



Global Soil Moisture Estimation from L-Band Satellite Data: Impact of Radiative Transfer Modeling in Assimilation and Retrieval Systems

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Global Modeling and Assimilation Office (Code 610.1), NASA/GSFC, Greenbelt, MD, USA

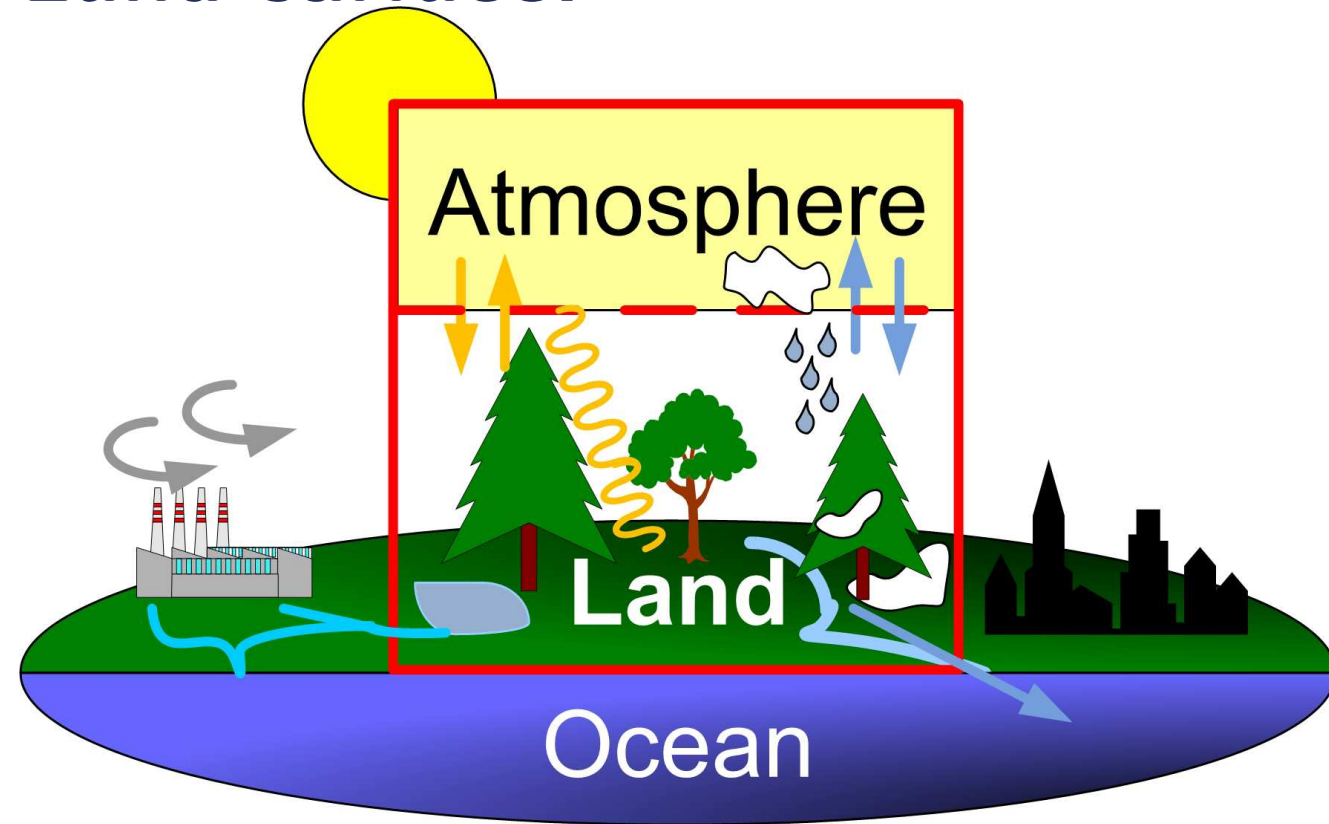
University of California, Irvine, Department of Civil and Environmental Engineering, Irvine, CA, USA

ISPA, INRA Bordeaux, France

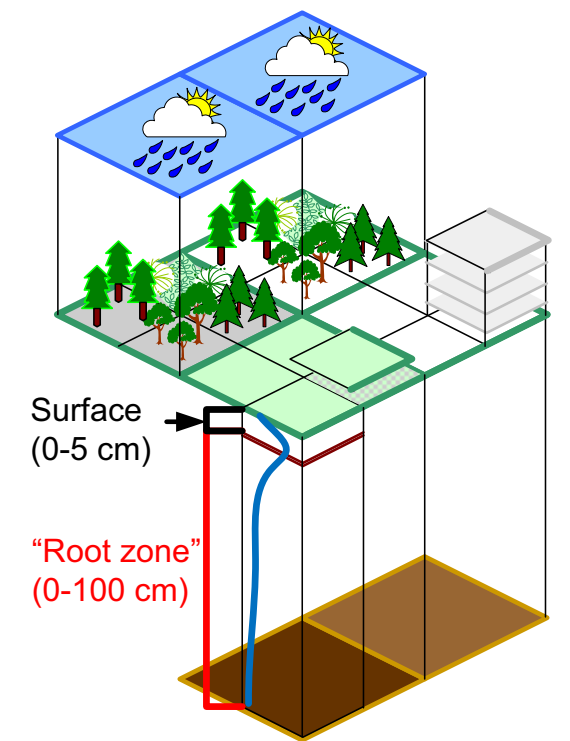
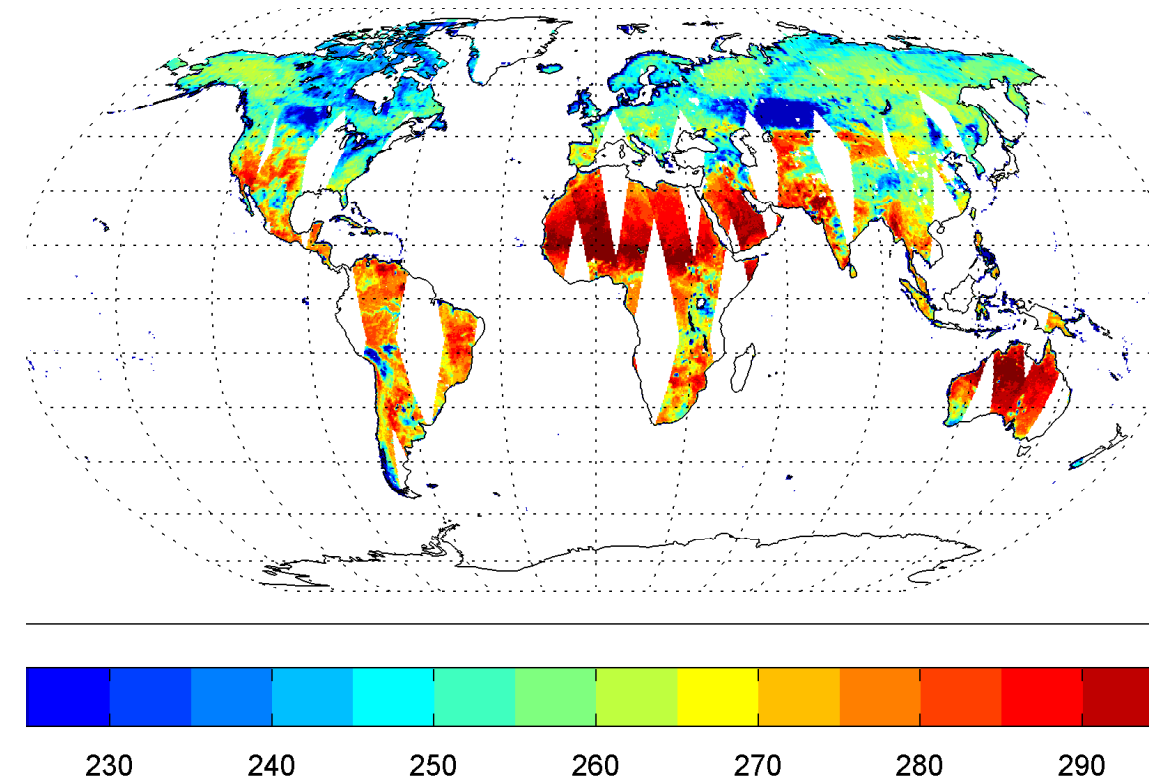
5 April 2018

- System
- System
- L-band
- SMOS Retrieval
- SMOS Assimilation
- Conclusions

Land surface:



Observing and modeling:



KU Leuven HPC Tier2:



- System
- L-band
- Data**
- Model
- Parameters
- Complexities
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L-band (1.4 GHz) brightness temperatures (T_b) are sensitive to soil moisture and temperature in the surface layer (5 cm)

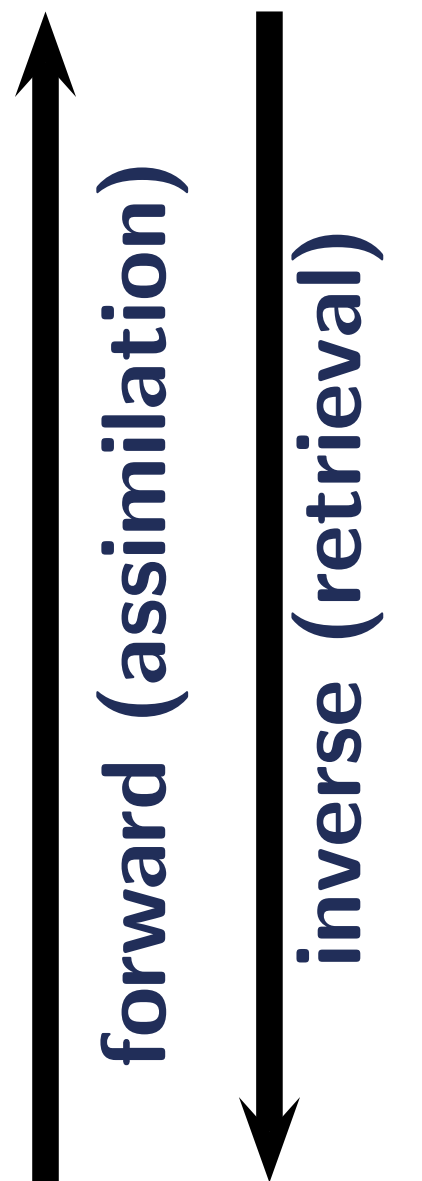


brightness temperature



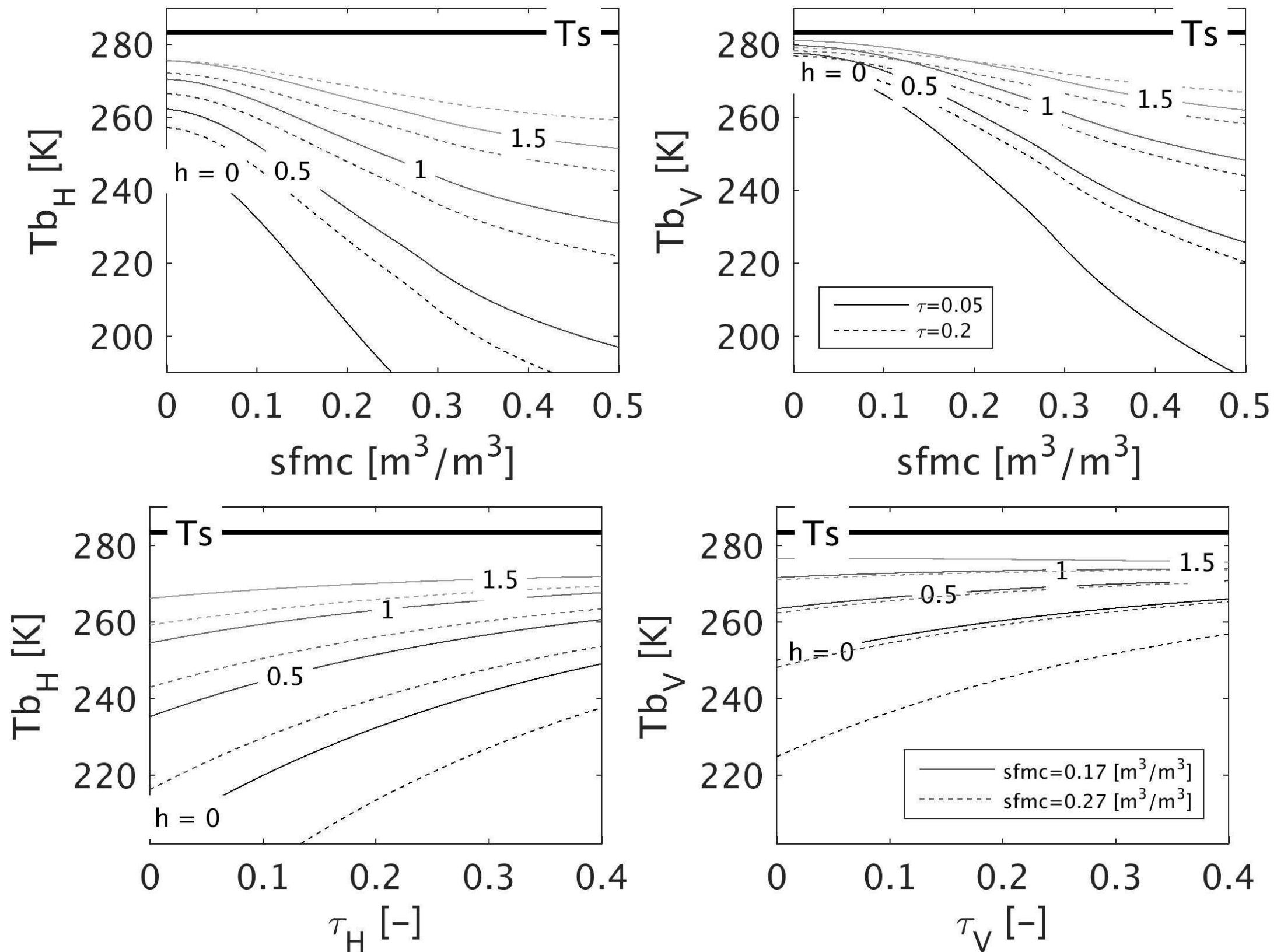
RTM (parameters)

- soil temperature
- soil moisture
- vegetation



L-Band Radiative Transfer Modeling

- System
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Tb increases with drier soil moisture (sfmc)

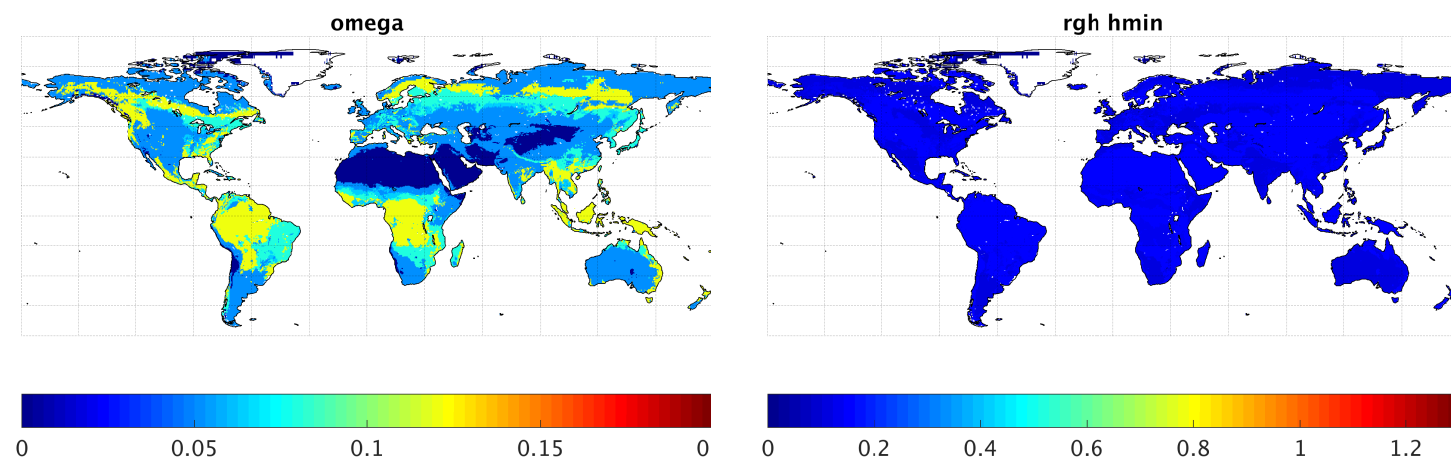
Tb increases with more vegetation (τ)

Tb strongly depends on parameters (e.g. h, roughness)

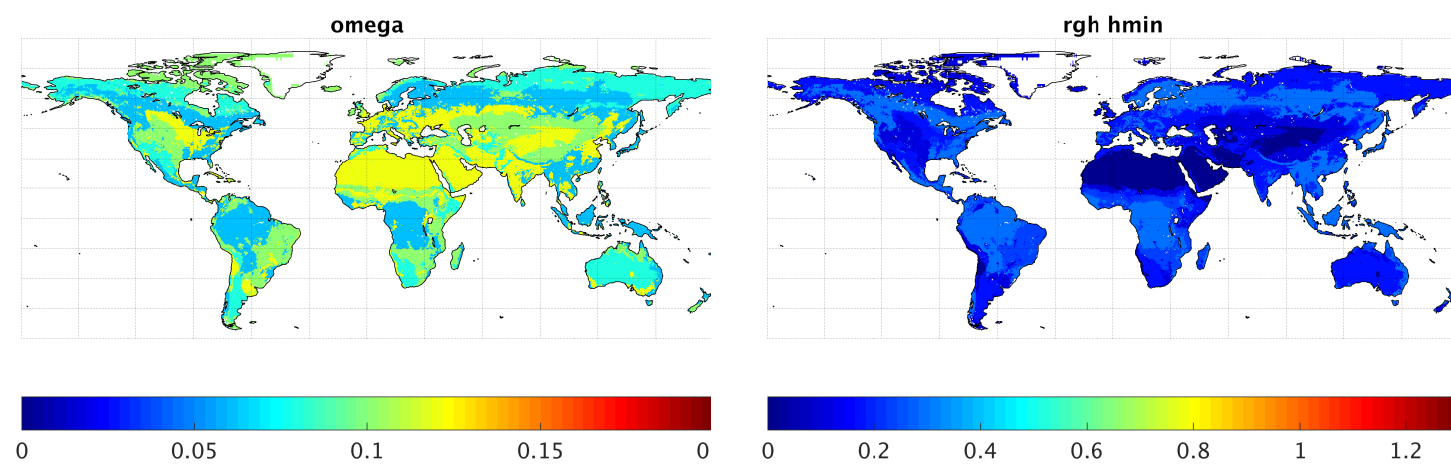
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Lookup tables: per vegetation class

