



WPI



Multi-Objective Reinforcement Learning for Cognitive Radio-based Satellite Communications

Paulo Ferreira, Randy Paffenroth, Alexander Wyglinski - (*WPI*)

Timothy Hackett, Sven Bilen - (*Penn State*)

Richard Reinhart, Dale Mortensen - (*NASA GRC*)

NASA GRC Grant: "Intelligent Media Access Protocol for SDR-based Satellite Communications."

Grant number: NNC14AA01A

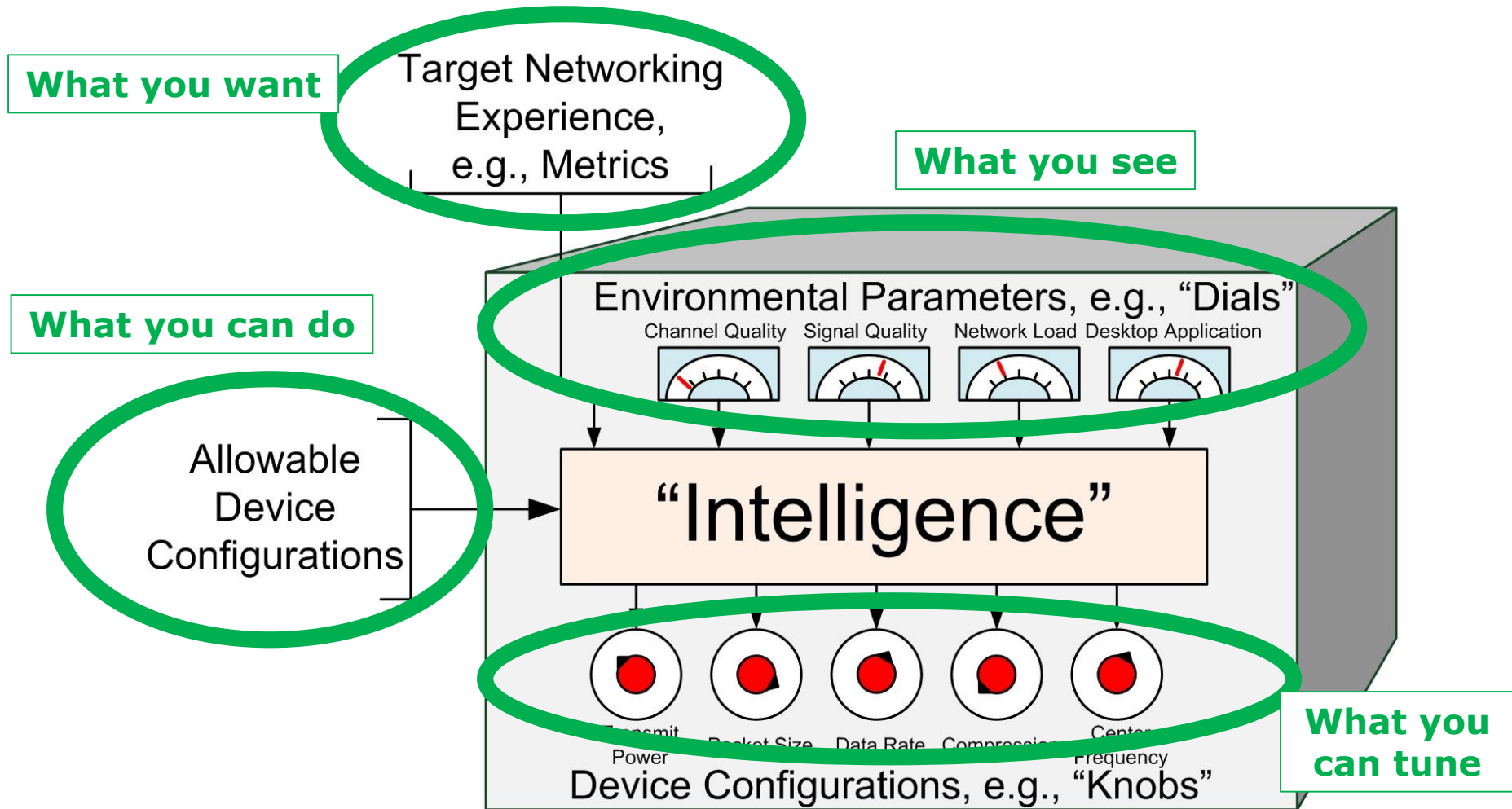
Agenda

- What is a Cognitive Radio?
- CR applications
- The problem: Multi-objective performance
- Reinforcement Learning: The solution
- Satcom RL performance

What is a Cognitive Radio ?



