



Advanced Mirror Technology Development (AMTD) for Very Large Space Telescopes

Status: Year 2 of multi-year effort

H. Philip Stahl
Astrophysics Roadmap Team
6 May 13



Top Level

Most future space telescope missions require mirror technology.

Just as JWST's architecture was driven by launch vehicle, future mission's architectures (mono, segment or interferometric) will depend on future launch vehicle capacities (and also budget).

Since we cannot predict future, we must prepare for all futures.

UVOIR mission architectures (monolithic, segmented or interferometric) share similar mirror needs:

- Very Smooth Surfaces < 10 nm rms
- Thermal Stability Low CTE Material
- Mechanical Stability High Stiffness Mirror Substrates

Finally, Telescopes are only 15 to 25% of Total Mission Cost.



AMTD Approach

Mirror technology must enable missions capable of both general astrophysics & ultra-high contrast observations of exoplanets.

Outstanding academic, industry & government team with expertise:

- UVOIR astrophysics and exoplanet characterization,
- monolithic and segmented space telescopes, and
- optical manufacturing and testing.

Integrate science & systems engineering to:

- derive engineering specifications from science measurement needs and implementation constraints;
- identify technical challenges in meeting these specifications;
- iterate between science and systems engineering to mitigate challenges; and
- prioritize the challenges.

Systematically mature TRL of prioritized challenges using

- design tools to construct analytical models and
- prototypes/test beds to validate models in relevant environments.



Objectives

Derive engineering specifications for a future monolithic or segmented space telescope based on science needs & implementation constraints.

Mature 6 inter-linked critical technologies.

- *Large-Aperture, Low Areal Density, High Stiffness Mirrors:* 4 to 8 m monolithic & 8 to 16 m segmented primary mirrors require larger, thicker, stiffer substrates.
- *Support System:* Large-aperture mirrors require large support systems to ensure that they survive launch and deploy on orbit in a stress-free and undistorted shape.
- *Mid/High Spatial Frequency Figure Error:* A very smooth mirror is critical for producing a high-quality point spread function (PSF) for high-contrast imaging.
- *Segment Edges:* Edges impact PSF for high-contrast imaging applications, contributes to stray light noise, and affects the total collecting aperture.
- *Segment-to-Segment Gap Phasing:* Segment phasing is critical for producing a high-quality temporally stable PSF.
- *Integrated Model Validation:* On-orbit performance is determined by mechanical and thermal stability. Future systems require validated performance models.



Philosophy

Simultaneous technology maturation because all are required to make a primary mirror assembly (PMA); AND, it is the PMA's on-orbit performance which determines science return.

- PMA stiffness depends on substrate and support stiffness.
- Ability to cost-effectively eliminate mid/high spatial figure errors and polishing edges depends on substrate stiffness.
- On-orbit thermal and mechanical performance depends on substrate stiffness, the coefficient of thermal expansion (CTE) and thermal mass.
- Segment-to-segment phasing depends on substrate & structure stiffness.

We are deliberately pursuing multiple design paths to enable either a future monolithic or segmented space telescope

- Gives science community options
- Future mission architectures depend on future launch vehicles, AND
- We cannot predict future launch vehicle capacities



AMTD Project Technical Team

Principle Investigator		Systems Engineering	
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Science Advisory		Engineering	
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Jessica Gersh-Range	Cornel		

Funding

NASA ROSES SAT (10-SAT10-0048)

Space Act Agreement (SAA8-1314052) with Ziva Corp

NASA Graduate Student Research Program (NNX09AJ18H)



Heritage

AMTD builds on over 30 yrs of US Gov mirror technology development:

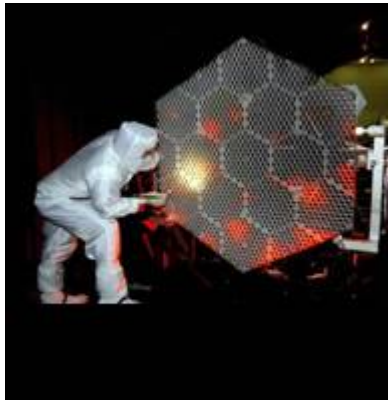
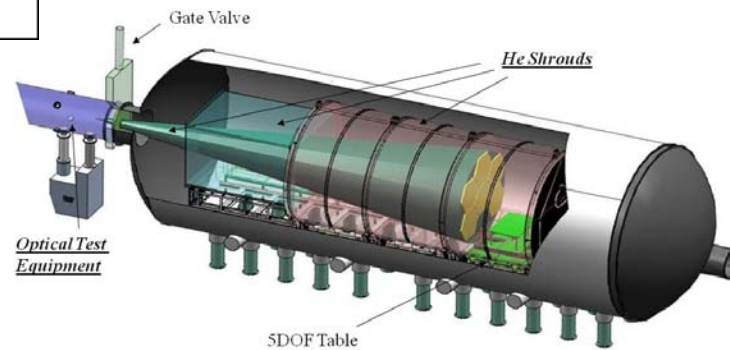


Figure 3-7: LAMP (left), AMSD (center) and SMT (right)



ITT's 2.4m ATT Demonstration Mirror





Goals, Progress & Accomplishments

Key

Year 1 Done

Year 1 Stopped

Year 2 In-Process

Year 3 Not Started Yet

Systems Engineering:

- **derive from science requirements monolithic mirror specifications**
- **derive from science requirements segmented mirror specifications**

Large-Aperture, Low Areal Density, High Stiffness Mirror Substrates:

- **make a subsection mirror via a process traceable to 500 mm deep mirrors**

Support System:

- **produce pre-Phase-A point designs for candidate primary mirror architectures;**
- **demonstrate specific actuation and vibration isolation mechanisms**

Mid/High Spatial Frequency Figure Error:

- 'null' polish a 1.5-m AMSD mirror & subscale deep core mirror to a < 6 nm rms zero-g figure at the 2°C operational temperature.

Segment Edges:

- **demonstrate an achromatic edge apodization mask**

Segment to Segment Gap Phasing:

- **develop models for segmented primary mirror performance; and**
- **test prototype passive & active mechanisms to control gaps to ~ 1 nm rms.**

Integrated Model Validation:

- **validate thermal model by testing** the AMSD and **deep core mirrors at 2°C**; and
- **validate mechanical models by static load test.**



9 Publications from Year 1

Stahl, H. Philip, *Overview and Recent Accomplishments of the Advanced Mirror Technology Development (AMTD) for large aperture UVOIR space telescopes project*, SPIE Conference on UV/Optical/IR Space Telescopes and Instrumentation, 2013.

Stahl, H. Philip, W. Scott Smith, Marc Postman, *Engineering specifications for a 4 meter class UVOIR space telescope derived from science requirements*, SPIE Conference on UV/Optical/IR Space Telescopes and Instrumentation, 2013.

Matthews, Gary, et al, *Development of stacked core technology for the fabrication of deep lightweight UV quality space mirrors*, SPIE Conference on Optical Manufacturing and Testing X, 2013.

Matthews, Gary, et al, *Thermal testing of a stacked core mirror for UV applications*, SPIE Conference on Material Technologies and Applications to Optics, Structures, Components, and Sub-Systems, 2013.

Eng, Ron, et. al., *Cryogenic optical performance of a lightweighted mirror assembly for future space astronomical telescopes: correlation of optical test results and thermal optical model*, SPIE Conference on Material Technologies and Applications to Optics, Structures, Components, and Sub-Systems, 2013.

Sivaramakrishnan, Anand, *Calibrating apodizer fabrication techniques for high contrast coronagraphs on segmented and monolithic space telescopes*, SPIE Conference on UV/Optical/IR Space Telescopes and Instrumentation, 2013.

Arnold, William et al, *Next generation lightweight mirror modeling software*, SPIE Conference on Optomechanical Engineering, 2013.

Arnold, William et al, *Integration of Mirror design with Suspension System using NASA's new mirror modeling software*, SPIE Conference on Optomechanical Engineering, 2013.

Gersh-Range, Jessica A., William R. Arnold, Mason A. Peck, and H. Philip Stahl, *A parametric finite-element model for evaluating segmented mirrors with discrete edgewise connectivity*, SPIE Proceedings 8125, 2011, DOI:10.1117/12.893469

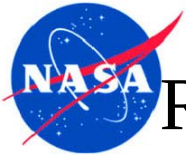


Engineering Specifications

Derived engineering specifications for monolithic primary mirror from science measurement needs & implementation constraints.

Segmented mirror specifications are in-process.

Stahl, H. Philip, W. Scott Smith, Marc Postman, *Engineering specifications for a 4 meter class UVOIR space telescope derived from science requirements*, SPIE Conference on UV/Optical/IR Space Telescopes and Instrumentation, 2013.



Requirements for a large UVOIR space telescope are derived directly from fundamental Science Questions

Table 2.1: Science Flow-down Requirements for a Large UVOIR Space Telescope

Science Question	Science Requirements	Measurements Needed	Requirements
Is there life elsewhere in Galaxy?	Detect at least 10 Earth-like Planets in HZ with 95% confidence.	High contrast ($\Delta\text{Mag} > 25$ mag) SNR=10 broadband ($R = 5$) imaging with IWA ~ 40 mas for ~ 100 stars out to ~ 20 parsecs.	≥ 8 meter aperture Stable 10^{-10} starlight suppression
	Detect presence of habitability and bio-signatures in the spectra of Earth-like HZ planets	High contrast ($\Delta\text{Mag} > 25$ mag) SNR=10 low-resolution ($R=70$ -100) spectroscopy with an IWA ~ 40 mas; spectral range 0.3 – 2.5 microns; Exposure times < 500 ksec	~ 0.1 nm stable WFE per 2 hr ~ 1.3 to 1.6 mas pointing stability
What are star formation histories of galaxies?	Determine ages (~ 1 Gyr) and metallicities (~ 0.2 dex) of stellar populations over a broad range of galactic environments.	Color-magnitude diagrams of solar analog stars ($V_{\text{mag}} \sim 35$ at 10 Mpc) in spiral, lenticular & elliptical galaxies using broadband imaging	≥ 8 meter aperture Symmetric PSF
What are kinematic properties of Dark Matter	Determine mean mass density profile of high M/L dwarf Spheroidal Galaxies	0.1 mas resolution for proper motion of ~ 200 stars per galaxy accurate to $\sim 20 \mu\text{as/yr}$ at 50 kpc	500 nm diffraction limit 1.3 to 1.6 mas pointing stability
How do galaxies & IGM interact and affect galaxy evolution?	Map properties & kinematics of intergalactic medium over contiguous sky regions at high spatial sampling to ~ 10 Mpc.	SNR = 20 high resolution UV spectroscopy ($R = 20,000$) of quasars down to FUV mag = 24, survey wide areas in < 2 weeks	≥ 4 meter aperture
How do stars & planets interact with interstellar medium?	Measure UV Ly-alpha absorption due to Hydrogen “walls” from our heliosphere and astrospheres of nearby stars	High dynamic range, very high spectral resolution ($R = 100,000$) UV spectroscopy with SNR = 100 for $V = 14$ mag stars	500 nm diffraction limit Sensitivity down to 100 nm wavelength.
How did outer solar system planets form & evolve?	UV spectroscopy of full disks of solar system bodies beyond 3 AU from Earth	SNR = 20 - 50 at spectral resolution of $R \sim 10,000$ in FUV for 20 AB mag	



Technology Challenges are derived directly from Science & Mission Requirements, and Implementation Constraints

Table 3.1: Science Requirement to Technology Need Flow Down

Science	Mission	Constraint	Capability	Technology Challenge
Sensitivity	Aperture	EELV 5 m Fairing, 6.5 mt to SEL2	4 m Monolith	4 m, 200 Hz, 60 kg/m ²
				4 m support system
		8 m Segmented		2 m, 200 Hz, 15 kg/m ²
				8 m deployed support
		HLLV-Medium 10 m Fairing, 40 mt to SEL2	8 m Monolith	8 m, <100Hz, 200kg/m ²
				8 m, 10 mt support
		16 m Segmented		2-4m, 200Hz, 50kg/m ²
				16 m deployed support
	2 hr Exposure	HLLV-Heavy 10 m Fairing, 60 mt to SEL2	8 m Monolith	8m, <100Hz, 480kg/m ²
				8 m, 20 mt support
		16 m Segmented		2-4m, 200Hz, 120kg/m ²
				16 m deployed support
		Thermal 280K ± 0.5K 0.1K per 10min	< 5 nm rms per K	low CTE material
			> 20 hr thermal time constant	thermal mass
	Dynamics TBD micro-g		< 5 nm rms figure	passive isolation
				active isolation
	Reflectance	Substrate Size	> 98% 100-2500 nm	Beyond Scope
High Contrast	Diffraction Limit	Monolithic	< 10 nm rms figure	mid/high spatial error
		Segmented	< 5 nm rms figure	fabrication & test
			< 2 mm edges	edge fabrication & test
			< 1 nm rms phasing	passive edge constraint
				active align & control



Telescope Performance Requirements

Telescope Specifications depend upon the Science Instrument.

