NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

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PROPERTIES OF LOW-ASPECT-RATIO POINTED WINGS AT SPEEDS BELOW AND ABOVE THE SPEED OF SOUND By Robert T. Jones

SUMMARY

The second description of the Low-aspect-ratio wings having pointed plan forms are treated on the assumption that the flow potentials in planes at right angles to the long axis of the airfoils. are similar to the corresponding two-dimensional poten-tials. For the limiting case of small angles of attack and low appect ratios the theory brings out the following significant properties;

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(1) The lift of a slender, pointed sirfoil moving in the direction of its long axis depends on the increase in width of the sections in a downstream direction. Sections behind the section of maximum width develop no lift.

(2) The spanwise loading of such an airfoil is independents of the plan form and approaches the distribution giving a minimum induced drag.

(3) The Life distribution of a pointed airfoil travelling point-foremost is relatively unaffected by the compressibility of the air below or above the speed of sound.

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sonic. At speeds above the speed of sound application of the same assumptions leads to the Ackeret theory (reference 4), according to which the wing sections generate plane sound waves of small amplitude. As is well known, the Ackeret theory predicts a radical change in the properties of such wings on transition to supersonic velocities and these changes have been verified by experiments in supersonic wind tunnels (reference 5).

Both the Ackeret theory and the Munk theory apply to the case of a wing having a large span and a small chord. The present discussion is based on assumptions similar to those used by Ackeret and Munk but covers the opposite extreme, namely, the wing of small span and large chord. In the latter case the flow is expected to be twodimensional when viewed in planes perpendicular to the direction of motion.

A theory for the rectangular wing of small aspect ratio has been given by Bollay (reference 6). Bollay assumes a separated, or discontinuous, potential flow similar to the well-known Kirchoff flow and shows that under these circumstances the lift is proportional to the square of the angle of attack. Bollay does not consider the effect of compressibility. The present treatment covers other plan forms and, although based on different assumptions, is not inconsistent with Bollay's theory in the limiting case of small angles of attack.

By limiting the plan forms to small vertex angles, the properties of the wings in compressible flow at high subsonic and at supersonic speeds are also covered. Tsien (reference 7) has pointed out that Munk's airship theory (reference 8) applies to a slender body of revolution at speeds greater than sonic. The lift and moment of such a body are not expected to change appreciably with Mach number. The present paper gives an analysis of the low-aspect-ratio airfoil based on similar assumptions and shows that little change of the lift distribution of an airfoil of pointed plan form lying near the center of the Mach cone is to be expected.

SYMBOLS

v flight velocity

angle of attack

3

A

X

У

z

wing area aspect ratio $\left(\frac{b_{max}^2}{S}\right)$

distance along axis of symmetry of pointed airfoil, measured downstream from nose

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spanwise distance, measured from axis of symmetry

vertical distance from plane of wing

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density of air and the south of the second p i and 北京にあるこうで dynamic pressure q. and a set of the set of the set of the 谷谷代风县 local lift force (per unit length) 3.6 cr local lift coefficient (qb dx) Induced drag Dist induced-drag coefficient $\begin{pmatrix} D_1 \\ q_3 \end{pmatrix}$. S. A.W પ્રેમ્સ્ટ્રેસ્ટ્રિસ્ટ્રેસ્ટ્રિસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રે આગ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્રેસ્ટ્ to a set in the second CDI の意味ないない

L total lift

CL lift coefficient (as)

ø surface potential

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op local pressure difference

Mach number; ratio of flight velocity to spead of

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L_M lift at Mach number M L_o lift at zero Mach number max maximum (used as subscript)

THEORY FOR WINGS OF LOV ASPECT RATIO

The flow about an airfoil of very low aspect ratio may be considered two-dimensional when viewed in cross sections perpendicular to the longitudinal axis. With this idealization, the treatment of the low-aspect-ratio airfoil becomes exceedingly simple; formulas are obtained that are similar in some respects to those derived by Munk (reference 8) and Tsien (reference 7) for an elongated body of revolution.

