

Design and Analyses of High Aspect Ratio Nozzles for Distributed Propulsion Acoustic Measurements

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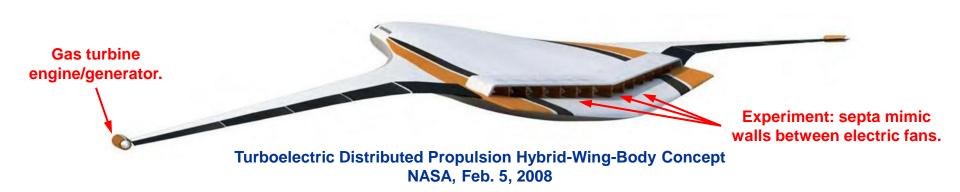


Outline

- Introduction
- Nozzle Design Requirements
- Screening Simulations and Nozzle Grids
- Nozzle Designs
- Conclusions and Recommendations



Introduction



- NASA's roadmap for future transport aircraft includes departure from tube-and-wing aircraft.
- Above: wingtip gas turbine engines power multiple electric-driven fans in mail slot distributed arrangement.
- Jet-Surface Interaction High Aspect Ratio nozzle tests conducted at NASA Glenn Research Center Nozzle Acoustic Test Rig (NATR) took acoustic measurements of similar configuration:
 - High aspect ratio, mail slot-like nozzle.
 - Septa inserts to mimic individual fan ducts.
 - Aft deck.
- Goal: design nozzle for NATR to simulate distributed propulsion system.



High Aspect Ratio Nozzle Requirements

<u>Purpose:</u> Design a series of round-to-rectangular high aspect ratio (HAR) convergent nozzles for NATR to simulate distributed propulsion nozzle system.

Requirements:

- HAR nozzle aspect ratios: 8:1, 12:1, 16:1.
- Inflow: circular, *D*=10.29 inches.
- Exit area: ~39.68 square inches.
- Max length: ~24 inches
 - NATR has free-jet around nozzle to simulating forward flight.
 - Maximum length ensures HAR nozzle plume is contained within NATR free-jet potential core.
- Constant span segment near exit for septa inserts.
- Minimize unfavorable flow characteristics that would potentially produce rig noise: flow separations, exit shocks.
- Near-uniform flow entering septa inserts.

Exit Dimensions of High Aspect Ratio Nozzles					
				Equivalent	
				Diameter	
Aspect Ratio	Height [in]	Width [in]	Area (A_{iet}) [in ²]	(D_{ea}) [in]	
8:1	2.227	17.820	39.685	7.108	
12:1	1.818	21.822	39.672	7.107	
16:1	1.575	25.197	39.685	7.108	

Exit Dimensions of High Aspect Ratio Nozzles



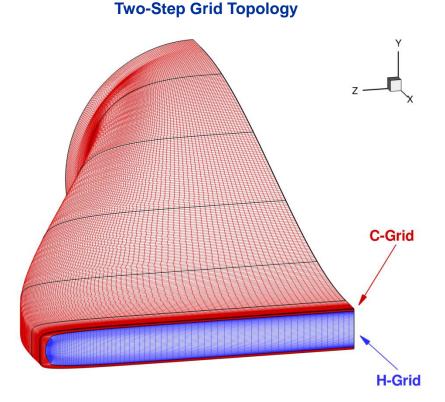
Screening Simulations

- Wind-US v4 used for all simulations.
 - General purpose, compressible Reynolds-Averaged Navier-Stokes solver.
 - SST turbulence model used.
 - Steady flow simulations, i.e. constant CFL number.
- Flow conditions for simulations used Tanna Matrix Set Point 7:
 - Quiescent Freestream: p_{∞} =14.3 psi; M_{∞} =0.01
 - NPR=1.861 \rightarrow M_{jet} =0.98 (M_a =0.90)
 - "Unheated" Jet: T_0 =529.64°R (T_{jet}/T_{∞} =0.835)
 - Did <u>not</u> simulate NATR free-jet (forward flight).
- Simulations performed on NASA Advanced Supercomputing System:
 - "Ivy Bridge" nodes, using 32-100 processor cores per simulation.
 - Typically, obtained converged solution in about a week.



