



The Boeing SUGAR Truss-Braced Wing Aircraft: Wind-Tunnel Data and Aeroelastic Analyses

Dr. Robert Bartels, Senior Research Engineer, Aeroelasticity Branch, LaRC

Co-investigators:

Mr. Rob Scott, Senior Research Engineer, Aeroelasticity Branch, LaRC

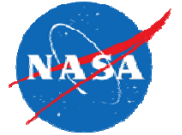
Mr. Timothy J. Allen, Boeing Research and Technology, Huntington Beach

Mr. Bradley W. Sexton, Boeing Research and Technology, St Louis



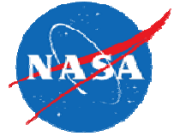
**NASA Ames Applied Modeling and Simulation Seminar
April 16, 2015**

Outline



- **Context and objectives**
- **Wind tunnel testing and validation data**
- **Analyses**
 - **Structural Models**
 - **Aerodynamic Modeling**
 - **Mode Shape Transfer Between Dissimilar CSD/CFD Models**
 - **Results**
 - **Flutter Simulations with Linear Aerodynamics**
 - **Sensitivity to structural model and angle of attack**
- **Conclusions**

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TBW Context in Fixed Wing Project



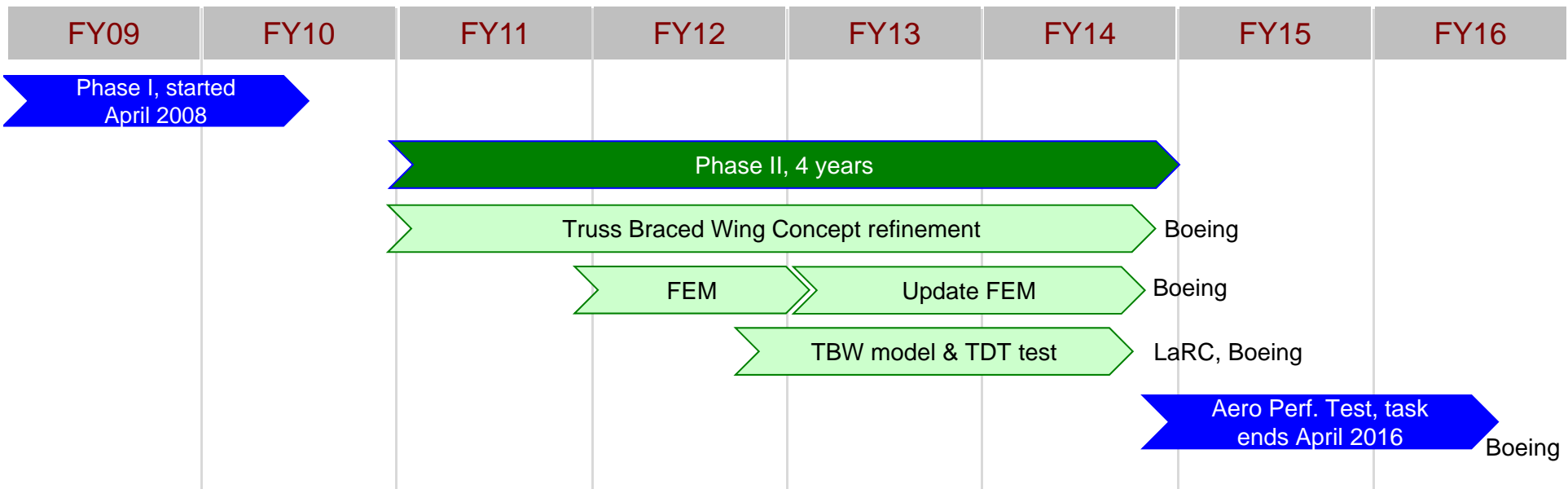
Goals Metrics (N+3)	Noise Stage 4 – 52 dB cum	Emissions (LTO) CAEP6 – 80%	Emissions (cruise) 2005 best – 80%	Energy Consumption 2005 best – 60%
Goal-Driven Advanced Concepts (N+3)				

Research Theme 2: Higher Aspect Ratio Optimal Wing

Future wings will be of higher aspect ratio, lighter, more flexible, and have varying degrees of laminar flow to reduce drag and improve performance

Technical Challenge 2.1 Higher Aspect Ratio Wing

Enable a 1.5-2X increase in the wing aspect ratio with safe structures and flight control (TRL 3)



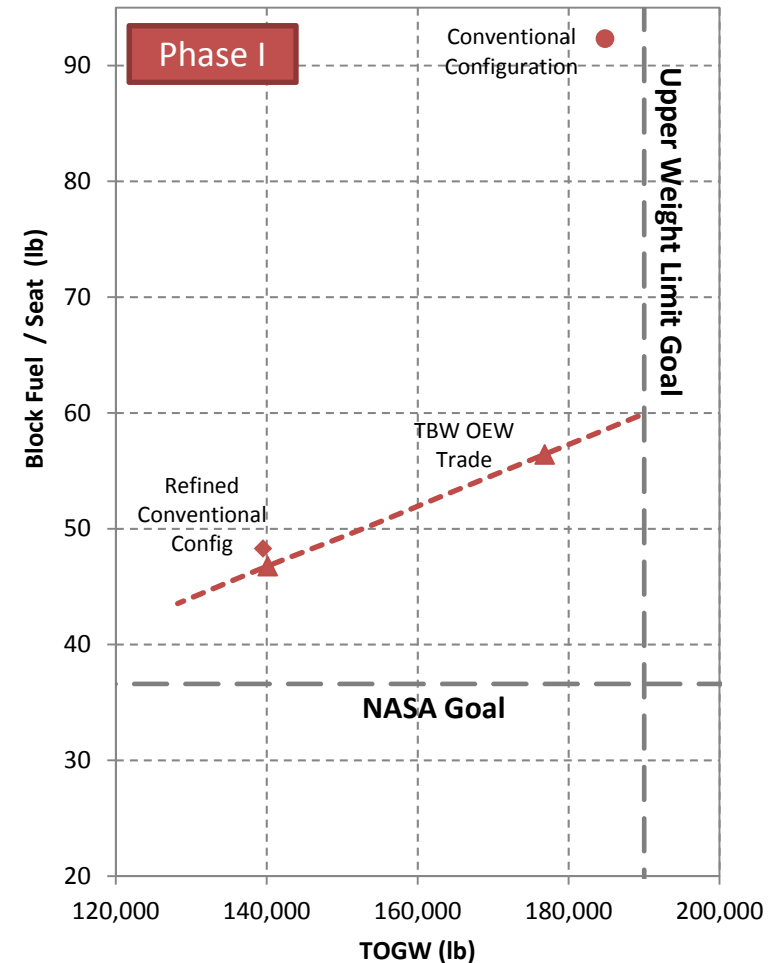
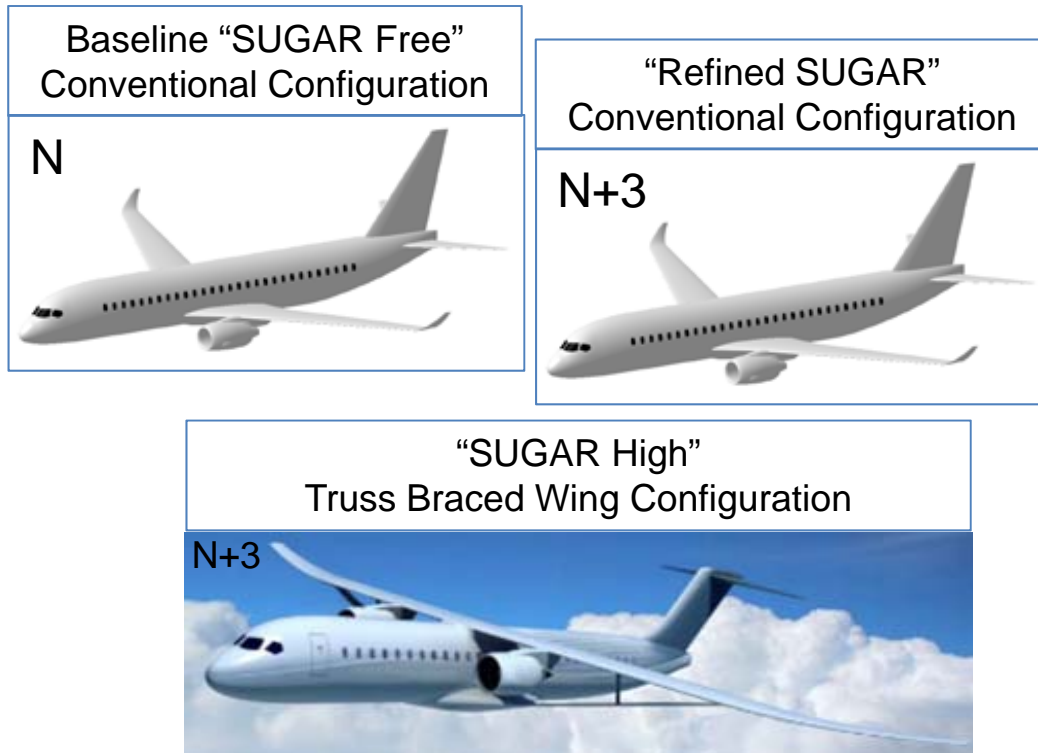
BR&T, BCA, GE, GT, VT, NextGen, MicroCraft