Perhaps the simplest case from the analytical point of view is that of the long, flat, triangular airfoil travelling point-foremost at a small angle of attack. Viewed from a reference system at rest in the undisturbed fluid, the flow pattern in a plane cutting the airfoil at a distance x from the nose is the familiar twodimensional flow caused by a flat plate having the normal velocity Va. (See fig. 1.) Observed in this plane, the width of the plate and hence the scale of the flow pattern continually increase as the airfoil progresses through the plane. This increase in the scale of the flow pattern requires a local lift force 1 equal to the downward velocity Va times the local rate of increase of the. additional apparent mass m', or

$$\iota = Va \frac{dm'}{dt}$$
$$= V^2 a \frac{dm'}{dx}$$

since

 $V = \frac{dx}{dt}$

By a well-known formula from two-dimensional-flow theory,

 $m' = \frac{b^2}{4p} dx$

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where b is the local width of the plate. Hence

$$\frac{db}{xb} xb q \frac{d}{S}n = \frac{mb}{xb}$$

and the lift per unit length l will be given by the

$$x = \frac{db}{dx} d^2 V^2 b \frac{db}{dx} dx$$

Dividing by $\frac{2}{S}$ and by the area b dx gives the local lift coefficient

(1)
$$\frac{dr}{dr} = \frac{dr}{dr}$$

When this flow is considered in more detail, it is potential & is distributed spanwise according to the ordinates of an ellipse, that is,

$$\phi = \pm \Lambda \alpha \left(\frac{5}{p} \right)^2 - \frac{1}{2} \nabla \beta$$

 $= \pm \sqrt{\alpha} \frac{2}{p} a \pi \theta$

(2)

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where $\cos \theta = \frac{y}{b/2}$ and the sign changes in going from the upper to the lower surface of the airfoil. (See fig. 2.) An instant later, in the same plane, the ordinates are those of a slightly larger ellipse, corresponding to an increase of Ø. The local pressure difference is given by the local rate of increase of Ø,

$$\Delta p = 2p \frac{\partial t}{\partial \delta}$$
$$\Delta p = 2p \frac{\partial t}{\partial \delta}$$

 $= 2\rho \sqrt{\frac{db}{db}} \frac{d\delta}{d\delta} = 2\rho \sqrt{2}$

(£)

where $\partial \mathbf{J}/\partial \mathbf{b}$ is a function of y. Differentiation of \mathbf{J} yields the equation

$$\Delta p = 2\rho v^2 - \frac{b}{\sqrt{\left(\frac{b}{2}\right)^2 - y^2}} \frac{db}{dx} \frac{a}{4}$$

or

$$\frac{\Delta p}{q} = \frac{2a}{\sin \theta} \frac{db}{dx}$$
(4)

The pressure distribution thus shows an infinite peak along the sloping sides of the airfoil similar to the pressure peak at the leading edge of a conventional airfoil. The distribution along radial lines passing through the vertex of the triangle (lines of constant $\frac{y}{b/2}$) is uniform, however (fig. 3), and the center of pressure coincides with the center of area.

Equations (1) and (4) show that the development of lift by the long slender airfoil depends on an expansion of the sections in a downstream direction; hence a part of the surface having parallel sides would develop no lift. Furthermore, a decreasing width would, according to equation (4), require negative lift with infinito negative pressure poaks along the edges of the narrower sections. In the actual flow, however, the edge belied the maximum cross section will lie in the viscous or turbulent wake formed over the surface ahead; and for this reason it will be assumed that the infinite pressure difference indicated by equation (5) cannot be developed across these edges. It is this assumption, corresponding to the Kutta condition, which gives the plate the properties of an airfoil as distinct from another type of body, such as a body of revolution.

