Advanced Wireless Sensor Nodes -MSFC 2016

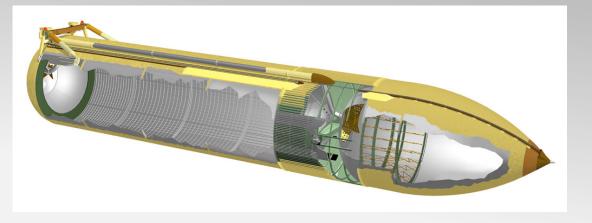
Kosta Varnavas-Electronic Design Design Branch - ES 36





Jeff

Richeson-ES35 ESSSAI Jacobs





#### Sensor proliferation is exploding...



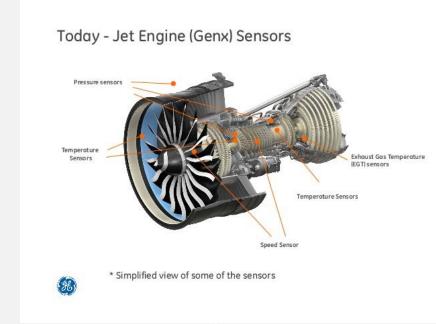
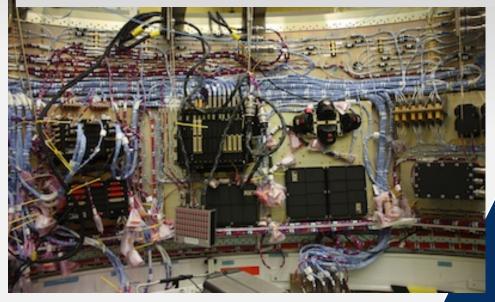
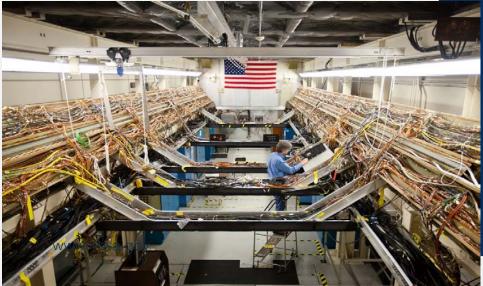


Image Sources: Google Images

## DRAWBACKS TO HARDWIRED SPACECRAFT BUS ARCHITECTURES





Failures of wires and connectors

Mass of cabling and electrical interfaces

Physical restrictions on wired sensor placements (tankage, bulkhead penetrations, etc)

Undesired ground loops on the communication paths; long wire runs acting as antennas

Image Sources: Google Images

## ADVANTAGES OF WIRELESS TECHNOLOGY

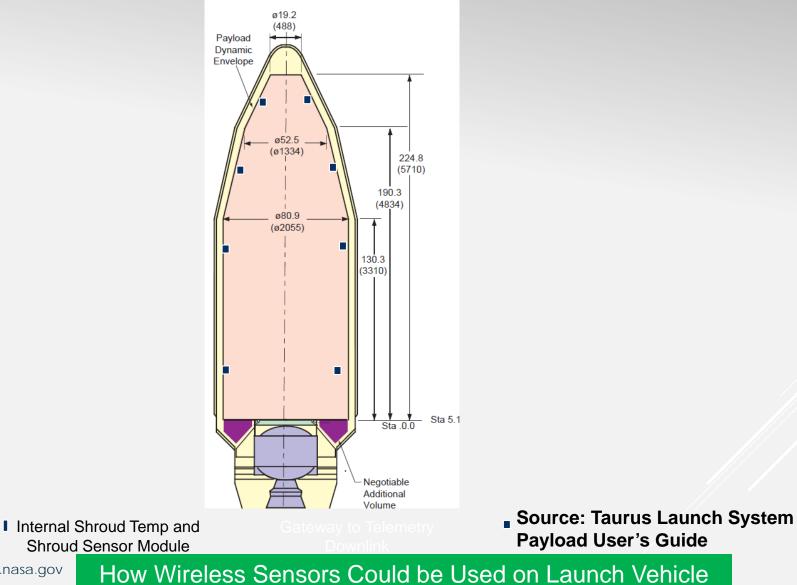
Covers common-mode faults due to structural failure that may affect critical wiring!

