

NASA CR-177,980

NASA Contractor Report 177980

ICASE REPORT NO. 85-41

NASA-CR-177980
19860004961

ICASE

QUALITATIVE PROPERTIES OF LARGE
BUCKLED STATES OF SPHERICAL SHELLS

Ke-Gang Shih
Stuart S. Antman

NASA Contract No. NAS1-17070
September 1985

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Hampton Virginia 23665



NF01009

1 Report No NASA CR-177980 ICASE Report No. 85-41		2 Government Accession No		3 Recipient's Catalog No	
4 Title and Subtitle QUALITATIVE PROPERTIES OF LARGE BUCKLED STATES OF SPHERICAL SHELLS				5 Report Date September 1985	
				6 Performing Organization Code	
7 Author(s) Ke-Gang Shih and Stuart S. Antman				8 Performing Organization Report No 85-41	
				10 Work Unit No	
9 Performing Organization Name and Address Institute for Computer Applications in Science and Engineering Mail Stop 132C, NASA Langley Research Center Hampton, VA 23665				11 Contract or Grant No NAS1-17070	
				13 Type of Report and Period Covered Contractor Report	
12 Sponsoring Agency Name and Address National Aeronautics and Space Administration Washington, D.C. 20546				14 Sponsoring Agency Code 505-31-83-01	
15 Supplementary Notes Langley Technical Monitor: Submitted to Archive for Rational J. C. South Jr. Mechanics and Analysis Final Report					
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17 Key Words (Suggested by Author(s)) shell buckling bifurcation			18 Distribution Statement 59 - Mathematical & Computer Sciences 31 - Engineering Unclassified - Unlimited		
19 Security Classif (of this report) Unclassified	20 Security Classif (of this page) Unclassified	21 No of Pages 75	22 Price A04		

QUALITATIVE PROPERTIES OF LARGE BUCKLED STATES
OF SPHERICAL SHELLS

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Abstract

A system of 6th-order quasi-linear Ordinary Differential Equations is analyzed to show the global existence of axisymmetrically buckled states. A surprising nodal property is obtained which shows that everywhere along a branch of solutions that bifurcates from a simple eigenvalue of the linearized equation, the number of simultaneously vanishing points of both shear resultant and circumferential bending moment resultant remains invariant, provided that a certain auxiliary condition is satisfied.

Research was supported in part by the National Aeronautics and Space Administration under NASA Contract No. NAS1-17070 while the author was in residence at ICASE, NASA Langley Research Center, Hampton, VA 23665.

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1. INTRODUCTION

In this paper we study the global qualitative behavior of axisymmetric buckled states of homogeneous isotropic nonlinearly elastic shells that can suffer flexure, compression, and shear. Our model is geometrically exact in the sense that a geometric quantity, such as $\sin\theta$, is not replaced by an approximation, such as θ or $\theta - \theta^3/6$. (The usual justification for such a replacement is that θ is known to be small for the physical situation under study. But it is quite possible that a mathematical model with exact geometry permits only small solutions, while those with approximate geometry have large solutions.) We allow the material properties to be described by a very general class of nonlinear constitutive relations. Consequently our governing equations form a quasilinear sixth-order system of ordinary differential equations.

Our main result is that nontrivial branches of solutions pairs can be globally characterized by a novel nodal pattern relating shear and bending effects. The detection of this pattern is greatly aided by the generality of our theory, which does not obscure the simple mathematical structure of the governing equations with approximate geometrical relations.

Indeed, the beautiful numerical results of Bauer, Reiss, & Keller (1970) for their technical theory of shells indicate that their solution branches do not enjoy the nodal properties we discover for our exact theory. We surmise that no such technical theory would have these properties. Consequently,

the nature of the bifurcation diagram away from the trivial solution for these technical theories could differ markedly from ours.

There is a large literature on the buckling of spherical shells. The articles by Bauer, Reiss, & Keller (1970), Antman (1971), Lange & Kriegsmann (1981), and Shih (1985) give extensive lists of references. Our results differ markedly from those developed in these references (except for the work of Antman) by virtue of the generality of our theory and the global character of our theorems.

The heart of our paper is in Sections 5 and 6. In Section 5 we show that our equations meet the hypotheses of Rabinowitz's Global Bifurcation Theorem. In Section 6 we prove a basic uniqueness theorem that enables us to show that solution branches preserve the nodal pattern they inherit from the trivial branch. The use of the isotropy of the shell material is crucial in enabling us to overcome the difficulties posed by the polar singularities.

Notation. Partial derivatives are denoted by subscripts. Ordinary derivatives with respect to the variable s are denoted by primes. If f and g are functions of x and y , then $\frac{\partial(f,g)}{\partial(x,y)}$ denotes the matrix of partial derivatives of f and g with respect to x and y .

§2. FORMULATION OF THE GOVERNING EQUATIONS.

Let $\{ \underline{i}, \underline{j}, \underline{k} \}$ be a fixed right-handed orthonormal basis for the Euclidean 3-space E^3 . For each ϕ in R we define

$$(2.1) \quad \underline{e}_1(\phi) = \cos \phi \underline{i} + \sin \phi \underline{j}, \quad \underline{e}_2(\phi) = -\sin \phi \underline{i} + \cos \phi \underline{j}, \\ \underline{e}_3 = \underline{k} \quad .$$

To each $(s, \phi) \in [0, \pi] \times [0, 2\pi]$ there corresponds exactly one point on the sphere of radius 1 centered at the origin with position vector of the form

$$(2.2) \quad \underline{r}_*(s, \phi) = \sin s \underline{e}_1(\phi) - \cos s \underline{e}_3 \quad .$$

Note that s measures the arc length to $\underline{r}_*(s, \phi)$ from the south pole of the sphere. This convention will simplify some of the formulas. We interpret the sphere defined by (2.2) to be the natural reference state of the midsurface of a spherical shell. The coordinates (s, ϕ) identify material points on this surface.

An axisymmetric-configuration of a spherical shell that can suffer flexure, extension, and shear is determined by a pair of vector functions

$$(2.3) \quad (s, \phi) \mapsto \underline{r}(s, \phi), \quad \underline{b}(s, \phi)$$

with $\underline{r}(s, \cdot)$ and $\underline{b}(s, \cdot)$ having period 2π and with

$$(2.4) \quad \begin{aligned} \underline{r}(s, \phi) \cdot \underline{e}_2(\phi) &= 0, \\ \underline{b}(s, \phi) \cdot \underline{e}_2(\phi) &= 0. \\ |\underline{b}(s, \phi)| &= 1. \end{aligned}$$

The reference configuration of the shell is given by $\underline{r} = \underline{r}_*$, $\underline{b} = -\underline{r}_*$. The vector $\underline{b}(s, \phi)$ is interpreted as characterizing the deformed configuration of the material points that in the natural state of the shell lie along the ray determined by $\underline{r}_*(s, \phi)$.

We set

$$(2.5) \quad \underline{r}(s, \phi) \equiv r(s)\underline{e}_1(\phi) + z(s)\underline{k},$$

$$(2.6) \quad \begin{aligned} \underline{a}(s, \phi) &\equiv \cos \psi(s)\underline{e}_1(\phi) + \sin \psi(s)\underline{k}, \\ \underline{b}(s, \phi) &\equiv -\sin \psi(s)\underline{e}_1(\phi) + \cos \psi(s)\underline{k}, \end{aligned}$$

$$(2.7) \quad \underline{r}_s(s, \phi) \equiv v(s)\underline{a}(s, \phi) + \eta(s)\underline{b}(s, \phi),$$

$$(2.8) \quad \begin{aligned} \tau(s) &\equiv \frac{r(s)}{\sin s}, \\ \mu(s) &\equiv \psi'(s) - 1, \\ \sigma(s) &\equiv \frac{\sin \psi(s)}{\sin s} - 1. \end{aligned}$$

The strain variables for our problem are

$$(2.9) \quad \underline{w} \equiv (v, \tau, \eta, \mu, \sigma).$$

Let $\underline{n}_1(s, \phi)$ and $\underline{m}_1(s, \phi)$ denote the resultant contact force and contact couple per unit reference length

of the circle $\phi \mapsto \underline{r}_*(s, \phi)$ of radius $\sin s$ that are exerted across this circular section at $\underline{r}_*(s, \phi)$. Let $\underline{n}_2(s, \phi)$ and $\underline{m}_2(s, \phi)$ denote the resultant contact force and contact couple per unit reference length of the circle $s \mapsto \underline{r}_*(s, \phi)$ of radius 1 that are exerted across this section at $\underline{r}_*(s, \phi)$. Since we seek axisymmetric solutions, we require these resultants to have the form

$$(2.10) \quad \underline{n}_1(s, \phi) = \hat{N}(s)\underline{a}(s, \phi) + \hat{H}(s)\underline{b}(s, \phi) \quad ,$$

$$(2.11) \quad \underline{n}_2(s, \phi) = \hat{T}(s)\underline{e}_2(\phi) \quad ,$$

$$(2.12) \quad \underline{m}_1(s, \phi) = -\hat{M}(s)\underline{e}_2(\phi) \quad ,$$

$$(2.13) \quad \underline{m}_2(s, \phi) = \hat{\Sigma}(s)\cos \psi(s)\underline{e}_1(\phi) + \hat{L}(s)\underline{k} \quad .$$

Then the equilibrium equations for the shell under an external hydrostatic pressure of intensity λ per unit actual area are

$$(2.14) \quad [\sin s\hat{N}(s)]' - \hat{T}(s)\cos \psi(s) - \sin s\hat{H}(s)\psi'(s) - \lambda r(s)\eta(s) = 0,$$

$$(2.15) \quad [\sin s\hat{H}(s)]' + \hat{T}(s)\sin \psi(s) + \sin s\hat{N}(s)\psi'(s) + \lambda r(s)\nu(s) = 0,$$

$$(2.16) \quad [\sin s\hat{M}(s)]' - \hat{\Sigma}(s)\cos \psi(s) + \sin s[\nu(s)\hat{H}(s) - \eta(s)\hat{N}(s)] = 0.$$

We can combine (2.14) and (2.15) to obtain

$$(2.17) \quad \{\sin s[\sin \psi(s)\hat{N}(s) + \cos \psi(s)\hat{H}(s)] + \lambda r(s)^2/2\}' = 0,$$

$$(2.18) \quad \{ \sin s [-\cos \psi(s) \hat{N}(s) + \sin \psi(s) \hat{H}(s)] \}' + \\ + \hat{T}(s) + \lambda r(s) z'(s) = 0 \quad .$$

The material of the shell is homogeneous and non-linearly elastic if there are constitutive functions N , T , H , M , Σ such that

$$(2.19) \quad \hat{N}(s) = N(\tilde{w}(s)), \quad \text{etc.},$$

when (2.3)-(2.8) hold.

We assume that these constitutive functions are thrice continuously differentiable on their common domain of definition

$$(2.20) \quad \mathcal{D} = \{ \tilde{w} \in R^5 : v > h |\mu+1|, \quad \tau > h |\sigma+1| \}$$

where h is a given number in $(0,1)$, which may be interpreted as half the thickness of the shell. The inequalities in (2.20) ensure that in a standard three-dimensional interpretation of our deformation variables the local ratio of deformed to reference volume never be zero.

We require the constitutive functions to satisfy the monotonicity conditions:

$$(2.21) \quad \frac{\partial(N, H, M)}{\partial(v, \eta, \mu)}, \quad \frac{\partial(T, \Sigma)}{\partial(\tau, \sigma)} \quad \text{are positive-definite.}$$

(This is the strict form of the strong-ellipticity condition for axisymmetric deformations of axisymmetric shells. Cf. Antman (1978).) These conditions ensure, e.g., that an increase in the bending strain μ is accompanied by a corresponding increase in the bending couple M . We also use special forms of the following very natural inequalities

$$(2.22) \quad N_\nu + N_\tau > 0 \quad , \quad T_\tau + T_\nu > 0 \quad .$$

We impose compatible growth conditions ensuring that extreme strains are accompanied by extreme resultants:

$$(2.23) \quad \begin{aligned} N(\tilde{w}) &\rightarrow +\infty \text{ as } \nu \rightarrow \infty && \text{if } \tau - h|1+\sigma| \text{ has a positive} \\ &&& \text{lower bound and if } \eta, \mu, \sigma \text{ are bounded,} \\ N(\tilde{w}) &\rightarrow -\infty \text{ as } \nu \rightarrow h|1+\mu| && \text{if } \tau \text{ is bounded above and} \\ &&& \text{if } \eta, \mu, \sigma, \text{ are bounded,} \\ T(\tilde{w}) &\rightarrow +\infty \text{ as } \tau \rightarrow \infty && \text{if } \nu - h|1+\mu| \text{ has a positive} \\ &&& \text{lower bound and if } \eta, \mu, \sigma \text{ are bounded,} \\ T(\tilde{w}) &\rightarrow -\infty \text{ as } \nu \rightarrow h|1+\sigma| && \text{if } \nu \text{ is bounded above} \\ &&& \text{and if } \eta, \mu, \sigma \text{ are bounded,} \\ H(\tilde{w}) &\rightarrow \pm\infty \text{ as } \eta \rightarrow \pm\infty && \text{if } (\nu, \tau, \mu, \sigma) \text{ lies in a} \\ &&& \text{compact subset of } \{(\nu, \tau, \mu, \sigma) : \nu > h|1+\sigma|, \\ &&& \tau > h|1+\sigma|\} \\ M(\tilde{w}) &\rightarrow \pm\infty \text{ as } \mu \rightarrow \pm\infty && \text{if } \nu > h|1+\sigma| \text{ and if } (\tau, \eta, \mu) \\ &&& \text{lies in a compact subset of } \{(\tau, \eta, \mu) : \\ &&& \tau > h|1+\sigma|\} \end{aligned}$$

$\Sigma(\tilde{w}) \rightarrow \pm \infty$ as $\sigma \rightarrow \pm \infty$ if $\tau > h|1+\sigma|$ and if (ν, η, μ) lies in a compact subset of $\{(\nu, \eta, \mu) : \nu > h|1+\sigma|\}$.

