

# Overview of Unmanned Aerial System Traffic Management (UTM)

# Motivation

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- Many applications of Unmanned Aerial System (UAS) have been proposed
  - Humanitarian
  - Precision agricultural
  - Package delivery
  - Infrastructure monitoring
- Worldwide interest is intense
- UAS will need to operate in uncontrolled airspace
- No infrastructure is available to support these new operations
  - Today's Air Traffic Management (ATM) started after mid-air collision over Grand Canyon in 1956
- The US needs a system for managing UAS operations in civilian low-altitude airspace

# Sense of Urgency

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- Business applications are emerging rapidly
- Low-altitude operations could become dominant aviation activity
- Vehicle designs are changing continuously
- Airworthiness certificate relief and Certificate of authorization (COA) are taxing processes
- Visual line of sight is limiting
- Several efforts to integrate civilian UAS into the National Airspace System are underway
- An automation system, operational procedures, flight rules, and regulations are urgently needed to enable the industry

# Agenda

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- Objectives
- Development Approach
  - Builds
  - Services
  - Simulation Capabilities
  - Field Tests
- UTM Build 1 Field Test Description
- Summary

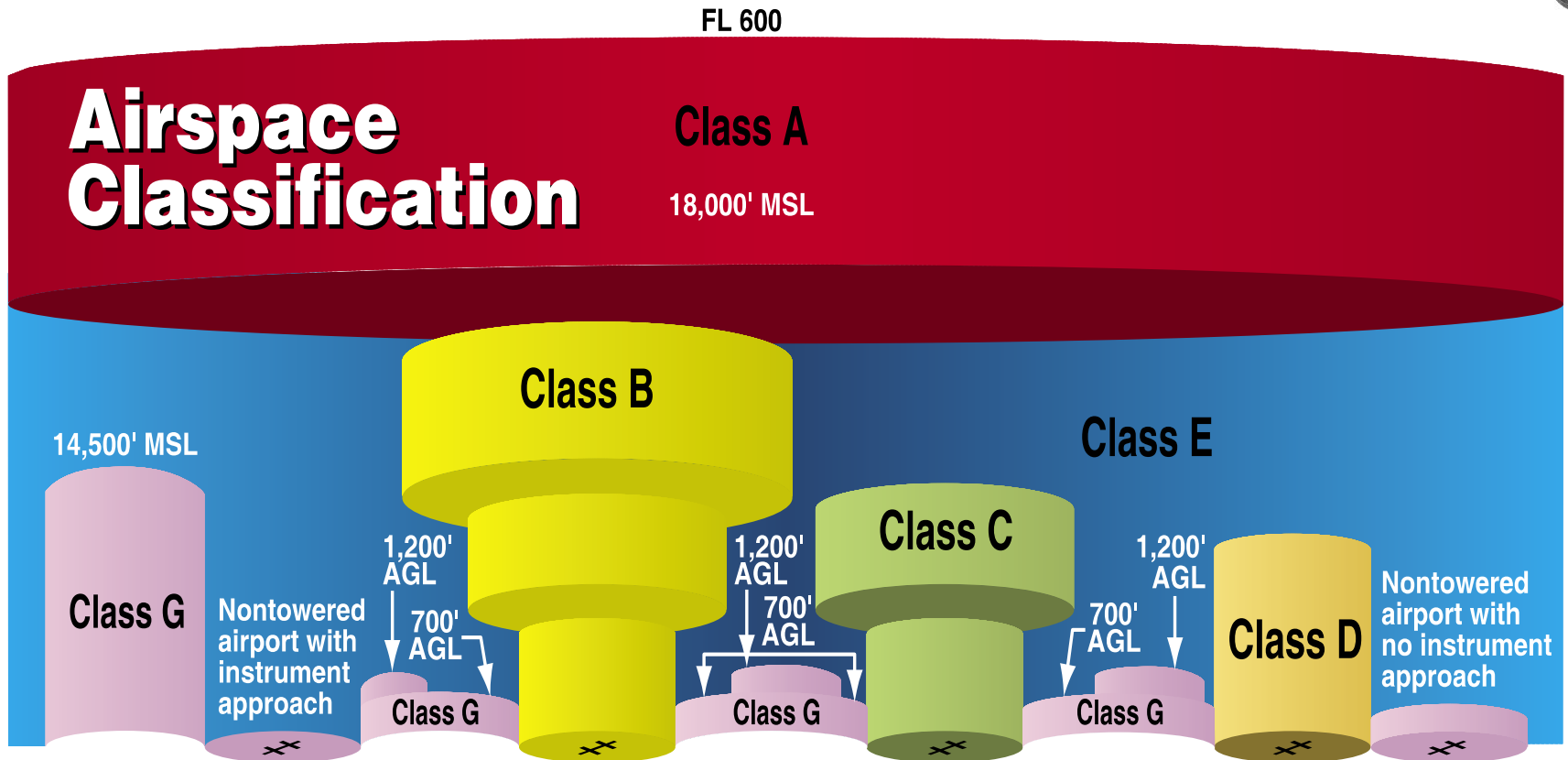
# Objectives

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- Develop proof-of-concept UTM system to safely enable low-altitude small UAS operations
  - Automation system
  - Operational procedures
  - Flight rules
- Demonstrate UTM system in field tests in conjunction with a broad set of partners

