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Universal Test Fixture
for Monolithic mm-Wave
Integrated Circuits
Calibrated With an
Augmented TRD Algorithm

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Summary

The design and evaluation of a novel fixturing technique for characterizing millimeter-wave solid-state devices is presented. The technique utilizes a cosine-tapered ridge guide fixture and a one-tier de-embedding procedure to produce accurate and repeatable device-level data. Advanced features of this technique include nondestructive testing, full waveguide bandwidth operation, universality of application, and rapid, yet repeatable, chip-level characterization. In addition, only one set of calibration standards is required regardless of the device geometry.

Introduction

The accurate characterization of solid-state devices at and above K-band is hindered by limited metrological techniques due to increased parasitics, diminutive physical dimensions, and inconvenient interface methods (ref. 1). The quality of device characterization will inevitably affect the integrity of the intended application. Since many system applications can tolerate only marginal variations in device performance, much effort is spent in accurately quantifying radiofrequency (RF) parameters. Small-signal S -parameter techniques that use automatic vector network analyses are fundamental to this device evaluation.

Typically, microwave and millimeter-wave monolithic integrated circuits (MMIC's), whether packaged or in die form, must be mounted in a fixture which provides a means to connect the chip to the automatic network analyzer (ANA) via coaxial cables or rectangular waveguide. The fixture introduces substantial insertion and return loss effects, both in magnitude and phase, often masking the true device characteristics. Calibration is normally done at the ANA transmission line-to-fixture interface by using known standards. Consequently, the measurement (reference) plane is removed from the physical device terminals by the fixture geometry. *This discrepancy can be compensated for with a procedure known as de-embedding. The technique requires applying chip-level microstrip standards to mathematically shift the reference plane to the device area. A detailed discussion of the calibration and de-embedding procedures is given in the section Fixture Calibration.*

Drawbacks of existing fixtures include the inability to obtain repeatable data, the difficulty in securing a device in the

fixture, the complexity of calibrating the fixture, and the limitations on bandwidth imposed by the waveguide-to-microstrip transition. In addition, most techniques are destructive to the device and are labor intensive. This report describes the evolution of a new test fixture with several innovative features that is operable over the K_a band (26.5 to 40.0 GHz). A photograph of the fixture is shown in figure 1.

A cosine-tapered ridge transition matches the high waveguide impedance to the 50- Ω microstrip. The taper length and profile have been analytically determined to provide maximum bandwidth and minimum insertion loss. Integrated circuits and devices are mounted on a customized carrier which is inserted between the bottom of the ridge and the base of the waveguide. The electric field is concentrated by the ridge and launched onto the carrier microstrip via direct pressure contact. Isolation between the device under test and the fixture, as well as bias/control circuitry, is also provided by the carrier. Control voltages are applied to the carrier by a self-aligned bias module with integral spring-loaded contacts. The carrier assembly is designed for direct insertion into a given system, such as a phased array, and thus serves the dual role of test vehicle and package. De-embedding is accomplished with *through-reflect-delay* (TRD) microstrip standards and software. These calibration standards set the ancillary reference plane at the bisector of the chip carrier. Then, the complex propagation constant of the carrier microstrip line is determined from the standards, and the reference plane is subsequently shifted to the device boundaries. Figure 2 illustrates this concept.

Chip Carrier Design

The most complex component of the test fixture is the chip carrier. Since the fixture itself is mechanically rigid to improve data repeatability, the required versatility was built into the carrier. A 0.020-in. alumina substrate was chosen for its manufacturability, good dielectric properties, and relatively good thermal and mechanical characteristics. The substrate thickness was constrained to a narrow range by line-width restrictions. Whereas the lithography process imposed a minimum feature size on the coupled-line section, the possibility of generating surface waves imposed a maximum substrate thickness. A 0.020-in. substrate was a suitable compromise for K_a band. Features of the carrier include coupled-line direct-current (dc) blocks, input (gate) and output

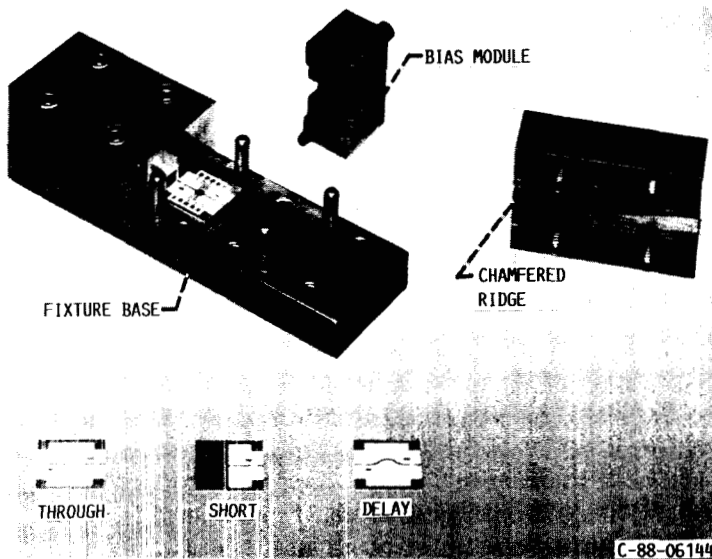


Figure 1.—Partially disassembled view of cosine-tapered ridge guide fixture along with through-reflect-delay (TRD) calibration standards. Monolithic 30-GHz gain control amplifier is mounted on carrier.

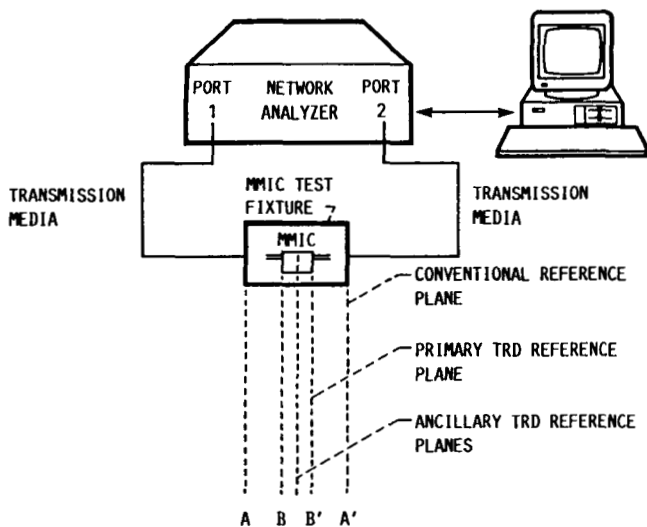
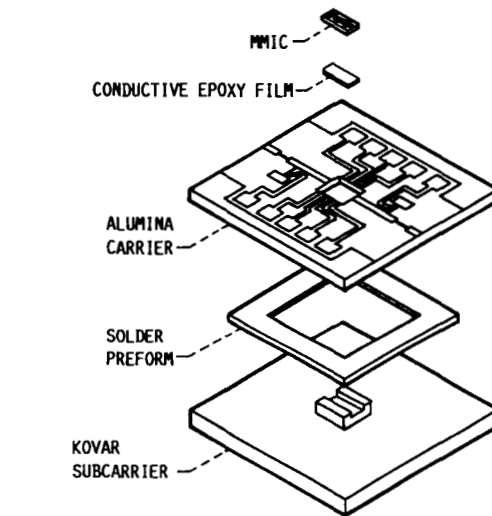
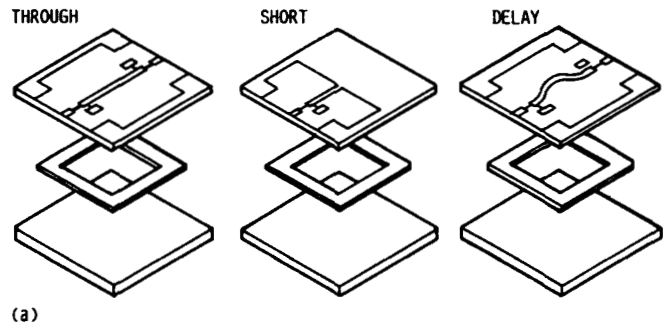


Figure 2.—Simplified diagram denoting relationship among various reference planes.

(drain) bias filters, and 10 bias pads. A key feature of the design is a generic footprint; that is, except for a central area on the carrier, the metalization pattern is common for all chip and device types. Figure 3 highlights the carrier topology and demonstrates the assembly.

The dc blocks are required since the carrier microstrip lines are in contact with the fixture body, which is at ground potential. The obtainable bandwidth of the dc blocks is a strong function of the gap between the coupled lines. A 0.002-in. gap and a 0.032-in.-long coupled section with 0.0029-in.-wide fingers were found to be optimum (refs. 2 and 3). The dc block design was modeled with commercially available software which predicted an insertion loss of less than 0.25 dB over



(a) Through-short-delay (TSD) calibration standards.
(b) Chip carrier assembly.

Figure 3.—Detailed schematic of calibration standards.

most of the band. The chip was mounted in a laser-machined well in the center of the carrier and supported by a gold-plated kovar subcarrier. A mesa was machined on the kovar subcarrier such that the surfaces of the chip and alumina carrier were flush. The mesa was extended beyond the width of the chip to accommodate chip capacitors, if necessary, and to facilitate grounding requirements. The carrier was bonded to the kovar with a special indium alloy preform by heating to 210 °C. Subsequent to this procedure, the die was attached with silver-impregnated epoxy which was cured at 125 °C. The carrier can accommodate chips up to 0.250 in. long.

Bias could be fed directly to the chip input and output microstrip lines, if required, through two bias filters. The filters consisted of a midband quarter-wavelength high impedance line cascaded with a quarter-wavelength, open-circuit, low impedance line. The input impedance of this combination was extremely high over a significant bandwidth and served to isolate the RF from the bias supply. Actual dc contact was made at the junction of the two quarter-wavelength lines so as not to perturb the impedance.

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Transition Design

A number of transition candidates were reviewed for coupling the waveguide to the microstrip. Most had inherent bandwidth limitations and required complex mounting arrangements. In addition, bonding was normally required to attach the transition to the microstrip. The finline transition, for example, possesses an in-band resonance which must be tuned-out from the desired frequency range. The probe-type transition must be mounted perpendicular to the waveguide axis and is sensitive to placement. Both transitions must be wire- or ribbon-bonded to the microstrip, which adds to the fixturing complexity and testing time and compromises data repeatability. The ridge waveguide transition, which is an \vec{E} -plane taper, surmounted these limitations and provided a convenient interface method. Figure 4(a) to (d) illustrates the transition mechanism. Notice that no \vec{E} -field realignment was required. The use of ridge waveguides as transition elements spans several decades (ref. 4). A ridge waveguide has a lower cutoff frequency and greater higher order mode separation than a conventional waveguide with the same aspect ratio. The lower cutoff frequency results from the capacitive effect of the ridge. Although, in principle, the cutoff wavelength could be extended indefinitely, it is limited in practice because of the corresponding impedance limitations. As mentioned earlier, the attractiveness of the ridge waveguide stems from its superior bandwidth, and loss performance, as well as manufacturability. Actually designing the transition involved finding the correct ridge thickness and an acceptable profile to produce an impedance-matching transformer.

The design method first outlined by Singh and Seashore (ref. 5) can be subdivided into three calculations. (Symbols

are defined in appendix A.) The first calculation entails evaluating the ridge waveguide cutoff wavelength λ_c . At the cutoff frequency, propagation may be considered to be restricted to a wave traveling transversely across the guide with no longitudinal component. This can be modeled by an equivalent network consisting of a discontinuity capacitance shunted by two transmission lines. The parallel plate transmission line terminates in a short circuit representing the waveguide wall. The cutoff wavelength is obtained by deriving an expression for the input impedance, which becomes infinite at cutoff. If the ridge is thick and approaches the waveguide sidewall, proximity effects should be taken into account (ref. 6). The resulting equation is transcendental and must be solved numerically. Based on the equivalent circuit model in figure 4(f), the following expression results:

$$1 - Z_2 \omega c \tan \varphi_2 - Z_2/Z_1 \tan \varphi_2 \tan \varphi_1 = 0 \quad (1)$$

where $Z_2 \omega c$ is the normalized junction reactance obtained from reference 5, and $Z_2/Z_1 = b/t$ is the impedance ratio of the equivalent parallel plate lines. The transmission line equivalent lengths at cutoff are φ_1 and φ_2 . Figure 5 illustrates cutoff wavelength in ridge guide as a function of ridge width for various substrate thicknesses. Once the cutoff wavelength is known, the ridge thickness, which is used to tailor the characteristic impedance Z_o , can be determined. Impedance Z_o as a function of frequency can be related to the infinite frequency characteristic impedance $Z_{o\infty}$ through

$$\frac{Z_o(x)}{Z_{o\infty}(x)} = \frac{\lambda_g}{\lambda_o} = \frac{1.0}{\sqrt{1 - \left(\frac{f_c}{f}\right)^2}} \quad (2)$$

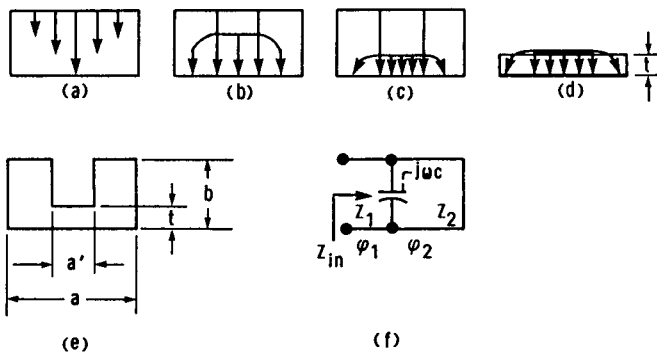


Figure 4.—Schematic depicting how ridge guide transition couples waveguide TE_{10} mode to microstrip quasi-TEM mode and its equivalent circuit at cutoff.

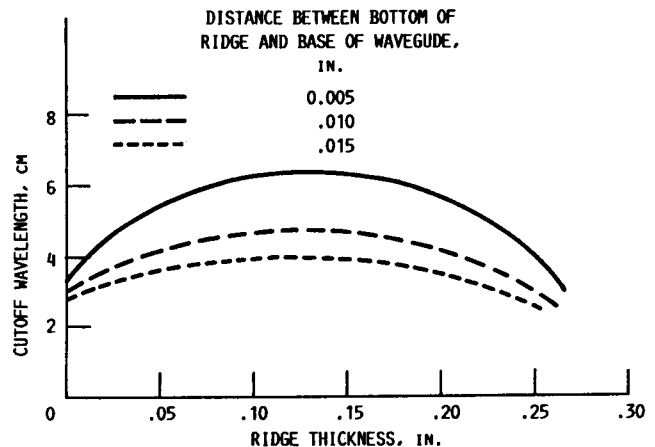


Figure 5.—Cutoff wavelength in ridge guide.

where λ_g is the guide wavelength and λ_o is the free space wavelength. The impedance $Z_{o\infty}$ for the TE₁₀ mode is given by Cohn (ref. 4) as

$$Z_{o\infty} = \frac{120\pi^2 t}{\lambda_c \left[\sin \varphi_1 + \frac{t}{b} \cos \varphi_1 \tan \left(\frac{\varphi_2}{2} \right) \right]} \quad (3)$$

Since the band of interest is significantly above the cutoff frequency, the radical in equation (2) approaches unity and Z_o can be approximated by $Z_{o\infty}$ for the ridge thickness calculation. As for the cutoff wavelength, numerical techniques are required for the solution. The impedance Z_o is a function of ridge height and, hence, a function of position along the taper. The final stage of the design process involves solving for the physical taper, the length of which should provide adequate bandwidth without introducing unnecessary loss. A sinusoidal variation of the form

$$Z_o(x) = \frac{Z_0 + Z_L}{2} - \frac{Z_L - Z_0}{2} \cos \frac{\pi x}{\ell} \quad (4)$$

is assumed (ref. 8). With the possible exception of a Dolph-Tchebycheff profile, the sinusoidal taper outperforms other candidate tapers by minimizing the return loss in a given length. For example, a sinusoidal transition performs as well as a linear transition but is only half as long. The length of the taper is ℓ , and x is the position along the taper from its origin. The characteristic impedances of the open waveguide at $x = 0$ and the ridge guide at $x = \ell$, are Z_0 and Z_L , respectively. Both impedances were calculated at the midband frequency. The taper provides a smooth transition from the full waveguide height to the substrate thickness and couples the dominant TE₁₀ waveguide mode to the quasi-TEM microstrip mode. Substituting equation (3) into equation (2) yields an expression for the taper height t as a function of position:

$$t = \frac{\lambda_c \sqrt{1 - \left(\frac{f_c}{f} \right)^2} Z_o(x) \sin \varphi_1}{120\pi^2 - \frac{\lambda_c}{b} \sqrt{1 - \left(\frac{f_c}{f} \right)^2} Z_o(x) \cos \varphi_1 \tan \frac{\varphi_2}{2}} \quad (5)$$

A computer program was written to calculate the ridge geometry, given the basic waveguide and substrate dimensional parameters. Based on the previous calculations, a taper length of 1.366 in. ($3\lambda_g$ at 26.5 GHz) and a ridge thickness of 0.0695 in. were chosen. A smooth chamfer was machined at the end of each transition to eliminate sharp edges and, hence, reduce radiation. Performance data are included in the section

Test Fixture Radiofrequency Performance. Taper profile coordinates are included in table I for this 26.5- to 40.0-GHz case as well as other waveguide bands up to 110 GHz.