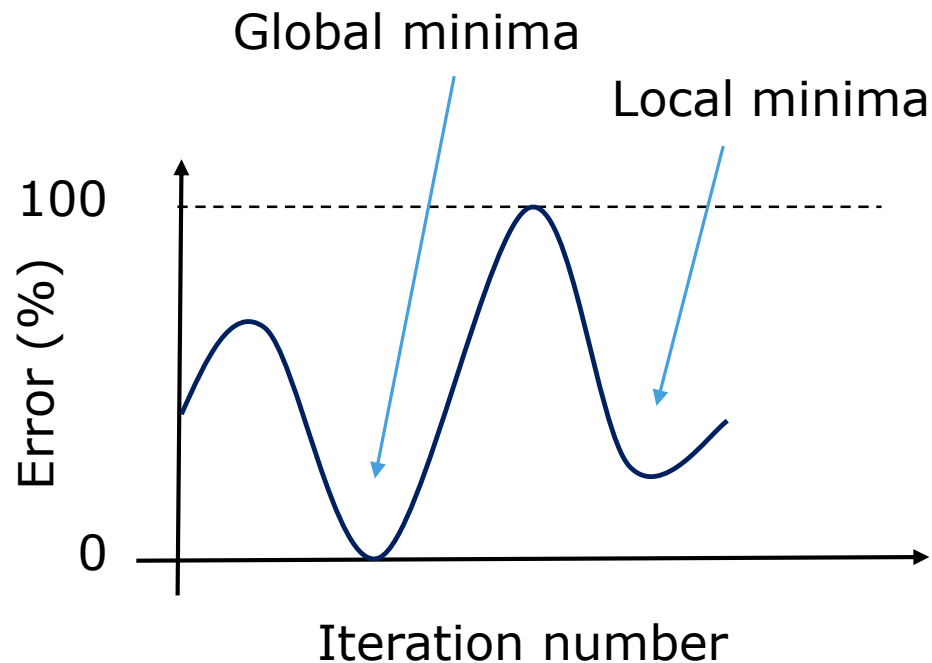
What is a Cognitive Radio ?



T. Collins, A.M. Wyglinski. "Enabling Security in Cognitive Radios and Wireless Spectrum." MILCOM Tutorial, 2014.

What is a Cognitive Radio ?

- Learning algorithm
 - Explore vs. Exploit



CR applications



CR applications

- **Satcom**



Reinhart, R. C. Using International Space Station For Cognitive System Research And Technology With Space-based Reconfigurable Software Defined Radios. 66th International Astronautical Congress, IAC 2015.

CR Satcom – What you tune: PHY layer

- Modulation scheme
- Encoding scheme
- Symbol rate
- Bandwidth
- Carrier frequency
- ADC/DAC resolution
- Antenna
- Transmission power level

Multi-Objective Comms Performance

The problem



Multi-objective comms performance

Table 1. Radio parameter adaptation inter-relationship

Adaptation	Goals	Consequences	Conflicts	Constants
$\downarrow M$	$\min(\text{BER}), \min(P)$	$\downarrow R, P, \text{BER}$	$\max(R)$	E_b
$\uparrow M$	$\max(R)$	$\uparrow R, P, \text{BER}$	$\min(\text{BER}), \min(P)$	E_b
$\uparrow R$	$\max(R), W \text{ const.}^*$	$\uparrow W, P$	$\min(P), W \text{ const.}^*$	M, E_b
$\downarrow R$	$\min(P), W \text{ const.}^*$	$\downarrow W, P$	$\max(R), W \text{ const.}^*$	M, E_b

* Keeping W constant can be a goal or a conflicting goal while adapting R .

