

The GMAO OSSE for Weather Analysis and Prediction Using the High-Resolution GEOS-5 Nature Run

Ronald Errico
Nikki Privé
David Carvalho

Goddard Earth Sciences Technology and Research Center
at Morgan State University
and
Global Modeling and Assimilation Office
at NASA Goddard Space Flight Center



Applications of OSSEs

1. Estimate effects of **proposed instruments** (and their competing designs) on analysis skill by exploiting simulated environment.
2. Evaluate present and **proposed techniques** for data assimilation by exploiting known truth.

Almost all OSSE validation and application metrics are concerned with how analysis accuracy or forecast skill are affected by the observations.

Therefore, OSSEs are about simulating observation errors and other system errors, not simply about simulating observations themselves.

$$\begin{aligned} O - F &= y^o - H(x^b) \\ &= e^o - e^b \end{aligned}$$

Uncommon Aspects of the GMAO OSSE Framework:

Sondes are advected by NR winds.

Radiances are (crudely) affected by clouds or precip.

AMVs are only where NR clouds can be distinguished.

GPSRO obs are produced using ROPP software.

Observation errors are correlated vertically, horizontally, and/or between channels.

Tuning of observation errors is mostly automated.

Validation includes obs impact estimates produced using GSI and model adjoints.

56K lines of software are extensively documented both internally and externally (140 pages).

Model for explicitly simulated observation errors

Schematically:

$$\epsilon(\lambda, \theta, z) = \epsilon_f \left[\sqrt{\nu(z)} \gamma(z) + \sqrt{1 - \nu(z)} \alpha(\lambda, \theta, z) \right]$$
$$\alpha(\lambda, \theta, z) = \sum_i s_i(\lambda, \theta) \phi_i(z)$$

ϵ_f is a scaling factor (generally 1)

ν is the the fraction of total variance ascribed to an uncorrelated part of the error

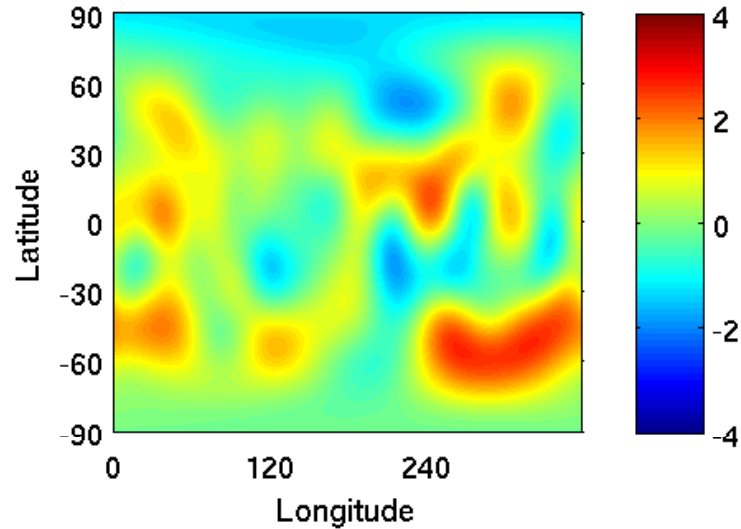
γ is a random number from a $N(0, V)$ distribution.

s_i are a set of random, homogeneous, isotropic, horizontally correlated, global, scalar or vector fields

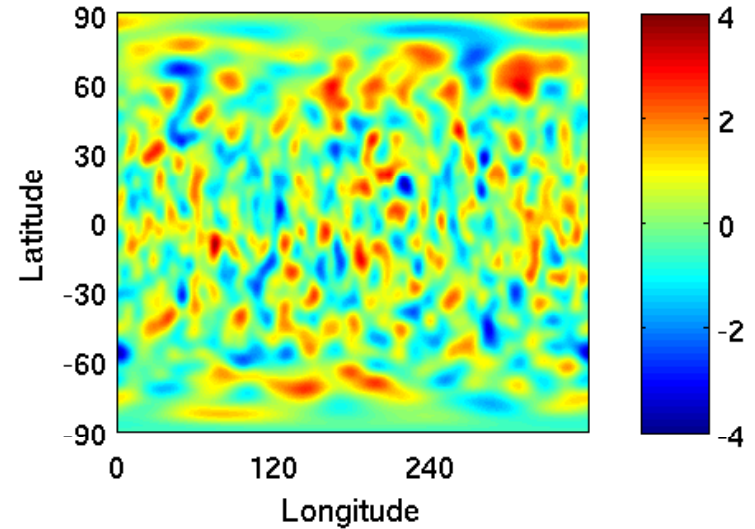
ϕ_i are PCs of a vertical or channel error covariance

