



# National Research Council Dialogue to Assess Progress on Development of NASA's

# High Energy Power and Propulsion Capability Roadmap

**General Background and Introduction** 

Perry Bankston April 7, 2005



### **Agenda**



 General Background and Introduction of High Energy Power and Propulsion Capability Roadmap

**Agency Objective** 

**Strategic Planning Transformation** 

**Advanced Planning Organizational Roles** 

**Public Involvement in Strategic Planning** 

Strategic Roadmaps and Schedule

**Capability Roadmaps and Schedule** 

**Purpose of NRC Review** 

Capability Roadmap Development (Progress to Date)



## **Agency Goals and Objectives**



National Goal	Advance U.S. scientific, security an program.	d economic interests through a robust space exploration						
National Objectives	Implement a sustained and affordable human and robotic program to explore the solar system and beyond.	2. Extend human presence across the solar system, starting with a human return to the Moon by the year 2020, in preparation for human exploration of Mars and other destinations.						
	Undertake robotic and human lunar exploration to further science, and to develop and test new approaches, technologies, and systems to enable and support sustained human and robotic exploration of Mars and more distant destinations. First robotic mission no later than 2008. (SRM 1)	6. Return the Space Shuttle to flight and focus its use on completion of the ISS, complete assembly of the ISS, and retire the Space Shuttle as soon as assembly of the ISS is completed, planned for the end of this decade. Conduct ISS activities consistent with U.S. obligations to ISS partners. (SRM 6, 7)						
NASA Objectives	2. Conduct robotic exploration of Mars to search for evidence of life, to understand the history of the solar system, and to prepare for future human exploration. (SRM 2)	7. Develop a new crew exploration vehicle to provide crew transportation for missions beyond low Earth orbit. First test flight to be by the end of this decade with operational capability for human exploration NLT 2014. (SRM 5)						
	3. Conduct robotic exploration across the solar system for scientific purposes and to support human exploration. In particular, explore Jupiter's moons, asteroids and other bodies to search for evidence of life, to understand the history of the solar system, and to search for resources. (SRM 3)	8. Focus research and use of the ISS on supporting space exploration goals, with emphasis on understanding how the space environment affects human health and capabilities, and developing countermeasures. (SRM 6)						
	Conduct advanced telescope searches for Earth-like planets and habitable environments around other stars. (SRM 4)	9. Conduct the first extended human expedition to the lunar surface as early as 2015, but no later than the year 2020. (SRM 1)						
	Explore the universe to understand its origin, structure, evolution, and destiny. (SRM 8)	10. Conduct human expeditions to Mars after acquiring adequate knowledge about the planet using robotic missions and after successfully demonstrating sustained human exploration missions to the Moon. (SRM 2)						



