

**HMI Data Driven MHD Model Predicted Active Region Photospheric Heating Rates: Their Scale Invariant Power Law Distributions, and Their Plausible Temporal Correlation With Flares**

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## 1. Introduction & Summary of Approach and Results

- Flare forecasting is important for protecting astronauts and space assets.
- How can forecasting be improved?
- Flares involve the largest current densities in the solar atmosphere.
- The magnetic field  $\mathbf{B}$ , and hence current density  $\mathbf{J} = c\nabla \times \mathbf{B}/(4\pi)$  are most accurately known at the photosphere.
- Large flares (M, X) occur in the neutral line regions (NLRs) of active regions (ARs).  $J$  is max. in NLRs.  $B_{vertical}$  changes sign. Max. free energy.
- Are there changes in the photospheric  $\mathbf{J}$  in NLRs of ARs that are useful for forecasting M/X flares?
- Can HMI (Helioseismic & Magnetic Imager) be used to detect previously undetected changes in  $\mathbf{J}$ ?

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- **HMI:** Full disk, continuous time observations of photospheric  $\mathbf{B}$  at  $1''$ , 12 minute resolution. High enough to begin to resolve granulation dynamics: space and time scales  $\sim 1000$  km and  $\sim 15 - 20$  minutes.
  - Existing flare models we are aware of do not compute the complete  $\mathbf{J}$ .  $\mathbf{J} \neq 0 \Leftrightarrow$  non-potential  $\mathbf{B}$ . Flares relax  $\mathbf{B}$  towards  $\mathbf{J} = 0$ : Min. energy state.
  - **Objective:** Develop a model that computes  $\mathbf{J}$  using highest resolution data with continuous space and time coverage of entire ARs.
  - **Problem:** Photospheric measurements return  $\mathbf{B}(x, y, t)$ , not  $\mathbf{B}(x, y, z, t)$ . So  $J_z$  can be computed, but not  $J_x$  or  $J_y$ .
  - **Solution:** We combine HMI data, the  $\nabla \cdot \mathbf{B} = 0$  constraint, and a Fourier expansion of  $\mathbf{B}$  in  $(x, y)$  to determine  $\mathbf{B}(x, y, z, t)$  through second order in  $z$ , where  $z = 0$  is the photosphere.
  - Then the complete  $\mathbf{J}(x, y, 0, t)$  can be computed.

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- From  $\mathbf{B}(x, y, z, t)$  compute  $\mathbf{J}, \mathbf{A}, \mathbf{E}$  in each pixel for 14 ARs. 7 with M/X flares. 7 with B, C, or no flares.

- Compute time series of  $Q(t) = \eta J^2$  for each AR  $\text{NLR}(t)$ . Are there correlations between changes in  $Q$  and M/X flare times?

Answer: Plausibly yes.

- Compute the cumulative distribution function (CDF)  $N(Q)$  for each AR time series of  $Q$ .  $N(Q)$  is the number of events with heating rates  $\geq Q$ . Compare with the observed  $N(E)$  for the total energy  $E$  released in solar flares.  $E$  is the amount of magnetic energy converted into particle energy.

**Result:** Like  $N(E)$ ,  $N(Q)$  is a scale invariant power law distribution:  $N(Q) = C_{AR} Q^{-S}$ .  $N(Q)$  and  $N(E)$  have essentially the same exponent range.

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## 2. Magnetic Field

Let  $L_x$  and  $L_y$  be the  $x$  and  $y$  dimensions of the rectangular region used to enclose most or all of the AR modeled. The HMI pixel side length  $\Delta = 0.5''$ . The number of HMI data points covering this region is  $N = (N_x + 1)(N_y + 1)$ , where  $N_x = L_x/\Delta$ ,  $N_y = L_y/\Delta$ , and  $(N_x, N_y)$  are given by the HMI datasets. For sufficiently small  $z$ ,

$$\mathbf{B}(x, y, z, t) = e^{-z/L(x,y,t)} \sum_{n=0}^{N_x} \sum_{m=0}^{N_y} \mathbf{b}_{nm}(t) e^{2\pi i \left( \frac{nx}{L_x} + \frac{my}{L_y} \right)}. \quad (1)$$

- $\mathbf{b}_{nm}(t)$  are complex, and  $L(x, y, t) = L_0(x, y, t) + zL_1(x, y, t)/L_0$  where  $L_0$  and  $L_1$  are real and determined by the HMI data and the  $\nabla \cdot \mathbf{B} = 0$  condition.
- For  $z = 0$ , and given the  $N$  vectors  $\mathbf{B}(x_i, y_i, 0, t_j)$  from the HMI data for each  $j$ , Eq. (1) is solved for the time series of the  $\mathbf{b}_{nm}(t)$  using a FFT.