Lower mass

Redundant data access nodes improves robustness

Low-power battery-powered sensor packages can last years and be placed in difficult locations for wires to reach (penetrations, high vibration, rotating structures and components)

# for Launch System Technology Development



## The Chosen ZigBee Module

 The Synapse RF200
Modules, contain a complete
A/D, Microcontroller
802.15.4 radio and
Mesh Protocol
Software Stack.

Capable of uploading new software into each module over the air (OTA). RF200P81 / SM200 Synapse 2.4 GHZ IEEE 802.15.4/ZIGBEE® RF TRANSCEIVER

RX: 22.5 mA (@ 3.3 V)

TX: 22.5 mA (@ 3.3 V)

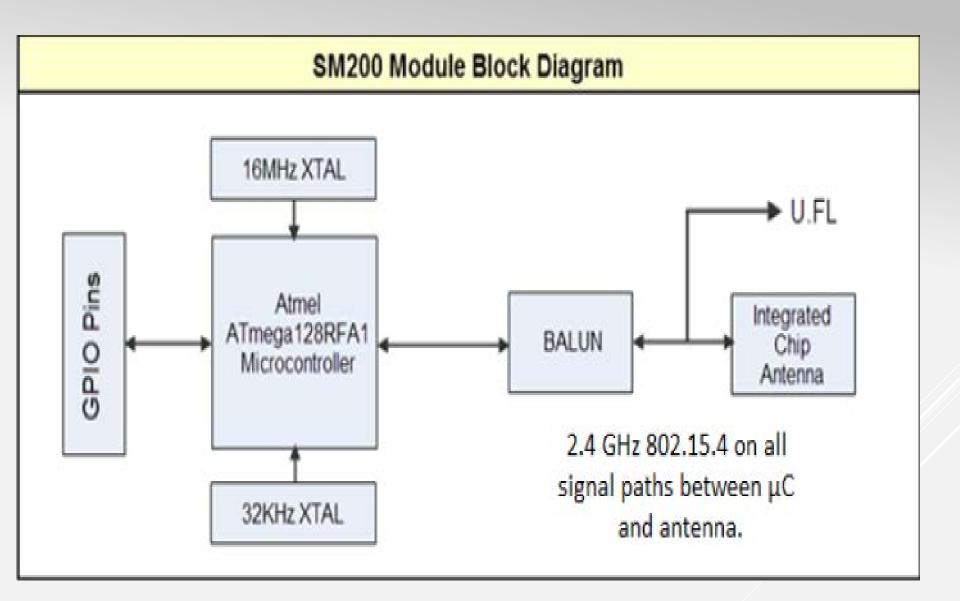
33.86mm x 33.86mm

20 GPIO and up to 7 A/D inputs

#### SN132 SNAPstick USB module







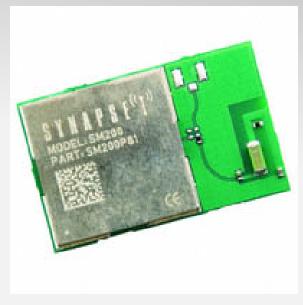
## WIRELESS SYNAPSE FOOTPRINTS

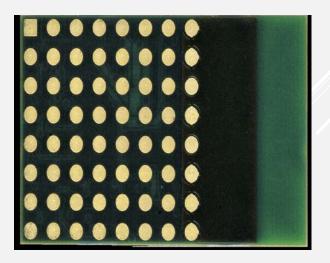
### Through Hole (DIP)





#### Surface mount





### Comparing the two generations



GEN 1

- 6 gauges all powered at same time.
- Strain gauged excitation voltage is straight off main battery rail.
- Op amp only has a 200 gain. This is a fixed gain set by on board resistor.
- No shunt or other method for onboard calibration.
- No Power Management.

W



- Only 1 Gauge
- Each strain gauge has an independent
  - constant voltage regulator driving the excitation voltage.
  - Power management hardware.
- eneration • Op Amp has much larger and adjustable gains.
- Power management software.



