Preliminary Design of a Radiator Shading Device for a Lunar Outpost

Submitted to: Michael K. Ewert Thermal Control System Analyst Lyndon B. Johnson Space Center NATIONAL AERONAUTICS AND SPACE ADMINISTRATION Houston, Texas

> Prepared by: Carlos Barron Norma I. Castro Brian Phillips (Team Leader)

Mechanical Engineering Design Projects Program THE UNIVERSITY OF TEXAS AT AUSTIN

Fall 1991



THE UNIVERSITY OF TEXAS AT AUSTIN

ETC 4.102 · Austin, Texas 78712-1063 · (512) 471-3900 · FAX (512) 471-7682

November 20, 1991

Mr. Michael K. Ewert Crew and Thermal Systems Division Lyndon B. Johson Space Center, EC7 Houston, TX 77058

Dear. Mr. Ewert:

Enclosed is the design report entitled <u>Preliminary Design of a Radiator Shading Device for a Lunar Outpost</u>. The report discusses the shading devices developed by the design team. The shading devices also include alternates for supporting and deploying and retracting the shading systems. A shading device, support structure, and deploy and retract alternates were combined and a prelimnary design was developed. In addition, a thermal performance analysis of the thermal control system was conducted for the shading devices. The preliminary design includes thermal performance and mechanical stress analyses.

It has been a pleasure working with you in this design project and we look forward to seeing you at our oral presentation. The oral presentation is scheduled for Tuesday, December 3, 1991, at 1 p.m. in room 4.110 of the Engineering Teaching Center at the University of Texas at Austin. A catered luncheon starting at noon will precede the presentation.

Thank you for your assistance throughout the semester.

Sincerely,

1ka Brinon Carlos Barron

Norma I. Castro

Brian Phillips

ACKNOWLEDGEMENTS

The design team would like to first acknowledge the project sponsor, Mr. Michael K. Ewert and the National Aeronautics and Space Administration, for giving the design team the opportunity to work on one of their design projects, thus providing the design team with valuable engineering experience. The design team also wishes to acknowledge Professor Philip S. Schmidt, who was the faculty advisor, for his time and expert assistance during the development of the project.

The design team would like to give special thanks to Mr. Bert Herigstad, the Mechanical Engineering Design Projects Program Administrative Assistant, for his hard work and dedication to the design teams and the Design Projects Program. Also, the design team wishes to give special thanks to Mr. Hank Kleespies, the Teaching Assistant for M.E. 466 K, for his time and guidance throughout the semester.

The design team would like to thank Professor John R. Howell, for his expert advice and valuable time. Also, the design team wishes to acknowledge Mr. Wendell Deen, for his assistance in graphic matters. Last, but not least, the design team would like to acknowledge Dr. Steven P. Nichols, for giving the design teams the opportunity to participate in the Mechanical Engineering Design Projects Program.

TABLE OF CONTENTS

i
ü
vi
vii
1
1
2
5
6
7
7

I. ALTERNATE DESIGNS	9
2.1 Background	9
2.1.1 Albedo, Solar, and Planetary IR 1	0
2.1.2 Reflectivity, Absorptivity, and Transmissivity	0
2.1.3 Serrated Surfaces 1	3
2.1.4 Thermal Performance Using Shading Devices 1	3
2.2 Alternates for Reducing the Radiation Incident on the Radiator 1	5
2.2.1 Parabolic Reflector 1	5
2.2.2 Modified Parabolic Reflector 1	7
2.2.3 L-Shaped Panels 1	8

	2.2.4 Fresnel Reflector	20
	2.2.5 Winged Radiator	22
	2.2.6 Modified Winged Radiator	23
	2.2.7 Shading Blinds	24
	2.2.6 Summary	26
2.3 A	Iternates of the Deploy Mechanism	27
	2.3.1 Folding Support Structure and Motion System	28
	2.3.2 Rail Support Structure and Scissors Mechanism	29
2.4 S	election of Final Design Solution	31
III. DESCRI	PTION OF FINAL DESIGN	33
3.1 T	hermal Performance Analysis	33
3.2 F	inal Design Analysis	35
IV. CONCI	LUSIONS AND RECOMMENDATIONS	40
4.1 C	Conclusions	. 40
4.2 R	ecommendations for Dust Control	. 41
	4.2.1 Shaking Mechanism	. 42
	4.2.2 Appllication of Removable Transparent Layers	. 43
	4.2.3 Gas Jets	. 44
	4.2.4 Explosive Inflation of a Balloon	46
	4.2.5 Dust Blowing Device	. 47
4.3 R	ecommendations for Future Work	. 49
References		. 50

Appendices

A:	Comparison of Different Conducting Materials	A1
B:	Design Requirements	B1
C:	Material and Thermal Parameters	C1
D:	Estimated Thermal Performance Calculations	Dl
E:	Heat Transfer Calculations	E1
F:	Mass, Volume, and Power Calculations	F1
G:	Desicion Matrix	G1
H:	Final Thermal Performance Calculations	H1
I:	Analysis of Final Design Solution	I 1

LIST OF FIGURES

Figure 1. Sun's path relative to a vertical radiator	3
Figure 2. Radiators oriented in the vertical and horizontal positions	4
Figure 3. Radiator heat transfer processes	4
Figure 4. Parabolic Shading Device	5
Figure 5. Modes of reflection	11
Figure 6. Heat Transfer Processes	14
Figure 7. Parabolic Reflector	16
Figure 8. Modified Parabolic Reflector	18
Figure 9. L-Shaped Panels	21
Figure 10. Fresnel Reflector	21
Figure 11. Winged Radiator	22
Figure 12. Modified Winged Radiator	24
Figure 13. Shading Blind	25
Figure 14. Folding Support Structure and Motion System	29
Figure 15. Winged Radiator System	30
Figure 16. Modified Shading Device with the Rail Support Structure	39
Figure 17. Removable Layers	44
Figure 18. Gas Jets	45
Figure 19. Balloon Mechanism	47
Figure 20. Dust Blowing Device	48

LIST OF TABLES

Table 1	Thermal Performance Comparison for Alternates	26
Table 2	Thermal Analysis Results for Different Parameters	35

I. INTRODUCTION

The National Aeronautics and Space Administration (NASA) sponsored a project at The University of Texas at Austin to design a shading device for a radiator. The radiator is part of a thermal control system for a permanent outpost on the moon. This section presents the purpose of the project, design criteria, results required of the project, and the design methodology.

1.1 Sponsor Background

NASA, established by the United States government in 1958, is responsible for aeronautical and aerospace research and exploration [1]. The design project sponsor, the Lyndon B. Johnson Space Center, is one of ten NASA facilities. Several responsibilities of the Johnson Space Center are

- the selection and training of astronauts
- the design, development, and testing of spacecraft and associated systems for manned space flights
- thermal and fluid systems analysis and testing
- selection and testing of materials and structures
- planning and conducting of manned space flight missions

Currently, NASA is planning to establish manned bases on the moon and Mars. In addition, NASA is involved in the design, development, and testing of Space Station Freedom, which is to be placed in earth orbit.

1.2 Project Background

The extreme temperatures on the moon surface (102 K to 384 K) and the length of the lunar day/night cycle (29.5 earth days) make it necessary for a permanent habitat to have a thermal control system [2]. A thermal control system controls the heat transfer processes occurring between the habitat and the surroundings, making it possible to heat or cool the habitat. An example of a thermal control system is a home air conditioning system.

Due to the absence of a lunar atmosphere, the only ways to transfer heat are through radiation and/or conduction. Conduction can be accomplished through the moon's top surface material (also called regolith). The lunar regolith's thermal conductivity (0.0021 W/m K) is less than the thermal conductivity of cotton (0.06 W/m K), which is a good thermal insulator [3]. As a result, a very large lunar surface area is necessary to conduct heat through regolith. For example, to conduct 1 Watt through a 1 meter thick sample of lunar regolith that is maintained at a 1°C temperature differential, an area of 476 m² is needed (see Appendix A).

A radiator can be used to reject heat to the lunar environment. The radiator carries a working fluid that absorbs waste heat produced in the habitat. As the fluid passes through the radiators, it radiates heat to the environment.

The habitat assumed for this project will be the lunar equator. In this case, if a

vertical radiator is used, it will be aligned with the line of the equator, along the sun's path (see Figure 1). As a result, the radiator area exposed to the incident solar radiation will be negligible. The area exposed to the solar radiation will vary slightly because the sun's path varies with an angle of 1.53 degrees from the vertical.

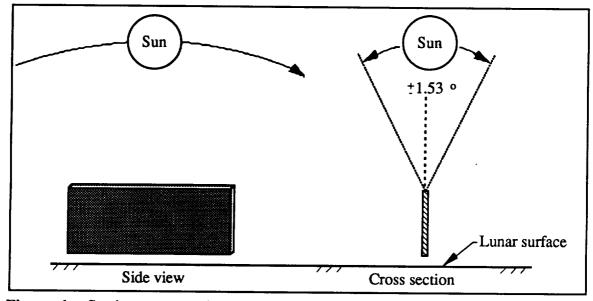


Figure 1. Sun's path relative to a vertical radiator

A drawback of using a radiator at the lunar equator is that the radiator absorbs more heat than it rejects during the lunar midday, which is roughly two earth days long. The radiators can be oriented in a vertical or horizontal position (see Figure 2). The heat absorbed by a vertical radiator is due to *albedo*^{*}, surface infrared radiation, and direct solar radiation incident on the radiator (see Figure 3). The heat absorbed by a horizontal radiator results from direct solar radiation. During midday, the *effective heat sink temperature* is greater than the operating temperature of the radiator [4]. As a result, there is a net heat transfer into the radiator.

^{*} All italicized terms are defined in the Glossary

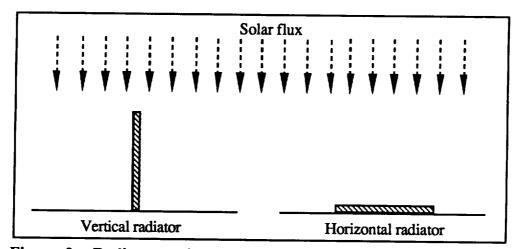


Figure 2. Radiators oriented in the vertical and horizontal positions [2]

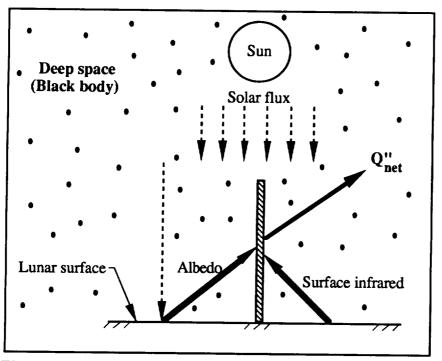


Figure 3. Radiator heat transfer processes [2]

Rejecting heat during the lunar midday can be accomplished by raising the radiator temperature or by decreasing the radiation incident on the radiator. The incident radiation can be decreased by using a shading device. NASA is considering the use of a

parabolic shading device (see Figure 4). The parabolic shade reduces the radiation incident on the radiator by blocking planetary infrared radiation. Solar radiation is reflected off the inner surface of the parabola to a focal point above the radiator. Engineers at NASA found that the effective heat sink temperature is reduced below the temperature of the radiator, thus allowing a net heat rejection from the radiator. An advantage of using a shading device is that it does not require power to operate. Raising the radiator temperature requires the use of a powered device, such as a heat pump.

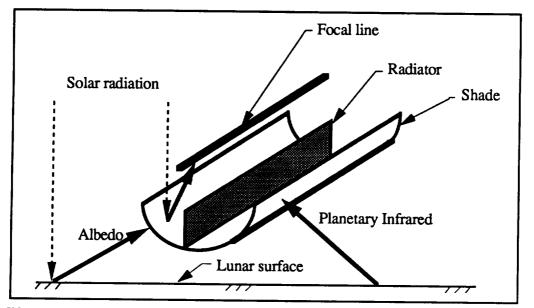


Figure 4. Parabolic shading device [4]

1.3 <u>Purpose of the Project</u>

The purpose of this project was to develop several alternates of a shading device. The alternates were evaluated and the alternate receiving the highest rating was developed into a preliminary design. The preliminary design included means of attaching the radiator to the shading device, a support structure for the shade and radiator, and means of deploying the radiator and support structure from the lunar transport.

1.4 Design Criteria

Shading devices were developed for a thermal control system capable of rejecting 10 kW and 25 kW of waste heat. The shading device and radiator (from now on referred to as shading system) for the 10 kW thermal control system must be automatically deployable. The deploy mechanism (support structure and device used to place the shading system in operating position) must perform its function for 200 deploy/retract cycles. Due to limited power supply on the moon, the power to deploy the shading system should be minimal. The 25 kW thermal control system is to be used for the permanent habitat. The shading system can be automatically deployable or easily assembled by two crewmen and must have a life of 20 years. Because of limited cargo space, the volume occupied by the shading system and deploying mechanism must be minimal. Because transportation costs to the moon are high, the mass of the shading system and deploy mechanism must be minimized. Other design requirements are presented in Appendix B

Other aspects considered in designing the shading system are the moon's gravity (1/6 of earth's gravity) and near perfect vacuum. It is assumed that the shading system will be deployed on a smooth surface. Several thermal and material parameters were provided by the project sponsor for the purpose of comparing the performance of the shading systems on the same basis. Other design parameters are presented in Appendix C.

1.5 Required Results

A preliminary design and analysis of the chosen alternate is provided. The preliminary design includes preliminary drawings, mass breakdown, power requirement estimates, stowed and deployed volumes, and results of analyses. Preliminary analyses include mechanical stresses, and thermal performance of the shading system. In addition, the design team provided recommendations for dust removal on the shading system.

1.6 <u>Design Methodology</u>

The design team's approach to arrive at different design solutions is based on Pahl and Beitz's design methodology [5]. One of the objectives of the project was to design a shade for a radiator. Subfunctions considered in meeting the goal are to reduce the radiation incident on the radiator, support the shading system, deploy and retract the shading system, and control lunar dust accumulation. Several alternates were developed for each subfunction and combined to fulfill the project goal.

First, the team decided to develop ideas on how to reduce the radiation incident on the radiator. Once ideas were obtained, alternates for reducing the radiation incident on the radiator were developed. At the same time, a literature and patent search was conducted to aid in the development of solutions. Research was done on methods of changing material optical properties, methods of influencing the effects of solar and planetary radiation, methods of increasing radiator thermal performance, studies done on space thermal systems, lunar environment, dust accumulation, and materials. This process resulted in several solutions for reducing the radiation incident on the radiator. The same process was repeated for the remaining subfunctions. Combination of the subfunction alternates resulted in different solutions for shading systems.

By means of a decision matrix, ratings were assigned to each concept according to how well the concepts fulfilled the design considerations. Ratings were assigned to each alternate according to how well the alternates fulfilled the design considerations. The design considerations used were low mass, low volume, thermal performance, low power consumption, safety, reliability, ease of assembly, and ease of maintenance. The alternate receiving the highest overall rating was selected for preliminary design development. The preliminary design of the alternate having the highest rating includes preliminary drawings, mechanical and thermal stress analysis, thermal performance analysis, mass calculations, volume calculations, and power consumption estimates.

