



# **5.0 Aerodynamic and Propulsive Decelerator Systems**

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# Presentation Outline



## **Part I - Introduction**

- Capability Breakdown Structure
- Decelerator Functions
- Candidate Solutions

## **Part II - Performance and Technology**

- Capability State-of-the-Art
- Performance Needs
- Candidate Configurations

## **Part III - Possible Technology Roadmaps**

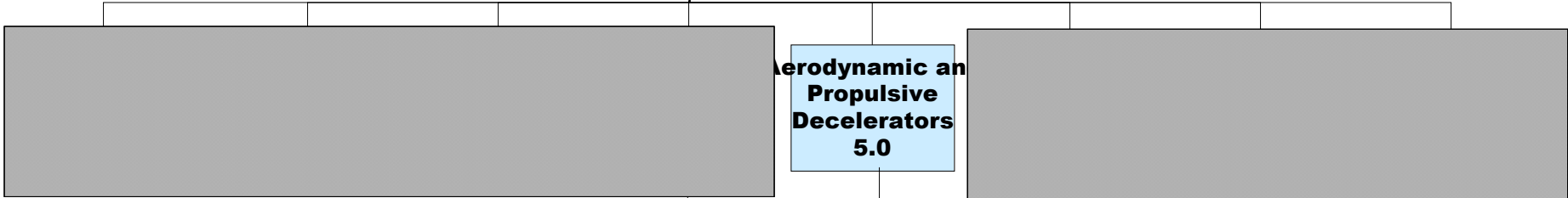
- Capability Roadmaps



# Capability Breakdown Structure



## Human Planetary Landing Systems CRM # 7

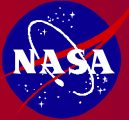


- 5.1 Supersonic Aerodynamic Decelerators**
- 5.2 Subsonic Aerodynamic Decelerators**
- 5.3 Supersonic Propulsive Decelerators**
- 5.4 Systems Design, Development, Testing, and Qualification**



**Decelerators typically provide one or more of the following functions in planetary landing systems:**

- **Deceleration from supersonic to subsonic speed**
- **Controlled acceleration**
- **Minimize descent rate**
- **Provide specified descent rate**
- **Provide stability (parachute drogue function)**
- **System deployment (parachute pilot function)**
- **Provide difference in ballistic coefficient for separation events**
- **Provide height**
- **Provide timeline**
- **Provide specific state (e.g., altitude, location, speed for precision landing)**



