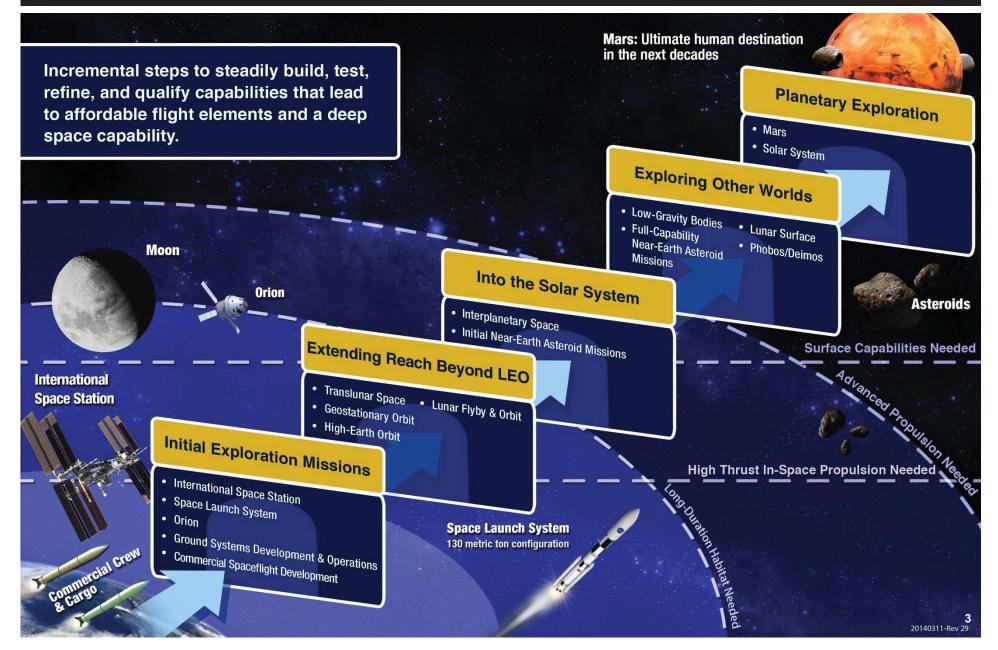


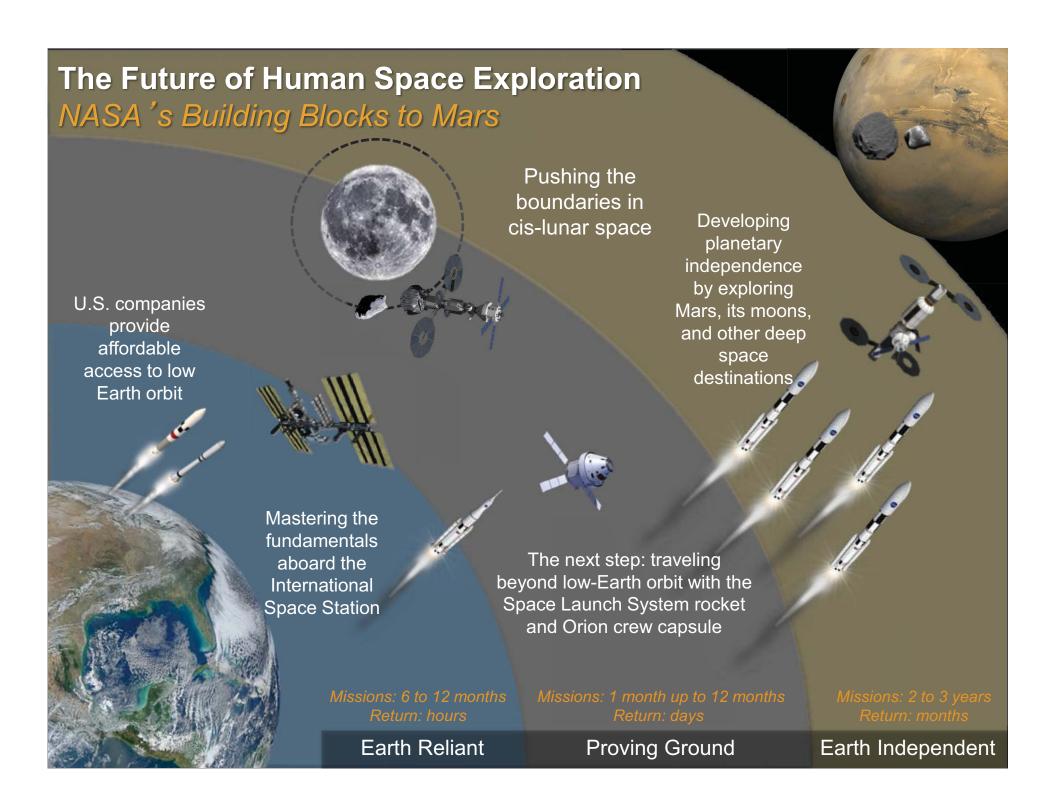
Agenda

- Overview of NASA Vision
- Deep Space Vehicle Power Architecture
- Traditional Space Vehicle Control Architecture
- Intelligent Control Architecture
- Power System Simulations for Test & Verification
- Applicability of Controls to Terrestrial Micro-grids
- Wrap-up

The Capability Driven Framework









What is the problem?

Communication and recovery times are longer than any previous experience

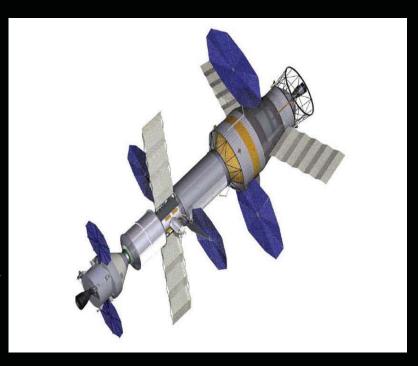
Mission	Duration of Mission After Incident	Communication Latency Time
Deep Space Habitat	9 months to 1 year	15 to 45 mins.
Apollo/Orion	3 – 5 days	1 to 2 sec.
Mount Everest	1 – 2 days	Real time
Deep Sea Submersible	8 hours	Real time