TBW Phase I Findings, Phase II Objectives



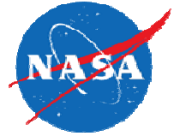
Phase I – Design Study of TBW Configuration

- Large uncertainty in wing weight estimates prevent concluding whether TBW is viable/beneficial concept



Phase II - Includes High Fidelity FEM to Refine Weight Estimate and Experimental Validation via ASE Wind-Tunnel Test in the TDT

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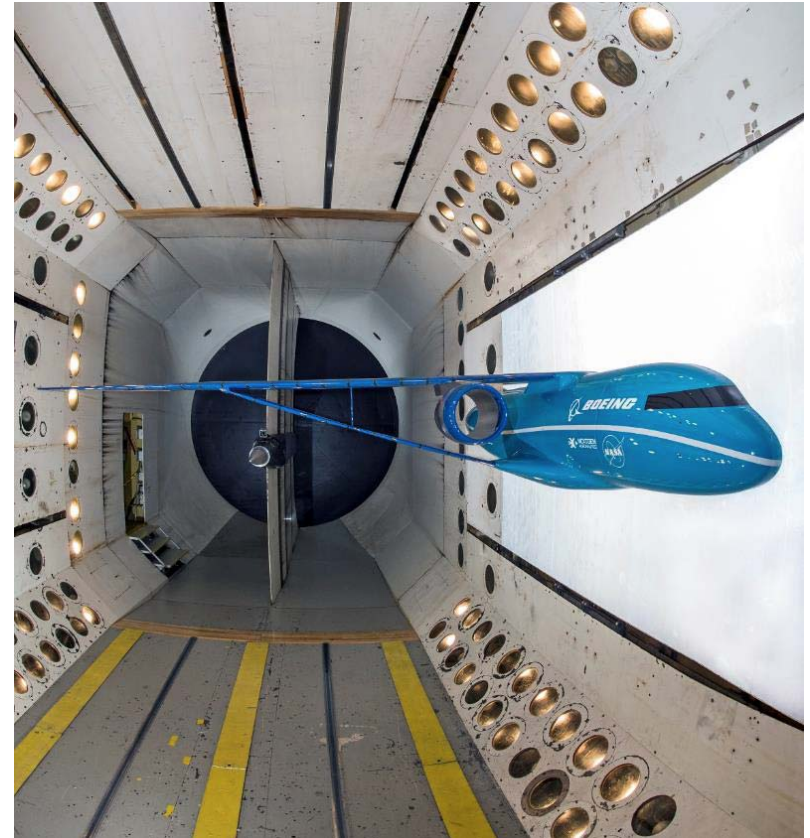


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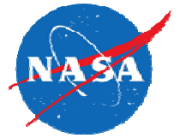
Wind-Tunnel Test Objectives



- Determine Experimental Flutter Boundaries
- Investigate Active Flight Controls
 - System ID
 - Flutter Suppression
 - Assess Effects of FS on Gust Response

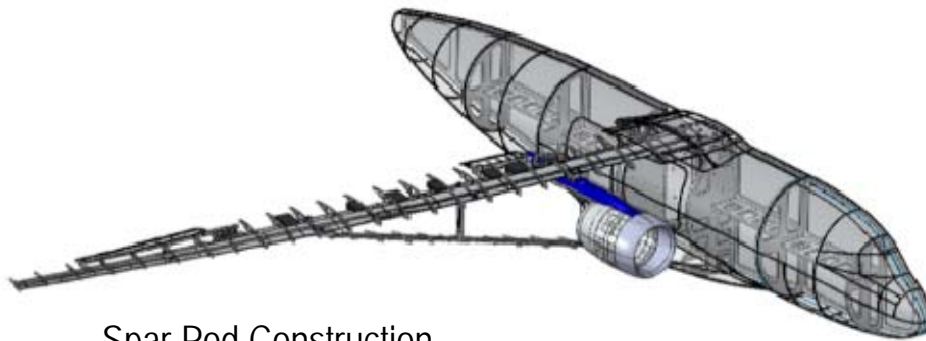


TBW Aeroelastic Wind-Tunnel Model

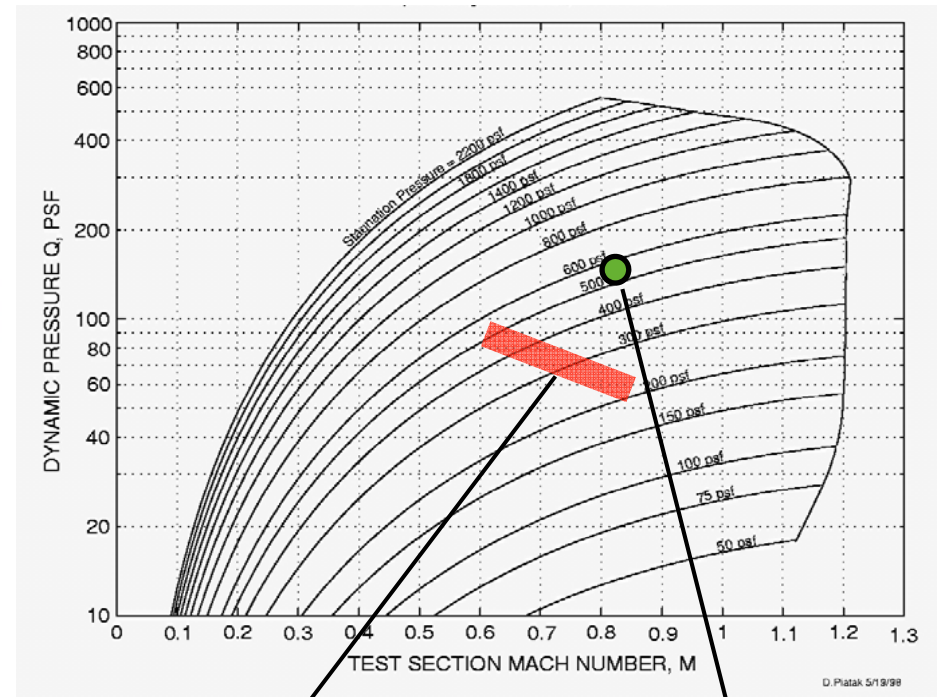


Full-Scale Design Point:

Mach = 0.82
 Altitude = 15,915 ft
 Span = 170 ft
 Weight = 143,164 lb



Spar Pod Construction
 Wing, Strut, Pylon Scaled
 High Bandwidth Control Surfaces:
 2 Trailing Edge
 Designed for Side Wall Mount
 Fuselage 13.4 ft (reduced from 18.7 ft)
 Span = 12.75 ft (to centerline)
 Standoff = 2.25 in
 Weight = 500 lb
 Model Scale Factors:
 Length = 0.15
 Frequency = 3.470