Bias Module Design

A single-piece bias module was developed to supply the device being tested with the necessary bias and control power. The most important feature of this module is its ability to make solid, repeatable, nondestructive electrical connections to metalized pads on the alumina chip carrier. To do this, the bias module relies on the contacting properties of miniature spring-loaded plunger contacts. The contacts are mounted vertically in a single block of insulating material that serves as an alignment guide, contact support structure, and RF shield. This block is manufactured from a machinable material with dielectric properties similar to Lexan or Rexolite.

The bias module feeds power directly to the chip carrier through 10 spring-loaded contacts. Each contact consists of two parts—a spring-loaded plunger contact and a contact sleeve. Each plunger contact body has a slight deformation (bow) to retain it by friction in the contact sleeve. The obvious advantage of the two-piece design is that the pin contact can be easily replaced if damaged, or changed to another contact type if desired. A solder cup in the closed end of the contact sleeve provides a solderable connection to the pin assembly. Both the contact and contact sleeve are manufactured from nickel-silver alloy for high electrical conductivity. Each contact sleeve has a small rectangular collar on its open end. If the collar is carefully designed and machined, it can be used to seat the pin assembly and oppose the compression forces of the contact springs. This seating then maintains the vertical clearance of the pins over the chip carrier and ensures uniform contact pressure at all times.

To achieve the proper contact positioning, the bias module is equipped with precisely aligned holes parallel to the vertical axis of the contact block. Cylindrical posts inserted into the fixture base guide the bias module down vertically onto the chip carrier. The bias module is then secured to the test fixture with two thumbscrews to enable quick assembly and disassembly. Center-to-center contact spacing for this application was selected as 0.062 in. to provide firm mechanical support for the pin assemblies. The insulating material of the bias block provides electrical isolation.

If testing indicates the presence of severe electromagnetic interference, the bias module is designed to facilitate the insertion of an RF shielding structure. This shield may be nothing more than conductive foil lining the clearance cavity inside the bias module, or it may be a machined insert to the module. In either case, the cavity resonances must be considered to prevent misleading test results or unpredictable side effects.

In all, the bias module represents a novel, yet simple, way to apply the bias to the chip carrier. The design can be used

for a variety of carrier layouts and can be scaled to meet the needs of various frequency ranges.

Fixture Calibration

To extract device-level data, a de-embedding technique which removes all systematic errors, including those introduced by the fixture, must be used. Numerous de-embedding procedures exist, each offering a unique set of advantages and disadvantages. Since each measurement required by a specific technique introduces some additional error, it is desirable to minimize the number of calibration standards. Furthermore, standards such as accurate loads and predictable open circuits are difficult to implement in a microstrip, especially at millimeter wavelengths. To curtail the proliferation of measurement errors, a novel technique, first proposed by Franzen and Speciale (ref. 9) was chosen. The method uses a one-tier calibration and assumes an eight-term error model. Only three standards are required. A photograph of the set of a typical calibration standard along with a chip carrier is provided in figure 6.

The model topography is illustrated in figure 7. The two-port networks to the left and right of the device represent hardware and fixture effects as well as the carrier coupled lines and bias filters. Recall that the primary reference plane is adjacent to the chip and excludes much of the carrier topology.

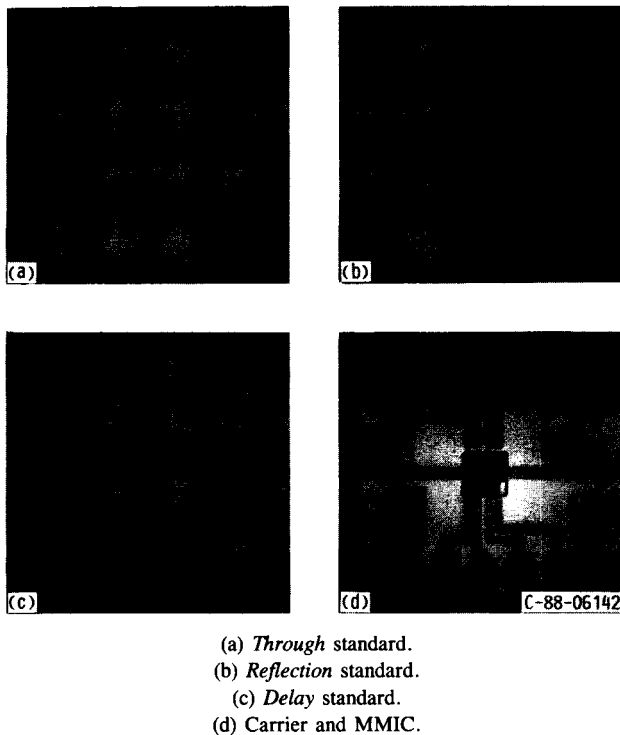


Figure 6.—Cosine-tapered ridge guide fixture calibration standards and chip carrier.

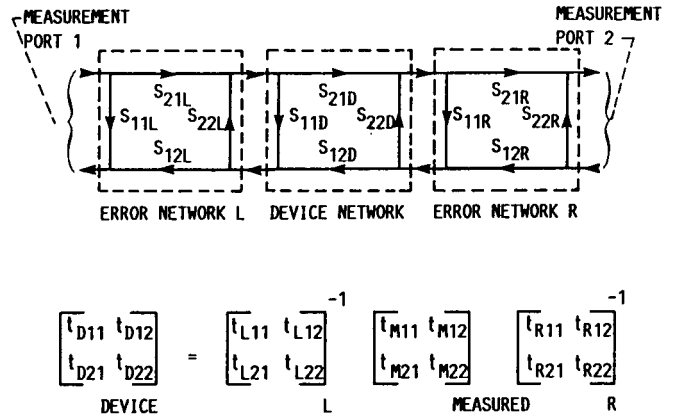


Figure 7.—Eight-term cascaded two-port error model for *through-reflect-delay* (TRD) technique and equivalent chain matrix derivation of device parameters.

Three measurements must be made to acquire the needed calibration data and resolve the individual error terms of the model. The first entails measuring a microstrip *through* calibration standard for which the input and output reference planes are coincident. The second requires measuring a *delay* microstrip line which is inserted between the reference planes. A prior knowledge of the length and propagation constant of the line is not required to establish the ancillary reference plane; however, the length is constrained to a limited range because of mathematical considerations which are described in appendix B. For the K_a band on the 0.020-in. alumina, a 0.028-in.-long *delay* was chosen. This corresponds to a theoretical phase shift of $\sim 60^\circ$ to 95° across the band. The line, which uses a slight bow in the microstrip for the added length, is assumed to behave as a linear delay—that is, there are no discontinuity or coupling effects from the curvature. The final calibration standard is a highly reflective termination which is required to resolve a phase ambiguity in the equations and results in a solution to error terms S_{22L} and S_{11R} . Initially, a microstrip short circuit was used to provide this standard. Note that all three standards incorporate the dc blocks and bias filters so that their effects are accounted for in the de-embedding routine.

To place the primary reference planes at the chip boundaries, error coefficients are shifted through an electrical translation. Initially, the reference plane is set at the center of the carrier. Subsequent to the initial physical calibration, this ancillary reference plane is mathematically shifted to the device boundaries through the translation $e^{-\gamma \ell}$. Consequently, the exact length ℓ of the device must be known. The complex propagation constant γ , however, is determined from the *through* and *delay* measurements. This manipulation permits the use of only one set of standards, regardless of device periphery.

Since the topography of the model consists of three cascaded two-port networks, the measured S -parameters of the error

networks and inserted device can be converted to T -parameters for convenience. The T -matrix of the model is equal to the product of the individual T -matrices; therefore, the matrix of the de-embedded device can be extracted and reconverted to S -parameters (fig. 7). The mathematical derivation, which assumes that the microstrip characteristic impedance is 50 Ω (independent of frequency), treats the left and right halves of the fixture independently—that is, no assumption is made regarding symmetry and reciprocity (ref. 10). Furthermore, the model neglects fringing capacitance from the microstrip line to ground at the input and output of the chip as well as any coupling admittance. Including these parasitic reactances would require additional standards, and this was contrary to the design philosophy of maximizing repeatability and accuracy by minimizing mechanical and electrical complexity. From the TRD measurements and the stated assumptions, all 16 terms (magnitude and phase) of the error networks can be determined.

Software was created to carry out the enhanced TRD calibration algorithm on a Hewlett-Packard 9836 desktop computer. The computer program, written in BASIC, performs all the instrument control functions, the data acquisition and transfer routines, and the TRD matrix calculations. This de-embedding code is shown in Appendix C.

The TRD program begins with the transfer of raw, uncorrected S -parameter data from the ANA. The data arrive in 10 sets: 4 sets describe the *through* standard (S_{11} , S_{12} , S_{21} , S_{22}); 4 sets describe the *delay* standard (S_{11} , S_{12} , S_{21} , S_{22}); and 2 sets describe the *reflection* standard (S_{11} , S_{22}). Each data set includes a complete 201-point frequency sweep and presents data in real/imaginary pairs. The data can be transferred directly from the active ANA trace memory or from storage locations on an internal tape drive. The transferred data are then held in computer memory and withdrawn by the TRD calculation subroutine as needed.

The second section of the TRD code performs the actual error-coefficient calculations. During this subroutine, each of the necessary calculations is performed at each step in the frequency range. The entire calculation procedure takes approximately 2 minutes. Once completed, the error-terms are stored in memory arrays. Each error term is made up of a real and an imaginary component, thereby correcting for both magnitude and phase aberrations of the test system. This set of eight error terms establishes the reference plane at the bisector of the *through* line.

To mathematically shift the reference plane to the edges of the device under test, the computer program must know the exact device length. The value is entered from the keyboard in mils (thousandths of an inch). This section of the program is isolated from the rest of the calculations so that different lengths can be entered without having to recalculate the eight basic error terms. This approach saves time and allows convenient testing of various sized chips. The original set of unshifted terms is retained for later use if needed. The shifted

error terms are placed in complex data arrays in a format compatible with the ANA protocol.

After the TRD error model has been generated, there are two possible methods to extract the device data from the full measurement. One choice is to extract the device data by using the set of eight error terms with the HP 9836 computer, and then to return the S -parameter data to the ANA for display. Since this is the most straightforward and accurate approach, it was adopted for this application. Unfortunately, the quasi-real-time display of the data is compromised. An alternative approach would be to translate the 8 TRD error terms to the HP 12-term error model. In this way, the ANA would resume control of the test system and the data trace would be updated virtually in real time. This approach is appealing because it would allow the engineer to actively tune or control the device under test while viewing the results. However, the adaptation to the 12-term model requires additional assumptions which may not be justified. The following error-term translations between the two models are (as given in ref. 11):

$$\begin{array}{ll} E_{DF} = S_{11L} & E_{DR} = S_{22R} \\ E_{SF} = S_{22L} & E_{SR} = S_{11R} \\ E_{RF} = S_{21L}S_{12L} & E_{RR} = S_{21R}S_{12R} \\ E_{XF} = 0 & E_{XR} = 0 \\ E_{LF} = S_{11R} & E_{LR} = S_{22L} \\ E_{TF} = S_{21R}S_{21L} & E_{TR} = S_{12R}S_{12L} \end{array}$$

Test Fixture Radiofrequency Performance

The RF characteristics of the ridge waveguide test fixture were measured with a Hewlett-Packard 8510 ANA. To extend the operating range of the analyzer to include the K_a band, it was configured with a 26.5- to 40-GHz waveguide test set and the appropriate components to coherently up and down convert the test signals. This arrangement allowed error-corrected, two-port, S -parameter measurements to be made across the full 26.5- to 40.0-GHz frequency range while still maintaining the resolution and functionality of the standard HP 8510 ANA. Because the test set operates in WR-28 waveguide media, direct connection of the ridge waveguide test fixture to the measurement system is possible without transitions of any type.

The RF measurements were made on the ANA by using two different techniques. For evaluation of the test fixture, the ANA was calibrated with precision waveguide standards at the test set waveguide flange. This technique placed the calibration reference planes at the input and output of the fixture so that the RF characteristics of the complete assembly could be measured. The waveguide standards included a flush *short*, a quarter-wavelength *offset short*, and a sliding termination.

Figure 8 displays the results of measurements made when the two cosine-tapered ridge sections were connected back-to-back on a special baseplate (no carrier or transmission line).

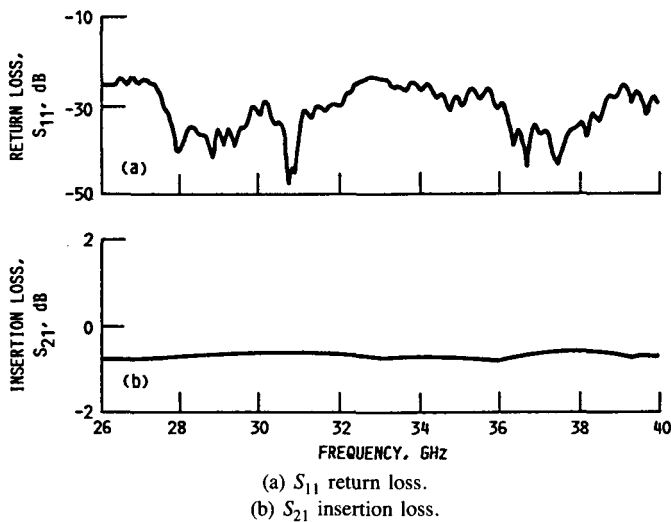


Figure 8.—Characteristics for two back-to-back cosine-tapered ridge guide transitions.

The results show approximately 0.7 ± 0.1 dB of insertion loss (S_{21}) with a corresponding return loss (S_{11}) of greater than 25 dB across the full waveguide band. These measurements verify the predicted performance of low loss and large operating bandwidth.