Shuttle	2 – 5 hours	Real time
Submarine	1 – 2 hours	Real time

- Power Is Most Critical System On Board Vehicle
 - System will need a high level of availability
 - System will need to operate autonomously for long periods of time



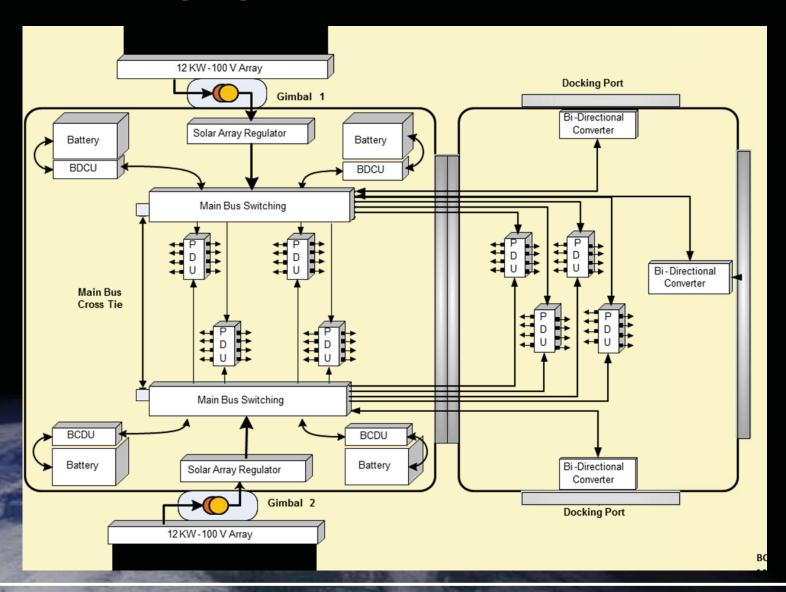
Potential Deep Space Vehicle Power System Characteristics

- Power 10 kW average
- Two independent power channels with multi-level cross-strapping
- Solar array power
 - 24+ kW Multi-junction arrays
- Lithium Ion battery storage
 - 200+ amp*hrs
 - Sized for deep space or low lunar orbit operation
- Distribution
 - 120 V secondary (SAE AS 5698)
 - 2 kW power transfer between vehicles



Deep space vehicle concept

Notional Deep Space Vehicle Power Architecture







So What is Intelligent Power?