Predicted Flutter Boundary

Model Design Point

Gas = R134a
 Scaled Weight = 109.63 lb
 Mach = 0.82
 Q=162 psf

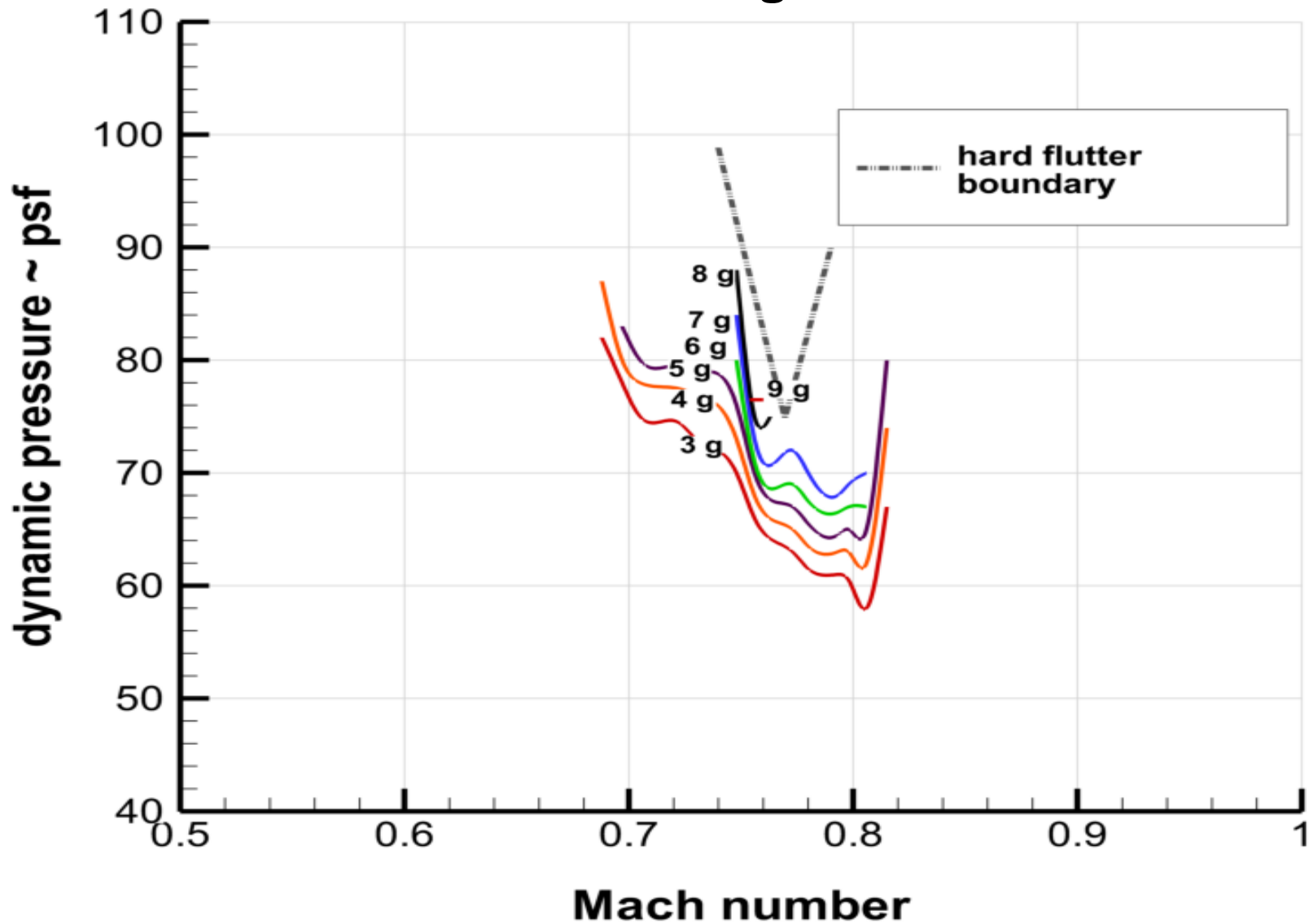


NEXTGEN AERONAUTICS

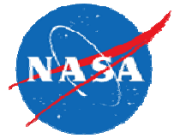
TBW Wind-Tunnel Model Wing Tip Accelerations



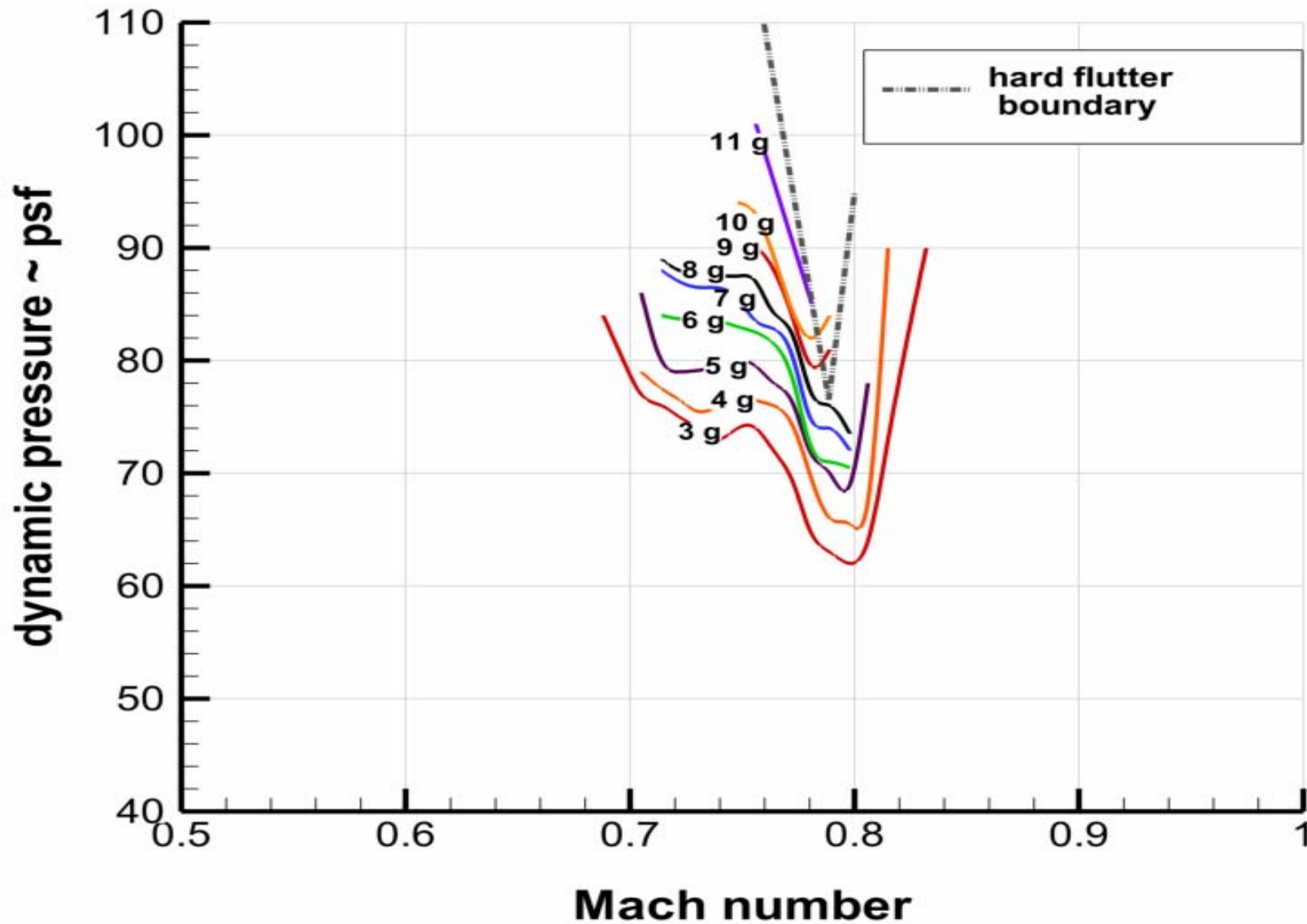
AOA -1 degree



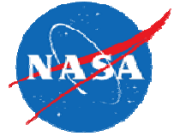
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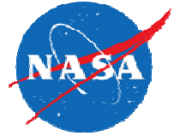