# US Airspace Classification

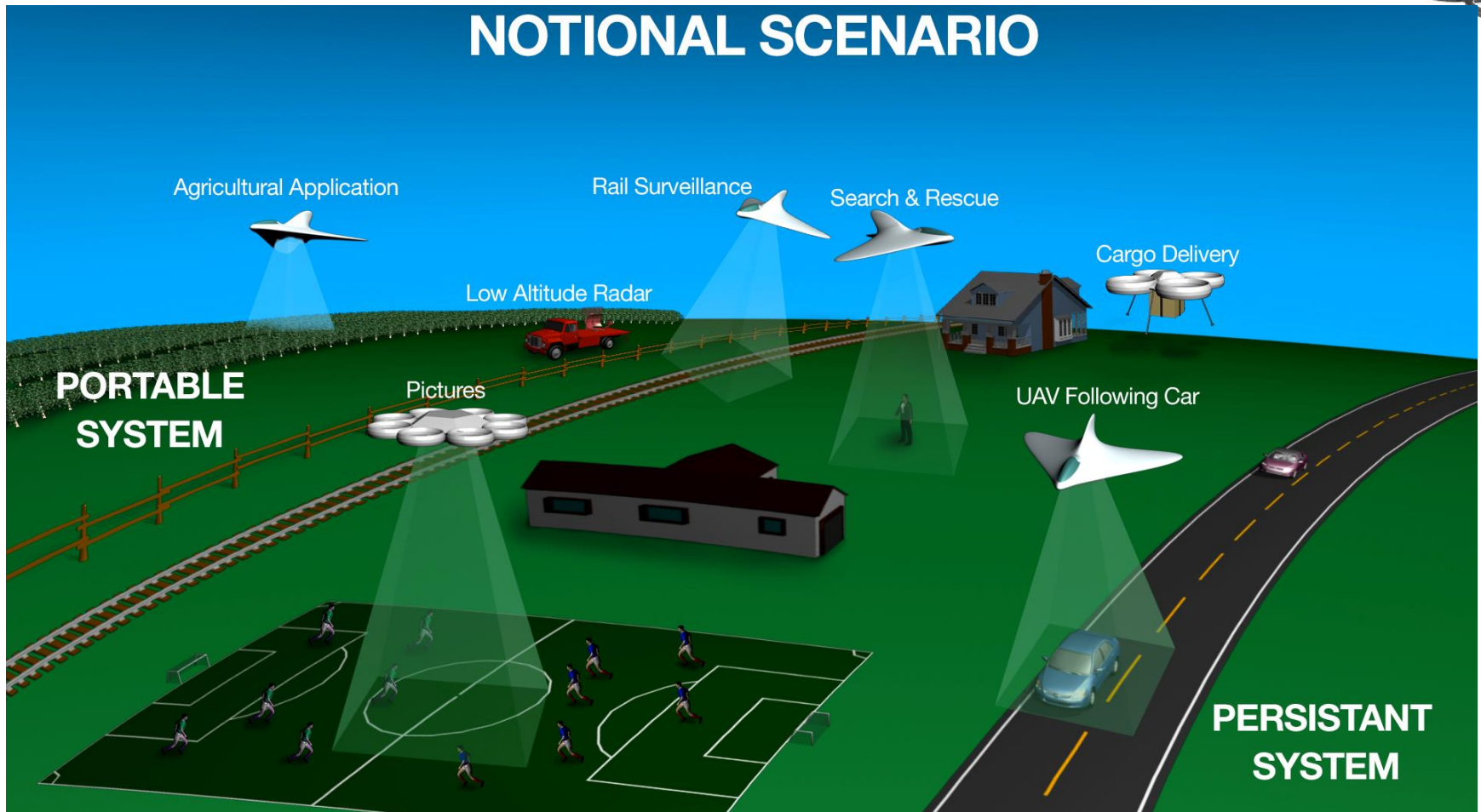


Source: Pilot's Handbook of Aeronautical Knowledge, FAA

# UTM Applications



## NOTIONAL SCENARIO



# Notional UTM Scope





# UTM Builds and Services

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- Based upon four risk-based criteria:
  - Density of people on the ground
  - Number of structures on the ground
  - Likelihood of manned operations in close proximity
  - Number of UAS operations in close proximity
- Each build enables certain types of missions and provides certain services
- Each build includes supports the missions and services of the previous builds
- Builds are intended to be developmental milestones as well as self-contained systems.

# High-Level UTM Builds

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- **Build 1:**
  - Within visual line-of-sight
  - Over unpopulated land or water
  - No manned aircraft
  - Geo-fences separate UAS
  - Contingencies handled manually by UAS pilot
- **Build 2:**
  - Beyond line-of-sight
  - Over sparsely populated land
  - Few manned aircraft
  - Procedures and rules-of-the road separate UAS
  - Contingencies alerted to UAS operator
- **Build 3:**
  - Beyond line-of-sight
  - Over modestly populated land
  - Some manned aircraft
  - In-flight separation of UAS
  - Some contingencies resolved
- **Build 4:**
  - Beyond line-of-sight
  - Urban environments
  - Manned aircraft commonplace
  - Autonomous separation of UAS
  - Large-scale system-wide contingencies resolved

# Notional UTM Airspace



# High-Level UTM Services

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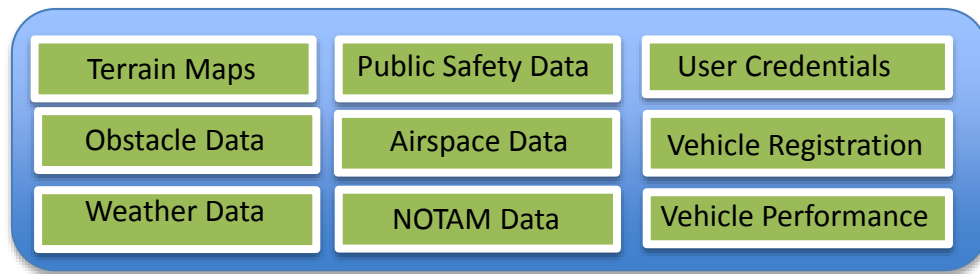