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### 2.1. The $\nabla \cdot \mathbf{B} = 0$ Condition

Define  $\mathbf{B}_0 = \mathbf{B}(x, y, 0, t)$ . Take the divergence of Eq. (1) and set it equal to zero. Solving the resulting equation through order  $z$  gives

$$L_0(x, y, t) = \frac{B_{0z}}{B_{0x,x} + B_{0y,y}}, \quad (2)$$

and

$$L_1(x, y, t) = -\frac{L_0}{2B_{0z}} (B_{0x}L_{0,x} + B_{0y}L_{0,y}). \quad (3)$$

The right hand sides of Eqs. (2) and (3) are evaluated at  $z = 0$ . Therefore,  $L_0$  and  $L_1$  are completely determined by the HMI data. Gives  $\partial\mathbf{B}/\partial z$  at  $z = 0$ .

It is the  $\nabla \cdot \mathbf{B} = 0$  condition plus the HMI data that determine the  $z$  dependence of the model that allows  $J_x$  and  $J_y$  to be computed.

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### 3. Current Density

The current density  $\mathbf{J}(x, y, z, t) = c\nabla \times \mathbf{B}/(4\pi)$ . Through order  $z$ ,

$$(\nabla \times \mathbf{B})_x = \exp(-z/L) \left[ \frac{z}{L_0^2} L_{0,y} B_{0z} + B_{0z,y} + \frac{1}{L_0} \left( 1 - \frac{2L_1 z}{L_0^2} \right) B_{0y} \right], \quad (4)$$

$$(\nabla \times \mathbf{B})_y = -\exp(-z/L) \left[ \frac{z}{L_0^2} L_{0,x} B_{0z} + B_{0z,x} + \frac{1}{L_0} \left( 1 - \frac{2L_1 z}{L_0^2} \right) B_{0x} \right], \quad (5)$$

$$(\nabla \times \mathbf{B})_z = \exp(-z/L) \left[ \frac{z}{L_0^2} (L_{0,x} B_{0y} - L_{0,y} B_{0x}) + (B_{0y,x} - B_{0x,y}) \right]. \quad (6)$$

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#### 4. Vector Potential and Electric Field

Assume the following expansion, valid through order  $z^3$  for sufficiently small  $z$ .

$$\mathbf{A}(x, y, z, t) = \mathbf{a}_0(x, y, t) + \mathbf{a}_1(x, y, t)z + \mathbf{a}_2(x, y, t)z^2 + \mathbf{a}_3(x, y, t)z^3. \quad (7)$$

Expand  $\mathbf{B}$  through order  $z^2$  to obtain

$$\mathbf{B}(x, y, z, t) = \left(1 - \frac{z}{L_0} + \left(1 + \frac{2L_1}{L_0}\right) \frac{z^2}{2L_0^2}\right) \mathbf{B}_0(x, y, t) \quad (8)$$

- The  $\mathbf{a}_i$  ( $0 \leq i \leq 3$ ) are found by solving  $\mathbf{A} = \nabla \times \mathbf{B}$  with the Coulomb gauge condition  $\nabla \cdot \mathbf{A} = 0$  (ensures uniqueness), order by order in powers of  $z$ .