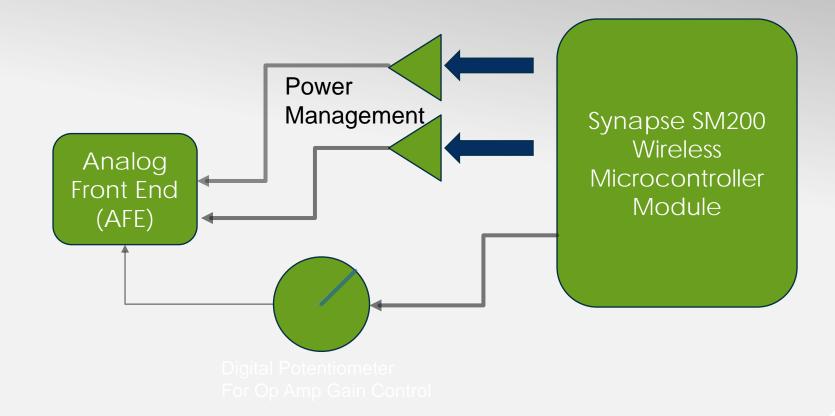


Gen 2 Wireless Strain Gauge

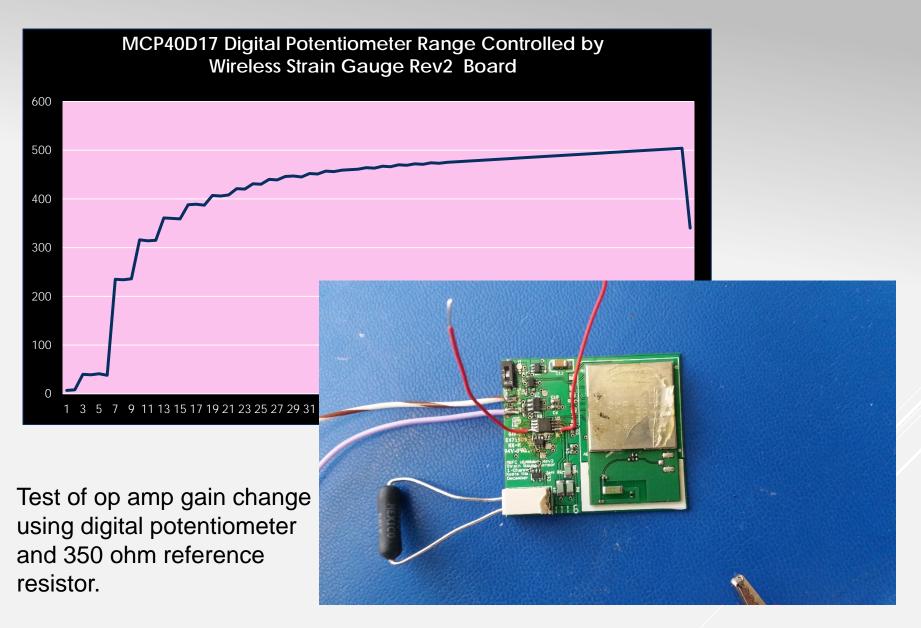
- \* 1 Channel
- \* With Battery
- \* 1.5 " x 1.3 " without case.

Gen 2 Wireless Strain Gauge with power leads And strain gauge Attached.

