



# Nondestructive Evaluation Education, Experiences and Career at NASA

ASNT Chapter Meeting  
[Brazosport College](#)

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## Part 2

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# Agenda



## *Nondestructive Evaluation Laboratory*

- Organization of NDE at NASA
- Qualifications of NDE personnel at NASA
- NDE Requirements
- NDE Inspection
- NDE Methods
- NDE Method Application Examples
- POD Analysis
- Method Selection Factors
- Online Resources



# Organization of NDE at NASA



## *Nondestructive Evaluation Laboratory*

- Centers with NDE Facilities
  - Johnson Space Center (JSC)
    - International Space station (Boeing), Orion (Lockheed Martin), Morpheus, Commercial Cargo/Crew (SpaceX Dragon/Falcon 9, Sierra Nevada Dream Chaser, Orbital Sciences, and Boeing CST-100)
    - JSC Engineering Contractor: Jacobs Eng. / JETS Contract
  - Marshall Space Flight Center (MSFC)
    - Space Launch System
  - Glenn Research Center (GRC)
  - Goddard Space Flight Center (GSFC)
  - Kennedy Space Center (KSC)
    - NDE Contractor: PaR systems (Former United Space Alliance, Hanger N NDE) supporting KSC launch/assembly operations and commercial activities
  - Langley Research Center (LaRC)
    - NDE Research Branch
    - NASA Engineering Safety Center, NDE Manager
    - NASA Headquarters Code Q NDE Manager
      - Also known as NASA NDE Working Group (NNWG)
        - » NASA Commercial Crew NDE Liaison
  - White Sands Test Facility
- Centers with NDE or IVHM
  - Each center has some of the two. Other centers are
  - Jet Propulsion Lab, Stennis Research Center, Armstrong Flight Research Center and Ames Research Center



# Qualifications of NDE Personnel at NASA



## *Nondestructive Evaluation Laboratory*

- Civil Service
  - Ph. D.'s mostly at NASA LaRC
  - B.S. or M.S. in science, engineering, or mathematics
  - NAS 410 certified (NASA MSFC)
  - ASNT level 3 (MSFC and JSC)
- Contractor
  - NAS 410 required for part acceptance inspection
  - Formal education: high school diploma, AA, AS, BA, BS, MS, Ph. D.



# NDE Requirements



## *Nondestructive Evaluation Laboratory*

- NDE is part of Materials and Processes Engineering
- NASA Programs at JSC
  - Requirements are program specific, for example
    - NASA-STD-6016 Standard Materials and Process Requirements for Spacecraft
    - NASA-STD-5019: Fracture Control requirements for Spaceflight Hardware
    - NASA-STD-5009: Nondestructive Evaluation Requirements for Fracture Critical Metallic Hardware
  - NAS 410
  - MIL-HDBK-6870
  - Data Requirements Document DRD: NDE Plan
- Commercial Programs with JSC involvement
  - Some of above requirements would be applicable as negotiated between NASA and the provider



# NDE Inspection



*Nondestructive Evaluation Laboratory*

- NDE Inspection
  - Routine NDE inspection is performed by Quality organization, Safety and Mission Assurance (S & MA) by NAS 410
  - Engineering personnel certified as NAS 410 may also perform the acceptance NDE
  - When authorized by program it may also be performed by NDE experts that are not NAS 410 certified



# What is NDE?



## *Nondestructive Evaluation Laboratory*

- Nondestructive evaluation is a broad interdisciplinary field concerned with the development and use of inspection technologies to evaluate the integrity or measure a characteristic of a material, component or structure without impairing its future usefulness
- Common applications include:
  - Detection and sizing of defects in raw materials and manufactured components
  - Detection and sizing of in-service damage, e.g. fatigue cracks, corrosion and impact damage
  - Manufacturing process control
  - Assembly verification
  - Material verification and sorting
  - Coating thickness measurement
  - Physical, electrical and thermal property measurement
  - Stress measurement
- NDE is divided into various methods each based on a particular scientific principle (sound propagation in solids, thermal conductivity, electromagnetic induction, etc.)
- Each method is further divided into techniques based on the specific ways the method can be performed (ultrasonic pulse-echo, through transmission, contact, immersion); the total number of potential techniques is easily in the hundreds



# NDE Methods



## *Nondestructive Evaluation Laboratory*

- Acoustic Emission
- Electromagnetic
  - AC Field Measurement
  - Eddy Current
  - Remote Field
- Ground Penetrating Radar
- Guided Wave
- Laser
  - Profilometry
  - Holography/Shearography
- Leak Testing
  - Bubble Testing
  - Pressure Change
  - Halogen Diode
  - Mass Spectrometer
- Liquid Penetrant
- Magnetic Flux Leakage
- Magnetic Particle
- Neutron Radiography
- Radiological
  - Radiography
  - Computed Radiography
  - Computed Tomography
  - Digital Radiography
- Thermal/Infrared
- Ultrasonics
  - Time of Flight Diffraction
  - Phased Array
- Vibration Analysis
- Visual



# The Most Common Methods



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- Visual (VT)
- Liquid Penetrant (PT)
- Magnetic Particle (MT)
- Eddy Current (ET)
- Ultrasonic (UT)
  - Phased Array (PAUT)
- Radiographic (RT)



- Most basic and common inspection method used for detection of flaws visible on the surface of a part
- Tools include borescopes, magnifying glasses, mirrors, and video cameras





# SAFER Welded Tubing Visual Inspection

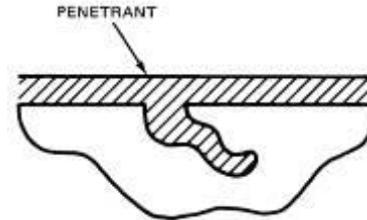


*Nondestructive Evaluation Laboratory*

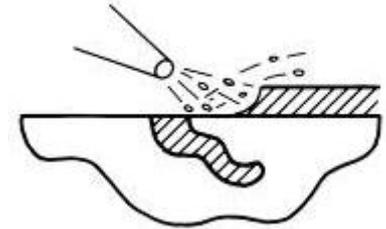
Tubing weld



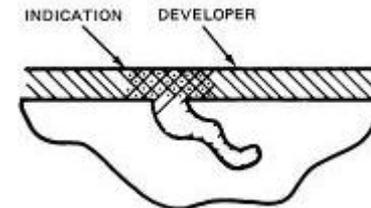
- Used for detection of flaws that are open or connected to the surface of a nonporous metal or nonmetal part
- Basic Process Steps
  1. Clean the part
  2. Apply penetrant
  3. Allow the penetrant to dwell for a minimum of 10 minutes
  4. Remove excess penetrant from the surface of the part
  5. Dry the part
  6. Apply developer
  7. Examine the part for indications a minimum of 10 minutes and a maximum of 60 minutes after the developer is applied
- Process details vary depending on the penetrant materials and equipment that are used.



