTS IN VORTEX TABLE
C
    DO 140 J=2,NXVTX
      IF (XPT(I),LE,XV(J)) GO TO 150
140 CONTINUE
      J = NXVTX
150 JM1 = J-1
      SLOPE = XV(J)-XV(JM1)
      IF (SLOPE,NE,0.) SLOPE=(XPT(I)-XV(JM1))/SLOPE
C
C INTERPOLATE FOR STRENGTH AND LOCATION OF EACH VORTEX
C
      DO 160 K=1,NVIX
        GK(K) = GX(K,JM1)+(GX(K,J)-GX(K,JM1))*SLOPE
        VK(K) = YVRTX(K,JM1)+(YVRTX(K,J)-YVRTX(K,JM1))*SLOPE
        VZ(K) = ZVRTX(K,JM1)+(ZVRTX(K,J)-ZVRTX(K,JM1))*SLOPE
160 CONTINUE
C
C RH IS HORIZONTAL AXIS AND BL IS VERTICAL AXIS
C
      RL = AV(JM1)+(AV(J)-AV(JM1))*SLOPE
      RB = BV(JM1)+(BV(J)-BV(JM1))*SLOPE
C
C DETERMINE Y AND Z COORDINATES OF POINT ON THE BODY SURFACE,
C LYING ON THE SAME RADIUS AS POINT XPT,YPT,ZPT, THAT IS WITH THE
C SAME POLAR ANGLE.
C
      THTP=ATAN2(ZPT(I),YPT(I))
      SINE=SIN(THTP)
      COSINE=COS(THTP)
      RAD=1.0/SQRT((COSINE/RL)**2+(SINE/BL)**2)
C
C MOVE POINT OUT 1 PERCENT OF BODY RADIUS.
C
      RAD=1.01*RAD

```



```

      VSURF=RAD*COSINE
      ZSURF=RAD*SINE
C
C COMPUTE VELOCITY COMPONENTS INDUCED BY THE SPECIFIED VORTICITY
C AT THE POINTS CALCULATED ABOVE.
C
      CALL VVELS(VVTX,YSURF,ZSURF,VX,VY,G,RR,BL,VA(I),WA(I),0,35)
C
      IF (LPRT3) WRITE(6,260) I,XPT(I),YSURF,ZSURF,VA(I),WA(I),RR,HL
      IF (LPRT3) WRITE(6,265) (K,VX(K),VY(K),G(K),K=1,NVTX)
170 CONTINUE
      RETURN
180 FORMAT(10F7.3)
190 FORMAT(///,10X,26HVORTEX LOCATION AND STRENGTH,
* 72X,12H** ELBOVT **)
200 FORMAT(/,5H I=,13,7H ZVRTX=,10F10.4)
210 FORMAT(/,5H I=,13,7H Gx=,10F10.4)
220 FORMAT(/,5H I=,13,7H YVRTX=,10F10.4)
230 FORMAT(///10X,26HVORTEX INTERPOLATION TABLE)
240 FORMAT(/ 5X,6HVORTEX,15,
* //5H STAT,7X,2HXV,5X,5HYVRTX,5X,5HZVRTX,8X,2HBY,8X,2HAZ
* ,5X,5HGAM/V/)
250 FORMAT(15,F10.3,5F10.4)
260 FORMAT(6H I=,15,7H XPT=,F10.4,7H YSURF=,F10.4,7H ZSURF=,F10.4,
* ,7H VA=,F10.5,7H WA=,F10.5,7H RR=,F10.4,7H HL=,F10.4)
265 FORMAT(6H K=,15,7H VX=,F10.4,7H VY=,F10.4,
* 7H G=,F10.4)
270 FORMAT(1H1,10X,43HVORTEX STRENGTHS AND VELOCITIES AFTER VVELS /)
      END

```

```

      SUBROUTINE FORMOM(NPAN,NPASS,ALFA,COMPT,TSTXCP)
C
C CALCULATE THE FORCE AND MOMENT COEFFICIENTS ON THE BODY, WING,
C FIN (VERTICAL TAIL) AND CANARD (HORIZONTAL TAIL)
C NOTE: AS USED IN PROGRAM WOYBOY, BODY ONLY IS TREATED.
C
      COMMON /JUPNTS/ IZ1(59),IVLIN
* ,NCPNT,XSTART,XLEN,NCP,IFLOT(4),IPRT(5),IXZSYM
      COMMON /HEAD / TITLE1(6),TITLE2(8)
      COMMON /DCN/ DCN(600),DCM(600),DCT(600),Z5(600),SIND(600),
1 CDSO(600),CP(600),DUD(500),SINT(600),COST(600),GH(600),
2 GH(600),DZTDX(600)
      COMMON /FORM / CMA,CTA,CMA,CMB,CTB,CMB,CMS(20),CTS(20),CMS(20)
      COMMON /PARAM / NBDY,NWING,NTAIL,LHC,THK,XHACH,ALPHA,BETA,ALPHAC
1 ,PHIR,REFR,REFH,REFC,REFD,REFL,REFX,REFZ
      COMMON /VELCOM/ NPOINT,NPART,IMAX,JMAX,NMAX,EM,IPHINT,NWTHK
1 ,NARBLK,NARON(20),NARBLK,NARON(60)
      COMMON /AEACOM/ KJ,KWAF,KWAFOR,KRADX(4),KFORX(4),KFUS,MAX,K4,K5
1 ,KF(6),KAN(6),KFINDR(6),KANOR(6),KOL,NCPT,LOCPT(20),XCPT(20)
      COMMON /SEG / NSEG,NROX(20),NCUL(20),COS8(20),SINS(20)
1 ,BTE(20),VAT(20),SPIN(20),ALEW(20),BLE(20),ZLEW(20),NPLT(60)
      COMMON /POINT / ARRAY(6000)
C
      DIMENSION XPT(600),YPT(600),ZPT(600),THET(600),DELTA(600),SGN(600)
1 ,AREA(600),PULAR(600),CHD(20),XLE(600), XC(50,20)
C
      EQUIVALENCE (CHD(1),DUD(1))

```

```

1      ,(XPT(1),ARRAY(1)),          (YPT(1),ARRAY(601))      *R18  28
2      ,(ZPT(1),ARRAY(1201)),      (THET(1),ARRAY(1801))   *R18  29
3      ,(DELTA(1),ARRAY(2401)),     (XC(1,1),ARRAY(3601))  *R18  30
4      ,(SGV(1),ARRAY(3601)),       (AREA(1),ARRAY(4801))  *R18  31
5      ,(XLE(1),ARRAY(5401)),       (PILAR(1),OZTOX(1))    *R18  32
      INTEGER COMPT
      LOGICAL LHC,LPLT,TSTXCP
      DATA RADDEG/0.0174532926/
      *R18  33
      *R18  34
      *R18  35
      *R18  36
      *R18  37
      *R18  38
      *R18  39
      *R18  40
      *R18  41
      *R18  42
      *R18  43
      *R18  44
      *R18  45
      *R18  46
      *R18  47
      *R18  48
      *R18  49
      *R18  50
      *R18  51
      *R18  52
      *R18  53
      *R18  54
      *R18  55
      *R18  56
      *R18  57
      *R18  58
      *R18  59
      *R18  60
      *R18  61
      *R18  62
      *R18  63
      *R18  64
      *R18  65
      *R18  66
      *R18  67
      *R18  68
      *R18  69
      *R18  70
      *R18  71
      *R18  72
      *R18  73
      *R18  74
      *R18  75
      *R18  76
      *R18  77
      *R18  78
      *R18  79
      *R18  80
      *R18  81
      *R18  82
      *R18  83
      *R18  84
      *R18  85
      *R18  86
      *R18  87
      *R18  88
      *R18  89
      *R18  90
C
C NOTE THAT THE WING, CANARD, AND TAIL ARE ALL SEGMENTS OF THE WING
C IN THIS SUBROUTINE
C
C COMPT=1 INDICATES BODY FORCE AND MOMENT CALCULATION
C      =2 INDICATES WING FORCE AND MOMENT CALCULATION
C
C NPASS=1 FOR THE BODY
C      =1 FOR THE WING UPPER AND LOWER SURFACES IF THE NON-PLANAR
C      BOUNDARY CONDITION OPTION IS SELECTED
C      =1 FOR THE WING UPPER SURFACE IF THE PLANAR BOUNDARY
C      CONDITION OPTION IS SELECTED
C      =2 FOR THE WING LOWER SURFACE IF THE PLANAR BOUNDARY
C      CONDITION OPTION IS SELECTED
C
C TSTXCP=FALSE, COMPUTE FORCES FOR ALL PANELS
C      =TRUE , COMPUTE FORCE ONLY BETWEEN XSTART AND XMLE
C
C IF (TSTXCP .AND. XSTART.GE.XMLE) RETURN
C NPAN=NPAN
C IF (COMPT.EQ.1) XON=XC(1,1)
C CAX=0.
C CTH=0.
C CMA=0.
C
C ALFA IS ALPHA SUB C IN RADS.
C
C SIAL=STN(ALFA)
C COAL=COS(ALFA)
C WRITE (6,320) TITLE1,TITLE2
C WRITE (6,310)
C IF (.NOT.TSTXCP) WRITE (6,450)
C IF ( TSTXCP) WRITE(6,460) XSTART,XMLE
C WRITE (6,330) XMACH,ALPHAC,PNIR
C WRITE (6,350)
C DO 50 I=1,MPAN
C   SGN(I)=1.
C   SIND(I)=SIN(DELTA(I))
C   COSD(I)=COS(DELTA(I))
C   SINT(I)=SIN(THET(I))
C   COST(I)=COS(THET(I))
50 CONTINUE
C   CNE0.
C   CT=0.
C   CN=0.
C   CYN=0.
C   CLHOLL=0.
C   CNYAW=0.
C   IP=0
C
C CALCULATE THE FORCES AND MOMENT ACTING ON EACH PANEL AND SUM OVER
C THE ENTIRE COMPONENT
C
C DO 160 I=1,MPAN
C   IP=IP+1

```

```

      XP=XP(I)
      YP=YP(I)
      ZP=ZP(I)
C
C CHECK WHETHER TO COMPUTE FORCE BETWEEN XSTART AND X*LE ONLY.
C
      IF (.NOT.TSTXCP) GO TO 150
      DCN(I) = 0.
      DCT(I) = 0.
      DCM(I) = 0.
      IF (XP.LT.XSTART .OR. XP.GT.X*LE) GO TO 160
150 CONTINUE
      CNORM=-CP(I)*AREA(I)*SGN(I)
C
C FORCE AND MOMENT SIGN CONVENTIONS, BODY COORDINATE SYSTEM.
C CNORM = POSITIVE OUTWARD NORMAL FORCE ON PANEL
C CXB = POSITIVE AFT
C CYB = POSITIVE TO RIGHT
C CZB = POSITIVE UP
C CMH = POSITIVE NOSE UP
C CNYAW = POSITIVE NOSE RIGHT VIEWING FORWARDS
C CLROLL = POSITIVE CLOCKWISE VIEWING FORWARDS
C
      DCXB = -CNORM*SIND(I)
      DCYB = -CNORM*COSD(I)*SINT(I)
      DCZB = CNORM*COSD(I)*COST(I)
      DCMB = -DCZB*(XP-REFX)+DCXB*(ZP-REFZ)
      DCNYAW = -DCYB*(XP-REFX)+DCXB*YP
      DCLROLL = -DCZB*YP +DCYB*(ZP-REFZ)
      DCN(I) = DCZB
      DCT(I) = DCXB
      DCM(I) = DCMB
      XQ=XP
      YQ=YP
      ZQ=ZP
C
C NONDIMENSIONALIZE BODY PANEL CONTROL POINT COORDINATES
C X COORDINATES ARE DIVIDED BY THE BODY REFERENCE LENGTH
C Y AND Z COORDINATES ARE DIVIDED BY THE BODY REFERENCE DIAMETER
C
      XQ=(XP-XON)/REFL
      YQ=YP/REFD
      ZQ=ZP/REFD
      THETP=ATAN2(ZP,YP)*57.29578
      IF (THETP.LT.0.0) THETP=THETP+360.0
      WRITE (6,360) IP,XP,YP,ZP,THETP,CP(I),DCXB,DCYB,DCZB,DCMB
      * ,DCNYAW,DCLROLL
      CN=CN+DCN(I)
      CT=CT+DCT(I)
      CM=CM+DCM(I)
      CYB = CYB+DCYB
      CNYAW = CNYAW+DCNYAW
      CLROLL = CLROLL+DCLROLL
160 POLAR(I)=ATAN2(YP,-ZP)*57.29
C
C PLOT CP VERSUS X AND POLAR ANGLE AROUND BODY
C
      IF (TSTXCP) GO TO 168
      LPLT=IPLOT(2).GT.0
      IF (.NOT.LPLT) GO TO 168
      NCHR=KFORX(I)-1
      NDP =KFAOX(I)-1
      IF (KFAUS.GT.1) NDP=NPANL

```

```

WB1A 91
WB1A 92
WB1A 93
WB1A 94
WB1A 95
WB1A 96
WB1A 97
WB1A 98
WB1A 99
WB1A 100
WB1A 101
WB1A 102
WB1A 103
WB1A 104
WB1A 105
WB1A 106
WB1A 107
WB1A 108
WB1A 109
WB1A 110
WB1A 111
WB1A 112
WB1A 113
WB1A 114
WB1A 115
WB1A 116
WB1A 117
WB1A 118
WB1A 119
WB1A 120
WB1A 121
WB1A 122
WB1A 123
WB1A 124
WB1A 125
WB1A 126
WB1A 127
WB1A 128
WB1A 129
WB1A 130
WB1A 131
WB1A 132
WB1A 133
WB1A 134
WB1A 135
WB1A 136
WB1A 137
WB1A 138
WB1A 139
WB1A 140
WB1A 141
WB1A 142
WB1A 143
WB1A 144
WB1A 145
WB1A 146
WB1A 147
WB1A 148
WB1A 149
WB1A 150
WB1A 151
WB1A 152
WB1A 153

```

```

IF (KFUS.GT.1) NCUR=1
DO 164 I=1, NCUR
164 NPLT(I)=NDP
CALL PLOTAP(XPT,CP,2,NPLT,NDP,NCUR,100,50)
WRITE(6,500)
CALL PLOTAP(POLAR,CP,2,NPLT,NDP,NCUR,100,50)
WRITE(6,510)
168 CONTINUE
C
C STORE BODY AND WING FORCES AND MOMENT
C
CNR=CN
CTR=CT
CNR=CN
WRITE(6,370)
IF (.NOT.TSTXCP) WRITE(6,450)
IF (.TSTXCP) WRITE(6,460) XSTART,XALE
C
C COMPUTE NORMAL AND TANGENTIAL (AXIAL) FORCE, PITCHING MOMENT,
C LIFT AND DRAG COEFFICIENTS, AND COMPONENT CENTER OF PRESSURE
C
C CHECK FOR SYMMETRIC CONFIGURATION
SYM = 2.0
IF (IXZSYM.EQ.0) SYM=1.0
CN=SYM*CN/REFA
CT=SYM*CT/REFA
CM=SYM*CM/(REFA*REFD)
CYR=CVR/REFA
CNYA=(CNYA)/(REFA*REFD)
CLRROLL=CLRROLL/(REFA*REFD)
C
C
IF (IXZSYM.EQ.0) CYR=0.
IF (IXZSYM.EQ.0) CLRROLL=0.
IF (IXZSYM.EQ.0) CNYA=0.
C
C TRANSFORM FORCES AND MOMENTS (EXCEPT ROLLING MOMENT) INTO
C X-Y-Z AXIS SYSTEM.
C
PHI=PHI*WADDEG
SINPHI=SIN(PHI)
COSPHI=COS(PHI)
C
CL=CN*COSPHI*COAL-CYR*SINPHI*COAL-CT*SIAL
CY=CN*SINPHI+CYR*COSPHI
CD=CT*COAL-CYR*SIAL+SINPHI*CN*SIAL+COSPHI
C
CNYA=(CNYA+COSPHI-CNYA*SINPHI
CNYA=(CNYA*COAL+SINPHI+CNYA*COAL+COSPHI-CLRROLL*SIAL
C
C XN IS CENTER OF PRESSURE LOCATION MEASURED FROM NOSE TIP
C
OX=0.
IF (CM.EQ.0.) OX=(+CM/CN)*REFD+REFX
IF (CMPT.EQ.1) WRITE(6,590) WLEA,REFD,REFL
WRITE(6,300) REFX,REFZ
WRITE(6,010) XNACH,ALPHAC,ALPHA,PHI,PHI,PHI,CT,CYR,CN,CM,CNYA
* CLRROLL,OXN,CL,CY,CD,CNA,CNYA
RETURN
310 FORMAT (//OX,40) INTEGRATION OF THE PRESSURE DISTRIBUTION
* ,OX,12** FORM ** /)
320 FORMAT (1-1,9,4A10//OX,8A10)

```

```

*H1R 154
*H1R 155
*H1R 156
*H1R 157
*H1R 158
*H1R 159
*H1R 160
*H1R 161
*H1R 162
*H1R 163
*H1R 164
*H1R 165
*H1R 166
*H1R 167
*H1R 168
*H1R 169
*H1R 170
*H1R 171
*H1R 172
*H1R 173
*H1R 174
*H1R 175
*H1R 176
*H1R 177
*H1R 178
*H1R 179
*H1R 180
*H1R 181
*H1R 182
*H1R 183
*H1R 184
*H1R 185
*H1R 186
*H1R 187
*H1R 188
*H1R 189
*H1R 190
*H1R 191
*H1R 192
*H1R 193
*H1R 194
*H1R 195
*H1R 196
*H1R 197
*H1R 198
*H1R 199
*H1R 200
*H1R 201
*H1R 202
*H1R 203
*H1R 204
*H1R 205
*H1R 206
*H1R 207
*H1R 208
*H1R 209
*H1R 210
*H1R 211
*H1R 212
*H1R 213
*H1R 214
*H1R 215
*H1R 216

```

```

330  FORMAT (/10X,6MMACH =,F8.4,3X,7HALPHAC=,F8.4,4X,5MHPHIZ=,F8.4/)      WB18 217
350  FORMAT (3X,5MPOINT,7X,1HX,10X,1HY,10X,1HZ,6X,5MHTFPT,AX,2MCP,9X,      WB18 218
* 2MCHX,4X,2MCHY,4X,2MCHZ,9X,2MCH,8X,3MCLM,8X,3MCLL/)                WB18 219
360  FORMAT (I7,I1F1),5)                                                WB18 220
370  FORMAT (14I,9X,18MTOTAL COEFFICIENTS/10X,18(1H=))                  WB18 221
390  FORMAT (10X,5MREFAC=,F14.4,3X,5MREFDC=,F14.4,3X,5MREFL=,F14.4)     WB18 222
400  FORMAT (/10X,5MXXM =,F14.4,3X,5MZZM =,F14.4)                        WB18 223
410  FORMAT (/8X,5MMACH=,F15.5/6X,7HALPHAC=,F15.5,7X,6HALPHA=,F15.5,      WB18 224
* /8X,5MHPHIZ=,F15.5,4X,5MBETA=,F15.5,/10X,3MCHY=,F15.5              WB18 225
* /10X,3MCHZ=,F15.5,/10X,3MCH=,F15.5,/10X,3MCM=,F15.5                WB18 226
* /9X,4MCLM=,F15.5,/9X,4MCLL=,F15.5,/9X,4MCHCP=,F15.5,              WB18 227
* //10X,33M FOLLOWING ARE IN WIND AXIS SYSTEM,                          WB18 228
* /10X,3MCL=,F15.5,/10X,3MCHY=,F15.5,                                  WB18 229
* /10X,3MCHZ=,F15.5,/9X,4MCM=,F15.5,                                   WB18 230
* /6X,7MCHYAW=,F15.5,/)                                                WB18 231
450  FORMAT (10X,11MIN THE BODY//)                                       WB18 232
460  FORMAT(10X,24MIN THE BODY FROM XSTART=,F10.4,9H TO XMLE=,F10.4//)  WB18 233
500  FORMAT(/20X,11MCP VERSUS X).                                         WB18 234
510  FORMAT//20X,24MCP VERSUS MERIDIAN ANGLE)                             WB18 235
END                                                                        WB18 236

```

```

SUBROUTINE GEOM                                                         WB19  1
CDC  OVERLAY (L=0,1,0)                                                WB19  2
CDC  PROGRAM GEOM                                                      WB19  3
C                                                                              WB19  4
C  INPUT CONFIGURATION GEOMETRY AND COMPUTE PANELS                    WB19  5
C                                                                              WB19  6
C  SPECIAL COMMENT CARDS STARTING WITH:                                WB19  7
C  CH = ELIMINATED FOR BODY PROGRAM VERSION ONLY                      WB19  8
C  CNP = ELIMINATED FOR NON PLANAR PANEL ONLY                         WB19  9
C                                                                              WB19 10
C  TAPE USAGE IN GEOM=                                               WB19 11
C  TAPE5:  GEOM,  READ INPUT                                          WB19 12
C                                                                              WB19 13
C  TAPE7:  GEOM,  REWIND                                             WB19 14
C          BODYPAN, WRITE ARRAY  = SAVE BODY GEOMETRY                WB19 15
C                                                                              WB19 16
C  TAPE8:  NOT USED IN BODY VERSION                                  WB19 17
C  TAPE9:  NOT USED IN BODY VERSION                                  WB19 18
C                                                                              WB19 19
C  TAPE10: GEOM,  REWIND                                             WB19 20
C          NEWRAD, WRITE XB,YB,ZB = FROM ARRAY                        WB19 21
C          BODYPAN, REWIND                                           WB19 22
C                                                                              WB19 23
C          READ XB,YB,ZB = INTO BLOCK                                WB19 24
C          REWIND                                                    WB19 25
C                                                                              WB19 26
COMMON /JOPTNS/ IZ1(8)                                               WB19 27
1  ,J0,J1,J2,J3,J4,J5,J6,NWAF,NWAFOR,NFUS,NRADX(4),NFORX(4)         WB19 28
2  ,NP,NPDIR,NF,NFINOR,NCAN,NCANOR,J2TEST,NW,  IZ2(25)              WB19 29
3  ,NVLIN,NCPINT,XSTART,XMLE,NMCP,IPLOT(4),IPRT(5),IXZSYM          WB19 30
COMMON /PARAM / KBODY,NHING,NTAIL,LBC,THK,XMACH,ALPHA,BETA,ALPHAC  WB19 31
1  ,PHI0,REFA,REFB,REFC,REFD,REFL,REFY,REFZ                          WB19 32
COMMON /HEAD / TITLE1(8),TITLE2(8)                                   WB19 33
COMMON /SEG / NSEG,NRUX(20),NCOL(20),CNSS(20),SINS(20)             WB19 34
1  ,RTE(20),NWT(20),SPN*(20),XLE*(20),BLE*(20),ZLE*(20),ZB(60)    WB19 35
COMMON /BLOCK(7500)                                                  WB19 36
COMMON /NEWCOM/ K1,KWAF,KWAFOR,KWADIX(4),KFORX(4),KFUS,MAX,K4,K5   WB19 37
1  ,KF(6),KX(6),KFINDX(6),KAMOR(6),KFL,NCPT,LCCPT(20),XCPT(20)    WB19 38
COMMON /VELCOM/ MPOINT,MPART,IZ4(2),NMAX,EM,IPRINT,NWTHK

```

1	,N=NBLOCK,NVROW(20),N=NBLOCK,NBROW(60)	WB19	39
	COMMON/ITERAT/ITMAX,CCTEST	WB19	40
	COMMON /RVMTX / NVTX,NXVTX,XV(10),AV(10),BV(10)	WB19	41
C	LOGICAL LBC,THK,TAIL,LPRT	WB19	42
C	IF (INIT.EQ.1) GO TO 9	WB19	43
	DO 5 I=1,24	WB19	44
5	KF(I)=0	WB19	45
	DO 6 I=1,260	WB19	46
6	MPW(I)=0	WB19	47
9	INIT=1	WB19	48
C	LBC=TRUE,, FOR PLANAR BOUNDARY CONDITION ON WINGS (LINBC=1)	WB19	49
C	LBC=FALSE,, FOR NON-PLANAR BOUNDARY CONDITION (LINBC=0)	WB19	50
C	THK = ,TRUE,, FOR WINGS WITH THICKNESS AND NONPLANAR PANELING	WB19	51
C	(ITHICKX0)	WB19	52
CNP	LBC=FALSE.	WB19	53
	LBC=TRUE.	WB19	54
	THK=FALSE.	WB19	55
	EM=1.	WB19	56
	ALPHA = 0.0	WB19	57
	BETA = 0.0	WB19	58
	IPRINT=0	WB19	59
	NCPT=0	WB19	60
	NBODY=0	WB19	61
	NWING=0	WB19	62
	NTAIL=0	WB19	63
	NSEGE=0	WB19	64
	KOL=0	WB19	65
	REFR=1.	WB19	66
	REFC=1.	WB19	67
	REFD=1.	WB19	68
	REFL=1.	WB19	69
	REFX=0.	WB19	70
	REFZ=0.	WB19	71
	ITMAX=0	WB19	72
	CCTEST=0.	WB19	73
	REWIND 7	WB19	74
CR	REWIND 8	WB19	75
CR	REWIND 9	WB19	76
	REWIND 10	WB19	77
C		WB19	78
C	INPUT CONFIGURATION PARAMETERS	WB19	79
C	READ (5,150) TITLE1	WB19	80
	IF (EOF(5).NE.0.)	WB19	81
	STOP 20	WB19	82
10	WRITE (6,170) TITLE1	WB19	83
C		WB19	84
C	DEBUG PRINT CONTROL OPTIONS	WB19	85
	READ (5,180) IPRT,IXZSYM,IPLOT,NWCPT,NVTX,NXVTX,NCPOUT,NVLIN	WB19	86
	LPRT = IPRT(1),GT.0	WB19	87
	IF (LPRT) WRITE(6,220) IPRT,IXZSYM,IPLOT,NWCPT,NVTX,NXVTX,NCPOUT	WB19	88
	*,NVLIN	WB19	89
C		WB19	90
C	VORTEX CALCULATION PARAMETERS	WB19	91
	READ (5,160) XWLE,XSTART	WB19	92
	IF (LPRT) WRITE(6,290) XWLE,XSTART	WB19	93
C		WB19	94
C	GEOMETRY DEFINITION OPTIONS	WB19	95
	READ (5,180) J0,J1,J2,J3,J4,J5,J6,NWAF,NWAFOR,NFUS,	WB19	96
	1 (NRAOX(I),NFURX(I),I=1,4),NP,NPOORH,NF,NFINOR,NCAN,NCANOR	WB19	97
	IF (LPRT) WRITE(6,230) J0,J1,J2,J3,J4,J5,J6,NWAF,NWAFOR,NFUS	WB19	98
		WB19	99
		WB19	100
		WB19	101

	1	,KRADX,KFORX,NP,NPCORR,KF,KFINOR,KAN,KCANOR	WB19 102
C			WB19 103
C		INPUT DESCRIPTION AND INITIALIZATION	WB19 104
C		SET BOUNDARY CONDITION AND WING THICKNESS OPTIONS	WB19 105
C			WB19 106
30		CALL COMFIG	WB19 107
CDC		CALL OVERLAY (L*H,1,1)	WB19 108
		READ (5,150) TITLE2	WB19 109
		IF (LPRT) WRITE(6,170) TITLE2	WB19 110
		READ (5,140) LINHC,ITHICK,IPRINT,LCPA,LCPB,LCPC,ITMAX,CCTEST	WB19 111
		IF (LPRT) WRITE(6,240)	WB19 112
		* LINHC,ITHICK,IPRINT,LCPA,LCPB,LCPC,ITMAX,CCTEST	WB19 113
		IF (LINHC.GT.0) LBC=TRUE.	WB19 114
		IF (LCP.AND.ITHICK.GT.0) THK=TRUE.	WB19 115
C			WB19 116
C		INPUT REVISED CONFIGURATION PANELING DESCRIPTION CONTROL INTEGERS	WB19 117
C			WB19 118
		READ (5,180) K0,K1,K2,K3,K4,K5,K6,KWAF,KWAFOR,KFUS,	WB19 119
		1 (KRADX(I),KFORX(I),I=1,4)	WB19 120
		IF (LPRT) WRITE(6,250) K0,K1,K2,K3,K4,K5,K6,KWAF,KWAFOR,KFUS,	WB19 121
		1 KRADX,KFORX	WB19 122
		TAIL=FALSE.	WB19 123
		IF (K4.GT.0.OR.K5.GT.0) TAIL=TRUE.	WB19 124
		IF (TAIL)	WB19 125
		1 READ (5,180) (KF(I),KFINOR(I),I=1,6),(KAN(I),KCANOR(I),I=1,6)	WB19 126
		IF (LPRT.AND.TAIL) WRITE(6,260) KF,KFINOR,KAN,KCANOR	WB19 127
C			WB19 128
CH40		READ (9) REFA	WB19 129
		IF (K0.EQ.0) GO TO 50	WB19 130
		READ (5,160) REFAF,REFB,REFC,REFD,REFL,REFX,REFZ	WB19 131
		IF (LPRT) WRITE (6,270) REFAF,REFB,REFC,REFD,REFL,REFX,REFZ	WB19 132
		IF (REFAF.EQ.0.) REFA=REFAF	WB19 133
		IF (REFB.EQ.0.) REFB=1.	WB19 134
		IF (REFC.EQ.0.) REFC=1.	WB19 135
		IF (REFD.EQ.0.) REFD=1.	WB19 136
		IF (REFL.EQ.0.) REFL=1.	WB19 137
C			WB19 138
C		GENERATE GEOMETRY IN ORDER WING, V, TAIL, H, TAIL, BODY	WB19 139
C			WB19 140
50		CONTINUE	WB19 141
		IF (KRADX(1).LE.21) GO TO 70	WB19 142
		WRITE (6,200)	WB19 143
		STOP 200	WB19 144
70		CONTINUE	WB19 145
C			WB19 146
C		READ AND COMPUTE BODY VORTEX GEOMETRY REQUIRED -----	WB19 147
C			WB19 148
		CALL READVX (NFUS,NFORX,LPRT)	WB19 149
C			WB19 150
C		REVISE BODY (FUSELAGE) MERIDIAN LINE SPACING, THEN	WB19 151
C		REVISE AXIAL PANEL SPACING ON BODY (FUSELAGE) AND	WB19 152
C		COMPUTE NEW PANEL GEOMETRY	WB19 153
C			WB19 154
		CALL NEWRAD	WB19 155
		CALL BODPAN	WB19 156
CDC		CALL OVERLAY (L*H,1,4)	WB19 157
CDC		CALL OVERLAY (L*H,1,5)	WB19 158
C			WB19 159
C		WRITE CONTROL POINTS ON TAPE4 -----	WB19 160
C		IF NCPOUT.GT.0, PRTCP GENERATES CONTROL POINT FOR VPATHL	WB19 161
C		IF NCPOUT=2, STOP AFTER WRITING POINTS	WB19 162
C			WB19 163
		IF (NCPOUT.GT.0) CALL PRTCP(NBODY)	WB19 164

```

C      CALL CPUTIM (TIME,DT,1)
      IF (IPRINT.LT.0) WRITE(6,210) TIME,DT
      RETURN
C
C
140  FORMAT (7I3,F7.0)
150  FORMAT (A10)
160  FORMAT (10F7.0)
170  FORMAT (///5X,A10,25X,12H** GEOM ** )
180  FORMAT (24I5)
200  FORMAT (100,46HERROR= BODY HAS MORE THAN 20 COLUMNS OF PANELS)
210  FORMAT(///10X,16HEND GEOM , , TIME=,F10.3,5X,3HDT=,F10.3)
220  FORMAT(///5X,52HADDITIONAL PRINT OPTIONS (IPRT) * XZ-PANEL SYMMETRY
*      //43H   IN GEOM VORTEX   VEL   SOLN IXZSYM //6I7
*      //5X,20HPLOT OPTIONS (IPLT)
*      //28H   GEOM   CP   U/V/W //4I7
*      //5X,26HVORTEX CALCULATION CONTROL
*      //35H   N-CPT   NVTX   NVVIX   NCPRT   NVLIN //5I7)
230  FORMAT(///10X,37HJ-DATA CARDS REQUIRED (NO=0,YES,NE,0)
*      //40H   REFA   WING   BODY   POD   V,FIN H,TAIL XY=SYM
*      //49H   J0      J1      J2      J3      J4      J5      J6//7I7
*      //21H   WING GEOM:   KWAF=,15,3X,7HKWAFOR=,15,
*      //21H   BODY GEOM:   KWBS=,15,4X,6HKWBOXR=,4I5
*      //30X,6HKWFORX=,4I5
*      //21H   POD GEOM:   KP=,15,3X,7HKPPODR=,15
*      //21H   V,FIN GEOM:   KFB=,15,3X,7HKFINOR=,15
*      //21H   H,TAIL GEOM:   KCAN=,15,3X,7HKCANOR=,15)
240  FORMAT(///50H   LINHC THICK IPRINT LCPA LCPB LCPC ITMAX
*      //7H   CCFST //7I7,F10.5)
250  FORMAT(///10X,44HJ-DATA CARDS, ADDITIONAL CARDS FOR PANELING
*      //50H   REF   WING   BODY   V/A   V,FIN H,TAIL   N/A
*      //50H   K0      K1      K2      K3      K4      K5      //7I7
*      //22H   WING PANEL:   KWAF=,15,3X,7HKWAFOR=,15,
*      //22H   BODY PANEL:   KWBS=,15,4X,6HKWBOXR=,4I5
*      //31X,6HKWFORX=,4I5)
260  FORMAT(10H   V,FIN PANEL:16X,7H   KFB=,6I5,//30X,7HKFINOR=,6I5
*      //10H   H,TAIL PANEL:16X,7H   KCAN=,6I5,//30X,7H   KCANOR=,6I5)
270  FORMAT(///10X,23HPANEL REFERENCE LENGTHS
*      //4X,5HREFAR,6X,4HREFR,6X,4HREFC,6X,4HREFD,6X,4HREFL
*      //6X,4HREFX,6X,4HREFZ,//F10.3)
290  FORMAT (/6X,4HXPLE,4X,6HXSTART //2F10.3)
      END

```

```

WR19 165
WR19 166
WR19 167
WR19 168
WR19 169
WR19 170
WR19 171
WR19 172
WR19 173
WR19 174
WR19 175
WR19 176
WR19 177
WR19 178
WR19 179
WR19 180
WR19 181
WR19 182
WR19 183
WR19 184
WR19 185
WR19 186
WR19 187
WR19 188
WR19 189
WR19 190
WR19 191
WR19 192
WR19 193
WR19 194
WR19 195
WR19 196
WR19 197
WR19 198
WR19 199
WR19 200
WR19 201
WR19 202
WR19 203
WR19 204
WR19 205
WR19 206
WR19 207

```

```

      SUBROUTINE INVERT(A,IA,NROWS)
C
C MATRIX INVERSION --- GAUSS-JORDAN ELIMINATION WITHOUT PIVOTING
C
      DIMENSION IPIVOT(60),INDX(60),INDX(60),A(60,60),N=IA
      DO 10 J=1,N
      IPIVOT(J)=0
10  CONTINUE
      DO 100 I=1,
      I=0
      DO 30 J=1,
      IF (IPIVOT(J).EQ.1) GO TO 30
      DO 20 K=1,
      IF (IPIVOT(K).EQ.1) GO TO 20

```

```

WR20 1
WR20 2
WR20 3
WR20 4
WR20 5
WR20 6
WR20 7
WR20 8
WR20 9
WR20 10
WR20 11
WR20 12
WR20 13
WR20 14
WR20 15

```


	IF (.NOT.(ABS(A(J,K))-ABS(1,GT,0.)) GO TO 20	WR20 16
	IROW=J	WR20 17
	ICOL=K	WR20 18
	T=A(J,K)	WR20 19
20	CONTINUE	WR20 20
30	CONTINUE	WR20 21
	IPIVOT(ICOL)=IPIVOT(ICOL)+1	WR20 22
	IF (IROW.EQ.ICOL) GO TO 50	WR20 23
	DO 40 L=1,N	WR20 24
	T=A(IROW,L)	WR20 25
	A(IROW,L)=A(ICOL,L)	WR20 26
	A(ICOL,L)=T	WR20 27
40	CONTINUE	WR20 28
50	INDXR(I)=IROW	WR20 29
	INDXC(I)=ICOL	WR20 30
	PIVOT=A(ICOL,ICOL)	WR20 31
	IF (PIVOT.EQ.0.) GO TO 130	WR20 32
	A(ICOL,ICOL)=1.	WR20 33
	DO 70 L=1,N	WR20 34
	A(ICOL,L)=A(ICOL,L)/PIVOT	WR20 35
70	CONTINUE	WR20 36
	DO 90 L=1,N	WR20 37
	IF (L.EQ.ICOL) GO TO 90	WR20 38
	T=A(L,ICOL)	WR20 39
	A(L,ICOL)=0.	WR20 40
	DO 80 M=1,N	WR20 41
	A(L,M)=A(L,M)-A(ICOL,M)*T	WR20 42
80	CONTINUE	WR20 43
90	CONTINUE	WR20 44
100	CONTINUE	WR20 45
	DO 120 I=1,N	WR20 46
	L=N+1-I	WR20 47
	IF (INDXR(L).EQ.INDXC(L)) GO TO 120	WR20 48
	IROW=INDXR(L)	WR20 49
	ICOL=INDXC(L)	WR20 50
	DO 110 K=1,N	WR20 51
	T=A(K,IROW)	WR20 52
	A(K,IROW)=A(K,ICOL)	WR20 53
	A(K,ICOL)=T	WR20 54
110	CONTINUE	WR20 55
120	CONTINUE	WR20 56
	RETURN	WR20 57
130	WRITE (6,140)	WR20 58
	STOP	WR20 59
140	FORMAT (1H0,30HERROR = THE MATRIX IS SINGULAR)	WR20 60
	END	WR20 61

	SUBROUTINE ITRATE	WR21 1
C		WR21 2
C	SOLVE THE BOUNDARY CONDITION EQUATIONS BY AN ITERATIVE METHOD AND	WR21 3
C	DETERMINE THE STRENGTHS OF THE BODY SOURCES AND THE WING, FIN	WR21 4
C	(VERTICAL TAIL), AND CANARD (HORIZONTAL TAIL) VORTICES.	WR21 5
C		WR21 6
	COMMON /POINT / D(60,60),DNR(600),DNR(600),Z6(1200)	WR21 7
	COMMON	WR21 8
	NR(600),NR(600),NT(600),A(600),R*(600),RR(600),	WR21 9
	I Z7(2160),G*(600),G3(600),GT(600)	WR21 10
	COMMON /PARAM / NHODY,NWING,NTAIL,LHC,THK,XMACH,ALPHA,BETA,ALPHAC	WR21 11
	I ,DNTR,REFA,REFB,REFC,REFD,REFL,REFX,REFZ	WR21 12
	COMMON /VELCOM/ NPOINT,NPART,IMAX,JMAX,NMAX,EM,IPRINT,NHTK	WR21 13

1	,NBLOCK,NBROW(20),NBBLOCK,NBROW(60)	WR21	13
	COMMON /ITERAT/ ITMAX,CCTEST	WR21	14
	REAL NB,NA,NT	WR21	15
C		WR21	16
C	VARIABLE DEFINITIONS:	WR21	17
C	NW,NB = INPUT NORMAL VELOCITY, WING AND BODY	WR21	18
C	GA,GB = OUTPUT STRENGTH (WING AND BODY)	WR21	19
C	D = DIAGONAL BLOCK MATRIX	WR21	20
C	RW,RR = RESIDUAL NORMAL VELOCITY COMPONENT	WR21	21
C	NT,GT = TEMPORARY VECTORS FOR LAST ITERATION	WR21	22
C		WR21	23
	ITMAX=15	WR21	24
	IF (ITMAX.NE.0) ITMAX=ITMAX	WR21	25
	EPS=1.E-3	WR21	26
	IF (CCTEST.NE.0.) EPS=CCTEST	WR21	27
	REWIND 9	WR21	28
C		WR21	29
C	INITIALIZE WING AND BODY SOLUTION	WR21	30
C		WR21	31
	IF (NBBODY.EQ.0) GO TO 20	WR21	32
	DO 10 N=1,NBBODY	WR21	33
	NT(N)=0.	WR21	34
	RB(N)=RB(N)	WR21	35
10	CONTINUE	WR21	36
20	CONTINUE	WR21	37
C8	IF (NBWING.EQ.0) GO TO 40	WR21	38
C8	DO 30 N=1,NBWING	WR21	39
C8	GT(N)=0.	WR21	40
C8	RW(N)=RW(N)	WR21	41
C830	CONTINUE	WR21	42
C		WR21	43
C	START ITERATION -----	WR21	44
C		WR21	45
40	DO 250 IT=1,ITMAX	WR21	46
	CALL CPUTIM(TIME,OT,1)	WR21	47
	IF (IABS(IPRINT).GT.2) WRITE(6,390) IT,TIME,OT	WR21	48
	ITEST=0	WR21	49
	IH=0	WR21	50
	I=0	WR21	51
	IF (NBBODY.EQ.0) GO TO 80	WR21	52
C		WR21	53
C	COMPUTE BODY STRENGTHS FROM DIAGONAL BLOCKS - GB = 0*RB	WR21	54
C		WR21	55
	JS=0	WR21	56
	NBLOCK=NBBLOCK	WR21	57
	DO 60 NN=1,NBLOCK	WR21	58
	NRROW=NRROW(NN)	WR21	59
	NCOL=NRROW	WR21	60
	READ (10) D	WR21	61
	DO 50 I=1,NRROW	WR21	62
	IH=IH+1	WR21	63
	GB(IH)=0.	WR21	64
	DO 50 JJ=1,NCOL	WR21	65
	JJ=J+JS	WR21	66
	GB(IH)=GB(IH)+D(I,J)*RB(JJ)	WR21	67
50	CONTINUE	WR21	68
	JS=JS+NRROW	WR21	69
60	CONTINUE	WR21	70
C	BODY CONVERGENCE TEST	WR21	71
	IF (IT.EQ.1) GO TO 80	WR21	72
	DO 70 N=1,NBBODY	WR21	73
	IF (ABS(GB(N)-NT(N)).GE.EPS) ITEST=1	WR21	74
	IF (ITEST.EQ.1) GO TO 80	WR21	75

70	CONTINUE	WR21	76
C		WR21	77
C	COMPUTE WING STRENGTHS FROM DIAGONAL BLOCKS = GW = D*RW	WR21	78
C		WR21	79
80	CONTINUE	WR21	80
CR	IW = 0	WR21	81
CR	IF (N*WING.EQ.0) GO TO 120	WR21	82
CR	JS=0	WR21	83
CR	NHBLK=N*HBLK	WR21	84
CR	DO 100 I=1,NHBLK	WR21	85
CR	NRD=N*NRD+(I*NN)	WR21	86
CR	NCDL=NRD*	WR21	87
CR	READ (10) D	WR21	88
CR	DO 90 I=1,NRDW	WR21	89
CR	IW=IW+1	WR21	90
CR	GW(IW)=0.	WR21	91
CR	DO 90 J=1,NCDL	WR21	92
CR	JJ=J+JS	WR21	93
CR	GW(IW)*GW(I*J)+D(I,J)*RW*(JJ)	WR21	94
CR90	CONTINUE	WR21	95
CR	JS=JS+NRD*	WR21	96
CR100	CONTINUE	WR21	97
CR	WING CONVERGENCE TEST	WR21	98
CR	IF (IT.EQ.1) GO TO 120	WR21	99
CR	DO 110 N=1,N*WING	WR21	100
CR	IF (ABS(GW(N)-GT(N)).GE.EPS) ITTEST=1	WR21	101
CR	IF (ITTEST.EQ.1) GO TO 120	WR21	102
CR110	CONTINUE	WR21	103
C		WR21	104
C	PRINT ITERATION INFORMATION -----	WR21	105
C		WR21	106
120	REKIND 10	WR21	107
	IF (IAHS(IPRINT).LT.3) GO TO 130	WR21	108
	WRITE (6,300) IT	WR21	109
	IF (N*BODY.GT.0) WRITE (6,370) N*BODY,(GB(N),N=1,N*BODY)	WR21	110
	IF (N*WING.GT.0) WRITE (6,380) N*WING,(GW(N),N=1,N*WING)	WR21	111
130	IF (IAHS(IPRINT).LT.4) GO TO 140	WR21	112
	IF (N*BODY.GT.0) WRITE (6,290) N*BODY,(RB(N),N=1,N*BODY)	WR21	113
	IF (N*WING.GT.0) WRITE (6,300) N*WING,(RW(N),N=1,N*WING)	WR21	114
140	IF (ITTEST.EQ.0.AND.IT.NE.1) GO TO 260	WR21	115
	IF (IT.GE.IMAX) GO TO 270	WR21	116
C		WR21	117
C	COMPUTE CROSS INFLUENCE BETWEEN BLOCKS -----	WR21	118
C	BODY PANEL J ON BODY CONTROL POINT I	WR21	119
C		WR21	120
CR	IF (N*BODY.EQ.0) GO TO 200	WR21	121
	DO 165 I=1,N*BODY	WR21	122
	BT(I)=GB(I)	WR21	123
	DNB(I)=0.	WR21	124
	READ (9) (A(J),J=1,N*BODY)	WR21	125
	IF (N*BODY.LE.N*MAX) GO TO 160	WR21	126
	DO 150 J=1,N*BODY	WR21	127
	DNB(I)=DNB(I)+A(J)*GB(J)	WR21	128
150	CONTINUE	WR21	129
160	DR(I)=NRB(I)-DNB(I)	WR21	130
165	CONTINUE	WR21	131
C	WING PANEL J ON BODY CONTROL POINT I	WR21	132
CR	IF (N*WING.EQ.0) GO TO 200	WR21	133
CR240	CONTINUE	WR21	134
250	REKIND 9	WR21	135
C		WR21	136
C	PRINT ITERATION SUMMARY -----	WR21	137
260	WRITE (6,310) IT,EPS	WR21	138

GO TO 280	WR21 139
270 WRITE (6,320) IMAX,EPS	WR21 140
280 WRITE (6,330)	WR21 141
IF (NBODY,GT,0) WRITE (6,370) NBODY,(NT(N),N=1,NBODY)	WR21 142
IF (N*ING,GT,0) WRITE (6,380) N*ING,(GT(N),N=1,N*ING)	WR21 143
WRITE (6,340)	WR21 144
IF (NBODY,GT,0) WRITE (6,370) NBODY,(GB(N),N=1,NBODY)	WR21 145
IF (N*ING,GT,0) WRITE (6,380) N*ING,(GW(N),N=1,N*ING)	WR21 146
RETURN	WR21 147
290 FORMAT (2X,10HRR(N),N=1,,13/(1X,10F10,5))	WR21 148
300 FORMAT (2X,10HRR(N),N=1,,13/(1X,10F10,5))	WR21 149
310 FORMAT (1H0,29HTHE ITERATION CONVERGED AFTER,14,2X,	WR21 150
1 35HITERATIONS WITH A TEST CRITERION OF,F10,7)	WR21 151
320 FORMAT (1H0,36HTHE ITERATION DID NOT CONVERGE AFTER,14,2X,	WR21 152
1 35HITERATIONS WITH A TEST CRITERION OF,F10,7)	WR21 153
330 FORMAT (1H0,41HTHE SOLUTION AT THE PREVIOUS ITERATION IS)	WR21 154
340 FORMAT (1H0,40HTHE SOLUTION AT THE PRESENT ITERATION IS)	WR21 155
350 FORMAT (17H0ITERATION NUMBER,14)	WR21 156
370 FORMAT (2X,10HGR(N),N=1,,13/(1X,10F10,5))	WR21 157
380 FORMAT (2X,10HGA(N),N=1,,13/(1X,10F10,5))	WR21 158
390 FORMAT (/10X,25HCPU TIME IN ITRATE AT IT=,14	WR21 159
* ,5X,5HTIME=,F10,4,5X,3HDT=,F10,4)	WR21 160
END	WR21 161

SUBROUTINE MXOUT (PAR,VAL,A,N,M,LINS,IPOS,ISP,NO,MO)	WR22 1
-----	WR22 2
	WR22 3
SUBROUTINE MXOUT	WR22 4
	WR22 5
PURPOSE	WR22 6
PRODUCES AN OUTPUT LISTING OF ANY SIZED ARRAY ON	WR22 7
LOGICAL UNIT 6	WR22 8
	WR22 9
USAGE	WR22 10
CALL MXOUT (PAR,VAL,A,N,M,LINS,IPOS,ISP,NO,MO)	WR22 11
	WR22 12
DESCRIPTION OF PARAMETERS	WR22 13
PAR = ALPHANUMERIC PARAMETER NAME, HH-----	WR22 14
VAL = NUMERICAL VALUE OF PAR	WR22 15
A = NAME OF OUTPUT MATRIX	WR22 16
N = NUMBER OF ROWS IN A	WR22 17
M = NUMBER OF COLUMNS IN A	WR22 18
LINS = NUMBER OF PRINT LINES ON THE PAGE (USUALLY 60)	WR22 19
IPOS = NUMBER OF PRINT POSITIONS ACROSS THE PAGE (132)	WR22 20
ISP = LINE SPACING CODE, 1 SINGLE SPACE, 2 DOUBLE SPACE	WR22 21
3 SINGLE SPACE, NEW PAGE, 4 DOUBLE SPACE, NEW PAGE	WR22 22
NO = N DIMENSIONED SIZE OF A	WR22 23
MO = M DIMENSIONED SIZE OF A	WR22 24
	WR22 25
SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED	WR22 26
NONE	WR22 27
	WR22 28
METHOD	WR22 29
	WR22 30
THIS SUBROUTINE CREATES A STANDARD LISTING OF ANY	WR22 31
SIZED ARRAY WITH ANY STORAGE MODE, EACH PAGE IS HEADED WITH	WR22 32
THE CODE NUMBER, DIMENSION AND STORAGE MODE OF THE ARRAY.	WR22 33
EACH COLUMN AND ROW IS ALSO HEADED WITH ITS RESPECTIVE	WR22 34
NUMBER.	WR22 35

C		WR22	36
C	-----	WR22	37
C		WR22	38
	DIMENSION A(MD,MD)	WR22	39
CDC	DIMENSION PAR(2)	WR22	40
1	FORMAT(/,5X, A8,1X,F7.3,4X,I3,5H ROWS,4X,I3,8H COLUMNS, * 4X,4X,5HPART, I2)	WR22	41
2	FORMAT(1X,10HROW/COLUMN,10(1X,I3,8X))	WR22	43
3	FORMAT(1H)	WR22	44
4	FORMAT(1H ,17,10G12.5)	WR22	45
5	FORMAT(1H0,17,10G12.5)	WR22	46
6	FORMAT (1H1)	WR22	47
	J = 1	WR22	48
C		WR22	49
C	WRITE HEADING	WR22	50
C		WR22	51
	NEND = IPDS/12=1	WR22	52
	LEND = (LINS/(MOD(ISP=1,2)+1))=2	WR22	53
	IPAGE = 1	WR22	54
10	LSTRT = 1	WR22	55
20	IF (ISP.GE.3) WRITE (6,6)	WR22	56
	WRITE(6,1)PAR,VAL,N,M,IPAGE	WR22	57
	JNT = J+NEND=1	WR22	58
	IPAGE = IPAGE+1	WR22	59
31	IF (JNT=M) 33,33,32	WR22	60
32	JNT = M	WR22	61
33	CONTINUE	WR22	62
	WRITE(6,2)(JCUR,JCUR=J,JNT)	WR22	63
40	LTEND = LSTRT+LEND=1	WR22	64
	DO 55 L=LSTRT,LTEND	WR22	65
C		WR22	66
C	FORM OUTPUT ROW LINE	WR22	67
C		WR22	68
	DO 55 K=1,NEND	WR22	69
	KK = K+J=1	WR22	70
	JT = J+K=1	WR22	71
C		WR22	72
C	CHECK IF LAST COLUMN. IF YES GO TO 60	WR22	73
C		WR22	74
	IF (JT=M) 55,60,60	WR22	75
55	CONTINUE	WR22	76
C		WR22	77
C	END OF LINE, NOW WRITE	WR22	78
C		WR22	79
60	IF (MOD(ISP=1,2)) 65,65,70	WR22	80
65	WRITE(6,4)L,(A(L,J),J=J,KK)	WR22	81
	GO TO 75	WR22	82
70	WRITE(6,5)L,(A(L,J),J=J,KK)	WR22	83
C		WR22	84
C	IF END OF ROWS, GO CHECK COLUMNS	WR22	85
C		WR22	86
75	IF (N=L) 85,85,80	WR22	87
80	CONTINUE	WR22	88
C		WR22	89
C	END OF PAGE, NOW CHECK FOR MORE OUTPUT	WR22	90
C		WR22	91
	LSTRT = LSTRT+LEND	WR22	92
	GO TO 20	WR22	93
C		WR22	94
C	END OF COLUMNS, THEN RETURN	WR22	95
85	IF(JT=M) 90,95,95	WR22	96
90	J = JT+1	WR22	97
	GO TO 10	WR22	98
95	RETURN	WR22	99
	END	WR22	100

```

SUBROUTINE NEWRAD
CDC OVERLAY (LAB,1,4)
CDC PROGRAM HEAD
C
C REVISE BODY (FUSELAGE) MERIDIAN LINE SPACING
C BODY DEFINITION OPTIONS FOR EACH SEGMENT:
C J2TEST = 1, CIRCULAR FUSELAGE WITH NO BODY CAMBER
C           = 2, CIRCULAR FUSELAGE WITH BODY CAMBER
C           = 3, ARBITRARY Y,Z CROSS SECTION
C KRADX = 0, USE KRADX MERIDIAN ANGLES
C         < 0, READ KRADX MERIDIAN ANGLES
C         > 0, GENERATE KRADX EQUAL SPACING MERIDIAN ANGLES
C           TOTAL NUMBER OF ANGLES MUST BE LESS THAN 21.
C IXZSYM = 0, SYMMETRIC GEOMETRY AND LOADS ASSUMED
C         = 1, GENERATE FULL SYMMETRIC CONFIGURATION
C         = -1, READ FULL CONFIGURATION (2*KRADX=1 VALUES)
C
COMMON /J2TEST/ IZ1(8)
1 J0,J1,J2,J3,J4,J5,J6,NWAF,KAAFOR,NFUS,NRADX(4),NFORX(4)
2 NP,NPOR,NFINOR,NCAN,NCANOR,J2TEST,NW
3 IZ2(34),IPRT(5),IXZSYM
COMMON /BLOCK/ BLOCK(7500)
COMMON /POINT / ARRAY(6000)
COMMON /EACOM/ K1,KWAF,KAAFOR,KRADX(4),KFORX(4),KFUS,MAX,K4,K5
1 KF(6),KAN(6),KFINOR(6),KANOR(6),KOL,NCPT,LOCPT(20),XCPT(20)
C
DIMENSION XFUS(30,4),ZFUS(30,4),ZF(30,30),FUSRAD(30,4),
1 SFUS(30,30,8),ANSIN(30),ANCOS(30),PHIN(30),PHIK(30),XR(30),
2 YF(30,50),YF(30),ZF(30),FUSAZ(30,4)
C
EQUIVALENCE (XFUS(1,1),BLOCK(1)), (ZFUS(1,1),BLOCK(121))
* (SFUS(1,1,1),BLOCK(241)), (FUSRAD(1,1),BLOCK(361))
* (FUSAZ(1,1),BLOCK(481))
EQUIVALENCE (YF(1,1),ARRAY(1)), (ZF(1,1),ARRAY(1801))
* (XR(1),ARRAY(3601)), (ANSIN(1),ARRAY(3661))
* (ANCOS(1),ARRAY(3691)), (PHIN(1),ARRAY(3721))
* (PHIK(1),ARRAY(3751))
LOGICAL NEWPHI
C
XIN(X1,Y1,X2,Y2,Y)=X1+(X2-X1)*(Y-Y1)/(Y2-Y1)
C
NEWPHI=.FALSE.
EPS=1.E-6
EP2=EPS*EPS
C
M = AXIAL STATION NUMBER
N=0
KFUS=NFUS
KTEST=0
RADD=1./57.2957795
REWIND 10
DO 110 NFUS=1,NFUS
KRAD=NRADX/NFU)
KRAD=KRADX*(PI)
C
C J2TEST = 3 AND KRAD = 0 INDICATE AN ARBITRARY FUSELAGE WITH
C MERIDIAN LINES DEFINED BY READ IN THE GEOMETRY INPUT
C KTEST = ARBITRARY BODY INDICATOR: 0=CTO, 1=ARBITRARY
C
IF (J2TEST.EQ.3.AND.KRAD.EQ.0) KTEST=1
IF (KRAD.EQ.0) KRAD=360
IF (KRAD.GT.201) GO TO 130
IF (IXZSYM.NE.0 .AND. (2*KRAD=1).GT.30) GO TO 130
IF (KRAD.LT.0) NEWPHI=.TRUE.

```

```

      KRAD=IARS(KRAD)
      KRADX(NFU)=KRAD
      NFUSOR=NFUR*(NFU)
      FANG=FLOAT(2*(KRAD=1))
      DELE=6.2831853/FANG
C
C READ NEW MERIDIAN ANGLES FOR SYMMETRIC HALF
C
      IF (NEWPHI) READ (5,160) (PHIK(K),K=1,KRAD)
      IF (NEWPHI .AND. IPRT(1).GT.0) WRITE(6,190) NFU,(PHIK(K),K=1,KRAD)
      DO 30 K=1,KRAD
      IF (.NOT. NEWPHI) PHIR=PHIK(K)*RADD
      IF (.NOT. NEWPHI) PHIR=DELE*FLOAT(K=1)
20  PHIK(K)=PHIR
      IF (J2TEST.EQ.4) GO TO 30
      PHIR4=PHIR+4.712389
      ANSIN(K)=SIN(PHIR4)
      A*COS(K)=COS(PHIR4)
30  CONTINUE
      KY=1+(NFU-1)*2
      KZ=KY+1
C
C COMPUTE INTERMEDIATE VALUES AROUND CIRCUMFERENCE -----
C      MAXIAL STATION INDEX
      DO 100 N=1,NFUSOR
      M=M+1
      IF (M.GT.60) GO TO 120
      XR(N)=XFUS(N,NFU)
      IF (J2TEST.EQ.3) GO TO 50
C
C CASE 1, COMPUTE SECTION Y + Z COORDINATES FOR CIRCULAR/ELLIPTIC BODY
C
      HY=FUORAD(N,NFU)
      AZ=FUOAZ(N,NFU)
      CAM=ZFUS(N,NFU)
      DO 40 K=1,KRAD
      RAD=0.0
      IF (HY.NE.0.)
      * RAD=1.0/SQRT((ANCOS(K)/HY)**2+(ANSIN(K)/AZ)**2)
      YR(N,K)=RAD*ANCOS(K)
      ZR(N,K)=RAD*ANSIN(K)+CAM
40  CONTINUE
      GO TO 100
C
C CASE2, COMPUTE SECTION Y AND Z ORDINATES FOR NONCIRCULAR BODY
C BY LINEAR INTERPOLATION
C      K,NN=CIRCUMFERENTIAL STATION INDICES
C
50  KI=2
      PHIN(1)=0.
      YR(N,1)=SFUS(1,N,KY)
      ZR(N,1)=SFUS(1,N,KZ)
      YF(1)=YR(N,1)
      ZF(1)=ZR(N,1)
      ZC=(SFUS(1,N,KZ)+SFUS(NRAD,N,KZ))/2.
      DO 90 NN=2,NRAD
      IF (KTEST.EQ.1) GO TO 80
      YF(NN)=SFUS(NN,N,KY)
      ZF(NN)=SFUS(NN,N,KZ)-ZC
      NMI=NN-1
      IF (YF(NN).EQ.0. .AND. ZF(NN).EQ.0.) GO TO 80
      IF (ABS(YF(NN)).LE.EP2) YF(NN)=0.
      PHIN(NN)=ATAN2(YF(NN),-ZF(NN))

```

```

WB23 64
WB23 65
WB23 66
WB23 67
WB23 68
WB23 69
WB23 70
WB23 71
WB23 72
WB23 73
WB23 74
WB23 75
WB23 76
WB23 77
WB23 7A
WB23 79
WB23 80
WB23 81
WB23 82
WB23 83
WB23 84
WB23 85
WB23 86
WB23 87
WB23 8A
WB23 89
WB23 90
WB23 91
WB23 92
WB23 93
WB23 94
WB23 95
WB23 96
WB23 97
WB23 98
WB23 99
WB23 100
WB23 101
WB23 102
WB23 103
WB23 104
WB23 105
WB23 106
WB23 107
WB23 108
WB23 109
WB23 110
WB23 111
WB23 112
WB23 113
WB23 114
WB23 115
WB23 116
WB23 117
WB23 118
WB23 119
WB23 120
WB23 121
WB23 122
WB23 123
WB23 124
WB23 125
WB23 126

```

```

      DO 60 K=KI,KRAD                                *R23 127
      IF (PHIK(K).GT.PHIN(NN)) GO TO 70              *R23 128
      YR(N,K)=YI*(YF(NM1),PHIN(NM1),YF(NN),PHIN(NN),PHIK(K)) *R23 129
      ZR(N,K)=ZI*(ZF(NM1),PHIN(NM1),ZF(NN),PHIN(NN),PHIK(K))+ZC *R23 131
60  CONTINUE                                          *R23 131
70  KTK                                            *R23 132
      GO TO 40                                       *R23 133
C
C CASE 3, USE INPUT Y,Z VALUES                      *R23 135
C
80  YR(N,NK)=SFUS(NN,N,KY)                          *R23 137
      ZR(N,NK)=SFUS(NN,N,KZ)                          *R23 138
90  CONTINUE                                          *R23 139
100 CONTINUE                                          *R23 141
C
C GENERATE SYMMETRIC HALF OF BODY FOR IXZSYM=1 ----- *R23 142
C
      IF (IXZSYM.LE.0) GO TO 106                     *R23 143
      DO 104 I=1,NFUSIR                               *R23 144
      K=KRAD                                           *R23 145
      DO 104 J=2,KRAD                                  *R23 147
      K=K+1                                             *R23 148
      IK=KRAD-I+1                                       *R23 149
      YR(N,K)=YR(N,IK)                                  *R23 150
      ZR(N,K)=ZR(N,IK)                                  *R23 151
104  CONTINUE                                          *R23 152
      KRAD=K                                             *R23 153
      KPAIX(NFI)=KRAD                                   *R23 154
106  CONTINUE                                          *R23 155
      MAX=M                                             *R23 156
      WRITE (10),YR,YZ,ZH                               *R23 157
110  CONTINUE                                          *R23 158
      RETURN                                             *R23 159
120  WRITE (6,140)                                     *R23 160
      STOP 120                                          *R23 161
130  WRITE (5,170)                                     *R23 162
      STOP 130                                          *R23 163
150  FORMAT (10F7,0)                                   *R23 164
170  FORMAT (40H ERROR = BODY HAS MORE THAN 20 MERIDIANS *R23 165
      * ,70X,12H** N=NRAD ** )                       *R23 166
180  FORMAT (40H ERROR = BODY HAS MORE THAN 60 AXIAL STATIONS *R23 167
      * ,65X,12H** N=NRAD ** )                       *R23 168
190  FORMAT(7H NFI=,I5,7H PHIK=,10G12,5,2(/7X,10G12,5)) *R23 169
      END                                              *R23 170

```

```

      SUBROUTINE PANEL(IP,IQ,J,K,L,AP,AP)            *R24 1
C
C CALCULATE PANEL GEOMETRY (BASED ON THE HYPERSONIC ARBITRARY BODY *R24 2
C PROGRAM OF A. E. GENTRY) FOR NON-PLANAR PANELS *R24 3
C
C COMMON /POINT/ XPT(500),YPT(500),ZPT(500),THET(500),DELTA(500), *R24 4
1  XC(30,20),YC(30,20),ZC(30,20),DUM(1200) *R24 7
C COMMON *R24 8
      ZI(5000),ZJ(50,20) *R24 8
      DIMENSION XIN(4),YIN(4),ZIN(4),XI(4),ETA(4) *R24 9
      REAL X,Y,Z *R24 10
C
C REORDER THE PANEL CORNER POINTS TO CORRESPOND TO GENTRY CONVENTION *R24 11
C *R24 12
C *R24 13

```


	EPS=1.E=6	WR24	14
	J1=J=1	WR24	15
	K1=K=1	WR24	16
	XIN(1)=XC(J1,K1)	WR24	17
	XIN(2)=XC(J,K1)	WR24	18
	XIN(3)=XC(J,K)	WR24	19
	XIN(4)=XC(J1,K)	WR24	20
	YIN(1)=YC(J1,K1)	WR24	21
	YIN(2)=YC(J,K1)	WR24	22
	YIN(3)=YC(J,K)	WR24	23
	YIN(4)=YC(J1,K)	WR24	24
	IF (L.EQ.1) GO TO 10	WR24	25
	ZIN(1)=ZC(J1,K1)	WR24	26
	ZIN(2)=ZC(J,K1)	WR24	27
	ZIN(3)=ZC(J,K)	WR24	28
	ZIN(4)=ZC(J1,K)	WR24	29
	GO TO 20	WR24	30
10	ZIN(1)=ZU(J1,K1)	WR24	31
	ZIN(2)=ZU(J,K1)	WR24	32
	ZIN(3)=ZU(J,K)	WR24	33
	ZIN(4)=ZU(J1,K)	WR24	34
C		WR24	35
C	FORM DIAGONAL VECTORS	WR24	36
C	FORM VECTOR CROSS PRODUCT, N = T2 X T1	WR24	37
C		WR24	38
20	T1X=XIN(3)-XIN(1)	WR24	39
	T2X=XIN(4)-XIN(2)	WR24	40
	IF (IP.EQ.1) T2X=-T2X	WR24	41
	T1Y=YIN(3)-YIN(1)	WR24	42
	T2Y=YIN(4)-YIN(2)	WR24	43
	IF (IP.EQ.1) T2Y=-T2Y	WR24	44
	T1Z=ZIN(3)-ZIN(1)	WR24	45
	T2Z=ZIN(4)-ZIN(2)	WR24	46
	IF (IP.EQ.1) T2Z=-T2Z	WR24	47
	NX=T2Y*T1Z-T1Y*T2Z	WR24	48
	NY=T1X*T2Z-T2X*T1Z	WR24	49
	NZ=T2X*T1Y-T1X*T2Y	WR24	50
	IF (ABS(NX).LE.EPS) NX=0.	WR24	51
	IF (ABS(NY).LE.EPS) NY=0.	WR24	52
	IF (ABS(NZ).LE.EPS) NZ=0.	WR24	53
	VN=SQRT(NX*NX+NY*NY+NZ*NZ)	WR24	54
	IF (VN.EQ.0.) GO TO 30	WR24	55
C		WR24	56
C	FORM UNIT NORMAL VECTOR, THEN COMPUTE AVERAGE POINT	WR24	57
C		WR24	58
	VND=1./VN	WR24	59
	NX=NX*VND	WR24	60
	NY=NY*VND	WR24	61
	NZ=NZ*VND	WR24	62
30	AVX=.25*(XIN(1)+XIN(2)+XIN(3)+XIN(4))	WR24	63
	AVY=.25*(YIN(1)+YIN(2)+YIN(3)+YIN(4))	WR24	64
	AVZ=.25*(ZIN(1)+ZIN(2)+ZIN(3)+ZIN(4))	WR24	65
C		WR24	66
C	COMPUTE PROJECTION DISTANCE	WR24	67
C		WR24	68
	DENX*(AVX-XIN(1))+NY*(AVY-YIN(1))+NZ*(AVZ-ZIN(1))	WR24	69
	T=SQRT(T1X*T1X+T1Y*T1Y+T1Z*T1Z)	WR24	70
	IF (T.EQ.0.) GO TO 40	WR24	71
	TOR=1./T	WR24	72
	T1X=T1X*TOR	WR24	73
	T1Y=T1Y*TOR	WR24	74
	T1Z=T1Z*TOR	WR24	75
40	T2X=NY*T1Z-NZ*T1Y	WR24	76

	T2Y=NZ+T1X-AX*T1Z	*R24	77
	T2Z=NX+T1Y-NY*T1X	*R24	78
C		*R24	79
C	COMPUTE COORDINATES OF CORNER POINTS IN REFERENCE COORDINATE SYSTEM	*R24	80
C	TRANSFORM CORNER POINT TO ELEMENT COORDINATE SYSTEM (XI,ETA)	*R24	81
C	WITH AVERAGE POINT AS ORIGIN	*R24	82
C		*R24	83
	DO 50 N=1,4	*R24	84
	XPA=XI*(N)+XX*D	*R24	85
	YPA=YI*(N)+Y*D	*R24	86
	ZPA=ZI*(N)+Z*D	*R24	87
	DE=D	*R24	88
	XDIF=XPA-AXX	*R24	89
	YDIF=YPA-AYY	*R24	90
	ZDIF=ZPA-AVZ	*R24	91
	XI(N)=T1X*XDIF+T1Y*YDIF+T1Z*ZDIF	*R24	92
	ETA(N)=T2X*XDIF+T2Y*YDIF+T2Z*ZDIF	*R24	93
50	CONTINUE	*R24	94
C		*R24	95
C	COMPUTE CENTROID	*R24	96
C	OBTAIN CORNER POINTS IN SYSTEM WITH CENTROID AS ORIGIN	*R24	97
C		*R24	98
	ETACK=ETA(2)-ETA(4)	*R24	99
	IF (ETACK.EQ.0.) GO TO 60	*R24	100
	XI0=0.	*R24	101
	GO TO 70	*R24	102
60	XI0=(XI(4)*(ETA(1)-ETA(2))+XI(2)*(ETA(4)-ETA(1)))/(3.*ETACK)	*R24	103
70	ETA0=-ETA(1)/3.	*R24	104
	XI(1)=XI(1)-XI0	*R24	105
	XI(2)=XI(2)-XI0	*R24	106
	XI(3)=XI(3)-XI0	*R24	107
	XI(4)=XI(4)-XI0	*R24	108
	ETA(1)=ETA(1)-ETA0	*R24	109
	ETA(2)=ETA(2)-ETA0	*R24	110
	ETA(3)=ETA(3)-ETA0	*R24	111
	ETA(4)=ETA(4)-ETA0	*R24	112
C		*R24	113
C	TRANSFORM CENTROID TO REFERENCE COORDINATE SYSTEM	*R24	114
C		*R24	115
	XPT(NP)=AVX+T1X*XI0+T2X+ETA0	*R24	116
	YPT(NP)=AVY+T1Y*XI0+T2Y+ETA0	*R24	117
	ZPT(NP)=AVZ+T1Z*XI0+T2Z+ETA0	*R24	118
C		*R24	119
C	COMPUTE PANEL INCIDENCE AND INCLINATION ANGLE	*R24	120
C	COMPUTE PANEL AREA	*R24	121
C		*R24	122
	DELTA(NP)=0.	*R24	123
	THET(NP)=0.	*R24	124
	R=SQRT(NY**2+Z**2)	*R24	125
	IF (L.EQ.0) GO TO 90	*R24	126
	SL=-1.	*R24	127
	IF (L.EQ.2) SL=1.	*R24	128
C		*R24	129
C	DELTA = ANGLE BETWEEN THE Y-AXIS AND THE LINE OF INTERSECTION	*R24	130
C	WITH THE PANEL OF A PLANE PASSING THROUGH THE Y-AXIS AND THE	*R24	131
C	PERPENDICULAR TO THE PANEL.	*R24	132
	IF (R1.EQ.0.) DELTA(NP)=ATAN2(SL*RX,RM)	*R24	133
	SP=PL*AT(1)-2*IP)	*R24	134
	IF (ABS(SP).LE.(EPS*EPS)) SP=0.	*R24	135
	IF (IQ.EQ.1) GO TO 80	*R24	136
C		*R24	137
C	THET = ANGLE BETWEEN THE Y-AXIS AND THE LINE OF INTERSECTION	*R24	138
C		*R24	139

C	OF THE PANEL WITH THE Y-Z PLANE.	WB24	140
	IF (NY.EQ.0.) THET(IP)=ATAN2(SP*NY,-SP*NZ)	WB24	141
	GO TO 100	WB24	142
80	IF (NZ.NE.0.) THET(IP)=ATAN2(-SP*NZ,SP*NY)	WB24	143
	GO TO 100	WB24	144
90	IF (NX.NE.0.) DELTA(IP)=ATAN2(-NX,NY)	WB24	145
	IF (NY.EQ.0.,AND,NZ.EQ.0.) GO TO 100	WB24	146
	THET(IP)=ATAN2(-NY,NZ)	WB24	147
100	AP=5*(XI(3)-XI(1))*ETACK	WB24	148
	IF (IP.EQ.1) AP=AP	WB24	149
	RETURN	WB24	150
	END	WB24	151

	SUBROUTINE PARTIN	WB25	1
C		WB25	2
C	FOR WING-BODY COMBINATIONS, INVERT THE MATRIX PARTITIONS (PROVIDED	WB25	3
C	THE ORDER DOES NOT EXCEED 60).	WB25	4
C		WB25	5
C	FOR ISOLATED WINGS OR BODIES, ALSO SOLVE THE BOUNDARY CONDITION	WB25	6
C	EQUATIONS AND DETERMINE THE WING VORTEX STRENGTHS OR BODY SOURCE	WB25	7
C	STRENGTHS.	WB25	8
C		WB25	9
	COMMON NW(600),NB(600),NT(600),A(60,60),Z3(300),GW(600),	WB25	10
	1 GR(600),GT(600)	WB25	11
	COMMON /PARAM / NBODY,NWING,NTAIL,LHC,THK,XMACH,ALPHA,BETA,ALPHAC	WB25	12
	1 ,PHIP,REFA,REFB,REFC,REFD,REFL,REFX,REFZ	WB25	13
	COMMON /POINT / ARRAY(6000)	WB25	14
	DIMENSION D(60,60)	WB25	15
	EQUIVALENCE (D(1,1),ARRAY(1))	WB25	16
	REAL NW,NB,NT	WB25	17
C		WB25	18
	CALL CPUTIM(TIME,DT,1)	WB25	19
	NDIM=60	WB25	20
	REWIND 9	WB25	21
	NPANEL=NBODY+NWING	WB25	22
	IF (NWING.EQ.0.OR.NBODY.EQ.0) GO TO 50	WB25	23
C		WB25	24
C	INVERT DIAGONAL BLOCKS -----	WB25	25
C	INVERT BODY INFLUENCE MATRIX AND WRITE ON TAPE 10	WB25	26
C		WB25	27
	REWIND 10	WB25	28
	DO 10 I=1,NBODY	WB25	29
	READ (9) (D(I,J),J=1,NBODY)	WB25	30
10	CONTINUE	WB25	31
	CALL INVERT(D,NBODY,NDIM)	WB25	32
	WRITE (10) D	WB25	33
C		WB25	34
C	READ PAST BODY/WING INFLUENCE MATRICES	WB25	35
CB	DO 20 I=1,NBODY	WB25	36
CB	READ (9) (D(I,J),J=1,NWING)	WB25	37
CB20	CONTINUE	WB25	38
CB	DO 30 I=1,NWING	WB25	39
CB	READ (9) (D(I,J),J=1,NBODY)	WB25	40
CB30	CONTINUE	WB25	41
CB	DO 40 I=1,NWING	WB25	42
CB	READ (9) (D(I,J),J=1,NWING)	WB25	43
CB40	CONTINUE	WB25	44
CB	CALL INVERT(D,NWING,NDIM)	WB25	45
CB	WRITE (10) D	WB25	46
CB	REWIND 9	WB25	47

```

      REWIND 10
      GO TO 100
C
C SOLVE ENTIRE MATRIX IF NPANEL)61 = ONLY WINGS OR ROOTS -----
C
50  DO 60 I=1, NPANEL
      READ (9) (A(I,J),J=1, NPANEL)
60  CONTINUE
      REWIND 9
      CALL INVERT(A, NPANEL, NDIM)
C
C SUBSTITUTE WING BOUNDARY CONDITION AND COMPUTE STRENGTHS = GW
C
      IF (NWING, EQ, 0) GO TO 80
C4  DO 70 I=1, NWING
C4  GW(I)=0.
C4  DO 70 J=1, NWING
C4  GW(I)=GW(I)+A(I,J)*NW(J)
C470 CONTINUE
      GO TO 100
C
C SUBSTITUTE BODY BOUNDARY CONDITION AND COMPUTE STRENGTHS = GB
C
50  DO 90 I=1, NBODY
      GB(I)=0.
      DO 90 J=1, NBODY
      GB(I)=GB(I)+A(I,J)*NB(J)
90  CONTINUE
100 REWIND 9
      CALL CPUTIM(TIME, DT, 1)
      WRITE(6, 110) TIME, DT
110 FORMAT(/10X, 18HEND PART II.  TIME=F10.4, 5X, 4HDT=F10.4)
      RETURN
      END

```

```

      *R25  48
      *R25  49
      *R25  50
      *R25  51
      *R25  52
      *R25  53
      *R25  54
      *R25  55
      *R25  56
      *R25  57
      *R25  58
      *R25  59
      *R25  60
      *R25  61
      *R25  62
      *R25  63
      *R25  64
      *R25  65
      *R25  66
      *R25  67
      *R25  68
      *R25  69
      *R25  70
      *R25  71
      *R25  72
      *R25  73
      *R25  74
      *R25  75
      *R25  76
      *R25  77
      *R25  78
      *R25  79
      *R25  80
      *R25  81

```

```

SUBROUTINE PLOTA2 (X, Y, IOPT, NP, NDP, NC, LWID, LENG)
-----
C
C SUBROUTINE PLOTA2
C
C PURPOSE
C ROUTINE TO GENERATE A SINGLE CHARACTER PLOT OF NC SIMULTANEOUS
C CURVES OF Y VERSUS X. THE MAIN CURVE IS STORED COLUMNWISE IN
C ARRAYS X(I,J) AND Y(I,J) AND MAY HAVE A VARIABLE NUMBER OF
C POINTS, NP(J).
C
C CALLING FORMAT
C CALL PLOTA2 (X, Y, IOPT, NP, NDP, NC, LWID, LENG)
C
C PARAMETERS
C NAME TYPE I/O/S UNIT DESCRIPTION
C
C X, Y R I (NDP, NC) ORDINATE + ABSCISSA ARRAYS
C IOPT I I NONE OPTION FOR TYPE OF PAGE SCALING
C 1. USER SPECIFIES SCALE LIMITS
C 2. INTERNAL AUTOMATIC BEST SCALING
C 3. AUTOMATIC TRIP SHAPE SCALING, SEE
C NOTE: 0.6*LWID/LENG = XDIFF/YDIFF
C 4. USE MAX AND MIN VALUES OF DATA

```

```

      *R26  1
      *R26  2
      *R26  3
      *R26  4
      *R26  5
      *R26  6
      *R26  7
      *R26  8
      *R26  9
      *R26  10
      *R26  11
      *R26  12
      *R26  13
      *R26  14
      *R26  15
      *R26  16
      *R26  17
      *R26  18
      *R26  19
      *R26  20
      *R26  21
      *R26  22
      *R26  23
      *R26  24
      *R26  25

```

```

C          5, INPUT XMAX,YMIN# AUTO Y-SCALING      WR26 26
C          6, INPUT YMAX,YMIN# AUTO X-SCALING      WR26 27
C          NP      I      I      NONE VECTOR OF NUMBER OF POINTS IN J*TH WR26 28
C          CURVE, IF NDP=1, NP IS ASSUMED EQUAL WR26 29
C          TO 1 FOR ALL CURVES.                    WR26 30
C          NDP      I      I      NONE FIRST DIMENSION OF ARRAYS *X,*Y IN WR26 31
C          CALLING ROUTINE                          WR26 32
C          NC      I      I      NONE NUMBER OF SIMULTANEOUS PLOTS, WR26 33
C          IF NC#41, CHARACTER SET REPEATS,        WR26 34
C          L*TD     I      I      NONE WIDTH OF PLOTTED REGIONS AT 10 WR26 35
C          CHARACTERS/INCH, NORMALLY=100,         WR26 36
C          FOR CRT OR T.I. TERMINALS=50.          WR26 37
C          MAXIMUM DIMENSIONED = 100.             WR26 38
C          LENG     I      I      NONE NUMBER OF LINES IN PLOTTED REGION WR26 39
C          NORMALLY=50 AT 6 LINES/INCH#          WR26 40
C          FOR 8.5" PAPER=40.                      WR26 41
C                                                  WR26 42
C          USER SUPPLIED COMMON BLOCKS            WR26 43
C          IOPT =1,5,6: /RSCALE/ XMAX,XMIN,YMAX,YMIN WR26 44
C                                                  WR26 45
C          COMMON /RSCALE/                          WR26 46
C          NAME     TYPE  I/O/S  DIM  DESCRIPTION                WR26 47
C          XMAX     R     I/O     NONE  MAXIMUM X SCALE VALUE ACROSS PAGE WR26 48
C          XMIN     R     I/O     NONE  MINIMUM X SCALE VALUE ACROSS PAGE WR26 49
C          YMAX     R     I/O     NONE  MAXIMUM Y SCALE VALUE AT TOP OF PAGE WR26 51
C          YMIN     R     I/O     NONE  MINIMUM Y SCALE VALUE DOWN PAGE WR26 52
C          EXTERNAL REFERENCES                      WR26 53
C          PLOTA SUBROUTINES: PLOTA7, PLOTA8      WR26 54
C                                                  WR26 55
C          AUTHOR                                    WR26 56
C          JOSEPH MULLEN JR., NIELSEN ENGINEERING + RESEARCH, INC. WR26 57
C          DATED: DECEMBER, 1976                  WR26 58
C                                                  WR26 59
C          ----- WR26 60
C          DIMENSION X(NDP,NC),Y(NDP,NC),XPRINT(7),NP(NC),FMT(6) WR26 61
C          INTEGER SYMBOL(40)                      WR26 62
C          COMMON /RPLTA1/ NXPR,NYPR,IXAXIS,IXAXIS,IOFFX,IOFFY,LLINE WR26 63
C          COMMON /RPLTA2/ LINE(103)              WR26 64
C          COMMON /RSCALE/ XMAX,XMIN,YMAX,YMIN    WR26 65
C          DATA FMT/4H(7X,4H,616,4H,4,6,4H( 4X,4HG(16,,4H4)) / WR26 66
C          DATA SYMBOL/1H*,1H+,1H-,1H.,1H0,1H1,1H2,1H3,1H4,1H5,1H6,1H7 WR26 67
C          *,1H8,1H9,1HA,1HB,1HC,1HD,1HE,1HF,1HG,1HH,1HT,1HJ,1HK,1HL,1HM WR26 68
C          *,1HN,1HO,1HP,1HQ,1HR,1HS,1HT,1HU,1HV,1HW,1HX,1HY,1HZ/ WR26 69
C          FIND MAX AND MIN OF X (ORDINATE) AND Y (ABSCISSA) WR26 70
C                                                  WR26 71
C          NPJ = 1                                  WR26 72
C          IF (IOPT,LT,1) IOPT=2                    WR26 73
C          IF (IOPT,EG,1) GO TO 40                  WR26 74
C          IF (IOPT,EG,5) GO TO 60                  WR26 75
C          XMAX = X(1,1)                             WR26 76
C          XMIN = X(1,1)                             WR26 77
C          DO 50 J=1,NC                              WR26 78
C          IF (NDP,GT,1) NPJ = NP(J)                WR26 79
C          IF (NPJ,LT,1) GO TO 50                    WR26 80
C          DO 40 I=1,NPJ                              WR26 81
C          XMAX = AMAX1(X(I,J),XMAX)                 WR26 82
C          XMIN = AMIN1(X(I,J),XMIN)                 WR26 83
C          CONTINUE                                  WR26 84
C          IF (IOPT,EG,6) GO TO 40                   WR26 85
C          40                                         WR26 86
C          50                                         WR26 87
C          50                                         WR26 88

```

C		NR26 89
60	YMAX = Y(1,1)	NR26 90
	YMIN = Y(1,1)	NR26 91
	DO 70 J=1,NC	NR26 92
	IF (NRP,GT,1) NPJ = NP(J)	NR26 93
	IF (NPJ,LT,1) GO TO 70	NR26 94
	DO 65 I=1, NPJ	NR26 95
	YMAX = AMAX1(Y(I,J),YMAX)	NR26 96
55	YMIN = AMIN1(Y(I,J),YMIN)	NR26 97
70	CONTINUE	NR26 98
C		NR26 99
C	DETERMINE SCALING AND ROUND OFF MAX AND MIN VALUES AND LOCATE	NR26 100
C	X- AND Y-AXES.	NR26 101
C		NR26 102
80	CALL PLOTAB(OX,DY,FNT,LWID,LENG,IUPT)	NR26 103
	NRROWS = LENG+1	NR26 104
C		NR26 105
C	INITIALIZE PRINTING BANDWIDTH	NR26 106
C		NR26 107
	YLOW = YMAX+0.5*DY	NR26 108
	YHID = YMAX	NR26 109
	YUP = YMAX+0.5*DY	NR26 110
C		NR26 111
C	FORM UPPER BOUNDARY	NR26 112
C		NR26 113
	CALL PLOTAT (LINE,1,1)	NR26 114
	WRITE(6,1) (LINE(I),I=1,LLINE)	NR26 115
	DO 230 L=1,NRROWS	NR26 116
C		NR26 117
C	INITIALIZE BLANK ROW OR X-AXIS	NR26 118
C		NR26 119
	IF (L,NE,IXAXIS) CALL PLOTAT (LINE,L-IOFFX,2)	NR26 120
	IF (L,ER,IXAXIS) CALL PLOTAT (LINE,L-IOFFX,1)	NR26 121
C		NR26 122
C	TEST FOR DATA IN L*TH ROW	NR26 123
C		NR26 124
	DO 210 J=1,NC	NR26 125
	JSYM = MOD(J-1,40)+1	NR26 126
	IF (NRP,GT,1) NPJ = NP(J)	NR26 127
	IF (NPJ,LT,1) GO TO 210	NR26 128
	DO 210 I=1, NPJ	NR26 129
	IF (Y(I,J),GT,YUP) GO TO 210	NR26 130
	IF (Y(I,J),LE,YLOW) GO TO 210	NR26 131
C		NR26 132
C	FIND X LOCATION OF POINT = CHECK IF WITHIN SIDE BOUNDS	NR26 133
C		NR26 134
	NDX = IFIX((Y(I,J)-YMIN)/DY+0.5)*2	NR26 135
	IF (NDX,LE,1) GO TO 210	NR26 136
	IF (NDX,GE,LLINE) GO TO 210	NR26 137
	LINE(NDX) = SYMBOL(JSYM)	NR26 138
210	CONTINUE	NR26 139
C		NR26 140
C	PRINT ROW OF OUTPUT = TEST TO WRITE SCALES	NR26 141
C		NR26 142
	IMOD = MOD(L-IOFFX-1,NYPR)	NR26 143
	IF (IMOD,EQ,0) WRITE (6,2) YHID,(LINE(I),I=1,LLINE)	NR26 144
	IF (IMOD,NE,0) WRITE (6,3) (LINE(I),I=1,LLINE)	NR26 145
C		NR26 146
C	INCREMENT Y-STRIP; REDEFINE YLOW AND YUP	NR26 147
C		NR26 148
	YUP = YHID	NR26 149
	YHID = YHID-DY	NR26 150
	IF (ABS(YHID/DY),LT,0.001) YHID=0.0	NR26 151

```

      YLOW = YLOW*DY
230  CONTINUE
C
C FROM LOWER BOUNDARY
C
      CALL PLOTAT (LINE,1,1)
      WRITE (n,3) (LINE(I),I=1,LINE)
C
C PRINT SCALES
C
      NXP = (LLINE-IGFFY)/NXPR+1
      XPRINT(1) = XMIN+DX*(IIGFFY-2)
      DO 240 I=2,NXP
      XPRINT(I) = XPRINT(I-1)+DX*NXP
      IF (ABS(XPRINT(I)/DX).LT.0.001) XPRINT(I)=0.0
240  CONTINUE
      WRITE(n,FMT) (XPRINT(I),I=1,NXP)
      RETURN
1   FORMAT (1H),14X,103A1)
2   FORMAT (1X,G13.4,1X,103A1)
3   FORMAT (15X,103A1)
      END

```

```

*RB26 152
*RB26 153
*RB26 154
*RB26 155
*RB26 156
*RB26 157
*RB26 158
*RB26 159
*RB26 160
*RB26 161
*RB26 162
*RB26 163
*RB26 164
*RB26 165
*RB26 166
*RB26 167
*RB26 168
*RB26 169
*RB26 170
*RB26 171
*RB26 172
*RB26 173

```

```

SUBROUTINE PLOTAS (X,Y,Z,NP,NOP,NC,THETA,XCG,XP,YP,ISC)
-----
C
C SUBROUTINE PLOTAS
C
C PURPOSE
C ROUTINE TO PERFORM AN ARBITRARY ROTATION IN 3-SPACE OF (X,Y,Z)
C DATA. THE THREE DIMENSIONAL DATA IS REDUCE TO THE (X,Y)
C PROJECTION, XP,YP.
C
C CALLING FORMAT
C CALL PLOTAS (X,Y,Z,NP,NOP,NC,THETA,XCG,XP,YP,ISC)
C
C PARAMETERS
C NAME TYPE I/O/S DIM DESCRIPTION
C
C X,Y,Z R I (NOP,NC) COORDINATE POINT ARRAYS
C NP I I NONE VECTOR OF NUMBER OF POINTS IN J*TH
C CURVE
C NOP I I NONE FIRST DIMENSION OF ARRAY *X,Y,Z* IN
C CALLING ROUTINE
C NC I I NONE NUMBER OF CURVES TO BE TRANSFORMED
C THETA R I (3) ROTATION ANGLES=THETA X,THETA Y,THETA Z
C (DEGREES). ROTATIONS ARE PERFORMED
C IN REVERSE ORDER.
C XCG R I (3) LOCATION OF CENTER OF ROTATION
C XCG = (XCG,YCG,ZCG)
C XP,YP R O (NOP,NC) COORDINATES OF TRANSFORMED POINT
C NOTE: YP,YP MAY BE STORED IN X,Y.
C ISC I I NONE SCALING OPTION
C 1, AUTOMATIC SCALING
C 2, AUTOMATIC SCALING ON ONLY Z
C 3, NO SCALING OF COORDINATES
C 4, INPUT SCALING VECTOR = S
C 5, INPUT XMAX,....,ZMIN = SCALE X,Y,Z
C

```

```

*RB27 1
*RB27 2
*RB27 3
*RB27 4
*RB27 5
*RB27 6
*RB27 7
*RB27 8
*RB27 9
*RB27 10
*RB27 11
*RB27 12
*RB27 13
*RB27 14
*RB27 15
*RB27 16
*RB27 17
*RB27 18
*RB27 19
*RB27 20
*RB27 21
*RB27 22
*RB27 23
*RB27 24
*RB27 25
*RB27 26
*RB27 27
*RB27 28
*RB27 29
*RB27 30
*RB27 31
*RB27 32
*RB27 33
*RB27 34
*RB27 35
*RB27 36

```

```

C      USER SUPPLIED COMMON BLOCKS                                *B27  37
C      ISC =4,5: /BSCAL2/ XMAX,XMIN,YMAX,YMIN,ZMAX,ZMIN,S(3)    *B27  38
C      *B27  39
C      COMMON /BSCAL2/                                           *B27  40
C      NAME      TYPE      I/O/S      DIM      DESCRIPTION                *B27  41
C      *B27  42
C      XMAX      R        I/O      NONE     MAXIMUM OF X DATA VALUES  *B27  43
C      XMIN      R        I/O      NONE     MINIMUM OF X DATA VALUES  *B27  44
C      YMAX      R        I/O      NONE     MAXIMUM OF Y DATA VALUES  *B27  45
C      YMIN      R        I/O      NONE     MINIMUM OF Y DATA VALUES  *B27  46
C      ZMAX      R        I/O      NONE     MAXIMUM OF Z DATA VALUES  *B27  47
C      ZMIN      R        I/O      NONE     MINIMUM OF Z DATA VALUES  *B27  48
C      S          R        I/O      NONE     VECTOR USED FOR RELATIVE SCALING *B27  49
C      OF X,Y,Z COMPONENTS BEFORE ROTATION.                    *B27  50
C      *B27  51
C      AUTHOR                                                *B27  52
C      JOSEPH MULLEN, JR., NIELSEN ENGINEERING + RESEARCH, INC. *B27  53
C      DATED: DECEMBER, 1976                                  *B27  54
C      *B27  55
C      ----- *B27  56
C      DIMENSION X(NDP,NC),Y(NDP,NC),Z(NDP,NC),NP(NC)          *B27  57
C      DIMENSION XP(NDP,NC),YP(NDP,NC),THETA(3),XCG(3)         *B27  58
C      REAL RX(3,3),RY(3,3),RZ(3,3),R(3,3)                   *B27  59
C      COMMON /BSCAL2/XMAX,XMIN,YMAX,YMIN,ZMAX,ZMIN,S(3)      *B27  60
C      DATA RX,RY,RZ/1.0,12*0.0,1.0,12*0.0,1.0/             *B27  61
C      DATA RADDFG/0.0174532926/                              *B27  62
C      NPJ = 1                                                 *B27  63
C      *B27  64
C      BUILD TRANSFORMATION MATRICES                            *B27  65
C      *B27  66
C      COSX = COS(THETA(1)*RADDFG)                             *B27  67
C      SINX = SIN(THETA(1)*RADDFG)                             *B27  68
C      COSY = COS(THETA(2)*RADDFG)                             *B27  69
C      SINY = SIN(THETA(2)*RADDFG)                             *B27  70
C      COSZ = COS(THETA(3)*RADDFG)                             *B27  71
C      SINZ = SIN(THETA(3)*RADDFG)                             *B27  72
C      *B27  73
C      DEFINE X-ROTATION                                        *B27  74
C      *B27  75
C      RX(2,2) = COSX                                          *B27  76
C      RX(2,3) = -SINX                                         *B27  77
C      RX(3,2) = SINX                                          *B27  78
C      RX(3,3) = COSX                                          *B27  79
C      *B27  80
C      DEFINE Y-ROTATION                                        *B27  81
C      *B27  82
C      RY(1,1) = COSY                                          *B27  83
C      RY(1,3) = SINY                                          *B27  84
C      RY(3,1) = -SINY                                         *B27  85
C      RY(3,3) = COSY                                          *B27  86
C      *B27  87
C      DEFINE Z-ROTATION                                        *B27  88
C      *B27  89
C      PZ(1,1) = COSZ                                          *B27  90
C      PZ(1,2) = -SINZ                                         *B27  91
C      PZ(2,1) = SINZ                                          *B27  92
C      PZ(2,2) = COSZ                                          *B27  93
C      *B27  94
C      OBTAIN SCALING = FIND MAXIMA AND MINIMA                 *B27  95
C      *B27  96
C      GO TO (100,100,150,100,150), ISC                       *B27  97
C      *B27  98
100  XMAX = X(1,1)                                             *B27  99
      XMIN = X(1,1)

```


	YMAX = Y(1,1)	WR27 100
	YMIN = Y(1,1)	WR27 101
	ZMAX = Z(1,1)	WR27 102
	ZMIN = Z(1,1)	WR27 103
	DO 120 J=1,NC	WR27 104
	IF (NDP.GT.1) NPJ = NP(J)	WR27 105
	IF (NPJ.LT.1) GO TO 110	WR27 106
	DO 110 I=1,NPJ	WR27 107
	YMAX = AMAX1(XMAX,X(I,J))	WR27 108
	YMIN = AMIN1(XMIN,X(I,J))	WR27 109
	YMAX = AMAX1(YMAX,Y(I,J))	WR27 110
	YMIN = AMIN1(YMIN,Y(I,J))	WR27 111
	ZMAX = AMAX1(ZMAX,Z(I,J))	WR27 112
	ZMIN = AMIN1(ZMIN,Z(I,J))	WR27 113
110	CONTINUE	WR27 114
120	XDIFF = YMAX-XMIN	WR27 115
	YDIFF = YMAX-YMIN	WR27 116
	ZDIFF = ZMAX-ZMIN	WR27 117
C		WR27 118
C	CHOOSE SCALING = ISC=1,5, SCALE X,Y,Z	WR27 119
C		WR27 120
	GO TO (130,140,150,160,130),ISC	WR27 121
130	D = SQRT(XDIFF*XDIFF+YDIFF*YDIFF+ZDIFF*ZDIFF)	WR27 122
	S(1) = D/XDIFF	WR27 123
	S(2) = D/YDIFF	WR27 124
	S(3) = D/ZDIFF	WR27 125
	GO TO 160	WR27 126
C		WR27 127
C	ISC=2, SCALE ONLY Z.	WR27 128
C		WR27 129
140	D = SQRT(XDIFF*XDIFF+YDIFF*YDIFF)	WR27 130
	S(1) = 1.0	WR27 131
	S(2) = 1.0	WR27 132
	S(3) = D/ZDIFF	WR27 133
	GO TO 160	WR27 134
C		WR27 135
C	ISC=3, USE NO SCALING	WR27 136
C		WR27 137
150	S(1) = 1.0	WR27 138
	S(2) = 1.0	WR27 139
	S(3) = 1.0	WR27 140
C		WR27 141
C	COMPUTE GLOBAL TRANSFORMATION: R = RZ*RY*RX*S	WR27 142
C		WR27 143
160	DO 160 J=1,3	WR27 144
	DO 180 I=1,3	WR27 145
	SUM = 0.0	WR27 146
	DO 170 K=1,3	WR27 147
	DO 170 L=1,3	WR27 148
170	SUM = SUM+RZ(I,K)*RY(K,L)*RX(L,J)	WR27 149
180	R(I,J) = SUM*S(J)	WR27 150
C		WR27 151
C	TRANSFORM COORDINATE VARIABLES: XP = R*(X-XCG)	WR27 152
C		WR27 153
	DO 210 J=1,NC	WR27 154
	IF (NDP.GT.1) NPJ = NP(J)	WR27 155
	IF (NPJ.LT.1) GO TO 210	WR27 156
	DO 200 I=1,NPJ	WR27 157
	DX = X(I,J)-XCG(1)	WR27 158
	DY = Y(I,J)-XCG(2)	WR27 159
	DZ = Z(I,J)-XCG(3)	WR27 160
	XP(I,J) = R(1,1)*DX+R(1,2)*DY+R(1,3)*DZ	WR27 161
	YP(I,J) = R(2,1)*DX+R(2,2)*DY+R(2,3)*DZ	WR27 162

200	CONTINUE	WR27	163
210	CONTINUE	WR27	164
	RETURN	WR27	165
	END	WR27	166

```

SUBROUTINE PLOTAS (X,IEXP,IROUND)
-----
C
C SUBROUTINE PLOTAS
C
C PURPOSE
C ROUTINE TO ROUND OFF X
C
C CALLING FORMAT
C CALL PLOTAS (X,IEXP,IROUND)
C
C PARAMETERS
C NAME TYPE I/O/S DIM DESCRIPTION
C X R I/O NONE VALUE TRUNCATED AT GIVEN EXPONENT
C IEXP I I NONE EXPONENT AT WHICH TRUNCATION OCCURS
C IROUND I I NONE ROUND OFF INDICATOR:
C ROUND UP (=+1), DOWN (=0)
C
C AUTHOR
C JOSEPH MULLEN JR., NIELSEN ENGINEERING & RESEARCH, INC.
C DATE: DECEMBER, 1976
C
C NOTES
C CALLED BY PLOTAA, PLOTAA9, PLOTII, & IPLOT.
-----
COMMON /ORUGA / IPR
IF (X.LT.0.0) IX = IROUND-1
IF (X.GE.0.0) IX = IROUND
YS = X
X = X/10.**IEXP
IX = IFIX(X)
IF (FLOAT(ABS(IX)).LT.ABS(X)) IX = IX+IX
X = FLOAT(IX)*10.**IEXP
C
IF (IPR.GT.0) WRITE(6,10) X,IEXP,IROUND,YS
10 FORMAT(23H PLOTAS = DEBUG PRINT =,8H X=OUT#,G12.5,
* 7H IEXP#,15,8H IROUND#,14,7H X=IN#,G12.5)
RETURN
END
-----

```

```

SUBROUTINE PLOTAB (UX,IEXP,APRINT)
-----
C
C SUBROUTINE PLOTAB
C
C PURPOSE
C ROUTINE TO ROUND OFF SCALING TO NEAREST ACCEPTABLE PLOTTING
C SCALE.
-----

```

C						WB29	9
C	CALLING FORMAT					WB29	10
C	CALL PLOTAB (DX, IEXP, NPRINT)					WB29	11
C						WB29	12
C	PARAMETERS					WB29	13
C	NAME	TYPE	I/O/S	DIM	DESCRIPTION	WB29	14
C						WB29	15
C	DX	H	I/O	NONE	VARIABLE TO ROUNDED OFF	WB29	16
C	IEXP	I	0	NONE	EXPONENT OF ROUNDED VARIABLE	WB29	17
C	NPRINT	I	0	NONE	NUMBER OF CHARACTERS BETWEEN LABELS	WB29	18
C						WB29	19
C	AUTHOR					WB29	20
C	JOSEPH MULLEN JR., NIELSEN ENGINEERING + RESEARCH, INC.					WB29	21
C	DATED: DECEMBER, 1976					WB29	22
C						WB29	23
C	NOTES					WB29	24
C	ARRAYS XSCL AND NPR IN THIS ROUTINE DETERMINE THE *ACCEPTABLE*					WB29	25
C	VALUES TO BE USED AS EVEN INCREMENTS IN PERFORMING SCALING.					WB29	26
C	CALLED BY PLOTAB, PLOTA9, PLUTI, + IRPLOT.					WB29	27
C						WB29	28
C	-----					WB29	29
C	COMMON /ORUGA / IPR					WB29	30
C	DIMENSION XSCL(6), NPR(4)					WB29	31
C	DATA XSCL/2.,2.5,4.,5.,8.,10./					WB29	32
C	DATA NPR /25,20,25,20,25,20/ ,NSCL/6/					WB29	33
C	DATA OXSAVE /1,0/					WB29	34
C						WB29	35
C	ABSX = ABS(DX)					WB29	36
C	IF (ABSX.LE.0.) WRITE(6,10) DX					WB29	37
C	IF (ABSX.LE.0.) ABSX=OXSAVE					WB29	38
C	IF (ABSX.GT.0.) OXSAVE=ABSX					WB29	39
10	FORMAT(///5'2H *),45H WARNING = ILLEGAL DATA TO BE SCALED (PLOTAB)					WB29	40
C	* .6H = DX,G20,13,5(2H *)					WB29	41
C						WB29	42
C	DETERMINE EXPONENT OF DX					WB29	43
C	AL = ALOG10(ABSX)					WB29	44
C	IEXP = AL					WB29	45
C	IF (ABSX.LT.1.) IEXP=IEXP-1					WB29	46
C	AL = DX					WB29	47
C						WB29	48
C	SET ABSX BETWEEN 1 AND 10					WB29	49
C	ABSX = ABSX/10.**IEXP					WB29	50
C						WB29	51
C	COMPARE WITH + LOCATE ACCEPTABLE SCALE					WB29	52
C	DO 80 I=1,NSCL					WB29	53
C	IF (ABSX.LE.XSCL(I)) GO TO 85					WB29	54
80	CONTINUE					WB29	55
C	I = NSCL					WB29	56
85	ABSX = XSCL(I)					WB29	57
C	NPRINT = NPR(I)					WB29	58
C						WB29	59
C	RETURN SCALED VALUES					WB29	60
C	DX = SIGN(ABSX,DX)*10.**IEXP					WB29	61
C	IF (IPR.GT.0) WRITE(6,12) DX,IEXP,NPRINT,I,AL					WB29	62
12	FORMAT(23H PLOTAB = DEBUG PRINT =,4H DX=OUT=,G12.5,7H IEXP=,15,					WB29	63
C	* 8H NPRINT=,14,4H I=,13,7H DX=IN=,G12.5)					WB29	64
C	RETURN					WB29	65
C	END					WB29	66

```

SUBROUTINE PLOTA7 (LINE,L,IOPT)                                *R30  1
-----*R30  2
C *R30  3
C SUBROUTINE PLOTA7 *R30  4
C *R30  5
C PURPOSE *R30  6
C ROUTINE TO INITIALIZE A ROW OF PLOTTED OUTPUT. THE ARRAY LINE *R30  7
C IS INITIALIZED WITH THE BORDER AND WITH X- AND Y-AXES. *R30  8
C *R30  9
C *R30 10
C CALLING FORMAT *R30 11
C CALL PLOTA7 (LINE,L,IOPT) *R30 12
C *R30 13
C PARAMETERS *R30 14
C NAME TYPE I/O/S DIM DESCRIPTION *R30 15
C *R30 16
C LINE I O NONE VECTOR CONTAINING LINE OF OUTPUT. *R30 17
C L I I NONE L*TH ROW OF OUTPUT *R30 18
C IOPT I I NONE OPTION: IOPT=1, INITIALIZE LINE AS *R30 19
C BOUNDARY OR AXIS *R30 20
C IOPT=2, INITIALIZE LINE AS BLANK *R30 21
C *R30 22
C AUTHOR *R30 23
C JOSEPH MULLEN JR., NIELSEN ENGINEERING + RESEARCH, INC. *R30 24
C DATED: DECEMBER, 1976 *R30 25
C *R30 26
C NOTES *R30 27
C CALLED BY APLOT, PLOTA1, PLOTA2, + PLOTV2 *R30 28
C *R30 29
C THE DATA VARIABLES DASH, SLASH, BLANK, AND SLASHI DETERMINE THE *R30 30
C CHARACTERS WHICH MAKE UP THE PLOT BORDER AND TICK MARKS. *R30 31
C THIS IS THE ONLY STATEMENT REQUIRED TO CHANGE THESE CHARACTER *R30 32
C REPRESENTATIONS. *R30 33
C *R30 34
-----*R30 35
C INTEGER DASH,SLASH,BLANK,SLASHI,SYM,LINE(103) *R30 36
C COMMON /MPLTA1/ NXPR,NYPR,IYAXIS,IXAXIS,IOFFY,IOFFX,LLINE *R30 37
C DATA DASH,SLASH,BLANK,SLASHI/1H=,1H1,1H ,1H1/ *R30 38
CIRM DATA DASH,SLASH,BLANK,SLASHI/1H=,1H1,1H ,1H1/ *R30 39
C SYM = SLASH *R30 40
C LMI = LLINE-1 *R30 41
C *R30 42
C SET Y-SCALE TICK MARKS *R30 43
C IF (MOD(L-1,NYPR/2),EQ,0) SYM = DASH *R30 44
C LINE(1) = SYM *R30 45
C LINE (LLINE) = SYM *R30 46
C IF (IOPT,EQ,2) GO TO 200 *R30 47
C *R30 48
C INITIALIZE BOUNDARY WITH X-SCALE TICK MARKS *R30 49
C DO 70 J=P,LMI *R30 50
C LINE(J) = DASH *R30 51
C IS = MOD(IOFFY,10) *R30 52
C IF (IS,LE,0) IS=IS+10 *R30 53
C DO 80 J=IS,LMI,10 *R30 54
C LINE(J) = SLASH *R30 55
C DO 90 J=IOFFY,LMI,NXPR *R30 56
C LINE(J) = SLASHI *R30 57
C RETURN *R30 58
C *R30 59
C INITIALIZE BLANK ROW *R30 60
C 200 DO 210 I=2,LMI *R30 61
C 210 LINE(I) = BLANK *R30 62
C IF (IYAXIS,GT,0) LINE(IYAXIS) = SYM *R30 63

```

RETURN *R30 64
 END *R30 65

```

SUBROUTINE PLOTAB (DX,DY,FMT,LWID,LENG,IOPT) *R31 1
-----*R31 2
SUBROUTINE PLOTAB *R31 3
PURPOSE *R31 4
ROUTINE TO SELECT SCALES, AND ROUND MAX AND MIN VALUES TO *R31 5
ACCEPTABLE VALUES, AND LOCATE X= AND Y=AXES. *R31 6
CALLING FORMAT *R31 7
CALL PLOTAB (DX,DY,FMT,LWID,LENG,IOPT) *R31 8
PARAMETERS *R31 9
NAME TYPE I/O/S DIM DESCRIPTION *R31 10
DX I I/O NONE X DATA INCREMENT (OUTPUT) *R31 11
DY I I/O NONE Y DATA INCREMENT (OUTPUT) *R31 12
FMT M I/O (6) OBJECT TYPE FORMAT FOR PRINTING *R31 13
X=AXIS SCALES. *R31 14
LWID I I NONE WIDTH OF PLOT (NO. OF CHARACTERS) *R31 15
LENG I I NONE LENGTH OF PLOT (NO. OF CHARACTERS) *R31 16
IOPT I I NONE OPTION FOR TYPE OF PAGE SCALING *R31 17
1, USER SPECIFIES SCALE LIMITS *R31 18
2, INTERNAL AUTOMATIC BEST SCALING *R31 19
3, AUTOMATIC TRUE SHAPE SCALING, USES *R31 20
RATIO: 0.6*LWID/LENG = XDIFF/YDIFF *R31 21
4, USE MAX AND MIN VALUES OF DATA *R31 22
5, INPUT XMAX,YMIN# AUTO Y-SCALING *R31 23
6, INPUT YMAX,YMIN# AUTO X-SCALING *R31 24
EXTERNAL REFERENCES *R31 25
PLOT# SUBROUTINES: PLOTAS, PLOTAB *R31 26
AUTHOR *R31 27
JOSEPH MULLEN JR., NIELSEN ENGINEERING + RESEARCH, INC. *R31 28
DATED: DECEMBER, 1976 *R31 29
NOTES *R31 30
1. PRODUCES SCALING CONSISTENT WITH ARPL0T, PLOT#1, PLOT#2, AND *R31 31
PLOT#2. VALUES COMPUTED BESIDES THE ARGUMENT LIST ARE XMAX, *R31 32
YMIN, YMAX, YMIN, XPR, YPR, IXAXIS, IYAXIS, IOFFX, IOFFY, AND FMT. *R31 33
CALLED BY ARPL0T, PLOT#1, PLOT#2, + PLOT#2. *R31 34
2. THE DATA VARIABLE *RATIO* IN THIS ROUTINE SETS THE CHARACTER *R31 35
SIZE WIDTH=TO=HEIGHT RATIO FOR TRUE SHAPE SCALING. TO CHANGE *R31 36
SET *RATIO* EQUAL TO NO. OF CHARACTERS/INCH DOWN PAGE DIVIDED *R31 37
BY NO. OF CHARACTERS /INCH ACROSS PAGE. *R31 38
-----*R31 39
DIMENSION DX(4),DY(4),IEXP(4),NPR(4),FMT(6),FMTX(27) *R31 40
COMMON /PLOT#1/ NXPR,NYPR,IYAXIS,IXAXIS,IOFFX,IOFFY,LLINE *R31 41
COMMON /HSCALE/ XMAX,XMIN,YMAX,YMIN *R31 42
COMMON /ORUGA / IPR *R31 43
DATA FMTX/ 0MC ,4M(0X ,4M(7X ,4M(8X ,4M(9X ,4M(10X,4M(11X,4M(12X *R31 44
* ,4M(13X,4M(14X,4M(15X,4M(16X,4M(17X,4M(18X,4M(19X,4M(20X *R31 45

```

```

*      .4H(21X,.4H(22X,.4H(23X,.4H(24X,.4H(25X,.4H(26X,.4H(27X,.4H(28X
*      .4H(29X,.4H(30X,.4H(31X/
DATA RND,.4ALF/0,0001,0,5001/
C  DEFINE RATIO OF PRINTED CHARACTER WIDTH-TO-HEIGHT
DATA RATIO/0.6/
C
C  TEST FOR ILLEGAL WIDTH AND LENGTH
C
IF (LENG.LT.2) LENG=40
IF (LWID.GT.100) LWID=100
IF (LWID.LT.2) LWID=100
LLINE = L-ID+3
C
C  DEBUG DATA CHECK (IF INPUT
IF (IPR.LT.0) IPR=0
IF (IPR.GT.0) WRITE(6,10) IOPT,LWID,LENG,LLINE,XMAX,XMIN,YMAX,YMIN
10  FORMAT(24H PLOTAB = DEBUG PRINT =,7H IOPT=,15,7H LWID=,15,
*      7H LENG=,15,7H LLINE=,15,7H XMAX=,612,5,
*      7H XMIN=,612,5,7H YMAX=,612,5,7H YMIN=,612,5)
C
XDIFF = XMAX-XMIN
YDIFF = YMAX-YMIN
DX = XDIFF/LWID
DY = YDIFF/LENG
IXPAS = 0
IYPAS = 0
C
C  BRANCH TO APPROPRIATE TYPE OF SCALING REQUESTED
C
230  GO TO (240,250,260,240,290,300),IOPT
C
C  IOPT=1,4, SPECIFY X-Y SCALE LIMITS
C
240  NXPR = 20
      NYPR = 10
      IF (ABS(RATIO*DY/DX-1.0).LT.0.01) NYPR=12
      GO TO 330
C
C  IOPT=2, COMPUTE AUTOMATIC SCALED LIMITS
C
250  CALL PLOTAB (DX,IEXPX,NXPR)
      CALL PLOTAB (DY,IEXPY,NYPR)
      NYPR = 10
      GO TO 310
C
C  IOPT=3, COMPUTE AUTOMATIC TRUE SHAPE SCALES
C
260  DYI(1) = DY
      DXI(2) = DX+RATIO
      DXI(3) = DX
      DYI(4) = DY/RATIO
      CALL PLOTAB(DYI(1),IEXP(1),NPR(1))
      CALL PLOTAB(DXI(2),IEXP(2),NPR(2))
      CALL PLOTAB(DXI(3),IEXP(3),NPR(3))
      CALL PLOTAB(DYI(4),IEXP(4),NPR(4))
      DXI(1) = DYI(1)*RATIO
      DYI(2) = DXI(2)/RATIO
      DYI(3) = DXI(3)/RATIO
      DXI(4) = DYI(4)*RATIO
      DAM = AMAX1(DXI(1),DXI(2),DXI(3),DXI(4))
      DO 270 I=1,4
      IF (DXI(I).LT,DX) GO TO 270
      IF (DYI(I).LT,DY) GO TO 270

```

```

WB31 58
WB31 59
WB31 60
WB31 61
WB31 62
WB31 63
WB31 64
WB31 65
WB31 66
WB31 67
WB31 68
WB31 69
WB31 70
WB31 71
WB31 72
WB31 73
WB31 74
WB31 75
WB31 76
WB31 77
WB31 78
WB31 79
WB31 80
WB31 81
WB31 82
WB31 83
WB31 84
WB31 85
WB31 86
WB31 87
WB31 88
WB31 89
WB31 90
WB31 91
WB31 92
WB31 93
WB31 94
WB31 95
WB31 96
WB31 97
WB31 98
WB31 99
WB31 100
WB31 101
WB31 102
WB31 103
WB31 104
WB31 105
WB31 106
WB31 107
WB31 108
WB31 109
WB31 110
WB31 111
WB31 112
WB31 113
WB31 114
WB31 115
WB31 116
WB31 117
WB31 118
WB31 119
WB31 120

```

	IF (DXI(I),GT,DXM) GO TO 270	WR31 121
	DXM = DXI(I)	WR31 122
	IHEST = I	WR31 123
270	CONTINUE	WR31 124
	DX = DXI(IHEST)	WR31 125
	DY = DYI(IHEST)	WR31 126
	IEXPX = IEXP(IHEST)	WR31 127
	IEXPY = IEXP(IHEST)	WR31 128
	IF (IHEST,LE,2) NXPR=20	WR31 129
	IF (IHEST,LE,2) NYPR=NYR(IHEST)/2	WR31 130
	IF (IHEST,GE,3) NXPR=NYR(IHEST)	WR31 131
	IF (IHEST,GE,3) NYPR=12	WR31 132
	GO TO 310	WR31 133
C		WR31 134
C	IOPT=5, SPECIFY X-SCALES, AUTOMATIC Y-SCALE SELECTION	WR31 135
C		WR31 136
290	NXPR = 20	WR31 137
	CALL PLOTA6(DY,IEXPY,NYPR)	WR31 138
	NYPR = 10	WR31 139
	GO TO 310	WR31 140
C		WR31 141
C	IOPT=6, SPECIFY Y-SCALES, AUTOMATIC X-SCALE SELECTION	WR31 142
C		WR31 143
300	NYPR = 10	WR31 144
	CALL PLOTA6(DX,IEXPX,NXPR)	WR31 145
	GO TO 320	WR31 146
C		WR31 147
C	RELOCATE AND ROUND OFF YMAX + XMIN	WR31 148
C	YMIN	WR31 149
310	IYPAS = IYPAS+1	WR31 150
	IF (IYPAS,GT,1) GO TO 315	WR31 151
	IYPAS = 1	WR31 152
	YMINI = YMIN-0.5*(DY*(LENG-YDIFF))	WR31 153
	CALL PLOTA6 (YDIFF,IRND,NRND)	WR31 154
	CALL PLOTA5 (YMINI,IRND,0)	WR31 155
315	IF (YMINI,LE,0.) YMINI=DY*FLOAT(IFIX(YMINI/DY+SIGN(RND,YMINI)))	WR31 156
C		WR31 157
C	CHECK FOR ZERO AS A POSSIBLE MINIMUM SCALE	WR31 158
	IF (ABS(YMINI/DY),LT,0.25) YMINI=0.0	WR31 159
	IF (YMINI,GE,0.0) YMINI=AMAX1(YMINI,0.0)	WR31 160
	IF (YMINI,LT,0.0) YMINI=YMINI	WR31 161
	IF (IYPAS,GT,2) GO TO 320	WR31 162
C		WR31 163
C	CHECK FOR POSSIBLE LOSS OF DATA	WR31 164
	YMAXI = YMIN+DY*LENG	WR31 165
	IF (YMAXI,LT,YMAX) DY=(YMAX-YMIN)/LENG	WR31 166
	IF (YMAXI,LT,YMAX) GO TO 250	WR31 167
	YMAX = YMIN+DY*LENG	WR31 168
C		WR31 169
C	XMIN	WR31 170
C		WR31 171
320	IF (IOPT,EQ,5) GO TO 330	WR31 172
	IXPAS = IXPAS+1	WR31 173
	IF (IXPAS,GT,1) GO TO 325	WR31 174
	IXPAS = 1	WR31 175
	XMINI = XMIN-0.5*(DX*(LENG-XDIFF))	WR31 176
	CALL PLOTA6 (XDIFF,IRND,NRND)	WR31 177
	CALL PLOTA5 (XMINI,IRND,0)	WR31 178
325	XMINI=DX*FLOAT(IFIX(XMINI/DX+SIGN(RND,XMINI)))	WR31 179
C		WR31 180
C	CHECK FOR ZERO AS A POSSIBLE MINIMUM SCALE	WR31 181
	IF (ABS(XMINI/DX),LT,0.25) XMINI=0.0	WR31 182