High Aspect Ratio Nozzle Grids

- Two-step structured grid for HAR nozzle internal flow:
 - "C" grid along nozzle wall (red).
 - "H" grid through center of nozzle flow (blue).
 - Reduced highly skewed cells, singularities, unresolved geometry
 - Continued two-step grid through jet plume and external flow.
- Wall spacing: 0.0002 inches (nominal y⁺=2).
- Farfield boundary: 30 inches (4.2×D_{eq}).
- Downstreeam boundary: 280 inches (25.3×D_{eq}).
- Grid size: 9.2 million to 33.5 million cells.





High Aspect Ratio Nozzle Designs

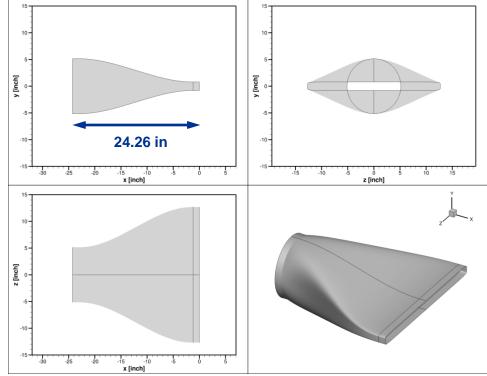
- Assumptions:
 - Aspect ratio 16:1 nozzle would be most challenging, since span grows the most (2.45x inflow diameter). Design AR=16:1 nozzle first, use similar techniques for AR 12:1, 8:1 HAR nozzles.
 - Round-to-rectangular nozzle could be designed as a backwards inlet using SUPIN (parameterized inlet design code).
- Nomenclature: A*x.y* nozzle design:
 - x=aspect ratio
 - y=nozzle design iteration
 - A16.2 \rightarrow aspect ratio 16:1; design iteration 2
- <u>Note:</u> Only the more interesting nozzle designs will be presented. Some design iterations will be skipped.



A16.2 Nozzle Design

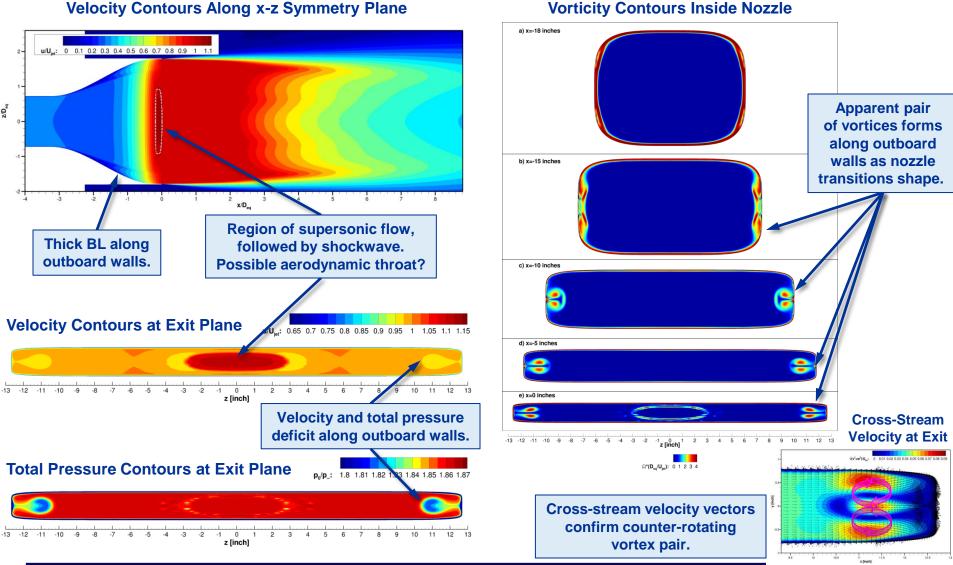
- Used modified version of SUPIN.
 - SUPIN is a parametric inlet design tool by John Slater at NASA GRC (AIAA Paper 2012-0016).
 - Thought it could be a quick method to generate complex nozzle geometries.
 - John Slater delivered a version of SUPIN, adapted for nozzle geometry design.
 - Ran SUPIN to generate backwards nozzle designs.
- Set:
 - Inflow Area (RadEF)
 - Exit Area (FAcap)
 - Aspect Ratio (ARtopcap, ARbotcap)
- Variable Parameters:
 - Total Length (FLsubd)
 - Length of Constant Area Exit (Lthrt)
 - Super-ellipse Parameter (ptopcap, pbotcap)
 - Y-position of exit (Yinlet)
 - NURBS CURVE Parameters (Xsdgc2, Fdsdgc2, Fdsdgc1, Fdsdgc3)

