

Fast Approximate Broadband Phase Retrieval for Segmented Systems

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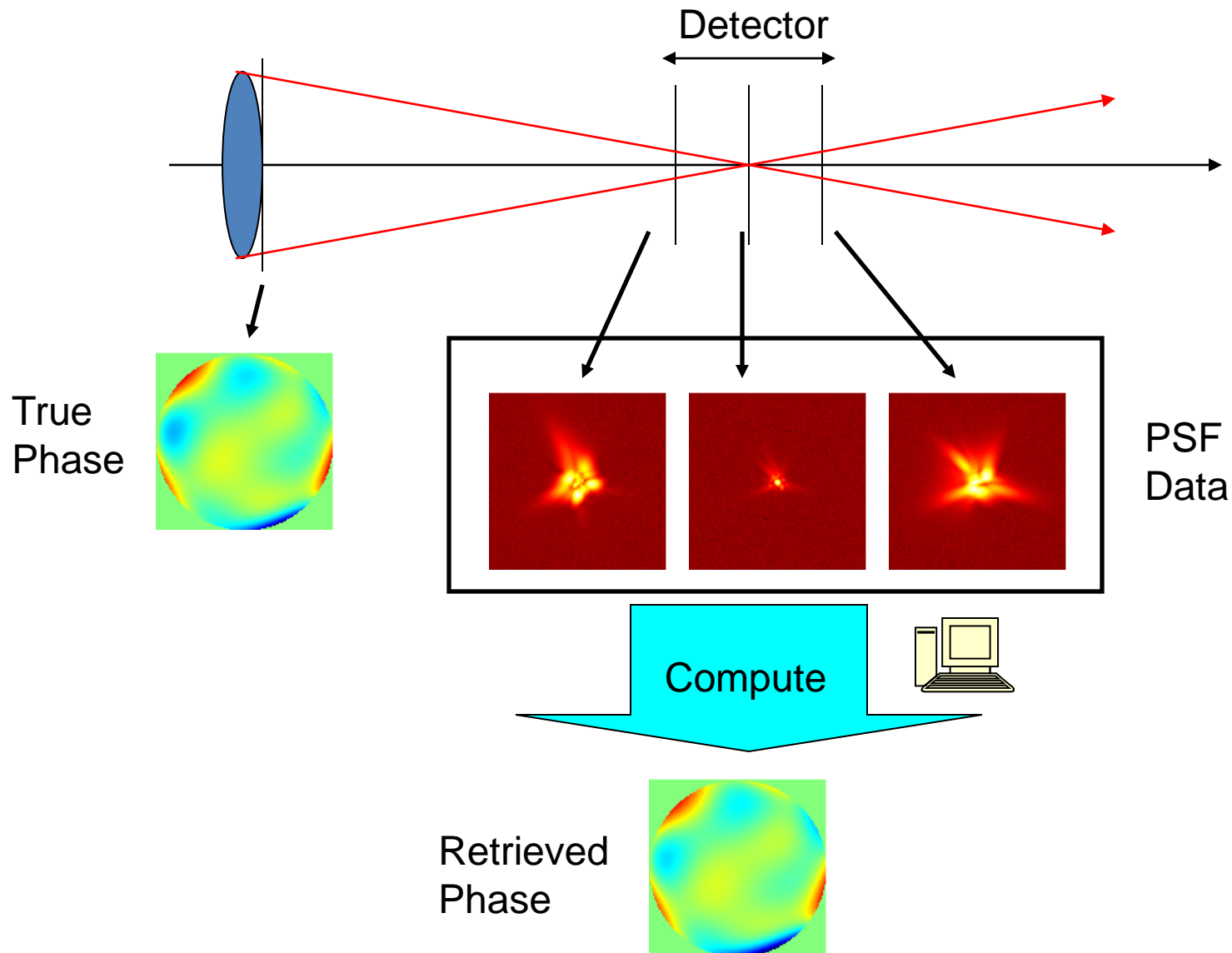
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- Application: Wavefront sensing for large telescopes
 - Space telescopes (James Webb Space Telescope)
 - Adaptive Optics for ground based telescopes
- Wavefront sensing method: Focus diverse phase retrieval
- Case of interest: Extremely broadband sources
- Problem
 - Monochromatic phase retrieval algorithms fail above ~10% fractional bandwidth
 - Broadband (polychromatic) algorithms are computationally expensive
- Solution
 - Employ monochromatic algorithm with approximation method
- Result
 - 270x speed up in computational performance for 133% fractional bandwidth
 - Acceptable accuracy
 - Accuracy better for monolithic systems, worse for segmented
- Investigate difference in accuracy between segmented and monolithic systems

Focus Diverse Phase Retrieval



- Given
 - System parameters ($F/\#$, detector pixel pitch, etc.)
 - Measured point spread function images (e.g. images of stars) through focus
 - Clear aperture of pupil
- Determine
 - Wavefront error in the exit pupil of the system (phase)
- Issues
 - Optical fields are complex-valued quantities
 - Measured data (intensity) has only magnitude, no phase
 - Measured data corrupted with noise
- Solution strategies
 - Gerchberg-Saxton / iterative transform type algorithms
 - Non-linear optimization type algorithms

- Parameterize problem in terms of a set of variables (e.g. Zernike coefficients)
- Generate wavefront (W) and/or field from parameters
- Propagate field to PSF plane
- Use an error metric to evaluate agreement between model and data¹
- Use standard non-linear optimization algorithm to reduce error metric value
- Analytic expressions for error metric gradients allow use of gradient search algorithms

$$E(W) = \frac{1}{K} \frac{\sum_k \left[\alpha_k I_k(u) + \beta_k - D_k(u) \right]^2}{\sum_u \left[D_k(u) \right]^2}$$

Diagram labels for the error metric equation:

- Gain**: points to α_k
- Bias**: points to β_k
- Model**: points to $I_k(u)$
- Data**: points to $D_k(u)$

$$I_k(u) = \left| F \left[A(x) \exp \left(\frac{2\pi}{\lambda} W(x) \right) \right] \right|^2$$

(simplified)

¹S. T. Thurman and J. R. Fienup, "Phase retrieval with signal bias," J. Opt. Soc. Am. A 26, 1008–1014 (2009).

- Use cases for broadband phase retrieval
 - Narrow spectral filters unavailable
 - Dim sources
 - Low throughput due to misalignment
 - Short exposures times
 - Pointing instability (space)
 - Atmospheric instability (ground based AO)
 - Segment piston determination
- Traditional approach^{1,2}
 - Simulate multiple individual wavelengths
 - Rule of thumb: 1 wavelength per 5% fractional bandwidth
 - Add incoherently to simulate polychromatic PSF
 - Do normal nonlinear optimization phase retrieval

¹ J. R. Fienup, "Phase retrieval for undersampled broadband images," J. Opt. Soc. Am. A **16**, 1831–1837 (1999).

² G. R. Brady and J. R. Fienup, "Effect of broadband illumination on reconstruction error of phase retrieval in optical metrology," Proc. SPIE 6617, 66170I (2007).

- Fine for modest bandwidth
- Very computationally intensive for large bandwidths
 - More wavelengths \rightarrow more computation
 - Linear in number of wavelengths
 - Shorter wavelengths \rightarrow larger arrays \rightarrow more computation
 - Pupil sampling requirement
 - Avoid π phase jumps
 - Phase for given OPD increases with shorter wavelength
 - Array size inversely proportional to wavelength
 - Cost approximately quadratic in array size