With the aid of the Kutta condition, it may easily be shown that sections of the airfoil behind the section of greatest width develop no lift. A potential flow satisfying both the boundary condition and the Kutta condition may be obtained by the introduction of a free surface of discontinuity behind the widest section. This surface of discontinuity (fig. 4) would be composed of parallel vortices extending downstream from the widest section of the airfoil as prolongations of the vortices

representing the discontinuity of potential over the forward part of the airfoil. This sheet, although possibly wider than the downstream sections of the airfoil, still satisfies their boundary condition, since the lateral arrangement of the vortices is such as to give uniform downward velocity equal to Va over the entire width of the sheet including the rearward portion of the airfoil. Since the pressure difference across the airfoil is proportional to $\partial \emptyset / \partial x$ and since this gradient disappears as soon as the vortices become parallel to the stream, no lift is developed on the rearward sections.

Integration of the pressures in a chordwise direction from the leading edge downstream to the widest section will give the span load distribution and the induced drag. The span load distribution is

$$\frac{\partial \mathbf{L}}{\partial \mathbf{y}} = \int \Delta \mathbf{p} \, \mathrm{d}\mathbf{x}$$

or, from equation (3),

$$\frac{\partial L}{\partial v} = 20V \emptyset$$

From equation (2),

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Hence $\partial L/\partial y$ is elliptical and independent of the plan form. With the elliptical span load the induced drag is a minimum and is equal to

$$D_{1} = \frac{L^{2}}{\pi q b_{max}^{2}}$$
(5)

A second integration of $\frac{\partial L}{\partial y}$ dy across the widest section gives the total lift, which is

$$L = \frac{\pi}{4} p V^2 a b_{max}^2 \qquad (6)$$

(7)

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The lift of the slender airfoil therefore depends only on the width and not on the area. If the lift is divided and if the aspect ratio A is considered to ov2s bmax, then

 $c_{L} = \frac{\pi}{2}Ax$

be

and the induced-drag coefficient is

$$c_{D_{1}} = \frac{c_{L}^{2}}{\pi A}$$
$$= c_{T_{1}} \frac{\alpha}{2}$$
(8)

From equation (8) it appears that the resultant force lies halfway between the normal to the surface and the normal to the air stream.

It is seen that in the case of a rectangular plan form the simplified formula (equation (4)) gives an infinite concentration of lift at the leading edge and no lift elsewhere, whereas a more accurate theory would show some distribution of the lift rearward. If the rate of increase of the width becomes too great, the flow cannot be expected to remain two-dimensional. It can be shown by examination of the known three-dimensional (nonlifting) potential flow around an elliptic disk (reference 9), however, that the two-dimensional theory gives a good approximation in the case of an elliptical leading edge, which indicates that the theory is applicable over a large range of nose shapes. In figure 5 is shown a comparison of the lift calculated by the present theory for elliptical wings of low aspect ratio with the results of the more accurate three-dimensional potentialflow calculations of Krienes (reference 10). The results are in good agreement up to aspect ratios approaching 1. Application of equation (4) gives a center of pressure on the elliptical plan form at one-sixth of the chord. Figure 6 also shows this value compared with values given by Krienes's theory. In this respect it appears that the agreement is not so good as for the lift.

EFFECT OF COMPRESSIBILITY

In order to show the effect of compressibility, use will be made of the theory of potential flow with small disturbances. Glauent (reference 2) and Prandtl (reference 3) have demonstrated that, at subsonic speeds, a distribution of potential satisfying Laplace's equation will satisfy the linearized compressible-flow equation if the distribution $\mathscr{P}(x,y,z)$ is foreshortened along the direction of motion by the transformation

 $x' = \frac{x}{\sqrt{1 - M^2}}$ y' = y z' = z

This fact may be applied in a calculation procedure by starting with a fictitious airfoil longer in the x-direction than the true one and calculating the potential distribution for this airfoil by methods of incompressible flow. The correct dimensions and correct distribution of \emptyset are then obtained when the transformation is applied.