M – modulation and encoding schemes

R – data rate

BER – bit error rate

P – transmission power

W – bandwidth

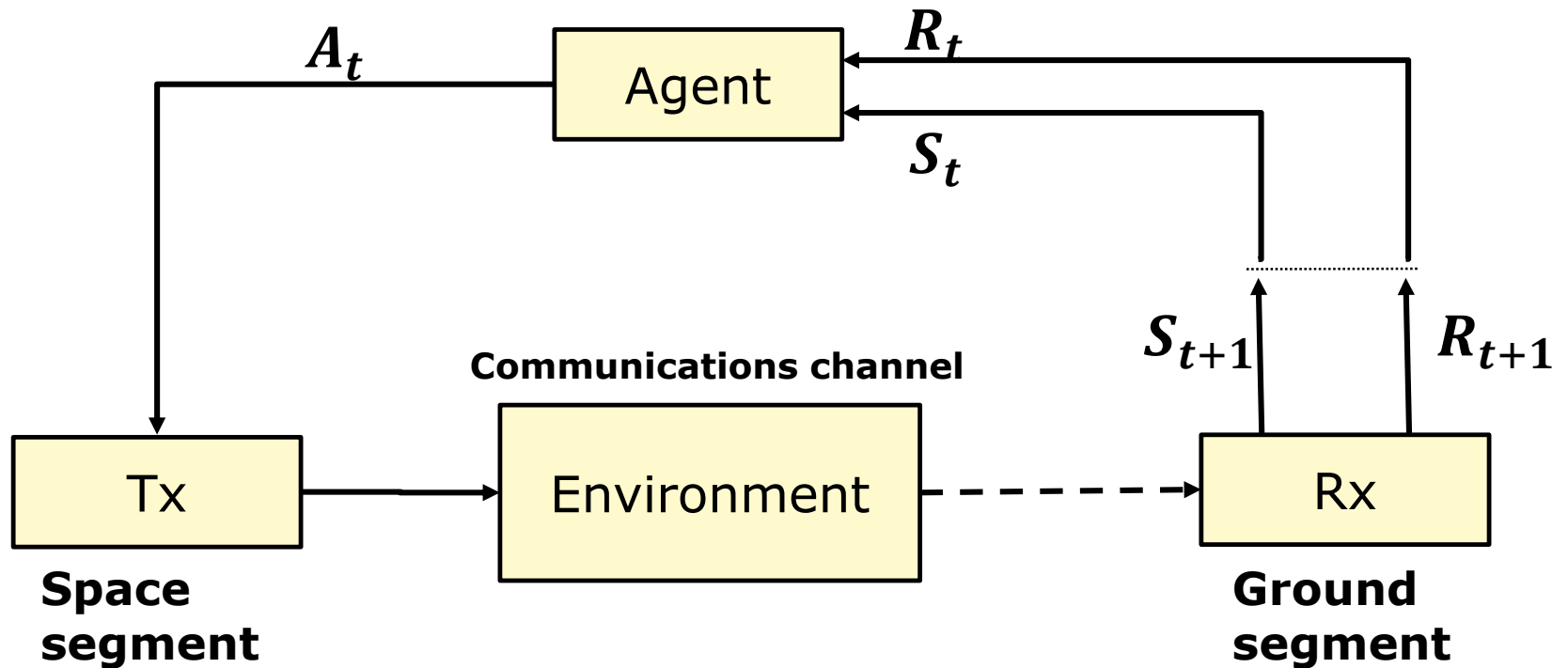
E_b – energy per bit

Reinforcement Learning

The solution

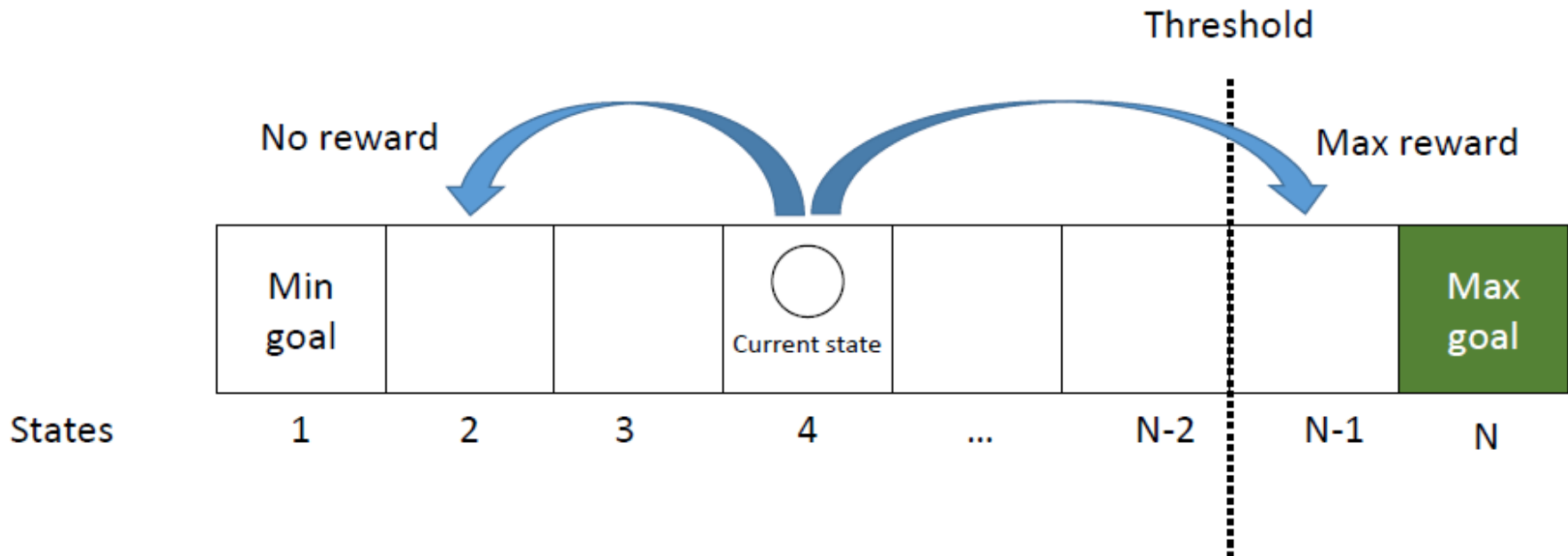


Reinforcement Learning



A_t = action
 R_t = reward