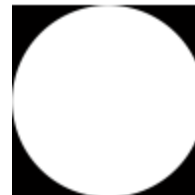
Monochromatic Pupil

3 μm , 128x128



Broadband Pupil

1-5 μm , 384x384



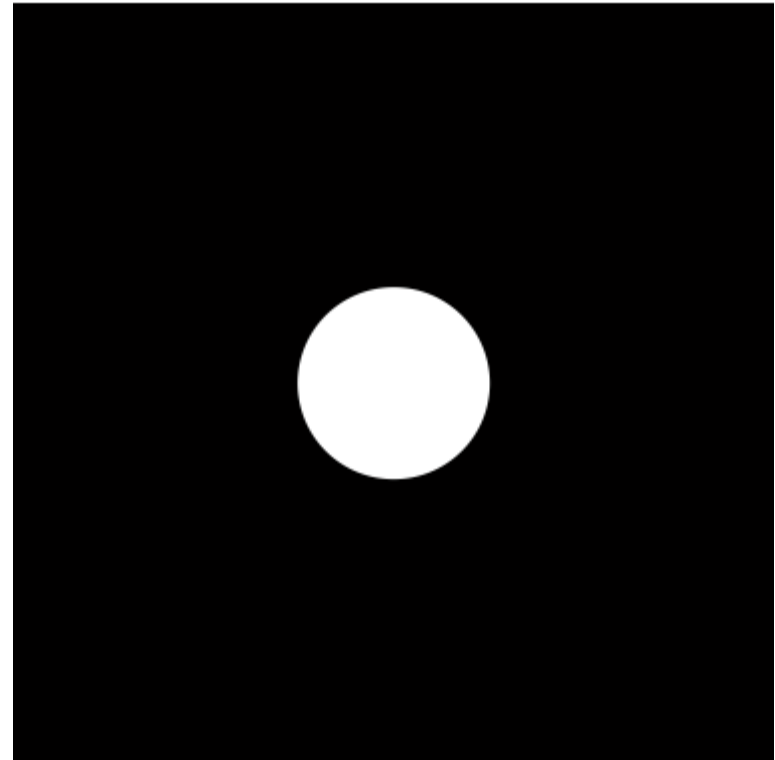
Array Sizes

- Shorter / longer wavelengths → under / over sampling
→ more computation

- PSF initially computed on large array
- Requires padding in pupil domain

Broadband Pupil
(largest) 1518x1518

Monochromatic Pupil
342x342



- Achromatic system
 - Reflecting telescopes
 - Color corrected instruments
- OPD / rays the same at all wavelengths
- Geometrical optics spot diagram the same at all wavelengths
- For poorly corrected systems geometrical optics should predict PSF shape
- PSF shape should be roughly the same at all wavelengths
- Only high frequency diffraction effects depend strongly on wavelength

Approximation Procedure

- Data D , blurring kernel B , forward model F , wavefront W , K image planes
- Blur measured PSF data with Gaussian kernel (suppress diffraction effects)

$$D_{B,k} = B \otimes D_k$$

- Simulate monochromatic PSF at the center wavelength

$$I_k = F_{\lambda,k}[W]$$

- Blur modeled PSF with same Gaussian kernel

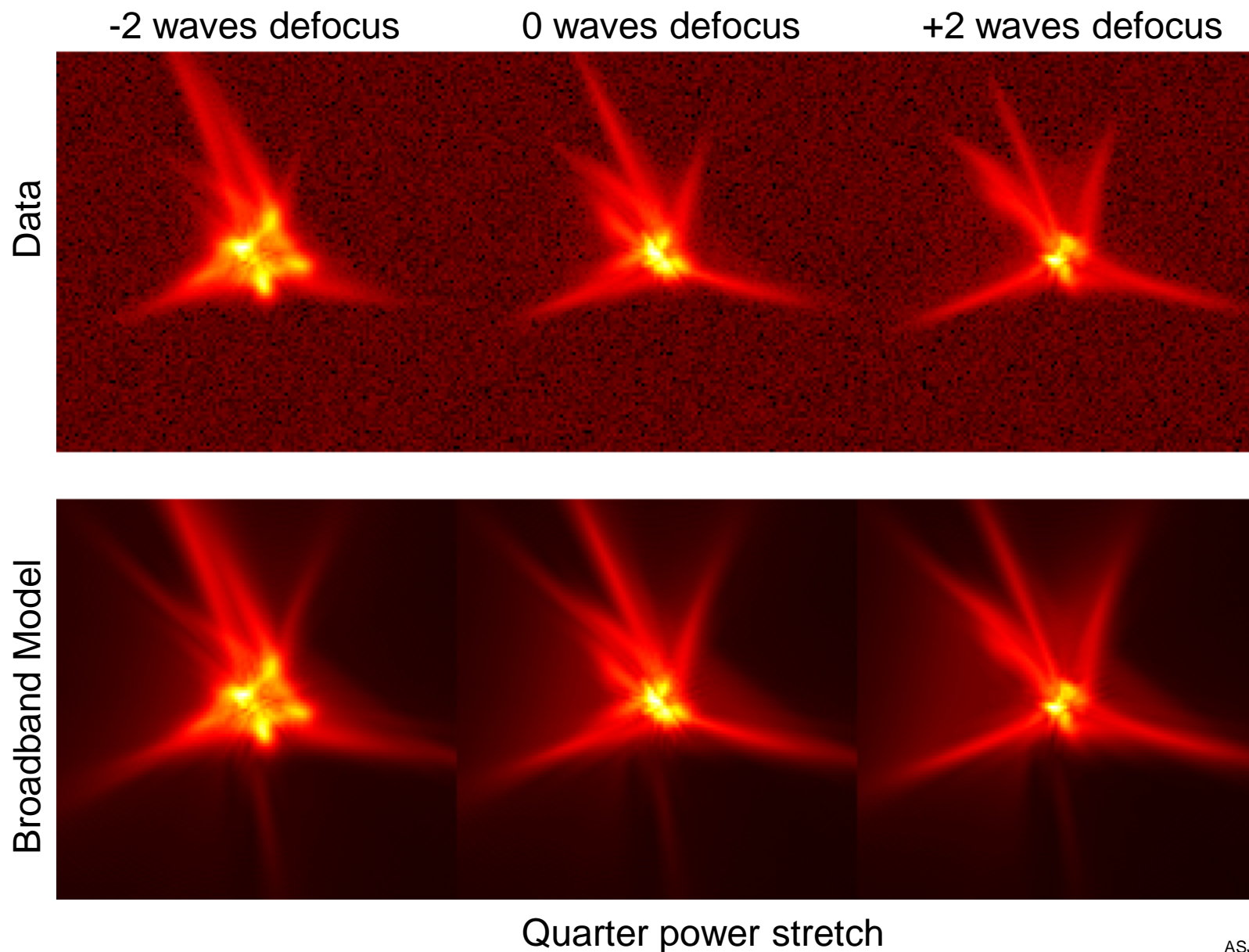
$$I_{B,k} = B \otimes I_k = B \otimes F_{\lambda,k}[W]$$

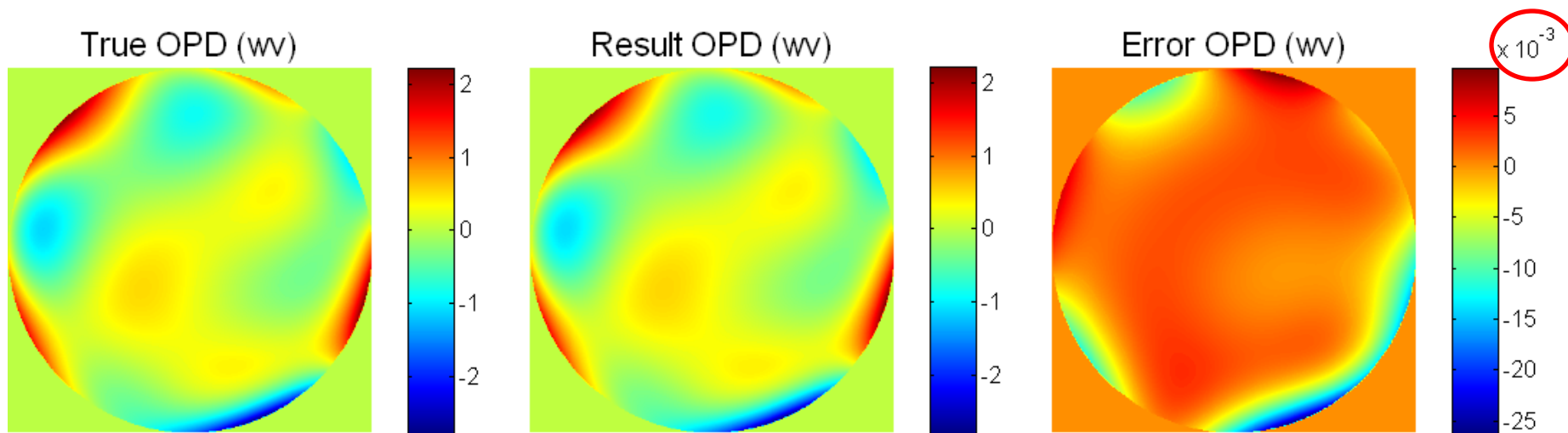
- Use non-linear optimization to fit blurred data against blurred model

$$E(W) = \frac{1}{K} \frac{\sum_k \sum_u \left[\alpha_k I_{B,k}(u) + \beta_k - D_{B,k}(u) \right]^2}{\sum_u \left[D_{B,k}(u) \right]^2}$$