Telescope Specifications have been defined for 3 cases:

- 4 meter Telescope with an Internal Masking Coronagraph
- 8 meter Telescope with an Internal Masking Coronagraph
- 8 meter Telescope with an External Occulter

WFE Specification is before correction by a Deformable Mirror

WFE/EE Stability and MSF WFE are the stressing specifications

Specifications have not been defined for a Visible Nulling Coronagraph or phase type coronagraph.



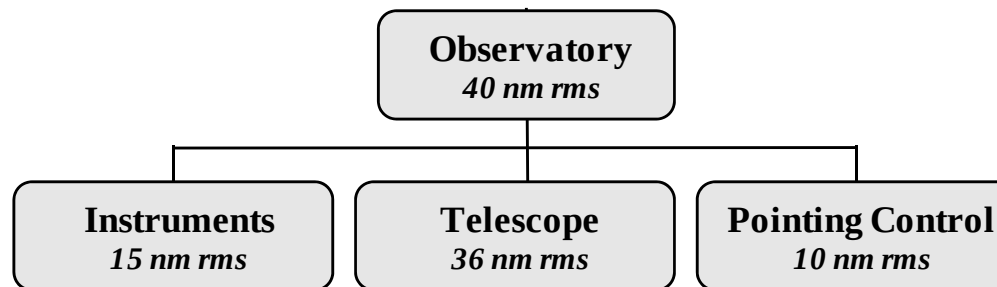
8m Telescope Requirements for Coronagraph

On-axis Monolithic 8-m Telescope with $3\lambda/D$ Coronagraph			
Performance Parameter	Specification	Source	Comments
Maximum total system rms WFE	38 nm	Diffraction limit (80% Strehl ratio at 500 nm)	
Encircled Energy Fraction (EEF)	80% within 16 mas at 500 nm	HST spec, modified to larger aperture and slightly bluer wavelength	Vary < 5% across 4 arcmin FOV
EEF stability	<2%	JWST	
WFE stability over 20 minutes	~1.5 nm	$\lambda/500$ at 760 nm	
PM rms surface error	5 - 10 nm	HST / ATLAST studies	
Pointing stability (jitter)	~2 mas	Guyon, scaled from HST	~ 0.5 mas floor determined by stellar angular diameter.
Mid-frequency WFE	< 20 nm	HST	

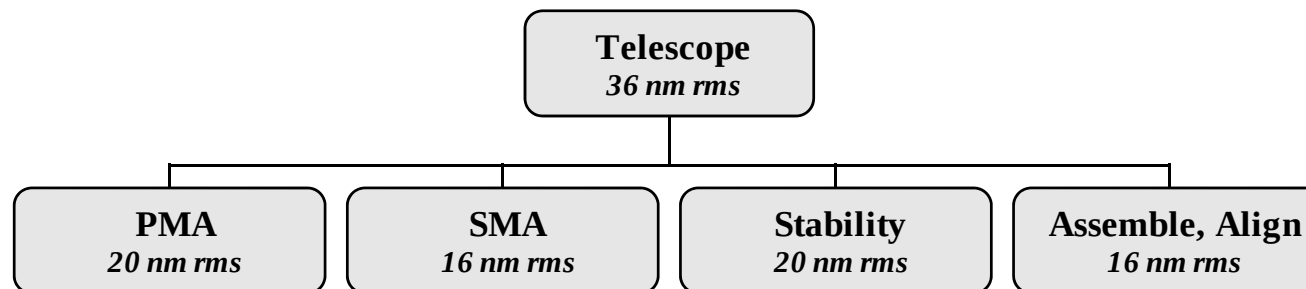


Primary Mirror Total Surface Figure Requirement

Primary Mirror requirements are derived by flowing System Level diffraction limited and pointing stability requirements to major observatory elements:



The flowing the Telescope Level Requirements to its major Sub-Systems

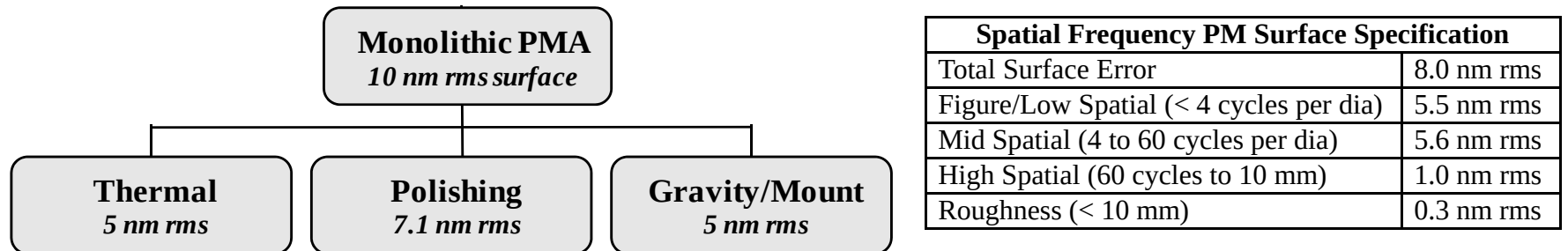




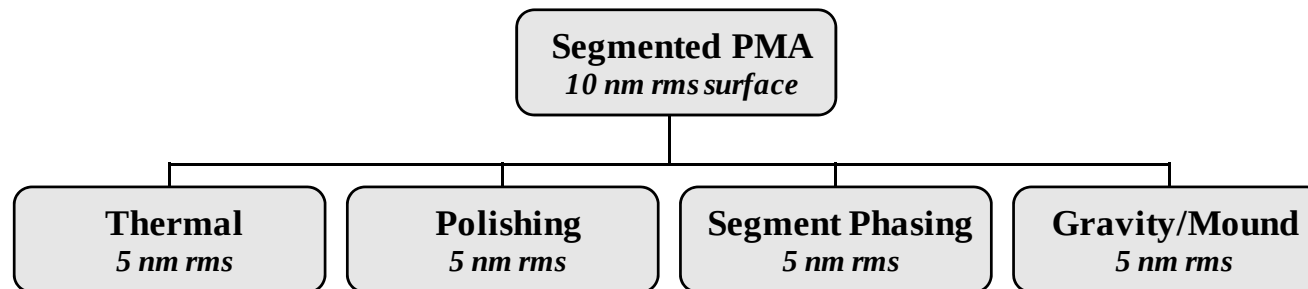
Primary Mirror Total Surface Figure Requirement

Regardless whether monolithic or phased, PM must have < 10 nm rms surface.

Monolithic PM Specification depends on its Thermal behavior and Mounting Uncertainty, leaving $< \sim 8$ nm rms for Total Manufactured WFE.



Segmenting increases complexity and redistributes the error allocations.
But there is currently no consensus on the Segment Phasing error allocation.





43 cm Deep Core Mirror

Future large aperture space telescopes need low-areal-density high-stiffness mirror substrates. This requires deeper substrates.

State of the Art is ATT Mirror: 2.4 m, 3-layer, 0.3 m deep, 60 kg/m² substrate

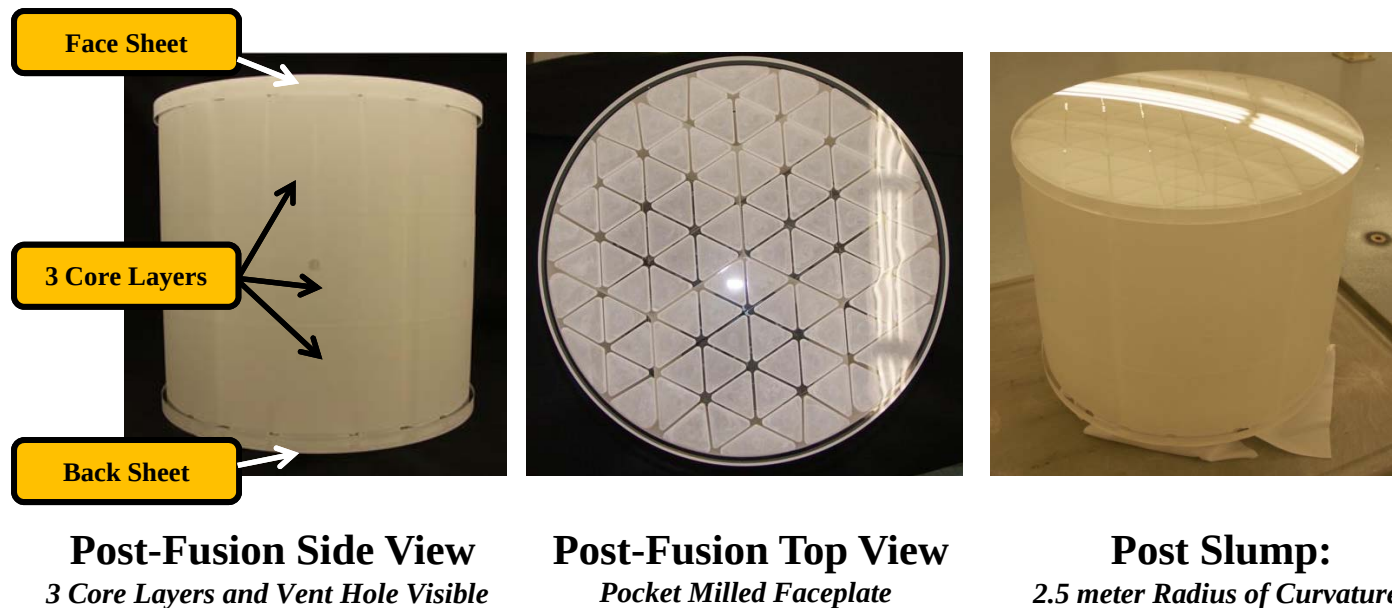
Also 1.4 m AMSD and 1 m Kepler



43 cm Deep Core Mirror

Exelis successfully demonstrated 5-layer 'stack & fuse' technique which fuses 3 core structural element layers to front & back faceplates.

Made 43 cm 'cut-out' of a 4 m dia, > 0.4 m deep, 60 kg/m^2 mirror substrate.



This technology advance leads to stiffer 2 to 4 to 8 meter class substrates at lower cost and risk for monolithic or segmented mirrors.

Matthews, Gary, et al, *Development of stacked core technology for the fabrication of deep lightweight UV quality space mirrors*, SPIE Conference on Optical Manufacturing and Testing X, 2013.



Mid/High Spatial Frequency

UVOIR telescopes require a ~ 7 nm rms primary mirror surface figure.

