

BIOMECHANICAL MODELING OF THE DEADLIFT EXERCISE ON THE HULK DEVICE TO IMPROVE THE EFFICACY OF RESISTIVE EXERCISE MICROGRAVITY COUNTERMEASURES

K.M. Jagodnik^{1,2}, W.K. Thompson¹, C.A. Gallo¹, L. Crentsil³, J.H. Funk⁴, N.W. Funk⁴, G.P. Perusek¹, C.C. Sheehan⁴, B.E. Lewandowski¹

¹NASA Glenn Research Center, 21000 Brookpark Rd., Cleveland, OH 44135

²Baylor College of Medicine, 1 Baylor Plaza, Houston, TX 77030

³George Washington University, 2121 I St. NW, Washington, DC, 20052

⁴ZIN Technologies, 6745 Engle Road, Airport Executive Park, Cleveland, OH 44130



INTRODUCTION & MOTIVATION

- Extended spaceflight typically results in the loss of muscular strength and bone density due to exposure to microgravity.
- Resistive exercise countermeasures have been developed to maintain musculoskeletal health during spaceflight.
- The Advanced Resistive Exercise Device (ARED)¹ is the "gold standard" of available devices; however, its footprint and volume are too large for use in space capsules employed in exploration missions.
- The Hybrid Ultimate Lifting Kit (HULK) device, with its smaller footprint, is a prototype exercise device for exploration missions.
- This work models the deadlift exercise being performed on the HULK device using biomechanical simulation, with the long-term goal to improve and optimize astronauts' exercise prescriptions, to maximize the benefit of exercise while minimizing time and effort invested.**

PROJECT VISION

NASA's Digital Astronaut Project Vision

The Digital Astronaut Project (DAP) implements well-validated computational models to predict and assess spaceflight health and performance risks and to enhance countermeasure development by

- Partnering with subject matter experts to inform Human Research Program (HRP) knowledge gaps and countermeasure development decisions
- Modeling and simulating the adverse physiologic responses to exposure to reduced gravity and analog environments
- Ultimately providing timely input to mission architecture and operations decisions in areas where clinical data are lacking

RISKS & GAPS

Human Research Program Risks/Gaps Addressed

Risks:

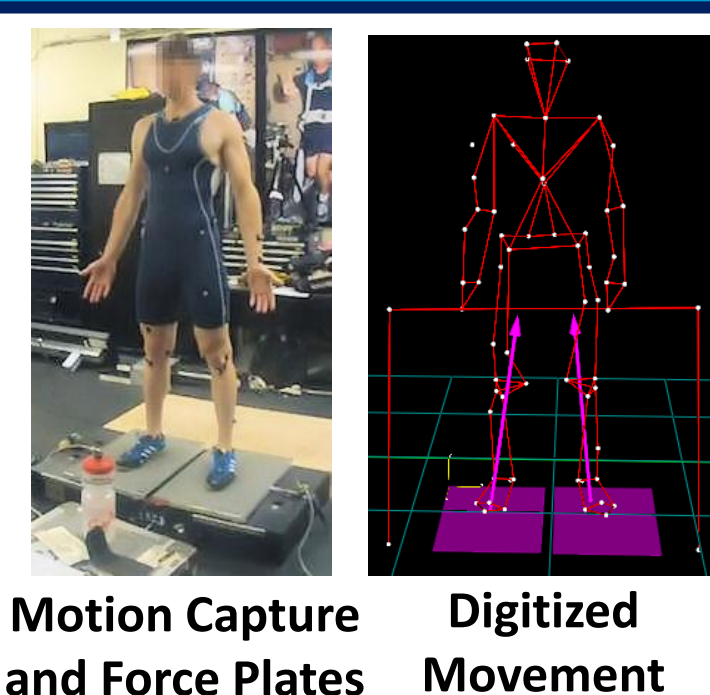
- The Risk of Impaired Performance Due to Reduced Muscle Mass, Strength and Endurance
- The Risk of Bone Fracture
- The Risk of Early Onset Osteoporosis Due To Spaceflight

Gaps:

- What exercise protocols are necessary to maintain skeletal health, and can exercise hardware be designed to provide these?
- What is the minimum exercise regimen needed to maintain fitness levels for tasks?
- What is the minimum set of exercise hardware needed to maintain those fitness levels?