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Let  $\Sigma'$  denote the sum over  $n, m$  except the term with  $n = m = 0$ . Then

$$A_x = -\frac{L_x^2 L_y}{2\pi} \sum' \frac{m I_{z,nm}}{(n^2 L_y^2 + m^2 L_x^2)} - \frac{y R_{z,00}}{2} + z \left(1 - \frac{z}{2L_0}\right) B_{0y} + \frac{1}{6} \left( \left(1 + \frac{2L_1}{L_0}\right) \frac{B_{0y}}{L_0^2} - (B_{0y,xx} - B_{0x,xy}) \right) z^3 \quad (9)$$

$$A_y = \frac{L_x L_y^2}{2\pi} \sum' \frac{n I_{z,nm}}{(n^2 L_y^2 + m^2 L_x^2)} + \frac{x R_{z,00}}{2} - z \left(1 - \frac{z}{2L_0}\right) B_{0x} - \frac{1}{6} \left( \left(1 + \frac{2L_1}{L_0}\right) \frac{B_{0x}}{L_0^2} - (B_{0x,yy} - B_{0y,xy}) \right) z^3 \quad (10)$$

$$A_z = \left[ -\frac{1}{2} (B_{0y,x} - B_{0x,y}) \left(1 - \frac{z}{3L_0}\right) + \frac{z}{6L_0^2} (B_{0x} L_{0,y} - B_{0y} L_{0,x}) \right] z^2. \quad (11)$$

Then  $\mathbf{E} = -c^{-1} \partial \mathbf{A} / \partial t - \nabla \Phi \sim -c^{-1} \partial \mathbf{A} / \partial t$ .

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## 5. Need to Remove Spurious Doppler Periods From the HMI B

- There is spurious, Doppler shift generated noise in the form of 6, 12, and 24 hour period oscillations in the components of B for each pixel. Noise is due to SDO orbital motion.
- The noise is removed from the time series of HMI B for each pixel using an FFT based bandpass filter.
- Doppler Noise in Pixel Level Quantities:

Figures 1-3 shows the filtered and un-filtered HMI time series of  $B_x$ ,  $B_y$ , and  $B_z$  for a randomly selected pixel from the NLR of NOAA AR 1166 during a 70 hour long time series.

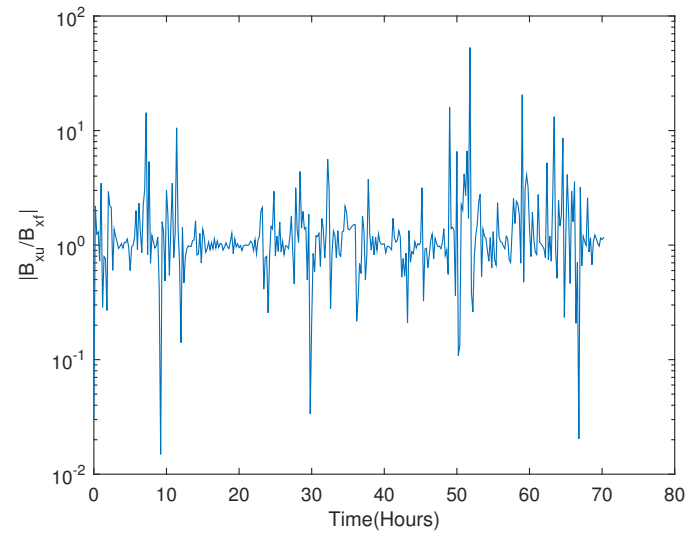
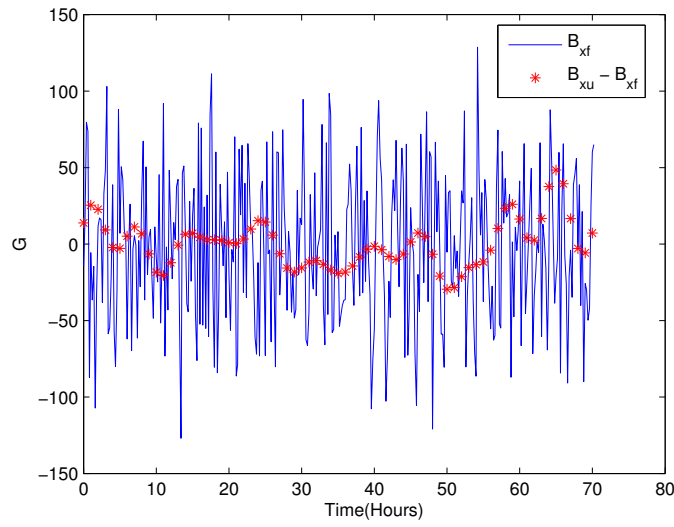


Figure 1: Comparison of the Filtered and Un-filtered  $B_x$  in a pixel from NLR/AR 1166.