State of the Art for 60 kg/m^2 mirrors is:

- ~ 10 nm rms on AMSD

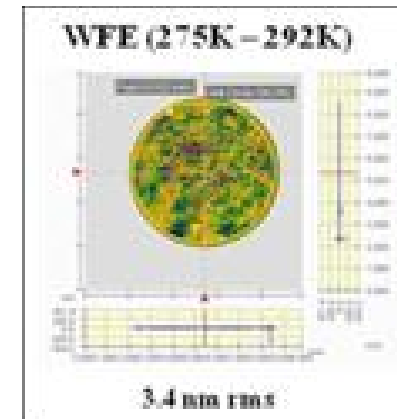
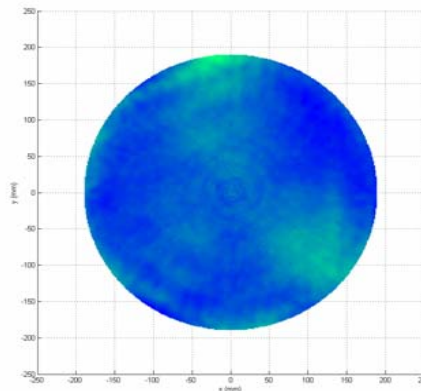
- ~ 20 nm rms on ATT

HST at 170 kg/m^2 mirrors was ~ 7 nm rms.



Mid/High Spatial Frequency Error

Exelis polished 43 cm deep-core mirror to a zero-gravity figure of 5.5 nm rms using ion-beam figuring to eliminate quilting.



Capability is traceable to UVOIR figure specification.

MSFC tested 43 cm mirror from 250 to 300K. Its thermal deformation was insignificant (smaller than 4 nm rms ability to measure the shape change)

Matthews, Gary, et al, *Development of stacked core technology for the fabrication of deep lightweight UV quality space mirrors*, SPIE Conference on Optical Manufacturing and Testing X, 2013.

Matthews, Gary, et al, *Thermal testing of a stacked core mirror for UV applications*, SPIE Conference on Material Technologies and Applications to Optics, Structures, Components, and Sub-Systems, 2013.

Eng, Ron, et. al., *Cryogenic optical performance of a lightweighted mirror assembly for future space astronomical telescopes: correlation of optical test results and thermal optical model*, SPIE Conference on Material Technologies and Applications to Optics, Structures, Components, and Sub-Systems, 2013.



Model Validation

On-orbit performance is determined by mechanical and thermal stability.
Future systems require validated performance models.



Deep Core Thermal Model

Thermal Model of 43 cm deep core mirror generated and validate by test.

43 cm deep core mirror tested from 250 to 300K

Test Instrumentation

4D Instantaneous Interferometer to measure surface Wavefront Error

InSb Micro-bolometer to measure front surface temperature gradient to 0.05C

12 Thermal Diodes.

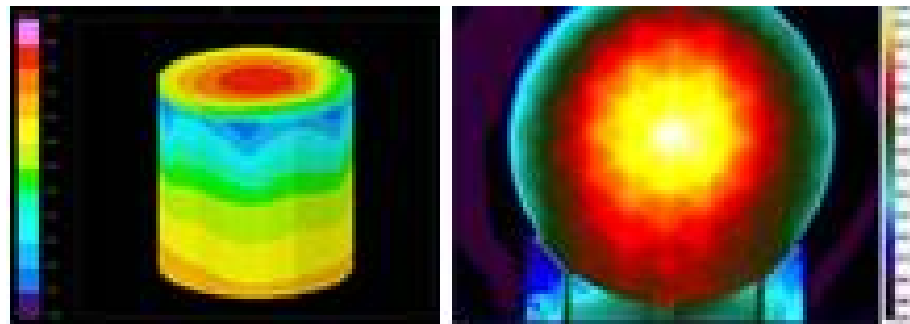


Figure 3-13 Predicted vs Actual

NOTE: This was first ever XRCF test using thermal imaging to monitor temperature

Matthews, Gary, et al, *Thermal testing of a stacked core mirror for UV applications*, SPIE Conference on Material Technologies and Applications to Optics, Structures, Components, and Sub-Systems, 2013.

Eng, Ron, et. al., *Cryogenic optical performance of a lightweighted mirror assembly for future space astronomical telescopes: correlation of optical test results and thermal optical model*, SPIE Conference on Material Technologies and Applications to Optics, Structures, Components, and Sub-Systems, 2013.



Edge Apodization

Successfully demonstrated achromatic edge apodization process.

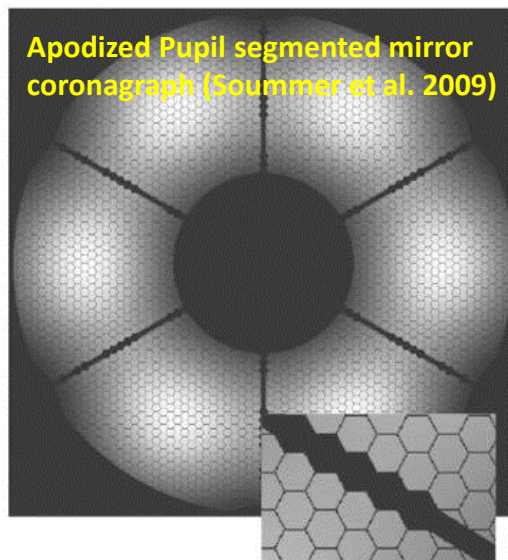
This technology minimizes segment edge diffraction and straylight on high-contrast imaging PSF.

Sivaramakrishnan, Anand, *Calibrating apodizer fabrication techniques for high contrast coronagraphs on segmented and monolithic space telescopes*, SPIE Conference on UV/Optical/IR Space Telescopes and Instrumentation, 2013.



Primary mirror segment gap apodization in the optical

A. Sivaramakrishnan, G. L. Carr, R. Smith, X. X. Xi, & N. T. Zimmerman



Apodization mitigates segment gaps

Achromatic apodization in collimated space

Tolerancing can be tight

Gemini Planet Imager (1.1-2.4 μm) – 0.5% accuracy req.

UVOIR space coronagraphy - 0.55 – 1.1 μm

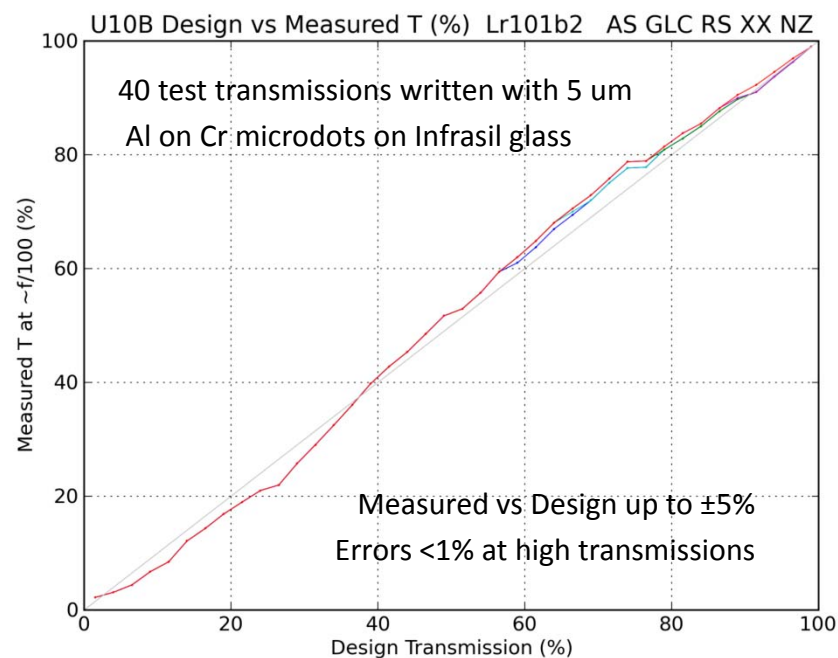
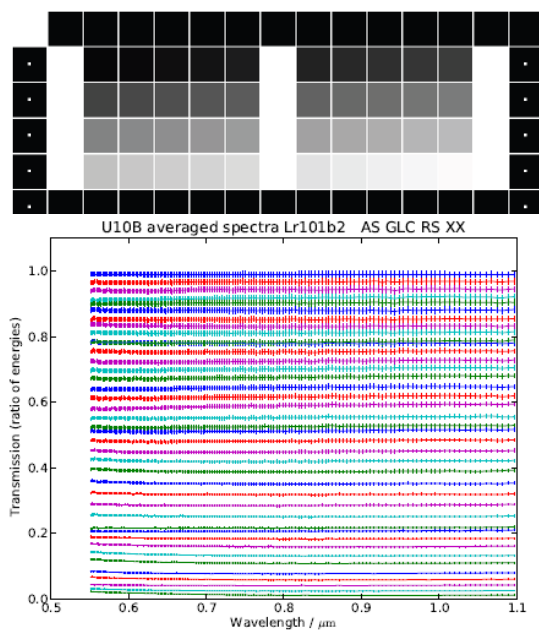
Metal-on-glass dots look OK

Next

Develop & confirm on reflective surfaces

Reqs. on accuracy, reflectivity, absorption/, polarization?

Use larger dots to reduce non-linearity



Use of the National Synchrotron Light Source, Brookhaven National Laboratory, was supported by the U.S. Department of Energy, Office of Science, Office of Basic Energy Sciences, under Contract No. DE-AC02-98CH10886.



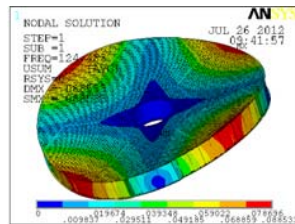
Design Tools and Point Designs



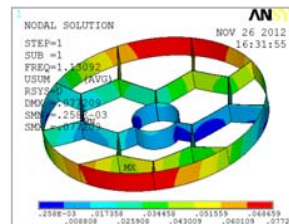
Design Tools and Point Designs

AMTD has developed a powerful tool which quickly creates monolithic or segmented mirror designs; and analyzes their static & dynamic mechanical and thermal performance.

Point Designs: AMTD has used these tools to generate Pre-Phase-A point designs for 4 & 8-m mirror substrates.



**Free-Free 1st Mode: 4 m
dia 40 cm thick substrate**



**Internal Stress: 4 m dia
with 6 support pads**

Support System: AMTD has used these tools to generate Pre-Phase-A point designs for 4-m mirror substrate with a launch support system.

Arnold, William et al, *Next generation lightweight mirror modeling software*, SPIE Conference on Optomechanical Engineering, 2013.

Arnold, William et al, *Integration of Mirror design with Suspension System using NASA's new mirror modeling software*, SPIE Conference on Optomechanical Engineering, 2013.