# Aerodynamic and Propulsive Decelerator Capabilities for Mars - Integrated Mission Architecture



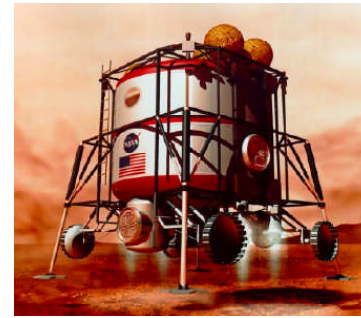
Options for Hypersonic Decelerators



Parachutes



Inflatable Decelerators



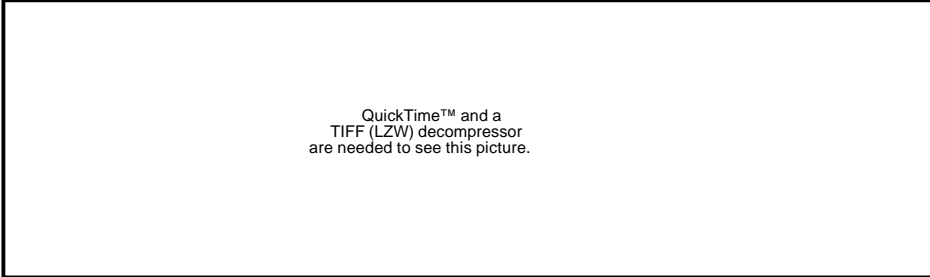
Propulsion

Options for Supersonic & Subsonic Decelerators

Options for Terminal Descent Systems



# 5.0 Aerodynamic and Propulsive Decelerator Candidate Solutions

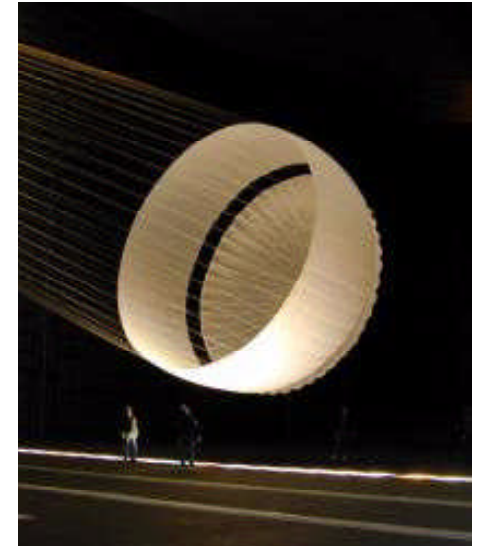


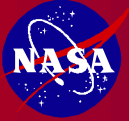
	Candidate Mission Scenario	Candidate Solutions
Mars Descent	Mars human and cargo landing	Supersonic parachutes, subsonic parachute clusters Inflatable decelerators Supersonic and subsonic propulsion <u>Combination</u>
Earth Return (Mars)	Human direct entry or landing from orbit	Subsonic parachute cluster Parafoils Lifting body/wings
Earth Return (Lunar)	Human direct entry or landing from orbit	Subsonic parachute cluster Parafoils Lifting body/wings



## Supersonic Parachutes

- **Disk-Gap-Band (DGB) heritage parachutes**
- **Deployment at Mach number  $M \bullet 2.1$  (Viking heritage)**
- **Deployment at dynamic pressure  $q \bullet 800$  Pa (MER heritage)**
- **Nominal diameter,  $D_0 \bullet 16.15$  m (Viking heritage)**
- **Maximum drag area,  $C_D S \bullet 108$  m<sup>2</sup> (approximate for Viking parachute with  $D_0 = 16.15$  m at  $M = 2.1$ )**
- **No reefing, clustering, or glide control**
- **Mortar deployment**