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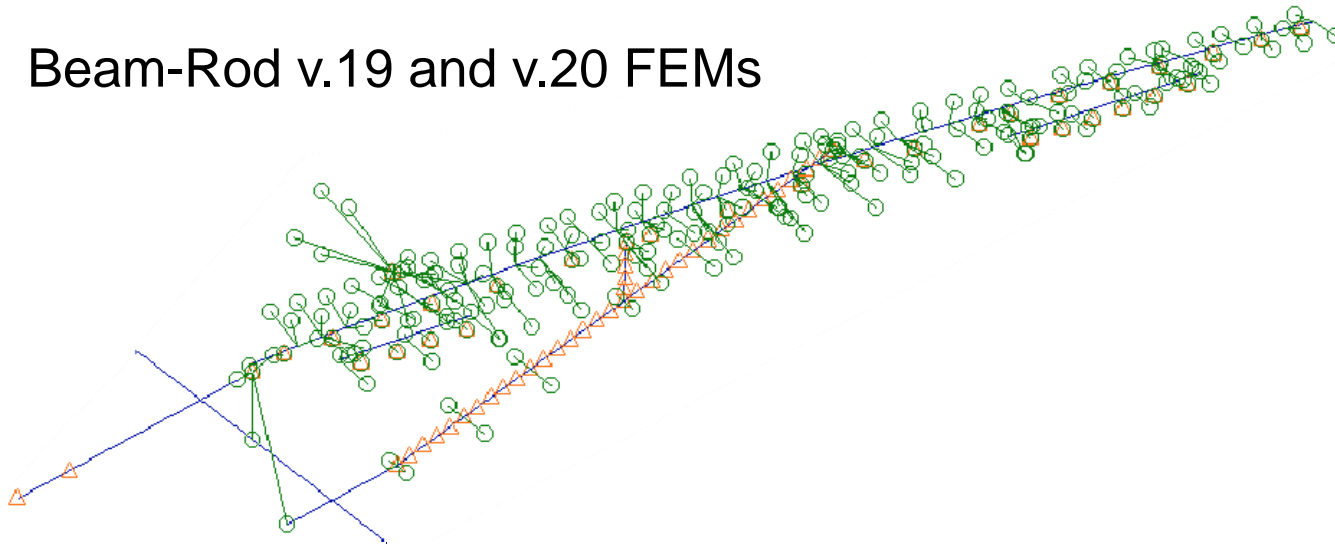


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Structural Models

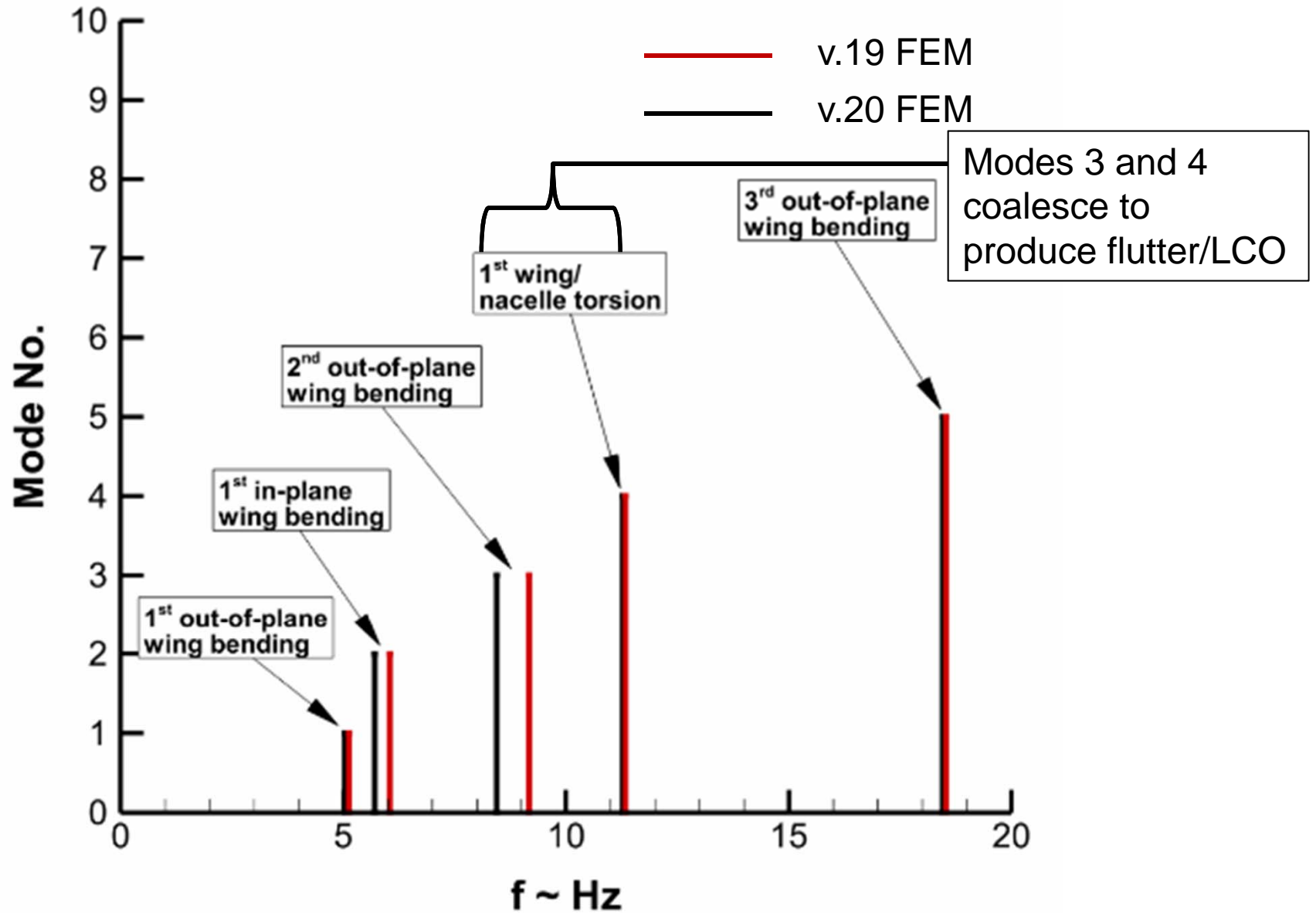
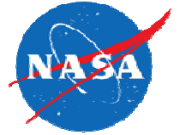


Beam-Rod v.19 and v.20 FEMs

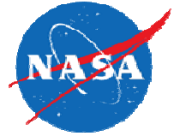


- V.19 FEM was updated with *before-test* ground vibration test (GVT) data.
- V.20 FEM was updated with *after-test* GVT data.
 1. Correlation of mode 3 was improved by decreasing bending stiffness on the strut attachment beam and on certain wing elements.
 2. Correlation of mode 4 was improved by adjusting torsional stiffness on inner wing elements.

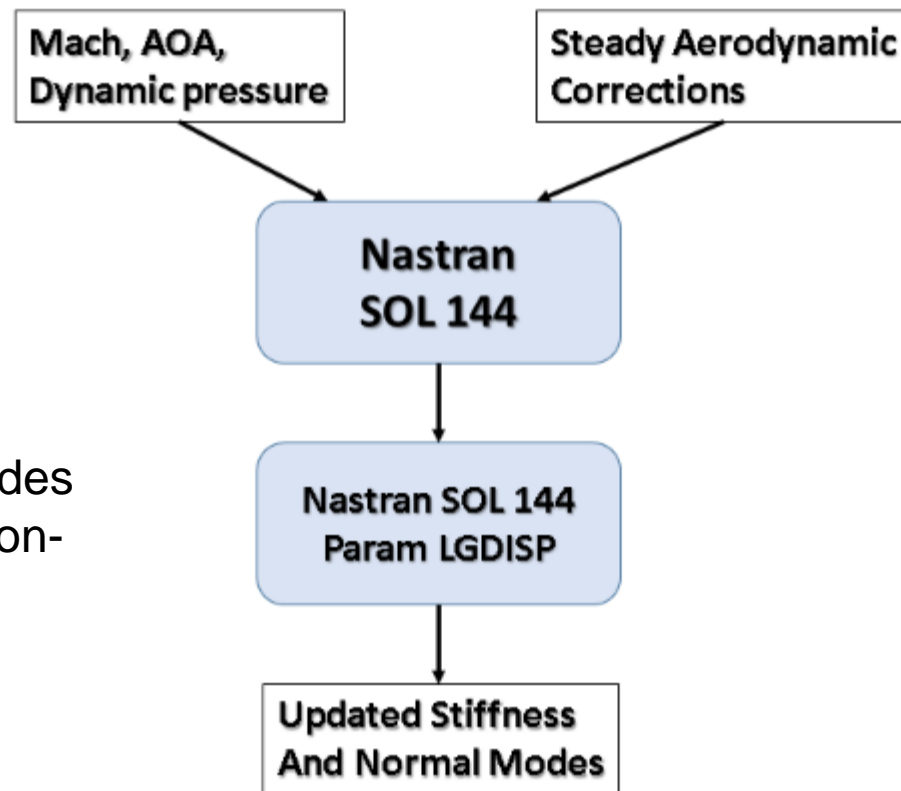
Structural Models



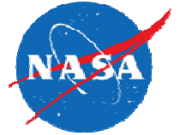
Structural Models



- Cases at zero degrees AoA use unloaded structural modes.
- Cases at +1 and -1 degree AoA use structural modes derived from a nonlinear loaded static solution. i.e., modes derived from a geometrically non-linear structure.