Examples of random scalar fields

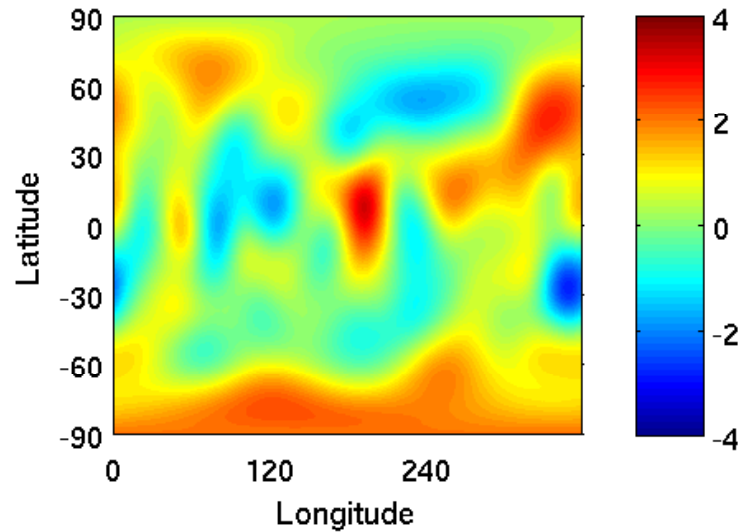
Scalar field (L=2000 km, realization 1)



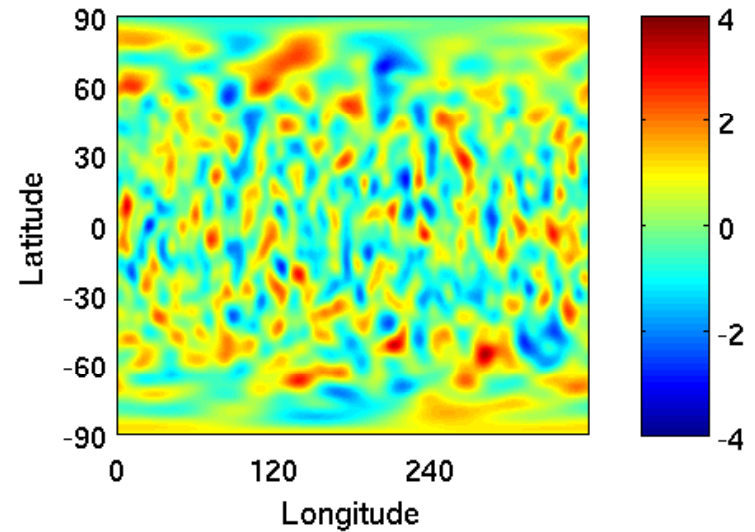
Scalar field (L=500 km, realization 1)



Scalar field (L=2000 km, realization 2)