```

IF (XMIN,GE,0,0) X=IN+MAXI(XMINI,0,0)
IF (YMIN,GE,0,0 .AND. (XMAX=DX*L+ID),LE,0,0) XMIN=0,0
IF (XMIN,LT,0,0) XMIN=XMINI
IF (IYPAS,GT,2) GO TO 330
C
C CHECK FOR POSSIBLE LOSS OF DATA
XMAXI = XMIN+DX*L+ID
IF (XMAXI,LT,XMAX) DX=(XMAX-XMIN)/L+ID
IF (XMAXI,LT,XMAX) GO TO 230
XMAX = XMIN+DX*L+ID
C
C ESTABLISH LOCATION OF Y-AXIS, IF ANY
330 IF (XMIN,LT,0,0) IYAXIS=IFIX(ABS(XMIN/DX)+HALF)+2
IF (XMIN,GE,0,0) IYAXIS=0
C
C ESTABLISH LOCATION OF X-AXIS, IF ANY
IF (YMIN,LT,0,0) IXAXIS=IFIX(ABS(YMIN/DY)+HALF)+1
IF ((YMIN,GE,0,0).OR.(YMAX,LE,0,0)) IXAXIS=0
C
C COMPUTE Y-SCALE OFFSET OF ZERO OR BOTTOM OF PLOT
IF (YMIN,LT,0,0) IOFFY = MOD(IXAXIS,NYPR)-1
IF (YMIN,GE,0,0) IOFFY = MOD(LENG,NYPR)
C
C COMPUTE X-SCALE OFFSET OF ZERO OR FIRST LABEL
IF (XMIN,LT,0,0) IOFFX=IYAXIS
IF (XMIN,GE,0,0) IOFFX=IFIX(-XMIN/DX+HALF)+2
IOFFX = MOD(IOFFX,NXPR)
IF (IOFFX,LT,2) IOFFX=IOFFX+NXPR
IF ((IOPT,EQ,1),OR,(IOPT,EQ,5)) IOFFX=2
C
C SET FORMAT, FMT, FOR Y-AXIS
IFMT = MAX(3,IOFFX+1)
FMT(1) = FMTX(IFMT)
IF (NXPR,EQ,25) FMT(4)=FMTX(5)
IF (NXPR,EQ,20) FMT(4)=FMTX(2)
IF (NXPR,EQ,16) FMT(4)=FMTX(1)
C
IF (IDR,LE,0) GO TO 999
WRITE(6,12) XMAX,XMIN,DX,NXPR,IYAXIS,IOFFY,YMAXI,XMINI,IYPAS
WRITE(6,14) YMAX,YMIN,DY,NYPR,IXAXIS,IOFFX,YMAXI,YMINI,IYPAS
IF (IOPT,EQ,3) WRITE(6,16) DXI,DYI,IXPR,NYPR,IREST
WRITE(6,18) FMT
12 FORMAT(20H PLOTAB = X-SCALES =,7H Y-AXIS,G12.5,7H XMINI,G12.5,
* 7H DX,G12.5,7H NXPR=,15,6H IYAXIS=,14,7H IOFFY=,14,
* /20X,7H XMAXI=,G12.5,7H XMINI=,G12.5,7H IYPAS=,15)
14 FORMAT(20H PLOTAB = Y-SCALES =,7H Y-AXIS,G12.5,7H YMINI,G12.5,
* 7H DY,G12.5,7H NYPR=,15,6H IXAXIS=,14,7H IOFFX=,14,
* /20X,7H YMAXI=,G12.5,7H YMINI=,G12.5,7H IYPAS=,15)
16 FORMAT(20H PLOTAB = IOPT=,6H DXI=,4G12.5,
* /20X,6H DYI=,4G12.5,/20X,6H IXPR=,4I12,
* /20X,6H NYPR=,4I12,16X,6H IREST=,14)
18 FORMAT(20H PLOTAB = FORMAT =,7H FMT=,2X,6A4)
999 RETURN
END

```


	SUBROUTINE PLOTG	WR32	1
C		WR32	2
C	ROUTINE TO PLOT PANEL GEOMETRY AND ROTATE CONFIGURATION FOR	WR32	3
C	PERSPECTIVE VIEWING	WR32	4
C		WR32	5
C	DATA STORAGE (TAPE7):	WR32	6
C	1. ARRAY(6000) = WING/TAIL CORNER POINTS AND PANEL GEOMETRY	WR32	7
C	2. ARRAY(6000) = BODY CORNER POINTS	WR32	8
C		WR32	9
	DIMENSION ARRAY(6000),X(5,300),Y(5,300),Z(5,300)	WR32	10
	* ,CHORD(600),SLOPE(600),XP(5,300),YP(5,300)	WR32	11
	* ,NPLT(300),XCG(5),AROT(5),LINE(3000)	WR32	12
C		WR32	13
	COMMON /JOPTS/ IZ1(8)	WR32	14
	1 ,J0,J1,J2,J3,J4,J5,J6,NWAF,NWAFOR,NFUS,NRADX(4),NFORX(4)	WR32	15
	2 ,NP,NPQDIR,NF,NFINOR,NCAN,NCANOR,J2TEST,NW	WR32	16
	3 ,IZ2(34),IPRT(5),IXZSYN	WR32	17
	COMMON /PARAM / NBDY,NWING,NTAIL,LHC,THK,XMACH,ALPHA,BETA,ALPHAC	WR32	18
	1 ,PHIR,REFA,REFB,REFC,REFD,REFL,REFX,REFZ	WR32	19
	COMMON /POINT / XPT(600),YPT(600),ZPT(600),THEY(600)	WR32	20
	* ,DELTA(600),XC(30,20),YC(30,20),ZC(30,20),AREA(600),XLE(600)	WR32	21
	COMMON BLOCK(7500)	WR32	22
	COMMON /NE-COM/ K1,KWAF,KWAFOR,KRADX(4),KFORX(4),KFUS,MAX,K4,K5	WR32	23
	1 ,KF(6),KAN(6),KFINOR(6),KANOR(6),KOL,NCPY,LOCPT(20),XCPT(20)	WR32	24
	COMMON /SEG / NSEG,NROW(20),NCOL(20),COSS(20),SINS(20)	WR32	25
	1 ,HT(20),NNT(20),HL(140)	WR32	26
	COMMON /BSIZE / XYPT(4),ITAPE	WR32	27
C		WR32	28
	EQUIVALENCE (ARRAY(1),XPT(1))	WR32	29
	* ,(X(1),BLOCK(1)), (Y(1),BLOCK(1501)), (Z(1),BLOCK(3001))	WR32	30
	* ,(XP(1),BLOCK(4501)), (YP(1),BLOCK(6001))	WR32	31
	* ,(CHORD(1),AREA(1)), (SLOPE(1),XLE(1))	WR32	32
	* ,(XPT(1),LINE(1))	WR32	33
C		WR32	34
	DATA XCG,AROT/3*0., 3*0./, NPLT/300*5/	WR32	35
	DATA IOPT,NOP,L*ID,LENG/3,5,100,50/	WR32	36
	DATA NLIN/3000/	WR32	37
	ITAPE=9	WR32	38
C		WR32	39
C	COPY WING PANEL POINTS IN TO (X,Y,Z)	WR32	40
C		WR32	41
	CALL CPUTIM(TIME,DT,1)	WR32	42
	REWIND 7	WR32	43
	JP = 0	WR32	44
	IF (K1.EQ.0 .AND. K4.EQ.0 .AND. K5.EQ.0) GO TO 150	WR32	45
	READ (7) ARRAY,CHORD,SLOPE	WR32	46
	ONE = 1.	WR32	47
	CALL MXOUT (8M XC=WING,ONE,XC,30,20,60,132,1,30,20)	WR32	48
C	CALL YXOUT (8M YC=WING,ONE,YC,30,20,60,132,1,30,20)	WR32	49
C	CALL ZXOUT (8M ZC=WING,ONE,ZC,30,20,60,132,1,30,20)	WR32	50
C		WR32	51
C	DEFINE CLOSED CURVE AROUND BOUNDARY OF PANEL	WR32	52
C	POINTS ARE ACCESSED IN THE FOLLOWING ORDER	WR32	53
C	1 = (J=1,K=1) 3 = (J=1,K)	WR32	54
C	2 = (J ,K=1) 4 = (J ,K)	WR32	55
C	CURVE IS DRAWN IN FOLLOWING ORDER: (1,2,4,3,1)	WR32	56
C		WR32	57
	IF (NSEG.EQ.0) GO TO 150	WR32	58
	L = 1	WR32	59
	DO 140 N=1,NSEG	WR32	60
	NW = NROW(N)	WR32	61
	NC = NCOL(N)	WR32	62
C		WR32	63

DO 130 K=2,NC	WA32 64
L = L+1	WA32 65
KM1 = L-1	WA32 66
C	WA32 67
DO 120 J=2,NR	WA32 68
JM1 = J-1	WA32 69
JP = JP+1	WA32 70
C 1ST CORNER	WA32 71
X(1,JP) = XC(JM1,KM1)	WA32 72
Y(1,JP) = YC(JM1,KM1)	WA32 73
Z(1,JP) = ZC(JM1,KM1)	WA32 74
C 2ND CORNER	WA32 75
X(2,JP) = XC(J,KM1)	WA32 76
Y(2,JP) = YC(J,KM1)	WA32 77
Z(2,JP) = ZC(J,KM1)	WA32 78
C 3RD CORNER	WA32 79
Y(3,JP) = XC(J,K)	WA32 80
Y(3,JP) = YC(J,K)	WA32 81
Z(3,JP) = ZC(J,K)	WA32 82
C 4TH CORNER	WA32 83
X(4,JP) = XC(JM1,K)	WA32 84
Y(4,JP) = YC(JM1,K)	WA32 85
Z(4,JP) = ZC(JM1,K)	WA32 86
C 5TH CORNER = CLOSE CURVE	WA32 87
X(5,JP) = XC(JM1,KM1)	WA32 88
Y(5,JP) = YC(JM1,KM1)	WA32 89
Z(5,JP) = ZC(JM1,KM1)	WA32 90
IF (JP,GE,500) GO TO 250	WA32 91
120 CONTINUE	WA32 92
130 CONTINUE	WA32 93
140 CONTINUE	WA32 94
C	WA32 95
C READ BODY PANEL DATA FOR CORNER POINTS (XC,YC,ZC) -----	WA32 96
C	WA32 97
150 IF (NFUS,EG,0) GO TO 250	WA32 98
READ (7) ARRAY	WA32 99
TWO = 2.	WA32 100
C CALL MXOUT (8H XC=BODY,TWO,XC,30,20,60,132,1,30,20)	WA32 101
C CALL MXOUT (8H YC=BODY,TWO,YC,30,20,60,132,1,30,20)	WA32 102
C CALL MXOUT (8H ZC=BODY,TWO,ZC,30,20,60,132,1,30,20)	WA32 103
C	WA32 104
C COPY BODY CORNER POINTS INTO CURVES	WA32 105
C	WA32 106
L = 1	WA32 107
DO 240 IFUS=1,NFUS	WA32 108
NC = KPADX(IFUS)	WA32 109
NR = KFORX(IFUS)	WA32 110
C	WA32 111
DO 230 K=2,NC	WA32 112
L = L+1	WA32 113
KM1 = L-1	WA32 114
C	WA32 115
DO 220 J=2,NR	WA32 116
JP = JP+1	WA32 117
JM1 = J-1	WA32 118
C 1ST CORNER	WA32 119
X(1,JP) = XC(JM1,KM1)	WA32 120
Y(1,JP) = YC(JM1,KM1)	WA32 121
Z(1,JP) = ZC(JM1,KM1)	WA32 122
C 2ND CORNER	WA32 123
X(2,JP) = XC(J,KM1)	WA32 124
Y(2,JP) = YC(J,KM1)	WA32 125
Z(2,JP) = ZC(J,KM1)	WA32 126

C	3RD CORNER	WA32 127
	X(3,JP) = XC(J,K)	WA32 128
	Y(3,JP) = YC(J,K)	WA32 129
	Z(3,JP) = ZC(J,K)	WA32 130
C	4TH CORNER	WA32 131
	X(4,JP) = XC(JM,K)	WA32 132
	Y(4,JP) = YC(JM,K)	WA32 133
	Z(4,JP) = ZC(JM,K)	WA32 134
C	5TH CORNER = CLOSE CURVE	WA32 135
	X(5,JP) = XC(JM1,KM1)	WA32 136
	Y(5,JP) = YC(JM1,KM1)	WA32 137
	Z(5,JP) = ZC(JM1,KM1)	WA32 138
	IF (JP,GE,300) GO TO 250	WA32 139
220	CONTINUE	WA32 140
230	CONTINUE	WA32 141
240	CONTINUE	WA32 142
C		WA32 143
C	PLOT PERSPECTIVE VIEWS OF PANEL GEOMETRY -----	WA32 144
250	CONTINUE	WA32 145
	IF (JP,LE,0) GO TO 999	WA32 146
C		WA32 147
C	TOP VIEW	WA32 148
	CALL PLOTV2(X,Y,IOPT,NPLT,NOP,JP,LWID,LENG,LINE,NLIN)	WA32 149
	WRITE(6,10)	WA32 150
C	CALL PLOTI (X,Y,IOPT,NPLT,NOP,JP,1,1,2HX*,2HY*)	WA32 151
C		WA32 152
C	SIDE VIEW	WA32 153
	CALL PLOTV2(X,Z,IOPT,NPLT,NOP,JP,LWID,LENG,LINE,NLIN)	WA32 154
	WRITE(6,11)	WA32 155
C	CALL PLOTI (X,Z,IOPT,NPLT,NOP,JP,1,1,2HX*,2HZ*)	WA32 156
C		WA32 157
C	FRONT VIEW	WA32 158
	CALL PLOTV2(Y,Z,IOPT,NPLT,NOP,JP,LWID,LENG,LINE,NLIN)	WA32 159
	WRITE(6,12)	WA32 160
C	CALL PLOTI (Y,Z,IOPT,NPLT,NOP,JP,1,1,2HY*,2HZ*)	WA32 161
C		WA32 162
C	PERSPECTIVE VIEW	WA32 163
	AROT(2) = 45.	WA32 164
	AROT(3) = -45.	WA32 165
	CALL PLOTAS(X,Y,Z,NPLT,NOP,JP,AROT,XCG,YP,YP,3)	WA32 166
	CALL PLOTV2(XP,YP,IOPT,NPLT,NOP,JP,LWID,LENG,LINE,NLIN)	Added
C	CALL PLOTI (XP,YP,IOPT,NPLT,NOP,JP,1,1,3HXP*,3HYP*)	WA32 167
	WRITE(6,13) AROT	WA32 168
	CALL CPUTIM(TIME,DT,1)	WA32 169
	WRITE(6,15) TIME,DT	WA32 170
10	FORMAT(/20X,20HTOP VIEW = Y VS X)	WA32 171
11	FORMAT(/20X,20HSIDE VIEW = Z VS X)	WA32 172
12	FORMAT(/20X,20HFRONT VIEW = Z VS Y)	WA32 173
13	FORMAT(/20X,19HPERSPECTIVE VIEW =	WA32 174
	* ,7HTHETA X=,F8,3,5X,7HTHETA Y=,F8,3,5X,7HTHETA Z=,F8,3)	WA32 175
15	FORMAT(/10X,18HEND PLOTG , TIME= ,F10,3,5X,3HDT=,F10,3)	WA32 176
C		WA32 177
999	RETURN	WA32 178
	END	WA32 179
	SUBROUTINE PLOTV2 (X,Y,IOPT,NP,NOP,JC,LWID,LENG,LINE,NLIN)	WA33 1
C	-----	WA33 2
C		WA33 3
C	SUBROUTINE PLOTV2	WA33 4
C		WA33 5

PURPOSE					WR33	6
ROUTINE TO GENERATE A CHARACTER PLOT OF NC SIMULTANEOUS					WR33	7
CURVES OF Y VS X. A LINEAR INTERPOLATION IS MADE BETWEEN					WR33	8
SEQUENTIAL POINTS.					WR33	9
					WR33	10
					WR33	11
CALLING FORMAT					WR33	12
CALL PLOTV2 (X,Y,IOPT, NP, NDP, NC, LWID, LENG, LINE, MLIN)					WR33	13
					WR33	14
PARAMETERS					WR33	15
NAME	TYPE	I/O/S	DIM	DESCRIPTION	WR33	16
X,Y	R	I	(NDP,NC)	ORIGINATE + ABSCISSA ARRAYS	WR33	18
IOPT	I	I	NONE	OPTION FOR TYPE OF PAGE SCALING	WR33	19
				1, USER SPECIFIES SCALE LIMITS	WR33	20
				2, INTERNAL AUTOMATIC BEST SCALING	WR33	21
				3, AUTOMATIC TRUE SHAPE SCALING, USES	WR33	22
				RATIO: $0.6 * LWID / LENG = XDIFF / YDIFF$	WR33	23
				4, USE MAX AND MIN VALUES OF DATA	WR33	24
				5, INPUT XMAX, XMIN# AUTO Y-SCALING	WR33	25
				6, INPUT YMAX, YMIN# AUTO X-SCALING	WR33	26
NP	I	I	NONE	VECTOR OF NUMBER OF POINTS IN J*TH	WR33	27
				CURVE	WR33	28
NDP	I	I	NONE	FIRST DIMENSION OF ARRAYS *X,Y* IN	WR33	29
				CALLING ROUTINE	WR33	30
NC	I	I	NONE	NUMBER OF SIMULTANEOUS PLOTS.	WR33	31
				IF NC#41, CHARACTER SET REPEATS.	WR33	32
LWID	I	I	NONE	WIDTH OF PLOTTED REGIONS AT 10	WR33	33
				CHARACTERS/INCH. NORMALLY=100.	WR33	34
				FOR CRT OR T.I. TERMINALS=50.	WR33	35
				MAXIMUM DIMENSIONED = 100.	WR33	36
LENG	I	I	NONE	NUMBER OF LINES IN PLOTTED REGION	WR33	37
				NORMALLY=50 AT 6 LINES/INCH#	WR33	38
				FOR 8.5" PAPER=40.	WR33	39
LINE	I	S	(MLINE)	SCRATCH MATRIX USED IN PLOTTING	WR33	40
				CHARACTERS. WHERE:	WR33	41
				$(LWID+3) * LE * MLIN * LE * (LWID+3) * (LENG+1)$	WR33	42
MLIN	I	I	NONE	DIMENSIONED LENGTH OF SCRATCH ARRAY	WR33	43
				LINE. VALUES GREATER THAN $(LWID+3)$	WR33	44
				ONLY IMPROVE THE EFFICIENCY OF THE	WR33	45
				PLOT ALGORITHM	WR33	46
					WR33	47
					WR33	48
USER SUPPLIED COMMON BLOCKS					WR33	49
IOPT #1,5,6; /RSCALE/ XMAX,XMIN,YMAX,YMIN					WR33	50
					WR33	51
COMMON /RSCALE/					WR33	52
NAME	TYPE	I/O/S	DIM	DESCRIPTION	WR33	53
XMAX	R	I/O	NONE	MAXIMUM X SCALE VALUE ACROSS PAGE	WR33	54
XMIN	R	I/O	NONE	MINIMUM X SCALE VALUE ACROSS PAGE	WR33	55
YMAX	R	I/O	NONE	MAXIMUM Y SCALE VALUE AT TOP OF PAGE	WR33	56
YMIN	R	I/O	NONE	MINIMUM Y SCALE VALUE DOWN PAGE	WR33	57
					WR33	58
					WR33	59
EXTERNAL REFERENCES					WR33	60
PLOT# SUBROUTINES: PLOT#7, PLOT#8					WR33	61
					WR33	62
AUTHOR					WR33	63
JOSEPH WILLEN JR., NIELSEN ENGINEERING + RESEARCH, INC.					WR33	64
DATED: DECEMBER, 1975					WR33	65
					WR33	66
					WR33	67
DIMENSION X(NDP,NC),Y(NDP,NC),XPRIN(7),NP(NC),FMT(6)					WR33	68

C	INITIALIZE BLANK ROW OR X-AXIS	NR33	132
C		NR33	133
	J = JSAVE	NR33	134
	JK = 1	NR33	135
	DO 110 K=1,NOL	NR33	136
	J = J+1	NR33	137
	IF (J.GT.NROWS) GO TO 115	NR33	138
	IF (J.EQ,TRAXIS) CALL PLOTA7 (LINE(JK),J=IOFFX,1)	NR33	139
	IF (J.NE,TRAXIS) CALL PLOTA7 (LINE(JK),J=IOFFX,2)	NR33	140
	JK = JK+LLINE	NR33	141
110	CONTINUE	NR33	142
C		NR33	143
C	TEST FOR VECTOR DRAWN ACROSS NEXT NOL LINES OF OUTPUT	NR33	144
C		NR33	145
115	DO 140 L=1,NC	NR33	146
	LSYM = MOD(L-1,40)+1	NR33	147
	NPL = NP(L)	NR33	148
	IF (NPL.LT,1) GO TO 140	NR33	149
	X2 = X(1,L)	NR33	150
	Y2 = Y(1,L)	NR33	151
C		NR33	152
C	START LOOP ON NUMBER OF VECTORS IN EACH LINE	NR33	153
C		NR33	154
	DO 130 K=1,NPL	NR33	155
	X1 = X2	NR33	156
	Y1 = Y2	NR33	157
	X2 = X(K,L)	NR33	158
	Y2 = Y(K,L)	NR33	159
C		NR33	160
C	TEST WHETHER VECTOR CROSSES BLOCK OF LINES	NR33	161
C		NR33	162
	IF ((Y1.GE,YUP).AND.(Y2.LE,YUP)) GO TO 130	NR33	163
	IF ((Y1.LE,YLOW).AND.(Y2.GE,YLOW)) GO TO 130	NR33	164
C		NR33	165
C	COMPUTE INTERMEDIATE POINTS AND STORE IN LINE.	NR33	166
C		NR33	167
	DELX = X2-X1	NR33	168
	DELY = Y2-Y1	NR33	169
	IDX = IFIX(ABS(DE LX/DX))	NR33	170
	IDY = IFIX(ABS(DE LY/DY))	NR33	171
	NV = MAX0(IDX,IDY)+1	NR33	172
	DELX = DELX/NV	NR33	173
	DELY = DELY/NV	NR33	174
	NV = NV+1	NR33	175
	XV = X1	NR33	176
	YV = Y1	NR33	177
C		NR33	178
	DO 125 IV=1,NV	NR33	179
	IX = IFIX((XV-XMIN)/DX+0.5)+2	NR33	180
	IY = IFIX((YV-YMIN)/DY+1.)	NR33	181
	IF ((IY.LT,1).OR.(IY.GT,NOL)) GO TO 120	NR33	182
	IF ((IX.LT,2).OR.(IX.GE,LLINE)) GO TO 120	NR33	183
	IXY = LLINE+(IY-1)+IX	NR33	184
	LINE(IXY) = SYMHOL(LSYM)	NR33	185
120	XV = XV+DELX	NR33	186
	YV = YV+DELY	NR33	187
125	CONTINUE	NR33	188
130	CONTINUE	NR33	189
140	CONTINUE	NR33	190
C		NR33	191
C	PRINT NOL LINES OF OUTPUT - CHECK FOR SCALES	NR33	192
C		NR33	193
	I = JSAVE	NR33	194

	JK = 1	WB33 195
	JK2 = LLINE	WB33 196
	DO 150 K=1,6L	WB33 197
	J = J+1	WB33 198
	IF (J.GT.NROWS) GO TO 160	WB33 199
	IMOD = MOD(J-(OFFX-1),NYP)	WB33 200
	IF (IMOD.EQ.0) WRITE (6,2) Y MID, (LINE(I),I=JK,JK2)	WB33 201
	IF (IMOD.NE.0) WRITE (6,3) (LINE(I),I=JK,JK2)	WB33 202
	JK = JK+LLINE	WB33 203
	JK2 = JK2+LLINE	WB33 204
C		WB33 205
C	INCREMENT Y-STRIP; REDEFINE YLOW AND YUP	WB33 206
C		WB33 207
	YUP = YUP+DY	WB33 208
	YMID = YMID+DY	WB33 209
	IF (ABS(YMID/DY).LT.0.001) YMID=0.0	WB33 210
	YLOW = YLOW+DY	WB33 211
150	CONTINUE	WB33 212
	ISAVE = J	WB33 213
160	CONTINUE	WB33 214
C		WB33 215
C	FORM LOWER BOUNDARY	WB33 216
C		WB33 217
	CALL PLDTA7 (LINE,1,1)	WB33 218
	WRITE (6,3) (LINE(I),I=1,LLINE)	WB33 219
C		WB33 220
C	PRINT SCALES	WB33 221
C		WB33 222
	NXP = (LLINE-IOFFY)/NXP+1	WB33 223
	XPRINT(1) = XMIN+DX*(IOFFY-2)	WB33 224
	DO 240 I=2,NXP	WB33 225
	XPRINT(I) = XPRINT(I-1)+DX*NXP	WB33 226
	IF (ABS(XPRINT(I)/DX).LT.0.001) XPRINT(I)=0.0	WB33 227
240	CONTINUE	WB33 228
	WRITE(6,FMT) (XPRINT(I),I=1,NXP)	WB33 229
	RETURN	WB33 230
1	FORMAT (1H1,14X,103A1)	WB33 231
2	FORMAT (1X,613.4,1X,103A1)	WB33 232
3	FORMAT (15X,103A1)	WB33 233
	END	WB33 234

	SUBROUTINE PRESS(NP,XMACH,ARA,U,V,W,CPP,CPSTAG,CPCRT,CPVAC,COMP)	WB34 1
C		WB34 2
C	THE PRESSURE COEFFICIENT IS CALCULATED USING THE EXACT ISENTROPIC	WB34 3
C	FORMULA IN ALL CASES EXCEPT FOR WING, CANARD (HORIZONTAL TAIL),	WB34 4
C	AND FIN (VERTICAL TAIL) COMPONENTS ANALYZED UNDER THE PLANAR	WB34 5
C	BOUNDARY CONDITION OPTION. IN THESE CASES, THE LINEARIZED THEORY	WB34 6
C	PRESSURE COEFFICIENT FORMULA IS USED AND THE PRESSURE COEFFICIENT	WB34 7
C	IS LIMITED BY THE VACUUM PRESSURE COEFFICIENT.	WB34 8
C		WB34 9
C	COMPUTE THE STAGNATION PRESSURE COEFFICIENT, CRITICAL PRESSURE	WB34 10
C	COEFFICIENT, AND VACUUM PRESSURE COEFFICIENT.	WB34 11
C		WB34 12
	COMMON /PAWAM /NHDDY,OWING,NTAIL,LRC,THK,AMACH,ALPHA,BETA,ALPHAC	WB34 13
	1 ,PHIR,REFA,REFR,REFC,REFD,PEFL,REFX,REFZ	WB34 14
	DIMENSION H(1),V(1),W(1),CPP(1)	WB34 15
	INTEGER COMP	WB34 16
	LOGICAL LRC	WB34 17

```

X*2=XMACH*XMACH
CPCRT=0.
CPSTAG=1.
CPVAC=0.
COSARA=COS(ARA)
SINARA=SIN(ARA)
IF (XM2.EQ.0.) GO TO 10
CON1=.42857/XM2
CPVAC=CON
CON1=.2*XM2
C
C LOOP THROUGH NP=PANELS TO CALCULATE PRESSURE COEFFICIENTS -----
C
10 DO 40 J=1, NP
U=PM=U(J)*COSARA+V(J)*SINARA
IF (LBC.AND.COMPT.EQ.2) GO TO 20
U=IND=1.+U*PM
V=IND=V(J)
W=IND=W(J)*COSARA-U(J)*SINARA
V*2=V*IND+V*IND+W*IND+W*IND
Q2=U*IND+U*IND+V*2
IF (XMACH.EQ.0.) GO TO 30
ARG=1.+CON1*(1.-Q2)
IF (ARG.LT.0.) ARG=0.
CPP(J)=CON*(ARG**3.5-1.)
GO TO 40
20 CPP(J)=-2.*U(J)
C
C CONSTRAIN THE PRESSURE COEFFICIENT SO THAT IT DOES NOT
C EXCEED THE VACUUM PRESSURE COEFFICIENT
C
IF (CPP(J).LT.CPVAC) CPP(J)=CPVAC
GO TO 40
30 CPP(J)=1.-Q2
40 CONTINUE
IF (XMACH.EQ.0.) RETURN
CPSTAG=CON*((1.+CON1)**3.5-1.)
CPCRT=CON*((5./6.+XM2/6.)*3.5-1.)
RETURN
END

```

```

SUBROUTINE PRICPT(NBODY)
C
C ROUTINE TO PRINT A COPY OF THE CONTROL POINTS AFT OF *XSTART*
C AND FORWARD OF *XMLE* ON TAPE4 FOR USE BY OTHER PROGRAMS
C
COMMON /JDPNMS/ IZI(59),NVLIN
* ,NCPNUT,ASTART,XMLE,NXCPT,IPLUT(4),IPHT(5),IXZSY*
COMMON /PRINT / XPT(600),YPT(600),ZPT(600),THPT(600),DELTA(600),
1 XC(30,20),YC(30,20),ZC(30,20),DELTI(600),XLE(600)
C
IF (NXCPT.NE.0) GO TO 999
IF (NVLIN.GT.0) GO TO 999
WRITE(5,750)
N=IND 4
IJ = 0
DO 100 I=1,NBODY
IF (XPT(I).LT.XSTART) GO TO 100

```


	IF (XPT(I).GT.X*LE) GO TO 100	WR35	19
	IJ = IJ+1	WR35	19
	*WRITE(4,745) IJ,XPT(I),YPT(I),ZPT(I)	WR35	20
	WRITE(6,745) IJ,XPT(I),YPT(I),ZPT(I)	WR35	21
100	CONTINUE	WR35	22
	ENOFIL 4	WR35	23
	IF (NCPDUT,EQ,2) STOP 500	WR35	24
999	RETURN	WR35	25
C		WR35	26
750	FORMAT(1H1,9X,42HSUMMARY OF CONTROL POINTS WRITTEN ON TAPE4	WR35	27
	* ,58X,12H** PRICPT **)	WR35	28
745	FORMAT(15,3G12,5)	WR35	29
	END	WR35	30

	SUBROUTINE READVX (NFUS,NFORX,LPRT)	WR36	1
C		WR36	2
C	ROUTINE TO READ THE VORTEX LOCATIONS AND STRENGTHS OF BODY VORTICES	WR36	3
C		WR36	4
	DIMENSION XFUS(30,4),FUSHY(30,4),FUSAZ(30,4),NFORX(4)	WR36	5
	LOGICAL LPRT	WR36	6
C		WR36	7
	COMMON /HVRTX / NVTX,NVVTX,XV(10),AV(10),BV(10)	WR36	8
	COMMON BLOCK(7500)	WR36	9
C		WR36	10
	EQUIVALENCE (XFUS(1,1),BLOCK(1))	WR36	11
	* , (FUSHY(1,1),BLOCK(361)) , (FUSAZ(1,1),BLOCK(481))	WR36	12
C		WR36	13
	IF (NVVTX.LE.0) GO TO 999	WR36	14
C		WR36	15
C	READ VORTEX PATH X-STATIONS	WR36	16
	READ (5,160) (XV(I),I=1,NVVTX)	WR36	17
	IF (LPRT) WRITE(6,170) (XV(I),I=1,NVVTX)	WR36	18
C		WR36	19
C	INTERPOLATE IN GEOMETRY FOR MAJOR AND MINOR AXES,	WR36	20
C	B AND A RESPECTIVELY.	WR36	21
C		WR36	22
	DO 120 K=1,NVVTX	WR36	23
C	FIND GEOMETRY BODY STATION	WR36	24
	DO 100 NFU=1,NFUS	WR36	25
	NFUSOR=NFORX(NFU)	WR36	26
	DO 100 J=2,NFUSOR	WR36	27
	IF (XV(K).LE.XFUS(J,NFU)) GO TO 110	WR36	28
100	CONTINUE	WR36	29
	J = NFUSOR	WR36	30
	NFU = NFUS	WR36	31
110	JM1 = J-1	WR36	32
	DX = XFUS(J,NFU)-XFUS(JM1,NFU)	WR36	33
	IF (DX.NE.0.) DX=(XV(K)-XFUS(JM1,NFU))/DX	WR36	34
C		WR36	35
C	INTERPOLATE FOR A AND B	WR36	36
C		WR36	37
	AV(K) = FUSAZ(JM1,NFU)+DX*(FUSAZ(J,NFU)-FUSAZ(JM1,NFU))	WR36	38
	BV(K) = FUSHY(JM1,NFU)+DX*(FUSHY(J,NFU)-FUSHY(JM1,NFU))	WR36	39
120	CONTINUE	WR36	40
	IF (LPRT) WRITE(6,180) (BV(I),I=1,NVVTX)	WR36	41
	IF (LPRT) WRITE(6,190) (AV(I),I=1,NVVTX)	WR36	42
999	RETURN	WR36	43
C		WR36	44

```

160  FORMAT(10F7.0)
170  FORMAT(///,10X,30HVORTEX LOCATIONS AND BODY AXES,
* 70X,12H** READUVX **,//5H XV=,10F10.4)
180  FORMAT(/5H HV=,10F10.4)
190  FORMAT(/5H AZ=,10F10.4)
END

```

```

SUBROUTINE RDVEL(VA,WA,XPT,YPT,ZPT,NBODY,XSTART,X*LE)
C
C ROUTINE TO READ VELOCITY COMPONENTS AT CONTROL POINTS DEFINED IN
C PRTOPT.
C
C DIMENSION VA(1),WA(1),XPT(1),YPT(1),ZPT(1)
C REWIND 4
C
C WRITE(6,750)
C DO 100 I=1,NBODY
C IF (XPT(I).LT,XSTART) GO TO 100
C IF (YPT(I).GT,Y*LE) GO TO 100
C READ(4,745) IJ,XCP,YCP,ZCP,VA(I),WA(I)
C IF (END(4).NE.0.) GO TO 100
C WRITE(6,745) I,XPT(I),YPT(I),ZPT(I),VA(I),WA(I)
100 CONTINUE
C RETURN
C
745  FORMAT(15,5612.5)
750  FORMAT(14I,9X,34HVORTEX VELOCITIES READ FROM TAPE 4 ,
* 56X,12H** RDVEL **,
* //4X,14I,3X,3HXPT,9X,3HYPT,9X,3HZPT,10X,2HVA,10X,2HWA//)
END

```

```

SUBROUTINE SCAMP4(X,Y,N,NDA,NDB,DA,DB,C,S,M)
C
C GIVEN A SET OF N POINTS WHOSE ABSCISSAE FORM A STRICTLY MONOTONIC
C SEQUENCE, AND GIVEN A FIRST OR SECOND DERIVATIVE AT X(1) AND A
C FIRST OR SECOND DERIVATIVE AT X(N), TO FIND THE SMOOTHEST POSSIBLE
C CURVE PASSING RIGOROUSLY THROUGH THE GIVEN POINTS, SATISFYING THE
C SPECIFIED BOUNDARY CONDITIONS, AND POSSESSING CONTINUOUS FIRST AND
C SECOND DERIVATIVES. THE CRITERION OF SMOOTHNESS IS THE
C MINIMIZATION OF THE INTEGRAL OF THE SQUARE OF THE SECOND
C DERIVATIVE, AND THE CURVE FOUND IS ACCORDINGLY A CHAIN OF CURVES,
C I. E., A SEPARATE CURVE ON EACH INTERVAL (X(I),X(I+1))
C
C DIMENSION C(4,1),S(1),X(1),Y(1),Z(4)
C L=1
C K=1
C D1=DA
C D2=DB
C IF (N.NE,12) GO TO 10
C K=2
10 IF ((NDA+1).LT,0) D1=DERIV2(X,Y,X)
IF ((NDA+1).EQ,0) D1=DERIV1(X,Y,1)
N=[ABS(NDA)
60 IF ((NDB+1).LT,0) D2=DERIV2(X(N-3),Y(N-3),X(N))
IF ((NDB+1).EQ,0) D2=DERIV1(X(N-2),Y(N-2),3)

```

	NR=IABS(NOB)	NR38	25
	CALL COMCU(D1,D2,S,X,Y,M,N,NA,NS)	NR3A	26
	IF (M,NE,0) RETURN	NR3A	27
	K=1	NR3A	28
	DO 50 J=1,K	NR3A	29
	CALL CURIC2(X(J),Y(J),S(J),Z,M)	NR3A	30
	IF (M,FO,1) GO TO 20	NR3B	31
	M=100+J+M	NR3A	32
	RETURN	NR3A	33
20	IF (KK,EO,2) GO TO 40	NR3A	34
	DO 50 I=1,4	NR3B	35
	C(I,J)=Z(I)	NR3A	36
30	CONTINUE	NR3A	37
	GO TO 50	NR3A	38
40	L=7+J	NR3B	39
	C(L-6,1)=X(J)	NR3A	40
	C(L-5,1)=X(J+1)	NR3B	41
	C(L-4,1)=3.	NR3B	42
	C(L-3,1)=Z(1)	NR3B	43
	C(L-2,1)=Z(2)	NR3B	44
	C(L-1,1)=Z(3)	NR3B	45
	C(L,1)=Z(4)	NR3B	46
50	CONTINUE	NR3B	47
	NR0	NR3A	48
	RETURN	NR3A	49
	END	NR3B	50

	SUBROUTINE SOLVE	NR39	1
CDC	OVERLAY (L=8,3,0)	NR39	2
CDC	PROGRAM SOLVE	NR39	3
C		NR39	4
C	SOLVE FOR THE STRENGTHS OF THE BODY SOURCES AND WING VORTICES	NR39	5
C	WHICH SATISFY THE BOUNDARY CONDITION OF TANGENTIAL FLOW AT THE	NR39	6
C	PANEL CONTROL POINTS, ALSO DETERMINE THE CORRESPONDING PRESSURE	NR39	7
C	DISTRIBUTION AND THE FORCES AND MOMENTS ON THE CONFIGURATION.	NR39	8
C		NR39	9
C	THE PROGRAM MUST SOLVE A SYSTEM OF LINEAR EQUATIONS OF MAXIMUM	NR39	10
C	ORDER 1200, THE SOLUTION TECHNIQUE SELECTED CAN BE DESCRIBED AS A	NR39	11
C	BLOCKED JACOBI ITERATIVE METHOD, THE 1200 BY 1200 MATRIX IS	NR39	12
C	NATURALLY PARTITIONED INTO FOUR 600 BY 600 BLOCKS, EACH PARTITION	NR39	13
C	IS FURTHER SUBDIVIDED INTO BLOCKS OF MAXIMUM SIZE 60 BY 60, THE	NR39	14
C	MATRIX ELEMENTS IN EACH BLOCK ARE CAREFULLY CHOSEN TO REPRESENT	NR39	15
C	SOME WELL DEFINED FEATURE OF THE ORIGINAL CONFIGURATION, FOR	NR39	16
C	EXAMPLE, A BODY BLOCK REPRESENTS THE INFLUENCE OF ONE RING OF	NR39	17
C	PANELS AROUND THE BODY, WHILE A WING BLOCK REPRESENTS THE	NR39	18
C	INFLUENCE OF ONE CHORDWISE COLUMN OF WING PANELS, FOR WINGS USING	NR39	19
C	THE NON-PLANAR BOUNDARY CONDITION OPTION, THE BLOCK SIZE	NR39	20
C	CORRESPONDS TO THE TOTAL NUMBER OF PANELS ON THE UPPER AND LOWER	NR39	21
C	SURFACES OF THE COLUMN, THIS ENSURES DOMINANCE OF THE ELEMENTS	NR39	22
C	ALONG THE DIAGONAL	NR39	23
C		NR39	24
C	THE INITIAL ITERATION CALCULATES THE SINGULARITY STRENGTHS	NR39	25
C	CORRESPONDING TO EACH BLOCK IN ISOLATION, FOR THIS STEP, ONLY THE	NR39	26
C	DIAGONAL BLOCKS ARE PRESENT IN THE AERODYNAMIC MATRIX, ONCE THE	NR39	27
C	INITIAL APPROXIMATION TO THE SINGULARITY STRENGTHS IS DETERMINED,	NR39	28
C	THE INTERFERENCE EFFECT OF EACH BLOCK ON ALL THE OTHERS IS	NR39	29
C	CALCULATED BY MATRIX MULTIPLICATION, THE INCREMENTAL NORMAL	NR39	30
C	VELOCITIES OBTAINED ARE SUBTRACTED FROM THE NORMAL VELOCITIES	NR39	31
C	SPECIFIED BY THE BOUNDARY CONDITIONS, THIS PROCESS IS ITERATED	NR39	32

```

C UNTIL A CONVERGENCE TEST ON THE MAXIMUM RESIDUAL IS SATISFIED OR A *R39 33
C MAXIMUM NUMBER OF ITERATIONS IS REACHED.. *R39 34
C ----- *R39 35
C BODY ONLY VERSION: JUNE 1977 *R39 36
C THOSE PORTIONS OF THE ORIGINAL PROGRAM *UNAERO* WHICH PERTAINED *R39 37
C TO CALCULATIONS OF WINGS HAVE BEEN DELETED. *R39 38
C JOE MULLEN *R39 39
C ----- *R39 40
C *R39 41
C TAPE USAGE IN SOLVE= *R39 42
C TAPE7: SOLVE, READ ARRAY = CALCULATE BOUNDARY CONDITION *R39 43
C DIAGIN, READ D = INVERT DIAGONALS, N GT NMAX *R39 44
C SOLVE, REWIND *R39 45
C READ ARRAY = CALCULATE NORMAL VELOCITIES *R39 46
C REWIND *R39 47
C *R39 48
C TAPE8: SOLVE, REWIND *R39 49
C READ UA,VA,WA = CALCULATE U,V,W *R39 50
C REWIND *R39 51
C *R39 52
C TAPE9: PARTIN, REWIND *R39 53
C READ D = INVERT DIAGONAL BLOCKS, N LT NMAX *R39 54
C REWIND *R39 55
C DIAGIN, REWIND *R39 56
C READ D = INVERT DIAGONAL BLOCKS, N LT NMAX *R39 57
C ITRATE, REWIND *R39 58
C READ A = ITERATE WITH AIC FOR SOLN *R39 59
C *R39 60
C TAPE10: PARTIN, REWIND *R39 61
C WRITE D(INVERSE) *R39 62
C REWIND *R39 63
C DIAGIN, REWIND *R39 64
C WRITE D(INVERSE) = DIAGONAL BLOCKS *R39 65
C REWIND *R39 66
C ITRATE, REWIND *R39 67
C READ D(INVERSE) = ITERATE ON SOLUTION *R39 68
C *R39 69
C COMMON /JOPTNS/ IZ(50),NVLIN *R39 70
C * ,NCPDUT,XSTART,XMLE,N*CP,IPLGT(4),IPRT(5),IXZSYM *R39 71
C COMMON U(600),V(600),W(600),A(60,60),Z3(300),GW(600), *R39 72
C 1 GR(600),DZTDX(600) *R39 73
C COMMON /PARAM/ NBODY,NWING,NTAIL,LBC,THK,XMACH,ALPHA,BETA,ALPHAC *R39 74
C 1 ,PHIR,REFA,REFB,REFC,REFD,REFL,REFX,REFZ *R39 75
C COMMON /VELCOM/ NPOINT,NPART,IMAX,JMAX,NMAX,EM,IPRINT,NWTHK *R39 76
C 1 ,NBLOK,NBROW(20),NBLOK,NBROW(60) *R39 77
C COMMON /POINT / ARRAY(6000) *R39 78
C COMMON /MATCOM/ MATIN *R39 79
C *R39 80
C DIMENSION UA(600),VA(600),WA(600),CP(600),NS(600),CHORD(600) *R39 81
C 1 ,THET(600),DELTA(600),NB(600),NW(600),NT(600),DEL(600) *R39 82
C 2 ,COSTH(600),XPT(600),YPT(600),ZPT(600) *R39 83
C *R39 84
C EQUIVALENCE (U(1),NW(1)) *R39 85
C 1 ,(V(1),NH(1)), (N(1),NT(1)) *R39 86
C 2 ,(UA(1),A(1,1)), (VA(1),A(1,11)) *R39 87
C 3 ,(WA(1),A(1,21)), (CP(1),A(1,31)) *R39 88
C 4 ,(NS(1),A(1,41)), (GW(1),DEL(1)) *R39 89
C 5 ,(GH(1),COSTH(1)) *R39 90
C 6 ,(XPT(1),ARRAY(1)) (YPT(1),ARRAY(1801)) *R39 91
C 7 ,(ZPT(1),ARRAY(1201)), (THET(1),ARRAY(1801)) *R39 92
C 8 ,(DELTA(1),ARRAY(2401)), (CHORD(1),ARRAY(3601)) *R39 93
C REAL NH,N*PT,NS: *R39 94
C INTEGER COMPT *R39 95

```

	LOGICAL LRC,THK	WR39 9A
	DATA RADDEG/0.0174532926/	WR39 97
C	CALL CPUTIN(TIME0,NT,1)	WR39 98
	EM=YMACH	WR39 99
	VPASS=0	WR39 100
	REWIND 7	WR39 101
	REWIND 8	WR39 102
	ALP=ALPHA*RADDEG	WR39 103
	ALPHAC=ALPHA	WR39 104
	PHI=PHIP*RADDEG	WR39 105
	SINAL=SIN(ALP)	WR39 106
	COSAL=COS(ALP)	WR39 107
	SINB=0.	WR39 108
	SINA=SINAL	WR39 109
C		WR39 110
C		WR39 111
C	ALPHAC.....INCLUDED ANGLE OF ATTACK	WR39 112
C	PHI.....ANGLE OF ROLL	WR39 113
C	ALPHA.....ANGLE OF PITCH	WR39 114
C	BETA.....ANGLE OF SIDE SLIP	WR39 115
C	ALL IN DEGREES.	WR39 116
C		WR39 117
C		WR39 118
	IF (IYZSYM,EQ,0) GO TO 5	WR39 119
	SINB=SINAL*SIN(PHI)	WR39 120
	SINA=SINAL*COS(PHI)	WR39 121
	BETA=ASIN(SINB)/RADDEG	WR39 122
	ALPHA=ASIN(SINA)/RADDEG	WR39 123
	IF (IPRINT,NE,0) WRITE(6,430) ALPHAC,PHI,ALPHA,BETA	WR39 124
	CONTINUE	WR39 125
S		WR39 126
C		WR39 127
C	CALCULATE NORMAL VELOCITIES REQUIRED TO SATISFY BOUNDARY	WR39 128
C	CONDITIONS AT BODY CONTROL POINTS	WR39 129
C		WR39 130
20	IF (NBODY,EQ,0) GO TO 70	WR39 131
C		WR39 132
C	BOUNDARY CONDITION FOR BODY,CONTRIBUTION FROM FREE STREAM.	WR39 133
C		WR39 134
	READ (7) ARRAY	WR39 135
	DO 30 I=1,NBODY	WR39 136
	NR(I)=COSAL*SIN(DELTA(I))	WR39 137
	1 +COS(DELTA(I))*(-SINA+COS(THET(I))-SINB*SIN(THET(I)))	WR39 138
30	CONTINUE	WR39 139
C		WR39 140
C	-----	WR39 141
C	SOLVE MATRIX EQUATIONS - DIRECT SOLUTION IF MATRIX LESS THAN 60X60,	WR39 142
C	OTHERWISE ITERATIVE SOLUTION	WR39 143
C		WR39 144
70	IF (NBODY.LE.NMAX,AND,N*ING.LE.NMAX) GO TO 80	WR39 145
	IF (MATIN,EQ,1) CALL DIAGIN	WR39 146
	REWIND 10	WR39 147
	GO TO 90	WR39 148
80	CALL PARTIN	WR39 149
	IF (NBODY,EQ,0,OR,N*ING,EQ,0) GO TO 100	WR39 150
90	CALL ITRATE	WR39 151
100	REWIND 7	WR39 152
110	VPASS=VPASS+1	WR39 153
	IF (NBODY,EQ,0) GO TO 220	WR39 154
C		WR39 155
C	CALCULATE VELOCITY COMPONENTS ON BODY PANELS	WR39 156
C	U = UA*GB, V = VA*GB, W = WA*GB	WR39 157
C		WR39 158

```

      DO 100 I=1,NBODY                                WR39 154
      U(I)=0.                                         WR39 155
      V(I)=0.                                         WR39 161
      W(I)=0.                                         WR39 162
      READ (8) (UA(J),VA(J),WA(J),J=1,NBODY)         WR39 163
      DO 110 J=1,NBODY                                WR39 164
      U(I)=U(I)+UA(J)*GB(J)                           WR39 165
      V(I)=V(I)+VA(J)*GB(J)                           WR39 166
      W(I)=W(I)+WA(J)*GB(J)                           WR39 167
150  CONTINUE                                         WR39 168
140  CONTINUE                                         WR39 169
C                                                    WR39 170
C CALCULATE WING VELOCITY COMPONENTS HERE DUE TO VORTEX SHEDDING ----- WR39 171
C FROM WING:          V = V+V(VOR),   W = W+W(VOR)   WR39 172
C                                                    WR39 173
      IF (NPASS.EQ.1) READ (7) ARRAY                 WR39 174
      DO 145 I=1,NBODY                                WR39 175
      VA(I)=0.                                         WR39 176
145  WA(I)=0.                                         WR39 177
C                                                    WR39 178
C COMPUTE VORTEX VELOCITIES BY INTERPOLATION IN STRENGTHS USING VVELS WR39 179
C                                                    WR39 180
      CALL ELBOVT (VA,WA,XPT,YPT,ZPT,NBODY)          WR39 181
C                                                    WR39 182
C READ IN VELOCITY CONTRIBUTIONS FOR CONTROL POINTS WRITTEN OUT BY WR39 183
C PRTCPRT. VELOCITY COMPONENTS ARE COMPUTED BY VPATHL WR39 184
C                                                    WR39 185
      IF (NVLIN.EQ.1 .AND. NCPRT.LE.0)              WR39 186
      * CALL RDVEL(VA,WA,XPT,YPT,ZPT,NBODY,XWLE)    WR39 187
C                                                    WR39 188
C COMPUTE NORMAL VELOCITIES AT CONTROL POINTS        WR39 189
C                                                    WR39 190
      DO 190 I=1,NBODY                                WR39 191
180  NS(I)=(W(I)*COS(THET(I))-V(I)*SIN(THET(I)))*COS(DELTA(I))-U(I)* WR39 192
      I SIN(DELTA(I))                                  WR39 193
190  CONTINUE                                         WR39 194
      IF (IAH3(IPRINT).LT.2) GO TO 210              WR39 195
      WRITE (6,350) EM,ALPHAC,PHIC                 WR39 196
      WRITE (6,400)                                  WR39 197
      DO 200 N=1,NBODY                                WR39 198
      WRITE (6,420) N,GB(N),U(N),V(N),W(N),NS(N),VA(N),WA(N) WR39 199
200  CONTINUE                                         WR39 200
C                                                    WR39 201
C CALCULATE PRESSURES ON BODY PANELS, THEN          WR39 202
C CALCULATE FORCES AND MOMENT ON BODY               WR39 203
C                                                    WR39 204
210  COMPT=1                                          WR39 205
      DO 150 I=1,NBODY                                WR39 206
      V(I) = V(I)+VA(I)                               WR39 207
150  W(I) = W(I)+WA(I)                               WR39 208
      CALL PRESS(-BODY,EM,ALP,U,V,W,CP,CPSTAG,CPCRT,CPVAC,COMPT) WR39 209
      CALL FURFON(NBODY,NPASS,ALP,COMPT,.FALSE.)    WR39 210
C                                                    WR39 211
C COMPUTE FORCE AND MOMENTS FOR CONTROL POINTS BETWEEN XSTART AND XWLE WR39 212
C                                                    WR39 213
      CALL FURFON(-BODY,NPASS,ALP,COMPT,.TRUE.)     WR39 214
220  CONTINUE                                         WR39 215
340  WRITE (6,390) CPSTAG,CPCRT,CPVAC              WR39 216
      READING ?                                       WR39 217
C READING W                                          WR39 218
      CALL CPRTIME(TIME,DT,1)                         WR39 219
      TIME=TIME+DT                                    WR39 220
      WRITE (6,440) TIME,DT                          WR39 221

```

```

RETURN
350 FORMAT (///10X,16HVELOCITY ON BODY,84X,12H** SOLVE **,
* //5X,5HMACH=F6.5,3X,6HALPHA=F7.3,3X,5HPHIR=F7.3//)
390 FORMAT (/9H CPSTAG =,F10.5,3X,8HCPCRIT =,F10.5,3X,7HCPVAC =,F10.5)
400 FORMAT (8X,5HPANEL,3X,6HSOURCE, 7X,5HAXIAL,10X,7HLATERAL,10X,
1 8HVERTICAL,10X,6HNORMAL,8X,10HLAT.VORTEX,7X,10HVFR,VORTEX
2 //8X,3HNO.,4X,8HSTRENGTH,4X,8HVELOCITY,5(9X,8HVELOCITY))
420 FORMAT (I12,F10.5,G15.5,5G17.5)
430 FORMAT (/10X,25HCOMBINED ANGLES OF ATTACK,75X,12H** SOLVE **
* //5X,7HALPHAC=F10.4,5X,7H PHIR=F10.4
* //5X,7H ALPHA=F10.4,5X,7H BETA=F10.4)
440 FORMAT (/5X,18HEND SOLVE, TIME=F10.4,5X,3HDT=F10.4)
END

```

```

WB39 222
WB39 223
WB39 224
WB39 225
WB39 226
WB39 227
WB39 228
WB39 229
WB39 230
WB39 231
WB39 232
WB39 233
WB39 234

```

```

SUBROUTINE SORPAN(OPM,VPM,*PM)
C
C COMPUTE THE THREE COMPONENTS OF VELOCITY INDUCED AT A SPECIFIED
C CONTROL POINT BY A CONSTANT SOURCE DISTRIBUTION ON A
C QUADRILATERAL PANEL HAVING LONGITUDINAL TAPER AND INCLINED AT AN
C ANGLE DELTA TO THE FREE STREAM DIRECTION
C
COMMON /RODCOM/ AMACH,SA,CX,XC(4),YC(4),ZC(4),XI,YI,ZI,XJ,ZJ
DIMENSION SX(4),SM(4),DX(4),DY(4),DZ(4),D(4),E(4),F(4),G(4),
H(4),XPM(4),YPM(4),ZAX(4),AYM(4),RPM2(4)
C
REAL NUM
DATA EPS,PI/1,E=5,3.14195265/
C
EP2=EPS*EPS
RT2=1.-AMACH*AMACH
BT=SQRT(ABS(RT2))
HA2=RT2*SA*SA
TA=1.+HA2
IF (TA,LT,0.) GO TO 200
SM(3)=0.
DO 190 I=1,4
ZC(I)=ZJ-9A*(XJ-XC(I))
IF (I,LE,2) SM(1)=(YC(2)-YC(I))/CX
IF (I,GT,2) SM(3)=(YC(4)-YC(I))/CX
SM(2)=SM(1)
SM(4)=SM(3)
SM=SIGN(1.,SM(I))
RM2=RT2*SM(I)*SM(I)
TAM=TA+RM2
IF (ABS(TAM),LE,EPS) TAM=0.
SAM=SQRT(ABS(TAM))
SAXD=1./SAM
CPM=CX*SAM
DX(I)=XI-XC(I)
DY(I)=YI-YC(I)
DZ(I)=ZI-ZC(I)
IF (ABS(DX(I)),LE,EPS) DX(I)=0.
IF (ABS(DY(I)),LE,EPS) DY(I)=0.
IF (ABS(DZ(I)),LE,EPS) DZ(I)=0.
RPM2(I)=0.
DX2=DX(I)*DX(I)
DY2=DY(I)*DY(I)
DZ2=DZ(I)*DZ(I)
OR2=DX2+DY2+DZ2

```

```

WB40 1
WB40 2
WB40 3
WB40 4
WB40 5
WB40 6
WB40 7
WB40 8
WB40 9
WB40 10
WB40 11
WB40 12
WB40 13
WB40 14
WB40 15
WB40 16
WB40 17
WB40 18
WB40 19
WB40 20
WB40 21
WB40 22
WB40 23
WB40 24
WB40 25
WB40 26
WB40 27
WB40 28
WB40 29
WB40 30
WB40 31
WB40 32
WB40 33
WB40 34
WB40 35
WB40 36
WB40 37
WB40 38
WB40 39
WB40 40
WB40 41
WB40 42
WB40 43
WB40 44
WB40 45

```

	D2=DX2+HT2+DR2	WB40	46
	D(I)=0.	WB40	47
	IF (AMACH,GE,1.) DXZ=DX(I)-HTA*ABS(DZ(I))	WB40	48
	IF (AMACH,GE,1.,AND,DXZ,LT,0.) GO TO 170	WB40	49
	IF (D2,GT,0.) D(I)=SQRT(D2)	WB40	50
	XPM(I)=DX(I)+HT2*(SM(I)*DY(I)+SA*DZ(I))	WB40	51
	YMX(I)=DY(I)-SM(I)*DX(I)	WB40	52
	ZAX(I)=DZ(I)-SA*DX(I)	WB40	53
	AYM(I)=SA*DY(I)-SM(I)*DZ(I)	WB40	54
	IF (ABS(XPM(I)),LE,EPS) XPM(I)=0.	WB40	55
	IF (ABS(YMX(I)),LE,EPS) YMX(I)=0.	WB40	56
	IF (ABS(ZAX(I)),LE,EPS) ZAX(I)=0.	WB40	57
	IF (ABS(AYM(I)),LE,EPS) AYM(I)=0.	WB40	58
	IF (I,LE,2) RPM2(1)=YMX(I)**2+ZAX(I)**2+RT2*AYM(I)**2	WB40	59
	RPM2(2)=RPM2(1)	WB40	60
	IF (I,GT,2) RPM2(3)=YMX(I)**2+ZAX(I)**2+RT2*AYM(I)**2	WB40	61
	RPM2(4)=RPM2(3)	WB40	62
	IF (ABS(RPM2(I)),LE,FP2) RPM2(I)=0.	WB40	63
	RPM=SQRT(ABS(RPM2(I)))	WB40	64
	IF (RPM,LE,EPS) RPM=0.	WB40	65
	RPM=SAM*D(I)	WB40	66
	F(I)=0.	WB40	67
	DNUM=DX(I)+YMX(I)-BT2*DZ(I)+AYM(I)	WB40	68
	FNUM=D(I)*ZAX(I)	WB40	69
	IF (FNUM,EQ,0.,AND,DNUM,EQ,0.) GO TO 10	WB40	70
	IF (D(I),EQ,0.,OR,ZAX(I),EQ,0.) FNUM=0.	WB40	71
	F(I)=ATAN2(FNUM,DNUM)	WB40	72
	IF (D(I),EQ,0.) F(I)=F(I)*SIGN(1.,ZAX(I))	WB40	73
10	IF (TAM) 100,90,20	WB40	74
20	IF (AMACH,GT,1.,AND,D(I),FR,0.) GO TO 70	WB40	75
	IF (RPM,LE,EPS) GO TO 40	WB40	76
	NUM=XPM(I)+CPM	WB40	77
	G(I)=ALOG(NUM/(BTA*RPM))*SAM0	WB40	78
	GO TO 160	WB40	79
40	SX(I)=SIGN(1.,XPM(I))	WB40	80
	IF (AMACH,LT,1.) GO TO 50	WB40	81
	IF (I,EQ,1,AND,XPM(I),LT,CPM) GO TO 130	WB40	82
	IF (I,EQ,3,AND,XPM(I),LT,CPM) GO TO 140	WB40	83
50	IF (I,EQ,2) SGN12=SX(1)*SX(2)	WB40	84
	IF (I,EQ,4) SGN34=SX(3)*SX(4)	WB40	85
	IF (XPM(I)) 60,70,80	WB40	86
60	IF (I,EQ,2,AND,SGN12,LT,0.) GO TO 150	WB40	87
	IF (I,EQ,4,AND,SGN34,LT,0.) GO TO 160	WB40	88
	G(I)=-ALOG(ABS(XPM(I)))*SAM0	WB40	89
	GO TO 160	WB40	90
70	G(I)=0.	WB40	91
	GO TO 160	WB40	92
80	G(I)=ALOG(XPM(I))*SAM0	WB40	93
	GO TO 160	WB40	94
90	G(I)=0.	WB40	95
	IF (XPM(I),GT,HTA*RPM) G(I)=D(I)/XPM(I)	WB40	96
	GO TO 160	WB40	97
100	G(I)=0.	WB40	98
	ARG=SIGN(1.,XPM(I))	WB40	99
	IF (RPM,NE,0.) ARG=XPM(I)/(HTA*RPM)	WB40	100
	IF (ARG,GE,1.) GO TO 160	WB40	101
	IF (ARG,LE,-1.) GO TO 110	WB40	102
	IF (D(I),GT,0.) G(I)=ACOS(ARG)*SAM0	WB40	103
	GO TO 160	WB40	104
110	AM2=SA+SA+S*(I)*SM(I)	WB40	105
	TRM1=(SM(I)*DY(I)+SA*DZ(I)+ABS(AYM(I)+SAM))/AM2	WB40	106
	IF (DX(I),GT,TRM1) GO TO 120	WB40	107
	F(I)=0.	WB40	108


```

IF (SSM.GT.0.) F(I)=PI*SIGN(1.,ZAX(I))      WR40 109
GO TO 160                                     WR40 110
120 IF (SSM*YMX(1).GE.0.) GO TO 160         WR40 111
G(I)=PI*SAMO                                 WR40 112
GO TO 160                                     WR40 113
130 G(1)=500.*SAMO                           WR40 114
IF (AMACH.LT.1.) G(2)=-G(1)                 WR40 115
GO TO 160                                     WR40 116
140 G(3)=500.*SAMO                           WR40 117
IF (AMACH.LT.1.) G(4)=-G(3)                 WR40 118
160 H(I)=0.                                   WR40 119
HARG=-HTA*DY(I)                              WR40 120
IF (D(I).EQ.0. .AND. HARG.EQ.0.) GO TO 180  WR40 121
IF (AMACH.LT.1.) H(I)=BTA*.5*ALOG((D(I)+HARG)/(D(I)-HARG)) WR40 122
IF (AMACH.GT.1.) H(I)=BTA*ATAN2(D(I),HARG)   WR40 123
GO TO 180                                     WR40 124
170 F(I)=G.                                  WR40 125
G(I)=0.                                       WR40 126
H(I)=0.                                       WR40 127
AYM(I)=0.                                     WR40 128
YMX(I)=0.                                     WR40 129
ZAX(I)=0.                                     WR40 130
XPM(I)=0.                                     WR40 131
DPM=0.                                       WR40 132
RPM=0.                                       WR40 133
RPM2(2)=RPM2(1)                              WR40 134
RPM2(4)=RPM2(3)                              WR40 135
180 E(I)=H(I)+HT2*SM(I)*G(I)                 WR40 136
190 CONTINUE                                 WR40 137
TAD=1./TA                                     WR40 138
F14=(E(1)-E(2)-E(3)+E(4))*TAD                WR40 139
F14=(F(1)-F(2)-F(3)+F(4))*TAD                WR40 140
G14=G(1)-G(2)-G(3)+G(4)                     WR40 141
R4PI=1./(4.*PI)                              WR40 142
IF (AMACH.GT.1.) R4PI=2.*R4PI                 WR40 143
UPM=R4PI*(E14/HT2-SA*F14)                    WR40 144
VPM=R4PI*G14                                 WR40 145
WPM=R4PI*(F14+SA*E14)                        WR40 146
RETURN                                         WR40 147
200 WRITE (6,210)                             WR40 148
STOP                                          WR40 149
210 FORMAT (1H0,43HERROR = BODY PANEL SLOPE EXCEEDS MACH ANGLE) WR40 150
END                                           WR40 151

```

```

SUBROUTINE VELCMP                             WR41  1
CDC OVERLAY (LWB,2,0)                         WR41  2
CDC PROGRAM VELCMP                            WR41  3
C                                              WR41  4
C COMPUTE THE VELOCITY COMPONENTS (U,V,W) AT THE PANEL CONTROL WR41  5
C POINTS AND FORM THE AERODYNAMIC INFLUENCE COEFFICIENT MATRICES WR41  6
C                                              WR41  7
C TAPE USAGE IN VELCMP=                       WR41  8
C TAPES: READ XMACH,ALPHA,PHIR                WR41  9
C                                              WR41 10
C TAPF7: VELCMP, RE=IND                        WR41 11
C READ ARRAY = CALCULATE BODY INDUCED VELOCITIES WR41 12
C WRITE D = DIAGONAL BLOCKS, N GT NMAX       WR41 13
C RE=IND                                       WR41 14

```

```

C   TAPE8:  VELCOMP,  REWIND                                WR41  15
C   HOOVEL,  WRITE 08,09,10 = COMPONENT VELOCITY MATRICES WR41  16
C   VELCOMP,  REWIND                                       WR41  17
C   TAPE9:  VELCOMP,  REWIND                                WR41  18
C   HOOVEL,  WRITE AN = NORMAL VELOCITY MATRIX             WR41  19
C   VELCOMP,  REWIND                                       WR41  20
C   TAPE10: VELCOMP,  REWIND                                WR41  21
C   HOOVEL,  WRITE ON = DIAGONAL BLOCKS, N GT NMAX       WR41  22
C   VELCOMP,  REWIND                                       WR41  23
C   READ 0 = COPY TO TAPE7                                WR41  24
C   REWIND                                               WR41  25
C   REWIND                                               WR41  26
C   REWIND                                               WR41  27
C   TAPE11: NOT USED BY BODY VERSION                       WR41  28
C   WR41  29
C   COMMON /JOPTNS/ IZ1(63),NACPT,IPLOT(4),IPRT(5),IXZSYN WR41  30
C   COMMON /PARAM / NBODY,NWING,NTAIL,LHC,THK,XMACH,ALPHA,BETA,ALPHAC WR41  31
C   1 ,PHIR,REFA,REFB,REFC,REFD,REFL,REFX,REFZ           WR41  32
C   COMMON /VELCOM/ NPOINT,NPART,IMAX,IMAX,NMAX,EM,IPRINT,NWTHK WR41  33
C   1 ,NABLOCK,NBROK(20),NBBLOCK,NBROK(50)              WR41  34
C   COMMON /NEWCOM/K1,KWAF,KWAFOR,KRADX(4),KFORX(4),KFUS,MAX,K4,K5 WR41  35
C   1 ,KF(6),KAN(6),KFINDR(6),KANOR(6),KOL,NCPT,LOCPT(20),XCPT(20) WR41  36
C   COMMON BLOCK(7500)                                     WR41  37
C   COMMON /POINT / ARRAY(6000)                           WR41  38
C   COMMON /SEG / NSEG,NROW(20),NCOL(20),COSS(20),SINS(20) WR41  39
C   1 ,BTE(20),HWT(20),SPRW(20),XLE-(20),BLE(20),ZLE-(20),ZB(60) WR41  40
C   COMMON /MATCOM/ MATIN                                  WR41  41
C   WR41  42
C   DIMENSION XLE(600),XPT(600),DEL(600),COSTH(600),XRT(600),YRT(600), WR41  43
C   1 ZRT(600),YPT(600),ZPT(600),CHORD(600),OZTOX(600),IT(600), WR41  44
C   2 R(60,60),DELTA(600),DELTI(600)                     WR41  45
C   WR41  46
C   EQUIVALENCE                                           WR41  47
C   1 , (COSTH(1),BLOCK(601)), (OEL(1),BLOCK(1)), WR41  48
C   2 , (YRT(1),BLOCK(4501)), (XRT(1),BLOCK(3901)) WR41  49
C   3 , (IT(1),BLOCK(5701)), (ZRT(1),BLOCK(5101)) WR41  50
C   4 , (OZTOX(1),BLOCK(6901)), (CHORD(1),BLOCK(6301)) WR41  51
C   5 , (XPT(1),ARRAY(1)), (YPT(1),ARRAY(601)) WR41  52
C   6 , (ZPT(1),ARRAY(1201)), (O(1),ARRAY(1801)) WR41  53
C   7 , (DELTA(1),ARRAY(2401)), (DELTI(1),ARRAY(4801)) WR41  54
C   7 , (XLE(1),ARRAY(5401)) WR41  55
C   LOGICAL LRC,SUR                                       WR41  56
C   WR41  57
C   MATIN=0                                               WR41  58
C   NMAX=60                                              WR41  59
C   EPS=1.E-3                                           WR41  60
C   CALL CPU TIME(TIME0,DT,1)                            WR41  61
C   WR41  62
C   READ IN MACH NUMBER AND ANGLE OF ATTACK              WR41  63
C   WR41  64
C   READ (5,290) XMACH,ALPHA,PHIR                        WR41  65
C   ALPHAC=ALPHA                                         WR41  66
C   IF (XMACH.LT.0..OR.XMACH.EQ.EM) RETURN              WR41  67
C   IF (TANS(IPRINT).GT.1) WRITE(6,500)                  WR41  68
C   SUR=XMACH,LT.1.                                      WR41  69
C   BETAM=SQRT(TANS(XMACH*XMACH-1.))                     WR41  70
C   RETAD=1./BETAM                                       WR41  71
C   NABLOCK=0                                           WR41  72
C   NABLOCK=0                                           WR41  73
C   REWIND 8                                             WR41  74
C   REWIND 9                                             WR41  75
C   REWIND 10                                           WR41  76
C   REWIND 10                                           WR41  77

```

NPPOINT=NCPT	WR41	78
NPANEL=NBODY+NWING	WR41	79
IF (NPANEL.EQ.0) RETURN	WR41	80
REWIND 7	WR41	81
NCPT=NWING	WR41	82
CB IF (NWING.EQ.0) GO TO 70	WR41	83
C	WR41	84
C COMPUTE SIZES OF WING DIAGONAL BLOCKS, THEN	WR41	85
C COMPUTE CHORDWISE CONTROL POINT LOCATIONS ON WING	WR41	86
C (PLANAR BOUNDARY CONDITION OPTION ONLY)	WR41	87
C	WR41	88
C ----- INSERT WING BLOCK CODE HERE -----	WR41	89
C	WR41	90
70 EMEYMACH	WR41	91
NPART=1	WR41	92
WRITE (6,510) NPART	WR41	93
WRITE (6,250) NWING,NBODY,NCPT,NSEG	WR41	94
IF (NSEG.EQ.0) GO TO 75	WR41	95
WRITE (6,260) NSEG,(NROW(N),N=1,NSEG)	WR41	96
WRITE (6,270) NSEG,(NCOL(N),N=1,NSEG)	WR41	97
75 CONTINUE	WR41	98
CB IF (NWING.NE.0) READ (7) ARRAY,CHORD,CZTDX	WR41	99
IF (NBODY.EQ.0) GO TO 100	WR41	100
READ (7) ARRAY	WR41	101
DO 80 N=1,NBODY	WR41	102
XHT(N)=XPT(N)	WR41	103
YHT(N)=YPT(N)	WR41	104
ZHT(N)=ZPT(N)	WR41	105
80 CONTINUE	WR41	106
NPPOINT=NBODY	WR41	107
90 IF (NPART.EQ.1) WRITE (6,320)	WR41	108
C	WR41	109
C COMPUTE VELOCITY COMPONENTS INDUCED BY BODY PANELS	WR41	110
C	WR41	111
CALL BODVEL	WR41	112
CALL CPUTIME(TIME,DT,1)	WR41	113
WRITE(6,360) TIME,DT,NPART	WR41	114
100 CONTINUE	WR41	115
160 REWIND 8	WR41	116
REWIND 9	WR41	117
REWIND 10	WR41	118
NATIN=1	WR41	119
C	WR41	120
C WRITE DIAGONAL BLOCKS OF AERODYNAMIC MATRIX ON TAPE 7	WR41	121
C	WR41	122
IF (NBODY.EQ.0) GO TO 190	WR41	123
NBLOK=1	WR41	124
NBROW(1)=NBODY	WR41	125
IF (NBODY.LE.NMAX) GO TO 190	WR41	126
NBLOK=0	WR41	127
DO 180 KFU=1,KFUS	WR41	128
NR=KPADX(KFU)-1	WR41	129
NC=KFORDX(KFU)-1	WR41	130
DO 180 NN=1,NC	WR41	131
NBLOK=NBLOK+1	WR41	132
NBROW(NBLOK)=NR	WR41	133
DO 170 N=1,NR	WR41	134
READ (10) (D(N,N),N=1,NR)	WR41	135
170 CONTINUE	WR41	136
WRITE (7) D	WR41	137
180 CONTINUE	WR41	138
190 CONTINUE	WR41	139
CB IF (NWING.LE.NMAX.OR.NWING.EQ.0) GO TO 220	WR41	140

08	TRANSFER WING DIAGONAL BLOCKS	NR41 141
220	NWBLOK=1	NR41 142
	NBROW(1)=N*WING	NR41 143
230	REWIND 7	NR41 144
	REWIND 10	NR41 145
	WRITE(6,280) NRHLOK,NWBLOK	NR41 146
	CALL CPUTIM(TIME,DT,1)	NR41 147
	DT=TIME-TIME0	NR41 148
	WRITE(6,370) TIME,DT	NR41 149
	RETURN	NR41 150
250	FORMAT(7H N*WING=,I6,2X,6HNRBODY=,I6,2X,5HNCPT=,I6,2X,5HNSEG=,I6)	NR41 151
260	FORMAT(13H NRQA(N),N=1,,I4/(1X,20I6))	NR41 152
270	FORMAT(13H NRQL(N),N=1,,I4/(1X,20I6))	NR41 153
280	FORMAT(10X,7HNRHLOK=,I6,2X,7HNRBLOK=,I6)	NR41 154
290	FORMAT(10F7.0)	NR41 155
300	FORMAT(1H1,10X,38HAERODYNAMIC VELOCITY MATRIX COMPUTATION, * 63X,12H** VELCMP **)	NR41 156
310	FORMAT(/// 12H PARTITION =,I3)	NR41 158
320	FORMAT(26H INFLUENCE OF BODY ON BODY)	NR41 159
360	FORMAT(/10X,18HEND BODYVEL, TIME=,F10.4,5X,3HDT=,F10.4 * ,5X,6HNPART=,I3)	NR41 160
370	FORMAT(/10X,18HEND VELCMP, TIME=,F10.4,5X,3HDT=,F10.4) END	NR41 162 NR41 163

	SUBROUTINE VVELS(NV,YY,ZZ,VX,VY,G,AB,RR,V,W,VRTMAX)	NR42 1
C		NR42 2
C	THIS SUBROUTINE COMPUTES PERTURBATION VELOCITY COMPONENTS DUE TO	NR42 3
C	NV EXTERNAL VORTICES AND THEIR IMAGES INSIDE A BODY WITH	NR42 4
C	ELLIPTICAL CROSS SECTION	NR42 5
C		NR42 6
C		NR42 7
C	DIMENSION VX(1),VY(1),G(1)	NR42 8
C		NR42 9
C	COMMON/COM1/A2,B2,R2	NR42 10
	COMMON/COM2/SIG2,M2	NR42 11
C		NR42 12
C	COMPLEX TO,VI,DSOT,Z,DSOZ,SI,SIR,SU,TAU,CT,VEL	NR42 13
C		NR42 14
C	EXTERNAL Z,DSOZ	NR42 15
	PI=3.14159265	NR42 16
	TLC=0.001	NR42 17
	CI=CMPLX(0.0,1.0)	NR42 18
	A2=AB*AB	NR42 19
	R2=RR*RR	NR42 20
	APP=AR*RR	NR42 21
	APR2=APR*APR	NR42 22
	R=0.5*APR	NR42 23
	H2=APR2	NR42 24
	R2=R*R	NR42 25
	SIG2=R2	NR42 26
	TO=CMPLX(YY,ZZ)	NR42 27
	SO=Z(TO)	NR42 28
	VI=CMPLX(0.0,0.0)	NR42 29
	DSOT=DSOZ(SU)	NR42 30
C		NR42 31
C	LOOP OVER THE NUMBER OF VORTICES,NV	NR42 32
C		NR42 33

	DO 1 I=1,NV	WR42	34
	TAU=CMPLX(VX(I),VY(I))	WR42	35
	SI=Z(TAU)	WR42	36
	SIB=CONJG(SI)	WR42	37
	D=CAHS(SI-SB)	WR42	38
	IF(D.LE.TLC) GO TO 2	WR42	39
	V1=V1-G(I)/(SD-SI)	WR42	40
2	CONTINUE	WR42	41
	D=CAHS(SD-R2/SIB)	WR42	42
	IF(D.LE.TLC) GO TO 1	WR42	43
1	V1=V1+G(I)/(SD-R2/SIB)	WR42	44
	CONTINUE	WR42	45
C		WR42	46
	VEL=0.5*CI*V1*DSDT/PI	WR42	47
	V=REAL(VEL)	WR42	48
	W=AIMAG(VEL)	WR42	49
	AV=ABS(V)	WR42	50
	AW=ABS(W)	WR42	51
	IF(V.GT.0.0.AND.AV.GE.VRTMAX) V=VRTMAX	WR42	52
	IF(V.LT.0.0.AND.AV.GE.VRTMAX) V=-VRTMAX	WR42	53
	IF(W.GT.0.0.AND.AW.GE.VRTMAX) W=VRTMAX	WR42	54
	IF(W.LT.0.0.AND.AW.GE.VRTMAX) W=-VRTMAX	WR42	55
	RETURN	WR42	56
	END	WR42	57

	COMPLEX FUNCTION Z(CT)	WR43	1
C		WR43	2
C	THIS FUNCTION SUBROUTINE CALCULATES THE SIGMA VALUE IN THE	WR43	3
C	TRANSFORMED (CIRCLE) PLANE FOR GIVEN TAU IN THE PHYSICAL PLANE	WR43	4
C	FOR AN ELLIPTICAL BODY WITH WINGS	WR43	5
C		WR43	6
	COMMON/COM2/SIG2,H2	WR43	7
	COMMON/COM3/ZR,ZI	WR43	8
	COMMON/COM4/G2,G1	WR43	9
	COMMON/COM6/W2,W	WR43	10
C		WR43	11
C		WR43	12
	COMPLEX W,G1,G2,CT,*2,CBLU	WR43	13
C		WR43	14
	EXTERNAL DBLU	WR43	15
C		WR43	16
	Z=DRBLU(CT)	WR43	17
	G1=**SIG2/W	WR43	18
	G2=G1+G1-W2	WR43	19
	Y=AIMAG(G2)	WR43	20
	AY=1.0	WR43	21
	IF(Y.LT.0.0) AY=-1.0	WR43	22
	Y/=AIMAG(G1)	WR43	23
	AYZ=1.0	WR43	24
	IF(YZ.LT.0.0)AYZ=-1.0	WR43	25
	G2=CSQRT(G2)*AY*AYZ	WR43	26
	IF((ABS(YZ).LE.0.0).AND.(REAL(G1).LT.0.0)) G2=CMPLX(-REAL(G2),	WR43	27
	AIMAG(G2))	WR43	28
1	Z=0.5*(G1+G2)	WR43	29
	IF((ABS(ZI).LE.0.0).AND.(ABS(ZR).LE.0.0)) Z=CMPLX(ZR+ABS(REAL(Z)),	WR43	30
	ZI+ABS(AIMAG(Z)))	WR43	31
	RETURN	WR43	32
	END	WR43	33

APPENDIX L

DESCRIPTION OF PROGRAM VPATH2 AND VPATHL

This appendix is concerned with the description of the vortex chasing programs. They are used to accompany programs DEMON2 and WDYBDY in accordance with the procedures described in section 5 of this report.

Program VPATH2 computes the paths of external vortices along a body with circular cross section with or without cruciform fins attached to it. The configuration can be pitched and rolled. The cruciform fins may have arbitrary deflection angles. Program VPATHL determines the paths of external vortices along a body with elliptical cross section with or without a monoplane wing in the midwing position.

In what follows, the basic theoretical method is described. The geometrical characteristics accounted for in the programs are listed. This is followed by a description of the flow of the programs and program operation. Program limitations and precautions are discussed and the input and output described. Finally program listings are given for programs VPATH2 and VPATHL.

Program Description

The vortex chasing scheme implemented in programs VPATH2 and VPATHL makes use of crossflow plane solutions obtained from slender-body theory. Because of the linear nature of the problem it is possible to superimpose different solutions.

Fundamentally, at given axial stations, velocity components are computed in the crossflow plane at the points occupied by a finite set of external vortices in the presence of a wing-body combination. In this calculation, mutual interaction between the vortices, the interaction between the vortices and the wing-body, the effects of included angle of attack and roll, and fin deflection (if applicable) must be included. Once the lateral velocity components are known, the vortex locations at the next axial station downstream can be determined by means of an integration scheme. The vortices move from one axial station to the next in accordance with the flow angle calculated from the lateral velocity components.

APPENDIX L

Appendix I contains the crossflow plane solutions for 8 different conditions and/or cross sectional shapes. In both programs, the calculation is started at given axial locations (starting station) with a set of vortices with specified strengths and lateral coordinates. The geometry in the crossflow plane is specified a priori and the programs proceed to integrate in the downstream direction to obtain the vortex paths.

Once the vortex paths are calculated over the length of body or body-wing of interest, the programs can calculate velocity components induced by the set of vortices at specified points. In this process, the vortices are taken to be in the presence of the body only, i.e., the lifting surfaces are not accounted for. This approach serves two purposes. First, for wing-body combinations, the effects of the external vortices with known paths induced in the flow tangency condition can be applied at the control points of the constant u-velocity panels laid out over the wings or fins in program DEMON2, Appendix J. Second, the velocity components induced by the external vortices in the presence of the body only are included in the calculation of pressures on the fins and the body surface. Further discussions are given in sections 3.4 and 4.3 of this report.

Geometrical Characteristics

This section describes the geometrical characteristics which can be accounted for by the programs. Since the two programs were written for different cross sections, the geometric details of the configurations will be listed separately for each program.

Program VPATH2

Body: axisymmetric, constant cross-sectional area

Lifting surfaces: cruciform fins, each fin planar, may have breaks in sweep, each fin can be arbitrarily deflected

Program VPATHL

Body: elliptic in cross section, ellipticity constant, may change size of cross section

Lifting surfaces: monoplane wing in midwing position, may have breaks in sweep

Calculation Procedure

In this section, the sequence of the calculative processes is indicated. The description will be given for both programs simultaneously. Important differences between programs VPATH2 and VPATHL will be pointed out, however.

After reading in the run title, body geometry and wing or fin geometry, the programs proceed to define the side edge of the wing or fin. Flow conditions, the permissible error used in the integration scheme and maximum magnitude of the vortex induced velocity components are then input to both programs. In addition, program VPATH2 reads in the fin deflection angles.

Both programs proceed to read the lateral coordinates of the vortices at the axial station at which they start. The geometrical characteristics of the configuration at hand and flow conditions are written out. Leading- and side-edge vorticity characteristics, if applicable, are then input to both programs. Their influence will be included in the computation of the vortex paths. Program VPATH2 expects this information for 4 fins, program VPATHL expects information for both sides of the monoplane wing.

At the axial station where the vortex path integration is started, program VPATH2 calculates the body radius, the distance from the body centerline to the edge of the lifting surfaces as seen in this crossflow plane. For this and all subsequent axial stations, subroutine SHAPE of program VPATH2 performs this task. For bodies with elliptical cross section (and with constant ellipticity), subroutine SHAPE of program VPATHL computes the horizontal and vertical semiaxes in addition to the distance out to the edge of the monoplane wing as seen in the crossflow plane.

After printing the vortex strengths and the initial vortex coordinates, both programs call on subroutine DASCURU to compute the flow angles at the vortex locations and to determine the vortex locations at the next downstream axial station. To accomplish the former, subroutine DASCURU calls subroutine F. The latter contains calls to subroutines implemented with the various crossflow plane solutions described in Appendix I. The two programs are equipped with different versions of

APPENDIX L

subroutine F on account of the different configurations and/or conditions handled.

Consider program VPATH2 first. It treats a cruciform fin-body combination or body alone. Subroutine F in this program first calculates the lateral velocity components at the vortex points due to angle of attack and roll by calling subroutine PITROL. The crossflow plane solution programmed in PITROL is given in Appendix I, section 2. The source term is omitted in that it leads to unbounded potential at infinity. If two opposite fins are symmetrically deflected, subroutine SYMFIN is called from subroutine F to compute an additional contribution to the velocity components at the vortex points. The crossflow plane solution is given in Appendix I, section 3. If only one fin is deflected or if all fins are arbitrarily deflected, subroutine CRUCI is called by subroutine F to calculate the contribution to the velocity components at the vortex points due to this condition. Then, if edge vorticity associated with the lifting surfaces is specified, its contribution to the velocity components at the vortex points is also computed. Subroutine VVELS is used to accomplish this task. The solution implemented in this subroutine is a specialized adaptation of the solution given in Appendix I, section 1. Finally, subroutine F calls subroutine VOTEX to compute the contributions to the velocity components at each vortex point due to the effect of all vortices in the presence of the cruciform fin-body combination. The solution for this sub problem is given in Appendix I, section 1.

The version of subroutine F in program VPATHL treats elliptical cross sections with or without a monoplane wing. The effects of included angle of attack and roll are calculated by a different version of PITROL. The crossflow plane solution is given in Appendix I, section 6. Provision exists to account for a growing body by the use of subroutine EXPAND. The associated solution is given in Appendix I, section 8. Contributions from specified vorticity associated with the monoplane wing edges are calculated with another version of subroutine VVELS. It employs an adaptation of the solution given in Appendix I, section 5. Finally, the contributory effects due to all vortices, in the presence of the monoplane wing-body, at each vortex location is computed by a call to a different version of subroutine VOTEX. The crossflow plane solution implemented in

it is described in Appendix I, section 5. The solutions given in sections 5 and 7 in Appendix I only differ by angles of pitch and sideslip effects.

With the lateral velocities determined by subroutine F at each vortex location and passed back to subroutine DASCURU, the vortices are moved to the next axial station in accordance with the flow angle calculated from the velocity components. The velocity calculation process is repeated and the vortices moved to the next axial station in the downstream direction. This process is repeated until the last axial station, specified in the input, is reached.

Both programs can proceed with the calculation of velocity components in the crossflow plane induced by the vortices at specified points. As mentioned earlier in this appendix, for the purpose of inclusion in the wing boundary condition implemented in program DEMON2, the vortices are considered to be in the presence of the body only.

Program Operation

Programs VPATH2 and VPATHL are written in the FORTRAN IV language (029 punch) and has been run on the CDC 6600 machine belonging to Boeing Computer Services, Inc. Core requirement is about 60K octal words.

In addition to the standard input (TAPE5) and output (TAPE6) tapes, the program may require additional devices such as disc files or tapes for reading or storing data sets generated when certain options are used. TAPE4 and TAPE7 are used for this purpose. One data set would consist of a set of control-point coordinates and the other would contain a set of perturbation velocities. It should also be noted that these programs contain complex variables.

Running time required by both programs is a function of the length over which the vortex paths are to be calculated and the permissible error $E5$ specified in the input. As an example, with $E5$ equal to 0.0001, running time should not exceed 5 seconds for a pitched and rolled configuration with about 8 external vortices including the computation of vortex induced velocity components at 268 field points.

As an aid in debugging and quick visual inspection, both programs are equipped with a simplified plotting capability. They should only be used with few vortices and over a short running length.

APPENDIX L

Program Limitations and Precautions

There are certain limitations associated with the dimension statements programmed in the vortex tracking programs VPATH2 and VPATHL. The number of vortices to be tracked should not exceed 30. One fin of a cruciform fin configuration or one half of a monoplane wing must be described by a maximum of 7 points in planform. This poses a limitation on the number of allowable breaks in sweep. Some care must be exercised in the choice of the permissible error, E5. If its value is orders of magnitude smaller than 10^{-4} , computation time may become unduly long. The number of stations at which the vortex coordinates are printed in the output cannot exceed 50.

Subroutine DASCURU adjusts the integration interval in accordance with the permissible error E5. If for some reason it cannot satisfy the built in criteria for deciding whether or not given stepsize is accurate enough, DASCURU will stop reducing the stepsize after 32 attempts. The program will then stop and register STOP40. A faulty crossflow plane flow field can cause this problem. At times, the problem can be alleviated by reducing the difference between the first and second stations XIP (see input section).

At the present time, program VPATHL is limited to elliptical cross sections with constant ellipticity. Program VPATH2 cannot handle expanding or contracting axisymmetric cross sections.

Both programs may suffer from slight numerical errors when the running length is very long. It is suspected to be caused by errors introduced by the integration scheme in subroutine DASCURU. This behavior can be observed when chasing a set of vortices, initially symmetrically located relative to the free stream vector in the cross flow plane, along an axisymmetric body of considerable length (15 radii long).

A further limitation occurs when a vortex comes very close to the leading edge of a lifting surface. The computer program will tend to move the vortex away from the lifting surface, or it may move along the contour in an unrealistic fashion. This constitutes a limit to the theory used in the programs. In reality, a vortex is made up of a cloud of small vortices with cores in which the lateral velocity components go to zero towards the center. In any event, such a vortex cloud passes right over

(and under) the lifting surface in question. It is recommended in such a case to forego the vortex chasing calculation and to assume that the vortex moves back parallel to the body centerline.

Description of Input

This section contains a description of the input for programs VPATH2 and VPATHL. There are some differences in the input on account of the differences in the configurations treated by each program. The input for program VPATH2 will be described first. Then, the description of the input for program VPATHL follows with references made to items of the input for program VPATH2. Listings of all input variables are given at the end of the respective input descriptions.

Input for program VPATH2

Item 1

The first card serves as identification and may contain any alphanumeric information desired. This information is printed on the first page of the output.

Item 2

The second card contains indices concerning the body and lifting-surface geometry, control indices governing the number of axial stations at which information is to be printed, reading in control-point coordinates, writing velocity components, amount of output, and the option to print plots in the program generated output.

Item 3

This card contains the endpoints for each body section for which coefficients describing a meridian will be given (Item 4). Usually, only one endpoint is required; that is, one body section will be considered.

Item 4

For each body section, a set of coefficients (7 maximum) are specified on this card. They are members of the polynomial shown below and programmed in subroutine SHAPE.

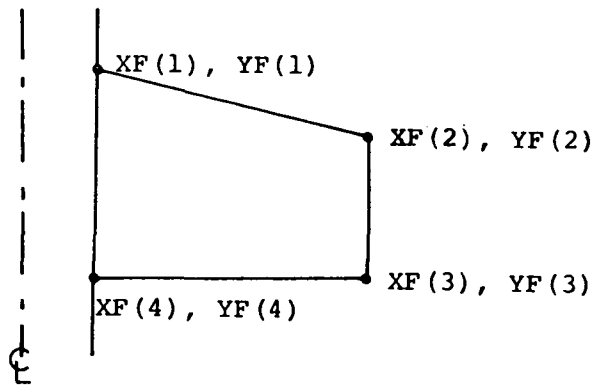
APPENDIX L

$$\frac{r}{\ell} = c_1 + c_7 \sqrt{c_2 \left(\frac{x}{\ell}\right)^2 + c_3 \left(\frac{x}{\ell}\right) + c_4} + c_5 \left(\frac{x}{\ell}\right) + c_6 \left(\frac{x}{\ell}\right)^2 \quad (L1)$$

where C_1 through C_7 are the coefficients, r is the local body radius, and ℓ is the body length. The body length ℓ equals the difference of the endpoints specified in item 3.

Item 5

The coordinates of the fin planform outline corner points are read in if a fin or wing is present. Only one fin or one wing half needs to be described. The XF and YF coordinates are shown in the example shown below; XF is measured from the body nose and YF is measured from the body



centerline. Note: the axial coordinate of the trailing edge of the rootchord must be made to be slightly larger than the axial coordinate of the trailing edge of the side edge.

Item 6

Flow conditions and fin deflection angles, if applicable, are specified on this card. In addition, the permissible error, E5, used as a criterion in the integration scheme programmed in subroutine DASCURU is read in. Note: E5 must not be taken too small or the running time required may become unduly large. This card also reads in the upper bound, VRTMAX, imposed on the magnitude of the vortex induced velocity components.

Item 7

The number of vortices at the axial stations to be specified in item 9 are read in by this card. This arrangement allows for the introduction of additional vortices. This information must be supplied for increasing axial location (x_B -station).

Item 8

The starting coordinates, in the crossflow plane with y_B to the right and z_B upwards (i.e. the body coordinate system shown in figure 1), and strengths of the vortices are read in by these cards. If additional vortices are to be accounted for, the starting coordinates and strengths are read in at this time also. This information must be supplied for increasing axial location in synchronization with the number of vortices of item 7 and the axial station of item 9. Note that coordinates $VX(=y_B)$ and $VY(=z_B)$ are dimensional.

Item 9

These cards contain the axial stations at which the program will print vortex coordinates. Also, these stations are chosen such that they coincide with the introduction of additional vortices, if applicable, see items 7 and 8.

Item 10

This and the next three items read in specifications describing leading- and side-edge vorticity characteristics. They are obtained from the results calculated by program DEMON2 described in Appendix J of this report. This card contains the number of stations in the spanwise direction at which leading-edge vorticity locations and strengths are to be specified. This information must be supplied for all 4 fins of a cruciform configuration.

Item 11

If the information of item 10 is read in as nonzero, the locations along the leading edge and the strength of the leading-edge vorticity are read in. Note that the dimensional quantity XLE is measured in the wing coordinate system, as calculated by program DEMON2, not the body coordinate system. This information must be supplied for all fins.

APPENDIX L

Item 14

This optional input is specified when NCPIN of item 2 is read in as zero. The number NCP is the number of field points at which vortex induced velocity components are to be computed on the basis of the vortices being in the presence of the body only.

Item 15

If the information of item 14 is nonzero, these cards contain the coordinates, in the body coordinate system, of the fieldpoints at which vortex induced effects are to be computed. Note: in connection with the use of programs VPATH2 and VPATHL together with program DEMON2, index NCPIN is set equal to 1 and the information of items 14 and 15 is read in by means of a data set stored on TAPE4.

INPUT VARIABLES FOR PROGRAM VPATH2
(Circular Cross Section Bodies With Cruciform Fins)

PROGRAM VARIABLE	ALGEBRAIC SYMBOL (IF APPLICABLE)	COMMENTS
<u>Item 1</u>	(20A4)	Any alphanumeric information to identify the run.
<u>Item 2</u>	(8I10)	
NS		Number of body sections for which coefficients C(I,J) are required, $1 \leq NS \leq 7$.
NF		Number of corner points used to define fin geometry, $1 \leq NF \leq 7$.
NIP		Number of axial stations to be printed in output; $1 \leq NIP \leq 50$.
NCPIN		NCPIN = 1 Read in control point and body pressure points from data set (TAPE4). NCPIN = 0 No input.
NVLOUT		NVLOUT = 1 Write velocities induced by moving vortices (and calculated in this program) on data set (TAPE7). NVLOUT = 0 No input.

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
NOUT		NOUT = 1 Print additional output. NOUT = 0 Minimum output.
IPLT		IPLT = 0 No plots showing vortex positions in the output. IPLT = 1 Vortex positions shown in crossflow planes.
<u>Item 3</u>	(7F10.5)	
XE(I)	$x_{B,i}$	Axial coordinate of the end of each body section, $1 \leq I \leq NS$.
<u>Item 4</u>	(7F10.5)	
C(I,J)	C_{ij}	Coefficients in the body meridian equation, $1 \leq I \leq NS, 1 \leq J \leq 7$.
<u>Item 5</u>	(8F10.5)	
XF(I)	$x_{B,i}$	Optional input concerning fin planform geometry when $NF \neq 0$. Axial coordinate of fin corner point, $1 \leq I \leq NF$.
YF(I)	$y_{B,i}$	Lateral coordinate of fin corner point, $1 \leq I \leq NF$.
<u>Item 6</u>	(8F10.5)	
ALFAC	α_c	Included angle of attack, measured between free-stream velocity vector and body centerline.
PHI	ϕ	Angle of roll, positive right fin down.
D1	δ_1	Deflection angle of upper vertical fin, positive: trailing edges to right, degrees.
D2	δ_2	Deflection angle of right horizontal fin, positive: trailing edge down, degrees.
D3	δ_3	Deflection angle of lower vertical fin, positive: trailing edge to right, degrees.
D4	δ_4	Deflection angle of left horizontal fin, positive: trailing edge down, degrees.

APPENDIX L

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
E5		Error allowed in integration subroutine DASCUR. Use the value 0.0001 or less.
VRTMAX		Maximum magnitude of vortex induced velocities, use the value 0.35.
<u>Item 7</u>	(16I5)	
NVV(I)		Total number of vortices at each axial station, $1 \leq I \leq NIP$, NVMAX = NVV(NIP).
<u>Item 8</u>	(6F10.5)	
VX(I)	Y_B	Y_B -coordinate of vortex I.
VY(I)	z_B	z_B -coordinate of vortex I.
G(I)	$\frac{\Gamma_V}{V_\infty}$	Vortex strength, counterclockwise positive (when viewing forward), $1 \leq I \leq NVMAX$, NVMAX = NVV(NIP).
<u>Item 9</u>	(8F10.5)	
XIP(I)	$x_{B,i}$	Axial station at which output is required, $1 \leq I \leq NIP$.
<u>Item 10</u>	(8I10)	
MSWR		Number of leading-edge vortex information stations for right horizontal fin.
MSWL		Number of leading-edge vortex information stations for the left horizontal fin.
MSWU		Number of leading-edge vortex information stations for the upper vertical fin.
MSWD		Number of leading-edge vortex information stations for the lower vertical fin.
		NEDGV = MSWR + MSWL + MSWU + MSWD.
<u>Item 11</u>	(6F10.5)	
XLE(JLE)	$x_{w,LE}$	Wing x-coordinate of station on fin leading edge.

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
CGLOC (JLE)	$\bar{y}_{LE}, \bar{z}_{LE}$	Center of gravity of the leading-edge vorticity distribution at $x_{w,LE}$.
GAMLE (JLE)	$\frac{\Gamma_{LE}}{V_{\infty}}$	Strength of the vorticity distribution at XLE (JLE). $1 \leq JLE \leq NEDGV.$
<u>Item 12</u>	(I10)	
NCW		Number of side-edge vortex information stations. Same for all fins. NSIDGE = 4 (NCW).
<u>Item 13</u>	(6F10.5)	Optional input when NSIDGE \neq 0.
XSE (JSE)	$x_{w,SE}$	Wing x-coordinate of station on fin side edge
CGSELC (JSE)	$\bar{y}_{SE}, \bar{z}_{SE}$	Center of gravity of side-edge vorticity distribution at $x_{w,SE}$.
GAMSE (JSE)	$\frac{\Gamma_{SE}}{V_{\infty}}$	Strength of vorticity distribution at XSE (JSE). $1 \leq JSE \leq NSIDGE.$
<u>Item 14</u>	(I10)	Next two items are optional input for NCPIN = 0, only.
NCP		Number of control points and body pressure points or field points at which vortex-induced velocities are to be calculated.
<u>Item 15</u>	(3F10.5)	Optional input when NCP \neq 0 specifying field point coordinates.
CPX	x_B	Body x-coordinate of field point.
CPY	y_B	Body y-coordinate of field point.
CPZ	z_B	Body z-coordinate of field point.

APPENDIX L

Input for program VPATHL

Item 1

Refer to input item 1 under program VPATH2.

Item 2

Refer to input item 2 under program VPATH2. Only difference is option to set optional output plot size. The bounds read in as item 4 below.

Item 3

This card specifies the inverse of the ellipticity ratio of the elliptical cross section under consideration. This ratio is a constant for all axial locations.

Item 4

Refer to input item 3 under program VPATH2.

Item 5

Refer to input item 4 under program VPATH2. The polynomial is used to describe the meridian associated with the horizontal semiaxis of an elliptical cross section.

Item 6

Refer to input item 5 under program VPATHL.

Item 7

If IPLT equals 1 in item 2, the maximum and minimum values of the lateral coordinates are read in by this card. Now, XMAX and XMIN pertain to y_B coordinate and YMAX and YMIN pertain to z_B coordinate of the body coordinate system, see figure 1.

Item 8

Refer to input item 6 under program VPATH2. Omit deflection angles.

Item 9

Refer to item 7 under program VPATH2.

Item 10

Refer to item 8 under program VPATH2.

Item 11

Refer to item 9 under program VPATH2.

Item 12

Refer to item 10 under program VPATH2. Only MSWR and MSWL need be specified since the lifting surface is a monoplane wing designated as right and left "fins".

Item 13

Refer to item 11 under program VPATH2. Here, leading-edge vorticity characteristics need only be specified for the right and left "fins".

Item 14

Refer to item 12 under program VPATH2. Here NSIDGE = 2 NCW.

Item 15

Refer to item 13 under program VPATH2. In this instance, this information is only specified for the side edges of the right and left "fins".

Item 16

Refer to item 14 under program VPATH2.

Item 17

Refer to item 15 under program VPATH2.

INPUT VARIABLES FOR PROGRAM VPATHL
(Elliptical Cross Section Bodies With Monoplane Wing)

PROGRAM VARIABLE	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
Item 1	(20A4)	Any alphanumeric information to identify the run.

APPENDIX L

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
<u>Item 2</u>	(8I10)	
NS		Number of body sections for which coefficients C(I,J) are required, $1 \leq NS \leq 7$.
NF		Number of corner points used to define fin geometry, $1 \leq NF \leq 7$.
NIP		Number of axial stations to be printed in output, $1 \leq NIP \leq 50$.
NCPIN		NCPIN = 1 Read in control point and body pressure points from data set (TAPE4). NCPIN = 0 No input.
NVLOUT		NVLOUT = 1 Write velocities induced by moving vortices (and calculated in this program) on data set (TAPE7). NVLOUT = 0 No output on data set.
NOUT		NOUT = 0 Minimum output. NOUT = 1 Some additional debug output. NOUT = 2,3 Large amount of debug output containing information about intermediate complex variables. (use only when NIP = 2)
IPLT		IPLT = 0 No plots showing vortex positions in the output. IPLT = 1 Specify maximum and minimum x and y to be used in the plots, also see Item 4. IPLT = 3 Program determines plot size.
<u>Item 3</u>	(F10.5)	
BFACT	$1/\epsilon$	Ratio of vertical semiaxis over horizontal semiaxis.
<u>Item 4</u>	(7F10.5)	
XE(I)	$x_{B,i}$	Axial coordinate of the end of each body section, $1 \leq I \leq NS$.

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
<u>Item 5</u>	(7F10.5)	
C(I,J)	C_{ij}	Coefficients in the body meridian equation, $1 \leq I \leq NS, 1 \leq J \leq 7$.
<u>Item 6</u>	(8F10.5)	
XF(I)	$x_{B,i}$	Axial coordinate of fin corner point, $1 \leq I \leq NF$.
YF(I)	$y_{B,i}$	Lateral coordinate of fin corner point, $1 \leq I \leq NF$.
<u>Item 7</u>	(8F10.5)	
XMAX		Maximum x-value used in program generated plots in output.
XMIN		Minimum x-value used in program generated plots in output.
YMAX		Maximum y-value used in program generated plots in output.
YMIN		Minimum y-value used in program generated plots in output.
<u>Item 8</u>	(8F10.5)	
ALFAC	α_c	Included angle of attack, measured between free-stream velocity vector and body centerline.
PHI	ϕ	Angle of roll, positive right fin down.
E5		Error allowed in integration subroutine DASCUR. Use the value 0.0001 or less.
VRTMAX		Maximum magnitude of vortex induced velocities, if VRTMAX = 0, the value 0.35 is used.
<u>Item 9</u>	(16I5)	
NVV(I)		Total number of vortices at each axial station, $1 \leq I \leq NIP, NVMAX = NVV(NIP)$.

APPENDIX L

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
<u>Item 10</u>	(6F10.5)	Initial vortex positions in crossflow plane.
VX(I)	$y_{B,i}$	y_B -coordinate of vortex I.
VY(I)	$z_{B,i}$	z_B -coordinate of vortex I.
G(I)	$\frac{\Gamma_{V,i}}{V_\infty}$	Vortex strength, counterclockwise positive (when viewing forward), $1 \leq I \leq NVMAX$, $NVMAX = NVV(NIP)$.
<u>Item 11</u>	(8F10.5)	
XIP(I)	$x_{B,i}$	Axial station at which output is required, $1 \leq I \leq NIP$.
<u>Item 12</u>	(8I10)	
MSWR		Number of leading-edge vortex information stations for right horizontal fin.
MSWL		Number of leading-edge vortex information stations for the left horizontal fin.
		$NEDGV = MSWR + MSWL$
<u>Item 13</u>	(6F10.5)	Optional input when $NEDGV \neq 0$.
XLE(JLE)	$x_{w,LE}$	Wing x-coordinate of station on fin leading edge.
CGLOC(JLE)	$\bar{y}_{LE}, \bar{z}_{LE}$	Center of gravity of the leading-edge vorticity distribution at $x_{w,LE}$.
GAMLE(JLE)	$\frac{\Gamma_{LE}}{V_\infty}$	Strength of the vorticity distribution at XLE(JLE).
		$1 \leq JLE \leq NEDGV$
<u>Item 14</u>	(I10)	
NCW		Number of side-edge vortex information stations. Same for all fins. $NSIDE = 2$ (NCW).

<u>PROGRAM VARIABLE</u>	<u>ALGEBRAIC SYMBOL (IF APPLICABLE)</u>	<u>COMMENTS</u>
<u>Item 15</u>	(6F10.5)	Optional input when NSIDGE \neq 0.
XSE(JSE)	$x_{w,SE}$	Wing x-coordinate of station on fin side edge.
CGSELC(JSE)	$\bar{y}_{SE}, \bar{z}_{SE}$	Center of gravity of side-edge vorticity distribution at $x_{w,SE}$.
GAMSE(JSE)	$\frac{\Gamma_{SE}}{V_{\infty}}$	Strength of vorticity distribution at XSE(JSE). $1 \leq JSE \leq NSIDGE$
<u>Item 16</u>	(I10)	Next two items are optional input for NCPIN = 0, only.
NCP		Number of control points and body pressure points or field points at which vortex induced velocities are to be calculated.
<u>Item 17</u>	(3F10.5)	Optional input when NCP \neq 0 specifying field point coordinates.
CPX	x_B	Body x-coordinate of field point.
CPY	y_B	Body y-coordinate of field point.
CPZ	z_B	Body z-coordinate of field point.

Description of Output

This section describes the output generated by programs VPATH2 and VPATHL. Only a few items in the output of these programs are different as pointed out below. The output to be described is generated when print control index NOUT is set equal to zero. For nonzero values, large amounts of additional output results. Thus, other than for debugging purposes, index NOUT must be set equal to zero in item 2 of the input for both programs. The results of the output plot options are self evident and will not be discussed here.

The first page of output contains the run identification and the geometry of the fin or wing planform. Included angle of attack and roll

APPENDIX L

are printed. Program VPATH2 also gives the deflection angles of the fins, if applicable. The permissible error in the integration scheme is specified. This output is followed by a list of vortex coordinates in the crossflow plane as a function of increasing axial location. Quantity $Y, VRTX$ is y_B and $Z, VRTX$ is z_B , both in the body coordinate system, refer to figure 1. The vortex strengths divided by the free-stream velocity, $GAMMA/VINF$, are also indicated. This information is given for each of the output stations, XIP , specified in the input and printed as X . At each station, the local body geometry and semispan (distance from body centerline to edge of fin or wing as seen in the crossflow plane) are written. Program VPATH2 gives the local body radius for the axisymmetric body. Program VPATHL specifies the local horizontal semiaxis and the vertical semiaxis.

The final item in the output of both programs are the coordinates of field points (or control points), read in by means of input or data set, and the velocity components induced by the vortices at the points. The coordinates and the velocity components are given in the body coordinate system, refer to figure 1. The vortex effects are calculated on the basis of the vortices in the presence of the body only.

Program Listings

Programs VPATH2 and VPATHL are written in FORTRAN IV (029 punch) computer language for the CDC 6600 computer. Program VPATH2 consists of a main routine, VPATH, and 12 subroutines. Program VPATHL consists of a main routine, VPATHL, and 13 subroutines. The listings are shown on the indicated pages with the main program first and the subroutines following in alphabetical order.

PROGRAM VPATH2

	<u>ROUTINE</u>	<u>IDENTIFICATION</u> Cols. 73-77	<u>PAGE NO.</u>
1.	VPATH	VPC01	413
2.	CRUCI	02	419
3.	DASCRU	03	420
4.	F	04	423
5.	FCT	05	426
6.	PITROL	06	427
7.	PLOTVB	07	427
8.	SHAPE	08	430
9.	SIMP	09	431
10.	SYMFIN	10	431
11.	VOTEX	11	432
12.	VVELS	12	433
13.	Z	13	434

PROGRAM VPATH2

```

PROGRAM VPATH(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,TAPE4,TAPE7) VPC01 1
C VPC01 2
C VERSION: VPATH2 VPC01 3
C VPC01 4
C THIS PROGRAM COMPUTES THE PATHS AND VORTEX INDUCED CROSSFLOW VPC01 5
C VELOCITIES AT SPECIFIED FIELD POINTS FOR A SET OF VORTICES IN THE VPC01 6
C PRESENCE OF A WING-BODY COMBINATION AT ANGLE OF ATTACK AND ROLL, ANY VPC01 7
C OR ALL OF THE FINS MAY BE DEFLECTED. SLENDER BODY THEORY IS USED VPC01 8
C IN THE COMPUTATION OF THE CROSSFLOW VELOCITIES. VPC01 9
C VPC01 10
C THE COORDINATE SYSTEM USED HERE IS THE BODY COORDINATE SYSTEM VPC01 11
C WITH THE X-AXIS ALONG THE BODY CENTER-LINE STARTING AT THE NOSE TIP, VPC01 12
C Y-AXIS TO THE RIGHT WHEN LOOKING FORWARD,Z-AXIS UP. VPC01 13
C VPC01 14
C WHEN FINS ARE PRESENT,THE Y-AXIS FALLS ALONG RIGHT FIN, VPC01 15
C THE Z-AXIS ALONG THE UPPER FIN. THUS,THIS PROGRAM PERFORMS ALL VPC01 16
C VORTEX PATH CALCULATIONS IN A ROLLED COORDINATE SYSTEM. VPC01 17
C VPC01 18
C *****NOTE: CRUCIFORM FINS ONLY***** VPC01 19
C VPC01 20
C DIMENSION TITLE(24),XD(60),XIP(50),PK(120) VPC01 21
C DIMENSION VXP(30,30,2),VYV(30) VPC01 22
C VPC01 23
C COMMON/VFL/AL,RE,01,02,03,04,VX(30),VY(30),G(30),AV,NDDEL,FS,FE, VPC01 24
C LXE(7),XE(7),YE(7),CL(7),JFIN VPC01 25
C COMMON/BLK2/AC,PBT VPC01 26
C COMMON/FTNLE/ZLF(40),CGLUC(60),GAMLE(40),MSWR,MSWL,MSH,MSWD, VPC01 27
C I,NEGGY,XTITLE VPC01 28
C COMMON/STDEG/XSF(40),CGSEL(40),GAMSE(40),NCW,NSIDGL,XTITPE VPC01 29
C COMMON XPLT(30,52),YPLT(30,52),ZPLT(30,52),NPLT(52),ROT(3) VPC01 30
C * XPR(17,18),YPR(17,18) VPC01 31
C VPC01 32
C NAMELIST/DEBUG/MS,RE,NDIP,NDPIN,VALOUT,ROUT,VRTMAX,XE,C,XE,YE,AV VPC01 33
C VPC01 34
C 1 FORMAT(20A4) VPC01 35
C 0 FORMAT(A10) VPC01 36
C 5 FORMAT(7F10,5) VPC01 37
C 6 FORMAT(8F10,5) VPC01 38
C 7 FORMAT(A4F10,5) VPC01 39
C 9 FORMAT(//5X,20HLOCAL BODY RADIUS = ,F10,5,5X, VPC01 40
C 1 20HLOCAL SECT SPAN S = ,F10,5/) VPC01 41
C 11 FORMAT(//5X,33H INCLUDED ANGLE OF ATTACK(DEG) = ,F10,5, VPC01 42
C 1 24H ROLL ANGLE(DEG) = ,F10,5/) VPC01 43
C 12 FORMAT(2X,24H PANEL DEFL.(DEG) 1,//9X,9H DELTA1= ,F6,3, VPC01 44
C 1 11H DELTA2= ,F6,3,11H DELTA3= ,F6,3,11H DELTA4= ,F6,3//) VPC01 45
C 21 FORMAT(//19H X-STATION NO.,(3,9H X=,F6,3,6X, VPC01 46
C 1 25H INTEGRATION STEP SIZE = ,F10,5//) VPC01 47
C 22 FORMAT(I15,4X,2E17,5,F15,5) VPC01 48
C 25 FORMAT(////16X,36HVORTEX COORDINATES IN CROSS-FLOW PLANE,/) VPC01 49
C 26 FORMAT(//43H INITIAL VORTEX POSITIONS AT X = ,F6,3/) VPC01 50
C 27 FORMAT(10X,7H VORTEX,10X,7H Y,VPTX,10X,7H Z,VPTX,6X, VPC01 51
C 1 10HGAMMA/VIF/) VPC01 52
C 30 FORMAT(16I5) VPC01 53
C 31 FORMAT(/// 6X,76HCROSSFLOW VELOCITIES AT CONTROL POINTS INDUCED BY VPC01 54
C 1 VORTICES AND THEIR IMAGES,/) VPC01 55
C 1 6X,26IC,10X,6HX,BODY,10X,6HY,BODY,10X,6HZ,BODY,10X,1HV,15X,1HW) VPC01 56
C 32 FORMAT(4X,15,6X,5E15,5) VPC01 57
C 50 FORMAT(3F10,5) VPC01 58
C 700 FORMAT(//5(1H*),59HPERMISSIBLE RELATIVE ERROR,ES,USED IN INTEGRAVPC01 59
C 1TIN SCHEME = ,E12,5/) VPC01 60
C 701 FORMAT(//5(1H*),61HROUTINE BASCPU CAN NOT OBTAIN VALUE FOR IVPC01 61
C 62 VPC01 62
C 63 VPC01 63

```


	IP1=I+1	VPC01127
	IF (YF(I),EQ,YMAX,AND,YF(IP1),EQ,YMAX) GO TO R2	VPC01128
	IF (YF(I),EQ,YMAX) GO TO R3	VPC01129
R1	CONTINUE	VPC01130
	GO TO R4	VPC01131
R2	YMAX=I	VPC01132
	IMAXPI=J+1	VPC01133
	XTIPLE=YF(IMAX)	VPC01134
	VTIPLE=YF(IMAX)	VPC01135
	XTIPIE=YF(IMAXPI)	VPC01136
	VTIPIE=YF(IMAXPI)	VPC01137
	GO TO R4	VPC01138
R3	XTIPLE=YF(IMAX)	VPC01139
	XTIPIE=XTIPLE	VPC01140
R4	CONTINUE	VPC01141
C		VPC01142
C		VPC01143
C		VPC01144
C		VPC01145
C	ALFAC=INCLUDED ANGLE OF ATTACK, PHI=ROLL ANGLE BOTH IN DEGREE	VPC01146
C	D1,D2,D3,D4 ARE FIN DEFLECTIONS IN DEGREES, POSITIVE TRAILING	VPC01147
C	EDGE DOWN FOR HOP, FINS, TRAILING EDGE TO THE RIGHT FOR VERT.	VPC01148
C	FINS	VPC01149
C	E5 = PERMISSIBLE RELATIVE ERROR IN THE PATH INTEGRATION SCHEME	VPC01150
C		VPC01151
	READ(5,6)ALFAC,PHI,D1,D2,D3,D4,E5,VRTMAX	VPC01152
	IF (VRTMAX,EQ,0.0) VRTMAX=0.35	VPC01153
	M1=ABS(D1)+ABS(D2)+ABS(D3)+ABS(D4)	VPC01154
	NOEL=0	VPC01155
	IF (M1,NE,0.0) NOEL=1	VPC01156
C	.. X-STATIONS, INTEGRATION INFO, + INITIAL VORTEX POSITIONS AND STRENGTH	VPC01157
C		VPC01158
C		VPC01159
C	NVV = TOTAL NUMBER OF VORTICES AT EACH X-STATION	VPC01160
C		VPC01161
C		VPC01162
	READ(5,30)(NVV(I),I=1,NIP)	VPC01163
	NV=NVV(1)	VPC01164
	NVMAX=NVV(NIP)	VPC01165
C		VPC01166
C	READ IN CROSSFLOW STARTING COORDINATES AND STRENGTHS FOR ALL	VPC01167
C	VORTICES REGARDLESS OF THE X-STATION AT WHICH THEY START.	VPC01168
C	THIS INFO MUST BE INPUT FOR INCREASING X-STATION.	VPC01169
C		VPC01170
C	HERE....VX(I)...Y-COORDINATE	VPC01171
C	VY(I)...Z-COORDINATE	VPC01172
C	G(I)...GAMMA/WING, COUNTERCLOCKWISE POSITIVE,	VPC01173
C	WHEN VIEWING FORWARD.	VPC01174
C		VPC01175
	READ(5,7)(VX(I),VY(I),G(I),I=1,NVMAX)	VPC01176
	DO R I=1,NV	VPC01177
	J=2*I-1	VPC01178
	K=J+1	VPC01179
	VXP(1,I,1)=VX(I)	VPC01180
	VXP(1,I,2)=VY(I)	VPC01181
	XI(J)=VX(I)	VPC01182
A	XI(K)=VY(I)	VPC01183
C		VPC01184
C	YI= Y- VALUES AT THE NIP X-STATIONS AT WHICH OUTPUT READ.	VPC01185
C	FIRST VALUE FOR XI CAN BE ANY NUMBER LARGER THAN ZERO	VPC01186
C	INTEGRATION STARTS AT XIP(I)	VPC01187
C	INTEGRATION STEP SIZE DETERMINED BY DASCRO...H	VPC01188
C		VPC01189

```

C      READ(5,6)(XIP(I),I=1, NIP)
C
C      WRITE(6,1)TITLE
C      IF (NF.NE.0)
C      1 WRITE (6,704) YMAX,CMP,XF(1),YF(1),XTIPLE,YTIPLE,XTIPTE,YTIPTE,
C      1 XF(NF),YF(NF)
C      WRITE(6,11)ALFAC,PHI
C      WRITE(6,12)D1,D2,D3,D4
C      IF (NOUT.NE.0) WRITE (6,DEHUG)
C
C      READ NUMBERS OF FIN LEADING EDGE VORTEX INFO STATIONS XLE FOR
C      EACH FIN.
C      FOR EACH XLE STATION,READ IN YBAR OR ZBAR(=CGLOC) AND STRENGTH
C      OF THE VORTICITY DISTRIBUTION.
C      NOTE: THIS VORTICITY IS FIXED IN POSITION,IT AFFECTS THE FLOWFIELD
C      NOTE: XLE AND YSE ARE READ IN IN THE FIN COORDINATE SYSTEM AND
C      MUST BE TRANSFORMED TO BODY COORDINATE SYSTEM.
C
C      READ (5,4) MSWR,MSWL,MSWD,MSWD
C      NEDGV=MSWR+MSWL+MSWD+MSWD
C      IF (NEDGV.EQ.0) GO TO 19
C      READ (5,7) (XLE(IFV),CGLOC(IFV),GAMLE(IFV),
C      1 IFV=1,NEDGV)
C      WRITE (6,706)
C      DO 15 JLE=1,NEDGV
C      XLE(JLE)=XLE(JLE)+XF(1)
C      15 WRITE (6,705) JLE,XLE(JLE),CGLOC(JLE),GAMLE(JLE)
C      19 CONTINUE
C
C      READ NUMBER OF FIN SIDE EDGE VORTEX INFO STATIONS XSE FOR EACH
C      FIN.
C      NOTE: THIS VORTICITY IS FIXED IN POSITION,IT AFFECTS THE FLOWFIELD
C      FOR EACH XSE STATION,READ IN YBAR OR ZBAR(=CGSELC) AND THE
C      STRENGTH OF THE VORTICITY DISTRIBUTION
C
C      READ (5,4) NSW
C      NSIDGE=NSW+NSW
C      IF (NSIDGE.EQ.0) GO TO 18
C      READ (5,7) (XSE(JSE),CGSELC(JSE),GAMSE(JSE),
C      1 JSE=1,NSIDGE)
C      WRITE (6,707)
C      DO 16 JSE=1,NSIDGE
C      XSE(JSE)=XSE(JSE)+XF(1)
C      16 WRITE (6,705) JSE,XSE(JSE),CGSELC(JSE),GAMSE(JSE)
C      18 CONTINUE
C
C      WRITE (6,700) 65
C      WRITE (6,25)
C      WRITE(6,26)XIP(1)
C      CALL SHAPE (XIP(1),WLOC,SLCC)
C      WRITE (6,9) WLOC,SLCC
C      WRITE(6,27)
C      WRITE(6,22)(L,VX(L),VY(L),G(L),L=1,NV)
C
C      CONVERT ANGLES TO RADIAN
C
C      AC=ALFAC*RAO
C      HA=PHI*RAO
C      PHI=DE

```