The next test was also performed with the reference planes placed at the flanges of the test fixture. A section of matched transmission line placed between the two ridge sections was used to test the quality of the compression connection to the microstrip. Figure 9 displays the results of this measurement; the transmission line and interconnect added from 0.25 to 1.25 dB to the loss total. Since the microstrip line itself imparts several tenths of a dB loss, each connection is apparently

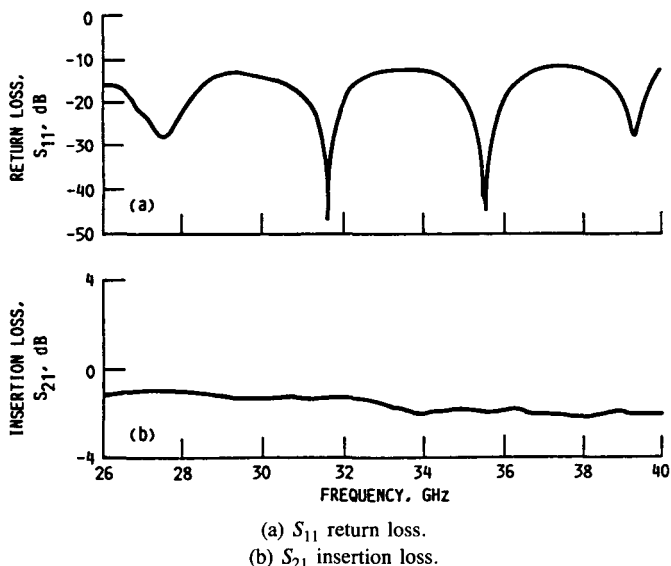


Figure 9.—Characteristics of uncalibrated fixture with 0.5-in. section of microstrip line inserted between transitions.

responsible for a maximum of about 0.5 dB. The TRD algorithm can compensate for these effects.

To test the accuracy of the TRD algorithm and associated hardware, the fixture was calibrated by using the *through*, *short*, and *delay* microstrip standards, and the error correction was verified by reinserting the *through* standard. This is equivalent to connecting the system without a test device. Ideally, this would result in 0-dB insertion loss, 0° phase shift, and infinite return loss. The actual test results are presented in figure 10. The insertion loss was measured at approximately 0.1 dB and the phase shift was 0.5° . The return loss was measured at nearly 40 dB across the frequency range, thereby indicating a high quality calibration. During initial testing, S_{22} performance was marginal. Upon further investigation the electrical quality of the short circuit was found to be questionable. Therefore, an open circuit was substituted, and the fixture was recalibrated. These results are shown in figure 11. Insertion loss was better than 0.1 dB with a corresponding phase accuracy of 1.0° . Return loss at both ports exceeded 40 dB across most of the band. The accuracy of these measurements approaches that of lower frequency calibrations and exceeds the accuracy and capabilities of similar systems currently available.

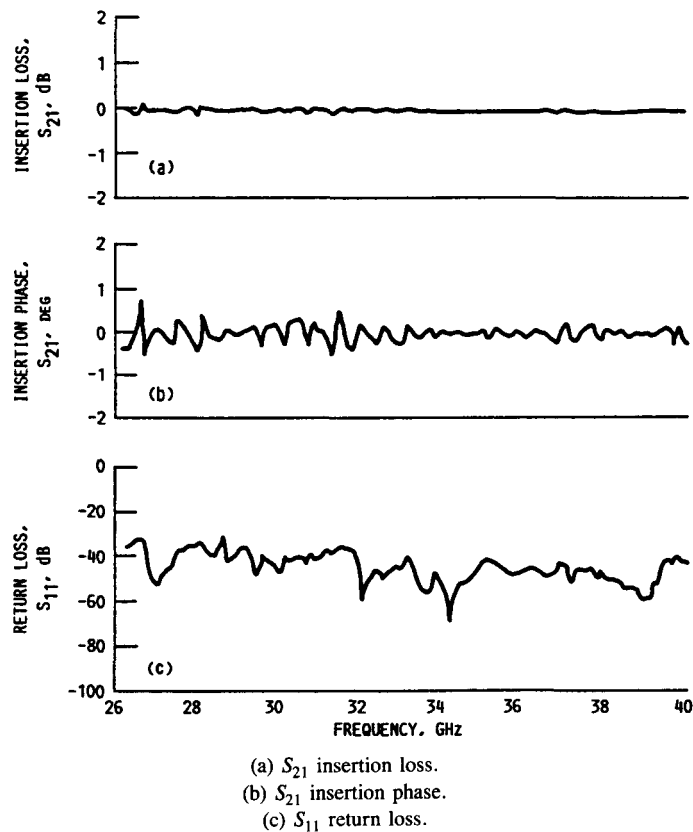
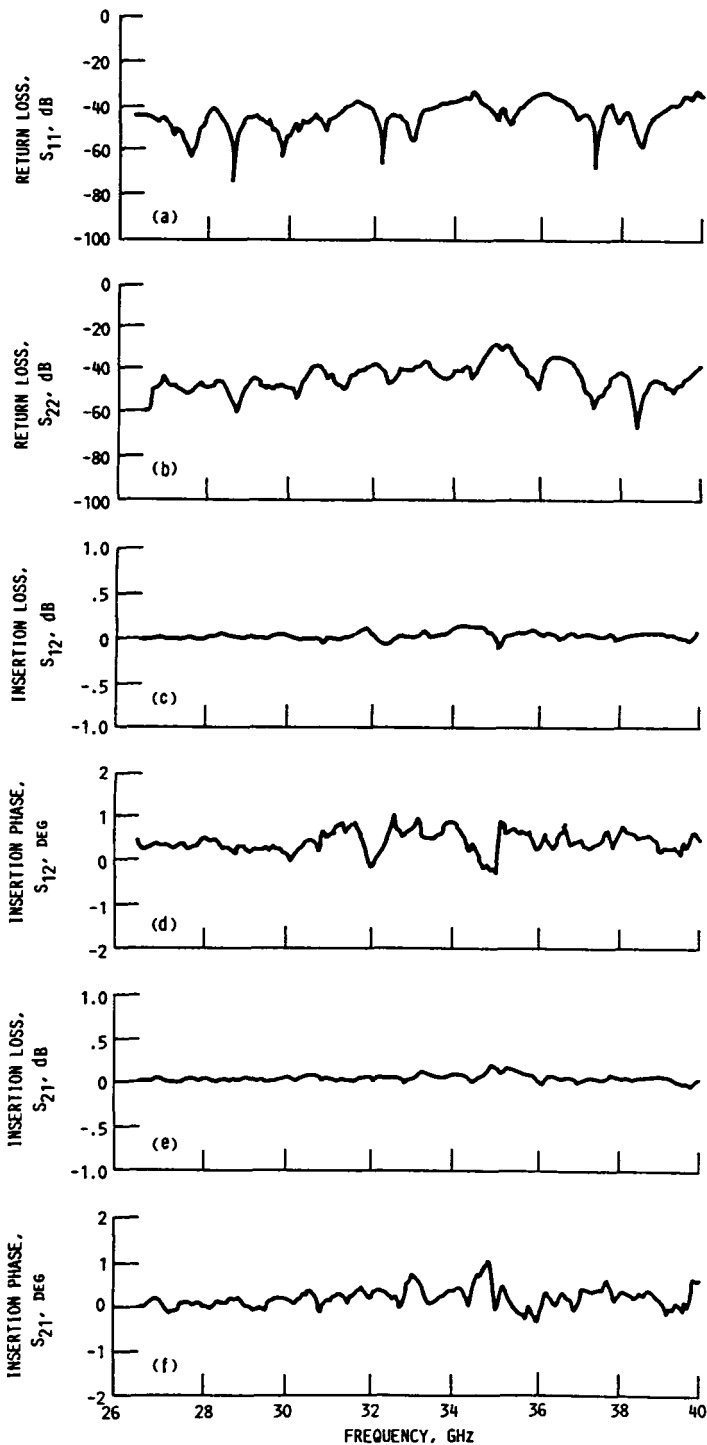


Figure 10.—Through-short-delay (TSD) calibration results.



- (a) S_{11} return loss.
- (b) S_{22} return loss.
- (c) S_{12} insertion loss.
- (d) S_{12} insertion phase.
- (e) S_{21} insertion loss.
- (f) S_{21} insertion phase.

Figure 11.—Through-open-delay (TOD) calibration results.

Conclusions

An innovative fixture was proposed to overcome many of the limitations of conventional techniques for characterizing solid-state devices. Combining a cosine-tapered ridge guide transition, a versatile chip carrier, and an enhanced *through-reflect-delay* calibration algorithm resulted in a mechanically simple, yet functionally sophisticated, fixture. This development provided a unique, previously unavailable ability to perform accurate, nondestructive, and repeatable characterizations of a variety of millimeter-wave devices. Furthermore, the demonstrated RF performance of the fixture and calibration scheme across the K_a band indicated its potential to operate at much higher frequencies.

A primary motive for designing this fixture was the need for a universal solid-state-device characterization method. This method was achieved through the interrelationship of a flexible carrier and a customized software package. The technique enables the fixture to accommodate numerous types of devices without compromising accuracy or convenience. An additional feature of the method is the ability to utilize the device carrier as both the test vehicle and the package; that is after a successful operational test, the carrier is incorporated into a generic package that can then be directly inserted into a system.

NASA Lewis Research Center is pursuing the development of advanced solid-state components, including state-of-the-art discrete devices and monolithic microwave integrated circuits, operating at frequencies up to and beyond 50 GHz. Our fixture is being used to evaluate devices developed under this research effort and to characterize and select those devices suitable for potential use in NASA missions.

Lewis Research Center
National Aeronautics and Space Administration
Cleveland, Ohio, January 23, 1989

Appendix A Symbols

a	h -plane width of the waveguide	T_{Lij}	elements of T_L
a'	width of the ridge	$T_{m,d}$	chain matrix representing measured <i>delay</i> standard
b	\vec{E} -plane waveguide dimension	$T_{m,t}$	chain matrix representing measured <i>through</i> standard
c	junction capacitance	T_R	chain matrix of error network to right of device
E_{DF}	directivity error term in forward direction	T_{Rij}	elements of T_R
E_{DR}	directivity error term in reverse direction	T_t	chain matrix of isolated <i>through</i> standard
E_{LF}	load match error term in forward direction	t	distance between ridge and base at substrate
E_{LR}	load match error term in reverse direction	t_{Lij}	entries in left error chain matrix
E_{RF}	reflection tracking error term in forward direction	t_{Rij}	entries in right error chain matrix
E_{RR}	reflection tracking error term in reverse direction	x	position along taper from origin
E_{SF}	source match error term in forward direction	Z_L	characteristic impedance of ridge waveguide at $x = L$
E_{SR}	source match error term in reverse direction	Z_o	characteristic impedance of microstrip line
E_{TF}	transmission tracking error term in forward direction	$Z_{o,\infty}$	infinite frequency characteristic impedance
E_{TR}	transmission tracking error term in reverse direction	Z_0	characteristic impedance of open waveguide at $x = 0$
E_{XF}	isolation error term in forward direction	Z_1	characteristic impedance of parallel plate line of height t
E_{XR}	isolation error term in reverse direction	Z_2	characteristic impedance of parallel plate line of height b
f_c	cutoff frequency	Z_2/Z_1	impedance ratio of equivalent parallel plate lines
ℓ	length of taper	$Z_2\omega c$	normalized junction reactance
M_{ij}	elements of matrix that is product of $T_{m,d}$ and inverse of $T_{m,t}$	γ	complex propagation constant
N_{ij}	elements of matrix that is product of inverse of $T_{m,t}$ and $T_{m,d}$	λ_c	ridge waveguide cutoff wavelength
S_{ijR}, S_{ijL}	equivalent scattering parameter elements of resolved error networks.	λ_g	guide wavelength
S_{msij}	measured scattering parameter element of <i>short</i>	λ_o	free space wavelength
S_{mtij}	measured scattering parameter element of <i>through</i>	φ_1	electrical length corresponding to $a'/2$
T_d	chain matrix of isolated <i>delay</i> standard	φ_2	electrical length corresponding to $(a - a')/2$
T_L	chain matrix of error network to left of device	ω	radian frequency

Appendix B

Through-Reflect-Delay (TRD) Mathematics

The basis for the derivation of the TRD algorithm is available in the cited references. An abbreviated summary of the mathematical technique is included herein to acquaint the reader with the procedure. A copy of the de-embedding routine, written in HP BASIC, is included for convenience. The TRD augmentation procedure, which relocates the reference plane to the device terminals, is also explained.

The measured scattering matrices are converted to chain (or transfer) matrices for mathematical convenience. By definition, the chain matrix for the *through* standard is

$$[T_t] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad (B1)$$

and the *delay* standard chain matrix, which assumes a frequency-independent 50- Ω match, is

$$[T_d] = \begin{bmatrix} e^{-\gamma\ell} & 0 \\ 0 & e^{\gamma\ell} \end{bmatrix} \quad (B2)$$

The error networks to the left and right of the device are designated $[T_L]$ and $[T_R]$, respectively. The equivalent chain matrix representation of the measured S -parameters of the *through* can be defined by

$$[T_{m,t}] = [T_L][T_t][T_R] = [T_L] [T_R] \quad (B3)$$

Similarly, the chain matrix representation from the *delay* measurement is

$$[T_{m,d}] = [T_L][T_d][T_R] \quad (B4)$$

Multiplying $[T_{m,d}]$ by $[T_{m,t}]^{-1}$ yields equations of the form

$$M_{21} \left(\frac{t_{L11}}{t_{L21}} \right)^2 + (M_{22} - M_{11}) \left(\frac{t_{L11}}{t_{L21}} \right) - M_{12} = 0 \quad (B5)$$

$$M_{21} \left(\frac{t_{L12}}{t_{L22}} \right)^2 + (M_{22} - M_{11}) \left(\frac{t_{L12}}{t_{L22}} \right) - M_{12} = 0 \quad (B6)$$

where the M_{ij} are entries in the resultant matrix $[M]$ and t_{Lij} and t_{Rij} are entries in the left and right error matrices. Multiplying $[T_{m,t}]^{-1}$ by $[T_{m,d}]$ yields equations of the form

$$N_{12} \left(\frac{t_{R11}}{t_{R12}} \right)^2 + (N_{22} - N_{11}) \left(\frac{t_{R11}}{t_{R12}} \right) - N_{21} = 0 \quad (B7)$$

$$N_{12} \left(\frac{t_{R21}}{t_{R22}} \right)^2 + (N_{22} - N_{11}) \left(\frac{t_{R21}}{t_{R22}} \right) - N_{21} = 0 \quad (B8)$$

where the N_{ij} are entries in the resultant matrix $[N]$. As mentioned in the section on fixture calibration, there are some constraints on the length of the *delay*. If the *delay* is very short, its chain matrix will approach the identity matrix and $[T_L]$ and $[T_R]$ will be indeterminate. Also, if the *delay* is a half-wavelength multiple of the *through* and the associated propagation loss is small, a similar situation results. Therefore, the length must be chosen to avoid these extremes by some margin. This constraint limits the TRD technique to octave bandwidth performance. However, the method is ideally suited to conventional waveguide operation for which the bandwidth ratio is typically 1.5. To utilize the full potential, one could design the entire measurement system in ridge guide, if a corresponding bandwidth could be realized with the chip carrier. Comparing the S -parameter equivalents of $[T_L]$ and $[T_R]$ shows that $|t_{L11}/t_{L21}| > |t_{L12}/t_{L22}|$ and that $|t_{L11}/t_{L12}| > |t_{L21}/t_{L22}|$. With this information, the four unknowns can be resolved.