This report presents a discussion of the alternates developed by the design team for a shading device, support structure, and deploy mechanism. The report discusses the design solution and preliminary design. Finally, the report presents the conclusion and recommendations for future work.

II. ALTERNATE DESIGNS

This section discusses the alternates developed by the design team for the following subfunctions:

- reducing the radiation incident on the radiator
- supporting and deploying the shading system

From the number of alternate designs that were developed for each subfunction, the alternate having the highest rating is discussed. This section begins with background information which is provided for the purpose of helping the reader understand the alternates developed. The discussion of the different alternates for reducing the radiation incident on the radiator follows the background information. The alternates for supporting and deploying and retracting the system are then discussed. Finally, this section makes recommendations on ways to prevent the accumulation of dust on the shade surfaces.

2.1 Background

The primary goal of the design team was to develop several shades that will reduce the planetary infrared radiation (IR), albedo, and/or solar radiation incident on the radiator. This section identifies which type of radiation has the greatest effect on the effective heat sink temperature. Also, the surface properties that the shading device surface can have to reduce the incident radiation are discussed. **2.1.1** Albedo. Solar. and Planetary IR. Reducing the radiation incident on the radiator can be explained by the heat transfer processes occurring between the radiator and the environment (see Appendix D). The effective heat sink temperature (T_{sink}) is a term that accounts for the components of the absorbed radiation (direct solar flux, albedo, and planetary infrared) in simplified form. The basic task of the shading device is to reduce T_{sink} by reducing the planetary infrared radiation, reducing the direct solar radiation and albedo, or reducing a combination of all the components incident on the radiator. For a vertical radiator, it will be necessary to reduce the planetary infrared by more than 58%. Reducing only the albedo and direct solar radiation will not result in a net radiator is eliminated, then the planetary infrared radiation will have to be reduced by more than 54%. For a horizontal radiator, the direct solar radiation must be reduced by more than 23% for a net transfer out of the radiator. Since the planetary infrared radiation has the greatest effect on T_{sink} , the shading device should minimize the planetary infrared radiation incident on the radiator.

2.1.2 Reflectivity. Absorptivity. and Transmissivity. The inner and outer surface properties of a shade, which can be different, are described by its ability to reflect, absorb, and transmit radiation. These properties will be used to reduce the heat absorbed by the radiator. Radiation can be absorbed, selectively transmitted, or reflected by the shade surface. Equation 2.1 shows how these properties are related.

$$\rho + \alpha + \tau = 1 \tag{2.1}$$

where ρ is the reflectivity, α is the absorptivity, and τ is the transmissivity. Equation 2.1 assumes that the properties are averaged over the entire spectrum. The reflectivity, absorptivity and transmissivity can be varied by applying a coating to the surface. The

material used determines which of these characteristics is dominant. A wide variety of material surfaces can be polished and coated to reflect nearly all of the incident radiation [6]. The coating is a thin layer of metal such as aluminum, silver, or gold. The outer surface of the radiator should be highly reflective to planetary IR to prevent heat absorption.

A characteristic of most polished surfaces is that they are specular. The angle of reflection for radiation reflected off a specular surface is equal to the incident angle. It is an advantage to have a specular surface instead of a diffuse surface because a diffuse surface will reflect radiation in all directions (see Figure 5). By using a specular surface, it will be possible to redirect radiation away from the radiator and predict the resulting path of the radiation.

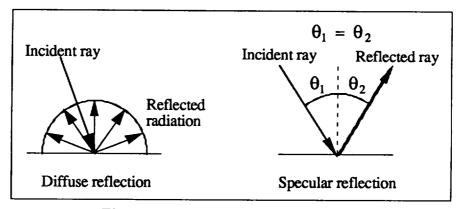


Figure 5. Modes of reflection [7]

Filtering of radiation is the selective transmission of certain radiation wavelengths. The wavelengths that are not transmitted are either reflected or absorbed. Filters are classified according to their range of transmission. Short-pass filters allow transmission of everything below a given wavelength; long-pass filters allow transmission of everything above a given wavelength; band-pass filters allow transmission in a wavelength range; and rejection filters reject radiation in a given wavelength range [8]. A shade surface cannot utilize a filter to prevent transmission of albedo, infrared and/or solar radiation into the radiator while allowing radiation from the radiator to be transmitted away from the radiator. Heat transfer by radiation results from matter being at a finite temperature. The range of wavelengths that are emitted is temperature dependent. For a blackbody (ideal surface), which emits and absorbs more radiation than any other surface, the intensity of radiation at smaller wavelengths increases with increasing temperature. The temperature of the radiator (270 K) and the lunar surface (384 K) do not differ enough to make much of a difference in their range of wavelengths. The sun, which is assumed to be a blackbody at 5800 K, emits a spectrum of radiation that encompasses the spectrum of radiation of the radiator and the lunar surface. Because the spectra of radiation overlap, it will not be possible to prevent transmission of albedo, solar, and/or planetary radiation to the radiator while allowing radiator emission to pass through the filter. Therefore, the only way to reduce the infrared and albedo radiation absorbed by the radiator is to make the surfaces of the shade highly reflective.

The outer surface of the shade should a have a low absorptivity in the planetary IR spectrum. For a given surface emissivity, a decrease in absorptivity decreases the amount of heat that is emitted to the radiator. The inner surface will have a low emissivity and the absorptivity depends on the shading device used. These characteristics will reduce the amount of solar radiation incident on the radiator while minimizing the radiation emitted from the shade. For the parabolic reflector the inner surface is highly reflective and the radiation is reflected to a focal point above the radiator. This thermal energy can be converted to electricity or some other form of energy.

Using equation 2.1, the reflectivity of the outer surface can be maximized by making the surface opaque ($\tau = 0$) and minimizing the absorptivity. For the inner surface, the appropriate reflectivity and absorptivity can be determined by performing a thermal

12

analysis.

2.1.3 Serrated Surfaces. To further reduce the radiation reflected to the radiator the shade surfaces can be serrated. Serrations are grooves of a specified angle or radius of curvature which reflect radiation in a different direction. Thermal analysis were made assuming the surfaces were not serrated. Several of the alternates incorporate serrated surfaces.

2.1.4 Thermal Performance Using Shading Devices. The thermal performance, using different shades, can be accomplished by performing an energy balance on a vertical radiator (see Figure 5). Doing an energy balance results in equation (2). Substituting T_{sink} into equation (3) gives the area necessary to reject a quantity of heat. From equation (3), it can be seen that reducing T_{sink} reduces the radiator area required to reject a fixed quantity of heat, and hence reduces the mass of the system. An estimated effective heat sink temperature and radiator area for each alternate is presented at the end of the descriptions to give a general idea of the relative thermal performance of each alternate (see Table 1). The calculations are made on the assumption that the system rejects 25 kW of waste heat produced in the habitat. The system is designed for the worst case, which is rejection of heat at the lunar midday. A drawback of designing the shading system for the worst case is that the thermal control system will be oversized for operation during the lunar night. An oversized thermal control system will be capable of rejecting more than the 10 kW or 25 kW of waste heat, which will cause the habitat to become too cold for the astronauts. To control the amount of heat being rejected at night, the flow rate of the heat transfer fluid can be reduced or some of the radiators can be bypassed. The project does not propose how to implement these solutions. The design team did not consider the

performance of the systems when arranged side by side, end to end, or in an array. For purposes of illustration and simplicity, the calculations represent one radiator/shade system.

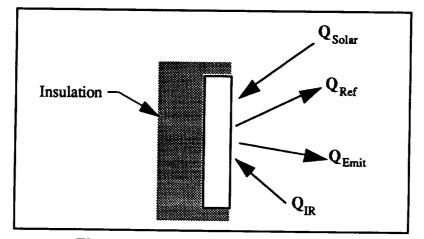


Figure 6. Heat Transfer Processes

$$T_{sink} = \left[\sigma^{-1}((\alpha/\epsilon)q_{sol} + q_{IR})\right]^{1/4}$$
(2.2)

$$A = Q/\eta \varepsilon \sigma (T_r^4 - T_{sink}^4)$$
(2.3)

Where,

$$\sigma$$
 = Stefan-Boltzmann constant (5.67x10⁻⁸ W m⁻² K⁻⁴)
 α = Absorptivity of the surface
 ϵ = emissivity of the surface
 q_{sol} = Solar radiation heat flux(approx. 1371 W m⁻²)
 q_{IR} = Infrared radiation flux
 η = Efficiency of the radiating surface
 A = Area of radiating surface
 T_r = Temperature of the radiating surface
 Q = Quantity of heat to be rejected

By qualitatively considering the radiator area and geometry of each shade a relative comparison of the shade masses can be made. The design team rated the alternates as having a low, moderate, or high mass.

2.2 Alternates for Reducing the Radiation Incident on the Radiator

The geometries and function of the shading devices are described in the following section. The shading devices are evaluated on mass, thermal performance, and stowage volume occupied.

Unless specified, the shade and radiator length are aligned with the lunar equator. In this position, only the top of the radiator is directly exposed to the sun during the course of the day. Unless otherwise specified, the surfaces of the shades are highly reflective. The surfaces of the shades facing the radiator have a low emissivity so that radiation emitted to the radiator is minimized. The shading devices do not prevent dust from accumulating and the value of the surface properties (reflectivity, emissivity, and absorptivity) do not account for the effect of dust.

2.2.1 Parabolic Reflector. The shade is a parabola when viewed in transverse cross section. Its curved inner surface surrounds a vertical radiator (See Figure 6). The outer surface blocks IR radiation and albedo, and the inner surface redirects solar radiation to a focal point above the radiator. The shade can be made of either a rigid or flexible material that is coated with a thin layer of highly reflective material, such as aluminum, silver, or gold.

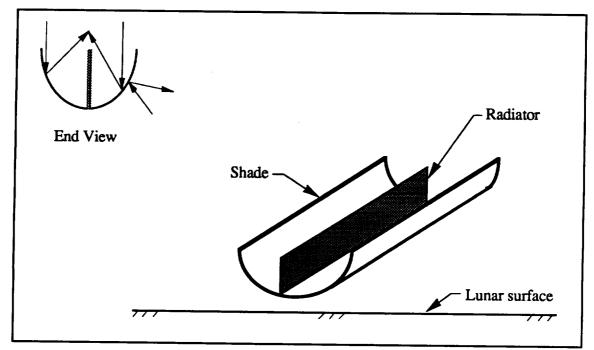


Figure 7. Parabolic Reflector

Advantages of the Parabolic Reflector are

- 1. Planetary IR and albedo do not strike the radiator.
- 2. Focussed solar radiation can be converted to useful energy.
- 3. If shade is made of rigid material the shade can be formed precisely into a parabolic shape.
- 4. If the shade is made of flexible material, it can be rolled, bent, or folded into a compact package to save space.
- 5. Using a Parabolic Reflector decreases the effective heat sink temperature more than the other shading devices.

Disadvantages of the Parabolic Reflector are

- 1. The rigid parabolic shade occupies more space than the flexible shade, since it cannot be bent, rolled, or folded into a smaller package.
- 2. A parabolic shade made of flexible material may not achieve a true

parabolic shape. It may assume an elliptic shape when hung from above or it may assume a hyperbolic shape when supported from below.

- Solar radiation incident on the reflective shade at points close to the radiator will be directed into the radiator after reflection towards the focal point.
- 4. Moderate mass

2.2.2 Modified Parabolic Reflector. The shade in this alternate is essentially a parabola when viewed in transverse cross section, like the parabolic reflector, but with a modified vertex. The vertical radiator is situated, as shown in Figure 7. By slanting the vertex downwards on either side of the radiator, solar radiation incident at points close to the radiator will be reflected away from the radiator instead of towards it. The rest of the shade is exactly the same as that for the Parabolic Reflector. Advantages of the Modified Parabola are

- 1. The planetary IR and albedo are blocked.
- 2. Compared to the parabolic reflector design, less solar radiation is reflected towards the radiator.
- 3. A shade made of flexible material can be made compact, since it can be rolled, folded or bent.
- 4. A shade made of rigid material can maintain a true parabolic shape.
- 5. The Modified Parabola significantly increases the thermal performance of the thermal control system.

Disadvantages of the Modified Parabola are

1. The slanted vertex adds a degree of complexity to manufacturing the parabolic reflector, for both rigid and flexible materials.

- 2. A shade of flexible material may not maintain the vertex indentation, it also may not assume a true parabolic shape.
- 3. A shade of rigid material cannot be easily bent, rolled, or folded into a small package.
- 4. Moderate mass

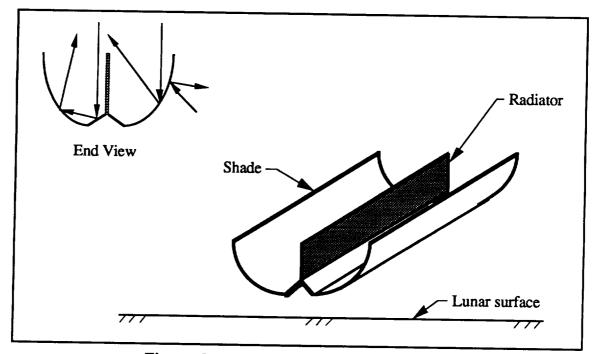


Figure 8. Modified Parabolic Reflector

2.2.3 L-Shaped Panels. In this design reflective panels are connected to form L-shaped shades. The shades are in a slanted position relative to the vertical radiator and are attached to the base of the radiator (See Figure 8). The downward slanted sides of the shade reflect incoming solar radiation away from the radiator. The small end pieces are turned up to prevent planetary IR and albedo from striking the radiator.

The angle and length of the side panels and end pieces that allow the to reduce

planetary IR, albedo, and the reflected radiation emitted from the radiator back to the radiator. Advantages are:

- 1. The shade panels are simple to manufacture.
- The straight flat panels can be joined so they can be folded and made to lie along the vertical sides of the radiator prior to stowing.

Disadvantages of the L-Shaped Panels are.