 S_t = state

Reinforcement Learning



Reinforcement Learning

- Satcom $Q(S, A)$

$$Q_{k+1}(s_k, u_k) = Q_k(s_k, u_k) + \alpha_k r_{k+1}$$

$u_k = h(s_k)$ \longrightarrow State-action policy

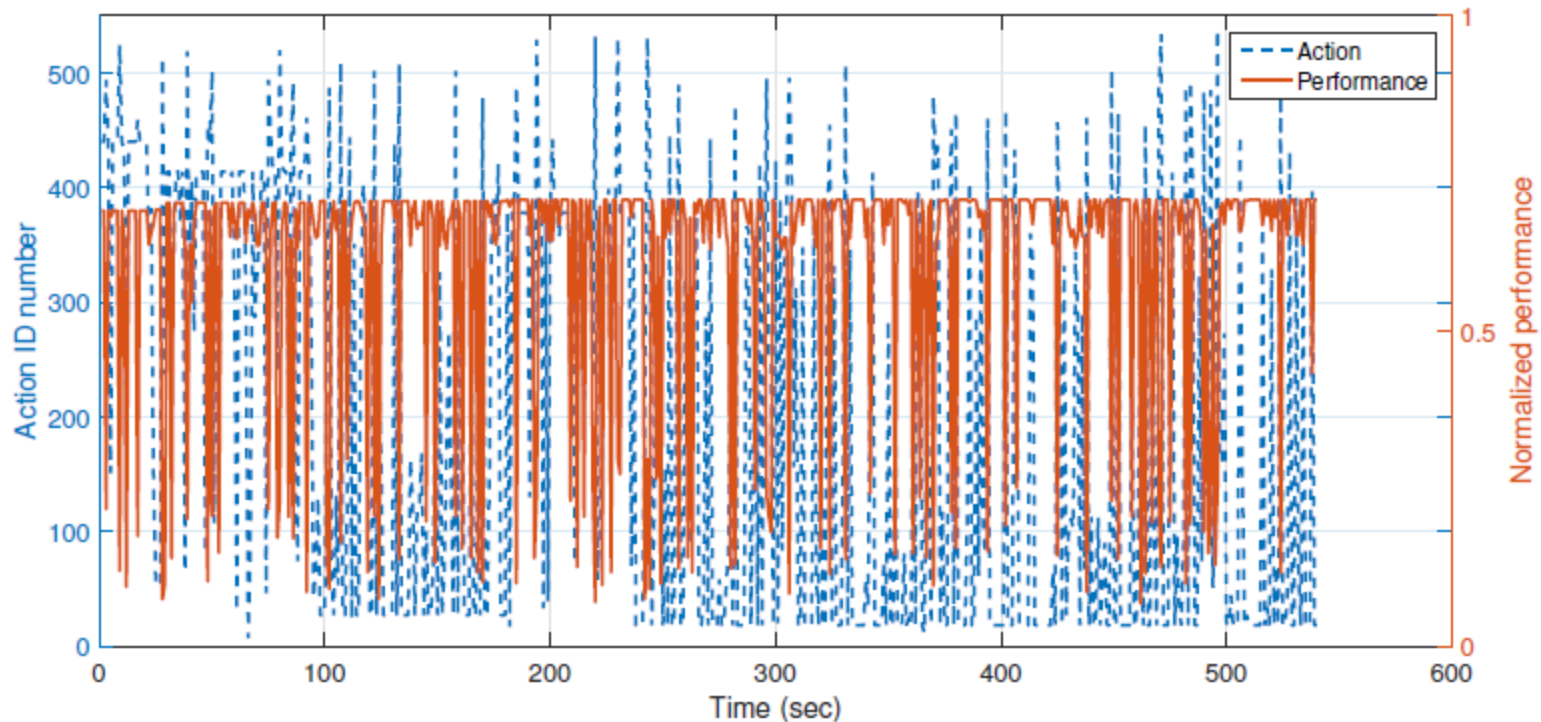
$s_{k+1} = g(s_k, u_k)$ \longrightarrow State-transition function