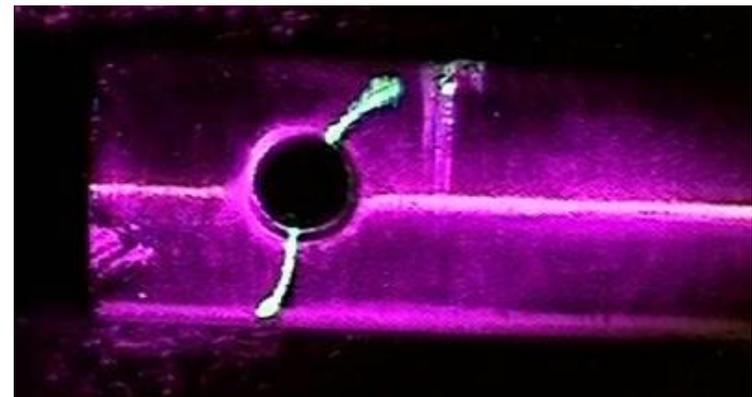
Apply Penetrant



Remove Excess



Develop

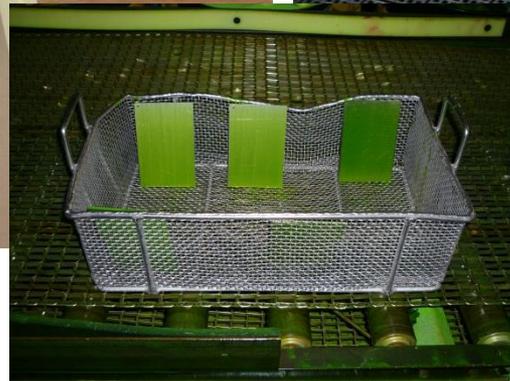




# Dye Penetrant Testing



*Nondestructive Evaluation Laboratory*



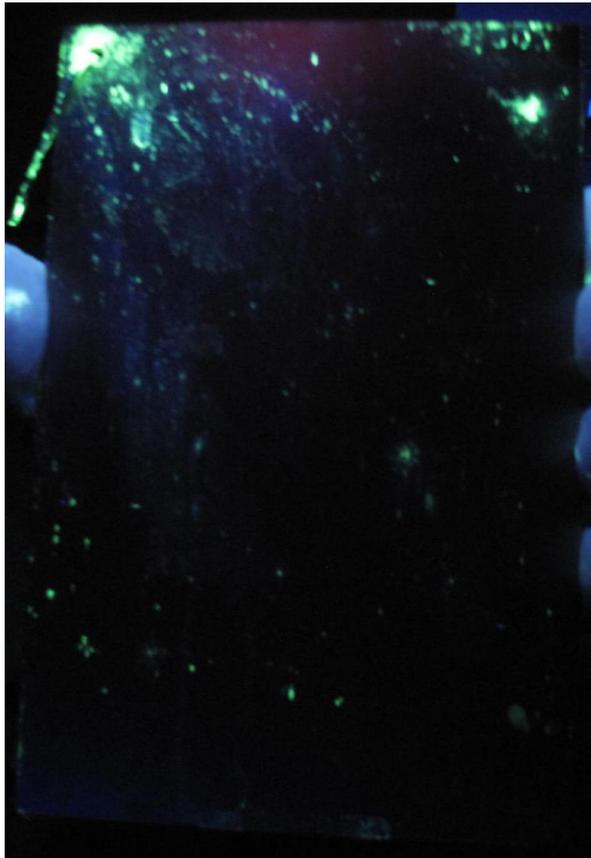


# Dye Penetrant Testing

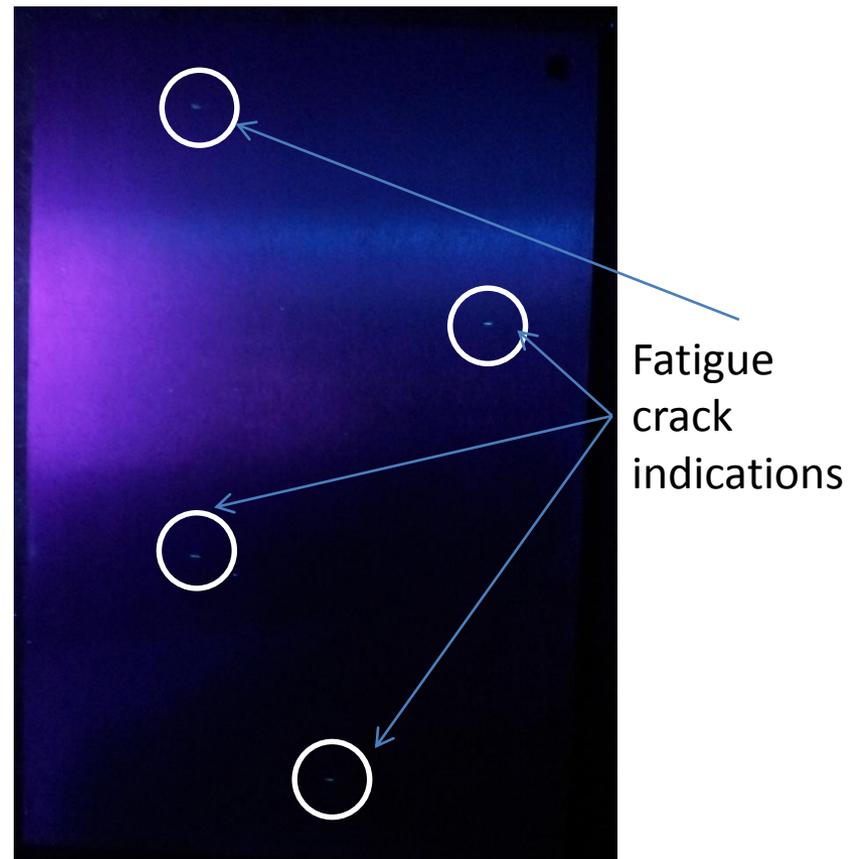


*Nondestructive Evaluation Laboratory*

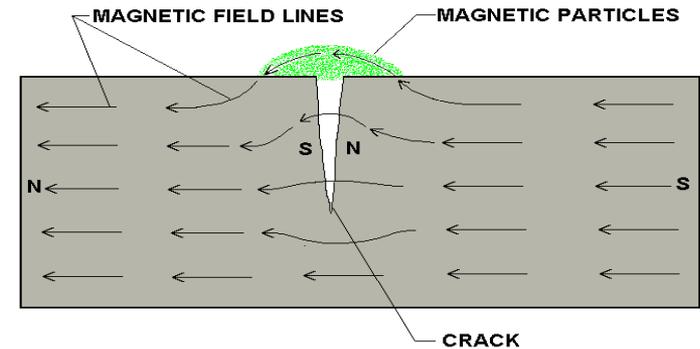
Excessive Background Fluorescence



Ideal Background Fluorescence



- Used for detection of surface or slightly subsurface flaws in ferromagnetic materials
- The part is magnetized ; AC or DC, circular or longitudinal
- Finely milled iron particles coated with a dye are applied to the part
- The particles are attracted to magnetic flux leakage fields and will cluster to form a visible indication directly over the discontinuity
- Flaws are difficult to detect when they make an angle of less than  $45^\circ$  to the direction of magnetization
  - For this reason, parts are normally magnetized in at least two perpendicular directions





# Magnetic Particle Testing



## Nondestructive Evaluation Laboratory

- Verification of appropriate magnetic field direction and strength is vital
  - The tangential field strength measured at the part surface should be a minimum of 30 Gauss (3 mT)
- Four commonly used methods:
  - Flexible laminated strip (field direction only)
  - Pie gauge (field direction only)
  - Notched shims (QQI)
  - Hall effect probe (gauss meter)
- Cannot depend on the formulas – they're only meant for simple part geometries
  - Fields in complex parts can cancel each other out!
- A QQI or gauss meter are the only reliable methods





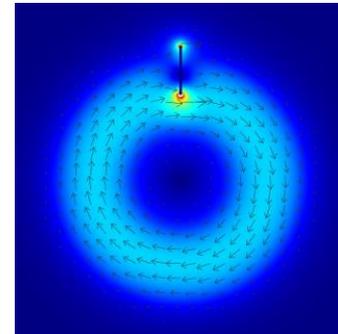
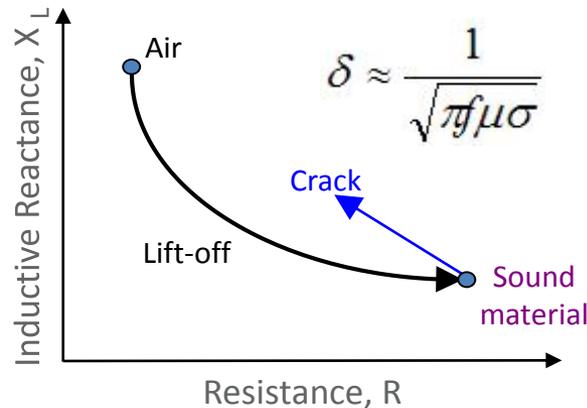
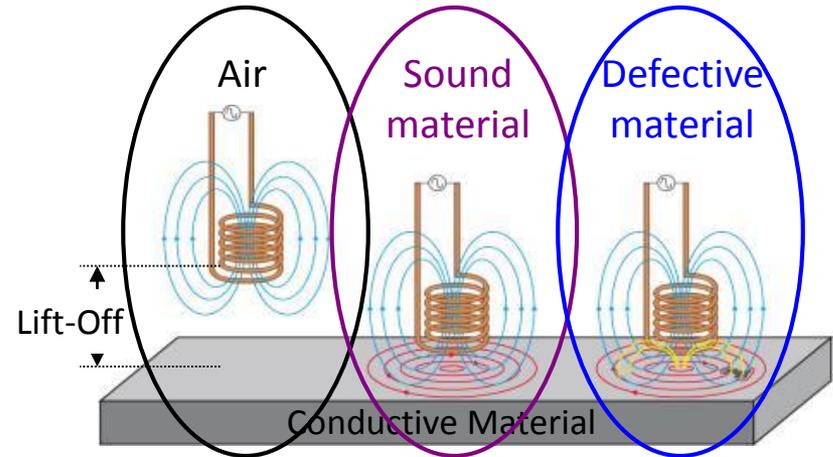
# Portable Magnetic Particle Inspection Kit



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- Used for detection of surface and subsurface flaws in electrically conductive materials
- An AC current is passed through a wire coil producing a primary alternating magnetic field around the coil
- When the primary magnetic field intersects a conductive material, oscillating eddy currents are induced in the material
- The eddy currents produce a secondary magnetic field which interacts with the primary field and changes the coil's impedance
- Flaws will disrupt the flow of eddy currents which in turn disrupts the secondary magnetic field and ultimately the coil's impedance



