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SNR Degradation in Square-Wave Subcarrier Downconversion

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realizable filter does not have a flat magnitude in the pass band; so, some of the noise in this region will be weakened, assuming unity filter gain at the center frequency. Hence, the output noise power may change as compared to the ideal case. This change can be measured as the noise power gain in decibels, defined as follows:

noise power gain = $10 \log \frac{\text{noise power using real filter}}{\text{noise power using ideal filter}}$

When the value of the noise power gain is negative, the implication is that the noise power is decreased, as compared with the ideal case.

The noise power after filtering can be computed as follows: Assuming additive white noise with a power spectral density of $S(\omega) = N_0/2$, the noise power theoretically becomes [2]

If the FIR bandpass filters are used, the integrals can be evaluated by using Parseval's theorem [3, p. 187]:

$$\sum_{n=-\infty}^{\infty}|h[n]|^2=\frac{1}{2\pi}\int_{-\pi}^{\pi}|H(e^{j\omega})|^2d\omega$$

Since h[n] has a finite duration, the sum is over a finite number of terms.

The IIR filters are obtained by converting the analog Butterworth filters, using bilinear transformation with frequency prewarping. The cutoff frequency is the half-power or 3-dB cutoff frequency. The FIR filters are designed using the classical method of windowed linear-phase FIR filter design. A Hamming window is used in this case.

comes [2] By varying the IIR filter order and the cutoff frequency, inhered in murranianlly avaluated and the noice

III. Signal Power Change

There are three factors that cause the degradation in signal power: the cutoff of the data bandwidth, the finite number of harmonics considered, and the nonideal filtering. These are next discussed individually.

A. Data Bandwidth Cutoff

The bandwidth of the BPF should be greater than or equal to the data bandwidth if the data are band limited. However, this may not be satisfied in practice.

In the simulation, the signal consists of a square-wave subcarrier modulated by a 1-kHz pseudorandom sequence as data. A pseudorandom-noise (PN) shift register generator of length 10 associated with $\{3,10\}$ is used to generate the data [4, p. 342]. The power spectral density of the PN sequence is [4, p. 380]

$$P_{PN}(f) = -\frac{1}{N}\delta(f)$$

$$+\frac{N+1}{N^2}\operatorname{sinc}^2(\pi f T_c) \sum_{m=-\infty}^{\infty} \delta\left(f + \frac{m}{NT_c}\right)$$

where N is the sequence length, and T_c is the chip time. Clearly, a PN sequence is not band limited. Hence, when the BPF's are applied to a data modulated square-wave subcarrier, some of the signal power carried by the higher frequency components is filtered out, which leads to a signal power degradation. In general, the wider the filter bandwidth is, the lower the signal power degradation is. This relationship is shown in Fig. 2. However, there are upper limits on the filter bandwidth so that the undesirable harmonic terms can easily be separated from the desired ones [1]. For instance, in the simulation, the restriction is 22.5 kHz- $f_B/2 \ge 3f_B$, which implies that the filter bandwidth, f_B , should not exceed 6.43 kHz because aliasing may occur beyond this point. An alternative downconversion procedure (see Appendix B) may be used where no upper limit on the filter bandwidth will apply. However, the goal is to keep the bandwidth narrow for a low sample rate.

B. Finite Number of Harmonics Considered

Another factor that causes the signal power degradation is that only the first, third, and fifth harmonics are down-converted. The first three harmonics of a square-wave subcarrier carries only 93.3 percent of the total power of the square wave. So, there is about a 0.3-dB signal power

degradation in neglecting the higher order harmonics. Table 4 shows the relationship between the power loss and the harmonic number up to which the downconversion is carried out.

C. Nonideal Filtering

Finally, the signal degradation, due to the nonideal filtering, is analyzed through simulation. To separate the nonideal filtering effect from the other two factors, the input signal is considered to have the first three harmonics only:

subcarrier =
$$\frac{4}{\pi} \left[\sin(2\pi f t) + \frac{1}{3} \sin(2\pi \times 3f t) + \frac{1}{5} \sin(2\pi \times 5f t) \right]$$

where $f=22.5~\mathrm{kHz}$ for the Galileo signal. The simulation results can be subtracted from the signal power degradation due to the data-bandwidth cutoff computed in Section III.A. The results obtained directly from the simulation are shown in Table 5 and Figs. 3 and 4. These results reflect the signal power degradation due to both data-bandwidth cutoff and nonideal filtering. The signal degradation due to only nonideal filtering is shown in Table 6 and Figs. 5 and 6. This simulation was done with 5×10^6 samples at a sample rate of 260 kHz for filter bandwidths less than 5 kHz, and at 270 kHz otherwise.

