

# SEA SURFACE SALINITY: THE NEXT REMOTE SENSING CHALLENGE

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**I**N LATE AUTUMN 1993, a conference on Satellite Altimetry and the Oceans was held in Toulouse, France. The TOPEX/Poseidon satellite had begun the second year in orbit, and all indications were that the data quality was beyond expectations. During the final address at the conference, Carl Wunsch recounted, among other things, the technical progress of satellite altimetry over nearly two decades, wherein the accuracy had improved a 100-fold. He emphasized that this success resulted from early recognition that fundamental "zeroth-order" scientific impact could be derived from planning and implementing requisite technology development. The same has held true for technology to measure winds, sea surface temperature (SST), ocean color, and the gravity field from space, he pointed out, and then asked "What are we overlooking? What new technological challenges are there for zeroth-order impact on the knowledge of the ocean?" The purpose of this paper is to suggest that measuring the global surface salinity field from satellite is the next challenge.

Satellite observations are becoming an integral part of global ocean observing systems designed ultimately to monitor interannual to interdecadal time scale processes as we attempt to understand the uncertainties for forecasting El Niño-Southern Oscillation, global warming, and other climate variations. Perhaps the foremost example of where sea surface salinity (SSS) plays an important role in these processes is the far north Atlantic. Surface low-salinity intrusions are believed to influence the deep convection that drives thermohaline circulation and the meridional heat transport (Dickson *et al.*, 1988; Aagaard and Carmack, 1989; Broecker, 1991; Delworth *et al.*, 1993). The re-

moteness and harsh climate of the dynamically important regions inhibits conventional measurements making the advantages of an all-weather satellite measurement self-evident.

Salinity variations also influence upper ocean dynamics in the tropics. It has been suggested that upper ocean buoyancy accumulation due to excess rainfall in the western Pacific is a factor in El Niño dynamics (Godfrey, 1990). Tropical air-sea heat fluxes are influenced by surface freshened lenses in the heavy rainfall regimes (Lukas and Lindstrom, 1991). For over two decades, the French ORSTOM agency has monitored SSS from several merchant ship tracks in the Pacific, providing perhaps the most comprehensive regional SSS record available. Among other things, these data show that interannual SSS variations are influenced by the precipitation patterns associated with ENSO (Delcroix and Henin, 1991).