A16.2 Nozzle Design





A16.2 Nozzle Screening Simulation



Velocity Contours Along x-z Symmetry Plane

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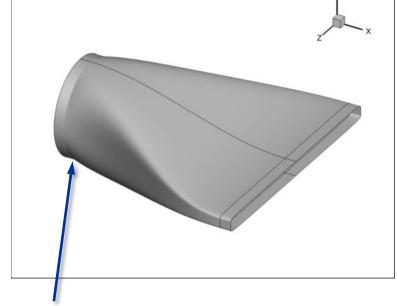


SUPIN-Designed HAR Nozzles

- Performed screening simulating of • several HAR nozzle designs generated with SUPIN.
- Nozzles produced undesirable flow features:
 - Thick boundary layers and flow separation along outboard walls as span grew.
 - Non-uniform flow along outboard walls near exit plane: velocity and total pressure deficit: vortex pair.
 - Normal shock along centerline, likely due to aerodynamic throat from thick BL on sidewalls.
- SUPIN-generated nozzle designs ۲ were not always smooth near inflow.
- SUPIN was not adequate tool for • generating nozzle designs.
 - Required greater ability to control and parameterize nozzle designs



A16.2 Nozzle Design

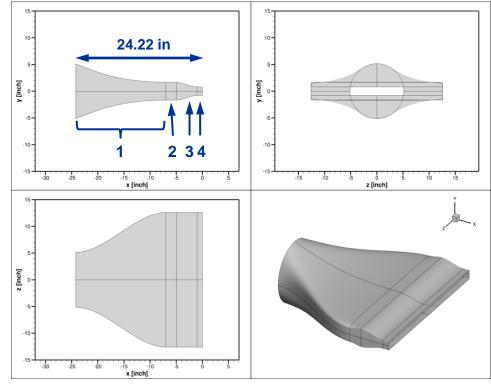


Non-smooth flow lines.



A16.6 Nozzle Design: Segmented Approach

- For greater control over HAR nozzle design, wrote code that generated nozzle in segments.
- Each segment focused on changing one or two aspects of geometry (e.g., contraction, span, crosssection shape).
- A16.6 nozzle consisted of 4 segments:
 - Transition from circular to order 10 superellipse; grow major axis (span) to nozzle exit width via cubic polynomial; maximum divergence angle less than 33°; constant area.
 - 2. Transition from order 10 superellipse to order 100 via exponential function; constant area.
 - 3. Contract area to nozzle exit area (<u>100% of</u> <u>total contraction</u>) using cubic polynomial for minor axis (height).
 - 4. Constant area and shape to nozzle exit.



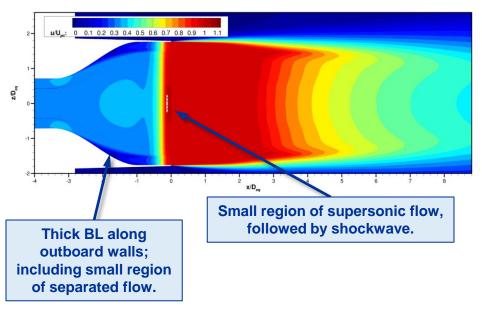
A16.6 Nozzle Design



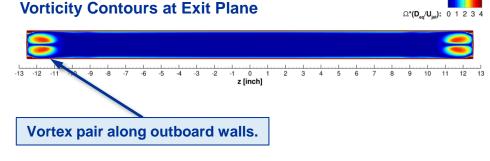
A16.6 Nozzle Screening Simulation

- A16.6 nozzle design still had undesirable flow features:
 - Thick BL along outboard walls (appears thicker than A16.2 design).
 - Small region of separated flow (that does reattach).
 - Small region of supersonic flow at nozzle exit.
 - Pair of counter-rotating vortices along outboard walls.

Velocity Contours Along x-z Symmetry Plane



 Is it possible better distribute the flow towards the outboard walls as the span grows?