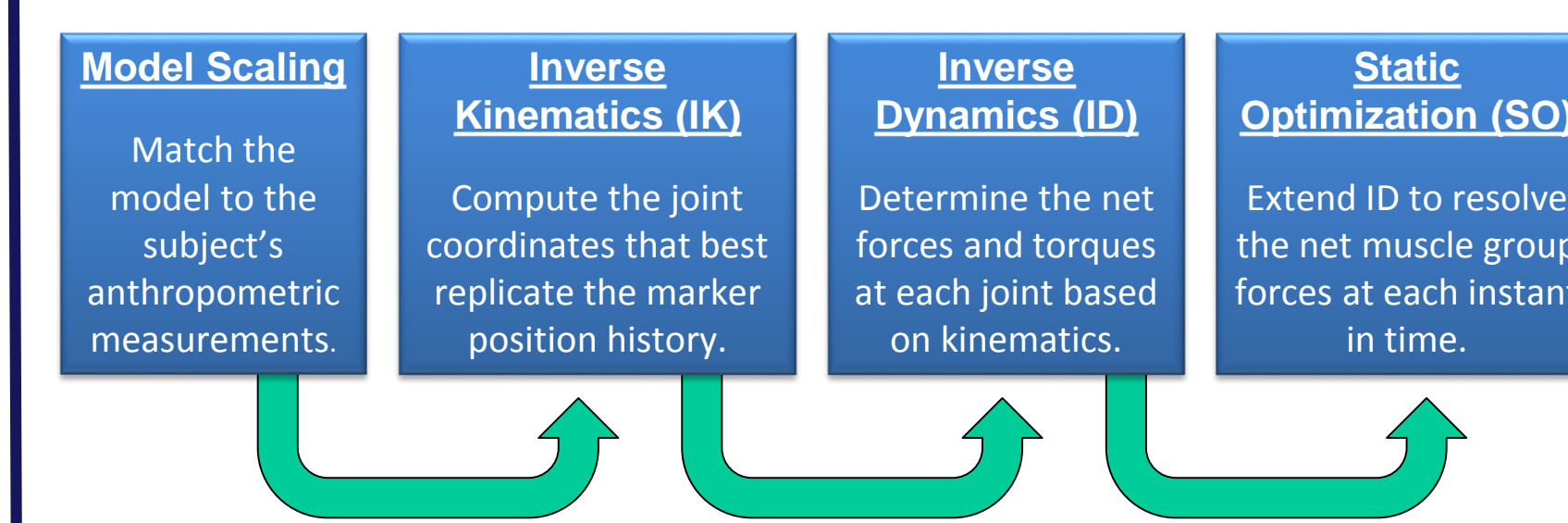
MOTION CAPTURE

- BTS Bioengineering Smart-D 12-camera motion capture system used
- Recorded data are digitized to translate physical data into biomechanical model in OpenSim²



OPENSIM MODEL WORKFLOW

(Iteration among steps is assumed)



EXERCISE HARDWARE

Hybrid Ultimate Lifting Kit (HULK)³

(ZIN Technologies)

- Compressed air and piston assembly provides direct resistance
- Servo motor provides an eccentric overload
- Load cells in cables for load history
- Offers a wide variety of resistance exercises