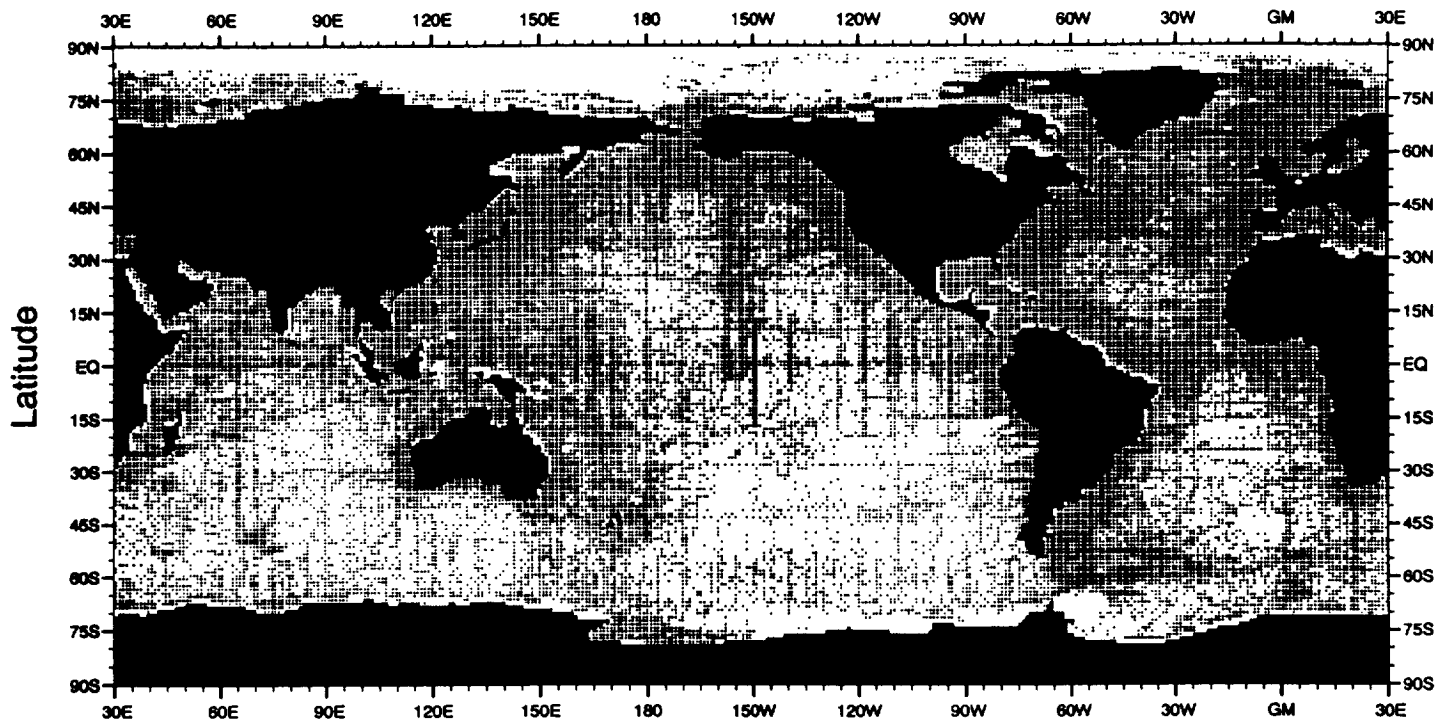
The water and heat fluxes associated with precipitation and evaporation over the global ocean are fundamental processes regulating climate and weather. The SSS field, and its seasonal-to-interannual variability, are stringent constraints on the hydrologic balance and coupled ocean-atmosphere climate models. Our knowledge of SSS remains quite limited, however. A census of  $1^\circ \times 1^\circ$  squares shows that ~30% have no SSS observations at all (Levitus *et al.*, 1994; Table 1) and large expanses are unobserved (Fig. 1). There is an average of about 40 observations per square in those squares with data. Seasonal variations for the world ocean have been estimated (Levitus, 1986) but documenting past interannual-to-interdecadal SSS variability, with the exception of a few long-time series, has not been possible. The situation is improving somewhat with recent world data center acquisitions of previously unavailable historical data sets. However, conventional global SSS observations will not increase significantly in the near future. In contrast, we now possess global satellite measurements of SST, surface topography, winds, and ocean color. The new perspectives on the ocean provided by these data do not need

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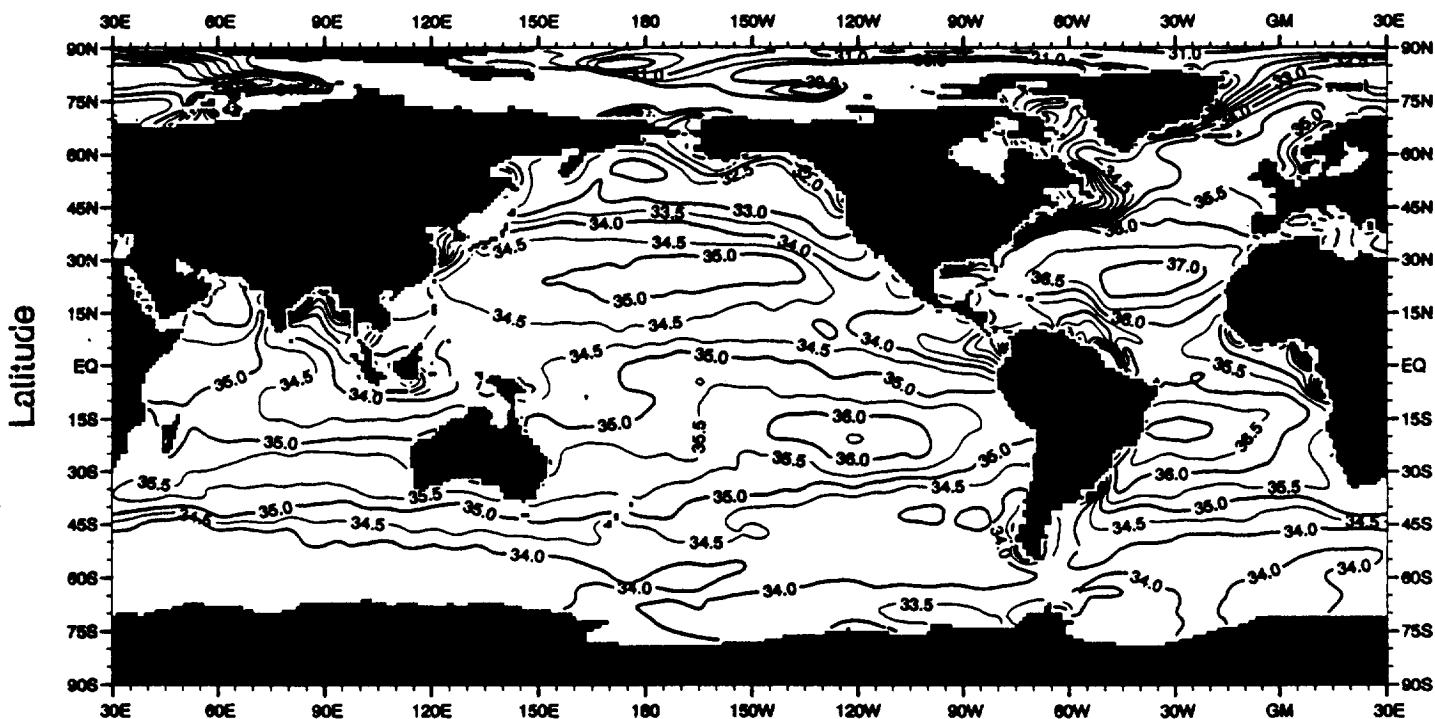