$r_{k+1} = \rho(s_k, u_k)$ \longrightarrow Reward function

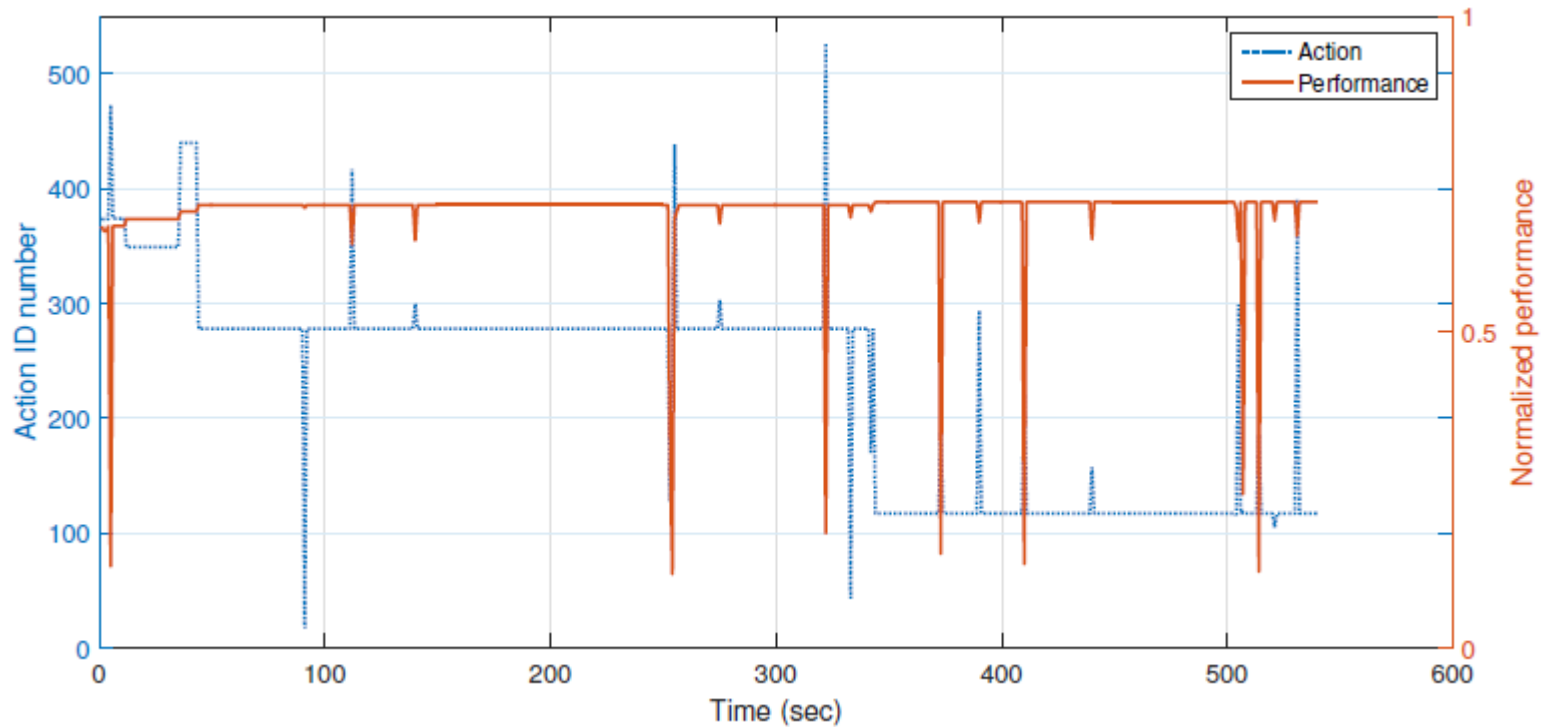