We finally require that the shell be isotropic and have a stress-free natural state :

$$\begin{aligned}
 (2.24) \quad & \eta \mapsto H(\tilde{w}) \text{ is odd, } \eta \mapsto N(\tilde{w}), T(\tilde{w}), M(\tilde{w}), \Sigma(\tilde{w}) \text{ are even,} \\
 & M(\tilde{w}) = 0 = \Sigma(\tilde{w}) \quad \text{if } \mu = 0 = \sigma, \\
 & N_{\sigma}(\tilde{w}) = N_{\mu}(\tilde{w}) = T_{\sigma}(\tilde{w}) = T_{\mu}(\tilde{w}) = 0 \quad \text{if } \eta = \mu = \sigma = 0, \\
 & N(\nu, \tau, 0, \mu, \sigma) = T(\tau, \nu, 0, \sigma, \mu), \\
 & M(\nu, \tau, 0, \mu, \sigma) = \Sigma(\tau, \nu, 0, \sigma, \mu), \\
 & N(1, 1, 0, 0, 0) = T(1, 1, 0, 0, 0) = 0.
 \end{aligned}$$

Our boundary conditions essentially require that the deformation be regular at the poles and that there be no net rigid displacement in the z -direction :

$$(2.25a,b) \quad r(0) = 0 = r(\pi),$$

$$(2.26a,b) \quad \eta(0) = 0 = \eta(\pi),$$

$$(2.27a,b) \quad \psi(0) = 0, \quad \psi(\pi) = \pi.$$

$$(2.28) \quad \int_0^{\pi} z(s) ds = 0.$$

Substituting (2.25a) into the integral of (2.17) we obtain

$$(2.29) \quad \sin s [\hat{N}(s) \sin \psi(s) + \hat{H}(s) \cos \psi(s)] + \lambda r(s)^2 / 2 = 0.$$

If \hat{N} and \hat{H} are bounded and if $\lambda > 0$, then (2.27) implies that (2.25b) holds. If we further assume that τ is bounded, then (2.29) and (2.27) imply that $\hat{H}(0) = 0 = \hat{H}(\pi)$. The properties of H then ensure that (2.26) holds. By comparing the integrals of (2.18) over $[0, s]$ and $[s, \pi]$ we readily obtain

$$(2.30) \quad \int_0^\pi \hat{T}(s) \, ds = -\lambda \int_0^\pi r(s) z'(s) \, ds .$$

Note that the integral on the right side is the signed area between the curve (r, z) and the k -axis.

Our boundary value problem consists of the strain configuration equations (2.5)-(2.8), the equilibrium equations (2.14)-(2.16) the constitutive equations (2.19) and the boundary conditions (2.25)-(2.28). A regular solution of the remaining equations would automatically satisfy (2.25b) and (2.26).

The shell theory we employ was originated by the Cosserats (1909). (Cf. Naghdi (1972) and Libai & Simmonds (1983).) Our formulation was foreshadowed by several papers of Reissner, typical of which is his paper of 1963. The variables we employ, and the very simple form of constitutive equations they induce, were introduced by Antman (1971).

§3. TRIVIAL SOLUTIONS.

We now seek solutions of our boundary value problem in which the shell remains spherical, unsheread, and uniformly stretched, so that $v = \tau = k(\text{const})$, $\eta = 0$, $\psi(s) = s$. Thus $\mu = 0 = \sigma$. Under these conditions, (2.22) reduces (2.14)-(2.17) to

$$(3.1) \quad N(k,k,0,0,0) = T(k,k,0,0,0) = -\lambda k^2/2 \quad .$$

Then (2.22) and (2.23) imply that $k \mapsto N(k,k,0,0,0) + \lambda k^2/2$ strictly increases from $-\infty$ to ∞ as k increases from 0 to ∞ provided that $\lambda \geq 0$. Thus (3.1) has a unique solution for k , denoted $k(\lambda)$ with

$$(3.2) \quad [0, \infty) \ni \lambda \mapsto k(\lambda) \in (0, 1]$$

thrice continuously differentiable and strictly decreasing .

§ 4. THE LINEARIZED EQUATIONS.

We adopt the convention that if R is any constitutive function (such as N , N_ν , \dots), then

$$(4.1) \quad R^0(\lambda) \equiv R(k(\lambda), k(\lambda), 0, 0, 0).$$

The linearization of our boundary value problem about the trivial solution is equivalent to the following boundary value problem for the linearized variables v_1 , η_1 , ψ_1 :

$$(4.2) \quad r_1(s) = \int_0^s \{v_1(t) \cos t - [\eta_1(t) + k\psi_1(t)] \sin t\} dt = \\ = \tau_1(s) \sin s \quad ,$$

$$(4.3) \quad N_\nu^0 [(v_1 \sin s)' - \tau_1 \cos s] = [(N_\tau^0 + H_\eta^0 + \lambda k)\eta_1 + \\ + (N_\tau^0 k + \lambda k^2/2)\psi_1] \sin s \quad ,$$

$$(4.4) \quad H_\eta^0 (\eta_1 \sin s)' = -(N_\nu^0 + N_\tau^0 + \lambda k) (v_1 + \tau_1) \sin s + \\ + (\lambda k^2/2) (\psi_1 \sin s)' \quad ,$$

$$(4.5) \quad M_\mu^0 [(\psi_1' \sin s) - \psi_1/\sin s] + (M_\mu^0 - M_\sigma^0) \psi_1 \sin s = \\ = -[H_\eta^0 k + \lambda k^2/2] \eta_1 \sin s \quad ,$$

$$(4.6) \quad \eta_1(0) = 0 = \eta_1(\pi), \quad \psi_1(0) = 0 = \psi_1(\pi) \quad ,$$

$$(4.7) \quad \int_0^\pi z_1(s) ds \equiv \int_0^\pi \{v_1(t) \sin t + [\eta_1(t) + k\psi_1(t)] \cos t\} dt = 0 \quad .$$

In deriving this system, we relied crucially on (2.24).

From this system, we wish to extract a system for η_1 and ψ_1 alone. To accomplish this efficiently we write (4.3), (4.4), and the derivative of (4.4) in the form

$$(4.8) \quad \begin{aligned} (\nu_1 \sin s)' - \tau_1 \cos s &= f, & (\nu_1 + \tau_1) \sin s &= g, \\ (\nu_1 \sin s)' + \nu_1 \cos s &= h, \end{aligned}$$

from which we immediately deduce that

$$(4.9) \quad g = (h-f) \tan s .$$

We write out this equation, replacing $(\psi_1' \sin s)' - \psi_1 / \sin s$ by its expression from (4.5) and supplement the resulting equation with (4.5), (4.6) to get the system

$$(4.10a) \quad (L\eta_1)(s) + A\eta_1(s) \sin s = -a\psi_1(s) \sin s ,$$

$$(4.10b) \quad (L\psi_1)(s) + B\psi_1(s) \sin s = -b\eta_1(s) \sin s ,$$

$$(4.11) \quad \eta_1(0) = 0 = \eta_1(\pi) , \quad \psi_1(0) = 0 = \psi_1(\pi) ,$$

where

$$(4.12) \quad (Lu)(s) \equiv [u'(s) \sin s]' - u(s) / \sin s ,$$

$$(4.13) \quad A = (H_\eta^0)^{-1} [\frac{1}{2} \lambda k^2 b + (N_\nu^0 + N_\tau^0 + \lambda k) (N_\nu^0)^{-1} (N_\tau^0 - N_\nu^0 + \lambda k + H_\eta^0)] ,$$

$$a = (H_{\eta}^0)^{-1} \left[\frac{1}{2} \lambda k^2 B + (N_{\nu}^0 + N_{\tau}^0 + \lambda k) (N_{\nu}^0)^{-1} (k N_{\tau}^0 - k N_{\nu}^0 + \frac{1}{2} \lambda k^2) \right] ,$$

$$B \equiv 1 - M_{\sigma}^0 / M_{\mu}^0 , \quad b \equiv [H_{\eta}^0 k + \lambda k^2 / 2] / M_{\mu}^0 .$$

We now convert (4.10), (4.11) to a problem for a single complex-valued function

$$(4.14) \quad \phi = \alpha \eta_1 + \beta \psi_1$$

where α and β are complex constants to be adjusted so that (4.10a,b) can be combined into a single complex equation. Thus we require that

$$(4.15) \quad (\alpha A + \beta b) \eta_1 + (\alpha a + \beta B) \psi_1 = C \phi = C (\alpha \eta_1 + \beta \psi_1)$$

where C is a complex constant to be determined. It follows from (4.15) that

$$(4.16) \quad \alpha A + \beta b = \alpha C , \quad \alpha a + \beta B = \beta C$$

so that

$$(4.17) \quad \alpha \alpha^2 + (B-A) \alpha \beta - b \beta^2 = 0 .$$

Using (4.15) we reduce (4.10), (4.11) to

$$(4.18) \quad (L\phi)(s) + C\phi \sin s = 0, \quad \phi(0) = 0 = \phi(\pi),$$

which has a nontrivial solution if and only if

$$(4.19) \quad C = n(n+1), \quad n = 1, 2, \dots$$

in which case

$$(4.20) \quad \phi(s) = \phi_n(s) = \text{const. } P_n^1(\cos s)$$

where P_n^1 is the associated Legendre function of the first kind of degree n and order 1. When (4.19) holds, system (4.16) has a nontrivial solution if and only if

$$(4.21) \quad g(\lambda; n) \equiv [A - n(n+1)][B - n(n+1)] - ab = 0.$$

Note that A, B, a, b each depends on the eigenvalue parameter λ . For a given integer n there can be none, one, or many real solutions λ of (4.21). Noting that $N^0(\lambda) = -\lambda k(\lambda)^2/2$, we could readily fashion conditions on the constitutive assumptions to ensure any of these possibilities. (Cf. Antman & Rosenfeld (1978) for a discussion of this issue.) We limit our attention to positive solutions λ of (4.21). Negative solutions correspond to shear instabilities. (Cf.

Antman & Carbone (1977).)

For $\lambda > 0$, (2.21) implies that $b > 0$. Thus (4.16) has no nontrivial solutions (α, β) with $\alpha = 0$. We can accordingly adopt the special normalization that $\alpha = 1$. In this case, the roots β of (4.17) are

$$(4.22) \quad \beta_{\pm} \equiv \frac{B-A \pm \sqrt{(A-B)^2 + 4ab}}{2b} = \frac{B-A \pm [A+B-2n(n+1)]}{2b} ,$$

the second equality coming from (4.21). Thus β_{\pm} are real when (4.21) holds. In this case, β_{\pm} are distinct if and only if

$$(4.23) \quad A+B \neq 2n(n+1) .$$

When (4.21) and (4.23) hold, (4.14) and (4.20) reduce to a system of the form

$$(4.24) \quad \eta_1 + \beta_{\pm} \psi_1 = D_{\pm} P_n^1(\cos s) .$$

If we take D_{\pm} real and not both 0, then the distinctness of β_{\pm} ensures that (4.24) can be solved uniquely for η_1 and ψ_1 . These solutions are proportional to $P_n^1(\cos s)$. To find D_{\pm} , i.e., to find the constants of proportionality, we normalize ψ_1 by setting

$$(4.25) \quad \psi_1(s) = P_n^1(\cos s) , \quad \eta_1(s) = EP_n^1(\cos s) .$$

Then a comparison of (4.10) and (4.11) with (4.18) implies that

$$(4.26) \quad A + a/E = n(n+1) = B + bE \quad .$$

whence

$$(4.27) \quad E = \frac{n(n+1)-B}{b} = \frac{a}{n(n+1)-A} \quad .$$

The compatibility of these two expressions for E is ensured by (4.21) .

Now we study the special case that

$$(4.28) \quad A + B = 2n(n+1), \quad n = 1, 2, \dots \quad .$$

Then (4.22) implies that β is unique with

$$(4.29a,b) \quad 2b\beta = B - A, \quad b\beta^2 = a \quad .$$

Consequently (4.20) yields

$$(4.30) \quad \eta_1 + \beta\psi_1 = DP_n^1(\cos s) \quad .$$

Note that (4.29b) implies that there are no such solutions if $a < 0$.