# Longitude



## Distribution of salinity observations at the sea surface

# Longitude



**Fig. 1** *Top:* The present distribution of salinity observations at the surface. *Bottom:* the mean annual surface salinity field deduced from these observations. (From Levitus et al., 1994.)

Table 1  
ESTAR salinity error budget estimate

| Error Source | $T_B$ Error, °K | S Error*, psu | Length Scale†, Km | Samples (N) per<br>330 Km · 10 d‡ | $N^{1/2}$ | Error, psu |
|--------------|-----------------|---------------|-------------------|-----------------------------------|-----------|------------|
| Sensor§      | 1.0             | 3.0           | 10                | 3250                              | 57        | 0.05       |
| SST          |                 | 0.3           | 10                | 3250                              | 57        | 0.01       |
| Wind¶        | 0.5             | 1.5           | 10                | 3250                              | 57        | 0.03       |
| Galactic#    | 0.05            | 0.15          | $10^3$            | 3                                 | 1.7       | 0.09       |
| Ionosphere** | 0.05            | 0.15          | $10^3$            | 3                                 | 1.7       | 0.09       |
| Atmosphere†† | 0.02            | 0.06          | $10^3$            | 3                                 | 1.7       | 0.03       |
| Total RSS    |                 |               |                   |                                   |           | 0.14       |

\*  $\partial\text{SSS}/\partial T_B$  at 1.4 GHz ranges from ~2 to 4 (Fig. 2) and average value of 3 is assumed.

† Length scale same as sensor resolution for ESTAR SST and wind retrievals.

‡ Assumes 3 satellite passes every 10 d (~3-d repeat) and no subgrid independent samples for long length errors.

§ Sensor accuracy 1°K (Swift *et al.*, 1993).

|| Coupled effect of SSS and SST at 1.4 GHz is that  $\partial\text{SSS}/\partial\text{SST}$  varies from -0.2 to 0.4 and is zero near SST = 15°C (Swift and McIntosh, 1983). Assume magnitude of 0.3 and SST uncertainty of 1°C.

¶ Wind speed relation at 1.4 GHz is estimated between 0.16 and  $0.32^\circ\text{Km}^{-1}$ s (Webster *et al.*, 1976; Lerner and Hollinger, 1977). Assume  $\partial T_B/\partial W = 0.25^\circ\text{Km}^{-1}$ s and wind speed uncertainty  $2\text{ ms}^{-1}$ .

# Maximum bias at 1.4 GHz is ~1°K when galactic core is within 20° of zenith and otherwise negligible over much of the sky (Blume *et al.*, 1978). Assume correctable to  $0.05^\circ\text{K}$ .

\*\* Maximum ionospheric bias at 1.4 GHz is ~2°K in peak daytime conditions and reduced by an order of magnitude at night. This can be corrected with ionosphere models to  $<0.05^\circ\text{K}$  uncertainty assuming only nighttime observations.

†† Atmosphere corrections at 1.4 GHz vary by ~0.3°K over the range of atmospheric conditions (Lerner and Hollinger, 1977), and are due mostly to oxygen absorption, which can be corrected with meteorological analyses.