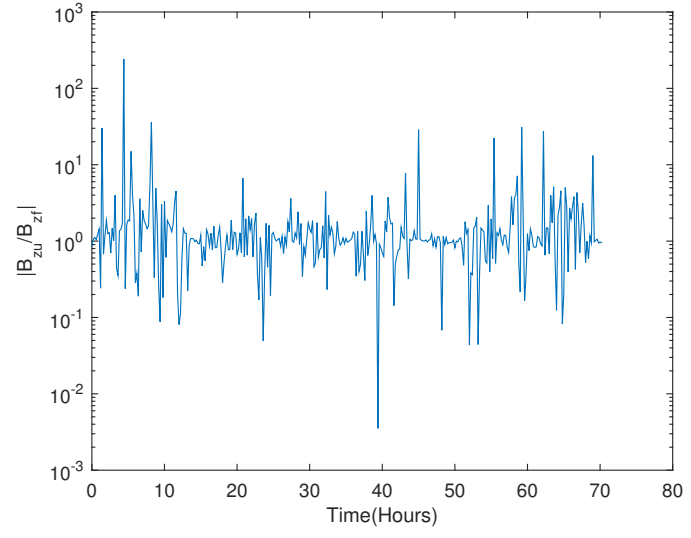
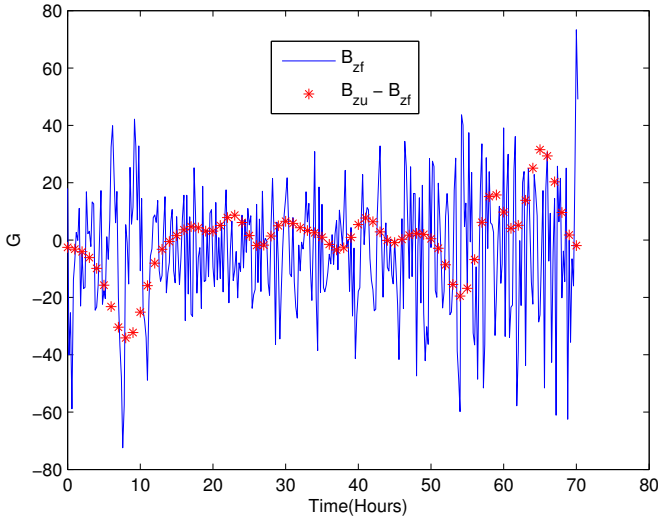


Figure 2: Comparison of the Filtered and Un-filtered  $B_z$  in a pixel from NLR/AR 1166.

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- Doppler Noise in NLR Integrated Quantities:

Figures 4-7 show the results of integrating the filtered and un-filtered pixel level results for  $\eta J^2$  and  $B^2/8\pi$  over the NLR at each time.

The 70 hour long time interval includes 1 X, 2 M, and 9 C flares.

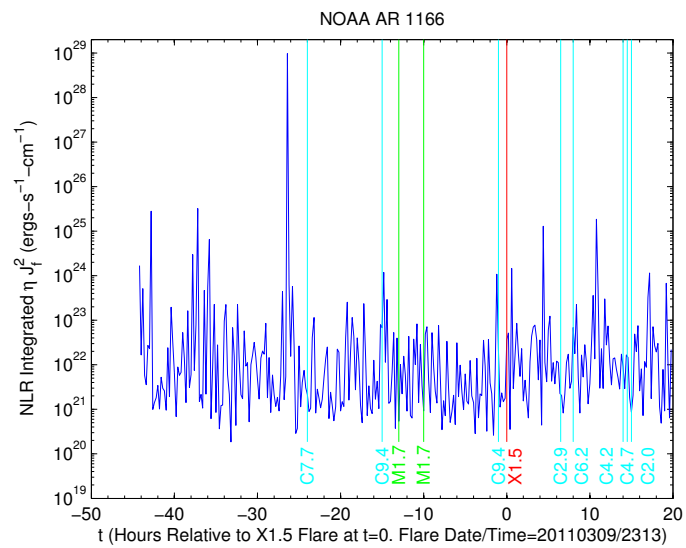
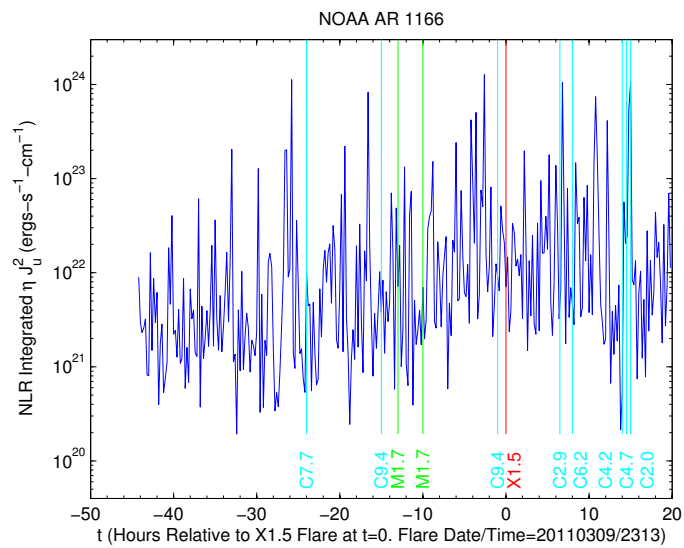