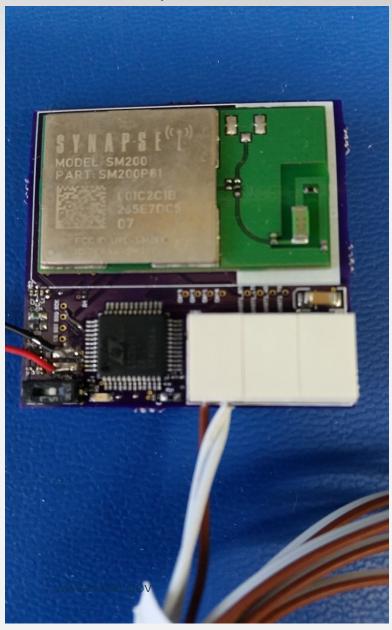


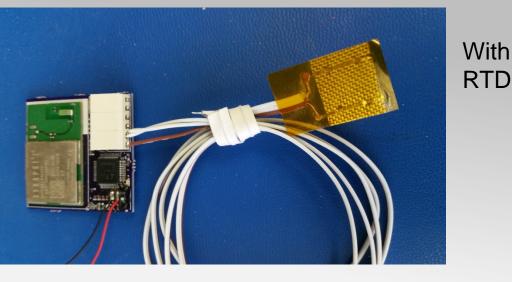


### BLOCK DIAGRAM WIRELESS STRAIN GAUGE www.nasa.gov



#### Wireless Temp Board



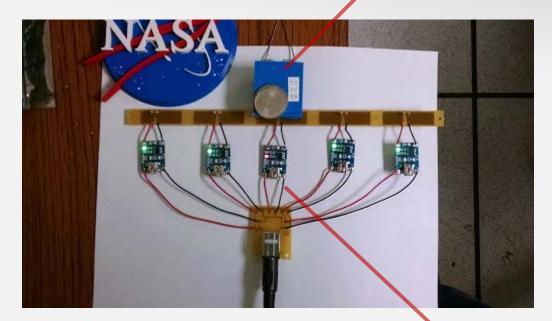


#### Can measure :

- virtually all standard (type B,
  - E, J, K, N, S, R, T) or custom thermocouples.
- Automatically compensate for cold junction temperatures and linearize the results.
- 2-, 3-, or 4-wire RTDs.
- Thermistors.
- Diodes.
- SPI bus controlled.

3-D printed (additive manufactured) casing for the 5-bay charging system was designed and created. Same as the blue housing for sensor node.

This is one wireless module on charging circuit. Charging bay has room for 5 modules.

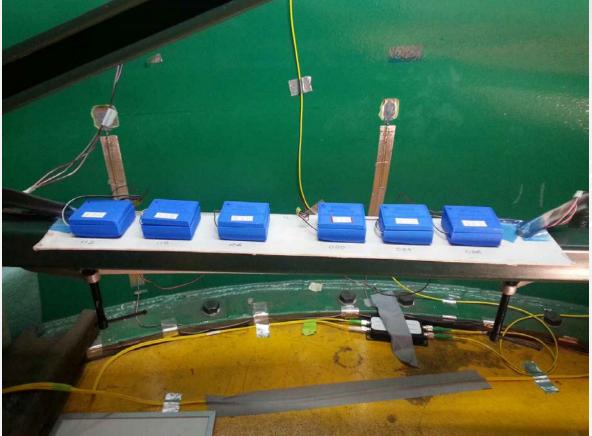


Commercial charging nodes , are specific for charging and preventing over charging of Li-ion batteries.



Composite Shell Buckling Test

# 20 – 1 Channel MSFC Wireless Sensor inside Composite shell



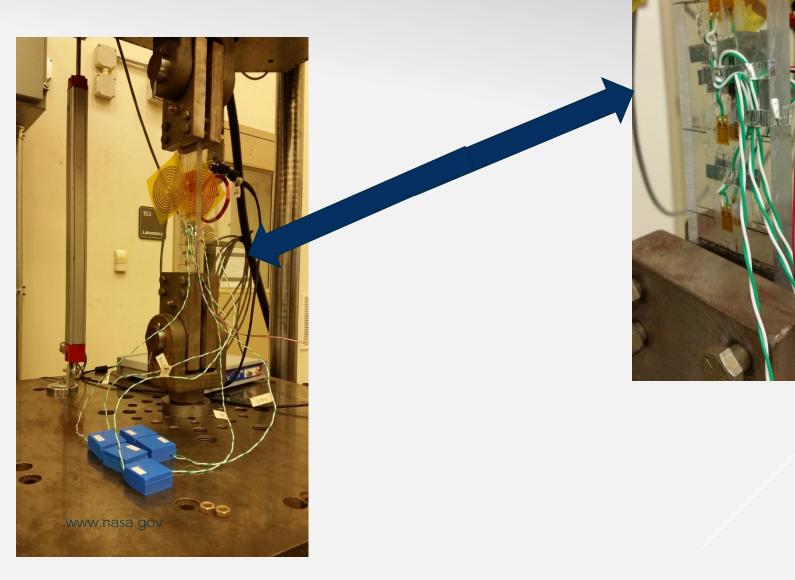
Synapse P	ortal: default.s	wn - Workspace	C:\Users\kvarnav	a\Documents\Portal