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repeating here, but it has long been recognized that SSS is an important parameter missing from the satellite remote sensing tool kit. It has been far less recognized that SSS remote sensing is possible and has been demonstrated.

#### Salinity Remote Sensing—A Brief History, and How It Works

It may surprise the reader that the first (and only) attempt to measure SSS from space took place 20 years ago on Skylab (Lerner and Hollinger, 1977). A 1.4 GHz microwave radiometer collected data intermittently, there was no "ground truth" other than standard surface charts, and many of the ambient corrections were not as well understood then as they are today. Nevertheless, a correlation was found between the sensor data (after correcting for other influences) and SSS. This was an encouraging early result.

The research leading up to the Skylab experiment began with several efforts during the late 1940s and early 1950s to measure the complex dielectric constant of saline solutions for various salinities, temperatures, and microwave frequencies. These relationships provide the physical basis for microwave remote sensing of the ocean. In brief, the ocean radiometric brightness temperature ( $T_B$ ) is related to the absolute thermodynamic temperature ( $T$ ) by the emissivity ( $e$ ) as

$$T_B = eT \quad (1)$$

The emissivity is a complex function of the dielectric constant of seawater, viewing angle, polarization, and other factors. The dielectric constant, in turn, is governed by the electrical conduc-

tivity and the microwave frequency of observation. Since conductivity is governed by salinity and temperature,  $T_B$  can be expressed as a function of SSS and SST, although the equations are quite complicated; Klein and Swift (1977) and Swift and McIntosh (1983) give a detailed discussion. At relatively low microwave frequencies ~1 to 3 GHz the sensitivity is sufficient to permit SSS remote sensing. Figure 2 shows the  $T_B$  model function at 1.43 (L-band) and 2.65 (S-band) GHz for zero incidence (nadir view). The  $T_B$  relation with SSS and SST differs at these two frequencies, and it is possible to obtain both SSS and SST with dual frequency measurements (Blume *et al.*, 1978). Furthermore, atmospheric water and ice clouds have a negligible effect at these frequencies, and the observations are possible in all weather.

Droppelman *et al.* (1970) demonstrated the first airborne salinity measurements in the Mississippi River outflow. This led to renewed efforts to refine the dielectric constant and governing equations with application to ocean remote sensing. (Klein and Swift, 1977). Meanwhile, a series of airborne experiments followed Skylab and mapped coastal salinity patterns in the Chesapeake and Savannah river plumes and along the Puerto Rico shoreline. (Blume *et al.*, 1978 and 1981; Blume and Kendall, 1982; Kendall and Blanton, 1981). Swift and McIntosh (1983) described a satellite concept with an ideal precision of ~0.25 practical salinity units (psu; equivalent to parts per thousand) and spatial resolution of ~100 km. They reviewed a number of measurement and technical issues needing study. These issues remain, but

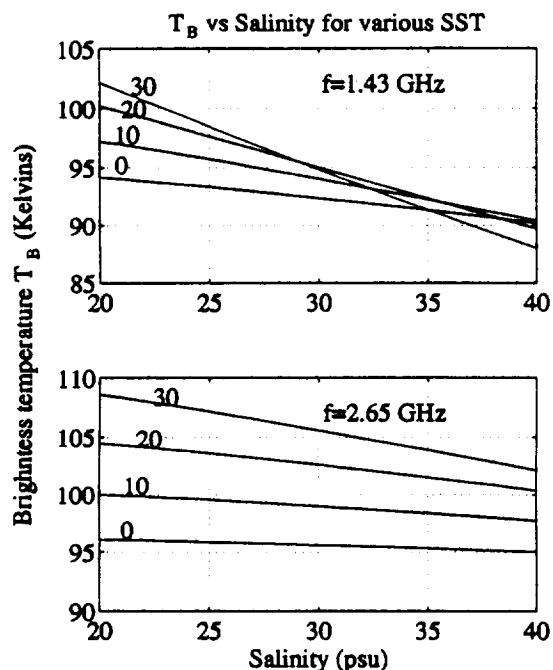


Fig. 2: The variation of brightness temperature due to salinity at 1.4 GHz and 2.65 GHz, with SST as a parameter, according to the formulas given by Klein and Swift (1977).

reasonable estimates of their influence on measurement accuracy can be made (see below). It was becoming evident that satellite SSS remote sensing was a possibility.