First we treat the even more special subcase that

$$(4.31) \quad A = B = n(n+1) \quad .$$

Then $\beta = 0$, $\eta_1 = DP_n^1(\cos s)$. Moreover (4.16) implies that $a = 0$. Since $b > 0$, the alternative theorem implies that (4.10b) has no solution unless $D = 0$ and hence $\eta_1 = 0$. In this case, $\psi_1 = \text{const } P_n^1(\cos s)$. Note that if we make the eminently reasonable assumption that $B < 2$, then (4.31) cannot hold. Likewise, (4.31) cannot hold if $a \neq 0$.

Now we assume that (4.28) holds, but that

$$(4.32) \quad A \neq B \neq n(n+1) \quad .$$

Hence $\beta \neq 0$. Using (4.30) we convert (4.10b) to

$$(4.33) \quad L\psi_1 + n(n+1)\psi_1 = -bDP_n^1(\cos s)\sin s \quad ,$$

since (4.28) and (4.29) imply that $B - b\beta = n(n+1)$. Since $b \neq 0$, the alternative theorem implies that (4.33) has no solution unless $D = 0$, in which case (4.30) yields

$$(4.34) \quad \eta_1 = -\beta\psi_1 \quad .$$

In summary, the eigenvalues of (4.10) , (4.11) are solutions λ of (4.21). We limit our attention to positive eigenvalues. If $B < 2$, then the corresponding eigenfunctions are

$$(4.35) \quad (\eta_1, \psi_1) = ([n(n+1)-B]/b, 1)P_n^1(\cos s) \quad .$$

Now the function $P_n^1(\cos s)$ has exactly $n+1$ zeros on $[0, \pi]$, including those at 0 and π , each of which is simple. Thus every nontrivial solution (η_1, ψ_1) of (4.10) , (4.11) is characterized by the fact that η_1 and ψ_1 have exactly the same zeros.

§5. GLOBAL BIFURCATION .

To show that our equations meet the hypotheses of the bifurcation theorem and uniqueness theorem, which form the basis of our analysis, we must transform them into alternative forms that enable us to control the polar singularity manifested by the presence of $\sin s$ as a coefficient of the highest derivatives of our differential equations. We substitute (2.19) into (2.14)-(2.17), carry out the differentiation of the leading terms, use Cramer's rule (justified by (2.21)) to solve the resulting equations for $v'\sin s$, $\eta'\sin s$, $\mu'\sin s$, and finally force this latest version of the system into a form suggested by the linear equations (4.3)-(4.5). Using (4.12) we obtain

$$(5.1) \quad (v \sin s)' = \tau \cos s + (N_{\nu}^0)^{-1} (N_{\tau}^0 + H_{\tau}^0 + \lambda k) \eta \sin s + \\ + (N_{\nu}^0)^{-1} (N_{\tau}^0 k + \lambda k^2 / 2) (\psi - s) \sin s + n ,$$

$$(5.2) \quad (\eta \sin s)' = -(H_{\eta}^0)^{-1} (N_{\nu}^0 + N_{\tau}^0 + \lambda k) (v + \tau) \sin s + \\ + (H_{\eta}^0)^{-1} (\lambda k^2 / 2) [(\psi - s) \sin s]' + h ,$$

$$(5.3) \quad L(\psi - s) = -B(\psi - s) \sin s - b \sin s + m ,$$

where

$$(5.4) \quad n \equiv \Delta^{-1} D_1 + (v - \tau) \cos s - (N_{\nu}^0)^{-1} (N_{\tau}^0 + H_{\eta}^0 + \lambda k) \eta \sin s - \\ - (N_{\nu}^0)^{-1} (N_{\tau}^0 k + \lambda k^2 / 2) (\psi - s) \sin s ,$$

$$(5.5) \quad h \equiv \Delta^{-1} D_2 + \eta \cos s + (H_\eta^0)^{-1} (N_\nu^0 + N_\tau^0 + \lambda k) (\nu + \tau) \sin s \\ - (H_\eta^0)^{-1} (\lambda k^2 / 2) [(\psi - s) \sin s]' ,$$

$$(5.6) \quad m \equiv \Delta^{-1} D_3 + (\psi - s)' \cos s - \frac{\psi - s}{\sin s} + B(\psi - s) \sin s \\ + b \eta \sin s ,$$

$$(5.7a) \quad \Delta \equiv \det \frac{\partial (N, H, M)}{\partial (\nu, \eta, \mu)} ,$$

$$(5.7b) \quad D_j \text{ is the determinant obtained from } \Delta \text{ by} \\ \text{replacing its } j\text{th column with } \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} ,$$

$$(5.8a) \quad \alpha \equiv -(N_\tau \tau' + N_\sigma \sigma') \sin s + T \cos \psi - N \cos s + H \psi' \sin s + \lambda r \eta ,$$

$$(5.8b) \quad \beta \equiv -(H_\tau \tau' + H_\sigma \sigma') \sin s - T \sin \psi - H \cos s - N \psi' \sin s - \lambda r \nu ,$$

$$(5.8c) \quad \gamma \equiv -(M_\tau \tau' + M_\sigma \sigma') \sin s + \Sigma \cos \psi - M \cos s - (\nu H - \eta N) \sin s .$$

From (2.5)-(2.8) we find that

$$(5.9) \quad Lr = (\nu \sin s)' \cos \psi + (\nu \sin s) (\cos \psi)' - \\ - (\eta \sin s)' \sin \psi - (\eta \sin s) (\sin \psi)' - \tau ,$$

$$(5.10) \quad (z' \sin s)' = (\nu \sin s)' \sin \psi + (\nu \sin s) (\sin \psi)' + \\ + (\eta \sin s)' \cos \psi + (\eta \sin s) (\cos \psi)' .$$

We now introduce new variables $(u_1, u_2, u_3) \equiv \underline{u}$ by

$$(5.11a) \quad u_1(s) (\sin s)^{\frac{1}{2}} = (Lr)(s) \quad , \quad .$$

$$(5.11b) \quad u_2(s) (\sin s)^{\frac{1}{2}} = (z' \sin s)' \quad ,$$

$$(5.11c) \quad u_3(s) (\sin s)^{\frac{1}{2}} = L(\psi-s)(s) \quad .$$

Let us assume that \underline{u} is continuous. Then we can solve (5.11a,c), (2.25), (2.27) in terms of u_1 and u_3 . Now from (5.11b) we see that u_2 must satisfy

$$(5.12) \quad \int_0^{\pi} u_2(s) (\sin s)^{\frac{1}{2}} ds = 0 \quad .$$

We thus find that

$$(5.13) \quad \begin{aligned} z'(s) &= (\sin s)^{-1} \int_0^s u_2(t) (\sin t)^{\frac{1}{2}} dt \\ &= -(\sin s)^{-1} \int_s^{\pi} u_2(t) (\sin t)^{\frac{1}{2}} dt \quad . \end{aligned}$$

This representation shows that z satisfies the boundary conditions $z'(0) = 0 = z'(\pi)$, which are consequences of (2.5)-(2.8), (2.26), (2.27). We integrate one of the equations of (5.13) and then use (2.28) to evaluate the constant of integration. We obtain

$$(5.14a) \quad r(s) = \int_0^{\pi} K(s,t) u_1(t) (\sin t)^{\frac{1}{2}} dt \equiv (Gu_1)(s) \quad ,$$

$$\begin{aligned}
 (5.14b) \quad z(s) &= \int_0^\pi \frac{[\pi^{-1}y-1+\chi_{[0,s]}(y)]}{\sin y} \int_0^y u^2(t) (\sin t)^{\frac{1}{2}} dt dy \\
 &\equiv (Zu_2)(s) \quad ,
 \end{aligned}$$

$$(5.14c) \quad \psi(s)-s = \int_0^\pi K(s,t)u_3(t) (\sin t)^{\frac{1}{2}} dt \equiv (Gu_3)(s)$$

where $\chi_{[0,s]}$ is the characteristic function for $[0,s]$ and K is Green's function for L subject to Dirichlet data:

$$(5.15) \quad K(s,t) \equiv \begin{cases} -\frac{1}{2} \frac{1+\cos s}{1+\cos t} \frac{\sin t}{\sin s} & \text{for } t < s \quad , \\ -\frac{1}{2} \frac{1+\cos t}{1+\cos s} \frac{\sin s}{\sin t} & \text{for } t > s \quad . \end{cases}$$

(We could express (5.14b) in terms of a Green's function, but doing so would interfere with our analysis.) We also record that

$$(5.16a) \quad r'(s) = \int_0^\pi K_S(s,t)u_1(t) (\sin t)^{\frac{1}{2}} dt \equiv (Gu_1)'(s) \quad ,$$

$$(5.16b) \quad \psi'(s)-1 = \int_0^\pi K_S(s,t)u_3(t) (\sin t)^{\frac{1}{2}} dt \equiv (Gu_3)'(s)$$

where,

(5.17)

$$K_s(s,t) = \begin{cases} \frac{1}{2} \frac{1+\cos s}{1+\cos t} \frac{\sin t}{\sin^2 s} & \text{for } t < s, \\ -\frac{1}{2} \frac{1+\cos t}{1+\cos s} \frac{1}{\sin t} & \text{for } t > s. \end{cases}$$

z' is given by (5.13). From (2.7), (2.8) we then obtain

$$(5.18a) \quad v = (Gu_1)' \cos(s+Gu_3) + (Zu_2)' \sin(s+Gu_3),$$

$$(5.18b) \quad \eta = - (Gu_1)' \sin(s+Gu_3) + (Zu_2)' \cos(s+Gu_3),$$

$$(5.18c,d) \quad \tau = (Gu_1)/\sin s, \quad \sigma = [\sin(s+Gu_3)/\sin s] - 1.$$

We now convert our differential equations (5.1)-(5.3) into integral equations for \underline{u} : We replace the left sides of (5.9), (5.10), and (5.3) with (5.14). We next substitute (5.1), (5.2) into the right sides of (5.9), (5.10). Then we replace the variables appearing on the right sides of (5.9), (5.10), (5.3) with their representations from (5.14)-(5.18). Finally, as a precautionary measure, we subtract from the right side of the resulting form of (5.11) its mean value, a move suggested by (5.12). We denote the resulting system of integral equations by

$$(5.19) \quad \underline{u} = \underline{f}(\lambda, \underline{u}).$$

Let

$$(5.20a) \quad U = \{ \underline{u} \in C^0([0, \pi])^3 : (5.12) \text{ holds.} \}$$

We wish to show that $f(\lambda, \cdot)$ is a compact mapping from

$$(5.20b) \quad U \cap \{ \underline{u} : \underline{w} \in \mathcal{D} \} \equiv E$$

into itself (\mathcal{D} is defined in (2.20)).

Let $\underline{w} \rightarrow R(\underline{w})$ be any constitutive function. If $R \in C^1(\mathcal{D})$, then

$$(5.21a) \quad R(\underline{y}) = R(\underline{x}) + R_i(\underline{x}, \underline{y}) (y_i - x_i)$$

with

$$(5.21b) \quad R_i(\underline{x}, \underline{y}) \equiv \int_0^1 R_{w_i}(\underline{t}\underline{y} + (1-t)\underline{x}) dt .$$

Here and below, twice repeated indices are summed from 1 to 5. If $R \in C^2(\mathcal{D})$, then

$$(5.21c) \quad R(\underline{y}) = R(\underline{x}) + R_{w_i}(\underline{x}) (y_i - x_i) + \frac{1}{2} R_{ij}(\underline{x}, \underline{y}) (y_i - x_i) (y_j - x_j)$$

with

$$(5.21d) \quad R_{ij}(\underline{x}, \underline{y}) = \int_0^1 R_{w_i w_j}(\underline{t}\underline{y} + (1-t)\underline{x}) dt .$$

We let $\bar{R}_{w_i}(\tilde{w})$ and $\bar{R}_{w_i w_j}(\tilde{w})$ be any values of R_i and R_{ij} in which the arguments consist solely of entries from \tilde{w} . E.g., $\bar{R}_{w_i}(\tilde{w})$ could be taken to be $R_i((\tau, \nu, 0, \sigma, \mu), (\nu, \tau, \eta, \mu, \sigma))$.

Since we shall use only the continuity of $\{\bar{R}_{w_i}, \bar{R}_{w_i w_j}\}$ and not the specific functional forms, we allow their meaning to vary even in the same expression.