- Similar to JWST Fine Guidance Sensor (FGS)
- F/8 system
- 18 μm pixels
- 1-5 μm bandwidth (133% fractional bandwidth)
 - Flat spectrum
- Modeled detector area: 128x128 pixels (artificially small)
- Noise model: 50,000 photons in peak pixel, 25 photons of read noise, 100 photon noise-free bias
- Measured point spread functions at -2 , 0 , 2 waves center to edge defocus
- Modeled with monolithic aperture
- Monte Carlo simulation
 - 64 trials
 - Minimum wavefront error: 0.025 waves RMS
 - Maximum wavefront error: 0.500 waves RMS

Broadband Phase Retrieval Results





OPD in waves

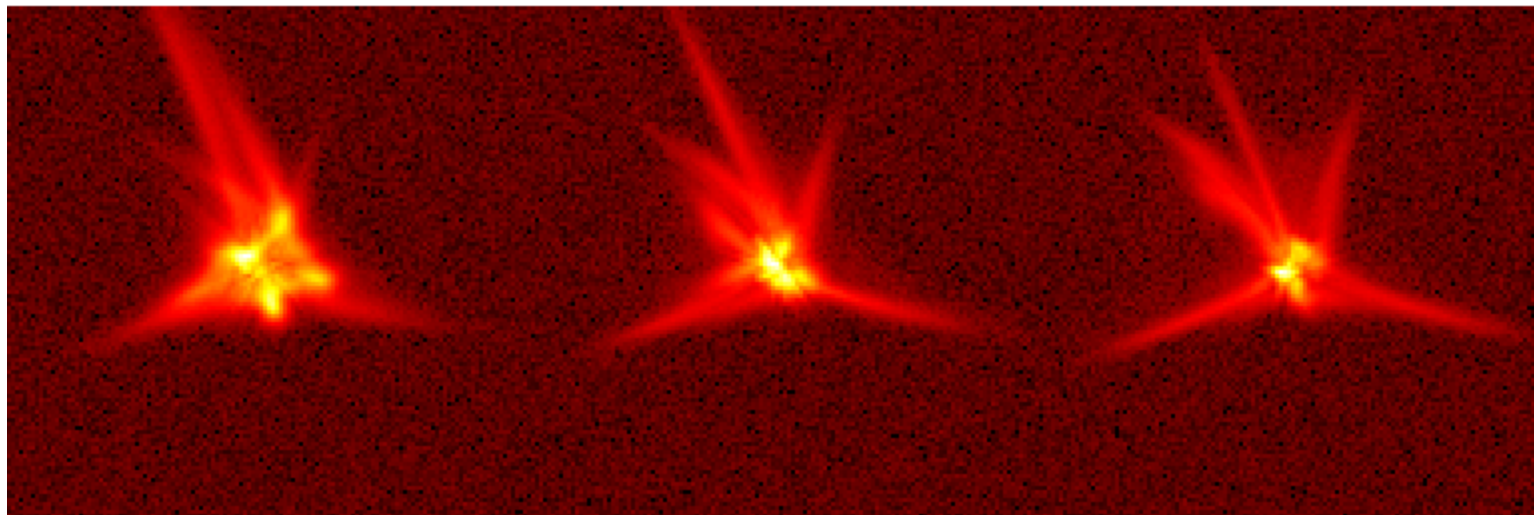
Unblurred PSFs (Monolithic)

-2 waves defocus

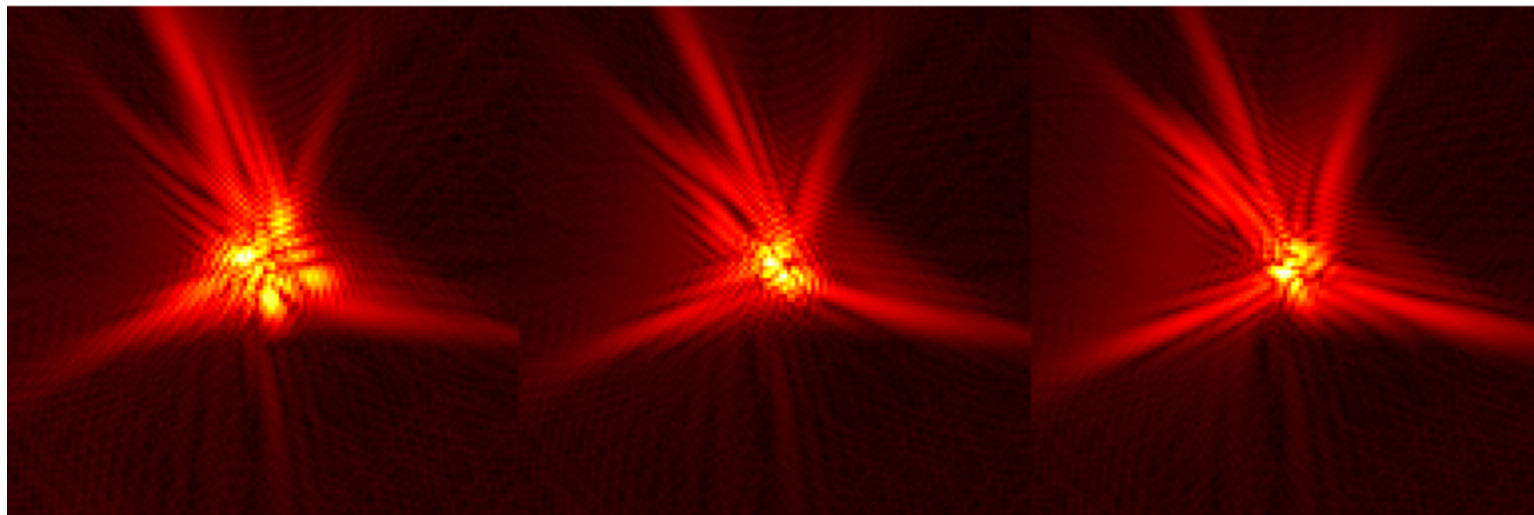
0 waves defocus

+2 waves defocus

Data



Unblurred
Monochromatic



Quarter power stretch

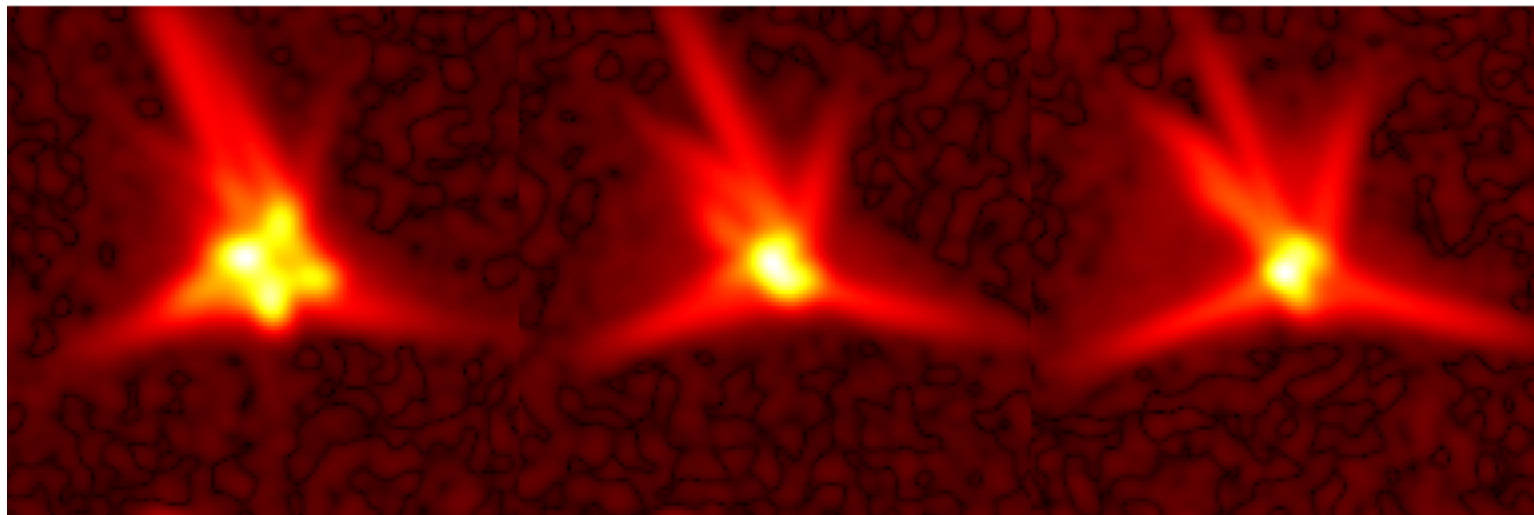
Blurred PSFs (Monolithic)