## **Agency Goals and Objectives**



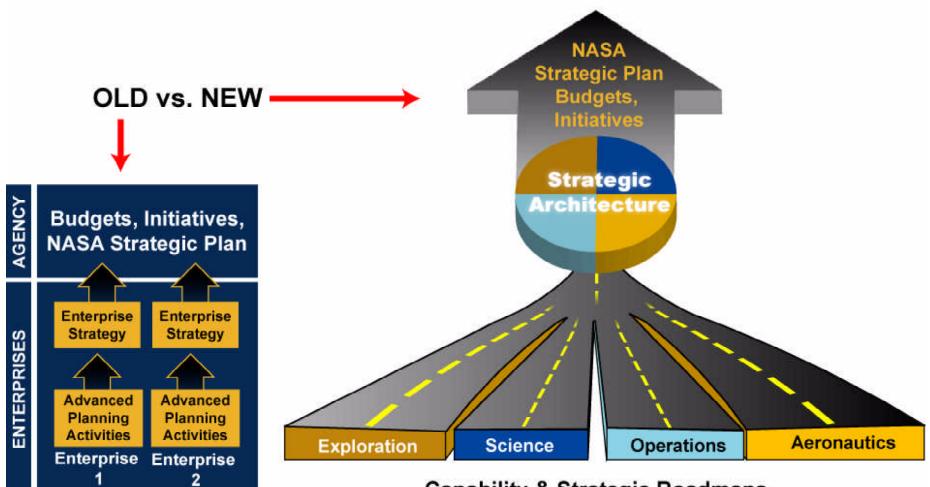
			dvanced lanning & integration.
National Goal0	Advance U.S. scientific, sec program.	curity and economic interests thro	ugh a robust space exploration
National Objectives	3. Develop innovative technologies, knowledge, and infrastructure both to explore and to support decisions about the destinations for human exploration.	4. Promote international and commercial participation in exploration to further U.S. scientific, security, and economic interests.	5. Study the Earth system from space and develop new space-based and related capabilities for this purpose.
	11. Develop and demonstrate power generation, propulsion, life support and other key capabilities required to support more distant, more capable, and/or longer duration human and robotic exploration of Mars and other destinations. (SRM 13 and Capability Roadmaps)	14. Advance scientific knowledge of the Earth system through space-based observation, assimilation of new observations, and development and deployment of enabling technologies, systems, and capabilities, including those with the potential to improve future operational systems. (SRM 9)	17. Pursue commercial opportunities for providing transportation and other services supporting International Space Station and exploration missions beyond Earth orbit. Separate to the maximum extent practical crew from cargo. (SRM 5, 6, 7)
NASA Objectives	12. Provide advanced aeronautical technologies to meet the challenges of next-generation systems in aviation, for civilian and scientific purposes, in our atmosphere and in the atmospheres of other worlds. (SRM 11)	15. Explore the Sun-Earth system to understand the Sun and its effects on Earth, the solar system, and the space environmental conditions that will be experienced by human explorers, and demonstrate technologies that can improve future operational Earth observation systems. (SRM 10)	18. Use U.S. commercial space capabilities and services to fulfill NASA requirements to the maximum extent practical and continue to involve, or increase the involvement of, the U.S. private sector in design and development of space systems. (SRM 5,6,7)
	13. Use NASA missions and other activities to inspire and motivate the nation's students and teachers, to engage and educate the public, and to advance the scientific and technological capabilities of the nation. (SRM 12)	16. Pursue opportunities for international participation to support U.S. space exploration goals. (All SRMs)	



### **Strategic Planning Transformation**



## **ACHIEVING THE VISION**

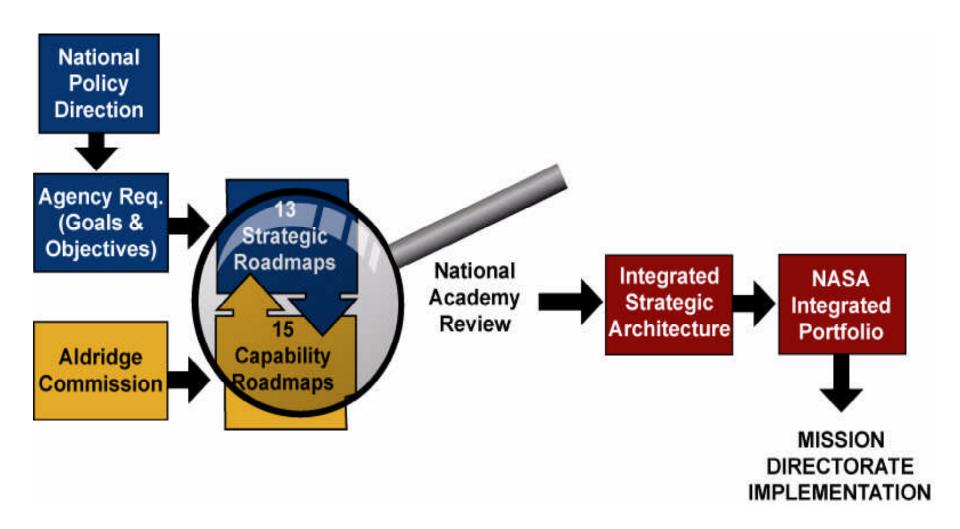


Capability & Strategic Roadmaps



# Strategic Planning Transformation - continued







## **Advanced Planning Organizational Roles**



- NASA Strategic Planning Council (Chair, NASA Administrator)
  - Agency-level strategic decisions & NASA Strategic Plan
- NASA Operations Council (Chair, NASA Deputy Administrator)
  - Implementation of strategies through integrated Agency tactical & operational activities
- Associate Deputy Administrator for Systems Integration (Mary Kicza)
  - Tracks & assesses integrated schedules, progress towards goals, Agency needs, strategic investments
- Director for Advanced Planning (Charles Elachi through 24 Mar 05)
  - Develops input, options, & assessments for Strategic Planning Council
- Advanced Planning & Integration Office (Dir. APIO, Bernie Seery)
  - Provides staff to the Director for Advanced Planning and the Associate Deputy Administrator for Systems Integration
- Mission Directorates (Craig Steidle, Al Diaz, Victor Lebacqz, William Readdy)
  - Technical knowledge & expertise to implement overall Agency architecture(s)