In the spirit of (5.21) we define the continuously differentiable functions C and S by

$$(5.22a) \quad 1 - \cos \theta = \theta^2 C(\theta) \quad ,$$

$$(5.22b) \quad \theta - \sin \theta = \theta^3 S(\theta) \quad .$$

Then

$$(5.23a) \quad \cos \psi - \cos s = -(\psi - s) \sin s + U \quad ,$$

$$(5.23b) \quad U \equiv -(\psi - s)^2 C(\psi - s) \cos s + (\psi - s)^3 S(\psi - s) \sin s \quad ,$$

$$(5.23c) \quad \sin \psi - \sin s = (\psi - s) \cos s + V \quad ,$$

$$(5.23d) \quad V \equiv -(\psi - s)^2 C(\psi - s) \sin s - (\psi - s)^3 S(\psi - s) \cos s \quad .$$

Thus

$$(5.23e) \quad \tau' \sin s = (\nu - \tau) \cos s - (\psi - s) (\nu \sin s + \eta \cos s) - \\ - \eta \sin s + \nu U - \eta V ,$$

$$(5.23f) \quad \sigma' \sin s = (\mu - \sigma) \cos s + \psi' [U - (\psi - s) \sin s] .$$

Let

$$(5.24) \quad \tilde{w}^* = (\tau, \nu, 0, \sigma, \mu) .$$

By using the formulas (5.21)-(5.23) we can convert α , given by (5.8a), to

$$(5.25) \quad \alpha = T(\tilde{w}) [U - (\psi - s) \sin s] + \frac{1}{2} \bar{T}_{\eta\eta} \eta^2 \cos s - \\ - [N_{\nu}(\tilde{w}^*) (\nu - \tau) + N_{\mu}(\tilde{w}^*) (\mu - \sigma) + \frac{1}{2} N_{ij}(\tilde{w}^*, \tilde{w}) (w_i - w_i^*) \\ (w_j - w_j^*) + \bar{N}_{\tau w_i} (\nu - \tau) (w_i - w_i^*) + \bar{N}_{\sigma w_i} (\mu - \sigma) (w_i - w_i^*)] \cos s \\ + N_{\tau}(\tilde{w}) [(\psi - s) (\nu \sin s + \eta \cos s) + \eta \sin s - \nu U + \eta V] - \\ - N_{\sigma}(\tilde{w}) \psi' [U - (\psi - s) \sin s] + \bar{H}_{\eta} \eta \psi' \sin s + \lambda r \eta .$$

We obtain similar representations for β and γ . Note that $\alpha + [N_{\nu}(\tilde{w}^*) (\nu - \tau) + N_{\mu}(\tilde{w}^*) (\mu - \sigma)] - \eta (\bar{H}_{\eta} \psi' \sin s + \lambda r)$ consists of sums of product of continuous functions of $(\tilde{w}, \psi - s)$ with quadratic functions of $\nu - \tau$, η , $\mu - \sigma$, $\psi - s$. By a lengthy computation we find that the terms in f consist of products of continuous functions of $(\tilde{w}, \psi - s)$ with quadratic functions of $(\sin s)^{-\frac{1}{2}} (\nu - \tau)$, $(\sin s)^{-\frac{1}{2}} \eta$, $(\sin s)^{-\frac{1}{2}} (\mu - \sigma)$, and

with a number of other such functions of $(\tilde{w}, \psi-s)$. Let us examine $(\sin s)^{-\frac{1}{4}}(\mu-\sigma)$, which (5.23c), (5.14c), (5.16b) reduce to

$$(5.26a) \quad (\sin s)^{-\frac{1}{4}}[\psi'(s) - 1 - (\psi(s)-s)\cot s - V(s)\csc s] \\ = \int_0^\pi J(s,t)u_3(t) dt - (\sin s)^{-5/4} V(s)$$

where

$$(5.26b) \quad J(s,t) = \begin{cases} \frac{1}{2} \frac{(1+\cos s)^2}{1+\cos t} \left(\frac{\sin s}{\sin t}\right)^{9/4} (\sin t)^{-3/4} & . t < s, \\ -\frac{1}{2} \frac{(1-\cos s)^2}{1-\cos t} \left(\frac{\sin t}{\sin s}\right)^{9/4} (\sin t)^{-3/4} & . t > s . \end{cases}$$

The Arzelà-Ascoli Theorem supports a straightforward proof that the kernel J generates a compact and continuous operator from $C^0([0,\pi])$ to itself. Note that the kernel $(\sin s)^{-\frac{1}{4}}K_s$ (See (5.17)) does not. It is the cancellation of terms in J that is responsible for this compactness.

Now (5.23d) implies that

$$(5.26c) \quad -(\sin s)^{-5/4}V = [(\sin s)^{-1/8}(\psi-s)]^2 C(\psi-s) + \\ + [(\sin s)^{-5/12}(\psi-s)]^3 S(\psi-s)\cos s .$$

Since the Arzelà-Ascoli Theorem implies that the integral representation for $(\sin s)^{-5/12}(\psi-s)$ obtained from (5.14c)

in a compact mapping of \underline{u} , it follows that (5.26c) defines a compact mapping. Since compositions of continuous and compact mappings are compact, we find that (5.26c), (5.26a), and $(\sin s)^{-1/2}(\mu-\sigma)^2$ correspond to compact operators taking $C^0([0,\pi])$ into itself. We emphasize that the appearance of terms such as $(\mu-\sigma)$ in \underline{f} is a consequence of the isotropy conditions.

By extensive use of arguments such as these, We find that \underline{f} is a compact and continuous mapping of \underline{E} into itself. Moreover, the form of \underline{f} shows that it is Fréchet differentiable at the trivial branch of solutions.

Let $\underline{u}_0(\lambda)$ be the trivial solution of (5.19) for fixed λ ; \underline{u}_0 corresponds to the trivial solutions discussed in Section 3. The linearization of (5.19) about the trivial state \underline{u}_0 , namely

$$(5.27) \quad \underline{v} = \underline{f}_{\underline{v}}(\lambda, \underline{u}_0(\lambda)) \underline{v},$$

is equivalent to the equations of Section 4. We accordingly can invoke the global bifurcation theory of Rabinowitz(1971) and the local theory of Crandall & Rabinowitz (1971) to obtain

5.28. Theorem. For a given positive integer n let $\bar{\lambda}_n$ be a solution of (4.21) of odd algebraic multiplicity, i.e., let there be an odd positive integer k such that

$$(5.29) \quad \frac{\partial^j}{\partial \lambda^j} g(\bar{\lambda}_n, \underline{u}) = 0, \quad j=0, \dots, k-1, \quad \frac{\partial^k}{\partial \lambda^k} g(\bar{\lambda}_n, \underline{u}) \neq 0 .$$

Then bifurcating from the point $(\bar{\lambda}_n, \underline{u}_0(\bar{\lambda}_n))$ on the trivial branch of solutions are two connected sets $C^\pm(\bar{\lambda}_n)$ of non-trivial solution pairs (λ, \underline{u}) of (5.19) that enjoy at least one of the following properties :

- (i) $C^\pm(\bar{\lambda}_n)$ cannot be confined to any compact subset of E .
- (ii) The closure of $C^\pm(\bar{\lambda}_n)$ contains another point $(\zeta, \underline{u}_0(\zeta))$ where ζ satisfies (4.21) .

Suppose, moreover, that $\bar{\lambda}_n$ is simple, i.e., that $k=1$ in (5.29). Let \underline{v}_n be a normalized eigenfunction of (5.27).

Let $P(\bar{\lambda}_n)$ be the projection of u onto $\text{span}(\underline{v}_n)$. Then there is a number $\bar{\varepsilon} > 0$ and there are continuous functions $\kappa_n :$

$[-\bar{\varepsilon}, \bar{\varepsilon}] \mapsto \mathbb{R}$, $\underline{y}_n : [-\bar{\varepsilon}, \bar{\varepsilon}] \mapsto [I - P(\bar{\lambda}_n)] u$ with $\kappa_n(0) = 0$,

$\underline{y}_n(0) = 0$ such that $(\bar{\lambda}_n + \kappa_n(\varepsilon), \underline{u}_0(\bar{\lambda}_n + \kappa_n(\varepsilon)) + \varepsilon[\underline{v}_n + \underline{y}_n(\varepsilon)])$

is a solution pair of (5.19) for $|\varepsilon| < \bar{\varepsilon}$. Moreover,

there is a neighborhood N_n of $(\bar{\lambda}_n, \underline{u}_0(\bar{\lambda}_n))$ such that if

(λ, \underline{u}) is a solution pair of (5.19) lying in N_n , then

either $(\lambda, \underline{u}) = (\lambda, \underline{u}_0(\lambda))$ or else there is an $\varepsilon \in [-\bar{\varepsilon}, \bar{\varepsilon}]$

such that $(\lambda, \underline{u}) = (\bar{\lambda}_n + \kappa_n(\varepsilon), \underline{u}_0(\bar{\lambda}_n + \kappa_n(\varepsilon)) + \varepsilon[\underline{v}_n + \underline{y}_n(\varepsilon)])$.

Note also that (5.14)-(5.18) imply that \underline{w} corresponding to any solution of (5.19) is continuous and in

particular $\psi \in C^1([0, \pi])$. Moreover

$$(5.30) \quad \lim_{s \rightarrow 0, \pi} [\nu(s) - \tau(s)] = 0, \quad \lim_{s \rightarrow 0, \pi} [\mu(s) - \sigma(s)] = 0 .$$

It follows from (5.1)-(5.3) that \underline{u} generates a classical solution to our boundary value problem. In fact, the requirement that the constitutive functions N, T, H, M, Σ be thrice continuously differentiable on \mathcal{D} implies that the strains \underline{w} generated by \underline{u} are twice continuously differentiable on the open interval $(0, \pi)$. To determine the boundary behavior of η' , which is needed in the sequel, we divide (2.29) by $\sin^2 s$ and use (2.19) and (5.21) to obtain

$$(5.31) \quad N(\underline{w}(s)) \frac{\sin \psi(s)}{\sin s} + \bar{H}_{\eta}(\underline{w}) \frac{\eta(s)}{\sin s} \cos \psi(s) + \lambda \tau(s)^2 / 2 = 0$$

on $(0, \pi)$. Since η satisfies (2.26), we can let $s \rightarrow 0, \pi$ in (5.31) to conclude that η is differentiable on $[0, \pi]$. To show that $\eta \in C^1([0, \pi])$ we use the expression for η' obtained from (5.2) and examine its limits as $s \rightarrow 0, \pi$. This process is simplified by the observation that the limiting forms for η' can equivalently be obtained by substituting (2.19) into (2.15), carrying out the differentiations, dividing the resulting equation by $\sin s$, and exploiting (2.24) and (5.30) to show that the limits $\eta'(0)$ and $\eta'(\pi)$ agree with those found from (5.31).

An essentially equivalent version of Theorem 5.28 can be obtained by using the theory of Fitzpatrick & Pejsachowicz (1985), which generalizes that of Crandall and Rabinowitz. The former theory does not require the use of Green functions. The role of isotropy still remains paramount.

§6. NODAL PROPERTIES OF SOLUTIONS

The determination of nodal properties of solutions of our boundary value problem is a more subtle question than that for the boundary value problem for plates. The main reason for this difference is that in the plate theory (cf. Antman (1978)) η is the product of a certain function with $\sin \psi$ and so the nodal properties of η are determined directly from those of ψ . On the other hand, in our shell theory v , τ , η , ψ are all coupled by nonlinear differential equations, which lack an obvious nodal pattern. To approach the question for shells we first need a candidate for a nodal pattern that is preserved on solution branches.

The solutions of the linearized problem, treated in Section 4, have the property that η_1 and ψ_1 have the same zeros, which are simple. The perturbation solutions of Section 8 also have this feature. Thus we are motivated to study whether the number of simultaneous zeros of η and $\psi - s$ is fixed on each bifurcating branch.

We immediately confront a serious difficulty. Let S_n , $n = 1, 2, \dots$ be the collection of all real-valued functions ρ in $C^1([0, \pi])$ having zeros at $0, \pi$ and having exactly $n - 1$ zeros on $(0, \pi)$, each zero being simple. Then S_n is open in $C^1([0, \pi])$. Given any function in S_n , it follows that all sufficiently nearby functions enjoy the same nodal properties, i.e., have the

same number $n + 1$ of zeros, each of which is simple. Moreover, the boundary ∂S_n consists of functions having at least one double zero on $[0, \pi]$. These observations support the nodal theory introduced by Crandall & Rabinowitz (1970) for bifurcation problems governed by nonlinear Sturm-Liouville equations. To study pairs of functions with simultaneous zeros, we let T_n be the collection of all complex-valued functions in $[C^1([0, \pi])]^2$ having zeros at $0, \pi$ and having exactly $n - 1$ zeros on $(0, \pi)$, each zero being simple. But T_n is not open in $[C^1([0, \pi])]^2$ and there is no useful characterization of ∂T_n . To circumvent this difficulty, we must exploit the fact that $(\eta, \psi-s)$ is not merely an arbitrary element of T_n , but is also a solution of a boundary value problem.

Our strategy is as follows. We first describe an auxiliary condition ensuring that if there is a solution of our boundary value problem for which $\eta, \eta', \psi-s, (\psi-s)'$ all vanish at a point s_0 in $[0, \pi]$, then $v-\tau$ also vanishes at s_0 . Next we prove a basic uniqueness theorem stating that if there is a solution of our boundary value problem to which $v-\tau, \eta, \psi-s, (\psi-s)'$ all vanish at a point s_0 in $[0, \pi]$, then the solution is trivial. This result does not enable us to assert that on a nontrivial solution branch $(\eta, \psi-s)$ remains in T_n if $(\eta, \psi-s)$ is in T_n at any solution pair on the branch. To remedy this difficulty, we set

$$(6.1) \quad \eta(s) = \rho(s) \cos \theta(s),$$

$$\psi(s) - s = \rho(s) \sin \theta(s).$$

If $\eta(s_0) = 0 = \psi(s_0) - s_0$, then $\rho(s_0) = 0$. Thus the zeros of the real-valued function ρ are the simultaneous zeros of η and $\psi - s$. If η and ψ are part of a nontrivial solution of our boundary value problem for which the auxiliary condition holds, we use the uniqueness theorem to prove that ρ can be defined so that it belongs to $C^1([0, \pi])$. We can accordingly determine where $\rho \in S_n$. In particular, if at a point on a nontrivial solution branch $\rho \in S_n$, then ρ remains in S_n until it has a double zero (by virtue of our discussion of ∂S_n).