SMAP L2



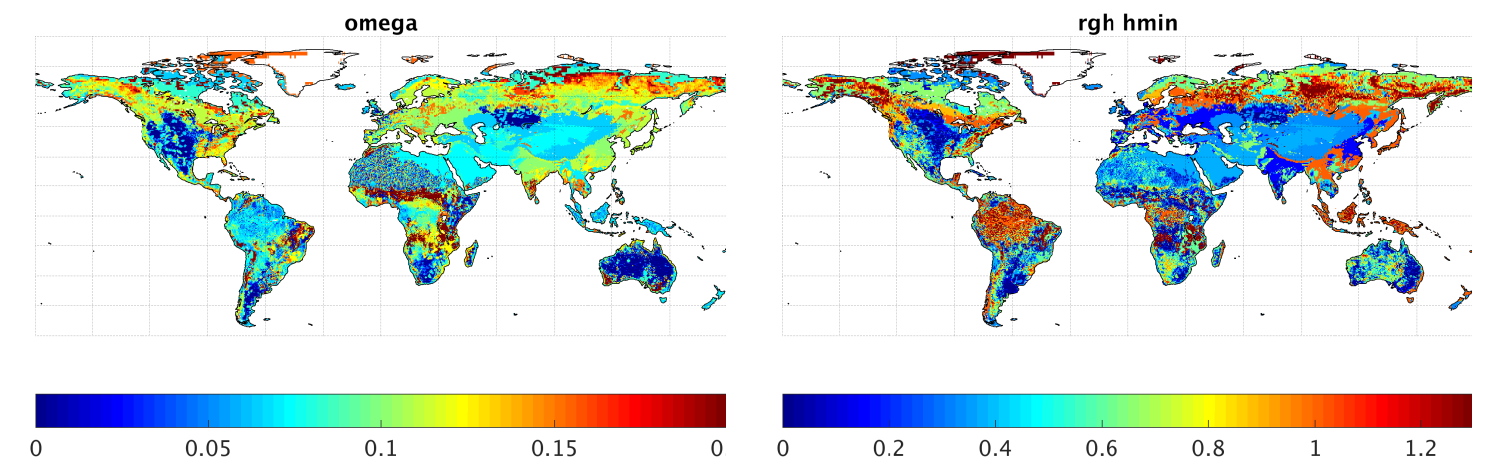
SMOS IC



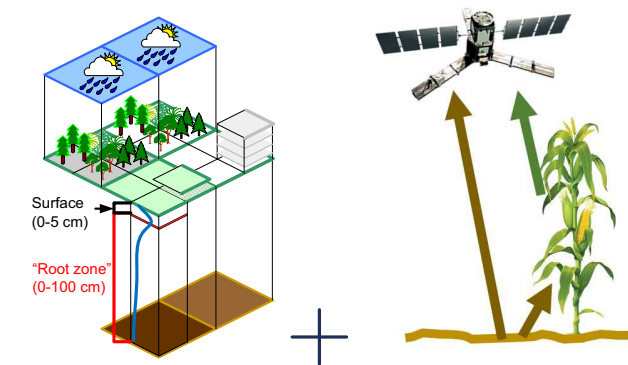
- Based on field experiments; optimizing retrievals vs in situ soil moisture
- Can this also be used for forward modeling (DA experiments)?

Calibrated: per grid cell

SMAP L4



- Based on optimizing SMOS Tb versus simulated Tb, using simulated soil moisture (De Lannoy et al., 2013, 2014)



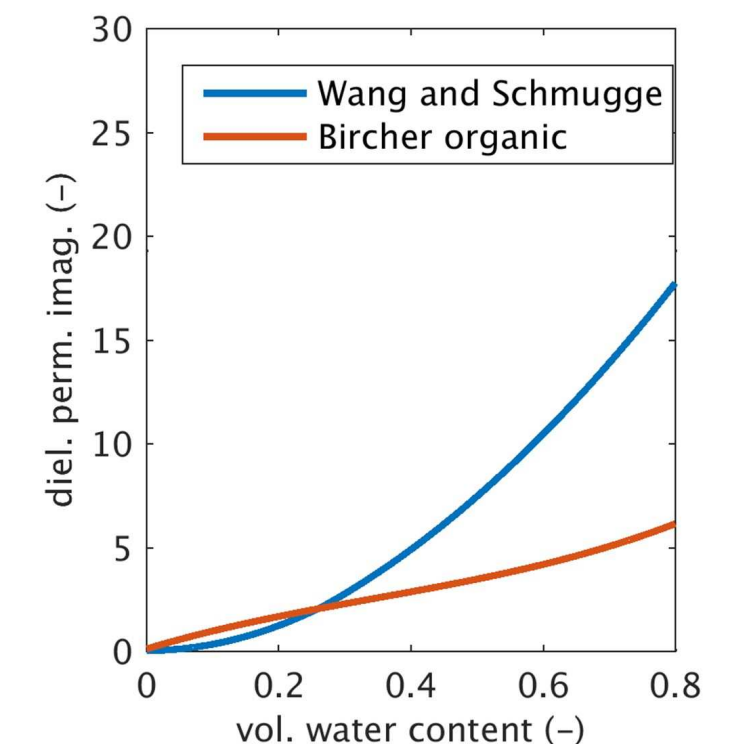
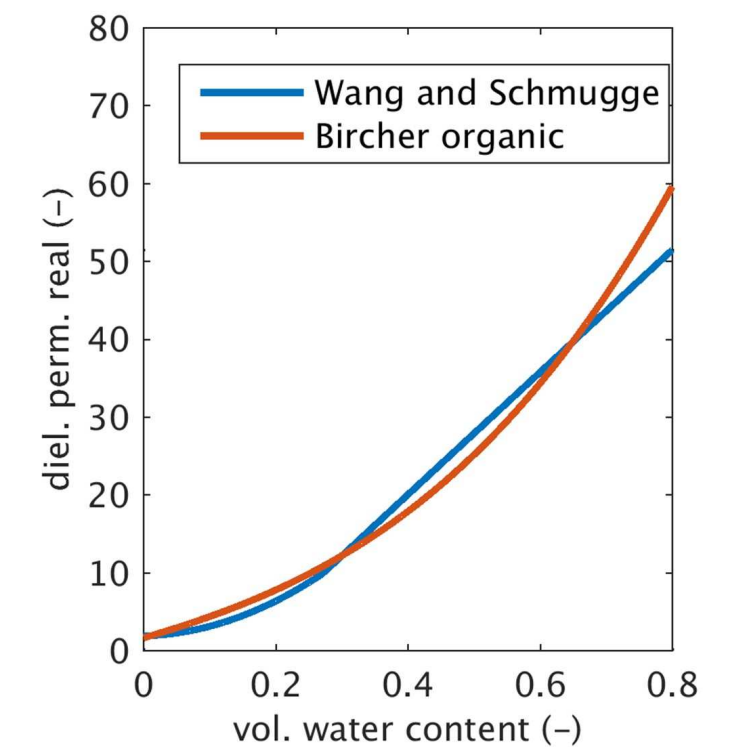
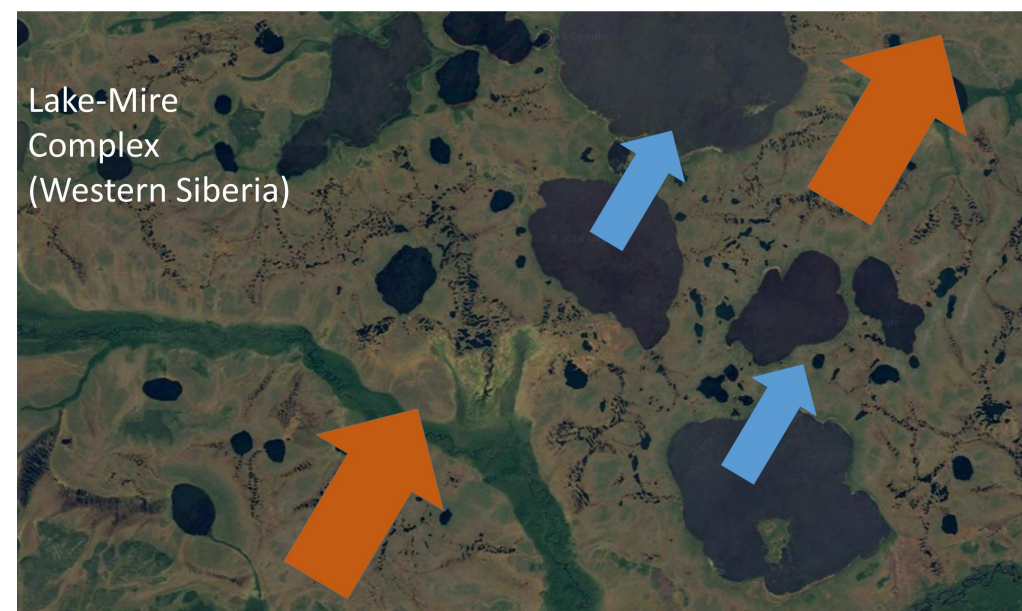
- Can this also be used for inverse modeling (retrievals)?

Enhance the RTM for specific land cover types, e.g. peatlands:

- **Soil moisture dynamics:**
improved physical processes in peatland
- **RTM w/ dielectric model:**
Wang & Schmugge (1980) for mineral soils versus Bircher et al. (2016) for organic soils
- **Open water:**
incl. open water reduces bias in Tb forward modeling

$$Tb = f_{land} \cdot Tb_{land} + f_{SOW} \cdot Tb_{SOW} + f_{DOW} \cdot Tb_{DOW}$$

land + static (land mask) + dynamic open water (AMSR2)

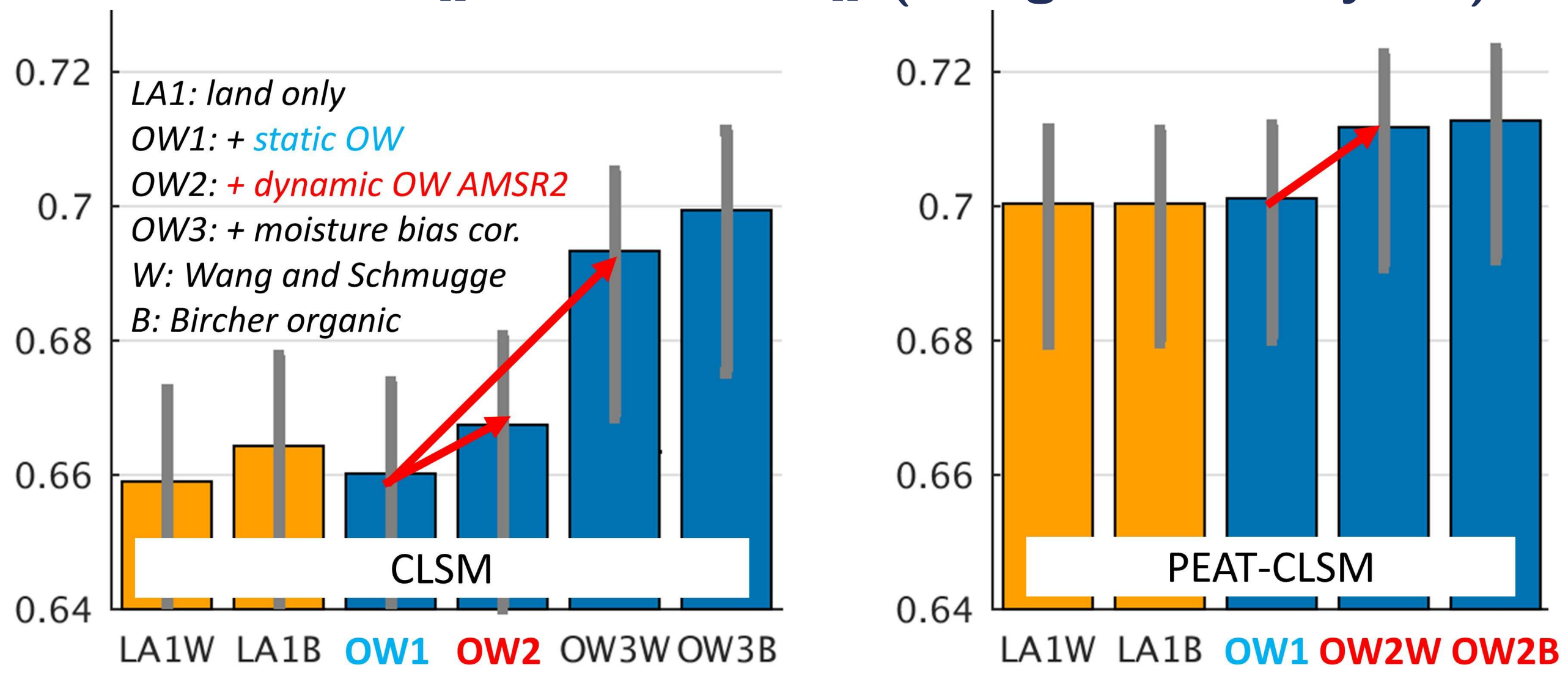


(Michel Bechtold, Simon De Canniere)

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Time series correlation [-]
simulated Tb_H vs SMAP Tb_H (210 grid cells, 2 years)



- Dielectric model only has minor impact (Bircher vs Wang & Schmugge)
- PEAT-CLSM outperforms CLSM for both soil moisture and Tb simulations
- Adding dynamic open water fraction further improves the results

System

L-band

SMOS Retrieval

Retrieval

SM

VOD

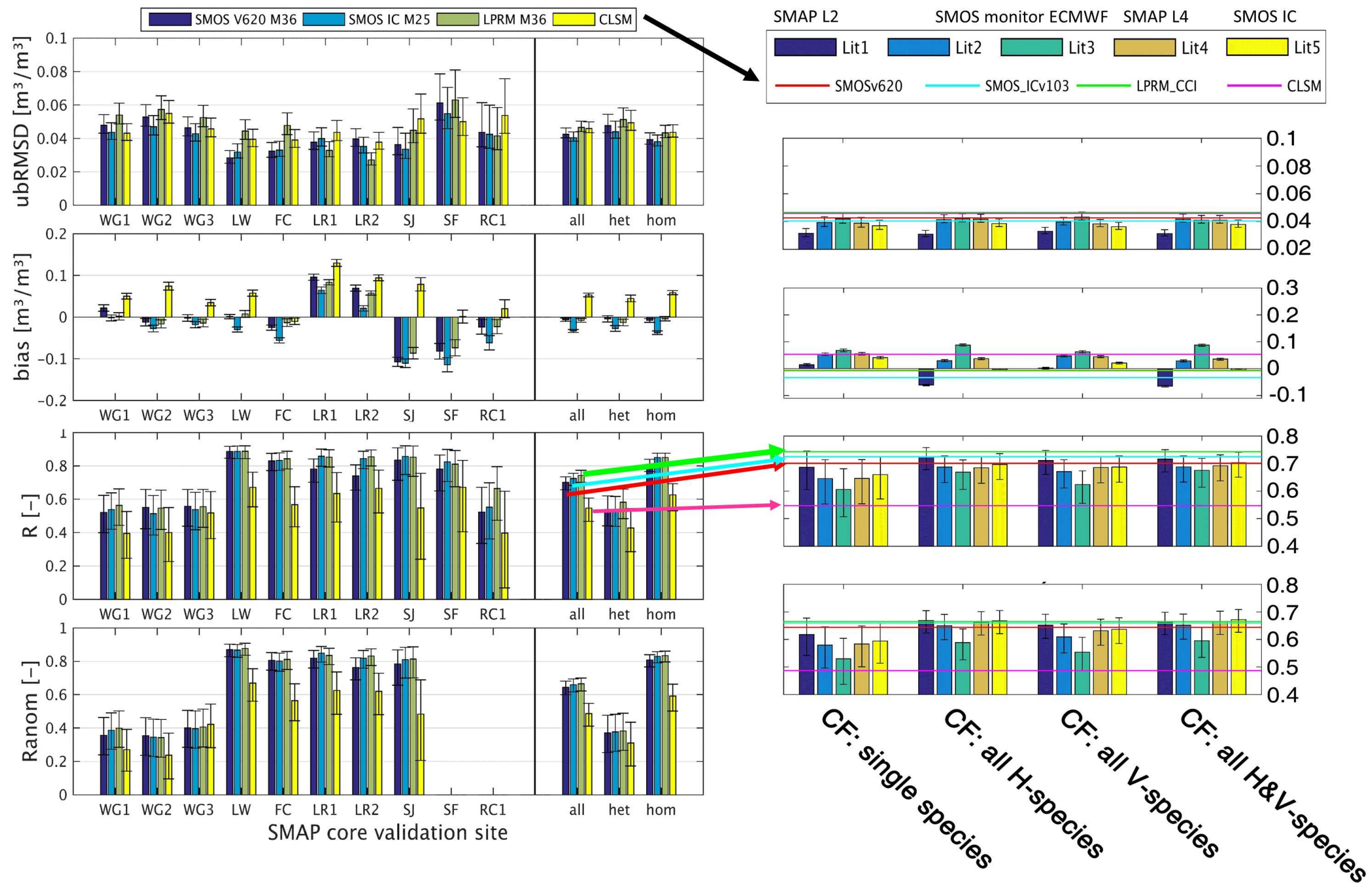
SMOS Assimilation

Conclusions

SMOS Retrievals

- SMOS (quasi-)operational retrieval products:
 - ◆ **SMOS L2/L3**
 - only retrieval for nominal fraction, low vegetation/forest
 - $(SM, VOD) = f(Tb^{SMOS}, MODIS\ LAI, ECMWF\ T_s, Tb_{notnominal}^{ECMWF}, RTM)$
 - ◆ **SMOS-IC** (*Fernandez-Moran et al., 2017*)
 - homogenous pixels
 - $(SM, VOD) = f(Tb^{SMOS}, ECMWF\ T_s, RTM)$
 - ◆ **SMOS-LPRM** in ESA CCI
 - homogenous pixels
 - $VOD = f(MPDI^{SMOS}, \omega)$, and $SM = f(Tb^{SMOS}, VOD, model\ T_s, RTM)$
- **SMOS research products:** physically-based, neural network, various RTMs, ...
 - ◆ homogenous pixels
 - ◆ $VOD = f(Tb^{SMOS}, MERRA2\ T_s, MERRA2\ SM, RTM)$,
or $SM = f(Tb^{SMOS}, MERRA2\ T_s, MERRA2\ LAI, RTM)$

In situ validation (CaVal sites)