```

VPC01190
VPC01191
VPC01192
VPC01193
VPC01194
VPC01195
VPC01196
VPC01197
VPC01198
VPC01199
VPC01200
VPC01201
VPC01202
VPC01203
VPC01204
VPC01205
VPC01206
VPC01207
VPC01208
VPC01209
VPC01210
VPC01211
VPC01212
VPC01213
VPC01214
VPC01215
VPC01216
VPC01217
VPC01218
VPC01219
VPC01220
VPC01221
VPC01222
VPC01223
VPC01224
VPC01225
VPC01226
VPC01227
VPC01228
VPC01229
VPC01230
VPC01231
VPC01232
VPC01233
VPC01234
VPC01235
VPC01236
VPC01237
VPC01238
VPC01239
VPC01240
VPC01241
VPC01242
VPC01243
VPC01244
VPC01245
VPC01246
VPC01247
VPC01248
VPC01249
VPC01250
VPC01251
VPC01252

```

```

D1=D1*RAD
D2=D2*RAD
D3=D3*RAD
D4=D4*RAD
AL=ASIN(SIN(AC)*COS(HE))
RE=ASIN(SIN(AC)*SIN(HE))

```

```

VPC01253
VPC01254
VPC01255
VPC01256
VPC01257
VPC01258
VPC01259
VPC01260
VPC01261
VPC01262
VPC01263
VPC01264
VPC01265
VPC01266
VPC01267
VPC01268
VPC01269
VPC01270
VPC01271
VPC01272
VPC01273
VPC01274
VPC01275
VPC01276
VPC01277
VPC01278
VPC01279
VPC01280
VPC01281
VPC01282
VPC01283
VPC01284
VPC01285
VPC01286
VPC01288
VPC01289
VPC01290
VPC01291
VPC01292
VPC01293
VPC01294
VPC01295
VPC01296
VPC01297
VPC01298
VPC01299
VPC01300
VPC01301
VPC01302
VPC01303
VPC01304
VPC01305
VPC01306
VPC01307
VPC01308
VPC01309
VPC01310
VPC01311
VPC01312
VPC01313
VPC01314
VPC01315

```

```

..... COMPUTE VORTEX PATHS USING DASCRO INTEGRATION SUBROUTINE.....

```

```

NIP=NIP+1
H=XIP(2)-VIP(1)
DO 20 I=1,NIP
  I=I+1
  NV=NVV(I)
  NVN=NVV(I1)
  NV1=NV+1
  N=2*NV
  A1=XIP(I)
  B1=XIP(I+1)

```

```

CALL DASCRO(A1,B1,H,N,XD,K,IER,E5,VRTMAX)

```

```

IF IER GREATER THAN 32, DASCRO HAD TROUBLE GETTING STEP SIZE.
THEN, RATHER THAN CONTINUING, IF THE INTEGRATION, STOP 40
REDUCE XIP(2)=XIP(1) AND RERUN

```

```

IF (IER.GE.32) GO TO 28
GO TO 29
28 WRITE (6,701)
STOP 40
29 CONTINUE

```

```

.. ADD THE NEW VORTICES AND THEIR POSITIONS FOR THE NEXT X-INTERVAL

```

```

IF (NVN.EQ.NV) GO TO 39
DO 35 K=NV1,NVN
  JL=2*K-1
  KK=JL+1
  X0(JL)=VX(K1)
35 X0(KK)=VY(K1)
39 CONTINUE

```

```

.. OUTPUT VORTEX POSITIONS AND CONFIGURATION CHARACTERISTICS AT THIS
STATION.

```

```

WRITE(6,21)I1,B1,H
CALL SHAPE (H1,PL0C,SL0C)
WRITE (6,9) PL0C,SL0C
WRITE(6,27)
DO 23 L=1,NVN
  J=2*L-1
  K=J+1
  VXP(I1,L,1)=X0(J)
  VXP(I1,L,2)=X0(K)
WRITE(6,22)L,X0(J),X0(K),G(L)

```

```

SAVE VORTEX LOCATION FOR PLOT

```

```

JCV=JCV+L+1
XPLT(I,JCV)=H1
YPLT(I,JCV)=X0(J)
ZPLT(I,JCV)=X0(K)

```


	23 CONTINUE	VPC01316
C		VPC01317
C	SAVE BODY POINTS FOR PLOT	VPC01318
C		VPC01319
	XPLT(1,11)=R1	VPC01320
	YPLT(1,11)=RLOC	VPC01321
	ZPLT(1,11)=RLOC	VPC01322
	YPLT(2,11)=SLOC	VPC01323
	20 CONTINUE	VPC01324
C		VPC01325
C	PLOT VORTEX LOCATIONS	VPC01326
C		VPC01327
	XPLT(1,1)=XIP(1)	VPC01328
	IF (IPLT.GT.0)	VPC01329
	* CALL PLOTVH(XPLT,YPLT,ZPLT,NPLT,NIP1,NVN,30,ROT,XF,YF,NF,XP2,YP2)	VPC01330
C		VPC01331
C	COMPUTE VELOCITIES AT THE SPECIFIED CONTROL POINTS INDUCED BY MV	VPC01332
C	EXTERNAL VORTICES AND THEIR IMAGES.	VPC01333
C		VPC01334
C		VPC01335
C	NOTE: IF CONTROL POINTS ARE PASSED THROUGH BY MEANS OF A DATA SET	VPC01336
C	I.E. WHEN MCPIN IS NOT EQUAL TO 0, INDEX MCP IS READ IN FROM	VPC01337
C	THE DATA SET ALSO.	VPC01339
C	NOTE: X-COORDINATE OF CONTROL POINT MUST THEN BE TRANSFORMED TO BODY	VPC01339
C	COORDINATE SYSTEM.	VPC01340
C	THIS IS DONE BELOW.	VPC01341
C		VPC01342
C		VPC01343
	MCP=0	VPC01344
	IF (MCPIN.NE.0) REWIND 4	VPC01345
	IF (MVLOUT.NE.0) REWIND 7	VPC01346
	IF (MCPIN.EQ.0) GO TO 72	VPC01347
	IF (MCPIN.NE.0) READ (4,745) MCP	VPC01348
	IF (EMF(4).NE.0) GO TO 99	VPC01349
	GO TO 73	VPC01350
	72 READ (5,4) MCP	VPC01351
	73 CONTINUE	VPC01352
	IF (MCP.EQ.0) GO TO 99	VPC01353
	WRITE (6,31)	VPC01354
	DO 69 J11=1,MCP	VPC01355
	IF (MCPIN.EQ.0) GO TO 70	VPC01356
	READ (4,745) IC,CPX,CPY,CPZ	VPC01357
	CPX=CPX+XF(1)	VPC01358
	GO TO 71	VPC01359
	70 READ (5,60) CPX,CPY,CPZ	VPC01360
	71 CONTINUE	VPC01361
C		VPC01362
C	DETERMINE THE X-STATIONS ADJACENT TO THE CONTROL POINT	VPC01363
C		VPC01364
	DO 61 I=1,NIP	VPC01365
	IF (CPX.LT.XIP(I)) GO TO 64	VPC01366
	J=I-1	VPC01367
	IF (I.EQ.1) J=1	VPC01368
	IF (CPX.LE.XIP(I)) GO TO 62	VPC01369
	61 CONTINUE	VPC01370
C		VPC01371
C	DETERMINE BY INTERPOLATION THE POSITION IN THE CROSSFLOW PLANE OF ALL	VPC01372
C	VORTICES AT EACH STATION CPX.	VPC01373
C		VPC01374
	62 K=J+1	VPC01375
	X1=XIP(J)	VPC01376
	X2=XIP(K)	VPC01377
	-T1=(X2-CPX)/(X2-X1)	VPC01378

```

      AT2=(CPX-X1)/(X2-X1)
      NV=VV(J)
      CALL SHAPE (CPX,HB,SL)
      IF (NOUT.EQ.0) WRITE (6,703)
      DO 63 I=1,NV
      VX(I)=T1*VXP(J,I,1)+T2*VXP(K,I,1)
      VY(I)=T1*VXP(J,I,2)+T2*VXP(K,I,2)
      IF (NOUT.EQ.0) GO TO 63
      WRITE (6,702) I,VX(I),VY(I)
63 CONTINUE
C
C SUBROUTINE VVELS CALCULATES VORTEX VELOCITIES INCLUDING EFFECTS
C FROM IMAGE VORTICES. CENTER VORTEX EFFECTS ARE OMITTED.
C
      CALL VVELS(V,CPY,CPZ,VX,VY,G,RR,V,N,VRTAX)
      WRITE (6,32) J11,CPX,CPY,CPZ,V,VX
      IF (NOUT.EQ.0) GO TO 69
      IC=J11
      WRITE (7,746) IC,CPX,CPY,CPZ,V,VX
69 CONTINUE
      GO TO 99
2 STOP
      END
VPC01379
VPC01380
VPC01381
VPC01382
VPC01383
VPC01384
VPC01385
VPC01386
VPC01387
VPC01388
VPC01389
VPC01390
VPC01391
VPC01392
VPC01393
VPC01394
VPC01395
VPC01396
VPC01397
VPC01398
VPC01399
VPC01400
VPC01401

```

```

      SUBROUTINE CRUCI(NC,D,X,Y,VS,*3)
C
C VERSION: VPATH2
C
C USING (X,Y) AS COORDINATES IN THE CROSS FLOW PLANE.
C THIS SUBROUTINE COMPUTES THE CROSSFLOW VELOCITY COMPONENTS AT A POINT
C (X,Y) DUE TO THE DEFLECTION OF A SINGLE FIN IN A WING-BODY COMBINATION.
C THE ANGLE OF DEFLECTION IS D RADIANS AND THE FIN THAT IS DEFLECTED IS
C IDENTIFIED BY THE CODE NC. IF NC=1 THE RIGHT HORIZONTAL FIN IS DEFLECTED
C IF NC=2 ETC. WE COUNT COUNTERCLOCKWISE. NUMERICAL INTEGRATION IS USED
C DETERMINE THE VELOCITIES. THE ACCURACY OF INTEGRATION IS DETERMINED BY
C THE TOLERANCE TOL = IN THE DATA STATEMENT. A POINT NEAR THE BODY REQUIRES
C MANY INTEGRATION POINTS. THE SCHEME IS SINGULAR ON THE BODY.
C
      COMMON/BLK1/A,R,S,PI,CI
      COMMON AA,SIG,SS,GAM
      EXTERNAL FCT
      COMPLEX CI,TAU,TT,TPA,SIG,SS,EGP,EGT,T1,VEL,T2,DSDT,TP2,TH2,TP4,
      IECT, T21,T22,SIMP,T20
      DATA TOL/,02/
      SCA=R
      X=X/SCA
      Y=Y/SCA
      A=A/SCA
      AA=A*A
      GAM=.5*ACOS(AA)
      GAM1=.9+GAM
C
C TRANSFORM X,Y TO PROPER QUADRANT
C
      THE=FLOAT(NC-1)*PI/2.
      XS=X*COS(TH)+Y*SIN(TH)
      YS=Y*COS(TH)-X*SIN(TH)
      TAU=CMPLX(XS,ABS(YS))
      TT=TAU*TAU
VPC02 1
VPC02 2
VPC02 3
VPC02 4
VPC02 5
VPC02 6
VPC02 7
VPC02 8
VPC02 9
VPC02 10
VPC02 11
VPC02 12
VPC02 13
VPC02 14
VPC02 15
VPC02 16
VPC02 17
VPC02 18
VPC02 19
VPC02 20
VPC02 21
VPC02 22
VPC02 23
VPC02 24
VPC02 25
VPC02 26
VPC02 27
VPC02 28
VPC02 29
VPC02 30
VPC02 31
VPC02 32
VPC02 33
VPC02 34
VPC02 35
VPC02 36

```

TPA=TT+AA*AA/TT	VPC02 37
TM2=TPA-2.	VPC02 38
TP2=TPA+2.	VPC02 39
IF(AIMAG(TM2).GE.0.)TM2=CSQRT(TM2)	VPC02 40
IF(AIMAG(TM2).LT.0.)TM2=-CSQRT(TM2)	VPC02 41
IF(AIMAG(TP2).GE.0.)TP2=CSQRT(TP2)	VPC02 42
IF(AIMAG(TP2).LT.0.)TP2=-CSQRT(TP2)	VPC02 43
TP4=TP2*TM2	VPC02 44
SIG=.5*(TM2+TP2)	VPC02 45
SS=SIG*SIG	VPC02 46
EGP=CEXP(CI*GAM)	VPC02 47
EGM=1./EGP	VPC02 48
T1=A*(1./(SIG-EGP)-1./((SIG+EGM)))	VPC02 49
NG=10	VPC02 50
T20=CMPLX(0.,0.)	VPC02 51
22 T21=SIMP(0.,GAM1,NG,FACT)	VPC02 52
IF(CABS(T21-T20)/CABS(T21).LT.TOL)GO TO 21	VPC02 53
IF(NG.GT.3000)*WRITE(6,5)	VPC02 54
IF(NG.GT.5000)GO TO 21	VPC02 55
5 FORMAT(// * SORRY DOES NOT CONVERGE IN CRUCT *//)	VPC02 56
NG=NG*2	VPC02 57
T20=T21	VPC02 58
GO TO 22	VPC02 59
21 T20=CMPLX(0.,0.)	VPC02 60
NG=20	VPC02 61
33 T22=SIMP(GAM1,GAM,NG,FACT)	VPC02 62
IF(CABS(T22-T20)/CABS(T22).LT.TOL)GO TO 31	VPC02 63
IF(NG.GT.3000)*WRITE(6,5)	VPC02 64
IF(NG.GT.5000)GO TO 31	VPC02 65
NG=NG*2	VPC02 66
T20=T22	VPC02 67
GO TO 33	VPC02 68
31 CONTINUE	VPC02 69
T2=T21+T22	VPC02 70
DSDT=.5*(TAU-AA*JA/(TT*TAU)) *(TP2+TM2)/TP4	VPC02 71
VEL=0*DSDT*(T1-C1+T2/SQRT(2.))/PI	VPC02 72
V=REAL(VEL)	VPC02 73
W=AIMAG(VEL)	VPC02 74
IF(YS.LT.0.)V=-V	VPC02 75
ROTATE VELOCITIES BACK	VPC02 76
	VPC02 77
	VPC02 78
	VPC02 79
VS=V*COS(TM)+W*SIN(TM)	VPC02 80
W=V*SIN(TM)+W*COS(TM)	VPC02 81
AA*SCA	VPC02 82
XX*SCA	VPC02 83
Y=V*SCA	VPC02 84
RETURN	VPC02 85
END	

SUBROUTINE DASCRO (A,B,H,A,X0,PK,IER,ES,VRTMAX)	VPC03 1
	VPC03 2
VERSION: VPATH2	VPC03 3
	VPC03 4
THIS SUBROUTINE PERFORMS INTEGRATION	VPC03 5
	VPC03 6
	VPC03 7
ES SHOULD BE SET TO .5 TIMES THE DESIRED RELATIVE PRECISION OF	VPC03 8

THE SOLUTION

VPC03 9
VPC03 10
VPC03 11
VPC03 12
VPC03 13
VPC03 14
VPC03 15
VPC03 16
VPC03 17
VPC03 18
VPC03 19
VPC03 20
VPC03 21
VPC03 22
VPC03 23
VPC03 24
VPC03 25
VPC03 26
VPC03 27
VPC03 28
VPC03 29
VPC03 30
VPC03 31
VPC03 32
VPC03 33
VPC03 34
VPC03 35
VPC03 36
VPC03 37
VPC03 38
VPC03 39
VPC03 40
VPC03 41
VPC03 42
VPC03 43
VPC03 44
VPC03 45
VPC03 46
VPC03 47
VPC03 48
VPC03 49
VPC03 50
VPC03 51
VPC03 52
VPC03 53
VPC03 54
VPC03 55
VPC03 56
VPC03 57
VPC03 58
VPC03 59
VPC03 60
VPC03 61
VPC03 62
VPC03 63
VPC03 64
VPC03 65
VPC03 66
VPC03 67
VPC03 68
VPC03 69
VPC03 70
VPC03 71

DIMENSION X(1),X0(1)
INTEGER SW
LOGICAL BE,RE,SE,RE,RE
DATA ZERO,PI,OPS,THREE,FOUR,0.,.5,1,5,3.,4./

IER = 0
IF(A = PI) 4,100,0
I1=1+N
I2=I1+N
M=IN=0,01+ABS(M)
RE=TRUE.
RE=TRUE.
RE=TRUE.

CHECK FOR THE PROPER SIGN OF M

M=SIGN(ABS(M),M=A)
X=A
5 XS=X
DO 10 J=1,N
IJK0=M+J
XK(IJK0)=X0(J)
10 CONTINUE
15 M=H
G=X+M=H
RE=TRUE.
IF(.NOT.(M.GT.ZERO.AND.0.GE.ZERO).OR.(M.LT.ZERO.AND.0.LE.ZERO))
1 GO TO 20
M=B=X
RE=FALSE.
20 M3=M/THREE

CALCULATE SOLN. AT X+H

NOTE: ARRAY XK CONTAINS V FOR ODD INDEX, W FOR EVEN INDEX.

DO 90 SW=1,5
CALL F(X0,X,M,XK,VRTMAX)
DO 70 I=1,N
O=M+X(I)
IJK0=M+I
IJK1=I1+I
IJK2=I2+I
GO TO (25,30,35,40,45),SW
25
XK(IJK1)=G
GO TO 50
30
R=PS+(O+X(IJK1))
GO TO 50
35
R=THREE*O
XK(IJK2)=H
R=.375*(R+X(IJK1))
GO TO 50
40
R=X(IJK1)+FOUR*O
XK(IJK1)=H
R=OPS*(R+X(IJK2))
GO TO 50
45
R=PS*(O+X(IJK1))

		GE ABS(WR = DP5*(D-X(IJK2)))	VPC03 72
	50	X0(I)=X(IJK)+D	VPC03 73
		IF(S=HE,5) GO TO 70	VPC03 74
C			VPC03 75
C		AUTOMATIC STEP CHANGE	VPC03 76
C			VPC03 77
		R=ABS(X0(I))	VPC03 78
		R=5	VPC03 79
		IF(E,GF,1,E-3) R=E+ES	VPC03 80
C			VPC03 81
C		TEST ADJUSTMENT OF THE STEP	VPC03 82
C			VPC03 83
		IF(D,LT,0 .OR. (.NOT. BX)) GO TO 65	VPC03 84
		HE=TRUE.	VPC03 85
		HE=FALSE.	VPC03 86
		H=5*M	VPC03 87
		IF(ABS(H),GE,HMIN) GO TO 55	VPC03 88
C			VPC03 89
C		THE STEP IS HALVED RESTORE X AND X0,	VPC03 90
C		AND GO BACK FOR REPEATED INTEGRATION	VPC03 91
C		WITH THIS NEW STEP	VPC03 92
C			VPC03 93
		H=SIGN(I,H)*HMIN	VPC03 94
		BX=FALSE.	VPC03 95
	55	DO 60 J=1,N	VPC03 96
		X0(J)=X(J)	VPC03 97
		X(J)=X(IJK)	VPC03 98
	60	CONTINUE	VPC03 99
		Y=X	VPC03100
		GO TO 15	VPC03101
	65	IF(D,GE,0.03125*M) HE=FALSE.	VPC03102
	70	CONTINUE	VPC03103
		GO TO (75,90,H0,85,90),S	VPC03104
	75	X=X+H	VPC03105
		GO TO 90	VPC03106
	80	X=X+P5*M	VPC03107
		GO TO 90	VPC03108
	85	X=X+P5*M	VPC03109
	90	CONTINUE	VPC03110
C			VPC03111
C		TEST A POSSIBLE DOUBLING OF THE STEP	VPC03112
C			VPC03113
		IF(.NOT.(HE,AND,HM,AND,HR)) GO TO 95	VPC03114
		H=H+H	VPC03115
		BX=TRUE.	VPC03116
	95	HE=TRUE.	VPC03117
		IF(RR) GO TO 5	VPC03118
		H=H	VPC03119
		IF(BX .OR. HE) GO TO 9005	VPC03120
		IFR = 33	VPC03121
		GO TO 9005	VPC03122
	100	DO 105 I=1,N	VPC03123
		X0(I)=ZERO	VPC03124
	105	CONTINUE	VPC03125
	9005	RETURN	VPC03126
		END	VPC03127

	SUBROUTINE F(X0,PX,A,K,VRTMAX)	VPC04	1
C		VPC04	2
C	VERSION: VPATH2	VPC04	3
C		VPC04	4
C	THIS SUBROUTINE IS CALLED BY PASCRO TO CALCULATE CROSS FLOW	VPC04	5
C	PLANE VELOCITIES	VPC04	6
C		VPC04	7
C	COMPLEX CI,Z,FACT,SIMP	VPC04	8
C	COMMON/VEL/AL,NE,D1,D2,D3,D4,VX(50),VY(50),G(50),NV,NDFL,NS,NF,	VPC04	9
C	IXE(7),YF(7),YF(7),C(7,7),IFIN	VPC04	10
C	COMMON/HLK1/A,K,S,PI,CI	VPC04	11
C	COMMON/HLK2/AC,PHI	VPC04	12
C	COMMON/FINLE/XLE(80),CGLOC(80),GAMLE(80),MSAR,MSWL,MSWI,MS+D,	VPC04	13
C	I,NEGV,XTIPLE	VPC04	14
C	COMMON/STDEG/XSE(80),CGSELC(80),GAMSE(80),NCW,NSIDG,XTIPTS	VPC04	15
C		VPC04	16
C	DIMENSION X0(1),K(1),V(50),K(50),VV(50),KK(50),NCC(4)	VPC04	17
C		VPC04	18
C	EXTERNAL Z,FACT,SIMP	VPC04	19
C	CI=CMPLX(0.,1.)	VPC04	20
C	PI=3.14159265	VPC04	21
C	DO 888 I=1,NV	VPC04	22
C	J=2*I-1	VPC04	23
C	K=J+1	VPC04	24
C	VX(I)=X0(J)	VPC04	25
C	VY(I)=X0(K)	VPC04	26
C	CALL SHAPE(PX,A,S)	VPC04	27
C		VPC04	28
C	NOTE: COORDINATE VX(I) IS THE Y-COORDINATE IN THE CROSS FLOW	VPC04	29
C	COORDINATE VY(I) IS THE Z-COORDINATE IN THE CROSS FLOW	VPC04	30
C	PLANE.	VPC04	31
C	.. COMPUTE VELOCITIES IN THE CROSSFLOW PLANE ...	VPC04	32
C	V(I) IS IN THE Y-DIRECTION,	VPC04	33
C	W(I) IS IN THE Z-DIRECTION.	VPC04	34
C		VPC04	35
C		VPC04	36
C	R=SQRT(.5*(S+S+A**4/(S+S)))	VPC04	37
C	DO 31 J=1,4	VPC04	38
C	NCC(J)=0	VPC04	39
C	IF(D1,NE,0.)NCC(1)=1	VPC04	40
C	IF(D2,NE,0.)NCC(2)=1	VPC04	41
C	IF(D3,NE,0.)NCC(3)=1	VPC04	42
C	IF(D4,NE,0.)NCC(4)=1	VPC04	43
C	MM=NCC(2)+NCC(4)	VPC04	44
C	VV=NCC(1)+NCC(3)	VPC04	45
C	DO 100 I=1,NV	VPC04	46
C	X=VX(I)	VPC04	47
C	Y=VY(I)	VPC04	48
C	VS=0.	VPC04	49
C	+S=0.	VPC04	50
C	IF(AL,NE,0.)CALL PITRIL(AL,X,Y,VS,+S)	VPC04	51
C	V(I)=VS	VPC04	52
C	W(I)=-S	VPC04	53
C	IF(RE,EQ,0.)GO TO 17	VPC04	54
C	CALL PITRIL(RE,Y,-X,VS,+S)	VPC04	55
C	V(I)=V(I)+S	VPC04	56
C	W(I)=-W(I)+VS	VPC04	57
C	17 CONTINUE	VPC04	58
C	IF(NDFL,EQ,0,OR,IFIN,EG,0)GO TO 60	VPC04	59
C	IF(MH,EQ,0)GO TO 6	VPC04	60
C	IF(M+EQ,1)GO TO 5	VPC04	61
C	CALL 9YHFA(1,04,X,Y,VS,+S)	VPC04	62
C	V(I)=V(I)+VS	VPC04	63

```

W(I)=W(I)+*S
5 CONTINUE
IF (MH, EQ, 2) GO TO 8
IF (NCC(2), EQ, 1) NC=1
IF (NCC(4), EQ, 1) NC=3
IF (NCC(2), EQ, 1) DD=02
IF (NCC(4), EQ, 1) DD=04
CALL CRUCI(NC, DD, X, Y, VS, *S)
V(I)=V(I)+VS
W(I)=W(I)+*S
GO TO 6
8 DD=02=04
CALL CRUCI(1, DD, X, Y, VS, *S)
V(I)=V(I)+VS
W(I)=W(I)+*S
6 CONTINUE
IF (MV, EQ, 0) GO TO 66
IF (MV, EQ, 1) GO TO 55
CALL SYMFIN(2, 03, X, Y, VS, *S)
V(I)=V(I)+VS
W(I)=W(I)+*S
55 CONTINUE
IF (MV, EQ, 2) GO TO 88
IF (NCC(1), EQ, 1) NC=2
IF (NCC(3), EQ, 1) NC=4
IF (NCC(1), EQ, 1) DD=01
IF (NCC(3), EQ, 1) DD=03
CALL CRUCI(NC, DD, X, Y, VS, *S)
V(I)=V(I)+VS
W(I)=W(I)+*S
GO TO 66
88 DD=01=03
CALL CRUCI(2, DD, X, Y, VS, *S)
V(I)=V(I)+VS
W(I)=W(I)+*S
66 CONTINUE
C
C IF FIN LE VORTICITY IS INCLUDED, DETERMINE BY INTERPOLATION THE
C EFFECTS OF THE SPECIFIED VORTICITY.
C
C NOTE: HERE IFIN=1...RIGHT FIN
C 2...LEFT FIN
C 3...UPPER FIN
C 4...LOWER FIN.
C
IF (NEDGV, EQ, 0) GO TO 20
IFIN=1
KSTART=1
KUL=MSWR
23 CONTINUE
IF (IFIN, EQ, 5) GO TO 20
IF (IFIN, EQ, 2) KSTART=MSWR+1
IF (IFIN, EQ, 3) KSTART=MSWR+MS-L+1
IF (IFIN, EQ, 4) KSTART=MSWR+*S*L+*S*U+1
DO 21 IFV=KSTART, KUL
IF (PX, LY, XLE(KSTART)) GO TO 20
JV=IFV-1
IF (IFV, EQ, 1) JV=1
IF (PX, LE, XLE(IFV)) GO TO 22
21 CONTINUE
IF (PX, LE, XTIPLE) GO TO 3A
GO TO 20
22 KV=JV+1

```

```

VPC04 64
VPC04 65
VPC04 66
VPC04 67
VPC04 68
VPC04 69
VPC04 70
VPC04 71
VPC04 72
VPC04 73
VPC04 74
VPC04 75
VPC04 76
VPC04 77
VPC04 78
VPC04 79
VPC04 80
VPC04 81
VPC04 82
VPC04 83
VPC04 84
VPC04 85
VPC04 86
VPC04 87
VPC04 88
VPC04 89
VPC04 90
VPC04 91
VPC04 92
VPC04 93
VPC04 94
VPC04 95
VPC04 96
VPC04 97
VPC04 98
VPC04 99
VPC04100
VPC04101
VPC04102
VPC04103
VPC04104
VPC04105
VPC04106
VPC04107
VPC04108
VPC04109
VPC04110
VPC04111
VPC04112
VPC04113
VPC04114
VPC04115
VPC04116
VPC04117
VPC04118
VPC04119
VPC04120
VPC04121
VPC04122
VPC04123
VPC04124
VPC04125
VPC04126

```

```

X1=XLE(JV)
X2=XLE(KV)
WT1=(X2-PX)/(X2-X1)
WT2=(PX-X1)/(X2-X1)
IF (IFIN.EQ.3.OR.IFIN.EQ.4) GO TO 24
YVINT=WT1*CGLOC(JV)+WT2*CGLOC(KV)
ZVHAR=(PX-XF(1))*TAN(AL/2.0)
GAMINT=WT1*GAMLE(JV)+WT2*GAMLE(KV)
GO TO 39
3A GAMINT=GAMLE(KUL)
IF (IFIN.EQ.3.OR.IFIN.EQ.4) GO TO 40
YVINT=CGLOC(KUL)
ZVHAR=(PX-XF(1))*TAN(AL/2.0)
GO TO 39
40 ZVINT=CGLOC(KUL)
YVHAR=(PX-XF(1))*TAN(BE/2.0)
GO TO 41
39 CALL VVFLS(1,X,Y,YVINT,ZVHAR,GAMINT,A,VS,NS,VRTMAX)
GO TO 25
24 ZVINT=WT1*CGLOC(JV)+WT2*CGLOC(KV)
YVHAR=(PX-XF(1))*TAN(BE/2.0)
GAMINT=WT1*GAMLE(JV)+WT2*GAMLE(KV)
41 CALL VVFLS(1,X,Y,YVHAR,ZVINT,GAMINT,A,V,NS,VRTMAX)
25 V(I)=V(I)+VS
W(I)=W(I)+WS
IFIN=IFIN+1
IF (IFIN.EQ.2) KUL=NSR+NSWL
IF (IFIN.EQ.3) KUL=NSR+NSWL+NSU
IF (IFIN.EQ.4) KUL=NSR+NSWL+NSU+NSWD
GO TO 23
20 CONTINUE
C
C
C
C
IF FIN SP VORTICITY IS INCLUDED, DETERMINE BY INTERPOLATION THE
EFFECTS OF THE SPECIFIED VORTICITY.
IF (NSIDG.EQ.0) GO TO 26
IFIN=1
KSTART=1
KUL=NC
27 CONTINUE
IF (IFIN.EQ.5) GO TO 28
IF (IFIN.EQ.2) KSTART=NC+1
IF (IFIN.EQ.3) KSTART=2*NC+1
IF (IFIN.EQ.4) KSTART=3*NC+1
DO 29,JSE=KSTART,KUL
IF (PX,LT,XSE(KSTART)) GO TO 28
JVSE=JSE-1
IF (JSE.EQ.1) JVSE=1
IF (PX,LE,XSE(JVSE)) GO TO 30
29 CONTINUE
IF (PX,LE,XTJPT) GO TO 51
GO TO 26
30 KVSE=JVSE+1
X1=XSE(JVSE)
X2=XSE(KVSE)
WT1=(X2-PX)/(X2-X1)
WT2=(PX-X1)/(X2-X1)
IF (IFIN.EQ.3.OR.IFIN.EQ.4) GO TO 32
YVINT=WT1*CGSELG(JVSE)+WT2*CGSELG(KVSE)
ZVHAR=(PX-XF(1))*TAN(AL/2.0)
GAMINT=WT1*GAMSE(JVSE)+WT2*GAMSE(KVSE)
GO TO 50
VPC04127
VPC04128
VPC04129
VPC04130
VPC04131
VPC04132
VPC04133
VPC04134
VPC04135
VPC04136
VPC04137
VPC04138
VPC04139
VPC04140
VPC04141
VPC04142
VPC04143
VPC04144
VPC04145
VPC04146
VPC04147
VPC04148
VPC04149
VPC04150
VPC04151
VPC04152
VPC04153
VPC04154
VPC04155
VPC04156
VPC04157
VPC04158
VPC04159
VPC04160
VPC04161
VPC04162
VPC04163
VPC04164
VPC04165
VPC04166
VPC04167
VPC04168
VPC04169
VPC04170
VPC04171
VPC04172
VPC04173
VPC04174
VPC04175
VPC04176
VPC04177
VPC04178
VPC04179
VPC04180
VPC04181
VPC04182
VPC04183
VPC04184
VPC04185
VPC04186
VPC04187
VPC04188
VPC04189

```


51	GAMINT=GAMSE(KUL)	VPC04190
	IF (IFIN.EQ.3.OR,IFIN.EQ.4) GO TO 52	VPC04191
	YVINT=CGSELC(KUL)	VPC04192
	ZVBAR=(PX-XF(1))*TAN(AL/2,0)	VPC04193
	GO TO 59	VPC04194
52	ZVINT=CGSELC(KUL)	VPC04195
	YVBAR=(PX-XF(1))*TAN(BE/2,0)	VPC04196
	GO TO 53	VPC04197
59	CALL VVELS (1,X,Y,YVINT,ZVBAR,GAMINT,A,VS,WS,VRTMAX)	VPC04198
	GO TO 35	VPC04199
32	ZVINT=WT1*CGSELC(JVSE)+WT2*CGSELC(KVSE)	VPC04200
	YVBAR=(PX-XF(1))*TAN(BE/2,0)	VPC04201
	GAMINT=WT1*GAMSE(JVSE)+WT2*GAMSE(KVSE)	VPC04202
53	CALL VVELS(1,X,Y,YVBAR,ZVINT,GAMINT,A,VS,WS,VRTMAX)	VPC04203
35	V(I)=V(I)+VS	VPC04204
	W(I)=W(I)+WS	VPC04205
	IFIN=IFIN+1	VPC04206
	IF (IFIN.EQ.2) KUL=2*NDK	VPC04207
	IF (IFIN.EQ.3) KUL=3*NDK	VPC04208
	IF (IFIN.EQ.4) KUL=4*NDK	VPC04209
	GO TO 27	VPC04210
28	CONTINUE	VPC04211
100	CONTINUE	VPC04212
	CALL VOTEX(NV,VX,VY,G,VV,*)	VPC04213
	CAL=COS(AC)	VPC04214
	DO 101 I=1,NV	VPC04215
	V(I)=V(I)+VV(I)	VPC04216
	W(I)=W(I)+WW(I)	VPC04217
	J=2*I-1	VPC04218
	K=J+1	VPC04219
	W(K)=V(I)/CAL	VPC04220
	W(K)=W(I)/CAL	VPC04221
101	CONTINUE	VPC04222
	RETURN	VPC04223
	END	VPC04224

	COMPLEX FUNCTION FCT(T)	VPC05 1
C		VPC05 2
C	VERSION: VPATH2	VPC05 3
C		VPC05 4
C	FCT IS THE INTEGRAND OF THE INTEGRAL ASSOCIATED WITH VELOCITY	VPC05 5
C	COMPONENTS FOR THE SINGLY DEFLECTED FIN CASE.	VPC05 6
C		VPC05 7
	COMPLEX SIG,SS	VPC05 8
	COMMON AA,SIG,SS,GAM	VPC05 9
	TE=COS(2,*T)-AA	VPC05 10
	IF(T.GE.GAM)TE=0.	VPC05 11
	FCT=2.*(SQRT(TE)+SQRT(COS(2,*T)+AA-1))*((SS+1)*COS(T)	VPC05 12
	-2.*SIG)/((SS-2.*SIG+COS(T)+1)*(SS-2.*SIG+COS(T)+1))	VPC05 13
	RETURN	VPC05 14
	END	VPC05 15

SUBROUTINE PITROL(AL,X,Y,VS,RS)		VPC06	1
C		VPC06	2
C	VERSION: VPATH2	VPC06	3
C		VPC06	4
C	THIS SUBROUTINE COMPUTES THE CROSSFLOW VELOCITY COMPONENTS FOR A CROU	VPC06	5
C	*ING BODY CONFIGURATION AT ANGLE OF ATTACK AL, AND SIDESLIP ANGLE BE	VPC06	6
C		VPC06	7
C	COMMON/BLK1/A,R,S,PI,CI	VPC06	8
C	COMPLEX Z,CI,ZA,SO,SOS,VELAL	VPC06	9
C	AA=AA*	VPC06	10
C	Z=CMPLX(X,Y)	VPC06	11
C	ZA=Z+AA/Z	VPC06	12
C	SA=S+AA/S	VPC06	13
C	SO=ZA*ZA+SA*SA	VPC06	14
C	AY=1.0	VPC06	15
C	IF(AIMAG(ZA).LT.0.0) AY=-1.0	VPC06	16
C	AYZ=1.0	VPC06	17
C	IF(AIMAG(SO).LT.0.0) AYZ=-1.0	VPC06	18
C	SOS=CSORT(SO)*AY*AYZ	VPC06	19
C	IF((ABS(AIMAG(ZA)).LE.0.0).AND.(REAL(ZA).LT.0.0))SOS=CMPLX(-REAL(SV	VPC06	20
C	ROS),AIMAG(SOS))	VPC06	21
C	VELAL=-CI*SIN(AL)*(1.-AA/Z**2)*ZA/SOS	VPC06	22
C		VPC06	23
C	VS=...SIDEWASH INCLUDING FREE STREAM COMPONENT	VPC06	24
C	*S=...CRASH INCLUDING FREE STREAM COMPONENT	VPC06	25
C		VPC06	26
C	VS=REAL(VELAL)	VPC06	27
C	*S=-4*MAG(VELAL)	VPC06	28
C	RETURN	VPC06	29
C	END	VPC06	30

SUBROUTINE PLOTVB(X,Y,Z,NP,N(PI,NVN,NDP,ROT,XE,YE,NE,X2,Y2)		VPC07	1
C		VPC07	2
C	VERSION: VPATH2	VPC07	3
C		VPC07	4
C	ROUTINE TO GENERATE A PLOT VORTEX LOCATION RELATIVE TO	VPC07	5
C	THE KING-BODY CONFIGURATION	VPC07	6
C	DEFINITIONS:	VPC07	7
C	NC = INDEX OF CURVE	VPC07	8
C	NPI = NO. OF BODY STATIONS	VPC07	9
C	NVN = NO. OF VORTICES	VPC07	10
C	NE = NO. OF KING DEFINITION CARDS	VPC07	11
C		VPC07	12
C	DIMENSION X(NDP,52),Y(NDP,52),Z(NDP,52)	VPC07	13
C	DIMENSION NP(52),ROT(1),XCG(3),XE(7),YE(7)	VPC07	14
C	DIMENSION X2(17,18),Y2(17,18),NP2(18),SYMHDL(40)	VPC07	15
C		VPC07	16
C	DATA L=10,LENG,XCG/ 100,SO, 0.,0.,0./	VPC07	17
C	DATA SYMHDL / 1H*,1H*,1H*,1H*,1H0,1H1,1H2,1H3,1H4,1H5,1H6,	VPC07	18
C	* 1H7,1H8,1H9,1H*,1H*,1H*,1H0,1H*,1H*,1H*,1H*,1H*,1H*,1H*,1H*,1H*,	VPC07	19
C	* 1H*,1H*,1H0,1H*,1H0,1H*,1H*,1H*,1H0,1H*,1H*,1H*,1H*,1H*,1H*,1H*/	VPC07	20
C	WRITE(6,10)	VPC07	21
C	WRITE(6,11)	VPC07	22
10	FORMAT(1H1)	VPC07	23
11	FORMAT(1H2)	VPC07	24
C		VPC07	25
C	FIND MAXIMUM DIAMETER	VPC07	26
C		VPC07	27

```

      HMAX=0.
      DO 100 I=1,NIP1
100    RMAX=AMAX1(HMAX,Y(1,I+1),Z(1,I+1))
      C
      C CURVE 1: DRAW AXES
      C
      NC=1
      DO 120 I=1,6
      Y(I,1)=Y(1,1)
      Y(I,1)=0.
120    Z(I,1)=0.
      X(2,1)=X(1,NIP1+1)
      Y(4,1)=1.5*RYAX
      Z(6,1)=1.5*RHMAX
      NP(1)=6
      C
      C CURVES: 2 TO NIP1+1
      C GENERATE CROSS SECTIONS
      C
      NGV=NIP1+NVN+3
      MERID=17
      DO 160 J=1,NIP1
      NC=NC+1
      R1 =X(1,NC)
      RLOC=Y(1,NC)
      RLOC=Z(1,NC)
      SLOC=Y(2,NC)
      C SAVE RLOC AND BLOC
      Y(J,NGV)=RLOC
      Z(J,NGV+1)=RLOC
      Y(J,NGV+2)=SLOC
      C
      C GENERATE BODY CROSS SECTION
      C
      DTH=2.*3.1415926/(MERID-1)
      DO 140 I=1,MERID
      PHI=(I-1)*DTH
      RAD=(COS(PHI)/RLOC)**2+(SIN(PHI)/RLOC)**2
      RAD=SQRT(1./RAD)
      Y(I,NC)=RAD*SIN(PHI)
      Z(I,NC)=RAD*COS(PHI)
      X(I,NC)=R1
140    CONTINUE
160    NP(NC)=MERID
      C
      C PLOT VORTEX LOCATION (ALREADY DEFINED)
      C
      DO 170 I=1,NVN
      NC=NC+1
170    NP(NC)=NIP1
      C
      C WING OUTLINE
      C
      IF (NF.LE.0) GO TO 200
      DO 180 J=1,NF
      NC=NC+1
      SGN=(-1)**(J+1)
      DO 180 I=1,NF
      X(I,NC)=XF(I)
      Y(I,NC)=YF(I)*SGN
      Z(I,NC)=0.0
180    CONTINUE
      NF=NF+1

```

```

VPC07 28
VPC07 29
VPC07 30
VPC07 31
VPC07 32
VPC07 33
VPC07 34
VPC07 35
VPC07 36
VPC07 37
VPC07 38
VPC07 39
VPC07 40
VPC07 41
VPC07 42
VPC07 43
VPC07 44
VPC07 45
VPC07 46
VPC07 47
VPC07 48
VPC07 49
VPC07 50
VPC07 51
VPC07 52
VPC07 53
VPC07 54
VPC07 55
VPC07 56
VPC07 57
VPC07 58
VPC07 59
VPC07 60
VPC07 61
VPC07 62
VPC07 63
VPC07 64
VPC07 65
VPC07 66
VPC07 67
VPC07 68
VPC07 69
VPC07 70
VPC07 71
VPC07 72
VPC07 73
VPC07 74
VPC07 75
VPC07 76
VPC07 77
VPC07 78
VPC07 79
VPC07 80
VPC07 81
VPC07 82
VPC07 83
VPC07 84
VPC07 85
VPC07 86
VPC07 87
VPC07 88
VPC07 89
VPC07 90

```

	X(NF1,NC)=XF(1)	VPC07 91
	Y(NF1,NC)=YF(1)*SGN	VPC07 92
	Z(NF1,NC)=0.0	VPC07 93
	NP(NC)=NF1	VPC07 94
190	CONTINUE	VPC07 95
200	CONTINUE	VPC07 96
C		VPC07 97
C	PLOT CROSS SECTIONS WITH VORTEX LOCATIONS -----	VPC07 98
C		VPC07 99
	DO 240 JSECTN=1,3	VPC07100
	IF (JSECTN.EQ.1) JSECTN=1	VPC07101
	IF (JSECTN.EQ.2) JSECTN=NPI/2	VPC07102
	IF (JSECTN.EQ.3) JSECTN=NPI	VPC07103
C		VPC07104
C	COPY BODY	VPC07105
C		VPC07106
	DO 220 I=1,NERID	VPC07107
	X2(I,1)=Y(I,JSECTN+1)	VPC07108
	Y2(I,1)=Z(I,JSECTN+1)	VPC07109
220	CONTINUE	VPC07110
	NP2(1)=NERID	VPC07111
	NC2=1	VPC07112
C		VPC07113
C	ATING OUTER BOUNDARIES	VPC07114
C		VPC07115
	SLOC=Y(JSECTN,NGV+2)	VPC07116
	X2(1,2)=SLOC	VPC07117
	Y2(1,2)=0.	VPC07118
	X2(2,2)=SLOC	VPC07119
	Y2(2,2)=0.	VPC07120
	NP2(2)=2	VPC07121
	NC2=NC2+1	VPC07122
C		VPC07123
C	COPY VORTICES AT JSECTN	VPC07124
C		VPC07125
	DO 230 J=1,NVN	VPC07126
	NC2=NC2+1	VPC07127
	JCV=NPI+1+J	VPC07128
	X2(1,NC2)=Y(JSECTN,JCV)	VPC07129
	Y2(1,NC2)=Z(JSECTN,JCV)	VPC07130
	NP2(NC2)=1	VPC07131
230	CONTINUE	VPC07132
C		VPC07133
C	PLOT CROSS SECTIONS	VPC07134
C		VPC07135
	CALL PLOT2(X2,Y2,3,NP2,17,NC2,L*ID,LENG)	VPC07136
	WRITE(6,23) JSECTN,A(1,JSECTN+1)	VPC07137
	WRITE(6,24) (I,SYMBOL(I+2),I=1,NVN)	VPC07138
240	CONTINUE	VPC07139
C		VPC07140
C	PLOT PERSPECTIVE VIEWS -----	VPC07141
C		VPC07142
C	TOP VIEW	VPC07143
C		VPC07144
	CALL PLOT2(X,Y,3,NP,NP,NC,L*ID,LENG)	VPC07145
	CALL PLOT2(A,Y,3,NP,NP,NC,L*ID,LENG,LINE,NLIP)	VPC07146
	WRITE(6,20)	VPC07147
	NSYM=NVN	VPC07148
	JSYM=1+NPI	VPC07149
	JN = JSYM+NVN	VPC07150
	IF (JN.GT.40) NSYM=JN-30	VPC07151
	WRITE(6,24) (I,SYMBOL(I+JSYM),I=1,NSYM)	VPC07152
	IF (JN.LE.40) GO TO 210	VPC07153

```

      JSYM=NSYM+1
      ISYM = NSYM
      WRITE(6,24) (I,SYMBOL(I+ISYM),I=JSYM,NVM)
210  CONTINUE
C
C   SIDE VIEW
      CALL PLOT42(X,Z,S,NP,NDP,NC,L=10,LENG)
C   CALL PLOT42(X,Z,S,NP,NDP,NC,L=10,LENG,LINE,MLIN)
      WRITE(6,21)
C
C   PERSPECTIVE VIEW
      ROT(1) = 0.
      ROT(2) = 30.
      ROT(3) = 20.
      CALL PLOT43(X,Y,Z,NP,NDP,NC,ROT,XCG,X,Y,3)
      CALL PLOT42(X,Y,3,NP,NDP,NC,L=10,LENG)
C   CALL PLOT42(X,Y,S,NP,NDP,NC,L=10,LENG,LINE,MLIN)
      WRITE(6,22) ROT
C
C
C
20  FORMAT(/20X,22HTOP VIEW = Y VERSUS X)
21  FORMAT(/20X,22HSIDE VIEW = Z VERSUS X)
22  FORMAT(/20X,18HPERSPECTIVE = ROT=,3F10,2)
23  FORMAT(/20X,29HBODY CROSS SECTION = JSFCTN=,I3,
*   5X,4MXIP=,F10,3)
24  FORMAT(20X,14HVORTEK SYMBOLS,10(1X,I2,1H=,A1,1H,))
C
C   RETURN
      END

```

```

SUBROUTINE SHAPE(X,R,S)
C
C   VERSION: VPATH2
C
C   SUBROUTINE TO COMPUTE LOCAL BODY RADIUS AND FIN SPAN MEASURED FROM
C   THE BODY CENTERLINE
C
      COMMON/VEL/AL,BE,D1,D2,D3,D4,VX(30),VY(30),G(30),AV,NDEL,NS,NF,
      IXE(7),XFE(7),YFE(7),C(7,7),IFIN
      IFIN=0
      DO 1 K=1,NS
      XL=XE(K)
      J=K
      IF(X,LE,XL)GO TO 2
1  CONTINUE
      2  R=C(J,1)+X+C(J,5)+X+X+C(J,6)
      ARG=X+Y+C(J,2)+X+C(J,3)+C(J,4)
      R=R+SQRT(ARG)*C(J,7)
      S=R
      IF(NF,FE,0)RETURN
      IF(X,LE,XE(1),OR,X,GT,XE(NF))RETURN
      IFIN=1
      DO 3 K=2,NF
      J=K
      XL=XF(K)
      IF(X,LE,XL)GO TO 4
3  CONTINUE
      4  JI=J-1
      S=(X-XF(JI))*(YF(J)-YF(JI))/(XF(J)-XF(JI))+YF(JI)
      RETURN
      END

```

```

COMPLEX FUNCTION SIMP(A,B,N,F)          VPC09 1
C                                     VPC09 2
C                                     VPC09 3
C                                     VPC09 4
C                                     VPC09 5
C                                     VPC09 6
C                                     VPC09 7
C                                     VPC09 8
C                                     VPC09 9
C                                     VPC09 10
C                                     VPC09 11
C                                     VPC09 12
C                                     VPC09 13
C                                     VPC09 14
C                                     VPC09 15
C                                     VPC09 16
C                                     VPC09 17
C                                     VPC09 18
C                                     VPC09 19

EXTERNAL F
COMPLEX F,SUMEND,SUMID
TANH=(B-A)/N
H=TANH/2.
SUMEND=CNPLX(0.,0.)
SUMID=CNPLX(0.,0.)
DO 1 K=1,N
X=A+FLOAT(K-1)*TANH
SUMEND=SUMEND+F(X)
1 SUMID=SUMID+F(X+H)
SIMP=(2.*SUMEND+4.*SUMID-F(A)+F(B))*H/3.
RETURN
END

```

```

SUBROUTINE SYMFIN(NC,D,X,Y,VS,WS)      VPC10 1
C                                     VPC10 2
C                                     VPC10 3
C                                     VPC10 4
C THIS SUBROUTINE COMPUTES THE CROSSFLOW VELOCITY COMPONENTS VS,WS VPC10 5
C AT THE POINT X,Y, INDUCED BY A SYMMETRIC DEFLECTION OF A PAIR OF FIN VPC10 6
C BY AN ANGLE D RADIANS IN A CRUCIFORM WING BODY COMBINATION. THE CC VPC10 7
C NC DETERMINES WHICH PAIR OF FINS ARE DEFLECTED. IF NC=1, HORIZONTAL VPC10 8
C IF NC=2 IT IS THE VERTICAL PAIR. VPC10 9
C                                     VPC10 10
C                                     VPC10 11
C                                     VPC10 12
C                                     VPC10 13
C                                     VPC10 14
C                                     VPC10 15
C                                     VPC10 16
C                                     VPC10 17
C                                     VPC10 18
C                                     VPC10 19
C                                     VPC10 20
C                                     VPC10 21
C                                     VPC10 22
C                                     VPC10 23
C                                     VPC10 24
C                                     VPC10 25
C                                     VPC10 26
C                                     VPC10 27
C                                     VPC10 28
C                                     VPC10 29
C                                     VPC10 30
C                                     VPC10 31
C                                     VPC10 32
C                                     VPC10 33
C..... SECOND TERM VPC10 34
C                                     VPC10 35
C                                     VPC10 36
C                                     VPC10 37
C                                     VPC10 38
C                                     VPC10 39

COMMON/HLK1/A,R,S,PI,CI
COMPLEX CI,T,TT,TPA,SQ,CC, T2,T3,T4,VCL,T,CL,CLI,ARG,TINV,CCS
RO=.5*(S+AAA/S)
XS=X
YS=Y
IF THE VERTICAL FINS ARE DEFLECTED ROTATE (X,Y) BY PI/2
IF(NC.NE.2)GO TO 1
XS=Y
YS=-X
1 TZ=CNPLX(ABS(XS),ABS(YS))
TT=T+T
AA=A*AA
TPA=TT+AA
SQ=TPA+TPA
TMA=TI-AA
CCS=SQ=0.,*RO*TT
SRT=SQRT(1.-AA/400)
IF(ATANH(CCS),GE.0.)CC=CSQRT(CCS)
IF(ATANH(CCS),LT.0.)CC=-CSQRT(CCS)
T2=TPA+SRT/(A+CC/RO)
ARG=(CI+TT)/(CI-TI)
CL=CLCLOG(ANG)
TINV=CI*.5*CLI
T2= (TMA/TT)*.5*CLI

```

C...	THIRD TERM	VPC10	40:
	T3=CT*PI*.5*TPA/TT	VPC10	41:
C....	FOURTH TERM	VPC10	42:
	T4=CI+TMA*TPA*(PI*.5+ACOS(A/R0))/(CC+TT)	VPC10	43:
C....	VELOCITY	VPC10	44:
	VEL=0*(T2+T3+T4)/PI	VPC10	45:
	V=REAL(VEL)	VPC10	46:
	W=AI*AG(VEL)	VPC10	47:
	IF(XS*YS,LT,0.)V=W	VPC10	48:
	VS=V	VPC10	49:
	WS=W	VPC10	50:
	IF(NC.NE.2)RETURN	VPC10	51:
	VS=W	VPC10	52:
	WS=V	VPC10	53:
	RETURN	VPC10	54:
	END	VPC10	55:

	SUBROUTINE VUTEX(NV,XV,YV,GV,VV,WW)	VPC11	1:
C		VPC11	2:
C	VERSION: VPATH2	VPC11	3:
C		VPC11	4:
C	THIS SUBROUTINE COMPUTES THE PERTURBATION VELOCITY COMPONENTS AT THE	VPC11	5:
C	VORTEX LOCATIONS ACCOUNTING FOR MUTUAL EFFECTS AND THE PRESENCE	VPC11	6:
C	OF A CRUCIFORM BIRING RUDY COMBINATION	VPC11	7:
C		VPC11	8:
	DIMENSION XV(30),YV(30),GV(30),VV(30),WW(30)	VPC11	9:
	DIMENSION VX(30),VY(30),G(30)	VPC11	10:
	COMMON/VV/AG,R4	VPC11	11:
	COMMON/SLK1/A,R,S,PI,CT	VPC11	12:
	EXTERNAL Z	VPC11	13:
	COMPLEX CI,T0,Z,S0,T2,S2,T3,S3,T4,S4,TM44,SMR4,DSOT,DTOS,D2SDT	VPC11	14:
	I,V1,V2,V3,VEL,TAU,S1,SOB,SIN	VPC11	15:
	NN=NV-1	VPC11	16:
	AA=AA+AA	VPC11	17:
	AA=AA*AA	VPC11	18:
	RR=RR+RR	VPC11	19:
	RR=RR+RR	VPC11	20:
	DO 100 I=1,NV	VPC11	21:
	X0=XV(I)	VPC11	22:
	Y0=YV(I)	VPC11	23:
	G0=GV(I)	VPC11	24:
	K1=0	VPC11	25:
	DO 99 J=1,NV	VPC11	26:
	IF(J.EQ.1)GO TO 99	VPC11	27:
	K1=K1+1	VPC11	28:
	VX(K1)=XV(J)	VPC11	29:
	VY(K1)=YV(J)	VPC11	30:
	G(K1)=GV(J)	VPC11	31:
99	CONTINUE	VPC11	32:
	T0=CMPLX(X0,Y0)	VPC11	33:
	S0=Z(T0)	VPC11	34:
	SOB=CONJG(S0)	VPC11	35:
	T2=T0+T0	VPC11	36:
	T3=T0+T2	VPC11	37:
	T4=T2+T2	VPC11	38:
	S2=S0+S0	VPC11	39:
	S3=S2+S0	VPC11	40:
	S4=S2+S2	VPC11	41:
	TM44=T4-AA	VPC11	42:
	SMR4=S4-AA	VPC11	43:

	DSOT=TM44*S3/(T3+S444)	VPC11 44
	DTDS=SM44+T3/(S3+T44)	VPC11 45
	D2SDT=S3*(T3+3.*A4)/(SM44+T4)=S2*DSOT*TM44*(S4+3.*R4)/	VPC11 46
	I(T3+SM44+S44)	VPC11 47
	V1=-GD*DTDS*D2SDT/2.	VPC11 48
	V2=GD*DSOT*SDR/(SDR+SN=RW)	VPC11 49
	V3=CMPLX(G.,H.)	VPC11 50
	DO 3 K=1,N	VPC11 51
	TAU=CMPLX(VX(K),VY(K))	VPC11 52
	SI=Z(TAU)	VPC11 53
	SIB=CMPLX(SI)	VPC11 54
3	V3=V3-G(K)*(1./(SD-SI)-SIB/(SD*SIB-V3))+DSOT	VPC11 55
	VEL=CI*(V1+V2+V3)/(PI+P1)	VPC11 56
	VV(I)=REAL(VEL)	VPC11 57
	MM(I)=-4*MAG(VEL)	VPC11 58
100	CONTINUE	VPC11 59
	RETURN	VPC11 60
	END	VPC11 61

	SUBROUTINE VVELS(NV,YY,ZZ,VX,VY,G,RB,V,*,VRTMAX)	VPC12 1
C		VPC12 2
C	VERSION: VPATH2.	VPC12 3
C		VPC12 4
C	THIS SUBROUTINE COMPUTES PERTURBATION VELOCITY COMPONENTS DUE TO	VPC12 5
C	NV EXTERNAL VORTICES AND THEIR IMAGES INSIDE A BODY WITH CIRCULAR	VPC12 6
C	CROSS SECTION.	VPC12 7
C	CENTER VORTEX EFFECTS ARE NOT ACCOUNTED FOR.	VPC12 8
C		VPC12 9
C	DIMENSION VX(1),VY(1),G(1)	VPC12 10
		VPC12 11
	TLC=0.000001	VPC12 12
	PI=3.1415926	VPC12 13
	V=0.	VPC12 14
	R=0.	VPC12 15
	VX=VY/R	VPC12 16
	Z=ZZ/R	VPC12 17
	DO 1 I=1,NV	VPC12 18
	GG=G(I)/(2.*PI*RB)	VPC12 19
	XV=VX(I)/RB	VPC12 20
	YV=VY(I)/RB	VPC12 21
	ZVS=XV*XV+YV*YV	VPC12 22
	DY=Y-XV	VPC12 23
	DZ=Z-YV	VPC12 24
	DYS=DY*DY	VPC12 25
	DZS=DZ*DZ	VPC12 26
	DEN1=DYS+DZS	VPC12 27
	IF(DEN1.LE.TLC) GO TO 2	VPC12 28
	VAV=GG*DZ/DEN1	VPC12 29
	WAV=GG*DY/DEN1	VPC12 30
2	DEN2=(Y-XV/ZVS)**2+(Z-YV/ZVS)**2	VPC12 31
	IF(ABS(DEN2).LE.TLC) GO TO 3	VPC12 32
	VAV+GG*(Z-YV/ZVS)/DEN2	VPC12 33
	WAV+GG*(Y-XV/ZVS)/DEN2	VPC12 34
3	CONTINUE	VPC12 35
C		VPC12 36
C	LIMIT MAGNITUDE OF PERTURBATION VELOCITIES TO VRTMAX.	VPC12 37
C		VPC12 38
1	CONTINUE	VPC12 39
	IF (V,GT.,0.,0.,AND,ABS(V),GE,VRTMAX) V=VRTMAX	VPC12 40


```

IF (V.LT.0.0.AND.ABS(V).GE.VRTMAX) V=-VRTMAX
IF (-.GT.0.0.AND.ABS(V).GE.VRTMAX) V=VRTMAX
IF (-.LT.0.0.AND.ABS(V).GE.VRTMAX) V=-VRTMAX
RETURN
END

```

```

VPC12 41
VPC12 42
VPC12 43
VPC12 44
VPC12 45

```

C
C
C
C
C
C
C

COMPLEX FUNCTION Z(C1)

VERSION: VPATH2

THIS FUNCTION ROUTINE CALCULATES THE SIGMA VALUE IN THE
TRANSFORMED (CIRCLE) PLANE FOR GIVEN TAU IN THE PHYSICAL PLANE
TAU=X+IY

```

COMMON/V/A4,R4
COMPLEX T,II,TPA,STP,SI,TPA2,SSI,SSTP,CT
R1=ABS(REAL(CT))
R1=ABS(AIMAG(CT))
I1=0
II=0
IF (R1.NE.0.) I1=REAL(CT)/R1
IF (R1.NE.0.) II=AIMAG(CT)/R1
T=CMPLX(R1,I1)
II=II+T
TPA=II+A4/II
TPA2=TPA*TPA
STP=TPA2-4.*R4
AY=1.0
IF (AIMAG(TPA).LT.0.0) AY=-1.0
AYZ=1.0
IF (AIMAG(STP).LT.0.0) AYZ=-1.0
SSTP=CSORT(STP)*AY*AYZ
IF ((ABS(AIMAG(TPA)).LE.0.0).AND.(REAL(TPA).LT.0.0))
1 S1=CMPLX(-REAL(SSTP),AIMAG(SSTP))
SSI=.5*(TPA+S1)
SI=CSORT(SSI)
Z=CMPLX(I1*ABS(REAL(SI)),II*ABS(AIMAG(SI)))
RETURN
END

```

```

VPC13 1
VPC13 2
VPC13 3
VPC13 4
VPC13 5
VPC13 6
VPC13 7
VPC13 8
VPC13 9
VPC13 10
VPC13 11
VPC13 12
VPC13 13
VPC13 14
VPC13 15
VPC13 16
VPC13 17
VPC13 18
VPC13 19
VPC13 20
VPC13 21
VPC13 22
VPC13 23
VPC13 24
VPC13 25
VPC13 26
VPC13 27
VPC13 28
VPC13 29
VPC13 30
VPC13 31
VPC13 32
VPC13 33

```

PROGRAM VPATHL

<u>ROUTINE</u>	<u>IDENTIFICATION</u> Cols. 73-77	<u>PAGE NO.</u>
1. VPATHL	VPL01	437
2. DASCURU	02	443
3. DBLU	03	445
4. DSDZ	04	446
5. DZDS	05	446
6. D2SDZ2	06	447
7. EXPAND	07	447
8. F	08	448
9. PITROL	09	450
10. PLOTVB	10	451
11. SHAPE	11	454
12. VOTEX	12	455
13. VVELS	13	456
14. Z	14	457

PROGRAM VPATHL

```

PROGRAM VPATHL(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,TAPE4,TAPE7) VPL01 1
C VPL01 2
C THIS PROGRAM COMPUTES THE PATHS AND VORTEX INDUCED CROSSFLOW VPL01 3
C VELOCITIES AT SPECIFIED FIELD POINTS FOR A SET OF VORTICES IN THE VPL01 4
C PRESENCE OF A WING-BODY COMBINATION AT ANGLE OF ATTACK AND ROLL. VPL01 5
C SLENDER BODY THEORY IS USED IN THE COMPUTATION OF THE CROSSFLOW VPL01 6
C VELOCITIES. THE BODY IS ASSUMED TO HAVE ELLIPTICAL CROSS SECTION. VPL01 7
C VPL01 8
C VPL01 9
C THE COORDINATE SYSTEM USED HERE IS THE BODY COORDINATE SYSTEM VPL01 10
C WITH THE X-AXIS ALONG THE BODY CENTER-LINE STARTING AT THE NOSE TIP, VPL01 11
C Y-AXIS TO THE RIGHT WHEN LOOKING FORWARD,Z-AXIS UP. VPL01 12
C VPL01 13
C VPL01 14
C *****NOTE: WINGS ONLY - NO VERTICAL SURFACES***** VPL01 15
C VPL01 16
C VPL01 17
C DIMENSION TITLE(20),XN(60),XIP(50),AK(120) VPL01 18
C DIMENSION VXP(30,30,2),NVV(30) VPL01 19
C VPL01 20
C COMMON/VEL/AL,BE, VX(30),VY(30),G(30),NV, NS,NF, VPL01 21
C IXE(7),YF(7),YF(7),C(7,7),IFIN VPL01 22
C COMMON/HLK2/AC,PHI VPL01 23
C COMMON/FINLE/XLE(40),CGLOC(40),GAMLE(40),MSWR,MSWL,MSWD,MSWD, VPL01 24
C I,DEGV,XTIPLE VPL01 25
C COMMON/STEDG/XSE(80),CGSELC(40),GAMSE(80),NCV,NBIDGE,XTIPE VPL01 26
C COMMON/COX8/BFACT VPL01 27
C COMMON XPLT(30,52),YPLT(30,52),ZPLT(30,52),NPLT(52),ROT(4) VPL01 28
C X,XP2(17,16),YP2(17,14) VPL01 29
C COMMON /RSCALE/ XMAX,XMIN,YMAX,YMIN VPL01 30
C COMMON/PARAM/ROUT VPL01 31
C VPL01 32
C NAMELIST/DEFUG/NS,NF,NIP,NCPIN,NVLOUT,ROUT,VRTMAX,XE,C,XF,YF,NVV VPL01 33
C VPL01 34
C 1 FORMAT(20A4) VPL01 35
C 4 FORMAT(4I10) VPL01 36
C 5 FORMAT(7F10.5) VPL01 37
C 6 FORMAT(8F10.5) VPL01 38
C 7 FORMAT(6F10.5) VPL01 39
C 9 FORMAT(/5X,34=LOCAL BODY HORIZONTAL SEMI-AXIS = ,F10.5/5X, VPL01 40
C 1 34=LOCAL BODY VERTICAL SEMI-AXIS = ,F10.5/5X, VPL01 41
C 2 34=LOCAL SEMI SPAN S = ,F10.5/) VPL01 42
C 11 FORMAT (/5X,33H INCLUDED ANGLE OF ATTACK(DEG) = ,F10.5, VPL01 43
C 1 24H HOLL ANGLE(DEG) = ,F10.5/) VPL01 44
C 21 FORMAT(/19H X=STATION NO.,I3,9H X=,F6.3,6X, VPL01 45
C 1 25H INTEGRATION STEP SIZE = ,F10.5//) VPL01 46
C 22 FORMAT(I15,4X,2E17.5,E15.5) VPL01 47
C 25 FORMAT (///10X,36HVORTEX COORDINATES IN CROSS-FLOW PLANE,/) VPL01 48
C 26 FORMAT (///43H INITIAL VORTEX POSITIONS AT X = ,F6.5/) VPL01 49
C 27 FORMAT (10X,7H VORTEX,10X,7H Y,VRTX,10X,7H Z,VRTX,6X, VPL01 50
C 1 10HGAMMA/VIN//) VPL01 51
C 30 FORMAT(16I5) VPL01 52
C 31 FORMAT(/// 6X,76HCROSSFLOW VELOCITIES AT CONTROL POINTS INDUCED BYVPL01 53
C 1 VORTICES AND THEIR IMAGES,/) VPL01 54
C 1 6X,2HC,10X,6HX,BODY,10X,6HY,BODY,10X,6HZ,BODY,10X,1HV,(5X,14H) VPL01 55
C 32 FORMAT(5X,I3,6X,5E15.5) VPL01 56
C 40 FORMAT(3F10.5) VPL01 57
C 700 FORMAT (//5(1*), 59HPERMISSIBLE RELATIVE ERROR,R5,USED IN INTEGRAVPL01 58
C 1TION SCHEME = ,F12.5/) VPL01 59
C 701 FORMAT (///5(1*),61HSUBROUTINE GASCRO CAN NOT OBTAIN VALUE FOR I VPL01 60
C 1TEGRATION STEP H,S(1+1)////) VPL01 61
C 702 FORMAT (A5X,I3,2F10.5) VPL01 62
C 703 FORMAT (//A5X,31HINTERPOLATED VORTEX COORDINATES/H7X,1HI,5X, VPL01 63

```


	RE=PHI*PI*2	VPL01253
	PHI=BE	VPL01254
	AL=ASIN(SIN(AC)*COS(BE))	VPL01255
	RE=ASIN(SIN(AC)*SIN(BE))	VPL01256
C		VPL01257
CCOMPUTE VORTEX PATHS USING DASCRI INTEGRATION SUBROUTINE.....	VPL01258
C		VPL01259
	NIP1=NIP-1	VPL01260
	H=XIP(2)-XIP(1)	VPL01261
	DO 20 I=1,NIP1	VPL01262
	I=I+1	VPL01263
	NV=NVV(I)	VPL01264
	NVN=NVV(I)	VPL01265
	NV1=NV+1	VPL01266
	N=2*NV	VPL01267
	A1=XIP(I)	VPL01268
	R1=XIP(I+1)	VPL01269
C		VPL01270
	CALL DASCRI(A1,B1,H,N,X0,K,IER,ES,VRTMAX)	VPL01271
C		VPL01272
C	IF IER GREATER THAN 32,DASCRI HAD TROUBLE GETTING STEP SIZE,	VPL01273
C	THEN, RATHER THAN CONTINUING WITH THE INTEGRATION, STOP 40	VPL01274
C	REDUCE XIP(2)=XIP(1) AND RERUN	VPL01275
C		VPL01276
	IF (IER,GE,32) GO TO 28	VPL01277
	GO TO 29	VPL01278
	28 WRITE (6,701)	VPL01279
	STOP 40	VPL01280
	29 CONTINUE	VPL01281
C		VPL01282
C		VPL01283
C	.. ADD THE NEW VORTICES AND THEIR POSITIONS FOR THE NEXT X-INTERVAL	VPL01284
		VPL01285
	IF (NVN,EQ,0) GO TO 39	VPL01286
	DO 35 K1=NV1,NVN	VPL01287
	JL=2*K1-1	VPL01288
	KK=JL+1	VPL01289
	X0(JL)=VX(K1)	VPL01290
	35 X0(KK)=VX(K1)	VPL01291
	39 CONTINUE	VPL01292
C		VPL01293
C	.. OUTPUT VORTEX POSITIONS AND CONFIGURATION CHARACTERISTICS AT THIS	VPL01294
C	STATION.	VPL01295
C		VPL01296
	WRITE(6,21)I1,R1,H	VPL01297
	CALL SHAPE (B1,PL0C,BL0C,SL0C,WPL0C)	VPL01298
	WRITE (6,9) RL0C,BL0C,SL0C	VPL01299
C		VPL01300
C	SAVE BODY POINTS FOR PLOT	VPL01301
C		VPL01302
	XPLT(1,I1)=R1	VPL01303
	YPLT(1,I1)=PL0C	VPL01304
	ZPLT(1,I1)=BL0C	VPL01305
	YPLT(2,I1)=SL0C	VPL01306
	WRITE (6,27)	VPL01307
	DO 23 L=1,NVN	VPL01308
	J=2*L-1	VPL01309
	K=J+1	VPL01310
	VXP(I1,L,1)=X0(J)	VPL01311
	VXP(I1,L,2)=X0(K)	VPL01312
	WRITE (6,22)L,X0(J),X0(K),R(L)	VPL01313
C		VPL01314
C	SAVE VORTEX LOCATION FOR PLOT	VPL01315


```

C
      JCV=NIP1+L+1
      XPLT(I,JCV)=B1
      YPLT(I,JCV)=XIP(J)
      ZPLT(I,JCV)=XO(K)
23  CONTINUE
20  CONTINUE
C
C   PLOT VORTEX LOCATIONS
C
      XPLT(1,1)=XIP(1)
      IF (IPLT.GT.0)
      * CALL PLOTVB(XPLT,YPLT,ZPLT,NPLT,NIP1,NVN,30,ROT,XE,YE,WF,XP2,YP2,
      *             IPLT)
C
C.. COMPUTE VELOCITIES AT THE SPECIFIED CONTROL POINTS INDUCED BY NV
C   EXTERNAL VORTICES AND THEIR IMAGES.
C
C   NOTE: IF CONTROL POINTS ARE PASSED THROUGH BY MEANS OF A DATA SET
C   I.E. WHEN NCPIN IS NOT EQUAL TO 0, INDEX NCP IS READ IN FROM
C   THE DATA SET ALSO.
C   NOTE: X-COORDINATE OF CONTROL POINT MUST THEN BE TRANSFORMED TO BODY
C   COORDINATE SYSTEM.
C   THIS IS DONE BELOW.
C
      NCP=0
      IF (NCPIN.NE.0) REWIND 4
      IF (NVLOUT.NE.0) REWIND 7
      IF (NCPIN.EQ.0) GO TO 72
      IF (NCPIN.NE.0) READ (4,745) NCP
      IF (EOF(4).NE.0) GO TO 99
      GO TO 73
72  READ (5,4) NCP
73  CONTINUE
      IF (NCP.EQ.0) GO TO 99
      WRITE(6,31)
      DO 69 J1=1,NCP
      IF (NCPIN.EQ.0) GO TO 70
      READ (4,745) IC,CPX,CPY,CPZ
      CPX=CPX+XF(1)
      GO TO 71
70  READ(5,60)CPX,CPY,CPZ
71  CONTINUE
C
C.. DETERMINE THE X-STATIONS ADJACENT TO THE CONTROL POINT
C
      DO 61 I=1,NJP
      IF (CPX.LT.XIP(I)) GO TO 69
      J=1-1
      IF (I.EQ.1) J=1
      IF (CPX.LE.XIP(I)) GO TO 62
61  CONTINUE
C
C   DETERMINE BY INTERPOLATION THE POSITION IN THE CROSSFLOW PLANE OF ALL
C   VORTICES AT EACH STATION CPX.
C
62  K=J+1
      X1=XIP(J)
      X2=XIP(K)
      WT1=(X2-CPX)/(X2-X1)
      WT2=(CPX-X1)/(X2-X1)

```

```

VPL01316
VPL01317
VPL01318
VPL01319
VPL01320
VPL01321
VPL01322
VPL01323
VPL01324
VPL01325
VPL01326
VPL01327
VPL01328
VPL01329
VPL01330
VPL01331
VPL01332
VPL01333
VPL01334
VPL01335
VPL01336
VPL01337
VPL01338
VPL01339
VPL01340
VPL01341
VPL01342
VPL01343
VPL01344
VPL01345
VPL01346
VPL01347
VPL01348
VPL01349
VPL01350
VPL01351
VPL01352
VPL01353
VPL01354
VPL01355
VPL01356
VPL01357
VPL01358
VPL01359
VPL01360
VPL01361
VPL01362
VPL01363
VPL01364
VPL01365
VPL01366
VPL01367
VPL01368
VPL01369
VPL01370
VPL01371
VPL01372
VPL01373
VPL01374
VPL01375
VPL01376
VPL01377
VPL01378

```

	NV=NVV(J)	VPL01379
	CALL SHAPE (CPX,HB,HL,SL,RPL)	VPL01380
	IF (NDOUT,EG,0) WRITE (A,703)	VPL01381
	GO TO 63	VPL01382
	TX(I)=T1+VXF(J,I,1)+T2+VXP(K,I,1)	VPL01383
	VY(I)=+T1+VXP(J,I,2)+T2+VXP(K,I,2)	VPL01384
	IF (NDOUT,EG,0) GO TO 63	VPL01385
	WRITE (A,702) I,VX(I),VY(I)	VPL01386
63	CONTINUE	VPL01387
	THETP=ATAN2(CPZ,CPY)	VPL01388
	SINTH=STN(THETP)	VPL01389
	COSTH=COS(THETP)	VPL01390
	RCPT=SQRT(CPY*CPY+CPZ*CPZ)	VPL01391
	RBODY=SQRT(1.0/((SINTH/RL)**2+(COSTH/RB)**2))	VPL01392
	IF (RCPT,LE,RBODY) GO TO 64	VPL01393
	GO TO 65	VPL01394
64	RBODYP=1.01*RBODY	VPL01395
	CPY=RBODYP*COSTH	VPL01396
	CPZ=RBODYP*SINTH	VPL01397
65	CONTINUE	VPL01398
		VPL01399
		VPL01400
	SUBROUTINE VVELS CALCULATES VELOCITIES INDUCED BY EXTERNAL	VPL01401
	VORTICES AROUND ELLIPTICAL CROSS SECTION BODY BY SETTING S=RB IN	VPL01402
	THE ARGUMENT LIST.	VPL01403
		VPL01404
	CALL VVELS(NV,CPY,CPZ,VX,VY,G,HB,SL,RB,V,W,VNTHMAX)	VPL01405
	WRITE(A,32) J11,CPX,CPY,CPZ,V,A	VPL01406
	IF (NVLOUT,EG,0) GO TO 69	VPL01407
	IC=J11	VPL01408
	WRITE (7,746) IC,CPX,CPY,CPZ,V,A	VPL01409
69	CONTINUE	VPL01410
	GO TO 99	VPL01411
2	STOP	VPL01412
	END	VPL01413

	SUBROUTINE DASCRO (A,B,M,N,X0,K,IER,ES,VNTHMAX)	VPL02 1
		VPL02 2
	THIS SUBROUTINE PERFORMS INTEGRATION	VPL02 3
		VPL02 4
	ES SHOULD BE SET TO .5 TIMES THE	VPL02 5
	DESIRED RELATIVE PRECISION OF	VPL02 6
	THE SOLUTION	VPL02 7
		VPL02 8
	DIMENSION WK(1),X0(1)	VPL02 9
		VPL02 10
	INTEGER SW	VPL02 11
		VPL02 12
	LOGICAL HE,HH,RR,HX	VPL02 13
		VPL02 14
	DATA ZERO,PS,CPS,THREE,FOUR,0.,.5,1.5,3.,4.	VPL02 15
		VPL02 16
	TEP = 0	VPL02 17
	IF (A = B) A=100.4	VPL02 18
4	I41=N+4	VPL02 19
	I42=I41+4	VPL02 20
	NMIN=0.01+4HS(M)	VPL02 21

HR=,TRUE.
HR=,TRUE.
HX=,TRUE.

VPL02 22
VPL02 23
VPL02 24

C
C
C

CHECK FOR THE PROPER SIGN OF H

VPL02 25
VPL02 26
VPL02 27

H=SIGN(ARS(H),R-A)

VPL02 28

X=A

VPL02 29

5 XS=X

VPL02 30

DO 10 J=1,N

VPL02 31

IJK0=N+J

VPL02 32

HK(IJK0)=X(J)

VPL02 33

10 CONTINUE

VPL02 34

15 HS=H

VPL02 35

Q=X+H-R

VPL02 36

HR=,TRUE.

VPL02 37

IF(,NOT,(H.GT,ZERO,AND,Q.GE,ZERO),OR,(H.LT,ZERO,AND,Q.LE,ZERO))

VPL02 38

1 GO TO 20

VPL02 39

H=R-X

VPL02 40

HR=,FALSE.

VPL02 41

20 HS=H/THREE

VPL02 42

C
C
C
C

CALCULATE SOLN. AT X+H

VPL02 43

NOTE: ARRAY HK CONTAINS V FOR ODD INDEX, W FOR EVEN INDEX.

VPL02 44

VPL02 45

VPL02 46

VPL02 47

VPL02 48

DO 90 S=1,5

VPL02 49

CALL F(X0,X,N,HK,VPTMAX)

VPL02 50

DO 70 I=1,N

VPL02 51

Q=H3+HK(I)

VPL02 52

IJK0=N+I

VPL02 53

IJK1=I*2+I

VPL02 54

IJK2=I*2+I

VPL02 55

GO TO (25,30,35,40,45),S

VPL02 56

25

R=Q

VPL02 57

HK(IJK1)=Q

VPL02 58

GO TO 50

VPL02 59

30

Q=Q5*(Q+HK(IJK1))

VPL02 60

GO TO 50

VPL02 61

45

R=THREE*Q

VPL02 62

HK(IJK2)=R

VPL02 63

R=.375*(R+HK(IJK1))

VPL02 64

GO TO 50

VPL02 65

40

R=HK(IJK1)+FOUR*Q

VPL02 66

HK(IJK1)=R

VPL02 67

H=NP5*(R+HK(IJK2))

VPL02 68

GO TO 50

VPL02 69

45

R=Q5*(Q+HK(IJK1))

VPL02 70

Q=ARS(R+R - NP5*(Q+HK(IJK2)))

VPL02 71

50

X(I)=HK(IJK0)+R

VPL02 72

IF(S=,4E,5) GO TO 70

VPL02 73

C
C
C

AUTOMATIC STEP CHANGE

VPL02 74

VPL02 75

VPL02 76

VPL02 77

VPL02 78

VPL02 79

E=ARS(X(I))

VPL02 80

R=E5

VPL02 81

IF(E,GE,1,E=3) Q=E*E5

VPL02 82

C
C
C

TEST ADJUSTMENT OF THE STEP

VPL02 83

VPL02 84

IF(Q,LT,0,OR,(,NOT, HX)) GO TO 65

VPL02 85

HR=,TRUE.

VPL02 86

H=,FALSE.

VPL02 87

```

      H=PS*M
      IF(AHS(H),GE,MMIN) GO TO 55
C
C
C
C
      THE STEP IS HALVED RESTORE X AND X0,
      AND GO BACK FOR REPEATED INTEGRATION
      WITH THIS NEW STEP
C
      H=SIGN(1,H)*MMIN
      HX=FALSE
55      DO 60 I=1,N
          IJX=I+J
          X0(I)=X(IJX)
60      CONTINUE
          X=X/2
          GO TO 15
65      IF(Q,GE,0.03125*R) HX=FALSE
70      CONTINUE
          GO TO (75,90,80,85,90),HX
75      X=X+H3
          GO TO 90
80      X=X+P5*H3
          GO TO 90
85      X=X+P5*H
90      CONTINUE
C
C
C
      TEST A POSSIBLE DOUBLING OF THE STEP
C
      IF(.NOT.(HE.AND,BH.AND,HR)) GO TO 95
      H=H*H
      HX=TRUE
95      H=H*H
          IF(HR) GO TO 5
          H=H/2
          IF(HX .OR. HE) GO TO 9005
          IPR = 33
          GO TO 9005
100      DO 105 I=1,N
          X0(I)=ZERO
105      CONTINUE
9005      RETURN
      END
VPL02 85
VPL02 86
VPL02 87
VPL02 88
VPL02 89
VPL02 90
VPL02 91
VPL02 92
VPL02 93
VPL02 94
VPL02 95
VPL02 97
VPL02 98
VPL02 99
VPL02100
VPL02101
VPL02102
VPL02103
VPL02104
VPL02105
VPL02106
VPL02107
VPL02108
VPL02109
VPL02110
VPL02111
VPL02112
VPL02113
VPL02114
VPL02115
VPL02116
VPL02117
VPL02118
VPL02119
VPL02120
VPL02121
VPL02122
VPL02123
VPL02124
VPL02125

```

```

      COMPLEX FUNCTION DBLU(Z)
C
C
C
C
      THIS FUNCTION SUBROUTINE CALCULATES THE INTERMEDIATE TRANSFORM
      VARIABLE W FOR THE CONFORMAL TRANSFORMATION OF AN ELLIPTICAL
      BODY WITH WINGS TO A CIRCLE.
C
      COMMON/COM1/A2,B2,R2
      COMMON/COM3/ZR,ZI
      COMMON/COM5/U=0
      COMMON/COM6/*2,*
      COMMON/PARAM/NOIT
C
      COMPLEX Z,Z2,D=0Z,*2,*
C
700      FORMAT (/19X,2H Z2,22X,4HD D Z/14X,2H RE,9X,2H IM,11X,2H RE,9X,2H IM)
701      FORMAT (10X,F10.5,1X,F10.5,2X,F10.5,1X,F10.5)
C
VPL03 1
VPL03 2
VPL03 3
VPL03 4
VPL03 5
VPL03 6
VPL03 7
VPL03 8
VPL03 9
VPL03 10
VPL03 11
VPL03 12
VPL03 13
VPL03 14
VPL03 15
VPL03 16
VPL03 17

```

C

```

IF (NOUT.EQ.2) WRITE (6,700)
Z2=Z+Z
ZR=REAL(Z)
ZI=AIMAG(Z)
IF (ZR.NE.0.0) ZR=ZR/ABS(ZR)
IF (ZI.NE.0.0) ZI=ZI/ABS(ZI)
Z2=ZR+I*ZI
IF (NOUT.EQ.2) WRITE (6,701) Z2
Y=AIMAG(Z2)
AY=1.0
IF (Y.LT.0.0) AY=-1.0
AYZ=1.0
IF (ZI.LT.0.0) AYZ=-1.0
Z2=CSQRT(Z2)*AY*AYZ
IF (NOUT.EQ.2) WRITE (6,701) Z2
IF ((ABS(ZI).LE.0.0).AND.(REAL(Z).LT.0.0)) Z2=CMPLX(-REAL(Z2),
1 AIMAG(Z2))
DWDZ=0.5*(1.0+Z/Z2)
IF (NOUT.EQ.2) WRITE (6,701) Z2,DWDZ
W=0.5*(Z+Z2)
*Z=1.0/(W+W)
DCLU=W
RETURN
END

```

VPL03 18
VPL03 19
VPL03 20
VPL03 21
VPL03 22
VPL03 23
VPL03 24
VPL03 25
VPL03 26
VPL03 27
VPL03 28
VPL03 29
VPL03 30
VPL03 31
VPL03 32
VPL03 33
VPL03 34
VPL03 35
VPL03 36
VPL03 37
VPL03 38
VPL03 39
VPL03 40
VPL03 41
VPL03 42

C
C
C

```

COMPLEX FUNCTION DSQZ(S)
CALCULATE DZETA/DTAU
COMMON/COM2/SIG2,H2
COMMON/COM5/DWDZ
COMMON/COM4/G2,G1
COMMON/COM6/*2,*
COMPLEX *2,DWDZ,G1,G2
DSQZ=0.5*(1.0-SIG2*2)*(1.0+G1/G2)*DWDZ
RETURN
END

```

VPL04 1
VPL04 2
VPL04 3
VPL04 4
VPL04 5
VPL04 6
VPL04 7
VPL04 8
VPL04 9
VPL04 10
VPL04 11
VPL04 12

C
C
C

```

COMPLEX FUNCTION DZOS(S)
CALCULATE DZ/DZETA
COMMON/COM1/A2,H2,H2
COMMON/COM2/SIG2,H2
COMMON/COM6/*2,*
COMPLEX *2,S,*2,G1,S2,7,Z2
S2=S*S
G1=0.5*(1.0+0.25*(A2+H2)*2)*(1.0+R2/S2)
Z=S+R2/S
Z2=Z+Z-4.0*SIG2
Y=AIMAG(Z)
YZ=AIMAG(Z2)
AY=1.0
AYZ=1.0

```

VPL05 1
VPL05 2
VPL05 3
VPL05 4
VPL05 5
VPL05 6
VPL05 7
VPL05 8
VPL05 9
VPL05 10
VPL05 11
VPL05 12
VPL05 13
VPL05 14
VPL05 15
VPL05 16

```

IF(Y.LT.0.0) AY=-1.0
IF(YZ.LT.0.0) AYZ=-1.0
Z2=CSQRT(Z2)*AY*AYZ
IF((ABS(Y).LE.0.0).AND.(REAL(Z).LT.0.0)) ZP=CMPLX(-REAL(Z2),
1     AIMAG(Z2))
DZDS=G1*(1.0+Z/Z2)
RETURN
END
VPL05 17
VPL05 18
VPL05 19
VPL05 20
VPL05 21
VPL05 22
VPL05 23
VPL05 24

```

```

C
C
C
COMPLEX FUNCTION D2SDZ2(S)
CALCULATE DZETA2/DZ2
COMMON/COM2/SIG2,H2
COMMON/COM4/G2,G1
COMMON/COM6/A2,+
COMMON/COM5/D*HZ
COMPLEX X,H2,D*HZ,G2,G1
D2SDZ2=(1.0+G1/G2)*SIG2*A2/+
D2SDZ2=D2SDZ2-0.5*(1.0-SIG2*H2)*(1.0-SIG2*H2)+H2/(G2*(G1+G1-H2))
D2SDZ2=D2SDZ2*D*HZ/D*HZ
RETURN
END
VPL06 1
VPL06 2
VPL06 3
VPL06 4
VPL06 5
VPL06 6
VPL06 7
VPL06 8
VPL06 9
VPL06 10
VPL06 11
VPL06 12
VPL06 13
VPL06 14

```

```

C
C
C
SUBROUTINE EXPAND(RP,Y,Y,VS,*S)
THIS SUBROUTINE CALCULATES VELOCITIES INDUCED BY EXPANDING OR
CONTRACTING ELLIPTICAL CROSS SECTION.
COMMON/COM1/A2,H2,H2
COMMON/BLK1/A,R,S,PI,CI
COMMON/COM8/H*EACT
COMPLEX VE,Z,ZI,CI
SP=H*EACT*A*RP
Z=CMPLX(X,Y)
ZI=Z*Z
AY=1.0
IF(AIMAG(Z).LT.0.0) AY=-1.0
AYZ=1.0
IF(AIMAG(ZI).LT.0.0) AYZ=-1.0
Z=CSQRT(ZI-A2+H2)*AY*AYZ
IF((ABS(AIMAG(Z)).LE.0.0).AND.(REAL(Z).LT.0.0))
1     Z=CMPLX(-REAL(Z),AIMAG(Z))
VE=SP/Z
VS=REAL(VE)
-S=AIMAG(VE)
RETURN
END
VPL07 1
VPL07 2
VPL07 3
VPL07 4
VPL07 5
VPL07 6
VPL07 7
VPL07 8
VPL07 9
VPL07 10
VPL07 11
VPL07 12
VPL07 13
VPL07 14
VPL07 15
VPL07 16
VPL07 17
VPL07 18
VPL07 19
VPL07 20
VPL07 21
VPL07 22
VPL07 23
VPL07 24

```

```

SUBROUTINE F(XO,PX,H,AK,VRTMAX)
C
C THIS SUBROUTINE IS CALLED BY DASCRO TO CALCULATE CROSS FLOW
C PLANE VELOCITIES
C
C COMPLEX CI,Z,FACT,SIMP
COMMON/VEL/AL,RE,
      VX(30),VY(30),G(30),NV,
      NS,NF,
      IXE(7),XF(7),YF(7),C(7,7),IFIN
COMMON/HLK1/A,R,S,PI,CI
COMMON/HLK2/AC,PHI
COMMON/FINLE/YLF(80),CGLUC(80),GAMLE(80),MSHR,MSVL,MSWU,MSWD,
      I AEOGV,XTIPLE
COMMON/SIDEGG/XSE(80),CGSELC(80),GAMSE(80),HCV,NSIGGE,XTIPE
COMMON/CM1/A2,H2,R2
COMMON/CM2/SIG2,H2
COMMON/CM7/B
COMMON/CM9/IGROW
COMMON/PARAM/NDUT
C
C DIMENSION X0(1),WK(1),V(30),W(30),VV(30),WW(30)
C
C EXTERNAL Z,FACT,SIMP
C
C NANELIST/DEBUG/X,Y,YVINT,ZVBAR,GAMINT,A,H,VRTMAX,VS,NS
C
C CI=CMPLX(0.,1.)
C PI=3.14159265
C DO 888 I=1,NV
C J=2*I-1
C K=J+1
C VX(I)=X0(J)
C 888 VY(I)=X0(K)
C CALL SHAPE(PX,A,B,S,RP)
C
C NOTE: COORDINATE VX(I) IS THE Y-COORDINATE IN THE CROSS FLOW PLANE.
C COORDINATE VY(I) IS THE Z-COORDINATE IN THE CROSS FLOW PLANE.
C
C COMPUTE VELOCITIES IN THE CROSSFLOW PLANE ...
C V(I) IS IN THE Y-DIRECTION.
C W(I) IS IN THE Z-DIRECTION.
C
C
C A2=A*A
C H2=H*H
C APB=A+B
C APH2=APB*APB
C R1=S+SQRT(S*S+A2+H2)
C W=0.25*(R1+APH2/R1)
C H=H+R
C H2=H*H
C SIG=0.5*APB
C SIG2=SIG*SIG
C R2=R*R
C DO 100 I=1,NV
C X=VX(I)
C Y=VY(I)
C VS=0.
C WS=0.
C
C COMPUTE VELOCITIES IN CROSS FLOW PLANE DUE TO ANGLE OF PITCH AND
C ANGLE OF SIDESLIP.
C

```

```

VPL08 1
VPL08 2
VPL08 3
VPL08 4
VPL08 5
VPL08 6
VPL08 7
VPL08 8
VPL08 9
VPL08 10
VPL08 11
VPL08 12
VPL08 13
VPL08 14
VPL08 15
VPL08 16
VPL08 17
VPL08 18
VPL08 19
VPL08 20
VPL08 21
VPL08 22
VPL08 23
VPL08 24
VPL08 25
VPL08 26
VPL08 27
VPL08 28
VPL08 29
VPL08 30
VPL08 31
VPL08 32
VPL08 33
VPL08 34
VPL08 35
VPL08 36
VPL08 37
VPL08 38
VPL08 39
VPL08 40
VPL08 41
VPL08 42
VPL08 43
VPL08 44
VPL08 45
VPL08 46
VPL08 47
VPL08 48
VPL08 49
VPL08 50
VPL08 51
VPL08 52
VPL08 53
VPL08 54
VPL08 55
VPL08 56
VPL08 57
VPL08 58
VPL08 59
VPL08 60
VPL08 61
VPL08 62
VPL08 63

```

```

      IF (NDOUT.EQ.3) WRITE (6,DEBHG)
      IF ((AL.NE.0.0).OR.(HE.NE.0.0)) CALL PITMOL(AL,HE,X,Y,VS,NS)
      IF (NDOUT.EQ.3) WRITE (6,DEBHG)
      V(I)=VS
      W(I)=WS
C
C   COMPUTE VELOCITIES IN CROSSFLOW PLANE DUE TO EXPANDING BODY
C
      VS=0.0
      WS=0.0
      IF (IGROW.GT.0) CALL EXPAND(RP,X,Y,VS,WS)
      IF (NDOUT.EQ.3) WRITE (6,DEBHG)
      V(I)=V(I)+VS
      W(I)=W(I)+WS
C
C   IF WING LE VORTICITY IS INCLUDED, DETERMINE BY INTERPOLATION THE
C   EFFECTS OF THE SPECIFIED VORTICITY.
C
C   NOTE: HERE IFIN=1....RIGHT WING
C         2....LEFT WING
C
      IF (NEDGV.EQ.0) GO TO 20
      IFIN=1
      KSTART=1
      KUL=MSWR
      23 CONTINUE
      IF (IFIN.EQ.2) KSTART=MSWR+1
      DO 21 IFV=KSTART,KUL
      IF (PX,LT,XLE(KSTART)) GO TO 20
      JV=IFV-1
      IF (IFV.EQ.1) JV=1
      IF (PX,LE,XLE(IFV)) GO TO 22
      24 CONTINUE
      IF (PX,LE,XTIPLF) GO TO 38
      GO TO 20
      22 KV=JV+1
      X1=XLE(JV)
      X2=XLE(KV)
      T1=(X2-PX)/(X2-X1)
      T2=(PX-X1)/(X2-X1)
      YVINT=T1*CGLOC(JV)+T2*CGLOC(KV)
      ZVBAR=(PX-XF(1))*TAN(AL/2.0)
      GAMINT=T1*GAMLE (JV)+T2*GAMLE (KV)
      IF (NDOUT.EQ.3) WRITE (6,DEBHG)
      GO TO 39
      38 GAMINT=GAMLE(KUL)
      YVINT=CGLOC(KUL)
      ZVBAR=(PX-XF(1))*TAN(AL/2.0)
      IF (NDOUT.EQ.3) WRITE (6,DEBHG)
      39 CALL VVEL3(1,X,Y,YVINT,ZVBAR,GAMINT,A,B,S,VS,WS,VRT,AX)
      IF (NDOUT.EQ.3) WRITE (6,DEBHG)
      V(I)=V(I)+VS
      W(I)=W(I)+WS
      IFIN=IFIN+1
      IF (IFIN.GT.2) GO TO 20
      KUL=MSR+MSAL
      GO TO 23
      20 CONTINUE
C
C
C   IF WING SE VORTICITY IS INCLUDED, DETERMINE BY INTERPOLATION THE
C   EFFECTS OF THE SPECIFIED VORTICITY.
C

```

```

VPL08 64
VPL08 65
VPL08 66
VPL08 67
VPL08 68
VPL08 69
VPL08 70
VPL08 71
VPL08 72
VPL08 73
VPL08 74
VPL08 75
VPL08 76
VPL08 77
VPL08 78
VPL08 79
VPL08 80
VPL08 81
VPL08 82
VPL08 83
VPL08 84
VPL08 85
VPL08 86
VPL08 87
VPL08 88
VPL08 89
VPL08 90
VPL08 91
VPL08 92
VPL08 93
VPL08 94
VPL08 95
VPL08 96
VPL08 97
VPL08 98
VPL08 99
VPL08100
VPL08101
VPL08102
VPL08103
VPL08104
VPL08105
VPL08106
VPL08107
VPL08108
VPL08109
VPL08110
VPL08111
VPL08112
VPL08113
VPL08114
VPL08115
VPL08116
VPL08117
VPL08118
VPL08119
VPL08120
VPL08121
VPL08122
VPL08123
VPL08124
VPL08125
VPL08126

```



```

IF (NSIDG, EQ, 0) GO TO 28
IFIN=1
KSTART=1
KUL=NCW
27 CONTINUE
IF (IFIN, EQ, 2) KSTART=NCW+1
DO 29 JSE=KSTART, KUL
IF (PX, LT, XSE(KSTART)) GO TO 28
JVSE=JSE-1
IF (JSE, EQ, 1) JVSE=1
IF (PX, LE, XSE(JSE)) GO TO 30
29 CONTINUE
IF (PX, LE, XTIPTE) GO TO 51
GO TO 28
30 KVSE=JVSE+1
X1=XSE(JVSE)
X2=XSE(KVSE)
WT1=(X2-PX)/(X2-X1)
WT2=(PX-X1)/(X2-X1)
YVINT=WT1*CGSELC(JVSE)+WT2*CGSELC(KVSE)
ZVBAR=(PX-XF(1))*TAN(AL/2, 0)
GAMINT=WT1*GAMRE(JVSE)+WT2*GAMRE(KVSE)
IF (NOUT, EQ, 5) WRITE (6, DEBUG)
GO TO 59
51 GAMINT=GAMSE(KUL)
YVINT=CGSELC(KUL)
ZVBAR=(PX-XF(1))*TAN(AL/2, 0)
IF (NOUT, EQ, 3) WRITE (6, DEBUG)
59 CALL VVELS(I, X, Y, YVINT, ZVBAR, GAMINT, A, B, S, VS, S, VRTMAX)
IF (NOUT, EQ, 5) WRITE (6, DEBUG)
V(I)=V(I)+VS
W(I)=W(I)+S
IFIN=IFIN+1
IF (IFIN, GT, 2) GO TO 28
KUL=2+KUL
GO TO 27
28 CONTINUE
100 CONTINUE
C
C CALCULATE VELOCITIES INDUCED BY ALL VORTICES ON ONE VORTEX IN THE
C PRESENCE OF AN ELLIPTICAL BODY-MONOPLANE WING.
C
C CALL VORTEX(MV, VX, VY, G, VV, WW)
CAL=CCOS(AC)
DO 101 I=1, MV
V(I)=V(I)+VV(I)
W(I)=W(I)+WW(I)
J=2+I-1
K=J+1
WK(J)=V(I)/CAL
WK(K)=W(I)/CAL
101 CONTINUE
RETURN
END

```

VPL08127
VPL08128
VPL08129
VPL08130
VPL08131
VPL08132
VPL08133
VPL08134
VPL08135
VPL08136
VPL08137
VPL08138
VPL08139
VPL08140
VPL08141
VPL08142
VPL08143
VPL08144
VPL08145
VPL08146
VPL08147
VPL08148
VPL08149
VPL08150
VPL08151
VPL08152
VPL08153
VPL08154
VPL08155
VPL08156
VPL08157
VPL08158
VPL08159
VPL08160
VPL08161
VPL08162
VPL08163
VPL08164
VPL08165
VPL08166
VPL08167
VPL08168
VPL08169
VPL08170
VPL08171
VPL08172
VPL08173
VPL08174
VPL08175
VPL08176
VPL08177
VPL08178
VPL08179
VPL08180

```

SUBROUTINE PITPOL(AL, RE, X, Y, VS, *S)
C
C THIS SUBROUTINE COMPUTES THE CROSSFLOW COMPONENTS FOR A WINGED
C ELLIPTICAL BODY AT ANGLE OF ATTACK, AL, AND SIDESLIP ANGLE, BE.
C
C COMMON/BI X1/A, R, S, PI, CI

```

VPL09 1
VPL09 2
VPL09 3
VPL09 4
VPL09 5
VPL09 6

```

COMPLEX SZ,CI,ZA,SO,SQS,VFLAL,Z,OSDZ          VPL09 7
EXTERNAL Z,OSDZ                                VPL09 8
RR=RR/R                                         VPL09 9
ZA=CMPLX(X(X,Y))                              VPL09 10
SZ=Z(ZA)                                       VPL09 11
SO=SZ+SZ                                       VPL09 12
SQS=OSDZ(ZA)                                  VPL09 13
VFLAL=CMPLX(0,0,0)                            VPL09 14
IF(AL.NE.0,0) VFLAL=-CI*SIGN(AL)*(1,0+RR/SQ) + SQS + VFLAL VPL09 15
IF(HE.NE.0,0) VFLAL=VFLAL-SIGN(HE)*(1,0-RR/SQ) + SQS VPL09 16
VS=REAL(VFLAL)                                 VPL09 17
-SE=AIMAG(VFLAL)                              VPL09 18
RETURN                                         VPL09 19
END                                             VPL09 20

```

```

SUBROUTINE PLOTVB(X,Y,Z,NP,NIP1,NVN,NOP,ROT,XP,YE,NF,X2,Y2,IPRT) VPL10 1
C ROUTINE TO GENERATE A PLOT VERTEX LOCATION RELATIVE TO THE VPL10 2
C THE WING-BODY CONFIGURATION VPL10 3
C DEFINITIONS: VPL10 4
C NC = INDEX OF CURVE VPL10 5
C NIP1 = NO. OF BODY STATIONS VPL10 6
C NVN = NO. OF VERTICES VPL10 7
C NF = NO. OF WING DEFINITION CARDS VPL10 8
C DIMENSION X(NOP,52),Y(NOP,52),Z(NOP,52) VPL10 9
C DIMENSION NP(52),ROT(3),XCG(5),XF(7),YF(7) VPL10 10
C DIMENSION X2(17,18),Y2(17,18),HP2(18),SYMBOL(40) VPL10 11
C DATA SYMBOL / 1H+,1H-,1H=,1H.,1H0,1H1,1H2,1H3,1H4,1H5,1H6, VPL10 12
C * 1H7,1H8,1H9,1HA,1HB,1HC,1HD,1HE,1HF,1HG,1HH,1HI,1HJ,1HK,1HL, VPL10 13
C * 1HM,1HN,1HO,1HP,1HQ,1HR,1HS,1HT,1HU,1HV,1HW,1HX,1HY,1HZ/ VPL10 14
C LENG AND LWD: GIVE A PLOT THAT IS 9"X10" VPL10 15
C DATA LWD,LENG,XCG/ 100,54, 0.,0.,0./ VPL10 16
C IF (IPRT.LE.0) IPRT=3 VPL10 17
C !NG WRITTEN HERE IS TO SUPPRESS THE AUTOMATIC PAGE EJECT VPL10 18
C WRITE(6,10) VPL10 19
C WRITE(6,11) VPL10 20
10 FORMAT(1H1) VPL10 21
11 FORMAT(1H0) VPL10 22
C FIND MAXIMUM DIAMETER VPL10 23
C RMAX=0. VPL10 24
C DO 100 I=1,NIP1 VPL10 25
100 RMAX=AMAX1(RMAX,Y(I,I+1),Z(I,I+1)) VPL10 26
C CURVE 1: DRAW AXES VPL10 27
C NC=1 VPL10 28
C DO 120 I=1,5 VPL10 29
120 X(I,1)=X(1,I) VPL10 30
Y(I,1)=0. VPL10 31
Z(I,1)=0. VPL10 32
X(2,1)=X(1,NIP1+1) VPL10 33
Y(4,1)=1.5*RMAX VPL10 34
Z(6,1)=1.5*RMAX VPL10 35
NP(1)=6 VPL10 36
C CURVES: 2 TO NIP1+1 VPL10 37
C GENERATE CROSS SECTIONS VPL10 38

```

```

C
NGV=NIP1+NVN+5
MERID=17
DO 160 J=1,NIP1
NC=NC+1
R1 =X(1,NC)
RLC=Y(1,NC)
RLC=Z(1,NC)
SLOC=Y(2,NC)
C SAVE RLOC AND BLOC
Y(J,NGV)=RLC
Z(J,NGV+1)=RLC
Y(J,NGV+2)=SLOC
C
C GENERATE ELLIPTIC BODY CROSS SECTION
C
RTH=2.431415926/(MERID=1)
DO 140 I=1,MERID
PHI=(I-1)*RTH
RAD=(COS(PHI)/RLC)**2+(SIN(PHI)/RLC)**2
RAD=SQRT(1./RAD)
Y(I,NC)=RAD*SIN(PHI)
Z(I,NC)=RAD*COS(PHI)
X(I,NC)=R1
140 CONTINUE
160 MP(NC)=MERID
C
C PLOT VORTEX LOCATION (ALREADY DEFINED)
DO 170 I=1,NVN
NC=NC+1
170 MP(NC)=NIP1
C
C DRAWING OUTLINE
C
IF (NF,LF,0) GO TO 200
DO 190 J=1,2
NC=NC+1
SGN=(-1)**(J+1)
DO 180 I=1,NF
X(I,NC)=XF(I)
Y(I,NC)=YF(I)*SGN
Z(I,NC)=0.0
180 CONTINUE
NF=NF+1
X(NF1,NC)=XF(1)
Y(NF1,NC)=YF(1)*SGN
Z(NF1,NC)=0.0
MP(NC)=NF1
190 CONTINUE
200 CONTINUE
C
C PLOT CROSS SECTIONS WITH VORTEX LOCATIONS
C
DO 240 ISECTN=1,5
IF (ISECTN,EQ,1) JSECTN=1
IF (ISECTN,EQ,2) JSECTN=NIP1/2
IF (ISECTN,EQ,3) JSECTN=NIP1
C
C COPY BODY
DO 220 I=1,MERID
X2(I,1)=Y(I,JSECTN+1)

```

```

VPL10 47
VPL10 48
VPL10 49
VPL10 50
VPL10 51
VPL10 52
VPL10 53
VPL10 54
VPL10 55
VPL10 56
VPL10 57
VPL10 58
VPL10 59
VPL10 60
VPL10 61
VPL10 62
VPL10 63
VPL10 64
VPL10 65
VPL10 66
VPL10 67
VPL10 68
VPL10 69
VPL10 70
VPL10 71
VPL10 72
VPL10 73
VPL10 74
VPL10 75
VPL10 76
VPL10 77
VPL10 78
VPL10 79
VPL10 80
VPL10 81
VPL10 82
VPL10 83
VPL10 84
VPL10 85
VPL10 86
VPL10 87
VPL10 88
VPL10 89
VPL10 90
VPL10 91
VPL10 92
VPL10 93
VPL10 94
VPL10 95
VPL10 96
VPL10 97
VPL10 98
VPL10 99
VPL10100
VPL10101
VPL10102
VPL10103
VPL10104
VPL10105
VPL10106
VPL10107
VPL10108
VPL10109

```

Y2(1,1)=Z(1,JSECTN+1)	VPL10110
220 CONTINUE	VPL10111
NP2(1)=NERID	VPL10112
NC2=1	VPL10113
C	VPL10114
C MARKING OUTER BOUNDARIES	VPL10115
C	VPL10116
SLOC=Y(JSECTN,NGV+2)	VPL10117
X2(1,2)=SLOC	VPL10118
Y2(1,2)=0.	VPL10119
X2(2,2)=-SLOC	VPL10120
Y2(2,2)=0.	VPL10121
NP2(2)=P	VPL10122
NC2=NC2+1	VPL10123
C	VPL10124
C COPY VORTICES AT JSECTN	VPL10125
C	VPL10126
DO 230 J=1,NVN	VPL10127
NC2=NC2+1	VPL10128
JCV=NIPI+1+J	VPL10129
Y2(1,NC2)=Y(JSECTN,JCV)	VPL10130
Z2(1,NC2)=Z(JSECTN,JCV)	VPL10131
NP2(NC2)=1	VPL10132
230 CONTINUE	VPL10133
C	VPL10134
C PLOT CROSS SECTIONS	VPL10135
C	VPL10136
CALL PLOTAP(X2,Y2,3,NP2,17,NC2,LWID,LENG)	VPL10137
WRITE(6,23) JSECTN,Y(1,JSECTN+1)	VPL10138
WRITE(6,24) (I,SYMBOL(I+2),I=1,NVN)	VPL10139
240 CONTINUE	VPL10140
C	VPL10141
C PLOT PERSPECTIVE VIEWS -----	VPL10142
LENG = .50	VPL10143
TOPT = 3	VPL10144
C	VPL10145
C SIDE VIEW	VPL10146
CALL PLOT2(X,Z,3,NP,NDP,NC,LWID,LENG)	VPL10147
CALL PLOTV2(X,Z,3,NP,NDP,NC,LWID,LENG,LINE,PLTY)	VPL10148
WRITE(6,21)	VPL10149
NSYM=NVN	VPL10150
JNSYM=1+NIPI	VPL10151
JN = JNSYM+NVN	VPL10152
IF (JN.GT.40) NSYM=JN-40	VPL10153
WRITE(6,24) (I,SYMBOL(I+JNSYM),I=1,NSYM)	VPL10154
IF (JN.LE.40) GO TO 210	VPL10155
JNSYM=NSYM+1	VPL10156
NSYM = NSYM	VPL10157
WRITE(6,24) (I,SYMBOL(I+JNSYM),I=JNSYM,NVN)	VPL10158
210 CONTINUE	VPL10159
TOPT = 1	VPL10160
C	VPL10161
C TOP VIEW	VPL10162
CALL PLOT2(X,Y,3,NP,NDP,NC,LWID,LENG)	VPL10163
CALL PLOTV2(X,Y,3,NP,NDP,NC,LWID,LENG,LINE,PLTY)	VPL10164
WRITE(6,20)	VPL10165
C	VPL10166
C PERSPECTIVE VIEW	VPL10167
TOPT = 3	VPL10168
ROT(1)=0.	VPL10169
ROT(2)=30.	VPL10170
ROT(3)=20.	VPL10171

```

CALL PLOTAS(X,Y,Z,WP,NDP,NC,ROT,XCG,X,Y,3)
CALL PLOTAS2(X,Y,3,WP,NDP,NC,L=10,LENG)
C CALL PLOTVP(X,Y,3,WP,NDP,NC,L=10,LENG,LINE,CLIN)
WRITE(6,22) ROT
C
C
20 FORMAT(/20X,22HTOP VIEW = Y VERSUS X)
21 FORMAT(/20X,22H SIDE VIEW = Z VERSUS X)
22 FORMAT(/20X,18HPERSPECTIVE = ROT=,3F10.2)
23 FORMAT(/20X,29HBODY CROSS SECTION = JSECTION=,I3,
* 5X,4HYIP=,F10.3)
24 FORMAT(20X,14HVERTICAL SYMBOLS,10(1X,I2,1H=,A1,1H,))
C
C
RETURN
END

```

```

VPL10172
VPL10173
VPL10174
VPL10175
VPL10176
VPL10177
VPL10178
VPL10179
VPL10180
VPL10181
VPL10182
VPL10183
VPL10184
VPL10185
VPL10186
VPL10187

```

```

SUBROUTINE SHAPE(X,R,R,S,RP)
C
C THIS SUBROUTINE COMPUTES HORIZONTAL SEMI-MAJOR AXIS AND VERTICAL
C SEMI-MAJOR AXIS AND WING SPAN MEASURED FROM THE BODY CENTERLINE.
C
C IF ELLIPTICAL CROSS SECTION, R IS VERTICAL SEMI-AXIS
C R IS HORIZONTAL SEMI-AXIS.
C
COMMON/VEL/AL,RE, VX(30),VY(30),G(30),VV, NS,NF,
1XF(7),XF(7),YF(7),C(7,7),IFIN
COMMON/CONB/HFACT
COMMON/CONV/IGROW
IGROW=0
IFIN=0
DO 1 K=1,NS
XL=XF(K)
JK
IF(X,LE,XL)GO TO 2
1 CONTINUE
2 R=C(J,1)+X*C(J,5)+Y*X*C(J,6)
ARG=X+Y*C(J,2)+Y*C(J,3)+C(J,4)
R=R+SQR(ARG)*C(J,7)
IF((C(J,5).GT.0.0).OR.(C(J,6).GT.0.0)) IGROW=1
RP=C(J,5)+2.0*C(J,6)*Y
IF(ARG.LE.0.0) GO TO 5
RP=RP+0.5*C(J,7)*(2.0*C(J,2)*Y+C(J,3))/SQR(ARG)
IGROW=1
5 CONTINUE
SR
H=H+HFACT
IF(NF.EQ.0)RETURN
IF(X,LE,XF(1),OR,Y,GT,XF(NF))RETURN
IFIN=1
DO 3 K=2,NF
JK
XL=XF(K)
IF(X,LE,XL)GO TO 4
3 CONTINUE
4 JI=J-1
S=(X=XF(JI))*YF(J)-YF(JI))/(YF(J)-XF(JI))+YF(JI)
RETURN
END

```

```

VPL11 1
VPL11 2
VPL11 3
VPL11 4
VPL11 5
VPL11 6
VPL11 7
VPL11 8
VPL11 9
VPL11 10
VPL11 11
VPL11 12
VPL11 13
VPL11 14
VPL11 15
VPL11 16
VPL11 17
VPL11 18
VPL11 19
VPL11 20
VPL11 21
VPL11 22
VPL11 23
VPL11 24
VPL11 25
VPL11 26
VPL11 27
VPL11 28
VPL11 29
VPL11 30
VPL11 31
VPL11 32
VPL11 33
VPL11 34
VPL11 35
VPL11 36
VPL11 37
VPL11 38
VPL11 39
VPL11 40
VPL11 41
VPL11 42
VPL11 43

```

	SUBROUTINE VOTEX(NV,XV,YV,GV,VV,NV)	VPL12 1
C		VPL12 2
C	THIS SUBROUTINE COMPUTES THE PERTURBATION VELOCITY COMPONENTS AT THE	VPL12 3
C	VERTEX LOCATIONS ACCOUNTING FOR MUTUAL EFFECTS AND THE PRESENCE	VPL12 4
C	OF A WINGED ELLIPTICAL CROSS SECTION	VPL12 5
C		VPL12 6
	DIMENSION XV(30),YV(30),GV(30),VV(30),AA(30)	VPL12 7
	DIMENSION VX(30),VY(30),G(30)	VPL12 8
	COMMON/V/A4,R4	VPL12 9
	COMMON/BLK1/A,R,S,PI,C1	VPL12 10
	COMMON/CON7/B	VPL12 11
	COMMON/CON1/A4,RR,RR	VPL12 12
	COMMON/CON2/SIG2,H2	VPL12 13
	COMPLEX C1,IG,Z,SD,DSOT,DTOS,D2SDT,V1,V2,V3,VEL,TAU,SI,SHR,SH	VPL12 14
	,DSDZ,D7DS,D2SDZ2	VPL12 15
	EXTERNAL Z,DSDZ,CZDS,D2SDZ2	VPL12 16
	N=N*NV-1	VPL12 17
	AA=AA+4	VPL12 18
	RH=H+H	VPL12 19
	APH=AA+H	VPL12 20
	APH2=APH*APH	VPL12 21
	R1=S+SQRT(S*S-AA+RH)	VPL12 22
	R=0.25*(R1+APH2/R1)	VPL12 23
	H=R+R	VPL12 24
	H2=H*H	VPL12 25
	SIG=0.5*APH	VPL12 26
	SIG2=SIG*SIG	VPL12 27
	RH=H+H	VPL12 28
	DO 100 I=1,NV	VPL12 29
	X0=XV(I)	VPL12 30
	Y0=YV(I)	VPL12 31
	G0=GV(I)	VPL12 32
	K1=0	VPL12 33
	DO 99 J=1,NV	VPL12 34
	IF(J.EQ,I)GO TO 99	VPL12 35
	K1=K1+1	VPL12 36
	VX(K1)=XV(J)	VPL12 37
	VY(K1)=YV(J)	VPL12 38
	G(K1)=GV(J)	VPL12 39
	99 CONTINUE	VPL12 40
	T=CMPLEX(X0,Y0)	VPL12 41
	SH=Z(T0)	VPL12 42
	SOB=CONJG(S0)	VPL12 43
	DSOT=DSDZ(S0)	VPL12 44
	DTOS=DZDS(S0)	VPL12 45
	D2SDT=D2SDZ2(S0)	VPL12 46
	V1=G0*DTOS+D2SDT/2.	VPL12 47
	V2=G0*DSOT+H*H/(SOB+S0+RR)	VPL12 48
	V3=CMPLEX(1.,0.)	VPL12 49
	DO 3 K=1,NV	VPL12 50
	TAU=CMPLEX(VX(K),VY(K))	VPL12 51
	SI=Z(TAU)	VPL12 52
	SIB=CONJG(SI)	VPL12 53
	3 V3=V3-G(K1)*(1./((S0-SI)-SIB/(S0+SIB+RR))+DSOT	VPL12 54
	VEL=DT*(V1+V2+V3)/(R1+PI)	VPL12 55
	VV(I)=DFAL(VEL)	VPL12 56
	VV(I)=-ATMAG(VEL)	VPL12 57
	100 CONTINUE	VPL12 58
	RETURN	VPL12 59
	END	VPL12 60

```

SUBROUTINE VVELS(NV,YY,ZZ,VY,VV,GAH,HH,S,V,W,VRTMAX)
VPL13 1
C
VPL13 2
C THIS SUBROUTINE COMPUTES PERTURBATION VELOCITY COMPONENTS DUE TO
VPL13 3
C NV EXTERNAL VERTICES AND THEIR IMAGES INSIDE A BODY WITH
VPL13 4
C ELLIPTICAL CROSS SECTION WITH OR WITHOUT MONO-PLANE WING.
VPL13 5
C
VPL13 6
C
VPL13 7
C DIMENSION VX(1),VY(1),G(1)
VPL13 8
C
VPL13 9
C COMMON/COM1/A2,H2,H2
VPL13 10
C COMMON/COM2/SIG2,H2
VPL13 11
C COMMON/PARAM/NOOT
VPL13 12
C
VPL13 13
C COMPLEX T0,V1,OSDT,Z,OSDZ,S1,SIM,S0,TAU,C1,VEL
VPL13 14
C
VPL13 15
C EXTERNAL Z,OSDZ
VPL13 16
C
VPL13 17
700 FORMAT (5X,15,5X,F10.5,1X,F10.5, 4(2X,F10.5,1X,F10.5))
VPL13 18
701 FORMAT (/10X,4HIVRT,14X,2HSI,21X,5HSIH,21X,2HVI,21X,4HOSDT,21X,
VPL13 19
1 2HSOZ
VPL13 20
1 14X,2HRE,9X,2HIM,10X,2HRE,9X,2HIM,11X,2HRE,9X,2HIM,11X,2HRE,
VPL13 21
1 9X,2HIM,11X,2HRE,9X,2HIM)
VPL13 22
C
VPL13 23
PI=3.14159265
VPL13 24
TLC=0.001
VPL13 25
C1=CMPLX(0.0,1.0)
VPL13 26
A2=AH*AH
VPL13 27
R2=RH*RH
VPL13 28
APR2=AH*RH
VPL13 29
APR2=APR*APR
VPL13 30
W1=S+SQRT(S+S-A2+H2)
VPL13 31
R2=0.25*(R1+APR2/R1)
VPL13 32
R2=RH
VPL13 33
H2=H
VPL13 34
H2=H*H
VPL13 35
SIG2=0.5*APR
VPL13 36
SIG2=SIG*SIG
VPL13 37
T0=CMPLX(YY,ZZ)
VPL13 38
S0=Z(T0)
VPL13 39
V1=CMPLX(0.0,0.0)
VPL13 40
OSDT=OSDZ(S0)
VPL13 41
C
VPL13 42
C LOOP OVER THE NUMBER OF VERTICES,NV
VPL13 43
C
VPL13 44
IF (NOOT.GE.2) WRITE (6,701)
VPL13 45
NOOT=1+NV
VPL13 46
TAU=CMPLX(VX(I),VY(I))
VPL13 47
S1=Z(TAU)
VPL13 48
S1=CO-SIG(S1)
VPL13 49
C=CARS(S1-S0)
VPL13 50
IF (0.LE.TLC) GO TO 2
VPL13 51
V1=V1+G(I)/(30-S1)
VPL13 52
2 CONTINUE
VPL13 53
C=CARS(S0-R2/SIM)
VPL13 54
IF (0.LE.TLC) GO TO 1
VPL13 55
V1=V1+G(I)/(30-R2/SIM)
VPL13 56
IF (NOOT.GE.2) WRITE (6,700) I,S1,SIB,V1,OSDT,S0
VPL13 57
1 CONTINUE
VPL13 58
C
VPL13 59
VEL=0.5*C1*V1*OSDT/PI
VPL13 60
VREFAL(VEL)
VPL13 61
A=ATNAG(VEL)
VPL13 62
AVEARS(V)
VPL13 63

```