By the remarks at the beginning of the last paragraph, we conclude that the solution is trivial if ρ has a double zero (and hence η and $\psi - s$ have simultaneous double zeros) provided the auxiliary condition is met. Let $\bar{\lambda}_n$ be a simple solution of (4.21) and let $C^\pm(\bar{\lambda}_n)$ be the two nontrivial branches bifurcating from $(\bar{\lambda}_n, u_0(\bar{\lambda}_n))$. We wish to show that on $C^\pm(\bar{\lambda}_n)$ the function ρ remains in S_n as long as the auxiliary condition is met. To do this, we must show that ρ admits a linearization and enjoys properties like those stated in the last part of Theorem 5.28. We thereby demonstrate that on $C^\pm(\bar{\lambda}_n)$, the function ρ inherits its nodal properties from those of its linearization and preserves them as long as the auxiliary condition is met, i.e., on $C^\pm(\bar{\lambda}_n)$, $\rho \in S_n$ as long as the auxiliary

condition is met. Thus on $C^{\pm}(\bar{\lambda}_n)$ the function η and $\psi - s$ have $n - 1$ simultaneous zeros on $(0, \pi)$ as long as the auxiliary condition is met.

We now proceed to carry out this program. We assume throughout the ensuing discussion that $(\lambda, \psi, \underline{w})$ generates a solution pair for our boundary value problem.

Suppose that there is an $s_0 \in (0, \pi)$ such that $\eta(s_0) = \eta'(s_0) = \psi(s_0) - s_0 = \psi'(s_0) - 1 \equiv \mu(s_0) = 0$. Then (2.24) ensures that (2.15), (2.19), (2.29) reduce to

$$(6.2) \quad N + T + \lambda \tau(s_0) \nu(s_0) = 0,$$

$$(6.3) \quad N + \frac{1}{2} \lambda \tau(s_0)^2 = 0$$

where the arguments of N and T are $(\nu(s_0), \tau(s_0), 0, 0, 0)$. We know from Section 3 that (6.2), (6.3) admit a solution of the form $\nu(s_0) = \tau(s_0) = k(\lambda)$ and that this is the only solution of these equations for which $\nu(s_0) = \tau(s_0)$. By virtue of (2.20) the variables ν , τ , λ are confined to $(h, \infty) \times (h, \infty) \times (0, \infty)$. Let G be the subset of this region for which the only solution of (6.2), (6.3) is $\nu(s_0) = \tau(s_0) = k(\lambda)$. We then have the following result, which is virtually a tautology.

6.4. LEMMA. If $\eta(s_0) = \eta'(s_0) = \psi(s_0) - s_0 = \psi'(s_0) - 1 = 0$ and if $(\nu(s_0), \tau(s_0), \lambda) \in G$, then $\nu(s_0) = \tau(s_0) = k(\lambda)$.

In the next section we shall study the nature of G the "auxiliary condition", alluded to above is just the requirement that $(v(s_0), \tau(s_0), \lambda) \in G$. Our basic uniqueness theorem is

6.5. Theorem. If there is an $s_0 \in [0, \pi]$ such that

$$(6.6) \quad v(s_0) - k(\lambda) = \tau(s_0) - k(\lambda) = \eta(s_0) = \psi(s_0) - s_0 = \\ = \psi'(s_0) - 1 = 0 \quad ,$$

then the solution is trivial .

Proof. Let

$$(6.7a) \quad \underline{v} \equiv (v_1, v_2, v_3, v_4, v_5) \\ = ((v-\tau)\sin s, (v+\tau-2k)\sin s, \eta\sin s, \mu\sin s, \psi-s) \quad ,$$

$$(6.7b) \quad v = |v_1| + |v_2| + |v_3| + |v_4| + |v_5| \quad .$$

Then we can combine (5.1)-(5.3), (2.8), and (5.23) to obtain the system

$$(6.8a) \quad \dot{v}_1 = v(v_5 \sin s - U) + v_3 + \eta(v_5 \cos s + V) + \Delta^{-1} D_1 \quad ,$$

$$(6.8b) \quad \dot{v}_2 = (v_1 + v_2) \cot s - v(v_5 \sin s - U) - v_3 - \\ - \eta(v_5 \cos s + V) + \Delta^{-1} D_1 \quad ,$$

$$(6.8c) \quad v_3' = v_3 \cot s + \Delta^{-1} D_2 \quad ,$$

$$(6.8d) \quad v_4' = v_4 \cot s + \Delta^{-1} D_3 \quad ,$$

$$(6.8e) \quad v_5' = v_4 (\sin s)^{-1} \quad .$$

If $s_0 \in (0, \pi)$ and if \underline{v} satisfies (6.6) and (6.8) then $\underline{v} = 0$, because the right-hand side of (6.8) is a well-behaved function of s and \underline{v} . Consequently the initial-value problem has a unique solution, which is the trivial solution $\underline{v} = 0$.

Thus we need only concern ourselves with the cases $s_0 = 0, \pi$, in which the right-hand side of (6.8) is singular in s . We just treat the former case. Throughout our discussion we let \underline{v} represent an arbitrary, given solution of our boundary value problem (known to exist by the results of Section 5) which we subject to the additional requirement that it satisfy (6.6). In the analysis to follow, we let c denote a typical positive constant depending on the fixed but arbitrary solution \underline{v} . The meaning of c can change from place to place. We tacitly restrict s to lie in an interval of the form $[0, \varepsilon]$ where ε is small and positive.

Since $\sin s \geq s \cos s$ on $[0, \varepsilon]$, we find that

$$(6.9) \quad \int_0^s (\sin t)^{-\frac{1}{2}} dt \leq 2(\sin s)^{\frac{1}{2}} / \cos s \leq c(\sin s)^{\frac{1}{2}} \quad .$$

Using this result in (5.13)-(5.18) and using the fact that $|\underline{u}| \leq c$, we obtain after careful analysis that

$$(6.10) \quad \begin{aligned} |v-\tau| + |\eta| + |\mu-\sigma| &\leq c(\sin s)^{\frac{1}{2}} \quad , \\ |\psi-s| &\leq c \sin s \quad , \quad |\mu| + |\sigma| \leq c \quad . \end{aligned}$$

Since (5.23) implies that

$$(6.11) \quad |\sigma| \leq c|v_5|(\sin s)^{-1} \quad ,$$

we find from (5.25) and related expressions that

$$(6.12) \quad |\alpha| + |\beta| + |\gamma| \leq c(\sin s)^{\frac{1}{2}} \quad .$$

Let us now examine (6.8a). From (6.10) we immediately obtain

$$(6.13) \quad |v_1 - \Delta^{-1} D_1| \leq c(|v_3| + |v_5|) \leq cv \leq cv(\sin s)^{-\frac{1}{2}} \quad .$$

Note that (2.21) and (2.23) imply that

$$(6.14) \quad \Delta^{-1} \leq c \quad .$$

Accounting for (2.24) by using the notation introduced after (5.21) we obtain

$$(6.15) \quad D_1 = \alpha H_{\eta} M_{\mu} - \alpha \bar{H}_{\mu\eta} \bar{M}_{\eta\eta} \eta^2 - (\beta M_{\mu} - \gamma H_{\mu}) \bar{N}_{\eta\eta} \eta + \\ + \beta N_{\mu} \bar{M}_{\eta\eta} \eta - \gamma H_{\eta} (\bar{N}_{\mu\eta} \eta + \bar{N}_{\mu\mu} \mu + \bar{N}_{\mu\sigma} \sigma) \quad ,$$

$$(6.16) \quad \Delta^{-1} - (N_{\nu} H_{\eta} M_{\mu})^{-1} \equiv Q = \bar{Q}_{\eta} \eta + \bar{Q}_{\mu} \mu + \bar{Q}_{\sigma} \sigma \quad .$$

Inequalities (6.10)-(6.12), (6.14)-(6.16) imply that

$$(6.17) \quad |\Delta^{-1} D_1 - \alpha (N_{\nu})^{-1}| \leq cv(\sin s)^{-\frac{1}{2}} \quad .$$

If in (5.25) we replace $N_{\nu}(\underline{w}^*)$ with $N_{\nu}(\underline{w}) + \bar{N}_{\nu w_i} (w_i^* - w_i)$

and replace $N_{\mu}(\underline{w}^*)$ with $\bar{N}_{\mu\eta} \eta + \bar{N}_{\mu\mu} \mu + \bar{N}_{\mu\sigma} \sigma$, then we obtain from (6.10), (6.11) that

$$(6.18) \quad |\alpha + N_{\nu}(\nu - \tau) \cos s| \leq cv(\sin s)^{-\frac{1}{2}} \quad .$$

Inequalities (6.13), (6.17), (6.18) imply that

$$(6.19) \quad |v_1' + v_1 \cot s| \leq cv(\sin s)^{-\frac{1}{2}} \quad .$$

A virtually identical analysis yields

$$(6.20) \quad |v_2' - v_2 \cot s| \leq cv(\sin s)^{-\frac{1}{2}} \quad .$$

The treatment of (6.8c) is just slightly different. Using the same ideas as those leading to (6.17) we obtain

$$(6.21) \quad |\Delta^{-1}D_2| \leq c|\beta| + cv(\sin s)^{-\frac{1}{2}} \quad .$$

Since $H_\tau = \bar{H}_{\tau\eta}\eta$, $H_\sigma = \bar{H}_{\sigma\eta}\eta$ by (2.24), equation (5.8) yields

$$(6.22) \quad |\beta| \leq cv(\sin s)^{-\frac{1}{2}} + |T+N+\lambda v\tau| \sin s \quad .$$

Equation (3.1) implies that

$$(6.23) \quad \begin{aligned} T + N + \lambda v\tau \equiv X &= \bar{X}_\nu(\nu-k) + \bar{X}_\tau(\tau-k) \\ &= \frac{1}{2}[\bar{X}_\nu(\nu_1+\nu_2) + \bar{X}_\nu(-\nu_1+\nu_2)] (\sin s)^{-1} \quad . \end{aligned}$$

Combining (6.8c), (6.21)-(6.23), we obtain

$$(6.24) \quad |v_3' - v_3 \cot s| \leq cv(\sin s)^{-\frac{1}{2}} \quad .$$

We remark that the only place that the variable v_2 appears in (6.8a,c,d,e) is in the right side of (6.8c). Similar techniques produce

$$(6.25) \quad |v_4' - v_5 \cot s| \leq cv(\sin s)^{-\frac{1}{2}} \quad .$$

Combining (6.19), (6.20), (6.24), (6.25), (6.8e) we obtain

$$(6.26) \quad v' \leq |v_1'| + |v_2'| + |v_3'| + |v_4'| + |v_5'| \leq v \cot s + cv(\sin s)^{-\frac{1}{2}} \quad ,$$

the first inequality being a standard consequence of the absolute continuity of \underline{v} . Since (6.6) implies that

$$(6.27) \quad v(s)/s \rightarrow 0 \quad \text{as } s \rightarrow 0, \quad ,$$

we can invoke the standard uniqueness theorems associated with differential inequalities (cf. Hartman(1964, Sec.III.6)) to conclude that $v = 0$. \square

It is important to note that if we were to insert a constant exceeding 1 in front of $v \cot s$ in (6.26), then we could not conclude that $v = 0$. That the coefficient in front of $v \cot s$ is 1 is a consequence of the isotropy condition.

We are now ready to study the polar coordinates ρ and θ introduced in (6.1). We state their properties in a series of lemmas.

6.28. Lemma. Let the boundary value problem have a non-trivial solution pair with (ν, τ, λ) taking values only in G and with ρ and θ defined in any manner consistent with (6.1). Then the zeros of ρ on $[0, \pi]$ are isolated.

Proof. If not, they would accumulate at a point $s_0 \in [0, \pi]$, at which η and $\psi - s$ would consequently have simultaneous double zeros. By Lemma 6.4 and Theorem 6.5, the solution would then be trivial. \square

Now (6.1) implies that

$$(6.29) \quad \tan \theta = (\psi - s) / \eta .$$

Suppose that the solution is not trivial and that (ν, τ, λ) take values only in G . Let s_1 and s_2 be a pair of adjacent zeros of ρ . If η vanishes nowhere on (s_1, s_2) , then (6.29) implies that $\tan \theta$ is continuously differentiable on (s_1, s_2) and we can define θ itself (mod π) to be continuously differentiable on (s_1, s_2) . If η vanishes at $s_3 \in (s_1, s_2)$, then we define

$$(6.30) \quad \theta(s) \equiv \pi/2 + \int_{s_3}^s \frac{\{\eta(t)[\psi'(t)-1]-[\psi(t)-1]\eta'(t)\}}{\eta(t)^2+[\psi(t)-t]^2} dt \pmod{\pi}$$

for $s \in (s_1, s_2)$. If s_4 is a zero of ρ and if $\eta'(s_4)$ and $\psi'(s_4) - 1$ do not both vanish, then l'Hôpital's rule enables us to deduce from (6.29) that

$$(6.31) \quad \tan \theta(s) \rightarrow \frac{\psi'(s_4)-1}{\eta'(s_4)} \quad \text{as } s \rightarrow s_4 ,$$

the limit existing as an extended real number. (If $\eta'(s_4) = 0 = \psi'(s_4) - 1$, then we could use Lemma 6.4 and Theorem 6.5 to show that the solution is trivial when the condition on G holds.) Then $\theta(s_4)$ is defined mod π . By selecting the value of θ at such zeros of ρ appropriately, we can define

$$(6.32) \quad \rho = \eta \cos \theta + (\psi - s) \sin \theta .$$

Hence Lemma 6.4 and Theorem 6.5 imply

6.33. Lemma. Let the boundary value problem have a non-trivial solution pair with (ν, η, λ) taking values only in G . Then ρ and θ satisfying (6.1) can be chosen to be continuous on $[0, \pi]$.