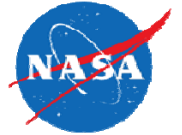


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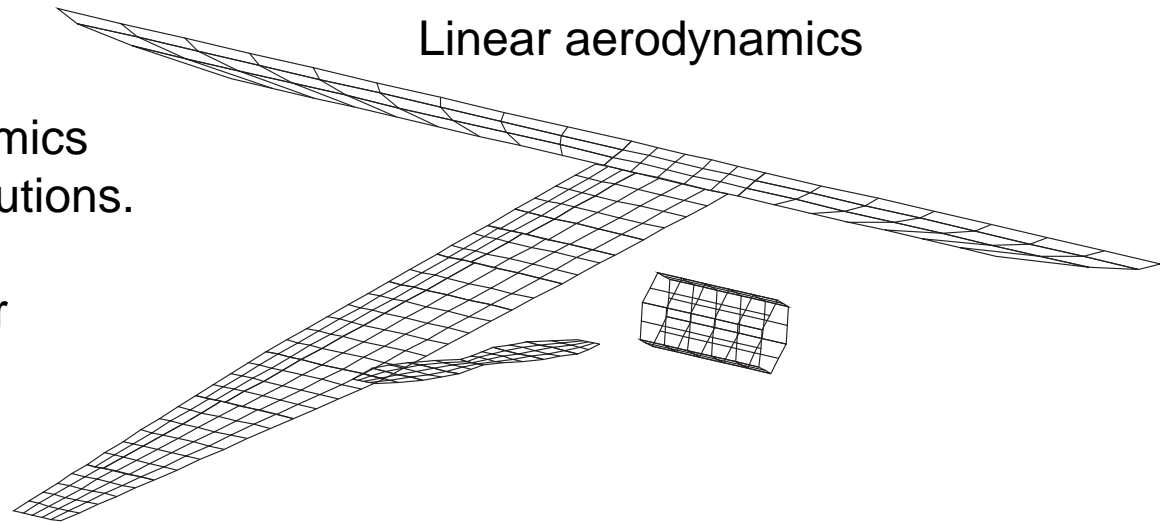


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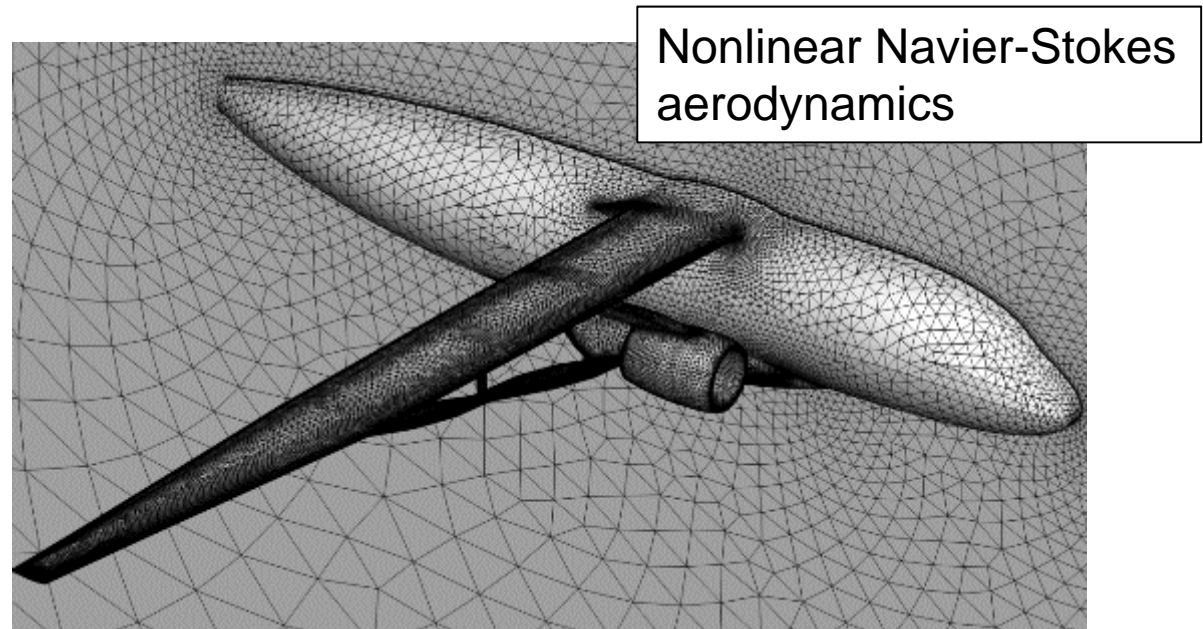
Aerodynamic Modeling



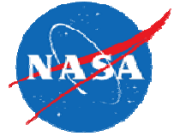
- Vortex-lattice aerodynamics for static aeroelastic solutions.
- Doublet-lattice for flutter solutions.



- The Navier-Stokes grid has 4.5 million nodes.
- The wind-tunnel wall is treated as a symmetry plane.

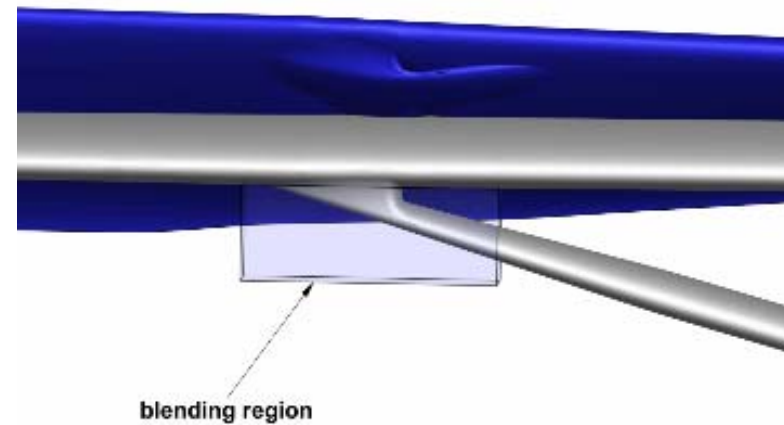
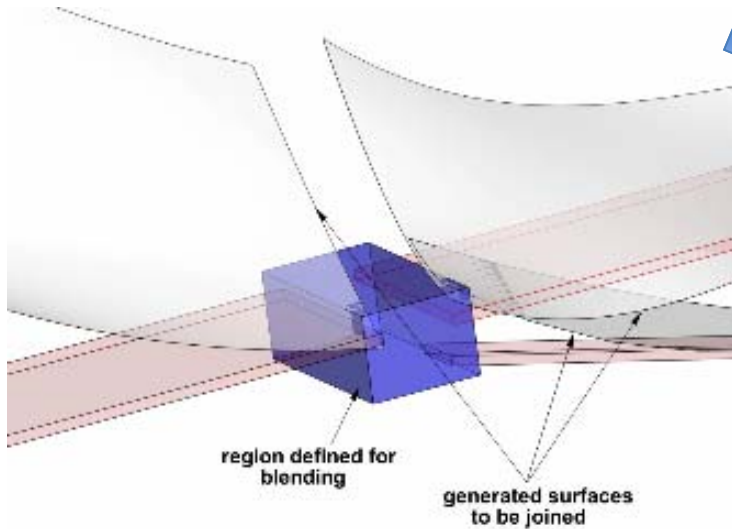
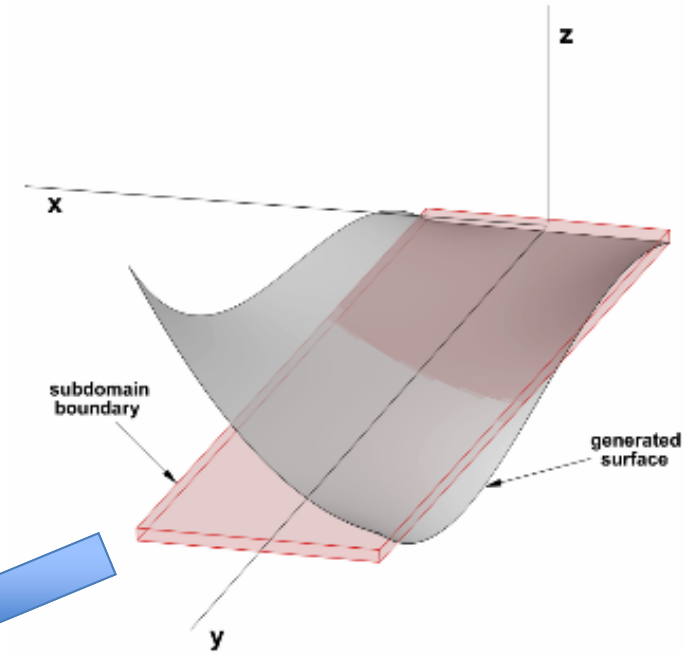
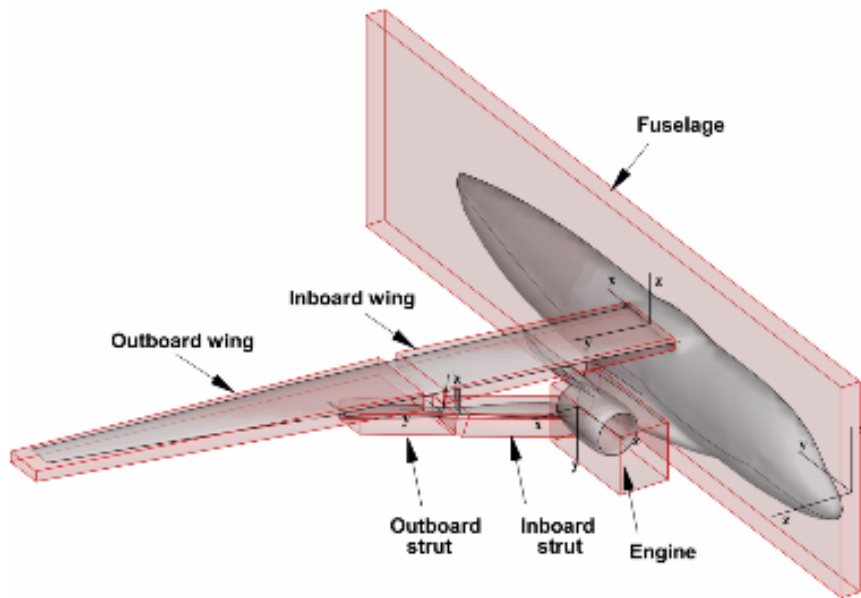
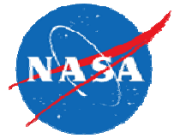