-2 waves defocus

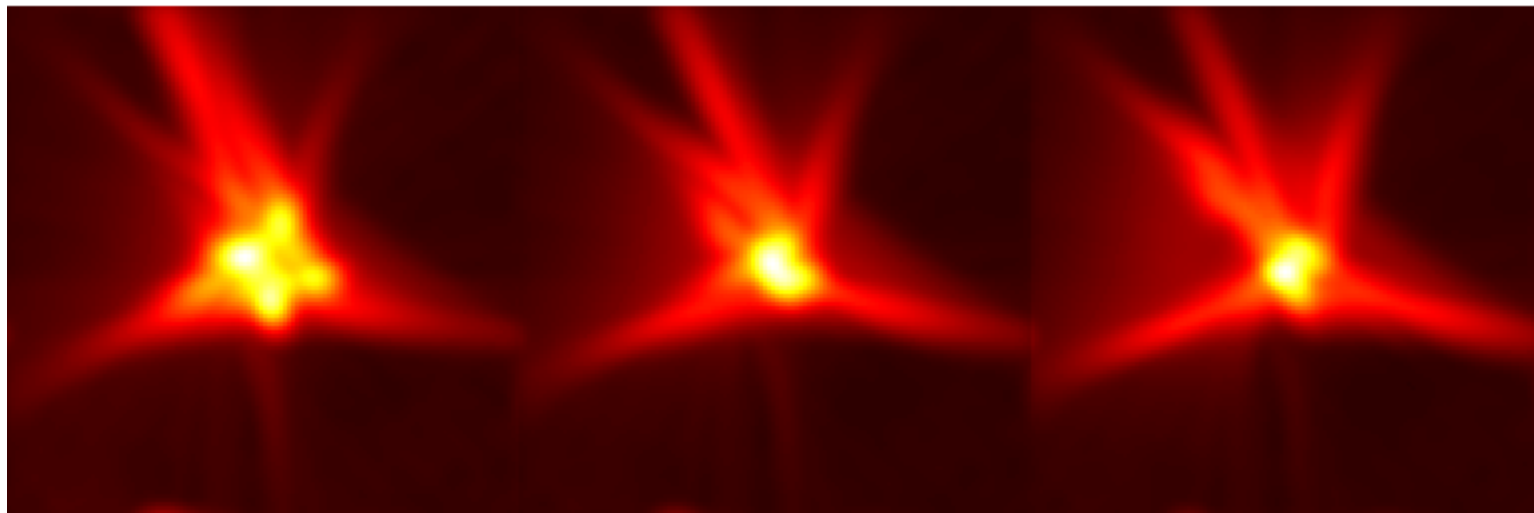
0 waves defocus

+2 waves defocus

Data

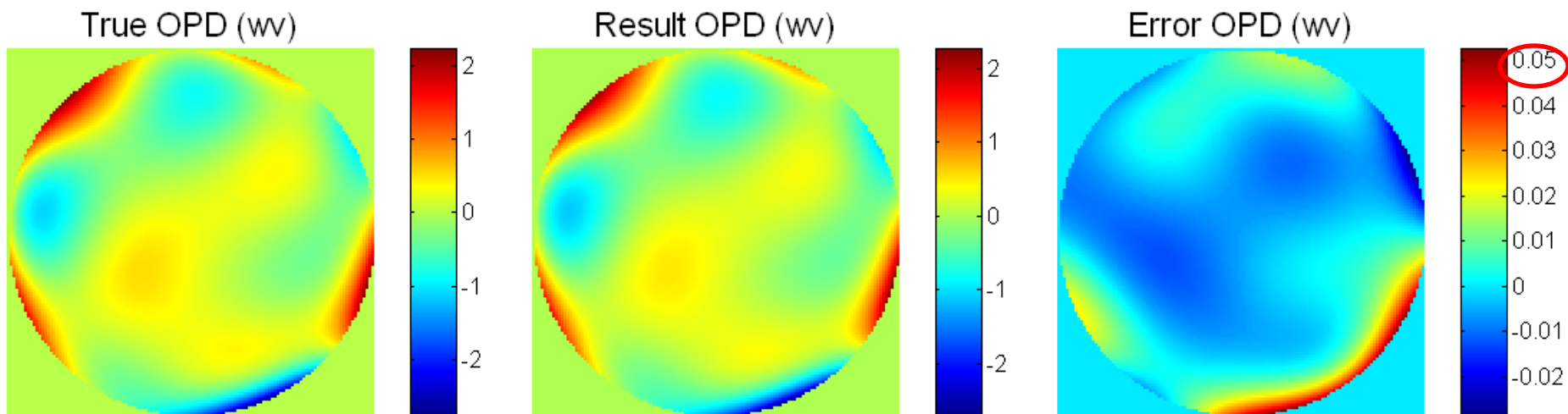


Blurred
Monochromatic



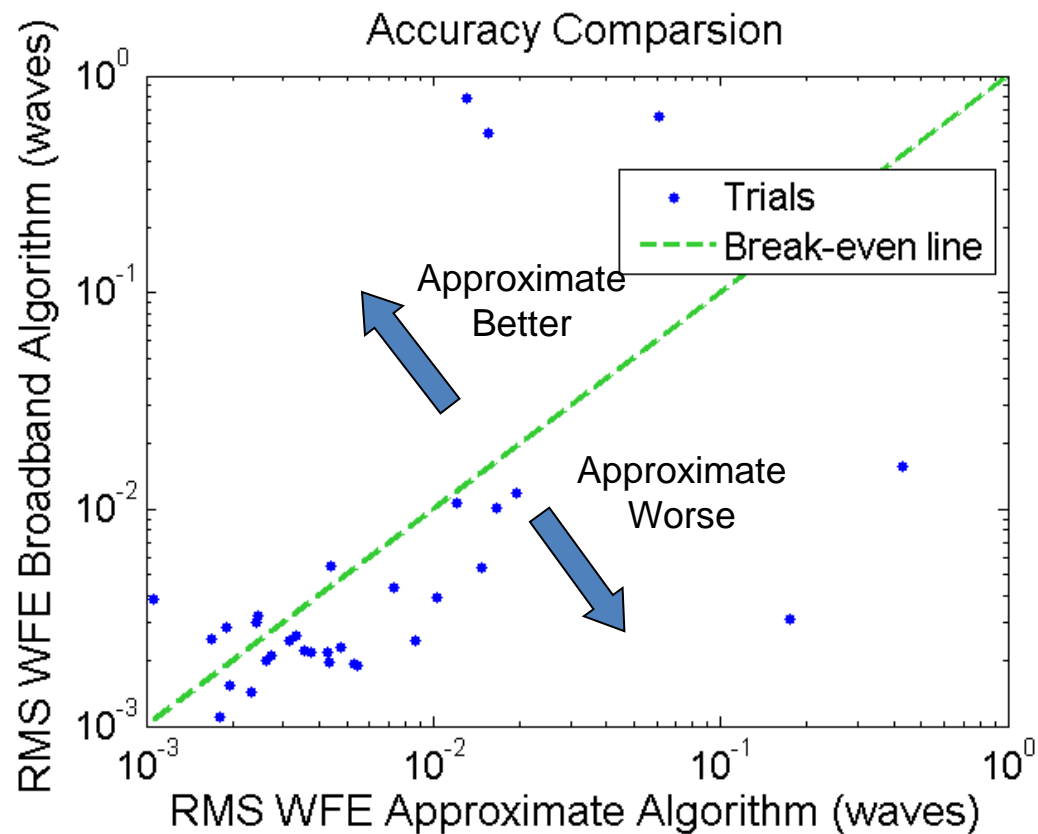
Quarter power stretch

Wavefront Retrieval Results With Blurring

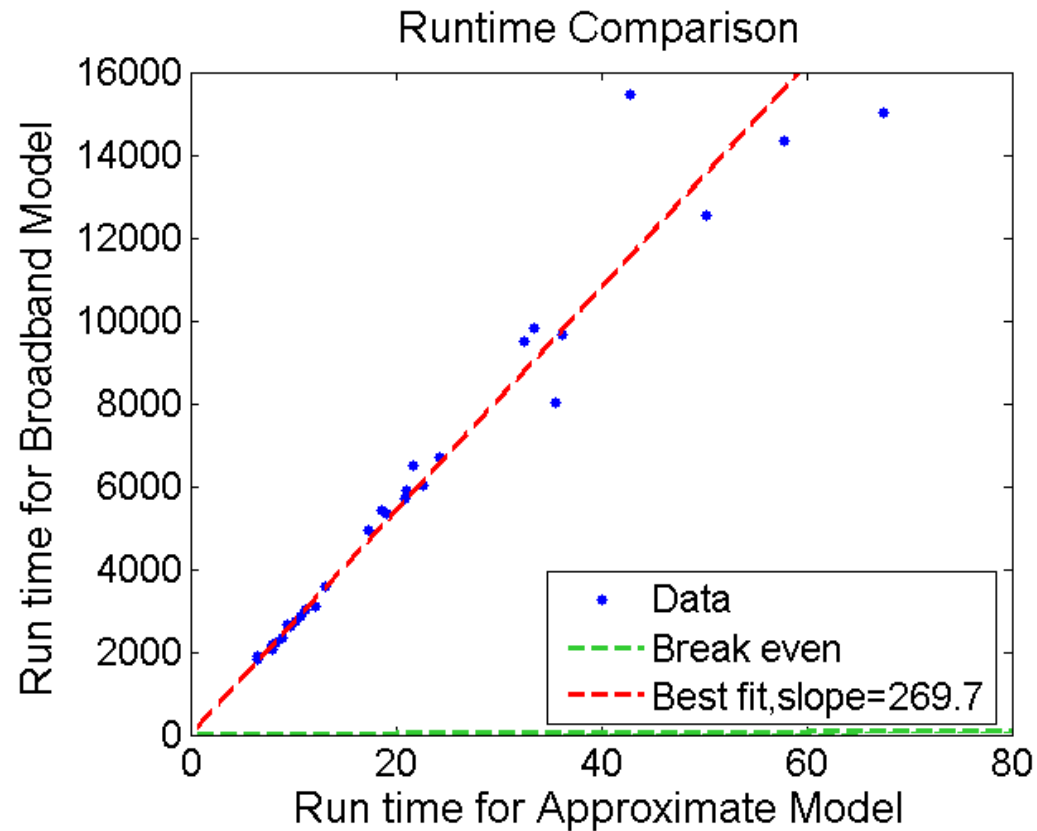


OPD in waves

Monte Carlo Results



Monte Carlo Results



- Monolithic System Results