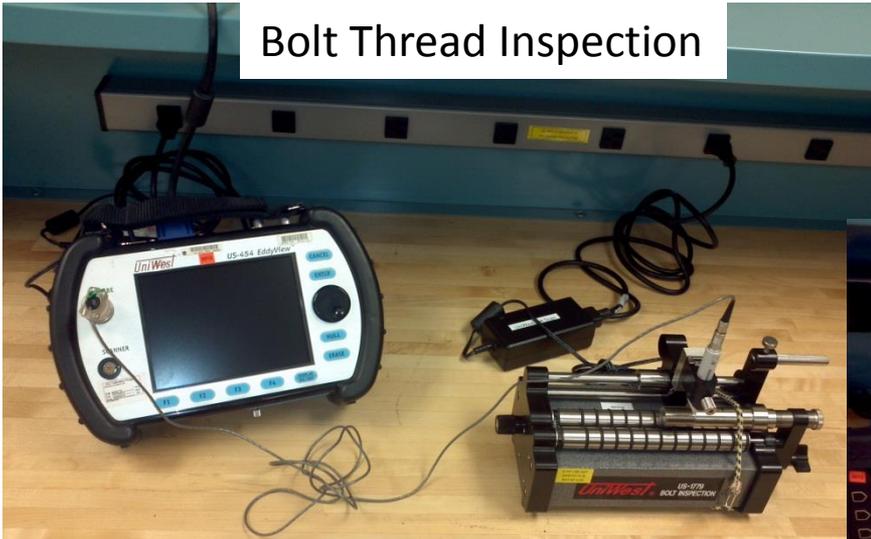


# Eddy Current Testing

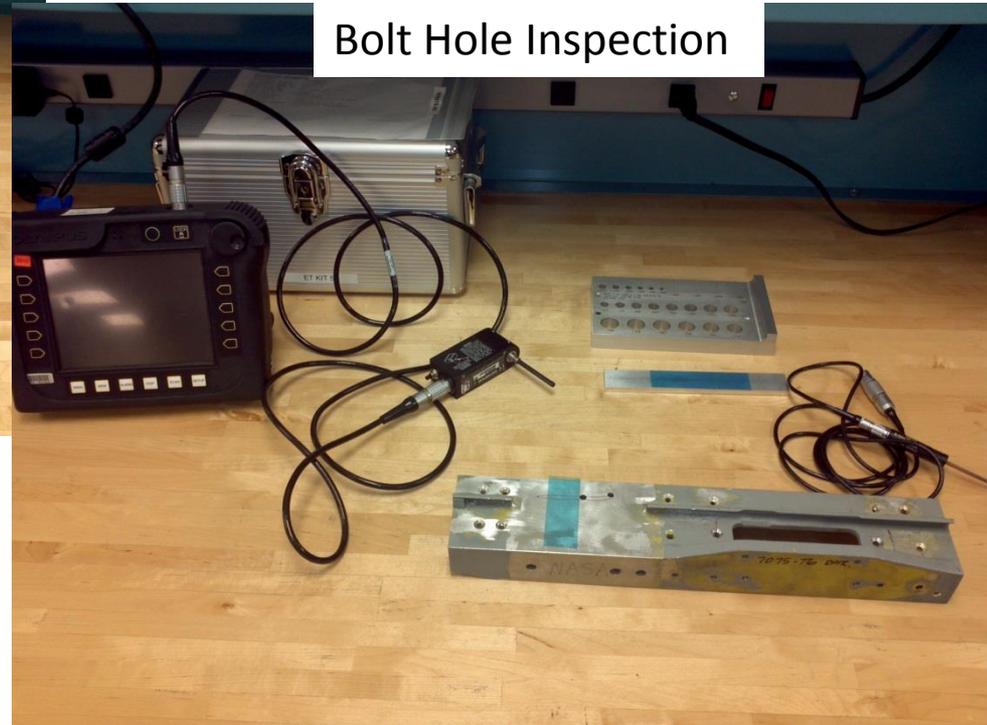


## *Nondestructive Evaluation Laboratory*

Bolt Thread Inspection



Bolt Hole Inspection



Eye Bolt Thread Inspection

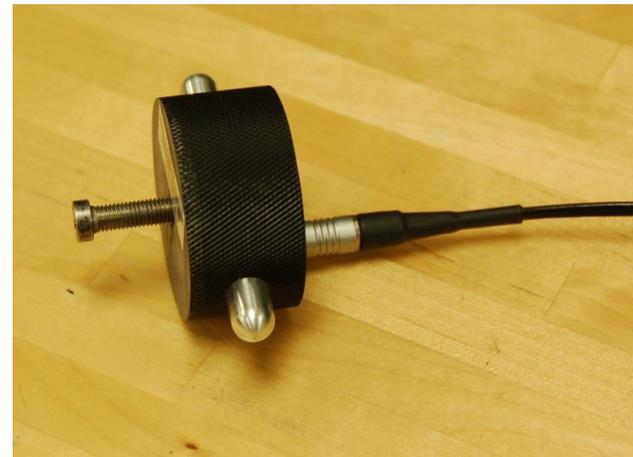


## NDE Laboratory Scanners and Probes

Bolt Scanner



"Nut" Type Bolt Probe



Bolt Hole Scanner



Array Probes





# Eddy Current Testing

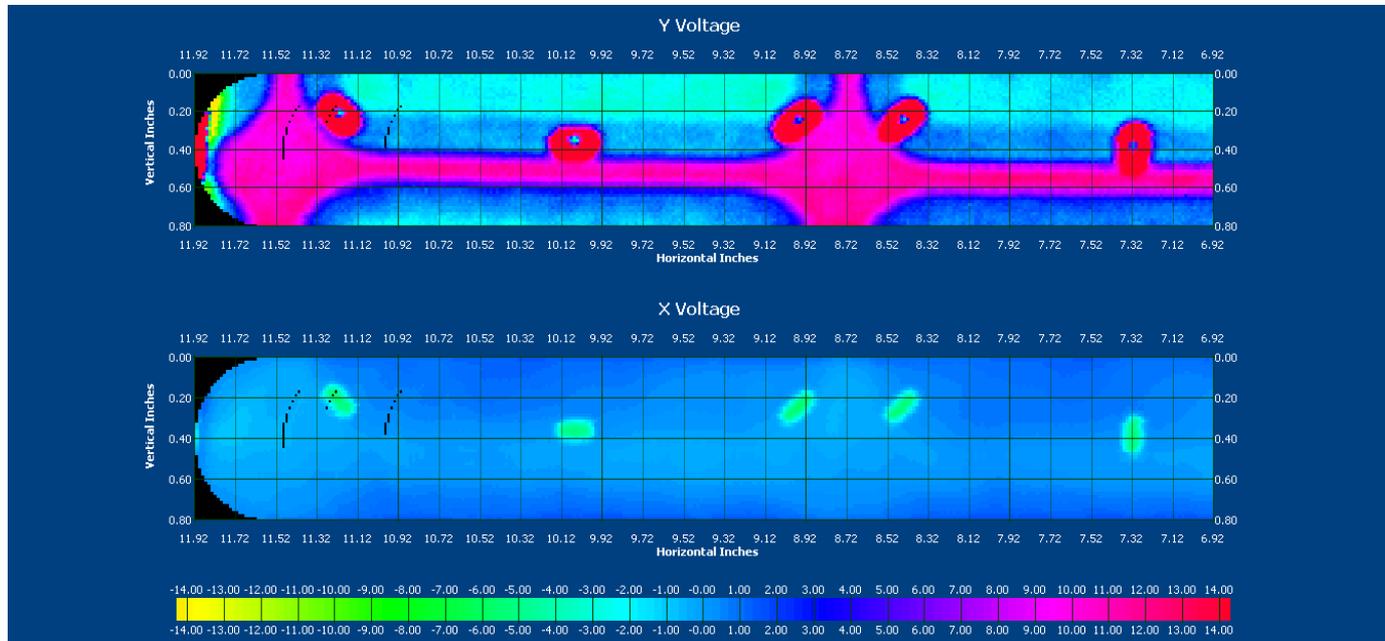


*Nondestructive Evaluation Laboratory*

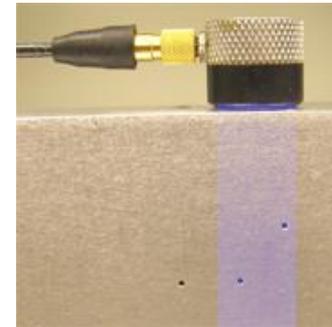
## UniWest ECS-3 Rotating Scanner



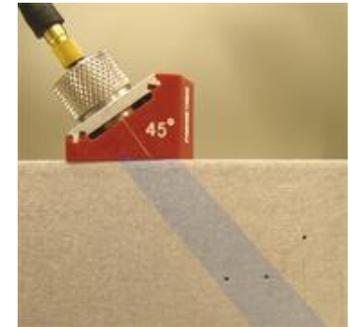
- Russian ISS Pressure Wall (Aluminum; 0.0625" skin thickness; 0.438" rib thickness)
- 12 kHz test frequency
- 0.1" long x 0.020" deep backside EDM notches in the skin



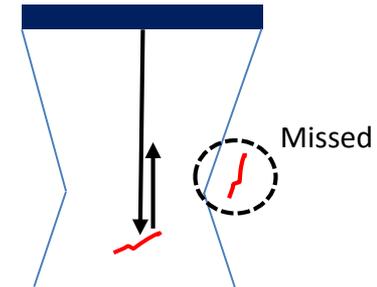
- Used for detection of surface and subsurface flaws in metals, nonmetals and composites
- Conventional transducers use a single piezoelectric element to transmit and receive high frequency (1 to 15 MHz) sound waves, typically longitudinal (compression) or transverse (shear)
- The sound beam is unidirectional and divergent although focusing is possible using specialized transducers
- For maximum response, the direction of sound propagation must be perpendicular to the plane of the flaw
- Accept/reject decisions are usually made based on a comparison of the signal amplitudes produced by the flaw and a specified reference reflector, typically a drilled hole or EDM slot



0° Longitudinal



45° Shear



A-Scan



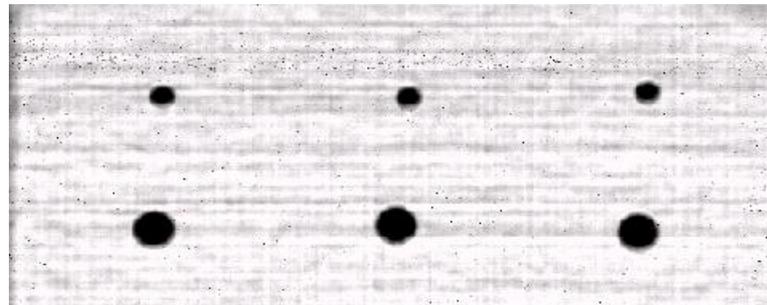


# Ultrasonic Testing

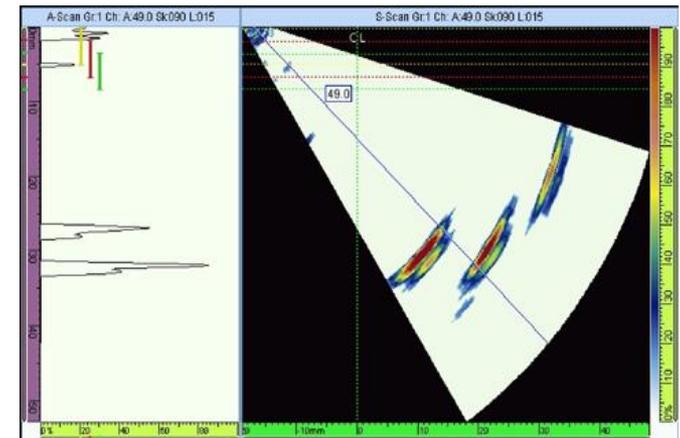
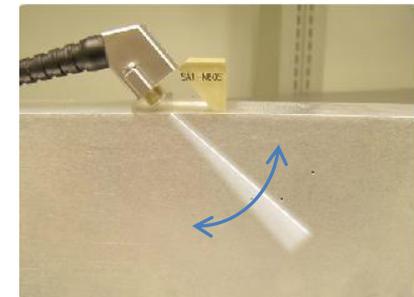
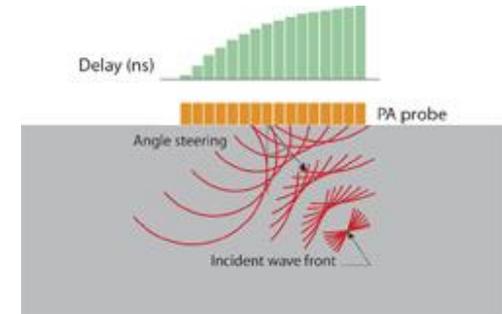


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## Matec Immersion/Bubbler Scanning System



- Phased array transducers contain between 10 and 256 piezoelectric elements that can be individually pulsed
- By pulsing the elements at slightly different times, the ultrasonic waves produced by each element will combine through constructive and destructive interference to form a sound beam at a specified angle and focus depth
- Electronic beam steering makes it possible to sweep the sound through a range of angles or along a linear path
  - Increases the volume of material inspected from a single transducer position
  - Increases the chances that a flaw will be intersected by a beam at the optimum angle for detection
- Electronic focusing increases the chances of detecting smaller flaws at a greater range of depths
- Data is typically displayed as a 2-D cross-sectional view with signal amplitude plotted as a function of beam angle, depth in the part and distance from the front edge of the transducer (S-Scan)

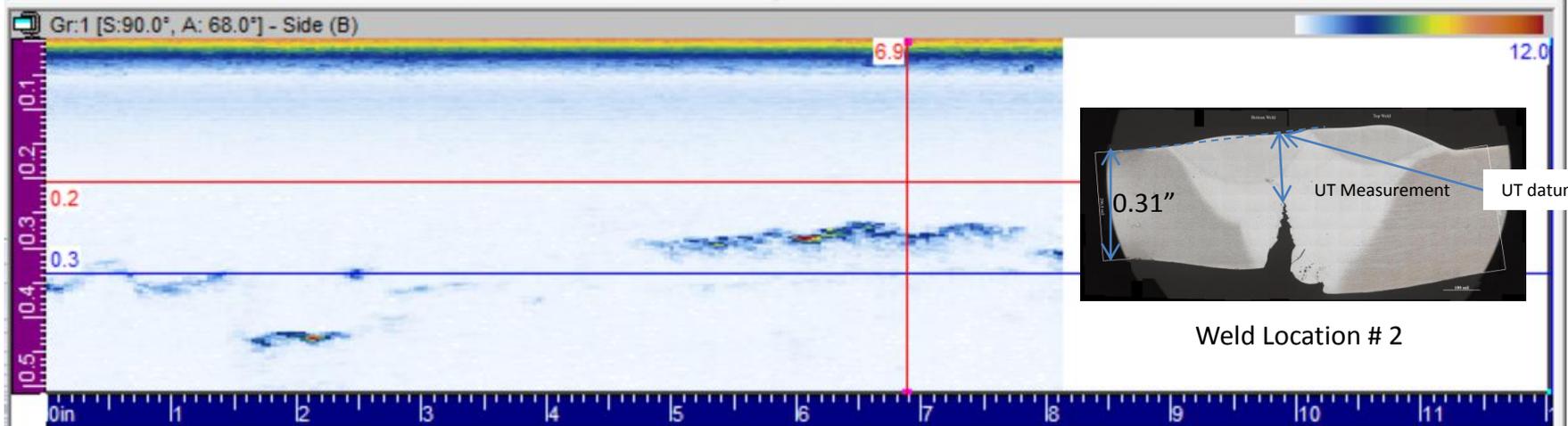
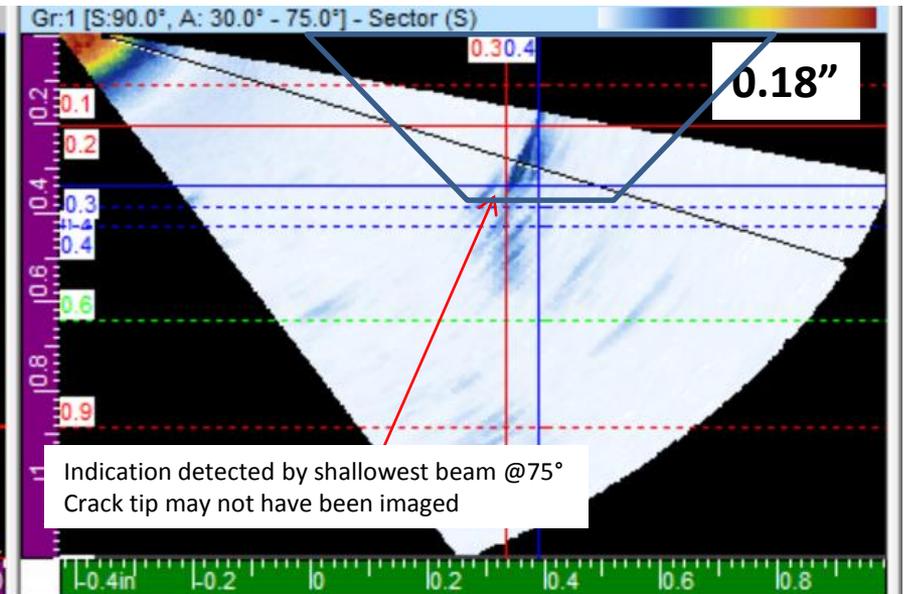
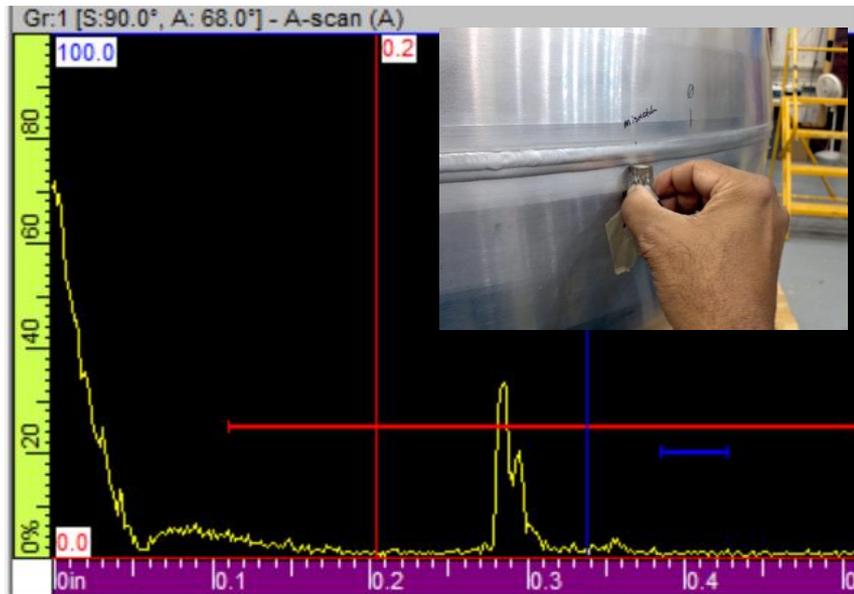