Although the *reflection* calibration standard is necessary to determine S_{22L} , it results in a quadratic, which implies a 180° phase ambiguity. Since the *reflection* should represent a low return loss with roughly a 180° phase shift, the uncertainty can be eliminated. Similarly, an open circuit should result in an in-phase (0°) reflection. Also, the fixture uses the same *reflection* standard during the S_{11} and S_{22} measurement; therefore, no assumption is made regarding the equality of the measured reflection coefficients. The remaining equations result from straightforward algebraic manipulation and signal flow analysis and are listed for convenience as follows:

$$S_{22L} = \left[\left(\frac{t_{L12}/t_{L22} - S_{M511}}{t_{L11}/t_{L21} - S_{M511}} \right) \left(\frac{t_{R11}/t_{R12} + S_{M522}}{t_{R21}/t_{R22} + S_{M522}} \right) \left(\frac{t_{L12}/t_{L22} - S_{M11}}{t_{L11}/t_{L21} - S_{M11}} \right) \right]^{1/2} \quad (B9)$$

$$S_{11R} = \left(\frac{1}{S_{22L}} \right) \left(\frac{t_{L12}/t_{L22} - S_{M11}}{t_{L11}/t_{L21} - S_{M11}} \right) \quad (B10)$$

$$S_{21L}S_{12L} = (t_{L12}/t_{L22} - t_{L11}/t_{L21})S_{22L} \quad (B11)$$

$$S_{12R}S_{21R} = (t_{R11}/t_{R12} - t_{R21}/t_{R22})S_{11R} \quad (B12)$$

$$S_{21L}S_{21R} = S_{M121}(1 - S_{22L}S_{11R}) \quad (B13)$$

$$S_{12R}S_{12L} = S_{M12}(1 - S_{22L}S_{11R}) \quad (\text{B14})$$

The conventional TRD algorithm and the given standards would establish the reference plane at the bisector of the carrier. To shift the error coefficients to the chip terminals, the equivalent electrical length (including loss and dispersion) representing the chip must be known. This requires knowing

the length of the chip and the complex propagation constant, the latter of which is determined from the *through* and *delay* measurements. Both the products of the transmission error coefficients and the *reflection* error coefficients are shifted through the translation $e^{-\gamma\ell}$, where ℓ is the device length. The BASIC program that solves for all eight complex error coefficients and interfaces with the network analyzer is included in appendix C.

Appendix C

Program to Solve for Complex Error Coefficients

This program implements the *through-reflect-delay* de-embedding technique using the Hewlett-Packard model 8510B network analyzer and the model 9836 computer/controller. This version of the software (B3) is designed for use with the

millimeter-wave test set for frequencies between 26.5 and 40.0 GHz.

Currently configured for *open* standard. See lines 6910,6920.

```

270 !
280 !
290 Initialization: !
300 Clear$=CHR$(12)
310 OUTPUT 1;Clear$
320 Crt=1
330 Printer=701
340 PRINTER IS Crt
350 OPTION BASE 1
360 DEG
370 !
380 Thru_flag=0
390 Short_flag=0
400 Delay_flag=0
410 Out_flag=0
420 Calc_flag=0
430 Model_flag=0
440 !
450 BEEP
460 PRINT TAB(10);"***** TSD_CAL_B3 *****"
470 PRINT ""
480 PRINT ""
490 PRINT TAB(10);"You have just activated the THRU-SHORT-DELAY calibration "
500 PRINT TAB(10);"program. To operate the program, please follow the "
510 PRINT TAB(10);"instructions as they appear on this screen."
520 PRINT ""
530 PRINT ""
540 PRINT TAB(10);"NOTE: An IEEE-488 cable must connect this computer"
550 PRINT TAB(10);" to the HP 8510. Install the cable on the connector"
560 PRINT TAB(10);" labeled 'HP-IB' on the rear of the analyzer."
570 PRINT ""
580 PRINT ""
590 PRINT TAB(10);"*****"
600 !
610 DISP " Press CONTINUE to proceed"
620 PAUSE
630 DISP ""
640 !
650 OUTPUT 1;Clear$ ! Establishes Input/Output
660 ASSIGN @To8510 TO 716 ! data transfer paths .
670 CLEAR @To8510 ! "
680 ASSIGN @From8510 TO 716;FORMAT OFF ! "
690 CLEAR @From8510 ! "
700 ASSIGN @DataToana TO 716;FORMAT OFF ! "
710 CLEAR @DataToana ! "
720 ASSIGN @IPIB TO 7 ! "

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730 !
740 DIM Smt_r(201,5),Smt_i(201,5) ! Dimensions array space
750 DIM Smd_r(201,5),Smd_i(201,5) ! in computer memory.
760 DIM Sms_r(201,3),Sms_i(201,3) ! "
770 DIM Sdut_r(201,5),Sdut_i(201,5) ! (S-parameter measurements)
780 DIM Smeas_r(201,5),Smeas_i(201,5)
790 DIM Tmdr(2,2),Tmdi(2,2) ! (T-parameter matrices)
800 DIM Tmtr(2,2),Tmti(2,2) ! "
810 DIM Tmtr_inv(2,2),Tmti_inv(2,2) ! "
820 !
830 DIM Mr(2,2),Mi(2,2) ! ("M" and "N" data matrices)
840 DIM Mr1(2,2),Mi1(2,2) ! "
850 DIM Mr2(2,2),Mi2(2,2) ! "
860 DIM Nr(2,2),Ni(2,2) ! "
870 DIM Nr1(2,2),Ni1(2,2) ! "
880 DIM Nr2(2,2),Ni2(2,2) ! "
890 !
900 DIM E00r(201),E00i(201) ! (Calculated error
910 DIM E11r(201),E11i(201) ! coefficients)
920 DIM E10_e01r(201),E10_e01i(201) ! "
930 DIM E23_e32r(201),E23_e32i(201) ! "
940 DIM E10_e32r(201),E10_e32i(201) ! "
950 DIM E23_e01r(201),E23_e01i(201) ! "
960 DIM E22r(201),E22i(201) ! "
970 DIM E33r(201),E33i(201) ! "
980 !
990 DIM Data(201,2) ! (Data for transfer)
1000 DIM Newdata(201,2) ! "
1010 !
1020 !
1030 INTEGER Preamble,Size ! Used in 8510 data transfer
1040 Preamble=9025 ! (9025 represents #A)
1050 Size=3216 ! (3216 for 201 points,6416 for 401 points)
1060 !
1070 !
1080 !
1090 INPUT "Enter Start Frequency in GHz",Fstart ! Enters start freq.
1100 INPUT "Enter Stop Frequency in GHz",Fstop ! Enters stop freq.
1110 Fstep=(Fstart-Fstop)/200 ! Freq step size
1120 Freq=Fstart
1130 !
1140 REMOTE 716
1150 OUTPUT @To8510;"CORROFF;" ! HP 8510 setup instructions
1160 OUTPUT @To8510;"POIN201;" ! "
1170 !OUTPUT @To8510;"STEP;" <--- Activate for additional accuracy.
1180 !OUTPUT @To8510;"AVERON1000;" <--- Activate for additional accuracy.
1190 OUTPUT @To8510;"SINC;CHAN1;" ! "
1200 OUTPUT @To8510;"STAR";Fstart;"GHZ;" ! "
1210 OUTPUT @To8510;"STOP";Fstop;"GHZ;" ! "
1220 OUTPUT @To8510;"ENTO;" ! "
1230 LOCAL 7
1240 FOR N=1 TO 201 ! Assigns freq to memory
1250 Smd_r(N,5)=Freq ! locations to ease in later
1260 Smd_i(N,5)=Freq ! data recall. (Presently
1270 Smt_r(N,5)=Freq ! unused.)
1280 Smt_i(N,5)=Freq ! "

```

```

1290   Sms_r(N,3)=Freq           !           "
1300   Sms_i(N,3)=Freq           !           "
1310   Sdut_r(N,5)=Freq          !           "
1320   Sdut_i(N,5)=Freq          !           "
1330   Freq=Freq+Fstep          !           "
1340   NEXT N                    !           "
1350   !
1360   !
1370   Menu: !
1380   DISP " Enter desired function on softkeys below"
1390   ON KEY 0 LABEL "THRU" GOSUB Thru
1400   ON KEY 1 LABEL "SHORT" GOSUB Short
1410   ON KEY 2 LABEL "DELAY" GOSUB Delay
1420   ON KEY 3 LABEL "MEAS DUT" GOSUB Dut_meas
1430   ON KEY 4 LABEL "" GOTO Menu
1440   ON KEY 5 LABEL "CALCULATE" GOSUB Calculate
1450   ON KEY 6 LABEL "SEND MODEL" GOSUB Send
1460   ON KEY 7 LABEL "SEND DATA" GOSUB Send_actual
1470   ON KEY 8 LABEL "" GOTO Menu
1480   ON KEY 9 LABEL "EXIT" GOTO Exit
1490   GOTO Menu
1500   !
1510   !
1520   STOP
1530   !
1540   !
1550   !
1560   !
1570   !
1580   !***** SUBROUTINES *****
1590   !
1600   Thru: !                      Reads S-parameter data on the "THRU"
1610   !                      calibration standard from the HP 8510.
1620   !                      (Data in real, imaginary data pairs.)
1630   !
1640   DISP ""
1650   PRINTER IS Crt
1660   OUTPUT 1;Clear$
1670   BEEP
1680   PRINT TABXY(10,6);"Insert the THRU standard in the FORWARD direction"
1690   DISP "Press CONTINUE to proceed"
1700   PAUSE
1710   OUTPUT 1;Clear$
1720   DISP ""
1730   PRINT TABXY(35,6);"PLEASE WAIT"
1740   REMOTE 716
1750   OUTPUT @To8510;"CORROFF;"
1760   !
1770   S11_thru: !                      Reads S11 "THRU" data from 8510
1780   OUTPUT @To8510;"S11;SING;"
1790   OUTPUT @To8510;"FGRM3;OUTPRAW1;"
1800   ENTER @From8510;Preamble,Size,Newdata(*)
1810   FOR N=1 TO 201
1820       Smt_r(N,1)=Newdata(N,1)
1830       Smt_i(N,1)=Newdata(N,2)
1840   NEXT N

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1850     OUTPUT @To8510;"CONT;"
1860     !
1870     !
1880 S21_thru:  !                               Reads S21 "THRU" data from 8510
1890     OUTPUT @To8510;"S21;SING;"
1900     OUTPUT @To8510;"FORM3;OUTPRAW1;"
1910     ENTER @From8510;Preamble,Size,Newdata(*)
1920     FOR N=1 TO 201
1930         Smt_r(N,3)=Newdata(N,1)
1940         Smt_i(N,3)=Newdata(N,2)
1950     NEXT N
1960     OUTPUT @To8510;"CONT;"
1970     !
1980     !
1990     !
2000     DISP ""
2010     PRINTER IS Crt
2020     OUTPUT 1;Clear$
2030     BEEP
2040     PRINT TABXY(10,6);"Insert the THRU standard in the REVERSE direction"
2050     DISP "Press CONTINUE to proceed"
2060     PAUSE
2070     OUTPUT 1;Clear$
2080     DISP ""
2090     PRINT TABXY(35,6);"PLEASE WAIT"
2100     !
2110     !
2120 S12_thru:  !                               Reads S12 "THRU" data from 8510
2130     OUTPUT @To8510;"S12;SING;"
2140     OUTPUT @To8510;"FORM3;OUTPRAW1;"
2150     ENTER @From8510;Preamble,Size,Newdata(*)
2160     FOR N=1 TO 201
2170         Smt_r(N,2)=Newdata(N,1)
2180         Smt_i(N,2)=Newdata(N,2)
2190     NEXT N
2200     OUTPUT @To8510;"CONT;"
2210     !
2220     !
2230 S22_thru:  !                               Reads S22 "THRU" data from 8510
2240     OUTPUT @To8510;"S22;SING;"
2250     OUTPUT @To8510;"FORM3;OUTPRAW1;"
2260     ENTER @From8510;Preamble,Size,Newdata(*)
2270     FOR N=1 TO 201
2280         Smt_r(N,4)=Newdata(N,1)
2290         Smt_i(N,4)=Newdata(N,2)
2300     NEXT N
2310     OUTPUT @To8510;"CONT;"
2320     !
2330     !
2340     PRINTER IS Crt!                           Prints "THRU" data
2350     FOR N=1 TO 201
2360         PRINT Smt_r(N,1),Smt_r(N,2),Smt_r(N,3),Smt_r(N,4)
2370     NEXT N
2380     DISP "Press CONTINUE to proceed."
2390     PAUSE
2400     OUTPUT 1;Clear$

```



```

2410 BEEP
2420 PRINT "Transfer of 'THRU' data completed"
2430 OUTPUT @To8510;"CONT;";
2440 Thru_flag=1
2450 LOCAL 7
2460 RETURN
2470 !
2480 !
2490 ! -----
2500 !
2510 Delay: ! Reads S-parameter data on the "DELAY"
2520 ! calibration standard from the HP 8510.
2530 ! (Data in real, imaginary pairs.)
2540 !
2550 DISP ""
2560 PRINTER IS Crt
2570 OUTPUT 1;Clear$
2580 BEEP
2590 PRINT TABXY(10,6);"Insert the DELAY standard in the FORWARD direction "
2600 DISP "Press CONTINUE to proceed"
2610 PAUSE
2620 OUTPUT 1;Clear$
2630 DISP ""
2640 PRINT TABXY(35,6);"PLEASE WAIT"
2650 REMOTE 716
2660 OUTPUT @To8510;"CORROFF;";
2670 !
2680 !
2690 S11_delay: ! Reads S11 "DELAY" data from 8510
2700 OUTPUT @To8510;"S11;SING;FORM3;OUTPRAW1;";
2710 ENTER @From8510;Preamble,Size,Newdata(*)
2720 FOR N=1 TO 201
2730 Smd_r(N,1)=Newdata(N,1)
2740 Smd_i(N,1)=Newdata(N,2)
2750 NEXT N
2760 !
2770 !
2780 S21_delay: ! Reads S21 "DELAY" data from 8510
2790 OUTPUT @To8510;"S21;SING;FORM3;OUTPRAW1;";
2800 ENTER @From8510;Preamble,Size,Newdata(*)
2810 FOR N=1 TO 201
2820 Smd_r(N,3)=Newdata(N,1)
2830 Smd_i(N,3)=Newdata(N,2)
2840 NEXT N
2850 !
2860 !
2870 DISP ""
2880 PRINTER IS Crt
2890 OUTPUT 1;Clear$
2900 BEEP
2910 PRINT TABXY(10,6);"Insert the DELAY standard in the REVERSE direction "
2920 DISP "Press CONTINUE to proceed"
2930 PAUSE
2940 OUTPUT 1;Clear$
2950 DISP ""

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2960 PRINT TABXY(35,6);"PLEASE WAIT"
2970 !
2980 !
2990 S12_delay: ! Reads S12 "DELAY" data from 8510
3000 OUTPUT @To8510;"S12;SING;FORM3;OUTPRAW1;"
3010 ENTER @From8510;Preamble,Size,Newdata(*)
3020 FOR N=1 TO 201
3030     Smd_r(N,2)=Newdata(N,1)
3040     Smd_i(N,2)=Newdata(N,2)
3050 NEXT N
3060 !
3070 !
3080 S22_delay: ! Reads S22 "DELAY" data from 8510
3090 OUTPUT @To8510;"S22;SING;FORM3;OUTPRAW1;"
3100 ENTER @From8510;Preamble,Size,Newdata(*)
3110 FOR N=1 TO 201
3120     Smd_r(N,4)=Newdata(N,1)
3130     Smd_i(N,4)=Newdata(N,2)
3140 NEXT N
3150 !
3160 !
3170 PRINTER IS Crt! Prints "DELAY" data
3180 FOR N=1 TO 201
3190     PRINT Smd_r(N,1),Smd_r(N,2),Smd_r(N,3),Smd_r(N,4)
3200 NEXT N
3210 DISP "Press CONTINUE to proceed."
3220 PAUSE
3230 OUTPUT 1;Clear$
3240 BEEP
3250 PRINT "Transfer of 'DELAY' data completed"
3260 OUTPUT @To8510;"CONT;"
3270 Delay_flag=1
3280 LOCAL 7
3290 RETURN
3300 !
3310 !
3320 !-----
3330 !
3340 Short: ! Reads S-parameter data on the "SHORT"
3350 ! calibration standard from the HP 8510.
3360 ! (Data in real, imaginary pairs.)
3370 !
3380 DISP ""
3390 PRINTER IS Crt
3400 OUTPUT 1;Clear$
3410 BEEP
3420 PRINT TABXY(20,6);"Insert the SHORT at port 1 in FORWARD direction"
3430 DISP "Press CONTINUE to proceed"
3440 PAUSE
3450 OUTPUT 1;Clear$
3460 DISP ""
3470 PRINT TABXY(35,6);"PLEASE WAIT"
3480 REMOTE 716
3490 OUTPUT @To8510;"CORROFF;"
3500 !
3510 S11_short: ! Reads S11 "SHORT" data from 8510