Satcom RL performance



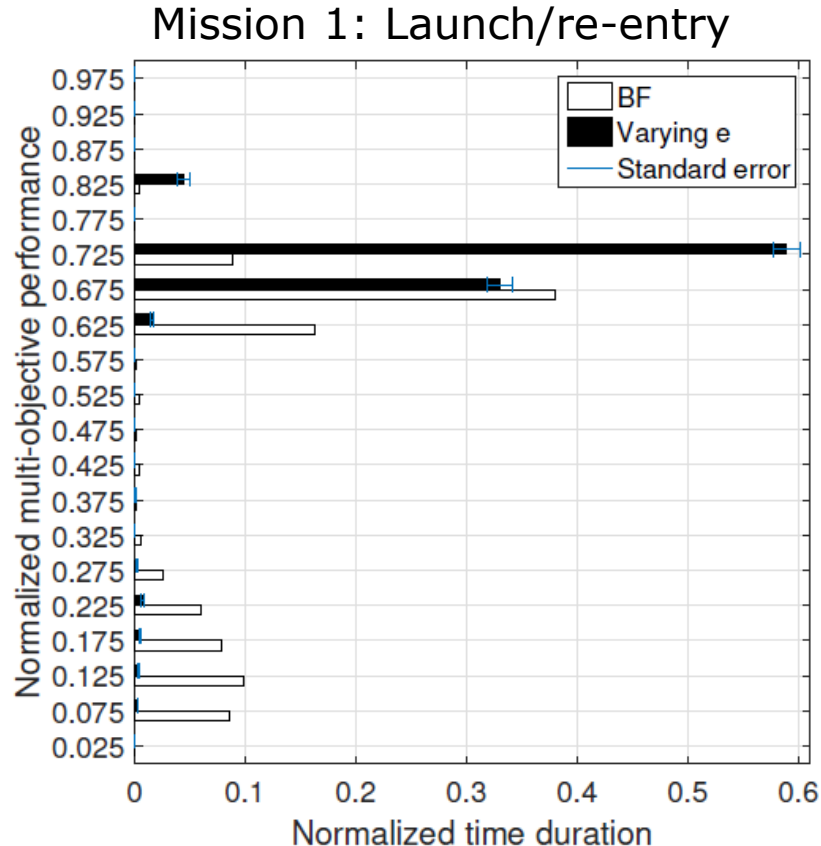
Fixed exploration probability ($\varepsilon = 0.5$)