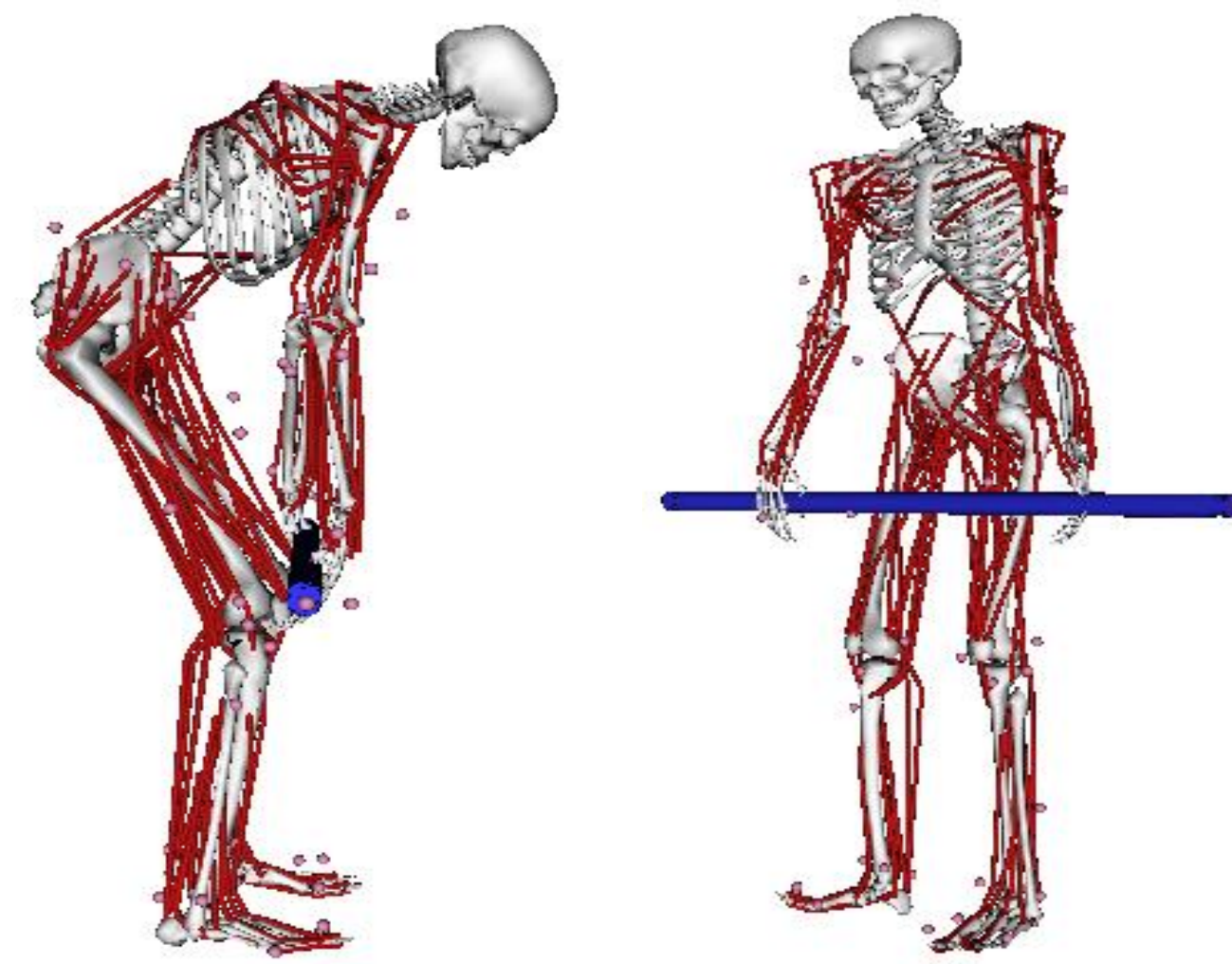


HULK Deadlift Exercise

MODELING METHODS

OpenSim Biomechanical Deadlift Model

- Human Data: 2 human subjects performed 26 deadlift trials; load, load configuration, cadence and stance width were varied across trials
- Deadlift model consists of modified versions of existing lower extremity⁴ and upper extremity⁵ OpenSim models
- Deadlift model is scaled to the test subjects
- Model is based on subject's anthropometrics and motion capture data while in static pose and exercising
- HULK resistance load applied to model as a force at the bar ends
- Ground reaction force from force plates applied to model at the feet



OpenSim Model of Deadlift Exercise with HULK Bar Load

EMG

- BTS Free EMG System: 16 wireless sensors placed according to <http://seniam.org> & Thought Technology Ltd. surface EMG placement guide
- DC component removal, rectify and envelop signal with RMS calculation
- Signals normalized to MVC