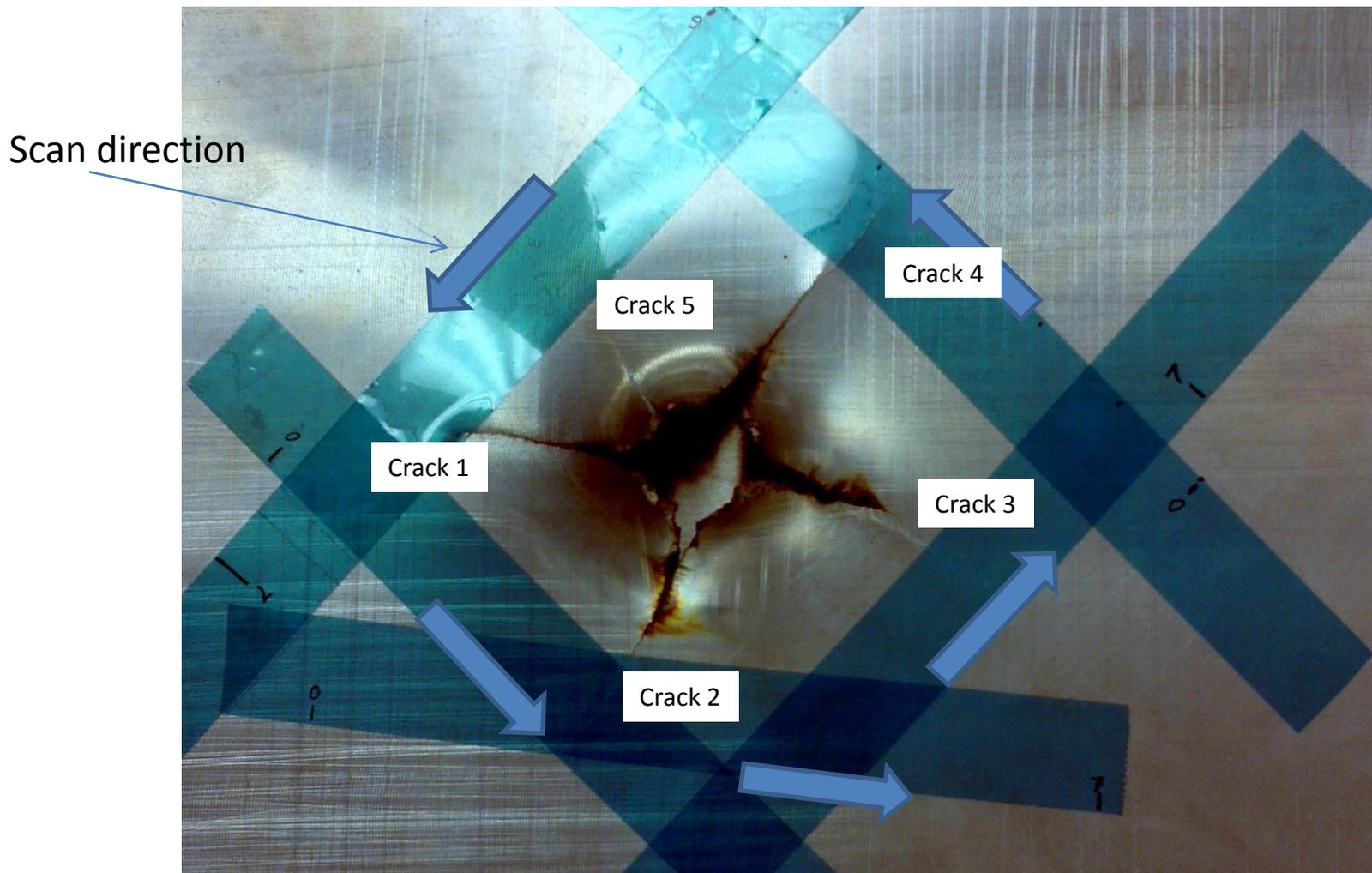
# Phased Array Inspection of Girth Weld



## Nondestructive Evaluation Laboratory



# Scan Path Markings on the Part Surface





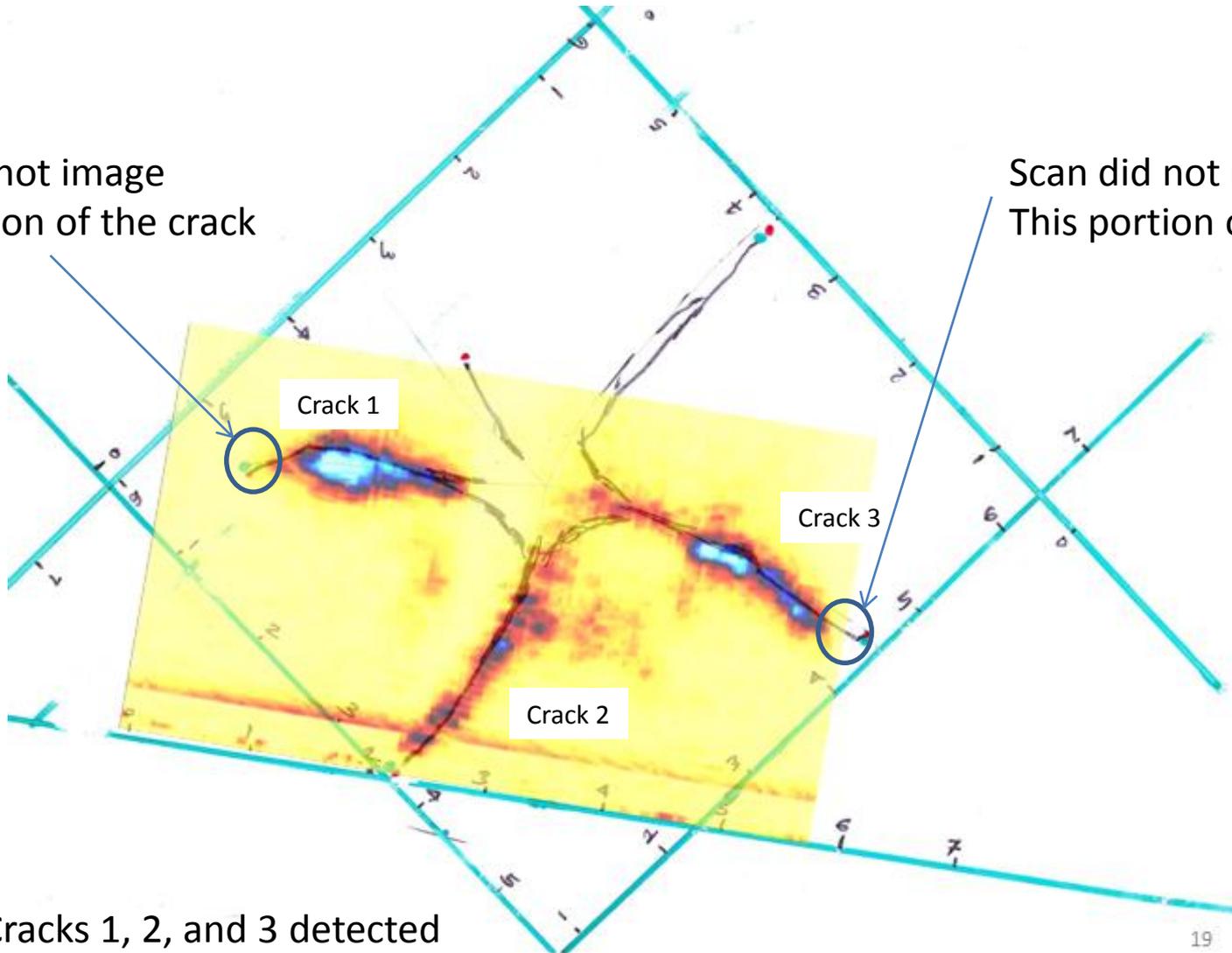
# Superimposed on Hand Trace of Cracks on Ultrasonic Phased Array Testing Results



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Scan did not image  
This portion of the crack