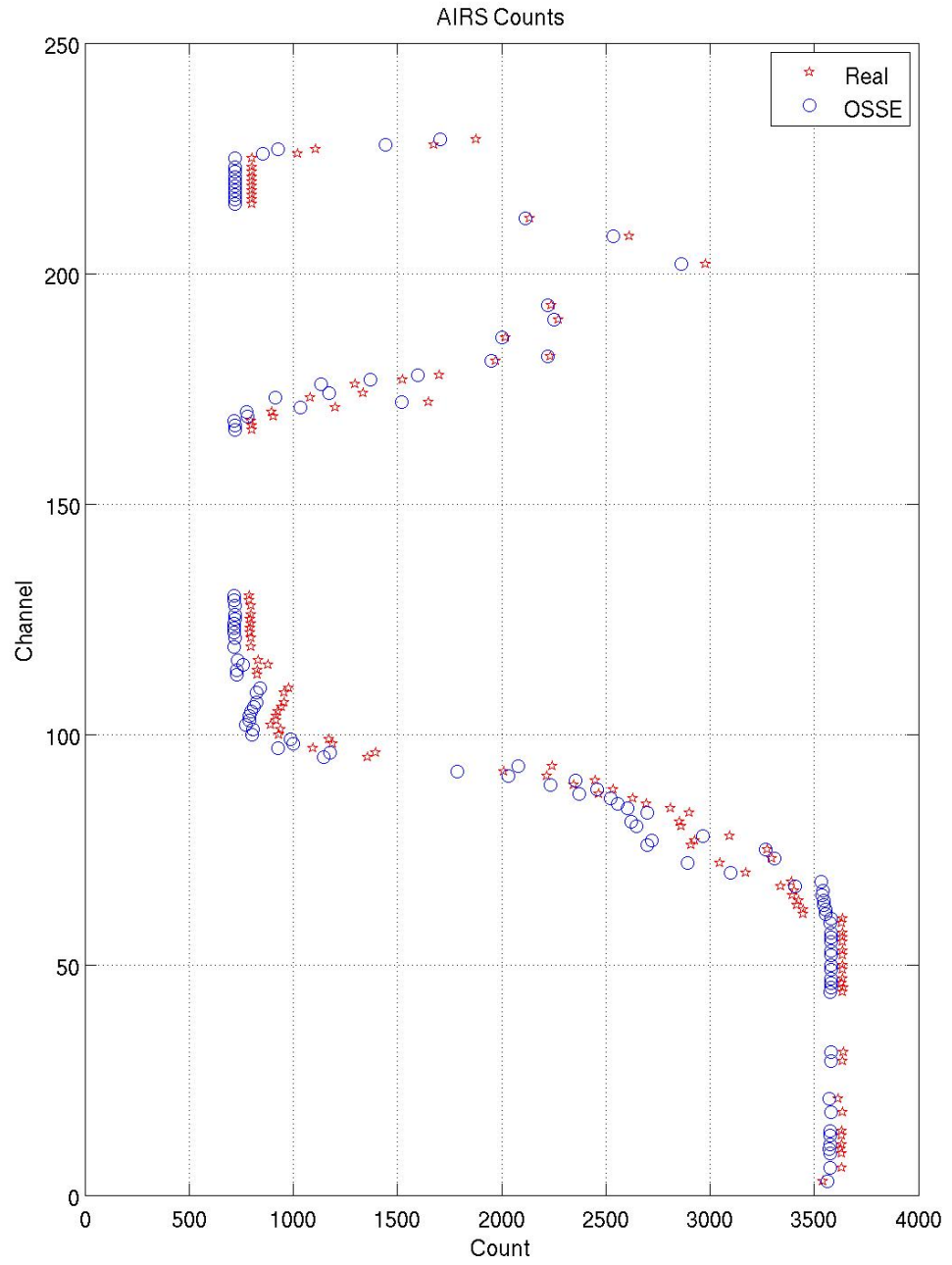


Scalar field (L=500 km, realization 2)



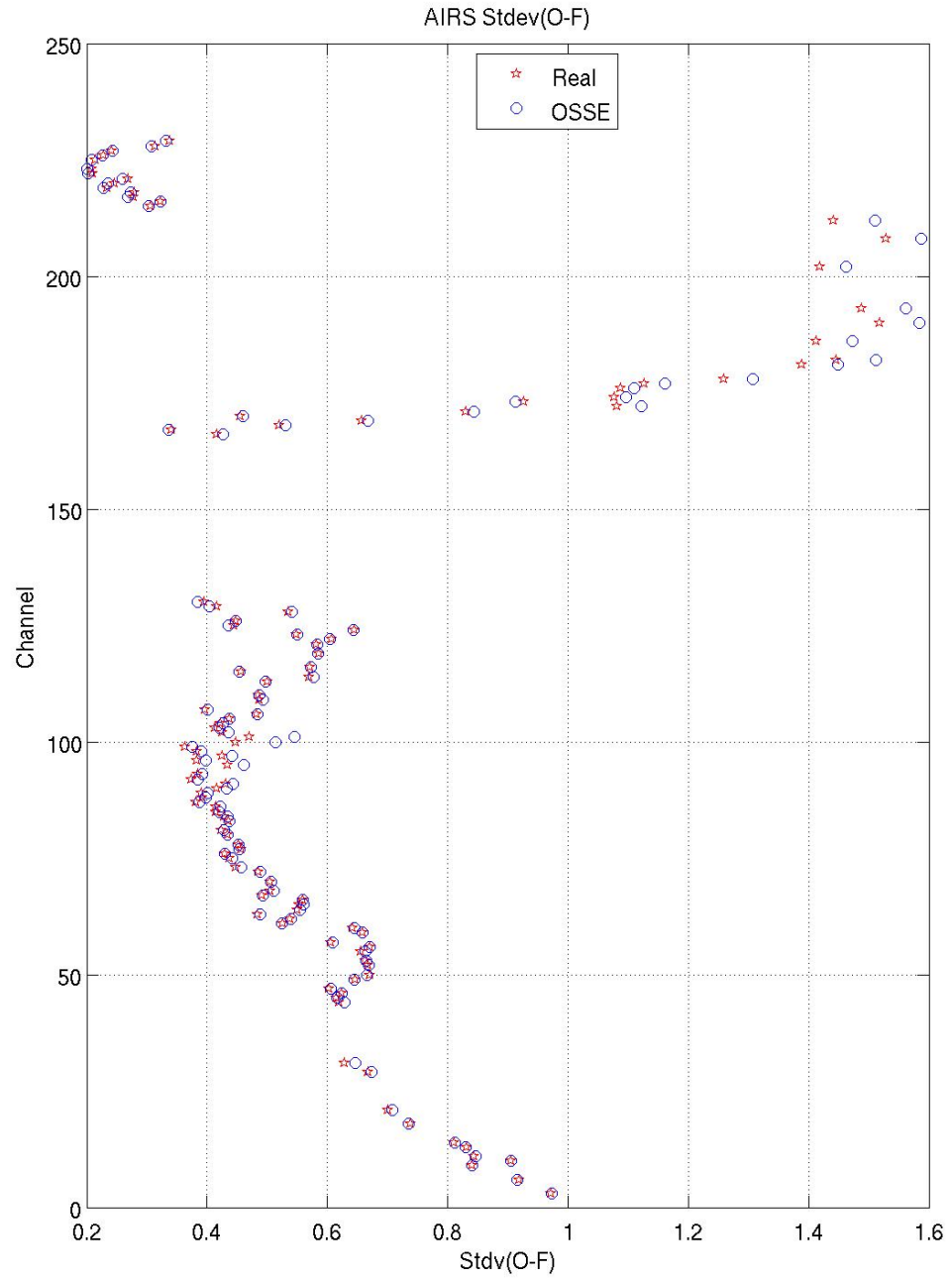
Mean counts per
6-hour assimilation window
for QC-accepted
AIRS channels