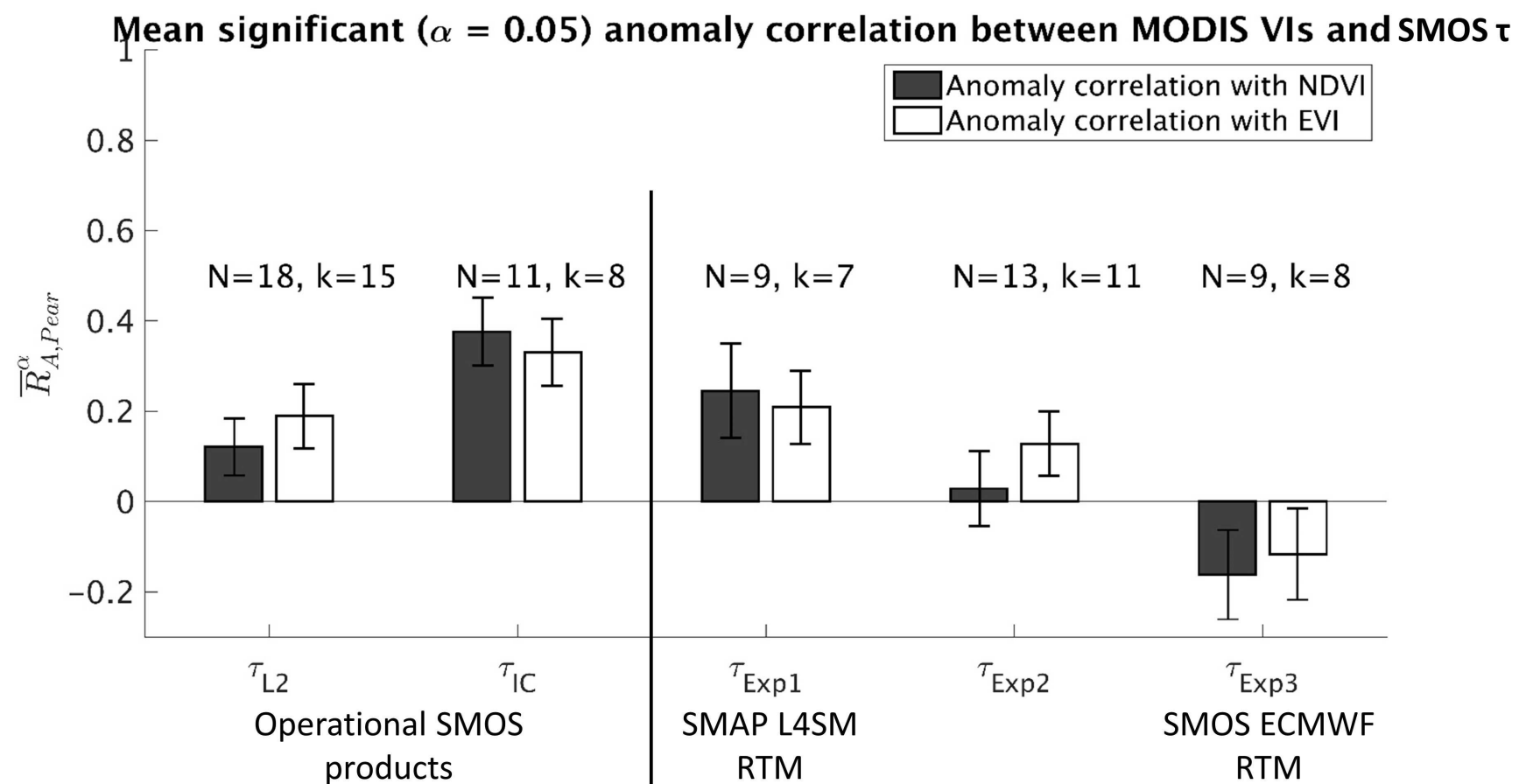


- all operational products do better than model simulations
- much simpler SMOS-IC product performs as good as complex SMOS L2

- RTM calibrated for forward modeling could serve for SM retrievals
- Lit3 (fwd modeling) is inferior for retrievals

Representative site evaluation (11 vegetation classes)

- System
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- Retrieval
- SM
- VOD**
- SMOS Assimilation
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- limited (anomaly) correlations: L-band VOD contains other information than optical vegetation indices (VI)
- SMOS-IC performs better than operational SMOS L2 (anomaly R)
- RTM calibrated for forward modeling could serve for τ retrievals
- Lit3 (fwd modeling) is inferior for retrievals

(Michiel Van Gompel)

System

L-band

SMOS Retrieval

SMOS Assimilation

Data assimilation

SM DA

Tb DA

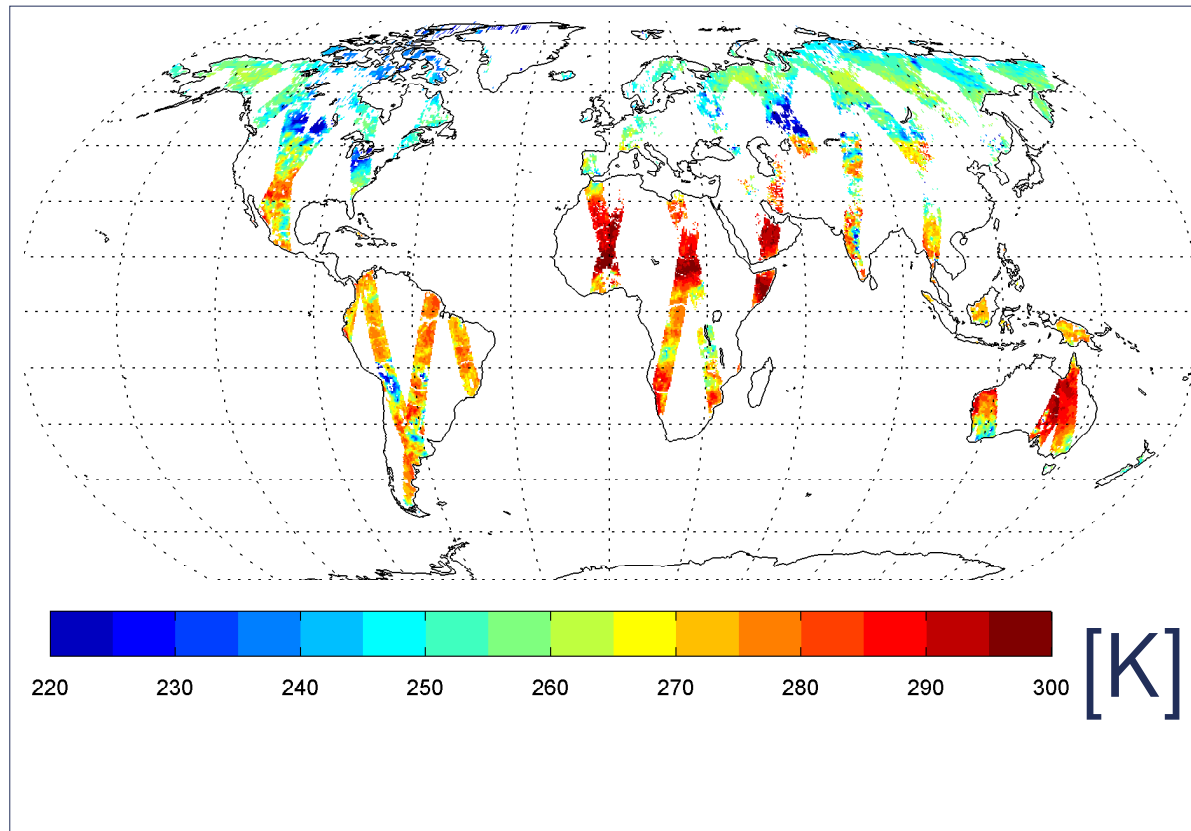
RTM impact

Conclusions

SMOS Data Assimilation

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SMOS Obs (footprint)

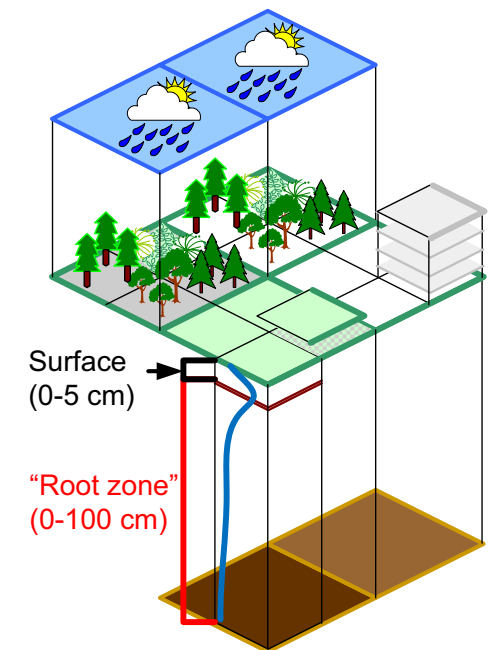


NASA GEOS-5 Land Surface Modeling (36 km)

- Catchment land surface model
- MERRA surface meteorology

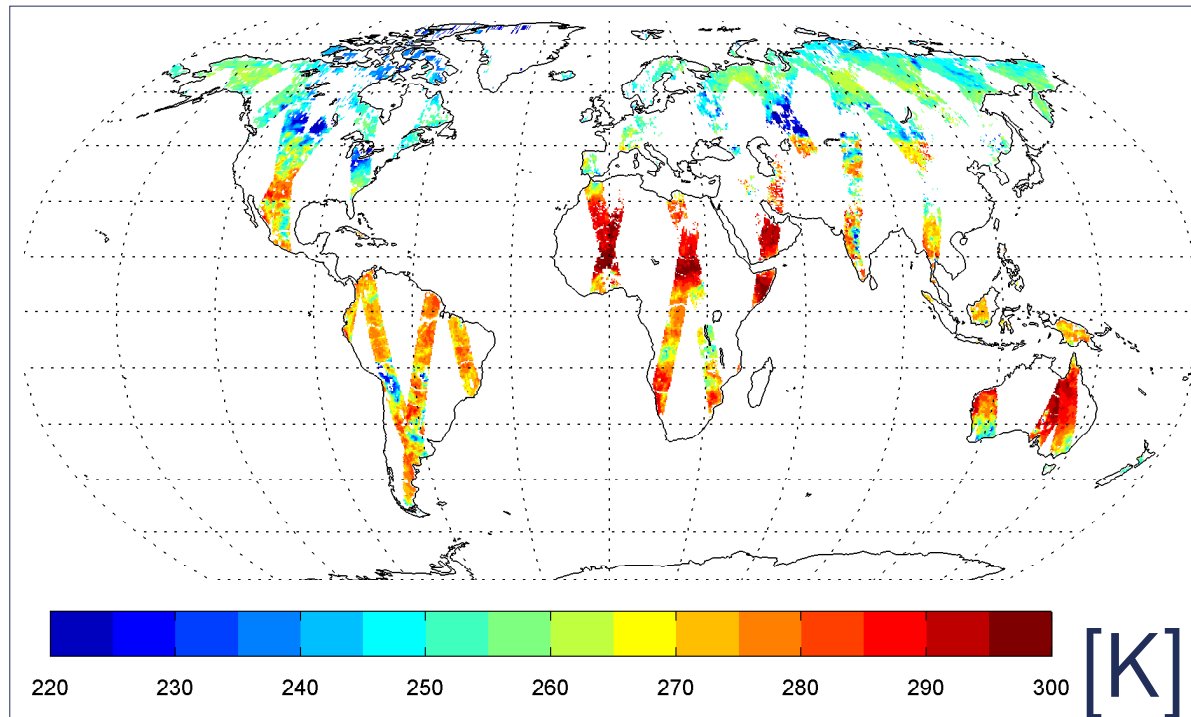
Observation operator:

- spatial aggregation
- radiative transfer model*
only in case of Tb assimilation



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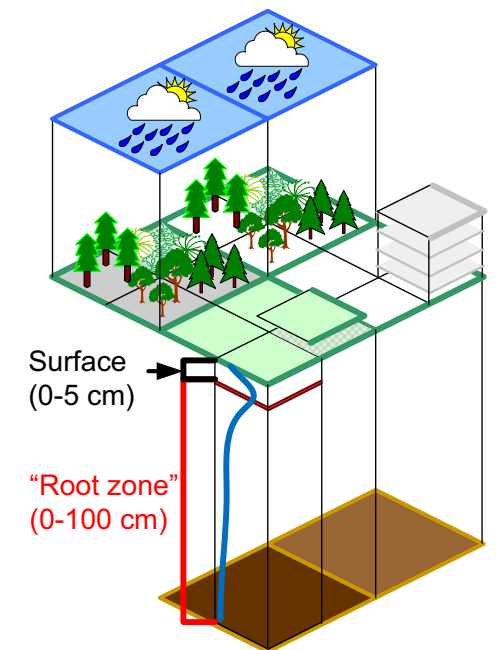
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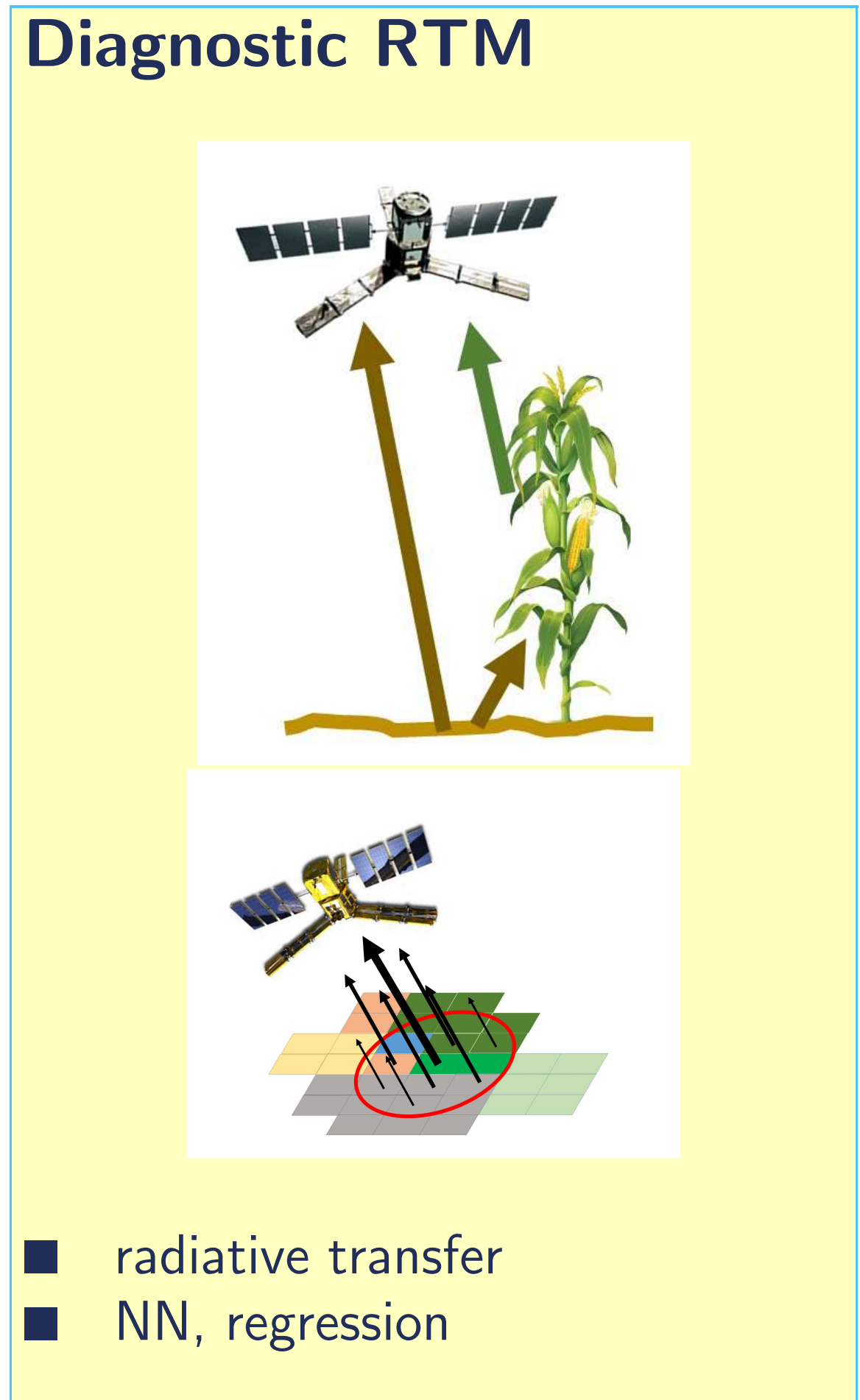
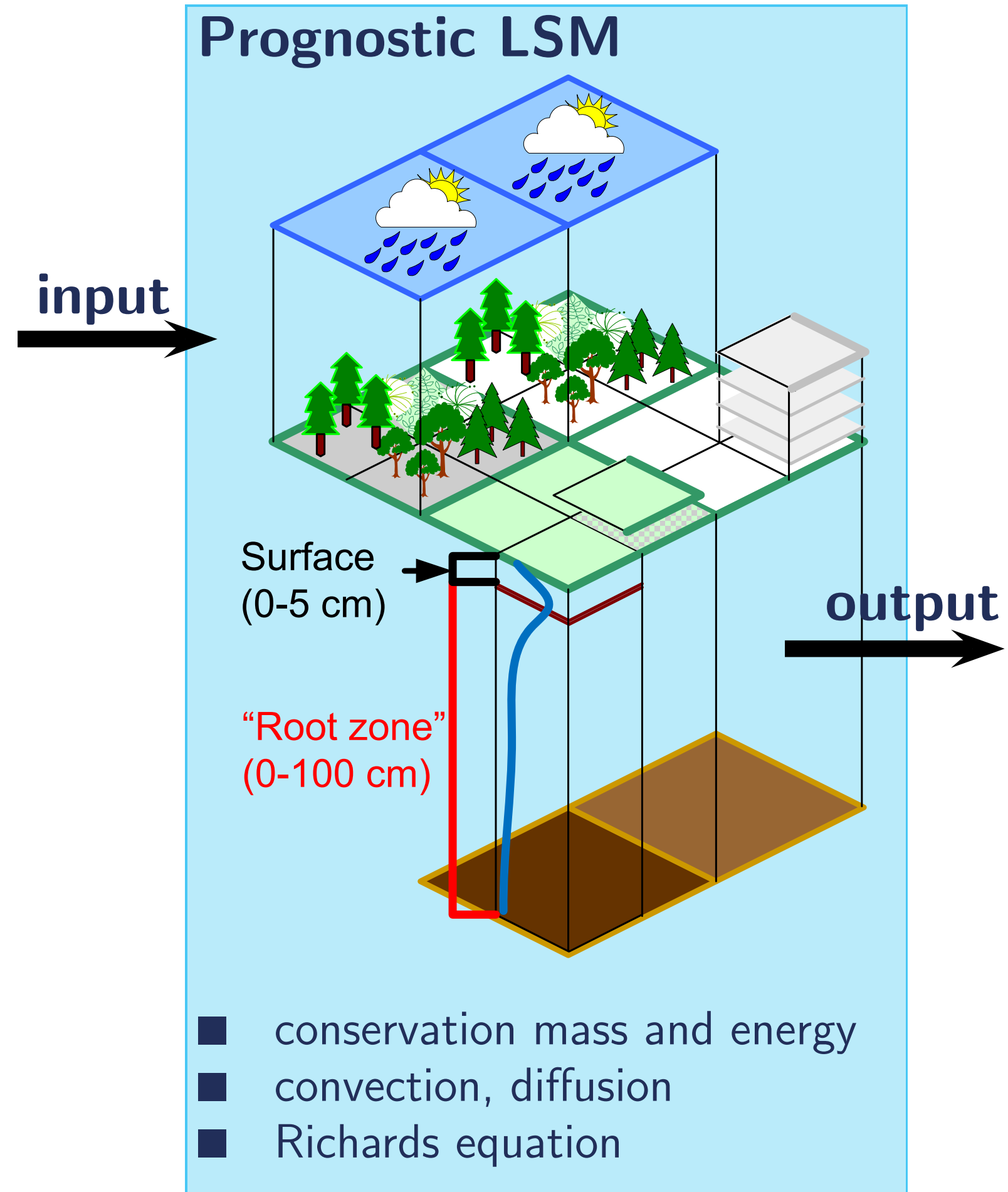