Scan did not image  
This portion of the crack



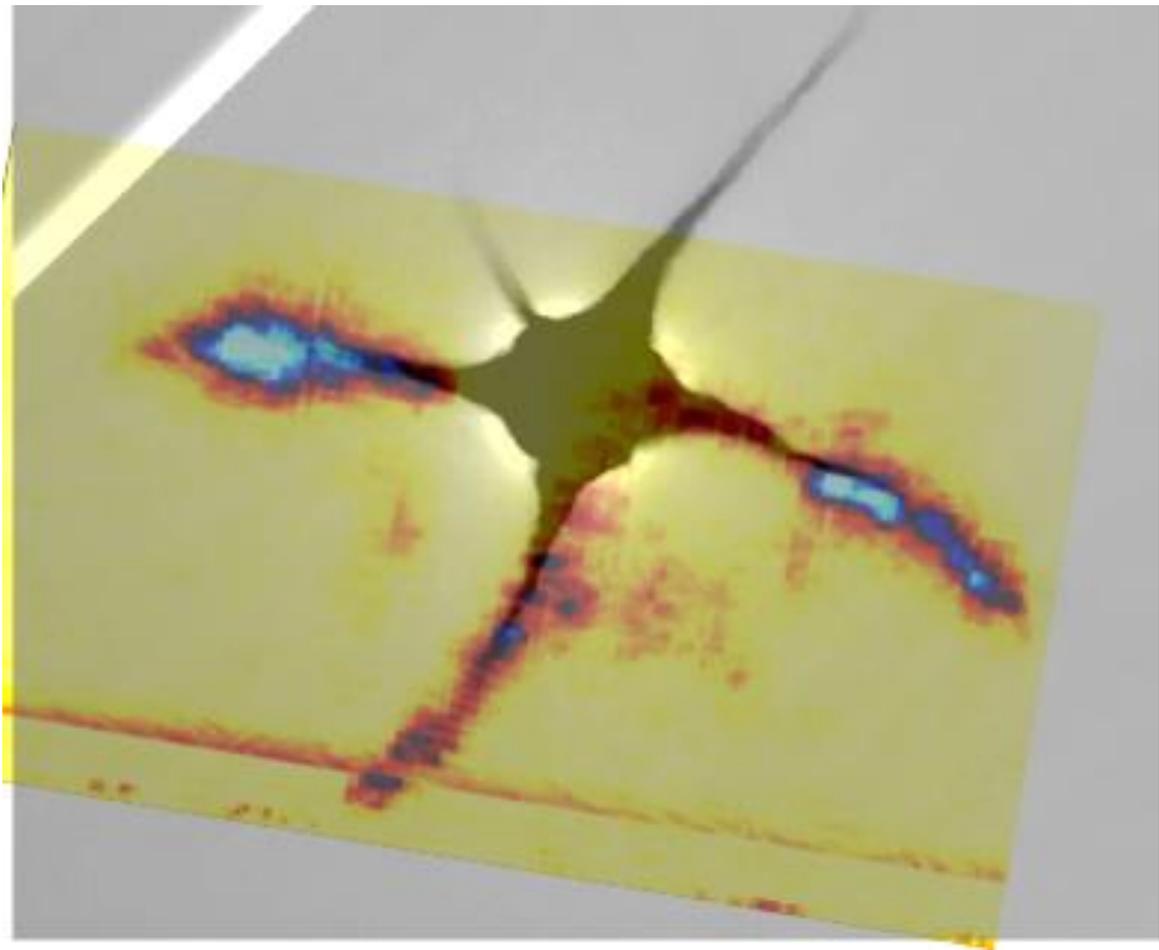
Cracks 1, 2, and 3 detected



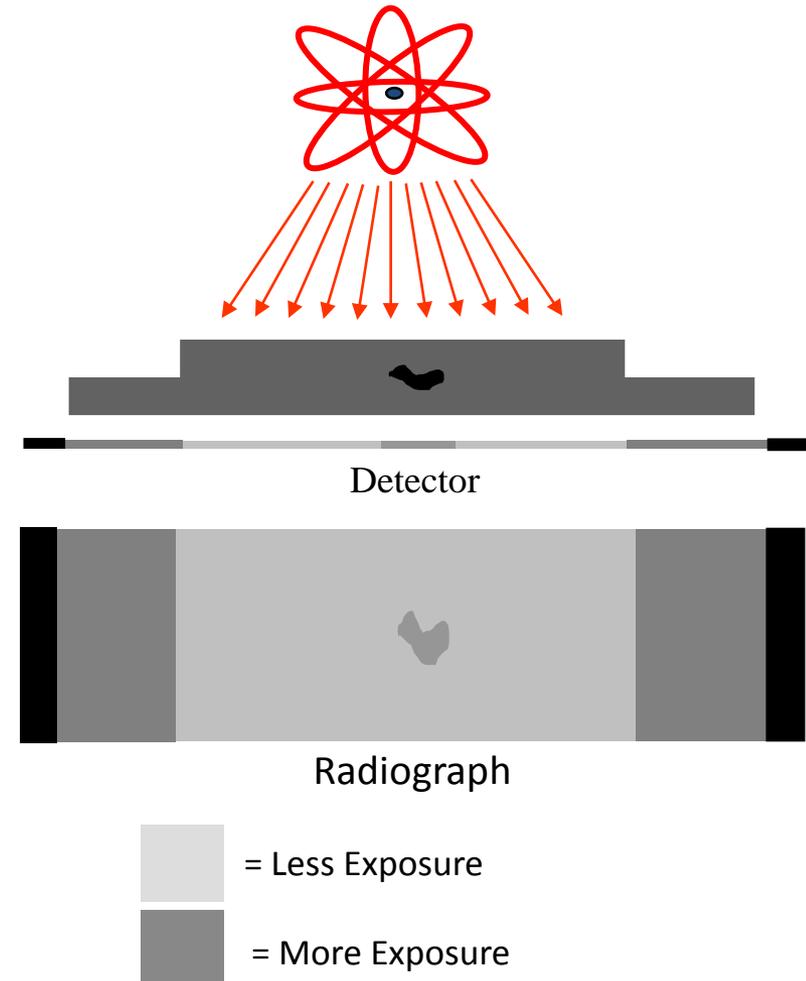
# Ultrasonic Phased Array Testing Results Superimposed on Digital X-ray



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- Used for detection of subsurface flaws, assembly verification and FOD detection
- Applicable to most materials
- Ideal for detecting three dimensional (volumetric) flaws such as porosity, voids, high and low density inclusions
- Considered a poor method for fatigue crack detection (crack must be aligned with the radiation beam)
- Utilizes penetrating radiation (X-rays,  $\Gamma$ -rays, neutrons) to expose discontinuities in materials
- Requires access to both sides of the part for radiation source and detector placement
  - X-ray backscatter is an exception
- There are a variety of detector options: film, phosphor plates (CR), flat panel DR detectors - amorphous silicon & amorphous selenium, and CMOS

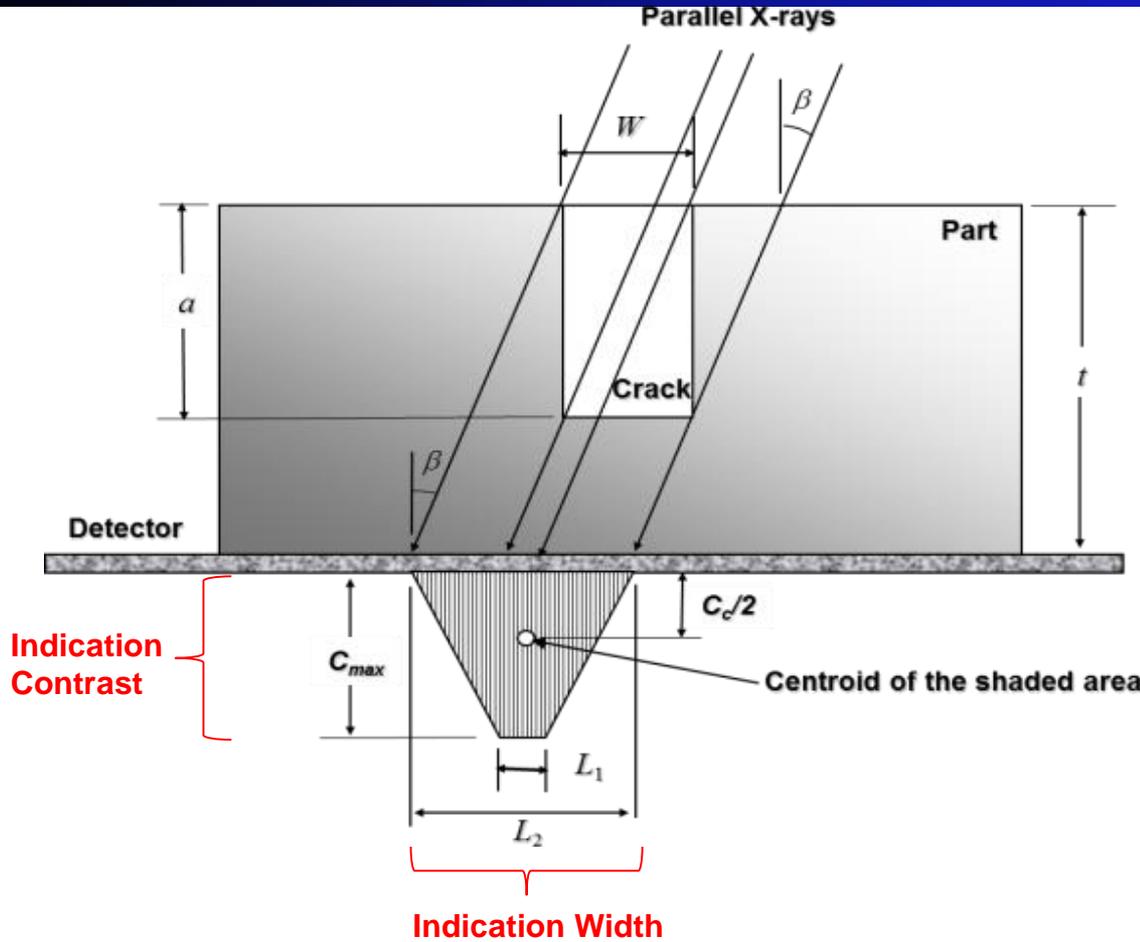




# Cross Sectional Geometry of Part, Slot, and X-ray Shadow Profile on the Detector



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Visual detection of a fine flaw like a crack is based on contrast magnitude

The rectangular cross sectional area of the crack is mapped as a trapezoidal area

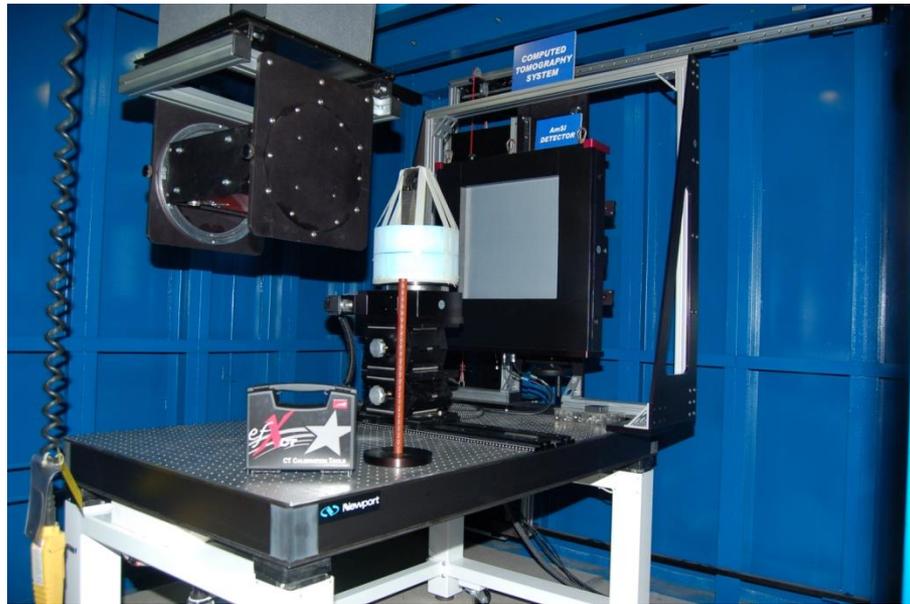
Cross Sectional Geometry of Part, Slot, and X-ray Shadow Profile on the Detector



# Computed Tomography/Digital Radiography



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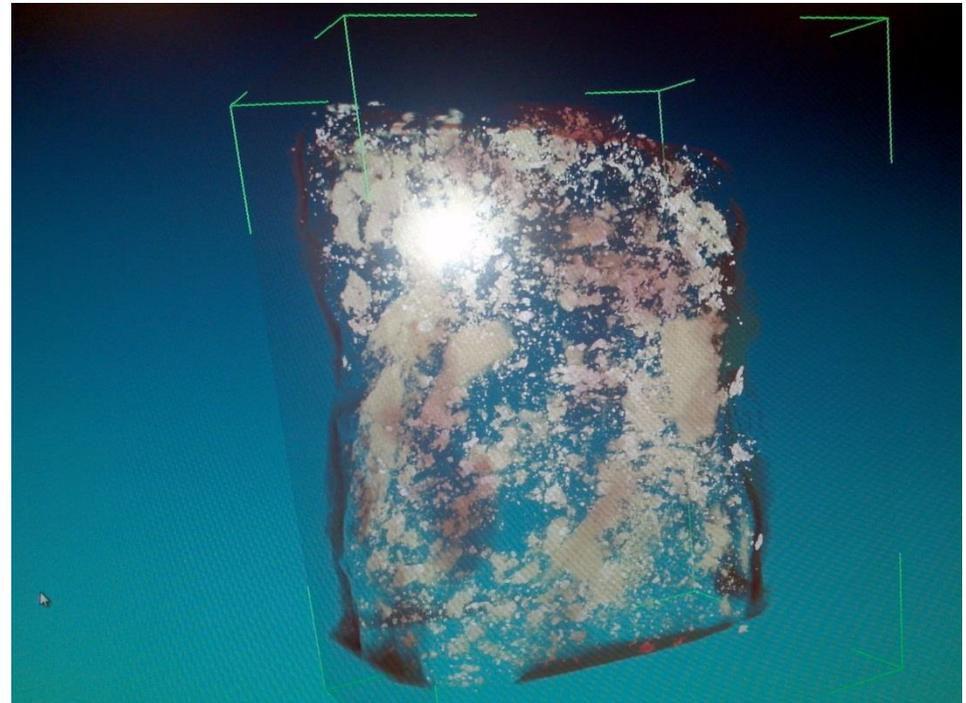
# X-ray Computed Tomography of Rock



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X-ray CT Image



The Critical Role of High Resolution X-ray Micro-computed Tomography for Ultra-thin Wall Space Component Characterization, D. J. Roth, R. W. Rauser, R.R. Bowman, R.E. Martin, A. M. Koshti, and D. S. Morgan, *Materials Evaluation*, March 2014, page 383.