REAL stars OSSE circles



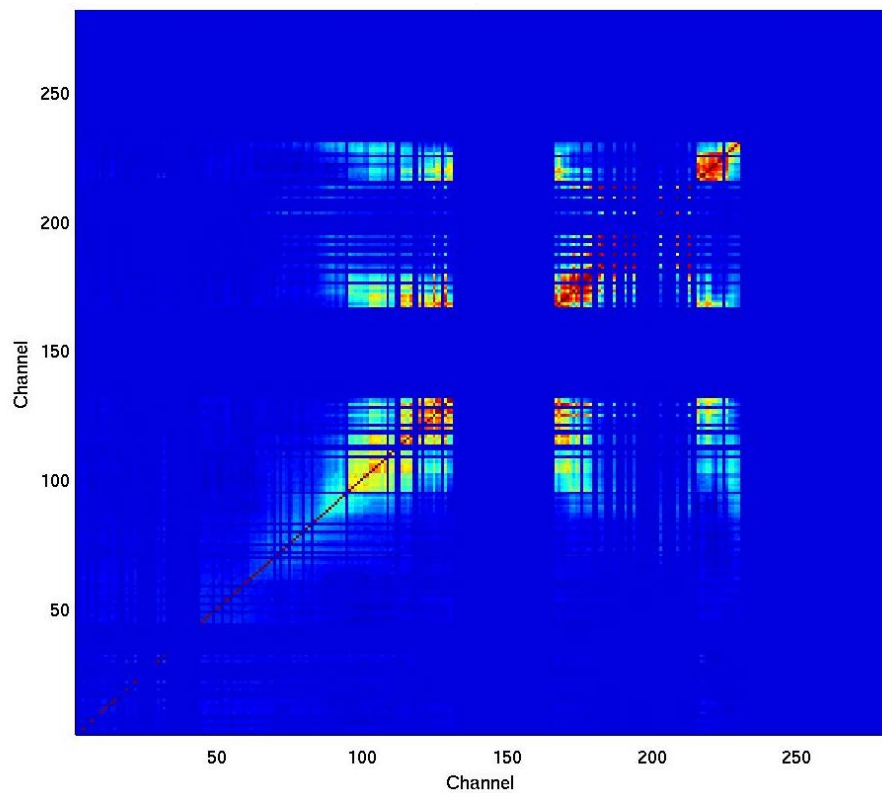
Standard Deviations of T_B
O-F for QC-accepted
AIRS channels