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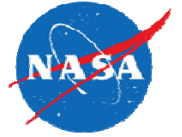
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Mode Shape Transfer Between Dissimilar CSD/CFD Models



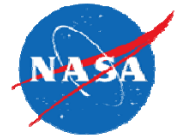
Final (blue) and initial (gray) surfaces

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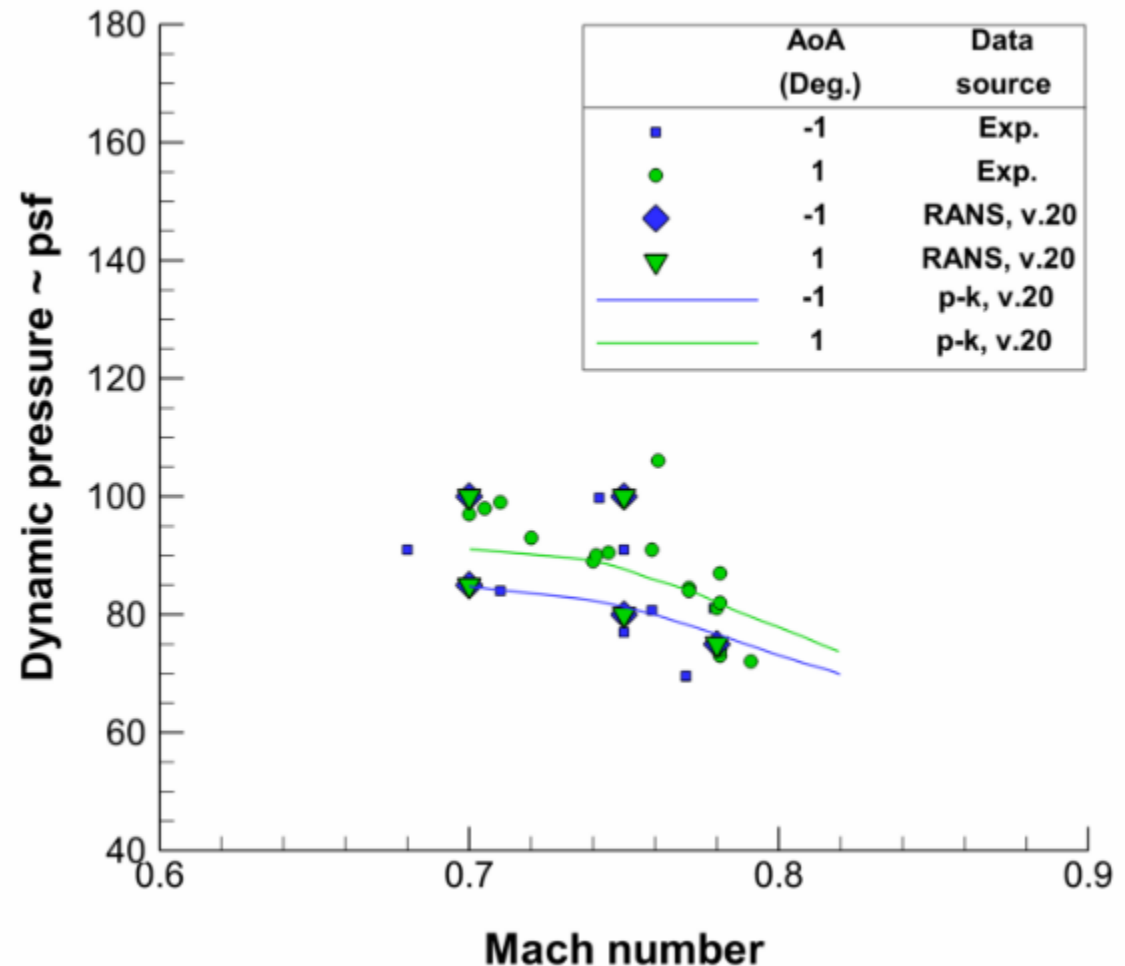


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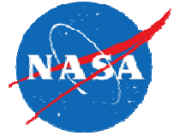
Results – Linear Aerodynamics



- Flutter simulations with linear aerodynamics
- Conditions at which Navier-Stokes simulations are performed
- All conditions in this figure are at -1 or +1 degree AoA.
- Static wing and strut loading influences the dynamic pressure at which flutter occurs.
- Note that experimental conditions are also included for reference.