# X-ray Computed Tomography of Li-Ion Battery



*Nondestructive Evaluation Laboratory*

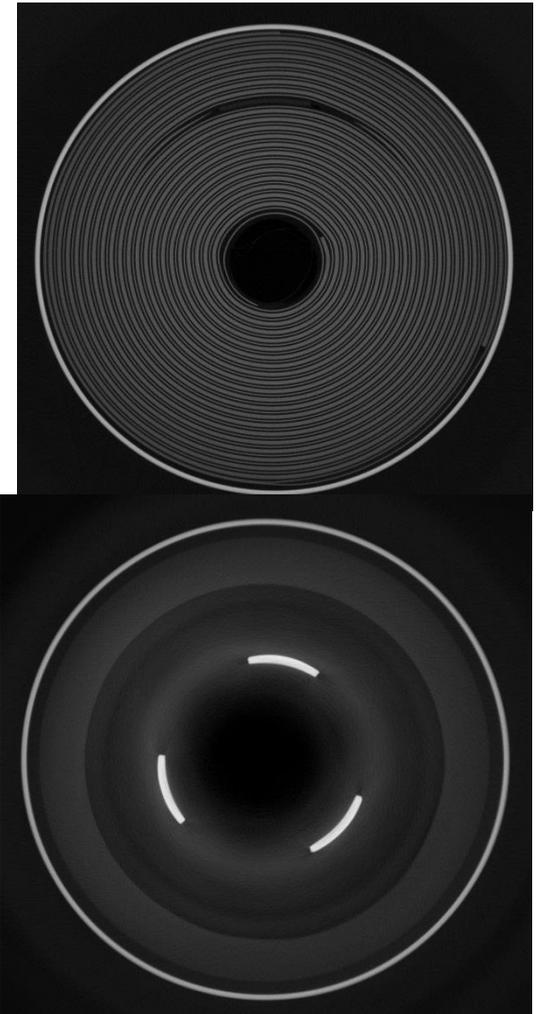
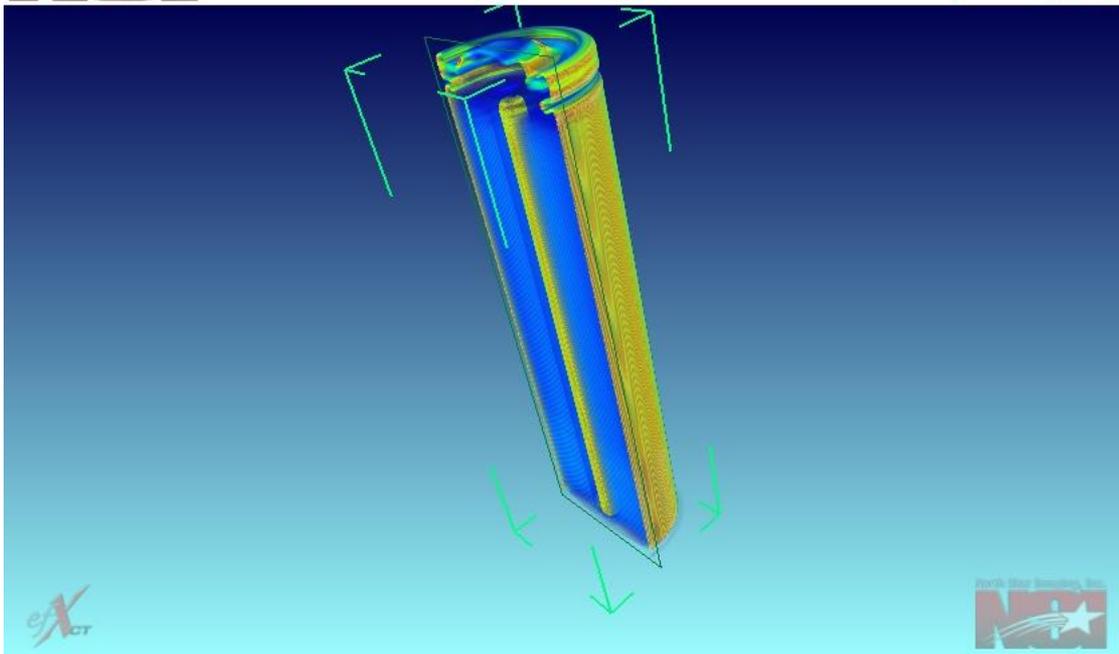


NORTH STAR IMAGING, INC.

[www.4nsi.com](http://www.4nsi.com)

800-635-8392

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# Additional Methods

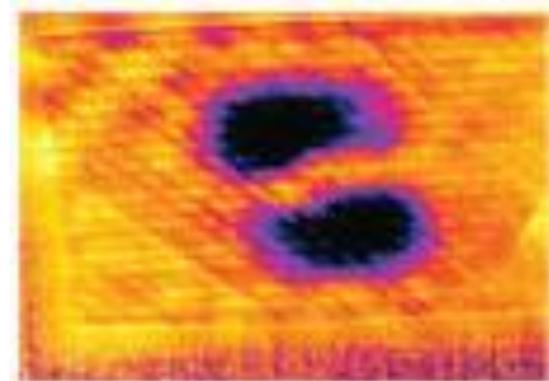
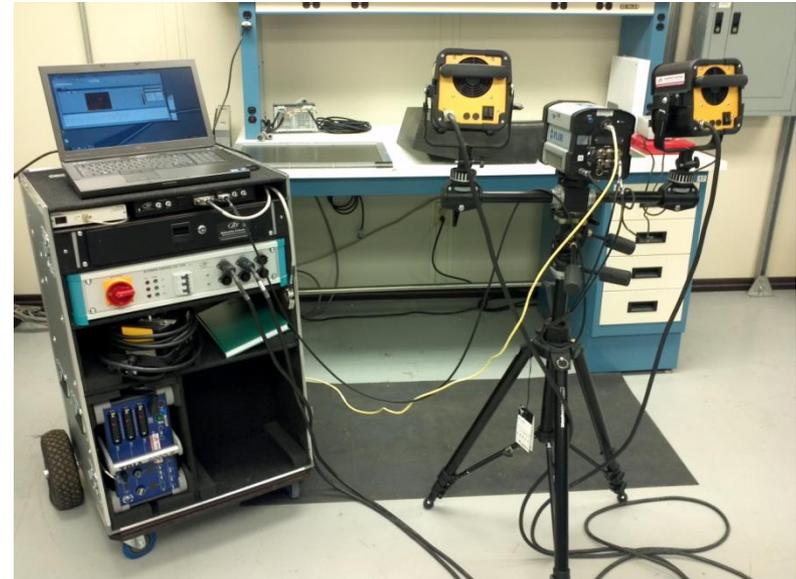


*Nondestructive Evaluation Laboratory*

- Infrared Thermography
- Laser Shearography
- Optical 3D Deformation Analysis (Aramis)
- High Speed Video
- X-ray Fluorescence (XRF) Spectrometer

### MoviTherm Composite-Check IRT System

- Used for detection of subsurface flaws in composites and bonded structures
- Heat is applied to the surface of a part and an infrared camera is used to record changes in the surface temperature (irradiance)
- The surface temperature is affected by internal flaws such as disbonds, voids and inclusions which obstruct the flow (conduction) of heat through the part
- The obstructed heat flow is observable as a hot or cold spot on the part surface
- A number of heat sources are used for camera side or backside heating: flash lamps, heat lamps, heat guns, vibration, electromagnetic inductance





# Space Shuttle Orbiter Flash IR Inspection



## *Nondestructive Evaluation Laboratory*

RCC Panel IR Inspection at JSC



Orbiter RCC inspection in Orbiter Possessing Facility at KSC



Flash IR Hood attached to Strong Arm that is attached to a cart on rails. Worked as a project engineer to develop and implement IR thermography Inspection of Orbiter wing leading edge at Kennedy Space Center

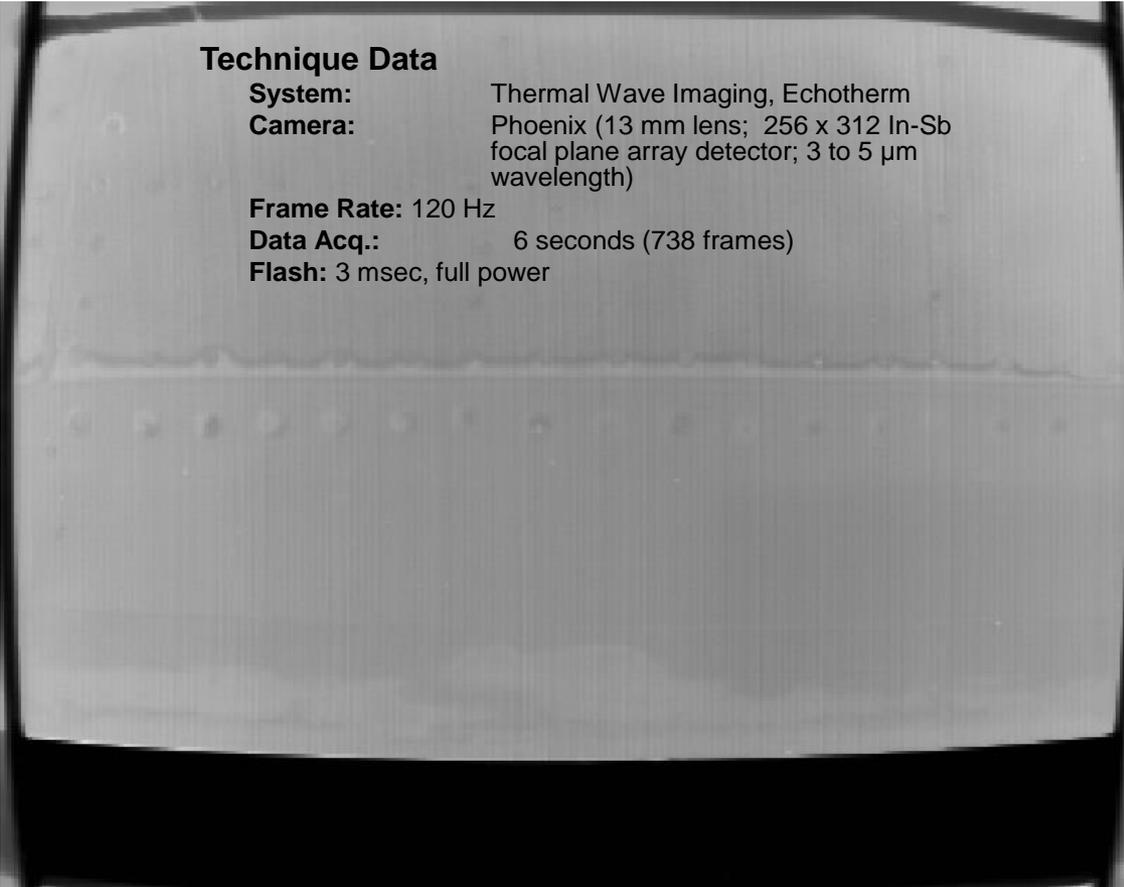
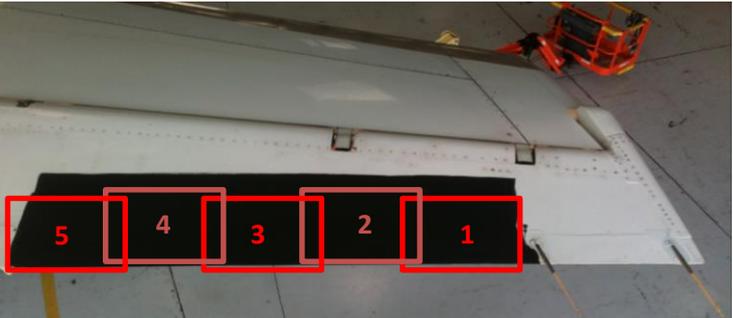