Elliptic lowpass and bandpass filters have been simulated as well. The results in signal power degradation are lower than those using the same order Butterworth filters, but the output is severely distorted.

IV. SNR Degradation

Finally, the total SNR degradation can be obtained by adding the noise power gain in Table 3 to the signal power loss in Table 5. The results are shown in Table 7 and Figs. 7 and 8.

Note that the results in Table 7 exclude the effect of the consideration of a finite number of harmonics for the square wave.

V. Conclusion

This article presented an analysis on the SNR degradation in the square-wave subcarrier downconversion pro-

cess, as may be used in the Galileo S-band mission. There are three factors that affect the SNR degradation: the data-bandwidth cutoff, the approximation of a square wave with a finite number of harmonics, and nonideal

filtering. The three factors were analyzed separately, and the analytical and simulated results were presented. The distortion effects on the detection were not considered.

Acknowledgment

The authors thank Edgar Satorius for his many helpful suggestions and contributions to this work.

Table 1. Noise power gain (dB) due to IIR BPF.

Filter order		Filter bandwidth, kHz						
Filter order	2	3	4	5	6			
6 (analytical)	0.1999	0.1993	0.1986	0.1977	0.1965			
8 (analytical)	0.1120	0.1117	0.1114	0.1109	0.1104			
10 (analytical)	0.0716	0.0714	0.0712	0.0709	0.0706			
6 (simulated)	0.1760	0.1915	0.1899	0.2046	0.1957			
8 (simulated)	0.1169	0.1004	0.1262	0.1108	0.1080			
10 (simulated)	0.0926	0.0611	0.0785	0.1080	0.0732			

Table 2. Noise power gain (dB) due to FIR BPF.

Filter order		Intended	l filter band	ndwidth, kHz						
Filter order	2	3	4	5	6					
Obtained filter bandwidth, kHz										
160	2.2820	2.5420	3.0620	3.7640	4.6740					
320	1.5280	2.3340	3.3480	4.3360	5.3500					
		Noi	se power g	ain, dB						
160 (analytical)	0.2447	0.2678	0.1513	0.0915	0.0336					
320 (analytical)	0.1583	0.0386	0.0129	0.0155	0.0266					
160 (simulated)	0.2304	0.2646	0.1303	0.0998	0.0123					
320 (simulated)	0.1560	0.0739	-0.0012	-0.0032	0.0198					

Table 3. Noise power gain (dB) in downconversion.

Filter order		Filter	r bandwidt	h, kHz	
ritter order	2	3	4	5	6
IIR 6	-0.0646	-0.0801	-0.0801	-0.0801	-0.0795
IIR 8	-0.0752	-0.0882	-0.0827	-0.0960	-0.0711
IIR 10	-0.0743	-0.0943	-0.0748	-0.0736	-0.0998
FIR 160	-	-0.1429	-0.1610	-0.1422	-0.1501
FIR 320	-0.1328	-0.1009	-0.1210	-0.0451	-0.0664

Table 4. Signal power loss due to finite number of harmonics.

Harmonic number	1st	3rd	5th	7th	9th
Power loss, dB	0.9121	0.4545	0.3009	0.2246	0.1719
Harmonic number	11th	13th	15th	17th	19th
Power Loss, dB	0.1489	0.1274	0.1113	0.0988	0.0888

Table 5. Signal power loss (dB) from simulation.