Since $\eta, \psi \in C^1([0, \pi])$, the constructions we have made above ensure that ρ and θ are continuously differen-

tiabile where ρ does not vanish provided the hypotheses of Lemma 6.33 hold. Differentiating (6.1) we obtain

$$(6.34a,b) \quad \begin{aligned} \rho' &= \eta' \cos \theta + (\psi' - 1) \sin \theta \quad , \\ \rho \theta' &= -\eta' \sin \theta + (\psi' - 1) \cos \theta \end{aligned}$$

where ρ does not vanish. The continuity of the right sides of (6.34) then yields

6.35. Lemma. If the hypotheses of Lemma 6.33 hold, then
 $\rho' , \rho \theta' \in C^0([0, \pi])$.

We require the following refinement of this lemma :

6.36. Lemma. If s_0 is a zero of ρ and if $\eta'(s_0)$
and $\psi'(s_0) - 1$ are not both zero, then $\rho(s_0)\theta'(s_0) = 0$.

Proof. The Mean Value Theorem yields

$$(6.37) \quad \eta(s) = \left[\int_0^1 \eta'(\alpha s + (1-\alpha)s_0) d\alpha \right] (s-s_0) \quad ,$$

$$\psi(s) - s = \left[\int_0^1 \mu(\alpha s + (1-\alpha)s_0) d\alpha \right] (s-s_0) \quad .$$

On any small one-sided neighborhood of s_0 , (6.34b) thus yield

$$(6.38) \quad \pm \rho(s) \theta'(s) = \frac{\mu(s) \int_0^1 \eta' d\alpha - \eta'(s) \int_0^1 \mu d\alpha}{\left(\left[\int_0^1 \eta' d\alpha \right]^2 + \left[\int_0^1 \mu d\alpha \right]^2 \right)^{\frac{1}{2}}}$$

where the arguments of η' and μ in the integrands are $\alpha s + (1-\alpha)s_0$. Since η' and μ are uniformly continuous on $[0, \pi]$, we find that $\int_0^1 \eta'(\alpha s + (1-\alpha)s_0) d\alpha \rightarrow \eta'(s_0)$ as $s \rightarrow s_0$, etc. Thus in the limit as $s \rightarrow s_0$, the numerator on the right side of (6.38) approaches 0, while the denominator approaches a positive number. \square

In view of Lemma 6.35 we can examine whether $\rho \in S_n$. By the introductory remarks of this section, functions ρ in ∂S_n have a double zero. But this fact alone does not guarantee that η and ψ -s have a simultaneous double zeros, as an examination of (6.1) and (6.34a) shows. But Lemma 6.36 coupled with (6.34) implies that at a double zero of ρ the functions η and ψ -s have a simultaneous double zero, a result that enables us to invoke Lemma 6.4 and Theorem 6.5. Marshalling these facts in the manner proposed in the introductory remarks in this section, we obtain

6.39.Theorem. Let K be a connected set of nontrivial solution pairs with the property that (ν, τ, λ) takes values

only in G for each solution pair in K . If for one solution pair in K the function $\rho \in S_n$, then ρ remains in S_n for every solution pair in K . Thus η and ψ -s have exactly $n+1$ simultaneous zeros on K .

Let $\bar{\lambda}_n$ be a simple root of (4.21) (so that (5.29) holds with $k = 1$). Then the last part of Theorem 5.28 together with the representations (5.14c) and (5.18b) imply that on the branch $C(\bar{\lambda}_n)$ near the bifurcation point $(\bar{\lambda}_n, \underline{0})$, λ , η , ψ have representations of the form

$$(6.40) \quad \lambda = \bar{\lambda}_n + \kappa(\varepsilon), \quad \eta = \varepsilon\eta_1 + o(\varepsilon),$$

$$\psi - s = \varepsilon\psi_1 + o(\varepsilon)$$

as $\varepsilon \rightarrow 0$, where κ is continuous and $\kappa(0) = 0$. If we substitute (6.40) into (6.29) and use (4.25) we obtain

$$(6.41) \quad \tan \theta = \psi_1 / \eta_1 + o(1) = E^{-1} + o(1).$$

Thus we may take

$$(6.42) \quad \theta = \arctan (E^{-1}) + o(1).$$

Then (6.32) implies that

$$(6.43) \quad \rho = \varepsilon\rho_1 + o(\varepsilon) = \varepsilon[\rho_1 + o(\varepsilon)\varepsilon^{-1}]$$

with

$$\begin{aligned}
 (6.44) \quad \rho_1 &= (1+E)^{-\frac{1}{2}} [E\eta_1 + \psi_1] \\
 &= (1+E)^{\frac{1}{2}} P_n^1(\cos s).
 \end{aligned}$$

It follows that $\rho_1 \in S_n$ and that $\rho \in S_n$ for ε sufficiently small. (Incidentally, we show in the next section that (ν, τ, λ) generically belongs to G for ε sufficiently small essentially because $\nu - \tau = 0$ on the trivial branch.) We accordingly have

6.45. Theorem. Let $\bar{\lambda}_n$ be a simple root of (4.21).
On the maximal connected subset of the closure of $C^\pm(\bar{\lambda}_n)$
containing $(\bar{\lambda}_n, u_0(\bar{\lambda}_n))$ for which (ν, τ, λ) takes values
only in G , n and ψ -s have exactly $n + 1$ simul-
taneous zeros.

§ 7. PROPERTIES OF G .

We now study (6.2), (6.3), which we rewrite as

$$(7.1) \quad N(v, \tau) = -\frac{1}{2}\lambda\tau^2 \quad ,$$

$$(7.2) \quad N(v, \tau) + T(v, \tau) = -\lambda v\tau \quad ,$$

from which we obtain

$$(7.3) \quad T(v, \tau) = \lambda\tau(\frac{1}{2}\tau - v) \quad .$$

Here we have suppressed the last three arguments $(0, 0, 0)$ of the functions N and T . The set G consists of all (v, τ, λ) in $(h, \infty) \times (h, \infty) \times (0, \infty)$ for which the only solution of (7.1), (7.2) is $v = \tau = k(\lambda)$. We make a few remarks about (7.1), (7.2) in general before studying a specific example.

Since $N_v > 0$ by (2.21) and since N satisfies the growth conditions of (2.23), equation (7.1) can be solved uniquely for v in terms of τ and λ :

$$(7.4) \quad v = f(\tau; \lambda), \quad \text{with } 1 = f(1; 0) \quad .$$

Since $f_\tau = -(N_\tau + \lambda\tau)/N_v$, we find that $f_\tau < 0$ if $N_\tau > 0$ and that $f_\tau(1; 0) > -1$ if $N_\tau(1, 1) < N_v(1, 1)$.

The isotropy condition (2.24) ensures that the curve in the (v, τ) -plane defined by (7.2) is symmetric

about the line $v = \tau$. If $T_v + N_v > 0$, if $T + N \rightarrow -\infty$ as $v \rightarrow 0$ for fixed τ , and if $\liminf T + N \geq 0$ as $v \rightarrow \infty$ for fixed τ , then (7.2) can be uniquely solved for v in terms of τ and λ :

$$(7.5) \quad v = g(\tau; \lambda) \quad \text{with} \quad 1 = g(1; 0) .$$

The results of Section 3 ensure that the graphs of $f(\cdot; \lambda)$ and $g(\cdot; \lambda)$ intersect on the line $v = \tau$. Since

$$(7.6) \quad g_\tau = - \frac{(\lambda g + N_\tau + T_\tau)}{(\lambda_\tau + N_v + T_\tau)} .$$

it follows that $g_\tau < 0$ under our assumptions and, not surprisingly, that $f_\tau(\tau; \lambda) = -1$ when $\tau = g(\tau; \lambda)$. Thus the graphs of $f(\cdot; \lambda)$ and $g(\cdot; \lambda)$ cross transversally on the line $v = \tau$ when $f_\tau \neq -1$ here, i.e., when

$$(7.7a) \quad N_v(\tau, \tau) - N_\tau(\tau, \tau) - \lambda\tau \neq 0 .$$

Using (7.1) we can rewrite (7.7a) as a condition involving only the constitutive function N :

$$(7.7b) \quad N_v(\tau, \tau) - N_\tau(\tau, \tau) + 2N(\tau, \tau)/\tau \neq 0 .$$

Wherever (7.7) holds, there is a neighborhood about (τ, τ, λ) lying in G . (See the parenthetical remark

preceding Theorem 6.45.)

There are several ways to analyze (7.1), (7.2) further by making general restrictions on N and T leading to suitable estimates. It is also illuminating to view (7.1) and (7.2) as each describing the intersection of two graphs over the (v, τ) -plane. Alternatively we could assume that N and T are derivable from a stored energy function (as in (7.9) below), characterize the equations as Euler-Lagrange equations for a constrained problem, and study the extremization of a real valued function on a constraint curve. There are several ways to choose the constraint. It is more illuminating, however, to analyze a specific class of materials.

Let A, B, C, α be positive numbers and let

$$(7.8) \quad W(v, \tau) = A\alpha^{-1} v^{-\alpha} \tau^{-\alpha} + \frac{1}{2}B(v+\tau)^2 + \frac{1}{2}C(v^2+\tau^2) \quad ,$$

$$(7.9) \quad N(v, \tau) = W_v(v, \tau) - W_v(1, 1) \quad ,$$

$$T(v, \tau) = W_\tau(v, \tau) - W_\tau(1, 1) \quad .$$

These equations give a reasonable model for material behavior in compression for $h = 0$. When (7.8), (7.9) hold, equations (7.1), (7.2) reduce to

$$(7.10) \quad -Av^{-(\alpha+1)}\tau^{-(\alpha+1)}\tau + B(v+\tau) + Cv + A - 2B - C = -\frac{1}{2}\lambda\tau^2 \quad ,$$

$$(7.11) \quad -Av^{-(\alpha+1)}\tau^{-(\alpha+1)}(v+\tau) + (2B+C)(v+\tau) + 2A - 2(2B+C) = -\lambda v\tau .$$

We now solve (7.11) for $-A(v\tau)^{-(\alpha+1)}$ and substitute the resulting expression into (7.10), obtaining an equation with a factor $v - \tau$. Since we wish to study the locations of possible solutions of (7.1), (7.2) with $v \neq \tau$, we cancel this factor obtaining

$$(7.12) \quad (B+C)(v+\tau) + A - 2B - C = \frac{1}{2} \lambda \tau^2 .$$

Let us denote the solution of (7.12) for v in terms of τ by $v^\#(\tau, \lambda)$. If we replace v in (7.10) with $v^\#(\tau)$, we obtain

$$(7.13) \quad A\tau^{-(\alpha+1)} = (\lambda\tau - C) [v^\#(\tau, \lambda)]^{\alpha+1} .$$

For $\lambda > 0$, trivial solutions of our boundary value problem are characterized by $v = \tau = k(\lambda) \in (0, 1)$, $N = T = -\frac{1}{2}\lambda k(\lambda)^2$. We accordingly limit our attention to a neighborhood (possibly quite large) of the trivial solutions by seeking solutions of (7.13) for which

$$(7.14a, b, c, d) \quad \tau \in (0, 1), \quad v^\#(\tau, \lambda) \in (0, 1) , \\ N(v^\#(\tau, \lambda), \tau) < 0, \quad T(v^\#(\tau, \lambda), \tau) < 0$$

for $\lambda > 0$. We wish to characterize where (7.13) has solutions satisfying (7.14). Such solutions lie in the

complement of G . (If (7.14) is not imposed, then (7.13) always has a solution.)

Note that (7.14c) is automatically satisfied by virtue of (7.1) . We now use (7.12)-(7.14) to show that the set of points $(v, \tau) \in (0,1) \times (0,1)$ at which (7.1) , (7.2) has solutions for (7.8), (7.9) can be quite small. Call this set $H(\lambda)$. Clearly

$$(7.15) \quad H(\lambda) \equiv \{ (v, \tau) \in (0,1) \times (0,1) : v = v^\#(\tau, \lambda) , \\ \tau \text{ satisfies (7.13), } T(v^\#(\tau, \lambda), \tau) < 0 \} .$$

We now obtain a number of inequalities that elements of $H(\lambda)$ must satisfy .