# Public Involvement in Strategic Planning



- NASA wants:
  - A broad community perspective when doing its strategic planning
  - Best strategies and most creative and innovative ideas from across the nation to implement the Vision
  - To provide opportunities for community input

RFI for Capability and Strategic Roadmap Input

Public workshop held in Washington DC on November 30<sup>th</sup> for Capability Roadmaps (509 people attended, 514 white papers submitted)

White Papers submitted for Strategic Roadmaps

Roadmap team members drawn from NASA, other Government Agencies, Academia, and Industry Review by the National Research Council (NRC) Presentations to professional societies, workshops, and conferences



### **Strategic Roadmaps**



- Strategic Roadmap
  - One of thirteen elements of the NASA Strategy that will explore options and establish pathways for implementing the Vision for Exploration.
- Roadmaps will include:
  - Broad human and robotic science and exploration goals, priorities, anticipated discoveries
  - High-level milestones, options, and decision
  - points
  - Implementation approaches, suggested
  - missions



## **Strategic Roadmaps - continued**



Roadmap	Chairs (HQ Directorate, Center)	External chair
Robotic and Human Lunar Exploration	Adm. (Ret.) Craig Steidle (HQ/ESMD) and William Readdy (HQ/SOMD) Gen. (Ret.) Jefferson Howell (JSC)	Gen. (Ret.) Tom Stafford
Robotic and Human Exploration of Mars	Al Diaz (HQ/SMD) Dr. Charles Elachi (JPL)	Tom Young (Lockheed Martin, Ret.)
Solar System Exploration	Orlando Figueroa (HQ/SMD) Scott Hubbard (ARC)	Dr. Jonathan Lunine (Uni. of Arizona)
Search for Earth-Like Planets	Dr. Ghassem Asrar (HQ/SMD) Dr. Charles Beichman (JPL)	Dr. Adam Burrows (Uni. of Arizona)
Exploration Transportation System	Adm. (Ret.) Craig Steidle (HQ/ESMD) Jim Kennedy (KSC)	Gen. (Ret.) Charles Bolden
International Space Station	Mark Uhran (HQ/SOMD) Bob Cabana (JSC)	Adm. (Ret.) Tom Betterton
Space Shuttle	Deferred	Deferred



## **Strategic Roadmaps - continued**



Roadmap	Chairs (HQ Directorate, Center)	External Chair
Universe Exploration	Dr. Anne Kinney (HQ/SMD) Dr. Nick White (GSFC)	Dr. Kathy Flanagan (MIT)
Earth Science and Applications from Space	Orlando Figueroa (HQ/SMD) Dr. Diane Evans (JPL)	Dr. Charles Kennel (UCSD/Scripps)
Sun-Solar System Connection	Al Diaz (HQ/SMD) Dr. Franco Einaudi (GSFC)	Dr. Timothy Killeen (NCAR)
Aeronautical Technologies	Terry Hertz (HQ/ARMD) None (Center)	James Jamieson (Boeing)
Education	Dr. Adena Loston (HQ/Office of Education) Dr. Julian Earls (GRC)	Dr. France Cordova (Uni. of Cal., Riverside)
Nuclear Systems	Adm. (Ret.) Craig Steidle (HQ/ESMD) Chris Scolese (GSFC)	Dr. John Ahearne (Duke Uni.)

**Directorate and APIO Coordinators Also with Each Team** 

= DoD Participation



# **Strategic Roadmaps Schedule**



Milestone	Nov	Dec	Jan	Feb	Mar	A	pr	May	Jun	Jul	Aug	Sep	Oct
Plan Approved and Co-chairs Signed Up													
Complete Team Formation, Begin Work													
Interim Roadmap Products													
Teams Mid-term Status Review													
Interim Roadmap Deliverable													
First Synthesis Workshop													
Roadmaps Submitted for NRC Review													
NRC Reviews Complete								_					
Second Synthesis Workshop										4			
NAC Workshop												7	
Integrated Strategic Architecture												_	



### **Capability Roadmaps**



Capability is defined as a <u>set of systems</u> (or system of systems) with associated technologies & knowledge that enable NASA to perform a function (e.g. scientific measurements) required to accomplish the NASA mission.