- Security Services:
  - System Health Monitoring
  - Vehicle Registration
  - User Authentication
  - Flight Monitoring
- Information Services:
  - Airspace Definition
  - Weather Information
  - Terrain and Obstructions
  - Traffic Operations
- Flight Services:
  - Flight Planning
  - Scheduling and Demand Management
  - Separation Assurance
  - Contingency Management

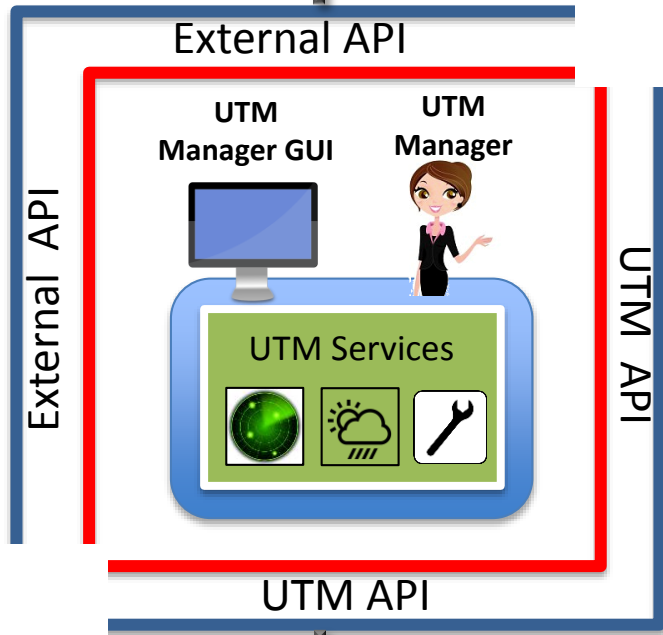
# UTM System Architecture

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Data Service Providers



External API

UTM API

**UTM API**



UAS



UAS PIC

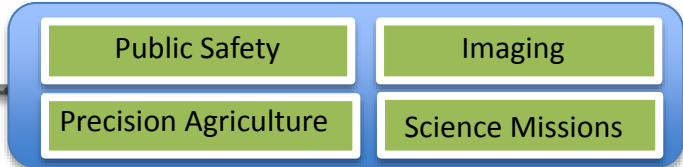


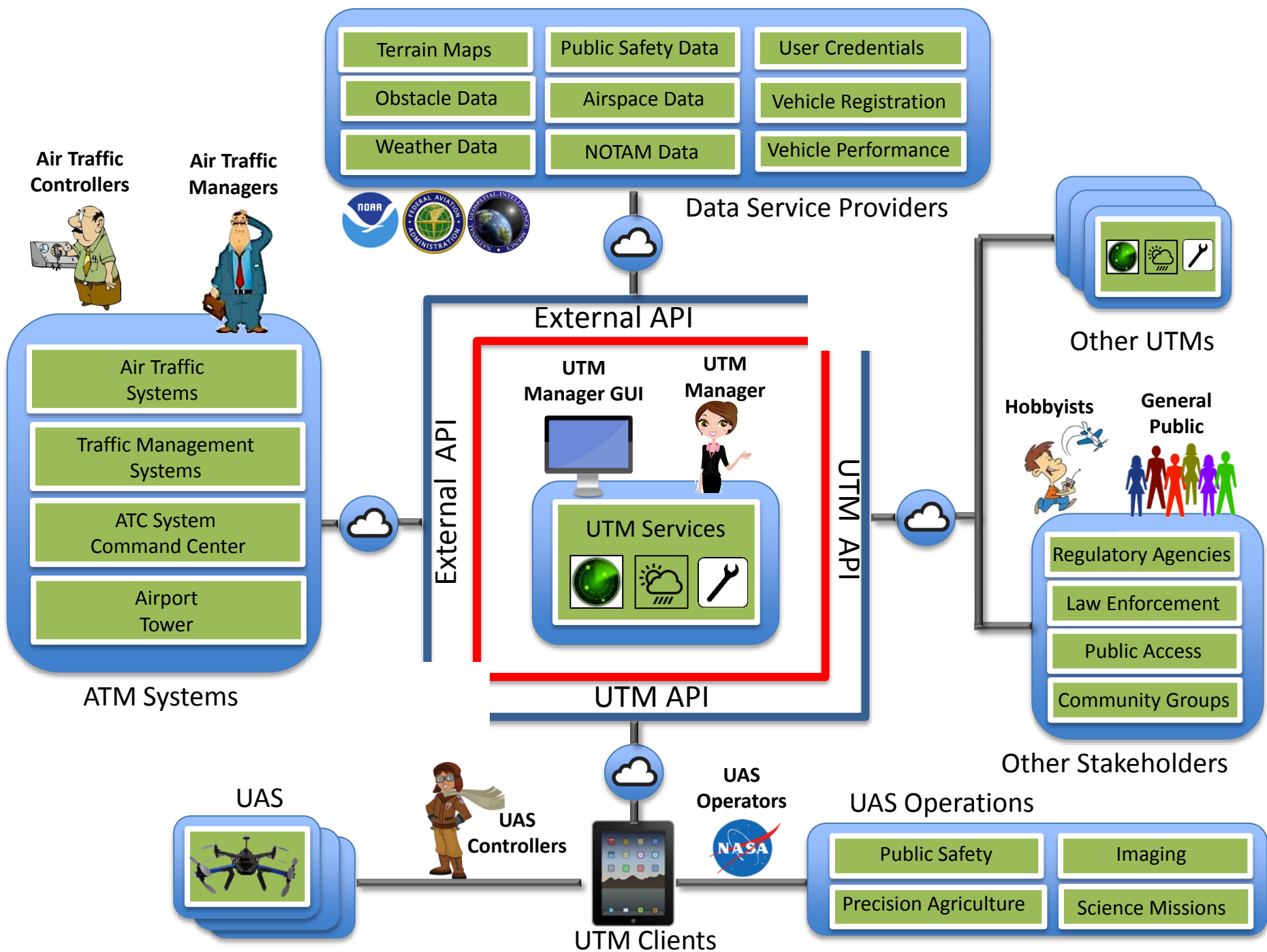
UTM Clients

UAS Operators



UAS Operations





# UTM Simulations

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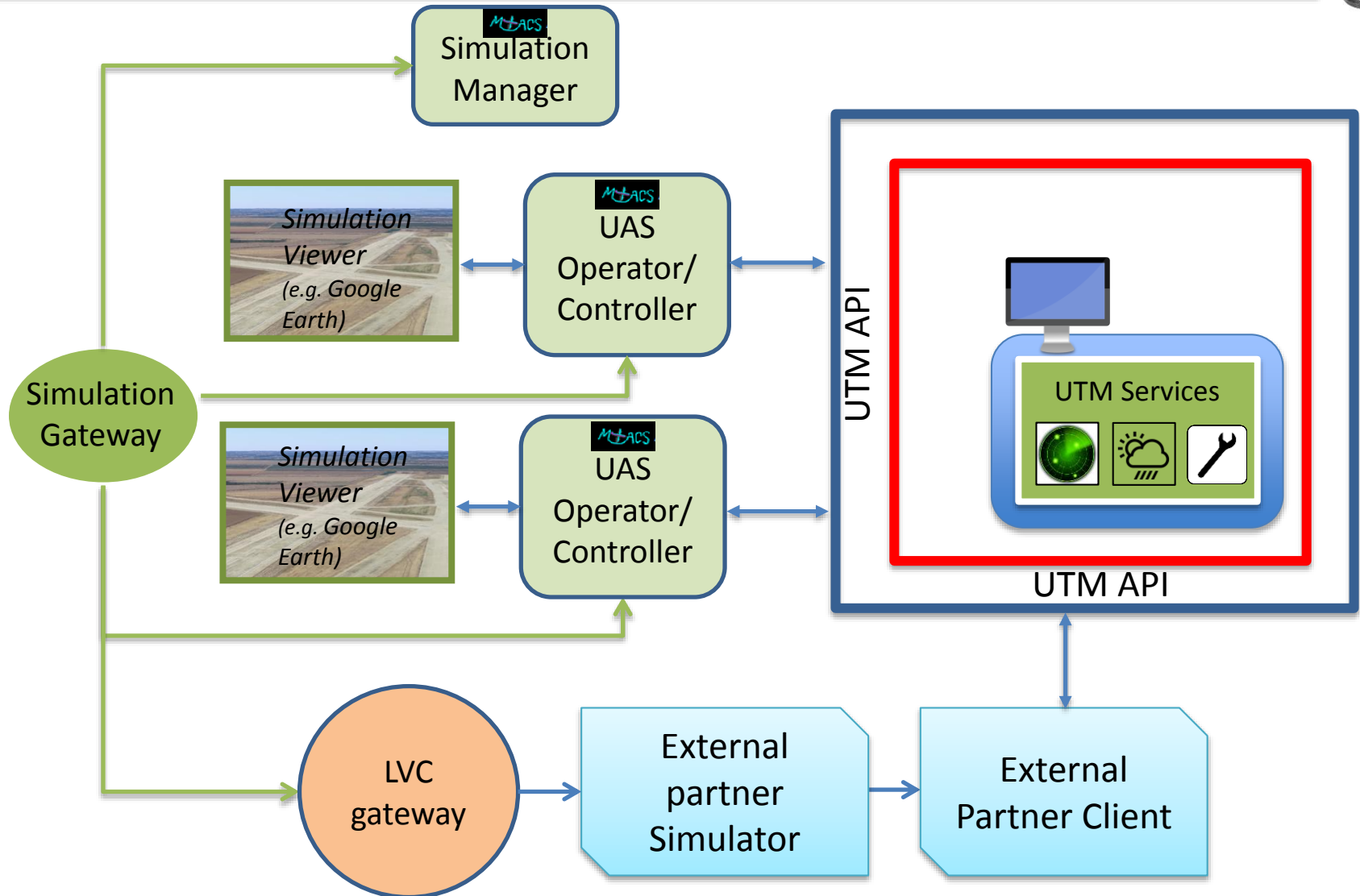


- Demonstrate and evaluate advanced UTM services and UAS operations in high-fidelity human-in-the-loop simulations
- Define human's roles, responsibilities and procedures for managing UTM operations
- Perform verification and validation testing of UTM system prior to field tests
- Simulate complex operations that cannot be done during the field tests (e.g., urban operations, 9/11 type scenarios)



# NASA Lab Test Bed

## UTM simulator with access for external partners



# UTM Field Tests

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- Demonstrate, and evaluate current UTM services and UAS operations in conjunction with UTM stakeholders
- Verify tools and procedures to manage UTM operations
- Accelerate deployment of UTM System to FAA UAS test sites
- Validate assumptions made by the UTM Concept of Operations (e.g., vehicle performance, operational conditions, integration with real flight hardware and NAS systems)
- Provide tangible products for technology transfer of UTM requirements and capabilities to the FAA and UTM stakeholders

# Build 1 Field Test Scenario

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- Physical Location: Low Altitude Class G Airspace
  - Outside the Mode-C Veil
  - At least 3 nmi away from airports, helipads, etc.
  - 1,200 feet AGL or lower
- Risk Criteria
  - Population Density: Only people involved in operation
  - Structural Density: Only structures related to the operation
  - Manned operations: No non-participating aircraft expected
  - UAS Operations: Segregated by geo-fences or time
- Test Constraints
  - Within visual line-of-sight of Pilot-in-Command
  - During daylight hours
  - With visibility greater than 1 statute mile and clear of clouds