Monolithic Substrate Point Designs

4-m designs are mass constrained to 720 kg for launch on EELV

8-m designs are mass constrained to 22 mt for launch on SLS

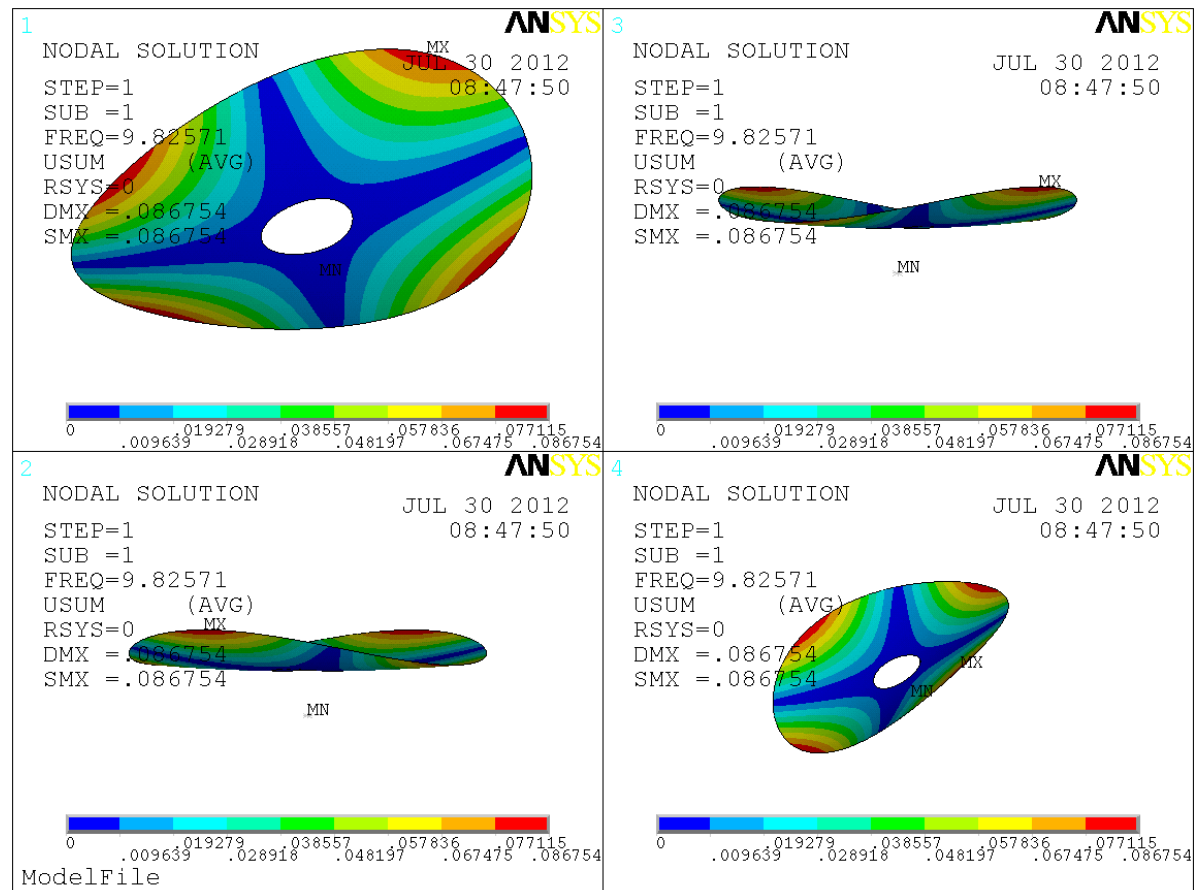


Trade Study Concept #1: 4 m Solid

Design:

Diameter 4 meters
Thickness 26.5 mm
Mass 716 kg
First Mode 9.8 Hz

SET	TIME/FREQ
1	9.8257
2	9.8257
3	23.548
4	23.552
5	41.021
6	41.021
7	62.123
8	62.123
9	86.807
10	86.807

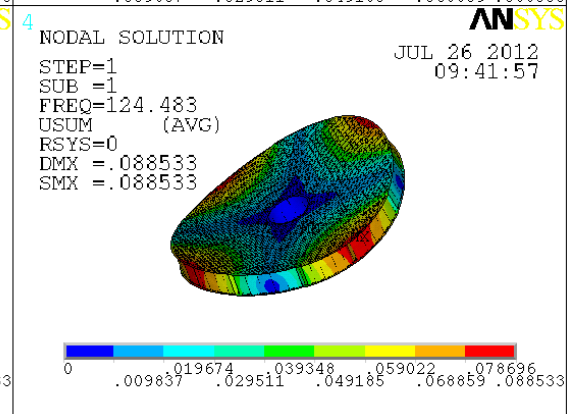
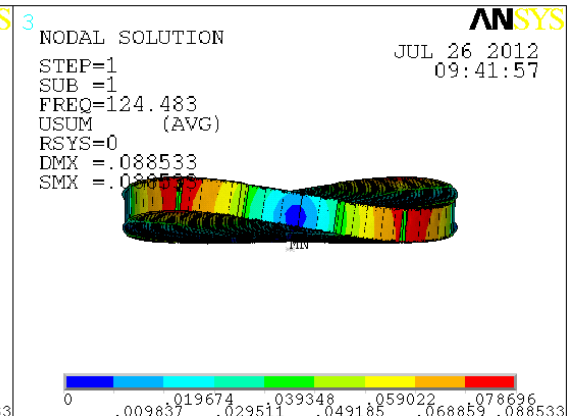
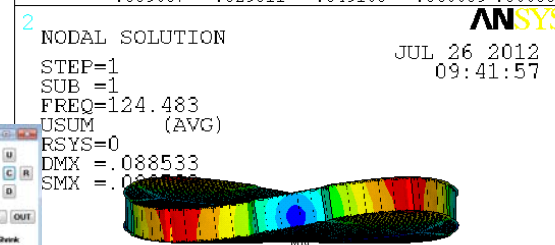
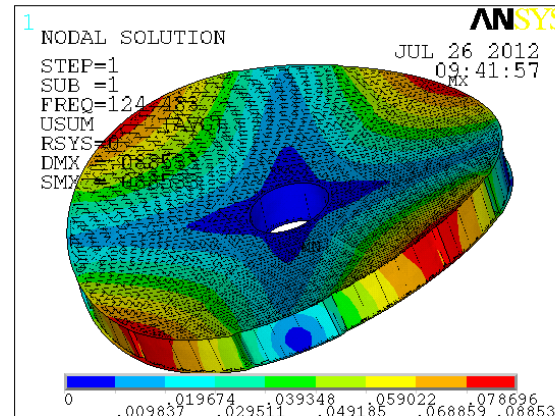
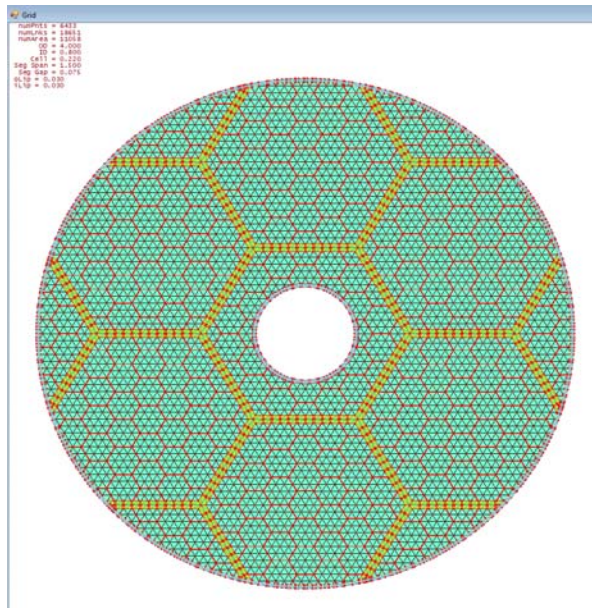




Trade Study Concept #2: 4 meter Lightweight

Design:

Diameter 4 meters
Thickness 410 mm
Facesheet 3 mm
Mass 621 kg
First Mode 124.5 Hz



SET	TIME/FREQ
1	124.48
2	124.77
3	199.39
4	257.85
5	275.88
6	321.22
7	321.60
8	350.07
9	350.08
10	350.33



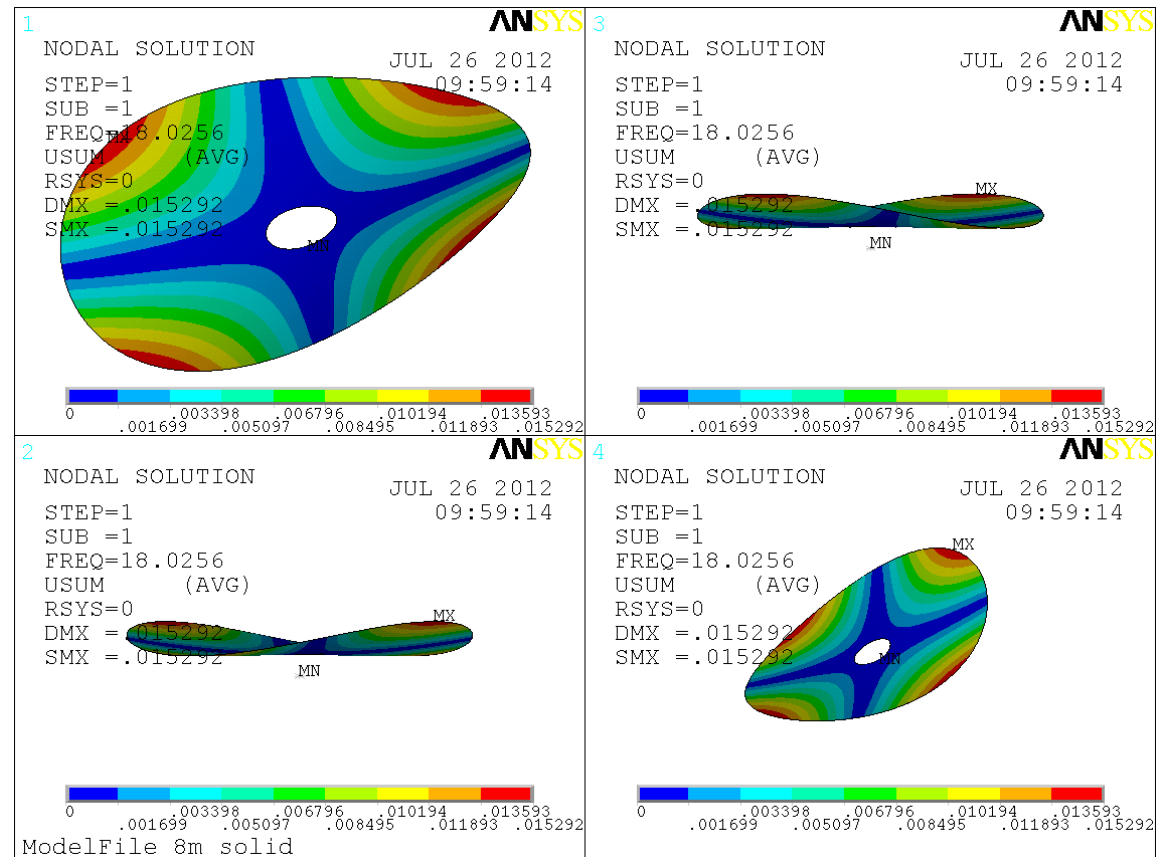
Trade Study Concept #3: 8 meter Solid 22 MT

Design:

Diameter 8 meter
Thickness 200 mm
Mass 21,800 kg
First Mode 18 Hz

Same as ATLAST Study

SET	TIME/FREQ
1	18.026
2	18.035
3	42.449
4	42.452
5	47.827
6	74.041
7	74.045
8	75.174
9	75.176
10	112.96





Trade Study Concept #4: 8 meter Lightweight

Design:

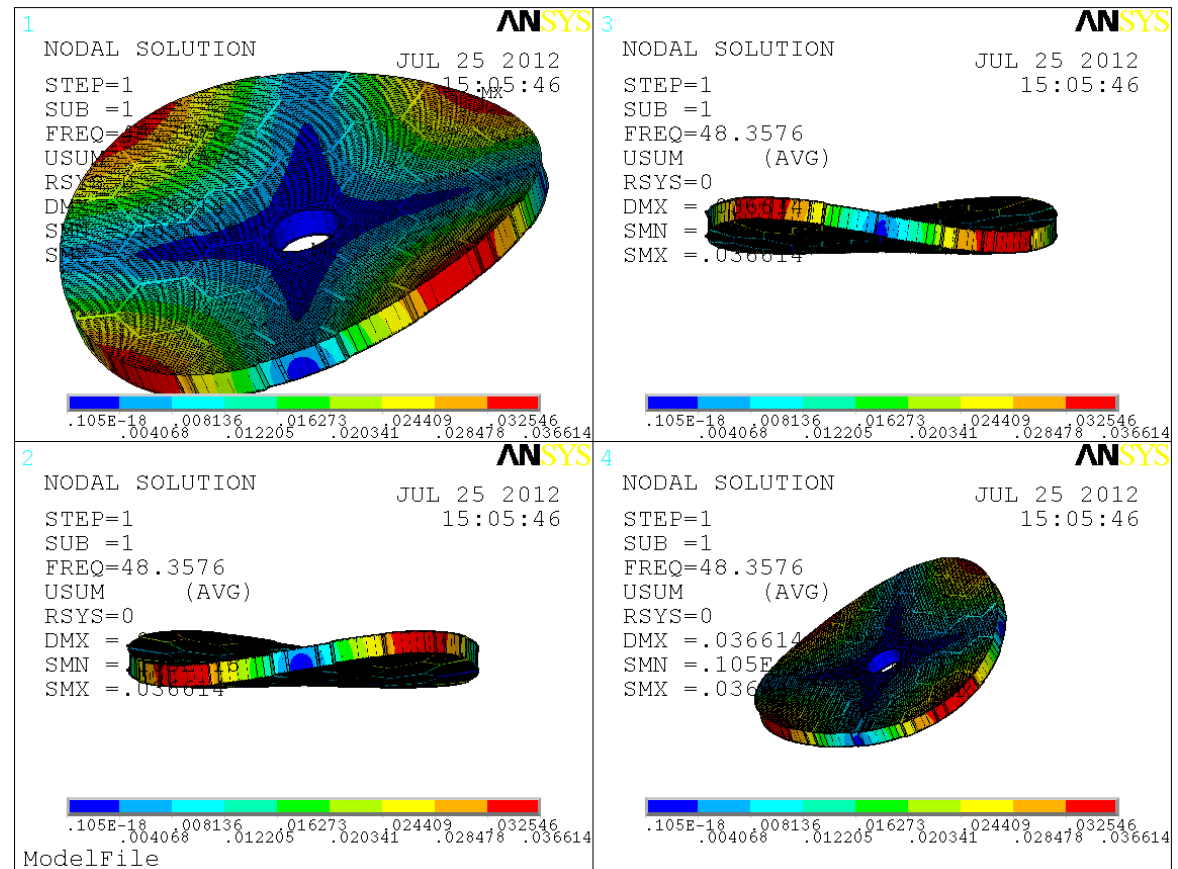
Diameter 8 meter

Thickness 510 mm

Facesheet 7 mm

Mass 3,640 kg

First Mode 48.4 Hz





Modeling Tool



Program Control Window

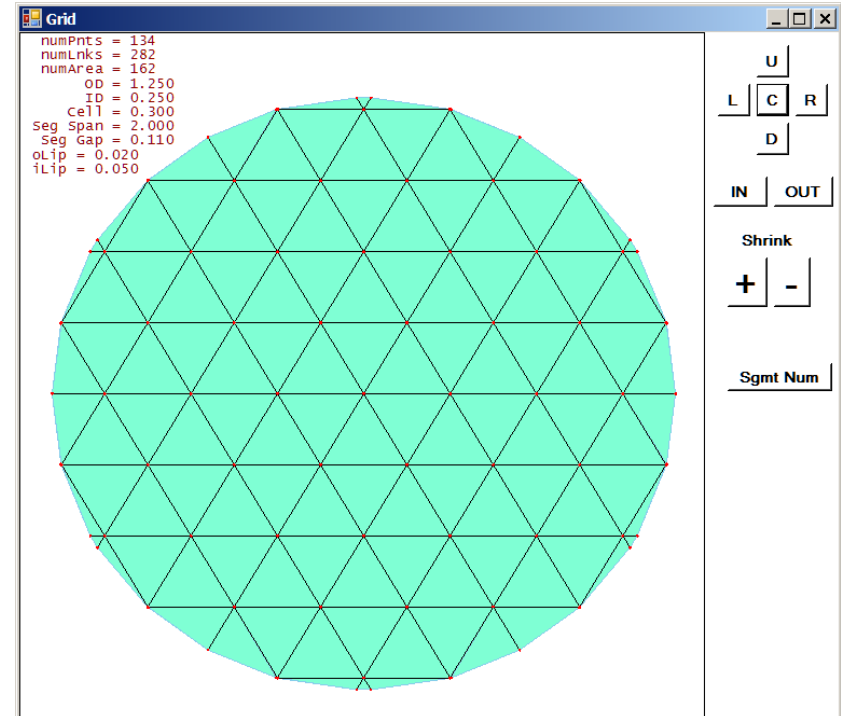
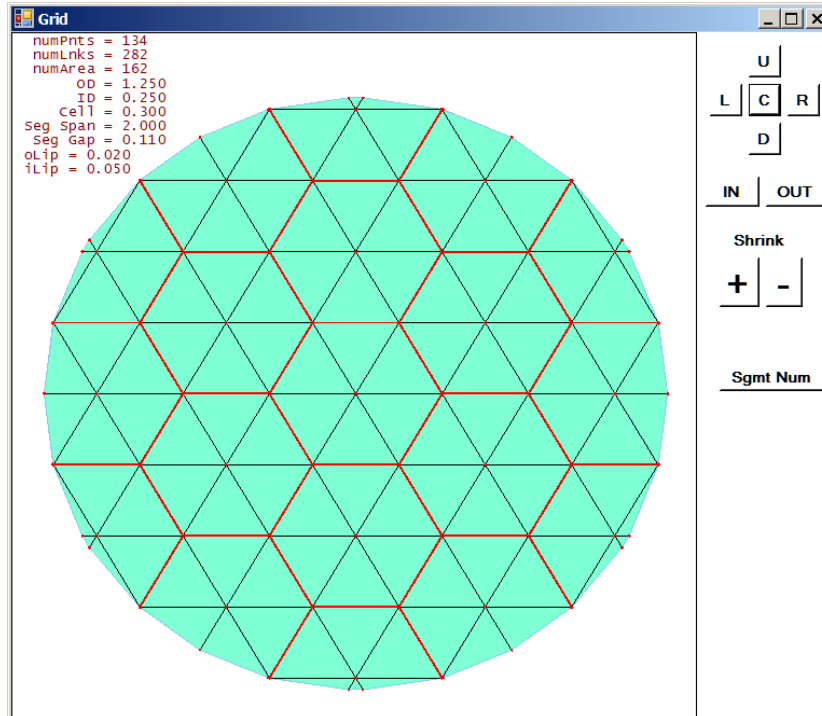
Arnold Lightweight Mirror Modeler (Ver 2.0) [X]

Outer Dia	2	Supports ☐ Each Segment ☒ Whole Mirror	DISPLAY GRID				
Inner Dia	0.25			DISPLAY MODEL			
Cell Width	0.3				WRITE MODEL		
Lip Inner	0.05					SAVE RESTORE	
Segment Lip	0.05						MERGE NODES
Mirror Lip	0.1						
Num Rings	0	☒ Show Whole Grid					
Sgmt Span	1	☐ Show Supports					
Sgmt Gap	0.15	☐ Show Fillets					
Merge Tol	0.025	Modal (PSD) Boule Mapping					
Grid Zoom	1	Grid Options Optical Reals Core Hexapod Axial Radial Inertial Loads					
Segment Shown	1	☐ Outer Sgmt Lip					
Srink Factor	0.05	☐ Outer Mirror Lip					
		☐ Inner Mirror Lip					
		☐ Circular Segment					
		☐ Circular Mirror					
		☒ Seal Ring Outer					
		☒ Seal Ring Inner					
		☒ Seal Ring Mirror					
		☐ Segment Lip Ribs					
		☐ Isogrid Front					
		☐ Isogrid Back					
		☐ Backface Holes					
		☐ Core Projection					
		☐ Include Fillets					
		☐ Off Center Pattern					
		☐ No Backsheet					
		☐ Central Hole					
		☐ Cell Level 0					
		☐ Cell Level 1					
		☒ Cell Level 2					

Status

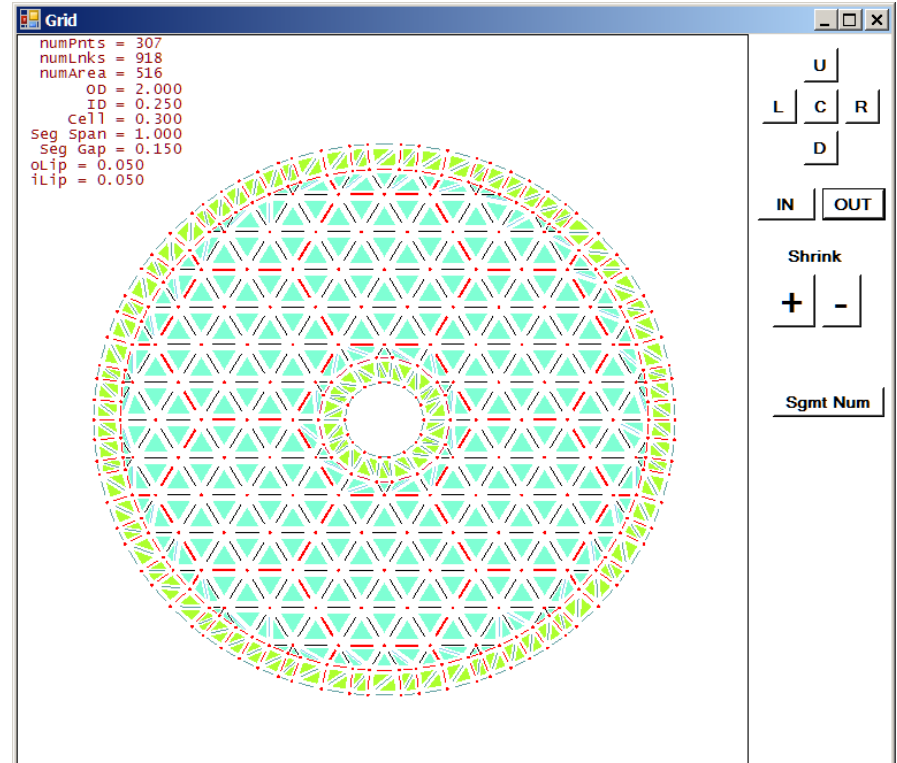
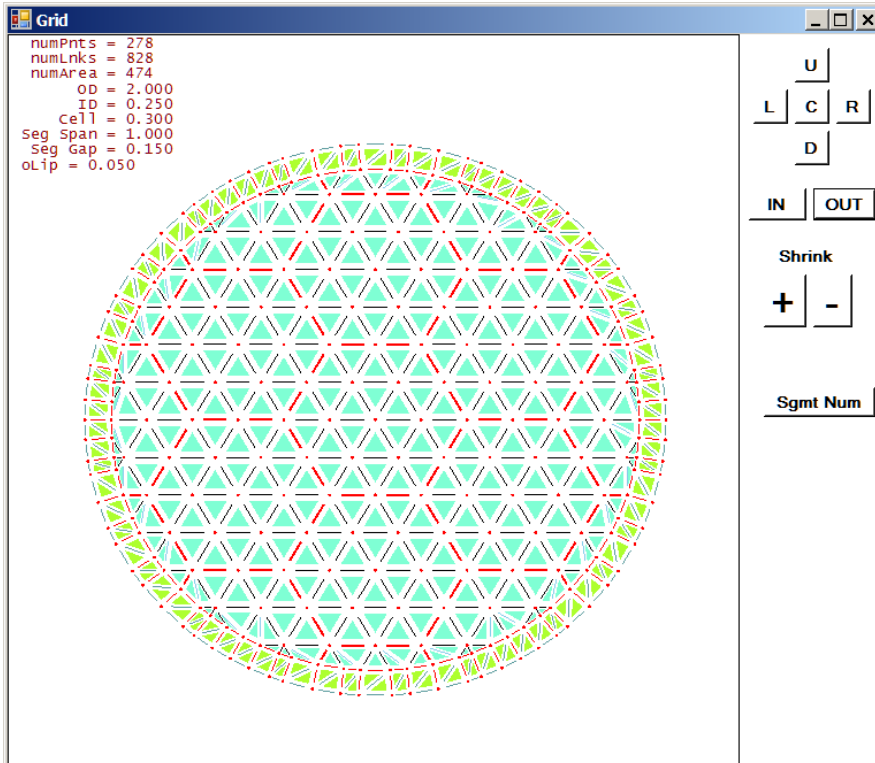