```

      A=ABS(A)
      IF (V.GT.0.0.AND.AV.GE.VRTMAX) V=VRTMAX
      IF (V.LT.0.0.AND.AV.GE.VRTMAX) V=-VRTMAX
      IF (A.LT.0.0.AND.AV.GE.VRTMAX) V=-VRTMAX
      IF (A.LT.0.0.AND.AV.GE.VRTMAX) A=-VRTMAX
      RETURN
      END
      VPL13 64
      VPL13 65
      VPL13 66
      VPL13 67
      VPL13 68
      VPL13 69
      VPL13 70

      COMPLEX FUNCTION Z(CT)
      VPL14 1
      VPL14 2
      C THIS FUNCTION SUBROUTINE CALCULATES THE ZETA VALUE IN THE
      VPL14 3
      C TRANSFORMED (CIRCLE) PLANE FOR GIVEN TAU IN THE PHYSICAL PLANE
      VPL14 4
      C FOR AN ELLIPTICAL BODY WITH WINGS
      VPL14 5
      C
      VPL14 6
      COMMON/COM2/SIG2,M2
      VPL14 7
      COMMON/COM3/ZR,ZI
      VPL14 8
      COMMON/COM4/G2,G1
      VPL14 9
      COMMON/COM5/A2,A
      VPL14 10
      COMMON/PAPAM/NOU
      VPL14 11
      C
      VPL14 12
      COMPLEX *8 G1,G2;CT,*2,DBLU
      VPL14 13
      VPL14 14
      700 FORMAT (/19X,2FG1,22X,2HG2/14X,2HRE,9X,2HY,11X,2HRE,9X,2HY)
      VPL14 15
      701 FORMAT (10X,F10.5,1X,F10.5,2X,F10.5,1X,F10.5)
      VPL14 16
      C
      VPL14 17
      EXTERNAL DBLU
      VPL14 18
      C
      VPL14 19
      DBLE DBLU(CT)
      VPL14 20
      G1=+SIG2/
      VPL14 21
      G2=G1+G1*M2
      VPL14 22
      IF (NOU,EG,2) WRITE (6,700)
      VPL14 23
      IF (NOU,EW,2) WRITE (6,701) G1,G2
      VPL14 24
      AY=AINAG(G2)
      VPL14 25
      AY=1.0
      VPL14 26
      IF (YL,0.0) AY=-1.0
      VPL14 27
      YZ=A*AG(G1)
      VPL14 28
      AYZ=1.0
      VPL14 29
      IF (YZ,LT,0.0) AYZ=-1.0
      VPL14 30
      G2=CSQRT(G2)*AY*AYZ
      VPL14 31
      IF (NOU,EG,2) WRITE (6,701) G1,G2
      VPL14 32
      IF ((ABS(YZ),LE,0.0).AND.(REAL(G1),LT,0.0)) G2=CMPLX(+REAL(G2),
      VPL14 33
      1.0*ATNAG(G2))
      VPL14 34
      IF (NOU,EG,2) WRITE (6,701) G1,G2
      VPL14 35
      Z=0.5*(G1+G2)
      VPL14 36
      IF ((ABS(ZI),NE,0.0).AND.(ABS(ZR),NE,0.0)) Z=CMPLX(ZR*ABS(REAL(Z)),
      VPL14 37
      ZI*ABS(ATNAG(Z)))
      VPL14 38
      RETURN
      VPL14 39
      END
      VPL14 40

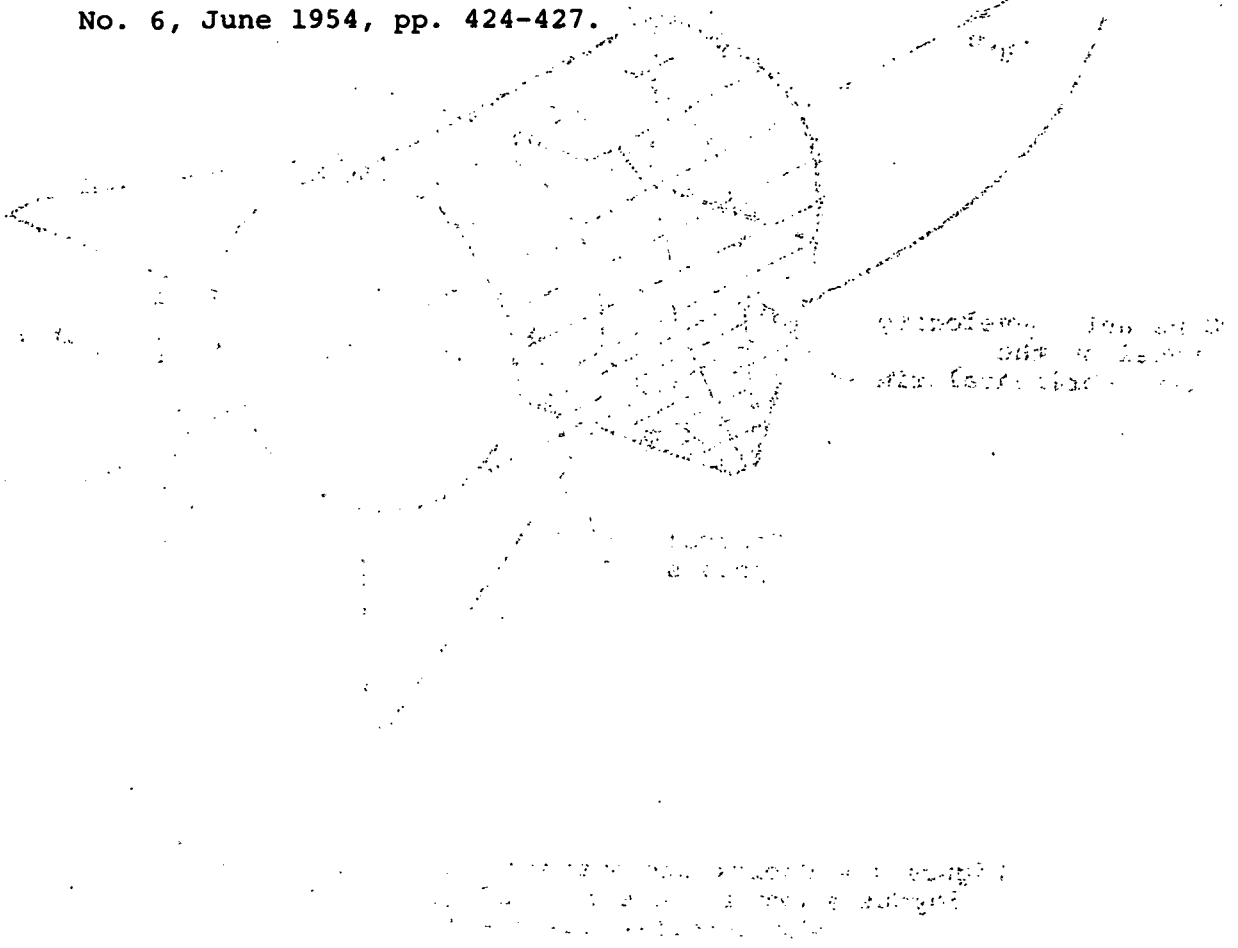
```


REFERENCES

1. Dillenius, Marnix F. E., Nielsen, Jack N.: Supersonic Lifting-Surface Computer Program for Cruciform Wing-Body Combinations in Combined Pitch and Sideslip. Office of Naval Research, Contract No. N00014-74-C-0050, Annual Report, December 1974 (also NEAR TR 74).
2. Dillenius, Marnix F. E., Nielsen, Jack N.: Prediction of Aerodynamics of Missiles at High Angles of Attack in Supersonic Flow. Office of Naval Research, Contract No. N00014-74-C-0050, Annual Report, October 1975 (also NEAR TR 99).
3. Polhamus, E. C.: Prediction of Vortex-Lift Characteristics Based on a Leading-Edge Suction Analogy. AIAA paper no. 69-1133, October 1969 (Jour. of Aircraft, vol. 8, no. 4, April 1971, pp. 193-199).
4. Mendenhall, Michael R., Nielsen, Jack N.: Effect of Symmetrical Vortex Shedding on the Longitudinal Aerodynamic Characteristics of Wing-Body-Tail Combinations. NASA CR-2473, Jan. 1975.
5. Spangler, Selden B., Mendenhall, Michael R.: Further Studies of Aerodynamic Loads at Spin Entry. Office of Naval Research, Contract No. N00014-74-C-0344, Annual Report, May 1, 1977 (also NEAR TR 141).
6. Woodward, F. A. and Larson, J. W.: A Method of Optimizing Camber Surfaces for Wing-Body Combinations at Supersonic Speeds. Part 1 - Theory and Application. NASA CR-69181, 1965.
7. Dillenius, Marnix F. E., Goodwin, Fred K., Nielsen, Jack N.: Prediction of Supersonic Store Separation Characteristics. Vol. 1 - Theoretical Methods and Comparisons with Experiment. AFFDL-TR-76-41, vol. 1, May 1976.
8. Nielsen, J. N.: Missile Aerodynamics. McGraw-Hill Book Co., 1960.
9. Woodward, F. A.: An Improved Method for the Aerodynamic Analysis of Wing-Body-Tail Configurations in Subsonic and Supersonic Flow. Part 1 - Theory and Application. NASA CR-2228, Part 1, May 1973.

10. Woodward, F. A.: An Improved Method for the Aerodynamic Analysis of Wing-Body-Tail Configurations in Subsonic and Supersonic Flow. Part II - Computer Program Description. NASA CR-2228, Part II, May 1973.
11. Graves, E. B.: Aerodynamic Characteristics of a Monoplanar Missile Concept with Bodies of Circular and Elliptical Cross Sections. NASA Technical Memorandum 74079, Dec. 1977.
12. Perkins, S. C., Jr., Goodwin, F. K.: Data Report for an External Store Test Program Conducted at Supersonic Speeds. Vol. V - Mach Number 1.5 Pressure Distribution Data. NEAR TR 103, Dec. 1975.
13. Perkins, S. C., Jr., Goodwin, F. K.: Data Report for an External Store Test Program Conducted at Supersonic Speeds. Vol. VI - Mach Number 2.0 Pressure Distribution Data. NEAR TR 103, Dec. 1975.
14. Perkins, S. C., Jr., Goodwin, F. K.: Data Report for an External Store Test Program Conducted at Supersonic Speeds. Vol. VII - Mach Number 2.5 Pressure Distribution Data. NEAR TR 103, Dec. 1975.
15. Nielsen, J. N., Spangler, S. B., Hensch, M. J.: A Study of Induced Rolling Moments for Cruciform-Winged Missiles. NEAR TR 61, Dec. 1973. Work performed for Naval Weapons Center, China Lake, CA, under Hughes Aircraft Subcontract K4-570727-WA6.
16. Margolis, K.: Theoretical Calculations of the Lateral Force and Yawing Moment due to Rolling at Supersonic Speeds for Swept Back Tapered Wings with Streamline Tips, Subsonic Leading Edges. NACA TN 2122, June 1950.
17. Cohen, D.: Formulas for the Supersonic Loading, Lift and Drag of Flat Swept-back Wings, with Leading Edges behind the Mach Lines. NACA Report 1050, 1951.
18. Lamar, John E.: Prediction of Vortex Flow Characteristics of Wings at Subsonic and Supersonic Speeds. J. of Aircraft, Vol. 13, No. 7, July 1976.
19. Peirce, B. O.: A Short Table of Integrals. Rev. by R. M. Foster, 4th ed., Boston, Ginn, 1956.

20. Gröbner, W. and Hofreiter, N.: Integraltafel. Springer-Verlag, 1961.
21. Adams, Gaynor J. and Dugan, Duane W.: Theoretical Damping in Roll and Rolling Moment Due to Differential Wing Incidence For Slender Cruciform Wing and Wing-Body Combinations. NACA TR 1088, 1952.
22. Bryson, Arthur E., Jr.: Evaluation of Inertia Coefficients of the Cross Section of a Slender Body. Jour. of Aero. Sci., Vol. 21, No. 6, June 1954, pp. 424-427.



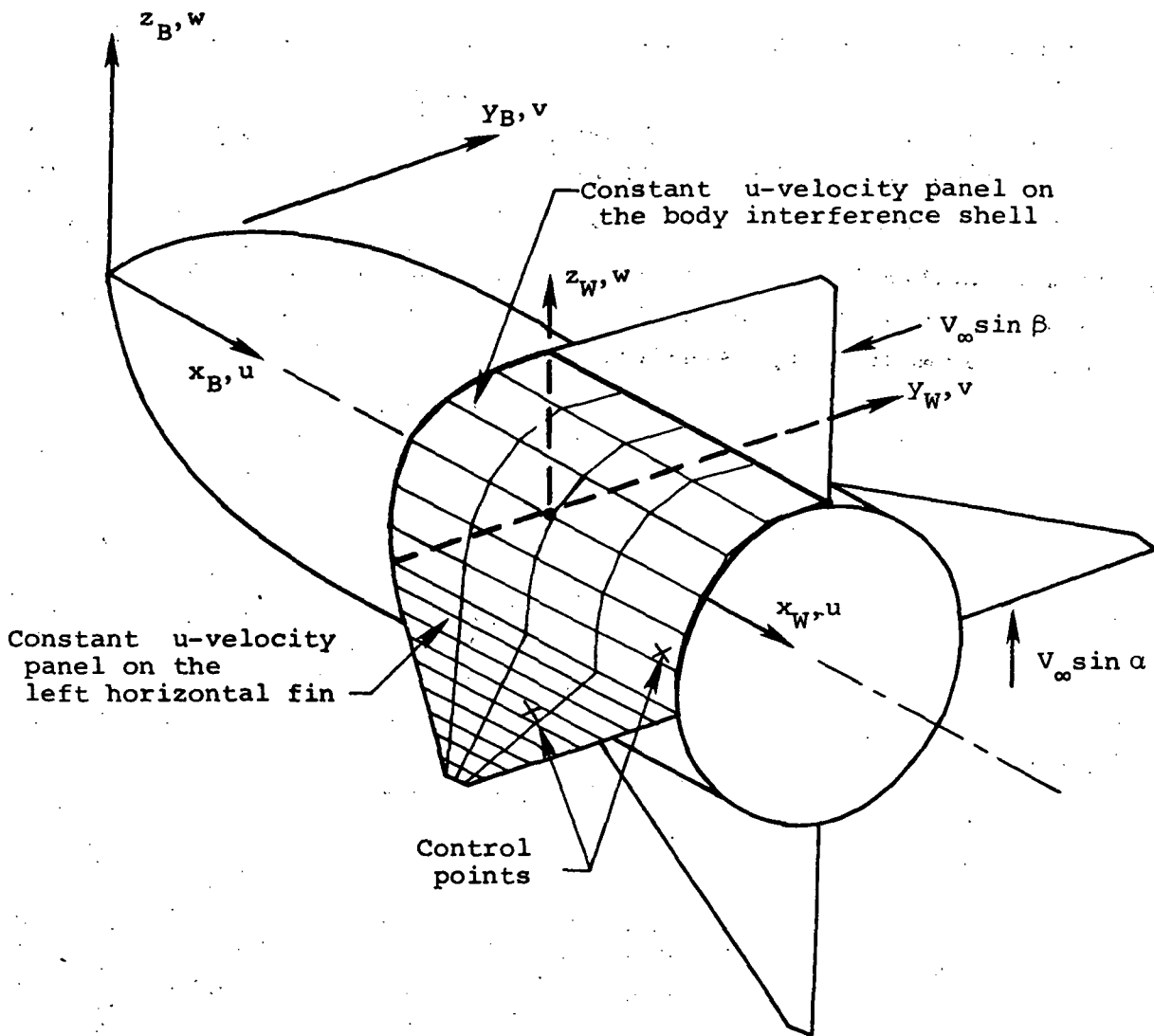


Figure 1.- Coordinate systems and typical panel layout shown for one fin and quarter of the interference shell.

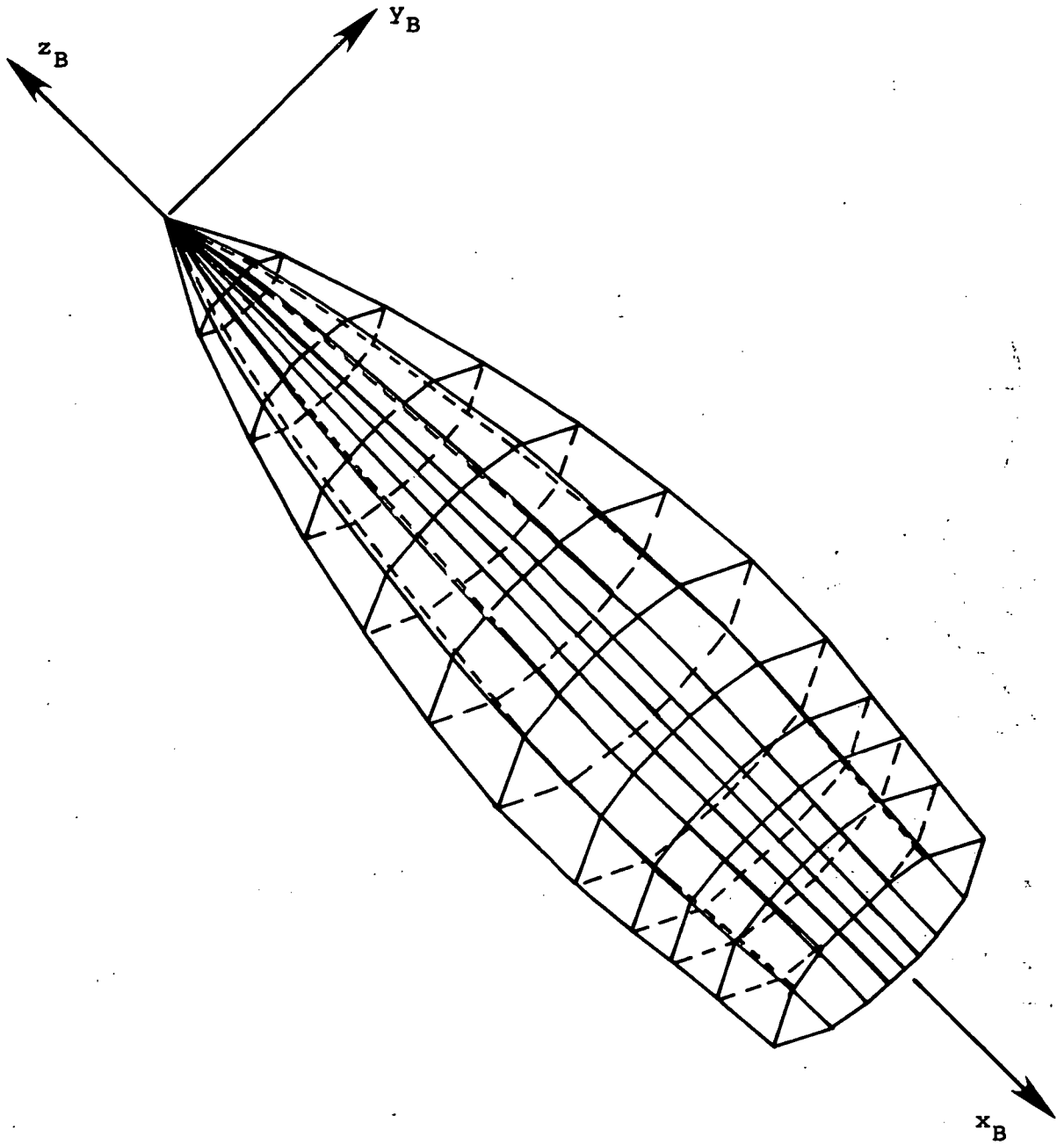
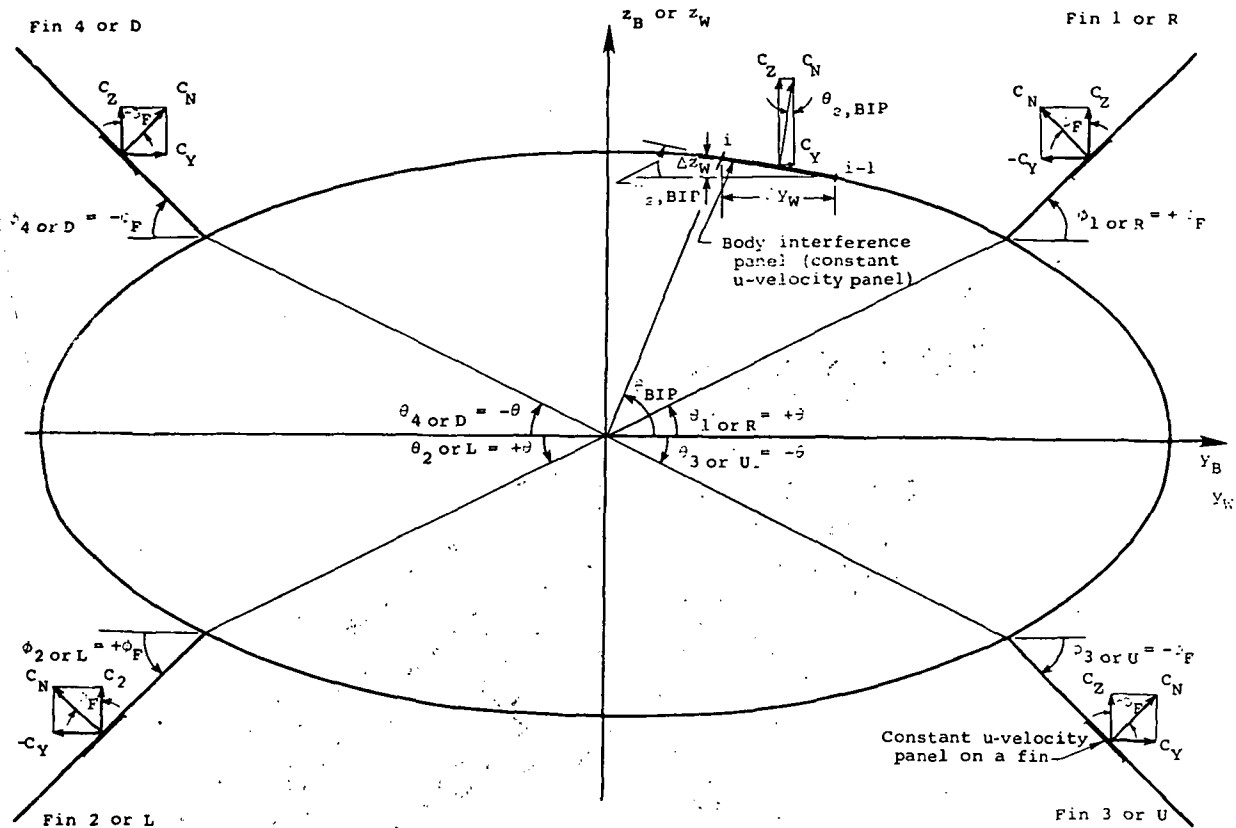


Figure 2.- Isometric view of typical layout of body source panels on the surface of a body with elliptical cross section, 11 rings with 16 panels each.



- ϕ_F = fin dihedral angle, PHIDIH
- ϕ_1 or R = dihedral angle of right upper fin, PHIFR=PHIDIH
- ϕ_2 or L = dihedral angle of left lower fin, PHIFL=PHIDIH
- ϕ_3 or U = dihedral angle of right lower fin, PHIFU=-PHIDIH
- ϕ_4 or D = dihedral angle of left upper fin, PHIFD=-PHIDIH
- θ = fin location polar angle, THETIT
- θ_1 or R = polar angle of right upper fin, THETR=THETIT
- θ_2 or L = polar angle of left lower fin, THETL=THETIT
- θ_3 or U = polar angle of right lower fin, THETI=-THETIT
- θ_4 or D = polar angle of left upper fin, THETD=-THETIT

Body interference panels:

$$\theta_{2,BIP,j} = \text{THETI}(j),$$

$$\Delta z_W = z_{W,i} - z_{W,i-1}$$

$$\Delta y_W = y_{W,i} - y_{W,i-1}$$

$$\sin \theta_{2,BIP} = \frac{\Delta z_W}{\sqrt{\Delta z_W^2 + \Delta y_W^2}}$$

$$\cos \theta_{2,BIP} = \frac{-\Delta y_W}{\sqrt{\Delta z_W^2 + \Delta y_W^2}}$$

these functions are used in the transformation (rotation) of the body interference panel to the reference (x_B, y_B, z_B) or (x_W, y_W, z_W) system

Figure 3.- Geometrical angles associated with case involving interdigitated tails on body with elliptical cross section as required by program DEMON2. Force coefficients associated with fins and body interference panel.

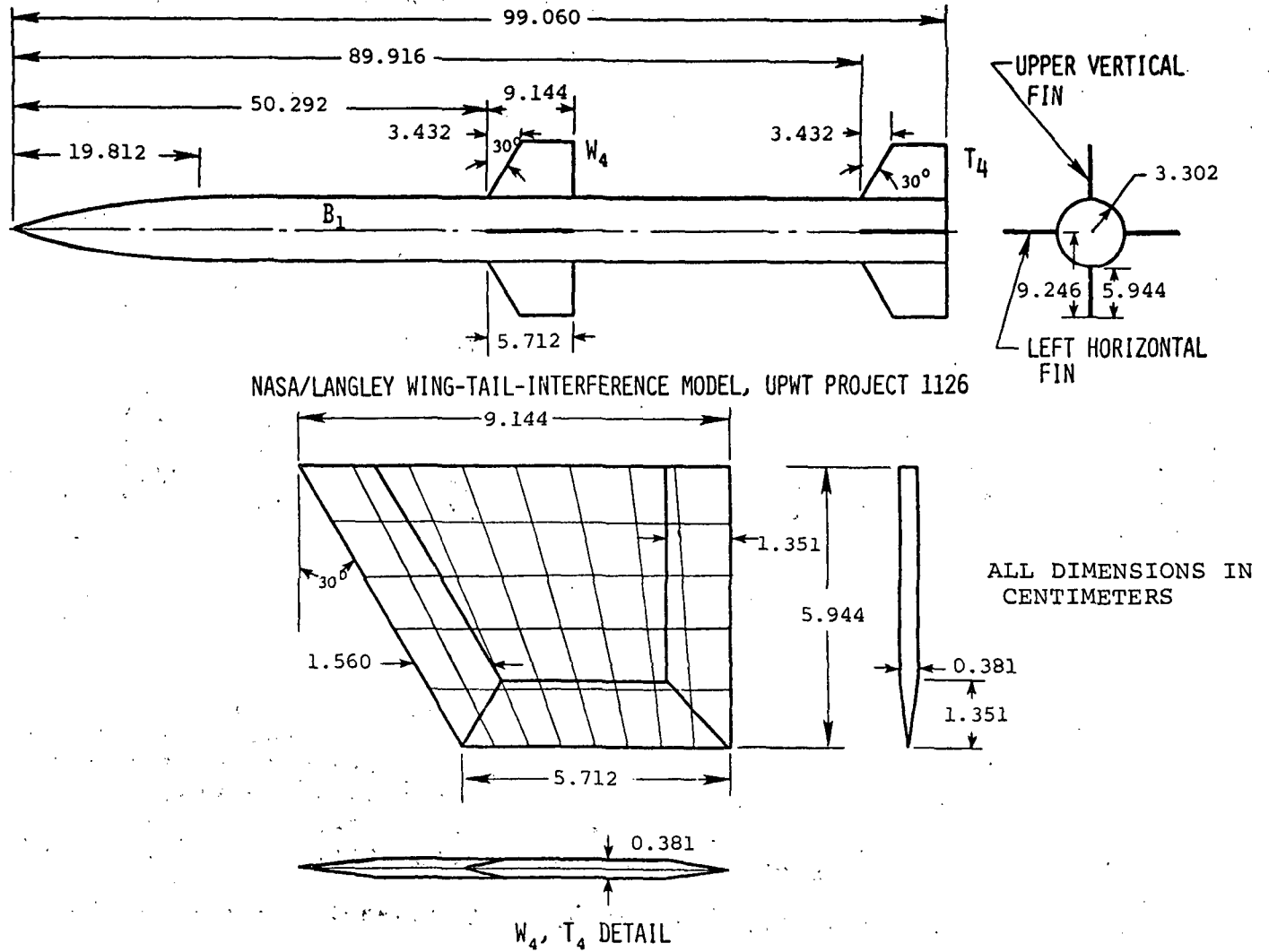


Figure 4.- Configuration used for first calculation example.

NASA/LANGLEY WING-TAIL INTERFERENCE MODEL, PRNT PROJ. 1126, CONFIGURATION B1W4.
 \$INPUT
 CRP=3.6, SWLEP=30.0, H2=2.34, SWLEV=30.0, CRPV=3.6, H2V=2.34,
 NCW=3, MSWR=5, MSWL=5, MSWD=5, MSWD=5, NCRX=1,
 ALFAC=14.216, PHI=45.0, FMACH=1.7,
 RB=1.3, NBDGR=16, NCAB=3, BIL=3.6, XWLF=19.8,
 SREF=5.30929, REFL=2.69,
 NDLINP=1, NOUT=0, NDRAG=1, NBDYPR=1,
 VRTMAX=0.5,
 NCPDUT=1,
 NTDAT=1, NCWT=8,
 XM=19.5, ZM=0.0,
 \$END

5	0	0							
0.122	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.141
0.122	0.122	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.141
0.122	0.122	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.141
0.122	0.122	0.0	0.0	0.0	0.0	0.0	0.0	-0.141	-0.141
0.122	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.141

\$BODY
 NXBODY=39, LNOSE=7.8, LHODY=39.0, BCONE=2,
 \$END

7777777777

Figure 5.- Input for program DEMON2, first sample case, step 16.

NASA/LANGLEY WING-TAIL INTERFERENCE MODEL, HPNT PROJ. 1126, CONFIGURATION B1=0.
 SENDIT

CRP	= .56E+01,	SREF	= .53E+02E+01,
S+LEP	= .3E+02,	REFL	= .269E+01,
S+TEP	= 0.0,	PHINT	= 0.0,
NCW	= 3,	THETIT	= 0.0,
MSWR	= 5,	XALE	= .198E+02,
MSWL	= 5,	NOLINP	= 1,
ALFAC	= .14216E+02,	NOUT	= 0,
PHI	= .45E+02,	NPR	= 0,
BZ	= .234E+01,	NDRAG	= 1,
FMACH	= .17E+01,	NVRTX	= 0,
LVS+P	= 0,	NPRESS	= 0,
FAC	= .95E+00,	VRTMAX	= .5E+00,
NFVDPH	= 0,	NCWR	= 3,
TOLFAC	= .1E+01,	VAGAIN	= 0,
MSWU	= 5,	RIL	= .36E+01,
MSWD	= 5,	ITATI	= 0,
S+LEV	= .3E+02,	NVRTPL	= 0,
S+TFV	= 0.0,	NHDYPR	= 1,
CRPV	= .36E+01,	NTPR	= 0,
BZV	= .234E+01,	NTDAT	= 1,
NCRX	= 1,	NCWT	= 8,
RR	= .13E+01,	NCPDIT	= 1,
RA	= .13E+01,	NVELTU	= 0,
CPATIO	= .1E+01,	XSTART	= 0.0,
NHDCR	= 16,	JCPT	= 0,
DELR	= 0.0,	EKLE	= .5E+00,
DELL	= 0.0,	EKSE	= .5E+00,
DELU	= 0.0,	X4	= .195E+02,
DELD	= 0.0,	Z4	= 0.0,
		SEND	

Figure 6.- Output of program DEMON2, first sample case, step 1b.

WING GEOMETRY

TIP CHORD = 2.24000
 ROOT CHORD = 5.60000
 WING SEMISPAN = 2.80000
 LEADING EDGE SWEEP = 30.00000 DEGREES
 TRAILING EDGE SWEEP = 0.00000 DEGREES

FLIGHT CONDITIONS

MACH = 1.70000 ALPHAC = 14.21600 PHI = 45.00000 ALFA = 10.00000 BETA = 10.00010

CRPT = 3.60000
 CRPTV = 3.60000

WING THICKNESS INPUT DATA

SPANWISE LOCATIONS OF PANEL SIDE EDGES AND SWEEP ANGLES
 OF WING SECTION TO THE LEFT

I	SPANWISE LOCATION FEET	LE SWEEP DEGREES	TE SWEEP DEGREES
---	------------------------------	---------------------	---------------------

RIGHT WING SURFACE

1	1.30000	0.00000	0.00000
2	1.76000	30.00000	0.00000
3	2.23600	30.00000	0.00000
4	2.70000	30.00000	0.00000
5	3.17200	30.00000	0.00000
6	3.64000	30.00000	0.00000

40 THICKNESS PANELS ARE TO BE Laid OUT
 5 CHORDWISE ROWS WITH 8 IN EACH ROW

UPPER WING SURFACE

1	1.30000	0.00000	0.00000
2	1.76000	30.00000	0.00000
3	2.23600	30.00000	0.00000
4	2.70000	30.00000	0.00000
5	3.17200	30.00000	0.00000
6	3.64000	30.00000	0.00000

40 THICKNESS PANELS ARE TO BE Laid OUT
 5 CHORDWISE ROWS WITH 8 IN EACH ROW

Figure 6.- Continued.

INPUT VALUES OF THE LOCAL SURFACE SLOPE OF THE THICKNESS
DISTRIBUTION, FOR EACH CROSSWISE ROW THE FIRST VALUE
IS FOR THE PANEL NEAREST THE LEADING EDGE

RIGHT WING SURFACE

ROW	SLOPES							
1	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
2	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
3	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
4	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
5	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100

UPPER WING SURFACE

ROW	SLOPES							
1	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
2	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
3	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
4	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
5	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100

CONTROL POINTS WRITTEN ON TABLE

I	XCPT	YCPT	ZCPT
1	1.2311	1.5310	0.
2	2.4867	1.5310	0.
3	3.5422	1.5310	0.
4	1.4157	1.9987	0.
5	2.4812	1.9987	0.
6	3.5467	1.9987	0.
7	1.6002	2.4664	0.
8	2.5757	2.4664	0.
9	3.4512	2.4664	0.
10	1.7847	2.9340	0.
11	2.6702	2.9340	0.
12	3.5557	2.9340	0.
13	1.9691	3.4016	0.
14	2.7647	3.4016	0.
15	3.5402	3.4016	0.
16	1.2311	-1.5310	0.
17	2.4867	-1.5310	0.
18	3.5422	-1.5310	0.
19	1.4157	-1.9987	0.
20	2.4812	-1.9987	0.
21	3.5467	-1.9987	0.
22	1.6002	-2.4664	0.
23	2.5757	-2.4664	0.
24	3.4512	-2.4664	0.
25	1.7847	-2.9340	0.
26	2.6702	-2.9340	0.
27	3.5557	-2.9340	0.
28	1.9691	-3.4016	0.
29	2.7647	-3.4016	0.
30	3.5402	-3.4016	0.
31	1.2311	0.	1.5310
32	2.4867	0.	1.5310

33	3.5422	0.	1.5110
34	3.4157	0.	1.9987
35	2.4812	0.	1.9987
36	3.5467	0.	1.9987
37	1.6002	0.	2.4864
38	2.5757	0.	2.4864
39	3.5512	0.	2.4864
40	1.7847	0.	2.9340
41	2.6702	0.	2.9340
42	3.5557	0.	2.9340
43	1.9691	0.	3.4016
44	2.7647	0.	3.4016
45	3.5602	0.	3.4016
46	1.2311	0.	-1.5310
47	2.3467	0.	-1.5310
48	3.5422	0.	-1.5310
49	1.4157	0.	-1.9987
50	2.4812	0.	-1.9987
51	3.5467	0.	-1.9987
52	1.6002	0.	-2.4864
53	2.5757	0.	-2.4864
54	3.5512	0.	-2.4864
55	1.7847	0.	-2.9340
56	2.6702	0.	-2.9340
57	3.5557	0.	-2.9340
58	1.9691	0.	-3.4016
59	2.7647	0.	-3.4016
60	3.5602	0.	-3.4016
61	1.1400	1.2505	.24874
62	1.1400	1.0601	.70836
63	1.1400	.70836	1.0601
64	1.1400	.24874	1.2505
65	1.1400	-.24874	1.2505
66	1.1400	-.70836	1.0601
67	1.1400	-1.0601	.70836
68	1.1400	-1.2505	.24874
69	1.1400	-1.2505	-.24874
70	1.1400	-1.0601	-.70836
71	1.1400	-.70836	-1.0601
72	1.1400	-.24874	-1.2505
73	1.1400	.24874	-1.2505
74	1.1400	.70836	-1.0601
75	1.1400	1.0601	-.70836
76	1.1400	1.2505	-.24874
77	2.3400	1.2505	.24874
78	2.3400	1.0601	.70836
79	2.3400	.70836	1.0601
80	2.3400	.24874	1.2505
81	2.3400	-.24874	1.2505
82	2.3400	-.70836	1.0601
83	2.3400	-1.0601	.70836
84	2.3400	-1.2505	.24874
85	2.3400	-1.2505	-.24874
86	2.3400	-1.0601	-.70836
87	2.3400	-.70836	-1.0601
88	2.3400	-.24874	-1.2505
89	2.3400	.24874	-1.2505
90	2.3400	.70836	-1.0601

91	2.3400	1.0601	-.70836
92	2.3400	1.2505	-.24874
93	3.5400	1.2505	.24874
94	3.5400	1.0601	.70836
95	3.5400	.70836	1.0601
96	3.5400	.24874	1.2505
97	3.5400	-.24874	1.2505
98	3.5400	-.70836	1.0601
99	3.5400	-1.0601	.70836
100	3.5400	-1.2505	.24874
101	3.5400	-1.2505	-.24874
102	3.5400	-1.0601	-.70836
103	3.5400	-.70836	-1.0601
104	3.5400	-.24874	-1.2505
105	3.5400	.24874	-1.2505
106	3.5400	.70836	-1.0601
107	3.5400	1.0601	-.70836
108	3.5400	1.2505	-.24874

BRNDY
 NBRNDY = 39,
 LNDRF = .7AF+01,
 LBRNDY = .39F+02,
 BCOOF = 2,
 SEND

Figure 6.- Continued.

PHYSICAL DIMENSIONS OF BODY AND LINE SINGULARITY STRENGTHS REPRESENTING THE BODY AT $\rho = 1.7000$

ALFACB 10.2160

X	U	DR/DX	TY	T(1)	TC(1)
1 0.0000	-.02635E-13	.50784	.58610E-13	.10092	.34463E-01
2 1.0263	.32639	.29453	.57741	-.00121E-01	-.10955E-01
3 2.0526	.00316	.28611	1.2244	-.25012E-01	-.42846E-02
4 3.0789	.85207	.27020	1.9350	-.25274E-01	-.01341E-02
5 4.1053	1.0145	.15547	2.7106	-.18861E-01	-.74517E-02
6 5.1316	1.1515	.11164	3.5085	-.15477E-01	-.75496E-02
7 6.1579	1.2439	.08039E-01	4.0079	-.11952E-01	-.73645E-02
8 7.1842	1.2921	.25613E-01	5.0073	-.083169E-02	-.70718E-02
9 8.2105	1.3000	0.	6.0243	.31078E-01	-.28112E-02
10 9.2368	1.3000	0.	7.0404	.35293E-02	.47755E-02
11 10.2632	1.3000	0.	8.0470	.34046E-02	.39930E-02
12 11.2895	1.3000	0.	9.5023	.14132E-02	.36673E-02
13 12.3158	1.3000	0.	10.529	.93969E-03	.28432E-02
14 13.3421	1.3000	0.	11.555	.55466E-03	.17866E-02
15 14.3684	1.3000	0.	12.581	.36257E-03	.10708E-02
16 15.3947	1.3000	0.	13.608	.25450E-03	.56355E-03
17 16.4211	1.3000	0.	14.634	.16227E-03	.22980E-03
18 17.4474	1.3000	0.	15.660	.11249E-03	.33410E-04
19 18.4737	1.3000	0.	16.686	.79559E-04	-.67255E-04
20 19.5000	1.3000	0.	17.713	.57218E-04	-.10624E-03
21 20.5263	1.3000	0.	18.739	.41794E-04	-.10943E-03
22 21.5526	1.3000	0.	19.765	.30961E-04	-.05708E-04
23 22.5789	1.3000	0.	20.792	.23276E-04	-.75192E-04
24 23.6053	1.3000	0.	21.818	.17650E-04	-.54633E-04
25 24.6316	1.3000	0.	22.844	.13554E-04	-.37078E-04
26 25.6579	1.3000	0.	23.871	.10525E-04	-.25532E-04
27 26.6842	1.3000	0.	24.897	.82509E-05	-.15875E-04
28 27.7105	1.3000	0.	25.923	.65280E-05	-.74713E-05
29 28.7368	1.3000	0.	26.950	.52100E-05	-.35327E-05
30 29.7632	1.3000	0.	27.976	.41922E-05	-.13202E-05
31 30.7895	1.3000	0.	29.002	.33993E-05	-.22844E-06
32 31.8158	1.3000	0.	30.029	.27766E-05	.19378E-06
33 32.8421	1.3000	0.	31.055	.22435E-05	.25675E-06
34 33.8684	1.3000	0.	32.081	.18903E-05	.15744E-06
35 34.8947	1.3000	0.	33.108	.15745E-05	.11691E-07
36 35.9211	1.3000	0.	34.134	.13191E-05	-.12295E-06
37 36.9474	1.3000	0.	35.160	.11112E-05	-.22221E-06
38 37.9737	1.3000	0.	36.186	.94102E-06	-.28186E-06
39 39.0000	1.3000	0.	37.213	0.	0.

PRESSURE COEFFICIENTS AT POINTS ON BODY MERIDIANS

I	THETA, DEG.	ZB	YB	ZB	DTOT	VTOT	WTOT	CP, LIN.	CP, REFN.	DR/DX	P/PINF, REFN.	P/PINF, LIN.
---	-------------	----	----	----	------	------	------	----------	-----------	-------	---------------	--------------

TOTAL NUMBER OF PRESSURE POINTS: JCPTB 320

BODY RINGS 1

1	11.25000	.51316	.16626	.03307	-.29308	.36619	.14431	.40615	.31470	.31793	1.63664	1.82164
2	22.50000	.51316	.15662	.04087	-.18444	.24906	.22763	.34934	.20360	.31793	1.40299	1.70720

Figure 6.- Continued.

3	51,75000	.51310	.10995	.09418	-.16471	.20227	.26242	.32442	.18128	.31793	1.38673	1.66602
4	45,00000	.51310	.11987	.11987	-.14395	.11616	.26874	.28789	.13035	.31793	1.26371	1.58241
5	56,25000	.51310	.09418	.14095	-.12318	.04000	.25033	.24637	.09186	.31793	1.18533	1.49840
6	67,50000	.51310	.06447	.15662	-.10322	-.01932	.21344	.20644	.06525	.31793	1.13200	1.41742
7	78,75000	.51310	.03307	.16626	-.08482	-.05811	.16788	.16964	.04898	.31793	1.09908	1.34318
8	90,00000	.51310	-.00000	.16952	-.06869	-.07629	.12065	.13738	.04083	.31793	1.08261	1.27792
9	101,25000	.51310	.03307	.16626	-.05505	-.07713	.08050	.11091	.03828	.31793	1.07744	1.22437
10	112,50000	.51310	.06447	.15662	-.04527	-.06654	.05227	.09124	.03876	.31793	1.07822	1.18458
11	123,75000	.51310	.09418	.14095	-.03956	-.05195	.03986	.07913	.04007	.31793	1.08107	1.16007
12	135,00000	.51310	.11987	.11987	-.03752	-.04093	.04093	.07504	.04089	.31793	1.08232	1.15180
13	146,25000	.51310	.14095	.09418	-.03956	-.03986	.05195	.07913	.04007	.31793	1.08107	1.16007
14	157,50000	.51310	.15662	.06447	-.04527	-.06654	.05227	.09124	.04876	.31793	1.07822	1.18458
15	168,75000	.51310	.16626	.03307	-.05505	-.08050	.07713	.11091	.03828	.31793	1.07744	1.22437
16	180,00000	.51310	.16952	-.00000	-.06869	-.07629	.12065	.13738	.04083	.31793	1.08261	1.27792
17	191,25000	.51310	.16626	.03307	-.08482	-.16788	.05811	.16964	.04898	.31793	1.09908	1.34318
18	202,50000	.51310	.15662	.06447	-.10322	-.21344	.01932	.20644	.06525	.31793	1.13200	1.41742
19	213,75000	.51310	.14095	.09418	-.12318	-.25033	.04000	.24637	.09186	.31793	1.18533	1.49840
20	225,00000	.51310	.11987	.11987	-.14395	-.26874	.11616	.28789	.13035	.31793	1.26371	1.58241
21	236,25000	.51310	.09418	.14095	-.16471	-.20227	.26242	.32942	.18128	.31793	1.36673	1.66602
22	247,50000	.51310	.06447	.15662	-.18448	-.22783	.28976	.36935	.24369	.31793	1.49299	1.74720
23	258,75000	.51310	.03307	.16626	-.20388	-.16431	.36619	.40615	.31470	.31793	1.63664	1.82161
24	270,00000	.51310	.00000	.16952	-.21920	-.07629	.42368	.43841	.38919	.31793	1.78734	1.88690
25	281,25000	.51310	.03307	.16626	-.23244	.02907	.45337	.46488	.46006	.31793	1.93070	1.94045
26	292,50000	.51310	.06447	.15662	-.24227	.14177	.45015	.48455	.51904	.31793	2.05002	1.99024
27	303,75000	.51310	.09418	.14095	-.24833	.25047	.41274	.49686	.55827	.31793	2.12949	2.00475
28	315,00000	.51310	.11987	.11987	-.25038	.34397	.34397	.50075	.57205	.31793	2.15725	2.03002
29	326,25000	.51310	.14095	.09418	-.24833	.41274	-.25047	.49686	.55827	.31793	2.12939	2.00475
30	337,50000	.51310	.15662	.06447	-.24227	.14177	.45015	.48455	.51904	.31793	2.05002	1.99024
31	348,75000	.51310	.16626	.03307	-.23244	.45337	.45337	.46488	.46006	.31793	1.93070	1.94045
32	360,00000	.51310	.16952	.00000	-.21920	.42368	.07629	.43841	.38919	.31793	1.78734	1.88690

RNDY PING# 2

1	11,25000	2.56579	.70961	.14115	-.14124	.29958	.18203	.28247	.19422	.22298	1.39291	1.57144
2	22,50000	2.56579	.66843	.27687	-.12479	.21696	.23429	.24959	.12886	.22298	1.26089	1.50441
3	33,75000	2.56579	.60157	.40196	-.10695	.12713	.25530	.21390	.07388	.22298	1.14905	1.43273
4	45,00000	2.56579	.51160	.51160	-.08980	.04161	.24586	.17679	.03113	.22298	1.06297	1.35766
5	56,25000	2.56579	.40196	.60157	-.06980	-.02944	.21090	.13969	.00171	.22298	1.00347	1.28258
6	67,50000	2.56579	.27687	.66843	-.05200	-.07871	.15864	.10400	-.01550	.22298	.98864	1.21040
7	78,75000	2.56579	.14115	.70961	-.03556	-.10271	.09915	.07112	-.02244	.22298	.95460	1.14387
8	90,00000	2.56579	.00000	.72351	-.02115	-.10212	.04282	.04224	-.02170	.22298	.95609	1.08556
9	101,25000	2.56579	-.14115	.70961	-.00937	-.08155	-.00133	.01864	-.01644	.22298	.96695	1.03770
10	112,50000	2.56579	-.27687	.66843	-.00053	-.04863	-.02703	.00106	-.00950	.22298	.98677	1.00214
11	123,75000	2.56579	-.40196	.60157	.00088	-.01272	-.03168	-.00977	-.00406	.22298	.99179	.98024
12	135,00000	2.56579	-.51160	.51160	.00871	.01671	-.01671	-.00362	-.00200	.22298	.99595	.97285
13	146,25000	2.56579	-.60157	.40196	.00888	.03168	-.01272	-.00977	-.00406	.22298	.99179	.98024
14	157,50000	2.56579	-.66843	.27687	.00053	.02703	.04863	.00106	-.00950	.22298	.98677	1.00214
15	168,75000	2.56579	-.70961	.14115	-.00032	.00133	.08155	.01864	-.01644	.22298	.96695	1.03770
16	180,00000	2.56579	-.72351	.00000	-.02115	.04282	.10212	.04224	-.02170	.22298	.95609	1.08556
17	191,25000	2.56579	-.70961	-.14115	-.03556	-.09915	.07112	-.02244	-.02244	.22298	.95460	1.14387
18	202,50000	2.56579	-.66843	-.27687	-.05200	-.15864	.07871	.10400	-.01550	.22298	.98864	1.21040
19	213,75000	2.56579	-.60157	.40196	-.06980	-.21090	.02944	.13969	.00171	.22298	1.00347	1.28258
20	225,00000	2.56579	-.51160	.51160	-.08980	-.24586	-.04161	.17679	.03113	.22298	1.06297	1.35766
21	236,25000	2.56579	-.40196	.60157	-.10695	-.25530	-.12713	.21390	.07388	.22298	1.14905	1.43273
22	247,50000	2.56579	-.27687	.66843	-.12479	-.23429	.24959	.12886	.07388	.22298	1.26089	1.50441
23	258,75000	2.56579	-.14115	.70961	-.14124	-.18203	.29958	.28247	.19422	.22298	1.39291	1.57144

Figure 6.- Continued.

24	270,00000	2,56579	.00000	-.72351	-.15565	-.10212	-.36372	.31130	.26490	.22298	1,53599	1,62975
25	281,25000	2,56579	.14115	-.70941	-.14708	-.00223	-.40006	.33495	.33372	.22298	1,67511	1,67761
26	292,50000	2,56579	.27887	-.68843	-.17427	.10695	-.40243	.35253	.39199	.22298	1,79299	1,71317
27	303,75000	2,56579	.40196	-.60157	-.14164	.21315	-.36971	.36335	.43119	.22298	1,87230	1,73507
28	315,00000	2,56579	.51160	-.51160	-.14350	.30418	-.30418	.36701	.44503	.22298	1,90030	1,70206
29	326,25000	2,56579	.60157	-.40196	-.14164	.36971	-.21315	.36335	.43119	.22298	1,87230	1,73507
30	337,50000	2,56579	.68843	-.27887	-.17427	.40263	-.10695	.35253	.39199	.22298	1,79299	1,71317
31	348,75000	2,56579	.70961	-.14115	-.16748	.40006	.00223	.33495	.33372	.22298	1,67511	1,67761
32	360,00000	2,56579	.72351	.00000	-.15565	.36372	.10212	.31130	.26490	.22298	1,53599	1,62975

BODY RING 3

1	11,25000	4,61842	1,05771	.21238	-.00033	.22574	.20086	.16066	.00989	.13346	1,14139	1,32501
2	22,50000	4,61842	1,00576	.41660	-.00000	.13775	.24102	.13359	.01221	.13346	1,02471	1,27026
3	33,75000	4,61842	.90516	.60481	-.05211	.04519	.24720	.10423	-.03411	.13346	.93100	1,21085
4	45,00000	4,61842	.76977	.76977	-.03484	-.03919	.22098	.07369	-.06712	.13346	.86423	1,14907
5	56,25000	4,61842	.60481	.90516	-.02157	-.10436	.16857	.04315	-.08669	.13346	.82863	1,08779
6	67,50000	4,61842	.41660	1,00576	-.00000	-.14264	.09977	.01378	-.09400	.13346	.80985	1,02788
7	78,75000	4,61842	.21238	1,08863	.00664	-.15070	.02641	-.01328	-.09112	.13346	.81567	.97313
8	90,00000	4,61842	.00000	1,08863	.01850	-.13008	-.03951	-.03701	-.08092	.13346	.83030	.92514
9	101,25000	4,61842	-.21238	1,06771	.02824	-.08677	-.08768	-.05647	-.06693	.13346	.84461	.88575
10	112,50000	4,61842	-.41660	1,00576	.03547	-.03020	-.11104	-.07094	-.05303	.13346	.89273	.85409
11	123,75000	4,61842	-.60481	.90516	.03992	.02825	-.10687	-.07985	-.04285	.13346	.91124	.83847
12	135,00000	4,61842	-.76977	.76977	.04143	.07716	-.07716	-.08286	-.03916	.13346	.92073	.83238
13	146,25000	4,61842	-.90516	.60481	.03992	.10687	-.02825	-.07985	-.04289	.13346	.91374	.83847
14	157,50000	4,61842	-1,00576	.41660	.03547	.11104	-.05020	-.07094	-.05303	.13346	.91374	.83847
15	168,75000	4,61842	-1,06771	.21238	.02824	.08768	.08677	-.05647	-.06693	.13346	.89273	.85409
16	180,00000	4,61842	-1,08863	.00000	.01850	.13008	.03951	-.03701	-.08092	.13346	.83030	.92514
17	191,25000	4,61842	-1,06771	-.21238	.00664	.15070	-.02641	-.01328	-.09112	.13346	.81567	.97313
18	202,50000	4,61842	-1,00576	.41660	.03992	.09977	.14264	.01378	-.09400	.13346	.80985	1,02788
19	213,75000	4,61842	-.90516	.60481	-.02157	-.16857	.10436	.04315	-.08669	.13346	.82463	1,08779
20	225,00000	4,61842	-.76977	.76977	-.03484	-.03919	.22098	.07369	-.06712	.13346	.86423	1,14907
21	236,25000	4,61842	-.60481	.90516	-.05211	-.24720	.04519	.10423	-.03411	.13346	.93100	1,21085
22	247,50000	4,61842	-.41660	1,00576	-.00000	-.24102	-.13775	.13359	.01221	.13346	1,02471	1,27026
23	258,75000	4,61842	-.21238	1,06771	.00664	-.20086	-.22574	.16066	.00989	.13346	1,14139	1,32501
24	270,00000	4,61842	.00000	1,08863	.01850	-.13008	-.03951	.14438	.01608	.13346	1,27215	1,37300
25	281,25000	4,61842	.21238	1,06771	-.10192	.03661	.33983	.20385	.19915	.13346	1,40288	1,41238
26	292,50000	4,61842	.41660	1,00576	-.10016	.08818	.34857	.21831	.25494	.13346	1,51574	1,40164
27	303,75000	4,61842	.60481	.90516	-.11361	.17108	.32064	.22722	.29296	.13346	1,59265	1,45967
28	315,00000	4,61842	.76977	.76977	-.11511	.25895	.25895	.23023	.30647	.13346	1,61998	1,46575
29	326,25000	4,61842	.90516	.60481	-.11361	.32064	-.17108	.22722	.29296	.13346	1,59265	1,45967
30	337,50000	4,61842	1,00576	.41660	-.10916	.34857	.08818	.21831	.25494	.13346	1,51574	1,40164
31	348,75000	4,61842	1,06771	-.21238	-.10192	.33983	.03661	.20385	.19915	.13346	1,40288	1,41238
32	360,00000	4,61842	1,08863	.00000	-.09219	.29660	.13008	.18438	.13453	.13346	1,27215	1,37300

BODY RING 4

1	11,25000	6,67105	1,24992	.24845	-.01697	.14328	.22303	.03394	-.06233	.04699	.87392	1,06887
2	22,50000	6,67105	1,17655	.48734	-.00804	.04966	.25004	.01608	-.10916	.04699	.77918	1,03254
3	33,75000	6,67105	1,05887	.70751	.00165	-.00565	.24017	-.00320	-.14409	.04699	.70850	.99334
4	45,00000	6,67105	.90049	.90049	.01172	-.12864	.19587	-.02345	-.14569	.04699	.66041	.95257
5	56,25000	6,67105	.70751	1,05887	.02180	-.18734	.12471	-.04368	-.17404	.04699	.64791	.91180
6	67,50000	6,67105	.48734	1,17655	.03144	-.21365	.03819	-.06298	-.17024	.04699	.65561	.87280
7	78,75000	6,67105	.24845	1,24992	.04042	-.26448	-.05002	-.08080	-.15623	.04699	.68394	.83647
8	90,00000	6,67105	.00000	1,27340	.00825	-.36226	-.12618	-.09649	-.13495	.04699	.76699	.80080

Figure 6.- Continued.

9	101,25000	6.67105	-.24445	1.24902	.05467	-.09444	-.17860	-.14934	-.11043	.04699	.77659	.77841
10	112,50000	6.67105	-.48734	1.17655	.05944	-.01246	-.19939	-.11888	-.04758	.04699	.82282	.75950
11	123,75000	6.67105	-.70751	1.05887	.06238	.07024	-.18570	-.12476	-.07135	.04699	.85566	.70761
12	135,00000	6.67105	-.90049	.90049	.06337	.14011	-.14011	-.12674	-.06547	.04699	.86744	.70359
13	146,25000	6.67105	-1.05887	.70751	.06238	.18570	-.07024	-.12476	-.07135	.04699	.85566	.70761
14	157,50000	6.67105	-1.17655	.48734	.05944	.19939	.01246	-.11888	-.04758	.04699	.82282	.76950
15	168,75000	6.67105	-1.24902	.24445	.05467	.17860	.09444	-.11043	-.04699	.04699	.77659	.77841
16	180,00000	6.67105	-1.27349	.00000	.04825	.12618	.16226	-.09649	-.13495	.04699	.72699	.80480
17	191,25000	6.67105	-1.24902	.24445	.04825	.05002	.20448	-.04048	-.15623	.04699	.68194	.83647
18	202,50000	6.67105	-1.17655	-.48734	.03149	-.03819	.21365	-.06298	-.17024	.04699	.65560	.87260
19	213,75000	6.67105	-1.05887	-.70751	.02180	-.12471	.18734	-.04360	-.17404	.04699	.67791	.91180
20	225,00000	6.67105	-.90049	-.90049	.01172	-.19527	.12864	-.02345	-.16569	.04699	.68481	.95257
21	236,25000	6.67105	-.70751	-1.05887	.00165	-.24017	.04565	-.00329	-.14409	.04699	.70850	.99334
22	247,50000	6.67105	-.48734	-1.17655	-.00884	-.25004	-.04966	.01608	-.10916	.04699	.77918	1.03254
23	258,75000	6.67105	-.24445	-1.24902	-.01697	-.22303	-.14328	.03394	-.06233	.04699	.87392	1.06867
24	270,00000	6.67105	.00000	-1.27349	-.02480	-.16226	-.22127	.04960	-.00729	.04699	.98525	1.10034
25	281,25000	6.67105	.24445	-1.24902	-.03122	-.07591	-.27186	.06244	.04963	.04699	1.10040	1.12632
26	292,50000	6.67105	.48734	-1.17655	-.03600	.02393	-.28724	.07199	.09997	.04699	1.20723	1.14564
27	303,75000	6.67105	.70751	-1.05887	-.03893	.12307	-.26474	.07787	.13482	.04699	1.27274	1.15753
28	314,00000	6.67105	.90049	-.90049	-.03993	.20735	-.20735	.07985	.14730	.04699	1.29799	1.16154
29	326,25000	6.67105	1.05887	-.70751	-.03493	.26476	-.12307	.07787	.13482	.04699	1.27274	1.15753
30	337,50000	6.67105	1.17655	-.48734	-.03600	.28724	-.02393	.07199	.09997	.04699	1.20723	1.14564
31	348,75000	6.67105	1.24902	-.24445	-.04122	.27186	.07591	.06244	.04963	.04699	1.10040	1.12632
32	360,00000	6.67105	1.27349	.00000	-.02480	.22127	.16226	.04960	-.00729	.04699	.98525	1.10034

BODY RING= 5

BODY NOSE SEPARATION AT XB/RB = 5.52485
 VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = .07510
 VORTEX Y/RLOC (UNROLLED COORDS) = .63291
 VORTEX Z/RLOC (UNROLLED COORDS) = 1.17494

RIGHT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = .07510
 RIGHT VORTEX Y(ROLLED COORDS,)/RLOC = .38327
 RIGHT VORTEX Z(ROLLED COORDS,)/RLOC = 1.27835
 LEFT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = -.07510
 LEFT VORTEX Y(ROLLED COORDS,)/RLOC = -1.27835
 LEFT VORTEX Z(ROLLED COORDS,)/RLOC = .38327

1	11,25000	8.72368	1.27502	.25362	.01884	.09244	.24186	-.03492	-.13846	0.00000	.71949	.92531
2	22,50000	8.72368	1.20104	.49749	.02098	-.00453	.25906	-.04195	-.17259	0.00000	.65086	.91513
3	33,75000	8.72368	1.08091	.72224	.02471	-.09954	.23510	-.04742	-.19340	0.00000	.60875	.90407
4	45,00000	8.72368	.91924	.91924	.02655	-.17601	.17601	-.05310	-.19873	0.00000	.59797	.89257
5	56,25000	8.72368	.72224	1.08091	.02939	-.21820	.08754	-.05879	-.18674	0.00000	.62223	.88108
6	67,50000	8.72368	.49749	1.20104	.03213	-.21115	-.01551	-.06425	-.15486	0.00000	.66673	.87092
7	78,75000	8.72368	.25362	1.27502	.03464	-.13439	-.11302	-.06929	-.09967	0.00000	.70837	.85983
8	90,00000	8.72368	.00000	1.30000	.03685	.03919	-.17544	-.07370	-.02491	0.00000	.93950	.85090
9	101,25000	8.72368	-.25362	1.27502	.03866	.51798	-.14709	-.07733	-.03667	0.00000	.92583	.84357
10	112,50000	8.72368	-.49749	1.20104	.04001	.37297	-.09365	-.08092	-.04200	0.00000	.87458	.83812
11	123,75000	8.72368	-.72224	1.08091	.04084	.23609	-.13492	-.08168	-.02545	0.00000	.94852	.83477
12	135,00000	8.72368	-.91924	.91924	.04112	.17544	-.17544	-.08224	-.02079	0.00000	.95795	.83344
13	146,25000	8.72368	-1.08091	.72224	.04084	.13492	-.23609	-.08168	-.02545	0.00000	.94852	.83477
14	157,50000	8.72368	-1.20104	.49749	.04001	.09365	-.37297	-.08002	-.06240	0.00000	.87458	.83812
15	168,75000	8.72368	-1.27502	.25362	.03686	.14709	-.51798	-.07744	-.03667	0.00000	.92583	.84357
16	180,00000	8.72368	-1.30000	.00000	.03685	.17544	-.03919	-.07370	-.02491	0.00000	.93950	.85090
17	191,25000	8.72368	-1.27502	-.25362	.03464	.11342	.13639	-.06929	-.09967	0.00000	.70837	.85983

Figure 6.- Continued.

18	202,50000	8.72368	-1.26104	.49749	.02133	.01531	.21115	-.06425	-.15486	0.00000	.68675	.87002
19	214,75000	8.72368	-1.08091	-.72224	.02439	-.04758	.21820	-.05879	-.18674	0.00000	.62223	.88108
20	225,00000	8.72368	-.91924	-.91924	.02655	-.17601	.17601	-.05310	-.19873	0.00000	.59797	.89257
21	236,25000	8.72368	-.72224	-1.08091	.02371	-.23410	.09954	-.04742	-.19480	0.00000	.68875	.90407
22	247,50000	8.72368	-.49749	-1.26104	.02098	-.25906	.00453	-.04195	-.17259	0.00000	.65086	.91513
23	258,75000	8.72368	-.25362	-1.27502	.01846	-.24186	-.09244	-.03692	-.13846	0.00000	.71989	.92531
24	270,00000	8.72368	.00000	-1.30000	.01625	-.18759	-.17544	-.03250	-.09467	0.00000	.80849	.93625
25	281,25000	8.72368	.25362	-1.27502	.01444	-.10449	-.23121	-.02888	-.04710	0.00000	.90472	.94157
26	292,50000	8.72368	.49749	-1.20104	.01309	-.00668	-.25088	-.02819	-.00372	0.00000	.99247	.94702
27	303,75000	8.72368	.72224	-1.08091	.01227	.09183	-.23132	-.02453	.02686	0.00000	1.05435	.95037
28	315,00000	8.72368	.91924	-.91924	.01199	.17544	-.17544	-.02397	.03792	0.00000	1.07671	.95151
29	326,25000	8.72368	1.08091	-.72224	.01227	.23132	-.09183	-.02453	.02686	0.00000	1.05435	.95037
30	337,50000	8.72368	1.26104	-.49749	.01309	.25088	.00668	-.02819	-.00372	0.00000	.99247	.94702
31	348,75000	8.72368	1.27502	-.25362	.01444	.24121	.10449	-.02888	-.04710	0.00000	.90472	.94157
32	360,00000	8.72368	1.30000	.00000	.01625	.17544	.18759	-.03250	-.09467	0.00000	.80849	.93625

BODY RING#

BODY NOSE SEPARATION AT XR/RH = 5.52485
 VORTEX STRENGTH GAMMA/(2*PI*RLUC*VINF) = .07701
 VORTEX Y/RLOC (UNROLLED COORDS) = .63679
 VORTEX Z/RLOC (UNROLLED COORDS) = 1.22147

RIGHT VORTEX STRENGTH GAMMA/(2*PI*RLUC*VINF) = .07701
 RIGHT VORTEX Y/RLOC (UNROLLED COORDS) = -.41343
 RIGHT VORTEX Z/RLOC (UNROLLED COORDS) = 1.31399
 LEFT VORTEX STRENGTH GAMMA/(2*PI*RLUC*VINF) = -.07701
 LEFT VORTEX Y/RLOC (UNROLLED COORDS) = -1.31399
 LEFT VORTEX Z/RLOC (UNROLLED COORDS) = .41343

1	11,25000	10.77632	1.27502	.25362	.01723	.09187	.24573	-.03446	-.13919	0.00000	.71841	.93030
2	22,50000	10.77632	1.26104	.49749	.01669	-.00614	.26294	-.03338	-.16925	0.00000	.65760	.93247
3	33,75000	10.77632	1.08091	.72224	.01611	-.10186	.23957	-.03222	-.18568	0.00000	.62437	.93482
4	45,00000	10.77632	.91924	.91924	.01550	-.17871	.17871	-.03101	-.18601	0.00000	.62371	.93727
5	56,25000	10.77632	.72224	1.08091	.01490	-.22080	.08452	-.02980	-.16797	0.00000	.68019	.93972
6	67,50000	10.77632	.49749	1.20104	.01432	-.21334	-.01441	-.02863	-.12885	0.00000	.73975	.94207
7	78,75000	10.77632	.25362	1.27502	.01378	-.15943	-.11281	-.02756	-.08501	0.00000	.80848	.94424
8	90,00000	10.77632	.00000	1.30000	.01331	-.02598	-.17544	-.02662	.01263	0.00000	1.02555	.94615
9	101,25000	10.77632	-.25362	1.27502	.01292	.27244	-.15615	-.02585	.02547	0.00000	1.05153	.94771
10	112,50000	10.77632	-.49749	1.20104	.01246	.34955	-.10333	-.02528	-.00024	0.00000	.99952	.94887
11	123,75000	10.77632	-.72224	1.08091	.01246	.24047	-.13199	-.02492	.03044	0.00000	1.06159	.94958
12	135,00000	10.77632	-.91924	.91924	.01240	.17544	-.17544	-.02480	.03706	0.00000	1.07497	.94982
13	146,25000	10.77632	-1.08091	.72224	.01298	.13199	-.24047	-.02492	.03044	0.00000	1.06159	.94958
14	157,50000	10.77632	-1.20104	.49749	.01264	.10333	-.34955	-.02528	-.00024	0.00000	1.07497	.94982
15	168,75000	10.77632	-1.27502	.25362	.01292	.15615	-.27244	-.02585	.02547	0.00000	1.05153	.94771
16	180,00000	10.77632	-1.30000	.00000	.01331	-.17544	-.02598	-.02662	.01263	0.00000	1.02555	.94615
17	191,25000	10.77632	-1.27502	-.25362	.01378	.11281	.13943	-.02756	-.06501	0.00000	.80848	.94424
18	202,50000	10.77632	-1.26104	.49749	.01432	.01441	.21334	-.02863	-.12885	0.00000	.73975	.94207
19	213,75000	10.77632	-1.08091	.72224	.01490	-.09932	.22080	-.02980	-.16797	0.00000	.68019	.93972
20	225,00000	10.77632	-.91924	.91924	.01550	-.17871	.17871	-.03101	-.18601	0.00000	.62371	.93727
21	236,25000	10.77632	-.72224	1.08091	.01611	-.23957	.10186	-.03222	-.18568	0.00000	.62437	.93482
22	247,50000	10.77632	-.49749	1.20104	.01669	-.26294	.00614	-.03338	-.16925	0.00000	.65760	.93247
23	258,75000	10.77632	-.25362	-1.27502	.01723	-.24573	-.09187	-.03446	-.13919	0.00000	.71841	.93030
24	270,00000	10.77632	.00000	-1.30000	.01770	-.19104	-.17544	-.03540	-.09925	0.00000	.79922	.92839
25	281,25000	10.77632	.25362	-1.27502	.01808	-.10759	-.23174	-.03617	-.05520	0.00000	.88833	.92683
26	292,50000	10.77632	.49749	-1.20104	.01847	-.00846	-.25162	-.03674	-.04473	0.00000	.97021	.92567

Figure 6.- Continued.

27	303.75000	10.77632	.72224	-1.08091	.01855	.09101	-.25186	-.03709	.01392	0.00000	1.02817	.92496
28	315.00000	10.77632	.91924	-.91924	.01861	.17544	-.17544	-.03721	.02430	0.00000	1.04914	.92472
29	326.25000	10.77632	1.08091	-.72224	.01855	.25186	-.09101	-.03709	.01392	0.00000	1.02817	.92496
30	337.50000	10.77632	1.20104	-.49749	.01857	.25162	.00846	-.03674	-.01473	0.00000	.97021	.92567
31	348.75000	10.77632	1.27502	-.25362	.01808	.25174	.10759	-.03617	-.05529	0.00000	.88433	.92683
32	360.00000	10.77632	1.30000	.00000	.01770	.17544	.18104	-.03540	-.04925	0.00000	.79922	.92839

HDDY PTNG= 7

HDDY NOISE SEPARATION AT XB/RB = 5.52485
 VORTEX STRENGTH GAMMA/(2*PI*R/LC*VINF) = .07893
 VORTEX Y/R/LC (UNROLLED COORDS) = .84087
 VORTEX Z/R/LC (UNROLLED COORDS) = 1.26800

RIGHT VORTEX STRENGTH GAMMA/(2*PI*R/LC*VINF) = .07691
 RIGHT VORTEX Y(ROLLED COORDS,)/R/LC = -.44345
 RIGHT VORTEX Z(ROLLED COORDS,)/R/LC = 1.34977
 LEFT VORTEX STRENGTH GAMMA/(2*PI*R/LC*VINF) = .07891
 LEFT VORTEX Y(ROLLED COORDS,)/R/LC = -1.34977
 LEFT VORTEX Z(ROLLED COORDS,)/R/LC = .44345

1	11.25000	12.82895	-1.27502	.25362	.01336	.09328	.23765	-.02672	-.12754	0.00000	.74199	.94594
2	22.50000	12.82895	1.20104	.49749	.01226	-.00257	.25433	-.02452	-.15614	0.00000	.68412	.95039
3	34.75000	12.82895	1.08091	.72224	.01107	-.09622	.23113	-.02210	-.17124	0.00000	.65359	.95522
4	45.00000	12.82895	.91924	.91924	.00983	-.17112	.17112	-.01965	-.17022	0.00000	.65544	.96074
5	56.25000	12.82895	.72224	1.08091	.00858	-.21166	.08321	-.01717	-.15079	0.00000	.69495	.96527
6	67.50000	12.82895	.49749	1.20104	.00739	-.20346	-.01850	-.01478	-.11026	0.00000	.77695	.97010
7	78.75000	12.82895	.25362	1.27502	.00629	-.18127	-.11444	-.01258	-.04674	0.00000	.86544	.97455
8	90.00000	12.82895	.00000	1.30000	.00533	-.07363	-.17544	-.01065	-.02799	0.00000	1.05663	.97845
9	101.25000	12.82895	-.25362	1.27502	.00454	.24321	-.16196	-.00907	.04810	0.00000	1.09731	.98165
10	112.50000	12.82895	-.49749	1.20104	.00395	.32994	-.11145	-.00790	.02477	0.00000	1.05012	.98403
11	123.75000	12.82895	-.72224	1.08091	.00359	.24358	-.12992	-.00717	.04813	0.00000	1.09731	.98549
12	135.00000	12.82895	-.91924	.91924	.00346	.17544	-.17544	-.00693	.05564	0.00000	1.11264	.98599
13	146.25000	12.82895	-1.08091	.72224	.00359	.12992	-.24358	-.00717	.04813	0.00000	1.09731	.98549
14	157.50000	12.82895	-1.20104	.49749	.00395	.11145	-.32994	-.00790	.02477	0.00000	1.05012	.98403
15	168.75000	12.82895	-1.27502	.25362	.00454	.16196	-.24321	-.00907	.04810	0.00000	1.09731	.98165
16	180.00000	12.82895	-1.30000	.00000	.00533	.17544	-.07363	-.01065	.02799	0.00000	1.05663	.97845
17	191.25000	12.82895	-1.27502	-.25362	.00629	.11444	.18127	-.01258	-.04674	0.00000	.90544	.97455
18	202.50000	12.82895	-1.20104	.49749	.00739	.01850	.20346	-.01478	-.11026	0.00000	.77695	.97010
19	214.75000	12.82895	-1.08091	.72224	.00858	.08321	.21166	-.01717	-.15079	0.00000	.69495	.96527
20	225.00000	12.82895	-.91924	.91924	.00983	-.17112	.17112	-.01965	-.17022	0.00000	.65544	.96074
21	236.25000	12.82895	-.72224	1.08091	.01107	-.23113	.09622	-.02210	-.17124	0.00000	.65359	.95522
22	247.50000	12.82895	-.49749	1.20104	.01226	-.25433	.00257	-.02452	-.15614	0.00000	.68412	.95039
23	258.75000	12.82895	-.25362	1.27502	.01336	-.23765	-.09328	-.02672	-.12754	0.00000	.74199	.94594
24	270.00000	12.82895	.00000	1.30000	.01433	-.18411	-.17544	-.02865	-.08923	0.00000	.81948	.94204
25	281.25000	12.82895	.25362	1.27502	.01512	-.10230	-.24069	-.03023	-.04694	0.00000	.94503	.93844
26	292.50000	12.82895	.49749	1.20104	.01570	-.00504	-.25020	-.03141	-.04813	0.00000	.98356	.93466
27	303.75000	12.82895	.72224	1.08091	.01607	.09257	-.23082	-.03213	-.01932	0.00000	1.03909	.93499
28	315.00000	12.82895	.91924	.91924	.01619	.17544	-.17544	-.03238	-.02925	0.00000	1.05918	.93459
29	326.25000	12.82895	1.08091	.72224	.01607	.25082	-.09257	-.03213	-.01932	0.00000	1.03909	.93499
30	337.50000	12.82895	1.20104	.49749	.01570	.25020	.00504	-.03141	-.04813	0.00000	.98356	.93466
31	348.75000	12.82895	1.27502	-.25362	.01512	.23069	.10230	-.03023	-.04694	0.00000	.94503	.93844
32	360.00000	12.82895	1.30000	.00000	.01433	.17544	.18411	-.02865	-.08923	0.00000	.81948	.94204

Figure 6.- Continued.

BODY NOSE SEPARATION AT XB/RH = 5.52485
 VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = .08082
 VORTEX Y/RLOC (UNROLLED COORDS) = .64591
 VORTEX Z/RLOC (UNROLLED COORDS) = 1.31453

RIGHT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = .08082
 RIGHT VORTEX Y(ROLLED COORDS,)/RLOC = -.47279
 RIGHT VORTEX Z(ROLLED COORDS,)/RLOC = 1.38624
 LEFT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = -.08082
 LEFT VORTEX Y(ROLLED COORDS,)/RLOC = -1.38624
 LEFT VORTEX Z(ROLLED COORDS,)/RLOC = .47279

1	11.25000	14.88158	1.27502	.25362	.00091	.09490	.22946	-.01855	-.11532	0.00000	.76670	.96247
2	22.50000	14.88158	1.20104	.49749	.00000	.00103	.24562	-.01691	-.14371	0.00000	.70927	.96579
3	33.75000	14.88158	1.08091	.72224	.00757	-.09054	.22262	-.01513	-.15873	0.00000	.67888	.96939
4	45.00000	14.88158	.91924	.91924	.00664	-.16351	.16351	-.01328	-.15776	0.00000	.68004	.97314
5	56.25000	14.88158	.72224	1.08091	.00571	-.20255	.07712	-.01143	-.13858	0.00000	.71965	.97689
6	67.50000	14.88158	.49749	1.20104	.00482	-.19377	-.02251	-.00964	-.09890	0.00000	.79993	.98049
7	78.75000	14.88158	.25362	1.27502	.00400	-.12339	-.11600	-.00800	-.03793	0.00000	.92326	.98381
8	90.00000	14.88158	.00000	1.30000	.00328	.02217	-.17544	-.00656	.03169	0.00000	1.06410	.98672
9	101.25000	14.88158	-.25362	1.27502	.00249	.22012	-.16656	-.00538	.05492	0.00000	1.11111	.98911
10	112.50000	14.88158	-.49749	1.20104	.00225	.31040	-.11955	-.00451	.03517	0.00000	1.07114	.99089
11	123.75000	14.88158	-.72224	1.08091	.00198	.24356	-.12993	-.00397	.05147	0.00000	1.10412	.99198
12	135.00000	14.88158	-.91924	.91924	.00180	.17544	-.17544	-.00378	.05899	0.00000	1.11933	.99235
13	146.25000	14.88158	-1.08091	.72224	.00198	.12993	-.24356	-.00397	.05147	0.00000	1.10412	.99198
14	157.50000	14.88158	-1.20104	.49749	.00225	.11955	-.31040	-.00451	.03517	0.00000	1.10412	.99198
15	168.75000	14.88158	-1.27502	.25362	.00249	.16656	-.22012	-.00538	.05492	0.00000	1.11111	.98911
16	180.00000	14.88158	-1.30000	.00000	.00328	.17544	-.02217	-.00656	.03169	0.00000	1.06410	.98672
17	191.25000	14.88158	-1.27502	-.25362	.00400	.11600	.12339	-.00800	-.03793	0.00000	.92326	.98381
18	202.50000	14.88158	-1.20104	-.49749	.00482	.02251	.19377	-.00964	-.09890	0.00000	.79993	.98049
19	213.75000	14.88158	-1.08091	-.72224	.00571	-.07712	.20255	-.01143	-.13858	0.00000	.71965	.97689
20	225.00000	14.88158	-.91924	-.91924	.00664	-.16351	.16351	-.01328	-.15776	0.00000	.68004	.97314
21	236.25000	14.88158	-.72224	-1.08091	.00757	-.22262	.09054	-.01513	-.15873	0.00000	.67888	.96939
22	247.50000	14.88158	-.49749	-1.20104	.00846	-.24562	-.00103	-.01691	-.14371	0.00000	.70927	.96579
23	258.75000	14.88158	-.25362	-1.27502	.00924	-.22962	-.09490	-.01855	-.11532	0.00000	.76670	.96247
24	270.00000	14.88158	.00000	-1.30000	.01000	-.17709	-.17544	-.01999	-.07743	0.00000	.84337	.95956
25	281.25000	14.88158	.25362	-1.27502	.01099	-.09693	-.22962	-.02117	-.03571	0.00000	.92775	.95717
26	292.50000	14.88158	.49749	-1.20104	.01182	-.00157	-.24877	-.02295	.00247	0.00000	1.00500	.95539
27	303.75000	14.88158	.72224	-1.08091	.01139	.09416	-.22976	-.02259	.02942	0.00000	1.05952	.95430
28	315.00000	14.88158	.91924	-.91924	.01139	.17544	-.17544	-.02277	.03916	0.00000	1.10922	.95393
29	326.25000	14.88158	1.08091	-.72224	.01130	.22976	-.09416	-.02249	.02942	0.00000	1.05952	.95430
30	337.50000	14.88158	1.20104	-.49749	.01102	.24877	.00157	-.02205	.00247	0.00000	1.00500	.95539
31	348.75000	14.88158	1.27502	-.25362	.01059	.22962	.09693	-.02117	-.03571	0.00000	.92775	.95717
32	360.00000	14.88158	1.30000	.00000	.01000	.17544	.17709	-.01999	-.07743	0.00000	.84337	.95956

BODY RING 9

BODY NOSE SEPARATION AT XB/RH = 5.52485
 VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = .08272
 VORTEX Y/RLOC (UNROLLED COORDS) = .65095
 VORTEX Z/RLOC (UNROLLED COORDS) = 1.36106

Figure 6.- Continued.

5	56.25000	18.98684	.72224	1.08091	.00427	-.19196	.07004	-.00653	-.12567	0.00000	.74577	.98678
6	67.50000	18.98684	.49749	1.20104	.00304	-.18211	-.02734	-.00609	-.08742	0.00000	.82315	.98764
7	78.75000	18.98684	.25362	1.27502	.00284	-.11411	-.11785	-.00568	-.03043	0.00000	.93844	.98851
8	90.00000	18.98684	.00000	1.30000	.00264	-.01843	-.17544	-.00532	-.03175	0.00000	1.06423	.98924
9	101.25000	18.98684	-.25362	1.27502	.00244	.18801	-.17295	-.00503	.05746	0.00000	1.11625	.98943
10	112.50000	18.98684	-.49749	1.20104	.00224	.27961	-.13230	-.00481	.04404	0.00000	1.08910	.99028
11	123.75000	18.98684	-.72224	1.08091	.00204	.24039	-.13205	-.00467	.05139	0.00000	1.10397	.99055
12	135.00000	18.98684	-.91924	.91924	.00231	.17544	-.17544	-.00463	.05810	0.00000	1.11754	.99064
13	146.25000	18.98684	-1.08091	.72224	.00234	.13205	-.24039	-.00467	.05139	0.00000	1.10397	.99055
14	157.50000	18.98684	-1.20104	.49749	.00240	.13230	-.27961	-.00481	.04404	0.00000	1.08910	.99028
15	168.75000	18.98684	-1.27502	.25362	.00251	.17295	-.18801	-.00503	.05746	0.00000	1.11625	.98943
16	180.00000	18.98684	-1.30000	.00000	.00264	.17544	-.01843	-.00532	.03175	0.00000	1.06423	.98924
17	191.25000	18.98684	-1.27502	-.25362	.00284	.11785	.11411	-.00568	-.03043	0.00000	.93844	.98851
18	202.50000	18.98684	-1.20104	-.49749	.00304	.02734	.18211	-.00609	-.08742	0.00000	.82315	.98768
19	213.75000	18.98684	-1.08091	-.72224	.00327	-.07004	.19196	-.00653	-.12567	0.00000	.74577	.98678
20	225.00000	18.98684	-.91924	-.91924	.00350	-.15498	.15498	-.00700	-.14030	0.00000	.70809	.98580
21	236.25000	18.98684	-.72224	-1.08091	.00373	-.21339	.08436	-.00746	-.14494	0.00000	.70679	.98491
22	247.50000	18.98684	-.49749	-1.20104	.00395	-.23640	-.00485	-.00791	-.12464	0.00000	.73774	.98401
23	258.75000	18.98684	-.25362	-1.27502	.00416	-.22095	-.09640	-.00832	-.10104	0.00000	.79560	.98318
24	270.00000	18.98684	.00000	-1.30000	.00434	-.16949	-.17544	-.00867	-.06304	0.00000	.87247	.98245
25	281.25000	18.98684	.25362	-1.27502	.00448	-.09147	-.22854	-.00897	-.02137	0.00000	.95677	.98185
26	292.50000	18.98684	.49749	-1.20104	.00459	.00193	-.24732	-.00919	.01666	0.00000	1.03371	.98141
27	303.75000	18.98684	.72224	-1.08091	.00466	.64575	-.22869	-.00932	.04345	0.00000	1.08790	.98114
28	315.00000	18.98684	.91924	-.91924	.00468	.17544	-.17544	-.00937	.05312	0.00000	1.10746	.98105
29	326.25000	18.98684	1.08091	-.72224	.00466	.22869	-.09575	-.00932	.04345	0.00000	1.08790	.98114
30	337.50000	18.98684	1.20104	-.49749	.00459	.24732	-.00193	-.00919	.01666	0.00000	1.03371	.98141
31	348.75000	18.98684	1.27502	-.25362	.00448	.22854	.09147	-.00897	-.02137	0.00000	.95677	.98185
32	360.00000	18.98684	1.30000	.00000	.00434	.17544	.16989	-.00867	-.06304	0.00000	.87247	.98245

TOTAL NUMBER OF PRESSURE POINTS, JCPT= 428

CONTROL POINT COORDINATES FOR 3 CHORDWISE BY 5 SPANWISE PANELS ON WING 1 OR 4, 5 SPANWISE PANELS ON WING 2 OR L AND 5 SPANWISE PANELS ON WING 3 OR U, 5 SPANWISE ON WING 4 OR D

J	X(J)	Y(J)	Z(J)	RU(J)	HV(J)	RW(J)	VVRTX	WVRTX
1	1.25112	1.53096	0.00000	.30415E-02	.12609E+00	.12789E+00	0.	0.
2	2.38667	1.53096	0.00000	.25419E-02	.12617E+00	.12768E+00	0.	0.
3	3.54222	1.53096	0.00000	.22035E-02	.12622E+00	.12755E+00	0.	0.
4	1.41565	1.99870	0.00000	.30173E-02	.73266E-01	.75357E-01	0.	0.
5	2.48119	1.99870	0.00000	.25478E-02	.73455E-01	.75200E-01	0.	0.
6	3.54672	1.99870	0.00000	.22281E-02	.73581E-01	.75098E-01	0.	0.
7	1.60017	2.46640	0.00000	.30518E-02	.47405E-01	.49788E-01	0.	0.
8	2.57570	2.46640	0.00000	.26235E-02	.47650E-01	.49633E-01	0.	0.
9	1.55122	2.46640	0.00000	.22924E-02	.47877E-01	.49541E-01	0.	0.
10	1.78486	2.93403	0.00000	.31062E-02	.32808E-01	.35417E-01	0.	0.
11	2.67019	2.93403	0.00000	.26945E-02	.33091E-01	.35293E-01	0.	0.
12	3.55572	2.93403	0.00000	.23729E-02	.33299E-01	.35206E-01	0.	0.
13	1.96912	3.40158	0.00000	.32017E-02	.23701E-01	.24577E-01	0.	0.
14	2.76467	3.40158	0.00000	.28079E-02	.24011E-01	.24461E-01	0.	0.
15	3.56022	3.40158	0.00000	.24715E-02	.24266E-01	.24377E-01	0.	0.
16	1.25112	-1.53096	0.00000	.25333E-02	.12635E+00	.12789E+00	0.	0.
17	2.38667	-1.53096	0.00000	.21254E-02	.12648E+00	.12788E+00	0.	0.
18	3.54222	-1.53096	0.00000	.19174E-02	.12640E+00	.12754E+00	0.	0.
19	1.41565	-1.99870	0.00000	.22883E-02	.73472E-01	.75357E-01	0.	0.
20	2.48119	-1.99870	0.00000	.21091E-02	.74042E-01	.75200E-01	0.	0.

Figure 6.- Continued.

21	3.54672	-1.9987	0.0000	.19229E+02	.74077E+01	.75098E+01	0.	0.
22	1.60017	-2.46640	0.0000	.21940E+02	.48455E+01	.49768E+01	0.	0.
23	2.57570	-2.46640	0.0000	.20524E+02	.48538E+01	.49633E+01	0.	0.
24	3.55122	-2.46640	0.0000	.18949E+02	.48586E+01	.49541E+01	0.	0.
25	1.78466	-2.93403	0.0000	.21408E+02	.34196E+01	.35417E+01	0.	0.
26	2.67019	-2.93403	0.0000	.20174E+02	.34274E+01	.35291E+01	0.	0.
27	3.55572	-2.93403	0.0000	.18423E+02	.34317E+01	.35206E+01	0.	0.
28	1.96912	-3.40158	0.0000	.20349E+02	.25363E+01	.26577E+01	0.	0.
29	2.76467	-3.40158	0.0000	.19547E+02	.25464E+01	.26441E+01	0.	0.
30	3.56022	-3.40158	0.0000	.18804E+02	.25558E+01	.26377E+01	0.	0.
31	1.23112	0.0000	1.53096	.23343E+02	-.12789E+00	-.12635E+00	0.	0.
32	2.38667	0.0000	1.53096	.21254E+02	-.12789E+00	-.12635E+00	0.	0.
33	3.54222	0.0000	1.53096	.19174E+02	-.12755E+00	-.12640E+00	0.	0.
34	1.41565	0.0000	1.99870	.22884E+02	-.75357E+01	-.73972E+01	0.	0.
35	2.48119	0.0000	1.99870	.21091E+02	-.75200E+01	-.74022E+01	0.	0.
36	3.54872	0.0000	1.99870	.19229E+02	-.75098E+01	-.74077E+01	0.	0.
37	1.60017	0.0000	2.46640	.21940E+02	-.49768E+01	-.49633E+01	0.	0.
38	2.57570	0.0000	2.46640	.20524E+02	-.49633E+01	-.49538E+01	0.	0.
39	3.55122	0.0000	2.46640	.18949E+02	-.49541E+01	-.49586E+01	0.	0.
40	1.78466	0.0000	2.93403	.21408E+02	-.35417E+01	-.34196E+01	0.	0.
41	2.67019	0.0000	2.93403	.20174E+02	-.35291E+01	-.34274E+01	0.	0.
42	3.55572	0.0000	2.93403	.18423E+02	-.35206E+01	-.34317E+01	0.	0.
43	1.96912	0.0000	3.40158	.20349E+02	-.26577E+01	-.25363E+01	0.	0.
44	2.76467	0.0000	3.40158	.19547E+02	-.26461E+01	-.25464E+01	0.	0.
45	3.56022	0.0000	3.40158	.18804E+02	-.26377E+01	-.25558E+01	0.	0.
46	1.23112	0.0000	-1.53096	.30415E+02	-.12789E+00	-.12608E+00	0.	0.
47	2.38667	0.0000	-1.53096	.28419E+02	-.12789E+00	-.12617E+00	0.	0.
48	3.54222	0.0000	-1.53096	.22034E+02	-.12755E+00	-.12622E+00	0.	0.
49	1.41565	0.0000	-1.99870	.30113E+02	-.75357E+01	-.74266E+01	0.	0.
50	2.48119	0.0000	-1.99870	.28678E+02	-.75200E+01	-.73453E+01	0.	0.
51	3.54872	0.0000	-1.99870	.22281E+02	-.75098E+01	-.73581E+01	0.	0.
52	1.60017	0.0000	-2.46640	.30518E+02	-.49768E+01	-.47405E+01	0.	0.
53	2.57570	0.0000	-2.46640	.28235E+02	-.49633E+01	-.47654E+01	0.	0.
54	3.55122	0.0000	-2.46640	.22924E+02	-.49541E+01	-.47827E+01	0.	0.
55	1.78466	0.0000	-2.93403	.31062E+02	-.35417E+01	-.32818E+01	0.	0.
56	2.67019	0.0000	-2.93403	.26945E+02	-.35291E+01	-.33041E+01	0.	0.
57	3.55572	0.0000	-2.93403	.23729E+02	-.35206E+01	-.33249E+01	0.	0.
58	1.96912	0.0000	-3.40158	.32017E+02	-.26577E+01	-.23701E+01	0.	0.
59	2.76467	0.0000	-3.40158	.28029E+02	-.26461E+01	-.24011E+01	0.	0.
60	3.56022	0.0000	-3.40158	.24715E+02	-.26377E+01	-.24268E+01	0.	0.

CENTRAL POINT COORDINATES FOR HIP-9 (WING FRAME)

J	X(J)	Y(J)	Z(J)	THU(J)	THV(J)	THW(J)
61	1.14000	1.25052	.24874	-.13891E+02	-.18221E+01	.34655E+02
62	1.14000	1.06014	.70836	-.15717E+01	-.88792E+02	.20553E+01
63	1.14000	.70836	1.06014	-.15717E+01	.20553E+01	-.88792E+02
64	1.14000	.24874	1.25052	-.13891E+02	.34655E+02	-.18221E+01
65	1.14000	-.24874	1.25052	-.13891E+02	-.34655E+02	-.18221E+01
66	1.14000	-.70836	1.06014	-.15717E+01	-.20553E+01	-.88792E+02
67	1.14000	-1.06014	.70836	-.15717E+01	.88792E+02	.20553E+01
68	1.14000	-1.25052	.24874	-.13891E+02	-.18221E+01	.34655E+02
69	1.14000	-1.25052	-.24874	-.13891E+02	.18221E+01	-.34655E+02
70	1.14000	-1.06014	-.70836	-.15717E+01	.88792E+02	-.20553E+01

Figure 6.- Continued.

71	1.14000	-.70846	-1.06014	-.15717E-01	-.20553E-01	.8A792E-02
72	1.14000	-.24874	-1.25052	-.13401E-02	-.10645E-02	.1A221E-01
73	1.14000	.24874	-1.25052	-.13401E-02	.10645E-02	.1A221E-01
74	1.14000	.70846	-1.06014	-.15717E-01	-.20553E-01	.8A792E-02
75	1.14000	1.06014	-.70846	-.15717E-01	-.20553E-01	.8A792E-02
76	1.14000	1.25052	-.24874	-.13401E-02	-.10645E-02	.1A221E-01
77	2.34000	1.25052	.24874	-.10617E-01	-.8A355E-02	.4A345E-02
78	2.34000	1.06014	.70836	-.22211E-01	-.16042E-01	.6A216E-02
79	2.34000	.70836	1.06014	-.22211E-01	-.16042E-01	.6A216E-02
80	2.34000	-.24874	1.25052	-.10617E-01	-.8A355E-02	.4A345E-02
81	2.34000	-.24874	1.25052	-.10617E-01	-.8A355E-02	.4A345E-02
82	2.34000	-.70836	1.06014	-.22211E-01	-.16042E-01	.6A216E-02
83	2.34000	-1.06014	.70836	-.22211E-01	-.16042E-01	.6A216E-02
84	2.34000	-1.25052	.24874	-.10617E-01	-.8A355E-02	.4A345E-02
85	2.34000	-1.25052	.24874	-.10617E-01	-.8A355E-02	.4A345E-02
86	2.34000	-1.06014	-.70836	-.22211E-01	-.16042E-01	.6A216E-02
87	2.34000	-.70836	-1.06014	-.22211E-01	-.16042E-01	.6A216E-02
88	2.34000	-.24874	-1.25052	-.10617E-01	-.8A355E-02	.4A345E-02
89	2.34000	.24874	-1.25052	-.10617E-01	-.8A355E-02	.4A345E-02
90	2.34000	.70836	-1.06014	-.22211E-01	-.16042E-01	.6A216E-02
91	2.34000	1.06014	-.70836	-.22211E-01	-.16042E-01	.6A216E-02
92	2.34000	1.25052	-.24874	-.10617E-01	-.8A355E-02	.4A345E-02
93	3.54000	1.25052	.24874	-.20323E-01	-.26782E-01	.54507E-01
94	3.54000	1.06014	.70836	-.22241E-01	-.11295E-01	.6A311E-02
95	3.54000	.70836	1.06014	-.22241E-01	-.11295E-01	.6A311E-02
96	3.54000	-.24874	1.25052	-.20323E-01	-.26782E-01	.54507E-01
97	3.54000	-.24874	1.25052	-.20323E-01	-.26782E-01	.54507E-01
98	3.54000	-.70836	1.06014	-.22241E-01	-.11295E-02	.6A311E-02
99	3.54000	-1.06014	.70836	-.22241E-01	-.11295E-01	.6A311E-02
100	3.54000	-1.25052	.24874	-.20323E-01	-.26782E-01	.54507E-01
101	3.54000	-1.25052	.24874	-.20323E-01	-.26782E-01	.54507E-01
102	3.54000	-1.06014	-.70836	-.22241E-01	-.11295E-01	.6A311E-02
103	3.54000	-.70836	-1.06014	-.22241E-01	-.11295E-02	.6A311E-02
104	3.54000	-.24874	-1.25052	-.20323E-01	-.26782E-01	.54507E-01
105	3.54000	.24874	-1.25052	-.20323E-01	-.26782E-01	.54507E-01
106	3.54000	.70836	-1.06014	-.22241E-01	-.11295E-02	.6A311E-02
107	3.54000	1.06014	-.70836	-.22241E-01	-.11295E-01	.6A311E-02
108	3.54000	1.25052	-.24874	-.20323E-01	-.26782E-01	.54507E-01

LOADING INFORMATION

MACH NUMBER = .17000E+01
 ANGLE OF ATTACK = 10.000 DEGREES
 SIDE SLIP ANGLE = 10.000 DEGREES
 WING AREA = 13.04000
 REFERENCE AREA = 4.30000
 REFERENCE LENGTH = 2.60000
 EXPOSED WING SPAN = 2.60000
 MOMENT CENTER X = 12.50000
 Z = 0.00000

WING TYPE LOADING PRESSURE

OFFL. ANGLE DEG. =	TOTAL	FIN 1 OR R	FIN 2 OR L	FIN 3 OR U	FIN 4 OR D	INTERF. SPFL
		0.00000	0.00000	0.00000	0.00000	
CTMR =	.43232E+01	.15958E+01	.15958E+01	.15958E+01	.15958E+01	
CZ =	.15749E+01	.66031E+00	.66031E+00	0.	0.	.25832E+00
CY =	-.15749E+01	0.	0.	-.66031E+00	-.66031E+00	-.25832E+00
CM =	-.15743E+01	-.64660E+00	-.64660E+00	0.	0.	-.28518E+00
CLN =	.15743E+01	0.	0.	.64660E+00	.64660E+00	.28518E+00
CLL =	.17047E+14	-.57494E+00	.57494E+00	-.57494E+00	.57494E+00	.24098E-15

FOLLOWING ARE IN WIND-AXIS SYSTEM

CI =	.21813E+01	.45653E+00	.45653E+00	.45653E+00	.45653E+00	.35414E+00
CY-IND =	.76117E+12	.46691E+00	.46691E+00	-.46691E+00	-.46691E+00	.72387E-12
COI =	.48649E+00	.99193E-01	.99193E-01	.99193E-01	.99193E-01	.89715E-01
COI/CL*P =	.10234E+00					
CM-IND =	-.22321E+01	-.45721E+00	-.45721E+00	-.45721E+00	-.45721E+00	-.40328E+00
CLN-IND =	-.67146E-12	-.30202E+00	-.58440E+00	-.58440E+00	.30202E+00	-.61640E-12

NOTE: L.E. OF LEAD PANEL IN FIRST CHORDWISE ROW IS SUPERSONIC

-----RIGHT WING-----

SPACIALISE DISTRIBUTIONS

I	Y/(R/2)	CH+C/(2AR)	CT+C/(2AR)	CY+C/(2AR)	CYINT+C/(2AR)	CS+C/(2AR)	CSINT	VBAR	GAMMAET(1)	GAMMA,LE/VINF	XL
1	.65426	.18934	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.88666	0.00000	.13334
2	.85415	.18692	0.00000	0.00000	.00266	0.00000	0.00000	0.00000	.01136	0.00000	.40340
3	1.05402	.17349	0.00000	0.00000	.00215	0.00000	0.00000	0.00000	.06091	0.00000	.67342
4	1.25346	.14734	0.00000	0.00000	.00205	0.00000	0.00000	0.00000	.12540	0.00000	.94341
5	1.45367	.10536	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.20592	0.00000	1.21335
6	1.55554	0.00000							.48294		

SUMFX = 0.
SUMFY1 = 0.
SUMFY2 = .50439E+02
SUMFT2 = .27045E+01

Figure 6.- Continued

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SUCTION FORCE PER UNIT LENGTH / (0.1 TIPCHORD)	GAMMA,RE / VINF	YBAR	XSE
1	1	.33333	.00307	.00054	3.64000	1.35100
2	2	.66667	.03561	.00696	3.64000	2.10067
3	3	1.00000	.04649	.01511	3.64000	2.85033

***** FIN VORTEX INFO*****

IVRT GAMMA/VINF Y.C.G.

1 .88621 3.27795

----- LEFT WING-----

SPANWISE DISTRIBUTIONS

I	Y/(H/2)	CW/C/(2*B)	CL/C/(2*B)	CV1/C/(2*B)	CVTOT/C/(2*B)	CS/C/(2*B)	CSTNT	YBAR	GAMNET(I)	GAMMA,LE/VINF	XLE
7	-.65476	.18946	0.00000	0.00000	-.00040	0.00000	0.00000	0.00000	.88666	0.00000	.13330
8	-.85415	.18692	0.00000	0.00000	-.00266	0.00000	0.00000	0.00000	-.01154	0.00000	.40340
9	-1.05402	.17489	0.00000	0.00000	-.00215	0.00000	0.00000	0.00000	-.06091	0.00000	.67342
10	-1.25386	.14706	0.00000	0.00000	-.00205	0.00000	0.00000	0.00000	-.12554	0.00000	.94341
11	-1.45367	.10308	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.20592	0.00000	1.21335
12	-1.65354	0.00000							-.48293		

SUMFX = 0.
 SUMFY1 = 0.
 SUMFY2 = -.59819E+02
 SUMFT2 = -.27045E+01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SUCTION FORCE PER UNIT LENGTH / (0.1 TIPCHORD)	GAMMA,RE / VINF	YBAR	XSE
1	1	.33333	-.00407	-.00054	-3.64000	1.35100
2	2	.66667	-.03561	-.00696	-3.64000	2.10067
3	3	1.00000	-.04649	-.01511	-3.64000	2.85033

Figure 6.- Continued.

****E. FIN VORTEX INFO****

IVRT GAMMA/VINE Y.C.G.

2 .AR621 =3.27795

-----UPPER WING-----

SPANWISE DISTRIBUTIONS

I	Z/(B/2)	C1+C/(2*B)	C1+C/(2*B)	C21+C/(2*B)	C2TOT+C/(2*B)	C3+C/(2*B)	CSINT	ZBAR	GAMMA(1)	GAMMA,LF/VINE	XLF
13	.65426	.18936	0.00000	0.00000	.00000	0.00000	0.00000	0.00000	.AR621	0.00000	.13334
14	.85415	.18692	0.00000	0.00000	.00226	0.00000	0.00000	0.00000	.01136	0.00000	.20340
15	1.05402	.17389	0.00000	0.00000	.00215	0.00000	0.00000	0.00000	.06091	0.00000	.67342
16	1.25396	.14706	0.00000	0.00000	.00265	0.00000	0.00000	0.00000	.12554	0.00000	.94341
17	1.45367	.10308	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.20592	0.00000	1.21335
18	1.55556	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.49293		

SUMFX = 0.
 SUMFZ1 = 0.
 SUMFZ2 = .59839E-02
 SUMFT2 = .27045E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SECTION FORCE PER UNIT LENGTH / (0.5TIPCHORD)	GAMMA,SE / VINE	ZBAR	XSE
1	4	.33333	.00307	.00054	3.64000	1.35100
2	5	.66667	.03561	.00696	3.64000	2.10067
3	6	1.00000	.00649	.01511	3.64000	2.95033

****E. FIN VORTEX INFO****

IVRT GAMMA/VINE Z.C.G.

3 .AR621 3.27795

Figure 6.- Continued.

-----LOWER WING-----

SPANWISE DISTRIBUTIONS

I	Z/(R/2)	CN*C/(2*B)	CT*C/(2*B)	CZ1*C/(2*B)	CZTOT*C/(2*B)	CS*C/(2*B)	CSINT	ZBAR	GAMMA(I)	GAMMA,LE/VINF	XLE
19	-.65426	.18936	0.00000	0.00000	-.00040	0.00000	0.00000	0.00000	.88666	0.00000	.13554
20	-.85415	.18692	0.00000	0.00000	-.00246	0.00000	0.00000	0.00000	-.01136	0.00000	.46340
21	-1.25402	.17349	0.00000	0.00000	-.00215	0.00000	0.00000	0.00000	-.06091	0.00000	.67542
22	-1.25386	.14706	0.00000	0.00000	-.00205	0.00000	0.00000	0.00000	-.12554	0.00000	.94341
23	-1.45367	.10498	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.20592	0.00000	1.21355
24	-1.55556	0.00000							-.48293		

SUMFY = 0.
 SUMFZ1 = 0.
 SUMFZ2 = -.59839E+02
 SUMFY2 = -.27045E+01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SECTION FORCE PER UNIT LENGTH / (Q*TIPCHORD)	GAMMA,SE / VINF	ZBAR	XRE
1	7	.43343	-.00307	-.00054	-3.64000	1.35100
2	8	.66667	-.03561	-.00686	-3.64000	2.10067
3	9	1.00000	-.04649	-.01511	-3.64000	2.85033

****E. FIN VORTEX INFO****

IVRT GAMMA/VINF Z,C.S.

4 =.88621 =3.27795

VELOCITIES AND REYNOLDS PRESSURES AT CONTINUOUS POINTS IMMEDIATELY ABOVE AND BELOW HORIZONTAL WING SURFACE

J	X(J)	Y(J)	Z(J)	UTOTA	VTOTA	WTOTA	PRESSA	UTOTH	VTOTH	WTOTH	PRESSB
1	1.231118	1.530959	0.000000	.150107	-.0009157	-.173650	-.232106	-.186636	.185261	-.173650	.507944
2	2.386670	1.530959	0.000000	.129322	.070070	-.173650	-.185694	-.119079	.165680	-.173650	.336862
3	1.542222	1.530959	0.000000	.113465	.148769	-.173650	-.167160	-.068697	.203827	-.032650	.189374
4	1.415654	1.998701	0.000000	.251532	-.157014	-.173650	-.178470	-.111513	.072591	-.173650	.363894
5	2.481188	1.998701	0.000000	.130365	.023599	-.173650	-.195638	-.150795	.124119	-.173650	.362347

Figure 6.- Continued.

4	3.546723	1.994701	0.000000	1.145735	1.24139	-.314650	-.218475	-.051527	.158102	-.032650	.151421
7	1.600170	2.466397	0.000000	1.76868	-.019452	-.173650	-.275450	-.179328	.186197	-.173650	.489158
8	2.575697	2.466397	0.000000	1.67531	-.001452	-.173650	-.254622	-.118118	.108495	-.173650	.328461
9	3.551224	2.466397	0.000000	2.57271	.088465	-.314650	-.337191	.044207	.125403	-.032650	-.047964
10	1.784662	2.934030	0.000000	1.84450	-.031710	-.173650	-.274223	-.158442	.144180	-.173650	-.032650
11	2.671193	2.934030	0.000000	1.98584	-.055507	-.173650	-.305871	-.086151	.054054	-.173650	.217995
12	3.555723	2.934030	0.000000	1.17778	.294844	-.314650	-.184044	-.040092	.059098	-.032650	.102817
13	1.969121	3.401580	0.000000	1.26247	.042307	-.173650	-.185437	-.173276	.215247	-.173650	.470855
14	2.784672	3.401580	0.000000	1.41750	.018390	-.173650	-.134517	-.099502	.002003	-.173650	.279028
15	3.546222	3.401580	0.000000	2.12912	-.063427	-.173650	-.333054	-.096642	.000951	-.032650	-.174457
16	1.231118	-1.530959	0.000000	1.52074	.265202	-.173650	-.214753	-.184670	.070784	-.173650	.485702
17	2.386670	-1.530959	0.000000	1.22868	.178460	-.173650	-.167575	-.125543	.081251	-.173650	.340432
18	3.542222	-1.530959	0.000000	2.28762	.162443	-.314650	-.324682	.046600	.127406	-.032650	-.052137
19	1.415654	-1.998701	0.000000	2.54058	.288444	-.173650	-.348754	-.108487	.079299	-.173650	.299437
20	2.481188	-1.998701	0.000000	1.46320	.146320	-.173650	-.205016	-.114838	.045543	-.173650	.303185
21	3.546723	-1.998701	0.000000	2.34443	.125737	-.314650	-.316291	.041221	.047774	-.032650	-.046644
22	1.600170	-2.466397	0.000000	1.74014	.145310	-.173650	-.248710	-.140142	.070349	-.173650	.507340
23	2.575697	-2.466397	0.000000	1.70160	.102179	-.173650	-.242750	-.115489	-.007767	-.173650	.281734
24	3.551224	-2.466397	0.000000	2.42287	.015453	-.314650	-.340987	.049313	-.021485	-.032650	-.089321
25	1.784662	-2.934030	0.000000	1.79484	.098715	-.173650	-.349977	-.159887	-.097175	-.173650	.329457
26	2.670193	-2.934030	0.000000	2.01080	.127388	-.173650	-.282531	-.083658	.017789	-.173650	.219104
27	3.555723	-2.934030	0.000000	1.32138	.054871	-.314650	-.205623	-.021734	.029459	-.032650	.045939
28	1.969121	-3.401580	0.000000	1.25080	.006754	-.173650	-.191249	-.174443	-.166173	-.173650	.502127
29	2.784672	-3.401580	0.000000	0.99902	.041085	-.173650	-.130050	-.180350	-.042528	-.173650	.228046
30	3.560222	-3.401580	0.000000	2.15752	.118020	-.314650	-.311258	.099483	.095648	-.032650	-.148916

VELOCITIES AND MERIDIONAL PRESSURES AT CONTROL POINTS IMMEDIATELY TO RIGHT AND LEFT OF VERTICAL WING SURFACE

J	X(J)	Y(J)	Z(J)	UTOTR	VTOTR	WTOTR	PRESSR	UTOTL	VTOTL	WTOTL	PRESSL
31	1.231118	0.000000	1.530959	-.184670	.173650	-.070784	.485707	.142073	.173650	-.265202	-.218475
32	2.386670	0.000000	1.530959	-.125543	.173650	-.081251	.340432	.122868	.173650	-.178460	-.167575
33	3.542222	0.000000	1.530959	.046600	.314650	-.127406	-.052137	.228762	.032650	-.162443	-.324682
34	1.415654	0.000000	1.998701	-.108987	.173650	-.079299	.299457	.254058	.173650	-.288901	-.348754
35	2.481188	0.000000	1.998701	-.114434	.173650	-.045543	.303185	.146320	.173650	-.146320	-.205016
36	3.546723	0.000000	1.998701	.041221	.314650	-.087774	-.046644	.238483	.032650	-.125737	-.336291
37	1.600170	0.000000	2.466397	-.180142	.173650	-.070339	.397380	.176014	.173650	-.135310	-.248710
38	2.575697	0.000000	2.466397	-.115489	.173650	-.007767	.281734	.170160	.173650	-.102179	-.242750
39	3.551224	0.000000	2.466397	.049313	.314650	.021685	-.089321	.242287	.032650	-.015485	-.340987
40	1.784662	0.000000	2.934030	-.152807	.173650	-.097175	.328657	.179484	.173650	-.098715	-.255977
41	2.670193	0.000000	2.934030	-.083658	.173650	-.017789	.201080	.173650	.173650	-.127388	-.282531
42	3.555723	0.000000	2.934030	-.021734	.314650	-.029459	.064939	.142135	.032650	-.054871	-.205623
43	1.969121	0.000000	3.401580	-.174443	.173650	.166173	.302127	.125040	.173650	-.208756	-.191249
44	2.784672	0.000000	3.401580	-.108350	.173650	.042528	.228046	.090902	.173650	-.031085	-.136050
45	3.560222	0.000000	3.401580	.099483	.314650	-.095648	-.148916	.215752	.042650	-.114024	-.311258
46	1.231118	0.000000	-1.530959	-.184663	.173650	-.185261	.507040	.150107	.173650	-.009157	-.032106
47	2.386670	0.000000	-1.530959	-.114079	.173650	-.165880	.336822	.129322	.173650	-.070070	-.185488
48	3.542222	0.000000	-1.530959	-.084647	.314650	-.203827	.189374	.113445	.032650	-.168769	-.167160
49	1.415654	0.000000	-1.998701	-.111513	.173650	-.072591	.303890	.251532	.173650	-.137014	-.378070
50	2.481188	0.000000	-1.998701	-.130793	.173650	-.124119	.362347	.130365	.173650	-.023309	-.195638
51	3.546723	0.000000	-1.998701	-.051527	.314650	-.151102	.151621	.145735	.032650	-.120139	-.218475
52	1.600170	0.000000	-2.466397	-.179328	.173650	-.168197	.489158	.178888	.173650	.039062	-.275450
53	2.575697	0.000000	-2.466397	-.118118	.173650	-.108495	.328461	.167531	.173650	-.001452	-.254622
54	3.551224	0.000000	-2.466397	.044207	.314650	-.125403	-.047964	.247271	.032650	-.064065	-.337191
55	1.784662	0.000000	-2.934030	-.158442	.173650	-.164180	.436643	.180450	.173650	.031710	-.278462
56	2.670193	0.000000	-2.934030	-.086151	.173650	-.054054	.217995	.198586	.173650	-.035542	-.305871
57	3.555723	0.000000	-2.934030	-.047964	.314650	-.059098	.102817	.117778	.032650	-.029459	-.180350

Figure 6.- Continued.

5A	1.969121	0.000000	-3.401580	-.173276	.173650	-.215237	.470854	.126247	.173650	-.042307	-.185537
59	2.764672	0.000000	-3.401580	-.099502	.173650	-.092003	.279228	.091750	.173650	-.014490	-.134517
60	3.560222	0.000000	-3.401580	.046602	.314450	.040951	-.174457	.212912	.032650	.063327	-.333055

PRESSURE LOADINGS AT CONTROL POINTS

J	X(J)	Y(J)	Z(J)	DELTP, LIN.	DELTP, WERN.
1	1.231118	1.530959	0.000000	.673486	.740049
2	2.386670	1.530959	0.000000	.496803	.522560
3	3.542222	1.530959	0.000000	.364325	.356534
4	1.415654	1.998701	0.000000	.726090	.682364
5	2.481188	1.998701	0.000000	.522316	.557945
6	3.546723	1.998701	0.000000	.394522	.370496
7	1.600170	2.466397	0.000000	.712392	.764408
8	2.575497	2.466397	0.000000	.571298	.543081
9	3.551224	2.466397	0.000000	.385949	.289228
10	1.784662	2.934030	0.000000	.678583	.714766
11	2.670193	2.934030	0.000000	.569475	.543464
12	3.555723	2.934030	0.000000	.307739	.291860
13	1.969121	3.401580	0.000000	.599046	.656192
14	2.764672	3.401580	0.000000	.382503	.414445
15	3.560222	3.401580	0.000000	.242539	.158598
16	1.231118	-1.530959	0.000000	.673486	.704460
17	2.386670	-1.530959	0.000000	.496803	.508007
18	3.542222	-1.530959	0.000000	.364325	.272545
19	1.415654	-1.998701	0.000000	.726090	.648391
20	2.481188	-1.998701	0.000000	.522316	.508200
21	3.546723	-1.998701	0.000000	.394522	.289407
22	1.600170	-2.466397	0.000000	.712392	.646089
23	2.575497	-2.466397	0.000000	.571298	.524487
24	3.551224	-2.466397	0.000000	.385949	.260665
25	1.784662	-2.934030	0.000000	.678583	.584635
26	2.670193	-2.934030	0.000000	.569475	.501635
27	3.555723	-2.934030	0.000000	.307739	.269561
28	1.969121	-3.401580	0.000000	.599046	.493376
29	2.764672	-3.401580	0.000000	.382503	.358096
30	3.560222	-3.401580	0.000000	.242539	.162342
31	1.231118	0.000000	1.530959	.673486	.704460
32	2.386670	0.000000	1.530959	.496803	.508007
33	3.542222	0.000000	1.530959	.364325	.272545
34	1.415654	0.000000	1.998701	.726090	.648391
35	2.481188	0.000000	1.998701	.522316	.508200
36	3.546723	0.000000	1.998701	.394522	.289407
37	1.600170	0.000000	2.466397	.712392	.646089
38	2.575497	0.000000	2.466397	.571298	.524487
39	3.551224	0.000000	2.466397	.385949	.260669
40	1.784662	0.000000	2.934030	.678583	.584635
41	2.670193	0.000000	2.934030	.569475	.501635
42	3.555723	0.000000	2.934030	.307739	.269561
43	1.969121	0.000000	3.401580	.599046	.493376
44	2.764672	0.000000	3.401580	.382503	.358096
45	3.560222	0.000000	3.401580	.242539	.162342
46	1.231118	0.000000	-1.530959	.673486	.740049
47	2.386670	0.000000	-1.530959	.496803	.522560
48	3.542222	0.000000	-1.530959	.364325	.356534
49	1.415654	0.000000	-1.998701	.726090	.682364

Figure 6.- Continued.

50	2.481188	0.000000	-1.998701	.522318	.557985
51	3.546725	0.000000	-1.998701	.394522	.370498
52	1.800170	0.000000	-2.466397	.712392	.764808
53	2.575697	0.000000	-2.466397	.571298	.581083
54	3.551224	0.000000	-2.466397	.485909	.289228
55	1.784862	0.000000	-2.934030	.875583	.714768
56	2.870193	0.000000	-2.934030	.589475	.543966
57	3.555723	0.000000	-2.934030	.507730	.291860
58	1.969121	0.000000	-3.401580	.599046	.656192
59	2.764672	0.000000	-3.401580	.382503	.818485
60	3.560222	0.000000	-3.401580	.232539	.158598

LOADING INFORMATION

MACH NUMBER = .1700E+01
 ANGLE OF ATTACK = 10.000 DEGREES
 SIDE SLIP ANGLE = 10.000 DEGREES
 WING AREA = 13.88888
 REFERENCE AREA = 5.50929
 REFERENCE LENGTH = 2.59000
 EXPOSED WING SPAN B = 4.68000
 MOMENT CENTER XM = 19.50000
 ZM = 0.00000

BERNOULLI TYPE LOADING PRESSURE

REFL. ANGLE DEG.	TOTAL	FIN 1 OR R	FIN 2 OR L	FIN 3 OR U	FIN 4 OR D	INTERF. SHELL
CTHR	.61347E+01	.16075E+01	.14598E+01	.14598E+01	.16075E+01	
CZ	.15087E+01	.66375E+00	.58666E+00	0.	0.	.25832E+00
CY	-.15087E+01	0.	0.	.58666E+00	.66375E+00	-.25832E+00
CM	-.14851E+01	.43842E+00	.56128E+00	0.	0.	-.28518E+00
CLM	.14851E+01	0.	0.	.56128E+00	.63862E+00	.28518E+00
CLI	.60190E+13	.57593E+00	.50480E+00	.50480E+00	.57593E+00	.24098E+15

FOLLOWING ARE IN XIND=AXIS SYSTEM

CL	.20840E+01	.45892E+00	.40571E+00	.40571E+00	.45892E+00	.35414E+00
CY-IND	.72202E-12	.46934E+00	.41483E+00	-.41483E+00	-.46934E+00	.72387E-12
COT	.46452E+00	.99677E+01	.87723E-01	.87723E-01	.99677E+01	.89715E-01
COT/CL*2	.10702E+00					
CM-IND	-.21002E+01	-.45157E+00	-.39688E+00	-.39688E+00	-.45157E+00	-.40328E+00
CLN-IND	-.65725E-12	.29631E+00	.50870E+00	.50870E+00	.29631E+00	-.61400E-12

NOTE: L.F. OF LEAD PANEL IN FIRST CHORDWISE QU. IS SUPERSONIC

Figure 6.- Continued.

-----RIGHT WING-----

SPANNISE DISTRIBUTIONS

I	Y/(R/2)	CN=C/(2*B)	CT=C/(2*B)	CY1=C/(2*B)	CYTOT=C/(2*B)	CS=C/(2*B)	CSINT	YBAR	GAMNET(I)	GAMMA ₁ (E/VINF)	XLE
1	.65426	.14979	0.00000	0.00000	.00425	0.00000	0.00000	0.00000	-.94550	0.00000	.13334
2	.85415	.14427	0.00000	0.00000	.00106	0.00000	0.00000	0.00000	.07730	0.00000	.40340
3	1.05402	.17008	0.00000	0.00000	.00208	0.00000	0.00000	0.00000	.05478	0.00000	.67342
4	1.25386	.14656	0.00000	0.00000	.00203	0.00000	0.00000	0.00000	.11192	0.00000	.94341
5	1.45367	.10438	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.19747	0.00000	1.21335
6	1.55556	0.00000							.48904		

SUMFX = 0.
 SUMFY1 = 0.
 SUMFY2 = .69502E+02
 SUMFT2 = .28353E+01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE /TIPCHORD	SUCTION FORCE PER UNIT LENGTH /(R*TIPCHORD)	GAMMA _{SE} /VINF	YBAR	XSE
1	1	.33333	.00337	.00060	3.64000	1.45100
2	2	.66667	.03885	.00749	3.64000	2.10067
3	3	1.00000	.04707	.01984	3.64000	2.85031

T.E. FIN VIBRTEX INFO

IVRY GAMMA/VINF Y.C.G.
 1 .93503 3.18446

----- LEFT WING -----

SPANNISE DISTRIBUTIONS

I	Y/(R/P)	CX/C/(2*R)	CT/C/(2*R)	CY1/C/(2*P)	CYTOT/C/(2*R)	CS/C/(2*B)	CSINT	YBAR	GAMNET(I)	GAMMA,LF/VINF	YLL
7	-.45426	.18324	0.00000	0.00000	-.00362	0.00000	0.00000	0.00000	.85800	0.00000	.13314
8	-.45415	.16451	0.00000	0.00000	-.00281	0.00000	0.00000	0.00000	-.08752	0.00000	.40340
9	-1.05492	.14906	0.00000	0.00000	-.00182	0.00000	0.00000	0.00000	-.07227	0.00000	.67302
10	-1.25385	.12816	0.00000	0.00000	-.00197	0.00000	0.00000	0.00000	-.09779	0.00000	.94341
11	-1.45367	.08608	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.19706	0.00000	1.21335
12	-1.55556	0.00000							-.40327		

SUMFY = 0.00000
 SUMFY1 = 0.00000
 SUMFY2 = -.84305E-02
 SUMFT2 = -.22939E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SECTION FORCE PER UNIT LENGTH / (700 * TIPCHORD)	GAMMA, SE / VINF	YBAR	XSE
1	1	.33433	-.00253	-.00045	-3.64000	1.45100
2	2	.65667	-.03089	-.00593	-3.64000	2.10067
3	3	1.00000	-.03582	-.01281	-3.64000	2.85033

****T.F. FIN VORTEX INFO****
 IVRT GAMMA/VINF Y.C.G.
 2 -.85757 -3.11600

Figure 6.- Continued.

-----UPPER WING-----

SPANWISE DISTRIBUTIONS

I	Z/(H/2)	CN* $C/(2*B)$	CT* $C/(2*B)$	CZ1* $C/(2*B)$	CZTOT* $C/(2*B)$	CS* $C/(2*B)$	CSINT	ZBAR	GAMNET(I)	GAMMA,LE/VINF	XLE
13	.65426	.18324	0.00000	0.00000	.00362	0.00000	0.00000	0.00000	.85800	0.00000	.13334
14	.85415	.16451	0.00000	0.00000	.00281	0.00000	0.00000	0.00000	.08762	0.00000	.40340
15	1.05402	.14996	0.00000	0.00000	.00182	0.00000	0.00000	0.00000	.07227	0.00000	.67342
16	1.25386	.12816	0.00000	0.00000	.00197	0.00000	0.00000	0.00000	.09779	0.00000	.94341
17	1.45367	.08638	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.19704	0.00000	1.21335
18	1.54556	0.00000							.40327		

SUMEX = 0.
 SUMEZ1 = 0.
 SUMEZ2 = .84305E+02
 SUMFT2 = .22939E+01.

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE /TIPCHORD	SUCTION FORCE PER UNIT LENGTH /(0.5TIPCHORD)	GAMMA,SE /VINF	ZBAR	XSE
1	4	.33333	.00253	.00045	3.64000	1.35100
2	5	.66667	.03089	.00593	3.64000	2.10067
3	6	1.00000	.03882	.01281	3.64000	2.85033

*****E. FIN VORTEX INFO*****

IVRT GAMMA/VINF Z.C.G.
 3 .85757 3.11604

Figure 6.- Continued.

SPANWISE DISTRIBUTIONS

I	Z/(R/2)	C1+C/(2*B)	C1-C/(2*B)	CZ1+C/(2*B)	CZ1-C/(2*B)	CZTOT+C/(2*B)	CS+C/(2*B)	CSTNT	ZBAR	GAMNET(I)	GAMMA,LF/VINF	X/E
19	-.65426	.19479	0.00000	0.00000	-.00325	0.00000	0.00000	0.00000	0.00000	.93550	0.00000	.13350
20	-.85415	.18327	0.00000	0.00000	-.00106	0.00000	0.00000	0.00000	0.00000	-.07730	0.00000	.40340
21	-1.05402	.17044	0.00000	0.00000	-.00208	0.00000	0.00000	0.00000	0.00000	-.05978	0.00000	.67342
22	-1.25386	.14656	0.00000	0.00000	-.00203	0.00000	0.00000	0.00000	0.00000	-.11192	0.00000	.94341
23	-1.45367	.10438	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.19747	0.00000	1.21335
24	-1.55456	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.48904		

SUMFX = 0.
 SUMFZ1 = 0.
 SUMFZ2 = -.69542E+02
 SUMFT2 = -.28353E+01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE /TIPCHORD	SUCTION FORCE PER UNIT LENGTH /(G*TIPCHORD)	GAMMA,SP /VINF	ZBAR	X/E
1	7	.53333	-.00337	-.00060	-3.64000	1.35100
2	8	.66667	-.03885	-.00749	-3.64000	2.10067
3	9	1.00000	-.04707	-.01584	-3.64000	2.85033

****I.E. FIN VORTEX INFO****

IVRT GAMMA/VINF Z,C.G.

4 -.93503 -5.18446

 AFT OF LEADING EDGE OF FIN POINTCHORDS

Figure 6.- Continued.

PRESSURE COEFFICIENTS AT POINTS ON BODY MERIDIANS

J	THETA, DEG.	XH	YH	ZH	UHT	VHT	WHT	CP, LIN.	CP, REAR.	OR/UV	P/PTNF. BFNN.	P/PTNF. LIN.
BODY RINGS 1												
1	11.25000	20.94000	1.25052	.24874	.11130	.12273	.11776	-.22260	-.21167	0.00000	.57179	.54968
2	33.75000	20.94000	1.06014	.70836	.02622	-.09448	.23203	-.05244	-.19266	0.00000	.61026	.89390
3	56.25000	20.94000	.70836	1.06014	-.05100	-.19760	.07152	.10199	-.04014	0.00000	.91880	1.20633
4	78.75000	20.94000	.24874	1.25052	-.12330	-.10673	-.12489	.24661	.23477	0.00000	1.07494	1.49488
5	101.25000	20.94000	-.24874	1.25052	.11085	.02473	-.21377	-.22171	-.16584	0.00000	.66451	.55149
6	123.75000	20.94000	-.70836	1.06014	.02016	.11698	-.22613	-.04832	.00696	0.00000	1.01407	.90226
7	146.25000	20.94000	-1.06014	.70836	.02416	.22613	-.11698	-.04832	.00696	0.00000	1.01407	.90226
8	168.75000	20.94000	-1.25052	.24874	.11085	.21377	-.02473	-.22171	-.16584	0.00000	.66451	.55149
9	191.25000	20.94000	-1.25052	-.24874	-.12330	.12489	.10673	.24661	.23477	0.00000	1.07494	1.49488
10	213.75000	20.94000	-1.06014	-.70836	-.05100	-.19760	.07152	.10199	-.04014	0.00000	.91880	1.20633
11	236.25000	20.94000	-.70836	-1.06014	.02622	-.09448	.23203	-.05244	-.19266	0.00000	.61026	.89390
12	258.75000	20.94000	-.24874	-1.25052	.11130	.11776	-.12273	-.22260	-.21167	0.00000	.57179	.54968
13	281.25000	20.94000	.24874	-1.25052	-.12286	.03577	-.21161	.24571	.31677	0.00000	1.64085	1.49707
14	303.75000	20.94000	.70836	-1.06014	-.04843	.15140	-.20317	.09787	.16871	0.00000	1.34131	1.19798
15	326.25000	20.94000	1.06014	-.70836	-.04843	.20317	-.15140	.09787	.16871	0.00000	1.34131	1.19798
16	348.75000	20.94000	1.25052	-.24874	-.12286	.21161	-.03577	.24571	.31677	0.00000	1.64085	1.49707
BODY RINGS 2												
1	11.25000	22.14000	1.25052	.24874	.11021	.12916	.08542	-.20841	-.18841	0.00000	.61884	.57838
2	33.75000	22.14000	1.06014	.70836	.01537	-.02324	.12539	-.03074	-.09119	0.00000	.81552	.93781
3	56.25000	22.14000	.70836	1.06014	-.07275	-.09832	.00518	.14551	.09614	0.00000	1.19449	1.29436
4	78.75000	22.14000	.24874	1.25052	-.11800	-.02813	-.12859	.23600	.23666	0.00000	1.47878	1.47742
5	101.25000	22.14000	-.24874	1.25052	.11874	.02657	-.21341	-.23708	-.17802	0.00000	.64987	.51958
6	123.75000	22.14000	-.70836	1.06014	.10747	.12241	-.22251	-.21494	-.14596	0.00000	.70473	.56517
7	146.25000	22.14000	-1.06014	.70836	.10747	.22251	-.12241	-.21494	-.14596	0.00000	.70473	.56517
8	168.75000	22.14000	-1.25052	.24874	.11874	.21341	-.02657	-.21748	-.17802	0.00000	.64987	.51958
9	191.25000	22.14000	-1.25052	-.24874	-.11800	.12859	.02813	.23600	.23666	0.00000	1.47878	1.47742
10	213.75000	22.14000	-1.06014	-.70836	-.07275	-.04518	.09832	.14551	.09614	0.00000	1.19449	1.29436
11	236.25000	22.14000	-.70836	-1.06014	.01537	-.12539	.02324	-.03074	-.09119	0.00000	.81552	.93781
12	258.75000	22.14000	-.24874	-1.25052	.11021	-.08542	-.12916	-.20841	-.18841	0.00000	.61884	.57838
13	281.25000	22.14000	.24874	-1.25052	-.13253	.02387	-.21397	.26506	.34497	0.00000	1.67745	1.54622
14	303.75000	22.14000	.70836	-1.06014	-.14485	.14948	-.20445	.32971	.44960	0.00000	1.90954	1.66699
15	326.25000	22.14000	1.06014	-.70836	-.14485	.20445	-.14948	.32971	.44960	0.00000	1.90954	1.66699
16	348.75000	22.14000	1.25052	-.24874	-.13253	.21397	-.02387	.26506	.34497	0.00000	1.67745	1.54622
BODY RINGS 3												
1	11.25000	23.34000	1.25052	.24874	.07229	.14316	.01498	-.14459	-.11128	0.00000	.77484	.70750
2	33.75000	23.34000	1.06014	.70836	.00171	.00802	.07860	-.00342	-.03324	0.00000	.93275	.99407
3	56.25000	23.34000	.70836	1.06014	-.01831	-.08238	-.00548	.03662	.00163	0.00000	1.00331	1.07408
4	78.75000	23.34000	.24874	1.25052	-.00643	-.13334	-.11960	.01285	-.02404	0.00000	.95137	1.02601
5	101.25000	23.34000	-.24874	1.25052	.17952	.06566	-.20564	-.35404	-.28020	0.00000	.47362	.27367
6	123.75000	23.34000	-.70836	1.06014	.15449	.12491	-.22084	-.30897	-.21983	0.00000	.55528	.37495
7	146.25000	23.34000	-1.06014	.70836	.15449	.22084	-.12491	-.30897	-.21983	0.00000	.55528	.37495
8	168.75000	23.34000	-1.25052	.24874	.17952	.20564	-.06566	-.35404	-.28020	0.00000	.47362	.27367
9	191.25000	23.34000	-1.25052	-.24874	-.00643	.11960	.01285	-.02404	-.00163	0.00000	.95137	1.02601
10	213.75000	23.34000	-1.06014	-.70836	-.01831	.08548	.08238	.00548	.00163	0.00000	1.00331	1.07408

Figure 6.- Continued.

11	236,25000	23,34000	-.70836	-1.06014	.00171	-.07860	-.00802	-.00342	-.03424	0.00000	.91275	.99307
12	258,75000	23,34000	-.24874	-1.25052	.07229	-.01498	-.14316	-.10459	-.11128	0.00000	.77488	.70750
13	281,25000	23,34000	.24874	-1.25052	-.11345	-.05276	-.22421	.22730	.24834	0.00000	1.50240	1.45983
14	303,75000	23,34000	.70836	-1.06014	-.17108	.12113	-.22339	.34217	.45961	0.00000	1.92980	1.69220
15	326,25000	23,34000	1.06014	-.70836	-.17108	.22339	-.12113	.34217	.45961	0.00000	1.92980	1.69220
16	348,75000	23,34000	1.25052	-.24874	-.11345	.22921	.05276	.22730	.24834	0.00000	1.50240	1.45983

Figure 6.- Concluded.

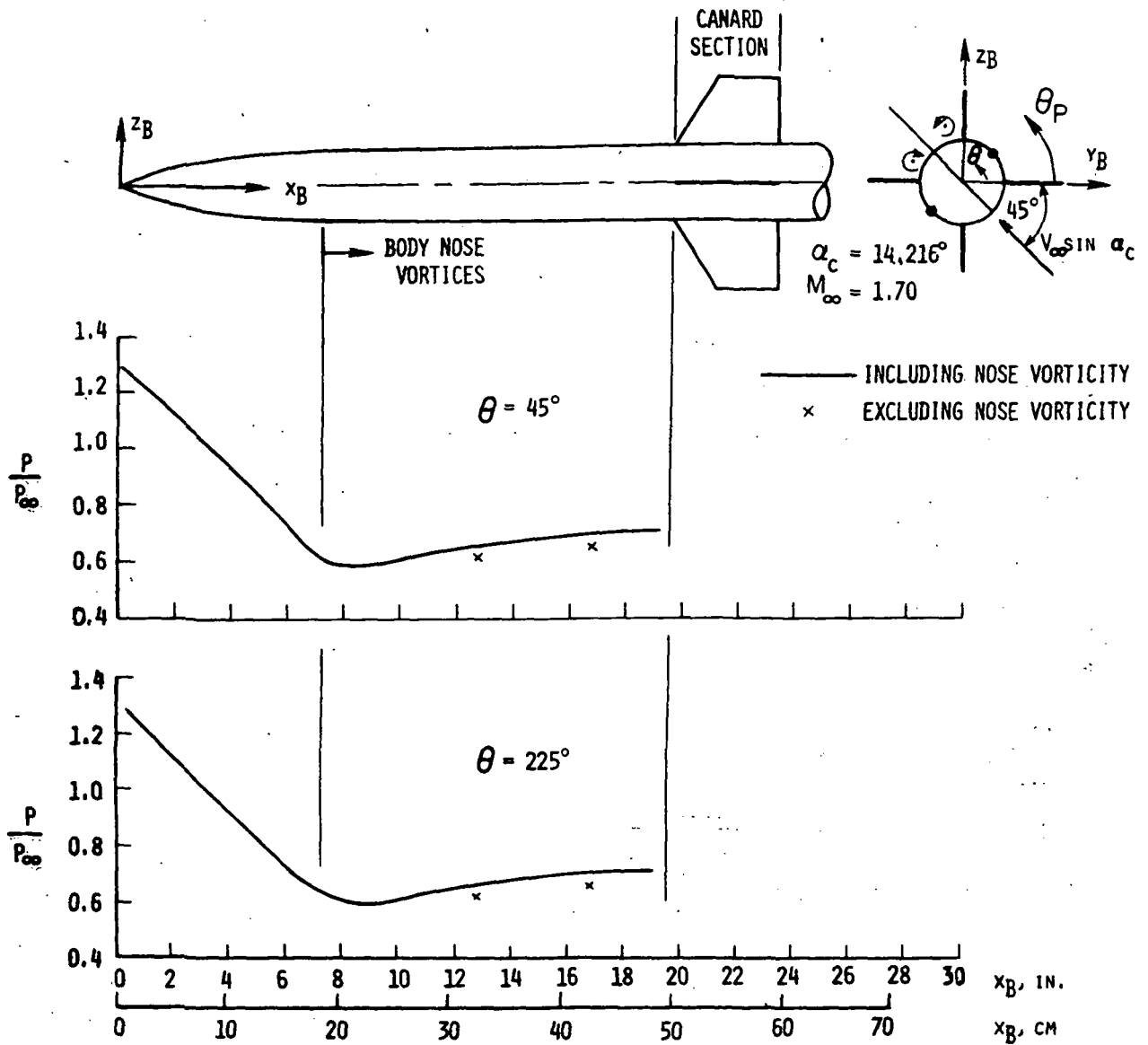


Figure 7(a).- Calculated pressure distributions along body meridians up to canard section; first sample case.

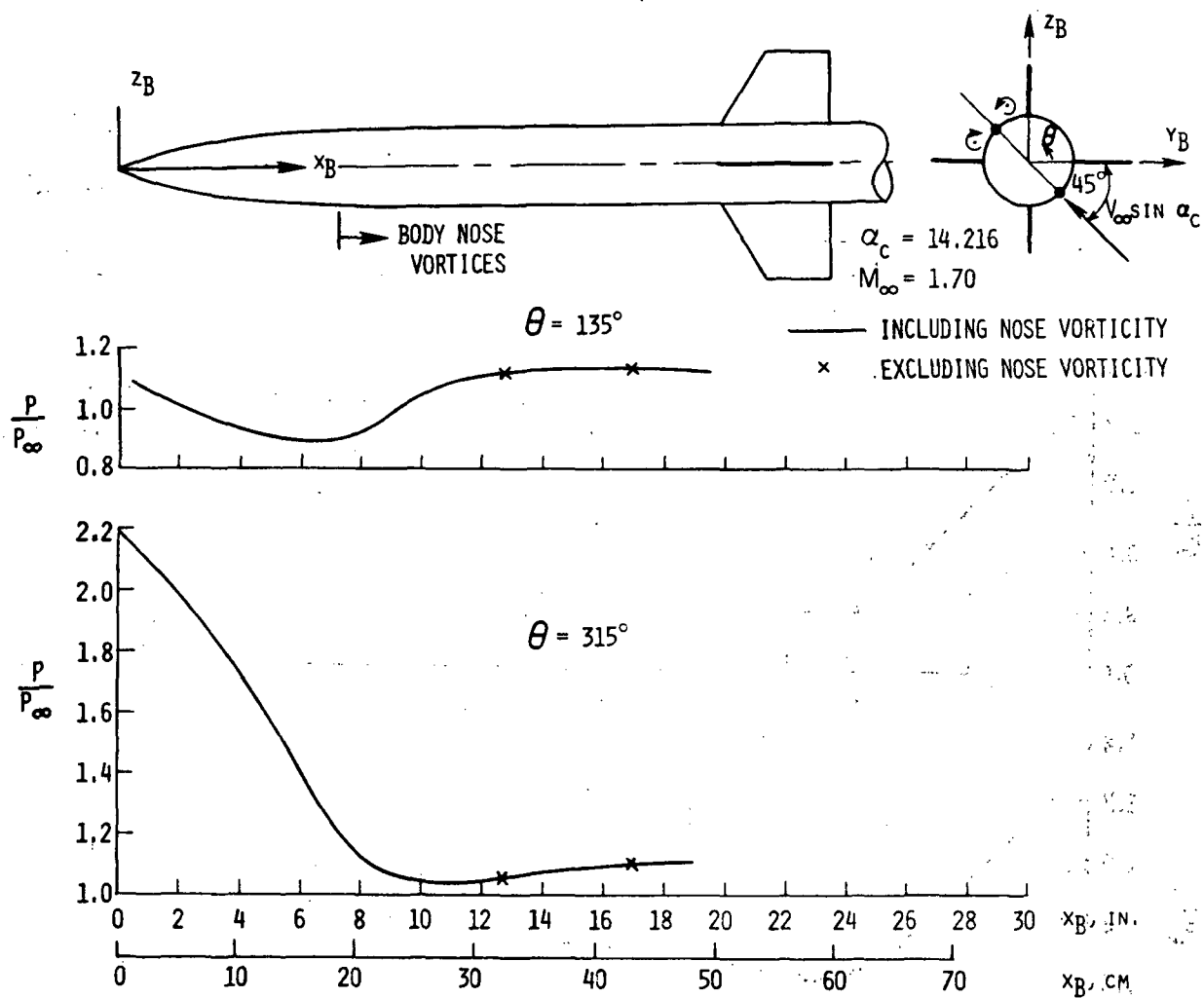


Figure 7(b).- Concluded.

NASA/LRC PROJECT 1126, CONFIGURATION B1W4, CHASE NOSE VORTICES PAST CANARD SECTION

	1	4	11	1	1	0	1
23.4							
1.3							
19.8	1.3	21.151	3.64	23.4	3.64	23.400001	1.3
14.216	45.0					0.0001	0.35
2	2	2	2	2	2	2	2
-0.64337	1.8382	0.8024	-1.8382	0.64337	-0.8024		
19.8	20.163	20.514	20.878	21.242	21.606	21.957	22.321
22.685	23.036	23.4					
	0	0	0	0			
	0						

Figure 8.- Input for program VPATH2, first sample case, step 2.

NASA/LRC PROJECT 112A, CONFIGURATION B1=4, CHASE NOSE VORTICES PAST CANARD SECTION