 Capability Roadmap is a description of the developments (including alternate paths and options) required to achieve the capability.



### **Capability Charter**



- NASA, in response to the Presidential Commission recommendations, will prepare roadmaps and related implementation plans that define national capabilities needed to meet the Agency's strategic roadmaps. The roadmap titles are based on the Presidential Commission's recommendation of seventeen technologies, updated by the NASA Strategic Council.
- The capability roadmap development process will be accomplished in two phases.
  - Phase 1 will be the development of capability roadmaps and associated technical products.
    - During this phase, technical experts both internal and external to NASA will provide the technical knowledge and expertise in the development of roadmaps which identify the capabilities that are needed to meet the missions of the Agency. The capability roadmap team will identify and analyze each of the associated technologies and assess the capability performance afforded by the current state of the art, the performance level needed by the strategic mission and trace the development required.
  - Phase 2 will be the development of Investment Plans.
    - During this phase, a NASA team will develop investment plans for the capability roadmaps. This team will be working to determine the critical capabilities that are identified on the roadmaps and to develop an investment plan for each individual roadmap area to include schedules and yearly budgets. The activity of the Investment Plan Teams consists of using the perspectives and values described by the Capability Roadmaps and selecting and then formulating an optimized development plan suitable for consideration by the Agency in its budget submissions.



# Method and Timing of Integrating Capability Roadmaps with Strategic Roadmaps



- Strategic roadmaps are being developed in parallel with the Capability roadmaps
  - Assumptions were made to begin the Capability roadmap development.

Created a missions assumptions framework Provided a set of design reference missions

- The Capability roadmaps being presented today are based on mission assumptions which will be updated by the agency strategic roadmap effort
- This dialogue review is, therefore, a work in progress
- Another NRC review in the June timeframe will include the integrated strategic and capability roadmap product



### **Process for Team Selection**



- Guidelines for Team Member Selection
  - Small teams of 12 -15 members with participation from:
    - 1/3 Industry
    - 1/3 NASA & other Government Agencies
    - 1/3 Academia
- Strategic Planning Council assigned roadmaps to Mission Directorate
- Mission Directorates assigned a NASA Chair with roadmap expertise
- NASA Chairs chose team members from industry, academia, other Government & within NASA who are recognized experts



## **Capability Roadmaps - continued**



Capability	NASA chair	External chair
High-Energy Power and Propulsion	Joe Nainiger (GRC)	Dr. Tom Hughes (Penn State Uni.)
In-Space Transportation	Paul McConnaughey (MSFC)	Col. Joe Boyles (US Air Force SMC)
Advanced Telescopes and Observatories	Lee Feinberg (GSFC)	Dr. Howard MacEwen (SRS Technologies)
Communication and Navigation	Bob Spearing (HQ/SOMD)	Michael Regan (DoD)
Robotic Access to Planetary Surfaces	Mark Adler (JPL)	Dr. Robert Braun (Georgia Tech)
Human Planetary Landing Systems	Robert Manning (JPL)	Dr. Harrison Schmitt
Human Health and Support Systems	Dennis Grounds (JSC)	Al Boehm (Ret, Hamilton-Sundstrand)
Human Exploration Systems and Mobility	Chris Culbert (JSC)	Dr. Jeff Taylor (Uni. of Hawaii)

**Directorate and APIO Coordinators Also with Each Team** 



## **Capability Roadmaps - continued**



Capability	NASA chair	External chair
Autonomous Systems and Robotics	Dr. Steve Zornetzer (ARC)	Doug Gage (Ret. DARPA)
Transformational Spaceport/Range	Karen Poniatowski (HQ/SOMD)	Gen. (Ret.) Jimmy Morrell Col. Dennis Hilley (OSD)
Scientific Instruments/Sensors	Rich Barney (GSFC)	Dr. Maria Zuber (MIT)
In Situ Resource Utilization	Jerry Sanders (JSC)	Dr. Mike Duke (Colorado School of Mines)
Advanced Modeling, Simulation, Analysis	Dr. Erik Antonsson (JPL)	Dr. Tamas Gombosi (Uni. Of Michigan)
Systems Engineering Cost/Risk Analysis	Steve Cavanaugh (LaRC)	Dr. Alan Wilhite (Georgia Institute of Technology)
Nanotechnology	Dr. Murray Hirschbein (HQ/ARMD) and Dr. Minoo Dastoor (HQ/ESMD)	Dr. Dimitris Lagoudas (Texas A&M)