In the early 1980s, NASA was in the process of establishing the oceanic processes remote sensing program around a package of missions and sensors for measuring dynamic topography, wind stress, ocean color, SST, and sea ice. Salinity remote sensing was considered, but there was a tendency to view it in the context of  $\sim 1$  km,  $1^\circ\text{C}$  infrared SST capability. As shown below, such a program would require enormous antenna structures, and the measurement accuracy would not rival that of SST. Oceanographers accustomed to making high-precision salinity measurements at sea concluded that remote sensing data quality did not justify a dedicated effort. This, coupled with the lack of a clearly defined scientific need for the data at the degraded accuracy and resolution, prompted the decision to abandon SSS remote sensing and focus on the other elements of the ocean program.

Interest in SSS remote sensing revived in the late 1980s with the development of a 1.4 GHz airborne Electrically Scanning Thinned Array Radiometer (ESTAR). ESTAR imaging is done electronically with no moving antenna parts, thus making larger antenna structures more feasible. The airborne version was developed as an engineering prototype and to provide the proof-of-concept that aperture synthesis can be extrapolated to a satellite design (Le Vine *et al.*, 1990). On a few occasions there have been opportunities to collect

ocean data with this sensor; results from a flight across the Gulf Stream near Cape Hatteras are shown in Figure 3. The change from  $\text{SSS} > 36$  in the offshore waters to  $\text{SSS} < 32$  near shore is evident, along with several frontal features noted in the satellite SST image from the same day (not shown). The Gulf Stream transect suggests that smaller open ocean variations can be detected as well as the strong salinity gradients in the coastal and estuary settings demonstrated previously. In fact, development of a sensor to be routinely carried on commercial aircraft to monitor SSS along routes crossing the subpolar North Atlantic has been proposed. At this point, however, we wish to focus our discussion on satellite measurements.

### ESTAR—A New Mission Concept

Circumstances have evolved to where we should reconsider the choices made a decade ago regarding salinity remote sensing. First, the scientific agenda has changed. Long-term commitments for the existing ocean remote sensing measurements are gradually falling into place. It is time to examine which new applications and parameters should next be addressed. Coupled with this are the scientific developments, alluded to above, which have stimulated interest in measuring surface salinity. Second, the new ESTAR technology implies that spatial resolution can be significantly improved at these low frequencies, which in turn removes a major limitation on measurement precision, given that random errors can be reduced by averaging over larger areas.

Improving spatial resolution requires the larger antenna size that is made practical with ESTAR. A radiometer footprint size ( $x$ ) is determined by the electromagnetic wavelength ( $\lambda$ ), satellite altitude ( $h$ ) and antenna aperture ( $D$ ) as follows:

$$x \approx 1.22 \frac{\lambda h}{D} \quad (2)$$

With ESTAR it is feasible to deploy a  $\sim 10$  m aperture antenna to obtain 10-km resolution from an orbit altitude of  $\sim 400$  km for a 1.4-GHz ( $\lambda = 21$  cm) radiometer (see Swift, 1993 for more technical detail). In contrast to achieving a 10-km footprint, it would still require an enormous (and unfeasible) antenna to obtain  $\sim 1$ -km resolution. We should dispel any misconceptions that spaceborne salinity remote sensing will ever provide the rich detail of surface processes evident in SST images. Instead, we should adjust our thinking and evaluate if scientifically useful measurements can be obtained at larger spatial scales. A clue to defining those scales can come from other satellite projects.

### Comparing SSS With Other Satellite Measurements

The Special Sensor Microwave Imager (SSM/I) operates at frequencies from 18 to 85 GHz, where the  $T_B$  variations caused by atmospheric water