Isogrid and Simplified Meshes



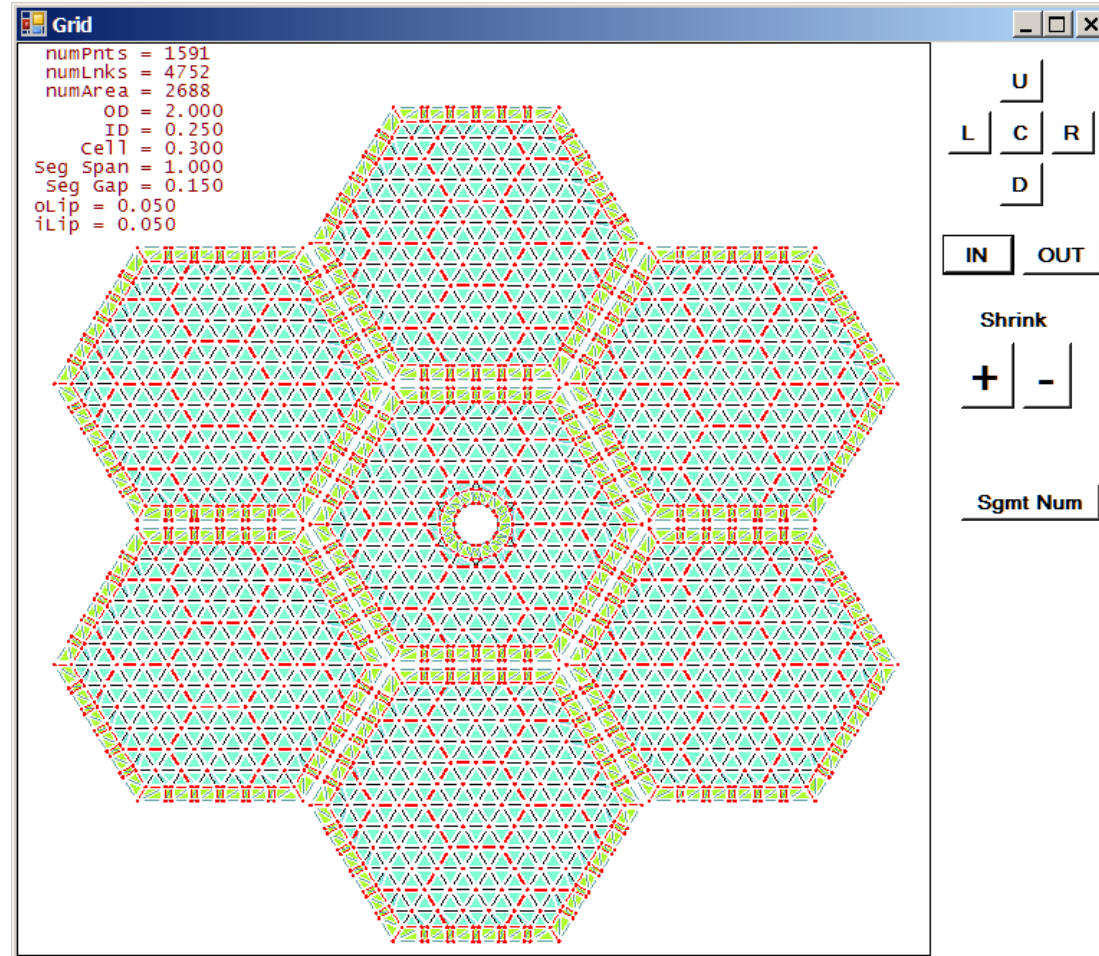


Easily Add a Central Hole



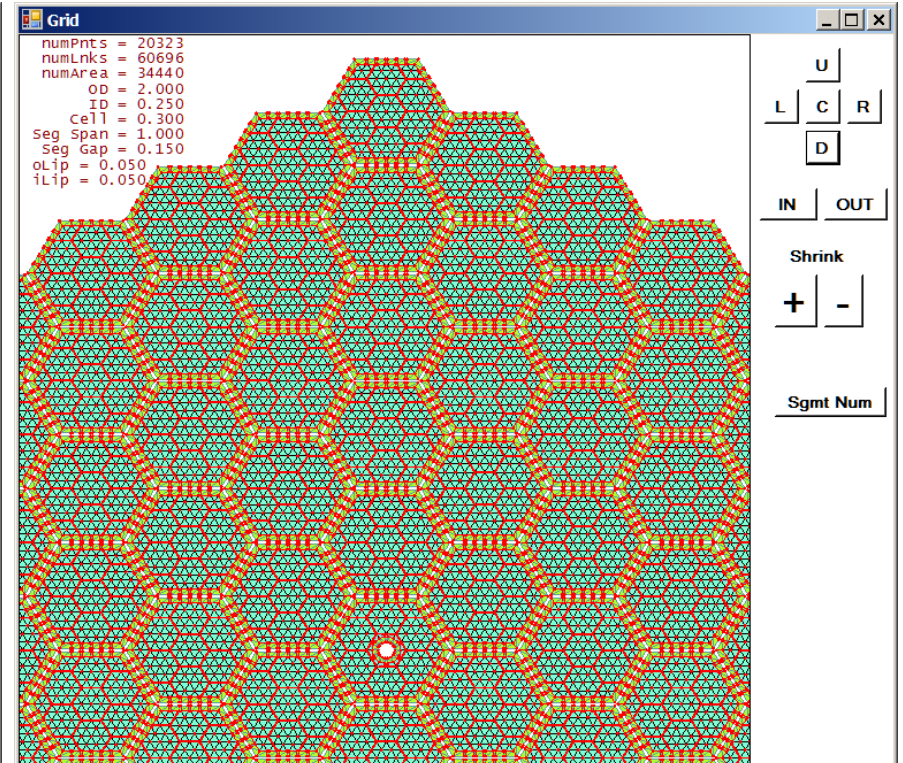
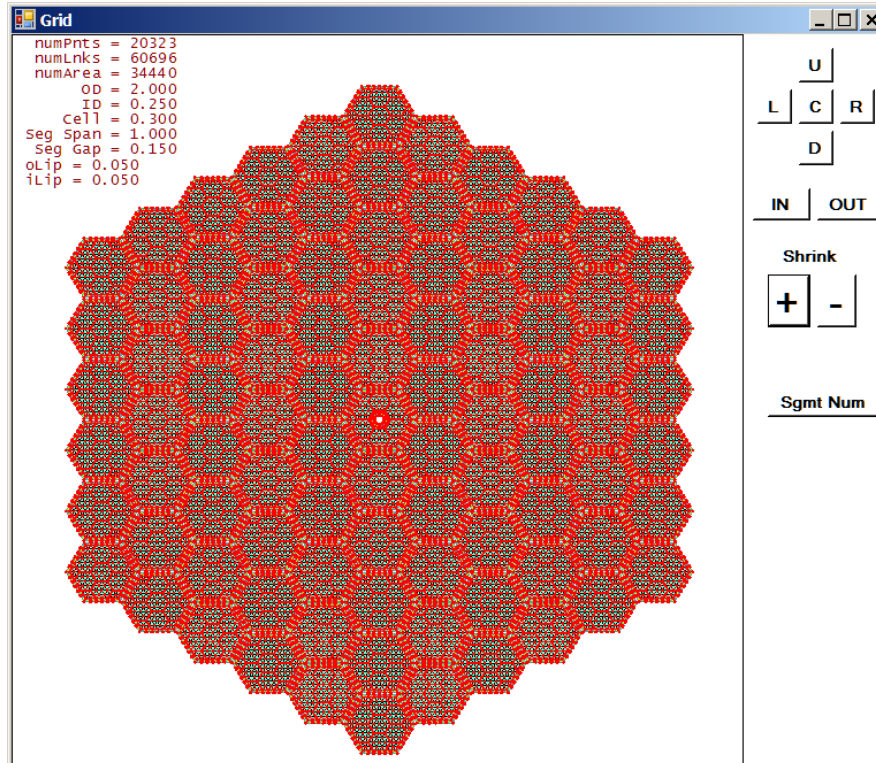


Segmented Mirrors



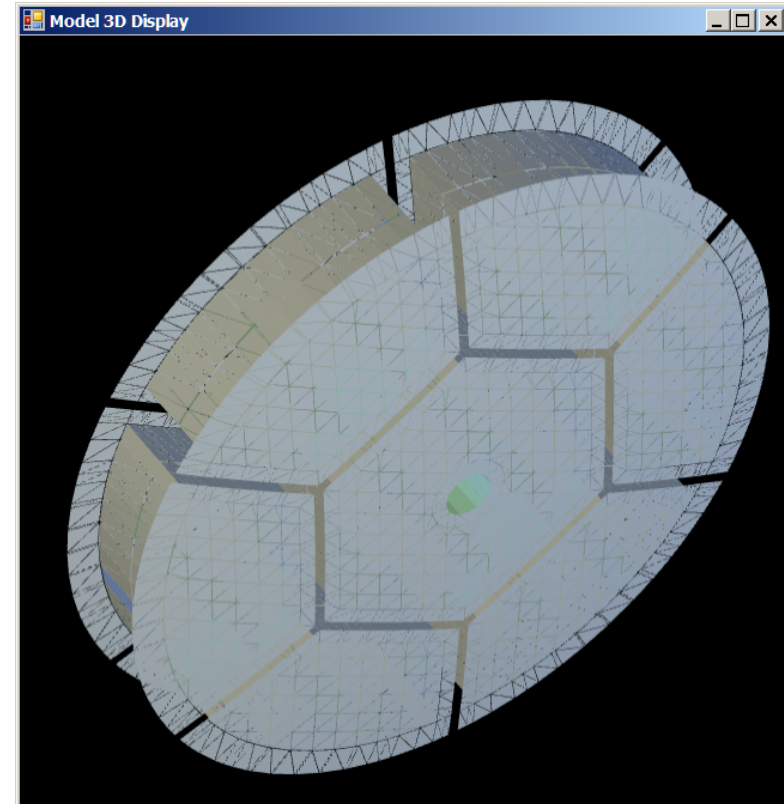
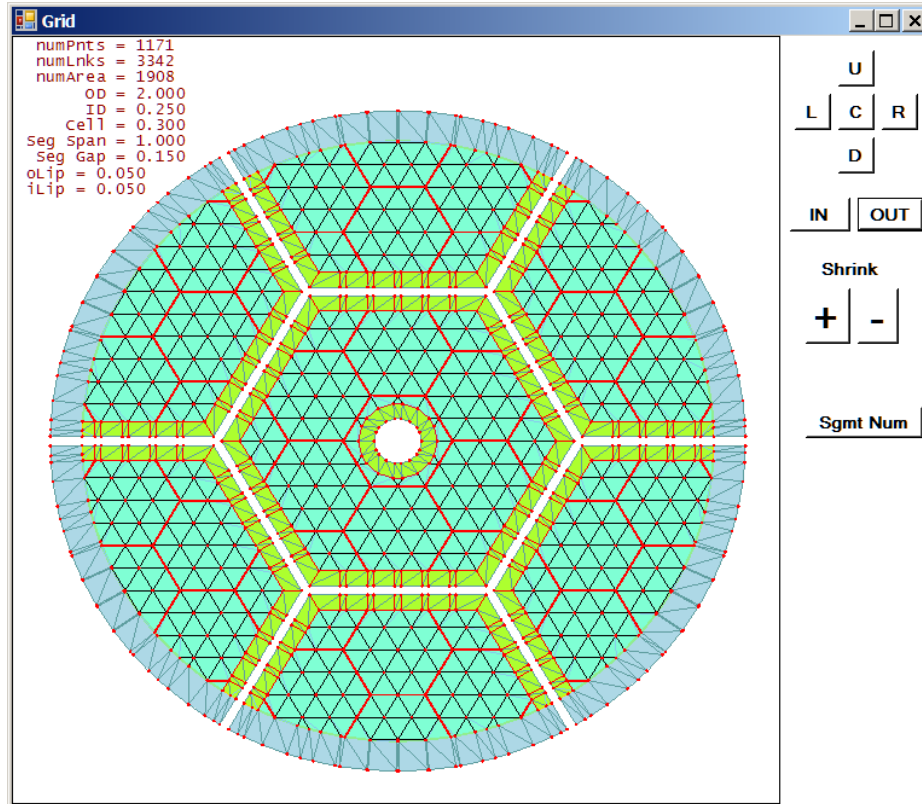