 - Good results for monolithic system
 - 270x speed improvement
 - Small loss in accuracy
 - How does approximation perform for a segment system?
- Segmented test case
 - Same 1-5 μm FGS-like system
 - Global aberration model: Third order aberrations
 - Segment aberration model: Piston, tip, tilt
 - Monte Carlo simulation
 - 16 trials
 - 0.1 waves RMS wavefront errors

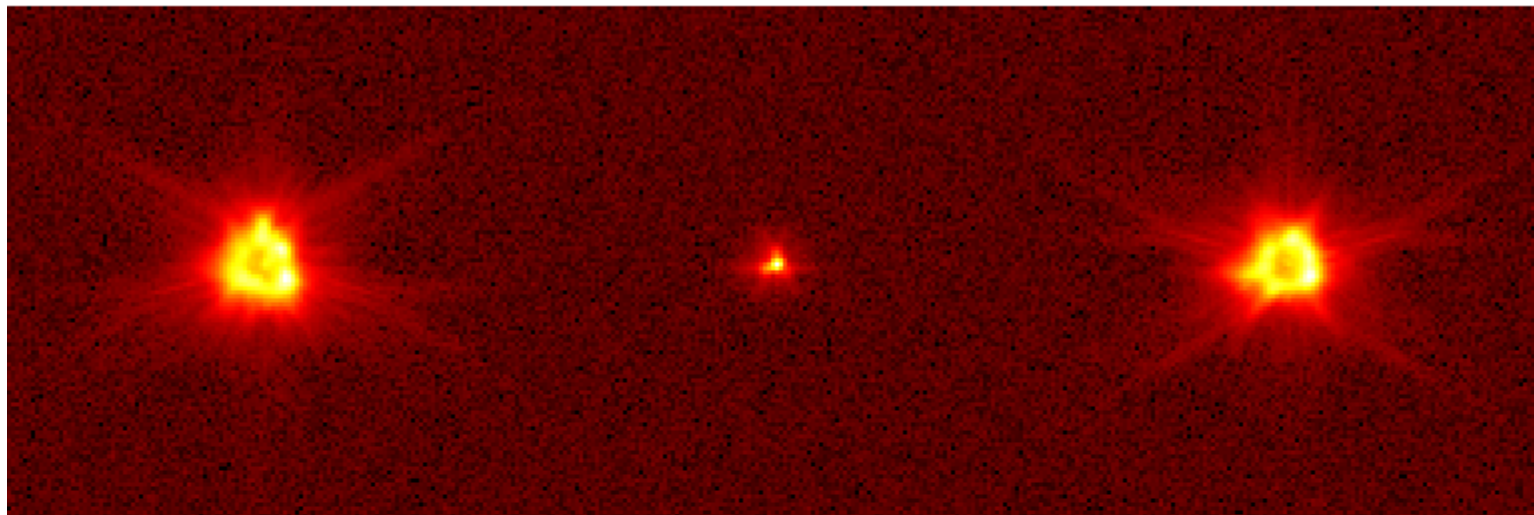
Unblurred PSFs (Segmented)