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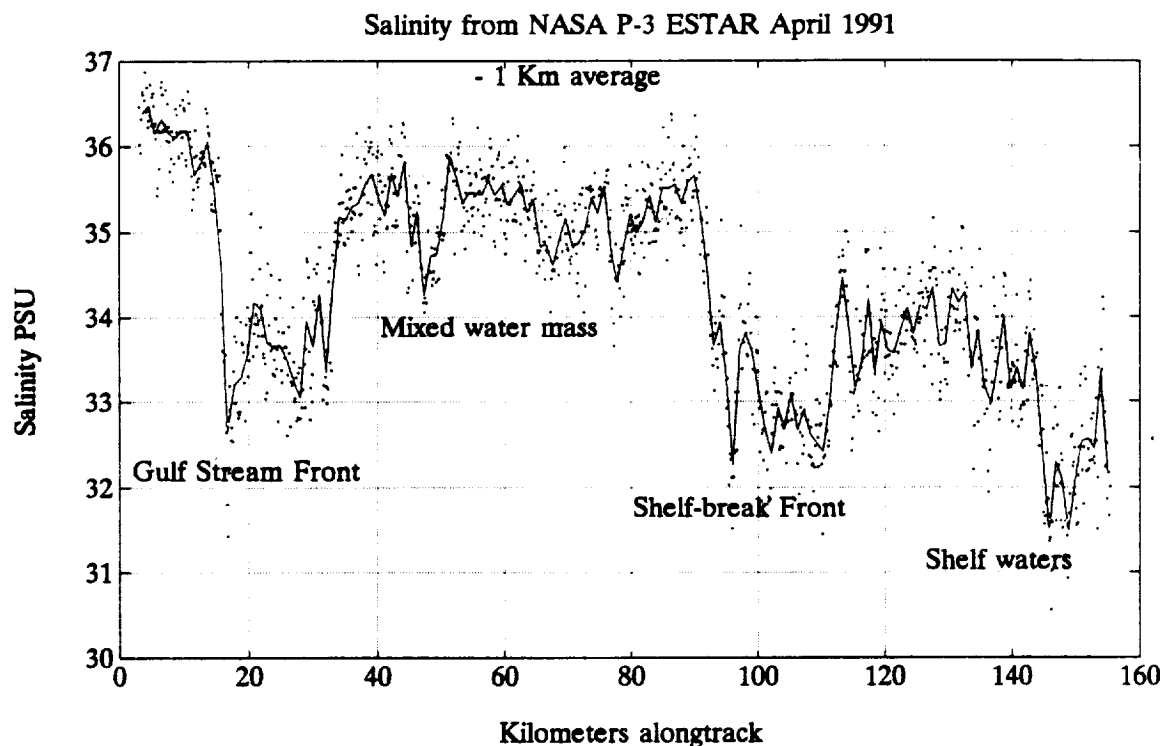


Fig. 3: Salinity measurements with the airborne ESTAR along a transect from seaward of the Gulf Stream to Cape Hatteras, April 1991. The SSS change from  $>36$  in the offshore waters to  $<32$  in coastal waters is evident, along with several frontal features noted in the satellite SST image from the same day (not shown). Points are 1-s averages and the solid line is 1 km along-track averages ( $\sim 7$  s).

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vapor and rainfall cover dynamic ranges of  $\sim 100^\circ\text{K}$ , and a sensor error of  $1^\circ\text{K}$  provides very good parameter resolution. We can see from Figure 2 that at 1.4 GHz the  $T_b$  range is only  $\sim 5^\circ\text{K}$  over open ocean conditions (remote from coastal regions). It is no wonder that experienced remote sensing scientists take a skeptical view of salinity remote sensing using a microwave radiometer with a  $\sim 1^\circ\text{K}$  sensor error. However, oceanic time scales are generally much slower than the atmospheric synoptic scale, and sampling requirements can be relaxed. TOPEX/Poseidon, for example, measures ocean dynamic topography in an orbit that traces a diamond-shaped lattice grid repeated every 10 d (Fig. 4). The area of one grid cell at low latitude is about 110,000 km<sup>2</sup> or the equivalent of a  $\sim 330$ -km square. It is instructive to compare the capabilities of TOPEX/Poseidon at this spatial and temporal resolution with a salinity sensor such as ESTAR to assess the scientific potential of the latter. The sampling density would increase with latitude commensurately for both satellites, so 330-km resolution can be used as a general basis for comparison. Table 1 shows summaries of the estimated salinity measurement errors and the impact of error reduction through spatial and temporal averaging. It is assumed that the sensor is in a sun-synchronous orbit with a revisit time of  $\sim 3$  d, measures SSS at 10-km resolution each pass, and carries channels to measure SST

and wind at the same resolution (see Swift *et al.*, 1993). It is immediately apparent that the sensor noise is the largest error source at the fine scale (10 km), but is a minor term on the large scales due to averaging. The long length scale errors do not have this advantage and represent the largest uncertainties needing to be modeled and corrected. Reasonable estimates of the uncertainties after correction are given in the table and notes, and the total root sum square (rss) error is estimated to be  $\sim 0.14$  psu at these scales.