```

FIN GEOMETRY
FIN SEMISPAN      = 3.64000
FIN ROOTCHORD    = 3.60000
FIN ROOT L.E. X-STATION= 19.80000
                L.E. Y-STATION= 1.30000
FIN TIP L.E. X-STATION = 21.15100
                L.E. Y-STATION = 3.64000
FIN TIP T.E. X-STATION = 23.40000
                T.E. Y-STATION = 3.64000
FIN ROOT T.F. X-STATION= 23.40000
                T.E. Y-STATION= 1.30000
    
```

INCLUDED ANGLE OF ATTACK(DEG) = 14.21600 ROLL ANGLE(DEG) = 45.00000

PANEL DEFL.(DEG) :

DELTA1= 0.000 DELTA2= 0.000 DELTA3= 0.000 DELTA4= 0.000

***PERMISSIBLE RELATIVE ERROR, ES, USED IN INTEGRATION SCHEME = .10000E-03

VORTEX COORDINATES IN CROSS-FLOW PLANE

INITIAL VORTEX POSITIONS AT X = 19.800

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.64337E+00	.18382E+01	.40240E+00
2	-.14382E+01	.64337E+00	-.80240E+00

X-STATION NO. 2 X=20.163 INTEGRATION STEP SIZE = .18150

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.92873

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
--------	--------	--------	------------

Figure 9.- Output of program VPATH2, first sample case, step 2.

1	-.68037E+00	.18568E+01	.80240E+00
2	-.18568E+01	.68037E+00	-.80240E+00
X-STATION NO. 3 X=20.514 INTEGRATION STEP SIZE = .18150			
LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 2.53668			
VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.70316E+00	.18633E+01	.80240E+00
2	-.18633E+01	.70316E+00	-.80240E+00
X-STATION NO. 4 X=20.878 INTEGRATION STEP SIZE = .18150			
LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.16715			
VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.70923E+00	.18674E+01	.80240E+00
2	-.18674E+01	.70923E+00	-.80240E+00
X-STATION NO. 5 X=21.242 INTEGRATION STEP SIZE = .18150			
LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000			
VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.70610E+00	.18736E+01	.80240E+00
2	-.18736E+01	.70610E+00	-.80240E+00
X-STATION NO. 6 X=21.606 INTEGRATION STEP SIZE = .36300			
LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000			
VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.70153E+00	.18806E+01	.80240E+00
2	-.18806E+01	.70153E+00	-.80240E+00
X-STATION NO. 7 X=21.957 INTEGRATION STEP SIZE = .36300			
LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000			
VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF

Figure 9.- Continued.

1	-.69747E+00	.18977E+01	.80240E+00
2	-.18977E+01	.69747E+00	-.80240E+00

X=STATION NO. 8 X=22.321 INTEGRATION STEP SIZE = .72600

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.69363E+00	.18953E+01	.80240E+00
2	-.18953E+01	.69363E+00	-.80240E+00

X=STATION NO. 9 X=22.685 INTEGRATION STEP SIZE = .72600

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.69017E+00	.19031E+01	.80240E+00
2	-.19031E+01	.69017E+00	-.80240E+00

X=STATION NO. 10 X=23.036 INTEGRATION STEP SIZE = .72600

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.68720E+00	.19109E+01	.80240E+00
2	-.19109E+01	.68720E+00	-.80240E+00

X=STATION NO. 11 X=23.400 INTEGRATION STEP SIZE = .72600

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.68451E+00	.19192E+01	.80240E+00
2	-.19192E+01	.68451E+00	-.80240E+00

CROSSFLOW VELOCITIES AT CONTROL POINTS INDUCED BY VORTICES AND THEIR IMAGES

IC	X,BODY	Y,BODY	Z,BODY	V	W
1	.21631E+02	.15310E+01	0.	.21494E-02	-.70848E-02
2	.22187E+02	.15310E+01	0.	.22417E-02	-.73904E-02
3	.23342E+02	.15310E+01	0.	.23375E-02	-.77102E-02
4	.21218E+02	.19987E+01	0.	.40063E-02	-.44570E-02
5	.22261E+02	.19987E+01	0.	.41696E-02	-.46394E-02
6	.23347E+02	.19987E+01	0.	.43342E-02	-.48258E-02
7	.21400E+02	.24664E+01	0.	.43372E-02	-.26581E-02

Figure 9.- Continued.

8	.22376E+02	.24664E+01	0.	.44995E-02	-.27581E-02
9	.23351E+02	.24664E+01	0.	.46627E-02	-.28607E-02
10	.21585E+02	.29340E+01	0.	.41198E-02	-.14995E-02
11	.22470E+02	.29340E+01	0.	.42595E-02	-.15510E-02
12	.23356E+02	.29340E+01	0.	.44001E-02	-.16042E-02
13	.21769E+02	.34016E+01	0.	.37321E-02	-.76368E-03
14	.22565E+02	.34016E+01	0.	.34456E-02	-.78745E-03
15	.23360E+02	.34016E+01	0.	.39599E-02	-.81237E-03
16	.21031E+02	-.15310E+01	0.	-.76760E-01	-.17026E+00
17	.22187E+02	-.15310E+01	0.	-.76729E-01	-.17591E+00
18	.23342E+02	-.15310E+01	0.	-.75708E-01	-.18067E+00
19	.21216E+02	-.19987E+01	0.	-.13521E+00	-.38546E-01
20	.22291E+02	-.19987E+01	0.	-.13885E+00	-.42546E-01
21	.23347E+02	-.19987E+01	0.	-.14371E+00	-.47503E-01
22	.21400E+02	-.24664E+01	0.	-.76287E-01	.33442E-01
23	.22376E+02	-.24664E+01	0.	-.80075E-01	.34808E-01
24	.23351E+02	-.24664E+01	0.	-.84175E-01	.35781E-01
25	.21585E+02	-.29340E+01	0.	-.32972E-01	.36466E-01
26	.22470E+02	-.29340E+01	0.	-.34252E-01	.37988E-01
27	.23356E+02	-.29340E+01	0.	-.35706E-01	.39482E-01
28	.21769E+02	-.34016E+01	0.	-.14196E-01	.27926E-01
29	.22565E+02	-.34016E+01	0.	-.14621E-01	.28922E-01
30	.23360E+02	-.34016E+01	0.	-.15116E-01	.29847E-01
31	.21031E+02	.73521E-13	.15310E+01	.17026E+00	.76760E-01
32	.22187E+02	.73521E-13	.15310E+01	.17591E+00	.76729E-01
33	.23342E+02	.73521E-13	.15310E+01	.18067E+00	.75708E-01
34	.21216E+02	.95983E-13	.19987E+01	.38546E-01	.13321E+00
35	.22291E+02	.95983E-13	.19987E+01	.42546E-01	.13885E+00
36	.23347E+02	.95983E-13	.19987E+01	.47503E-01	.14371E+00
37	.21400E+02	.11844E-12	.24664E+01	-.34442E-01	.76287E-01
38	.22376E+02	.11844E-12	.24664E+01	-.34808E-01	.80075E-01
39	.23351E+02	.11844E-12	.24664E+01	-.35781E-01	.84175E-01
40	.21585E+02	.14090E-12	.29340E+01	-.36466E-01	.32972E-01
41	.22470E+02	.14090E-12	.29340E+01	-.37988E-01	.34252E-01
42	.23356E+02	.14090E-12	.29340E+01	-.39482E-01	.35706E-01
43	.21769E+02	.16335E-12	.34016E+01	-.27926E-01	.14196E-01
44	.22565E+02	.16335E-12	.34016E+01	-.28922E-01	.14621E-01
45	.23360E+02	.16335E-12	.34016E+01	-.29847E-01	.15116E-01
46	.21031E+02	-.73521E-13	-.15310E+01	.70888E-02	-.21494E-02
47	.22187E+02	-.73521E-13	-.15310E+01	.73904E-02	-.22417E-02
48	.23342E+02	-.73521E-13	-.15310E+01	.77102E-02	-.23375E-02
49	.21216E+02	-.95983E-13	-.19987E+01	.44570E-02	-.40063E-02
50	.22291E+02	-.95983E-13	-.19987E+01	.46394E-02	-.41696E-02
51	.23347E+02	-.95983E-13	-.19987E+01	.48258E-02	-.43342E-02
52	.21400E+02	-.11844E-12	-.24664E+01	.26581E-02	-.43372E-02
53	.22376E+02	-.11844E-12	-.24664E+01	.27581E-02	-.44995E-02
54	.23351E+02	-.11844E-12	-.24664E+01	.28607E-02	-.46627E-02
55	.21585E+02	-.14090E-12	-.29340E+01	.14995E-02	-.41198E-02
56	.22470E+02	-.14090E-12	-.29340E+01	.15510E-02	-.42595E-02
57	.23356E+02	-.14090E-12	-.29340E+01	.16042E-02	-.44001E-02
58	.21769E+02	-.16335E-12	-.34016E+01	.76368E-03	-.37321E-02
59	.22565E+02	-.16335E-12	-.34016E+01	.79743E-03	-.38456E-02
60	.23360E+02	-.16335E-12	-.34016E+01	.81237E-03	-.39599E-02
61	.21031E+02	.12505E+01	.24874E+00	.20095E-02	.12229E-01
62	.22187E+02	.10601E+01	.70836E+00	.12919E-01	-.20885E-01
63	.23342E+02	.70836E+00	.10601E+01	.42643E-01	-.31116E-01
64	.21216E+02	.24874E+00	.12505E+01	.12866E+00	-.32286E-01
65	.22291E+02	-.24874E+00	.12505E+01	.32968E+00	.55337E-01
66	.23347E+02	.70836E+00	.10601E+01	.16618E+00	.13512E+00
67	.21400E+02	.10601E+01	.70836E+00	-.13512E+00	-.16618E+00
68	.22470E+02	-.12505E+01	.24874E+00	-.32933E-01	-.32968E+00
69	.23356E+02	-.12505E+01	-.24874E+00	.32286E-01	-.12866E+00
70	.21585E+02	-.10601E+01	-.70836E+00	.31116E-01	-.42643E-01
71	.22470E+02	-.70836E+00	-.10601E+01	.20885E-01	-.12919E-01
72	.23347E+02	-.24874E+00	-.12505E+01	.12229E-01	-.20095E-02

Figure 9.- Continued.

73	.20940E+02	.24874E+00	-.12505E+01	.58282E-02	.14082E-02
74	.20940E+02	.70836E+00	-.10601E+01	.13956E-02	.11524E-02
75	.20940E+02	.10601E+01	-.70836E+00	-.11524E-02	-.13956E-02
76	.20940E+02	.12505E+01	-.24874E+00	-.58282E-02	-.14082E-02
77	.22140E+02	.12505E+01	.24874E+00	.20985E-02	-.12770E-01
78	.22140E+02	.10601E+01	.70836E+00	.13486E-01	-.21799E-01
79	.22140E+02	.70836E+00	.10601E+01	.44448E-01	-.32424E-01
80	.22140E+02	.24874E+00	.12505E+01	.13321E+00	-.33330E-01
81	.22140E+02	-.24874E+00	.12505E+01	.32996E-01	.56340E-01
82	.22140E+02	-.70836E+00	.10601E+01	.15939E+00	.12975E+00
83	.22140E+02	-.10601E+01	.70836E+00	-.12975E+00	-.15939E+00
84	.22140E+02	-.12505E+01	.24874E+00	-.56340E-01	-.32996E+00
85	.22140E+02	-.12505E+01	-.24874E+00	.33330E-01	-.13321E+00
86	.22140E+02	-.10601E+01	-.70836E+00	.32424E-01	-.44448E-01
87	.22140E+02	-.70836E+00	-.10601E+01	.21799E-01	-.13486E-01
88	.22140E+02	-.24874E+00	-.12505E+01	.12770E-01	-.20985E-02
89	.22140E+02	.24874E+00	.12505E+01	.60864E-02	.14706E-02
90	.22140E+02	.70836E+00	-.10601E+01	.14575E-02	.12035E-02
91	.22140E+02	.10601E+01	-.70836E+00	-.12035E-02	-.14575E-02
92	.22140E+02	.12505E+01	-.24874E+00	-.14706E-02	-.60864E-02
93	.23340E+02	.12505E+01	.24874E+00	.21926E-02	-.13340E-01
94	.23340E+02	.10601E+01	.70836E+00	.14077E-01	-.22751E-01
95	.23340E+02	.70836E+00	.10601E+01	.46275E-01	-.35741E-01
96	.23340E+02	.24874E+00	.12505E+01	.13737E+00	-.34239E-01
97	.23340E+02	-.24874E+00	.12505E+01	.32742E+00	.56877E-01
98	.23340E+02	-.70836E+00	.10601E+01	.15241E+00	.12413E+00
99	.23340E+02	-.10601E+01	.70836E+00	-.12413E+00	-.15241E+00
100	.23340E+02	-.12505E+01	.24874E+00	-.56877E-01	-.32742E+00
101	.23340E+02	-.12505E+01	-.24874E+00	.34239E-01	-.13737E+00
102	.23340E+02	-.10601E+01	-.70836E+00	.35741E-01	-.46275E-01
103	.23340E+02	-.70836E+00	-.10601E+01	.22751E-01	-.35741E-01
104	.23340E+02	-.24874E+00	-.12505E+01	.13340E-01	-.21926E-02
105	.23340E+02	.24874E+00	.12505E+01	.63609E-02	.15369E-02
106	.23340E+02	.70836E+00	-.10601E+01	.15235E-02	.12579E-02
107	.23340E+02	.10601E+01	-.70836E+00	-.12579E-02	-.15235E-02
108	.23340E+02	.12505E+01	-.24874E+00	-.15369E-02	-.63609E-02

Figure 9.- Concluded.

NASA/LANGLEY WING-TAIL INTERFERENCE MODEL INPUT PROJ. 1124, CONFIGURATION: 8140
 SINDIT
 SREF = .550020E+01,
 CRP = .36E+01, REFL = .269E+01,
 S-LEP = .3E+02, PNIDTH = 0.0,
 S-TEP = 0.0, THEFIT = 0.0,
 NCM = 3, XMLE = .199E+02,
 NS=0 = 5, NOLINP = 1,
 NSHL = 5, NOUT = 0,
 ALFAC = .14216E+02, NPR = 0,
 PH1 = .45E+02, NDRAG = 1,
 B2 = .234E+01, NVRTY = 0,
 FMACH = .17E+01, NPRESS = 0,
 LVS=0 = 0, VRTMAX = .5E+00,
 FAC = .95E+00, NCWR = 3,
 NFNDR = 0, NAGAIN = 0,
 TOLFAC = .1E+01, BIL = .36E+01,
 MSWU = 5, ITAIL = 0,
 MSWD = 5, NVRTPL = 0,
 S-LEV = .3E+02, NRDYDR = 1,
 S-TEV = 0.0, NTPR = 0,
 CRPV = .36E+01, NTDAT = 1,
 B2V = .234E+01, NCWT = 8,
 NCRY = 1, NCPDIT = 0,
 R4 = .13E+01, NVLIN = 1,
 RA = .13E+01, XSTART = 0.0,
 ERATIO = .1E+01, JCPT = 0,
 NBDCR = 16, FKLE = .5E+00,
 DELR = 0.0, FKSE = .5E+00,
 DFLL = 0.0, XM = .195E+02,
 DELU = 0.0, ZM = 0.0,
 DELD = 0.0, SEND

Figure 10.- Output of program DEMON2, first sample case, step 3.

WING GEOMETRY

TIP CHORD = 2.24000
 ROOT CHORD = 3.60000
 WING SEMISPAN = 2.54000
 LEADING EDGE SWEEP = 30.00000 DEGREES
 TRAILING EDGE SWEEP = 0.00000 DEGREES

FLOW CONDITIONS

MACH = 1.70000 ALPHAC = 14.21600 PWT = 45.00000 ALFA = 10.00010 BETA = 10.00010

CRPT = 3.60000
 CRPTV = 3.60000

WING THICKNESS INPUT DATA

SPANWISE LOCATIONS OF PANEL SIDE EDGES AND SWEEP ANGLES
 OF WING SECTION TO THE LEFT

I	SPANWISE LOCATION FEET	LE SWEEP DEGREES	TE SWEEP DEGREES
---	------------------------------	---------------------	---------------------

RIGHT WING SURFACE

1	1.30000	0.00000	0.00000
2	1.76800	30.00000	0.00000
3	2.23600	30.00000	0.00000
4	2.70400	30.00000	0.00000
5	3.17200	30.00000	0.00000
6	3.64000	30.00000	0.00000

40 THICKNESS PANELS ARE TO BE LAID OUT
 5 CHORDWISE ROWS WITH 8 IN EACH ROW

UPPER WING SURFACE

1	1.30000	0.00000	0.00000
2	1.76800	30.00000	0.00000
3	2.23600	30.00000	0.00000
4	2.70400	30.00000	0.00000
5	3.17200	30.00000	0.00000
6	3.64000	30.00000	0.00000

40 THICKNESS PANELS ARE TO BE LAID OUT
 5 CHORDWISE ROWS WITH 8 IN EACH ROW

INPUT VALUES OF THE LOCAL SURFACE SLOPE OF THE THICKNESS
DISTRIBUTION, FOR EACH CHORDWISE ROW THE FIRST VALUE
IS FOR THE PANEL NEAREST THE LEADING EDGE

RIGHT WING SURFACE

ROW	SLOPES							
1	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
2	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
3	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
4	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
5	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100

UPPER WING SURFACE

ROW	SLOPES							
1	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
2	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
3	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
4	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
5	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100

\$BODY

NXBODY = 39.

LNASE = .78E+01.

LRDDY = .39E+02.

BCODE = 2.

\$END

PHYSICAL DIMENSIONS OF BODY AND LINE SINGULARITY STRENGTHS REPRESENTING THE BODY AT MACH= 1.7000 ALFAC= 14.2140

	X	R	OR/DX	TX	T(I)	TC(I)
1	0.0000	-.42633E-13	.34286	.58619E-13	.10092	.39465E-01
2	1.0763	.32639	.29353	.57761	-.40121E-01	-.10955E-01
3	2.0526	.60316	.24611	1.2234	-.25012E-01	-.62846E-02
4	3.0789	.83207	.20020	1.9350	-.24274E-01	-.81381E-02
5	4.1053	1.0145	.15447	2.7106	-.18881E-01	-.74517E-02
6	5.1316	1.1515	.11164	3.5085	-.15477E-01	-.75496E-02
7	6.1579	1.2439	.68439E-01	4.4479	-.11952E-01	-.73645E-02
8	7.1842	1.2921	.25613E-01	5.4078	-.83169E-02	-.70718E-02
9	8.2105	1.3000	0.	6.4233	.31078E-01	-.28112E-02
10	9.2368	1.3000	0.	7.4496	.35295E-02	.47755E-02
11	10.2632	1.3000	0.	8.4760	.34046E-02	.39930E-02
12	11.2895	1.3000	0.	9.5023	.14152E-02	.36673E-02
13	12.3158	1.3000	0.	10.529	.93969E-03	.28432E-02
14	13.3421	1.3000	0.	11.555	.55466E-03	.17866E-02
15	14.3684	1.3000	0.	12.581	.36257E-03	.10708E-02
16	15.3947	1.3000	0.	13.608	.23850E-03	.54355E-03
17	16.4211	1.3000	0.	14.634	.16227E-03	.22988E-03
18	17.4474	1.3000	0.	15.660	.11249E-03	.13410E-04

Figure 10.- Continued.

19	18.4737	1.3000	0.	1A.6AA	.79559E-04	-.67255E-04
20	19.5000	1.3000	0.	17.713	.57218E-04	-.11629F-03
21	20.5263	1.3000	0.	1A.719	.41794E-04	-.17943F-03
22	21.5526	1.3000	0.	10.765	.30961E-04	-.95708E-04
23	22.5789	1.3000	0.	20.792	.23266E-04	-.75192E-04
24	23.6053	1.3000	0.	21.81A	.17650E-04	-.54633E-04
25	24.6316	1.3000	0.	22.840	.13558E-04	-.47078E-04
26	25.6579	1.3000	0.	23.871	.10525E-04	-.39532E-04
27	26.6842	1.3000	0.	24.897	.82509E-05	-.35475E-04
28	27.7105	1.3000	0.	25.923	.65280E-05	-.34743E-05
29	28.7368	1.3000	0.	26.950	.52100E-05	-.34327E-05
30	29.7632	1.3000	0.	27.976	.41922E-05	-.35202E-05
31	30.7895	1.3000	0.	29.002	.33993E-05	-.22844E-06
32	31.8158	1.3000	0.	30.029	.27768E-05	-.19378E-06
33	32.8421	1.3000	0.	31.055	.22835E-05	-.25675E-06
34	33.8684	1.3000	0.	32.081	.18903E-05	-.15784E-06
35	34.8947	1.3000	0.	33.108	.15745E-05	-.11691E-07
36	35.9211	1.3000	0.	34.134	.13191E-05	-.12245E-08
37	36.9474	1.3000	0.	35.160	.11112E-05	-.22221E-06
38	37.9737	1.3000	0.	36.186	.94102E-06	-.2A1AAE-06
39	39.0000	1.3000	0.	37.213	0.	0.

PRESSURE COEFFICIENTS AT POINTS ON BODY MERIDIANS

J	THETA, DEG.	XA	YH	ZH	UTOT	VTOT	WTOT	CP,LIN.	CP,ERN.	DR/DX	P/PINF, ERN.	P/PINF, LIN.
BODY RING# 1												
1	11.25000	.51316	.16626	.03307	-.2040A	.36619	.16431	.40615	.31470	.31793	1.63664	1.82164
2	22.50000	.51316	.15662	.06447	-.194AA	.2990A	.22763	.36935	.24369	.31793	1.49299	1.74720
3	33.75000	.51316	.14095	.0941A	-.18471	.20227	.26242	.32942	.1A128	.31793	1.36673	1.66642
4	45.00000	.51316	.11987	.11987	-.14395	.11616	.26874	.29789	.13035	.31793	1.26371	1.58241
5	56.25000	.51316	.0941A	.14095	-.1231A	.04000	.25033	.24637	.09186	.31793	1.18583	1.49840
6	67.50000	.51316	.06447	.15662	-.10322	-.01932	.2138A	.20644	.06525	.31793	1.13200	1.41742
7	78.75000	.51316	.03307	.16626	-.08082	-.05811	.16768	.16964	.04898	.31793	1.09908	1.34318
8	90.00000	.51316	-.00000	.16952	-.04869	-.07629	.12065	.13738	.04083	.31793	1.08261	1.27792
9	101.25000	.51316	-.03307	.16626	-.05545	-.07713	.08050	.11091	.03528	.31793	1.07744	1.22437
10	112.50000	.51316	-.06447	.15662	-.04567	-.08654	.05275	.09124	.03876	.31793	1.07842	1.18458
11	123.75000	.51316	-.09418	.14095	-.03954	-.05195	.03986	.07913	.04007	.31793	1.08107	1.16007
12	135.00000	.51316	-.11987	.11987	-.03752	-.04093	.04093	.07504	.04009	.31793	1.08242	1.15180
13	146.25000	.51316	-.14095	.0941A	-.03956	-.03986	.05195	.07913	.04007	.31793	1.08107	1.14007
14	157.50000	.51316	-.15662	.06447	-.04562	-.05275	.06654	.09124	.03876	.31793	1.07842	1.12458
15	168.75000	.51316	-.16626	.03307	-.05545	-.08050	.07713	.11091	.03528	.31793	1.07744	1.22437
16	180.00000	.51316	-.16952	-.00000	-.06869	-.12065	.07629	.13738	.04083	.31793	1.08261	1.27792
17	191.25000	.51316	-.16626	-.03307	-.08082	-.16768	.05811	.16964	.04898	.31793	1.09908	1.34318
18	202.50000	.51316	-.15662	-.06447	-.10322	-.2138A	.01932	.20644	.06525	.31793	1.13200	1.41742
19	213.75000	.51316	-.14095	-.0941A	-.1231A	-.25033	-.04000	.24637	.09186	.31793	1.18583	1.49840
20	225.00000	.51316	-.11987	-.11987	-.14395	-.26874	-.11616	.28789	.13035	.31793	1.26371	1.58241
21	236.25000	.51316	-.09418	-.14095	-.16471	-.26242	-.20227	.32942	.1A128	.31793	1.36673	1.66642
22	247.50000	.51316	-.06447	-.15662	-.1846A	-.22763	-.28906	.36935	.24369	.31793	1.49299	1.74720
23	258.75000	.51316	-.03307	-.16626	-.2050A	-.16431	-.36619	.40615	.31470	.31793	1.63664	1.82164
24	270.00000	.51316	-.00000	-.16952	-.21920	-.07629	-.42368	.43841	.3A919	.31793	1.7A734	1.88690

Figure 10.- Continued.

25	291,25000	.51316	.03307	-.16626	-.21244	.02907	-.45337	.46488	.46006	.31793	1,93070	1,94005
26	292,50000	.51316	.03307	-.15692	-.24227	.14177	-.45019	.48455	.51904	.31793	2,05002	1,94024
27	303,75000	.51316	.09418	-.14095	-.24833	.25047	-.41274	.49666	.55827	.31793	2,12939	2,00475
28	315,00000	.51316	.11987	-.11987	-.25047	.34397	-.34397	.50075	.57705	.31793	2,15725	2,01302
29	326,25000	.51316	.14004	-.09418	-.24833	.41274	-.25047	.49666	.55827	.31793	2,12939	2,00475
30	347,50000	.51316	.15662	-.06047	-.24227	.45015	-.14177	.48455	.51904	.31793	2,05002	1,94024
31	348,75000	.51316	.16626	-.03307	-.21244	.45337	-.45337	.46488	.46006	.31793	1,93070	1,94005
32	360,00000	.51316	.16952	.00000	-.21920	.42348	.07620	.41841	.38919	.31793	1,78734	1,88690

BODY WINGS 2

1	11,25000	2,56579	.70961	.14115	-.14124	.29954	.18203	.28247	.19422	.22298	1,39291	1,57144
2	22,50000	2,56579	.66843	.27687	-.12479	.21696	.23020	.24959	.12886	.22298	1,28069	1,50401
3	33,75000	2,56579	.60157	.40196	-.10695	.12713	.25530	.21390	.07368	.22298	1,14905	1,43773
4	45,00000	2,56579	.51160	.51160	-.08840	.04161	.24586	.17679	.03113	.22298	1,04297	1,34766
5	56,25000	2,56579	.40196	.60157	-.06984	-.02940	.21090	.13969	.00171	.22298	1,00307	1,28258
6	67,50000	2,56579	.27687	.66843	-.05200	-.07871	.15864	.10400	-.01550	.22298	.98844	1,21040
7	78,75000	2,56579	.14115	.70961	-.03556	-.10271	.09915	.07112	-.02244	.22298	.95460	1,14387
8	90,00000	2,56579	.00000	.72351	-.02115	-.10212	.04229	.04229	-.02170	.22298	.95609	1,08556
9	101,25000	2,56579	-.14115	.70961	-.00932	-.08155	-.00133	.01864	-.01633	.22298	.96695	1,03770
10	112,50000	2,56579	-.27687	.66843	-.00053	-.08843	-.02703	.00106	-.00950	.22298	.98077	1,00214
11	123,75000	2,56579	-.40196	.60157	.00488	-.01272	-.03168	-.00977	-.00406	.22298	.99179	.98024
12	135,00000	2,56579	-.51160	.51160	.00671	.01671	-.01671	-.01342	-.00200	.22298	.94505	.97245
13	146,25000	2,56579	-.60157	.40196	.00888	.03168	.01272	-.00977	-.00406	.22298	.99179	.98024
14	157,50000	2,56579	-.66843	.27687	.00053	.02703	.04863	.00106	-.00950	.22298	.98077	1,00214
15	168,75000	2,56579	-.70961	.14115	-.00932	.00133	.08155	.01864	-.01633	.22298	.96695	1,03770
16	180,00000	2,56579	-.72351	.00000	-.02115	-.04229	.10212	.04229	-.02170	.22298	.95609	1,08556
17	191,25000	2,56579	-.70961	.14115	-.03556	.09915	.10271	.07112	-.02244	.22298	.95460	1,14387
18	202,50000	2,56579	-.66843	.27687	-.05200	.15864	.07871	.10400	-.01550	.22298	.98844	1,21040
19	213,75000	2,56579	-.60157	.40196	-.06984	.21090	.02940	.13969	.00171	.22298	1,00307	1,28258
20	225,00000	2,56579	-.51160	.51160	-.08840	.24586	.04161	.17679	.03113	.22298	1,04297	1,34766
21	236,25000	2,56579	-.40196	.60157	-.10695	.25530	.12713	.21390	.07368	.22298	1,14905	1,43773
22	247,50000	2,56579	-.27687	.66843	-.12479	.23429	.21696	.24959	.12886	.22298	1,28069	1,50401
23	258,75000	2,56579	-.14115	.70961	-.14120	.18203	-.29958	.28247	.19422	.22298	1,39291	1,57144
24	270,00000	2,56579	.00000	.72351	-.15564	-.10212	-.36372	.31130	.26490	.22298	1,53549	1,62975
25	291,25000	2,56579	.14115	.70961	-.16748	-.00223	-.40006	.33495	.33372	.22298	1,67511	1,67761
26	292,50000	2,56579	.27687	.66843	-.17627	.10695	-.40263	.35253	.39199	.22298	1,79299	1,71317
27	303,75000	2,56579	.40196	.60157	-.18188	.21315	-.36971	.36335	.43119	.22298	1,87230	1,73507
28	315,00000	2,56579	.51160	.51160	-.18350	.30418	-.30418	.36701	.44503	.22298	1,90030	1,70246
29	326,25000	2,56579	.60157	.40196	-.18168	.16971	-.21315	.36335	.43119	.22298	1,87230	1,73507
30	337,50000	2,56579	.66843	.27687	-.17627	.40263	-.10695	.35253	.39199	.22298	1,79299	1,71317
31	348,75000	2,56579	.70961	.14115	-.16748	.40006	.00223	.33495	.33372	.22298	1,67511	1,67761
32	360,00000	2,56579	.72351	.00000	-.15565	.36372	.10212	.31130	.26490	.22298	1,53549	1,62975

BODY RINGS 3

1	11,25000	4,61842	1,06771	.21238	-.08033	.22574	.20094	.16066	.06989	.13346	1,14139	1,32501
2	22,50000	4,61842	1,00576	.41660	-.06880	.13775	.24102	.13359	.01221	.13346	1,02471	1,27026
3	33,75000	4,61842	.90516	.50481	-.05211	.04519	.24720	.10423	-.03411	.13346	.91100	1,21045
4	45,00000	4,61842	.76977	.76977	-.03684	-.03919	.22098	.07369	-.06712	.13346	.84223	1,14907
5	56,25000	4,61842	.60441	.90516	-.02157	-.10436	.16857	.04315	-.08669	.13346	.82463	1,08278
6	67,50000	4,61842	.41660	1,00576	-.00689	-.14264	.09977	.01374	-.09400	.13346	.80985	1,02788
7	78,75000	4,61842	.21238	1,06771	.00884	-.15070	.02641	-.01328	-.09112	.13346	.81547	.97313
8	90,00000	4,61842	.00000	1,08843	.01850	-.13084	-.03951	-.04701	-.08092	.13346	.83630	.92514
9	101,25000	4,61842	.21238	1,06771	.02824	-.08677	-.08768	-.05647	-.06693	.13346	.84461	.88575
10	112,50000	4,61842	.41660	1,00576	.03547	-.03020	-.11104	-.07094	-.05303	.13346	.89273	.85409

Figure 10.- Continued.

11	123,75000	4,61842	-.80441	.90516	.03992	.02825	-.10687	-.07985	-.04289	.13346	.91324	.83847
12	135,00000	4,61842	-.76977	.76977	.04103	.07716	-.07716	-.08286	-.03918	.13346	.92073	.83238
13	146,25000	4,61842	-.90516	.60441	.03992	.10687	-.02825	-.07985	-.04289	.13346	.91324	.83847
14	157,50000	4,61842	-1.00576	.41660	.03547	.11104	.03020	-.07094	-.05303	.13346	.89273	.85649
15	168,75000	4,61842	-1.06771	.21238	.02824	.08768	.08677	-.05647	-.06693	.13346	.86461	.88575
16	180,00000	4,61842	-1.02443	.00000	.01850	.13008	.03951	-.04701	-.08092	.13346	.85650	.92514
17	191,25000	4,61842	-1.06771	-.21238	.00644	.02641	.15070	-.01328	-.09112	.13346	.81567	.97313
18	202,50000	4,61842	-1.01576	-.41660	-.00689	-.09977	.14264	.01378	-.09400	.13346	.80985	1.02788
19	213,75000	4,61842	-.90516	-.60441	-.02157	-.16457	.10436	.04315	-.08669	.13346	.82463	1.08729
20	225,00000	4,61842	-.76977	-.76977	-.03644	-.22098	.03919	.07369	-.04712	.13346	.86423	1.14907
21	236,25000	4,61842	-.60441	.90516	-.05211	-.24720	-.04519	.10423	-.03411	.13346	.95100	1.21085
22	247,50000	4,61842	-.41660	-1.00576	-.06680	-.24102	-.13775	.13359	.01221	.13346	1.02471	1.27026
23	258,75000	4,61842	-.21238	-1.06771	-.08033	-.20086	-.22574	.16066	.06499	.13346	1.14139	1.32501
24	270,00000	4,61842	.00000	-1.08863	-.09219	-.13008	-.29660	.18438	.13453	.13346	1.27215	1.37300
25	281,25000	4,61842	.21238	-1.06771	-.10192	-.03661	-.35984	.20345	.19915	.13346	1.40288	1.41238
26	292,50000	4,61842	.41660	-1.00576	-.10916	.06818	-.34857	.21831	.25494	.13346	1.51574	1.44164
27	303,75000	4,61842	.60441	-.90516	-.11361	.17109	-.32064	.22722	.29296	.13346	1.59265	1.45967
28	315,00000	4,61842	.76977	-.76977	-.11511	.25495	-.25895	.23023	.30647	.13346	1.61998	1.46575
29	326,25000	4,61842	.90516	-.60441	-.11361	.32064	-.17108	.22722	.29296	.13346	1.59265	1.45967
30	337,50000	4,61842	1.00576	-.41660	-.10916	.34857	-.06818	.21831	.25494	.13346	1.51574	1.44164
31	348,75000	4,61842	1.06771	-.21238	-.10192	.35983	-.03661	.20345	.19915	.13346	1.40288	1.41238
32	360,00000	4,61842	1.08863	.00000	-.09219	.29660	.13008	.18438	.13453	.13346	1.27215	1.37300

HDDY RING

1	11,25000	6,67105	1.24902	.24845	-.01697	.14328	.22303	.03394	-.06231	.04699	.87392	1.06867
2	22,50000	6,67105	1.17655	.48734	-.00804	.04966	.25004	.01608	-.10916	.04699	.77918	1.03254
3	33,75000	6,67105	1.05887	.70751	.00165	-.04565	.24017	-.00329	-.14409	.04699	.70850	.99334
4	45,00000	6,67105	.90049	.90049	.01172	-.12864	.19587	-.02345	-.16569	.04699	.66481	.95257
5	56,25000	6,67105	.70751	1.05887	.02180	-.18744	.12471	-.04360	-.17404	.04699	.64791	.91180
6	67,50000	6,67105	.48734	1.17655	.03149	-.21365	.03819	-.06298	-.17024	.04699	.65560	.87260
7	78,75000	6,67105	.24845	1.24902	.04022	-.20408	-.05002	-.08084	-.15623	.04699	.68394	.83647
8	90,00000	6,67105	.00000	1.27349	.04825	-.16226	-.12618	-.09649	-.13495	.04699	.72699	.80480
9	101,25000	6,67105	-.24845	1.24902	.05447	-.09406	-.17860	-.10934	-.11043	.04699	.77659	.77881
10	112,50000	6,67105	-.48734	1.17655	.05904	-.01246	-.19939	-.11888	-.08758	.04699	.82282	.75950
11	123,75000	6,67105	-.70751	1.05887	.06238	.07024	-.18570	-.12476	-.07135	.04699	.85566	.74761
12	135,00000	6,67105	-.90049	.90049	.06357	.14011	-.14011	-.12675	-.06547	.04699	.88756	.74359
13	146,25000	6,67105	-1.05887	.70751	.06238	.18570	.07024	-.12476	-.07135	.04699	.85566	.74761
14	157,50000	6,67105	-1.17655	.48734	.05944	.19959	.01296	-.11888	-.08758	.04699	.82282	.75950
15	168,75000	6,67105	-1.24902	.24845	.05467	.17860	.09406	-.10934	-.11043	.04699	.77659	.77881
16	180,00000	6,67105	-1.27349	.00000	.04825	.12618	.16226	-.09649	-.13495	.04699	.72699	.80480
17	191,25000	6,67105	-1.24902	-.24845	.04042	.05002	.20408	-.08084	-.15623	.04699	.68394	.83647
18	202,50000	6,67105	-1.17655	-.48734	.03149	-.03819	.21365	-.06298	-.17024	.04699	.65560	.87260
19	213,75000	6,67105	-1.05887	-.70751	.02180	-.12471	.18734	-.04360	-.17404	.04699	.64791	.91180
20	225,00000	6,67105	-.90049	.90049	.01172	-.19587	.12864	-.02345	-.16569	.04699	.66481	.95257
21	236,25000	6,67105	-.70751	1.05887	.00165	-.24017	.04565	-.00329	-.14409	.04699	.70850	.99334
22	247,50000	6,67105	-.48734	1.17655	-.00804	-.25004	-.04966	.01608	-.10916	.04699	.77918	1.03254
23	258,75000	6,67105	-.24845	1.24902	-.01697	-.22303	.03394	-.06231	.04699	.04699	.87392	1.06867
24	270,00000	6,67105	.00000	1.27349	-.02400	-.16226	.04960	-.09600	-.13499	.04699	.98525	1.10034
25	281,25000	6,67105	.24845	1.24902	-.03122	-.07591	-.27186	.06244	-.04963	.04699	1.10040	1.12632
26	292,50000	6,67105	.48734	1.17655	-.03600	.02393	-.28724	.07149	-.09997	.04699	1.20223	1.14564
27	303,75000	6,67105	.70751	1.05887	-.03893	.12307	-.26476	.07787	-.13482	.04699	1.27274	1.15753
28	315,00000	6,67105	.90049	.90049	-.03993	.20755	-.20755	.07985	.14730	.04699	1.29799	1.16154
29	326,25000	6,67105	1.05887	-.70751	-.03893	.26476	-.17307	.07787	.13482	.04699	1.27274	1.15753
30	337,50000	6,67105	1.17655	-.48734	-.03600	.28724	-.02393	.07149	.09997	.04699	1.20223	1.14564
31	348,75000	6,67105	1.24902	-.24845	-.03122	.27186	.07591	.06244	.04963	.04699	1.10040	1.12632
32	360,00000	6,67105	1.27349	.00000	-.02400	.22127	.16226	.04960	-.09729	.04699	.98525	1.10034

Figure 10.- Continued.

BODY RING# 5

BODY NOSE SEPARATION AT X/RR = 5.52485
 VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = .07510
 VORTEX Y/RLOC (UNROLLED COORDS) = .83291
 VORTEX Z/RLOC (UNROLLED COORDS) = 1.17494

RIGHT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = .07510
 RIGHT VORTEX Y(ROLLED COORDS,1/RLOC) = -.38327
 RIGHT VORTEX Z(ROLLED COORDS,1/RLOC) = 1.27835
 LEFT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = -.07510
 LEFT VORTEX Y(ROLLED COORDS,1/RLOC) = -1.27835
 LEFT VORTEX Z(ROLLED COORDS,1/RLOC) = .38327

1	11,25000	8.72368	1.27502	.25362	.01844	.09244	.24186	-.03692	-.13846	0.00000	.71989	.92531
2	22,50000	8.72368	1.20104	.49749	.02008	.00455	.25906	-.04195	-.17259	0.00000	.65086	.91513
3	33,75000	8.72368	1.08091	.72224	.02371	-.04954	.23610	-.04742	-.19340	0.00000	.60875	.90407
4	45,00000	8.72368	.91924	.91924	.02655	-.17601	.17601	-.05310	-.19873	0.00000	.59797	.89257
5	56,25000	8.72368	.72224	1.08091	.02939	-.21820	.08758	-.05879	-.18674	0.00000	.62223	.88108
6	67,50000	8.72368	.49749	1.20104	.03213	-.21115	-.01531	-.06425	-.15486	0.00000	.68673	.87002
7	78,75000	8.72368	.25362	1.27502	.03484	-.13639	-.11342	-.06929	-.09967	0.00000	.78637	.85983
8	90,00000	8.72368	-.00000	1.30000	.03865	.03919	-.17544	-.07370	-.02991	0.00000	.93950	.85090
9	101,25000	8.72368	-.25362	1.27502	.03865	.31798	-.14709	-.07733	-.03667	0.00000	.92583	.84357
10	112,50000	8.72368	-.49749	1.20104	.04001	.37297	-.09363	-.08002	-.06200	0.00000	.87458	.83812
11	123,75000	8.72368	-.72224	1.08091	.04084	.23609	-.13492	-.08168	-.02545	0.00000	.94852	.83477
12	135,00000	8.72368	-.91924	.91924	.04112	.17544	-.17544	-.08224	-.02079	0.00000	.95795	.83364
13	146,25000	8.72368	-1.08091	.72224	.04084	.13492	-.23609	-.08168	-.02545	0.00000	.98852	.83077
14	157,50000	8.72368	-1.20104	.49749	.04001	.09363	-.37297	-.08002	-.06200	0.00000	.87458	.81812
15	168,75000	8.72368	-1.27502	.25362	.03865	.14709	-.31798	-.07733	-.03667	0.00000	.92583	.84357
16	180,00000	8.72368	-1.30000	-.00000	.03865	.17544	-.03919	-.07370	-.02991	0.00000	.93950	.85090
17	191,25000	8.72368	-1.27502	-.25362	.03484	.11342	-.13639	-.06929	-.09967	0.00000	.78637	.85983
18	202,50000	8.72368	-1.20104	-.49749	.03213	.01531	.21115	-.06425	-.15486	0.00000	.68673	.87002
19	213,75000	8.72368	-1.08091	-.72224	.02939	-.08758	.21820	-.05879	-.18674	0.00000	.62223	.88108
20	225,00000	8.72368	-.91924	-.91924	.02655	-.17601	.17601	-.05310	-.19873	0.00000	.59797	.89257
21	236,25000	8.72368	-.72224	-1.08091	.02371	-.23610	.09954	-.04742	-.19340	0.00000	.60875	.90407
22	247,50000	8.72368	-.49749	-1.20104	.02008	-.25906	.00453	-.04195	-.17259	0.00000	.65086	.91513
23	258,75000	8.72368	-.25362	-1.27502	.01844	-.24186	-.09244	-.03692	-.13846	0.00000	.71989	.92531
24	270,00000	8.72368	.00000	-1.30000	.01625	-.18759	-.17544	-.04250	-.09467	0.00000	.80849	.93475
25	281,25000	8.72368	.25362	-1.27502	.01444	-.10489	-.23121	-.02868	-.04710	0.00000	.90472	.94157
26	292,50000	8.72368	.49749	-1.20104	.01309	-.00468	-.25088	-.02619	-.00372	0.00000	.99247	.94702
27	303,75000	8.72368	.72224	-1.08091	.01227	.09183	-.23132	-.02453	.02686	0.00000	1.05435	.95037
28	315,00000	8.72368	.91924	-.91924	.01199	.17444	-.17544	-.02497	.03792	0.00000	1.07671	.95151
29	326,25000	8.72368	1.08091	-.72224	.01227	.23132	-.09183	-.02453	.02686	0.00000	1.05435	.95037
30	337,50000	8.72368	1.20104	-.49749	.01309	.25088	.00668	-.02619	-.00372	0.00000	.99247	.94702
31	348,75000	8.72368	1.27502	-.25362	.01444	.23121	.10489	-.02868	-.04710	0.00000	.90472	.94157
32	360,00000	8.72368	1.30000	.00000	.01625	.17544	.18759	-.03250	-.09467	0.00000	.80849	.93475

BODY RING# 6

BODY NOSE SEPARATION AT X/RR = 5.52485
 VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINF) = .07701
 VORTEX Y/RLOC (UNROLLED COORDS) = .83679
 VORTEX Z/RLOC (UNROLLED COORDS) = 1.22147

Figure 10.- Continued.

					RIGHT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINP) =	.07701						
					RIGHT VORTEX Y(ROLLED COORDS.)/RLOC =	-.41303						
					RIGHT VORTEX Z(ROLLED COORDS.)/RLOC =	1.31399						
					LEFT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINP) =	-.07701						
					LEFT VORTEX Y(ROLLED COORDS.)/RLOC =	-1.31399						
					LEFT VORTEX Z(ROLLED COORDS.)/RLOC =	.41303						
1	11.25000	10.77632	1.27502	.25362	.01723	.09167	.24573	-.03446	-.13919	0.00000	.71841	.93030
2	22.50000	10.77632	1.20104	.49749	.01669	-.00614	.26294	-.03338	-.16925	0.00000	.65760	.93247
3	33.75000	10.77632	1.08091	.72224	.01611	-.10186	.23957	-.03222	-.18568	0.00000	.62437	.93482
4	45.00000	10.77632	.91924	.91924	.01550	-.17871	.17871	-.03101	-.18601	0.00000	.62371	.93727
5	56.25000	10.77632	.72224	1.08091	.01490	-.22080	.09932	-.02980	-.16797	0.00000	.66019	.93972
6	67.50000	10.77632	.49749	1.20104	.01432	-.21334	-.01441	-.02863	-.17865	0.00000	.73975	.94207
7	78.75000	10.77632	.25362	1.27502	.01378	-.13943	-.11281	-.02756	-.06501	0.00000	.86848	.94424
8	90.00000	10.77632	.00000	1.30000	.01331	-.02598	-.17544	-.02662	.01263	0.00000	1.02553	.94615
9	101.25000	10.77632	-.25362	1.27502	.01292	.27244	-.15615	-.02585	.02547	0.00000	1.05153	.94771
10	112.50000	10.77632	-.49749	1.20104	.01244	.34955	-.10333	-.02528	-.00024	0.00000	.99952	.94887
11	123.75000	10.77632	-.72224	1.08091	.01206	.24047	-.13199	-.02492	.03044	0.00000	1.06158	.94958
12	135.00000	10.77632	-.91924	.91924	.01170	.17544	-.17544	-.02480	.03706	0.00000	1.07497	.94982
13	146.25000	10.77632	-1.08091	.72224	.01144	.13199	-.24047	-.02492	.03044	0.00000	1.06158	.94958
14	157.50000	10.77632	-1.20104	.49749	.01126	.10333	-.34955	-.02528	-.00024	0.00000	.99952	.94887
15	168.75000	10.77632	-1.27502	.25362	.01122	.15615	-.27244	-.02585	.02547	0.00000	1.05153	.94771
16	180.00000	10.77632	-1.30000	.00000	.01131	.17544	-.02598	-.02662	.01263	0.00000	1.02553	.94615
17	191.25000	10.77632	-1.27502	-.25362	.01378	.11281	.13943	-.02756	-.06501	0.00000	.86848	.94424
18	202.50000	10.77632	-1.20104	-.49749	.01432	.01441	.21334	-.02863	-.12865	0.00000	.73975	.94207
19	213.75000	10.77632	-1.08091	-.72224	.01490	-.08952	.22080	-.02980	-.16797	0.00000	.66019	.93972
20	225.00000	10.77632	-.91924	-.91924	.01550	-.17871	.17871	-.03101	-.18601	0.00000	.62371	.93727
21	236.25000	10.77632	-.72224	-1.08091	.01611	-.23957	.10186	-.03222	-.18568	0.00000	.62437	.93482
22	247.50000	10.77632	-.49749	-1.20104	.01669	-.26294	.00614	-.03338	-.16925	0.00000	.65760	.93247
23	258.75000	10.77632	-.25362	-1.27502	.01723	-.24573	-.09167	-.03446	-.13919	0.00000	.71841	.93030
24	270.00000	10.77632	.00000	-1.30000	.01770	-.19104	-.17544	-.03540	-.09925	0.00000	.79422	.92839
25	281.25000	10.77632	.25362	-1.27502	.01808	-.10759	-.23174	-.03617	-.05520	0.00000	.88833	.92683
26	292.50000	10.77632	.49749	-1.20104	.01837	-.00846	-.25162	-.03674	-.01473	0.00000	.97021	.92567
27	303.75000	10.77632	.72224	-1.08091	.01855	.09101	-.23186	-.03709	.01392	0.00000	1.02817	.92496
28	315.00000	10.77632	.91924	-.91924	.01868	.17544	-.17544	-.03721	.02430	0.00000	1.04915	.92472
29	326.25000	10.77632	1.08091	-.72224	.01855	.23186	-.09101	-.03709	.01392	0.00000	1.02817	.92496
30	337.50000	10.77632	1.20104	-.49749	.01837	.25162	.00846	-.03674	-.01473	0.00000	.97021	.92567
31	348.75000	10.77632	1.27502	-.25362	.01808	.23174	.10759	-.03617	-.05520	0.00000	.88833	.92683
32	360.00000	10.77632	1.30000	.00000	.01770	.17544	.19104	-.03540	-.09925	0.00000	.79422	.92839

BODY RING# 7

BODY NOSE SEPARATION AT XB/RB	=	5.52485
VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINP)	=	.07891
VORTEX Y/RLOC (UNROLLED COORDS)	=	.64087
VORTEX Z/RLOC (UNROLLED COORDS)	=	1.24800

RIGHT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINP)	=	.07891
RIGHT VORTEX Y(ROLLED COORDS.)/RLOC	=	-.44345
RIGHT VORTEX Z(ROLLED COORDS.)/RLOC	=	1.34977
LEFT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINP)	=	-.07891
LEFT VORTEX Y(ROLLED COORDS.)/RLOC	=	-1.34977
LEFT VORTEX Z(ROLLED COORDS.)/RLOC	=	.44345

1	11.25000	12.82895	1.27502	.25362	.01336	.09328	.23765	-.02672	-.12754	0.00000	.74199	.94594
2	22.50000	12.82895	1.20104	.49749	.01226	-.00257	.25433	-.02452	-.15614	0.00000	.68412	.95030

Figure 10.- Continued.

3	33,75000	12,82895	1,08091	.72224	.01197	-.00422	.23113	-.02214	-.17124	0,00000	.64354	.94522
4	45,00000	12,82895	.91924	.91924	.00983	-.17112	.17112	-.01945	-.17022	0,00000	.65444	.94624
5	56,25000	12,82895	.72224	1,04071	.00983	-.21166	.00321	-.01717	-.15079	0,00000	.60495	.94624
6	67,50000	12,82895	.49749	1,20104	.00739	-.20434	-.01850	-.01478	-.11026	0,00000	.77695	.97010
7	78,75000	12,82895	.25362	1,27502	.00629	-.15127	-.11444	-.01258	-.04674	0,00000	.90544	.97455
8	90,00000	12,82895	.00000	1,30000	.00533	.02363	-.17544	-.01065	.02799	0,00000	1,04663	.97845
9	101,25000	12,82895	-.25362	1,27502	.00454	.24321	-.14196	-.00907	.04810	0,00000	1,09731	.98165
10	112,50000	12,82895	-.49749	1,20104	.00395	.32994	-.11145	-.00790	.02477	0,00000	1,09612	.98603
11	123,75000	12,82895	-.72224	1,08091	.00359	.24358	-.12992	-.00717	.04813	0,00000	1,09736	.98449
12	135,00000	12,82895	-.91924	.91924	.00346	.17544	-.17544	-.00693	.05568	0,00000	1,11264	.98599
13	146,25000	12,82895	-1,08091	.72224	.00359	.12992	-.24358	-.00717	.04813	0,00000	1,09736	.98549
14	157,50000	12,82895	-1,20104	.49749	.00395	.11145	-.32994	-.00790	.02477	0,00000	1,09612	.98403
15	168,75000	12,82895	-1,27502	.25362	.00454	.14196	-.24321	-.00907	.04810	0,00000	1,09731	.98165
16	180,00000	12,82895	-1,30000	.00000	.00533	.17544	-.02363	-.01065	.02799	0,00000	1,05663	.97845
17	191,25000	12,82895	-1,27502	-.25362	.00429	.11444	.14127	-.01258	-.04674	0,00000	.90544	.97455
18	202,50000	12,82895	-1,20104	-.49749	.00739	.10450	.20346	-.01478	-.11026	0,00000	.77695	.97010
19	213,75000	12,82895	-1,08091	-.72224	.00844	.08321	.21166	-.01717	-.15079	0,00000	.60495	.94624
20	225,00000	12,82895	-.91924	-.91924	.00983	-.17112	.17112	-.01945	-.17022	0,00000	.65444	.94624
21	236,25000	12,82895	-.72224	-1,08091	.01107	-.23113	.04622	-.02214	-.17124	0,00000	.64354	.94522
22	247,50000	12,82895	-.49749	-1,20104	.01226	-.25433	.00257	-.02452	-.15614	0,00000	.60412	.95039
23	258,75000	12,82895	-.25362	-1,27502	.01336	-.23765	-.09328	-.02672	-.12754	0,00000	.70199	.94594
24	270,00000	12,82895	.00000	-1,30000	.01433	-.18411	-.17544	-.02865	-.04423	0,00000	.81988	.94204
25	281,25000	12,82895	.25362	-1,27502	.01512	-.10230	-.23069	-.03023	-.04694	0,00000	.90503	.93844
26	292,50000	12,82895	.49749	-1,20104	.01570	-.00504	-.25020	-.03141	-.00813	0,00000	.98356	.93646
27	303,75000	12,82895	.72224	-1,08091	.01607	.09257	-.25082	-.04213	-.01932	0,00000	1,03909	.93499
28	315,00000	12,82895	.91924	-.91924	.01619	.17544	-.17544	-.03238	.02925	0,00000	1,05918	.93450
29	326,25000	12,82895	1,08091	-.72224	.01607	.23062	-.09257	-.03213	.01932	0,00000	1,03909	.93499
30	337,50000	12,82895	1,20104	-.49749	.01570	.25020	-.00504	-.03141	-.00813	0,00000	.98356	.93646
31	348,75000	12,82895	1,27502	-.25362	.01512	.23069	.10230	-.03023	-.04694	0,00000	.90503	.93844
32	360,00000	12,82895	1,30000	.00000	.01433	.17544	.18411	-.02865	-.04423	0,00000	.81988	.94204

NOSE PING= A

NOSE PING SEPARATION AT X/RH	=	4,52845
VORTEX STRENGTH GAMMA/(2*PI*RLC*VINF)	=	.00082
VORTEX Y/RLC (UNROLLED COURSES)	=	.64591
VORTEX Z/RLC (UNROLLED COURSES)	=	1,31451

RIGHT VORTEX STRENGTH GAMMA/(2*PI*RLC*VINF)	=	.00082
RIGHT VORTEX Y(ROLLED COURSES,)/RLC	=	-.47279
RIGHT VORTEX Z(ROLLED COURSES,)/RLC	=	1,38624
LEFT VORTEX STRENGTH GAMMA/(2*PI*RLC*VINF)	=	-.00082
LEFT VORTEX Y(ROLLED COURSES,)/RLC	=	-1,38624
LEFT VORTEX Z(ROLLED COURSES,)/RLC	=	.47279

1	11,25000	14,88158	1,27502	.25362	.00928	.09490	.22946	-.01855	-.11532	0,00000	.78670	.94247
2	22,50000	14,88158	1,20104	.49749	.00808	.06103	.24562	-.01691	-.14371	0,00000	.70927	.94579
3	33,75000	14,88158	1,08091	.72224	.00757	-.09054	.22262	-.01513	-.15873	0,00000	.60939	.94939
4	45,00000	14,88158	.91924	.91924	.00644	-.16351	.16351	-.01328	-.15776	0,00000	.60084	.97314
5	56,25000	14,88158	.72224	1,08091	.00571	-.20245	.07712	-.01143	-.13858	0,00000	.71965	.97689
6	67,50000	14,88158	.49749	1,20104	.00482	-.19377	-.02251	-.00984	-.04890	0,00000	.79993	.98009
7	78,75000	14,88158	.25362	1,27502	.00400	-.12339	-.11400	-.00800	-.03793	0,00000	.92326	.98391
8	90,00000	14,88158	.00000	1,30000	.00328	.02217	-.17544	-.00656	.03149	0,00000	1,06410	.98472
9	101,25000	14,88158	-.25362	1,27502	.00269	.22012	-.16654	-.00438	.05492	0,00000	1,11111	.99011
10	112,50000	14,88158	-.49749	1,20104	.00225	.31040	-.11955	-.00451	.03517	0,00000	1,07114	.99089
11	123,75000	14,88158	-.72224	1,08091	.00198	.24356	-.12993	-.00397	.05147	0,00000	1,10412	.99198
12	135,00000	14,88158	-.91924	.91924	.00189	.17544	-.17544	-.00378	.05899	0,00000	1,11933	.99255

Figure 10.- Continued.

13	146,25000	14,88158	-1,00091	.72224	.00198	.12993	-.24356	-.00397	.05147	0,00000	1,17412	.99198
14	157,50000	14,88158	-1,20104	.49749	.00224	.11954	-.31040	-.00451	.03517	0,00000	1,07114	.99089
15	168,75000	14,88158	-1,27502	.25362	.00249	.10654	-.22012	-.00538	.05492	0,00000	1,11111	.98911
16	180,00000	14,88158	-1,30000	.00000	.00328	.17544	-.02217	-.00654	.03169	0,00000	1,06410	.98672
17	191,25000	14,88158	-1,27502	-.25362	.00400	.11600	.12339	-.00800	-.03793	0,00000	.92326	.98381
18	202,50000	14,88158	-1,20104	-.49749	.00482	.02251	.19377	-.00964	-.00890	0,00000	.79993	.98049
19	213,75000	14,88158	-1,00091	-.72224	.00571	-.07712	.20255	-.01143	-.13858	0,00000	.71965	.97689
20	225,00000	14,88158	-.91924	-.91924	.00664	-.16351	.18351	-.01328	-.15776	0,00000	.68044	.97314
21	236,25000	14,88158	-.72224	-1,08091	.00757	-.22262	.09054	-.01513	-.15873	0,00000	.67888	.96939
22	247,50000	14,88158	-.49749	-1,20104	.00846	-.24562	-.00103	-.01691	-.14371	0,00000	.70927	.96579
23	258,75000	14,88158	-.25362	-1,27502	.00928	-.22944	-.09490	-.01855	-.11532	0,00000	.76670	.96249
24	270,00000	14,88158	.00000	-1,30000	.01000	-.17709	-.17544	-.01499	-.07743	0,00000	.84337	.95956
25	281,25000	14,88158	.25362	-1,27502	.01059	-.09693	-.22962	-.02117	-.03571	0,00000	.92775	.95717
26	292,50000	14,88158	.49749	-1,20104	.01102	-.00157	-.24877	-.02205	-.00247	0,00000	1,00500	.95539
27	303,75000	14,88158	.72224	-1,08091	.01130	.09416	-.22976	-.02259	.02942	0,00000	1,05952	.95430
28	315,00000	14,88158	.91924	-.91924	.01139	.17544	-.02277	-.02277	.05916	0,00000	1,07922	.95393
29	326,25000	14,88158	1,00091	-.72224	.01130	.22976	-.09416	-.02259	.02942	0,00000	1,05952	.95430
30	337,50000	14,88158	1,20104	-.49749	.01102	.24877	.00157	-.02205	.00247	0,00000	1,00500	.95539
31	348,75000	14,88158	1,27502	-.25362	.01059	.22962	.09693	-.02117	-.03571	0,00000	.92775	.95717
32	360,00000	14,88158	1,30000	.00000	.01000	.17544	.17709	-.01499	-.07743	0,00000	.84337	.95956

RODY RINGS 9

RODY HOSE SEPARATION AT XH/RB = 5,52485
 VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINFL) = .08272
 VORTEX Y/RLOC (UNROLLED COORDS) = .65095
 VORTEX Z/RLOC (UNROLLED COORDS) = 1,36106

RIGHT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINFL) = .08272
 RIGHT VORTEX Y(ROLLED COORDS,)/RLOC = -.50213
 RIGHT VORTEX Z(ROLLED COORDS,)/RLOC = 1,42271
 LEFT VORTEX STRENGTH GAMMA/(2*PI*RLOC*VINFL) = -.08272
 LEFT VORTEX Y(ROLLED COORDS,)/RLOC = -1,42271
 LEFT VORTEX Z(ROLLED COORDS,)/RLOC = .50213

1	11,25000	16,93421	1,27502	.25362	.00617	.09596	.22413	-.01234	-.10656	0,00000	.78443	.97504
2	22,50000	16,93421	1,20104	.49749	.00572	.00339	.23992	-.01144	-.13511	0,00000	.72668	.97687
3	33,75000	16,93421	1,00091	.72224	.00523	-.08678	.21701	-.01046	-.15036	0,00000	.69592	.97824
4	45,00000	16,93421	.91924	.91924	.00472	-.15845	.15845	-.00944	-.14971	0,00000	.69714	.98090
5	56,25000	16,93421	.72224	1,08091	.00421	-.19647	.07306	-.00842	-.13103	0,00000	.73493	.98296
6	67,50000	16,93421	.49749	1,20104	.00372	-.18740	-.02515	-.00745	-.09241	0,00000	.81306	.98493
7	78,75000	16,93421	.25362	1,27502	.00327	-.11886	.11690	-.00655	-.03396	0,00000	.93130	.98676
8	90,00000	16,93421	.00000	1,30000	.00288	.01863	-.17544	-.00576	.01137	0,00000	1,00346	.98835
9	101,25000	16,93421	-.25362	1,27502	.00254	.19951	-.17066	-.00511	.05697	0,00000	1,11504	.98966
10	112,50000	16,93421	-.49749	1,20104	.00231	.29103	-.12757	-.00463	.04108	0,00000	1,08311	.99064
11	123,75000	16,93421	-.72224	1,08091	.00217	.24097	-.13166	-.00433	.05163	0,00000	1,10445	.99174
12	135,00000	16,93421	-.91924	.91924	.00212	.17544	-.17544	-.00423	.05852	0,00000	1,11858	.99144
13	146,25000	16,93421	-1,00091	.72224	.00217	.13166	.24097	-.00433	.05163	0,00000	1,10445	.99174
14	157,50000	16,93421	-1,20104	.49749	.00211	.12757	-.29103	-.00463	.04108	0,00000	1,08311	.99064
15	168,75000	16,93421	-1,27502	.25362	.00255	.17066	-.19951	-.00511	.05697	0,00000	1,11504	.98966
16	180,00000	16,93421	-1,30000	.00000	.00288	.17544	-.17544	-.00576	.03137	0,00000	1,06346	.98835
17	191,25000	16,93421	-1,27502	-.25362	.00327	.11690	.11886	-.00655	-.03396	0,00000	.93130	.98676
18	202,50000	16,93421	-1,20104	-.49749	.00372	.02515	.18740	-.00745	-.09241	0,00000	.81306	.98493
19	213,75000	16,93421	-1,00091	-.72224	.00421	-.07306	.19647	-.00842	-.13103	0,00000	.73493	.98296
20	225,00000	16,93421	-.91924	-.91924	.00472	-.15845	.15845	-.00944	-.14971	0,00000	.69714	.98090
21	236,25000	16,93421	-.72224	-1,08091	.00523	-.21701	.08678	-.01046	-.15036	0,00000	.69592	.97824
22	247,50000	16,93421	-.49749	-1,20104	.00572	-.23992	-.00339	-.01144	-.13511	0,00000	.72668	.97687

Figure 10.- Continued.

23	258,75000	16,93421	-.25362	-1,27502	.00617	-.22413	-.09594	-.01244	-.16656	0,00000	.78444	.97504
24	270,00000	16,93421	0,00000	-1,30000	.00696	-.17254	-.17544	-.01313	-.06861	0,00000	.86120	.97345
25	281,25000	16,93421	-.25362	-1,27502	.00649	-.02306	-.22891	-.01377	-.07695	0,00000	.94547	.97214
26	292,50000	16,93421	-.49749	-1,20104	.00713	.00000	-.24784	-.01426	-.01110	0,00000	1,02245	.97116
27	303,75000	16,93421	-.72224	-1,08091	.00728	.09518	-.22908	-.01455	-.03792	0,00000	1,07670	.97056
28	315,00000	16,93421	-.91924	-.91924	.00713	.17544	-.17544	-.01445	-.04760	0,00000	1,09639	.97016
29	326,25000	16,93421	-1,08091	-.72224	.00728	.22908	-.09518	-.01455	-.03792	0,00000	1,07670	.97056
30	337,50000	16,93421	-1,20104	-.49749	.00713	.24784	-.00000	-.01426	-.01110	0,00000	1,02245	.97116
31	348,75000	16,93421	-.25362	-1,27502	.00649	.22891	-.09346	-.01377	-.02695	0,00000	.94547	.97214
32	360,00000	16,93421	0,00000	-.00000	.00696	.17544	.17544	-.01313	-.06861	0,00000	.86120	.97345

BODY RING 10

BODY NOSE SEPARATION AT XM/NH	=	5,52445
VORTEX STRENGTH GAMMA/(2*PI*RLC*VINF)	=	.08688
VORTEX Y/RLOC (CONTROLLED CHORDS)	=	.45576
VORTEX Z/RLOC (CONTROLLED CHORDS)	=	1,40759

RIGHT VORTEX STRENGTH GAMMA/(2*PI*RLC*VINF)	=	.08688
RIGHT VORTEX Y/RLOC (CONTROLLED CHORDS, 1/RLOC)	=	-.53143
RIGHT VORTEX Z/RLOC (CONTROLLED CHORDS, 1/RLOC)	=	1,45901
LEFT VORTEX STRENGTH GAMMA/(2*PI*RLC*VINF)	=	-.08688
LEFT VORTEX Y/RLOC (CONTROLLED CHORDS, 1/RLOC)	=	-1,45901
LEFT VORTEX Z/RLOC (CONTROLLED CHORDS, 1/RLOC)	=	.53143

1	11,25000	18,98684	1,27502	.25362	.00616	.09660	.22095	-.00632	-.10104	0,00000	.79560	.98318
2	22,50000	18,98684	1,20104	.49749	.00395	.00485	.21640	-.00791	-.12464	0,00000	.71774	.98401
3	33,75000	18,98684	1,08091	.72224	.00373	-.00436	.21339	-.00746	-.14404	0,00000	.70679	.98491
4	45,00000	18,98684	.91924	.91924	.00350	-.15498	.15498	-.00700	-.14430	0,00000	.70880	.98544
5	56,25000	18,98684	.72224	1,08091	.00327	-.19196	.17004	-.00653	-.12567	0,00000	.74577	.98678
6	67,50000	18,98684	.49749	1,20104	.00304	-.18211	-.02734	-.00609	-.08742	0,00000	.82315	.98748
7	78,75000	18,98684	-.25362	1,27502	.00280	-.11911	-.11785	-.00568	-.01045	0,00000	.93444	.98851
8	90,00000	18,98684	-.00000	1,30000	.00266	.01843	-.17544	-.00532	.03175	0,00000	1,08423	.98924
9	101,25000	18,98684	-.25362	1,27502	.00241	.18601	-.17295	-.00503	.05706	0,00000	1,011625	.98983
10	112,50000	18,98684	-.49749	1,20104	.00200	.27961	-.13230	-.00481	.04404	0,00000	1,08910	.99028
11	123,75000	18,98684	-.72224	1,08091	.00234	.24039	-.13295	-.00467	.05139	0,00000	1,01397	.99055
12	135,00000	18,98684	-.91924	.91924	.00231	.17544	-.17544	-.00463	.05810	0,00000	1,011754	.99064
13	146,25000	18,98684	-1,08091	.72224	.00210	.15265	-.24039	-.00467	.05139	0,00000	1,01397	.99055
14	157,50000	18,98684	-1,20104	.49749	.00210	.15230	-.27961	-.00441	.04404	0,00000	1,08910	.99028
15	168,75000	18,98684	-1,27502	.25362	.00241	.17295	-.18601	-.00503	.05706	0,00000	1,011625	.98983
16	180,00000	18,98684	-.00000	1,30000	.00266	.17544	-.01843	-.00532	.03175	0,00000	1,08423	.98924
17	191,25000	18,98684	-1,27502	-.25362	.00280	.11785	.11411	-.00568	-.03043	0,00000	.93444	.98851
18	202,50000	18,98684	-1,20104	.49749	.00304	.02714	.18211	-.00609	-.08742	0,00000	.82315	.98748
19	213,75000	18,98684	-.91924	.91924	.00327	-.07004	.19196	-.00653	-.12567	0,00000	.74577	.98678
20	225,00000	18,98684	-.72224	.91924	.00350	-.15498	.15498	-.00700	-.14430	0,00000	.70880	.98544
21	236,25000	18,98684	-.49749	1,08091	.00373	-.21339	.08436	-.00746	-.14404	0,00000	.70679	.98491
22	247,50000	18,98684	-.25362	1,20104	.00405	-.23440	-.00485	-.00791	-.12464	0,00000	.71774	.98401
23	258,75000	18,98684	0,00000	-1,27502	.00616	-.22095	-.09660	-.00632	-.10104	0,00000	.79560	.98318
24	270,00000	18,98684	0,00000	-1,30000	.00696	-.17544	-.16949	-.00667	-.06304	0,00000	.86120	.98245
25	281,25000	18,98684	-.25362	-1,27502	.00649	-.09147	-.22854	-.00687	-.07137	0,00000	.94547	.98145
26	292,50000	18,98684	-.49749	-1,20104	.00699	.00193	-.24732	-.00699	-.01666	0,00000	1,03371	.98141
27	303,75000	18,98684	-.72224	-1,08091	.00746	.04575	-.22869	-.00632	-.04345	0,00000	1,08790	.98114
28	315,00000	18,98684	-.91924	-.91924	.00746	.17544	-.17544	-.00637	-.05312	0,00000	1,010746	.98105
29	326,25000	18,98684	-1,08091	-.72224	.00746	.22869	-.09575	-.00632	-.04345	0,00000	1,08790	.98114

Figure 10.- Continued.

30	337,50000	1A,9A6d4	1,20104	-.49749	.00050	.24732	-.00193	-.00919	.01666	0,00000	1,03371	.98141
31	344,75000	1A,9A8A4	1,27502	-.25362	.0005A	.22854	.09147	-.00897	-.02137	0,00000	.95677	.98145
32	349,00000	1A,9B6H4	1,30000	.00000	.00054	.17544	.16969	-.00867	-.06304	0,00000	.87247	.98245

TOTAL NUMBER OF PRESSURE POINTS,JCPT= 320

POINT COORDINATES AND PERTURBATION VELOCITIES CALCULATED BY PROGRAM VPATM2OR VPATM1

IC	XCP	YCP	ZCP	VVEL(IC)	WVEL(IC)
1	21,05100	1,53100	0,00000	.21094E+02	-.70848E+02
2	22,18700	1,53100	0,00000	.27417E+02	-.73904E+02
3	23,34200	1,53100	0,00000	.23375E+02	-.77102E+02
4	21,21600	1,99870	0,00000	.40063E+02	-.404570E+02
5	22,28100	1,99870	0,00000	.41696E+02	-.46394E+02
6	23,34700	1,99870	0,00000	.43302E+02	-.49259E+02
7	21,40000	2,46640	0,00000	.43472E+02	-.26581E+02
8	22,37600	2,46640	0,00000	.44995E+02	-.27581E+02
9	23,35100	2,46640	0,00000	.46627E+02	-.28607E+02
10	21,58500	2,93400	0,00000	.41108E+02	-.14995E+02
11	22,47000	2,93400	0,00000	.42595E+02	-.15510E+02
12	23,35600	2,93400	0,00000	.44001E+02	-.16042E+02
13	21,76900	3,40160	0,00000	.47321E+02	-.76348E+03
14	22,56500	3,40160	0,00000	.38456E+02	-.78743E+03
15	23,36000	3,40160	0,00000	.39599E+02	-.81257E+03
16	21,03100	-1,53100	0,00000	-.76740E+01	-.17026E+00
17	22,18700	-1,53100	0,00000	-.76729E+01	-.17591E+00
18	23,34200	-1,53100	0,00000	-.75708E+01	-.18067E+00
19	21,21600	1,99870	0,00000	-.13321E+00	-.38446E+01
20	22,28100	1,99870	0,00000	-.13885E+00	-.42546E+01
21	23,34700	1,99870	0,00000	-.14371E+00	-.47503E+01
22	21,40000	2,46640	0,00000	-.76287E+01	.33042E+01
23	22,37600	2,46640	0,00000	-.80075E+01	.30808E+01
24	23,35100	2,46640	0,00000	-.84175E+01	.35741E+01
25	21,58500	2,93400	0,00000	-.32972E+01	.36666E+01
26	22,47000	2,93400	0,00000	-.34252E+01	.37988E+01
27	23,35600	2,93400	0,00000	-.35706E+01	.39482E+01
28	21,76900	3,40160	0,00000	-.14196E+01	.27926E+01
29	22,56500	3,40160	0,00000	-.14621E+01	.28902E+01
30	23,36000	3,40160	0,00000	-.15118E+01	.29897E+01
31	21,05100	0,00000	1,53100	.17026E+00	.76740E+01
32	22,18700	0,00000	1,53100	.17591E+00	.76729E+01
33	23,34200	0,00000	1,53100	.18067E+00	.75708E+01
34	21,21600	0,00000	1,99870	.38446E+01	.13321E+00
35	22,28100	0,00000	1,99870	.42546E+01	.13885E+00
36	23,34700	0,00000	1,99870	.47503E+01	.14371E+00
37	21,40000	0,00000	2,46640	.33042E+01	.76287E+01
38	22,37600	0,00000	2,46640	.30808E+01	.80075E+01
39	23,35100	0,00000	2,46640	.35741E+01	.84175E+01
40	21,58500	0,00000	2,93400	.36666E+01	.32972E+01
41	22,47000	0,00000	2,93400	.37988E+01	.34252E+01
42	23,35600	0,00000	2,93400	.39482E+01	.35706E+01
43	21,76900	0,00000	3,40160	.27926E+01	.14196E+01
44	22,56500	0,00000	3,40160	.28902E+01	.14621E+01
45	23,36000	0,00000	3,40160	.29897E+01	.15118E+01
46	21,03100	0,00000	-1,53100	.76740E+02	-.21499E+02

Figure 10.- Continued.

47	22,14700	-.00000	-1,53100	.73004E-02	-.22417E-02
48	21,14700	-.00000	-1,53100	.77102E-02	-.23375E-02
49	21,21600	-.00000	-1,99070	.04570E-02	-.40063E-02
50	22,24100	-.00000	-1,99070	.46394E-02	-.41496E-02
51	23,14700	-.00000	-1,99070	.48254E-02	-.43302E-02
52	21,40000	-.00000	-2,46040	.26541E-02	-.43372E-02
53	22,37600	-.00000	-2,46040	.27541E-02	-.44495E-02
54	23,45100	-.00000	-2,46040	.28607E-02	-.44427E-02
55	21,58500	-.00000	-2,93000	.14995E-02	-.41198E-02
56	22,47000	-.00000	-2,93000	.15510E-02	-.42495E-02
57	23,35600	-.00000	-2,93000	.16042E-02	-.44001E-02
58	21,78900	-.00000	-3,40160	.76384E-03	-.37321E-02
59	22,56500	-.00000	-3,40160	.78703E-03	-.34056E-02
60	23,36000	-.00000	-3,40160	.81237E-03	-.39599E-02
61	20,94000	1,25050	.24874	.20095E-02	-.12229E-01
62	20,94000	1,00010	.70836	.12910E-01	-.20845E-01
63	20,94000	.70836	1,00010	.42443E-01	-.31116E-01
64	20,94000	.24874	1,25050	.12886E-00	-.32286E-01
65	20,94000	-.24874	1,25050	.32964E+00	-.54337E-01
66	20,94000	-.70836	1,00010	.16614E+00	-.13512E+00
67	20,94000	-1,00010	.70836	-.13512E+00	-.14618E+00
68	20,94000	-1,25050	.24874	-.55337E-01	-.32964E+00
69	20,94000	-1,25050	-.24874	.32246E-01	-.12886E+00
70	20,94000	-1,00010	-.70836	.31116E-01	-.42643E-01
71	20,94000	-.70836	-1,00010	.20845E-01	-.12914E-01
72	20,94000	-.24874	-1,25050	.12229E-01	-.20095E-02
73	20,94000	.24874	-1,25050	.54242E-02	.14027E-02
74	20,94000	.70836	-1,00010	.13956E-02	.11524E-02
75	20,94000	1,00010	-.70836	-.11524E-02	-.13956E-02
76	20,94000	1,25050	-.24874	-.14027E-02	-.54242E-02
77	22,14000	1,25050	.24874	.20985E-02	-.12770E-01
78	22,14000	1,00010	.70836	.13486E-01	-.21794E-01
79	22,14000	.70836	1,00010	.44444E-01	-.32424E-01
80	22,14000	.24874	1,25050	.13321E+00	-.33330E-01
81	22,14000	-.24874	1,25050	.32994E+00	-.56340E-01
82	22,14000	-.70836	1,00010	.15030E+00	-.12975E+00
83	22,14000	-1,00010	.70836	-.12975E+00	-.15934E+00
84	22,14000	-1,25050	.24874	-.56340E-01	-.32994E+00
85	22,14000	-1,25050	-.24874	.33310E-01	-.13321E+00
86	22,14000	-1,00010	-.70836	.32424E-01	-.44444E-01
87	22,14000	-.70836	-1,00010	.21794E-01	-.13486E-01
88	22,14000	-.24874	-1,25050	.12770E-01	-.20985E-02
89	22,14000	.24874	-1,25050	.60880E-02	.14706E-02
90	22,14000	.70836	-1,00010	.14575E-02	.12035E-02
91	22,14000	1,00010	-.70836	-.12035E-02	-.14575E-02
92	22,14000	1,25050	-.24874	-.14706E-02	-.60880E-02
93	23,34000	1,25050	.24874	.21726E-02	-.13406E-01
94	23,34000	1,00010	.70836	.14077E-01	-.22751E-01
95	23,34000	.70836	1,00010	.46275E-01	-.33741E-01
96	23,34000	.24874	1,25050	.13737E+00	-.32339E-01
97	23,34000	-.24874	1,25050	.32702E+00	-.58777E-01
98	23,34000	-.70836	1,00010	.15241E+00	-.12413E+00
99	23,34000	-1,00010	.70836	-.12413E+00	-.15241E+00
100	23,34000	-1,25050	.24874	-.58777E-01	-.32742E+00
101	23,34000	-1,25050	-.24874	.42304E-01	-.13737E+00
102	23,34000	-1,00010	-.70836	.33741E-01	-.46275E-01
103	23,34000	-.70836	-1,00010	.22751E-01	-.14077E-01
104	23,34000	-.24874	-1,25050	.13406E-01	-.21726E-02
105	23,34000	.24874	-1,25050	.63609E-02	.15364E-02

Figure 10.- Continued.

106	23.34000	.70836	-1.06010	.15235E-02	.1279E-02
107	23.34000	1.06010	-.70836	-.1279E-02	-.15235E-02
108	23.34000	1.25050	-.24474	-.15349E-02	-.63604E-02

CONTROL POINT COORDINATES FOR 3 CHORDWISE BY 5 SPANWISE PANELS ON WING 1 OR R, 5 SPANWISE ON WING 2 OR L
AND 5 SPANWISE PANELS ON WING 3 OR U, 5 SPANWISE ON WING 4 OR D

J	X(J)	Y(J)	Z(J)	RU(J)	RV(J)	RW(J)	VVRTX	WVRTX
1	1.23112	1.53096	0.00000	.30415E-02	.12608E+00	.12749E+00	0.	0.
2	2.38667	1.53096	0.00000	.25619E-02	.12617E+00	.12768E+00	0.	0.
3	3.54222	1.53096	0.00000	.22035E-02	.12622E+00	.12755E+00	0.	0.
4	1.41565	1.99870	0.00000	.30173E-02	.73266E-01	.75357E-01	0.	0.
5	2.48119	1.99870	0.00000	.25678E-02	.73453E-01	.75200E-01	0.	0.
6	3.54672	1.99870	0.00000	.22281E-02	.73581E-01	.75098E-01	0.	0.
7	1.60017	2.46640	0.00000	.30518E-02	.47405E-01	.49768E-01	0.	0.
8	2.57570	2.46640	0.00000	.26235E-02	.47650E-01	.49633E-01	0.	0.
9	3.55122	2.46640	0.00000	.22924E-02	.47827E-01	.49541E-01	0.	0.
10	1.78466	2.93403	0.00000	.31062E-02	.32808E-01	.35417E-01	0.	0.
11	2.67019	2.93403	0.00000	.26949E-02	.33091E-01	.35293E-01	0.	0.
12	3.55572	2.93403	0.00000	.23729E-02	.33299E-01	.35206E-01	0.	0.
13	1.96912	3.40158	0.00000	.32017E-02	.24701E-01	.26577E-01	0.	0.
14	2.76467	3.40158	0.00000	.28029E-02	.24011E-01	.26441E-01	0.	0.
15	3.56022	3.40158	0.00000	.24715E-02	.24266E-01	.26377E-01	0.	0.
16	1.23112	-1.53096	0.00000	.23353E-02	.12635E+00	.12749E+00	0.	0.
17	2.38667	-1.53096	0.00000	.21254E-02	.12638E+00	.12768E+00	0.	0.
18	3.54222	-1.53096	0.00000	.19174E-02	.12640E+00	.12755E+00	0.	0.
19	1.41565	-1.99870	0.00000	.22883E-02	.73972E-01	.75357E-01	0.	0.
20	2.48119	-1.99870	0.00000	.21091E-02	.74042E-01	.75200E-01	0.	0.
21	3.54672	-1.99870	0.00000	.19229E-02	.74077E-01	.75098E-01	0.	0.
22	1.60017	-2.46640	0.00000	.21980E-02	.48453E-01	.49768E-01	0.	0.
23	2.57570	-2.46640	0.00000	.20524E-02	.48538E-01	.49633E-01	0.	0.
24	3.55122	-2.46640	0.00000	.18969E-02	.48588E-01	.49541E-01	0.	0.
25	1.78466	-2.93403	0.00000	.21408E-02	.34196E-01	.35417E-01	0.	0.
26	2.67019	-2.93403	0.00000	.20174E-02	.34274E-01	.35293E-01	0.	0.
27	3.55572	-2.93403	0.00000	.18823E-02	.34317E-01	.35206E-01	0.	0.
28	1.96912	-3.40158	0.00000	.20349E-02	.25363E-01	.26577E-01	0.	0.
29	2.76467	-3.40158	0.00000	.19547E-02	.25464E-01	.26441E-01	0.	0.
30	3.56022	-3.40158	0.00000	.18804E-02	.25558E-01	.26377E-01	0.	0.
31	1.23112	0.00000	1.53096	.23353E-02	-.12789E+00	-.12645E+00	0.	0.
32	2.38667	0.00000	1.53096	.21254E-02	-.12768E+00	-.12638E+00	0.	0.
33	3.54222	0.00000	1.53096	.19174E-02	-.12755E+00	-.12640E+00	0.	0.
34	1.41565	0.00000	1.99870	.22883E-02	-.75357E-01	-.73972E-01	0.	0.
35	2.48119	0.00000	1.99870	.21091E-02	-.75200E-01	-.74042E-01	0.	0.
36	3.54672	0.00000	1.99870	.19229E-02	-.75098E-01	-.74077E-01	0.	0.
37	1.60017	0.00000	2.46640	.21980E-02	-.49768E-01	-.48453E-01	0.	0.
38	2.57570	0.00000	2.46640	.20524E-02	-.49633E-01	-.48538E-01	0.	0.
39	3.55122	0.00000	2.46640	.18969E-02	-.49541E-01	-.48588E-01	0.	0.
40	1.78466	0.00000	2.93403	.21408E-02	-.35417E-01	-.34196E-01	0.	0.
41	2.67019	0.00000	2.93403	.20174E-02	-.35293E-01	-.34274E-01	0.	0.
42	3.55572	0.00000	2.93403	.18823E-02	-.35206E-01	-.34317E-01	0.	0.
43	1.96912	0.00000	3.40158	.20349E-02	-.26577E-01	-.25363E-01	0.	0.
44	2.76467	0.00000	3.40158	.19547E-02	-.26441E-01	-.25464E-01	0.	0.
45	3.56022	0.00000	3.40158	.18804E-02	-.26377E-01	-.25558E-01	0.	0.
46	1.23112	0.00000	-1.53096	.30415E-02	-.12789E+00	-.12608E+00	0.	0.
47	2.38667	0.00000	-1.53096	.25619E-02	-.12768E+00	-.12617E+00	0.	0.
48	3.54222	0.00000	-1.53096	.22035E-02	-.12755E+00	-.12622E+00	0.	0.
49	1.41565	0.00000	-1.99870	.30173E-02	-.75357E-01	-.75200E-01	0.	0.
50	2.48119	0.00000	-1.99870	.25678E-02	-.75200E-01	-.74453E-01	0.	0.