-2 waves defocus

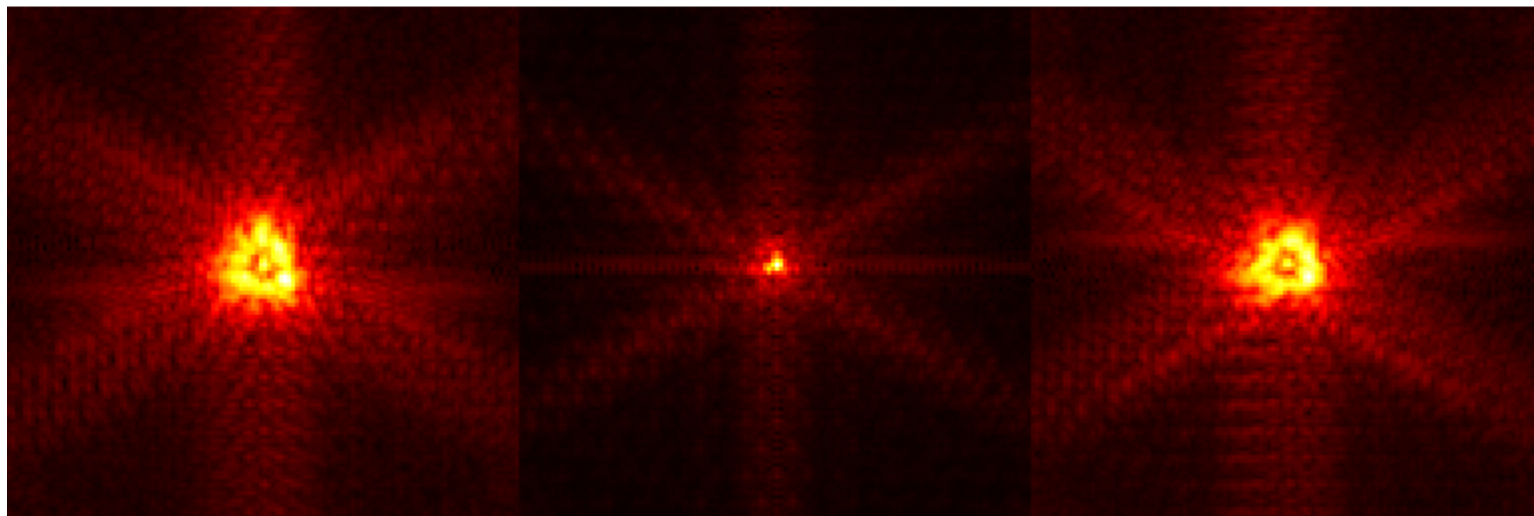
0 waves defocus

+2 waves defocus

Data



Unblurred
Monochromatic



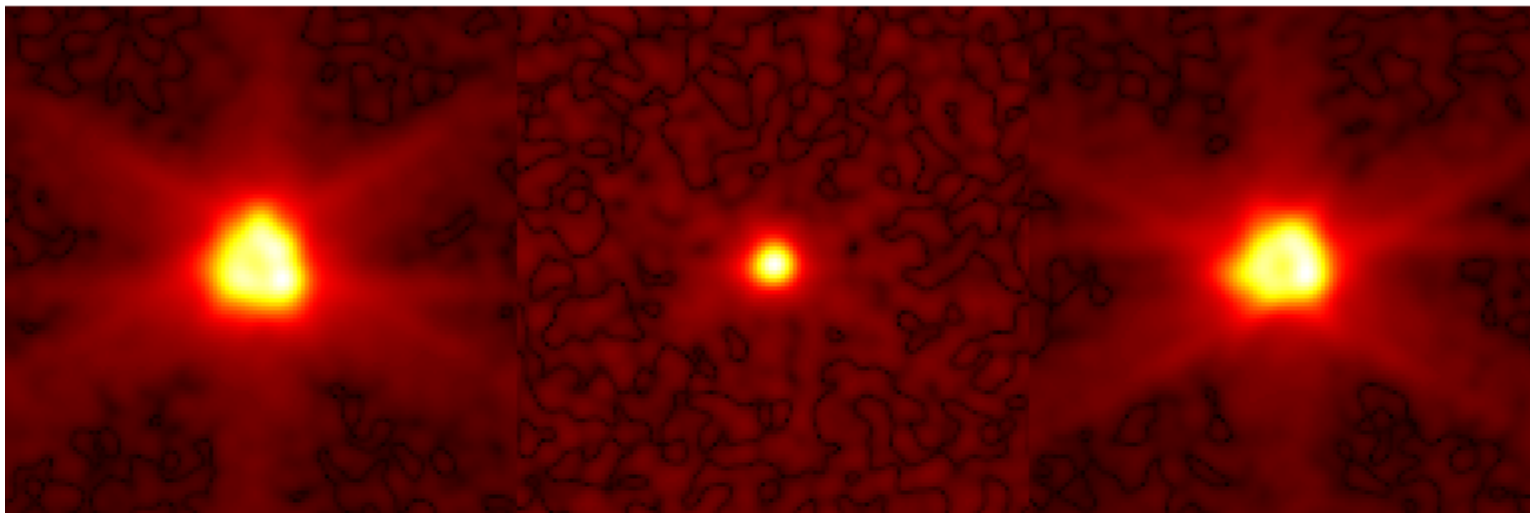
Blurred PSFs (Segmented)