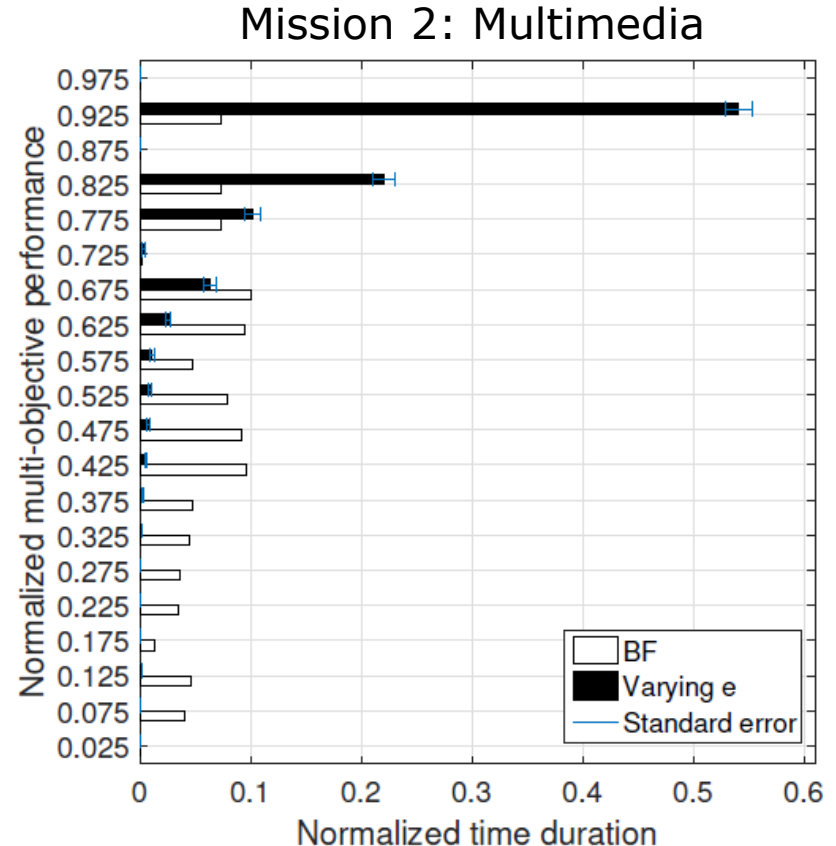
Variable exploration probability ε



Time spent at performance levels



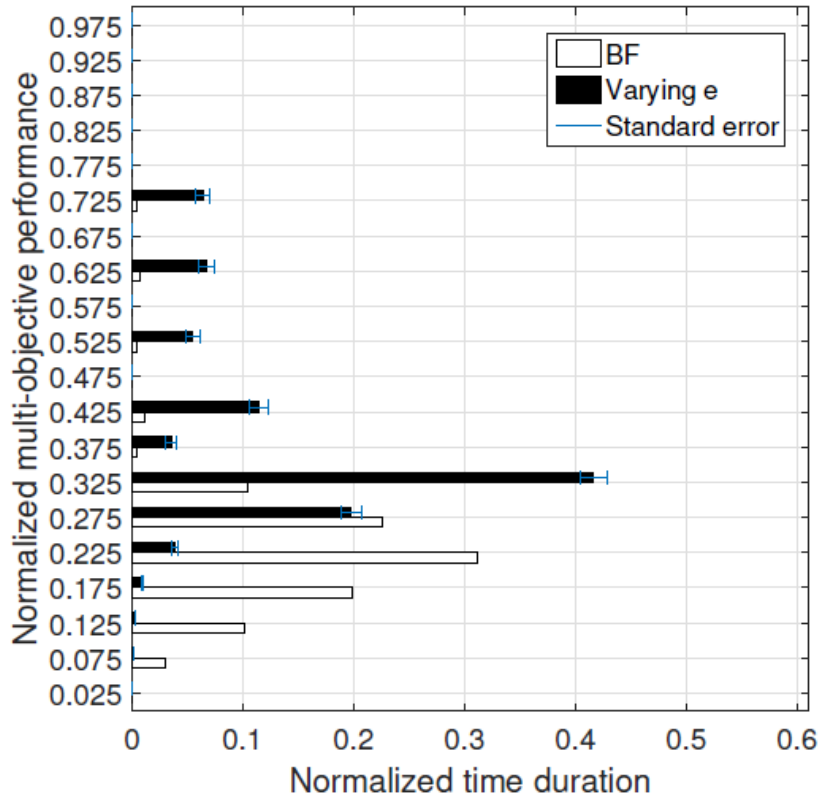
(a)



(b)