Figure 10.- Continued.

51	1,54672	0,00000	=1,99870	,22241E-02	=,75098E-01	=,74581E-01	0,
52	1,40017	0,00000	=2,46640	,30518E-02	=,49764E-01	=,47405E-01	0,
53	2,47570	0,00000	=2,46640	,26235E-02	=,49633E-01	=,47650E-01	0,
54	3,55122	0,00000	=2,46640	,22924E-02	=,49541E-01	=,47827E-01	0,
55	1,78466	0,00000	=2,93403	,31022E-02	=,35417E-01	=,32804E-01	0,
56	2,67019	0,00000	=2,93403	,26295E-02	=,35293E-01	=,33091E-01	0,
57	3,55572	0,00000	=2,93403	,23729E-02	=,35206E-01	=,33299E-01	0,
58	1,96912	0,00000	=3,40158	,32017E-02	=,26577E-01	=,23701E-01	0,
59	2,76467	0,00000	=3,40158	,28029E-02	=,26461E-01	=,24011E-01	0,
60	3,56022	0,00000	=3,40158	,24715E-02	=,26477E-01	=,24266E-01	0,

CONTROL POINT COORDINATES FOR RTP-3 (WING FRAME)

J	X(J)	Y(J)	Z(J)	THU(J)	THV(J)	THW(J)
61	1,14000	1,25052	,24874	=,13891E-02	=,18221E-01	,34655E-02
62	1,14000	1,06014	,70836	=,15717E-01	=,88792E-02	,20553E-01
63	1,14000	,70836	1,06014	=,15717E-01	,20553E-01	=,88792E-02
64	1,14000	,24874	1,25052	=,13891E-02	,34655E-02	=,18221E-01
65	1,14000	=,24874	1,25052	=,13891E-02	=,34655E-02	=,18221E-01
66	1,14000	=,70836	1,06014	=,15717E-01	=,20553E-01	=,88792E-02
67	1,14000	=1,06014	,70836	=,15717E-01	=,88792E-02	,20553E-01
68	1,14000	=1,25052	,24874	=,13891E-02	=,18221E-01	,34655E-02
69	1,14000	=1,25052	=,24874	=,13891E-02	=,18221E-01	=,34655E-02
70	1,14000	=1,06014	=,70836	=,15717E-01	=,88792E-02	=,20553E-01
71	1,14000	=,70836	=1,06014	=,15717E-01	=,20553E-01	=,88792E-02
72	1,14000	=,24874	=1,25052	=,13891E-02	=,34655E-02	=,18221E-01
73	1,14000	=,24874	=1,25052	=,13891E-02	=,34655E-02	=,18221E-01
74	1,14000	=,70836	=1,06014	=,15717E-01	=,20553E-01	=,88792E-02
75	1,14000	=1,06014	=,70836	=,15717E-01	=,88792E-02	=,20553E-01
76	1,14000	1,25052	=,24874	=,13891E-02	=,18221E-01	=,34655E-02
77	2,34000	1,25052	=,24874	=,13891E-02	=,18221E-01	=,34655E-02
78	2,34000	1,06014	,70836	=,10617E-01	=,85805E-02	=,48355E-02
79	2,34000	,70836	1,06014	=,22211E-01	=,16042E-01	=,68216E-02
80	2,34000	,24874	1,25052	=,10617E-01	=,85805E-02	=,48355E-02
81	2,34000	=,24874	1,25052	=,10617E-01	=,85805E-02	=,48355E-02
82	2,34000	=,70836	1,06014	=,22211E-01	=,16042E-01	=,68216E-02
83	2,34000	=1,06014	,70836	=,22211E-01	=,16042E-01	=,68216E-02
84	2,34000	=1,25052	,24874	=,10617E-01	=,85805E-02	=,48355E-02
85	2,34000	=1,25052	=,24874	=,10617E-01	=,85805E-02	=,48355E-02
86	2,34000	=1,06014	=,70836	=,22211E-01	=,16042E-01	=,68216E-02
87	2,34000	=,70836	=1,06014	=,22211E-01	=,16042E-01	=,68216E-02
88	2,34000	=,24874	=1,25052	=,10617E-01	=,85805E-02	=,48355E-02
89	2,34000	=,24874	=1,25052	=,10617E-01	=,85805E-02	=,48355E-02
90	2,34000	=,70836	=1,06014	=,22211E-01	=,16042E-01	=,68216E-02
91	2,34000	1,06014	=,70836	=,22211E-01	=,16042E-01	=,68216E-02
92	2,34000	1,25052	=,24874	=,10617E-01	=,85805E-02	=,48355E-02
93	3,54000	1,25052	=,24874	=,20323E-01	=,26782E-01	=,54507E-01
94	3,54000	1,06014	,70836	=,22241E-01	=,11295E-01	=,88311E-02
95	3,54000	,70836	1,06014	=,22241E-01	=,11295E-01	=,88311E-02
96	3,54000	,24874	1,25052	=,20323E-01	=,26782E-01	=,54507E-01
97	3,54000	=,24874	1,25052	=,20323E-01	=,26782E-01	=,54507E-01
98	3,54000	=,70836	1,06014	=,22241E-01	=,11295E-01	=,88311E-02
99	3,54000	=1,06014	,70836	=,22241E-01	=,11295E-01	=,88311E-02
100	3,54000	=1,25052	=,24874	=,20323E-01	=,26782E-01	=,54507E-01
101	3,54000	=1,25052	=,24874	=,20323E-01	=,26782E-01	=,54507E-01
102	3,54000	=1,06014	=,70836	=,22241E-01	=,11295E-01	=,88311E-02
103	3,54000	=,70836	=1,06014	=,22241E-01	=,11295E-01	=,88311E-02

Figure 10.- Continued.

104	3.54000	-.24874	=1.25052	.20323E-01	.54507E-01	-.24782E-01
105	3.54000	.24874	=1.25052	.20323E-01	-.54507E-01	-.24782E-01
106	3.54000	.70834	=1.06014	-.22241E-01	.68311E-02	-.11295E-01
107	3.54000	1.06014	-.70834	-.22241E-01	.11295E-01	-.68311E-02
104	3.54000	1.25052	-.24874	.20323E-01	.54507E-01	-.24782E-01

LOADING INFORMATION

MACH NUMBER = .17000E+01
 ANGLE OF ATTACK = 10.000 DEGREES
 SIDE SLIP ANGLE = 10.000 DEGREES
 WING AREA = 13.68666
 REFERENCE AREA = 5.30029
 REFERENCE LENGTH = 2.69000
 EXPOSED WING SPAN B = 0.68000
 MOMENT CENTER: X = 19.50000
 Y = 0.00000
 Z = 0.00000

WING TYPE LOADING PRESSURE

DEFL. ANGLE DEG.	TOTAL	FIN 1 OR R	FIN 2 OR L	FIN 3 OR U	FIN 4 OR D	INTERF. SHELL
CTMD =	.53916E+01	0.00000	0.00000	0.00000	0.00000	
CZ =	.14450E+01	.14774E+01	.12184E+01	.14774E+01	.14774E+01	.22517E+00
CY =	-.14450E+01	.66234E+00	.55746E+00	.55746E+00	.66234E+00	-.22517E+00
CM =	-.14547E+01	-.65426E+00	-.54950E+00	-.54950E+00	-.65426E+00	-.25492E+00
CLN =	.14547E+01	0.	0.	.54950E+00	.65426E+00	.25492E+00
CLI =	.14346E+13	-.57478E+00	.50518E+00	-.50518E+00	.57478E+00	.13507E-15

FOLLOWING ARE IN WIND-AXIS SYSTEM

CL =	.14942E+01	.45743E+00	.34511E+00	.38511E+00	.45743E+00	.30849E+00
CY-IND =	.66164E-12	.46810E+00	.39419E+00	-.39419E+00	-.46810E+00	.63505E-12
CO1 =	.44957E+00	.10049E+00	.94992E-01	.84992E-01	.10049E+00	.78202E-01
CO1/CL**2 =	.11345E+00					
CM-IND =	-.20429E+01	-.46263E+00	-.38855E+00	-.38855E+00	-.46263E+00	-.36052E+00
CL-IND =	-.61014E-12	-.30731E+00	.50072E+00	.50072E+00	.30731E+00	-.56044E-12

NOTE: L.S. OF LEAD PANEL IN FIRST CHORDWISE ROW IS SUPERSONIC

Figure 10.- Continued.

-----RIGHT TAIL-----

SPANWISE DISTRIBUTIONS

I	Y/(H/2)	CN=C/(2*H)	CI=C/(2*R)	CY1=C/(2*R)	CYTOT=C/(2*B)	CS=C/(2*R)	CSINT	YBAR	GAMMA(I)	GAMMA,LE/VINF	XLE
1	.65476	.19347	0.00000	0.00000	.00070	0.00000	0.00000	0.00000	-.90825	0.00000	.13334
2	.85415	.18840	0.00000	0.00000	.00259	0.00000	0.00000	0.00000	.02601	0.00000	.40344
3	1.05402	.17267	0.00000	0.00000	.00225	0.00000	0.00000	0.00000	.07359	0.00000	.67342
4	1.25386	.14562	0.00000	0.00000	.00201	0.00000	0.00000	0.00000	.12655	0.00000	.94341
5	1.45367	.10212	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.20344	0.00000	1.21335
6	1.55556	0.00000							.47841		

SUMFX = 0.
 SUMFY1 = 0.
 SUMFY2 = .62235E+02
 SUMFT2 = .25695E+01

SIDE EDGE DISTRIBUTION

JTID	JSE	DISTANCE FROM LE /TIPCHORD	SUCTION FORCE PER UNIT LENGTH /(0.1TIPCHORD)	GAMMA,SE /VINF	YBAR	XSE
1	1	.33333	.00311	.00055	3.64000	1.55100
2	2	.66667	.03528	.00681	3.64000	2.10067
3	3	1.00000	.04564	.01491	3.64000	2.45033

*****E. FIN VORTEX INFO*****

IVRT GAMMA/VINF Y,C.G.
 1 .90779 3.23687

SPANWISE DISTRIBUTIONS

I	Y/(B/2)	CN*C/(2*B)	CT*C/(2*H)	CY1*C/(2*B)	CYTOT*C/(2*B)	CS*C/(2*B)	CSINT	YBAR	GAMNET(I)	GAMMA,LF/VINF	XLE
7	-.85424	.12209	0.00000	0.00000	-.00401	0.00000	0.00000	0.00000	.57449	0.00000	.13334
8	-.85415	.14651	0.00000	0.00000	-.00178	0.00000	0.00000	0.00000	.11159	0.00000	.40340
9	-1.05402	.15930	0.00000	0.00000	-.00165	0.00000	0.00000	0.00000	.05999	0.00000	.67342
10	-1.25386	.14379	0.00000	0.00000	-.00351	0.00000	0.00000	0.00000	-.07257	0.00000	.94341
11	-1.45367	.10337	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.18919	0.00000	1.21335
12	-1.55556	0.00000							-.48431		

SUMFX = 0.
 SUMFY1 = 0.
 SUMFY2 = -.61037E-02
 SUMFZ2 = -.32174E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SUCTION FORCE PER UNIT LENGTH / (D*TIPCHORD)	GAMMA,SE / VINF	YBAR	XSE
1	1	.33333	-.00495	-.00088	-3.64000	1.35100
2	2	.66667	-.00491	-.00920	-3.64000	2.10067
3	3	1.00000	-.00446	-.01797	-3.64000	2.85033

****T.E. FIN VORTEX INFO****

IVRT	GAMMA/VINF	Y/C.G.
2	.17134	-1.93153
3	-.74554	-3.43010

Figure 10.- Continued.

.....UPPER KING.....

SPANISH DISTRIBUTIONS

T	Z/(R/2)	C4=C/(2*H)	C1=C/(2*H)	C21=C/(2*H)	C2117=C/(2*H)	C3=C/(2*H)	CSINT	ZBAR	GAMMAE(1)	GAMMA,LE/VINF	XLE
13	.85426	.12269	0.00000	0.00000	.00401	0.00000	0.00000	0.00000	-.57409	0.00000	.13330
14	.85015	.14651	0.00000	0.00000	-.00178	0.00000	0.00000	0.00000	-.11159	0.00000	.40340
15	1.05402	.15930	0.00000	0.00000	.00165	0.00000	0.00000	0.00000	-.05909	0.00000	.07347
16	1.25386	.14479	0.00000	0.00000	.00351	0.00000	0.00000	0.00000	.07257	0.00000	.94341
17	1.45367	.10357	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.18919	0.00000	1.21335
18	1.55556	0.00000							.04431		

SUMF1 = 0.
 SUMF2 = 0.
 SUMF3 = .01017E-02
 SUMF4 = .32174E-01

STEP EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SUCTION FORCE PER UNIT LENGTH / (0.01PCCHORD)	GAMMA,SE / VINF	ZBAR	XSE
1	4	.55353	.04095	.00000	3.64000	1.35100
2	5	.06667	.04691	.00920	3.64000	2.10067
3	6	1.00000	.04906	.01797	3.64000	2.85033

****T.F. FIN VORTEX INFO****

JVRT	GAMMA/VINF	Z.C.C.
4	-.17134	1.93153
5	.74554	3.45010

Figure 10.- Continued.

SPANWISE DISTRIBUTIONS

I	Z/(H/2)	C1+C/(2+H)	C7+C/(2+H)	C2+C/(2+H)	C2TOT+C/(2+H)	C8+C/(2+H)	CSTNT	ZBAR	GAMNET(1)	GAMMA,LE/VINF	XLF
19	-.65426	.19397	0.00000	0.00000	-.00070	0.00000	0.00000	0.00000	.90825	0.00000	.13330
20	-.85415	.18840	0.00000	0.00000	-.00259	0.00000	0.00000	0.00000	-.02601	0.00000	.40340
21	-1.05402	.17267	0.00000	0.00000	-.00225	0.00000	0.00000	0.00000	-.07359	0.00000	.67342
22	-1.25386	.14562	0.00000	0.00000	-.00201	0.00000	0.00000	0.00000	-.12655	0.00000	.94341
23	-1.45367	.10212	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.20368	0.00000	1.21345
24	-1.55556	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.47841	0.00000	

SUMFX = 0.
 SUMFZ1 = 0.
 SUMFZ2 = -.62235E+02
 SUMFT2 = -.26694E+01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SUCTION FORCE PER UNIT LENGTH / (Q+TIPCHORD)	GAMMA,SE / VINF	ZBAR	XSE
1	7	.33333	-.00311	-.00055	-3.64000	1.35100
2	8	.66667	-.03528	-.00681	-3.64000	2.10067
3	9	1.00000	-.04568	-.01491	-3.64000	2.85033

T.E. FIN VORTEX INFO

TVRT GAMMA/VINF Z.C.G.
 h = .90779 -3.23687

VELOCITIES AND BERNOULLI PRESSURES AT CONTROL POINTS IMMEDIATELY ABOVE AND BELOW HORIZONTAL WING SURFACE

J	X(J)	Y(J)	Z(J)	UTOTA	VTOTA	WTOTA	PRESSA	UTOTB	VTOTB	WTOTB	PRESSB
1	1.251118	1.530959	0.00000	.14695	-.00546	-.173650	-.22679	-.182872	.140985	-.173650	.498202
2	2.386670	1.530959	0.00000	.124987	.070735	-.173650	-.178168	-.116691	.167834	-.173650	.331516
3	3.542222	1.530959	0.00000	.102488	.159554	-.173650	-.212304	-.071752	.200785	-.032650	.196546
4	1.415454	1.998701	0.00000	.248685	.131702	-.173650	-.374805	-.107671	.074156	-.173650	.295550
5	2.481188	1.998701	0.00000	.12951	.026553	-.173650	-.193772	-.126751	.125200	-.173650	.352481

6	3.546723	1.998701	0.000000	.140537	.112974	-.314650	-.246240	-.050542	.154275	-.052650	.149361
7	1.600170	2.466397	0.000000	.174346	-.033659	-.173650	-.270427	-.176446	.149078	-.173650	.422765
8	2.475697	2.466397	0.000000	.165459	.003287	-.173650	-.251365	-.115465	.111646	-.173650	.323032
9	3.551224	2.466397	0.000000	.239154	.092494	-.314650	-.338494	.042493	.130264	-.032650	-.044914
10	1.784662	2.934030	0.000000	.178746	-.024407	-.173650	-.274891	.167316	.167316	-.173650	.432284
11	2.670193	2.934030	0.000000	.197168	-.051134	-.173650	-.303190	-.083959	.057072	-.173650	.233414
12	3.555723	2.934030	0.000000	.118982	.031854	-.314650	-.104419	-.044274	.041348	-.032650	.099520
13	1.969121	3.401580	0.000000	.125277	.046599	-.173650	-.143220	-.172306	.218409	-.173650	.467925
14	2.764672	3.401580	0.000000	.090547	.022494	-.173650	-.151423	-.096299	.095385	-.173650	.277790
15	3.560222	3.401580	0.000000	.212661	-.059434	-.173650	-.332044	.097731	-.037715	-.032650	-.175148
16	1.231118	-1.530959	0.000000	.070132	.140441	-.173650	-.076494	-.103380	.040703	-.173650	.274053
17	2.386670	-1.530959	0.000000	.095711	.090441	-.173650	-.127488	-.096230	.016555	-.173650	.247741
18	3.542222	-1.530959	0.000000	.190549	.073434	-.314650	-.244295	.058445	.048087	-.032650	-.086420
19	1.415654	-1.998701	0.000000	.206874	.128113	-.173650	-.289425	-.062594	-.027466	-.173650	.151471
20	2.481188	-1.998701	0.000000	.124540	-.020499	-.173650	-.192702	-.096286	-.097495	-.173650	.191176
21	3.546723	-1.998701	0.000000	.206749	-.032055	-.314650	-.319963	.053188	-.061412	-.032650	-.110478
22	1.600170	-2.466397	0.000000	.170040	.055564	-.173650	-.247981	-.174197	.143171	-.173650	.323006
23	2.575697	-2.466397	0.000000	.154059	.015503	-.173650	-.232395	-.100169	-.082349	-.173650	.203289
24	3.551224	-2.466397	0.000000	.228727	-.071603	-.314650	-.351000	.062395	-.143614	-.032650	-.143375
25	1.784662	-2.934030	0.000000	.192359	.073174	-.173650	-.275643	-.172682	-.137580	-.173650	.324580
26	2.670193	-2.934030	0.000000	.190175	.088438	-.173650	-.271239	-.073527	-.012941	-.173650	.182647
27	3.555723	-2.934030	0.000000	.119597	.014754	-.314650	-.194090	-.012214	.006614	-.032650	.032195
28	1.969121	-3.401580	0.000000	.141591	.062093	-.173650	-.217201	-.190954	-.149902	-.173650	.315261
29	2.764672	-3.401580	0.000000	.086720	.014855	-.173650	-.126854	-.096148	-.055539	-.173650	.211039
30	3.560222	-3.401580	0.000000	.203448	.100104	-.314650	-.298294	.110529	.082141	-.032650	-.168646

VELOCITIES AND HEMPHILL PRESSURES AT CONTROL POINTS IMMEDIATELY TO RIGHT AND LEFT OF VERTICAL WING SURFACE

J	X(J)	Y(J)	Z(J)	UTOTR	VTOTR	WTOTR	PRESSR	UTOTL	VTOTL	WTOTL	PRESSL
31	1.231118	0.000000	1.530959	-.103380	.173650	-.040703	.274053	.070132	.173650	-.149481	-.074948
32	2.386670	0.000000	1.530959	-.096230	.173650	-.016555	.247741	.045711	.173650	-.090433	-.127484
33	3.542222	0.000000	1.530959	-.094845	.173650	-.048687	.247741	.045711	.173650	-.090433	-.127484
34	1.415654	0.000000	1.998701	-.062598	.173650	.027466	.151471	.206874	.173650	-.128113	-.289425
35	2.481188	0.000000	1.998701	-.062598	.173650	.027466	.151471	.206874	.173650	-.128113	-.289425
36	3.546723	0.000000	1.998701	-.062598	.173650	.027466	.151471	.206874	.173650	-.128113	-.289425
37	1.600170	0.000000	2.466397	-.174197	.173650	.143171	.323006	.170030	.173650	-.055564	-.247981
38	2.575697	0.000000	2.466397	-.100169	.173650	.082349	.203289	.154059	.173650	-.015503	-.232395
39	3.551224	0.000000	2.466397	-.062395	.173650	.103614	.143375	.228727	.032650	.071603	-.351000
40	1.784662	0.000000	2.934030	-.172682	.173650	.147580	.324580	.192359	.173650	-.073176	-.275643
41	2.670193	0.000000	2.934030	-.073527	.173650	.012961	.182647	.190175	.173650	-.088438	-.271239
42	3.555723	0.000000	2.934030	-.012214	.173650	.006614	.032195	.119597	.032650	-.012941	-.190954
43	1.969121	0.000000	3.401580	-.140954	.173650	.189902	.151521	.141591	.173650	-.062093	-.217201
44	2.764672	0.000000	3.401580	-.086720	.173650	.055539	.211039	.086720	.173650	-.014855	-.126854
45	3.560222	0.000000	3.401580	.110529	.173650	-.082141	-.148646	.203448	.032650	-.100104	-.289425
46	1.231118	0.000000	-1.530959	-.162472	.173650	.146495	.146495	.173650	.005464	-.054644	-.226794
47	2.386670	0.000000	-1.530959	-.116491	.173650	-.167834	.315116	.124947	.173650	-.074735	-.178168
48	3.542222	0.000000	-1.530959	-.071752	.173650	-.200785	.126546	.142448	.032650	-.159554	-.212364
49	1.415654	0.000000	-1.998701	-.107471	.173650	-.074156	.294550	.208685	.173650	-.131702	-.374805
50	2.481188	0.000000	-1.998701	-.126751	.173650	-.125204	.352481	.124551	.173650	-.026553	-.193772
51	3.546723	0.000000	-1.998701	-.050542	.173650	-.154275	.164537	.164537	.032650	-.112476	-.244240
52	1.600170	0.000000	-2.466397	-.176446	.173650	-.169074	.422765	.174346	.173650	-.033659	-.270427
53	2.575697	0.000000	-2.466397	-.115465	.173650	-.111646	.303190	.165459	.173650	-.004287	-.251145
54	3.551224	0.000000	-2.466397	-.042493	.173650	-.130264	-.044914	.239154	.032650	-.092494	-.338494
55	1.784662	0.000000	-2.934030	-.157118	.173650	-.167316	.432284	.178746	.173650	-.024407	-.274891
56	2.670193	0.000000	-2.934030	-.083959	.173650	-.057072	.233190	.197168	.173650	-.051134	-.303190
57	3.555723	0.000000	-2.934030	-.034274	.173650	-.061348	.099520	.118982	.032650	-.031854	-.190418

Figure 10.- Continued.

58	1.969121	0.000000	-3.401580	-.172306	.173650	-.218409	.467925	.125277	.173450	-.046509	-.181220
59	2.764672	0.000000	-3.401580	-.098299	.173650	-.095385	.277790	.090547	.173650	-.022698	-.131423
60	1.560222	0.000000	-3.401580	.097731	.318650	.037715	-.175108	.212661	.032650	.059830	-.332048

PRESSURE LOADINGS AT CONTROL POINTS

J	X(J)	Y(J)	Z(J)	DELTP, LIN.	DELTP, HFRN.
1	1.23111A	1.530959	0.000000	.659734	.724996
2	2.386670	1.530959	0.000000	.483756	.509684
3	3.542222	1.530959	0.000000	.428480	.408850
4	1.415654	1.998701	0.000000	.713112	.670455
5	2.48118A	1.998701	0.000000	.512603	.546253
6	3.546723	1.998701	0.000000	.430237	.375601
7	1.600170	2.466397	0.000000	.702303	.753532
8	2.575697	2.466397	0.000000	.563049	.574397
9	3.551224	2.466397	0.000000	.492520	.293978
10	1.784662	2.934030	0.000000	.671770	.707175
11	2.670193	2.934030	0.000000	.562255	.537004
12	3.555723	2.934030	0.000000	.306512	.28993A
13	1.969121	3.401580	0.000000	.695167	.651145
14	2.764672	3.401580	0.000000	.377692	.409213
15	3.560222	3.401580	0.000000	.229861	.154900
16	1.23111A	-1.530959	0.000000	.347024	.351000
17	2.386670	-1.530959	0.000000	.343882	.375229
18	3.542222	-1.530959	0.000000	.283406	.197475
19	1.415654	-1.998701	0.000000	.538944	.441296
20	2.48118A	-1.998701	0.000000	.441654	.383878
21	3.546723	-1.998701	0.000000	.307162	.209285
22	1.600170	-2.466397	0.000000	.688454	.570987
23	2.575697	-2.466397	0.000000	.408455	.435683
24	3.551224	-2.466397	0.000000	.332665	.207625
25	1.784662	-2.934030	0.000000	.730082	.600274
26	2.670193	-2.934030	0.000000	.527405	.453886
27	3.555723	-2.934030	0.000000	.263632	.22628A
28	1.969121	-3.401580	0.000000	.665988	.532461
29	2.764672	-3.401580	0.000000	.365775	.337895
30	3.560222	-3.401580	0.000000	.184679	.129650
31	1.23111A	0.000000	1.530959	.347024	.351000
32	2.386670	0.000000	1.530959	.383882	.375229
33	3.542222	0.000000	1.530959	.283406	.197475
34	1.415654	0.000000	1.998701	.538944	.441296
35	2.48118A	0.000000	1.998701	.441654	.383878
36	3.546723	0.000000	1.998701	.307162	.209285
37	1.600170	0.000000	2.466397	.688454	.570987
38	2.575697	0.000000	2.466397	.408455	.435683
39	3.551224	0.000000	2.466397	.332665	.207625
40	1.784662	0.000000	2.934030	.730082	.600274
41	2.670193	0.000000	2.934030	.527405	.453886
42	3.555723	0.000000	2.934030	.263632	.22628A
43	1.969121	0.000000	3.401580	.665988	.532461
44	2.764672	0.000000	3.401580	.365775	.337895
45	3.560222	0.000000	3.401580	.184679	.129650
46	1.23111A	0.000000	-1.530959	.347024	.351000
47	2.386670	0.000000	-1.530959	.343756	.509684
48	3.542222	0.000000	-1.530959	.428480	.408850
49	1.415654	0.000000	-1.998701	.713112	.670355

Figure 10. - Continued.

50	2.481188	0.000000	-1.998701	.512603	.546253
51	3.546723	0.000000	-1.998701	.430237	.595401
52	1.800170	0.000000	-2.466397	.702303	.753532
53	2.575497	0.000000	-2.466397	.563049	.574397
54	3.551224	0.000000	-2.466397	.392520	.273974
55	1.784462	0.000000	-2.466397	.871770	.707175
56	2.670193	0.000000	-2.934030	.562255	.537004
57	3.555723	0.000000	-2.934030	.306512	.289938
58	1.969121	0.000000	-3.401580	.595167	.651145
59	2.764672	0.000000	-3.401580	.377692	.409213
60	3.560222	0.000000	-3.401580	.229861	.154900

LOADING INFORMATION

MACH NUMBER = .17000E+01
 ANGLE OF ATTACK = 10.000 DEGREES
 SIDE SLIP ANGLE = 10.000 DEGREES
 WING AREA = 13.48666
 REFERENCE AREA = 5.30929
 REFERENCE LENGTH = 2.89000
 EXPOSED WING SPAN H = 4.48000
 MOMENT CENTER: X = 19.50000
 Z = 0.00000

BERNOULLI TYPE LOADING PRESSURE

REFL. ANGLE DEG.	TOTAL	FIN 1 OR R	FIN 2 OR L	FIN 3 OR U	FIN 4 OR D	INTERP. SMALL
CTR	.49666E+01	.10912E+01	.99211E+02	.49211E+02	.14912E+01	
CZ	.14535E+01	.66290E+00	.46540E+00	0.	0.	.22517E+00
CY	-.13535E+01	0.	0.	-.46540E+00	-.66290E+00	-.22517E+00
CM	-.13488E+01	-.42751E+00	-.45135E+00	0.	0.	-.25092E+00
CLN	.13488E+01	0.	0.	.45133E+00	.42751E+00	.25092E+00
CLL	.46320E+13	-.57374E+00	.41884E+00	-.41884E+00	.57374E+00	.13507E+13

FOLLOWING ARE IN WIND-AXIS SYSTEM

CL	.18477E+01	.45808E+00	.32145E+00	.32145E+00	.45808E+00	.30869E+00
CY-IND	.62261E+12	.46877E+00	.32909E+00	-.32909E+00	-.46877E+00	.63505E+12
CDI	.42193E+00	.10066E+00	.71199E-01	.71199E-01	.10066E+00	.78207E-01
CDI/CL**2	.12495E+00					
CM-IND	-.19070E+01	-.45432E+00	-.31914E+00	-.31914E+00	-.45432E+00	-.36852E+00
CLN-IND	-.56577E+12	-.29950E+00	-.41222E+00	.41222E+00	.29950E+00	-.56844E+12

NOTE: I.E. OF LEAD PANEL IN FIRST CHORD-ISE HO- IS SUPERSONIC

SPARWISE DISTRIBUTIONS

I	Y/(B/2)	C*AC/(2*B)	CT*C/(2*B)	CY1*C/(2*B)	CYT/T+C/(2*B)	CS*C/(2*B)	CSINT	YBAR	GAMMA(I)	GAMMA,LF/VINF	XLE
1	.65426	.20280	0.00000	0.00000	.00352	0.00000	0.00000	0.00000	-.94959	0.00000	.13334
2	.85415	.18342	0.00000	0.00000	.00198	0.00000	0.00000	0.00000	.09066	0.00000	.40340
3	1.05402	.16892	0.00000	0.00000	.00223	0.00000	0.00000	0.00000	.06743	0.00000	.67342
4	1.25385	.14501	0.00000	0.00000	.00198	0.00000	0.00000	0.00000	.11185	0.00000	.94341
5	1.45367	.10335	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.19506	0.00000	1.21335
6	1.55556	0.00000							.48420		

SUMFY = 0.
 SUMFY1 = 0.
 SUMFY2 = .72775E-07
 SUMFTP = .27974E-01

STOP EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE /TIPCHORD	SUCTION FORCE PER UNIT LENGTH /(Q*VINF*CHORD)	GAMMA,SE /VINF	YBAR	XSE
1	1	.35333	.00340	.00040	3.64000	1.35100
2	2	.66667	.03845	.00742	3.64000	2.10067
3	3	1.00000	.04624	.01563	3.64000	2.85033

****T.F. FIN VORTEX INFO****
 IVRT GAMMA/VINF Y.C.G.
 1 .94911 3.15420

Figure 10.- Continued.

----- LEFT TIP -----

SPACIAL DISTRIBUTIONS

I	Y/(R/2)	CN+C/(2*H)	CT+C/(2*H)	CY1+C/(2*H)	CYTOT+C/(2*H)	CS+C/(2*H)	CSTNT	YR#R	GAMNET(I)	GAMMA,IE/VINF	XLE
7	-.6942A	.11396	0.00000	0.00000	-.00097	0.00000	0.00000	0.00000	.53369	0.00000	.13334
8	-.85415	.11759	0.00000	0.00000	.00142	0.00000	0.00000	0.00000	.01743	0.00000	.40340
9	-1.05402	.12647	0.00000	0.00000	-.00085	0.00000	0.00000	0.00000	.04116	0.00000	.67342
10	-1.25386	.12104	0.00000	0.00000	-.00310	0.00000	0.00000	0.00000	-.02535	0.00000	.44641
11	-1.45307	.08490	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.16916	0.00000	1.21335
12	-1.55556	0.00000							-.39778		

SUMFY = 0.
 SUMFY1 = 0.
 SUMFY2 = -.29015E+02
 SUMFY3 = -.26735E+01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE /TIPCHORD	SECTION FORCE PER UNIT LENGTH /(C*TIPCHORD)	GAMMA,SE /VINF	YR#R	XLE
1	1	.33333	-.00396	-.00070	-3.64000	1.35100
2	2	.66667	-.03961	-.00773	-3.64000	2.10067
3	3	1.00000	-.04062	-.01493	-3.64000	2.45033

****E. FIN VERTX INFO****

IVRT GAMMA/VINF Y,C,G.

2 .05844 -2.09688
 3 -.59187 -3.46609

-----UPPER WING-----

SPANWISE DISTRIBUTIONS

I	Z/(R/2)	CN*C/(2*B)	CT*C/(2*B)	CZ1*C/(2*B)	CZTOT*C/(2*B)	CS*C/(2*B)	CSIN	ZBAR	GAMNET(I)	GAMMA,LE/VINF	XLE
13	.65426	.11398	0.00000	0.00000	.00097	0.00000	0.00000	0.00000	-.53369	0.00000	.13334
14	.85415	.11769	0.00000	0.00000	-.00142	0.00000	0.00000	0.00000	-.01743	0.00000	.40340
15	1.05402	.12647	0.00000	0.00000	.00085	0.00000	0.00000	0.00000	-.04116	0.00000	.67342
16	1.25386	.12104	0.00000	0.00000	.00310	0.00000	0.00000	0.00000	.02535	0.00000	.94341
17	1.45367	.08490	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.16916	0.00000	1.21335
18	1.55556	0.00000							.39778		

SUMFX = 0.
 SUMFZ1 = 0.
 SUMFZ2 = .29015E-02
 SUMFT2 = .26735E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SUCTION FORCE PER UNIT LENGTH / (Q*TIPCHORD)	GAMMA,SE / VINF	ZBAR	XSE
1	4	.33333	.00396	.00070	3.64000	1.35100
2	5	.66667	.03961	.00773	3.64000	2.10067
3	6	1.00000	.04062	.01493	3.64000	2.85033

****T.F. FIN VORTEX INFO****

IVRT	GAMMA/VINF	Z,C,G.
4	-.05844	2.09688
5	.59187	3.46609

-----L0+R TAG-----

SPANWISE DISTRIBUTIONS

I	Z/(R*2)	CN*C/(2*B)	CT*C/(2*B)	CZ1*C/(2*B)	CZTOT*C/(2*B)	CS*C/(2*B)	CSINT	ZBAR	GAMMA(I)	GAMMA,LE/VINF	XLE
10	-.65426	.20280	0.00000	0.00000	-.00352	0.00000	0.00000	0.00000	.94959	0.00000	.13354
20	-.45415	.18342	0.00000	-0.00000	-.00108	0.00000	0.00000	0.00000	-.09046	0.00000	.40340
21	-1.05402	.16892	0.00000	0.00000	-.00223	0.00000	0.00000	0.00000	-.06783	0.00000	.67342
22	-1.25388	.14501	0.00000	0.00000	-.00198	0.00000	0.00000	0.00000	-.11185	0.00000	.94361
23	-1.45367	.10335	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.19596	0.00000	1.21335
24	-1.55556	0.00000							-.48420		

SUMFX = 0.
 SUMFZ1 = 0.
 SUMFZ2 = -.72775E-02
 SUMFTP = -.27974E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE Z(TIPCHORD)	SUCTION FORCE PER UNIT LENGTH Z(C*TIPCHORD)	GAMMA,SE /VINF	ZBAR	XSE
1	7	.35353	-.00340	-.00040	-.5,64000	1.35100
2	8	.60067	-.03845	-.00742	-3,64000	2.10067
3	9	1.00000	-.04624	-.01543	-3,64000	2.85033

*****E. FIN VORTEX THEO*****

TVRT GAMMA/VINF Z.C.G.

6 -.94911 -3.15024

PRESSURE COEFFICIENTS AT PRINTS ON BODY MERIDIANS

J	THETA, DEG.	XH	YH	ZH	UTOT	VTOT	WTOT	CP,LIN.	CP,BERN.	DR/DX	P/PINF, BERN.	P/PINF, LIN.
BODY RING# 1												
1	11,25000	20,94000	1,25052	.24874	.10899	.12438	.10735	-.21798	-.20414	0,00000	.58702	.55903
2	33,75000	20,94000	1,06014	.70836	.02510	-.05031	.20926	-.05019	-.17282	0,00000	.65039	.69846
3	56,25000	20,94000	.70836	1,06014	-.03280	-.16979	.05031	.06568	-.04375	0,00000	.91148	1,13287
4	78,75000	20,94000	.24874	1,25052	-.06999	-.03950	-.14496	.13818	.15867	0,00000	1,32099	1,27954
5	101,25000	20,94000	-.24874	1,25052	.05658	.29243	-.17075	-.11515	-.06355	0,00000	.87145	.77109
6	123,75000	20,94000	-.70836	1,06014	.00437	.26577	-.10263	-.01273	.03526	0,00000	1,07133	.97424
7	146,25000	20,94000	-1,06014	.70836	.00637	.10263	.01273	.03526	0,00000	0,00000	1,07133	.97424
8	168,75000	20,94000	-1,25052	.24874	.05658	.17075	-.29243	-.11315	-.06355	0,00000	.87145	.77109
9	191,25000	20,94000	-1,25052	-.24874	-.06999	.14496	.03950	.15818	.15867	0,00000	1,32099	1,27954
10	213,75000	20,94000	-1,06014	-.70836	-.03280	-.05031	.16979	.06568	-.04375	0,00000	.91148	1,13287
11	236,25000	20,94000	-.70836	-1,06014	.02510	-.20926	.08031	-.05019	-.17282	0,00000	.65039	.69846
12	258,75000	20,94000	-.24874	-1,25052	.10899	.10735	-.12438	-.21798	-.20414	0,00000	.58702	.55903
13	281,25000	20,94000	.24874	-1,25052	-.12048	.13923	-.21068	.24096	.31248	0,00000	1,63216	1,48746
14	303,75000	20,94000	.70836	-1,06014	-.04817	.15212	.20247	.09635	.16708	0,00000	1,33800	1,19491
15	326,25000	20,94000	1,06014	-.70836	-.04817	.20247	-.15212	.09635	.16708	0,00000	1,33800	1,19491
16	348,75000	20,94000	1,25052	-.24874	-.12048	.21068	-.03923	.24096	.31248	0,00000	1,63216	1,48746
BODY RING# 2												
1	11,25000	22,14000	1,25052	.24874	.10843	.12970	.08047	-.21286	-.18996	0,00000	.61571	.56939
2	33,75000	22,14000	1,06014	.70836	.03484	-.02592	.12779	-.06968	-.12572	0,00000	.74567	.85903
3	56,25000	22,14000	.70836	1,06014	-.04816	-.04119	-.00899	.09632	.06189	0,00000	1,12521	1,19486
4	78,75000	22,14000	.24874	1,25052	-.09199	-.01047	-.15087	.18399	.22506	0,00000	1,45530	1,37220
5	101,25000	22,14000	-.24874	1,25052	.08900	.30800	-.16680	-.17800	-.12513	0,00000	.74687	.63991
6	123,75000	22,14000	-.70836	1,06014	.06088	.27827	-.09511	-.12136	-.07382	0,00000	.85066	.75409
7	146,25000	22,14000	-1,06014	.70836	.06088	.09511	-.27827	-.12136	-.07382	0,00000	.85066	.75409
8	168,75000	22,14000	-1,25052	.24874	.08900	.16680	.30800	-.17800	-.12513	0,00000	.74687	.63991
9	191,25000	22,14000	-1,25052	-.24874	-.09199	.15087	.01047	.18399	.22506	0,00000	1,45530	1,37220
10	213,75000	22,14000	-1,06014	-.70836	-.04816	.00899	.08119	.09632	.06189	0,00000	1,12521	1,19486
11	236,25000	22,14000	-.70836	-1,06014	.03484	-.12779	.02592	-.06968	-.12572	0,00000	.74567	.85903
12	258,75000	22,14000	-.24874	-1,25052	.10843	-.08047	-.12970	-.21286	-.18996	0,00000	.61571	.56939
13	281,25000	22,14000	.24874	-1,25052	-.13102	.02976	-.21254	.26204	.33398	0,00000	1,67583	1,53101
14	303,75000	22,14000	.70836	-1,06014	-.16212	.15054	.20351	.32425	.44280	0,00000	1,89578	1,65595
15	326,25000	22,14000	1,06014	-.70836	-.16212	.20351	-.15054	.32425	.44280	0,00000	1,89578	1,65595
16	348,75000	22,14000	1,25052	-.24874	-.13102	.21254	-.02976	.26204	.33398	0,00000	1,67583	1,53101
BODY RING# 3												
1	11,25000	23,34000	1,25052	.24874	.09347	.14430	.00695	-.18695	-.14480	0,00000	.70707	.62180
2	33,75000	23,34000	1,06014	.70836	-.01523	.01571	.06542	-.03046	-.04986	0,00000	.89958	.93838
3	56,25000	23,34000	.70836	1,06014	-.01296	.06034	-.02303	.02592	.00788	0,00000	1,01593	1,05244
4	78,75000	23,34000	.24874	1,25052	.00349	-.05293	.14251	-.00778	.00044	0,00000	1,00090	.98426

Figure 10.- Continued.

5	101,25000	23,34000	-.24874	1,25052	.14834	.34241	-.15880	-.29676	-.22665	0,00000	.54148	.39966
6	123,75000	23,34000	-.70836	1,06014	.13228	.26647	-.10396	-.24457	-.19226	0,00000	.61106	.46478
7	146,25000	23,34000	-1,06014	.70836	.13228	.10396	-.26647	-.26457	-.19226	0,00000	.61106	.46478
8	168,75000	23,34000	-1,25052	.24874	.14834	.15880	-.34241	-.27676	-.22665	0,00000	.54148	.39966
9	191,25000	23,34000	-1,25052	-.24874	.00340	.14251	.05293	-.00778	.00000	0,00000	1,00000	.98426
10	213,75000	23,34000	-1,06014	-.70836	-.01295	.02303	.06034	.02592	.00788	0,00000	1,01593	1,05244
11	236,25000	23,34000	-.70836	-1,06014	.01523	-.06542	-.01571	-.03046	-.04966	0,00000	.60954	.93838
12	258,75000	23,34000	-.24874	-1,25052	.09347	-.00695	-.14430	-.18695	-.14440	0,00000	.70717	.62180
13	281,25000	23,34000	.24874	-1,25052	-.11401	-.04527	-.22745	.22802	.25389	0,00000	1,51362	1,46128
14	303,75000	23,34000	.70836	-1,06014	-.16774	.12646	-.21958	.33549	.45252	0,00000	1,91545	1,67870
15	326,25000	23,34000	1,06014	-.70836	-.16774	.21958	-.12646	.33549	.45252	0,00000	1,91545	1,67870
16	348,75000	23,34000	1,25052	-.24874	-.11401	.22745	.04527	.22802	.25389	0,00000	1,51362	1,46128

Figure 10.- Concluded.

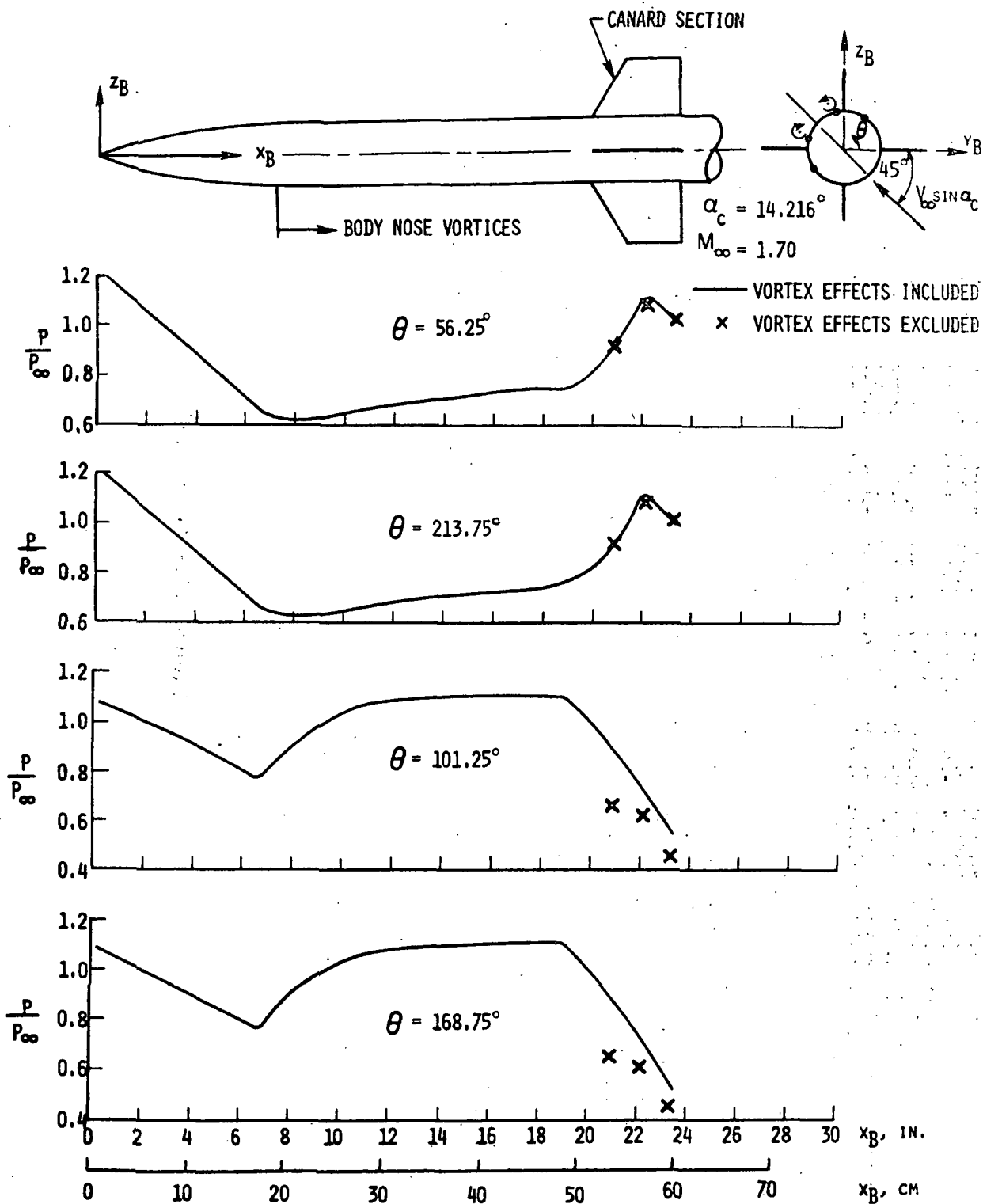


Figure 11(a).— Calculated pressure distributions along body meridians through canard section; first sample case.

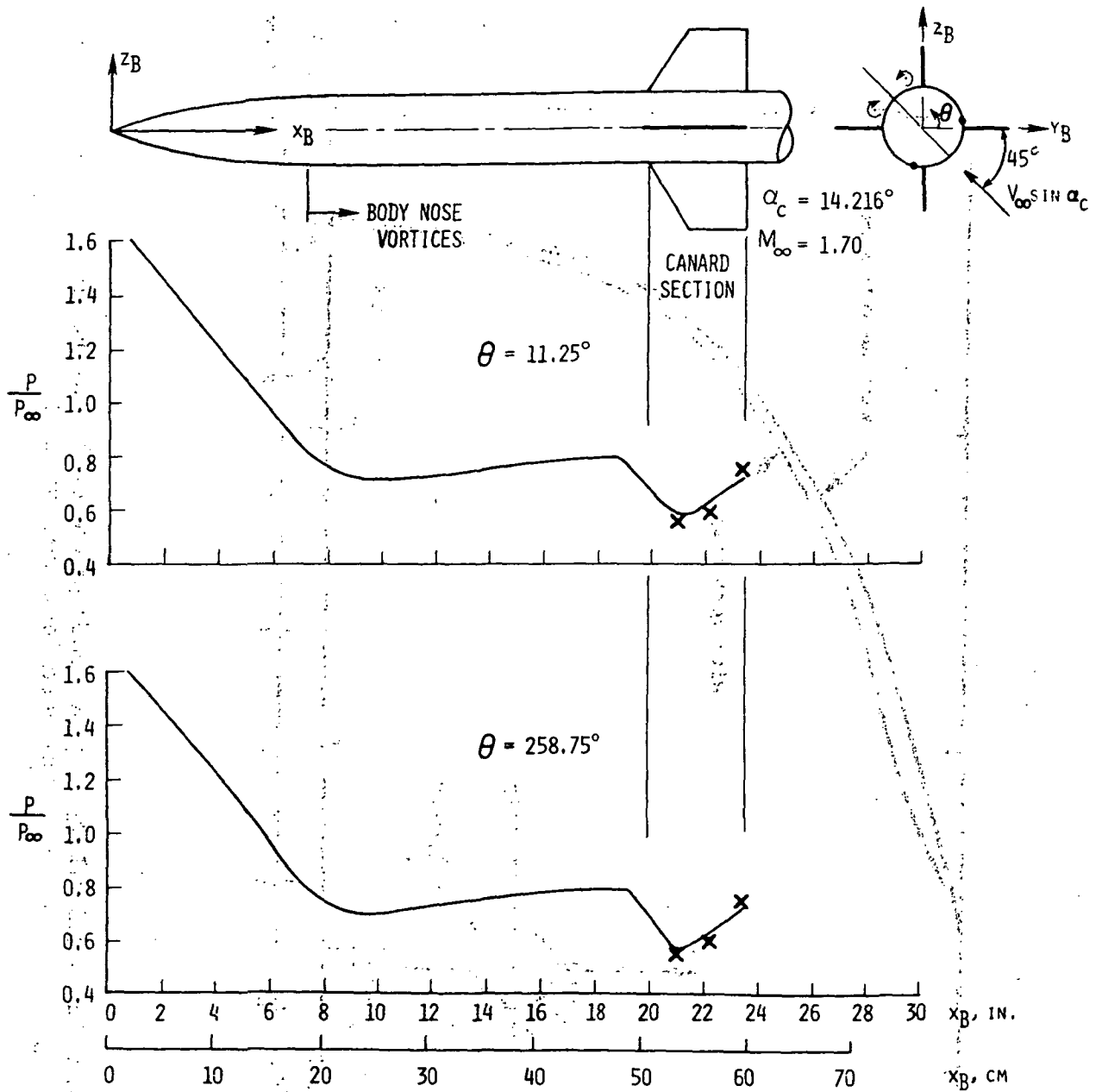


Figure 11(b).- Concluded.

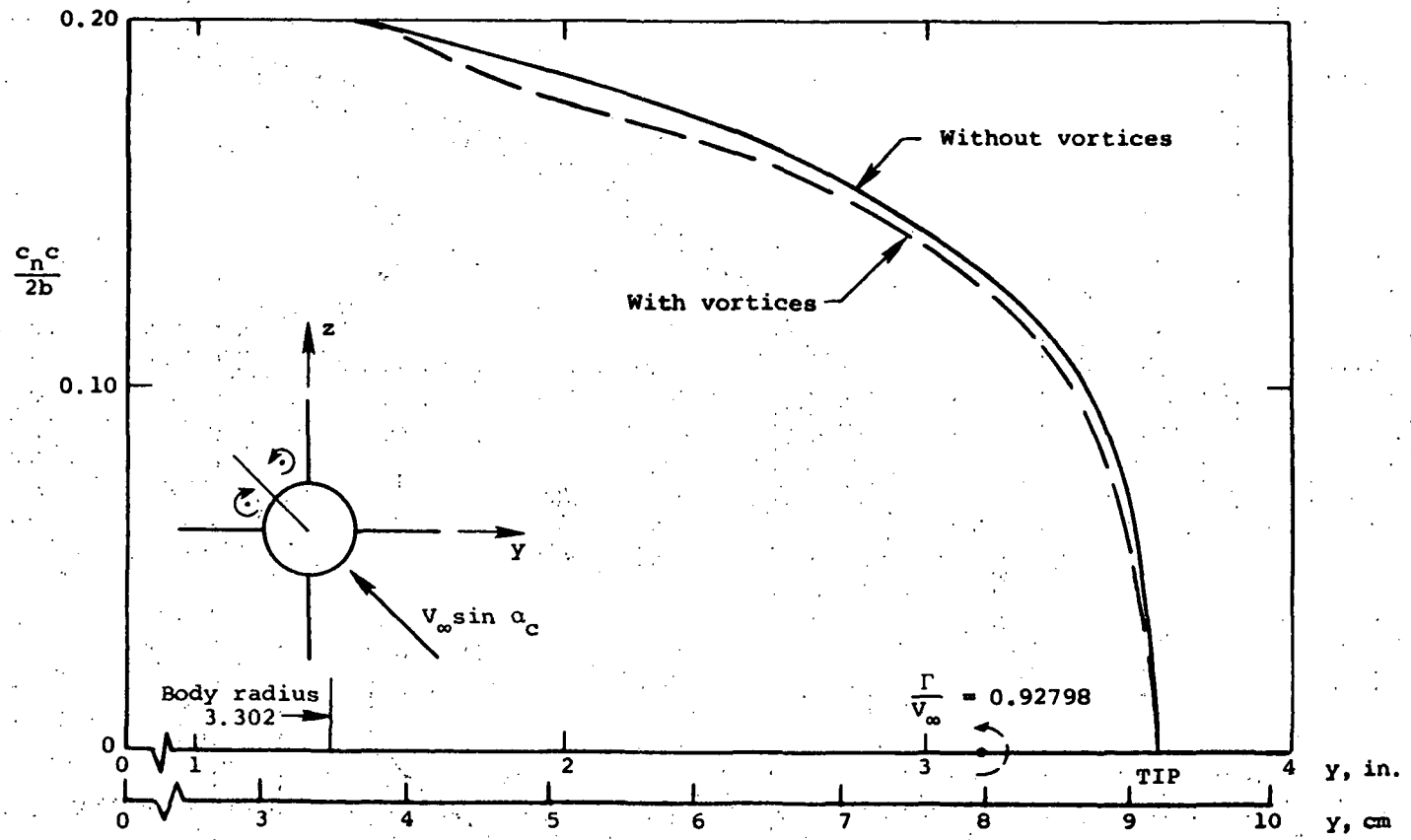


Figure 12.- Calculated span loading on right horizontal canard fin, first sample case, step 3.

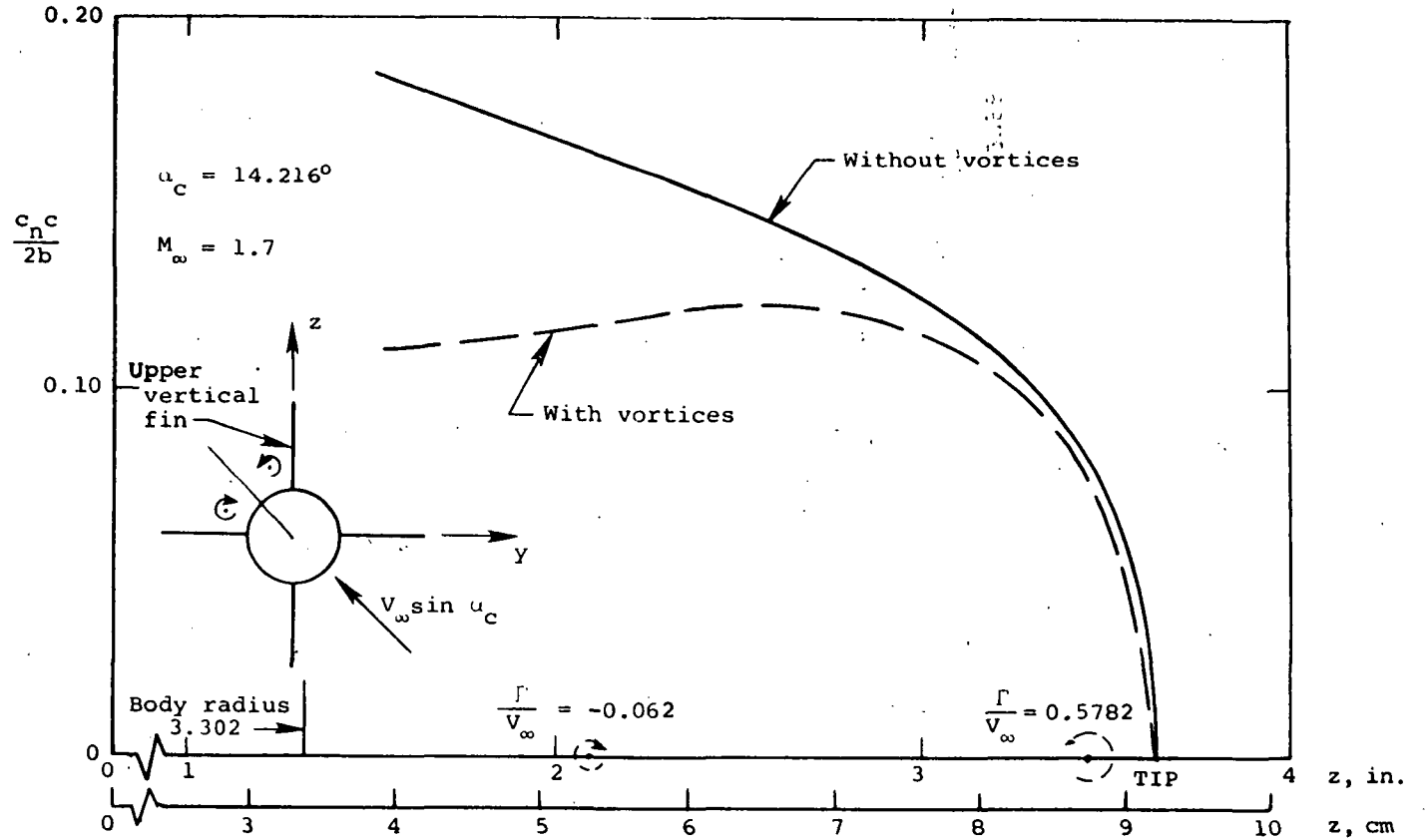
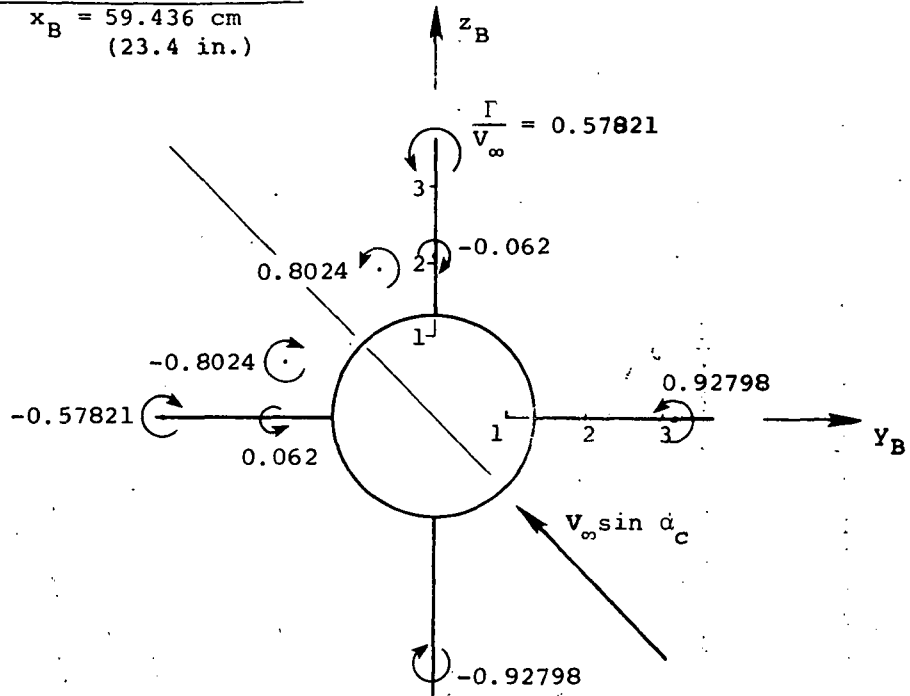


Figure 13.- Calculated span loading on the upper vertical fin, first sample case, step 3.

CANARD TRAILING EDGE

$x_B = 59.436 \text{ cm}$
(23.4 in.)



BODY BASE

$x_B = 99.060 \text{ cm}$
(39.0 in.)

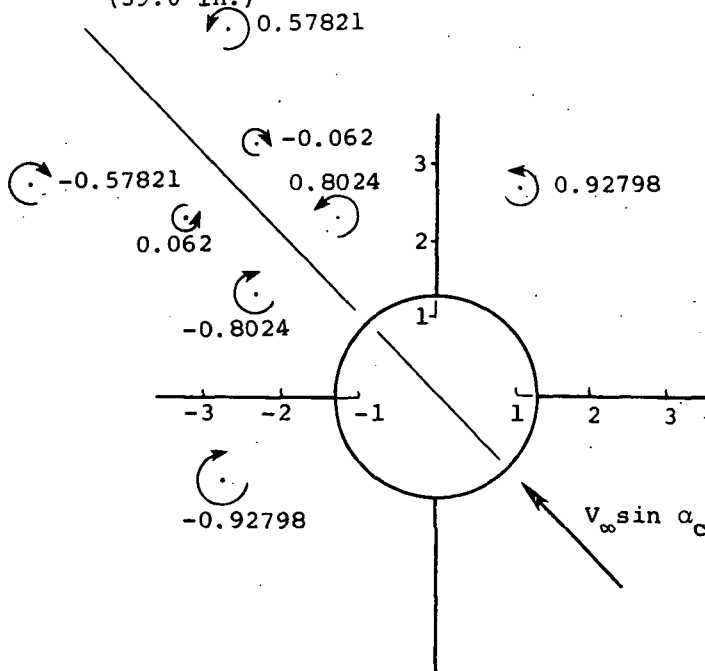


Figure 14.- Calculated vortex positions,
first sample case, step 5.

NASA/LRC PROJECT 1126, CONFIGURATION 8114, CHASE VORTICES AFT OF CANARD SECTION.

	1	4	26	1	1	0		
39.0								
1.3								
35.4	1.3	36.751	3.64	39.0	3.64	39.00001	1.3	
14.216	45.0	0.0	0.0	0.0	0.0	0.00001	0.35	
8	8	8	8	8	8	8	8	8
8	8	8	8	8	8	8	8	8
=0.68451	1.9192	0.8024	-1.9192	0.68451	-0.8024			
5.15424	0.0	0.94911	-2.09688	0.0	0.05844			
=3.46609	0.0	=0.59187	0.0	2.09688	=0.05844			
0.0	3.46609	0.59187	0.0	=3.15424	=0.94911			
23.4	24.024	24.648	25.272	25.896	26.52	27.144	27.768	
28.392	29.016	29.64	30.264	30.888	31.512	32.136	32.76	
33.384	34.008	34.632	35.256	35.88	36.504	37.128	37.752	
38.376	39.0							
0	0	0	0	0				
0								

Figure 15.- Input for program VPATH2, first sample case, step 5.

NASA/LRC PROJECT 1126, CONFIGURATION WITH CHASE VORTICES AFT OF CANARD SECTION.

FIN GEOMETRY
 FIN SEMISPAN = 3.64000
 FIN ROOTCHORD = 3.60001
 FIN ROOT L.E. X-STATION= 35.40000
 L.E. Y-STATION= 1.30000
 FIN TIP L.E. X-STATION = 36.75100
 L.E. Y-STATION = 3.64000
 FIN TIP T.E. X-STATION = 39.00000
 T.E. Y-STATION = 3.64000
 FIN ROOT T.E. X-STATION= 39.00001
 T.E. Y-STATION= 1.30000

INCLUDED ANGLE OF ATTACK(DEG) = 14.21600 ROLL ANGLE(DEG) = 45.00000

PANEL DEFL.(DEG) :

DELTA1= 0.000 DELTA2= 0.000 DELTA3= 0.000 DELTA4= 0.000

***PERMISSIBLE RELATIVE ERROR, AS USED IN INTEGRATION SCHEME = .10000E+00

VORTEX COORDINATES IN CROSS-FLow PLANE
 INITIAL VORTEX POSITIONS AT X= 23.400

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI-SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.64451E+00	.19192E+01	.80240E+00
2	-.19192E+01	.68451E+00	.80240E+00
3	.31542E+01	0.	.94911E+00
4	-.20969E+01	0.	.58440E+01
5	-.34661E+01	0.	.54187E+00
6	0.	.20969E+01	.58440E+01
7	0.	.34661E+01	.54187E+00
8	0.	.31542E+01	.94911E+00

X-STATION NO. 2 X=24.024 INTEGRATION STEP SIZE = .09984

Figure 16.- Output of program VPATH2, first sample case, step 5.

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.70738E+00	.19461E+01	.80240E+00
2	-.19461E+01	.70738E+00	.80240E+00
3	.30065E+01	.10549E+00	.94911E+00
4	-.22397E+01	.80295E-01	.58440E-01
5	-.35540E+01	.12835E+00	-.59187E+00
6	-.80872E+01	.22397E+01	-.58440E-01
7	-.12871E+00	.35539E+01	.59187E+00
8	-.10505E+00	.30065E+01	-.94911E+00

X-STATION NO. 3 X=24.046 INTEGRATION STEP SIZE = .19966

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.73263E+00	.19738E+01	.80240E+00
2	-.19738E+01	.73263E+00	.80240E+00
3	.30065E+01	.21217E+00	.94911E+00
4	-.23810E+01	.17808E+00	.58440E-01
5	-.36394E+01	.25624E+00	-.59187E+00
6	-.17871E+00	.23810E+01	-.58440E-01
7	-.25660E+00	.36394E+01	.59187E+00
8	-.21172E+00	.30065E+01	-.94911E+00

X-STATION NO. 4 X=25.272 INTEGRATION STEP SIZE = .19966

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.74032E+00	.20019E+01	.80240E+00
2	-.20019E+01	.74032E+00	.80240E+00
3	.27315E+01	.32003E+00	.94911E+00
4	-.25136E+01	.29043E+00	.58440E-01
5	-.37227E+01	.38294E+00	-.59187E+00
6	-.29112E+00	.25136E+01	-.58440E-01
7	-.38338E+00	.37226E+01	.59187E+00
8	-.31457E+00	.27315E+01	-.94911E+00

X-STATION NO. 5 X=25.896 INTEGRATION STEP SIZE = .39936

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.77015E+00	.20298E+01	.80240E+00
2	-.20298E+01	.77015E+00	.80240E+00
3	.24500E+01	.42908E+00	.94911E+00
4	-.26324E+01	.41257E+00	.58440E-01
5	-.38038E+01	.50814E+00	-.59187E+00
6	-.41532E+00	.26324E+01	-.58440E-01
7	-.50852E+00	.38037E+01	.59187E+00
8	-.42801E+00	.24500E+01	-.94911E+00

X-STATION NO. 6 X=26.520 INTEGRATION STEP SIZE = .39936

Figure 16.- Continued.

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.82163E+00	.20574E+01	.80240E+00
2	-.20574E+01	.82154E+00	-.80240E+00
3	.27796E+01	.53929E+00	.94911E+00
4	-.27354E+01	.53923E+00	.58440E+01
5	-.36629E+01	.65174E+00	-.59187E+00
6	-.54005E+00	.27353E+01	-.58440E+01
7	-.63209E+00	.38828E+01	.59187E+00
8	-.53882E+00	-.27797E+01	-.94911E+00

X-STATION NO. 7 X=27.144 INTEGRATION STEP SIZE = .39936

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.85443E+00	.20845E+01	.80240E+00
2	-.20845E+01	.85435E+00	-.80240E+00
3	.27022E+01	.65964E+00	.94911E+00
4	-.28250E+01	.66517E+00	.58440E+01
5	-.39004E+01	.75356E+00	-.59187E+00
6	-.66704E+00	.28228E+01	-.58440E+01
7	-.75391E+00	.39603E+01	.59187E+00
8	-.65016E+00	-.27023E+01	-.94911E+00

X-STATION NO. 8 X=27.768 INTEGRATION STEP SIZE = .39936

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.88821E+00	.21111E+01	.80240E+00
2	-.21111E+01	.88813E+00	-.80240E+00
3	.26237E+01	.76507E+00	.94911E+00
4	-.28949E+01	.79060E+00	.58440E+01
5	-.40363E+01	.87357E+00	-.59187E+00
6	-.79151E+00	.28966E+01	-.58440E+01
7	-.87392E+00	.40362E+01	.59187E+00
8	-.76258E+00	-.26237E+01	-.94911E+00

X-STATION NO. 9 X=28.392 INTEGRATION STEP SIZE = .39936

Figure 16.- Continued.

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.92271E+00	.21372E+01	.80240E+00
2	-.21372E+01	.92263E+00	-.80240E+00
3	.25437E+01	.87647E+00	.94911E+00
4	-.29594E+01	.91105E+00	-.58440E-01
5	-.41110E+01	.99178E+00	-.59187E+00
6	-.91200E+00	.29589E+01	-.58440E-01
7	-.99212E+00	.41109E+01	.59187E+00
8	-.87598E+00	-.25438E+01	-.94911E+00

X-STATION NO. 10 X=29.016 INTEGRATION STEP SIZE = .39936

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.95776E+00	.21628E+01	.80240E+00
2	-.21628E+01	.95769E+00	-.80240E+00
3	.24623E+01	.99074E+00	.94911E+00
4	-.31124E+01	.10269E+01	-.58440E-01
5	-.41847E+01	.11082E+01	-.59187E+00
6	-.10279E+01	.30118E+01	-.58440E-01
7	-.11085E+01	.41846E+01	.59187E+00
8	-.99024E+00	-.24624E+01	-.94911E+00

X-STATION NO. 11 X=29.640 INTEGRATION STEP SIZE = .39936

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.99319E+00	.21879E+01	.80240E+00
2	-.21879E+01	.99312E+00	-.80240E+00
3	.23791E+01	.11057E+01	.94911E+00
4	-.30579E+01	.11379E+01	-.58440E-01
5	-.42575E+01	.12229E+01	-.59187E+00
6	-.11389E+01	.30572E+01	-.58440E-01
7	-.12232E+01	.42574E+01	.59187E+00
8	-.11052E+01	-.23792E+01	-.94911E+00

X-STATION NO. 12 X=30.264 INTEGRATION STEP SIZE = .79872

Figure 16.- Continued.

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.10289E+01	.22125E+01	.80240E+00
2	-.22125E+01	.10289E+01	-.80240E+00
3	.22942E+01	.12211E+01	.94911E+00
4	-.30974E+01	.12443E+01	-.58440E-01
5	-.43297E+01	.13359E+01	-.59187E+00
6	-.12454E+01	.30965E+01	-.58440E-01
7	-.13363E+01	.43295E+01	.59187E+00
8	-.12206E+01	-.22943E+01	-.94911E+00

X=STATION NO. 14 X=30.885 INTEGRATION STEP SIZE = .79872

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.10546E+01	.22363E+01	.80240E+00
2	-.22363E+01	.10546E+01	-.80240E+00
3	.22073E+01	.13368E+01	.94911E+00
4	-.31320E+01	.13463E+01	-.58440E-01
5	-.44013E+01	.14474E+01	-.59187E+00
6	-.13473E+01	.31309E+01	-.58440E-01
7	-.14477E+01	.44012E+01	.59187E+00
8	-.13363E+01	-.22074E+01	-.94911E+00

X=STATION NO. 14 X=31.512 INTEGRATION STEP SIZE = .79872

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.11024E+01	.22595E+01	.80240E+00
2	-.22595E+01	.11024E+01	-.80240E+00
3	.21165E+01	.14526E+01	.94911E+00
4	-.31627E+01	.14440E+01	-.58440E-01
5	-.44726E+01	.15573E+01	-.59187E+00
6	-.14451E+01	.31615E+01	-.58440E-01
7	-.15576E+01	.44724E+01	.59187E+00
8	-.14521E+01	-.21186E+01	-.94911E+00

X=STATION NO. 15 X=32.136 INTEGRATION STEP SIZE = .79872

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
--------	--------	--------	------------

Figure 16.- Continued.

1	-.11559E+01	.22417E+01	.80240E+00
2	-.22417E+01	.11559E+01	-.80240E+00
3	.20278E+01	.15681E+01	.94911E+00
4	-.31905E+01	.15379E+01	.58440E+01
5	-.44435E+01	.16657E+01	-.59187E+00
6	-.15389E+01	.31891E+01	-.58440E+01
7	-.16661E+01	.45434E+01	.59187E+00
8	-.15676E+01	-.20279E+01	-.94911E+00

X-STATION NO. 16 X=32.760 INTEGRATION STEP SIZE = .79872

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.11712E+01	.23029E+01	.80240E+00
2	-.23029E+01	.11712E+01	-.80240E+00
3	.19352E+01	.16431E+01	.94911E+00
4	-.32158E+01	.16280E+01	.58440E+01
5	-.46143E+01	.17728E+01	-.59187E+00
6	-.16290E+01	.32142E+01	-.58440E+01
7	-.17732E+01	.46142E+01	.59187E+00
8	-.16820E+01	-.19353E+01	-.94911E+00

X-STATION NO. 17 X=33.384 INTEGRATION STEP SIZE = .79872

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.12060E+01	.23229E+01	.80240E+00
2	-.23229E+01	.12060E+01	-.80240E+00
3	.18409E+01	.17975E+01	.94911E+00
4	-.32392E+01	.17147E+01	.58440E+01
5	-.46450E+01	.18787E+01	-.59187E+00
6	-.17157E+01	.32374E+01	-.58440E+01
7	-.18740E+01	.46448E+01	.59187E+00
8	-.17970E+01	-.18410E+01	-.94911E+00

X-STATION NO. 18 X=34.008 INTEGRATION STEP SIZE = .79872

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 1.30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.12401E+01	.23415E+01	.80240E+00
2	-.23415E+01	.12401E+01	-.80240E+00
3	.17450E+01	.19111E+01	.94911E+00
4	-.32613E+01	.17982E+01	.58440E+01
5	-.47555E+01	.19433E+01	-.59187E+00
6	-.17992E+01	.32593E+01	-.58440E+01
7	-.19436E+01	.47554E+01	.59187E+00
8	-.19166E+01	-.17452E+01	-.94911E+00

X-STATION NO. 19 X=34.652 INTEGRATION STEP SIZE = .79872

Figure 16.- Continued.

LOCAL BODY RADIUS = 1,30000 LOCAL SEMI SPAN S = 1,30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.12735E+01	.23586E+01	.80240E+00
2	-.23587E+01	.12735E+01	-.80240E+00
3	.16478E+01	.20237E+01	.94911E+00
4	-.32823E+01	.18786E+01	.58440E-01
5	-.48261E+01	.20864E+01	-.59187E+00
6	-.18796E+01	.32802E+01	-.58440E-01
7	-.20871E+01	.48259E+01	.59187E+00
8	-.20232E+01	-.16480E+01	-.94911E+00

X-STATION NO. 20 X=35,256 INTEGRATION STEP SIZE = .79872

LOCAL BODY RADIUS = 1,30000 LOCAL SEMI SPAN S = 1,30000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.13058E+01	.23739E+01	.80240E+00
2	-.23740E+01	.13058E+01	-.80240E+00
3	.15495E+01	.21354E+01	.94911E+00
4	-.33028E+01	.19563E+01	.58440E-01
5	-.48966E+01	.21892E+01	-.59187E+00
6	-.19572E+01	.33004E+01	-.58440E-01
7	-.21895E+01	.48964E+01	.59187E+00
8	-.21349E+01	-.15497E+01	-.94911E+00

X-STATION NO. 21 X=35,880 INTEGRATION STEP SIZE = .15600

LOCAL BODY RADIUS = 1,30000 LOCAL SEMI SPAN S = 2,13138

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.13363E+01	.23855E+01	.80240E+00
2	-.23856E+01	.13363E+01	-.80240E+00
3	.14500E+01	.22455E+01	.94911E+00
4	-.33221E+01	.20309E+01	.58440E-01
5	-.49667E+01	.22905E+01	-.59187E+00
6	-.20318E+01	.33195E+01	-.58440E-01
7	-.22908E+01	.49665E+01	.59187E+00
8	-.22450E+01	-.14501E+01	-.94911E+00

X-STATION NO. 22 X=36,504 INTEGRATION STEP SIZE = .15600

LOCAL BODY RADIUS = 1,30000 LOCAL SEMI SPAN S = 3,21218

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	-.13557E+01	.23814E+01	.80240E+00
2	-.23815E+01	.13558E+01	-.80240E+00
3	.13547E+01	.23508E+01	.94911E+00
4	-.33629E+01	.20992E+01	.58440E-01
5	-.50321E+01	.23904E+01	-.59187E+00
6	-.20900E+01	.33301E+01	-.58440E-01
7	-.23907E+01	.50319E+01	.59187E+00
8	-.23503E+01	-.13548E+01	-.94911E+00

Figure 16.- Continued.

X-STATION NO. 23 X=37.124 INTEGRATION STEP SIZE = .31200

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000

VORTEX	V.VRTX	Z.VRTX	GAMMA/VINF
1	-.14564E+01	.23648E+01	.80240E+00
2	-.23649E+01	.13564E+01	-.80240E+00
3	.12754E+01	.24445E+01	.94911E+00
4	-.34298E+01	.21551E+01	-.58440E+01
5	-.50477E+01	.24880E+01	-.59187E+00
6	-.21554E+01	.33269E+01	-.58440E+01
7	-.24883E+01	.50875E+01	-.59187E+00
8	-.24880E+01	-.12754E+01	-.94911E+00

X-STATION NO. 24 X=37.752 INTEGRATION STEP SIZE = .62400

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000

VORTEX	V.VRTX	Z.VRTX	GAMMA/VINF
1	-.13546E+01	.23468E+01	.80240E+00
2	-.24669E+01	.13546E+01	-.80240E+00
3	.11981E+01	.25470E+01	.94911E+00
4	-.33275E+01	.22076E+01	-.58440E+01
5	-.51432E+01	.25841E+01	-.59187E+00
6	-.22082E+01	.33244E+01	-.58440E+01
7	-.25844E+01	.51430E+01	-.59187E+00
8	-.25465E+01	-.11983E+01	-.94911E+00

X-STATION NO. 25 X=38.376 INTEGRATION STEP SIZE = .62400

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000

VORTEX	V.VRTX	Z.VRTX	GAMMA/VINF
1	-.13520E+01	.23281E+01	.80240E+00
2	-.24282E+01	.13520E+01	-.80240E+00
3	.11204E+01	.26476E+01	.94911E+00
4	-.33211E+01	.22545E+01	-.58440E+01
5	-.51999E+01	.26790E+01	-.59187E+00
6	-.22500E+01	.33244E+01	-.58440E+01
7	-.26793E+01	.51997E+01	-.59187E+00
8	-.26471E+01	-.11209E+01	-.94911E+00

X-STATION NO. 26 X=39.000 INTEGRATION STEP SIZE = .62400

LOCAL BODY RADIUS = 1.30000 LOCAL SEMI SPAN S = 3.64000

VORTEX	V.VRTX	Z.VRTX	GAMMA/VINF
1	-.13485E+01	.23086E+01	.80240E+00
2	-.23086E+01	.13485E+01	-.80240E+00
3	.10450E+01	.27506E+01	.94911E+00

Figure 16.- Continued.

4	-.33316E+01	.23082E+01	.58440E-01
5	-.52578E+01	.27729E+01	-.59187E+00
6	-.23086E+01	.33882E+01	.58440E-01
7	-.27732E+01	.52578E+01	.59187E+00
8	-.27500E+01	-.10432E+01	-.94011E+00

CROSSFLOW VELOCITIES AT CONTROL POINTS INDUCED BY VORTICES AND THEIR IMAGES

IC	X, BODY	Y, BODY	Z, BODY	V	W
1	.36631E+02	.15310E+01	0.	.22541E-01	-.74105E-01
2	.37787E+02	.15310E+01	0.	.19927E-01	-.67006E-01
3	.38942E+02	.15310E+01	0.	.17798E-01	-.61175E-01
4	.38816E+02	.19987E+01	0.	.41619E-01	-.45614E-01
5	.37481E+02	.19987E+01	0.	.37375E-01	-.42293E-01
6	.38947E+02	.19987E+01	0.	.33859E-01	-.39479E-01
7	.37000E+02	.24664E+01	0.	.44308E-01	-.28003E-01
8	.37976E+02	.24664E+01	0.	.40555E-01	-.25916E-01
9	.38951E+02	.24664E+01	0.	.37364E-01	-.24108E-01
10	.37185E+02	.29340E+01	0.	.40999E-01	-.13556E-01
11	.38070E+02	.29340E+01	0.	.38258E-01	-.13699E-01
12	.38956E+02	.29340E+01	0.	.35851E-01	-.13763E-01
13	.37369E+02	.34016E+01	0.	.36017E-01	-.60080E-02
14	.38165E+02	.34016E+01	0.	.34184E-01	-.65582E-02
15	.38960E+02	.34016E+01	0.	.32528E-01	-.70081E-02
16	.36631E+02	-.15310E+01	0.	.25922E-01	-.24335E+00
17	.37787E+02	-.15310E+01	0.	.24109E-01	-.25303E+00
18	.38942E+02	-.15310E+01	0.	.19507E-01	-.25801E+00
19	.36816E+02	-.19987E+01	0.	.51219E-01	-.17161E+00
20	.37881E+02	-.19987E+01	0.	.53408E-01	-.18549E+00
21	.38947E+02	-.19987E+01	0.	.48996E-01	-.19858E+00
22	.37000E+02	-.24664E+01	0.	.59843E-01	-.91572E-01
23	.37976E+02	-.24664E+01	0.	.74149E-01	-.10355E+00
24	.38951E+02	-.24664E+01	0.	.84330E-01	-.12168E+00
25	.37185E+02	-.29340E+01	0.	.56495E-01	-.21821E-01
26	.38070E+02	-.29340E+01	0.	.75910E-01	-.23056E-01
27	.36956E+02	-.29340E+01	0.	.98558E-01	-.29250E-01
28	.37369E+02	-.34016E+01	0.	.41993E-01	.14525E+01
29	.38165E+02	-.34016E+01	0.	.57886E-01	.19927E-01
30	.38960E+02	-.34016E+01	0.	.74961E-01	.25394E-01
31	.36631E+02	.73521E-13	.15310E+01	.24338E+00	-.25911E-01
32	.37787E+02	.73521E-13	.15310E+01	.25305E+00	-.24092E-01
33	.38942E+02	.73521E-13	.15310E+01	.25802E+00	-.19486E-01
34	.36816E+02	.95983E-13	.19987E+01	.17165E+00	-.51210E-01
35	.37881E+02	.95983E-13	.19987E+01	.18549E+00	-.53383E-01
36	.38947E+02	.95983E-13	.19987E+01	.19861E+00	-.48956E-01
37	.37000E+02	.11844E-12	.24664E+01	.91616E-01	-.59862E-01
38	.37976E+02	.11844E-12	.24664E+01	.10360E+00	-.74159E-01
39	.38951E+02	.11844E-12	.24664E+01	.12174E+00	-.84319E-01
40	.37185E+02	.14090E-12	.29340E+01	.21847E-01	-.56537E-01
41	.38070E+02	.14090E-12	.29340E+01	.23094E-01	-.75960E-01
42	.38956E+02	.14090E-12	.29340E+01	.29311E-01	-.98614E-01
43	.37369E+02	.16335E-12	.34016E+01	-.14321E-01	-.44031E-01
44	.38165E+02	.16335E-12	.34016E+01	-.19920E-01	-.57935E-01
45	.38960E+02	.16335E-12	.34016E+01	-.25385E-01	-.75025E-01
46	.36631E+02	-.73521E-13	-.15310E+01	.74107E-01	-.22546E-01
47	.37787E+02	-.73521E-13	-.15310E+01	.67006E-01	-.19931E-01
48	.38942E+02	-.73521E-13	-.15310E+01	.61173E-01	-.17801E-01
49	.38816E+02	-.95983E-13	-.19987E+01	.45611E-01	-.41626E-01
50	.37481E+02	-.95983E-13	-.19987E+01	.42284E-01	-.37381E-01
51	.38947E+02	-.95983E-13	-.19987E+01	.39475E-01	-.33864E-01
52	.37000E+02	-.11844E-12	-.24664E+01	.25997E-01	-.44314E-01
53	.37976E+02	-.11844E-12	-.24664E+01	.25009E-01	-.40561E-01
54	.38951E+02	-.11844E-12	-.24664E+01	.24101E-01	-.37368E-01
55	.37185E+02	-.14090E-12	-.29340E+01	.13548E-01	-.41002E-01

Figure 16.- Continued.

56	.3A770E+02	-.14040E-12	-.29340E+01	.13092E-01	-.56261E-01
57	.3A956E+02	-.14040E-12	-.29340E+01	.13750E-01	-.35954E-01
58	.37369E+02	-.14335E-12	-.34016E+01	.60006E-02	-.56018E+01
59	.3A165E+02	-.16335E-12	-.34016E+01	.65510E-02	-.34145E-01
60	.3B900E+02	-.16335E-12	-.40115E+01	.70012E-02	-.32529E+01
61	.36540E+02	.12505E+01	.24874E+00	.21274E-01	-.12973E+00
62	.36540E+02	.10601E+01	.70836E+00	.12747E+00	-.20246E+00
63	.36540E+02	.70836E+00	.10601E+01	.28733E+00	-.19570E+00
64	.36540E+02	.24874E+00	.12505E+01	.32366E+00	-.60836E-01
65	.36540E+02	-.24874E+00	.12505E+01	.24801E+00	-.53501E-01
66	.36540E+02	-.70836E+00	.10601E+01	.91774E-01	.73741E-01
67	.36540E+02	-.10601E+01	.70836E+00	-.73710E-01	-.91728E-01
68	.36540E+02	-.12505E+01	.24874E+00	-.53496E-01	-.24796E+00
69	.36540E+02	-.12505E+01	-.24874E+00	.60831E-01	-.32366E+00
70	.36540E+02	-.10601E+01	-.70836E+00	.19573E+00	-.26788E+00
71	.36540E+02	-.70836E+00	-.10601E+01	.20250E+00	-.12770E+00
72	.36540E+02	-.24874E+00	-.12505E+01	.12675E+00	-.21275E-01
73	.36540E+02	.24874E+00	-.12505E+01	.61460E-01	.14660E-01
74	.36540E+02	.70836E+00	-.10601E+01	.14602E-01	.12662E-01
75	.36540E+02	.10601E+01	-.70836E+00	-.12066E-01	-.14607E-01
76	.36540E+02	.12505E+01	-.24874E+00	-.14800E-01	-.61401E-01
77	.37740E+02	.12505E+01	.24874E+00	.19040E-01	-.11463E+00
78	.37740E+02	.10601E+01	.70836E+00	.11255E+00	-.17859E+00
79	.37740E+02	.70836E+00	.10601E+01	.26421E+00	-.14126E+00
80	.37740E+02	.24874E+00	.12505E+01	.32649E+00	-.62557E-01
81	.37740E+02	-.24874E+00	.12505E+01	.25853E+00	.55706E-01
82	.37740E+02	-.70836E+00	.10601E+01	.95493E-01	.77032E-01
83	.37740E+02	-.10601E+01	.70836E+00	-.76997E-01	-.95841E-01
84	.37740E+02	-.12505E+01	.24874E+00	-.55699E-01	-.25849E+00
85	.37740E+02	-.12505E+01	-.24874E+00	-.62555E-01	-.32650E+00
86	.37740E+02	-.10601E+01	-.70836E+00	.18130E+00	-.26427E+00
87	.37740E+02	-.70836E+00	-.10601E+01	.17462E+00	-.11257E+00
88	.37740E+02	-.24874E+00	-.12505E+01	.11464E+00	-.19041E-01
89	.37740E+02	.24874E+00	-.12505E+01	.55514E-01	.13401E-01
90	.37740E+02	.70836E+00	-.10601E+01	.13307E-01	.10989E-01
91	.37740E+02	.10601E+01	-.70836E+00	-.10893E-01	-.13314E-01
92	.37740E+02	.12505E+01	-.24874E+00	-.13401E-01	-.55516E-01
93	.38940E+02	.12505E+01	.24874E+00	.17227E-01	-.10314E+00
94	.38940E+02	.10601E+01	.70836E+00	.99922E-01	-.15845E+00
95	.38940E+02	.70836E+00	.10601E+01	.23901E+00	-.16495E+00
96	.38940E+02	.24874E+00	.12505E+01	.31998E+00	-.62611E-01
97	.38940E+02	-.24874E+00	.12505E+01	.26666E+00	.57132E-01
98	.38940E+02	-.70836E+00	.10601E+01	.10028E+00	.80495E-01
99	.38940E+02	-.10601E+01	.70836E+00	-.80058E-01	-.10022E+00
100	.38940E+02	-.12505E+01	.24874E+00	-.57127E-01	-.26662E+00
101	.38940E+02	.12505E+01	-.24874E+00	.62613E-01	-.32000E+00
102	.38940E+02	.10601E+01	-.70836E+00	.14499E+00	-.23900E+00
103	.38940E+02	.70836E+00	-.10601E+01	.15849E+00	-.49937E-01
104	.38940E+02	.24874E+00	-.12505E+01	.16318E+00	-.17227E-01
105	.38940E+02	.24874E+00	-.12505E+01	.50709E-01	.12211E+01
106	.38940E+02	.70836E+00	-.10601E+01	.12245E-01	.10108E-01
107	.38940E+02	.10601E+01	-.70836E+00	-.10113E-01	-.12252E-01
108	.38940E+02	.12505E+01	-.24874E+00	-.12212E-01	-.50714E-01
109	.25145E+02	.12750E+01	.25342E+00	.51894E-01	-.26088E+00
110	.25145E+02	.12010E+01	.49749E+00	.48341E-01	-.23745E+00
111	.25145E+02	.17809E+01	.72224E+00	.13145E+00	-.19612E+00
112	.25145E+02	.91924E+00	.91924E+00	.15447E+00	-.15447E+00
113	.25145E+02	.72224E+00	.10449E+01	.17758E+00	-.11866E+00
114	.25145E+02	.49749E+00	.12010E+01	.20820E+00	-.86245E-01
115	.25145E+02	.25342E+00	.17750E+01	.25233E+00	-.50194E-01
116	.25145E+02	-.46525E-09	.13000E+01	.31195E+00	.11188E-09
117	.25145E+02	-.25342E+00	.12750E+01	.55000E+00	.72225E-01
118	.25145E+02	-.49749E+00	.12010E+01	.32579E+00	.13497E+00
119	.25145E+02	-.72224E+00	.10449E+01	.17191E+00	.11488E+00
120	.25145E+02	-.91924E+00	.91924E+00	.21260E+00	.19278E-04

Figure 16.- Continued.

121	.25145E+02	-.10609E+01	.72224E+00	-.11485E+00	-.17187E+00
122	.25145E+02	-.12010E+01	.49749E+00	-.13496E+00	-.32577E+00
123	.25145E+02	-.12750E+01	.25362E+00	-.72226E-01	-.35000E+00
124	.25145E+02	-.11000E+01	-.93250E-09	.22377E-09	-.31196E+00
125	.25145E+02	-.12750E+01	-.25362E+00	.50195E-01	-.25232E+00
126	.25145E+02	-.12010E+01	-.49749E+00	.86201E-01	-.20819E+00
127	.25145E+02	-.10809E+01	-.72224E+00	.11665E+00	-.17757E+00
128	.25145E+02	-.91924E+00	-.91924E+00	.15445E+00	-.15445E+00
129	.25145E+02	-.72224E+00	-.10809E+01	.19610E+00	-.13101E+00
130	.25145E+02	-.49749E+00	-.12010E+01	.23743E+00	-.98352E-01
131	.25145E+02	-.25362E+00	-.12750E+01	.26098E+00	-.51893E-01
132	.25145E+02	.13968E-08	-.13000E+01	.24729E+00	.26608E-09
133	.25145E+02	.25362E+00	-.12750E+01	.19580E+00	.38953E-01
134	.25145E+02	.49749E+00	-.12010E+01	.12534E+00	.51432E-01
135	.25145E+02	.72224E+00	-.10809E+01	.56213E-01	.37546E-01
136	.25145E+02	.91924E+00	-.91924E+00	.18354E-04	.17729E-04
137	.25145E+02	.10809E+01	-.72224E+00	-.37535E-01	-.56170E-01
138	.25145E+02	.12010E+01	-.49749E+00	-.51913E-01	-.12530E+00
139	.25145E+02	.12750E+01	-.25362E+00	-.39944E-01	-.19574E+00
140	.25145E+02	.13000E+01	.14659E-08	.35473E-09	-.24726E+00
141	.27197E+02	.12750E+01	.25362E+00	.57843E-01	-.29080E+00
142	.27197E+02	.12010E+01	.49749E+00	.11533E+00	-.27853E+00
143	.27197E+02	.10809E+01	.72224E+00	.15419E+00	-.25075E+00
144	.27197E+02	.91924E+00	.91924E+00	.17505E+00	-.17505E+00
145	.27197E+02	.72224E+00	.10809E+01	.18984E+00	-.12685E+00
146	.27197E+02	.49749E+00	.12010E+01	.20942E+00	-.86749E-01
147	.27197E+02	.25362E+00	.12750E+01	.24021E+00	-.47784E-01
148	.27197E+02	-.46625E-09	.13000E+01	.28172E+00	.10104E-09
149	.27197E+02	-.25362E+00	.12750E+01	.31289E+00	.62238E-01
150	.27197E+02	-.49749E+00	.12010E+01	.27791E+00	.11513E+00
151	.27197E+02	-.72224E+00	.10809E+01	.15109E+00	.10096E+00
152	.27197E+02	-.91924E+00	.91924E+00	.15768E-04	.13993E-04
153	.27197E+02	-.10809E+01	.72224E+00	-.10095E+00	-.15106E+00
154	.27197E+02	-.12010E+01	.49749E+00	-.11512E+00	-.27784E+00
155	.27197E+02	-.12750E+01	.25362E+00	-.62237E-01	-.31289E+00
156	.27197E+02	-.13000E+01	-.93250E-09	.20208E-09	-.28172E+00
157	.27197E+02	-.12750E+01	-.25362E+00	.47781E-01	-.24019E+00
158	.27197E+02	-.12010E+01	-.49749E+00	.66740E-01	-.20940E+00
159	.27197E+02	-.10809E+01	-.72224E+00	.12583E+00	-.18982E+00
160	.27197E+02	-.91924E+00	-.91924E+00	.17503E+00	-.17503E+00
161	.27197E+02	-.72224E+00	-.10809E+01	.23072E+00	-.15416E+00
162	.27197E+02	-.49749E+00	-.12010E+01	.27852E+00	-.11537E+00
163	.27197E+02	-.25362E+00	-.12750E+01	.29082E+00	-.57847E-01
164	.27197E+02	.13968E-08	-.13000E+01	.25424E+00	.27356E-09
165	.27197E+02	.25362E+00	-.12750E+01	.18614E+00	.37032E-01
166	.27197E+02	.49749E+00	-.12010E+01	.11272E+00	.46701E-01
167	.27197E+02	.72224E+00	-.10809E+01	.49035E-01	.32767E-01
168	.27197E+02	.91924E+00	-.91924E+00	.16423E-04	.15883E-04
169	.27197E+02	.10809E+01	-.72224E+00	.32741E-01	-.48996E-01
170	.27197E+02	.12010E+01	-.49749E+00	-.46641E-01	-.11267E+00
171	.27197E+02	.12750E+01	.25362E+00	.37021E-01	-.18609E+00
172	.27197E+02	.13000E+01	.14659E-08	.36467E-09	-.25419E+00
173	.29250E+02	.12750E+01	.25362E+00	.57819E-01	-.29069E+00
174	.29250E+02	.12010E+01	.49749E+00	.12823E+00	-.30958E+00
175	.29250E+02	.10809E+01	.72224E+00	.18263E+00	-.27333E+00
176	.29250E+02	.91924E+00	.91924E+00	.20743E+00	-.20743E+00
177	.29250E+02	.72224E+00	.10809E+01	.21495E+00	-.14362E+00
178	.29250E+02	.49749E+00	.12010E+01	.22129E+00	-.91664E-01
179	.29250E+02	.25362E+00	.12750E+01	.23612E+00	-.46969E-01
180	.29250E+02	-.46625E-09	.13000E+01	.25921E+00	.92966E-10
181	.29250E+02	-.25362E+00	.12750E+01	.27333E+00	.54369E-01
182	.29250E+02	-.49749E+00	.12010E+01	.23805E+00	.98619E-01
183	.29250E+02	-.72224E+00	.10809E+01	.13121E+00	.87680E-01
184	.29250E+02	-.91924E+00	.91924E+00	.12532E-04	.10972E-04
185	.29250E+02	-.10809E+01	.72224E+00	-.87664E-01	-.13119E+00

Figure 16.- Continued.

186	.29250E+02	-.12010E+01	.49749E+00	-.98611E-01	-.23304E+00
187	.29250E+02	-.12750E+01	.25362E+00	-.54366E-01	-.27331E+00
188	.29250E+02	-.13000E+01	-.93250E-09	.18592E-09	-.25910E+00
189	.29250E+02	-.12750E+01	-.25362E+00	.48963E-01	-.23409E+00
190	.29250E+02	-.12010E+01	-.49749E+00	.91548E-01	-.22125E+00
191	.29250E+02	-.10809E+01	-.72224E+00	.14360E+00	-.21441E+00
192	.29250E+02	-.91924E+00	-.91924E+00	-.20759E+00	-.20759E+00
193	.29250E+02	-.72224E+00	-.10809E+01	.27331E+00	-.18262E+00
194	.29250E+02	-.49749E+00	-.12010E+01	.50960E+00	-.12824E+00
195	.29250E+02	-.25362E+00	-.12750E+01	.29075E+00	-.57231E-01
196	.29250E+02	.13948E-08	-.13000E+01	.22939E+00	.24683E-09
197	.29250E+02	.25362E+00	-.12750E+01	.15653E+00	.31141E-01
198	.29250E+02	.49749E+00	-.12010E+01	.41194E-01	.37785E-01
199	.29250E+02	.72224E+00	-.10809E+01	.58978E-01	.26047E-01
200	.29250E+02	.91924E+00	-.91924E+00	.11744E-04	.11317E-04
201	.29250E+02	.10809E+01	-.72224E+00	-.26027E-01	-.38449E-01
202	.29250E+02	.12010E+01	-.49749E+00	-.37768E-01	-.41159E-01
203	.29250E+02	.12750E+01	-.25362E+00	-.31130E-01	-.15647E+00
204	.29250E+02	.13000E+01	.18592E-09	.32900E-09	-.22933E+00
205	.31303E+02	.12750E+01	.25362E+00	.49546E-01	-.24911E+00
206	.31303E+02	.12010E+01	.49749E+00	.29865E+00	-.29865E+00
207	.31303E+02	.10809E+01	.72224E+00	.20006E+00	-.29940E+00
208	.31303E+02	.91924E+00	.91924E+00	.24551E+00	-.24551E+00
209	.31303E+02	.72224E+00	.10809E+01	.25475E+00	-.17021E+00
210	.31303E+02	.49749E+00	.12010E+01	.24885E+00	-.10308E+00
211	.31303E+02	.25362E+00	.12750E+01	.24583E+00	-.40901E-10
212	.31303E+02	-.48625E-09	.13000E+01	.24957E+00	.89510E-10
213	.31303E+02	-.25362E+00	.12750E+01	.24707E+00	.49147E-01
214	.31303E+02	.49749E+00	.12010E+01	.20811E+00	.86210E-01
215	.31303E+02	.72224E+00	.10809E+01	.11440E+00	.76488E-01
216	.31303E+02	.91924E+00	.91924E+00	.12027E-04	.10661E-04
217	.31303E+02	.10809E+01	.72224E+00	-.76431E-01	-.11438E+00
218	.31303E+02	-.12010E+01	.49749E+00	-.86210E-01	-.20809E+00
219	.31303E+02	-.12750E+01	.25362E+00	-.49141E-01	-.24704E+00
220	.31303E+02	.13000E+01	-.93250E-09	.17899E-09	-.24954E+00
221	.31303E+02	-.12750E+01	-.25362E+00	.48891E-01	-.24579E+00
222	.31303E+02	-.12010E+01	.49749E+00	.10306E+00	-.24880E+00
223	.31303E+02	.10809E+01	-.72224E+00	.17019E+00	-.25470E+00
224	.31303E+02	.91924E+00	-.91924E+00	-.24549E+00	-.24549E+00
225	.31303E+02	-.72224E+00	-.10809E+01	.29943E+00	-.20007E+00
226	.31303E+02	-.49749E+00	-.12010E+01	.29872E+00	-.12373E+00
227	.31303E+02	-.25362E+00	-.12750E+01	-.86210E-01	-.49560E-01
228	.31303E+02	.13948E-08	-.13000E+01	.18250E+00	.19637E-09
229	.31303E+02	.25362E+00	-.12750E+01	.12022E+00	.23914E-01
230	.31303E+02	.49749E+00	-.12010E+01	.69124E-01	.28640E-01
231	.31303E+02	.72224E+00	-.10809E+01	.29432E-01	.19668E-01
232	.31303E+02	.91924E+00	.91924E+00	.62402E-05	.59178E-05
233	.31303E+02	.10809E+01	-.72224E+00	-.19657E-01	-.29416E-01
234	.31303E+02	.12010E+01	.49749E+00	-.28631E-01	-.69101E-01
235	.31303E+02	.12750E+01	-.25362E+00	-.23911E-01	-.12018E+00
236	.31303E+02	.13000E+01	.18592E-09	.28173E-09	-.18244E+00
237	.33355E+02	.12750E+01	.25362E+00	.38101E-01	-.19157E+00
238	.33355E+02	.12010E+01	.49749E+00	.10173E+00	-.24562E+00
239	.33355E+02	.10809E+01	.72224E+00	.18542E+00	-.27750E+00
240	.33355E+02	.91924E+00	.91924E+00	.26061E+00	-.26061E+00
241	.33355E+02	.72224E+00	.10809E+01	.29458E+00	-.19683E+00
242	.33355E+02	.49749E+00	.12010E+01	.28977E+00	-.12003E+00
243	.33355E+02	.25362E+00	.12750E+01	.27176E+00	-.54056E-01
244	.33355E+02	-.48625E-09	.13000E+01	.25552E+00	.91645E-10
245	.33355E+02	-.25362E+00	.12750E+01	.23542E+00	.26831E-01
246	.33355E+02	-.49749E+00	.12010E+01	.18926E+00	.78408E-01
247	.33355E+02	-.72224E+00	.10809E+01	.12231E+00	.68364E-01
248	.33355E+02	.91924E+00	.91924E+00	.14117E-04	.12498E-04
249	.33355E+02	.10809E+01	.72224E+00	-.68364E-01	-.10227E+00
250	.33355E+02	-.12010E+01	.49749E+00	-.78393E-01	-.18723E+00

Figure 16.- Continued.

251	.33355E+02	-.12750E+01	.25362E+00	-.46822E-01	-.23538E+00
252	.33355E+02	-.13000E+01	-.93250E-09	.18325E-09	-.25548E+00
253	.33355E+02	-.12750E+01	-.25362E+00	.54046E-01	-.27171E+00
254	.33355E+02	-.12010E+01	-.49749E+00	.12001E+00	-.28973E+00
255	.33355E+02	-.10809E+01	-.72224E+00	.19882E+00	-.29457E+00
256	.33355E+02	-.91924E+00	-.91924E+00	.26064E+00	-.26064E+00
257	.33355E+02	-.72224E+00	-.10809E+01	.27756E+00	-.18544E+00
258	.33355E+02	-.49749E+00	-.12010E+01	.24568E+00	-.10174E+00
259	.33355E+02	-.25362E+00	-.12750E+01	.19162E+00	-.38111E-01
260	.33355E+02	.13488E-08	-.13000E+01	.13693E+00	.14734E-09
261	.33355E+02	.25362E+00	-.12750E+01	.89920E-01	.17890E-01
262	.33355E+02	.49749E+00	-.12010E+01	.51906E-01	.21507E-01
263	.33355E+02	.72224E+00	-.10809E+01	.22193E-01	.14830E-01
264	.33355E+02	.91924E+00	-.91924E+00	.16726E-05	.14291E-05
265	.33355E+02	.10809E+01	-.72224E+00	-.14827E-01	-.22184E-01
266	.33355E+02	.12010E+01	-.49749E+00	-.21503E-01	-.51898E-01
267	.33355E+02	.12750E+01	-.25362E+00	-.17887E-01	-.89904E-01
268	.33355E+02	.13000E+01	.18450E-08	.19641E-09	-.13690E+00

Figure 16.- Concluded.