- 1. Not all planetary IR and albedo will be blocked. For example, the angle of the panel from the vertical can be increased so that less reflected solar radiation strikes the radiator. The panel length can simultaneously be increased so that all planetary IR and albedo is blocked. Doing this will increase the mass of the shading device, which is a parameter to be minimized. Instead, the radiator length can be kept constant and the angle of the panel can be varied. This increases the radiator's view of deep space and allows planetary IR and albedo to strike the radiator. At a certain angle a good thermal performance is achieved. The same procedure can be performed for panels of different lengths and the results can be compared to determine the design length and angle.
- 2. High mass
- 3. Does not reduce the effective heat sink temperature below the operating temperature of the radiator

19

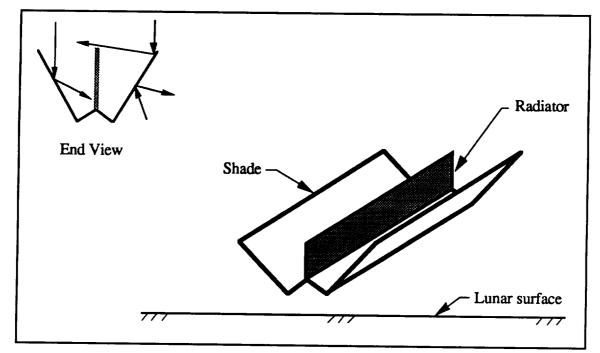


Figure 9. L-Shaped Panels

2.2.4 Fresnel Reflector. The shade consists of a flat panel laid horizontally with angled side panels attached to the ends of it. Both the flat and side panels are highly reflective on their upper and lower surfaces. The upper surfaces of both panels incorporate a serrated surface. The system is oriented so the path of the sun is along the top edge of the radiator (see Figure 9).

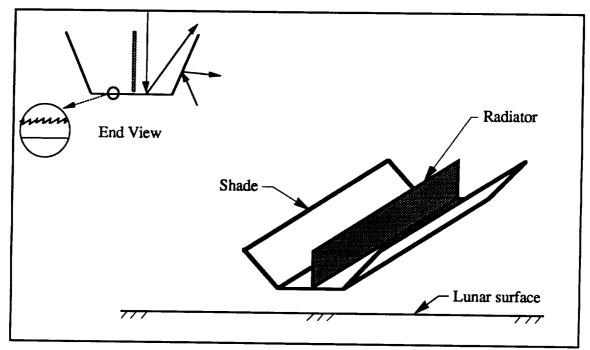


Figure 10. Fresnel Reflector

The side panels reduce the planetary IR and albedo incident on the radiator. The serrated surfaces have their grooves angled so that solar radiation is reflected away from the radiator. The length and angle of the side panels as well as the groove angles in the serrated surface can be optimized to obtain the maximum performance of the radiator.

The advantages of the Fresnel Reflector are:

- 1. The flat panels can be folded to produce a compact package.
- 2. The design is simple.
- 3. The shade can be constructed of rigid or flexible materials.

Its disadvantages are:

- 1. Not all planetary IR and albedo will be blocked.
- 2. Moderate mass
- 3. Does not reduce the effective heat temperature below the operating temperature of the radiator

2.2.5 <u>Winged Radiator</u>. The shading system in this alternate consists of panels attached to the corners of the vertical radiator, as shown in Figure 10. By means of detentes in the attaching mechanism, the panels can be maintained at open or closed positions.

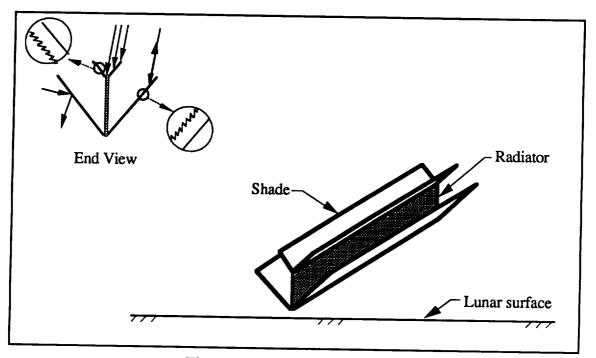


Figure 11. Winged Radiator

The top panels block direct solar radiation. Planetary IR and albedo are blocked by the bottom panels. The top panels are made shorter than the bottom panels because if the top panels were longer they would receive planetary IR radiation which would then be reflected to the radiator. Also, for a vertical radiator at the lunar equator, the effect of solar radiation is not as significant as that of planetary IR. This effect is because the the normal component of the sun's radiation on the radiator is smaller than the normal component due to planetary IR and albedo

The bottom surface of the top panel, and the top surface of the bottom panel are

serrated so that radiation that would ordinarily be reflected towards the radiator by a smooth reflective surface is instead reflected away from the radiator. Advantages are

- 1. The shading device is simple to manufacture.
- 2. The panels can be folded for compact storage.
- 3. The shading device can be made lightweight.
- 4. This is the only shading device that blocks solar radiation.
- 5. Decreases the effective heat sink temperature enough to allow the thermal control system to perform well

The disadvantages of the Winged Radiator are

- 1. Does not block all planetary IR and albedo
- 2. Outer surface of the top panels emit radiation to the radiator and decrease the radiator's view of the sky.

2.2.6 <u>Modified Winged Radiator</u>. This alternate is similar to the Winged Radiator, except there are no upper panels to block direct solar radiation. The assumption is that the component of direct solar radiation has little effect on the effective heat sink temperature. Blocking sufficient planetary IR and albedo will reduce the effective heat sink temperature enough to accomplish heat rejection from the radiator at lunar midday.

The upper surface of each panel is serrated to aid in directing solar radiation away from the radiator (see Figure 11).

Advantages of the Modified Winged Radiator are

- 1. This design can be folded and hence has small space requirements.
- 2. Manufacturing the panels is simple
- 3. Has the lowest mass of all shading devices

The disadvantages of the Modified Winged Radiator are

- 1. Does not block direct solar radiation.
- 2. The thermal performance is not as good as other systems.
- 3. Solar radiation that will normally not reach the radiator might reflect from the upper surface of the shade directly into the radiator.

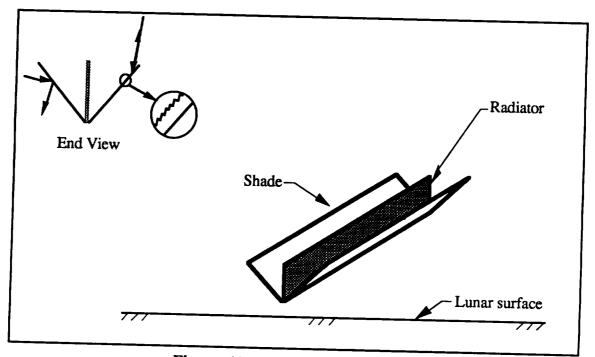


Figure 12. Modified Winged Radiator

2.2.7 Shading Blinds. This alternate is similar to Venetian blinds that shade windows in buildings. It differs from the other alternates due to the fact that it is an active system. In the design, reflective panels of rectangular cross section (slats) are placed above a horizontal radiator so that their centers of mass describe an arc above the radiator (see Figure 12). The slats are positioned so that their length is perpendicular to the sun's path.

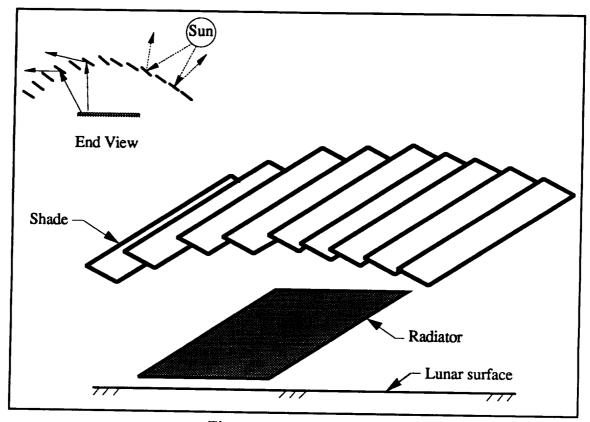


Figure 13. Shading Blinds

To prevent solar radiation from passing through the spaces between the slats, the system has a sun tracking device that rotates the slats with the sun's motion to ensure that they are always normal to the sun. Therefore, on the side facing the sun, the slats will be very close to one another, and some amount of radiator emission will be reflected back to the radiator from those slats. Most of the radiator's emission will pass between the slats on the side which is not exposed to the sun. The advantages of the Shading Blinds are

1. Since it is composed of parts, it will be relatively easy to store.

Disadvantages of the Shading Blinds are

- 1. The sun tracking device makes the system more unreliable.
- 2. High mass
- 3. This shading device does not reduce the effective heat sink temperature

below the operating temperature of the radiator.

Appendix E

Table 1				
Thermal	Performance	Comparison	for	Alternates

Shade	Estimated Effective Heat Sink Temperature (K)
Parabolic Reflector	214
Modified Parabolic Reflector	212
L-Shaped Panels	273
Fresnel Reflector	265
Winged Radiator	229
Modified Winged Radiator	250
Shading Blind	339

2.2.6 Summary. The thermal performance analysis conclude that the L-Shaped Panels, Fresnel Reflector, and Shading Blind Reflector do not decrease the effective heat sink temperature below the operating temperature of the radiator. Therefore, these devices will not be incorporated into the thermal control system. The Modified Winged Radiator has the lowest mass of all alternates. The thermal performance when using the Modified Parabolic Reflector or the Parabolic Reflector is better than.the other concepts......

2.3 Alternates of the Deploy Mechanism

In addition to developing different alternates for shading the radiator, the design team developed deploy mechanisms (support structure and device used to place the shading system in operating position). Since developing alternates for deploying and retracting involves developing a support structure for the shading system, alternates for both deploying and retracting and supporting the shading system were simultaneously worked on.

The shading system and support structure can be remotely operated. In other words, astronauts do not have to perform any EVA each time the shading system is to be deployed or retracted. The shading system will be placed on and deployed from the lunar surface. The shading system of the 25 kW thermal control system will be placed on the lunar surface and permanently established. Therefore, it is not as critical to have the shading system remotely deployed. Since the 10 kW and 25 kW thermal control systems differ mainly in the number of radiators available for heat rejection, the alternates developed are adaptable to both thermal control systems. For the 25 kW thermal control system, in the event that it has to be repacked and moved to another location, it will be advantageous to have it remotely activated so astronauts will be free for other important activities.

The deploy and retract devices are designed to be simple. Complex devices inherently have many more parts. Each part introduces an element of failure, and therefore, complex systems tend to be less reliable than simple ones. Alternates should minimize mass because of the enormous cost of transporting something from the earth to the moon. The volume occupied should be minimal because of the limited cargo capacity available in the lunar lander. Because of limited power supply the power required to deploy the shading system should be minimal.

27

Each shading device is paired with a support structure. This section describes the alternates. Also, the mass, power, and volume is calculated for each alternate. To make a comparison it is assumed that each support structure holds 5 shading devices. Appendix F contains detailed calculations of the mass, volume, and power of each alternative.

2.3.1 Folding Support Structure and Motion System. The Folding Support Structure stacks shading systems in a way that they overlap. To place the shading systems in operating position, the top section of the Rail Support Structure is rotated 180[°] (See Figure 14). The Folding Support Structure can be used with the Rigid Parabolic Reflector and Modified Parabolic Reflector.

The top section of the support structure is made of two rails. The shading systems are attached to the rails. The bottom section is identical to the top section. Rod crosssection dimensions can be determined through stress analysis. The rails can be assumed to be loaded cantilever beams supported at one end. The motion system provides a torque in order to place the shading systems in an operating position.

Because the mass of the Rigid Parabolic Reflector and Modified Parabolic Reflector are the same, the results are the same. The total mass of this alternative, which is the heaviest of all alternatives is 270.47 kg. Because of the high torque required rotate the top section the estimated power to deploy the alternatives is 24 W. Advantages of the Folding System are

1. Compared to other support structures, twice as many shading systems can be placed in one support structure.

Disadvantages of the design are

- 1. Of all alternate, this alternate requires the most power to deploy
- 2. The rails which account for more than half of the total masss make this

28

system heavy.

3. The stowage volume occupied is the highest of all alternates.

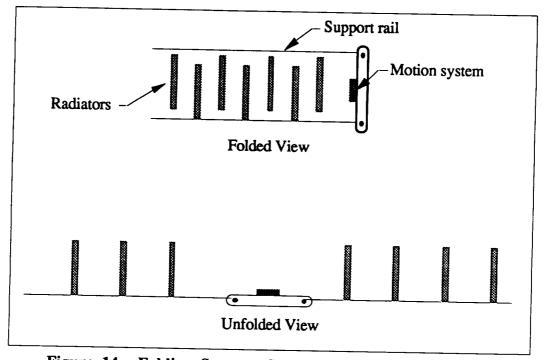


Figure 14. Folding Support Structure and Motion System

2.3.2 Rail Support Structure and Scissors Mechanism. In this alternative the shading devices lay side by side (see Figure 15). The shading devices are attached to a scissors mechanism which is used to place the shading devices in operating mode. As the scissors are extended a force is applied on the shading devices. The shading devices are separated as they slide along the rails. The shades open due to an inherent moment. To stow the shading devices the the scissors are retracted. As the scissors mechanism is retracted the shading panels come in contact and force each other to a vertical position. Shading devices that can be folded, such Winged Radiator and Modified Winged Radiator are appropriate for this system.

The support structure is a pair of rails. The rails bear the weight of shading devices

and serve as a means of moving the shading devices to the deployed position. Rollers or collars can be used. A drawback of using rollers is that grooves must be made in the rails. The grooves act as guide for the rollers. Using collars, the wear of the rail and collar occurs. If the wear is excess the structure of the rails will weaken, thus causing the rails to fail.

The total mass of the Winged Radiator and Folding Support 50.90 kg. To put it in operating position, the power required is 0.148 W. The stowed volume and deployed volume 4.2 m³ and 14.8 m³, respectively. For the Modified Winged Radiator, total mass is 47.34 kg and the power is 0.147 W. The deployed volume is 3.6 m^3 and the stowage volume is 12.24 m^3 .

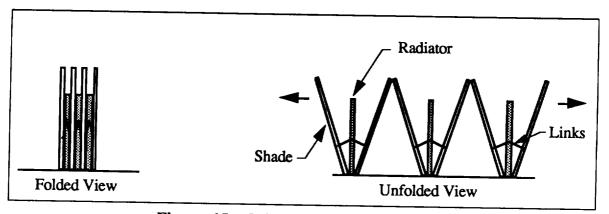


Figure 15. Winged Radiator System

The advantages of this design are

- The rails, which constitute the support structure, can be made lightweight
- 2. The entire assembly can be made very compact for stowing.

Disadvantages of the design are

1. The

2. The outside surface of the shade will be scored with repeated deploying and retracting.

Selection of Final Design Solution

In order to select the best alternate for preliminary design, the solutions were compared by means of a decision matrix (see Appendix G). The decision matrix contained evaluation criteria that were given weighting factors according to their relative importance as design requirements. Ratings were assigned to each alternate according to how well they fulfilled the design considerations. The rating was done in a scale from zero to ten, where zero corresponds to an absolutely useless solution and ten corresponds to an ideal solution [5]. Overall values for each alternate were calculated from the multiplication of the weighting factor and the alternate rating. The best solutions were those with the highest overall values. The evaluation criteria result from the design requirements and consist of the following factors:

1. <u>Safety</u>. The shading system should be safe during manual and automatic deploymend and during operation. The design should also be safe when subjected to any vibrations during operation.

2. <u>Total mass</u>. The shading system should minimize the total mass due to the energy cost involved in transporting mass from the earth to the Moon..