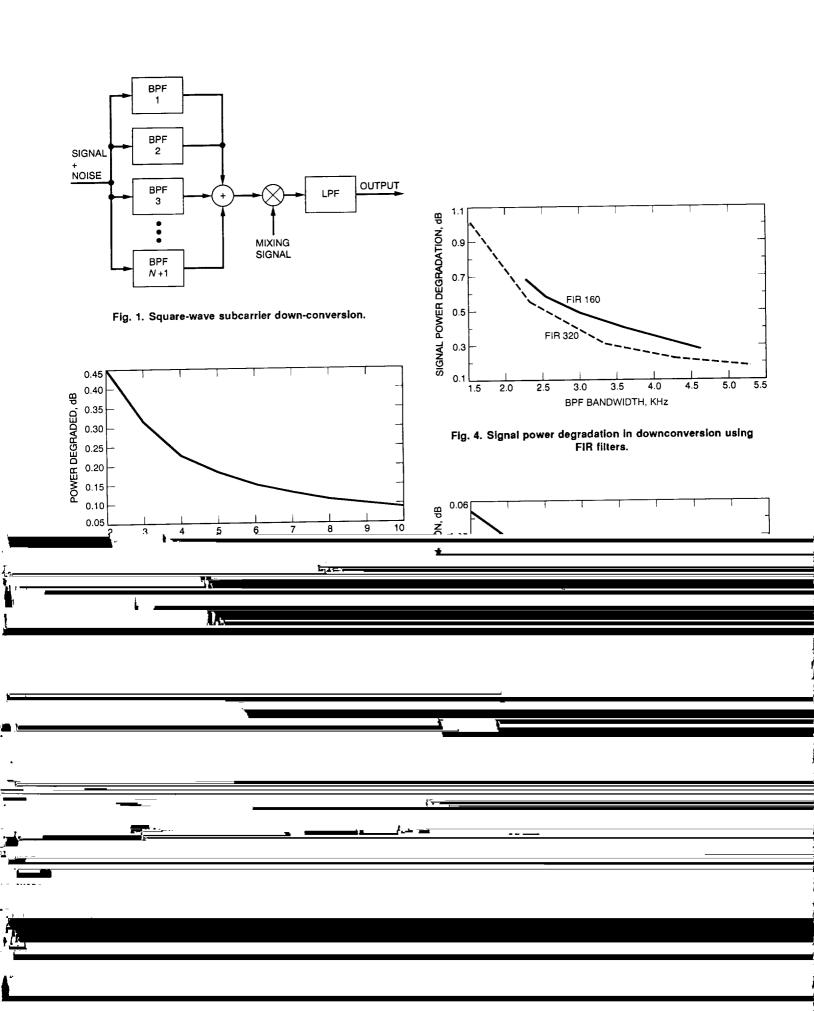
Filter order	Filter bandwidth, kHz						
r liter order	2	3	4	5	6		
IIR 6	0.5069	0.3554	0.2639	0.2105	0.1780		
IIR 8	0.4816	0.3422	0.2484	0.1999	0.1661		
IIR 10	0.4708	0.3351	0.2403	0.1946	0.1604		
FIR 160	_	0.5851	0.4807	0.3857	0.2772		
FIR 320	1.0134	0.5556	0.3120	0.2253	0.1813		

Table 6. Signal power degraded (dB) due to nonideal filtering.

Filter order		Filter bandwidth, kHz					
riter order	2	3	4	5	6		
IIR 6	0.0517	0.0413	0.0393	0.0284	0.0295		
IIR 8	0.0318	0.0281	0.0238	0.0178	0.0176		
IIR 10	0.0210	0.0210	0.0157	0.0125	0.0119		
FIR 160	_	0.1653	0.1643	0.1366	0.0462		
FIR 320	0.4936	0.1134	0.0464	0.0063	-0.0136		

Table 7. Total SNR degradation (dB) in downconversion.

Filter order		Filter bandwidth, kHz						
r itter of der	2	3	4	5	6			
IIR 6	0.4413	0.2753	0.1837	0.1304	0.0985			
IIR 8	0.4064	0.2541	0.1657	0.1039	0.0950			
IIR 10	0.3964	0.2407	0.1655	0.1210	0.0606			
FIR 160	_	0.4422	0.3197	0.2435	0.1271			
FIR 320	0.8806	0.4547	0.1910	0.1802	0.1149			



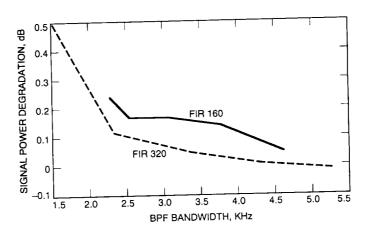


Fig. 6. Signal power degradation due to nonideal FIR filtering.