-2 waves defocus

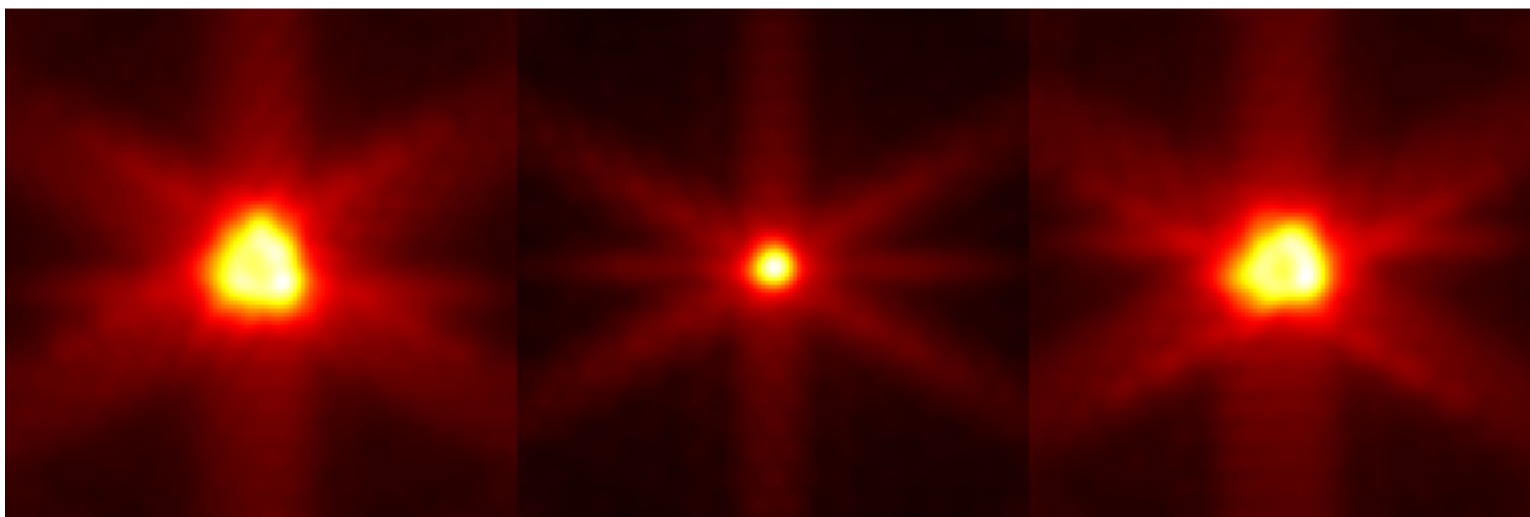
0 waves defocus

+2 waves defocus

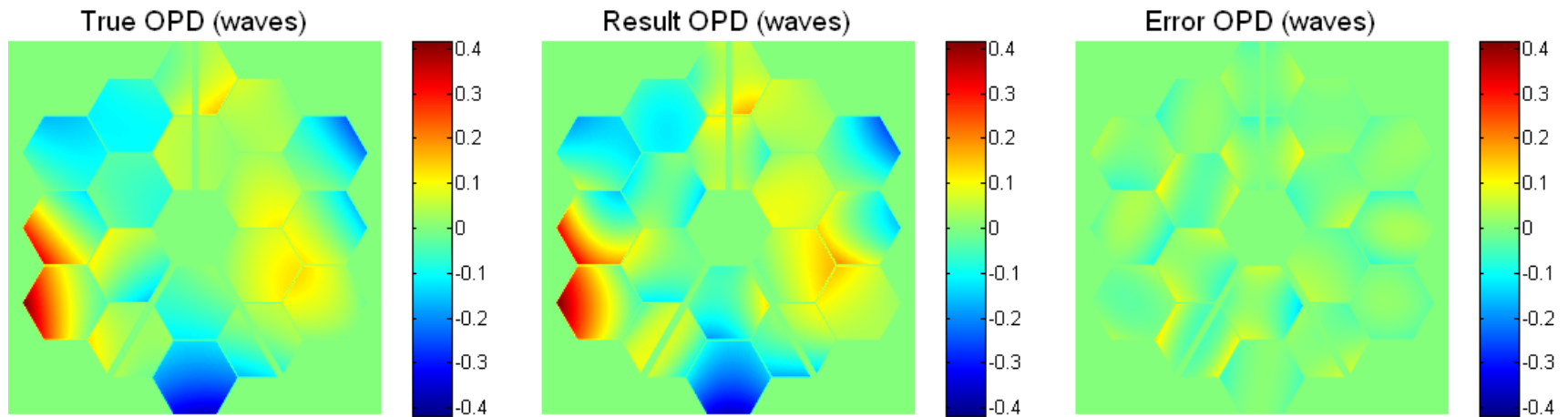
Data

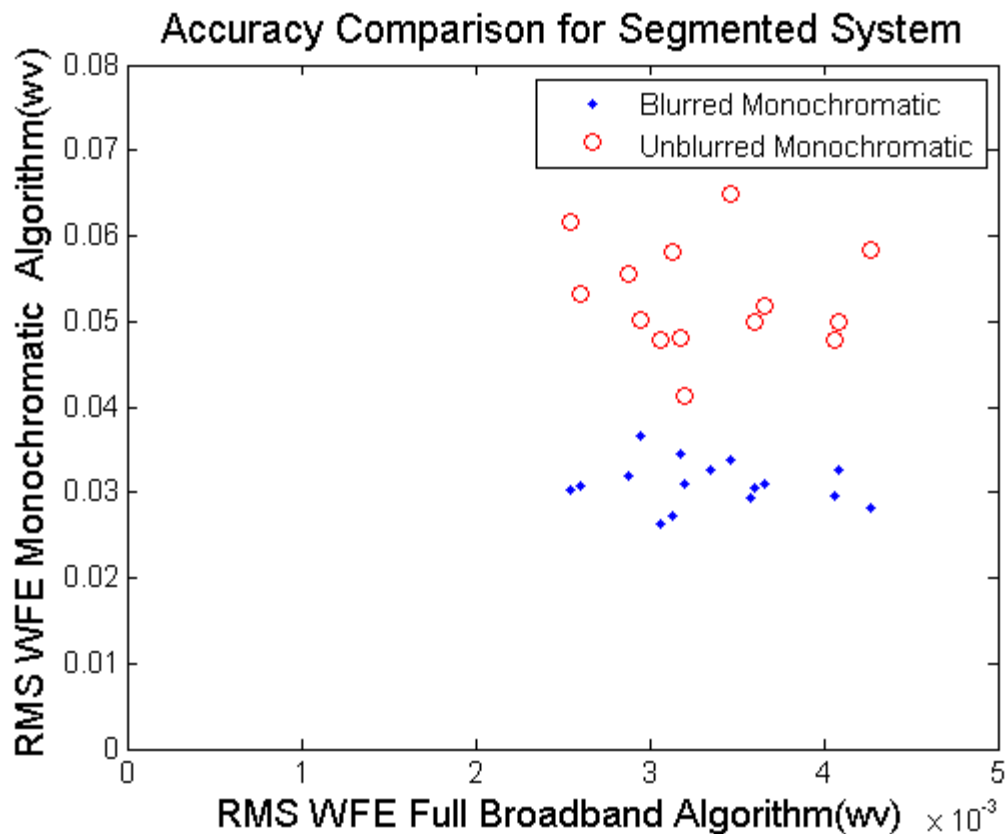


Blurred
Monochromatic



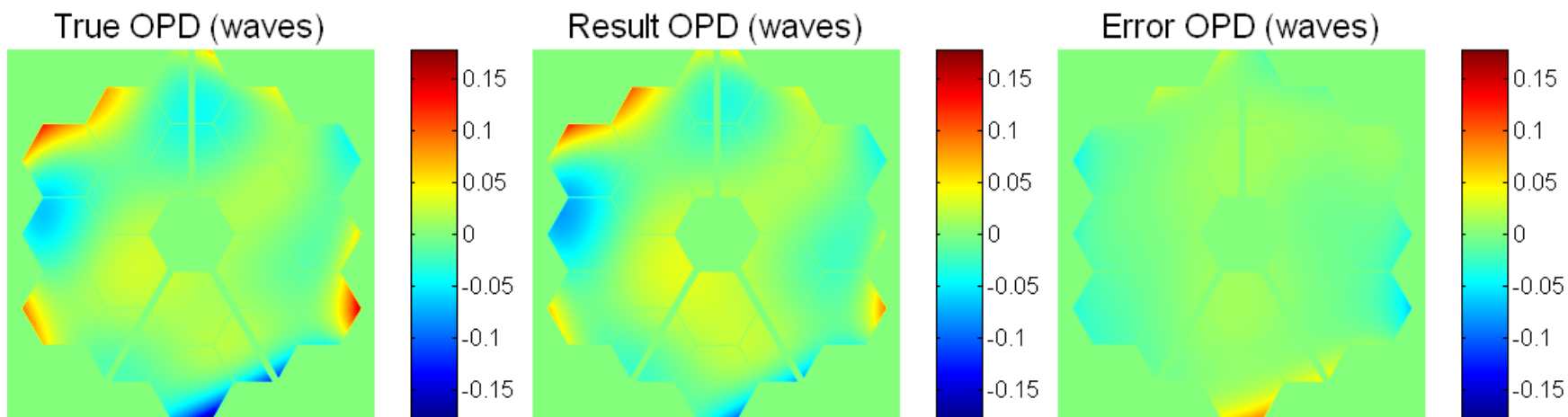
Results, Segmented System





- Reduced Accuracy with segmented system
- Possible causes
 - More diffraction
 - More variables (higher order phases)
 - Which is responsible?
- To investigate
 - Apply segmented system mask to low order phases
 - Same phase model as monolithic aperture
 - Same aperture mask as segmented system
 - Isolates diffraction effect from higher order phase effect
 - Limit study to 0.25 waves wavefront to avoid issues with large wavefronts

Results: Segmented Mask



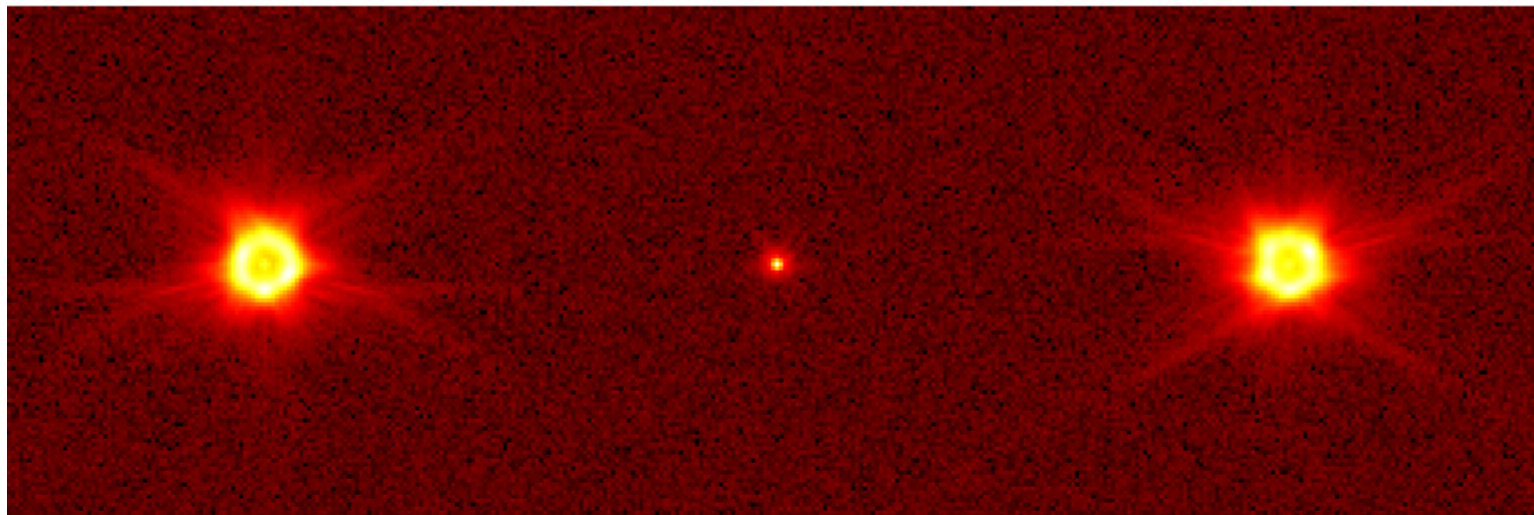
Unblurred PSFs (Segmented Mask)