# Capability Roadmap Development Schedule Overview



MILESTONE	Nov	Dec	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep
Begin Roadmap Teams Formation											
Public Workshop in Washington											
Working First Drafts of Roadmaps											
Strategic Planning Council Preview											
Engineering Academy (NRC) Dialogues											
Identify Potential Gaps for POP Input											
Strategic Roadmap Drafts Complete											
Align with Strategic Roadmaps											
Phase 2 - Engineering Academy (NRC) Summary Review						Г					
Brief Strategic Planning Council											
Finalize Roadmaps											



# **Integrated Capability Crosswalk**



															dvanced	lanning &
		2. High-energy power and propulsion	3. In-space transportation	4. Advanced telescopes and observatories	5.Communication & Navigation	6. Robotic access to planetary surfaces	7. Human planetary landing systems	8. Human health and support systems	Human exploration systems and mobility	10. Autonomous systems and robotics	11. Transformational spaceport/range technologies	12. Scientific instruments and sensors	13. In situ resource utilization	14. Advanced modeling, simulation, analysis	15. Systems engineering cost/risk analysis	16. Nanotechnology
	<ol><li>High-energy powers</li><li>and propulsion</li></ol>															
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	4. Advance															
	5. Cor		rvatorie ation &	Navigat												
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	6. R0	botic ac	cess to	planeta	iry surfa											
		7. Hu	ıman pl	anetary	landing	system										
			8. Hu	man he	alth and	suppor	tsystem									
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		Samo	element			10		l mobility nous sy								
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	Critical Relatio		lepende enabling)			11.	Transfo	rmation	al space tech	port/ran nologie:						
	Moderate Relation	ship (er	nhancing				12.	Scientif i								
			ergistic) ationship						13. <i>li</i>	n situ re	source	utilizatio				
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													16. N	anotech	nology	
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# HEP&P Capability Crosswalk



															- tunning u
	2. High-energy power and propulsion	3. In-space transportation	4. Advanced telescopes and observatories	5.Communication & Navigation	6. Robotic access to planetary surfaces	7. Human planetary landing systems	8. Human health and support systems	9. Human exploration systems and mobility	10. Autonomous systems and robotics	11. Transformational spaceport/range technologies	12. Scientific instruments and sensors	13. In situ resource utilization	14. Advanced modeling, simulation, analysis	15. Systems engineering cost/risk analysis	16. Nanotechnology
2. High-energy power															
and propulsion 3. In-space transpo	ortation														
4. Advanced		s and vatories													
5. Com	municatio		gation												
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	7 Hu	man nlane	etary landi	na system	<u> </u>										
	7.110	•	•	•											
		8. Hun	nan health	and supp	ort syster	ns									
				9. Human exploration systems											
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							-	robotics							
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				15. Systems engineering cost/risk analysis											
No Relationship				16. Nanotechnology											



# Capability Crosswalk Details(Ex)



High Energy Power and Propulsion Capability
Flow and
Criticaltiy

**Related Roadmap** 

**Nature of Relationship** 

materials, etc.

Sub-Topic or Subsidiary Capability	Sub-Topic or Subsidiary Capability	
	Human Exploration Systems & Mobi	<u>lity</u>
Surface Power (PV/Radioisotope)	Crew Mobility/Surface rovers	Power sources required for crev surface rovers
Surface Power (PV/nuclear fission)	In-Space Assembly Large & Intermediate Scale Assy Sys	High Power needed for cranes,
	In Situ Resource Utilization	
Surface Power (PV/nuclear fission)	Resource Extraction; excavation, drilling Resource Processing; consumable(O2), feedstock, etc. production In situ manufacturing	
	Human Health & Support Systems	<u>.</u>
Component Technologies; Batteries, PMAD	Life Support & Habitation; EVA(Portable Support Systems)	lAdvanced batteries; efficient power supplies
Surface Power(PV/nuclear fission)	Life Support & Habitation; Advanced life support, habitats	High power systems will be needed to support human activities
	<u>Nanotechnology</u>	
Component Technologies	Advanced Nano-Scale Materials & Conce for Nano-Scale Devices; Nano-to-Micro Systems Integration	