# Build 1 Field Test Objectives

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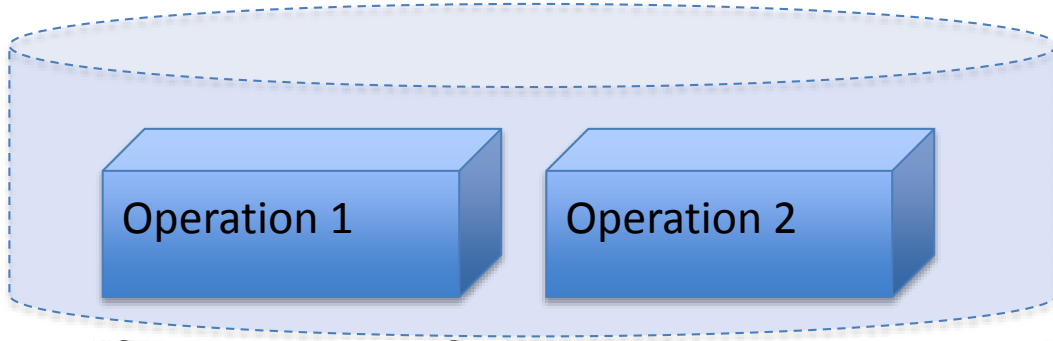


- Objective 1: Demonstrate UTM Build 1 capabilities and effectiveness under real world uncertainties
- Objective 2: Collect data to support Build 2 development

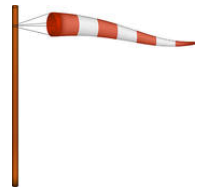
# Build 1 Field Test Approach



Demonstration Airspace



Surveillance  
Weather



NASA Flight  
Support Crew



Partner(s) Flight  
Support Crew



Visual Observers



Range Safety  
Officer



Mission  
Manager



NASA  
GCS/Display



Partner(s)  
GCS/Display



UTM System



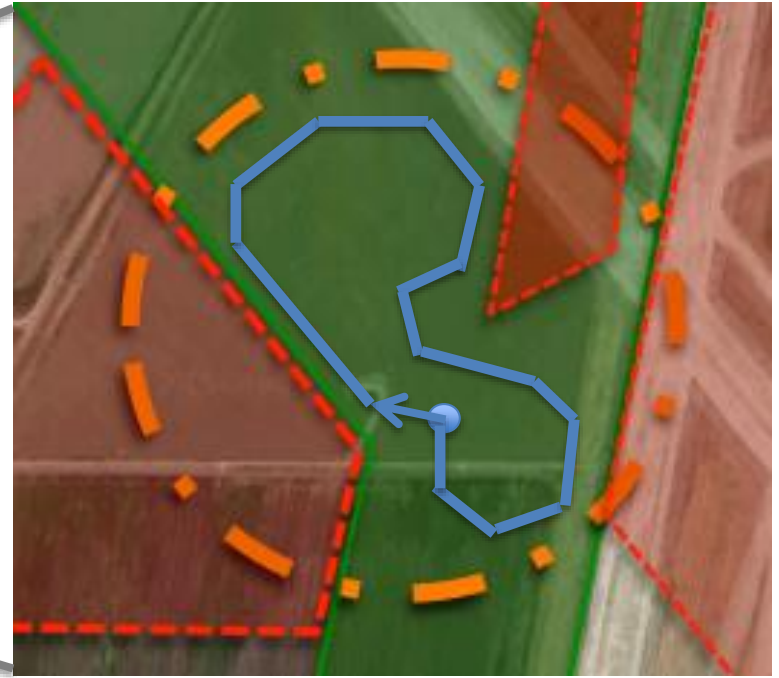
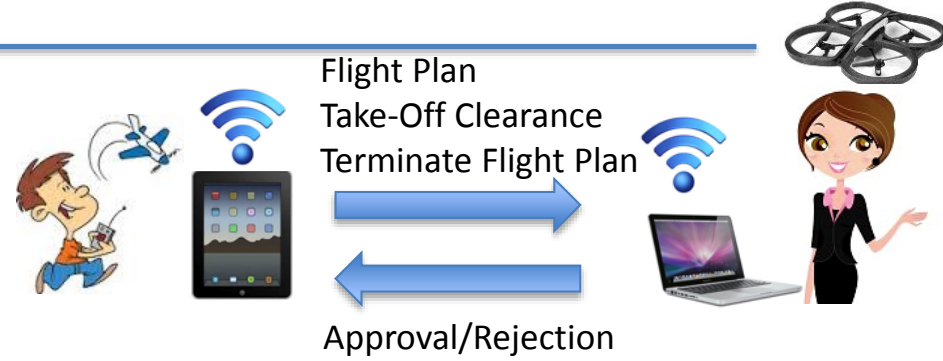
UTM Manager



Ad-hoc network



# Build 1 Field Test Example



# Summary

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- UTM is a unique and necessary effort to enable safe operations
- Collaboration is welcome: private sector, university, and government agencies
- Field testing and simulations will demonstrate UTM feasibility

# Backup Slides





# UTM Services: Security Services

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- **System Health Monitoring**
  - Monitors the status of the internal subsystem and external system components required to provide each UTM service
- **Vehicle Registration**
  - Ensures that only registered vehicles are approved for operations within UTM airspace and receive the appropriate UTM services
- **User Authentication**
  - Ensures that only credentialed users can access the system and are provided the appropriate UTM services
- **Flight Monitoring**
  - Monitors both UAS and non-UAS operations within the UTM airspace in terms of their safety and security risk to each other