Data Assimilation

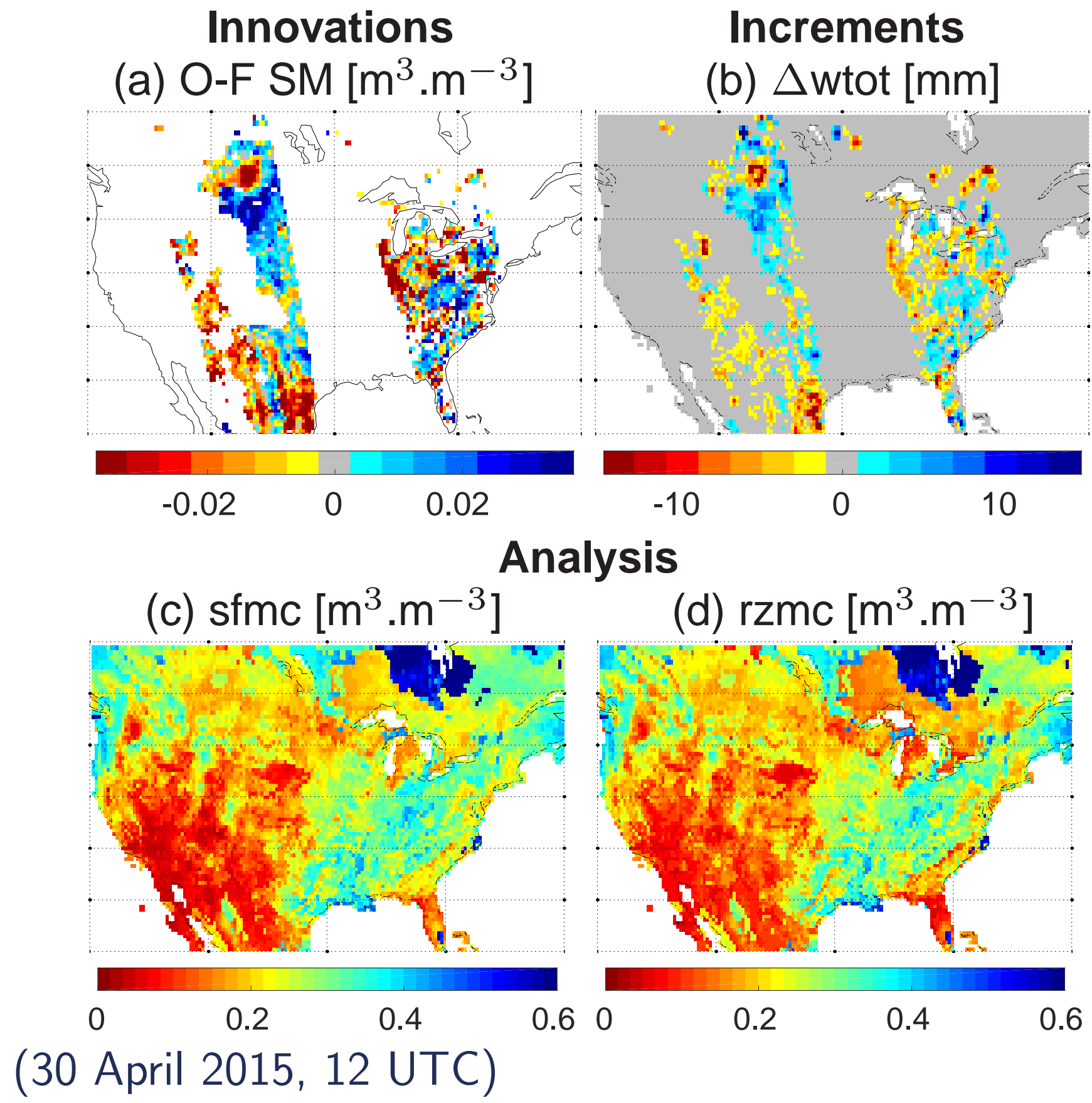
- 3D EnKF
- bias mitigation*
- filter parameters*

- Surface soil moisture (~ top 5 cm)
 - Root zone soil moisture (~ top 1 m)
 - Other consistent geophysical fields, with error estimates
- ⇒ * calibration using long-term SMOS record

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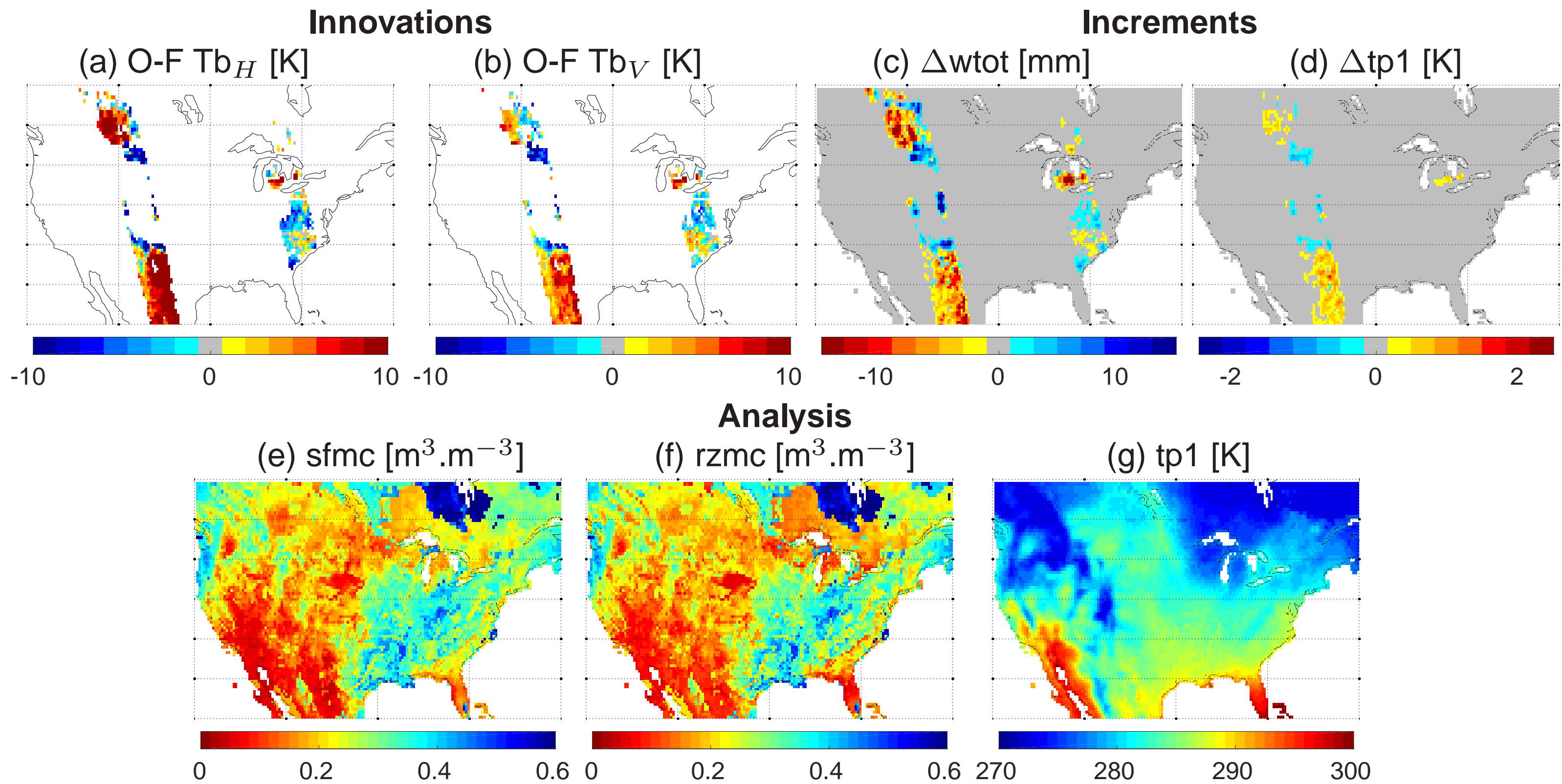
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- Observation-minus-forecast (O-F, innovation), footprint-scale
- Increment, model grid
- Analysis, model grid
- 3D EnKF: smooth transitions, no swath edges in analysis

Tb Data Assimilation

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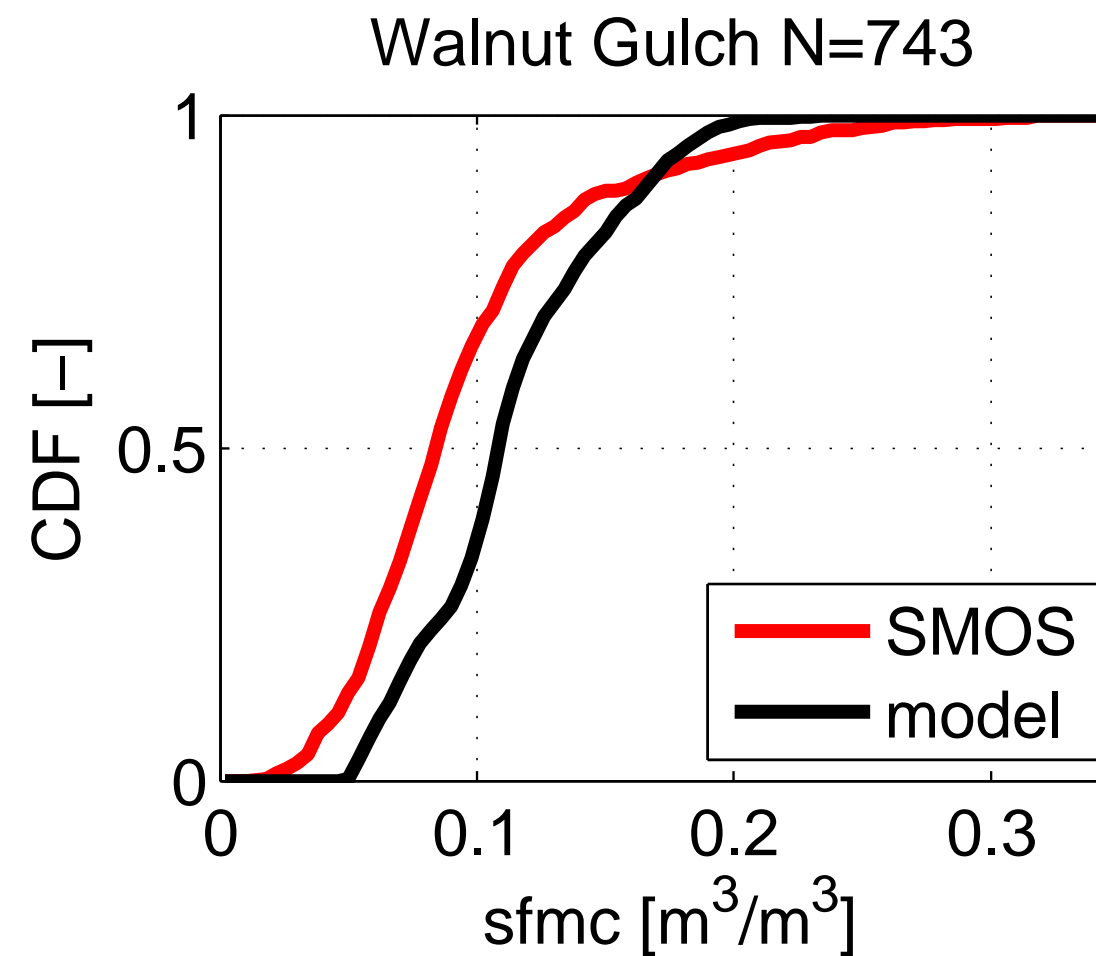


(30 April 2015, 12 UTC)

SM is relatively stationary

Example: at one location,

- **at any time**, replace an observed SM of $0.08 \text{ m}^3/\text{m}^3$ with a value of $0.10 \text{ m}^3/\text{m}^3$



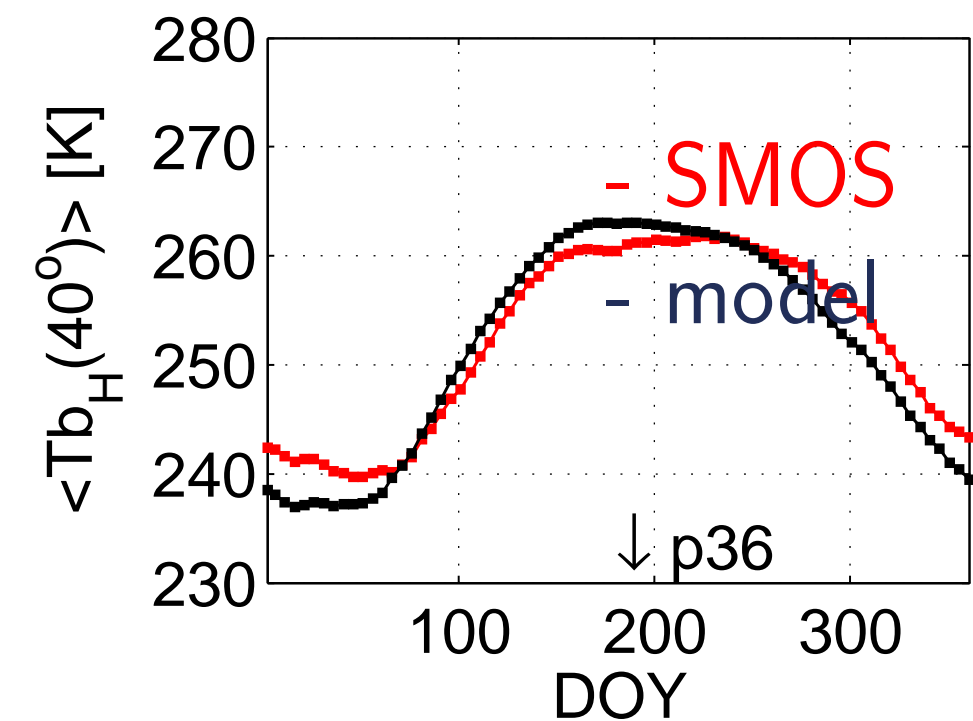
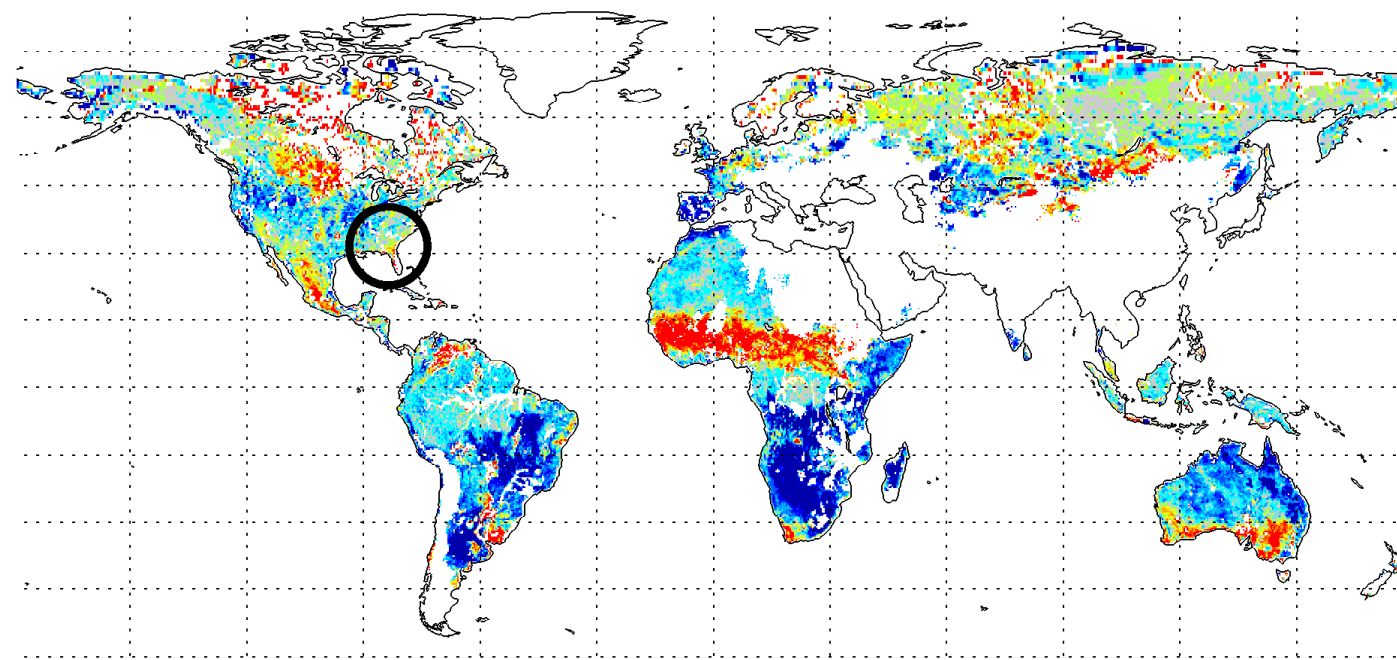
- CDF based on 5 years, all seasons
- separate rescaling for ascending (6 am) and descending (6 pm) times