```

```

3520 OUTPUT @To8510;"S11;SING;FORM3;OUTPRAW1;"
3530 ENTER @From8510;Preamble,Size,Newdata(*)
3540 FOR N=1 TO 201
3550     Sms_r(N,1)=Newdata(N,1)
3560     Sms_i(N,1)=Newdata(N,2)
3570 NEXT N
3580 !
3590 PRINTER IS Crt
3600 OUTPUT 1;Clear$
3610 BEEP
3620 PRINT TABXY(20,6);"Insert the SHORT at Port 2 in REVERSE direction"
3630 DISP "Press CONTINUE to proceed"
3640 PAUSE
3650 OUTPUT 1;Clear$
3660 DISP
3670 PRINT TABXY(35,6);"PLEASE WAIT"
3680 !
3690 S22_short: ! Reads S22 "SHORT" data from 8510
3700 OUTPUT @To8510;"S22;SING;FORM3;OUTPRAW1;"
3710 ENTER @From8510;Preamble,Size,Newdata(*)
3720 FOR N=1 TO 201
3730     Sms_r(N,2)=Newdata(N,1)
3740     Sms_i(N,2)=Newdata(N,2)
3750 NEXT N
3760 !
3770 !
3780 PRINTER IS Crt! Prints "SHORT" data
3790 FOR N=1 TO 201
3800     PRINT Sms_r(N,1),Sms_r(N,2)
3810 NEXT N
3820 DISP "Press CONTINUE to proceed."
3830 PAUSE
3840 OUTPUT 1;Clear$
3850 BEEP
3860 PRINT "Transfer of 'SHORT' data completed"
3870 OUTPUT @To8510;"CONT;"
3880 Short_flag=1
3890 LOCAL 7
3900 RETURN
3910 !
3920 !
3930 !
3940 Dut_meas: ! Reads S-parameter data on the "DUT"
3950 ! from the HP 8510.
3960 ! (Data in real, imaginary data pairs.)
3970 !
3980 DISP ""
3990 PRINTER IS Crt
4000 OUTPUT 1;Clear$
4010 BEEP
4020 PRINT TABXY(10,6);"Insert Device Under Test in FORWARD direction "
4030 DISP "Press CONTINUE to proceed"
4040 PAUSE
4050 OUTPUT 1;Clear$
4060 DISP ""
4070 PRINT TABXY(35,6);"PLEASE WAIT"

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4080     REMOTE 716
4090     OUTPUT @To8510;"CORROFF;"
4100     !
4110     !
4120 S11_meas: !                               Reads S11 "DUT" data from 8510
4130     OUTPUT @To8510;"S11;SING;"
4140     OUTPUT @To8510;"FORM3;OUTPRAW1;"
4150     ENTER @From8510;Preamble,Size,Newdata(*)
4160     FOR N=1 TO 201
4170         Smeas_r(N,1)=Newdata(N,1)
4180         Smeas_i(N,1)=Newdata(N,2)
4190     NEXT N
4200     OUTPUT @To8510;"CONT;"
4210     !
4220     !
4230 S21_meas: !                               Reads S21 "DUT" data from 8510
4240     OUTPUT @To8510;"S21;SING;"
4250     OUTPUT @To8510;"FORM3;OUTPRAW1;"
4260     ENTER @From8510;Preamble,Size,Newdata(*)
4270     FOR N=1 TO 201
4280         Smeas_r(N,3)=Newdata(N,1)
4290         Smeas_i(N,3)=Newdata(N,2)
4300     NEXT N
4310     OUTPUT @To8510;"CONT;"
4320     !
4330     !
4340     DISP ""
4350     PRINTER IS Crt
4360     OUTPUT 1;Clear$
4370     BEEP
4380     PRINT TABXY(10,6);"Insert Device Under Test in REVERSE direction "
4390     DISP "Press CONTINUE to proceed"
4400     PAUSE
4410     OUTPUT 1;Clear$
4420     DISP ""
4430     PRINT TABXY(35,6);"PLEASE WAIT"
4440     !
4450     !
4460 S12_meas: !                               Reads S12 "DUT" data from 8510
4470     OUTPUT @To8510;"S12;SING;"
4480     OUTPUT @To8510;"FORM3;OUTPRAW1;"
4490     ENTER @From8510;Preamble,Size,Newdata(*)
4500     FOR N=1 TO 201
4510         Smeas_r(N,2)=Newdata(N,1)
4520         Smeas_i(N,2)=Newdata(N,2)
4530     NEXT N
4540     OUTPUT @To8510;"CONT;"
4550     !
4560     !
4570 S22_meas: !                               Reads S22 "DUT" data from 8510
4580     OUTPUT @To8510;"S22;SING;"
4590     OUTPUT @To8510;"FORM3;OUTPRAW1;"
4600     ENTER @From8510;Preamble,Size,Newdata(*)
4610     FOR N=1 TO 201
4620         Smeas_r(N,4)=Newdata(N,1)

```

```

4630         Smeas_i(N,4)=Newdata(N,2)
4640     NEXT N
4650     OUTPUT @To8510;"CONT;"
4660     !
4670     !
4680     PRINTER IS Crt!                               Prints "DUT" data
4690     FOR N=1 TO 201
4700         PRINT Smeas_r(N,1),Smeas_r(N,2),Smeas_r(N,3),Smeas_r(N,4)
4710     NEXT N
4720     DISP "Press CONTINUE to proceed."
4730     PAUSE
4740     OUTPUT 1;Clear$
4750     BEEP
4760     PRINT "Transfer of 'DUT' data completed"
4770     OUTPUT @To8510;"CONT;"
4780     Dut_flag=1
4790     LOCAL 7
4800     RETURN
4810     !
4820     !
4830     !-----
4840     !
4850 Calculate:      !                               Performs all TSD mathematics, including
4860                 !                               matrix manipulations and calculation
4870                 !                               of error coefficients.
4880     DISP ""
4890     OUTPUT 1;Clear$
4900     !                               Ensures acquisition of all
4910     !                               calibration standard data.
4920     IF (Thru_flag=0) THEN No_thru !           "
4930     IF (Delay_flag=0) THEN No_delay !         "
4940     IF (Short_flag=0) THEN No_short !         "
4950     IF (Dut_flag=0) THEN No_dut !            "
4960     GOTO Stds_done !                          "
4970 No_thru:      !                               "
4980     PRINT "You forgot to measure THRU standard"! "
4990     BEEP 150,.35 !                             "
5000     RETURN !                                   "
5010 No_delay:   !                               "
5020     PRINT "You forgot to measure DELAY standard"! "
5030     BEEP 150,.35 !                             "
5040     RETURN !                                   "
5050 No_short:   !                               "
5060     PRINT "You forgot to measure SHORT standard"! "
5070     BEEP 150,.35 !                             "
5080     RETURN !                                   "
5090 No_dut:     !                               "
5100     PRINT "You forgot to measure the DUT"!   "
5110     BEEP 150,.35 !                             "
5120     RETURN !                                   "
5130 Stds_done: !                               "
5140     !
5150     !
5160     !                               Ldelay is the physical length (in mils)
5170     !                               of the delay line calibration standard

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5180      !
5190      DISP ""
5200      Ldelay=27.85      !           <----- change this as required
5210      !
5220      Enter_delay: !
5230      !           L_dut is the length (in mils) of the DUT
5240      !
5250      INPUT "Enter length of device under test in mils",L_dut
5260      IF (L_dut<0) THEN Enter_delay
5270      !
5280      !
5290      FOR F=1 TO 201
5300      DISP "CALCULATING ERROR COEFFICIENT";F      !           -v-
5310      S1=Smd_r(F,1)      !           "
5320      S2=Smd_i(F,1)      !           "
5330      S3=Smd_r(F,2)      !           ! Puts acquired S-parameter
5340      S4=Smd_i(F,2)      !           ! data into real and imaginary
5350      S5=Smd_r(F,3)      !           ! matrix pairs
5360      S6=Smd_i(F,3)      !           "
5370      S7=Smd_r(F,4)      !           "
5380      S8=Smd_i(F,4)      !           "
5390      S9=Smt_r(F,1)      !           "
5400      S10=Smt_i(F,1)     !           "
5410      S11=Smt_r(F,2)     !           "
5420      S12=Smt_i(F,2)     !           "
5430      S13=Smt_r(F,3)     !           "
5440      S14=Smt_i(F,3)     !           "
5450      S15=Smt_r(F,4)     !           "
5460      S16=Smt_i(F,4)     !           "
5470      CALL Tconv(S1,S2,S3,S4,S5,S6,S7,S8,Tmdr(1,1),Tmdi(1,1),Tmdr(1,2),Tm
di(1,2),Tmdr(2,1),Tmdi(2,1),Tmdr(2,2),Tmdi(2,2))
5480      CALL Tconv(S9,S10,S11,S12,S13,S14,S15,S16,Tmtr(1,1),Tmti(1,1),Tmtr(
1,2),Tmti(1,2),Tmtr(2,1),Tmti(2,1),Tmtr(2,2),Tmti(2,2))
5490      Ele11_r=Tmtr(1,1)      !           -v-
5500      Ele11_i=Tmti(1,1)     !           "
5510      Ele12_r=Tmtr(1,2)     !           ! Generates "THRU" T-matrix
5520      Ele12_i=Tmti(1,2)     !           "
5530      Ele21_r=Tmtr(2,1)     !           "
5540      Ele21_i=Tmti(2,1)     !           "
5550      Ele22_r=Tmtr(2,2)     !           "
5560      Ele22_i=Tmti(2,2)     !           "
5570      CALL Cmult(Ele11_r,Ele11_i,Ele22_r,Ele22_i,X3,Y3)
5580      Det1r=X3
5590      Det1i=Y3
5600      CALL Cmult(Ele21_r,Ele21_i,Ele12_r,Ele12_i,X3,Y3)
5610      Det2r=X3
5620      Det2i=Y3
5630      Detr=Det1r-Det2r
5640      Deti=Det1i-Det2i
5650      Ele12_r=-Ele12_r      !           ! Used in calculating inverse
5660      Ele12_i=-Ele12_i      !           ! T-matrix of THRU standard
5670      Ele21_r=-Ele21_r      !           "
5680      Ele21_i=-Ele21_i      !           "
5690      Tempr=Ele11_r        !           "
5700      Tempi=Ele11_i        !           "

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5710 Ele11_r=Ele22_r ! "
5720 Ele11_i=Ele22_i ! "
5730 Ele22_r=TempR ! "
5740 Ele22_i=TempI ! "
5750 CALL Cdiv(Ele11_r, Ele11_i, Detr, Deti, X3, Y3) ! "
5760 Tmtr_inv(1,1)=X3 ! "
5770 Tmti_inv(1,1)=Y3 ! "
5780 CALL Cdiv(Ele12_r, Ele12_i, Detr, Deti, X3, Y3) ! "
5790 Tmtr_inv(1,2)=X3 ! "
5800 Tmti_inv(1,2)=Y3 ! "
5810 CALL Cdiv(Ele21_r, Ele21_i, Detr, Deti, X3, Y3) ! "
5820 Tmtr_inv(2,1)=X3 ! "
5830 Tmti_inv(2,1)=Y3 ! "
5840 CALL Cdiv(Ele22_r, Ele22_i, Detr, Deti, X3, Y3) ! "
5850 Tmtr_inv(2,2)=X3 ! "
5860 Tmti_inv(2,2)=Y3 ! "
5870 MAT Mr1= Tmtr* Tmtr_inv
5880 MAT Mi1= Tmtr* Tmti_inv
5890 MAT Mi2= Tmdi* Tmtr_inv
5900 MAT Mr2= Tmdi* Tmti_inv
5910 Mr(1,1)=Mr1(1,1)-Mr2(1,1) ! "M" coefficients
5920 Mi(1,1)=Mi1(1,1)+Mi2(1,1) ! "
5930 Mr(1,2)=Mr1(1,2)-Mr2(1,2) ! "
5940 Mi(1,2)=Mi1(1,2)+Mi2(1,2) ! "
5950 Mr(2,1)=Mr1(2,1)-Mr2(2,1) ! "
5960 Mi(2,1)=Mi1(2,1)+Mi2(2,1) ! "
5970 Mr(2,2)=Mr1(2,2)-Mr2(2,2) ! "
5980 Mi(2,2)=Mi1(2,2)+Mi2(2,2) ! "
5990 MAT Nr1= Tmtr_inv* Tmtr
6000 MAT Ni1= Tmtr_inv* Tmdi
6010 MAT Ni2= Tmti_inv* Tmtr
6020 MAT Nr2= Tmti_inv* Tmdi
6030 Nr(1,1)=Nr1(1,1)-Nr2(1,1) ! "N" coefficients
6040 Ni(1,1)=Ni1(1,1)+Ni2(1,1) ! "
6050 Nr(1,2)=Nr1(1,2)-Nr2(1,2) ! "
6060 Ni(1,2)=Ni1(1,2)+Ni2(1,2) ! "
6070 Nr(2,1)=Nr1(2,1)-Nr2(2,1) ! "
6080 Ni(2,1)=Ni1(2,1)+Ni2(2,1) ! "
6090 Nr(2,2)=Nr1(2,2)-Nr2(2,2) ! "
6100 Ni(2,2)=Ni1(2,2)+Ni2(2,2) ! "
6110 Br=Mr(2,2)-Mr(1,1)
6120 Bi=Mi(2,2)-Mi(1,1)
6130 CALL Quad(Mr(2,1), Mi(2,1), Br, Bi, -Mr(1,2), -Mi(1,2), Rrp, Rip, Rrm, Rim)
6140 CALL Rtop(Rrp, Rip, Mag, Phase)
6150 Rmp=Mag ! 'plus' root of quadratic
6160 Rpp=Phase ! "
6170 CALL Rtop(Rrm, Rim, Mag, Phase)
6180 Rmm=Mag ! 'minus' root of quadratic
6190 Rpm=Phase ! "
6200 IF (Rmp>Rmm) THEN
6210 Ar_m=Rrp ! TL11/TL21 REAL
6220 Ai_m=Rip ! TL11/TL21 IMAG
6230 Br_m=Rrm ! TL12/TL22 REAL
6240 Bi_m=Rim ! TL12/TL22 IMAG
6250 ELSE !
6260 Ar_m=Rrm ! Selects larger magnitude root
for a, smaller for b

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6270      Ai_m=Rim
6280      Br_m=Rrp
6290      Bi_m=Rip
6300      END IF
6310      Br=Nr(2,2)-Nr(1,1)
6320      Bi=Ni(2,2)-Ni(1,1)
6330      CALL Quad(Nr(1,2),Ni(1,2),Br,Bi,-Nr(2,1),-Ni(2,1),Rrp,Rip,Rrm,Rim)
6340      CALL Rtop(Rrp,Rip,Mag,Phase)
6350      Rmp=Mag
6360      Rpp=Phase
6370      CALL Rtop(Rrm,Rim,Mag,Phase)
6380      Rmm=Mag
6390      Rpm=Phase
6400      IF (Rmp>Rmm) THEN
6410          Cr_n=Rrp ! TR11/TR12 REAL
6420          Ci_n=Rip ! TR11/TR12 IMAG
6430          Dr_n=Rrm ! TR21/TR22 REAL
6440          Di_n=Rim ! TR21/TR22 IMAG
6450      ELSE !
6460          Cr_n=Rrm !
6470          Ci_n=Rim
6480          Dr_n=Rrp
6490          Di_n=Rip
6500      END IF
6510      Tnr=Br_m-Sms_r(F,1) ! Used in calculation of e11
6520      Tni=Bi_m-Sms_i(F,1) !
6530      Tdr=Ar_m-Sms_r(F,1) !
6540      Tdi=Ai_m-Sms_i(F,1) !
6550      CALL Cdiv(Tnr,Tni,Tdr,Tdi,X3,Y3) !
6560      Tr=X3 !
6570      Ti=Y3 !
6580      Unr=Cr_n+Sms_r(F,2) !
6590      Uni=Ci_n+Sms_i(F,2) !
6600      Udr=Dr_n+Sms_r(F,2) !
6610      Udi=Di_n+Sms_i(F,2) !
6620      CALL Cdiv(Unr,Uni,Udr,Udi,X3,Y3) !
6630      Ur=X3 !
6640      Ui=Y3 !
6650      Vnr=Br_m-Smt_r(F,1) !
6660      Vni=Bi_m-Smt_i(F,1) !
6670      Vdr=Ar_m-Smt_r(F,1) !
6680      Vdi=Ai_m-Smt_i(F,1) !
6690      CALL Cdiv(Vnr,Vni,Vdr,Vdi,X3,Y3) !
6700      Vr=X3 !
6710      Vi=Y3 !
6720      CALL Cmult(Tr,Ti,Ur,Ui,X3,Y3) !
6730      Wr=X3 !
6740      Wi=Y3 !
6750      CALL Cmult(Wr,Wi,Vr,Vi,X3,Y3) !
6760      Zr=X3 !
6770      Zi=Y3 !
6780      CALL Rtop(Zr,Zi,Mag,Phase) !
6790      Zm=Mag !
6800      Zp=Phase !
6810      S22a_m=SQR(Zm)
6820      S22a_p=Zp/2