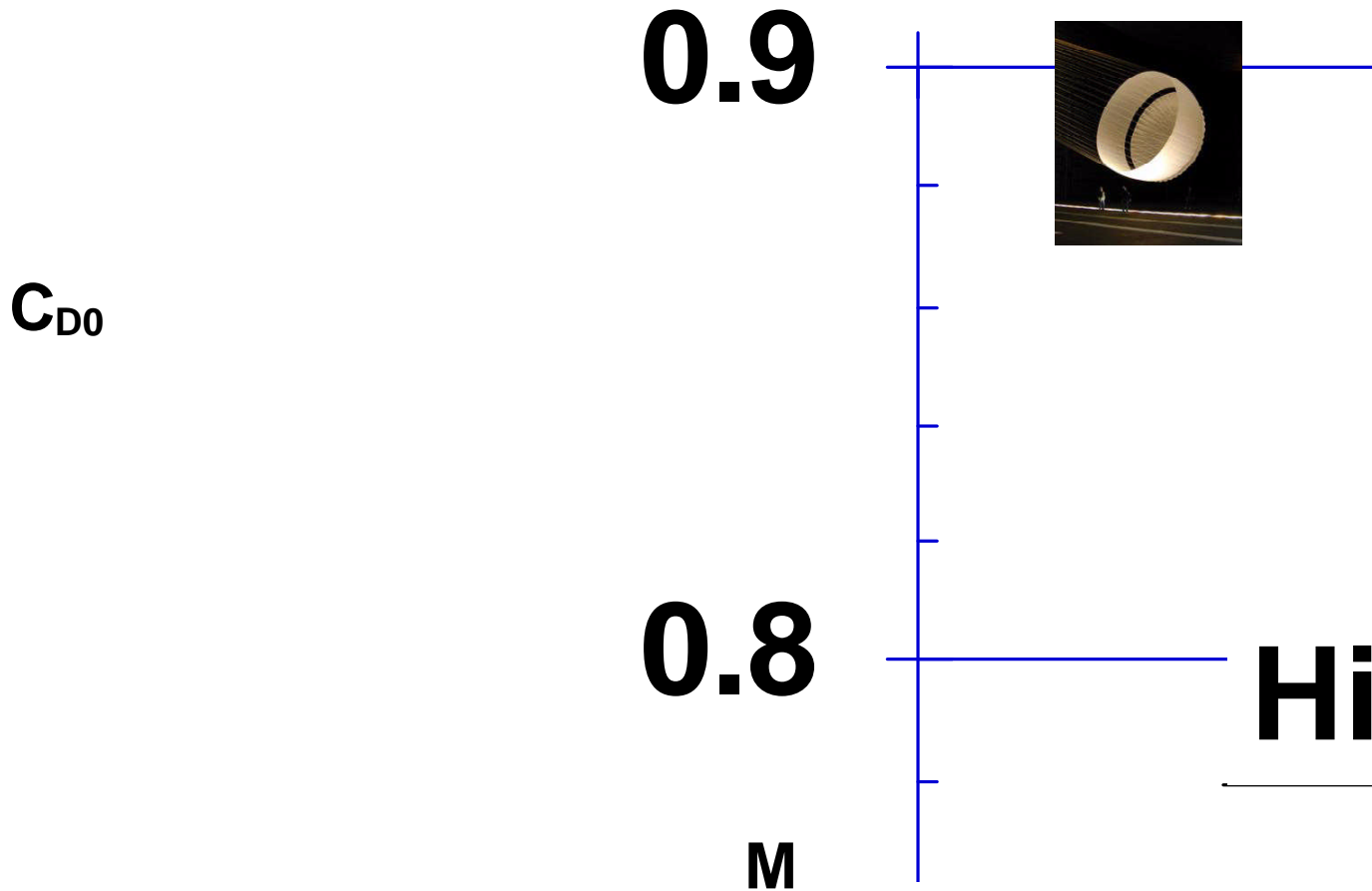




# Current Mars Aerodynamic Decelerator Technology Capabilities and Limitations



## Viking DGB Parachute Drag Model







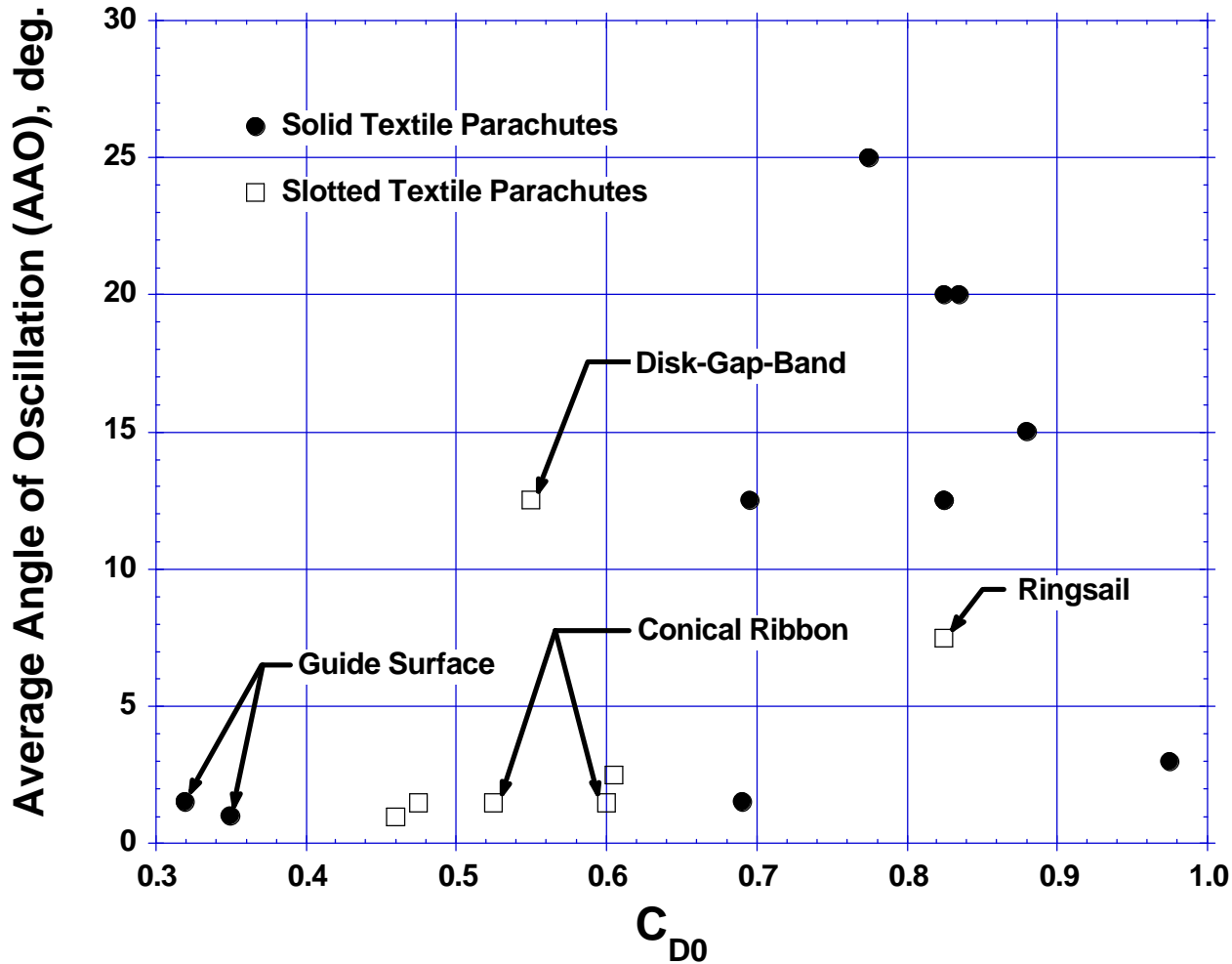
## Subsonic Parachutes

- **DGB heritage parachutes (see supersonic parachutes)**
  - Maximum drag area,  $C_D S \bullet 139 \text{ m}^2$
- **Ringsail heritage parachutes**
  - Beagle 2, MTP Subsonic Parachute, extensive Earth-flight experience (e.g., Mercury, Gemini, Apollo)
  - Deployment at Mach number  $M \bullet 0.8$  (MTP Subsonic Parachute)
  - Nominal diameter,  $D_0 \bullet 33.5 \text{ m}$  (MTP Subsonic Parachute)
  - Maximum drag area,  $C_D S \bullet 679 \text{ m}^2$
  - Reefing
  - No clustering or glide control





## Drag vs Stability Comparison





## Inflatable Supersonic Decelerators

- No inflatable supersonic decelerators have been flown in planetary exploration missions
- Several concepts proposed, some tested
- Some concepts show promise

