

Visible Contrast Energy Metrics for Detection and Discrimination

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Energy Metric for Detection

- Inputs: Luminance image = $L(x,y)$
Pixel area = $dx dy$ in deg^2 ,
Duration = dt in sec
- Compute visible contrast image = $C_v(x,y)$
- Visible Energy Metric :
$$E_v = dx dy dt \sum_{x,y} C_v(x,y)^2 \text{ deg}^2 \text{ sec}$$
$$\text{dBV} = 10 \log_{10}(E_v / 10^{-6})$$
- Modelfest average threshold = $7 \pm 2 \text{ dBV}$

Visible Contrast Image

- Optic Blur : $Lo(x,y) = L(x,y) * O(x,y)$
- Background Luminance :
 $Lb(x,y) = a(dt) (Lo(x,y) * B(x,y)) + (1 - a(dt)) B_0$
- Contrast : $C(x,y) = \frac{Lo(x,y) - Lb(x,y)}{Lb(x,y)}$
- Eccentricity Sensitivity :
 $Cv(x,y) = C(x,y) S(x,y)$

Parameters

- Optic Blur : $F(O(x,y)) = \exp(-f / f_0)$,
 $f = \sqrt{(f_x^2 + f_y^2)}$, $f_0 = 12$ cpd
- Background Luminance :
 $F(B(x,y)) = \exp(-(f / f_1)^2)$, $f_1 = 2$ cpd
 $a(dt) = \exp(-dt / t_0)$, $t_0 = 0.4$ sec
- Eccentricity Sensitivity :
 $S(x,y) = 1 / (1 + g (1 - \exp(-r / r_0)))$,
 $r = \sqrt{(x^2 + y^2)}$, $r_0 = 5.7$ deg,
 $g = 4.1$, $1 / (1 + g) = 0.2$

Metric-Validating Model

- Visibility Image: $C_v(x,y)$
- Additive White Noise with 2-sided power spectral density

$$N = \sigma^2 dx dy dt ,$$

Each pixel is independently distributed as

Normal with mean 0 and standard deviation σ

- Ideal Observer detects presence or absence of signal in a two interval forced choice (2IFC) experiment.

2IFC Model Performance

- Visibility Image: $C_v(x,y)$ with visible contrast energy E_v and noise spectral density N
- Distance between observer output distributions divided by their common standard deviation is

$$d' = \sqrt{(2 E_v / N)}$$

- $\text{Prob}(\text{Correct}) = P_c = F_z(d') - 0.5$
- Estimated $N = 2 E_v / d'^2$
- If $P_c = 0.84$, $d' = 1$, $N = 2 E_v$
- Modelfest : $10 \log_{10}(N) + 60 = 10 \pm 2 \text{ dB}$

Discrimination Model

- Visibility Images: $C_v(x,y,j)$, $j = 1,M$
- Additive White Noise with power spectral density
 $N = \sigma^2 dx dy dt$
- Ideal Observer responds k if image j is presented and image k has the smallest squared distance $d(k)$ to the noisy image

$$d(k) = || C_v(j) + N - C_v(k) ||^2$$

$$d(k) = || C_v(j) + N ||^2 + || C_v(k) ||^2 - 2 (C_v(j) \cdot C_v(k) + N \cdot C_v(k))$$

Discrimination Model Metric

- Orthogonal Images: $C_v(j) \cdot C_v(k) = 0, j \neq k$
- Same energy: $E_v(j) = E_v$
- Let $d' = \sqrt{(E_v / N)}$