Tb has a strong seasonal pattern

Example: at one location,

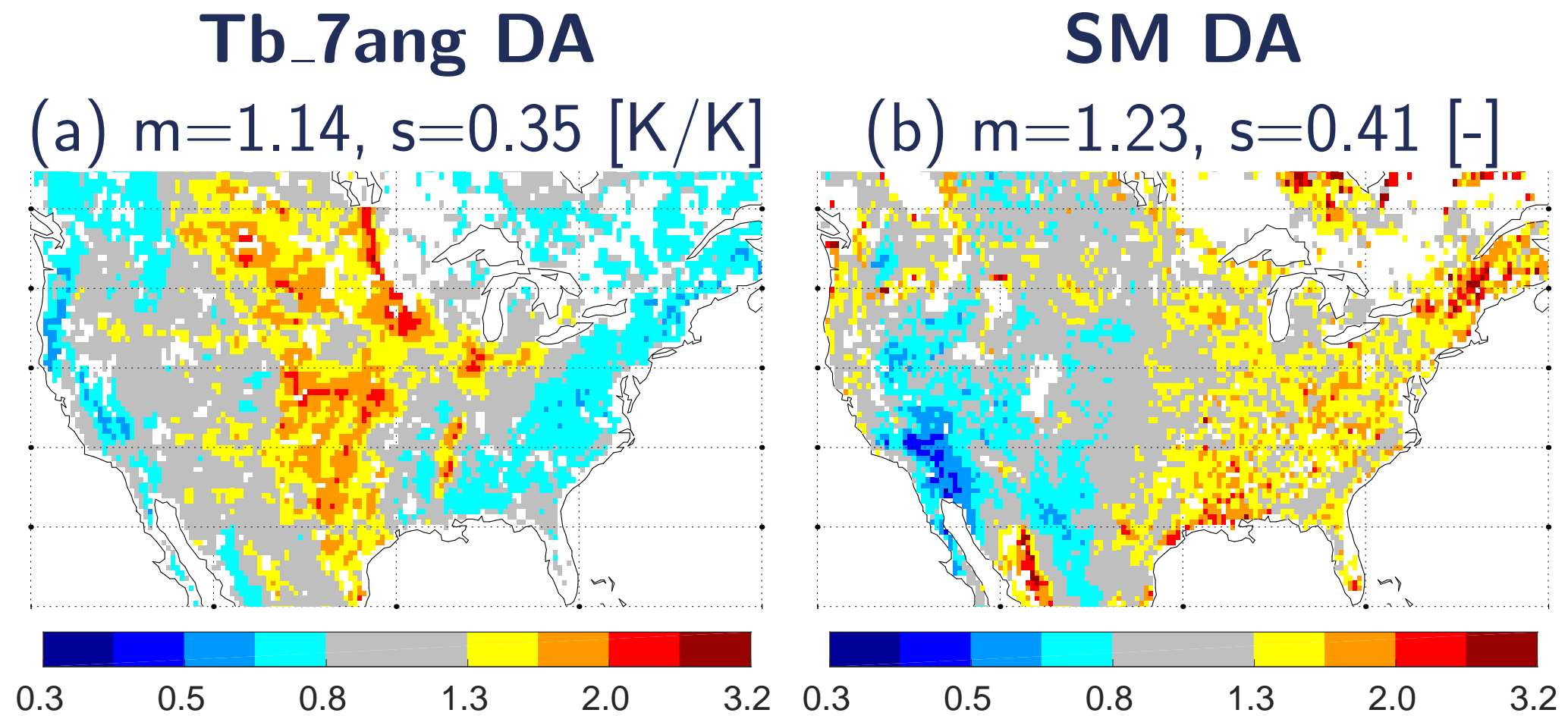
- **at pentad 7**, correct the observed Tb_H for a bias of 237-241 K
- **at pentad 36**, correct the observed Tb_H for a bias of 262-260 K
- **at pentad ...**, correct ...

model-SMOS $\langle Tb_H(40^\circ) \rangle$ [K], Asc, pentad 36 Little River



- mean-only, 5 year-average, per pentad
- separate rescaling for ascending (6 am) and descending (6 pm), 7 angles, 2 polarizations

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$$\text{std}(\mathbf{O}-\mathbf{F} / \sqrt{\sigma_F^2 + \sigma_O^2}),$$

with σ_F^2 and σ_O^2 determined by DA design parameters (ensemble perturbations).

Target value = 1

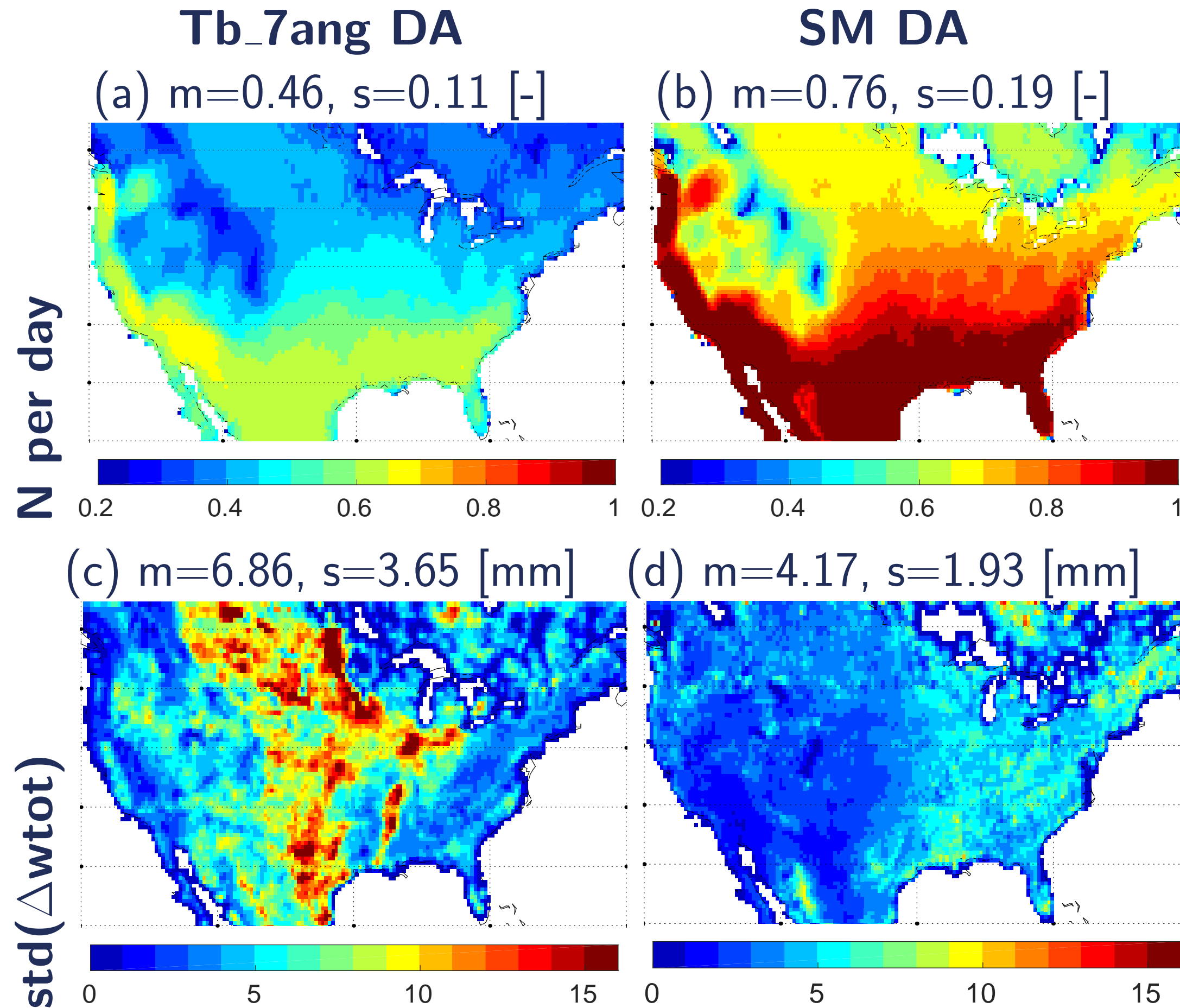
< --- DA system --- >

overestimates

underestimates

actual uncertainty

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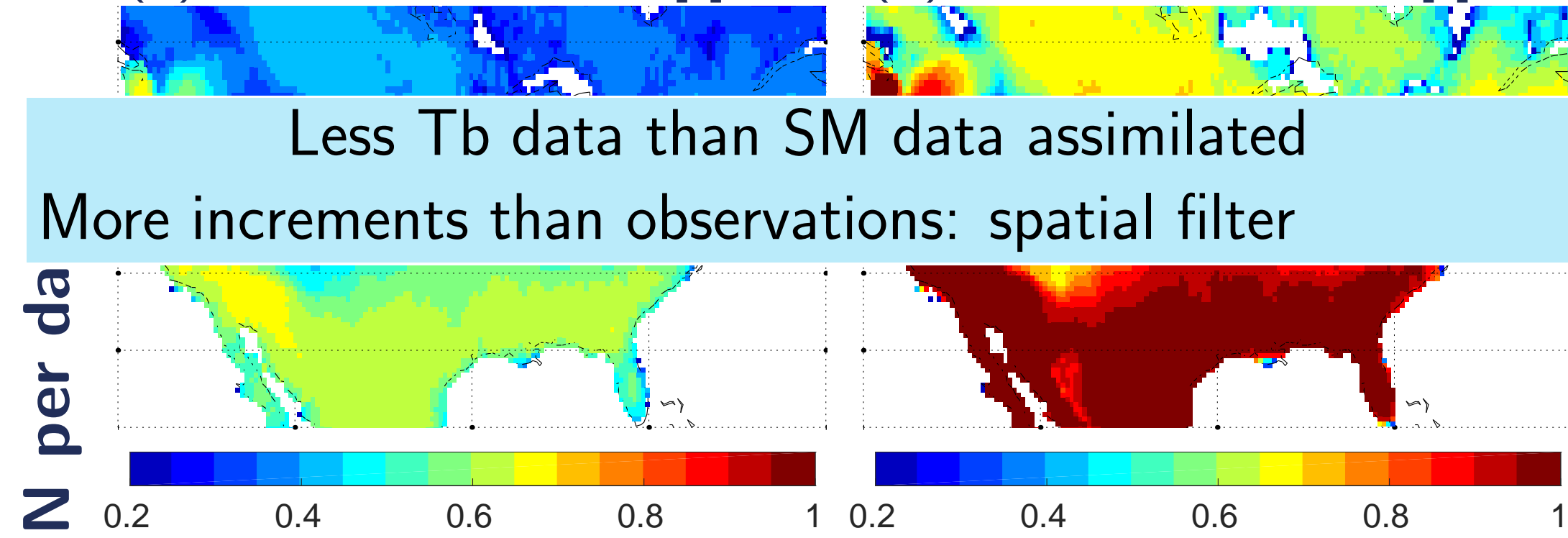
Tb_7ang DA

SM DA

(a) $m=0.46, s=0.11$ [-]

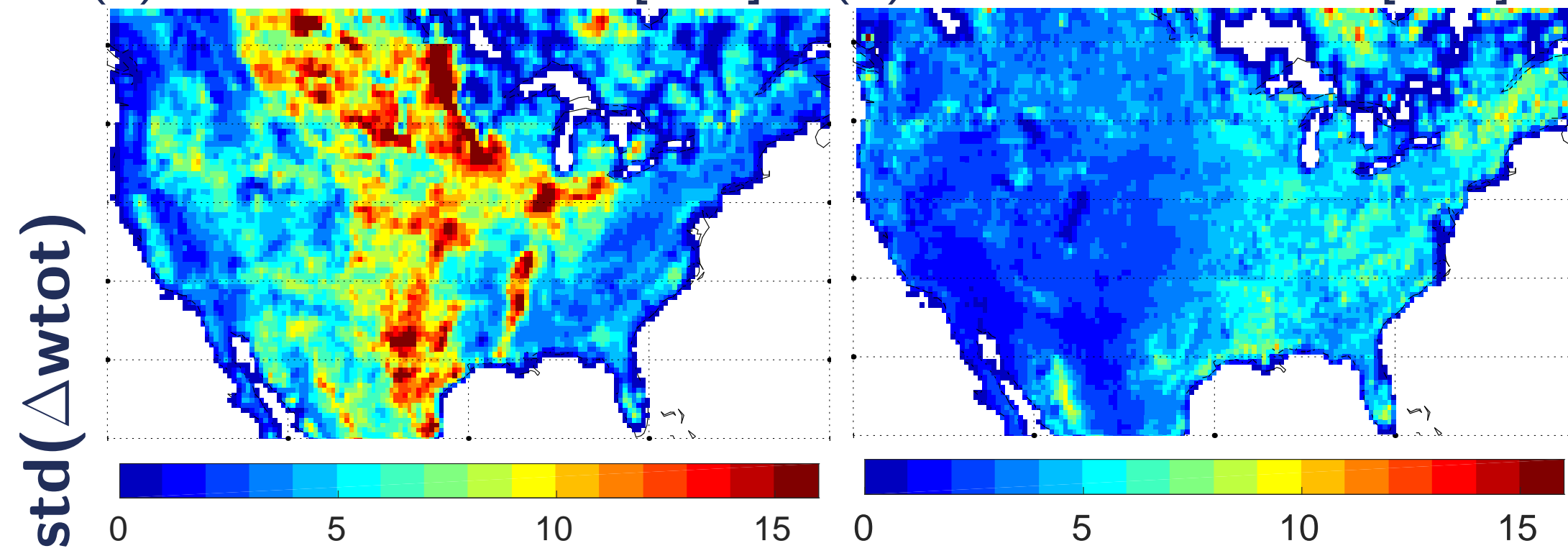
(b) $m=0.76, s=0.19$ [-]

Less Tb data than SM data assimilated
 More increments than observations: spatial filter



(c) $m=6.86, s=3.65$ [mm]

(d) $m=4.17, s=1.93$ [mm]



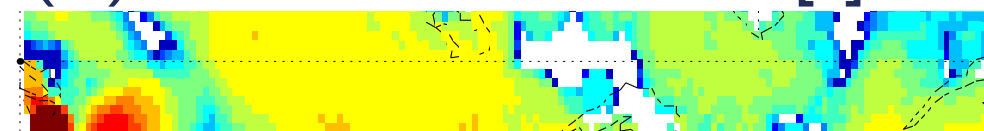
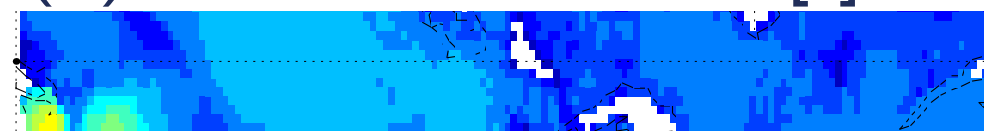
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Tb_7ang DA

SM DA

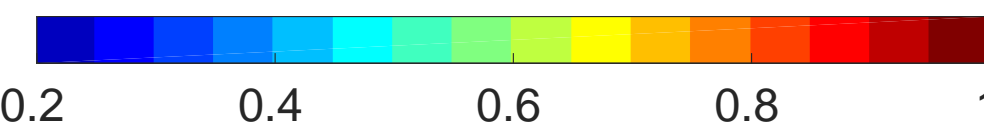
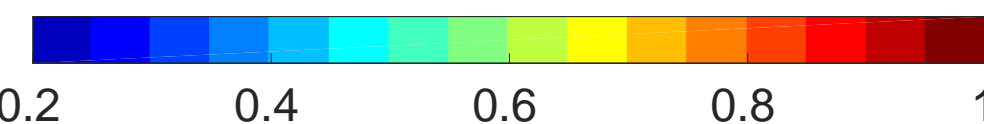
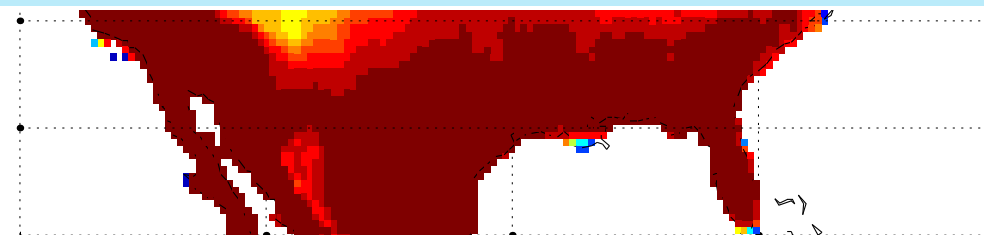
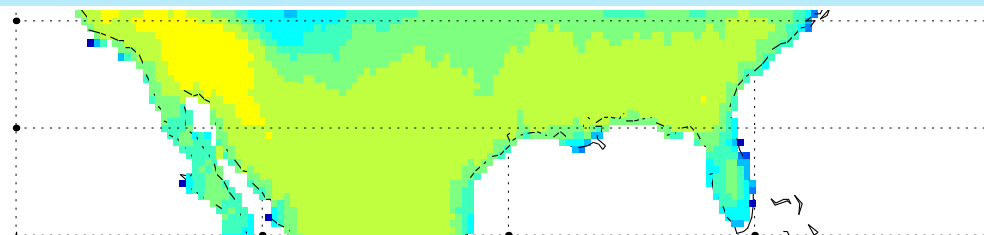
(a) $m=0.46, s=0.11$ [-]

(b) $m=0.76, s=0.19$ [-]



Less Tb data than SM data assimilated
 More increments than observations: spatial filter