File View Ontions Network Hel

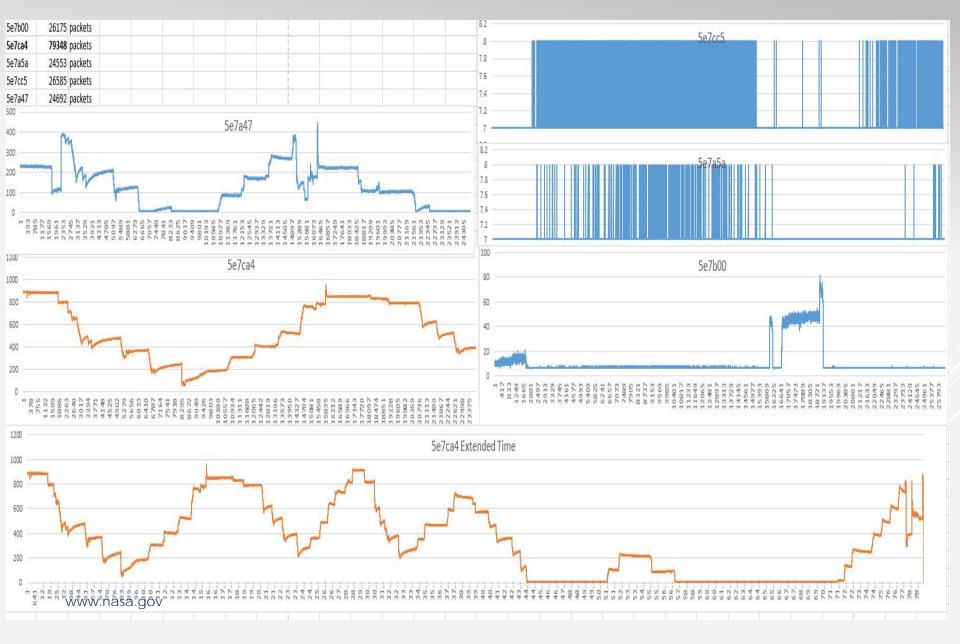
File View Optic	ns Network Help							
🖉 🗀 🐚 💉	🧖   🚠 🛐 📃 🖿	🛩 此 💿 🏦						
Node Views $\times$	Master_Node_Logger	.py BridgeNodeBroa	adcaster.py	BridgeNode1.py	Node In			
🔲 🗄   🗟 🥥	Active Nodes 🔻 2	23 nodes			🔊 🤪 🐔	🕏 🛃 🛃 🥵	1 👘 🗉 🗙 🤣 🕭	
Node	Network Address	Device Image	Link Quality	Device Type	Brid	lae		
🚔 Portal	00.00.01	Master_Node_Logg		Portal	Dire			
후 Bridge	5C.DB.98	BridgeNodeBroadc	68%	None			n: 2.4.22 with AES-128 (Out of Da	
Rode19	5E.79.A9	MSFC_Strain_1-Cha	79%	None		Platform:	RF200	<u>BridgeNodeBroadcaster</u>
🖗 Node14	5E.79.C3	MSFC_Strain_1-Cha	6%	None		Network Address	s: 5C.DB.98	broadcastValue(val)
🖗 Node10	5E.79.FA	MSFC_Strain_1-Cha	76%	None		MAC Address:	00:1C:2C:1B:26:5C:DB:98	EnableBroadcast(En)
🖗 Node20	5E.79.FE	MSFC_Strain_1-Cha	76%	None		Device Image:	BridgeNodeBroadcaster	<pre>startupEvent() &lt; Startup</pre>
Node18	5E.7A.33	MSFC_Strain_1-Cha	76%	None		-		timerEvent() < 1s Timer
🖗 Node8	5E.7A.47	MSFC_Strain_1-Cha	71%	None		Image CRC:	0xE800	BuiltIn
🖗 Node5	5E.7A.5A	MSFC_Strain_1-Cha	6%	None		Image Size:	1914 bytes (3%)	pinWakeupATmega128RFA1
🖗 Node7	5E.7A.5B	MSFC_Strain_1-Cha	75%	None		License:	Permanent	
Node16	5E.7A.94	MSFC_Strain_1-Cha	80%	None		Channel:	4	
Node4	5E.7B.00	MSFC_Strain_1-Cha	72%	None			1 1 6 2 6	
Node3	5E.7C.A4	MSFC_Strain_1-Cha	58%	None		Network ID:	0x1C2C	
Node11	5E.7C.C5	MSFC_Strain_1-Cha	6%	None		Path		
Node15	5E.7C.CA	MSFC_Strain_1-Cha	67%	None				
Node23	5E.7C.D3	MSFC_Strain_1-Cha	74%	None				
Node22	5E.7C.D5	MSFC_Strain_1-Cha	67%	None				
Node 🖗	5E.7D.11	MSFC_Strain_1-Cha	70%	None				
Node6	5E.7D.6C	MSFC_Strain_1-Cha	74%	None				
Node21	5E.7D.96	MSFC_Strain_1-Cha	71%	None				
🖗 Node9	5E.7D.9C	MSFC_Strain_1-Cha	6%	None				
Node17	5E.7D.85	MSFC_Strain_1-Cha	68%	None				
Node12	5E.7D.86	MSFC_Strain_1-Cha	68%	None			h information collected	
						Info		
						In your Portal scri		
						remoteNode.setC to display informa	Column(name, value)	
						to display informa	ation here	
Event Log								
Time	Event Dev					Value		
2016-05-12 14:43:36	· ·	Network ID						
	NV PARAM Node19		s 00:1C:2C:1B:2	5:5E:79:A9				
2016-05-12 14:43:36		SNAPpy Space						
2016-05-12 14:43:36	NV PARAM Node19	Device Type	None					
Ready				www.synapse-wireless.	.com	R	RPCs in Queue: 0	Connected: USB0 [38400]