## Materials

- Kevlar, Nylon, Polyester (Dacron) are “qualified” materials
- Vectran, Spectra, Technora, Nextel, Zylon now used in some “qualified” applications
- Coated materials (impermeable, ablative) have been used for munitions programs



## Analysis Methods

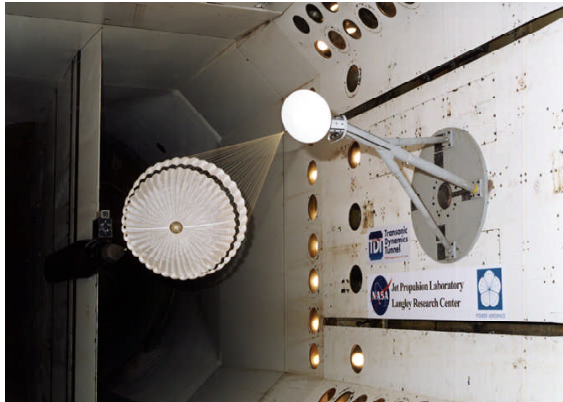
- Current methods have a significant empirical component (need data to calibrate)
- First-principle methods (e.g., Fluid Structures Interaction analyses) are available but validation is lacking
- Scaling of results (physical size and test conditions) possible but poorly understood

## Test Methods

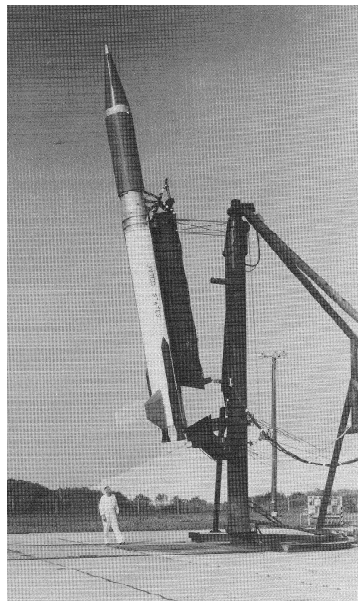
- Need improvements in our ability to adjust results of all testing to other scales and different conditions
- Wind tunnel testing (sub-scale and full-scale)
  - Available facilities at risk of closing
- Low altitude flight testing (subsonic)
- High altitude flight testing (supersonic and subsonic)
  - Sounding rocket
  - Balloon
  - Balloon/Rocket