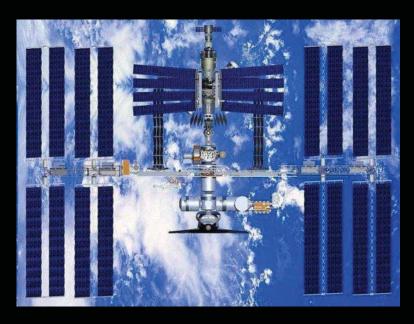




What is Intelligent Power?



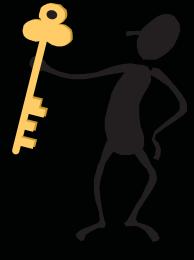
Exploration Systems



Near Earth Systems

An Intelligent Power Controller utilizes advanced hardware and control technology and works in conjunction with the space craft mission manager to autonomously manage and control distributed power generation and storage assets, power distribution networks, and loads for both near earth and space exploration systems.



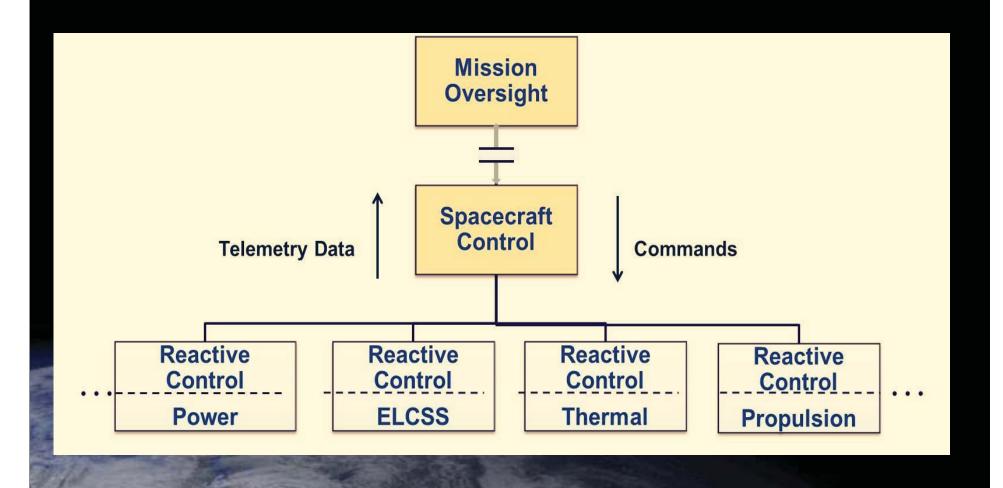


Intelligent Power Architecture



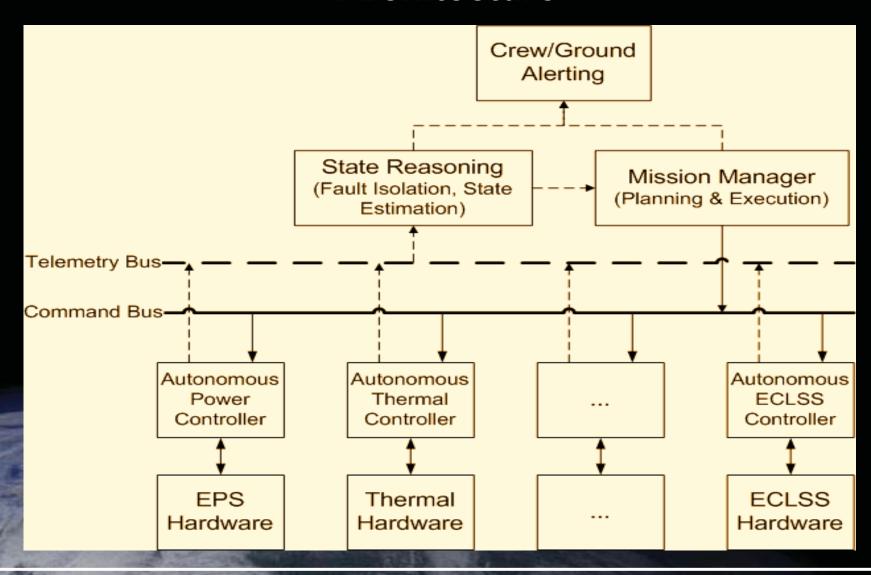


Simplified Space Craft Control Architecture





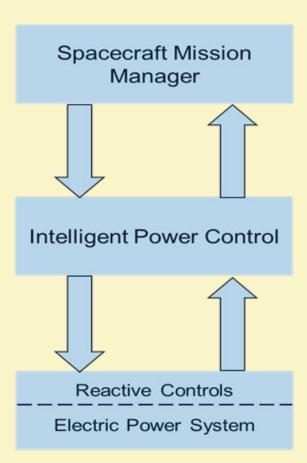
Intelligent Space Craft Controller Architecture