# Infrared Thermography



## Nondestructive Evaluation Laboratory

### Flash Thermography of the DC-9 Elevator Closeout Panel (Upper Side Shot 5)

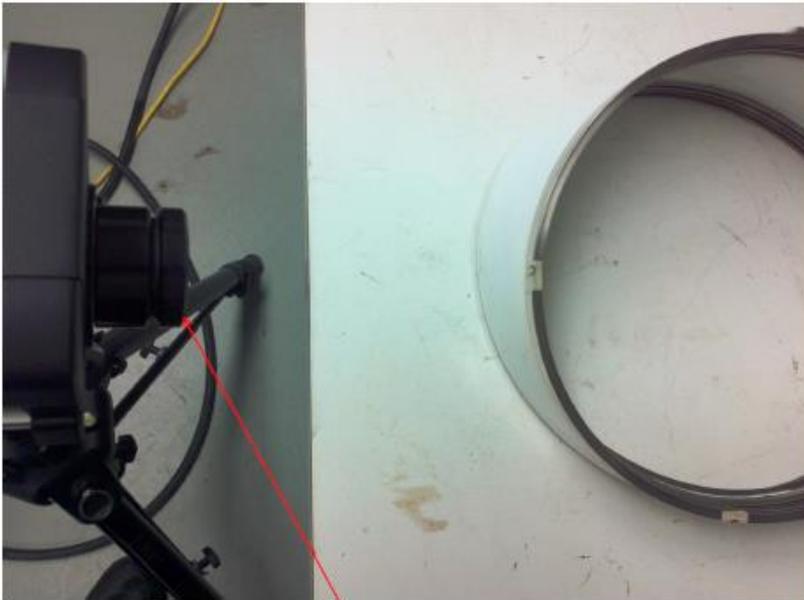




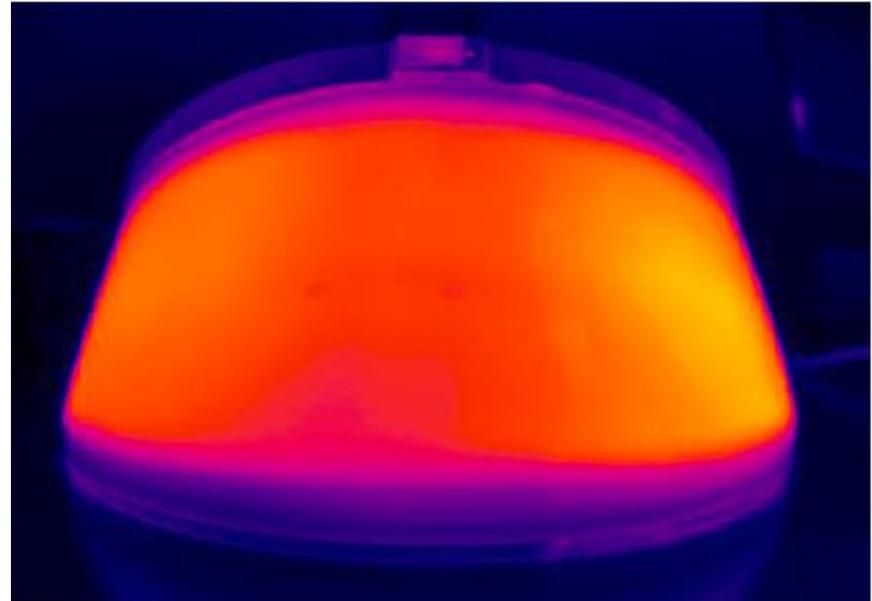
# Infrared Inspection of Mark III Spacesuit Link



*Nondestructive Evaluation Laboratory*



IR camera





# MoviTherm System: Inspecting T-38 Door Panel

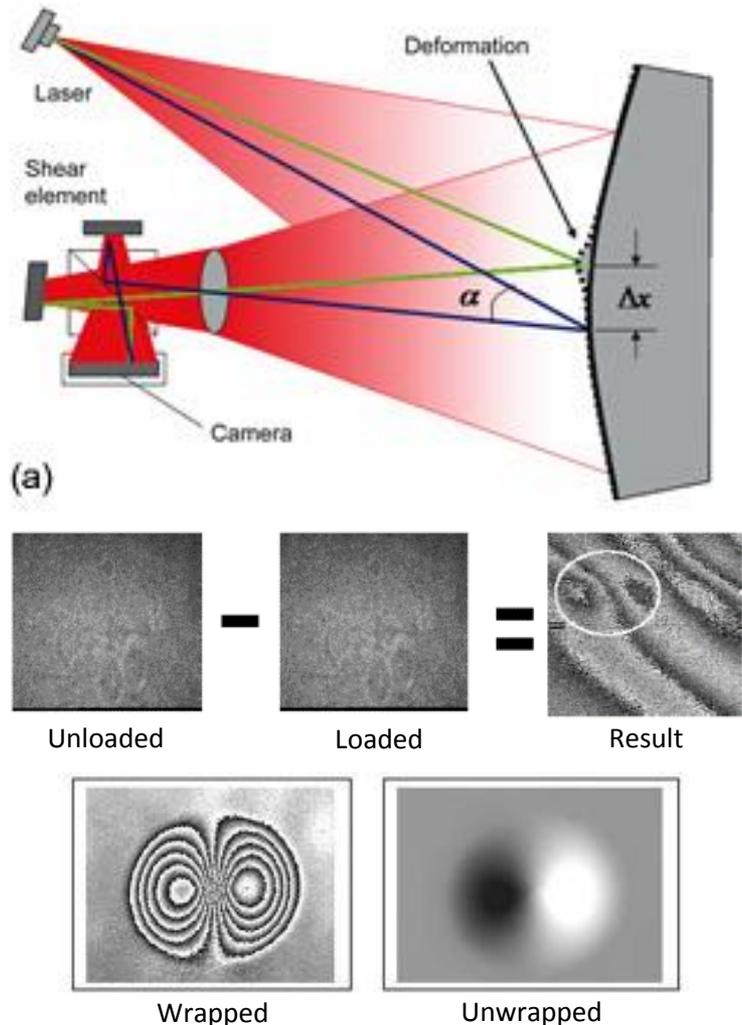


*Nondestructive Evaluation Laboratory*





- Used for detection of subsurface flaws in composites and bonded structures:
  - Disbonds
  - Delaminations
  - Porosity
  - Foreign objects
  - Impact damage
- Basic Principle
  - An unloaded part is illuminated with a laser producing a speckle pattern which is captured by a digital camera
  - Before the image reaches the camera, it is doubled, laterally sheared (shifted) and superposed creating a double image of the part (shearogram)
  - The part is then loaded and a second shearogram is generated
  - The two shearograms are then subtracted to create an image showing the first derivative of any out-of-plane surface deformation (“butterfly” fringe pattern) due to the presence of a flaw



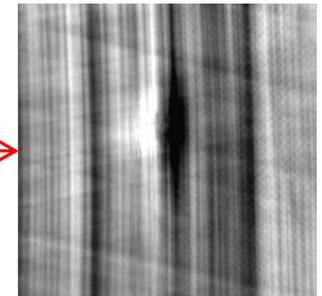
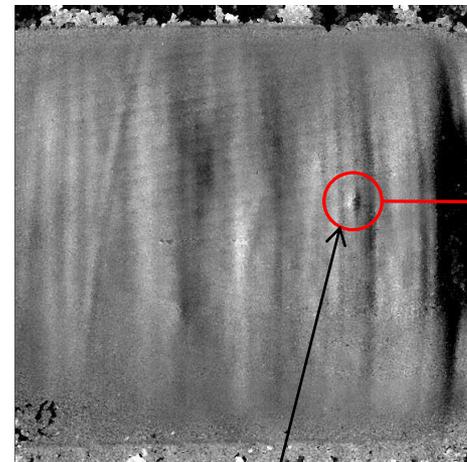


# Laser Shearography: Inspection of Linerless Composite Tank



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Inspection of a Microcosm Linerless Composite Tank at WSTF  
using the Laser Technology Inc. Shearography System



Suspect anomaly



# Optical 3D Deformation Analysis



## Nondestructive Evaluation Laboratory

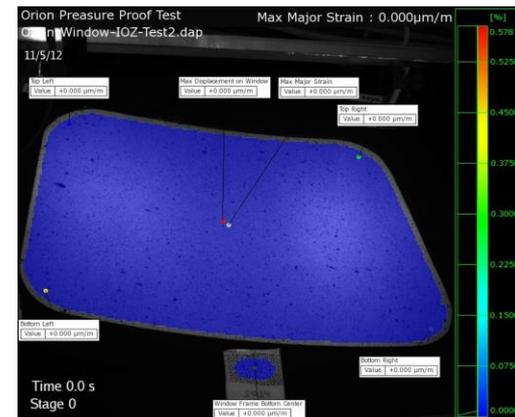
### Orion Window Proof Pressure Test

#### ARAMIS

ARAMIS is a non-contact optical 3D measuring system capable of analyzing, calculating and documenting deformations. ARAMIS is suitable for three-dimensional deformation measurements under static and dynamic loads.

#### Fields of Application

- Material testing
- Strength assessment
- Component dimensioning
- Examination of non-linear behavior
- Characterization of creep and aging processes
- Determination of Forming Limit Curves (FLC)
- Verification of FE models
- Determination of material characteristics
- Analysis of the behavior of homogeneous and inhomogeneous materials during deformation
- Strain computation





# High Speed Video



## Nondestructive Evaluation Laboratory

### Phantom Cameras

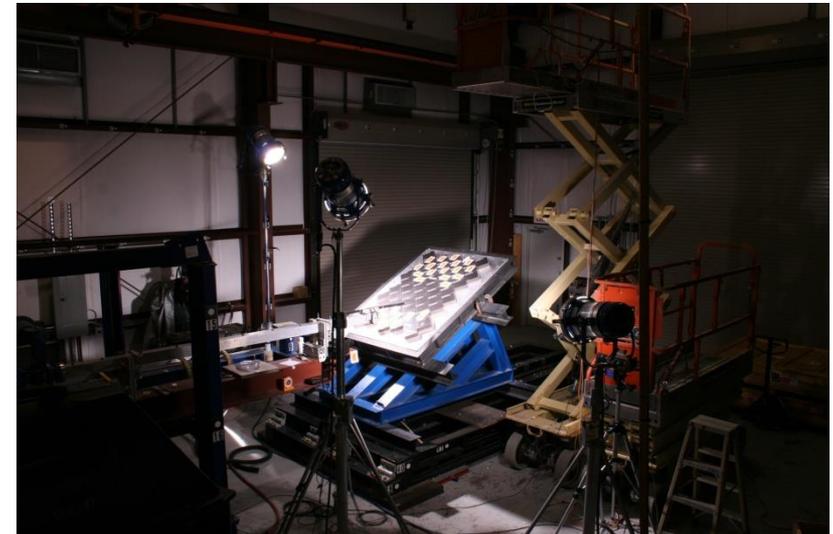
Phantom cameras are high speed digital video cameras capable of recording events at high frame rate. At full resolution of 800 x 600 pixels, the Phantom camera can reach rates of 4800 frames per seconds. For events that requires faster frame rate we can sacrifice resolution for speed. At a 256 x 256 pixels the frame rate can reach 27,000 frames per seconds.