# Current Earth and Mars Aerodynamic Decelerator Technology Capabilities and Limitations



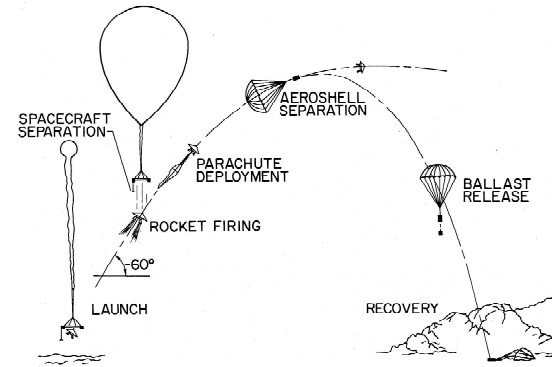
**Sub-Scale Wind Tunnel Testing**



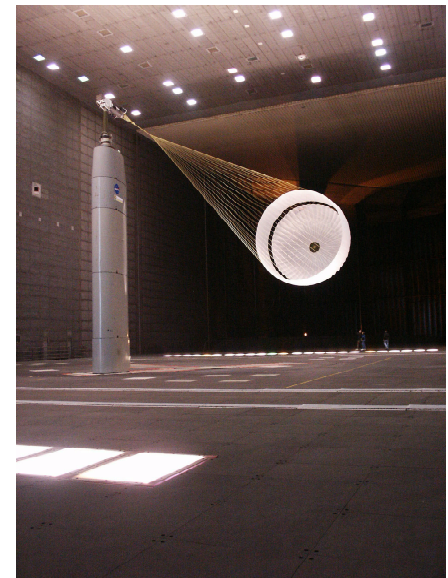
**Sounding Rocket**



**Full-Scale Flight Testing**



**Balloon/Rocket**



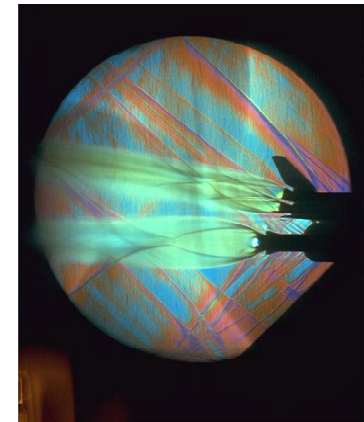
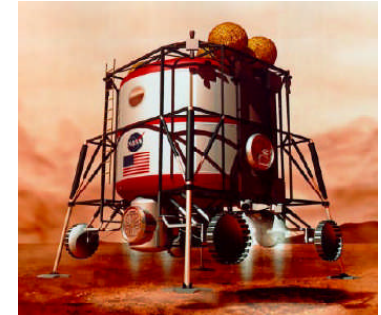
**Full-Scale Wind Tunnel Testing**



# Mars Propulsive Decelerators



- **Supersonic deceleration at Mars may require a propulsive component**
  - An aerodynamic-decelerator only solution may not be realistic (extremely large parachutes)
- **Use of retrorockets to decelerate from supersonic to subsonic speeds has issues**
  - Initiation of thrusting is likely to require blow-out covers in TPS
    - MER TIRS motor covers are a primitive example
  - Thermal protection must be provided while vehicle is enveloped in high enthalpy recirculating exhaust
  - Plume / freestream interaction will be fundamentally unsteady
    - Freestream Mach number and dynamic pressure change rapidly
    - Rapidly changing aerodynamic forces on aeroshell will require significant control authority, especially in the transonic regime
- **Development of modeling capability for this “inverse base flow” problem will be likely require subscale wind tunnel tests and flight testing.**





## Supersonic-to-Subsonic Deceleration

- Larger aero decelerator drag area ( $C_D S$ ) at supersonic speeds
- Aero decelerator drag area control at supersonic speeds (loads and trajectory)
- Aero decelerator deployment at Mach number  $> 4$
- Propulsive supersonic deceleration

## Subsonic Terminal Descent

- Larger aero decelerator drag area ( $C_D S$ ) at subsonic speeds
- Large propulsive descent system

## Pinpoint Landing Capability

- Ability to make parachute glide in a chosen direction
- Propulsive descent system guidance and hazard avoidance



## Fluid-Structures Interaction Analyses

- **Joining of Computational Fluid Mechanics (CFD) with structural Finite Element Methods (FEM)**
- **Allows for numerical design optimization**
- **Can yield insight on scaling of test results (physical size and test conditions)**
- **Can yield values of quantities usually obtained by test (e.g.,  $C_{D0}$ )**
- **Can yield values of quantities that are difficult to obtain by test (e.g., dynamic aero coefficients -  $C_{mq}$ )**
- **Has possibility of reducing testing and qualification costs by decreasing number of tests**
- **Works with trend of cheaper computing**
- **In need Verification (are we solving the equations right?) and Validation (are we solving the right equations?) to obtain level of trust suitable for exploration missions**
- **Must-have technology**





# Earth and Mars: Aerodynamic Decelerators Technology Needs



## Scaling

- Ability to scale test results to the system size and test conditions
- May allow for relevant sub-scale testing of systems in flight at supersonic conditions
- Must-have technology for large Mars systems