Mission Manager Intelligent Power Control Interface

- Navigation Vectors
- Traffic / Array Pointing Constraints
- Spacecraft (other subsystems) Operations State
- · Proposed load profile
 - •
- Array Pointing
- Array Voltage S.P.
- Battery Charge/Discharge SP.
- · Switchgear Positions



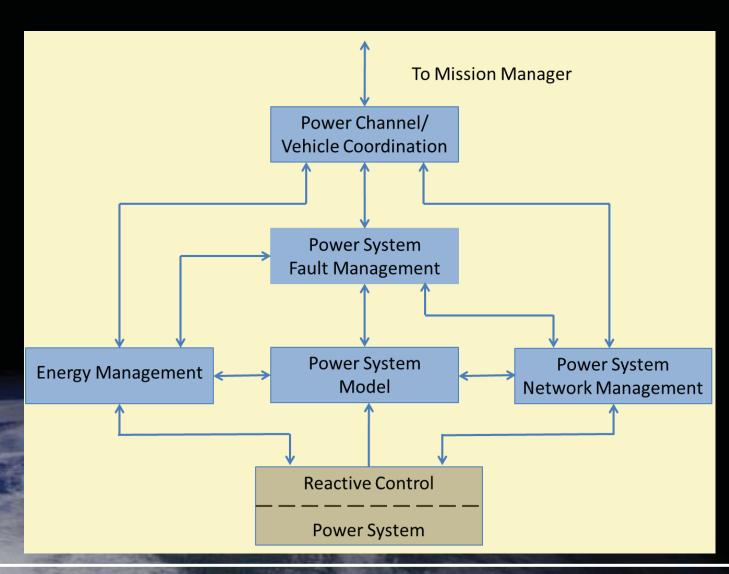
- Energy Availability
- Load Profile Evaluation
- EPS Operating State
- EPS ORU State of Health
- Caution/Warning Alarms
- Proposed Corrective Action(s)

.

- Array Voltage
- Battery Voltage
- · Battery Current
- Main Bus Currents
- · Main Bus Voltages
- · Secondary Bus Voltage
- Secondary Bus Currents
- · Switch States



Intelligent Control Function Architecture





Intelligent Control Functions

- Energy Management
 - Power availability timeline
 - Set points for array regulation, battery charging / discharging,
 - Detect generation and storage failures
- Power System Model
 - Generation model using orbital parameters
 - Energy storage model
 - Power load flow
 - State Estimator

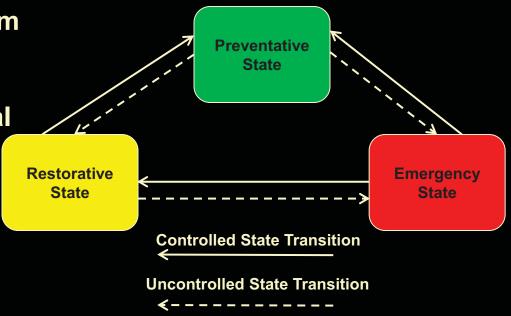
- Power System
 Network management
 - Power network security
 - Power quality
 - Detect soft faults
 - Report hard faults
 - Configure switchgear
- Power System Coordination
 - Communicate with Manager
 - Coordinate with identical power channel entities and/or vehicles



Power System Fault Management

Assess / Manage Power System State

- Preventative state -- Normal operation, continue indefinitely without interruption
- Emergency State Fault occurs – relieve system stress and prevent further deterioration
- Restorative State System is degraded but safe – restore power flow to all loads in a safe manner in minimum time