# UTM Services: Flight Services

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- **Flight Planning**
  - Assesses proposed UAS operations against airspace availability and operational constraints
- **Scheduling and Demand Management**
  - Schedules UAS operations to reduce congestion, conflicts, and improve overall safety as traffic demand increases
- **Separation Assurance**
  - Provides temporal, procedural and in-flight separation services from other traffic, weather, terrain, and vertical obstructions
- **Contingency Management**
  - Resolves off-nominal conditions that occur during an operation such as flight non-conformance and lost communication

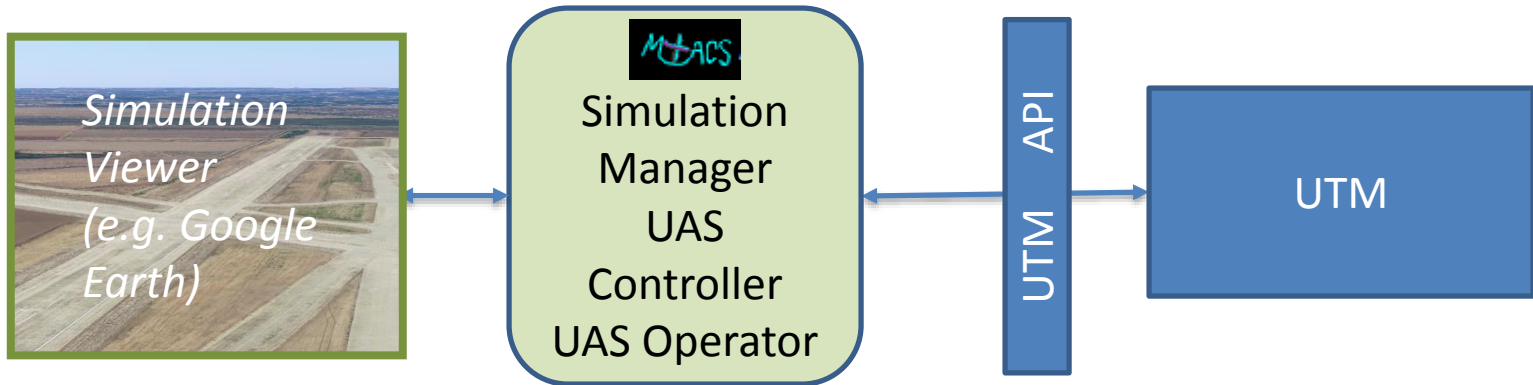
# UTM Services: Information Services

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- **Airspace Definition**
  - Provides users with the physical extents of its UTM airspace as well as regions within that airspace where operations are not permitted – either permanently or temporarily
- **Weather Information**
  - Provides users with information about the current and predicted weather conditions in the UTM airspace
- **Terrain and Vertical Obstructions**
  - Provides users with information about the terrain, man-made structures, and vertical obstacles in the UTM airspace
- **Air Traffic Operations**
  - Provides users with information about the planned and current UAS operations in the UTM airspace

# Standalone Testbed: UTM-PS Personal Simulator for UTM



## Functionality

- Create and control UAS scenarios in MACS
- Visualize in Simulation Viewer
- Communicate to UTM via UTM API
- MACS Messaging Window to display UTM comm.

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MACS Messages
20:01 – IN: UAS1 ACCEPTED
20:12- OUT: UAS1 ALL CLEAR