## Testing

- Adequate wind tunnel and flight test (e.g., high-altitude balloons, sounding rockets) capabilities must be retained and in some cases expanded
- Capability to flight test supersonic systems will become a necessity for Mars systems

## Materials

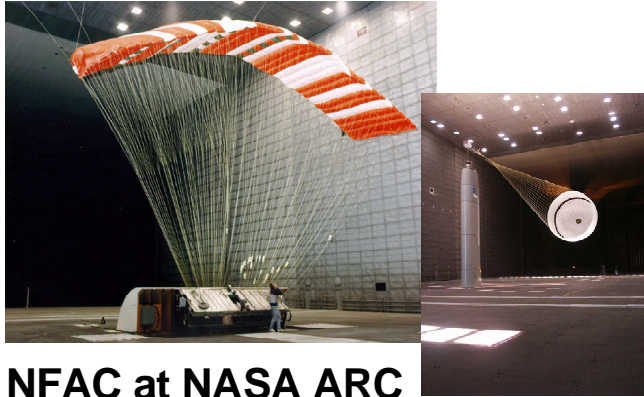
- Development of new space-qualified materials will have a significant impact on aerodynamic decelerator design (i.e., mass to drag area ratio)
- Materials with high temperature capabilities for parachutes ( $M > 2.5$ ) and inflatable decelerators will be required



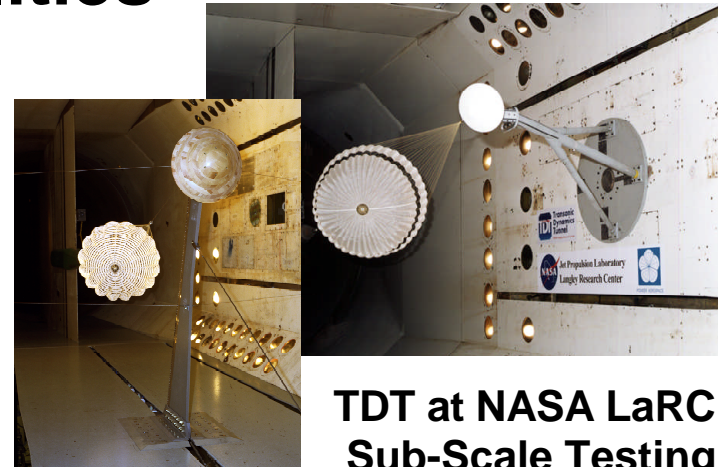
# Earth and Mars: Aerodynamic Decelerators Technology Needs



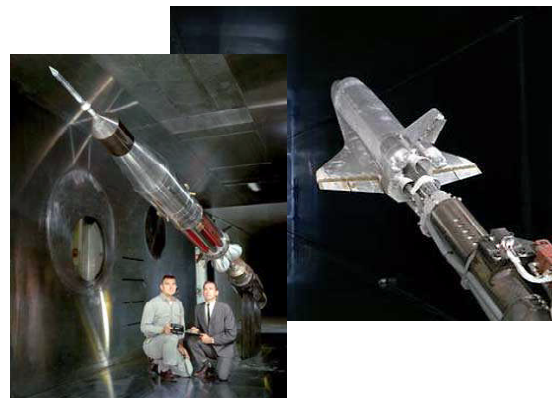
## Key Wind Tunnel Testing Facilities



**NFAC at NASA ARC**  
Full- and Sub-Scale Testing  
Subsonic



**TDT at NASA LaRC**  
Sub-Scale Testing  
Subsonic and Transonic



**10' x 10' Supersonic at NASA GRC**  
Sub-Scale Testing Supersonic

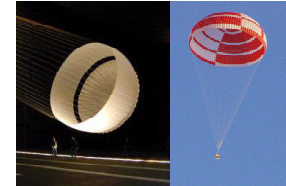


# Possible Mars Configurations



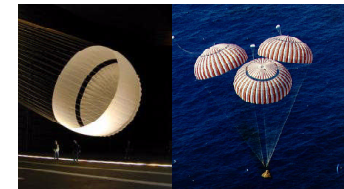
## 2 Metric Ton Entry Mass Level

Disk-Gap-Band Supersonic Parachute  
Ringsail Subsonic Parachute (single canopy)



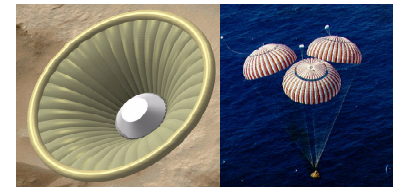
## 4 Metric Ton Entry Mass Level

Disk-Gap-Band Supersonic Parachute (reefed)  
Ringsail Subsonic Parachute (cluster)