Control GUI – Large amount of interference caused all of the nodes to drop out shortly after test began. The test article was in a safety keep out zone so there was no way to fix or restart with fewer nodes after testing started.

## Test Lab Pull Test July 2016 Setup



## Test Lab Pull Test July 2016 Data Results





#### Better Battery and Power Management

Calibration shunt that can be switched in and out of circuit by software.





# Coming In Gen 3

Advanced Software Controls



- Kosta Varnavas ES36
  - <u>kosta.varnavas@nasa.gov</u>
  - 256-544-2638
- Jeff Richeson ES35
  - James.j.richeson@nasa.gov
  - > 256-961-0128

# **Back Up Charts**

## SM200 Specifications

Table 1.0 Sp	ecifications	SM200P81/PU1	RF200P81/PU1			
	Outdoor LOS Range	Up to 1500/2500 feet at 250Kbps				
Performance	Transmit Power Output	3 dBm				
Ferrormance	RF Data Rate	250Kbps, 500Kbps, 1Mbps, 2Mbps				
	Receiver Sensitivity	-100 dBm (1% PER, 250Kbps)				
	Supply Voltage	1.8 - 3.6 V				
Power	Transmit Current (Typ@3.3V)	22.5 mA				
Requirements	Idle/Receive Current (Typ@3.3V)	20.5 mA				
	Power-down Current (Typ@3.3V)	0.37 μA				
	Frequency	ISM 2.4 GHz				
	Spreading Method	Direct Sequence (DSSS)				
General	Modulation					
General	Dimensions	29.8mm x 19mm	33.86mm x 33.86mm			
	Operating Temperature	- 40 to 85 deg C.				
	Antenna Options	Integrated Chip Antenna / External Antenna				
	Topology	SNAP				
Networking	Error Handling	Retries and acknowledgement				
	Number of Channels	16				
Available I/O	UARTS with HW Flow Control	2 Ports - 8 total I/O				
	GPIO	38 total; 7 can be analog- in with 10bit ADC	20 total; 7 can be analog- in with 10bit ADC			
Agency	FCC Part 15.249	FCC ID: U9O-SM200	FCC ID: U9O-SM200			
Agency Approvals	Industry Canada (IC)	IC: 7084A-SM200	IC: 7084A-SM200			
	CE Certified	Yes	Yes			