Almost Unlimited Size



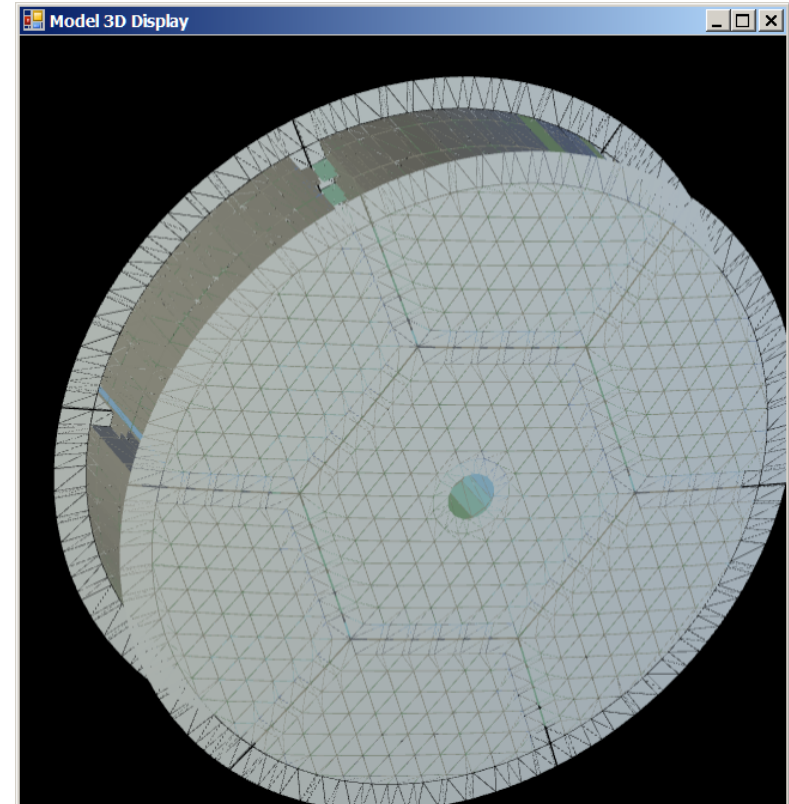
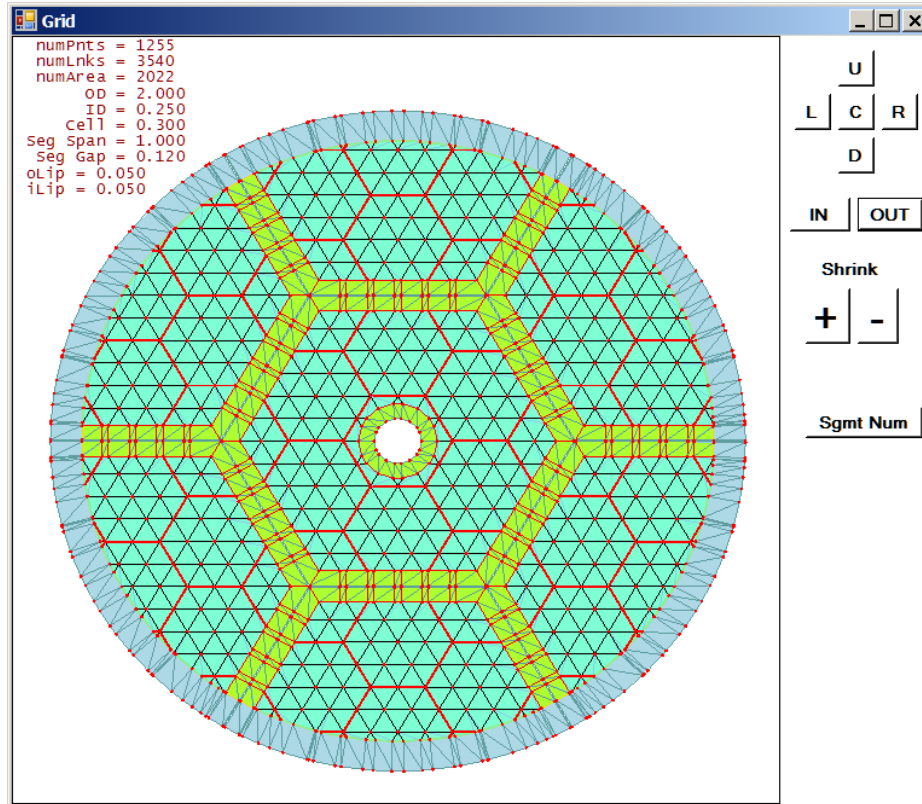


Circular Segmented Mirrors





Model can be Merged in One Mirror





Whole Mirror or Segment Supports

Arnold Lightweight Mirror Modeler (Ver 2.0)

Outer Dia	2	Model Statistics		Supports		DISPLAY GRID	
Inner Dia	0.25	6830	num Nodes	☐ Each Segment	DISPLAY MODEL		
Cell Width	0.3	15751	num Elems	☒ Whole Mirror	WRITE MODEL		
Lip Inner	0.05	206.4664	Weight (kg)	☒ Show Whole Grid	SAVE RESTORE		
Segment Lip	0.05	17.01546	Area (m ²)	☐ Show Supports	MERGE NODES		
Mirror Lip	0.1	12.13405	W/A (kg/m ²)	☐ Show Fillets			

Num Rings: 2
Sgmt Span: 1.25
Sgmt Gap: 0.11
Merge Tol: 0.025
Grid Zoom: 0.99
Segment Shown: 1
Sink Factor: 0.12

Modal (PSD) | **Boule Mapping**
Grid Options | Optical | Reals | Core | Hexapod | Axial | Radial | Inertial Loads

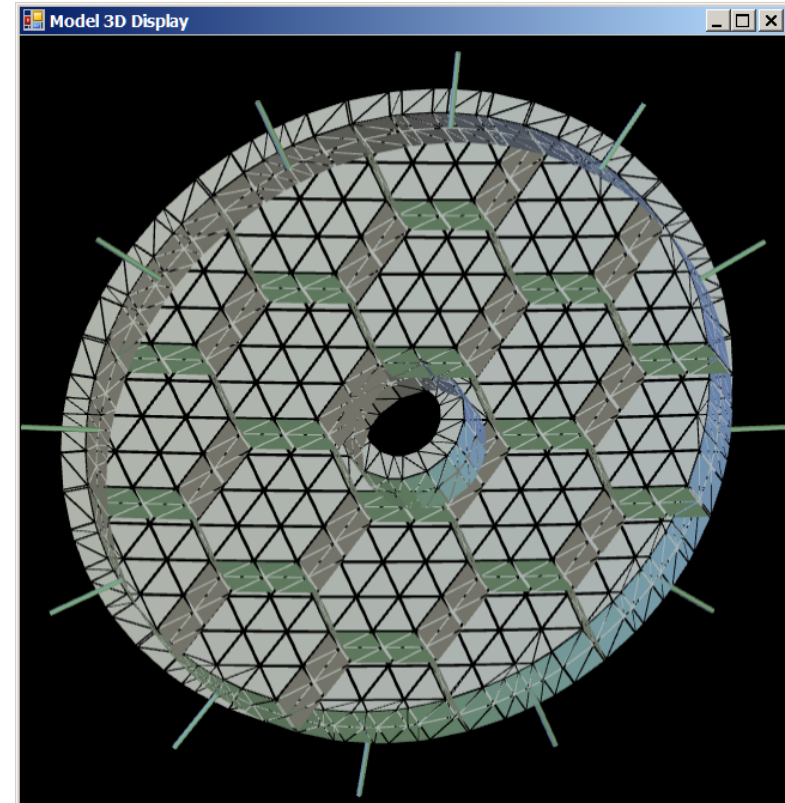
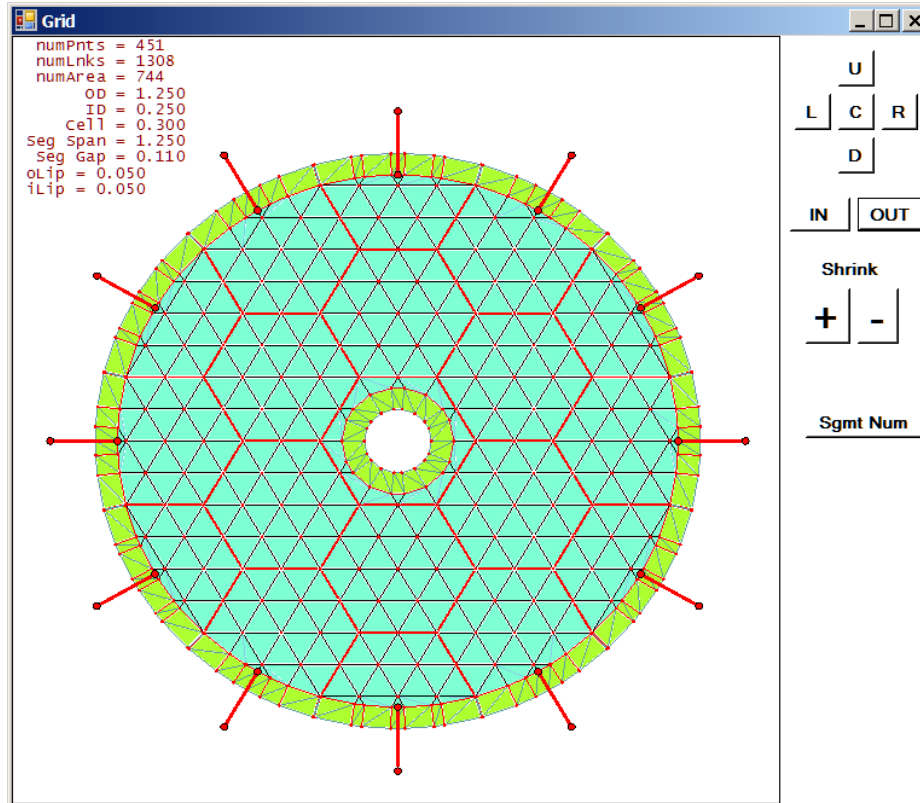
☐ Do Radial Support

Num Points: 12
Support Length: 0.15 (m)
Spring Rate: 2000 (N/m)
Start Angle: 0 (deg)
Fitting Mass: 1 (kg)
Acceptable Near: 1E-05 (m)