## 10 Metric Ton Entry Mass Level

Inflatable Supersonic Decelerator  
Ringsail Subsonic Parachute (cluster)

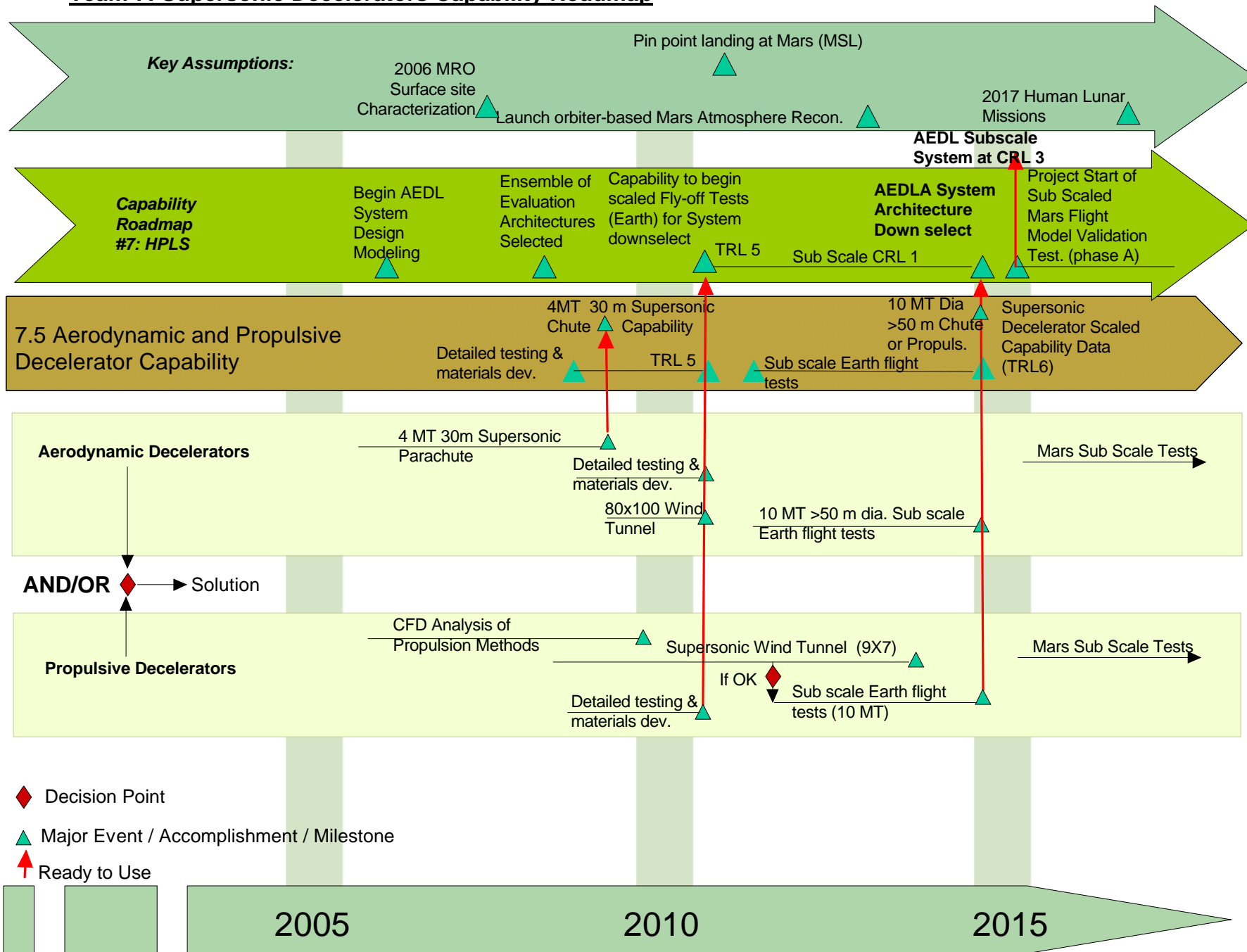


## 50 Metric Ton Entry Mass Level (Human)

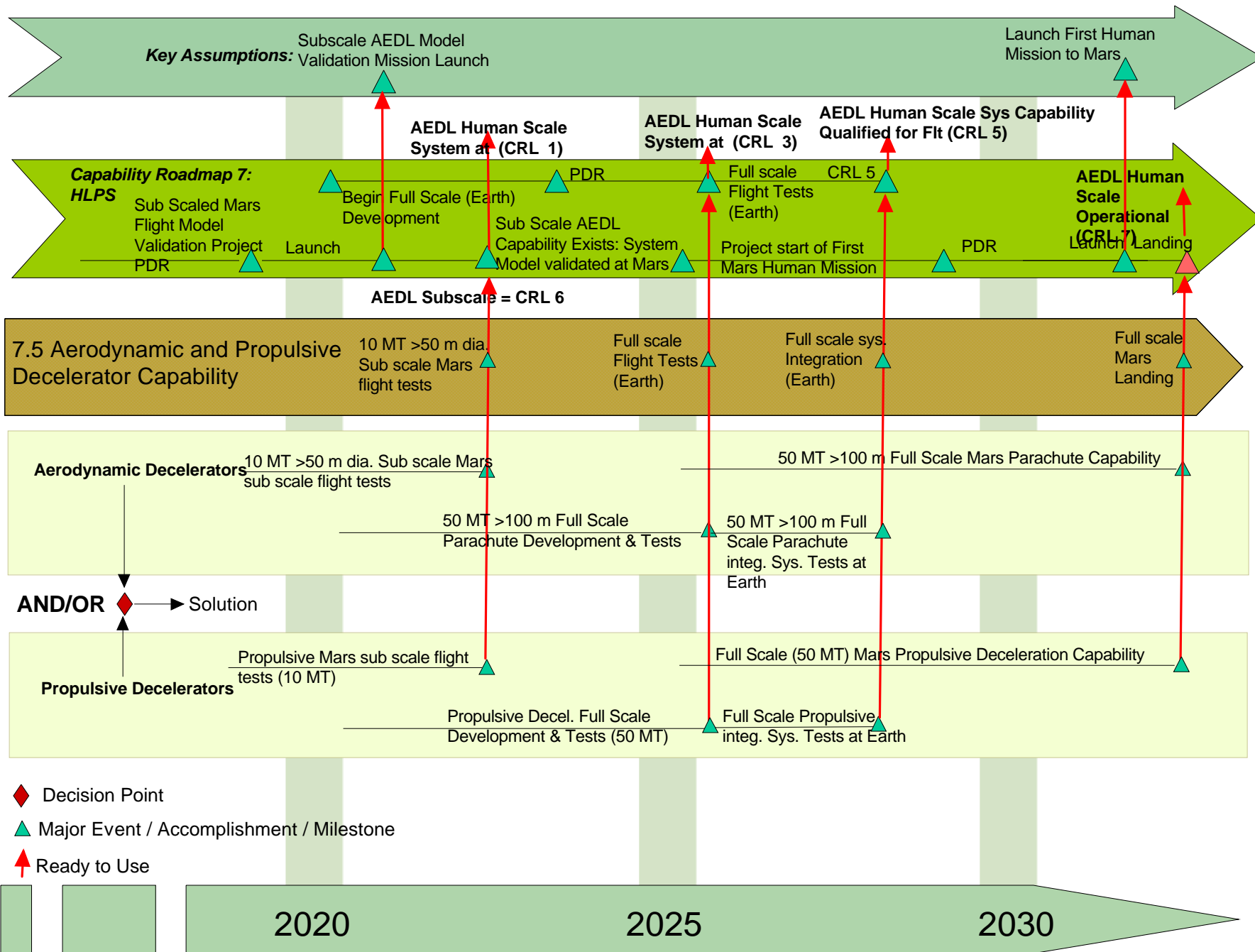
Inflatable Supersonic Decelerator  
Ringsail Subsonic Parachute (cluster)  
Propulsion Assisted Deceleration



# Team 7: Supersonic Decelerators Capability Roadmap



# Team 7: Supersonic Decelerators Capability Roadmap





# Backup Material



# Symbols and Acronyms



## Symbols

$C_{D0}$	drag coefficient
$C_{DS}$	drag area
$C_{mq}$	derivative of pitching moment with respect to pitch rate
$D_0$	nominal diameter
$M$	Mach number
$q$	dynamic pressure

## Acronyms

AAO	Average Angle of Oscillation
ARC	Ames Research Center
CFD	Computational Fluid Dynamics
DGB	Disk-Gap-Band
FEM	Finite Element Method
FSI	Fluid Structures Interaction
GRC	Glenn Research Center
LaRC	Langley Research Center
MER	Mars Exploration Rover
MT	Metric Ton
MTP	Mars Technology Program
NFAC	National Full-Scale Aerodynamics Complex
TDT	Transonic Dynamics Tunnel
V&V	Verification and Validation
WT	Wind Tunnel