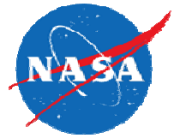


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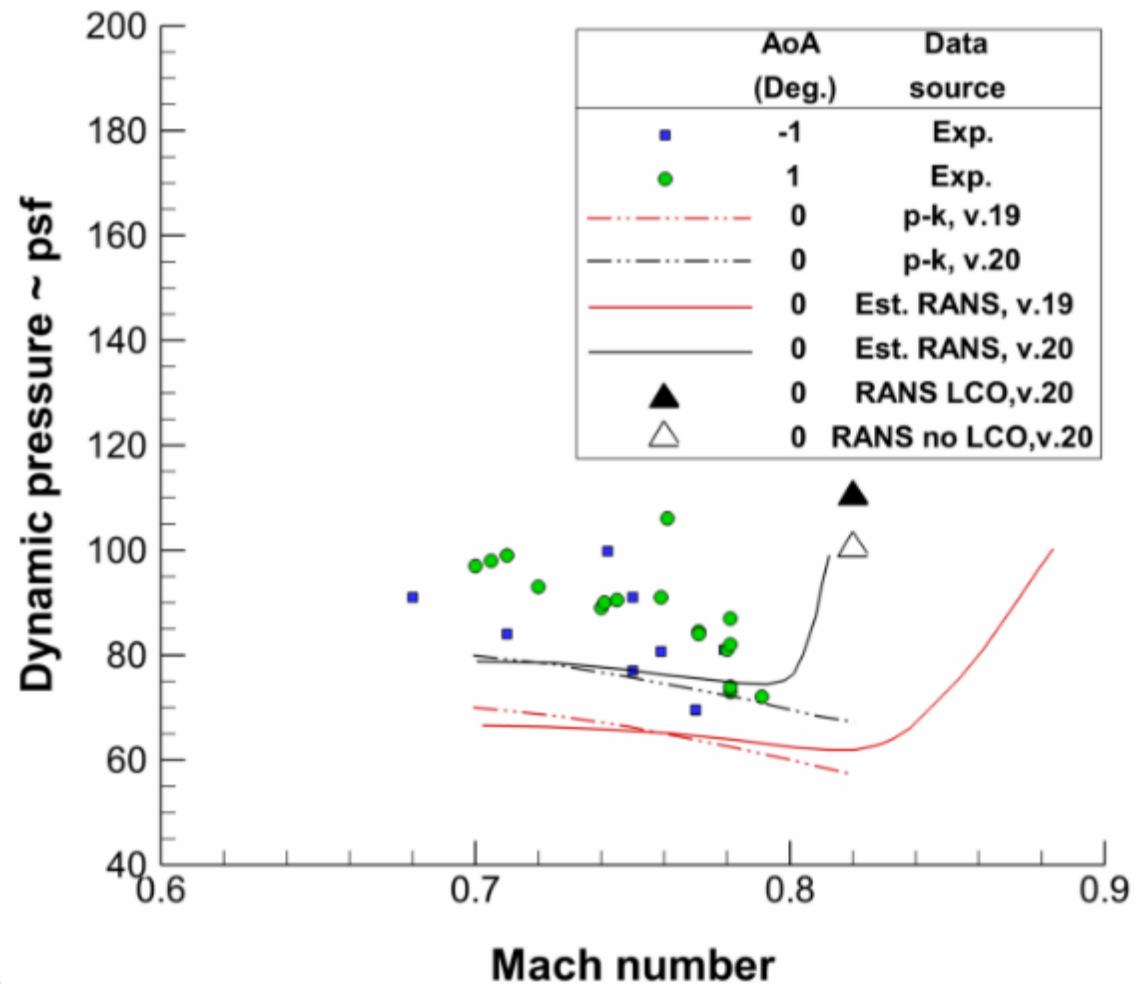


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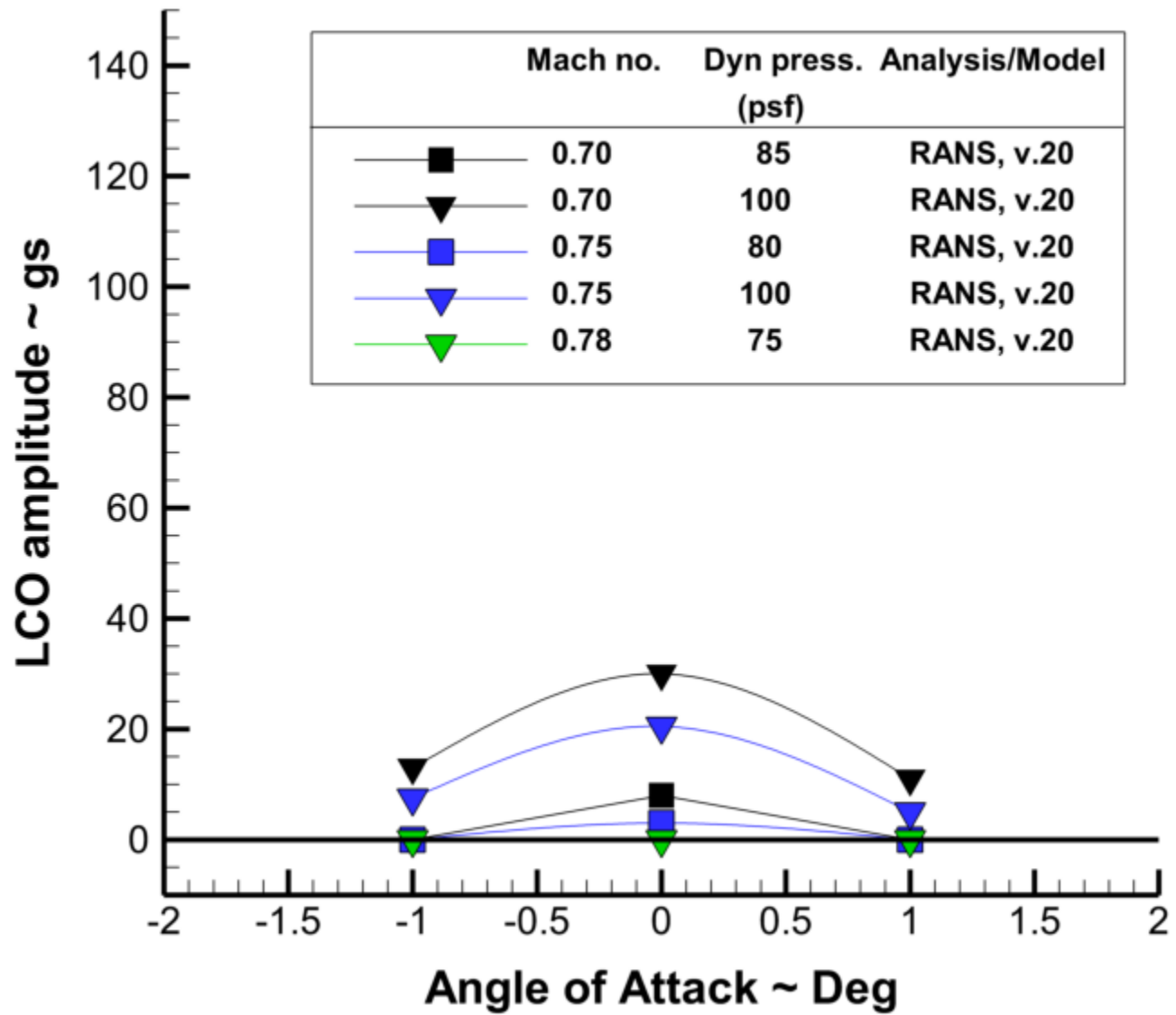
Results – Comparison of v.19 and v.20 FEM



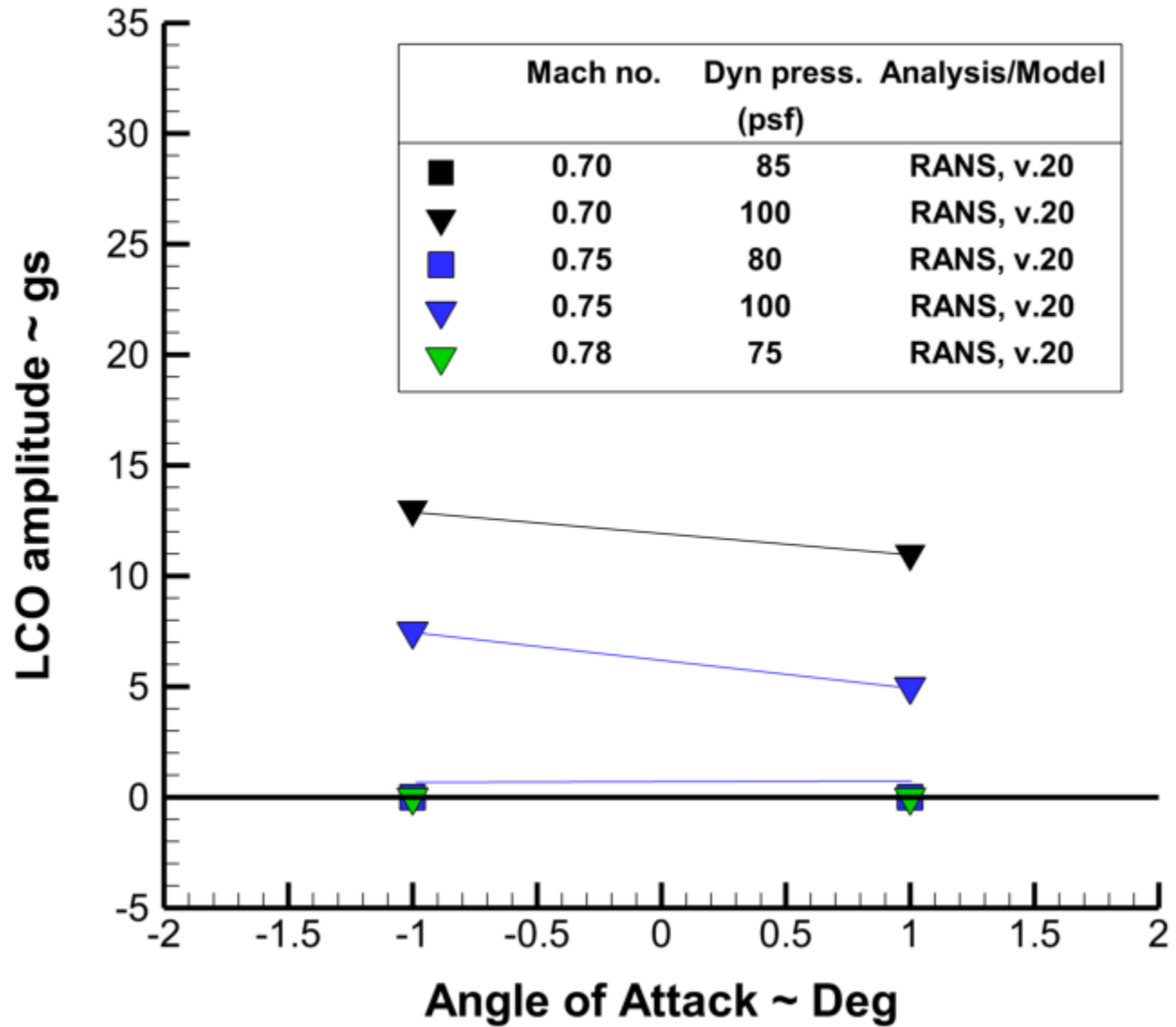
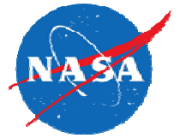
- Time step and sub-iterative convergence of RANS solutions was studied in Bartels et al. (2014)
- Comparison is made between the v.19 and v.20 TBW FEMs at 0 AoA.
- Flutter occurs for the v.20 FEM at a higher dynamic pressure due to larger separation of mode 3 and 4 frequencies.
- The shape of the v.20 flutter onset above Mach 0.80 is different than the v.19 FEM flutter onset.