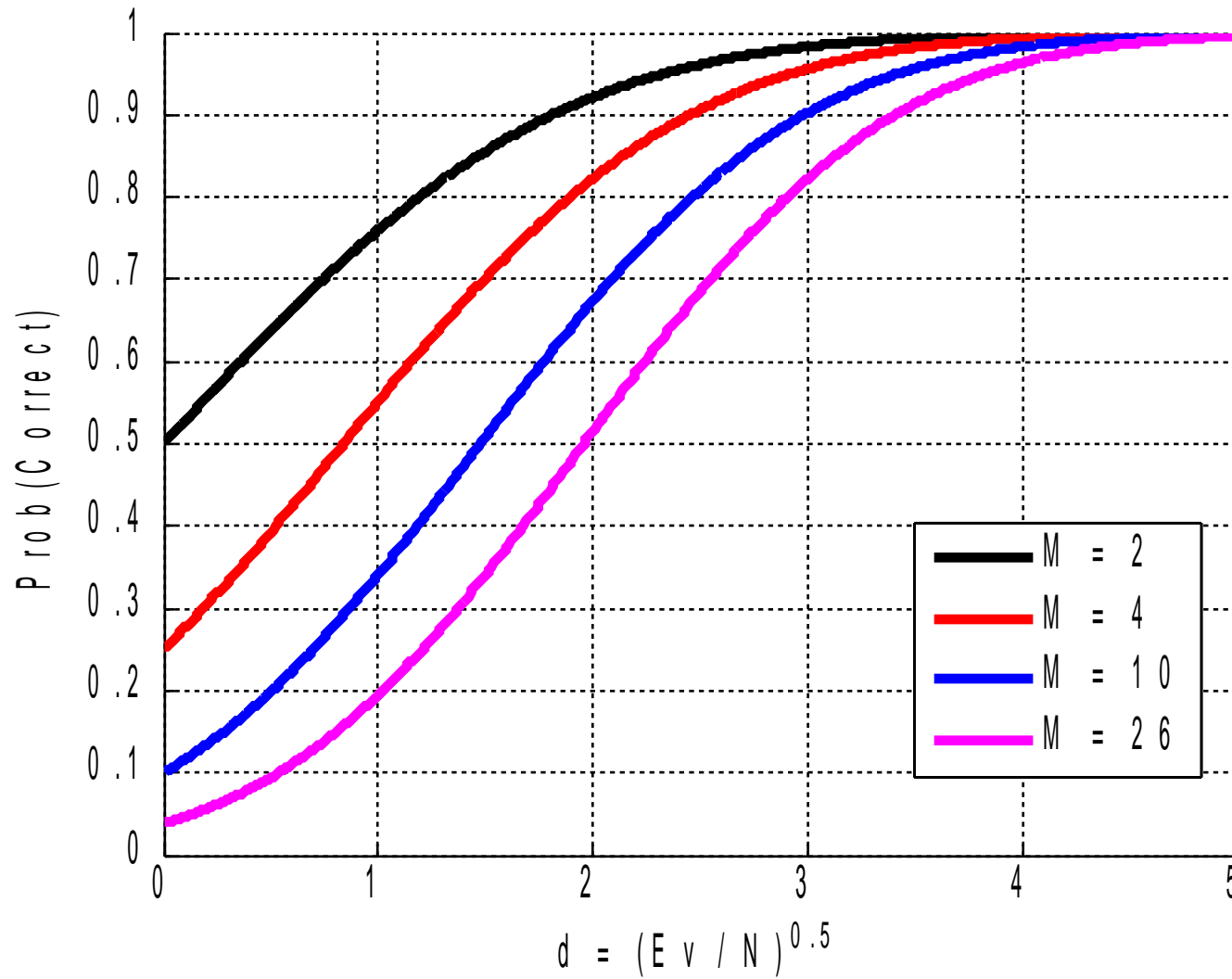
$$P_c = \int F(x)^{k-1} f(x-d') dx ,$$

where F and f are the cumulative and density distribution functions of the standard normal.