OUT>> UAS2 CANCELLED
```

## Automated messages:

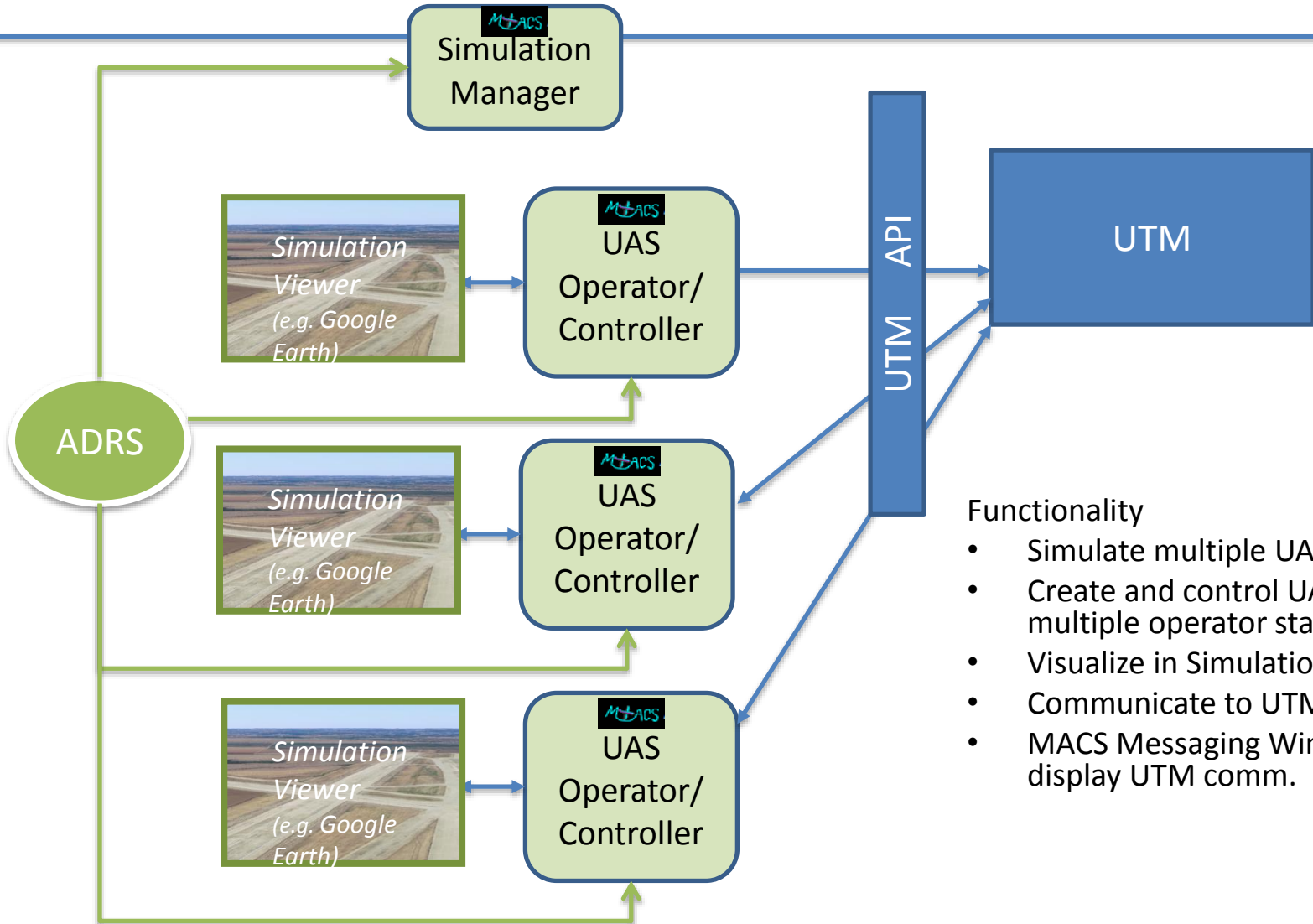
- MACS flight plan->Operational plan
- ALL CLEAR (TBD sec) before activating aircraft
- MACS flights state -> UTM position updates
- CLOSED message ->UTM (landed)

## Manual messages

- UTM messaging window in MACS for viewing UTM messages and sending responses from MACS

# NASA Lab test bed: UTM-LS

## Lab Simulator for UTM

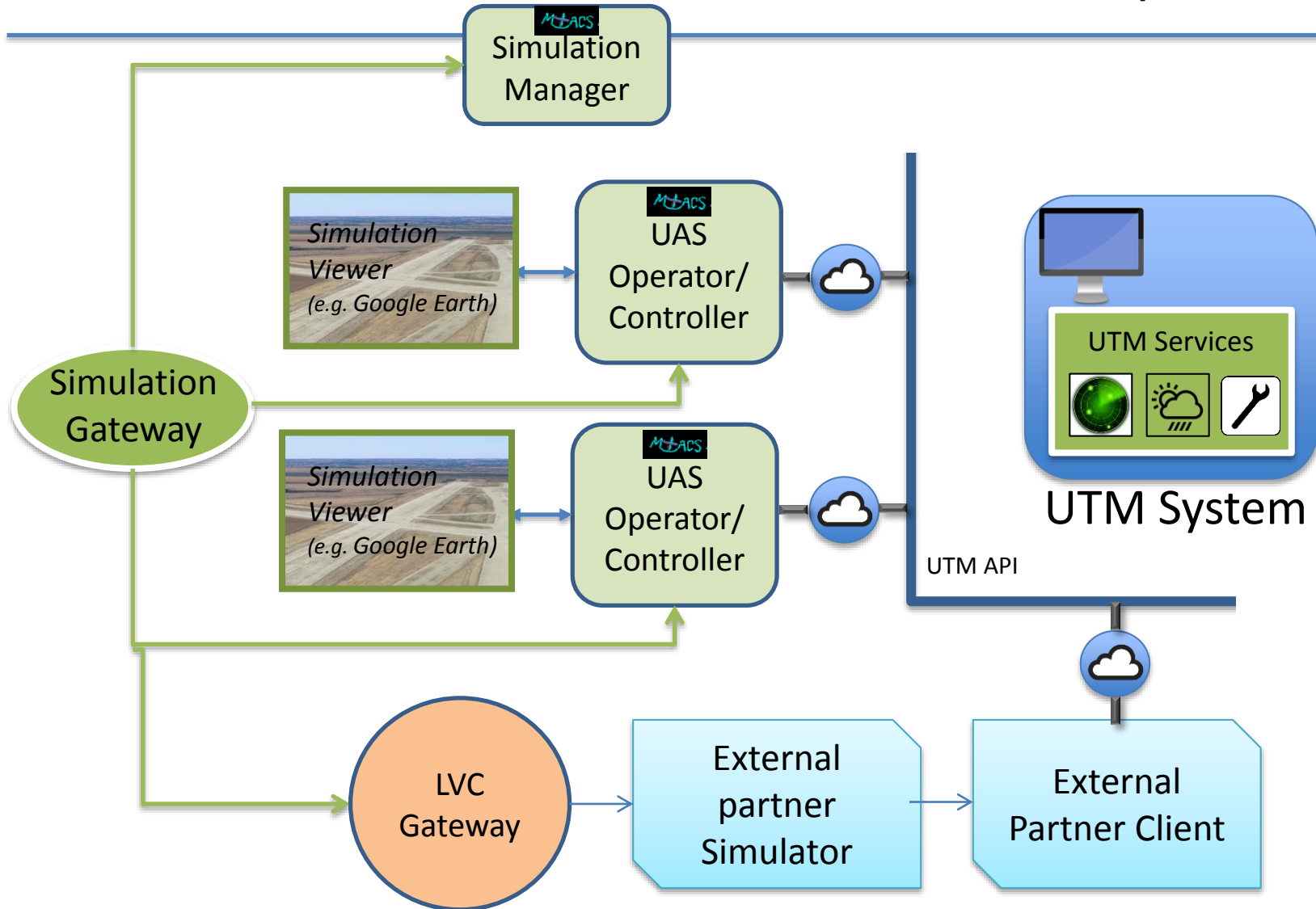


### Functionality

- Simulate multiple UAS clients
- Create and control UAS from multiple operator station in MACS
- Visualize in Simulation Viewer
- Communicate to UTM via UTM API
- MACS Messaging Window to display UTM comm.

# NASA Lab Test Bed

## UTM simulator with access for external partners



# Build 1 Location and Layout



- Test Location: Crows Landing Airfield
  - 35 miles east of Moffett Field, CA
  - NASA Ames Research Center has a Use Agreement with Stanislaus Co. which owns most of the property.
  - Vehicles would be operating under a NASA MOA\*
  - There are no usable facilities or services at Crows Landing. Users must be 100% self-sufficient and bring all their own equipment, power, bathrooms, shade, water, and food.
  - There are services several miles away in the towns of Crows Landing or Patterson.
- Test Duration: 1 Week