Figure 3: Comparison of the filtered and un-filtered, NLR integrated  $\eta J^2$ .

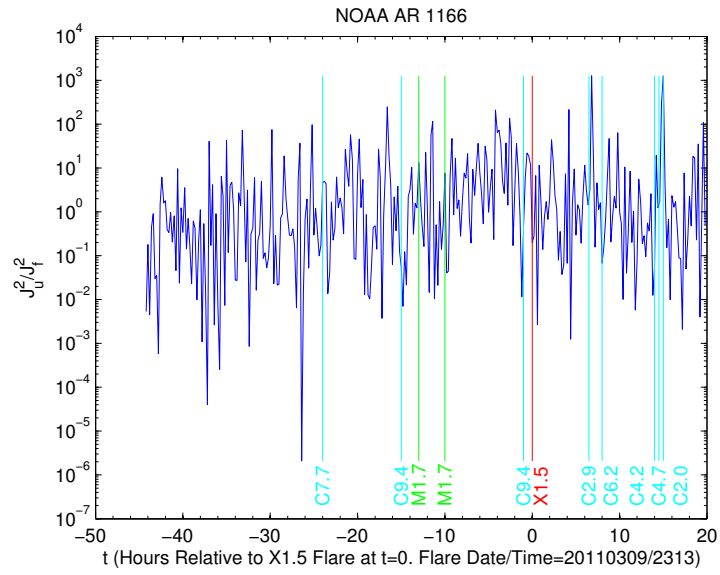


Figure 4: Comparison of the filtered and un-filtered, NLR integrated  $\eta J^2$ .

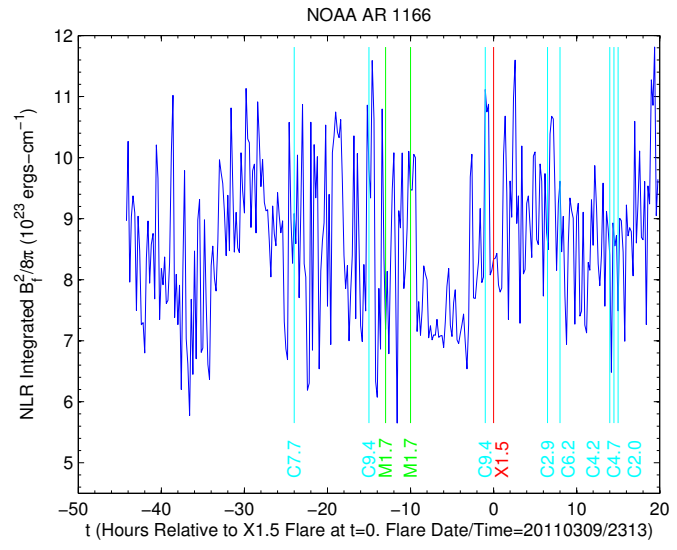
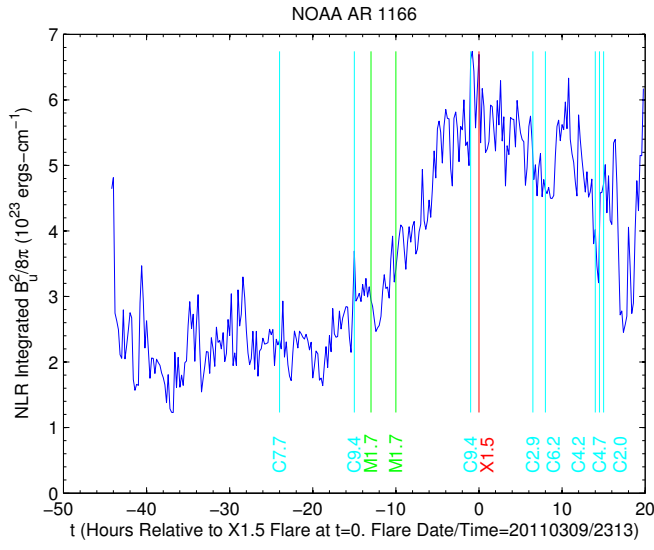