3. <u>Stowed volume</u>. The shading system should also minimize the stowed volume due to the space constraints of the spacecraft.

4. <u>Thermal performance</u>. A good thermal performance is quantified with the effective heat sink temperature. The lower the effective heat sink temperature, the better the

31

thermal performance since a lower radiator area will be required for the required heat loads.

5. <u>Power consumption</u>. The deployment operation should minimize power consumption.

6. <u>Reliability</u>. Reliability qualitatively describes the many factors, such as the possibility of failure and the possibility of performing within design parameters.

7. Ease of maintenance. Due to the constraints that exist in the lunar environment and the limited movement of an astronaut in his spacesuit, the system should be designed for ease of maintenance by its general geometry (providing accesibility to areas that require maintenance) or by incorporating features that will help in performing the mainenance operation.

The next section will present the preliminary design of the best alternate.

III. DESCRIPTION OF FINAL DESIGN

This section presents the a description of the final design solution, which combines the Modified Shading Device with the Rail Support Structure and Scissors Mechanism. A thermal performance analysis was performed to determine the ratio of the dimensions and angles of the shade relative to the radiator. In addition, an estimate of the power required to deploy the shading system, the volume occupied during stowage and when the system is deployed is provided. Finally, a breakdown of the total mass is provided.

3.1 Thermal Performance Analysis

One disadvantage of the modified winged radiator is that, although the shades could block albedo and surface infrared radiation away from the radiator, direct solar radiation will be reflected from the shade directly into the radiator. The amount of reflected solar radiation will vary with the shade length (L_s), the angle (θ) between the shade and the radiator, and the shade surface properties. The reflected radiation will decrease with decreasing shade surface reflectivity and decreasing shade length. However, the radiation from the lunar surface to the radiator will increase with decreaseng shade length when the shade does not completely block the radiator view to the lunar surface. Also, for a given length and surface property, the reflected radiation will decrease with increasing θ .

Optimum combinations of L_s , θ , and shade properties were obtained by performing

a thermal performance analysis on the shading system through the variation of θ and the length of the shade (in non-dimensional terms as the ratio,R, of the length of the radiator over the length of the shade). In addition, two different cases of shade properties were varied: case 1 with a shade solar absorptivity of 0.9 and case 2 with a solar absorptivity of 0.14. Making the absorptivity high (with a corresponding decrease in reflectivity) will decrease the direct solar radiation reflected from the shade and directed to the radiator but will increase the infrared radiation emission into the radiator due to the increased shade temperature. On the other hand, making the absorptivity low (with a corresponding increase the infrared radiation from the shade.

The analysis (see Appendix H) was done by performing an energy balance on the radiator and shade. All possible radiation components (direct solar radiation and reflection and direct emission from the moon surface and shade) incident on the radiator were considered. Some of the view factors were approximated, in some cases by considering the moon surface as a finite plate of an area of 500 by 400 meters [9], in other cases by considering the shade and the radiator as infinite long plates. Other assumptions made on the analysis were,

1. All the surfaces were *diffuse* surfaces (emit and reflect diffusively). In reality, it will be preferred to make the surfaces *specular*, so that reflection and/or emission will depend on direction. A specular surface will make it possible to reduce the radiation incident on the radiator as opposed to a diffuse surface, which will emit or reflect the same in all directions. Assuming that all the surfaces are diffuse will give results for a worse case and it will be reasonable to assume that the properties of a specular surface could be varied in order to reduce the radiation incident on the radiator.

2. The radiator temperature is constant at 270K and the lunar surface is at 384K

34

3. The analysis does not take into account lunar dust accumulation, which will i ncrease the absorptivity of the surfaces.

4. The shade emissivity is 0.05.

Some results obtained are presented in Table 2. The variables were varied by considering cases 1 and 2 separately and for each case R was varied for q ranging from 5 degrees to 85 degrees.

Angle	R	T _{sink} , Case 1	T _{sink} , Case 2
60	0.5	341 K	271 K
65	0.5	335 K	260 K
70	0.5	329 K	247 K
75	0.55	313 K	217 K

 Table 2

 Thermal Analysis Results for Different Parameters

The mass of the Modified Winged Radiator and Rail Support Structure depends on the aspect ratio and radiator to shade angle. An increase in aspect ratio increases the length of the shading device panels. Increasing the radiator to shade angle increases the width of the shading device. Therefore, a longer support structure is required. An increase in these parameters increases the total mass. An aspect ratio of 0.55 and radiator to shade angle of 75⁰ was used to do mass calculations.

Using equation X, the length of the shading device panels is calculated.

$$L_S = rL$$
 (3.1)
 $L_S = length of the shading panel$

r= aspect ratio

L= length of radiator

The length of the shading panel is 8.25 cm.

This shading panel length is used to calculate the mass of the Modified Winged Radiator. The mass of the Modified Winged Radiator, which is dependent on the thickness of the shading device, is calculated using Equation XX.

$m = rhLt\rho$	(3.2)
m = mass per shading device	
L = length of the shading device panel	
ρ = aspect ratio	
h = height of radiator	
t= thickness of the shading device material	

The dimensions of the radiator selected by the design team were 6 m x 0.02 m x 0.15 m. The length of the shading device is fixed by the dimension of the shading device. The independent parameters are the thickness of the shading device and the density.

Aluminum alloys are a common material used to make devices which are exposed to the lunar atmosphere. Aluminum alloys are easy to manufacuture and are readily available. Aluminum alloys are light relative steel. Therefore, the independent variable of the equation is the thickness of the shading device material.

The thickness of the shading device can be varied to obtain different values of the shading device mass. Using a thickness of 0.635 cm yields a mass of 17.6 kg. Because transportation costs are very high, the design team decided to minimize the thickness. The design team selected Kapton, which is an Aluminum alloy, of thickness 0.0127 cm. This thickness gives a mass of 0.352 kg.

The Kapton sheets are supported by a frame, which is made of aluminum rods.

Three rods are equally spaced at a distance of 3m. The rods bear the weight of the transverse rods and Kapton sheets. The sides of the cross-section are of length 1.98 mm (See Appendix I for calculations).

The shading device support rods are inserted in the holes of the shade panel support which are slightly angled. When in the closed position, the shading panels are at a slight angle. As a result, a moment is produced. This idea is analogous to a long slender rod which is standing vertically. If the rod is tilted slightly a moment about the point where the rod is in contact with the surface is produced. As a result, the rod to fall to the surface. When the shades are separated this inherent moment causes the shade panels to open.

The radiator support attaches supports the radiator. The radiator is put in a groove which is several centimeters deep and is insulated to minimize heat conduction between the mating surfaces. The walls of the groove keep the radiator from falling over if a force is applied to the top of radiator.

The radiator support is attached to collars which slide along the rail. To reduce the wear of he aluminum parts the collar can be coated. Most plastics can not be used in applications in the lunar extreme temperatures of 102 K to 384 K. Silicone Rubber of General Electric can be used in applications where temperatures range from 185 K to 519 K[10]. To reduce the wear of the coating a high hardness is desired. The wear percentage, in 200 deploy and retract cycles, of each collar and rail is calculated assuming no coating is used. A XX % of the collar and XX% of rail is removed.

As given in Figure 16 the rails can be folded into the transport package. The length of the rails are limited by the length of the transport package, which is 6 m. The the rails have a square cross-section of length 9.18 cm. The legs of the rail are 0.91 meters high and have a square cross-section length of 6.28 cm.

The scissors mechanism is made of links. The length of the scissors can be varied

37

(See Figure 16). Moving the handles towards each other will extend the mechanism, yielding the deployed position, conversely, pulling them away from each other will retract the mechanism. The radiators are attached to the scissors mechanism where the links come in contact.

The number of radiators required to reject 10 kW and 25 kW was calculated using the radiator area determined from the thermal analysis. is 389 m² for the 10 kW heat rejection system and 973 m² for the 25 kW. From the dimensions of radiator it was calculated that 433 and 1082 radiators are required for the 10 kW and 25 kW heat rejection system, respectively.

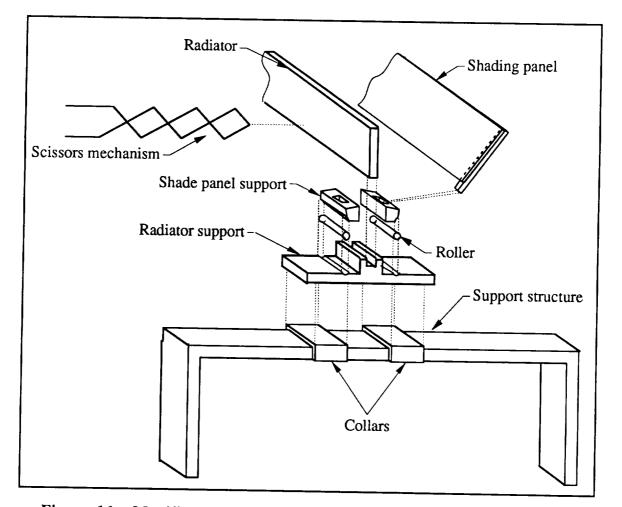


Figure 16. Modified Shading Device with the Rail Support Structure

Note: Blank page. Report continues on next page.

.

IV. CONCLUSIONS AND RECOMMENDATIONS

This section presents the conclusions of the project. Also, the design team makes recommendations for removing dust from the shading system.

4.1 Conclusions

The design team developed a preliminary design of the Modified Winged Radiator, Rail Support Structure, and deploy mechanism. The main objective of the design team was to develop alternates will reduce the radiation incident on the radiator. Because the planetary IR has the greatest effect on the performance of the radiator, the shading devices were designed to reduce the planetary IR incident on the radiator. The other objectives were to design a support structure for the shading system and a means of the deploying the system, and conduct a thermal performance. The device light by using sheets of Kapton attached to aluminum supports. The stowage volume of the shading device was made small by allowing the shading device panels to be closed prior to storing. Attaching the shading device panels to a support mounted on rollers will allow the panels to be closed. Finally, the power required to deploy this alternate is low.

From the thermal performance, the dimension of the shading device was calculated.

In developing the alternates for the shading device, support structure, and

deploying mechanism, the design team did not consider the problem of dust accumulation. It was assumed that the shading system had a dust control mechanism.

4.1 Recommendations for Dust Control

Most of the moon's surface is covered with regolith (small particulate matter), a large percentage of which is composed of lunar soil. Particle size of the lunar soil ranges from 45 to 100 micrometers in diameter, which is similar in size to the silty sands on earth. An example is sand along a coast. Many particles though, are much smaller than silty sand. The particles are generally angular in shape with sharp edges and have a low electrical conductivity and dielectric loss [11]. These characteristics allow lunar dust to accumulate and keep electrical charge for long periods of time. The sharp edges serve to concentrate charge at a point to create high charge densities which result in strong electrical dipoles. The electrical dipoles enable the dust particles to adhere to a variety of surfaces.

With a rarefied atmosphere and a gravity that is 1/6 the gravity of the earth's gravity, not much effort is necessary to make dust fly great distances. Dust therefore can settle on surfaces far away from where the dust was originally settled. There is evidence to show that dust can be set into motion by the passage of the boundary between day and night on the lunar surface. The proposed theory is that the steep ultraviolet flux gradient across the day night boundary may be responsible for creating electrostatically supported clouds of dust that follow the moving boundary. On the Apollo missions, dust coatings reduced visibility through helmet visors and camera lenses, and dust found its way into moving parts [11].

It is important that measures be taken to reduce dust accumulation on the shading devices. The optical performance of the shades will be reduced if dust is allowed to

41

accumulate on them. Also, if dust is allowed to get into joints, such as the joints on the shade deploying mechanisms, it will create a grinding powder with the dry lubricant in the joint and severely reduce the life of the joint.

The next section discusses various alternates for removing or preventing dust from adhering to critical surfaces such as the shade surfaces and joint surfaces.

4.1.1 Shaking Mechanism. In this alternate, a device for producing high frequency low amplitude vibration is rigidly attached to the radiator/shade support structure. The surface that will be protected must be tilted at a shallow angle. The direction of the tilt depends on the radiator/shade geometry, but must direct loosened dust towards an edge or location from which it can be removed later, or allowed to fall to the lunar surface.

With sufficiently strong vibration, the attractive force between the dust and surface can be overcome. The dust particles alternately lose contact with the surface then regain contact. Each time the particles are loose and set into motion by vibration, they will move alternately in different directions, but the resultant direction will be down the sloped surface. All shade designs but the Shading Blinds can benefit from the Shaking Mechanism because the optical surfaces are inclined. It may be advantageous to vibrate the system at its resonant frequency or at an integral multiple of that frequency so that the maximum shaking effect can be obtained from the Shaking Mechanism. It is important to ensure that the amplitude of vibration delivered by the Shaking Mechanism at the resonant frequency be small so that the radiator shading system does not vibrate hard enough to be damaged.

A suitable energy source for the system is the sun via solar cells. The intervals between between dust removal times by the device will be dictated by the rate at which dust

42

accumulates, and can be set by a digital timer. Advantages of the Shaking Mechanism are

- 1. The alternate can be adapted to a wide variety of shade designs which have a support structure capable of transmitting vibration.
- The design does not require a replenishable source of energy, such as a battery. The sun provides enough energy to drive a small low voltage motor with an eccentric weight or to drive a transducer.

Disadvantages of the Shaking Mechanism are

- 1. The system will have a low reliability because of numerous mechanical parts.
- The low amplitude vibration means that one device will have to be placed one each radiator/shading system. This will increase the mass of each radiator/shading system.

4.1.2 Application of Removable Transparent Layers. This alternate makes use of an idea already in worldwide use. The surface of the shade is covered with several very thin layers of material transparent to both visible and infrared radiation (see Figure 17). Dust is allowed to collect on the top layer and is intermittently wiped off. When the surface is scratched and cannot be used, the top layer is pulled off, exposing a new untouched protective layer. This idea has been in use in the Formula One racing circuit and by motorcycle dirt bike riders for some period of time. Their helmet visors have several layers of optically clear material. The driver or rider pulls off the top layer when it becomes difficult to see through it. Two advantages of the Transparent Layers are

- 1. Not much mass is added to the existing radiator/shading system.
- 2. The protective layers can be applied to a wide variety of shade geometries. Also, the pull tabs can be designed for an astronaut's

gloved hand.

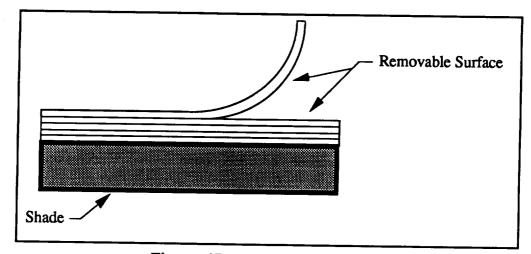


Figure 17. Removable Layers

Disadvantages of the Transparent Layers found by the design team are

- 1. The life of the protective layers is finite. Once they are depleted, new ones cannot be applied to the surface.
- 2. Also, the astronaut has to wipe or remove the layers from the shade on a regular basis and at intervals determined by the rate of dust accumulation. Therefore, the layers constitute a maintenance intensive design. If the design of the thermal control system requires the use of several radiators, then a lot of unnecessary work exists for the astronauts.
- 3. Surface thermal properrties are wavelength dependent. Depending on the material used, it will be more to absorptive to one range than the other. Therefore, the material will experience a temperature rise that may affect the radiator performance.
- 3.3 Gas Jets.