```

Selects larger magnitude root
for c, smaller for d.


```

6830      CALL Ptor(S22a_m,S22a_p,X,Y)
6840      S22a_r=X
6850      S22a_i=Y
6860      CALL Cdiv(Tr,Ti,S22a_r,S22a_i,X3,Y3)
6870      Gam_r=X3
6880      Gam_i=Y3
6890      CALL Rtop(Gam_r,Gam_i,Mag,Phase)
6900      !
6910      !           Selects proper root for e11
6920      IF (ABS(Phase)<90) AND (ABS(Phase)>270) THEN Gamma_skip !OPEN
6930      IF (ABS(Phase)>90) AND (ABS(Phase)<270) THEN Gamma_skip !SHORT
6940      S22a_r=-S22a_r
6950      S22a_i=-S22a_i
6960      Gamma_skip:      !           Uses a,b,c,d and e11 to compute
6970      !           !           remaining error coefficients.
6980      CALL Cdiv(Vr,Vi,S22a_r,S22a_i,X3,Y3)
6990      S11b_r=X3
7000      S11b_i=Y3
7010      B_ar=Br_m-Ar_m
7020      B_ai=Bi_m-Ai_m
7030      CALL Cmult(B_ar,B_ai,S22a_r,S22a_i,X3,Y3)
7040      E10_e01r(F)=X3 !S21aS12a real
7050      E10_e01i(F)=Y3 !S21aS12a imag
7060      C_dr=Cr_n-Dr_n
7070      C_di=Ci_n-Di_n
7080      CALL Cmult(C_dr,C_di,S11b_r,S11b_i,X3,Y3)
7090      E23_e32r(F)=X3 !S12bS21o real
7100      E23_e32i(F)=Y3 !S12bS21b imag
7110      CALL Cmult(S22a_r,S22a_i,S11b_r,S11b_i,X3,Y3)
7120      E11_e22r=X3
7130      E11_e22i=Y3
7140      Var=1-X3
7150      CALL Cmult(Smt_r(F,3),Smt_i(F,3),Var,-E11_e22i,X3,Y3)
7160      E10_e32r(F)=X3 ! S21aS21b real
7170      E10_e32i(F)=Y3 ! S21aS21b imag
7180      CALL Cmult(Smt_r(F,2),Smt_i(F,2),Var,-E11_e22i,X3,Y3)
7190      E23_e01r(F)=X3 ! S12bS12a real
7200      E23_e01i(F)=Y3 ! S12bS12a imag
7210      E00r(F)=Br_m ! S11a real
7220      E00i(F)=Bi_m ! S11a imag
7230      E33r(F)=-Dr_n ! S22b real
7240      E33i(F)=-Di_n ! S22b imag
7250      E11r(F)=S22a_r
7260      E11i(F)=S22a_i
7270      E22r(F)=S11b_r
7280      E22i(F)=S11b_i
7290      !
7300      !
7310      !           ! Determines complex propagation coefficient gamma
7320      !           !
7330      !           ! NOW SHIFT REFERENCE PLANE TO ACTUAL CHIP BOUNDARY
7340      CALL Cmult(Mr(2,1),Mi(2,1),Br_m,Bi_m,X3,Y3)
7350      Gr=X3+Mr(2,2)
7360      Gi=Y3+Mi(2,2)
7370      CALL Rtop(Gr,Gi,Mag,Phase)
7380      Gam_lm=LOG(Mag)

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```
7380 Gam_lp=Phase*PI/180
7390 Alpha=Gam_lm/Ldelay
7400 Beta=Gam_lp/Ldelay
7410 RAD
7420 Er_ref=EXP(-Alpha*L_dut)*COS(-Beta*L_dut)
7430 Ei_ref=EXP(-Alpha*L_dut)*SIN(-Beta*L_dut)
7440 DEG
7450 !
7460 ! Multiplies error coefficients by shifting terms
7470 !
7480 CALL Cmult(Br_m,Bi_m,Er_ref,Ei_ref,X3,Y3)
7490 E00r(F)=X3
7500 E00i(F)=Y3
7510 CALL Cmult(S22a_r,S22a_i,Er_ref,Ei_ref,X3,Y3)
7520 E11r(F)=X3
7530 E11i(F)=Y3
7540 CALL Cmult(S11b_r,S11b_i,Er_ref,Ei_ref,X3,Y3)
7550 E22r(F)=X3
7560 E22i(F)=Y3
7570 CALL Cmult(-Dr_n,-Di_n,Er_ref,Ei_ref,X3,Y3)
7580 E33r(F)=X3
7590 E33i(F)=Y3
7600 E10_e01rt=E10_e01r(F)
7610 E10_e01it=E10_e01i(F)
7620 CALL Cmult(E10_e01rt,E10_e01it,Er_ref,Ei_ref,X3,Y3)
7630 E10_e01r(F)=X3
7640 E10_e01i(F)=Y3
7650 E10_e32rt=E10_e32r(F)
7660 E10_e32it=E10_e32i(F)
7670 CALL Cmult(E10_e32rt,E10_e32it,Er_ref,Ei_ref,X3,Y3)
7680 E10_e32r(F)=X3
7690 E10_e32i(F)=Y3
7700 E23_e32rt=E23_e32r(F)
7710 E23_e32it=E23_e32i(F)
7720 CALL Cmult(E23_e32rt,E23_e32it,Er_ref,Ei_ref,X3,Y3)
7730 E23_e32r(F)=X3
7740 E23_e32i(F)=Y3
7750 E23_e01rt=E23_e01r(F)
7760 E23_e01it=E23_e01i(F)
7770 CALL Cmult(E23_e01rt,E23_e01it,Er_ref,Ei_ref,X3,Y3)
7780 E23_e01r(F)=X3
7790 E23_e01i(F)=Y3
7800 Extraction: !
7810 S12m_rt=Smeas_r(F,2)
7820 S12m_it=Smeas_i(F,2)
7830 E23_e01rt=E23_e01r(F)
7840 E23_e01it=E23_e01i(F)
7850 CALL Cdiv(S12m_rt,S12m_it,E23_e01rt,E23_e01it,X3,Y3)
7860 Ar=X3
7870 Ai=Y3
7880 S21m_rt=Smeas_r(F,3)
7890 S21m_it=Smeas_i(F,3)
7900 E10_e32rt=E10_e32r(F)
7910 E10_e32it=E10_e32i(F)
7920 CALL Cdiv(S21m_rt,S21m_it,E10_e32rt,E10_e32it,X3,Y3)
7930 Br=X3
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7940 Bi=Y3
7950 Cnum_r=Smeas_r(F,1)-E00r(F)
7960 Cnum_i=Smeas_i(F,1)-E00i(F)
7970 E10_e01rt=E10_e01r(F)
7980 E10_e01it=E10_e01i(F)
7990 CALL Cdiv(Cnum_r,Cnum_i,E10_e01rt,E10_e01it,X3,Y3)
8000 Cr=X3
8010 Ci=Y3
8020 Dnum_r=Smeas_r(F,4)-E33r(F)
8030 Dnum_i=Smeas_i(F,4)-E33i(F)
8040 E23_e32rt=E23_e32r(F)
8050 E23_e32it=E23_e32i(F)
8060 CALL Cdiv(Dnum_r,Dnum_i,E23_e32rt,E23_e32it,X3,Y3)
8070 Dr=X3
8080 Di=Y3
8090 E11rt=E11r(F)
8100 E11it=E11i(F)
8110 CALL Cmult(E11rt,E11it,Cr,Ci,X3,Y3)
8120 E1_r=1+X3
8130 E1_i=Y3
8140 E22rt=E22r(F)
8150 E22it=E22i(F)
8160 CALL Cmult(E22rt,E22it,Dr,Di,X3,Y3)
8170 Er_r=1+X3
8180 Er_i=Y3
8190 CALL Cmult(E1_r,E1_i,Er_r,Er_i,X3,Y3)
8200 E1_r=X3
8210 E1_i=Y3
8220 CALL Cmult(E11rt,E11it,E22rt,E22it,X3,Y3)
8230 E11_e22r=X3
8240 E11_e22i=Y3
8250 CALL Cmult(E11_e22r,E11_e22i,Ar,Ai,X3,Y3)
8260 E2_r=X3
8270 E2_i=Y3
8280 CALL Cmult(E2_r,E2_i,Br,Bi,X3,Y3)
8290 E3_r=X3
8300 E3_i=Y3
8310 Er=E1_r-E3_r
8320 Ei=E1_i-E3_i
8330 CALL Cmult(Cr,Ci,Dr,Di,X3,Y3)
8340 Cdr=X3
8350 Cdi=Y3
8360 CALL Cmult(Ar,Ai,Br,Bi,X3,Y3)
8370 Abr=X3
8380 Abi=Y3
8390 Cd_abr=Cdr-Abr
8400 Cd_abi=Cdi-Abi
8410 CALL Cmult(E22rt,E22it,Cd_abr,Cd_abi,X3,Y3)
8420 S11num_r=Cr+X3
8430 S11num_i=Ci+Y3
8440 CALL Cdiv(S11num_r,S11num_i,Er,Ei,X3,Y3)
8450 Sdut_r(F,1)=X3 !S11_r
8460 Sdut_i(F,1)=Y3 !S11_i
8470 CALL Cdiv(Br,Bi,Er,Ei,X3,Y3)
8480 Sdut_r(F,3)=X3 !S21_r

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8490      Sdut_i(F,3)=Y3 !S21 i
8500      CALL Cdiv(Ar,Ai,Er,Ei,X3,Y3)
8510      Sdut_r(F,2)=X3 !S12 r
8520      Sdut_i(F,2)=Y3 !S12 i
8530      CALL Cmult(E11rt,E11it,Cd_abr,Cd_abi,X3,Y3)
8540      S22num_r=Dr+X3
8550      S22num_i=Dj+Y3
8560      CALL Cdiv(S22num_r,S22num_i,Er,Ei,X3,Y3)
8570      Sdut_r(F,4)=X3 !S22 r
8580      Sdut_i(F,4)=Y3 !S22 i
8590      NEXT F
8600      DISP " "
8610      PRINTER IS Crt
8620      OUTPUT 1;Clear$
8630      PRINT "Calculation of error coefficients completed"
8640      Calc_flag=1
8650      BEEP
8660      RETURN
8670      !
8680      !
8690      !
8700      !
8710      !-----
8720      !
8730 Send: !                               Transfers fake error coefficient
8740      !                               sets to 8510 memory
8750      DISP ""
8760      BEEP
8770      OUTPUT 1;Clear$
8780      DISP ""
8790      ! IF (Calc_flag=1) THEN Go
8800      !     BEEP
8810      !     PRINTER IS Crt
8820      !     PRINT "You must calculate error coefficients before transfer"
8830      !     RETURN
8840 Go:   !
8850      PRINTER IS Crt
8860      PRINT TABXY(15,6);"The TSD calibration will be stored in CAL SET 1"
8870      PRINT TABXY(10,8);"Transfer the contents of this cal set or loss of d
ata will result"
8880      DISP "Press CONTINUE to send TSD calibration data"
8890      BEEP
8900      LOCAL 7
8910      PAUSE
8920      DISP ""
8930      REMOTE 716
8940      OUTPUT @To8510;"DEL;CAL51;"
8950      OUTPUT 1;Clear$
8960      DISP "SENDING DATA"
8970      BEEP
8980      OUTPUT 1;Clear$
8990      DISP ""
9000      PRINTER IS Crt
9010      OUTPUT 1;Clear$
9020      !

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```
9030      !
9040      FOR N=1 TO 201
9050          Data(N,1)=0
9060          Data(N,2)=0
9070      NEXT N
9080      OUTPUT @To8510;"DISPDATA"
9090      OUTPUT @To8510;"CORROFF;CAL1;CALIFUL2;FORM3;INPUCALC01;"
9100      OUTPUT @Datatoana;Preamble;Size;Data(*)
9110      PRINT "COEFFICIENT 01 DATA SENT"
9120      !
9130      FOR N=1 TO 201
9140          Data(N,1)=0
9150          Data(N,2)=0
9160      NEXT N
9170      OUTPUT @To8510;"INPUCALC02:"
9180      OUTPUT @Datatoana;Preamble;Size;Data(*)
9190      PRINT "COEFFICIENT 02 DATA SENT"
9200      !
9210      FOR N=1 TO 201
9220          Data(N,1)=1
9230          Data(N,2)=0
9240      NEXT N
9250      OUTPUT @To8510;"INPUCALC03:"
9260      OUTPUT @Datatoana;Preamble;Size;Data(*)
9270      PRINT "COEFFICIENT 03 DATA SENT"
9280      !
9290      FOR N=1 TO 201
9300          Data(N,1)=0
9310          Data(N,2)=0
9320      NEXT N
9330      IF Isol_flg=0 THEN Omit_isol_1
9340      FOR N=1 TO 201
9350          Data(N,1)=Smi_r(N,2)
9360          Data(N,2)=Smi_i(N,2)
9370      NEXT N
9380      Omit_isol_1:      !
9390      OUTPUT @To8510;"INPUCALC04:"
9400      OUTPUT @Datatoana;Preamble;Size;Data(*)
9410      PRINT "COEFFICIENT 04 DATA SENT"
9420      !
9430      FOR N=1 TO 201
9440          Data(N,1)=0
9450          Data(N,2)=0
9460      NEXT N
9470      OUTPUT @To8510;"INPUCALC05:"
9480      OUTPUT @Datatoana;Preamble;Size;Data(*)
9490      PRINT "COEFFICIENT 05 DATA SENT"
9500      !
9510      FOR N=1 TO 201
9520          Data(N,1)=1
9530          Data(N,2)=0
9540      NEXT N
9550      OUTPUT @To8510;"INPUCALC06:"
9560      OUTPUT @Datatoana;Preamble;Size;Data(*)
9570      PRINT "COEFFICIENT 06 DATA SENT"
```