N per da

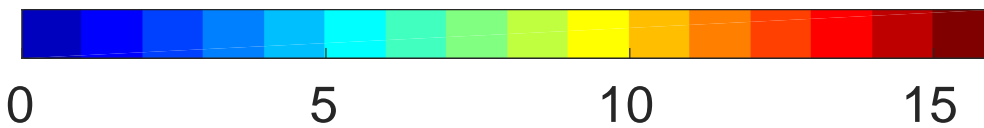
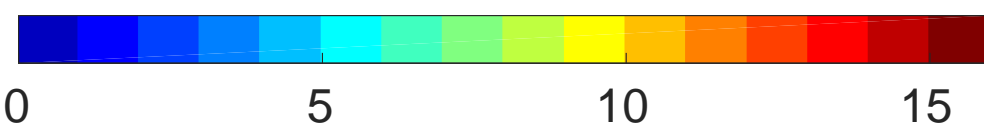
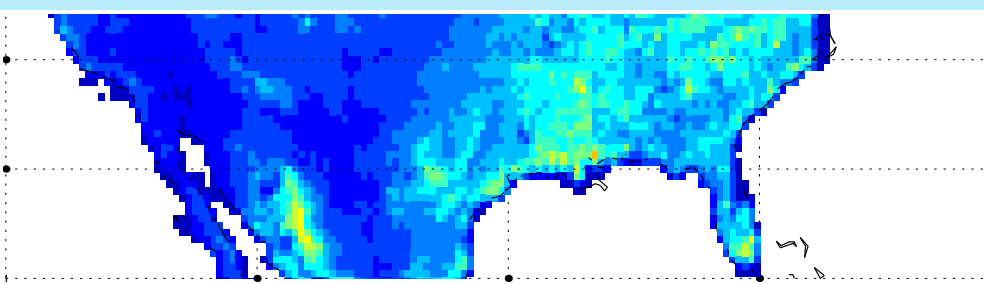
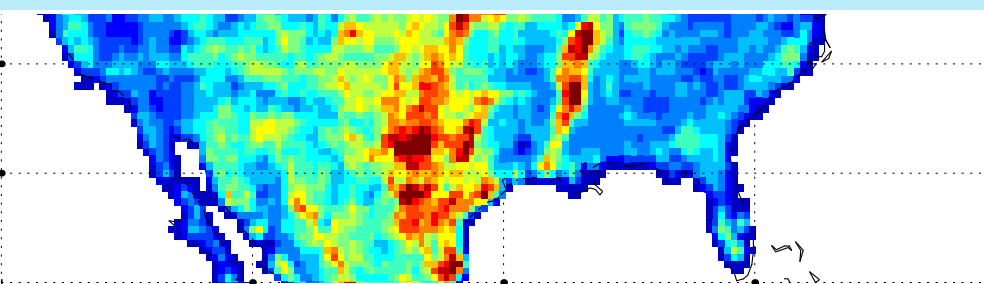


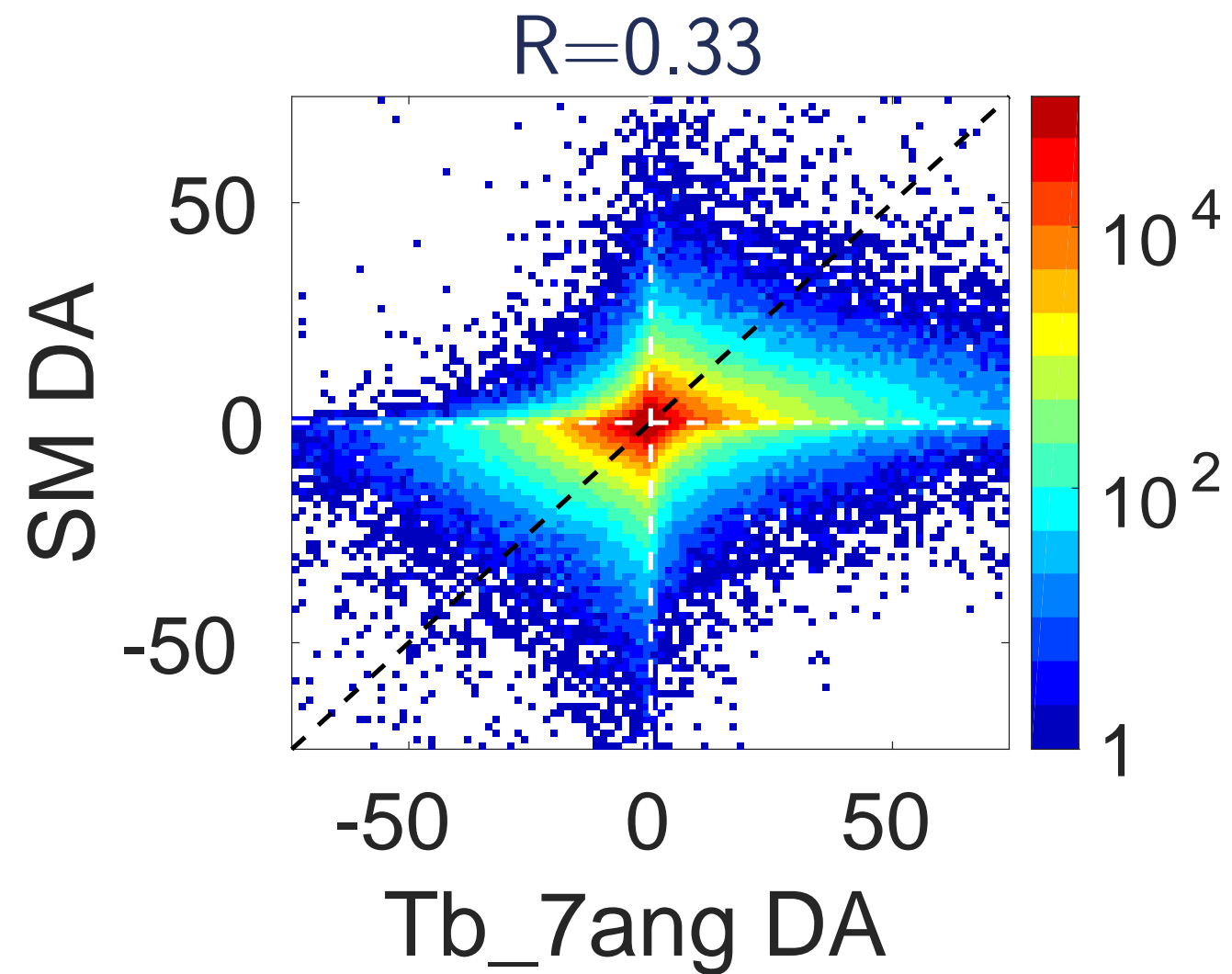
(c) $m=6.86, s=3.65$ [mm]

(d) $m=4.17, s=1.93$ [mm]

$stdv(\Delta w_{tot})$ for Tb DA larger than SM DA
 due to relatively higher Tb O-F, more info in Tb O-F

$std(\Delta w_{tot})$





- unbiased system
- Tb DA introduces more large increments than SM DA
 ~ Tb DA has larger innovations than SM DA
- different information extracted during Tb DA and SM retrieval process?

(De Lannoy and Reichle, 2016, HESS)

System

L-band

SMOS Retrieval

SMOS Assimilation

Data assimilation

SM DA

Tb DA

RTM impact

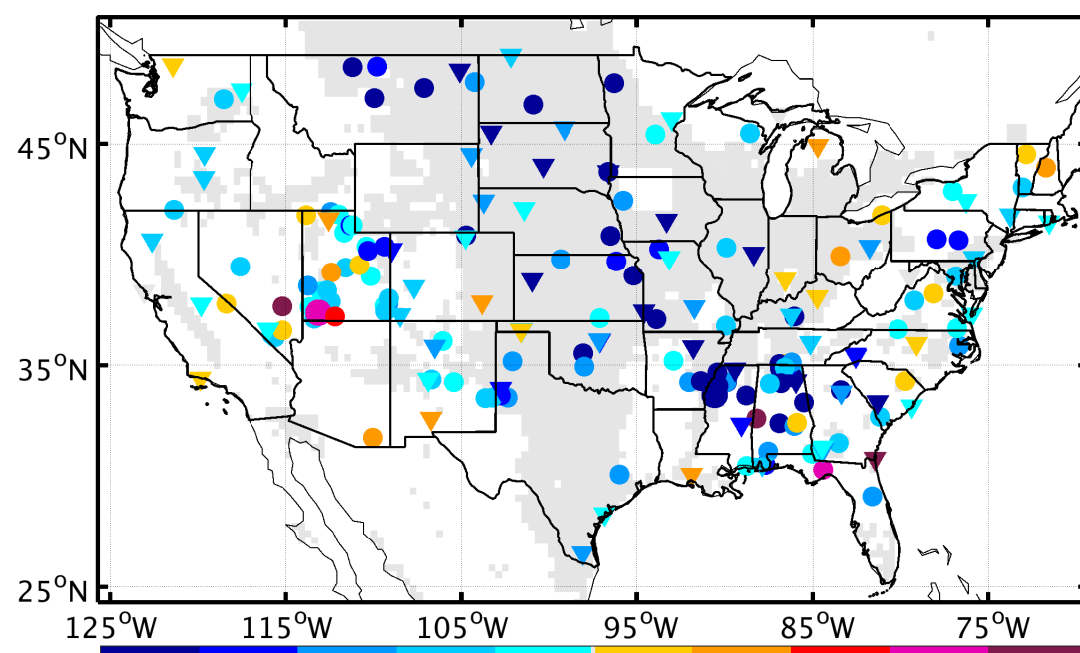
Conclusions

Surface s.m.

Root-zone s.m.

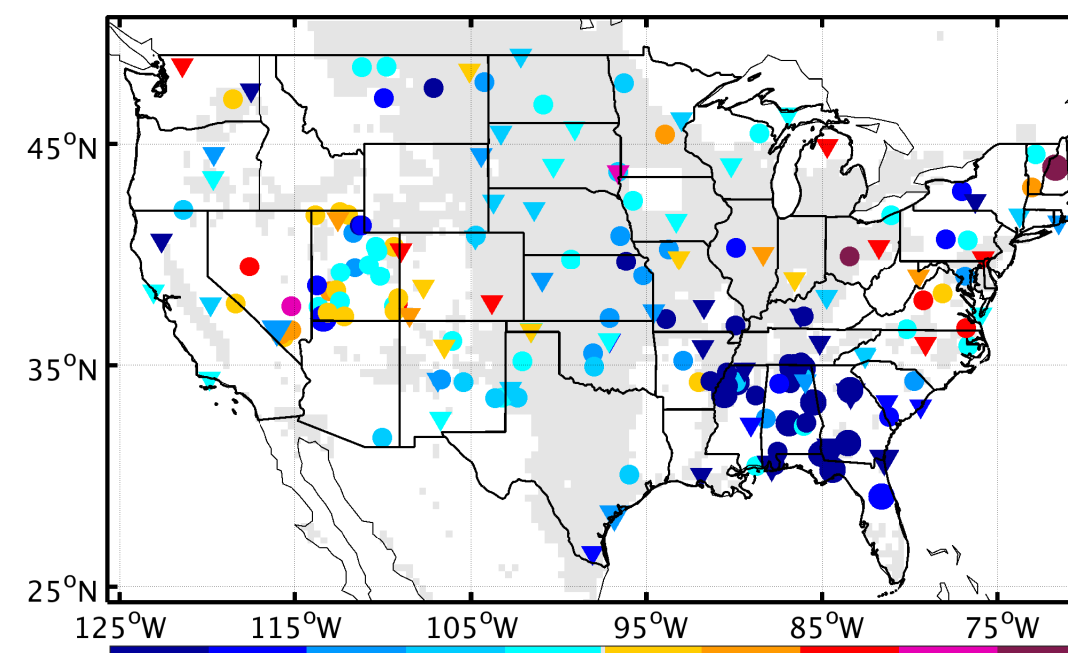
Tb_7ang DA

(a) $\Delta\text{RMSD}_{ub} = -0.004 \text{ [m}^3/\text{m}^3\text{]}$
(153/187 improved)



SM retrieval DA

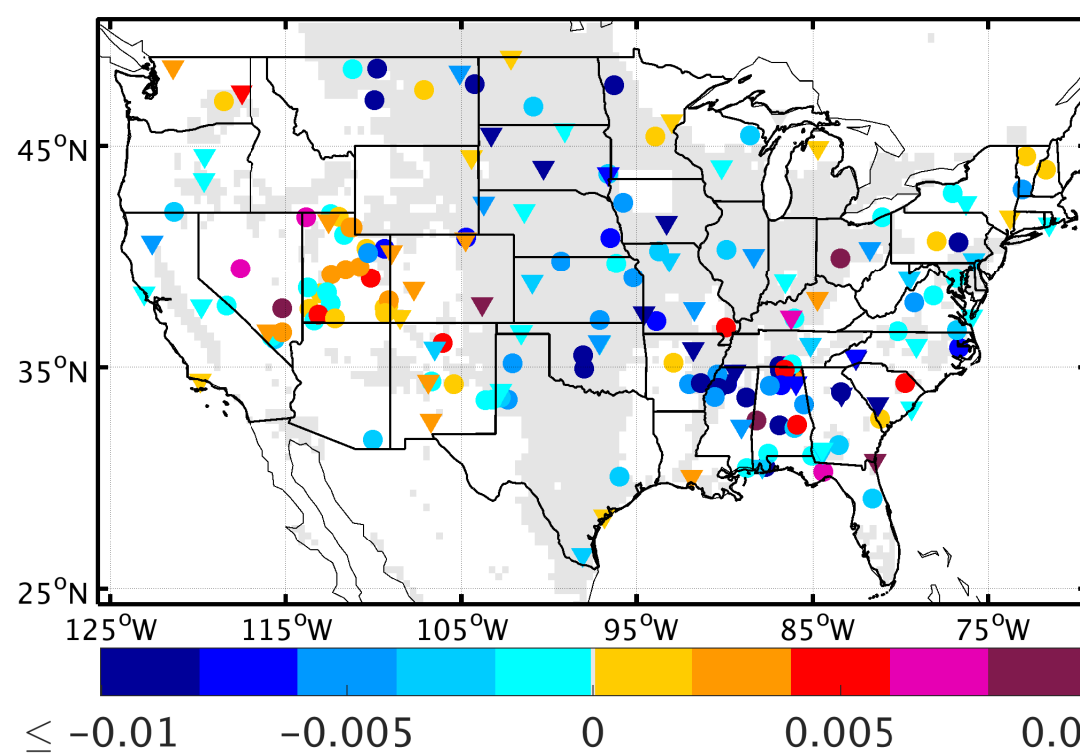
(b) $\Delta\text{RMSD}_{ub} = -0.003 \text{ [m}^3/\text{m}^3\text{]}$
(143/187 improved)



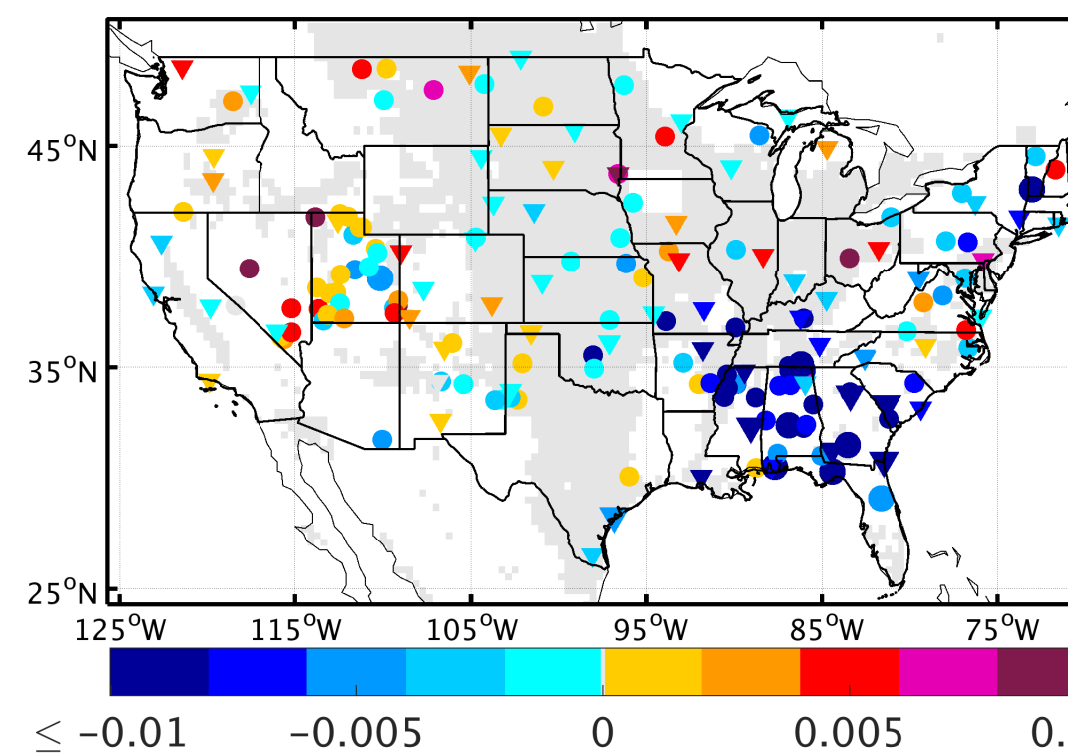
Blue=better

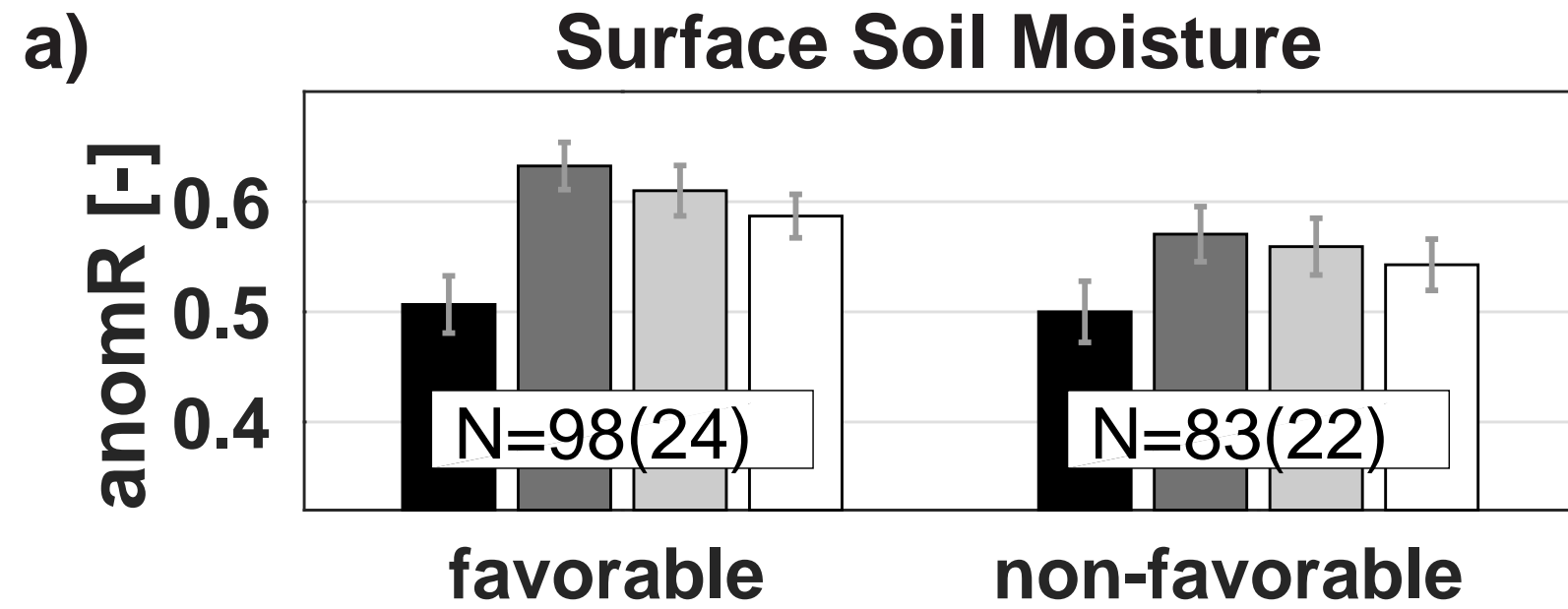
Red=worse

(c) $\Delta\text{RMSD}_{ub} = -0.002 \text{ [m}^3/\text{m}^3\text{]}$
(125/187 improved)