Equation (7.3) implies that (7.14d) is satisfied if and only if

$$(7.16) \quad v^\#(\tau, \lambda) > \tau/2 .$$

Equation (7.12) implies that

$$(7.17) \quad v^\#(\tau, \lambda) > -\tau + 1 + \frac{B - A}{B + C} ,$$

which can represent a very severe or an insignificant restriction depending on the relative size of A, B, C . Equation (7.12) and conditions (7.14a,b) imply that

$$(7.18) \quad \tau \leq [2(C+A)]^{\frac{1}{2}} \lambda^{-\frac{1}{2}} .$$

A simple graphical analysis of (7.13) based on (7.14a,b) shows that

$$(7.19) \quad \tau \geq \min\left(\frac{A+C}{\lambda}, 1\right) .$$

Note that if $B-A$ and λ are sufficiently large, then the set of τ 's satisfying (7.14), (7.17), (7.18) is empty. If λ is small enough, then (7.19) implies that $\tau \geq 1$.

By substituting (7.16) into (7.12) we obtain

$$(7.20) \quad \tau \notin [\tau_-, \tau_+] , \quad \lambda\tau_{\pm} \equiv \frac{3}{2}(B+C) \pm \left[\frac{9}{4}(B+C)^2 + 2\lambda(A-2B-C)\right]^{\frac{1}{2}} ,$$

the interval $[\tau_-, \tau_+]$ being regarded as empty if τ_{\pm} are not real. If $A-2B-C > 0$ and if λ is large enough, then (7.20) delivers a lower bound for τ that is larger than that of (7.19) .

We seek similar estimates independent of λ . Let us use (7.18) to get a lower bound for $A\tau^{-(\alpha+1)}$. A sketch shows that a lower bound for τ is the solution of

$$(7.21) \quad A \left[\frac{2(C+A)}{\lambda} \right]^{-(\alpha+1)/2} = (\lambda\tau - C) .$$

Thus

$$(7.22) \quad \tau \geq \frac{C}{\lambda} + \frac{A\lambda^{(\alpha-1)/2}}{[2(C+A)]^{(\alpha+1)/2}} .$$

If $\alpha \in (0,1)$, then (7.22) delivers a lower bound dependent on λ , but nevertheless better than those of (7.19) and (7.20) when λ is large enough. If $\alpha = 1$, then (7.22) gives bound that is clearly better than (7.19) and that itself has a further lower bound independent of λ . If $\alpha > 1$, then

$$(7.23) \quad \begin{aligned} 2\tau &\geq \xi x^{-2} + (1-\xi)x^{\alpha-1} \\ &= \frac{(\alpha+1)C^{(\alpha-1)/(\alpha+1)} A^{2/(\alpha+1)}}{(\alpha-1)^{(\alpha-1)/(\alpha+1)} 2^{-2(\alpha+2)/(\alpha+1)} (C+A)} \end{aligned}$$

with $x \equiv \left[\frac{2C}{(\alpha-1)A} \right]^{1/(\alpha+1)}$, $\xi = \frac{C}{C+A}$, the expressions on the right side of (7.23) being the minimum of the right side of (7.22) for $\lambda \in (0, \infty)$. An upper bound for the rightmost term of (7.23) can be obtained by the Young inequality. The right side of (7.23) can be made arbitrarily large by taking $\alpha - 1$ sufficiently small and positive.

It is not difficult to obtain further estimates, e.g., estimates for the neighborhood discussed in the comments following (7.7b). We refrain from doing so.

The basic message of this section is that the set G can be very large and that precise information about it can

be gained directly from degenerate constitutive equations. Moreover, we would be able to strengthen the global results of Section 7 even more by obtaining estimates for the location of solutions of our boundary value problem and restricting G to reflect such estimates. We do not attempt such estimates here.

8. CONCLUSION.

In an unshearable shell η is constrained to be zero. The shear resultant H , not defined constitutively, is the Lagrange multiplier maintaining the constraint of unshearability. It is a fundamental unknown of the constrained problem. The same analysis as that used above can treat unshearable shells if H is treated as η is.

Some of our techniques are reminiscent of those of Antman (1978) for plates. The difference in boundary conditions forced us to give the coordinate functions r and z a central role in the analysis of Section 5, which they lacked in the plate theory. The issues treated in Section 7 never arose for plates. Of course the nodal properties of branches for shells differ markedly from those for plates and for circular arches (cf. Antman & Dunn, (1980).) Incidentally, the uniqueness theorem of Antman (1978, Section 7) is faulty; it can be readily corrected by following the development of Section 6 above.

It is illuminating to compare our results with the numerical results of Bauer, Reiss, & Keller (1970). Treating an engineering theory of shells they discovered the remarkable fact that all the bifurcating branches they analyzed are connected. Our results point in the diametrically opposite direction. We showed that nodal properties of branches bifurcating from simple eigenvalues could only lose their nodal structure at certain special places in solution-

parameter space. In particular, if we could obtain delicate pointwise estimates showing that $v \in (0,1)$, $\tau \in (0,1)$, $N < 0$, $T < 0$, everywhere on a family of bifurcating branches, then the results of Sections 6 and 7 show that nodal properties cannot switch along such branches. Consequently such branches could not connect bifurcation points with simple eigenvalues having different eigenfunctions.

Now Section 7 shows that for fixed λ the complement of G is generically a finite number of points. On the basis of such genericity arguments we could expect that on a given bifurcating branch there would be no $s_0 \in [0, \pi]$ and $\lambda > 0$ such that $(v(s_0), \tau(s_0), \lambda) \notin G$. (Such genericity arguments are dangerous: The nodal structure we found for η and ψ -s is not generic for pairs of functions.)

The chief source of the suspected variance between our results and those of Bauer, Reiss, & Keller is likely the fact that various geometric terms regarded as small were discarded in their theory (as is typical of all technical shell theories). Consequently these terms could not come into play in the large solutions they computed. A conceivable alternative explanation of the connectedness of all the bifurcating branches found by Bauer, Reiss, & Keller is that they correspond to spurious solution branches of the sort often found in numerical studies of bifurcation problems. We tend to dismiss this explanation because it

does not seem compatible with the consistent pattern they found. Bauer, Reiss, & Keller did not give enough data for us to determine what sort of nodal properties their solutions possess.

Our approach may also be compared with that of Lange & Kriegsmann (1981) who studied continuation properties for very thin shells by using asymptotic expansions. Our global bifurcation theory gives an approach to the continuation of branches that does not require special hypotheses on thickness, or more generally, on constitutive functions. Presumably their detailed approach could be applied to our geometrically exact theory for constitutive functions corresponding to very thin shells. We could also introduce the thickness h as a second bifurcation parameter and study the role of thickness by using global multiparameter bifurcation theory (cf. Alexander & Antman (1981)).

We mention that the perturbation results of Shih (1985) show that the local disposition of bifurcating branches depends critically on the nature of our nonlinear constitutive equations. In particular, the local structure can be quite different from that found in technical shell theories, which essentially use linear constitutive relations.

As we have indicated above, the process of numerically constructing solution branches can be quite tricky. It would seem that nodal properties on solution branches could give an extra control on numerical computation. But, to our knowledge, no such use of nodal properties has been attempted.

Acknowledgement. Part of the work presented here was developed by Shih (1985) for his doctoral dissertation in the Department of Mathematics of the University of Maryland. The work of Antman was partially supported by a grant from the National Science Foundation.

§9. APPENDIX A. FORMULATION OF THE GOVERNING EQUATIONS.

In this appendix we describe a special director theory for a nonlinearly elastic axisymmetric shell undergoing an axisymmetric deformation. Let $\{\underline{i}, \underline{j}, \underline{k}\}$ be a right-handed orthonormal basis for the Euclidean space E^3 .

In the special Cosserat theory we employ, a shell is regarded as a surface together with a unit vector field, called the director field, defined on it. For such an axisymmetric shell undergoing an axisymmetric deformation, the surface is generated by a plane curve rotated about the \underline{k} -axis and the director field is likewise generated by rotating a director field coplanar with the generating curve.

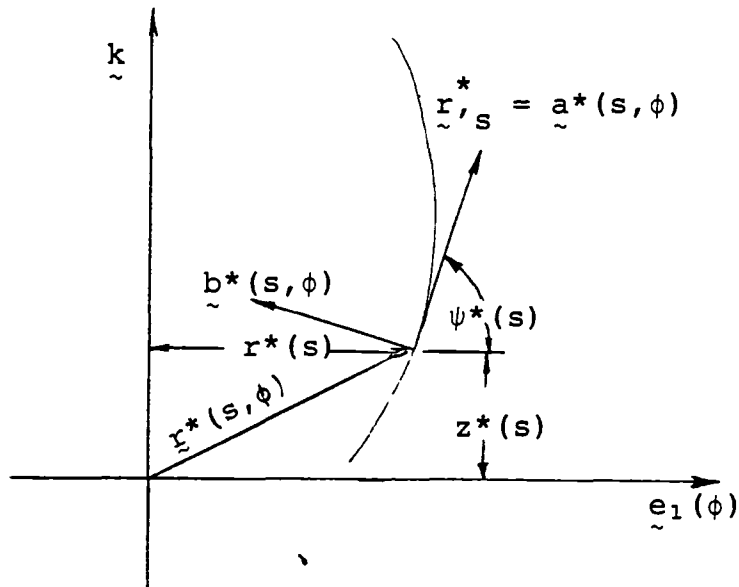


Fig. 9-1

Reference Configuration

Let

$$(9.1) \quad \underline{e}_1(\phi) = \cos \phi \underline{i} + \sin \phi \underline{j} \quad ,$$

$$(9.2) \quad \underline{e}_2(\phi) = -\sin \phi \underline{i} + \cos \phi \underline{j} \quad .$$

The position $\underline{r}^*(s, \phi)$ of a typical material point on the (mid) surface of an axisymmetric shell in its undeformed reference configuration is (see Fig. 9-1),

$$(9.3) \quad \underline{r}^*(s, \phi) = r^*(s) \underline{e}_1(\phi) + z^*(s) \underline{k} \quad ,$$

where ϕ is the meridional angle and s measures arc length parameter. (s, ϕ) identify each material point of the (mid) surface. We let $s \in [0, L]$. Define

$$(9.4) \quad \underline{a}^*(s, \phi) = \cos \psi^*(s) \underline{e}_1(\phi) + \sin \psi^*(s) \underline{k} \quad ,$$

$$(9.5) \quad \underline{b}^*(s, \phi) = -\sin \psi^*(s) \underline{e}_1(\phi) + \cos \psi^*(s) \underline{k} \quad .$$

where $\psi^*(s)$ is the angle between the direction of the tangent vector to the curve $\underline{r}^*(\cdot, 0)$ at s and that of $\underline{e}_1(\phi)$.

Deformed Configuration

The axisymmetrically deformed configuration of an axisymmetric shell is determined by a pair of continuously differentiable functions

$$(9.6) \quad [0, L] \times [0, 2\pi] \ni (s, \phi) \mapsto \underline{r}(s, \phi), \underline{b}(s, \phi)$$

where

$$(9.7) \quad \underline{r}(s, \phi) = r(s) \underline{e}_1(\phi) + z(s) \underline{k} \quad ,$$

$$(9.8) \quad \underline{b}(s, \phi) = -\sin \psi(s) \underline{e}_1(\phi) + \cos \psi(s) \underline{k} \quad .$$

Define

$$(9.9) \quad \underline{\tilde{a}}(s, \phi) = \cos \psi(s) \underline{\tilde{e}}_1(\phi) + \sin \psi(s) \underline{\tilde{k}} \quad ,$$

$$(9.10) \quad \underline{\tilde{r}}_{,s}(s, \phi) = v(s) \underline{\tilde{a}}(s, \phi) + \eta(s) \underline{\tilde{b}}(s, \phi) \quad ,$$

$$(9.11) \quad \underline{\tilde{r}}_{,\phi}(s, \phi) = r(s) \underline{\tilde{e}}_2(\phi) \quad ,$$

where $\underline{\tilde{r}}_{,s}(s, \phi)$ and $\underline{\tilde{r}}_{,\phi}(s, \phi)$ are partial derivatives of $\underline{\tilde{r}}(s, \phi)$ with respect to s and ϕ . (See Fig. 9-2)

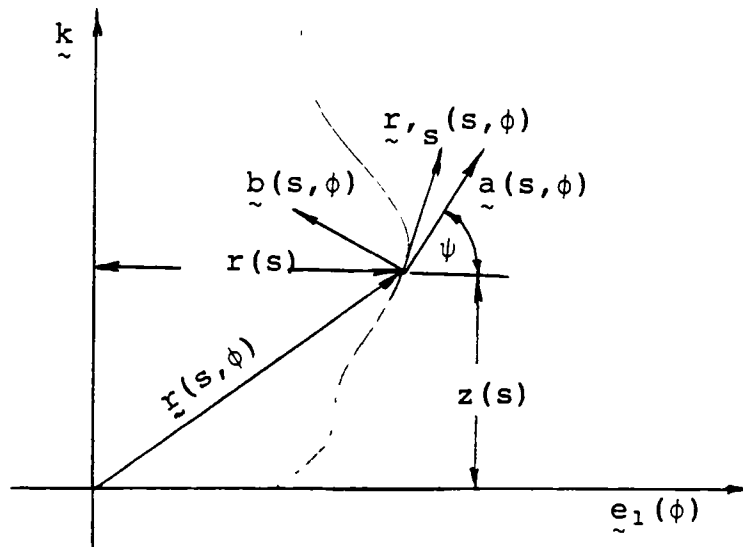


Fig. 9-2.