### SwRI Impact Test

Target: Shuttle Tile Array

Projectile: Foam

Velocities: 400 to 1,000 ft/sec





# XRF Spectrometer



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- Oxford Instruments handheld X-MET5100 energy dispersive X-ray fluorescence spectrometer
- Rapid in-situ chemical analysis of aluminum, titanium, copper, nickel and ferrous alloys
- Spectrum and tabular analysis displays
- Tabular display gives percent concentration of each element and alloy grade
- Emits X-ray radiation; users must take radiation safety training, be approved by the RSO, and wear a dosimeter ring badge





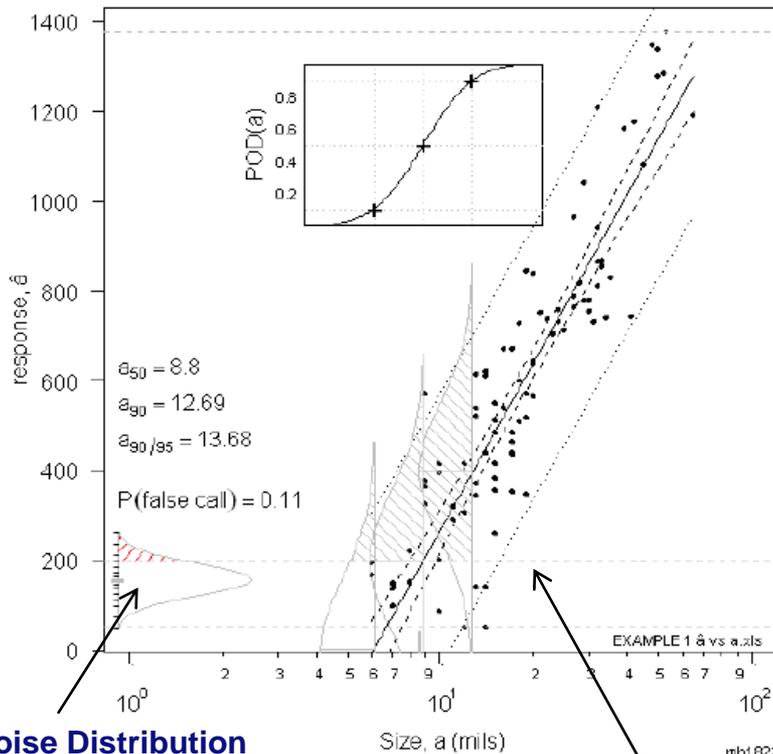
# Signal Response POD Analysis per MIL-HDBK-1823



## Nondestructive Evaluation Laboratory

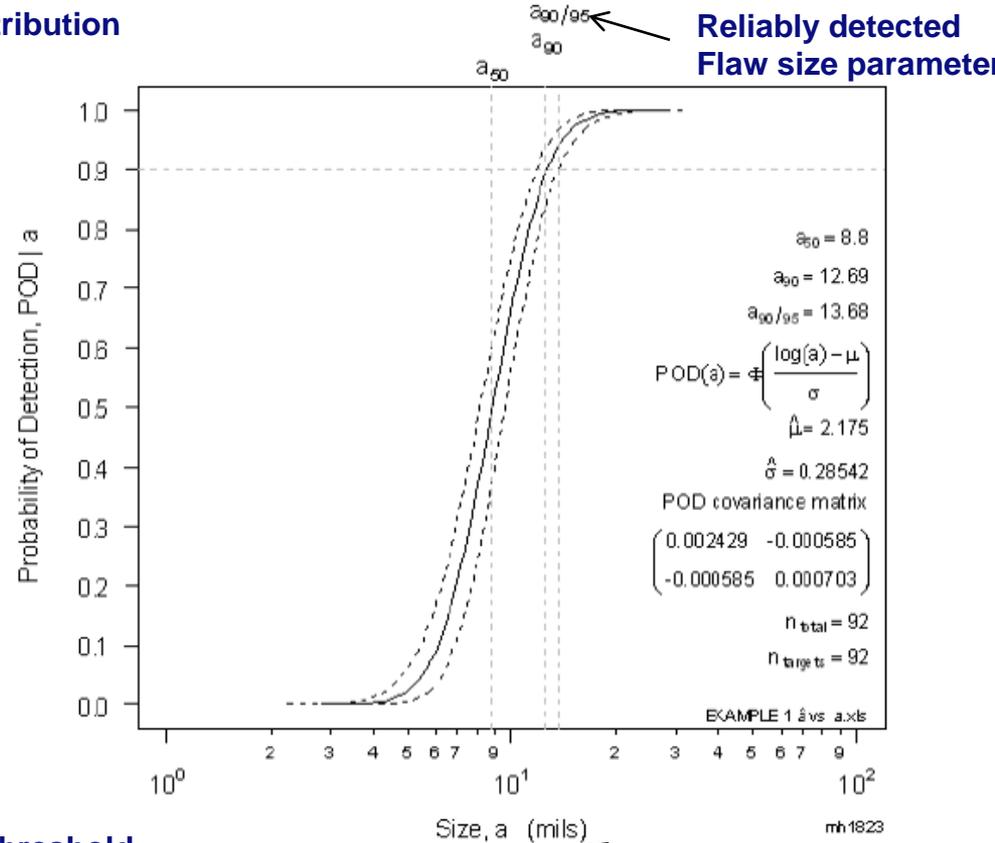
Plot of Experimental Data with 90% Data Bounds, Linear Model with 95% Confidence Bounds, and Noise Distribution

POD Curve with 95% Confidence Bounds.



Noise Distribution

Detection Threshold



Reliably detected  
Flaw size parameter

Flaw Size  
Parameter

See following paper for example of POD analysis.

The Critical Role of High Resolution X-ray Micro-computed Tomography for Ultra-thin Wall Space Component Characterization, D. J. Roth, R. W. Rauser, R.R. Bowman, R.E. Martin, A. M. Koshti, and D. S. Morgan, Materials Evaluation, March 2014, page 383.



# Standard NDE 90/95 Crack Sizes



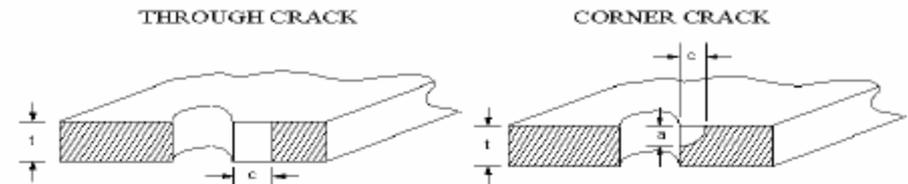
## Nondestructive Evaluation Laboratory

### U. S. CUSTOMARY UNITS (inches)

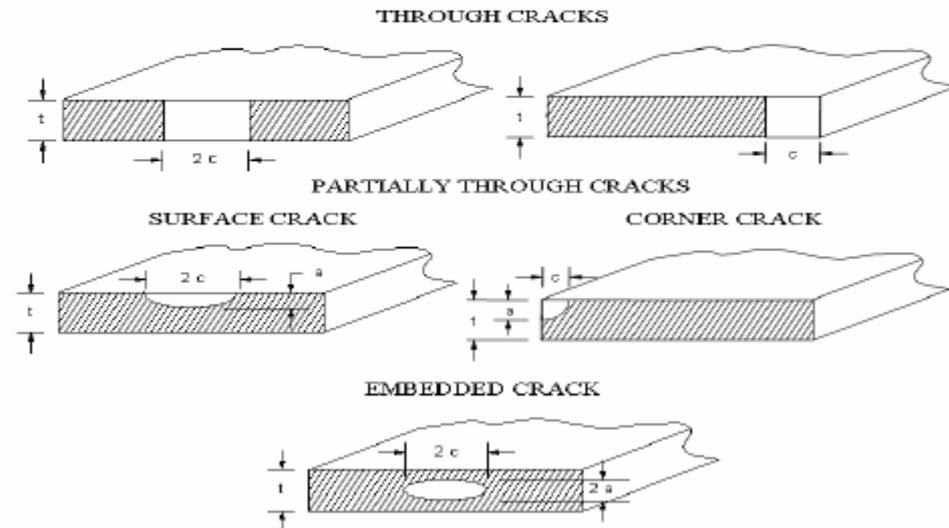
Crack Location	Part Thickness, $t$	Crack Type	Crack Dimension, $a^{\pm}$	Crack Dimension, $c^{\pm}$
<u>Eddy Current NDE</u>				
Open Surface	$t \leq 0.050$	Through PTC <sup>1</sup>	$t$	0.050
	$t > 0.050$		0.020 0.050	0.100 0.050
Edge or Hole	$t \leq 0.075$	Through Corner	$t$	0.100
	$t > 0.075$		0.075	0.075
<u>Penetrant NDE</u>				
Open Surface	$t \leq 0.050$	Through PTC	$t$	0.100
	$0.050 < t < 0.075$		$t$	$0.150 - t$
	$t > 0.075$		0.025 0.075	0.125 0.075
Edge or Hole	$t \leq 0.100$	Through Corner	$t$	0.150
	$t > 0.100$		0.100	0.150
<u>Magnetic Particle NDE</u>				
Open Surface	$t \leq 0.075$	Through PTC	$t$	0.125
	$t > 0.075$		0.038 0.075	0.188 0.125
Edge or Hole	$t \leq 0.075$	Through Corner	$t$	0.250
	$t > 0.075$		0.075	0.250
<u>Radiographic NDE</u>				
Open Surface	$t \leq 0.107$ $t > 0.107$	PTC	$0.7t$	0.075
		PTC	$0.7t$	0.7t
		Embedded	$2a=0.7t$	0.7t
<u>Ultrasonic NDE</u>				
Comparable to a Class A Quality Level (ASTM-E-2375)				
Open Surface	$t \geq 0.100$	PTC	0.030	0.150
			0.065	0.065
		Embedded**	0.017	0.087
			0.039	0.039

Taken from NASA-STD-5009

### GEOMETRIES FOR CRACKS AT HOLES



### GEOMETRIES FOR CRACKS NOT AT HOLES



<sup>1</sup> PTC - Partly through crack (Surface Crack)

\* See figure 1 for definitions of "a" and "c" for different geometries.

\*\* Equivalent area is acceptable, ASTM-E-2375 Class A.



# Method Selection Factors



## *Nondestructive Evaluation Laboratory*

- Each NDE method and technique has its advantages and disadvantages
  - No one method or technique will work for every application
- In fact, two or more complementary methods are often required to ensure a complete inspection
  - For example, critical welds require:
    - Visual inspection to verify weld size and geometry
    - Penetrant inspection for surface flaws (cracks and porosity)
    - Radiographic inspection for subsurface flaws (lack of fusion, lack of penetration, inclusions, porosity and slag)
- Selection of the best method or combination of methods requires a clear understanding of the inspection problem and careful consideration of a number of technical and nontechnical factors
- Ultimately, the chosen method must be validated against standards containing real or simulated flaws
  - Depending on the requirements, validation may require evaluation of the probability of detection (POD) for a specified flaw size



# Method Selection Factors



## *Nondestructive Evaluation Laboratory*

- When a method is not specified by a requirements document, method selection is based on the following factors:
  - Material
    - Metal, nonmetal or composite
    - Homogeneous or heterogeneous
    - Conductive or nonconductive
    - Magnetic or nonmagnetic
  - Fabrication Method
    - Rolled, forged, cast, extruded, powder metallurgy, injection molded
    - Heat treatment, grain size
    - Welded, brazed, bonded
  - Origin and Type of Flaw
    - Manufacturing or in-service
    - Surface or subsurface
    - Planar or volumetric
  - Flaw Location and Orientation
    - Near surface or far surface
    - Parallel or perpendicular to the part surface
    - Direction of maximum stress
  - Flaw Size
    - What size flaw can we safely miss? (Not, how small can we find?)



# Method Selection Factors



## *Nondestructive Evaluation Laboratory*

- Part thickness, size and geometry
- Surface condition
  - Smooth or rough
  - Porous or nonporous
  - Plated, coated or bare
  - As welded or machined flush
- Accessibility
  - In-place or disassembled
  - One sided or two sided
  - Direct or indirect access
- Part Criticality
  - Critical or noncritical
  - High or low stress
- Permanent Inspection Record or Pass/Fail
- Type of equipment available
- Availability of Trained and Certified Personnel
- Time Available
- Cost



# Online Resources



## *Nondestructive Evaluation Laboratory*

- The NDT Resource Center website (<http://www.ndt-ed.org/EducationResources/CommunityCollege/communitycollege.htm>) offers online training courses in:
  - Penetrant Testing
  - Magnetic Particle Testing
  - Eddy Current Testing
  - Ultrasonic Testing
  - Radiographic Testing
  - Acoustic Emission Testing
  - Infrared/Thermal Testing
  - Remote Field Testing
- The Olympus website (<http://www.olympus-ims.com/en/knowledge/>) offers training and application information on several methods, including phased array ultrasonic testing and eddy current array testing



# JSC NDE Team



## *Nondestructive Evaluation Laboratory*



1<sup>st</sup> from left: Ajay Koshti, 2<sup>nd</sup> from left: Ovidio Oliveras, Center: Norman Ruffino, 2<sup>nd</sup> from right: David Stanley, 1<sup>st</sup> from right: Michael Tipton . Morpheus in the background.