```

NASA/LANGLEY UPWT PROJ.1126,CONFIGURATION BIT4.
$INPUT
CRP=3.6,SWLEP=30.0,B2=2.34,SWLEV=30.0,CRPV=3.6,B2V=2.34,
NCW=3,MSWR=5,MSWL=5,MSWU=5,MSWD=5,NCRX=1,
ALFAC=14.216,PHI=45.0,FMACH=1.70,
RB=1.3,NADCR=16,NCWB=3,BIL=3.6,
XWLE=35.4,
XSTART=23.4,
SREF=5.30929,REFL=2.69,
NOLINP=1,NOUT=0,NDRAG=1,NBDYPR=1,NCPDUT=0,NVLIN=1,ITAIL=1,
JCPT=268,
VRTMAX=0.5,
XM=19.5,
NTDAT=1,NCWT=8,
SEND
      5      0      0
0.122      0.0      0.0      0.0      0.0      0.0      0.0      0.0      0.0      =0.141
0.122      0.0      0.0      0.0      0.0      0.0      0.0      0.0      0.0      =0.141
0.122      0.122      0.0      0.0      0.0      0.0      0.0      0.0      0.0      =0.141
0.122      0.122      0.0      0.0      0.0      0.0      0.0      0.0      0.0      =0.141
0.122      0.122      0.0      0.0      0.0      0.0      0.0      0.0      =0.141
0.122      0.0      0.0      0.0      0.0      0.0      0.0      0.0      =0.141
0.122      0.0      0.0      0.0      0.0      0.0      0.0      0.0      =0.141
$BODY
NXBODY=39,LNOSE=7.8,LBODY=39.0,BCODE=2,
SEND
      0      0      0      0
      0
ZZZZZZZZZZ

```

Figure 17.- Input for program DEMON2, first sample case, step 6.

NASA/ANGLEY (PMT PROJ. 112A) CONFIGURATION BITS,
INPUT

CRP = .36E+01,
S-LEP = .5E+02,
S+TEP = 0.0,
NCW = 3,
MSWQ = 5,
MSWL = 5,
ALFAC = .14216E+02,
PMI = .45E+02,
H2 = .234E+01,
FMACH = .17E+01,
LVSWP = 0,
FAC = .95E+00,
NFUNPR = 0,
TOLFAC = .1E+01,
MSWU = 5,
MSWD = 5,
S+LEV = .5E+02,
S-TEV = 0.0,
CRPV = .36E+01,
H2V = .234E+01,
NCRX = 1,
RH = .13E+01,
RA = .13E+01,
FRATIO = .1E+01,
MHDCR = 16,
DFIR = 0.0,
DELL = 0.0,
DELU = 0.0,
DELD = 0.0,

SREF = .530929E+01,
REFL = .269E+01,
PHIDIN = 0.0,
THETIT = 0.0,
KALE = .354E+02,
NOLINP = 1,
NOUT = 0,
NPR = 0,
NDRAG = 1,
NVRTX = 0,
NPRESS = 0,
VRTMAX = .5E+00,
NCWB = 3,
NAGAIN = 0,
HIL = .36E+01,
ITAIL = 1,
NVRTPL = 0,
MHQYPR = 1,
NTPR = 0,
VTDAT = 1,
NCWT = 8,
NCPDIT = 0,
NVLIN = 1,
XSTART = .234E+02,
JCPT = 268,
FKLE = .5E+00,
FKSE = .5E+00,
XM = .195E+02,
ZM = 0.0,
SEND

551

Figure 18.- Output of program DEMON2, first sample case, step 6.

WING GEOMETRY

TIP CHORD = 7.24900
 ROOT CHORD = 3.60000
 WING SEMISPAN = 2.34000
 LEADING EDGE SWEEP = 30.00000 DEGREES
 TRAILING EDGE SWEEP = 0.00000 DEGREES

FLOW CONDITIONS

MACH = 1.70000 ALPHAC = 14.21600 PWT = 85.00000 ALFA = 10.00010 BETA = 10.00010

CRCT = 3.60000
 CRPTV = 3.60000

WING THICKNESS INPUT DATA

SPANWISE LOCATIONS OF PANEL SIDE EDGES AND SWEEP ANGLES
 OF WING SECTION TO THE LEFT

I	SPANWISE LOCATION FEET	LE SWEEP DEGREES	TE SWEEP DEGREES
---	------------------------------	---------------------	---------------------

RIGHT WING SURFACE

1	1.30000	0.00000	0.00000
2	1.76400	30.00000	0.00000
3	2.23400	30.00000	0.00000
4	2.70400	30.00000	0.00000
5	3.17200	30.00000	0.00000
6	3.64000	30.00000	0.00000

40 THICKNESS PANELS ARE TO BE LAYED OUT
 5 CHORDWISE ROWS WITH 8 IN EACH ROW

UPPER WING SURFACE

1	1.30000	0.00000	0.00000
2	1.76400	30.00000	0.00000
3	2.23400	30.00000	0.00000
4	2.70400	30.00000	0.00000
5	3.17200	30.00000	0.00000
6	3.64000	30.00000	0.00000

40 THICKNESS PANELS ARE TO BE LAYED OUT
 5 CHORDWISE ROWS WITH 8 IN EACH ROW

INPUT VALUES OF THE LOCAL SURFACE SLOPE OF THE THICKNESS DISTRIBUTION, FOR EACH CHORDWISE ROW THE FIRST VALUE IS FOR THE PANEL NEAREST THE LEADING EDGE

RIGHT WING SURFACE

ROW	SLOPES							
1	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
2	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
3	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
4	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
5	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100

UPPER WING SURFACE

ROW	SLOPES							
1	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
2	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
3	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
4	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100
5	.12200	.12200	0.00000	0.00000	0.00000	0.00000	0.00000	-.14100

SHDDY

MXBODY = 39.

LXNSE = .78E+01

LXDDY = .39E+02.

RCODE = 2.

SEAD

PHYSICAL DIMENSIONS OF BODY AND LINE SINGULARITY STRENGTHS REPRESENTING THE BODY AT MACH= 1.7000

ALFAC= 14.2160

K	DRDY	TX	Y(I)	TC(I)
1	0.0000	.58610E-13	.10092	.39463E-01
2	1.0263	.57781	-.40121E-01	-.10956E-01
3	2.0526	1.2234	-.25012E-01	-.62846E-02
4	3.0789	1.9150	-.25274E-01	-.81381E-02
5	4.1053	2.7106	-.18881E-01	-.74517E-02
6	5.1316	3.5485	-.15477E-01	-.75496E-02
7	6.1579	4.4479	-.11952E-01	-.73645E-02
8	7.1842	5.4078	-.84169E-02	-.70718E-02
9	8.2105	6.4233	.31078E-01	-.28112E-02
10	9.2368	7.4496	.35294E-02	.47754E-02
11	10.2632	8.4760	.34046E-02	.19940E-02
12	11.2895	9.5023	.14132E-02	.36673E-02
13	12.3158	10.5287	.93969E-03	.24432E-02
14	13.3421	11.5550	.55066E-03	.17866E-02
15	14.3684	12.5814	.36257E-03	.10708E-02
16	15.3947	13.6077	.23850E-03	.56355E-03
17	16.4210	14.6341	.16227E-03	.22480E-03
18	17.4474	15.6604	.11249E-03	.33410E-04

Figure 18.- Continued.

10	18.4737	1.3000	0.	36.888	.74559E-04	-.67235E-04
20	19.5000	1.3000	0.	17.713	.57218E-04	-.10824E-03
21	20.5265	1.3000	0.	18.739	.41794E-04	-.10993E-03
22	21.5528	1.3000	0.	19.765	.30461E-04	-.94708E-04
23	22.5789	1.3000	0.	20.792	.23236E-04	-.75192E-04
24	23.6053	1.3000	0.	21.818	.17450E-04	-.54633E-04
25	24.6316	1.3000	0.	22.844	.13558E-04	-.37078E-04
26	25.6579	1.3000	0.	23.871	.10525E-04	-.25532E-04
27	26.6842	1.3000	0.	24.897	.82509E-05	-.13675E-04
28	27.7105	1.3000	0.	25.923	.65280E-05	-.74713E-05
29	28.7368	1.3000	0.	26.950	.52100E-05	-.35327E-05
30	29.7632	1.3000	0.	27.976	.41922E-05	-.13202E-05
31	30.7895	1.3000	0.	29.002	.33493E-05	-.22844E-06
32	31.8158	1.3000	0.	30.029	.27766E-05	.19378E-06
33	32.8421	1.3000	0.	31.055	.22835E-05	.26675E-06
34	33.8684	1.3000	0.	32.081	.18903E-05	.15784E-06
35	34.8947	1.3000	0.	33.108	.15745E-05	.11691E-07
36	35.9211	1.3000	0.	34.134	.13191E-05	-.12295E-06
37	36.9474	1.3000	0.	35.160	.11112E-05	-.22221E-06
38	37.9737	1.3000	0.	36.186	.94402E-06	-.28188E-06
39	39.0000	1.3000	0.	37.213	0.	0.

POINT COORDINATES AND PERTURBATION VELOCITIES CALCULATED BY PROGRAM VPATHE

IC	XCP	YCP	ZCP	VVEL(IC)	WVEL(IC)
1	36.63100	1.53100	0.00000	.22541E-01	-.74105E-01
2	37.78700	1.53100	0.00000	.19927E-01	-.67006E-01
3	38.94200	1.53100	0.00000	.17748E-01	-.61175E-01
4	39.81800	1.99870	0.00000	.41619E-01	-.45614E-01
5	37.88100	1.99870	0.00000	.37375E-01	-.42293E-01
6	38.94700	1.99870	0.00000	.34459E-01	-.39479E-01
7	37.00000	2.46640	0.00000	.44308E-01	-.26003E-01
8	37.97600	2.46640	0.00000	.40555E-01	-.25016E-01
9	38.95100	2.46640	0.00000	.37344E-01	-.24108E-01
10	37.18500	2.93400	0.00000	.40999E-01	-.13556E-01
11	38.07000	2.93400	0.00000	.38258E-01	-.13699E-01
12	38.95600	2.93400	0.00000	.35851E-01	-.13763E-01
13	37.36900	3.40160	0.00000	.36017E-01	-.60080E-02
14	38.14500	3.40160	0.00000	.34184E-01	-.65582E-02
15	38.96000	3.40160	0.00000	.32528E-01	-.70081E-02
16	36.63100	-1.53100	0.00000	.25922E-01	-.24335E+00
17	37.78700	-1.53100	0.00000	.24109E-01	-.25303E+00
18	38.94700	-1.53100	0.00000	.19507E-01	-.25401E+00
19	36.81800	-1.99870	0.00000	.51219E-01	-.17161E+00
20	37.88100	-1.99870	0.00000	.53088E-01	-.18545E+00
21	38.94700	-1.99870	0.00000	.48996E-01	-.19858E+00
22	37.00000	-2.46640	0.00000	.59433E-01	-.91572E-01
23	37.97600	-2.46640	0.00000	.74149E-01	-.10355E+00
24	38.95100	-2.46640	0.00000	.84330E-01	-.12168E+00
25	37.18500	-2.93400	0.00000	.56495E-01	-.21821E-01
26	38.07000	-2.93400	0.00000	.75918E-01	-.23056E-01
27	38.95600	-2.93400	0.00000	.98548E-01	-.29258E-01
28	37.36900	-3.40160	0.00000	.43943E-01	.14325E-01
29	38.14500	-3.40160	0.00000	.57886E-01	.19927E-01
30	38.96000	-3.40160	0.00000	.74961E-01	.25394E-01
31	36.63100	.00000	1.53100	.24338E+00	-.25911E-01
32	37.78700	.00000	1.53100	.25305E+00	-.24092E-01

Figure 18.- Continued.

33	3A,94200	.00000	1,53100	.25802E+00	-.10486E-01
34	3A,81600	.00000	1,99870	.17145E+00	-.51210E-01
35	37,88100	.00000	1,99870	.18509E+00	-.53383E-01
36	3A,94700	.00000	1,99870	.19881E+00	-.48956E-01
37	37,00000	.00000	2,46640	.91618E-01	-.59462E-01
38	37,97800	.00000	2,46640	.10380E+00	-.74159E-01
39	3A,95100	.00000	2,46640	.12174E+00	-.84317E-01
40	37,14500	.00000	2,93400	.21847E-01	-.56537E-01
41	3A,07000	.00000	2,93400	.23094E-01	-.75960E-01
42	3A,95800	.00000	2,93400	.29311E-01	-.98810E-01
43	37,36900	.00000	3,40160	-.14321E-01	-.44031E-01
44	3A,16500	.00000	3,40160	-.19920E-01	-.57935E-01
45	3A,96000	.00000	3,40160	-.25384E-01	-.75025E-01
46	3A,63100	-.00000	-1,53100	.74107E-01	-.22546E-01
47	37,78700	-.00000	-1,53100	.67008E-01	-.19931E-01
48	3A,94200	-.00000	-1,53100	.61173E-01	-.17801E-01
49	3A,81600	-.00000	-1,99870	.45611E-01	-.41626E-01
50	37,88100	-.00000	-1,99870	.42284E-01	-.37381E-01
51	3A,94700	-.00000	-1,99870	.39475E-01	-.33864E-01
52	37,00000	-.00000	-2,46640	.25997E-01	-.44314E-01
53	37,97600	-.00000	-2,46640	.25009E-01	-.40561E-01
54	3A,95100	-.00000	-2,46640	.24101E-01	-.37368E-01
55	37,14500	-.00000	-2,93400	.13548E-01	-.41002E-01
56	3A,07000	-.00000	-2,93400	.13692E-01	-.38261E-01
57	3A,95600	-.00000	-2,93400	.13746E-01	-.35854E-01
58	37,36900	-.00000	-3,40160	.60006E-02	-.36018E-01
59	3A,16500	-.00000	-3,40160	.65510E-02	-.34185E-01
60	3A,96000	-.00000	-3,40160	.70012E-02	-.32529E-01
61	3A,54000	1,25050	.24874	.21274E-01	-.12874E+00
62	3A,54000	1,06010	.70836	.12787E+00	-.20246E+00
63	3A,54000	.70836	1,06010	.28783E+00	-.19570E+00
64	3A,54000	.24874	1,25050	.32388E+00	-.60836E-01
65	3A,54000	-.24874	1,25050	.24801E+00	.53504E-01
66	3A,54000	-.70836	1,06010	.91774E-01	.73741E-01
67	3A,54000	-1,06010	.70836	-.73710E-01	-.91728E-01
68	3A,54000	-1,25050	.24874	-.53496E-01	-.24796E+00
69	3A,54000	-1,25050	-.24874	.60831E-01	-.32364E+00
70	3A,54000	-1,06010	-.70836	.19573E+00	-.28788E+00
71	3A,54000	-.70836	-1,06010	.20250E+00	-.12770E+00
72	3A,54000	-.24874	-1,25050	.12875E+00	-.21275E-01
73	3A,54000	.24874	-1,25050	.61400E-01	.14866E-01
74	3A,54000	.70836	-1,06010	.14602E-01	.12062E-01
75	3A,54000	1,06010	-.70836	-.12066E-01	-.14607E-01
76	3A,54000	1,25050	-.24874	-.14866E-01	-.61401E-01
77	37,74000	1,25050	.24874	.19040E-01	-.11463E+00
78	37,74000	1,06010	.70836	.11255E+00	-.17854E+00
79	37,74000	.70836	1,06010	.26421E+00	-.18126E+00
80	37,74000	.24874	1,25050	.32649E+00	-.62557E-01
81	37,74000	-.24874	1,25050	.25853E+00	.55706E-01
82	37,74000	-.70836	1,06010	.95893E-01	.77032E-01
83	37,74000	-1,06010	.70836	-.78997E-01	-.95401E-01
84	37,74000	-1,25050	.24874	-.55899E-01	-.25849E+00
85	37,74000	-1,25050	-.24874	.62555E-01	-.32650E+00
86	37,74000	-1,06010	-.70836	.18130E+00	-.26427E+00
87	37,74000	-.70836	-1,06010	.17862E+00	-.11257E+00
88	37,74000	-.24874	-1,25050	.11484E+00	-.19041E-01
89	37,74000	.24874	-1,25050	.55514E-01	.13401E-01
90	37,74000	.70836	-1,06010	.13307E-01	.10984E-01

Figure 18.- Continued.

91	37,74000	1,06010	-.70836	-.10001E+01	-.13314E+01
92	37,74000	1,25050	-.24874	-.13401E+01	-.55518E+01
93	38,94000	1,25050	.24874	.17227E+01	-.10318E+00
94	38,94000	1,06010	.70836	.99922E+01	-.15445E+00
95	38,94000	.70836	1,06010	.23901E+00	-.16495E+00
96	38,94000	.24874	1,25050	.31998E+00	-.42611E+01
97	38,94000	-.24874	1,25050	.26666E+00	.57132E+01
98	38,94000	-.70836	1,06010	.10028E+00	.80495E+01
99	38,94000	-1,06010	.70836	-.80495E+01	-.10022E+00
100	38,94000	-1,25050	.24874	-.57127E+01	-.26662E+00
101	38,94000	-1,25050	-.24874	.82613E+01	-.32000E+00
102	38,94000	-1,06010	-.70836	.16490E+00	-.23006E+00
103	38,94000	-.70836	-1,06010	.15804E+00	-.49937E+01
104	38,94000	-.24874	-1,25050	.10318E+00	-.17227E+01
105	38,94000	.24874	-1,25050	.50709E+01	.12211E+01
106	38,94000	.70836	-1,06010	.12245E+01	.10108E+01
107	38,94000	1,06010	-.70836	-.10113E+01	-.12252E+01
108	38,94000	1,25050	-.24874	-.12212E+01	-.50714E+01
109	25,14500	1,27500	.25362	.51894E+01	-.26088E+00
110	25,14500	1,20100	.49749	.98361E+01	-.23745E+00
111	25,14500	1,08090	.72224	.13105E+00	-.19612E+00
112	25,14500	.91924	.91924	.15447E+00	-.15447E+00
113	25,14500	.72224	1,08090	.17758E+00	-.11865E+00
114	25,14500	.49749	1,20100	.20820E+00	-.86245E+01
115	25,14500	.25362	1,27500	.25233E+00	-.50196E+01
116	25,14500	-.00000	1,30000	.11195E+00	.11188E+09
117	25,14500	-.25362	1,27500	.35000E+00	.72225E+01
118	25,14500	-.49749	1,20100	.32579E+00	.13447E+00
119	25,14500	-.72224	1,08090	.17191E+00	.11488E+00
120	25,14500	-.91924	.91924	.21280E+00	.19278E+04
121	25,14500	-1,08090	.72224	-.11485E+00	-.17187E+00
122	25,14500	-1,20100	.49749	-.13496E+00	-.12577E+00
123	25,14500	-1,27500	.25362	-.72228E+01	-.35000E+00
124	25,14500	-1,30000	-.00000	-.22377E+09	-.31196E+00
125	25,14500	-1,27500	-.25362	.50194E+01	-.25232E+00
126	25,14500	-1,20100	-.49749	.86241E+01	-.26819E+00
127	25,14500	-1,08090	-.72224	.11865E+00	-.17757E+00
128	25,14500	-.91924	-.91924	.15445E+00	-.15445E+00
129	25,14500	-.72224	-1,08090	.19610E+00	-.13103E+00
130	25,14500	-.49749	-1,20100	.23743E+00	-.98352E+01
131	25,14500	-.25362	-1,27500	.26088E+00	-.51893E+01
132	25,14500	.00000	-1,30000	.24729E+00	.26808E+09
133	25,14500	.25362	-1,27500	.19580E+00	.38953E+01
134	25,14500	.49749	-1,20100	.12514E+00	.51932E+01
135	25,14500	.72224	-1,08090	.58213E+01	.37564E+01
136	25,14500	.91924	-.91924	.18554E+04	.17729E+04
137	25,14500	1,08090	-.72224	-.17535E+01	-.56170E+01
138	25,14500	1,20100	-.49749	-.51913E+01	-.12530E+00
139	25,14500	1,27500	-.25362	-.38940E+01	-.19576E+00
140	25,14500	1,30000	.00000	.35473E+09	-.24726E+00
141	27,19700	1,27500	.25362	.57843E+01	-.29040E+00
142	27,19700	1,20100	.49749	.11538E+00	-.27853E+00
143	27,19700	1,08090	.72224	.15419E+00	-.23075E+00
144	27,19700	.91924	.91924	.17505E+00	-.17505E+00
145	27,19700	.72224	1,08090	.18940E+00	-.12885E+00
146	27,19700	.49749	1,20100	.20942E+00	-.86749E+01
147	27,19700	.25362	1,27500	.24021E+00	-.47784E+01
148	27,19700	-.00000	1,30000	.28172E+00	.10104E+09

Figure 18.- Continued.

149	27,19700	-.25362	1,27500	.31290F+00	.62238E-01
150	27,19700	-.49749	1,20100	.27791E+00	.11515E+00
151	27,19700	-.72224	1,08090	.15109F+00	.10096E+00
152	27,19700	-.91924	.91924	.15788F+00	.13993E+00
153	27,19700	-1,08090	.72224	-.10095F+00	-.15106E+00
154	27,19700	-1,20100	.49749	-.11512F+00	-.27791E+00
155	27,19700	-1,27500	.25362	-.62237E-01	-.31290E+00
156	27,19700	-1,30000	-.00000	.20208E+09	-.28172E+00
157	27,19700	-1,27500	-.25362	.47781F+01	-.24019E+00
158	27,19700	-1,20100	-.49749	.86740E+01	-.20940E+00
159	27,19700	-1,08090	-.72224	.12683E+00	-.18982E+00
160	27,19700	-.91924	-.91924	.17503E+00	-.17503E+00
161	27,19700	-.72224	-1,08090	.23072F+00	-.15416E+00
162	27,19700	-.49749	-1,20100	.27852F+00	-.11537E+00
163	27,19700	-.25362	-1,27500	.29022F+00	-.57847E-01
164	27,19700	.00000	-1,30000	.25024E+00	.27356E+09
165	27,19700	.25362	-1,27500	.18610F+00	.37032E-01
166	27,19700	.49749	-1,20100	.11272F+00	.46701F-01
167	27,19700	.72224	-1,08090	.49035F-01	.32767E-01
168	27,19700	.91924	-.91924	.16023E-04	.15883E-04
169	27,19700	1,08090	-.72224	-.32741E-01	-.48996E-01
170	27,19700	1,20100	-.49749	-.46681F-01	-.11267E+00
171	27,19700	1,27500	-.25362	-.37021E-01	-.18608E+00
172	27,19700	1,30000	.00000	.36447E-09	-.25419E+00
173	29,25000	-1,27500	.25362	.57819E-01	-.29069E+00
174	29,25000	-1,20100	.49749	.12823E+00	-.30958E+00
175	29,25000	-1,08090	.72224	.18283E+00	-.27333E+00
176	29,25000	-.91924	.91924	.20783E+00	-.20783E+00
177	29,25000	.72224	1,08090	.21895E+00	-.18362E+00
178	29,25000	.49749	1,20100	.22124E+00	-.91664E-01
179	29,25000	.25362	1,27500	.23612E+00	-.48969E-01
180	29,25000	.00000	1,30000	.25921E+00	.92466E-10
181	29,25000	-.25362	1,27500	.27333E+00	.54364E-01
182	29,25000	-.49749	1,20100	.23805E+00	.98819E-01
183	29,25000	-.72224	1,08090	.13121E+00	.87680E-01
184	29,25000	-.91924	.91924	.12532E-04	.10972E-04
185	29,25000	-1,08090	.72224	.87844E-01	-.13119E+00
186	29,25000	-1,20100	.49749	.95611E-01	-.23808E+00
187	29,25000	-1,27500	.25362	.54388E-01	-.27431E+00
188	29,25000	-1,30000	-.00000	.18502E-09	-.25919E+00
189	29,25000	-1,27500	-.25362	.48983E-01	-.23809E+00
190	29,25000	-1,20100	-.49749	.91688E-01	-.22125E+00
191	29,25000	-1,08090	-.72224	.10480E+00	-.21491E+00
192	29,25000	-.91924	-.91924	.20759E+00	-.20759E+00
193	29,25000	-.72224	-1,08090	.27331E+00	-.18262E+00
194	29,25000	-.49749	-1,20100	.30980E+00	-.12824E+00
195	29,25000	-.25362	-1,27500	.29075E+00	-.57831E-01
196	29,25000	.00000	-1,30000	.22939E+00	.24683F+09
197	29,25000	.25362	-1,27500	.15853E+00	.31141E-01
198	29,25000	.49749	-1,20100	.91104E-01	.37785E-01
199	29,25000	.72224	-1,08090	.38978E-11	.28007E-01
200	29,25000	.91924	-.91924	.11744E-04	.11317E-04
201	29,25000	1,08090	-.72224	-.26027E-01	-.38949E-01
202	29,25000	1,20100	-.49749	-.37188F-01	-.91154E-01
203	29,25000	1,27500	-.25362	-.31110F-01	-.15847E+00
204	29,25000	1,30000	.00000	.32900E-09	-.22933E+00
205	31,30300	-1,27500	.25362	.49544E-01	-.24911E+00
206	31,30300	-1,20100	.49749	.12370E+00	-.29865E+00
207	31,30300	-1,08090	.72224	.20006E+00	-.29940E+00

Figure 18.- Continued.

208	31,30300	.91924	.41924	.20541E+00	-.20541E+00
209	31,30300	.72224	1.08090	.25075E+00	-.17021E+00
210	31,30300	.49749	1.20100	.24885E+00	-.10308E+00
211	31,30300	.25362	1.27500	.24583E+00	-.08900E+01
212	31,30300	.00000	1.30000	.24957E+00	.80410E-10
213	31,30300	-.25362	1.27500	.24707E+00	.44147E-01
214	31,30300	-.49749	1.20100	.20811E+00	.88214E-01
215	31,30300	-.72224	1.08090	.11400E+00	.76400E-01
216	31,30300	-.91924	.91924	.17027E-04	.10661E-04
217	31,30300	-1.08090	.72224	-.76431E-01	-.11438E+00
218	31,30300	-1.20100	.49749	-.66203E-01	-.20808E+00
219	31,30300	-1.27500	.25362	-.49141E-01	-.24704E+00
220	31,30300	-1.30000	.00000	.17809E-09	-.24954E+00
221	31,30300	-1.27500	-.25362	.48891E-01	-.24579E+00
222	31,30300	-1.20100	-.49749	.10308E+00	-.24880E+00
223	31,30300	-1.08090	-.72224	.17019E+00	-.25470E+00
224	31,30300	-.91924	-.91924	.24549E+00	-.24549E+00
225	31,30300	-.72224	-1.08090	.29903E+00	-.20007E+00
226	31,30300	-.49749	-1.20100	.29977E+00	-.12373E+00
227	31,30300	-.25362	-1.27500	.24918E+00	-.49560E-01
228	31,30300	.00000	-1.30000	.18240E+00	.19837E-09
229	31,30300	.25362	-1.27500	.12022E+00	.23914E-01
230	31,30300	.49749	-1.20100	.69174E-01	.28640E-01
231	31,30300	.72224	-1.08090	.29432E-01	.19868E-01
232	31,30300	.91924	-.91924	.62402E-05	.59178E-05
233	31,30300	1.08090	-.72224	-.19657E-01	-.29416E-01
234	31,30300	1.20100	-.49749	-.28631E-01	-.69101E-01
235	31,30300	1.27500	-.25362	-.23911E-01	-.12018E+00
236	31,30300	1.30000	.00000	.26173E-09	-.18244E+00
237	33,35500	1.27500	.25362	.38101E-01	-.19157E+00
238	33,35500	1.20100	.49749	.10173E+00	-.24562E+00
239	33,35500	1.08090	.72224	.18542E+00	-.27750E+00
240	33,35500	.91924	.41924	.26061E+00	-.26061E+00
241	33,35500	.72224	1.08090	.29458E+00	-.19683E+00
242	33,35500	.49749	1.20100	.28977E+00	-.12003E+00
243	33,35500	.25362	1.27500	.27176E+00	-.54059E-01
244	33,35500	.00000	1.30000	.25552E+00	.91845E-10
245	33,35500	-.25362	1.27500	.23542E+00	.46831E-01
246	33,35500	-.49749	1.20100	.18926E+00	.78408E-01
247	33,35500	-.72224	1.08090	.10231E+00	.68364E-01
248	33,35500	-.91924	.91924	.14117E-04	.12844E-04
249	33,35500	-1.08090	.72224	-.68443E-01	-.10227E+00
250	33,35500	-1.20100	.49749	-.78343E-01	-.18923E+00
251	33,35500	-1.27500	.25362	-.46422E-01	-.23538E+00
252	33,35500	-1.30000	.00000	.18325E-09	-.25548E+00
253	33,35500	-1.27500	-.25362	.54046E-01	-.27171E+00
254	33,35500	-1.20100	-.49749	.12001E+00	-.28973E+00
255	33,35500	-1.08090	-.72224	.19642E+00	-.29457E+00
256	33,35500	-.91924	-.91924	.26060E+00	-.26064E+00
257	33,35500	-.72224	-1.08090	.27756E+00	-.18546E+00
258	33,35500	-.49749	-1.20100	.24548E+00	-.10176E+00
259	33,35500	-.25362	-1.27500	.19162E+00	-.38111E-01
260	33,35500	.00000	-1.30000	.13894E+00	.14734E-09
261	33,35500	.25362	-1.27500	.89920E-01	.17890E-01
262	33,35500	.49749	-1.20100	.51906E-01	.21507E-01
263	33,35500	.72224	-1.08090	.22193E-01	.14830E-01
264	33,35500	.91924	-.91924	.16726E-05	.14291E-05
265	33,35500	1.08090	-.72224	-.14827E-01	-.22188E-01

Figure 18.- Continued.

26A	33,35500	1,20100	-.49749	-.21503E-01	-.51898E-01
267	33,35500	1,27500	-.25362	-.17887E-01	-.89904E-01
26A	33,35500	1,40000	.00000	.19641E-09	-.13690E+00

PRESSURE COEFFICIENTS AT POINTS ON BODY MERIDIANS

J	THETA, DEG.	XR	YR	ZR	UTOT	VTOT	WTOT	CP,LIN.	CP,HEMN.	DR/DX	P/DINF, HEMN.	P/DINF, LIN.
TOTAL NUMBER OF PRESSURE POINTS,JCPT= 26A												
BODY RING= 13												
1	11,25000	25,14474	1,27502	.25362	.00178	.14660	-.03041	-.00356	.03653	0,00000	1,07390	.99279
2	22,50000	25,14474	1,20104	.49749	.00176	.09743	.01196	-.00352	.01690	0,00000	1,03419	.99289
3	33,75000	25,14474	1,08091	.72224	.00173	.03527	.03435	-.00347	-.00544	0,00000	.98899	.99299
4	45,00000	25,14474	.91924	.91924	.00171	-.02205	.02205	-.00342	-.01932	0,00000	.94091	.99309
5	56,25000	25,14474	.72224	1,08091	.00168	-.05289	-.00337	-.01680	-.02288	0,00000	.94091	.99319
6	67,50000	25,14474	.49749	1,20104	.00166	-.04121	-.08571	-.00332	.00320	0,00000	1,00647	.99329
7	78,75000	25,14474	.25362	1,27502	.00164	.02186	-.14490	-.00327	.03408	0,00000	1,06494	.99338
8	90,00000	25,14474	-.00000	1,30000	.00162	.13543	-.17544	-.00323	.05799	0,00000	1,11731	.99346
9	101,25000	25,14474	-.25362	1,27502	.00160	.25422	-.15717	-.00320	.05231	0,00000	1,16582	.99353
10	112,50000	25,14474	-.49749	1,20104	.00159	.32525	-.11337	-.00317	.03129	0,00000	1,06331	.99358
11	123,75000	25,14474	-.72224	1,08091	.00158	.26661	-.11451	-.00316	.04659	0,00000	1,09426	.99361
12	135,00000	25,14474	-.91924	.91924	.00158	.17547	-.17543	-.00315	.05465	0,00000	1,12047	.99362
13	146,25000	25,14474	-1,08091	.72224	.00158	.11454	-.26657	-.00316	.04660	0,00000	1,09428	.99361
14	157,50000	25,14474	-1,20104	.49749	.00159	.11335	-.32523	-.00317	.03130	0,00000	1,06332	.99358
15	168,75000	25,14474	-1,27502	.25362	.00160	.15717	-.25422	-.00320	.05231	0,00000	1,10582	.99353
16	180,00000	25,14474	-1,30000	-.00000	.00162	.17544	-.13544	-.00323	.05799	0,00000	1,11731	.99346
17	191,25000	25,14474	-1,27502	-.25362	.00164	.14490	-.02185	-.00327	.03407	0,00000	1,06495	.99338
18	202,50000	25,14474	-1,20104	-.49749	.00166	.08571	.04122	-.00332	.00320	0,00000	1,00646	.99329
19	213,75000	25,14474	-1,08091	-.72224	.00168	.02287	.05290	-.00337	-.01680	0,00000	.94090	.99319
20	225,00000	25,14474	-.91924	-.91924	.00171	-.02207	.02207	-.00342	-.01934	0,00000	.94091	.99309
21	236,25000	25,14474	-.72224	-1,08091	.00173	-.03437	-.03525	-.00347	-.00544	0,00000	.98896	.99299
22	247,50000	25,14474	-.49749	-1,20104	.00176	-.03198	-.09782	-.00352	.01680	0,00000	1,03417	.99289
23	258,75000	25,14474	-.25362	-1,27502	.00178	.03041	-.14660	-.00356	.03653	0,00000	1,07390	.99279
24	270,00000	25,14474	-.00000	-1,30000	.00180	.07077	-.17544	-.00360	.04779	0,00000	1,09668	.99271
25	281,25000	25,14474	.25362	-1,27502	.00182	.10002	-.19044	-.00363	.05299	0,00000	1,10720	.99265
26	292,50000	25,14474	.49749	-1,20104	.00183	.12480	-.19641	-.00366	.05819	0,00000	1,11374	.99260
27	303,75000	25,14474	.72224	-1,08091	.00184	.15092	-.19183	-.00367	.05819	0,00000	1,11772	.99257
28	315,00000	25,14474	.91924	-.91924	.00184	.17546	-.17543	-.00368	.05910	0,00000	1,11955	.99256
29	326,25000	25,14474	1,08091	-.72224	.00184	.19186	-.15087	-.00367	.05819	0,00000	1,11771	.99257
30	337,50000	25,14474	1,20104	-.49749	.00183	.19643	-.12476	-.00366	.05819	0,00000	1,11324	.99260
31	348,75000	25,14474	1,27502	-.25362	.00182	.19045	-.09998	-.00363	.05299	0,00000	1,10719	.99265
32	360,00000	25,14474	1,30000	.00000	.00180	.17544	-.07074	-.00360	.04779	0,00000	1,09667	.99271

BODY RING= 14

1	11,25000	27,19737	1,27502	.25362	.00147	.15258	-.06048	-.00293	.04584	0,00000	1,09233	.99406
2	22,50000	27,19737	1,20104	.49749	.00145	.11491	-.02928	-.00290	.03401	0,00000	1,06880	.99414
3	33,75000	27,19737	1,08091	.72224	.00143	.05851	-.00043	-.00286	.01443	0,00000	1,02910	.99422
4	45,00000	27,19737	.91924	.91924	.00141	-.00134	.00134	-.00281	-.00365	0,00000	.99261	.99431

Figure 18.- Continued.

5	56,25000	27,19737	.72224	1,08091	.0013A	-.0400H	-.03117	-.00277	-.00884A	0,00000	.9A285	.99040
6	67,50000	27,19737	.49749	1,20104	.0013A	-.03943	-.08628	-.00273	-.00447	0,00000	1,00940	.99048
7	78,75000	27,19737	.25362	1,27502	.00135	-.06989	-.14252	-.00269	-.03057	0,00000	1,00183	.99046
8	90,00000	27,19737	-.00000	1,30000	.00133	-.10533	-.17544	-.00266	-.05513	0,00000	1,11152	.99062
9	101,25000	27,19737	-.25362	1,27502	.00132	-.21721	-.16714	-.00263	-.05810	0,00000	1,11755	.99068
10	112,50000	27,19737	-.49749	1,20104	.00130	-.27744	-.13318	-.00261	-.04687	0,00000	1,09043	.99072
11	123,75000	27,19737	-.72224	1,08091	.00130	-.24582	-.12801	-.00260	-.05241	0,00000	1,10602	.99075
12	135,00000	27,19737	-.91924	.91924	.00130	-.17546	-.17543	-.00259	-.06024	0,00000	1,12186	.99075
13	146,25000	27,19737	-1,08091	.72224	.00130	-.12802	-.24579	-.00260	-.05241	0,00000	1,10603	.99075
14	157,50000	27,19737	-1,20104	.49749	.00130	-.13319	-.27742	-.00261	-.04688	0,00000	1,09044	.99072
15	168,75000	27,19737	-1,27502	.25362	.00132	-.16714	-.21721	-.00263	-.05810	0,00000	1,11755	.99068
16	180,00000	27,19737	-1,30000	-.00000	.00133	-.17544	-.17543	-.00266	-.05513	0,00000	1,11152	.99062
17	191,25000	27,19737	-1,27502	-.25362	.00135	-.14251	-.06987	-.00269	-.03056	0,00000	1,00182	.99046
18	202,50000	27,19737	-1,20104	-.49749	.0013A	-.08627	-.03985	-.00273	-.00446	0,00000	1,00942	.99048
19	213,75000	27,19737	-1,08091	-.72224	.0013A	-.03115	-.04050	-.00277	-.008849	0,00000	.9A283	.99040
20	225,00000	27,19737	-.91924	.91924	.00141	-.00136	-.00136	-.00281	-.00367	0,00000	.99259	.99031
21	236,25000	27,19737	-.72224	-1,08091	.00143	-.00000	-.05804	-.00286	-.01441	0,00000	1,02911	.99022
22	247,50000	27,19737	-.49749	-1,20104	.00145	-.02927	-.11490	-.00290	-.03400	0,00000	1,00879	.99014
23	258,75000	27,19737	-.25362	-1,27502	.00147	-.06050	-.15258	-.00293	-.04565	0,00000	1,09234	.99006
24	270,00000	27,19737	-.00000	-1,30000	.00148	-.07785	-.17544	-.00297	-.04995	0,00000	1,10106	.99000
25	281,25000	27,19737	.25362	-1,27502	.00150	-.09046	-.19234	-.00300	-.05198	0,00000	1,10515	.99394
26	292,50000	27,19737	.49749	-1,20104	.00151	-.11225	-.20161	-.00302	-.05488	0,00000	1,11142	.99390
27	303,75000	27,19737	.72224	-1,08091	.00151	-.14377	-.19661	-.00303	-.05825	0,00000	1,11784	.99387
28	315,00000	27,19737	.91924	-.91924	.00152	-.17546	-.17543	-.00303	-.05978	0,00000	1,12093	.99387
29	326,25000	27,19737	1,08091	-.72224	.00151	-.19663	-.14373	-.00303	-.05825	0,00000	1,11783	.99387
30	337,50000	27,19737	1,20104	-.49749	.00151	-.20163	-.11220	-.00302	-.05487	0,00000	1,11100	.99390
31	348,75000	27,19737	1,27502	-.25362	.00150	-.19235	-.09040	-.00300	-.05196	0,00000	1,10512	.99394
32	360,00000	27,19737	1,30000	-.00000	.00148	-.17544	-.07780	-.00297	-.04994	0,00000	1,10104	.99400

BODY PING 15

1	11,25000	29,25000	1,27502	.25362	.00123	-.15258	-.06051	-.00247	-.04613	0,00000	1,09332	.99501
2	22,50000	29,25000	1,20104	.49749	.00122	-.12782	-.06047	-.00243	-.04439	0,00000	1,08941	.99504
3	33,75000	29,25000	1,08091	.72224	.00120	-.08704	-.04315	-.00239	-.03427	0,00000	1,06933	.99516
4	45,00000	29,25000	.91924	.91924	.00118	-.03136	-.03136	-.00235	-.01775	0,00000	1,03542	.99524
5	56,25000	29,25000	.72224	1,08091	.00116	-.01523	-.04803	-.00232	-.00664	0,00000	1,01343	.99532
6	67,50000	29,25000	.49749	1,20104	.00114	-.02782	-.09125	-.00228	-.01040	0,00000	1,07145	.99539
7	78,75000	29,25000	.25362	1,27502	.00112	-.00594	-.14173	-.00224	-.02960	0,00000	1,05988	.99546
8	90,00000	29,25000	-.00000	1,30000	.00111	-.08294	-.17544	-.00221	-.05176	0,00000	1,16471	.99552
9	101,25000	29,25000	-.25362	1,27502	.00109	-.17774	-.17499	-.00219	-.06045	0,00000	1,12270	.99557
10	112,50000	29,25000	-.49749	1,20104	.00108	-.23764	-.14967	-.00217	-.05564	0,00000	1,11256	.99561
11	123,75000	29,25000	-.72224	1,08091	.00108	-.22597	-.14168	-.00216	-.05663	0,00000	1,11457	.99563
12	135,00000	29,25000	-.91924	.91924	.00108	-.17546	-.17543	-.00215	-.06070	0,00000	1,12240	.99564
13	146,25000	29,25000	-1,08091	.72224	.00108	-.14169	-.22595	-.00216	-.05664	0,00000	1,11457	.99563
14	157,50000	29,25000	-1,20104	.49749	.00108	-.14968	-.23763	-.00217	-.05564	0,00000	1,11256	.99561
15	168,75000	29,25000	-1,27502	.25362	.00109	-.17499	-.17772	-.00219	-.06045	0,00000	1,12270	.99557
16	180,00000	29,25000	-1,30000	-.00000	.00111	-.17544	-.08292	-.00221	-.05175	0,00000	1,10470	.99552
17	191,25000	29,25000	-1,27502	-.25362	.00112	-.14172	-.00591	-.00224	-.02959	0,00000	1,05946	.99546
18	202,50000	29,25000	-1,20104	-.49749	.00114	-.09123	-.02786	-.00228	-.01078	0,00000	1,02181	.99540
19	213,75000	29,25000	-1,08091	-.72224	.0011A	-.04801	-.01527	-.00232	-.00662	0,00000	1,01339	.99532
20	225,00000	29,25000	-.91924	.91924	.0011A	-.03132	-.03132	-.00235	-.01773	0,00000	1,03547	.99524
21	236,25000	29,25000	-.72224	-1,08091	.00120	-.04313	-.08703	-.00239	-.03426	0,00000	1,06932	.99516
22	247,50000	29,25000	-.49749	-1,20104	.00122	-.06049	-.12783	-.00243	-.04400	0,00000	1,08932	.99504
23	258,75000	29,25000	-.25362	-1,27502	.00123	-.06057	-.15259	-.00247	-.04615	0,00000	1,09346	.99501
24	270,00000	29,25000	-.00000	-1,30000	.00125	-.05312	-.17544	-.00250	-.04473	0,00000	1,09049	.99495
25	281,25000	29,25000	.25362	-1,27502	.00126	-.06094	-.19821	-.00252	-.04601	0,00000	1,09338	.99490
26	292,50000	29,25000	.49749	-1,20104	.00127	-.09078	-.21050	-.00254	-.05142	0,00000	1,10403	.99486
27	303,75000	29,25000	.72224	-1,08091	.00128	-.13174	-.20331	-.00255	-.05761	0,00000	1,11655	.99480

Figure 18.- Continued.

28	315,00000	29,25000	.91924	-.91924	.00128	.17546	-.17543	-.00256	.06028	0,00000	1,12195	.99443
29	328,25000	29,25000	1,08091	-.72224	.00128	.20433	-.13371	-.00255	.05741	0,00000	1,11654	.99444
30	337,50000	29,25000	1,20104	-.49749	.00127	.21052	-.09074	-.00254	.05102	0,00000	1,11401	.99446
31	348,75000	29,25000	1,27502	-.25362	.00126	.19823	-.06088	-.00252	.04599	0,00000	1,09385	.99490
32	380,00000	29,25000	1,30000	.00000	.00125	.17544	-.05306	-.00250	.04472	0,00000	1,09066	.99495

BODY RING# 16

1	11,25000	31,30263	1,27502	.25362	.00104	.14433	-.01905	-.00210	.03433	0,00000	1,08995	.99573
2	22,50000	31,30263	1,20104	.49749	.00103	.12334	-.04966	-.00207	.04159	0,00000	1,08414	.99582
3	33,75000	31,30263	1,08091	.72224	.00102	.10456	-.08934	-.00203	.04401	0,00000	1,08094	.99588
4	45,00000	31,30263	.91924	.91924	.00100	.08935	-.08935	-.00200	.03759	0,00000	1,07604	.99596
5	56,25000	31,30263	.72224	1,08091	.00098	.07469	-.07471	-.00196	.02693	0,00000	1,05448	.99603
6	67,50000	31,30263	.49749	1,20104	.00097	.00014	-.10272	-.00193	.02360	0,00000	1,00773	.99609
7	78,75000	31,30263	.25362	1,27502	.00095	.01577	-.14368	-.00190	.03342	0,00000	1,00771	.99616
8	90,00000	31,30263	.00000	1,30000	.00094	.07341	-.17544	-.00187	.05016	0,00000	1,00107	.99621
9	101,25000	31,30263	-.25362	1,27502	.00093	.15157	-.18019	-.00185	.06045	0,00000	1,12230	.99626
10	112,50000	31,30263	-.49749	1,20104	.00092	.20775	-.16205	-.00183	.05964	0,00000	1,12065	.99629
11	123,75000	31,30263	-.72224	1,08091	.00091	.20918	-.15289	-.00182	.05922	0,00000	1,11980	.99631
12	135,00000	31,30263	-.91924	.91924	.00091	.17546	-.17543	-.00182	.06105	0,00000	1,12351	.99632
13	146,25000	31,30263	-1,08091	.72224	.00091	.15291	-.20916	-.00182	.05922	0,00000	1,11980	.99631
14	157,50000	31,30263	-1,20104	.49749	.00092	.16206	-.20772	-.00183	.05964	0,00000	1,12065	.99629
15	168,75000	31,30263	-1,27502	.25362	.00093	.18020	-.15154	-.00185	.06045	0,00000	1,12230	.99626
16	180,00000	31,30263	-1,30000	.00000	.00094	.17544	-.07338	-.00187	.05015	0,00000	1,10106	.99621
17	191,25000	31,30263	-1,27502	-.25362	.00095	.14368	-.01577	-.00190	.03341	0,00000	1,06758	.99616
18	202,50000	31,30263	-1,20104	.49749	.00097	.10270	.00019	-.00193	.02357	0,00000	1,04789	.99609
19	213,75000	31,30263	-1,08091	.72224	.00098	.07469	-.02464	-.00196	.02691	0,00000	1,05448	.99603
20	225,00000	31,30263	-.91924	.91924	.00100	.08933	-.08933	-.00200	.03758	0,00000	1,07604	.99596
21	236,25000	31,30263	-.72224	1,08091	.00102	.06937	-.10457	-.00203	.04401	0,00000	1,08094	.99588
22	247,50000	31,30263	-.49749	1,20104	.00103	.04966	-.12337	-.00207	.04161	0,00000	1,08414	.99582
23	258,75000	31,30263	-.25362	1,27502	.00105	.01912	-.14434	-.00210	.04433	0,00000	1,08995	.99573
24	270,00000	31,30263	.00000	1,30000	.00106	.00634	-.17544	-.00213	.03092	0,00000	1,08250	.99570
25	281,25000	31,30263	.25362	1,27502	.00107	.02472	-.20542	-.00215	.03591	0,00000	1,07249	.99566
26	292,50000	31,30263	.49749	1,20104	.00108	.06876	-.21963	-.00216	.04658	0,00000	1,09424	.99562
27	303,75000	31,30263	.72224	1,08091	.00109	.12422	-.20967	-.00217	.05663	0,00000	1,11457	.99560
28	315,00000	31,30263	.91924	.91924	.00109	.17545	-.17544	-.00218	.06088	0,00000	1,12235	.99559
29	326,25000	31,30263	1,08091	.72224	.00109	.20968	-.12420	-.00217	.05663	0,00000	1,11457	.99560
30	337,50000	31,30263	1,20104	.49749	.00108	.21963	-.06876	-.00216	.06658	0,00000	1,09424	.99562
31	348,75000	31,30263	1,27502	-.25362	.00107	.20543	-.02464	-.00215	.06592	0,00000	1,07249	.99566
32	380,00000	31,30263	1,30000	.00000	.00106	.17544	-.00628	-.00213	.03090	0,00000	1,08250	.99570

BODY RING# 17

1	11,25000	33,35526	1,27502	.25362	.00090	.13291	.03838	-.00180	.01205	0,00000	1,02437	.99635
2	22,50000	33,35526	1,20104	.49749	.00089	.10142	.00325	-.00178	.02243	0,00000	1,04537	.99641
3	33,75000	33,35526	1,08091	.72224	.00087	.08999	-.04755	-.00175	.03664	0,00000	1,07413	.99646
4	45,00000	33,35526	.91924	.91924	.00084	.08454	-.08454	-.00172	.04410	0,00000	1,09021	.99652
5	56,25000	33,35526	.72224	1,08091	.00084	.06463	-.10140	-.00169	.04283	0,00000	1,08664	.99658
6	67,50000	33,35526	.49749	1,20104	.00083	.04090	-.11972	-.00166	.03922	0,00000	1,07936	.99664
7	78,75000	33,35526	.25362	1,27502	.00082	.04181	-.14888	-.00163	.04194	0,00000	1,08484	.99670
8	90,00000	33,35526	.00000	1,30000	.00081	.07905	-.17544	-.00161	.05169	0,00000	1,10457	.99674
9	101,25000	33,35526	-.25362	1,27502	.00080	.13999	-.18249	-.00159	.05999	0,00000	1,12135	.99678
10	112,50000	33,35526	-.49749	1,20104	.00079	.18895	-.16984	-.00158	.06105	0,00000	1,12350	.99681
11	123,75000	33,35526	-.72224	1,08091	.00078	.19712	-.16096	-.00157	.06055	0,00000	1,12250	.99683
12	135,00000	33,35526	-.91924	.91924	.00078	.17546	-.17544	-.00157	.06132	0,00000	1,12406	.99685
13	146,25000	33,35526	-1,08091	.72224	.00078	.16098	-.19708	-.00157	.06056	0,00000	1,12251	.99683
14	157,50000	33,35526	-1,20104	.49749	.00079	.16985	-.18892	-.00158	.06105	0,00000	1,12350	.99681

Figure 18.- Continued.

15	164,75000	33,35526	-1,27562	.25362	.00000	.18250	-.13495	-.00159	.05998	.0,00000	1,12135	.99678
16	180,00000	33,35526	-1,30000	-.00000	.00001	.17544	-.07941	-.00161	.05168	.0,00000	1,10456	.99670
17	191,25000	33,35526	-1,27502	-.25362	.00002	.14885	-.04176	-.00163	.04193	.0,00000	1,08481	.99674
18	202,50000	33,35526	-1,20104	-.49749	.00003	.11970	-.00086	-.00166	.03922	.0,00000	1,07934	.99664
19	213,75000	33,35526	-1,08091	-.72224	.00004	.10139	-.06462	-.00169	.04282	.0,00000	1,08663	.99658
20	225,00000	33,35526	-.91924	-.91924	.00006	.08457	-.08457	-.00172	.04411	.0,00000	1,08923	.99652
21	236,25000	33,35526	-.72224	-1,08091	.00007	.06761	-.09003	-.00175	.03667	.0,00000	1,07417	.99646
22	247,50000	33,35526	-.49749	-1,20104	.00009	-.00319	-.10145	-.00178	.02245	.0,00000	1,06542	.99641
23	254,75000	33,35526	-.25362	-1,27502	.00009	-.03833	-.15292	-.00180	.01207	.0,00000	1,02441	.99635
24	270,00000	33,35526	.00000	-1,30000	.00001	-.04914	-.17544	-.00183	.01338	.0,00000	1,02707	.99631
25	281,25000	33,35526	.25362	-1,27502	.00002	-.00551	-.21144	-.00185	.02545	.0,00000	1,05148	.99627
26	292,50000	33,35526	.49749	-1,20104	.00003	.05159	-.22674	-.00186	.04200	.0,00000	1,08498	.99624
27	303,75000	33,35526	.72224	-1,08091	.00003	.11760	-.21450	-.00187	.05573	.0,00000	1,11274	.99622
28	315,00000	33,35526	.91924	-.91924	.00004	.17545	-.17544	-.00187	.06100	.0,00000	1,12340	.99621
29	326,25000	33,35526	1,08091	-.72224	.00003	.21450	-.11699	-.00187	.05573	.0,00000	1,11274	.99622
30	337,50000	33,35526	1,20104	-.49749	.00003	.22674	-.05158	-.00186	.04200	.0,00000	1,08497	.99624
31	348,75000	33,35526	1,27502	-.25362	.00002	.21144	.00553	-.00185	.02544	.0,00000	1,05146	.99627
32	360,00000	33,35526	1,30000	.00000	.00001	.17544	.03917	-.00183	.01337	.0,00000	1,02704	.99631

TOTAL NUMBER OF PRESSURE POINTS, JCPT= 268

CONTROL POINT COORDINATES FOR 5 CHORDWISE BY 5 SPANWISE PANELS ON WING 1 OR R, 5 SPANWISE ON WING 2 OR L AND 5 SPANWISE PANELS ON WING 3 OR U, 5 SPANWISE ON WING 4 OR D

J	X(J)	Y(J)	Z(J)	RU(J)	RV(J)	RW(J)	VVRTX	WVRTX
1	1,23112	1,53096	0,00000	.73009E-03	.12641E+00	.12640E+00	0.	0.
2	2,38667	1,53096	0,00000	.67838E-03	.12642E+00	.12691E+00	0.	0.
3	3,54222	1,53096	0,00000	.63160E-03	.12643E+00	.12689E+00	0.	0.
4	1,41565	1,99870	0,00000	.72683E-03	.74025E-01	.74581E-01	0.	0.
5	2,48119	1,99870	0,00000	.67887E-03	.74034E-01	.74559E-01	0.	0.
6	3,54672	1,99870	0,00000	.63539E-03	.74051E-01	.74538E-01	0.	0.
7	1,60017	2,46640	0,00000	.72543E-03	.48843E-01	.49061E-01	0.	0.
8	2,57570	2,46640	0,00000	.68143E-03	.48850E-01	.49043E-01	0.	0.
9	3,55122	2,46640	0,00000	.64127E-03	.48851E-01	.49027E-01	0.	0.
10	1,78466	2,93403	0,00000	.72621E-03	.34141E-01	.34740E-01	0.	0.
11	2,67019	2,93403	0,00000	.68808E-03	.34160E-01	.34725E-01	0.	0.
12	3,55572	2,93403	0,00000	.64988E-03	.34177E-01	.34711E-01	0.	0.
13	1,96912	3,40158	0,00000	.72815E-03	.25290E-01	.25908E-01	0.	0.
14	2,76467	3,40158	0,00000	.69144E-03	.25309E-01	.25895E-01	0.	0.
15	3,56022	3,40158	0,00000	.65783E-03	.25326E-01	.25883E-01	0.	0.
16	1,23112	-1,53096	0,00000	.68844E-03	.12645E+00	.12694E+00	0.	0.
17	2,38667	-1,53096	0,00000	.64085E-03	.12645E+00	.12691E+00	0.	0.
18	3,54222	-1,53096	0,00000	.59508E-03	.12645E+00	.12689E+00	0.	0.
19	1,41565	-1,99870	0,00000	.63974E-03	.74120E-01	.74581E-01	0.	0.
20	2,48119	-1,99870	0,00000	.59980E-03	.74125E-01	.74559E-01	0.	0.
21	3,54672	-1,99870	0,00000	.56302E-03	.74129E-01	.74538E-01	0.	0.
22	1,60017	-2,46640	0,00000	.63001E-03	.48827E-01	.49061E-01	0.	0.
23	2,57570	-2,46640	0,00000	.59399E-03	.48831E-01	.49043E-01	0.	0.
24	3,55122	-2,46640	0,00000	.56193E-03	.48836E-01	.49027E-01	0.	0.
25	1,78466	-2,93403	0,00000	.62103E-03	.34329E-01	.34740E-01	0.	0.
26	2,67019	-2,93403	0,00000	.58808E-03	.34333E-01	.34725E-01	0.	0.
27	3,55572	-2,93403	0,00000	.55908E-03	.34336E-01	.34711E-01	0.	0.
28	1,96912	-3,40158	0,00000	.61243E-03	.25519E-01	.25908E-01	0.	0.
29	2,76467	-3,40158	0,00000	.58375E-03	.25521E-01	.25895E-01	0.	0.
30	3,56022	-3,40158	0,00000	.55720E-03	.25523E-01	.25883E-01	0.	0.

Figure 18.- Continued.

31	1.25112	0.00000	1.55096	.60840E-03	-.12690E+00	-.12645E+00	0.	0.
32	2.14667	0.00000	1.53096	.60485E-03	-.12641E+00	-.12645E+00	0.	0.
33	3.54222	0.00000	1.53096	.58506E-03	-.12640E+00	-.12645E+00	0.	0.
34	1.41565	0.00000	1.49870	.53970E-03	-.74541E+01	-.74120E+01	0.	0.
35	2.41119	0.00000	1.49870	.59900E-03	-.74552E+01	-.74125E+01	0.	0.
36	3.54672	0.00000	1.49870	.56302E-03	-.74538E+01	-.74120E+01	0.	0.
37	1.66017	0.00000	2.46640	.63001E-03	-.49001E+01	-.48627E+01	0.	0.
38	2.57570	0.00000	2.46640	.59300E-03	-.49003E+01	-.48631E+01	0.	0.
39	3.55122	0.00000	2.46640	.61033E-03	-.49027E+01	-.48636E+01	0.	0.
40	1.78466	0.00000	2.93403	.62103E-03	-.34740E+01	-.34329E+01	0.	0.
41	2.67019	0.00000	2.93403	.58490E-03	-.34725E+01	-.34333E+01	0.	0.
42	3.55572	0.00000	2.93403	.55900E-03	-.34711E+01	-.34334E+01	0.	0.
43	1.98912	0.00000	3.40158	.61243E-03	-.25490E+01	-.25519E+01	0.	0.
44	2.78467	0.00000	3.40158	.58375E-03	-.25495E+01	-.25521E+01	0.	0.
45	3.56022	0.00000	3.40158	.55720E-03	-.25483E+01	-.25523E+01	0.	0.
46	1.23112	0.00000	-1.53096	.73009E-03	-.12649E+00	-.12641E+00	0.	0.
47	2.38667	0.00000	-1.53096	.67838E-03	-.12641E+00	-.12642E+00	0.	0.
48	3.54222	0.00000	-1.53096	.63100E-03	-.12640E+00	-.12643E+00	0.	0.
49	1.41565	0.00000	-1.49870	.72644E-03	-.74541E+01	-.74025E+01	0.	0.
50	2.41119	0.00000	-1.49870	.67847E-03	-.74549E+01	-.74039E+01	0.	0.
51	3.54672	0.00000	-1.49870	.63549E-03	-.74538E+01	-.74051E+01	0.	0.
52	1.66017	0.00000	-2.46640	.72545E-03	-.49001E+01	-.48643E+01	0.	0.
53	2.57570	0.00000	-2.46640	.68143E-03	-.49003E+01	-.48600E+01	0.	0.
54	3.55122	0.00000	-2.46640	.64127E-03	-.49027E+01	-.48616E+01	0.	0.
55	1.78466	0.00000	-2.93403	.72621E-03	-.34740E+01	-.34141E+01	0.	0.
56	2.67019	0.00000	-2.93403	.68400E-03	-.34725E+01	-.34160E+01	0.	0.
57	3.55572	0.00000	-2.93403	.64899E-03	-.34711E+01	-.34177E+01	0.	0.
58	1.98912	0.00000	-3.40158	.72115E-03	-.25490E+01	-.25290E+01	0.	0.
59	2.78467	0.00000	-3.40158	.67100E-03	-.25495E+01	-.25309E+01	0.	0.
60	3.56022	0.00000	-3.40158	.63783E-03	-.25483E+01	-.25326E+01	0.	0.

CONTROL POINT COORDINATES FOR HTP-9 (WING FRAME)

POINT	X(J)	Y(J)	Z(J)	THX(J)	THY(J)	THZ(J)
61	1.14000	1.25052	-.24874	-.13891E-02	-.14221E-01	-.34655E-02
62	1.14000	1.06014	-.70836	-.15717E-01	-.88792E-02	-.20553E-01
63	1.14000	.70836	1.06014	-.15717E-01	-.20553E-01	-.88792E-02
64	1.14000	-.24874	1.25052	-.13891E-02	-.34655E-02	-.14221E-01
65	1.14000	-.70836	1.06014	-.15717E-01	-.88792E-02	-.20553E-01
66	1.14000	-.24874	1.06014	-.15717E-01	-.88792E-02	-.20553E-01
67	1.14000	1.06014	-.70836	-.15717E-01	-.88792E-02	-.20553E-01
68	1.14000	1.25052	-.24874	-.13891E-02	-.14221E-01	-.34655E-02
69	1.14000	1.25052	-.24874	-.13891E-02	-.14221E-01	-.34655E-02
70	1.14000	1.06014	-.70836	-.15717E-01	-.88792E-02	-.20553E-01
71	1.14000	-.70836	1.06014	-.15717E-01	-.20553E-01	-.88792E-02
72	1.14000	-.24874	1.25052	-.13891E-02	-.34655E-02	-.14221E-01
73	1.14000	-.70836	1.06014	-.15717E-01	-.88792E-02	-.20553E-01
74	1.14000	-.24874	1.06014	-.15717E-01	-.88792E-02	-.20553E-01
75	1.14000	1.06014	-.70836	-.15717E-01	-.88792E-02	-.20553E-01
76	1.14000	1.25052	-.24874	-.13891E-02	-.14221E-01	-.34655E-02
77	2.34000	1.25052	-.24874	-.10003E-01	-.50293E-02	-.31303E-02
78	2.34000	1.06014	-.70836	-.11993E-02	-.60701E-03	-.75132E-02
79	2.34000	-.70836	1.06014	-.11993E-02	-.75132E-02	-.60701E-03
80	2.34000	-.24874	1.25052	-.10003E-01	-.50293E-02	-.31303E-02
81	2.34000	-.70836	1.06014	-.10003E-01	-.50293E-02	-.31303E-02
82	2.34000	-.24874	1.06014	-.11993E-02	-.75132E-02	-.60701E-03

Figure 18.- Continued.

83	2.34000	-1.06014	.70836	-.71993E-02	-.60701E-03	-.75132E-02
84	2.34000	-1.25052	.24874	-.10403E-01	.31303E-02	-.54293E-02
85	2.34000	-1.25052	-.24874	-.10403E-01	.31303E-02	.54293E-02
86	2.34000	-1.06014	-.70836	-.71993E-02	-.60701E-03	.75132E-02
87	2.34000	-.70836	-1.06014	-.71993E-02	.75132E-02	-.60701E-03
88	2.34000	-.24874	-1.25052	-.10403E-01	.54293E-02	.31303E-02
89	2.34000	.24874	-1.25052	-.10403E-01	-.54293E-02	.31303E-02
90	2.34000	.70836	-1.06014	-.71993E-02	-.75132E-02	-.60701E-03
91	2.34000	1.06014	-.70836	-.71993E-02	.60701E-03	.75132E-02
92	2.34000	1.25052	-.24874	-.10403E-01	-.31303E-02	.54293E-02
93	3.54000	1.25052	.24874	.26703E-01	.18903E-01	-.45436E-01
94	3.54000	1.06014	.70836	-.26070E-01	.92392E-02	.94557E-02
95	3.54000	.70836	1.06014	-.26070E-01	.92392E-02	.94557E-02
96	3.54000	.24874	1.25052	.26703E-01	-.45436E-01	.18903E-01
97	3.54000	-.24874	1.25052	.26703E-01	-.45436E-01	.18903E-01
98	3.54000	-.70836	1.06014	-.26070E-01	.92392E-02	.94557E-02
99	3.54000	-1.06014	.70836	-.26070E-01	.94557E-02	.92392E-02
100	3.54000	-1.25052	.24874	.26703E-01	.18903E-01	-.45436E-01
101	3.54000	-1.25052	-.24874	.26703E-01	.18903E-01	-.45436E-01
102	3.54000	-1.06014	-.70836	-.26070E-01	.94557E-02	.92392E-02
103	3.54000	-.70836	-1.06014	-.26070E-01	.92392E-02	.94557E-02
104	3.54000	-.24874	-1.25052	.26703E-01	.45436E-01	-.18903E-01
105	3.54000	.24874	-1.25052	.26703E-01	-.45436E-01	-.18903E-01
106	3.54000	.70836	-1.06014	-.26070E-01	.92392E-02	.94557E-02
107	3.54000	1.06014	-.70836	-.26070E-01	.94557E-02	.92392E-02
108	3.54000	1.25052	-.24874	.26703E-01	.18903E-01	-.45436E-01

LOADING INFORMATION

MACH NUMBER = .17000E+01
 ANGLE OF ATTACK = 10.000 DEGRFES
 SIDE SLIP ANGLE = 10.000 DEGRFES
 WING AREA = 13.48666
 REFERENCE AREA = 9.30920
 REFERENCE LENGTH = 2.64000
 EXPOSED WING SPAN B = 4.58000
 MOMENT CENTER: XM = 14.50000
 ZM = 0.00000

UVWING TYPE LOADING PRESSURE

DEFL. ANGLE DEG.	TOTAL	FIN 1 OR R	FIN 2 OR L	FIN 3 OR U	FIN 4 OR D	INTERF. SMALL
CTHR	.30615E-01	0.00000	0.00000	0.00000	0.00000	0.00000
CL	.10224E+01	.40495E-01	.48137E-02	.48118E-02	.10495E-01	0.
CLV	-.10223E+01	.58127E+00	.28949E+00	0.	0.	.15172E+00
CLW	-.49633E+01	0.	0.	-.28940E+00	-.58123E+00	-.15171E+00
CLX	.49624E+01	-.39520E+01	-.19585E+01	0.	0.	-.10524E+01
CLY	.49624E+01	0.	0.	.19578E+01	.39521E+01	.10527E+01
CLZ	.91614E-04	-.50670E+00	.27706E+00	-.27694E+00	.50671E+00	.47694E+14

Figure 18:- Continued.

FOLLOWING ARE IN WIND-AXIS SYSTEM

CL =	.18091E+01	.40092E+00	.19062E+00	.19952E+00	.40090E+00	.20799E+00
CY-IND =	.86084E+04	.41099E+00	.20470E+00	-.20464E+00	-.41099E+00	.99703E+05
CDI =	.12540E+00	.90754E+01	.45604E+01	.45591E+01	.90754E+01	.42691E+01
CDI/CL*2 =	.10308E+00					
CM-IND =	-.08471E+01	-.27945E+01	-.13844E+01	-.13844E+01	-.27945E+01	-.14899E+01
CLN-IND =	-.45862E+03	-.25845E+01	-.14105E+01	.14100E+01	.25845E+01	-.66543E+04

NOTE: L.E. OF LEAD PANEL IN FIRST CHORDWISE ROW IS SUPERSONIC

-----RIGHT WING-----

SPANWISE DISTRIBUTIONS

1	Y/(B/2)	CN*C/(2*B)	CT*C/(2*B)	CY1*C/(2*B)	CYTOT*C/(2*B)	CS*C/(2*B)	CSINT	YBAR	GAMNET(T)	GAMMA,LE/VINF	XLE
1	.65426	.16708	0.00000	0.00000	.00025	0.00000	0.00000	0.00000	-.78235	0.00000	.13334
2	.85415	.16341	0.00000	0.00000	.00112	0.00000	0.00000	0.00000	.01711	0.00000	.40340
3	1.05402	.15153	0.00000	0.00000	.00153	0.00000	0.00000	0.00000	.05558	0.00000	.67342
4	1.25386	.12992	0.00000	0.00000	.00187	0.00000	0.00000	0.00000	.10112	0.00000	.94341
5	1.45367	.09252	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.17509	0.00000	1.21335
6	1.55556	0.00000							.43345		

SUMFX = 0.
 SUMFY1 = 0.
 SUMFY2 = .37742E-02
 SUMFT2 = .23655E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SECTION FORCE PER UNIT LENGTH / (Q*TIPCHORD)	GAMMA,SE / VINF	YBAR	XSE
1	1	.33333	.00354	.00063	3.64000	1.35100
2	2	.66667	.03255	.00640	3.64000	2.10067
3	3	1.00000	.03840	.01321	3.64000	2.45033

Figure 18.- Continued.

****F, FIN VORTEX INFO****

IVRT GAMMA/VINF Y,C,G.

1 .78196 3.27310

----- LEFT WING-----

SPANWISE DISTRIBUTIONS

I	Y/(H/2)	CN*C/(2*H)	CT*C/(2*H)	CY1*C/(2*H)	CYINT*C/(2*H)	CS*C/(2*H)	CSTNT	YBAR	GAMNET(I)	GAMMA,LE/VINF	XLE
7	-.65426	.04806	0.00000	0.00000	-.00151	0.00000	0.00000	0.00000	.22503	0.00000	.13334
8	-.85415	.06115	0.00000	0.00000	-.00066	0.00000	0.00000	0.00000	.04143	0.00000	.40340
9	-1.05402	.07844	0.00000	0.00000	-.00010	0.00000	0.00000	0.00000	.08102	0.00000	.67342
10	-1.25386	.08807	0.00000	0.00000	-.00038	0.00000	0.00000	0.00000	.04513	0.00000	.94341
11	-1.45367	.07516	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.06041	0.00000	1.21335
12	-1.55556	0.00000							-.35211		

SUMFY = 0.
 SUMFY1 = 0.
 SUMFY2 = -.21914E-02
 SUMFY2 = -.23866E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE /TIPCHORD	SUCTION FORCE PER UNIT LENGTH /(Q*TIPCHORD)	GAMMA,SE /VINF	YBAR	XRE
1	1	.33333	-.00686	-.00122	-3.64000	1.35100
2	2	.66667	-.03686	-.00776	-3.64000	2.10067
3	3	1.00000	-.03080	-.01322	-3.64000	2.85053

****F, FIN VORTEX INFO****

IVRT GAMMA/VINF Y,C,G.

2 .18725 -2.19543
 3 -.41216 -3.57139

SPANWISE DISTRIBUTIONS

I	Z/(H/2)	C1*C/(2*H)	C2*C/(2*H)	C21*C/(2*H)	C2111*C/(2*H)	C25*C/(2*H)	CSJAT	ZHAR	GAMMA(T)	GAMMA,LE/VINF	XLE
13	.65026	.04004	0.00000	0.00000	.00151	0.00000	0.00000	0.00000	-.22494	0.00000	.13334
14	.85415	.06113	0.00000	0.00000	.00066	0.00000	0.00000	0.00000	-.06131	0.00000	.46340
15	1.05002	.07842	0.00000	0.00000	.00010	0.00000	0.00000	0.00000	-.08170	0.00000	.67342
16	1.25386	.08404	0.00000	0.00000	.00038	0.00000	0.00000	0.00000	-.04515	0.00000	.90341
17	1.45367	.07514	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.06035	0.00000	1.21335
18	1.55556	0.00000							.35205		

SUMFX = 0.
 SUMFZ1 = 0.
 SUMFZ2 = .21909E-02
 SUMFT2 = .23682E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE /TIP(=0.0)	SUCTION FORCE PER UNIT LENGTH /(C*TIP(=0.0))	GAMMA,SE /VINF	ZHAR	XSE
1	4	.33333	.00687	.00122	3.64000	1.35100
2	5	.66667	.03686	.00776	3.64000	2.10767
3	6	1.00000	.03079	.01322	3.64000	2.85033

***** FIN VORTEX INFO*****

(NOT GAMMA/VINF Z.C.G.

4	-.18721	2.19551
5	.01204	3.57143

Figure 18.- Continued.

SPANWISE DISTRIBUTIONS

I	Z/(B/2)	CN+C/(2*B)	CT+C/(2*B)	CZ1+C/(2*B)	CZTOT+C/(2*B)	CS+C/(2*B)	CSINT	ZBAR	GAMMA(1)	GAMMA,LE/VINF
19	-.65426	.16709	0.00000	0.00000	-.00025	0.00000	0.00000	0.00000	.78236	0.00000
20	-.85415	.16342	0.00000	0.00000	-.00112	0.00000	0.00000	0.00000	-.01711	0.00000
21	-1.05402	.15153	0.00000	0.00000	-.00153	0.00000	0.00000	0.00000	-.05557	0.00000
22	-1.25386	.12992	0.00000	0.00000	-.00167	0.00000	0.00000	0.00000	-.10112	0.00000
23	-1.45367	.09252	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.17509	0.00000
24	-1.55556	0.00000							-.43346	

SUMFX = 0.
 SUMFZ1 = 0.
 SUMFZ2 = -.37762E-02
 SUMFT2 = -.23655E-01

SIDE FORCE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE / TIPCHORD	SECTION FORCE PER UNIT LENGTH / (0.1TIPCHORD)	GAMMA,SE / VINF	ZBAR	XSE
1	7	.34333	-.00354	-.00063	-3.64000	1.35100
2	8	.66667	-.03255	-.00640	-3.64000	2.10067
3	9	1.00000	-.03840	-.01321	-3.64000	2.85033

****E. FIN VORTEX INFO****

IVRT GAMMA/VINF Z,C.G.
 6 -.78196 -3.27321

VELOCITIES AND BERNOULLI PRESSURES AT CONTROL POINTS IMMEDIATELY ABOVE AND BELOW HORIZONTAL WING SURFACE

J	X(J)	Y(J)	Z(J)	UTOT4	VTOT4	WTOT4	PRESS4	UTOT8	VTOT8	WTOT8	PRESS8
1	1.231118	1.530959	0.000000	.129145	.068203	-.173650	-.185699	-.129328	.217259	-.173650	.358780
2	2.386670	1.530959	0.000000	.101384	.088861	-.173650	-.137395	-.107142	.189123	-.173650	.307666
3	3.542222	1.530959	0.000000	.150268	.148505	-.314650	-.223650	-.060070	.288985	-.032650	.169474
4	1.415654	1.998701	0.000000	.152781	-.031297	-.173650	-.241259	-.138542	.136910	-.173650	.383371
5	2.481188	1.998701	0.000000	.113561	.058478	-.173650	-.162344	-.109953	.144508	-.173650	.313307

Figure 18.- Continued.

6	3,544723	1,999701	0,000000	1,461209	1,240225	3,14650	2,40721	0,042107	1,45153	0,327450	1,31724
7	1,600170	2,466397	0,000000	1,91832	0,54983	1,73650	2,97720	0,110493	1,19796	0,173450	3,12729
8	2,575497	2,466397	0,000000	1,29401	0,30109	1,73650	1,93434	0,116276	1,24824	0,173450	3,24213
9	3,551224	2,466397	0,000000	2,06549	0,7211	3,14650	3,03594	0,27879	1,10594	0,327450	0,018133
10	1,744662	2,934030	0,000000	1,44754	0,95172	1,73650	2,27381	0,155865	1,79004	0,173450	4,24061
11	2,670193	2,934030	0,000000	1,67200	0,12209	1,73650	2,51417	0,050142	1,67411	0,173450	2,37021
12	3,555723	2,934030	0,000000	2,09434	1,00777	3,14650	3,04979	0,74149	1,26403	0,327450	1,102489
13	1,969121	1,401580	0,000000	1,57981	0,32492	1,73650	2,14765	0,122717	1,04553	0,173450	3,45299
14	2,746472	3,401580	0,000000	1,04232	0,26553	1,73650	1,53399	0,061653	0,00537	0,173450	1,09837
15	3,560222	3,401580	0,000000	1,01044	0,46797	3,14650	1,60045	0,033557	0,05704	0,327450	0,022616
16	1,231118	-1,530959	0,000000	0,37972	1,14557	1,73650	0,14657	0,35365	1,39216	0,173450	1,34411
17	2,386670	-1,530959	0,000000	0,34291	1,14103	1,73650	0,07364	0,045334	1,50396	0,173450	1,61572
18	1,542222	-1,530959	0,000000	1,24857	1,46280	3,14650	1,185776	0,083083	1,38260	0,327450	1,17261
19	1,415654	-1,998701	0,000000	0,63527	2,22175	1,73650	0,65450	0,04249	1,54796	0,173450	1,64037
20	2,431184	-1,998701	0,000000	0,60120	1,44307	1,73650	0,57346	0,39398	1,0002	0,173450	1,46557
21	3,546723	-1,998701	0,000000	1,37455	1,43383	3,14650	2,05406	0,74005	1,31922	0,327450	1,10909
22	1,600170	-2,466397	0,000000	1,27203	2,14945	1,73650	1,76074	0,04054	1,18724	0,173450	1,61674
23	2,575497	-2,466397	0,000000	0,75563	1,62503	1,73650	0,054974	0,54974	1,10743	0,173450	1,83398
24	3,551224	-2,466397	0,000000	1,54574	1,36504	3,14650	2,30745	0,06113	1,23330	0,327450	1,23540
25	1,744662	-2,934030	0,000000	1,19540	1,45994	1,73650	1,162743	0,12882	0,03715	0,173450	1,31459
26	2,670193	-2,934030	0,000000	1,26500	1,56456	1,73650	1,73723	0,36527	0,03622	0,173450	1,34796
27	3,555723	-2,934030	0,000000	1,77442	1,05272	3,14650	2,44400	1,21315	0,04432	0,327450	1,194191
28	1,969121	-3,401580	0,000000	1,55547	0,96444	1,73650	2,22228	1,20515	0,02396	0,173450	2,62251
29	2,746472	-3,401580	0,000000	0,79984	1,06955	1,73650	0,97793	0,37631	0,01685	0,173450	1,29956
30	3,560222	-3,401580	0,000000	0,78544	1,04215	3,14650	1,111764	0,29624	0,09401	0,327450	0,022946

VELOCITIES AND BERNULLI PRESSURES AT CONTROL POINTS IMMEDIATELY TO RIGHT AND LEFT OF VERTICAL WING SURFACE

J	X(J)	Y(J)	Z(J)	UTOTR	VTOTR	WTOTR	PRESSR	UTOTL	VTOTL	WTOTL	PRESSL
31	1,231118	0,000000	1,530959	0,35304	1,73650	1,39216	1,38369	0,37954	1,73450	1,181535	0,014620
32	2,386670	0,000000	1,530959	0,45320	1,73650	1,50384	1,61541	0,34277	1,73450	1,181021	0,007536
33	1,542222	0,000000	1,530959	0,843091	3,14650	1,38222	1,17274	1,24856	0,32650	1,46260	1,185776
34	1,415654	0,000000	1,998701	0,046223	1,73650	1,58402	1,63478	0,63501	1,73450	2,22151	0,05749
35	2,431184	0,000000	1,998701	0,39379	1,73650	1,29945	1,46515	0,60103	1,73450	1,68275	0,05414
36	3,546723	0,000000	1,998701	1,78414	3,14650	1,31406	1,09527	1,37850	0,327450	1,43304	0,205941
37	1,600170	0,000000	2,466397	0,46425	1,73650	1,18740	1,61013	1,27173	1,73450	2,18947	0,176027
38	2,575497	0,000000	2,466397	0,454953	1,73650	1,10761	1,88352	0,75492	1,73450	1,62565	0,085919
39	3,551224	0,000000	2,466397	0,88130	3,14650	1,23325	1,23571	1,54557	0,32650	1,34492	2,30721
40	1,744662	0,000000	2,934030	1,26459	1,73650	0,03770	3,14432	1,19534	1,73450	1,46427	1,62304
41	2,670193	0,000000	2,934030	0,36504	1,73650	0,93750	1,34756	1,26517	1,73450	1,56498	0,173450
42	3,555723	0,000000	2,934030	1,21437	3,14650	0,94443	1,184220	1,77619	0,32650	1,05325	0,264566
43	1,969121	0,000000	3,401580	1,26505	1,73650	0,62352	2,62256	1,55537	1,73450	0,97021	2,22210
44	2,746472	0,000000	3,401580	0,37616	1,73650	0,811740	1,29938	0,74969	1,73450	1,04094	0,097761
45	1,542222	0,000000	3,401580	0,29034	3,14650	0,99447	0,22264	0,74530	0,32650	1,09277	1,11733
46	1,231118	0,000000	1,530959	1,29027	1,73650	2,17204	3,58778	1,29144	1,73450	0,88208	1,185497
47	2,386670	0,000000	-1,530959	1,07144	1,73650	1,69127	3,07672	1,01386	1,73450	0,88804	1,37349
48	3,542222	0,000000	-1,530959	0,60075	3,14650	2,08990	1,69483	1,50266	0,32650	1,64910	0,223645
49	1,415654	0,000000	-1,998701	1,34563	1,73650	1,36918	3,43375	1,52782	1,73450	0,31290	2,41249
50	2,431184	0,000000	-1,998701	1,09956	1,73650	1,04516	3,13356	1,13563	1,73450	0,54443	1,62346
51	1,542222	0,000000	-1,998701	0,42110	3,14650	1,65141	1,31332	1,61207	0,32650	1,26033	2,00718
52	1,600170	0,000000	-2,466397	1,10497	1,73650	1,19804	3,12738	1,91836	1,73450	0,54979	2,97723
53	2,575497	0,000000	-2,466397	1,16279	1,73650	1,24831	3,26630	1,29804	1,73450	0,30114	1,93037
54	3,551224	0,000000	-2,466397	0,27477	3,14650	1,10599	0,16130	2,06540	0,32650	0,74215	0,303595
55	1,744662	0,000000	-2,934030	1,55470	1,73650	1,79950	0,29074	1,44759	1,73450	0,43172	2,27344
56	2,670193	0,000000	-2,934030	0,80445	1,73650	1,07415	2,37202	1,73450	1,73450	1,12211	2,25120
57	3,555723	0,000000	-2,934030	0,74198	3,14650	1,26807	1,02485	2,09439	0,32650	1,00780	0,304930

Figure 18.- Continued.

58	1.969121	0.000000	-3.401580	-.122722	.173650	-.194557	.345311	.157986	.173650	-.032490	-.234773
59	2.764672	0.000000	-3.401580	-.061665	.173650	-.090509	.190441	.104234	.173650	-.026654	-.153402
60	3.560222	0.000000	-3.401580	-.003356	.314650	-.065706	.022617	.101604	.032450	-.044798	-.160046

PRESSURE LOADINGS AT CONTROL POINTS

J	X(J)	Y(J)	Z(J)	DELT.P.LIN.	DELT.P.HEMN.
1	1.231118	1.530959	0.000000	.516305	.544479
2	2.386670	1.530959	0.000000	.417051	.445061
3	3.542222	1.530959	0.000000	.420677	.493123
4	1.415654	1.998701	0.000000	.562686	.624629
5	2.481188	1.998701	0.000000	.447027	.475691
6	3.546723	1.998701	0.000000	.406632	.371745
7	1.600170	2.466397	0.000000	.605451	.610449
8	2.575697	2.466397	0.000000	.492153	.520055
9	3.551224	2.466397	0.000000	.357319	.285461
10	1.784662	2.934030	0.000000	.609237	.456443
11	2.670193	2.934030	0.000000	.494643	.488434
12	3.555723	2.934030	0.000000	.270477	.202441
13	1.969121	3.401580	0.000000	.561396	.580064
14	2.764672	3.401580	0.000000	.331792	.344234
15	3.560222	3.401580	0.000000	.194493	.182661
16	1.231118	-1.530959	0.000000	.144674	.153088
17	2.386670	-1.530959	0.000000	.159248	.164935
18	3.542222	-1.530959	0.000000	.064508	.068515
19	1.415654	-1.998701	0.000000	.219553	.229447
20	2.481188	-1.998701	0.000000	.199036	.203903
21	3.546723	-1.998701	0.000000	.118900	.096334
22	1.600170	-2.466397	0.000000	.347314	.337149
23	2.575697	-2.466397	0.000000	.268955	.274354
24	3.551224	-2.466397	0.000000	.136922	.107234
25	1.784662	-2.934030	0.000000	.492684	.477202
26	2.670193	-2.934030	0.000000	.326134	.308510
27	3.555723	-2.934030	0.000000	.112657	.080410
28	1.969121	-3.401580	0.000000	.552124	.444479
29	2.764672	-3.401580	0.000000	.235230	.227749
30	3.560222	-3.401580	0.000000	.097441	.088818
31	1.231118	0.000000	1.530959	.146599	.152489
32	2.386670	0.000000	1.530959	.159195	.168877
33	3.542222	0.000000	1.530959	.084331	.088500
34	1.415654	0.000000	1.998701	.219449	.229774
35	2.481188	0.000000	1.998701	.198264	.203424
36	3.546723	0.000000	1.998701	.118871	.096314
37	1.600170	0.000000	2.466397	.347196	.337040
38	2.575697	0.000000	2.466397	.268969	.274270
39	3.551224	0.000000	2.466397	.138853	.107149
40	1.784662	0.000000	2.934030	.492793	.477136
41	2.670193	0.000000	2.934030	.326044	.308442
42	3.555723	0.000000	2.934030	.112565	.080446
43	1.969121	0.000000	3.401580	.552084	.444466
44	2.764672	0.000000	3.401580	.235170	.227699
45	3.560222	0.000000	3.401580	.097784	.088788
46	1.231118	0.000000	-1.530959	.146343	.154475
47	2.386670	0.000000	-1.530959	.147060	.145078
48	3.542222	0.000000	-1.530959	.020680	.031128
49	1.415654	0.000000	-1.998701	.212641	.224634

Figure 18.- Continued.

50	2.481184	0.000000	-1.498701	.447038	.475702
51	3.546724	0.000000	-1.498701	.406635	.371749
52	1.800170	0.000000	-2.466397	.545465	.610061
53	2.575897	0.000000	-2.466397	.492166	.520067
54	3.551224	0.000000	-2.466397	.357326	.285066
55	1.784662	0.000000	-2.434030	.609257	.656462
56	2.670193	0.000000	-2.434030	.494094	.488008
57	3.555723	0.000000	-2.434030	.270462	.202044
58	1.969121	0.000000	-3.401580	.561416	.540084
59	2.744672	0.000000	-3.401580	.331799	.444244
60	3.560222	0.000000	-3.401580	.196496	.182664

LOADING INFORMATION

MACH NUMBER = .17000E+01
 ANGLE OF ATTACK = 10.000 DEGREES
 SIDE SLIP ANGLE = 10.000 DEGREES
 WING AREA = 13.000000
 REFERENCE AREA = 5.30929
 REFERENCE LENGTH = 2.00000
 EXPOSED WING SPAN H = 0.00000
 MOMENT CENTER XM = 10.50000
 ZM = 0.00000

BERNOULLI TYPE LOADING PRESSURE

REF. ANGLE	TOTAL	FIN 1 OR 2	FIN 2 OR 3	FIN 3 OR 4	FIN 4 OR 5	INTERF. SHELL
DEG. =	0.00000	0.00000	0.00000	0.00000	0.00000	
CTHP. =	.29447E+01	.10504E+01	.43780E+02	.43780E+02	.10546E+00	
CZ =	.10099E+01	.58324E+00	.27494E+00			.15172E+00
CY =	-.10099E+01	0.	0.	.27486E+00	.58325E+00	.15171E+00
CM =	-.48638E+01	.39542E+01	.18559E+01	0.	0.	.10527E+01
CLM =	.48624E+01	0.	0.	.18554E+01	.39543E+01	.10527E+01
CLL =	.48597E+04	-.50701E+00	.26086E+00	-.26079E+00	.50702E+00	.47694E+14

FOLLOWING ARE IN WIND-AXIS SYSTEM

CL =	.13914E+01	.40237E+00	.18953E+00	.18948E+00	.40234E+00	.20799E+00
CY-IND. =	.59651E+04	.41241E+00	.19441E+00	-.19436E+00	-.41242E+00	.99707E+05
CMT. =	.32179E+00	.91557E+01	.43500E+01	.43487E+01	.91558E+01	.52691E+01
CDT/CL+2 =	.10013E+00	0.	0.	0.	0.	0.
CY-IND. =	-.07054E+01	.27960E+01	-.13123E+01	-.13120E+01	-.27961E+01	-.14484E+01
CL-IND. =	-.41231E+03	.25859E+01	-.13362E+01	.13358E+01	.25860E+01	-.66543E+04

NOTE: E.L. OF LEAD PANEL IN FIRST COLUMNISE ROW IS SUPERSONIC

-----RIGHT-TING-----

SPANWISE DISTRIBUTIONS

I	Y/(H/2)	CN*C/(2*H)	CF*C/(2*H)	CY1*C/(2*H)	CYTOT*C/(2*H)	CS*C/(2*H)	CSINT	YHAR	GAMNET(I)	GAMMA,LE/VINF	XLE
1	.65426	.17051	0.00000	0.00000	.00017	0.00000	0.00000	0.00000	-.79887	0.00000	.13334
2	.65415	.16748	0.00000	0.00000	.00207	0.00000	0.00000	0.00000	.01460	0.00000	.40380
3	1.05402	.14747	0.00000	0.00000	.00146	0.00000	0.00000	0.00000	.09361	0.00000	.67342
4	1.25386	.12736	0.00000	0.00000	.00146	0.00000	0.00000	0.00000	.09411	0.00000	.94341
5	1.05367	.09399	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.15623	0.00000	1.21335
6	1.55556	0.00000							.44032		

SUMFY = 0.
 SUMFY1 = 0.
 SUMFY2 = .42571E+02
 SUMFT2 = .24266E+01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE /TIPCHORD	SUCTION FORCE PER UNIT LENGTH /(1/2)*TIPCHORD	GAMMA,SE /VINF	YHAR	XSE
1	1	.53333	.00566	.00065	3.64000	1.45100
2	2	.65667	.03568	.00662	3.64000	2.10067
3	3	1.00000	.03901	.01354	3.64000	2.85033

****T.E. FIN VORTEX INFO****

IVRT GAMMA/VINF Y.C.G.
 1 .79886 3.23908

----- LEFT WING -----

SPANWISE DISTRIBUTION

I	Y/(B/2)	CX*C/(2*B)	CT*C/(2*B)	CY1*C/(2*B)	CYTOT*C/(2*B)	CS*C/(2*B)	CSINT	YBAR	GAMMA(T)	GAMMA,LE/VINF	XLE
7	-.65426	.04819	0.00000	0.00000	-.00150	0.00000	0.00000	0.00000	.22543	0.00000	.13334
8	-.65415	.06031	0.00000	0.00000	-.00056	0.00000	0.00000	0.00000	.05680	0.00000	.40340
9	-1.05402	.07455	0.00000	0.00000	-.00007	0.00000	0.00000	0.00000	.06813	0.00000	.67342
10	-1.25386	.08147	0.00000	0.00000	-.00066	0.00000	0.00000	0.00000	.03293	0.00000	.94341
11	-1.45367	.06801	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.06486	0.00000	1.21335
12	-1.55554	0.00000							-.31864		

SUMFX = 0.
 SUMFY1 = 0.
 SUMFY2 = -.22984E-02
 SUMFT2 = -.21352E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE AT TIP (ORD)	SUCTION FORCE PER UNIT LENGTH / (0.1 * TIP CHORD)	GAMMA,SE / VINF	YBAR	XSE
1	1	.35553	-.00602	-.00107	-3.64000	1.35100
2	2	.66667	-.03334	-.00698	-3.64000	2.10067
3	3	1.00000	-.02787	-.01193	-3.64000	2.85033

****T.F. FIN VORTEX INFO****

IVRT GAMMA/VINF . . . Y.C.G.

2	.15764	-2.16595
3	-.36318	-5.56077

Figure 18.- Continued.

-----UPPER ATIC-----

SPANWISE DISTRIBUTIONS--

I	Z/(R/2)	CN=C/(2*H)	CT=C/(2*R)	CZ1=C/(2*H)	CZTOT=C/(2*H)	CS=C/(2*B)	CSINT	ZBAR	GAMMA, LE/VINF	XLE	
13	.65426	.04817	0.00000	0.00000	.00150	0.00000	0.00000	0.00000	-.22554	0.00000	.13334
14	.85415	.06024	0.00000	0.00000	.00056	0.00000	0.00000	0.00000	-.05678	0.00000	.40340
15	1.05402	.07483	0.00000	0.00000	.00007	0.00000	0.00000	0.00000	-.04811	0.00000	.67342
16	1.25386	.08185	0.00000	0.00000	.00006	0.00000	0.00000	0.00000	-.03296	0.00000	.94341
17	1.45367	.08800	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	.06481	0.00000	1.21335
18	1.55556	0.00000							.31859		

SUMFX = 0.
 SUMFZ1 = 0.
 SUMFZ2 = .22974E-02
 SUMFT2 = .21349E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE /TIPCHORD	SUCTION FORCE PER UNIT LENGTH /(0.5TIPCHORD)	GAMMA, SE /VINF	ZBAR	XSE
1	4	.33333	.09602	.00107	3.64000	1.35100
2	5	.66667	.03334	.00698	3.64000	2.10167
3	6	1.00000	.02787	.01193	3.64000	2.85033

****T.E. FIN VORTEX INFO****

IVRT GAMMA/VINF Z.C.G.

4 =.19764 2.16521
 5 .38107 3.56081

Figure 18.- Continued.

-----LOWEN WING-----

SPANWISE DISTRIBUTIONS

I	Z/(R/2)	CN=C/(2*B)	CT=C/(2*B)	CZ1=C/(2*B)	CZTIT=C/(2*B)	CS=C/(2*B)	CSINT	ZBAR	GAMMA(I)	GAMMA,LE/VINF	YLF
19	-.65426	.17051	0.00000	0.00000	-.00017	0.00000	0.00000	0.00000	.79444	0.00000	.13330
20	-.45015	.16718	0.00000	0.00000	-.00207	0.00000	0.00000	0.00000	-.01460	0.00000	.40340
21	-1.05402	.14747	0.00000	0.00000	-.00146	0.00000	0.00000	0.00000	-.09361	0.00000	.67342
22	-1.25386	.12756	0.00000	0.00000	-.00146	0.00000	0.00000	0.00000	-.09411	0.00000	.94341
23	-1.45367	.09399	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	-.15423	0.00000	1.21335
24	-1.55556	0.00000							-.44033		

SUMFX = 0.
 SUMFZ1 = 0.
 SUMFZ2 = -.42571E-02
 SUMFT2 = -.24247E-01

SIDE EDGE DISTRIBUTION

JTIP	JSE	DISTANCE FROM LE /TIPCHORD	SUCTION FORCE PER UNIT LENGTH /(Q*TIPCHORD)	GAMMA,SE /VINF	ZBAR	XSE
1	7	.33333	-.00366	-.00065	-3.64000	1.35100
2	8	.66667	-.03368	-.00642	-3.64000	2.10067
3	9	1.00000	-.03901	-.01350	-3.64000	2.85033

*****E. FIN VORTEX INFO*****

IVRT GAMMA/VINF Z.C.G.

A -.79407 -1.23910

 AFT OF LEADING EDGE OF FIN QUOTCHORDS

PRESSURE COEFFICIENTS AT POINTS ON BODY MERIDIANS

J	THETA, DEG.	X4	Y4	Z4	UTOT	VTOT	WTOT	CP, LIN.	CP, HERN.	OR/DX	P/PINF, HERN.	P/PINF, LIN.
BODY RING# 1												
1	11.25000	36.54000	1.25052	.24874	.08210	.13852	.01640	-.1643A	-.12894	0.00000	.73915	.66747
2	33.75000	36.54000	1.06014	.70836	.01475	.05202	.03127	-.02949	-.02949	0.00000	.91955	.94034
3	56.25000	36.54000	.70836	1.06014	-.02327	.04871	-.10981	.04655	.09578	0.00000	1.19375	1.09416
4	78.75000	36.54000	.24874	1.25052	-.03442	.11770	-.16598	.06884	.13193	0.00000	1.27093	1.13926
5	101.25000	36.54000	-.24874	1.25052	.01842	.17193	-.18030	-.04685	.02463	0.00000	1.04982	.92544
6	123.75000	36.54000	-.70836	1.06014	-.06634	.18091	-.17097	.01267	.07637	0.00000	1.15449	1.02564
7	146.25000	36.54000	-1.06014	.70836	-.08633	.17099	-.18087	.01266	.07636	0.00000	1.15448	1.02562
8	168.75000	36.54000	-1.25052	.24874	.01844	.18031	-.17190	-.03688	.02460	0.00000	1.04977	.92540
9	191.25000	36.54000	-1.25052	-.24874	-.03443	.16598	-.17169	.06887	.13196	0.00000	1.27099	1.13932
10	213.75000	36.54000	-1.06014	-.70836	-.07328	.10984	-.06876	.04655	.09580	0.00000	1.19381	1.09418
11	236.25000	36.54000	-.70836	-1.06014	.01475	-.03123	-.03205	-.02949	-.02986	0.00000	.93959	.94034
12	258.75000	36.54000	-.24874	-1.25052	.08219	-.01634	-.13852	-.16437	-.12894	0.00000	.73916	.66747
13	281.25000	36.54000	.24874	-1.25052	-.09828	.06821	-.20246	.14656	.26977	0.00000	1.54575	1.39765
14	303.75000	36.54000	.70836	-1.06014	-.04277	.15795	-.19643	.08555	.15552	0.00000	1.31462	1.17307
15	326.25000	36.54000	1.06014	-.70836	-.04277	.19642	-.15796	.08555	.15552	0.00000	1.31462	1.17307
16	348.75000	36.54000	1.25052	-.24874	-.09828	.20246	-.06821	.14656	.26977	0.00000	1.54575	1.39765
BODY RING# 2												
1	11.25000	37.74000	1.25052	.24874	.09340	.14188	.00241	-.18680	-.14353	0.00000	.78965	.62210
2	33.75000	37.74000	1.06014	.70836	.05033	.06741	-.02045	-.10067	-.07064	0.00000	.85710	.79635
3	56.25000	37.74000	.70836	1.06014	-.03353	.07450	-.11789	.00705	.05716	0.00000	1.11564	1.01427
4	78.75000	37.74000	.24874	1.25052	-.03836	.12796	-.16918	.07671	.14399	0.00000	1.29128	1.15519
5	101.25000	37.74000	-.24874	1.25052	.03431	.19227	-.17615	-.08661	-.08789	0.00000	.98444	.86120
6	123.75000	37.74000	-.70836	1.06014	.02468	.21202	-.14964	-.04935	.00988	0.00000	1.01908	.90016
7	146.25000	37.74000	-1.06014	.70836	.02468	.14967	-.21198	-.04937	.00987	0.00000	1.01907	.90013
8	168.75000	37.74000	-1.25052	.24874	.03432	.17615	-.19224	-.06864	-.08771	0.00000	.98439	.86114
9	191.25000	37.74000	-1.25052	-.24874	-.03837	.16918	-.12799	.07674	.14402	0.00000	1.29135	1.15525
10	213.75000	37.74000	-1.06014	-.70836	-.03434	.11774	-.07857	.00708	.05721	0.00000	1.11573	1.01431
11	236.25000	37.74000	-.70836	-1.06014	.05033	.02044	-.06743	-.10066	-.07062	0.00000	.85714	.79636
12	258.75000	37.74000	-.24874	-1.25052	.09340	-.02230	-.14188	-.18680	-.14352	0.00000	.78965	.62210
13	281.25000	37.74000	.24874	-1.25052	-.11208	.05872	-.20464	.22416	.29970	0.00000	1.60630	1.45348
14	303.75000	37.74000	.70836	-1.06014	-.12123	.14059	-.20823	.24245	.33892	0.00000	1.68564	1.49048
15	326.25000	37.74000	1.06014	-.70836	-.12122	.20823	-.14060	.24245	.33892	0.00000	1.68564	1.49048
16	348.75000	37.74000	1.25052	-.24874	-.11208	.20464	-.05872	.22416	.29970	0.00000	1.60630	1.45348
BODY RING# 3												
1	11.25000	38.94000	1.25052	.24874	.10902	.15137	-.04299	-.21804	-.15818	0.00000	.68000	.55880
2	33.75000	38.94000	1.06014	.70836	.03374	.07778	-.02726	-.06749	-.03683	0.00000	.92549	.82297
3	56.25000	38.94000	.70836	1.06014	.00734	.08662	-.12365	-.01469	.03689	0.00000	1.07409	.98599
4	78.75000	38.94000	.24874	1.25052	.03709	.08564	-.16211	-.07418	-.02054	0.00000	.98445	.88994
5	101.25000	38.94000	-.24874	1.25052	.08829	.23668	-.16751	-.17657	-.11217	0.00000	.77308	.68240
6	123.75000	38.94000	-.70836	1.06014	.05310	.20442	-.15419	-.10638	-.04540	0.00000	.90816	.78479
7	146.25000	38.94000	-1.06014	.70836	.05310	.15421	-.20438	-.10638	-.04539	0.00000	.90817	.78479
8	168.75000	38.94000	-1.25052	.24874	.08829	.16751	-.23665	-.17657	-.11217	0.00000	.77309	.68279
9	191.25000	38.94000	-1.25052	-.24874	.03708	.16211	-.08567	-.07416	-.02052	0.00000	.98448	.88997
10	213.75000	38.94000	-1.06014	-.70836	.00734	.12369	-.08668	-.01467	.03692	0.00000	1.07469	.97032

Figure 18.- Continued.

11	246,25000	38,94000	-.70836	-1,06014	.03373	.02729	-.07281	-.06747	-.03640	0,00000	.92555	.86351
12	254,75000	38,94000	-.24874	-1,25052	.10902	.04299	-.15137	-.21803	-.15817	0,00000	.68002	.55492
13	281,25000	38,94000	.24874	-1,25052	-.09663	-.00224	-.21700	.19326	.23784	0,00000	1,48116	1,39096
14	313,75000	38,94000	.70836	-1,06014	-.15488	.13903	-.20945	.30977	.42275	0,00000	1,85523	1,62666
15	326,25000	38,94000	1,06014	-.70836	-.15488	.20944	-.13904	.30977	.42275	0,00000	1,85523	1,62666
16	344,75000	38,94000	1,25052	-.24874	-.09663	.21700	.00223	.19325	.23784	0,00000	1,48115	1,39095

Figure 18.- Concluded.

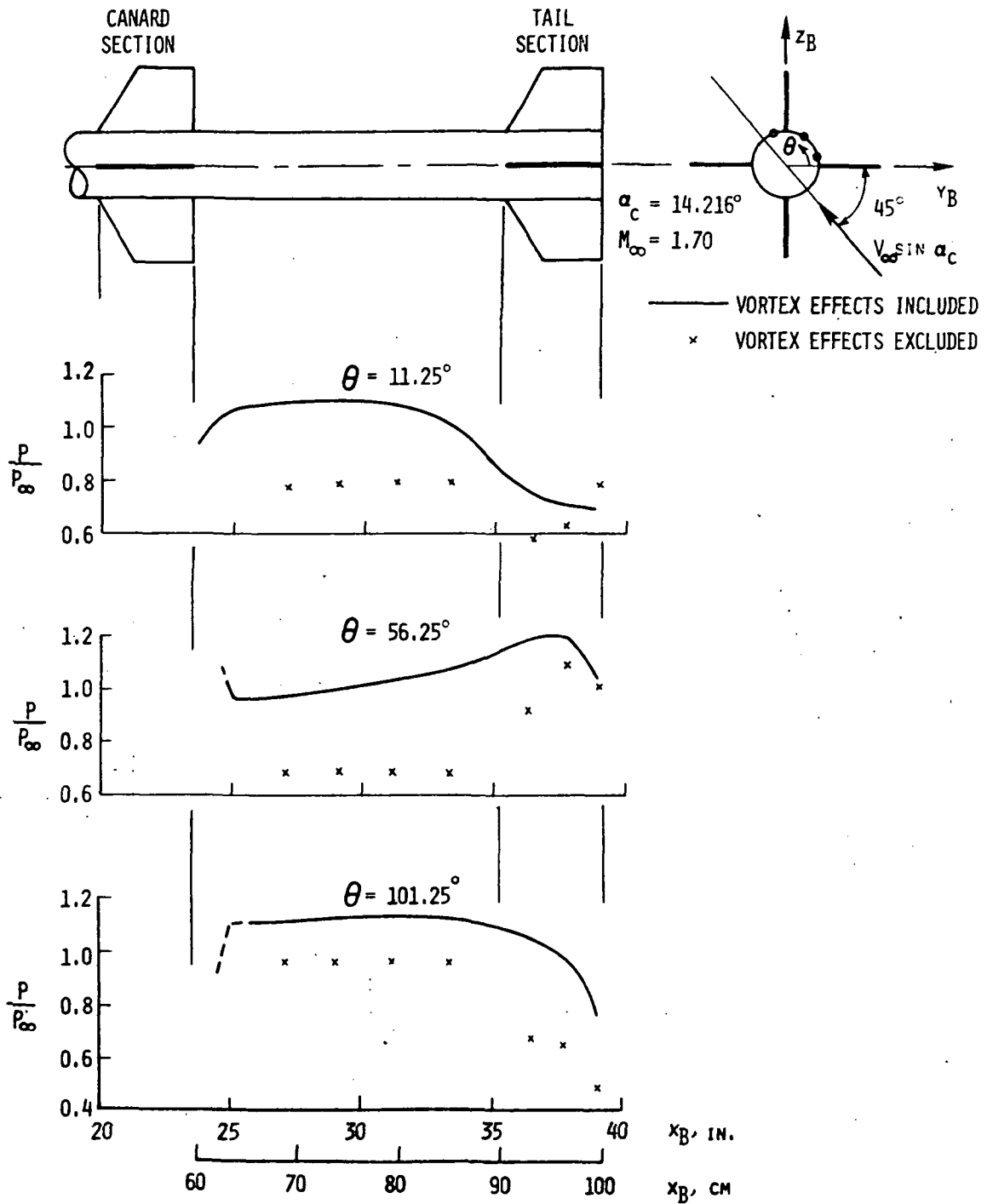


Figure 19.- Calculated pressure distributions along body meridians from canard section to body base, first sample case, step 6.

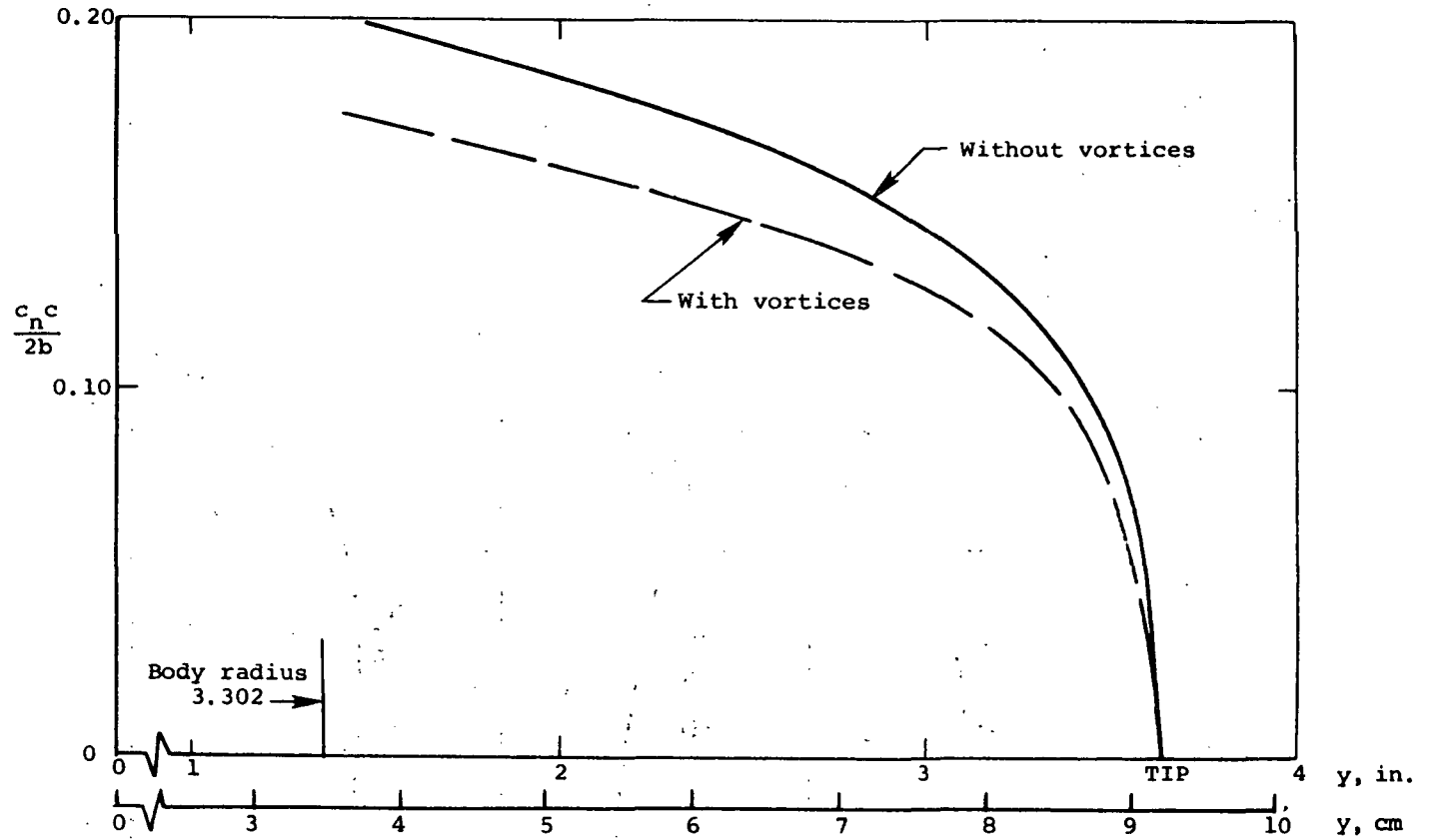


Figure 20.- Calculated span load distribution on right horizontal tail fin, first sample case, step 6.

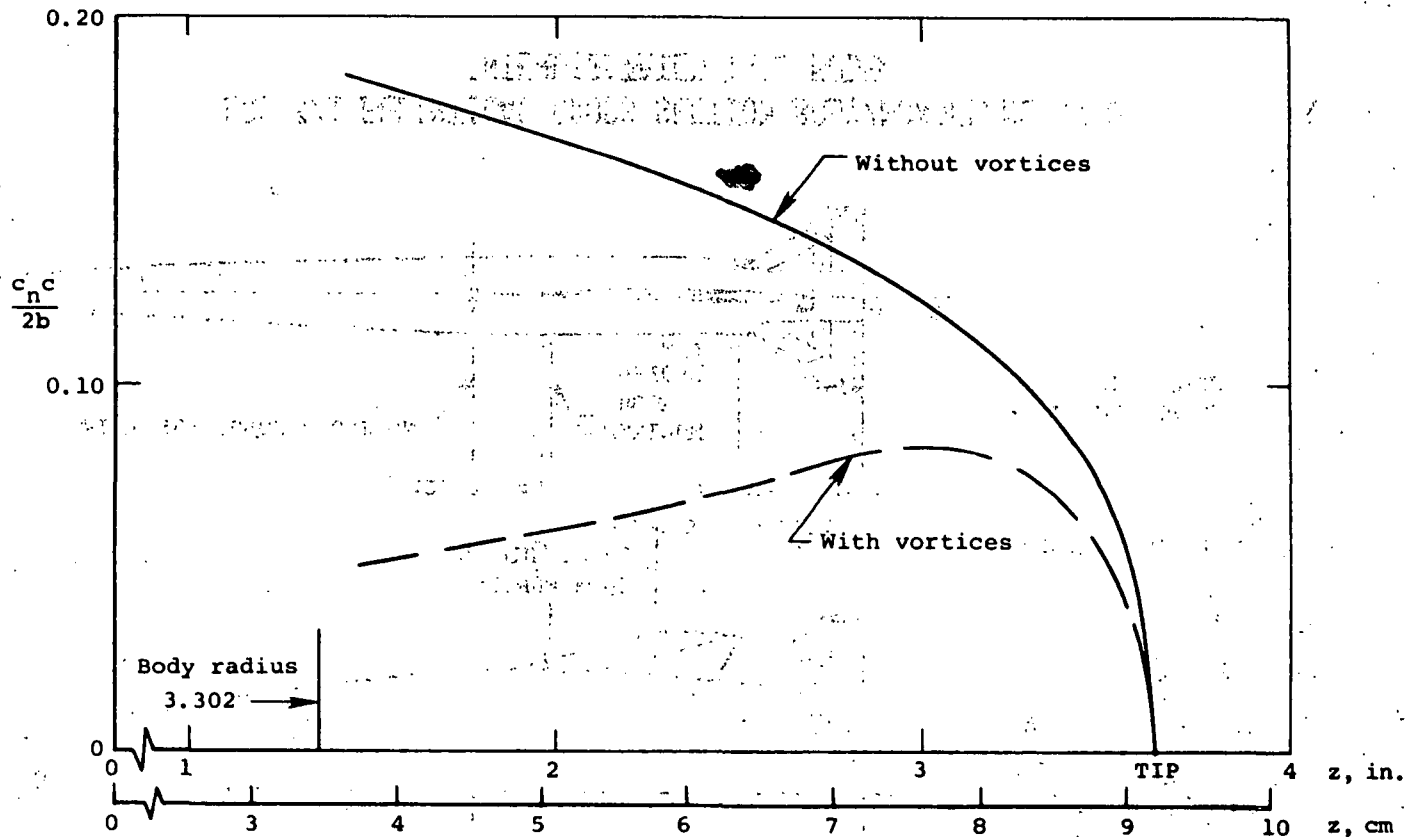
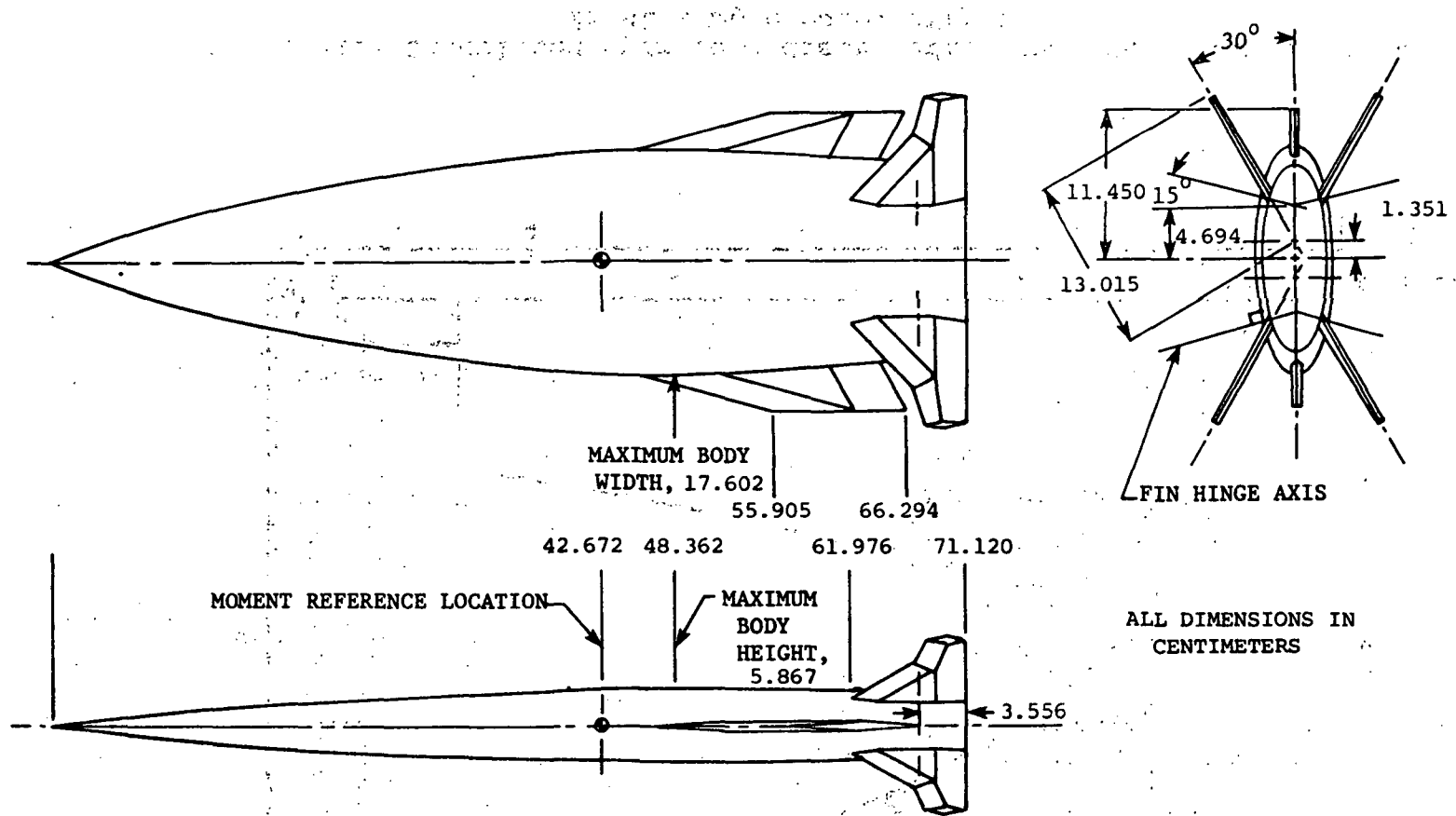


Figure 21.- Calculated span-load distribution on upper vertical fin, first sample case, step 6.



LRC 3/1 ELLIPTICAL CROSS SECTION BODY/MONOPLANE WING/
INTERDIGITATED TAIL MODEL

Figure 22.- Configuration used for second sample case.

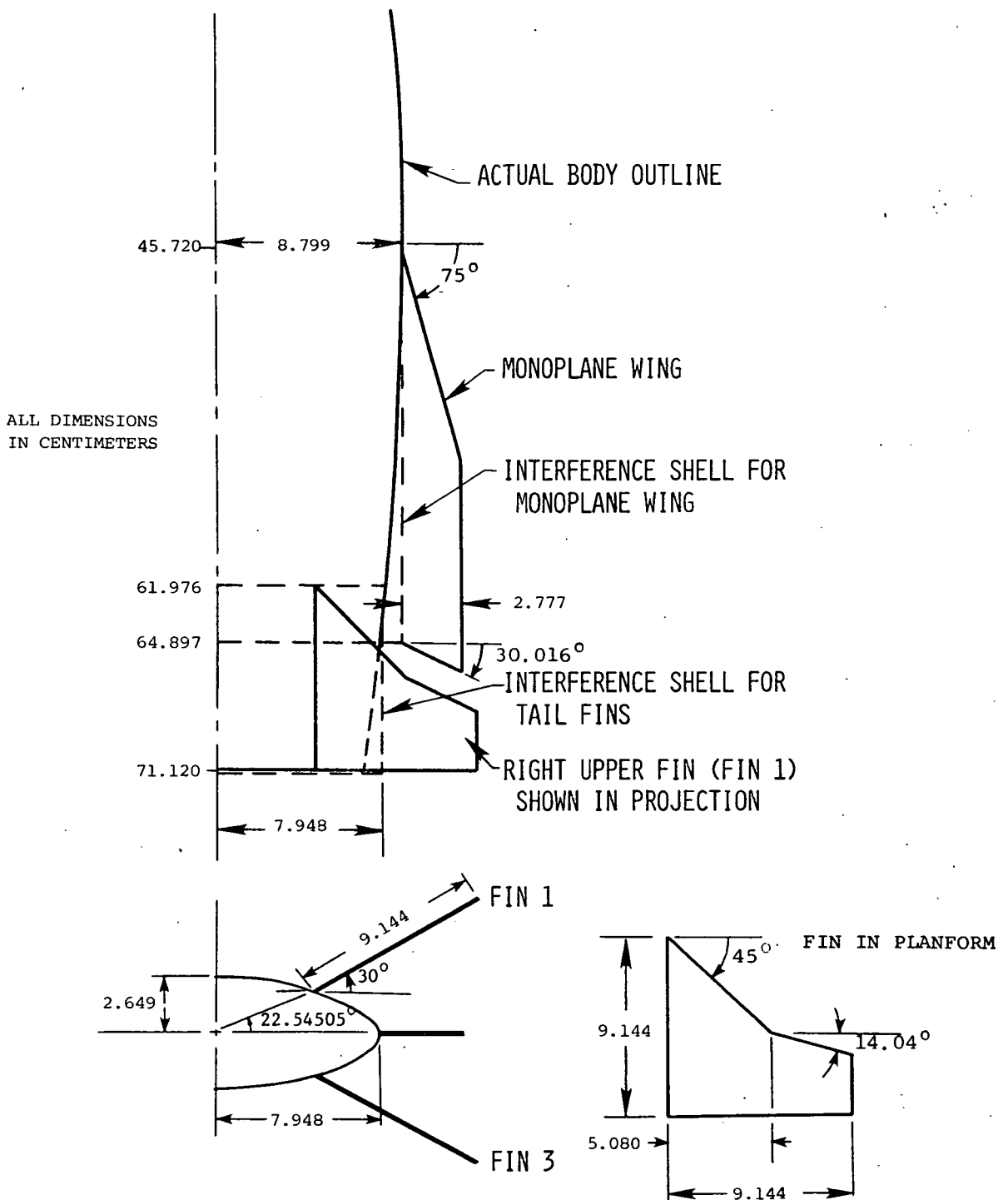
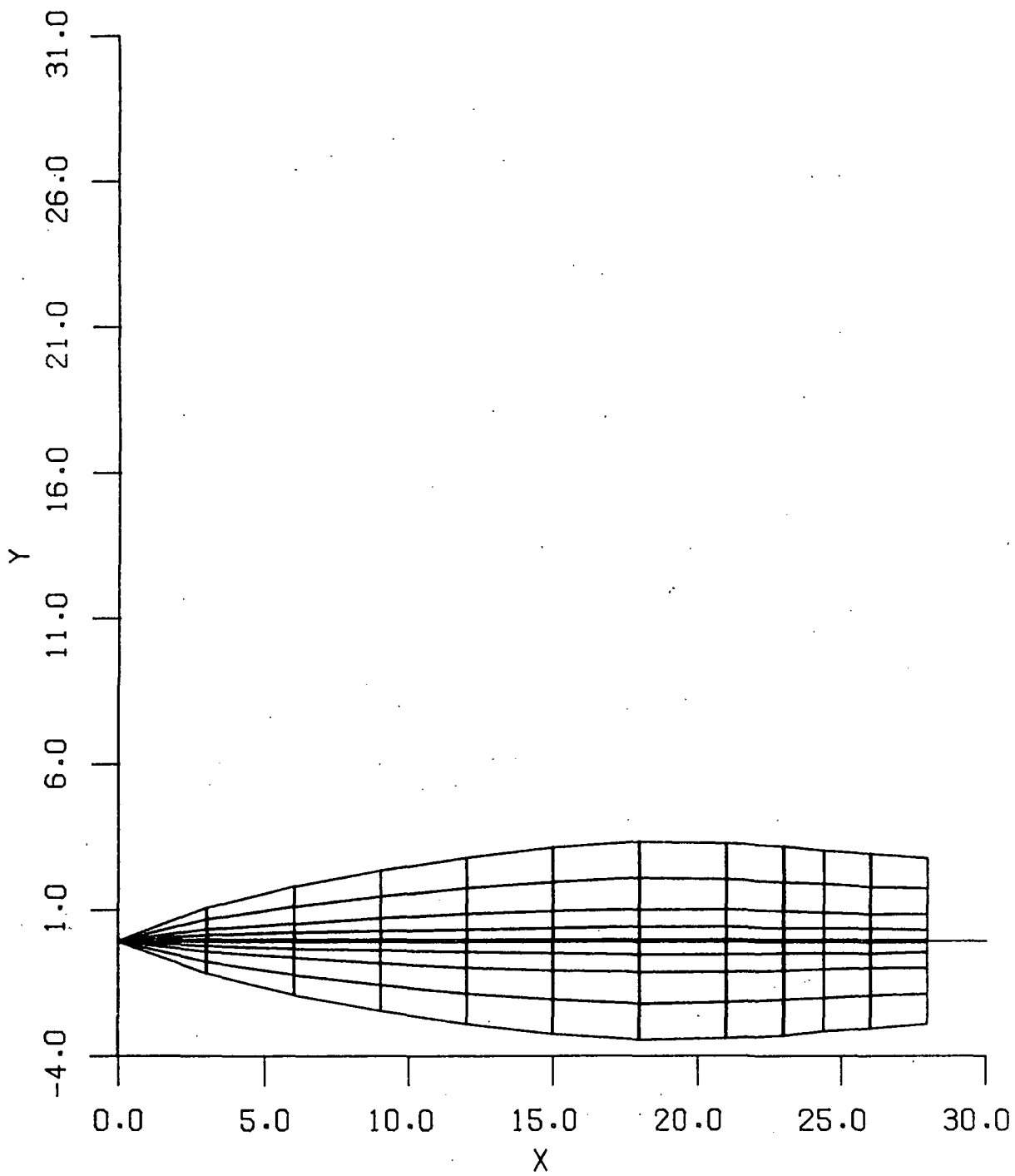
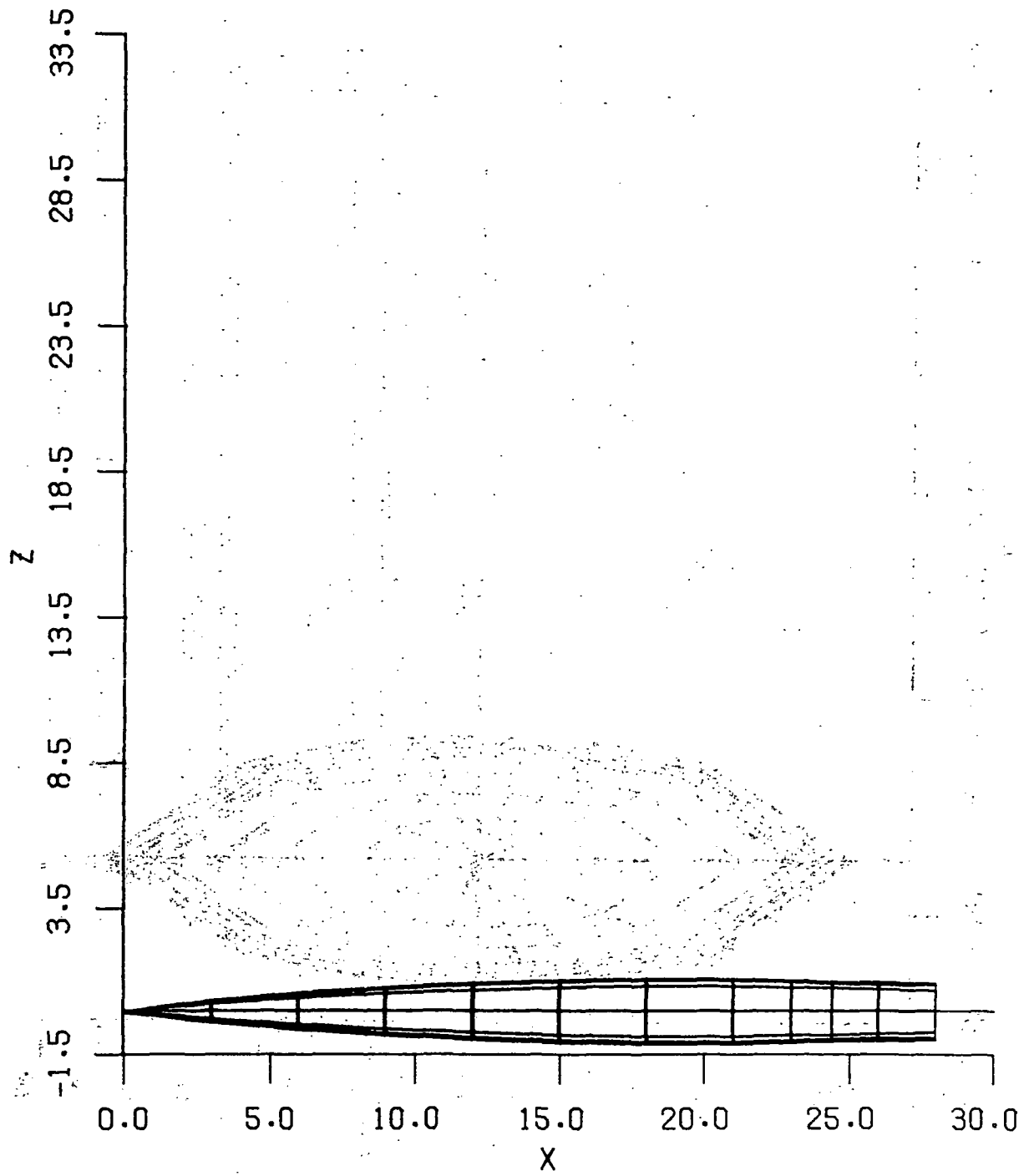


Figure 23.- Geometrical details, idealizations of configuration used for second sample case.



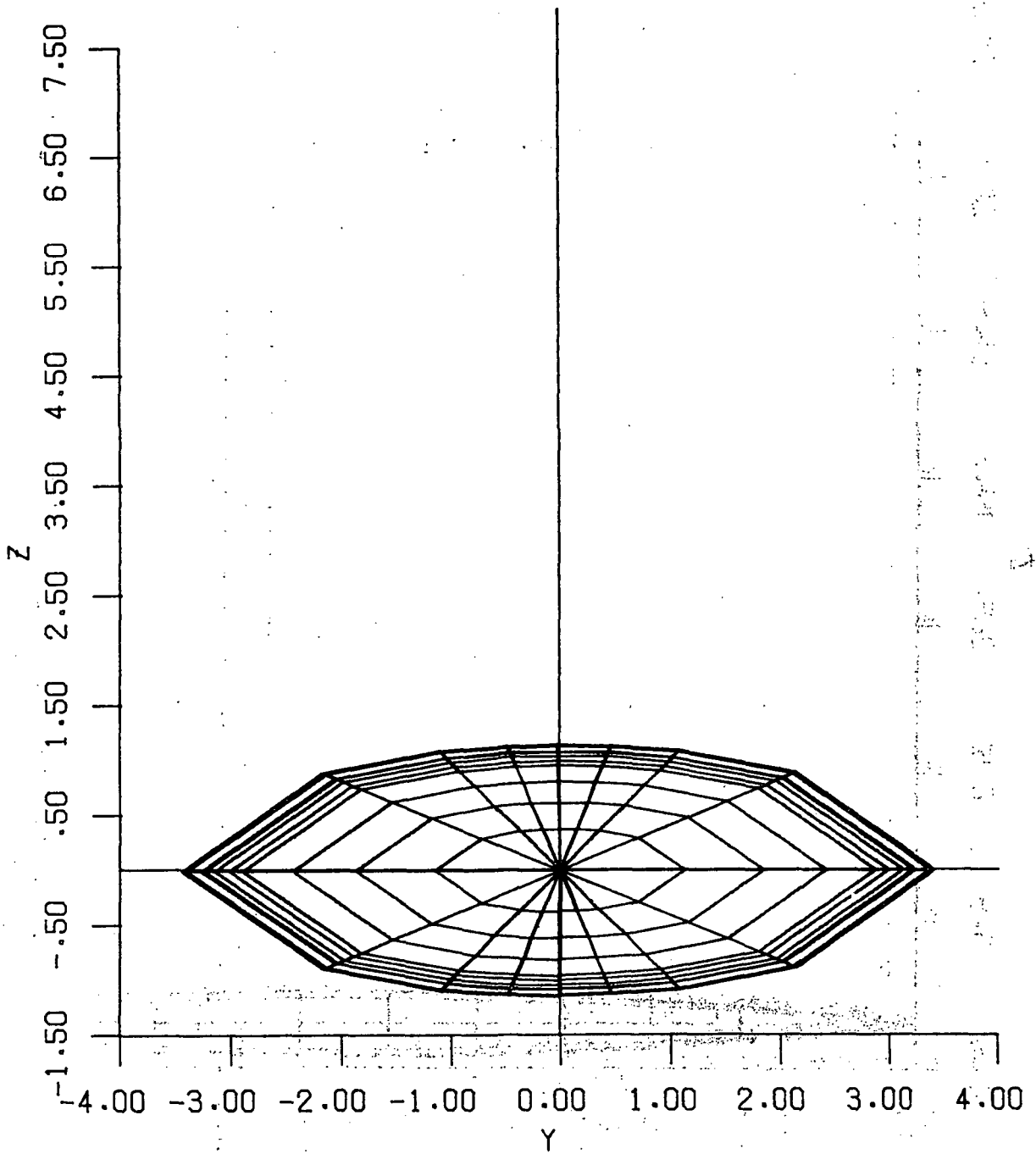
(a) Plan View

Figure 24.- Body source paneling layout, second sample case.



(b) Elevation

Figure 24.- Continued.



(c) End View

Figure 24.- Concluded.