REAL stars OSSE circles

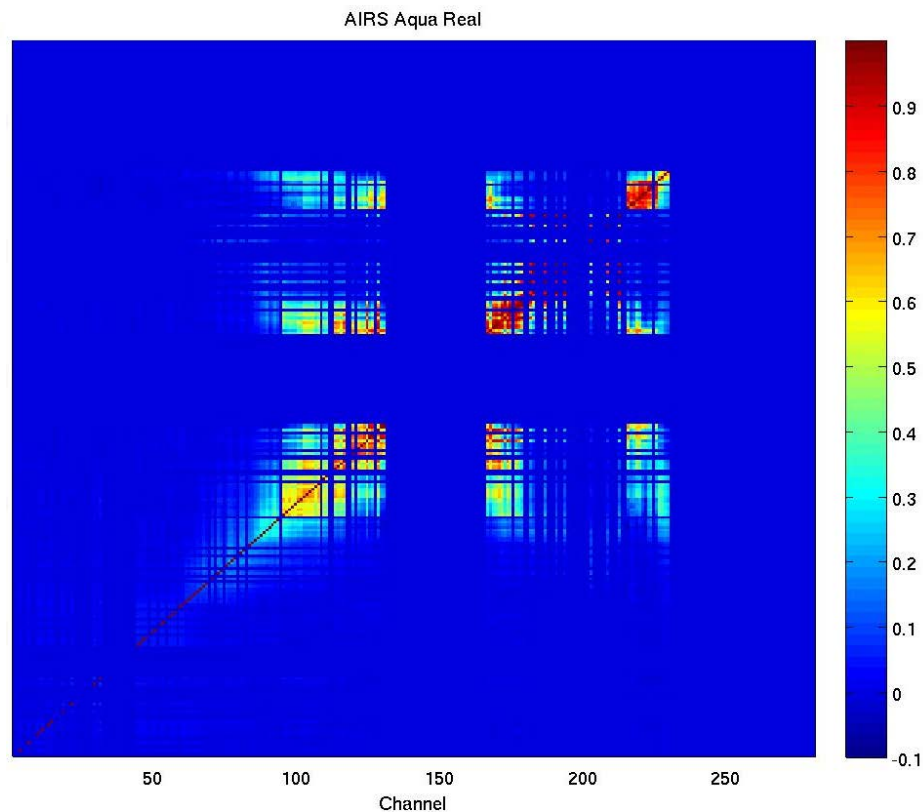


Inter-channel correlation of O-F for AIRS

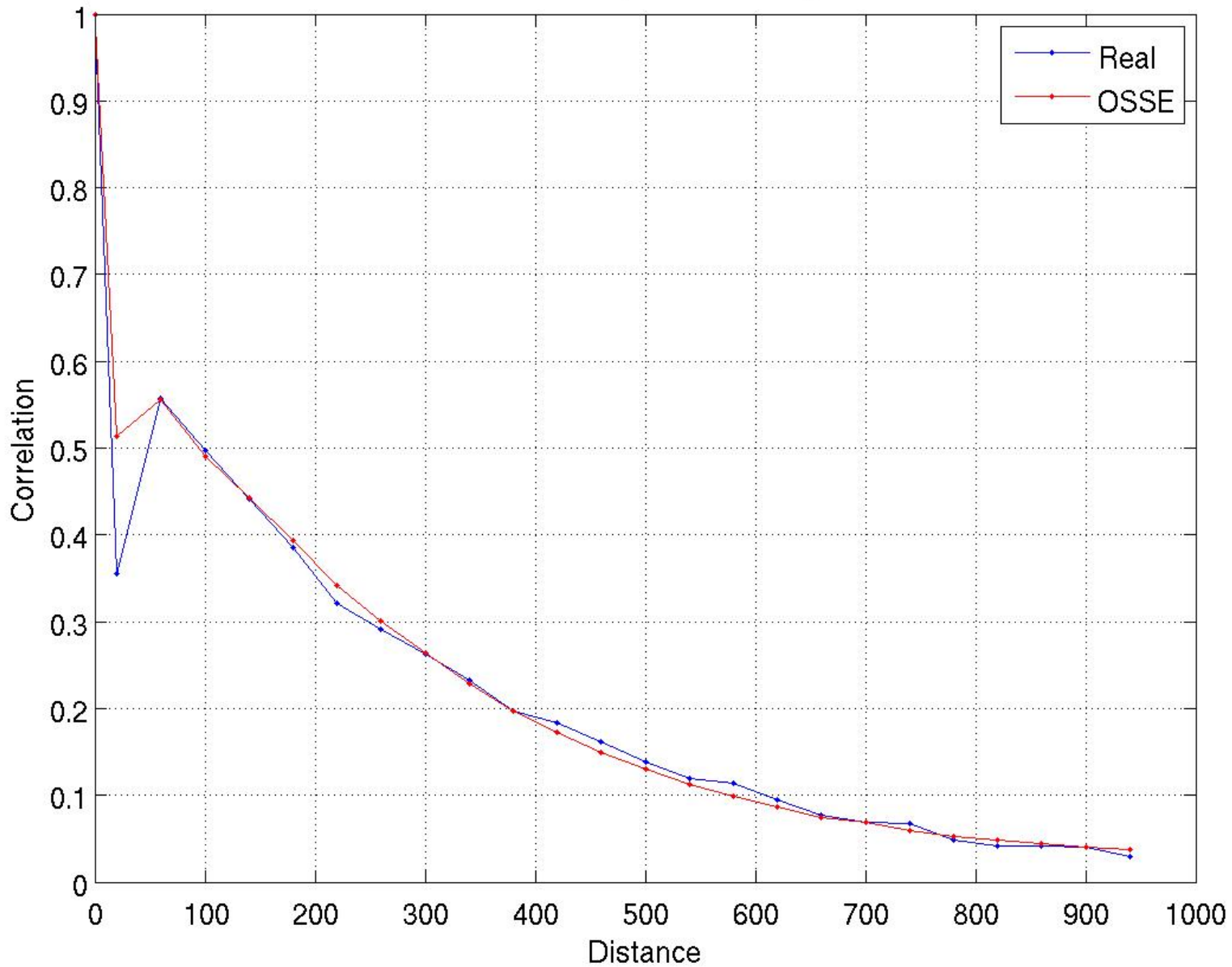
OSSE



Real



Horizontal correlation, AMSU-A n18, channel 4