Figure 5: Comparison of the filtered and un-filtered, NLR integrated  $B^2/8\pi$ .



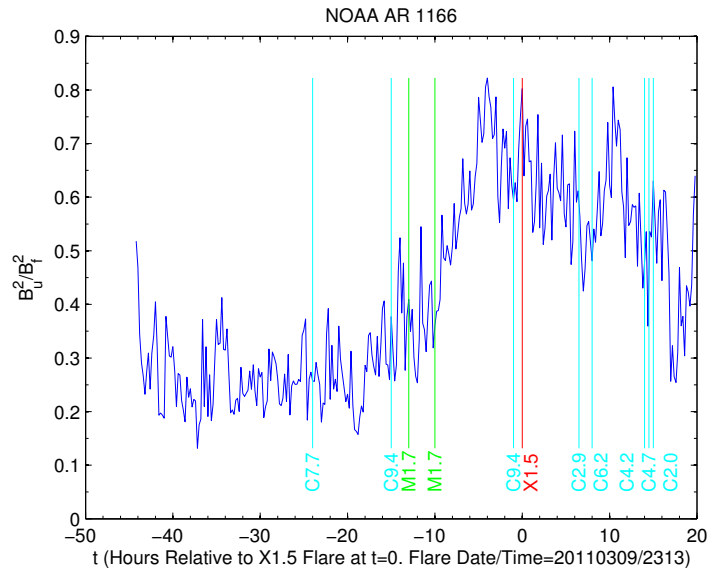


Figure 6: Comparison of the filtered and un-filtered, NLR integrated  $B^2/8\pi$ .

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## 6. NLR Integrated Resistive Heating Rates $Q(t)$ of Strongly Flaring (SF) ARs: Comparison with Flare Times

- Plot  $Q(t)$ . Superimpose the times of C, M, and X flares. NOAA database.
- Look for changes in  $Q$  that may be correlated with flare times. Large spikes.
- Check to what extent  $\mathbf{J}$  is force-free (i.e.  $J_{\perp}/J_{\parallel} \ll 1$ ). The largest heating events, which are found to occur in single pixels, are highly non-force-free:  $\mathbf{J} \times \mathbf{B} = 0$  is a bad assumption at the photosphere.
- Results for weakly flaring ARs (C, B, or no flares) are not shown.  $Q$  is  $\sim 10 - 100$  times less than for SF ARs, and there does not seem to be a correlation between spikes in  $Q$  and subsequent flaring.