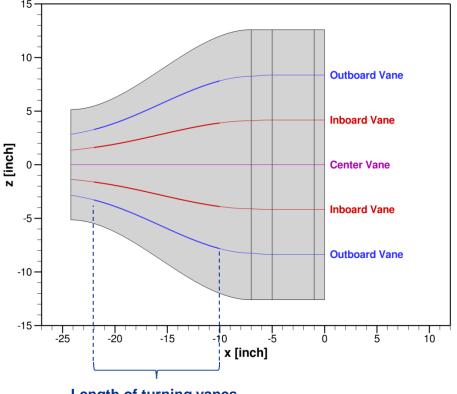




Adding Turning Vanes to the A16.6 Nozzle

- Turning vanes added to divide cross-sectional area into six equal areas.
- Grid zonal interfaces placed along locations of turning vanes.
 - Wall boundary condition used to model vane.
- Vanes modeled as infinitely thin and inviscid.
- Low-cost method for screening simulation to determine whether vanes distribute flow outwards.
- A16.6-vaneA nozzle included inboard and outboard vanes.

A16.6 Nozzle Design with Turning Vanes



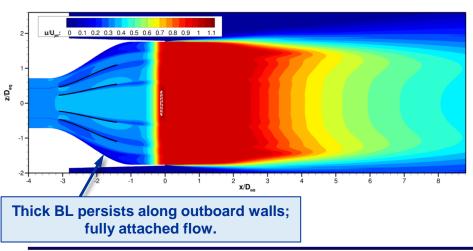
Length of turning vanes.



A16.6-vaneA Nozzle Screening Simulation

- Turning vanes were successful at distributing flow towards outboard walls and reducing BL.
 - BL remained fully attached.
- Turning vanes did produce vorticity disturbances near the nozzle exit from shedding off the vanes.
 - Non-uniformity would be amplified into actual wakes if vanes modeled with viscous boundary condition.





a) x=-20 inches b) x=-15 inches **Vorticity from** flow shedding off vanes. c) x=-10 inches d) x=-5 inches e) x=0 inches -13 -12 -11 -10 -9 -8 -7 -6 -5 -4 -3 -2 10 11 Vortex pair along Ω*(D_{an}/U_{int}): 0 1 2 3 4 outboard walls.

Vorticity Contours Inside Nozzle

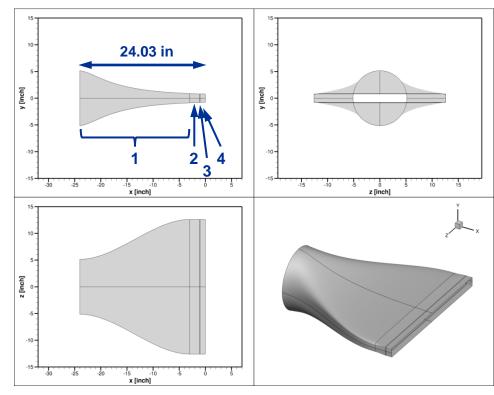
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A16.7 Nozzle Design

- Continued the segmented nozzle design approach
- Included area contraction through Segments 1-3.
- A16.7 nozzle consisted of 4 segments:
 - 1. Transition from circular to order 10 superellipse; grow major axis (span) to nozzle exit width using cubic polynomial; maximum divergence angle less than 28°; linear area contraction, <u>91.3% of total</u> <u>contraction</u>.
 - 2. Transition from order 10 superellipse to order 100 via exponential function; linear area contraction, <u>8.3% of total contraction</u>.
 - 3. Complete linear area contraction, <u>0.4% of</u> total contraction.
 - 4. Constant area and shape to nozzle exit.

A16.7 Nozzle Design

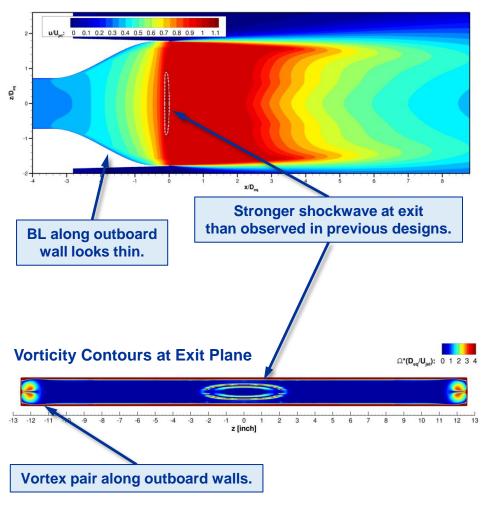




A16.7 Nozzle Screening Simulation

- A16.7 nozzle design made some improvements, but also :
 - Thin BL along outboard walls (thinner than A16.2 and A16.6 designs).
 - Region of supersonic flow at nozzle exit, with stronger shock than previous designs.
 - Pair of counter-rotating vortices along outboard walls.