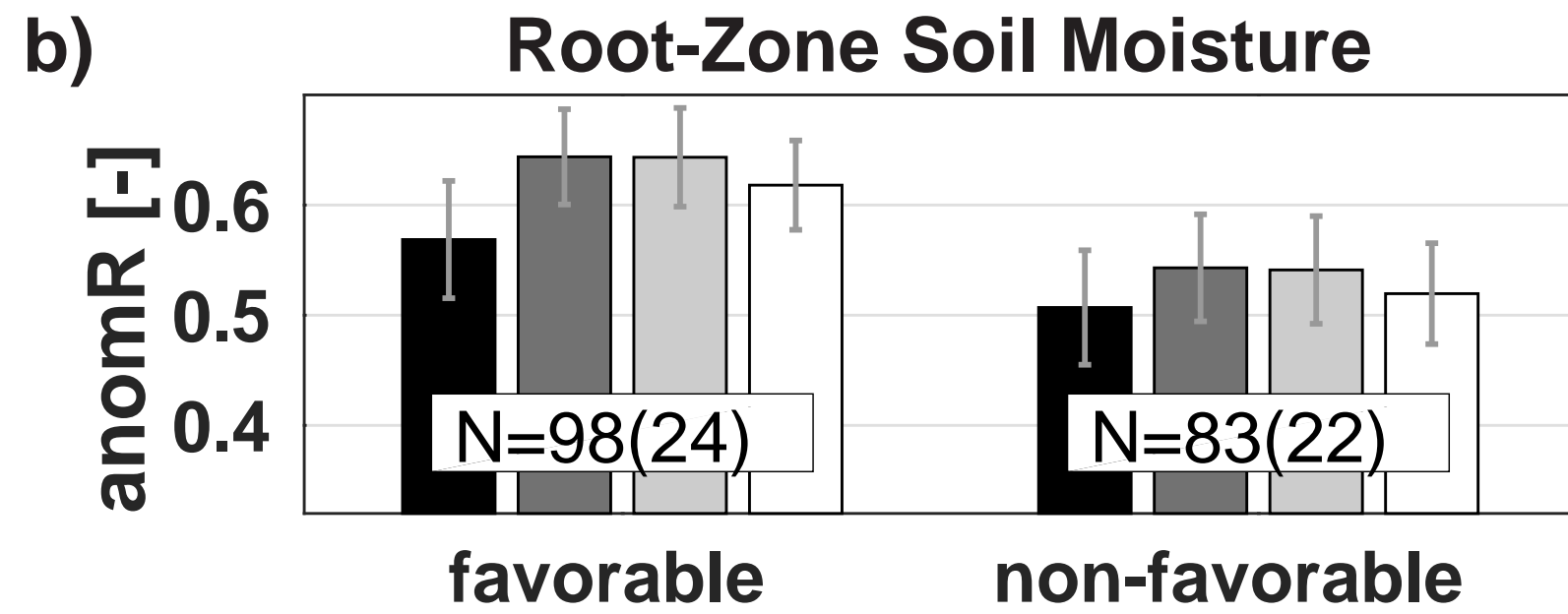


(d) $\Delta\text{RMSD}_{ub} = -0.001 \text{ [m}^3/\text{m}^3\text{]}$
(121/187 improved)

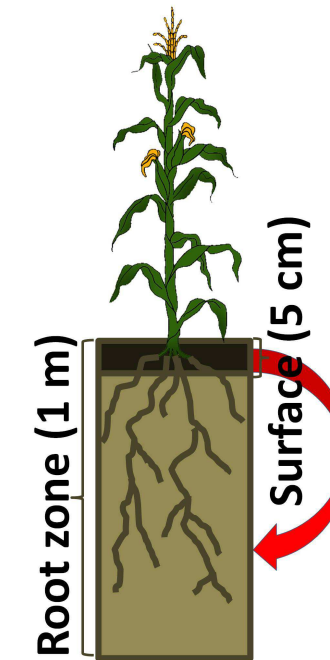




- largest soil moisture improvements in favorable areas
- similar averaged skill statistics for Tb and SM DA



■ open loop, ■ Tb_7ang DA,
 ■ Tb_fit DA, □ SM DA



(De Lannoy and Reichle, 2016)

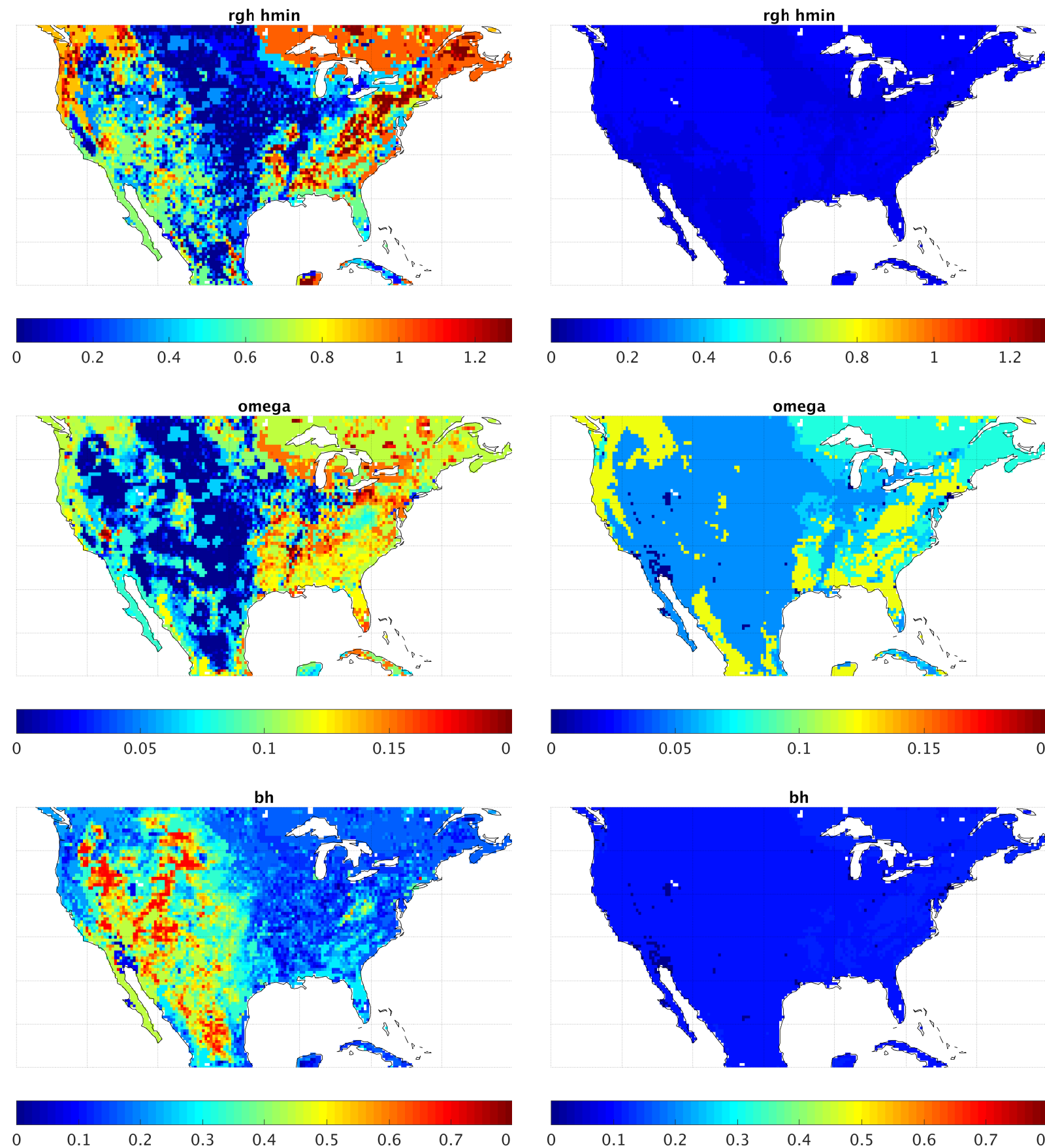
Effect of RTM on Tb DA

Repeat the Tb_7ang DA experiment, but with lookup table RTM parameters:

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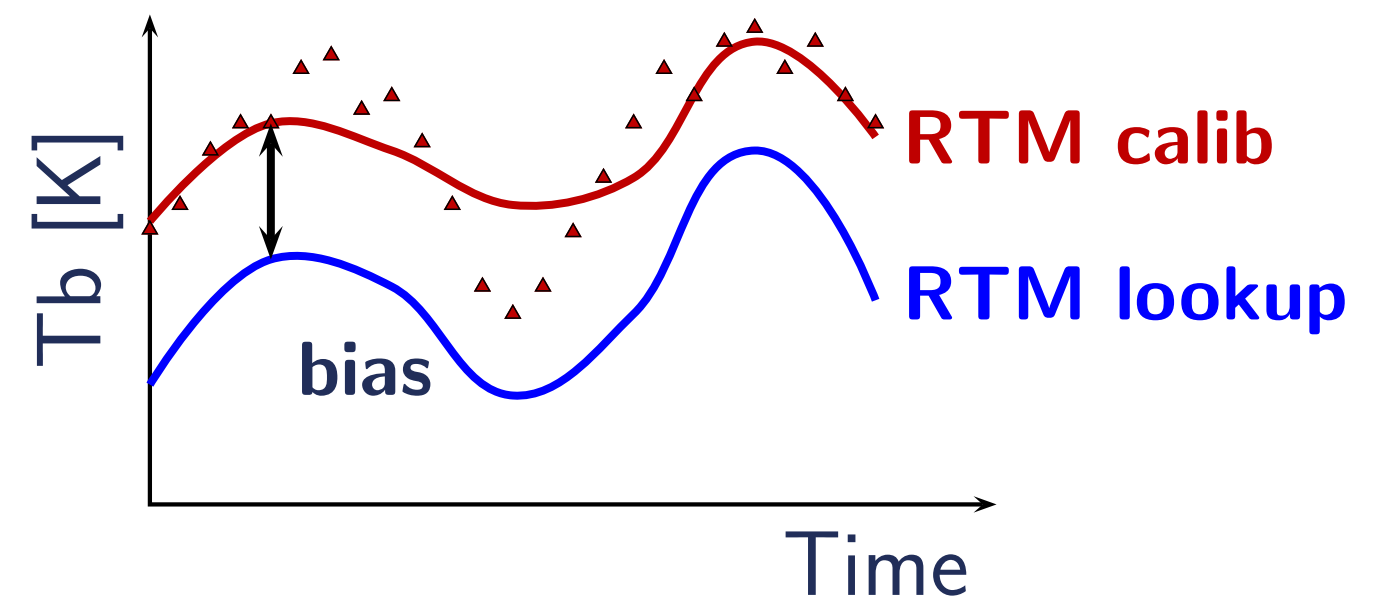
Calibrated

Lookup (SMAP L2)



Effect on Tb obs predictions:

- primary: different seasonal bias
→ Tb rescaling
- secondary: different anomalies?

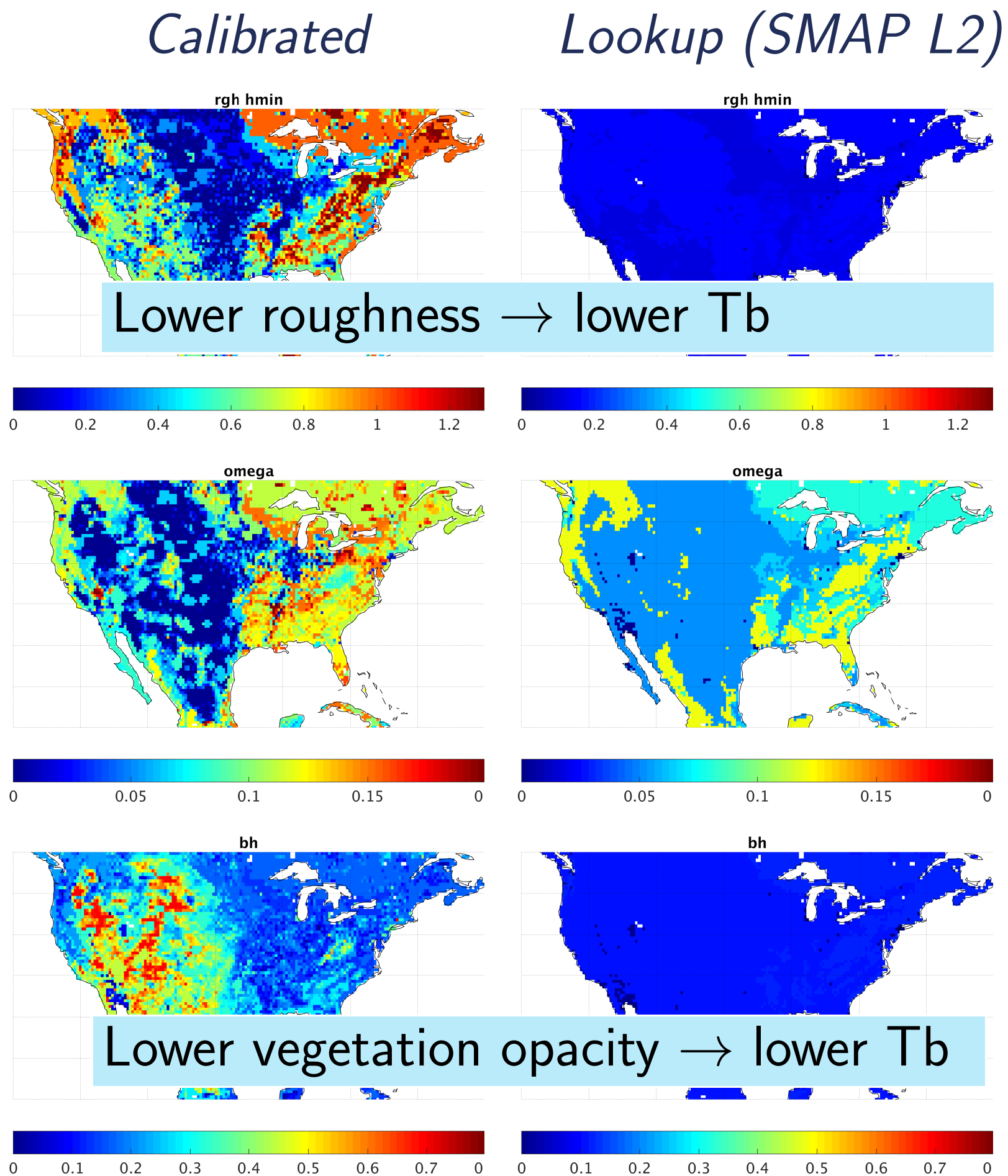


(Alexander Gruber)

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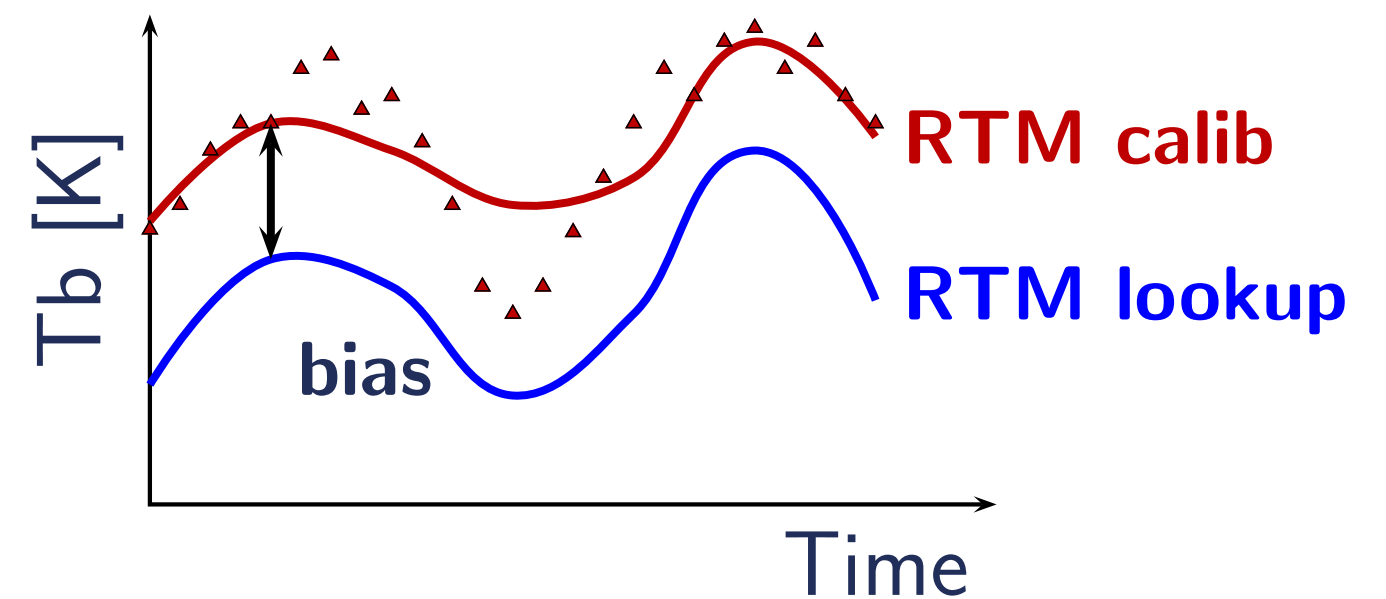
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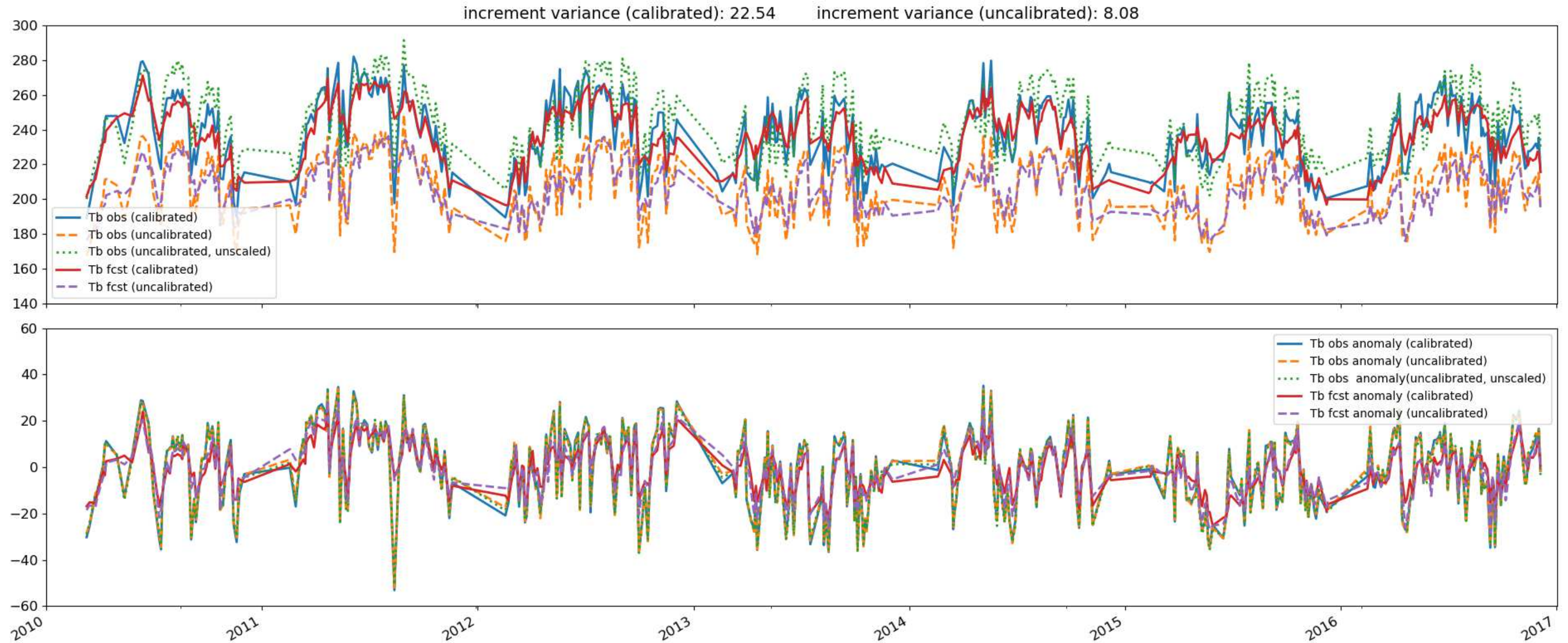