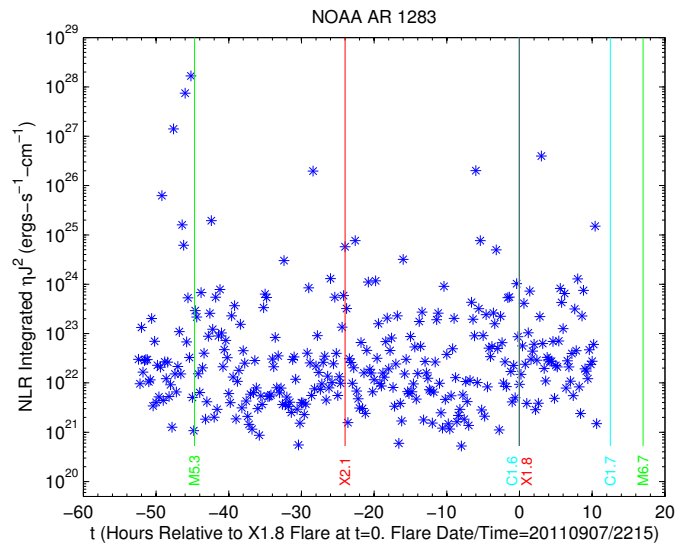
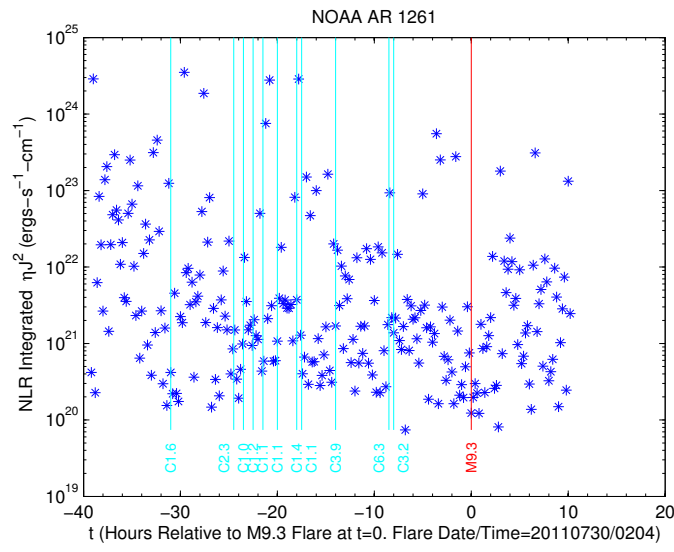


Figure 8: NLR integrated Q for 2 of 7 SF ARs.



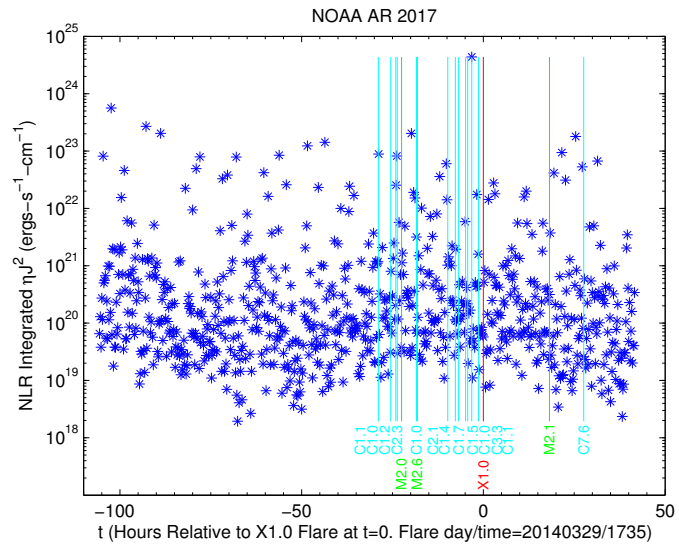


Figure 10: NLR integrated  $Q$  for the 7th SF AR.

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## 7. Scale Invariant Power Law Distributions of $Q$ - Comparison with Flares

- Compute the Cumulative Distribution Functions (CDFs) of the time series for  $Q$ . The CDF is the number  $N(Q)$  of heating events with heating rate  $\geq Q$ .
- Above an AR dependent threshold value, the CDF for each AR is well fit by a scale invariant power law distribution  $N(Q) = AQ^{-S}$ , with  $S$  constant over a range of several orders of magnitude in  $Q$ .

Scale invariance means that a change in scale of  $Q$  (i.e. replacing  $Q$  by  $kQ$ ) does not change the form of  $N(Q)$  (i.e.  $N(kQ) = \text{constant} \times N(Q)$ ).  $N(Q)$  is scale invariant over the range of  $Q$  for which  $S$  is constant.