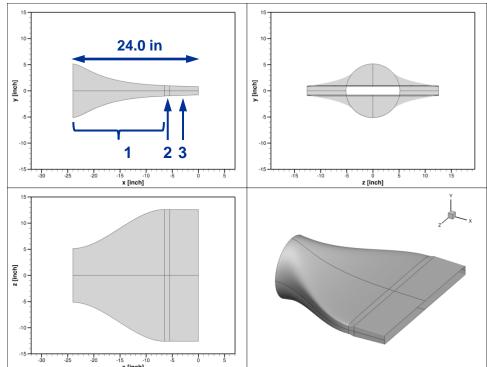
Velocity Contours Along x-z Symmetry Plane





A16.10 Nozzle Design

- Continued the segmented nozzle design approach
- Area contraction through <u>all</u> segments.
- Lengthened segment for septa inserts to 5.5 inches; relaxed requirements so height could change if span constant.
- A16.10 nozzle consisted of 3 segments:
 - 1. Transition from circular to order 10 superellipse; grow major axis to nozzle exit width via cubic polynomial; maximum divergence angle less than 33°; linear area contraction, <u>75.7% of total contraction</u>.
 - Transition from order 10 superellipse to order 100 via exponential function; linear area contraction, <u>4.3% of total contraction;</u> constant major axis (span) length.
 - Linear area contraction, <u>20% of total</u> <u>contraction</u>; constant major axis (span) length and constant superellipse order; longer segment length (5.5 inches) to accommodate septa inserts.



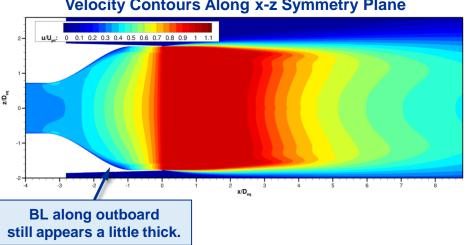
A16.10 Nozzle Design



Ω*(D_/U

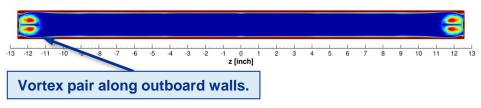
A16.10 Nozzle Screening Simulation

- A16.10 nozzle design looked • good, with mostly uniform flow near exit:
 - BL along outboard walls not as thin as A16.7 design, but thinner than A16.2 and A16.6 designs.
 - No region of supersonic flow or shockwave at exit plane
 - Still had pair of counter-rotating vortices, about as strong as previous designs.