  - Dates: TBD (August 17-20<sup>th</sup> 2015)



# Build 1 Flight Test Scope

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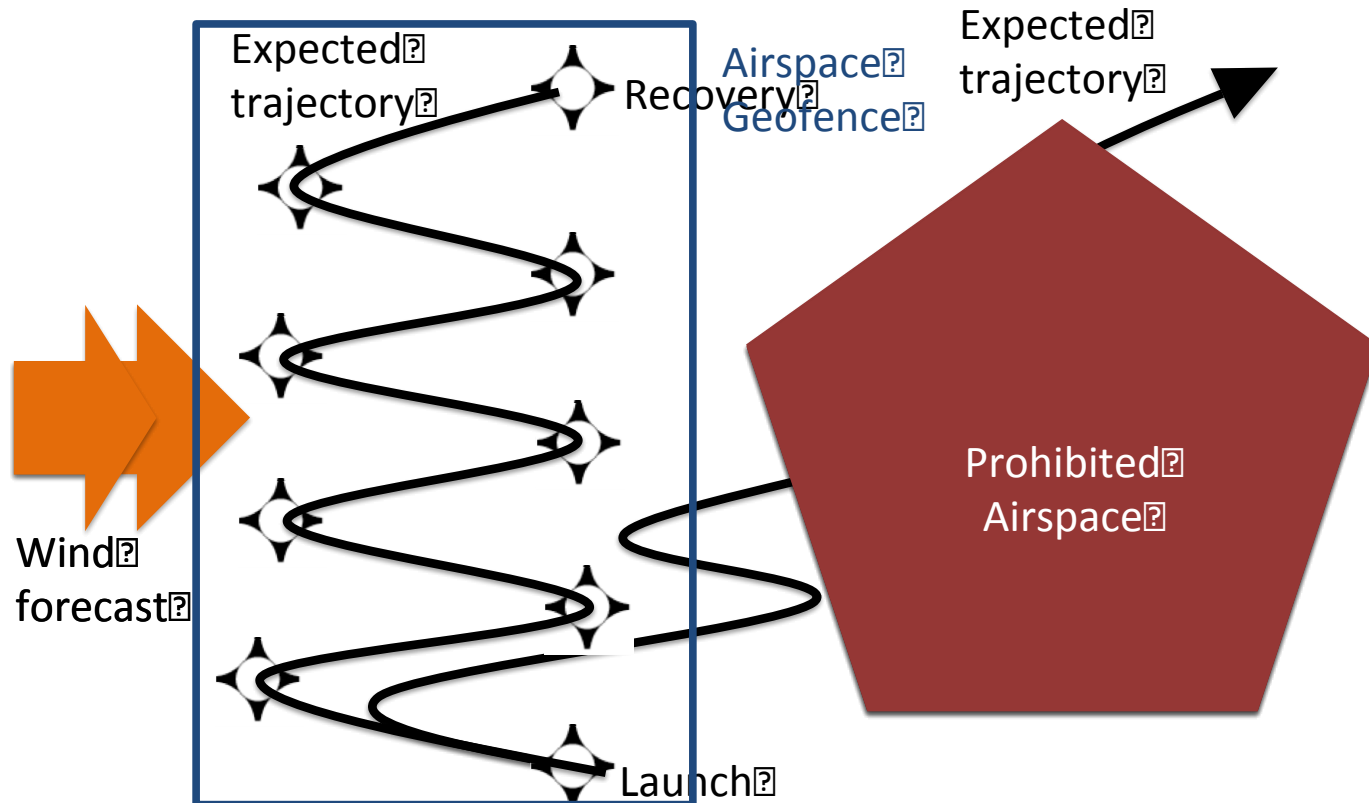
- Block A: Singleton Operations
  - Testing UTM Services in Nominal Conditions
  - Testing Operational Procedures in Nominal Conditions
  - Testing Vehicle Conformance
  - Data Collection: Vehicle and Surveillance Performance
  
- Block B: Sequential Operations
  - Testing UTM Services in Nominal and Off-Nominal Conditions
  - Testing Operational Procedures in Nominal and Off-Nominal Conditions
  - Testing Vehicle Conformance
  - Data Collection: Vehicle and Surveillance Performance
  
- Block C: Coincidental Operations
  - Testing UTM Services in Nominal and Off-Nominal Conditions
  - Testing Operational Procedures in Nominal and Off-Nominal Conditions
  - Testing Vehicle Conformance
  - Data Collection: Vehicle and Surveillance Performance



# UTM Constraint Checking



Operation plan ~~approved~~





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- Trajectory conformance depends on:
    - Aerodynamic characteristics
    - Vehicle performance (e.g. thrust)
    - Automatic flight control
  - Three ongoing efforts:
    - Vehicle modeling with available data
    - Model validation with field tests
    - Assessing feasibility of wind tunnel tests