For the long slender airfoil, the potential distribution at each section is similar to that for an infinitely long body; therefore $\partial \not / \partial x$ and hence the local pressures vary in inverse proportion to the length. The foregoing calculation procedure gives a null result in this case, since the pressures calculated for the fictitious airfoil at M = 0 will be reduced in the same ratio that the length is increased and the Lorentz transformation to restore the correct length will also restore the same pressures as those obtained at H = 0. Since $\partial \not / \partial z$ is unchanged by the transformation, the normal velocity component and hence the angle of attack are unchanged also. These results can be obtained by referring directly to the linearized equation for the potential

$$\left(1 - M^2\right)\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$$
(9)

(See reference 3.) If the airfoil is sufficiently slender, $\partial^2 \emptyset / \partial x^2$ can be neglected in comparison with $\partial \emptyset / \partial x$ except near the edge. Since the lift is proportional

0

to $\partial \emptyset / \partial x$, the increase of the lift with Mach number can therefore be neglected in comparison with the lift.

It is important to note that the theory of small disturbances is not limited to subsonic velocities and $(2) e^{2} a$

that, so long as the term $(1 - M^2) \frac{\partial^2 \phi}{\partial x^2}$ in equation (9)

remains small, the solution in the region of the wing will continue to be given by the potential (equation (2)). Evidently the Mach number cannot be increased indefinitely, for then the coefficient of $\frac{\partial^2}{\partial x^2}$ will become so large that the first term will no longer be negligible. The required condition will be satisfied, however, by adopting a pointed plan form with the vertex angle so small that the entire surface lies near the center of the Mach cone (fig. 7). The condition of a small vertex angle is also necessary in order that the potential distribution of equation (2) may apply. In the case of a wing with a blunt-leading-edge plan form, abrupt changes in the flow arise on transition to supersonic velocities, and potential flow of the subsonic type no longer exists.

The lift and lift distribution for rectangular surfaces at supersonic speeds have been calculated by Schlichting (reference 11). Figure 7 shows the variation of lift-curve slope with Mach number as obtained from Schlichting's results for rectangular wings of two different aspect ratios and for the range of speeds in which the two Mach cones from the tips do not reach the center of the wing. In the subsonic range, values given by the Prandtl-Glauert rule are shown. These curves are compared with the values indicated by the present theory for a triangular wing lying near the center of the Mach cone. Figure 8 shows the travel of the center of pressure for these plan forms. It is to be noted that, with the blunt-leading-edge plan forms, the center of pressure travels from a point near the quarter chord to a point near the midchord when the velocity is increased above the speed of sound.

TESTS OF A TRIANCULAR AIRFOIL AT SUPERSONIC SPEED

As a test of the foregoing analysis, a small triangular airfoil in the form of a steel plate with rounded leading edges was constructed and tested in the Langley model supersonic tunnel. The tests were made at a Mach number of 1.75. Figure 9 shows the details of the model and figure 10 summarizes the results of the test. At zero angle of attack a small lift and a small pitching moment occur, which are presumably the result of the camber given the airfoil by rounding off the leading edges in the manner shown by section A-A in figure 9. In general, the results are in good agreement with the theory if an allowance is made for this camber, as shown in figure 10.

CONCLUSIONS

1. The lift of a slender, pointed airfoil moving in the direction of its long axis depends on the increase in width of the sections in a downstream direction. Sections behind the section of maximum width develop no lift.

2. The spanwise loading of such an airfoil is independent of the plan form and approaches the distribution giving a minimum induced drag.

3. The lift distribution of a pointed airfoil travelling point-foremost is relatively unaffected by the compressibility of the air below or above the speed of sound.

Langley Memorial Aeronautical Laboratory National Advisory Committee for Aeronautics Langley Field, Va., May 11, 1945

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Figure 1. - Flow pattern.



Figure 2.- Potential.



Figure 3. - Pressure distribution.



Figure 4. - Wake.

Figs. 1,2,3,4

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Figs. 5,6

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Figs. 7,8

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Figure 8, - Travel of evalor of pressure with Each number for different plan forms,

NACA TN No. 1032 Fig. 9 ٦ Α 1/2" THE R 16 2 MT. Mounting attachment 11 anon non non Section A-A NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS Figure 9. - Airfoil tested in Langley model supersonic tunnel.

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Figure 10. - Test of triangular airfoil in Langley model supersonie tunnel. Mach number, 1.75; Reynolds number, 1,600,000.

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