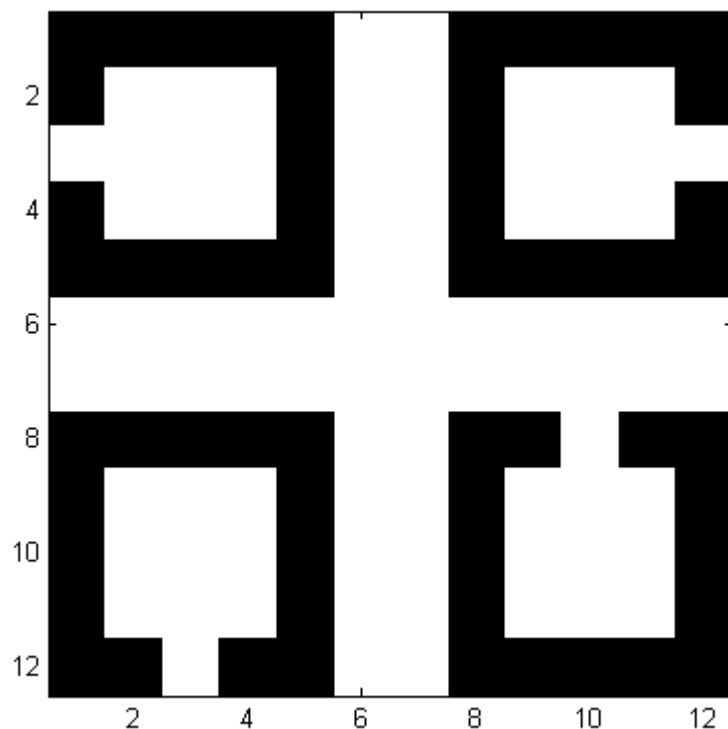
- Also $E_v = dx dy dt \sum_j ||C_v(j) - C||^2 / (M-1)$

$$\text{where } C = \sum_j C_v(j) / M$$

Discrimination Model Performance

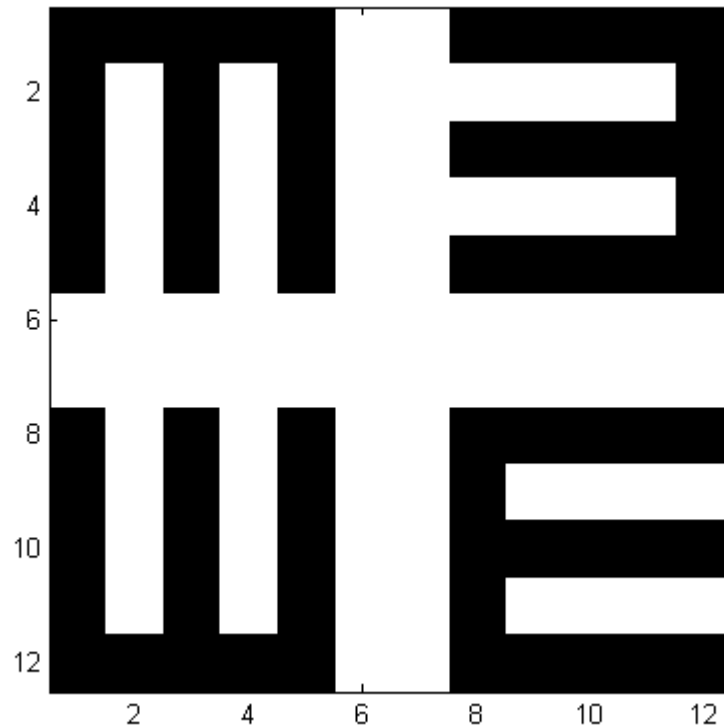


Example: Landolt C



Pedestal invariance of ideal observer allows the orthogonal stimulus model.

Example: Tumbling E's



- Model simulation for $n = 10000$ trials, $d' = 1$.
95% confidence interval for $P_c = 0.538 \pm 0.010$
- Metric prediction $P_c = 0.552$

Method Considerations

- When pattern energies are similar, varying the contrast adds little or no uncertainty; varying size or blur contributes significant uncertainty.
- Practice of computing thresholds by averaging reversal endpoints has problems
 - 1) P_c at threshold is not actually known
 - 2) No estimate of the slope at threshold is provided
 - 3) Valuable data is effectively discarded

Summary

- Detection metric:
Visible contrast energy
- Approximate Discrimination metric:
Average $(M-1)$ squared distance from
each visible contrast pattern to the
mean visible contrast pattern
- Model simulation is fast

Tumbling E Model Matlab Code

```
c = s' * s ; % 4x25 times 25x4
[u , x, v] = svd(c) ;
f = u * (x.^0.5) ;

sn =
ones(n, 4) * c(1, 1:4) + randn(n, 4) * f' ;

Pc = mean (
    sn(1:n, 1) > max(sn(1:n, 2:4)')'
) ;
```

Watson & Ahumada (2005)

Metric Elements



Figure 4. Elements of the component model.