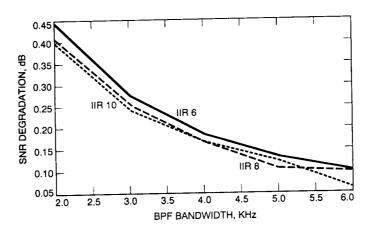


Fig. 7. SNR degradation in downconversion using IIR filters.

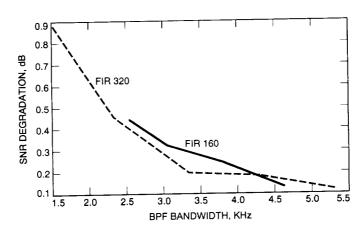


Fig. 8. SNR degradation in downconversion using FIR filters.

Appendix A

Number of Samples Needed in the Simulation

For N independent samples, x_i , of a random variable, x, the variance can be estimated by using an asymptotically unbiased and consistent estimate [5], namely,

$$\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^{N} (x_i - \hat{M})^2$$
 (A-1)

where \hat{M} is the mean estimate

$$\hat{M} = \frac{1}{N} \sum_{i=1}^{N} x_i$$

The mean of the variance estimate is

$$E\{\hat{\sigma}^2\} = \frac{N-1}{N}\sigma^2$$

where σ^2 is the true variance, and the variance of the estimate is

$$\operatorname{Var}\{\hat{\sigma}^2\} = \frac{1}{N}(\operatorname{E}\{x^4\} - \operatorname{E}^2\{x^2\})$$
 (A-2)

Assuming that the noise has a normal distribution, $E\{x^4\} = 3E^2\{x^2\}$ [6]. Substituting the last expression in Eq. (A-2),

$$\operatorname{Var}\{\hat{\sigma}^2\} = \frac{2}{N} (\sigma^2)^2 \tag{A-3}$$

or

standard deviation
$$\{\hat{\sigma}^2\} = \sqrt{\frac{2}{N}}\sigma^2$$

where N is the number of independent samples. In this case, at the BPF output, the number of independent samples reduces to approximately $N_{in}f_B/(f_s/2)$, with N_{in} being the number of independent samples at the input, f_B being the BPF bandwidth, and f_s being the sample rate. When $N_{in} = 5 \times 10^6$ and $f_s = 260$ kHz, the deviations (in decibels) of the estimated variance, $\hat{\sigma}^2$, from the true variance, σ^2 , in terms of f_B are shown in Table A-1.

Table A-1. Deviation of the estimated variance (dB) at output of BPF.

BPF bandwidth (kHz)	2	3	4	5	6
$10 \log (\hat{\sigma}^2/\sigma^2)$	0.0210	0.0180	0.0156	0.0140	0.0128

Appendix B

An Alternative Downconversion Procedure

An alternative procedure for the square-wave subcarrier downconversion is shown in Fig. B-1. This procedure differs from the one shown in Fig. 1 in the following ways: The undesirable terms will reside in a farther region in the frequency domain. For instance, assuming that the subcarrier frequency is smaller than the mixing signal frequency, $f_s < f_m$, then the lowest frequency of the undesirable terms in the procedure of Fig. 1 is

$$7f_s - 5f_m = 2f_s + 5(f_s - f_m)$$

whereas in the alternative procedure, this frequency is

$$f_s + f_m = 2f_s + (f_m - f_s)$$

The second term of the last two expressions are negative and positive, respectively. This fact makes the lowest frequency of the undesirable terms in the second case much larger than the first case, which is desired since this may lead to lesser interference from the undesirable terms when nonideal filters are realized. From the hardware perspective, this procedure may need four multipliers and three adders versus six adders and one multiplier in the procedure shown in Fig. 1.

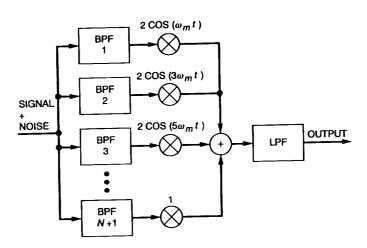


Fig. B-1. Alternative procedure for square-wave subcarrier downconversion.

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