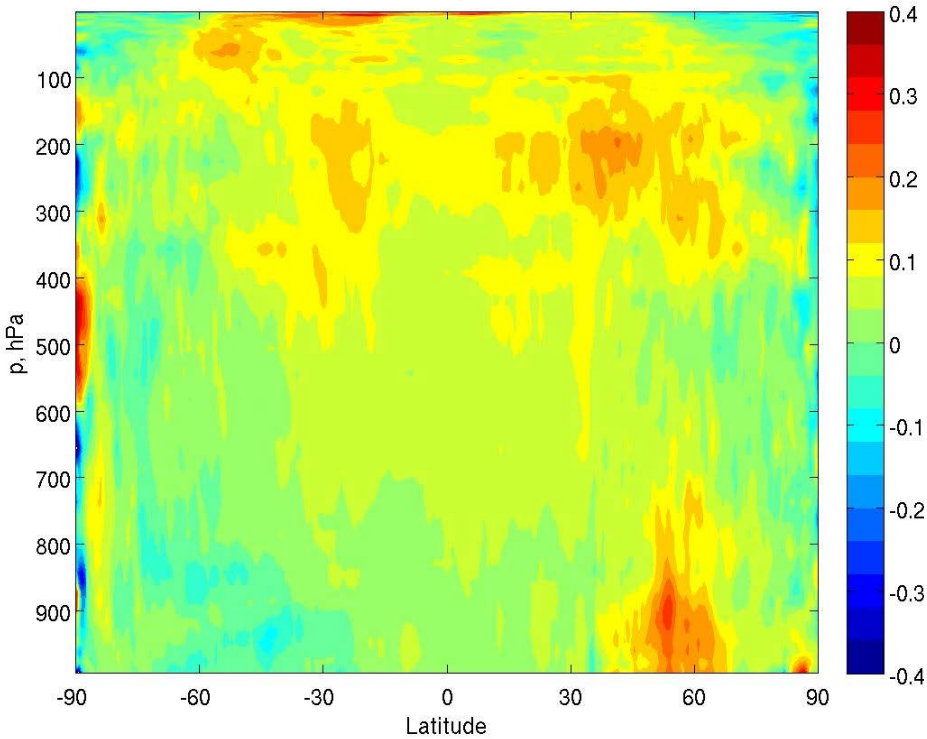


“Kalman Gain”

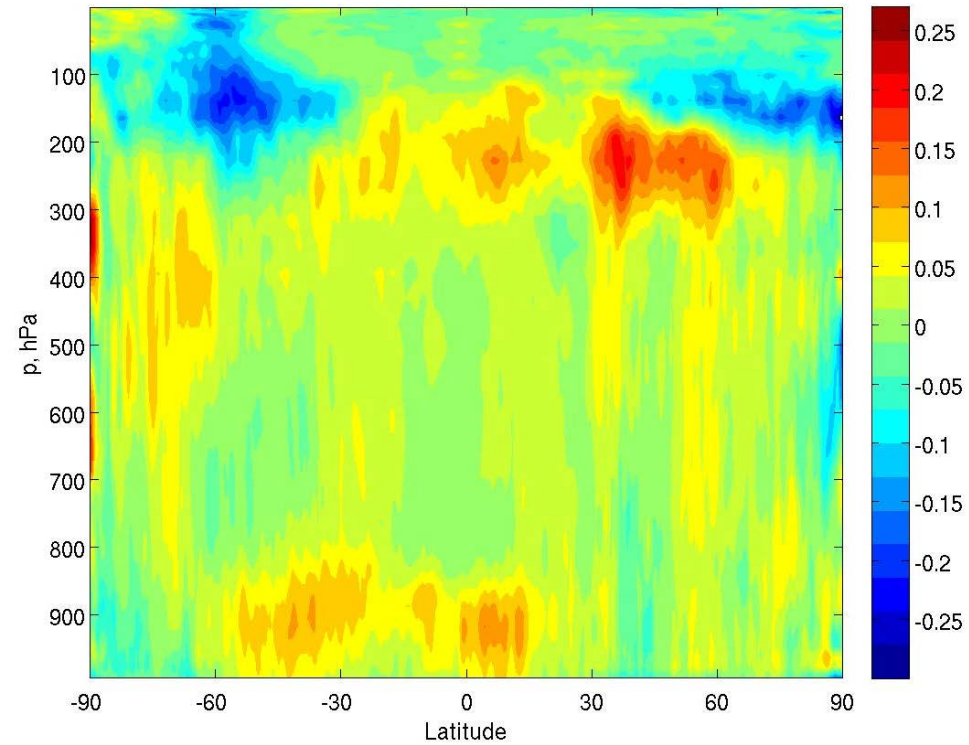
$$K = (\text{Var}(\text{bkg error}) - \text{Var}(\text{ana error})) / \text{Var}(\text{bkg error})$$