Table 2 shows a comparison to TOPEX/Poseidon. The mean dynamic topography has a dynamic range of  $\sim 250$  cm globally and, with a  $\sim 5$ -cm error, TOPEX/Poseidon yields a  $\sim 50:1$  signal-to-error ratio. Open ocean surface salinity varies from 32 to 37 psu globally, for a 5 psu dynamic range. We see that a  $\sim 0.14$  psu rss error,

Table 2  
Performance comparison

|                       | TOPEX/Poseidon | ESTAR Salinity |
|-----------------------|----------------|----------------|
| Spatial resolution    | 330 Km         | 330 Km         |
| Temporal resolution   | 10 d           | 10 d           |
| Signal dynamic range  | 250 cm         | 5 psu          |
| Error                 | 5 cm           | 0.14 psu       |
| Signal to error ratio | 50:1           | 35:1           |

suggests that a comparable  $\sim 35:1$  signal-to-error ratio is possible for SSS measurements at the same spatial and temporal scales as TOPEX/Poseidon. Even with larger errors, say  $\sim 0.25$  psu, the signal-to-error ratio would be on the same order. Other altimeter mission (ERS1, Geosat) signal-to-error ratios are likewise smaller than TOPEX/Poseidon, and the scientific value of those missions is well recognized. There are a number of assumptions in the error estimates of Table 1, so it would be more prudent, perhaps, to consider these as reasonable technical objectives. We can add some margin here by giving a range, say of 0.1 to 0.3 psu error on length scales of 100 to 300 km and periods of weeks to months. Quite honestly, we cannot be more specific without further engineering study. Nevertheless, salinity remote sensing has significant promise at the resolution scales of satellite altimetry. In terms of global observations, we see a simple trade-off between sparse yet very accurate conventional salinity measurements versus much less accurate data with much more dense and orderly sampling from satellite. At 10-km resolution and 3-day repeat sampling, about 1,000 samples per 1-degree square can be obtained per month. Consider this in comparison to Figure 1, which is the present day accumulation of all historical data. Large ocean expanses, particularly in the Southern Hemisphere, would be observed for the first time. Remote sensing can provide a vast amount of new information, even with a signal-to-noise ratio of order 1. The ocean salinity spectrum is red, and assuming the error noise is white, there exists a time and space scale where the signal will emerge. With appropriate emphasis on technology, rudimentary signal processing and careful attention to modeling the requisite corrections to the data, it will be possible to measure SSS usefully on climatic scales. Absolute calibration and monitoring of instrument drift could be done, the same way we presently do SST remote sensing, with surface observations from a variety of conventional platforms such as drifters, moorings and volunteer ships.

## Conclusion

We have sought to convince the reader that SSS satellite remote sensing is a practical idea. There are some who will argue that the error estimates given here are unrealistic. The counter argument is that errors can be significantly reduced with proper commitment of resources to the technology. Salinity remote sensing carries no more technical risk than other well-known remote sensing techniques did in their infancy. Advancing technology always generates improvements. It is instructive to recall the accuracy of the earliest dedicated altimeter mission (GEOS-3), nearly 20 years ago, in which the radial orbit error was many meters and the altimeter noise level was  $\sim 50$  cm. TOPEX/Poseidon has cut those errors by about two orders of magnitude and now measures