Pressurized carbon dioxide gas can be used to blow dust off the shade surface (see Figure 18). The carbon dioxide gas can be stored in a portable thermally insulated tank which is kept inside the lunar habitat to prevent the gas from solidifying during the cold lunar night and from developing dangerous pressure levels in the tank during the hot lunar day. Carbon dioxide gas may be an ideal propellant. It is produced by human beings and will have to be removed by the habitat air management system. The gas can be stored by chemical means (for example it can be absorbed by activated charcoal) and when enough gas has been stored, the chemical storing process is reversed to allow it to be captured in an appropriate container. The good points of the Gas Jets are

- The main advantage of this design is that carbon dioxide gas is a byproduct of human metabolism, and therefore it does not have to be brought from earth in large quantities for future use.
- 2. The device can be made portable.

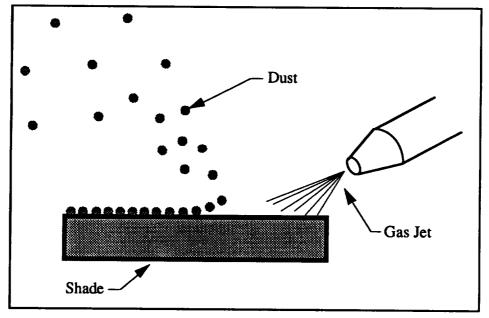


Figure 18. Gas Jets

Disadvantages of the Gas Jets are

- The rate of carbon dioxide accumulation and the process of storing and removing the gas may be so slow and inefficient that the device will be impractical.
- 2. Carbon dioxide released from the tank will contaminate the lunar atmosphere [6].

3.4 Explosive Inflation of a Balloon

The device in this alternate is a balloon or bladder made of a material having a high tensile strength. The material can be transmissive or it can form the reflective coating for the shade. The balloon is made so that when inflated, one end rises higher than the other, about 2 or 3 millimeters. The design works by rapidly (almost explosively) filling the balloon with a suitable gas so the accumulated dust on its surface is hurled far enough away from the shade (see Figure 19).

Two advantages the Explosive Inflation of a Balloon found are

- 1. The gas used to inflate the balloon is recoverable so it may be used repeatedly.
- The balloon can be used once each time to remove most of the accumulated dust, and therefore is not continuously exposed to any stressful situation that may shorten its service life.

In analyzing the Explosive Inflation of a Balloon the following disadvantages were found

1. If the balloon ruptures, the shade will be rendered inoperable, and this is the most serious flaw of the design.

- 2. The explosive inflation may transmit damaging shocks to the rest of the radiator/shade structure
- 3. The balloon surface may not be smooth so it may be difficult to predict the direction of the reflected rays.

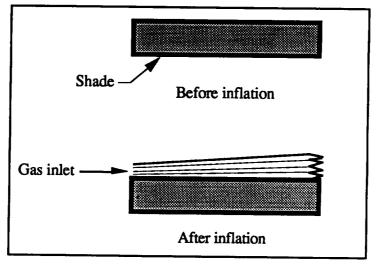


Figure 19. Balloon Mechanism

3.5 Dust Blowing Device.

In this alternate, dust is fed into a hopper that in turn delivers the dust to a rotating impeller. The impeller accelerates the dust to a velocity which is given by:

 $V = r\omega$

where: V = velocity of the dust particle as it leaves the impeller

 $\mathbf{r} = \mathbf{radius}$ of the impeller

 ω = angular velocity of the impeller.

The rapidly moving dust particles can be aimed at the stationary particles on the shade to hit them off the shade(see Figure 20). Advantages of the Dust Blowing Device are

1. There is a plentiful supply of dust on the moon.

2. Operating the device is simple.

3. The device can be made very light and portable.

4. Operation for extended periods is possible by connecting it to a solar cell

array.

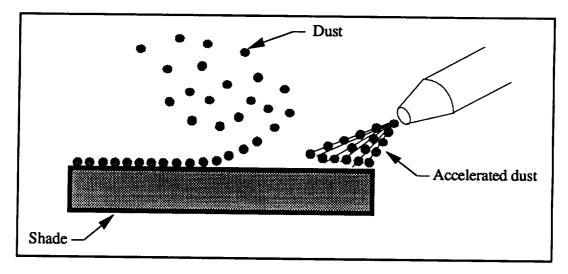


Figure 20. Dust Blowing Device

Disadvantages of the Dust Blowing Device are

- 1. The accelerated dust particles will scratch and score the shade surface.
- 2. The dust particles will wear out the rotating parts in the motor/impeller system.
- 3. The flying dust will cover other shades or devices in the vicinity of the operating device.
- 4. Large particles accidentally dropped down the hopper will destroy the rapidly rotating impeller.
- 5. A small portable system cannot operate for long periods of time.

4.2 Recommendations for Future Work

From the preliminary designs, the design team makes the following recommendations for future work. First, it is possible that the thermal performance can be improved by serrating the surfaces of the shading devices. Therefore, it is recommended that thermal analysis and testing be performed. The desgin team incorporated the scissors mechanism to deploy the shading devices. The rails of the support structure can be folded into the transport package. A device to deploy the rails will be necessary to deploy the rails. A stress analysis of the scissor's mechanism will determine the cross-sectional area of the links comprising the scissor's mechanism.

References

- The World Book Encyclopedia, <u>N O</u>, Volume 14, World Book Inc., Scott Fetzer Co., Chicago, 1986, pp. 25.
- M. K. Ewert, P. A. Petete, J. Dzenitis, "Active Thermal Control Systems for Lunar and Martian Exploration," <u>SAE Technical Paper Series</u>, 20th intercity conference on Environmental Systems, Williamsburg, Virginia, July 9-12, 1990
- John W. Lucas. <u>Thermal Characteristics of the Moon</u>, (Cambridge, Massachusetts: MIT Press, 1972).
- Michael K. Ewert, "<u>Design and Application of a Lunar Radiator Parabolic Shade.</u>" NASA, Lyndon B Johnson Space Center, Houston, Texas, November 9, 1990
- G. Pahl and W. Beitz, <u>Engineering Design. a Systematic Approach</u>, (London: Springer Verlag, 1988)
- 6. Sheldahl Corporation, "Thermal Control Material and Metalized Films," brochure (Northfield, Mn: Sheldahl Corporation, 1990).
- 7. 7.F. P. Incropera and D. P. De Witt, Fundamentals of Heat and Mass Transfer,

edition # 3 (New York: John Wiley & Sons, 1990).

- 8. D. Malacara, <u>Geometrical and Instrumental Optics</u>, (New York: Academic Press, Inc., 1988).
- Michael K. Ewert, Craig S. Clark, "Analysis and Conceptual Design of a Lunar Radiator Parabolic Shade", presented at the 26th Intersociety Energy Conversion Conference, Boston, Massachussetts, August 5-9, 1991
- Brady and Clauser, <u>Materials Handbook</u>, 12th edition, (New York: McGraw-Hill Book Co., 1980).
- G. Heiken, D. Vaniman, B. Lehnert, <u>Dust-A Major Environmental Hazard on the</u> <u>Earth's Moon</u>, LA-UR-90-3705, (Los Alamos NM: Lost Alamos National Laboratory), 5 November 1990.

AppEndix A
Comparison of different conducting materials
The heat transfer rate through a material
is given by:

$$Q = -KA \stackrel{\text{off}}{=} for one dimensional
Steady state conduction
is a plane wall with
no heat generation
and constant thermal
conductivity []].
Where $Q = \text{that transfer rate (w)}$
 $K = \text{Thermal Conductivity (w/m.K)}$
 $A = \text{Area of wall normal to direction}$
 $of heat transfer.$
 $T = \text{Absolute temperature (K)}$
 $X = \text{Thickness of the wall.}$
For a plane wall with steady state conduction;
 $Q = -KA \stackrel{\Delta T}{\Delta X}$; Solving for A
 $A = - \frac{Q}{K\Delta X} = - \frac{Q(XI - X_2)}{K(TI - T2)}$
If $Q = IW$, $\Delta T = IK$, $\Delta X = Im$, then$$

For lunar regulith with
$$K = 0.0021 \text{ W/mK}$$
,
 $A = -\frac{(1 \text{ W})(1 \text{ m})}{(0.0021 \text{ W/mK})(-1 \text{ K})} = 476.2 \text{ m}^2$
For Cotton, $K = 0.06 \text{ W/m.K}$
 $\therefore A = 16.7 \text{ m}^2$
Similarly;
 $A_{\text{copper}} = 0.0025 \text{ m}^2 = 25 \text{ cm}^2$
 $A_{\text{silver}} = 0.0023 \text{ m}^2 = 23 \text{ cm}^2$
 $A_{\text{silver}} = 0.00023 \text{ m}^2 = 23 \text{ cm}^2$
 $A_{\text{bismond}} = 0.00044 \text{ m}^2 = 4.4 \text{ cm}^2$
 $K = 300 \text{ K}.$

Appendix B

Design Requirements

Demand/Wish	Requirements I. Functional	
D	1. Reduce the heat absorbed by the radiator	
D	2. Support the radiator and the shade	
D	3. Deploy the system	
D	4. Retract the system	
D	5. Store the system	
W	6. Control dust accumulation	
D	7. Attach radiator to shading device	
	II. Geometry	
D	1. Minimize stowed volume	
	III. Forces	
D	1. Minimize deploying forces for manual assembly	
D	2. System should withstand acceleration forces during takeoff and landing	
D	3. Isolate structure from damaging vibrations	
D	 Safety factor = 1.5. Yield stresses should be 1.5 times the maximum stresses of the system 	
	IV. Energy	
D	1. Two systems: 10 kW and 25 kW heat rejection capacity.	
D	2. Minimize power consumption of deploying and retracting mechanism, if automatic	
D	3. Shade should reduce the radiant energy incident on the radiator	

i

Design Requirements (Continued)

	V. Materials 1. 10 kW system should withstand 200 deploy/retract cycles	
D		
D	2. 25 kW system must have a 20 year life	
D	3. Resist deterioration caused by spectrum of solar and planetary radiation	
D	4. Should function in the range of temperatures on the moon: 102 K to 384 K	
w	5. Minimize adhesion of lunar dust to shade material	
	VI. Safety	
D	1. Safe during remote deployment and retraction	
D	2. Safe during extravehicular activity (EVA) deployment and retraction	
D	3. Structure must be stable under possible impacts and vibrations	
_	VII. Ergonomics	
D	1. Reasonable to operate, deploy, and retract for an astronaut (astronau has limited mobility)	
D	2. Components that need maintenance should be easily accessible	
D	3. Tools (if any) should be easily handled by astronauts.	
W	4. If possible, integrate tools into design of the structure	
	VIII. Assembly	
D	 If the 25 kW system cannot be made remotely deployable, it must be constructed by 2 crew members performing a maximum of 3 hours of EVA each 	
_D	2. The backup should require no more than 2 hours of EVA	
	IX. Transport	
D	1. Minimize mass of shade and support structure	

Design Requirements (Continued)

	X. Operation	
D	1. System should operate under severe thermal gradients	
D	2. System should perform its function at the lunar equator during midday	
D	3. Misalignment of \pm 5° from the equator should not affect the performance of the system	
	XI. Maintenance	
D	1. Service intervals are once every 5 years, for no more than 2 hours of EVA	
	XII. Reliability	
D	1. Incorporate redundant components or procedure where a failure will cause the system to perform at less than 50% of design capacity	

Appendix C

Material and Thermal Parameters [5]

Parameter	Value	
Radiator operating temperature	270 K	
Solar flux at lunar surface	1371 W/m ²	
Average albedo at lunar surface	0.07	
Lunar surface temperatures	102 K at night to 384 K during the day	
Lunar surface absorptivity	0.93	
Lunar surface emissivity	0.96	
Radiator fin efficiency	0.9	
Radiator emissivity	0.9	
Radiator solar absorptivity	0.23	
Shade material	aluminized polyimide	
Shade inner surface emissivity	0.05	
Shade IR reflectivity	0.95	
Shade solar reflectivity	0.86	
Moon's gravity	1/6 of earth's gravity	
Thermal system working fluid	Freon or ammonia	

APPENDIX D
Estimated Relative Thermal Retarmance Calculations.
Thermal performance calculations were done for
Shades at lunar milday when the sun in at ±1.53°
from the ecliptic.
Values were calculated using estimated values for
the view factors for the purpose of relative comparisons
between the chade systems. They are not meant to
be absolute values for each system.
I deneral Equations
X. Steady state temperature of the shade:
Qaborbed = Qout
X solar [F]Qistar + Xir[F]Qir = EOT 4
Where
Xir = absorptivity in solar spectral range

$$X = emissivity$$

 $[F]_x = View Factors.$

C. Assumptions;
1. Neglect-dust accumulation.
2. Specular reflectivity of shade in both IR
and solar spectral ranges.
3. Diffuse emissivities,
4. Shade is at ground level.
D. Q" Values;
1. Q" values;
1. Q" values;
2. Q" alued = (0.07)(1371W/m2) = 95.97W/m2
3. Q" @ Lunar midday

$$= ET T_{emisca}^{4}$$

 $= (0.9)(5.67X10^{8}W/m^{2}K^{4})(384K)^{4}$
 $= 1146.54W/m^{2}$
4. Q" radiator = ET T⁴
 $= (0.9)(5.67X10^{5}W/m^{2}K^{4})(384K)^{4}$
 $= 271.19W/m^{2}$
E. Radiator properties: $X sclar = 0.23(P sclar = 0.77)$
 $X_{IR} = 0.9$
Shade properties: $X sclar = 0.14(P sclar = 0.86)$
 $X_{IR} = 0.05(P sclar = 0.95)$

.