Var = zonal mean of temporal variance of indicated error field

T
Gain, T



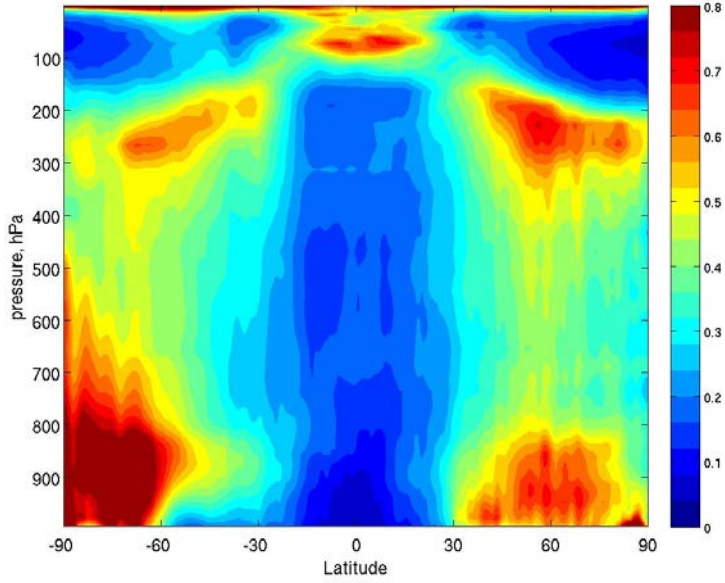
V
Gain, V



Standard deviations of zonal-mean temporal variances of Ana-Bkg

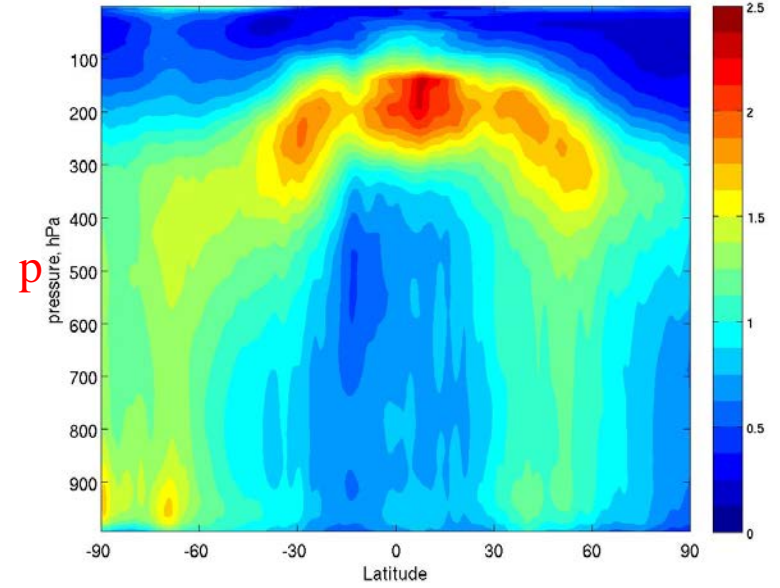
T

Stdev(A-B), Real (real2moment), July, T



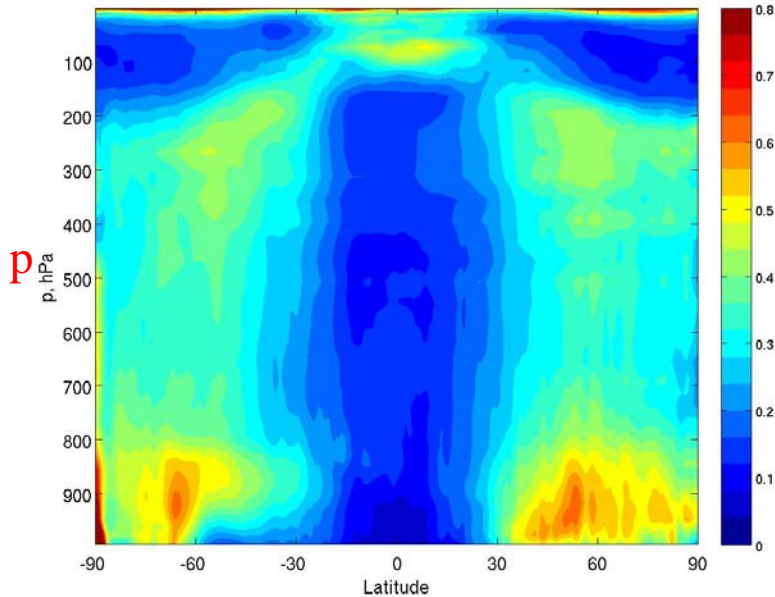
V

Stdev(A-B), Real (real2moment), July, V

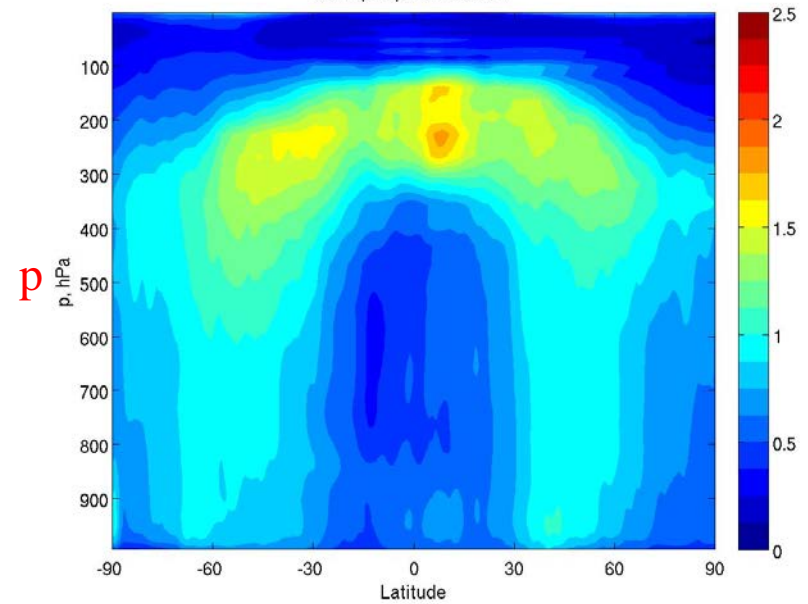


Real

stdev(A-B), G514osse, T

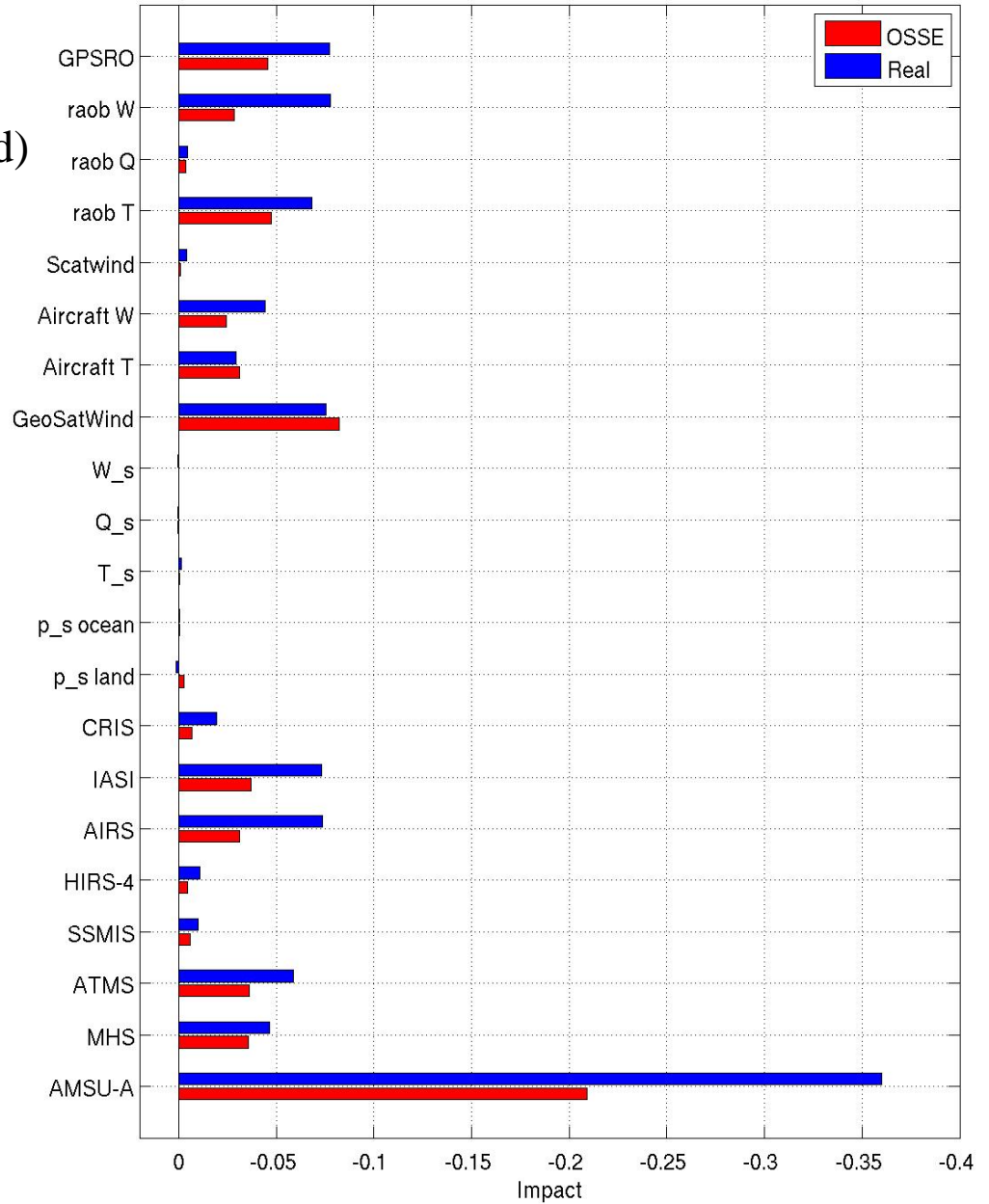


OSSE



Obs Impacts (adjoint-derived)
24-hour forecast error
Moist energy norm

OSSE vs. Real



Summary

1. New GMAO OSSE for Weather Analysis Software Package

Includes:

Use of PREPBUFR, GPSRO, AMV, AIRS, IASI, CRIS, AMSUA, MHS, ATMS, SSMIS, and generic radiances

Simulation of correlated observation errors

Software for quasi-automated tuning of obs error parameters

Technical note for external documentation

Anticipated availability September 2017

2. Simulated observations for selected periods of GEOS-5 NR:

Bufr files of simulated obs with no explicit errors added

Bufr files of simulated obs with added explicit simulated errors

Anticipated availability September 2017