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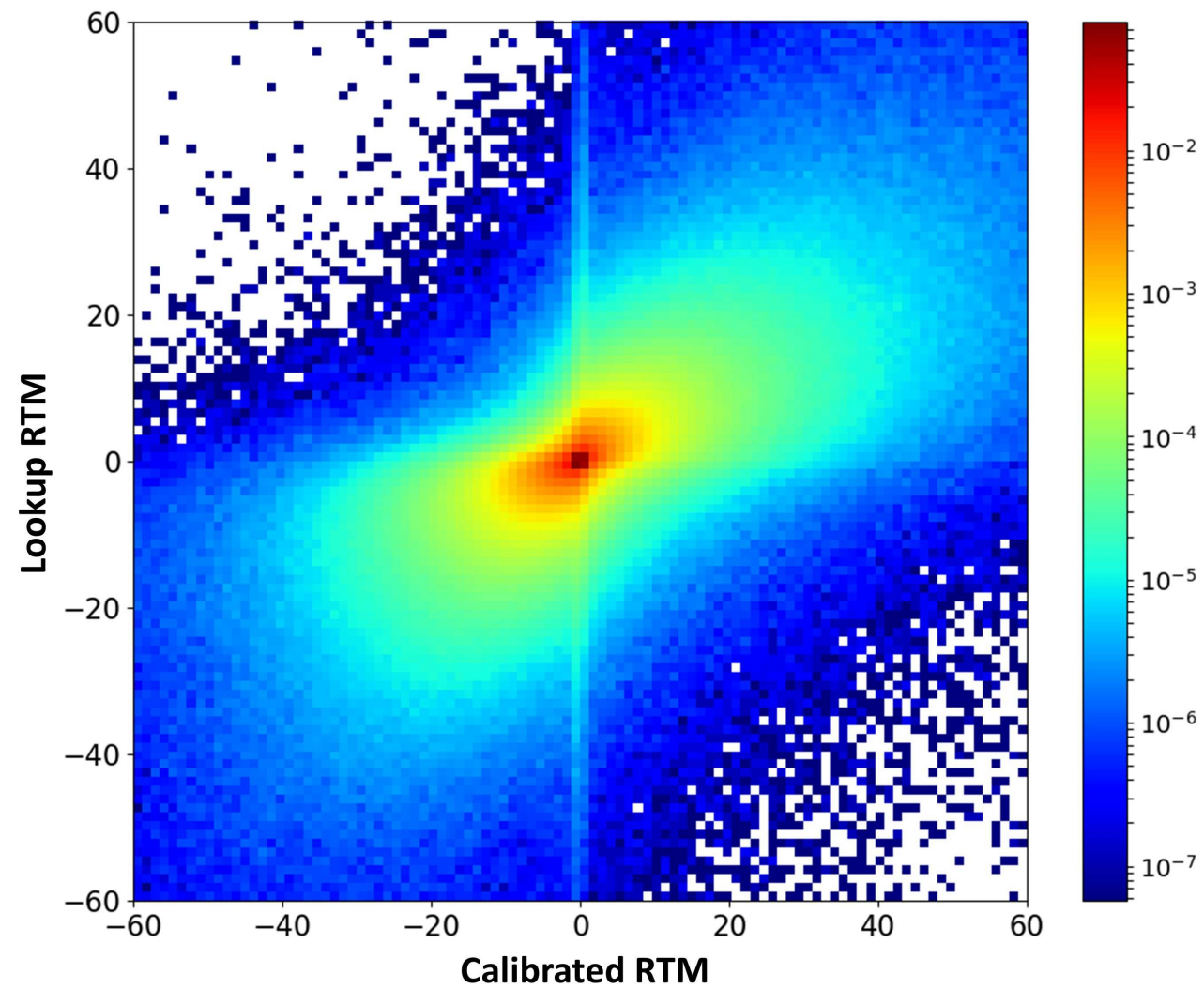
(Alexander Gruber)



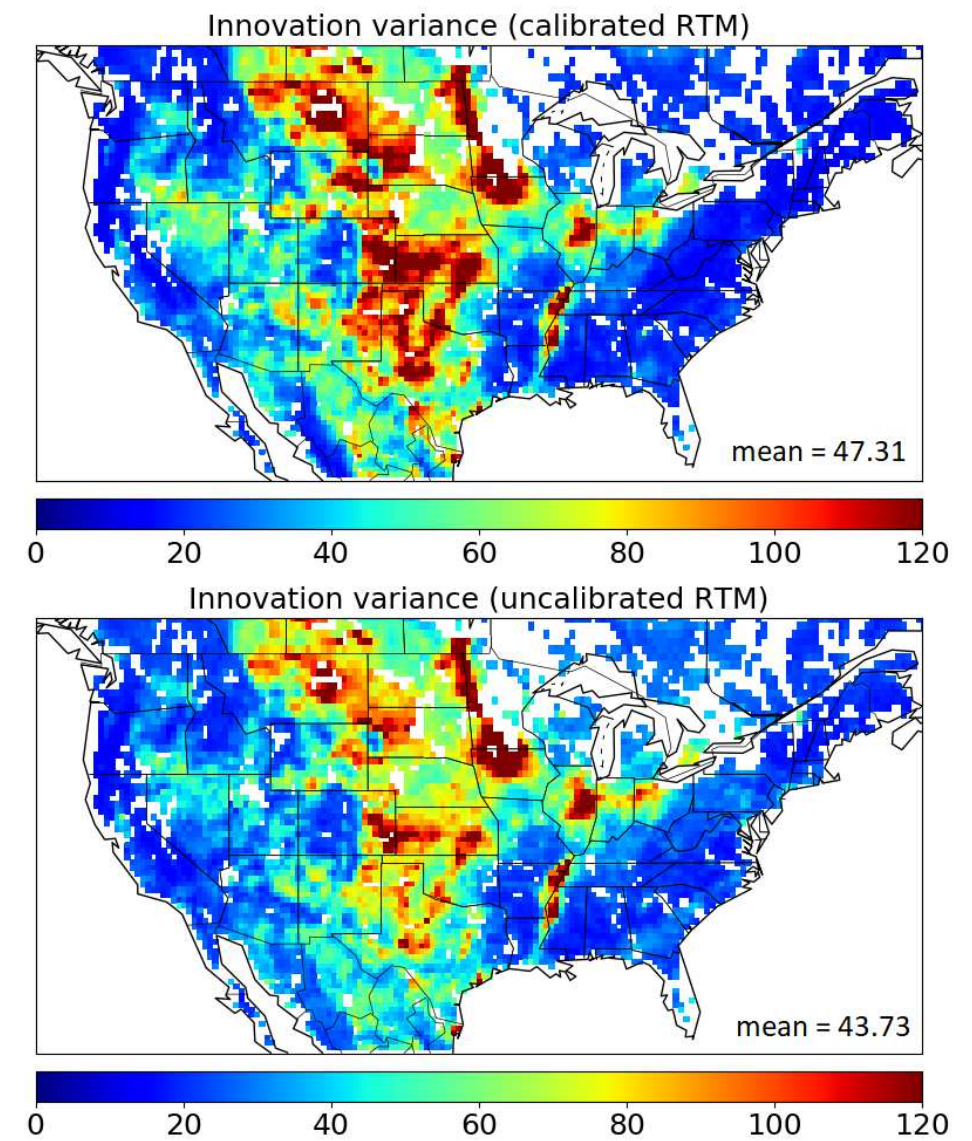
- obvious seasonal bias RTM calib vs lookup
- after rescaling: similar Tb anomalies for RTM calib and lookup
- different variance in Tb obs and Tb fct anomalies (for both RTM calib and lookup)
- Tb anomaly innov variance is slightly larger for RTM calib (not over forests)

- System
- L-band
- SMOS Retrieval
- SMOS Assimilation
- Data assimilation
- SM DA
- Tb DA
- RTM impact
- Conclusions

Increments [mm]

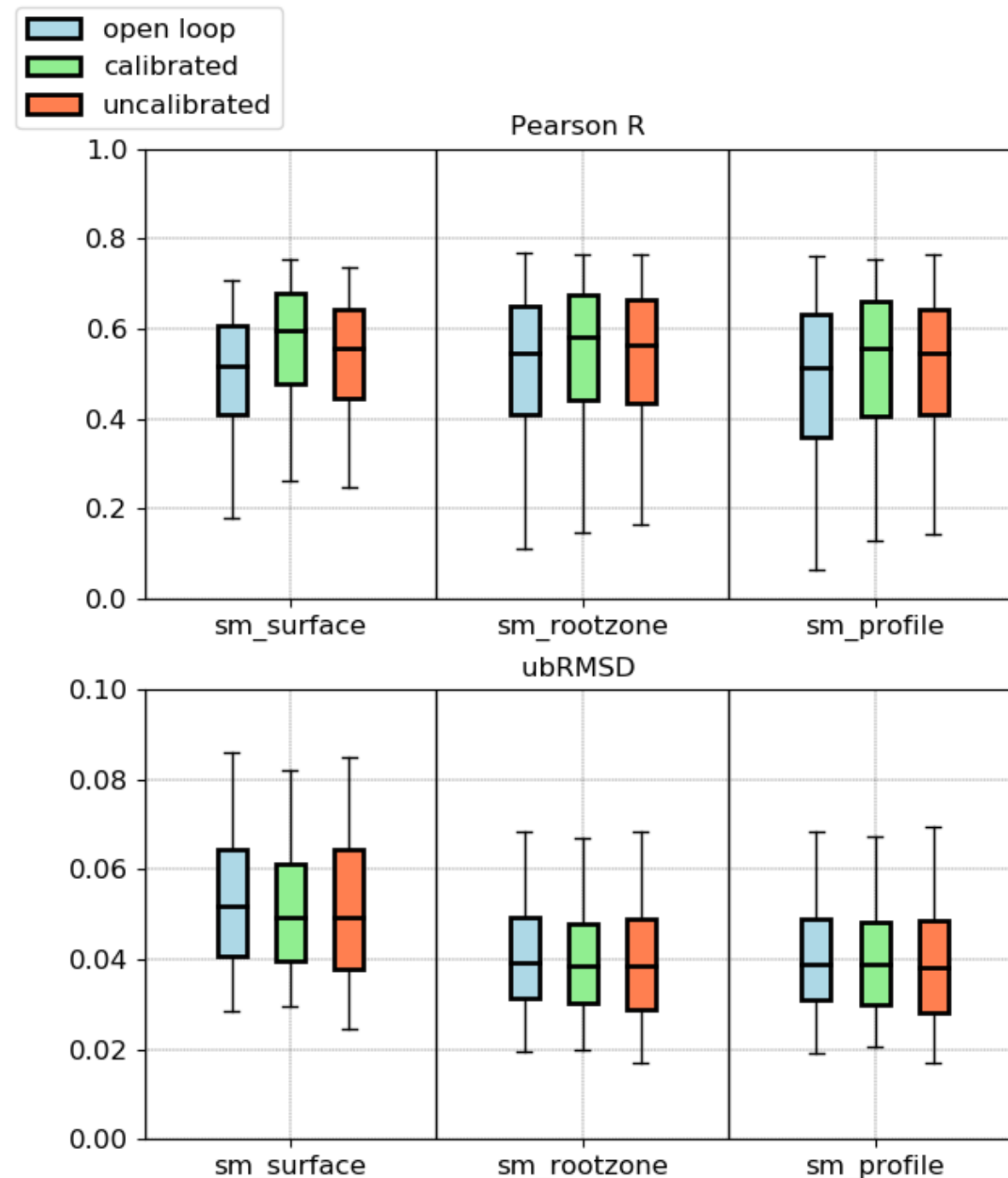
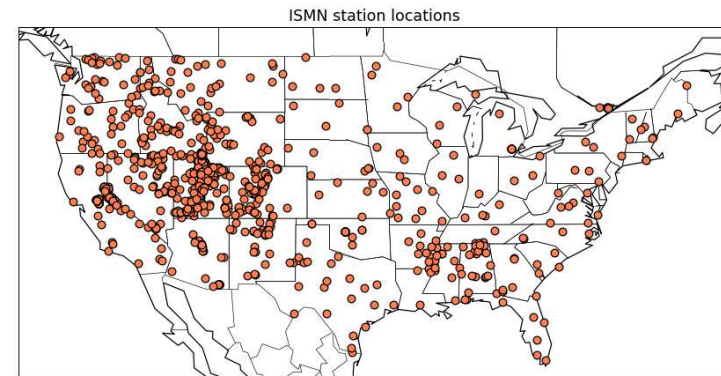


Innovations [K^2]

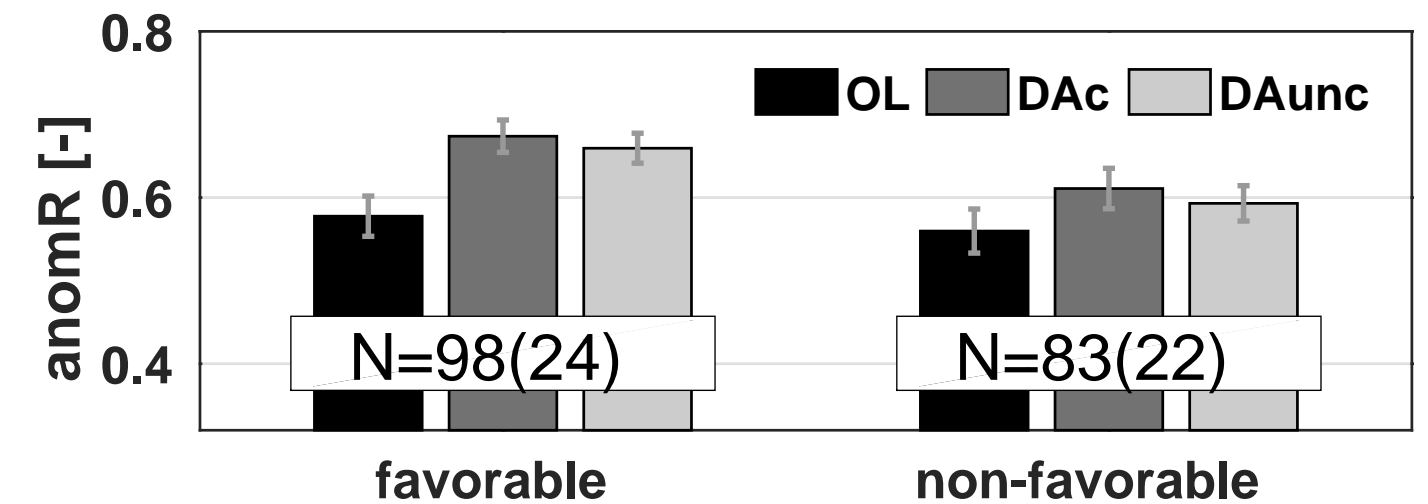


- unbiased system
- both Tb DA schemes correct soil moisture trajectories similarly
- calibrated RTM introduces more large increments than lookup RTM
 \sim Tb (anomaly) innovation variance

In situ surface and root-zone soil moisture (ISMN, not strictly QC-ed)



In situ surface soil moisture (SCAN+USCRN, strictly QC-ed)



- DA always performs better than OL (even when forced with qualitative MERRA2)
- similar averaged skill statistics for Tb DA using RTM calib and lookup

SMOS (or SMAP) Tb to soil moisture via radiative transfer modeling

- very different RTM parameterizations available for forward and inverse modeling
 - ◆ optimized parameters for retrievals work for data assimilation (fwd RTM)
 - ◆ optimized parameters for fwd modeling work for retrievals (inverse RTM)
- Tb estimates much improved when accounting for open water in RTM

Data assimilation:

- SM DA and Tb DA both improve surface and root-zone soil moisture
- SM DA and Tb DA add different increments to products
- seasonal bias mitigation in Tb DA effectively overcomes shortcomings in RTM parameterization (calibrated or not)
- to do: spatio-temporal optimization of Tb (obs and forecast) errors