I
Parabolic Shading Device
A. View factors for shade:

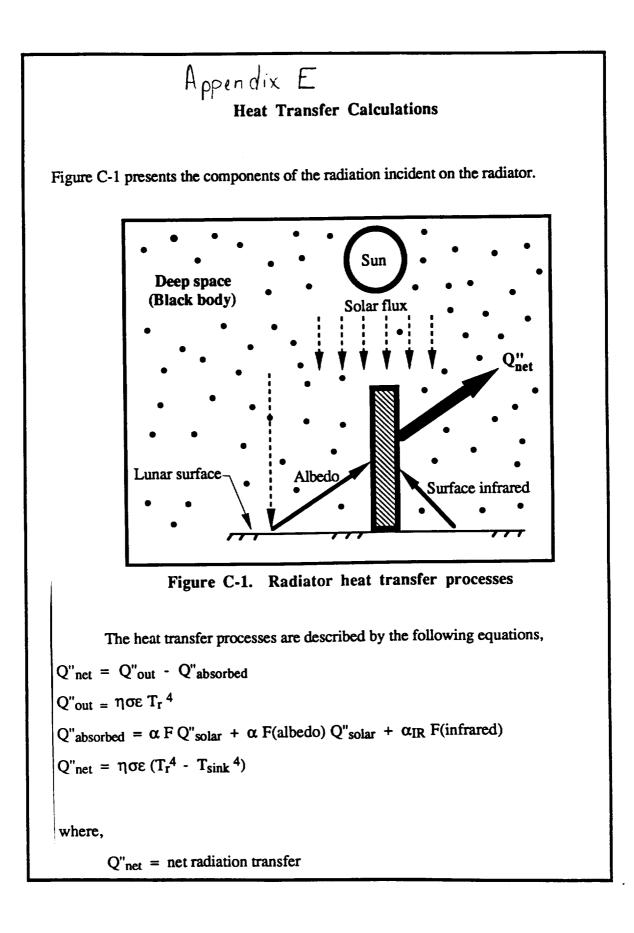
$$Fabedo = 0.8$$

 $Fridedie = 0.4$
 $Fridedie = 0.8$
 $Frontal = 0.8$
 $Frontal = 0.6$
 $Q_{cload}^{e} = X_{colar} [Fabodo Quobedo + Finicetisolar Q'_{solar} + Fridedier
 $I_{rad}] + X_{R} [Forthe Qe + Fradiatir Qeodiater]$
 $= 0.14 [(0.9)(95.97W/m^2) + (0.4)(137W/m^2) + (1)(137W/m^2)(0.77F Seil 1:53^{\circ})]$
 $+ 0.05 [(0.8)(1146.54W/m^2) + (0.06)(27H.9W/m)]$
 $Q_{slade}^{e} = (0.055)(475.94)^{4} = 145.47W/m^{2}$
B. View factors for vabiator
 $F_{abedo} = 0$
 $F_{sinetuc} = 0.153$
 $Fridestude = 0.75$
 $F_{sinetuc} = 0.71$
 $F_{slade risk = 0.01$$

$$\begin{aligned} & (x_{oder} [F_{etodeo} Q_{abbedo} + F_{abirect-scher} Q_{scher} + F_{rel-stude} f_{scher} stude. \\ & (Q_{scher} F_{aret-coher cluste}] + X_{IR} [F_{etorplace} Q_{IR} + F_{andec} Q_{stude} \\ & + F_{rel} rad Q_{radiater} f_{abode in} F_{robister}] \\ &= E_{0} T_{solk}^{-4} \\ \hline 023 [Sill 153 (1371 W/m^2) + (0.05) (0.80) (1371 W/m^2) (0.4)] \\ & + 0.9 [0.7 (14547 W/m^2) + (0.01) (271 \cdot 19W/m^2) (.95) (0.6) \\ &= 0.9 J T_{sink}^{-4} \\ \hline T_{sink} = 213 \cdot 93 K \\ \hline \\ \hline \\ \hline \\ \hline \\ Modified farabolic kellector \\ A. View factors for shade; \\ F_{aibedo} = 0.8 \\ F_{aibedo} = 0.8 \\ F_{rotating} = 0.4 \\ F_{ret rad} = 1.0 \\ F_{surface} = 0.8 \\ F_{radiatri} = 0.59 \\ \hline \\ X_{cdar} [F_{aibedo} Q_{abbedo} + F_{rbist} scher Q_{scher} + F_{ret rad} f_{ab} Q_{scher} Sill Sill \\ + X_{IR} [F_{urbac} Q_{surface}] + F_{radiatio} Q_{radiator}] = E_{0} T_{sude}^{-4} \\ \hline \end{aligned}$$

$$\begin{split} \overrightarrow{\mathbf{N}} & \ \text{L-Shaped Panels} \\ \overrightarrow{\mathbf{A}}. \quad \text{View facloxs for shade}: \\ & \ \textbf{factors for shade}: \\ & \ \textbf{factors for shade} = 0.7 \\ & \ \textbf{Factors for shade} = 0.7 \\ & \ \textbf{Fradicts} = 0.7 \\ & \ \textbf{Fradicts} = 0.5 \\ \hline \textbf{Xeolor}[\textbf{Feibedo & \textit{Collecto}} + \textbf{factor scien}(\textbf{Solu} + \textbf{Frit.rab}(Solu 1.53°)] \text{frad}(\textbf{Solur}) \\ & + \ \textbf{Xre}[\textbf{Feirface} & \ \textbf{Surface} + \textbf{Fradictor}(\textbf{Qradictor})] \\ & = \mathcal{E} \sigma T \textbf{Shade} \\ \hline \textbf{O.14} \begin{bmatrix} \textbf{O.74}(\textbf{95.}\textbf{9.7}\textbf{W/m^2}) + (\textbf{O.5})(\textbf{1371}\textbf{W/m^2}) + \textbf{I}(Sin 1.53)(\textbf{D.77}) \\ & \ \textbf{(1371}\textbf{W/m^2})] \\ & + O.05[\textbf{O.7}(1146.54 \textbf{W/m^2}) + 0.5(271.19 \textbf{W/m^2})] \\ & = 0.05(\sigma) T \textbf{Shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.05 \sigma T \textbf{T} \textbf{shade} \\ \hline \textbf{Q}^{\text{Stade}} & = 0.9 \\ \hline \textbf{Fabric f solar} & = 0.9 \\ \hline \textbf{Fabric f solar} & = 0.75 \\ \hline \textbf{From Sumface} & = 0 \\ \hline \textbf{Fshade} & = 0.75 \\ \hline \textbf{Fshade} & = 0.75 \\ \hline \textbf{Fshade} & = 0.4 \\ \hline \end{array}$$

$$\begin{aligned} & (\sin 1.53^{\circ}(1371^{\circ}/m^{2}) + \text{Fret.} \text{ and } \text{Furret-coder} \text{ from the Qlister}] \\ & + (XiR [Founde Qlishade + Founder and Qlindo Franchettic Stander in?] = EOT Find. \\ & 0.23[Sin(1.53^{\circ}(1371^{\circ}/m^{2}) + 0.3(0.4)(0.86)(1371^{\circ}/m^{2})] \\ & + 0.9[0.75(147.65^{\circ}/m^{2}) + 0.5(271.19^{\circ}/m^{2})(0.5)(0.95)] \\ & = 0.90\text{ Tsink.} \\ \hline \text{Tsink} = 249.771 \text{ K}] \\ \hline \text{UID} \qquad \text{Shading Bluids} \\ & (Xastar Folian Qlister + 1000 FQline = EVTSink) \\ & (Xastar Folian Qlister + 1000 FQline = EVTSink) \\ & (Xastar Folian Qlister + 1000 FQline = EVTSink) \\ & (Xastar Folian Qlister + 1000 FQline = EVTSink) \\ & (Xastar Folian Qlister + 1000 FQline = -0.71 Fradiator) (Aradiator) \\ & = Qlistade \\ & Fastar = 1 \\ & F(Surtate to stude) = 0.71 \\ & (Fradiator) = 0.55 \\ & (Qstude = 0.14(1)(1371^{\circ}/m^{2}) + (0.05)(0.72)(11460.54^{\circ}/m^{2}/m^{2})) \\ & + (0.5)(0.05)(271.19^{\circ}/m^{2}) \\ & = 238.85^{\circ}/m^{2} \end{aligned}$$



 $\begin{array}{l} Q"_{out} = radiation \ out \ of \ the \ radiator \\ Q"_{absorbed} = radiation \ into \ the \ radiator \\ T_r = radiator \ temperature \\ T_{sink}^{\ 4} = effective \ heat \ sink \ temperature \ (270K) \\ \eta = radiator \ fin \ efficiency \ (0.9) \\ \sigma = Steffan \ Boltzman's \ constant \ (5.67 * 10 \ ^8) \\ \varepsilon = radiator \ emissivity \ (0.9) \\ F = view \ factor \\ \alpha = solar \ absorptivity \ (0.23) \\ \alpha_{IR} = radiator \ absorptivity \ in \ the \ infrared \ (long \ wavelength) \ range \ (0.9) \\ albedo = .07 \end{array}$

I. Vertical Radiator

Considering the view factors for a vertical radiator, the fluxes incident on the radiator are [5]:

Solar flux = 37 W/m^2 Albedo radiation = 48 W/m^2 Surface infrared radiation = 592 W/m^2

A. Percentage (x) by which the infrared radiation has to be reduced to produce a net radiation transfer out of the radiator,

 $Q''_{out} = Q''_{absorbed}$ $\eta \sigma \epsilon T_r^4 = \alpha F Q''_{solar} + \alpha F(albedo) Q''_{solar} + \alpha IR F(infrared) (1 - x)$ 244.07 W/m² = 19.55 W/m² + 532.8 (1 - x)W/m² x = 57.9% B. Percentage (x) by which the solar radiation (albedo & direct solar radiation) has to be reduced to produce a net radiation transfer out of the radiator,

 $Q''_{out} = Q''_{absorbed}$ $\eta \sigma \epsilon T_r^4 = \alpha F Q''_{solar} (1 - x) + \alpha F(albedo) Q''_{solar} (1 - x) + \alpha IR F(infrared)$ $244.07 W/m^2 = 19.55 (1 - x) W/m^2 + 532.8 W/m^2$ $-288.73 W/m^2 = 19.55 (1 - x)$ x = 1,577% x > 100%

Therefore, reducing only the albedo and direct solar radiation will not result in a net radiation transfer out of the radiator.

C. Percentage (x) by which the infrared radiation has to be reduced if there is no albedo or direct solar radiation incident on the radiator.

 $Q''_{out} = Q''_{absorbed}$ $\eta \sigma \epsilon T_r^4 = \alpha IR F(infrared) (1 - x)$ $244.07 W/m^2 = 532.8 (1 - x)W/m^2$ x = 54%

II. Horizontal Radiator

The view factors for the albedo and infrared radiation are almost zero for a horizontal radiator. The only incident radiation to be considered is the solar flux (1371 W/m^2) [2].

Percentage (x) by which the solar radiation has to be reduced so that there is a net radiation transfer out of the radiator,

 $Q''_{out} = Q''_{absorbed}$ $\eta \sigma \epsilon T_r^4 = \alpha F Q''_{solar} (1 - x)$ $244.07 W/m^2 = 315.33 (1 - x) W/m^2$ x = 22.6%

Appendix F.
Mass, Volume, and Power Calculations
This Appendix presents detailed calculations of the
mass of each shading device and support structure.
Also, the stowage volume, deployed volume, and power
required to deploy each system is provided.
Assumptions common to all alternates:
1. The shading device is fitted to a radiator of
dimensions: 6m x 0.02 m x 0 15 m

$$0 \propto m$$

Radiator $f_{0.15m}$
The density of the radiator pn unit width is
 $P_{r} = 5 \frac{10}{M}$

Mass Calculations of Rigid Parabola Shading System
and Folding Support Structure
Parabolic Shading Device
and Folding Support Structure
Parabolic shating druce
Reduator
- mass of 5 radiators

$$m_r = Q_r A = 5 \frac{L_R}{M^2} \text{ for x 0.15 m}$$

 $m_r = 4.5 \frac{L_R}{M^2}$
 $m_r = 5 \times 4.5 \frac{L_R}{M^2} = 22.5 \frac{L_R}{M^2}$
- both mass of Kapton in 5 shates:
Acsume: shate geometry is a semicircle
 $r = 0.35 m$
L= 6 m
 $m_s = Q_K PL$
 $P = \pi r$

$$M_{s} = 0.1814 \frac{L_{s}}{M^{2}} \times T \times 0.35 \text{ m} \times 6 \text{ m}$$

$$M_{s} = 1.47 \text{ kg}$$

$$m_{s_{T}} = 5 \times 1.197 = 5.98 \text{ kg}$$

$$- \text{ total mass of support rods}$$

$$J_{support rods}$$

$$J_{support rods}$$

$$J_{support rods are baded cantilever beams}$$

$$M_{s} = \frac{1.5 \times q \times L^{4}}{8 \times E_{W} \times T}$$

$$M_{schanics of Midsur}$$

$$g = \frac{M_{s} \times q}{L}$$

$$I = \frac{1}{12} b^{4}$$

$$b = \left[\frac{12 \times 1.5 \times L^{3} \times m_{s} \times q}{8 \times E_{Re} \times \delta_{max}}\right]^{\frac{1}{2}}$$

$$b = \left[\frac{12 \times 1.5 \times (0.550)^{3} m^{3} \times 1.477 \text{ kg} \times 9.81 \text{ m}}{8 \times 72 \times 10^{9} \frac{11}{\text{m}^{2}} \times 0.001 \text{ m}}\right]^{\frac{1}{2}}$$

$$b = 0.0157 \text{ m}$$

$$b = 1.57 \text{ cm}$$

$$m_{sR} = b^{2} \times L \times \rho_{RI} = (.0157)^{2} \text{ m}^{2} \times b \text{ m} \times 2800 \frac{1}{\text{M}^{3}}$$

$$m_{SR} = 0.379$$
each shale has 6 support rods and there are 5 shales

$$m_{SR_{T}} = 6 \times 5 \times 0.379 \text{ kg}$$

$$m_{SR_{T}} = 11.38 \frac{1}{38}$$

$$b = 1.38 \text{ kg} + 22.5 \text{ kg} + 5.98 \text{ kg}$$

$$= 39.86 \text{ kg}$$

$$\approx 40 \frac{1}{8}$$

$$\int \frac{1}{14} \int \frac{1}{5max} = \frac{1}{5max} \int \frac{1}{5} \frac{1}{5max} = \frac{1}{5} \frac{1}{5max} = \frac{1}{5} \frac{1$$

-mass of column The column joins the top section and bottom section of the support structure. It is assumed the weight of the shading systems is concentrated. - Rail WR COLUMN WR = weight of the rail W = weight of the shading systems Because each rail supports half of the weight of the shading system the moment caused by the weight on the left rail is equal and opposite to the moment caused by theother rail. As a result, the column is under compression. L= 0.40 m 6= 2.61 m

To determine the minimum value of h which will prevent
the column from buckling, Euler's equation is used

$$P_{CR} = \frac{\pi^{2} E \Gamma}{Le^{2}}$$

$$\frac{[Robert C. Juvinal]}{[Fundamentals of Machine]}$$

$$P_{CR} = load which causes buckling
$$\Gamma = moment of inertia of the section with respect to
the buckling - bending axis. This is the smallest
$$\Gamma = bould any axis.$$

$$Le = equivalent length of the column$$

$$Assumptions:$$

$$I. perfectly straight column$$

$$Z. bod precisely axial
$$S. stress in linear range$$

$$Aralysis:$$

$$P_{CR} = sf \times m \times g$$

$$= 1.5 \times (40 \text{ kg} + 112 \text{ kg}) \times 9.81 \text{ m/s}^{2}$$

$$P_{CR} = 2236.7 \text{ N}$$$$$$$$

Le = L
The smallest value of I occurs about the x-x axis.