Deformed Configuration

The strain variables (which do not all vanish in the reference configuration) consist of invariants (namely the scalar product and scalar triple products) of

$$(9.12) \quad \underline{\tilde{r}}_{,s}(s, \phi) = v \underline{\tilde{a}}(s, \phi) + \eta \underline{\tilde{b}}(s, \phi) \quad ;$$

$$\underline{\tilde{b}}_{,s}(s, \phi) = -\psi' \underline{\tilde{a}}(s, \phi) \quad ;$$

$$\begin{aligned} \tilde{r}_{,\phi}(s, \phi)/r^*(s) &= [r(s)/r^*(s)] \tilde{e}_2(\phi) ; \\ \tilde{b}_{,\phi}(s, \phi)/r^*(s) &= -[\sin \psi(s)/r^*(s)] \tilde{e}_2(\phi) . \end{aligned}$$

These invariants depend only on

$$\bullet \quad (9.13) \quad \tilde{w}(s) = (v, \tau, \eta, \mu, \sigma) ,$$

where

$$(9.14) \quad \tau(s) = r(s)/r^*(s) ;$$

$$(9.15) \quad \mu(s) = \psi' - (\psi^*)' ;$$

$$(9.16) \quad \sigma(s) = \sin \psi(s)/r^*(s) - \sin \psi^*(s)/r^*(s)$$

and the prime denotes the derivative with respect to s .

REMARKS. (1) In the case of a spherical shell of radius 1, where $\psi^*(s) = s$, $r^*(s) = \sin s$, we have $v = \tau = 1$, $\eta = 0$, $\sigma = \mu = 0$ in the reference configuration. Thus $v - 1$ is a measure of longitudinal strain, $\tau - 1$ the meridional strain, η the shear strain and σ and μ are the circumferential and longitudinal bending strains respectively. Note that $\mu + 1$ and $\sigma + 1$ are almost curvatures.

(2) In the uniform contraction and expansion of a spherical shell into one of different radius, $v - 1$ and $\tau - 1$ change but μ and σ remain zero, so that μ and σ isolate the effects of bending.

EQUILIBRIUM EQUATIONS.

We suppose the shell is subjected to a uniform external hydrostatic pressure of constant intensity λ per unit actual area. Accordingly, the corresponding force per unit reference area of the shell is

$$(9.17) \quad \lambda \frac{\frac{\tilde{r}_{,s} \times \tilde{r}_{,\phi}}{|\tilde{r}_{,s}| |\tilde{r}_{,\phi}|}}{\frac{\tilde{r}_{,s} \times \tilde{r}_{,\phi}}{|\tilde{r}_{,s}^* \times \tilde{r}_{,\phi}^*|}} = \lambda \frac{\tilde{r}_{,s} \times \tilde{r}_{,\phi}}{r^*} .$$

Let

\tilde{n}_1 be contact force resultant per unit reference length acting across $s = \text{constant}$.

\tilde{n}_2 be contact force resultant per unit reference length acting across $\phi = \text{constant}$.

\tilde{m}_1 be contact couple resultant per unit reference length acting across $s = \text{constant}$.

\tilde{m}_2 be contact couple resultant per unit reference length acting across $\phi = \text{constant}$.

The equilibrium of total force on the material of $\{(s, \phi) : s_1 \leq s \leq s_2 ; \phi_1 \leq \phi \leq \phi_2\}$ implies

$$(9.18) \quad \int_{\phi_1}^{\phi_2} [\tilde{n}_1(s_2, \phi) r^*(s_2) - \tilde{n}_1(s_1, \phi) r^*(s_1)] d\phi + \\ + \int_{s_1}^{s_2} [\tilde{n}_2(s, \phi_2) - \tilde{n}_2(s, \phi_1)] ds + \\ + \int_{\phi_1}^{\phi_2} \int_{s_1}^{s_2} \lambda \frac{\tilde{r}'_{,s} \times \tilde{r}'_{,\phi}}{r^*} r^* d\phi ds = \underline{0} .$$

If \underline{n}_1 and \underline{n}_2 are continuously differentiable, we can differentiate (9.18) with respect to ϕ_2 and s_2 and then replace ϕ_2 and s_2 with ϕ and s to get

$$(9.19) \quad [\underline{r}^*(s)\underline{n}_1(s,\phi)],_s + \frac{\partial \underline{n}_2}{\partial \phi}(s,\phi) + \lambda \underline{r},_s(s,\phi) \times \\ \times \underline{r},_\phi(s,\phi) = \underline{0} \quad .$$

The equilibrium of total moments on the same shell element implies

$$(9.20) \quad \int_{\phi_1}^{\phi_2} (\underline{r} \times \underline{n}_1 + \underline{m}_1) \underline{r}^*(s) \Big|_{s_1}^{s_2} d\phi + \int_{s_1}^{s_2} (\underline{r} \times \underline{n}_2 + \underline{m}_2) \\ \Big|_{\phi_1}^{\phi_2} ds + \lambda \int_{\phi_1}^{\phi_2} \int_{s_1}^{s_2} \underline{r} \times (\underline{r},_s \times \underline{r},_\phi) ds d\phi = \underline{0} \quad .$$

Thus, if \underline{m}_1 and \underline{m}_2 are continuously differentiable, we obtain

$$(9.21) \quad [\underline{r} \times \underline{n}_1 \underline{r}^*(s)],_s + [\underline{r}^*(s)\underline{m}_1],_s + (\underline{r} \times \underline{n}_2 + \underline{m}_2),_\phi + \\ + \lambda \underline{r} \times (\underline{r},_s \times \underline{r},_\phi) = \underline{0} \quad .$$

Substituting (9.19) into (9.21), we get

$$(9.22) \quad [\underline{r}^*(s)\underline{m}_1(s,\phi)],_s + \underline{r},_s(s,\phi) \times \underline{r}^*(s)\underline{n}_1(s,\phi) + \\ + \underline{m}_2,_\phi = \underline{0} \quad .$$

We seek axisymmetric solutions, for which we require

$$(9.23) \quad \underline{\underline{n}}_1(s, \phi) = \hat{N}(s) \underline{\underline{a}}(s, \phi) + \hat{H}(s) \underline{\underline{b}}(s, \phi) \quad ,$$

$$(9.24) \quad \underline{\underline{n}}_2(s, \phi) = \hat{T}(s) \underline{\underline{e}}_2(\phi) \quad ,$$

$$(9.25) \quad \underline{\underline{m}}_1(s, \phi) = -\hat{M}(s) \underline{\underline{e}}_2(\phi) \quad ,$$

$$(9.26) \quad \underline{\underline{m}}_2(s, \phi) \cdot \underline{\underline{e}}_2 = 0 \quad .$$

Thus

$\underline{\underline{m}}_2 = (\underline{\underline{m}}_2 \cdot \underline{\underline{a}}) \underline{\underline{a}} + (\underline{\underline{m}}_2 \cdot \underline{\underline{b}}) \underline{\underline{b}}$ with components regarded independent of ϕ . Then

$$(9.27) \quad \frac{\partial \underline{\underline{m}}_2}{\partial \phi} = (\underline{\underline{m}}_2 \cdot \underline{\underline{a}}) \cos \psi \underline{\underline{e}}_2(\phi) - (\underline{\underline{m}}_2 \cdot \underline{\underline{b}}) \sin \psi \underline{\underline{e}}_2$$

$$= \underline{\underline{k}} \times \underline{\underline{m}}_2 \quad .$$

Thus (9.19) and (9.22) become

$$(9.19a) \quad \{r^*(s) [\hat{N}(s) \underline{\underline{a}}(s, \phi) + \hat{H}(s) \underline{\underline{b}}(s, \phi)]\}_{,s} - \hat{T}(s) \underline{\underline{e}}_2(\phi) +$$

$$+ \lambda r(s) \underline{\underline{r}}(s, \phi)_{,s} \times \underline{\underline{e}}_2(\phi) = \underline{\underline{0}} \quad .$$

$$(9.22a) \quad [r^*(s) \hat{M}(s)]_{,s} + r^*(s) [\nu \hat{H}(s) - \eta \hat{N}(s)] - (\underline{\underline{k}} \times \underline{\underline{m}}_2) \cdot \underline{\underline{e}} = \underline{\underline{0}}.$$

Now we set $(\underline{\underline{m}}_2 \cdot \underline{\underline{a}}) \cos \psi(s) - (\underline{\underline{m}}_2 \cdot \underline{\underline{b}}) \sin \psi(s) = \hat{\Sigma}(s) \cos \psi(s)$

to obtain

$$(9.22b) \quad [r^*(s)\hat{M}(s)]' + r^*(s)(\nu\hat{H} - \eta\hat{N}) - \hat{\Sigma}(s)\cos\psi(s) = 0 \quad .$$

SPECIALIZATION TO SPHERICAL SHELLS.

Without loss of generality we take the shell radius to be 1. Thus $r^*(s) = \sin s$, $\psi^*(s) = s$, $z^*(s) = -\cos s$, $L = \pi$, and equilibrium equations (9.19a) and (9.22b) become

$$(9.28a) \quad [\hat{N}(s)\sin s]' - \hat{T}(s)\cos\psi(s) - \lambda r\eta - \hat{H}(s)\sin s\psi'(s) = 0 \quad ,$$

$$(9.28b) \quad [\hat{H}(s)\sin s]' + \hat{T}(s)\sin\psi(s) + \lambda r\nu + \hat{N}(s)\sin s\psi'(s) = 0 \quad ,$$

$$(9.28c) \quad [\hat{M}(s)\sin s]' - \hat{\Sigma}(s)\cos\psi(s) + (\nu\hat{H} - \eta\hat{N})\sin s = 0 \quad .$$

In order to understand the component Σ occurring in (9.22b), it is convenient to have recourse to the principle of virtual work.

Let $\underline{y}(s, \phi)$, $\underline{x}(s, \phi) \in C^2(\Omega)$ with compact support, where $\Omega = [s_1, b] \times [\phi_1, \beta]$, $0 \leq b \leq L$, $0 \leq \beta \leq 2\pi$. The principle of virtual work requires that

$$(9.29) \quad 0 = \int_{\phi_1}^{\beta} \int_{s_1}^b \{ r^* \underline{n}_1 \cdot \underline{y}_{,s} + \underline{n}_2 \cdot \underline{y}_{,\phi} + (\underline{r} \times \underline{n}_1 + \underline{m}_2) r^* \underline{x}_{,s} + \\ + (\underline{r} \times \underline{n}_2 + \underline{m}_2) \cdot \underline{x}_{,\phi} - \lambda (\underline{r}, \underline{s} \times \underline{r}, \phi) \cdot \underline{y} - \lambda \underline{r} \times (\underline{r}, \underline{s} \times \underline{r}, \phi) \cdot \underline{x} \} ds d\phi \quad .$$

It is convenient to use the traditional notations. Let δv , $\delta \eta$ and $\delta \psi$ be in $C^2(\Omega)$ with compact supports and set

$$(9.30) \quad \underline{y} = \delta \underline{r} - (\underline{r} \times \underline{e}_2) \delta \psi ; \quad \underline{x} = -\delta \psi \underline{e}_2 ,$$

where

$$(9.31) \quad (\delta \underline{r})_{,s} = \delta \underline{r}_{,s} = \delta v \underline{a} + \delta \eta \underline{b} + (v \underline{b} - \eta \underline{a}) \delta \psi .$$

Thus,

$$(9.32) \quad \delta \underline{r}_{,\phi} = \delta r \underline{e}_2 = (\delta v \cos \psi - \delta \eta \sin \psi - v \sin \psi \delta \psi - \eta \cos \psi \delta \psi) \underline{e}_2 .$$

Also, we get

$$(9.33) \quad \delta \tau = \frac{\delta r}{r^*} ,$$

$$(9.34) \quad \delta \sigma = \frac{\delta \psi}{r^*} \cos \psi ,$$

$$(9.35) \quad \delta \mu = \delta \psi' ,$$

$$(9.36) \quad \underline{x}_{,\phi} = \delta \psi \underline{e}_1 .$$

Thus (9.29) becomes

$$(9.37) \quad 0 = \int_{\phi_1}^{\beta} \int_{s_1}^b (N\delta v + H\delta\eta + T\delta\tau + M\delta\mu + \Sigma\delta\sigma) \mathbf{r}^* ds d\phi - \\ - \lambda \int_{\phi_1}^{\beta} \int_{s_1}^b (\mathbf{r}_{,s} \times \mathbf{r}_{,\phi}) \cdot \delta \mathbf{r} ds d\phi \quad .$$

This is the traditional form of the principle of virtual work with Σ as the generalized force corresponding to the strain variable σ .

Note that in the expression $(\mathbf{m}_2 \cdot \mathbf{a}) \cos \psi - (\mathbf{m}_2 \cdot \mathbf{b}) \sin \psi = \hat{\Sigma} \cos \psi$, we do not imply that $\hat{\Sigma} = \mathbf{m}_2 \cdot \mathbf{a}$ and that $\mathbf{b} \cdot \mathbf{m}_2 = 0$.

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