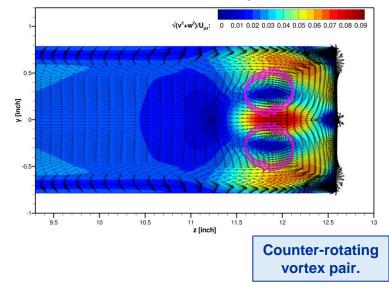


Velocity Contours Along x-z Symmetry Plane

Vorticity Contours at Exit Plane



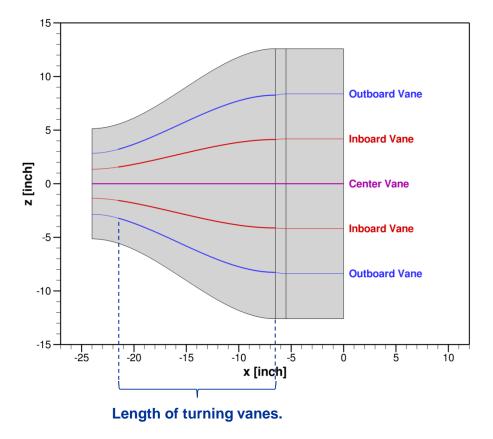
Cross-Stream Velocity at Exit





A16.10 Nozzle with Vanes

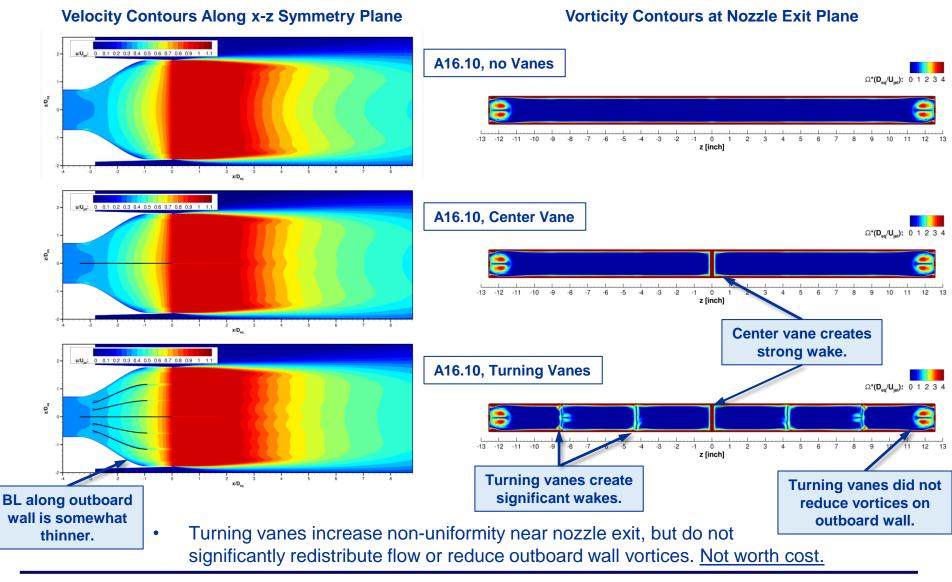
- Added turning vanes and center vane to A16.10 nozzle design
- Mechanical studies showed that center vane needed for AR=16:1 nozzle to maintain structural integrity
- Vanes modeled as infinitely thin, but now <u>viscous</u>



A16.10 Nozzle Design with Turning Vanes



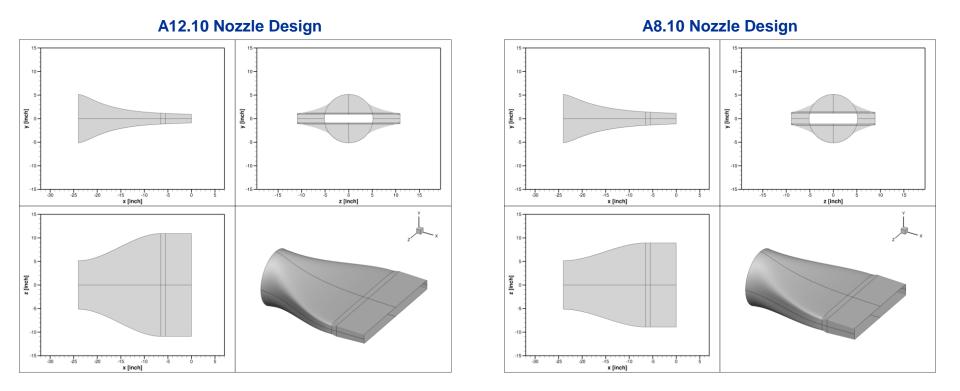
A16.10 Nozzle with Vanes





A12.10 and A8.10 Nozzle Designs

• The same code the was used to generate A16.10 nozzle was used to generate A12.10 and A8.10 nozzle (aspect ratio 12:1, 8:1).