$$x = \frac{y}{y} + \frac{P_{eR}}{P_{eR}} - x$$

$$R_{ewriting} \text{ Euler's Equation}$$

$$I = \frac{P_{eR} L_{e}^{2}}{\Pi = \frac{1}{12}} bh^{3}$$

$$h = \left[\frac{12}{M} \times \frac{P_{eR}}{R} \times \frac{L_{e}^{2}}{M}\right]^{\frac{y}{3}} = \left[\frac{12}{\frac{0.61}{M}} \times \frac{2236.7 \times (0.40)^{2} \text{ m}^{2}}{\pi^{2} \times 72 \times 10^{4} \text{ N/m}^{2}}\right]^{\frac{y}{3}}$$

$$h = 2.15 \text{ mm}$$

$$M_{column} = P_{el} V = 2300 \frac{k_{a}}{M^{3}} \times 0.00215 \text{ m} \times 0.61 \text{ m} \times 0.40 \text{ m}$$

$$M_{column} = \frac{1.47 \text{ kg}}{M}$$
Total Mass of the Rigid Parabola Shading System and Folding Support 40 kg + 1 kg + 4 kg + 224 kg + 147 kg
$$= 270.47 \text{ kg}$$

Estimated Power Required to Deploy the Rigid Porabola
Shading System and Folding Support
Assume: - weight of the shade system is a concentrated
load. Each rail carries half of the weight of the
Rail Shade. Lt T,
$$\omega$$
 Li = 3.67 m
 $(56.27 + 20)$ kg × 1.635 m/s²
T = torque that must be provided to
rotate the rail
 ω = angular speed
 $Z_1 M_0 = 76.27$ kg × 1.635 m/s² × 1.94 m × Z
T = 458.90 N·m
 $\omega = \frac{T}{\omega \times cs} = 0.0523$
 \therefore the power is
 $P_2 T \omega = 458.90$ N·m × 0.0523 rod/s
 $P = 24.0$ W

The perimeter of the Modified Parabolic Reflector is assumed to be a semicircle. The radius is 0.35 m, which is equal to the radius of the Parabolic Reflector. Therefore, the mass, volume, and power calculations of Parabolic Shading System apply to the Modified Parabolic Reflector.

,

,

- mass of support ists
0.2121 m Support ists
Assume: - support rods are cantilever beams
- load of shade is evenly distributed
If I I I I I B
Smax =
$$\frac{1.5 \times g \times L^4}{3 \times E_{AL} \times I}$$

 $\int_{B} = \frac{m_s \times g}{2 L}$
 $I = \frac{1}{12} b^4$
 $b = \left[\frac{12 \times 1.5 \times L^3 \times m_s \times g}{3 \times E_{AL} \times Smax}\right]^{\frac{1}{4}}$
 $b = \left[\frac{12 \times 1.5 \times (0.2121)^3 m^3 \times 0.4618 k_3 \times 9.31 m/s^2}{8 \times 72 \times 10^9 \frac{11}{m^2} \times 0.001 m}\right]^{\frac{1}{4}}$

mass for 1 rod

$$m_r = \rho_r V = 2300 \frac{k_0}{m_3} (0.05 m)^2 (0.2121 m)$$

 $m_r = 0.0159 \text{ sg}$
thure are a total of 30 support rats
 $m_{rT} = 30 \times 0.0154 \text{ J}_1$
 $m_{rT} = 0.462 \text{ J}_2$
total mass of the shading device and ratiator.
2.31 kg + 22.5 kg + 0.462 kg
 $= 25.27 \text{ J}_2$
Miscellaneus Masses:
rollors : 9 kg
joints : 1 kg

- mass of the legs
Assume
- effect of shading system and rail weight can be
replaced by an equivalent bad and moment.
- load of shade system is concentrated.

$$I_{L} = 1.7 \text{ m}$$

 $W = \text{weight of shading system and rail}$
 $= (12.64 + 5.35/2) \text{ by x 981 m/s^2}$
 $W = 75.12 \text{ N}$
 $P_{ce} = (25.27 + 5.35) \text{ bg x 9.81 m/s^2}$
 $P_{ce} = 37.55 \text{ N}$
 $M = W \cdot \frac{1}{2} = 127.66 \text{ Nm}$
 $b = (1.5 \times 37.55 \text{ N} \times (0.91)^2 \text{ m}^2 \times 12) \frac{1}{10} \frac{1}{10}$
 $b = 0.00529 \text{ m}$ $\frac{1}{2} \text{ minimum length due to compression}$
 $b = 5.30 \text{ mm}$

cross-section due to bending
Assume: leg is supported at one end

$$\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\end{array} \\
\end{array} \\
\begin{array}{c}
\end{array}{cross-section due to bending}\\
\end{array} \\
\end{array} \\
\end{array} \\
\end{array} \\
\end{array} \\
\end{array} \\$$

cross-section due to bending \\
\end{array} \\
\end{array} \\
\end{array} \\

cross-section due to bending \\
\end{array} \\

cross-section due to bending \\

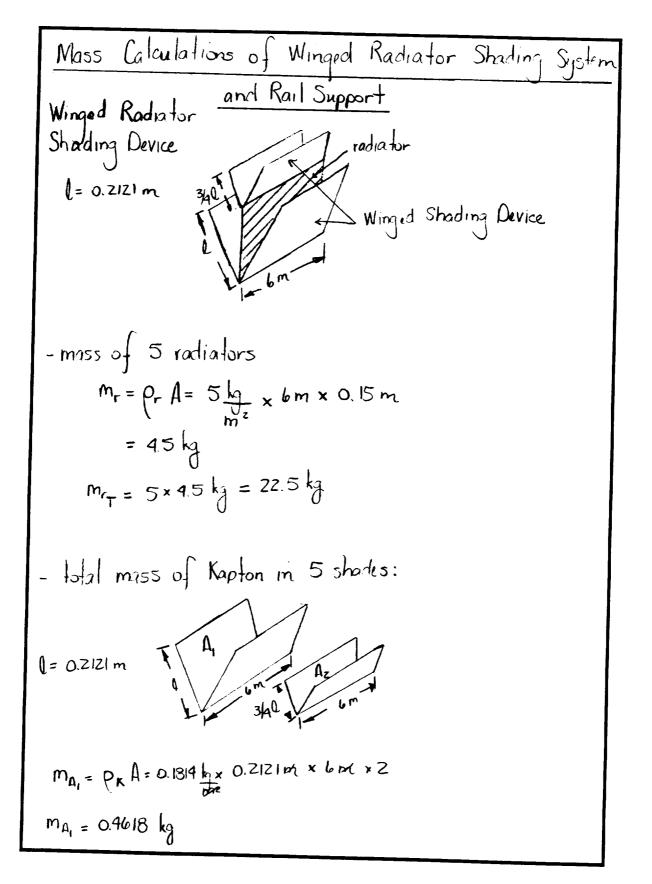
cross-section due to bending \\

cross-section due to bending \\

cross-section due to bendind \\

The energy is doply the system is:

$$E = F.d = 4.42$$
 N× Im = 8.84 J
Assume it is performed in 60 seconds.
 $P = \frac{E}{t} = \frac{8.34}{60} \frac{J}{5} = 0.1473 \frac{W}{100}$



$$m_{n_{z}} = \rho_{x} A = 0.1814 \frac{k_{g}}{m^{2}} \times \frac{3}{4} \times 0.2121 m \times 6 m \times 2m$$

$$m_{a_{z}} = 0.3463 k_{g}$$

$$m_{s_{T}} = 5 \times (0.4613 \pm 0.3463 k_{g})$$

$$m_{s_{T}} = 4.041 k_{g}$$

$$- 100055 \text{ of support rods} \qquad \text{Support Rods} \qquad \text{Support Rods}$$

$$0 \qquad \qquad 1000 \text{ m}^{2} \text{$$

$$\begin{split} & \prod = \frac{1}{12} b^{4} \\ b &= \left[\frac{12 \times 1.5 \times L^{3} \times m_{5} \times q}{8 \times E_{nL} \times 5_{max}} \right]^{\frac{1}{4}} \\ b &= \left[\frac{12 \times 1.5 \times (0.2121)^{3} m^{3} \times 0.4018/2 \times 9.81 m/s^{2}}{3 \times 72 \times 10^{9} N/m^{2} \times 0.01 m} \right]^{\frac{1}{4}} \\ b &= 0.0051 m \\ b &= 0.0051 m \\ b &= 5.1 mm \\ \end{split}$$

$$\begin{split} mass of rods for 5 shades : \\ m_{r_{0}} &= \rho_{0} V = 2800 \frac{h_{3}}{M_{3}} \times (0.0051)^{3} m^{2} \times 30 \\ m_{r_{0}} &= 0.462 \frac{h_{3}}{M} \\ \hline & \left[\frac{12 \times 1.5 \times (0.151)^{3} m^{3} \times 0.3463 h_{3} \times 9.81 m/s^{2}}{8 \times 72 \times 10^{9} N/m^{2} \times 0.001 m} \right]^{\frac{1}{4}} \\ b &= 0.0038m \\ b &= 0.0038m \\ b &= 3.8 mm \\ mass p_{2} : 124 \\ m_{r_{2}} &= \rho_{0} V = 2800 \frac{h_{3}}{m^{3}} \times (0.0038m)^{2} (0.151 m) = 0.00643k \\ \end{split}$$

$$m_{r_{e}} = 30 \times 0.00643 \text{ kg}$$

$$m_{r_{e}} = 0.1923 \text{ kg}$$

$$m_{sr_{T}} = (0.462 + 0.1923) \text{ kg}$$

$$m_{sr_{T}} = 0.654 \text{ kg}$$

$$\text{total mass of the shading device and reductor:}$$

$$4.041 \text{ kg} + 22.5 \text{ kg} + 0.654 \text{ kg} = 27.20 \text{ kg}$$

$$\text{Aliscellanious Alosses:}$$

$$\text{rollers: 4 kg}$$

$$\text{joints: 2 kg}$$

.

ORIGINAL PARE 13 OF POOR QUALITY

- mass of support structure The uidth of this shading divice when stowed and deployed is the equal to the Winged Shading Device. uidth when being transported: W1= .20 m uidth when deployed: Wd= 1.7 m Therefore the length of the rails are 1.7m Assumptions in the remaining calculations are the same as for the Modified Winged Radiator - total mass of the rails $\int P = 13.60 \text{ kg} \times 9.81 \text{ m/s}^2 = 133.40 \text{ N}$ Smax IIII 11 Smax 4 Icm $b = \left[\frac{1.5 \times 12 \times 133.40 \text{ N} \times (1.7)^3 m^3}{0.01 \text{ m} \times 48 \times 72 \times 10^9 \text{ N/m^2}} \right] \frac{1}{4}$ b=0.0242m b= 2.42 cm

mass per rail

$$m_{rail} = P_{a1}V = 2800 \frac{l_{a}}{M^{3}} \times (0.0242)^{2} m^{2} \times 1.7 = 2.79 lg$$

$$= \frac{1}{6} l_{a1} l_{a1} mass$$

$$m_{a2.1} = 2 \times 2.79 = 5.58 kg$$

$$= mass of the legs$$

$$dimensions of the legs are determined by the moment.$$

$$T_{ra} P_{ra}$$

$$P_{ra} = \left[\frac{5.58}{8} + \frac{27.716}{8}\right] l_{g} \times 9.81 m/s^{2}$$

$$P_{cr} = 40.19 N$$

$$M = \left[\frac{5.58}{2} + \frac{27.196}{2}\right] \times 9.81 m/s^{2} \times 0.85 m$$

$$M = 136.65 N m$$
Under compression the minimum dimensions of the cross - section is calculated usim Euler's equation.
$$b = \left[\frac{15 \times 40.19 N \times (0.91) m^{2} \times 12}{\pi^{2} \times 72 \times 10^{9} N/m^{2}}\right]^{4}$$

$$b = 5.58 mm$$

-the minimum cross section due to bending

$$b = \left[\frac{12 \times 1.5 \times L^{4} \times M}{2 \times E_{Re} \times S_{max}}\right] = \left[\frac{12 \times 1.5 \times (0.91)^{2} m^{2} \times 137 M^{4}}{2 \times (72 \times 10^{3}) \frac{M}{M^{4}} \times 0.01 m^{2}}\right]$$

$$b = 3.45 \text{ cm}$$

$$- \text{ mass per leg}$$

$$m_{log} = \rho_{Re} V = 2800 \frac{\text{kg}}{\text{M}^{3}} \times (0.035)^{2} m^{2} \times (0.91 \text{ m})$$

$$m_{log} = 3.03 \text{ kg}$$

$$- \text{ total mass of legs:}$$

$$m_{logr} = 4 \times 3.03 = 12.12 \text{ kg}$$

$$Total \text{ Mass of the total mass of legs:}$$

$$27.196 \text{ kg} + 5.58 \text{ kg} + 12.12 \text{ kg} + 4 \text{ kg} + 2 \text{ kg}$$

$$= \frac{50.90}{9} \text{ kg}$$

Estimated Stowed and Deployed Volume of the Winged Radiator and Rail Support Estimated Stowed Volume 1.40m m ->| 0.5m V= 6m × 0.5m × 1.40 m $V = 4.2 \text{ m}^3$ Estimated Deployed Volume: V= 1.7m × 1.40m × 6m V= 14.28 m³

· _____ .