# **Generation 2**

#### Only 1 Gauge

 Another version coming with 3 gauges for 3-dimensionl measurements

Each strain gauge has an independent constant voltage regulator driving the excitation voltage

• This provides solid voltages for more accurate measurements.

#### Power Management Hardware

 The power for each gauge sub circuit can be turned on or off by software saving battery power.

#### Op Amp has much larger and adjustable gains

- Gains up to 1000 and is variable under
- software control via digital potentiometer.

Power Management Software

Software can control power management
www.fahardware to maximize battery life.



## DRAWBACKS TO HARDWIRED SPACECRAFT BUS ARCHITECTURES

Failures of wires and connectors

Mass of cabling and electrical interfaces

High cost of late design changes in hardwired bus architectures; DFI change costs

Development time overhead for allocating routes and places, shields, connectors, brackets, cable trays, fasteners, supporting structure, etc.

Physical restrictions on wired sensor placements (tankage, bulkhead penetrations, etc)

Undesired ground loops on the communication paths; long wire runs acting as antennas

Electromagnetic compatibility issues (EMC), crosstalk, solar flux across wires

(from Amini, et al 2007)

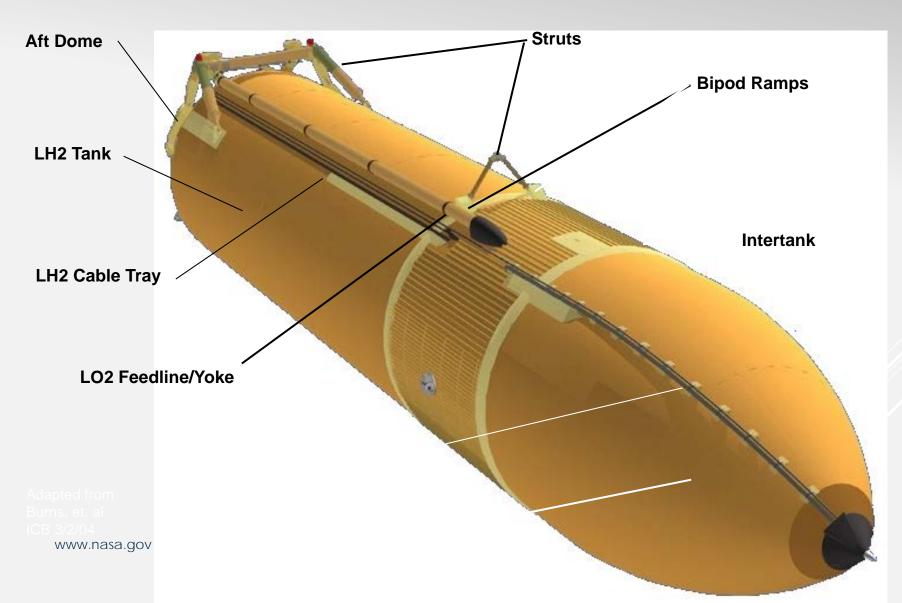


## TILES DURING INSTALLATION ON THE SPACE SHUTTLE

Note grouping of tiles by array



## ET CAPABILITIES & CONSTRAINTS



## SPACE SHUTTLE DURING REENTRY

The tiles prove to be "one of the most successful subsystems on the Orbiter."

-- Aaron Cohen, Orbiter Project Manager

Success of the tiles is a tribute to Robert Beasley, Inventor

www.nasa.gov



http://www.lr.tudelft.nl/live/binaries/72bd2130-888f-4040-8997-fb2245aa24a2/doc/Delft\_

### **Wireless Sensors for Automobiles**

Measure strain, torque, displacement, temperature, acceleration & orientation