### **Purpose of NRC Review**



 NASA wants the National Research Council (NRC) to review Capability Roadmap products and assess progress in four areas:

### Four NRC Questions:

Do the Capability Roadmaps provide a clear pathway to (or process for) technology and capability development?

Are technology maturity levels accurately conveyed and used? (Note: Maturity levels will be evaluated using Technology Readiness Levels (TRLs) and Capability Readiness Levels (CRLs) or other appropriate methodologies)

Are proper metrics for measuring advancement of technical maturity included?

- Do the Capability Roadmaps have connection points to each other when appropriate?



# **Technology Readiness Levels**



9	Actual System Proven in Operation
8	Actual System Qualified by Demonstration
7	System Prototype Demonstration in an Operational Environment
6	System/Subsystem Model or Prototype Demonstration in a Relevant Environment
5	Component and/or Breadboard Validation in a Relevant  Environment
4	Component and/or Breadboard Validation in a Laboratory Environment
3	Analytical and Experimental Critical Functions Characteristic Proof-of-Concept
2	Technology Concept and/or Application  Formulated
1	Basic Principles Observed and Reported



## **Capability Readiness Levels**



7	Capability Operational Readiness
6	Integrated Capability Demonstrated in an Operational Environment
5	Integrated Capability Demonstrated in a Relevant Environment
4	Integrated Capability Demonstrated in a Laboratory Environment
3	Sub-Capabilities* Demonstrated in a Relevant Environment
2	Sub-Capabilities* Demonstrated in a Laboratory Environment
1	Concept of Use Defined, Capability, Constituent Sub-capabilities* and Requirements Specified

A Capability is defined as a <u>set of systems</u> (or system of systems) with associated technologies & knowledge that enable NASA to perform a function (e.g. scientific measurements) required to accomplish the NASA mission.





# **Back-up charts**



### **Capability Readiness Levels Defined**



#### CRL 1: Concept of Use Defined, Capability, Constituent Sub-capabilities\* and Requirements Specified

 The Capability is defined in written form. The use/application of the Capability is described in a concept paper. The uses are speculative, and no proof or detailed analysis exists to support the concept. The constituent Sub-capabilities and requirements of the Capability are specified.

#### • CRL 2: Sub-Capabilities\* Demonstrated in a Laboratory Environment:

 A Proof-of-Concept analysis of the Capability is performed. Analytical and laboratory studies of the Sub-capabilities are performed to physically validate separate elements of the Capability. Analytical studies are performed to determine how constituent Sub-capabilities will work together.

#### • CRL 3: Sub-Capabilities\* demonstrated in a Relevant Environment:

- Sub-capabilities are demonstrated with realistic supporting elements to simulate an operationally relevant environment (e.g. to the Capability).
  - of appropriate scale
  - functionally equivalent flight articles
  - major system interactions identified
- Limited analytical modelling of the integrated Capability can be performed.

#### CRL 4: Integrated Capability Demonstration in a Laboratory Environment

A representative model or prototype of the integrated Capability is tested in a laboratory environment. Performance of the
constituent Sub-capabilities are observed in addition to the Capability as an integrated system. are specified.

#### CRL 5: Integrated Capability Demonstration in a Relevant Environment

- An integrated prototype of the Capability is demonstrated with realistic supporting elements to simulate an operationally relevant environment (e.g. to the Capability).
  - of appropriate scale
  - actual flight articles
  - all system interactions identified

#### CRL 6: Integrated Capability Demonstration in an Operational Environment

- The Capability is near or at the completed system stage. This level represents the demonstration of an integrated Capability in an operational environment with representatives of the intended user organization(s).
- -full scale flight articles
- -demonstration in appropriate operational 'envelope'

#### CRL 7: Capability Operational Readiness

The Capability has been proven to work in its final form and under expected operational conditions. This level represents
the application of the Capability in its operational configuration and under "mission" conditions.