		ndix							
	Dect	in	Matr:	X					
CONCEPTS	DESIGN PARAMETERS								Γ_
	Safety	Low Mass	Ease of Manual Deployment	Low Stowed Volume	Low Effective Heat Sink Temp.	Low Power Consumption	Reliability	Ease of Maintenance	SUM OF PRODUCTS
WEIGHTING FACTORS	0.11	0.20	0.10	0.15	0.20	0.04	0.13	0.07	1.00
Modified Winged Radiator With Linked System	6 0.66	7 1.40	7 0.70	8	7	8	6 0.78	5	6.81
Winged Radiator With Linked System	6 0.66	7	6 0.60	8 1.20	7	8	6 0.78	5 0.35	6.71
cissors fechanism	3 0.33	5 1.00	5 0.50	8	8	6 0.24	5	4	5.80
anels With inked System	0.66	1.40	6 (1 0.60	8	2 0.40		6 0.78	5	5.71
eflector With olding System	0.44	1.00	3 0.30	3 8 0.45	1.60	0.16	4 7	0.49	4.96
flector With Iding System	0.44	1.00	0.30	3 8 0.45	1.60	0.16	0.52		.96
esnel Reflector 4 th Scissors echanism	0.44 S		0.50			0.20	4		.42

$$CASE 2$$

$$F_{1-2} + F_{2-1} = 1$$

$$F_{3-1} = 1 - F_{12} = 1 - \frac{L_1 + L_2 - L_3}{24} = 1 - \frac{L_2 + L_2 - L_3}{2L_2}$$

$$R = \frac{L_3}{L_R}$$
Lew of sizes : $L_2^2 = R^2 L_2^2 + L_1^2 + 3RL^2 + 3R$

$$\therefore F_{3}ncd_4 + 5 - cducton = 1 - \frac{R + R^2 + 1 + 3RL_2 + 3R}{3R}$$

$$F_{3}ncd_4 + 5 - cducton = 1 - \frac{R + R^2 + 1 + 3RL_2 + 3R}{3R}$$

$$F_{3}ncd_4 + 5 - cducton = 1 - \frac{R + R^2 + 1 + 3RL_2 + 3R}{3R}$$

$$F_{3}ncd_4 + 5 - cducton = 1 - \frac{R + R^2 + 1 + 3RL_2 + 3R}{3R}$$

$$F_{3}ncd_4 + 5 - cducton = R - \frac{R + R^2 + 1 + 3RL_2 - R}{2}$$

$$F_{3}ncd_4 + 5 - cducton = R - \frac{R + R^2 + 1 + 3RL_2 - R}{2}$$

$$F_{3}ncd_4 + 5 - cducton = R - \frac{R + R^2 + 1 + 3RL_2 - R}{2}$$

View factor of strip of reductor to when handles
It she de does not black all the lunan minimum.
Here: infinite plane and a surfice strip
Wants: Finitace by strip = Finitum b strip - Findse to strip
Four face lestrip =
$$(L_n - R(n \log \theta) | (100))$$

 $(E_{00})(400)$
 $K = \frac{1}{2\pi} \left(then' \left(\frac{400}{R(1) \log 0} \right) - \frac{R(200)}{4(100)} \right)^2$
 $K = \frac{1}{\sqrt{(1.25)^2 + \frac{R(200)}{R(1) \log 0}}} - \frac{R(200)}{\sqrt{(1.25)^2 + \frac{R(200)}{4(00)}}}^2$
 $K = \frac{1}{\sqrt{(1.25)^2 + \frac{R(200)}{R(1) \log 0}}}$
Finisher to strip = $\frac{R}{1 - R(n \log \theta)} \left[\frac{R(100) + 1 - \frac{1}{(1 - R(100))^2 + \frac{R(200)}{4(00)}}{2(1 - R(100))} + \frac{R(200)}{2(1 - R(100))} - \frac{1}{2\pi} \left[\frac{1}{2\pi} \left(\frac{1}{1 - R(100)} \right) - \frac{1}{\sqrt{(1.25)^2 + \frac{R(200)}{R(100)}}} \right]$
 $= \frac{R(200)}{(500)(100)} = \frac{1}{2\pi} \left[\frac{1}{2\pi} \left(\frac{1}{1 - R(100)} \right)^2 + \frac{R(200)}{R(200)} \right]$
 $= \frac{R(200)}{(200)(100)} = \frac{1}{2\pi} \left[\frac{1}{2\pi} \left(\frac{1}{1 - R(100)} \right)^2 + \frac{R(200)}{R(200)} \right]$
 $= \frac{R(200)}{(200)(100)} = \frac{1}{2\pi} \left[\frac{1}{2\pi} \left(\frac{1}{1 - R(100)} \right)^2 + \frac{R(200)}{R(200)} \right]$
 $= \frac{R(200)}{(200)(100)} = \frac{1}{2\pi} \left[\frac{1}{2\pi} \left(\frac{1}{1 - R(100)} \right)^2 + \frac{R(200)}{R(200)} \right]$
 $= \frac{R(200)}{(200)(100)} = \frac{1}{2\pi} \left[\frac{1}{2\pi} \left(\frac{1}{1 - R(100)} \right)^2 + \frac{R(200)}{R(200)} \right]$

.

Appendix I
Analysis of Final Design Solution
Modified Winged Radiator and Rail Support
A detailed calculation of the mass of the Modified
Winged Radiator and Rail Support Alternate is provided.
Also provided are estimates of the deployed and stourage
volume and power consumed during deployment.
Using data from thermal performance analysis the
length of the shading device panel and the radiator
area required to reject 10 kW and 25 IW of woske heat
wre determined.
Data gathered from thermal performance: If of

$$R = \frac{L_s}{L_s} = aspect ratio = 0.55$$

 $\partial = angle between the radiator and shade panel = 75°
radiator area required to reject 10 kW and 25 IW
of woske heat:
 $A_{z_s,w} = 389 m^2$
 $A_{z_s,w} = 713 m^2$$

- the number of radiators required to reject 10 kW and 25 kW
A = Radiator Ava = 6m × 0.15 m

$$n_{ww} = \frac{A_{ww}}{A} = \frac{389 \text{ m}^2}{6m \times 0.15 \text{ m}} = 432.2 \approx 433 \text{ radiators}$$

$$n_{z5_{kW}} = \frac{A_{z5_{w}}}{A} = \frac{973 \text{ m}^2}{6m \times 0.15 \text{ m}} = 1081.1 \approx 1082 \text{ radiators}$$

$$- \text{ number of packages needed}$$

$$N_{10} = \frac{n_{ww}}{n_{s5}} = \frac{433}{26} = 16.65 \approx 17$$

$$N_{25} = \frac{n_{z5_{w}}}{n_{s5}} = \frac{1082}{26} = 41.61 \approx 42$$

$$-\text{Mass of } 2.6 \text{ radiators}$$

$$m_{rT} = 2.6 \times P_{r} \times A = 5 \frac{\text{kg}}{\text{m}^2} \times 6m \times 0.15 \text{ m}^{\times} 26$$

$$m_{TT} = \frac{117}{15} \frac{\text{kg}}{112}$$

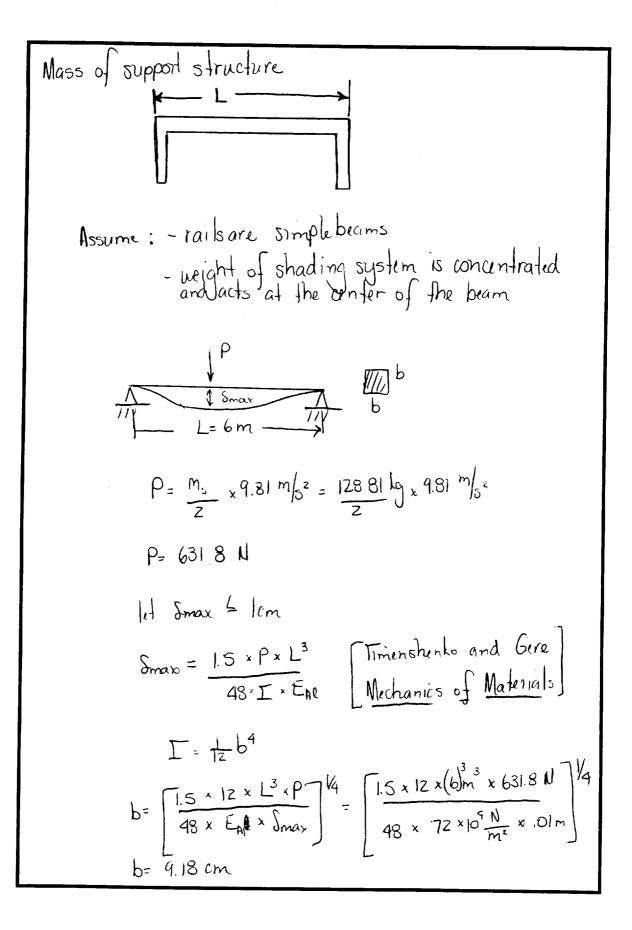
$$-\text{Mass of } \text{Kapton in } 26 \text{ shades}$$

$$m_{s_{T}} = P_{k} \times A \times 26 = 280.1814 \frac{\text{kg}}{\text{M}} \times 26 \times 0.0825 \text{ m} \times 6m \times 26$$

- mass for 1rd

$$m_r = \rho_{rr} V = 2800 lg_{m^3} \times (0.00198)^{2} m^4 (0.0825)m$$

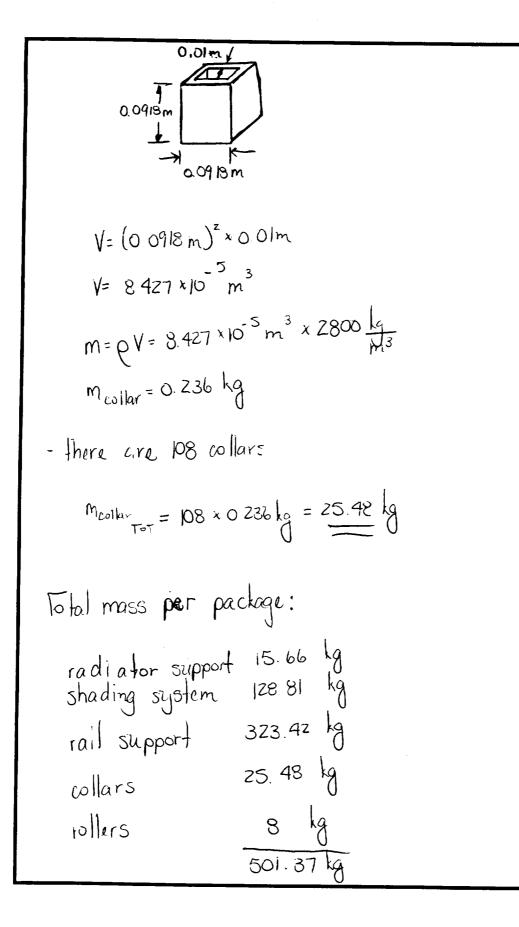
 $m_r = 0.00091 kg$
- Jhue are a total of 156 rods
 $m_{rr} = 156 \times (0.00091) lg = 0.141 lg$
- mass of transverse rods
 $26 \text{ shades } \times 4 \text{ rods} = 104$
Assume dimensions of III b
 $b = 2mm$
 $m_{\text{remus}} = (0.002)^{2}m \times 6m \times 2800 lg_{M^3} \times 104 = 7 lg$
- total mass of shading device and radiator
 $117 lg + 4.66 kg + 8 0.146 kg + 7 kg = 128.81 kg$



Niscellaneous Masses:
joints: 5 kg
collars: 25.48 kg
rollers: 6 kg

$$3mm = 0.5 \text{ cm}^{2} \text{ for a onlow m}$$

 $3mm = 0.003 \text{ m} \times 0.03 \text{ m} \times 0.0418 \text{ m}$
 $4 0.003 \text{ m} \times (0.0918)^{\text{m}^2}$
 $m = 0.3012 \text{ kg}$
there are 52 rodiator supports
 $m_{rot} = 0.3012 \text{ kg} \times 52 = 15.66 \text{ kg}$
 m_{rot} collars:



•

Estimated Power to Deploy the Modified Winged-System
and Rail Support
Assume: - each rail carries half of the total shade
system weight
- collar and rail material is aluminum, collar
is coated
F
rail
F= frictional force that must be overcome to
deploy the shading systems
W = total weight of shades acting on one rail.
F=
$$\mu W$$

 $\mu \approx 0.2$
W = 128 81 kg x 9.81 m/s² = 631.81 N
F = 0.20 (631.81 N) = 126.36 N
Assume each shading system moves an average of
4m.
the energy required to deploy the system
E = Fd = 126.26 N × 9m = 505.45 N·m

- Assume the deploying and retracting process occurs
in 120 secs; the power is
$$P = \frac{E}{L} = \frac{505 \ 45 \ \text{Nm}}{45 \ \text{Mm}} = 4.21 \ \text{W}$$
for the P KW system the total power required is:
$$P_{\text{FoT}} = 4.21 \ \text{W} \times 17 \ \text{poclages} = 71.6 \ \text{W}$$
for the 25 LW system the total power required is:
$$P_{\text{FoT}} = 4.21 \ \text{X} \times 17 \ \text{poclages} = 71.6 \ \text{W}$$
for the 25 LW system the total power required is:
$$P_{\text{FoT}} = 4.21 \times 42 = 176.32 \ \text{W}$$

Appendix
Wear of the collars and rail
In this appendix, the wear percentage of the collar
and rail is calculated. The total amount of material
removed from the surfaces after 200 deptoy and retract
cycles is provided.
Assumptions --the collar is not coated
-collar and rail material is
aluminum

$$W = \left(\frac{K}{H}\right)FS$$
 [Juvinall, Robert C.
Fundamentals of Machine Component
W= volume of material worn away, mm³
F= compressive force between the surfaces, N
S= total rubbing distance, mm
K= wean coefficient
H= surface hardness

F, the compressive force is the weight of the shading
system and radiator support conried by one rail

$$F = 5.44^{12}.163^{163} \cdot 8.87 \text{ N}$$

S, the total rubbing distance will be different for the
collar and rail
 $S_{rail} = 200 \text{ addes} \times 8000 \text{ mm} \times 54 \text{ collar} = 8.64 \times 10^{10} \text{ mm}$
 $t \text{ each shading distance}$
K, is approximately 5×10^{-2} , from figure $9-12$, for identical
mutals
 $H_{6} = 95$ for Al
 $W = \left(\frac{5 \times 10^{-2} \times 2.871 \text{ N}}{(95 \times 9.81) \text{ MBa}}\right) \times 8.69 \times 10^{7} \text{ mm} \times \frac{1 \times 10^{6} \text{ mm}^{2}}{1 \text{ m}^{2}}$
 $W = 411160 \text{ mm}^{3}$ material removed from the rail after 200
cyclus
Volume of the rail : $6m \times (0.0943)^{2}m^{2} = 0.0501 \text{ m}^{3} (50 \times 10^{10} \text{ mm}^{2})^{10}$

The amount of material removed from each collar:

$$S = \frac{200 \text{ collos} \times 8000 \text{ mm}}{\text{cycle}} = 1.6 \times 10^{6} \text{ mm}}$$

$$W = \left(\frac{5 \times 10^{-2} \times 8.87 \text{ N}}{(95 \times 9.81) \text{ MPa}}\right) \times \frac{1.6 \times 10^{6} \text{ mm} \times \frac{1 \times 10^{6} \text{ mm}^{2}}{1 \text{ m}^{2}}}{1 \text{ m}^{2}}$$

$$W = 761 \text{ mm}^{3}$$

$$W = 761 \text{ mm}^{3}$$

$$V = 100 \text{ mm}^{3}$$

$$V = (0.0919)^{2} \text{ m}^{2} \times 0.01 \text{ m}}$$

$$V = 83539 \text{ mm}^{3}$$

$$V = 100 \text{ mm}^{3}$$

$$V = 83539 \text{ mm}^{3}$$

$$V = 83539 \text{ mm}^{3}$$

$$V = 83539 \text{ mm}^{3}$$

$$V = 100 \text{ mm}^{3}$$

$$V = 83539 \text{ mm}^{3}$$

$$V = 100 \text{ mm}^{3}$$

$$V = 83539 \text{ mm}^{3}$$

$$V = 100 \text{ mm}^{3}$$

$$V$$