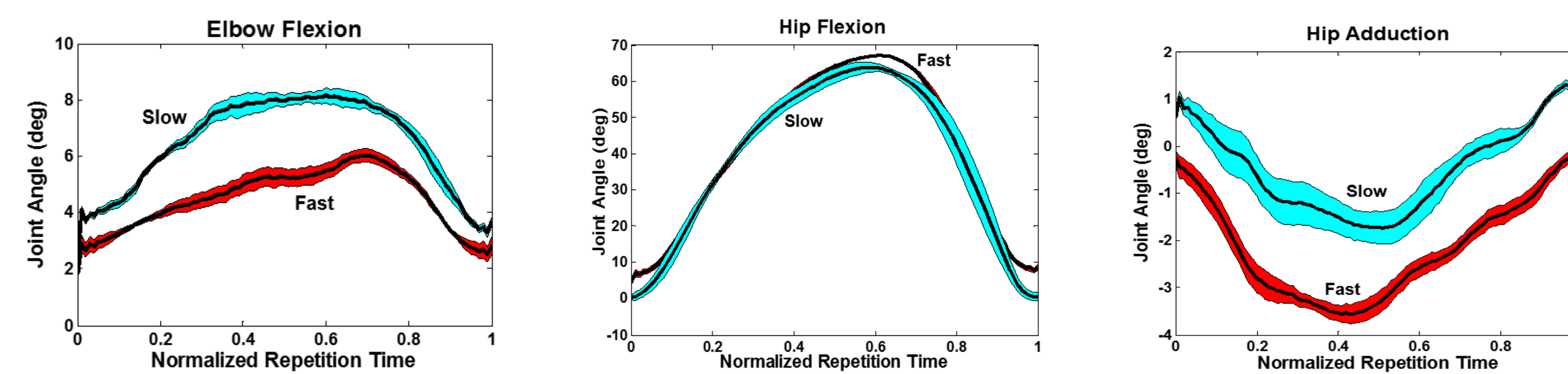


ACKNOWLEDGMENTS

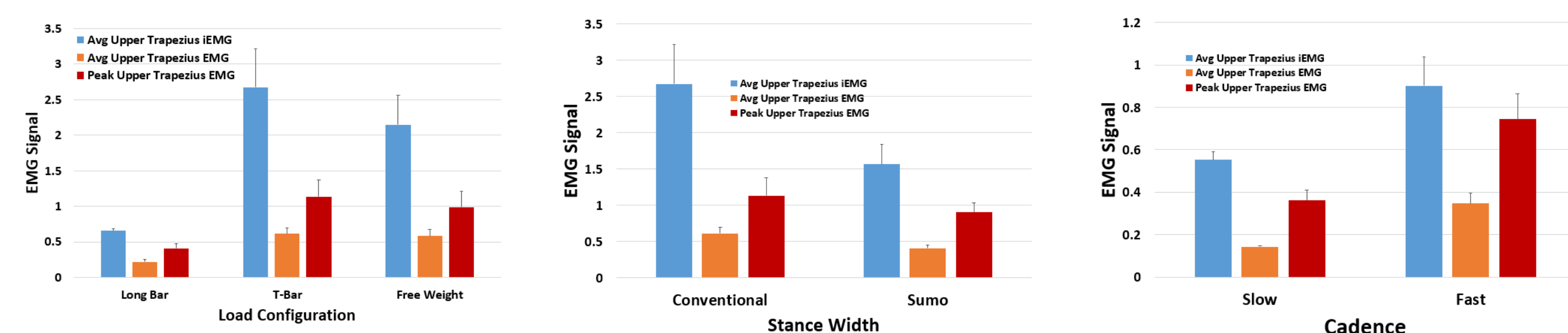
This work is partially supported by the National Space Biomedical Research Institute through NCC 9-58. This work is funded by the NASA Human Research Program, managed by the NASA Johnson Space Center. Specifically, this work is part of the Digital Astronaut Project (DAP), which directly supports the Human Health and Countermeasures (HHC) Element. The DAP project is managed out of NASA/Glenn Research Center (GRC) by De'Von W. Griffin, Ph.D., and Beth Lewandowski, Ph.D., serves as the DAP Project Scientist.