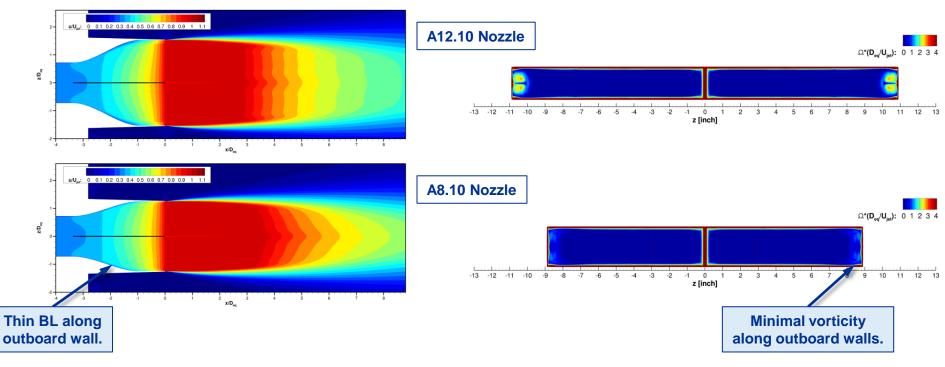




A12.10 and A8.10 Nozzle Screening Simulations

Velocity Contours Along x-z Symmetry Plane

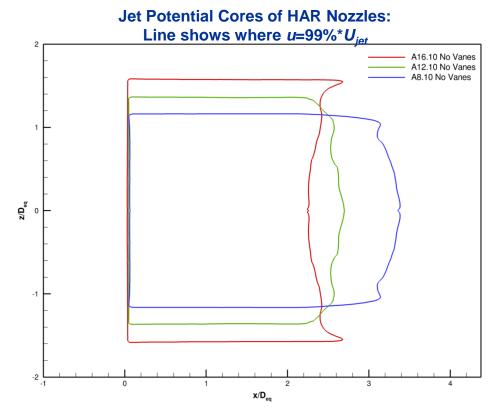
Vorticity Contours at Nozzle Exit Plane



- Smaller aspect ratio (AR=8:1) minimizes undesirable flow features:
 - BL along outboard wall remains thin.
 - Minimal vorticity and non-uniformities near nozzle exit.
- AR=12:1 also reduces undesirable flow features some, as compared to AR=16:1 nozzle.



Comparison of Nozzle Jet Potential Cores



- Jet potential core of A16.10 nozzle breaks down along centerline first, but is sustained along outboard edges longer.
- Is it possible that vortices help sustain the potential core longer along the outboard edges of the AR=16:1 nozzle?



High Aspect Ratio Nozzle Dischange and Thrust Coefficients

Nozzle	C _d	Cv
A8.10	0.9829	0.9916
A12.10	0.9809	0.9908
A16.10	0.9795	0.9886
A16.2	0.9810	0.8840

• Discharge Coefficient:
$$C_d = \frac{\int_{A_{jet}} (\boldsymbol{\rho} \cdot \boldsymbol{u}) \cdot dA}{\boldsymbol{\rho}_{jet} \cdot \boldsymbol{U}_{jet} \cdot A_{jet}}$$

• Thrust Coefficient:
$$C_d = \frac{\int_{A_{jet}} [\rho \cdot u^2 \cdot (p - p_{\infty})] \cdot dA}{U_{jet} \cdot \int_{A_{jet}} (\rho \cdot u) \cdot dA}$$

- Clearly, discharge and thrust coefficients decrease as nozzle exit aspect ratio increases.
- Large improvement in thrust coefficient from early HAR nozzle design
 to final HAR nozzle design



Conclusions

- A series of three round-to-rectangular high aspect ratio convergent nozzles were designed using: AR=16:1, 12:1, 8:1.
- Custom code used to generate nozzle designs using a segment approach in order to control various aspects of geometry:
 - Transition from round to rectangular via superellipse.
 - Area contraction.
 - Nozzle span growth.
- Generating good design for AR=16:1 nozzle was most challenging, but lead to good designs of AR=12:1 and AR=8:1 nozzles.
 - Minimized potential sources of rig noise and non-uniformity in flow near nozzle exit.
 - Unable to eliminate counter-rotating vortex pair from AR=16:1 and AR=12:1 nozzle designs.
 - Greatly improved HAR nozzle thrust coefficient from early design to final design.
- Key observations:
 - Area contraction through entire length is best: maintain favorable pressure gradient and reduce chance of aerodynamic throat near exit.
 - Flow turning in short nozzles with larger AR (i.e., AR=12:1, 16:1) seems to produce counter-rotating vortex pair along outboard wall that cannot be fully eliminated.
 - Internal turning vanes reduced BL growth some, but produced wakes and did not suppress vortices.
 - As nozzle exit aspect ratio increased, discharge and thrust coefficients decreased.
- RANS simulations were valuable in screening designs of test hardware. Helped reduce risk and improve designs before nozzles fabricated.



Future Work

- Perform RANS simulations of HAR nozzles with septa and/or aft deck:
 - These configurations were tested in Jet-Surface Interaction-High Aspect Ratio (JSI-HAR) tests at NASA Nozzle Acoustic Test Rig (NATR) with limited flowfield measurements.
 - RANS simulations would provide greater understanding of aerodynamic performance not observed in experiments.



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