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- For the 14 ARs analyzed it is found that  $0.40 \leq S \leq 0.53$ , with a mean and standard deviation across the ARs of 0.47 and 0.045. This  $\Rightarrow$  little statistical variation in  $S$  from one AR to another.
  - The CDF  $N(E)$  for the total energy  $E$  released in solar flares is determined from observations to have the same form:  $N(E) = \text{constant} \times E^{-\alpha}$ .
  - EUV and SXR observations of nanoflares in the 0.7–4 MK range, and HXR observations of flares imply that  $0.51 \leq \alpha \leq 0.57$ , and  $0.4 \leq \alpha \leq 0.6$ .
  - Observations also show that, as is found for the exponent  $S$  in  $N(Q)$ , there is little variation of  $\alpha$  among ARs.
  - Therefore, the power law scaling of the *photospheric*  $Q$  is essentially identical to that found for *coronal* flares.
  - Suggests the mechanisms that generate  $Q$  and coronal flares are closely related.



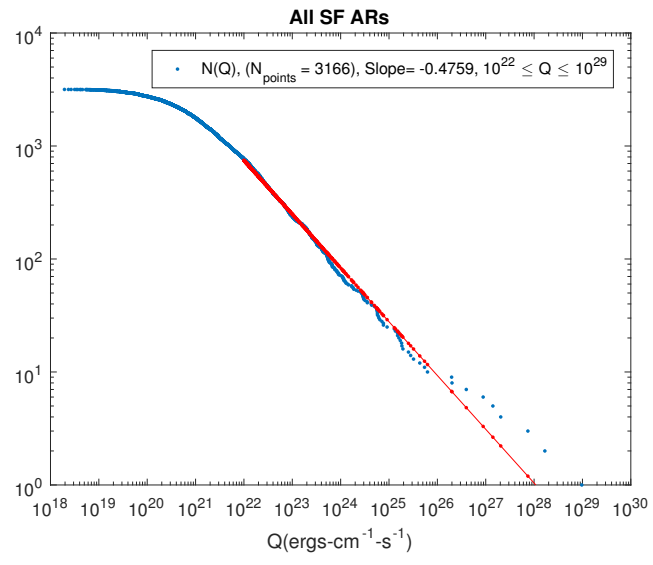
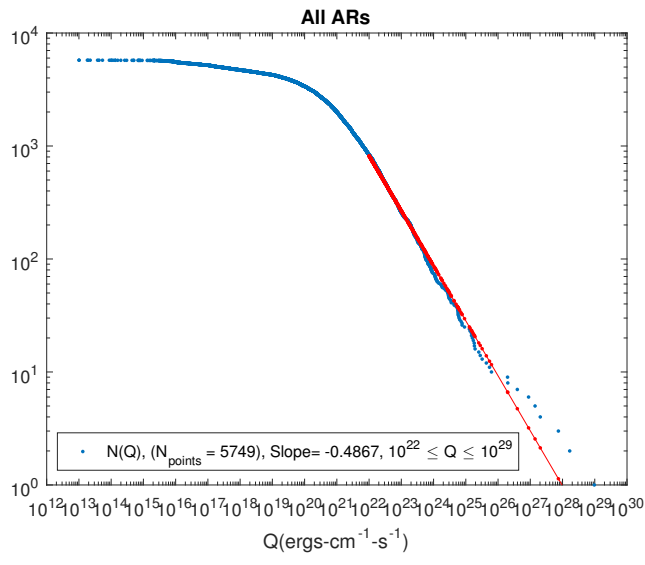


Figure 11: CDFs for all ARs, and all SF ARs.

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## 8. Conclusions

- Flare forecasting models based on computing time dependent maps of the complete photospheric current density need to be developed.
- The spurious Doppler periods in the HMI magnetic field can introduce large errors into B and derived quantities.
- In combination with the model, HMI might be revealing previously undetected photospheric heating events on granulation space and time scales in NLRs of ARs.
- The largest heating events occur in NLRs that exhibit M/X flares. They are highly non-force-free.
- It is plausible these events are correlated with M/X flares, preceding them by several hours to several days. But the sample size of 14 ARs is too small to determine if a correlation exists. Analysis of more ARs is needed.

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- The CDFs of  $Q$  obey a scale invariant power law distribution essentially identical to that of the energy released in flares. This suggests a close connection between the process that drives  $Q$ , which is a photospheric phenomenon, and the process that drives flares, which are a coronal phenomenon.