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```
9580      !
9590      FOR N=1 TO 201
9600          Data(N,1)=0
9610          Data(N,2)=0
9620      NEXT N
9630      OUTPUT @To8510;"INPUCALC07;"
9640      OUTPUT @Datatoana;Preamble;Size;Data(*)
9650      PRINT "COEFFICIENT 07 DATA SENT"
9660      !
9670      FOR N=1 TO 201
9680          Data(N,1)=0
9690          Data(N,2)=0
9700      NEXT N
9710      OUTPUT @To8510;"INPUCALC08;"
9720      OUTPUT @Datatoana;Preamble;Size;Data(*)
9730      PRINT "COEFFICIENT 08 DATA SENT"
9740      !
9750      FOR N=1 TO 201
9760          Data(N,1)=1
9770          Data(N,2)=0
9780      NEXT N
9790      OUTPUT @To8510;"INPUCALC09;"
9800      OUTPUT @Datatoana;Preamble;Size;Data(*)
9810      PRINT "COEFFICIENT 09 DATA SENT"
9820      !
9830      FOR N=1 TO 201
9840          Data(N,1)=0
9850          Data(N,2)=0
9860      NEXT N
9870      IF Isol_flag=0 THEN Omit_isol_2
9880      FOR N=1 TO 201
9890          Data(N,1)=Smi_r(N,1)
9900          Data(N,2)=Smi_i(N,1)
9910      NEXT N
9920 Omit_isol_2:      !
9930      OUTPUT @To8510;"INPUCALC10;"
9940      OUTPUT @Datatoana;Preamble;Size;Data(*)
9950      PRINT "COEFFICIENT 10 DATA SENT"
9960      !
9970      FOR N=1 TO 201
9980          Data(N,1)=0
9990          Data(N,2)=0
10000     NEXT N
10010     OUTPUT @To8510;"INPUCALC11;"
10020     OUTPUT @Datatoana;Preamble;Size;Data(*)
10030     PRINT "COEFFICIENT 11 DATA SENT"
10040     !
10050     FOR N=1 TO 201
10060         Data(N,1)=1
10070         Data(N,2)=0
10080     NEXT N
10090     OUTPUT @To8510;"INPUCALC12;"
10100     OUTPUT @Datatoana;Preamble;Size;Data(*)
10110     PRINT "COEFFICIENT 12 DATA SENT"
10120     !
10130     !
```

```

10140 OUTPUT @To8510;"SAVC;CAL51;CONT;CORRON;CAL51;"
10150 OUTPUT @To8510;"DISPDATA;"
10160 OUTPUT @To8510;"MENUPRIO;"
10170 LOCAL 7
10180 DISP ""
10190 PRINT "DATA TRANSFER COMPLETED"
10200 FOR N=1 TO 201
10210 PRINT USING "SD.DDDD";E00r(N);E11r(N);E10_e01r(N);E22r(N);E10_e32r(N)
;E33r(N);E23_e32r(N);E23_e01r(N)
10220 NEXT N
10230 Model_flag=1
10240 BEEP
10250 DISP "ERROR COEFFICIENTS TRANSFERED"
10260 WAIT 3
10270 DISP ""
10280 RETURN
10290 !
10300 !
10310 !
10320 Send_actual: !
10330 BEEP
10340 OUTPUT 1;Clear$
10350 DISP ""
10360 PRINTER IS Crt
10370 IF (Calc_flag=1) THEN Mod_flag
10380 PRINT "You must calculate error coefficients before transfer"
10390 RETURN
10400 Mod_flag: !
10410 IF (Model_flag=1) THEN Go_to_it
10420 PRINT "You must send error model before OUT data"
10430 RETURN
10440 Go_to_it: !
10450 REMOTE 716
10460 OUTPUT @To8510;"CORRON;CAL51;"
10470 FOR N=1 TO 201
10480 Data(N,1)=Scut_r(N,1)
10490 Data(N,2)=Scut_i(N,1)
10500 NEXT N
10510 OUTPUT @To8510;"HOLD;FORM3;INPURAW1;"
10520 OUTPUT @Datatoana;Preamble,Size,Data(*)
10530 PRINT "S11 Sent"
10540 !
10550 FOR N=1 TO 201
10560 Data(N,1)=Scut_r(N,3)
10570 Data(N,2)=Scut_i(N,3)
10580 NEXT N
10590 ! OUTPUT @To8510;"HOLD;FORM3;INPURAW2;"
10600 OUTPUT @To8510;"INPURAW2;"
10610 OUTPUT @Datatoana;Preamble,Size,Data(*)
10620 PRINT "S21 Sent"
10630 !
10640 FOR N=1 TO 201
10650 Data(N,1)=Scut_r(N,2)
10660 Data(N,2)=Scut_i(N,2)
10670 NEXT N
10680 ! OUTPUT @To8510;"HOLD;FORM3;INPURAW3;"

```

```

10690 OUTPUT @To8510;"INPURAW3;"
10700 OUTPUT @Datatoana;Preamble,Size,Data(*)
10710 PRINT "S12 Sent"
10720 !
10730 FOR N=1 TO 201
10740     Data(N,1)=Sdut_r(N,4)
10750     Data(N,2)=Sdut_i(N,4)
10760 NEXT N
10770 ! OUTPUT @To8510;"HOLD;FORM3;INPURAW4;"
10780 OUTPUT @To8510;"INPURAW4;"
10790 OUTPUT @Datatoana;Preamble,Size,Data(*)
10800 PRINT "S22 Sent"
10810 ! OUTPUT @To8510;"CONT;"
10820 LOCAL 7
10830 ! PRINTER IS 701
10840 ! FOR N=1 TO 201
10850 !     PRINT N;Sdut_r(N,1);Sdut_r(N,2);Sdut_r(N,3);Sdut_r(N,4)
10860 !     PRINT N;Sdut_i(N,1);Sdut_i(N,2);Sdut_i(N,3);Sdut_i(N,4)
10870 ! NEXT N
10880 PRINTER IS 1
10890 RETURN
10900 !
10910 Exit: !
10920 DISP ""
10930 OUTPUT 1;Clear$
10940 DISP ""
10950 PRINTER IS Crt
10960 PRINT TABXY(15,6);"The program has ended. Press run to restart"
10970 END
10980 !
10990 !
11000 !*****SUBPROGRAMS*****
11010 !
11020 ! Returns the roots of a quadratic equation
11030 !
11040 SUB Quad(Ar,Ai,Br,Bi,Cr,Ci,Rrp,Rip,Rrm,Rim)
11050     CALL Cmult(Br,Bi,Br,Bi,X3,Y3)
11060     Bsqr=X3
11070     Bsqi=Y3
11080     CALL Cmult(Ar,Ai,Cr,Ci,X3,Y3)
11090     Ac4r=4*X3
11100     Ac4i=4*Y3
11110     Tr=Bsqr-Ac4r
11120     Ti=Bsqi-Ac4i
11130     CALL Rtop(Tr,Ti,Mag,Phase)
11140     Radm=SQR(Mag)
11150     Radp=Phase/2
11160     CALL Ptor(Radm,Radp,X,Y)
11170     Numx_p=-Br+X
11180     Numy_p=-Bi+Y
11190     Numx_m=-Br-X
11200     Numy_m=-Bi-Y
11210     Denomx=2*Ar
11220     Denomy=2*Ai
11230     CALL Cdiv(Numx_p,Numy_p,Denomx,Denomy,X3,Y3)
11240     Rrp=X3

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11250      Rip=Y3
11260      CALL Cdiv(Numx_m,Numy_m,Denomx,Denomy,X3,Y3)
11270      Rrm=X3
11280      Rim=Y3
11290      SUBEND
11300      !
11310      !
11320      !   Converts an S-parameter matrix to a T-parameter matrix
11330      !
11340      SUB Tconv(S11r,S11i,S12r,S12i,S21r,S21i,S22r,S22i,T11r,T11i,T12r,T
12i,T21r,T21i,T22r,T22i)
11350      CALL Cmult(S11r,S11i,S22r,S22i,X3,Y3)
11360      D1r=X3
11370      D1i=Y3
11380      CALL Cmult(S12r,S12i,S21r,S21i,X3,Y3)
11390      Drr=X3
11400      Dri=Y3
11410      Del_r=D1r-Drr
11420      Del_i=D1i-Dri
11430      CALL Cdiv(-Del_r,-Del_i,S21r,S21i,X3,Y3)
11440      T11r=X3
11450      T11i=Y3
11460      CALL Cdiv(S11r,S11i,S21r,S21i,X3,Y3)
11470      T12r=X3
11480      T12i=Y3
11490      CALL Cdiv(-S22r,-S22i,S21r,S21i,X3,Y3)
11500      T21r=X3
11510      T21i=Y3
11520      CALL Cdiv(1,0,S21r,S21i,X3,Y3)
11530      T22r=X3
11540      T22i=Y3
11550      SUBEND
11560      !
11570      !
11580      !   Multiplies two complex numbers
11590      !
11600      SUB Cmult(X1,Y1,X2,Y2,X3,Y3)
11610      X3=X1*X2-Y1*Y2
11620      Y3=X1*Y2+Y1*X2
11630      SUBEND
11640      !
11650      !
11660      !   Divides two complex numbers
11670      !
11680      SUB Cdiv(X1,Y1,X2,Y2,X3,Y3)
11690      Denom=X2*X2+Y2*Y2
11700      Denom1=X1*X1+Y1*Y1
11710      IF (Denom<1.E-30*Denom1) THEN
11720          X3=1.E+30
11730          Y3=1.E+30
11740      ELSE
11750          X3=(X1*X2+Y1*Y2)/Denom
11760          Y3=(Y1*X2-X1*Y2)/Denom
11770      END IF
11780      SUBEND
11790      !