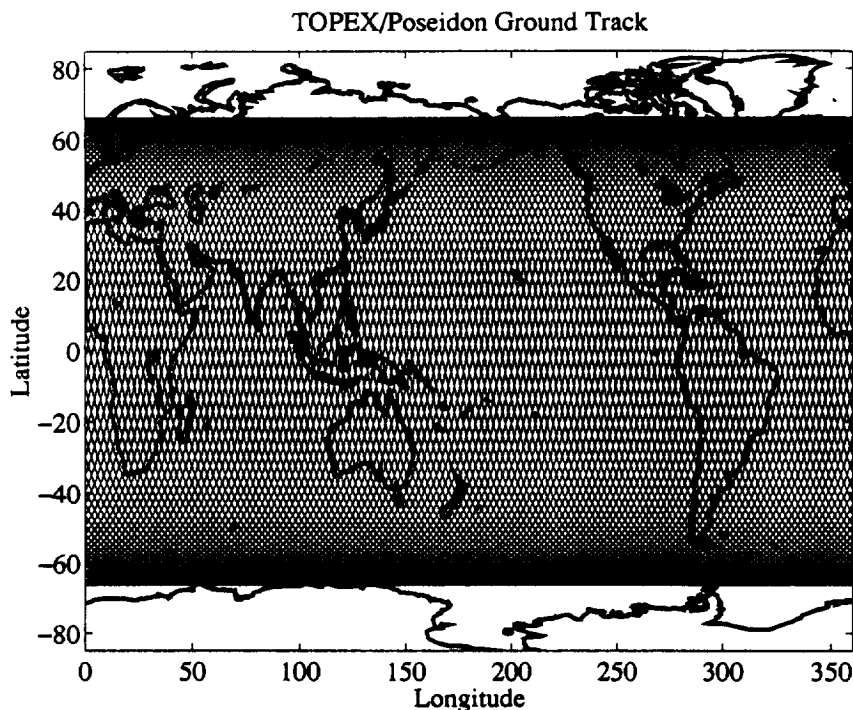


Fig. 4: The TOPEX/Poseidon radar altimeter satellite ground track measuring dynamic height variability with an error of about 5 cm. The orbit is repeated every 10 d, and the area of the grid spaces is approximately equal to a 330-km square at the equator. We estimate the potential accuracy of an ESTAR salinity measurement to be  $\sim 0.14$  psu if data at 10-km resolution and 3-d repeat are averaged to the TOPEX/Poseidon spatial and temporal resolution (see text). An ESTAR orbit would extend to about  $82^\circ$  latitude.

global sea level to an accuracy of  $\sim 5$  cm. SSS remote sensing is technically feasible and can deliver a precision of 0.1–0.3 psu on a spatial scale of about 100–300 km and a time scale of weeks to months.

Such a global data set would significantly advance climate research and provide data from large ocean regions presently unobserved. Global SSS monitoring would provide data to help close the hydrologic budget and constrain coupled climate models, monitor the upper ocean response to precipitation variability in the tropical convergence, and provide early detection of low-salinity intrusions in the subpolar Atlantic and Southern oceans. For example, the surface anomalies described by Dickson *et al.*, (1988) ranged from 0.1 to 1.0 psu on interannual time scales. The above analyses suggest that such variations would be detectable by a satellite sensor such as ESTAR and traceable over the evolution of the multi-year event. Such monitoring would allow years of advance notice to plan observations of the ensuing thermohaline variations as they propagate through intermediate and deep North Atlantic waters (e.g., Levitus, 1989; Delworth *et al.*, 1993).

It should be noted that much of the original motive for the ESTAR development came from requirements to measure soil moisture (Le Vine *et al.*, 1992). A significant effort has gone into devel-

... salinity remote sensing has significant promise at the resolution scales of satellite altimetry.

oping models for 1.4 GHz soil moisture measurements, which have a much wider  $T_b$  dynamic range ( $\sim 100^\circ\text{K}$ ) than salinity (Jackson *et al.*, 1982). An *ad hoc* technical review of ESTAR was convened in 1992 by NASA. The report recommended exploring an economical ESTAR satellite mission with the lesser restriction on accuracy demanded by soil moisture. Salinity requirements were considered too costly, but the report noted that data from a soil moisture mission should certainly be analyzed for salinity. A simplified 1.4 GHz sensor would lack the additional channels to correct for SST and wind over the ocean. In this case the requisite corrections could be obtained from operational and climate data bases, as well as Earth Observing System (EOS) sensors which will provide all-weather wind and SST data at useful resolution. Notwithstanding, a 1.4 GHz single-channel sensor with the  $1^\circ\text{K}$  accuracy requirement for soil moisture would serve as an important experiment to measure SSS. We see that an ESTAR mission can serve the needs of surface hydrology for most of the earth surface, providing surface data over land as well the ocean. Many of us recognize that the present funding climate is not favorable to new mission proposals, and ESTAR is not being actively promoted presently within NASA. Successful programs now often require support from several agencies or nations and need interdisciplinary scientific advocacy. As in the past, this implies broad recognition of the potential for new knowledge the measurements can provide and a commitment to develop the necessary technology. To move ESTAR forward, interested scientists must be made aware of its possibilities and become vocal advocates for serious consideration by the agencies. Our purpose here has been to give a candid assessment of the present state of the technology as a first step in that process.

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