-2 waves defocus

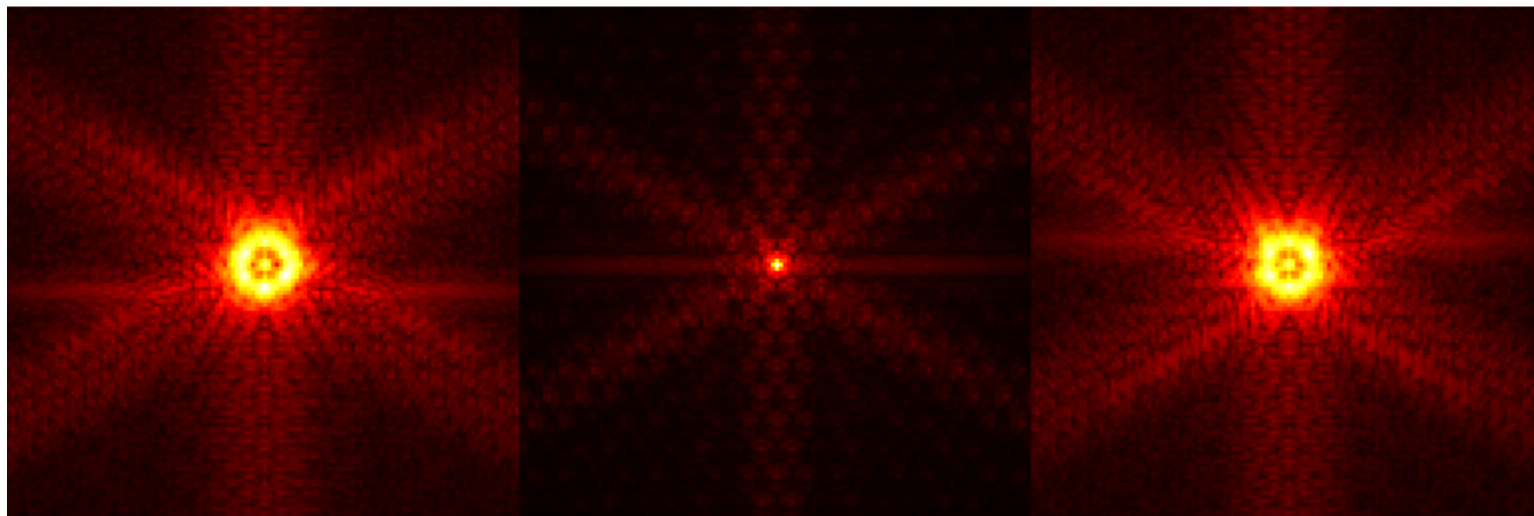
0 waves defocus

+2 waves defocus

Data



Unblurred
Monochromatic



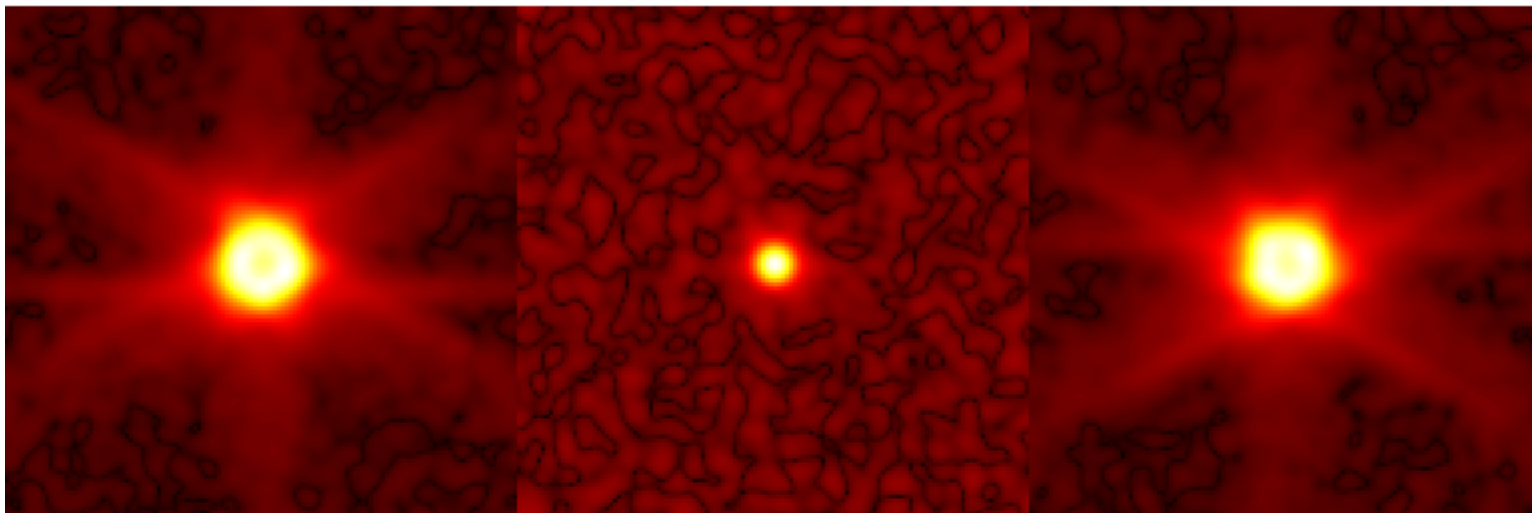
Blurred PSFs (Segmented Mask)

-2 waves defocus

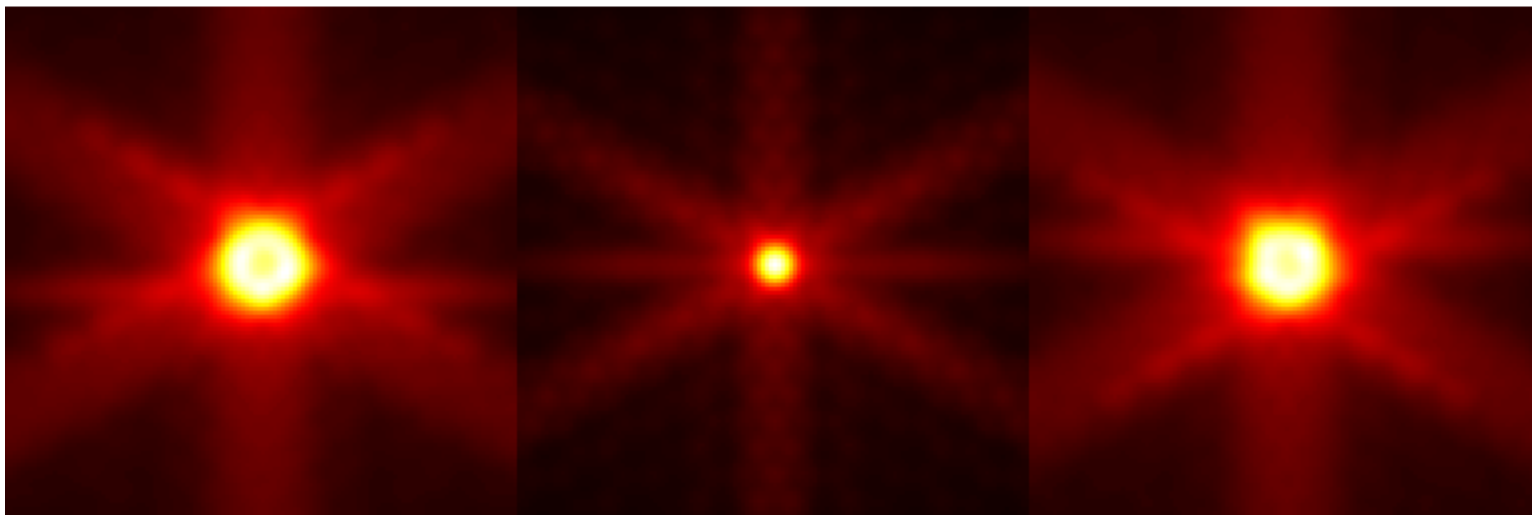
0 waves defocus

+2 waves defocus

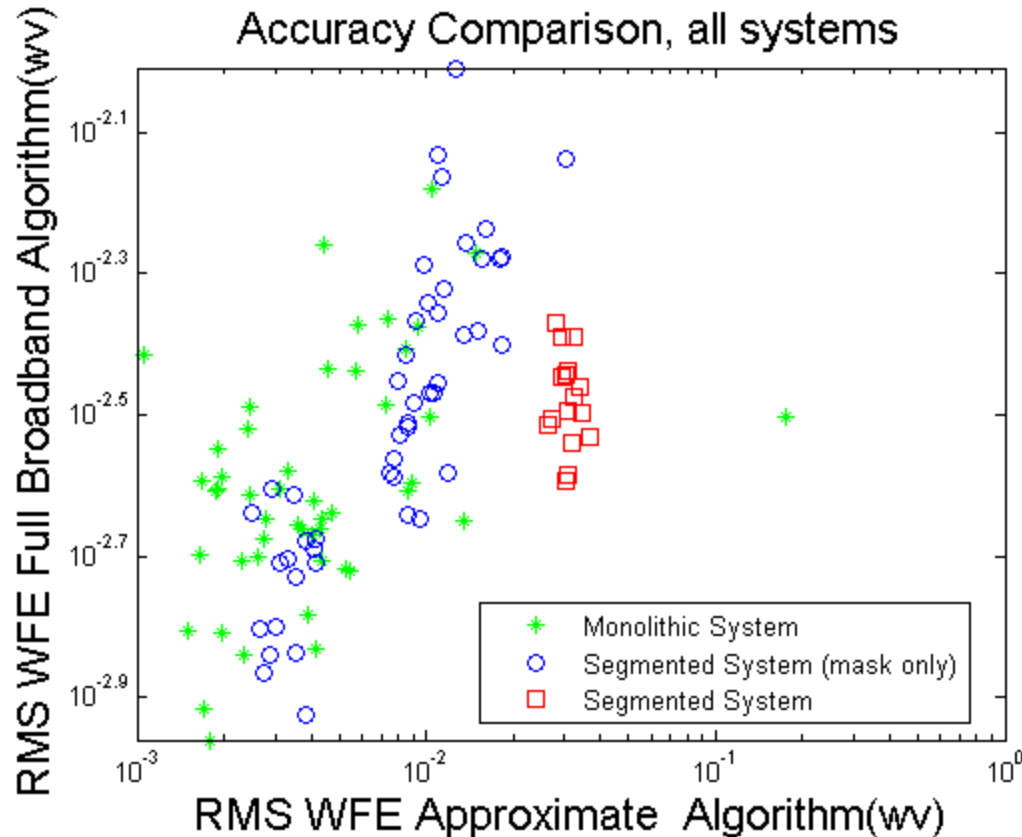
Data



Blurred
Monochromatic



Accuracy Comparison: Three Cases



Medians:

Monolithic: 0.004 waves

Mask: 0.009 waves

Segments: 0.0308 waves

Both diffraction and higher order phase reduce accuracy!

- Broadband phase retrieval needed when:
 - Narrow spectral filters unavailable
 - Dim sources
 - Low throughput due to misalignment
 - Short exposures times
 - Pointing instability (space)
 - Atmospheric instability (ground based AO)
- Traditional approach is computationally burdensome for extreme bandwidths
- Approximate approach
 - Substitute monochromatic model
 - Blur model and data
- Test case performance
 - ~270x reduction in computational cost for FGS-like test case
 - Good accuracy for monolithic system
 - Acceptable accuracy for segmented systems
 - Reduced by diffraction
 - Reduced by higher order segment model

Questions?