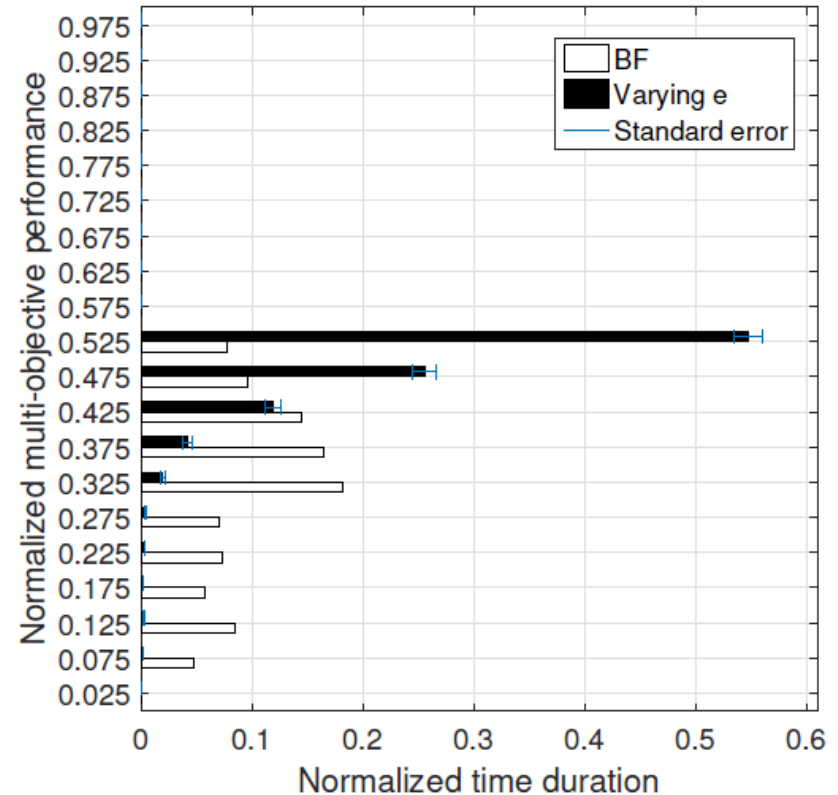
Time spent at performance levels

Mission 3: Power saving



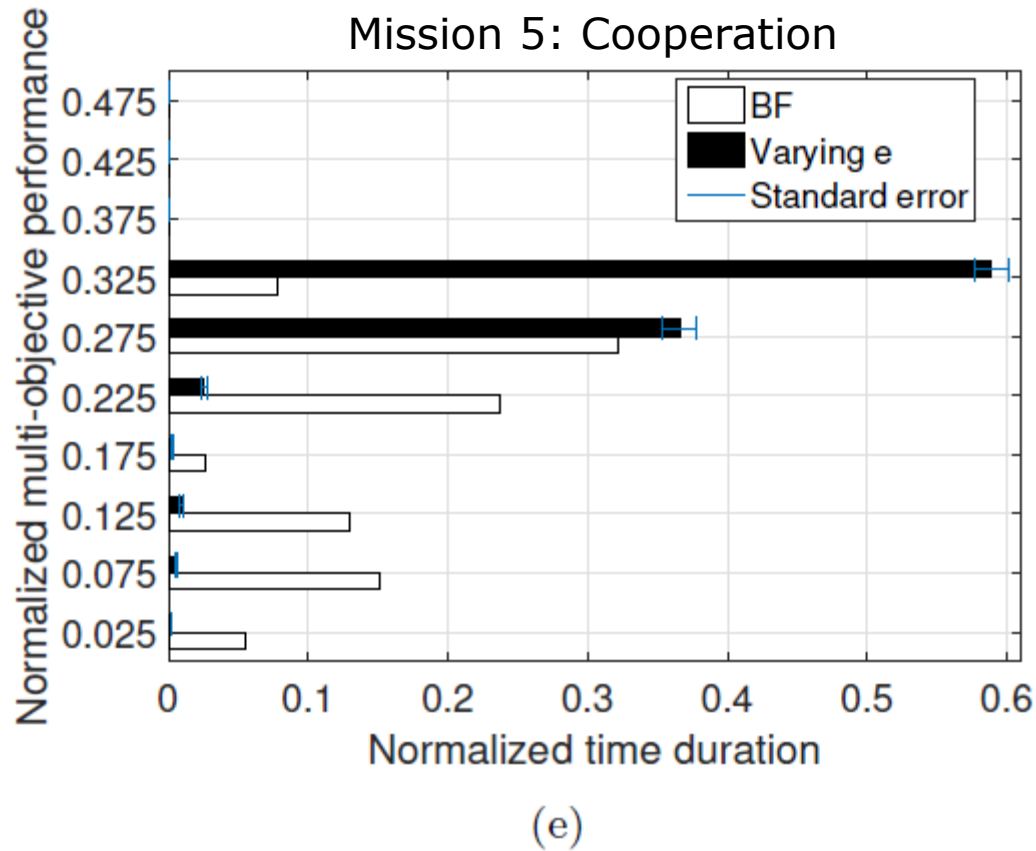
(c)

Mission 4: Normal



(d)

Time spent at performance levels



THANK YOU!



Applied Research Solutions for a Connected Society

Contact us



PRFERREIRA@wpi.edu



ALEXW@wpi.edu

<http://www.wireless.wpi.edu/>