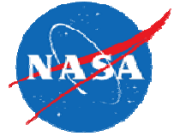
Results – Comparison, AoA -1, 0 and +1 deg



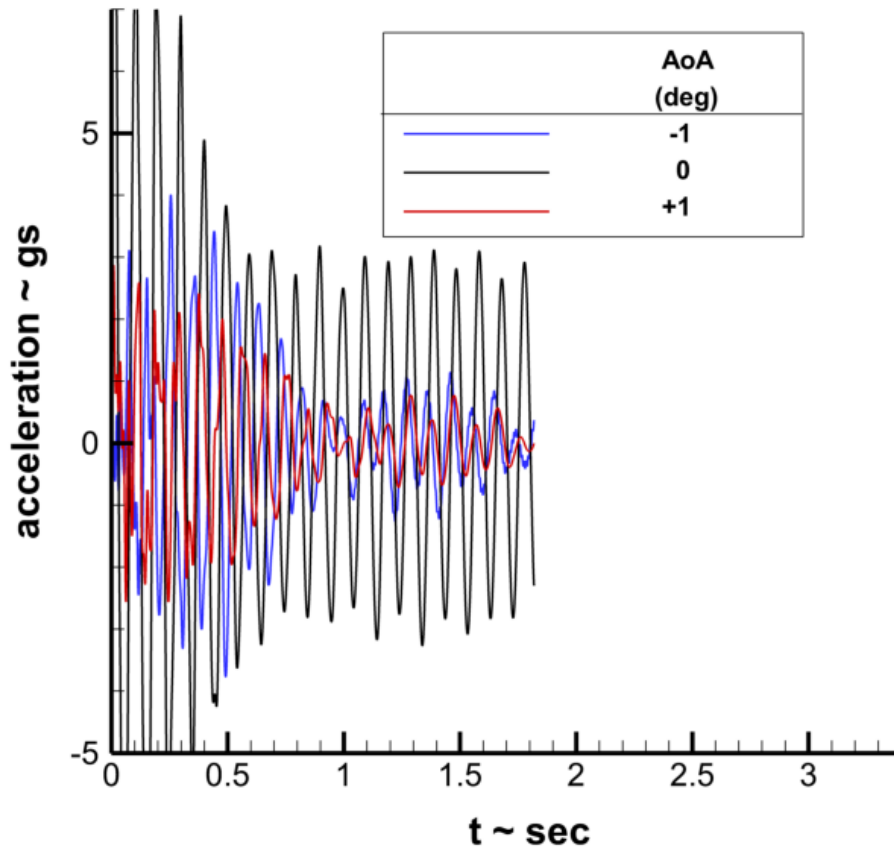
Results – Comparison, AoA -1 and +1 deg



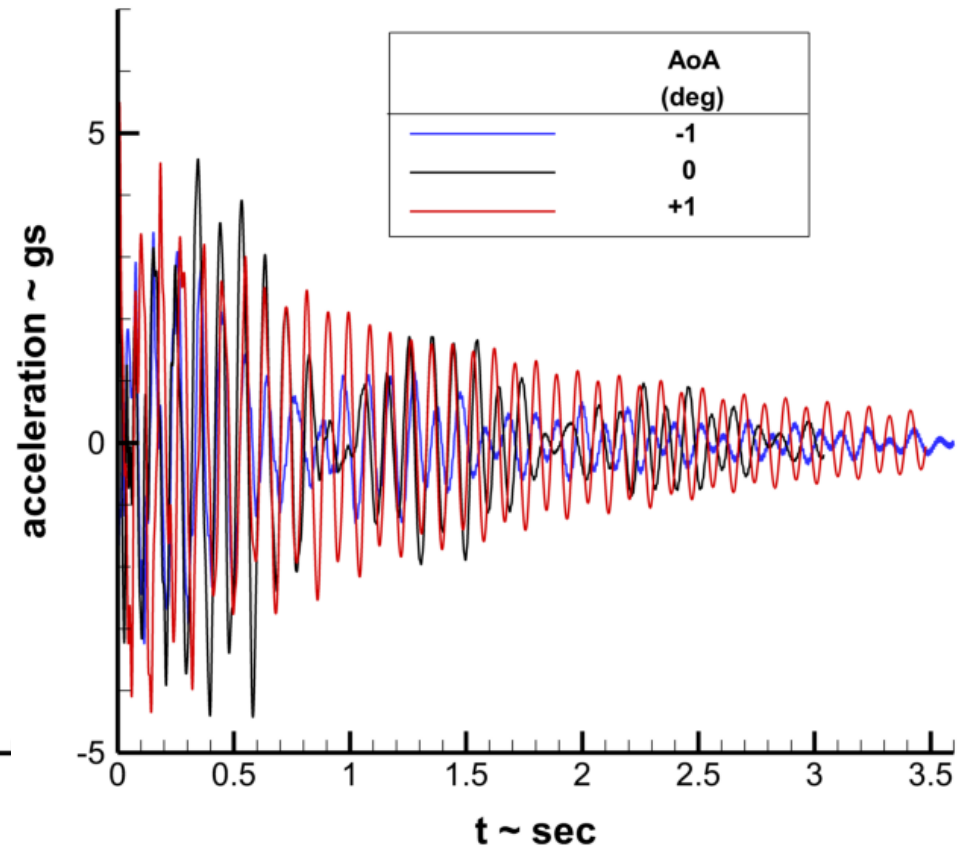
Results – Comparison, AoA -1 and +1 deg



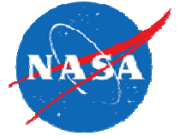
Mach 0.75, 80 psf



Mach 0.78, 75 psf



Conclusions



- Conclusions that can be clearly made:
 1. Angle of attack and model sensitivity is predicted well with linear aerodynamics and a static nonlinear structural model.
 2. LCO is predicted with nonlinear aerodynamics (Navier-Stokes) and linear dynamic structural model
 3. Flutter and LCO onset are quite sensitive to the mass and/or stiffness distribution of the wing.
 4. Force/displacement transfer between fluid and structure meshes requires algorithms that can accommodate complex beam structures models and fine CFD mesh spacing.
- Somewhat tentative conclusions:
 1. A better refined CFD mesh may enable better correlation of simulated LCO onset with experiment.