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11800      !  
11810      ! Performs polar to rectangular conversion  
11820      !  
11830      SUB Ptor(Mag,Phase,X,Y)  
11840          DEG  
11850          X1=Mag  
11860          X=X1*COS(Phase)  
11870          Y=X1*SIN(Phase)  
11880      SUBEND  
11890      !  
11900      !  
11910      ! Performs rectangular to polar conversion  
11920      !  
11930      SUB Rtop(X,Y,Mag,Phase)  
11940          DEG  
11950          Mag=SQR(X^2+Y^2)  
11960          Phase=2*ATN(Y/(X+Mag))  
11970      SUBEND  
11980      !  
11990      !  
12000      !  
12010      !
```

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TABLE I.—TAPER PROFILE COORDINATES FOR RIDGE GUIDE TRANSITION

[Microstrip line characteristic impedance = 50Ω]

(a) WR-42

Substrate thickness, <i>T</i> , mils					
0.005		0.010		0.020	
Ridge thickness, <i>W</i> , mils					
32.500		66.500		139.000	
<i>y</i> , mils	<i>x</i> , mils	<i>y</i> , mils	<i>x</i> , mils	<i>y</i> , mils	<i>x</i> , mils
000.00	0000.00	000.00	0000.00	000.00	0000.00
000.68	0033.46	000.35	0033.58	000.18	0035.85
002.67	0066.91	001.39	0067.15	000.74	0067.70
005.91	0100.37	003.10	0100.73	001.65	0101.54
010.24	0133.83	005.45	0134.31	002.92	0135.39
015.53	0167.28	008.38	0167.88	004.53	0169.24
021.56	0200.74	011.86	0201.46	006.47	0203.09
028.17	0234.20	015.80	0235.03	008.72	0236.93
035.16	0267.66	020.16	0268.61	011.27	0270.78
042.36	0301.11	024.85	0302.19	014.08	0304.63
049.64	0334.57	029.82	0335.76	017.14	0338.48
056.86	0368.03	034.99	0369.34	020.43	0372.32
063.94	0401.48	040.31	0402.92	023.92	0406.17
070.79	0434.94	045.72	0436.49	027.59	0440.02
077.38	0468.40	051.16	0470.07	031.41	0473.87
083.65	0501.85	056.60	0503.64	035.35	0507.71
089.59	0535.31	061.99	0537.22	039.40	0541.71
095.18	0568.77	067.29	0570.80	043.53	0575.41
100.44	0602.22	072.48	0604.37	047.72	0609.26
105.36	0635.68	077.55	0637.95	051.95	0643.11
109.96	0669.14	082.46	0671.53	056.20	0676.95
114.24	0702.59	087.21	0705.10	060.44	0710.80
118.22	0736.05	091.78	0738.68	064.67	0744.65
121.93	0769.51	096.18	0772.25	068.87	0778.50
125.37	0802.97	100.39	0805.83	073.03	0812.34
128.56	0836.42	104.41	0839.41	077.12	0846.19
131.53	0869.88	108.25	0872.98	081.15	0880.04
134.28	0903.34	111.91	0906.56	085.09	0913.89
136.84	0936.79	115.39	0940.14	088.95	0947.73
139.21	0970.25	118.69	0973.71	092.72	0981.58
141.40	1003.71	121.82	1007.29	096.38	1015.43
143.44	1037.16	124.78	1040.86	099.93	1049.28
145.34	1070.62	127.58	1074.44	103.37	1083.13
147.10	1104.08	130.22	1108.02	106.70	1116.97
148.73	1137.53	132.72	1141.59	109.90	1150.82
150.24	1170.99	135.07	1175.17	112.99	1184.67
151.64	1204.45	137.28	1208.75	115.95	1218.52
152.94	1237.91	139.37	1242.32	118.78	1252.36
154.15	1271.36	141.32	1275.90	121.49	1286.21
155.27	1304.82	143.15	1309.47	124.08	1320.06
156.31	1338.28	144.86	1343.05	126.53	1353.91
157.26	1371.73	146.47	1376.63	128.86	1387.75
158.15	1405.19	147.96	1410.20	131.07	1421.60
158.97	1438.65	149.35	1443.78	133.15	1455.45
159.72	1472.10	150.64	1477.36	135.10	1489.30
160.41	1505.56	151.83	1510.93	136.93	1523.14
161.04	1539.02	152.94	1544.51	138.63	1556.99
161.62	1572.47	153.95	1578.08	140.22	1590.84
162.14	1605.93	154.87	1611.66	141.68	1624.69
162.62	1639.39	155.72	1645.24	143.02	1658.54
163.05	1672.85	156.48	1678.81	144.24	1692.38
163.43	1706.30	157.16	1712.39	145.34	1726.23
163.77	1739.76	157.77	1745.97	146.32	1760.08
164.06	1773.22	158.30	1779.54	147.19	1793.93
164.31	1806.67	158.75	1813.12	147.94	1827.77
164.52	1840.13	159.45	1846.69	148.57	1861.62
164.70	1873.59	159.45	1880.27	149.08	1895.47
164.83	1907.04	159.69	1913.85	149.48	1929.32
164.92	1940.50	159.86	1947.42	149.77	1963.16
164.98	1973.96	159.97	1981.00	149.94	1997.01
165.00	2007.41	160.00	2014.58	150.00	2030.86

TABLE I.—CONTINUED.

[Microstrip line characteristic impedance = 50Ω]

(b) WR-28

Substrate thickness, T , mils					
0.005		0.010		0.020	
Ridge thickness, W , mils					
34.000		69.500		149.000	
y , mils	x , mils	y , mils	x , mils	y , mils	x , mils
000.00	0000.00	000.00	0000.00	000.00	0000.00
000.38	0022.66	000.20	0022.76	000.11	0023.08
001.51	0045.33	000.81	0045.53	000.44	0046.16
003.36	0067.99	001.81	0068.29	000.99	0069.23
005.88	0090.66	003.19	0091.05	001.76	0092.31
009.00	0113.32	004.94	0113.82	002.73	0115.39
012.65	0135.98	007.02	0136.58	003.91	0138.47
016.75	0158.65	009.43	0159.34	005.29	0161.55
021.20	0181.31	012.13	0182.11	006.87	0184.63
025.92	0203.97	015.08	0204.87	008.63	0207.70
030.83	0226.64	018.27	0227.63	010.56	0230.78
035.86	0249.30	021.65	0250.40	012.66	0253.86
040.94	0271.97	025.19	0273.16	014.91	0276.94
046.01	0294.63	028.87	0295.92	017.31	0300.02
051.02	0317.29	032.66	0318.69	019.83	0323.09
055.93	0339.96	036.52	0341.45	022.48	0346.17
060.71	0362.62	040.43	0364.21	025.24	0369.25
065.34	0385.29	044.36	0386.97	028.10	0392.33
069.79	0407.95	048.30	0409.74	031.04	0415.41
074.06	0430.61	052.21	0432.50	034.05	0438.49
078.14	0453.28	056.09	0455.26	037.12	0461.56
082.02	0475.94	059.92	0478.03	040.25	0484.64
085.71	0498.61	063.68	0500.79	043.41	0507.72
089.20	0521.27	067.36	0523.55	046.59	0530.80
092.50	0543.93	070.96	0546.32	049.80	0553.88
095.61	0566.60	074.46	0569.08	053.01	0576.96
098.55	0589.26	077.85	0591.84	056.21	0600.03
101.31	0611.92	081.14	0614.61	059.40	0623.11
103.91	0634.59	084.32	0637.37	062.57	0646.19
106.35	0657.25	087.38	0660.13	065.70	0669.27
108.65	0679.92	090.33	0682.90	068.80	0692.35
110.80	0702.58	093.16	0705.66	071.85	0715.42
112.82	0725.24	095.86	0728.42	074.85	0738.50
114.71	0747.91	098.46	0751.19	077.78	0761.58
116.47	0770.57	100.93	0773.95	080.65	0784.66
118.13	0793.24	103.29	0796.71	083.44	0807.74
119.68	0815.90	105.53	0819.48	086.16	0830.82
121.12	0838.56	107.66	0842.24	088.79	0853.89
122.47	0861.23	109.68	0865.00	091.34	0876.97
123.73	0883.89	111.59	0887.77	093.79	0900.05
124.90	0906.55	113.40	0910.53	096.15	0923.13
125.99	0929.22	115.10	0933.29	098.41	0946.21
127.00	0951.88	116.69	0956.06	100.57	0969.28
127.94	0974.55	118.19	0978.82	102.63	0992.36
128.81	0997.21	119.59	1001.58	104.57	1015.44
129.61	1019.87	120.89	1024.35	106.41	1038.52
129.34	1042.54	122.10	1047.11	108.14	1061.60
131.02	1065.20	123.21	1069.87	109.76	1084.68
131.63	1087.87	124.24	1092.64	111.26	1107.75
132.19	1110.53	125.18	1115.40	112.64	1130.83
132.69	1133.19	126.03	1138.16	113.91	1153.91
133.14	1155.86	126.79	1160.92	115.06	1176.99
133.54	1178.52	127.47	1183.69	116.10	1200.07
133.88	1201.18	128.07	1206.45	117.01	1223.15
134.18	1223.85	128.58	1229.21	117.80	1246.22
134.43	1246.51	129.02	1251.98	118.47	1269.30
134.64	1269.18	129.37	1274.74	119.02	1292.38
134.80	1291.84	129.65	1297.50	119.45	1315.46
134.91	1314.50	129.84	1320.27	119.76	1338.54
134.98	1337.17	129.96	1343.03	119.94	1361.61
135.00	1359.83	130.00	1365.79	120.00	1384.69

TABLE I.—CONTINUED.

[Microstrip line characteristic impedance = 50Ω]

(c) WR-22

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Substrate thickness, <i>T</i> , mils					
0.005		0.010		0.020	
Ridge thickness, <i>W</i> , mils					
34.000		70.500		161.500	
<i>y</i> , mils	<i>x</i> , mils	<i>y</i> , mils	<i>x</i> , mils	<i>y</i> , mils	<i>x</i> , mils
000.00	0000.00	000.00	0000.00	000.00	0000.00
000.25	0018.22	000.13	0018.33	000.07	0018.86
000.99	0036.44	000.53	0036.65	000.29	0037.73
002.21	0054.66	001.19	0054.98	000.64	0056.59
003.87	0072.88	002.10	0073.31	001.14	0075.45
005.95	0091.10	003.26	0091.64	001.78	0094.31
008.40	0109.32	004.65	0109.96	002.55	0113.18
011.18	0127.55	006.26	0128.29	003.46	0132.04
014.24	0145.77	008.08	0146.62	004.50	0150.90
017.52	0163.99	010.09	0164.94	005.66	0169.77
020.98	0182.21	012.27	0183.27	006.95	0188.63
024.57	0200.43	014.61	0201.60	008.35	0207.49
028.25	0218.65	017.08	0219.92	009.87	0226.35
031.97	0236.87	019.67	0238.25	011.49	0245.22
035.70	0255.09	022.36	0256.58	013.21	0264.08
039.40	0273.31	025.13	0274.91	015.03	0282.94
043.06	0291.53	027.96	0293.23	016.93	0301.81
046.65	0309.75	030.84	0311.56	018.92	0320.67
050.15	0327.97	033.75	0329.89	020.98	0339.53
053.54	0346.19	036.68	0348.21	023.11	0358.40
056.82	0364.41	039.62	0366.54	025.30	0377.26
059.98	0382.64	042.54	0384.87	027.55	0396.12
063.02	0400.86	045.44	0403.19	029.84	0414.98
065.92	0419.08	048.31	0421.52	032.16	0433.85
068.70	0437.30	051.14	0439.85	034.53	0452.71
071.34	0455.52	053.93	0458.18	036.91	0471.57
073.85	0473.74	056.65	0476.50	039.32	0490.44
076.24	0491.96	059.32	0494.83	041.73	0509.30
078.50	0510.18	061.91	0513.16	044.15	0528.16
080.64	0528.40	064.44	0531.48	046.56	0547.02
082.67	0546.62	066.89	0549.81	048.97	0565.89
084.58	0564.84	069.26	0568.14	051.36	0584.75
086.39	0583.06	071.55	0586.47	053.73	0603.61
088.09	0601.28	073.76	0604.79	056.06	0622.48
089.69	0619.50	075.88	0623.12	058.37	0641.34
091.20	0637.73	077.92	0641.45	060.63	0660.20
092.61	0655.95	079.87	0659.77	062.85	0679.06
093.94	0674.17	081.73	0678.10	065.01	0697.93
095.18	0692.39	083.51	0696.43	067.13	0716.79
096.35	0710.61	085.20	0714.75	069.17	0735.65
097.44	0728.83	086.81	0733.08	071.16	0754.52
098.46	0747.05	088.33	0751.41	073.07	0773.38
099.40	0765.27	089.77	0769.74	074.91	0792.24
100.28	0783.49	091.12	0788.06	076.67	0811.10
101.10	0801.71	092.39	0806.39	078.35	0829.97
101.86	0819.93	093.57	0824.72	079.95	0848.83
102.55	0838.15	094.68	0843.04	081.45	0867.69
103.19	0856.37	095.70	0861.37	082.87	0886.56
103.78	0874.60	096.64	0879.70	084.19	0905.42
104.31	0892.82	097.51	0898.03	085.41	0924.28
104.79	0911.04	098.30	0916.35	086.54	0943.15
105.22	0929.26	099.00	0934.68	087.57	0962.01
105.60	0947.48	099.64	0953.01	088.49	0980.87
105.93	0965.70	100.19	0971.33	089.30	0999.73
106.22	0983.92	100.67	0989.66	090.02	1018.60
106.46	1002.14	101.08	1007.99	090.62	1037.46
106.65	1020.36	101.41	1026.31	091.12	1056.32
106.81	1038.58	101.67	1044.64	091.50	1075.19
106.91	1056.80	101.85	1062.97	091.78	1094.05
106.98	1075.02	101.96	1081.30	091.94	1112.91
107.00	1093.24	102.00	1099.62	092.00	1131.77

TABLE I.—CONTINUED.

[Microstrip line characteristic impedance = 50Ω]

(d) WR-15

Substrate thickness, T , mils			
0.005		0.010	
Ridge thickness, W , mils			
34.500		74.000	
y , mils	x , mils	y , mils	x , mils
000.00	0000.00	000.00	0000.00
000.11	0012.06	000.06	0012.21
000.45	0024.12	000.24	0024.42
001.01	0036.19	000.55	0036.63
001.77	0048.25	000.97	0048.84
002.74	0060.31	001.51	0061.05
003.90	0072.37	002.16	0073.26
005.24	0084.44	002.93	0085.47
006.72	0096.50	003.80	0097.68
008.35	0108.56	004.77	0109.90
010.11	0120.62	005.83	0122.11
011.96	0132.68	006.98	0134.32
013.90	0144.75	008.22	0146.53
015.91	0156.81	009.53	0158.74
017.97	0168.87	010.92	0170.95
020.07	0180.93	012.36	0183.16
022.18	0192.99	013.87	0195.37
024.30	0205.06	015.42	0207.58
026.42	0217.12	017.02	0219.79
028.52	0229.18	018.66	0232.00
030.60	0241.24	020.32	0244.21
032.64	0253.31	022.01	0256.42
034.64	0265.37	023.71	0268.63
036.59	0277.43	025.43	0280.84
038.49	0289.49	027.15	0293.05
040.34	0301.55	028.87	0305.26
042.12	0313.62	030.58	0317.47
043.85	0325.68	032.29	0329.69
045.51	0337.74	033.97	0341.90
047.11	0349.80	035.64	0354.11
048.65	0361.86	037.28	0366.32
050.12	0373.93	038.90	0378.53
051.52	0385.99	040.48	0390.74
052.87	0398.05	042.03	0402.95
054.14	0410.11	043.54	0415.16
055.36	0422.18	045.01	0427.37
056.52	0434.24	046.44	0439.58
057.61	0446.30	047.82	0451.79
058.65	0458.36	049.15	0464.00
059.63	0470.42	050.43	0476.21
060.55	0482.49	051.66	0488.42
061.42	0494.55	052.84	0500.63
062.24	0506.61	053.96	0512.84
063.00	0518.67	055.03	0525.05
063.72	0530.74	056.04	0537.26
064.38	0542.80	056.99	0549.48
064.99	0554.86	057.89	0561.69
065.56	0566.92	058.72	0573.90
066.08	0578.98	059.50	0586.11
066.56	0591.05	060.21	0598.32
066.99	0603.11	060.87	0610.53
067.38	0615.17	061.46	0622.74
067.72	0627.23	061.99	0634.95
068.02	0639.29	062.46	0647.16
068.28	0651.36	062.87	0659.37
068.50	0663.42	063.21	0671.58
068.68	0675.48	063.50	0683.79
068.82	0687.54	063.72	0696.00
068.92	0699.61	063.87	0708.21
068.98	0711.67	063.97	0720.42
069.00	0723.73	064.00	0732.63

TABLE I.—CONCLUDED.

[Microstrip line characteristic impedance = 50Ω]

(e) WR-12

(f) WR-10

Substrate thickness, <i>T</i> , mils			
0.005		0.010	
Ridge thickness, <i>W</i> , mils			
35.005		78.000	
<i>y</i> , mils	<i>x</i> , mils	<i>y</i> , mils	<i>x</i> , mils
000.00	000.00	000.00	000.00
000.08	010.08	000.04	010.29
000.31	020.15	000.17	020.59
000.70	030.23	000.38	030.88
001.23	040.31	000.67	041.18
001.91	050.38	001.05	051.47
002.73	060.46	001.50	061.76
003.67	070.54	002.04	072.06
004.72	080.61	002.65	082.35
005.89	090.69	003.33	092.64
007.15	100.77	004.08	102.94
008.50	110.84	004.90	113.23
009.92	120.92	005.78	123.53
011.40	131.00	006.73	133.82
012.94	141.07	007.72	144.11
014.52	151.15	008.78	154.41
016.12	161.23	009.88	164.70
017.75	171.30	011.02	175.00
019.39	181.38	012.20	185.29
021.03	191.46	013.42	195.58
022.66	201.53	014.67	205.88
024.29	211.62	015.95	216.17
025.89	221.69	017.24	226.47
027.48	231.76	018.56	236.76
029.03	241.84	019.89	247.05
030.55	251.92	021.23	257.35
032.04	261.99	022.58	267.64
033.49	272.07	023.92	277.93
034.89	282.15	025.27	288.23
036.26	292.22	026.61	298.52
037.58	302.30	027.94	308.82
038.85	312.38	029.25	319.11
040.07	322.45	030.55	329.40
041.25	332.53	031.83	339.70
042.37	342.61	033.09	349.99
043.45	352.68	034.32	360.29
044.49	362.76	035.52	370.58
045.47	372.83	036.69	380.87
046.40	382.91	037.83	391.17
047.29	392.99	038.93	401.46
048.13	403.06	039.99	411.76
048.93	413.14	041.02	422.05
049.68	423.22	042.00	432.34
050.38	433.29	042.94	442.64
051.04	443.37	043.83	452.93
051.65	453.45	044.67	463.22
052.23	463.52	045.47	473.52
052.76	473.60	046.22	483.81
053.24	483.68	046.91	494.11
053.69	493.75	047.56	504.40
054.10	503.83	048.15	514.69
054.46	513.91	048.68	524.99
054.79	523.98	049.17	535.28
055.07	534.06	049.59	545.58
055.32	544.14	049.97	555.87
055.53	554.21	050.28	566.16
055.70	564.29	050.54	576.46
055.83	574.37	050.74	586.75
055.92	584.44	050.88	597.05
055.98	594.52	050.97	607.34
056.00	604.60	051.00	617.63

Substrate thickness, <i>T</i> , mils	
0.005	
Ridge thickness, <i>W</i> , mils	
35.500	
<i>y</i> , mils	<i>x</i> , mils
000.00	000.00
000.05	008.08
000.22	016.16
000.48	024.24
000.85	032.32
001.32	040.40
001.89	048.48
002.55	056.56
003.29	064.64
004.12	072.72
005.02	080.80
005.98	088.88
007.01	096.96
008.09	105.04
009.22	113.12
010.38	121.20
011.58	129.28
012.80	137.36
014.05	145.44
015.30	153.52
016.57	161.60
017.83	169.68
019.10	177.76
020.35	185.84
021.60	193.92
022.82	202.00
024.03	210.08
025.22	218.16
026.38	226.24
027.52	234.32
028.62	242.40
029.70	250.48
030.74	258.56
031.75	266.64
032.72	274.72
033.66	282.80
034.56	290.88
035.43	298.96
036.25	307.04
037.04	315.12
037.79	323.20
038.51	331.28
039.18	339.36
039.82	347.44
040.42	355.52
040.98	363.60
041.50	371.68
041.99	379.76
042.44	387.84
042.85	395.92
043.22	404.00
043.56	412.08
043.87	420.16
044.13	428.24
044.36	436.32
044.56	444.40
044.72	452.48
044.84	460.56
044.93	468.64
044.98	476.72
045.00	484.80



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16. Abstract <p>The design and evaluation of a novel fixturing technique for characterizing millimeter-wave solid-state devices is presented. The technique utilizes a cosine-tapered ridge guide fixture and a one-tier de-embedding procedure to produce accurate and repeatable device-level data. Advanced features of this technique include nondestructive testing, full waveguide bandwidth operation, universality of application, and rapid, yet repeatable, chip-level characterization. In addition, only one set of calibration standards is required regardless of the device geometry.</p>					
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