Status: 21 elems with bad aspect ratios

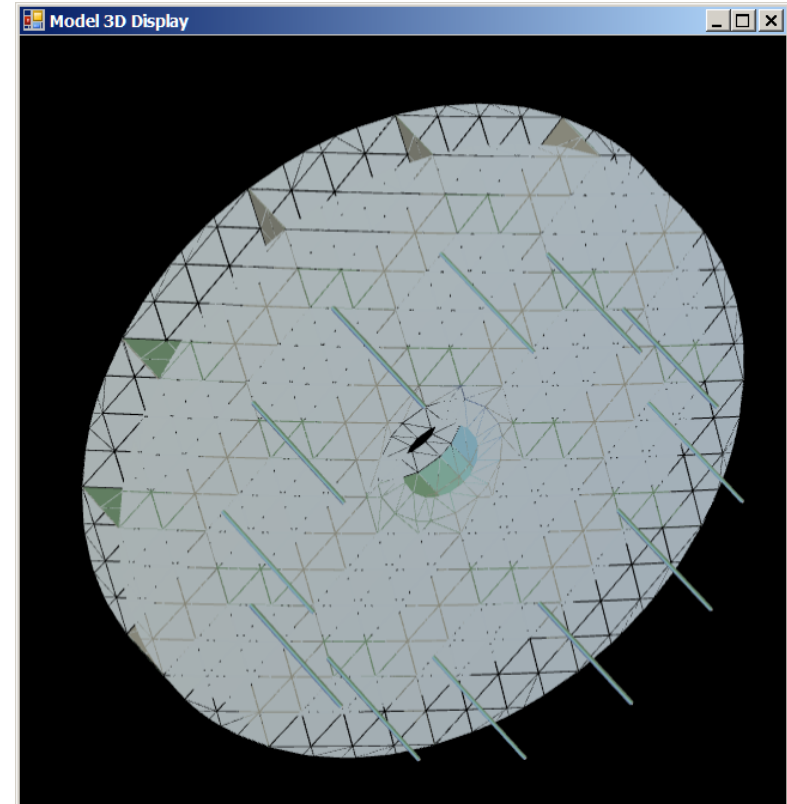
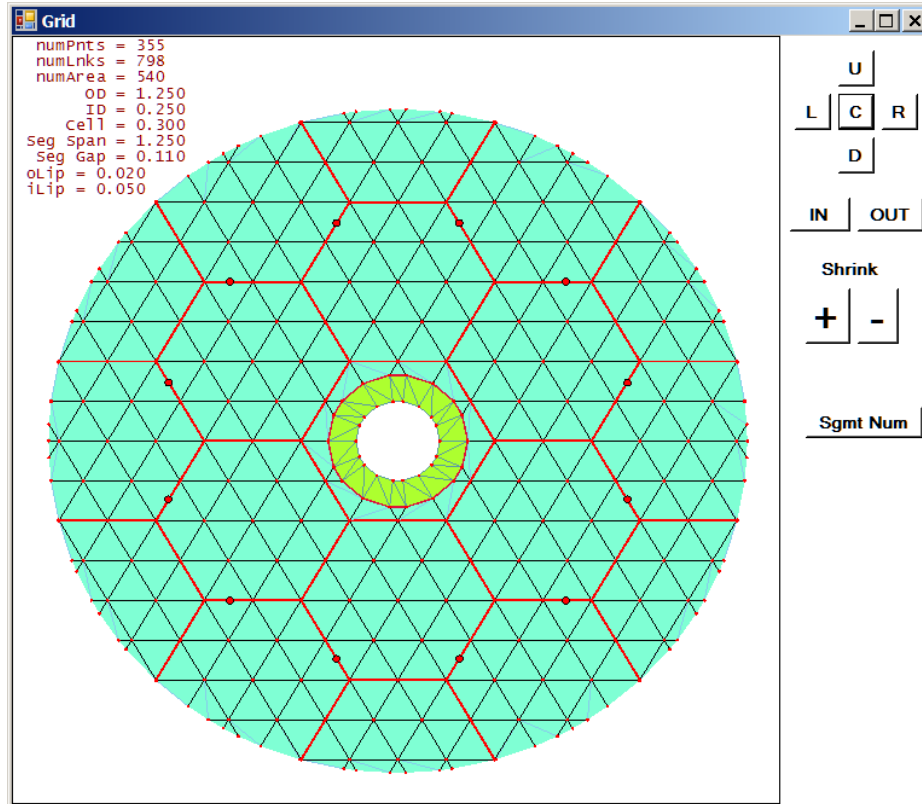


Radial Support



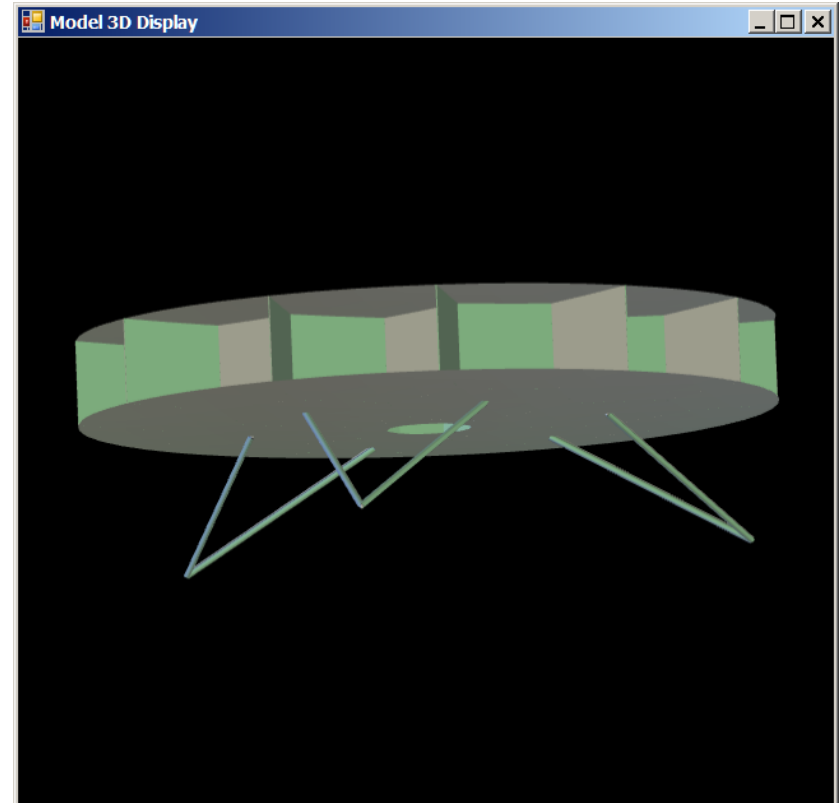
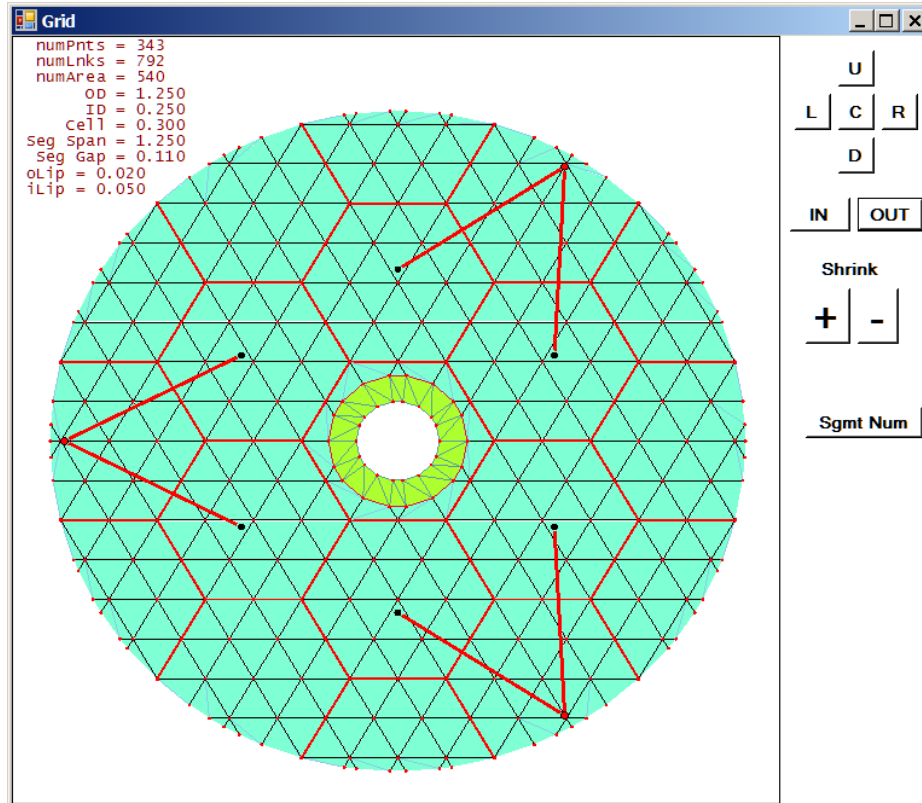


Axial Support





Hexapod Support





Generate Static Loading Conditions

Arnold Lightweight Mirror Modeler (Ver 2.0)

Outer Dia: 2
Inner Dia: 0.25
Cell Width: 0.3
Lip Inner: 0.05
Segment Lip: 0.05
Mirror Lip: 0.1

Num Rings: 2
Sgmt Span: 1.25
Sgmt Gap: 0.11
Merge Tol: 0.025

Grid Zoom: 0.99
Segment Shown: 1
Sink Factor: 0.12

Model Statistics

6830	num Nodes
15751	num Elms
206.4664	Weight (kg)
17.01546	Area (m ²)
12.13405	W/A (kg/m ²)

Supports

☐ Each Segment
☒ Whole Mirror

☒ Show Whole Grid
☐ Show Supports
☐ Show Fillets

DISPLAY GRID
DISPLAY MODEL
WRITE MODEL
SAVE **RESTORE**
MERGE NODES

Modal (PSD) **Boule Mapping**

Grid Options **Optical** **Reals** **Core** **Hexapod** **Axial** **Radial** **Inertial Loads**

	Accel X	Accel Y	Accel Z
1	0	0	0
2	0	0	0
3	0	0	0
4	0	0	0
5	0	0	0
6	0	0	0
7	0	0	0
8	0	0	0

☐ Calculate Static LCs
num Loadcases: 0

Status 21 elms with bad aspect ratios



Generate Dynamic Loading Sets

Arnold Lightweight Mirror Modeler (Ver 2.0)

Outer Dia: 2
Inner Dia: 0.25
Cell Width: 0.3
Lip Inner: 0.05
Segment Lip: 0.05
Mirror Lip: 0.1

Num Rings: 2
Sgmt Span: 1.25
Sgmt Gap: 0.11
Merge Tol: 0.025

Grid Zoom: 0.99
Segment Shown: 1
Sink Factor: 0.12

Model Statistics

6830	num Nodes
15751	num Elems
206.4664	Weight (kg)
17.01546	Area (m ²)
12.13405	W/A (kg/m ²)

Supports

☐ Each Segment
☒ Whole Mirror

☒ Show Whole Grid
☐ Show Supports
☐ Show Fillets

DISPLAY GRID
DISPLAY MODEL
WRITE MODEL
SAVE **RESTORE**
MERGE NODES

Grid Options | **Optical** | **Reals** | **Core** | **Hexapod** | **Axial** | **Radial** | **Inertial Loads**
Modal (PSD) | **Boule Mapping**

☒ Calculate Modes
num Modes: 10

☐ Calculate X PSD

☐ Calculate Y PSD

☐ Calculate Z PSD

	f1	f2	f3	f4	f5	f6	f7
f	0	0	0	0	0	0	0
g2	0	0	0	0	0	0	0
f	0	0	0	0	0	0	0
g2	0	0	0	0	0	0	0
f	0	0	0	0	0	0	0
g2	0	0	0	0	0	0	0

Status 21 elems with bad aspect ratios



ULE CTE Mapping

Arnold Lightweight Mirror Modeler (Ver 2.0)

Outer Dia	2	Model Statistics		Supports		DISPLAY GRID	
Inner Dia	0.25	6830	num Nodes	☐ Each Segment	DISPLAY MODEL		
Cell Width	0.3	15751	num Elems	☒ Whole Mirror	WRITE MODEL		
Lip Inner	0.05	206.4664	Weight (kg)	☒ Show Whole Grid	SAVE RESTORE		
Segment Lip	0.05	17.01546	Area (m ²)	☐ Show Supports	MERGE NODES		
Mirror Lip	0.1	12.13405	W/A (kg/m ²)	☐ Show Fillets			

Num Rings: 2
Sgmt Span: 1.25
Sgmt Gap: 0.11
Merge Tol: 0.025
Grid Zoom: 0.99
Segment Shown: 1
Sink Factor: 0.12

Grid Options | **Optical** | **Reals** | **Core** | **Hexapod** | **Axial** | **Radial** | **Inertial Loads**
Modal (PSD) | **Boule Mapping**

Input Boule Data	Input Boule Assign Data
Write Boule Data	Write Boule AssignData
Load Boule Data	Load Boule AssignData
List Boule Data	Map Boules to Model

Status 21 elems with bad aspect ratios



Conclusions

Assembled outstanding team from academia, industry and government with expertise in science and space telescope engineering.

Derived engineering specifications for monolithic primary mirror from science measurement needs & implementation constraints.

Pursuing long-term strategy to mature technologies necessary to enable future large aperture space telescopes.

Successfully demonstrated capability to make 0.5 m deep mirror substrate and polish it to UVOIR traceable figure specification.