Additional Functions

- Contingency Analysis
- Develop corrective actions
- Component Health Monitor



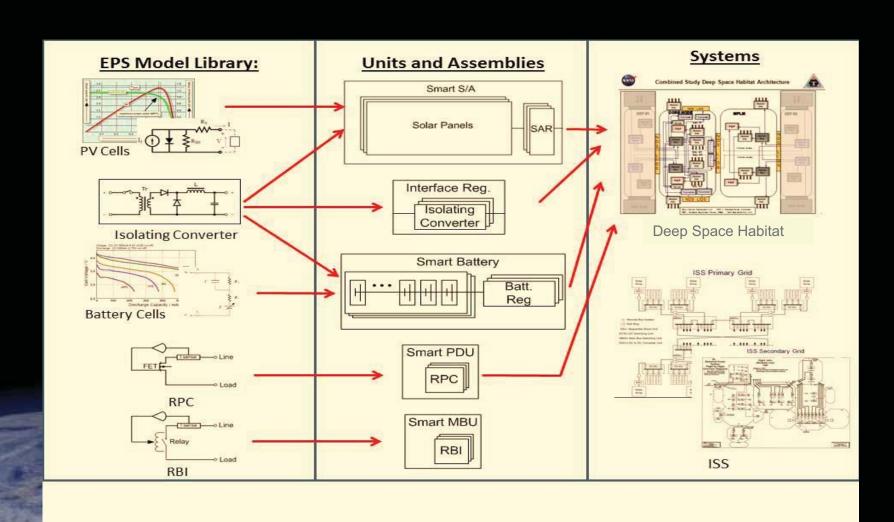


Intelligent Power Controller Verification Approach





Power System Simulation Development

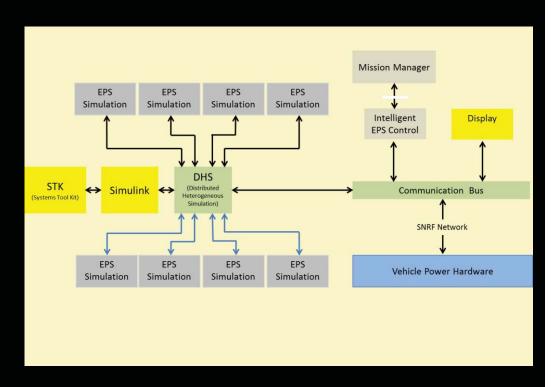




Intelligent Control Simulation Architecture

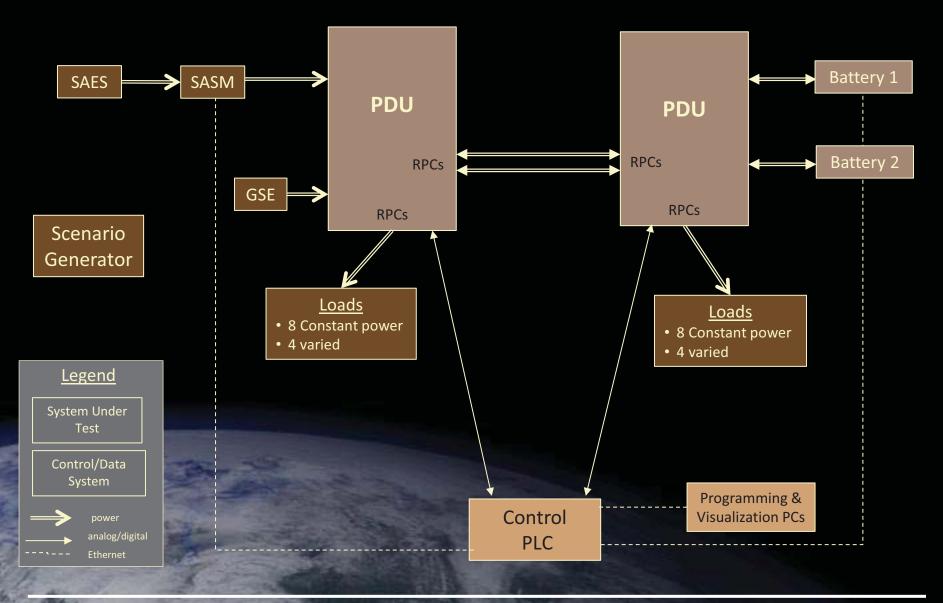
Distributed Heterogeneous Simulation Platform

- 6 High speed multi-core PC's with 8 processors each
- Total of 48 processors
- PC's interconnected through high speed Ethernet
- Middleware provides synchronized interconnection of any number of dynamical subsystem simulation processors
- DHS-enabled to support time synchronization and real-time execution