```

LRC 3/1 ELLIPTIC WING/BODY MISSILE CONFIGURATION - NOSE VORTICITY
 1 0 0 0 0 0 0 0 0 0 0 22 2 10 0
18.0 0.0
 0 0 =3 0 0 0 -1 0 0 1 13 30 0 0 0 0 0 0 0 0 0 0 0
 0.000 .420 .700 2.100 3.500 4.900 5.600 6.300 7.700 8.400
 9.100 10.500 11.900 12.600 13.300 14.700 15.400 16.800 17.500 18.200
19.040 19.600 20.300 21.000 22.400 23.100 24.500 25.900 26.600 28.000
 0.0000 .2675 .3914 .8808 1.2745 1.6168 1.7736 1.9222 2.1978 2.3256
 2.4471 2.6721 2.8735 2.9653 3.0510 3.2033 3.2692 3.3777 3.4184 3.4481
 3.4641 3.4563 3.4322 3.3970 3.3029 3.2476 3.1283 3.0090 2.9552 2.8846
 0.0000 .0892 .1305 .2936 .4248 .5389 .5912 .6407 .7326 .7752
 .8157 .8907 .9578 .9884 1.0170 1.0678 1.0897 1.1259 1.1395 1.1494
 1.1547 1.1521 1.1441 1.1323 1.1010 1.0825 1.0428 1.0030 .9851 .9615
ELLIPTIC BODY PANELING - KRAD=9, KFORX=11
 0 0 =2
 1 0 1 0 0 0 -1 0 0 1 9 11 0 0 0 0 0 0
12.567 3.4641 16.8
 0.0 2.0 4.0 6.0 8.0 10. 12. 14. 16. 18.
 0.000 3.000 6.000 9.000 12.00 15.00 18.00 21.00 23.00 24.40
25.6
 1.70 10.
 0.0 .653 .990 1.281 1.528 1.7465 1.932 2.1 2.24 2.35
 0.0 .299 .531 .739 .929 1.1028 1.272 1.423 1.551 1.673
 0.0 .191 .4725 .675 .851 1.008 1.151 1.283 1.406 1.52
 0.0 -.653 -.990 -1.281 -1.528 -1.7465 -1.932 -2.1 -2.24 -2.35
 0.0 .299 .531 .739 .929 1.1028 1.272 1.423 1.551 1.673
 0.0 -.191 -.4725 -.675 -.851 -1.008 -1.151 -1.283 -1.406 -1.52
-1.0

```

IPRT
 XWLE
 OJCARD
 XFUS
 XFUS
 XFUS
 FUSBY
 FUSBY
 FUSBY
 FUSAZ
 FUSAZ
 FUSAZ
 BC/PRINT
 KCARD
 REF
 XV
 XFUS10
 XFUS11
 MALPHA
 YVRTX1
 ZVRTX1
 GAM1
 YVRTX2
 ZVRTX2
 GAM2

Figure 25.- Input of program WDYBDY, second sample case, step 2.

VORTEX CALCULATION CONTROL
 N=CPT NVIX NVVIX NCPDUT NVLIN
 22 2 10 0 0

X=LE Y=740T
 14,000 0,000

J=DATA CARDS REQUIRED (NO=0, YES=1, 0)

OFFA	WING	BODY	PDD	V.FIN	H.TAIL	YY=SYM
J0	J1	J2	J3	J4	J5	J6
0	0	=3	0	0	0	=1

WING GEOM:	NWAF:	0	NWAFOR:	0			
BODY GEOM:	NBFS:	1	NBFSOR:	13	0	0	0
			NBFSOR:	30	0	0	0
PDD GEOM:	NP:	0	NPOR:	0			
V.FIN GEOM:	NV:	0	NVOR:	0			
H.TAIL GEOM:	NH:	0	NHOR:	0			

VEHICLE GEOMETRY DEFINITION
 REFERENCE AREA (J0, J1, 0) REFAR 1,00000

.. CONFIG ..

NFU	XFUS = FUSelage	X=STATIONS								
1	0,0000	,4200	,7000	2,1000	3,5000	4,9000	5,6000	6,3000	7,7000	8,4000
1	9,1000	10,5000	11,9000	12,6000	13,3000	14,7000	15,4000	16,8000	17,5000	18,2000
1	19,0000	19,6000	20,3000	21,0000	22,4000	23,1000	24,5000	25,9000	26,6000	28,0000

NFU	FUSRY = ELLIPTIC FUSELAGE	SEMI-MAJOR AXIS								
1	0,0000	,2675	,3010	,MMOR	1,2745	1,4168	1,7756	1,9222	2,1978	2,3258
1	2,4071	2,6721	2,8735	2,9653	3,0510	3,2033	3,2692	3,3777	3,4184	3,4481
1	3,4641	3,4563	3,4322	3,3970	3,3029	3,2476	3,1283	3,0090	2,9552	2,8846

NFU	FUSAZ = ELLIPTIC FUSELAGE	SEMI-MAJOR AXIS								
1	0,0000	,0992	,1505	,2938	,4248	,5189	,5912	,6407	,7326	,7752
1	,8157	,8907	,9578	,9884	1,0170	1,0678	1,0897	1,1259	1,1395	1,1494
1	1,1507	1,1521	1,1441	1,1323	1,1010	1,0825	1,0428	1,0030	,9851	,9615

ELLIPTIC BODY PANNING = NWAF=0, NBFS=1

.. GEOM ..

LINBC	THICK	PRINT	LCPA	LCPR	LCPC	ITMAX	ECTEST
0	0	=2	0	0	0	0	0,00000

K=DATA CARDS, ADDITIONAL CARDS FOR PANELING

REF	WING	BODY	V/A	V,FIN	H,TAIL	N/A
K0	K1	K2	K3	K4	K5	K6
1	0	1	0	0	0	-1

WING PANEL:	K=AF#	0	K=AFDR#	0
BODY PANEL:	K=US#	1	K=ADY#	9
			K=DRY#	11
				0
				0
				0

PANEL DIFFERENCE LENGTHS

REFAR	REFH	REFC	REFD	REFL	REFY	REFZ
12.567	0.000	0.000	3.464	0.000	16.800	0.000

VORTEX LOCATIONS AND BODY AXES

.. READVX ..

	XVB	YVB	ZVB	XVB	YVB	ZVB	XVB	YVB	ZVB	XVB	YVB	ZVB
	0.0000	2.0000	4.0000	6.0000	8.0000	10.0000	12.0000	14.0000	16.0000	18.0000		
	0.0000	.845A	1.39AA	1.85B5	2.2526	2.5917	2.886A	3.1272	3.3157	3.4196		
	0.0000	.2420	.4656	.6195	.7509	.8639	.9622	1.0424	1.1052	1.1466		

BODY PANEL CURVED POINT COORDINATES

.. BODY PAN ..

1 AND 3 INDICATE BODY PANEL LEADING-EDGE POINTS, 2 AND 4 INDICATE TRAILING-EDGE POINTS

PANEL	X	Y	Z	X	Y	Z	X	Y	Z	X	Y	Z
	1	2	3	2	3	3	4	4	4			
1	0.00000	0.00000	0.00000	3.00000	0.00000	0.00000	0.00000	0.00000	0.00000	3.00000	.1550A	.37439
2	0.00000	0.00000	0.00000	3.00000	.1550A	-.37439	0.00000	0.00000	0.00000	3.00000	.35855	-.35855
3	0.00000	0.00000	0.00000	3.00000	.35855	-.35855	0.00000	0.00000	0.00000	3.00000	.71086	-.29445
4	0.00000	0.00000	0.00000	3.00000	.71086	-.29445	0.00000	0.00000	0.00000	3.00000	1.13389	-.00000
5	0.00000	0.00000	0.00000	3.00000	1.13389	-.00000	0.00000	0.00000	0.00000	3.00000	.71086	.29445
6	0.00000	0.00000	0.00000	3.00000	.71086	.29445	0.00000	0.00000	0.00000	3.00000	.35855	.35855
7	0.00000	0.00000	0.00000	3.00000	.35855	.35855	0.00000	0.00000	0.00000	3.00000	.1550A	.37439
8	0.00000	0.00000	0.00000	3.00000	.1550A	.37439	0.00000	0.00000	0.00000	3.00000	.00000	.37794
9	3.00000	.00000	-.37794	6.00000	.00000	-.61949	3.00000	.1550A	-.37439	6.00000	.25419	-.61366
10	3.00000	.1550A	-.37439	6.00000	.25419	-.61366	3.00000	.35855	-.35855	6.00000	.58770	-.58770
11	3.00000	.35855	-.35855	6.00000	.58770	-.58770	3.00000	.71086	-.29445	6.00000	1.16516	-.48263
12	3.00000	.71086	-.29445	6.00000	1.16516	-.48263	3.00000	1.13389	.00000	6.00000	1.85851	.00000
13	3.00000	1.13389	.00000	6.00000	1.85851	.00000	3.00000	.71086	.29445	6.00000	1.16516	.48263
14	3.00000	.71086	.29445	6.00000	1.16516	.48263	3.00000	.35855	.35855	6.00000	.58770	.58770
15	3.00000	.35855	.35855	6.00000	.58770	.58770	3.00000	.1550A	.37439	6.00000	.25419	.61366
16	3.00000	.1550A	.37439	6.00000	.25419	.61366	3.00000	.00000	.37794	6.00000	.00000	.61949
17	6.00000	.00000	-.61949	9.00000	.00000	-.80291	6.00000	.25419	-.61366	9.00000	.31232	-.80230
18	6.00000	.25419	-.61366	9.00000	.31232	-.80230	6.00000	.58770	-.58770	9.00000	.76835	-.76835
19	6.00000	.58770	-.58770	9.00000	.76835	-.76835	6.00000	1.16516	-.48263	9.00000	1.52331	-.63090
20	6.00000	1.16516	-.48263	9.00000	1.52331	-.63090	6.00000	1.85851	.00000	9.00000	2.42974	.00000

Figure 26.- Continued.

21	6.00000	1.85451	.00000	9.00000	2.42974	.00000	6.00000	1.16514	.48263	9.00000	1.52331	.63098
22	6.00000	1.12516	.48263	9.00000	1.52331	.63098	6.00000	.58770	.48770	9.00000	.78835	.78835
23	6.00000	.58770	.48770	9.00000	.78835	.78835	6.00000	.25419	.61366	9.00000	.33232	.80230
24	6.00000	.25419	.61366	9.00000	.33232	.80230	6.00000	-.00000	.61949	9.00000	-.00000	.80991
25	9.00000	.00000	-.40991	12.00000	.00000	-.96217	9.00000	.33232	-.80230	12.00000	.39480	-.95313
26	9.00000	.33232	-.80230	12.00000	.39480	-.95313	9.00000	.76835	-.76835	12.00000	.91280	-.91280
27	9.00000	.76835	-.76835	12.00000	.91280	-.91280	9.00000	1.52331	-.63098	12.00000	1.80970	-.74960
28	9.00000	1.52331	-.63098	12.00000	1.80970	-.74960	9.00000	.00000	.00000	12.00000	2.88661	.00000
29	9.00000	2.42974	.00000	12.00000	2.88661	.00000	9.00000	1.52331	.63098	12.00000	1.80970	.74960
30	9.00000	1.52331	.63098	12.00000	1.80970	.74960	9.00000	.76835	.76835	12.00000	.91280	.91280
31	9.00000	.76835	.76835	12.00000	.91280	.91280	9.00000	.33232	.80230	12.00000	.39480	.95313
32	9.00000	.33232	.80230	12.00000	.39480	.95313	9.00000	.00000	.80991	12.00000	-.00000	.96217
33	12.00000	.00000	-.96217	15.00000	.00000	-1.07719	12.00000	.39480	-.95313	15.00000	.44199	-1.06706
34	12.00000	.39480	-.95313	15.00000	.44199	-1.06706	12.00000	.91280	-.91280	15.00000	1.02191	-1.02191
35	12.00000	.91280	-.91280	15.00000	1.02191	-1.02191	12.00000	1.80970	-.74960	15.00000	2.02600	-.83920
36	12.00000	1.80970	-.74960	15.00000	2.02600	-.83920	12.00000	2.88661	.00000	15.00000	3.23154	.00000
37	12.00000	2.88661	.00000	15.00000	3.23154	.00000	12.00000	1.80970	.74960	15.00000	2.02600	.83920
38	12.00000	1.80970	.74960	15.00000	2.02600	.83920	12.00000	.91280	.91280	15.00000	1.02191	1.02191
39	12.00000	.91280	.91280	15.00000	1.02191	1.02191	12.00000	.39480	.95313	15.00000	.44199	1.06706
40	12.00000	.39480	.95313	15.00000	.44199	1.06706	12.00000	-.00000	.96217	15.00000	-.00000	1.07719
41	15.00000	.00000	-1.07719	18.00000	.00000	-1.14657	15.00000	.44199	-1.06706	18.00000	.47046	-1.13580
42	15.00000	.44199	-1.06706	18.00000	.47046	-1.13580	15.00000	1.02191	-1.02191	18.00000	1.08773	-1.08773
43	15.00000	1.02191	-1.02191	18.00000	1.08773	-1.08773	15.00000	2.02600	-.83920	18.00000	2.15644	-.89324
44	15.00000	2.02600	-.83920	18.00000	2.15644	-.89324	15.00000	3.23154	.00000	18.00000	3.43961	.00000
45	15.00000	3.23154	.00000	18.00000	3.43961	.00000	15.00000	2.02600	.83920	18.00000	2.15644	.89324
46	15.00000	2.02600	.83920	18.00000	2.15644	.89324	15.00000	1.02191	1.02191	18.00000	1.08773	1.08773
47	15.00000	1.02191	1.02191	18.00000	1.08773	1.08773	15.00000	.44199	1.06706	18.00000	.47046	1.13580
48	15.00000	.44199	1.06706	18.00000	.47046	1.13580	15.00000	-.00000	1.07719	18.00000	-.00000	1.14657
49	18.00000	.00000	-1.14657	21.00000	.00000	-1.13230	18.00000	.47046	-1.13580	21.00000	.46461	-1.12166
50	18.00000	.47046	-1.13580	21.00000	.46461	-1.12166	18.00000	1.08773	-1.08773	21.00000	1.07420	-1.07420
51	18.00000	1.08773	-1.08773	21.00000	1.07420	-1.07420	18.00000	2.15644	-.89324	21.00000	2.12969	-.88215
52	18.00000	2.15644	-.89324	21.00000	2.12969	-.88215	18.00000	3.43961	.00000	21.00000	3.39700	.00000
53	18.00000	3.43961	.00000	21.00000	3.39700	.00000	18.00000	2.15644	.89324	21.00000	2.12969	.88215
54	18.00000	2.15644	.89324	21.00000	2.12969	.88215	18.00000	1.08773	1.08773	21.00000	1.07420	1.07420
55	18.00000	1.08773	1.08773	21.00000	1.07420	1.07420	18.00000	.47046	1.13580	21.00000	.46461	1.12166
56	18.00000	.47046	1.13580	21.00000	.46461	1.12166	18.00000	-.00000	1.14657	21.00000	-.00000	1.13230
57	21.00000	.00000	-1.13230	23.00000	.00000	-1.08514	21.00000	.46461	-1.12166	23.00000	.44526	-1.07495
58	21.00000	.46461	-1.12166	23.00000	.44526	-1.07495	21.00000	1.07420	-1.07420	23.00000	1.02946	-1.02946
59	21.00000	1.07420	-1.07420	23.00000	1.02946	-1.02946	21.00000	2.12969	-.88215	23.00000	2.04099	-.84540
60	21.00000	2.12969	-.88215	23.00000	2.04099	-.84540	21.00000	3.39700	.00000	23.00000	3.25550	.00000
61	21.00000	3.39700	.00000	23.00000	3.25550	.00000	21.00000	2.12969	.88215	23.00000	2.04099	.84540
62	21.00000	2.12969	.88215	23.00000	2.04099	.84540	21.00000	1.08773	1.07420	23.00000	1.02946	1.02946
63	21.00000	1.08773	1.07420	23.00000	1.02946	1.02946	21.00000	.46461	1.12166	23.00000	.44526	1.07495
64	21.00000	.46461	1.12166	23.00000	.44526	1.07495	21.00000	-.00000	1.13230	23.00000	-.00000	1.08514
65	23.00000	.00000	-1.08514	24.00000	.00000	-1.04564	23.00000	.44526	-1.13230	24.00000	.42905	-1.03581
66	23.00000	.44526	-1.07495	24.00000	.42905	-1.03581	23.00000	1.02946	-1.02946	24.00000	.99197	-.99197
67	23.00000	1.02946	-1.02946	24.00000	.99197	-.99197	23.00000	2.04099	-.84540	24.00000	1.96664	-.81461
68	23.00000	2.04099	-.84540	24.00000	1.96664	-.81461	23.00000	3.25550	.00000	24.00000	3.13682	.00000
69	23.00000	3.25550	.00000	24.00000	3.13682	.00000	23.00000	2.04099	.84540	24.00000	1.96664	.81461
70	23.00000	2.04099	.84540	24.00000	1.96664	.81461	23.00000	1.02946	1.02946	24.00000	.99197	.99197
71	23.00000	1.02946	1.02946	24.00000	.99197	.99197	23.00000	.44526	1.07495	24.00000	.42905	1.03581
72	23.00000	.44526	1.07495	24.00000	.42905	1.03581	23.00000	-.00000	1.08514	24.00000	-.00000	1.04564

Figure 26.- Continued.

73	24.40000	.00000	-1.04564	25.60000	.00000	-1.01153	24.40000	.42905	-1.03581	25.60000	.41505	-1.00202
74	24.40000	.42905	-1.03581	25.60000	.41505	-1.00202	24.40000	.99197	-.99197	25.60000	.95962	-.95962
75	24.40000	.99197	-.99197	25.60000	.95962	-.95962	24.40000	1.96644	-.81461	25.60000	1.90251	-.78804
76	24.40000	1.96644	-.81461	25.60000	1.90251	-.78804	24.40000	3.13692	.00000	25.60000	3.03456	.00000
77	24.40000	3.13692	.00000	25.60000	3.03456	.00000	24.40000	1.96644	.81461	25.60000	1.90251	.78804
78	24.40000	1.96644	.81461	25.60000	1.90251	.78804	24.40000	.99197	.99197	25.60000	.95962	.95962
79	24.40000	.99197	.99197	25.60000	.95962	.95962	24.40000	.42905	1.03581	25.60000	.41505	1.00202
80	24.40000	.42905	1.03581	25.60000	.41505	1.00202	24.40000	-.00000	1.04564	25.60000	-.00000	1.01153

BODY PANEL CENTROID POINT COORDINATES

POINT	X	Y	Z
	CP	CP	CP
1	2.00000	.05169	-.25078
2	2.00000	.17121	-.24431
3	2.00000	.35447	-.21767
4	2.00000	.61492	-.09815
5	2.00000	.61492	.09815
6	2.00000	.55447	.21767
7	2.00000	.17121	.24431
8	2.00000	.05169	.25078
9	4.62108	.10432	-.50607
10	4.62108	.34550	-.49303
11	4.62108	.71936	-.43925
12	4.62107	1.24090	-.19807
13	4.62107	1.24090	.19807
14	4.62108	.71936	.43925
15	4.62108	.34550	.49303
16	4.62108	.10432	.50607
17	7.56661	.14750	-.71555
18	7.56661	.48851	-.69710
19	7.56661	1.01711	-.62107
20	7.56660	1.75050	-.28005
21	7.56660	1.75050	.28005
22	7.56661	1.01711	.62107
23	7.56661	.48851	.69710
24	7.56661	.14750	.71555
25	10.54296	.18223	-.88405
26	10.54296	.60355	-.86126
27	10.54297	1.25463	-.76732
28	10.54297	2.16767	-.34599
29	10.54297	2.16767	.34599
30	10.54297	1.25463	.76732
31	10.54296	.60355	.86126
32	10.54296	.18223	.88405
33	13.52820	.20942	-1.01596
34	13.52820	.69361	-.98977
35	13.52819	1.44013	-.84161
36	13.52818	2.40110	-.49762
37	13.52818	2.40110	.49762
38	13.52819	1.44013	.84161
39	13.52820	.69361	.98977
40	13.52820	.20942	1.01596

Figure 26.- Continued.

41	16.51560	.22819	-1.10701
42	16.51560	.75577	-1.07807
43	16.51560	1.57154	-.96083
44	16.51559	2.71429	-.43325
45	16.51559	2.71429	.43325
46	16.51560	1.57154	.96083
47	16.51560	.75577	1.07807
48	16.51560	.22819	1.10701
49	19.49687	.23377	-1.13410
50	19.49687	.77026	-1.10486
51	19.49688	1.61204	-.96434
52	19.49689	2.78973	-.44385
53	19.49689	2.78973	.44385
54	19.49688	1.61204	.96434
55	19.49687	.77026	1.10486
56	19.49687	.23377	1.13410
57	21.99291	.22750	-1.10368
58	21.99291	.75349	-1.07523
59	21.99291	1.56882	-.95795
60	21.99291	2.70620	-.43195
61	21.99291	2.70620	.43195
62	21.99291	1.56882	.95795
63	21.99291	.75349	1.07523
64	21.99291	.22750	1.10368
65	23.69567	.21860	-1.06650
66	23.69567	.72402	-1.03117
67	23.69567	1.50744	-.92047
68	23.69567	2.60029	-.41505
69	23.69567	2.60029	.41505
70	23.69567	1.50744	.92047
71	23.69567	.72402	1.03117
72	23.69567	.21860	1.06650
73	24.99668	.21104	-1.02384
74	24.99668	.69899	-.99745
75	24.99669	1.45532	-.88864
76	24.99669	2.51036	-.40070
77	24.99669	2.51036	.40070
78	24.99669	1.45532	.88864
79	24.99668	.69899	.99745
80	24.99668	.21104	1.02384

BODY PANEL AREAS AND INCLINATION ANGLES

PANEL	AREA	DELTA RAD	THETA RAD	DELTA DEG	THETA DEG
1	.23452	.12529	-.5.11870	7.17849	-178.688
2	.30865	.12773	-.1.06389	7.31861	-175.548
3	.54231	.13810	-.2.96162	7.91231	-169.688
4	.79094	.21266	-.2.55353	12.18008	-145.166
5	.79094	.21266	-.6.08297	12.18008	-30.840
6	.54231	.13810	-.1.74994	7.91231	-10.312

Figure 26.- Continued.

7	.30865	.12773	-.07770	7.31841	-4.452
8	.23452	.12529	-.07290	7.17840	-1.312
9	.81605	.08832	-3.11870	4.60200	-178.688
10	.81603	.08190	-3.06389	4.69239	-175.548
11	1.42314	.08859	-2.96161	5.07577	-169.688
12	2.05964	.13713	-2.53351	7.85675	-145.160
13	2.05964	.13713	-.60808	7.85675	-34.840
14	1.42314	.08859	-.17998	5.07577	-10.312
15	.81063	.08190	-.07770	4.69239	-4.452
16	.61605	.08032	-.02290	4.60200	-1.312
17	.88177	.06337	-3.11869	3.63109	-178.688
18	1.16022	.06462	-3.06389	4.70252	-175.548
19	2.03642	.06991	-2.96160	4.00557	-169.687
20	2.94107	.10836	-2.53349	6.20850	-145.158
21	2.94107	.10836	-.60810	6.20859	-34.842
22	2.03642	.06991	-.17999	4.00557	-10.313
23	1.16022	.06462	-.07771	3.70252	-4.452
24	.88177	.06337	-.02290	3.63109	-1.312
25	1.09238	.05070	-3.11869	2.90465	-178.688
26	1.43729	.05169	-3.06389	2.96189	-175.548
27	2.52243	.05593	-2.96160	3.20478	-169.687
28	3.63850	.08678	-2.53350	4.97216	-145.159
29	3.63850	.08678	-.60810	4.97216	-34.841
30	2.52243	.05593	-.17999	3.20478	-10.313
31	1.43729	.05169	-.07770	2.96180	-4.452
32	1.09238	.05070	-.02290	2.90465	-1.312
33	1.25644	.03831	-3.11869	2.19405	-178.688
34	1.65312	.03906	-3.06389	2.23818	-175.548
35	2.90091	.04227	-2.96160	2.42164	-169.687
36	4.18047	.06560	-2.53349	3.75857	-145.158
37	4.18047	.06560	-.60810	3.75857	-34.842
38	2.90091	.04227	-.17999	2.42164	-10.313
39	1.65312	.03906	-.07771	2.23818	-4.452
40	1.25644	.03831	-.02290	2.19405	-1.312
41	1.56941	.02312	-3.11869	1.32498	-178.688
42	1.80171	.02357	-3.06389	1.35068	-175.548
43	3.16135	.02551	-2.96159	1.46147	-169.687
44	4.55203	.03961	-2.53347	2.26947	-145.157
45	4.55203	.03961	-.60812	2.26947	-34.843
46	3.16135	.02551	-.18000	1.46146	-10.313
47	1.80171	.02357	-.07771	1.35068	-4.452
48	1.56941	.02312	-.02290	1.32498	-1.312
49	1.40299	.00476	-3.11869	-.27248	-178.688
50	1.84548	.00885	-3.06389	-.27779	-175.548
51	3.25473	.00524	-2.96160	-.30034	-169.687
52	4.66146	.00813	-2.53348	-.46583	-145.158
53	4.66146	.00813	-.60811	-.46583	-34.842
54	3.25473	.00524	-.18000	-.30034	-10.313
55	1.84548	.00485	-.07771	-.27779	-4.452
56	1.40299	.00476	-.02290	-.27248	-1.312
57	.91036	.02357	-3.11869	-1.35065	-178.688
58	1.19775	.02403	-3.06389	-1.37700	-175.548

Figure 26.- Continued.

59	2.10167	-.02601	-2.96161	-1.49909	-169.687
60	3.02636	-.04040	-2.51350	-2.31449	-145.159
61	5.02636	-.04040	-.00000	-2.31449	-30.841
62	2.10167	-.02601	-.17449	-1.49909	-10.313
63	1.19775	-.02003	-.07770	-1.37700	-4.452
64	.91036	-.02357	-.02290	-1.35035	-1.312
65	.61242	-.02429	-3.11869	-1.61602	-178.688
66	.80576	-.02476	-3.06389	-1.64000	-175.548
67	1.41365	-.03113	-2.96160	-1.78371	-169.687
68	2.03629	-.04037	-2.53348	-2.77161	-145.159
69	2.03629	-.04037	-.60811	-2.77161	-40.802
70	1.41365	-.03113	-.18000	-1.78371	-10.313
71	.80576	-.02476	-.07771	-1.64000	-4.452
72	.61242	-.02429	-.02290	-1.61602	-1.312
73	.50680	-.02441	-3.11869	-1.62762	-178.688
74	.66679	-.02497	-3.06388	-1.65967	-175.548
75	1.17000	-.03134	-2.96159	-1.79569	-169.687
76	1.64508	-.04066	-2.53347	-2.78778	-145.157
77	1.64508	-.04066	-.60812	-2.78778	-34.843
78	1.17000	-.03134	-.18000	-1.79569	-10.313
79	.66679	-.02497	-.07771	-1.65967	-4.452
80	.50680	-.02441	-.02290	-1.62762	-1.312

END GEOM , TIME= .228 DT= .228

AERODYNAMIC VELOCITY MATRIX COMPUTATION

** VELEMP **

PARTITION = 1

N4ING= 0 NRODY= 80 NCPTR 0 NSEGE 0
INFLUENCE OF BODY ON BODY

END BODYVEL, TIME= 5.3050 DT= 5.0770 NPART= 1

NBRLINK= 10 NBRLINK= 1

END VELEMP, TIME= 5.3630 DT= 5.1350

BEGIN A NEW CASE

** BODYDY **

END DIAGN, TIME= 5.4350 DT= .0650

THE ITERATION CONVERGED AFTER 11 ITERATIONS WITH A TEST CRITERION OF .0010000

THE SOLUTION AT THE PREVIOUS ITERATION IS

GR(N), N=1, 80									
.60815	.60675	.60245	.62966	-.24230	-.35477	-.57133	-.37538	.77418	.72887
.70514	.73049	-.46254	-.54706	-.56437	-.59123	.67301	.67160	.74809	.77488
-.55746	-.61343	-.56460	-.57469	.69438	.69136	.69179	.79600	-.61080	-.59570

Figure 26.- Continued.

-.60161	-.60523	.69417	.49731	.49144	.78268	-.64319	-.62337	-.63162	-.63179
.70879	.70467	.69999	.79237	-.70788	-.66863	-.67059	-.66967	.72405	.70972
.70103	.80192	-.83150	-.75263	-.75308	-.75563	.80566	.79111	.76535	.76222
-.89037	-.81893	-.81511	-.81820	.73959	.74769	.85206	.90431	-.90644	-.85580
-.79820	-.79912	.82412	.80987	.78823	.81892	-.94559	-.84463	-.85797	-.86823

THE SOLUTION AT THE PRESENT ITERATION IS
GR(N), N=1, R0

.60815	.60675	.60245	.62066	-.24230	-.35677	-.37133	-.37538	.77414	.72887
.70514	.73049	-.46254	-.54706	-.56037	-.59123	.67301	.67160	.74809	.77486
-.55746	-.61343	-.56960	-.57469	.49439	.49136	.69179	.79600	-.61080	-.39570
-.60161	-.60523	.69517	.69731	.69144	.78268	-.64319	-.62337	-.63162	-.63179
.70879	.70467	.69999	.79237	-.70788	-.66863	-.67059	-.66967	.72405	.70972
.70103	.80192	-.83150	-.75263	-.75308	-.75563	.80566	.79111	.76535	.76222
-.89037	-.81893	-.81511	-.81820	.73959	.74769	.85206	.90431	-.90644	-.85580
-.79820	-.79912	.82312	.80987	.78823	.81892	-.94559	-.84463	-.85797	-.86823

VORTEX LOCATION AND STRENGTH

** ELEVAT **

I= 1	YVRTX=	0.0000	.6530	.9900	1.2810	1.5280	1.7465	1.9320	2.1000	2.2400	2.3500
I= 1	ZVRTX=	0.0000	.2990	.5310	.7390	.9290	1.1028	1.2720	1.4230	1.5510	1.6730
I= 1	GX=	0.0000	.1910	.4725	.6750	.8510	1.0080	1.1510	1.2830	1.4060	1.5200
I= 2	YVRTX=	0.0000	-.6530	-.9900	-1.2810	-1.5280	-1.7465	-1.9320	-2.1000	-2.2400	-2.3500
I= 2	ZVRTX=	0.0000	.2990	.5310	.7390	.9290	1.1028	1.2720	1.4230	1.5510	1.6730
I= 2	GX=	0.0000	-.1910	-.4725	-.6750	-.8510	-1.0080	-1.1510	-1.2830	-1.4060	-1.5200

VORTEX INTERPOLATION TABLE

VORTEX		1				
STAT	XV	YVRTX	ZVRTX	RY	47	GAM/V
1	0.000	0.0000	0.0000	0.0000	0.0000	0.0000
2	2.000	.6530	.2990	.8458	.2820	.1910
3	4.000	.9900	.5310	1.3949	.4656	.4725
4	6.000	1.2810	.7390	1.8585	.6195	.6750
5	8.000	1.5280	.9290	2.2526	.7509	.8510
6	10.000	1.7465	1.1028	2.5917	.8439	1.0080
7	12.000	1.9320	1.2720	2.8866	.9072	1.1510
8	14.000	2.1000	1.4230	3.1272	1.0024	1.2830
9	16.000	2.2400	1.5510	3.3157	1.1052	1.4060
10	18.000	2.3500	1.6730	3.4396	1.1466	1.5200

Figure 26.- Continued.

VORTEX 2

STAT	XV	YVRTX	ZVRTX	HY	AZ	GAM/V
1	0.000	0.0000	0.0000	0.0000	0.0000	0.0000
2	2.000	-.6530	.2490	.845A	.2470	-.1910
3	4.000	-.9900	.5310	1.39AA	.4656	-.4725
4	6.000	-1.2810	.7190	1.85A5	.6195	-.6750
5	8.000	-1.5260	.9290	2.252A	.7509	-.8510
6	10.000	-1.7465	1.102A	2.5917	.8639	-1.0080
7	12.000	-1.9320	1.2720	2.886A	.9622	-1.1510
8	14.000	-2.1000	1.4230	3.1272	1.0474	-1.2830
9	16.000	-2.2400	1.5510	3.3157	1.1052	-1.4060
10	18.000	-2.3500	1.6740	3.4396	1.1466	-1.5200

VELOCITY ON BODY

MACH= 1.700 ALPHA= 10.000 PHIR= 0.000

** SOLVE **

PANEL NO.	SOURCE STRENGTH	AXIAL VELOCITY	LATERAL VELOCITY	VERTICAL VELOCITY	NORMAL VELOCITY	LAT. VORTEX VELOCITY	VFD. VORTEX VELOCITY
1	.60215	-.11784	.16037E-01	-.28250	.29530	-.21087E-03	-.15168E-04
2	.60675	-.11969	.55979E-01	-.28089	.29717	-.73365E-03	-.64852E-04
3	.60245	-.12713	.12055	-.27287	.3047A	-.18A11E-02	-.369A1E-03
4	.62066	-.17190	.34530	-.14717	.34717	-.9219E-02	-.736A6E-02
5	-.24230	-.26758E-02	-.7R232E-01	.1491A	.68542E-01	.13435	-.87685E-01
6	-.35677	-.11105E-01	-.64029E-01	-.21314E-01	-.33651E-01	.10521	-.22110E-01
7	-.37153	.947A7E-02	-.20A29E-01	-.43240E-01	-.46262E-01	.23587E-01	-.23402E-02
8	-.3753A	.90632E-02	-.89A27E-02	-.4A241E-01	-.49180E-01	.60384E-02	-.400A1E-03
9	.7741A	-.49425E-01	.27541E-01	-.24829	.25206	-.27A52E-03	-.19886E-04
10	.726A7	-.72574E-01	.8278A7E-01	-.24231	.25311	-.9610A8E-03	-.914A3E-04
11	.70514	-.A40A7E-01	.14475	-.22A65	.25730	-.24535E-02	-.4A204E-03
12	.73049	-.116A5	.3A67A	-.A4115E-01	.275A0	-.11940E-01	-.93151E-02
13	-.4A254	.2A511E-01	-.1A601	.12620	-.65A32E-02	.13497	-.89632E-01
14	-.5470A	.23679E-01	-.99542E-01	-.A4490E-01	-.83044E-01	.27169	-.57753E-01
15	-.5A637	.22294E-01	-.5A889E-01	-.A6306E-01	-.91481E-01	.53A79E-01	-.53230E-02
16	-.59123	.11527E-01	-.1A945E-01	-.92995E-01	-.94028E-01	.13175E-01	-.9A549E-03
17	.67301	-.70611E-01	.87470E-02	-.23148	.23562	-.30468E-03	-.21911E-04
18	.A7160	-.A4445E-01	.24471E-01	-.23122	.23636	-.105A6E-02	-.10074E-03
19	.70809	-.416A1E-01	.11979	-.21898	.23922	-.269A3E-02	-.53007E-03
20	.774A6	-.89709E-01	.370A9	-.34114E-01	.24819	-.12995E-01	-.10132E-01
21	-.55746	.31494E-01	-.22567	.11815	-.3517A7E-01	.13454	-.90011E-01
22	-.61343	.118A4E-01	-.917A7E-01	-.A6191E-01	-.10163	.35000	-.74316E-01
23	-.5A9A0	.30961E-01	-.20133E-01	-.10615	-.10917	.A9584E-01	-.69921E-02
24	-.574A9	.31223E-01	-.65845E-02	-.10900	-.110A8	.17166E-01	-.12591E-02
25	.6943A	-.4A635E-01	.10372E-01	-.220A2	.2232A	-.33A39E-03	-.24191E-04
26	.69136	-.5302A7E-01	.555A3E-01	-.2170A	.2237A	-.11A85E-02	-.11119E-03
27	.69179	-.54942E-01	.10A12	-.20726	.22563	-.29757E-02	-.5A452E-03
28	.79A00	-.59261E-01	.35246	-.26411E-01	.22734	-.14244E-01	-.11100E-01
29	-.610A0	.26301E-01	-.24214	.10210	-.56628E-01	.13957	-.93A26E-01
30	-.5957A	.30622E-01	-.912A9E-01	-.99251E-01	.35000	-.11552	-.A1963E-01
31	-.60161	.2A979E-01	-.4A534E-01	-.11752	-.12201	.22236E-01	-.A2528E-02
32	-.60523	.2143A7E-01	-.1A269E-01	-.12221	-.1234A	.20340E-01	-.14415E-02

Figure 26.- Continued.

33	.69517	-.39175E-01	.14733E-01	-.20956	.21119	-.37751E-03	-.27147E-04
34	.69731	-.37750E-01	.47779E-01	-.20705	.21105	-.13111E-02	-.12475E-03
35	.69166	-.43159E-01	.11499	-.19321	.21230	-.33364E-02	-.65531E-03
36	.74268	-.44979E-01	.34976	-.54074E-02	.20677	-.15889E-01	-.12378E-01
37	-.64319	.30170E-01	-.26128	.89072E-01	-.77656E-01	.14440	-.10019
38	-.62337	.32003E-01	-.10279	-.11120	-.12908	.35000	-.84902E-01
39	-.63162	.27081E-01	-.45964E-01	-.14040	-.13453	.93842E-01	-.93865E-02
40	-.66179	.26872E-01	-.13736E-01	-.14055	-.13576	.23403E-01	-.17147E-02
41	.70879	-.20666E-01	.12106E-01	-.19567	.19632	-.43398E-03	-.31208E-04
42	.70667	-.23565E-01	.50166E-01	-.19247	.19629	-.15071E-02	-.14339E-03
43	.69990	-.28498E-01	.10973	-.17848	.19590	-.38431E-02	-.75282E-03
44	.79237	-.19270E-01	.34912	-.22758E-01	.18140	-.18192E-01	-.14168E-01
45	-.70788	.29386E-01	-.29248	.78930E-01	-.10341	.16369	-.11091
46	-.66863	.34123E-01	-.99607E-01	-.12910	-.14567	.35000	-.80639E-01
47	-.67059	.30967E-01	-.47305E-01	-.14594	-.14986	.10323	-.10276E-01
48	-.66967	.31067E-01	-.14531E-01	-.14982	-.15079	.26073E-01	-.19075E-02
49	.72405	.10358E-01	-.17563E-01	-.16851	-.16892	0.	0.
50	.70972	.18017E-03	.58809E-01	-.16429	.16835	0.	0.
51	.70104	-.27017E-02	.10653	-.14903	.16568	0.	0.
52	.80192	.36156E-01	.35251	.81845E-01	.13451	0.	0.
53	-.83150	.24808E-01	-.34667	.57674E-01	-.15052	0.	0.
54	-.75263	.44304E-01	-.10389	-.16023	-.17600	0.	0.
55	-.75308	.40954E-01	-.54426E-01	-.17440	-.17790	0.	0.
56	-.75563	.39542E-01	-.15980E-01	-.17415	-.17828	0.	0.
57	.80566	.32240E-01	.35015E-01	-.14887	.15035	0.	0.
58	.79111	.34623E-01	.80856E-01	-.14277	.14941	0.	0.
59	.76535	.28214E-01	.12924	-.12355	.14518	0.	0.
60	.76222	.54103E-01	.31738	.98433E-01	.10263	0.	0.
61	-.89037	.23917E-01	-.37223	.35782E-01	-.18217	0.	0.
62	-.81893	.34415E-01	-.12483	-.17788	-.19659	0.	0.
63	-.81511	.37500E-01	-.54430E-01	-.19407	-.19674	0.	0.
64	-.81820	.42946E-01	-.21014E-01	-.19738	-.19676	0.	0.
65	.75959	.43137E-01	.13606E-01	-.14433	.14576	0.	0.
66	.74769	.38085E-01	.31969E-01	-.14164	.14473	0.	0.
67	.85206	.56250E-01	.17220	-.10936	.14011	0.	0.
68	.80431	.42808E-01	.33927	.12314	.94731E-01	0.	0.
69	-.96644	.27204E-02	-.39092	.40223E-01	-.18997	0.	0.
70	-.85580	.21285E-01	-.13728	-.18051	-.20141	0.	0.
71	-.79820	.32517E-01	-.51720E-01	-.19898	-.20137	0.	0.
72	-.79912	.24432E-01	-.17669E-01	-.20172	-.20131	0.	0.
73	.82312	.37525E-01	.20165E-01	-.14413	.14556	0.	0.
74	.80987	.52087E-01	.57851E-01	-.13901	.14453	0.	0.
75	.78823	.74790E-01	.11422	-.11910	.13990	0.	0.
76	.81892	.41946E-01	.35553	.14077	.94450E-01	0.	0.
77	-.94549	-.57881E-02	-.41097	.54350E-01	-.19025	0.	0.
78	-.84463	-.41409E-02	-.12342	-.18244	-.20162	0.	0.
79	-.85797	.15042E-01	-.45874E-01	-.19913	-.20157	0.	0.
80	-.86823	.22596E-01	-.80174E-02	-.20210	-.20150	0.	0.

Figure 26.- Continued.

LRC 3/1 ELLIPTIC WING/BODY MISSILE CONFIGURATION - NOSE VORTICITY
 ELLIPTIC BODY PANELING - KRAO=0, KFORV=1

INTEGRATION OF THE PRESSURE DISTRIBUTION
 ON THE BODY

•• FORMUM ••

MACH = 1.7000 ALPHAC= 10.0000 PWTOR 0.0000

POINT	X	Y	Z	THETP	CP	CX	CY	CZ	C _V	CLN	CLL
1	2.00000	.05169	-.25078	281.64720	.27900	.00819	-.00149	.06499	.95906	-.02161	-.00209
2	2.00000	.17121	-.24431	305.02186	.28070	.01104	-.00667	.08567	1.26526	-.09683	-.01304
3	2.00000	.35047	-.21767	328.59115	.28509	.02128	-.02741	.15066	2.22517	-.39812	-.00774
4	2.00000	.61492	-.09815	350.93129	.26536	.04430	-.11720	.16838	2.48774	-1.70736	-.00204
5	2.00000	.61492	.09815	9.06871	-.01818	-.00303	.00803	.01154	.17044	.11497	-.00631
6	2.00000	.35047	.21767	31.40884	-.01042	-.00078	.00100	.00551	.08131	.01455	-.00174
7	2.00000	.17121	.24431	54.97814	-.00503	-.00020	.00012	.00153	.02263	.00173	-.00023
8	2.00000	.05169	.25078	78.35280	-.00324	-.00010	.00002	.00076	.01176	.00025	-.00004
9	4.62106	.10432	-.50607	281.64720	.13039	.00644	-.00183	.08004	.97159	-.02165	-.00742
10	4.62106	.34550	-.49303	305.02186	.17489	.01160	-.01097	.14087	1.70990	-.12457	-.00326
11	4.62106	.71936	-.43925	328.59112	.18609	.02343	-.04722	.25954	3.15059	-.55427	-.16596
12	4.62107	1.24090	-.19807	350.93124	.11943	.03362	-.11921	.19990	2.42901	-1.65365	-.22060
13	4.62107	1.24090	.19807	9.06877	-.06978	-.01965	.08133	.11685	1.40917	.96617	-.12889
14	4.62108	.71936	.43925	31.40884	-.04759	-.00599	.01208	.06637	.80571	.14277	-.04244
15	4.62108	.34550	.49303	54.97815	-.02068	-.00137	.00130	.01666	.29218	.01532	-.00512
16	4.62108	.10432	.50607	78.35281	.00093	.00003	-.00001	.00057	.00001	-.00016	-.00005
17	7.56661	.14750	-.71555	281.64719	.18039	.01007	-.00363	.15870	1.45815	-.03207	-.02081
18	7.56661	.48851	-.69710	305.02184	.17489	.01310	-.01572	.20187	1.85085	-.13873	-.08786
19	7.56661	1.01711	-.62107	328.59108	.10136	.01442	-.03686	.20257	1.86104	-.32568	-.18315
20	7.56660	1.75450	-.28005	350.93114	.05610	.01784	-.09371	.13462	1.23799	-.83903	-.20995
21	7.56660	1.75450	.28005	9.06886	-.07716	-.02454	.12889	.18516	1.70274	1.14700	-.28876
22	7.56661	1.01711	.62107	31.40893	-.05810	-.00826	.02113	.11612	1.06707	.18669	-.10499
23	7.56661	.48851	.69710	54.97816	-.03687	-.00276	.00331	.04256	.39101	.02925	-.01848
24	7.56661	.14750	.71555	78.35281	-.03550	-.00198	.00072	.03123	.28695	.00631	-.00409
25	10.54296	.18223	-.88405	281.64719	.12751	.00706	-.00319	.13908	.86397	-.01864	-.02253
26	10.54296	.60355	-.86126	305.02185	.13894	.01032	-.01548	.19803	1.23519	-.09064	-.10667
27	10.54297	1.25663	-.76732	328.59109	.13496	.01903	-.06085	.33441	2.07784	-.35682	-.37354
28	10.54297	2.16767	-.54599	350.93117	.10152	.00332	-.02178	.03128	1.9459	-.12906	-.06028
29	10.54297	2.16767	.54599	9.06883	-.06288	-.01983	.13021	.18708	1.16388	.77175	-.36043
30	10.54297	1.25663	.76732	31.40892	-.09134	-.01288	.04118	.22632	1.40621	.24148	-.25280
31	10.54298	.60355	.86126	54.97816	-.02675	-.00199	.00298	.03827	.23777	.01745	-.02053
32	10.54298	.18223	.88405	78.35281	-.01488	-.00082	.00037	.01623	.10081	.00218	-.00263
33	13.52820	.20442	-1.01596	281.64719	.11238	.00541	-.00323	.14109	.45601	-.00944	-.02626
34	13.52820	.69361	-.99977	305.02184	.10721	.00692	-.01375	.17656	.57083	-.04018	-.10886
35	13.52819	1.44413	-.88181	328.59108	.10771	.01370	-.05588	.30712	.99320	-.16378	-.39424
36	13.52818	2.49110	-.59782	350.93115	-.01878	-.00515	.04476	.06430	-1.20834	.13363	.14230
37	13.52818	2.49110	.59782	9.06886	-.06605	-.01810	.15741	.22614	.73269	.06994	-.50075
38	13.52819	1.44413	.88181	31.40893	-.09052	-.01110	.04697	.25812	.83473	.13765	-.35134
39	13.52820	.69361	.99977	54.97816	-.02682	-.00173	.00344	.04417	.14281	.01005	-.02723
40	13.52820	.20442	1.01596	78.35281	-.02454	-.00118	.00071	.03080	.09947	.00206	-.00573
41	16.51560	.22819	-1.10701	281.64719	.07340	.00232	-.00230	.10046	.02600	-.00012	-.02038
42	16.51560	.75477	-1.07847	305.02183	.07725	.00328	-.01080	.13872	.03591	-.00659	-.09319

Figure 26.- Continued.

43	1A,51560	1,57354	-.960A3	32A,59103	.07A29	.006A1	-.04430	.24343	.06317	-.00267	-.34049
44	1A,51559	2,71429	-.43325	350,93104	-.07101	-.012A0	.1A453	-.2A50A	-.0A9A5	.01774	.61956
45	1A,51559	2,71429	.43325	9,0A896	-.0A223	-.01122	.16171	.23230	.0A121	.01554	-.50046
4A	1A,51560	1,57354	.9A0A3	31,40A97	-.09515	-.00767	.053A4	.295A8	.07677	.00324	-.413A1
47	1A,51560	.75577	1,07A47	54,97A17	-.03444	-.00146	.00480	.061A7	.01597	.00026	-.00143
48	1A,51560	.22819	1,10701	7A,352A1	-.031A5	-.00101	.00100	.04360	.0112A	.00005	-.00A84
49	19,496A7	.25377	-1,13410	2A1,64719	.00937	-.00006	-.00030	.01315	-.0353A	.00000	-.00273
50	19,496A7	.77426	-1,10A86	30A,02184	-.02A7A	-.00024	-.00384	.0492A	-.1326A	.0101A	-.03302
51	19,496A8	1,41204	-.9A434	32A,5910A	.02392	-.00041	-.013A7	.07621	-.20512	.03A74	-.10920
52	19,496A9	2,7A073	-.403A5	350,93110	-.19561	.00741	.52092	-.7A434	2,014A9	-1,3A027	1,84971
53	19,496A9	2,7A073	.403A5	9,0A890	-.1A75A	.00635	.44627	.64119	-1,72615	-1,1A589	-1,5A4A3
54	19,496A6	1,61204	.0A434	31,40A95	-.06657	.00113	.03860	.21212	-.57094	-.10227	-.303A5
55	19,496A7	.77426	1,10A86	54,97A1A	-.05299	.00047	.00759	.09751	-.26246	-.02011	-.06711
56	19,496A7	.25377	1,13410	7A,352A1	-.007A2	.00032	.00154	.06707	-.18052	-.00407	-.01394
57	21,99291	.22750	-1,1036A	2A1,64720	-.03529	.00076	.00074	-.03211	.16539	-.00365	.00049
58	21,99291	.75349	-1,07523	30A,021A5	-.04517	.00130	.00420	-.05393	.278A4	-.020A2	.00012
59	21,99291	1,56A82	-.95795	32A,59110	-.04397	.00240	.01654	-.090A9	.469A9	-.00211	.12675
60	21,99291	2,70020	-.43195	350,93110	-.210A1	.02576	.36418	-.52319	2,70533	-1,82143	1,25854
61	21,99291	2,70020	.43195	9,0A8A1	-.17270	.02111	.29816	.428A2	-2,216A8	-1,49222	-1,03107
62	21,99291	1,56A82	.95795	31,40A91	-.05231	.00286	.019A7	.10813	-.55A75	-.0976A	-.1507A
63	21,99291	.75349	1,07523	54,97A15	-.0A6A1	.00135	.00435	.055A8	-.2A8A7	-.0215A	-.03743
64	21,99291	.22750	1,1036A	7A,352A1	-.05325	.00114	.00111	.0A845	-.25033	-.00550	-.009A0
65	23,695A7	.21A60	-1,06050	2A1,64719	-.05535	.00096	-.00078	-.033A7	.23257	-.00514	.00658
66	23,695A7	.72402	-1,03317	30A,02184	-.04A69	.00108	-.00292	-.03749	.25741	-.01935	.02413
67	23,695A7	1,50744	-.92047	32A,59105	-.10794	.00075	.02731	-.15007	1,03043	-.1A114	.20108
68	23,695A7	2,60029	-.41505	350,93110	-.21421	.02109	.24892	-.3575A	2,45702	-1,66161	.82651
69	23,695A7	2,60029	.41505	9,0A890	-.15303	.01507	.177A3	.25546	-1,75529	-1,1A705	-.59045
70	23,695A7	1,50744	.92047	31,40A94	-.03043	.00134	.00770	.04231	-.29009	-.05107	-.056A9
71	23,695A7	.72402	1,03317	54,97A17	-.03722	.00086	.00233	.02989	-.20520	-.01542	-.01923
72	23,695A7	.21A60	1,06050	7A,352A1	-.01939	.00033	.00027	.01187	-.08147	-.00180	-.00231
73	24,996A8	.21104	-1,023A4	2A1,64719	-.04490	.00065	.00052	-.02274	.1A575	-.00413	.00427
74	24,996A8	.69899	-.99745	30A,021A4	-.07521	.00145	.00389	-.0499A	.40A21	-.03088	.031A5
75	24,996A9	1,45532	-.8A8A4	32A,59103	-.12541	.00460	.02626	-.1442A	1,17A57	-.20A52	.1A665
76	24,996A9	2,51036	-.40070	350,93104	-.2251A	.01A45	.21651	-.31103	2,54199	-1,72A3A	.69A03
77	24,996A9	2,5103A	.40070	9,06A96	-.15733	.01289	.15129	.21733	-1,77623	-1,20771	-.48496
78	24,996A9	1,45532	.8A8A4	31,40A97	.02117	-.000A6	-.00489	-.0268A	.21949	.03A85	.03478
79	24,996A8	.69899	.99745	54,97A17	-.00245	.00005	.00013	-.00163	-.01329	-.00101	-.00101
80	24,996A8	.21104	1,023A4	7A,352A1	-.01555	.00022	.00018	.00787	-.06A31	-.00143	-.00148

TOTAL COEFFICIENTS

ON THE BODY

PEFA#	12,567A	WFFD#	3,4641	REFLE	1,0000
XM #	16,8000	ZM #	0,0000		
CACHE	1,70000				
ALPHA#	10,00000	ALPHA#	10,00000		
PHIR#	0,00000	META#	0,00000		
CX#	.04322				

Figure 26.- Continued.

CV= 0.00000
 CZ= .85386
 CM= 1.94833
 CLN= 0.00000
 CLL= 0.00000
 XCP= 8.89360

FOLLOWING ARE IN WIND AXIS SYSTEM

CL= .85388
 CV= 0.00000
 CZ= .19083
 CM= 1.94883
 CNYA= 0.00000

LPC 3/1 ELLIPTIC WING/BODY MISSILE CONFIGURATION - NOISE VORTICITY
 ELLIPTIC BODY PANELING - KHA0=9, KFORX=11

INTEGRATION OF THE PRESSURE DISTRIBUTION

** FORMOM **

ON THE BODY FROM XSTART= 0.0000 TO XBLE= 18.0000

MACH = 1.7000 ALPHAC= 10.0000 PHIR= 0.0000

POINT	X	Y	Z	THETP	CP	CX	CV	CZ	CM	CLN	CLL
1	2.00000	.05169	-.25078	281.64720	.27940	.00819	-.00149	.06499	.95946	-.02161	-.00299
2	2.00000	.17121	-.24431	305.02186	.28070	.01104	-.00667	.08567	1.26526	-.29683	-.01304
3	2.00000	.35447	-.21767	328.59115	.28509	.02128	-.02741	.15066	2.22517	-.34812	-.04774
4	2.00000	.61492	-.09815	350.93129	.26516	.04430	-.11720	.16838	2.48774	-1.70736	-.09204
5	2.00000	.61492	.09815	9.06871	-.01818	-.00303	.00003	.01154	.17044	.11497	-.00631
6	2.00000	.35447	.21767	31.40886	-.01042	-.00078	.00100	.00551	.08131	.01455	-.00174
7	2.00000	.17121	.24431	54.97814	-.00503	-.00020	.00012	.00153	.02246	.00173	-.00073
8	2.00000	.05169	.25078	78.35286	-.00328	-.00010	.00002	.00076	.01126	.00025	-.00074
9	4.62108	.10432	-.50607	281.64720	.13039	.00644	-.00183	.08004	.97159	-.02165	-.00747
10	4.62108	.34550	-.49303	305.02186	.17489	.01160	-.01097	.14087	1.70990	-.12957	-.04326
11	4.62108	.71936	-.43925	328.59112	.18609	.02343	-.04722	.25954	3.15059	-.55827	-.16596
12	4.62107	1.28090	-.19807	350.93123	.11943	.03362	-.13921	.19999	2.42901	-1.45365	-.22060
13	4.62107	1.28090	.19807	9.06877	-.06978	-.01965	.08133	.11685	1.41917	.06617	-.12889
14	4.62108	.71936	.43925	31.40888	-.04759	-.00599	.01208	.06637	.80571	.14277	-.04244
15	4.62108	.34550	.49303	54.97815	-.02068	-.00137	.00130	.01666	.20218	.01532	-.00512
16	4.62108	.10432	.50607	78.35281	.00093	.00005	-.00001	-.00057	-.00697	-.00016	-.00005
17	7.56661	.14750	-.71555	281.64719	.18039	.01007	-.00363	.15870	1.45815	-.03207	-.02081
18	7.56661	.48451	-.69710	305.02184	.17489	.01310	-.01572	.20187	1.85485	-.13873	-.08766
19	7.56661	1.01711	-.62107	328.59108	.10136	.01442	-.03686	.20257	1.86148	-.32588	-.18315
20	7.56660	1.75450	-.28005	350.93118	.05610	.01784	-.09371	.13462	1.23799	-.23393	-.20994
21	7.56660	1.75450	.28005	9.06886	-.07716	-.02454	.12889	.18516	1.70274	1.14700	-.28876
22	7.56661	1.01711	.62107	31.40889	-.05810	-.00826	.02113	.11612	1.08707	.18669	-.10499
23	7.56661	.48451	.69710	54.97816	-.03687	-.00276	.00331	.04256	.39101	.02925	-.01868
24	7.56661	.14750	.71555	78.35281	-.03350	-.00198	.00072	.03123	.28695	.00631	-.00649
25	10.54296	.18223	-.88405	281.64719	.12751	.00706	-.00310	.13908	.86397	-.01864	-.02253

Figure 26.- Continued.

26	10.54296	.60355	-.86126	305.02185	.13894	.01032	-.01548	.19883	1.23519	-.09064	-.10667
27	10.54297	1.25563	-.76732	32A.59109	.13496	.01903	-.06085	.33441	2.07784	-.35682	-.37354
28	10.54297	2.16767	-.40599	350.93117	.01052	.00332	-.02178	.03128	.19459	-.12906	-.06078
29	10.54297	2.16767	.34599	9.06883	-.06288	-.01983	.13021	.18706	1.16358	.77175	-.36043
30	10.54297	1.25563	.76732	31.40897	-.00134	-.01288	.04118	.22632	1.40621	.24148	-.25280
31	10.54296	.60355	.86126	54.97816	-.02675	-.00199	.00298	.03627	.23777	.01745	-.02053
32	10.54296	.18223	.88405	7A.35281	-.01488	-.00082	.00037	.01623	.10081	.00218	-.00263
33	13.52820	.20942	-1.01596	281.64719	.11238	.00541	-.00323	.14105	.45601	-.00944	-.02626
34	13.52820	.69361	-.98977	305.02184	.10721	.00692	-.01375	.17656	.57086	-.04918	-.10886
35	13.52819	1.40413	-.86181	32A.59108	.10771	.01320	-.05568	.30712	.99320	-.16378	-.39424
36	13.52818	2.40110	-.39762	350.93115	-.01878	-.00515	.04476	-.06430	-.20834	.13363	.14239
37	13.52818	2.40110	.39762	9.06886	-.06605	-.01810	.15741	.22614	.73269	.06994	-.50075
38	13.52819	1.40413	.86181	31.40893	-.00952	-.01110	.04697	.25812	.83473	.11765	-.33134
39	13.52820	.69361	-.98977	54.97816	-.02682	-.00173	.00344	.04417	.14281	.01045	-.02723
40	13.52820	.20942	1.01596	7A.35281	-.02454	-.00118	.00071	.03080	.09957	.00206	-.00573
41	16.51560	.22819	-1.10701	281.64719	.07340	.00232	-.00230	.10046	.02600	-.00012	-.02038
42	16.51560	.75577	-1.07847	305.02183	.07725	.00328	-.01080	.13872	.04591	-.00059	-.09319
43	16.51560	1.57354	-.96083	32A.59103	.07829	.00631	-.04430	.24343	.06317	-.00267	-.34049
44	16.51559	2.71429	-.43325	350.93104	-.07101	-.01280	.19453	-.26508	-.06985	.01774	.63956
45	16.51559	2.71429	.43325	9.06896	-.06223	-.01122	.16171	.23230	.06121	.01554	-.56046
46	16.51560	1.57354	.96083	31.40897	-.00915	-.00767	.05384	.29586	.07677	.00324	-.41381
47	16.51560	.75577	1.07847	54.97817	-.03434	-.00146	.00480	.06167	.01597	.00024	-.04143
48	16.51560	.22819	1.10701	7A.35281	-.03185	-.00101	.00140	.04360	.01128	.00005	-.00884

TOTAL COEFFICIENTS

ON THE BODY FROM XSTART = 0.0000 TO XWLF = 1A.0000

REFR = 12.5670 REFID = 1.4641 REFL = 1.0000
 XM = 16.8000 ZM = 0.0000
 PACM = 1.70000
 ALPHAC = 10.00000 ALPHA = 10.00000
 PHIR = 0.00000 BETA = 0.00000
 CX = .01841
 CY = 0.00000
 CZ = .88865
 C4 = 1.78654
 CLN = 0.00000
 CLL = 0.00000
 XCP = 9.83546

FOLLOWING ARE IN WIND AXIS SYSTEM

CL = .87190
 CY = 0.00000
 CZ = .17264
 C4 = 1.78654
 CNYAW = 0.00000

CPSTAR = 1.94542 CPCRIT = .79466 CPVAC = -.49031

FWD SOLVE TIME = 6.4530 DT = 1.0000

PERTURBATION VELOCITIES AT SPECIFIED CONTROL POINTS BY SOURCE PANELS

** HOYVEL **

JCPT	CONTROL POINT			PANEL ANGLES		VELOCITIES			NORMAL
	X	Y	Z	THET	DELTA	U	V	W	
1	21.9A180	3.64130	0.00000	0.00000	.12529	.03077	-.03893	.27791	.2718A
2	25.47690	3.64130	0.00000	0.00000	.12773	.01671	-.03515	.20167	.19790
3	22.79380	4.00490	0.00000	0.00000	.13810	.02826	-.0335A	.1728A	.16732
4	25.71560	4.00490	0.00000	0.00000	.21266	.01619	-.02840	.14465	.13797
5	21.40470	-4.36790	0.00000	0.00000	.21266	.02664	-.03160	.12540	.11695
6	25.95390	4.36790	0.00000	0.00000	.13810	.01549	-.0241A	.11243	.10923
7	21.58590	2.81800	.44979	0.00000	.12773	.02376	-.05273	.05990	.05630
8	21.58590	1.63360	-.99752	0.00000	.12529	.03627	-.02796	-.17431	-.17747
9	21.58590	.78462	1.11960	0.00000	.08032	.03568	-.05563	-.18569	-.18796
10	21.58590	.23690	1.14930	0.00000	.08190	.04522	-.01440	-.1951A	-.19823
11	21.58590	.23690	-1.14930	0.00000	.08459	.01995	.02000	-.1536A	-.15480
12	21.58590	.78462	-1.11960	0.00000	.13713	.04230	.08505	-.12776	-.13234
13	21.58590	1.63360	-.99752	0.00000	.13713	.02622	.11854	-.12042	-.1228A
14	21.58590	2.81800	.44979	0.00000	.08459	.05307	.30334	.12184	.1166A
15	25.36050	2.81800	.44979	0.00000	.08190	-.00575	-.33634	.14262	.14262
16	25.36050	1.63360	-.99752	0.00000	.08032	.00208	-.13981	-.18074	-.18033
17	25.36050	.78462	1.11960	0.00000	.06337	.00767	-.0635A	-.1438A	-.14397
18	25.36050	.23690	1.14930	0.00000	.06462	.02787	-.01179	-.20495	-.20632
19	25.36050	.23690	-1.14930	0.00000	.06991	.03946	.01976	-.13909	-.14150
20	25.36050	.78462	-1.11960	0.00000	.10836	.05313	.06701	-.13473	-.1396A
21	25.36050	1.63360	-.99752	0.00000	.10836	.05702	.1270A	-.11184	-.11735
22	25.36050	2.81800	.44979	0.00000	.06991	.04292	.27085	.21186	.20835

Figure 26.- Concluded.

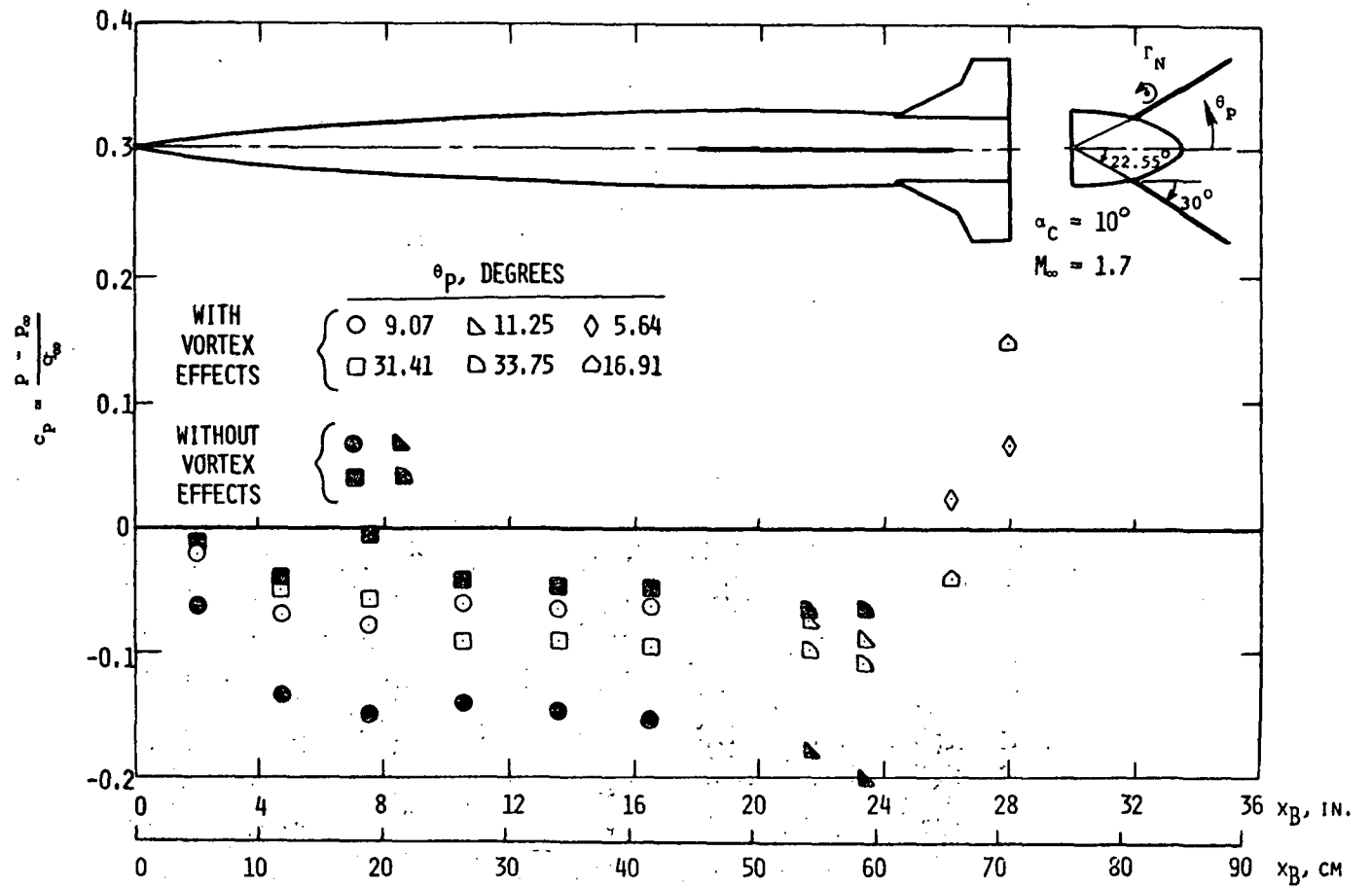


Figure 27(a).- Calculated pressure distributions, second sample case.

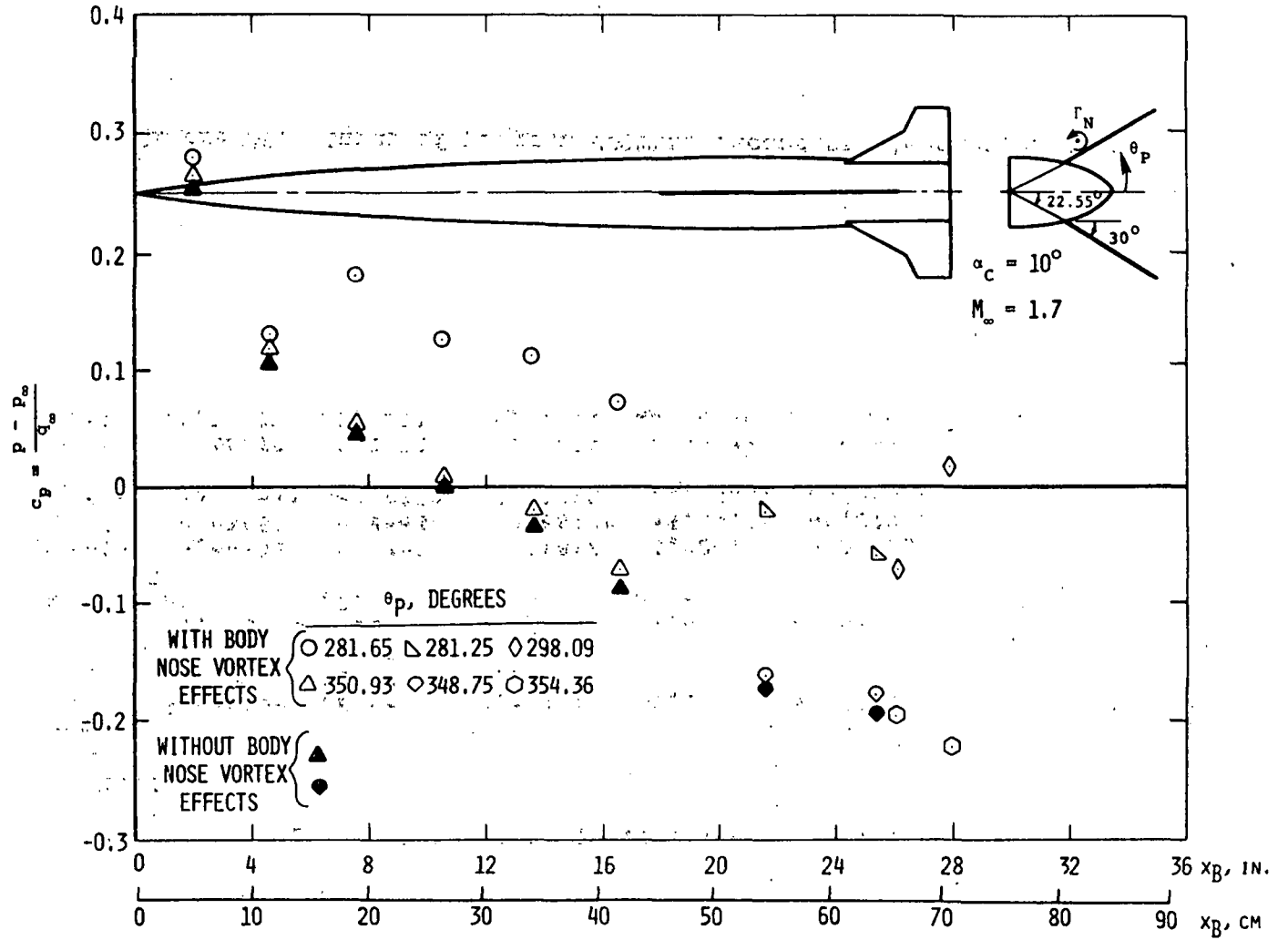


Figure 27(b).- Concluded.

LRC 3/1 ELLIPTICAL BODY/MONOPLANE WING, TRACK BODY NOSE VORTICES.

	1	4	5	1	1	0	0
0.3333333							
25.55							
3.464106							
18.0	3.464106	22.081	4.55761	25.55	4.55761	25.56	3.464106
10.0	0.0	0.0001	0.50				
2	2	2	2				
2.35	1.673	1.52	-2.35	1.673	-1.52		
18.0	20.0	22.0	24.0	25.55			
	3	3					
0.66148	3.64135	0.27984	2.01812	3.82511	0.27786		
3.37295	4.03457	0.28634	0.66148	-3.64135	-0.27984		
2.01812	-3.82511	-0.27786	3.37295	-4.03457	-0.28634		
	2						
4.081	4.34073	0.44937	6.13099	4.40075	0.58150		
4.081	-4.34073	-0.44937	6.13099	-4.40075	-0.58150		

Figure 28.- Input of program VPATHL, second sample case, step 4.

LRC 3/1 ELLIPTICAL BODY/MONOPLANE WING, TRACK BODY NOSE VORTICES.

```

      FIN GEOMETRY
      FIN SEMISPAN      = 4.55761
      FIN ROOTCHORD    = 7.56000
      FIN ROOT L.E. X-STATION= 18.00000
      L.E. Y-STATION= 3.46411
      FIN TIP L.E. X-STATION = 22.08100
      L.E. Y-STATION = 4.55761
      FIN TIP T.E. X-STATION = 25.55000
      T.E. Y-STATION = 4.55761
      FIN ROOT T.E. X-STATION= 25.56000
      T.E. Y-STATION= 3.46411
  
```

```

INCLUDED ANGLE OF ATTACK( DEG ) = 10.00000  WING ANGLE( DEG ) = 0.00000
  
```

```

      FIN LEADING EDGE VORTICITY
      JLF      X      Y OR Z BAR  GAMMA/VINF.
      1  18.66148  3.64135  .27984
      2  20.01812  3.82511  .27786
      3  21.47295  4.03457  .28634
      4  18.66148 -3.64135 - .27984
      5  20.01812 -3.82511 - .27786
      6  21.47295 -4.03457 - .28634
  
```

```

      FIN SIDE EDGE VORTICITY
      JSE      X      Y OR Z BAR  GAMMA/VINF.
      1  22.08100  4.34073  .44937
      2  24.13099  4.40075  .52150
      3  22.08100 -4.34073 - .44937
      4  24.13099 -4.40075 - .52150
  
```

```

****PERMISSIBLE RELATIVE ERROR, ES, USED IN INTEGRATION SCHEME = .10000E+03
  
```

```

VORTEX COORDINATES IN CROSS-FLUID PLANE
  
```

Figure 29.- Output of program VPATHL, second sample case, step 4.

INITIAL VORTEX POSITIONS AT X = 18.000

LOCAL BODY HORIZONTAL SEMI-AXIS = 3.46411
 LOCAL BODY VERTICAL SEMI-AXIS = 1.15470
 LOCAL SEMI SPAN S = 3.46411

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	.21500E+01	.16730E+01	.15200E+01
2	-.23500E+01	.16730E+01	-.15200E+01

X-STATION NO. 2 X=20.000 INTEGRATION STEP SIZE = 1.00000

LOCAL BODY HORIZONTAL SEMI-AXIS = 3.46411
 LOCAL BODY VERTICAL SEMI-AXIS = 1.15470
 LOCAL SEMI SPAN S = 4.00000

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	.23864E+01	.17470E+01	.15200E+01
2	-.23864E+01	.17470E+01	-.15200E+01

X-STATION NO. 3 X=22.000 INTEGRATION STEP SIZE = 1.00000

LOCAL BODY HORIZONTAL SEMI-AXIS = 3.46411
 LOCAL BODY VERTICAL SEMI-AXIS = 1.15470
 LOCAL SEMI SPAN S = 4.53591

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	.24152E+01	.18080E+01	.15200E+01
2	-.24152E+01	.18080E+01	-.15200E+01

X-STATION NO. 4 X=24.000 INTEGRATION STEP SIZE = 1.00000

LOCAL BODY HORIZONTAL SEMI-AXIS = 3.46411
 LOCAL BODY VERTICAL SEMI-AXIS = 1.15470
 LOCAL SEMI SPAN S = 4.55761

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VINF
1	.24432E+01	.18500E+01	.15200E+01
2	-.24432E+01	.18500E+01	-.15200E+01

X-STATION NO. 5 X=25.550 INTEGRATION STEP SIZE = 1.00000

LOCAL BODY HORIZONTAL SEMI-AXIS = 5.46011
 LOCAL BODY VERTICAL SEMI-AXIS = 1.15470
 LOCAL SEMI SPAN S = 4.55761

VORTEX	Y,VRTX	Z,VRTX	GAMMA/VTRF
1	.24609E+01	.18792E+01	.15200E+01
2	-.24609E+01	.18792E+01	-.15200E+01

CROSSFLOW VELOCITIES AT CONTROL POINTS INDUCED BY VORTICES AND THEIR IMAGES

IC	X,BODY	Y,BODY	Z,BODY	V	W
1	.21982E+02	.36413E+01	0.	.22027E-01	-.73043E-01
2	.25477E+02	.36413E+01	0.	.25261E-01	-.78140E-01
3	.22794E+02	.40049E+01	0.	.32846E-01	-.58780E-01
4	.25716E+02	.40049E+01	0.	.30452E-01	-.41193E-01
5	.23605E+02	.45679E+01	0.	.32199E-01	-.21043E-01
6	.25954E+02	.45679E+01	0.	.33399E-01	-.22172E-01
7	.21586E+02	.31558E+01	.50368E+00	.18131E+00	-.12379E+00
8	.21586E+02	.16764E+01	.10237E+01	.38057E+00	-.75801E-01
9	.21586E+02	.79548E+00	.11457E+01	.11080E+00	-.10914E-01
10	.21586E+02	.23943E+00	.11435E+01	.28788E-01	-.20990E-02
11	.21586E+02	.21943E+00	-.11435E+01	-.52670E-03	-.57474E-04
12	.21586E+02	.79548E+00	-.11457E+01	-.18247E-02	-.17398E-03
13	.21586E+02	.16764E+01	-.10237E+01	-.46457E-02	-.91229E-03
14	.21586E+02	.31558E+01	-.50368E+00	-.21879E-01	-.17031E-01
15	.25361E+02	.31558E+01	.50368E+00	.18892E+00	-.12949E+00
16	.25361E+02	.16764E+01	.10237E+01	.35303E+00	-.69473E-01
17	.25361E+02	.79548E+00	.11357E+01	.11003E+00	-.10781E-01
18	.25361E+02	.23943E+00	.11435E+01	.29018E-01	-.21119E-02
19	.25361E+02	.21943E+00	-.11435E+01	-.57450E-03	-.41311E-04
20	.25361E+02	.79548E+00	-.11357E+01	-.19944E-02	-.18974E-03
21	.25361E+02	.16764E+01	-.10237E+01	-.50641E-02	-.99439E-03
22	.25361E+02	.31558E+01	-.50368E+00	-.23762E-01	-.18491E-01

IDEALIZED LRC ELLIPTICAL BODY MONOPLANE WING

INPUT

CRP=7.54926, SWLEP=75.0, SWTEP=30.01584, B2=1.0935, HIL=7.54926,
XWLE=18.0,
RB=3.464106, RAB=1.1547005, ERATIO=3.0,
NCW=2, MSWP=3, MSWL=0, NBDCR=8, NCWB=2,
NRDCR=16,
ALFAC=10.0, PHI=0.0, FMACH=1.7,
SREF=12.567, REFL=3.464106,
NDLINP=1, NDRAG=1, NBDYPR=1,
NDOUT=0,
NCPDUT=0,
NVLIN=1,
NTDAT=1, NCWT=4,
XM=16.8, ZM=0.0,
SEND

3	0	0		
0.049692	0.0	0.0	-0.07889	
0.049692	0.049692	0.0	-0.07889	
0.049692	0.049692	0.0	-0.07889	
0	0	0	0	0
0				

ZZZZZZZZZZZZ

Figure 30.- Input of program DEMON2, second sample case, step 5.

IDEALIZED LPC ELLIPTICAL BODY MONOPLANE WING

```

SINPHI = 0.0
CORR = .754926E+01,
SWLEP = .75E+02,
SSTED = .5001560E+02,
NC = 2,
MS+R = 5,
MS+L = 0,
ALFAC = .1E+02,
PHI = 0.0,
H2 = .10935E+01,
FMACH = .17E+01,
LVS+P = 0,
FAC = .95E+00,
NEVNDP = 0,
TOLFAC = .1E+01,
MS+U = 0,
MS+D = 0,
SWLEV = 0.0,
SSTEV = 0.0,
CORV = 0.0,
RDV = 0.0,
MCRV = 0,
RR = .5464106E+01,
RA = .11547005E+01,
ERATIO = .30000038971145E+01,
BRDCN = 16,
DELR = 0.0,
DELL = 0.0,
DELU = 0.0,
DELD = 0.0,
SREF = .12547E+02,
REFL = .3444106E+01,
PHIDTH = 0.0,
TMEITT = 0.0,
X*LE = .18E+02,
VOLINP = 1,
VOUT = 0,
NPR = 0,
NDHAR = 1,
NVRTX = 0,
NPRESS = 0,
VOT*AX = .35E+00,
NC*H = 2,
NAGAIN = 0,
BIL = .754926E+01,
ITAIL = 0,
NVRTPL = 0,
NRDYDR = 1,
VTPR = 0,
NTDAT = 1,
VCWT = 4,
VCPDUT = 0,
VVLIN = 1,
VSTART = 0.0,
JCPT = 0,
FALE = .5E+00,
FASE = .5E+00,
Z1 = .16E+02,
Z2 = 0.0,
KEND

```

Figure 31.- Output of program DEMON2, second sampel case, step 5.

WING GEOMETRY

TIP CHORD = 4.09999
 ROOT CHORD = 7.54926
 WING SEMISPAN = 1.09350
 LEADING EDGE SWEEP = 75.00000 DEGREES
 TRAILING EDGE SWEEP = 30.01564 DEGREES

FLOW CONDITIONS

MACH = 1.70000 ALPHAC = 10.00000 PHI = 0.00000 ALFA = 10.00000 BETA = 0.00000

CRPT = 7.54926

WING THICKNESS INPUT DATA

SPANWISE LOCATIONS OF PANEL SIDE EDGES AND SWEEP ANGLES
 OF WING SECTION TO THE LEFT

I	SPANWISE LOCATION FEET	LE SWEEP DEGREES	TE SWEEP DEGREES
1	4.46411	0.00000	0.00000
2	3.82861	75.00000	30.01564
3	4.19311	75.00000	30.01564
4	4.55761	75.00000	30.01564

RIGHT WING SURFACE

12 THICKNESS PANELS ARE TO BE LAID OUT
 3 CHORDWISE ROWS WITH 4 IN EACH ROW

INPUT VALUES OF THE LOCAL SURFACE SLOPE OF THE THICKNESS
 DISTRIBUTION. FOR EACH CHORDWISE ROW THE FIRST VALUE
 IS FOR THE PANEL NEAREST THE LEADING EDGE

RIGHT WING SURFACE

ROW	SLOPES			
1	.04969	0.00000	0.00000	-.07889
2	.04969	.04969	0.00000	-.07889
3	.04969	.04969	0.00000	-.07889

BODY UNDER CONSIDERATION HAS ELLIPTICAL CROSS SECTION,
 INTERFERENCE SHELL HAS FOLLOWING PROPERTIES:
 HORIZONTAL SEMI-AXIS = 1.40411
 VERTICAL SEMI-AXIS = 1.15470

POINT COORDINATES AND PERTURBATION VELOCITIES CALCULATED BY PROGRAM VPATH OR VPATHL

IC	XCP	YCP	ZCP	VVEL(IC)	WVEL(IC)
1	21.98200	3.64130	0.00000	.22027E-01	-.73045E-01
2	25.47700	3.64130	0.00000	.23261E-01	-.74140E-01
3	22.79400	4.00490	0.00000	.32844E-01	-.48780E-01
4	25.71600	4.00490	0.00000	.34452E-01	-.41193E-01
5	23.60500	4.36790	0.00000	.32109E-01	-.21043E-01
6	25.95400	4.36790	0.00000	.33399E-01	-.22172E-01
7	21.58600	3.15540	.50368	.18131E+00	-.12374E+00
8	21.58600	1.67640	1.02370	.18057E+00	-.75801E-01
9	21.58600	.79588	1.13570	.11088E+00	-.10914E-01
10	21.58600	.23983	1.16350	.28788E-01	-.20990E-02
11	21.58600	.23983	-1.16350	-.52670E-03	-.37870E-04
12	21.58600	.79588	-1.13570	-.18287E-02	-.17398E-03
13	21.58600	1.67640	-1.02370	-.46457E-02	-.01229E-03
14	21.58600	3.15540	-.50368	-.21879E-01	-.17031E-01
15	25.36100	3.15540	.50368	.18992E+00	-.12949E+00
16	25.36100	1.67640	1.02370	.35303E+00	-.89873E-01
17	25.36100	.79588	1.13570	.11003E+00	-.10781E-01
18	25.36100	.23983	1.16350	.29018E-01	-.21119E-02
19	25.36100	.23983	-1.16350	-.57450E-03	-.41311E-04
20	25.36100	.79588	-1.13570	-.19940E-02	-.18974E-03
21	25.36100	1.67640	-1.02370	-.50641E-02	-.99439E-03
22	25.36100	3.15540	-.50368	-.23762E-01	-.18491E-01

CONTROL POINT COORDINATES FOR 2 CHORDWISE BY 3 SPANWISE PANELS ON WING 1 OR R, 0 SPANWISE ON WING 2 OR L
 AND 0 SPANWISE PANELS ON WING 3 OR U, 0 SPANWISE ON WING 4 OR D

I	X(J)	Y(J)	Z(J)	RU(J)	RV(J)	RW(J)	VVRTX	WVRTX
1	3.98181	3.64135	0.00000	.50788E-01	-.38935E-01	.27791E+00	0.	0.
2	7.47690	3.64135	0.00000	.16709E-01	-.35151E-01	.20167E+00	0.	0.
3	4.79380	4.00486	0.00000	.28259E-01	-.33580E-01	.17286E+00	0.	0.
4	7.71557	4.00486	0.00000	.16190E-01	-.28395E-01	.14465E+00	0.	0.
5	5.60471	4.36789	0.00000	.28643E-01	-.31892E-01	.12540E+00	0.	0.
6	7.95393	4.36789	0.00000	.15490E-01	-.24185E-01	.11245E+00	0.	0.

CONTROL POINT COORDINATES FOR RTP'S (WING FRAME)

I	X(J)	Y(J)	Z(J)	THU(J)	THV(J)	THW(J)
7	3.58590	2.81795	.44979	-.14293E-02	-.50900E-02	.19263E-02
8	3.58590	1.63362	.99752	-.21755E-02	-.28706E-02	.14883E-02
9	3.58590	.78462	1.11965	0.	0.	0.
10	3.58590	.23690	1.14927	0.	0.	0.
11	3.58590	.23690	-1.14927	0.	0.	0.
12	3.58590	.78462	-1.11965	0.	0.	0.
13	3.58590	1.63362	-.99752	-.21755E-02	-.28706E-02	-.14883E-02
14	3.58590	2.81795	-.44979	-.14293E-02	-.50900E-02	-.19263E-02

15	7.36053	2.81795	.44979	.11729E-01	.12612E-01	-.75118E-02
16	7.36053	1.63362	.99752	-.17810E-02	-.42403E-02	.22634E-02
17	7.36053	.78442	1.11905	-.25780E-02	.13265E-02	.11738E-02
18	7.36053	.25690	1.14927	-.26999E-02	.79477E-03	.13010E-02
19	7.36053	.25690	-1.14427	-.26999E-02	.79477E-03	-.13010E-02
20	7.36053	.78442	-1.11965	-.25780E-02	.13265E-02	-.11738E-02
21	7.36053	1.63362	-.99752	-.37810E-02	-.42403E-02	-.22634E-02
22	7.36053	2.81795	-.44979	.11729E-01	.12612E-01	.75118E-02

LOADING INFORMATION

MACH NUMBER = .17000E+01
 ANGLE OF ATTACK = 10.000 DEGREES
 SIDE SLIP ANGLE = 0.000 DEGREES
 WING AREA = 12.73846
 REFERENCE AREA = 12.56700
 REFERENCE LENGTH = 3.46411
 EXPOSED WING SPAN B = 2.18700
 MOMENT CENTER: X = 16.80000
 Z = 0.00000

WING TYPE LOADING PRESSURE

REFL. ANGLE DEG.	TOTAL	FIN 1 OR R	FIN 2 OR L	FIN 3 OR U	FIN 4 OR D	INTERF. SHELL
CTHR =	.29818E-01	0.00000	0.00000	0.00000	0.00000	
CZ =	.47064E+00	.10409E-01	.10409E-01	0.	0.	.27878E+00
CY =	0.	.95932E-01	.95932E-01	0.	0.	0.
CM =	-.10223E+01	0.	0.	0.	0.	0.
CLN =	0.	-.18717E+00	-.18717E+00	0.	0.	-.64798E+00
CLL =	0.	0.	0.	0.	0.	0.
		-.10990E+00	.10990E+00	0.	0.	0.

FOLLOWING ARE IN WIND-AXIS SYSTEM

CL =	.46711E+00	.96282E-01	.96282E-01	0.	0.	.27454E+00
CY WIND =	0.	0.	0.	0.	0.	0.
COY =	.61224E-01	.64074E-02	.64074E-02	0.	0.	.48410E-01
COY/CL**2 =	.28060E+00					
CM WIND =	-.10223E+01	-.18717E+00	-.18717E+00	0.	0.	-.64798E+00
CL WIND =	0.	.19084E-01	-.19084E-01	0.	0.	0.

-----RIGHT WING-----

B. WING TIP

SPANNWISE DISTRIBUTIONS

I	Y/(H/2)	CN+C/(2*B)	CT+C/(2*B)	CY1+C/(2*B)	CYTOT+C/(2*B)	CS+C/(2*B)	CSIN1	YHAR	GAMNET(I)	GAMMA,LE/VINF	XLE
1	3.32099	.27982	.02268	.06378	.02942	.08743	.03194	3.64135	-.61334	.19406	.66144
2	3.66242	.27199	.02547	.07117	.09879	.09843	.06782	3.83365	.01657	.19763	2.01812
3	3.99441	.20436	.03423	.10075	.10075	.15225	.11602	4.05562	.14759	.21123	3.37295
4	4.16791	0.00000							.08910		

SUMFX = .10452E-01
 SUMFY1 = .29902E-01
 SUMFY2 = -.85195E-03
 SUMFZ = .10511E+00

SIDE EDGE DISTRIBUTION

JTID	JSF	DISTANCE FROM LE /TIPCHORD	SUCTION FORCE PER UNIT LENGTH /(D*TIPCHORD)	GAMMA,SE /VINF	YHAR	XSE
1	1	.50000	.09399	.35606	4.36126	4.08100
2	2	1.00000	.06318	.07179	4.41924	6.13099

***** FIN VORTEX INFO*****

TVPT GAMMA/VINF Y.C.G.

1 .61196 4.44912

VELOCITIES AND BERNOULLI PRESSURES AT CONTROL POINTS IMMEDIATELY ABOVE AND BELOW HORIZONTAL WING SURFACE

J	X(J)	Y(J)	Z(J)	UTOTA	VTOTA	WTOTA	PRESSA	UTOTB	VTOTB	WTOTB	PRESSB
1	3.981812	3.641349	0.000000	.079004	-.240061	-.173648	-.165056	-.028511	.160947	-.171648	.062203
2	7.076901	3.641349	0.000000	.067994	-.025306	-.252538	-.105974	.000063	.121077	-.090758	.069207
3	4.793803	4.004860	0.000000	.074117	-.274804	-.123956	-.180050	-.072305	.242574	-.221440	.090370
4	7.715573	4.004860	0.000000	.062914	-.027248	-.252538	-.097007	.069085	.088744	-.094758	-.001919
5	5.4004708	4.367885	0.000000	.115213	-.314455	-.123956	-.249191	-.055308	.317540	-.223340	.033511
6	7.953725	4.367885	0.000000	.037632	-.046344	-.252538	-.050934	.016947	.008211	-.094758	-.004734

Figure 31.- Continued.

PRESSURE LOADINGS AT CONTROL POINTS

	X(J)	Y(J)	Z(J)	DELTP, LIN.	DELTP, REF.
1	3.941812	3.641349	0.000000	.215114	.227239
2	7.476901	3.641349	0.000000	.135861	.115181
3	4.793893	4.004860	0.000000	.308845	.270421
4	7.715573	4.004860	0.000000	.107659	.095088
5	5.604708	4.367885	0.000000	.341043	.292701
6	7.953925	4.367885	0.000000	.041370	.041200

LOADING INFORMATION

MACH NUMBER = .17000E+01
 ANGLE OF ATTACK = 10.000 DEGREES
 SIDE SLIP ANGLE = 0.000 DEGREES
 WING AREA = 12.75844
 REFERENCE AREA = 12.56709
 REFERENCE LENGTH = 3.46011
 EXPOSED WING SPAN H = 2.16700
 MOMENT CENTER: XM = 14.80000
 ZM = 0.00000

PERNOUILLI TYPE LOADING PRESSURE

DEFL. ANGLE DEG.	TOTAL	FIN 1 OR R	FIN 2 OR L	FIN 3 OR U	FIN 4 OR D	INTERF. SHELL
CTHR =	.18694E-01	0.00000	0.00000	0.00000	0.00000	
CZ =	.45372E+00	.94469E-02	.94469E-02	0.	0.	.27878E+00
CY =	0.	.87468E-01	.87468E-01	0.	0.	0.
CM =	-.98554E+00	0.	0.	0.	0.	-.64798E+00
CLN =	0.	.16879E+00	.16879E+00	0.	0.	0.
CLL =	0.	0.	0.	0.	0.	0.
		-.99789E-01	-.99789E-01	0.	0.	0.

FOLLOWING ARE IN WIND-AXIS SYSTEM

CL =	.45010E+00	.87779E-01	.87779E-01	0.	0.	.27454E+00
CY*IND =	0.	0.	0.	0.	0.	0.
CDI =	.46180E-01	.58852E-02	.58852E-02	0.	0.	.48410E-01
CDI/CL*2 =	.29705E+00					
CM*IND =	-.98554E+00	-.16879E+00	-.16879E+00	0.	0.	-.64798E+00
CLN*IND =	0.	.17328E-01	.17328E-01	0.	0.	0.

Figure 31.- Continued.

.....RIGHT WING.....

SPANWISE DISTRIBUTIONS

T	Y/(R/2)	CX+C/(2*H)	CT+C/(2*H)	CY1+C/(2*R)	CY1DT+C/(2*R)	CS+C/(2*H)	CSINT	YBAR	GAMNET(T)	GAMMA, LE/VINF	XLE
1	3.32000	.27500	.02356	.06693	.07816	.09105	.03319	3.64135	.59819	.20163	.66148
2	3.66242	.24316	.02289	.06392	.16174	.08833	.06538	3.82035	.06003	.19760	2.01812
3	3.99441	.17500	.02837	.08352	.08352	.10963	.10514	4.02865	.15351	.20115	3.37295
4	4.16791	0.00000							.38046		

SUMFY = .96890E-02
 SUMFY1 = .27183E-01
 SUMFY2 = .62412E-02
 SUMFT2 = .87896E-01

SIDE EDGE DISTRIBUTION

JTTP	JSE	DISTANCE FROM LE / TIPCHORD	SECTION FORCE PER UNIT LENGTH / (R*TIPCHORD)	GAMMA, SE / VINF	YBAR	XSE
1	1	.50000	.07791	.31498	4.33889	4.08100
2	2	1.00000	.05351	.41103	4.40173	6.13099

*****E. FIN VORTEX INFO*****

1/RT GAMMA/VINF Y.C.G.
 1 .59700 4.48465

.....
 AFT OF LEADING EDGE OF FIN BOUTCHORDS

PRESSURE COEFFICIENTS AT POINTS ON BODY MERIDIANS

J	THETA DEG.	YR	ZR	DTOT	VTOT	WTOT	CP,LIN.	CP,HEMN.	OR/UX	P/PINF, BERN.	P/PINF, LIN.
---	------------	----	----	------	------	------	---------	----------	-------	---------------	--------------

Figure 31.- Continued.

BODY RING# 1												
1	11,25000	21,58490	2,81795	.44979	.03566	-.15872	-.07273	-.07133	-.07258	0,00000	.85317	.85570
2	33,75000	21,58490	1,63362	.99752	.04018	.25728	-.25096	-.04036	-.11227	0,00000	.77289	.83743
3	56,25000	21,58490	.78462	1,11965	.04365	.06333	-.19724	-.08730	-.05954	0,00000	.87956	.82340
4	78,75000	21,58490	.23690	1,14927	.04888	.01555	-.19731	-.09777	-.06592	0,00000	.86665	.80222
5	281,25000	21,58490	.23690	-1,10927	.02438	.02071	-.15369	-.04675	-.01705	0,00000	.96551	.90542
6	303,75000	21,58490	.78462	-1,11965	.04090	.08727	-.12762	-.08980	-.06656	0,00000	.86534	.81853
7	326,25000	21,58490	1,63362	-.99752	.02139	.11089	-.12188	-.04278	-.02688	0,00000	.94583	.91345
8	348,75000	21,58490	2,81795	-.44979	.03800	.26433	.09288	-.07599	-.16311	0,00000	.67003	.84627

BODY RING# 2												
1	11,25000	25,36053	2,81795	.44979	.04331	-.11684	-.00815	-.08663	-.09132	0,00000	.81526	.82475
2	33,75000	25,36053	1,63362	.99752	.04291	.24035	-.25555	-.08502	-.14983	0,00000	.77751	.82801
3	56,25000	25,36053	.78462	1,11965	.07093	.10105	-.20891	-.14186	-.11497	0,00000	.76741	.71302
4	78,75000	25,36053	.23690	1,14927	.06884	.03170	-.20739	-.13169	-.09814	0,00000	.80146	.73360
5	281,25000	25,36053	.23690	-1,10927	.04033	.02233	-.13906	-.08866	-.05820	0,00000	.88227	.82064
6	303,75000	25,36053	.78462	-1,11965	.06190	.08776	-.13315	-.12480	-.09722	0,00000	.80332	.74955
7	326,25000	25,36053	1,63362	-.99752	.03814	.11786	-.11359	-.07232	-.05733	0,00000	.88402	.85349
8	348,75000	25,36053	2,81795	-.44979	.02213	.24577	.19245	-.04425	-.17885	0,00000	.63819	.91047

Figure 31.- Concluded.

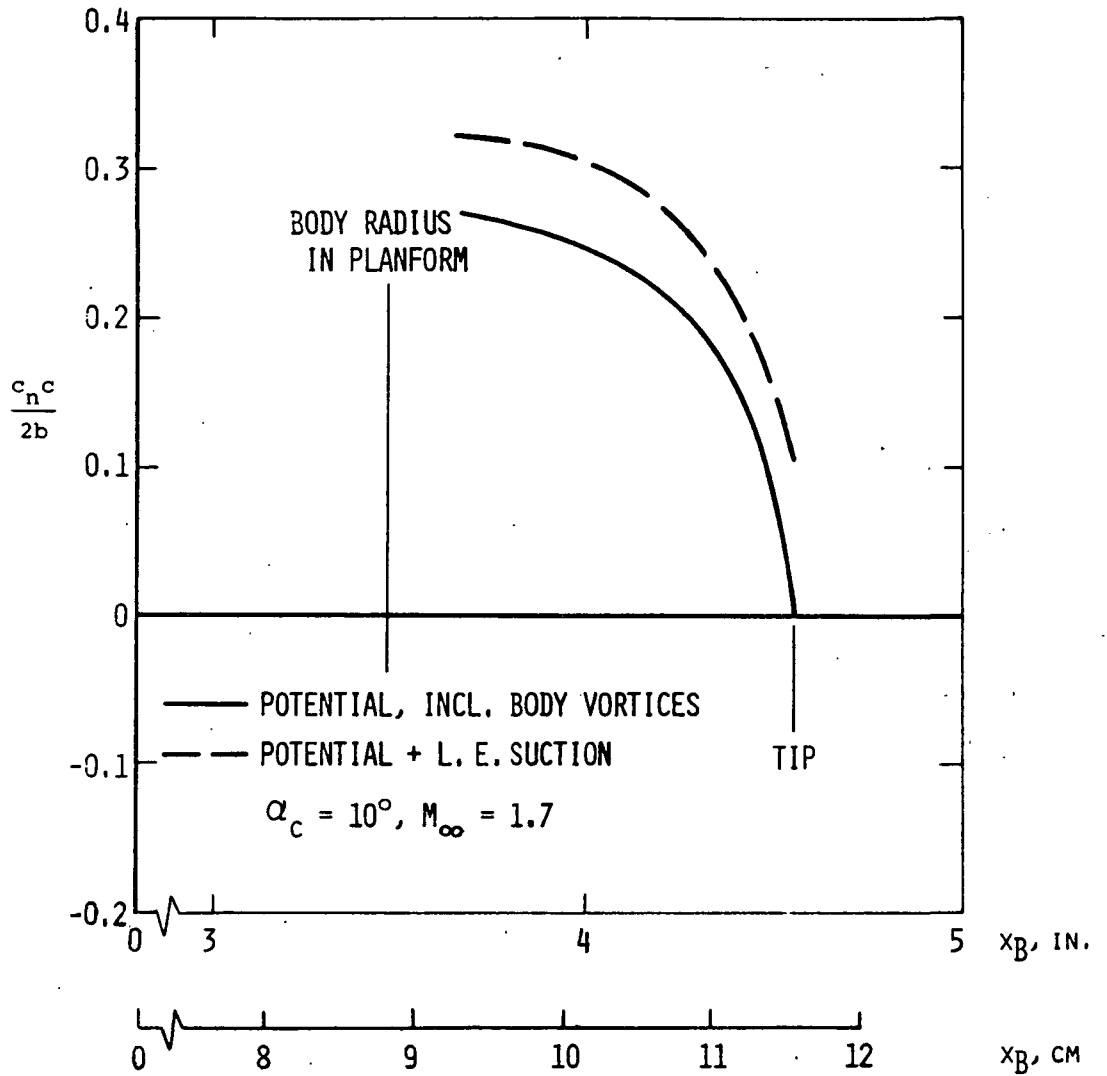


Figure 32.- Calculated span-load distribution on monoplane wing, second sample case.

IDEALIZED LRC ELLIPTICAL BODY-INTERDIGITATED FINS.

```

$INPUT
CRP=3.6, B2=3.6, CRPV=3.6, B2V=3.6, NCRX=1,
BIL=3.6, RB=3.129, RAM=1.043,
PHIDI=30., THETIT=22.545,
XWLE=24.4,
NCW=2, MSWR=4, MSWU=4, NBDCR=8, NCWB=2,
NBDCR=16,
ALFAC=10.0, FMACH=1.7, PHI=0.,
SREF=12.567, REFL=3.464106,
NVRTX=6,
LVSWP=1, NOLINP=1,
NDOUT=0,
NBDYPR=1,
NDRAG=0,
XM=16.0, ZM=0.0,
$END
0.0      45.0      0.0
1.0      45.0      0.0
2.0      45.0      0.0
3.0      14.03624  0.0
3.6      14.03624  0.0
0.0      45.0      0.0
1.0      45.0      0.0
2.0      45.0      0.0
3.0      14.03624  0.0
3.6      14.03624  0.0
1.52     2.4609    1.8809
-1.52    -2.4609    1.8809
0.47179  4.41828    0.661
-0.47179 -4.41828    0.661
0.59704  4.38465    0.0
-0.59704 -4.38465    0.0
      0
      0
ZZZZZZZZZZ

```

Figure 33.- Input of program DEMON2, second case, step 10.

IDEALIZED LRC ELLIPTICAL HOBY-INTERDIGITATED FINS.

```

SIAPIT
CRP  = .36E+01,
S-LEP = 0.0,
S-TEP = 0.0,
NCH  = 2,
MSWR = 4,
MSHL = 0,
ALFAC = .1E+02,
PHI  = 0.0,
B2   = .36E+01,
FMACH = .17E+01,
LVSAP = 1,
FAC  = .95E+00,
NFVNPR = 0,
TOLFAC = .1E+01,
MSHU = 4,
MSWD = 0,
S-LEV = 0.0,
S-TEV = 0.0,
CRPV  = .36E+01,
B2V   = .36E+01,
NCRV  = 1,
RB    = .3129E+01,
RA    = .1043E+01,
ERATIO = .3E+01,
NBOD  = 16,
DELR  = 0.0,
DELL  = 0.0,
DELU  = 0.0,
DELD  = 0.0,
SREF  = .12567E+02,
REFL  = .346410E+01,
PHIDIM = .3E+02,
T-FITT = .22545E+02,
X-LE  = .244E+02,
NOLIP = 1,
NOUT  = 0,
NPR   = 0,
NDRAG = 0,
NVRTX = 6,
NDRSS = 0,
VRTMAX = .35E+00,
NCWB  = 2,
NAGAIN = 0,
BIL   = .36E+01,
ITAIL = 0,
NVRTPL = 0,
NBODYPW = 1,
NTPR  = 0,
NTDRT = 0,
NCWT  = 0,
NCRPUT = 0,
NVLIN = 0,
XSTART = 0.0,
JCPT  = 0,
FKLE  = .5E+00,
FKSF  = .5E+00,
XM    = .16E+02,
XZM   = 0.0,
SEND

```

Figure 34.- Output of program DEMON2, second sample case, step 10.

WING 1 SURFACE

SPECIFIED SPANWISE LOCATIONS OF OUTBOARD PANEL EDGES AND SWEEP ANGLES

K	X OR Z	L.E. SWEEP ANGLE	T.E. SWEEP ANGLE
1	0.00000	45.00000	0.00000
2	1.00000	45.00000	0.00000
3	2.00000	45.00000	0.00000
4	3.00000	14.03624	0.00000
5	3.60000	14.03624	0.00000

WING 3 SURFACE

1	0.00000	45.00000	0.00000
2	1.00000	45.00000	0.00000
3	2.00000	45.00000	0.00000
4	3.00000	14.03624	0.00000
5	3.60000	14.03624	0.00000

WING GEOMETRY

TIP CHORD = 1.20000
 ROOT CHORD = 3.60000
 WING SEMISPAN = 3.60000

FLOW CONDITIONS

MACH = 1.70000 ALPMACH = 10.00000 PHI = 0.00000 ALFA = 10.00000 BETA = 0.00000

CRPY = 3.60000
 CRPTV = 3.00000

BODY UNDER CONSIDERATION HAS ELLIPTICAL CROSS SECTION.
 INTERFERENCE SHELL HAS FOLLOWING PROPERTIES:
 HORIZONTAL SEMI-AXIS = 3.12900
 VERTICAL SEMI-AXIS = 1.04300

TWO DIMENSIONAL VORTEX STRENGTHS AND FIXED COORDINATES IN CROSS FLOW PLANE

IVRTX	GAMMA/VINF	VVRTX	ZVRTX
1	1.52000	2.46090	1.88090
2	-1.52000	-2.46090	1.88090
3	.47179	4.41828	.66100
4	-.47179	-4.41828	.66100
5	.59704	4.38465	0.00000
6	-.59704	-4.38465	0.00000

CONTROL POINT COORDINATES FOR 2 CHORDWISE BY 4 SPANWISE PANELS ON WING 1 OR R. 0 SPANWISE ON WING 2 OR L
AND 4 SPANWISE PANELS ON WING 3 OR U. 0 SPANWISE ON WING 4 OR D

J	X(J)	Y(J)	Z(J)	BU(J)	BV(J)	BW(J)	VVRTX	WVRTX
1	1.95839	2.36879	1.04983	-.22304E-01	-.27928E+00	-.24470E-01	.35000E+00	-.16737E+00
2	3.52183	2.36879	1.04983	-.99857E-02	-.21752E+00	-.13710E-01	.34000E+00	-.16737E+00
3	2.47667	3.22373	1.54343	-.35266E-02	-.12940E+00	.35743E-01	.14981E+00	.90173E-01
4	3.54651	3.22373	1.54343	-.37760E-01	-.92972E-01	.72383E-01	.16981E+00	.90173E-01
5	2.82377	4.11189	2.05621	.89070E-02	-.83780E-01	.30439E-01	-.44104E-01	.38832E-01
6	3.56304	4.11189	2.05621	.49493E-02	-.77348E-01	.30450E-01	-.44104E-01	.38832E-01
7	2.92985	4.81185	2.46033	.11607E-01	-.62414E-01	.21053E-01	-.52146E-01	.56886E-01
8	3.56809	4.81185	2.46033	.10375E-01	-.61533E-01	.22700E-01	-.52146E-01	.56886E-01
9	1.95839	2.36879	-1.04983	.66523E-01	.18515E+00	.39039E-01	-.56348E-01	-.49656E-01
10	3.52183	2.36879	-1.04983	.16705E-01	.18064E+00	.86807E-02	-.56348E-01	-.49656E-01
11	2.47667	3.22373	-1.54343	.46986E-01	.76537E-01	.78011E-01	.57644E-02	-.82758E-01
12	3.54651	3.22373	-1.54343	.45037E-01	.65613E-01	.78516E-01	.57644E-02	-.82758E-01
13	2.82377	4.11189	-2.05621	.18352E-01	.54070E-01	.53548E-01	.43949E-01	-.47547E-01
14	3.56304	4.11189	-2.05621	.33221E-01	.32119E-01	.60967E-01	.43949E-01	-.47547E-01
15	2.92985	4.81185	-2.46033	.19116E-01	.32005E-01	.44612E-01	.43341E-01	-.22704E-01
16	3.56809	4.81185	-2.46033	.17010E-01	.32982E-01	.43647E-01	.43341E-01	-.22704E-01

CONTROL POINT COORDINATES FOR BIP+B (WING FRAME)

J	X(J)	Y(J)	Z(J)	THU(J)	THV(J)	THW(J)
17	1.71000	2.90725	.26764	0.	0.	0.
18	1.71000	2.32228	.67428	0.	0.	0.
19	1.71000	1.31938	.91568	0.	0.	0.
20	1.71000	.33985	1.03055	0.	0.	0.
21	1.71000	.33985	-1.03055	0.	0.	0.
22	1.71000	1.31938	-.91568	0.	0.	0.
23	1.71000	2.32228	-.67428	0.	0.	0.
24	1.71000	2.90725	-.26764	0.	0.	0.
25	3.51000	2.90725	.26764	0.	0.	0.
26	3.51000	2.32228	.67428	0.	0.	0.
27	3.51000	1.31938	.91568	0.	0.	0.
28	3.51000	.33985	1.03055	0.	0.	0.
29	3.51000	.33985	-1.03055	0.	0.	0.
30	3.51000	1.31938	-.91568	0.	0.	0.
31	3.51000	2.32228	-.67428	0.	0.	0.
32	3.51000	2.90725	-.26764	0.	0.	0.

Figure 34.- Continued.

LOADING INFORMATION

MACH NUMBER ■ .17000E+01
 ANGLE OF ATTACK ■ 10.000 DEGREES
 SIDE SLIP ANGLE ■ 0.000 DEGREES
 WING AREA ■ 14.88000
 REFERENCE AREA ■ 12.56700
 REFERENCE LENGTH ■ 3.46411
 EXPOSED WING SPAN ■ 7.20000
 MOMENT CENTER: XM ■ 16.80000
 ZM ■ 0.00000

U/WING TYPE LOADING PRESSURE

	TOTAL	FIN 1 OR R	FIN 2 OR L	FIN 3 OR U	FIN 4 OR O	INTERF. SHELL
DEFL. ANGLE DEG. ■		0.00000	0.00000	0.00000	0.00000	
CTHR ■ 0.		0.	0.	0.	0.	
CZ ■	.79276E+00	.15866E+00	.28077E+00	.28077E+00	.15866E+00	-.86142E-01
CY ■	.44409E-15	-.91614E-01	-.16210E+00	.16210E+00	.91614E-01	0.
CM ■	-.24358E+01	-.49867E+00	-.84948E+00	-.84948E+00	-.49867E+00	.26055E+00
CLN ■	.17764E-14	.28791E+00	.49044E+00	-.49044E+00	-.28791E+00	0.
CLL ■ 0.		-.23775E+00	.33936E+00	-.33936E+00	.23775E+00	0.

FOLLOWING ARE IN WIND-AXIS SYSTEM

CL ■	.78071E+00	.15627E+00	.27650E+00	.27650E+00	.15627E+00	-.84834E-01
CY*IND ■	.44409E-15	-.91614E-01	-.16210E+00	.16210E+00	.91614E-01	0.
CDI ■	.13766E+00	.27554E-01	.48755E-01	.48755E-01	.27554E-01	-.14058E-01
CDI/CL*2 ■	.22985E+00					
CM*IND ■	-.24358E+01	-.49867E+00	-.84948E+00	-.84948E+00	-.49867E+00	.26055E+00
CLN*IND ■	-.17764E-14	.32482E+00	.42406E+00	-.42406E+00	-.32482E+00	0.

NOTE: L.E. OF LEAD PANEL IN FIRST CHORDWISE ROW IS SUPERSONIC

Figure 34.- Continued.

PRESSURE LOADINGS EXCLUDE VORTEX INDUCED COMPONENTS PARALLEL TO WING SURFACES

VELOCITIES AND BERNOULLI PRESSURES AT CONTROL POINTS IMMEDIATELY ABOVE AND BELOW HORIZONTAL WING SURFACE											
J	X(J)	Y(J)	Z(J)	UTOTA	VTOTA	WTOTA	PRESSA	UTOTB	VTOTB	WTOTB	PRESSB
1	1.958387	2.368794	1.049832	-.060417	-.204603	-.114140	.095448	.039836	-.222632	-.114140	-.095567
2	3.521828	2.368794	1.049832	.029305	-.204153	-.128938	-.069335	-.039318	-.249308	-.128818	-.042954
3	2.476667	3.223734	1.543432	.121688	-.143424	-.148312	-.205019	-.103367	-.143647	-.148312	-.232944
4	3.546508	3.223734	1.543432	.003099	-.029810	-.099819	.016312	-.159358	-.094465	-.099819	.374784
5	2.823771	4.111893	2.056211	.213850	.015533	-.194012	.316096	-.196036	-.143093	-.194012	.438050
6	3.563037	4.111893	2.056211	.189108	.009019	-.198712	.288204	-.153581	-.192393	-.198712	.528900
7	2.929853	4.811851	2.460332	.199154	.047522	-.188801	-.299563	-.175940	-.172307	-.188801	.394577
8	3.568088	4.811851	2.460332	.142559	.029981	-.184547	-.222648	-.121809	-.153047	-.184547	.273116

VELOCITIES AND BERNOULLI PRESSURES AT CONTROL POINTS IMMEDIATELY TO RIGHT AND LEFT OF VERTICAL WING SURFACE											
J	X(J)	Y(J)	Z(J)	UTOTR	VTOTR	WTOTR	PRESSR	UTOTL	VTOTL	WTOTL	PRESSL
9	1.958387	2.368794	-1.049832	-.040991	-.169237	.373959	-.175641	.249192	-.148237	-.033052	-.372582
10	3.521828	2.368794	-1.049832	-.040396	-.140092	.362762	-.166626	.138586	-.140092	-.071779	-.265562
11	2.476667	3.223734	-1.543432	-.101947	-.198473	.293438	-.027210	.243875	-.198473	-.062978	-.369046
12	3.546508	3.223734	-1.543432	-.056798	-.131307	.299349	-.024477	.168714	-.131307	-.058905	-.276415
13	2.823771	4.111893	-2.056211	-.136484	.003334	.191478	.163305	.173188	.003334	-.145856	-.265484
14	3.563037	4.111893	-2.056211	-.129189	-.048806	.262599	.079400	.239683	-.048806	-.158975	-.345343
15	2.929853	4.811851	-2.460332	-.125169	-.018274	.196437	.135183	.163401	-.018274	-.168696	-.251941
16	3.568088	4.811851	-2.460332	-.088420	-.012932	.152513	.095937	.122440	-.012932	-.126693	-.193134

PRESSURE LOADINGS AT CONTROL POINTS

J	X(J)	Y(J)	Z(J)	DELTP.LTN.	DELTP.HERN.
1	1.958387	2.368794	1.049832	-.708505	-.191010
2	3.521828	2.368794	1.049832	.137247	.112289
3	2.476667	3.223734	1.543432	.450110	.437964
4	3.546508	3.223734	1.543432	.324916	.358472
5	2.823771	4.111893	2.056211	.819773	.754146
6	3.563037	4.111893	2.056211	.685458	.613104
7	2.929853	4.811851	2.460332	.750189	.694140
8	3.568088	4.811851	2.460332	.528737	.495764
9	1.958387	2.368794	-1.049832	.596305	.196941
10	3.521828	2.368794	-1.049832	.365964	.098936
11	2.476667	3.223734	-1.543432	.691645	.341835
12	3.546508	3.223734	-1.543432	.451023	.251738
13	2.823771	4.111893	-2.056211	.619343	.428789
14	3.563037	4.111893	-2.056211	.737743	.424743
15	2.929853	4.811851	-2.460332	.577138	.387123
16	3.568088	4.811851	-2.460332	.421718	.289071

Figure 34.- Continued.

LOADING INFORMATION

MACH NUMBER # .17000E+01
 ANGLE OF ATTACK # 10.000 DEGREES
 SIDE SLIP ANGLE # 0.000 DEGREES
 WING AREA # 14.8000
 REFERENCE AREA # 12.56700
 REFERENCE LENGTH # 3.46411
 EXPOSED WING SPAN H # 7.20000
 MOMENT CENTER: XM # 14.80000
 ZM # 0.00000

BERNOULLI TYPE LOADING PRESSURE

REFL. ANGLE DEG. #	TOTAL	FIN 1 OR R 0.00000	FIN 2 OR L 0.00000	FIN 3 OR U 0.00000	FIN 4 OR D 0.00000	INTERF. SHELL
CTHR # 0.	0.	0.	0.	0.	0.	0.
CZ # 0.	.28572E+00	.15017E+00	.13574E+00	.13576E+00	.15017E+00	-.86147E-01
CY # 0.	0.	-.86703E-01	-.78379E-01	.78379E-01	.86703E-01	0.
CM # 0.	-.15093E+01	-.47164E+00	-.41326E+00	-.41326E+00	-.47164E+00	.26055E+00
CLN # 0.	0.	.27232E+00	.23859E+00	-.23859E+00	-.27232E+00	0.
CLL # 0.	0.	-.22411E+00	.17658E+00	-.17658E+00	.22411E+00	0.

FOLLOWING ARE IN WIND-AXIS SYSTEM

CL #	.47434E+00	.14749E+00	.13369E+00	.13369E+00	.14749E+00	-.86147E-01
CY-IND #	0.	-.86703E-01	-.78379E-01	.78379E-01	.86703E-01	0.
CDI #	.84344E+01	.26074E-01	.23574E-01	.23574E-01	.26074E-01	-.14959E-01
CNT/CL**2 #	.36862E+00					
CM-IND #	-.15093E+01	-.47164E+00	-.41326E+00	-.41326E+00	-.47164E+00	.26055E+00
CLN-IND #	0.	.30710E+00	.20431E+00	-.20431E+00	-.30710E+00	0.

NOTE: I.E. OF LEAD PANEL IN FIRST CHORDWISE POINTS SUPERSONIC

 AFT OF LEADING EDGE OF FIN ROOTCHORDS

PRESSURE COEFFICIENTS AT PRINTS ON BODY MERIDIANS

J	THETA, DEG.	XB	YB	ZB	UTOT	VTOT	WTOT	CP, LIN.	CP, HERN.	NR/DX	P/PINF, BERN.	P/PINF, LIN.
BODY RING# 1												
1	5,63625	26,11000	2,90725	.26764	.06120	-.00056	-.06231	-.00247	.01547	0,00000	1,03129	.99500
2	16,90875	26,11000	2,32228	.67428	.02805	-.06340	-.18355	-.05691	-.03014	0,00000	.93903	.89047
3	50,63625	26,11000	1,31938	.91568	-.03987	.14164	-.18516	.07973	.09247	0,00000	1,18768	1,16130
4	84,36375	26,11000	.33945	1,03055	.01402	.00238	-.21697	-.02943	-.00133	0,00000	.99732	.93965
5	99,09125	26,11000	.33945	-1,03055	.05091	.03767	-.14973	-.10182	-.07077	0,00000	.95684	.79402
6	331,81875	26,11000	1,31938	-.91568	.01217	.05166	-.13975	-.02435	-.00221	0,00000	1,00448	.95075
7	343,09125	26,11000	2,32228	.67428	.23305	.00596	-.04719	-.46610	-.34416	0,00000	.30376	.05708
8	354,36375	26,11000	2,90725	-.26764	.11716	-.04363	-.05913	-.23432	-.19382	0,00000	.60789	.52597
BODY RING# 2												
1	5,63625	27,91000	2,90725	.26764	-.04536	.21072	-.21777	.09073	.07482	0,00000	1,15136	1,18354
2	16,90875	27,91000	2,32228	.67428	-.05142	-.01007	-.16570	.10365	.14193	0,00000	1,28712	1,20968
3	50,63625	27,91000	1,31938	.91568	-.02660	.13444	-.17723	.05321	.04675	0,00000	1,13504	1,10764
4	84,36375	27,91000	.33945	1,03055	-.04515	-.00781	-.19347	.09031	.12675	0,00000	1,25602	1,18269
5	99,09125	27,91000	.33945	-1,03055	.00890	-.00809	-.14352	-.01149	.01765	0,00000	1,01571	.97595
6	331,81875	27,91000	1,31938	-.91568	.00849	.02511	-.13126	-.01498	.01191	0,00000	1,02228	.96564
7	343,09125	27,91000	2,32228	.67428	.16337	.06735	-.04384	-.32673	-.26440	0,00000	.44532	.33902
8	354,36375	27,91000	2,90725	-.26764	.14197	-.06378	-.07977	-.28393	-.22945	0,00000	.53582	.47560

Figure 34.- Concluded.

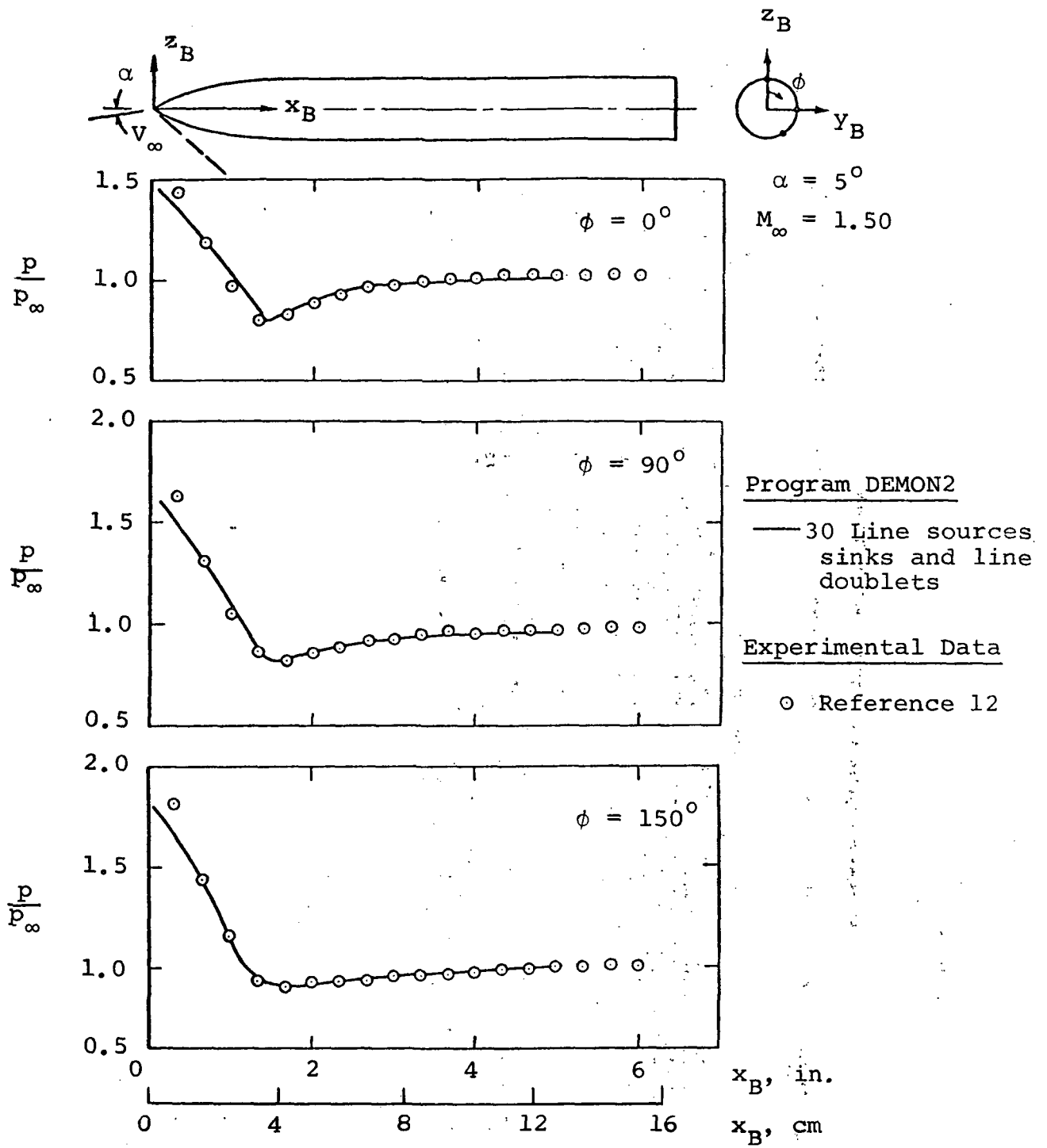
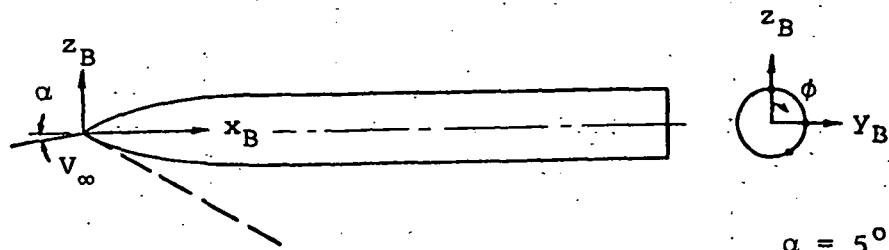


Figure 35.- Pressure distribution on ogive cylindrical body in uniform flow; $M_\infty = 1.50$.



$\alpha = 5^\circ$
 $M_\infty = 2.0$

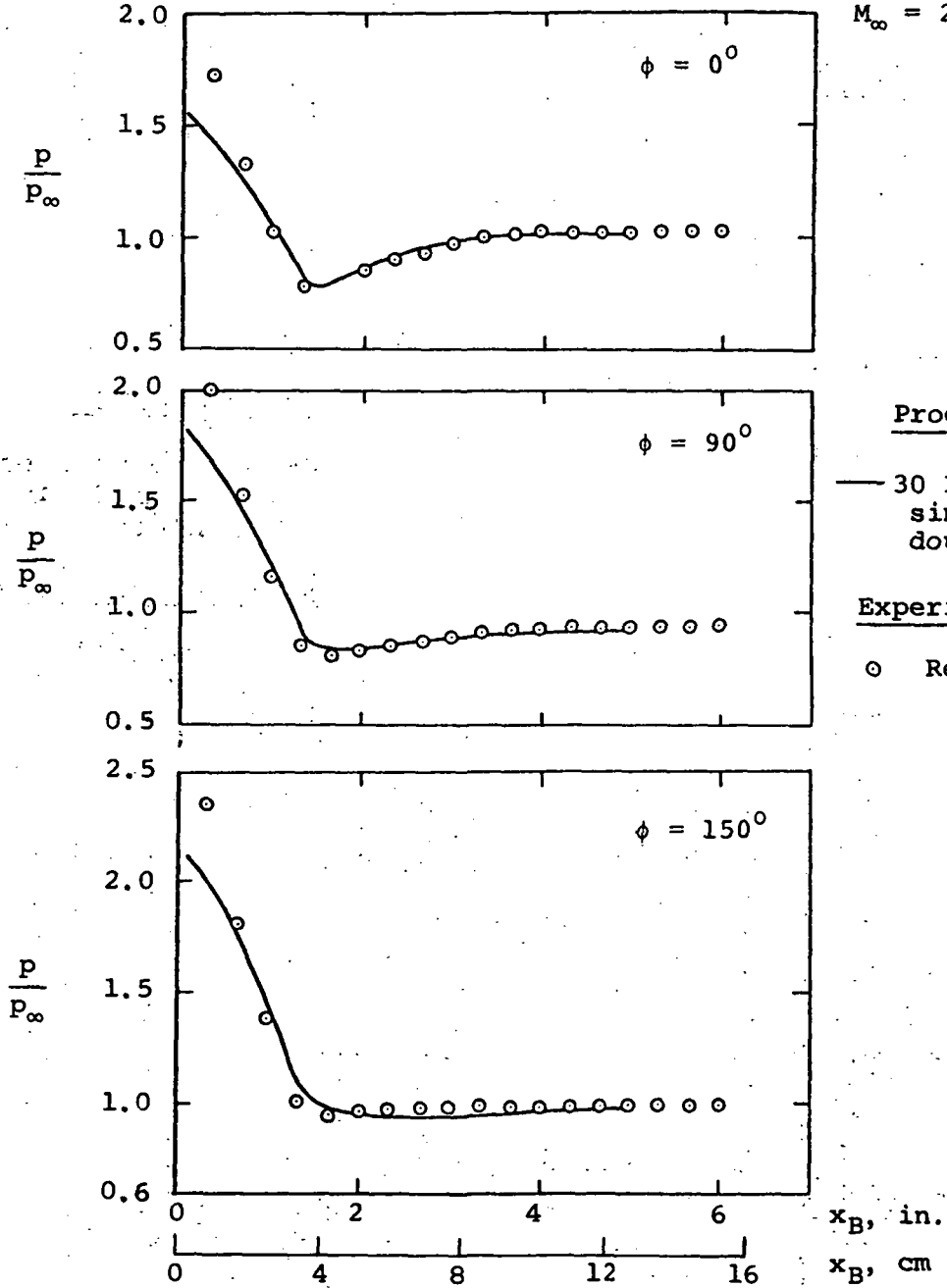
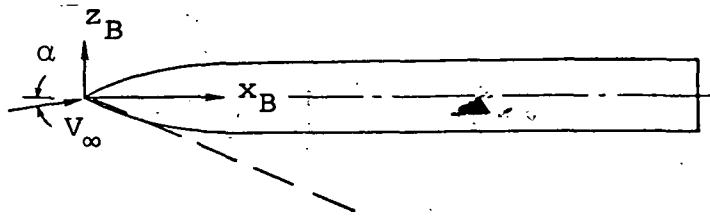
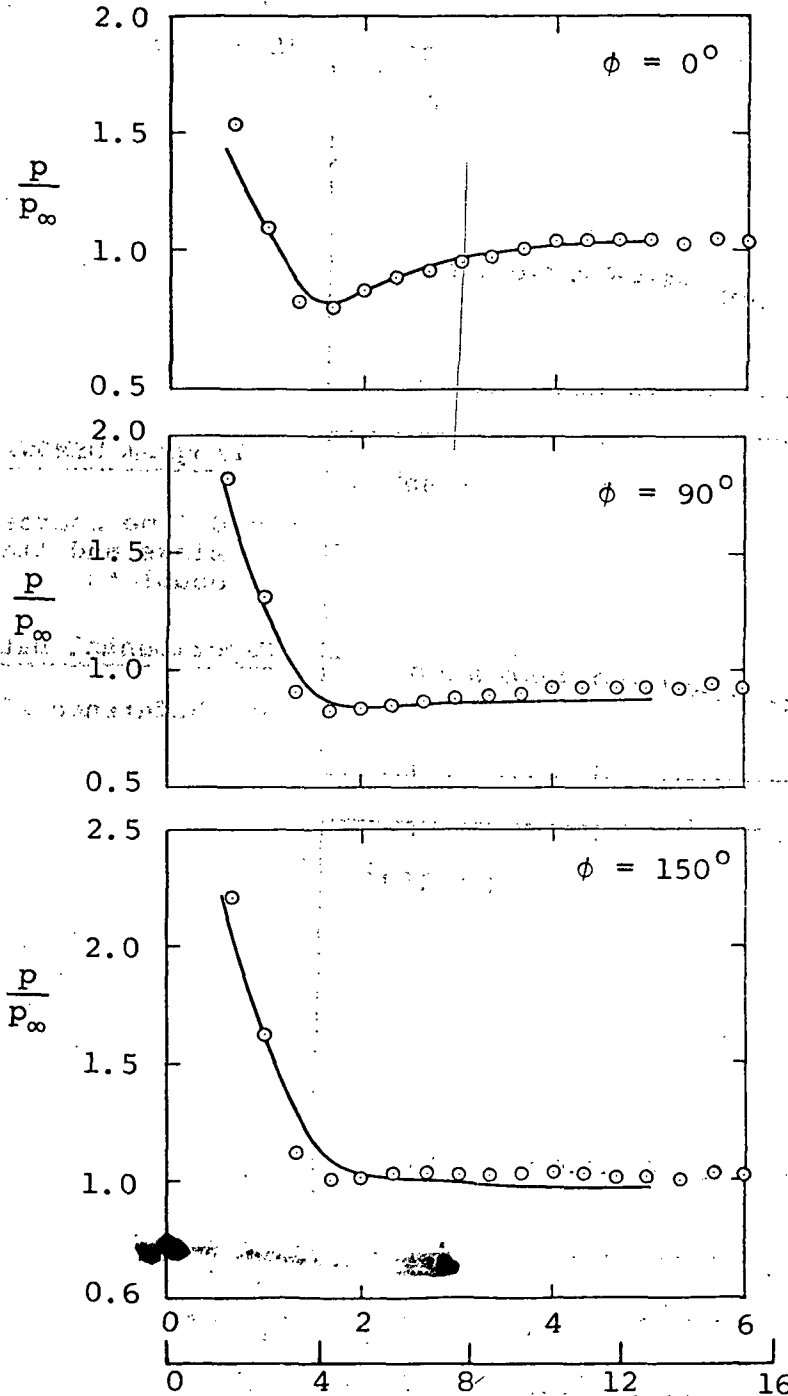


Figure 36.- Pressure distribution on ogive cylindrical body in uniform flow; $M_\infty = 2.0$.



$\alpha = 5^\circ$

$M_\infty = 2.5$



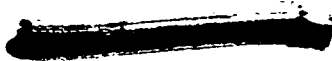
Program DEMON2

— 30 Line sources/
sinks and line
doublets

Experimental Data

○ Reference 14

Figure 37.- Pressure distribution on ogive cylindrical body in uniform flow; $M_\infty = 2.5$.

1. Report No. NASA CR-3122		2. Government Accession No.		3. Recipient's Catalog No.	
4. Title and Subtitle COMPUTER PROGRAMS FOR CALCULATING PRESSURE DISTRIBUTIONS INCLUDING VORTEX EFFECTS ON SUPERSONIC MONOPLANE OR CRUCIFORM WING-BODY-TAIL COMBINATIONS WITH ROUND OR ELLIPTICAL BODIES				5. Report Date April 1979	
				6. Performing Organization Code	
7. Author(s) Marnix F. E. Dillenius and Jack N. Nielsen				8. Performing Organization Report No. NEAR TR 154	
9. Performing Organization Name and Address Nielsen Engineering & Research, Inc. 510 Clyde Avenue Mountain View, CA 94043				10. Work Unit No.	
				11. Contract or Grant No. NAS1-14495	
12. Sponsoring Agency Name and Address National Aeronautics & Space Administration Langley Research Center Hampton, Virginia 23665				13. Type of Report and Period Covered Contractor Report 7/1/76-7/1/78	
				14. Sponsoring Agency Code	
15. Supplementary Notes Langley Technical Monitor: Wallace C. Sawyer Final Report					
16. Abstract Computer programs are presented capable of calculating detailed aerodynamic loadings and pressure distributions acting on pitched and rolled supersonic missile configurations which utilize bodies of circular or elliptical cross sections. The applicable range of angle of attack is up to 20°, and the Mach number range is 1.3 to about 2.5. Effects of body and fin vortices are included in the methods, as well as arbitrary deflections of canard or fin panels.					
17. Key Words (Suggested by Author(s)) cruciform missiles supersonic flow, elliptical bodies wing-body interference wing-body-tail interference missile aerodynamics				18. Distribution Statement 	
19. Security Classif. (of this report) Unclassified		20. Security Classif. (of this page) Unclassified		21. No. of Pages 633	22. Price*