HULK DEADLIFT EXERCISE RESULTS

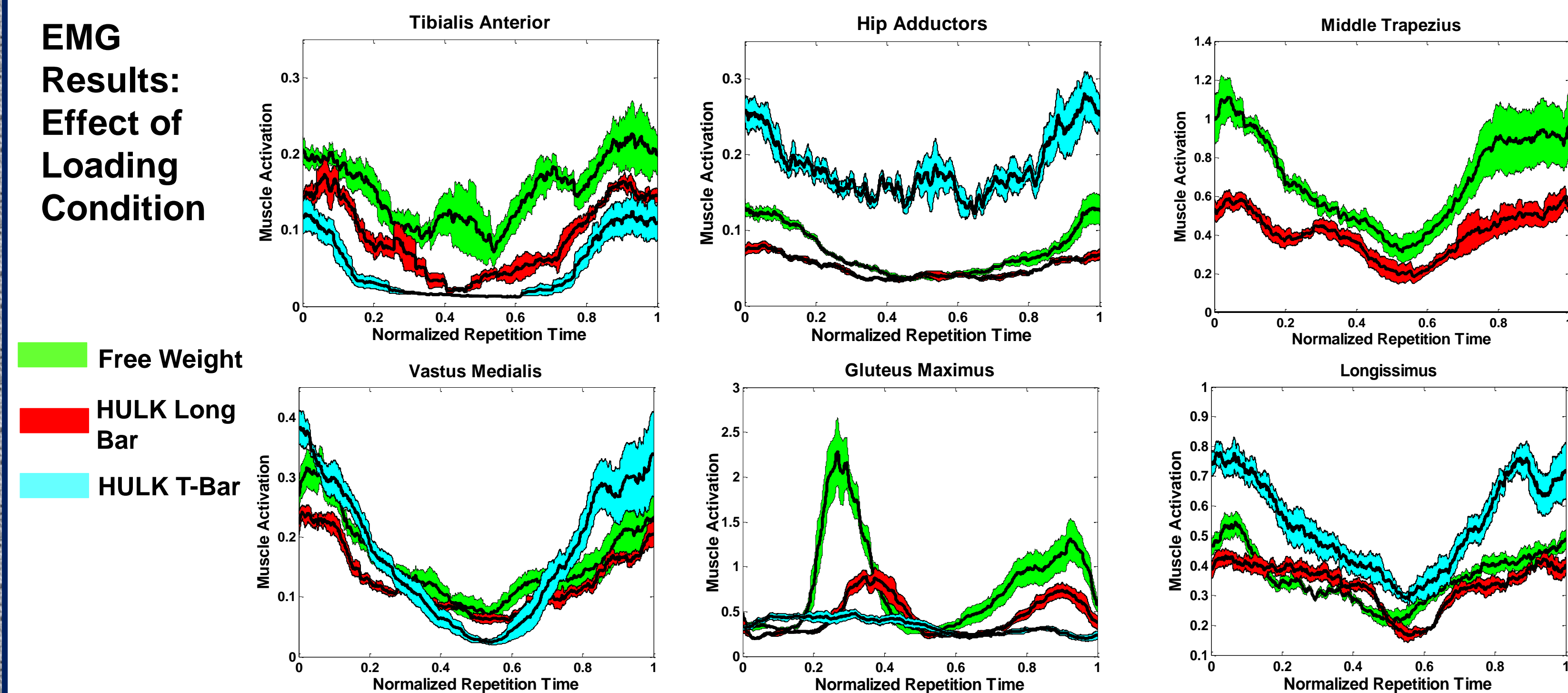
Kinematics Results: Joint Angles for Differing Deadlift Cadences



EMG Results: Effect of Deadlift Parameters on Upper Back Muscle Activity



EMG Results: Effect of Loading Condition



DISCUSSION

- Inverse kinematics completed for subset of deadlift trials; joint angle analysis reveals similarities and differences between experimental conditions to inform exercise prescriptions.
- EMG can be used to compare muscle activity for different exercise parameters; these results can yield non-obvious conclusions about how exercise design affects the activity of specific muscles.
- The 16 recorded muscles are each affected differently by varying loading conditions; employ this knowledge to assist in designing exercise prescriptions to achieve effective activity for a wide range of muscles.

VERIFICATION & VALIDATION

- Ensure that root mean square (RMS) marker positions are within OpenSim² guidelines
- Joint errors are within 2 degrees of experimental values
- Employ NASA-STD-7009 standards to assess credibility
- Compare deadlift modeling results with ground-based 1g deadlift exercise studies published in the literature

CHALLENGES & LIMITATIONS

- Investigate consistency of EMG data over different data collection sessions
- Include more human subjects for a more representative and general data set
- Collect additional trials to achieve more confidence in results

FUTURE WORK

- Further develop deadlift model to include shoulder stability
- Investigate developing deadlift model to improve efficiency
- Continue performing inverse kinematics (IK) analyses
- Determine dynamic properties of the deadlift using inverse dynamics (ID) analysis
- Perform static optimization (SO) to determine net forces of muscle groups

REFERENCES

- Smith SM et al., Benefits for bone from resistance exercise and nutrition in long-duration spaceflight: Evidence from biochemistry and densitometry. American Society for Bone and Mineral Research, 27(9): 1896-1906, 2012.
- Delp SL et al., OpenSim: Open-source software to create and analyze dynamic simulations of movement, IEEE Transactions on Biomedical Engineering, 54(11): 1940-1950, 2007.
- High Eccentric Resistive Overload Device, Concept of Operations, ZIN Technologies, Cleveland, OH.
- Arnold, EM et al., A model of the lower limb for analysis of human movement, Annals Biomedical Engineering 2010 Feb; 38(2): 269-79. Epub 2009 Dec 3, 2010.
- Saul KR et al., Benchmarking of dynamic simulation predictions in two software platforms using an upper limb musculoskeletal model. Computer Methods in Biomechanics and Biomedical Engineering, 18(13): 1445-1458, 2015

PARTNERS