Hardware In the Loop Verification





www.nasa.gov

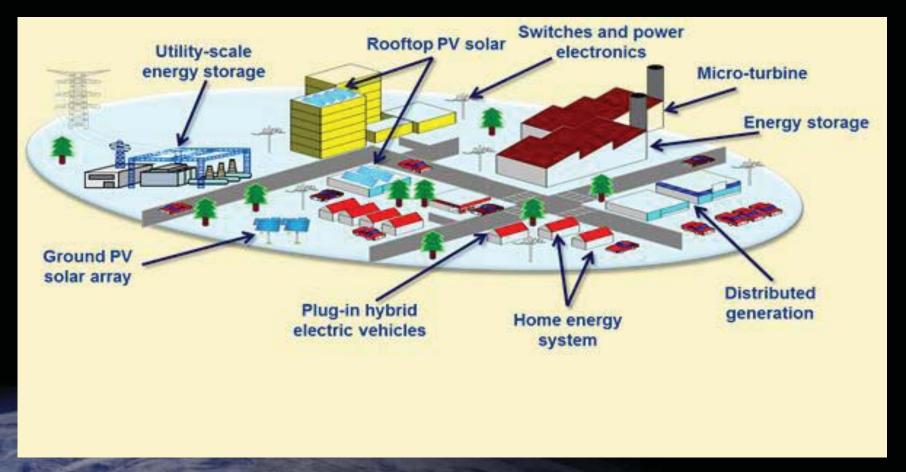


Application to Terrestrial Micro-Grids





Terrestrial Micro Power Grid



Islanded micro-grids have higher level control needs that are very similar to deep space vehicle power systems

Wrap-up

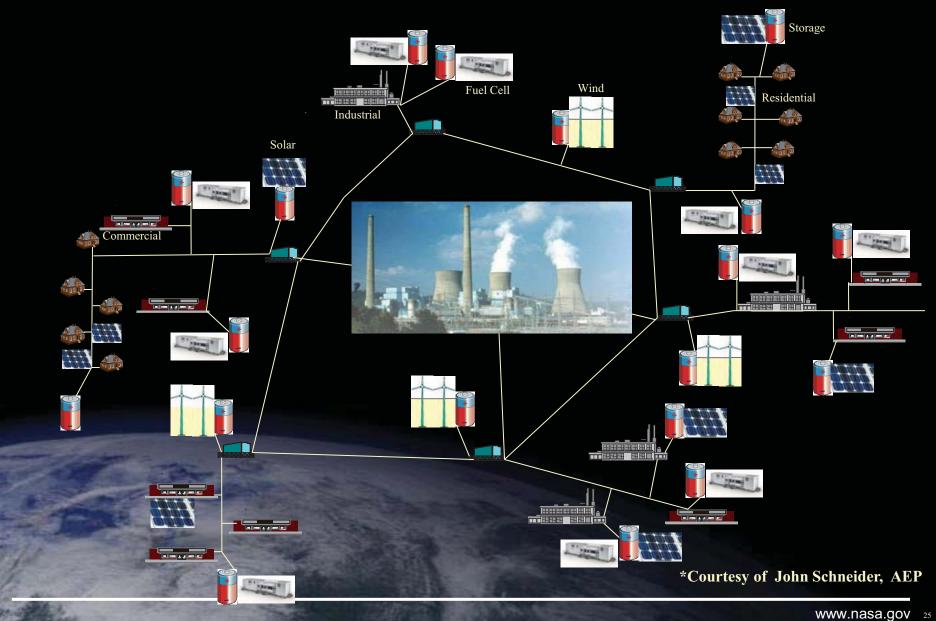


- We need Intelligent Power Systems for long term operation far from earth
- Utilization of real-time simulations, hardware in the loop and power system test beds can achieve this development goal
- Technology to operate proposed deep space exploration vehicles can be utilized to operate terrestrial micro grids





...the Grid of the Future?*





Terrestrial Micro Grids

Islanded micro-grids have very similar needs to space vehicle power systems

- Both need to function autonomously for extended periods of time
 - Both need to manage distributed energy resources
- Both need to manage loads over constrained capacity and time horizons
- Both need to guarantee that the network is safely managed
 - Both need to detect, isolate, reconfigure and

accommodate faults

